In quantum metrology, nonlinear many-body interactions can enhance the precision of Hamiltonian parameter estimation to surpass the Heisenberg scaling. Here, we consider the estimation of the interaction strength in linear systems with long-range interactions and using the Kitaev chains as a case study, we establish a transition from the Heisenberg to super-Heisenberg scaling in the quantum Fisher information by varying the interaction range. We further show that quantum control can improve the prefactor of the quantum Fisher information. Our results explore the advantage of optimal quantum control and long-range interactions in many-body quantum metrology.

I. INTRODUCTION

Quantum metrology is a paradigmatic example of an emergent technology in which quantum resources can provide an advantage with no classical counterpart [1–4]. The general scheme for estimating the parameters in a Hamiltonian system is depicted in Fig. 1. Quantum mechanics provides two key ingredients improving the precision: (a) the coherence in state $\rho_{\theta}$ of the probe, which is controlled by the probe time $T$, and (b) entanglement, when $N$ probes are allowed in a single round, which can be introduced in the initial state or generated via many-body interactions during the sensing process. According to the quantum Cramer-Rao bound, the uncertainty $\delta \theta$ in the estimation of the parameter $\theta$ in Fig. 1 is governed by the quantum Fisher information $I(\theta)$ (QFI) as $\delta \theta \geq 1/\sqrt{\nu I(\theta)}$, where $\nu$ is the number of repetitions of the process. The QFI plays a fundamental role in the geometry of the space of quantum states and has manifold applications, which include witnessing a quantum phase transition [5–8], critical sensing [9–12] and detecting multi-partite entanglement [13–15].

Recently, optimal control has been shown to offer a new arena for enhancing quantum parameter estimation [18–20]. The interplay between quantum control theory and quantum many-body systems is yet to be undertaken and it is crucial to understand quantum parameter estimation of coupling constants in realistic systems with long-range interactions. In Hamiltonian parameter estimation of noninteracting spin systems, the maximum possible QFI scales linearly with the number of probes, for an uncorrelated initial state [16]. The scaling becomes quadratic if the probes are initially prepared in the GHZ state with maximum entanglement, known as the Heisenberg scaling (HS) [16]. This naturally motivates the idea of surpassing the HS, reaching the so-called super-HS scaling, by introducing nonlinear interactions in the sensing Hamiltonian [17, 21, 22]. These works have led to the intuitive belief that surpassing the HS requires nonlinear interactions.

In this paper, we explore Hamiltonain parameter estimation in linear systems with long-range interactions, using a case study of the generalization of the Long-Range Kitaev (LRK) chain [23–25] to allow for general decay laws of the long-range interactions. By focusing on the estimation of the long-range superconducting strength, we establish that super-HS can be achieved in the case of slowly decaying linear long-range interactions. Indeed, we observe a transition from HS to super-HS for a specific value of the exponent governing the decay law of the interactions. In all cases, quantum control may improve the prefactor of the scaling of the QFI as a function of the the number of lattice sites.

II. HAMILTONIAN ESTIMATION OF THE LRK MODEL.

We consider parameter estimation with a general time-dependent Hamiltonian $H(\theta t)$, where $\theta$ is the estimation parameter and the parametric dependence is general, i.e., not necessarily multiplicative. The effective generator for the parameter estimation is defined as $|\psi_0\rangle = e^{-iG_\theta} |\psi_0\rangle$ [17], where $|\psi_0\rangle$ is the initial state and $|\psi_\theta\rangle$ is the effective parameter-dependent state which gives the same QFI as the true physical state [26]. For a general Hamiltonian it is given by [17, 19, 27]

$$G_\theta = \int_0^T \mathcal{U}_\theta(\tau) \partial_\theta H(\theta \tau) \mathcal{U}_\theta(\tau) d\tau,$$
where $U_\theta(t)$ is the evolution operator. Once the generator is obtained, the quantum Fisher information is given by $I(\theta) = 4 \text{Var}[G_\theta]|_{|\psi(0)\rangle}$. Maximization over all the possible initial states gives

$$I(\theta) = [\theta_{\text{max}}(T) - \theta_{\text{min}}(T)]^2,$$

where $|\theta_{\text{min}}(T)\rangle$ and $|\theta_{\text{max}}(T)\rangle$ as the eigenvectors that correspond to the minimum and maximum eigenvalues of $G_\theta$ and the corresponding initial state is prepared in an equal superposition between $|\theta_{\text{max}}(T)\rangle$ and $|\theta_{\text{min}}(T)\rangle$. When coherent optimal controls are possible, one can further optimize the QFI over the unitary dynamics appear in the generator $G_\theta$. We denote the eigenstates of $\partial_\theta H_\theta(t)$ at the instant time $t$ as $|\chi_n(t)\rangle$. It turns out the optimal unitary dynamics is the one which steers the state always towards $|\chi_n(t)\rangle$, if one starts with $|\chi_0(0)\rangle$ [19]. With this intuition, it is easily found that the total Hamiltonian after including the control is

$$H_{\text{tot}}(t) = i\hbar \partial_\theta U_{\text{tot}}(t) U_{\theta}^{-1}(t),$$

where

$$U_{\text{tot}}(t) = \sum_n |\chi_n(t)\rangle \langle \chi_n(0)|$$

is a unitary operator formed by the eigenvectors of $\partial_\theta H_\theta(t)$. Therefore, the optimal control Hamiltonian is [28, 29]

$$H_\theta(t) = H_{\text{tot}}(t) - H_\theta(t).$$

When optimal control is applied, the generator is $G_{\theta} = \sum_n |\chi_n(0)\rangle \langle \chi_n(0)| \int_0^T \chi_n(\tau)d\tau$. Thus the upper bound of the QFI after optimization over the initial states and unitary dynamics is

$$I_0(\theta) = \left( \int_0^T |\chi_{\text{max}}(\tau) - \chi_{\text{min}}(\tau)|d\tau \right)^2,$$

where $\chi_{\text{max}}(t)$ and $\chi_{\text{min}}(t)$ are the maximum and minimum eigenvalues of $\partial_\theta H_\theta(t)$. The optimal initial state is the equal superposition between $|\chi_{\text{max}}(0)\rangle$ and $|\chi_{\text{min}}(0)\rangle$. For time-independent Hamiltonians, $I_0(\theta)$ is simply proportional to the square of the difference of the minimum and maximum eigenvalues of $\partial_\theta H_\theta$, with the prefactor $4T^2$.

Now we consider $H_\theta$ be the LRK Hamiltonian [23]

$$H_\theta = \frac{J}{2} \sum_{j=1}^N (a_j^\dagger a_{j+1} + a_{j+1}^\dagger a_j) - \mu \sum_{j=1}^N (a_j^\dagger a_j - \frac{1}{2})$$

$$+ \frac{\Delta}{2} \sum_{j=1}^{N-1} \sum_{l=1}^{N-j} \kappa_{l,\alpha} (a_j a_{j+l} + a_{j+l}^\dagger a_j^\dagger),$$

where consider a unit lattice spacing, $J$ represents the tunneling rate between nearest neighbors, $\mu$ is the chemical potential, $\Delta$ represents the strength of the $p$-wave pairing, $N$ is the number of Fermionic lattice sites, and $\kappa_{l,\alpha}$ satisfies the symmetry property: $\kappa_{l,\alpha} = \kappa_{N-l,\alpha}$ for $1 \leq l \leq N/2$. Here, $\alpha \geq 0$ characterizes the decay property of the long-range interaction. Without loss of generality, we choose the normalization condition $\kappa_{1,\alpha} = 1$. The Kitaev chain has recently attracted broad attention as it supports noise-resilient Majorana zero modes at its two ends for open boundary conditions [30, 31]. Recent works [23–25] have generalized the original model to the LRK chain, which contains long-range superconducting $p$-wave pairing, i.e., the last term on the r.h.s. of Eq. (6). Note that by contrast to the power-law decay law in Ref. [23], we consider a general decay law $\kappa_{l,\alpha}$ as in the original proposal of the LRK model [23], and $\kappa_{l,\alpha} = (1 + \ln l)^{-\alpha} (\alpha \geq 0)$ [32]. Assuming the anti-periodic boundary condition $a_j = -a_{j+\pi}$, the LRK Hamiltonian (6) can be diagonalized via the Bogoliubov transformation [15], yielding

$$H_\theta = \sum_k \epsilon_k(k) \psi_k^\dagger(k) \psi_k(k),$$

where $k = \frac{2\pi}{N}, \frac{2\pi}{N} \cdots \frac{2\pi}{N}(N = \frac{1}{2})$, the factor of 2 in front of $\epsilon_k(k)$ accounts for the symmetry property of $\epsilon_k$. The generator $G_\theta$ can be diagonalized via the Bogoliubov transformation as (see Appendix A for details)

$$G_\theta = \sum_k \epsilon_\theta(k) \psi_k^\dagger(k) \psi_k(k),$$

where the Fermionic operators $\psi_k^\dagger$ and $\psi_k$ are defined in Eq. (A20) and the spectrum is

$$\epsilon_k(k) \equiv (\partial_\theta \epsilon_k(k))^2 + \frac{1}{4} \xi_k^2(k) \sin^2(2\epsilon_k(k)T) + \frac{1}{4} \xi_k(k) (1 - \cos(2\epsilon_k(k)T))^2)^{1/2},$$

with

$$\xi_k(k) \equiv \partial_\theta \cos(\epsilon_k(k) T) / \sin(\epsilon_k(k)).$$

We next determine the optimal controls and optimal initial states for parameter estimation, by using the spectral properties of $\partial_\theta H_\theta(t)$, for the different choices of the Hamiltonian

III. OPTIMAL CONTROL AND OPTIMAL INITIAL STATE
parameter \( \theta \). According to Eq. (A1) in Appendix A, the representation of the LRK Hamiltonian in the momentum space, it is readily calculated that

\[
\partial_J H = - \sum_k a^\dagger(k) a(k) \cos k, \tag{15}
\]

\[
\partial_\mu H = - \sum_k a^\dagger(k) a(k). \tag{16}
\]

We note that \( \partial_J H \) and \( \partial_\mu H \) commute with each other. Thus, according to the preceding section, the optimal control for estimating \( J \) and \( \mu \) is to cancel the long-range superconducting terms. The maximum and minimum eigenstates for \( \partial_J H \) are

\[
|\text{I}/2\rangle = \prod_{k, \cos k \leq 0} a^\dagger(k) |0\rangle, \tag{17}
\]

and

\[
|-\text{I}/2\rangle = \prod_{k, \cos k > 0} a^\dagger(k) |0\rangle, \tag{18}
\]

respectively. We adopt this notation since in momentum space both the maximum and minimum eigenstates are half-occupied. The optimal initial state for estimating \( J \) under optimal control is

\[
|\psi_0\rangle = \frac{1}{\sqrt{2}} (|\text{I}/2\rangle + |-\text{I}/2\rangle). \tag{19}
\]

Similarly, for \( \partial_\mu H \), the maximum eigenstate is \( |0\rangle \), the vacuum state annihilated by \( a(k) \) or \( a_j \), and the minimum eigenstate is the fully occupied state in the momentum space, which we denote as

\[
|\text{I}\rangle = \prod_k a^\dagger(k) |0\rangle. \tag{20}
\]

Therefore, the optimal initial state for estimating \( \mu \) under optimal control is

\[
|\psi_0\rangle = \frac{1}{\sqrt{2}} (|0\rangle + |\text{I}\rangle). \tag{21}
\]

The optimal control for the estimation of \( \Delta \) is to cancel all the local interaction terms, including the tunneling and kinetic terms. We note that the diagonalization of \( \partial_\Delta H \) is a special case for the diagonalization of the LRK Hamiltonian, corresponding to \( J = \mu = 0 \) and \( \Delta = 1 \). With this observation one finds

\[
\partial_\Delta H = \frac{1}{2} \sum_k |f_\alpha(k)| b^\dagger(k) b(k),
\]

where \( b(k) = u_\alpha a(k) + v_\alpha a(-k), u_k = 1/2, v_k = -i/\sqrt{2} \) if \( f_\alpha(k) \geq 0 \) and \( v_k = i/\sqrt{2} \) if \( f_\alpha(k) < 0 \). We note that \( v_k = -v_{-k} \) because \( f_\alpha(k) \) is an odd function of \( k \). The minimum eigenstate of \( \partial_\Delta H \) is the ground state annihilated by \( b(k) \). According to the BCS ansatz, it is

\[
|\text{GS}\rangle = \prod_k [u_k - v_\alpha a(k) a^\dagger(k)] |0\rangle. \tag{22}
\]

The maximum eigenvalue of \( \partial_\Delta H \) corresponds to the fully occupied state in the picture of \( b(k) \) and \( b^\dagger(k) \), which we denote by |FO\rangle and can be written as

\[
|\text{FO}\rangle = \prod_k [u_k^* - v_\alpha^* a(k) a^\dagger(-k)] |\text{I}\rangle. \tag{23}
\]

One can explicitly check that |FO\rangle is normalized and satisfies \( b^\dagger(k) |\text{FO}\rangle = 0 \) for all \( k \). We call Eq. (23) the BCS-like fully occupied states since its construction is inspired by the BCS-ground state. Thus the optimal initial state for estimating \( \Delta \) is

\[
|\psi_0\rangle = (|\text{GS}\rangle + |\text{FO}\rangle)/\sqrt{2}. \tag{24}
\]

### A. HS for estimation of \( J \) and \( \mu \)

The difference between the maximum and minimum eigenvalues of \( \partial_\Delta H \) in the many-body Hilbert space is \( |\cos k| \). Thus the QFI for estimating \( J \) according to Eq. (5) is

\[
I_0(J) = \langle \sum_k |\cos k| \rangle^2 \pi^2. \tag{25}
\]

where we have replaced \( \sum_k \rightarrow N/2\pi \int dk \) taking the continuum limit, as the integrand is not singular in the integration region. In fact, the error introduced does not scale with \( N \) according to the analysis with the Euler-Maclaurin formula in Appendix B. Similarly, the difference between the maximum and minimum eigenvalues of \( \partial_\mu H \) in the many-body Hilbert space is 1 and therefore \( I_0(\mu) = N^2 \pi^2 \). We see that the scaling of the ultimate QFI for estimating \( J \) and \( \mu \) is the HS. The plot of \( I_0(J) \) with the number of lattice sites is shown in Fig. 2. We will show shortly that even in the case of imperfect control or without control, such scaling is not altered.

### B. HS to super-HS transition for estimating \( \Delta \)

The maximum and minimum eigenvalues of \( \partial_\Delta H \) in the many-body Hilbert space are \( \gamma_\alpha(N)/2 \) and 0, where \( \gamma_\alpha(N) \equiv \sum_k |f_\alpha(k)| \). Thus, for estimating \( \Delta \), the QFI reads

\[
I_0(\Delta) = \langle \gamma_\alpha(N)/2 \rangle^2 \pi^2. \tag{26}
\]

Determining the scaling of \( I_0(\Delta) \) boils down to computing the scaling of \( \gamma_\alpha(N) \) at large \( N \). Let us first discuss a simple case, with \( \kappa_{i,0} = 1 \). In this case, \( f_\alpha(k) = \cot(k/2) \). According to Appendix C, when applying the Euler-Maclaurin formula, the upper bound of the scaling of the remainder, which is the difference between \( \gamma_\alpha(N) \) and the main integral \( N/(2\pi) \int_{|k|}^N \cot(k/2)dk \), is \( N \) due to the singularity of \( f_\alpha(k) \) around \( k = 0 \). Nevertheless, since the main integral \( N/(2\pi) \int_{|k|}^N \cot(k/2)dk \sim N \ln N \), which is still much larger than \( N \) in the asymptotic limit of larger \( N \), we conclude that the leading order \( \gamma_\alpha(N) \) is \( N \).
Let us next focus on the case of the power-law decay for the long-range interaction in the original proposal of LRK [23], i.e., $k_{t,a} = l^{-a}$. For $a > 1$, $f_{a}(k)$ has no singularity for all the values of the momentum $k$. This is because $|\sum_{i=1}^{N-1} \sin(kl)/P| \leq \frac{1}{\sin(\pi/a)}$ and the latter series is convergent for $a > 1$. With the Euler-Maclaurin formula discussed in Appendix B, $\gamma_a(N)$ scales as $N$. Thus the QFI $I_0(\Delta)$ obeys the HS for $a > 1$. For $0 < a \leq 1$, using the properties of polylogarithmic function [33], one finds $f_a(k) \sim 1/k^{1-a}$ (see also Appendix D and Ref. [23]). According to Appendix C, the upper bound of the scaling of the remainder in the Euler-Maclaurin formula is strictly slower than $N$ and the leading order of $\gamma_a(N)$ is controlled by the main integral $N/2\pi \int_{\pi/a}^{\pi} |f_{a}(k)|dk$. We note that $\int_{\pi/a}^{\pi} [f_{a}(k) - 1/k^{1-a}]dk$ should be constant as $N \to \infty$ since the singularity has been removed. So $\int_{\pi/a}^{\pi} |f_{a}(k)|dk \sim \int_{\pi/a}^{\pi} 1/k^{1-a}dk$ is a constant, which does not scale with $N$ and therefore $\gamma_a(N) \sim N$. We thus find that for $k_{t,a} = l^{-a}$, super-HS scaling only occurs for $a = 0$.

Now, let us explore more general long-range interactions that satisfy the regularity condition at the beginning. As we have seen above, the scaling $\gamma_a(N)$ crucially depends on the singularities of $f_a(k)$, which is caused by the slow-decaying long-range interactions. We argue at the end of Appendix G that $\int_{\pi/a}^{\pi} dk f_a(k) \sim N \int_{\pi/a}^{\pi} (\kappa_{x,a}/x) \sim N \ln N$. Then according to Appendix C, we find the leading order scaling of $\gamma_a(N)$ is controlled by $N/2\pi \int_{\pi/a}^{\pi} dk f_a(k) \sim N \int_{\pi/a}^{\pi} (\kappa_{x,a}/x)dx$. We see that the maximum possible scaling $\gamma_a(N)$ is $N \ln N$, where $\kappa_{x,a}$ is a constant that does not depend on $x$. Therefore, according to Eq. (26),

$$I_0(\Delta) \sim N^2 \left[ \int_{\pi/a}^{\pi} (\kappa_{x,a}/x)dx \right]^2,$$

and it is bounded by $N^2(\ln N)^2$ rather than the HS. In particular, when the long-range interaction decays sufficiently slow, $\int_{\pi/a}^{\pi} (\kappa_{x,a}/x)$ can diverge at large $N$ and therefore super-HS occurs for $I_0(\Delta)$. This is the case, e.g., when $\kappa_{x,a} = [\ln(e\lambda)]^{-\alpha} = (1 + \ln x)^{-\alpha}$ which satisfies the regularity conditions with $Q \geq 1$. So we obtain $\gamma_a(N) \sim N \int_{\pi/a}^{\pi} dx/[x(1 + \ln x)^a]$. The integral can be evaluated with the change of variable $s = 1 + \ln x$, which leads to

$$I_0(\Delta) \sim \left\{ \begin{array}{ll} N^2(\ln N)^2 & \alpha \in [0, 1) \\ N^2(\ln N)^2 & \alpha = 1 \\ N^2 & \alpha > 1 \end{array} \right.. \tag{28}$$

As a result, super-HS occurs for the very slow decay law dictated by the power of logarithms when $\alpha \leq 1$. As one can see from Fig. 3 (a)-(b), the analytical scalings of $I_0(\Delta)$ for $\kappa_{0,1} = 1$ and $\kappa_{0,1} = (1 + \ln l)^{-0.2}$ shown by the blue solid lines, are in excellent agreement with their respective numerical calculations, shown by the cyan and red triangles in Fig. 3 (a)-(b), respectively.

### C. Resilience of the scaling under no or imperfect control

We have seen that the HS of $I_0(J)$ and $I_0(\mu)$ is due to the fact that the spectrum of $\xi_J(k)$ and $\xi_{\mu}(k)$ is regular near $k = 0$, while the possibility of super-HS scaling in $I_0(\Delta)$ is due to the fast divergence of $\xi_J(k)$ near $k = 0$. It is natural to consider the fate of these scaling laws when control is not optimally applied or is not available. According to Eq. (1), we find

$$I(\theta) = \left[ \sum_{k} \phi_{0}(k) \right]^2. \tag{29}$$

Let us first discuss the estimation of $J$. First, from Eqs. (8, 12), one can readily obtain

$$\partial_f \xi_J(k) = \cos(k \cos \mu + \mu)/\xi_J(k), \tag{30}$$

$$\xi_J(k) = \Delta f_{a}(k) \cos k/[2\xi_J^2(k)]. \tag{31}$$

Since we focus on the no-control or imperfect control case, $\Delta \neq 0$. We see that the only possibility for $\partial_f \xi_J(k)$ and $\partial_f \xi_{\mu}(k)$ to blow up is when their denominators vanish, i.e., $J \cos k + \mu = 0$ and $f_a(k) = 0$ near $k = 0$. However, we note that whenever $f_a(k) = 0$, $\partial_f \xi_J(k) = \pm \cos k$. The same argument also applies to $\xi_J(k)$. Therefore $\xi_J(k)$ does not blow up. Thus we conclude in the absence of controls or in the presence of imperfect control, the HS is not affected. For the estimation of $\Delta$, it is readily found from Eqs. (8, 12) that

$$\partial_s \xi_{\Delta}(k) = \Delta f_{a}^2(k)/[4\xi_{\Delta}(k)], \tag{32}$$

$$\xi_{\Delta}(k) = -(J \cos k + \mu) f_a(k)/[2\xi_{\Delta}^2(k)]. \tag{33}$$

Since around $k = 0$, $\xi_{\Delta}(k) \sim f_a(k)$, we know $\lim_{k \to 0} \xi_{\Delta}(k) = 0$ and $\partial_s \xi_{\Delta}(k) \sim f_a(k)$. Therefore, the dominant divergence in
Figure 3. Quantum Fisher information $I(\Delta)$ for $\Delta$ estimation in the case with no control or imperfect control, as well as for optimal control as function of $N$ for (a) $\kappa_{t_{\alpha}} = I^{-\alpha}$ and (b) $\kappa_{t_{\alpha}} = (1 + \ln I)^{-\alpha}$. The probe time $T = 1$ in both figures. (a) All the discrete points are numerically calculated from Eq. (29). The values of the parameters for (i) red circle dots: $J = \mu = 0.5\Delta$ and $\alpha = 0$ (ii) purple squares: $J = \mu = \Delta$ and $\alpha = 0.5$ (iii) pink stars are $J = \mu = \Delta$ and $\alpha = 0.5$ (iv) Cyan triangles: $J = \mu = 0$ and $\alpha = 0$. The blue solid line is the scaling $N^2(\ln N)^2$, where the prefactor is determined by the QFI for $J = \mu = 0$ and $N = 1000$. (b) The red triangles are numerical calculations of $I_\theta(\Delta)$ for $\alpha = 0.2$ and the blue line is the fitted to the red triangles with $\theta(\ln N)^\alpha + B$, where $\theta = 0.20$, $\alpha = 1.54$ and $B = 0.17$. The values $\alpha$ is very close to the expected value $2(1 - \alpha) = 1.6$. The slight deviation of the scaling exponent between theory and the fitted results is because $\ln N$ is a very slowly increasing function compared to the power functions.

$\delta_\kappa(k)$ is controlled by $\delta_\kappa(k)$ and is the same as the case of the optimal estimation of $\Delta$. The scaling of estimating $\Delta$ is again unchanged.

Fig. 2 and 3 show a comparison between the cases with optimal controls and with no controls or imperfect controls, respectively. As we can see from these figures, the slopes of the lines for the cases with no or imperfect control match the one for optimal control. The same conclusion holds for the estimation of $\mu$. Therefore, the role of optimal quantum controls here is to improve the prefactor of the leading order scaling of the ultimate QFI rather than the scaling exponent.

IV. DISCUSSIONS AND CONCLUSIONS

We have established that the scaling of the QFI for estimating the superconducting strength $\Delta$ is bounded by $N^2(\ln N)^2$ rather than the HS due to the long-range interactions. As in Eq. (6), long-range interactions contains $N^2$ terms whose strength is controlled by $\kappa_{t_{\alpha}}$. Intuitively, if $\kappa_{t_{\alpha}}$ decays quickly, these $N^2$ terms effectively behave like a local interaction containing only $N$ terms, like in the estimation of $J$ and $\mu$, and lead to the HS in estimating $\Delta$. However, if $\kappa_{t_{\alpha}}$ decays sufficiently slow, these $N^2$ terms can collectively give rise to the super-HS behavior. We have illustrated this in two examples with $\kappa_{t_{\alpha}} = I^{-\alpha}$ and $\kappa_{t_{\alpha}} = (1 + \ln I)^{-\alpha}$, respectively. Interestingly, when $N$ is not large enough, we have shown in Appendix H that super-HS $N^2(\ln N)^2$ and $N^2(\ln \ln N)^2$ can also occur as long as

$$\epsilon \ll (\ln N)^{-1}$$

for $\kappa_{x,\epsilon} = x^{-\epsilon}$ and

$$\epsilon \ll \ln \ln N$$

for $\kappa_{x,1+\epsilon} = (1 + \ln I)^{-(1+\epsilon)}$, respectively. Note that the LRK model here is linear, and thus different from the super-HS in the nonlinear models [17, 21, 22]. Since the HS characterizes the many-body entanglement of the probes if the generator only contains local operators [13–15], our results may indicate there may be an intimate connection between the HS to super-HS transition and the property of quantum entanglement.

One can also view the super-HS in the spin representation: LRK Hamiltonian (6) can be transformed into the one for spin systems via the Jordan-Wigner transformation [34]. The resulting Hamiltonian becomes (see Appendix I)

$$H_{\text{spin}} = -\frac{J}{4} \sum_{j=1}^{N} (\sigma_x^{j} \sigma_x^{j+1} + \sigma^y_j \sigma^y_{j+1}) - \frac{\mu}{2} \sum_{j=1}^{N} \sigma_z^j$$

$$- \frac{\Delta}{8} \sum_{j=1}^{N} \kappa_{t_{\alpha}} (\sigma^z_j \sigma^z_j - \sigma^x_j \sigma^x_{j+1})$$

$$+ \frac{\Delta}{8} \sum_{j=1}^{N} \sum_{k=1}^{N} (-1)^{j} \kappa_{t_{\alpha}} (\sigma^x_j \sigma^x_{j+1} - \sigma^y_j \sigma^y_{j+1}) \otimes_{k=1}^{N} \sigma^z_{j+k},$$

which contains the long-range pairing term involves interaction among ($l + 1$)-spins, with $1 \leq l \leq N - 1$. This agrees with the intuition that for spin systems, reaching the super-HS requires interactions involving more than one single spin operator [17, 22].

We have further shown that the singularity is not altered by whether external control is optimally applied or not. Therefore, we conclude that in the LRK model, quantum controls can improve the ultimate QFI by altering the prefactor while preserving the scaling exponent.

Our results are of direct relevance to practical quantum metrology with quantum dots [35], trapped ions [36, 37] and cold atoms [38]. Our findings should be applicable to the relation between the HS/super-HS and the many-body entanglement [13–15], the physical preparations of the optimal initial states (Fermionic GHZ states) [39], optimal detection associated with the HS and super-HS [4, 40, 41] and quantum estimation of the LRK in the presence of decoherence and dissipation [21].
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Appendix A: The diagonalization of the LRK Hamiltonian and the generator for parameter estimation

We note that the LKR Hamiltonian in momentum space reads [15]

\[
H_0 = -\frac{J}{2} \sum_k \left[ a^\dagger(k)a(k) + a^\dagger(-k)a(-k) \right] \cos k - \mu \left[ \sum_k a^\dagger(k)a(k) + \sum_{-k} a^\dagger(-k)a(-k) \right] \\
+ \frac{i\Lambda}{4} \sum_k \left[ a(-k)a(-k) - a^\dagger(-k)a^\dagger(-k) \right] f_\alpha(k).
\]  

(A1)

The Fourier transformation that relates the original Hamiltonian (6) to above Hamiltonian does not depend on any estimation parameters. Thus, the Fisher information is preserved by the transformation. Eq. (A1) can be diagonalized as follows

\[
H_\theta = \frac{1}{2} \sum_k \varepsilon_\theta(k) \left[ a^\dagger(k) \sigma_z U_\theta(k) \right] \left[ a(k) \right] + \frac{1}{2} \sum_k \varepsilon_\theta(k) \left[ a^\dagger(-k) \sigma_z U_\theta(k) \right] \left[ a(-k) \right],
\]  

(A2)

through the Bogoliubov transformation \( U_\theta(k) \)

\[
U_\theta(k) \equiv \begin{pmatrix} \cos \left[ \phi_\theta(k) / 2 \right] & i \sin \left[ \phi_\theta(k) / 2 \right] \\ i \sin \left[ \phi_\theta(k) / 2 \right] & \cos \left[ \phi_\theta(k) / 2 \right] \end{pmatrix},
\]

(A3)

\[
\sin \phi_\theta(k) = -\frac{\Delta f_\alpha(k)}{2 \varepsilon_\theta(k)},
\]

(A4)

\[
\cos \phi_\theta(k) = -\frac{(J \cos k + \mu)}{\varepsilon_\theta(k)}.
\]

(A5)

Denoting

\[
\begin{pmatrix} \eta_\theta(k) \\ \eta_\theta(-k) \end{pmatrix} \equiv U_\theta(k) \left[ \begin{pmatrix} a(k) \\ a^\dagger(-k) \end{pmatrix} \right],
\]

(A6)

the Hamiltonian can be rewritten as

\[
H_\theta = \sum_k \varepsilon_\theta(k) \left[ \eta^\dagger_\theta(k) \eta_\theta(k) - \frac{1}{2} \right].
\]

(A7)

Therefore,

\[
\hat{g}_\theta H_\theta = \sum_k \hat{g}_\theta \varepsilon_\theta(k) \eta^\dagger_\theta(k) \eta_\theta(k) + \frac{i}{2} \sum_k \hat{g}_\theta \varepsilon_\theta(k) \eta_\theta(k) \left( \eta_\theta(-k) \eta_\theta(k) - \eta^\dagger_\theta(k) \eta^\dagger_\theta(-k) \right).
\]

(A10)

Substituting Eq. (A10) into Eq. (A8), we find

\[
G_\theta = T \sum_k \hat{g}_\theta \varepsilon_\theta(k) \eta^\dagger_\theta(k) \eta_\theta(k) + \frac{i}{2} \sum_k \hat{g}_\theta \varepsilon_\theta(k) \eta_\theta(k) \int_0^T dt \tau e^{\Sigma \alpha \varepsilon_\alpha(x) \eta^\dagger_\alpha(x) \eta_\alpha(x)} \left( \eta_\theta(-k) \eta_\theta(k) - \eta^\dagger_\theta(k) \eta^\dagger_\theta(-k) \right) e^{-i \Sigma \alpha \varepsilon_\alpha(x) \eta^\dagger_\alpha(x) \eta_\alpha(x)}.
\]

(A11)
We rewrite Eq. (A15) in a more compact form

\[ e^{i \epsilon_\sigma \theta} n_\sigma(k) \eta_\sigma(k) - n_\sigma(-k) \eta_\sigma(-k) \left[ (n_\sigma(k) + n_\sigma(-k)) - (\eta_\sigma(k) + \eta_\sigma(-k)) \right] \]

Using the relation

\[ e^{i \eta_\sigma \delta} = 1 + \eta_\sigma \eta_\sigma(e^{i \theta} - 1) = e^{i \theta} - \eta_\sigma \eta_\sigma(e^{i \theta} - 1) \]

for Fermionic operators, Eq. (A12) becomes

\[ e^{i \epsilon_\sigma \theta} n_\sigma(k) \eta_\sigma(k) e^{i \epsilon_\sigma \theta} n_\sigma(-k) \eta_\sigma(-k) \]

where we have used \( \eta_\sigma^2(k) = 0 \). The generator now becomes

\[ G_\theta = \sum_k \left[ T \partial_\theta \eta_\sigma(k) n_\sigma(k) \eta_\sigma(k) + \frac{\xi_\theta(k)}{4} \left( (1 - e^{-2i \epsilon_\sigma \theta}) \eta_\sigma(-k) \eta_\sigma(k) + (1 - e^{2i \epsilon_\sigma \theta}) \eta_\sigma(k) \eta_\sigma(-k) \right) \right] \]

We rewrite Eq. (A15) in a more compact form

\[ G_\theta = \frac{1}{2} \sum_k \left[ n_\sigma(k), \eta_\sigma(-k) \right] \eta_\sigma(k) \eta_\sigma(-k) \]

where the matrix \( \mathcal{G}_\theta(k) \) is defined as

\[ \mathcal{G}_\theta(k) = T \partial_\theta \eta_\sigma(k) \sigma_z + \frac{\xi_\theta(k)}{2} (1 - \cos[2 \epsilon_\sigma \theta T]) \sigma_x + \frac{\xi_\theta(k)}{2} \sin[2 \epsilon_\sigma \theta T] \sigma_y = \mathcal{E}_\theta(k) \eta_\sigma(k) \cdot \sigma. \]

Furthermore we note that

\[ V_\theta(k) [ n_\sigma(k), \eta_\sigma(-k) ] \]

where

\[ V_\theta(k) = \left( \downarrow n_\sigma(k), \uparrow n_\sigma(k) \right) \]

and \( \downarrow n_\sigma(k) \) and \( \uparrow n_\sigma(k) \) are the vectors aligned and anti-aligned with the vector \( \eta_\sigma(k) \) on the Bloch sphere, respectively. Introducing

\[ \begin{bmatrix} \psi_\sigma(k) \\ \psi_\sigma(-k) \end{bmatrix} = V_\theta(k) \begin{bmatrix} \eta_\sigma(k) \\ \eta_\sigma(-k) \end{bmatrix}, \]

one can readily obtain Eqs. (10, 11) in the main text.

**Appendix B: The Euler-Maclaurin formula**

**Lemma 1.** (Euler-Maclaurin formula) For arbitrary function \( g(x) \) with continuous derivatives, the infinite series \( \sum_{n=a}^{b} g(n) \) can be converted the corresponding integral plus reminder terms via the Euler-Maclaurin formula [42].

\[ \sum_{n=a}^{b} g(n) = \int_{a}^{b} g(x) dx + R, \]

where the remainder is

\[ R = \frac{1}{2} [g(b) - g(a)] + \sum_{m=1}^{M} \frac{b_{2m}}{(2m)!} [g^{(2m-1)}(b) - g^{(2m-1)}(a)] + \int_{a}^{b} \frac{1}{(2M + 1)!} \left[ P_{2M+1}(x) g^{(2M+1)}(x) \right] dx. \]

Here, \( M \) can be arbitrarily chosen from the natural numbers \( 0, 1, 2, \cdots, b_{2m} \) is the Bernoulli number. \( P_0(x) = 1 \) for \( M > 0 \)

\[ P_M(x) = \frac{1}{M!} B_M(x), \]
where \([x] \equiv x - [x]\) and \(B_M\) is the Bernoulli polynomial.

We can use the Euler-Maclaurin formula to approximate a series

\[
\sum_{n=0}^{N-1} f \left( \frac{(2n+1)\pi}{N} \right) = \frac{N}{2\pi} \sum_{n=0}^{N-1} f(n) + R_j, \tag{B7}
\]

where

\[
R_j = \int_{F_j} P_1(x) \sin \left( \frac{(2x+1)\pi}{N} \right) dx + \text{boundary terms},
\]

and \(P_1(x)\) is defined in Eq. (B3). We note that the boundary terms remain finite and does not scale with \(N\). They will be omitted subsequently. In the Fourier representation, we find

\[
\sum_{n=0}^{N-1} f \left( \frac{(2n+1)\pi}{N} \right) = \frac{N}{2\pi} \sum_{n=0}^{N-1} f(n) + R_j,
\]

where

\[
R_j = \int_{F_j} P_1(x) \sin \left( \frac{(2x+1)\pi}{N} \right) dx + \text{boundary terms}.
\]

Since \(f(k)\) is differentiable on \(F_j\), \(f'(k)\) is regular on \(F_j\). The boundary terms remain finite as long as the number of the \(F_j\)'s does not scale with \(N\). So we conclude that when \(f(k)\) is regular, \(\sum_{k=\pi} f(k) \sim N\). For example, in Eq. (25) of the main text, we take \(f(k) = |\cos k|\), which is differentiable on \(F_1 = [\pi/N, \pi/2 - \pi/N]\), \(F_2 = [\pi/2 + \pi/N, \pi - \pi/N]\) and \(F_3 = [\pi - \pi/N, 2\pi - \pi/N]\) respectively.

However, we note that if \(f(k)\) has a singularity in \([0, 2\pi]\), the remainder may not be necessarily stay as a constant as \(N \to \infty\). For example, if we take

\[
f(k) = \cot \left( \frac{k}{2} \right),
\]

where \(k \in [\pi/N, \pi - \pi/N]\). Then we obtain

\[
\sum_{n=0}^{N/2-1} \cot \left( \frac{(2n+1)\pi}{2N} \right) = \frac{N}{\pi} \int_{\pi/N}^{\pi/2} \cot \left( \frac{k}{2} \right) dk + R,
\]

where

\[
R = \frac{1}{2} \left[ \cot \left( \frac{\pi}{2} - \frac{\pi}{2N} \right) - \cot \left( \frac{\pi}{2N} \right) \right] - \int_{\pi/N}^{\pi/2} P_1 \left( \frac{Nk}{2\pi} - \frac{1}{2} \right) \frac{1}{\sin^2(k/2)} dk,
\]

with \(P_1(t)\) given in Eq. (B3). The integrand in the remainder has a singularity around \(k = 0\) and there main integral is no longer a good approximation of the sum. Nevertheless we can upper bound the scaling of the integral in the remainder, i.e.,

\[
\int_{\pi/N}^{\pi/2} \frac{1}{\sin^2(k/2)} \sim \cot \left( \frac{\pi}{2N} \right) + \epsilon.
\]

We thus conclude the remainder will scale at most as \(N\). Since \(\int_{\pi/N}^{\pi/2} \cot(k/2)dk \sim N \ln N\), we obtain the scaling of \(\gamma_0(N)\) in the main text. We see that in the current case the remainder depends on \(N\) instead of being a constant as indicated in Eq. (B12). We would like to emphasize that when the summand of a sum has a singularity in the limit \(N \to \infty\), it is not rigorous to analyze the scaling of the sum only with the main integral because the remainder may contribute to the scaling.

**Appendix C: The scaling of \(\gamma_0(N)\) for \(f_1(k) \leq O(1/k)\) near \(k = 0\)**

**Theorem 2.** We shall assume the only possible singularity of \(f_1(k)\) is near \(k = 0\), a fact which we will prove in Corollary 4. Then the scaling of \(\gamma_0(N)\) is controlled by the main integral if \(f_1(k) \leq O(1/k)\) near \(k = 0\).

**Proof.** Let us first focus on the case \(f_1(k)\) is strictly smaller than \(1/k\) near \(k = 0\). We denote \(E_j\) as the intervals where \(f_1([2x+1]\pi/N)\) is smooth as function \(x\). Similar as Sec. B, this denomination allows \(f_1(k)\) to be piecewise functions joined by smooth functions, as long as there are no singularities at the joints. The intervals \(E_j\) becomes \(F_j\) when the function is written in terms of the variable \(k\). In particular, one can easily show that \(f_1(\pi/N)\) is positive. Applying Euler-Maclaurin formula (B1) to each of these intervals, we find

\[
\gamma_0(N) = 2 \left\lfloor \sum_{j} \left( \int_{E_j} (1)^{j-1} f_1 \left( \frac{[2x+1]\pi}{N} \right) dx + R_{aj} \right) \right\rfloor, \tag{C1}
\]

where the remainder is

\[
R_{aj} = \int_{E_j} P_1(x) (1)^{j-1} f_1 \left( \frac{[2x+1]\pi x}{N} \right) dx + \text{boundary terms}.
\]

Since the boundary terms does not scale with \(N\), we shall suppress them in subsequent analysis. Now we change \(x\) back to \(k\), we find

\[
\gamma_0(N) = 2 \left[ \frac{N}{2\pi} \int_{\pi/N}^{\pi/2} f_1(k) dk + \sum_j R_{aj} \right], \tag{C3}
\]
where

\[ R_{aj} = \int_{F_j} P_1 \left( \frac{Nk}{2\pi} - \frac{1}{2} \right) (-1)^{j-1} f_a(k) dk. \] (C4)

For the remainders, if \( F_j \) does not contain the origin, then the integral in \( R_j \) is regular and does not scale with constant. For \( F_j \) contains the origin, we use a common trick in asymptotic analysis [43]: The leading order of a singular integral can be found by replacing the integrand with its leading order Laurent expansion near the singular point. In our current case, since

\[ f_a(k) < O\left( \frac{1}{k} \right), \] (C5)

we find

\[
\begin{align*}
\left| \int_{F_j} P_1 \left( \frac{Nk}{2\pi} - \frac{1}{2} \right) (-1)^{j-1} f_a(k) dk \right| \\
< \left| \int_{F_j} P_1 \left( \frac{Nk}{2\pi} - \frac{1}{2} \right) (-1)^{j-1} \left( \frac{1}{k} \right) dk \right| \\
\leq \left| \int_{\pi/N} \left( \frac{1}{k} \right) dk \right| \sim N,
\end{align*}
\]

where we have used that \( P_1(x) \in [-1/2, 1/2] \) is bounded. That is, the remainder scale strictly slower than \( N \), which is subleading order compared to the first term on the r.h.s. of Eq. (C3).

When \( f_a(k) \sim O(1/k) \), one can go through the same argument and will find that the main integral will scale as \( N \ln N \) while the upper bound of the scaling of the remainder is \( N \). Therefore, we conclude that the leading order scaling of \( \gamma_a(N) \) is only given by the main integral if \( f_a(k) \leq O(1/k) \) near \( k = 0 \).

□

We conclude this section by note that the condition \( f_a(k) \leq O(1/k) \) is non-trivial and essential: Had \( f_a(k) \) scaled as \( 1/k^{1+\varepsilon} \) near \( k = 0 \), where \( \varepsilon \) is an arbitrary positive number, the above proof would yield that both the main integral and the upper bound of the remainder \( R_{aj} \) scales \( N^{1+\varepsilon} \). The analysis of the scaling of \( \gamma_a(N) \) would be subtle because the leading order scaling of the main integral and the remainder \( R_{aj} \) might cancel each other. Fortunately, we see such a situation does not occur because we have shown in the main text that \( f_a(k) \leq O(1/k) \).

**Appendix D: The singularity of \( f_a(k) \) for \( \kappa_\alpha = l^{-\alpha} \) with \( \alpha \in (0, 1] \)**

In this section, we prove an analytic property of \( f_a(k) \) for the particular case where \( \kappa_\alpha = l^{-\alpha} \):

\[ f_a(k) \sim \frac{1}{k^{1-\alpha}}, \ \alpha \in (0, 1]. \] (D1)

This result can be shown using the singularity of the polylogarithm functions [23, 33]. However, this approach does not allows to obtain general property of \( f_a(k) \) when \( \kappa_\alpha \) takes a more general class of functions. Now we shall we explicitly show the singularity of \( f_a(k) \sim 1/k^{1-\alpha} \) around \( k = 0 \) for \( \alpha \in (0, 1] \) without resorting to the polylogarithm functions. Recall

\[ f_a(k) \equiv \sum_{l=1}^{N/2-1} \kappa_{\alpha} \sin(kl) + \kappa_{N/2, \alpha}. \] (D2)

Note that due to the regularity condition (E1), we know that \( \kappa_{N/2, \alpha} \) is finite as \( N \to \infty \). Therefore in what follows we shall omit \( \kappa_{N/2, \alpha} \) in the definition of \( f_a(k) \) because it does not affect the analytic property of \( f_a(k) \). Now we are in a position to prove Eq. (D1):

**Proof.** Apparently \( f_0(k) \) can be exactly calculated to be \( \cot(k/2) \) which scales as \( 1/k \) near \( k = 0 \). For the case \( \alpha \in (0, 1] \), after applying the Euler-Maclaurin formula (B1), \( f_a(k) \) becomes

\[ f_a(k) = 2 \mathcal{F}_a(k) + \mathcal{R}_a(k), \] (D3)

where

\[ \mathcal{F}_a(k) = \int_1^{N/2-1} \frac{\sin(kx)}{x^\alpha} dx, \] (D4)

and the remainder is

\[ \mathcal{R}_a(k) = 2k \int_1^{N} P_1((x)) \frac{\cos(kx)}{x^\alpha} - 2 \int_1^{N} P_1((x)) \frac{\sin(kx)}{x^{\alpha+1}}, \] (D5)

where we have again ignored the finite boundary terms. Apparently the second term in Eq. (D5) is finite and therefore will not contribute to the singularity of \( f_a(k) \), since

\[ 2 \left| \int_1^{N} P_1((x)) \frac{\sin(kx)}{x^{\alpha+1}} \right| < \left| \int_1^{N} \frac{1}{x^{\alpha+1}} \right| < \infty. \] (D6)

Our goal now is to determine the asymptotic behavior of the first term of Eq. (D5). Applying Fourier transform of \( P_1((x)) \) [42]

\[ P_1((x)) = -\sum_{m=1}^{-\infty} \frac{\sin(2m\pi x)}{m\pi}, \] (D7)

we obtain

\[ \int_1^{N} P_1((x)) \frac{\cos(kx)}{x^\alpha} dx = \frac{1}{2} \sum_{m=1}^{-\infty} \frac{1}{m\pi} \int_1^{N} \left\{ \frac{\sin(2m\pi + k)x}{x^\alpha} + \frac{\sin(2m\pi - k)x}{x^\alpha} \right\} dx. \] (D8)

Integrating by parts, we find that

\[ \int_1^{N} \frac{\sin(2m\pi + k)x}{x^\alpha} dx = \frac{1}{2m\pi + k} \left\{ \frac{\cos(2m\pi + k)x}{x^\alpha} \right\}^{N}_{x=1} \]

\[ + \alpha \int_1^{N} \frac{\cos(2m\pi + k)x}{x^{\alpha+1}} dx. \] (D9)
Apparently, the integral on the r.h.s. is bounded in the limit $N \to \infty$ as long as $\alpha > 0$. So in the limit $N \to \infty$, we find

$$\int_1^N \frac{\sin[(2m\pi + k)x]}{x^\alpha} \leq \frac{1}{2m\pi + k}. \quad (D10)$$

By similar argument, one can show

$$\int_1^N \frac{\sin[(2m\pi - k)x]}{x^\alpha} \leq \frac{1}{2m\pi - k}. \quad (D11)$$

Note if $k$ is resonant with $2m\pi$ then the original integral vanishes and there is no need to do the scaling analysis for the second integral on the r.h.s. of Eq. (D8). Substituting above results into Eq. (D8), we find

$$\int_1^N P_1(x) \frac{\cos(\pi x)}{x^\alpha} \leq \sum_{m=0}^{\infty} \frac{1}{m^2} < \infty. \quad (D12)$$

Up to now, we have shown that there is no singularity in the remainder as long as $\alpha > 0$. To see the singularity in the first term of Eq. (D3), we make change of variables $kl = s$ and obtain

$$F_\alpha(k) = \frac{1}{k^{1-\alpha}} \int_0^{\pi \alpha / 2} \frac{s \sin s}{s^\alpha} ds, \quad (D13)$$

where we note $Nk = (2n + 1)\pi$, where $n = 0, 1, \cdots, N-1$. In the limit $N \to \infty$, if finite $n$ is finite, apparently the singularity of $f_\alpha(k) \sim 1/k^{1-\alpha}$. On the other hand, if $n \to \infty$, the integral in Eq. (D13) is still finite since

$$\int_0^\infty \frac{\sin s}{s^\alpha} ds = \frac{\Gamma(1-\alpha)}{\alpha}, \quad \text{for } \alpha \in (0, 1] \quad (D14)$$

as we will now show. We note that

$$\lim_{n \to \infty} \int_0^{\pi \alpha / 2} \frac{s \sin s}{s^\alpha} ds = \int_0^\infty \frac{\sin s}{s^\alpha} ds = \text{Im} \int_0^\infty dss^{-\alpha}e^{i\pi}. \quad (D15)$$

One can evaluate Eq. (D15) by first replacing $s \to it$ and obtain

$$\int_0^\infty dss^{-\alpha}e^{i\pi} = i^{1-\alpha} \int_0^\infty dt t^{-\alpha} e^{-t}$$

$$= i^{1-\alpha} \lim_{\epsilon \to 0} \left[ \int_0^\epsilon dt t^{-\alpha} e^{-t} + \int_{\epsilon}^{\infty} dt t^{-\alpha} e^{-t} \right]. \quad (D16)$$

The convergence of the first integral on the r.h.s. of Eq. (D16) requires that $\alpha < 1$. The convergence of the second integral on the r.h.s. of Eq. (D16) requires the integrand vanishes at $t = \infty$, which leads to $\alpha > 0$. Now we take advantage of the analyticity of the integrand for $\alpha \in (0, 1]$ and rotate the integral from positive imaginary $r$-axis to positive real $r$-axis, which yields,

$$\int_0^\infty dt t^{-\alpha} e^{-t} = \int_0^\infty dt t^{-\alpha} e^{-t} = \Gamma(1-\alpha), \quad (D17)$$

which concludes the proof of Eq. (D14) for $\alpha \in (0, 1)$. In fact Eq. (D14) also holds for $\alpha = 1$ since $\int_0^\infty ds \sin s/s = \frac{\pi}{2}$ which can be evaluated by the residue theorem is actually $\lim_{\alpha \to 1} \Gamma(1-\alpha) \cos \left( \frac{\pi\alpha}{2} \right)$.

Therefore, we have successfully shown that the singularity of $f_\alpha(k)$ only lies in the main term of the Euler-Maclaurin formula, which is Eq. (D3).

**Appendix E: An integral approximation to $f_\alpha(k)$**

We show in Sec. D that the singularity of $f_\alpha(k)$ when $\kappa_{l,\alpha} = l^{-\alpha}$ can be explicitly found with only elementary techniques, without resorting to the polylogarithmic function as in the original proposal of the LRK [23]. The advantage of this approach is that it will allow us to prove the following theorem for general functions $\kappa_{x,\alpha}$ that satisfy the regularity conditions (E1, E2):

**Theorem 3.** We consider a general piecewise smooth function $\kappa_{x,\alpha}$ that satisfies the regularity conditions in the main text, i.e., $\kappa_{x,\alpha}$ satisfies (i) $|\kappa_{x,\alpha}^{(q)}| < \infty, \ q = 0, 1, \cdots, 2Q, \quad (E1)$

which holds piecewisely on $[1, \infty)$, and

(ii) $\left| \int_1^\infty \kappa_{x,\alpha}^{(2Q+1)} dx \right| < \infty, \quad (E2)$

where $Q$ is a non-negative integer and the superscript $(q)$ denotes the $q$-th derivative with respect to $x$.

Then the singularity of $f_\alpha(k)$ near $k = 0$ is controlled by the main integral in the Euler-Maclaurin formula, i.e., the first term in

$$f_\alpha(k) = 2F_\alpha(k) + R_\alpha(k). \quad (E3)$$

Before we start the proof, let us first note that for the long-range decay function $\delta_{l,\alpha}$, we allow not only smooth functions of $x$, but also piecewise functions consisting of several smooth functions. This is because, as we have seen in Sec. B and C, one can apply the Euler-Maclaurin in a piecewise way. The condition (E1) indicates there can be only discontinuities at the joints, but no singularities. Nevertheless, in what follows, we shall prove for the case when $\delta_{l,\alpha}$ is smooth $[1, \infty)$, which can be easily generalized to the case of piecewise smoothness without any difficulty.

**Proof.** We take $M = Q$ in the Euler-Maclaurin formula (B1), and obtain

$$f_\alpha(k) = 2F_\alpha(k) + R_\alpha(k), \quad (E4)$$

where

$$F_\alpha(k) = \int_1^N \sin(kx)\kappa_{x,\alpha} dx, \quad (E5)$$
\[ R_a(k) = \sum_{q=0}^{2Q+1} R_{a,q}(k) + \sum_{m=1}^{Q} \frac{b_{2m}}{(2m)!} (\sin(\kappa_{x,a})[2m-1])_{x=1}^{x=N/2-1} \]

\[ R_{a,q}(k) \equiv C_{Q,q} \int_{1}^{N/2-1} P_{2Q+1}(x) \sin(kx) x^{q} \left[ \frac{\cos((2Q+1-q)x)}{2Q+1} \right] dx, \]

\[ C_{Q,q} \equiv \left( \frac{2Q - 1}{q} \right) \frac{1}{(2Q + 1)!}. \]

Apparently, the boundary term is finite due to the regularity condition (E1). Thus we shall focus on the integral in the remainder \( R_{a}(k) \) subsequently. For \( q = 0 \), we find

\[ R_{a,0}(k) \leq C_{Q,0} C_{2Q+1} \left| \int_{1}^{N/2-1} \kappa_{x,a}^{2Q+1} dx \right| < \infty, \]

where we have used the fact that \( P_{2Q+1}(x) \) is bounded, \( |P_{2Q+1}(x)| \leq C_{2Q+1} \) and Eq. (E2). When \( q \geq 1 \), we apply the Fourier transform of \( P_{2Q+1}(x) \) [42]

\[ P_{2Q+1}(x) = \sum_{m=1}^{\infty} (-1)^{m-1} \frac{2 \sin(2m\pi x)}{(2m\pi)^{2Q+1}}. \]

to Eq. (E7). For even \( q > 0 \), we obtain

\[ R_{a,q}(k) = C_{Q,q} k^{q} (-1)^{Q-1+q/2} \sum_{m=1}^{\infty} \frac{1}{(2m\pi)^{2Q+1}} \times \]

\[ \int_{1}^{N/2-1} (\cos(2m\pi - k)x) - \cos(2m\pi + k)x) \kappa_{x,a}^{2Q+1-q} dx, \]

and for odd \( q \geq 1 \), we obtain

\[ R_{a,q}(k) = C_{Q,q} k^{q} (-1)^{Q-1+(q-1)/2} \sum_{m=1}^{\infty} \frac{1}{(2m\pi)^{2Q+1}} \times \]

\[ \int_{1}^{N/2-1} [\sin(2m\pi + k)x] + \sin(2m\pi - k)x) \kappa_{x,a}^{2Q+1-q} dx. \]

Since the convergence of the series is determined by the behavior of the general term at large values of the index, we shall focus on the case of large \( m \) in the series in Eqs. (E11, E12) subsequently. Similarly with Eqs. (D9-D12), one can perform integration by parts until one gets an integrand that contains \( (\kappa_{x,a})^{2Q+1} \), which yields

\[ \int_{1}^{N/2-1} \cos(2m\pi \pm k)x) \kappa_{x,a}^{2Q+1-q} dx = \frac{1}{(2m\pi \pm k)} [\sin(2m\pi \pm k)x] \kappa_{x,a}^{2Q+1-q} \bigg|_{x=\infty}^{x=1} + \cdots \]

\[ + \frac{1}{(2m\pi \pm k)} \left[ \cos(2m\pi \pm k)x \kappa_{x,a}^{2Q+2-q} \bigg|_{x=\infty}^{x=1} \right] + \cdots \]

\[ + \frac{(-1)^{q-1/2}}{(2m\pi \pm k)^q} \int_{1}^{N/2-1} \cos(2m\pi \pm k)x) \kappa_{x,a}^{2Q+1} dx, \]

Apparently the last integral is bounded, according to Eq. (E2). Therefore, for large \( m \) we know

\[ \left| \int_{1}^{N/2-1} \cos((2m\pi \pm k)x) \kappa_{x,a}^{2Q+1-q} dx \right| \leq \frac{C_{2Q+1-q}(\alpha)}{(2m\pi \pm k)}, \]

where

\[ C_q(\alpha) \equiv \left( \kappa_{x,a}^{q} \right)_{x=1}^{x=N/2-1} \left| \kappa_{x,a}^{q} \right|_{x=\infty}. \]

which is finite according to the regularity condition Eq. (E1). With similar argument, we obtain

\[ \left| \int_{1}^{N/2-1} \sin((2m\pi \pm k)x) \kappa_{x,a}^{2Q+1-q} dx \right| \leq \frac{C_{2Q+1-q}(\alpha)}{(2m\pi \pm k)} \]

for large \( m \). So we conclude

\[ |R_{a,q}(k)| \leq C_{Q,q} C_{2Q+1-q}(\alpha) k^{q} \sum_{m=1}^{\infty} \frac{1}{(2m\pi)^{2Q+2}}, \]

which is bounded for all finite values of \( k \). Now we have shown that the remainder \( R_{a,q}(k) \) is regular with no singularity in \( k \), which completes the proof. □

**Appendix F: The possible singularity of \( F_a(k) \) or \( f_a(k) \) for \( \kappa_{x,a} \) satisfying the regularity conditions**

**Corollary 4.** If \( \kappa_{x,a} \) satisfies the regularity conditions (E1-E2), then \( F_a(k) \) is regular as long as \( k \neq 0 \).

**Proof.** The proof is straightforward: performing integration by part for the main integral in Eq. (E3), we find

\[ \int_{1}^{N/2-1} \sin(kx) \kappa_{x,a} dx = \frac{\cos(kx)}{k} \kappa_{x,a} \bigg|_{x=N/2-1}^{x=1} + \frac{\sin(kx)}{k^{2}} \kappa_{x,a} \bigg|_{x=N/2-1}^{x=1} + \cdots + \frac{(-1)^{q}}{k^{2}} \int_{1}^{N/2-1} \cos(kx) \kappa_{x,a}^{2Q+1} dx. \]

Since the integral is bounded according to Eq. (E2), we find

\[ |F_a(k)| \leq \sum_{m=1}^{2Q} \frac{C_{m-1}(\alpha)}{k^{m}}. \]

Thus, \( f_a(k) \) or \( F_a(k) \) are bounded as long as \( k \neq 0 \). □

From this proof, we immediately see that the only possible singularity of \( F_a(k) \) is at \( k = 0 \). As we have mentioned in the main text, we can introduce a trick to get a rough estimate about the possible singularity of the main integral \( F_a(k) \) near \( k = 0 \). We integrate over \( k \) from \( 1/N \) to \( \Lambda \), where \( \Lambda \) is finite. This yields

\[ \int_{1/N}^{\Lambda} dk F_a(k) = \int_{1/N}^{N/2-1} \frac{\kappa_{x,a}}{x} dx - \int_{1}^{N/2-1} \frac{\kappa_{x,a} \cos(\Lambda x)}{x} dx \]

(E3)
where we have interchanged the order of integration. According to Sec. G, the second integral on the r.h.s. of Eq. (F3) is bounded and the exact scaling with respect to $N$ can be easily found by integrating by parts. Therefore the scaling of $\int_{1/N}^{N} \mathcal{F}_a(k)dk$ is totally controlled by the first integral on the r.h.s of Eq. (F3). If the scaling of $\int_{1/N}^{N} \mathcal{F}_a(k)dk$ can be computed, it can reveal some partial information about the singularity of $\mathcal{F}_a(k)$ around $k = 0$. For example, if $\int_{1/N}^{N} \mathcal{F}_a(k)dk \sim \ln N$, then we know the singularity of $\mathcal{F}_a(k)$ at $k = 0$ is at most $1/k^{1-\varepsilon}$ or $1/k$ respectively, where $\varepsilon$ is arbitrary small positive number.

**Appendix G: The convergence of the integral $\int_{1}^{\infty} \kappa_{\alpha,\alpha} \cos(\lambda x)/x dx$**

One can prove the integral $\int_{1}^{\infty} \kappa_{\alpha,\alpha} \cos(\lambda x)/x dx$ is bounded via integration by parts. First, it is found that

$$\int_{1}^{\infty} \kappa_{\alpha,\alpha} \cos(\lambda x)/x dx = \frac{1}{\lambda} \sin(\lambda x) \kappa_{\alpha,\alpha} \frac{x}{x} |_{x=1}^{\infty} + \frac{1}{\lambda^2} \sin(\lambda x) \kappa_{\alpha,\alpha} \frac{x}{x} |_{x=1}^{\infty} + \frac{1}{\lambda^2} \cos(\lambda x) \kappa_{\alpha,\alpha} \frac{x}{x} |_{x=1}^{\infty} + \cdots + \frac{1}{\lambda^{2q+2}} \cos(\lambda x) \kappa_{\alpha,\alpha} \frac{x}{x} |_{x=1}^{\infty}.$$

Thus the convergence of $\int_{1}^{\infty} \kappa_{\alpha,\alpha} \cos(\lambda x)/x dx$ depends on $\int_{1}^{\infty} \sin(\lambda x) \kappa_{\alpha,\alpha} \frac{x}{x} |_{x=1}^{\infty}$. We use

$$\int_{1}^{\infty} \cos(\lambda x) \kappa_{\alpha,\alpha} \frac{x}{x} |_{x=1}^{\infty} < \int_{1}^{\infty} \kappa_{\alpha,\alpha} \frac{x}{x} |_{x=1}^{\infty} < \infty,$$

where $q = 1, 2, \ldots, \infty$ and

$$C_{\alpha,\alpha}^{(q)} \equiv \max_{x \in [1, \infty]} |\kappa_{\alpha,\alpha}(x)|.$$

According to regularity condition (E2), we conclude that the integral $\int_{1}^{\infty} \kappa_{\alpha,\alpha} \cos(\lambda x)/x dx$ is convergent.

**Appendix H: Finite-size scaling**

We note that Eq. (27) in the main text gives the asymptotic scaling of $I_0(\Delta)$ in the thermodynamics limit $N \to \infty$. For $\kappa_{\alpha,\alpha} = x^{-\alpha}$, super-HS transition only occurs at $\alpha = 0$ for $N \to \infty$. However, for large but finite $N$, small $\alpha$ near zero may also lead the super-HS, which we now discuss. Setting $\alpha = \epsilon$, where $\epsilon$ is a small number, we obtain

$$\int_{1}^{N} \frac{dx}{x^{1+\epsilon}} = \int_{1}^{N} \frac{dx}{x} e^{-\ln x}\epsilon = \int_{1}^{N} \frac{dx}{x} \left[ \sum_{n=0}^{\infty} (-1)^n e^{n(\ln x)^n} \right] = \sum_{n=0}^{\infty} \frac{(-1)^n e^n}{n!} \int_{1}^{N} dx \frac{(\ln x)^n}{x} = S(\epsilon \ln N) \ln N,$$

where

$$S(a) \equiv \sum_{n=0}^{\infty} \frac{(-1)^n a^n}{n!},$$

Therefore we find when

$$\epsilon \ln N \ll 1$$
\( S(\epsilon \ln N) \to 1 \), so that
\[
\int_1^N \frac{dx}{x^{1+\epsilon}} \sim \ln N. \tag{H4}
\]
Alternatively, \( S(a) \) may be evaluated exactly, which is
\[
S(a) = \frac{1}{a} \sum_{n=1}^{\infty} \frac{(-1)^n a^n}{n!} = \frac{1}{a} (1 - e^{-a}). \tag{H5}
\]
From which one can clearly see that \( S(\epsilon \ln N) \to 1 \) as \( \epsilon \ln N \to 0 \). Therefore, according to Eq. (27) in the main text, we see that for \( \xi_{x,\epsilon} = x^{-\epsilon} \), we have
\[
I_0(\Delta) \sim N^2 (\ln N)^2, \text{ for } \epsilon \ll (\ln N)^{-1}. \tag{H6}
\]
By similar analysis, one can show analogously that for \( \xi_{1+\epsilon} = (1 + \ln x)^{-1+\epsilon} \)
\[
I_0(\Delta) \sim N^2 (\ln N)^2, \text{ for } \epsilon \ll (\ln N)^{-1}. \tag{H7}
\]

Appendix I: The LRK Hamiltonian in the spin representation

With the Jordan-Wigner transformation [34],
\[
a^\dagger_j = (-1)^{j-1} \prod_{k=1}^{j-1} \sigma^z_k \sigma^+_j, \tag{I1}
\]
\[
a_j = (-1)^{j-1} \prod_{k=1}^{j-1} \sigma^z_k \sigma^-_j, \tag{I2}
\]
where \( \sigma^z_j \) is the standard Pauli z-matrix
\[
\sigma^z_j = \begin{bmatrix} 1 & 0 \\ 0 & -1 \end{bmatrix} \tag{I3}
\]
\[
\sigma^+_j = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \tag{I4}
\]
\[
\sigma^-_j = \begin{bmatrix} 0 & 0 \\ 1 & 0 \end{bmatrix} \tag{I5}
\]

It is readily checked that
\[
a_j^\dagger a_j = \sigma^+_j \sigma^-_j = \frac{1}{2}(\sigma^+_j + 1), \tag{I5}
\]
\[
a_{j+1}^\dagger a_j = -\sigma^+_j \sigma^-_j \sigma^+_j = \sigma^+_j \sigma^-_j, \tag{I6}
\]
where we have used the fact \( \sigma^+_j \sigma^-_j = \pm \sigma^z_j \) in the second equation. Furthermore,
\[
a_j a_{j+1} = (-1)^{j-1} \prod_{k=1}^{j-1} \sigma^z_k \sigma^-_j x (\epsilon_i) \prod_{k=1}^{j-1} \sigma^z_k \sigma^-_j \left[ (-1)^{j+1} + \prod_{m=1}^{j-1} \sigma^z_j \sigma^-_m \right] \text{ or} \prod_{k=1}^{j-1} \sigma^z_k \sigma^-_j \left[ (-1)^{j+1} + \prod_{m=1}^{j-1} \sigma^z_j \sigma^-_m \right] \tag{I7}
\]
where we have used the fact that \( \sigma^+_j \sigma^-_j = \mp \sigma^z_j \). Now using the relation
\[
\sigma^+_j \equiv \frac{1}{2}(\sigma^-_j + i \sigma^y_j), \tag{I8}
\]
\[
\sigma^-_j \equiv \frac{1}{2}(\sigma^-_j - i \sigma^y_j), \tag{I9}
\]
where \( \sigma^+_j \) and \( \sigma^y_j \) are standard Pauli x– and y– matrices respectively, we find
\[
\sigma^+_j \sigma^-_j \sigma^z_j + \sigma^z_j \sigma^+_j \sigma^-_j = \frac{1}{4}(\sigma^+_j + i \sigma^y_j)(\sigma^-_j - i \sigma^y_j) + \frac{1}{4}(\sigma^+_j - i \sigma^y_j)(\sigma^-_j + i \sigma^y_j)
\]
\[
= \frac{1}{2}(\sigma^+_j \sigma^-_j + \sigma^y_j \sigma^y_j), \tag{I10}
\]
\[
\sigma^+_j \sigma^-_j \sigma^z_j + \sigma^z_j \sigma^-_j \sigma^+_j = \frac{1}{4}(\sigma^+_j + i \sigma^y_j)(\sigma^-_j + i \sigma^y_j) + \frac{1}{4}(\sigma^+_j - i \sigma^y_j)(\sigma^-_j - i \sigma^y_j)
\]
\[
= \frac{1}{2}(\sigma^+_j \sigma^-_j - \sigma^y_j \sigma^y_j). \tag{I11}
\]
Using Eqs. (I1, I2, I10), the tunneling and kinetic terms become
\[
\sum_{j=1}^{N} (a_j^\dagger a_{j+1} + a_{j+1}^\dagger a_j) = \sum_{j=1}^{N} (\sigma^+_j \sigma^-_j + \sigma^-_j \sigma^+_j) = \frac{1}{2} \sum_{j=1}^{N} (\sigma^+_j \sigma^z_j + \sigma^y_j \sigma^y_j), \tag{I12}
\]
and
\[ \sum_{j=1}^{N} (a_j^\dagger a_j - \frac{1}{2}) = \frac{1}{2} \sum_{j=1}^{N} \sigma_j^z, \tag{113} \]
respectively. For the long-range superconducting terms, with the anti-periodic boundary condition, one can easily obtain the following alternative form
\[ \sum_{j=1}^{N-1} \sum_{l=1}^{N-j} k_{l,a} a_j a_{j+l} = \frac{1}{2} \sum_{j=1}^{N-1} \sum_{l=1}^{N-j} k_{l,a} a_j a_{j+l}, \tag{114} \]
and a similar equation for the term \( \sum_{j=1}^{N-1} \sum_{l=1}^{N-j} k_{l,a} a_j a_{j+l}^\dagger \). On the other hand, with Eqs. (I.1, I.2, I.11), we find
\[ \sum_{j=1}^{N} \sum_{l=1}^{N-1} k_{l,a} (a_j a_{j+l} + a_j^\dagger a_{j+l}^\dagger) = \frac{1}{2} \sum_{j=1}^{N} \sum_{l=1}^{N-1} (-1)^l k_{l,a} (\sigma_j^x \sigma_{j+l}^x - \sigma_j^y \sigma_{j+l}^y) \sigma_{j+l-1}^z \cdots \sigma_j^z. \tag{115} \]
Substituting Eqs. (I.12-I.15) into Eq. (6) in the main text yields the LRK Hamiltonian in the spin-representation, i.e., Eq. (36) in the main text.
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