The lambda mechanism in the lambda calculus and in other calculi

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Abstract
A comparison of Landin’s form of lambda calculus with Church’s shows that, independently of the lambda calculus, there exists a mechanism for converting functions with arguments indexed by variables to the usual kind of function where the arguments are indexed numerically. We call this the “lambda mechanism” and show how it can be used in other calculi. In first-order predicate logic it can be used to define new functions and new predicates in terms of existing ones. In a purely imperative programming language it can be used to provide an Algol-like procedure facility.

Categories and Subject Descriptors D.1.1 [Applicative (Functional) Programming]; D.3.1 [Formal Definitions and Theory]; D.3.3 [Language Constructs and Features]; F.3.2 [Semantics of Programming Languages]; F.3.3 [Studies of Program Constructs]

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1. Introduction

Lambda in programming languages Though lambda was used to name functions in the first Lisp, this does not imply that this language conforms to the lambda calculus: none of the early Lisps had lexical scoping. This shows that lambda is a mechanism that exists independently of lambda calculus.

Let us call “functional programming” the use of a programming language based on lambda calculus. In 1967 Landin described [13], ISWIM, the first programming language based on lambda calculus.

PAL [7] and POP-2 [3], which were based on ISWIM, became the first implemented functional programming languages. It was followed by many such languages, of which Scheme, Haskell, and the various forms of ML are the most widely known in computer science circles. A more recent phenomenon is that there are widely used languages, such as JavaScript and Python, of which many users don’t even know that there is a subset allowing functional programming.

The most important lesson of functional programming is that problems are often more easily solved functionally rather than imperatively. Yet at times it seems essential to program imperatively. Monads are a way to combine functional and imperative programming. We are interested in other ways of enriching imperative programming, if not by including lambda calculus, then perhaps with the lambda mechanism.

The lambda mechanism with predicate calculus Floyd’s verification method [8] leads to an intricate entanglement of imperative code with logic formulas, which suggests using logic itself as a programming language. This is of course what happens in logic programming, an approach that amounts to the use of a particular theorem prover as execution mechanism. Because of its highly specialized choices, logic programming does not exhaust the possible uses of logic as a programming language.

Independently of logic programming one sees the following promising features of first-order predicate logic for use as a programming language:

1. Both functions and predicates.
2. Simple mathematical semantics that is adaptable to ontologies familiar to program specifiers.
3. Potential for defining new functions in terms of existing ones.
4. Potential for defining new procedures in terms of existing ones.

One of the goals of this paper is to show how to realize the potential in items 3 and 4 by means of the lambda mechanism.

The lambda mechanism for Algol-like languages Procedure calls in Algol 60 with by-name parameters have a resemblance to beta reduction in lambda calculus. This sug-
gests reformulating procedure definition and call by means of the lambda mechanism. In this way a transition is made from a purely imperative language to one that shares some features with a functional programming language.

2. Notation and terminology
We denote the cardinality of a set \( V \) by \( |V| \). For a finite \( V \) with \( |V| = n \), we freely confuse the finite cardinals with the corresponding ordinals and loosely refer to them as “natural” numbers. As a result, locations such as “for all \( i \in n \)” are common as abbreviation of “for all \( i \in \{0, \ldots, n-1\} \)”.

The set of all functions from set \( S \) to set \( T \) is denoted \( S \to T \), so that we may write \( f \in (S \to T) \). To relieve the overloaded term “domain” we call \( S \) the source and \( T \) the target of \( S \to T \) and of any \( f \) belonging to it.

\[ |S \to T| = |T|^{|S|}. \]
Therefore, when \( |S| = 1 \) we have that \( |S \to T| = |T| \).

The value of \( f \) at \( x \in S \) is written as \( f(x) \) or as \( f_x \). The composition \( h \circ f \) of \( f \in (S \to T) \) and \( g \in (T \to U) \) is denoted \( g \circ f \) and is the function in \( S \to U \) defined by \( x \mapsto g(f(x)) \) for all \( x \in S \).

Tuples are regarded as functions. The tuple \( t \in (n \to S) \), with \( n \) a natural number, can be written as \( (t_0, \ldots, t_{n-1}) \). The subset \( t \) is “indexed by” \( n \). Tuples can also be indexed by other sets. For example, consider a relation \( \{(x, y, z) \mid (x, y) \in \{0, 1\} \} \) specified by \( f(x) = 0, f(y) = 1 \), and \( f(z) = 0 \). We may use instead the tabular representation of this tuple: \( f = } \)

Consider the set \( 1 \to D \) of tuples. Any subset of it is called a relation, and its type is \( 2^{1 \to D} \). I is the index set of the relation. An \( n \)-ary relation is a subset of \( n \to D \), where \( n \) is a natural number. A function \( f \in (D \to D) \) defines the binary relation \( \{(d, f(d)) \mid d \in D\} \). Consider a relation \( p \) of type \( 2 \to D \) such that \( (x, y) \in p \) and \( (x', y') \in p \) imply that \( y = y' \). Such a relation is called a partial function. “Partial function” might suggest a special case of “function”, but it is the other way around.

3. The lambda mechanism

The tuple form of lambda notation Landin introduced \[ ] \) what we shall call the tuple form of lambda notation. The distinction can be introduced by an example. Consider the lambda calculus expression

\[ \lambda x_0 \ldots \lambda x_{n-1} . M \quad (1) \]

In lambda calculus abstraction happens one variable at a time; in this example it is repeated \( n \) times. The \( n \) variables are assumed distinct; assuming otherwise leads to strange phenomena. For example, according to [12], Definition 1.22, \( (\lambda x \lambda \lambda . M)N \) rewrites according to \( \beta \)-reduction to \( [N]/x)(\lambda x . M) \), the result of substituting \( N \) for \( x \) in \( \lambda x . M \).

According to [9], case (d) in Definition 1.11 applies. This case states that \( [N/x](\lambda x . P) \equiv \lambda x . P \), so that \( (\lambda x \lambda x . M)N \beta \)-reduces to \( \lambda x . M \).

The counterpart of \( (1) \) in the tuple form of lambda notation is

\[ \lambda (x_0, \ldots, x_{n-1}) . M \]

It is a single abstraction on an \( n \)-tuple of distinct variables. In the tuple form it is a syntactic error to repeat a variable.

The application of \( (1) \) in sequence to \( M_0, \ldots, M_{n-1} \) is written as

\[ (((\ldots ((\lambda x_0 \ldots \lambda x_{n-1} . M)M_0) \ldots)M_{n-1}). \]

The application of \( (2) \) to \( (M_0, \ldots, M_{n-1}) \) is written as

\[ (\lambda (x_0, \ldots, x_{n-1}) . M)(M_0, \ldots, M_{n-1}). \]

An example of the lambda mechanism Any lambda expression with free variables can be used to specify a function. Suppose we are interested in functions over a domain \( D \). The lambda expression \( y(y) \) specifies a function in the sense that, if domain elements are given as values for \( x \) and \( y \), then \( x(y) \) is exactly one element of \( D \). The assignment of domain elements to these variables is a function of type \( \langle x, y \rangle \to D \). In this sense \( x(y) \) defines a function and that function is of type \( (\langle x, y \rangle \to D) \to D \). In symbols, \( (x(y)) \in (\langle \langle x, y \rangle \to D \rangle \to D) \).

Such a function is called a “binding” by Burstall and Lampson [11].

Suppose now that we want to use \( x(y) \) to define a two-argument function \( f \in (D^2 \to D) \). We can’t identify \( f \) with \( x(y) \) because they are of different types. We need a kind of adapter that converts type \( \langle x, y \rangle \to D \) to type \( D^2 \to D \).

Such conversions are effected by lambda abstraction in the tuple form of lambda calculus.

In this example we have that \( [\lambda (x, y). x(x)] \in (D^2 \to D) \), whereas \( [x(y)] \in (((\langle x, y \rangle \to D) \to D) \to D) \); two different expressions have denotations of different types. In general, for a lambda expression \( M \) with set \( X \) of free variables we have \( [M] \in ((X \to D) \to D) \) and \( [\lambda (x_0, \ldots, x_{n-1}). M] \in (D^{\{X\}} \to D) \), assuming that \( x_0, \ldots, x_{n-1} \) is one of the \( n! \) enumerations of the \( n \) variables in \( X \). The conversion of \( [M] \) to \( [\lambda (x_0, \ldots, x_{n-1}). M] \) we call the “lambda mechanism”, which is at work in the tuple form of lambda calculus. It converts an expression denoting a function in \( (X \to D) \to D \) to one denoting a function in \( D^{\{X\}} \to D \).

Mathematical formulation of the lambda mechanism Given an expression \( E \) with finite set \( X \) of \( n \) free variables. Let \( D \), the domain, be a set. Let \( \chi \) be a function in \( X \to D \) (in short, \( \chi \in (X \to D) \)), let \( x \in (n \to X) \), and let \( d \in (n \to D) \) be such that \( d(i) = \chi(x(i)) \) for all \( i \in n \). See Figure \[ ]

The lambda mechanism is the use of \( \lambda \) in any of the following three situations.

1. Lambda used to transform tuple \( \chi \) to tuple \( d \): \( d = \lambda x . \chi \).

This is nothing but another way of writing the functional
composition \(d = \chi \circ x\). We come even closer by writing
\[
d = x; \chi
\]
which is the way some authors write the functional composition of \(x\) and \(\chi\).
The fact that in the tuple form of lambda notation there can be no repeated variables in
\[
x = (x_0, \ldots, x_{n-1})
\]
translates to the existence of the inverse of \(x\) regarded as a function. Thus we can write \(d = \chi \circ x\) equivalently as \(\chi = d \circ x^{-1}\); see footnote\(^1\).

2. A natural extension of a transformation of a tuple to a tuple, as in item\(^1\) is to transform a set of tuples of the same type to a set of tuples of the same type. That is, a transformation of a relation to a relation when we think of a relation of type \(A \rightarrow B\) as a subset of \(A \rightarrow B\). In our situation, from \(P \subseteq (X \rightarrow D)\) to \(Q \subseteq (n \rightarrow X)\) so that \(\lambda x. P = Q\) with \(Q = \{\lambda x. p \mid p \in P\}\).

This use of lambda is similar to the one found in Section 9.3 of [1].

3. Another natural extension of item\(^1\) is a transformation from a function \(f \in (X \rightarrow D) \rightarrow D\) to a function \(g \in (n \rightarrow D)\). As in item\(^1\) we have that \(d = \lambda x. \chi\).

Suppose that \(f\) and \(g\) are related by \(f(\chi) = g(d)\) for all \(\chi \in (X \rightarrow D)\). Then we have \(g(\lambda x. \chi) = f(\chi)\) for all \(\chi \in (X \rightarrow D)\). As extension to functions of the lambda mechanism, we write instead \(g = \lambda x. f\).

4. Predicate logic as programming language

A functional programming language is one that is based on the lambda calculus or on combinatory logic. Similarly, a logic programming language would be one that is based on predicate logic. The attraction of the latter is that logic is more popular for program specification than lambda calculus.

Pure Prolog is a programming language, and it is based on first-order predicate logic. It is a special case in several ways: it is based on the clausal form of logic, it presupposes execution by a particular resolution theorem prover, and its data domain is the Herbrand universe of the program. The last restriction is lifted in the Prologs that are used in practice, and this has compromised its relation to logic.

The fact that pure Prolog is based on a thin slice of logic and its tenuous relationship to practice suggest that we consider anew the potential of first-order predicate logic as a programming language.

Logic has a lot going for it as starting point for a programming language. It has function symbols denoting functions and predicate symbols denoting relations. Variable-free terms denote objects and variable-free formulas denote truth values. Among the things that are lacking are facilities to define new functions and relations in terms of existing ones. In this section we describe how these facilities can be added by means of the lambda mechanism.

4.1 Semantics of logic formulas

According to an interpretation \(I\), an \(n\)-ary function symbol \(f\) denotes an \(n\)-argument function \(I(f)\) over a universe of discourse \(D\). An \(n\)-ary predicate symbol \(p\) denotes a relation \(I(p)\) consisting of \(n\)-tuples of elements of \(D\).

**Definition 1.** The meaning \(M^I\) of variable-free terms and formulas under interpretation \(I\) is defined as follows.

- \(M^I(c) = I(c)\) if \(c\) is a constant.
- \(M^I(f(t_0, \ldots, t_{n-1})) = (I(f))(M^I(t_0), \ldots, M^I(t_{n-1}))\) if \(f\) is a function symbol.
- \(q(t_0, \ldots, t_{k-1})\) is true in \(I\) iff \((M^I(t_0), \ldots, M^I(t_{k-1})) \in I(q)\) if \(q\) is a predicate symbol.
- A conjunction \(E_0 \land \cdots \land E_{n-1}\) of formulas is true in \(I\) iff \(E_i\) is true in \(I\) for all \(i \in n\).
- A disjunction \(E_0 \lor \cdots \lor E_{n-1}\) of formulas is true in \(I\) iff \(E_i\) is true in \(I\) for at least one \(i \in n\).
- A formula that is the negation of \(E\) is true in \(I\) iff \(E\) is not true in \(I\).

We regard the formula “\(A\) if \(B\)” true if and only if \(A\) is true or the negation of \(B\) is true.

We now consider meanings of formulas with a set \(V\) of free variables, possibly, but not typically, empty. Let \(\alpha\) be an assignment, which is a function in \(V \rightarrow D\), assigning an individual in \(D\) to every free variable. In other words, \(\alpha\) is a tuple of elements of \(D\) indexed by \(V\). As meanings of expressions with variables depend on \(\alpha\), we write \(M^I_{\alpha}\) for the function mapping a term to an element of the universe \(D\) and for mapping a formula to a truth value.

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\(^1\) It has been suggested [10] to write this as \(\chi = \lambda^{-1} x. d\), but this may be going too far.
DEFINITION 2. \( M^f_t \) is defined as follows.

- \( M^f_t(t) = \alpha(t) \) if \( t \) is a variable
- \( M^f_t(c) = I(c) \) if \( c \) is a constant
- \( M^f_t((t_0, \ldots, t_{n-1})) = (I(f))(M^f_t(t_0), \ldots, M^f_t(t_{n-1})) \)
- \( q(t_0, \ldots, t_{k-1}) \) is true or false in \( I \) with \( \alpha \) according to whether \((M^f_{\alpha}(t_0), \ldots, M^f_{\alpha}(t_{k-1})) \) is in \( I(q) \).

Now that satisfaction of atoms is defined, we can continue inductively with satisfaction of complex formulas.

- A conjunction \( \{ E_0 \land \ldots \land E_{n-1} \} \) is true in \( I \) with \( \alpha \) iff the formula \( E_i \) are true in \( I \) with \( \alpha \), for all \( i \in n \).
- A disjunction \( \{ E_0 \lor \ldots \lor E_{n-1} \} \) is true in \( I \) with \( \alpha \) iff there is a \( d \in D \) such that \( E \) is true in \( I \) with \( \alpha \) for at least one \( i \in n \).
- If \( E \) is a formula, then \( \exists x.E \) is true in \( I \) with \( \alpha \) iff there is a \( d \in D \) such that \( E \) is true in \( I \) with \( \alpha \) such that maps \( x \) to \( d \) and maps the other variables according to \( \alpha \).
- If \( E \) is a formula, then \( \forall x.E \) is true in \( I \) with \( \alpha \) iff for all \( d \in D \), \( E \) is true in \( I \) with \( \alpha \) such that maps \( x \) to \( d \) and maps the other variables according to \( \alpha \).

DEFINITION 3. Let \( F \) be a formula with set \( V \) of free variables. We define

\[ M^I(F) = \{ \alpha \in (V \rightarrow D) \mid F \text{ is satisfied by } I \text{ with } \alpha \}. \]

4.2 Defining new functions in terms of existing ones

So far, \( M^f \) has assigned meanings only to variable-free terms. This is now extended as follows to terms with free variables.

DEFINITION 4. If \( t \) is a term with set \( V \) of variables, then \( M^f_t \) is the function of type \((V \rightarrow D) \rightarrow D \) that maps \( \alpha \in (V \rightarrow D) \) to \( M^f_t(\alpha) \in D \).

EXAMPLE 1. \( D \) is the set of natural numbers and \( I \) is an interpretation in which \( I(+) \) is addition and \( I(\times) \) is multiplication.

\[ (M^I(x + y \times z))(x = \frac{1}{2}, \ y = \frac{3}{2}) = 7. \]

Tabular tuple notation is explained in Section 2.

Thus we see that a term \( t \) with set \( V \) of free variables can be used to define a function in \((V \rightarrow D) \rightarrow D \). However, we cannot use this to define the meaning of a new function symbol, as this meaning has to be a function in \( D^{\mid V\mid} \rightarrow D \). The required conversion can be made by the lambda mechanism.

DEFINITION 5. Let \( t \) be a term with set \( V \) of variables and let \((x_0, \ldots, x_{n-1})\) be one of the \( n! \) enumerations of the \( n \) variables in \( V \). Let \( f \) be a function symbol that does not occur in \( t \) and that is not interpreted by \( I \). We define the result of the extending \( I \) to be \( I(f) = \lambda(x_0, \ldots, x_{n-1} \cdot M^f_t) \), where the right-hand side is defined by item 2 on page 3.

Note that this definition rules out recursivity both directly and indirectly via other interpretation extensions.

EXAMPLE 2. \( D \) is the set of natural numbers and \( I \) is an interpretation in which \( I(+) \) is addition and \( I(\times) \) is multiplication. The same term \( x + y \times z \) can be used to extend \( I \) with function symbol \( f \) by defining \( I(f) \) as \( \lambda(x, y, z) \cdot M^I(x + y \times z) \) and by defining \( I(g) \) as \( \lambda(y, z, x) \cdot M^I(x + y \times z) \). With these extensions of \( I \) we have \( M^I(f(1, 2, 3)) = 7 \) and \( M^I(g(1, 2, 3)) = 5 \).

4.3 Defining new relations in terms of existing ones

The reason why Definition 5 rules out recursivity is that the function symbols denote total functions. Cartwright [4] responds to the need for recursive definitions by restricting the domain of discourse to those that are partially ordered with a unique least element that is interpreted as undefined. Our response to the need for recursivity is to represent partial functions via predicate symbols as relations. In this way there is no need to change the generality of allowing any domain of discourse, partially ordered or not. Without changing the classical semantics of first-order predicate logic \( n \)-ary relations of a given type are partially ordered as sets of tuples and include the empty tuple. Because of this the possibility of defining new relations from existing ones is more important than that of defining new functions. Here also the lambda mechanism is used.

Predicate logic does not provide a facility for defining new relations. To make up for this deficiency we introduce “predicate extensions”.

Syntax of predicate extensions

DEFINITION 6. A predicate extension is a set of expressions containing, for \( j \in k \ (k \geq 0) \),

\[ p_j := \lambda(x_{j,0}, \ldots, x_{j,n_j-1}) \cdot F_{j,0} \lor \cdots \lor F_{j,m_j-1} \]

where each of \( F_{j,0}, \ldots, F_{j,m_j-1} \) is a possibly existentially quantified conjunction of atoms. These expressions satisfy the following two constraints: (1) no two of the \( p_j \) are the same predicate symbol and (2) \((x_{j,0}, \ldots, x_{j,n_j-1})\) is an enumeration of the free variables in \( F_{j,0} \lor \cdots \lor F_{j,m_j-1} \).

We use “=” in the definition of \( p_j \) because of the prevailing convention in logic to use “=” to denote the identity relation over the domain of discourse. See Example 3.

EXAMPLE 3. (For a possible interpretation see Example 2)

\[ \{ \text{even } := \lambda(x). x = 0 \lor (\exists y. x = s(y) \land \text{odd}(y)), \text{ \ odd } := \lambda(x). x = s(0) \lor (\exists y. x = s(y) \land \text{even}(y)) \} \]

is a predicate extension that introduces the predicate symbols even and odd on the basis of the existing predicate symbol =.
Semantics of predicate extensions  Predicate extensions are syntactic structures that introduce new symbols. The intent is to define new relations as denotations of the new symbols. As a preparation for such a definition we introduce a class of interpretations for which the definition is valid.

**Definition 7.** An DFP-set of interpretations for a given predicate extension is a set containing interpretations with the following properties: (1) have the same domain D (2) have the same interpretation for the function symbols of the predicate extension (3) have the same interpretation for the predicate symbols that occur in the right-hand sides and not in the left-hand sides of the predicate extension.

Thus the interpretations of a DFP-set differ only in the interpretations of the predicate symbols occurring in the left-hand sides.

**Example 4.** A DFP-set for Example could have the natural numbers as domain D, interpret s as the successor function, and interpret = as the identity relation over the natural numbers.

**Definition 8.** Given a predicate extension E as in Definition All DFP-sets for E are partially ordered by ≤ where I₀ ≤ I₁ if for all predicate symbols p we have I₀(p) ⊆ I₁(p). The intersection of I₀ and I₁ is the interpretation I in the DFP-set for which I(p) = I₀(p) ∩ I₁(p) for all predicate symbols p in E.

**Definition 9.** Given a predicate extension E as in Definition I in a DFP-set of interpretations for E is a model of E iff

\[ \lambda(x₀, . . . , x_{j,m_j-1}).M_I(F_{j,0} \lor \cdots \lor F_{j,m_j-1}) \subseteq I(p_j) \]

for all j ∈ k.

Here \( \lambda \) is used according to Item 2 on page 3 and \( M_I \) is used according to Definition 3.

**Definition 10.** The formula corresponding to a predicate extension P as in Definition is the formula \( \bigwedge H₀ \land \cdots \land H_{k-1} \) where, for all j ∈ k, \( H_j \) is

\[ \forall x₀, . . . , x_{j,n_j-1}.p_j(x₀, . . . , x_{j,n_j-1}) \text{ if } (F_{j,0} \lor \cdots \lor F_{j,n_j-1}) \]

This correspondence allows us to use some results from 15.

**Lemma 1.** Let I be an interpretation in the DFP-set of a predicate extension P as in Definition. The formula corresponding to P is true in I iff I is a model of P (see Definition 2).

**Proof.** Let \( F_j \) abbreviate \( F_{j,0} \lor \cdots \lor F_{j,m_j-1} \). Let \( X_j \) abbreviate \( x₀, . . . , x_{j,n_j-1} \). For all j ∈ k:

1. \( H_j \) is true in I \( \iff \) (1)
2. \( M_I(F_j) \subseteq M_I(p(X_j)) \) \( \iff \) (2)
3. \( \lambda(X_j).M_I(F_j) \subseteq \lambda(X_j).M_I(p(X_j)) \)
4. \( \lambda(X_j).M_I(F_j) \subseteq I(p_j) \)

I is a model of \( P \)

1. (1) Lemma 1 in 15, (2) Monotonicity of \( \lambda \), (3) Definition of \( \lambda \) applied to sets of tuples, and (4) Definition 2.

**Theorem 1.** Every predicate extension has a minimal model.

**Proof.** By Theorem 5 in 15, every formula corresponding to a predicate extension has a minimal model. By Lemma 1, we conclude that every predicate extension has a minimal model.

**Example 5.** With the interpretation of Example 2 the minimal model assigns to predicate symbol “even” (“odd”) the set of even (odd) numbers.

We conclude that for every predicate extension, every one of its DFP-sets has a model that is minimal in the partial order. We consider the relations denoted in the minimal model by the predicates in the left-hand sides to be the result of the predicate extension. In this way we have added to first-order predicate logic a method for defining new relations in terms of existing ones. Note its use of the lambda mechanism.

5. The lambda mechanism for Algol-like languages

It is desirable in programming that basic components be easy to write and that components can be combined with ease and with few restrictions. Functional programming is attractive because functions are such components; they are easier to combine with fewer restrictions compared to, say, C.

Side effects don’t seem to combine naturally with functional programming. This makes Algol 60 interesting, as side effects are endemic in it and because procedures are a simple way of creating and combining components with relatively few restrictions.

This suggests the following experiment. Take as starting point a minimal imperative language; that is, without any facility for creating functions or procedures. Then add a facility for declaring and calling procedures modelled on the one of Algol 60. In the interest of simplicity and clarity “function procedures” will not be included in the experiment.

How to arrive at a minimal imperative language? Perhaps drop for-statements and arrays from Algol 60? What about switches? To bypass such questions we take a radical approach and appeal to the reader’s intuitive understanding of flowcharts and exploit the fact that these can be expressed in Algol 60. This allows us to replace the considerable amount of detail that goes into specifying the imperative part of Algol 60 by a compact specification of flowcharts, which we will leave at an abstract level.
5.1 Flowcharts without procedures

5.1.1 Syntax

“Syntax” may be a bit misleading, but it is a useful label to contrast with Section 5.1.2, Semantics. What we are concerned here is abstract syntax, the structure of flowcharts independent of graphical or textual representation.

A flowchart is a tuple \( \langle D, N, B, T \rangle \), where

1. \( D \) is a set of declarations. A declaration allocates a memory location and associates it with an identifier. This association is local to the flowchart.
2. \( N \) is a set of nodes,
3. \( B \) is a set of boxes. A box contains an assignment statement, which has an identifier as left-hand side and an arithmetic expression as right-hand side.
4. \( T \) is a set of tests. A test contains a boolean expression.

The components \( N, B, \) and \( T \) constitute the body of the flowchart. The identifiers occurring in the body have to be declared in \( D \).

Boxes, and tests are structured as follows. A box is a tuple \( \langle n_0, a, n_1 \rangle \), where \( n_0 \) is a node, the entry node of the box, \( a \) is the assignment statement, and \( n_1 \) is a node, the exit node of the test.

A test is a tuple \( \langle n_0, b, n_1, n_2 \rangle \), where \( n_0 \) is a node, the entry node of the test, \( b \) is the boolean expression, \( n_1 \) is a node, the positive exit node of the test, and \( n_2 \) is a node, the negative exit node of the test.

The nodes are not structured. They serve to connect boxes and tests by a node being an exit node of a test or box and being the entry node of another test or box. No node can be the entry node of more than one box. One node, the start node, is not an exit node of any box or test. One node, the halt node, is not an entry node of any box or test.

A translation of flowcharts to text can easily be defined. No new insights will be gained by presenting one here. We will merely assume that one exists.

5.1.2 Semantics

Operational semantics Executing the declarations results in the creation of the environment which, in the absence of procedures, consists only of a tuple of locations indexed by identifiers.

The state of a flowchart is a tuple \( \langle k, d \rangle \) where \( k \), the control state, is a node and where \( d \), the data state, is the contents of the tuple created by executing the declarations.

A transition of a flowchart is a change from state \( \langle k, d \rangle \) to state \( \langle k', d' \rangle \). If \( k \) is the entry node of a box, then \( k' \) is the exit node of that box and \( d' \) is the result of executing the assignment statement of the box starting in data state \( d \). If \( k \) is the entry node of a test, then \( d' = d \) and \( k' \) is the positive (negative) exit node of that test if evaluation of the boolean expression in data state \( d \) yields true (false).

Declarative semantics The declarative semantics of a box with assignment \( a \) is a binary relation of data states: the set of all \( \langle d, d' \rangle \) such that executing \( a \) with \( d \) as data state results in data state \( d' \).

\[ x := x-y \\
\]

\[ y := y-x \]

Figure 2. Example of a flowchart. Every small filled circle represents a node. Two such circles that are connected by a line without an arrow represent the same node. They are shown separated only for the convenience of graphical representation. Boxes are shown as rectangles; tests as ovals. A line with an arrow pointing away from a box or test points to an exit node of the box or test. A line with an arrow pointing towards a box or test comes from an entry node of the box or test. The positive and negative exit nodes of a test are indicated by plus and minus symbols, respectively.

A state is the successor of a state if there is a transition of the former to the latter. Every state has a successor except for the states in which the control state is the halt node.\(^{3}\)

A computation of a flowchart is a sequence of states in which the first state has the start node as control state and in which every next state is the successor of the state preceding it in the computation.

The meaning of a flowchart according to operational semantics is the binary relation on data states consisting of all pairs \( \langle d, d' \rangle \) such that there is a computation beginning with \( \langle s, d \rangle \) and ending with \( \langle h, d' \rangle \), where \( s \) and \( h \) are start and halt nodes, respectively.

---

3 The operations in arithmetic and in boolean expressions are built-in and their executions always terminate.
The declarative semantics of a test with boolean expression \( b \) is a pair of complementary subsets of the identity relation on data states, a positive subset and a negative subset. The positive (negative) subset is the set of all \( (d, d) \) such that evaluation of \( b \) yields true (false).

A declarative semantics of a flowchart can be defined by means of a matrix \( M \) of which the rows and columns are indexed by the nodes of the flowchart and of which the elements are binary relations over the data states of the flowchart. For every box with entry node \( i \) and exit node \( j \) \( M[j, i] \) is the relation denoted by that box. For every test with entry node \( i \), positive exit node \( j \), and negative exit node \( k \), \( M[j, i] \) is the positive and \( M[k, i] \) is the negative part of the decomposition of the identity denoted by the test. All other elements of \( M \) are the identity relation over data states.

The matrix representation of flowcharts shows them to be an instance of the “dual-state machines” of [14]. Theorem 2 of [14] implies that the operational and declarative semantics as given here are equivalent; that is, define the same binary relation.

5.2 Flowcharts with procedures

In Algol 60 procedure calls are reminiscent of substitution in lambda calculus. In fact, it is plausible that the lambda calculus and Algol 60 share a common origin in informal mathematics dating back to at least early 19th century. Consider for example \( f \) defined by

\[
f(j) = \Sigma_{i=1}^{n} ij
\]

In mathematics it goes without saying that

- the value of \( (3) \) is not changed if the occurrences of \( i \) are replaced by any other variable, except \( j \), and
- that such a change is mandatory if \( (3) \) is substituted for \( f \) in \( \Sigma_{i=1}^{n} f (i) \).

Similarly we have, in lambda calculus

Definition 1.11 (Substitution) For any \( M, N, x \) define \( [N/x]M \) to be the result of substituting for every free occurrence of \( x \) in \( M \), and changing bound variables to avoid clashes.

This is from Hindley and Seldin [9], where it is followed by a precise definition.

In the definition of Algol 60 [2] we find a similar stipulation:

4.7.3.3 Body replacement and execution. Subsequently the body, modified in this way, is inserted in place of the procedure statement and is executed. If the procedure is called from a place outside the scope of any quantity non-local to the procedure body, then any conflicts between the identifiers inserted through this process of body replacement and the identifiers whose declarations are valid at the place of the procedure statement are avoided by suitable systematic changes of the latter identifiers.

So far boxes in flowcharts can only contain assignment statements. Let us consider adding the possibility that the state transition effected by a box is the result of a procedure call and that the body of the procedure is a flowchart.

5.2.1 Using the lambda mechanism

The idea behind the lambda mechanism is that any expression with free variables defines a function. Here the term “variable” derives from lambda calculus. In the context of flowcharts it is prudent to avoid this term, so we use “location” for what is usually called “variable” in imperative languages and “formal parameter” for “variable” in the context of the lambda mechanism.

Thus the idea behind the lambda mechanism that any expression with free variables defines a function is rephrased in the context of flowcharts to the idea that any flowchart where certain identifiers have been designated as formal parameters defines a function of which the values are binary relations over states. Such a function is called “procedure”.

The most flexible procedure mechanism would allow any identifier in a statement to be designated as a parameter. We propose to follow the rule of Algol 60 where this is indeed allowed and where procedure calls are limited to those where the replacement of actual parameters by formal parameters yields a valid statement. This rule allows an identifier in the left-hand side of an assignment statement to be a formal parameter and forbids the corresponding actual parameter to be anything but an identifier associated with a location.

Definition 11. A procedure is a set of declarations of locations followed by a set of declarations of procedures followed by the body of the procedure. The set of declarations of procedures consists of, for all \( j \in k \) with \( k \geq 0 \),

\[
p_j = \lambda (x_{j,0}, \ldots, x_{j,n_j-1}). P_j
\]

satisfying the following constraints: (1) each of \( P_j \) is a procedure, (2) no two of the identifiers \( p_j \) are the same, and (3) \( (x_{j,0}, \ldots, x_{j,n_j-1}) \) is an enumeration of the formal parameters in \( P_j \).

The body of the procedure is the body of a flowchart, except that it may contain identifiers that are not declared in the procedure’s declaration.

Example 6. This example is a complicated way of computing the GCD of two numbers. It is distributed over four procedures with mutual recursion between three of them. See Figures 3 and 5.

5.2.2 Operational semantics of the procedure call

The declarations of the procedure (see Definition [11]) create the environment that determines the effect of executing the
nat X,Y,Z;
gcd0 = \lambda(x,y,z).G0
gcd1 = \lambda(x,y,z).G1
gcd2 = \lambda(x,y,z).G2

\begin{figure}
\centering
\begin{tikzpicture}
\node [startstop] (start) {start};
\node [input] (in) {X := 100; Y := 161};
\node [process] (proc) {gcd2(X,Y,Z)};
\node [stop] (stop) {halt};
\node [decision] (dec) {x == y};
\node [decision] (dec2) {x < y};
\node [input] (in1) {gcd0(x,y,z)};
\node [input] (in2) {gcd1(x,y,z)};
\node [stop] (stop1) {halt};
\node [process] (proc2) {gcd2(x,y,z)};

\draw [arrow] (start) -- (in);
\draw [arrow] (in) -- (proc);
\draw [arrow] (proc) -- (dec);
\draw [arrow] (dec) -- node [sloped, below] {\checkmark} (in1);
\draw [arrow] (dec) -- node [sloped, above] {\times} (in2);
\draw [arrow] (in1) -- (proc2);
\draw [arrow] (in2) -- (proc2);
\draw [arrow] (stop) -- (proc);
\draw [arrow] (proc) -- (dec2);
\draw [arrow] (dec2) -- node [sloped, below] {\checkmark} (proc2);
\draw [arrow] (dec2) -- node [sloped, above] {\times} (proc2);
\draw [arrow] (proc2) -- (stop1);
\end{tikzpicture}
\caption{Procedure main. \(G0\) and \(G1\) are the text representations of the flowcharts in Figure 4. \(G2\) is the text representation of the flowchart in Figure 5.}
\end{figure}

\begin{figure}
\centering
\begin{tikzpicture}
\node [startstop] (start) {start};
\node [input] (in) {x := x-y};
\node [process] (proc) {gcd2(x,y,z)};
\node [stop] (stop) {halt};
\node [decision] (dec) {x == y};
\node [process] (proc2) {gcd2(x,y,z)};

\draw [arrow] (start) -- (in);
\draw [arrow] (in) -- (proc);
\draw [arrow] (proc) -- (dec);
\draw [arrow] (dec) -- node [sloped, below] {\checkmark} (proc2);
\draw [arrow] (dec) -- node [sloped, above] {\times} (proc2);
\draw [arrow] (proc2) -- (stop);
\end{tikzpicture}
\caption{The procedures gcd0 (left) and gcd1 (right). Neither has any declarations. The identifiers \(x, y,\) and \(z\) are formal parameters.}
\end{figure}

\begin{figure}
\centering
\begin{tikzpicture}
\node [startstop] (start) {start};
\node [input] (in) {y := y-x};
\node [process] (proc) {gcd2(x,y,z)};
\node [stop] (stop) {halt};
\node [decision] (dec) {x < y};
\node [process] (proc2) {gcd2(x,y,z)};

\draw [arrow] (start) -- (in);
\draw [arrow] (in) -- (proc);
\draw [arrow] (proc) -- (dec);
\draw [arrow] (dec) -- node [sloped, below] {\checkmark} (proc2);
\draw [arrow] (dec) -- node [sloped, above] {\times} (proc2);
\draw [arrow] (proc2) -- (stop);
\end{tikzpicture}
\caption{The procedure gcd2. It has no declarations. The identifiers \(x, y,\) and \(z\) are parameters.}
\end{figure}

body of the procedure. This environment consists of two parts.

1. A tuple of locations indexed by identifiers.
2. A tuple of procedures indexed by identifiers.

The effect of the procedure call is specified when, for every data state of the caller, it is determined whether the call terminates and, if so, what the resulting data state of the caller will be. This is specified by the following steps.

1. Create the environment for the call. This environment is created by adding the callee’s environment to that of the caller while omitting declarations in the caller’s environment of variables that are declared in the callee’s environment.

2. Modify the body of the procedure. In the body of the procedure formal parameters are replaced by actual parameters after enclosing the latter in parentheses wherever syntactically possible. Possible conflicts between identifiers inserted through this process and other identifiers already present within the procedure body are avoided by suitable systematic changes of the identifiers involved.

3. Start execution of the body in the modified environment. The quote from [2] on page 7 applies.

4. In case of termination, restore the environment of the caller on termination.

\footnote{From [3], section 4.7.3.2.}
6. The lambda mechanism in the lambda calculus

We have demonstrated the lambda mechanism in first-order predicate logic and in an imperative programming language. In both cases the starting point was a base language of expressions of which the meaning could only be determined with the assignment of values to parameters. In predicate logic the base language was that of formulas. In the imperative programming language the base language was that of flowcharts. In both cases the lambda mechanism made it possible to define procedures, with partial functions as special case.

With these two examples in front of us, let us consider the question whether the lambda calculus is also an instance of the lambda mechanism. If so, then there must be a base language. What is it in the case of the lambda calculus?

The reason why the lambda mechanism has not been noticed in the lambda calculus may well be that the base language is so small: no constants (in the pure lambda calculus, usually the only form that is studied), and, apart from one binary operation for application, only variables. Moreover, abstraction acts on a single variable.

When we have a lambda expression $N$ with one free variable $x$, then $N$ by itself denotes a function, and it is a function of type $(\{x\} \to D) \to D$ when we interpret variables as functions of type $D \to D$. The difference lies in the distinction in the argument type $\{x\} \to D$ in the first case and $D$ in the second case. As stated in Section 2 $\{x\} \to D = D[\{x\}]$. Thus we see that $\{x\} \to D \neq [D]$. In other words, there is a bijection between these two sets. This may explain why we ignore the distinction between them.

7. Related work

Predicate extensions are similar to the relational programs of [12]. In turn, relational programs are closely related to Prolog programs.

For the semantics of flowcharts we have relied on the theory of dual-state automata, which is the subject of [14].

8. Future work

Definition 2 for flowcharts with procedures is similar to Definition 5 for predicate extensions. Yet for predicate extensions we have given a declarative semantics, while this is lacking so far for flowcharts with procedures. The reason for the difference is that we followed Algol 60 in allowing formal parameters to be procedure identifiers, thus making flowcharts with procedures a higher-order formalism in the sense that predicate extensions stay within first-order predicate logic.

If one would disallow procedure identifiers as parameters, then it seems that one could use predicate extensions as analogy to define models and to show that a unique minimal model can be identified as declarative semantics for flowcharts with procedures.

9. Conclusions

Lambda calculus is usually credited to Church’s 1941 publication [6]. In Church’s 1932 paper [5] he introduces a lambda notation, but not the lambda calculus. In another instance of the distinction, Landin gives as title of his paper “A correspondence between ALGOL 60 and Church’s Lambda-notation”. This paper proposes a mathematical interpretation of the distinction. Because of the added precision we were emboldened to graduate from mere “notation” to the “lambda mechanism”.

Although the lambda mechanism fails to cover the use of lambda notation in Church’s [5], we show that the lambda calculus itself is an instance and that another instance adds a facility to first-order predicate logic to define new functions and predicates in terms of existing ones, thus bringing logic closer to being usable as a programming language. Finally, we proposed to base procedures in Algol-like languages on the lambda mechanism.

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