Analysis of Activity Dependent Development of Topographic Maps in Neural Field Theory with Short Time Scale Dependent Plasticity.

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Abstract

Topographic maps are a brain structure connecting pre-synaptic and post-synaptic brain regions. Hebbian-based plasticity mechanisms working in conjunction with spontaneous patterns of neural activity generated in the pre-synaptic regions play a critical role in appropriate topographic development. Studies performed in mouse have shown that these spontaneous patterns can exhibit complex spatial-temporal structures which existing models cannot incorporate. Neural field theories are appropriate modelling paradigms for topographic systems due to the dense nature of the connections between regions and can be augmented with a plasticity rule general enough to capture complex time-varying structures.

We propose a theoretical framework for studying the development of topography in the context of complex spatial-temporal activity feed-forward from the pre-synaptic to post-synaptic regions. Analysis of the model leads to an analytic solution corroborating the conclusion that activity can drive the refinement of topographic projections. The analysis also suggests that biological noise is used in the development of topography to stabilise the dynamics. MCMC simulations are used to analyse and understand the differences in topographic refinement between wild-type and the $\beta^2$ knock-out mutant in mice. The time scale of the synaptic plasticity window is estimated as 0.56 seconds in this context with a model fit of $R^2 = 0.81$.

Keywords: Topographic maps; Neural Field theory; STDP; Plasticity; Spontaneous activity; Hebbian dynamics; Neural organisation.

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1 Introduction

A topographic map is a ubiquitous brain structure which connects two brain regions: a pre-synaptic region and post-synaptic region [48]. The structure is defined by the relationship that cells that are physically neighbouring in the pre-synaptic region will

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connect to physically neighbouring cells in the post-synaptic region and is the simplest instance of a topological map [7]. Topographic maps have been shown to have remarkable regeneration and re-organisational properties but this study will focus only on their development [8, 32, 35, 24]. Historically, topographic development was thought to be mediated by either Hebbian activity-based mechanisms, or chemotactic signalling mechanisms but these now are thought to more typically work in tandem [10].

The dense feed-forward connectivity pattern present in topographic systems make neural field theories (NFT) an attractive paradigm for modelling electrical activity patterns in topographic systems. An NFT is a continuum model where the spiking activity of many neural inputs are averaged into a smoothly varying function over temporal and spatial locations. A theory of topographic development was proposed for an NFT which relied on static inputs in the pre-synaptic region resulting in activity patterns in the post-synaptic region stabilising to be time-independent and thus allowing a simple Hebbian plasticity rule to be applied [4]. The requirement for activity to stabilise before updating weight is also a feature of more general cortical map plasticity models [43, 6]. A more recent study used an NFT to model topography in the somatosensory cortex under thalamocortical plasticity using Oja’s rule [15]. The assumption of static inputs limits the range of biological systems for which the theory developed in these works can apply in development.

A proposed candidate model organism is the mouse retinotopic map: the set of connections that map retinal cells in the eye to cells in the superior colliculus (SC) [23, 39]. This is distinct from other topographic projections such as somatosensory and tonotopic maps [25]. The mouse develops topography using three mechanisms: chemotaxis, competition, and activity based refinement [30, 10]. The activity component of development involves three stages of spontaneously generated retinal waves which are thought to refine a coarse topography of dendritic arbours (grown from afferent neurons which are guided topographically by a combination of chemotaxis and competitive interactions) down into a precise point-to-point mapping [10, 5, 28]. Disruptions to the patterning of these waves have been explored by knocking out the nicotinic-acetylcholine receptor $\beta_2$ which generates fast-spreading waves and thus a hyper-correlation – where neurons are correlated at a far greater inter-neuron distance than in wild type – between any two given retinal cells [42]. The effect of the $\beta_2$ knock-out is to reduce the precision of the resulting topographic map: the receptive field of a given SC location is large with respect to wild-type [33, 30, 11].

Modelling efforts in this field have focused recently on predicting map structure of various mutants and a unified model of chemotaxis, activity, competitive mechanisms was shown to give the best account of the data [22, 46, 45, 47]. The mutants examined were predominantly genetic perturbations of the chemical gradients and therefore activity was not considered as a major focus. These models by construction are unable to capture the various spatio-temporal statistics of the retinal waves condensing them all into a single correlation measure as a function of SC-distance; a corollary is that they have not been able to reproduce the effect of the $\beta_2$ knock-out when the correlation function is adjusted to match the knock-out [27]. While historical models have allowed for the incorporation of spatial patterning in the input stimulus, they do not consider time variations in stimulus at a time-scale below that of plasticity implicitly assuming all transient neuronal information (such as spatio-temporally patterned stimulus waves) is averaged out [49, 26, 43]. Recent efforts in a separate unified model which can incorporate dynamic activity were not able to quantitatively account for the $\beta_2$ mutant data and are too computationally demanding for rigorous statistical analysis [19]. There is a need for theory which can analyse and predict the effects of time-varying stimuli on the organisational structure of maps.
In this paper we aim to develop theory for modelling the development of topographic systems which can incorporate complex spatial-temporal patterns of activity, such as those seen in mouse. A candidate theoretical framework of Hebbian-based plasticity that can incorporate time-signatures of activity, spike timing dependent plasticity (STDP), has been developed for NFT [37, 1]. The framework is continuous, rather than discrete, which allows us to investigate synaptic efficacy between locations rather than modelling individual synapses. We shall demonstrate that NFT can support the refinement and establishment of precise topography via waves of propagating activity and biologically reasonable Hebbian learning rules and therefore establish it as a useful model to study the development of topographic systems. Moreover, we will validate the model against the β2 knock-out and make predictions about the time-scale on which the Hebbian activity operates. A glossary of symbols that will be used throughout the paper is shown in Table 1.

### 2 Model

We will choose a simple model architecture that closely imitates the systems of interest: input from a continuous pre-synaptic field of nerve cells stimulates activity in a continuous post-synaptic field of nerve cells via a collection of feed-forward connections. These feed-forward connections will evolve under a plasticity rule governed by the spatio-temporal relations between the input and induced activity in the pre-synaptic and post-synaptic fields respectively. The activity in the post-synaptic field will be supported by inhibitory and excitatory sets of isotropic recurrent (or lateral) connections which, for simplicity, we shall assume to be static; for a description of non-isotropic recurrent kernels refer to [21, 38]. Changes in the feed-forward connections are dictated by firing activity in the pre-synaptic and post-synaptic fields. The activity dynamics in the post-synaptic field will be modelled by a neural field equation which couples a membrane potential and firing activity spatio-temporally. The pre-synaptic field activity could be modelled the same way but because there is no feed-back from the post-synaptic field it is sufficient to simply instantiate it which can be motivated by experimental spiking data [31]. The model architecture is summarised in Figure 1 and we shall now explicitly lay out the details of the model.

### Representation of Topography

We need to establish what we mean by topography in the continuous sense. We aim to preserve two things: the neighbourhood projection, and
Figure 1: The connections and directionality of the model: activity is feed-forward from the pre-synaptic region by the structure of interest and is spatial-temporally propagated by a time-differential operator and spatial convolution of inhibitory and excitatory recurrent connections. We show cartoons of typical propagating activity patterns and recurrent connections but not feed-forward connections as determining these are the object of this study. The generated signal in the post-synaptic region and the driving signal in the pre-synaptic region are then convolved with a plasticity window to inform the synaptic changes on a slow time scale which is indicated by the variable $T = \epsilon t$ for some small $\epsilon$.

the excitatory feed-forward nature of the network. To preserve the neighbour-neighbour relation the connections, here referred to as a synaptic distribution, labelled $S$, and measured in synapses per mm$^2$, should take the form:

$$S(x, y, T) = S(|x - p(y) - \rho|, T),$$

(2.1)

where $p(y)$ is some monotonically increasing function and $\rho$ is some constant to indicate that a coordinate shift still permits a topographic mapping. The excitatory feed-forward nature means that a patch of activation in the pre-synaptic field should activate a local patch of the post-synaptic field associated with its topographically projected location. Therefore, $S$ should decay quickly at infinity, be positive at the topographically projected location, and have a finite (small) radius at which it transitions to being negative. Alternatively, it can be strictly positive but quickly decaying such that it never overpowers the recurrent inhibitory connections; see Figure 2.

**Neural Field Theory** We shall choose the NFT formulation proposed by Amari [4] which considers both excitatory and inhibitory connections in the same kernel $W$. We shall consider a kernel $S$ that also couples the pre-synaptic and post-synaptic regions.
Figure 2: Two examples of topographic organisation using a Wizard hat style function: a) shows a linear relationship between axes and for while b) shows a cubic relationship between axes. Both are topographic but a) has an even representation of the pre-synaptic field across the post-synaptic field while b) compresses the representation at the boundary and enlarges the interior.

It is this kernel in which we aim to demonstrate the evolution of topography. We shall denote the electrical activity, measured in millivolts (mV), of the pre-synaptic field by \( a(x,t) \) and in the post-synaptic field by \( u(x,t) \), and choose the firing rate function to be a sigmoid-logistic function:

\[
Q(u) = \frac{Q_{\text{max}}}{1 + \exp(-\beta(u - \theta))},
\]

where \( \beta \) and \( \theta \) dictate the steepness of the curve and the threshold respectively, and \( Q_{\text{max}} \) is the maximal firing rate; the units of each are \( \text{mV}^{-1}, \text{mV}, \) and spikes per second and can be found in Table 2. The activity dynamics are then governed by the internal dynamics mediated by \( W \) and the input provided through the pre-synaptic field, \( Q(a) \), and its transfer through \( S \):

\[
\frac{d}{dt} u(x,t) + \tau \frac{\partial u(x,t)}{\partial t} = \int_{-\infty}^{\infty} W(x,x')Q(u(x',t))dx' = \int_{-\infty}^{\infty} S(x,y,T)Q(a(y,t))dy.
\]

Note that the time variable \( T \) is on a much slower time scale which is realised by setting \( t = \epsilon T \) for \( 0 < \epsilon \ll 1 \). For the purposes of solving (2.3) these connections can be considered effectively constant. We assume for simplicity that the recurrent connections \( W \) remain constant throughout the course of synaptic development and are homogenous.

Following Robinson [37] a plasticity window is defined as a rapidly decaying envelope \( H \) that weights the cross-correlation of the input and response signals in a population in the same fashion as biologically-inspired plasticity rules weight individual spikes of a neuron [37]. These plasticity windows have been observed in several organisms and brain regions; a typical window has a time constant on the order of 10s of milliseconds but have been observed to be on the order of 10s of minutes [17, 52, 3, 29, 12]. The average synaptic dynamics are given by averaging over a time-window which is longer than the time-scale of the plasticity window and of the inverse frequencies of the forcing and the response stimuli but shorter than any long term plasticity changes:

\[
\tau \frac{dS(x,y,T)}{dT} = \int_{-\infty}^{\infty} \langle U(x,T + s)H(s)A(y,s) \rangle ds,
\]
where $U = Q(u)$, $A = Q(a)$ (the firing rates of the post-synaptic and pre-synaptic populations respectively), $\langle \cdot \rangle$ denotes averaging, and $\tau'$ is the time-scale of synaptic dynamics. In the case of no electrical activity present in the pre-synaptic field there will be a constant level of spontaneous firing $A$ inducing an electrical activity and firing rate $U$ which in turn will lead to run-away synaptic dynamics. We are interested in the dynamics of the average rate of synaptic change and the expected synaptic values; in later sections this will be taken as an adiabatic expansion and averaging over stimulus input locations. Therefore, the above equation should include a noise term $\eta$, which we shall take to have a strength $\kappa$, to incorporate the small deviations of spontaneous activity:

$$
\tau' \frac{dS(x,y,T)}{dT} = \int_{-\infty}^{\infty} (U(x, T + s)H(s)A(y, s))ds + \kappa \eta(x, y, t). \quad (2.5)
$$

**Regularisation** Several regularisation rules have been posed to stabilise these unstable Hebbian dynamics and are broadly classified in the form of subtractive and multiplicative rules [1]. In this study we choose a subtractive normalisation rule to stabilise the dynamics, assuming there is some atrophic factor to regulate the unbounded growth of synapses, governed by parameter $\lambda$, released at each location:

$$
\tau' \frac{dS(x,y,T)}{dT} + \lambda S(x, y, T) = \int_{-\infty}^{\infty} (U(x, T + s)H(s)A(y, s))ds + \kappa \eta(x, y, t). \quad (2.6)
$$

The idea of a synaptic decay on the basis of metabolic demands has also been introduced in a study of organisational behaviour in V1 [50]. We shall study the dynamics of (2.6) for the remainder of this text.

**Perturbations** We shall assume that in the absence of forcing activity that the post-synaptic field relaxes to a constant solution i.e. there is a constant level of spontaneous firing in the pre-synaptic and post-synaptic fields; note that this is not necessarily the case [13]. We then assume that all activity dynamics are small perturbations from these constant rates. Furthermore, if one makes the assumption that the firing rates can be expressed as perturbations from a baseline firing rate, $U(x, t) = U_0 + \delta U(x, t)$ and $A(x, t) = A_0 + \delta A(x, t)$, then taking Fourier transforms the average change in plasticity in the un-regularised dynamics can be expressed as:

$$
\frac{1}{2\pi} \int_{-\infty}^{\infty} \delta \hat{U}(x, \omega) \hat{H}(\omega) \ast \hat{\delta A}(y, \omega) d\omega, \quad (2.7)
$$

where $\hat{\cdot}$ denotes the Fourier transform, and $\hat{\cdot}^*$ denotes complex conjugation [37].

**Input Stimulus** We shall consider two classes of input stimulus: mono-directional and bi-directional (radial) waves. Mono-directional waves propagate either to the left/right at speed $c$ starting at some time $t_0$ and some starting position $y_0$ finally finishing at some time $t_1$. We note that these terms are rooted in a two dimensional consideration of the problem. A mono-directional wave might travel along a single radial angle whilst a radial wave travels isotropically. These choices allow for a description of the waves observed in the retina [31, 42, 2]. Of the two the mono-directional wave is the most appropriate model but the bidirectional wave is an equivalent but analytically preferable case as we show in Section 3. Letting $r(y, t) = y - ct - y_0$, these inputs accordingly take the form:

$$
a(y, t) = (\Theta(t - t_0) - \Theta(t - t_1)) h(r(y, t)). \quad (2.8)
$$
Radial inputs are similar, simply propagating in both directions:

\[ a(y, t) = \frac{(\Theta(t - t_0) - \Theta(t - t_1))(h(r(y, t)) + h(r(y, -t)))}{2}. \]  

(2.9)

In both cases \( h \) is used to denote the shape of the propagating wave-form. The choice of \( h \) is left to be general but can be thought of as a travelling Gaussian wave-packet. A function may be approximated by a linear sum of appropriately weighted Gaussian’s and so this forms a basis set and we will consider the simple case in Section 3.1.

**Plasticity Windows** There are two general forms of plasticity considered: time symmetric and time asymmetric plasticity. Time symmetric plasticity, also called Correlation Dependent Plasticity (CDP), means that connections are strengthened by spikes that are separated by short times and weakened by medium-long time separated spikes, but in which the ordering of the spikes is not important. Time asymmetric plasticity, or STDP, means that not only does the temporal closeness of pre-synaptic and post-synaptic spikes matter but the ordering in which they occur: post-synaptic firing that occurs before pre-synaptic firing weakens the connection and vice-versa. A canonical form of these two rules expressed as a plasticity envelope is given by:

\[
H(s) = \begin{cases} 
A_+ \exp\left(-\frac{s}{t_p}\right) & s \geq 0 \\
A_- \exp\left(\frac{s}{t_p}\right) & s < 0 
\end{cases}
\]  

(2.10)

where \( A_- = A_+ \) for CDP and \(-A_- = A_+ \) for STDP, and \( t_p \) is the time-scale of the plasticity [1]. The Fourier transforms of these learning rules are:

\[
\hat{H}_{CDP}(\omega) = \frac{2A_+}{1 + \omega^2t_p^2} 
\]  

(2.11)

\[
\hat{H}_{STDP}(\omega) = \frac{2A_+\omega t_p}{1 + \omega^2t_p^2}. 
\]  

(2.12)

In summary, a membrane signal is generated in the post-synaptic region on a fast-time scale which is supported by recurrent connections and generated by input from a pre-synaptic region. The spatial-temporal patterns of the pre-synaptic and post-synaptic activity then inform synaptic changes between the two regions on a slow time scale in accordance with a plasticity rule.

### 3 Analysis

We shall make the assumption that our connectivity kernels, pre-synaptic stimuli, and post-synaptic activity and firing rates are elements of Schwartz space i.e. the functions and derivatives that define these rates decay quickly at long range and they are localised. This assumption is made to ensure bio-physical realism. Connectivity kernels typically have short-range and long-range interactions but they do not interact at all with very distal connections and their functions must accordingly decay at infinity. Similarly, due to these recurrent connectivity kernels, electrical signals only seem to be able to support themselves on finite distances and they too must accordingly decay. The assumption of Schwartz functions ensures that we can take Fourier transforms and makes formulating our problem in Fourier space desirable.

**Approximating Input Stimulus** The inputs that we specified earlier are biologically realistic but will become more tractable if we are able to remove one of the Heaviside functions; this would amount to a stimulus propagating to infinity after being initialized.
To show this we need to demonstrate that the synaptic change induced by this different stimulus is arbitrarily small when compared to the synaptic change induced by the true stimulus. This is realised by the rapid decay of the plasticity window and shown formally in Lemma 4.1; see Appendix A.

**Activity Dynamics** It was reasoned on physical grounds that in the absence of presynaptic stimulation the only post-synaptic solution is a static, constant level of activity; we are interested in calculating perturbations away from these baseline levels. We shall assume the baseline is sufficiently close to the origin that the logistic function is analytical and has a convergent Taylor series expanded around \( u = u_0 \). Therefore, a good approximation is:

\[
Q(u) = Q(u_0) + uQ'(u_0).
\]  

(3.1)

This can then be inserted in (2.3) and a Fourier transform can be taken to yield:

\[
\hat{u}(k, \omega) = Q(u_0)\Gamma(k, \omega)(\hat{W}(k) + \hat{S}(k))\delta(k)\delta(\omega) + Q'(u_0)\hat{S}(k)\Gamma(k, \omega)\hat{a}(k, \omega),
\]  

(3.2)

with \( \Gamma(k, \omega) = (1 + i\tau \omega - \hat{W}(k))^{-1} \). Now recognising that \( Q(u_0)\Gamma(k, \omega)(\hat{W}(k) + \hat{S}(k))\delta(k)\delta(\omega) \) corresponds to the static solution, i.e. the baseline activity level, we can write an expression for the Fourier transform of the perturbation of the activity level:

\[
\delta\hat{U}(k, \omega) = \hat{S}(k)\Gamma(k, \omega)\hat{a}(k, \omega),
\]  

(3.3)

where \( U(x, t) = Q(u(x, t)) \). The Fourier Transform of the perturbation from the baseline rate in the pre-synaptic field, \( \delta\hat{A}(y, t) \) is trivial to compute: \( \delta\hat{A}(k, \omega) = \delta\hat{a}(k, \omega) \). This is all we need to explicitly compute the synaptic change between any two points in the pre-synaptic and post-synaptic field.

**Synaptic Dynamics** We shall assume that the synaptic field, and synaptic changes are isotropic; \( S(x, y, T) = S(x - y, T) \) for all \( T \). Then making the approximation of the firing rate, and taking spatial Fourier transforms the synaptic change can be written:

\[
\delta(p+k)\frac{d\hat{S}(k, T)}{dT} = \delta(p+k)(S_0 - S_1\hat{S}(k, T)) - S_2\int_{-\infty}^{\infty} \hat{a}(\omega, p)\hat{a}(\omega, k)^*\hat{H}(\omega)^*\hat{S}(k, T)^*\Gamma(\omega, k)d\omega,
\]

where \( S_0, S_1, \) and \( S_2 \) have absorbed the time constant, regularisation constants, baseline firing rate, and the Fourier normalisation terms. We have kept the sign of \( S_1 \) negative to indicate its relationship with the decay constant \( \lambda \). Integrating with respect to \( p \), the above equation may be solved as:

\[
\frac{d\hat{S}(k, T)}{dT} = S_0 - S_1\hat{S}(k, T) - S_2\hat{S}(k, T)^*\int_{-\infty}^{\infty} B(\omega)\hat{a}(\omega, k)\hat{H}(\omega)^*\Gamma(\omega, k)d\omega,
\]  

(3.4)

where \( B(\omega) = \int_{-\infty}^{\infty} \hat{a}(\omega, p)^*dp \). The connectivity kernel \( S \) in position space is physically required to be real. We can write it as the composition of odd and even functions. Then, from conjugate symmetry it follows that its Fourier transform is then composed of a real part consisting of the linear combination of the Fourier transforms of its even components, and an imaginary part consisting of the linear combination of the Fourier transforms of its odd components. For \( S \) to remain real its derivative must have an even function as its real component, and an odd function as its imaginary component. Denoting,

\[
G(k) = \int_{-\infty}^{\infty} \left( \int_{-\infty}^{\infty} \hat{a}(p, \omega)^*dp \right) \hat{a}(\omega, k)\hat{H}(\omega)^*\Gamma(k, \omega)d\omega,
\]  

(3.5)
we can see that if $G(k)$ is even and real, or odd and purely imaginary, then the above equation can be separated into odd and even parts and solved as two independent ODEs. Attention will be restricted to the even form of $G(k)$ as we will show in the next section that this must be the case. Denoting $S_O(x, T)$ and $S_E(x, T)$ to be the odd and even parts of the coupling function in position space these ODEs are then:

$$\frac{d\hat{S}_O(k, T)}{dT} = -(S_1 + S_2G(k))\hat{S}_O(k, T)$$

(3.6)

$$\frac{d\hat{S}_E(k, T)}{dT} = S_0 + (S_2G(k) - S_1)\hat{S}_E(k, T).$$

(3.7)

Therefore, in the asymptotic limit, provided $S_1 + S_2G(k) > 0$ the odd components of the initial organisation decay to zero and provided $S_1 > S_2G(k)$ the even components have solution:

$$\hat{S}_E(k) = \frac{S_0}{S_1 - S_2G(k)}.$$  

(3.8)

The final organisation is therefore dictated by the initial even components and the form of $G(k)$. We will show that $G(k) > 0$ which is sufficient to satisfy the above conditions. The form of $G$ is prescribed the learning rule employed and the input stimulus used, we shall refer to it as the training function.

**Mono-Directional Propagation** If we suppose the input stimulus is $a(y, t) = \Theta(t)(h(y - ct - y_0) + h(y + ct - y_0))$. Taking two Fourier transforms yields:

$$\tilde{a}(p, \omega) = \frac{1}{2} e^{-2\pi i y_0 p} \hat{h}(p) \left( \frac{2i w}{\pi (w - cp) \pi (w + cp)} \right).$$

(3.9)

Then integrating with respect to $p$ by using the Cauchy Residue Theorem and evenness of the last term and $h$ gives:

$$\int_{-\infty}^{\infty} \tilde{a}(p, \omega)^* dp = \left( 1 + \frac{2}{c} \right) h \left( \frac{\omega}{c} \right)^* \cosh \left( 2\pi i y_0 \frac{\omega}{c} \right).$$

(3.10)

$G(k) = G(k; y_0)$, and if we assume that the synaptic changes at each time step are small then the average synaptic changes can be written as:

$$\left\langle \frac{d\hat{S}(k, T)}{dT} \right\rangle = S_0 - S_1 \hat{S}(k, T) + S_2 \hat{S}(k, T)\langle G(k; y_0, c) \rangle.$$ 

(3.11)

The asymptotic limit, which we are ultimately interested in, will approach this average and for the remainder of this work we shall drop the angle brackets. Let $q(k; c) = (\tilde{H}(ck))^* \Gamma(k, ck) + \tilde{H}(-ck)^* \Gamma(k, -ck))/c$. Equation (3.10) can then be inserted into the expression for $G(k)$ and the Dirac-Deltas can be integrated. Then, we integrate out $y_0$
by assuming it is distributed over some interval of length $L$ giving exponential integral functions which vanish as $y_0 \to \infty$ yielding:

$$\frac{d\hat{S}(k, T)}{dT} = S_0 + \hat{S}(k, T) \left( S_{2g(k; c)} |\hat{h}(k)|^2 - S_1 \right).$$  \hspace{1cm} (3.12)

Showing that $g(k; c)$ is even may be done by direct substitution for both STDP and CDP rules under the assumption that both $\hat{W}$ and $\hat{h}$ are even. It then follows that all $G(k)$ are even. It remains to be shown that $G(k)$ is restricted to being non-negative or non-positive. All the scaling constants are positive and it is therefore clear for the STDP rule that $G(k) \geq 0$, while for the CDP rule $G(k)$ is never non-positive and is only non-negative if $\hat{W}(k) < 1$. It is certainly possible that this is the case, but it is not true for common choices of $W$. $W$ is typically chosen to be in the form of a “wizards-hat” with short-range excitation and long range inhibition which is theoretically grounded and observed experimentally [41, 34].

3.1 Computational Analysis and Parameter Estimation

So far, we have proceeded in a general manner without much reference to the recurrent connections or input stimulus (with the exception of wave-speed $c$) and the parameters and functional forms that characterise them. Here we shall specify explicit choices for both of these and examine the consequences on the organisation via computational means. We shall also try and estimate key parameters which contribute to the width, or arbor size, of the final organisation by means of Markov Chain Monte Carlo (MCMC) applied to wild-type and $\beta_2$ knockout data. This estimation allows us to both validate the model and estimate biological quantities which have not yet been experimentally examined.

We choose a Gaussian to describe the wave-form of the input stimulus with amplitude and width (variance) parameters of $\sigma_1$ and $\sigma_2$ respectively and with Fourier Transform $\hat{h}(k) = \sigma_1\sigma_2 \exp(-k^2\sigma^2_2/2)$. We then choose a difference of two Gaussians to describe the recurrent connections: $\hat{W}(k) = r_1 \exp(-k^2r^2_1/2) - r_2 \exp(-k^2r^2_2)$. The choice ensures that the dimensional requirements for the propagator are satisfied and that $|\hat{W}(k)| < 1$ for a suitable choice of recurrent connection parameters. These choices mean that there are 16 key biological parameters: $u_0, \tau, \tau', \kappa, \lambda, A_p, t_p, Q_{max}, \beta, \theta, c, \sigma_1, \sigma_2, R_1, r_1, r_2$.

Parameter Analysis Examination of (3.8) shows that $S_0$ (or $\kappa/\tau'$) serves to stabilise the dynamics at the cost of introducing noise - the Fourier spectrum of a biologically realistic organisation will decay to a constant i.e. to a baseline level of white noise. A tolerable level of system noise is expected and we will assume that this noise can be filtered by some means. The denominator dictates the deviations from this noise and noting that for both CDP and STDP $G(k) \to 0$ and $G(k) > 0$ we have that physically viable solutions enforce $0 < G(k) < S_1/S_2$ and non-viable solutions contain pairs of singularities (via evenness of $G$) where $G(k) > S_1/S_2$ for some $k$.

We note that an arbitrarily large wave-amplitude $\sigma_1$ can force a singularity in both cases and an arbitrarily large $c$ can force a singularity in the STDP case. From this we can deduce for stability in the STDP case that the maximum wave speed is bound by a contour inversely proportional to wave-amplitude and vice-versa. Given the likely biological restrictions on amplitude this implies that wave speed could be dictated in part by wave amplitude. With this in mind we will set $\sigma_1 = 5mV$ for the remainder of this work. This ensures that there is a baseline distinguishable level of firing when the wave reaches its peak amplitude but the neurons are not near a saturated level thus satisfying the assumptions required for the approximation in (3.1). We see that $u_0, \tau', \lambda, A_p, \beta, \theta$ are absorbed into $S_0, S_1$, and $S_2$ and their effects on the dynamics...
are immediate: they dictate the absolute measurable values of the organisation, not the form. We therefore set these parameters according to Table 2 for the remainder of this work.

| Param. | Value | Units | Description               |
|--------|-------|-------|---------------------------|
| $u_0$  | 0.58  | mV    | Resting potential         |
| $\tau$ | 0.1   | s     | Activity time-scale       |
| $\tau'$| 100   | s     | Synaptic time-scale       |
| $\kappa$| 0.001 | syn.mm$^{-2}$ | Synapse density |
| $\lambda$ | 0.001  | –     | Decay rate                |
| $A_p$  | 1     | syn.mm$^{-2}$ | Hebbian rate |
| $t_p$  | 1.0   | s     | Hebbian time-scale        |
| $Q_{\text{max}}$ | 1 | s$^{-1}$ | Max firing rate |
| $\beta$ | 0.26  | mV$^{-1}$ | Rate steepness |
| $\theta$ | -45   | mV    | Rate threshold            |
| $c$    | 0.1   | mm.s$^{-1}$ | Wave-speed |
| $\sigma_1$ | 5     | mV    | Wave-amplitude            |
| $\sigma_2$ | 0.1   | mm    | Wave-length               |
| $R_1$  | 1.08  | mm    | Recurrent amplitude       |
| $r_1$  | 0.129 | mm    | Inhibitory length-scale   |
| $r_2$  | 0.136 | mm    | Excitatory length-scale   |

Table 2: The choices made for each of the biological parameters used throughout the text, unless otherwise stated. The length scale is chosen to reflect the scale at which NFT typically applies in the brain and the appropriate scale for the mouse SC [36]. The resting membrane potential, the threshold voltage, and the voltage scale are estimated to be in line with electrophysiological recordings [40]. These parameters should be carefully measured if a specific biological system is to be closely analysed.

We can see also that for CDP $G(k)$ attains its global maximum at $k = 0$ meaning that its stability is determined entirely by the relationship between $S_1$ and $S_2$. Furthermore, with CDP synaptic changes have the potential be to large with no parameter available to mitigate them, in the STDP case the small timescale ensures that the changes are small and the adiabatic assumption is satisfied. We proceed only with the STDP case noting that extending the analysis to a CDP rule would be straightforward but care must be taken in the choice of parameters.

These choices, while considered, have reduced the problem to a single learning rule and several key parameters. We stress that the other parameters must be carefully measured for accurate predictions and are in some sense non-trivial: one can manipulate them biologically and cause a bifurcation in the organisation dynamics. Figure 3 demonstrates the manifold in the $c - \sigma_2$ plane for which the model presents plausible (stable) solutions. We have shown only a 2-dimensional slice of the overall manifold for which there are no solutions with singularities, but care should be taken in ensuring that any solution of interest lies within the volume of this manifold for all parameters.

**Fourier Space** The Fourier transform of $S$ has a characteristic bump near the origin which decays to a constant representing a baseline level of noise i.e. $\hat{S}(k) = c_0 + \hat{S}(k)$ where $\hat{S}(k)$ is a symmetric function decaying quickly to zero. Note that it is possible for $\hat{S}(k)$ to fall below the noise level which implies that the system will be out of phase and suppress signals at this wave length. A typical representation in Fourier and real space is shown in Figure 4a.
Figure 3: The manifold in \((c, \sigma^2)\) space which defines the stability of the final organisation. Below the surface solutions do not exhibit singularities and the training function is deemed to be stable; in general, small choices for the parameters exhibit stable synaptic organisations at the cost of arbitrarily small amplitude. The manifold appears to be well-above reasonable estimates for these parameters, ensuring the model is likely stable in plausible biological scenarios.

Figure 4: A typical organisation generated with the parameters shown in Table 2 with (a) showing the representation in Fourier space, and (b) the representation in real space after re-normalisation.
The distribution of the connections in physical space can be found by inverting its Fourier representation which presents a problem with the inclusion of the Dirac-Delta distribution introduced by $c_0$. This problem can be circumvented by realising that the baseline constant representation of all frequencies represents white noise which can be therefore be renormalised and omitted; see Figure 4b. This re-normalisation is done under the assumption that provided the amplitude of $\hat{S}(k)$ provides a high enough signal-to-noise ratio then this system will be absorbed into already present biological noise which is filtered out in downstream calculations.

**Refinement**  The steady state solution of the synaptic distribution $S$ takes its maximum at the origin and rapidly decays at large distances. The distributions feed-forward capability is therefore dictated by the magnitude at the origin and the rate of the decay. For precise signal transmission (or a refined retinotopy) the width of the distribution should be small with respect to the length scale. We can estimate width by taking the inverse of the wave-length that maximises the power spectrum:

$$\Omega(\vec{\rho}) = \frac{1}{\arg\max_k |\hat{S}(k; \vec{\rho})|},$$

(3.13)

where $\vec{\rho}$ represents the vector of parameters which define the model. We shall examine the width relationships in the plane of several pairs of variables within a stable region containing no singularities; shown in Figure 5. Refinement tends to decrease in accordance with decreases in $c, \sigma_2, (r_1/r_2), R_1, t_p,$ and $\tau$. On the biological scales of interest for the current work the decreases do not appear to be substantial in the $R_1$ and $\tau$ directions. In general the relationships between the variables are non-linear.

**Sensitivity**  In the context of refinement it is prescient to consider which parameters affect the models prediction of the width which we have defined. The width given by (3.13) will satisfy $dS(k; \vec{\rho})/dk = 0$ which inserted into (3.8) yields:

$$\frac{dg(k; \vec{\rho}_0)}{dk} = 0,$$

(3.14)

where $\vec{\rho}_0 = \{c, \tau, t_p, \sigma_2, R_1, r_1, r_2\}$. The width will only vary in accordance with these parameters which was confirmed by numerical simulation.

**MCMC Parameter Estimation**  The $\beta 2$ knock-out in mouse has the effect of altering the spatio-temporal patterns of spontaneous activity in the retina and SC during development [42]. The mutant mice have substantially wider arborisations than in wild-type establishing the importance of activity in refining the retinotopic projection [16]. Existing models have not been able to predict this wider arborisation when the patterns of activity associated with the knock-out are replicated in the models mechanisms for activity [27].

We estimate the arborisation widths as $0.24 \pm 0.077\text{mm}$ (wild-type) and $0.48 \pm 0.15\text{mm}$ ($\beta 2$) by taking half the square root of the arborisation area reported by [42]. We estimate the wave speeds as $0.13 \pm 0.015\text{mm s}^{-1}$ (wild-type) and $0.17 \pm 0.033\text{mm s}^{-1}$ ($\beta 2$), and the wave-widths as $0.11 \pm 0.012\text{mm}$ (wild-type) and $0.20 \pm 0.012\text{mm}$ ($\beta 2$) by taking half the total width reported by Stafford et al [42]. We estimate the inhibitory and excitatory lengths scales, and amplitude of the recurrent connections to be $0.14 \pm 0.014\text{mm}$ and $0.13 \pm 0.013\text{mm}$, and $1.04 \pm 0.014\text{mm}$ respectively using the data reported by [34]. We take our priors on these parameters to be normal distributions centred on the estimates with standard deviation corresponding to the measurement error. We take uninformative priors on the time-scale parameters assigning uniform distributions on $[0,1]$ and $[0,10]$ for
Figure 5: The variation in width ($\Omega$) in four distinct planar slices of the manifold of parameters which influence the models prediction of mean distribution width. Panel (a) shows that width decreases both with wave-speed and wave-width, qualitatively accounting for the differences between the wild-type and $\beta_2$ mutant. Panel (b) shows that width decreases with with the ratio of excitation to inhibition in the recurrent connections $W$ suggesting a smaller zone of excitatory support decreases arbor size. There is an anti-symmetry along the line $r_1 = r_2$ which is expected as the dominant connection type switches along this line. Panel (c) shows that width decreases with recurrent connection amplitude but the effect is not substantial. Panel (d) shows that width predominately decreases in accordance with the plasticity window time-scale, and while the activity time-scale has an effect it is not substantial.

the activity time scale ($\tau$) and the plasticity window scale ($t_p$), respectively. The MCMC was completed using a dedicated Mathematica package [9]. The MCMC completed in $10^5$ iterations using 6 chains with each parameter initialised within 10% of the mean of its prior. The maximum Gelman-Rubin statistic for convergence was 1.00037 indicating that the chains had converged [18]. The posteriors for each parameter are reported in Figure 6. The posteriors for the recurrent connections parameters, $r_1, r_2,$ and $R_1$ remained tightly constrained by their priors, indicating that the prior estimates were well informed and in agreement with the model. The activity time scale is broadly distributed throughout the range [0,1]s with a bias towards 0. The plasticity time-scale is distributed around a maximum of 0.56s. The computed $R^2$ statistic was 0.81.
Figure 6: Panel (a) shows the posterior histogram for the time-scale of activity which is broadly distributed through the search space of $[0,1]$s but biased towards the lower bound. This broad distribution is concordant with the observation that the time-scale of activity induces relatively small variations in the organisation width; see Figure 5. Panel (b) shows the posterior histogram for the time scale of the plasticity window which is maximised around 0.6s. The posterior histograms for the recurrent connection parameters $(r_1, r_2, R_1)$ are shown in Panels (c-e) and are tightly constrained by their informative priors suggesting that there is no predicted effect on these connections in the $\beta 2$ mutant. For all histograms presented an empirical distribution curve was fitted and overlain in blue.
4 Discussion

If the model is sound and the biological system is allowed sufficient time to reach a reasonable approximation of the asymptotic state then these results suggest that the computational/synaptic structures developed are primarily a result of activity dynamics. Under this model the chemotactic and competitive mechanisms serve to initialise a coarse isotropic retinotopy from which the activity dynamics can refine and ultimately dictate final synaptic organisation. This interpretation augments the understanding of the establishment of retinotopy by suggesting that the final synaptic organisation can be understood in a large part by understanding the spatio-temporal nature of the input stimulus, the recurrent connectivity, and the learning rule. Should the biological system not employ the learning routine until asymptotic stability then the model will still be able to make predictions about the final organisation given precise enough measurements of the relevant parameters. In both instances the model gives testable hypotheses the former of which has been benchmarked against the mouse wild-type and $\beta_2$ knock-out mutant.

Organisation  We have shown that the key aspects of the final organisational structure are dictated by the interplay between the spatio-temporal characteristics of the input stimulus and the structure of the recurrent connections. These dependencies on recurrent connections and input are in accordance with previous analysis performed with a simple Hebbian rule and static input [44]; the model proposed here, however, allows for richer construction in terms of specifying the input and connections by realising full temporal and spatial dynamics, and more complex structure in the final organisation. We have introduced regularisation rules which allow this organisation to take non-trivial structure when supplemented by system noise which we have assumed is able to be renormalised in downstream biological calculations or via some other mechanism. The regularisation necessitates neurotrophic factors being expressed during development. Finally, the measurable aspects of the organisation are dictated by the precise realisation of the relevant biological parameters.

Refinement  The results indicate parameter dependence on wave-speed, wave-width, plasticity time-scales, and the ratio of excitation to inhibition widths in the recurrent connections. Principally, parameter changes that would lead to a tighter correlation structure such as smaller wave-widths, slower wave-speeds, and smaller excitatory zones lead to a smaller width of topographic refinement. Interestingly, the time-scale of the plasticity rule has an effect of the width of the final organisation. The $\beta_2$ knock-out provides a phenomenological test of this component of model. The knock-out exhibits fast-moving, and hyper-correlated, retinal waves which lead to an imprecise topographic mapping - an effect that has not been captured in existing models. Our model suggests that an increase in wave-speed or wave width will lead to a less-refined map reproducing the results of the knock-out in silico; see Figure 5.

An MCMC parameter estimation was performed using known errors-in-measurement of wave-speed, wave-width, and organisation width in wild-type and the $\beta_2$ mutant. The model predicts the expected mean width of both wild-type and the $\beta_2$ knock-out within standard error when parametrized by likelihood maximising parameters and provides a good explanation of the variance between the wild-type and mutant ($R^2 = 0.81$). We found the model to be insensitive to the time-scale of activity with the posterior assuming a broad posterior over $[0,1]$s with a slight bias towards lower values suggesting that the activity time-scale does not account for much of the variance in organisation width. The posteriors of the parameters of the recurrent connections were largely dictated by...
their priors suggesting that the priors estimated from available are informative and that the $\beta^2$ knock-out does not have a substantial effect on the recurrent connections, as expected. We do not expect the time-scale of the plasticity window to be affected by the knock-out and thus the MCMC allows us to estimate this parameter on the order of seconds. The timescale of the plasticity window in two closely related biological systems, the Xenopus retinotectal projection and rat visual cortex, are estimated to be on the order of $10^{-2}$ seconds [17, 52]. Plasticity windows can have significantly longer time-scales on the order of 10s of minutes [12]. Our estimate is notably higher than what has been observed in similar systems but is in agreement with the typical duration of a wave of spontaneous activity in the developing retina in mice [51]. We might expect a deviation as we are analysing a different biological system. This result suggests that the plasticity windows in this system are calibrated to integrate all information contained in a spontaneous wave event.

**Future Directions** The analysis presented here has made simplifying assumptions about the statistical properties of spontaneously generated waves: these assumptions cannot be expected to hold in general. The analysis was also restricted to one dimension: the two-dimensional case has a much richer topology and is more relevant as the topographic projection is typically organised as a sheet. The analysis can be trivially extended into the plane by using the same assumption: every wave-direction is equiprobable. More realistic wave-statistics can be simulated numerically and examining the properties of the synaptic distribution generated by the data of spontaneous activity in mouse is a future research direction; for example using the model of activity proposed by Godfrey and Eglen [2, 14, 20].

The model predicts that the time-scale of the plasticity window in developing mouse SC neurons is 1-2 orders of magnitude higher than the scale typically used to describe neuronal plasticity in analogous systems. While we do not claim that this prediction represents a ground truth, the model makes several simplifying assumptions and estimations, it is a good candidate for experimental falsification.

**Conclusion** We have developed a modelling framework in which the effects of rich spatio-temporal patterns of activity on topographic refinement can be analysed alongside system specific measurements of parameters. The model posits that the final synaptic organisation is dictated in a large part by the characteristics of this activity suggesting a more involved role for activity, spontaneous or otherwise, in the developing visual system. The model explains topographic defects observed in the $\beta^2$ mutant which has had its spontaneous activity patterns altered and on the basis of the mutant and wild-type offers a prediction of the time-scale on which Hebbian refinement operates in mouse development.

**Generating Code** The code used to perform the analysis and generate the images in this project may be found at [https://github.com/Nick-Gale/Neural_Field_Theory_Topographic_Development](https://github.com/Nick-Gale/Neural_Field_Theory_Topographic_Development).

**Appendix: A**

**Lemma 4.1.** The synaptic change $\frac{dS}{dt}$ induced by a given input stimulus $A_p$ which terminates at some arbitrary $t_1$ can be well approximated by a similar input stimulus $A$ that terminates at $t = \infty$ i.e. $\left| \frac{dS_p}{dt} - \frac{dS}{dt} \right| < \epsilon$ for $\epsilon \ll 1$.

**Proof.** Consider a function $A(y, t)$ which propagates to infinity and induces and activity
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in the post-synaptic field of $U(x, t)$. For physical reasons this function must decay rapidly at infinity implying for all real $t_j$:

$$\int_{t_j}^{\infty} A(y, t)\, dt = \epsilon_j.$$ (4.1)

Then, due to the rapid decay of the plasticity function we also have that for all physical realisations of $u$ and for all $t$:

$$\int_{-\infty}^{\infty} H(\tau)U_i(t + \tau)\, d\tau = \xi_i < \infty.$$ (4.2)

Then, consider the functions $A(y, t) = \Theta(t)h(y, t)$ and $A_p(y, t) = (\Theta(t) - \Theta(t - t_1))h(y, t)$, and the functions $U(x, t)$ and $U_p(x, t)$ which are induced activities from stimulus $A$ and $A_p$. Observe that as a result of the rapidly decaying plasticity window there exists some $\epsilon$ such that:

$$\left| \int_{t_1}^{\infty} H(\tau)(U_p(x, t) - U(x, t))\, d\tau \right| < \xi,$$ (4.3)

and:

$$\left| \int_{-\infty}^{0} H(\tau)(u_p(x, t) - u(x, t))\, d\tau \right| < \xi,$$ (4.4)

for all $x$ and $t$. Also, observe that in the limit $t_1 \to \infty$, $\xi$ tends to zero. Now let $\epsilon_2 = \xi \int_{0}^{t_1} A(y, t)\, dt$ and note that in the limit $t_1 \to \infty$ this $\epsilon_2$ will also tend to zero, as the integral of $A(y, t)$ is bounded. Finally, suppose $\int_{t_1}^{\infty} A(y, t)\, dt < \epsilon_1$. Then, $\epsilon = K_0(\xi_1 + 2\epsilon_2)$ may be made arbitrarily small for sufficiently large $t_1$. Now consider the synaptic change induced by the truncated function $A_p$:

$$\frac{dS_p(x, y, T)}{dT} = K_0 \int_{-\infty}^{\infty} A_p(y, t) \int_{-\infty}^{\infty} H(\tau)U_p(x, t + \tau)\, d\tau\, dt$$

$$< K_0 \int_{0}^{t_1} h(y, t) \left( \int_{-\infty}^{\infty} H(\tau)U(x, t + \tau)\, d\tau + 2\xi \right)\, dt$$

$$< K_0 \int_{-\infty}^{\infty} \Theta(t)h(y, t) \int_{-\infty}^{\infty} H(\tau)U(x, t + \tau)\, d\tau\, dt + K_0 \epsilon_1 \xi + 2K_0 \epsilon_2$$

$$< \frac{dS(x, y, T)}{dT} + \epsilon.$$

Therefore, it is a sufficiently good approximation to consider the stimulus propagating to infinity, rather than the stimulus truncated at time $t = t_1$ when calculating the synaptic change.

\[ \square \]

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