Solvation model dependency of helix-coil transition in polyalanine

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Abstract

Helix-coil transitions in poly-alanine molecules of length 10 are studied by multicanonical Monte Carlo simulations. The solvation effects are included by either a distance-dependent dielectric permittivity or by a term that is proportional to the solvent-accessible surface area of the peptide. We found a strong dependence of the characteristics of the helix-coil transition from the details of the solvation model.

Keywords: Helix-coil transition, Protein folding, Generalized ensemble simulations, solvation models

1 Introduction

There has been recently a renewed interest in the conditions under which α-helices, a common structure in proteins, are formed or dissolved. It is long known that α-helices undergo a sharp transition towards a random coil state when the temperature is increased. The characteristics of this so-called helix-coil transition have been studied extensively [1], most recently in Refs. [2, 3]. In Refs. [4, 5] evidence was presented that the helix-coil transition in polyalanine exhibits a true thermodynamic phase transition when interactions between all atoms in the molecule are taken into account [4, 5].

The later results were obtained from gas-phase simulations of poly-alanine. While there is some experimental evidence [6] supporting the numerical results of these gas-phase simulations, the question remains how these results relate to the biologically more relevant case of solvated molecules. First investigations of this question were described in Refs. [7, 8] where it was claimed that the transition temperature is lower

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in water than in vacuum. However, that investigation relies on a single representation of the protein-water interaction and the dependence of their results on the details of the solvation term is not clear.

In this paper, we have investigated how the characteristics of helix-coil transition change with the details of the solvation term. For this purpose, we have performed multicanonical simulations of polyalanine molecules of length 10. The protein-water interaction was included in two ways: either by a distance-dependent dielectric permittivity or by a term that is proportional to the solvent-accessible surface area of the peptide. For the later case we have considered four different parameter sets: OONS [9], JRF [10], W92 [11] and SCH [12]. Quantities such as the energy, helicity and susceptibility were calculated as function of temperature. Our result were compared with that of gas phase simulations. A strong dependence of the characteristics of the helix-coil transition from the details of the solvation term was found.

2 Methods

Our investigation of the helix-coil transition for polyalanine is based on a detailed, all-atom representation of that homopolymer. The interaction between the atoms was described by a standard force field, ECEPP/2, [13] (as implemented in the program package SMMP [14]) and is given by:

\[
E_{\text{tot}} = E_C + E_{LJ} + E_{HB} + E_{\text{tor}},
\]

\[
E_C = \sum_{(i,j)} \frac{332q_i q_j}{\epsilon r_{ij}},
\]

\[
E_{LJ} = \sum_{(i,j)} \left( \frac{A_{ij}}{r_{ij}^{12}} - \frac{B_{ij}}{r_{ij}^6} \right),
\]

\[
E_{HB} = \sum_{(i,j)} \left( \frac{C_{ij}}{r_{ij}^{12}} - \frac{D_{ij}}{r_{ij}^{10}} \right),
\]

\[
E_{\text{tor}} = \sum_l U_l \left( 1 \pm \cos(n_l \chi_l) \right).
\]

Here, \(r_{ij}\) (in Å) is the distance between the atoms \(i\) and \(j\), and \(\chi_l\) is the \(l\)-th torsion angle. We have chosen ECEPP/2 instead of the newer ECEPP/3 differs because this choice allows a more easy comparison with our previous work. Both force fields differ from each other only in the way in which prolines and end groups are treated. In preliminary polyalanine simulations we found no qualitative differences in our results when ECEPP/3 was used instead of ECEPP/2 (data not shown).
The interactions between our homo-oligomer and water are approximated by means of two implicit water models. In the first model (DDE) the electrostatic interactions in the presence of water rely on a distance dependent electrostatic permittivity [15]:

$$\varepsilon(r) = D - \frac{D - 2}{2} [(sr)^2 + 2sr + 2]e^{-sr}. \quad (6)$$

For the parameters $D$ and $s$ empirical values are chosen such that for large distances the permittivity takes the value of bulk water ($\varepsilon \approx 80$), and the value $\varepsilon = 2$ for short distances (protein interior space). Equation (6) is the result of interpolation of two types of interactions. For short distances it models the interaction of two charges placed in continuum medium, while over long distances it represents a Debye curve. This is clearly a gross over-simplification of protein-solvent interactions. However, approximating solvation effects by a distance-dependent dielectric permittivity was used by many authors to study the proteins and nucleic acids (e.g. [16]) since it does not significantly slow down protein simulations below that of simple \textit{in vacuo} simulations.

In another common approximation of the protein-solvent interaction one assumes that the free energy contributions from atomic groups immersed in the protein interior differ from contributions of groups exposed to the water. It is commonly accepted [13, 11, 17, 18] that this free-energy difference is proportional to the surface area of the atomic group which is exposed to the solvent. Within this approximation, the total solvation energy of a protein is given by the sum of contributions from each solvated atomic groups:

$$E_{\text{sol}} = \sum_i \sigma_i A_i, \quad (7)$$

where $E_{\text{sol}}$ is the solvation energy, $A_i$ is the conformational dependent solvent accessible area of the surface of the $i$-th atom and $\sigma_i$ is the atomic solvation parameter for the atom $i$. The summation is extended over all atomic groups. The solvation parameters are evaluated experimentally by measuring the free energy needed to bring the group from a nonpolar environment (usually octanol or ethanol are used as convenient compounds) into water. Many sets of solvation parameters were evaluated by several authors with different methods, but unfortunately it is not always obvious which one is the most appropriate one. The sets we study here are named by us OONS [3], JRF [11], W92 [11] and SCH [12], and are described in the respective references.
Simulations of detailed models of biological macromolecules are notoriously difficult. This is because the various competing interactions within the polymer lead to an energy landscape characterized by a multitude of local minima. Hence, in the low-temperature region, canonical Monte Carlo or molecular dynamics simulations will tend to get trapped in one of these minima and the simulation will not thermalize within the available CPU time. Only recently, with the introduction of new and sophisticated algorithms such as multicanonical sampling \[19\] and other generalized-ensemble techniques \[20\] was it possible to alleviate this problem in protein simulations \[21\]. For polyalanine, both the failure of standard Monte Carlo techniques and the superior performance of the multicanonical algorithm are extensively documented in earlier work \[22\]. For this reason, we use again this sophisticated simulation technique for our project.

In the multicanonical algorithm \[19\] conformations with energy \(E\) are assigned a weight \(w_{\text{mu}}(E) \propto 1/n(E)\). Here, \(n(E)\) is the density of states. A simulation with this weight will lead to a uniform distribution of energy:

\[
P_{\text{mu}}(E) \propto n(E) \ w_{\text{mu}}(E) = \text{const}.
\] (8)

This is because the simulation generates a 1D random walk in the energy space, allowing itself to escape from any local minimum. Since a large range of energies are sampled, one can use the reweighting techniques \[23\] to calculate thermodynamic quantities over a wide range of temperatures \(T\) by

\[
\langle A \rangle_T = \frac{\int dx \ A(x) \ w^{-1}(E(x)) \ e^{-\beta E(x)}}{\int dx \ w^{-1}(E(x)) \ e^{-\beta E(x)}},
\] (9)

where \(x\) stands for configurations.

Unlike in the case of canonical simulations the weights

\[
w(E) = n^{-1}(E) = e^{-S(E)}
\] (10)

are not a priori known. Instead estimators for these weights have to be determined. This is often done by an iterative procedure in which for reasons of numerical stability Eq. \[10\] is replaced by

\[
w(E) = e^{-\beta(E)E - \alpha(E)}.
\] (11)

The multicanonical parameters \(\beta(E)\) and \(\alpha(E)\) are defined through

\[
\beta(E) = \frac{S(E') - S(E)}{E' - E} \quad \text{and} \quad \alpha(E) = \begin{cases} 0, & E \geq E_{\text{max}} \\ \alpha(E') + (\beta(E') - \beta(E))E', & E < E_{\text{max}} \end{cases}
\] (12)
with $E$ and $E'$ adjacent bins in the array $S(E)$. The $\beta(E)$ are then iteratively updated by the relation

$$\beta^{i+1}(E) = \beta^i(E) + g_0(E) \cdot \left( \ln H^i(E') - \ln H^i(E) \right) / (E' - E),$$  \hspace{1cm} (13)$$

in which $H^i(E)$ is the histogram of the $i$-th run (and $H(E) \geq 1$). In Ref. \cite{24} the factor $g_0(E)$ in Eq. 13 was defined through

$$g_0(E) = \frac{\hat{g}^i(E)}{\hat{g}^i(E) + \sum_{j=1}^{i-1} \hat{g}^j(E)} \quad \text{with} \quad \hat{g}^i(E) = \frac{H^i(E') \cdot H^i(E)}{H^i(E') + H^i(E)}. \hspace{1cm} (14)$$

The above relation assumes that the histogram $H(E)$ counts independent events which is in general not true. Hence, it is more appropriate and leads to a faster convergence of $\beta(E)$ if the array $\hat{g}^i(E)$ in Eq. 14 is instead defined by

$$\hat{g}^i(E) = \frac{K^i(E')K^i(E)}{K^i(E') + K^i(E)} \hspace{1cm} (15)$$

where the auxiliary array $K(E)$ now counts only the number of independent visits at energy $E$.

With the above described iterative procedure we needed 200,000 sweeps for the weight factor calculations. All thermodynamic quantities were then estimated from one production run of 1,000,000 Monte Carlo sweeps starting from a random initial conformation, i.e. without introducing any bias.

3 Results and Discussion

In previous gas-phase simulations of poly-alanine \cite{3, 4, 5, 22} we observed at $T = 430 \, K$ a pronounced transition between a high-temperature phase dominated by disordered coil structures and an ordered phase with single, extended helices. A natural order parameter for this helix-coil transition is the average number of residues in the oligomer which are part of an $\alpha$-helix. Following earlier work \cite{22} we define a residue as helical if the pair of backbone dihedral angles $\phi, \psi$ takes a value in the range $(-70 \pm 20, -37 \pm 20)$. In Fig. 1a this order parameter is displayed as function of temperature for a gas-phase simulation (GP) of Ala$_{10}$ and simulations with the various solvation terms. Fig. 1b shows the corresponding plots for the susceptibility $\chi(T)$ defined by

$$\chi(T) = \langle n_{H}^2(T) \rangle - \langle n_{H}(T) \rangle^2. \hspace{1cm} (16)$$
In Fig. 1a and 1b the curves, representing the various simulations, fall into three groups. For the case where the protein-solvent interaction was approximated by a distance-dependent permittivity (DDE), both \(< n_H >\) and \(\chi\) have a similar temperature dependence than is observed for poly-alanine in gas-phase simulations (GP). However, the transition temperature \(T_c\) is shifted from \(T = 435 \pm 20\) K (gas-phase) to a higher value \(T = 495 \pm 20\). This temperature was determined from the maximum of the susceptibility \(\chi(T)\) in Fig. 1b and is listed in table 1. To the same group belong the simulations in which the solvation energy was approximated by a solvent accessible surface term with either the OONS [9] or SCH [12] parameter set. In both cases susceptibility \(\chi\) and order parameter \(< n_H(T) >\) show also a temperature dependence similar to the one of gas-phase simulations. Only now, the transition temperature \(T_c\) is shifted to lower temperatures. The corresponding transition temperatures can be again determined from the positions of the maximum in \(\chi(T)\) and are also listed in table 1. The shift towards lower temperatures was one of the main results reported in Refs. [7, 8] for simulations with the OONS solvation energy, and our \(T_c = 345 \pm 20\) K agrees well with their value \(T_c = 340\) K (no errors quoted) in Refs. [7, 8].

A somehow different behavior is observed in the simulation where the protein-water interaction was approximated by a solvent accessible surface term relying on the W92 [11] parameter set. Here, the form of \(< n_H >\) indicates only partial helix formation and occurs only at much lower temperatures. The susceptibility \(\chi(T)\) in Fig. 1b gives no indication for a helix-coil transition. For this reason no value of \(T_c\) is listed for the W92 parameter set in table 1. Instead, we observe in Fig. 2 for this case at low temperatures even the appearance of residues whose backbone dihedral angles \(\phi, \psi\) take values typical for a \(\beta\)-sheet \((-150 \pm 30, 150 \pm 30)\).

Yet another behavior is observed in simulations where the solvation energy of Eq. 4 is evaluated by means of the JRF parameter set. No formation of helices or sheets is observed in Figs. 1 and 2. Since no transition temperature can be determined, we do not list a value of \(T_c\) for the JRF parameter set in table 1.

The same grouping can be found in Fig. 3a-f where we display various energy terms as a function of temperature. In these figures we have shifted the solvation energies and the partial ECEPP/2 energies \(E_C, E_{LJ}, E_{HB}\) and \(E_{tor}\) of Eq. 5 by a constant term such that we have for all solvation models at \(T = 1000\) K \(E_{sol} = 0\) and \(E_C = E_{LJ} = E_{HB} = E_{tor} = 0\). Such a shift by an irrelevant constant allows a better comparison of the different simulations. The average total energy \(< E_{tot} >\) which
is the sum of intramolecular potential energy $E_{ECEP/2}$ and the solvation energy $E_{sol}$, is displayed in Fig. 3a. We observe again that simulations with the parameters sets OONS and SCH, and such with distant dependent permittivity (DDE), have a similar temperature dependence as gas phase simulations (GP). On the other hand, in simulations relying on the W92 parameter set, the energy varies less with temperature and is at low temperatures considerably higher than in the simulations with other solvation energy terms. Finally, the energy in simulations with the JRF parameter set is an almost linear function of temperature and is especially at high temperatures much lower than the energies found in gas phase simulations.

The dissimilar behavior of energy for simulations with different solvation terms is even more obvious in Fig. 3b where the average intramolecular energy $E_{ECEP/2}$ is drawn. While this energy term decreases between 1000 K and 150 K by $\approx 50$ Kcal/mol (with most of that change, $\approx 30$ Kcal/mol, happening around the respective transition temperature $T_c$) in gas-phase simulations (GP) and in simulations with OONS, SCH and DDE solvation terms, it changes in the same temperature interval only by $\approx 20$ Kcal/mol in simulations utilizing the JRF or W92 parameter sets. Since for these two parameter sets also no or only little helix formation was observed it seems likely that the formation of helices is related to the large gain in potential energy observed for GP, OONS, SCH and DDE simulations. This gain in potential energy is in part due to the formation of hydrogen bonds between a residue and the fourth following one in the polypeptide chain which stabilize an $\alpha$-helix. Fig. 3c displays the average hydrogen-bonding energy $<E_{HB}>$ of Eq. 3 as a function of temperature and one can clearly see the gain in energy for the GP, DDE, OONS and SCH simulations at the respective helix-coil transition temperatures of table 1. No such gain is observed in W92 and JRF simulations where also no helix formation was found. A similar gain in energy with helix formations in gas-phase and simulations with DDE, OONS and SCH solvent representations is also observed for the average Lennard-Jones energy $<E_{LJ}>$ and the electrostatic energy $<E_C>$ displayed in Fig. 3d and 3e, respectively. Note also in Fig. 3e the large gain in $E_C$ for DDE at the helix-coil transition temperature which additionally stabilizes the $\alpha$-helix in this model.

A complementary picture is found in Fig. 3f where the solvation energy $E_{sol}$ is shown as a function of temperature. The observed helix formation in gas phase simulations and such with OONS, SCH and DDE solvent representations is correlated with an increases of the solvation energies by $\approx 5$ Kcal/mol. On the other hand,
in simulations with the W92 and JRF parameter sets, for which no helix-formation was observed in Fig. 1, $E_{\text{sol}}$ decreases with temperature. This decrease is only $\approx 5$ kcal/mol for W92, but it is much larger (of order 30 kcal/mol) in the case of JRF where the solvation energy is the dominant term.

The effects of the dominant solvation term in simulations with the JRF parameter set can also be seen in Fig. 4. In this figure the average radius of gyration, a measure for the compactness of configurations, is shown as a function temperature. One can see that this quantity changes little with temperature for the JRF data. However, its value is over the whole temperature range considerably smaller than observed in the other simulations. This indicates that the JRF solvation term favors already at high temperatures compact configurations, and that the pressure towards compact structure is such that the more elongated helices cannot be formed. Note however, that the tendency towards compact configurations does not lead to a lower Lennard-Jones energy $E_{\text{LJ}}$ as one would expect. Fig. 3d indicates that $<E_{\text{LJ}}>$ is at low temperatures in JRF simulations even larger than in GP, DDE, OONS and SCG simulations where helix-formation was observed. The tendency towards compact structures in JRF simulations may be due to the fact that JRF parameter set was developed from minimum energy (i.e. compact) conformations of peptides (the low-energy conformations of 13 tetrapeptides derived by NMR studies [10]), and therefore this parameter set may have an intrinsic bias towards compact structures.

On the other hand, the W92 parameter set was developed from measurements of free energies of amino acid side chain analogs from vapor to water [21]. The parameters for this set are negative for all atoms except carbon meaning that the nitrogen, oxygen and sulfur atoms are considered hydrophilic, i.e. favoring solvent exposure. This explains not only the small solvation energies observed for this parameter set in Fig. 3f, but also why in Fig. 4 the radius of gyration is consistently larger for this parameter set than for the others indicating that extended configurations are favored with this parameter set. This bias towards extended structures limits again the formation of $\alpha$-helices.

While the OONS parameter set was derived from experimental free energies of gas-to-water transfer of small aliphatic and aromatic molecules, the SCH is not directly based on experimental free energy data. Instead, it was developed as an optimized parameter set to complement the CHARMM force field [22]. In both parameter sets the hydrophobic character of the carbon atoms is increased and the hydrophilic character of uncharge oxygen and nitrogen atoms decreased resulting
into the large solvation energies of these two parameter sets (when compared with the one of the W92 parameter set) that one observes in Fig. 3f. The OONS and SCH solvation energies again favor extended structures (the radius of gyration has larger values than found in gas-phase simulations), however, the interplay of solvation energies and intramolecular ECEPP/2 energy is such that the radius of gyration (and consequently the compactness) of polyalanine configurations as a function of temperature shows a similar behavior as the gas-phase simulation. The same is true for the DDE simulation where the protein-solvent interaction was approximated by a distance-dependent permittivity.

Our results demonstrate that the helix formation is due to the gain in potential (intramolecular) energy while (with the exception of the JRF parameter set) the solvent-accessible surface terms favor extended peptide configurations. Table 2 summarizes the differences in total energy $\Delta E_{tot}$, solvation energy $\Delta E_{sol}$, potential energy $\Delta E_{ECEPP/2}$, and the partial energies $\Delta E_C$, $\Delta E_{LJ}$, $\Delta E_{HB}$ and $\Delta E_{tor}$ between complete helical configurations (all residues with exception of the terminal ones are part of an $\alpha$-helix) and coil configurations at temperature $T = 300$ K for gas-phase, DDE OONS and SCH simulations. Note, that the intramolecular energy differences $\Delta E_{ECEPP/2}$ of gas-phase, OONS and SCH simulations have within their error bars the same values. For simulations with the W92 parameter set the longest found helix consists of 6 consecutive residues. Hence, we measured for this case only the energy difference between configurations with at least three consecutive helical residues (i.e. one turn of an $\alpha$-helix) and coil configurations. This modified definition of the energy differences is also the reason for the smaller value of $\Delta E_{ECEPP/2}$ listed for W92 in table 2. We do not list energy differences for the JRF parameter set since no helices were found in simulations utilizing this parameter set.

Note that in simulations with distant dependent permittivity (DDE) helices are energetically more favored than in the gas-phase simulations. This is due to the increased contribution from the Coulomb term $E_C$ as one can also see in Fig. 3e. The larger energy gap between helical and coil conformations (when compared with gas-phase simulations) explains why the transition temperature is higher in DDE simulations than in gas-phase simulations.

For the OONS and the SCH parameter set the solvation energy difference $\Delta E_{sol}$ is positive (indicating that coil structures are energetically favored), but its magnitude is only approximately half that of the potential energy difference $\Delta E_{ECEPP/2}$. Hence, there is still an overall energetic gain connected with helix formation. However,
in both cases the total energy difference between helical and coil configurations is reduced by the solvation energy when compared with the gas-phase simulation. This reduction of the energy gap leads to the lower transition temperatures observed in OONS and SCH simulations.

On the other hand, for the W92 parameter set we find that $\Delta E_{ECCP/2}$ and $\Delta E_{sol}$ are of same magnitude so that helical configurations are not or only weakly energetically favored. This is consistent with our results in Fig. 1a and 1b where we find at $T = 280$ K a high average helicity in OONS and SCH simulations but only a small value of $< n_H >$ and no indications for a helix-coil transition in W92 simulations. An evaluation of energy differences was not possible for simulations with the JRF parameter set since no helices were found.

The above results indicate that the existence and characteristics of the helix-coil transition in polyalanine depend strong on the details of the solvent representation. In order to evaluate the validity of the different solvent models one has to compare the numerical results with experimental data. For this purpose we have calculated the helix propagation parameter $s$ which was also determined by experiments [28, 29]. According to the Zimm-Bragg model [27] the average number of helical residues $< n >$ and the average length $< \ell >$ of a helical segment are given for large number of residues $N$ by

$$
\frac{< n >}{N} = \frac{1}{2} - \frac{1 - s}{2\sqrt{(1 - s)^2 + 4s\sigma}},
$$

$$
< \ell > = 1 + \frac{2s}{1 - s + \sqrt{(1 - s)^2 + 4s\sigma}},
$$

where $s$ is the helix propagation parameter and $\sigma$ the nucleation parameter of the Zimm-Bragg model. From these equations with the values of $< n >/N$ and $< \ell >$ calculated from the multicanonical production runs, we have calculated $s$ at temperature $T = 280$ K for gas-phase and the different solvation models. Our values are summarized in table 3 which also lists our $\sigma$ values. Our results for gas-phase, DDE and OONS simulations are in agreement with the experimental results of Ref. [25] where they list values of $s$(Ala) between 1.5 and 2.19. On the other hand, the $s$ value obtained in the SCH simulation agrees well with the one obtained by the host-guest technique of Ref. [28]. However, the $s$ values which were obtained in W92 or JRF simulations do not agree with either of the experimental data. Hence, we conclude that the W92 and JRF parameter sets are not appropriate solvation models in simulations of polyalanine. Otherwise, the variation in the experimental data is
too large to give indications whether one of the remaining solvent representations (DDE, OONS, SCH or even no solvent at all (GP)) is preferable over the others.

4 Conclusions

We have performed multicanonical simulations of polyalanine. The intramolecular forces were modeled by the ECEPP/2 force field and various approximations for the solvation energy were studied. We observed that whether a helix-coil transition is observed for poly-alanine, and at what temperature, depends strongly on the chosen approximation for the protein-solvent interaction. Our results demonstrate both the importance (and need) of including solvation terms into protein simulations and the difficulties in choosing an adequate representation of the protein-water interactions. Especially when using the solvent-accessible surface approach, it seems necessary to carefully choose a parameter set that is suitable for the problem under consideration. Use of a specific parameter set without further justification could otherwise generate misleading results.

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Tables:

Table 1: Transition temperatures for the helix-coil transition in ALA$_{10}$ as obtained from gas-phase simulations and simulations with various solvent representations. All results rely on multicanonical simulations of 1,000,000 Monte Carlo sweeps each.

| Model | $T_c$   |
|-------|---------|
| GP    | 435(20) |
| DDE   | 495(20) |
| OONS  | 345(15) |
| SCH   | 285(25) |
| W92   | -       |
| JRF   | -       |

Table 2: Energy differences between helical and configurations (see text) at $T = 280$ K as measured in gas-phase simulations and simulations with various solvent representations. All results rely on multicanonical simulations of 1,000,000 Monte Carlo sweeps of ALA$_{10}$ for each case.

| Model | $\Delta E_{\text{tot}}$ | $\Delta E_{\text{sol}}$ | $\Delta E_{\text{ECEPP/2}}$ | $\Delta E_C$ | $\Delta E_{LJ}$ | $\Delta E_{HB}$ | $\Delta E_{\text{tor}}$ |
|-------|------------------------|------------------------|-----------------------------|--------------|----------------|----------------|-------------------|
| GP    | $-16.9(1)$             | -                      | $-16.9(1)$                 | 0.4(3)       | $-12.1(1)$     | $-4.3(3)$     | $-0.8(1)$        |
| DDE   | $-17.9(6)$             | -                      | $-17.9(6)$                 | $-3.6(2)$    | $-10.1(4)$     | $-3.9(2)$     | $-0.3(1)$        |
| OONS  | $-11.3(9)$             | 4.1(3)                 | $-15.4(6)$                 | $-0.2(1)$    | $-10.7(4)$     | $-4.1(1)$     | $-0.4(1)$        |
| SCH   | $-7.1(5)$              | 8.7(1)                 | $-15.8(5)$                 | 0.7(3)       | $-11.2(2)$     | $-4.6(3)$     | $-0.7(1)$        |
| W92   | $-0.7(7)$              | 5.6(6)                 | $-6.3(1.1)$                | 0.8(1)       | $-5.8(9)$      | $-1.0(2)$     | $-0.3(1)$        |
| JRF   | -                      | -                      | -                           | -            | -              | -              | -                 |
Table 3: Helix propagation parameter $s$ and nucleation parameter $\sigma$ at $T = 280$ K for Ala$_{10}$ as measured in gas-phase simulations and simulations with various solvent representations. All results rely on multicanonical simulations of 1,000,000 Monte Carlo sweeps for each case.

| Model | $s$     | $\sigma$ |
|-------|---------|----------|
| GP    | 1.67(9) | 0.15(1)  |
| DDE   | 1.78(12)| 0.15(1)  |
| OONS  | 1.31(15)| 0.13(1)  |
| SCH   | 1.02(15)| 0.11(2)  |
| W92   | $\approx 0$ | $> 1$    |
| JRF   | $\approx 0$ | $> 1$    |
Figure Captions:

**Fig. 1** Temperature dependence of (a) the average number $<n_H>$ of helical residues and (b) the susceptibility $\chi(T)$ for ALA$_{10}$ as calculated from a gas-phase simulation and from simulations with various solvation energy terms. All results rely on multicanonical simulations of 1,000,000 Monte Carlo sweeps each.

**Fig. 2** Temperature dependence of the average number $<n_B>$ of residues whose backbone dihedral angles $\phi, \psi$ take values as typically found in $\beta$-sheets. Results from a gas-phase simulation and such with various solvation terms are presented for ALA$_{10}$. All data rely on multicanonical simulations of 1,000,000 Monte Carlo sweeps.

**Fig. 3** Temperature dependence of (a) the total energy $<E_{total} = E_{ECEEP/2} + E_{sol}>$, (b) the intramolecular energy $<E_{ECEPP/2}>$, (c) the hydrogen-bonding energy $<E_{HB}>$, (d) Lennard-Jones energy $<E_{LJ}>$, (e) Coulomb energy $<E_{C}>$, and (f) the solvation energy $<E_{sol}>$ as calculated from a gas-phase simulation and from simulations with various solvation energy terms. All results rely on multicanonical simulations of ALA$_{10}$ with 1,000,000 Monte Carlo sweeps for each case.

**Fig. 4** Temperature dependence of the average radius-of-gyration $<R_{gg}>$ as measured in gas-phase simulations and simulations with various solvent representations. All data rely on multicanonical simulations of 1,000,000 Monte Carlo sweeps.
Number of helical residues

\langle n_H(T) \rangle

\begin{align*}
\text{GP} & \\
\text{DDE} & \\
\text{OONS} & \\
\text{SCH} & \\
\text{W92} & \\
\text{JRF} & 
\end{align*}

\(T\ [K]\)
Susceptibility

\[ \langle \chi(T) \rangle \]

Temperature \( T [K] \)

- GP
- DDE
- OONS
- SCH
- W92
- JRF
ECEPP/2 Energy

\[ \langle E \rangle (T) \ \text{[Kcal/Mol]} \]

\[ T \ \text{[K]} \]

GP
DDE
OONS
SCH
W92
JRF
Lennard-Jones Energy Term

\[ \langle E \rangle (T) \text{ [Kcal/Mol]} \]

- \( \langle E \rangle \) vs. temperature \( T \) in Kelvin (K).

Legend:
- GP
- DDE
- OONS
- SCH
- W92
- JRF

Temperature range: 200 to 1000 K.

Energy range: -35 to 0 Kcal/Mol.
Electrostatic Energy Term

\[ \langle E \rangle (T) \text{ [Kcal/Mol]} \]

- Graph showing the electrostatic energy term \( \langle E \rangle (T) \) as a function of temperature \( T \) in Kelvin (K).
- Different lines represent different computational methods:
  - GP
  - DDE
  - OONS
  - SCH
  - W92
  - JRF

The y-axis represents the electrostatic energy in Kcal/Mol, ranging from -7 to 0.

The x-axis represents the temperature in Kelvin (K), ranging from 200 to 1000.
 Radius of gyration

\langle r_GY(T) \rangle

T [K]

\begin{align*}
& \text{GP} \\
& \text{DDE} \\
& \text{OONS} \\
& \text{SCH} \\
& \text{W92} \\
& \text{JRF}
\end{align*}