Coloring vertices of a graph or finding a Meyniel obstruction*

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Abstract

A Meyniel obstruction is an odd cycle with at least five vertices and at most one chord. A graph is Meyniel if and only if it has no Meyniel obstruction as an induced subgraph. Here we give a $O(n^2)$ algorithm that, for any graph, finds either a clique and coloring of the same size or a Meyniel obstruction. We also give a $O(n^3)$ algorithm that, for any graph, finds either an easily recognizable strong stable set or a Meyniel obstruction.

Keywords: Perfect graphs, Meyniel graphs, Coloring, Robust algorithm, Strong stable set, Existentially polytime theorem

1 Introduction

A graph is Meyniel [10] if every odd cycle of length at least five has at least two chords. A Meyniel obstruction is an odd cycle of length at least five with at most one chord. Thus a graph is Meyniel if and only if it does not contain a Meyniel obstruction as an induced subgraph. Meyniel [10] and Markosyan and Karapetyan [9] proved that Meyniel graphs are perfect. This theorem can be stated in the following way:

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For any graph $G$, either $G$ contains a Meyniel obstruction, or $G$ contains a clique and coloring of the same size (or both).

We give a polytime algorithm which finds, in any graph, an instance of what the Meyniel-Markosyan-Karapetyan theorem says exists. This algorithm works in time $O(n^2)$ where $n$ is the number of vertices of the input graph. This is an improvement in the complexity of the algorithm of the first and second authors [3, 4], which finds, in any graph, a clique and coloring of the same size, or a Meyniel obstruction. This is an enhancement of the $O(n^2)$ algorithm of Roussel and Rusu [14], which optimally colors any Meyniel graph.

This work is motivated by the “Perfect Graph Robust Algorithm Problem” [2]: seek a polytime algorithm which, for any graph $G$, finds either a clique and a coloring of the same size or an easily recognizable combinatorial obstruction to $G$ being perfect. According to the Strong Perfect Graph Theorem [6], proved in a different way, a simple obstruction to perfectness is the existence of an odd hole or odd antihole.

A stable set in a graph $G$ is a set of vertices, no two of which are joined by an edge of $G$. A strong stable set in $G$ is a stable set that contains a vertex of every maximal (by inclusion) clique of $G$. Note that if one can find a strong stable set in every induced subgraph of a graph $G$, one can easily find an optimal coloring of $G$: if $S_1$ is a strong stable set of $G$, $S_2$ is a strong stable set of $G \setminus S_1$, $\ldots$, $S_\ell$ is a strong stable set of $G \setminus (S_1 \cup \ldots \cup S_{\ell-1})$, and $S_\ell$ is the last non-empty such set, then $S_1, \ldots, S_\ell$ is a coloring of $G$ which is the same size as some clique of $G$.

Ravindra [12] presented the theorem that

For any graph $G$, either $G$ contains a Meyniel obstruction, or $G$ contains a strong stable set (or both).

Ravindra’s proof is an informal description of an algorithm which finds, in any graph, an instance of what the theorem says exists.

Hoàng [8] strengthened this to the following:

For any graph $G$ and vertex $v$ of $G$, either $G$ contains a Meyniel obstruction, or $G$ contains a strong stable set containing $v$ (or both).

Hoàng [8] give a $O(n^7)$ algorithm that finds, for any vertex of a Meyniel graph, a strong stable set containing this vertex.

A disadvantage of the Ravindra-Hoàng theorem is that it is not an existentially polytime theorem. A theorem is called existentially polytime (EP)
if it is a disjunction of NP predicates which is always true [2]. The predicate “G contains a strong stable set” may not be an NP-predicate because the definition of strong stable set is not a polytime certificate.

The Ravindra-Hoàng theorem is strengthened in [3, 4] to:

For any graph $G$ and vertex $v$ of $G$, either $G$ contains a Meyniel obstruction, or $G$ contains a nice stable set containing $v$ (or both),

where nice stable sets are a particular type of strong stable set which have the following polytime-certifiable meaning. A nice stable set in a graph $G$ is a maximal stable set $S$ linearly ordered so that there is no induced $P_4$ between any vertex $x$ of $S$ and the vertex which arises from the contraction in $G$ of all the vertices of $S$ that precede $x$. (Contracting vertices $x_1, \ldots, x_k$ in a graph means removing them and adding a new vertex $x$ with an edge between $x$ and every vertex of $G \setminus \{x_1, \ldots, x_k\}$ that is adjacent to at least one of $x_1, \ldots, x_k$. As usual, $P_4$ denotes a path on four vertices.) The proof of the theorem in [3, 4] is a polytime algorithm which for any graph and any vertex in that graph, finds an instance of what the theorem says exists. In Section 5 we give an $O(n^3)$ algorithm for this, where $n$ is the number of vertices of the input graph.

2 The coloring algorithm

We recall the algorithm LexColor of Roussel and Rusu [14] which is a $O(n^2)$ algorithm that colors optimally the vertices of a Meyniel graph, thereby improving the complexity of previous coloring algorithms due to Hertz $O(nm)$ [7] (where $m$ is the number of edges of the input graph), Hoàng $O(n^8)$ [8] and Ravindra [12].

LexColor is a greedy coloring algorithm. The integers $1, 2, \ldots, n$ are viewed as colors. For each vertex $x$ of $G$ and each color $c \in \{1, 2, \ldots, n\}$, we have a label $\text{label}_x(c)$ defined as follows. If $x$ has no neighbor colored $c$, then $\text{label}_x(c)$ is equal to 0; if $x$ has a neighbor colored $c$, then $\text{label}_x(c)$ is equal to the integer $i$ such that the first neighbor of $x$ colored $c$ is the $(n-i)$-th colored vertex of the graph. We consider the following (reverse) lexicographic order on the labels : $\text{label}_x <_{\text{Lex}} \text{label}_y$ if and only if there exists a color $c$ such that $\text{label}_x(c) < \text{label}_y(c)$ and $\forall c' > c$, $\text{label}_x(c') = \text{label}_y(c')$. At each step, the algorithm selects an uncolored vertex which is maximum for the lexicographic order of the labels, assigns to this vertex the smallest color not present in its neighbourhood, and iterates this procedure until every vertex is colored. More formally:
Algorithm LexColor

Input: A graph $G$ with $n$ vertices.
Output: A coloring of the vertices of $G$.
Initialization: For every vertex $x$ of $G$ and every color $c$ do $\text{label}_x(c) := 0$;
General step: For $i = 1, \ldots, n$ do:
1. Choose an uncolored vertex $x$ that maximizes $\text{label}_x$ for $<_{\text{Lex}}$;
2. Color $x$ with the smallest color $c$ not present in its neighborhood;
3. For every uncolored neighbor $y$ of $x$, if $\text{label}_y(c) := 0$ do $\text{label}_y(c) := n - i$.

This coloring algorithm is optimal on Meyniel graph and its complexity is $O(n^2)$ [14].

Remark 1: This version of LexColor has a minor modification from the original version of Roussel and Rusu [14]. When $x$ has a neighbor colored $c$, the integer $\text{label}_x(c)$ was originally defined to be the integer $i$ such that the first neighbor of $x$ colored $c$ is the $(n - i)$-th vertex colored $c$ of the graph (instead of the $(n - i)$-th colored vertex of the graph). For a color $c$, the order between $\text{label}_x(c)$ of each vertex $x$ is the same in the two versions of the algorithm, so the lexicographic order is the same and there is no difference in the two executions of the algorithm. This modification only simplifies the description of the algorithm.

Remark 2: The graph $P_6$ is an example of a non-Meyniel graph on which Algorithm LexColor is not optimal. The graph $P_6$ has vertices $u, v, w, x, y, z$ and non-edges are $uv, vw, wx, xy, yz$. Algorithm LexColor can color the vertices in the following order with the indicated color: $v - 1, y - 2, w - 1, u - 3, x - 2, z - 4$; but the graph has chromatic number 3. Since $P_6$ is a member of many families of perfect graphs (such as brittle graphs, weakly chordal graphs, perfectly orderable graphs, etc; see [11] for the definitions), this algorithm will not perform optimally on these classes.

3 Finding a maximum clique

Given a coloring of a graph, there is a greedy algorithm that chooses one vertex of each color in an attempt to find a clique of the same size.
Algorithm Clique

Input: A graph $G$ and a coloring of its vertices using $\ell$ colors.
Output: A set $Q$ that consists of $\ell$ vertices of $G$.
Initialization: Set $Q := \emptyset$;
General step: For $c = \ell, \ldots, 1$ do:
Select a vertex $x$ of color $c$ that maximizes $N(x) \cap Q$, do $Q := Q \cup \{x\}$.

Algorithm Clique can be implemented in time $O(m + n)$.

We claim that when the input consists of a Meyniel graph $G$ with the coloring produced by LexColor, then the output $Q$ of Algorithm Clique is a clique of size $\ell$. This result is a consequence of the next section, we show that when the output of the algorithm is not a clique, we can find a Meyniel obstruction.

4 Finding a Meyniel obstruction

Let $G$ be a general (not necessarily Meyniel) graph on which Algorithm LexColor is applied. Let $\ell$ be the total number of colors used by the algorithm. Then we apply Algorithm Clique. At each step, we check whether the selected vertex $x$ of color $c$ is adjacent to all of $Q$ (this can be done without increasing the complexity of Algorithm Clique by maintaining a counter which for each vertex counts the number of its neighbors in $Q$). If this holds at every step, then the final $Q$ is a clique of cardinality $\ell$, and so we have a clique and a coloring of the same size, which proves the optimality of both. If not, then Algorithm Clique stops the first time $Q \cup \{x\}$ is not a clique and records the current color $c$ and the current clique $Q$. So we know that no vertex colored $c$ is adjacent to all of $Q$. Let us show now how to find a Meyniel obstruction in $G$. As usual, a path is called odd or even if its length (number of edges) is respectively odd or even.

Let $n_c$ be the number of vertices colored $c$, and for $i = 1, \ldots, n_c$ let $x_i$ be the $i$-th vertex colored $c$. Let $G^*$ be the subgraph of $G$ obtained by removing the vertices of colors $< c$. Let $G^*_i$ be the graph obtained from $G^*$ by removing $x_1, \ldots, x_i$ and adding a new vertex $w_i$ with an edge to every vertex that is adjacent to one of $x_1, \ldots, x_i$ (in other words, vertices $x_1, \ldots, x_i$ are contracted into $w_i$).

Let $h \leq n_c$ be the smallest integer such that every vertex of color $> c$ has a neighbor in $\{x_1, \ldots, x_h\}$. Integer $h$ exists because $n_c$ has that property.
There is a vertex $a$ of $Q$ that is not adjacent to $x_h$, because $x_h$ is not adjacent to all of $Q$. Thus $h \geq 2$. Note that $a$ is adjacent to $w_{h-1}$ in $G^*_{h-1}$. There is a vertex $b$ of $Q$ that is adjacent to $x_h$ and not to $w_{h-1}$, by the definition of $h$. Then $w_{h-1} - a - b - x_h$ is a chordless odd path in $G^*_{h-1}$.

For any $i > 1$, a bad path is any odd path $P = w_{i-1} - v_1 - \cdots - v_p$ in $G^*_i$ such that $v_p = x_i$, path $P$ has at most one chord, and such a chord (if any) is $v_{t-1}v_{t+1}$ with $1 < t < p - 1$. Note that the path $w_{h-1} - a - b - x_h$ obtained at the end of the preceding paragraph is a bad path.

A near-obstruction in $G$ is any pair $(P, z)$, where $P$ is a path $v_0 - \cdots - v_p$, with odd $p \geq 3$, $P$ has at most one chord, such a chord (if any) is $v_{t-1}v_{t+1}$ with $0 < t < p - 1$, vertex $z$ is a vertex of $G \setminus P$ that is adjacent to both $v_0, v_p$, and the pair $(P, z)$ satisfies one of the following conditions:

Type 1: $v_0v_2$ is the only chord of $P$, and $z$ is not adjacent to either of $v_1, v_2$.
Type 2: $v_1v_3$ is the only chord of $P$, and $z$ is not adjacent to one of $v_1, v_3$.
Type 3: $v_0v_2$ is not a chord of $P$, and $z$ is not adjacent to $v_1$.
Type 4: $v_0v_2$ and $v_1v_3$ are not chords of $P$, and $z$ is adjacent to $v_1$ and not to $v_2$.

The following lemmas show that the existence of a bad path is a certificate that the graph is not Meyniel. The proof of the first lemma can easily be read as a linear-time algorithm which, given a bad path, finds explicitly a near-obstruction. Likewise, the proof of the second lemma can easily be read as a linear-time algorithm which, given a near-obstruction, finds explicitly an obstruction. Since $G^*_{h-1}$ contains the bad path $w_{h-1} - a - b - x_h$, these two lemmas imply that $G$ contains a Meyniel obstruction.

**Lemma 1** If $G^*_i$ contains a bad path, then $G$ contains a near-obstruction.

**Lemma 2** If $G$ has a near-obstruction $(P, z)$, then $G$ has a Meyniel obstruction contained in the subgraph induced by $P \cup \{z\}$.

**Proof of Lemma 2.** Let $P = w_{i-1} - v_1 - \cdots - v_p$ be a bad path in $G^*_i$, with the same notation as above. We prove the lemma by induction on $i$. We first claim that:

(*) There exists a vertex $z$, colored before $x_i$ with a color $> c$, that is adjacent to $x_i$ and to $w_{i-1}$ in $G^*_i$ and satisfies the following property. If $v_1v_3$ is the chord of $P$, then $z$ is not adjacent to at least one of $v_1$ and $v_3$. If $v_1v_3$ is not a chord of $P$, then $z$ is not adjacent to at least one of $v_1$ and $v_2$. 

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For let us consider the situation when the algorithm selects \( x_i \) to be colored. Let \( U \) be the set of vertices of \( G^*_i \) that are already colored at that moment. We know that every vertex of \( G^*_i \) will have a color from \( \{ c, c + 1, \ldots, \ell \} \) when the algorithm terminates. So, if \( c \geq 2 \), every vertex \( v \) of \( U \) satisfies \( \forall \ c' < c, \ label_v(c') \neq 0 \). For any \( X \subseteq U \), let \( \text{color}(X) \) be the set of colors of the vertices of \( X \). Put \( T = N(x_i) \cap U \). Every vertex of \( T \) has a color \( \geq c + 1 \), and so is adjacent to at least one vertex colored \( c \) in \( G \) and thus is adjacent to \( w_{i-1} \) in \( G^*_i \). Specify one vertex \( v_r \) of \( T \) as follows: put \( r = 3 \) if \( v_1v_3 \) is a chord of \( P \); else put \( r = 2 \). Note that \( v_r \) is not adjacent to \( w_{i-1} \) and \( v_r \neq x_i \) by the definition of bad path. Suppose the claim is false: so every vertex of \( T \) is adjacent to \( v_1 \) and \( v_r \).

Since every vertex of \( T \) is adjacent to \( v_1 \), we have \( \text{label}_{v_1}(c') \geq \text{label}_{x_i}(c') \) for every color \( c' > c \). Since \( v_1 \) is adjacent to \( w_{i-1} \), we have \( \text{label}_{v_1}(c) > 0 \). Since \( x_i \) is colored \( c \), we have \( \text{label}_{x_i}(c) = 0 \). So \( \text{label}_{v_1} > \text{Lex label}_{x_i} \), which means that \( v_1 \) is already colored. Moreover, \( \text{color}(v_1) \notin \{ 1, \ldots, \ell \} \cup \text{color}(T) \).

Since every vertex of \( T \) is adjacent to \( v_r \), we have \( \text{label}_{v_r}(c') \geq \text{label}_{x_i}(c') \) for every color \( c' > c \). Since \( v_r \) is adjacent to \( v_1 \), we have \( \text{label}_{v_r}(\text{color}(v_1)) > 0 \). Since \( \text{color}(v_1) \notin \{ 1, \ldots, \ell \} \cup \text{color}(T) \) we have \( \text{label}_{x_i}(\text{color}(v_1)) = 0 \). So \( \text{label}_{v_r} > \text{Lex label}_{x_i} \), which means that \( v_r \) is already colored. However, \( v_r \) is not adjacent to \( w_{i-1} \), so \( c \) was the smallest color available for \( v_r \) when it was colored, which contradicts the definition of \( w_{i-1} \) and \( x_i \). This completes the proof of Claim (*)

Now let \( z \) be a vertex given by Claim (*). (It takes time \( \text{deg}(x_i) \) to find such a vertex \( z \).)

Let \( j \) be the smallest integer such that both \( v_1 \) and \( z \) have a neighbor in \( \{ x_1, \ldots, x_j \} \). Then \( j < i \) because \( z \) and \( v_1 \) are adjacent to \( w_{i-1} \).

Suppose that \( x_j \) is adjacent to both \( v_1 \) and \( z \). Then \( (x_j, v_{1}, \ldots, v_{p}, z) \) is a near-obstruction in \( G \). Indeed, by Claim (*), it is a near-obstruction of Type 2 if \( v_1v_3 \) is the chord of \( P \), of Type 3 if \( v_1v_3 \) is not a chord of \( P \) and \( z \) is not adjacent to \( v_1 \), or of Type 4 if \( v_1v_3 \) is a chord of \( P \) and \( z \) is adjacent to \( v_1 \) (and thus is not adjacent to \( v_2 \)).

Now suppose that \( x_j \) is not adjacent to both \( v_1 \) and \( z \). Then the definition of \( j \) implies that \( j > 1 \) and either (a) \( z \) is adjacent to \( x_j \) and not to \( w_{j-1} \), and \( v_1 \) is adjacent to \( w_{j-1} \) and not to \( x_j \) or (b) \( v_1 \) is adjacent to \( x_j \) and not to \( w_{j-1} \), and \( z \) is adjacent to \( w_{j-1} \) and not to \( x_j \). In either case, let \( k \) be the smallest integer with \( k \geq 1 \) such that \( z \) is adjacent to \( v_k \). Such a \( k \) exists because \( z \) is adjacent to \( v_p \).

Suppose that \( k \) is odd. If (a) holds, then let \( P' = w_{j-1}v_{1}\cdots v_{k}zx_{j} \); if (b) holds, let \( P' = w_{j-1}zv_{k}\cdots v_{1}x_{j} \). Then \( P' \) has at most one chord, which is the chord of \( P \) if it exists and if its two end-vertices are in \( P' \), so
$P'$ is a bad path in $G^*_{j-1}$, and the result follows by induction.

Now suppose that $k$ is even. Then $k < p$ since $p$ is odd. We consider the following cases:

Case 1: $P$ has a chord $v_{t-1}v_{t+1}$ with $t < k$. If (a) holds, then let $P' = w_{j-1}v_1\cdots v_{t-1}v_{t+1}v_k\cdots v_{x_j}$; if (b) holds, let $P' = w_{j-1}zv_k\cdots v_{t+1}v_{t-1}\cdots v_1x_j$. Then $P'$ is chordless, so $P'$ is a bad path in $G^*_{j-1}$, and the result follows by induction.

Case 2: $P$ has a chord $v_kv_{k+1}$. When $z$ is adjacent to both $v_{k+1}$ and $v_{k+2}$, if (a) holds, then let $P' = w_{j-1}v_1\cdots v_{k-1}v_{k+1}\cdots v_{k+2}\cdots v_1x_j$; if (b) holds, let $P' = w_{j-1}zv_k\cdots v_{k+1}v_{k+2}\cdots v_1x_j$; in either case, $P'$ has only one chord, which is $zv_k$, so $P'$ is a bad path in $G^*_{j-1}$, and the result follows by induction. When $z$ is not adjacent to $v_{k+1}$, then $v_k\cdots v_p$ is a chordless path, so $(v_k\cdots v_p, z)$ is a near-obstruction of Type 3. When $z$ is adjacent to $v_{k+1}$ and is not adjacent to $v_{k+2}$, then $v_k\cdots v_p$ is a chordless path, so $(v_k\cdots v_p, z)$ is a near-obstruction of Type 4.

Case 3: $P$ has a chord $v_kv_{k+2}$. When $z$ is adjacent to $v_{k+1}$, if (a) holds, then let $P' = w_{j-1}v_1\cdots v_{k-1}v_{k+1}\cdots v_{k+2}\cdots v_1x_j$; if (b) holds, let $P' = w_{j-1}zv_k\cdots v_{k+1}v_{k}\cdots v_1x_j$; in either case, $P'$ has only one chord, which is $zv_k$, so $P'$ is a bad path in $G^*_{j-1}$, and the result follows by induction. When $z$ is not adjacent to $v_{k+1}$ and is adjacent to $v_{k+2}$, if (a) holds, then let $P' = w_{j-1}v_1\cdots v_{k-1}v_{k+1}\cdots v_{k+2}\cdots v_1x_j$; if (b) holds, let $P' = w_{j-1}zv_{k+2}v_k\cdots v_1x_j$; in either case, $P'$ has only one chord, which is $zv_k$, so $P'$ is a bad path in $G^*_{j-1}$, and the result follows by induction. When $z$ is not adjacent to $v_{k+1}$ or to $v_{k+2}$, then $(v_k\cdots v_p, z)$ is a near-obstruction of Type 1.

Case 4: $P$ has no chord $v_{t-1}v_{t+1}$ with $t \leq k + 1$. When $z$ is adjacent to $v_{k+1}$, if (a) holds, then let $P' = w_{j-1}v_1\cdots v_{k-1}v_{k+1}\cdots zv_{x_j}$; if (b) holds, let $P' = w_{j-1}zv_k\cdots v_{k+1}\cdots v_1x_j$; in either case, $P'$ has only one chord, which is $zv_k$, so $P'$ is a bad path in $G^*_{j-1}$, and the result follows by induction. When $z$ is not adjacent to $v_{k+1}$, then $v_k\cdots v_p$ has at most one chord, which is the chord of $P$ if it exists and if its two end-vertices are in $P'$, so $(v_k\cdots v_p, z)$ is a near-obstruction of Type 3. This completes the proof of the last case. □

Let us discuss the complexity of the algorithmic variant of this proof. When we find a new bad path, the value of $i$ decreases by at least 1, and so this happens at most $n_c$ times. Dealing with one bad path takes time $O(deg(x_i) + deg(z))$ (for the corresponding $i$), and $x_i$ is different at each call since $i$ decreases. Vertex $z$ is also different at each call, because $z$ becomes a vertex of the new bad path. When the algorithm produces a new bad path to be examined, it also tells if the path has no chord or one chord, and what the chord is (if it exists); so we do not have to spend any time to find this
chord. So the total complexity of this algorithm is $O(m + n)$.

**Proof of Lemma 2.** We use the same notation for $P$ as above. We prove the lemma by induction on $p$. If $p = 3$, then the hypothesis implies immediately that $P \cup \{z\}$ induces an obstruction. Now let $p \geq 5$. If $(P, z)$ is a near-obstruction of Type 1, 2 or 3, then let $r$ be the smallest integer $\geq 1$ such that $z$ is adjacent to $v_r$. If $(P, z)$ is of Type 4, then let $r$ be the smallest integer $\geq 3$ such that $z$ is adjacent to $v_r$.

First assume that $(P, z)$ is a near-obstruction of Type 1. So $r \geq 3$. If $r$ is odd, then $z, v_0, \ldots, v_r$ induce an odd cycle with only one chord $v_0v_2$. If $r$ is even, then $z, v_0, v_2, \ldots, v_r$ induce an odd hole.

Now assume that $(P, z)$ is a near-obstruction of Type 2.

**Case 2.1:** $z$ is not adjacent to either of $v_1, v_2$. So $r \geq 3$. If $r$ is odd, then $z, v_0, \ldots, v_r$ induce an odd cycle with only one chord $v_1v_3$. If $r$ is even, then $r \geq 4$, and $z, v_0, v_1, v_3, \ldots, v_r$ induce an odd hole.

**Case 2.2:** $z$ is not adjacent to $v_1$ and is adjacent to $v_2$. So $r = 2$. If $z$ is not adjacent to $v_3$, then $z, v_0, v_1, v_3, v_2$ induce an odd cycle with only one chord $v_1v_2$. So suppose $z$ is adjacent to $v_3$. If $z$ is also adjacent to $v_4$, then $z, v_0, v_1, v_3, v_4$ induce an odd cycle with only one chord $v_3v_5$. If $z$ is not adjacent to $v_4$, then $p \geq 5$. Consider the path $P' = v_2 \cdots v_p$. Then $P'$ is chordless and $|P'| = |P| - r$, so $(P', z)$ is a near-obstruction of Type 4, and the result follows by induction.

**Case 2.3:** $z$ is adjacent to $v_1$. So $r = 1$, $z$ is not adjacent to $v_3$ by the definition of Type 2, and so $p \geq 5$. Consider the path $P' = v_1v_3 \cdots v_p$. Then $P'$ is chordless and $|P'| = |P| - r - 1$, so $(P', z)$ is a near-obstruction of Type 3, and the result follows by induction.

Now assume that $(P, z)$ is a near-obstruction of Type 3. If $r$ is odd, then $z, v_0, \ldots, v_r$ induce an odd cycle with at most one chord. If $r$ is even, we consider the following cases:

**Case 3.1:** $P$ has a chord $v_{t-1}v_{t+1}$ with $t < r$. Then $z, v_0, \ldots, v_{t-1}, v_{t+1}, \ldots, v_r$ induce an odd hole.

**Case 3.2:** $P$ has a chord $v_{r-1}v_{r+1}$. If $z$ is not adjacent to $v_{r+1}$, then $z, v_0, \ldots, v_{r-1}, v_{r+1}, v_r$ in this order induce an odd cycle with only one chord $v_{r-1}v_r$. So suppose $z$ is adjacent to $v_{r+1}$. If $z$ is also adjacent to $v_{r+2}$, then $z, v_0, \ldots, v_{r-1}, v_{r+1}, v_{r+2}$ induce an odd cycle with only one chord $zv_{r+1}$. If $z$ is not adjacent to $v_{r+2}$, then $p \geq r + 3$. Consider the path $P' = v_r \cdots v_p$. Then $P'$ is chordless and $|P'| = |P| - r$, so $(P', z)$ is a near-obstruction of Type 4, and the result follows by induction.

**Case 3.3:** $P$ has a chord $v_rv_{r+2}$. If $z$ is adjacent to $v_{r+1}$, then $z, v_0, \ldots, v_{r+1}$ induce an odd cycle with only one chord $zv_r$. So suppose $z$ is not
adjacent to \( v_{r+1} \). If \( z \) is adjacent to \( v_{r+2} \), then \( z, v_0, \ldots, v_r, v_{r+2} \) induce an odd cycle with only one chord \( zv_r \). If \( z \) is not adjacent to \( v_{r+2} \), then \( p \geq r + 3 \). Consider the path \( P' = v_r \cdots v_p \). Then \( v_r v_{r+2} \) is the unique chord of \( P' \) and \( |P'| = |P| - r \), so \( (P', z) \) is a near-obstruction of Type 1, and the result follows by induction.

Case 3.4: \( P \) has no chord \( v_{t-1}v_{t+1} \) with \( t \leq r + 1 \). If \( z \) is adjacent to \( v_{r+1} \), then \( z, v_0, \ldots, v_{r+1} \) induce an odd cycle with only one chord \( zv_r \). If \( z \) is not adjacent to \( v_{r+1} \), then consider the path \( P' = v_r \cdots v_p \). Then \( P' \) has at most one chord, which is the chord of \( P \) (if it exists) and \( |P'| = |P| - r \), so \( (P', z) \) is a near-obstruction of Type 3, and the result follows by induction.

Now assume that \( (P, z) \) is a near-obstruction of Type 4.

Suppose that \( P \) has a chord \( v_{t-1}v_{t+1} \) with \( 2 < t < r \). If \( r \) is odd, then \( z, v_1, \ldots, v_{t-1}, v_{t+1}, \ldots, v_r \) induce an odd hole. If \( r \) is even, then \( z, v_1, \ldots, v_r \) induce an odd cycle with only one chord \( v_{t-1}v_{t+1} \).

Now \( P \) has no chord \( v_{t-1}v_{t+1} \) with \( 2 < t < r \). If \( r \) is odd, then \( z, v_1, \ldots, v_r \) induce an odd cycle with only one chord \( zv_1 \). If \( r \) is even, then \( z, v_1, \ldots, v_r \) induce an odd hole. This completes the proof of the four cases.

In the algorithmic variant of this proof, each recursive call happens with the same vertex \( z \), so we need only run once through the adjacency array of \( z \). Note that the first near-obstruction is produced by the algorithm of Lemma 11 so we already know if \( P \) has no chord or one chord, and what its chord is, if it exists. Computing the value of \( r \) takes time \( O(r) \), and the rest of each call takes constant time. At each call, either a Meyniel obstruction is output, or a near-obstruction \( (P', z) \) is obtained. Note that \( |P'| \leq |P| - r \), and we know if \( P' \) has no chord or one chord, and what its unique chord is (if it exists); so we do not have to spend any time to find this chord. So the total running time is \( O(|P| + \text{deg}_P(z)) \).

Algorithms LexColor and Clique run in time \( O(n^2) \) and \( O(n + m) \) respectively, so the total time for finding, in any graph, either a clique and coloring of the same size, or a Meyniel obstruction is \( O(n^2) \).

Remark: As mentioned earlier, on the graph \( \overline{P}_6 \) with vertices \( u, v, w, x, y, z \) and non-edges \( uv, vw, wx, xy, yz \), a possible execution of LexBFS colors the vertices in the following order and with the given color: \( v - 1, y - 2, w - 1, u - 3, x - 2, z - 4 \). On this coloring, Algorithm Clique will stop when \( c = 1 \) and \( Q = \{x, u, z\} \). No vertex of color 1 is adjacent to all \( Q \) : \( w \) is not adjacent to \( x \) and \( v \) is not adjacent to \( u \). So \( w-u-x-v \) is a chordless path of length 3 between \( w \) and \( v \). Vertex \( w \) was colored before \( x \) because of \( y \), which is not adjacent to \( x \), and \( \{w, u, x, v, y\} \) induces a Meyniel
obstruction.

5 Strong stable sets

It can be proved that, in the case of a Meyniel graph, the set of vertices colored 1 by Algorithm LexColor is a strong stable set. But there are non-Meyniel graphs for which Algorithm LexColor and Algorithm Clique give a coloring and a clique of the same size but none of the color classes of the coloring is a strong stable set (see the example at the end of this section). In that case we would like to be able to find a Meyniel obstruction. This can be done in time $O(n^3)$ as described below.

Lemma 3 Every nice stable set is a strong stable set.

Proof. Let $S = \{x_1, \ldots, x_k\}$ be a nice stable set of a graph $G$. Suppose there exists a maximal clique $Q$ with $Q \cap S = \emptyset$. Let $G'$ be the graph obtained from $G$ by contracting $x_1, \ldots, x_i$ into $w_i$. For $i = 1, \ldots, k$, consider the following Property $P^i$: “In the graph $G'$, vertex $w_i$ is adjacent to all of $Q$.” Note that Property $P^k$ holds by the maximality of $S$ and by the definition of $w_k$ and that Property $P^1$ does not hold by the maximality of $Q$. So there is an integer $i \in \{2, \ldots, k\}$ such that $P^i$ holds and $P^{i-1}$ does not. Vertex $x_i$ is not adjacent to all of $Q$ by the maximality of $Q$. So, in the graph $G^{i-1}$, the clique $Q$ contains vertices $a$ and $b$ such that $a$ is adjacent to $w_{i-1}$ and not to $x_i$ and $b$ is adjacent to $x_i$ and not to $w_{i-1}$, and then the path $w_{i-1}-a-b-x_i$ is a $P_4$, which contradicts the property that $S$ is nice. \qed

Now, for any graph $G$ and any vertex $v$ of $G$, we can find a Meyniel obstruction or a strong stable set containing $v$ by the following algorithm:

Apply the algorithm LexColor on a graph $G$, choosing $v$ to be the first vertex to be colored. Let $S = \{s_1, \ldots, s_{n_1}\}$ be the set of vertices colored 1. So $S$ is a maximal stable set. We can check in time $O(n^3)$ whether $S$ is a nice stable set. If $S$ is a nice stable set, then $S$ is a strong stable set by Lemma 3. If $S$ is not a nice stable set, then the checking procedure returns some $i \in \{2, \ldots, n_1\}$ such that there is an induced path $t_{i-1}-a-b-s_i$, where $t_{i-1}$ is the vertex obtained by contracting $s_1, \ldots, s_{i-1}$. Applying the procedure described in Lemmas 1 and 2 of Section 4 to this bad path $t_{i-1}-a-b-s_i$ gives a Meyniel obstruction in $G$.

Remark: Here is an example of a non-Meyniel graph for which Algorithm LexColor followed by Algorithm Clique can give a coloring and a clique
of the same size but none of the color classes of the coloring is a strong stable
set. Consider the graph $G$ form by the 3 triangles \{a, d, e\}, \{b, f, g\}, \{c, h, i\}
plus the edges $af$, $ah$, $bd$, $bi$, $ce$, $cg$. Algorithm LexColor can color the
vertices in the following order and with the given color: $d - 1$, $b - 2$, $f - 1$,
$g - 3$, $c - 1$, $i - 3$, $h - 2$, $a - 3$, $e - 2$, and Algorithm Clique returns the
clique \{a, d, e\}. The algorithms give a coloring and a clique of the same size
but none of the color classes \{c, d, f\}, \{b, e, h\} or \{a, g, i\} is a strong stable
set.

6 Comments

The algorithms presented here are not recognition algorithms for Meyniel
graphs. It can happen that the input graph is not Meyniel and yet the
output is a clique and a coloring of the same size.

The fastest known recognition algorithm for Meyniel graph is due to
Roussel and Rusu \[13\] and its complexity is $O(m(m + n))$, (where $n$ is
the number of vertices and $m$ is the number of edges), which beats the
complexity of the algorithm of Burlet and Fonlupt \[1\]. So it appears to
be easier to solve the Meyniel Graph Robust Algorithm Problem than to
recognize Meyniel graphs. It could be the same for perfect graphs: it might
be simpler to solve the Perfect Graph Robust Algorithm Problem than to
recognize perfect graphs. Currently, the recognition of perfect graphs is
done by an $O(n^9)$ algorithm due to Chudnovsky, Cornuőjols, Liu, Seymour
and Vušković \[5\] which actually recognizes Berge graphs (graphs that do
not contain an odd hole or an odd antihole). The class of Berge graphs is
exactly the class of perfect graphs by the Strong Perfect Graph Theorem of
Chudnovsky, Robertson, Seymour and Thomas \[6\].

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