Neighborhood radius estimation for
Variable-neighborhood Random Fields

Eva Löcherbach, Enza Orlandi

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Abstract

We consider random fields defined by finite-region conditional probabilities depending on a neighborhood of the region which changes with the boundary conditions. To predict the symbols within any finite region it is necessary to inspect a random number of neighborhood symbols which might change according to the value of them. In analogy to the one dimensional setting we call these neighborhood symbols the context associated to the region at hand. This framework is a natural extension, to $d$-dimensional fields, of the notion of variable-length Markov chains introduced by Rissanen (1983) in his classical paper. We define an algorithm to estimate the radius of the smallest ball containing the context based on a realization of the field. We prove the consistency of this estimator. Our proofs are constructive and yield explicit upper bounds for the probability of wrong estimation of the radius of the context.

Key words: Gibbs measures, random lattice fields, Variable-neighborhood random fields, Context algorithm, consistent estimation.

AMS Classification: Primary: 60D05, 62F12 Secondary: 60G55, 60G60, 62M40

1 Introduction

We consider random fields on $\mathbb{Z}^d$ with finite state space defined by prescribing a family of conditional probabilities indexed by finite subsets $\Lambda$ of $\mathbb{Z}^d$. We assume that these conditional probabilities depend on a finite neighborhood which changes according to the boundary conditions. Contrary to standard Markov random fields which are defined by a family of conditional probabilities depending on a fixed neighborhood and not sensitive to the boundary conditions (fixed order Markov dependence), the families of conditional probabilities considered here are not restricted to a predefined uniform depth. Rather, by examining the training data, a model is constructed that fits higher order Markov dependencies where needed, while using lower order Markov dependence elsewhere. We call these random fields Variable-neighborhood random fields or Parsimonious Markov random fields.

Adopting this parsimonious description means that we are aiming at reducing information by finding the minimal neighborhood of a given block of sites able to predict the states of the sites within this block. The neighborhood changes when the outside configuration of the field changes, and the dependencies depend on the realization of the field.
Applications of Variable-neighborhood random fields are in image analysis: in texture synthesis, computer vision and graphics. We refer the interested reader to Efros and Leung (1999), \cite{Efros1999}, for the presentation of a non-parametric texture synthesis method. Texture is usually modelled as Markov random field, “composed of well defined texture primitives (texels) which are placed according to some syntactic rules” (Gidofalvi (2001), \cite{Gidofalvi2001}). Thus a modelization as Variable-neighborhood random field where the width of the context window may depend on the realization of the field is natural. Other possible applications of Variable-neighborhood random fields are in neuroscience’s and in general in spatial statistics, whenever information reduction is needed.

The notion of Variable-neighborhood random fields has been inspired by Rissanen’s Minimum Description Length principle for Markov chains, see Rissanen (1983), \cite{Rissanen1983}. Rissanen calls the relevant neighborhood of a site, i.e. the sequence of symbols needed to predict the next symbol, given a finite sample, context of a site and proposes an estimator of the length of the context. Since this seminal paper, there have been several implementations and extensions of the method. We refer to the book of Grunwald (2007), \cite{Grunwald2007}, and to a review paper by Galves and Löcherbach (2008), \cite{Galves2008}, for a comprehensive introduction. Results for the context algorithm can be found for example in Ferrari and Wyner (2003) and in Galves, Maume-Deschamps and Schmitt (2008), \cite{Galves2008a}. In this last paper, the rate of convergence of the context algorithm is established and non asymptotic error bounds implying the consistency of the estimator are obtained. All these results are related to processes in dimension one. Our aim is to extend this method to more than one dimension and to define an estimator of the context in the framework of random fields.

This requires to define a random field which can predict the symbol at a given site by inspecting a “random” number of neighborhood symbols which might change according to the value of them. In analogy to the one dimensional setting we call this neighborhood, i.e. the subset of symbols needed to predict the symbol at the given site, the context of this site. For such random fields we estimate the radius of the context of a given site, i.e. the radius of the smallest ball containing the context of this site. It is enough to consider the contexts for one site, since in our setting the one point specification uniquely determines the specification for any other set. We apply a penalized pseudo-likelihood method, first introduced by Besag (1975), \cite{Besag1975}, and developed by Csiszár and Talata (2006), \cite{Csiszar2006}, in order to construct our estimator. Our estimator is a function of the observed blocks or patterns appearing in the sample. It is based on a sequence of local decisions between two possible values of the radius of the context, lumping them together whenever their corresponding one point conditional probabilities are similar. We propose an estimator for any site within our observation window, depending on its local neighborhood. Hence we deal with a family of estimators indexed by the centers of observation patterns. For this family of estimators, we give in Theorem \ref{thm:consistency} and Theorem \ref{thm:asymptotic} explicit error-bounds for the probability of over- and underestimation. These bounds are non asymptotic with respect to the number of observed sites, i.e. the size of the observation window. As a consequence, we obtain the consistency of the neighborhood radius estimator.

Our results are based on several deviation inequalities which are interesting in its own right. They are collected in Sections \ref{sec:deviation} and \ref{sec:typicality}. The first part of them (Section \ref{sec:deviation}) is based on results obtained by Dedecker (2001), \cite{Dedecker2001}, on deviation inequalities for random fields, the second part (Section \ref{sec:typicality}) is a rewriting of typicality results obtained by Csiszár and Talata (2006), \cite{Csiszar2006}. Csiszár and Talata are only interested in consistency and they do not give explicit upper bounds for the error probabilities. We want to control the error bounds, for any fixed $n$, and so we carry on their ideas into non-asymptotic deviation inequalities.

We implement the estimates under the requirement that the one point conditional probabilities are strictly positive. This is enough for the overestimation. To implement
the estimates for the underestimation, we need to assume that Dobrushin’s contraction condition holds, see Dobrushin (1968), [9] and [10], and that there exists some finite order \( L \), unknown to the statistician, such that the random field is Markov of order at most \( L \). In the language of context-trees this means that we deal with finite trees only.

There is large number of papers devoted to parameter estimation for Markov random fields when the structure of the interaction is known, see for example Gidas (1993), [21], Comets (1992), [3], Dereudre and Lavancier (2011), [8], and many others. Typically, the parameter estimation addresses the problem of estimating parameters entering in determining the potential, but not directly the conditional probabilities. Quite recently, the non-parametric problem of model selection has been addressed, i.e. the statistical estimation of the interaction structure, see for example Ji and Seymour (1996), [24]. Csiszár and Talata (2006), [4], propose to estimate the basic neighborhood of Markov random fields and estimate the support of the neighborhood (i.e. its geometrical structure) which is relevant to determine the conditional probabilities. In their framework this neighborhood does not depend on the configuration, hence they work in a strict Markovian frame. In Galves et al. (2010), [19], a related problem has been studied. The authors estimate for an Ising model having pairwise interactions of infinite range the pairs of interacting sites based on i.i.d. observations of the field. Our paper is not situated in the same framework. We do not address the problem of estimating the geometrical structure of the contexts, since this would require to introduce too many free parameters. We deal with a problem which is simpler and more difficult at the same time: we estimate only the radius of the basic neighborhood, but this neighborhood varies when the configuration changes. This last feature is the main difference from previous models which have appeared in the literature.

The paper is organized as follows. In Section 2 we define the Variable-neighborhood random fields, based on the prescription of a “variable-neighborhood”-specification and we provide examples. In Section 3 we define the estimator of the radius of a single-site context and formulate the main results. In Theorem 3.5 we give the bound on the probability of overestimation and in Theorem 3.9 the bound on the probability of underestimation, under suitable assumptions on the decay of correlations in the field. In Section 4 we prove the deviation inequalities needed for controlling the underestimation and in Section 5 those needed for controlling the overestimation. In Sections 6 and 7 we give the proof of the main results. We conclude with some final remarks in Section 8. In Section 9, the appendix, we collect some mathematical tools needed along the way. In particular we prove a relation between single site contexts and contexts of finite sets of sites.

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2 Variable-neighborhood random fields

We consider the $d$ dimensional lattice $\mathbb{Z}^d$. The points $i \in \mathbb{Z}^d$ are called sites, $\|i\|$ denotes the maximum norm of $i$, i.e. for $i = (i_1, \ldots, i_d)$, $\|i\| = \max(|i_1|, \ldots, |i_d|)$ is the maximum of the absolute values of the coordinates of $i$. The cardinality of a finite set $\Delta$ is denoted by $|\Delta|$. The notations $\subset$ and $\Subset$ denote inclusion and strict inclusion. Subsets of $\mathbb{Z}^d$ will be denoted with uppercase Greek letters. If $\Lambda$ is a finite set, we write $\Lambda \Subset \mathbb{Z}^d$.

A random field $X$ is a family of random variables indexed by the sites $i$ of the lattice, \{X_i : i \in \mathbb{Z}^d\}, where each $X_i$ is a random variable taking values in a finite set $A$.

We denote the set of all possible configurations of the random field by $\Omega = A^{\mathbb{Z}^d}$, where $\Omega$ is endowed with the product topology. We adopt the following notational conventions. We write $\omega_\Lambda \in A^\Lambda$ for the restriction of the configuration $\omega$ to the subset $\Lambda$. If $\Lambda = \{i\}$ is a singleton, we shall write $\omega(i)$ for $\omega_\{i\}$. Configurations defined by regions are factorized with omitted subscripts indicating completion to the rest of the lattice: $\omega_{\Lambda \setminus \Delta} = \omega_\Lambda | \Delta$. We call local configurations the elements of $\bigcup_{\Lambda \Subset \mathbb{Z}^d} A^\Lambda$.

We identify the random field \{X_i : i \in \mathbb{Z}^d\} with the coordinate maps $X_i$ by $X_i(\omega) = \omega(i)$, for any $\omega \in \Omega$, and from now on we will use this canonical version of the random field. We define the following $\sigma$-algebras: For any $\Gamma \subset \mathbb{Z}^d$, let

$$F_\Gamma = \sigma\{X_i : i \in \Gamma\} \quad \text{and} \quad F = \sigma\{X_i : i \in \mathbb{Z}^d\}.$$ 

In this setup a random field is just a probability measure on the product space $(\Omega, F)$. This measure is defined by local specifications. To define them, we recall the following well-known notions in statistical mechanics, see Georgii (1988), \[20\].

**Definition 2.1** A probability kernel on $(\Omega, F)$ is a function $\Gamma(\cdot | \cdot) : F \times \Omega \rightarrow [0, 1]$ such that

(a) $\Gamma(\cdot | \omega)$ is a probability measure on $(\Omega, F)$, for each $\omega \in \Omega$,

(b) $\Gamma(A | \cdot)$ is a $F$-measurable function for each $A \in F$.

**Definition 2.2** A specification on $(\Omega, F)$ is a family $\gamma = \{\gamma_\Lambda\}_{\Lambda \Subset \mathbb{Z}^d}$ of probability kernels on $(\Omega, F)$ such that

(a) For each $\Lambda \Subset \mathbb{Z}^d$ and each $A \in F$, the function $\gamma_\Lambda(A | \cdot)$ is $F_\Lambda$-measurable,

(b) For each $\Lambda \Subset \mathbb{Z}^d$ and each $A \in F_\Lambda$, $\gamma_\Lambda(A | \omega) = 1_A(\omega)$,

(c) For any pair of regions $\Lambda$ and $\Delta$, with $\Lambda \subset \Delta \Subset \mathbb{Z}^d$, and any measurable set $A$,

$$\int \gamma_\Delta(d\omega' | \omega) \gamma_\Lambda(A | \omega') = \gamma_\Delta(A | \omega)$$

(2.1)

for all $\omega \in \Omega$. 

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Definition 2.3 A probability measure $\mu$ on $(\Omega, \mathcal{F})$ is consistent with a specification $\gamma$ if for each $\Lambda \subseteq \mathbb{Z}^d$ and for each $A \in \mathcal{F}$,
\[
\int \mu(\omega) \gamma_{\Lambda}(\cdot | \omega) = \mu(A).
\]
(2.2)

We now define the Variable-neighborhood random fields.

Definition 2.4 Variable-neighborhood random field
Let $\mu$ be a probability measure on $(\Omega, \mathcal{F})$ consistent with the specification $\gamma$. Then $\mu$ is a variable-neighborhood random field if for any $\Lambda \subseteq \mathbb{Z}^d$ and for $\mu$–almost all $\omega_{\Lambda^c}$ the following holds: there exists $\Gamma = \Gamma(\omega) \subseteq \mathbb{Z}^d$ such that
\[
\gamma_{\Lambda}(\cdot | \omega_{\Lambda^c}) = \gamma_{\Lambda}(\cdot | \omega_{\Gamma}),
\]
and for all $\tilde{\Gamma} \subset \mathbb{Z}^d$, if $\gamma_{\Lambda}(\cdot | \omega_{\Lambda^c}) = \gamma_{\Lambda}(\cdot | \omega_{\tilde{\Gamma}})$, then $\Gamma \subset \tilde{\Gamma}$. We denote
\[
\text{sp}_{\Lambda}(\omega) = \Gamma(\omega) \quad \text{and} \quad c_{\Lambda}(\omega) = \omega_{\text{sp}_{\Lambda}(\omega)},
\]
the restriction of $\omega$ on the set $\text{sp}_{\Lambda}(\omega)$.

Remark 2.5 In Definition 2.4 the requirement that if $\gamma_{\Lambda}(\cdot | \omega_{\Lambda^c}) = \gamma_{\Lambda}(\cdot | \omega_{\Gamma})$, then $\Gamma(\omega) \subset \tilde{\Gamma}$ allows to identify in an unambiguous way the random set $\Gamma(\omega)$ on which $\gamma_{\Lambda}(\cdot | \omega_{\Lambda^c})$ depends on.

Remark 2.6 We call the Variable-neighborhood random fields also Parsimonious Markov random fields. Namely $\gamma_{\Lambda}(\cdot | \omega_{\Lambda^c})$ depends only on $\omega_{\text{sp}_{\Lambda}(\omega)}$ and we do not need to inspect the whole configuration $\omega_{\Lambda^c}$ in order to decide about the configuration of symbols within $\Lambda$. Indeed it is sufficient to inspect $\omega_{\text{sp}_{\Lambda}(\omega)}$.

According to Definition 2.4 there might be a set of realizations of $\mu$–measure zero so that $|\text{sp}_{\Lambda}(\omega)| = \infty$. From now on we assume that for all $\omega \in \Omega$, $\text{sp}_{\Lambda}(\omega)$ is a finite set. This means that for all $\omega \in \Omega$, $\gamma_{\Lambda}(\cdot | \omega_{\Lambda^c})$ does only depend on a finite, but random neighborhood of $\Lambda$. When for some $\Gamma_0 \subseteq \mathbb{Z}^d$, $\text{sp}_{\Lambda}(\omega) = \Gamma_0$ for all $\omega$, then $\mu$ (respectively, $X$) is a Markov field with basic neighborhood $\Gamma_0$. Define the $\sigma$–algebra
\[
\mathcal{F}_{\text{sp}_{\Lambda}} = \left\{ A \in \mathcal{F} : \forall \Gamma \subset \mathbb{Z}^d : \{\text{sp}_{\Lambda} = \Gamma\} \cap A \in \mathcal{F}_\Lambda \right\}.
\]
(2.4)

Then for all $\omega_{\Lambda} \in \mathcal{A}_\Lambda$, $\gamma_{\Lambda}(\{\omega_{\Lambda}\}|\cdot)$ is a measurable function with respect to $\mathcal{F}_{\text{sp}_{\Lambda}}$.

In analogy to the terminology used for one dimensional variable length Markov chains we can rephrase the Definition 2.4 using the concept of family of contexts. This generalizes the notion of context trees to more than one dimension.

Definition 2.7 The family of contexts associated to the specification $\gamma$
For $\Lambda \subseteq \mathbb{Z}^d$ and $\omega \in \Omega$ we denote by $c_{\Lambda}(\omega) = c_{\Lambda}(\omega)$, see (2.3), the $\Lambda$–context of $\omega$ associated to the specification $\gamma$. We write $\tau(\Lambda) \equiv \tau(\Lambda)^{\gamma} = \{c_{\Lambda}(\omega), \omega \in \Omega\}$ for the family of $\Lambda$-contexts. Under our assumptions,
\[
\tau(\Lambda) \subseteq \bigcup_{\Gamma \in \mathbb{Z}^D \setminus \Lambda} \mathcal{A}_\Gamma.
\]
(2.5)

We use the short-hand notation $c_i(\omega)$ for $c_{\{i\}}(\omega)$, $\text{sp}_i(\omega)$ for $\text{sp}_{\{i\}}(\omega)$ and $\gamma_i(a|\omega)$ for $\gamma_{\{i\}}(\{a\}|\omega)$, $i \in \mathbb{Z}^d$. 
Remark 2.8 It is immediate to verify from Definition 2.4 that the family $\tau^{(\Lambda)}$ has the following properties:

- No element of $\tau^{(\Lambda)}$ is restriction of any other element of $\tau^{(\Lambda)}$: If $\eta_T$ and $\tilde{\eta}_T$ both belong to $\tau^{(\Lambda)}$, $\Gamma \subset \tilde{\Gamma}$ and $\eta_T = \tilde{\eta}_T$, then $\Gamma = \tilde{\Gamma}$.

- $\tau^{(\Lambda)}$ defines a partition of $A^{\mathbb{Z}^d \setminus \Lambda}$, that is, for each $\omega \in A^{\mathbb{Z}^d \setminus \Lambda}$ there exists a unique $\Gamma \subset \mathbb{Z}^d \setminus \Lambda$ such that $\omega_{\Gamma} \in \tau^{(\Lambda)}$.

In this way the family of local specifications associated to $\mu$ is

$$\gamma = \{\gamma_{\Lambda}(\cdot|c_{\Lambda}(\omega)), \Lambda \in \mathbb{Z}^d; c_{\Lambda}(\omega)\}$$

which leads to a more parsimonious description than the original

$$\{\gamma_{\Lambda}(\cdot|\omega_{\Lambda^n}), \Lambda \in \mathbb{Z}^d; \omega_{\Lambda^n}\}.$$ 

We close the section presenting three examples. In the first one we embed a renewal process in a one dimensional Variable-neighborhood random field. This example has been suggested by Ferrari and Wyner (2003), [14]. In the second example we construct a two dimensional Variable-neighborhood random field by specifying a variable-neighborhood interaction potential. In the third example, we define a two dimensional Voronoi cell interaction model. This example has been inspired by Dereudre, Drouilhet and Georgii (2010), [7].

Example 2.9 We consider $A = \{0, 1\}$. Let $\{X_n : n \in \mathbb{Z}\}$ be a stationary alternating renewal process taking values in $A$, i.e. the times when the process switches between 1 and 0 or 0 and 1 are independent and identically distributed random variables. They have the same distribution as the random variable $T$ defined through

$$\mathbb{P}[T = j] = c_1\rho_1^j + c_2\rho_2^j, \quad 0 < \rho_2 < \rho_1 < 1, \quad j \in \mathbb{N}.$$ 

Set $\mu = \mathbb{E}[T]$. This process can be realized as a one dimensional Variable-neighborhood random field. To this aim define for $a$ and $b$ in $\mathbb{Z}$

$$R_b(\omega) = \inf\{n > b + 1 : \omega(n) \neq \omega(b + 1)\}, \quad L_a(\omega) = \sup\{n < a - 1 : \omega(n) \neq \omega(a - 1)\},$$

where $\omega \in A^\mathbb{Z}$. The family of local specifications $\gamma_{\{a, b\}}$ indexed by $[a, b] \subset \mathbb{Z}$, is given as follows:

$$\gamma_{\{a, b\}}(\cdot|c_{\{a, b\}}(\omega)) = \gamma_{\{a, b\}}(\cdot|L_a(\omega) = -k, R_b(\omega) = l).$$

The context $c_{\{a, b\}}(\omega)$ depends only on the neighbor sites of $[a, b]$ which are all of the same type 0 or 1. By standard calculus we obtain the following formulas for the one point specification $\gamma_{\{0\}}(\cdot|c_0(\omega))$. Write $sp_0(\omega) = [L_0(\omega), R_0(\omega)] \setminus \{0\}$. Then

$$\gamma_{\{0\}}(1 \mid L_0(\omega) = -k, R_0(\omega) = l, \omega(1) = \omega(-1) = 1) = \frac{(c_1\rho_1^{l+k-1} + c_2\rho_2^{l+k-1})}{(c_1\rho_1^{l+k-1} + c_2\rho_2^{l+k-1}) + (c_1\rho_1^{k-1} + c_2\rho_2^{k-1}) + (c_1\rho_1^{l-1} + c_2\rho_2^{l-1})} = \frac{c_1\rho_1 + c_2\rho_2}{r_{\rho_1}^2 + r_{\rho_2}^2}$$

(2.9)
Denote

\[ \gamma_{(0)}(1 \mid L_0(\omega) = -k, R_0(\omega) = l, \omega(1) = 0, \omega(-1) = 1) \]

\[ = \frac{(c_1d^k_1 + c_2d^k_2)(c_1d^{l-1}_1 + c_2d^{l-1}_2)}{(c_1d^k_1 + c_2d^k_2)(c_1d^{l-1}_1 + c_2d^{l-1}_2) + (c_1d^{k-1}_1 + c_2d^{k-1}_2)(c_1d^l_1 + c_2d^l_2)}. \]  

(2.10)

Due to the symmetry between 0 and 1, it is clear that with formulas (2.9) and (2.10), we have completely described the one-point specification.

In this example the context \(c_0(\cdot)\) is \(\mathbb{P}\)-almost surely finite, i.e. there exists a subset of configurations of \(\mathbb{P}\)-measure zero for which \(|c_0(\omega)| = \infty\).

We now give an example of a Variable-neighborhood random field in dimension \(d = 2\). In analogy with the procedure used in statistical mechanics we define a variable-neighborhood interaction potential.

**Example 2.10** We consider \(A = \{-1, 1\}\) and \(d = 2\). In order to define the support of the variable-neighborhood interaction potential it is convenient to embed \(\mathbb{Z}^2\) into \(\mathbb{R}^2\). We partition \(\mathbb{R}^2\) into cubes of edge 1 centered at \(\mathbb{Z}^2\). We say that two cubes are connected if they have one face in common. We denote by \(\mathcal{R}\) the set of all connected unions of such cubes, by \(\Gamma\) an element of \(\mathcal{R}\) and by \(\partial\Gamma\) the topological surface of \(\Gamma\).

We say that \(\Gamma \subset \mathbb{Z}^2\) is a polygon if there exists \(R \in \mathcal{R}\) so that \(\Gamma = R \cap \mathbb{Z}^2\). We denote by \(\partial\Gamma = \{i \in \Gamma : d(i, \partial R) \leq \frac{1}{2}\}\), where \(d(i, \partial R) = \inf\{||i - j|| : j \in \partial R\}\) and \(|| \cdot ||\) is the maximum norm introduced at the beginning of this section. Finally, let \(\hat{\Gamma}\) be the interior of \(\Gamma\), \(\hat{\Gamma} = \Gamma \setminus \partial\Gamma\).

We say that \(\Gamma\) is a simple polygon if \(\partial\Gamma\) is a path in \(\mathbb{Z}^2\) which does not cross itself and \(\hat{\Gamma} \neq \emptyset\). Note that \(\partial\Gamma\) can be the union of disjoint connected paths.

Given \(\omega \in \mathcal{A}^\mathbb{Z}^2\) we define for each \(i \in \mathbb{Z}^2\)

\[ \Gamma_i^1(\omega) = \cap\{\Gamma \subset \mathbb{Z}^2, \Gamma\text{ simple polygon }, i \in \hat{\Gamma}, \omega_{\partial\Gamma} = 1\}. \]

In the above definition we do not require \(\Gamma\) to be finite. \(\Gamma\) could be equal to \(\mathbb{Z}^2\) in which case \(\partial\Gamma = \emptyset\). In order to get a bounded interaction range, we set

\[ \Gamma_i(\omega) = V_i(L) \cap \Gamma_i^1(\omega) \text{ and } c_i^K(\omega) = \{\omega_j : j \in \Gamma_i(\omega), j \neq i\}, \]

where \(V_i(L) = \{j \in \mathbb{Z}^2 : ||i - j|| \leq L\}\). In the above definition, the superscript \(K\) underlines the fact that the context \(c_i^K(\omega)\) for the interaction might not be the same as the context \(c_i(\omega)\) associated to the specification. Let \(\{J_n, n \in \mathbb{N}\}\) be a collection of real numbers and \(|\Gamma_i(\omega)|\) the cardinality of \(\Gamma_i(\omega)\). We define the variable neighborhood interaction \(\{K^i(\omega), i \in \mathbb{Z}^2\}\) as following:

\[ K^i(\omega) = K^i(c_i^K(\omega)) = J_{|\Gamma_i(\omega)|} \prod_{j \in \Gamma_i(\omega)} \omega(j). \]

By construction, the interaction is summable:

\[ \sup_{i \in \mathbb{Z}^2} \sum_{j \in \mathbb{Z}^2} \sup_{\omega : \Gamma_i(\omega) \neq \emptyset} |K^i(\omega)| < \infty. \]  

(2.11)

\[ \text{Denote} \]

\[ H_N(\omega_\Lambda, \omega_{\Lambda'}) = - \sum_{\{i \in \mathbb{Z}^2 : \Lambda \cap \Gamma_i(\omega) \neq \emptyset\}} K^i(\omega). \]
The Variable-neighborhood random field $\mu$ is determined by the following family of local specifications

$$
\gamma_\Lambda(\{\omega_\Lambda \mid \omega_{\Lambda^c}\}) = \frac{1}{Z_{\omega_{\Lambda^c}}} \exp\{-\beta H_\Lambda(\omega_\Lambda, \omega_{\Lambda^c})\}, \quad \omega_\Lambda \in \mathcal{A}_\Lambda, \omega_{\Lambda^c} \in \mathcal{A}_{\Lambda^c},
$$

(2.12)

where

$$
Z_{\omega_{\Lambda^c}} = \sum_{\omega_\Lambda \in \{-1,1\}^\Lambda} \exp\{-\beta H_\Lambda(\omega_\Lambda, \omega_{\Lambda^c})\}.
$$

The family of contexts $c_\Lambda(\omega) = \omega_{\text{sp}_\Lambda(\omega)}$ associated to $\{\gamma_\Lambda\}_\Lambda$, defined in (2.12), is determined by $c_i(\omega)$ for $i \in \Lambda$, therefore by the knowledge of $\omega$ only on $\text{sp}_1(\omega)$. By Definition 2.4 and by (2.12) we have that

$$
\text{sp}_1(\omega) = \left[ \bigcup_{j \in \mathbb{Z}^2} \{\Gamma_j(\omega) : i \in \Gamma_j(\omega)\} \cup \bigcup_{j \in \mathbb{Z}^2} \{\Gamma_j(\omega^j) : i \in \Gamma_j(\omega^j)\} \right] \setminus \{i\},
$$

(2.13)

where $\omega^j(j) = \omega(j)$ for all $j \neq i$, $\omega^j(i) = -\omega(i)$. This formula gives the relation between the support of the context of the specification and the support of the interaction. We show in the appendix that the following identity holds:

$$
\text{sp}_1(\omega) = (\Gamma_i^1(\omega) \cap V_i(2L)) \setminus \{i\}, \quad c_i(\omega) = \omega_{\text{sp}_1(\omega)}.
$$

(2.14)

Note that the context associated to the family of the constructed specification $c_i(\omega)$ is different from $c_i^K(\omega)$, the context associated to the interaction.

We now give a second example of a Variable-neighborhood random field in dimension $d = 2$ in which contexts are no more bounded. This example is inspired by a recent paper of Dereudre, Drouilhet and Georgii (2010), in which Gibbs point processes on $\mathbb{R}^d$ with geometry dependent interactions are considered. Such processes can be realized as Variable-neighborhood random fields. Compared to their work, our setup is simpler since we do not work on $\mathbb{R}^2$ but on the grid $\mathbb{Z}^2$.

**Example 2.11** We consider $\mathcal{A} = \{0,1\}$ and $d = 2$. For $\omega \in \mathcal{A}^{\mathbb{Z}^2}$ we denote by $C(\omega) = \{i \in \mathbb{Z}^2 : \omega(i) = 1\}$. We embed $\mathbb{Z}^2$ into $\mathbb{R}^2$. For any fixed $\omega \in \mathcal{A}^{\mathbb{Z}^2}$ with $C(\omega) \neq \emptyset$ and $i \in C(\omega)$, let

$$
\text{Vor}_i(\omega) := \{y \in \mathbb{R}^2 : \|i - y\|_2 \leq \|k - y\|_2, \forall k \in C(\omega), k \neq i\}
$$

be the Voronoi cell associated to a point $i \in C(\omega)$. If there exists no such $k \in C(\omega)$, then set $\text{Vor}_i(\omega) = \mathbb{Z}^2 \setminus \{i\}$. We denote by $\| \cdot \|_2$ the $L^2$-norm on $\mathbb{R}^2$. For a bounded function $\Phi : \mathcal{P}(\mathbb{R}^2) \to \mathbb{R}$ defined on all subsets of $\mathbb{R}^2$, we define for any $i \in C(\omega)$,

$$
K^i(\omega) = \Phi(\text{Vor}_i(\omega)).
$$

For $i \notin C(\omega)$, we set $K^i(\omega) = 0$. When $C(\omega) = \emptyset$ set $K^i(\omega) = 0$ for all $i \in \mathbb{Z}^2$. Finally, let

$$
H_\Lambda(\omega_\Lambda, \omega_{\Lambda^c}) = -\sum_{\{i \in \mathbb{Z}^2 : i \in C(\omega), \Lambda \cap \text{Vor}_i(\omega) \neq \emptyset\}} K^i(\omega).
$$

Clearly, the range of interaction is not bounded in this case. We have to ensure that the interaction is summable. Since for any fixed $i \in \mathbb{Z}^2$ and $k \in \mathbb{N}$

$$
\text{card}\{j \in \mathbb{Z}^2 : i \in \mathbb{Z}^2 \cap \text{Vor}_j(\omega), \|i - j\| = k\} \leq 8k,
$$

we have that

$$
\sum_{\{i \in \mathbb{Z}^2 : i \in C(\omega), \Lambda \cap \text{Vor}_i(\omega) \neq \emptyset\}} |K^i(\omega)| < \infty.
$$
In Section 2 we introduced the notion of Variable-neighborhood random fields. Such a random field is completely determined by the one point specification. It would therefore be interesting to estimate sp\(_\Lambda\) of a Variable-neighborhood random field. This implies that sp\(_\Lambda\) is then determined by the following family of local specifications

\[
\gamma_\Lambda (\omega_\Lambda | \omega_{\Lambda^c}) = \frac{1}{Z^{\omega_{\Lambda^c}}} \exp\{-\beta H_\Lambda (\omega_\Lambda, \omega_{\Lambda^c})\}, \quad \omega_\Lambda \in A^\Lambda, \omega_{\Lambda^c} \in A^{\Lambda^c},
\]

where

\[
Z^{\omega_{\Lambda^c}} = \sum_{\omega_\Lambda \in \{0,1\}^\Lambda} \exp\{-\beta H_\Lambda (\omega_\Lambda, \omega_{\Lambda^c})\}.
\]

One can generalize in a relatively straightforward way the last two examples to \(d \geq 3\).

We are interested in estimating the support of the context sp\(_\Lambda\) for a given set of sites \(\Lambda \subset \mathbb{Z}^d\) and a given observation \(\omega\). Proposition 9.1 of the Appendix shows that \(\gamma_\Lambda (\omega | c_\Lambda (\omega))\) can be derived from the one point specification \(\gamma_i (\cdot | c_i (\omega))\) and that for \(\Lambda \subset \mathbb{Z}^d\), we have

\[
\text{sp}_\Lambda (\omega) = \bigcup_{\omega_\Lambda \in \text{sp}_\Lambda (\omega)} \bigcup_{\omega_{\Lambda^c} \in \text{sp}_\Lambda (\omega_{\Lambda^c})} \Lambda.
\]

Hence, in order to estimate sp\(_\Lambda\) (\(\omega\)), it is sufficient to estimate the context for single sites, i.e. sp\(_i\)(\(\omega\)). To implement the estimation procedure we need translation covariant models.

For any fixed \(i \in \mathbb{Z}^d\), we denote by \(\tau_i : \mathbb{Z}^d \to \mathbb{Z}^d\) the \(i\)-shift defined by \(\tau_i (j) = i + j\). This naturally induces on \(\Omega\) the \(i\)-shift \(T_i : \Omega \to \Omega\) defined by

\[
(T_i \omega) (j) = \omega (\tau_i (j)) = \omega (i + j) \quad \forall j \in \mathbb{Z}^d.
\]

**Definition 2.12** A Variable-neighborhood random field \(\mu\) on \((\Omega, \mathcal{F})\), determined by a family of local specifications \(\{\gamma_\Lambda\}_\Lambda\), is translation covariant if for all \(\Lambda \subset \mathbb{Z}^d\) and for all \(\omega \in \Omega\)

\[
\gamma_\Lambda (\cdot | \omega) = \gamma_{\tau_i \Lambda} (\cdot | T_i \omega), \quad i \in \mathbb{Z}^d
\]

where \(\tau_i \Lambda = \Lambda + i\).

In the following we will consider only translation covariant Variable-neighborhood random fields. This implies that \(\gamma_i (\cdot | c_i (T_i (\omega))) = \gamma_0 (\cdot | c_0 (\omega))\).

### 3 Main Results and Estimation procedure

In Section 2 we introduced the notion of Variable-neighborhood random fields. Such a random field is completely determined by the one point specification. It would therefore be interesting to estimate sp\(_i\)(\(\omega\)), i.e. the set of points in \(\mathbb{Z}^d\) which enables to determine the value of the symbol at the site \(i\). This requires, however, to estimate too many unknown parameters. Therefore we are less ambitious and estimate the radius of the smallest ball containing sp\(_i\)(\(\omega\)). For \(\ell \geq 1\) and \(i \in \mathbb{Z}^d\), define

\[
V_i (\ell) = \{ j \in \mathbb{Z}^d : ||i - j|| \leq \ell \} \quad \text{and} \quad V_i^0 (\ell) = V_i (\ell) \setminus \{i\}.
\]
We also write
\[
\partial V_i(\ell) = \{j \in \mathbb{Z}^d : \|i - j\| = \ell\}.
\]
Then we define the length of the context of site \(i\) by
\[
l_i(\omega) = \inf\{\ell > 0 : \text{sp}(\omega) \subset V_i(\ell)\}.
\]
Note that \(l_i(\omega)\) is a stopping time with respect to the filtration \((\mathcal{G}_n)_{\omega}\) stands for a generic configuration of the field. In order to distinguish between generic configurations and observed data, we will denote the observed data by \(\sigma\). Our statistical inference is based on observations of the \(V_i(\ell)\), \(n\) \(\mathcal{H}\) hypothetical Markov random field for which the corresponding context is contained in \(X_i\), hence
\[
\text{Hence, at step } n, \text{ the sample is } (\sigma_n), \text{ where } \sigma_n \text{ is the fixed realization of } \mu \text{ in restriction to } \Lambda_n. \text{ We will construct our estimators based on sites within some security region } \bar{\Lambda}_n \subset \Lambda_n, \text{ where}
\]
\[
\bar{\Lambda}_n = \{i \in \Lambda_n : V_i(k(n)) \subset \Lambda_n\}
\]
with
\[
k(n) = (\log |\Lambda_n|)^{1/\beta}.
\]
In order to estimate \(u_i(\omega)\), we have to compare the neighborhood configuration of site \(i\) with the neighborhood configurations of different sites \(j\) for all \(j \in \bar{\Lambda}_n\). To do so we define for any fixed \(i \in \bar{\Lambda}_n\) and any \(1 \leq \ell \leq k(n)\),
\[
X_i^\ell(\omega) = \{X_i^\ell(\omega)(j) = \omega(i + j), \quad j : 0 < ||j|| \leq \ell\},
\]
hence \(X_i^\ell(\omega)\) is the configuration around \(i\) in a box of edge \(\ell\). In terms of the shift operator, \(X_i^\ell(\omega) = (\omega \circ \tau_i)^{V_0(\ell)}\), i.e. this is the restriction of \(T_i \omega\) to \(V_0(\ell)\). We stress that \(X_i^\ell\) does not depend on \(\omega(i)\), the center of the observation window, and this is important to our purposes. We shall use the short-hand notation
\[
X_i^\ell(\omega) = \omega_i^\ell.
\]
For any \(1 \leq \ell \leq k(n)\), for any fixed configuration \(\eta \in \mathcal{A}^{V_0(\ell)}\), let
\[
N_n(\eta) = \sum_{j \in \bar{\Lambda}_n} 1_{\{X_i^\ell(\omega) = \eta\}}
\]
be the total number of occurrences of \(\eta\) within \(\bar{\Lambda}_n\). Moreover, for any fixed value \(a \in \mathcal{A}\), we write
\[
N_n(\eta, a) = \sum_{j \in \bar{\Lambda}_n} 1_{\{X_i^\ell(\omega) = \eta, X_j = a\}}.
\]
In particular for the observed data \(\sigma\), \(\sigma_i^\ell\) is the data observed around the site \(i\) in a ball of radius \(\ell\), \(N_n(\sigma_i^\ell)\) is the total number of occurrences of the local pattern around \(i\) within \(\bar{\Lambda}_n\). By construction \(N_n(\sigma_i^\ell) \geq 1\). Note that \(N_n(\sigma_i^\ell, a)\) could be zero.

Let \(\gamma : \mathcal{A} \times \mathcal{A}^{V_0(\ell)} \to [0, 1]\). \(\gamma\) is interpreted as possible one-point specification of a hypothetical Markov random field for which the corresponding context is contained in \(V_i(\ell)\). For any site \(i\), under the hypothesis that its context is contained in \(V_i(\ell)\), we define the pseudo-likelihood of \(\gamma\) as follows:
\[
PL_n^{(i, \ell)}(\gamma) = \prod_{j \in \bar{\Lambda}_n, X_j = \sigma_i^\ell} \gamma(X_j | X_j^\ell) = \prod_{a \in \mathcal{A}} \gamma(a | \sigma_i^\ell)^{N_n(\sigma_i^\ell, a)},
\]
where we restrict the product to all sites $j \in \bar{\Lambda}_n$ in order to be sure that $V_j(\ell)$ is still contained inside the observation window $\Lambda_n$. Maximizing (3.8) with respect to $\gamma$ under the constraint

$$
\sum_{a \in A} \gamma(a|\sigma_i^\ell) = 1
$$

gives the following estimator of the one-point specification

$$
\hat{p}_n(a|\sigma_i^\ell) = \frac{N_n(\sigma_i^\ell, a)}{N_n(\sigma_i^\ell)}.
$$

(3.9)

Analogously, we can define for any fixed configuration $\eta \in A_{V_0(\ell)}$

$$
\hat{p}_n(a|\eta) = \begin{cases} 
\frac{N_n(\eta, a)}{N_n(\eta)} & \text{if } N_n(\eta) > 0, \\
0 & \text{otherwise.}
\end{cases}
$$

(3.10)

**Remark 3.1** Not all $\gamma$ satisfying $\sum_{a \in A} \gamma(a|\sigma_i^\ell) = 1$ are possible one-point specifications; one point specifications have to satisfy additional conditions, which are collected in the appendix, see (9.2), and which are not considered here. However, we define the pseudo-likelihood also for $\gamma$ not satisfying these additional conditions.

Thus, given the sample $\sigma_{\Lambda_n}$, the logarithm of the maximum pseudo-likelihood of $\gamma$ is the following quantity:

$$
\log MPL_n(i, \ell) = \sum_{a \in A} N_n(\sigma_i^\ell, a) \log \hat{p}_n(a|\sigma_i^\ell).
$$

(3.11)

The decision if for a given $i$ the context has radius $\ell - 1$ rather than $\ell$ is based on the Kullback-Leibler information. We introduce

$$
\log L_n(i, \ell) = \sum_{v \in A_{V_0}^{\ell-1}(i)} N_n(\sigma_i^{\ell-1}v) D(\hat{p}_n(\cdot|\sigma_i^{\ell-1}v), \hat{p}_n(\cdot|\sigma_i^{\ell-1})),
$$

(3.12)

where we sum over all possibilities of extending $\sigma_i^{\ell-1}$ to a configuration $\sigma_i^{\ell-1}v$ of radius $\ell$ and where

$$
D(\hat{p}_n(\cdot|\sigma_i^{\ell-1}v), \hat{p}_n(\cdot|\sigma_i^{\ell-1})) = \sum_{a \in A} \hat{p}_n(a|\sigma_i^{\ell-1}v) \log \left[ \frac{\hat{p}_n(a|\sigma_i^{\ell-1}v)}{\hat{p}_n(a|\sigma_i^{\ell-1})} \right]
$$

is the Kullback-Leibler information. Note that $\log L_n(i, \ell)$ is a function of $\sigma_i^{\ell-1}$, but not of $\sigma_i^\ell$. We rewrite it as follows:

$$
\log L_n(i, \ell) = \sum_{j: X_j^{\ell-1} = \sigma_i^{\ell-1}} \frac{1}{N_n(X_j^{\ell})} \sum_{a \in A} N_n(X_j^{\ell}, a) \log \left[ \frac{\hat{p}_n(a|X_j^{\ell})}{\hat{p}_n(a|X_j^{\ell-1})} \right].
$$

(3.13)

Finally note that

$$
\log L_n(i, \ell) = \left[ \sum_{j: X_j^{\ell-1} = \sigma_i^{\ell-1}} \frac{1}{N_n(X_j^{\ell})} \log MPL_n(j, \ell) \right] - \log MPL_n(i, \ell - 1). \tag{3.14}
$$
Now we start from $\ell = R_n$ and proceed successively from $\ell$ to $\ell - 1$. The log likelihood ratio statistics $\log L_n(i, \ell)$ will be basically equal to zero for all $\ell > l_i(\sigma)$. The first range at which $\log L_n(i, \ell)$ is significantly different from zero is a range such that $\hat{p}_n(\cdot | \sigma_{i}^{\ell-1}) \neq \tilde{p}_n(\cdot | \sigma_{i}^{\ell})$ in which case it is reasonable to suppose that $\ell = l_i(\sigma)$.

Before formalising this intuition in the definition of the estimator, for technical reasons we have to introduce the following security diameter

$$R_n = \left\lfloor (\log |\bar{\Lambda}_n|)^{\frac{1}{2}} \right\rfloor,$$  \hspace{1cm} (3.15)

where $\lfloor \cdot \rfloor$ denotes the integer part of a number. Note however that $R_n/k(n) \to 1$ as $n \to \infty$, where $k(n)$ was defined in (3.4). We are now able to define the estimator of the context length function.

**Definition 3.2 The estimator**  Given the observation $\sigma_{\Lambda_n}$, for any $i \in \bar{\Lambda}_n$, see (3.3), the estimator of $l_i(\sigma)$, defined in (3.2), is the following random variable

$$\hat{l}_n(i) = \hat{l}_n(i, \sigma) = \min\{\ell = 1, \ldots, R_n - 1 : \forall k > \ell, \log L_n(i, k) \leq \text{pen}(k, n)\}, \hspace{1cm} (3.16)$$

whenever $\{\ell = 1, \ldots, R_n - 1 : \forall k > \ell, \log L_n(i, k) \leq \text{pen}(k, n)\} \neq \emptyset$. Otherwise we set $\hat{l}_n(i) = R_n$. In the above definition,

$$\text{pen}(\ell, n) = \kappa |\mathcal{A}| |\mathcal{A}|^{\frac{1}{2}} \log |\Lambda_n|,$$  \hspace{1cm} (3.17)

and $\kappa$ is a positive constant that can be chosen freely, provided it is at least of the order given in (3.18).

In other words, the above estimator chooses the minimal length $\ell$ such that all sites which are relevant to determine the value of the symbol at site $i$ belong to a ball of radius $\ell$. Once we have estimated the context length function, the underlying context $c_i(\sigma)$ is then estimated by

$$\hat{c}_{n,i}(\sigma) = \sigma_{V_i(\hat{l}_n(i))},$$

and the corresponding one point specification by $\hat{\gamma}_{n,i}(a|\sigma) = \tilde{p}_n(a|\hat{c}_{n,i}(\sigma))$.

**Remark 3.3**  1. In one dimension the above penalization term is independent of $\ell$, since in this case $|\mathcal{A}|^{\frac{1}{2}} = |\mathcal{A}|^2$. This leads to a penalty term

$$\text{pen}(n) = \kappa |\mathcal{A}|^3 \log |\Lambda_n|.$$

2. Once the statistician has determined the radius of the context $\ell = l_i(\sigma)$ by means of the estimator $\hat{l}_n(i)$, is is possible, in a second step, to determine the geometry of the context, i.e. to estimate $c_i(\sigma)$ itself. This can be done by adapting the estimator of Csiszár and Talata (2006), [4], to our setup where the penalty can be restricted to all shapes contained in $V_i(\ell)$ for $\ell = \hat{l}_n(i)$. 

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3.1 Main results

The estimator \( \hat{l}_n(i) \) depends on the penalization term, \( (3.17) \), therefore on the choice of the constant \( \kappa \). Choose \( \delta > 2d \log \frac{\delta e}{4q_{\min}} \) and define

\[
\kappa = \kappa(\delta) = \frac{5d}{2} \left( \frac{3}{2} \right)^{1/2} \delta. \tag{3.18}
\]

For the estimator defined in this way the following theorems are our main results.

Assumption 3.4 The local specification is positive. We define

\[
q_{\min} = \inf_{a \in \mathcal{A}} \inf_{\omega \in \Omega} \gamma_0(a|\omega) > 0. \tag{3.19}
\]

Theorem 3.5 (Overestimation) Let \( \mu \) be a translation covariant Variable-neighborhood random field for which Assumption 3.4 holds. For any \( \epsilon > 0 \) there exist \( n_0 = n_0(\epsilon, \delta, q_{\min}) \) and \( c(\delta) = c(\delta, q_{\min}) \), so that for any \( n \geq n_0 \) the probability of overestimation is bounded by

\[
\mu \left[ \exists i \in \tilde{\Lambda}_n : \hat{l}_n(i) > l_i(\sigma) \right] \leq C(d)(\log |\tilde{\Lambda}_n|)^{\frac{1}{1+\epsilon}} \cdot \exp \left( -c(\delta) \sqrt{\log |\tilde{\Lambda}_n|} \right) + C(d) \exp \left( -|\tilde{\Lambda}_n|^{1-\epsilon} \right), \tag{3.20}
\]

where \( C(d) \) is a positive constant depending only on the dimension and where \( \tilde{\Lambda}_n \) is given in \( (3.3) \).

Remark 3.6 To obtain an upper bound in \( (3.20) \) summable in \( n \), we need a fast increase of the sampling regions of order for example

\[
\log |\tilde{\Lambda}_n| \sim (\log n^{1+\epsilon})^2,
\]

which requires faster increase than choosing \( \Lambda_n = [-\frac{n}{2}, \frac{n}{2}]^d \).

For bounding the probability of underestimation we need an additional assumption. To this aim define

\[
r(i, j) = \sup_{\omega, \omega' : \omega(i) = \omega'(i), \omega(j) = \omega'(j)} \frac{1}{2} \| \gamma_i(\cdot|\omega) - \gamma_i(\cdot|\omega') \|_{TV}
\]

where \( \| \cdot \|_{TV} \) denotes the total variation norm. By translation covariance \( r(i, j) = r(0, i - j) \). We denote

\[
\beta(\ell) = \sum_{k \in \mathbb{Z}^d : \|k\| > \ell} r(0, k). \tag{3.21}
\]

Assumption 3.7 We assume that there exists \( L > 0 \) such that

\[
r(0, i) = 0 \quad \text{for all } \|i\| \geq L \tag{3.22}
\]

and

\[
r = \sum_{i \in \mathbb{Z}^d \setminus \{0\}} r(0, i) < 1. \tag{3.23}
\]
Remark 3.8 Condition (3.22) implies that the observed random field is actually a Markov random field of order L. The order L, however, is unknown. We do not propose to estimate this unknown order L. When passing to the parsimonious description (2.6), what we actually propose is to estimate, for every site i, given the observation σ, the minimal order \( l_i(\sigma) \) that we need in order to determine the specification at that site, given σ. This is also called Minimum Description Length in the literature. However, if \( l_i(\sigma) \) does not depend on the configuration, then our estimator naturally provides an estimator of L.

Condition (3.23) is the Dobrushin condition which implies uniqueness of the measure \( \mu \), see Dobrushin (1968), [9], [10].

For the Example 2.10 and Example 2.11, thanks to the summability assumptions (2.11) and (2.15), there exists for both of them a critical value of the temperature \( \beta_c \) such that (3.23) is satisfied for all \( \beta < \beta_c \). For the Example 2.9, condition (3.23) is verified. This can be shown as in the paper by Ferrari and Wyner (2003), [14], page 23.

Theorem 3.9 (Underestimation) Let \( \mu \) be a translation covariant Variable-neighborhood random field for which Assumption 3.4 and Assumption 3.7 hold. Then for any \( \epsilon > 0 \) there exists \( n_0 = n_0(\epsilon, \delta, q_{\min}, L) \), so that for any \( n \geq n_0 \) the probability of underestimation is bounded by

\[
\mu \left[ \exists \ i \in \bar{\Lambda}_n : \hat{l}_n(i) < l_i(\sigma) \right] \leq \exp \left( -|\bar{\Lambda}_n|^{1-\epsilon} \right). \tag{3.24}
\]

Remark 3.10

1. The above results are stated for all \( n \geq n_0 \) where \( n_0 \) depends on the (unknown) model parameter \( q_{\min} \) and on the interaction through \( L \). It is possible to write down upper bounds which hold for all \( n \), but then the bounds become more complicated and depend on \( q_{\min} \) and on \( L \). We adopted the above way of writing in order to state the results in a more transparent way.

2. Note that the trade-off between the rates of the two kind of errors (exponential convergence for the probability of underestimation in (3.24) and (basically) polynomial convergence of the probability of overestimation in (3.20)) is a typical feature in problems of order estimation appearing already in the simpler problem of order estimation for Markov chains, see e.g. the papers by Finesso et al. (1996), [15], and Merhav et al. (1989), [25].

This represents the usual trade-off between type one and type two errors in statistical decision problems: Overestimation means that the estimate exceeds the true order and that we choose models that include the true data-generating mechanism. This choice is not optimal but does only lead to a higher cost. On the other hand underestimation leads to a restriction to lower order models that do not describe the observed data.

So it is desirable to have an exponential control on the probability of underestimation while keeping some polynomial control on the probability of overestimation.

3. The definition of our estimator depends on the parameter \( \delta \). This plays an important role only for the overestimation. Namely it appears in the exponent of the upper bound through the constant

\[
c(\delta) = \frac{2}{3} \frac{2q_{\min} \delta}{e} - 2^d \log |A|,
\]
(see end of the proof of Lemma 5.2). To ensure the consistency of the estimator we need to choose $\delta$ sufficiently large, depending on the one-point specification and on $q_{\min}$ such that $c(\delta) > 0$. Therefore, our estimator is not universal, in the sense that for fixed $\delta$ it fails to be consistent for any random field such that $c(\delta) < 0$.

This problem appears even in the simpler case of order estimation for Markov chains, see for example Finesso et al. (1996), [15], and Merhav et al. (1989), [25]. As pointed out by Finesso et al. (1996), [15], it is not possible to have an exponential bound on the overestimation probability of an order estimator without rendering it inconsistent, for at least one model, for the underestimation.

**Remark 3.11** Let us finally compare our results in the case of dimension one to the results of Ferrari and Wyner (2003), [14]. They consider stationary chains taking values in a finite alphabet without imposing any a priori bound on the memory. Hence, they are dealing with infinite trees. They overcome this difficulty by approximating the possibly infinite memory chain by a sequence of finite range Markov chains of growing order. The price to pay in order to deal with these general processes is to impose geometrically $\alpha$—mixing conditions both for the control of the over- and the underestimation.

In comparison to their results, to control the underestimation, we need a slightly stronger assumption. We require geometrically $\Phi$—mixing which implies geometrically $\alpha$—mixing. This is crucial to obtain Theorem 3.9. We use Condition (3.22) as sufficient condition to obtain the geometrically $\Phi$—mixing.

Condition (3.22), which implies that the random field is of finite range, could probably be relaxed. It should be possible to deal with infinite range models, provided one finds other sufficient conditions implying mixing.

Note however, that mixing implies automatically the uniqueness of the underlying measure $\mu$. Hence, using this kind of technique always implies that the Dobrushin uniqueness condition (3.23) must be satisfied. There is some hope to deal with the underestimation even in the case of phase transition, see Remark 4.3.

Concerning the control of the overestimation, we are able to deal with the general long range case without requiring mixing. Hence we can do better than Ferrari and Wyner (2003), [14], in this aspect. We need to impose the positivity condition on the specification, see Assumption 3.4. Ferrari and Wyner do only impose positivity within each step of the canonical Markov approximation, allowing these lower bounds to tend to zero at a certain rate.

## 4 Deviation inequalities for underestimation

The deviation inequalities needed for the underestimation are based on results obtained by Dedecker (2001), [6], on exponential inequalities for random fields. To adapt these results to our model we need Assumption 3.4 and Assumption 3.7. In the next subsection we present a preliminary deviation inequality based on the results of Dedecker (2001), [6], and then give in the following subsection the deviation inequalities needed to control the probability of underestimation.

### 4.1 Preliminaries

Fix $\ell > 0$. For a given configuration $\eta \in \mathcal{A}^{V_0(\ell)}$, we define

$$p(\eta) = \mu(\{X_i = \eta_i, \ \forall \ i \in V_0^0(\ell)\}).$$

(4.1)
Recall that \( N_n(\eta) \) is the total number of occurrences of \( \eta \) in the observation \( \sigma_{\Lambda_n} \). Then we get the following result which is an immediate consequence of Corollary 4 of Dedecker (2001), [6].

**Proposition 4.1** Under Assumption 3.4 and Assumption 3.7 there exists a constant \( c(d,L) \) depending only on the dimension and on the range \( L \), such that for any configuration \( \eta \in A_{V_0}(\ell) \),

\[
\mu \left( \left\lvert \frac{N_n(\eta)}{|\Lambda_n|} - p(\eta) \right\rvert \geq \delta \right) \leq e^{1/e} \exp \left( -\frac{c(d,L)|\Lambda_n|\delta^2}{(2\ell)^{2d-1}e} \right). \tag{4.2}
\]

The remainder of this section is devoted to show how this result can be obtained as a consequence of Corollary 4 of Dedecker (2001), [6]. We give this proof in detail since this shows at which extend Assumption 3.7 is needed.

**Proof.** For any \( i \), let

\[ Y_i = 1_{\{X_i = \eta\}}. \]

Then under \( \mu \), \( \{Y_i : i \in \mathbb{Z}^d\} \) is a stationary random field. The associated filtration is defined as follows. For any \( \Gamma \subset \mathbb{Z}^d \),

\[ G^\ell_{\Gamma} = \sigma\{Y_i, i \in \Gamma\}, \]

and define the \( \Phi \)-mixing coefficient

\[ \Phi(\Gamma_1, \Gamma_2) = \sup\{|\mu(B|\sigma_{\Gamma_1}) - \mu(B)|\sigma_{\Gamma_2}|, B \in G^\ell_{\Gamma_1}\}. \]

Moreover, let

\[ \Phi_{\infty,1}(n) = \sup\{\Phi(\Gamma_1, \Gamma_2) : |\Gamma_2| = 1, dist(\Gamma_1, \Gamma_2) \geq n\}, \tag{4.3} \]

where \( dist(\Gamma_1, \Gamma_2) = \min\{|j - i|, i \in \Gamma_1, j \in \Gamma_2\} \). Let

\[ \beta_\ell = 1 + \sum_{n \geq 1} \Phi_{\infty,1}(n)|\partial V_0(n)|. \tag{4.4} \]

The quantity \( \beta_\ell \) depends on \( \ell \) through the filtration \( \{G^\ell_{\Gamma}, \Gamma \subset \mathbb{Z}^d\} \). To avoid confusion we warn the reader that \( \beta_\ell \) defined in (4.4) is a different quantity from \( \beta(\ell) \) defined in (3.21), although related. Corollary 4 of Dedecker (2001), [6], implies the following exponential inequality

\[
\mu \left( \left\lvert \frac{N_n(\eta)}{|\Lambda_n|} - p(\eta) \right\rvert \geq \delta \right) \leq e^{1/e} \exp \left( -\frac{|\Lambda_n|\delta^2}{4\beta_\ell e} \right). \tag{4.5}
\]

We estimate \( \beta_\ell \) in Lemma 4.2 stated below. Then, defining \( c(d,L) = \frac{1}{C(d,L)} \), where \( C(d,L) \) is the constant of Lemma 4.2, we obtain (1.2).

Assumption 3.7 is essential for proving the following lemma.

**Lemma 4.2** Under Assumption 3.4 there exist constants \( c^* = c^*(L) \) and \( k = k(L) \) such that

\[ \Phi_{\infty,1}(n + 2\ell) \leq c^* |V_0^d(\ell)|e^{-kn}, \]

and for \( \beta_\ell \) defined in (4.4), we have

\[ \beta_\ell \leq C(d,L)(2\ell)^{2d-1} \tag{4.6} \]

where \( C(d,L) \) is a positive constant depending on the dimension \( d \) and on \( L \).
Therefore, we have
\[ \Phi_{\infty,1}(n + 2\ell) = \{ i \in \mathbb{Z}^d : d(i, \Gamma) \leq \ell \}. \]

We have that, whenever \(|\Gamma| > 1,
\[ \mathcal{G}_\Gamma^\ell = \sigma\{ \mathcal{Y}_i, i \in \Gamma \} \subset \sigma\{ \mathcal{X}_i, i \in \Gamma(\ell) \} = \mathcal{F}_{\Gamma(\ell)}. \]

When \(|\Gamma| = 1, assuming \( \Gamma = \{ i \},
\[ \mathcal{G}_\Gamma^\ell = \sigma\{ \mathcal{Y}_i \} \subset \sigma\{ \mathcal{X}_j, j \in \Gamma(\ell) \setminus \{ i \} \} = \sigma\{ \mathcal{X}_j, j \in V_0(\ell) \}. \]

By translational covariance, if it is sufficient to set \( \Gamma_2 = \{ 0 \}, |\Gamma_1| = \infty \) and \( \text{dist}(\Gamma_1, \Gamma_2) \geq n+2\ell, \) for \( n \geq 1. \) Now, take \( B = \{ X_0^\ell = \eta \} \) for some fixed \( \eta \in \mathcal{A}_V^{0(\ell)}. \) Since \( \mathcal{G}_1^\ell \subset \mathcal{F}_{V_0(n+\ell)^c} \) and \( \mu(B|\mathcal{G}_1^\ell) = \mu(B|\mathcal{F}_{V_0(n+\ell)^c})(\mathcal{G}_1^\ell), \) in order to bound \( \Phi_{\infty,1}^\ell(n + 2\ell), \) it is sufficient to bound
\[ ||\mu(B|\mathcal{G}_1^\ell) - \mu(B)||_\infty \leq ||\mu(B|\mathcal{F}_{V_0(n+\ell)^c}) - \mu(B)||_\infty. \]

But
\[ \mu(B) = \mu(B|\mathcal{F}_{V_0(n+\ell)^c}). \]

Hence, using the specification \( \gamma \) defined in (2.1) and (2.2), by definition (4.3) we have
\[ \Phi_{\infty,1}^\ell(n + 2\ell) \]
\[ \leq \sup_{\omega} \left\{ \int d\mu(\omega') \left[ \gamma_{V_0(n+\ell)}(B|\omega) - \gamma_{V_0(n+\ell)}(B|\omega') \right] \right\} \]
\[ \leq \sup_{\omega,\omega'} \left[ \gamma_{V_0(n+\ell)}(B|\omega) - \gamma_{V_0(n+\ell)}(B|\omega') \right] \]
\[ \leq \sup_{\omega(V_0^0(\ell)),\omega(V_0(n+\ell)^c),\omega'} \left[ \gamma_{V_0(n+\ell)}(V_0^0(\ell)|\omega) - \gamma_{V_0(n+\ell)}(V_0^0(\ell)|\omega'). \right]. \]

To control this last term Assumption 3.7 is essential. Indeed, we need to show that, uniformly on boundary conditions outside \( V_0(n+\ell), \) (4.7) is exponentially small in \( n. \)

Applying Theorem 3.1.3.2 of Presutti (2009), [26], we obtain the following. There exists a function \( u_{V_0(n+\ell)} : \mathbb{Z}^d \rightarrow \mathbb{R}_+ \) such that
\[ \sup_{\omega(V_0^0(\ell)),\omega(V_0(n+\ell)^c),\omega'} \left[ \gamma_{V_0(n+\ell)}(V_0^0(\ell)|\omega) - \gamma_{V_0(n+\ell)}(V_0^0(\ell)|\omega') \right] \]
\[ \leq \sum_{i \in V_0^0(\ell)} u_{V_0(n+\ell)}(i). \]

Moreover by Corollary 3.2.5.5. of Presutti (2009), [26], under (3.22), there exist \( c^* = c^*(L) \) and \( k = k(L) \) so that
\[ u_{V_0(n+\ell)}(i) \leq c^* e^{-kd(i, V_0(n+\ell)^c)}, i \in V_0^0(\ell). \]

Therefore, we have
\[ \Phi_{\infty,1}^\ell(n + 2\ell) \leq c^* e^{-kn} |V_0^0(\ell)|, \]
and thus
\[ \beta_\ell \leq |V_0^0(2\ell)| + \sum_{n \geq 2\ell+1} |\partial V_0(n)| \Phi_{\infty,1}^\ell(n) \]
\[ \leq (4\ell)^d + c^*(4\ell)^d \sum_{n \geq 2\ell+1} n^{d-1} e^{-k(n-2\ell)}. \]

Immediately one gets (4.6).
Remark 4.3 In Proposition 4.1 we obtain an exponential rate of convergence in the ergodic theorem. It is very likely that to our purposes polynomial or sub-exponential rates of convergence will be enough. This would allow to get the control for the probability of underestimation also in the regime of phase transition. This lies, however, outside the scope of the present paper.

4.2 Deviation inequalities

We are now able to state the deviation inequalities needed to control the probability of underestimation. They are consequences of Proposition 4.1 and follow ideas of Galves and Leonardi (2008), [17]. Before doing so, we define for any $a \in \mathcal{A}$, $\eta \in \mathcal{A}_{V_0}^{V_0}$,

$$p(a|\eta) = \frac{p((a, \eta))}{\mu(\{X_i = a, \forall i \in V_0^{V_0}(\ell)\})}.$$  \hspace{1cm} (4.11)

By Assumption 3.4 we have that for any given configuration $\eta \in \mathcal{A}_{V_0}^{V_0}$,

$$p(\eta) \geq q_{\min}^{(2L)^d},$$

and

$$p(a|\eta) \geq q_{\min}.$$  

We are interested in configurations having support in a ball of radius at most $L$. Hence, writing

$$\alpha_0 = \inf_{\ell \leq L} \inf_{a \in \mathcal{A}, \eta \in \mathcal{A}_{V_0}^{V_0}} \{p(a|\eta), p(\eta)\},$$  \hspace{1cm} (4.12)

we obtain that

$$\alpha_0 \geq q_{\min}^{(2L)^d}. \hspace{1cm} (4.13)$$

We define the following quantity

$$\Delta_n(\eta) = \sum_{a \in \mathcal{A}} \left( \frac{N_n(\eta, a)}{|\Lambda_n|} \log \hat{p}_n(a|\eta) - p((a, \eta)) \log p(a|\eta) \right),$$  \hspace{1cm} (4.14)

where $\hat{p}_n(a|\eta)$ is the quantity defined in (3.10). We obtain the following deviation inequalities.

Corollary 4.4 Let $\mu$ be a translation covariant Variable-neighborhood random field for which Assumption 3.4 and Assumption 3.7 hold. Let $t > 0$, $\ell \leq L$ where $L$ is given in (3.22), let $\eta \in \mathcal{A}_{V_0}^{V_0}$, $\hat{p}_n(\cdot|\eta)$ defined in (3.10), $p(\cdot|\eta)$ in (4.11) and let $\Delta_n(\eta)$ as defined in (4.14). Then there exists a constant $C(d, L)$ depending only on dimension and on $L$ such that

$$\mu(|\hat{p}_n(a|\eta) - p(a|\eta)| > t) \leq 2e^{1/e} \exp\left(-C(d, L)\frac{|\Lambda_n|t^2\alpha_0}{4e}\right), \hspace{1cm} \forall a \in \mathcal{A}, \hspace{1cm} (4.15)$$

$$\mu(|\Delta_n(\eta)| > t) \leq 3|\mathcal{A}|e^{1/e} \exp\left(-C(d, L)\frac{|\Lambda_n|(t \wedge t^2)\alpha_0^2}{8|\mathcal{A}|^2(\log^2\alpha_0 \lor 1)e}\right), \hspace{1cm} (4.16)$$

where $\alpha_0$ is given in (4.12) and estimated in (4.13).\hspace{1cm}
Proof. Concerning (4.15) we obtain by inserting and subtracting the term $\frac{N_n(\eta, a)}{|\Lambda_n| p(\eta)}$: 

$$|\tilde{p}_n(a|\eta) - p(a|\eta)| \leq \frac{|N_n(\eta, a) - N_n(\eta, a)|}{N_n(\eta)} \left| - \frac{N_n(\eta, a)}{|\Lambda_n| p(\eta)} \right| + \frac{1}{p(\eta)} \left( \frac{N_n(\eta, a)}{|\Lambda_n|} - p((a, \eta)) \right|.$$ 

The first term in the last expression can be upper bounded by 

$$\frac{N_n(\eta, a)}{N_n(\eta)} \left| \frac{N_n(\eta, a)}{|\Lambda_n| p(\eta)} \right| = N_n(\eta, a) \left| \frac{\Lambda_n p(\eta) - N_n(\eta)}{N_n(\eta)} \right| \frac{\Lambda_n |p(\eta)|}{N_n(\eta)}.$$ 

As a consequence we obtain that 

$$\mu (|\tilde{p}_n(a|\eta) - p(a|\eta)| > t) \leq \mu \left( \left| p(\eta) - \frac{N_n(\eta, a)}{|\Lambda_n|} \right| > \frac{t}{2} p(\eta) \right) + \mu \left( \left| \frac{N_n(\eta, a)}{|\Lambda_n|} - p((\eta, a)) \right| > \frac{t}{2} p(\eta) \right).$$ 

Then, applying (4.12), we get 

$$\mu (|\tilde{p}_n(a|\eta) - p(a|\eta)| > t) \leq 2 e^\frac{t}{4} \exp \left( - \frac{c(d, L) |\Lambda_n| t^2 p(\eta)^2}{4(2L)^{2d-1} \alpha_0} \right) \leq 2 e^\frac{t}{4} \exp \left( - \frac{c(d, L) |\Lambda_n| t^2 p(\eta)^2}{4(2L)^{2d-1} \alpha_0} \right).$$ 

Hence, writing $C(d, L) = c(d, L)/(2L)^{2d-1}$, where $c(d, L)$ is the constant of (4.12), assertion (4.15) follows. 

To show (4.16) we subtract and add the term $\frac{N_n(\eta, a)}{|\Lambda_n|} \log p(a|\eta)$ to $\Delta_n(\eta)$. We obtain 

$$\Delta_n(\eta) = \sum_{a \in A} \frac{N_n(\eta, a)}{|\Lambda_n|} \log \frac{\tilde{p}_n(a|\eta)}{p(a|\eta)} + \sum_{a \in A} \left( \frac{N_n(\eta, a)}{|\Lambda_n|} - p((\eta, a)) \right) \log p(a|\eta) = \Delta_n^1(\eta) + \Delta_n^2(\eta).$$ 

We rewrite $\Delta_n^1(\eta)$ in the following way and then apply the estimate (6.4): 

$$\Delta_n^1(\eta) = \frac{N_n(\eta)}{|\Lambda_n|} \sum_{a \in A} \tilde{p}_n(a|\eta) \log \frac{\tilde{p}_n(a|\eta)}{p(a|\eta)} \leq \frac{N_n(\eta)}{|\Lambda_n|} \sum_{a \in A} \frac{(\tilde{p}_n(a|\eta) - p(a|\eta))^2}{p(a|\eta)} \leq \sum_{a \in A} \frac{(\tilde{p}_n(a|\eta) - p(a|\eta))^2}{p(a|\eta)} \leq \sum_{a \in A} \frac{(\tilde{p}_n(a|\eta) - p(a|\eta))^2}{\alpha_0}.$$
Therefore
\[
\mu \left( |\Delta^1_n(\eta)| > \frac{t}{2} \right) \\
\leq \sum_{a \in \mathcal{A}} \mu \left( (\tilde{p}_n(a|\eta) - p(a|\eta))^2 > \frac{1}{|\mathcal{A}|^2} \frac{t}{\alpha_0} \right) \\
\leq 2|\mathcal{A}| e^{1/e} \exp \left( -C(d, L) \frac{|\Lambda_n| t \alpha_0^2}{8|\mathcal{A}| e} \right),
\] (4.17)
by (4.15). We get for the second term
\[
\mu \left( |\Delta^2_n(\eta)| > \frac{t}{2} \right) \\
\leq \sum_{a \in \mathcal{A}} \mu \left( \left| \frac{N_n(\eta, a)}{|\Lambda_n|} - p(|\eta, a|) \right| > \frac{1}{|\mathcal{A}|^2} \frac{t}{\log \alpha_0} \right) \\
\leq |\mathcal{A}| e^{1/e} \exp \left( -C(d, L) \frac{|\Lambda_n| t^2}{4|\mathcal{A}|^2 \log^2 \alpha_0 e} \right),
\] (4.18)
by (4.12). This finishes the proof.

5 Deviation inequalities for overestimation

In order to control the probability of overestimation we do not need as strong assumptions as for the control of the probability of underestimation. Indeed, we can avoid to impose Assumption 3.7. We mimic the method used by Csiszár and Talata (2006), see Proposition 3.1 and Lemma 3.3 of their paper. Their results are typicality results and they obtain the almost sure convergence of the empirical probabilities to the theoretical ones. We follow the way indicated by Csiszár and Talata (2006), but we quantify the errors and obtain in this way precise deviation inequalities. We will need only Assumption 3.4.

We partition the region \( \Lambda_n \) by intersecting it with a sub lattice of \( \mathbb{Z}^d \) such that the distance between sites in the sub lattice is \( 4R_n + 1 \). More precisely, let
\[
\Lambda^k_n = \{ j \in \Lambda_n, j = k + (4R_n + 1)l, l \in \mathbb{Z}^d \}, \quad \|k\| \leq 2R_n.
\]
For any \( \ell \leq R_n \) and any fixed configuration \( \eta \in A_{\mathcal{V}_0}^{(\ell)} \), let
\[
N^k_n(\eta) = \sum_{j \in \Lambda^k_n} 1_{\{X^\ell_j = \eta\}}
\]
be the number of occurrences of \( \eta \) in the sample having center in \( \Lambda^k_n \). In the same way we denote
\[
N^k_n(\eta, a) = \sum_{j \in \Lambda^k_n} 1_{\{X^\ell_j = \eta, X_j = a\}}.
\]
Note that we have
\[
N_n(\eta) = \sum_{k: \|k\| \leq 2R_n} N^k_n(\eta), \quad N_n(\eta, a) = \sum_{k: \|k\| \leq 2R_n} N^k_n(\eta, a).
\]
Let
\[
\mathcal{A}(n, \ell, k) = \left\{ \frac{3}{2} \log N^k_n(\eta) \geq \log |\Lambda_n|, \text{ for all } \eta \in A_{\mathcal{V}_0}^{(\ell)} \text{ s.t. } \ell \geq l_0(\eta) \right\}
\] (5.1)
and
\[ \mathcal{B}(n, \ell) = \bigcap_{k: ||k|| \leq 2R_n} \mathcal{A}(n, \ell, k). \] (5.2)

The probabilities \( \mu(\mathcal{A}(n, \ell, k)) \) and \( \mu(\mathcal{B}(n, \ell)) \) can be immediately obtained by Lemma 5.5 given at the end of this section. Recall the definition of \( \bar{p}_n \) in (3.9).

**Theorem 5.1** For any 
\[ \delta > 2^d \log |A| \frac{3e}{4q_{\min}}, \] (5.3)
there exist a positive constant \( c(\delta) = c(\delta, q_{\min}) \) and \( n_0 \) (not depending on \( q_{\min} \) nor on \( \delta \)) such that for all \( n \geq n_0 \), for any \( \ell \leq R_n \),
\[ \mu \left[ \exists \eta \in A_{\text{v}}^{\ell}(\ell), \ell \geq l_0(\eta) : |\bar{p}_n(a|\eta) - \gamma_{\{0\}}(a|\eta)| > \sqrt{\kappa(\delta)\gamma_{\{0\}}(a|\eta) \frac{\log N_n(\eta)}{N_n(\eta)}} \right] \]
\[ \leq 4 (4R_n + 1)^d \exp \left(-c(\delta) \sqrt{\log |A_n|} \right), \] (5.4)
where \( \kappa(\delta) > 0 \) is as in (3.18).

The main ingredient to prove Theorem 5.1 is the following lemma.

**Lemma 5.2** For any \( \delta \) as in (5.3) there exist \( n_0 \) (not depending on \( q_{\min} \) nor on \( \delta \)) and a positive constant \( c(\delta) = c(\delta, q_{\min}) \), such that for all \( n \geq n_0 \), for any \( \ell \leq R_n \),
\[ \mu \left[ \exists \eta \in A_{\text{v}}^{\ell}(\ell), \ell \geq l_0(\eta) : \frac{|N_n^k(\eta, a) - N_n^k(\eta)|}{N_n^k(\eta)} \geq \sqrt{\delta \gamma_{\{0\}}(a|\eta) \frac{\log N_n^k(\eta)}{N_n^k(\eta)}} \right] \]
\[ \leq 4 \exp \left(-c(\delta) \sqrt{\log |A_n|} \right). \] (5.5)

**Proof.** Fix \( \eta \in A_{\text{v}}^{\ell}(\ell) \) with \( \ell \geq l_0(\eta) \) and set \( \gamma(a) = \gamma_{\{0\}}(a|\eta) \). Recall that \( \gamma(a) \geq q_{\min} \). We first provide an upper bound for fixed \( \eta \) of
\[ \mu \left[ |N_n^k(\eta, a) - N_n^k(\eta)\gamma(a)| \geq \sqrt{\delta \gamma(a) N_n^k(\eta)(\log N_n^k(\eta))^{1/2}}, \mathcal{A}(n, \ell, k) \right]. \]

By definition
\[ N_n^k(\eta, a) - N_n^k(\eta)\gamma_{\{0\}}(a|\eta) = \sum_{j \in \Lambda_n^k} 1_{\{X_j = \eta\}} \left[ 1_{\{X_j = a\}} - \gamma_{\{0\}}(a|\eta) \right]. \] (5.6)

We order in some arbitrary way the points
\[ \{j \in \Lambda_n^k, X_j^\ell = \eta\} = \{j_l, 1 \leq l \leq N_n^k(\eta)\}. \]
Define 
\[ Z_l = \left[ 1_{\{X_l = a\}} - \gamma(0)(a|\eta) \right], \quad l = 1, \ldots, N_n^k(\eta). \]
The random variables \{Z_l, \ l = 1, \ldots, N_n^k(\eta)\} are identically distributed random variables with mean zero and conditionally independent, i.e. for \( i \neq j, \ 0 \leq |z_i| \leq 1, \ 0 \leq |z_j| \leq 1 \)
\[
\mu \left[ Z_i = z_i, Z_j = z_j | \omega(\tilde{\Lambda}_n \setminus \cup_j \in \Lambda_n^k V_j(\ell)) \right] = \mu \left[ Z_i = z_i | \omega(\tilde{\Lambda}_n \setminus \cup_j \in \Lambda_n^k V_j(\ell)) \right] \\
\cdot \mu \left[ Z_j = z_j | \omega(\tilde{\Lambda}_n \setminus \cup_j \in \Lambda_n^k V_j(\ell)) \right].
\]
Take an independent copy \( \{Z_i', i \geq 1\} \) of i.i.d. random variables, having the same distribution as \( Z_1 \), independent of \( X \). Then for \( i > N_n^k(\eta) \) we let \( Z_i = Z_i'_{N_n^k(\eta)} \). The important point of this definition is that in this way, the sequence of random variables \( Z_1, Z_2, \ldots \) is independent of \( N_n^k(\eta) \). Define partial sums
\[
S_N = \sum_{j=1}^{N} Z_j, \quad S_N^* = \max\{S_j; j \leq N\}.
\]
These are still independent of \( N_n^k(\eta) \). We write the quantity in (5.6) as
\[
N_n^k(\eta, a) - N_n^k(\eta)\gamma(0)(a|\eta) = S_{N_n^k(\eta)}^* \leq S_{N_n^k(\eta)}^{\leq e}(\eta).
\]
We now use arguments similar to those in the proof of Lemma 3.3 of Csiszár and Talata (2006), [4]. In the following,
\[
\tilde{\mu} = \mu(\cdot | \omega(\tilde{\Lambda}_n \setminus \cup_j \in \Lambda_n^k V_j(\ell)))
\]
denotes always conditional probability when conditioning with respect to \( \omega(\tilde{\Lambda}_n \setminus \cup_j \in \Lambda_n^k V_j(\ell)) \). Then,
\[
\tilde{\mu} \left[ S_{N_n^k(\eta)}^{\leq e}(\eta) \geq \sqrt{\delta \gamma(a)N_n^k(\eta)(\log N_n^k(\eta))^{1/2}}, \mathcal{A}(n, \ell, k) \right] \leq
\]
\[
\sum_{j \in \mathbb{N}} \tilde{\mu} \left[ S_{N_n^k(\eta)}^{\leq e}(\eta) \geq \sqrt{\delta \gamma(a)N_n^k(\eta)(\log N_n^k(\eta))^{1/2}}, \mathcal{A}(n, \ell, k) \right].
\]
Note that on \( \mathcal{A}(n, \ell, k) \cap \{e^j < N_n^k(\eta) \leq e^{j+1}\} \), see (5.1), since \( \log N_n^k(\eta) \leq \log |\tilde{\Lambda}_n| \),
\[
j < \log |\tilde{\Lambda}_n| \leq \frac{3}{2}(j + 1).
\]
Hence by independence of \( \{S_{N_n^k}^*, N \geq 1\} \) and \( N_n^k(\eta) \), the last expression of (5.8) can be bounded from above as follows.
\[
\sum_{j: j < \log |\tilde{\Lambda}_n| \leq \frac{3}{2}(j + 1)} \tilde{\mu} \left[ S_{e^j+1}^* \geq \sqrt{\delta \gamma(a)e^j \sqrt{j}} \right] \leq \sum_{j: \log |\tilde{\Lambda}_n| \leq \frac{3}{2}(j + 1)} \tilde{\mu} \left[ S_{e^j+1}^* \geq \sqrt{\delta \gamma(a)e^j \sqrt{j}} \right].
\]
(5.9)
Now, Bernstein’s inequality, see Lemma 9.2 yields
\[
\tilde{\mu} [S_N^* \geq c] \leq 2 \exp \left( -\frac{2e^2}{N} \right).
\]
This gives
\[
\tilde{\mu} \left[ S_{e^j+1}^* \geq \sqrt{\delta \gamma(a)e^j \sqrt{j}} \right] \leq 2 \exp \left( -\frac{2\log_{\min} e}{e} \delta \sqrt{j} \right).
\]
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Taking into account that
\[
\int_{\sqrt{\alpha}}^{\infty} e^{-by} dy = \frac{1}{b} e^{-b\sqrt{\alpha}} \sqrt{a} + \frac{1}{b^2} e^{-b\sqrt{\alpha}},
\]
setting \( b = 2q_{min}\delta/e \) and \( a = \frac{2}{3} \log |\Lambda_n| - 1 \), one can upper bound the sum over \( j \) in (5.9) obtaining
\[
\tilde{\mu} \left[ S^*_{N^k_B(\eta)} \geq \sqrt{\frac{\delta \gamma(a) N^k_B(\eta)}{N^k_B(\eta)}} \left( \log N^k_B(\eta) \right)^{1/2}, \mathcal{A}(n, \ell, k) \right]
\]
\[
\leq 2e^{3 \log |\Lambda_n| - 1} \frac{e}{2 \delta q_{min}} \exp \left( \frac{2q_{min}\delta}{e} \sqrt{\frac{1}{3} \log |\Lambda_n| - 1} \right)
\]
\[
\leq 4 \left( \sqrt{\frac{2}{3} \log |\Lambda_n| - 1} + 1 \right) \exp \left( -\frac{2q_{min}\delta}{e} \sqrt{\frac{2}{3} \log |\Lambda_n| - 1} \right),
\]
since by the choice of \( \delta \) in (5.3), \( \frac{e}{2 \delta q_{min}} \leq 1 \).

Now, there exists \( n_0 \) (not depending on \( q_{min} \) nor on \( \delta \)) such that for all \( n \geq n_0 \), this last upper bound can be replaced by
\[
\left( \sqrt{\frac{2}{3} \log |\Lambda_n| - 1} + 1 \right) \exp \left( -\frac{2q_{min}\delta}{e} \sqrt{\frac{2}{3} \log |\Lambda_n| - 1} \right) \leq \exp \left( -\frac{2q_{min}\delta}{e} \sqrt{\log |\Lambda_n|} \right).
\]
This upper bound also holds for the non-conditioned probability \( \mu \). Finally, in order to get the result uniformly over all possible configurations \( \eta \) having \( l_0(\eta) \leq \ell \), we need to sum over all possible choices of patterns \( \eta \). This gives, by definition of \( R_n \),
\[
|\mathcal{A}|^{V_0^0(\ell)} = |\mathcal{A}|^{(2\ell)^d} \leq |\mathcal{A}|^{(2R_n)^d} = e^{2d \log |\mathcal{A}| \sqrt{\log |\Lambda_n|}}
\]
terms. Thus we can conclude that for all \( n \geq n_0 \), taking \( \delta \) as in (5.3) we have
\[
\mu \left[ \exists \eta \in \mathcal{A}^{V_0^0(\ell)}, \ell \geq l_0(\eta) : \left| \frac{N^k_B(\eta, a)}{N^k_B(\eta)} - \gamma_{\{0\}}(a|\eta) \right| \geq \frac{\sqrt{\delta \gamma_{\{0\}}(a|\eta) \left( \log N^k_B(\eta) \right)^{1/2}}}{N^k_B(\eta)}, \mathcal{A}(n, \ell, k) \right]
\]
\[
\leq 4 e^{2d \log |\mathcal{A}| \sqrt{\log |\Lambda_n|}} \exp \left( -\frac{2q_{min}\delta}{e} \sqrt{\log |\Lambda_n|} \right)
\]
\[
= 4 \exp \left( -c(\delta) \sqrt{\log |\Lambda_n|} \right),
\]
where \( c(\delta) = \frac{2q_{min}\delta}{e} - 2d \log |\mathcal{A}| > 0 \). This concludes the proof.

We are now able to give the proof of Theorem 5.1.

**Proof of Theorem 5.1** Fix \( \eta \in \mathcal{A}^{V_0^0(\ell)} \) with \( \ell \geq l_0(\eta) \), let \( \gamma(a) = \gamma_{\{0\}}(a|\eta) \), \( \delta \) as in (5.3) and denote by
\[
E_n(\eta) = \bigcap_{k:|k|\leq 2R_n} \left\{ \left| \frac{N^k_B(\eta, a)}{N^k_B(\eta)} - \gamma(a) \right| \leq \sqrt{\frac{\delta \gamma(a) N^k_B(\eta)}{N^k_B(\eta)}} \right\}.
\]
Then on $E_n(\eta)$, using Jensen’s inequality, the definition of $R_n$ and $N_n^k(\eta) \leq N_n(\eta)$,

$$
\left| \hat{p}_n(a|\eta) - \gamma_0(a|\eta) \right| \\
\leq \sum_{k:||k|| \leq 2R_n} \frac{N_n^k(\eta, a)}{N_n^k(\eta)} - \gamma_0(a|\eta) \right| \cdot \frac{N_n^k(\eta)}{N_n(\eta)} \\
\leq \sum_{k:||k|| \leq 2R_n} \sqrt{\delta \gamma_0(a|\eta) \frac{\log N_n^k(\eta)}{N_n^k(\eta)} \cdot \frac{N_n^k(\eta)}{N_n(\eta)}} \\
\leq \sqrt{\sum_{k:||k|| \leq 2R_n} \delta \gamma_0(a|\eta) \frac{\log N_n^k(\eta)}{N_n(\eta)}} \\
\leq \frac{(4R_n + 1)^{d/2} \delta^{1/2} \gamma_0(a|\eta)^{1/2} [\log N_n(\eta)]^{1/4}}{[N_n(\eta)]^{1/2}} \\
\leq 5^{d/2} (\log |\bar{A}_n|)^{3/2} \delta^{1/2} \gamma_0(a|\eta)^{1/2} [\log N_n(\eta)]^{1/4} [N_n(\eta)]^{1/2}. \\
(5.10)
$$

On $\{ \log |\bar{A}_n| \leq \frac{3}{2} \log N_n(\eta) \}$, this last expression can be bounded from above by

$$
5^{d/2} (\frac{3}{2})^{1/4} \sqrt{\delta \gamma_0(a|\eta) \frac{\log N_n(\eta)}{N_n(\eta)}} = \sqrt{\kappa(\delta) \gamma_0(a|\eta) \frac{\log N_n(\eta)}{N_n(\eta)}},
$$

where $\kappa(\delta)$ is chosen as in (3.18). Hence we get

$$
\mu \left[ \exists \eta \in \mathcal{A}_n^{\gamma_0}(\ell), \ell \geq l_0(\eta) : |\hat{p}_n(a|\eta) - \gamma_0(a|\eta)| > \sqrt{\kappa(\delta) \gamma_0(a|\eta) \frac{\log N_n(\eta)}{N_n(\eta)}}, \mathcal{B}(n, \ell) \right] \\
\leq \mu \left[ \bigcup_{\eta \in \mathcal{A}_n^{\gamma_0}(\ell), \ell \geq l_0(\eta)} E_n(\eta)^c, \mathcal{B}(n, \ell) \right]. \\
(5.11)
$$

But

$$
\bigcup_{\eta \in \mathcal{A}_n^{\gamma_0}(\ell), \ell \geq l_0(\eta)} E_n(\eta)^c \\
= \bigcup_{k:||k|| \leq 2R_n} \bigcup_{\eta \in \mathcal{A}_n^{\gamma_0}(\ell), \ell \geq l_0(\eta)} \left\{ |N_n^k(\eta, a) - \gamma(a)| > \sqrt{\delta \gamma(a) \frac{\log N_n^k(\eta)}{N_n^k(\eta)}} \right\},
$$

therefore applying Lemma 5.2 we can finally upper bound

$$
\mu \left[ \bigcup_{\eta, \ell \geq l_0(\eta)} E_n(\eta)^c, \mathcal{B}(n, \ell) \right] \leq 4(4R_n + 1)^d \exp \left( -c(\delta) \sqrt{\log |\bar{A}_n|} \right),
$$

for all $n \geq n_0$. This finishes the proof.

The following lemma gives conditions ensuring that $\mu(\mathcal{B}(n, \ell)^c)$ converges to 0 by giving the precise rate of convergence.
Lemma 5.3 For any $0 < \epsilon_1 < 1$, $0 < \epsilon_2 < 1$, and for any positive $C_1$ and $C_2$ there exists $n_0 = n_0(q_{\text{min}}, \min(\epsilon_1, \epsilon_2), \min(C_1, C_2))$ so that for $n \geq n_0$ and for any $\ell \leq R_n$, we have

$$
\mu \left( \exists \eta \in A^{V_0^\ell} \colon \ell \geq l_0(\eta) : N_n^k(\eta) < C_1|\Lambda_n|^{1-\epsilon_1} \right) \leq \exp \left(-C_2|\Lambda_n|^{1-\epsilon_2} \right).
$$

(5.12)

Proof. Fix some $\eta$ with $l_0(\eta) \leq \ell \leq R_n$. Then $\{\eta(X_\ell^j) \in \Lambda_n^k\}$ is a collection of conditional independent random variables, conditioned on fixing the configuration $\omega(\Lambda_n \cup j \in \Lambda_n V_j(\ell))$. By Assumption 3.3 we have that

$$
\mu(X_\ell^j = \eta) \geq q^{(2\ell)d}_{\text{min}}.
$$

Here we have used that $|V_0^\ell(\ell)| = (2\ell)^d$. Then a conditional version of the Hoeffding inequality, see for example Lemma A3 in Csisz`{a}r and Talata (2006), [4], yields

$$
\mu \left[ \frac{N_n^k(\eta)}{|\Lambda_n^k|} < \frac{1}{2} q^{(2\ell)d}_{\text{min}} \omega(\Lambda_n \cup j \in \Lambda_n V_j(\ell)) \right] \leq e^{-|\Lambda_n^k|^{(2\ell)^d} q^{(2\ell)d}_{\text{min}}}. \tag{5.13}
$$

As a consequence, we obtain also for the unconditioned probability,

$$
\mu \left[ \frac{N_n^k(\eta)}{|\Lambda_n^k|} < \frac{1}{2} q^{(2\ell)d}_{\text{min}} \right] \leq e^{-|\Lambda_n^k|^{(2\ell)^d} q^{(2\ell)d}_{\text{min}}}, \tag{5.14}
$$

and thus

$$
\mu \left[ \exists \eta \in A^{V_0^\ell}, \ell \geq l_0(\eta) : \frac{N_n^k(\eta)}{|\Lambda_n^k|} < \frac{1}{2} q^{(2\ell)d}_{\text{min}} \right] \leq |A|^{(2R_n)^d} e^{-|\Lambda_n^k|^{(2\ell)^d} q^{(2\ell)d}_{\text{min}}}. \tag{5.15}
$$

To obtain (5.12) we need to compare $|\Lambda_n|$ to $|\Lambda_n^k|$. By construction we have for $n$ sufficiently large,

$$
|\Lambda_n^k| \geq \frac{|\Lambda_n|}{(4R_n + 1)^d} \geq \frac{|\Lambda_n|}{(5R_n)^d}. \tag{5.16}
$$

This and (5.15) imply that

$$
\mu \left[ \exists \eta \in A^{V_0^\ell}, \ell \geq l_0(\eta) : N_n^k(\eta) < \frac{1}{2} q^{(2\ell)d}_{\text{min}} \frac{|\Lambda_n|}{(5R_n)^d} \right] \leq |A|^{(2R_n)^d} e^{-|\Lambda_n|^{(2\ell)^d} q^{(2\ell)d}_{\text{min}}}. \tag{5.17}
$$

But

$$
q^{(2\ell)d}_{\text{min}} \frac{|\Lambda_n|}{(5R_n)^d} \geq |\Lambda_n|^{q^{(2R_n)^d}_{\text{min}} (5R_n)^d}. \tag{5.18}
$$

By the definition of $R_n$ in (3.15), $P_n^d = \sqrt{\log |\Lambda_n|}$. Thus for any $C > 0$ and for any $\epsilon > 0$ there exists $n_0 = n_0(q_{\text{min}}, \epsilon, C)$ so that for $n \geq n_0$,

$$
|\Lambda_n|^{q_{\text{min}}^{(2R_n)^d} (5R_n)^d} = |\Lambda_n| e^{2\epsilon \sqrt{\log |\Lambda_n|} \log q_{\text{min}}} \geq C.
$$

This and (5.17) imply that for any $\epsilon_1 > 0$ and $\epsilon_2 > 0$, positive $C_1$ and $C_2$, for $n \geq n_0$, we have

$$
\mu \left[ \exists \eta \in A^{V_0^\ell}, \ell \geq l_0(\eta) : N_n(\eta) < C_1|\Lambda_n|^{1-\epsilon_1} \right] \leq |A|^{(2R_n)^d} e^{-2C_2|\Lambda_n|^{1-\epsilon_2}}. \tag{5.19}
$$

Finally, note that for $n \geq n_0$,

$$
|A|^{(2R_n)^d} = e^{2\epsilon \log |A| \sqrt{\log |\Lambda_n|}} \leq e^{C_2|\Lambda_n|^{1-\epsilon_2}}.
$$

Thus we have proved the lemma.
6 Proof of Theorem 3.5

We show the probability of overestimation (3.20). Recall the definition of the set $\mathcal{B}(n, R_n)$ given in (5.2). Clearly,

\[
\mu(\exists i \in \tilde{\Lambda}_n : \hat{l}_n(i) > l_i(\sigma)) \leq \mu(\mathcal{B}(n, R_n)^c) + \mu(\exists i \in \tilde{\Lambda}_n : \hat{l}_n(i) > l_i(\sigma), \mathcal{B}(n, R_n)).
\]  

(6.1)

The first term is estimated by Lemma 5.3 choosing $\epsilon_1 = \frac{1}{3}, \epsilon_2 = \epsilon, C_1 = 1, C_2 = 2$. This yields

\[
\mu((\mathcal{B}(n, R_n))^c) \leq (4R_n + 1)^d e^{-2|\tilde{\Lambda}_n|^{1-\epsilon}},
\]

for all $n \geq n_0$ where $n_0$ depends on the choices $\epsilon_1 = \frac{1}{3}, \epsilon_2 = \epsilon, C_1 = 1, C_2 = 2$ and $q_{\text{min}}$. Since

\[(4R_n + 1)^d \leq C(d)\sqrt{\log |\tilde{\Lambda}_n|} \leq C(d)e^{|\tilde{\Lambda}_n|^{1-\epsilon}},\]

eventually, we have that for all $n \geq n_0$

\[
\mu((\mathcal{B}(n, R_n))^c) \leq C(d)e^{-|\tilde{\Lambda}_n|^{1-\epsilon}}.
\]  

(6.2)

We now study the last term of (6.1). We are interested in the event $\{\hat{l}_n(i) = \ell > l_i(\sigma)\}$. Note that $\ell > l_i(\sigma)$ implies that for any $j$ such that $X_{\ell}^{i-1} = \sigma_{i}^{\ell-1}$, necessarily $l_j(\sigma) \leq \ell - 1$ and as a consequence $\gamma_j(X_{\ell}^{i-1}) = \gamma_i(\sigma_{i}^{\ell-1})$.

Hence, for any $\ell > l_i(\sigma)$, we have, by (3.14)

\[
\log L_n(i, \ell) = \sum_{j: X_j^{\ell-1} = \sigma_{i}^{\ell-1}} \frac{1}{N_n(X_j^{\ell})} \left[ \log MPL_n(j, \ell) - \log MPL_n(i, \ell - 1) \right]
\]

\[
\leq \sum_{j: X_j^{\ell-1} = \sigma_{i}^{\ell-1}} \frac{1}{N_n(X_j^{\ell})} \left[ \log MPL_n(j, \ell) - \log MPL_n(i, \ell - 1) \right]
\]

\[
+ \sum_{j: X_j^{\ell-1} = \sigma_{i}^{\ell-1}} \left( \frac{\hat{p}_n(a|X_j^{\ell})}{\gamma_i(a|\sigma_{i}^{\ell-1})} \right)
\]

\[
= \sum_{j: X_j^{\ell-1} = \sigma_{i}^{\ell-1}} \left( \frac{\hat{p}_n(a|X_j^{\ell})}{\gamma_i(a|\sigma_{i}^{\ell-1})} \right)
\]

\[
\leq \sum_{j: X_j^{\ell-1} = \sigma_{i}^{\ell-1}} \left( \frac{\hat{p}_n(a|X_j^{\ell}) - \gamma_i(a|\sigma_{i}^{\ell-1})}{\gamma_i(a|\sigma_{i}^{\ell-1})} \right)^2
\]

\[
= \sum_{j: X_j^{\ell-1} = \sigma_{i}^{\ell-1}} \left( \frac{\hat{p}_n(a|X_j^{\ell}) - \gamma_j(a|c_j(\sigma))}{\gamma_j(a|c_j(\sigma))} \right)^2.
\]  

(6.3)

We used that for any two probability distributions $P$ and $Q$ on $A$,

\[
\sum_a P(a) \log \frac{P(a)}{Q(a)} \leq \sum_a \frac{(P(a) - Q(a))^2}{Q(a)}
\]  

(6.4)
(see Csiszár and Talata [5]), and in the last line the fact that \( \{ X_j^{\ell-1} = \sigma_i^{\ell-1}, \ell > l_i(\sigma) \} \) implies \( \gamma_j(a|c_j(\sigma)) = \gamma_i(a|\sigma_i^{\ell-1}) \). Hence, writing for short \( \gamma_j(\cdot) = \gamma_j(\cdot|c_j(\sigma)) \), define

\[
E_\ell = \left\{ j \in \Lambda_n, j \not< l, \forall a \in A : |\hat{\rho}_n(a|\sigma_j^\ell) - \gamma_j(a)| \leq \sqrt{\kappa(\delta)\gamma_j(a)\log N_n(\sigma_j^\ell) / N_n(\sigma_j^\ell)} \right\},
\]

where \( \delta \) is as in (6.3) and \( \kappa(\delta) \) is defined in (6.18). Then on \( E_\ell \), (6.3) can be bounded uniformly in \( i \in \Lambda_n \) from above by

\[
\sum_{j : X_j^{\ell-1} = \sigma_i^{\ell-1}} \sum_{a \in A} \kappa(\delta) \frac{\log N_n(X_j^\ell)}{N_n(X_j^\ell)} = \sum_{\nu \in A^{\gamma_0(\ell)}} \sum_{a \in A} \kappa(\delta) \frac{\log N_n(\sigma_i^{\ell-1} \nu)}{N_n(\sigma_i^{\ell-1} \nu)} \leq \kappa(\delta)|A| |A|^{|\gamma_0(\ell)|} \log |\Lambda_n|.
\]

Hence, on \( \bigcap_{\ell=1}^{R_n} E_\ell \), for all \( i \in \Lambda_n \) : We have for all \( \ell > l_i(\sigma) \),

\[
\log L_n(i, \ell) \leq \kappa(\delta)|A||A|^{|\gamma_0(\ell)|} \log |\Lambda_n| = \text{pen}(\ell, n).
\]

This implies that \( \tilde{l}_n(i) \leq l_i(\sigma) \) by definition of the estimator. Thus

\[
\mu(\exists i \in \Lambda_n : \tilde{l}_n(i) > l_i(\sigma), B(n, R_n)) \leq \sum_{\ell=1}^{R_n} \mu(E_\ell^c, B(n, R_n)).
\]

But

\[
E_\ell^c \subset \left\{ \exists a \in A, \exists \eta \in A^{\gamma_0(\ell)} : l_0(\eta) \leq \ell, |\hat{\rho}_n(a|\eta) - \gamma_0(a|\eta)| \geq \sqrt{\kappa(\delta)\gamma_0(a|\eta)\log N_n(\eta) / N_n(\eta)} \right\}.
\]

Hence by Theorem 5.1 for \( n \geq n_0 \), we have

\[
\sum_{\ell=1}^{R_n} \mu(E_\ell^c, B(n, R_n)) \leq |A|C(d)R_n^{d+1} \exp \left(-c(\ell)\sqrt{\log |\Lambda_n|} \right). \tag{6.5}
\]

By definition of \( R_n \),

\[
R_n^{d+1} \leq (\log |\Lambda_n|)^{d+\alpha}. \tag{6.6}
\]

Taking into account (6.1), (6.2), (6.5) and (6.6) we get (3.20). This finishes the proof of Theorem 3.5.

7 Proof of Theorem 3.9

We now turn to the problem of underestimation. We suppose that \( n_0 \) is sufficiently large such that \( R_n \geq L \). Fix \( i \in \Lambda_n \) and suppose that \( \tilde{l}_n(i) < l_i(\sigma) \). Since \( l_i(\sigma) \leq L \leq R_n \), this implies by definition of the estimator that for \( \ell = l_i(\sigma) \),

\[
\log L_n(i, \ell) \leq \text{pen}(\ell, n). \tag{7.1}
\]
Recall that by (3.14),

$$\log L_n(i, \ell) = \left[ \sum_{j: X_j^{\ell-1} = \sigma_{i-1}^{\ell-1}} \frac{1}{N_n(X_j^{\ell})} \log MPL_n(j, \ell) \right] - \log MPL_n(i, \ell - 1).$$

By definition of $\Delta_n(\eta)$ in (4.14) we can write

$$\frac{1}{|\Lambda_n|} \log L_n(i, \ell) = \left( \sum_{j: X_j^{\ell-1} = \sigma_{i-1}^{\ell-1}} \frac{1}{N_n(X_j^{\ell})} \Delta_n(X_j^{\ell}) \right) - \Delta_n(\sigma_{i-1}^{\ell-1})$$

$$+ \left( \sum_{v \in A^{\partial V_0(\ell)}} \sum_{a \in A} p((\sigma_{i-1}^{\ell-1}, v, a)) \log p(a|\sigma_{i-1}^{\ell-1}, v) \right)$$

$$- \sum_{a \in A} p((\sigma_{i-1}^{\ell-1}, a)) \log p(a|\sigma_{i-1}^{\ell-1}).$$

Set

$$D(i, \ell, \sigma) = \sum_{v \in A^{\partial V_0(\ell)}} \sum_{a \in A} p((\sigma_{i-1}^{\ell-1}, v, a)) \log p(a|\sigma_{i-1}^{\ell-1}, v)$$

$$- \sum_{a \in A} p((\sigma_{i-1}^{\ell-1}, a)) \log p(a|\sigma_{i-1}^{\ell-1}).$$

Moreover, for a constant $t > 0$ that will be chosen later, define

$$E(t, \ell) = \{ \forall \eta \in A^{V_0(\ell-1)}, \forall v \in A^{\partial V_0(\ell)} : |\Delta_n(\eta v)| \leq \frac{t}{2 |A||\partial V_0(\ell)|}, \ |\Delta_n(\eta)| \leq t/2 \}.$$

Then on $E(t, \ell),$

$$\frac{1}{|\Lambda_n|} \log L_n(i, \ell) \geq D(i, \ell, \sigma) - t.$$

Next we show that $D(i, \ell, \sigma)$ can be bounded away from zero. Taking into account

$$\sum_{v \in A^{\partial V_0(\ell)}} p((\sigma_{i-1}^{\ell-1}, v, a)) = p((\sigma_{i-1}^{\ell-1}, a)),$$

we can write

$$D(i, \ell, \sigma) = \sum_{v \in A^{\partial V_0(\ell)}} \sum_{a \in A} p((\sigma_{i-1}^{\ell-1}, v, a)) \log \frac{p(a|\sigma_{i-1}^{\ell-1}, v)}{p(a|\sigma_{i-1}^{\ell-1})}.$$

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By Pinsker’s inequality for relative entropy (see for example Fedotov et al. (2003), [13]), we have that for $P$ and $Q$ probability distributions on $\mathcal{A}$, 
\[
\sum_a P(a) \log \frac{P(a)}{Q(a)} \geq \frac{1}{2} ||P - Q||_{TV}^2.
\]
Moreover,
\[
||P - Q||_{TV}^2 \geq \sup_a (P(a) - Q(a))^2.
\]
But, since $\ell = l_i(\sigma)$, there exist $v$ and $a$ such that $p(a|\sigma_i^{\ell-1}) \neq p(a|\sigma_i^{\ell-1}, v)$. Hence we have that $D(i, \ell, \sigma) > 0$. Since we are working under the assumption that $l_i(\omega) \leq L$ for all $\omega$ (recall condition (3.22) of Assumption 3.7), we can thus conclude that
\[
D(i, \ell, \sigma) \geq d_0 > 0, \tag{7.3}
\]
where
\[
d_0 = \inf_{i, \sigma} D(i, l_i(\sigma), \sigma) > 0.
\]
Choosing now $t = \frac{d_0}{2}$, we finally obtain that on $E\left(\frac{d_0}{2}, \ell\right)$, for $\ell = l_i(\sigma)$,
\[
\log L_n(i, \ell) - pen(\ell, n) \geq |\bar{A}_n| \frac{d_0}{2} - pen(\ell, n) > 0
\]
for $n \geq n_0(i)$, since $pen(\ell, n) = \kappa |\mathcal{A}||A|^{\bar{V}_0(\ell)} \log |A_n| = O(\log |A_n|)$. This is in contradiction to (7.1) and implies that $\hat{\imath}_n(i) \geq l_i(\sigma)$. Hence we conclude that
\[
\mu[\exists i \in \Lambda_n : \hat{\imath}_n(i) < l_i(\sigma)] \leq \sum_{\ell \leq L} \mu \left[ E\left(\frac{d_0}{2}, \ell\right)^c \right]. \tag{7.4}
\]
We use (4.10) and sum over all possibilities of choosing $\eta \in \mathcal{A}^{V_0(\ell-1)}$ and of choosing patterns $X_j^{\ell}$ such that $X_j^{\ell-1} = \eta$, which gives $|\mathcal{A}|^{\bar{V}_0(\ell)}$ terms. But since for $\ell \leq L$, $|\mathcal{A}|^{\bar{V}_0(\ell)} \leq |\mathcal{A}|^{2L+1}$, we finally obtain
\[
\mu \left( E\left(\frac{d_0}{2}, \ell\right)^c \right) \leq 3|\mathcal{A}| e^{1/e} \left( |\mathcal{A}|^{(2L+1)^e} \right) \exp \left( -C(d, L) \frac{|\bar{A}_n| d_0 \alpha_0^2}{8 |\mathcal{A}|^e \log^2 \alpha_0 |A|^{\bar{V}_0(\ell)} e} \right) \leq 3|\mathcal{A}| e^{1/e} \left( |\mathcal{A}|^{(2L+1)^e} \right) \exp \left( -C_2(d, L, q_{\min}) |\bar{A}_n| \right)
\]
(recall the control of $\alpha_0$ given in (4.13)), where $C_2(d, L, q_{\min})$ is another constant depending on the dimension $d$, on the interaction range $L$ and on $q_{\min}$.

Thus, we can conclude that for any $0 < \epsilon < 1$ there exists $n_0 = n_0(\epsilon, q_{\min}, L, d)$ such that for all $n \geq n_0$,
\[
\sum_{\ell \leq L} \mu \left( E\left(\frac{d_0}{2}, \ell\right)^c \right) \leq \exp \left( -|\bar{A}_n|^{1-\epsilon} \right). \tag{7.5}
\]
(7.4) and (7.5) together conclude the proof of Theorem 3.9. •
8 Final comments

We generalize the concept of chains with memory of variable length to the multidimensional case of random fields. The main aim of this concept is to adopt a parsimonious way of describing data: the symbol at site $i$ is influenced only by a random set of symbols, the set depends on the observed data. As in the case of one dimensional models, the set of relevant neighbor states of site $i$ is called the context. The radius of the smallest ball containing the support of the context is the length of the context of site $i$.

We presented in Section 3 an estimator of the context length function based on a sequence of local decisions between two possible context lengths. These decisions are performed using the log likelihood ratio function. In the case of dimension one, our estimator is simply the context length estimator of variable length chains which has been classically considered in the literature. We refer the interested reader to Galves and Löcherbach (2008), [17], for a survey and bibliographic comments.

9 Appendix

At the end of Section 2 we argued that in order to estimate the context of a finite set of sites $\Lambda \subset \mathbb{Z}^d$ it is sufficient to estimate the contexts of the one-point specification. In particular, we stated formula (2.17), which relates $c_\Lambda(\omega)$ to $c_i(\omega)$. In the first subsection of this appendix we show this. In the second subsection, we complete the computations for the example 2.10. Finally we state a deviation inequality needed in Section 5.

9.1 From one point specifications to several points

It is well known in Statistical Mechanics that the positive one point specification uniquely determines the family of specifications, see Theorem 1.33 of Georgii (1988), [20]. This result still holds for Variable-neighborhood random fields, since they can be embedded into classical random fields. But we would like to determine if and how the context of a single site determines the $\Lambda$–contexts of the specification, for any $\Lambda \subset \mathbb{Z}^d$. Proposition 9.1 gives an answer.

We consider local specifications $\gamma$ which are positive, i.e.

$$\gamma_\Lambda(\omega_\Lambda | \cdot) > 0, \text{ for all } \omega_\Lambda \in \mathcal{A}_\Lambda \text{ and } \Lambda \subset \mathbb{Z}^d.$$ 

In the following it will be convenient to write

$$\gamma_\Lambda(\{\omega_\Lambda\} | \sigma) = g_\Lambda(\omega_\Lambda \sigma).$$

This family $\{g_\Lambda, \Lambda \subset \mathbb{Z}^d\}$ is a family of functions $g_\Lambda : \Omega \to [0,1]$ satisfying the following two conditions:

$$\sum_{\omega_\Lambda \in \mathcal{A}_\Lambda} g_\Lambda(\omega_\Lambda \sigma) = 1, \quad \forall \sigma \in \Omega,$$

and for every $\Lambda \subset \Delta \subset \mathbb{Z}^d$, all $\omega, \eta, \sigma$ in $\Omega$ we have

$$\frac{\rho_\Delta(\omega_\Lambda \sigma_\Delta \setminus \Lambda \sigma_{\Delta'})}{\rho_\Delta(\eta_\Lambda \sigma_\Delta \setminus \Lambda \sigma_{\Delta'})} = \frac{\rho_\Lambda(\omega_\Lambda \sigma_{\Lambda'})}{\rho_\Lambda(\eta_\Lambda \sigma_{\Lambda'})}. \quad (9.2)$$
Proposition 9.1 Assume that the family of local specifications $\gamma$ defined in (2.6) is positive. We have the following:

- $\gamma$ is uniquely determined by $\{\gamma_{\{i\}}(\cdot|c_i(\omega)), i \in \mathbb{Z}^d, \omega \in \Omega\}$.
- For $\Lambda \subseteq \mathbb{Z}^d$, 
  \[ \text{sp}_\Lambda(\omega) = \bigcup_{\omega_i \in A_{\{i\}}(\omega)} (\bigcup_{i \in \Lambda} \text{sp}_{\{i\}}(\omega)) \setminus \Lambda. \quad (9.3) \]

Proof. Recall that we set $\gamma_{\{i\}}(\{\omega(\cdot)|c_i(\omega)) = \rho_{\{i\}}(\omega)$. Further $\rho_{\{i\}}(\omega) > 0$ for $\omega \in \Omega$ since we assumed that $\gamma$ is positive. For each fixed $\omega(i)$, $\omega_{\{i\}} \mapsto \rho_{\{i\}}(\omega)$ is a measurable function with respect to $\mathcal{F}_{\text{sp}_{\{i\}}}$, see (2.4). For each $\Lambda$, Georgii (1988), p. 20, shows in the proof of Theorem 1.33 how to determine $\rho_{\Lambda}$ in terms of $\{\rho_{\{i\}}, i \in \mathbb{Z}^d\}$ such that for any measurable function $f$ we have that
  \[ \int f(\omega)d\mu(\omega) = \int d\mu(\omega_{\{i\}}) \sum_{\omega_{\{i\}} \in \Lambda^\Lambda} f(\omega)\rho_{\{i\}}(\omega), \quad \forall \Lambda \subseteq \mathbb{Z}^d, \quad (9.4) \]
  where $\mu$ is any measure on $\Omega$ so that
  \[ \int f(\omega)d\mu(\omega) = \int d\mu(\omega_{\{i\}}) \sum_{\omega_{\{i\}} \in A} f(\omega)\rho_{\{i\}}(\omega). \]

This immediately shows that $\gamma$ is uniquely determined by $\rho_{\{i\}}$. To construct $\rho_{\Lambda}$ and to prove (2.11), one proceeds by induction on $|\Lambda|$. The case $|\Lambda| = 1$ is trivial. Suppose then that $\rho_{\Lambda_1}$ and $\rho_{\Lambda_2}$ have been constructed. Let $\Lambda$ be the union of two disjoint sets, $\Lambda = \Lambda_1 \cup \Lambda_2$, $\Lambda_1 \cap \Lambda_2 = \emptyset$. Define
  \[ \rho_{\Lambda}(\omega) = \frac{\rho_{\Lambda_1}(\omega)}{\sum_{\omega_{\Lambda_1} \in A_{\Lambda_1}} \rho_{\Lambda_1}(\omega_{\Lambda_1}\omega_{\Lambda_2})} \quad (9.5) \]
  By induction, for any given $\omega_{\Lambda_1}, \omega_{\Lambda_2} \Rightarrow \rho_{\Lambda_1}(\omega) = \rho_{\Lambda_1}(\omega_{\Lambda_1}, \omega_{\Lambda_2})$ depends only on $\text{sp}_{\Lambda_1}(\omega)$, and for any given $\omega_{\Lambda_2}$, $\omega_{\Lambda_2} \Rightarrow \rho_{\Lambda_2}(\omega_{\Lambda_2}, \omega_{\Lambda_2})$ only on $\text{sp}_{\Lambda_2}(\omega)$. Hence (9.5) implies that for any given $\omega_{\Lambda}$, the function $\omega_{\Lambda} \Rightarrow \rho_{\Lambda}(\omega)$ depends, by construction, on the $\sigma$–algebra generated by $\text{sp}_{\Lambda_1}(\omega) \cup \bigcup_{\omega_{\Lambda_1} \in A_{\Lambda_1}} \text{sp}_{\Lambda_2}(\omega_{\Lambda_1}\omega_{\Lambda_2})$. Note that in general $\text{sp}_{\Lambda_1}(\omega) \cap \text{sp}_{\Lambda_2}(\omega) \neq \emptyset$. Therefore the value of $\omega_{\Lambda_1}$ might be relevant for determining $\text{sp}_{\Lambda_2}(\omega)$ and the value of $\omega_{\Lambda_2}$ might be relevant for determining $\text{sp}_{\Lambda_1}(\omega)$. To have a function $\rho_{\Lambda}(\omega)$ measurable for any choice of $\omega_{\Lambda}$ we set
  \[ \text{sp}_\Lambda(\omega) = \left[ \bigcup_{\omega_{\Lambda_1} \in \Lambda} \bigcup_{\omega_{\Lambda_2} \in \Lambda} (\text{sp}_{\Lambda_1}(\omega) \cup \text{sp}_{\Lambda_2}(\omega)) \right] \setminus (\Lambda_1 \cup \Lambda_2). \]
  In this way, for any choice of $\omega_{\Lambda}$, $\rho_{\Lambda}(\omega)$ is $\mathcal{F}_{\text{sp}_\Lambda}$–measurable. It is immediate to verify by induction that one has
  \[ \text{sp}_\Lambda(\omega) = \left[ \bigcup_{\omega_{\Lambda} \in \Lambda} \bigcup_{\omega_{\Lambda} \in A_{\{i\}}} \text{sp}_{\{i\}}(\omega) \right] \setminus \Lambda. \]
  We need to show that (9.4) holds. By induction, taking in account that $\omega = (\omega_{k}, \omega_{k})$,
  \[ \int f(\omega)d\mu(\omega) = \int d\mu(\omega_{k}) \sum_{\omega_{k}} f(\omega)\rho_{\Lambda_k}(\omega), \quad k = 1, 2 \quad (9.6) \]

---

1 The positivity requirement can be relaxed, under some minor modifications of the proof, see Georgii (1988), p. 20, Theorem 1.33.

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holds. To show that this holds for \( \rho_\Lambda \) take a positive measurable function \( f \) defined on \( \Omega \). We have
\[
\int d\mu(\bar{\omega}) \sum_{\omega_\Lambda} f(\omega_\Lambda \bar{\omega}_\Lambda) \\
= \int d\mu(\bar{\omega}) \sum_{\omega_{\Lambda_2} \omega_{\Lambda_1}} f(\omega_{\Lambda_1} \omega_{\Lambda_2} \bar{\omega}_\Lambda) \\
= \int d\mu(\bar{\omega}) \sum_{\omega_{\Lambda_2}} \rho_{\Lambda_2}(\omega_{\Lambda_2} \bar{\omega}_{\Lambda_2}) \rho_{\Lambda_2}^{-1}(\omega_{\Lambda_2} \bar{\omega}_{\Lambda_2}) \sum_{\omega_{\Lambda_1}} f(\omega_{\Lambda_1} \omega_{\Lambda_2} \bar{\omega}_\Lambda).
\]
But applying (9.6) first to \( \Lambda_2 \), then to \( \Lambda_1 \), this last line can be written as
\[
\int d\mu(\bar{\omega}) \sum_{\omega_{\Lambda_2}} \rho_{\Lambda_2}(\omega_{\Lambda_2} \bar{\omega}_{\Lambda_2}) \rho_{\Lambda_2}^{-1}(\omega_{\Lambda_2} \bar{\omega}_{\Lambda_2}) \sum_{\omega_{\Lambda_1}} f(\omega_{\Lambda_1} \omega_{\Lambda_2} \bar{\omega}_\Lambda) \\
= \int d\mu(\bar{\omega}) \rho_{\Lambda_2}^{-1}(\bar{\omega}) \left[ \sum_{\omega_{\Lambda_1}} f(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \right] \\
= \int d\mu(\bar{\omega}) \sum_{\omega_{\Lambda_1}} f(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \rho_{\Lambda_1}(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \rho_{\Lambda_1}^{-1}(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \left[ \sum_{\omega_{\Lambda_1}} f(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \right] \\
= \int d\mu(\bar{\omega}) \sum_{\omega_{\Lambda_1}} f(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \rho_{\Lambda_1}(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \rho_{\Lambda_1}^{-1}(\omega_{\Lambda_1} \bar{\omega}_{\Lambda_1}) \\
= \int d\mu(\bar{\omega}) \sum_{\omega_{\Lambda_1}} f(\omega) \rho_{\Lambda_1}(\omega) \rho_{\Lambda_1}^{-1}(\omega).
\]
Applying once more (9.6), we obtain
\[
\int d\mu(\omega_{\Lambda_1}) \sum_{\omega_{\Lambda_1}} f(\omega) \rho_{\Lambda_1}(\omega) \rho_{\Lambda_1}^{-1}(\omega) = \int d\mu(\omega) f(\omega) \rho_{\Lambda}^{-1}(\omega).
\]
By applying the above equality to \( f(\omega) \rho_{\Lambda}(\omega) \) instead of \( f(\omega) \) we get the result. The above definition of \( \rho_{\Lambda} \) depends on the choice of \( \Lambda_1 \) and \( \Lambda_2 \); one needs to obtain an unambiguous definition of \( \rho_{\Lambda} \) to choose a definite strategy to exhausting \( \Lambda \) site by site.

\[\text{\bullet}\]

9.2 Continuation of the example 2.10

Continuation of example 2.10

We prove formula (2.11), using (2.13). First note that \( i \in \Gamma_j(\omega) \) implies that \( ||i - j|| \leq L \). Now if \( i \in \Gamma_j(\omega) \), we have two cases. Either \( i \in \hat{\Gamma}_j(\omega) \), in which case \( \Gamma^1_j(\omega) = \Gamma^1_j(\omega) \). Or \( i \in \partial \Gamma^1_j(\omega) \). Then \( \omega(i) i = 1 \), and in this case, \( i \in \hat{\Gamma}_j(\omega^i) \). Then the same arguments as above show that

\[
\Gamma^1_j(\omega^i) = \Gamma^1_j(\omega).
\]
Hence
\[
\left\{ \bigcup_{j \in \mathbb{Z}^2} \{ \Gamma^1_j(\omega) : i \in \Gamma_j(\omega) \} \cup \bigcup_{j \in \mathbb{Z}^2} \{ \Gamma^1_j(\omega^i) : i \in \Gamma_j(\omega^i) \} \right\} = \Gamma^1_i(\omega).
\]

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Finally, by definition of $\Gamma_j(\omega)$,

\[
\left[ \bigcup_{j \in \mathbb{Z}^2} \{ \Gamma_j(\omega) : i \in \Gamma_j(\omega) \} \cup \bigcup_{j \in \mathbb{Z}^2} \{ \Gamma_j(\omega^i) : i \in \Gamma_j(\omega^i) \} \right] = \left[ \bigcup_{j \in \mathbb{Z}^2} \{ \Gamma_j^1(\omega) : i \in \Gamma_j(\omega) \} \cup \bigcup_{j \in \mathbb{Z}^2} \{ \Gamma_j^1(\omega^i) : i \in \Gamma_j(\omega^i) \} \right] \cap \bigcup_{j \in V_i(L)} V_j(L) = \Gamma_1^1(\omega^i) \cap V_i(2L).
\]

This concludes the proof.

We close with the following version of Bernstein’s inequality obtained by Friedman (1975), for discrete-time martingales having bounded jumps, see for instance Dzhaparidze and van Zanten.[11]

**Lemma 9.2** Let $M_n = \xi_1 + \ldots + \xi_n$ be a discrete martingale with respect to some filtration $(\mathcal{F}_n)_{n \geq 0}$ having bounded jumps $|\xi_n| \leq a$. Let

\[
\langle M \rangle_n = \sum_{i=1}^n E(\xi_i^2 | \mathcal{F}_{i-1}).
\]

Then

\[
P\left( \max_{k \leq n} |M_k| > z ; \langle M \rangle_n \leq L \right) \leq 2 \exp \left( -\frac{1}{2} \left( \frac{z^2}{L} + \frac{az}{3} \right) \right).
\]

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Eva Löcherbach  
CNRS UMR 8088  
Département de Mathématiques  
Université de Cergy-Pontoise  
95 000 CERGY-PONTOISE, France  
email: eva.loecherbach@u-cergy.fr

Enza Orlandi  
Dipartimento di Matematica  
Università di Roma Tre  
L.go S.Murialdo 1, 00146 Roma, Italy.  
email: orlandi@mat.uniroma3.it