A Modified Implementation of Tristate Inverter Based Static Master-Slave Flip-Flop with Improved Power-Delay-Area Product

Kunwar Singh, Satish Chandra Tiwari, and Maneesha Gupta

1 Department of Electrical Engineering, Delhi Technological University, Room No. FW1-SFl, EED, DTU, New Delhi 110042, India
2 Division of ECE, Netaji Subhas Institute of Technology (NSIT), University of Delhi, Sector 3, Dwarka, New Delhi 110078, India

Correspondence should be addressed to Kunwar Singh; kunwarsingh@dce.ac.in

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The paper introduces novel architectures for implementation of fully static master-slave flip-flops for low power, high performance, and high density. Based on the proposed structure, traditional C<sup>2</sup>MOS latch (tristate inverter/clocked inverter) based flip-flop is implemented with fewer transistors. The modified C<sup>2</sup>MOS based flip-flop designs mC<sup>2</sup>MOSff<sub>1</sub> and mC<sup>2</sup>MOSff<sub>2</sub> are realized using only sixteen transistors each while the number of clocked transistors is also reduced in case of mC<sup>2</sup>MOSff<sub>1</sub>. Postlayout simulations indicate that mC<sup>2</sup>MOSff<sub>1</sub> flip-flop shows 12.4% improvement in PDAP (power-delay-area product) when compared with transmission gate flip-flop (TGFF) at 16X capacitive load which is considered to be the best design alternative among the conventional master-slave flip-flops. To validate the correct behaviour of the proposed design, an eight bit asynchronous counter was designed at layout level. LVS and parasitic extraction were carried out on Calibre, whereas layouts were implemented using IC station (Mentor Graphics). HSPICE simulations were used to characterize the transient response of the flip-flop designs in a 180nm/1.8V CMOS technology. Simulations were also performed at 130nm, 90nm, and 65nm to reveal the scalability of both the designs at modern process nodes.

1. Introduction

Flip-flops are the key elements used in sequential digital systems. The appropriate selection of flip-flop topologies is instrumental in the design of VLSI integrated circuits such as microprocessors, microcontrollers, and other high complexity chips. However, factors such as high performance, low power, transistor count, clock load, design robustness, power-delay, and power-area tradeoffs are generally considered before choosing a particular flip-flop design. The highest operating frequency of clocked digital systems is determined by the flip-flops. Flip-flops and clock distribution network generally account for 30–70% of the total chip power consumption [1, 2]. Clock load is another major concern for digital system designers and several contributions have been reported in the past to reduce clock load and the associated power dissipation in the clocking network [3–5]. A design with elevated transistor count occupies a larger area on chip and leads to an increase in the overall manufacturing cost. Hence, design and implementation of low power high performance flip-flops with the least possible chip area is the main target of the modern chip manufacturing industry.

Flip-flops are broadly classified into three main categories, namely, master-slave [6–11], pulse triggered [12–17], and differential flip-flops [18–21]. Among them, master-slave and pulse-triggered flip-flops are the most efficient in terms of power-delay product. Master-slave flip-flops exhibit positive (negative) set-up time (hold time) requirements and hence not suitable for high speed systems due to extended data to output delays. But they are power efficient and can be used in low power applications. However, their main limitation is less robustness to clock skew. Pulse-triggered flip-flops have negative set-up time and thus lead to smaller data to output delay. They exhibit inherent soft clock edge property which minimizes clock skew related cycle time loss.
A classification of master-slave flip-flops is further elaborated in Figure 1. Clock-gated topologies exhibit internal clock gating to suppress the power consumption at lower data switching activities based on a clock gating logic and a comparator circuit. However, clock-gated flip-flops have extended latency due to enhanced clock-to-output delays along with increased chip area overhead. Clock-gated structures generally consume lesser power at low switching activities [22]. TGFF represents the best choice in the nonclock-gated flip-flop category in terms of power-delay product [6], whereas existence of NMOS transistors in the critical path along with partially nongated keepers leads to less significant power-delay tradeoff characteristics in case of write port master-slave flip-flop (WPMS) [7, 8] and pass transistor logic based flip-flop (PTLFF) [9].

In this paper, we introduce an alternative design approach for designing \( C^2 \)MOS based master-slave flip-flop, based on a new architecture with reduced transistor count and improved power-delay-area product. The proposed configurations \( mC^2 \)MOSff1 and \( mC^2 \)MOSff2 fall under the nonclock-gated flip-flop category as shown in Figure 1.

The rest of the paper is organized as follows. Section 2 compares the conventional master-slave flip-flop configurations with proposed designs. Section 3 highlights the simulation parameters and test bench along with techniques used for transistor sizing and methodology adopted for optimization of timing and power-delay product. Section 4 describes the simulation results. Section 5 concludes the paper. An appendix is added to show the calibration of parameters for delay calculations using LE theory and to outline the strategy followed for designing the eight-bit ripple counter.

2. Overview of Previous Work and Proposed Designs

Figure 2 shows the conventional master-slave flip-flop architecture, whereby two regenerative loops (L1 and L2) are present in the master and slave sections to account for a static functionality. Both loops operate independently of each other on complementary clock signals. Regenerative loops are composed of cross-coupled inverters. It can be observed from Figure 2 that for each loop, regenerative action is achieved through one inversion in the forward (critical) path while the other (clocked) inversion takes place in the feedback path. Moreover, there is no common component between both loops.

Since an inverter followed by transmission gate is equivalent to a clocked inverter, the combination is replaced by a clocked inverter to form a \( C^2 \)MOS based flip-flop architecture as shown in Figure 3 [23]. Two regenerative loops L3 and L4 are used in a similar manner as in the previous case to maintain the static nature of the flip-flop.
However, in the proposed architecture as reported in Figure 4(a), both inversions take place in the forward (critical) path and the loop is completed by a clocked switch for loop L6 while loop L5 is completed by using an inverter in the feedback path. It is clearly noticed from Figure 4(a) that the output node is always driven and never floating thus ensuring a static flip-flop operation. The size of transistors in the feedback path marked by asterisks (*) is kept at 360 nm (minimum technology width) to eliminate race conditions at nodes U and V. Yet another implementation is shown in Figure 4(b) which uses inverter INVX in the critical path and a clocked switch to form a regenerative loop L7. It is to be noted that INVX is common to both the regenerative loops L7 and L8 which is contrary to the realization of previous architectures.

Figure 5 represents the actual circuit design based on the proposed architectures in Figure 4, while TGFF is implemented using transmission gates as switches in the conventional architecture as demonstrated in Figure 6.

It can be clearly observed that mC²MOSff1 and mC²MOSff2 both are realized using sixteen transistors each. As a result, the area occupied by the proposed designs is significantly lesser than the conventional designs. Moreover, the number of clocked transistors in mC²MOSff1 is six as compared to eight in case of TGFF or conventional clocked inverter based flip-flop C²MOSff [23].

To illustrate the superior performance of the proposed flip-flop configurations, other flip-flop topologies, namely, TGFF, WPMS, PTLFF, gated master-slave latch (GMSL) [10], and data transition look ahead flip-flop (DTLA) [11] belonging to the master-slave class have been used for comparisons. Out of the above mentioned topologies GMSL, and DTLA represent flip-flops with internal clock gating. Schematic diagrams of WPMS, PTLFF, GMSL and DTLA are shown in Figures 7, 8, 9, and 10, respectively.

3. Simulation Parameters, Test Bench, and Optimization Methodology

Table 1 lists the CMOS parameters used for creating the simulation environment. The flip-flops were designed to layout level in 180 nm/1.8 V CMOS process at 250 MHz clock frequency. The width of transistors in the feedback structures was invariably fixed at the minimum value 360 nm while the slope of the data and clock signals was kept at 100 ps. Performances of the various flip-flop configurations are evaluated through SPICE simulation of the circuits extracted from the layout with the inclusion of parasitics.
Figure 5: Schematic diagrams of the proposed designs.

Table 1: Simulation parameters.

| Parameter | Value |
|-----------|-------|
| $W_{\text{min}}$ | 360 nm |
| $L_{\text{min}}$ | 140 nm |
| $C_{\text{min}}$ | 1.24 fF |
| $V_{\text{DD}}$ | 1.8 V |
| Frequency | 250 MHz |
| Signal slope | 100 ps |

Figure II shows the simulation test bench for characterization and comparison of the FF designs [3]. The clock and data signals are fed to the flip-flop through a two stage buffer. Data-to-output delay ($T_{\text{DQ, min}}$) is used for performance comparisons. Logical effort theory is extensively used for designing fast CMOS circuits based on pencil and paper calculations and is widely adopted in the literature [24]. Hence, the delay sensitivity factor introduced by Alioto et al. [25] based on logical effort theory has been used for performance optimization.

A 16-cycle long pseudorandom sequence with a switching factor $\alpha = 0.5$ is supplied at the data input for measurement of average power [26]. Since the delay and power characterization are strongly dependent on the capacitive load offered to FFs [27], varying capacitive loads $\{4, 16, 64\} \ C_{\text{min}}$, where $C_{\text{min}}$ is the input capacitance of a symmetrical minimum inverter ($W_p = 2W_n = 2W_{\text{min}}$), have been used to test the FF behaviour. Transistor sizing methodology adopted is the same as that in [28, 29], whereas power-delay product (PDP) and power-delay-area product (PDAP) are the chosen figures of merit (FOM).

The expression relating the absolute gate capacitance ($C_{\text{GATE}}$) in terms of $fF$ (femtofarads) and absolute transistor width ($W$) in terms of nanometers (nm) obtained at 180 nm process node by fitting simulation data [30] is given as

$$C_{\text{GATE}} = (1.15 \cdot 10^{-3}) \cdot W.$$  (1)
Figure 6: TGFF based on conventional architecture.

Figure 7: Schematic diagram for Write port master slave flip-flop (WPMS).

Figure 8: Schematic diagram for pass transistor logic style flip-flop (PTLFF).

Figure 9: Schematic diagram for Gated master slave latch (GMSL).

Figure 10: Schematic diagram for data transition look ahead flip-flop (DTLA).

LE method states that the optimized delay $D$ of a path of $N$ cascaded stages is

$$D = N \sqrt{GH} + P,$$

(2)

$$D = N \sqrt{F} + P,$$

(3)

where $G$, $B$, $H$ $(= C_L/C_{in})$ are the logical effort, branching effort, and electrical effort while $P$, $F$ $(= GBH)$ and $C_L$ are parasitic delay, path effort, and final load capacitance, respectively. One has the following:

$$D = P(1 + t).$$

(4)

From (2) and (4),

$$t = \frac{N \sqrt{GH} \sqrt{C_L}}{P \sqrt{C_{in}}}$$

(5)

where $t$ represents the relative delay increment with respect to parasitic delay. Equations (4) and (5) indicate that larger values of $C_{in}$ lead to a saturation in the optimized delay and based on the above analysis, the delay sensitivity factor introduced by Alioto et al. [25] is utilized to obtain the upper bound on the transistor widths for exploration of the power-delay design space with least computational effort. Consider the following:

$$S_{D}^C = \frac{\partial D}{\partial C_{in}} \frac{C_{in}}{D} = -\frac{1}{Nt + 1},$$

(6)
4. Results and Discussion

It is a well-established fact that the conventional $C^2$MOS although slower, is skew tolerant and occupies lesser area than TGFF [23, 33]. Moreover, $mC^2$MOSSF1 and $mC^2$MOSSF2 show nearly identical characteristics in terms of power, delay, and area and hence only $mC^2$MOSSF1 is considered for comparisons.

The waveforms in Figure 13 represent the transient analysis of $mC^2$MOSSF1 carried out over a period of 8 clock cycles. The SPICE simulation results verify the correct flip-flop operation at 1GHz clock frequency (all the flip-flops reported in the paper are designed for negative edge triggered operation). The variation of absolute data-to-output delays $T_{DQ,\text{min}}$ with FF input capacitance ($C_{in}$) for 16X (19.92 fF) capacitive load is illustrated in Figure 14.

TGFF utilizes transmission gates in the critical path and hence it is faster than the rival designs. There is exactly the same number of stages in the critical path of TGFF and $mC^2$MOSSF1, the only difference being that the latching circuit in case of TGFF is an inverter followed by a clocked transmission gate (inverting latch), whereas a clocked/tristate inverter is present in $mC^2$MOSSF1. Logical effort of both the latches is considered to be two; however, it is apparent that an inverter followed by a transmission gate is faster because the output node is driven by both the transistors of the transmission gate in parallel and this behaviour is reflected in Figure 14. From the above discussion, it is obvious that the value of logical effort for an inverting latch can be assumed to be two for most theoretical purposes, but for comparison with a $C^2$MOS latch, it must be slightly less than two if delays are to be modelled precisely.

Equation (2) clearly indicates that lesser branching effort leads to a faster circuit operation. The branching effort for a path with internal fan-out is expressed as [24]

$$b = \frac{C_{\text{on-path}} + C_{\text{off-path}}}{C_{\text{on-path}}}$$

where $C_{\text{on-path}}$ represents the load capacitance along the path under analysis and $C_{\text{off-path}}$ represents the capacitance of the connections that lead off the path.

The branching effort along the critical path is given as

$$B = \prod b_j$$

There are two branches each in TGFF and $mC^2$MOSSF1 represented as $b_1$, $b_2$ and $b_3$, $b_4$ in Figures 6 and 5(a), respectively. The branching effort corresponding to branches $b_1$, $b_2$, $b_3$, and $b_4$ is calculated as follows.

4.1. Branching Effort in Case of TGFF. One has the following.

$b_1$ Calculation:

$$C_{\text{on-path}} = C_{gd} (\text{TN5}) + C_{db} (\text{TN5})$$

$$+ C_{gd} (\text{TP5}) + C_{db} (\text{TP5}) = 8.43 \text{ fF},$$

$$C_{\text{off-path}} = C_g (\text{TN2}) + C_g (\text{TP2}) = 1.12 \text{ fF},$$

$$b_1 = 1.13.$$  \hspace{2cm} (10)

$b_2$ Calculation:

$$C_{\text{on-path}} = C_g (\text{TN9}) + C_g (\text{TP9}) = 12.33 \text{ fF},$$

$$C_{\text{off-path}} = C_g (\text{TN6}) + C_g (\text{TP6}) = 1.12 \text{ fF},$$

$$b_2 = 1.09,$$

$$B = b_1 \times b_2 = 1.23.$$  \hspace{2cm} (11)

4.2. Branching Effort in Case of $mC^2$MOSSF1. One has the following.

$b_3$ Calculation:

$$C_{\text{on-path}} = C_g (\text{TN14}) + C_g (\text{TP14}) = 7.76 \text{ fF},$$

$$C_{\text{off-path}} = C_{gd} (\text{TN16}) + C_{db} (\text{TN16}) + C_{gd} (\text{TP16})$$

$$+ C_{db} (\text{TP16}) = 1.47 \text{ fF},$$

$$b_3 = 1.18.$$  \hspace{2cm} (12)
Table 2: Traditional transmission gate flip-flop at 19.92 fF load (16X).

| $C_{in}$ (fF) | $w_1$ | $w_2$ | $w_3$ | $w_4$ | $T_{D0,min}$ (ps) | Power (uW) | PDP (fJ) |
|--------------|------|------|------|------|-----------------|-----------|---------|
| 2.48         | 2    | 2.35 | 2.79 | 6.65 | 226             | 554       | 125.2   |
| 4.96         | 4    | 3.95 | 3.95 | 7.91 | 191             | 585       | 111.7   |
| 7.44         | 6    | 5.35 | 4.84 | 8.76 | 173             | 599       | 103.6   |
| 9.92         | 8    | 6.65 | 5.59 | 9.41 | 166             | 615       | 102     |
| 12.4         | 10   | 7.86 | 6.25 | 9.95 | 162             | 632       | 102.3   |
| 14.8         | 12   | 9.01 | 6.85 | 10.4 | 159             | 648       | 103     |
| 17.3         | 14   | 10.1 | 7.40 | 10.8 | 157             | 665       | 104.4   |
| 19.8         | 16   | 11.1 | 7.91 | 11.2 | 155             | 675       | 104.6   |
| 22.3         | 18   | 12.2 | 8.39 | 11.5 | 154             | 682       | 105     |
| 24.8         | 20   | 13.2 | 8.84 | 11.8 | 153             | 689       | 105.4   |

Table 3: Technology parameters used for estimation of capacitances.

| Parameter | $C_{gdo}$ (F/m) | $C_{gso}$ (F/m) | $C_{jsw}$ (F/m) | $C_j$ (F/m$^2$) | $L_D$ (m) | $L_S$ (m) |
|-----------|-----------------|-----------------|-----------------|-----------------|----------|----------|
| NMOS      | $2.78E - 10$    | $2.78E - 10$    | $7.9E - 10$     | $0.00365$       | $31.6E - 09$ | $31.6E - 09$ |
| PMOS      | $2.78E - 10$    | $2.78E - 10$    | $1.44E - 9$     | $0.00138$       | $31.6E - 09$ | $31.6E - 09$ |

Calculation:

$$C_{on-path} = C_{g} (TN14) + C_{g} (TP14) = 7.76 \text{ fF},$$

$$C_{off-path} = C_{g} (TN13) + C_{g} (TP13) = 0.828 \text{ fF},$$

$$b4 = 1.10,$$

$$B = b3 \times b4 = 1.30,$$

where $C_{pd}$ is gate to drain capacitance, $C_{db}$ is drain to body capacitance, and $C_{g}$ is the gate capacitance of respective transistors.

Accordingly, using (2) and putting $G = 4, B = 1.23, H = 19.92/12.4 = 1.60, N = 4, and P = 6, we have $D = 12.7$ (absolute delay 165.1 ps) for TGFF; whereas putting $G = 4, B = 1.30, H = 19.92/12.4 = 1.60, N = 4, and P = 6, we have $D = 12.79$ (absolute delay 166.27 ps) for mC$^2$MOSff. Absolute delays $D_{abs}$ are obtained by multiplying parameter $D$ with parameter $\tau$ as follows:

$$D_{abs} = D\tau.$$
It is clearly observed that the delay of mC²MOSff1 is marginally higher than the delay of TGFF. Now, keeping other parameters to be the same and assuming the logical effort of inverting latch to be 1.8, the updated value of TGFF is evaluated as $D = 12.35$ (absolute delay 160.55 ps).

The value of process dependent parameter $\tau$ is determined as approximately 13 ps using the calibration technique as mentioned by Sutherland et al. [24]. The detailed procedure is discussed in the Appendix. The absolute delay measurements obtained through simulation are 162 ps for TGFF and 196 ps for mC²MOSff1 which is in close agreement with the theoretical values 160.55 ps and 166.27 ps, respectively (typically within 15% error).

WPMS and PTLFF topologies show degraded performance due to the presence of pass transistors in the critical path while the speed of clock-gated structures is worst mainly because gating circuit is inserted between the clock and the flip-flop terminals which deteriorates the timing characteristics. The characterizations are done assuming that $C_{in} = 12.4\ \text{fF}$ and $C_L = 19.92\ \text{fF}$ (16X) where $C_L$ represents the flip-flop load capacitance.

The variation of average power with $C_{in}$ for 16X loading condition is depicted in Figure 15. Due to threshold voltage drop at internal nodes, WPMS and PTLFF display worst power dissipation characteristics because of short circuit power dissipation. GMSL and DTLA exhibit greater power dissipation than nongated counterparts because pseudorandom sequence has an activity factor of 0.5. The reason being the presence of additional comparator and clock gating circuit which is beneficial only at sufficiently low switching activities or otherwise leads to both increased area and power overhead.

4.3. Clock Load Calculations. One has the following.

TGFF:
\[
\{C_g (TN1) + C_g (TP1) + C_g (TN5) + C_g (TP5)\} \\
+ \{C_g (TN3) + C_g (TP3) + C_g (TN7) + C_g (TP7)\}
\]

(15)

\{Transistors contributing towards clock load in the critical path\} + \{Transistors contributing towards clock load in the feedback structure\}

= 14.78 fF + 1.66 fF
= 16.44 fF.

mC²MOSff1:
\[
\{C_g (TN10) + C_g (TP10) + C_g (TN11) + C_g (TP11)\} \\
+ \{C_g (TN16) + C_g (TP16)\}
\]

(16)

\{Transistors contributing towards clock load in the critical path\} + \{Transistors contributing towards clock load in the feedback structure\}

= 22.18 fF + 0.84 fF
= 23.02 fF.

Apart from the clock load, the capacitance value at internal nodes of mC²MOSff1 is reduced as compared to TGFF by eliminating transistors TN6 and TP6 from the feedback structure.
Table 4: Comparison of flip-flop parameters at $C_{in} = 12.4$ fF and 16X capacitive loading.

| Design          | TGFF | $mC^2$MOSff1 | WPMS | PTLFF | GMSL | DTLA |
|-----------------|------|-------------|------|-------|------|------|
| Transistor count| 20   | 16          | 24   | 16    | 31   | 46   |
| No. of clocked transistors | 8    | 6           | 6    | 4     | 2    | 3    |
| Clock-to-output delay (ps) | 92   | 116         | 206  | 204   | 419  | 683  |
| Optimum setup time (ps) | 70   | 80          | 40   | 50    | 80   | –140 |
| Hold time (ps) | –19  | –21         | –33  | –32   | –23  | 25   |
| $T_{DQ,min}$ (ps) | 162  | 196         | 246  | 254   | 499  | 543  |
| Clock load (fF) | 16.44 | 23.02      | 9.05 | 8.22  | 7.76 | 7.31 |
| Power dissipation (uW)* | 550  | 550         | 550  | 550   | 550  | 550  |
| Leakage Power (uW) | 59.38 | 57.51      | 72.64 | 69.83 | 74.91 | 76.73 |

*Pseudorandom sequence with $\alpha = 0.5$ is used for power calculations.

4.4. Capacitance Calculations at Internal Nodes of TGFF

**Internal Capacitance at Nodes P and K**

Node P: $C_g(TN2) + C_g(TP2) + C_{gd}(TN5) + C_{db}(TN5) + C_{gd}(TP5) + C_{db}(TP5) = 9.28$ fF.

Node K: $C_g(TN6) + C_g(TP6) + C_g(TN9) + C_g(TP9) = 9.02$ fF.

**Internal Capacitance at Nodes M and N**

Node M: $C_{gd}(TN11) + C_{db}(TN11) + C_{gd}(TP1) + C_{db}(TP1) + C_{gd}(TN3) + C_{db}(TN3) + C_{gd}(TP3) + C_{db}(TP3) + C_g(TN4) + C_g(TP4) = 18.41$ fF.

Node N: $C_{gd}(TN5) + C_{db}(TN5) + C_{gd}(TP5) + C_{db}(TP5) + C_{gd}(TN7) + C_{db}(TN7) + C_{gd}(TP7) + C_{db}(TP7) + C_g(TN8) + C_g(TP8) = 14.80$ fF.

4.5. Capacitance Calculations at Internal Nodes of $mC^2$MOSff1

**Internal Capacitance at Nodes P’ and K’**

Node P’: $C_g(TN12) + C_g(TP12) = 9.76$ fF.

Node K’: $C_g(TN13) + C_g(TP13) + C_g(TN14) + C_g(TP14) + C_{gd}(TN16) + C_{db}(TP16) + C_{gd}(TN16) + C_{db}(TP16) = 10.06$ fF.

**Internal Capacitance at Node M’**

Node M’: $C_g(TN15) + C_g(TP15) = 12.35$ fF.

It can be easily concluded from calculations above that a total of 19.34 fF capacitance has been reduced from the internal nodes in the critical path of $mC^2$MOSff1 in comparison to TGFF. This leads to reduced internal power dissipation at these nodes as less capacitance has to be charged or discharged per clock cycle. However, reduction in the clock load of $mC^2$MOSff1 due to transistors eliminated from the feedback structure is nullified due to PMOS transistors TP10 and TP11 whose size is twice that of transistors TP1 and TP5 in case of TGFF and as a result the total power dissipation of both the flip-flops is nearly the same as it can be clearly observed from Figure 16. Following a similar procedure, the clock load of various flip-flops is obtained and listed in Table 4 along with number of clocked transistors and power consumption values. It is seen that TGFF and $mC^2$MOSff1 represent the most efficient designs in terms of reduced power consumption having power dissipation comparable to DTLA at $C_{in} = 12.4$ fF and $C_L = 19.92$ fF.

It can be observed that $mC^2$MOSff1 has the least transistor count along with PTLFF while GMSL and DTLA consist of maximum number of transistors. Since only sixteen transistors are used for circuit realization of $mC^2$MOSff1, power dissipation is comparable to TGFF. It is worth noting that GMSL and DTLA offer minimum clock load, as a result, these topologies exhibit least power dissipation at lower switching activities. The reason for extended clock-to-output delays of GMSL and DTLA is the insertion of clock gating circuitry while DTLA has a pulsed operation and hence shows negative set-up time requirements. Based on the power and delay measurements, power-delay product characteristics are derived for all the flip-flops as shown in Figure 16. The optimum power-delay product of gated structures GMSL and DTLA.
Table 5: PDAP comparison of TGFF and mC²MOSff1.

| Design   | Transistor count | Transistor widths (um) | Delay (ps) | Power (uW) | Layout area (um²) | PDP (fJ) | PDAP (fJ·um²) |
|----------|------------------|------------------------|------------|------------|------------------|----------|---------------|
| TGFF     | 20               | 52.52                  | 162        | 632        | 175              | 102.3    | 17902         |
| mC²MOSff1| 16               | 58.95                  | 196        | 640        | 125              | 125.4    | 15675         |

Table 6: Flip-flop simulation parameters at 65 nm CMOS technology.

| Process corner | Temperature (°C) | VDD | Lmin | Wmin | Cmin | Frequency | Signal slope |
|----------------|------------------|-----|------|------|------|-----------|--------------|
| TT             | 70               | 1   |      |      |      |           |              |
| FF             | 0                | 1.1 | 60 nm| 120 nm| 507 aF| 2 GHz     | 20 ps        |
| SS             | 125              | 0.9 |      |      |      |           |              |
| FS             | 70               | 1   |      |      |      |           |              |
| SF             | 70               | 1   |      |      |      |           |              |

Figure 17: Layout implementation of TGFF.

Figure 18: Layout implementation of mC²MOSff1.

Figure 19: Comparison chart of power dissipation at different switching frequencies.

The power dissipation results as illustrated in Figure 19 are obtained using $C_{in} = 12.4$ fF which ensures that all the transistors in the critical path have similar widths. At zero switching activity, clock-gated topologies are the most power...
efficient. GMSL and DTLA show GMSL 32.5% and 46.3% reduction in power in case of logic high at the input, whereas for logic low, the power consumption is reduced by 19.2% and 35.4%, respectively. Again, it can be clearly observed that there is only a slight difference in the power dissipation of TGFF and mC MOSfl1 at different switching activities.

The correct functionality of the proposed flip-flop mC MOSfl1 is validated by designing an 8-bit ripple counter at 16X capacitive load and the average power measurements were carried out over 256 clock cycles. It was noticed that the power consumption of the mC MOSfl1 based counter is comparable to the TGFF at varying frequencies. Again, LE theory has been adopted for sizing individual flip-flops in each counter for optimum performance which is expressed in detail in the Appendix.

The flip-flops were also designed and simulated to layout level with inclusion of parasitics at 130 nm, 90 nm, and 65 nm CMOS processes to address scalability issues at more advanced process nodes. The simulation test bench and optimization methodology are similar as mentioned in Section 3. PVT variations are emphasized to evaluate the performance of flip-flops at all process corners, namely, FF, SS, FS, and SF with voltages scaled from 0.9 to 1.1 V while the temperatures varied from 0 to 125 degrees as shown in Table 6. The simulation and technology parameters are also listed in Table 6 where $C_G$ represents the capacitance per unit gate oxide and was evaluated to be 1.3 fF/um by fitting simulation data. In addition, the capacitances per unit length of poly, metal 1 and metal 2 interconnects are also mentioned.

For illustration purposes, the delay and power variations with the flip-flop input capacitance with respect to different process corners at 65 nm CMOS technology for mC MOSfl1 are demonstrated in Figures 20 and 21, respectively, at 16X capacitive loading. Both mC MOSfl1 and mC MOSfl2 showed correct circuitual behaviour at the aforementioned process nodes which indicates that no internal noise violations exist especially due to the fact that logic levels are...
5. Conclusion

In this paper, an alternative architecture for designing C\textsuperscript{2}MOS based flip-flops is presented with a modified feedback strategy while preserving the fully static operation. Using the new feedback approach, a modified topology mC\textsuperscript{2}MOSff1 is proposed with decreased parasitic capacitances at internal nodes in comparison to the TGFF which is the finest design in terms of PDP. However, postlayout simulations and analyses indicate that the modified configuration mC\textsuperscript{2}MOSff1 presents the best alternative in terms of PDAP among all the conventional designs. Therefore, for high performance applications, TGFF still remains the best choice but it can be replaced by mC\textsuperscript{2}MOSff1 for high density applications. Comparisons were carried out with state-of-the-art flip-flops in the master-slave class. The simulation results are well supported with mathematical analysis based on logical effort theory within acceptable error (typically less than 15%).

Appendices

A. Delay Calibration Using LE Theory

For modelling delays using LE theory initially, all the delays are expressed in terms of a basic delay unit \( \tau \) which is process dependent such that the absolute delay is represented as the product of a unit less delay of the gate as shown in (2), and the delay unit \( \tau \). Accordingly,

\[
D_{\text{abs}} = D \tau. \tag{A.1}
\]

While \( D \) represents the delay for a multistage path, \( d \) corresponds to the delay of a single stage logic gate. Parameter \( \tau \) needs to be estimated in order to obtain absolute delays and accordingly a delay versus fanout curve is determined for an inverter as shown in Figure 22 by fitting simulation data. The curve is approximated as a straight line and the slope of the line represents \( \tau \) since \( d = (gh + p) \tau \) and logical effort of an inverter is 1. In our case, \( \tau \) is estimated as 13 ps.

B. Implementation of 8-Bit Ripple Counter

An 8-bit asynchronous counter was implemented by converting the D flip-flop configuration to a T flip-flop configuration using an EXOR gate as illustrated in Figure 23.

The T flip-flop designed using TGFF is shown in Figure 24. It is considered to be a five stage design and optimized for highest speed using LE theory. The EXOR gate was realized using transmission gates as revealed in Stage 1 of Figure 24. A similar procedure was followed for designing mC\textsuperscript{2}MOSff1 based T flip-flop.

For designing the modulo 256 counter, the output \( Q \) of each stage is connected to the clock terminal of the next stage through two intermediate inverters (acting as a buffer) sized (\( W_p = 11.52 \mu \text{m}, W_n = 5.76 \mu \text{m} \)) such that the input capacitance of the first inverter acts as the load capacitance for the flip-flop.
configuration of the previous stage as depicted in Figure 25. As a result, the load at the output terminal of each flip-flop is uniformly fixed at 19.92 fF.

Conflict of Interests

The authors declare that there is no conflict of interests regarding the publication of this paper.

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