Existence of periodic solutions for enzyme-catalysed reactions with periodic substrate input

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Abstract

Considering a basic enzyme-catalysed reaction, in which the rate of input of the substrate varies periodically in time, we give a necessary and sufficient condition for the existence of a periodic solution of the reaction equations. The proof employs the Leray-Schauder degree, applied to an appropriately constructed homotopy.

1 Introduction

The basic scheme for a reaction catalysed by an enzyme is

\[
I(t) \xrightarrow{k_1} S + E \xrightleftharpoons{k_2} C \xrightarrow{k_{-1}} P + E
\]

in which the substrate \(S\) and the enzyme \(E\) form a complex \(C\) through a reversible reaction, and the complex \(C\) can dissociate into the enzyme and the product \(P\). \(I(t)\) is the rate of input of the substrate into the system, satisfying

\[
I(t) \geq 0, \quad t \in \mathbb{R}.
\]

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Partially supported by the Edmund Landau Center for Research in Mathematical Analysis and Related Areas, sponsored by the Minerva Foundation (Germany).
The dynamics of this system are described by the rate equations for the concentrations of the species:

\[ E'(t) = -k_1 E(t)S(t) + (k_{-1} + k_2)C(t) \]  
(2)

\[ S'(t) = I(t) - k_1 E(t)S(t) + k_{-1}C(t) \]  
(3)

\[ C'(t) = k_1 E(t)S(t) - (k_{-1} + k_2)C(t) \]  
(4)

\[ P'(t) = k_2 C(t) \]  
(5)

Stoleriu, Davidson and Liu [2] recently investigated the case in which the rate of input of the substrate, \( I(t) \), fluctuates in time in a periodic manner. As they noted, such a situation is common in biological systems, both due to intrinsic oscillations in preceding steps of the reaction pathway, and to oscillations external to the organism.

Since by adding (2) and (4) we have \([E(t) + C(t)]' = 0\), that is the total amount of the free and bound enzyme is constant in time, we can set

\[ E(t) + C(t) = K, \]

and since (5) decouples from the other equations, we can rewrite the system in terms of \( S \) and \( C \) as

\[ S'(t) = I(t) - k_1[K - C(t)]S(t) + k_{-1}C(t), \]  
(6)

\[ C'(t) = k_1[K - C(t)]S(t) - (k_{-1} + k_2)C(t). \]  
(7)

Assuming that \( I(t) \) satisfies (1) and is \( T \)-periodic

\[ I(t + T) = I(t), \quad t \in \mathbb{R}, \]  
(8)

we ask, as a first step in understanding the dynamics of the system, whether there exists a \( T \)-periodic solution \( S(t), C(t) \), of (6), (7), with

\[ S(t) > 0, \quad t \in \mathbb{R}, \]  
(9)

\[ 0 < C(t) < K, \quad t \in \mathbb{R}. \]  
(10)

In the case of a constant rate of input \( I(t) = \bar{I} \), there is a unique stationary solution if and only if

\[ \bar{I} < k_2 K, \]  
(11)
given by
\[ \bar{C} = \frac{1}{k_2} \bar{I}, \quad \bar{S} = \frac{(k_2 + k_{-1}) \bar{I}}{k_1(k_2 K - \bar{I})}, \] (12)
and a phase-plane analysis shows that all solutions tend to this equilibrium. Note that the condition (11) says that the rate of input $\bar{I}$ of the substrate is not too large - indeed if this condition is violated then $S(t)$ will increase without bound, since the substrate enters the system more rapidly than it can be processed by the enzyme. The proof of our existence theorem for the periodic case will involve a homotopy connecting it to the case of constant input.

Returning to the general case of periodic $I(t)$, and adding (6) and (7) we get
\[ C'(t) + k_2 C(t) = I(t) - S'(t). \] (13)
Assuming that $C(t)$, $S(t)$ is a $T$-periodic solution, and integrating (13) on $[0, T]$, taking into account the periodicity, we get
\[ k_2 \int_0^T C(t) dt = \int_0^T I(t) dt. \] (14)
From (10) and (14) it follows that
\[ \frac{1}{T} \int_0^T I(t) dt < k_2 K. \] (15)
Thus (15) is a necessary condition for the existence of a $T$-periodic solution.

In [2], (where the case $I(t) = \bar{I}(1 + \epsilon \sin(\omega t))$ with $0 \leq \epsilon \leq 1$ is considered) it is proposed that the existence of a periodic solution can be proven by constructing an invariant rectangle for the flow corresponding to the system (6), (7), of the form
\[ D = \{(S, C) \mid 0 \leq S \leq \hat{S}, \quad 0 \leq C \leq K - \delta\}, \] (16)
(with $\hat{S}$ and $\delta$ chosen appropriately), so that Brouwer’s fixed-point theorem, applied to the time $T$ Poincaré map of (6), (7), implies the existence of a fixed point of this map, which corresponds to the required $T$-periodic solution. An examination of this method of proof shows that an invariant rectangle of the form (16) exists if and only if the input function $I(t)$ satisfies
\[ \max_{t \in [0, T]} I(t) < k_2 K. \] (17)
Note that this sufficient condition (17) for the existence of a $T$-periodic solution is more stringent than the necessary condition (15). Here we bridge this gap by proving that in fact (15) is sufficient for the existence of a positive $T$-periodic solution. We employ the methods of nonlinear functional analysis, reformulating the problem as a fixed-point problem for a nonlinear operator in a space of $T$-periodic functions, and using degree theory (see, e.g., [1, 3]) to prove the existence of a fixed point of this operator.

Our existence result raises the following question: is it true that for any $I(t)$ satisfying (15), the periodic solution is unique and globally stable?

2 The existence theorem

We set

$$I = \frac{1}{T} \int_{0}^{T} I(t) dt, \quad I_0(t) = I(t) - \bar{I}.$$  

**Theorem 1** Assume $k_1, k_2 > 0$, $k_{-1} \geq 0$, $K > 0$ and $I(t)$ is a continuous function satisfying (1) and (8). Then there exists a $T$-periodic solution $S(t), C(t)$ of (6), (7) satisfying (9), (10) if and only if

$$0 < \bar{I} < k_2 K. \quad (18)$$

The fact that (18) is a necessary condition for existence was explained above, so we now assume that (18) holds, and need to prove the existence of a $T$-periodic solution.

Note that (6), (7) is equivalent to (6), (13), and it is the latter which we will be using.

We define

$$\bar{C} = \frac{1}{k_2} \bar{I}, \quad (19)$$

$$C_0(t) = C(t) - \bar{C}.$$  

The condition (18) is equivalent to

$$0 < \bar{C} < K. \quad (20)$$

4
and from (14) we have that if $S, C$ is a $T$-periodic solution of (6), (13) then $C_0$ satisfies
\[ \int_0^T C_0(t)dt = 0. \] (21)

We can thus rewrite (6), (13) in terms of $S$ and $C_0$:
\[
S'(t) + k_1[K - C - C_0(t)]S(t) = I(t) + k_{-1}C_0(t) + k_{-1}\bar{C}, \tag{22}
\]
\[
C'_0(t) + k_2C_0(t) = I_0(t) - S'(t). \tag{23}
\]

The following lemma, in which we solve (22) for a $T$-periodic solution $S(t)$ in terms of $C_0(t)$, is the place where the key condition (18) is exploited.

**Lemma 1** Given a $T$-periodic continuous function $C_0(t)$ satisfying (21), the linear equation (22) has a unique $T$-periodic solution $S(t)$, and if, in addition,
\[ C(t) = \bar{C} + C_0(t) \geq 0, \quad t \in \mathbb{R}, \tag{24} \]
then $S$ satisfies (9).

**Proof:** Setting $C(t) = \bar{C} + C_0(t)$, the general solution of (22) is
\[
S(t) = \exp \left( -k_1 \int_0^t [K - C(s)]ds \right)S(0)
\]
\[ + \int_0^t \exp \left( k_1 \int_0^s [K - C(r)]dr \right)[I(s) + k_{-1}C(s)]ds. \tag{25} \]

The condition for $S$ to be $T$-periodic is $S(0) = S(T)$, or
\[
\left[ 1 - \exp \left( -k_1 \int_0^T[K - C(s)]ds \right) \right]S(0)
\]
\[ = e^{k_1T[K - \bar{C}]T} \int_0^T \exp \left( k_1 \int_0^s [K - C(r)]dr \right)[I(s) + k_{-1}C(s)]ds. \tag{26} \]

(20), (19) and (21) imply that
\[ \int_0^T [K - C(t)]ds = T[K - \bar{C}] > 0, \]
which implies that the coefficient of $S(0)$ on the left-hand side of (23) is positive, hence the existence of a unique $T$-periodic solution $S$ of (23) is ensured, given by

$$S(t) = \int_0^t \exp \left( k_1 \int_t^s [K - C(r)]dr \right) [I(s) + k_{-1}C(s)]ds$$

$$+ \left[ e^{k_1T(K-C)} - 1 \right]^{-1} \int_0^T \exp \left( k_1 \int_t^s [K - C(r)]dr \right) [I(s) + k_{-1}C(s)]ds.$$

If (24) holds, then recalling (11) and (20), we see that the second term in (27) is strictly positive, and since the first term is nonnegative, we get (9). □

We define $X$ to be the space of continuous $T$-periodic functions $C_0(t)$ satisfying (21), with the maximum norm.

Fixing $I(t)$ satisfying (13), we use the result of lemma 1 to define a mapping $\mathcal{F}(I; \cdot) : X \to X$ ($I$ is regarded as a parameter) as follows. Let $C_0 \in X$ and let $S$ be the $T$-periodic solution of (22) (given explicitly by (27)). Then define

$$\mathcal{F}(I; C_0) = S'.$$

Note that since $S$ is periodic the integral of $S'$ over $[0, T]$ is 0, so we indeed have $\mathcal{F}(I; C_0) \in X$. From the explicit formula (27) it can be be shown by standard methods that

**Lemma 2** The mapping $\mathcal{F}(I; \cdot) : X \to X$ is Fréchet differentiable, and maps bounded sets to bounded sets.

We can now reformulate the problem of finding periodic solutions of (22), (23) as: find $C_0 \in X$ satisfying

$$C_0'(t) + k_2 C_0(t) = I_0(t) - \mathcal{F}(I; C_0)(t).$$

(28)

We define a linear mapping $\mathcal{L} : X \to X$: for any $R \in X$, define $\mathcal{L}(R) = C$ to be the unique $T$-periodic solution of the equation

$$C'(t) + k_2 C(t) = R(t).$$

(29)

By integrating (29) over $[0, T]$ we see that

$$\int_0^T C(t)dt = 0,$$

6
so that $L(R) \in X$. Moreover, since in fact $L$ maps $X$ boundedly to the space of $C^1$-functions, which is compactly embedded in $X$, we have that

**Lemma 3** $L : X \to X$ is compact.

We can now rewrite (28) as

$$C_0 = L(I_0 - F(I; C_0)).$$

(30)

We will prove the existence of a solution of (30) by applying degree theory. Fixing $I$, we define the homotopy $\mathcal{H} : [0, 1] \times X \to X$ by

$$\mathcal{H}(\lambda, C_0) = L(\lambda I_0 - F(\bar{I} + \lambda I_0; C_0)),$$

and we will consider the equation

$$C_0 = \mathcal{H}(\lambda, C_0) \quad 0 \leq \lambda \leq 1.$$

(31)

Note that for $\lambda = 1$ (31) coincides with (30), while for $\lambda = 0$ (31) corresponds to the system with constant rate $\bar{I}$ of substrate input.

From lemmas 2 and 3 we have

**Lemma 4** $\mathcal{H} : [0, 1] \times X \to X$ is a continuous compact mapping.

This ensures that we can apply the Leray-Schauder degree (see, e.g., [1, 3]) to $\mathcal{H}$.

We define the bounded open set $G \subset X$ by

$$G = \{C_0 \in X \mid 0 < C_0(t) + \bar{C} < K \quad t \in \mathbb{R}\}.$$

The following lemma summarizes the reduction of our problem to a fixed-point problem, and provides essential a-priori bounds.

**Lemma 5** If $C_0 \in G$ solves (31) for some $0 \leq \lambda \leq 1$, and if $C = C_0 + C$ and $S$ is the $T$-periodic solution of

$$S'(t) = \bar{I} + \lambda I_0(t) - k_1[K - C(t)]S(t) + k_{-1}C(t),$$

(32)

then

$$C'(t) = k_1[K - C(t)]S(t) - (k_{-1} + k_2)C(t).$$

(33)

and $S, C$ satisfy (29), (30).
Proof: Assume $C_0$ satisfies (31). By the definition of $F$ we have $F(\bar{I} + \lambda I_0; C_0) = S'$ where $S$ is the periodic solution of (32), and by the definition of $L$ we have

$$C'_0(t) + k_2 C_0(t) = \lambda I_0(t) - F(\bar{I} + \lambda I_0; C_0) = \lambda I_0(t) - S'(t). \quad (34)$$

Taking the difference of (32) and (34) gives (33).

By (1) we have

$$\bar{I} + \lambda I_0(t) = (1 - \lambda) \bar{I} + \lambda I(t) \geq 0, \quad \lambda \in [0, 1], \ t \in \mathbb{R}, \quad (35)$$

and the assumption that $C_0 \in \bar{G}$ means that

$$0 \leq C(t) \leq K, \quad t \in \mathbb{R}, \quad (36)$$

so lemma 1 implies that $S$ satisfies (9).

To show that $C(t) > 0$ for all $t$, let $t_1$ be a point where $C$ achieves its global minimum, and assume by way of contradiction that $C(t_1) \leq 0$, so that by (36) $C(t_1) = 0$. Since $t_1$ is a minimum point, we also have $C'(t_1) = 0$. Substituting into (33) we get $k_1 K S(t_1) = 0$, so $S(t_1) = 0$, which contradicts (9), which has already been proved.

Similarly, to show that $C(t) < K$ for all $t$, let $t_2$ be a point where $C$ achieves its global maximum, and assume by way of contradiction that $C(t_2) \geq K$, so that by (36) $C(t_2) = K$. Since $t_2$ is a maximum point, we also have $C'(t_2) = 0$. Substituting into (33) gives $(k_{-1} + k_2) K = 0$, a contradiction. ■

We note that lemma 5 implies that if $C_0 \in \bar{G}$ then $C_0$ satisfies (10), so that $C_0 \in G$. We thus get

**Lemma 6** \(\lambda \in [0, 1], \ C_0 \in \partial G \quad \Rightarrow \quad C_0 \neq \mathcal{H}(\lambda, C_0).\)

By the homotopy invariance property of the degree, it follows that

**Lemma 7** \(\deg(id_X - \mathcal{H}(1, \cdot), G) = \deg(id_X - \mathcal{H}(0, \cdot), G).\)

We now show that

**Lemma 8** \(\deg(id_X - \mathcal{H}(0, \cdot), G) \neq 0.\)
Proof: When $\lambda = 0$, the only $T$-periodic solution of (32), (33) is that given by (12), so the only solution of (31) is $C_0 = 0$.

In order to prove the lemma it suffices, then, to prove that the local degree of $id_X - H(0, \cdot)$ at $C_0 = 0$ is nonzero, and this will follow if we can show the Fréchet derivative $id_X - D_{C_0} H(0, 0)$ is nonsingular.

We have

$$id_X - D_{C_0} H(\bar{I}, 0) = id_X + L \circ D_{C_0} \mathcal{F}(\bar{I}; 0),$$

so if this is singular there exists a nontrivial $\tilde{C}_0 \in X$ with

$$\tilde{C}_0 = -L(D_{C_0} \mathcal{F}(\bar{I}; 0)(\tilde{C}_0)).$$

(37)

We will thus assume that (37) holds, and show that it forces $\tilde{C}_0 = 0$.

By the definition of the Fréchet derivative,

$$D_{C_0} \mathcal{F}(\bar{I}; 0)(\tilde{C}_0) = \frac{d}{d\alpha} \mathcal{F}(\bar{I}; \alpha \tilde{C}_0) \bigg|_{\alpha = 0}.$$  

(38)

By the definition of $\mathcal{F}$, we have

$$\mathcal{F}(\bar{I}; \alpha \tilde{C}_0) = S_t(\alpha, t),$$

(39)

where $S(\alpha, t)$ satisfies

$$S_t(\alpha, t) + k_1[K - \bar{C} - \alpha \tilde{C}_0(t)]S(\alpha, t) = \bar{I} + k_{-1} \alpha \tilde{C}_0(t) + k_{-1} \bar{C}$$

(40)

In particular

$$S(0, t) = \tilde{S},$$

where $\tilde{S}$ is given in (12). Differentiating (40) with respect to $\alpha$ and setting $\alpha = 0$ we get

$$S_{\alpha t}(0, t) + k_1[K - \bar{C}]S_{\alpha}(0, t) = [k_1 \tilde{S} + k_{-1}] \tilde{C}_0(t)$$

(41)

From (38) and (39) we have

$$D_{C_0} \mathcal{F}(\bar{I}; 0)(\tilde{C}_0) = S_{\alpha t}(0, t),$$

which, using (37), implies

$$L(S_{\alpha t}(0, \cdot)) = -\tilde{C}_0.$$
so by the definition of $\mathcal{L}$

$$\ddot{C}_0(t) + k_2 \dot{C}_0(t) = -S_{\alpha t}(0, t) \quad (42)$$

Differentiating (41) with respect to $t$ we have

$$S_{\alpha tt}(0, t) + k_1[K - \bar{C}]S_{\alpha t}(0, t) = [k_1 \bar{S} + k_{-1}] \ddot{C}_0(t)$$

and substituting (42) we have

$$S_{\alpha tt}(0, t) - k_1[K - \bar{C}][\dot{C}_0(t) + k_2 \dot{C}_0(t)] = [k_1 \bar{S} + k_{-1}] \ddot{C}_0(t). \quad (43)$$

Differentiating (42) with respect to $t$ we have

$$S_{\alpha tt}(0, t) = -\dddot{C}_0(t) - k_2 \ddot{C}_0(t),$$

and together with (43) we get

$$\dddot{C}_0(t) + [k_2 + k_1(K - \bar{C} + \bar{S}) + k_{-1}] \ddot{C}_0(t) + k_1 k_2[K - \bar{C}] \dot{C}_0(t) = 0.$$

Multiplying this by $\dddot{C}_0(t)$ and integrating over $[0, T]$, taking into account the periodicity, we obtain

$$[k_2 + k_1(K - \bar{C} + \bar{S}) + k_{-1}] \int_0^T (\dddot{C}_0(t))^2 dt = 0,$$

and since, using (20), the coefficient is positive, we have $\dddot{C}_0 = 0$. Since $\dddot{C}_0 \in X$, this implies $\dddot{C}_0 = 0$, as we wanted to prove. □

From lemmas 7 and 8 we obtain

$$\operatorname{deg}(id_X - \mathcal{H}(1, \cdot), G) \neq 0$$

which implies the existence of a solution $C_0 \in G$ of (31), which, by lemma 5, implies theorem 1.

References

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10
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