Abstraction Logic: The Marriage of Contextual Refinement and Separation Logic

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Contextual refinement and separation logics are successful verification techniques that are very different in nature. First, the former guarantees behavioral refinement between a concrete program and an abstract program while the latter guarantees safety of a concrete program under certain conditions (expressed in terms of pre and post conditions). Second, the former does not allow any assumption about the context when locally reasoning about a module while the latter allows rich assumptions.

In this paper, we present a new verification technique, called abstraction logic (AL), that inherently combines contextual refinement and separation logics such as Iris and VST, thereby taking the advantages of both. Specifically, AL allows us to locally verify a concrete module against an abstract module under separation-logic-style pre and post conditions about external modules. AL are fully formalized in Coq and provides a proof mode that supports a combination of simulation-style reasoning using our own tactics and SL-style reasoning using IPM (Iris Proof Mode). Using the proof mode, we verified various examples to demonstrate reasoning about ownership (based on partial commutative monoids) and purity (i.e., termination with no system call), cyclic and higher-order reasoning about mutual recursion and function pointers, and reusable and gradual verification via intermediate abstractions. Also, the verification results are combined with CompCert, so that we formally establish behavioral refinement from top-level abstract programs, all the way down to their assembly code.

1 INTRODUCTION

Contextual refinement [Gu et al. 2015] and program logics [Hoare 1969] (most notably, separation logics [O’hearn 2007; Reynolds 2002]) are two successful verification techniques. The former is typically used for compiler verification, where both implementation and specification are given as executable programs and its verification establishes that all possible observable behaviors of the implementation program under an arbitrary context are included in those of the specification program under the same context. The latter are mainly used for verification of a program against its logical specification, where the specification is given as a pair of pre and post conditions and its verification typically establishes that if the program starts with a state satisfying the pre condition, then it executes safely, and if it terminates, the final state satisfies the post condition.

These two techniques are very different in nature and have their own advantages. First, specifications in contextual refinement describe intended dynamic behaviors including interactions with its context/environment and side effects such as fatal errors and non-termination, while those in program logics typically describe sufficient conditions for safe executions (i.e., those without fatal errors in case of partial correctness, and in addition without non-termination in case of total correctness). Second, contextual refinement allows to verify one aspect at a time via multiple intermediate (specification) programs since they are transitivity composable (e.g., a compiler translation consists of a sequence of optimizations, each of which is separately verified using a possibly
different simulation relation), while program logics require to find and verify safety conditions for the whole program in one step (although the conditions may be refined in further steps). Third, when locally reasoning about a module, in contextual refinement one cannot make any assumptions about external modules because they are completely arbitrary, while in program logics one can make specific assumptions (i.e., safety conditions) about each external module since the verified module is only composed with other verified modules instead of arbitrary modules.

In this paper, we present a new verification framework, called abstraction logic (AL), that inherently combines the two techniques of contextual refinement (CR) and separation logic (SL), thereby taking the advantages of both.

**High-level overview of AL.** We first highlight how AL is different from CR and the standard version of SL using an abstract example (See §8 for comparison with other variations of SL). For this, consider two modules, named M with a function f and named N with a function g, and suppose we have their implementations I₁, I₂ and SL-style specifications S₁, S₂.

In SL, one can locally verify each implementation Iᵢ for i ∈ {1, 2} against its specification Sᵢ assuming both specifications S₁, S₂, which we denote by S₁, S₂ ⊢ I₁ : S₁. Then SL combines the two verification results as follows:

\[ S₁, S₂ ⊢ I₁ : S₁ \]

\[ S₁, S₂ ⊢ I₂ : S₂ \]

\[ I₁ ∘ I₂ \text{ safe} \]

It guarantees that the linked program I₁ ∘ I₂ only produces safe behaviors (i.e., no fatal errors). For example, if M.f() ≡ (1+1) / N.g() in I₁, then by assuming N.g() is safe and returns 1, which is specified in S₂, we can prove that M.f() is safe and returns 2, which is specified in S₁. It is important to note that SL in general cannot guarantee anything when verified modules are composed with unverified ones because those unverified may trigger a fatal error. For example, if M.f() ≡ (L.h(); (1 + 1) / N.g()) in I₁ and the implementation I₃ for the module L is unverified, SL cannot guarantee safety of I₁ ∘ I₂ ∘ I₃ since I₃ might not be safe.

On the other hand, CR provides verification results that are valid under unverified contexts. Specifically, in CR, one can locally¹ verify I₁ against another more abstract implementation A₁, simply called abstraction, for M, which we denote by I₁ ⊆_{ctx} A₁. Then by the definition of CR, we have the following result for an arbitrary (even unsafe or abstract) implementation C for N.

\[ I₁ ⊆_{ctx} A₁ \]

\[ \text{Beh}(I₁ ∘ C) ⊆ \text{Beh}(A₁ ∘ C) \]

For example, when M.f() ≡ (1 + 1) / N.g() in I₁, we can verify it against A₁ with M.f() ≡ 2 / N.g(), which is valid even when N is an unverified arbitrary module because the behavioral refinement preserves even crash or non-termination behaviors between the implementation and abstraction (e.g., if the implementation crashes, so does the abstraction). However, its limitation is that we cannot verify I₁ against more useful abstractions such as M.f() ≡ 2 because N.g() in C is arbitrary and thus may not return 1.

The key innovation in AL is that we overcome the limitation of CR by internalizing, inside a module, SL-style specifications about other modules. To see this, revisit the above problematic example where M.f() ≡ (1 + 1) / N.g() in I₁ and M.f() ≡ 2 in A₁, and thus I₁ ⊆_{ctx} A₁ does not hold. To solve this problem, from A₁ together with the above specifications S₁, S₂ (i.e., saying that M.f() returns 2 and N.g() returns 1), AL derives a special abstraction for M, denoted [S₁, S₂ ∗ A₁ : S₁] and called abspec, that internalizes S₁, S₂ inside A₁. Then, one can actually prove I₁ ⊆_{ctx} [S₁, S₂ ∗ A₁ : S₁],

¹In theory, it might be possible to globally verify I₁ ∘ I₂, where you can make assumptions about I₁ and I₂. However, it would sacrifice the power of local reasoning and compositionality, so we aim high to support fully compositional verification.
which essentially amounts to proving that the behaviors of $I_1$ refines those of $A_1$ and satisfies $S_1$ under arbitrary contexts but assuming the specifications $S_1$ and $S_2$. Note that this verification is local to $I_1$ and $A_1$ for $M$ just relying on the specifications $S_1$ and $S_2$, so that the refinement can hold under an arbitrary implementation $C$ for $N$ (as required by the definition of $\leq_{ctx}$). Even further, when $M.f() \equiv (L.h(); (1 + 1) / N.g())$ in $I_1$ and $M.f() \equiv (L.h(); 2)$ in $A_1$ with the implementation of $L$ unknown (i.e., $L$ may even be unsafe or make arbitrary calls including mutually recursive calls to the modules $M$ and $N$), we can still prove $I_1 \leq_{ctx} [S_1, S_2 \bowtie A_1 : S_1]$ for $S_1, S_2$ the same as above without assuming anything about $L$.

To combine local verification results, AL provides the following theorem for any $S_1, S_2, A_1, A_2$.

$$[S_1, S_2 \bowtie A_1 : S_1] \circ [S_1, S_2 \bowtie A_2 : S_2] \leq_{ctx} A_1 \circ A_2$$

Then, by horizontal and vertical compositionality of CR and the definition of CR, we can derive, e.g., the following corollary for any (even unsafe or abstract) implementation $C$ for $L$:

$$I_1 \leq_{ctx} [S_1, S_2 \bowtie A_1 : S_1]$$
$$I_2 \leq_{ctx} [S_1, S_2 \bowtie A_2 : S_2]$$

$$\text{Beh}(I_1 \circ I_2 \circ C) \subseteq \text{Beh}(A_1 \circ A_2 \circ C)$$

We have two advantages from the fact that the resulting abstraction $A_1 \circ A_2 \circ C$ is also an executable program.

(1) One can test the abstraction by executing it, so that we can more easily see whether the abstraction works as intended.

(2) One can treat the abstraction as an implementation and further verify it using AL, which allows gradual abstraction from an implementation to the top-level abstraction in multiple steps and can also increase reusability of verification (See §3.3 for a concrete example). An example of such gradual and modular verification is depicted as follows.

Finally, we remark that AL can be seen as subsuming both CR and SL. The former is achieved by not making any assumptions, and the latter because AL can also be used to prove safety guarantees as follows. For example, for any $I_1, I_2$ and $S_1, S_2$, by setting $A_i$ to be a special abstraction, called Safe, we have the following:

$$I_1 \leq_{ctx} [S_1, S_2 \bowtie \text{Safe} : S_1]$$
$$I_2 \leq_{ctx} [S_1, S_2 \bowtie \text{Safe} : S_2]$$

$$\text{Beh}(I_1 \circ I_2) \subseteq \text{Beh}(\text{Safe} \circ \text{Safe})$$
where proving $I_i \leq_{\text{ctx}} [S_1, S_2 \times \text{Safe} : S_i]$ essentially amounts to proving $S_1, S_2 \vdash I_i : S_i$ in SL. Then since Beh(Safe $\circ$ Safe) is a set of safe behaviors, we can conclude that $I_1 \circ I_2$ only produces safe behaviors.

**Contributions.** In this paper, we developed the theory of abstraction logic (currently in a sequential setting) and tools for it including the AL proof mode and a verified compiler for AL down to assembly. All results are fully formalized in Coq [The Coq Development Team 2021] and summarized as follows.

1. We developed the first comprehensive theory, AL, that enables establishing contextual refinement via powerful local reasoning that allows us to rely on SL-style specifications. In particular, AL allows us to express various ownership via PCMs (Partial Commutative Monoids) [Calcagno et al. 2007] as in the state-of-the-art SLs such as Iris [Jung et al. 2015] and VST [Appel 2011].

2. We developed EMS (Executable Module Semantics) by generalizing Interaction Trees [Xia et al. 2019] to support module systems and two kinds of nondeterminism, called choose and take. In particular, via Coq’s extraction mechanism, we can extract an EMS to an executable program in OCaml as done in Interaction Trees. Also, we developed two sub-languages IMP and SPC that are embedded into EMS (via deep embedding for IMP and shallow embedding for SPC).
   - IMP: a C-like language with integer and (function and memory) pointer values, which is used to write underlying implementations like $I_1$ above that are verified against higher-level abstractions using AL and also compiled down to assembly via our verified compiler for IMP.
   - SPC: a specification language, which is used to write an abspec, which is a combination of an abstraction and SL-style specifications like $[S_1, S_2 \times A_1 : S_i]$ above.

3. We developed the AL proof mode that supports a combination of simulation-style reasoning and SL-style reasoning by allowing smooth switching between the two styles during a single proof, which is essentially necessary because AL inherently combines the two techniques. Specifically, for the former we developed our own tactics that allow to set up a simulation relation (possibly with a module-local relational invariant) between the implementation and abspec, and reason about it stepwise; and for the latter we employed the IPM (Iris Proof Mode) package (i.e., by instantiating it with our AL theory) to streamline the process for reasoning about separating conjunction, magic wand, and PCM resources.

4. Using the AL proof mode, we verified various examples written in IMP, which demonstrates reasoning about PCM-based ownership, proving and exploiting purity (i.e., termination with no system call), cyclic and higher-order reasoning about recursion and function pointers, and reusable and gradual verification via intermediate abstractions. Note that in spite of supporting cyclic and higher-order reasoning, AL does not rely on any step-indexing techniques [Ahmed 2006].

5. Finally, we developed a verified compiler for IMP targeting Csharpminor of CompCert [Leroy 2006], which is verified in the style of CompCert’s verification. Therefore, we formally establish behavioral refinement from the top-level abstractions of the above examples, all the way down to their assembly code generated by the IMP compiler and CompCert.

2 **KEY IDEAS**

We gradually introduce the key ideas behind AL by presenting how to express Hoare logic specifications (§2.1) and separation logic specifications (§2.2).
\[ I_M := \text{[Module Main]} \]
\[
\text{def main()} \equiv \\
\quad \text{var } x := 40; \\
\quad \text{var } r := F.f(x); \\
\quad \text{if } (r \mod 4 == 1) \text{ then } print(42) \text{ else } 1/0 \\
\]
\[ S_M := \{\{\text{True}\} \text{Main.main}\{\text{True}\}\} \]
\[ A_M := \text{[Module Main]} \]
\[
\text{def main()} \equiv \\
\quad \text{var } x := 40; \\
\quad \text{var } r := F.f(x); \\
\quad \text{print}(42) \\
\]
\[ [S_M \cup S_F \Rightarrow A_M : S_M] := \\
\quad \text{[Module Main]} \\
\quad \text{def main()} \equiv \\
\quad \quad \text{var } x := 40; \\
\quad \quad \text{\underline{\text{guarantee}}(x \mod 4 == 0);} \\
\quad \quad \text{var } r := F.f(x); \\
\quad \quad \text{\underline{\text{assume}}(r \mod 4 == 1);} \\
\quad \quad \text{\underline{\text{print}}(42)} \\
\]
\[ I_F := \text{[Module F]} \]
\[
\text{def f(x)} \equiv \\
\quad \text{var } r := x \times x/4 + x + 1; \\
\quad \text{\underline{print}}(r); \\
\quad r \\
\]
\[ S_F := \{\{\lambda x. x \mod 4 == 0\} F.f \{\lambda r. r \mod 4 == 1\}\} \]
\[ A_F := \text{[Module F]} \]
\[
\text{def f(x)} \equiv \\
\quad \text{var } r := (x/2 + 1)^{*2}; \\
\quad \text{\underline{print}}(r); \\
\quad r \\
\]
\[ [S_M \cup S_F \Rightarrow A_F : S_F] := \\
\quad \text{[Module F]} \\
\quad \text{def f(x: int)} \equiv \\
\quad \quad \text{\underline{assume}}(x \mod 4 == 0); \\
\quad \quad \text{var } r := (x/2 + 1)^{*2}; \\
\quad \quad \text{\underline{print}}(r); \\
\quad \quad \text{\underline{\text{guarantee}}(r \mod 4 == 1);} \\
\quad \quad \text{\underline{\text{r}}} \\
\]

**Fig. 1.** Implementations, HL specifications, Abstractions, and Abspecs for Main and F

### 2.1 Hoare logic specifications in abstraction logic

To demonstrate how to express Hoare logic (HL) specifications in abstraction logic, consider the implementations \(I_M\) and \(I_F\) of the modules Main and F, shown in Fig. 1. Here \(\text{Main.main()}\) (i) invokes \(F.f(x)\) with \(x = 40\), which computes \(x \times x/4 + x + 1\), prints it out via the system call \text{print} and returns it; (ii) if the result is an odd number, prints \(42\); (iii) otherwise, crashes by executing division by zero. In HL, the specification \(S_M\) says that \(\text{Main.main()}\) runs safely, \textit{assuming} the specification \(S_F\), which says that if the argument of \(F.f\) is a multiple of \(4\), it runs safely and returns a number \(r\) such that \(r\) modulus \(4\) is \(1\).

In AL, assuming the specifications \(S_M\) and \(S_F\) (ignoring the safety), we would like to \textit{locally} verify \(I_M\) and \(I_F\) against, e.g., the abstractions \(A_M\) and \(A_F\) in Fig. 1, where the abstracted parts are \textit{boxed} and \(*\) is the exponentiation operator. First, note that without any assumption neither \(I_M \subseteq_{\text{ctx}} A_M\) nor \(I_F \subseteq_{\text{ctx}} A_F\) holds because their context implementations are arbitrary. For example, \(\emptyset\) may be given for \(r\) in \(\text{Main.main()}\), and \(1\) may be given for \(x\) in \(F.f(x)\), in which cases the implementation and abstraction behave differently. The question here is how to \textit{internalize} the specifications inside \(A_M\) and \(A_F\).

The abspecs \([S_M \cup S_F \Rightarrow A_M : S_M]\) and \([S_M \cup S_F \Rightarrow A_F : S_F]\) internalizing \(S_M, S_F\) inside \(A_M\) and \(A_F\) are given in Fig. 1, where we simply insert \text{\underline{assume}} and \text{\underline{guarantee}} commands according to \(S_M\) and \(S_F\). Specifically, \(F.f(x)\) \text{\underline{assumes}} its precondition \(x \mod 4 == 0\) at the beginning and \text{\underline{guarantees}} its postcondition \(r \mod 4 == 1\) at the end. Conversely, \(\text{Main.main()}\) \text{\underline{guarantees}} the precondition of \(F.f(x)\) before invoking it and \text{\underline{assumes}} the postcondition of \(F.f(x)\) after the invocation. Note that we simply omitted \text{\underline{assume}}(true) and \text{\underline{guarantee}}(true) corresponding to \{True\} \{True\} of \(\text{Main.main()}\) because they do nothing as we will see below.

Now the computational interpretation of \text{\underline{assume}} and \text{\underline{guarantee}} is given as follows. First, \text{\underline{assume}}(\text{P}) for a proposition \(P\) does nothing if \(P\) holds; otherwise triggers \textit{undefined behavior} (UB), which is a standard notion (e.g., in CompCert) and interpreted as exhibiting all possible
behaviors:

\[
\text{assume}(P) \overset{\text{def}}{=} \text{if } P \text{ then skip else UB}
\]

To see the intuition, consider proving \(I \leq \text{ctx} [S_{\text{Main}} \cup S_f \triangleright A_f : S_f] \). If the argument \(x\) to \(f.\) does not satisfy \(x \mod 4 = 0\), the abspec triggers UB thereby exhibiting all possible behaviors, which trivially include whatever behavior the implementation may exhibit. Therefore in the verification we do not need to consider the cases where the assume command fails (i.e., we can assume it holds).

Second, \text{guarantee}(P)\) does nothing if \(P\) holds; otherwise triggers no behavior (NB), which appeared in [Kang et al. 2015; Ševčík et al. 2013] and is interpreted as exhibiting no behaviors (see §4 for the formal definition):

\[
\text{guarantee}(P) \overset{\text{def}}{=} \text{if } P \text{ then skip else NB}
\]

Again, for \(I \leq \text{ctx} [S_{\text{Main}} \cup S_f \triangleright A_f : S_f] \), suppose the argument \(x\) satisfies \(x \mod 4 = 0\) and then both implementation and abspec will compute and print the same value \(r\). Now if \(r\) does not satisfy \(r \mod 4 = 1\), the abspec triggers NB thereby exhibiting no behaviors, which does not include whatever behavior the implementation may exhibit (unless it also triggers NB, which is not the case here). Therefore in the verification we must prove that the guarantee command succeeds (i.e., we should guarantee it holds).

Then, we can actually prove \(I_{\text{Main}} \leq \text{ctx} [S_{\text{Main}} \cup S_f \triangleright A_{\text{Main}} : S_{\text{Main}}]\) and \(I_f \leq \text{ctx} [S_{\text{Main}} \cup S_f \triangleright A_f : S_f]\). For the former, we first prove \(\text{guarantee}(x \mod 4 = 0)\) succeeds since \(x\) is \(40\); then for any given \(r\) from \(f.\), we can assume \(r \mod 4 = 1\), which implies \(r \mod 2 = 1\) thereby proving that both implementation and abspec print 42. For the latter, we can assume \(x \mod 4 = 0\) thereby proving that both implementation and abspec compute and print the same value \(r\). Then \(\text{guarantee}(r \mod 4 = 1)\) succeeds since \(r\) is \((x/2 + 1) \times 2\) and we assumed \(x \mod 4 = 0\). Finally, both return the same \(r\).

Finally, we can see that the following hold:

\[
\text{Beh([}S_{\text{Main}} \cup S_f \triangleright A_{\text{Main}} : S_{\text{Main}}]\circ [S_{\text{Main}} \cup S_f \triangleright A_f : S_f]) \subseteq \text{Beh}(A_{\text{Main}} \circ A_f)
\]

which easily follows using the following lemma: for any proposition \(P\) and any program with a hole \(K[-]\),

\[
\text{Beh}(K[\text{guarantee}(P); \text{assume}(P)]) \subseteq \text{Beh}(K[\text{skip}])
\]

This lemma holds trivially if \(P\) holds; otherwise it holds since the left hand side exhibits no behavior.

### 2.2 Separation logic specifications in abstraction logic

Now to see how we can express separation logic (SL) specifications in abstraction logic, consider the implementations \(I_{\text{Cannon}}\) and \(I_{\text{Main}}\) of the two modules Main and Cannon, shown in Fig. 2. Here \(\text{Main.main()}\) invokes \(\text{Cannon.fire()}\) and prints the return value for a fixed number, \(\text{NUM.FIRE}\), of times. The Cannon module consists of (i) the \text{module-local} variable powder (i.e., not accessible to other modules), which is initially set to 1 and (ii) the function \text{fire}, which sets the variable \(r\) to be \(1/powder\), prints \(r\), decrements powder by 1, and returns \(r\). Note that \text{Cannon.fire()} can be safely invoked only once because it will crash due to division by zero at the second invocation; therefore, if \(\text{NUM.FIRE}\) is 2, the whole program crashes.

We briefly discuss how one can prove safety of the program when \(\text{NUM.FIRE}\) is 1 in SL. First, the SL specification \(S_{\text{Cannon}}\) (given in Fig. 2) says that if the resource \text{Ball} is logically given, \text{Cannon.fire()} safely executes and returns 1 but does not logically give the \text{Ball} back (i.e., \text{Ball} is consumed). Here one can intuitively understand a \text{resource} as something that is neither duplicable nor creatable out of nothing. In this example, we can design the universe of resources—via a general mechanism based on PCMs (Partial Commutative Monoids)—in such a way that there can be at most one \text{Ball}, relying on which we can then \textit{locally} prove the safety of \text{Cannon.fire()} since it requires
Ball and thus can be invoked at most once. Second, the SL specification $S_{\text{Main}}$ says that given a Ball, $\text{Main.main()}$ safely executes, which is locally provable relying on $S_{\text{Cannon}}$ since NUM_FIRE is 1 and thus $\text{Cannon.fire()}$ is invoked only once. Indeed, if NUM_FIRE was 2, one cannot verify $\text{Main.main()}$ against $S_{\text{Main}}$ since there is no Ball left at the second invocation of $\text{Cannon.fire()}$. Note that this kind of reasoning would not be possible in Hoare logic because $\text{Cannon.fire()}$ has no arguments, so that it would be hard to express any kind of precondition.

With this intuition, in AL, assuming $S_{\text{Main}}$ and $S_{\text{Cannon}}$, we would like to locally verify $I_{\text{Main}}$ and $I_{\text{Cannon}}$ against, e.g., the abstractions $A_{\text{Main}}$ and $A_{\text{Cannon}}$ in Fig. 2, where the abstracted parts are boxed. Note that without any assumption neither $I_{\text{Main}} \subseteq \text{ctx} A_{\text{Main}}$ nor $I_{\text{Cannon}} \subseteq \text{ctx} A_{\text{Cannon}}$ holds since their context modules are arbitrary and hence, e.g., 0 may be given for $r$ in $\text{Main.main()}$, and also $\text{Cannon.fire()}$ may be invoked twice by the context in which case $I_{\text{Cannon}}$ crashes but $A_{\text{Cannon}}$
runs successfully. As before, to solve this problem, we will internalize the SL specifications inside the abstractions, which are the abspecs given in Fig. 2:

\[ S_{\text{Main}} \cup S_{\text{Cannon}} \times (A_{\text{Main}}, \sigma_{\text{Main}}) : S_{\text{Main}} \] and \[ S_{\text{Main}} \cup S_{\text{Cannon}} \times (A_{\text{Cannon}}, \sigma_{\text{Cannon}}) : S_{\text{Cannon}} \]

To understand the abspecs, we first see how the set of resources PCM\(_{\text{Cannon}}\) is defined. Concretely, PCM\(_{\text{Cannon}}\) consists of five elements Undef, Unit, Ready, Fired, Ball with a commutative binary operator + defined as follows:

- \( \forall p \in \text{PCM}_{\text{Cannon}}, \text{Undef} + p = \text{Undef} \)
- \( \forall p \in \text{PCM}_{\text{Cannon}}, \text{Unit} + p = p \)
- \( \text{Ready} + \text{Ball} = \text{Fired} \)
- \( \text{Fired} + \text{Ready} = \text{Fired} + \text{Ball} = \text{Ready} + \text{Ready} = \text{Fired} + \text{Fired} = \text{Ball} + \text{Ball} = \text{Undef} \)

The intuition here is that Undef represents undefinedness (i.e., inconsistency); Unit the empty resource, which is the identity for +; Ready the knowledge that Cannon is not yet fired; Fired that Cannon is already fired; and Ball the capability to invoke Cannon.\(\text{fire}()\). The definition of + captures that only a subset of \{Ready, Ball\} or \{Fired\} is consistent; in particular, there cannot be two (or more) Balls since Ball + Ball = Undef.

Now we look at the abspecs. The dotted boxes are generated from \(S_{\text{Main}}\) and \(S_{\text{Cannon}}\), where AS\(\text{SUM}\) and GU\(\text{ARANTEE}\) are the macros defined at the bottom of Fig. 2. Also the gray code is boilerplate and the highlighted parts are modules’ initial resources, which come from \(\sigma_{\text{Main}}\) and \(\sigma_{\text{Cannon}}\) of the abspecs.

Then we see how it works. Each module has a module-local resource, \(\text{res}_n\), initialized with its initial resource and each function has a function local resource, \(\text{res}_f\), initialized with Unit. Then Cannon.\(\text{fire}()\) assumes its precondition saying that a resource Ball is given at the beginning, and guarantees its postcondition saying that no resource is returned and the return value \(r\) is 1 at the end. Main.\(\text{main}()\) also assumes its precondition saying that a resource Ball is given at the beginning; then guarantees the precondition of Cannon.\(\text{fire}()\) before invoking it and assumes the postcondition of Cannon.\(\text{fire}()\) after the invocation; finally guarantees its postcondition at the end.

Now we see the computational interpretation of AS\(\text{SUM}\) and GU\(\text{ARANTEE}\), whose macro definitions are given in Fig. 2. First, AS\(\text{SUM}(\text{Cond})\) takes a resource; assumes it satisfies Cond; adds it to \(\text{res}_f\); and assumes \(\text{res}_f\) is consistent with \(\text{res}_m\). Here the take operation is a key technique in AL and will be explained below. For now, we simply consider as if take(PCM\(_{\text{Cannon}}\)) magically takes the resource that is given by the caller or returned by the callee. Second, GU\(\text{ARANTEE}(\text{Cond})\) (i) nondeterministically updates \(\text{res}_m\) and \(\text{res}_f\) via fpu, called frame-preserving update (FPU)\(^2\); (ii) nondeterministically chooses a resource; (iii) guarantees it satisfies Cond; and (iv) subtracts it from \(\text{res}_f\). In (i), we are allowed to update the module and function resources before jumping to another function, which however is restricted to FPFs. The definition of fpu is given as follows:\(^3\):

\[
\text{fpu}(\text{res}_m, \text{res}_f) \triangleq \text{choose}\{((\text{res}_m', \text{res}_f')) | \forall \text{frame} \in \text{PCM}_{\text{Cannon}}, \\
\text{res}_\text{frame} + \text{res}_m + \text{res}_f' \neq \text{Undef} \implies \text{res}_\text{frame} + \text{res}_m + \text{res}_f' \neq \text{Undef}\}
\]

where \text{choose}(X) nondeterministically picks an element from the given set \(X\). The intuition is that one can update \(\text{res}_m\) and \(\text{res}_f\) in such a way that consistency is preserved under an arbitrary frame resource \(\text{res}_\text{frame}\) (capturing possible resources remaining in other modules). In (ii), although a resource \(\text{res}\) is just nondeterministically chosen, for now we simply consider as if it is magically passed to the callee or returned to the caller. In (iii), if the chosen \(\text{res}\) does not satisfy

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\(^2\)The notion of frame-preserving update comes from modern separation logic such as Iris [Jung et al. 2018].

\(^3\)Our formal definition of fpu is slightly more general as found in SLs (see Fig. 9 for details).
the condition Cond, it triggers no behavior, which means that only that resource satisfying the condition can be chosen. In (ii), we performed the subtraction because we are passing it to another function, which will add it to its own function resource as we have seen above in $\text{ASSUME}(\text{Cond})$. The definition of $\text{minus}$ is given as follows:

$$\text{minus}(\text{res}_f, \text{res}) \overset{\text{def}}{=} \text{choose}(\{\text{res}_f'|\text{res}_f' + \text{res} = \text{res}_f\})$$

Note that when there is no such $\text{res}_f'$, it triggers no behavior because choosing from the empty set does so.

Now we see how the illusion of resource passing between functions works via $\text{choose}$ and $\text{take}$. First of all, note that it does not make sense to physically pass any resource information to context modules or receive it from them because context modules are completely arbitrary and thus may not understand such resource information (e.g., those written in IMP). Our key observation, however, is that by defining $\text{take}$ as the dual operation to $\text{choose}$, we can logically make such an illusion. Specifically, the nondeterministic choice $\text{choose}$ and its dual $\text{take}$\(^4\) are defined as follows for any set $X$ (See §4 for formal definitions).

$$\text{Beh}(x := \text{choose}(X); K[x]) \overset{\text{def}}{=} \bigcup_{x \in X} \text{Beh}(K[x])$$

$$\text{Beh}(x := \text{take}(X); K[x]) \overset{\text{def}}{=} \bigcap_{x \in X} \text{Beh}(K[x])$$

Note that $\text{choose}(\emptyset)$ is NB and $\text{take}(\emptyset)$ is UB. The intuition is that when proving $\text{Beh}(I) \subseteq \text{Beh}(\text{res} := \text{choose}(\text{PCM}_\text{Cannon}); K[\text{res}])$, it suffices to prove $\text{Beh}(I) \subseteq \text{Beh}(K[\text{res}])$ for some resource $\text{res}$, which allows us to logically (i.e., in the proof) pick a particular resource to pass to the context. On the other hand, when proving $\text{Beh}(I) \subseteq \text{Beh}(\text{res} := \text{take}(\text{PCM}_\text{Cannon}); K[\text{res}])$, we need to prove $\text{Beh}(I) \subseteq \text{Beh}(K[\text{res}])$ for every resource $\text{res}$, which makes sense because we do not know what resource will be given from the context, and thus we have to prove the refinement whatever resource is given. Then we have the following theorem, which makes the illusion of passing a resource from $\text{choose}$ to $\text{take}$.

$$\text{Beh}(\text{res} := \text{choose}(\text{PCM}_\text{Cannon}); K[\text{res}]; \text{res}' := \text{take}(\text{PCM}_\text{Cannon}); K'[\text{res}']) \subseteq \text{Beh}(\text{res} := \text{choose}(\text{PCM}_\text{Cannon}); K[\text{res}]; K'[\text{res}']) \quad (\star)$$

This theorem holds simply by instantiating the $\text{take}$ operation with the chosen resource $\text{res}$.

With this, we can prove $l_{\text{Main}} \leq_{\text{ctx}} [S_{\text{Main}} \cup S_{\text{Cannon}} \bowtie (A_{\text{Main}}, \sigma_{\text{Main}}) : S_{\text{Main}}]$ for $\text{NUM\_FIRE} = 1$. When $\text{Main.main}$ is invoked, by $\text{ASSUME}(\lambda\text{res} . \text{res} = \text{Ball})$ for any taken resource $\text{res}$, we can assume $\text{res} = \text{Ball}$ and thus add Ball to $\text{res}_f$ yielding Ball. Then for $\text{GUARANTEE}(\lambda\text{res} . \text{res} = \text{Ball})$ the abspec does not update $\text{res}_m$, $\text{res}_f$, chooses Ball for $\text{res}$ to satisfy the precondition of Cannon.fire(), and successfully subtracts Ball from $\text{res}_f$ yielding Unit. Then both implementation and abspec invoke Cannon.fire() and receive the same return value $r$. By $\text{ASSUME}(\lambda\text{res} . \text{res} = \text{Unit} \& \& r = 1)$ for any taken resource $\text{res}$, we can assume $\text{res} = \text{Unit}$ $\& \& r = 1$, and thus add Unit to $\text{res}_f$ yielding Unit. Since $r = 1$, both implementation and abspec print 1. Finally, we can trivially satisfy $\text{GUARANTEE}(\lambda\text{res} . \text{res} = \text{Unit})$ by not updating the module and function resources and choosing $\text{Unit}$ for $\text{res}$. It is important to note that for $\text{NUM\_FIRE} = 2$ the above proof breaks down since at the second iteration we do not have Ball anymore and thus cannot satisfy $\text{GUARANTEE}(\lambda\text{res} . \text{res} = \text{Ball})$.

Similarly, we can prove $l_{\text{Cannon}} \leq_{\text{ctx}} [S_{\text{Main}} \cup S_{\text{Cannon}} \bowtie (A_{\text{Cannon}}, \sigma_{\text{Cannon}}) : S_{\text{Cannon}}]$. This time we set the module-local relational invariant to be $(\text{powder} = 1 \land \text{res}_m = \text{Ready}) \lor (\text{powder} = 0 \land \text{res}_m = \text{Fired})$, which initially holds. Then when Cannon.fire() is invoked, by $\text{ASSUME}(\lambda\text{res} . \text{res} = \text{Ball})$.

\(^4\)The dual to (standard or demonic) nondeterminism is called angelic nondeterminism in the literature [Back and Wright 2012; Bodik et al. 2010; Koenig and Shao 2020; Tyrrell et al. 2006].
res == Ball for any taken resource res, we can assume res == Ball and thus add Ball to res_f yielding Ball. Now due to the relational invariant, we have two cases. First, when powder == 0 && res_m == Fired, the refinement trivially holds since res_m + res_f == Undef and thus the abspec triggers UB. Second, when powder == 1 && res_m == Ready, both implementation and abspec assign 1 to r and print 1; the implementation decrements powder by 1 yielding 0 while for GUARANTEE(res. res == Unit && r == 1) the abspec updates (res_m, res_f) to (Fired, Unit), which is frame-preserving, and chooses Unit for res to satisfy the postcondition and successfully subtract Unit from res_f yielding Unit; finally both return the same value 1 and establish the relational invariant with powder == 0 && res_m == Fired. It is important to note that invariants relating implementations and abspecs like (powder == 1 && res_m == Ready) v (powder == 0 && res_m == Fired) above do not appear in the abspecs, but only as a part of simulation proofs.

Finally, we can compose the abspecs to erase the specification parts:

\[
\text{Beh}(\{S_{\text{Main}} \cup S_{\text{Cannon}} \ni (A_{\text{Main}}, \sigma_{\text{Main}}) : S_{\text{Main}}\} \circ \{S_{\text{Main}} \cup S_{\text{Cannon}} \ni (A_{\text{Cannon}}, \sigma_{\text{Cannon}}) : S_{\text{Cannon}}\}) \subseteq \text{Beh}(A_{\text{Main}} \circ A_{\text{Cannon}})
\]

We can prove this theorem, called spec erasure theorem, as follows. To discharge the initial ASSUME of Main.main() (i.e., to replace it with skip), we just need to choose an initial resource \(\sigma_{\text{main}}\) to Main.main(), which will be Ball here, and show that (i) it is consistent with the initial module-local resources (i.e., \(\sigma_{\text{main}} + \sigma_{\text{Main}} + \sigma_{\text{Cannon}} != \text{Undef}\)) and (ii) it satisfies the precondition of Main.main() (i.e., \(\sigma_{\text{main}} == \text{Ball}\)). Then each remaining ASSUME(Cond) with a predicate Cond on PCM_{Cannon} is discharged by the immediately preceding GUARANTEE(Cond) with the same predicate. To prove this, we first show that consistency of the whole resources (i.e., those stored in all res_m and res_f) is invariant: the consistency holds initially because we have shown it by (i) above, and is preserved by GUARANTEE(Cond); ASSUME(Cond) because the frame-preserving update via fpu preserves it by definition and, by (⋆) above, the subtracted resource res in GUARANTEE is immediately added back in ASSUME. Then we can complete the proof by discharging all the assumptions in ASSUME, again by (⋆): assume(Cond(res)) is discharged by guarantee(Cond(res)), and assume(res_m + res_f != Undef) by the above invariant (i.e., consistency of the whole resources). Note that the spec erasure theorem holds in general among any compatible abspecs: for example, even when \(\text{NUM\_FIRE} == 2\), the above erasure holds.

To conclude, the most important idea in AL is to give an illusion of passing logical information via choose and take in an operational way. In the next section, we will see how this powerful mechanism can be used to model various logical features seamlessly.

## 3 ADVANCED FEATURES AND EXAMPLES OF ABSTRACTION LOGIC

In this section, we will demonstrate a general version of abstraction logic with five advanced features: (i) dealing with unknown contexts, (ii) proving and exploiting purity (i.e., absence of side effects), (iii) decomposing and reusing verification tasks via gradual abstraction, (iv) abstracting function arguments and return values, and (v) reasoning about function pointers. We will introduce them by walking through various examples.

### 3.1 Dealing with unknown contexts

Unlike in the previous section where we composed abspecs for the whole modules, here we will see how to compose those for only selected modules, called friends, while still allowing them to interact with arbitrary context modules, called contexts (i.e., establishing contextual refinement as a result).
For this, our first observation is that there is a specification that every module satisfies. Specifically, one can easily see the following holds: for any module C in EMS,

\[ C \leq_{\text{ctx}} [S_v \times (C, \epsilon) : S_v] \]

where \( \epsilon \) is the identity for a PCM in consideration and \( S_v \) has \( s_v = \{ \text{True} \} \) for every function \( f \) in the scope (i.e., the first \( S_v \) above specifies all the functions invoked by \( C \) while the second \( S_v \) all the functions defined by \( C \)). The essential reason why every module can satisfy the above CR is because specifications in AL do not require safety, unlike in SL.

Although we can give specifications to arbitrary contexts as above, we still have to address the problem that the specifications for contexts are not compatible with those for friends. Specifically, the contexts assume \( S_v \) for each module \( F \) among the friends while its specification \( S_F \) may not be \( S_v \). We solve this problem by allowing abspecs to provide two different behaviors: those satisfying intended specifications when invoked by the friends; and those satisfying \( S_v \) when invoked by the contexts. To enable this, we add a special mechanism to EMS that allows a callee to get the caller’s module name, so that the callee can behave differently depending on who’s the caller.

As an example, consider the module \( \text{Mem} \) given in Fig. 3. The implementation \( I_{\text{Mem}} \) is directly written in EMS, which provides a CompCert-like memory model for the IMP language. Here, to see what, e.g., \( \text{[p: ptr, v: val]}? \) in store means, note that in EMS every function takes a value of type \( \text{Any} \), which can be seen as the set of all mathematical values, and also returns an \( \text{Any} \) value, while the IMP language supports values of type \( \text{val}^5 \) consisting of 64-bit integers (\( \text{int64} \)) and function and memory pointers (\( \text{ptr} \)). Therefore, when defining the semantics of IMP in EMS, we pack arguments to a function into a single value of type list \( \text{val} \) and upcast it into \( \text{Any} \), and conversely downcast and unpack a given \( \text{Any} \) argument to a list of values of expected types, where we trigger UB if the downcast or the unpacking fails. The notation \( \text{[p: ptr, v: val]}? \) denotes such downcast and unpacking of an \( \text{Any} \) argument into a list of two values of types \( \text{ptr} \) and \( \text{val} \). Now we see what \( I_{\text{Mem}} \) does. alloc\((n)\) allocates a memory block consisting of \( n \) cells, each of which can store a value of type \( \text{val} \), and returns the pointer pointing to the beginning of the block; free\((p)\) deallocates the cell pointed to by \( p \); load\((p)\) reads a value from the cell pointed to by \( p \) and returns it; and store\((p, v)\) stores the value \( v \) in the cell pointed to by \( p \).

\(^5\)To support a compilation to CompCert, \( \text{val} \) also contains the special value undefined.
Now we see how the abspec for $\text{Mem}$, given in Fig. 3, is defined, where each function consists of two definitions, $\text{friend}$ and $\text{context}$. Concretely, the $\text{friend}$ definitions are all TRIVIAL, which can be simply understood as skip for now (see §3.2 for details), while the $\text{context}$ definitions are identical to their implementations. The intention is that the former defines its behaviors when invoked by friends and the latter by contexts. Although we do not know which modules will be friends yet, we can still locally verify the following CR for any specification $S$ with $\sigma_{\text{Mem}}$. $S_{\text{Mem}}$ is given in Fig. 3,

$$I_{\text{Mem}} \leq_{\text{ctx}} [S \times (A_{\text{Mem}}, \sigma_{\text{Mem}}) : S_{\text{Mem}}]$$

Here the EMS semantics of each function $f$ in $[S \times (A_{\text{Mem}}, \sigma_{\text{Mem}}) : S_{\text{Mem}}]$ is given by intersecting the semantics of $\text{friend}$ and that of $\text{context}$. Specifically, we can intersect them by:

$$\text{var } b = \text{take}(\text{bool}); \text{ if } (b) \text{ then } C_{\text{friend}} \text{ else } C_{\text{context}}$$

where the semantics $C_{\text{friend}}$ for $f$ is generated from the $\text{friend}$ definition of $f$ in $A_{\text{Mem}}$ together with its specification $S \times S_{\text{Mem}}$ (and $\sigma_{\text{Mem}}$) in the way we have seen in the previous section; similarly for $C_{\text{context}}$ but with the $\text{context}$ definition and $S \times S$. Such intersection makes sense because it is essential to establish refinement between $I_{\text{Mem}}$ and $A_{\text{Mem}}$ for both friends and contexts. It is important to note that the specification $S \times S_{\text{Mem}}$ for $C_{\text{context}}$ means that when we prove $C_{\text{context}}$ satisfies $S_{\text{Mem}}$, we can still rely on the intended assumptions $S$ about friends when it invokes their functions. We will see such examples in §3.2 and §3.4.

For such abspecs with $\text{friend}$ and $\text{context}$, we have a general spec erasure theorem yielding contextual refinement (i.e., under arbitrary contexts).

**Theorem 3.1.** Given a global PCM $\Sigma$ (including all PCMs of interest) and abspecs $[S \times (A_i, \sigma_i) : S_i]$ w.r.t. $\Sigma$ for $i \in \{1, \ldots, n\}$ with any $S \supseteq S_1 \cup \ldots \cup S_n$, suppose that their module names (i.e., friends) are $N = \{\text{name}_1, \ldots, \text{name}_n\}$, and for any argument value $v$ to $\text{Main.main}$, there is an initial resource $\sigma$ to $\text{Main.main}$ such that $\sigma + \sigma_1 + \ldots + \sigma_n \vdash \text{Undef}$ and, if $\text{Main.main}$ is among the friends, $(v, \sigma)$ satisfies its precondition. Then we have the following:

$$[S \times (A_i, \sigma_i) : S_i] \circ \ldots \circ [S \times (A_n, \sigma_n) : S_n] \leq_{\text{ctx}} [A_1]_N \circ \ldots \circ [A_n]_N$$

Here we can understand $S \supseteq S'$ as $S \supseteq S'$ though it has a slightly more general definition (see §4 for details). Also the semantics of a function $f$ in $[A_i]_N$ is defined by combining its $\text{friend}$ semantics $C_{\text{friend}}$ and its $\text{context}$ semantics $C_{\text{context}}$ in $A_i$ as follows:

$$\text{if } (\text{get.caller}() \in N) \text{ then } C_{\text{friend}} \text{ else } C_{\text{context}}$$

where $\text{get.caller}()$ is supported by EMS and returns the module name of the caller. Also we henceforth call such $A_i$ pre-abstraction and such $[A_i]_N$ abstraction. Note that since the theorem establishes contextual refinement, the contexts are completely unrestricted (e.g., they may be unsafe, make system calls, or make mutually recursive calls to the friends).

Now we discuss the details of $S_{\text{Mem}}$. Here we ignore the measure parameter $d$ (used to prove termination) and $\_\_\_$ in $S_{\text{Mem}}$, which will be discussed in §3.2 and §3.4. First, $\uparrow$ is the upcast operator (i.e., $\uparrow x$ is a value of type Any for $x$ of any type $X$) and $\uparrow \text{val} = \{ \uparrow v | v \in \text{val} \}$. The parameters $x$ and $r$ are bound to argument and return values. Then $S_{\text{Mem}}$ is a standard specification for such memory operations that one would write in modern separation logics such as Iris [Jung et al. 2018]. Specifically, the pre and post conditions define predicates on resources (i.e., $\Sigma \rightarrow \text{Prop}$, which we call $\text{rProp}$) when values for the quantifiers and argument are given; and the separating conjunction $\ast$, magic wand $\rightarrow$, lifting $\uparrow$ of $\text{Prop}$ to $\text{rProp}$, and existential and universal quantifiers for $\text{rProp}$ are defined in the standard way. Also, the PCM $\text{Auth}(p \text{ptr} \rightarrow \text{Ex}(\text{val}))$ is a standard authoritative PCM and the points-to predicate $p \mapsto \ell$, capturing that the pointer $p$ points to the
beginning of consecutive cells that contain the values in \( \ell \), is derived in the standard way satisfying
the following law:
\[
p \mapsto v :: \ell \iff (p \mapsto [v]) \ast (p + 8 \mapsto \ell)
\]
Note that in AL, universal quantifiers such as \( \forall(p, v) : \text{ptr} \times \text{val} \) above are also modeled via \texttt{choose}
and \texttt{take}. The reason is because values for those quantifiers are essentially determined by the
callers, and therefore the caller \texttt{chooses} a value for the quantifier and the callee \texttt{takes} the value as
we have seen in the previous section.
Now we briefly discuss how to verify \( I_{\text{Mem}} \): for any specification \( S \),
\[
I_{\text{Mem}} \leq_{\text{ctx}} [S \times (A_{\text{Mem}}, \sigma_{\text{Mem}}) : S_{\text{Mem}}]
\] (1)
As usual, we first set up a module-local relational invariant and prove refinement between \( I_{\text{Mem}} \)
and \( [S \times (A_{\text{Mem}}, \sigma_{\text{Mem}}) : S_{\text{Mem}}] \), which is split into two cases because the abspec is defined as the
intersection of \texttt{friend} and \texttt{context}: proving (i) that \( I_{\text{Mem}} \) refines the \texttt{friend} definitions of \( A_{\text{Mem}} \)
under \( S \times S_{\text{Mem}} \) and (ii) that \( I_{\text{Mem}} \) refines the \texttt{context} definitions of \( A_{\text{Mem}} \) under \( S \times S_{s} \), where both
proofs involve preservation of the (common) relational invariant, which essentially captures that
the \texttt{friend} and \texttt{context} definitions work in harmony (i.e., they do not interfere each other’s
reasoning in any interleaved invocations of the two definitions). Specifically, the invariant says that
the blocks allocated in the implementation are split into two groups such that in the abspec, one of
the groups is allocated at the same addresses\(^6\) (performed by \texttt{context}) and the other resides in the
module-local resource (but not in the memory) in terms of the points-to predicate (performed by
\texttt{friend}). The reason why this invariant is preserved even when the \texttt{context} definitions are invoked
with arbitrary pointers is essentially because when a context tries to access the blocks allocated
by friends by forging their addresses, the invariant guarantees that in the abspec no blocks are
allocated at those addresses so that such accesses always trigger \texttt{UB}, which immediately completes
the refinement. Except the preservation of the invariant, the proof of \( (ii) \) is straightforward because
it establishes refinement between identical definitions; and that of \( (i) \) essentially amounts to a
standard SL proof for those specifications together with a termination proof, which will be discussed
in the following section.

3.2 Proving and exploiting purity

Now we discuss how to express, prove and exploit purity of an abspec of a function. Note that
it is possible that even though an implementation has impurity, if the impurity only changes the
module’s local state, its abspec can be made pure by migrating the impurity to its specification (i.e.,
pre and post conditions). Indeed this is the case for the module \texttt{Mem} and we will see how we can do
it in this section.

To see this clearly, we need another example, which is the module \texttt{Stack} given in Fig. 4 and
implemented using the module \texttt{Mem}. Concretely, \( I_{\text{Stack}} \) presents the EMS semantics of an IMP
program\(^7\) that implements stacks using linked lists, where \texttt{new()} creates a new stack; \texttt{push(}}\texttt{stk, v)}
 Pushes the value \( v \) into the stack \( \text{stk} \); and \texttt{pop(stk)} pops a value from \( \text{stk} \) and returns it if \( \text{stk} \) is
nonempty; otherwise returns \( \emptyset \).

Then \( A^{I}_{\text{Stack}} \) presents an abstract version of the functions, which \texttt{module-locally} manage a pool
of mathematical lists using \texttt{ptr} values as their handles (defined as \texttt{ptr} \rightarrow \text{option (}}\text{list } \text{val})
. Concretely, \texttt{new()} nondeterministically chooses an \texttt{unused} handle (via \texttt{choose} and \texttt{guarantee}),
registers the empty list with the handle in the pool and returns the handle; \texttt{push(handle, v)} gets
the list with handle from the pool (if fails, trigger \texttt{UB}) by \texttt{unopt?} in case of failure) and then updates

\(^6\)This is possible because our allocator is nondeterministic.

\(^7\)The downcast to and upcast from \texttt{val} (with \texttt{UB} in case of failure) around a function call are omitted for syntactic clarity.
I_{Stack} := [Module Stack]
def new([]?)
  var stk := Mem.alloc(1);
  Mem.store(stk, NULL);
  stk
def push([stk: val, v: val]?)
  var node := Mem.alloc(2);
  var hd := Mem.load(stk);
  Mem.store(node, v);
  Mem.store(node+8, hd);
  Mem.store(stk, node)
def pop([stk: val]?)
  var hd := Mem.load(stk);
  if hd == NULL
    then 0
  else
    var v := Mem.load(hd);
    var next := Mem.load(hd+8);
    Mem.store(stk, next);
    Mem.free(hd); Mem.free(hd+8);
    v

A^1_{Stack} := [Module Stack]
local pool := (\lambda _. None)
  : ptr \rightarrow option (list val)
def new =
friend, context([]?)
  var handle := choose(ptr);
  guarantee(pool handle == None);
  pool := pool[handle := Some []];
  handle
def push =
friend, context([handle: ptr, v: val]?)
  var stk := unopt?(pool handle);
  pool := pool[handle := Some (x::stk)]
def pop =
friend, context([handle: ptr]?)
  var stk := unopt?(pool handle);
  match stk
    with |
      | [] => 0
      | v :: stk' =>
        pool := pool[handle := Some stk'];
        v
end

S^1_{Stack} := \{ Stack.new : s_0, Stack.push : s_0, Stack.pop : s_0 \}
\sigma^1_{Stack} := \epsilon

where s_0 = \forall x : (). \{ \lambda x_0 d. \text{ if } d = \text{None} \land x = x_0 \text{ then } \{ \lambda r_0, \text{ if } r = r_0 \text{ then } \}

**Fig. 4.** An implementation and its first abspec for the module Stack.
Now we discuss (i): how to enforce and specify purity in AL. The notion of purity of a function \( f \), saying that \( f \) does not produce any side effects, can be mostly enforced by defining the pre-abstraction of \( f \) as an IPC. Since IPC only allows invoking pure functions, verifying against IPC essentially amounts to proving the absence of side effects except for non-termination. Therefore, the remaining questions are how to enforce termination, how to specify purity and how to make a pure call.

We can answer all the question by adding the measure parameter \( d \) to preconditions, which can be passed from a caller to the callee via choose and take. First, we define the type of measures to be \( \text{option ord} \) with \( \text{ord} \) the set of ordinals\(^8\) with a well-founded order \( < \) and define a relation \( \sqsubset \) between them by the following two cases:

\[
\text{Some } o \sqsubset \text{Some } o' \text{ with } o < o' \in \text{ord} \quad \quad d \sqsubset \text{None with } d \in \text{option ord}
\]

Second, invoking a function with a measure \( \text{Some } _\_ \) is considered as a pure call and the EMS semantics of a function in an abspec, when invoked with \( \text{Some } _\_ \), is defined to be an IPC. Third, to enforce termination, when a function \( f \) is invoked with a measure \( d \), for each function call made inside the invocation we add the guarantee that it should pass \( \text{i.e., choose} \) a measure \( d' \) with \( d' \sqsubset d \). Then it is guaranteed that a pure call \( \text{i.e., with Some } o \) can only make pure calls as sub calls (thereby producing no side effects other than non-termination) and should terminate because any measure \( d \sqsubset \text{Some } o \) should be \( \text{Some } o' \) with \( o' < o \). Note that an impure call \( \text{i.e., with the measure None} \) can still make any calls because we have \( d \sqsubset \text{None} \) for any measure \( d \) including \text{None}.

Then, we achieve (iii): the spec erasure theorem can soundly eliminate all IPCs in the resulting abstractions. Also, note that the friend definition of \( f \) in an abspec only describe the impure behavior of \( f \) since its pure behavior is defined to be an IPC.

With this in mind, we revisit the module Mem. First, all the specifications have \( d = \text{Some } _\_ \) in their preconditions, which implies that only pure calls to those functions can be made. Second, since the functions in Mem do not allow any impure calls to them, their friend definitions are never executed, which we can guarantee by defining them as NB \( \text{i.e., TRIVIAL}=\text{NB} \). Then, in the abstraction \( [A_{\text{Mem}}]_N \) for Mem after applying the spec erasure theorem with friends \( N \), we have the functions that trigger NB if invoked by the friends, and do the original jobs otherwise. This implies that the friends are guaranteed not to invoke any memory operations \( \text{i.e., all the calls to Mem by the friends are eliminated in their abstractions} \). Note that using the fact that NB contextually refines any possible definitions, we can also revert the abstraction \( [A_{\text{Mem}}]_N \) back to \( l_{\text{Mem}} \) \( \text{i.e., } [A_{\text{Mem}}]_N \leq \text{ctx } l_{\text{Mem}} \). Also note that as discussed above, the implementation \( l_{\text{Mem}} \) can be seen as impure because, \( \text{e.g., calls to store} \) have impact on subsequent calls to load, while its pre-abstraction, IPC, for friends are indeed pure and thus can be eliminated.

Finally, we can verify \( I_{\text{Stack}} \): for any \( S \sqsupseteq S_{\text{Mem}} \),

\[
I_{\text{Stack}} \leq \text{ctx } [S \times (A_{\text{Stack}}^1, o_{\text{Stack}}^1) : S_{\text{Stack}}^1]
\]

(2)

For this, we set up the module-local invariant saying that the lists in the pool are matched with the linked lists stored in the module-local resource of Stack in terms of the points-to predicate, which are obtained via IPCs to the memory functions with \( S_{\text{Mem}} \). Then, one can easily establish a simulation proof preserving the invariant.

3.3 Decomposing and reusing verification tasks via gradual abstraction

Although the abstraction \( [A_{\text{Stack}}^1]_{\{\text{Mem, Stack}\}} \) obtained by applying the spec erasure theorem for the friends Mem and Stack, can be directly used by other modules, it would be better to provide useful logical specifications for Stack like those we provided for Mem.

\( ^8\)We developed our own Coq library for ordinals, which will be published elsewhere.
\[
A^2_{\text{Stack}} := \langle \text{Module Stack} \rangle
\]
\[
\text{local} \; \text{pool} := (\lambda_. \text{None})
\]
\[
: \text{ptr} \rightarrow \text{option (list val)}
\]

\(\sigma^{2A}_{\text{Stack}} := \bullet e \in \text{Auth (ptr} \rightarrow \text{Ex (list val))} \subseteq \Sigma\)

\[
S^{2A}_{\text{Stack}} := \{\text{Stack.new: } \forall \cdot ()\}
\]
\[
\{\lambda x.d. \; \exists \cdot (\text{list val}) \subseteq \{\lambda x.d. \; \exists \cdot (\text{list val})\}
\]

\[
\begin{align*}
\sigma^{2B}_{\text{Stack}} := & \bullet e \in \text{Auth (ptr} \rightarrow \text{Option (Ag (P(val))}} \subseteq \Sigma \\
S^{2B}_{\text{Stack}} := & \{\text{Stack.new: } \forall P : \text{P(val)}\}
\end{align*}
\]
\[
\{\lambda x.d. \; \exists \cdot (\text{list val}) \subseteq \{\lambda x.d. \; \exists \cdot (\text{list val})\}
\]

Fig. 5. Two abspecs on top of the first abstraction for the module Stack

Fig. 5 shows two such specifications \(S^{2A}_{\text{Stack}}\) and \(S^{2B}_{\text{Stack}}\) for Stack. Then we can separately verify the previous abstraction against the two specifications together with the pure pre-abstraction \(A^2_{\text{Stack}}\). Specifically, we prove the following: for any specification \(S\),

\[
[A^1_{\text{Stack}}\{\text{Mem.Stack}\}] \leq_{\text{ctx}} [S \triangleright (A^2_{\text{Stack}}, \sigma^{2A}_{\text{Stack}}) : S^{2A}_{\text{Stack}}] \tag{3}
\]

\[
[A^1_{\text{Stack}}\{\text{Mem.Stack}\}] \leq_{\text{ctx}} [S \triangleright (A^2_{\text{Stack}}, \sigma^{2B}_{\text{Stack}}) : S^{2B}_{\text{Stack}}] \tag{4}
\]

Here both \(S^{2A}_{\text{Stack}}\) and \(S^{2B}_{\text{Stack}}\) only allow pure calls to the functions by requiring \(d = \text{Some -}\) and the pre-abstraction \(A^2_{\text{Stack}}\) is the same as \(A^1_{\text{Stack}}\) for context, and NB for friend, as we have done for Mem. The two specifications provide different benefits to the client: the former precisely tracks the contents of a stack via the predicate is_stk \(h \ell\) saying that the stack with handle \(h\) in the pool coincides with \(\ell\), while the latter maintains a certain property for a stack via the predicate is_bag \(h P\) saying that all the elements in the stack with handle \(h\) satisfy the property \(P\) and furthermore allows duplicating the resource thereby permitting multiple modules to update the stack at the same time as long as the pushed elements satisfy \(P\). The proof structures for these two verifications are similar to that for the verification for Mem: is_stk and is_bag are defined similarly as the points-to predicate using standard authoritative PCMs; the module-local relational invariant for the former says each list in the pool is matched with the corresponding list stored in the module-local resource in terms of is_stk; and that for the latter says all the elements of each list in the pool satisfy the corresponding property stored in the module-local resource in terms of is_bag.

Benefits of such gradual abstraction for Stack are two-fold. First, we can achieve separation of concerns via gradual abstraction. For example, in the first abstraction for Stack, the verification focused on abstracting linked lists into mathematical lists without thinking about providing useful specifications to the client, while in the second abstractions, the verifications focused on providing such specifications based on mathematical lists. Second, gradual abstraction increases reusability of verification results. For example, for Stack, we essentially reused the first verification result turning linked lists into mathematical lists, in the two verifications providing different specifications to the client. Also note that in final abstractions obtained by applying the spec erasure theorem either with the is_stk specification or with the is_bag specification, the result of the first abstraction,
which is based on mathematical lists instead of linked lists.

Indeed, in abstraction logic, such abstraction can be easily achieved.

3.4 Abstracting function arguments and return values

Since friends are enforced to respect each other’s specification by the spec erasure theorem, it would make sense to abstract even function arguments and return values among the friends. Indeed, in abstraction logic, such abstraction can be easily achieved.

To see this, we consider the example given in Fig. 6. In the implementation \( I_{\text{Echo}} \), \( \text{Echo}().\text{echo}() \) creates a new stack, \( \text{stk} \); invokes \( \text{Echo}().\text{input}(\text{stk}) \), which repeatedly gets an integer via \( \text{IO}.\text{getint}() \) and pushes it into \( \text{stk} \) until getting 0; and then invokes \( \text{Echo}().\text{output}(\text{stk}) \), which repeatedly pops an integer from \( \text{stk} \) and outputs it via \( \text{IO}.\text{putint}() \) until the stack is empty (i.e., 0 is returned). The pre-abstraction \( A_{\text{Echo}} \) directly uses mathematical lists instead of using the module \( \text{Stack} \). Concretely, the \textbf{friend} definitions of input and output take a mathematical list as an argument, instead of a \texttt{val} value. The argument \( \text{stk}!:\text{list int64} \) denotes that the \texttt{Any} value given as an argument is downcast to \texttt{list int64} and if it fails, triggers \( \text{NB} \), which guarantees that every friend invokes them with a mathematical list. On the other hand, we will treat the \texttt{IO} module as an unrestricted context (i.e., specified as \( S_s \)) and thus trigger \( \text{UB} \) if the downcast from an \texttt{Any} value given by \( \text{IO}.\text{getint}() \) to \texttt{int64} fails, which is denoted by \( \text{var v:? int64 := IO.getint()} \).

It is important to note that the \textbf{context} definitions of input and output immediately trigger \( \text{UB} \), which specifies that contexts are not allowed to invoke them because they are intended to be such \textit{internal} functions whose arbitrary invocation may interfere the behavior of the module \( \text{Echo} \). On the other hand, echoes have the same definition for \textbf{friend} and \textbf{context} with \( s_s \), which specifies that it can be freely invoked by both friends and contexts since it does not interfere the behavior of \( \text{Echo} \).

\footnote{It shows the semantics of an IMP program, omitting the downcast and upcast around function calls.}
Now we see how we support the abstraction of argument and return values of input and output from val to list int64. For this, AL adds an extra argument $x_a$, called abstract argument, and an extra return value $r_a$, called abstract return value, to the specifications. Then we can specify relationship between concrete ones and abstract ones in the pre and post conditions. For example, the specifications of input and output say that the concrete argument $x$ contains a handle $h$, the abstract one $x_a$ a list $ℓ$, and they satisfy is_estk $h$ $ℓ$ (defined as $¬\text{nonzero}(ℓ) \land \text{is_stk}$ $h$ $ℓ$) stating that $ℓ$ only has non-zero elements and $h$ is a handle for a stack containing $ℓ$; and similarly for concrete and abstract return values.

Then we can define the abspec semantics to give an illusion of passing abstract values as follows. When we make a call to $f$ with an abstract value (e.g., Echo.input($\langle v::stk\rangle$)), we choose a concrete value, guarantee that they are related as specified in the precondition of $f$, and pass the concrete value as a real argument. Conversely, in the friend definition of $f$, we first receive a concrete value as a real argument, and then take an abstract value, assume that they are related as specified in the precondition of $f$ and pass the abstract value as an argument to the friend definition. The abspec semantics also does similarly for return values. From these constructions, it follows that the spec erasure theorem can soundly eliminate concrete values and directly pass abstract ones in the final abstractions.

For verification of Echo, we use $S^{2A}_{\text{Stack}}$ as a specification for the module Stack and prove

$$I_{\text{Echo}} \leq_{\text{ctx}} [S \times (A_{\text{Echo}}, σ_{\text{Echo}}) : S_{\text{Echo}}]$$

for any $S \subseteq S_{\text{Echo}} \cup S^{2A}_{\text{Stack}} \cup S_x$ with $S_x$ for the module IO. The proof is quite straightforward: the local simulation argument directly follows from the precondition of each function without using any module-local invariant or resource. Note that this proof essentially involves cyclic reasoning since Echo.input and Echo.output make recursive calls; however, it does not require any special treatment.

Now we compose all the verification results so far as follows. By applying the spec erasure theorem to Equations (1) and (2), and to Equations (3) and (5), we have

$$I_{\text{Mem}} \circ I_{\text{Stack}} \circ I_{\text{Echo}} \leq_{\text{ctx}} [A_{\text{Mem}}]\{\text{Mem.Stack}\} \circ [A^1_{\text{Stack}}]\{\text{Mem.Stack}\}$$

Then by horizontal and vertical compositionality of CR, we have

$$I_{\text{Mem}} \circ I_{\text{Stack}} \circ I_{\text{Echo}} \leq_{\text{ctx}} [A^2_{\text{Stack}}]\{\text{Stack.Echo}\} \circ [A_{\text{Echo}}]\{\text{Stack.Echo}\}$$

Furthermore, the following three CRs hold trivially by exploiting NB in friend and UB in context.

$$[A_{\text{Mem}}]\{\text{Mem.Stack}\} \leq_{\text{ctx}} I_{\text{Mem}} \circ [A^2_{\text{Stack}}]\{\text{Stack.Echo}\} \leq_{\text{ctx}} [A_{\text{Echo}}]\{\text{Stack.Echo}\} \leq_{\text{ctx}} [A_{\text{Echo}}]\{\text{Echo}\}$$

Therefore, we can further simplify the top-level abstraction as follows.

$$I_{\text{Mem}} \circ I_{\text{Stack}} \circ I_{\text{Echo}} \leq_{\text{ctx}} I_{\text{Mem}} \circ [A^1_{\text{Stack}}]\{\} \circ [A_{\text{Echo}}]\{\}$$

We conclude the sequence of examples shown so far with a few remarks. First, the module IO is a part of the context, so that it can be arbitrary. For example, it is completely valid for IO.getint and IO.putint to make mutually recursive calls to Echo.echo although calls to Echo.input or Echo.output by IO will trigger UB. Second, it is possible to leave useful assumptions and guarantees in the final abstractions, which may be necessary or helpful for further abstractions. For example, guarantee(pool handle == None) in $A^1_{\text{Stack}}$ can be seen as such a guarantee. As a further example, in $A_{\text{Echo}}$, we can also insert assume(is_prime(v)) after the call IO.getint() and guarantee(is_prime(h)) before the call IO.putint(h). Third, the definition $s_r$ (given in $S^1_{\text{Stack}}$ of Fig. 4) says that it must be an impure call and the concrete and abstract arguments (also return values) coincide, which is needed to prove that every EMS function semantics satisfies $s_r$. Finally,
Echo.echo() may terminate or not depending on the behavior of the IO module, which may even behave nondeterministically, and thus its termination may be nondeterministic as well. However, this does not cause any problem in AL because we are not proving termination or non-termination for Echo; rather we guarantee preservation of termination: if the abstraction terminates, so does the implementation.

3.5 Reasoning about function pointers

In this section, we present a general pattern for doing higher-order reasoning in AL without requiring any special support. For this, consider the simple example given in Fig. 7. The function RP.repeat(f, n, m) in I_{RP} recursively apply \(*f, n\) times, to \(m\), where \(*f\) is the function pointed to by the pointer value \(f\). The definitions in I_{SC} and I_{AD} are straightforward to understand except that \&SC.succ is the pointer value pointing to the function \SC.succ. For RP and SC, we give the pure pre-abstractions A_{RP} and A_{SC}, where we maximally simplified them for presentation purposes. For AD, the pre-abstractions A_{AD} turns the call to RP.repeat into the native addition with the non-negativity assumption about the first argument.

To specify RP.repeat, we essentially need to embed expected specifications for argument functions \(f\) inside the specification of \(\text{RP-repeat}\). Directly supporting this would make the definition of specification more involved since we need to solve a recursive equation to define it. Although such an equation could be solved by employing the step-indexing technique, here we propose a more elementary solution that does not introduce any cyclic definition.

Now we see how to do it. First, we give a higher-order specification H_{RP} to the module RP, given in Fig. 7, which is given as a function from specifications to specifications. We can understand that the input specification \(S_{f}\) includes the specifications for all the functions that are passed to \RP.repeat by friends. Then \(H_{RP}(S_{f})\) gives a specification for \RP.repeat that only allow those functions in \(S_{f}\) to be given as an argument to \RP.repeat. With this intuition, we see the definition of \(H_{RP}(S_{f})\): for arguments \(f, n, m\) and a mathematical function \(f_{\text{sem}}\), we require \(S_{f}\) to include the expected specification for \(*f\) saying that \(*f\) is pure with measure \(\text{Some } \omega\) and returns \(f_{\text{sem}}(m)\) for any argument \(m\). Here \(\omega\) is the smallest ordinal bigger than every natural number and thus we can allow \(*f\) to have any \textit{finite} recursion depth. Also we require \RP.repeat to be pure with measure at least \text{Some } (\omega + n)^{10} because \RP.repeat makes recursive calls with depth \(n\) followed by a call to \(*f*\).

\[^{10}\text{d} \geq \text{Some } \alpha \text{ is defined as } 0 \alpha' \geq \alpha. d = \text{Some } \alpha'.\]

Fig. 7. Implementations and their specifications for the modules RP, SC, AD

\[I_{RP} := \text{[Module RP]} \quad \begin{array}{c}
\text{def repeat}(f: \text{ptr}, n: \text{int64}, m: \text{int64}) \equiv \\
\text{if } n \leq 0 \text{ then } m \\
\text{else } \{ \text{var } v := (*f)(m); \\
\text{RP-repeat}(f, n-1, v) \}\end{array} \quad \begin{array}{c}
I_{SC} := \text{[Module SC]} \\
\text{def succ}(m: \text{int64}) \equiv m + 1 \quad I_{AD} := \text{[Module AD]} \\
\text{def add}(n: \text{int64}, m: \text{int64}) \equiv \text{RP-repeat}(\&SC.succ, n, m) \\
\text{def add = friend.context} \quad \begin{array}{c}
\text{(n:int64, m:int64)} \equiv \\
\text{assume(n > 0); n + m}
\end{array} \end{array} \]

\[A_{RP} := \text{[Module RP]} \quad \begin{array}{c}
\text{def repeat = friend(\_)} \equiv \text{NB context UB} \\
A_{SC} := \text{[Module SC]} \quad \begin{array}{c}
\text{def succ = friend(\_)} \equiv \text{NB context UB}
\end{array} \]

\[H_{BP}(S_{f}) := \{ \text{RP-repeat : } \forall (f, n, m, f_{\text{sem}}): \text{ptr} \times \text{int64} \times \text{int64} \times (\text{int64} \rightarrow \text{int64}). \\
\{ \text{\lambda x . d . r = } \uparrow\![f, n, m] \land n \geq 0 \land d \geq \text{Some } (\omega + n) \land \\
\text{S_{f} \supseteq } \{ *f : \forall m : \text{int64}, (\lambda x . d . r = \uparrow\![m] \land d = \text{Some } \omega^\prime) \land (\lambda r . \text{r = } \uparrow\![f_{\text{sem}}(m)]^\prime) \}\} \}
\]

\[S_{SC} := \{ \text{SC.succ} : \exists m : \text{int64}, (\lambda x . d . r = \uparrow\![m] \land d = \text{Some } \omega) \land (\lambda r . \text{r = } \uparrow\![m + 1]^\prime) \} \]

\[S_{AD} := \{ \text{AD.add : s_{0}} \} \]
Then we can easily verify RP: for any $S_f$ (i.e., no restriction for $f$) and any $S \supseteq (S_f \cup H_{RP}(S_f))$ (since $R_P \mathbin{.} \text{repeat}$ makes a call to $*f$ and itself), we prove

$$I_{RP} \leq_{ctx} [S \mathbin{\times} (A_{RP}, \epsilon) : H_{RP}(S_f)]$$

Also, we can easily verify SC: for any $S$, we prove

$$I_{SC} \leq_{ctx} [S \mathbin{\times} (A_{SC}, \epsilon) : S_{SC}]$$

Then, we can easily verify AD: for any $S_f \supseteq S_{SC}$ (since $SC \mathbin{.} \text{succ}$ is passed to $RP \mathbin{.} \text{repeat}$) and any $S \supseteq H_{RP}(S_f)$ (since $AD \mathbin{.} \text{add}$ makes a call to $RP \mathbin{.} \text{repeat}$), we prove

$$I_{AD} \leq_{ctx} [S \mathbin{\times} (A_{AD}, \epsilon) : S_{AD}]$$

Finally, we can instantiate the above CRs with $S_f = S_{SC}$ and $S = H_{RP}(S_{SC}) \cup S_{SC} \cup S_{AD}$ and apply the spec erasure theorem to them as follows:

$$I_{RP} \circ I_{SC} \circ I_{AD} \leq_{ctx} [S \mathbin{\times} (A_{RP}, \epsilon) : H_{RP}(S_{SC})] \circ [S \mathbin{\times} (A_{SC}, \epsilon) : S_{SC}] \circ [S \mathbin{\times} (A_{AD}, \epsilon) : S_{AD}]$$

(by compositionality of CR)

$$\leq_{ctx} [A_{RP}]_{(RP, SC, AD)} \circ [A_{SC}]_{(RP, SC, AD)} \circ [A_{AD}]_{(RP, SC, AD)}$$

(by spec erasure thm.)

As a more advanced example, we also verified Landin’s knot [Birkedal and Bizjak 2020], which can be found in our Coq development [Author(s) 2021]. Since we do not know of any practical higher-order example for which our approach fails, we believe it is general enough in practice.
4 FORMAL DEFINITIONS OF ABSTRACTION LOGIC

In this section, we present formal definitions, key properties, and the embedding of abspecs and abstraction into EMS. First of all, our Coq formalization largely relies on interaction trees [Xia et al. 2019]. Intuitively, the interaction tree \(\text{itree } E T\) for an event type \(E\) (defining a set of events \(E(X)\) for each set \(X\)) and a return type \(T\) can be understood as a small-step operational semantics that can take a silent step, terminate with a value in \(T\), or trigger an event in \(E(X)\) for any set \(X\), in which case its continuation nondeterministically receives each value in \(X\). We enjoy two benefits of interaction trees: (i) they provide useful combinators, which made our various constructions straightforward, and (ii) they can be extracted to executable programs in OCaml. In particular, all the language constructs shown in the examples so far are simply combinators for itrees. The key combinator we use is the \textit{interpretation} function with states in \(ST\), which has type:

\[
\text{itree } E T \rightarrow (\forall X. E(X) \rightarrow ST \rightarrow \text{itree } E' (X \times ST)) \rightarrow ST \rightarrow \text{itree } E' (T \times ST)
\]

where we use the notation \(t[e_1 \mapsto t_1, \ldots, e_n \mapsto t_n]\) to denote the interpretation of the events \(e_i\) to the (state-indexed) itree \(t_i\) in the itree \(t\) and implicitly drop identical interpretations essentially mapping \(e\) to itself and also drop the state component when \(ST = ()\).

Fig. 8 shows the formal definitions of AL. First, we define two notations \((\text{cond } \Rightarrow X)\) for conditional construction of a set and \(\text{fundef}(E)\) for semantics of a function that takes a value in \(\text{Any}\) and executes by possibly triggering events in the event type \(E\). We first define the primitive events \(E_{\text{prim}}\) consisting of \text{Choose} and \text{Take} for any type \(X\), and \text{Obs} for triggering observable events such as system calls that pass and receive an \text{Any} value; and the events \(E_{\text{EMS}}\) extends \(E_{\text{prim}}\) with \text{Call} for making a function call, \text{Get} and \text{Put} for reading from and writing to the module local state, and \text{GetCaller} for getting the caller’s module name. Then EMS for semantics of a module is defined as the set of triples consisting of a module’s name, an initial module-local state and function semantics triggering events in \(E_{\text{EMS}}\) for (a finite set of) module functions. The events \(E_{\text{PAbs}}\) extends \(E_{\text{EMS}}\) with \text{IPC} for triggering an IPC, and \text{PAbs} for pre-abstraction of a module is defined similarly as EMS except that \(\text{PAbs}\) has a pair of function semantics (for \text{friend} and \text{context}) triggering events in \(E_{\text{PAbs}}\) for each module function.

PCM, the set of PCMs, is defined in a standard way [Jung et al. 2018], where the predicate \(\forall\) indicates whether a resource is defined or not. A specification (for a function) in \(\text{Spec}_{\Sigma}\), parameterized by a global PCM \(\Sigma\), consists of a set \(\Lambda\) over which the universal quantifier in the specification quantifies, and a condition \(c\) that, given a value \(a \in \Lambda\), gives a pair of pre and post conditions. A precondition takes concrete and abstract arguments with a measure and gives a resource proposition, which is a predicate on \(\Sigma\); and similarly for a postcondition but without measure. A collection of specifications in \(\text{Spec}_{\Sigma}\) is a finite map from function names to function specifications. We also define the strengthening relation \(\supseteq\) between specifications, which generalizes the simple inclusion relation following Iris [Jung et al. 2018].

Mod gives a notion of code for a single module (i.e., before loading), which is parameterized by a notion of loading data LD, which happens to be required to form a PCM to combine loading data from all modules and express consistency between them. A module code consists of its own loading data in LD and a function in LD \(\rightarrow\) EMS that, given the global loading data gathered from all the modules, returns its module semantics. A modules code in Mods is simply a list of module codes, which forms basic units in contextual refinement, and linking \(\circ\) between them is the list append.

Then we coinductively define the set of traces, Trace. A trace is a finite or infinite sequence of observable events in ObsEvents, defined as \(\{(\text{Obs } fn \text{ args},r) \mid fn \in \text{string}, \text{args},r \in \text{Any}\}\), possibly ended with one of the four cases: (i) normal termination with an \text{Any} value, (ii) divergence without producing any observable events, (iii) fatal error, or (iv) partial termination. The notion of partial termination can be intuitively understood as terminating the execution at the user’s will.
such as pressing Ctrl 1+C, which is dual to fatal error (i.e., termination due to the program’s fault). This will be clarified in the definition of Beh that gives the set of those traces that can possibly arise when loading and executing a given module’s code. The definition (omitted for brevity; see our Coq development [Author(s) 2021] for details) is defined as usual except that (i) the partial termination, Partial, may occur nondeterministically at any point during execution (capturing that the user can stop the program at any time), and (ii) triggering a Choose (or Take) event is interpreted as taking the union (or intersection) of the behaviors of all possible continuations. Note that triggering UB (i.e., taking from the empty set) can produce all possible traces, which is dual to the interpretation of triggering NB (i.e., choosing from the empty set) that can only immediately terminate with Partial without any other possible traces (capturing that there is no behavior caused by the program after NB is triggered). Finally, we define contextual refinement $\leq_{ctx}$ between modules codes as usual.

In AL, we establish CR using a standard simulation technique that allows module-local relational invariants, $I$, to depend on Kripke-style possible worlds equipped with a preorder ($\sqsubseteq_w$). Then, the (coinductively-defined) greatest simulation relation $\leq_w$ at a given world $w$ relates target states (i.e., the implementation side) and source states (i.e., the abspec side), both of which consist of a module-local state and an itree$^{11}$. Two notable cases are the return and call cases shown below: in the former one has to prove that the invariant $I$ holds at the current or a future world, and relying on that, in the latter, one can assume the invariant holds after every function call.

Fig. 9 formally presents our translation of abspeccs into EMS and that of pre-abstractions into EMS (i.e., abstractions). These translations are done in the same way as we have explained except that, as we mentioned before, instead of requiring frame-preserving updates we allow to update local resources as long as they are consistent with the frame resource given at the latest interaction point. Also note that we used the same macros \texttt{ASSUME} and \texttt{GUARANTEE} for both pre and post conditions although the latter lacks the measure parameter. Here we implicitly cast postconditions to the type of preconditions by making them to ignore the measure parameter.

Now we present our core theorems. The most important one – spec erasure theorem – is already presented in Theorem 3.1. Then we present adequacy of the simulation relation.

**Theorem 4.1 (Adequacy).** For a given pair of module $M_i$ and $M_a$, a possible world $W$ equipped with $\sqsubseteq_w$, and a module-local relational invariant $I$, if each pair of functions with the same name for $M_i$ and $M_a$ are related by the simulation relation $\leq$ for any argument and any module-local states satisfying $I$, then we have the contextual refinement between them:

$$[M_i] \leq_{ctx} [M_a]$$

We also use the following strengthening theorem.

**Theorem 4.2 (Strengthening).** For any $S, S', A, \sigma, S_A$, the following holds:

$$S' \not\equiv S \implies [S \not\Rightarrow A, \sigma : S_A] \leq_{ctx} [S' \not\Rightarrow A, \sigma : S_A]$$

Finally, we briefly discuss how to define the abstraction Safe mentioned in §1. The module Safe $(ns, ns')$ defines each function in $ns'$ whose semantics is simply defined to nondeterministically invoke an arbitrary function in $ns$ with arbitrary arguments any number of times (even infinitely many). Then we have the following theorem.

$^{11}$We also support the stuttering index using our ordinal library, but omit it here for brevity.
\[
\begin{align*}
[A]_N & \overset{\text{def}}{=} (\text{A.name, A.init, } \lambda fn. \text{toAbs}(N, A.funs fn)) \\
toAbs(N, (frd, ctxx)) & \text{ : fundef}(E_{\text{EMS}}) \overset{\text{def}}{=} \lambda x. \\
\text{var} \ mn & := \text{get.caller}(); \\
\text{if}(\text{mn} \in N) \ frd(x)[\text{IPC} \mapsto \text{skip}] \\
\text{else} & \ ctxx(x)[\text{IPC} \mapsto \text{skip}] \\
[S \Rightarrow \sigma: S_0] & \overset{\text{def}}{=} (\text{A.name, (A.init, } \sigma), \\
\lambda \ sns. \text{toAbspec}(S, A.funs fn, S_0 fn)) \\
toAbspec(S, (frd, ctxx), s) & \text{ : fundef}(E_{\text{EMS}}) \overset{\text{def}}{=} \lambda x. \\
\text{var} \ is\_friend & := \text{take}(\text{bool}); \\
\text{if}(\text{is\_friend}) \ abspecFun(S, s, frd)(x) \\
\text{else} & \ abspecFun(S, s, ctxx)(x) \\
abspecFun(S, s, \text{fun: fundef}(E_{\text{PAbs}})) & \overset{\text{def}}{=} \lambda x. \\
\text{var} \ (A, PQ) & := s; \\
\text{var} \ a & := \text{take}(\text{A}); \text{var} \ (P, Q) := PQ(a); \\
\text{var} \ (x_a, d, \text{frm}) & := \text{ASSUME}(P, x, \epsilon); \\
\text{match} \ d \ \text{with} \\
| \ \text{None} & \Rightarrow \text{var} \ (r_a, \text{frm}) := \\
| \ \text{abspecBody}(S, d, \text{frm}, \text{fun}(x_a)) \\
| \ \text{Some} \ o & \Rightarrow \\
| \ \text{var} \ (-, \text{frm}) := \text{abspecIPC}(S, d, \text{frm}); \\
| \ \text{var} \ r_a & := \text{choose}(\text{Any}) \ \text{end}; \\
\text{var} \ (r, -) & := \text{GUARANTEE}(Q, r_a, \text{frm}); \\
r & \ abspecBody(S, d, \text{frm}, \text{body}) \overset{\text{def}}{=} \text{body}[ \\
\text{Call} \ fn \ x_a & \mapsto \lambda frm. \text{abspecCall}(S, d, \text{frm}, fn, x_a), \\
\text{IPC} & \mapsto \lambda frm. \text{abspecIPC}(S, d, \text{frm})] \\
\end{align*}
\]

\textbf{Fig. 9.} Translations of abspecs and pre-abstractions into EMS.

\textbf{Theorem 4.3 (Safety).} For \(ns = ns_1 \cup \ldots \cup ns_n\), Safe \((ns, ns_1) \circ \ldots \circ Safe\ (ns, ns_n)\) is safe (i.e., never produces an Error).

\section{Proofmode}

\textbf{AL proof mode consists of two modes supporting simulation reasoning and separation logic reasoning.}

\subsection{Simulation Reasoning}

\textbf{Reduction Tactics.} We establish CR using a simulation technique, which relates an implementation state and an abspec state\textsuperscript{12}. To take steps, we provide reduction tactics that reduces the current itree (either in implementation or in abspec) into the head normal form by, e.g., converting \((i \gg j) \gg k\) into \(i \gg (j \gg k)\). Also, we made the tactics extensible: when embedding a new language with new effects and a new handler H into EMS, we can register new reduction lemmas about H so that they are used by the reduction tactics (e.g., converting \(H(i \gg j)\) into \(H(i) \gg H(j)\)).

\textbf{Simulation Tactics.} We provide tactics that automate common parts of simulation reasoning. Specifically, the tactics repeatedly apply the rules given below (i.e., converting the conclusion into the premise), where we omitted the state component and the world index in the simulation

\textsuperscript{12}In fact, our simulation tactics generally work for relating \textit{any} two EMS semantics.
relation for brevity. Note that the [dash-boxed] rules are complete (i.e., the premise and conclusion are equivalent) while the others not. Then we provide three tactics: steps automatically applies complete rules as many as possible, force_i applies any available rule once in the implementation side, and force_a does the same for the abspec side.

\[
\begin{align*}
\exists x \in X. \; & T_i \leq K_i[x] & \frac{T_i \leq x := \text{choose}(X); \; K_i[x]}{
\forall x \in X. \; & T_i \leq K_i[x] & \frac{T_i \leq x := \text{take}(X); \; K_i[x]}{
\forall x \in X. \; & K_i[x] \leq T_i & \frac{x := \text{choose}(X); \; K_i[x] \leq T_i}{
\forall x \in X. \; & T_i \leq K_i[x] & \frac{P \land (T_i \leq T_a)}{\exists x \in X. \; & T_i \leq K_i[x] & \frac{P \land (T_i \leq T_a)}{\forall x \in X. \; & T_i \leq K_i[x] & \frac{P \implies T_i \leq T_a}{P \implies T_i \leq T_a}}
\end{align*}
\]

5.2 Separation Logic Reasoning

\[
\forall x. \; P \mid \exists x. \; (\forall \exists \land 
\mid P \land Q \mid P \lor Q \mid P \implies Q \mid P \Leftarrow Q \mid \exists \notin \left[ a : \Sigma \right] \mid \implies P \mid P \lor Q
\]

We support the SL tactics provided by IPM (Iris Proof Mode). For this, we define the standard Iris connectives shown above on rProp, instead of iProp of Iris with step indices, and prove the lemmas that IPM (Iris Proof Mode) requires, which allows us to use IPM when proving logical entailment. Note that we omitted the later modality (\(\rhd\)) because we do not use step-indexing.

At Interaction Points. We have three tactics – slinit, slcall, and slret – for each interaction points. slinit is used at the beginning of a function and it moves the precondition (in rProp) into Coq hypothesis (current_rProps). slcall is used when calling a function — where source have its call decorated with abspec_call (Fig. 9) and target not. It asks the user to specify a subset of current_rProps that will be consumed when proving (with IPM) both (i) callee’s precondition and (ii) the relational invariant. After that, the user proceeds the proof with fresh rProps satisfying (i) callee’s postcondition and (ii) the relational invariant. In other words, while the mechanism is implemented with various assume/guarantees in low-level (e.g., abspec_call), we give a high-level interface with these tactics. slret is used at the end of the function and is similar to slcall.

In Between. We also support operations on current_rProps in the middle of the simulation proof. Notably, we support (i) eliminating connectives like \(\forall, \exists, \lor, \land, \implies, \top\), (ii) Assert tactic that consumes specified rProps to establish specified goal (using IPM), and (iii) OwnV tactic that gives \(\forall V(\sigma)\) for given \(\left[ \sigma \right]\). It is worth noting that, despite such functionalities, it suffices to put updates and validity checking only at the interaction points (as in \(\S 2.2\)), not in between.

6 IMP AND COMPILATION TO COMPCERT

The IMP language, extended from Imp presented in [Xia et al. 2019], has the following syntax and its semantics is defined in EMS.

\[
\begin{align*}
x, f, g & \in \text{String} \\
e & \in \text{Expr} \equiv \text{Expr} := x \mid u : \mathbb{Z} \mid e_1 \equiv e_2 \mid e_1 < e_2 \mid e_1 + e_2 \mid e_1 - e_2 \mid e_1 \times e_2 \\
s & \in \text{Stmt} \equiv \text{Stmt} := \text{skip} \mid x := e \mid s_1 ; s_2 \mid \text{if } (e) \text{ then } s_1 \text{ else } s_2 \mid x = f(e_1, \ldots, e_n) \mid x = f(p(e_1, \ldots, e_n)) \mid x = \delta g \mid x = \text{malloc}(e) \mid \text{free}(e) \mid x = \text{load}(e) \mid \text{store}(e_1, e_2) \mid x = \text{cmp}(e_1, e_2)
\end{align*}
\]

We have developed a verified compiler\(^\dagger\) from IMP to CSharpminor of CompCert [Leroy 2006], which is then composed with CompCert to give a compiler \(C\) from IMP to CompCert’s assembly.

\(^\dagger\)As a simple solution to resolve a subtle mismatch between CompCert’s memory model and our simplified one, we compile the free instruction to skip.
Theorem 6.1 (Separate Compilation Correctness). Let $(I_1, Asm_1), \ldots, (I_n, Asm_n)$ be pairs of IMP and Asm modules such that $C(I_i) = \text{Some}(Asm_i)$ for all $i$. Then, the following holds:

$$\text{Beh}(Asm_1 \circ \cdots \circ Asm_n) \subseteq \text{Beh}(I_{\text{mem}} \circ I_1 \circ \cdots \circ I_n)$$

Note that CompCert assemblies are linked with the syntactic linking operator ($\bullet$) and we followed the lightweight verification approach of [Kang et al. 2016].

7 EVALUATION

The right table shows the SLOC of the whole development (counted by coqwc). EMS and its meta-theory amount to 5609 SLOC, SL-specific theory (including PAbs, proof mode, translations, and spec erasure theorem) to 9341 SLOC, IMP-specific theory (including syntax, semantics, its compiler, and compiler verification) to 7899 SLOC, verification examples (Cannon, Mem, Stack, Echo, Repeat, and Landin’s knot) to 6136 SLOC, and general purpose Coq libraries to 3539 SLOC. In total, our Coq definitions amount to 17834 SLOC and proofs to 14690 SLOC.

The proof effort for verifying each example in AL is split into two: (i) that for reasoning about SL entailment, which would be comparable to that in Iris because we use IPM and prove essentially similar goals, and (ii) that for simulation reasoning, which was quite straightforward in all the examples thanks to our tactics.

Vertical compositionality of CR (i.e., gradual abstraction) also simplified the proof of meta theory of AL. For instance, the spec erasure theorem (Theorem 3.1) is established by transitively composing six contextual refinements, two major ones of which are (i) removing ASSUME and GUARANTEE while concretizing the measure information and (ii) removing pure calls by proving their termination using the measure information.

All the examples in the paper are extracted to OCaml programs, and we indeed found bugs by testing before verification. For extraction, all the events are handled inside Coq except for $E_{\text{prim}}$, which are handled by special handlers written in OCaml. Specifically, we wrote a few handlers doing IO for Obs and a handler for Choose and Take, which asks the user for a nondeterministic choice (currently only supports int64). For testing, we extracted both implementations and abstractions, executed them and compared the results. Interestingly, we found two mis-downcast bugs in the abstraction of Echo by testing before verification. Also we can extract and run even the abspecs although it would introduce so much nondeterminism.

8 RELATED WORK

There have been many works in proving safety and refinement of programs in various directions but occasionally with certain restrictions. Abstraction logic can be seen as a unifying theory, based on elementary mechanisms, that can subsume most of the works without such restrictions. We will discuss those works and their restrictions if any.

Specifications as programs. Refinement calculus [Back and Wright 2012] understands Hoare-style specifications as programs and provides refinement between them, which enjoys fully compositionality as in CR. [Koenig 2020; Koenig and Shao 2020] recently made advances in this line of research, where they also employ dual-nondeterminism and algebraic effects (similar to interaction trees but without extraction) like AL. However, unlike AL, they do not support SL-style specifications.

\[^{14}\text{We cast CompCert’s events into Obs events in EMS.}\]
Separation Logics. First of all, compared to the state-of-the-art separation logics such as Iris and VST, abstraction logic does not support concurrency yet although we plan to extend AL to support it following their approaches.

There have been works based on separation logics that go beyond safety such as CaReSL [Turon et al. 2013] and ReLoC [Frumin et al. 2018]. Like AL, they establish contextual refinement using SL but in a restricted setting that does not allow transformations essentially relying on logical specifications of external modules.

Using Iris, [Sammler et al. 2019] establishes guarantee of desired properties on observable traces (i.e., a sequence of system calls), instead of safety guarantee, in the presence of unverified contexts, but in a restricted setting that does not allow the contexts to invoke system calls.

Contextual Refinement. Certified Abstraction Layers (CAL) [Gu et al. 2015, 2018] proved effectiveness of contextual refinement in large scale verification by verifying a realistic operating system. Compared to AL, although it supports concurrency, CAL is limited in a few aspects. For example, CAL does not support SL-style specifications and thus does not allow implementations to use shared resources across modules. Also it does not allow mutual recursion between modules.

9  CONCLUSION AND FUTURE WORK

We present a comprehensive theory combining the benefits of contextual refinement and separation logic, together with practical tools, using the key idea of *choose* and *take* that gives an illusion of passing any information to anyone without involving physical operations. As future works, we plan to extend abstraction logic to support concurrency, and also develop testing tools that can efficiently find bugs that breaks desired contextual refinement, which may also give a certain level of confidence without verification.

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