Controlling Conditional Language Models with Distributional Policy Gradients

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Abstract

Machine learning is shifting towards general-purpose pretrained generative models, trained in a self-supervised manner on large amounts of data, which can then be applied to solve a large number of tasks. However, due to their generic training methodology, these models often fail to meet some of the downstream requirements (e.g. hallucination in abstractive summarization or wrong format in automatic code generation). This raises an important question on how to adapt pre-trained generative models to a new task without destroying its capabilities. Recent work has suggested to solve this problem by representing task-specific requirements through energy-based models (EBMs) and approximating these EBMs using distributional policy gradients (DPG). Unfortunately, this approach is limited to unconditional distributions, represented by unconditional EBMs. In this paper, we extend this approach to conditional tasks by proposing Conditional DPG (CDPG). We evaluate CDPG on three different control objectives across two tasks: summarization with T5 and code generation with GPT-Neo. Our results show that fine-tuning using CDPG robustly moves these pretrained models closer towards meeting control objectives and — in contrast with baseline approaches — does not result in catastrophic forgetting.

1 Introduction

Pretrained generative models are shifting the landscape of machine learning research and practice. General purpose models such as the GPT family (Radford et al., 2019; Brown et al., 2020; Black et al., 2021), T5 (Raffel et al., 2020), CLIP (Radford et al., 2021) and Codex (Chen et al., 2021) are trained in a self-supervised manner on large amounts of uncurated data and can then be adapted to specific downstream tasks (e.g. generating Python code) or control objectives (e.g. controlling the style of generated code). Frequently, control objectives are motivated by the desire to address the shortcomings of certain pretrained models. These can be due to the uncurated nature of the original training data (e.g. a large portion of Python source code on the Internet violates PEP8 (van Rossum et al., 2001), the Python Style Guide) or the difficulty of learning a desired behaviour by purely self-supervised training (e.g. there is not enough training signal to ensure that a model trained on source code always generates compilable code or that a summarization model always produces factually correct summaries).

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The practice of adapting and controlling pretrained generative models poses two open problems. The first is that control objectives frequently lack ground truth data that could be used for supervised fine-tuning; in general, we are only given an indicator $b(x)$ of whether a given sample from the model $x$ satisfies a given control objective. Thus, approaches such as reinforcement learning (RL) (Pasunuru & Bansal, 2018; Ziegler et al., 2019), weighted decoding (Ghazvininejad et al., 2017; Holtzman et al., 2018; See et al., 2019) or decoding with perturbed activations (Dathathri et al., 2020) need to be employed. The second problem is catastrophic forgetting: most approaches to enforcing a control objective result in a dramatic loss of capabilities of the original model beyond the scope of the control objective. Notably, there exists one approach largely avoiding both of these problems (Parshakova et al., 2019a; Khalifa et al., 2021): representing the control objective as an energy-based models (EBM) and approximating that EBM using distributional policy gradients (DPG).

Although this approach shows great improvements in controlling pretrained language models while avoiding catastrophic forgetting (Khalifa et al., 2021), it is limited to unconditional generation tasks and is not able to fine-tune conditional models that are behind the most impactful NLP tasks such as machine translation, summarization or dialogue systems.

In this paper, we present Conditional DPG (CDPG), an extension of DPG that can approximate conditional EBMs. A conditional EBM $P$ defines an unnormalized distribution for each context $c$ (e.g. a source document). Extending the approach of Khalifa et al. (2021) we build a conditional EBM that represents the ideal behaviour of a generative model given context $c$ as the distribution that incorporates the control objectives while remaining as close as possible to the original distribution. Then, to approximate conditionals EBMs we build unconditional EBMs $P_c$ on the fly for any given context and estimate their normalizing constants $Z_c = \sum_x P_c(x)$ by importance sampling.

We demonstrate the effectiveness of CDPG in addressing shortcomings of pretrained generative models by considering two tasks, summarization and code generation, and two corresponding pretrained generative models: T5 (Raffel et al., 2020) and GPT-Neo (Black et al., 2021). An open problem in summarization is ensuring that summaries are factually faithful to source documents given that summarization models are prone to hallucinating named entities never mentioned in the source (Maynez et al., 2020). We show that a preference for factually faithful summaries (operationalized as entity-level factual consistency (Nan et al., 2021)) can be represented by a conditional EBM. Then, we show that using CDPG to fine-tune T5 to approximate this EBM increases the number of correct and relevant named entities in summaries and improves T5’s Rouge score. In contrast with RL approaches, CDPG does not degrade the diversity and quality of summaries. For code generation, we consider the task of generating a Python function given its signature (name and arguments). While general-purpose language models can generate idiomatic Python functions (Chen et al., 2021; Austin et al., 2021), they still may struggle to learn some desirable properties of generated code. For instance, a Python function generated by GPT-Neo will compile only 40% of the time and will contain on average 4 violations of PEP8. We show that using CDPG to approximate a conditional EBM expressing corresponding constraints improves both compilability and PEP8-compliance without hurting the diversity of summaries or leading to degeneration (Holtzman et al., 2020).

To summarize, the contributions of this paper are as follows:

1. We introduce a formal framework for representing control objectives for conditional generative models as conditional EBMs,

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2See Appendix A for an extended discussion of related work.
2. We design CDPG, an extension of DPG suitable for approximate conditional EBMs,
3. We evaluate CDPG on three control objectives across two tasks: summarization constrained
to be factually correct, code generation constrained to generate compilable Python functions
and code generation constrained to respect PEP8.

2 Method

Conditional EBMs A standard, “unconditional” EBM is a function $P$ from a (discrete, i.e. finite
or countable) space $X$ to the non-negative reals, such that the partition function $Z = \sum_{x \in X} P(x)$
is strictly positive and finite. We will denote by lowercase $p$ the normalized distribution over $X$
associated with $P$, namely $p(x) = P(x)/Z$. Let us now consider a discrete, potentially infinite set
$C$ of conditions $c$. Formally, $P$, a conditional EBM over $C$, is defined as a function from $C$ to the set
of unconditional EBMs over $X$, in other words, a function that maps each $c \in C$ to an unconditional
EBM $P_c$ over $X$:

$$P : c \mapsto P_c,$$

$$P_c : x \mapsto \mathbb{R}_+.$$ (1) (2)

We denote by $Z_c$ the partition function of $P_c(x)$, namely: $Z_c = \sum_{x \in X} P_c(x)$, and by $p_c(x)$ the
normalized version of $P_c(x)$, namely: $p_c(x) = P_c(x)/Z_c$. We will use the shortcut notation $P(x|c)$ to
denote $P(c|x)$: a conditional EBM $P$ evaluated first at a given context $c$ (resulting in an unconditional
EBM $P_c$) and then at given $x$ (resulting in a non-negative EBM score).

Representing constraints as conditional EBMs The problem of fine-tuning a pretrained model
$a(x|c)$ to satisfy a control objective (e.g. generating factually correct summaries) can be seen as a
constraint satisfaction problem: finding a model $p(x|c)$ that meets the demands of the control
objective but at the same time stays as close as possible to the original pretrained model $a(x|c)$. We
represent such an optimal model as a conditional EBM $P(x,c)$. A control objective can be defined
in terms of a binary scorer $b(x,c)$ such that $b(x,c) = 1$ if a sample $(c,x)$ satisfies a constraint
given by a control objective (e.g. $x$ is factually correct with respect to $c$) and $b(x,c) = 0$ otherwise.
Let us consider a set of contexts $c \in C$. For each $c$, there is a unique model $p_c(x)$ such that (i)
$b(x,c) = 1$ for all samples $x \sim p_c(x)$, and (ii) $p_c(x)$ has minimal KL divergence from $a(\cdot|c)$.
Following our example, $p_c$ could be a distribution over factually correct summaries of $c$ as similar
as possible to a distribution over summaries the original model $a$ would produce for a document
c. In information-geometric terms, $p_c$ is an I-projection of $a$ onto the manifold of all distributions
satisfying a constraint given by $b$ (Csiszár & Shields 2004). As shown by (Khalifa et al. 2021), $p_c$
can be represented as an unconditional EBM $P_c(x)$ of the following form:

$$P_c(x) = a(x|c)b(x,c).$$ (3)

Approximating conditional EBMs While $P$ represents the target conditional model optimally
reconciling distance from $a(x|c)$ and the control objective, sampling or MAP decoding for $p(x|c)$
is intractable for two reasons. First, $p(x|c)$ actually represents a potentially infinite collection of
unconditional models of the form $p_c(x)$. Second, each of these conditional models still cannot
be easily sampled from because they do not admit an autoregressive factorisation: $b(x,c)$ is only
defined for the whole sequence $x$.

The second problem was addressed by [Parshakov et al. 2019] and [Khalifa et al. 2021] who used
the distributional policy gradients (DPG) algorithm to approximate unconditional EBMs $p$ using a
new unconditional model $\pi_\theta$ trained to minimize the cross-entropy $\text{CE}(p, \pi_\theta)$. Unfortunately, DPG
is no longer usable for conditional models that should satisfy infinitely many constraints represented
by the set of conditional EBMs defined by $P$.

To address the second problem, we instead try to find a single model $\pi_\theta$ approximating $p$ on average
across contexts. Concretely, we minimize the expected cross-entropy between $\pi_\theta$ and multiple $p_c$’s:

$$\mathcal{L}(\theta) = \mathbb{E}_{c \sim \tau(\cdot)} \text{CE}(p_c(\cdot), \pi_\theta(\cdot|c)),$$

(4)

[Khalifa et al. 2021] provide a more general, exponential family form of this EBM. The product-of-experts
[Hinton 2002] form in (3) is a special case of the exponential form, see [Khalifa et al. 2021] Appendix A.2.)
where the expectation is over \( \tau(c) \), a distribution over \( c \in C \). The gradient of this objective takes the following form:

\[
\nabla_\theta \mathcal{L}(\theta) = \mathbb{E}_{c \sim \tau(c)} \nabla_\theta \mathbb{E}_{x \sim \pi_c(\cdot \mid c)} \log \pi_\theta(x|c) - \mathbb{E}_{c \sim \tau(c)} \mathbb{E}_{x \sim p_c(\cdot)} \nabla_\theta \log \pi_\theta(x|c) \quad (5)
\]

\[
= \mathbb{E}_{c \sim \tau(c)} \mathbb{E}_{x \sim \pi_\theta(x|c)} \nabla_\theta \log \pi_\theta(x|c) \quad (6)
\]

\[
= \mathbb{E}_{c \sim \tau(c)} \mathbb{E}_{x \sim \pi_\theta(x|c)} \frac{p_c(x)}{\pi_\theta(x|c)} \nabla_\theta \log \pi_\theta(x|c), \quad (7)
\]

\[
= \mathbb{E}_{c \sim \tau(c)} \mathbb{E}_{x \sim \pi_\theta(x|c)} \frac{p_c(x)}{Z_c \pi_\theta(x|c)} \nabla_\theta \log \pi_\theta(x|c), \quad (8)
\]

where in (7) we applied importance sampling from \( \pi_\theta \) and (8) expresses \( p_c \) in terms of unconditional EBM \( P_c \) and its partition function \( Z_c \).

We approximate both expectations in (8) by sampling. Intuitively, this corresponds to building unconditional EBM \( P_c(\cdot) \) on the fly for each \( c \sim \tau(c) \), computing the EBM “score” \( P_c(x) \) for each sample from the conditional model \( x \sim \pi_\theta(\cdot | x) \) and then using this score as a “pseudoreward” term \( P_c(x)/Z_c \pi_\theta(x|c) \) in the policy gradient estimate.

**Estimating \( Z_c \)** The one term in (8) that remains difficult to evaluate is the partition function \( Z_c \). For a single unconditional EBM, Khalifa et al. (2021) had no need to evaluate its partition function \( Z_c \): it just scaled gradient estimates and therefore could be absorbed into the learning rate. In the conditional case, \( Z_c \) varies with \( c \). Therefore for each \( c \), we compute \( Z_c \) using a batch of \( M \) samples \( \{x_1, \ldots, x_M\} \) from \( \pi_\theta(x|c) \).

Then, \( Z_c \) is estimated using importance sampling by reweighting samples \( x_j \) by their likelihood according to \( \pi_\theta(\cdot|c_i) \).

**Training loop** We train \( \pi_\theta \) by stochastic gradient descent using the gradient estimate (8). At each epoch, we first sample \( N \) contexts \( c \) and then, for each \( c \), we sample \( M \) samples \( x \) from \( \pi_\theta(x|c) \). We maintain a buffer \( B \) storing each \((c_i, x_j)\) pair along with its corresponding partition function \( Z_{c_i} \). Finally, we shuffle \( B \) and iterate over it to perform gradient steps using (8) with learning rate \( \alpha(\theta) \). The procedure is summarized in Algorithm 1:

**Algorithm 1 Conditional DPG (CDPG)**

**Input:** conditional EBM \( P(x, c) \), initial model \( a(x|c) \)

1: \( \pi_\theta \leftarrow a \)
2: for each iteration do
3: \( B \leftarrow \{\} \)
4: sample batch \( \{c_1, \ldots, c_N\} \) from \( \tau(c) \)
5: for each \( c_i \) do
6: sample batch \( \{x_1, \ldots, x_M\} \) from \( \pi_\theta(x|c_i) \)
7: \( \hat{Z}_{c_i} = \frac{1}{M} \sum_{j=1}^{M} P_c(x_j|c_i) \)
8: for each \( x_j \) do
9: \( B \leftarrow (x_j, c_i, \hat{Z}_{c_i}) \)
10: for \( (x, c, \hat{Z}_{c}) \) in shuffle(\( B \)) do
11: \( \theta \leftarrow \theta + \alpha(\theta) \frac{1}{Z_c \pi_\theta(x|c)} \nabla_\theta \log \pi_\theta(x|c) \)

**Output:** \( \pi_\theta \)

3 **Experiments**

We evaluate CDPG as well as three baselines on three control objectives across two tasks: summarization and code generation. Each task is associated with \( C_{train} \), a set of contexts \( c \) used for prompting the model: these are Python function signatures in case of code generation and source documents in case of summarization. When computing evaluation metrics, we sample contexts from a held out set \( C_{test} \) not used for training. In addition to that, for each experiment, we measure \( \mathbb{E}_{c \sim \tau(c)} D_{KL}(P_c, \pi_c) \), the expected forward KL divergence from the optimal distribution \( p_c \), as well as \( \mathbb{E}_{c \sim \tau(c)} D_{KL}(\pi_\theta, a) \), the expected reverse KL divergence from the original pretrained model\(^4\).

### Footnotes

4. This last form of the gradients estimate bears some resemblance to policy gradients methods in reinforcement learning (Sutton et al., 1999) with term \( P_c(x)/Z_c \pi_\theta(x|c) \) playing the role of a pseudoreward. This similarity, however, is only partial: the objective \(^5\) that we minimize is expected cross-entropy, not expected (negative) reward.

5. See Appendix B for details of metrics calculation.
3.1 Baselines

Unconditional DPG We compare our algorithm against the original DPG for unconditional EBMs developed by Parshakova et al. (2019a) and extended by Khalifa et al. (2021). This algorithm differs from conditional DPG: it ignores the partition function $Z_c$ in the denominator of (8) assuming it to be constant (which it is for unconditional EBMs but not for conditional ones). For a fair comparison, we use the on-policy variant (called “DPG-on” in Parshakova et al. (2019b)) where we sample from $π_θ$ as opposed to a different proposal distribution $q$.

Reinforcement learning The problem of fine-tuning a pretrained model to satisfy a pointwise constraint $b(x, c)$ can be posed as maximising the expected reward $E_{c∼τ(c)}E_{x∼π_θ(x|c)}R(x, c)$. We consider two instances of this approach: Reinforce (Williams 1992) and Ziegler (Ziegler et al., 2019). For Reinforce, we simply define $R(x, c) = b(x, c)$. Ziegler prevents too large departures from $α$ by adding a KL penalty term and defining $R(x, c) = b(x, c) − βD_{KL}(π_θ, α)$, where $β$ is a hyperparameter updated using an adaptive schedule.

3.2 Summarization

3.2.1 Experimental setup

Dataset To conduct our summarization experiments, we use the CNN/DailyMail dataset (Nallapati et al., 2016): we sampled 5k source documents from the train and test subsets of CNN/DailyMail to use for fine-tuning and evaluation, respectively. $τ(c)$ from Algorithm 1 will be a uniform distribution over a given subset of source documents. Note that neither CDPG nor the baselines utilise ground truth summaries; we compute $b(x, c)$ based on source documents and generated summaries. However, we use ground truth summaries for computing reference-based evaluation metrics such as Rouge score or recall-target.

Model We conduct our experiments on the T5 architecture (Raffel et al., 2020), using the pre-trained model t5-small (60m parameters) as $π_θ$. During fine-tuning, we generate summaries $x$ conditioned on a source document $c$ by pure ancestral sampling from $π_θ$; for evaluation, we follow the setup described by Raffel et al. (2020) and use beam search.

Constraints Following Nan et al. (2021), we define an entity-level factual consistency constraint as a product of two constraints: there must be at least four named entities in the summary $x$ and all the named entities $x$ must have occurred in the source $c$. More formally, let $NER(·)$ denote the set of named entities found in a text. Then, $b(x, c) = 1$ iff $|NER(x)| ≥ 4 ∧ |NER(x)| ⊆ NER(c)$ and $b(x, c) = 0$ otherwise.

Metrics In addition to measuring expected $D_{KL}(p_c, π_θ)$ and $D_{KL}(π_θ, α)$, we evaluate the quality and factual consistency of generated summaries using the following metrics:

1. Precision-source (Nan et al. 2021), defined as $|NER(x ∩ c)|/|NER(x)|$ is the percentage of named entities in the summary that can be found in the source. Low precision-source indicates severe hallucination.
2. Recall-target (Nan et al. 2021), defined as $|NER(x ∩ t)|/|NER(t)|$, is the percentage of named entities in the target summary $t$ that can be found in the generated summary $x$.
3. Distinct-2 (Li et al., 2016), a measure of text diversity in terms of the frequency of bigram repetitions within a single continuation $x$.
4. Rouge-1 (Lin, 2004), a measure summarization quality in terms of unigram overlap between the source document and ground truth summary.

See Appendix B.3 for how scorers $b$ and metrics are computed for summarization experiments.

Results We present the evolution of our 7 metrics through time on Figure 2. CDPG is the only method stably decreasing expected $D_{KL}(p_c, π_θ)$ and thus approaching (as opposed to drifting away from) optimal distributions $p_c$. This is reflected in moderate divergence from $α$ and translates into downstream metrics. Summaries generated by the fine-tuned model contain, on average, more named entities. Moreover, name entities in summaries are both more factually consistent with source
Figure 2: Summarization with factual consistency constraint. Evaluation metrics: expected $D_{KL}(p_c, \pi)$ ($\downarrow$ better) and $D_{KL}(\pi_\theta, a)$ ($\downarrow$ better), precision-source ($\uparrow$ better), recall-target ($\uparrow$ better), number of named entities ($\uparrow$ better), Distinct-2 ($\uparrow$ better), Rouge-1 ($\uparrow$ better) for models obtained from fine-tuning with conditional DPG, DPG, Ziegler and Reinforce.

(an increase in precision-source) and more relevant (an increase in recall-target). The tendency towards mentioning more factually consistent named entities increases the bigram diversity within summaries (Distinct-2) and the overall quality of generated summaries compared to ground truth (Rouge-1). This last results might seem surprising given that CDPG did not have access to ground truth summaries. A plausible explanation is that the original pretrained model was biased towards mentioning too few factually correct entities, at least compared to ground truth summaries. Satisfying the factual consistency constraint reduced this bias.

Baseline approaches fall short of achieving similar results. Standard DPG, the closest contender, still leaves a significant gap in terms of all metrics and is far less stable than CDPG (e.g. its $D_{KL}(p_c, \pi_\theta)$ starts to diverge again after around 500 epochs). Ziegler stays extremely close to the original model $a$, failing to improve its shortcomings. In contrast, Reinforce heavily departs from $a$ pushing it to mention a large number of named entities. This results in artificially inflated recall-target but no increase in precision-source and a decrease in Rouge-1. The additional named entities frequently are frequently irrelevant (i.e. not mentioned in ground truth summaries) or simply hallucinated. See Tables 3-7 in the Appendix for randomly chosen summaries of documents in the test set.

3.3 Code generation

Dataset For code generation experiments, we condition a language model on Python function signatures (both of methods and standalone functions) extracted from the Python150 dataset which consists of Python source code obtained from GitHub (Raychev et al., 2016). We use the code provided by Roziere et al. (2020) for function extraction and randomly choose 5k functions for $C_{train}$ and 5k for $C_{test}$. $\tau(c)$ is a uniform distribution over these signatures. Note that neither in fine-tuning nor in evaluation do we use ground truth function bodies.

Model We conduct experiments using GPT-Neo (Black et al., 2021): an off-the-shelf, freely available autoregressive language model mirroring the GPT-3 architecture (Brown et al., 2020). GPT-Neo’s training set included 85 GiB of source code from GitHub which endowed it with some code completion abilities (Gao et al., 2020). We use the gpt-neo-125 variant available on Huggingface Transformers (Wolf et al., 2019). During both fine-tuning and evaluation we generate function bodies by conditioning on signatures using pure ancestral sampling.

Constraints For experiments with compilability control condition, we check compilability of a Python function declaration obtained by concatenating $[c, x]$ and trying to execute it. $b(x, c) = 1$ if the Python interpreter raises an exception and 0 otherwise. See Appendix B.3 for more details.

For experiments with PEP8-compliance control condition, we check whether a function declaration given by $[c, x]$ violates PEP8 (van Rossum et al., 2001), the style guide for Python, by running
Figure 3: Code generation with compilability (a) and PEP8 (b) constraint. Evaluation metrics: compilability (↑ better), number of PEP8 errors (↓ better), expected $D_{KL}(p_c, \pi_\theta)$ (↓ better) and $D_{KL}(\pi_\theta, a)$ (↓ better), number of characters, AST node count (↑ better) for models obtained from fine-tuning with CDPG, DPG, Ziegler and Reinforce.

pycodestyle, an off-the-shelf linter (static code analysis tool)[6] $b(x, c) = 1$ if the number of PEP8 violations found by pycodestyle is 0, otherwise $b(x, c) = 0$.

**Metrics** We evaluate the quality of generated Python functions using the following metrics:

1. PEP8 error count, the average number of violations of PEP8,
2. Compilability, the fraction of samples $[c, x]$ that compile,
3. The average number of characters in $[c, x]$ (after detokenization),
4. The average number of nodes in an abstract syntax tree (AST) of sequences that compile.

Intuitively, this metric indicates the logical (as opposed to surface) complexity of generated programs.

For more details on how scorers $b$ and metrics are implemented, see Appendix B.3.

**Results** We present the evolution of metrics through time on Figure 3. CDPG was able to increase the fraction of compilable functions from around 40% to around 65% and decrease the average number of PEP8 violations. Incidentally, the PEP8 control objective also leads to an increase in compilability because many PEP8 violations are also compilation errors. Similarly to the summarization experiment, CDPG and DPG are the only methods actually approaching optimal distributions $p_c$ and diverging moderately from $a$. This allows them to maintain the original statistics of $a$: length and the number of nodes in AST trees of generated functions. In contrast, Reinforce learns to generate shorter functions (having less opportunity for mistakes) and Ziegler produces heavily degenerated samples [Holtzman et al., 2020]: syntactically simple functions with severe repetitions. This is reflected in an increase in length and a decrease in AST nodes count. See Tables 8-10 and Tables 11-13 for randomly chosen samples from the compilability and PEP8 experiments, respectively.

Note that the gap between CDPG and DPG is much closer for code generation (especially with compilability control objective) than for summarization. This can be accounted for by the normalized standard deviation of partition functions $Z_c$ for EBMs $P_c$ in the range of conditional EBMs $P$ for each control objective. For code generation, this standard deviation is lower meaning that $Z_c$ in (8) is better approximated by a constant which can be absorb into the learning rate $\alpha(\theta)$. For summarization, this variance is higher, therefore ignoring the $Z_c$ term incurs higher bias. See Appendix C.1 for a comparison.

[6]https://github.com/PyCQA/pycodestyle
In the previous sections, we showed how CDPG is able to fine-tune a pretrained model \( a \) to satisfy certain constraints without destroying \( a \)'s capabilities. Here we attempt to gain a better understanding of how different fine-tuning approaches affect the distributions of final models. On Figure 4 we present frequencies of errors and named entities obtained from fine-tuned models. While errors and named entities differ significantly in their frequency, CDPG consistently decreases frequencies of these errors and consistently increases the frequencies of all kinds of named entities, including the long tail of rare ones.

To compare lexical diversity of samples obtained from fine-tuned models, we plot the frequency of each token (the number of times it occurs) and its rank (its index in a sorted list of tokens) in Figure 5. CDPG and DPG are able to closely match original token frequencies while Ziegler and Reinforce tend to have shorter tails of rare tokens.

### 3.4 Qualitative analysis

In the previous sections, we showed how CDPG is able to fine-tune a pretrained model \( a \) to satisfy certain constraints without destroying \( a \)'s capabilities. Here we attempt to gain a better understanding of how different fine-tuning approaches affect the distributions of final models. On Figure 4 we present frequencies of errors and named entities obtained from fine-tuned models. While errors and named entities differ significantly in their frequency, CDPG consistently decreases frequencies of these errors and consistently increases the frequencies of all kinds of named entities, including the long tail of rare ones.

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**Figure 4:** Relative frequencies of most common compilation errors (a), absolute frequencies of most common PEP8 violations (b) and absolute frequencies of named entities (c) in a batch of 10280 samples from the original model \( a \) as well as models obtained from fine-tuning with CDPG, DPG, Ziegler and Reinforce.

**Figure 5:** Token frequency against token rank computed for tokens in 10280 samples from \( a \), Conditional DPG and baselines. Longer tails imply more diverse samples.
4 Conclusion

We presented CDPG, a principled approach to fine-tuning conditional language models to satisfy arbitrary constraints. In contrast with other methods, CDPG does not require ground truth training data and is able to shift model distribution in a minimally invasive way. In consequence, models fine-tuned with CDPG share desired characteristics, such as improved factual consistency or compilability, with the fluency and diversity of the original model.

Future work could evaluate CDPG on other tasks — such as machine translation or dialogue response generation — as well as explore other control objectives such as constraining the semantics (as opposed to syntax) of generated Python functions. Another future direction consists in extending CDPG to approximate conditional analogues of the more general, exponential-form (Khalifa et al., 2021) EBMs which can represent distributional constraints: desired expected values of certain features of generated samples.

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A Extended related work

Reducing hallucinations in summarization Neural abstractive summarization is highly prone to hallucinate content in the summary that is unfaithful to the source document. Maynez et al. (2020) found that hallucinations occur in more than 70% of single-sentence summaries and most of these are extrinsic hallucinations: adding information not directly inferable from the input document. Therefore, a substantial effort was devoted to improving factual consistency of abstractive summarization. Some notable attempts include reranking summaries based on their correctness predicted by entailment classifiers (Falke et al., 2019) or fine-tuning using RL with a reward derived from an entailment classifier (Pasunuru & Bansal, 2018). The notion of entity-level factual consistency – a property such that that all named entities in the summary are actually mentioned in the source document – was introduced (Nan et al., 2021) as is one way of operationalizing the notion of extrinsic hallucinations.

Controllable code generation Generating source code is an established application of language models (Nguyen et al., 2013; Raychev et al., 2014; Karpathy et al., 2015; Bielik et al., 2016) that recently enjoys renewed interest (Lu et al., 2021; Chen et al., 2021; Austin et al., 2021). The task is formulated both as unconditional generation (with applications in code completion, e.g. Codex (Lu et al., 2021) or GitHub Copilot[1]) and as conditional generation (e.g. program synthesis or generating a program satisfying a given input-output specification, e.g. (Austin et al., 2021)). Our task of function generation can be seen as a simplified program synthesis when the specification is given by a function signature (a name of a function and a list of arguments). Previous work found compilability errors to be a significant failure mode of neural code generation (Roziere et al., 2020). Previous attempts at improving compilability of generated code include Maddison & Tarlow (2014), who augment neural probabilistic context free grammars with semantic constraints and use them for unconditional generation or Zhong et al. (2017), who used policy gradients to train a model translating natural language questions to corresponding SQL queries and – in addition for rewarding for query execution results – added a penalty for syntactically invalid queries. Most in line with our work, Korbáč et al. (2021) were using DPG to improve compilability of unconditional language models for code.

B Details of metric and score calculation

B.1 KL divergences

Calculation of metrics relative to \( p_c \)’s, such as \( \mathbb{E}_{c \sim \tau(c)} D_{KL}(p_c, \pi_\theta) \), requires estimating \( Z_c \)’s. This is done using importance sampling from \( \pi_\theta \) in a manner analogous to the training loop (Algorithm 1). Then, expected KL can be simplified to the following form:

\[
\mathbb{E}_{c \sim \tau(c)} D_{KL} \left[ p_c(x) \mid\mid \pi_\theta(x|c) \right] = \mathbb{E}_{c \sim \tau(c)} \sum_x p_c(x) \log \frac{p_c(x)}{\pi_\theta(x|c)}
= \mathbb{E}_{c \sim \tau(c)} \sum_x p(x|c) \log \frac{P_c(x)}{Z_c \pi_\theta(x|c)}
= \mathbb{E}_{c \sim \tau(c)} \left[ - \log Z_c + \sum_x p(x|c) \log \frac{P_c(x)}{\pi_\theta(x|c)} \right]
= \mathbb{E}_{c \sim \tau(c)} \left[ - \log Z_c + \sum_x \pi_\theta(x|c) \log \frac{P_c(x)}{\pi_\theta(x|c)} \log \frac{P_c(x)}{\pi_\theta(x|c)} \right]
= \mathbb{E}_{c \sim \tau(c)} \left[ - \log Z_c + \frac{1}{Z_c} \mathbb{E}_{x \sim \pi_\theta(x|c)} \log \frac{P_c(x)}{\pi_\theta(x|c)} \right].
\]

A small \( \epsilon \) is added to \( Z_c \) for stability. We approximate both expectations (over \( \tau \) and \( \pi_\theta \)) using importance sampling. For a complete procedure, see Algorithm 2.

[1] https://copilot.github.com
\( E_{c \sim \tau(c)} D_{KL}(\pi_\theta, a) \) is computed in a simpler manner as it doesn’t require estimating \( Z_c \)’s and we can directly sample from \( \pi_\theta \). It boils down to sampling a batch of \( N \) contexts \( c_i \), a batch of \( M \) samples \( x_j \) from \( \pi_\theta(x|c_i) \) for each \( c_i \) and evaluating:

\[
E_{c \sim \tau(c)} D_{KL}(\pi_\theta, a) \approx \frac{1}{NM} \sum_{i=1}^{N} \sum_{j=1}^{M} \frac{\pi_\theta(x_j|c_i)}{a(x_j|c_i)}.
\]

(14)

To avoid bias, when computing KL divergences we always sample from \( \pi_\theta \) using pure ancestral sampling (as opposed to top \( p \) sampling or beam search decoding).

**Algorithm 2** Estimating \( E_{c \sim \tau(c)} D_{KL}(p_c, \pi_\theta) \)

**Input:** a distribution over queries \( \tau(c) \)

**Input:** conditional model \( \pi_\theta \)

**Input:** \( N \), number of contexts

**Input:** \( M \), number of samples for each context

1: sample batch \( \{c_1, ..., c_i, ..., c_N\} \) from \( \tau(c) \)
2: for \( i \in \{1, ..., N\} \) do
3: sample batch \( \{x_1, ..., x_j, ..., x_M\} \) from \( \pi_\theta(x|c_i) \)
4: \( \hat{Z}_{c_i} = \frac{1}{M} \sum_{j=1}^{M} \frac{p(c_i|x_j)}{\pi_\theta(x_j|c_i)} \)
5: \( D_{KL}(p, \pi_\theta) = \frac{1}{N M} \sum_{i=1}^{N} \sum_{j=1}^{M} \frac{p(c_i|x_j)}{\pi_\theta(x_j|c_i)} \left[ - \log \hat{Z}_{c_i} + \log p(c_i|x_j) \right] \)

**Output:** An estimate of \( E_{c \sim \tau(c)} D_{KL}(p_c, \pi_\theta) \)

**B.2 Summarization**

Following Nan et al. (2021), we implement NER(·) as using a pretrained SpaCy (Honnibal et al., 2020) named entity recognizer. We use the en_core_web_sm module and restrict the named entities we extract to the following categories: PERSON, FAC (buildings, airports, highways, bridges, etc.), GPE (geopolitical entities: countries, cities, etc.), ORG (companies, agencies, institutions, etc.), NORP (nationalities or religious or political groups), LOC (Non-GPE locations: mountain ranges, bodies of water, etc.), EVENT (named hurricanes, battles, wars, sports events, etc.). Also following Nan et al. (2021), we ignore entities such as date, time and numerals due to large variation in their representation in documents.

**B.3 Code generation**

**Compilability** To check for compilability, we call the compile_command function from the codeop module of Python Standard Library with a sequence obtained by string concatenation \([c, x]\) as argument. We then check if compile_command returns a code object. The post-processing we apply is removing any characters from \( x \) after the end of function declaration (with function end defined in terms of indentation) as we are concerned specifically with function generation. codeop.compile_command is the implementation that Python interactive interpreters use in read-eval-print loop (REPL) to determine whether a string is a valid Python code. The method tries to compile a string of Python code and raise and exception if compilation fails, for instance a SyntaxError for invalid Python syntax and ValueError or OverflowError if there is an invalid literal. Note that our notion of compilability is concerned only with syntactic correctness as Python interpreter does not execute the body of a function at function declaration time.

**PEP8** To compute the number of PEP8 violations triggered by a sequence \([c, x]\), we run py-codestyle a Python linter (static code analysis tool) and report the number of violations it reports.

**AST node count** Finally, to compute AST node count, the average number of nodes in an abstract syntax trees (ASTs) of generated functions, we consider only samples \([c, x]\) that compile. They are parsed to their corresponding ASTs using the ast module from Python Standard Library.

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[1] https://docs.python.org/3/library/codeop.html
[2] https://github.com/FyCQA/pycodestyle
[3] https://docs.python.org/3/library/ast.html
C Additional figures

See Figure 7 for histograms of 25 most common compilation errors and PEP8 violations of the original model and their corresponding frequencies for fine-tuned models.

C.1 Normalized standard deviations for $Z_c$ across tasks

See Figure 6 of normalized standard deviations of $Z_c$ across tasks. Here normalized standard deviations is defined as $\text{std}(Z_c)/\text{avg}(Z_c)$, where

$$\text{avg}(Z_c) = \frac{1}{N} \sum_{i=1}^{N} Z_{c_i},$$  \hspace{1cm} (15)

$$\text{std}(Z_c) = \sqrt{\frac{1}{N} \sum_{i=1}^{N} (Z_{c_i} - \text{avg}(Z_c))^2}.$$  \hspace{1cm} (16)

Lower normalized standard deviation for a task explains closer performance gap between CDPG and DPG for that task on Figures 2-3.

![Figure 6: Normalized standard deviations for $Z_c$'s associated with unconditional EBMs $P_c$ in the codomain of conditional EBMs $P$ defined for three control objectives: summarization with factual consistency constraint, code generation with compilability constraint and code generation with PEP8 constraint.](image)
Figure 7: Absolute frequencies of compilation errors (a) and PEP8 violations (b) in a batch of 10280 samples from the original model $a$ as well as models obtained from fine-tuning with conditional DPG, DPG, Ziegler and Reinforce.
D Hyperparameters and implementation details

We implemented all models using PyTorch (Paszke et al., 2019) and HuggingFace Transformers (Wolf et al., 2019). Each training run took approximately 5 days on 2 Nvidia V100 GPUs. For a detailed list of hyperparameter values, see Table 1 and 2. For a description of hyperparameters specific to Ziegl see (Ziegler et al., 2019).

| Hyperparameter          | Value                     | Symbol |
|-------------------------|---------------------------|--------|
| original model          | EleutherAI/gpt-neo-125M   | α      |
| batch size              | 2048                      |        |
| maximum sequence length | 128 tokens                |        |
| learning rate for πθ    | $1.41 \times 10^{-6}$     | $\alpha^{(\theta)}$ |
| optimizer               | Adam (Kingma & Ba, 2014)  |        |
| learning rate schedule  | constant with warmup (100 epochs) |        |
| total epochs            | 1000                      |        |
| number of c’s for training | 5000                  | $|C_{train}|$ |
| number of c’s per batch | 32                       | N      |
| number of x’s per c     | 64                       | M      |
| Ziegler                 |                           |        |
| policy gradients clip range | 0.2                   |        |
| target KL value for adaptive schedule | 6.0             |        |
| initial coefficient of KL penalty | 0.2               | $\beta$ |

Table 1: Hyperparameters used for code generation experiments

| Hyperparameter          | Value                     | Symbol |
|-------------------------|---------------------------|--------|
| original model          | t5-small                  | α      |
| batch size              | 1024                      |        |
| maximum sequence length | 200 tokens                |        |
| learning rate for πθ    | $1 \times 10^{-4}$        | $\alpha^{(\theta)}$ |
| optimizer               | Adam (Kingma & Ba, 2014)  |        |
| learning rate schedule  | constant with warmup (100 epochs) |        |
| total epochs            | 1000                      |        |
| number of c’s for training | 5000                  | $|C_{train}|$ |
| number of c’s per batch | 32                       | N      |
| number of x’s per c     | 32                       | M      |
| Ziegler                 |                           |        |
| policy gradients clip range | 0.2                   |        |
| target KL value for adaptive schedule | 6.0             |        |
| initial coefficient of KL penalty | 0.2               | $\beta$ |

Table 2: Hyperparameters used for summarization experiments
E  Samples

E.1  Summarization with entity-level factual consistency constraint

See Tables 3-7 for summaries of 5 randomly chosen documents from our evaluation set $C_{test}$ generated by models fine-tuned using Conditional DPG, 3 baselines and $a$. Summaries were generated with beam search.

E.2  Code generation with compilability constraint

See Tables 8-10 for functions obtained by sampling conditioned on 3 randomly chosen signatures from our evaluation set $C_{test}$ generated by models fine-tuned using Conditional DPG, 3 baselines and $a$. We used pure ancestral sampling.

E.3  Code generation with PEP8 constraint

See Tables 11-13 for functions obtained by sampling conditioned on 3 randomly chosen signatures from our evaluation set $C_{test}$ generated by models fine-tuned using Conditional DPG, 3 baselines and $a$. We used pure ancestral sampling.
"Success Kid" is likely the Internet’s most famous baby. You’ve seen him in dozens of memes, fist clenched in a determined look of persevering despite the odds. Success Kid – now an 8-year-old named Sammy Griner – needs a little bit of that mojo to rub off on his family. His dad, Justin, needs a kidney transplant. About a week ago, Laney Griner, Justin’s wife and Sammy’s mother, created a GoFundMe campaign with a goal of $75,000 to help cover the medical expenses that go along with a kidney transplant. The campaign is already a success. By Wednesday it had topped its goal. Griner told The Daily Dot that her husband was diagnosed with kidney disease in 2006 and suffered complete kidney failure three years later. "One can only survive with no natural kidney function for so long," Laney Griner said. "His energy and mood are affected, he can no longer work, and he spends 12 hours a week in dialysis clinic. "Having been on dialysis for this long greatly increases his risks of developing further complications. The only way to save his life is to get a transplant. There’s no other way around that," she said. The family doesn’t know when a kidney might become available. Their GoFundMe page has a link for potential donors. Sammy’s Internet fame began in 2007 when his mom posted a picture of him on a beach with a fist full of sand and a satisfied look on his face. Myspace picked it up, so did Reddit. The rest is Internet history. Success just seems to run in some families.
A picture, believed to be the only image of the Civil War ironclad, the CSS Georgia has been revealed to be a fake created in a teenage hoax using a 2ft model. John Potter, from Savannah, has admitted forging the picture with his brother in the 1980s and placing it in a frame which now holds a picture of his dead dog. He then passed on the image on to the Georgia Historical Society and the photo became an unofficial part of the ship's history even though it was never authenticated. Scroll down for video. John Potter (pictured), from Savannah, has admitted forging the picture with his brother in the 1980s and placing the picture in a frame which now holds a picture of his dead dog. In 1986 he fiddled that he was at a yard sale when he found the photograph in an antique frame. Inscribed on the back of the frame, he claimed, was 'CSS Georgia.' He told historians that he didn't have the $175 the owner wanted. The picture Mr Potter handed over to the society was actually a picture of a picture. In 1986 he fiddled that he was at a yard sale when he found the photograph in an antique frame. Inscribed on the back of the frame, he claimed, was 'CSS Georgia.' He told historians that he didn't have the $175 the owner wanted, so he took a photo of it and then mailed it to historical groups in Savannah. Potter has now admitted the sham and explained how he falsified the image. When he was a teenager in Savannah, Potter, his brother Jeffrey and a friend shot a short 8mm movie about the building — and destruction — of the CSS Georgia in a fictional battle with Union troops. For the movie, they built an 18-foot long boat of plywood and Styrofoam, as well as a smaller 2-foot model. They based the design, in part, on his grandfather’s recollections of details passed down by word of mouth through generations of their family. Potter also used an illustration of the ironclad he found on a postcard. To create the fake image Potter’s younger brother put on a coat and straw hat went out to a marsh with a cane fishing pole and Potter took a photo. He took another photo of the 2-foot model and cut out the boat’s image, glued it onto the photo of his brother, then used diet and glue to create the illusion of a photo faded by age and stained by water or chemicals. Evidence of the hoax. All elements of the fakery were snapped by Potter at one time. The small model boat here appears alongside the false picture, polaroids of it and a 1984 copy of Mad Magazine. He bought an old picture frame and beat it up even further. He put the photo in it. Then he drove 120 miles to a yard sale in Waycross, Georgia, put the picture down and took a Polaroid of it. He laughs now, when he remembers that it had seemed so important that he actually do this at a yard sale, so at least that part would be true. 'Who knows what goes through the mind of a kid,' he said. The US Army Corps of Engineers appealed for information about the picture as it embarked on a project to raise the ironclad. Potter sent out the photo to historical groups, setting off the sporadic, and fruitless, search for a CSS Georgia photo that he now says never existed. As the Army Corps of Engineers embarked this year on a $14 million project to raise the wreckage of the real CSS Georgia from the river, archaeologists publicised the image online and in news stories hoping to track down the original photo. 'Wanted. A Photo Of This Confederate Battleship,' read the headline above the image on the Army Corps website. There are a lot of characteristics in the photograph that lead us to believe it is the CSS Georgia,' Julie Morgan, the Army Corps archaeologist in charge of raising the ironclad’s remains, said in a February interview. 'On the other side, there are some skeptics who believe it’s a complete fake.' Robert Holcombe, former curator of the National Civil War Naval Museum in Columbus, Georgia, said in February that while the original photograph would be needed to confirm if the image was authentic, he believed it was real. 'Most people seem to think so,' he said. 'Or else it’s an awfully good fake.' The peeling gilt frame that once held the disputed photo, is now filled with a portrait of Potter’s deceased pug, Puggy Van Dug. He never became a successful special effects artist with the exception of the one faked photo. The peeling gilt frame that once held the disputed photo, is now filled with a portrait of Potter’s deceased pug, Puggy Van Dug. 

Table 4: Summaries generated by beam search on πθ(α|c): models fine-tuned to satisfy entity-level factual consistency constraint. Named entities in summaries are highlighted in red.
Everton’s Steven Pienaar has admitted he considered retirement as frustration took its toll during his injury-ravaged season. The influential 33-year-old midfielder Pienaar has been dogged by groin and knee injuries this season limiting him to just 11 appearances. He returned to action from his latest setback in the 1-1 draw with Swansea City earlier this month but muscle fatigue ruled him out of the win over Burnley last weekend. Everton midfielder Steven Pienaar is held back by Swansea’s Ki Sung-Yueng at the Liberty Stadium. Pienaar said: ‘At one stage, I thought I had better just hang my boots up and call it a day but on the other side I was just thinking that I enjoy going in and seeing the guys so I just had to stay strong and that kept me going. ‘When you are at home not coming in for training you feel very down but as soon as I walk through the door, there’s always the camaraderie in the group, there is always fun. ‘Even if you are injured, you can always laugh and it keeps you going. Just to be among the players, it’s kept me going.’ Pienaar has made just 11 appearances for the Toffees this season due to groin and knee injuries.

Table 5: Summaries generated by beam search on $\pi_\theta(c)$: models fine-tuned to satisfy entity-level factual consistency. Named entities in summaries are highlighted in red.
Expat: Detectives are investigating the killing of David King (pictured), a 70-year-old pensioner from Newham, east London, who retired to Normandy 15 years ago. His body was found by sniffer dogs last week in the picturesque hamlet of Pierres, south-west of Caen, and an unnamed 28-year-old Frenchman has been charged with his murder. The alleged killer was living rough in the area, and is thought to have been behind a number of thefts in the area. Now prosecutor Carole Etienne has said that Mr King, a keen gardener, may well have confronted the man over stolen vegetables. Ms Etienne, who is leading the police enquiry, said: ‘Among the vague attempts at an explanation given by the accused, we are looking at the possibility of a fight over the theft of foodstuffs. ’In one night, a whole plot of leeks might disappear. One person saw four rabbits vanishing overnight’. Ms Etienne added: ‘People were getting more and more angry, and some were even threatening to defend their plots with shotguns’. Neighbours of Mr King, who was hugely proud of his vegetable garden, told Le Parisien newspaper that a description of the thief corresponds to the alleged murderer. Discovery: In February, Mr King’s car, a Renault Scenic (above) was found parked in Vire, a nearby town, but there was no sign of any body. Family and neighbours of Mr King have attacked detectives for allowing his suspected murderer to remain at large for six months. Interpol, the international police organisation, had initially refused to open a missing person’s enquiry. Instead they believed Mr King had travelled to Australia to see his daughter. Sandie Ray, Mr King had been living in France for 15 years. Ms Ray, who lives in Perth, Australia, said her father’s passport details had been mixed up with another David King, who had indeed travelled to Australia from France. She said this was known by November last year, but ‘the French authorities still hadn’t been formally notified of this via Interpol until approximately three months later’. Ms Ray said a quicker enquiry would have avoided ‘lots of anxiety and frustration for our family and dear friends.’ John King, Mr King’s son, who lives in Brighton, East Sussex, said the botched investigation had been a ‘bureaucratic nightmare’ for all concerned. Other expats living in the area said it was ‘hugely frightening’ to have a suspected murderer living in their midst while the operation went on. ‘This is an isolated part of the world, and everyone is potentially vulnerable to attack,’ said one. ‘Detectives should have worked out what was going on far quicker. The slow speed of the enquiry was unacceptable.’ In February, Mr King’s car, a Renault Scenic was found parked in Vire, a nearby town, but there was no sign of any body.

**Table 6:** Summaries generated by beam search on $\pi_0(\cdot|c)$: models fine-tuned to satisfy entity-level factual consistency constraint. Named entities in summaries are highlighted in red.
German legend Franz Beckenbauer has accused Bayern Munich stars of playing as if they had taken ‘sleeping pills’ in their midweek defeat by Porto. The Bundesliga champions conceded twice in the opening 10 minutes before losing 3-1 to the Portuguese in the first leg of their Champions League quarter-final on Wednesday. Der Kaiser may be a brand ambassador for the club but he couldn’t hide his feelings after the game, when he criticised defender Dante for playing as if he were wearing ‘ski boots’ before turning on the entire team. Franz Beckenbauer was speaking in New York as part of Bayern Munich’s media agreement with MSN. New York Cosmos legends Beckenbauer and Pelé pose together after launching the team’s spring season.

Ricardo Quaresma scored the opening goal from the spot in Porto’s 3-1 defeat of the Germans. Beckenbauer accused Brazilian defender Dante (left) of playing as if he were wearing ‘ski boots’. Speaking to reporters in New York to mark the club’s new media agreement with MSN, Beckenbauer said: ‘It was one of those days, all the players didn’t show their real performance. ’After 10 minutes you are 2-0 down in the quarter-final in the Champions League, so many mistakes. I never saw this before. I thought they took sleeping pills! Porto were much faster, real power. It made me angry. Quaresma celebrates with Porto team-mates after netting his second goal inside the first 10 minutes. Bayern Munich head coach Pep Guardiola goes crazy at his team’s performance. Bayern players trudge off after defeat knowing they will have to vastly improve to reach the semi-finals.’ If they played like that again, no chance [they can go through].’ But they can win 2-0 or go to extra-time. They have a chance. Last year we had the same problem, playing excellent in the Bundesliga and then we had two bad days and were out of the competition.’ The 69-year-old did attempt to play down his comments over Dante’s performance, he said: ‘At half-time, I have to give a comment and that was my reaction. And I’m sorry to give him the ski boots... but he’s Brazilian, and Brazilian to me means for me, technique and Pelé and... Brazil. But not this.’ ‘If you want to win the Champions League you need a strong league with a lot of players. Internationally, Bayern Munich belongs to the top teams but to win the Champions League... you saw the game probably two days ago, we are far, far away. With this performance, you don’t win anything,’ he added.

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Table 7: Summaries generated by beam search on $\pi_\theta(\cdot|c)$: models fine-tuned to satisfy entity-level factual consistency constraint. Named entities in summaries are highlighted in red.

| $b(x, c)$ | $x$ |
|-----------|-----|
| 0 | German legend claims players played as if they had taken ‘sleeping pills’; Porto lost 3-1 to Porto in the first leg of their champions league quarter-final. the 69-year-old was speaking to reporters in New York as part of the club’s media agreement with MSN. |
| 1 | German legend Franz Beckenbauer was speaking in New York as part of the club’s media agreement with MSN. he accused defender Dante of playing as if he were wearing ‘ski boots’ the 69-year-old said: ‘if they played like that again, no chance [they can go through] but they can win 2-0 or go to extra-time’ |
| 0 | The Germans conceded twice in the opening 10 minutes before losing 3-1 to Porto. the 69-year-old criticised defender Dante for playing as if he were wearing ‘ski boots’ he said: ‘if they played like that again, no chance [they can go through]’ |
| 0 | German legend claims players played as if they had taken ‘sleeping pills’; Porto lost 3-1 to Porto in the first leg of their champions league quarter-final. The 69-year-old was speaking to reporters in New York as part of the club’s media agreement with MSN. |
| 1 | Franz Beckenbauer has accused Bayern Munich stars of playing as if they had taken ‘sleeping pills’. the Bundesliga champions concede twice in opening 10 minutes before losing 3-1 to the Portuguese in their Champions League quarter-final on Wednesday. Der Kaiser may be a brand ambassador for the club but he couldn’t hide his feelings after the game. Ricardo Quaresma scored his opening goal from spot in Porto’s 3-1 defeat of the Germans. Bayern Munich head coach Pep Guardiola goes crazy at his team’s performance. Bayern players trudge off after defeat knowing they will have to vastly improve to reach the semi-finals’ |

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Source document: e
| b(x, c) | [x, c] |
|---|---|

Sequences sampled from the original model $\alpha$

```python
def __init__(self):
    self.peneturn = TitlePane(text='Screen' if len(self.peneturn) > 0 else 'Find' )
    self.gentlemen = TitlePane()
    self.managers = TitlePane()
    self.title = TitleBox(title='Title')
    self.pane = self.hide(self.menus, menus=self.menus)
    self.instructions = Label(text='I')
    self.scripture =
```

Sequences sampled from a model fine-tuned using Conditional DPG

```python
def __init__(self):
    self.context = 100
```

Sequences sampled from a model fine-tuned using DPG

```python
def __init__(self):
    pass
```

Sequences sampled from a model fine-tuned using Ziegler

```python
def __init__(self):
    self.headers_headers_headers_headers_headers_headers_headers_headers_headers_headers_headers_headers_headers_headers
```

Sequences sampled from a model fine-tuned using Reinforce

```python
def __init__(self):
    self.screen = screen
```

### Table 8: Samples obtained from $\pi_B(\cdot|c)$ with $c = \text{def \_init\_\(self\)}$ fine-tuned to satisfy a compilability constraint

24
Sequences sampled from the original model $\alpha$

```python
def __init__(self, *args, **kwargs):
    self.algorithm = algorithm
    self.scope = scope
    instance = remotely(self.altstr, 1.4)
    if (num == 3 and instance_level >= 3):
        self.args = args
        self.kwargs = kwargs
        self.kwargs = kwargs
        self.kwargs = kwargs
        self.kwargs = kwargs
        self.kwargs = kwargs
        self.kwargs = kwargs
        self.kwargs = kwargs
        self.kwargs = kwargs
        super(SceneApplication, self).__init__(self.plane)
```

Sequences sampled from a model fine-tuned using Conditional DPG

```python
def __init__(self, *args, **kwargs):
    super(SceneApplication, self).__init__(args, kwargs, self.plane)
```

Sequences sampled from a model fine-tuned using DPG

```python
def __init__(self, *args, **kwargs):
    raise ValueError('"' + self.__class__.__name__ + '" does not exist' + self.__class__.__name__ + '_LINE')
```

Sequences sampled from a model fine-tuned using Ziegler

```python
def __init__(self, *args, **kwargs):
    self.args = args
    self.kwargs = kwargs
    self.kwargs = kwargs
    self.kwargs = kwargs
    self.kwargs = kwargs
    self.kwargs = kwargs
    self.kwargs = kwargs
    self.kwargs = kwargs
```

Sequences sampled from a model fine-tuned using Reinforce

```python
self.typer = typer
```

Table 9: Samples obtained from $\pi_\theta(\cdot|c)$ with $c = \text{def } __init__(\text{self, } * \text{args, } ** \text{kwargs})$ fine-tuned to satisfy a compilability constraint
Sequences sampled from the original model

```python
def __iter__(self):
    from models import model
    params = model.take_model_parameters()
    is_float = model.is_float_pos(not params)
    solvent = model.penesannex(params, is_float)
    solver_params = model.torneyred(params)
    solver_nwm(params)
```

Table 10: Samples obtained from $\pi(\cdot|c)$ with $c = \text{def __iter__}(\text{self})$ fine-tuned to satisfy a compilability constraint
Sequences sampled from the original model $\alpha$

```python
0 def __init__(self):

    # mutation() method.

0 def __init__(self):

    self.vcam = cham_OLEDeaderCenterPythRHAPUV()
    self.vcam_rc = bool_ ("with_ DisneySaudiDisney) Official Created Source Title and Updated Collection
    self.volume = float(1000)
    self.title = float(params()[3])

0 def __init__(self):

    # Returns the inner type that is of the proper type when performing
    # self-self-transpose().

    self.th = "arg1",

Sequences sampled from a model fine-tuned using Conditional DPG

```

```python
0 def __init__(self):

    self.tile_flag_invalid=0.0
    self.tile_flag_handler_out_A = True
    self.tile_flag_handler_out_B = True
    self.layer_list_out_A = self.tile_flag_invalid=2
    self.layer_list_out_B = self.tile_flag_handler_out_A
    self.layer_select_with_dropdown_flat_flag_in=self.tile_flag_invalid=

0 def __init__(self):

    return self.InitExceptaughtClient();

1 def __init__(self):

    flood_handler = ScreenGroup.set_buffer_manager_function(buffers, None)
    heavy = _charging_class(self, fill_handler)

Sequences sampled from a model fine-tuned using DPG

```

```python
1 def __init__(self):

    class App(QtWndrixApplication):

        Slipped: bool = QtWnd technique
        # Member of gtk.SafePlacement floated
delgiate: NamedConstraint: QListPlacementElementDelegateDelegate

0 def __init__(self):

    gqlary(self):

    presentation_data = ([$"parent", " Imperium", "Segaron", "la datos de 214000 "],
                        ["Lamos en su inicio", 0, "Por supuesto", 0],
                        
0 def __init__(self):

    # placeholders

Sequences sampled from a model fine-tuned using Ziegler

```

```python
0 def __init__(self):

    name=SHA_
    [base] __name__.strip()
    message=Message(path=_md5.

1 def __init__(self):

    as_printer = asv(0)
    i = 3
    symbol = _sparse_symbol()

0 def __init__(self):

    self.identity_dont_print_view = 'Identities'

Sequences sampled from a model fine-tuned using Reinforce

```

```python
0 def __init__(self):

    self.dataset = TensorsRotatedDeviceDataset()
    self.start = None
    self.dataset.dataset = TensorsRotatedPose(self, 100)

1 def __init__(self):

    tf._init_(self)

0 def __init__(self):

    self.tile_flag_invalid=0.0
    self.tile_flag_handler_out_A = True
    self.tile_flag_handler_out_B = True
    self.layer_list_out_A = self.tile_flag_invalid=2
    self.layer_list_out_B = self.tile_flag_handler_out_A
    self.layer_select_with_dropdown_flat_flag_in=self.tile_flag_invalid=

Table 11: Samples obtained from $\pi_0(\cdot|c)$ with $c = \text{def } _\text{init}_\text{ }(\text{self})$ fine-tuned to satisfy a PEP8 constraint.
Sequences sampled from the original model

```python
def __init__(self, *args, **kwargs):
    it = lambda: args
    it(None)
```

Sequences sampled from a model fine-tuned using Conditional DPG

```python
def __init__(self, *args, **kwargs):
    dgram = dgram_preprocessor(self.parser, *args, **kwargs)
    self.node = defaultdict([node])
    kwargs = kwargs
    self.classpath = '%(classpath)s//%(pathname)s//'
    self.param = classpath()
    self.property = classpath()
    self.sys.exists = False
    return self
```

Sequences sampled from a model fine-tuned using DPG

```python
def __init__(self, *args, **kwargs):
    tip = {}
    buffer = ''
    clean_of_this = ''
    tip.set_value(op_type())
    tip.set_value(ostream(f" excerpting this", oproc = self.poetrip_extrapol))
```

Sequences sampled from a model fine-tuned using Ziegler

```python
def __init__(self, *args, **kwargs):
    U particles = sorted(p.get_particles(c4))
    kwargs.append(p)
    if self.like_class:
        p.like_class = kwargs[0]
```

Sequences sampled from a model fine-tuned using Reinforce

```python
def __init__(self, *args, **kwargs):
    self.akpo_be(akpo_key, **args)
    self.apps ata, r\% name(dfhn) type(dfhn) ::
    sdt = self.akpo_fishing(a/a[0], r8h[0])[]
```

Table 12: Samples obtained from \( \pi_\theta (\cdot | c) \) with \( c = \text{def } \_\_\text{init}\_\_\_\text{(self, } * \text{ args, } ** \text{ kwargs)} \) fine-tuned to satisfy a PEP8 constraint
Sequences sampled from the original model

```python
def __repr__(self):
    return '__repr__'
```

Sequences sampled from a model fine-tuned using Conditional DPG

```python
def __repr__(self):
    if __name__ == '__main__':
        return self.os_main()
    else:
        return self.req.as_raw_object(
            __name__,
            method = 'GET',
            accept_parser = self.parser, accept_kwargs = self.accept_kwargs,
        )
```

Sequences sampled from a model fine-tuned using DPG

```python
def __repr__(self):
    self.loadstrli()
```

Sequences sampled from a model fine-tuned using Ziegler

```python
def __repr__(self):
    with self:
        self.__repr__[ 0.0] = 1
```

Sequences sampled from a model fine-tuned using Reinforce

```python
def __repr__(self):
    _ = self.name
```

```python
def __repr__(self):
    return self
```

```python
def __repr__(self):
    v = self.__repr__(self)
    if v not in __repr__:
        __repr__(self, v)
        return v
```

```python
def __repr__(self):
    print("\n...\n....").stack(self.dim[0], self.dimensional[0][0], sizeof(self) * self.dimensional[0])
```

Table 13: Samples obtained from $\pi_0(\cdot | c)$ with $c = \text{def \_\_repr\_\_(self)}$ fine-tuned to satisfy a PEP8 constraint