Topological Hopf algebras, quantum groups and deformation quantization

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Abstract

After a presentation of the context and a brief reminder of deformation quantization, we indicate how the introduction of natural topological vector space topologies on Hopf algebras associated with Poisson Lie groups, Lie bialgebras and their doubles explains their dualities and provides a comprehensive framework. Relations with deformation quantization and applications to the deformation quantization of symmetric spaces are described.

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1 Introduction

1.1 Presentation of the context.

The expression “quantum groups” is a name coined by Drinfeld (see [Dri87]) in the first half of the 80’s which is superb, even if the notion is not necessarily quantum and the objects are not really groups. But they are Hopf algebras and their theory can be viewed as an avatar of deformation quantization [BFFLS] (see [DS02] for a recent review which this presentation complements), applied to the quantization of Poisson-Lie groups.

The philosophy underlying the role of deformations in physics has been consistently put forward by Flato, almost since the definition of the deformation of rings and algebras by Gerstenhaber [Ger64], and was eventually expressed by him in [Fla82]. In short, the passage from one level of physical theory to another, when a new fundamental constant is imposed by experiments, can be understood (and might even have been predicted) using deformation theory. The only question is, in which category do we seek for deformations? Usually physics is rather conservative and if we start e.g. with the category of associative or Lie algebras, we tend to deform in the same category.

But there are important instances of generalizations of this principle. The most elaborate is maybe noncommutative geometry, where the strategy is to formulate the “undeformed” (commutative) geometry in terms of algebraic structures in such a way that it becomes possible to “plug in” the deformation (noncommutativity) in a quite natural, and mathematically rigorous, manner. We shall not elaborate on that aspect here, referring e.g. to [Co00] for a presentation, to [CDV02] for important recent examples of noncommutative manifolds, and to [Co94, CFS92] for the basics and a relation with deformation quantization.

We shall concentrate on another prominent example: quantum groups. Instead of looking at the associative algebra of functions over a Poisson-Lie group or at the enveloping algebra, one makes full use of the Hopf algebra structure in both cases. In general both the product and the coproduct have to be (compatibly) deformed, but cohomological results ([Dri89] and section 3.1) show that, when the Lie group is semi-simple, the deformation is always equivalent to a “preferred” one, that is, a deformation where only the product or the coproduct (resp.) is deformed. The group aspect is a special case of deformation quantization and we shall show that the enveloping algebra aspect can be seen as its dual, in the sense of topological vector spaces duality.

1.2 Deformation theory of algebras.

A concise formulation of a Gerstenhaber deformation of an algebra (associative, Lie, bialgebra, etc.) is [Ger64, BFGP92].
Definition 1 A deformation of an algebra $A$ over a field $\mathbb{K}$ is a $\mathbb{K}[[v]]$-algebra $\tilde{A}$ such that $\tilde{A}/v\tilde{A} \cong A$. Two deformations $\tilde{A}$ and $\tilde{A}'$ are said equivalent if they are isomorphic over $\mathbb{K}[[v]]$ and $\tilde{A}$ is said trivial if it is isomorphic to the original algebra $A$ considered by base field extension as a $\mathbb{K}[[v]]$-algebra.

Whenever we consider a topology on $A$, $\tilde{A}$ is supposed to be topologically free. For associative (resp. Lie) algebras, Definition 1 tells us that there exists a new product $*$ (resp. bracket $[\cdot,\cdot]$) such that the new (deformed) algebra is again associative (resp. Lie). Denoting the original composition laws by ordinary product (resp. bracket), we can show $[BFFLS]$ ($[GS90, Bon92]$) that a deformation of an algebra $A$ with the same unit and counit, but in general not trivial.

Equivalence means that there is an isomorphism $T_v = 1 + \sum_{t=1}^{\infty} v^t T_r$, $T_r \in \mathcal{L}(A,A)$ so that $T_v(u \ast v) = (T_v u \ast T_v v)$ in the associative case, denoting by $\ast$ (resp. $*$) the deformed laws in $\tilde{A}$ (resp. $\tilde{A}'$); and similarly in the Lie, bialgebra and Hopf cases. In particular we see (for $r = 1$) that a deformation is trivial at order 1 if it starts with a 2-cocycle which is a 2-coboundary. More generally, exactly as above, we can show $[BFFLS]$ ($[GS90, Bon92]$) that if two deformations are equivalent up to some order $t$, the condition to extend the equivalence one step further is that a 2-cocycle (defined using the $T_r$) is a 2-coboundary, i.e. $T_r u = \sum_{k \leq t} T_r \partial \theta_k$ and therefore the obstructions to equivalence lie in the 2-cohomology. In particular, if that space is null, all deformations are trivial.

Unit. An important property is that a deformation of an associative algebra with unit (what is called a unital algebra) is again unital, and equivalent to a deformation with the same unit. This follows from a more general result of Gerstenhaber (for deformations leaving unchanged a subalgebra) and a proof can be found in $[GS88]$.

Remark 1 In the case of (topological) bialgebras or Hopf algebras, equivalence of deformations has to be understood as an isomorphism of (topological) $\mathbb{K}[[v]]$-algebras, the isomorphism starting with the identity for the degree 0 in $v$. A deformation is again said trivial if it is equivalent to that obtained by base field extension. For Hopf algebras the deformed algebras may be taken (by equivalence) to have the same unit and counit, but in general not the same antipode.

1.3 Deformation quantization and physics.

Intuitively, classical mechanics is the limit of quantum mechanics when $\hbar = \frac{i}{2\pi}$ goes to zero. But how can this be realized when in classical mechanics the observables are functions over phase space (a Poisson manifold) and not operators? The deformation philosophy promoted by Flato shows the way: one has to look for deformations of algebras of classical observables, functions over Poisson manifolds, and realize there quantum mechanics in an autonomous manner.

What we call “deformation quantization” relates to (and generalizes) what in the conventional (operational) formulation are the Heisenberg picture and Weyl’s quantization procedure. In the latter $[Wey31]$, starting with a classical observable $u(p,q)$, some function on phase space $\mathbb{R}^{2\ell}$ (with $p,q \in \mathbb{R}^\ell$), one associates an operator (the corresponding quantum observable) $\Omega(u)$ in the Hilbert space $L^2(\mathbb{R}^\ell)$ by the following general recipe:

$$ u \mapsto \Omega(u) = \int_{\mathbb{R}^{2\ell}} \tilde{u}(\xi,\eta) \exp(i(P,\xi + Q,\eta)/\hbar) w(\xi,\eta) d\xi d\eta $$

where $\tilde{u}$ is the inverse Fourier transform of $u$, $P_\alpha$ and $Q_\alpha$ are operators satisfying the canonical commutation relations $[P_\alpha, Q_\beta] = i\hbar \delta_{\alpha\beta}$ ($\alpha, \beta = 1, \ldots, \ell$), $w$ is a weight function and the integral is taken in the weak operator topology. What is called in physics normal (or antinormal) ordering corresponds to choosing for weight
Fourier-Stieltjes transform (in quantizing a mechanical system \([DN01]\), e.g. in the framework of Weyl quantization: representations. of the Hopf algebra structures and of the "duality" between the group structure and the set of its irreducible for "manifolds with singularities" and for algebraic varieties, and has many far reaching ramifications in both symplectic and Poisson (finite dimensional) manifolds, with further results for infinite dimensional manifolds.

The formal series may be deduced (see e.g. \([Bie00]\)) from an integral formula of the type:

\[ M(u_1, u_2) = v^{-1} \sinh(vP)(u_1, u_2) = P(u_1, u_2) + \sum_{r=1}^{\infty} \frac{v^{2r}}{(2r+1)!} P^{2r+1}(u_1, u_2) \]

where \(2v = i\hbar\), \(P^r(u_1, u_2) = N^{i_1 j_1} \cdots N^{i_r j_r}(\partial_{q_1} \cdots \partial_{q_r} u_1)(\partial_{p_1} \cdots \partial_{p_r} u_2)\) is the \(r^{th}\) power \((r \geq 1)\) of the Poisson bracket bidifferential operator \(P\), \(i_k, j_k = 1, \ldots, 2\ell, k = 1, \ldots, r\) and \((N^{i j}) = (0)^{-(i-j)}\). To fix ideas we may assume here \(u_1, u_2 \in \mathcal{C}^\infty(\mathbb{R}^{2\ell})\) and the sum is taken as a formal series. A corresponding formula for the symbol of a product \(\Omega_1(u)\Omega_1(v)\) can be found in \([Gre46]\), and may now be written more clearly as a (Moyal) star product:

\[ u_1 \ast_M u_2 = \exp(vP)(u_1, u_2) = u_1 u_2 + \sum_{r=1}^{\infty} \frac{v^r}{r!} P^r(u_1, u_2). \]

The formal series may be deduced (see e.g. \([Bie00]\)) from an integral formula of the type:

\[ (u_1 \ast_M u_2)(x) = c_{\hbar} \int_{\mathbb{R}^{2\ell} \times \mathbb{R}^{2\ell}} u_1(x + y)u_2(x + z) e^{-\frac{i}{\hbar}(\Lambda^{-1}(y,z))} dydz. \]

It was noticed, however after deformation quantization was introduced, that the composition of symbols of pseudodifferential operators (ordered, like differential operators, "first \(q\), then \(p\)") is a star product.

But the deformation philosophy tells us more. Deformation quantization is not merely "a reformulation of quantizing a mechanical system" \([DN01]\), e.g. in the framework of Weyl quantization: The process of quantization itself is a deformation. In order to show that explicitly it was necessary to treat in an autonomous manner significant physical examples, without recourse to the traditional operatorial formulation of quantum mechanics. That was achieved in \([BFFLS]\) with the paradigm of the harmonic oscillator and more, including the angular momentum and the hydrogen atom. In particular what plays here the role of the unitary time evolution operator of a quantized system is the "star exponential" of its classical Hamiltonian \(H\) (expressed as a usual exponential series but with "star powers" of \(iH/\hbar\), \(t\) being the time, and computed as a distribution both in phase space variables and in time); in a very natural manner, the spectrum of the quantum operator corresponding to \(H\) is the support of the Fourier-Stieljes transform (in \(t\)) of the star exponential (what Laurent Schwartz had called the spectrum of that distribution). Further examples were (and are still being) developed, in particular in the direction of field theory.

That aspect of deformation theory has since 25 years or so been extended considerably. It now includes general symplectic and Poisson (finite dimensional) manifolds, with further results for infinite dimensional manifolds, for "manifolds with singularities" and for algebraic varieties, and has many far reaching ramifications in both mathematics and physics (see e.g. a brief overview in \([DS02]\)). As in quantization itself \([Wey31]\), symmetries (group theory) play a special role and an autonomous theory of star representations of Lie groups was developed, in the nilpotent and solvable cases of course (due to the importance of the orbit method there), but also in significant other examples. The presentation that follows can be seen as an extension of the latter, when one makes full use of the Hopf algebra structures and of the "duality" between the group structure and the set of its irreducible representations.

Finally one should mention that deformation theory and Hopf algebras are seminal in a variety of problems ranging from theoretical physics (see e.g. \([CK99, DS02]\), including renormalization and Feynman integrals and diagrams, to algebraic geometry and number theory (see e.g. \([Ko01, KZ01]\)), including algebraic curves à la Zagier (cf. \([CM03]\) and Connes’ lectures at Collège de France, January to March 2003).
2 Some topological Hopf algebras

We shall now briefly review applications of the deformation theory of algebras in the context of Hopf algebras endowed with appropriate topologies and in the spirit of deformation quantization. That is, we shall consider Hopf algebras of functions on Poisson-Lie groups (or their topological duals) and their deformations, and show how this framework is a powerful tool to understand the standard examples of quantum groups, and more. In order to do so we first recall some notions on topological vector spaces and apply them to our context.

2.1 Well-behaved Hopf algebras

**Definition 2** A topological vector space (tvs) V is said well-behaved if V is either nuclear and Fréchet, or nuclear and dual of Fréchet [Grt55, Tre67].

**Proposition 1** If V is a well-behaved tvs and W a tvs, then

- (i) $V^{**} \simeq V$
- (ii) $(V \hat{\otimes} V)^* \simeq V^* \hat{\otimes} V^*$
- (iii) $\text{Hom}_K(V, W) \simeq V^* \hat{\otimes} W$

where $V^*$ denotes the strong topological dual of V, $\hat{\otimes}$ the projective topological tensor product and the base field $K$ is $\mathbb{R}$ or $\mathbb{C}$.

**Definition 3** $(A, \mu, \eta, \Delta, \varepsilon, S)$ is a WB (well-behaved) Hopf algebra [BFGP94] if

- $A$ is a well-behaved topological vector space.
- The multiplication $\mu : A \hat{\otimes} A \to A$, the coproduct $\Delta : A \to A \hat{\otimes} A$, the unit $\eta$, the counit $\varepsilon$, and the antipode $S$ are continuous.
- $\mu, \eta, \Delta, \varepsilon$ and $S$ satisfy the usual axioms of a Hopf algebra.

**Corollary 1** If $(A, \mu, \eta, \Delta, \varepsilon, S)$ is a WB Hopf algebra, then $(A^*, \varepsilon^*, \Delta^*, \varepsilon, \mu, \eta, S)$ is also a WB Hopf algebra.

2.2 Examples of well-behaved Hopf algebras [BFGP94]

Let $G$ be a semi-simple Lie group and $\mathfrak{g}$ its complexified Lie algebra. For simplicity we shall assume here $G$ linear (i.e. with a faithful finite dimensional representation) but the same results hold, with some modification in the proofs, for any semi-simple Lie group.

2.2.1 Example 1

$C^\infty(G)$, the algebra of the smooth functions on $G$, is a WB Hopf algebra (Fréchet and nuclear).

2.2.2 Example 2

$\mathcal{D}(G) = C^\infty(G)^*$, the algebra of the compactly supported distributions on $G$, is a WB Hopf algebra (dual of Fréchet and nuclear). The product is the transposed map of the coproduct of $C^\infty(G)$ that is, the convolution of distributions.

2.2.3 Example 3

$\mathcal{H}(G)$, the algebra of coefficient functions of finite dimensional representations of $G$ (or polynomial functions on $G$) is a WB Hopf algebra, the Hopf structure being that induced from $C^\infty(G)$.

A short description of that algebra is as follows: We take a set $\hat{G}$ of irreducible finite dimensional representations of $G$ such that there is one and only one element for each equivalence class, and, if $\pi \in \hat{G}$, its contragredient $\check{\pi}$ is also in $\hat{G}$. We define $C_\pi = \text{vect}\{\text{coefficient functions of } \pi\}$ Burnside $\simeq \text{End}(V_\pi)$ for $\pi \in \hat{G}$. Then $\mathcal{H}(G) \overset{\text{alg}}{\simeq} \bigoplus_{\pi \in \hat{G}} C_\pi \overset{\text{top}}{\simeq} \bigoplus_{\pi \in \hat{G}} \text{End}(V_\pi)$. So we take on $\mathcal{H}(G)$ the “direct sum” topology of $\bigoplus_{\pi \in \hat{G}} \text{End}(V_\pi)$. Then $\mathcal{H}(G)$ is dual of Fréchet and nuclear, that is, WB.
2.4 Example 4

Let \( \mathcal{A}(G) \), the algebra of “generalized distributions”, be defined by
\[
\mathcal{A}(G) = \mathcal{H}(G)^* \cong \prod_{\pi \in \mathcal{G}} \text{End}(V_\pi).
\]
The (product) topology is Fréchet and nuclear, and therefore \( \mathcal{A}(G) \) is WB.

2.3 Inclusions [BP96, BFGP94]

We denote by \( U_g \) the universal enveloping algebra of \( g \) and by \( C G \) the group algebra of \( G \). All the following inclusions are inclusions of Hopf algebras. \( \in, \exists, \cup, \cap \) mean a dense inclusion.

\[
\begin{align*}
U_g & \in \mathcal{A}(G) \exists C G \quad \mathcal{H}(G) \cap C^\ast(G) \\
U_g & \subset \mathcal{D}(G) \exists C G \quad C^\ast(G)
\end{align*}
\]

(*) is true if and only if \( G \) is linear, but comparable results can be obtained for \( G \) non linear.

3 Topological quantum groups

We shall now deform the preceding topological Hopf algebras and indicate how this explains various models of quantum groups. For clarity of the exposition, throughout this Section and the remainder of the paper, we shall limit to a minimum the details concerning the Hopf algebra structures other than product and coproduct. But whenever we write Hopf algebras and not only bialgebras, the relevant structures are included in the discussion and dealing with them is quite straightforward.

3.1 Quantization

Theorem 1 ([Dri89]) Let \( g \) be a semi-simple Lie algebra and \( (U_g, \mu_0, \Delta_0) \) denote the usual Hopf structure on \( U_g \).

1. If \( (U_g, \mu_0) \) is a deformation (as an algebra) of \( (U_g[t], \mu_0) \) then \( U_g \cong U_g[t] \) (i.e. \( U_g \) is rigid).

2. If \( (U_g[t], \mu_0, \Delta_0) \) is a deformation (as a Hopf algebra) of \( (U_g[t], \mu_0, \Delta_0) \) then

\[
\exists P_1 \in (U_g \otimes U_g)[[t]] \text{ such that } P_{t=0} = 1 \text{ and } \Delta(a) = P_t \Delta_0(a) P^{-1}_t, \forall a \in U_g.
\]

An isomorphism \( \phi \) (it is not unique!) appearing in item 1 above is called a Drinfeld isomorphism.

Corollary 2 ([BFGP93]) Let \( G \) be a linear semi-simple Lie group and \( g \) be its complexified Lie algebra.

1. If \( U_g \) is a deformation of \( U_g \) (a “quantum group”) then \( (U_g, \mu_1, \Delta_1) \cong (U_g[t], \mu_0, P_t \Delta_0 P^{-1}_t) \).

2. \( \mathcal{A}(G) := (\mathcal{A}(G)[[t]], \mu_0, P_t \cdot \Delta_0 \cdot P^{-1}_t) \) is a Hopf deformation of \( \mathcal{A}(G) \) and \( U_g \) is\( \mathcal{A}(G) \).

3. \( \mathcal{D}(G) := (\mathcal{D}(G)[[t]], \mu_0, P_t \cdot \Delta_0 \cdot P^{-1}_t) \) is a Hopf deformation of \( \mathcal{D}(G) \) and \( U_g \) is\( \mathcal{D}(G) \).

4. \( C^\ast(G) \) and \( \mathcal{H}(G) := \mathcal{A}(G)^\ast \) are quantized algebras of functions. They are Hopf deformations of \( C^\ast(G) \) and \( \mathcal{H}(G) \).

Similar results hold in the non linear case [BP96] and for other WB Hopf algebras (e.g. constructed with infinite dimensional representations) [BP96].

Proof. (1) Direct consequence of Theorem 1 (2) \( P_1 \in (U_g \otimes U_g)[[t]] \subset (\mathcal{A}(G) \otimes \mathcal{A}(G))[[[t]]]. \) We obtain coassociativity from \( U_g \in \mathcal{A}(G) \). (3) By restriction of (2). (4) By simple dualization from (2) and (3).
group is still there, acting as a kind of “hidden variables” in this quantum group theory, which is exactly what we see in this quantum group theory. This fact was implicit in Drinfeld’s work. The Tannaka-Krein interpretation of the twisting of quasi-Hopf algebras can be found in Majid (see e.g. [Ma92]). It was made explicit, within the framework exposed here, in [BFGP94].

3.2 Unification of models and generalizations

3.2.1 Drinfeld models

We call “Drinfeld model of quantum group” a deformation of $\mathcal{U}_G$ for $\mathfrak{g}$ simple, as given in [Dri87]. We have seen in the preceding section that from any Drinfeld model $\mathcal{U}_G$ of a quantum group (which can be generalized to any deformation of the Hopf algebra $\mathcal{U}_G$), we obtain a deformation of $\mathcal{D}(G)$ and $\mathfrak{A}(G)$ that contains $\mathcal{U}_G$ as a sub-Hopf algebra. So $\mathcal{D}_t(G)$ and $\mathfrak{A}_t(G)$ are quantum group models that describe Drinfeld models. By duality, $\mathcal{C}_t(G)$ and $\mathcal{H}_t(G)$ are “quantum group deformations” of $\mathcal{C}(G)$ and $\mathcal{H}(G)$. The deformed product on $\mathcal{H}(G)$ is the restriction of that on $\mathcal{C}_t(G)$. Furthermore, as we shall see, these deformations coincide with the usual “quantum algebras of functions”. Let us look more in detail at $\mathcal{H}_t(G)$:

3.2.2 Faddeev-Reshetikhin-Takhtajan (FRT) models

In [FRT88] quantized algebras of functions are defined in terms of generators and relations, the key relation being given by the star-triangle (Yang-Baxter) equation, $R(T \otimes \text{Id})(\text{Id} \otimes T)(T \otimes \text{Id})R$, for a given $R$-matrix $R \in \text{End}(V \otimes V)$ and for $T \in \text{End}(V)$, $V$ being a finite dimensional vector space.

As our deformations are given by a twist $P$, it is not surprising, from a structural point of view [Ma92], that, dually, we obtain in each case a Yang-Baxter relation and so a “FRT-type” quantized algebra of functions. Our Fréchet-topological context permits to write precisely such a construction for the infinite-dimensional Hopf algebras involved.

3.2.2.1. Linear case. If $G$ is semi-simple and linear, there exists $\pi$ a finite dimensional representation of $G$ such that $\mathcal{H}(G) \simeq \mathbb{C}[\pi_{ij}; 1 \leq i, j \leq N]$ where the $\pi_{ij}$ are the coefficient functions of $\pi$. Denote by $(\mathcal{H}_t(G), *)$ the deformation of $\mathcal{H}(G)$ obtained in this way and by $T$ the matrix $[\pi_{ij}]$. Define $T_1 := T \otimes \text{Id}$ and $T_2 := \text{Id} \otimes T$. Then we have

**Proposition 2.** ([BFGP94, BP96])

1. $\{\pi_{ij}; 1 \leq i, j \leq N\}$ is a topological generator system of the $\mathbb{C}[[t]]$-algebra $\mathcal{H}(G)$.
2. There exists an invertible $\mathfrak{R} \in \mathcal{L}(V_\pi \otimes V_\pi)[[t]]$ such that $\mathfrak{R} \cdot T_1 \ast T_2 = T_2 \ast T_1 \cdot \mathfrak{R}$ (so $\mathcal{H}_t(G)$ is a “quantum algebra of functions” of type FRT).
3. We recover every quantum group given in [FRT88] by this construction.

**Sketch of proof.**

1. Perform a precise study of the deformed tensor product of representations.
2. Since the deformations $\mathfrak{A}_t(G)$ are given by a twist $P_t$, $\mathfrak{A}_t(G)$ is quasi-cocommutative, i.e. there exists $R \in (\mathfrak{A}(G) \otimes \mathfrak{A}(G))[t]$, such that $\sigma \circ \Delta_a = R\Delta_t(a)R^{-1}$ with $\sigma(a \otimes b) = b \otimes a$. Standard computations give the result.
3. We want to follow the way used in [Dri87] to link Drinfeld to FRT models. But the main point is that our deformations are obtained through a Drinfeld isomorphism. We therefore have to show:
   - There exists a specific Drinfeld isomorphism deforming the standard representation of $\mathfrak{g}$ into the representation of $\mathcal{U}_G$ used in [Dri87].
   - Two Drinfeld isomorphisms give equivalent deformations.

For instance, the FRT quantization of $SL(n)$ can be seen as a Hopf deformation of $\mathcal{H}(\mathfrak{su}(n))$ (with non deformed coproduct). Moreover, this Hopf deformation extends to $\mathcal{C}_t(G)$. 


Remark 3

1. This proposition justifies the terminology “deformation”, often employed but never justified in these cases. See e.g. [GG82] where it is shown that relations of type $A_1 A_2 = A_2 A_1$ need not define a deformation, even if $A$ is Yang-Baxter.

2. Starting from Drinfeld models, our construction produces FRT models also for e.g. $G = Spin(n)$ and for exceptional Lie groups. In addition, at least some multiparameter deformations [Res90] can be easily treated in this way [BF92].

3.2.2. Non-linear case.

Proposition 3 (BP96) If $G$ is semi-simple with finite center, there exists a dense subalgebra of $(\mathscr{C}^\infty(G), *)$ generated by the coefficient functions of a finite number of (possibly infinite dimensional) representations.

3.2.3 Jimbo models

These are models [Jim85] with generators $E_i^\pm, K_i$ and $K_i^{-1}$. For $G = SU(2)$ [BFP92] and $G = SL(2, \mathbb{C})$ [MZ96] we realize $U_q\mathfrak{su}(2)$ and $U_q\mathfrak{sl}(2, \mathbb{C})$ as dense sub-Hopf algebras of $\mathscr{A}(G)$, $\forall \ell \in \mathbb{C} \setminus 2\pi\mathbb{Q}$ (with $q = e^{\ell}$). For $\mathfrak{sl}(2)$ this gives the original model of Jimbo [Jim85]. For the Lorentz algebra $\mathfrak{sl}(2, \mathbb{C})$ this unifies [MZ96] all the models proposed so far in the literature for a quantum Lorentz group. We obtain here convergent deformations (not only formal).

For $\mathfrak{sl}(2, \mathbb{C})$ it was first proposed in [PW90] to consider the quantum double [Dri87] of $U_q\mathfrak{su}(2)$ as $q$-deformed Lorentz group. It was known from [RSts90] that in such cases the double, as an algebra, is the tensor product of two copies of $U_q\mathfrak{su}(2)$. See also [SWZ91] for a dual version and another semi-direct product form.

3.2.4 Deformation quantization

From the main construction, using deformations of $U\mathfrak{g}$, we deduce the following general theorem:

Theorem 2 (BP96) Let $G$ be a semi-simple connected Lie group with a Poisson-Lie structure. There exists a deformation $(\mathscr{C}^\infty(G), *)$ of $\mathscr{C}^\infty(G)$ such that $*$ is a (differential) star product.

Remark 4

- When $\text{Lie}(G)$ is the double of some Lie algebra, the same result holds.

- The fact that $*$ is differential comes from the twist $P_i \Delta_0 P_i^{-1}, P_i \in (U\mathfrak{g} \times U\mathfrak{g})[[\hbar]].$

- Since from any Drinfeld quantum group we obtain a star product, and since any FRT quantum group can be seen as a restriction of such a star product, we have showed that the data of a “semi-simple” quantum group is equivalent to the data of a star product on $\mathscr{C}^\infty(G)$ satisfying $\Delta(f * g) = \Delta(f) * \Delta(g)$. The functorial existence results of Etingof and Kazhdan [EK96] on the quantization of Lie bialgebras (see also [Em02]) show that the latter is true also for “non semi-simple” quantum groups.

- Techniques similar to those indicated here can be applied to other $q$-algebras (more general quantum groups such as those in [Pro97] and more recent examples, Yangians, etc.). In particular those used in the case of the Jimbo models should be applicable to $q$-algebras defined by generators and relations. That direction of research has not yet been developed.

4 Topological quantum double

From now on we use the Sweedler notation for the coproducts [Swe68]: in a coalgebra $(H, \Delta)$, $\Delta(x) = \sum_{(x)} x_{(1)} \otimes x_{(2)}$ and, by coassociativity, $(\text{Id} \otimes \Delta) \Delta(x) = (\Delta \otimes \text{Id}) \Delta(x) = \sum_{(x)} x_{(1)} \otimes x_{(2)} \otimes x_{(3)}$.

In [Dri87] Drinfeld defines the quantum double of $U\mathfrak{g}$ (see also [Sts94]). This can be adapted to the context of topological Hopf algebras [Bon94].
4.1 Definitions

Let $A$ be $\mathcal{A}(G), \mathcal{A}'(G), \mathcal{A}_I(G)$ or $\mathcal{A}'_I(G)$. If $A = (A, \mu, \Delta, S)$ then $A^* = (A^*, \Delta^*, \mu^*, S^*)$. Define $A^0 = A^{\text{co-op}} = (A^*, \Delta^*, \mu^*, S^*)$, where $\mu^*(x \otimes y) := \mu(y \otimes x)$ and $S^*$ is the antipode compatible with $\mu^*$ and $\Delta$.

If we consider the vector space $A^* \otimes A$, Drinfeld [Dri87] defines the quantum double as follows:

i) $D(A) \simeq A^0 \otimes A$ as coalgebras,

ii) $(f \otimes Id_A)(Id_A \otimes b) = f \otimes b$,

iii) $(Id_A \otimes e_j)(e_i \otimes Id_A) = \Delta^{(i \mu)}_{jk} S^{(i \mu)}_{kl} (e^i \otimes Id_A)(Id_A \otimes e_j)$, where $\{e_i\}$ is a basis of $A$ and $\{e^i\}$ the dual basis.

The Drinfeld double was expressed [Ma90] in a Sweedler form for dually paired Hopf algebras as an example of a theory of ’double smash products’. Adapting that formulation to our topological context we can now define the double as:

**Definition 4** The double of $A$, $D(A)$, is the topological Hopf algebra $(A^* \hat{\otimes} A, \mu_D, \Delta D, \mu^*(S^* \otimes S^*))$ with

\[
\mu_D((f \otimes a) \otimes (g \otimes b)) = \sum_{(a)} f < g, S^*(a) > a_{(2)} b
\]

where $< , >$ denotes the pairing $A^*/A$, “$^*$” stands for a variable in $A$ and $\hat{\otimes}$ is the completed inductive tensor product.

As topological vector spaces we have $D(A) = A^* \hat{\otimes} A$. Thus $D(A)^* = A \hat{\otimes} A^*$ and $D(A)^{**} = D(A)$. So $D(A)$ is “almost self dual” (it is self dual up to a completion) and is reflexive.

4.2 Extension theory

- If $A$ is cocommutative then the product $\mu_D$ of $D(A)$ is the smash product $\mu$ on $A^0 \hat{\otimes} A$

\[
\mu ((f \otimes a) \otimes (g \otimes b)) = \sum_{(a)} f(a_1) \rightarrow g \otimes a_{(2)} b
\]

where $\rightarrow$ denotes the coadjoint action of $A$ on $A^0$, $< a \rightarrow f, b > = \sum_{(a)} < f, S(a_1)b_{a(2)} >$. This product is the “zero class” of an extension theory, defined by Sweedler [Swe69], classified by a space of 2-cohomology $H^2_{\text{cov}}(A, A^0)$. The products are of the form, for $\tau$ a 2-cocycle,

\[
\mu_{\tau} ((f \otimes a) \otimes (g \otimes b)) = \sum_{(a\otimes b)} f(a_1) \rightarrow g \otimes (a_{(2)} \otimes b_{(2)})) \otimes a_{(3)} b_{(2)}.
\]

- The coproduct of $D(A)$ is a smash coproduct for the trivial co-action. We can dualize the theory and, putting the two things together, we can extend the theory for bialgebras which is classified by a cohomology space $H^2_{\text{cov}}(A^0, A)$.

**Question** : Are there other possible definitions of the double as an extension of $A^0$ by $A$?

**Answer** : NO, for $A = \mathcal{A}(G)$ [Bon94], because $H^2_{\text{cov}}(\mathcal{A}(G), \mathcal{C}^{\infty}(G)) = \{0\}$.

5 Crossed products and deformation quantization

In this section we shall see that the Hopf algebra techniques presented in the preceding sections can be useful not only to understand quantum groups, but also to develop very nice formulas in deformation quantization itself.

In order to shed light on the general definition which follows, we return to the simplest case of deformation quantization: the Moyal product on $\mathbb{R}^2$. We look at $\mathbb{R}^2$ as $T^* \mathbb{R} \simeq \mathbb{R} \times \mathbb{R}$ and therefore can write $\mathcal{C}^{\infty}(\mathbb{R}^2) \simeq \mathcal{C}^{\infty}(\mathbb{R}) \otimes \mathcal{C}^{\infty}(\mathbb{R})$. We consider first two functions of a special kind in this algebra: $u(x) = u(x_1, x_2) = f(x_1)p(x_2)$ and $v(x) = v(x_1, x_2) = g(x_1)Q(x_2)$ where $f, g \in \mathcal{C}^{\infty}_0(\mathbb{R})$ and $P, Q$ are polynomials in $\text{Pol}(\mathbb{R}) \simeq \mathbb{R}^\times$. We can then write the usual coproduct on the symmetric algebra $\mathbb{S}\mathbb{R}$ as $\Delta(P)(x_1, y_2) = P(x_2 + y_2)$ (notation $\sum_{(P)} P_{(1)}(x_2)P_{(2)}(y_2)$).
We now look at Formula (7) for the Moyal star product on $\mathbb{R}^2$ and perform on it some formal calculations (we do not discuss the convergence of the integrals involved). Up to a constant (depending on $\hbar$) we get:

\[
(u \ast v)(x) = \int_{\mathbb{R}^2 \times \mathbb{R}^2} u(x + y)v(x + z)e^{-\frac{i}{\hbar}A^{-1}(y,z)}dydz
\]

\[
= \int_{\mathbb{R}^2 \times \mathbb{R}^2} f(x_1 + y_1)P(x_2 + y_2)g(x_1 + z_1)Q(x_2 + z_2)e^{-\frac{i}{\hbar}A^{-1}(y_1,z_1)}dy_1dz_1dy_2dz_2
\]

\[
= \int_{\mathbb{R}^2} f(x_1 + y_1)Q(x_2 + z_2)e^{\frac{i}{\hbar}A^{-1}(y_1,z_1)}dy_1dz_1\int_{\mathbb{R}^2} g(x_1 + z_1)P(x_2 + y_2)e^{\frac{i}{\hbar}A^{-1}(y_2,z_1)}dy_2dz_1
\]

\[
= \sum_{(P),(Q)} (\partial_{\bar{Q}(1)}^\hbar f)(x_1)Q_2(x_2). (\partial_{\bar{R}(1)}^\hbar g)(x_1)P_2(x_2) \quad \text{(up to a constant)}
\]

with $\partial_{\bar{Q}(1)}^\hbar f = Q_1(\mp i\hbar \partial x_1)$ (the same for $P$), since $F_{\hbar}^\pm (\alpha F_{\hbar}^\pm (h)(\alpha)) (x) = \mp i\hbar \partial x\ h(x)$ for $h \in \mathcal{C}_c^\infty (\mathbb{R})$ with $F_{\hbar}^\pm (h)(\alpha)$ defined as $\int_{\mathbb{R}} h(x)e^{\pm i\hbar \alpha x}dx$. This suggests the following small generalization of the smash product:

**Definition 5** Let $B$ be a cocommutative bialgebra and $C$ a $B$-bimodule algebra [i.e. $C$ is both a left $B$-module algebra and a right $B$-module algebra such that $(a \mapsto f) \iff b = a \mapsto (f \mapsto b)$.] We define the L-R smash product on $C \otimes B$ by

\[
(f \otimes a) \ast (g \otimes b) = \sum_{(a)} (f \mapsto b_1)(a_1 \mapsto g) \otimes a_2 b_2.
\]

**Proposition 4** The L-R smash product is associative.

### 5.1 Relation with usual deformation quantization

Let $G$ be a Lie group, $T^*G$ its cotangent bundle, $\mathfrak{g} = \text{Lie}(G)$. We have

\[
\mathcal{C}_c^\infty (T^*G) \simeq \mathcal{C}_c^\infty (G \times \mathfrak{g}) \simeq \mathcal{C}_c^\infty (G) \otimes \mathcal{C}_c^\infty (\mathfrak{g}^*) \supset \mathcal{C}_c^\infty (G) \otimes \text{Pol}(\mathfrak{g}^*) \simeq \mathcal{C}_c^\infty (G) \otimes S\mathfrak{g}.
\]

We define a deformation of $\mathcal{C}_c^\infty (G) \otimes S\mathfrak{g}$ by a L-R smash product:

- We deform $S\mathfrak{g}$ by the “parametrized version” of $U\mathfrak{g}$: $U\mathfrak{g}[[\hbar]] = \frac{T\mathfrak{g}}{< xy - yx - t[x,y]>}$. This is a Hopf algebra with $\Delta$, $\varepsilon$ and $S$ as for $U\mathfrak{g}$.

- Let $\{X_i : i = 1, \ldots, n\}$ be a basis of $\mathfrak{g}$ and $\overset{\rightarrow}{X_i}$ (resp. $\overset{\leftarrow}{X_i}$) be the left (resp. right) invariant vector fields on $G$ associated with $X_i$. For $\lambda \in [0, 1]$ we consider the following actions of $B = U\mathfrak{g}[[\hbar]]$ on $C = \mathcal{C}_c^\infty (G)$:

1. $(X_i \mapsto f)(x) = \hbar(\lambda - 1)(\overset{\rightarrow}{X_i} \cdot f)(x)$

2. $(f \mapsto X_i)(x) = \lambda(\overset{\leftarrow}{X_i} \cdot f)(x)$.

**Lemma 1** These actions define on $\mathcal{C}_c^\infty (G)$ a $B$-bimodule algebra structure.

**Definition 6** We denote by $\star_{\lambda}$ the L-R smash product on $\mathcal{C}_c^\infty (G) \otimes \text{Pol}(\mathfrak{g}^*)$ given by this $B$-bimodule algebra structure on $\mathcal{C}_c^\infty (G)$.

**Proposition 5** For $G = \mathbb{R}^n$, $\ast_{1/2}$ is the Moyal (Weyl ordered) star product, $\ast_0$ is the standard ordered star product and in general $\ast_{\lambda}$ is called $\lambda$-ordered star product on $\mathbb{R}^2^n$ [Pfl99].

**Remark 5** For a general Lie group $G$, $\ast_{\lambda}$ gives in the generic case new deformation quantization formulas on $T^*G$. It would be interesting to study the properties of these $\ast_{\lambda}$ for a noncommutative $G$ and their relations with the star products that are known. In particular $\ast_{1/2}$ is formally different from the star product on $\mathcal{C}_c^\infty (T^*G)$ given by S. Gutt in [Gut83] but preliminary calculations seem to indicate that, in a neighborhood of the unit of $G$, they are equivalent by a symplectomorphism.
5.2 Application to the quantization of symmetric spaces

Definition 7 ([Bie00]) A symplectic symmetric space is a triple \((M,\omega,s)\), where \((M,\omega)\) is a smooth connected symplectic manifold and \(s : M \times M \to M\) is a smooth map such that:

(i) for all \(x\) in \(M\), the partial map \(s_x : M \to M : y \mapsto s_x(y) := s(x,y)\) is an involutive symplectic diffeomorphism of \((M,\omega)\) called the symmetry at \(x\).

(ii) For all \(x\) in \(M\), \(x\) is an isolated fixed point of \(s_x\).

(iii) For all \(x\) and \(y\) in \(M\), one has \(s_x s_y s_x = s_{s_x(y)}\).

Two symplectic symmetric spaces \((M,\omega,s)\) and \((M',\omega',s')\) are isomorphic if there exists a symplectic diffeomorphism \(\varphi : (M,\omega) \to (M',\omega')\) such that \(\varphi s_x = s'_{\varphi(x)} \varphi\).

Definition 8 Let \((\mathfrak{g},\sigma)\) be an involutive algebra, that is, \(\mathfrak{g}\) is a finite dimensional real Lie algebra and \(\sigma\) is an involutive automorphism of \(\mathfrak{g}\). Let \(\Omega\) be a skewsymmetric bilinear form on \(\mathfrak{g}\). Then the triple \((\mathfrak{g},\sigma,\Omega)\) is called a symplectic triple if the following properties are satisfied:

1. Let \(\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{p}\) where \(\mathfrak{k}\) (resp. \(\mathfrak{p}\)) is the \(+1\) (resp. \(-1\)) eigenspace of \(\sigma\). Then \([\mathfrak{p},\mathfrak{p}] = \mathfrak{k}\) and the representation of \(\mathfrak{k}\) on \(\mathfrak{p}\), given by the adjoint action, is faithful.

2. \(\Omega\) is a Chevalley 2-cocycle for the trivial representation of \(\mathfrak{g}\) on \(\mathbb{R}\) such that \(\forall \mathfrak{x} \in \mathfrak{k}\), \(\mathfrak{i}(\mathfrak{x})\mathfrak{\Omega} = 0\). Moreover, the restriction of \(\Omega\) to \(\mathfrak{p} \times \mathfrak{p}\) is nondegenerate.

The dimension of \(\mathfrak{p}\) defines the dimension of the triple. Two such triples \((\mathfrak{g}_i,\sigma_i,\Omega_i)\) \((i = 1,2)\) are isomorphic if there exists a Lie algebra isomorphism \(\psi : \mathfrak{g}_1 \to \mathfrak{g}_2\) such that \(\psi \circ \sigma_1 = \sigma_2 \circ \psi\) and \(\psi^* \Omega_2 = \Omega_1\).

Proposition 6 ([Bie95]) There is a bijective correspondence between the isomorphism classes of simply connected symplectic symmetric spaces \((M,\omega,s)\) and the isomorphism classes of symmetric triples \((\mathfrak{g},\sigma,\Omega)\).

Definition 9 A symplectic symmetric space \((M,\omega,s)\) is called an elementary solvable symplectic symmetric space if its associated triple \((\mathfrak{g},\sigma,\Omega)\) is of the following type:

1. The Lie algebra \(\mathfrak{g}\) is a split extension of Abelian Lie algebras \(a\) and \(b\):

   \[
   \begin{array}{c}
   b \\ \downarrow \\ \mathfrak{g} \\ \downarrow \\ a
   \end{array}
   \]

2. The automorphism \(\sigma\) preserves the splitting \(\mathfrak{g} = b \oplus a\).

3. There exists \(\xi \in \mathfrak{k}^*\) such that \(\Omega(X,Y) = \delta \xi = \langle \xi, [X,Y]_\mathfrak{g} \rangle\) (Chevalley 2-coboundary).

For such an elementary solvable symplectic symmetric space there exists a global Darboux chart such that \((M,\omega) \simeq (\mathfrak{p} = l \oplus a,\Omega)\) \([\text{Bie00}]\). So we have

\[
\mathcal{C}^\infty(M) \simeq \mathcal{C}^\infty(p) \simeq \mathcal{C}^\infty(l) \otimes \mathcal{C}^\infty(a) \simeq \mathcal{C}^\infty(l) \otimes \mathcal{C}^\infty(l^*) \otimes \mathcal{O}(l^*) \simeq \mathcal{C}^\infty(l) \otimes \mathcal{O}(1)_{\text{abelian}}
\]

One can now define \(\ast_{1/2}\) (Moyal) on \(\mathcal{C}^\infty(M) \simeq \mathcal{C}^\infty(l \oplus a)\) or, using our preceding construction, on \(\mathcal{C}^\infty(l) \otimes \mathcal{O}(1)\).

In order to have an invariant star product on \(M\) under the action of \(G\) (such that \(g = \text{Lie}(G)\)) \(P\). Bieliavsky \([\text{Bie00}]\) defines an integral transformation \(S : \mathcal{C}^\infty(l) \to \mathcal{C}^\infty(l)\) and then an invariant star product \(\ast_S\) by, for \(T := S \otimes \text{Id}\),

\[
(f \otimes a) \ast_S (g \otimes b) := T^{-1} \{(f \otimes a) \ast_{1/2}(g \otimes b)\}.
\]

Let us define \(f \ast_S g := S^{-1}(f \ast g)\), \(a \overset{S}{\rightarrow} f := S^{-1}(a \rightarrow f)\) and \(f \overset{S}{\leftarrow} a := S^{-1}(f \leftarrow a)\).

Proposition 7 ([BB02]) \(\ast_S\) is the L-R smash product of \((\mathcal{C}^\infty(l), \ast_S)\) by \(\mathcal{O}(1)\) with the \(\mathcal{O}(1)\)-bimodule structure given by \(\overset{S}{\leftarrow}\) and \(\overset{S}{\rightarrow}\).
**Remark 6** Since we were dealing with quantum groups in the first sections, we want to stress that the homogeneous (symmetric) spaces involved here are strictly different from those appearing in the quantum group approach of quantized homogeneous spaces [Dj79]. Indeed, in the latter, the spaces come from Poisson-Lie groups, so that the Poisson bracket has to be singular; therefore this bracket (and a fortiori a star product deforming this bracket) cannot be invariant (otherwise it would be zero everywhere). Here the Poisson brackets are invariant and regular.

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