On equilibrium equations and their perturbations using three different variational formulations of nonlinear electroelastostatics

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Abstract

We derive the equations of nonlinear electroelastostatics using three different variational formulations involving the deformation function and an independent field variable representing the electric character – considering either one of the electric field $\mathbf{E}$, electric displacement $\mathbf{D}$, or electric polarization $\mathbf{P}$. The first variation of the energy functional results in the set of Euler-Lagrange partial differential equations which are the equilibrium equations, boundary conditions, and certain constitutive equations for the electroelastic system. The partial differential equations for obtaining the bifurcation point have been also found using the second variation based bilinear functional. We show that the well-known Maxwell stress in vacuum is a natural outcome of the derivation of equations from the variational principles and does not depend on the formulation used. As a result of careful analysis it is found that there are certain terms in the bifurcation equation which appear difficult to obtain by an ordinary perturbation based analysis of the Euler-Lagrange equation. From a practical viewpoint, the formulations based on $\mathbf{E}$ and $\mathbf{D}$ result in simpler equations and are anticipated to be more suitable for analysing problems of stability as well as post-buckling behaviour.

Introduction

Early development of a nonlinear theory of elastic dielectrics is attributed to the seminal work of Toupin (1956). Past couple of decades have seen a surge in the study of a nonlinear theory of electroelasticity within the framework of Continuum Mechanics (Dorfmann and Ogden, 2005; McMeeking and Landis, 2005) largely motivated by the development of electro-active polymers (EAPs). EAPs are capable of producing large deformations in the presence of electric fields and alternatively can be used to convert mechanical deformation to electric potential difference (Pelrine et al., 2000; Kofod, 2001; Jung et al., 2008). Their use has been demonstrated in the development of artificial muscles and robotic manipulators (Wingert et al., 2006; Shintake et al., 2016), haptic interfaces (Ozsecen et al., 2010), electric generators (Pelrine et al., 2001), propulsion systems (Michel et al., 2008) and sensing equipments (O’Halloran et al., 2008).

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Development of variational principles for nonlinear electromechanics is essential to derive a consistent set of partial differential equations and suitable boundary conditions, analysis of stability of equilibrium, and to perform computations based on the finite element method. Initial variational principles have been provided by Pak and Herrmann (1986) and Yang and Batra (1995). McMeeking and Landis (2005) constructed principle of virtual work using the displacement and the electrostatic potential as the independent variable. Ericksen (2007) has revisited the theory of Toupin from a different starting point and derived a variational principle. Variational principles that are applicable up to derivation of equilibrium equations by taking the first variation are also presented by Bustamante et al. (2009a) and they are discussed in more detail later in the book by Dorfmann and Ogden (2014b). A variational principle with application to numerical computations (albeit only for computing equilibrium) has been presented by Vu and Steinmann (2012).

In this work, we present variational formulations of electroelasticity considering each one of either the electric field \( \mathbf{E} \), electric displacement \( \mathbf{D} \), or the electric polarization \( \mathbf{P} \) as the independent variable. For the formulations with \( \mathbf{E} \) and \( \mathbf{D} \), we start with the known potential energy functional given by Dorfmann and Ogden (2014b), while for the formulation with \( \mathbf{P} \) as the independent variable, we consider the potential energy functional used by Liu (2014). First variation of the functional gives the equilibrium equations and boundary conditions while second variation gives the equations for the critical point corresponding to a bifurcation of solution (onset of instability) (Koiter, 1965, 1970; van der Heijden, 2009; Hill, 1957). Critical instability points have also been studied by a direct perturbation of governing equations by Bertoldi and Gei (2011); Dorfmann and Ogden (2014a). We calculate the same Maxwell stress tensor outside the body for each of these three formulations (Bustamante et al., 2009b).

Computation of first variation for formulations based on \( \mathbf{D} \) apriori requires the Maxwell’s law that \( \mathbf{D} \) should satisfy. The Maxwell’s law corresponding to its conjugate vector \( \mathbf{E} \) is an outcome of the process along with a constitutive relationship between \( \mathbf{E} \) and \( \mathbf{D} \) via the energy density function. Similar observation is made for the variational formulation based on \( \mathbf{E} \). Differently from the above two, computation of first variation for formulations based on \( \mathbf{P} \) apriori requires the Maxwell’s laws both for \( \mathbf{E} \) and \( \mathbf{D} \). It is found that the formulations based on \( \mathbf{E} \) and \( \mathbf{D} \) result in simpler equations and are more amenable to the theory of ‘total energy’ and ‘total stress’ developed by Dorfmann and Ogden (2006) as the first Piola–Kirchhoff stress is obtained, quite simply, as the derivative of the energy density function with respect to the deformation gradient. However, this is not the case for the formulation based on \( \mathbf{P} \) primarily because polarisation vanishes outside the body.

This paper is organised as follows. After briefly introducing the mathematical preliminaries, in Section 1 we introduce the system under study and present the basic equations of nonlinear electroelasticity. In Sections 2 and 3, we present the derivations of first and second variations of the potential energy functionals corresponding to \( \mathbf{D} \) and \( \mathbf{E} \), respectively. In Section 4, we present the first variation of the potential energy functional corresponding to \( \mathbf{P} \) and then derive the equations for critical point by linearising the equilibrium equations. Some detailed calculations are presented in the three appendices.

Mathematical preliminaries

Direct notation of tensor algebra and tensor calculus is adopted throughout. The scalar product of two vectors \( \mathbf{a} \) and \( \mathbf{b} \) is denoted as \( \mathbf{a} \cdot \mathbf{b} = [\mathbf{a}]_i [\mathbf{b}]_i \), where a repeated index implies summation according to Einstein’s summation convention. The vector (cross) product of two vectors \( \mathbf{a} \) and \( \mathbf{b} \) is denoted as \( \mathbf{a} \times \mathbf{b} = [\mathbf{a}]_i [\mathbf{b}]_j \epsilon_{ijk} \). The tensor product of two vectors \( \mathbf{a} \) and \( \mathbf{b} \) is a second order tensor \( \mathbf{H} = \mathbf{a} \otimes \mathbf{b} \) with \( [\mathbf{H}]_{ij} = [\mathbf{a}]_i [\mathbf{b}]_j \). Operation of a second order tensor \( \mathbf{H} \) on a vector \( \mathbf{a} \) is given by \( [\mathbf{H} \mathbf{a}]_i = [\mathbf{H}]_{ij} [\mathbf{a}]_j \). Scalar product of two tensors \( \mathbf{H} \) and \( \mathbf{G} \) is denoted as \( \mathbf{H} \cdot \mathbf{G} = [\mathbf{H}]_{ij} [\mathbf{G}]_{ij} \). A list of key variables used throughout this manuscript is presented in Table 1.
Table 1: Notation used in this manuscript.

| Symbol | Description                      | Symbol | Description                      |
|--------|----------------------------------|--------|----------------------------------|
| \( \mathbf{x} \) | Position vector (spatial) | \( \mathbf{X} \) | Position vector (referential) |
| \( \mathbf{n} \) | Unit outward normal (spatial) | \( \mathbf{n}_0 \) | Unit outward normal (referential) |
| \( \phi \) | Electric scalar potential (spatial) | \( \Phi \) | Electric scalar potential (referential) |
| \( \mathbf{a} \) | Electric vector potential (spatial) | \( \mathbf{A} \) | Electric vector potential (referential) |
| \( \mathbf{e} \) | Electric field vector (spatial) | \( \mathbf{E} \) | Electric field vector (referential) |
| \( \mathbf{d} \) | Electric displacement vector (spatial) | \( \mathbf{D} \) | Electric displacement vector (referential) |
| \( \mathbf{p} \) | Electric polarization vector (spatial) | \( \mathbf{P} \) | Electric polarization vector (referential) |
| \( \sigma \) | Cauchy stress tensor | \( \mathbf{P} \) | First Piola–Kirchhoff stress tensor |
| \( \llbracket \{ \bullet \} \rrbracket \) | Jump of a quantity across the boundary | \( \{ \bullet \}_G \) | Partial derivative with respect to \( G \) |

For tensor calculus and variational method, we refer to (Knowles, 1997; Itskov, 2018) and (Gelfand and Fomin, 2003; Giaquinta and Hildebrandt, 2010), respectively, whereas the notation and definitions of physical entities in continuum mechanics typically follow (Gurtin, 1981).

1 Nonlinear electroelastostatics: some fundamental equations and entities

Consider a deformable body absent of free surface or volume charges occupying a domain \( \mathcal{B} \) lying inside a region \( \mathcal{V} \) as schematically depicted in Figure 1. We denote the exterior of the body relative to \( \mathcal{V} \) by

\[
\mathcal{B}' = \mathcal{V} \setminus (\mathcal{B} \cup \partial \mathcal{B}).
\]

We assume that the body occupies a domain \( \mathcal{B}_0 \) in its reference configuration. The points in domains \( \mathcal{B}_0 \) and \( \mathcal{B} \) corresponding to the same material point of the body are naturally mapped into each other by the deformation function

\[
\chi : \mathcal{B}_0 \to \mathcal{B}.
\]

In order to make sense of the Lagrangian description of fields in current region \( \mathcal{V} \), but outside the body, in a meaningful manner, we also define an extension of the deformation function \( \chi \) to the part of domain outside the body such that sufficient continuity requirements are maintained. Thus, by an abuse of notation, we assume an extension of mapping \( \chi \) on a larger region, also denoted by

\[
\chi : \mathcal{V}_0 \to \mathcal{V},
\]

where \( \mathcal{V}_0 \) is the referential region corresponding to \( \mathcal{V} \). This concept of a fictitious deformation function was initially used by Toupin (1956) (and possibly others) for similar problems. Following standard notation in continuum mechanics, we define the deformation gradient as \( \mathbf{F} = \text{Grad} \chi \). The extension of \( \chi \) to \( \mathcal{V}_0 \) allows us to define the exterior of the body in the reference configuration; this is denoted by

\[
\mathcal{B}'_0 = \mathcal{V}_0 \setminus (\mathcal{B}_0 \cup \partial \mathcal{B}_0).
\]

The electric field vector, electric displacement vector, and the electric polarization vector are denoted in the reference configuration as \( (\mathbf{E}, \mathbf{D}, \mathbf{P}) \), respectively and in the current configuration as \( (\mathbf{e}, \mathbf{d}, \mathbf{p}) \).
Electroelasticity

The deformation gradient as $F = \text{Grad} \chi$. Exterior of the $B^\prime$ in the reference configuration.

$B_0 \to B$. In order to be able

∀ $X \in B \cup B^\prime$, (2).

The divergence-free and curl-free conditions (2) lead to the existence of electric potential (vector) field $\mathbf{a}$ and electric potential (scalar) field $\phi$ on $B \cup B^\prime$; the respective expressions of $\mathbf{d}$ and $\mathbf{e}$ are given by $\mathbf{d} = \text{curl} \mathbf{a}$, $\mathbf{e} = -\text{grad} \phi$.

By using the Lagrangian counterparts of $\mathbf{d}$ and $\mathbf{e}$, defined by $\mathbf{D} = J F^{-1} \mathbf{d}$, $\mathbf{E} = F^\top \mathbf{e}$, we rewrite the Maxwell’s equations (2) in the reference configuration as $\text{Div} \mathbf{D} = 0$, $\text{Curl} \mathbf{E} = 0$, $\forall X \in B_0 \cup B_0^\prime$. (5)

Based on the referential equations (5), we also define the suitable Lagrangian counterparts of the electric vector potential and electric scalar potential on $B_0 \cup B_0^\prime$ as $\mathbf{D} = \text{Curl} \mathbf{A}$, $\mathbf{E} = -\text{Grad} \Phi$. (6)

It can be shown using tensor algebra and calculus that $\mathbf{A}(X) = F^\top(X) \mathbf{a}(x) \bigg|_{x=\chi(X)}$, $\Phi(X) = \phi(x) \bigg|_{x=\chi(x)}$. (7)
for all \( \mathbf{X} \in B_0 \cup B'_0 \). Upon substituting the transformations (4) into the constitutive relation (1), we get

\[
J^{-1} \mathbf{C} \mathbf{D} = \varepsilon_0 \mathbf{E} + \mathbf{P},
\]

where \( \mathbf{P} \) denotes the Lagrangian electric polarization vector field that relates to the current electric polarization vector field by

\[
\mathbf{P}(\mathbf{X}) = F^\top(\mathbf{X}) \mathbf{p}(\mathbf{x}) \bigg|_{x=\chi(\mathbf{X})},
\]

for all \( \mathbf{X} \in B_0 \cup B'_0 \) (as \( \mathbf{p} \) is zero in \( B' \), we also get vanishing \( \mathbf{P} \) in \( B'_0 \)).

2 Variational formulation based on electric displacement \( \mathbf{D} \)

Using the fact that \( \mathbf{D} \) is found in terms of \( \mathbf{A} \) by (6), i.e., \( \mathbf{D} = \text{Curl} \ \mathbf{A} \), the total potential energy of the system, i.e., the body and its exterior, is written as a functional depending on the deformation \( \chi \) and \( \mathbf{A} \) as (Dorfmann and Ogden, 2014b)

\[
E[\chi, \mathbf{A}] = \int_{B_0} \Omega(F, \mathbf{D})dv_0 + \frac{1}{2\varepsilon_0} \int_{B'_0} J^{-1}[F \mathbf{D}] : [F \mathbf{D}]dv_0 + \int_{\partial\mathcal{V}} [\mathbf{e}_a \wedge \mathbf{A}] \cdot \mathbf{n}ds
- \int_{B_0} \mathbf{f}^e \cdot \chi dv_0 - \int_{\partial B_0} \mathbf{t}^e \cdot \chi ds_0,
\]

where \( \Omega \) is the (scalar) total stored energy density per unit volume, \( \mathbf{e}_a \) is the externally applied electric (vector) field whose tangential component is prescribed on \( \partial\mathcal{V} \), \( \mathbf{f}^e \) is the body force (vector) field per unit volume while \( \mathbf{t}^e \) is the applied traction (vector) field due to dead loads at the boundary of the body in its current configuration. In (10) the integration is defined on the reference configuration and the current fields are mapped to the reference by using the mapping \( \chi \) as placement. The exception is the third term in equation (10), which is written in terms of the current region \( \mathcal{V} \). However, it assumed that the boundary (typically, \( \text{infinitely far away} \) is fixed (i.e., it does not change in space between reference and current description), so that the third term in equation (10) is also rewritten in the reference configuration simply as

\[
\int_{\partial\mathcal{V}_0} [\mathbf{E}_a \wedge \mathbf{A}] \cdot \mathbf{n}_0 ds_0.
\]

Notice that \( \mathbf{n}_0 \) and \( \mathbf{n} \) are used to denote the outward unit normals for the region \( \mathcal{V}_0 \) and \( \mathcal{V} \) as well.

2.1 Equilibrium: first variation

In order to describe \( \chi \) and \( \mathbf{A} \) when the body is in a state of equilibrium, the first variation of the energy functional should vanish, that is, using the functional (10)

\[
\delta E \equiv \delta E[\chi, \mathbf{A}; (\delta \chi, \delta \mathbf{A})] = 0.
\]

An expansion of the functional \( E \) up to the first order, owing to a variation of its arguments \( \chi \) and \( \mathbf{A} \), is given by

\[
E[\chi + \delta \chi, \mathbf{A} + \delta \mathbf{A}] = \int_{B_0} \Omega(F + \delta F, \mathbf{D} + \delta \mathbf{D})dv_0
\]
Using an elementary identity for vector fields, the total potential as stated above. Thus, it is found that the first variation \( \delta E \) of \( E \) is given by

\[
\delta E = E[\chi + \delta \chi, \mathbf{A} + \delta \mathbf{A}] - E[\chi, \mathbf{A}]
\]

\[
= \int_{B_0} [\Omega \cdot \delta \mathbf{F} + \Omega \cdot \mathbf{D} \cdot \text{Curl} \delta \mathbf{A}] \, dv_0
\]

\[
+ \frac{1}{2\varepsilon_0} \int_{B_0} \left[ - J^{-1} [\mathbf{F}^{-\top} \cdot \delta \mathbf{F}] [\mathbf{D}] \cdot [\mathbf{F}] + 2 J^{-1} [[\mathbf{F}] \otimes \mathbf{D}] \cdot \delta \mathbf{F} + 2 [C \mathbf{D}] \cdot \text{Curl} \delta \mathbf{A} \right] \, dv_0
\]

\[
+ \int_{\partial V_0} [\mathbf{n} \wedge [\mathbf{E}_a] \cdot \delta \mathbf{A}] \, ds_0 - \int_{B_0} \tilde{\mathbf{e}} \cdot \delta \chi \, dv_0 - \int_{\partial B_0} \tilde{\mathbf{e}} \cdot \delta \chi \, ds_0.
\]  

(13)

Taking advantage of the referential description, noting that

\[
\delta \mathbf{D} = \text{Curl} \delta \mathbf{A},
\]

while using expressions for first order variations stated in the form of Appendix A, we simplify further the expression of \( E[\chi + \delta \chi, \mathbf{A} + \delta \mathbf{A}] \) stated above. Thus, it is found that the first variation \( \delta E \) of \( E \) is given by

\[
\delta E = E[\chi + \delta \chi, \mathbf{A} + \delta \mathbf{A}] - E[\chi, \mathbf{A}]
\]

\[
= \int_{B_0} [\Omega \cdot \delta \mathbf{F} + \Omega \cdot \mathbf{D} \cdot \text{Curl} \delta \mathbf{A}] \, dv_0
\]

\[
+ \frac{1}{2\varepsilon_0} \int_{B_0} \left[ - J^{-1} [\mathbf{F}^{-\top} \cdot \delta \mathbf{F}] [\mathbf{D}] \cdot [\mathbf{F}] + 2 J^{-1} [[\mathbf{F}] \otimes \mathbf{D}] \cdot \delta \mathbf{F} + 2 [C \mathbf{D}] \cdot \text{Curl} \delta \mathbf{A} \right] \, dv_0
\]

\[
+ \int_{\partial V_0} [\mathbf{n} \wedge [\mathbf{E}_a] \cdot \delta \mathbf{A}] \, ds_0 - \int_{B_0} \tilde{\mathbf{e}} \cdot \delta \chi \, dv_0 - \int_{\partial B_0} \tilde{\mathbf{e}} \cdot \delta \chi \, ds_0.
\]

(15)

Using an elementary identity for vector fields \( \mathbf{u} \) and \( \mathbf{v} \), namely,

\[
\mathbf{v} \cdot \text{Curl} \mathbf{u} = \text{Div} [\mathbf{u} \wedge \mathbf{v}] + [\text{Curl} \mathbf{v}] \cdot \mathbf{u},
\]

we expand the above expression for \( \delta E \) as

\[
\delta E = \int_{B_0} [\Omega \cdot \delta \mathbf{F} + [\text{Curl} \Omega, \mathbf{D}] \cdot \delta \mathbf{A}] \, dv_0 + \int_{\partial B_0} [\mathbf{n} \cdot [\Omega, \mathbf{D}] \wedge \delta \mathbf{A}] \, ds_0
\]

\[
- \frac{1}{\varepsilon_0} \int_{\partial B_0} [\mathbf{n} \cdot [\mathbf{D}, \mathbf{D}] \wedge \delta \mathbf{A}] \, ds_0 + \frac{1}{2\varepsilon_0} \int_{B_0} \left[ - J^{-1} [\mathbf{F}^{-\top} \cdot \delta \mathbf{F}] [\mathbf{D}] \cdot [\mathbf{F}] + 2 J^{-1} [[\mathbf{F}] \otimes \mathbf{D}] \cdot \delta \mathbf{F} + 2 [C \mathbf{D}] \cdot \text{Curl} \delta \mathbf{A} \right] \, dv_0
\]

\[
+ [\text{Curl} (\mathbf{D}, \mathbf{D})] \cdot \delta \mathbf{A} \right] \, dv_0 + \int_{\partial V_0} [\mathbf{n} \wedge [\mathbf{E}_a - \frac{1}{\varepsilon_0} C \mathbf{D}] \cdot \delta \mathbf{A}] \, ds_0 - \int_{B_0} \tilde{\mathbf{e}} \cdot \delta \chi \, dv_0 - \int_{\partial B_0} \tilde{\mathbf{e}} \cdot \delta \chi \, ds_0.
\]

(17)

Inspection of above leads to consideration of the definition of a tensor field given by

\[
P_m = \frac{1}{\varepsilon_0 J} \left[ [\mathbf{F} \mathbf{D}] \otimes [\mathbf{F} \mathbf{D}] - \frac{1}{2} [\mathbf{F} \mathbf{D}] \cdot [\mathbf{F} \mathbf{D}] \mathbf{I} \right] \mathbf{F}^{-\top},
\]

(18)

where \( \mathbf{I} \) is a two-point identity tensor. Using the definition (18), we rewrite the first variation \( \delta E \) of the total potential as

\[
\delta E = \int_{B_0} \left[ - \left[ \text{Div} (\Omega \cdot \mathbf{F}) + \tilde{\mathbf{e}} \right] \cdot \delta \chi + [\text{Curl} \Omega, \mathbf{D}] \cdot \delta \mathbf{A} \right] \, dv_0
\]


Following the traditional definition, the total (first Piola–Kirchhoff) stress $P$ in the body is

$$P = \Omega F, \quad \text{in} \quad B_0, \quad (20)$$

and the (Maxwell) stress outside the body is given by (18), i.e.,

$$P = P_m, \quad \text{in} \quad B'_0. \quad (21)$$

Upon applying the condition (12) to the first variation (19) calculated above, the coefficients of arbitrary variations $\delta \chi$ and $\delta A$ should vanish for $\delta E$ to vanish. Vanishing of the coefficients of $\delta \chi$ results in the following equations

$$\text{Div} P + \tilde{f} = 0, \quad \text{in} \quad B_0, \quad (22a)$$

$$\text{Div} P = 0, \quad \text{in} \quad B'_0, \quad (22b)$$

$$[P] n_0 + \tilde{t} = 0, \quad \text{on} \quad \partial B_0, \quad (22c)$$

$$P n_0 = 0, \quad \text{on} \quad \partial V_0. \quad (22d)$$

We define the electric field $\mathbb{E}$ in the body as

$$\mathbb{E} = \Omega D = \frac{1}{\varepsilon_0} \left[ J^{-1} C D - \mathbb{P} \right], \quad \text{in} \quad B_0, \quad (23)$$

and outside the body as

$$\mathbb{E} = \frac{1}{\varepsilon_0} J^{-1} C D, \quad \text{in} \quad B'_0, \quad (24)$$

because the electric polarization $\mathbb{P}$ vanishes in $B'_0$ and use has been made of the constitutive relation (8). Since the body $B_0$ and normal to the boundary $n_0$ can be chosen arbitrarily, we get the following relations from the vanishing of the coefficients of $\delta A$

$$\text{Curl}(\mathbb{E}) = 0, \quad \text{in} \quad B_0 \cup B'_0, \quad (25a)$$

$$n_0 \wedge [\mathbb{E}] = 0, \quad \text{on} \quad \partial B_0, \quad (25b)$$

$$n_0 \wedge (\mathbb{E}_0 - \mathbb{E}) = 0, \quad \text{on} \quad \partial V_0. \quad (25c)$$

**Remark 2.1.** The Cauchy stress $\sigma$ in the body is related to the first Piola–Kirchhoff (20) by the Piola transform as

$$\sigma \ cof(F) = P. \quad (26)$$

Upon using the relation (4) and the tensor field stated as (18), the counterpart $\sigma_m$ of the Cauchy stress
stress $\sigma$ in $B'$ (vacuum) is given by the expression

$$\sigma = \sigma_m = \frac{1}{\varepsilon_0} \left( d \otimes d - \frac{1}{2} (d \cdot d) i \right) \text{ in } B', \quad (27)$$

where $i$ is the spatial identity tensor.

**Remark 2.2.** We note that in this formulation based on the electric displacement vector, we have apriori assumed that the equation $(5)_1$ is satisfied by $\mathbb{D}$ and have recovered the equation $(5)_2$ for the electric field $E$ as the Euler-Lagrange equation for the variational (energy minimisation) problem. This procedure implies the constitutive assumption $E = \Omega_{\mathbb{D}}$; the same constitutive assumption has been also independently derived using the second law of thermodynamics (Dorfmann and Ogden, 2005).

### 2.2 Critical point: second variation

For the analysis of critical point $(\chi, \mathbf{A})$, we need to find the functions $\Delta \chi$ and $\Delta \mathbf{A}$ such that the bilinear functional defined below vanishes at the critical point, that is

$$\delta^2 E \equiv \delta^2 E[\chi, \mathbf{A}; (\delta \chi, \delta \mathbf{A}), (\Delta \chi, \Delta \mathbf{A})] = 0. \quad (28)$$

Upon using the expressions derived in Appendix B, the bilinear functional associated with the second variation (28) of $E$ is expanded into the form

$$\delta^2 E = \int_{B_0} \left[ \Omega_{F\mathbb{D}} \Delta F + \frac{1}{2} \Omega_{F\mathbb{D}} \mathbb{D} \mathbb{D} + \frac{1}{2} \widetilde{\Omega}_{F\mathbb{D}} \Delta \mathbb{D} \right] \cdot \delta F$$

$$+ \left[ \Omega_{\mathbb{D}F\mathbb{D}} \Delta \mathbb{D} + \frac{1}{2} \Omega_{\mathbb{D}F\mathbb{D}} \mathbb{D} \mathbb{D} + \frac{1}{2} \widetilde{\Omega}_{\mathbb{D}F\mathbb{D}} \mathbb{D} \mathbb{D} F \mathbb{D} + \frac{1}{2} \widetilde{\Omega}_{\mathbb{D}F\mathbb{D}} \mathbb{D} \mathbb{D} F \mathbb{D} \right] \cdot \delta \mathbb{D} \right] dv_0$$

$$+ \frac{1}{2\varepsilon_0} \int_{B_0} J^{-1} \left[ [F \mathbb{D}] : [F \mathbb{D}] \left[ [F^{-T} \cdot \Delta F] [F^{-T} \cdot \delta F] + F^{-T} [\Delta F] \right] F^{-T} \cdot \delta F \right.$$

$$- 2 \left[ [\Delta F \mathbb{D}] \cdot [F \mathbb{D}] + [F \mathbb{D} \cdot \Delta \mathbb{D}] \cdot [F \mathbb{D}] \right] F^{-T} \cdot \delta F$$

$$- 2 \left[ [\delta F \mathbb{D}] \cdot [F \mathbb{D}] + [F \mathbb{D} \cdot \delta \mathbb{D}] \cdot [F \mathbb{D}] \right] F^{-T} \cdot \Delta F$$

$$+ 2 \left[ [\Delta F \mathbb{D}] \cdot [\delta F \mathbb{D}] + [F \mathbb{D} \cdot \Delta \mathbb{D}] \cdot [F \mathbb{D}] + 2 \delta F \mathbb{D} \cdot F \Delta \mathbb{D} + 2 \Delta F \mathbb{D} \cdot F \delta \mathbb{D} \right.$$\n
$$+ 2 \left[ \Delta F \mathbb{D} \cdot [\delta F \mathbb{D}] + 2 \left[ F \mathbb{D} \cdot \Delta \mathbb{D} \right] \cdot [F \mathbb{D} \cdot \delta \mathbb{D}] \right] dv_0. \quad (29)$$

In the expression stated above we have defined the third order tensors $\widetilde{\Omega}_{F\mathbb{D}}$ and $\widetilde{\Omega}_{\mathbb{D}F}$ according to the following property

$$\left[ \widetilde{\Omega}_{F\mathbb{D}} \mathbf{u} \right] \cdot \mathbf{U} = [\Omega_{\mathbb{D}F} \mathbf{u}] \cdot \mathbf{U}, \quad \left[ \widetilde{\Omega}_{\mathbb{D}F} \mathbf{u} \right] \cdot \mathbf{U} = [\Omega_{F\mathbb{D}} \mathbf{u}] \cdot \mathbf{U}, \quad (30)$$

$$8$$
which holds for arbitrary \( \mathbf{u} \) and \( \mathbf{U} \), while \( \mathbf{u} \) is a vector and \( \mathbf{U} \) is a second order tensor. Using the expression (29) of \( \partial^2 E \), in the region \( B'_0 \) the terms containing \( \partial \mathbf{D} \) can be written in the form \( \mathbf{v}_0 \cdot \partial \mathbf{D} \) where

\[
\mathbf{v}_0 = \frac{1}{\varepsilon_0 J} \left[ - \left( \mathbf{F}^{-\top} \partial \mathbf{F} \right) \mathbf{F}^{-\top} \mathbf{D} + \left[ \partial \mathbf{F} \right]^{-\top} \mathbf{F} \mathbf{D} + \mathbf{F}^{-\top} \partial \mathbf{F} \mathbf{D} + \mathbf{F}^{-\top} \partial \mathbf{F} \mathbf{D} \right].
\]  

(31)

Since equation (8) gives \( \mathbf{E} = J^{-1} \varepsilon_0^{-1} C \mathbf{D} \) in \( B'_0 \), it is easy to see that

\[
\mathbf{v}_0 = \partial \mathbf{E}.
\]  

(32)

Also, in the expression (29) of \( \partial^2 E \), in the region \( B'_0 \) the terms containing \( \partial \mathbf{F} \) can be written in the form \( \mathbf{T} \cdot \partial \mathbf{F} \) where

\[
\mathbf{T} = \frac{1}{2 \varepsilon_0 J} \left[ \left[ \mathbf{F} \mathbf{D} \right] : \left[ \mathbf{F} \mathbf{D} \right] \left[ \left( \mathbf{F}^{-\top} \partial \mathbf{F} \right) \mathbf{F}^{-\top} + \left[ \partial \mathbf{F} \right]^{-\top} \mathbf{F} \mathbf{D} \right] + \mathbf{F}^{-\top} \partial \mathbf{F} \mathbf{D} \right]
- 2 \left[ \left[ \partial \mathbf{F} \mathbf{D} \right] \cdot \left[ \mathbf{F} \mathbf{D} \right] + \left[ \mathbf{F} \partial \mathbf{D} \right] \cdot \left[ \mathbf{F} \mathbf{D} \right] \right] \mathbf{F}^{-\top} - 2 \left[ \mathbf{F}^{-\top} \partial \mathbf{F} \right] \left[ \mathbf{F} \mathbf{D} \right] \otimes \mathbf{D}
+ 2 \left[ \mathbf{F} \mathbf{D} \right] \otimes \partial \mathbf{D} + 2 \left[ \mathbf{F} \partial \mathbf{D} \right] \otimes \mathbf{D} + 2 \left[ \partial \mathbf{F} \mathbf{D} \right] \otimes \mathbf{D} \right].
\]  

(33)

By expanding the expression stated in equation (18), to first order perturbation, it is seen that

\[
\mathbf{T} = \partial \mathbf{P}_m.
\]  

(34)

With the details provided in Appendix C based on repeated application of the triple product identity involving the curl operator (16) and the divergence theorem, while observing that the variations \( \partial \chi \) and \( \partial \mathbf{A} \) are arbitrary, the equation \( \partial^2 E = 0 \) (29) finally leads to the following partial differential equations

\[
\text{Div} \left( \Omega_{,FF} \partial \mathbf{F} + \frac{1}{2} \left[ \Omega_{,F} \mathbf{D} + \bar{\Omega}_{,F} \mathbf{D} \right] \partial \mathbf{D} \right) = 0 \text{ in } B_0,
\]  

(35a)

\[
\text{Curl} \left( \Omega_{,D} \partial \mathbf{D} + \frac{1}{2} \left[ \Omega_{,D} \mathbf{F} + \bar{\Omega}_{,D} \mathbf{F} \right] \partial \mathbf{F} \right) = 0 \text{ in } B_0,
\]  

(35b)

\[
\left[ \Omega_{,FF} \partial \mathbf{F} + \frac{1}{2} \left[ \Omega_{,F} \mathbf{D} + \bar{\Omega}_{,F} \mathbf{D} \right] \partial \mathbf{D} \right] \mathbf{n}_0 = 0 \text{ on } \partial B_0,
\]  

(35c)

\[
\left[ \Omega_{,D} \partial \mathbf{D} + \frac{1}{2} \left[ \Omega_{,D} \mathbf{F} + \bar{\Omega}_{,D} \mathbf{F} \right] \partial \mathbf{F} \right] \mathbf{n}_0 = 0 \text{ on } \partial B_0,
\]  

(35d)

\[
\text{Div}(\mathbf{T}) = 0 \text{ in } B'_0,
\]  

(35e)

\[
\text{Curl}(\mathbf{v}_0) = 0 \text{ in } B'_0,
\]  

(35f)

\[
\mathbf{Tn}_0 = 0 \text{ on } \partial V_0,
\]  

(35g)

\[
\mathbf{v}_0 \wedge \mathbf{n}_0 = 0 \text{ on } \partial V_0.
\]  

(35h)

The set of equations (35) need to be solved for the non-trivial unknown functions \( \left( \partial \chi, \partial \mathbf{A} \right) \) describing the onset of bifurcation.

Remark 2.3. Note that since we have proved \( \mathbf{T} = \partial \mathbf{P}_m \) and \( \mathbf{v}_0 = \partial \mathbf{E} \), it also follows that the above set of equations for the variations \( \partial \mathbf{D} \) and \( \partial \mathbf{F} \) in \( B'_0 \) can be alternatively obtained by perturbing the corresponding equations of equilibrium (22a)–(25c). However, perturbation of the governing equations in \( B_0 \) do not result in the above equations due to presence of the \( \frac{1}{2} \left[ \Omega_{,F} \mathbf{D} + \bar{\Omega}_{,F} \mathbf{D} \right] \).
and $\frac{1}{2} \left[ \tilde{\Omega}_{1} F + \tilde{\Omega}_{2} F \right]$ terms. This general argument can be relaxed in cases when the energy density function $\Omega$ is assumed to be sufficiently continuous as has been considered, for example, by Dorfmann and Ogden (2010, 2014a).

**Remark 2.4.** We note in passing that the analysis presented above can be extended to include the special case of incompressibility in a straightforward manner. The assumption of incompressibility is equivalent to the constraint $J - 1 = 0$ in $B_0$. Hence, we consider a modified energy function which includes one more term

$$g(F) = p[J - 1],$$

(36)

in the integrand of total energy density in bulk. In this modified energy function, the scalar field $p$ is recognized as the Lagrange multiplier associated with the incompressibility constraint. Due to a variation $\delta \chi$, we get the following Taylor’s expansion for $g$

$$g(F + \delta F) = p[J - 1 + \delta J + \delta^2 J]$$

$$= p \left[ J - 1 + J F^{-\top} \cdot \delta F + \frac{1}{2} J \left[ F^{-\top} \cdot \delta F \right] \left[ F^{-\top} \cdot \delta F \right] F^{-\top} \left[ \delta F \right] F^{-\top} \cdot \delta F \right].$$

(37)

Substituting the above in the first variation of total potential energy functional and setting $J = 1$, we get the following updated constitutive equation for the first Piola–Kirchhoff stress

$$P = \Omega_F + p F^{-\top}.$$

(38)

### 3 Variational formulation based on electric field $E$

Noting that $E = - \text{Grad} \Phi$, the total potential energy of the system is written as (Dorfmann and Ogden, 2014b)

$$E[\chi, \Phi] = \int_{B_0} \tilde{\Omega}(F, E) d\nu_0 - \frac{1}{2} \varepsilon_0 \int \frac{1}{J} \left[ F^{-\top} \cdot \delta F \right] \left[ F^{-\top} \cdot \delta F \right] F^{-\top} \left[ \delta F \right] F^{-\top} \cdot \delta F \right]_0$$

$$- \int_{\partial \Omega_0} \tilde{f}_e \cdot \chi ds_0 - \int_{\partial \Omega_0} \tilde{t}_e \cdot \chi ds_0,$$

(39)

where $\tilde{\Omega}$ is the stored energy density per unit volume that depends on the deformation gradient $F$ and the referential electric displacement vector $E$. $d_o$ is the externally applied electric displacement whose normal component is prescribed on $\partial \Omega$, $\tilde{f}_e$ is the body force per unit volume while $\tilde{t}_e$ is the applied traction at the boundary. The third term in equation (39) is in the current configuration but the same argument as that preceding (11) allows it to be rewritten in the reference configuration as

$$- \int_{\partial \Omega_0} \Phi D_a \cdot n_0 ds_0.$$

(40)
3.1 Equilibrium: first variation

At state of equilibrium, $\chi$ and $\Phi$ are such that the first variation of the energy functional vanishes satisfying an analogue of equation (12), i.e.,

$$\delta E \equiv \delta E[\chi, \Phi; (\delta \chi, \delta \Phi)] = 0.$$  \hspace{1cm} (41)

The variation of the functional $E$ up to the first order in $(\delta \chi, \delta \Phi)$ is given by

$$\delta E = E[\chi + \delta \chi, \Phi + \delta \Phi] - E[\chi, \Phi] = \int_{B_0} \left[ \tilde{\Omega}_F \cdot \delta F - \tilde{\Omega}_{\mathbb{E}} \cdot \text{Grad} \delta \Phi \right] dv_0$$

$$- \frac{1}{2} \varepsilon_0 \int_{B_0} \left[ J F^{-\top} \cdot \delta F \left[ F^{-\top} \mathbb{E} \right] \cdot \left[ F^{-\top} \mathbb{E} \right] - 2J \left[ F^{-\top} \delta F \right] \cdot \left[ F^{-\top} \mathbb{E} \right] \right] dv_0$$

$$+ \frac{2J}{2} \left[ F^{-\top} \mathbb{E} \right] \cdot \left[ F^{-\top} \delta \Phi \right] dv_0 - \int_{\partial V_0} \delta \Phi \mathbb{D}_a \cdot n_0 ds_0 - \int_{\partial B_0} \tilde{\mathbf{f}} \cdot \delta \chi ds_0.$$  \hspace{1cm} (42)

We define the first Piola–Kirchhoff stress $\mathbf{P}$ and electric displacement $\mathbb{D}$ in the body as

$$\mathbf{P} = \tilde{\Omega}_F, \quad \mathbb{D} = -\tilde{\Omega}_{\mathbb{E}} \quad \text{in} \quad B_0,$$  \hspace{1cm} (43)

the (Maxwell) stress $\mathbf{P}_m$ outside the body as used earlier in equation (18) and recall the relation $J^{-1} \mathbf{F} \mathbb{D} = \varepsilon_0 \mathbf{F}^{-\top} \mathbb{E}$ in vacuum from equation (8). Using the above relations (43), we rewrite the first variation (42) as

$$\delta E = \int_{B_0} \left[ \text{Div} (\mathbf{P}^\top \delta \chi) - \left[ \text{Div} \mathbf{P} + \tilde{\mathbf{f}} \right] \cdot \delta \chi + \text{Div} (\delta \Phi \mathbb{D}) - \delta \Phi \text{Div} \mathbb{D} \right] dv_0$$

$$+ \int_{B_0} \left[ \text{Div} (\mathbf{P}_m^\top \delta \chi) - \left[ \text{Div} \mathbf{P}_m \right] \cdot \delta \chi + \text{Div} (\delta \Phi \mathbb{D}) - \delta \Phi \text{Div} \mathbb{D} \right] dv_0$$

$$- \int_{\partial V_0} \delta \Phi \mathbb{D}_a \cdot n_0 ds_0 - \int_{\partial B_0} \tilde{\mathbf{f}} \cdot \delta \chi ds_0.$$  \hspace{1cm} (44)

After an application of divergence theorem to (44), we get

$$\delta E = \int_{B_0} \left[ - \left[ \text{Div}(\mathbf{P}) + \tilde{\mathbf{f}} \right] \cdot \delta \chi - \delta \Phi \text{Div} \mathbb{D} \right] dv_0$$

$$+ \int_{\partial B_0} \left[ \mathbf{P}_m \cdot \delta \chi - \partial \mathbb{D} \cdot \mathbf{n}_0 \right] ds_0$$

$$+ \int_{\partial B_0} \left[ - \text{Div} \mathbf{P}_m \cdot \delta \chi - \delta \Phi \text{Div} \mathbb{D} \right] dv_0$$

$$+ \int_{\partial V_0} \mathbf{P}_m \mathbb{D}_a \cdot \mathbf{n}_0 \cdot \delta \chi + \delta \Phi \left[ \mathbb{D} - \mathbb{D}_a \right] \cdot \mathbf{n}_0 \right] dv_0.$$  \hspace{1cm} (45)
Since the two variations $\delta \chi$ and $\delta \Phi$ are arbitrary, their coefficients in each of the integrals must vanish. Accordingly, using the coefficient of $\delta \chi$ in (45), we get the equations

$$\text{Div} \mathbf{P} + \tilde{f}^e = 0, \quad \text{in } \mathcal{B}_0,$$

$$\text{Div} \mathbf{P} = 0, \quad \text{in } \mathcal{B}'_0,$$  \hspace{1cm}  \text{(46a)}

$$[\mathbf{P}] n_0 + \tilde{e}^e = 0, \quad \text{on } \partial \mathcal{B}_0,$$  \hspace{1cm}  \text{(46c)}

$$\mathbf{P} n_0 = 0, \quad \text{on } \partial \mathcal{V}_0,$$  \hspace{1cm}  \text{(46d)}

while the coefficient of $\delta \Phi$ in (45) leads to the equations

$$\text{Div} \mathbf{D} = 0, \quad \text{in } \mathcal{B}_0,$$  \hspace{1cm}  \text{(47a)}

$$\text{Div} \mathbf{D} = 0, \quad \text{in } \mathcal{B}'_0,$$  \hspace{1cm}  \text{(47b)}

$$[\mathbf{D}] \cdot n_0 = 0, \quad \text{on } \partial \mathcal{B}_0,$$  \hspace{1cm}  \text{(47c)}

$$[\mathbf{D}] \cdot n_0 = 0, \quad \text{on } \partial \mathcal{V}_0,$$  \hspace{1cm}  \text{(47d)}

Remark 3.1. Parallel to the remark 2.2 at the end of Section 2.1, we note that in this formulation based on the electric field (equivalently, the electric scalar potential), we have a priori assumed the equation (5) that $\mathbf{E}$ should satisfy and have recovered the equation (5) for the electric displacement $\mathbf{D}$ as an Euler-Lagrange equation of this minimisation problem. This procedure too implies the constitutive assumption $\mathbf{D} = -\tilde{\Omega}_E$ while it has been also independently derived earlier based on the second law of thermodynamics (Saxena et al., 2014).

Remark 3.2. We also note here that the two variational formulations based on $\mathbf{D}$ and $\mathbf{E}$ can be related by applying a Legendre-type transform on the energy functions $\Omega$ and $\tilde{\Omega}$ (Dorffmann and Ogden, 2005)

$$\Omega(F, \mathbf{D}) = \tilde{\Omega}(F, \mathbf{E}) + \mathbf{D} \cdot \mathbf{E}.$$  \hspace{1cm}  \text{(48)}

The above relations result in the electric constitutive relations (23) and (43). However, since $\mathbf{D}$ and $\mathbf{E}$ are not dual variables (a third electric variable $\mathbf{P}$ is also present), a proper Legendre transform to link $\Omega$ and $\tilde{\Omega}$ is not readily available. As such, the relation (48) leads to different convexity properties for $\Omega$ and $\tilde{\Omega}$ in general.

3.2 Critical point: second variation

For the analysis of critical point $(\chi, \Phi)$, we need to find $\Delta \chi$ and $\Delta \Phi$ such that certain bilinear functional based on the second variation vanishes at the critical point, that is

$$\delta^2 E \equiv \delta^2 E[\chi, \Phi; (\delta \chi, \delta \Phi), (\Delta \chi, \Delta \Phi)] = 0.$$  \hspace{1cm}  \text{(49)}

From the variational formulation based on the electric field $\mathbf{E}$ (39), using the expansions described in Appendix B, we get the expanded expression for $\delta^2 E$ as follows

$$\delta^2 E = \int_{\mathcal{B}_0} \text{Div} \left( \left[ \tilde{\Omega}_F F \Delta F + \frac{1}{2} \tilde{\Omega}_F F \Delta \mathbf{E} + \frac{1}{2} \tilde{\Omega}_F F \Delta \mathbf{E} \right]^\top \delta \chi \right).$$
while we have introduced the tensor $\tilde{T}$ and the vector $\tilde{v}_0$ as

$$\tilde{T} = J\varepsilon_0 \left[ F^{-T} [\Delta F] F^{-T} F^{-1} F^{-T} \right] + \left[ F^{-T} \Delta F F^{-1} - F^{-T} [\Delta F] F^{-T} \right] \rangle,$$

$$\tilde{v}_0 = J\varepsilon_0 \left[ F^{-1} \Delta F F^{-1} F^{-T} + F^{-1} F^{-T} [\Delta F] F^{-1} F^{-T} \right] \rangle,$$

while we have also utilized the definitions of two third order tensors $\hat{\Omega}_{F E}$ and $\hat{\Omega}_{E F},$ according to the relations

$$\left[ \hat{\Omega}_{F E} u \right] \cdot U = \left[ \hat{\Omega}_{E F} U \right] \cdot u, \quad \left[ \hat{\Omega}_{E F} U \right] \cdot u = \left[ \hat{\Omega}_{F E} u \right] \cdot U,$$

where $u$ and $U$ are arbitrary vector and arbitrary second order tensor, respectively. 

An application of divergence theorem to (50) gives

$$\delta^2 E = \int_{B_0} \left[ - \text{Div} \left( \hat{\Omega}_{F F} \Delta F + \frac{1}{2} \hat{\Omega}_{F E} \Delta E + \frac{1}{2} \hat{\Omega}_{F E} \Delta E \right) \right] \cdot \delta \chi$$

$$+ \text{Div} \left( \frac{1}{2} \hat{\Omega}_{E F} \Delta F + \frac{1}{2} \hat{\Omega}_{E F} \Delta F + \tilde{\Omega}_{E E} \Delta E \right) \delta \Phi$$

$$+ \int_{\partial B_0} \left[ \left[ \hat{\Omega}_{F F} \Delta F + \frac{1}{2} \hat{\Omega}_{F E} \Delta E + \frac{1}{2} \hat{\Omega}_{F E} \Delta E \right] \right] \cdot n_0 \cdot \delta \chi ds_0$$

$$+ \int_{\partial B_0} \left[ \left[ \hat{\Omega}_{E F} \Delta F + \frac{1}{2} \hat{\Omega}_{E F} \Delta F + \tilde{\Omega}_{E E} \Delta E \right] \right] \cdot n_0 \cdot \delta \Phi ds_0$$

$$+ \int_{B_0} \left[ - \text{Div} \tilde{T} \cdot \delta \chi - \text{Div} \tilde{v}_0 \delta \Phi \right] dv_0 + \int_{\partial v_0} \left[ \tilde{T} n_0 \cdot \delta \chi + \tilde{v}_0 \cdot n_0 \delta \Phi \right] ds_0.$$
Since the variations $\delta \chi$ and $\delta \Phi$ are arbitrary, we arrive at the following equations for the unknown functions $(\Delta \chi, \Delta \Phi)$

$$\text{Div}
\left(\tilde{\Omega}_{FF} \Delta F + \frac{1}{2} \tilde{\Omega}_{EF} \Delta E + \frac{1}{2} \tilde{\Omega}_{EE} \Delta E \right) = 0 \quad \text{in } B_0, \quad (55a)$$

$$\text{Div}
\left(\frac{1}{2} \tilde{\Omega}_{EF} \Delta F + \frac{1}{2} \tilde{\Omega}_{EE} \Delta E + \frac{1}{2} \tilde{\Omega}_{EE} \Delta E \right) = 0 \quad \text{in } B_0, \quad (55b)$$

$$\left[\begin{array}{c}
\tilde{\Omega}_{FF} \Delta F + \frac{1}{2} \tilde{\Omega}_{EE} \Delta E + \frac{1}{2} \tilde{\Omega}_{EE} \Delta E
\end{array}\right]_{-} - \tilde{T} \bigg|_{+} n_0 = 0 \quad \text{on } \partial B_0, \quad (55c)$$

$$\left[\begin{array}{c}
\frac{1}{2} \tilde{\Omega}_{EF} \Delta F + \frac{1}{2} \tilde{\Omega}_{EE} \Delta E + \tilde{\Omega}_{EE} \Delta E
\end{array}\right]_{-} - \tilde{v}_0 \bigg|_{+} \cdot n_0 = 0 \quad \text{on } \partial B_0, \quad (55d)$$

$$\text{Div}(\tilde{T}) = 0 \quad \text{in } B'_0, \quad (55e)$$

$$\text{Div}(\tilde{v}_0) = 0 \quad \text{in } B'_0, \quad (55f)$$

$$\tilde{T} n_0 = 0 \quad \text{on } \partial V_0, \quad (55g)$$

$$\tilde{v}_0 \cdot n_0 = 0 \quad \text{on } \partial V_0, \quad (55h)$$

describing the onset of bifurcation.

**Remark 3.3.** Note that a variation of the relation $\mathcal{D} = J_{\varepsilon_0} C^{-1} E$ from equation (8) gives

$$\Delta \mathcal{D} = \bar{v}_0, \quad (56)$$

since

$$\Delta \mathcal{D} = J_{\varepsilon_0} \left[ F^{-1} F^{-T} \Delta E - F^{-1} \Delta F \right] F^{-1} F^{-T} \mathcal{E} - F^{-1} F^{-T} [\Delta F]^T F^{-T} \mathcal{E}$$

$$+ \left[ F^{-T} \cdot \Delta F \right] F^{-1} F^{-T}. \quad (57)$$

A variation of the Maxwell stress (18) (after writing it in terms of $\mathcal{E}$ using the relation (8)) gives

$$\Delta P_m = \tilde{T}, \quad (58)$$

since

$$\Delta P_m = J_{\varepsilon_0} \left[ F^{-T} \Delta \mathcal{E} \otimes F^{-1} F^{-T} \mathcal{E} + F^{-T} \mathcal{E} \otimes F^{-1} F^{-T} \Delta \mathcal{E} \right.$$  

$$+ \left[ F^{-T} \cdot \Delta F \right] F^{-T} \mathcal{E} \otimes F^{-1} F^{-T} \mathcal{E} - F^{-T} [\Delta F]^T \mathcal{E} \otimes F^{-1} F^{-T} \mathcal{E}$$

$$- F^{-T} \mathcal{E} \otimes F^{-1} F^{-T} [\Delta F]^T \mathcal{E} - F^{-T} \mathcal{E} \otimes F^{-1} [\Delta F] F^{-1} F^{-T} \mathcal{E}$$

$$+ \frac{1}{2} [F^{-T} \mathcal{E}] \cdot [F^{-T} \mathcal{E}] [F^{-T} [\Delta F]^T F^{-T} - [F^{-T} \cdot \Delta F] F^{-T}]$$

$$+ \left[ - F^{-T} [\Delta F]^T F^{-T} \mathcal{E} \right] \cdot [F^{-T} \mathcal{E}] + [F^{-T} \mathcal{E}] \cdot F^{-T} [\Delta \mathcal{E}] \right] F^{-T} \right]. \quad (59)$$
Alternative to the statements \( \tilde{\nu}_0 = \Delta E (56) \) and \( \tilde{T} = \Delta P_m (58) \), it can be also shown that the above set of equations for the perturbations \( \Delta E \) and \( \Delta F \) can be obtained by linearising the equations of equilibrium (46a)–(47d).

4 Variational formulation based on electric polarization \( \mathbb{P} \)

Consider the body \( \mathcal{B}_0 \) in its reference configuration in a space \( \mathcal{V}_0 \). Noting that \( \tilde{\nu}_0 = -\text{Grad} \Phi \), the total potential energy of the system is given as (Liu, 2014)

\[
E[\chi, \mathbb{P}] = \int_{\mathcal{B}_0} \hat{\Omega}(\mathbb{F}, \mathbb{P}) \, dv_0 + \frac{\varepsilon_0}{2} \int_{\mathcal{V}_0} J \left| F^{-\top} \text{Grad} \Phi \right|^2 \, dv_0
\]

\[
- \int_{\mathcal{B}_0} \tilde{t}_e \cdot \chi \, dv_0 - \int_{\partial \mathcal{B}_0} \tilde{t}_e \cdot \chi \, ds_0 + \int_{\mathcal{V}_0} \phi_0 \mathbf{n}_0 \cdot \mathbb{D} \, ds_0,
\]

where \( \hat{\Omega} \) is the stored energy density per unit volume that depends on the deformation gradient \( \mathbb{F} \) and the referential electric polarization vector \( \mathbb{P} \). \( \phi_0 \) is the externally applied electric potential, \( \tilde{t}_e \) is the body force per unit volume while \( \tilde{t}_e \) is the applied traction at the boundary. Unlike the previous two formulations, the energy in the region outside \( \mathcal{B}_0 \) does not have a direct dependence on the independent variable \( \mathbb{P} \). Thus taking first variation of this functional requires a different treatment than the procedure adopted in the previous sections and is presented below.

4.1 Equilibrium: first variation

In order for a solution \( \chi \) and \( \mathbb{P} \) to be at equilibrium, the first variation of the energy functional should vanish satisfying equation (12). The variation of functional \( E \) up to the first order is given by

\[
\delta E = E[\chi + \delta \chi, \mathbb{P} + \delta \mathbb{P}] - E[\chi, \mathbb{P}] = \int_{\mathcal{B}_0} \left[ \hat{\Omega}_f \cdot \delta \mathbb{F} + \hat{\Omega}_m \cdot \delta \mathbb{P} \right] \, dv_0
\]

\[
- \int_{\mathcal{B}_0} \tilde{t}_e \cdot \delta \chi \, dv_0 - \int_{\partial \mathcal{B}_0} \tilde{t}_e \cdot \delta \chi \, ds_0 + \int_{\mathcal{V}_0} \left[ -\hat{P}_m \cdot \delta \mathbb{F} - J \varepsilon_0 \left[ C^{-1} \mathbb{E} \right] \cdot \text{Grad} \delta \Phi \right] \, dv_0 + \int_{\partial \mathcal{V}_0} \phi_0 \mathbf{n}_0 \cdot \delta \mathbb{D} \, ds_0.
\]

(61)

where \( \hat{P}_m \) is the tensor defined below

\[
\hat{P}_m = \varepsilon_0 J \left[ -\frac{1}{2} \left[ \mathbb{F}^{-\top} \mathbb{E} \right] \cdot \left[ \mathbb{F}^{-\top} \mathbb{E} \right] \mathbb{I} + \left[ \mathbb{F}^{-\top} \mathbb{E} \right] \otimes \left[ \mathbb{F}^{-\top} \mathbb{E} \right] \right] \mathbb{F}^{-\top}.
\]

Notice that outside the body, the electric polarization \( \mathbb{P} = 0 \), that gives \( \hat{P}_m = \hat{P}_m \), \( \hat{P}_m \) being the Maxwell stress tensor defined in equation (18).

We use the divergence theorem on the last term of (61) and use the condition from a variation of equation (5)_1 that Div(\( \delta \mathbb{D} \)) = 0 to get

\[
\int_{\partial \mathcal{V}_0} \phi_0 \mathbf{n}_0 \cdot \delta \mathbb{D} \, ds_0 = \int_{\mathcal{V}_0} \text{Div}(\phi \delta \mathbb{D}) \, dv_0 = \int_{\mathcal{V}_0} \text{Grad}(\phi) \cdot \delta \mathbb{D} \, dv_0 = - \int_{\mathcal{V}_0} \mathbb{E} \cdot \delta \mathbb{D} \, dv_0.
\]

(63)
Using the constitutive relation (8), an increment of electric displacement \( \mathbf{D} \) up to first order can be written as

\[
\delta \mathbf{D} = \left[ (\mathbf{F}^{-\top} \cdot \delta \mathbf{F}) \mathbf{I} - C^{-1} [\delta \mathbf{F}]^\top \mathbf{F} - \mathbf{F}^{-1} [\delta \mathbf{F}] \right] \mathbf{D} - \varepsilon_0 J C^{-1} \text{Grad} \delta \Phi + J C^{-1} \delta \mathbf{P}.
\] (64)

Upon substituting (63) and (64) in the last term of equation (61), we get

\[
\delta E = \int_{\mathcal{B}_0} \left[ \tilde{\Omega}_F \cdot \delta \mathbf{F} + \tilde{\Omega}_\mathbf{P} \cdot \delta \mathbf{P} - \tilde{\mathbf{f}}^e \cdot \delta \chi \right] dv_0 - \int_{\partial \mathcal{B}_0} \tilde{\mathbf{t}}^e \cdot \delta \chi ds_0 \\
+ \int_{\mathcal{V}_0} \left[ \tilde{\mathbf{P}}_m - \tilde{\mathbf{P}}_m \right] \cdot \delta \mathbf{F} - J C^{-1} \mathbf{I} \cdot \delta \mathbf{P} \right] dv_0,
\] (65)

where we have defined the tensor

\[
\tilde{\mathbf{P}}_m = \left[ - [\mathbf{D} \cdot \mathbf{I}] + [\mathbf{F} \mathbf{D}] \otimes [\mathbf{F}^{-\top} \mathbf{I}] + [\mathbf{F}^{-\top} \mathbf{I}] \otimes [\mathbf{F} \mathbf{D}] \right] \mathbf{F}^{-\top},
\] (66)

\[
= 2\mathbf{P}_m + J \left[ - \left[ C^{-1} \mathbf{I} \mathbf{P} \cdot \mathbf{I} \right] + [\mathbf{F}^{-\top} \mathbf{P}] \otimes [\mathbf{F}^{-\top} \mathbf{I}] + [\mathbf{F}^{-\top} \mathbf{I}] \otimes [\mathbf{F}^{-\top} \mathbf{P}] \right] \mathbf{F}^{-\top}.
\] (67)

In the region \( \mathcal{B}_0', \mathbf{P} = 0 \) which leads to \( \tilde{\mathbf{P}}_m = 2\mathbf{P}_m. \)

Upon separating the integral over \( \mathcal{V}_0 \) in (65) to two integrals on \( \mathcal{B}_0 \) and \( \mathcal{B}_0' \), we obtain

\[
\delta E = \int_{\mathcal{B}_0} \left[ \tilde{\Omega}_F + \tilde{\mathbf{P}}_m - \tilde{\mathbf{P}}_m \right] \cdot \delta \mathbf{F} - \tilde{\mathbf{f}}^e \cdot \delta \chi + \left[ \tilde{\Omega}_\mathbf{P} - J C^{-1} \mathbf{I} \right] \cdot \delta \mathbf{P} \right] dv_0 - \int_{\partial \mathcal{B}_0} \tilde{\mathbf{t}}^e \cdot \delta \chi ds_0 \\
+ \int_{\mathcal{B}_0'} \tilde{\mathbf{P}}_m \cdot \delta \mathbf{F} dv_0.
\] (68)

This is rewritten with the use of divergence theorem as

\[
\delta E = \int_{\mathcal{B}_0} \left[ - \left[ \text{Div} \left( \tilde{\Omega}_F + \tilde{\mathbf{P}}_m - \tilde{\mathbf{P}}_m \right) + \tilde{\mathbf{f}}^e \right] \cdot \delta \chi + \left[ \tilde{\Omega}_\mathbf{P} - J C^{-1} \mathbf{I} \right] \cdot \delta \mathbf{P} \right] dv_0 \\
+ \int_{\partial \mathcal{B}_0} \left[ \left[ \tilde{\Omega}_F + \tilde{\mathbf{P}}_m - \tilde{\mathbf{P}}_m \right] \cdot \mathbf{n}_0 - \tilde{\mathbf{t}}^e \right] \cdot \delta \chi ds_0 - \int_{\mathcal{V}_0} \text{Div} \tilde{\mathbf{P}}_m \cdot \delta \chi dv_0 + \int_{\partial \mathcal{V}_0} \tilde{\mathbf{P}}_m \cdot \mathbf{n}_0 \cdot \delta \chi ds_0.
\] (69)

We define the first Piola–Kirchhoff stress in the body as

\[
\mathbf{P} = \tilde{\Omega}_F + \tilde{\mathbf{P}}_m - \tilde{\mathbf{P}}_m, \quad \text{in} \quad \mathcal{B}_0,
\] (70)

while we have the same Maxwell stress \( \mathbf{P} = \mathbf{P}_m \) from equation (18) outside the body in \( \mathcal{B}_0' \) similar to what has been obtained in the other two formulations based on \( \mathbf{E} \) and \( \mathbf{D} \). Upon applying the condition (12) to the first variation calculated above, the coefficients of arbitrary variations \( \delta \chi \) and \( \delta \mathbf{P} \) should vanish for \( \delta E \) to be zero.

Vanishing of the coefficients of \( \delta \mathbf{P} \) results in the following constitutive relation between \( \mathbf{E} \) and \( \mathbf{P} \)

\[
\mathbf{E} = J^{-1} C \tilde{\Omega}_\mathbf{P}, \quad \text{in} \quad \mathcal{B}_0.
\] (71)
Upon substituting the above expression for $\mathbb{E}$ in equations (62), (67), and (70) the total first Piola–Kirchhoff stress can be rewritten in terms of the independent quantities $\mathbf{F}$ and $\mathbb{P}$ as

$$\mathbf{P} = \hat{\Omega}_{iF} + \varepsilon_0 J^{-1} \left[ - \frac{1}{2} \hat{\Omega}_{iP} \cdot [ C \hat{\Omega}_{iP} ] \mathbf{I} + \hat{\Omega}_{iP} \otimes [ C \hat{\Omega}_{iP} ] \right] F^{-\top}$$

$$+ \left[ - [ \mathbb{P} \cdot \hat{\Omega}_{iP} ] \mathbf{I} + \mathbb{P} \otimes \hat{\Omega}_{iP} + \hat{\Omega}_{iP} \otimes \mathbb{P} \right] F^{-\top}. \quad (72)$$

Vanishing of the coefficients of $\delta \chi$ results in the following equations

$$\text{Div} \mathbf{P} + \mathbf{f}^e = 0, \quad \text{in} \quad B_0, \quad (73a)$$
$$\text{Div} \mathbf{P} = 0, \quad \text{in} \quad B_0' \quad (73b)$$
$$\| \mathbf{P} \| n_0 + \mathbf{t}^e = 0, \quad \text{on} \quad \partial B_0, \quad (73c)$$
$$\mathbf{P} n_0 = 0, \quad \text{on} \quad \partial \mathcal{V}_0. \quad (73d)$$

**Remark 4.1.** We note that in this formulation based on the electric polarization vector, we have to apriori use both the Maxwell’s equations (5) to impose conditions on $\mathbb{D}$ and $\mathbb{E}$ unlike the previous two formulations in which one condition was imposed and the other was derived. Also unlike the previous two formulations, stress does not have a simple expression of being a derivative of the total energy density with respect to the deformation gradient tensor. The procedure implies the constitutive relation (71) between $\mathbb{E}$ and $\mathbb{P}$.

### 4.2 Critical point: perturbation of equilibrium equation

For the analysis of critical point $(\chi, \mathbb{P})$, the perturbations $\Delta \chi$ and $\Delta \mathbb{P}$ in the equilibrium state need to satisfy certain incremental equations and boundary conditions. These are derived from (73) and are stated below

$$\text{Div} \Delta \mathbf{P} = 0, \quad \text{in} \quad B_0, \quad (74a)$$
$$\text{Div} \Delta \mathbf{P} = 0, \quad \text{in} \quad B_0', \quad (74b)$$
$$[\Delta \mathbf{P}] n_0 = 0, \quad \text{on} \quad \partial B_0, \quad (74c)$$
$$\Delta \mathbf{P} n_0 = 0, \quad \text{on} \quad \partial \mathcal{V}_0. \quad (74d)$$

We find a perturbation in the first Piola–Kirchhoff stress using equation (72) as

$$\Delta \mathbf{P} = \hat{\Omega}_{iF} \Delta \mathbf{F} + \frac{1}{2} \left[ \hat{\Omega}_{iF} + \hat{\Omega}_{F} \right] \Delta \mathbb{P}$$

$$- \varepsilon_0 J^{-1} \left[ F^{-\top} \cdot \Delta \mathbf{F} \right] \left[ - \frac{1}{2} \hat{\Omega}_{iP} \cdot [ C \hat{\Omega}_{iP} ] \mathbf{I} + \hat{\Omega}_{iP} \otimes [ C \hat{\Omega}_{iP} ] \right] F^{-\top}$$

$$- \varepsilon_0 J^{-1} \left[ - \frac{1}{2} \hat{\Omega}_{iP} \cdot [ C \hat{\Omega}_{iP} ] \mathbf{I} + \hat{\Omega}_{iP} \otimes [ C \hat{\Omega}_{iP} ] \right] F^{-\top} \left[ \Delta \mathbf{F} \right]^{\top} F^{-\top}$$

$$+ \varepsilon_0 J^{-1} \left[ \hat{\Omega}_{iP} \cdot \left[ \Delta \mathbf{F} \hat{\Omega}_{iP} + \hat{\Omega}_{iP} \Delta \mathbb{P} + \frac{1}{2} \hat{\Omega}_{iP} \mathbb{P} \Delta \mathbf{F} + \frac{1}{2} \hat{\Omega}_{iP} \mathbf{F} \Delta \mathbf{F} \right] \right] \mathbf{I}$$
where we have defined two third order tensors $\tilde{\Omega}_F F$ and $\tilde{\Omega}_F F$ which have the following property

\[
\tilde{\Omega}_F F u \cdot U = \tilde{\Omega}_F F U \cdot u, \quad \tilde{\Omega}_F F u \cdot u = \tilde{\Omega}_F F u \cdot U,
\]  

\[
(76)
\]

$u$ being an arbitrary vector and $U$ being an arbitrary second order tensor.

Perturbation in the Maxwell stress $\Delta P_m$ in $B_0'$ in terms of $\Delta F$ and $\Delta E$ is given by Equation (59). The boundary condition (74c) connects $\Delta P$ (75) and $\Delta P_m$ (59) through the constitutive relation (71) for $E$.

Notice that contrary to the previous two cases, in this formulation based on polarization we employ a direct perturbation based approach to derive equations for critical point instead of the second variation based analysis as the latter requires lengthy and convoluted manipulations.

5 Concluding remarks

The equations of nonlinear electroelastostatics have been analyzed using three different variational formulations with respect to the field variable for the electric effect, namely, the electric field $\mathbf{E}$, the electric displacement $\mathbf{D}$, the electric polarization $\mathbf{P}$. Although the first variation based Euler-Lagrange equation has been found to coincide with that documented in the published literature, it is the second variation based critical point analysis which brings a small surprise. It is found that the second variation based partial differential equation satisfied by a perturbation near the critical point at bifurcation is not so straightforward. After careful manipulations and simplifications of the several terms arising out of repeated application of divergence theorem and identities in vector calculus, we were able to obtain the relevant equations. It is observed that there are certain terms which cannot be obtained by direct perturbation approach of the Euler–Lagrange equation.

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A Variation of some relevant functions

In order to evaluate the first and second variations, we note the following relations on account of Taylor’s expansion of relevant functions.

Upon a variation in $\chi \rightarrow \chi + \delta \chi$, we get

$$F(\chi + \delta \chi) = \text{Grad} \chi + \text{Grad}(\delta \chi) \Rightarrow \delta F = \text{Grad}(\delta \chi), \quad \delta^2 F = 0.$$  \hspace{1cm} (77)

The Cauchy–Green deformation tensor will change as

$$C(\chi + \delta \chi) = [F + \delta F]^T [F + \delta F] = F^T F + F^T \delta F + [\delta F]^T F + [\delta F]^T \delta F,$$

$$\Rightarrow \delta C = F^T \delta F + [\delta F]^T F, \quad \delta^2 C = [\delta F]^T \delta F.$$  \hspace{1cm} (78)

For the determinant $J$, we have

$$J(\chi + \delta \chi) = J + \delta J + \delta^2 J + \ldots$$

$$= \text{det}(F + \delta F)$$

$$= J + \text{cof}(F) \cdot \delta F + F \cdot \text{cof}(\delta F) + \text{det}(\delta F),$$

$$\Rightarrow \delta J = J F^{-T} \cdot \delta F, \quad \delta^2 J = F \cdot \text{cof}(\delta F).$$  \hspace{1cm} (79)

As $\delta F = \text{Grad}(\delta \chi)$, the second of the above expressions, $\delta^2 J$, is written in component form as

$$\delta^2 J = \frac{1}{2} \varepsilon_{i mn} \varepsilon_{j pq} F_{ij} [\delta \chi_{m, p}] [\delta \chi_{n, q}].$$  \hspace{1cm} (80)

Here $\varepsilon_{ijk}$ is the third order permutation tensor. We present another more useful expression for second derivative of $J$, simply obtained by differentiating the first derivative. We write

$$\delta J = \frac{\partial J}{\partial F} \cdot \delta F, \quad \Rightarrow \frac{\partial J}{\partial F} = J F^{-T}. \hspace{1cm} (81)$$

A directional derivative of the above expression gives

$$\delta J = \frac{\partial J}{\partial F} \cdot \delta F = J \left[ (F^{-T} \cdot \delta F) \left[ F^{-T} - J F^{-T} [\delta F]^T F^{-T} \right] \right].$$  \hspace{1cm} (82)

Thus, we have

$$\delta^2 J = \frac{1}{2} \left[ (F^{-T} \cdot \delta F) \left[ F^{-T} - J F^{-T} [\delta F]^T F^{-T} \right] \right].$$  \hspace{1cm} (83)

Taylor’s expansion for the inverse of determinant $J^{-1}$ is

$$J^{-1}(\chi + \delta \chi) = J_0 + J_1 + J_2 + \ldots$$

where

$$J_0 = J^{-1}, \quad J_1 = -J^{-1} F^{-T} \cdot \delta F, \quad J_2 = -J^{-2} F \cdot \text{cof}(\delta F) + J^{-1} \left[ F^{-T} \cdot \delta F \right]^2.$$  \hspace{1cm} (84)

Using the expression (84), we rewrite $J_2$ as

$$J_2 = \frac{1}{2} J \left[ (F^{-T} \cdot \delta F)^2 + F^{-T} [\delta F]^T F^{-T} \cdot \delta F \right].$$  \hspace{1cm} (85)

For the inverse tensors, let

$$[F(\chi + \delta \chi)]^{-1} = F^{-1} + D_1 F^{-1} + D_2 F^{-1} + \ldots$$  \hspace{1cm} (86)
Comparing the terms of similar order in \( \delta F \) in
\[
[F(\chi + \delta \chi)]^{-1} [F(\chi + \delta \chi)] - F^{-1} F = I - I = 0
\]
we get
\[
D_1 F^{-1} = -F^{-1}[\delta F] F^{-1}, \quad D_2 F^{-1} = F^{-1}[\delta F] F^{-1}[\delta F] F^{-1}.
\]
For the inverse of the right Cauchy–Green deformation tensor \( C^{-1} = F^{-1} F^{-\top} \), let
\[
[C(\chi + \delta \chi)]^{-1} = C^{-1} + D_1 C^{-1} + D_2 C^{-1} + \ldots
\]
Then, considering only the terms up to second order
\[
C^{-1} + D_1 C^{-1} + D_2 C^{-1} = [F^{-1} + D_1 F^{-1} + D_2 F^{-1}] [F^{-\top} + D_1 F^{-\top} + D_2 F^{-\top}],
\]
and comparing the terms of similar order in \( \delta F \), we get
\[
D_1 C^{-1} = -C^{-1}[\delta F]^{\top} F^{-\top} - F^{-1}[\delta F] C^{-1},
\]
\[
D_2 C^{-1} = C^{-1}[\delta F]^{\top} [\delta F]^{\top} F^{-\top} + F^{-1}[\delta F] C^{-1}[\delta F]^{\top} F^{-\top} + F^{-1}[\delta F] F^{-1}[\delta F] C^{-1}.
\]

### B On functions with two separate types of variations

Consider the energy density function \( \Omega(F, \mathbb{E}) \) and variations of the form \( (\delta F + \Delta F) \) and \( (\delta \mathbb{E} + \Delta \mathbb{E}) \). Then
\[
\Omega(F + \delta F + \Delta F, \mathbb{E} + \delta \mathbb{E} + \Delta \mathbb{E}) = \Omega(F, \mathbb{E}) + \Omega_{FF} [\delta F + \Delta F] + \Omega_{EE} [\delta \mathbb{E} + \Delta \mathbb{E}]
\]
\[
+ \frac{1}{2} \left[ \Omega_{FF} [\delta F + \Delta F] \right] \cdot [\delta F + \Delta F] + \frac{1}{2} \left[ \Omega_{EE} [\delta \mathbb{E} + \Delta \mathbb{E}] \right] \cdot [\delta \mathbb{E} + \Delta \mathbb{E}]
\]
\[
+ \frac{1}{2} \left[ \Omega_{EE} [\delta F + \Delta F] \right] \cdot [\delta \mathbb{E} + \Delta \mathbb{E}] + \frac{1}{2} \left[ \Omega_{EE} [\delta \mathbb{E} + \Delta \mathbb{E}] \right] \cdot [\delta F + \Delta F].
\]
Collecting only the second order terms and exploiting the major symmetries of \( \Omega_{FF} \) and \( \Omega_{EE} \), the second directional derivative \( D_2 \Omega \) is written as
\[
D_2 \Omega = \frac{1}{2} \left[ \Omega_{FF} \delta F \right] \cdot \delta F + \left[ \Omega_{FF} \Delta F \right] \cdot \delta F + \frac{1}{2} \left[ \Omega_{FF} \Delta F \right] \cdot \Delta F
\]
\[
+ \frac{1}{2} \left[ \Omega_{EE} \delta \mathbb{E} \right] \cdot \delta F + \frac{1}{2} \left[ \Omega_{EE} \Delta \mathbb{E} \right] \cdot \delta F + \frac{1}{2} \left[ \Omega_{EE} \delta \mathbb{E} \right] \cdot \Delta F + \frac{1}{2} \left[ \Omega_{EE} \Delta \mathbb{E} \right] \cdot \Delta F
\]
\[
+ \frac{1}{2} \left[ \Omega_{EE} \delta F \right] \cdot \delta \mathbb{E} + \frac{1}{2} \left[ \Omega_{EE} \Delta F \right] \cdot \delta \mathbb{E} + \frac{1}{2} \left[ \Omega_{EE} \delta F \right] \cdot \Delta \mathbb{E} + \frac{1}{2} \left[ \Omega_{EE} \Delta F \right] \cdot \Delta \mathbb{E}
\]
\[
+ \frac{1}{2} \left[ \Omega_{EE} \delta \mathbb{E} \right] \cdot \delta \mathbb{E} + \left[ \Omega_{EE} \Delta \mathbb{E} \right] \cdot \delta \mathbb{E} + \frac{1}{2} \left[ \Omega_{EE} \Delta \mathbb{E} \right] \cdot \Delta \mathbb{E}.
\]
Now variations of the form \( (\delta F + \Delta F) \) and \( (\delta \mathbb{E} + \Delta \mathbb{E}) \) in equation (39) gives for the integral over the region \( B'_0 \)
\[
- \frac{1}{2} \zeta_0 \int_{B'_0} \left[ 1 + F^{-\top} \cdot [\delta F + \Delta F] + \frac{1}{2} [F^{-\top} \cdot [\delta F + \Delta F]] \right] [F^{-\top} \cdot [\delta F + \Delta F]]
\]
Noting that

\[ \left( \begin{array}{c} \delta F + \Delta F \\ \Delta E + \Delta \| \end{array} \right) \]

and collecting only the second order terms upon multiplication of the relevant terms, we get

\[ \left( \begin{array}{c} \delta F + \Delta F \\ \Delta E + \Delta \| \end{array} \right) \]

Variations of the form

\[ \left( \begin{array}{c} \delta F + \Delta F \\ \Delta E + \Delta \| \end{array} \right) \]

and collecting only the terms up to second order after multiplication, we get

\[ \left( \begin{array}{c} \delta F + \Delta F \\ \Delta E + \Delta \| \end{array} \right) \]

(100)

\[ \left( \begin{array}{c} \delta F + \Delta F \\ \Delta E + \Delta \| \end{array} \right) \]

\[ \left( \begin{array}{c} \delta F + \Delta F \\ \Delta E + \Delta \| \end{array} \right) \]

\[ \left( \begin{array}{c} \delta F + \Delta F \\ \Delta E + \Delta \| \end{array} \right) \]

(101)

Variations of the form \((\delta F + \Delta F)\) and \((\delta \| + \Delta \|)\) in equation (10) gives for the integral over the region \(B'\)

\[ \frac{1}{2\varepsilon_0} \int_{B'0} J^{-1} \left[ 1 - \mathbf{F}^{-\top} \cdot \left[ \delta \mathbf{F} + \Delta \mathbf{F} \right] + \frac{1}{2} \left[ \mathbf{F}^{-\top} \cdot \left[ \delta \mathbf{F} + \Delta \mathbf{F} \right] \right] \right] \left[ \mathbf{F}^{-\top} \cdot \left[ \delta \mathbf{F} + \Delta \mathbf{F} \right] \right] \]

\[ \left[ \mathbf{F} + \delta \mathbf{F} + \Delta \mathbf{F} \right] \left[ \| \mathbf{D} + \delta \| + \Delta \| \right] \cdot \left[ \mathbf{F} + \delta \mathbf{F} + \Delta \mathbf{F} \right] \left[ \| \mathbf{D} + \delta \| + \Delta \| \right] \]

(102)

Upon collecting only the terms up to second order after multiplication, we get

\[ \frac{1}{2\varepsilon_0} \int_{B'0} \left[ \frac{1}{2} J^{-1} \left[ \mathbf{F} \| \mathbf{D} \right] \cdot \left[ \frac{1}{2} \mathbf{F}^{-\top} \cdot \left[ \delta \mathbf{F} + \Delta \mathbf{F} \right] \right] \right] \left[ \mathbf{F}^{-\top} \cdot \left[ \delta \mathbf{F} + \Delta \mathbf{F} \right] \right] \]
\[ + \mathbf{F}^\top [\delta \mathbf{F} + \Delta \mathbf{F}] \mathbf{F}^\top \cdot [\delta \mathbf{F} + \Delta \mathbf{F}] \]

\[- 2J^{-1} \mathbf{F}^\top \cdot [\delta \mathbf{F} + \Delta \mathbf{F}] \left[[\delta \mathbf{F} + \Delta \mathbf{F}] \mathbf{I} \right] \cdot \left[\mathbf{F} \mathbf{I} \right] + \left[\mathbf{F} \left[\delta \mathbf{I} + \Delta \mathbf{I} \right] \right] \cdot \left[\mathbf{F} \mathbf{I} \right] \]

\[+ 2J^{-1} \left[[\delta \mathbf{F} + \Delta \mathbf{F}] \left[\delta \mathbf{I} + \Delta \mathbf{I} \right] \right] \cdot \left[\mathbf{F} \mathbf{I} \right] + 2J^{-1} \left[[\delta \mathbf{F} + \Delta \mathbf{F}] \mathbf{I} \right] \cdot \left[\mathbf{F} \left[\delta \mathbf{I} + \Delta \mathbf{I} \right] \right] \]

\[+ J^{-1} \left[[\delta \mathbf{F} + \Delta \mathbf{F}] \mathbf{I} \right] \cdot \left[[\delta \mathbf{F} + \Delta \mathbf{F}] \mathbf{I} \right] + J^{-1} \left[\mathbf{F} \left[\delta \mathbf{I} + \Delta \mathbf{I} \right] \right] \cdot \left[\mathbf{F} \left[\delta \mathbf{I} + \Delta \mathbf{I} \right] \right] \right] dv_0. \quad (103) \]

C Auxiliary details for calculations in §2.2

Using the triple product identity involving the curl operator (16), we rewrite the equation \(\delta^2 E = 0\) (29) as

\[\int_{B_0} \left[ \text{Div} \left( [\Omega_{FF} \Delta \mathbf{F} + \frac{1}{2} \left[\Omega_{FI} + \tilde{\Omega}_{FI} \right] \Delta \mathbf{I} \right] \cdot \delta \chi \right) \]

\[- \left[ \text{Div} \left( \Omega_{FF} \Delta \mathbf{F} + \frac{1}{2} \left[\Omega_{FI} + \tilde{\Omega}_{FI} \right] \Delta \mathbf{I} \right) \right] \cdot \delta \chi \]

\[+ \left[ \Omega_{II} \Delta \mathbf{I} + \frac{1}{2} \left[\Omega_{IF} + \tilde{\Omega}_{IF} \right] \Delta \mathbf{F} \right] \cdot \delta \mathbf{I} \right] dv_0 \]

\[+ \int_{B_0} \left[ \text{Div} \left( \mathbf{T}^\top \delta \chi \right) - \left[ \text{Div}(\mathbf{T}) \right] \cdot \delta \chi + \text{Div}(\delta \mathbf{A} \wedge \mathbf{v}_0) + \text{Curl}(\mathbf{v}_0) \cdot \delta \mathbf{A} \right] dv_0 = 0. \quad (104) \]

By an application of the divergence theorem to (104), we get

\[\int_{B_0} \left[ -\text{Div} \left( \Omega_{FF} \Delta \mathbf{F} + \frac{1}{2} \left[\Omega_{FI} + \tilde{\Omega}_{FI} \right] \Delta \mathbf{I} \right) \right] \cdot \delta \chi \]

\[+ \left[ \Omega_{II} \Delta \mathbf{I} + \frac{1}{2} \left[\Omega_{IF} + \tilde{\Omega}_{IF} \right] \Delta \mathbf{F} \right] \cdot \delta \mathbf{I} \right] dv_0 \]

\[+ \int_{\partial B_0^-} \left[ \Omega_{FF} \Delta \mathbf{F} + \frac{1}{2} \left[\Omega_{FI} + \tilde{\Omega}_{FI} \right] \Delta \mathbf{I} \right] \mathbf{n}_0 \cdot \delta \chi ds_0 \]

\[+ \int_{B_0^+} \left[ -\text{Div}(\mathbf{T}) \cdot \delta \chi + \text{Div}(\delta \mathbf{A} \wedge \mathbf{v}_0) + \text{Curl}(\mathbf{v}_0) \cdot \delta \mathbf{A} \right] dv_0 \]

\[+ \int_{\partial V_0^-} \mathbf{T} \mathbf{n}_0 \cdot \delta \chi dv_0 - \int_{\partial V_0^+} \mathbf{T} \mathbf{n}_0 \cdot \delta \chi dv_0 = 0, \quad (105) \]

which can be simplified further by the identity (16) so that

\[\int_{B_0} \left[ -\text{Div} \left( \Omega_{FF} \Delta \mathbf{F} + \frac{1}{2} \left[\Omega_{FI} + \tilde{\Omega}_{FI} \right] \Delta \mathbf{I} \right) \right] \cdot \delta \chi \]

\[+ \text{Div} \left( \delta \mathbf{A} \wedge \left[ \Omega_{II} \Delta \mathbf{I} + \frac{1}{2} \left[\Omega_{IF} + \tilde{\Omega}_{IF} \right] \Delta \mathbf{F} \right] \right)] \]
Using the divergence theorem again

\[
\int_{\partial B_0} \left[ - \text{Div} \left( \Omega_{FF} \Delta F + \frac{1}{2} \left[ \Omega_{FD} + \widetilde{\Omega}_{FD} \right] \Delta \mathbb{D} \right) \right] \cdot n_0 \cdot \delta \chi ds_0
+ \int_{\partial B_0} \left[ \Omega_{DD} \Delta \mathbb{D} + \frac{1}{2} \left[ \Omega_{DF} + \widetilde{\Omega}_{DF} \right] \Delta F \right] \cdot \delta A ds_0
+ \int_{\partial V_0} \Omega_{DD} \Delta \mathbb{D} \cdot n_0 \cdot \delta \chi ds_0
+ \int_{\partial V_0} \frac{1}{2} \left[ \Omega_{DF} + \widetilde{\Omega}_{DF} \right] \Delta F \cdot n_0 \cdot \delta A ds_0
= 0.
\]

(107)

Since the variations \( \delta \chi \) and \( \delta A \) are arbitrary, we arrive at the equations (35).

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