Low-frequency ionospheric sounding with Narrow Bipolar Event lightning radio emissions: energy-reflectivity spectrum

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Abstract. We analyze data on radio-reflection from the D-region of the lower ionosphere, retrieving the energy-reflection coefficient in the frequency range \(\sim 5–95\) kHz. The data are the same as developed for a recent study of ionospheric-reflection height, and are based on recordings of powerful (multi-Gigawatt) radio emissions from a type of narrow (\(\sim 10\) \(\mu\)s) lightning discharge known as “Narrow Bipolar Events”. The sequential appearance of first the groundwave signal, and then the ionospheric single-hop reflection signal, permits us to construct the energy-reflection ratio. We infer the energy reflection’s statistical variation with solar zenith angle, angle-of-incidence, frequency, and propagation azimuth. There is also a marginally-significant response of the energy reflectivity to solar X-ray flux density. Finally, we review the relationship of our results to previous published reports.

Keywords. Ionosphere (Ionospheric irregularities; Plasma temperature and density; Instruments and techniques)

1 Introduction and background

The reflection of long radio waves from the lower ionosphere (D-region) has been studied since the 1940s, and from that perspective one might infer that anything worth doing has already been done. On the other hand, more recent work on lower-ionosphere disturbances associated with lightning (Cho and Rycroft, 1998; Inan et al., 1996a, b; Lev-Tov et al., 1995) and with lightning-induced energetic-particle precipitation (Bortnik et al., 2006a, b; Rodger et al., 2005) motivate further improvements in radio reflectometry from the D-region. Present understanding of morphologies, time histories, and intensities of the electron-density disturbances associated with lightning and precipitation is impeded by insufficiently fast and quantitative profiling of the disturbed D-region electron density.

Systematic radio-reflection observations of the D-region were pioneered (Bracewell et al., 1951) in the United Kingdom after World War II. During the 1960s there appeared both excellent summaries of two decades of observations, and sophisticated, full-wave numerical models of the radio propagation (e.g. Deeks, 1966; Johler and Harper, 1962; Piggott et al., 1965; Pitteway, 1965; Thomas and Harrison, 1970; Wait and Spies, 1964). Whereas medium-frequency (MF, 300 kHz–3 MHz) and, especially, high-frequency (HF, 3–30 MHz) ionosondes already existed and provided profiles of the E-region and F-region underside, there was no equivalent pulse-reflectometry tool for the lower ionosphere at very-low-frequency (VLF, 3–30 kHz) and low-frequency (LF, 30–300 kHz). Three factors prevent a D-region ionosonde: First, the low plasma frequency at D-layer heights necessitates use of LF or VLF techniques. For these frequencies, suitable radio-sounder antenna dimensions (on the order of the half-wavelength, or \(\lambda/2=5\) km for \(f=30\) kHz) cannot be realized in practice, so that one must make do with inefficient, low-gain antennas. Second, the D-layer’s high electron-neutral collision rate causes high signal loss in D-layer radio sounding, further worsening the signal-to-noise problem already implicit in the low-gain antennas. Together, in practice, these two factors prevented the ionosonde approach from being extended downward in altitude below 95 km. Third, partial reflections are more important for the VLF (and to some extent LF) spectral range than in the higher frequencies used for conventional ionosondes.

Thus the early VLF/LF radio-sounding technique was forcibly based on narrowband bistatic carrier-phase and amplitude measurements. The narrowband radio-link approach is well typefied by the 16-kHz observations (Bracewell et al., 1951) on the Rugby-to-Cambridge path, which were later summarized and compared to results of a full-wave model (Piggott et al., 1965). The narrowband technique is unable to discriminate partial reflections from “full” reflections.

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Fig. 1. Schematic of the ionospheric-reflection model. A “transmitter” $T$ (in this case an intracloud lightning discharge at height $H_i$) radiates both a ground wave (not shown) and two ionospheric echoes. The first of these echoes departs $T$ along an upward take-off angle directly to the ionosphere at height $H_i$. The second departs $T$ along a downward take-off angle to the ground, where it is reflected toward the ionosphere. A ground-based receiver $R$ records all three signals, including the two echoes shown here, plus the ground wave (not shown).

In a more recent and highly successful development, narrowband carrier-phase and amplitude measurements have been applied to long-range (up to $\sim 10^4$ km) propagation of signals from powerful VLF beacons (McRae and Thomson, 2000; Thomson and Clilverd, 2001; Thomson and Rodger, 2005; Thomson et al., 2004, 2007). Thomson’s approach has been to compare careful recordings of phase and amplitude at long range to predictions of a numerical model of VLF propagation in the Earth-ionosphere waveguide developed under the auspices of the United States Navy (Pappert and Ferguson, 1986). In Thomson’s approach, data and model results are compared to fit the two unknown parameters in the standard exponential model (Wait and Spies, 1964) for electron density: “$\beta$” is the logarithmic gradient (in units of km$^{-1}$), and $H'$ is a reference height (in units of km.) Thomson’s approach has provided accurate and stable determinations of $\beta$ and $H'$ over long distances with pure-daytime conditions over the full path (McRae and Thomson, 2000; Thomson, 1993). The approach has more recently been successfully applied to determinations of the transient D-region perturbations of $\beta$ and $H'$ in the sunlit hemisphere from solar flares (Thomson and Clilverd, 2001; Thomson and Rodger, 2005; Thomson et al., 2004).

An alternative approach to studying the D-region radio reflector, using wideband VLF emissions from lightning as the transmitter, rather than a narrowband artificial beacon, was developed in the late 1990s (Cummer et al., 1998). Cummer’s approach exploited the immense peak radiated VLF power (multi-GW) of lightning strokes, which elegantly bypassed the obstacles to an engineered D-region pulsed sounder. This wideband VLF approach was later applied to the study of ionospheric disturbances associated with lightning itself (Cheng and Cummer, 2005) and with particle precipitation (Cheng et al., 2006). The heart of the technique developed by Cummer is to compare the recorded against the modeled VLF spectral shape, using a form of the same numerical waveguide-propagation model as used by Thomson (Pappert and Ferguson, 1986). The sharpness parameter $\beta$ tends to control the degree of spectral interference, while the height parameter $H'$ tends to control the frequency spacing of the modulation (Cummer et al., 1998).

In addition to Cummer’s approach, some additional insight into VLF propagation in the Earth-ionosphere waveguide was provided by interpretation of long-range (>1000 km) sferic recordings (Grandt, 1992) in terms of a model based on dominance by the transverse-magnetic (TM) first mode. The model predicts the spectral dispersion via a group time-delay dispersion. (A “sferic” is the VLF/LF signal radiated from a lightning discharge.)

Our present approach is basically an evolution of Cummer’s, in that we rely on the powerful sferic emissions rather than an engineered transmitter. We use short (<800 km) paths, and lightning of a special type having a sufficiently narrow pulse to permit temporal separation, in the recorded signal, between the signal components from various propagation paths. Thus our model paradigm will not be based on complicated multi-mode waveguide propagation, but rather, on the single-hop ionospheric reflection process, in isolation. We hope that, eventually, this simplification will help to illuminate the reflection process via comparison with full-wave models (e.g. an adaptation of the approach used by Pitteway, 1965) of the single reflection.

The remainder of this article will describe our technical approach (Sect. 2), present our statistical results (Sects. 3–5), and discuss these results in the context of prior work (Sect. 6).

2 Technical approach

2.1 Basic model

In this paper we build upon recently published results (Jacobson et al., 2007), (“J7”), on improved retrieval of ionospheric reflection height from the delayed echoes seen in recordings of VLF/LF lightning sferics of Narrow Bipolar Event (NBE) discharges (Le Vine, 1980; Smith et al., 2004; Smith et al., 1999; Willett et al., 1989). Using exactly the same reflection model as in J7, we now retrieve the magnitude (though not the phase) of the VLF/LF reflection spectrum and that magnitude’s variation with frequency and with three controllable factors (angle-of-incidence, solar zenith angle, and propagation azimuth).

The reflection model is shown in Fig. 1. The NBE discharge provides a transmitter (“$T$”), assumed to be a short dipole radiator aligned with the local vertical and elevated at height $H_i$ in a thundercloud. The radiation from $T$ is
assumed to be that of a simple short dipole, with equal radiation below and above the dipole’s own equatorial plane. Radiation below the plane is assumed to reflect perfectly from the ground and then to propagate to the ionosphere (path 2) (at height \(H_i\)), while radiation above the dipole’s equatorial plane can propagate directly to the ionosphere (path 1). The receiver (“\(R\)” ) is close to the ground and receives signals from both paths 1 and 2, as well as the direct, line-of-sight signal (“ground wave”). The angles of incidence at transmitter, ground, ionosphere, and receiver are shown by the symbol \(\theta\) with various subscripts.

The ground wave arrives at the receiver first, and due to the narrow (<20-\(\mu\)s) duration of the pulse, does not overlap in time with the delayed echoes from paths 1 and 2. This is crucial— we are able to measure the ground wave, and then use that as “ground truth” for converting the recorded echoes into an energy-reflection spectrum. This differs from previous uses of broadband lightning emissions for ionospheric-reflection studies (Cheng and Cummer, 2005; Cheng et al., 2006; Cummer, 1997; Cummer et al., 1998), in which the ground wave and ionospheric echoes were overlapped in time. If one does not separately observe the ground-truth waveform, it is not possible to retrieve a reflection coefficient from a single sferic.

We wish to retrieve from our data the energy-reflection coefficient for the ionospheric underside, as a function of frequency \(f\), angle-of-incidence \(\theta\), solar zenith angle \(Z\), and \(T\)-to-\(R\) propagation azimuth (henceforth, “azimuth”). Toward this end, we make the following approximations:

1. We assume that the ground serves as a perfect conductor, and that the ground reflection dissipates no energy. We do not invoke this assumption for the ground wave, only for the second reflection in the pair of reflections. The dominant spectral attenuation in the reflection problem is due to the D-region, so this approximation is serviceable in our case.

2. We assume that the emission from \(T\) is that of a vertical dipole, with radiated electric field in the plane of incidence, normal to the radial vector, and varying in magnitude as \(\sin(\theta_T)\). Any tilts of the NBE dipole away from the local vertical would cause random errors in our final reflectivity retrieval.

3. We treat the ionospheric reflection as occurring from an “ionospheric height”, whose retrieval is described in \(J7\) and references therein. This height is fitted separately for each receiver’s signal in each NBE lightning discharge, in a manner that phenomenologically allows for variation of radio penetration height (into the ionosphere) with range (and hence \(\theta\), with \(Z\), and with azimuth. (Our retrieved height corresponds to the “virtual height” in Eq. (3) of Piggott et al., 1965) For the purpose of stratifying the energy-reflection coefficient versus angle of incidence, we use an average angle of incidence, averaged over the two echo paths:

\[\theta_I = (\theta_{11} + \theta_{12})/2\]

4. Since the receiver is a vertical dipole near the ground, capable of sensing only a vertical electric field, we ignore that portion of the ionospherically reflected field that is normal to the plane of incidence, because that portion will not contribute to the vertical electric field at the ground. Thus the reflection coefficient we obtain is for “p-polarization”, that is, with both the incident and reflected electric fields lying in the plane of incidence.

5. We sum the energy in both ionospheric echoes (paths 1 and 2) and take its ratio to the energy in the ground wave, to get the energy-reflection coefficient. This requires that we correct for modeled losses in the ground wave caused by resistive ground currents. The ground wave’s dissipative attenuation is estimated by assuming a ground conductivity \(\sigma_g=5\times10^{-3}\) Siemens m\(^{-1}\) over land and \(\sigma_g=\infty\) infinity over salt water, dividing the \(T\)-to-\(R\) ground wave path into sea and land portions, and calculating the dissipative attenuation over only the land portion of that path. This is done separately for each path according to its locus on a digital map. We use a simplified formula for attenuation (see Eq. (3.13) in vol. 2, chapter 3, “Longwave Sferics Propagation within the Atmospheric Waveguide”, in Volland, 1995) which suffices for estimating loss of signal power. The choice of land conductivity (\(\sigma_g=5\times10^{-3}\) Siemens m\(^{-1}\)) in Volland’s formula does not critically affect our results, due to the short ranges and low frequencies used here.

6. In addition to dissipative attenuation, the energy flux densities in all three signal components (ground wave, plus echoes 1 and 2) suffer dilution from spherical spreading, with electric field varying as \(1/s\), and energy flux density varying as \(1/s^2\), where \(s\) is the path distance. We correct the ground wave energy using \(s=\) the great-circle pathlength, and the sum of the echoes’ energy using \(s=\) the mean of the lengths of path 1 and path 2.

7. A short dipole has an energy-flux-density lobe varying as \(\sin^2(\theta)\), where \(\theta\) is the angle from the dipole axis (the vertical, in this case) and the radial vector to the field point. Thus the received groundwave is (approximately) at the maximum of the lobes of both the T and R dipoles (Fig. 1) The energy in the first and second recorded echoes, on the other hand, has been disfavored by a factor of \(\sin^2(\theta_{T1,2})\) at emission and by a factor of \(\sin^2(\theta_{R1,2})\) at reception. To correct the estimated energy in the sum of the received two echoes, we multiply the
received summed echo energy by a lobe-compensating factor averaged over the two paths:

$$L = \frac{2}{\sin^2(\theta_{T1}) \sin^2(\theta_{R1}) + \sin^2(\theta_{T2}) \sin^2(\theta_{R2})}$$  

(2)

We reiterate that in what follows, we will use “reflectivity” to mean “energy” reflectivity of the p-polarization. This study can provide no information about either s-polarization reflection, or polarization-mixing by the reflection process.

2.2 Data campaign

Data are from the Florida subarray of the Los Alamos Sferic Array (Jacobson and Heavner, 2005; Jacobson et al., 2007a, b; Smith et al., 2004, 2002; Susczynsky and Heavner, 2003) during the period 2000–2002. Figure 2 shows the area covered by this study. The Florida array in 2000–2002 was effectively centered on 28 deg N, −81.5 deg E. The circle in Fig. 2 is centered on that point and has radius 400 km. In this study we use data from lightning whose locations are within that circle and from any LASA station whose distance from the lightning is >200 km and <800 km. The data and their selection criteria are fully described in J7. As in the J7 study, we use a total of >65,000 recorded NBEs. The 3-year campaign started at the maximum of Solar Cycle 23 (April 2000). Cycle 23’s maximum was followed by two years of continued high solar flux; thus, the radio-reflection results here are thus obtained during solar-maximum-like conditions.

In Florida the magnetic declination is small (−4 deg in January 2002), and thus the geographical and geomagnetic meridians are effectively identical within the precision of this study. The local magnetic dip angle is about 58 deg.

2.3 Data example

Figure 3 shows time-domain data from a typical NBE recording, at the Gainesville station “gv”. The solar zenith angle (at the ground) was −61 degrees, the minus sign meaning that the time was before solar-local noon, i.e. AM. Figure 3a shows 1 millisec (=1000 samples) of the record, with the trigger on the ground wave and the delayed echoes about 70–100 μs later. Figure 3b shows the 128 samples (with an offset zero) centered on the received ground wave, and Fig. 3c shows the 128 samples centered on the two ionospheric echoes. The two windows (b and c) are time-offset to center the pulse energy optimally. This can differ from event to event. There is a small but visible background of noise. We estimate the noise using the first 120 samples in the record, that is, the pre-trigger samples preceding the ground pulse’s rise (see Fig. 3a).

Taking the ratio of the echo to ground-wave spectra will give the energy-reflection coefficient as a function of frequency. Figure 4 shows frequency-resolved results for this data example. Prior to performing a Fourier transform, we
impose a Hamming window centered on the time-domain data being analyzed. The frequency resolution is \( \sim 7.8 \) kHz. The solid curve in Fig. 3a is the logarithm (base 10) of the power spectrum of the echoes minus the logarithm (base 10) of power spectrum of the ground wave. We have corrected the spectra in this individual plot for \( 1/s^2 \), but not for either ground-wave dissipation or dipole-lobe effects (see Eq. 2). The solid curve in Fig. 4b is the logarithm of the signal-to-noise ratio (SNR), based on the recorded noise prior to the ground wave’s rise.

Note that both solid curves in Fig. 4 are amplitude-modulated, with a frequency periodicity of about 50 kHz. This is the inverse of the relative delay between the two echoes (Fig. 3b), \( \tau \sim 20 \mu s \). The modulation of the power spectrum is an artifact of the second echo’s being an approximate replica of the first echo, but with time delay \( \tau \). If the second pulse were a perfect replica (which it usually is not), then we would expect the sum of the two echo pulses to have a power spectrum proportional to the power spectrum of a single pulse, with a proportionality factor

\[
M(\omega) = 2[1 + \cos(\omega \tau)]
\]

where \( \omega = 2\pi f \). The dashed curve in Fig. 4b shows this M-factor. In order to smooth-out this modulation, we fit the energy-reflection ratio to a quadratic, shown as the dashed curve in Fig. 4a. All statistical results on energy-reflection spectra in the rest of this article will use the individual quadratic fit to the energy-reflection spectrum of each NBE recording. The interference (Eq. 3) modulation is of no interest to our study of the ionospheric reflection, and is only an artifact of our receiving two similar pulses in the spectral-analysis window, the second pulse delayed relative to the first. Examination of hundreds of case examples, analogous to that in Figs. 3 and 4, indicates that there is no “physical” spectral dependence of \( \log_{10}(\text{reflectivity}) \) more complicated than that which can be captured by a quadratic. This approximation in effect reduces the twelve independent frequencies to just three frequency parameters (of a quadratic fit). This reduction in degrees-of-freedom is a disadvantage of our technique relative to the technique of Cummer et al. The latter retains more information about spectral response.

3 Frequency-averaged statistical results

3.1 Statistical data

We perform the spectral analysis (see Fig. 4) on each of the \( N > 65,000 \) NBE recordings. For each recording’s energy-reflection spectrum, we fit a quadratic to minimize the spurious modulation (see Eq. 3). The fit is applied to the frequency range \( 0 < f < 100 \) kHz.

We obtain in this manner an \( N \times K \) matrix of spectral energy-reflection coefficients, where \( K=12 \) and the frequency grid is \([1, 2, \ldots, 12] \times 7.8 \) kHz. (The sampling rate is 1 megasample/s, so we could in principle extend the frequencies up to the Nyquist frequency = 500 kHz, but the signal-to-noise ratio is too low, above 100 kHz, for those highest frequencies to be useful, at least during daytime observations.) In addition we store the spectrum of signal-to-noise ratio (SNR), so there are two \( N \times K \) data matrices serving as inputs to the statistical analyses to follow.

We use a digital map program to get the land fraction of each of the \( N > 65,000 \) ground-wave propagation paths. The energy-reflection matrix is then fully corrected for three effects:

1. The lossless energy-flux-density scaling as \( 1/s^2 \), where \( s \) is the propagation pathlength;

2. the dissipative ground-wave attenuation as estimated by Volland’s approximation, applied to only the land portion of each propagation path; and

3. the biases against the echo-energy estimates caused by both transmitter and receiver dipole lobes (see Eq. 2).

3.2 Frequency bands

In order to survey the behavior of the energy-reflection spectrum with the most robust statistics, we first divide the 0–100 kHz frequency range into two frequency bands, low-band (5–50 kHz) and high-band (50–100 kHz). Each band includes six discrete multiples of 7.8 kHz: The low band

![Fig. 4. Frequency-domain analysis of the data of Fig. 3. (a) \( \log_{10}(\text{echo signal-to-noise ratio}) \), with ideal spectral-interference model (dashed curve).](image-url)
During daytime, the low- and high-band reflectivities are higher than during nighttime. The sunrise transition is essentially simultaneous for both the low and high bands. The transition consists of a sharp reduction in the reflectivity as the sun rises through $Z \sim 100$ deg, illuminating the D-layer (though not yet the ground). The low-band reflectivity reduction sharply overshoots the mean low-band daytime value; the high band shows no such dawn overshoot.

3.3 Band-averaged results

Figure 5 shows $\log_{10}(\text{energy reflectivity})$ versus solar zenith angle. The ionospheric angle of incidence $\theta_i$, averaged over both echoes, is coded in color from 50 deg (blue) to 74 deg (red).

Within each band, we average the fully-corrected quadratic fit to the reflection spectrum both over $n=1, 2, \ldots, N$ recordings and over the six frequencies within the band. The average in each band excludes any recording/frequency entry for which the SNR<10. In this manner we minimize the effect of noise being mistaken as echo signal, which would bias the energy reflection artificially high.

During daytime (say, $|Z|<80$ deg) there is a clear progression of reflectivity upward with increasing $\theta_i$, while this transition is less dramatic during night conditions (say, $|Z|>110$ deg). The dependence on $Z$ is more visibly dramatic, with grossly higher reflectivity at night than during the day, and with sharp transitions in reflectivity at both dawn and dusk. Clearly $Z$ and $\theta_i$ jointly control much of the variability in the energy reflectivity.

We wish to find regressions for the $Z$ and $\theta_i$ dependencies of the energy reflectivity. We start by treating only the highest angles of incidence (i.e. most grazing incidence): $71<\theta_i<74$ deg (the red points in Fig. 5). For this grazing-incidence data, we divide the signed-zenith range from $-140$ to $140$ deg into 56 bins, each 5-deg-wide. In zenith bins having $>100$ data points, we take the median of the energy-reflection coefficient. This median is shown for low band (solid curve) and high band (dashed curve.) The squares are centered on the bin centers. We note:

1. During daytime, the low- and high-band reflectivities differ by roughly an order of magnitude.
2. During nighttime, the low- and high-band reflectivities differ less, and are almost the same during pre-dawn.
3. The sunrise transition is essentially simultaneous for both the low and high bands. The transition consists of a sharp reduction in the reflectivity as the sun rises through $Z \sim 100$ deg, illuminating the D-layer (though not yet the ground). The low-band reflectivity reduction sharply overshoots the mean low-band daytime value; the high band shows no such dawn overshoot.
4. The sunset transition is not simultaneous between the bands. It begins as the sun sets past \( Z \sim 70–75 \) deg for the high band but as the sun sets past \( Z \sim 85–90 \) deg for the low band.

5. The zenith dependence of the reflectivity is far more cusp-like than is the relatively smooth zenith dependence of the ionospheric-reflection height \( H_i \) seen in J7 (see in particular Fig. 5 in J7).

Further removal of systematic variations is now implemented:

- We subtract the grazing-incidence logarithmic medians (Fig. 6) from the logarithmic reflectivities of all the data in the range \(-140 < Z < +140 \) deg. The medians are subtracted bin-by-bin in zenith. Due to their rather sharp and asymmetric features, the bin medians of Fig. 6 are not fitted to a function of zenith, but are used directly, in tabular form. This step leads to “zenith-regressed” logarithmic reflectivities of all the data in the range \(-140 < Z < +140 \) deg.

- Next, we regress the trends versus \( \cos(\theta_i) \), for both daytime and nighttime, and for both low-band and high-band.

Having detrended the energy reflectivity with respect to both zenith and angle-of-incidence, we now isolate the effect of \( T \)-to-\( R \) (see Fig. 1) propagation azimuth. Pure-nighttime (\( |Z| > 110 \) deg) data, detrended with respect to both zenith and angle-of-incidence, are shown in Fig. 7, for (a) low- and (b) high-band data. Each band’s azimuth variation is fitted to a two-harmonic function \( F(a) \), shown by a grey curve:

\[
F(a) = A_1 \cos(2\pi a + \phi_1) + A_2 \cos(4\pi a + \phi_2)
\]

where \( a \) is the azimuth in radians, \( A_{1,2} \) are amplitudes, and \( \phi_{1,2} \) are azimuth offsets. Figure 7a shows that the low-band residual variance (after detrending with respect to both zenith and angle-of-incidence) is about 50\% controlled by azimuth. The peak reflectivity occurs near +90 deg, which is to say, for propagation from West toward East. The minimum reflectivity is for propagation from East toward West. By contrast, the nighttime high-band data’s variations (Fig. 7b) are less controlled by azimuth than are the low-band’s.

Figure 8 is similar to Fig. 7 but for pure-daytime conditions (\( |Z| < 70 \) deg). Again, the low-band variability is about 50\% controlled by azimuth, while azimuth controls less of the high-band variability. We are unaware of previous reports of daytime VLF/LF propagation sensitivity to azimuth.

4 Frequency-resolved statistical results

At the risk of less-robust statistics, we can examine the results using frequency as an independent sorting variable. Although we will show all twelve Fourier frequencies in the range \( 0 < f < 100 \) kHz, there are in fact only three independent frequency parameters, due to the initial quadratic fit applied to each event’s reflection spectrum (see Fig. 4 and Sect. 2.3). In order to avoid the unstable time periods (see Fig. 6) around each solar terminator, we will restrict the frequency-sorted results analysis to either pure-nighttime (\( |Z| > 110 \) deg) or pure-daytime (\( |Z| < 70 \) deg) data. Interior to each of these \( |Z| \) ranges, we will ignore variability due to \( |Z| \). Figure 6 suggests that this is a viable approximation.

Figure 9 shows average \( \log_{10} \) (reflectivity) versus frequency for four different ranges of ionospheric angle of incidence, from (a) steepest-incidence to (d) most grazing incidence. Dashed curves show the pure-nighttime data, solid curves the pure-daytime data. The discrete symbols are the Fourier frequencies. Each point is the average over all events in the \( Z \) and \( \theta_i \) range box. These data have not been detrended against systematic variations with either \( Z \) or azimuth. We note:

1. Pure-nighttime reflectivity is practically flat versus frequency, whereas pure-daytime reflectivity decreases (by up to two orders of magnitude, at steepest incidence in Fig. 9a) across the spectrum.
Daytime reflectivity roll-off with frequency is strongest for θi > 71 deg and sunset: The terminator occurs simultaneously on low-band and high-band reflectivity at sunrise, but not at sunset, where the low-band recovery to nighttime levels is delayed with respect to the high-band. We are unaware of previous observations of this effect. Early bistatic VLF-propagation measurements were based on a recording of the radio signal from single-frequency. The more recent broadband-VLF approach of Cummer has been used exclusively during pure-nighttime conditions and has not been applied to terminator behavior. Recently a colleague (J. Zinn, private communication) has pointed out that our observed dawn transient at low band is probably due to prompt photo-detachment of electrons from nocturnal negative ions. The first rays of dawn cause a fast supply of free electrons in this manner. This effect has been predicted by a model of D-region photochemistry, but the effect eluded confirmation by the Arecibo incoherent-scatter radar due to that methods lack of sensitivity at D-region heights (Ganguly and Zinn, 1998).

Our empirical retrieval of the energy-reflectivity’s azimuth sensitivity, during both nighttime (Fig. 7) and daytime (Fig. 8), shows a peak in the reflectivity for “west-to-east” and a minimum for “east-to-west” propagation. The low-band data reflectivity variation versus azimuth is roughly sinusoidal. The high-band variation is noisier due to the lower ionospheric-echo SNR at higher frequencies and will not be discussed further.

The prior published information about observational evidence for azimuth effects on VLF reflectivity appears to condense down to a handful of reports. Two of these reports are from the United States Naval Electronics Laboratory Center or NELC (subsequently named Naval Ocean Systems Center or NOSC) and deal with the same dataset, gathered in 1969. The earlier of these reports (Bickel et al., 1970) compared signal-propagation paths from Hawaii roughly east-to-west to Wake Island, and from Hawaii roughly west-to-east to southern California. The signal was the 23.4-kHz transmission from the NPM beacon in Hawaii. Airborne amplitude recordings, conducted continuously along flights over portions of the propagation baselines, observed that there was more attenuation on the east-to-west than on the west-to-east path (see Figs. 7–8 and discussion thereof, in Bickel et al., 1970). On the other hand, the amplitudes on the east-to-west path were highly variable from day to day. The second of the NELC/NOSC reports (Pappert and Hitney, 1988) addresses this observed anisotropy and irreproducibility (in the east-to-west measurements) with detailed model calculations, but uses the same data as that of Bickel et al.

The other prior independent report of reflection anisotropy (Grandt, 1992) is based on VLF sferic recordings. Rather than in amplitude, the reported anisotropy is in the signal’s group delay dispersion (“gdd”). The gdd concept has been clearly reviewed elsewhere (Figure Eq. 3.49, and discussion thereof, in vol. 2, chapter 3, “Longwave Sferics Propagation within the Atmospheric Waveguide”, in Volland, 1995). At any rate, the evidence of the sferic recordings (see Fig. 2 in Grandt, 1992) appears to suggest that there may be

![Fig. 8. Propagation-azimuth dependence of zenith- and range-regressed data for pure-daytime values of solar zenith angle. Sinusoidal (fundamental + second harmonic) fit is shown as smooth curve.](image-url)
Fig. 9. Average $\log_{10}$ (reflectivity) versus frequency for four different ranges of ionospheric angle of incidence, from (a) steepest-incidence to (d) most grazing incidence. Dashed curves show the pure-nighttime data, solid curves the pure-daytime data. The discrete symbols are the Fourier frequencies. Each point is the average over all events in the $Z$ and $\theta_i$ range box. These data have not been detrended against systematic variations with either $Z$ or azimuth. The smooth variation versus frequency is primarily due to our reduction of the frequency information to just a quadratic fit (see Fig. 4 above) in analyzing each event’s reflection. This smooth variation may mask details of the frequency response that cannot be captured by a quadratic fit.

(a) $46 < \theta_i < 58$ deg (b) $58 < \theta_i < 62$ deg 
(c) $62 < \theta_i < 67$ deg (d) $67 < \theta_i < 80$ deg

In summary, then, the only journal-published, hard observations on amplitude anisotropy appear to be that of NELC/NOSC’s flights along two discrete azimuths. We infer, then, that the results in Figs. 7 (for nighttime) and 8 (for daytime) are quite new, at least in their making obvious the azimuthal variation of the single-hop ionospheric reflectivity. Moreover, the results in Fig. 8 are the first report of daytime VLF azimuth sensitivity, to the best that we can ascertain. We note, however, that NELC/NOSC has produced a wealth of reports on results of airplane-borne beacon recordings, which although not published in journals, were available as microfiches (as recently as 1995) from the United States National Technical Information Service. These reports are said to contain scattered information on the subject of magnetic anisotropy.

The second NELC/NOSC article (Pappert and Hitney, 1988) hypothesizes a mechanism for the irreproducibility of the east-to-west propagation amplitude relative to the west-to-east propagation: the east-to-west-propagating mode shape extends higher in altitude than does the west-to-east-propagating mode shape. This increases the susceptibility of east-to-west propagation to sporadic-E irregularities in the heights above 90 km. Sporadic-E is notoriously irregular in time and position, so it might introduce irreproducibility into VLF waveguide propagation modes that extend high enough to sample the sporadic-E. Examining our nighttime data (Fig. 7) however, we see no obvious tendency for greater reflectivity scatter at east-to-west azimuth compared to west-to-east azimuth.

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