**ABSTRACT**

Leadership supercomputers feature a diversity of storage, from node-local persistent memory and NVMe SSDs to network-interconnected flash memory and HDD. Memory mapping files on different tiers of storage provides a uniform interface in applications. However, system-wide services like mmap are optimized for generality and lack flexibility for enabling application-specific optimizations. In this work, we present UMap to enable user-space page management that can be easily adapted to access patterns in applications and storage characteristics. UMap uses the userfaultfd mechanism to handle page faults in multi-threaded applications efficiently. By providing a data object abstraction layer, UMap is extensible to support various backing stores. The design of UMap supports dynamic load balancing and I/O decoupling for scalable performance. UMap also uses application hints to improve the selection of caching, prefetching, and eviction policies. We evaluate UMap in five benchmarks and real applications on two systems. Our results show that leveraging application knowledge for page management could substantially improve performance. On average, UMap achieved 1.25 to 2.5 times improvement using the adapted configurations compared to the system service.

**KEYWORDS**

memory mapping, memmap, page fault, user-space paging, userfaultfd, page management

**Reference Format:**

Ivy B. Peng, Marty McFadden, Eric Green, Keita Iwabuchi, Kai Wu, Dong Li, Roger Pearce, and Maya Gokhale. 2019. *UMap* : Enabling Application-driven Optimizations for Page Management.

**1 INTRODUCTION**

Recently, leadership supercomputers provide enormous storage resources to cope with expanding data sets in applications. The storage resources come in a hybrid format for balanced cost and performance [10, 11, 13]. Fast and small storage, which is implemented using advanced technologies like persistent memory and NVMe SSDs, often co-locate with computing units inside compute node. Storage with massive capacity, on the other hand, uses cost-effective technologies like HDD and is interconnected to compute nodes through the network. In between, burst buffers use fast memory technologies and are accessible through the network. Memory mapping provides a uniform interface to access files on different types of storage as if to dynamically allocated memory. For instance, out-of-core data analytic workloads often need to process large datasets that exceed the memory capacity of a compute node [17]. Using memory mapping to access these datasets shift the burden of paging, prefetching, and caching data between storage and memory to the operating systems.

---

*MCHPC’19, Denver, USA*  
2019. ACM ISBN 978-1-4503-XXXX-X/YY/MM.
Currently, operating systems provide the `mmap` system call to map files or devices into memory. This system service performs well in loading dynamic libraries and could also support out-of-core execution. However, as a system-level service, it has to be tuned for performance reliability and consistency over a broad range of workloads. Therefore, it may reduce opportunities in optimizing performance based on application characteristics. Moreover, backing stores on different storage exhibit distinctive performance characteristics. Consequently, configurations tuned for one type of storage will need to be adjusted when mapping on another type of storage. In this work, we provide UMap to enable application-specific optimizations for page management in memory mapping various backing stores. UMap is highly configurable to adapt user-space paging to suit application needs. It facilitates application control on caching, prefetching, and eviction policies with minimal porting efforts from the programmer. As a user-level solution, UMap confines changes within an application without impacting other applications sharing the platform, which is unachievable in system-level approaches.

We prioritize four design choices for UMap based on surveying realistic use cases. First, we choose to implement UMap as a user-level library so that it can maintain compatibility with the fast-moving Linux kernel without the need to track and modify for frequent kernel updates. Also, we employ the recent userfaultfd [7] mechanism, other than the signal handling + callback function approach to reduce overhead and performance variance in multi-threaded applications. Third, we target an adaptive solution that sustains performance even at high concurrency for data-intensive applications, which often employ a large number of threads for hiding data access latency. Our design pays particular consideration on load imbalance among service threads to improve the utilization of shared resources even when data accesses to pages are skewed. UMap dynamically balances workloads among all service threads to eliminate bottleneck on serving hot pages. Finally, for flexible and portable tuning on different computing systems, UMap provides both API and environmental controls to enable configurable page sizes, eviction strategy, application-specific prefetching, and detailed diagnosis information to the programmer.

We evaluate the effectiveness of UMap in five use cases, including two data-intensive benchmarks, i.e., a synthetic sort benchmark and a breadth-first search (BFS) kernel, and three real applications, i.e., Lrzip [8], N-Store database [2], and an asteroid detection application that processes massive data sets from telescopes. We conduct out-of-core experiments on two systems with node-local SSD and network-interconnected HDD storage. Our results show that UMap can enable flexible user-space page management in data-intensive applications. On the AMD testbed with local NVMe SSD, applications achieved 1.25 to 2.5 times improvement compared to the standard system service. On the Intel testbed with network-interconnected HDD, UMap brings the performance of the asteroid detection application close to that uses local SSD for 500 GB data sets. In summary, our main contributions are as follows:

- We propose an open-source library\(^1\), called UMap that leverages lightweight userfaultfd mechanism to enable application-driven page management.
- We describe the design of UMap for achieving scalable performance in multi-threaded data-intensive applications.
- We demonstrate five use cases of UMap and show that enabling configurable page size is essential for performance tuning in data-intensive applications.
- UMap improves the performance of tested applications by 1.25 to 2.5 times compared to the standard mmap system service.

2 BACKGROUND AND MOTIVATION

In this section, we introduce memory mapping, prospective benefits from user-space page management, and the enabling mechanism userfaultfd.

2.1 Memory Mapping

Memory mapping links images and files in persistent storage to the virtual address space of a process. The operating system employs demand paging to bring only accessed virtual pages into physical memory because virtual memory can be much larger than physical memory. An access to memory-mapped regions triggers a page fault if no page table entry (PTE) is present for the accessed page. When such a page fault is raised, the operating system resolves it by copying in the physical data page from storage to the in-memory page cache.

Common strategies for optimizing memory mapping in the operating systems include page cache, read-ahead, and madvise hints. The page cache is used to keep frequently used pages in memory while less important pages may need to be evicted from memory to make room for newly requested pages. Least Recently Used (LRU) policy is commonly used for selecting pages to be evicted. The operating system may proactively flush dirty pages, i.e., modified pages in the page cache, into storage when the ratio of dirty page exceeds a threshold value \(^{[19]}\). Read-ahead preloads pages into physical memory to avoid the overhead associated with page fault handling, TLB misses and user-to-kernel mode transition. Finally, the madvise interface takes hints to allow the operating system to make informed decisions for managing pages.

\(^{1}\)UMap v2.0.0 https://github.com/LLNL/unmap
2.2 User-space Page Management

User-space page management uses application threads to resolve page faults and manage virtual memory in the background as defined by the application. The userfaultfd is a lightweight mechanism to enable user-space paging compared to the traditional SIGSEGV signal and callback function [7]. Applications register address ranges to be managed in user-space, and specify the type of events, e.g., page faults and events in un-cooperative mode, to be tracked. Page faults in the address ranges are delivered asynchronously so that the faulting process is blocked instead of idling, allowing other processes to be scheduled to proceed.

The fault-handling thread in the application can atomically resolve page faults with the `UFSIO_COPY` ioctl, which ensures the faulting process is (optionally) waken up only after the requested page has been fully copied into physical memory [7]. The fault-handling threads may utilize application-specific knowledge to optimize this procedure, providing the flexibility that is unachievable in kernel mode. For instance, the application could select arbitrary page sizes, read-ahead window size, or provides specific knowledge to optimize this procedure, providing the flexibility that is unachievable in kernel mode. For instance, the application could select arbitrary page sizes, read-ahead window size, or provides specific pages for prefetching or evicting. All these optimizations remain inside one application and will not impact other applications sharing the same system. User-space paging is not only limited to backing store on file systems. In contrast to kernel mode, the fault-handling thread has the liberty to fetch data from a variety of backing stores, such as a memory server, databases, and even another process.

3 DESIGN

In this section, we describe the design of UMap. We first provide an overview of the architecture and then focus on four optimizations for achieving high performance in user-space.

3.1 Overview

UMap provides an interface for applications to register multiple virtual address ranges, called UMap regions that bypass the kernel service and instead, be managed in user-space. Figure 1 presents the UMap architecture. Dark blue regions in the virtual address space are UMap regions. Each region has a backing store, where the data is physically located. UMap provides an abstraction layer in the store object (yellow circles) for accessing different types of storage. When an application accesses a UMap region, if the accessed page is not present in the physical memory, page faults are triggered. These page faults queue up in a FIFO buffer and multiple UMap fillers cooperatively resolve these faults. If the requested pages are not fetched in yet, UMap fillers will invoke the access functions defined in the store object to read data from the underlying storage. If the buffer is fully occupied, some pages need to be evicted following a user-defined strategy. In the background, a group of UMap evictors keep monitoring the ratio of dirty pages in the buffer. Once the ratio of dirty pages reaches a (configurable) high watermark, UMap evictors will coordinately write data to the storage.

3.2 I/O Decoupling

Our design decouples the I/O operation from the fault-handling threads to achieve high concurrency in long latency tasks. I/O operations that move data between storage and memory have a much longer latency than memory accesses. For instance, latency to the state-of-art persistent memory (PM) is about 100 - 500 ns [12], latency to NVMe-based SSD is in the range of $\approx 20 \mu s$ [3] while accesses to HDD would require several milliseconds. In contrast, memory accesses typically takes 20-100 ns. To improve the I/O performance, UMap employ a configurable number of threads for moving data between storage and memory to exploit the bandwidth supported by the hardware.

The dedicated two groups of I/O threads is referred to as fillers and evictors, as illustrated in the orange and blue boxes in Figure 1. Fillers split the workload of copying pages to memory while evictors concurrently write data to storage. A separate group of manager threads, typically with low concurrency, keeps polling for notification of tracked events from the operating system. By decoupling the tasks into three groups of workers, UMap has the flexibility to adapt the concurrency in each group to reflect their different workload. In contrast, a coupled design results in a long blocking operation that has limited flexibility to optimize.
3.3 Dynamic Load Balancing

UMap employs a dynamic load balancing strategy to improve resource utilization. We find that memory-mapped regions could have hot and cold segments. Hot segments require a higher level of concurrency for frequent data movement and more physical memory for buffering data than cold segments. For instance, social networks are considered as a type of scale-free network whose degree distribution follows a power law. Memory segment that stores high-degree vertices would naturally result in more accesses than the regions that store low-degree vertices. We design UMap to avoid load imbalance even in such skewed data access patterns by dynamically distributing workloads from all memory regions among UMap fillers.

UMap employs a dynamic scheduling strategy similar to “work stealing” approach in task-based programming models [15]. UMap uses a single UMap buffer object to manage the metadata of in-memory pages for all regions. When UMap receives the notification of a fault event from the operating system, it appends the workload for resolving this fault into a dynamically growing queue. A group of workers split the pending workload to load pages from the backing store collectively. Consequently, when hot memory segments generate more workloads than others, they will be assigned with more working threads. Orthogonal to the data fetching task is the data flushing task that writes dirty pages back to the persistent stores. When the number of dirty pages reaches a high watermark, the workload is appended to a separate queue and then split by a different group of workers. Figure 1 illustrates the shared (internal) buffer and the work distribution among workers. The dynamic load balancing design prepare UMap to cope with applications with diverse access patterns.

3.4 Extensible Back Store

UMap provides a data object abstraction layer to support different types of backing stores. Currently, applications running on leadership supercomputers have multiple choices of storage, including local SSD, network-interconnected SSD, and HDD. In the future, architectures that provide disaggregated memory and storage resources are likely to emerge. Based on this observation, our design ensures that UMap is extensible for current and future architectures.

UMap facilitates applications to associate their own backing store for each memory region. The application has specific control over which storage layer to access to resolve a page fault. In this way, an application is presented with a uniform interface as the virtual memory address space while UMap in the backend handles data movement to/from various types of storage.

3.5 User-controlled Page Flushing

We design UMap to enable user-space control on page flushing to a persistent store. There are two motivations. First, the system service may write dirty pages to storage whenever the operating system deems appropriate. Unpredictable behavior may occur if a memory range requires strong consistency such as atomicity among multiple pages. Second, frequent page flushing is known to cause increased performance variation and degradation. For instance, RHEL triggers page flushing when more than 10% pages are dirty [19]. With user control, the application could avoid aggressive page flushing by setting a high threshold or even postponed page flushing to a later stage. UMap monitors the ratio of dirty pages to compare with a user-defined high watermark to trigger page flushing as well as a low watermark that suspends page flushing.

3.6 Application-Specific Optimization

UMap maintains a set of parameters for programmers with application knowledge to configure page management. One of the most performance-critical parameters is the internal page size of a memory region, denoted as UMap page. UMap supports an arbitrary page size for each memory region while the system service only supports fixed page sizes. UMap page defines the finest granularity in data movement between memory and backing store. For the same memory region, choosing a large UMap page could reduce the overhead of metadata, but may also move more than accessed data into memory. By tuning the page size, an application could identify an optimal configuration that balances the overhead and data usage. Also, an application can control the page buffer size, which can alleviate OOM situations in unconstrained mmap.

UMap also supports a flexible prefetching policy that can fetch pages even in irregular patterns. The operating systems usually recognize page accesses as either sequential or random, to increase or decrease the readahead window size, respectively. Real-world applications, however, exhibit complex access patterns, and the general prefetching mechanism becomes insufficient. In contrast, UMap could prefetch a set of arbitrary pages into memory, as informed by the application. Moreover, an application can control the start of prefetching to avoid premature data migration that interferes with pages in use. This flexibility, together with knowledge from application algorithm or offline profiling, eases application performance tuning.

4 IMPLEMENTATION

UMap is implemented in C ++ and uses the userfaultfd system call [1]. UMap enables application controls on page management through both API and environmental variables. The
fault-handling thread resolves the page fault by calling the application-supplied function (if provided), or performing direct I/O to the backing store by invoking the defined access functions. UMap uses the UFFDIO_COPY ioctl [7] to ensure atomic copy to the allocated memory page before waking up the blocked process.

### 4.1 API

**UMap** provides similar interfaces as `mmap` to ease porting existing applications. An application can register/unregister multiple memory regions to be managed by **UMap** through the `umap` and `uunmap` interface. One additional flexibility provided by **UMap** is the multi-file backed region. Given a set of files, each with individual offsets and size, **UMap** maps them into a contiguous memory region. While applications can rely on **UMap** runtime for managing pages, **UMap** also provides a plugin architecture that allows application to register callback functions. A set of configuration interfaces with naming convention `umapcfg_set_xx`, allow the application to control paging explicitly: (1) the maximum size of physical memory used for buffering pages; (2) the level of concurrency for processing I/O operations in each group of workers; (3) the threshold value for starting or suspending writing dirty pages to back stores. Listing 1 illustrates a simple application that uses paging and prefetching services in **UMap**.

#### Listing 1: UMap API

```c
int fd = open(fname, O_RDWR);  
void* base_addr = umap(NULL, totalbytes, PROT_READ|PROT_WRITE, UMAP_PRIVATE, fd, 0);  
// Select two non-contiguous pages to prefetch  
std::vector<umap_prefetch_item> pfi;  
umap_prefetch_item p0 = {.page_base_addr = &base[5 * psize]};  
pfi.push_back(p0);  
umap_prefetch_item p1 = {.page_base_addr = &base[15 * psize]};  
pfi.push_back(p1);  
umap_prefetch(num_prefetch_pages, &pfi[0]);  
computation();  
// Release resources  
uunmap(base_addr, totalbytes);  
```

### 4.2 Environmental Controls

**UMap** uses a set of environment variables to control: the number of fillers and evictors; the buffer size; the buffer draining policy; and the read-ahead window size. We highlight the key environment variables that **UMap** tracks to dictate its runtime behavior:

- **UMAP_PAGESIZE** sets the internal page size for memory regions.
- **UMAP_PAGE_FILLERS** sets the number of workers to perform read operations from the backing store. Default: the number of hardware threads.
- **UMAP_PAGE_EVICTORS** sets the number of evictors that will perform evictions of pages. Default: the number of hardware threads.
- **UMAP_EVICT_HIGH_WATER_THRESHOLD** sets the threshold in **UMap** buffer to trigger the evicting procedure. Default: 90%
- **UMAP_EVICT_LOW_WATER_THRESHOLD** sets the threshold in **UMap** buffer to suspend evicting procedure. Default: 70%
- **UMAP_BUFSIZE** sets the size of physical memory to be used for buffering **UMap** pages. Default: (80% of available memory)
- **UMAP_READ_AHEAD** sets the number of pages to read-ahead when resolving a demand paging. Default: 0
- **UMAP_MAX_FAULT_EVENTS** sets the maximum number of page fault events that will be read from the kernel in a single call. Default: the number of hardware threads.

### 4.3 Limitations

The current implementation uses the write protection support from the kernel to track dirty pages in the physical memory. For pages in write-protected memory ranges, a writes will trigger a fault that sends a UFFD message to handling threads. Currently, the write protection support in userfaultfd is only available in the experimental Linux kernel [2].

### 5 Experimental Setup

In this section, we describe the experimental setup for the evaluation. We summarize the configuration parameters of two testbeds in Table 1 and 2. The AMD testbed includes three identical machines (Altus, Bertha, Pmemio) that feature two AMD EPYC 7401 (24 cores /48 hardware threads) processors. The testbed has a total of 256 GB DDR4 DRAM and 16 memory channels that operate at 2400 MT/s. Each machine has a total of 4.65 TiB disk capacity, including 1.8 GB SATA Micron 5200 Series SATA SSD. The platform runs Fedora 29 with Linux kernel 5.1.0-rc4-ufsd-wp-207866-gcc66ef4-dirty (experimental version). We compiled all applications using GCC 8.3.1 compiler with support for OpenMP. We use the local SSD on the AMD testbed to evaluate the impact of **UMap** page sizes in all applications. The second testbed, the Intel testbed is on a cluster called **flash**. Its storage includes a remote HDD through Lustre parallel distributed file system. It also features 1.5 TB local SSD. We test the asteroid detection

[2] Linux Patch https://git.kernel.org/pub/scm/linux/kernel/git/andrea/aa.git.
We use its default setting and the standard 4KiB page size. We study the performance benefit of enabling flexible page sizes. For the mmap tests, we varied the page size to identify the optimal concurrency for this benchmark. In most tested cases, using 48 fillers and 24 evictors brings the best performance. We then fixed the number of fillers and evictors to test the impact of different page sizes. For the mmap tests, we use its default setting and the standard 4KiB page size.

In this section, we evaluate the performance of UMap in data-intensive benchmarks and applications. In particular, we study the performance benefit of enabling flexible page sizes at application level.

6.1 Out-of-core Sort

Our first evaluation uses an in-house sorting benchmark, called umapsort. Umapsort is a multi-threaded program that performs quicksort on values stored in a file. Thus, umapsort is a read-write workload. For the evaluation, we use a single 500GiB data set of a sequence of ascending 64-bit words. We configured the benchmark to memory map data sets either using the mmap system call or UMap API. Then, the program sorts the values in the memory region into descending order. The application was configured to run with 96 OpenMP threads on the AMD testbed with 256GiB of physical memory. The data set is stored on the local NVMe-SSD device configured with its default boot-time values. We report the experimental results in Figure 2.

We used different numbers of fillers and evictors to identify the optimal concurrency for this benchmark. In most tested cases, using 48 fillers and 24 evictors brings the best performance. We then fixed the number of fillers and evictors to test the impact of different page sizes. For the mmap tests, we use its default setting and the standard 4KiB page size.

For UMap tests, we change the page size to identify the optimal configuration. At the smallest page size, UMap shows much higher overhead than mmap. We find that increasing page sizes in UMap steadily improves the performance. At 64KiB page, UMap starts outperforming mmap. By adjusting UMap page size to 8MiB, the UMap version achieves 2.5 times speedup compared to the mmap version. One reason for the improved performance at larger page sizes is that the reduction in page faults, which reduces the time spent in servicing page faults and also aggregate smaller data transfers into bulky transfers to exploit bandwidth. As the change is localized to the application process, there is no need to modify any OS page size or file system prefetch settings.

6.2 Graph Application

We implemented a conventional level-synchronous BFS algorithm. Our BFS program takes a graph with compressed sparse row (CSR) data format and stores only the CSR graph in the storage device. We used a separated program to generate a CSR graph to make a read-only benchmark and dropped page cache before running the benchmark to achieve consistent results. As for dataset, we used an R-MAT graph generator with the edge falling probabilities used in the Graph500.

Figure 3 shows UMap’s BFS performance normalizing to mmap’s best performance case where readahed is off. We varied Umap page size from 4 KB to 4 MB and used the default values for its other environmental variables. Umap showed its best performance and outperformed mmap by 1.8X with 512 KB page size whereas mmap slowed down as increased the page size. We clearly confirmed the benefit of Umap’s variable page size feature in terms of not only providing user level control but also better performance.

Table 1: The AMD Testbed Specifications

| Platform          | Penguin Altix XE2112 (Base Board: M291-FS6-ZB) |
|-------------------|-----------------------------------------------|
| Processor         | AMD EPYC 7401                                  |
| CPU               | 28 cores (48 hardware threads) x 2 sockets     |
| Speed             | 1.2 GHz                                        |
| Caches            | 64KB 8-way L1d and 32KB 6-way L1i, 512KB 6-way private L2, 8MB 8-way shared L3 per three cores |
| Memory            | 16GB DDR4 RDIMM x 8 channels (2400 MT/s) x 2 sockets |
| Storage           | ~3TB NVMe (type: HGST SN200)                   |

Table 2: The Intel Testbed Specifications

| Platform          | S2600WTTR (Base Board: S2600WTTR)             |
|-------------------|-----------------------------------------------|
| Processor         | Intel Xeon E5-2670 v3 (Haswell)              |
| CPU               | 12 cores (24 hardware threads) x 2 sockets   |
| Speed             | 2.3 GHz (Turbo 3.1 GHz)                      |
| Caches            | 32KB 8-way L1d and 32KB 8-way L1i, 256KB 8-way private L2, 300GB 20-way shared L3 |
| Memory            | 2 to 64GB DDR4 RDIMM x 4 channels (1866 MT/s) x 2 sockets |
| Storage           | ~1.5TB NVMe SSD (type: HGST SN200)           |
We constrain the available memory to the program to ensure which only has occasional data reuse of earlier portions of window. The version requires a command-line option to override the system time-series telescope data. We use UMap to create a search for transient objects, such as asteroids, in intermittent time-series telescope data. We use UMap to create a performance at about 1.25 times that of mmap system level, i.e., when duplicated hash values are found. Likely due to the mostly sequential access pattern in lrzip, sensitivity to the change in page size. This insensitivity is not affected redundancies in input files to reduce size. Lrzip uses a Long Range ZIP (lrzip) is a program that implements a full-file compression algorithm [8]. Compression algorithms detect redundancies in input files to reduce size. Lrzip uses a modified RZIP algorithm to achieve an effectively unlimited compression window size. The original mmap version of lrzip uses a large buffer, e.g., one-third of system memory, to mmap a window that ‘slides’ through the input file. When matches are found, lrzip may use a secondary 64k mmap region to page in any matching regions outside the main window. The UMap version removes these sliding buffers and replaces them with a single UMap region spanning the entire input file. UMap runtime automatically manages the amount of file data paged in memory during execution.

Our experiments run lrzip in pre-processing mode to compare the performance of mmap with UMap in RZIP algorithm. We constrain the available memory to the program to ensure out-of-core execution, i.e., 16 GB memory and a 64 GB input data. The UMap version sets the environmental variable to limit UMap buffer for caching pages in memory. The mmap version requires a command-line option to override the system memory on the testbed. In Figure 4, lrzip shows low sensitivity to the change in page size. This insensitivity is likely due to the mostly sequential access pattern in lrzip, which only has occasional data reuse of earlier portions of the input file, i.e., when duplicated hash values are found. Once the page size exceeds 1MB, the UMap version stabilizes performance at about 1.25 times that of the mmap system call.

### 6.4 Asteroid Detection Application

In this case study, we use UMap for an ongoing study that searches for transient objects, such as asteroids, in intermittent time-series telescope data. We use UMap to create a 3D cube of virtual address space, where each page is directly mapped to pixel data in a series of image files. UMap has the extensibility to integrate an application-specific FITS handler for resolving page fault to a particular file, which would require extensive porting efforts to achieve in mmap.

The application creates millions or even billions of vectors and then virtually translates them through the image cube to calculate the median pixel value along each vector. The starting point of each vector has a uniform random distribution in the data and their slope follows a given linear function. The backing store contains thousands of FITS format image files. Page faults are resolved to the FITS files containing the requested data, where the pixel data is subsequently read and decoded before copied into the faulting page. Note that a page fault may require access data in multiple files.

The evaluation uses a synthetic data set derived from 557 random images taken from an astronomical survey performed on 12/23 2018 by the Dark Energy camera in Chile. These files were resized via bicubic resampling to four times their original dimension in each axis in order to emulate the characteristics of real-world datasets. Each file is approximately 977 MB with dimensions of 16,000 by 16,000 pixels after this operation. The entire dataset is approximately 512 GB. For the Lustre tests, transparent Lustre compression and de-duplication reduces this size to 223 GB.

The experiments process a single pass of 32 million vectors with a UMap buffer size of 64 GB. We demonstrate two types of backing stores in this application. The first uses the local SSD on the AMD testbed. The second uses a backing store mapped to remote disks through a Lustre parallel file system on the Intel testbed. Figure 5 and 6 present the results. Our results show that the application has low sensitivity to page sizes because data reuse among the vectors. A slight performance degradation at large page sizes because larger pages bring more unused data. The execution time initially
Figure 5: Execution time of the asteroid application on local SSD at various UMap page sizes at 256GB input.

Figure 6: Compare performance of the asteroid application on local SSD and Lustre using 512GB input.

decreases to the optimal minimum at 1MiB page and then, slightly increases as larger amounts of unused data begins to contend for buffer space.

6.5 Database Workload

This use case demonstrates that UMap can be easily plugged into existing database applications to improve user-space control over memory mapping. We ported N-Store [2], an efficient NVM database, to use UMap API by changing approximately ten lines of code. N-Store uses persistent memory like SSD as the memory pool for data. Our experiments use a 384 GB persistent memory pool on the local NVMe-SSD on the AMD testbed. N-Store supports multiple executors to execute transactions to the database concurrently. In our evaluation, we sweep 4-32 executors to understand the scalability of UMap on variable concurrency. Our workload uses the popular YCSB [4] benchmark with eight million transactions and five million keys. The measurement is repeated ten times, and we report throughput from N-Store as the metric for performance.

We tested different numbers of fillers and evictors to select the concurrency to be 48 fillers and 24 evictors for this benchmark. Then, with a fixed number of fillers and evictors, we test the impact of different page sizes. Figure 7 reports the throughput of UMap version at different page sizes and the original mmap version at the default 4KiB page. We find that increasing page sizes in UMap does show a trend of increased performance as other applications. The highest throughput is achieved at 32KiB page size, which is about 34% improvement of the mmap version. This page size is smaller than the optimal page sizes in other applications because the access pattern in the benchmark has low locality and mostly random.

Figure 8 report the throughput of the database at an increased application concurrency, i.e., the number of executors increases. The scaling test results demonstrate the advantage of UMap in addressing application requirements that change dynamically. When the number of executors increases from four to 32, the gap between the UMap version and the mmap version increases (in the gray bars). In particular, the speedup by UMap increases from 1.3x to 1.6x steadily (the red line). This result highlights the importance
of a scalable design in UMap for handling various application workloads.

7 DISCUSSION

There are several future directions for UMap to support emerging architectures. **Multi-tiered Storage** has tiered access latency and bandwidth. Currently, UMap is extensible for new layers by defining new data objects. In the future work, we will automate data migration between data objects and adapt to application characteristics to improve storage utilization.

**Disaggregated Memory** architecture has large-capacity memory servers connected to compute node through high-performance network to provide memory on demand. UMap can be used to port applications on such architecture by providing a backing store that defines access functions likely using RDMA for moving to/from memory server.

**Byte-addressable NVM** requires strong consistency for system software like file systems and DAX-aware mmap lacks such support [20]. The UMap buffer could provide applications with explicit control on when to persist changes cached in volatile memory.

8 RELATED WORKS

Previous works have identified limitations in system services for data-intensive applications that perform out-of-core execution for large data sets [5, 18]. [16] analyzes the overhead in the path through Linux virtual memory subsystem for handling memory-mapped I/O. They conclude that kernel-based paging will prevent applications to exploit fast storage. Our approach aims to provide flexibility to adapt memory mapping to application characteristics and back store features.

**DI-MMAP** [17] provides a loadable kernel module that combines with a runtime to optimize page eviction and TLB performance. This approach requires updates to remain compatible with the fast-moving kernel. **CO-PAGER** [10] also provides a user-space paging service by combining a kernel module with a user-space component. CO-PAGER bypasses complex I/O subsystem in the kernel to reduce the overhead of accessing NVM. Our approach stays in user-space completely, and require no modification in the kernel or updates due to kernel updates. Moreover, our design can support a variety of back stores. For instance, remote memory paging that fetches data from a memory server or compute node [6, 14] could be easily integrated into UMap by providing a new store object.

9 CONCLUSIONS

In this work, we provide a user-space page management library, called UMap, to flexibly adapt memory mapping to application characteristics and storage features. UMap employs the lightweight userfaultfd mechanism to enable applications to control critical parameters that impact the performance of memory mapping large data sets while confining the customizations within the application without impacting other applications on the same system. We evaluate UMap in five applications using large data sets on both local SSD and remote HDD. By adapting the page size in each application, UMap achieved 1.25 to 2.5 times improvement compared to the system service mmap. In summary, aUMap can be easily plugged into data-intensive applications to enable application-specific optimization.

ACKNOWLEDGMENT

This work was performed under the auspices of the U.S. Department of Energy by Lawrence Livermore National Laboratory under Contract DE-AC52-07NA27344 (LLNL-PROC-788145). This research was also supported by the Exascale Computing Project (17-SC-20-SC), a collaborative effort of the U.S. Department of Energy Office of Science and the National Nuclear Security Administration. This document was prepared as an account of work sponsored by an agency of the United States government. Neither the United States government nor Lawrence Livermore National Security, LLC, nor any of their employees makes any warranty, expressed or implied, or assumes any legal liability or responsibility for the accuracy, completeness, or usefulness of any information, apparatus, product, or process disclosed, or represents that its use would not infringe privately owned rights. Reference herein to any specific commercial product, process, or service by trade name, trademark, manufacturer, or otherwise does not necessarily constitute or imply its endorsement, recommendation, or favoring by the United States government or Lawrence Livermore National Security, LLC. The views and opinions of authors expressed herein do not necessarily state or reflect those of the United States government or Lawrence Livermore National Security, LLC, and shall not be used for advertising or product endorsement purposes.

REFERENCES

[1] Andrea Arcangeli. 2019. Userland Page Faults and Beyond. https://schd.ws/hosted_files/leccnna2016/c4/userfaultfd.pdf.

[2] Joy Arulraj, Andrew Pavlo, and Subramanya R Dulloor. 2015. Let’s talk about storage & recovery methods for non-volatile memory database systems. In Proceedings of the 2015 ACM SIGMOD International Conference on Management of Data. ACM, 707–722.

[3] Danny Cobb and Amber Huffman. 2012. NVMe Overview. In Intel Developer Forum. Intel.

[4] Brian F Cooper, Adam Silberstein, Erwin Tam, Raghu Ramakrishnan, and Russell Sears. 2010. Benchmarking cloud serving systems with YCSB. In Proceedings of the 1st ACM symposium on Cloud computing. ACM, 143–154.

[5] Michael Cox and David Ellsworth. 1997. Application-controlled demand paging for out-of-core visualization. In Proceedings, Visualization’97 (Cat. No. 97CB36155). IEEE, 235–244.

[6] Sandhya Dwarkadas, Nikolaos Hardavellas, Leonidas Kontothanassis, Rishiyur Nikhil, and Robert Stets. 1999. Cashmere-VLM: Remote memory paging for software distributed shared memory. In Proceedings 13th International Parallel Processing Symposium and 10th Symposium on Parallel and Distributed Processing, IPDPS/SPDP 1999. IEEE, 153–159.

[7] Linux kernel. 2019. Userfaultfd. https://www.kernel.org/doc/Documentation/vm/userfaultfd.txt.

[8] Con Kolivas. 2019. Lzzip – Long Range Zip. https://github.com/colivas/lzzip.

[9] Anthony Koukas, Harinathan Devarajan, and Xian-He Sun. 2018. Hermes: a heterogeneous-aware multi-tiered distributed I/O buffering system. In Proceedings of the 27th International Symposium on High-Performance Parallel and Distributed Computing. ACM, 219–230.
[10] Feng Li, Daniel G Waddington, and Fengguang Song. 2019. Userland CU-PAGER: boosting data-intensive applications with non-volatile memory, userspace paging. In Proceedings of the 3rd International Conference on High Performance Compilation, Computing and Communications. ACM, 78–83.

[11] Sai Narasimhamurthy, Nikita Danilov, Sining Wu, Ganesan Umanesan, Stefano Markidis, Sergio Rivas-Gomez, Ivy Bo Peng, Erwin Laure, Dirk Fleiter, and Shaun De Witt. 2019. SAGE: percipient storage for exascale data centric computing. Parallel Comput. 83 (2019), 22–33.

[12] Ivy B. Peng, Maya B. Gokhale, and Eric W. Green. 2019. System Evaluation of the Intel Optane Byte-addressable NVM. In Proceedings of the International Symposium on Memory Systems. ACM. https://doi.org/10.1145/3357526.3357566

[13] I. B. Peng and J. S. Vetter. 2018. Siena: Exploring the Design Space of Heterogeneous Memory Systems. In SC18: International Conference for High Performance Computing, Networking, Storage and Analysis. 427–440. https://doi.org/10.1109/SC.2018.00036

[14] Sergio Rivas-Gomez, Roberto Gioiosa, Ivy Bo Peng, Gokcen Kestor, Sai Narasimhamurthy, Erwin Laure, and Stefano Markidis. 2018. MPI windows on storage for HPC applications. Parallel Comput. 77 (2018), 38–56.

[15] Arch Robison, Michael Voss, and Alexey Kukanov. 2008. Optimization via reflection on work stealing in TBB. In 2008 IEEE International Symposium on Parallel and Distributed Processing. IEEE, 1–8.

[16] Nae Young Song, Yongseok Son, Hyuck Han, and Heon Young Yeon. 2016. Efficient memory-mapped I/O on fast storage device. ACM Transactions on Storage (TOS) 12, 4 (2016), 19.

[17] Brian Van Essen, Henry Hsieh, Sasha Ames, Roger Pearce, and Maya Gokhale. 2013. DI-MMAP—a scalable memory-map runtime for out-of-core data-intensive applications. Cluster Computing (2013). https://doi.org/10.1007/s10586-013-0309-0

[18] Brian Van Essen, Roger Pearce, Sasha Ames, and Maya Gokhale. 2012. On the role of NVRAM in data-intensive architectures: an evaluation. In 2012 IEEE 26th International Parallel and Distributed Processing Symposium. IEEE, 703–714.

[19] Rik van Riel and Peter W. Morreale. 2008. Sysctl in kernel version 2.6.29. https://www.kernel.org/doc/Documentation/sysctl/vm.txt.

[20] Jian Xu and Steven Swanson. 2016. NOVA: A Log-structured File System for Hybrid Volatile/Non-volatile Main Memories. In 14th USENIX Conference on File and Storage Technologies (FAST 16). 323–338.