Next-to-next-to-leading order spin–orbit effects in the equations of motion of compact binary systems

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Abstract
We compute next-to-next-to-leading order spin contributions to the post-Newtonian equations of motion for binaries of compact objects, such as black holes or neutron stars. For maximally spinning black holes, those contributions are of third-and-a-half post-Newtonian (3.5 PN) order, improving our knowledge of the equations of motion, already known for non-spinning objects up to this order. Building on previous work, we represent the rotation of the two bodies using a pole–dipole matter stress–energy tensor and iterate Einstein’s field equations for a set of potentials parametrizing the metric in harmonic coordinates. Checks of the result include the existence of a conserved energy, the approximate global Lorentz invariance of the equations of motion and the recovery of the motion of a spinning object on a Kerr background in the test-mass limit. We verified the existence of a contact transformation, together with a redefinition of the spin variables that makes our result equivalent to a previously published reduced Hamiltonian, obtained from the Arnowitt–Deser–Misner formalism.

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1. Introduction
Gravitational wave detectors will soon enter a new era, with the advanced versions of Virgo and LIGO expected to start operating around 2015, and the construction of KAGRA [1–3]. Primary targets for these laser ground-based interferometers, or for possible future space-based interferometers, are inspiralling binaries of compact objects—neutron stars and/or black holes—which emit gravitational radiation during their late inspiral, merger and ringdown phases. Hunting for the faint signal and best separating it from the noise using matched-filtering techniques (e.g. [4, 5]) requires a very precise modelling of the expected waveform,
which the post-Newtonian (hereafter PN) approximation aims at providing for the inspiral phase [6].

Up to now, such high-precision PN templates are available for the non-spinning case up to the 3.5 PN order, i.e. the order $1/c^2$ in the formal expansion in powers of $1/c^2$ (with $c$ being the speed of light). However, observational evidence points towards the existence of fast-rotating black holes, endowed with significant angular momentum (or spin), for stellar size [7–11] as well as for supermassive black holes [12–14].

It is thus important to complete our knowledge of the PN predictions for the gravitational waves emitted by such systems by including the spins of each of the two bodies. This implies first taking those spins into account in the dynamics of the binary. For maximally spinning objects, the leading-order linear-in-spin (which we shall call spin–orbit) effect arises at 1.5 PN order when regarding the spin as a 0.5 PN quantity (see equation (1.1)). The next-to-leading and next-to-next-to-leading contributions show up at respectively 2.5 PN and 3.5 PN orders.

The effect of spacetime curvature on the motion of a spinning test particle was obtained in the seminal work by Papapetrou [15–17], after an earlier derivation by Mathisson (republished in [18]). Barker and O’Connell [19, 20] determined the leading-order spin–orbit and spin–spin effects in the two-body dynamics. More recently, Kidder, Will and Wiseman [21, 22] computed the corresponding contributions to the radiation field and, most importantly, to the orbital phase of the binary, to which the templates are crucially sensitive. Effective field theory methods [23] were also used to rederive the leading-order spin–orbit and spin–spin contributions to the dynamics [24]. The problem in the limit of a spinning test particle on a Kerr background has been addressed in [25, 26] (see also [27] for a Hamiltonian model neglecting the gravitation damping force).

By means of a PN iteration of the Einstein field equations in harmonic coordinates, the equation of motion at the next-to-leading order was first investigated by Tagoshi, Ohashi and Owen [28, 29]. It was then confirmed and completed (as well as extended to the radiation field) by Blanchet, Buonanno and Faye [30, 31]. The results for the evolution equations were retrieved by two independent calculations, using a Hamiltonian approach in Arnowitt–Deser–Misner (ADM) coordinates [32] on the one hand, and using effective field theory methods [33, 34] on the other hand. The ADM computation was later generalized to the many-body problem [35] and extended to the next-to-leading order spin1–spin2 and spin square (e.g. spin1–spin1) effects in [36, 37]. Next-to-next-to-leading order spin–orbit effects in the Hamiltonian of the binary were first computed in [38], resorting to the ADM scheme adapted to matter sources composed of spinning point particles [39]. In a subsequent work, spin1–spin2 interactions terms were also added at the 4 PN order [40]. Effective field theory methods progressed concurrently by computing the 3 PN spin1–spin2 and spin1–spin1 contributions [41–43], and the 4 PN spin1–spin2 interactions [44].

Our aim in this work is to extend the approach of [30], based on the PN expansion of the metric in harmonic coordinates, in order to compute the spin–orbit next-to-next-to-leading order 3.5 PN contributions to the equations of motion. We shall thus provide an essential validation of the result obtained by the ADM method [38]. Our final purpose is to derive the spin–orbit terms in the emitted GW energy flux and in the phase of the binary at the same approximation, extending therefore [31] to next-to-next-to-leading order, so as to provide more accurate PN predictions to the template–based data analysis.

We adopt the same convention for the PN order counting of the spins as in paper I; namely we redefine our spin variable with respect to the ‘true’ spin angular momentum following

$$S \equiv cS_{\text{true}} = Gm_{\text{body}}^2 \chi,$$

(1.1)

We will refer to [30] as paper I throughout this work.
where $m_{\text{body}}$ is the mass and $\chi$ the dimensionless spin parameter ($G$ denotes Newton’s constant). For a maximally rotating compact object, we have $\chi \sim 1$ and $S \sim Gm_{\text{body}}^2$, so that our spin variable can be counted as of Newtonian order in this case. For slowly rotating objects however, we have $\chi \sim v_{\text{surf}}/c$, where $v_{\text{surf}}$ is the rotation velocity of the body surface, which implies that $S$ acquires an additional factor $1/c$. In that case, spin–orbit contributions effectively appear at 2 PN order and spin–spin ones at 3 PN only. Our counting will always assume rapid rotation. The leading-order spin–orbit terms will thus carry an explicit factor $1/c^3$; in this paper, we shall obtain the next-to-leading and next-to-next-to-leading spin–orbit corrections $\sim 1/c^5$ and $\sim 1/c^7$.

The paper is organized as follows. In section 2, we review the pole–dipole formalism for modelling compact objects as point particles with spins. In section 3, we describe the parametrization of the PN metric in terms of a set of elementary potentials and present the equations of motion as deduced generically from metric components. The core of our work consists of the computation of the required potentials in sections 4 and 5, first using Hadamard’s regularization (as well as the ‘pure Hadamard–Schwartz’ prescription [45]), and next completing some of our calculations by means of the more powerful dimensional regularization. Section 6 contains our results for the precession equations and the acceleration. In section 7, we explain the various checks that have been performed to validate them: construction of a conserved energy, check of the global Lorentz invariance, test-mass limit and recovery of the results of [38] in the ADM Hamiltonian formulation. We conclude shortly in section 8.

2. Effective pole–dipole formalism

The starting point of our calculations is the model of pole–dipole particles developed by Mathisson [18], Papapetrou [16, 17], Tulczyjew [46, 47] and generalized by Dixon [48–50] and Bailey and Israel [51]. This model allows an effective description of the dynamics of bodies that accounts for their spin angular momentum by means of singular Dirac delta functions, making analytical computations tractable. We use the same version of the model as in paper I, staying linear in the spins, but we summarize here the main formulae for completeness and refer to paper I for more details.

The central assumption is that each particle is described by a stress–energy tensor made up of two parts, a monopolar one and a dipolar one: $T^{\mu\nu} = T^{\mu\nu}_M + T^{\mu\nu}_D$. These are built with respectively a Dirac delta function and a gradient of a delta function, integrated over the world line of the particle, according to

\begin{align}
T^{\mu\nu}_M &= c^2 \int_{-\infty}^{+\infty} d\tau \, p^{(\mu} u^{\nu)} \frac{\delta^{(4)}(x - y(\tau))}{\sqrt{-g(x)}}, \tag{2.1a} \\
T^{\mu\nu}_D &= -c \int_{-\infty}^{+\infty} d\tau \, \nabla_{\rho} \left[ S^{(\rho(\mu} u^{\nu))} \frac{\delta^{(4)}(x - y(\tau))}{\sqrt{-g(x)}} \right]. \tag{2.1b}
\end{align}

Here, $\tau$ is the proper time measured along the world line, described itself by the particle position $y^\mu(\tau)$; $\delta^{(4)}$ denotes the four-dimensional Dirac delta function, $g$ stands for the determinant of the spacetime metric $g_{\mu\nu}$; $u^\mu = dy^\mu/(c \, d\tau)$ is the 4-velocity of the particle (satisfying $u_\mu u^\mu = -1$), $p^\mu$ its linear momentum and $S^{\mu\nu}$ an antisymmetric tensor that represents the spin of the particle.

The linear momentum $p^\mu$ and spin tensor $S^{\mu\nu}$ obey the Mathisson–Papapetrou equations of evolution:

\begin{align}
\frac{DS^{\mu\nu}}{d\tau} &= c^2 (p^\rho u^{\mu} - p^{(\rho} u^{\nu)}) \tag{2.2a},
\end{align}

and
\[ \frac{Dp^\mu}{dr} = -\frac{1}{2} R^\mu_{\nu\rho\sigma} u^\nu S^{\rho\sigma}, \]  
\( (2.2b) \)

with \( D/dr \equiv cu^\nu \nabla_\nu \) and \( R^\mu_{\nu\rho\sigma} \) denoting the Riemann tensor. As is well known, a choice of supplementary spin condition (thereafter SSC) is necessary, in order to obtain the correct number of degrees of freedom (see [52] for a summary of the various choices in use in the literature). We adopt the following covariant SSC:

\[ S^{\mu\nu} p_\nu = 0. \]  
\( (2.3) \)

With this relation in hand, one can combine equations (2.2) to obtain the link between the 4-velocity \( u^\mu \) and the linear momentum \( p^\mu \); hence, we deduce the conservation laws:

\[ \frac{Dm}{dr} = 0, \quad \frac{DS}{dr} = 0, \]  
\( (2.4) \)

for the mass and the magnitude of the spin defined by \( m^2 c^2 = -p^\mu p_\mu \) and \( S^2 = S^{\mu\nu} S_{\mu\nu}/2 \), respectively, and thus conserved along the particle’s world line.

We now restrict the evolution equations themselves to linear order in spins, neglecting any term \( O(S^3) \), quadratic or of higher order. One can readily check the proportionality relation between \( u^\mu \) and \( p^\mu \) in that approximation:

\[ p^\mu = m c u^\mu + O(S^3). \]  
\( (2.5) \)

In particular, the SSC now reads \( S^{\mu\nu} u_\nu = O(S^3) \). Note that the monopolar part of the stress–energy tensor has the same form as the one of an ordinary point-like particle, but it does depend on the spin implicitly through the metric. Equations (2.2) become

\[ \frac{DS^{\mu\nu}}{dr} = O(S^2), \]  
\( (2.6a) \)

\[ mc \frac{Du^\mu}{dr} = -\frac{1}{2} R^\mu_{\nu\rho\sigma} u^\rho S^{\nu\sigma} + O(S^3). \]  
\( (2.6b) \)

We see that in the linear approximation, the spin tensor is parallely transported along the motion, which is actually non-geodesic due to the coupling of the spin tensor with the Riemannian curvature.

In the following, we shall use the three-dimensional form of the energy–momentum tensor (2.1). Using a \( 3 + 1 \) splitting of spacetime, the particle’s position and coordinate velocity are denoted as \( y^\mu = (c t, y(t)) \) and \( v^\mu(t) = (c, v(t)) \) (where \( v^\mu = cu^\mu/u^\alpha \), with \( u^0 = 1/\sqrt{-g_{\rho\sigma} v^\rho v^\sigma /c^2} \)), and the spin tensor \( S^{\mu\nu}(t) \) is considered a function of time. From now on, we use boldface letters to denote three-dimensional vectors. We have

\[ T^{\mu\nu}_M = mu^0 v^\mu v^\nu \frac{\delta^3(x - y(t))}{\sqrt{-g(t, x)}}, \]  
\( (2.7a) \)

\[ T^{\mu\nu}_D = -\frac{1}{c} \nabla_\rho \left[ S^{\rho(\mu} v^{\nu)} \frac{\delta^3(x - y(t))}{\sqrt{-g(t, x)}} \right], \]  
\( (2.7b) \)

where \( \delta^3 \) is the three-dimensional Dirac delta function. Making explicit the covariant derivative in the dipolar stress–energy tensor, we obtain an alternative form in terms of ordinary Christoffel symbols:

\[ \sqrt{-g} T^{\mu\nu}_D = -\frac{1}{c} \left( \partial_\rho \left[ S^{\rho(\mu} v^{\nu)} \delta^3(x - y(t)) \right] + S^{\rho(\mu} \Gamma^\nu_{\rho\sigma} v^\sigma \delta^3(x - y(t)) \right). \]  
\( (2.8) \)
Note that in (2.7)–(2.8) the factor $\sqrt{-\hat{g}}$ has the generic field point $(c t, \mathbf{x})$ for argument. Because of the SSC, we may work only with the spatial components $S^{ij}$ of the spin tensor and eliminate the $S^{0i}$ components according to

$$t_0 S^{0i} = -u_{j} S^{ij} + \mathcal{O}(S^3).$$

(2.9)

In paper I, a spin vector was used instead of a spin tensor. First, a spin covector was defined, consistently with the SSC $S^{ii} u_{i} = \mathcal{O}(S^3)$, by

$$S^{ij} = \varepsilon^{ij
\rho
\sigma} u_{\rho} S_{\sigma} + \mathcal{O}(S^3),$$

(2.10)

where $\varepsilon^{\mu
\nu
\rho
\sigma}$ is the Levi–Civita tensor such that $\varepsilon^{0123} = -1/\sqrt{-\hat{g}}$. Then, a spatial spin vector $S_{i\text{BB}}$ was constructed as $\gamma^{ij} S_{i\text{BB}} = \gamma^{ij} S_{j}$, with $\gamma^{ij}$ being the inverse of the spatial part of the metric, i.e. $\gamma^{ik} g_{kj} = \delta^{ij}$. In this paper, we shall mostly work with the spatial components $S^{ij}$ of the spin tensor. This presents two advantages: first, it somewhat simplifies the algebra and the index structure by getting rid of the Levi–Civita tensors, and second, it makes the check of the Lorentz invariance more straightforward, since $S^{ij}$ is directly the spatial components of the tensor $S^{\mu
\nu}$. We provide in the appendix the explicit link between $S^{ij}$ and the spin variable $S_{i\text{BB}}$.

3. Post-Newtonian metric and equations of motion

As in paper I, we use harmonic (or De Donder) coordinates, defined by the gauge condition $\partial_{t} (\sqrt{-\hat{g}} g^{0i}) = 0$. The PN iteration of Einstein’s field equations developed up to 3.5 PN order in [53] is valid for a generic matter source, the only hypothesis being that the stress–energy $\partial_{\nu} (\rho + p) g_{\mu\nu}$ is compact support. We will need here the full 3.5 PN metric, which is parametrized in terms of elementary potentials as

$$g_{00} = -1 + \frac{2}{c^{2}} V - \frac{2}{c^{4}} V^{2} + \frac{8}{c^{6}} \left( \hat{X} + V \hat{V} + \frac{V^{3}}{6} \right) + \frac{32}{c^{8}} \left( \hat{T} - \frac{1}{2} V \hat{X} + \hat{R} V - \frac{1}{2} V V \hat{V} - \frac{V^{4}}{48} \right) + \mathcal{O}(10),$$

(3.1a)

$$g_{0i} = -\frac{4}{c^{3}} V_{i} - \frac{8}{c^{5}} \hat{R}_{i} - \frac{16}{c^{7}} \left( \hat{Y}_{i} + \frac{1}{2} \hat{W}_{ij} V_{j} + \frac{1}{2} V^{2} V_{j} \right) + \mathcal{O}(9),$$

(3.1b)

$$g_{ij} = \delta_{ij} \left[ 1 + \frac{2}{c^{2}} V + \frac{2}{c^{4}} V^{2} + \frac{8}{c^{6}} \left( \hat{X} + V \hat{V} + \frac{V^{3}}{6} \right) \right] + \frac{4}{c^{2}} \hat{W}_{ij} + \frac{16}{c^{4}} \left( \hat{Z}_{ij} + \frac{1}{2} V \hat{W}_{ij} - \hat{V} \hat{V}_{ij} \right) + \mathcal{O}(8).$$

(3.1c)

From now on, spatial indices $i, j, \ldots$ will be raised and lowered using the Kronecker metric $\delta_{ij}$, and we will write them indifferently as upper or lower indices. The potentials are defined by means of the usual retarded ($R$) inverse flat d’Alembertian operator,

$$\left( \Box_{R}^{-1} f \right)(\mathbf{x}, t) = \frac{1}{4 \pi} \int \frac{d^{3} \mathbf{x}'}{|\mathbf{x} - \mathbf{x}'|} f \left( \mathbf{x}', t - \frac{|\mathbf{x} - \mathbf{x}'|}{c} \right),$$

(3.2)

where the sources $f$ are built with the following matter quantities:

$$\sigma = \frac{1}{c^{5}} (T^{00} + T^{ii}), \quad \sigma_{i} = \frac{1}{c} T^{0i}, \quad \sigma_{ij} = T^{ij},$$

(3.3)

4 We denote by $\mathcal{O}(n)$ remainder terms of order $(n/2)$-PN, i.e. behaving as $\mathcal{O}(1/c^{n})$. 5
as well as with the products of derivatives of lower order potentials. The potentials required for the 2.5 PN equations of motion were already used in paper I and read

\[ V = \Box^{-1} [-4\pi G\sigma], \]  

\[ V_i = \Box^{-1} [-4\pi G\sigma_i], \]  

\[ \dot{X} = \Box^{-1} [-4\pi GV_{\sigma \nu} + \hat{W}_{ij} \partial_{ij} V + 2V_{\nu} \partial_{\nu} \partial \partial V + V \partial^2 \partial V + \frac{1}{2} (\partial \partial V)^2 - 2 \partial \partial V \partial \partial V], \]  

\[ \dot{R}_i = \Box^{-1} [-4\pi G(V_{\sigma \nu} - V_{\nu \sigma}) - 2 \partial \partial V \partial \partial V - \frac{1}{2} \partial \partial V \partial \partial V], \]  

while the potentials required for the 3.5 PN order are given as the following definitions:

\[ \dot{T} = \Box^{-1} [-4\pi G(\frac{1}{2} \sigma_{ij} \hat{W}_{ij} + \frac{1}{2} V^2 \sigma_{ij} + \sigma V_{ij}) + \hat{Z}_{ij} \partial_{ij} V + \hat{R}_i \partial \partial V - 2 \partial \partial V \partial \partial V + V \partial^2 \partial V + \frac{1}{2} \partial \partial V \partial \partial V + \frac{3}{2} \partial \partial \partial V \partial \partial V - \frac{1}{2} (\partial \partial V)^2]. \]  

\[ \dot{Y}_i = \Box^{-1} [-4\pi G(-\sigma \hat{R}_i - \sigma V_{ij} + \frac{1}{2} \sigma_{ij} \hat{W}_{ij} + \frac{1}{2} \sigma_{\nu \nu} V_{\nu} + \frac{1}{2} \sigma_{\nu \nu} V_{\nu} + \frac{1}{2} \sigma_{\nu \nu} V_{\nu} + \hat{W}_{ij} \partial \partial V - \frac{1}{2} \partial \partial V \partial \partial V - 2 \partial \partial V \partial \partial V + V \partial^2 \partial V + \frac{3}{2} \partial \partial \partial V \partial \partial V - \frac{1}{2} (\partial \partial V)^2]. \]  

\[ \dot{Z}_{ij} = \Box^{-1} [-4\pi GV(\sigma_{ij} - \sigma_{\nu \nu} V_{\nu} - 2 \partial \partial V \partial \partial V + \hat{V}_{ij} \partial \partial V - \frac{1}{2} \partial \partial \partial V \partial \partial V - 2 \partial \partial V \partial \partial V - \frac{1}{2} \partial \partial \partial V \partial \partial V - \frac{1}{2} (\partial \partial V)^2]. \]  

Note the difference of structure between the sources of these potentials: some sources are proportional to one of the \( \sigma \) quantities and are compact supported, while others are only proportional to metric potentials. We will call the latter non-compact supported, since their source extends in all space.

Next, in keeping with notations of paper I, we rewrite the covariant equation of motion (2.6b) in the following (3 + 1)-form:

\[ \frac{dp_i}{dt} = F_i + \mathcal{F}_i. \]  

The leading order on the left-hand side of the force law (3.5) is simply the ordinary acceleration \( a^i = dv^i/dt \). The Newtonian-like linear momentum and forces are

\[ P_i = g_{i\nu} u^\nu v^\nu, \]  

\[ F_i = \frac{1}{2} \partial \partial g_{\rho \nu} u^\nu v^\rho v^\rho, \]  

\[ \mathcal{F}_i = - \frac{1}{2m} R_{\nu \rho \sigma} v^\nu S^{\rho \sigma}. \]  

With transparent meaning, we shall often call \( F_i \) the ‘geodesic part’ of the force law (or rather the acceleration), while \( \mathcal{F}_i \) will be referred to as the ‘Papapetrou part’, deviating from geodesic motion.
Expanding the metric in terms of the elementary potentials (3.4), one obtains the following 3.5 PN expressions for $P_i$ and $F_i$, which would correspond to the coordinate acceleration of a particle following a geodesic motion:

$$P_i = v'^i + \frac{1}{c^2} \left( \frac{1}{2} v'^2 v'^j + 3v'^i - 4V_i \right)$$

+ \frac{1}{c^5} \left( \frac{3}{8} v'^i v'^j + \frac{7}{2} V v'^2 v'^j - 4V_j v'^i v'^j - 2V^2 v'^i - \frac{9}{2} 2^2 v'^j - 4V_j + 4\hat{W}_j v'^j - \hat{R}_j \right)$$

+ \frac{1}{c^5} \left( \frac{5}{16} v'^i v'^j + \frac{33}{8} V v'^2 v'^j - \frac{3}{2} V^2 v'^i - 6V_j v'^i v'^j + \frac{49}{4} 2^2 v'^j \right)

+ 2\hat{W}_j v'^i v'^j + 2\hat{W}_j v'^i v'^j - 10V v'^i v'^j - 20V_j v'^j - 4\hat{R}_j v'^j - 8\hat{R}_j v'^j + 12\hat{W}_j v'^j + 12V_j v'^j + 12\hat{W}_j v'^j

$$+ 12\hat{X} v'^i + 16\hat{Z}_j v'^j - 10V^2 V_i - 8\hat{W}_j V_j - 8\hat{R}_j - 16\hat{Y} \right) + \mathcal{O}(8), \quad (3.7a)$$

$$F_i = \partial_i V + \frac{1}{c^2} \left( -V \partial_i V + \frac{3}{2} V \partial_j V v'^j - 4\partial_i V v'^j \right)$$

+ \frac{1}{c^5} \left( \frac{7}{8} \partial_i V v'^j - 2\partial_i V_j v'^j v'^j + \frac{9}{2} V \partial_i V v'^j + 2\partial_i \hat{W}_j v'^j v'^j - 4V_j \partial_i V v'^j \right.

$$- 4\hat{V}_j \partial_i V v'^j - 8\hat{R}_j \partial_i V + \frac{1}{2} V^2 \partial_i V + 8V_j \partial_i V_j + 4\partial_i \hat{X} \right)$$

+ \frac{1}{c^5} \left( \frac{11}{16} v'^i v'^j - \frac{3}{2} \partial_i V_j v'^j v'^j + \frac{49}{8} V \partial_i V v'^j + \partial_i \hat{W}_j v'^j v'^j \right.

$$- 2\hat{V}_j \partial_i V v'^j - 20V_j \partial_i V v'^j - 10V^2 \partial_i V v'^j - 8V_j \partial_i \hat{W}_j v'^j - 8\hat{W}_j \partial_i V v'^j - 8\hat{R}_j \partial_i V v'^j - 8V \partial_i \hat{R}_j - 16\partial_j v'^j \$$

$$+ \frac{1}{6} V^3 \partial_i V - 4V_j \partial_i V_j + 16\hat{R}_j \partial_i V_j + 16V_j \partial_i \hat{R}_j

- 8V_j \partial_i V_j - 4\hat{X} \partial_i V - 4V \partial_i \hat{X} + 16\partial_i \hat{R} \right) + \mathcal{O}(8). \quad (3.7b)$$

Specializing now to our problem, when computing for instance the equations of motion for body 1, the velocity $v'$ is to be replaced by $v'_1$ and the right-hand sides are to be evaluated at $y_1$. However, beware of the fact that the metric potentials are generically singular at the location of the two particles 1 and 2 where they are meant to be evaluated. This evaluation is thus given a sense through the Hadamard ‘partie finie’ regularization procedure explained in [54], which is of course to be performed after computing the derivatives of the potentials. We adopt the so-called pure Hadamard–Schwartz prescription [45] for the practical implementation of this regularization. In particular, we use the distributive rule for computing regularizations of products of potentials in equations (3.7), writing

$$\left(AB\right)_1 = \left(A\right)_1 \left(B\right)_1,$$  \quad (3.8)

for $A, B$ among (possibly derivatives of) metric potentials. The other ingredient of this regularization is the Schwartz distributional derivative which is used for source terms to be
Table 1. First line: the different spin parts (S) of potentials to be computed. Second line: the highest
PN order required for the spin part of the potentials. Third line: for which potentials an all-space
(A.S.) computation of the non-compact support part is possible with known techniques; and, if not,
which are the derivatives of potentials that have to be computed directly using the regularization in
4.4. Note that A.S. computations of \( \hat{\chi}^S \) and \( \hat{R}^S \) at the previous PN order \( \mathcal{O}(1) \) are possible and
have been checked to be consistent with the regularized versions.

| Potential | \( Y^S \) | \( V_i^S \) | \( \hat{\chi}^S \) | \( \hat{R}^S \) | \( \hat{W}_{ij}^S \) | \( \hat{T}^S \) | \( \hat{Y}_i^S \) | \( \hat{Z}_{ij}^S \) |
|-----------|---------|---------|---------|---------|---------|---------|---------|---------|
| Order     | \( \mathcal{O}(7) \) | \( \mathcal{O}(5) \) | \( \mathcal{O}(3) \) | \( \mathcal{O}(3) \) | \( \mathcal{O}(3) \) | \( \mathcal{O}(1) \) | \( \mathcal{O}(1) \) | \( \mathcal{O}(1) \) |
| Computation | A.S. | A.S. | \( (\partial, \hat{\chi})_1 \) | \( (\hat{R}_1, (\partial, \hat{\chi})_1) \) | A.S. | \( (\partial, \hat{T})_1 \) | \( (\hat{Y}, (\partial, \hat{T})_1) \) | A.S. |

integrated in equation (3.2), in the form of the Gel’fand–Shilov formula valid for homogeneous
functions, as given by equations (4.3)–(4.4).

In this work, we restrict ourselves to contributions to the coordinate acceleration that
are of linear order in spins. Considering equation (3.3), these linear-in-spin contributions to
the geodesic part of the acceleration can have two origins at this level: first, from the spin
ccontributions to the elementary metric potentials (3.4), which we will have to compute at
the required order, and secondly, from the time derivative \( \partial p_i/\partial t \), since it is understood that
order-by-order replacements of the accelerations are to be performed, which include in turn
spin contributions starting at \( \mathcal{O}(3) \). Table 1 indicates which spin parts of metric potentials
are needed at which order, for the present computation of the next-to-next-to-leading order
spin–orbit contributions to the equations of motion. As explained in section 4, some potentials
were computed in all space, but for the most nonlinear ones, only their regularized values at
the location of one of the particles could be computed. In the latter case, the calculation is
different for each different derivative structure of the potential, and table 1 gives the list of
these needed derivatives.

On the other hand, the effective Papapetrou part of the acceleration or force \( \mathcal{F}' \), which
corresponds to non-geodesic motion, can be found in paper I up to 2.5 PN order in terms of
the spin variable \( S_{iBB} \). We give here its complete expression up to 3.5 PN order, in terms of
the spin tensor \( S^{iJ} \) and the various metric potentials. Defining

\[
m\mathcal{F}' = \frac{1}{c^2} f_1^5 + \frac{1}{c^3} f_2^5 + \frac{1}{c^4} f_3^5 + \mathcal{O}(9),
\]

and expanding the Riemann tensor in equation (3.6c) in terms of metric components,
they themselves expanded in terms of the elementary potentials (3.4), we obtain

\[f_1^5 = S^{iJ} \left( \partial^i \partial_j V + v^k \partial_k \partial_j V \right) + S^{jk} \left( 2v^k \partial_i \partial_j V - 2\partial_i \partial_j V \right), \tag{3.10a}\]

\[f_2^5 = S^{iJ} \left( -v^k \partial_j \partial_k V + 2V \partial_k \partial_j V + 2v^k \partial_j \partial_k V + 2v^l \partial_k \partial_l V \right) \]
\[+ \partial_j \partial_k V + 2V \partial_k \partial_j V + v^l \partial_k \partial_l V + \partial_i \partial_j \partial_k V - 2v^l \partial_k \partial_l V \]
\[+ S^{jk} \left( 4v^l \partial_k \partial_l V - 3v^l \partial_k \partial_l V - 4v^l \partial_k \partial_l V + 4\partial_k \partial_l V - 4V v^l \partial_k V \right) \]
\[+ 4V \partial_k \partial_l V + 2v^l \partial_k \partial_l V - 2v^l \partial_k \partial_l V + 2v^l \partial_k \partial_l V \]
\[+ 2v^l \partial_k \partial_l V - 2v^l \partial_k \partial_l V + 2\partial_k \partial_l V \right), \tag{3.10b}\]

\[f_3^5 = S^{iJ} \left( 4\partial_j \partial_k \partial_l V - 2V v^l \partial_j \partial_k \partial_l V + 4V \partial_l \partial_j \partial_k V + 8v^l \partial_j \partial_k \partial_l V + 2V^2 v^l \partial_k \partial_l V \right) \]
\[+ 8v^l \partial_j \partial_k \partial_l V + 4v^l \partial_j \partial_k \partial_l V + 4v^l \partial_j \partial_k \partial_l V - 4V \partial_l \partial_j \partial_k V \]
\[+ 2v^l \partial_j \partial_k \partial_l V + 2v^l \partial_j \partial_k \partial_l V - 2v^l \partial_j \partial_k \partial_l V + 2v^l \partial_j \partial_k \partial_l V \]
\[+ 2V \partial_j \partial_k \partial_l V - 2v^l \partial_j \partial_k \partial_l V + v^l \partial_k \partial_l V \right), \tag{3.10c}\]
If we are computing the Papapetrou acceleration of body 1, \( F^j_1 \), then we have to replace in the latter expressions \( S^j \) by \( S^j_1 \) and \( v_j \) by \( v^j_1 \). Because of the explicit spin factor, at linear order in spins only the non-spin (NS) parts of the potentials are needed, and \( S^j_2 \) does not appear in this part of the acceleration. The factor \( m \equiv m_1 \) in equation (3.9) is at the origin of all terms depending on the spins by unit mass, i.e. through \( S^j_1 / m_1 \) or \( S^j_2 / m_2 \) in the final results. Note that terms with two velocities appear in equations (3.10) because of the replacement of \( S^j_1 \) by \( S^j_1 \) according to (2.9). Again all products of singular potentials have to be regularized following the rule of the pure Hadamard–Schwartz regularization, notably the distributivity rule \((3.8)^5\). However, we shall find in section 5 that the computation of the value at 1 of one particular potential, namely \( \partial_{\hat{y}_i} Y_i \), which is especially singular, \( a \text{ priori} \) requires the use of dimensional regularization.

As we said, since the Papapetrou part of the acceleration already includes an explicit spin factor, only the NS parts of the potentials are required there, and most of these have already been computed in previous works such as [55, 53]. Notable exceptions are the second spatial derivatives of the potentials \( \hat{R}_i \) and \( \hat{Y}_i \), which are defined in equations (3.4); we address the computation of these new regularized potentials in sections 4 and 5.

4. Hadamard regularization of potentials

4.1. Notation and general points

Throughout the rest of this paper, we use the following notation. The trajectories of the two bodies, with masses \( m_1 \) and \( m_2 \) and spin tensors \( S^j_1 \) and \( S^j_2 \), are denoted \( y_1(t) \) and \( y_2(t) \), and their coordinate velocities \( v_1(t) \) and \( v_2(t) \). The inter-body distance is \( r_{12} = |y_1 - y_2| \), and we set \( n_{12} = (y_1' - y_2')/|y_1 - y_2| \). For a generic field point \( x \), we pose \( r_1 = |x - y_1| \),

\[
\begin{align*}
+ 8v \bar{V}_i \partial_{\hat{y}_i} V_j + 4v^j \partial_{\hat{y}_i} V_j &+ 2 \bar{V}_i \hat{V}_j + 2V^2 \partial_{\hat{y}_i} V_j + 8V \partial_{\hat{y}_i} \hat{V}_j \\
+ 4 \partial_{\hat{y}_i} \hat{X} + 6V v \partial_{\hat{y}_i} V_j &- 4 \bar{V}_i \partial_{\hat{y}_i} V_j + 6V v \partial_{\hat{y}_i} V_j - 4V \partial_{\hat{y}_i} V_j \\
+ S^j \left(-8V \partial_{\hat{y}_i} \hat{V}_j + 8V \partial_{\hat{y}_i} \hat{V}_j + 8V v \partial_{\hat{y}_i} V_j &+ 8v^j \partial_{\hat{y}_i} V_j - 12v \partial_{\hat{y}_i} \hat{V}_j - 8 \bar{V}_i \partial_{\hat{y}_i} V_j \\
- 4v \partial_{\hat{y}_i} V_j &+ 4 \partial_{\hat{y}_i} V_j \hat{W}_j + 4V \partial_{\hat{y}_i} \hat{W}_j + 4v \partial_{\hat{y}_i} \hat{W}_j + 8 \bar{R}_i \partial_{\hat{y}_i} V_j \\
- 4V^2 v \partial_{\hat{y}_i} V_j &+ 8V v \partial_{\hat{y}_i} V_j + 4v^j \partial_{\hat{y}_i} V_j - 8v \partial_{\hat{y}_i} \hat{V}_j + 4V \partial_{\hat{y}_i} \hat{V}_j \\
&+ 8v \partial_{\hat{y}_i} \hat{V}_j + 8V v \partial_{\hat{y}_i} V_j - 16v \partial_{\hat{y}_i} \hat{V}_j - 4V v \partial_{\hat{y}_i} \hat{V}_j \\
&+ 4V \partial_{\hat{y}_i} \hat{W}_j - 8v \partial_{\hat{y}_i} \hat{X} + 8v \partial_{\hat{y}_i} \hat{Y}_j - 8v \partial_{\hat{y}_i} \hat{Z}_j - 4v \partial_{\hat{y}_i} V_j - 4v \partial_{\hat{y}_i} V_j - 4v \partial_{\hat{y}_i} V_j - 4v \partial_{\hat{y}_i} V_j \\
&+ 4v \partial_{\hat{y}_i} V_j - 4 \partial_{\hat{y}_i} \hat{V}_j + 4V \partial_{\hat{y}_i} \hat{V}_j + 8v \partial_{\hat{y}_i} \hat{V}_j - 8V v \partial_{\hat{y}_i} \hat{V}_j \\
&- 8v \partial_{\hat{y}_i} \hat{V}_j + 8v \partial_{\hat{y}_i} \hat{V}_j + 8v \partial_{\hat{y}_i} \hat{V}_j + 4v \partial_{\hat{y}_i} \hat{V}_j + 8v \partial_{\hat{y}_i} \hat{V}_j \\
&- 4v \partial_{\hat{y}_i} \hat{V}_j - 4v \partial_{\hat{y}_i} \hat{V}_j - 4V \partial_{\hat{y}_i} \hat{V}_j + 4V \partial_{\hat{y}_i} \hat{V}_j - 8V \partial_{\hat{y}_i} \hat{V}_j - 8V \partial_{\hat{y}_i} \hat{V}_j \\
&+ 2v \partial_{\hat{y}_i} \hat{V}_j + 2v \partial_{\hat{y}_i} \hat{V}_j + 2v \partial_{\hat{y}_i} \hat{V}_j - 2v \partial_{\hat{y}_i} \hat{V}_j + 2v \partial_{\hat{y}_i} \hat{V}_j \right). \tag{3.10c}
\end{align*}
\]
\(n'_i = (x' - y'_i)/|x - y_i|\) and similarly for 2. We denote by \(\bar{a}, \bar{a}'\) and \(\bar{a}''\) the partial derivative with respect to \(x', y'_1\) and \(y'_2\). The symbol \(1 \leftrightarrow 2\) means the expression obtained by the exchange of the two particles. Lengthy calculations are performed with the help of the scientific software Mathematica\textsuperscript{\textregistered}, supplemented by the package xTensor [56] dedicated to tensor calculus.

We systematically expand the retardations inside the retarded integral (3.2), truncated to the appropriate order. For instance, truncating at \(\mathcal{O}(3)\), we have

\[
-4\pi \square_R^{-1} f(x, t) = \int \frac{d^3 \mathbf{x}'}{|x - \mathbf{x}'|} f(\mathbf{x}', t) - \frac{1}{c} \int d^3 \mathbf{x}' \partial_t f(\mathbf{x}', t) + \frac{1}{2c^2} \int d^3 \mathbf{x}' |x - \mathbf{x}'| \partial^2_t f(\mathbf{x}', t) + \mathcal{O}(3).
\]

In this expression, time derivatives may be pulled out of the integrals, and it is understood that accelerations and time derivatives of the spin are to be replaced by the already computed lower order equations of motion and spin precession equations. Note that the second term in this expansion has no dependence to the field point \(x\).

Next, note that we are using Dirac delta functions in the stress–energy momentum tensor (2.7), while it makes no sense as a distribution à la Schwartz when acting on the class of general functions in the problem, which are generically singular at the locations of the two particles. We refer to [53] for a complete discussion of this issue, which was dealt with by defining a class of ‘pseudo-functions’ and using Hadamard regularization to define the value of a singular function at one of its singular points. In our case, we will give a sense to Dirac delta functions inside integrals, following the rule

\[
\int d^3 \mathbf{x} F(\mathbf{x}) \delta_1 = (F)_1, \quad (4.2a)
\]

where \(\delta_1 = \delta(\mathbf{x} - \mathbf{y}_1)\) and \((F)_1\) means the Hadamard ‘partie finie’ of \(F\) at the point \(\mathbf{y}_1\) [54]. This rule is extended in an obvious way to the derivatives of delta functions, for instance

\[
\int d^3 \mathbf{x} F(\mathbf{x}) \partial_1 \delta_1 = - (\partial_1 F)_1. \quad (4.2b)
\]

Other issues are the problem of distributivity of the partie finie already mentioned, and the treatment of the distributional parts of derivatives. Here, we shall not use the ‘extended Hadamard regularization’ introduced in [54]; instead, we will apply primarily the ‘pure Hadamard–Schwartz’ prescription described in [45] which is sufficient for most of our computations. The pure Hadamard–Schwartz regularization constitutes the core of the most powerful and fundamental regularization procedure which is dimensional regularization and has been successfully applied to the problem of the equations of motion in [45, 57]. Thus, in principle, the result of the pure Hadamard–Schwartz regularization of Poisson-type integrals is to be supplemented by a contribution from dimensional regularization which appears when the integral develops a pole \(\propto 1/(d - 3)\) in the dimension. The pole corresponds to the appearance of logarithmic divergences in the Hadamard regularization (see section 4.4). Here, we stick to the pure Hadamard–Schwartz prescription for the computation of the spin parts of potentials, where no problematic logarithms appear and where we expect that there is no difference between the extended Hadamard or pure Hadamard–Schwartz regularizations and the dimensional regularization (as it was the case up to 2.5 PN order in the NS equations of motion [55]). On the other hand, as already mentioned we do use dimensional regularization for one particular potential in the Papapetrou part of the equations of motion, as discussed in section 5.

For the distributional part of derivatives of singular functions, we employ a particular form of the Gel’Fand–Shilov formula valid for homogeneous functions. Denoting by \(\vartheta\) the full derivative, including the distributional part, and by \(\vartheta_1^{\text{ord}}\) the ordinary part, which also acts
on the Dirac delta functions, we obtain, in the relevant cases of double derivatives and a simple function of type $n^i/r^{nm}$ (which is homogeneous of degree $-m$),

$$
\partial_{ij} f = \partial_{ij}^{\text{dis}} f + D_i \partial_{ij}^{\text{ord}} f + \partial_{ij}^{\text{ord}} D_i f, \quad (4.3)
$$

where the distributional part is given when $\ell + m$ is an odd integer by

$$
D_i \left( \frac{n^i}{r^{nm}} \right) = -4\pi \frac{(-)^m (\ell + 1)!^{(\ell + m - 1)/2} \sum_{p=p_0}^{[m/2]} \Delta^{p-1} \partial_{AM} \delta_{L-2p} \delta_{L+2p-M}}{(\ell + m)!}.
$$

and is zero when $\ell + m$ is even. In the present context, we apply formulae (4.3)–(4.4) to the expansion of a singular function $f$ around the two singularities $y_1$ or $y_2$.

### 4.2. Leading-order potentials

We first deal with the lowest order potentials, namely the computation of the leading spin–orbit part of the potentials $V$, $V_i$, and $\hat{W}_{ij}$. We give all the results for completeness, translating results from paper I in terms of the spin tensor $S^j$. By explicitly the expression of the dipolar part (2.8) of the stress–energy tensor, one may check that the leading order for the spin part of the sources $\sigma$, $\sigma_i$, and $\sigma_{ij}$ is

$$
\sigma^S = 2 \frac{S^j v^j}{c^2} \frac{1}{r_1} \partial_1 + 1 \leftrightarrow 2 + \mathcal{O}(5),
$$

$$
\sigma_i^S = \frac{1}{2c} S^j v^j \partial_i \frac{1}{r_1} + 1 \leftrightarrow 2 + \mathcal{O}(3),
$$

$$
\sigma_{ij}^S = -\frac{1}{c^2} (\delta^j_i v^j - \delta^i_j v^j) d_1 \frac{1}{r_1} + 1 \leftrightarrow 2 + \mathcal{O}(3),
$$

where $(ij)$ indicates symmetrization, $d_1$ stands for $\delta(x - y_1)$ and the gradients are taken with respect to the field point $\mathbf{x}$. Given these expressions for the sources of potentials, and using $\Delta(1/r_1) = -4\pi \delta_1$ (with $r_1 = |x - y_1|$), equations (4.5) then yield

$$
V^S = \frac{2G}{c^2} S^j v^j \frac{1}{r_1} + 1 \leftrightarrow 2 + \mathcal{O}(5),
$$

$$
V_i^S = \frac{G}{2c} S^j v^j \frac{1}{r_1} + 1 \leftrightarrow 2 + \mathcal{O}(3),
$$

$$
\hat{W}_{ij}^S = -\frac{G}{c} (\delta^j_i v^j - \delta^i_j v^j) \partial_k \frac{1}{r_1} + 1 \leftrightarrow 2 + \mathcal{O}(3).
$$

Note that the leading-order of the spin part of these potentials has the typical dipolar structure $\Delta(1/r)$, while it is simply $1/r$ (monopolar) for the NS part. Note also the important fact that $V^S$ starts at $\mathcal{O}(3)$ and has no $\mathcal{O}(1)$ contribution. This makes the structure of the spin part of potentials different from the one of the NS part, and shifts a number of contributions to higher PN order. In particular, the non-compact support part of $\hat{W}_{ij}^S$, coming from $\square^{-1}_R \left(-\partial_i V \partial_j V\right)$, starts only at $\mathcal{O}(3)$ and not $\mathcal{O}(1)$. This in turn implies that the leading order of $\hat{W}_{ij}^S$ has the simpler structure of a compact-supported term, which makes a number of sources of higher potentials less nonlinear, such as the non-compact-supported term $\square^{-1}_R (\hat{W}_{ij} v^j) V$ in $\hat{X}^S$.

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6 Here we pose $p_0 = \max\{1, (m - \ell - 1)/2\}$, and $[m/2]$ means the integer part. Notation for multi-indices is for instance $L = j_1 j_2 \cdots j_k$, i.e., $L$ is the number of indices on $n^i = n^{i_1} \cdots n^{i_k}$. We denote $\delta_{i_1} = \delta_{j_{k+1}} \cdots \delta_{j_{2k+1}}$, where $2k = \ell + 2p - m + 1$ is the number of indices in the multi-index $iL + 2p - M$. The parenthesis refer to the complete symmetrization of indices.
4.3. Higher order compact-support terms

We turn now to the higher order PN computation of the compact-supported parts of potentials, i.e. whose sources include $\sigma$, $\sigma_i$ or $\sigma_{ij}$. We will take the potentials $V^S$ as an example and give only a schematic view of these computations, since their implementation is relatively straightforward. By expliciting expression (2.8) of the stress–energy tensor, we obtain the following structure for the compact-supported sources:

$$\sigma_i(x, t) = \tilde{\mu}_{1M} \delta_1 + \frac{1}{\sqrt{-g(x)}} \mu_{1D} \delta_1 + \frac{1}{\sqrt{-g(x)}} \delta_i (v_{1D} \delta_1) + \frac{1}{\sqrt{-g(x)}} \delta_i (v_{1D} \delta_1),$$  

(4.7)

indifferently for bodies 1 and 2, where the subscripts M and D refer to the monopolar and dipolar parts of the stress–energy tensor, respectively. The quantity $\tilde{\mu}_{1M}$ already intervenes in the study of the equations of motion without spin, and its 3.5 PN expression in terms of the metric potentials is given in equation (4.3) of [58]. Next, we Taylor expand the retardations (4.1) for each term. The time derivatives are pulled out of the integrals, which are then evaluated using the rules (4.2) for the delta functions and their derivatives, keeping in mind that the factors $1/\sqrt{-g}$ in (4.7) depend on the field point $x$.

As a check of the method, we also computed all the compact-support parts of the spin potentials using a fully non-distributive prescription, i.e. keeping the dependence in the field point $x$ as long as possible (also when evaluating the quantities such as $v_{1D}$), and taking the Hadamard partie finie at the very end of the calculation. We obtained no difference with the pure Hadamard distributive prescription (3.8).

Note that $V^S$, for instance, obtains contributions from both the dipolar and monopolar parts of the stress–energy tensor. For the dipolar part, the quantities $\tilde{\mu}_{1D}$, $v_{1D}$ and $v_{1D}'$ all display an explicit spin factor. For the monopolar part, spin terms appear indirectly in two ways: through the spin contributions to the metric potentials in the expression of $\tilde{\mu}_{1M}$ and through the acceleration replacements when evaluating time derivatives.

4.4. Non-compact support terms

The non-compact supported potentials are more complicated, since their source is itself made of potentials and does not allow the simple integration procedure with delta functions. However, if the source has a simple structure, some integrations can be computed explicitly to obtain a solution valid for a generic field point $x$. One encounters often the source structure $\partial (1/r) \partial^2 (1/r)$, which arises at leading order in all $\partial A^{\alpha \beta} \partial B^{\gamma \delta}$ terms, where $A$ and $B$ are chosen among $\{V, V_i\}$ and $\{V, V, W_{ij}\}$, respectively, as can be checked from the leading-order structure (4.6). Using the same techniques as in previous works (e.g. [55, 53]), in particular using the function $g$ such that

$$\Delta g = \frac{1}{r_1 r_2},$$  

(4.8a)

$$g \equiv \ln (r_1 + r_2 + r_{12}),$$  

(4.8b)

we find the following relations:

$$\Delta^{-1} \left[ \frac{1}{r_1} \right] \partial_{j \ell} \left[ \frac{1}{r_1} \right] = \frac{1}{16} \left[ \frac{1}{r_1} \partial_{j \ell} \ln (r_1) + (\delta^{ij} \partial_k + \delta^{ij} \partial_k - \delta^{jk} \partial_i) \left( \frac{1}{r_1^2} \right) \right],$$  

(4.9a)

$$\Delta^{-1} \left[ \frac{1}{r_1} \right] \partial_{j \ell} \left[ \frac{1}{r_2} \right] = -\delta_{j \ell} g,$$  

(4.9b)

where for instance $\frac{1}{r_1} \partial_{j \ell} = \partial / \partial y_{j \ell}$. With these relations in hand, completing the results for the compact-support parts, we are able to straightforwardly compute the leading order $\mathcal{O}(1)$ of $\tilde{X}^S, R^S_\ell, \tilde{Z}^S_{ij}$, as well as the 1 PN relative order $\mathcal{O}(3)$ of $W^3_{ij}$, as indicated in table 1.
We now turn to the computation of the partie finie of Poisson integrals, of the types of the first and third terms in (4.1)\(^7\). When direct integration is not possible (at least using known results) for the non-compact support part of nonlinear potentials, one by-passes the difficulty by directly computing the Hadamard regularized value of the integral at the points \(y_1\) or \(y_2\). By doing so, one will not have access to the full information about the potentials (hence the metric) everywhere in space, but only the information relevant for the computation of the equations of motion. Since the computation is different for each derivative of the potential, one has to figure out which derivatives of which potential will be needed in the final computation. Table 1 already gave the required spin parts of potentials. Furthermore, we find that two new NS potentials, featuring two derivatives, have to be computed in addition to known previous results [53]:

\[
(\partial_\mu \hat{R}^{NS})_1 \text{ to order } \mathcal{O}(2), \quad \text{and} \quad (\partial_\mu \hat{Y}^{NS})_1 \text{ to order } \mathcal{O}(0).
\]

(4.10)

Following [54] (to which we refer for details and definitions), we define generic Poisson integrals and twice-iterated Poisson integrals:

\[
P(x) = -\frac{1}{4\pi} \text{Pf} \int \frac{d^3x'}{|x - x'|} F(x'),
\]

(4.11a)

\[
Q(x) = -\frac{1}{4\pi} \text{Pf} \int d^3x |x - x'| F(x'),
\]

(4.11b)

where the source \(F\) is singular at \(y_1\) and \(y_2\). The symbol Pf stands for the Hadamard partie finie for integrals diverging near the particle locations. This regularization procedure consists in removing from the integration domain two spherical balls of radius \(s\) surrounding the two singularities, subtracting the purely divergent part and taking the limit \(s \to 0\). The partie finie regularization depends on two arbitrary constants \(s_1\) and \(s_2\) (see [54]). The results for the extended Hadamard partie finie (in the sense of equations (5.3)–(5.4) in [54]) of the Poisson potentials \(P\) and \(Q\) are

\[
(P)_1 = -\frac{1}{4\pi} \text{Pf} \int \frac{d^3x}{r_1} F(x) + \left[ \ln \left( \frac{r_1}{s_1} \right) - 1 \right] (r_1 F)_1,
\]

(4.12a)

\[
(Q)_1 = -\frac{1}{4\pi} \text{Pf} \int d^3x r_1 F(x) + \left[ \ln \left( \frac{r_1}{s_1} \right) + \frac{1}{2} \right] (r_1 F)_1,
\]

(4.12b)

\[
(\partial P)_1 = -\frac{1}{4\pi} \text{Pf} \int \frac{d^3x n_i}{r_1^{i+1}} F(x) + \ln \left( \frac{r_1}{s_1} \right) \left( r_1 n_i F \right)_1,
\]

(4.12c)

\[
(\partial Q)_1 = \frac{1}{4\pi} \text{Pf} \int d^3x n_1 F(x) - \left[ \ln \left( \frac{r_1}{s_1} \right) - \frac{1}{2} \right] \left( r_1 n_1 F \right)_1.
\]

(4.12d)

In these formulae, the first term would correspond to the naive prescription of taking directly \(x = y_1\) inside the integrals (4.11), and the second term features a regularization constant \(\ln(r_1)\) coming from the singular limit \(x' \to y_1\). Note that the constant \(s_1\) automatically cancels between the two terms, while the Pf term may induce a dependence on \(s_2\), so that the result depends on two constants \(r_1\) and \(s_2\). For this work, we had to extend these formulae to

---

\(^7\) Pure spatial integrals like the second term of (4.1), where the integrand is independent of \(x\), are computed using the Hadamard prescription for singular integrals, following the procedure described in [54].
the case of a double gradient, in order to compute the potentials (4.10). Using the same method as in [54], we obtained the corresponding required expressions for the double derivative

\[(\partial_j F)_1 = -\frac{1}{4\pi} \mathcal{P} \int d^3 x \frac{3n_{1j} - \delta_{ij}}{r_1^3} F(x) + \ln \left( \frac{r_1'}{s_1'} \right)((3n_{1j} - \delta_{ij})F) + \frac{1}{3} \delta_{ij}(F)_1, \quad (4.13a)\]

\[(\partial_j Q)_1 = -\frac{1}{4\pi} \mathcal{P} \int d^3 x \frac{\delta_{ij} - n_{1ij}}{r_1} F(x) + \left[ \ln \left( \frac{r_1'}{s_1'} \right) + \frac{1}{2} \right]((\delta_{ij} - n_{1ij}r_1^2)F)_1 - \delta_{ij}(r_1^2 F)_1, \quad (4.13b)\]

One readily checks that these expressions yield the correct results when contracted with \(\delta_{ij}\), namely \((\Delta F)_1 = 0 \quad \text{and} \quad (\Delta Q)_1 = 2(P)_1\). Crucial for this check, note the last term in equation (4.13a) which stems from a distributional contribution obtained when evaluating the two derivatives under the integral (4.11a). It can be absorbed by replacing, in the first term of (4.13a), the ordinary factor \((3n_{1j} - \delta_{ij})/r_1^3\) by the distributional derivative \(\delta'_{ij}/r'_1\).

With these tools in hand, we were able to compute all the needed non-compact support parts of potentials. Importantly, we obtain no contribution of the singular parts proportional to \(\ln(r'_1)\) in equations (4.12), in any of the spin parts of potentials listed in table 1. This gives a strong indication that the Hadamard regularization (actually the pure Hadamard–Schwartz version of it) is sufficient to deal with all spin parts of potentials. This is not surprising because the calculation we are doing is only of 2 PN relative order, while past experience in the NS case [55, 53] says that Hadamard’s regularization fails no earlier than at 3 PN relative order.

5. Dimensional regularization for one potential

By contrast, we have found that in the Papapetrou part of the acceleration, which is specific to the spin case (and outside past experience), we do obtain a contribution proportional to \(\ln(r'_1)\) in one of the new evaluations we had to perform, namely when computing the double-derivative potential \((\partial_j \partial_k Y_{NS})\) at Newtonian order using equation (4.13a). All the other NS potentials, including the other new one \((\partial_j \partial_k Y_{NS})\), we had to compute, could be safely obtained with the Hadamard regularization of section 4.

The appearance of this \(\ln(r'_1)\) tells us, on the contrary, that Hadamard’s regularization is insufficient for the potential \((\partial_j \partial_k Y_{NS})\), and that we a priori need dimensional regularization in order to get rid of possible ambiguities in the final equations of motion, as was the case of the NS 3 PN equations of motion in [45, 53]. On the other hand, when considering directly the Papapetrou contribution to the acceleration, we see that the dangerous contribution exists in only one term, with the index structure \(S^j_k \left( \partial_j \partial_k Y_{NS} \right)\), and we find that the problematic logarithms \(\ln(r'_1)\) cancel out in the final result because of the antisymmetry of \(S^j_k\). Therefore, we expect beforehand the pole \(\propto (d - 3)^{-1}\) we shall obtain in dimensional regularization to actually vanish in the final acceleration. Nevertheless, even though the result will be pole-free, we know that the finite part \(\propto (d - 3)^0\) should play a crucial role, and therefore we must a priori apply the powerful but tedious procedure of dimensional regularization to the problematic potential \((\partial_j \partial_k Y_{NS})\).

We refer to [45] for precise definitions and technical details about the method, which consists in studying the problem in \(d\) spatial dimensions, treating \(d\) as a complex variable and taking the analytical continuation of the obtained results when \(d \to 3\). We will associate a superscript \((d)\) to quantities which are defined in this \(d\) dimensional setting. One considers a
class of functions regular everywhere except at the points \(y_1\) and \(y_2\), and admitting expansions of the type \((\forall N \in \mathbb{N})\)

\[
F^{(d)}(x) = \sum_{p_0 \leq p \leq N} r^{p+q}_{1,p} f_{1,p}^{(e)}(n_1) + o(r^N_1),
\]

(5.1)

and similarly around \(y_2\), with \(\varepsilon \equiv d - 3\) and \(q_0, q_1, p_0 \in \mathbb{Z}\). As long as there are no terms in these expansions with both \(p < 0\) and \(q = 0\), and that there is no angular dependence of the \(p = 0, q = 0\) term in the expansion, which is always the case in practice, the presence of the factor \(r^{\varepsilon}_{1,p}\) allows one to write, by application of the analytical continuation on \(\varepsilon\):

\[
(F^{(d)} G^{(d)})(y_1) = F^{(d)}(y_1) G^{(d)}(y_1),
\]

(5.2a)

\[
F^{(d)}(x) \delta^{(d)}(x-y_1) = F^{(d)}(y_1) \delta^{(d)}(x-y_1),
\]

(5.2b)

which justifies the use of distributivity in our previous Hadamard three-dimensional computations. Indeed, it was checked in previous work [45] on the 3 PN NS equations of motion that the pure Hadamard prescription agreed with the \(d \to 3\) limit of the dimensional prescription for all the terms except those developing a pole. As explained in section 4.3, although we did not perform a full dimensional regularization computation of all quantities to be evaluated at \(y_1\) or \(y_2\), we checked that distributive and fully non-distributive prescriptions for the computation of compact-supported potentials yielded the same final result, which gives us confidence in this distributive prescription\(^8\).

The treatment of Poisson integrals such as (4.11) goes as follows. Defining \(P^{(d)}(x)\) as

\[
P^{(d)}(x) = -\frac{k}{4\pi} \int \frac{d^d x'}{|x-x'|^{d-2}} F^{(d)}(x'),
\]

(5.3)

where \(k \equiv \Gamma(d-2)/\pi^{d+2}\), analytical continuation allows us to take derivatives under the integral, to set apart the distributional contribution and to make directly the replacement \(x \to y_1\) under the remaining integral. We obtain

\[
(\partial_{ij} P^{(d)}(y_1)) = -\frac{k}{4\pi} (d-2) \int d^d x \frac{d n_{ij} - \delta_{ij}}{r^3_1} F^{(d)}(x) + \frac{\delta_{ij}}{d} F^{(d)}(y_1),
\]

(5.4)

where the second term on the right-hand side corresponds to the distributional contribution. It reads \(F^{(d)}(y_1) \equiv f^{(e)}_{0,0}\), according to the expansion (5.1), and must not have any angular dependence (since dimensional regularization does not include angular averaging in its definition, unlike Hadamard’s \(partie\ finie\)). We set here all the terms \(r^{\varepsilon}_{1,p} f^{(e)}_{0,q}(n_1)\) with \(q \neq 0\) to 0 since they are cancelled by analytical continuation (and have in general an angular dependence). We also assume that \(f^{(e)}_{0,0}\) has no pole in \(\varepsilon\) which is true, since no poles are generated at the level of the sources of potentials for this calculation.

When \(d \to 3\), we have \(F^{(d)} \to F\), where \(F\) is the corresponding function in the Hadamard three-dimensional context. That function admits the expansion

\[
F(x) = \sum_{p_0 \leq p \leq N} r^{p}_{1} f_{1,p}(n_1) + o(r^N_1).
\]

(5.5)

The Hadamard \(partie\ finie\) of the function is defined by the angular average over the unit direction \(n_1\) of the term \(p = 0\), say

\[
(F)_1 = \langle f_{0}(n_1) \rangle.
\]

(5.6)

\(^8\) Within the dimensional regularization scheme, distributional derivatives can be treated as Schwartz distributional derivatives, e.g. using Gel’Fand–Shilov formulae in \(d\) dimensions.
The three-dimensional coefficients $f_1 f_p(n_i)$ are related to the $\epsilon \to 0$ limits of the $d$-dimensional coefficients $f_{1,p,q}^{(3)}(n_i)$ appearing in equation (5.1) by
\[
f_{1,p}(n_i) = \sum_{q_0 \leq q \leq q_1} f_{1,p,q}^{(0)}(n_i),
\] (5.7)
which in turn gives us the link between the analytical continuation when $d \to 3$ of $F^{(d)}(y_1)$ and the Hadamard partie finie $(F)'_1$:
\[
(F)'_1 = F^{(3)}(y_1) + \sum_{q_0 \leq q \leq q_1} \{f_{1,0,q}^{(0)}(n_i)\}.
\] (5.8)

Next, we address the link between the Hadamard-regularized Poisson integral (4.11) and its dimensional regularization version (5.3). Defining
\[
\mathcal{D}(\partial_j P)(1) = (\partial_j P^{(d)}(y_1)) - (\partial_j P)_1,
\] (5.9)
and following the same steps as in [45], we obtain, working at the zeroth order in $\epsilon$,
\[
\mathcal{D}(\partial_j P)(1) = -\frac{1}{\epsilon} \sum_{q_0 \leq q \leq q_1} \left(\frac{1}{q} + \epsilon \ln r_1^j\right) [(d n_1^j - \delta^j) f_{1,0,q}^{(1)}] - \frac{1}{\epsilon (1 + \epsilon)} \sum_{q_0 \leq q \leq q_1} \left(\frac{1}{q + 1} + \epsilon \ln s_2 \right) \sum_{\ell = 0}^{+\infty} (-\epsilon)^\ell \partial^j_{m_1} \left(\frac{1}{e^{12}}\right) \langle n_1^j f_{2,-\ell,-3,q}^{(1)} \rangle + O(\epsilon).
\] (5.10)

The result of the PN iteration of the metric, starting with the $(d + 1)$-dimensional Einstein equations, and the corresponding definitions for the metric potentials are given in section 2 of [45]. In particular, the $d$-dimensional definition of the dangerous potential $Y$ is given by (2.12f) there\(^9\). We applied the previous method to the computation of the quantity $\mathcal{D}(\partial_j \hat{Y}_1)(1)$ defined above. This required computing the singular expansion of the needed non-compact support sources in $d$ dimensions up to the order $p = 0$, which was done following the methods of [45]. Our result for the pole part is quite compact,
\[
\mathcal{D}(\partial_j \hat{Y}_1)(1) = -\frac{1}{\epsilon} G^2 m_1^2 m_2}{252} v_{12}^j \hat{n}_{12}^j \left(\frac{1}{r_{12}}\right) + O(\epsilon^0).
\] (5.11)

Since this expression is symmetric by the exchange of the two indices $i$ and $j$ (or $k$), it does not contribute to the final equations of motion where only the contraction $S_{1k}^h (\partial_j \hat{Y}^{NS}_k)$ is involved. This confirms that the final equations of motion in dimensional regularization are directly pole-free. Furthermore, we also checked that the finite part $\propto \epsilon^0$ coming from equation (5.10) also cancels out in the final result (i.e. after contraction with the spin tensor $S_{ik}^h$). Although the latter fact could not a priori be guessed beforehand, it implies that finally the dimensional regularization was superfluous for the computation of the dangerous term $S_{1k}^h (\partial_j \hat{Y}^{NS}_k)$. This result gives us further confidence that the pure Hadamard–Schwartz regularization is sufficient for all our calculations.

\(^9\) Note that because we have already seen that the pole $1/\epsilon$ will necessarily cancel out in the final result, we do not have to worry about extending the Papapetrou part of the force (3.10) to $d$ dimensions, i.e. we can evaluate the term $\partial_{ij} \hat{Y}$ assuming it carries the three-dimensional coefficient, which is $+8$ in this case, see one of the terms in equation (3.10c).
6. Results for the equations of motion and precession

Since higher order results take the form of quite long formulae with many similar terms, we tried to adopt a systematic presentation. First, we split the expressions into terms of powers of $G$ and according to the powers of the masses $m_1$ and $m_2$. Each spin-dependent term is then denoted using the convention that $a^i_{p,q}$ gathers all the terms featuring $G^{p+q}m_1^pm_2^q$. For any two vectors $\mathbf{a}$ and $\mathbf{b}$, we use the notation $(ab)$ for the scalar product, i.e. $(ab) \equiv \mathbf{a} \cdot \mathbf{b} = d^i b^i$, and we define $(Sub) \equiv S^i d^i b^j$.

Before presenting the results, let us address an important point: every time an expression has at least one free index, it might admit several equivalent writings, in terms of the vectors appearing in the problem and of the spin tensors. Indeed, any of the final results, which are functions of time only (such as the acceleration of one of the bodies or the time derivative of one of the spins), can be written with the three vectors $v'_{12}$, $v'_1$, $v'_2$, and with at most one occurrence of either one of the spin tensors $S_i^j$ and $S^j_{ab}$ since we are working at linear order in spins. As the spatial indices run on three different values, we have the following two identities:

\begin{align}
S^i_{ij} a^j b^i a_j b_k c_l &= 0, \\
\alpha_{mn} S^i_{ij} a^j b^k c^l a_j b_k c_l &= 0,
\end{align}

where the brackets indicate antisymmetrization over the indices, $S^j_i$ is one of the spin tensors and $(a, b, c)$ is a permutation of the set of three vectors $(n_{12}, v_1, v_2)$. The number of identities of this kind that one must take into account depends on the number of vectors and tensors at disposal, and on the number of free indices. As an example, (6.1a) with $S = S_1$, $\alpha = n_{12}$, $b = v_1$ and $c = v_2$ gives, once expanded,

$$0 = -S^i_1 n_{12} v_2^i (n_{12} v_2) + S^j_1 n_{12} (n_{12} v_1) (v_1 v_2) + n_{12} (S_1 n_{12} v_1) (v_1 v_2)$$
$$- n_{12} v_1^j (S_1 n_{12} v_2) + n_{12} (S_1 v_1 v_2) - v_1^j (S_1 n_{12} v_1) (n_{12} v_2)$$
$$+ v_1^i (n_{12} v_1) (S_1 n_{12} v_2) - v_1^j (S_1 v_1 v_2) + S^j_1 v_1^j (n_{12} v_1) (n_{12} v_2)$$
$$- S^j_1 v_1^i (v_1 v_2) - S^j_1 v_2^i (n_{12} v_1)^2 + S^j_1 v_2^j v_1^2.$$  \(6.2\)

Hence, one must keep in mind that there is no unique writing for the results we are going to present, and take this into account when comparing two expressions. This becomes particularly important when using the method of undetermined coefficients (for instance, when looking for a contact transformation between harmonic and ADM variables, see section 7.4): the system of independent equations that these coefficients have to solve is to be determined only after taking into account the complete list of these identities. Note also that the use of an antisymmetric spin tensor reduces the number of these identities compared to the use of a vector spin variable and a Levi–Civita symbol, which was one of our motivations for changing the spin variable with respect to paper I. A straightforward but cumbersome work around this problem when comparing results is to project everything in an arbitrary orthonormal basis.

6.1. Spin evolution equation

First, we give the spin evolution equation, i.e. the equation giving the time derivative of the spatial components of the spin tensor $S_i^j$, up to 2 PN order. This result was in fact already contained in paper I, under the form of a precession equation for the spin vector $S_{BB}$, and it is a mere matter of traduction between the spin variables. Beware of the fact that our spin tensor is not of conserved norm, $S_i^j S^j_i \neq \text{const}$ beyond leading order. This equation is needed each time we perform order-by-order reduction when evaluating time derivatives.
Since we are working at 2 PN relative order, it is sufficient to know the 2 PN or $\mathcal{O}(4)$ spin evolution equation. This also means that the amount of nonlinearity in this computation is less than that in the computation of the acceleration. Indeed, expliciting equation (2.6o) in terms of potentials, we see that we need only 2 PN potentials, and we can ignore the spin contributions in these potentials, working at linear order in spins. However, note that, since the leading-order spin contributions to the total angular momentum of the system is of the form $S_1/c + S_2/c$, with $S_{1,2}$ spin vectors, the order of this spin evolution equation required for finding a conserved total angular momentum at 3.5 PN order is not 2 PN but 3 PN.

Defining
\[
\frac{d S^{ij}}{dt} = \frac{1}{c^2} B_{1,PN}^{ij} + \frac{1}{c^4} B_{2,PN}^{ij} + \mathcal{O}(6),
\]
we obtain for the 1 PN order:
\[
B_{1,PN}^{ij} = \frac{Gm_2}{r_{12}^2} \left[ 2 S_i^j (n_{12} v_{12}) + 4 n_{12}^{ij} v_{12}^{jk} v_{12}^k - 2 v_i^j v_{12}^{jk} n_{12}^k + 4 v_i^j v_{12}^{jk} n_{12}^k \right],
\]
and for the 2 PN order, splitting the result in terms of powers of $G$ and occurrence of the masses as explained above,
\[
B_{2,PN}^{ij} = \frac{G}{r_{12}} \beta_{0,1}^{ij} m_2 + \frac{G^2}{r_{12}} \left[ \beta_{1,1}^{ij} m_1 m_2 + \beta_{0,2}^{ij} m_2^2 \right],
\]
where
\[
\begin{align*}
\beta_{0,1}^{ij} &= n_{12}^{ij} v_{12}^{jk} v_{12}^k - 6 (n_{12} v_{12})^2 - 4 (v_{12} v_{12})^2 + 3 (n_{12} v_{12})^2 v_{12}^{jk} n_{12}^k + 2 (n_{12} v_{12}) v_{12}^{jk} n_{12}^k \\
&+ v_i^j v_{12}^{jk} n_{12}^k - 3 (n_{12} v_{12})^2 - 4 (v_{12} v_{12}) + v_i^j v_{12}^{jk} v_{12}^k [4 (n_{12} v_{12}) + 2 (n_{12} v_{12})] \\
&+ S_{1}^{ij} [3 (n_{12} v_{12}) (n_{12} v_{12})^2 + 2 (n_{12} v_{12}) (v_{12} v_{12})] \\
\beta_{1,1}^{ij} &= 32 (n_{12} v_{12}) n_{12}^{ij} v_{12}^{jk} v_{12}^k - 14 n_{12}^{ij} v_{12}^{jk} v_{12}^k - 12 v_i^j v_{12}^{jk} n_{12}^k \\
&- 2 v_i^j v_{12}^{jk} n_{12}^k + S_{1}^{ij} [2 (n_{12} v_{12}) + 2 (n_{12} v_{12})], \\
\beta_{0,2}^{ij} &= -4 (n_{12} v_{12}) n_{12}^{ij} v_{12}^{jk} n_{12}^k + 2 v_i^j v_{12}^{jk} n_{12}^k - 2 (n_{12} v_{12}) S_{1}^{ij}.
\end{align*}
\]

Note that, with the series of potentials already computed for the 3 PN equations of motion without spins [59, 45], we are able to control the precession equations up to the next 3 PN order; this will be investigated in future work.

### 6.2. Acceleration

The spin contributions in the acceleration have the following structure, with our PN counting valid for maximally spinning objects:
\[
\frac{dv_i}{dt} = A_N^i + \frac{1}{c^2} A_{1,PN}^i + \frac{1}{c^4} A_{3,5.5,PN}^i + \frac{1}{c^6} \left[ A_{2,PN}^i + A_{3,5,2.5,PN}^i \right] + \frac{1}{c^8} \left[ A_{2,5,PN}^i + A_{3,5,2.5,PN}^i \right] + \mathcal{O}(8),
\]
where the $S$ subscript indicates the spin–orbit contributions, and the $SS$ subscript indicates contributions that are quadratic in the spins and which we neglect in this work.\(^{10}\) For the
\[
\delta v^i = -\frac{G^2}{r_{12}^2 c^6} \left( m_1 S_1^i - m_2 S_2^i \right) n_{12}^i,
\]
whose effect on the accelerations is $\delta v^i = \delta d_\mu = d^2 \delta X^\mu / dt^2 + \mathcal{O}(8)$. This gauge transformation obviously respects the harmonicity condition in a perturbative sense, since $\Box \delta X^\mu = \mathcal{O}(8)$.\(^{10}\)
leading-order spin contributions, we obtain
\[
m_{1}A_{1.5,5}^{\text{PN}} = \frac{G}{r_{12}^{3}} \left[ m_{2} \left( 3S_{ij}^{i} m'_{i12} (n_{i12}v_{12}) + 6(S_{i12}v_{12})m'_{i12} - 3S_{ij}^{i} v_{12}^{i} \right) 
+ m_{1} \left( 6S_{ij}^{i} m'_{i12} (n_{i12}v_{12}) + 6(S_{i12}v_{12})m'_{i12} - 4S_{ij}^{i} v_{12}^{i} \right) \right].
\] (6.8)

It depends on the two velocities \( v'_{1} \) and \( v'_{2} \) only through the relative velocity \( v_{12} = v'_{1} - v'_{2} \). This is imposed by the Lorentz invariance of the harmonic-coordinate equations of motion, which reduces to a Galilean invariance at leading order (see section 7.2). For the 1 PN relative order contributions, we obtain the following:
\[
m_{1}A_{1.5,5}^{\text{PN}} = \frac{G}{r_{12}^{3}} \left[ \alpha_{0,1} m_{2} + \alpha_{1,0} m_{1} \right] + \frac{G^{2}}{r_{12}^{3}} \left[ \alpha_{0,2} m_{2}^{2} + \alpha_{1,1} m_{1} m_{2} + \alpha_{2,0} m_{1}^{2} \right].
\] (6.9)

where the coefficients are completely equivalent to those obtained in paper I and read\(^{11}\)
\[
\alpha_{0,1} = S_{ij}^{i} m'_{i12} \left[ -\frac{15}{2} (n_{i12}v_{12})(n_{i12}v_{2})^{2} - \frac{3}{2} (n_{i12}v_{12})v_{2}^{2} \right]
+ 3(n_{i12}v_{2})(v_{12}v_{2}) - \frac{3}{2} (n_{i12}v_{12})v_{2}^{2} 
+ S_{ij}^{i} v_{12}^{i} \left[ -3(n_{i12}v_{12})(n_{i12}v_{2}) + \frac{9}{2} (n_{i12}v_{2})^{2} + \frac{3}{2} v_{2}^{2} + 6(v_{12}v_{2}) + \frac{3}{2} v_{2}^{2} \right]
+ (S_{i12}v_{12})m'_{i12} \left[ -15(n_{i12}v_{2})^{2} - 3v_{2}^{2} - 12(v_{12}v_{2}) - 3v_{2}^{2} \right]
+ (S_{i12}v_{12})v_{12}^{i} \left[ -3(n_{i12}v_{12}) - 6(n_{i12}v_{2}) + 3(n_{i12}v_{2})(S_{i12}v_{12})v_{2}^{i} \right]
+ 3(n_{i12}v_{12})v_{12}^{i} + 3(n_{i12}v_{2})(S_{i12}v_{12})v_{2}^{i}
- 3(S_{i12}v_{12})v_{12}^{i} - 3(S_{i12}v_{12})v_{2}^{i},
\] (6.10a)
\[
\alpha_{1,0} = S_{i12}^{i} m'_{i12} \left[ -\frac{15}{2} (n_{i12}v_{12})(n_{i12}v_{2})^{2} - 6(n_{i12}v_{12})(v_{12}v_{2}) - 3(n_{i12}v_{12})v_{2}^{2} \right]
+ S_{ij}^{i} v_{12}^{i} \left[ 6(n_{i12}v_{2})^{2} + 4(v_{12}v_{2}) + 2v_{2}^{2} \right]
+ (S_{i12}v_{12})m'_{i12} \left[ -15(n_{i12}v_{2})^{2} - 6(v_{12}v_{2}) - 3v_{2}^{2} \right]
+ (S_{i12}v_{12})v_{12}^{i} \left[ -6(n_{i12}v_{12}) - 6(n_{i12}v_{2}) + 6(n_{i12}v_{2})(S_{i12}v_{12})v_{2}^{i} \right]
+ 6(n_{i12}v_{12})(S_{i12}v_{12})v_{12}^{i} - 4(S_{i12}v_{12})v_{12}^{i} - 4(S_{i12}v_{12})v_{2}^{i},
\] (6.10b)
\[
\alpha_{0,2} = -6(n_{i12}v_{12})S_{i12}^{i} m'_{i12} + 6S_{i12}^{i} v_{12}^{i} - 12(S_{i12}v_{12})m'_{i12},
\] (6.10c)
\[
\alpha_{1,1} = -14(n_{i12}v_{12})S_{i12}^{i} m'_{i12} + 14S_{i12}^{i} v_{12}^{i} - 26(S_{i12}v_{12})m'_{i12}
- 16(n_{i12}v_{12})S_{i12}^{i} m'_{i12} + 12S_{i12}^{i} v_{12}^{i} - 20(S_{i12}v_{12})m'_{i12},
\] (6.10d)
\[
\alpha_{2,0} = S_{i12}^{i} m'_{i12} \left[ -\frac{31}{2} (n_{i12}v_{12}) + 2(n_{i12}v_{2}) \right] + \frac{23}{2} S_{i12}^{i} v_{12}^{i} - \frac{45}{2} (S_{i12}v_{12})m'_{i12},
\] (6.10e)

Finally, the main result of our work, namely the next-to-next-to-leading 3.5 PN spin–orbit contributions to the acceleration, reads
\[
m_{1}A_{3.5,3P}^{\text{SN}} = \frac{G}{r_{12}^{3}} \left[ \gamma_{0,1} m_{2} + \gamma_{1,0} m_{1} \right] + \frac{G^{2}}{r_{12}^{3}} \left[ \gamma_{0,2} m_{2}^{2} + \gamma_{1,1} m_{1} m_{2} + \gamma_{2,0} m_{1}^{2} \right]
+ \frac{G^{3}}{r_{12}^{3}} \left[ \gamma_{0,3} m_{2}^{3} + \gamma_{1,2} m_{1} m_{2}^{2} + \gamma_{2,1} m_{1}^{2} m_{2} + \gamma_{3,0} m_{1}^{3} \right],
\] (6.11)

\(^{11}\) The link between the spin variable used in paper I and the present spin tensor is provided in the appendix.
\[\gamma_{0,1}^{\prime} = S_{1}^{2} n_{12}^{2} \left[ \frac{105}{4} (n_{12} v_{12}) (n_{12} v_{2})^{2} + \frac{15}{4} (n_{12} v_{12}) (n_{12} v_{2})^{2} v_{12}^{2} - \frac{3}{2} (n_{12} v_{12}) v_{12}^{4} \right] \\
+ \frac{3}{2} (n_{12} v_{12}) (n_{12} v_{12})^{2} (v_{12} v_{2}) - \frac{15}{2} (n_{12} v_{12})^{3} (v_{12} v_{2}) - \frac{3}{2} (n_{12} v_{12}) v_{12}^{2} (v_{12} v_{2}) \\
- \frac{3}{2} (n_{12} v_{2}) v_{12}^{2} (v_{12} v_{2}) - \frac{3}{2} (n_{12} v_{12}) (v_{12} v_{2})^{2} - 3 (n_{12} v_{12}) (v_{12} v_{2})^{2} \\
+ \frac{15}{2} (n_{12} v_{12}) (n_{12} v_{12})^{2} v_{2}^{2} - \frac{3}{2} (n_{12} v_{12}) v_{2}^{2} v_{2}^{2} - \frac{3}{2} (n_{12} v_{12}) (v_{12} v_{2})^{2} \\
+ \frac{3}{2} (n_{12} v_{2}) (v_{12} v_{2}) v_{2}^{2} - \frac{3}{2} (n_{12} v_{12}) v_{2}^{2} \\
+ S_{1}^{2} n_{12}^{2} \left[ \frac{15}{2} (n_{12} v_{12}) (n_{12} v_{2})^{3} - \frac{45}{8} (n_{12} v_{12})^{4} + \frac{3}{2} (n_{12} v_{12}) (n_{12} v_{2}) v_{12}^{2} - \frac{3}{2} (n_{12} v_{12}) v_{12}^{2} v_{12}^{2} \right] \\
+ \frac{3}{2} v_{12}^{4} + 3 (n_{12} v_{12}) (n_{12} v_{12}) (v_{12} v_{2}) - 12 (n_{12} v_{12})^{2} (v_{12} v_{2}) - \frac{3}{2} (v_{12} v_{2})^{2} \\
- \frac{3}{2} (n_{12} v_{12}) (n_{12} v_{12})^{2} v_{2}^{2} + \frac{3}{2} v_{12}^{2} v_{2}^{2} + 3 (v_{12} v_{2})^{2} v_{2}^{2} + \frac{3}{4} v_{2}^{4} \\
+ S_{1} (n_{12} v_{12}) n_{12} \left[ \frac{105}{4} (n_{12} v_{12})^{3} + \frac{15}{4} (n_{12} v_{12})^{3} v_{12}^{2} - \frac{3}{4} v_{12}^{4} + 30 (n_{12} v_{12})^{2} (v_{12} v_{2}) \\
+ 3 (n_{12} v_{12})^{3} - \frac{45}{8} (n_{12} v_{12})^{2} v_{2}^{2} - \frac{3}{2} v_{12}^{2} v_{2}^{2} - 6 (v_{12} v_{2}) v_{12}^{2} - \frac{3}{2} v_{2}^{2} \\
+ (S_{1} n_{12} v_{12}) v_{12} \left[ \frac{15}{2} (n_{12} v_{12}) (n_{12} v_{2})^{3} + 15 (n_{12} v_{12})^{3} + \frac{3}{2} (n_{12} v_{12}) v_{12}^{2} + 3 (n_{12} v_{12}) v_{12}^{2} \right] \\
+ 3 (n_{12} v_{12}) (v_{12} v_{2}) + 9 (n_{12} v_{12}) (v_{12} v_{2}) - \frac{9}{2} (n_{12} v_{12}) v_{12}^{2} - 3 (n_{12} v_{12}) v_{12}^{2} \\
+ (S_{1} n_{12} v_{12}) v_{12} \left[ -\frac{15}{2} (n_{12} v_{12}) (n_{12} v_{2})^{2} - \frac{3}{2} (n_{12} v_{12}) v_{12}^{2} - 3 (n_{12} v_{12}) (v_{12} v_{2}) \right] \\
+ 3 (n_{12} v_{12}) (v_{12} v_{2}) - \frac{9}{2} (n_{12} v_{12}) v_{12}^{2} \\
+ (S_{1} n_{12} v_{12}) v_{12} \left[ -\frac{15}{2} (n_{12} v_{12}) (n_{12} v_{2})^{2} - \frac{3}{2} (n_{12} v_{12}) v_{12}^{2} - 3 (n_{12} v_{12}) (v_{12} v_{2}) \right] \\
+ 3 (n_{12} v_{12}) (v_{12} v_{2}) - \frac{9}{2} (n_{12} v_{12}) v_{12}^{2} \\
+ (S_{1} n_{12} v_{12}) v_{12} \left[ -\frac{15}{2} (n_{12} v_{12}) (n_{12} v_{2})^{2} - \frac{3}{2} (n_{12} v_{12}) v_{12}^{2} - 3 (n_{12} v_{12}) (v_{12} v_{2}) \right] \\
+ 3 (n_{12} v_{12}) (v_{12} v_{2}) - \frac{9}{2} (n_{12} v_{12}) v_{12}^{2} \right] \\
+ (S_{1} n_{12} v_{12}) v_{12} \left[ -3 (n_{12} v_{12}) (n_{12} v_{2}) + \frac{9}{2} (n_{12} v_{12}) v_{12}^{2} + \frac{3}{2} v_{12}^{2} + 6 (v_{12} v_{2}) + \frac{3}{2} v_{2}^{2} \right] \\
+ (S_{1} n_{12} v_{12}) v_{12} \left[ -\frac{15}{2} (n_{12} v_{12}) (n_{12} v_{2})^{2} - \frac{3}{2} (n_{12} v_{12}) v_{12}^{2} - 3 (n_{12} v_{12}) (v_{12} v_{2}) \right] \\
+ 3 (n_{12} v_{12}) (v_{12} v_{2}) - \frac{9}{2} (n_{12} v_{12}) v_{12}^{2} \right] \right), (6.12a)\]

\[\gamma_{0,2}^{\prime} = S_{1}^{2} n_{12}^{2} \left[ \frac{18}{4} (n_{12} v_{12}) (n_{12} v_{2})^{2} - 3 (n_{12} v_{12}) v_{12}^{4} + 6 (n_{12} v_{12}) (v_{12} v_{2}) \\
- 6 (n_{12} v_{2}) (v_{12} v_{2}) + 3 (n_{12} v_{12}) v_{2}^{2} \right] \right], (6.12b)\]
\[
\gamma_{i,1} = S_i n_i'\Big[ -\frac{375}{8} (n_i v_{12})^3 - 33 (n_i v_{12})^2 (n_i v_{12}) + 45 (n_i v_{12}) (n_i v_{12})^2 + \frac{177}{2} (n_i v_{12}) n_i v_{12}^2 \\
+ 14 (n_i v_{12}) (v_{12} v_{12}) - 14 (n_i v_{12}) (v_{12} v_{12}) + 7 (n_i v_{12}) v_{12}^2 \\
+ S_i n_i'\Big[ \frac{721}{8} (n_i v_{12})^2 + 39 (n_i v_{12}) (n_i v_{12}) - 32 (n_i v_{12})^2 - \frac{73}{4} v_{12}^2 - 28 (v_{12} v_{12}) - 7 v_{12}^2 \\
+ (S_i n_i v_{12}) n_i v_{12}' - \frac{39}{2} (n_i v_{12})^2 - 42 (n_i v_{12}) (n_i v_{12}) + 90 (n_i v_{12})^2 + \frac{135}{4} v_{12}^2 \\
+ 52 (v_{12} v_{12}) + 13 v_{12}^2 \\
+ (S_i n_i v_{12}) v_{12}'\Big] \Big[ 122 (n_i v_{12}) + 20 (n_i v_{12}) \Big] - 14 (n_i v_{12}) (S_i n_i v_{12}) v_{12}' \\
- 14 (n_i v_{12}) (S_i n_i v_{12}) v_{12}' - 14 (n_i v_{12}) (S_i n_i v_{12}) v_{12}' + 14 (S_i n_i v_{12}) v_{12}' + 14 (S_i n_i v_{12}) v_{12}' \\
+ S_i n_i'\Big[ 48 (n_i v_{12}) (n_i v_{12})^2 + 16 (n_i v_{12}) (v_{12} v_{12}) - 16 (n_i v_{12}) (v_{12} v_{12}) + 8 (n_i v_{12}) v_{12}^2 \\
+ S_i n_i'\Big[ -24 (n_i v_{12})^3 - 12 (v_{12} v_{12}) - 6 v_{12}^2 \\
+ (S_i n_i v_{12}) n_i v_{12}^2\Big[ 60 (n_i v_{12})^2 + 20 (v_{12} v_{12}) + 10 v_{12}^2 \\
+ 20 (n_i v_{12}) (S_i n_i v_{12}) v_{12}' - 16 (n_i v_{12}) (S_i n_i v_{12}) v_{12}' - 16 (n_i v_{12}) (S_i n_i v_{12}) v_{12}' \\
+ 12 (S_i n_i v_{12}) v_{12}' + 12 (S_i n_i v_{12}) v_{12}' \\
\big(6.12d\big) 
\] 
\]
\[
\gamma_{i,2} = S_i n_i'\Big[ -\frac{1815}{8} (n_i v_{12})^3 - 51 (n_i v_{12})^2 (n_i v_{12}) + 54 (n_i v_{12}) (n_i v_{12})^2 - 6 (n_i v_{12})^3 \\
+ \frac{401}{4} (n_i v_{12}) v_{12}^2 + 12 (n_i v_{12}) v_{12}^2 + \frac{11}{2} (n_i v_{12}) (v_{12} v_{12}) - \frac{39}{4} (n_i v_{12}) (v_{12} v_{12}) \\
+ \frac{13}{2} (n_i v_{12}) v_{12}^2 - (n_i v_{12}) v_{12}^2 \\
+ S_i n_i'\Big[ \frac{1097}{12} (n_i v_{12})^2 + 56 (n_i v_{12}) (n_i v_{12}) - \frac{59}{2} (n_i v_{12})^2 - \frac{299}{8} v_{12}^2 \\
- \frac{15}{2} (v_{12} v_{12}) - \frac{3}{2} v_{12}^2 \\
+ (S_i n_i v_{12}) n_i v_{12}^2\Big[ -\frac{1097}{8} (n_i v_{12})^2 - 54 (n_i v_{12}) (n_i v_{12}) + 81 (n_i v_{12})^2 + \frac{323}{4} v_{12}^2 \\
+ \frac{23}{8} (v_{12} v_{12}) + \frac{45}{4} v_{12}^2 \\
+ (S_i n_i v_{12}) v_{12}'\Big[ 67 (n_i v_{12}) + \frac{35}{2} (n_i v_{12}) \Big] - 24 (n_i v_{12}) (S_i n_i v_{12}) v_{12}' \\
+ (S_i n_i v_{12}) v_{12}'\Big[ -\frac{31}{2} (n_i v_{12}) + 2 (n_i v_{12}) \Big] + (S_i n_i v_{12}) v_{12}'\Big[ -\frac{31}{2} (n_i v_{12}) + 2 (n_i v_{12}) \Big] \\
+ \frac{25}{2} (S_i n_i v_{12}) v_{12}' + \frac{23}{2} (S_i n_i v_{12}) v_{12}' \\
\big(6.12e\big) 
\] 
\[
\gamma_{i,3} = \frac{15}{8} (n_i v_{12}) S_i n_i' + \frac{15}{8} S_i n_i' + 15 (S_i n_i v_{12}) n_i v_{12}, 
\big(6.12f\big) 
\] 
\[
\gamma_{i,4} = \frac{15}{8} (n_i v_{12}) S_i n_i' - \frac{309}{8} S_i n_i' + \frac{60}{8} (S_i n_i v_{12}) n_i v_{12} \\
+ 32 (n_i v_{12}) S_i n_i' - 24 S_i n_i' + 42 (S_i n_i v_{12}) n_i v_{12}, 
\big(6.12g\big) 
\] 
\[
\gamma_{i,5} = \frac{29}{8} (n_i v_{12}) S_i n_i' - \frac{43}{8} S_i n_i' + 58 (S_i n_i v_{12}) n_i v_{12} \\
+ S_i n_i'\Big[ \frac{221}{2} (n_i v_{12}) - 14 (n_i v_{12}) \Big] - 61 S_i n_i' + \frac{115}{8} (S_i n_i v_{12}) n_i v_{12}, 
\big(6.12h\big) 
\] 
\[
\gamma_{i,6} = S_i n_i'\Big[ -\frac{73}{8} (n_i v_{12}) - 14 (n_i v_{12}) \Big] - \frac{119}{8} S_i n_i' + \frac{343}{8} (S_i n_i v_{12}) n_i v_{12}. 
\big(6.12i\big) 
\]
7. Checks of the results

7.1. Conserved energy

An important feature of all the spin–orbit contributions we have computed is that they are associated with the conservative part of the dynamics, i.e. obtained when neglecting the radiation-reaction dissipative terms associated with gravitational radiation. Therefore, these contributions should allow for the existence of a set of conserved quantities, namely energy, angular momentum, linear momentum and center-of-mass integral. Here we have checked that the new terms computed in the equations of motion in section 6.2 admit corresponding contributions in the conserved energy, which take the following structure:

\[ E = E_N + \frac{1}{c^2} E_{1\,\text{PN}} + \frac{1}{c^3} E_{1.5\,\text{PN}} + \frac{1}{c^4} [E_{2\,\text{PN}} + E_{2.5\,\text{PN}}] + \frac{1}{c^5} E_{3\,\text{PN}} + \frac{1}{c^6} E_{3.5\,\text{PN}} + \frac{1}{c^7} E_{3.5\,\text{PN}} + O \left( \frac{1}{c^8} \right). \]  

(7.1)

The leading order spin–orbit contribution to the energy reads

\[ E_{1.5\,\text{PN}} = \frac{Gm_2}{r_{12}^3} (S_1 n_{12} v_1) + 1 \leftrightarrow 2, \]  

(7.2)

while the 2.5 PN result (1 PN relative) was given in paper I, and reads, once translated into the spin tensor variable \( S^i \):

\[ E_{2.5\,\text{PN}} = \frac{G}{r_{12}^2} \epsilon_{0,1} m_2 + \frac{G^2}{r_{12}^3} \left[ \epsilon_{0,2} m_2^2 + \epsilon_{1,1} m_1 m_2 \right] + 1 \leftrightarrow 2, \]  

(7.3)

where

\[ \epsilon_{0,1} = (S_1 n_{12} v_1) [3(n_{12} v_1)(n_{12} v_2) + \frac{5}{2}(n_{12} v_2)^2 + (v_{12} v_2)] + (S_1 n_{12} v_2) [-3(n_{12} v_1)(n_{12} v_2) - 6(n_{12} v_1)(n_{12} v_2) - \frac{3}{2}(n_{12} v_2)^2 + v_{12}^2] + (S_1 v_{12} v_2) [(n_{12} v_1) + 3(n_{12} v_2)], \]  

(7.4a)

\[ \epsilon_{0,2} = 2(S_1 n_{12} v_1) - (S_1 n_{12} v_2), \]  

(7.4b)

\[ \epsilon_{1,1} = -2(S_1 n_{12} v_1) - 2(S_1 n_{12} v_2). \]  

(7.4c)

The result for the 3.5 PN contribution to the conserved energy has been obtained by the method of unknown coefficients and successfully determines the following unique result:

\[ E_{3.5\,\text{PN}} = \frac{G}{r_{12}^2} \eta_{0,1} m_2 + \frac{G^2}{r_{12}^3} \left[ \eta_{0,2} m_2^2 + \eta_{1,1} m_1 m_2 \right] + \frac{G^3}{r_{12}^4} \left[ \eta_{0,3} m_2^3 + \eta_{1,2} m_1 m_2^2 + \eta_{2,1} m_1^2 m_2 \right] + 1 \leftrightarrow 2, \]  

(7.5)

where

\[ \eta_{0,1} = \frac{1}{105} (n_{12} v_1) (n_{12} (v_{12} v_2)^3) (n_{12} (v_{12} v_2)^3) \left[ -15(n_{12} v_1)(n_{12} v_2)^2 - 15(n_{12} v_1)(n_{12} v_2)^2 - \frac{45}{2}(n_{12} v_1)(n_{12} v_2)^3 \right] - \frac{105}{8} (n_{12} v_2)^4 + \frac{9}{4}(n_{12} v_1)(n_{12} v_2)(v_{12} v_2)^2 + 3(n_{12} v_2)^2 v_{12}^2 - \frac{3}{4}(n_{12} v_1)(n_{12} v_2)^2(v_{12} v_2) + 3(n_{12} v_2)(v_{12} v_2)^3 + \frac{9}{8}(n_{12} v_2)^3(v_{12} v_2) + \frac{1}{144}(v_{12} v_2)(v_{12} v_2) + (v_{12} v_2)^2 + 3(n_{12} v_1)(n_{12} v_2)(v_{12} v_2)^2 + \frac{15}{4}(n_{12} v_2)^2 v_{12}^2 - v_{12}^2 v_{12}^2 + 2(v_{12} v_2) v_{12}^2] + (S_1 n_{12} v_2) \left[ -\frac{15}{4}(n_{12} v_1)^4 + 15(n_{12} v_1)^3(n_{12} v_2)^2 + \frac{45}{2}(n_{12} v_1)^3(n_{12} v_2)^2 + 15(n_{12} v_1)(n_{12} v_2)^3 \left[ -\frac{9}{2}(n_{12} v_1)^3 v_{12}^2 - 9(n_{12} v_1)(n_{12} v_2)^2 v_{12}^2 \right] \right] \]
asymptotically Minkowskian spacetime far away from the compact-support matter distribution. To check this, we follow mostly the presentation of [61] on our final equations of motion 12. To simplify this calculation, we leave for future work the study of the other conserved quantities at the same order, namely the total angular momentum, linear momentum and center-of-mass integral.

7.2. Lorentz invariance

Since we are working with the harmonic gauge condition which is manifestly Lorentz invariant, the global Lorentz invariance must be preserved by our calculations and must be manifested on our final equations of motion 12. To check this, we follow mostly the presentation of [61] and appendix A of paper I, with the difference that we use a different spin variable, which will simplify this calculation.

Let us consider two different frames \( \mathcal{F} \) and \( \mathcal{F}' \), with the latter being related to the former by a boost of velocity \( \mathbf{V} \). The coordinates of a given spacetime event \( P \) are \( x^\mu \) in the original frame \( \mathcal{F} \) and \( x'^\mu \) in the boosted frame \( \mathcal{F}' \), both being related by the Lorentz transformation \( x'^\mu = \Lambda^\mu_\nu x^\nu \), with

\[
\Lambda^0_0 = \gamma, \quad \Lambda^i_0 = -\gamma \frac{V^i}{c}, \quad \Lambda^i_j = \delta^i_j + \frac{\gamma^2}{\gamma^2 + 1} \frac{V^i V_j}{c^2},
\]

with \( \gamma = (1 - V^2/c^2)^{-1/2} \) being the Lorentz factor. We denote the trajectories of the two bodies in the frame \( \mathcal{F} \) by \( y^\mu_1 = (ct, y_1) \) and \( y^\mu_2 = (ct, y_2) \), and by \( y'^\mu_1 = (ct', y'_1) \) and \( y'^\mu_2 = (ct', y'_2) \) in the boosted frame \( \mathcal{F}' \). The point is that we cannot compare them directly, because the simultaneity surfaces are different in the two different frames. To give a sense to

\[\text{[23]}\]
simultaneity between the two frames, it is convenient to define an auxiliary event $\Omega(ct, x)$, which can be chosen at will—it could be for instance the point of coordinates $(ct, x = 0)$ in $(\mathcal{F})$, and whose coordinates in $(\mathcal{F}')$ will be $(ct', x')$. We define the two events $P_1(ct, y_1(t))$ and $P_2(ct, y_2(t))$ on the two worldlines, simultaneous to $\Omega$ in the frame $(\mathcal{F})$, and similarly two events $Q_1(ct', y_1'(t'))$ and $Q_2(ct', y_2'(t'))$, simultaneous to $\Omega$ in the frame $(\mathcal{F}')$. $\Omega$ plays the role of an observer, for which the equations of motion evaluated on the simultaneity surfaces $(\Omega, P_1, P_2)$ and $(\Omega, Q_1, Q_2)$ must take the same functional form, as explained below. Next, we define the times $t_1$ and $t_2$, such that the coordinates of $Q_1$ and $Q_2$ in $(\mathcal{F})$ are $(ct_1, y_1(t_1))$ and $(ct_2, y_2(t_2))$, respectively. We have, by construction, $y_1''(t') = \Lambda_{\mu}^\nu y_1'(t_1)$ and similarly for 2. The link between $y_1'(t')$ and $y_1(t)$ is provided in [61]. One obtains successively

$$y_1'(t') = y_1 - \gamma V \left( t - \frac{1}{c} \frac{\gamma}{\gamma + 1} (V x) \right) + \sum_{n=1}^{+\infty} \frac{(-\gamma)^n}{c^{2n} n!} \left[ (V r_1)^n \left( v_1 - \frac{\gamma}{\gamma + 1} V \right) \right],$$

$$v_1'(t') = \frac{v_1}{\gamma} - V + \frac{1}{\gamma} \sum_{n=1}^{+\infty} \frac{(-\gamma)^n}{c^{2n} n!} \left[ (V r_1)^n \left( v_1 - \frac{\gamma}{\gamma + 1} V \right) \right],$$

$$a_1'(t') = \frac{1}{\gamma^2} \left[ a_1 + \sum_{n=1}^{+\infty} \frac{(-\gamma)^n}{c^{2n} n!} \left[ (V r_1)^n \left( v_1 - \frac{\gamma}{\gamma + 1} V \right) \right] \right],$$

where the right-hand sides are evaluated at $t$, and $(V r_1)$ means $V \cdot (x - y_1)$. The expressions for the velocity and acceleration are obtained by taking the time derivative according to $\partial_t^i = \gamma \partial_t^0 + \gamma^2 \partial_t^\mu \partial^i_\mu$. Similar expressions hold for 2, and transformations for quantities such as $r_{12}$ or $n_{12}$ are deduced in a perturbative sense from the first of these formulae.

We turn now to the transformation rules for the spin tensor. As explained in paper I, we have for any function $f(t)$:

$$f(t_1) = f(t) + \sum_{n=1}^{+\infty} \frac{(-\gamma)^n}{c^{2n} n!} \left[ \frac{df}{dr}(V r_1)^n \right],$$

which can be applied to the components $S_{0i}^0$ and $S_{ij}^I$ of the spin tensor. Now, since these are the components of a contravariant tensor, we have

$$S_{0i}^0(t') = \Lambda_{\mu}^0 \Lambda_{\nu}^i S_{\mu i}^0(\tau_1),$$

$$S_{ij}^I(t') = \Lambda_{\mu}^i \Lambda_{\nu}^j S_{\mu \nu}^I(\tau_1).$$

Combining these expressions, we arrive at the desired transformation rule for $S_{ij}^I$:

$$S_{ij}^I(t') = S_{ij}^I - \frac{2\gamma^2}{\gamma + 1} \frac{\gamma}{c} S_{0i}^0(t') + \frac{2\gamma^2}{\gamma + 1} \frac{\gamma}{c} S_{ij}^0(t')$$

$$+ \sum_{n=1}^{+\infty} \frac{(-\gamma)^n}{c^{2n} n!} \left[ (V r_1)^n \left( \frac{df}{dr} + \frac{dS_{ij}^I}{dr} - \frac{2\gamma^2}{\gamma + 1} \frac{\gamma}{c} S_{0i}^0(t') \right) \right].$$

where $S_{0i}^0$ can be further eliminated using the spin supplementary condition (2.9). This transformation is somewhat simpler than (A13)–(A15) in appendix A of paper I because the transformation for the spin vector $S_{FB}^b$ is not as simple as in equations (7.10).

Lorentz invariance means that the acceleration in the boosted frame, obtained by transforming all variables according to equations (7.8) and (7.11), when systematically
the requested PN order, must take the same functional form as in the original non-boosted frame. We have verified that our result for the acceleration (6.11) passes this test. Note however that the test leaves a lot of freedom in the acceleration. In particular, one might add at the highest level \(1/e^3\) in the acceleration any quantity depending only on the relative velocity \(v_1^2 = v_1^1 - v_1^3\) and still pass this test.

Finally, let us remark that the pure Hadamard Schwartz regularization which has been used for all the terms in this computation, finally yields equations of motion which are manifestly Lorentz invariant. This is another indication that there is no need for using a more sophisticated regularization such as dimensional regularization in this problem.

7.3. Test-mass limit

Another important check of our result is to take the test-mass limit and show that we recover the equations of motion of a test particle orbiting in a black hole background. More precisely, we can check that:

(1) In the limit where one of the two bodies (say body 1) is a test particle with \(m_1 \rightarrow 0\) and is spinless \((S_{1j} = 0)\), its acceleration (6.7) reduces to that of a spinless test particle orbiting around a Kerr black hole;

(2) In the limit where body 1 is a test particle with spin (i.e. \(m_1 \rightarrow 0\) with constant ratio \(S_{1j}/m_1\)), equation (6.7) reduces to the equations of motion of a massless spinning particle orbiting around a Schwarzschild black hole.

Note that in case 2 we need to work with a Schwarzschild black hole because we restricted ourselves to spin–orbit effects. In this section, it will be more convenient to rewrite the equation of motion of a test particle orbiting in a black hole background. More precisely, we choose the origin of our coordinate system at the location of the central body 2 and suppose without loss of generality that the spin of body 2 points along the \(z\) axis: defining \(S' = e^{ij} S_{2j}^i\), we impose \(S' = S' = 0\) and \(S' = m_2 a\).

Given the symmetry of the problem, it is of course more convenient to work with the spherical coordinates associated with our harmonic coordinates and with the associated coordinate basis that we denote \((\hat{r}, \hat{\theta}, \hat{\phi})\). In practice, we will show that our PN result recovers the dynamics of a test-mass in a Kerr background by comparing the explicit expressions for the spin parts of the quantities \(\hat{r}, \hat{\theta}\) and \(\hat{\phi}\) obtained using equation (7.13).
and the geodesic equation in Kerr. In terms of \( r, \theta, \phi \), we have the following set of scalar quantities: \( r_{12} = r, (m_{12}r_{12}) = \dot{r}, (S_{2}m_{12}r_{12}) = -m_{2}r_{12}a \sin^{2} \theta \), and vector components \( v_{\phi}^{2} = \dot{\phi} \), \( v_{\theta}^{2} = 1 \), \( A_{\phi} = -m_{2}a / r \), \( B_{\phi} = -m_{2}a \sin \theta \cos \theta \), and \( B_{\theta} = m_{2}a (\dot{\phi} r \cot \theta + \dot{r} / r) \), all the other ones being zero. The components of the Cartesian acceleration are \( a' = \ddot{r} - \ddot{r} \sin^{2} \theta, a_{\phi}' = \ddot{\phi} + 2 \dot{r} \dot{\phi} / r - \ddot{r} \sin \theta \cos \theta \) and \( a^{\phi} = \ddot{\phi} + 2 \dot{r} \dot{\phi} / r + 2 \dot{r} \ddot{\phi} \cot \theta \). This yields

\[
\begin{align*}
(r)_{S} &= \frac{2Gm_{2}a}{c^{3}r_{3}^{2}} \phi \sin^{2} \theta - 6 \frac{Gm_{2}a}{c^{3}r_{3}^{2}} \phi r^{2} \sin^{2} \theta - 8 \frac{G^{2}m_{2}^{2}a}{c^{3}r^{5}} \phi \sin^{2} \theta + 18 \frac{G^{3}m_{2}^{3}a}{c^{7}r^{9}} \phi \sin^{2} \theta, \\
(\ddot{r})_{S} &= -4 \frac{Gm_{2}a}{c^{3}r_{3}^{2}} \phi \cos \theta \sin \theta - 6 \frac{Gm_{2}a}{c^{3}r_{3}^{2}} \phi r^{2} \cos \theta \sin \theta - 12 \frac{G^{2}m_{2}^{2}a}{c^{3}r^{5}} \phi \cos \theta \sin \theta \\
&- 24 \frac{G^{3}m_{2}^{3}a}{c^{7}r^{9}} \phi \cos \theta \sin \theta, \\
(\ddot{\phi})_{S} &= \frac{Gm_{2}a}{c^{3}r_{3}^{2}} (4r \theta \cot \theta - 2\phi - 6 \frac{Gm_{2}a}{c^{3}r_{3}^{2}} \phi \sin^{2} \theta + \frac{G^{2}m_{2}^{2}a}{c^{3}r^{5}} (4\phi - 12r \theta \cot \theta) \\
&+ 24 \frac{G^{3}m_{2}^{3}a}{c^{7}r^{9}} \phi \cot \theta).
\end{align*}
\] (7.14a, 7.14b, 7.14c)

We would like to compare this with the equations of motion of a test particle in the background of a Kerr black hole of mass \( m_{2} \) and spin parameter \( a \). Since our result is written in the harmonic gauge, we also need to work with the Kerr metric in harmonic coordinates rather than in the usual Boyer–Lindquist (BL) ones. A particular set of spatial harmonic coordinates \( (x^{1}, x^{2} \text{ and } x^{3}) \) constructed from the BL grid was obtained in [62] and reads

\[
\begin{align*}
x^{1} &= (r_{BL} - m_{2} + ia) \sin \theta_{BL} \exp \left( i \left[ \phi_{BL} + \frac{a}{r_{+} - r_{-}} \ln \left( \frac{r_{BL} - r_{+}}{r_{BL} - r_{-}} \right) \right] \right), \\
x^{3} &\equiv (r_{BL} - m_{2}) \cos \theta_{BL},
\end{align*}
\] (7.15a, 7.15b)

with \( r_{\pm} = (m_{2} \pm \sqrt{m_{2}^{2} - a^{2}}) \). For the time coordinate, we can simply choose \( t = t_{BL} \). Here again, we will use the spherical coordinates associated with \( x^{1}, x^{2} \text{ and } x^{3} \). The line element, expanded to linear order in the spin \( a \), reads

\[
dr^{2} = \frac{r - m_{2}}{r + m_{2}} dr^{2} + \frac{r + m_{2}}{r - m_{2}} dr^{2} + (r + m_{2})^{2} (d\phi^{2} + \sin^{2} \theta \, d\phi^{2}) \\
- 2 \frac{m_{2}^{2}a}{r^{2}} r + m_{2} \sin^{2} \theta \, dr \, d\phi - 4m_{2}a \frac{\sin^{2} \theta}{r + m_{2}} dr \, d\phi + O(a^{2}).
\] (7.16)

Note that in order to avoid heavy notations, we have set \( G = c = 1 \) in these non PN-expanded equations (7.15)–(7.16). Using (7.12), in which we set \( F_{\mu} \) to zero, for the coordinates \( x^{\mu} = (t, r, \theta, \phi) \), and developing at linear order in \( a \) and at 3.5 PN order, we obtain expressions for \( \dot{r}, \dot{\theta}, \dot{\phi} \) that reduce to the results of equations (7.4), but with the addition of the following extra pure gauge terms at 3 PN order:

\[
\begin{align*}
(\ddot{r})_{S} &= -2 \frac{G^{2}m_{2}^{2}a}{c^{5}r^{3}} \phi \sin^{2} \theta, \\
(\ddot{\theta})_{S} &= -2 \frac{G^{2}m_{2}^{2}a}{c^{9}r^{3}} \phi \cos \theta \sin \theta, \\
(\ddot{\phi})_{S} &= -\frac{G^{3}m_{2}^{2}a}{c^{9}r^{5}} (2 \dot{r}^{2} - 2 \dot{r} \dot{\phi} \cot \theta - \dot{r}^{2} \dot{\phi}^{2} \sin^{2} \theta) + \frac{G^{3}m_{2}^{3}a}{c^{13}r^{9}}.
\end{align*}
\] (7.17a, 7.17b, 7.17c)
The presence of these terms is simply a consequence of the fact that the coordinates (7.15)
are not exactly the same as the ones we used in our PN calculations: the harmonicity condition
does not completely fix the gauge and we still have the freedom to perform a coordinate change
$x^i \to x^i + \xi^i$ as long as $\partial_\nu (\sqrt{-g} g^{\mu \nu} \partial_\mu \xi^\nu) = 0$ without violating the harmonicity condition.
More precisely, the presence of these terms can be traced back to the metric element $g_{ij}$ which
can easily be put to zero (modulo higher order PN corrections) by the coordinate shift
$$\phi \to \phi + \frac{2G^2 m_2 \alpha}{3c^6 t^3}. \tag{7.18}$$

In terms of our harmonic coordinates, this translates into a shift $\xi^1 = -\frac{2G^2 m_2 \alpha}{3c^6 t^3}$ and
$\xi^2 = \frac{G^2 m_2 \alpha}{3c^6 t^3}$ which can easily be seen to satisfy $\partial_\nu (\sqrt{-g} g^{\mu \nu} \partial_\mu \xi^\nu) = 0$ modulo higher than 3.5 PN corrections: since $\xi^\nu = O(1/c^6)$ (and it does not depend on time), this equation
simply becomes $\Delta \xi^i = 0$.

### 7.3.2. Spinning test particle: equivalence with Papapetrou motion in Schwarzschild.

We now consider the limit $m_1 \to 0$, while $S_1^j/m_1$ is kept constant and we set $S_1^j = 0$ since we
only want to study linear effects in the spins (the spin–orbit terms involving $S_2$ are precisely
the ones that have been studied in the previous subsection). Here again, $v_2^i = 0$ is a solution
of the equations of motion and the acceleration of body 1 reduces to

$$(a'_1)_S = \frac{G m_2}{c^3 r_{12}^3 m_1} \left( 3(n_{12} v_1) A'_1 + 6(S_1 n_{12} v_1) n_{12}' - 3B'_1 \right)$$
+ $$\frac{G m_2}{c^3 r_{12}^3 m_1} \left( -\frac{3}{2} (n_{12} v_1) v_1^2 A'_1 - 3v_1^2 (S_1 n_{12} v_1) n_{12}' + \frac{3}{2} v_1^2 B'_1 - 3(n_{12} v_1)(S_1 n_{12} v_1) v_1' \right)$$
+ $$\frac{G^2 m_2^2}{c^5 r_{12}^5 m_1} \left( -6(n_{12} v_1) A'_1 - 12(S_1 n_{12} v_1) n_{12}' + 6B'_1 \right)$$
+ $$\frac{G m_2}{c^3 r_{12}^3 m_1} v_1' \left( -\frac{3}{8} (n_{12} v_1) v_1^2 A'_1 - \frac{3}{4} v_1^2 (S_1 n_{12} v_1) n_{12}' + \frac{3}{8} v_1^2 B'_1 \right)$$
+ $$\frac{3}{2} (n_{12} v_1)(S_1 n_{12} v_1) v_1' \right)$$
+ $$\frac{G^2 m_2^2}{c^5 r_{12}^5 m_1} \left( -3(n_{12} v_1) v_1^2 A'_1 - 6v_1^2 (S_1 n_{12} v_1) n_{12}' + 3v_1^2 B'_1 - 6(n_{12} v_1)(S_1 n_{12} v_1) v_1' \right)$$
+ $$\frac{G^3 m_3^2}{c^6 r_{12}^6 m_1} \left( \frac{15}{2} (n_{12} v_1) A'_1 + 15(S_1 n_{12} v_1) n_{12}' - \frac{15}{2} B'_1 \right), \tag{7.19}$$

with $A'_1 = n_{12}' S_1^j$ and $B'_1 = v_1' S_1^j$. Choosing once again the origin of the coordinate system at
the position of body 2 and moving to spherical coordinates, we obtain $A'_1 = 0$, $A'_\theta = -S_1^\theta$,
$A'_\phi = -S_1^\phi$, $B'_1 = r^2 \partial_\theta S_1^\phi + r^2 \phi \sin^2 \theta S_1^\phi$, $B'_1 = -r S_1^\theta + r^2 \phi \sin^2 \theta S_1^\phi$, $B'_1 = -r S_1^\phi - r^2 \phi \sin^2 \theta S_1^{\phi}$, and $(S_1 n_{12} v_1) = r^2 \partial_\theta S_1^\phi + r^2 \phi \sin^2 \theta S_1^{\phi}$. Plugging this into equation (7.19) leads to the explicit expressions

$$(\vec{F})_S = \left[ \frac{3}{2} \frac{G m_2}{c^3 r m_1} + \frac{3}{2} \frac{G m_2}{c^3 r m_1} (3r^2 + r^2 \partial^2 + r^3 \phi^2 \sin^2 \theta) - \frac{G^2 m_2^2}{c^5 r^3 m_1} \right.$$
+ $$\frac{G m_2}{c^3 r m_1} \left( \frac{9}{8} r^2 + \frac{3}{4} r^2 \partial^2 + \frac{3}{8} r^4 \phi^2 \sin^2 \theta \right.$$
+ $$\left. - \frac{3}{4} r^2 \partial^2 \phi^2 \sin^2 \theta - \frac{3}{8} r^4 \phi^3 \sin^4 \theta \right).$$

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In this section, we compare our results to the ones obtained in [38] by a completely different method. Using (7.20a)
\[
-3 \frac{G^2 m_2^2}{c^5 r^3 m_1} (3 \dot{r}^2 + r^2 \ddot{\theta}^2 + r^2 \dot{\phi}^2 \sin^2 \theta) + \frac{15}{2} \frac{G^3 m_2^2}{c^7 r^5 m_1} \big(\dot{\phi} S_{1\phi}^\theta + \dot{\phi} \sin^2 \theta S_{1\phi}^\theta\big),
\]
and all the other Poisson brackets vanish. Beware of the fact that additional \(c\) factor appearing in the second bracket: our PN counting is different from that in [38], and we have set \(\vec{\Sigma} = \hat{c} S_{\text{HS}}\) to keep close to the convention we use, see equation (1.1). One may as well employ a conserved-norm antisymmetric spin tensor defined (exactly) by
\[
\vec{S}^{ij} = \epsilon^{ijk} \vec{S}_k.
\]

The dynamics is entirely contained in the Hamiltonian of the two-body system, expressed in terms of these canonical variables. Besides the recent result for the spin–orbit 3.5 PN spin–orbit contributions [38], the NS part of the Hamiltonian up to 2 PN order can be found...
for instance in [63], and the spin–orbit part up to 2.5 PN order is given in [32]. As explained
before, since we are working at 2 PN relative order with respect to the leading order spin–orbit
contribution, we will need to know the NS part of the dynamics only up to 2 PN order. The
time derivative of any quantity \( f \) is obtained as
\[
\frac{df}{dt} = [f, H] + \frac{\partial f}{\partial t},
\]
(7.23)
where the second term accounts for a possible explicit time dependence of \( f \), absent in our
problem. Beware again of the fact that, because of the additional \( c \) factor in the Poisson
brackets for the spin, the PN truncation of the Hamiltonian must be handled carefully.

It is well known that, when comparing the results of the two formalisms, it is necessary to
present these formulae, we use the canonical spin tensor variable (7
\( \pi \)), the PN truncation of the Hamiltonian must be handled carefully.

As for the acceleration, we have
\[
a = A(\mathbf{x}, p, S) = \{ \{Y(\mathbf{x}, p, S), H\}, H\}. \tag{7.26}
\]
(7.26)
On the other hand, we may use (7.24) and (7.25) and the link between the spin variables (7.30)
to translate the harmonic-coordinates result (6.11) for the acceleration in terms of the ADM
variables as
\[
a = a(y, v, S) = a(Y(x, p, \tilde{S}), V(x, p, \tilde{S}), S(x, p, \tilde{S})), \tag{7.27}
\]
(7.27)
and this expression must be identical to (7.26). Thus, one is led to look for an extension
of the contact transformation (7.24) that realizes this identity. Focusing on the non-spin and
spin–orbit parts, the structure of this contact transformation is the following:
\[
Y_1 = x_1 + \frac{1}{c^3}Y_{51}^{1.5\,\text{PN}} + \frac{1}{c^4}Y_{21}^{\text{PN}} + \frac{1}{c^3}Y_{31}^{2.5\,\text{PN}} + \frac{1}{c^6}Y_{11}^{3\,\text{PN}} + \frac{1}{c^7}Y_{51}^{3.5\,\text{PN}} + O\left(\frac{1}{c^8}\right). \tag{7.28}
\]
(7.28)
The lower order already known expressions for this contact transformation can be found
in [63] and [32]. Note that, as when using the Hamiltonian to compute time derivatives in
the ADM setting, we need the NS part of this contact transformation up to 2 PN only. To
present these formulae, we use the canonical spin tensor variable (7.22) to obtain the same
index structure as in the other results of this paper, and we adopt the convenient notation
\( \pi_{a} \equiv \tilde{\pi}_{a}/\mu_{a} \) to shorten the expressions. We find
\[
Y_{1}^{\text{PN}} = Gm_2 \left[ \frac{1}{2} \pi_{1} (\tilde{\pi}_{12} \pi_{2}) - \frac{7}{4} \pi_{2} (\tilde{\pi}_{12} \pi_{2}) + \frac{1}{8} \pi_{12} (5 \pi_{2}^2 - (\tilde{\pi}_{12} \pi_{2})^2) \right] \\
+ \frac{Gm_2}{4 \pi_{12}} \pi_{12} (7m_1 + m_2), \tag{7.29a}
\]
\[
m_1 Y_{51}^{1.5\,\text{PN}} = - \frac{1}{2} \pi_{1} \pi_{2}, \tag{7.29b}
\]
\[
m_1 Y_{31}^{2.5\,\text{PN}} = \frac{\pi_{1} \pi_{1} \pi_{2}}{8 \pi_{1} \pi_{2}} + \frac{G}{\pi_{12}} \left[ m_2 \pi_{1} \pi_{2} + m_1 \left( \frac{3}{2} \pi_{1} \pi_{2} + (\tilde{\pi}_{12} \pi_{2}) \pi_{12} + \frac{1}{2} \pi_{12} (\tilde{\pi}_{12} \pi_{2}) \pi_{12} \right) \right]. \tag{7.29c}
\]
We need also the conversion rule between the harmonic spin tensor and the ADM canonical spin, say \( S = S(\mathbf{x}, \mathbf{p}, \mathbf{S}) \). The conversion rule from the conserved norm variable \( S_{\mathcal{FBB}} \) to \( \mathbf{S} \) is given in equations (6.4) and (6.5) of [32], and the conversion rule between this conserved norm spin and \( S_{\mathcal{FBB}} \) is given in equation (7.4) of [31]. Finally, knowing the link between \( S_{\mathcal{FBB}} \) and our spin tensor, equation (A.1) in the appendix, we obtain
\[
S_i^j = \tilde{S}_1^j + \frac{1}{c^2} \Sigma_{01}^{ij} + \frac{1}{c^4} \Sigma_{21}^{ij} + \mathcal{O}(5),
\]
where
\[
\Sigma_{01}^{ij} = -\pi^i_j \Sigma_1^{jk} \pi^k - \frac{2Gm_2}{r_{12}} \Sigma_1^j,
\]
\[
\Sigma_{21}^{ij} = \Sigma_{00}^{ij} + \frac{G}{r_{12}} \Sigma_{01}^{ij} m_2 + \frac{G^2}{r_{12}^2} \left( \Sigma_{02}^{ij} m_2^2 + \Sigma_{11}^{ij} m_1 m_2 \right),
\]
\[
\Sigma_{01}^{ij} = -\frac{4}{r_{12}} \pi^i_j \pi^k \pi^k + 2(\pi_1 \pi_2) \pi_1^j \pi_2^k \pi_1^k + 4\pi_1^i \pi_2^j \pi_1^k - 2(\pi_1 \pi_2) \pi_1^j \pi_2^k \pi_1^k
\]
\[
- 7\pi_1^i \pi_2^j \pi_1^k + 4\pi_2^i \pi_1^j \pi_2^k + (\pi_1 \pi_2)^2 \pi_1^k,
\]
\[
\Sigma_{02}^{ij} = \frac{G}{r_{12}} \pi_1^j \pi_2^k m_1 + 3\pi_2^j,
\]
\[
\Sigma_{11}^{ij} = -8\pi_1^j \pi_2^k m_2 - 8\pi_1^j m_1 m_2 - \pi_2^j.
\]

Using the same structural hypothesis as in [32] (namely that in \( m_1 Y_1 \) terms such as \( m_1^3 \delta_1 \) and \( m_1^2 S_2 \) are forbidden, where \( n \) is the total power of mass in the term), we build a putative spin contribution to the contact transformation with 112 unknown coefficients. Then, requiring the identity of the expressions (7.26) and (7.27) above, we find a unique solution for these coefficients, among which 69 remain in the final result, which fixes uniquely the contact transformation. Thus, we conclude that our result and the one obtained in the ADM formalism in [38] are equivalent.\(^\text{13}\)

We now give explicitly the 3.5 PN spin–orbit extension of the contact transformation, which reads:
\[
m_1 Y_1 \mathcal{S}_{3,5,SP} = -\frac{\pi_i^j}{16} \tilde{S}_1^j + \frac{G}{r_{12}} \left[ \lambda_{01}^i m_2 + \lambda_{10}^i m_1 \right] + \frac{G^2}{r_{12}^2} \left[ \lambda_{02}^i m_2^2 + \lambda_{11}^i m_1 m_2 + \lambda_{20}^i m_1^2 \right],
\]
where
\[
\lambda_{01}^i = \tilde{S}_1^j \left[ \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 - \frac{3}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^3 - \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^3 + \frac{3}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 \right.
\]
\[
+ \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_1) - \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 \left. \right]
\]
\[
+ \tilde{S}_1^j \left[ -\frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{3}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^3 - \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^3 + \frac{3}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 \right.
\]
\[
+ \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_1) - \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 \left. \right]
\]
\[
+ (\tilde{S}_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 \left. \right]
\]
\[
+ \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_1) - \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 - \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2
\]
\[
+ \left. (\tilde{S}_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{8} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 + \frac{1}{16} (\pi_1 \pi_1) (\pi_1 \pi_2)^2 \right].
\]
\(\text{13}\) We found a typographical error in the originally published version of the Hamiltonian (5) in [38]: the coefficient in front of the term \( \frac{1}{r_{12}} \frac{\partial S_1}{\partial \mathbf{p}_1} \mathbf{p}_1 \) \( \mathbf{S}_{11} \) should read \( -\frac{i}{8} \) instead of \( -\frac{i}{16} \).

\(30\)
which we denote $S_i$. In this appendix, we provide the explicit conversion rule from the spin variable used in paper I, its value at the location of the particles. Most importantly, this work opens the way to the construction of the conserved quantities other than the energy (total angular momentum, linear momentum, center-of-mass integral), the center-of-mass reduction of the equations of motion as well as the further reduction of the dynamics to quasi-circular orbits. We shall also provide the spin–orbit contributions to the components of the near-zone metric itself and its value at the location of the particles. Most importantly, this work opens the way to the computation of the 3.5 PN spin–orbit contributions to the energy flux emitted by the binary in the form of gravitational waves, and of the corresponding contribution in the phase of the GW signal, which should improve the templates used by current and future GW detectors.

### Appendix. Link between different spin variables

In this appendix, we provide the explicit conversion rule from the spin variable used in paper I, which we denote $S_{FBB}^i$, to our spin tensor variable $S^{ij}$. This rule allows one to readily translate

\[
\lambda_{1,0} = \frac{1}{2} \dot{S}_{ij}^i \dot{n}_{12}^j - \frac{1}{2} \dot{S}_i \dot{n}_{12}^i + \frac{1}{2} \dot{S}_j \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^i + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j.
\]

\[
\lambda_{1,1} = \frac{1}{2} \dot{S}_{ij}^i \dot{n}_{12}^j - \frac{3}{8} \dot{S}_i \dot{n}_{12}^i + \frac{3}{8} \dot{S}_j \dot{n}_{12}^j - \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^i + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j.
\]

\[
\lambda_{2,0} = \frac{1}{2} \dot{S}_{ij}^i \dot{n}_{12}^j - \frac{3}{8} \dot{S}_i \dot{n}_{12}^i + \frac{3}{8} \dot{S}_j \dot{n}_{12}^j - \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^i + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j + \frac{3}{8} \dot{S}_{ij} \dot{n}_{12}^j.
\]

### 8. Conclusion

In this work, we computed the next-to-next-to-leading order spin–orbit contributions to the equations of motion of compact binaries. Those are of 3.5 PN order for maximally spinning objects, thus improving our knowledge of the dynamics of such systems at this order. Our result was tested by checking the existence of a conserved energy, the manifest Lorentz invariance of the equations of motion and the agreement of the test-mass limit with the motion of a spinless test particle around a Kerr black hole as well as that of a spinning test particle around a Schwarzschild black hole. We also recover and confirm the result obtained previously in [38] using a reduced Hamiltonian method in ADM-type coordinates, extending the contact transformation that makes the link between the two formalisms.

We leave for future work the study of the 3 PN precession equation for the spins, the construction of the conserved quantities other than the energy (total angular momentum, linear momentum, center-of-mass integral), the center-of-mass reduction of the equations of motion as well as the further reduction of the dynamics to quasi-circular orbits. We shall also provide the spin–orbit contributions to the components of the near-zone metric itself and its value at the location of the particles. Most importantly, this work opens the way to the computation of the 3.5 PN spin–orbit contributions to the energy flux emitted by the binary in the form of gravitational waves, and of the corresponding contribution in the phase of the GW signal, which should improve the templates used by current and future GW detectors.
the lower order results of paper I in terms of our variables for comparison. We adopt the notation (\(\epsilon aS\)) for \(\epsilon^{ijkl}a^{ijkl}\), for any vector \(a\), with the indices in this precise order:

\[
S_{FBB}^{i} = \frac{1}{2} \epsilon^{ijkl}S_{1}^{jk} + \frac{1}{c^{2}} \Sigma_{1}^{i} p_{N}^{i} + \frac{1}{c^{4}} \Sigma_{2}^{i} p_{N}^{i} + \mathcal{O}(5),
\]

where

\[
\Sigma_{1}^{i} p_{N}^{i} = - \frac{1}{16} v_{1}^{i} \epsilon^{ijkl}S_{1}^{jk} + \frac{1}{4} (\epsilon v_{1}S_{1})v_{1}^{i} + \frac{Gm_{2}}{r_{12}} \epsilon^{ijkl}S_{1}^{jk} - \frac{5}{2} (\epsilon v_{1}S_{1})v_{1}^{i} - 2(\epsilon v_{2}S_{1})v_{2}^{i} - (\epsilon n_{12}v_{2})^{2} - \frac{G^{2}m_{1}m_{2}}{r_{12}} \left[ - \frac{7}{4} \epsilon^{ijkl}S_{1}^{jk} + 4(\epsilon n_{12}S_{1})n_{12}^{i} \right] + \frac{G^{2}m_{2}^{2}}{r_{12}} \left[ \frac{1}{4} \epsilon^{ijkl}S_{1}^{jk} - \frac{1}{2} (\epsilon n_{12}S_{1})n_{12}^{i} \right].
\]

(A.2a)

(A.2b)

On the other hand, the link between our spin tensor and the spin variable used in the ADM-Hamiltonian work [38] is provided in equations (7.30)–(7.31).

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