A New Kumaraswamy Generalized Family of Distributions with Properties, Applications, and Bivariate Extension

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Received: 28 September 2020; Accepted: 2 November 2020; Published: 7 November 2020

Abstract: For bounded unit interval, we propose a new Kumaraswamy generalized (G) family of distributions through a new generator which could be an alternate to the Kumaraswamy-G family proposed earlier by Cordeiro and de Castro in 2011. This new generator can also be used to develop alternate G-classes such as beta-G, McDonald-G, Topp-Leone-G, Marshall-Olkin-G, and Transmuted-G for bounded unit interval. Some mathematical properties of this new family are obtained and maximum likelihood method is used for the estimation of G-family parameters. We investigate the properties of one special model called the new Kumaraswamy-Weibull (NKwW) distribution. Parameters of NKwW model are estimated by using maximum likelihood method, and the performance of these estimators are assessed through simulation study. Two real life data sets are analyzed to illustrate the importance and flexibility of the proposed model. In fact, this model outperforms some generalized Weibull models such as the Kumaraswamy-Weibull, McDonald-Weibull, beta-Weibull, exponentiated-generalized Weibull, gamma-Weibull, odd log-logistic-Weibull, Marshall–Olkin–Weibull, transmuted-Weibull and exponentiated-Weibull distributions when applied to these data sets. The bivariate extension of the family is also proposed, and the estimation of parameters is dealt. The usefulness of the bivariate NKwW model is illustrated empirically by means of a real-life data set.

Keywords: bivariate family; Kumaraswamy-G family; Marshall and Olkin shock model; maximum likelihood method; parameter induction; T-X family; Weibull distribution

1. Introduction

The twenty-first century begun with establishing and extending new tools for modern statistics. In terms of distribution theory, one of the important developments is to define new useful models and then these are tested on real-life data sets available from simple to complex phenomenons. The modern distribution theory has also motivated statisticians and practitioners to propose new generalized (G) families and to investigate their special models, which can effectively be used in different fields, in particular, medicine, reliability engineering, agriculture, survival analysis, demography, actuarial study and others. The G-families proposed by Azzalini [1] (skew-Normal-G...
(SN-G)), Marshall and Olkin [2] (Marshall-Olkin-G (MO-G)), Gupta et al. [3] (exponentiated-G (exp-G) [Lehmann alternative 1 (LA1) and Lehmann alternative 2 (LA2)]), Eugene et al. [4] (beta-G), Gleaton and Lynch [5] (odd log-logistic-G (OLL-G)), Shaw and Buckley [6] (transmuted-G), Zografos and Balakrishnan [7] (ZBgamma-G), Cordeiro and de-Castro [8] (Kumaraswamy-G (Kw-G)), Alexander et al. [9] (McDonald-G (Mc-G)), Risti´c and Balakrishnan [10] (RBgamma-G), Cordeiro et al. [11] (exponentiated-generalized-G (EG-G)), Bourguignon et al. [12] (odd Weibull-G (OW-G)), Tahir et al. [13] (odd generalized-exponential (OGE-G)), Tahir et al. [14] (logistic-X) and Rezaei et al. [15] (Topp-Leone-G (TL-G)) have received increased attention in recent statistical literature. For more G-families, the reader is referred to Tahir and Nadarajah [16], and Tahir and Cordeiro [17].

Kumaraswamy [18] pioneered a two-parameter model for bounded unit interval \((0, 1)\) which we denote here by using random variable \(T \sim Kw(a, b)\). The cumulative distribution function (cdf) and probability density function (pdf) of \(T\) are

\[
R(t) = 1 - (1 - t^a)^b, \quad t \in (0, 1)
\]

and

\[
r(t) = ab t^{a-1} (1 - t^a)^{b-1},
\]

respectively, where \(a > 0\) and \(b > 0\) are shape parameters.

Cordeiro and de-Castro [8] defined the cdf and pdf of the Kw-G family by

\[
F_{KwG}(x; a, b, \xi) = 1 - [1 - G(x; \xi)^a]^b, \quad x \in (0, 1)
\]

and

\[
f_{KwG}(x; a, b, \xi) = ab g(x; \xi) G(x; \xi)^{a-1} [1 - G(x; \xi)^a]^{b-1},
\]

where \(a > 0\) and \(b > 0\) are two additional shape parameters, and \(\xi\) is the vector of baseline parameters.

The Kw-G family has received wide-spread recognition and more than sixty special models have been studied so far, namely: exponential, exponentiated-exponential, Weibull, exponentiated-Weibull, modified Weibull (Lai et al. [19]), flexible-Weibull (Bebbington et al. [20]), generalized power Weibull, log-logistic, half-logistic, Lomax, Burr, Kumaraswamy, generalized gamma, exponentiated-gamma, generalized Rayleigh, Pareto, generalized Pareto, Pareto-IV, Gumbel, exponentiated-Gumbel (type-II), Fréchet, Laplace, Gompertz, Gompertz-Makeham, normal, inverse Gaussian, skew-normal, generalized half-normal, Birnbaum-Saunders, skew-t, Nadarajah-Haghighi, linear failure rate, quadratic hazard rate, Lindley, quasi-Lindley, Lindley-Poisson, Sushila, half-Cauchy, inverse exponential, inverse Rayleigh, inverse Weibull, inverse Weibull-Poisson, inverse flexible-Weibull, modified inverse Weibull (using LA2), Fisher-Snedecor, compound-Rayleigh, exponential-Rayleigh, exponential-Weibull (compounded), exponentiated-Chen, generalized Kappa, generalized extreme-value, Weibull-geometric (WG), complementary WG, Marshall-Olkin exponential, Marshall-Olkin Fréchet (MOFr), Marshall-Olkin Lindley, transmuted Weibull, transmuted Pareto, transmuted modified-Weibull (Sarhan-Zaindin), transmuted exponentiated modified Weibull, transmuted exponentiated additive Weibull and transmuted MOFr.

Some other special models of the Kw-G family were also reported in the literature but these suffer non-identifiability issue (when two parameters appear, for example, in a product and it is impossible to determine their individual effects). These special models are: power function, Burr III, generalized linear failure rate, exponentiated-Pareto, exponentiated Burr and exponentiated-Lomax.

**Note 1.** The citations and the references of the authors of special models of the Kw-G family [8] are avoided in this section and in references to save some space.

Alzaatreh et al. [21] proposed a general method for constructing G-families by using the transformed-transformer (T-X) approach. Let \(r(t)\) be the pdf and \(R(t)\) be the cdf of a rv \(T \in [a, b]\) for \(-\infty < a < b < \infty\) and let \(W[G(x)]\) be a function of the cdf \(G(x)\) or survival function (sf)
\( \bar{G}(x) = 1 - G(x) \) of any baseline rv \((W(\cdot))\) is known as generator\) such that \(W[G(x)]\) satisfies three conditions:

(i) \( W[G(x)] \in [a, b], \)

(ii) \( W[G(x)] \) is differentiable and monotonically non-decreasing, and

(iii) \( \lim_{x \to -\infty} W[G(x)] = a \) and \( \lim_{x \to \infty} W[G(x)] = b. \)

The cdf of the \( T-X \) family is

\[
F_{TX}(x) = \int_{a}^{W[G(x)]} r(t) \, dt = R \left( W \left[ G(x) \right] \right),
\]  

(5)

where \( W[G(x)] \) satisfies the conditions (i)–(iii).

The pdf corresponding to Equation (5) is

\[
f_{TX}(x) = r \left( W \left[ G(x) \right] \right) \frac{d}{dx} W \left[ G(x) \right].
\]  

(6)

The main motivation for proposing new G-family are:

(i) Constructing new and novel G-families as a function of a cdf, \( W[G(x)] \), is a difficult task in these days. A few pioneer G-families were developed in the literature considering \( W[G(x)] \) viz. exponentiated-G with power parameter \( a > 0 \) (LA1 and LA2) (Gupta et al. \[3\]) \([G(x)^a \text{ and } 1 - \bar{G}(x)^a] \), beta-G (Eugene et al. \[4\]) \([G(x)], ZBgamma-G (Zografos and Balakrishnan \[7\]) \([- \log \bar{G}(x)] \), odd log-odd logistic-G (Gleaton and Lynch \[5\]) \([G(x)/\bar{G}(x)] \), RBgamma-G (Ristic and Balakrishnan \[10\]) \([- \log G(x)], \log-odd \logistic-G \) (Torabi and Montazeri \[22\]) \([\log \{ G(x)/\bar{G}(x) \}], \text{Gumbel-X (Al-Aqtash et al. \[23\])} \[\log \{ - \log \bar{G}(x) \}], \text{Weibull-X (T-X approach) and Weibull-X (Ahmad et al. \[24\])} \) \([\{ - \log G(x) \}/G(x)] \) are the pioneer works. Other G-families either non-composite (alone based on well-established parent model) or composite (mixture of two G-families) and compounded G-families are the extensions or modifications of the above described pioneer G-families. For example, the generator \( G(x) \), where \( T \in (0, 1) \) was pioneered by (Eugene et al. \[4\]) for defining the beta-G family, and later this generator was adopted by (Cordeiro and de-Castro \[8\]; Alexander et al. \[9\]; Rezaei et al. \[15\]) for defining the Kw-G, Mc-G and TL-G families, respectively. Similarly, the odd generator \( G(x)/\bar{G}(x) \) (where \( T \in (0, \infty) \)) was suggested by (Gleaton and Lynch, \[5\]) for proposing the odd log-logistic-G family, and it was adopted by (Bourguignon et al. \[12\]; Torabi and Montazeri \[25\]; Tahir et al. \[13\]; Silva et al. \[26\]; Cordeiro et al. \[27\]; Alizadeh et al. \[28\]; Cordeiro et al. \[29\]; Hassan et al. \[30\]; Hassan and Nassr \[31\]; Maiti and Pramanik \[32\]; El-Morshedy and Eliwa \[33\]; Alizadeh et al. \[34\]; El-Morshedy et al. \[35\]; Eliwa et al. \[36\]) for defining the odd Weibull-G, odd gamma-G, odd generalized-exponential-G, odd Lindley-G, odd Burr-G, odd power-Cauchy-G, odd half-Cauchy, odd additive Weibull-G, odd power-Lindley-G, odd Xgamma-G, odd flexible Weibull-H, odd log-logistic Lindley-G, odd Chen generator and exponentiated odd Chen-G, respectively, among others.

(ii) The proposed extension of the Kumaraswamy-G model is based on a new generator \( W[G(x)] = 1 - \bar{G}(x)^{G(x)} \) for \( T \in (0, 1) \) instead of the only existing generator \( G(x) \) for which the beta-G, Kw-G, Mc-G and TL-G classes were developed so far.

(iii) The proposed generator \( 1 - \bar{G}(x)^{G(x)} \) seems little complicated in comparison to earlier well-established generator for the unit interval but it has the ability to produce better estimates and goodness-of-fit (GoF) tests results that can make it distinguishable and attractive for applied researchers (as evident from the results in Sections 5 and 7).
For most of the families and models, if the cdf is in closed form, then the quantile function (qf) can be straightforward to obtain. In some families and models, where the qf is based on some special functions such as beta, gamma, and others, then the qfs can only be determined by using power series. In our case, the cdf of the family is in closed form but the qf can be obtained only numerically.

Note 2. A complete and independent investigation of the properties and application of our proposed generator \( F(x) = 1 - \bar{G}(x)^{G(x)} \) as a new family such as transmuted-G (Tr-G) and exponentiated-generalized-G (EG-G) will appear in another outlet very soon. It is noted here that the two G-families (Tr-G and EG-G) have not been developed from any existing parent model similar to our proposed one.

The paper is unfolded as follows. In Section 2, we define the new Kumaraswamy generalized (NKw-G) family. In Section 3, some of its mathematical properties are determined from a useful linear representation of the family density. We investigate the asymptotics and shapes of the density and hazard rate, ordinary and incomplete moments, generating function, mean deviations and estimation of the model parameters. Several properties of a special model viz. new Kumaraswamy Weibull (NKwW) distribution are discussed in Section 4. A simulation study is also conducted to assess the performance of maximum likelihood estimators of the newly proposed model in this section. In Section 5, the usefulness of new model is illustrated by means of two real-life data sets. In Section 6, we define the Bivariate New Kumaraswamy G-family of distributions. In Section 7, the usefulness of the new bivariate model is illustrated by means of a real-life data set. In fact, we prove empirically that our proposed model outperforms some well-known univariate and bivariate distributions. Finally, Section 8 offers some concluding remarks.

The important feature of our article is that the proposed model from this new generalized family, NKwW, is better in performance as compared to some well-known (or well-established) generalized Weibull models selected from the statistical literature. It can be noted from Section 5 that the Kolmogrov-Smirnov GoF statistic yields minimum GoF values along with high p-values of this statistic. Furthermore, it can also been observed from Section 5 that the GoF values of some other well-established statistics such as Akaike information Criterion, Bayesian Information Criterion, Hannan-Quinn Information Criterion, Anderson-Darling and Cramér-von Mises for our propose model are smallest as compared to some important generalized Weibull models. This fact reveals that the performance and flexibility of our proposed model is better in comparison to all other competitive models, when applied to these selected real-life data sets. The same fact is valid for our proposed bivariate model (see, Section 7).

2. The NKw-G Family

For \( W[G(x)] = G(x) \) and \( T \in (0, 1) \) just only the beta-G, Kw-G, Mc-G and TL-G families were reported so far. No other generators for \( T \in (0, 1) \) were published until now. Therefore, our main objective is to introduce a new family of distributions for \( T \in (0, 1) \) called the NKw-G family and to study its main structural properties.

Let \( r(t) \) be the Kumaraswamy density. By inserting Equation (2) in Equation (5) and letting \( W[G(x)] = 1 - G(x)^{G(x)} \), the cdf of the NKw-G family is given by

\[
F(x) = F(x; a, b, \xi) = \int_0^{1 - \bar{G}(x; \xi)^{G(x; \xi)}} t^{a-1} (1 - t)^{b-1} dt = 1 - \left\{ 1 - [1 - \bar{G}(x; \xi)^{G(x; \xi)}]^{a/b} \right\}^b, \tag{7}
\]

where \( a > 0 \) and \( b > 0 \) are two shape parameters of the Kw distribution and \( \xi \) is the vector of the baseline parameters.
The pdf corresponding to Equation (7) becomes

\[
f(x) = f(x; a, b, \xi) = a \frac{b}{G(x; \xi)} [\bar{G}(x; \xi)]^{G(x)} \left[ 1 - G(x; \xi)^{G(x; \xi)} \right]^{a-1} \times \left\{ 1 - \left[ 1 - \bar{G}(x; \xi)^{G(x; \xi)} \right]^a \right\}^{b-1} \left[ \frac{G(x; \xi)}{\bar{G}(x; \xi)} - \log \bar{G}(x; \xi) \right]. \tag{8}
\]

Henceforth, a rv \(X\) with the density (8) is denoted by \(X \sim \text{NKw-G}(a, b, \xi)\). The survival function (sf) \(S(x)\) and hazard rate function (hrf) \(h(x)\) of \(X\) are, respectively,

\[
S(x) = \left\{ 1 - \left[ 1 - \bar{G}(x; \xi)^{G(x; \xi)} \right]^a \right\}^b
\]

and

\[
h(x) = \frac{a b g(x; \xi) [\bar{G}(x; \xi)]^{G(x)} \left[ 1 - \bar{G}(x; \xi)^{G(x; \xi)} \right]^{a-1} \left[ \frac{G(x; \xi)}{\bar{G}(x; \xi)} - \log \bar{G}(x; \xi) \right]}{1 - \left[ 1 - \bar{G}(x; \xi)^{G(x; \xi)} \right]^a}. \tag{9}
\]

3. Properties of the NKw-G Family

In this section, we obtain some mathematical properties of the NKw-G family.

3.1. Quantile Function

The most common and simplest method for generating random variates is based on the inverse cdf. For an arbitrary cdf, the quantile function (qf) is defined as \(Q(u) = F^{-1}(u) = \min\{x; F(x) \geq u\}\). The qf of the NKw-G family can be determined by inverting (7) and then solving the two non-linear equations numerically. We can use the following procedure:

(i) Set \(z = z(u) = 1 - [1 - (1 - u)^{1/b}]^{1/a}\);
(ii) Find \(w = w(u)\) numerically in \(w \log(1 - w) = \log(z)\) using any Newton-Raphson algorithm;
(iii) Solving numerically for \(x\) in \(\bar{G}(x; \xi) = w\) yields the qf \(x = Q(u)\) of \(X\).

3.2. Asymptotics

The following asymptotics for the density, distribution function and hrf of \(X\) hold.

**Corollary 1.** The asymptotics of Equations (7)–(9) when \(x \to 0\) or \((G(x) \to 0)\) are

\[
F(x) \sim -b [G(x; \xi)]^{-a},
\]

\[
f(x) \sim a b g(x; \xi) [G(x; \xi)]^{-(a+1)},
\]

\[
h(x) \sim a b g(x; \xi) [G(x; \xi)]^{-(a+1)}.
\]

**Corollary 2.** The asymptotics of Equations (7)–(9) when \(x \to \infty\) or \((G(x; \xi) \to 1)\) are

\[
1 - F(x) \sim a \log G(x; \xi)^{-b},
\]

\[
f(x) \sim \frac{a b g(x; \xi)}{G(x; \xi)} [\log G(x; \xi)]^{-(b+1)},
\]

\[
h(x) \sim \frac{b g(x; \xi)}{G(x; \xi) \log G(x; \xi)}.
\]
3.3. Analytic Shapes of the Density and Hazard Rate Function

The shapes of the density and hrf of X can be described analytically. The critical points of the density of X are the roots of the equation:

\[
\frac{g'(x; \xi)}{g(x; \xi)} - \frac{G(x; \xi) g(x; \xi)}{G(x; \xi)} + \frac{g(x; \xi) \{ G(x; \xi) - 2 \}}{G(x; \xi) - 1} \left\{ G(x; \xi) + \{ G(x; \xi) - 1 \} \log G(x; \xi) \right\} \\
+ g(x; \xi) \log G(x; \xi) - \frac{(a - 1) g(x; \xi) M \left[ G(x; \xi) + \{ G(x; \xi) - 1 \} \log \bar{G}(x; \xi) \right]}{(M - 1) G(x; \xi)} \\
+ a(b - 1) g(x; \xi) M (1 - M)^{a-1} \left[ \frac{1}{G(x; \xi)} + \log \bar{G}(x; \xi) + 1 \right] = 0,
\]

where \( M = M(x; \xi) = [1 - G(x; \xi)]^{G(x; \xi)} \).

The critical points of the hrf of X are obtained from the equation:

\[
\frac{g'(x; \xi)}{g(x; \xi)} + \frac{1}{(M - 1) [G(x; \xi) - 1] \left[ (1 - M)^{a} - 1 \right] \left\{ G(x; \xi) + \{ G(x; \xi) - 1 \} \log \bar{G}(x; \xi) \right\}} \\
\times g(x; \xi) \left[ 1 - (1 - M)^{a} \right] \left[ G(x; \xi) + 1 \right] \left\{ - \log^{2} \bar{G}(x; \xi) + G(x; \xi) \left[ \log \bar{G}(x; \xi) + 1 \right]^2 + 2 \right\} \\
+ M \left\{ 2 - 2(1 - M)^{a} - a \log^{2} \bar{G}(x; \xi) - a G(x; \xi)^2 \left[ \log \bar{G}(x; \xi) + 1 \right]^2 \right\} \\
+ G(x; \xi) \left[ (1 - M)^{a} + 2a \log G(x; \xi) \left\{ \log G(x; \xi) + 1 \right\} - 1 \right] \right\} = 0.
\]

3.4. Linear Representation of the NKW-G Density

Here, we derive useful expansions for Equations (7) and (8) based on the concept of exponentiated distributions. For an arbitrary baseline cdf \( G(x; \xi) \), a rv is said to have the exponentiated-G (exp-G) distribution with power parameter \( a > 0 \) if its cdf and pdf are

\[
H_{a}(x; \xi) = G(x; \xi)^{a}, \quad h_{a}(x; \xi) = a g(x; \xi) G(x; \xi)^{a-1}, \quad \text{(10)}
\]

respectively.

The properties of the exponentiated distributions were studied by many authors in recent years. We consider the generalized binomial expansion

\[
(1 - z)^{b} = \sum_{k=0}^{\infty} (-1)^{k} \binom{b}{k} z^{k}, \quad \text{(11)}
\]

which holds for any real non-integer \( b \) and \( |z| < 1 \). Using (11) twice in the following expression \( T(x; \xi) = \left\{ 1 - \left[ 1 - P(x; \xi) \right]^{a} \right\}^{b} \) in Equation (7), where \( P(x; \xi) = \bar{G}(x; \xi)^{G(x; \xi)} \), we can write \( T(x; \xi) = \sum_{j=0}^{\infty} w_{j+1} P(x; \xi)^{j+1} \), where \( w_{j+1} = \sum_{m=0}^{\infty} (-1)^{j+m+1} \binom{b}{m} \binom{m+1}{j+1} \). Then, we can expand Equation (7) as

\[
F(x) = 1 - \sum_{j=0}^{\infty} w_{j+1} \left[ 1 - G(x; \xi) \right]^{(j+1)G(x; \xi)}.
\]

\[
F(x) = 1 - \sum_{j=0}^{\infty} w_{j+1} \left[ 1 - G(x; \xi) \right]^{(j+1)G(x; \xi)}.
\]
Furthermore, using Mathematica, the power series holds

$$[1 - G(x; \xi)]^{(j+1)}G(x; \xi) = 1 + \sum_{i=2}^{\infty} q_i (j+1) G(x; \xi)^i,$$

where $q_2(j+1) = -(j+1)$, $q_3(j+1) = -(j+1)/2$, $q_4(j+1) = (j+1)(3j+1)/6$, $q_5(j+1) = (j+1)(2j+1)/4$, etc.

By inserting Equation (13) in Equation (12) and noting that $\sum_{j=0}^{\infty} w_j = 1$, we obtain

$$F(x) = \sum_{i=2}^{\infty} t_i G(x; \xi)^i,$$

where

$$t_i = -\sum_{j=0}^{\infty} w_{j+1} q_i (j+1) \text{ for } i \geq 2.$$

By differentiating $F(x)$, the NKwG density has the form

$$f(x) = \sum_{i=1}^{\infty} t_{i+1} h_{i+1}(x; \xi),$$

where $h_{i+1}(x; \xi)$ is the exp-G density with power parameter $(i+1)$. Equation (16) reveals that the NKw-G density function is a linear combination of exp-G densities. Then, some of its mathematical properties can be determined directly from those of the exp-G distribution.

### 3.5. Mathematical Properties

The formulae derived throughout the paper can be easily handled in most symbolic computation platforms such as Maple, Mathematica and Matlab which have the ability to deal with analytic expressions of formidable size and complexity. Henceforth, let $Y_{i+1}$ be a rv with the exp-G distribution with power parameter $(i+1)$. We obtain some mathematical quantities of the NKw-G family from (16) and those properties of the exp-G distribution. The exp-G properties are known for at least fifty distributions; see those distributions listed in Tahir and Nadarajah [16].

First, the $n$th ordinary moment of $X$, say $E(X^n)$, can be expressed from (16) as

$$E(X^n) = \sum_{i=1}^{\infty} t_{i+1} E(Y_{i+1}^n) = \sum_{i=1}^{\infty} (i+1) t_{i+1} \tau_{n,i},$$

where $\tau_{n,i} = \int_{-\infty}^{\infty} x^n G(x; \xi)^i g(x; \xi) dx = \int_0^1 Q_G(u; \xi)^n u^i du$, and $Q_G(u; \xi)$ is the qf of the baseline G.

The quantities $E(Y_{i+1}^n)$ are known for many G distributions as can been seen in those papers cited in Tahir and Nadarajah (2015).

Moments are important in any statistical analysis. Some of the most important features of a distribution can be studied through moments. For instance, the first four moments can be used to describe some characteristics of a distribution. Clearly, the central moments and cumulants of X can be determined from (17) using well-known relationships.

Second, the $n$th lower incomplete moment of $X$, say $m_n(y) = \int_{-\infty}^{y} x^n f(x) dx$, is

$$m_n(y) = \sum_{i=1}^{\infty} t_{i+1} \int_{-\infty}^{y} x^n h_{i+1}(x) dx = \sum_{i=1}^{\infty} (i+1) t_{i+1} \int_0^{G(y; \xi)} Q_G(u; \xi)^n u^i du.$$

The last two integrals can be evaluated numerically for most G distributions.
The first incomplete moment \( m_1(y) \) is used to construct the Bonferroni and Lorenz curves (popular measures in economics, reliability, demography, insurance, and medicine) and to determine the totality of deviations from the mean and median of \( X \) (important statistics in statistical applications).

Third, for a given probability \( \pi \), the Bonferroni and Lorenz curves (popular measures in economics, reliability, demography, insurance, and medicine) of \( X \) are given by \( B(\pi) = m_1(q)/\left(\pi \mu_1^i\right) \) and \( L(\pi) = m_1(q)/\mu_1^i \), respectively, where \( q = Q(\pi; \xi) \) can be found from the procedure described at the last paragraph of Section 2.

Fourth, the total deviations from the mean and median are \( \delta_1 = 2\mu_1^i F(\mu_1^i) - 2m_1(\mu_1^i) \) and \( \delta_2 = \mu_1^i - 2m_1(M) \), where \( F(\mu_1^i) \) comes from (7).

Fifth, the moment generating function (mgf) \( M(t) = E(e^{tX}) \) of \( X \) follows from (16) as

\[
M(t) = \sum_{i=1}^{\infty} t_{i+1} M_{i+1}(t) = \sum_{i=0}^{\infty} (i+1) t_{i+1} \rho_i(t),
\]

where \( M_{i+1}(t) \) is the mgf of \( Y_{i+1} \) and \( \rho_i(t) = \int_{0}^{1} \exp[t Q_G(u; \xi)] \, du \). Hence, we can obtain the mgfs of many special NKw-G distributions directly from exp-G generating function and Equation (19).

3.6. Estimation

Here, we consider the estimation of the unknown parameters of the NKw-G family by the maximum likelihood method. The MLEs enjoy desirable properties and deliver simple approximations that work well in finite samples when constructing confidence intervals. The normal approximation for the MLEs can be handled either analytically or numerically.

The log-likelihood function \( \ell(\theta) \) for the vector of parameters \( \theta = (a, b, \xi)^T \) from \( n \) observations \( x_1, \cdots, x_n \) has the form

\[
\ell = \ell(\theta) = n \log(ab) + \sum_{i=1}^{n} \log \left[ g(x_i; \xi) \right] + \sum_{i=1}^{n} G(x_i; \xi) \log[1 - G(x_i; \xi)]
\]

\[
+ (a - 1) \sum_{i=1}^{n} \log \left\{ 1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)} \right\}
\]

\[
+ (b - 1) \sum_{i=1}^{n} \log \left[ 1 - \left\{ 1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)} \right\}^a \right]
\]

\[
+ \sum_{i=1}^{n} \log \left( \frac{G(x_i; \xi)}{1 - G(x_i; \xi)} \right) - \log[1 - G(x_i; \xi)].
\]

The MLE \( \hat{\theta} \) of \( \theta \) can be evaluated by maximizing \( \ell(\theta) \). There are several routines for numerical maximization of \( \ell(\theta) \) in the R program (optim function), SAS (PROC NLMIXED), Ox (sub-routine MaxBFGS), among others.

All distributions belonging to the NKw-G family can be fitted to real data using the AdequacyModel package for the R statistical computing environment (https://www.r-project.org/). An important advantage of this package is that it is not necessary to define the log-likelihood function and that it computes the MLEs, their standard errors and some GoF statistics. We only need to provide the pdf and cdf of the distribution to be fitted to a data set.
Alternatively, we can differentiate the log-likelihood and solving the resulting nonlinear likelihood equations. Then, the score components with respect to $a$, $b$ and $\xi$ are

\[
\frac{\partial \ell}{\partial a} = \frac{n}{a} + \sum_{i=1}^{n} \log \left\{ 1 - \left[ 1 - G(x_i; \xi) \right]^{G(x_i; \xi)} \right\}
- \left( b - 1 \right) \sum_{i=1}^{n} \left\{ \frac{1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)}}{1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)}} \right\}^{a} \log \left\{ 1 - \left[ 1 - G(x_i; \xi) \right]^{G(x_i; \xi)} \right\},
\]

\[
\frac{\partial \ell}{\partial b} = \frac{n}{b} + \sum_{i=1}^{n} \log \left\{ 1 - \left[ 1 - G(x_i; \xi) \right]^{G(x_i; \xi)} \right\}^{a},
\]

\[
\frac{\partial \ell}{\partial \xi} = \sum_{i=1}^{n} \frac{G(x_i; \xi)}{g(x_i; \xi)} - \sum_{i=1}^{n} \left\{ \frac{G(x_i; \xi)}{1 - G(x_i; \xi)} - \log(1 - G(x_i; \xi)) \right\} \frac{G(x_i; \xi)}{1 - G(x_i; \xi)}[G(x_i; \xi) - 2]
- \left( b - 1 \right) \sum_{i=1}^{n} \left\{ \frac{1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)}}{1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)}} \right\}^{a} \left[ - \log \{1 - G(x_i; \xi)\} + G(x_i; \xi) \right.
+ (a - 1) \left\{ \frac{1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)}}{1 - [1 - G(x_i; \xi)]^{G(x_i; \xi)}} \right\}^{a - 1} \left[ - \log \{1 - G(x_i; \xi)\} + G(x_i; \xi) \right] \{1 + \log(1 - G(x_i; \xi))\} \right\} G_i^\xi
\times \left( 1 - G(x_i; \xi) \right)^{G(x_i; \xi) - 1} \left[ - \log \{1 - G(x_i; \xi)\} + G(x_i; \xi) \right] \left\{1 + \log(1 - G(x_i; \xi))\right\}] G_i^\xi,
\]

where $g_i^\xi = \frac{\partial g(x_i; \xi)}{\partial \xi}$ and $G_i^\xi = \frac{\partial G(x_i; \xi)}{\partial \xi}$ are column vectors of the same dimension of $\xi$.

Setting the score components to zero and solving them simultaneously yields the MLEs of the model parameters. The resulting equations cannot be solved analytically, but some statistical softwares can be used to solve them numerically through iterative Newton-Raphson type algorithms.

For interval estimation and hypothesis tests on the model parameters, we can obtain the $(p + 2) \times (p + 2)$ observed information matrix $I(\theta)$ numerically ($p$ is the dimension of $\xi$) since the expected information matrix $K(\theta)$ is very complicated and requires numerical integration.

Under standard regularity conditions, we have $(\hat{\theta} - \theta) \sim N_{p+2}(0, K(\theta)^{-1})$, where $\sim$ means approximately distributed and $K(\theta)$ is the expected information matrix. The asymptotic behavior remains valid if $K(\theta)$ is replaced by the observed information matrix $I(\hat{\theta})$ evaluated at $\hat{\theta}$, i.e., $I(\hat{\theta})$. The multivariate normal $N_{p+2}(0, I(\hat{\theta})^{-1})$ distribution can be used to construct approximate confidence intervals for the model parameters.

4. The NKwW Distribution

We now define the NKwW distribution by taking the Weibull baseline with cdf $G(x) = 1 - \exp(-ax^\beta)$ and pdf $g(x) = a\beta x^{\beta-1} \exp(-ax^\beta)$. Then, the cdf and pdf of the NKwW distribution are, respectively, given by

\[
F_{NKwW}(x) = 1 - \left\{ 1 - \exp \left\{ -ax^\beta \left( 1 - \exp(-ax^\beta) \right) \right\} \right\}^{a}^{b}\]
and
\[
f_{\text{NKwW}}(x) = a b \alpha x^{\beta-1} \exp \left\{ -\alpha x^{\beta} \left(2 - \exp(-\alpha x^{\beta})\right) \right\} \\
\times \left[ 1 - \exp \left\{ -\alpha x^{\beta} \left(1 - \exp(-\alpha x^{\beta})\right)\right]\right]^{a-1} \\
\times \left\{ 1 - \left[ 1 - \exp \left\{ -\alpha x^{\beta} \left(1 - \exp(-\alpha x^{\beta})\right)\right]\right]^{a}\right\}^{b-1} \\
\times \left[ 1 - \exp(-\alpha x^{\beta}) + a x^{\beta} \right].
\] (21)

Henceforth, a rv with density (21) is denoted by \( X \sim \text{NKwW}(a, b, \alpha, \beta) \). The hrf of \( X \) has the form
\[
h(x) = a b \alpha x^{\beta-1} \exp \left\{ -\alpha x^{\beta} \left(2 - \exp(-\alpha x^{\beta})\right) \right\} \\
\times \left[ 1 - \exp \left\{ -\alpha x^{\beta} \left(1 - \exp(-\alpha x^{\beta})\right)\right]\right]^{a-1} \\
\times \left\{ 1 - \left[ 1 - \exp \left\{ -\alpha x^{\beta} \left(1 - \exp(-\alpha x^{\beta})\right)\right]\right]^{a}\right\}^{-1} \\
\times \frac{1 - \exp(-\alpha x^{\beta}) + a x^{\beta}}{\exp(-\alpha x^{\beta}) + a x^{\beta}}.
\]

Figures 1 and 2 display some plots of the pdf and hrf of \( X \) for selected parameter values. Figure 1 reveals that the NKwW distribution is right-skewed and reversed-J shaped. Also, Figure 2 shows that the NKwW hrf can produce increasing, decreasing, bathtub and upside-down bathtub shapes.

![Figures 1 and 2 displaying plots of the NKwW densities for some parameter values.](a) (b) (c) (d)

**Figure 1.** Plots of the NKwW densities for some parameter values.
4.1. Linear Representation

The cdf of the NKwW distribution follows from Equation (14) is

$$F_{NKwW}(x) = \sum_{i=2}^{\infty} t_i \left[ 1 - \exp(-\alpha x^{\beta}) \right]^i.$$  \hspace{1cm} (22)

By expanding the binomial term in (22) and noting that $\sum_{i=2}^{\infty} t_i = 1$, we can write

$$F_{NKwW}(x) = 1 + \sum_{i=2}^{\infty} t_i \sum_{p=1}^{i} (-1)^p \binom{i}{p} \exp(-p \alpha x^{\beta})$$

and then by changing the index $p$ by $(p+1)$ we get

$$F_{NKwW}(x) = 1 + \sum_{i=2}^{\infty} t_i \sum_{p=0}^{i} (-1)^{p+1} \binom{i}{p+1} \exp[-(p+1) \alpha x^{\beta}].$$

Let $\delta_p = 2$ for $p = 0, 1, 2$ and $\delta_p = p$ for $p \geq 3$. We can interchange the sums conveniently to obtain

$$F_{NKwW}(x) = 1 + \sum_{p=0}^{\infty} (-v_p) \exp[-(p+1) \alpha x^{\beta}],$$

where $v_p = (-1)^p \sum_{i=\delta_p}^{\infty} \binom{i}{p+1} t_i$. 

Figure 2. Plots of the NKwW hazard rate for some parameter values.
By differentiating the last expression, the NKwW density can be expressed as

\[ f_{NKwW}(x) = \sum_{p=0}^{\infty} v_p \pi(x; (p+1)\alpha, \beta), \]

where

\[ \pi(x; (p+1)\alpha, \beta) = (p+1)\alpha \beta x^{\beta-1} \exp(-(p+1)\alpha x^\beta) \]
denotes the Weibull density with scale parameter \((p+1)\alpha\) and shape parameter \(\beta\).

Equation (23) shows that the NKwW density is a linear combination of Weibull densities. Therefore, several NKwW mathematical properties can be derived from those of the Weibull distribution.

4.2. Properties

Let \(Z_p\) be a rv with density \(\pi(x; (p+1)\alpha, \beta)\). Then, several properties of \(X\) can follow from those of \(Z_p\). First, the \(n\)th ordinary moment of \(X\) can be written as

\[ \mu_n' = \Gamma\left(\frac{n+1}{\beta}\right) \sum_{p=0}^{\infty} \frac{v_p}{[(p+1)\alpha]^{n/\beta}}. \]

Second, the cumulants \((\kappa_s)\) of \(X\) can be determined recursively from (24) as \(\kappa_s = \mu_s' - \sum_{k=1}^{s-1} \binom{s-1}{k-1} \kappa_k \mu_{s-k}'\), respectively, where \(\kappa_1 = \mu_1'\).

The skewness \(\gamma_1 = \kappa_3/\kappa_2^{3/2}\) and kurtosis \(\gamma_2 = \kappa_4/\kappa_2^2\) of \(X\) can be calculated from the third and fourth standardized cumulants. The skewness and kurtosis plots of the NKwW distribution are displayed in Figure 3. These plots reveal that the parameters \(a\) and \(b\) play a significant role in modeling the skewness and kurtosis behaviors of \(X\).

**Figure 3.** Skewness and kurtosis plots of the NKwW model for some values of \(a=1.5, 0.5, 1.5\) and \(\beta=2.5, 3.5, 0.5\).

Third, we derive an approximation for the density of the sample average \(X = \frac{1}{\sqrt{n}} \sum_{i=1}^{n} X_i\) of independent and identically (iid) rvs \(X_1, \ldots, X_n\) with density (21). Without loss of generality, we can replace each \(X_i\) by \((X_i - \mu_1')/\text{Var}(X_i)\) in order to simplify the approximation. By doing this,
the previous third and fourth standardized cumulants are $\gamma_1 = \mu_3' \text{ and } \gamma_2 = \mu_4' - 3$. Furthermore, we require the first six Hermite polynomials defined by $(-1)^n \partial^n \phi(x) / \partial x^n = H_n(x) \phi(x)$ for $n \geq 0$, where $\phi(x)$ is the standard normal pdf. They satisfy the recurrence equation $H_n(x) = y H_{n-1}(x) - (r - 1) H_{r-2}(x)$ ($r \geq 2$) and follow as $H_0(x) = 1$, $H_1(x) = x$, $H_2(x) = x^2 - 1$, $H_3(x) = x^3 - 3x$, $H_4(x) = x^4 - 6x^2 + 3$, $H_5(x) = x^5 - 10x^3 + 15x$ and $H_6(x) = x^6 - 15x^4 + 45x^2 - 15$.

The second-order Edgeworth expansion for the sample mean $\bar{X}$ of standardized NKwW rvs can be expressed as

$$f_{\bar{X}}(x) = \phi(x) \left\{ 1 + \frac{\mu_3'}{6\sqrt{n}} H_3(x) + \frac{(\mu_4' - 3)}{24n} H_4(x) + \frac{\mu_3'^2}{72n} H_6(x) \right\} + O(n^{-3/2}). \quad (25)$$

It is much more frequent in statistical applications to compute distribution functions than density functions. By integrating Equation (25), the cdf of $\bar{X}$ has the form

$$F_{\bar{X}}(x) = \Phi(x) - \phi(x) \left\{ \frac{\mu_3'}{6\sqrt{n}} H_3(x) + \frac{(\mu_4' - 3)}{24n} H_4(x) + \frac{\mu_3'^2}{72n} H_6(x) \right\} + O(n^{-3/2}), \quad (26)$$

where $\Phi(x)$ is the standard normal cdf. Equation (26) provides highly accurate results for the probabilities associated with $\bar{X}$.

Fourth, the $n$th incomplete moment of $X$, denoted by $m_n(y) = E(X^n \mid X \leq y) = \int_0^y x^n f_{NKwW}(x)dx$, can easily be obtained by changing variables from the lower incomplete gamma function $\gamma(s, x) = \int_0^x e^{-t} t^{s-1} dt$ when calculating the corresponding moment of $Z_p$. Then, we obtain

$$m_n(z) = \sum_{p=0}^{\infty} \frac{v_p}{(p+1)\alpha^n p!} \gamma \left( \frac{n}{\beta} + 1, (p+1)az^p \right). \quad (27)$$

Fifth, the first incomplete moment $m_1(z)$ is used to determine the totality of deviations from the mean and median of a distribution and construct the Bonferroni and Lorenz curves. The total deviations from the mean and median $M$ of $X$ can be expressed as $\delta_1 = 2\mu_1' F_{NKwW}(\mu_1') - 2m_1(\mu_1')$ and $\delta_2 = \mu_1' - 2m_1(M)$, where $M$ can be determined from $F_{NKwW}(M) = 0.5$. The Bonferroni and Lorenz curves of $X$ for a given probability $\pi$ are given by $B(\pi) = m_1(q) / (\pi mu_1')$ and $L(\pi) = \pi B(\pi)$, respectively, where $q = Q_{\pi}^{-1}$ is the qf of $X$ discussed in Section 4.1.

4.3. Quantile Function and Simulation Study

The qf of the NKwW distribution cannot be obtained explicitly. However, we can use Newton-Raphson algorithm to generate NKwW variates as follows:

1. Set $n$, $\alpha$, $\beta$, $a$, $b$ and initial value $x^0$.
2. Generate $U \sim \text{Uniform}(0, 1)$.
3. Update $x^0$ by using the Newton’s formula

$$x^* = x^0 - R(x^0; \alpha, \beta, a, b),$$

where $R(x^0; \alpha, \beta, a, b) = \frac{F_{NKwW}(x^0; \alpha, \beta, a, b)}{f_{NKwW}(x^0; \alpha, \beta, a, b)}$, and $F_{NKwW}$ and $f_{NKwW}$ are obtained from Equation (20) and Equation (21), respectively.
4. If $|x^0 - x^*| \leq \epsilon$, ($\epsilon > 0$, very small tolerance limit), then store $x^0 = x^*$ as a variate from the NKwW($\alpha$, $\beta$, $a$, $b$) distribution.
5. If $|x^0 - x^*| > \epsilon$, then set $x^0 = x^*$ and go to step 3.
6. Repeat steps (2)–(5) $n$ times to generate $x_1, \cdots x_n$.

The R script to generate observations from the NKwW distribution is given in the Appendix A.
Here we study the performance and accuracy of maximum likelihood estimates of the NKwW parameters using Monte Carlo simulations. The simulation study is carried out for sample sizes $n = 25, 50, 75, 100, 200$ and parameter scenarios: I: $\alpha = 0.5, \beta = 0.5, a = 2.5,$ and $b = 1.5,$ II: $\alpha = 1.5, \beta = 1.5, a = 1.5,$ and $b = 1.5$ and III: $\alpha = 1.1, \beta = 5.5, a = 0.5,$ and $b = 0.5$. We used the above algorithm for sample generation whose R-codes are given in Appendix A. The simulation study is repeated for $N = 1000$ times each with given sample size and computed the average estimates (AE) along with their average biases (Bias) of the MLEs and mean squared errors (MSE).

$$\text{Bias}(\hat{\theta}) = \frac{1}{N} \sum_{i=1}^{N} \hat{\theta}_i - \theta \quad \text{and} \quad \text{MSE}(\hat{\theta}) = \frac{1}{N} \sum_{i=1}^{N} (\hat{\theta}_i - \theta)^2.$$  

We display Bias and MSE for the parameters $\alpha, \beta, a$ and $b$ in Figures 4 and 5, respectively, which indicate that as sample size increases the bias and MSE decreases. Thus, MLEs perform well in estimating the parameters of the NKwW distribution.

![Figure 4. Plots of estimated MSEs for selected parameter values.](image-url)
4.4. Estimation

Let \(x_1, \ldots, x_n\) be a sample of size \(n\) from the NKwW distribution given in Equation (21). The log-likelihood function \(\ell = \ell(\theta)\) for the vector of parameters \(\theta = (\alpha, \beta, a, b)^\top\) is

\[
\ell = n \log(a b \alpha \beta) - 2a \sum_{i=1}^{n} x_i^\beta + a \sum_{i=1}^{n} x_i^\beta \exp(-a x_i^\beta) \\
+ \sum_{i=1}^{n} \log \left[ a x_i^\beta + \exp(-a x_i^\beta) \left(1 - \exp(-a x_i^\beta)\right) \right] \\
+ (\beta - 1) \sum_{i=1}^{n} \log x_i + (a - 1) \sum_{i=1}^{n} \log \left[1 - \exp(-a x_i^\beta) \left(1 - \exp(-a x_i^\beta)\right)\right] \\
+ (b - 1) \sum_{i=1}^{n} \log \left[1 - \left\{1 - \exp(-a x_i^\beta) \left(1 - \exp(-a x_i^\beta)\right)\right\}^a\right].
\]
where

\begin{align*}
\mathcal{L} &= \left\{ -\alpha x_i^\beta \left[ 1 - \exp(-\alpha x_i^\beta) \right] \right\}, \\
z_{ia} &= x_i^\beta \left[ ax_i^\beta + \exp(ax_i^\beta) - 1 \exp(-ax_i^\beta) \right], \\
z_{ib} &= ax_i^\beta \log(x_i) \left[ ax_i^\beta + \exp(ax_i^\beta) - 1 \exp(-ax_i^\beta) \right].
\end{align*}

The MLE $\hat{\theta}$ of $\theta$ can be obtained by solving the nonlinear equations $U_a = 0$, $U_\beta = 0$, $U_a = 0$ and $U_b = 0$. These equations cannot be solved analytically and statistical software can be used to obtain the estimates numerically. We can use iterative techniques such as a Newton-Raphson type algorithm to obtain $\hat{\theta}$ using a wide range of initial values. The initial values for the parameters are important but are not hard to obtain from the fit of the Weibull distribution. This process often results or leads to more than one maximum. However, in these cases, we consider the MLEs corresponding to the largest value of the maximum. In a few cases, no maximum is identified for the selected initial values. In these cases, a new initial value is tried in order to obtain a maximum.

5. Empirical Illustrations of NKwW Model

In this section, we compare the NKwW distribution with some well-known extended (or generalized) Weibull distributions. To check the potentiality of the new distribution, we use two real data sets representing different hydrological events such as precipitation and flood. We compare the NKwW model with the Kumaraswamy-Weibull (KwW) (Cordeiro et al. [37]), beta-Weibull (BW) (Lee et al. [38]), exponentiated-generalized Weibull (EGW) (Oguntunde et al. [39]), McDonald-Weibull (McW) (Cordeiro et al. [40]), gamma-Weibull (GaW) (Cordeiro et al. [41]), odd log-logistic Weibull (OLLW) (da-Cruz et al. [42]), Marshall-Olkin Weibull (MOW) (Ghitany et al. [43]), transmuted-Weibull (TrW) (Khan et al. [44]) and Weibull (W) models by means of two real-life data sets which are described below:

Data Set 1. Precipitation data. The data were taken from Katz et al. [45] which represent the annual maximum precipitation (inches) for one rain gauge in Fort Collins, Colorado from 1900 through 1999. The data are: 239, 232, 434, 85, 302, 174, 170, 121, 193, 168, 148, 116, 132, 132, 144, 183, 223, 96, 298, 97, 116, 146, 84, 230, 138, 170, 117, 115, 132, 125, 156, 124, 189, 193, 71, 176, 105, 93, 354, 60, 151, 160, 219, 142, 117, 87, 223, 215, 108, 354, 213, 306, 169, 184, 71, 98, 96, 218, 176, 121, 161, 321, 102, 269, 98, 271, 95, 212, 151, 136, 240, 162, 71, 110, 285, 215, 103, 443, 185, 199, 115, 134, 297, 187, 203, 146, 94, 129, 162, 112, 348, 95, 249, 103, 181, 152, 135, 463, 183, 241.
Data set 2. Flood data. The data were taken from Asgharzadeh et al. [46] which represent the maximum annual flood discharges (in units of 1000 cubic feet per second) of the North Saskachevan River at Edmonton, over a period of 48 years. The data are: 19.885, 20.940, 21.820, 23.700, 24.888, 25.460, 25.760, 26.720, 27.500, 28.100, 28.600, 30.200, 30.380, 31.500, 32.600, 32.680, 34.400, 35.347, 35.700, 38.100, 39.020, 39.200, 40.000, 40.400, 40.400, 42.250, 44.730, 44.900, 46.300, 50.330, 51.442, 57.220, 58.700, 58.800, 61.200, 61.740, 65.440, 65.597, 66.000, 74.100, 75.800, 84.100, 106.600, 109.700, 121.970, 121.970, 185.560.

All the calculations in these two applications are performed using the AdequacyModel package in R. The unknown parameters of the models are estimated by the maximum likelihood method. The log-likelihood function is evaluated at the MLEs (\( \hat{\ell} \)). The well-known GoFS such as the Akaike information criterion (AIC), Bayesian Information Criterion (BIC), Hannan-Quinn Information Criterion (HQIC), Anderson-Darling (\( A^* \)), Cramér-von Mises (\( W^* \)) and Kolmogrov-Smirnov (K-S) are adopted for model comparisons. The lower values of GoFS and higher \( p \)-values of the K-S statistic indicate good fits.

Table 1 and Table 2 list the MLEs and their standard errors (SEs) for the NKwW distribution and other competitive models (KwW, BW, EGW, McW, GaW, OLLW, MOW, TrW and W) fitted to the two hydrological data sets. The values of the GoFS in Table 3 and Tabl 4 indicate that the NKwW model shows small values of these statistics and hence it provides the best fit as compared to the other models. The plots in Figures 6 and 7 also support our claim.

![Figure 6](image-url)  
(a) Estimated density (b) K-M (c) hazard rate, and (d) Box-plots for the data set 1.

![Figure 7](image-url)  
(a) Estimated density (b) K-M (c) hazard rate, and (d) Box-plots for the data set 2.
Table 1. MLEs and their SEs (in parentheses) for data set 1.

| Distribution | $\alpha$      | $\beta$      | $a$          | $b$          | $\theta$ |
|--------------|---------------|---------------|--------------|--------------|----------|
| NKwW         | 0.0089 (0.0023) | 1.1514 (0.0730) | 5.0192 (1.6716) | 0.5054 (0.1807) | –        |
| KwW          | 0.0160 (0.0277) | 1.3962 (0.2113) | 5.7590 (1.9264) | 0.3381 (0.1554) | –        |
| BW           | 0.0219 (0.0767) | 0.7969 (0.1903) | 13.2183 (5.1706) | 1.2340 (0.9787) | –        |
| EGW          | 0.0086 (0.0222) | 0.9045 (0.1288) | 2.0898 (0.6257) | 10.5512 (4.4416) | –        |
| McW          | 0.0132 (0.0332) | 1.2859 (0.2544) | 1.7925 (0.6126) | 0.5887 (0.3831) | 2.5824   |
| GaW          | 1.1306 (0.0496) | 0.5469 (0.0154) | 17.6158 (1.4970) | –            | –        |
| OLLW         | 0.0045 (0.0033) | 1.0313 (0.1759) | 2.4836 (0.4532) | –            | –        |
| MOW          | 0.0032 (0.0002) | 3.4739 (0.0154) | –            | –            | 0.1039   |
| TrW          | 0.0043 (0.0003) | 2.4549 (0.1755) | –            | –            | 0.6144   |
| W            | 0.0050 (0.0002) | 2.2745 (0.1629) | –            | –            | –        |

Table 2. MLEs and their standard errors (in parentheses) for data set 2.

| Distribution | $\alpha$      | $\beta$      | $a$          | $b$          | $\theta$ |
|--------------|---------------|---------------|--------------|--------------|----------|
| NKwW         | 0.1742 (0.0316) | 0.9887 (0.0619) | 59.0160 (0.4024) | 0.2183 (0.0585) | –        |
| KwW          | 0.1609 (0.0153) | 1.0252 (0.0276) | 54.7825 (0.1358) | 0.2041 (0.0382) | –        |
| BW           | 0.1320 (0.0073) | 1.1080 (0.0068) | 23.0602 (0.8794) | 0.1940 (0.0324) | –        |
| EGW          | 0.0090 (0.0041) | 0.7774 (0.1370) | 5.5966 (2.0458) | 10.5493 (5.6821) | –        |
| McW          | 0.1608 (0.0340) | 1.0049 (0.0466) | 14.5078 (9.8227) | 0.2210 (0.0895) | 2.5180   |
| GaW          | 4.6144 (0.1518) | 0.4983 (0.0217) | 14.7225 (1.7239) | –            | –        |
| OLLW         | 0.0154 (0.0021) | 0.9508 (0.3378) | 2.3925 (0.9487) | –            | –        |
| MOW          | 0.0065 (0.0014) | 3.3556 (0.4292) | –            | –            | 0.0145   |
| TrW          | 0.0137 (0.0016) | 1.9476 (0.1941) | –            | –            | 0.7003   |
| W            | 0.0171 (0.0015) | 1.7719 (0.1776) | –            | –            | –        |
The bivariate new Kumaraswamy (BvNKw) G-family is constructed from three independent NKw-G families by using a minimization process. Assume three independent rvs $Y_1, Y_2, Y_3$ and defining

$$X_1, X_2 = k_1, k_2, k_3$$

The marginal reliability functions (rfs) corresponding to (28) can be written as

$$S_{X_i}(x_i) = S_{NKw-G}(x_i; a, b_i + b_3, \xi); i = 1, 2.$$  (29)

The corresponding joint pdf (jpdf) to (28) can be formulated as

$$f_{X_1, X_2}(x_1, x_2; Y) = \begin{cases} f_{NKw-G}(x_1; a, b_1, \xi)f_{NKw-G}(x_2; a, b_2 + b_3, \xi) & \text{if } x_1 < x_2, \\ f_{NKw-G}(x_1; a, b_1 + b_3, \xi)f_{NKw-G}(x_2; a, b_2, \xi) & \text{if } x_1 > x_2, \\ f_{NKw-G}(x_1; a, b_1 + b_3, \xi)f_{NKw-G}(x_2; a, b_2 + b_3, \xi) & \text{if } x_1 = x_2 = x, \end{cases}$$  (30)

6. Bivariate New Kumaraswamy G-Family

In this Section, we introduce a bivariate extension of the NKw-G family according to Marshall and Olkin shock model (see, Marshall and Olkin, [47]). Several authors used the Marshall and Olkin approach as a method to generate bivariate distributions, see for example Sarhan and Balakrishnan, [48], Kundu and Dey [49], El-Gohary et al. [50], Muhammed [51], El-Bassiouny et al. [52], Ghosh and Hamedani [53], El-Morshedly et al. [54,55], Eliwa et al. [56], Hussain et al. [57], among others. The bivariate new Kumaraswamy (BvNKw) G-family is constructed from three independent NKw-G families by using a minimization process. Assume three independent rvs $Y_k \sim NKw-G(a, b_k, \xi); k = 1, 2, 3$ and defining $X_j = \min\{Y_j, Y_3\}; j = 1, 2$, the bivariate random vector $X$ is said to have the BvNKw-G family with parameters vector $Y = (a, b_1, b_2, b_3, \xi)$ if its joint reliability function (jrf) is given by

$$S_{X_1, X_2}(x_1, x_2; Y) = \begin{cases} S_{NKw-G}(x_1; a, b_1, \xi)S_{NKw-G}(x_2; a, b_2 + b_3, \xi) & \text{if } x_1 < x_2, \\ S_{NKw-G}(x_1; a, b_1 + b_3, \xi)S_{NKw-G}(x_2; a, b_2, \xi) & \text{if } x_1 \geq x_2. \end{cases}$$  (28)

The marginal reliability functions (rfs) corresponding to (28) can be written as

$$S_{X_i}(x_i) = S_{NKw-G}(x_i; a, b_i + b_3, \xi); i = 1, 2.$$  (29)

The corresponding joint pdf (jpdf) to (28) can be formulated as

$$f_{X_1, X_2}(x_1, x_2; Y) = \begin{cases} f_{NKw-G}(x_1; a, b_1, \xi)f_{NKw-G}(x_2; a, b_2 + b_3, \xi) & \text{if } x_1 < x_2, \\ f_{NKw-G}(x_1; a, b_1 + b_3, \xi)f_{NKw-G}(x_2; a, b_2, \xi) & \text{if } x_1 > x_2, \\ f_{NKw-G}(x_1; a, b_1 + b_3, \xi)f_{NKw-G}(x_2; a, b_2 + b_3, \xi) & \text{if } x_1 = x_2 = x, \end{cases}$$  (30)
where the jpdf in Equation (30) can be derived from a well-known formula (see Eliwa and El-Morshedy, [58]). The marginal pdfs corresponding to Equation (29) can be proposed as

$$f_{X_i}(x_i) = f_{NKw-G}(x_i; a, b_i + b_3, \xi); i = 1, 2.$$  \hfill (31)

If X have the BvNKw-G family, then the distributions of max{X_1, X_2} and min{X_1, X_2} are

$$F_{\max\{X_1,X_2\}}(w) = \prod_{i=1}^{3} F_{NKw-G}(w; a, b_i, \xi) \quad \text{and} \quad F_{\min\{X_1,X_2\}}(w) = 1 - \prod_{i=1}^{3} S_{NKw-G}(w; a, b_i, \xi),$$

respectively. If $X_j \sim \text{NKw-G}(a, b_j + b_3, \xi)$; $j = 1, 2$, then the coefficient of correlation between $X_1$ and $X_2$ is

$$Q(u)_{X_1,X_2} = \begin{cases} 4 F_{NKw-G} \left( Q(u)_{X_1}; a, b_1, \xi \right) F_{NKw-G} \left( Q(u)_{X_2}; a, b_2 + b_3, \xi \right) - 1 & \text{if } x_1 < x_2, \\ 4 F_{NKw-G} \left( Q(u)_{X_1}; a, b_1 + b_3, \xi \right) F_{NKw-G} \left( Q(u)_{X_2}; a, b_2, \xi \right) - 1 & \text{if } x_1 > x_2. \end{cases}$$ \hfill (32)

The BvNKw-G family has a singular part along the line $x_1 = x_2$ with weight $(b_1 + b_2 + b_3)^{-1}$, whereas on $x_1 \neq x_2$ with weight $(b_1 + b_2)(b_1 + b_2 + b_3)^{-1}$, the BvNKw-G family has an absolute continuous part. Assume $\delta_i = S_{X_i}(x_i)$ where $X_j \sim \text{NKw-G}(a, b_j + b_3, \xi)$; $j = 1, 2$, the jrf of the proposed family can be derived by using copula of the Marshall-Olkin model as

$$S_{X_1,X_2}(x_1, x_2; Y) = \delta_1^{1 - \tau_1} \delta_2^{1 - \tau_2} \max \left( \delta_1^{\tau_1}, \delta_2^{\tau_2} \right),$$

for $0 < \tau_1, \tau_2 < 1$,

where $\tau_j = \frac{b_j}{b_1 + b_2 + b_3}$. For more details on copula property, see Gijbels et al. [59] and Hušková and Maciak [60].

Using Equations (28) and (30), the joint hrf (jhrf) can easily be reported by using $h_{X_1,X_2}(x_1, x_2; Y) = f_{X_1,X_2}(x_1, x_2; y) \times f_{X_1,X_2}(y, x_2; x_1)$. Figures 8–10 show the jpdf, jhrf, and jrf for different values of the BvNKw-Weibull (BvNKwW) parameters.

**Figure 8.** The surface plots of the jpdf, jhrf and jrf of the BvNKwW model for $a = 0.6, b_1 = 4, b_2 = 4, b_3 = 4, \alpha = 0.6$ and $\beta = 2.9$. 
Figure 9. The surface plots of the jpdf, jhrf and jrf of the BvNKwW model for $a = 1.6, b_1 = 2, b_2 = 2, b_3 = 2, \alpha = 1.6$ and $\beta = 2.9$.

Figure 10. The surface plots of the jpdf, jhrf and jrf of the BvNKwW model for $a = 0.8, b_1 = 1.5, b_2 = 1.5, b_3 = 1.5, \alpha = 0.9$ and $\beta = 1.9$.

6.1. The MLE for the BvNKw-G Family

In this section, the unknown parameters of the BvNKw-G family are estimated by using the maximum likelihood approach. Assuming that $(x_{11}, x_{21}), (x_{12}, x_{22}), \ldots, (x_{1p}, x_{2p})$ is a sample of size $p$ from the BvNKw-G family where $\Lambda_1 = \{x_{1i} < x_{2i}\}, \Lambda_2 = \{x_{1i} > x_{2i}\}, \Lambda_3 = \{x_{1i} = x_{2i} = x_i\}$, $p_s = |\Lambda_s|; s = 1, 2, 3$ and $|\Lambda| = p = p_1 + p_2 + p_3$. Using Equation (30), the likelihood function $l(Y)$ can be expressed as

$$l(Y) = \prod_{i=1}^{p_1} f_{\text{NKw-G}}(x_{1i}; a, b_1, \xi) f_{\text{NKw-G}}(x_{2i}; a, b_2 + b_3, \xi) \prod_{i=1}^{p_2} f_{\text{NKw-G}}(x_{1i}; a, b_1 + b_3, \xi)$$

$$\times f_{\text{NKw-G}}(x_{2i}; a, b_2, \xi) \left(\frac{b_3}{b_1 + b_2 + b_3}\right) \prod_{i=1}^{p_3} f_{\text{NKw-G}}(x_{i}; a, b_1 + b_2 + b_3, \xi).$$ (33)

Through differentiation of the term $L(Y) = \log l(Y)$ with respect to $a, b_1, b_2, b_3$ and $\xi$, and then equating the resulting equations to zeros, we get the non-linear normal equations. An iterative procedure such as Newton–Raphson technique is required to solve them numerically.

7. Empirical Illustrations of BvNKwW Model Through Motors Data

In this Section, the flexibility of the BvNKwW model is shown through a real-life data application. This data is reported in Relia and Staff [61] which represents the failure times of a parallel system constituted by two identical motors in days. The fitted bivariate models are compared using some statistical criteria, namely AIC, CAIC, BIC and HQIC. To fit the marginals of the BvNKwW model, the K-S with its $p$-value are used. The BvNKwW model is compared with other bivariate distributions such as: bivariate generalized power Weibull (BvGPW), bivariate exponentiated Weibull (BvEW), bivariate Weibull (BvW), bivariate generalized exponential (BvGEx), bivariate exponential (BvEx),
and bivariate generalized linear failure rate (BvGLFR) distributions when applied to this data set. At first, the marginals $X_1$, $X_2$ and max$(X_1, X_2)$ are fitted separately to this data set. The MLEs of the parameters $(a, b, \alpha, \beta)$ of the corresponding NKwW distribution for $X_1$, $X_2$ and max$(X_1, X_2)$ are $(60.5030, 732.6059, 0.9694, 0.17440)$, $(1.8182, 84.4223, 0.0019, 0.9434)$ and $(27.8306, 263.4773, 0.4649, 0.2626)$, respectively. The $-L$, K-S, p-value for the marginals are reported in Table 5.

Table 5. The $-L$, K-S and p-values for $X_1$, $X_2$ and max$(X_1, X_2)$.

| Model | $-L$  | K-S  | P-Value | $-L$  | K-S  | P-Value | $-L$  | K-S  | P-Value |
|-------|-------|------|---------|-------|------|---------|-------|------|---------|
| NKwW  | 100.2890 | 0.2376 | 0.2614  | 102.9142 | 0.0902 | 0.9956  | 101.1965 | 0.1372 | 0.8871   |

Table 5 lists that the NKwW model fits to the real data for the marginals. Figures 11–13 show the fitted pdf, cdf and probability-probability (pp) plots, which support our empirical results in Table 5.

Figure 11. The fitted pdfs plots for $X_1$, $X_2$ and max$(X_1, X_2)$.

Figure 12. The estimated cdfs for $X_1$, $X_2$ and max$(X_1, X_2)$. 
Figure 13. The pp-plots for $X_1$, $X_2$ and $\max(X_1, X_2)$.

Figure 14 show the box and TTT plots for the $X_1$, $X_2$ and $\max(X_1, X_2)$, and the scatter plot for the motors data.

It is noted that the BvNKwW model can be used to analyze and the real data on motors. The MLEs, $-L$, AIC, CAIC, BIC and HQIC values for the BvNKwW model and some competitive models are listed in Table 6.

Table 6. The MLEs with its (SE) and goodness of fit measures for Motors data.

| Model | Statistic | BvNKwW | BvGPW | BvEW | BvW | BvGEx | BvEx | BvGLFR |
|-------|-----------|--------|-------|------|-----|-------|------|--------|
|       | $\hat{a}$ | 1.6395 | 0.0291 | 0.5203 | 0.0389 | 0.0137 | $-6.99\times10^{-5}$ |
|       |           | (0.0651) | (0.0557) | (0.0511) | (0.0158) | (0.0023) | $-1.09\times10^{-5}$ |
|       | $\hat{b}_1$ | 3.1333 | 1.5591 | 30.1381 | 0.2004 | 2.4541 | 0.0023 | 0.4171 |
|       |           | (0.2364) | (3.0428) | (9.6756) | (0.0511) | (1.0189) | (9.71\times10^{-7}) |
|       | $\hat{b}_2$ | 3.3989 | 1.8581 | 24.1351 | 0.2383 | 2.8803 | 0.0021 | 0.4864 |
|       |           | (0.1896) | (3.6787) | (7.6763) | (0.0513) | (1.1158) | (1.05\times10^{-6}) |
|       | $\hat{b}_3$ | 4.2869 | 3.7191 | 61.8051 | 0.3381 | 6.0641 | 0.0051 | 1.0188 |
|       |           | (0.0985) | (7.2630) | (6.3779) | (0.0622) | (1.8113) | (1.33\times10^{-6}) |
Table 6. Cont.

| Statistic | BvNKwW | BvGPW | BvEW | BvW | BvGEx | BvEx | BvGLFR |
|-----------|--------|-------|------|-----|-------|------|--------|
| $\hat{\alpha}$ | 0.0008 | 0.0291 | 0.5203 | 0.0389 | 0.0137 | – | $6.99 \times 10^{-5}$ |
| | (0.0001) | (0.0557) | (0.0511) | (0.0158) | (0.0023) | – | – |
| $\hat{\beta}$ | 1.2532 | – | – | – | – | – | – |
| | (0.3421) | – | – | – | – | – | – |
| $-L$ | 211.1711 | 431.7909 | 339.2656 | 422.9532 | 335.2312 | 355.7323 | 331.7681 |
| AIC | 434.3422 | 871.5818 | 688.5312 | 853.9064 | 678.4624 | 717.4646 | 673.5362 |
| CAIC | 441.9786 | 874.6887 | 693.5312 | 856.9833 | 681.5393 | 719.1789 | 678.5362 |
| BIC | 439.6844 | 875.1431 | 692.9831 | 857.4679 | 682.0239 | 720.1357 | 677.9881 |
| HQIC | 435.0788 | 872.0729 | 689.1451 | 854.3975 | 678.9535 | 717.8329 | 674.1501 |

From Table 6, it is observed that the BvNKwW model provides a better fit as compared to competitive models.

8. Concluding Remarks

Proposing new and flexible models through G-classes is an active research area in distribution theory. The new era has proved that flexible models can prove very helpful to researchers and practitioners in investigating data generated from different phenomena. G-classes are one of the basic source which provides a paradigm to data related science and its investigation.

The purpose of our article is to contribute a new G-family and hence a new Kumaraswamy-G family of distributions is introduced from a new generator $1 - \bar{G}(x)^{G(x)}$ for support $(0,1)$, that has ability to serve as an alternative to well-known Kumaraswamy-G family (pioneered in 2011) and other classes of distributions for $T \in (0,1)$. The proposed generator adopted here involves a different function of the cumulative function instead of existing generator which is only based on $G(x)$. In the literature, beta-G, Kw-G, Mc-G and TL-G families were introduced from the existing generator $G(x)$ for bounded unit interval. Therefore, similar G-families can be developed from our proposed generator $1 - \bar{G}(x)^{G(x)}$. We obtain some structural properties of this new Kumaraswamy-G family, and also study some properties of the special model called the new Kumaraswamy-Weibull (NKwW) distribution. We compare this distribution with the well-known generalized Weibull models (Kumaraswamy-Weibull, McDonald-Weibull, beta-Weibull, exponentiated-generalized Weibull, gamma-Weibull, odd log-logistic-Weibull, Marshall-Olkin-Weibull, transmuted-Weibull and Weibull) using six popular GoF test-statistics. We found that the new distribution provides better estimates and minimum GoF-tests values. Thus, the NKwW distribution outperforms the well-established competitive models on the basis of numerical and graphical analysis. Similarly, the BvNKwW distribution is introduced, and is compared with other well-known bivariate models such as bivariate generalized power Weibull, bivariate exponentiated Weibull, bivariate Weibull, bivariate generalized exponential, bivariate exponential, and bivariate generalized linear failure rate distributions. The results of popular goodness-of-fit statistics showed that our proposed bivariate model is better as compared to other well-known bivariate models. We expect that this new family will be able to attract readers and applied statisticians.

Author Contributions: The main results are a part of M.A.H.’s dissertation under M.H.T.’s supervision. The other authors G.M.C., M.E.-M. and M.S.E. contributed to the mathematical properties, and bivariate section and its application. In general, all authors have contributed in manuscript refinement, preparation and revision. All authors have read and agreed to the published version of the manuscript.

Funding: This publication was supported by the Deanship of Scientific Research (DSR) at Prince Sattam bin Abdulaziz University, Al-Kharj, Saudi Arabia.

Acknowledgments: The authors would like to thank the editor and the two worthy reviewers for useful comments and suggestions, which improved the earlier version of the manuscript.
Conflicts of Interest: The authors declare no conflict of interest.

Appendix A

The R script to generate NKwW variates is given below:

```r
n=20; alpha=1; beta=1.5; a=2.5; b=2.5;
f=function(x,alpha,beta,a,b)
{
  g=alpha*beta*x^{beta-1})*exp(-alpha*x^{beta})
  G=1-exp(-alpha*x^{beta})
  F=1-(1-(1-(1-G)^G)^a)^b
  D=a*b*g*(1-G)^G*(1-(1-G)^G)^(a-1)*((G)/(1-G)-log(1-G))
  return(D)
}
F=function(x,alpha,beta,a,b)
{
  g=alpha*beta*x^{beta-1})*exp(-alpha*x^{beta})
  G=1-exp(-alpha*x^{beta})
  F=1-(1-(1-(1-G)^G)^a)^b
  D=a*b*g*(1-G)^G*(1-(1-G)^G)^a)^b-1
  return(D)
}
u=runif(n,0,1);
x=rep(0,n);
for(i in 1:n)
{
  x0=1
  xnew=x0-((F(x0,alpha,beta,a,b)-u[i])/f(x0,alpha,beta,a,b))
  while(abs(xnew-x0) > 0.0001)
  {
    x0=xnew
    xnew=x0-((F(x0,alpha,beta,a,b)-u[i])/f(x0,alpha,beta,a,b))
  }
  x[i]=xnew
}
print(x)
```

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