FRONT FLUCTUATIONS FOR THE STOCHASTIC CAHN-HILLIARD EQUATION

LORENZO BERTINI, STELLA BRASSESCO, AND PAOLO BUTTÀ

ABSTRACT. We consider the Cahn-Hilliard equation in one space dimension, perturbed by the derivative of a space and time white noise of intensity $\varepsilon^2$, and we investigate the effect of the noise, as $\varepsilon \to 0$, on the solutions when the initial condition is a front that separates the two stable phases. We prove that, given $\gamma < \frac{2}{3}$, with probability going to one as $\varepsilon \to 0$, the solution remains close to a front for times of the order of $\varepsilon^{-\gamma}$, and we study the fluctuations of the front in this time scaling. They are given by a one dimensional continuous process, self similar of order $\frac{1}{4}$ and non Markovian, related to a fractional Brownian motion and for which a couple of representations are given.

1. Introduction

The kinematics of phase segregation for binary alloys can be described by the Cahn-Hilliard equation [14] [15] [13],

$$\partial_t u = -\Delta \left( \frac{1}{2} \Delta u - V'(u) \right),$$

(1.1)

where $\Delta$ is the Laplacian and $V: \mathbb{R} \to \mathbb{R}$ is a symmetric double well potential which, for the sake of concreteness, is chosen as

$$V(u) = \frac{1}{4} (u^2 - 1)^2.$$  

(1.2)

The scalar field $u = u(x, t)$ is an order parameter and represents the relative concentrations of the two species. The space homogeneous stationary solutions $u = \pm 1$ are to be interpreted as the pure phases of the alloy. In contrast with the Allen-Cahn flow [3], the evolution governed by (1.1) locally conserves the mass $\int dx u(x, t)$. Indeed, (1.1) can be viewed as the $H^{-1}$ gradient flow of the van der Waals free energy functional,

$$\int dx \left[ \frac{1}{4} |\nabla u|^2 + V(u) \right].$$

(1.3)

In particular, the critical points of (1.3) with mass conservation constraint are stationary solutions to (1.1). Moreover, when (1.1) is considered in a bounded domain, its solutions converge, apart from exceptional initial conditions, to a minimizer of (1.3) with the mass fixed by the initial datum.

2010 Mathematics Subject Classification. Primary 60H15, 35R60; secondary 82C24.

Key words and phrases. Cahn-Hilliard equation, interface dynamics.
and the yet unspecified boundary condition. By introducing an appropriate scaling parameter, the main issues from a heuristic point of view are the following ones. First, an early, relatively fast, stage of the dynamics (referred to as spinodal decomposition), in which the flow \((1.1)\) approaches to a critical point of \((1.3)\) by realizing a local separation of the pure phases \(\pm 1\). A later, slow, stage of the evolution toward the minimizer, taking place in a small neighborhood of the unstable manifold of the critical point.

Let us focus on the one dimensional case. For a bounded domain, a detailed analysis of the slow evolution of patterns of the rescaled Cahn-Hilliard equation is given in [2] and [6, 7]. More precisely, in a neighborhood of a stationary solution to \((1.1)\) having a given number of transition layers, the exponentially slow speed of the layer motion is determined. In addition, the existence of an unstable invariant manifold attracting solutions exponentially fast in the scaling parameter is established.

Analogous issues can be posed when the equation \((1.1)\) is considered on the whole line without scaling parameter. By interpreting \((1.3)\) as an action functional, it is easy to show that \((1.1)\) admits “droplet-shaped” stationary solutions, i.e., profiles of the form \(u_{\text{droplet}}(x) = g(x - x_0)\) with \(x_0 \in \mathbb{R}\) and \(g\) symmetric, monotone for \(x > 0\), and exponentially approaching its asymptotic value. The function \(g\) can be determined up to an arbitrary parameter which plays the role of the mass constraint. The linear stability of such stationary solutions is determined by the spectrum of the linearization of \((1.1)\) around \(u_{\text{droplet}}\). By translation invariance, zero is an eigenvalue, which is responsible for the exponentially small motion in finite but large domains [2, 6, 7]. Those results suggest that the remainder of the spectrum is bounded away from zero, but we are not aware if this has been proven.

Simpler stationary solutions are the “kink-shaped” profiles \(\bar{m}_{x_0}\), which describe a transition between the pure phases \(\pm 1\) at \(\pm \infty\) with “center” \(x_0 \in \mathbb{R}\). By translation invariance \(\bar{m}_{x_0}(x) = \bar{m}(x - x_0)\) with \(\bar{m} = \bar{m}_0\). For the specific choice \((1.2)\) of the potential, \(\bar{m}(x) = \tanh(x)\). Its linear stability has been analyzed in [12] and [21]. Again zero is a simple eigenvalue but, in contrast both to the droplet and to the kink for the Allen-Cahn dynamics, it is an accumulation point of the spectrum. Hence, the manifold

\[ \mathcal{M} = \{\bar{m}_{x_0}, x_0 \in \mathbb{R}\} \quad (1.4) \]

is not exponentially attracting for the Cahn-Hilliard flow. Sharp estimates on the actual rate of convergence are proven in [12] and [21]: roughly speaking, an initial datum close to \(\mathcal{M}\) relaxes to a front in \(\mathcal{M}\) with a diffusive behavior. We remark that this is due to the fact that the domain is unbounded.

Both from a conceptual and a modelling point of view, the addition of a small random forcing term to \((1.1)\) appears natural. Clearly, the random force should preserve the local mass and, under suitable assumptions, can be taken to be Gaussian. We thus consider the stochastic partial differential
equation,
\[ \partial_t u = -\Delta \left( \frac{1}{2} \Delta u - V'(u) \right) + \sqrt{\varepsilon} \nabla (a \varepsilon \dot{W}) \tag{1.5} \]
where \( \dot{W} \) is a space-time white noise, \( a \varepsilon \) is a convenient space cut-off, and \( \varepsilon > 0 \). In the framework of dynamical critical phenomena this is, with the choice (1.2), a model for the evolution with conserved order parameter (Model B in the review [20]). In spite of the short-scale singularity of the forcing term and of the unbounded domain, in the one dimensional case this equation has a meaningful mild formulation for suitable \( a \varepsilon \) (see the next section). We refer to the works [5, 16, 17] for existence results on stochastic perturbations of Cahn-Hilliard equation in bounded domains. The effect of the noise on the motion of the transition layers analyzed in the aforementioned works [2, 6, 7], is studied in [4]. It is there shown that the random fluctuations dominate the exponentially slow deterministic dynamics and an effective system of stochastic ordinary differential equations for the motion of the layers is derived.

The purpose of the present paper is to analyze the fluctuations of the kink profile \( \overline{m} \) due to the random noise in (1.5), in the limit \( \varepsilon \to 0 \). Let us first review the corresponding results for the stochastic non-conservative Allen-Cahn equation \( \partial_t u = \frac{1}{2} \Delta u - V'(u) + \sqrt{\varepsilon} \dot{W} \). If the initial datum is \( \overline{m} \), in [11, 12, 13], it is shown that the solution at times \( \varepsilon^{-1} t \) stays close to \( \overline{m} \zeta(t) \) for some random process \( \zeta(t) \) which converges to a Brownian motion as \( \varepsilon \to 0 \). To explain heuristically this result, let us regard the random forcing term as a source of independent small kicks, which we decompose along the directions parallel and orthogonal to \( M \). The orthogonal component is exponentially damped by the deterministic drift, while the parallel component, associated to the zero eigenvalue of the linearization around \( \overline{m} \zeta(t) \), is not contrasted and, by independence, sums up to a Brownian motion.

For the Cahn-Hilliard dynamics this picture has to be completely modified, taking into account the following two related effects. The local mass conservation, which implies that fluctuations of the interface center can occur only in infinite volume, as the extra mass has “to come from infinity”, and the absence of a spectral gap, which implies that perturbations in the direction orthogonal to \( M \) cannot be neglected. More precisely, the projection of the noise in the direction parallel to \( M \) vanishes, but its perpendicular component is not exponentially damped and gives rise, with a suitable delay, to the front fluctuations. On heuristic grounds, we expect that the increments of the resulting process are not independent but negatively correlated. Indeed, after a fluctuation in a given direction, the extra mass is reabsorbed, causing a successive fluctuation in the opposite direction. This mechanism is slower than that for the Allen-Cahn dynamics, and therefore a finite displacement of the interface should occur at times of the order \( \varepsilon^{-2} \). On the other hand, it is not at all clear whether the kink-like shape of the solution survives until so long times. If this is the case, as the limiting process is
anyway the sum of approximately Gaussian increments, we expect it to be a self-similar of order $\frac{1}{4}$, non-Markovian Gaussian process.

In this paper we show that, given $\gamma < \frac{2}{3}$, with probability going to 1 as $\varepsilon \to 0$, the solution to the equation (1.5) with initial condition $\overline{m}$ stays close to $\overline{m}Z_\varepsilon(t)$ up to times of order $\varepsilon^{-\gamma}$, and we describe the statistics of the kink fluctuations in this regime. More precisely, we prove that

$$u(\cdot, \varepsilon^{-\gamma} t) \approx \overline{m}Z_\varepsilon(t), \quad Z_\varepsilon(t) \approx \varepsilon^{\frac{1}{2}-\gamma}Z(t),$$

where the process $Z$ is the odd part of a two sided fractional Brownian motion with self-similarity parameter $\frac{1}{4}$, which is indeed a non-Markovian process, with negatively correlated increments. As previously remarked, the above result suggests that the order of the time needed to obtain a finite displacement of the front should be $\varepsilon^{-2}$, but the analysis required to reach this scaling is not clear.

Actually, the heuristic picture discussed before has been substantiated for the stochastic phase field equation [9]. In that case, due to the weak coupling between the order parameter and the phase field, there is a sharp separation between the instantaneous noise kicks and their delayed contribution to the front propagation; the analysis can thus be carried out up to the longer time scale.

We notice that, in contrast to the kink fluctuations, the picture describing the fluctuations of the droplet for (1.5) on the whole line should be analogous to that of the kink for the Allen-Cahn equation. In particular, the droplet fluctuations should become of order one at times $\varepsilon^{-1} t$ and converge to a Brownian motion, due to the fact that the mass conservation is not present here, and the droplet can move freely.

## 2. Notation and results

We consider, for each $\varepsilon > 0$, the process $u(x,t)$, $x \in \mathbb{R}$ and $t > 0$, solution to the initial value problem for the Cahn-Hilliard equation with a conservative stochastic perturbation,

$$\begin{align*}
\partial_t u &= -\partial_x^2 \left( \frac{1}{4} \partial_x^2 u - V'(u) \right) + \sqrt{\varepsilon} \nabla (a_\varepsilon \dot{W}), \\
u(x,0) &= u_0(x),
\end{align*}$$

(2.1)

where $\partial_j^x = \frac{\partial}{\partial x_j}$ ($j \in \mathbb{N}$), $V(u)$ as in (1.2), and $a_\varepsilon(x) = a(x \varepsilon^\beta)$, for $\beta > 2$ and $a$ a $C^\infty$ positive function with supp$(a) \subset [-1, 1]$, $a(0) = 1$, and $\|a\|_\infty = 1$. Finally, $\dot{W} = W_{x,t}$ is a space-time white noise, defined on a probability space $(\Omega, \mathcal{F}, \mathbb{P})$. The initial condition $u_0$ is taken close to the centered interface $\overline{m}(x) = \tanh(x)$.

The precise sense of the above equation is given by the integral equation obtained in terms of the Green function $G(x,y,t)$ corresponding to the
operator $e^{-\frac{2}{\varepsilon}t} \Delta^2$, where $\Delta^2 f = \partial_{x}^4 f$ when restricted to $f \in C^\infty$,

\begin{equation}
    u(x,t) = \int dy G(x,y,t) u_0(y)
    + \int_0^t ds \int dy \partial_y^2 G(x,y,t-s)V'(u(y,s)) + \sqrt{\varepsilon} Y(x,t).
\end{equation}

The last term above is the Gaussian process obtained formally as

\begin{equation}
    Y(x,t) = \int_0^t ds \int dy G(x,y,t-s) \partial_y (a_\varepsilon(y) \dot{W}_{y,s}).
\end{equation}

Precisely, $Y(x,t)$ is the centred Gaussian process with covariance,

\begin{equation}
    \mathbb{E}(Y(x,t)Y(x',t')) = \int_0^{t\wedge t'} ds \int dy \partial_y G(x,y,t-s) \partial_y G(x',y,t'-s) a_\varepsilon(y)^2.
\end{equation}

As usual, for $g \in L_2(\mathbb{R} \times [0,\infty))$, we denote $\dot{W}(g) = \int g(x,t) dW_{x,t}$, omitting the variables $x,t$ in the integral when clear otherwise. The elements in the space $\Omega$ will be denoted by $\omega$. We also consider the filtration,

$$
\mathfrak{F}_t = \sigma\{\dot{W}(A \times [0,t]) ; A \in \mathcal{B}(\mathbb{R})\}, \quad \mathcal{B}(\mathbb{R}) \text{ the Borel sets in } \mathbb{R}.
$$

In the sequel, we will denote by $C$ a generic positive constant, whose numerical value may change from line to line and from one side to the other in an inequality. The notation $a \wedge b$ ($a \vee b$) stands for the minimum (maximum) between the real numbers $a$ and $b$. Given $p \in [1,\infty]$, we let $\| \cdot \|_p$ be the norm in $L_p(\mathbb{R}, dx)$. We consider $C(\mathbb{R}_+)$ equipped with the (metrizable) topology of uniform convergence in compacts, and denote by $\Rightarrow$ weak convergence of processes in that space. Finally, to simplify the writing, we assume that the scaling parameter $\varepsilon \in (0,1)$.

Our main results are stated as follows.

**Theorem 2.1.** Given $0 < \gamma < \frac{2}{3}$ and $T > 0$, there exists a set $B(\varepsilon, \gamma, T) \in \mathfrak{F}$ such that $\mathbb{P}(B(\varepsilon, \gamma, T)) \rightarrow 1$ as $\varepsilon \rightarrow 0$, and, for $\omega \in B(\varepsilon, \gamma, T)$, the stochastic Cahn-Hilliard equation (2.1) with initial condition $\overline{m}$ has a unique bounded continuous solution $u(x,t)$, for $x \in \mathbb{R}$ and $t \leq \varepsilon^{-\gamma} T$. Moreover, there exists a one dimensional $\mathfrak{F}_t$-adapted process $\zeta_\varepsilon(t)$ such that

(i) For each $\eta > 0$,

$$
    \lim_{\varepsilon \rightarrow 0} \mathbb{P} \left( \sup_{t \leq \varepsilon^{-\gamma} T} \| u(\cdot,t) - \overline{m}_{\zeta_\varepsilon(t)} \|_{\infty} > \varepsilon^{(1-\gamma)\frac{2}{3} - \eta} \right) = 0.
$$

(ii) Consider the real process $X_\varepsilon(t) := \varepsilon^{-\frac{2}{3} + \frac{\gamma}{4}} \zeta_\varepsilon(\varepsilon^{-\gamma} t)$. Then,

$$
    X_\varepsilon(t) \Rightarrow (8\pi)^{\frac{1}{4}} r(t) \text{ as } \varepsilon \rightarrow 0,
$$

where $r(t)$ is the one dimensional centered Gaussian process with covariance,

\begin{equation}
    \mathbb{E}(r(t) r(t')) = \sqrt{t+t'} - \sqrt{t-t'}, \quad t \geq t'.
\end{equation}
Theorem 2.2. The one dimensional Gaussian process \( r(t) \) with covariance given by (2.4) is a continuous process, self-similar of order \( \frac{1}{4} \). It admits the following three representations, in terms of well known processes:

- Let \( \nu^{(H)}(t) \) be the usual two sided fractional Brownian motion with Hurst parameter \( H \), and \( \nu^{(H)}_O \) its odd part. Then,
  \[
  r(t) = 2 \nu^{(\frac{1}{4})}_O(t) .
  \]

- Let \( h(x,t) \) be the solution to the heat equation in \( \mathbb{R} \) with additive space-time white noise and initial condition \( 0 \). Then,
  \[
  r(t) = (2\pi)^{\frac{1}{4}} h(0,t) .
  \]

- Consider \( b(s) \) a standard Brownian motion. Then,
  \[
  r(t) = c \int_0^t \frac{s^{\frac{1}{4}}}{(t^2 - s^2)^{\frac{1}{4}}} \, \mathrm{d}b(s) .
  \]

where the constant \( c = (\frac{1}{2} B(\frac{3}{4}, \frac{3}{4}))^{-\frac{1}{2}} \), with \( B(\cdot, \cdot) \) the usual Euler beta function.

The paper is organized as follows. In the next section, we discuss the properties of the Gaussian process \( Y \), obtaining some \( \sup \)-norm estimates that allow to establish a local existence and uniqueness theorem for equation (2.2). In Section 4, we introduce a new integral equation, in terms of the kernel of the linearized equation around \( m \). With the aid of estimates for this kernel derived in [12], we obtain estimates that are used in Section 5 to show stability of the front in a convenient time-scaling. In Section 6 we study the Gaussian process \( H \) appearing in the linearization about the front under proper time scaling, and prove Theorem 2.1. Finally, Theorem 2.2 is proved in Section 7. Some technical proofs are reported in Appendix A.

3. Local existence and uniqueness of solutions

3.1. The process \( Y \). We investigate first the properties of the Gaussian process \( Y \), which are deduced from that of its covariance (2.3). In the next lemma, we provide some properties of the Green function \( G \) appearing in (2.2), that will be useful later.

Lemma 3.1. The Green function \( G(x,y,t) \) associated to \( e^{-\frac{1}{2} t \Delta} \) is given by

\[
G(x,y,t) = \frac{1}{t^{\frac{3}{4}}} \phi\left( \frac{x - y}{t^{\frac{1}{4}}} \right) , \quad \text{where} \quad \phi(x) = \frac{1}{2\pi} \int d\omega \, e^{-\frac{1}{2} \omega^2} e^{i\omega x} . \tag{3.1}
\]

Therefore,

\[
\partial_y G(x,y,t) = -\frac{1}{t^{\frac{3}{4}}} \phi'\left( \frac{x - y}{t^{\frac{1}{4}}} \right) , \quad \partial_y^2 G(x,y,t) = \frac{1}{t^{\frac{3}{4}}} \phi''\left( \frac{x - y}{t^{\frac{1}{4}}} \right) . \tag{3.2}
\]
Moreover, for each \( \lambda > 0 \) and nonnegative integer \( k \),

\[
\mathcal{c} = \mathcal{c}(\lambda, k) := \sup_{x \in \mathbb{R}} \left| e^{\lambda |x|} \frac{d^k \phi}{dx^k}(x) \right| < +\infty.
\]

(3.3)

Also, for any \( H > 0 \) and \( A \geq 1 \),

\[
\left| \frac{d^k \phi}{dx^k}(x + H) - \frac{d^k \phi}{dx^k}(x) \right| \leq CH \left( e^{-|x|} \mathbb{I}_{|x| > 2H} + \frac{1}{1 + H} \mathbb{I}_{|x| \leq 2H} \right),
\]

(3.4)

\[
\left| \frac{d^k \phi}{dx^k}(Ax) - \frac{d^k \phi}{dx^k}(x) \right| \leq C \frac{A - 1}{1 + (A - 1)|x|} |x| e^{-|x|} \leq \frac{A - 1}{A} e^{-|x|}.
\]

(3.5)

For the second derivative, we have also that

\[
|\phi''(x + H) - \phi''(x)| \leq C \frac{H^2 + H|x|}{1 + H^2 + H|x|}.
\]

(3.6)

**Proof.** The expression (3.1) follows by standard Fourier analysis. To prove (3.3), we observe that, as the entire function \( f(z) = \exp \left( \frac{1}{2}z^2 + iz \right) \) satisfies \( \max_{0 \leq y \leq 1} |f(\pm R + i\eta)| \to 0 \) as \( R \to \infty \), by Cauchy’s theorem we have

\[
\phi(x) = \frac{1}{2\pi} \int d\omega e^{-\frac{1}{2}(\omega + i\lambda)^4} e^{i(\omega + i\lambda)x},
\]

and hence

\[
\frac{d^k \phi}{dx^k}(x) = \frac{e^{-\lambda x}}{2\pi} \int d\omega (i\omega - \lambda)^k e^{-\frac{1}{2}(\omega + i\lambda)^4} e^{i\omega x}.
\]

As the integral on the right hand side is uniformly bounded in \( x \) for each \( \lambda \), the previous expression implies the bound (3.3) for \( x \geq 0 \), and then also for \( x < 0 \) as \( \phi \) is an even function.

The estimates (3.4) and (3.5) follow from (3.3) with \( \lambda = 2 \), as

\[
\left| \frac{d^k \phi}{dx^k}(x + H) - \frac{d^k \phi}{dx^k}(x) \right| \leq c \int_x^{x+H} dy e^{-2|y|} \leq \begin{cases} cHe^{-|x|} & \text{if } |x| > 2H, \\ c(H \wedge 1) & \text{if } |x| \leq 2H, \end{cases}
\]

and

\[
\left| \frac{d^k \phi}{dx^k}(Ax) - \frac{d^k \phi}{dx^k}(x) \right| \leq c \int_x^{Ax} dy e^{-2|y|} \leq c ((A - 1)|x| \wedge 1) e^{-|x|}
\]

(note that \( a \wedge 1 \leq 2a(1 + a)^{-1} \forall a \geq 0 \).

Finally, to prove (3.6), we consider the integral expression for \( \phi \) given in (3.1) and observe that

\[
|\cos(\omega x)(\cos(\omega H) - 1)| \leq \frac{(\omega H)^2}{2} \wedge 2, \quad |\sin(\omega x)\sin(\omega H)| \leq \omega^2 |x| H \wedge 1.
\]
Therefore,

\[ |\phi''(x + H) - \phi''(x)| = \frac{1}{2\pi} \left| \int d\omega e^{-\frac{1}{2}\omega^4} \omega^2 e^{i\omega x} (e^{i\omega H} - 1) \right| \]

\[ \leq \frac{1}{2\pi} \int d\omega e^{-\frac{1}{2}\omega^4} \omega^2 \left( |\cos(\omega x)\cos(\omega H) - 1| + |\sin(\omega x)\sin(\omega H)| \right) \]

\[ \leq C \int d\omega e^{-\frac{1}{2}\omega^4} \omega^2 \left[ (H^2\omega^2 + \omega^2|x|H) \wedge 1 \right] \leq C \left[ (H^2 + H|x|) \wedge 1 \right], \]

which proves (3.6) (using, as before, that \( a \wedge 1 \leq 2a(1 + a)^{-1} \forall a \geq 0 \)). □

The following proposition, whose proof is given in Appendix A, is a consequence of the estimates detailed in Lemma 3.1.

**Proposition 3.2.** Let \( Y(x, t) \) be the Gaussian process with covariance (2.3). Then, for any \( h > 0 \),

\[ \mathbb{E} Y(x, t)^2 \leq Ct^\frac{\gamma}{4}, \quad (3.7) \]

\[ \mathbb{E} (Y(x + h, t) - Y(x, t))^2 \leq Ch \log \left( 1 + h^{-1}t^\frac{1}{4} \right), \quad (3.8) \]

\[ \mathbb{E} (Y(x, t + h) - Y(x, t))^2 \leq Ch^\frac{1}{4}. \quad (3.9) \]

Using well known results for Gaussian processes, (3.8) and (3.9) imply Hölder continuity of the paths of \( Y(x, t) \) in both variables. From (3.7), it follows at once that \( Y(x, t) \in L^2(\mathbb{R} \times [0, T], d\mu) \) with probability one, for any \( T > 0 \) given, and \( \mu \) a finite measure on \( \mathbb{R} \times [0, T] \). The next results provide more precise global information on the paths, that will be useful in establishing uniqueness and existence of solutions to (2.2). Recall that, although not explicit in the notation, the process \( Y \) depends on \( \varepsilon \).

Let us define, for each positive \( \varepsilon \), \( \gamma \), and \( T \), the set

\[ \mathcal{T}_\varepsilon = \{(x, t) : x \in \mathbb{R}, \ t \in [0, T \varepsilon^{-\gamma}]\}. \quad (3.10) \]

**Proposition 3.3.** Consider the set \( \mathcal{T}_\varepsilon \) as defined in (3.10). Then the process \( Y(x, t) \) satisfies the following properties.

(i) For each \( \xi > 0 \) there exists a constant \( C > 0 \) such that, for any \( \varepsilon \in (0, 1) \),

\[ \mathbb{E} \sup_{(x, t) \in \mathcal{T}_\varepsilon} |Y(x, t)| < C\varepsilon^{-\frac{1}{2}-\xi}. \quad (3.11) \]

(ii) Given \( 0 < \gamma < 4 \),

\[ \mathbb{P} \left( \sup_{(x, t) \in \mathcal{T}_\varepsilon} \sqrt{\varepsilon} |Y(x, t)| < \infty \right) = 1. \quad (3.12) \]

(iii) Given \( 0 < \gamma < 4 \), for any \( 0 < \xi < \frac{4-\gamma}{16} \) there exist \( \zeta > 0 \) and a constant \( C > 0 \) such that,

\[ \mathbb{P} \left( \sup_{(x, t) \in \mathcal{T}_\varepsilon} \sqrt{\varepsilon} |Y(x, t)| > \varepsilon^\xi \right) \leq Ce^{-\varepsilon^\zeta}. \quad (3.13) \]
\textbf{Proof.} We first show that items (ii) and (iii) follow from item (i). Indeed, by (3.11) we have,
\[ \mathbb{E}\left( \sup_{(x,t) \in T_\varepsilon} \sqrt{\varepsilon} |Y(x,t)| \right) < \varepsilon^{\frac{4-n}{16}}, \]  
which implies (3.12). Next, from (3.7),
\[ \sigma_{T_\varepsilon}^2 := \sup \text{Var}(Y(x,t)) \leq C \varepsilon^{-\frac{2}{16}}, \]  
so that, from (3.14), (3.15), and Borell’s inequality [1],
\[ \mathbb{P}\left( \sup_{(x,t) \in T_\varepsilon} \sqrt{\varepsilon}|Y(x,t)| > \varepsilon^{\xi} \right) \leq 4 \exp \left( - \frac{(\varepsilon^{-\frac{1}{4}} + \varepsilon^{-\frac{1}{4}} + 4 \varepsilon^{\frac{2}{3}})^2}{2 \sigma_{T_\varepsilon}^2} \right), \]  
which implies (3.13).

We are left with the proof of item (i). Without loss of generality we can suppose $T = 1$ and $\varepsilon \in \left(0, \frac{1}{2}\right)$, what we do. Consider the pseudo-metric $d$ on $T_\varepsilon$ defined by
\[ d((x,t),(y,s)) = \left(\mathbb{E}(Y(x,t) - Y(y,s))^2\right)^{\frac{1}{2}}, \]
let $B_\delta(x,t)$ denote the $d$-ball of radius $\delta$ and center $(x,t)$, and $N(\delta)$ the minimum number of $d$-balls of radius $\delta$ needed to cover $T_\varepsilon$. From entropy estimates [1] we know that there is a universal positive constant $\kappa$ such that
\[ \mathbb{E}\sup_{(x,t) \in T_\varepsilon} |Y(x,t)| < \kappa \int_0^{\text{diam } T_\varepsilon} \text{d}\delta \left(\text{log } N(\delta)\right)^{\frac{1}{2}}. \]  
Recall that $Y(x,0) \equiv 0$. It follows from (3.7) that the diameter of $T_\varepsilon$ satisfies $\text{diam } T_\varepsilon \leq C_0 \varepsilon^{-\frac{2}{16}}$. To estimate $N(\delta)$ we let $R$ be a positive parameter, to be fixed later as a function of $\delta$ and $\varepsilon$. Proceeding as in (A.1), with the aid of (3.3) with $\lambda = 1$ and after recalling the definition of $a_\varepsilon$, if $|x| > \varepsilon^{-\beta} + R$ and $t \leq \varepsilon^{-\gamma}$, we have,
\[ \mathbb{E}Y(x,t)^2 \leq \int_0^t ds s^{-\frac{3}{2}} \int_{s^{-\frac{1}{4}}(x+\varepsilon^{-\beta})}^{s^{-\frac{1}{4}}(x+\varepsilon^{-\beta})} dy \phi'(y)^2 \leq \frac{\varepsilon}{2} \int_0^{\varepsilon^{-\gamma}} ds s^{-\frac{3}{2}} e^{-2s^{-\frac{1}{2}}R} \]  
\[ \leq \frac{\varepsilon R}{2} e^{-\varepsilon^{\frac{\gamma}{2}}} \int_0^{\varepsilon^{-4\varepsilon^{-\gamma}}} d\tau \tau^{\frac{3}{4}} e^{-\tau^{\frac{1}{4}}} \leq \frac{\varepsilon R}{2} e^{-\varepsilon^{\frac{\gamma}{2}}} C(R^{-1} \varepsilon^{-\frac{1}{2}}) \]  
\[ = C_1 \varepsilon^{-\frac{\gamma}{2}} e^{-\varepsilon^{\frac{\gamma}{2}}}, \]
with $C_1 > 0$.

Let $R$ be the unique non-negative solution to $C_1 \varepsilon^{-\frac{\gamma}{2}} e^{-\varepsilon^{\frac{\gamma}{2}}} = \delta^2$, which clearly exists if $\delta^2 \leq C_1 \varepsilon^{-\frac{\gamma}{2}}$, and it is
\[ R = \varepsilon^{-\frac{\gamma}{2}} \left| \log \frac{\delta^2 \varepsilon^{\frac{\gamma}{2}}}{C_1} \right| \]  
(3.18)
In particular, for each \( \delta \) such that \( \delta^2 < C_1 \varepsilon^{-\frac{3}{2}} \) and \( R \) as in (3.18), the set \( \mathcal{R}_1 = \mathcal{T}_\varepsilon \cap \{ x : |x| > \varepsilon^{-\beta} + R \} \) is contained in \( B_{\delta}(0,0) \), so it is covered with one ball of radius \( \delta \). If \( \delta^2 > C_1 \varepsilon^{-\frac{3}{2}} \), the corresponding set with \( R = 0 \) is covered by one ball of radius \( \delta \). Let us consider the rest of the parameter set, \( \mathcal{R}_2 = \mathcal{T}_\varepsilon \cap \{ x : |x| \leq \varepsilon^{-\beta} + R \} \). Let \( (x_0, t_0) \in \mathcal{R}_2 \), and denote by \( Q(x_0, t_0) = \{(x,t) : |x-x_0| \leq b, |t-t_0| \leq b^4 \} \) the rectangle of sides \( b \) and \( b^4 \) in the usual metric, for \( b \) that will be conveniently chosen. If \((x,t) \in Q(x_0, t_0) \cap \mathcal{T}_\varepsilon \), from (3.8) and (3.9) we get that,

\[
\mathbb{E}(Y(x,t)-Y(x_0, t_0))^2 \leq C(\log(1+|x-x_0|^{-1}|x^4|)+|t-t_0|^4)
\leq C(|x-x_0|\log(1+|x-x_0|^{-1})+|x-x_0|\log \varepsilon^{-1}+b)
\leq C_2 \log \varepsilon^{-1}(\sqrt{b} \mathbb{I}_{\{b \leq 1\}} + b \mathbb{I}_{\{b > 1\}}),
\]

with \( C_2 > 0 \) (recall we are assuming \( \varepsilon^{-1} \geq 2 \)). Then, choosing

\[
b = \left( \frac{\delta^2}{C_2 \log \varepsilon^{-1}} \right)^2 \mathbb{I}_{\{\delta^2 \leq C_2 \log \varepsilon^{-1}\}} + \frac{\delta^2}{C_2 \log \varepsilon^{-1}} \mathbb{I}_{\{\delta^2 > C_2 \log \varepsilon^{-1}\}},
\]

we obtain \( Q(x_0, t_0) \subset B_{\delta}(0,0) \). It is now clear that \( \mathcal{R}_2 \) is covered by \( b^{-5} \varepsilon^{-\gamma}(\varepsilon^{\beta} + R) \) rectangles (convenient translations of \( Q(x_0, t_0) \)). We conclude that \( N(\delta) \leq 1 + b^{-5} \varepsilon^{-\gamma}(\varepsilon^{\beta} + R) \). Then, noticing that (3.18) implies \( R \leq C \varepsilon^{-\frac{3}{4}} (|\log \varepsilon| + |\log \delta|) \), by (3.19) we get,

\[
N(\delta) \leq 1 + C \varepsilon^{-\gamma}(\varepsilon^{\beta} + \varepsilon^{-\frac{3}{2}} (|\log \varepsilon| + |\log \delta|))
\times \left( \left( \frac{C_2 \log \varepsilon^{-1}}{\delta^{20}} \right)^{10} \mathbb{I}_{\{\delta^2 \leq C_2 \log \varepsilon^{-1}\}} + \left( \frac{C_2 \log \varepsilon^{-1}}{\delta^{10}} \right)^{5} \mathbb{I}_{\{\delta^2 > C_2 \log \varepsilon^{-1}\}} \right).
\]

For \( \delta \leq \text{diam} \mathcal{T}_\varepsilon \leq C \varepsilon^{-\frac{2}{3}} \), the last estimate gives

\[
N(\delta) \leq 1 + C \varepsilon^{-A} \delta^{-21},
\]

with \( A > 0 \) sufficiently large. Substitution of this in (3.17) yields

\[
\int_0^{\text{diam} \mathcal{T}_\varepsilon} d\delta \left( \log N(\delta) \right)^{\frac{1}{2}} \leq \int_0^{C_0 \varepsilon^{-\frac{3}{4}}} d\delta \left( \log(1 + C \varepsilon^{-A} \delta^{-21}) \right)^{\frac{1}{2}}
\leq \frac{C_1 \varepsilon^{-\frac{3}{4}}}{21} \int_{C_0^{-21} \varepsilon^{\frac{20}{21}}}^{\infty} du \left( \log(1 + u) \right)^{\frac{1}{2}} u^{-\frac{22}{21}}
\]

\[
\leq C \varepsilon^{-\frac{3}{4} - A},
\]

where in the last inequality we estimated the integrand by \( u^{-\frac{22}{21} + \rho} \) with \( \rho \in (0, \frac{1}{21}) \). The estimate (3.11) now follows from (3.17) and (3.20) by choosing \( \rho < A^{-1} \xi \) for the given \( \xi \).

3.2. Existence and uniqueness of solutions. From the previous results, it is not difficult to prove the existence of a unique continuous solution to the integral equation (2.2) for \( t \leq T_0 \) if \( T_0 \) is small enough. To that end,
denote by $g$ and $G$ the following operators, defined in terms of the Green function $G$,
\[
g u_0(x,t) = \int dy \, G(x,y,t) u_0(y),
\]
\[
G F(x,t) = \int_0^t ds \int dy \, \partial_y^2 G(x,y,t-s) F(y,s).
\]
so that equation (2.2) reads,
\[
u = g u_0 + G(V'(u)) + \sqrt{\varepsilon} Y.
\]

Proposition 3.4. Given $u_0$ continuous, $\|u_0\|_\infty = M < \infty$, there exists a time $T_0$ (depending on $\|Y\|_\infty$ and on $M$) such that the equation (3.22) has a unique continuous bounded solution on $\mathbb{R} \times [0, T_0]$.

Proof. Denote $q = g u_0 + \sqrt{\varepsilon} Y$ and consider, for each $T > 0$ fixed, the set
\[
C = \{v \in C(\mathbb{R} \times [0, T]): \|v\|_{\infty, T} < 2\|q\|_{\infty, T}\},
\]
where, for any $t > 0$, $\|v\|_{\infty, t} := \sup\{ |v(x,s)|: (x,s) \in \mathbb{R} \times [0, t] \}$. Consider on $C$ the function $v \mapsto F(v) = G(V'(v)) + q$, and observe that if $v \in C$ then $\|V'(v)\|_{\infty, T} \leq 8\|q\|_{\infty, T}(\|q\|_{2, T} + 1)$. Therefore, from (3.2) and (3.3), for any $t \in [0, T]$,
\[
|G(V'(v))(x,t)| \leq \int_0^t ds \int dy \, |\partial_y^2 G(x,y,t-s) V'(u(y,s))| \\
\leq C\|q\|_{\infty, T}(\|q\|_{2, T} + 1)t^\frac{3}{4},
\]
Then, choosing $T = T_0$ small enough, from (3.23) we see that $F(C) \subseteq C$. Moreover, the Picard iterates given by $v_0 = q$, $v_{n+1} = F(v_n)$, form a Cauchy sequence on $C$ (with sup norm) if $T_0$ is small, that converges to a limit $u$, which is a solution to (3.22). To prove uniqueness, fix a realization of $Y$ and suppose that $u, \tilde{u}$ are continuous bounded solutions on $\mathbb{R} \times [0, T]$ with the same initial condition $u_0$ and same realization of $Y$. By (3.22), (3.3), and Hölder inequality, for any $t \in [0, T]$,
\[
\|u - \tilde{u}\|_{\infty, t} \leq C \int_0^t ds \frac{1}{\sqrt{t-s}} \|u - \tilde{u}\|_{\infty, s} \\
\leq C \left( \int_0^t ds (t-s)^{-\frac{3}{2}} \right)^\frac{1}{3} \left( \int_0^t ds \|u - \tilde{u}\|_{4, s}^4 \right)^{\frac{1}{4}},
\]
and therefore,
\[
\|u - \tilde{u}\|_{4, t}^4 \leq CT \int_0^t ds \|u - \tilde{u}\|_{4, s}^4,
\]
which implies that $u = \tilde{u}$ on $\mathbb{R} \times [0, T]$. □
4. Another integral equation

We introduce next a different integral equation equivalent to (2.1), which is more convenient to analyze the stability of $\bar{m}$. Following [12], we consider the kernel arising from a convenient linearization of equation (2.1) around $\bar{m}$. Precisely, let

$$u_0 = \bar{m} + h(x) \quad \text{with} \quad h = \partial_x f \quad \text{for some } f \text{ satisfying } f(\pm \infty) = 0, \quad (4.1)$$

and denote by

$$Lu = \frac{1}{2} \partial_x^2 u - V''(\bar{m})u,$$

the linearization around $\bar{m}$ of the non-linear operator $u \mapsto \frac{1}{2} \partial_x^2 u - V'(u)$. If $u$ solves (2.1) for $u_0$ satisfying (4.1), then $v = u - \bar{m}$ satisfies,

$$\begin{cases} 
\partial_t v = -\partial_x^2 Lv + \partial_x^2 (3\bar{m}v^2 + v^3) + \sqrt{\varepsilon} \nabla (a \dot{W}) , \\
v(x,0) = h(x) .
\end{cases} \quad (4.2)$$

Again, the previous equation is to be understood as the following integral equation for $v$ in terms of the Green function $K(x,y,t)$ corresponding to the operator $e^{-t \partial_x \frac{1}{2} \partial_x^2}$,

$$v(x,t) = \int dy \partial_x K(x,y,t)f(y) - \int_0^t ds \int dy \partial_x \partial_y K(x,y,t-s)(3\bar{m}v^2 + v^3)(y,s) \quad (4.2)$$

$$+ \sqrt{\varepsilon} \int_0^t \partial_x K(x,y,t-s)a(y) dW_{y,s} .$$

Let us now consider the right hand side above. The following expression for $K(x,y,t)$ can be deduced from the analogous one in [12, Propositions 3.1 and 3.2], where the case $L = \partial_x^2 - \frac{1}{2} V''(\bar{m})$ is considered.

**Proposition 4.1.** There exists $t_0 > 0$ such that the kernel $K(x,y,t)$ satisfies,

$$K(x,y,t) = \begin{cases} 
K_\infty(x-y,t) + \tilde{K}(x,y,t) & \text{if } t \in (0,t_0) , \\
K^*(x,y,t) + k(x,y,t) & \text{if } t \geq t_0 ,
\end{cases} \quad (4.3)$$

where $K_\infty(x-y,t)$ is the kernel associated with $e^{-t \partial_x (\frac{1}{2} \partial_x^2 - 2)} \partial_x$ and the following estimates hold. For $i,j \in \{0,1\}$, there exists a constant $C > 0$ such that

$$|\partial_x^i \partial_y^j K_\infty(x-y,t)| \leq Ct^{-\frac{i+j+i+j}{4}} \exp(-2^{\frac{1}{4}} t^{-\frac{1}{4}} |x-y|) , \quad (4.4)$$

$$|\partial_x^i \partial_y^j \tilde{K}(x,y,t)| \leq Ct^{-\frac{i+j}{4}} \exp(-2^{\frac{1}{4}} t^{-\frac{1}{4}} |x-y|) , \quad (4.5)$$
and
\[
K^*(x, y, t) = \frac{1}{\sqrt{2\pi t}} \left\{ -\frac{1}{2} \varphi(x)\varphi(y) \text{sign}(xy) + \frac{1}{2} e^{-\frac{y^2}{8t}} \varphi(x) \text{sign}(xy) \\
+ \frac{1}{2} e^{-\frac{x^2}{8t}} \varphi(y) \text{sign}(xy) - e^{-\frac{(x+y)^2}{8t}} \mathbb{I}_{\{\text{sign}(xy)=1\}} \right\},
\]
(4.6)
where
\[
\varphi(x) = \begin{cases} 
1 - \bar{m}(x) & \text{if } x \geq 0, \\
1 + \bar{m}(x) & \text{if } x \leq 0.
\end{cases}
\]
(4.7)
while, concerning the kernel \(k(x, y, t)\), for \(i, j \in \{0, 1\}\) there exist \(\mu > 0\) and \(C > 0\) such that,
\[
|\partial_x^i \partial_y^j k(x, y, t)| \leq \frac{C}{t} \exp\left(-\mu t^\frac{1}{2}|x - y|\right).
\]
(4.8)

For future reference, we compute \(\partial_x K^*(x, y, t)\) and \(\partial_y \partial_x K^*(x, y, t)\),
\[
\partial_x K^*(x, y, t) = \frac{1}{\sqrt{2\pi t}} \left\{ -\frac{1}{2} \bar{m}'(x)\varphi(y) \text{sign}(y) - \frac{1}{2} \bar{m}'(x)e^{-\frac{y^2}{8t}} \text{sign}(y) \\
- \frac{x}{8t} e^{-\frac{x^2}{8t}} \varphi(y) \text{sign}(x) \text{sign}(y) + e^{-\frac{(x+y)^2}{4t}} \mathbb{I}_{\{\text{sign}(xy)=1\}} \right\},
\]
(4.9)
\[
\partial_y \partial_x K^*(x, y, t) = \frac{1}{\sqrt{2\pi t}} \left\{ -\frac{1}{2} \bar{m}'(x)\bar{m}'(y) + \frac{1}{2} \bar{m}'(x)e^{-\frac{y^2}{8t}} \text{sign}(y) \\
+ \frac{x}{8t} e^{-\frac{x^2}{8t}} \bar{m}'(y) \text{sign}(x) + e^{-\frac{(x+y)^2}{4t}} \mathbb{I}_{\{\text{sign}(xy)=1\}} \right\}.
\]
(4.10)

Let us denote by \(H\) the Gaussian process on the last line of (4.12),
\[
H(x, t) = \int_0^t \int \partial_x K(x, y, t - s) a_\varepsilon(y) \, dW_{y,s}.
\]
(4.11)

More precisely, \(H(x, t)\) is the Gaussian process with covariance,
\[
\mathbb{E}(H(x, t)H(x', t'))
= \int_0^{t\wedge t'} ds \int dy \partial_x K(x, y, t - s) \partial_{x'} K(x', y, t' - s) a_\varepsilon(y)^2.
\]
(4.12)

An expression for \(H\) in terms of \(Y\) also holds. Indeed, from (2.41),
\[
\partial_s (H - Y) = -\partial_s^2 \left(\frac{1}{2} \partial_s^2 (H - Y) - \partial_s^2 (V''(\bar{m})H) \right).
\]
(4.13)
Recalling (3.21), and solving in terms of the Green functions \(G\) and \(K\) respectively we obtain,
\[
H = Y + G\partial_x^2 (V''(\bar{m})H) = Y + \mathcal{G}(V''(\bar{m})H),
\]
\[
H = Y + \nabla K \nabla (V''(\bar{m})Y).
\]
(4.14)

It is not difficult to see that the process \(H\) is bounded and continuous as long as \(Y\) is bounded and continuous. Moreover, \(u\) is a solution to (2.2) with
initial condition as in (1.1) if and only if \( v = u - m \) is a solution to (1.2).

The next proposition, whose proof is given in Appendix A, gives estimates on the increments of \( H \).

**Proposition 4.2.** Let \( H(x,t) \) be as in (1.1). Then, for any \( h > 0 \),

\[
\begin{align*}
\mathbb{E} H(x, t)^2 &\leq C \left( \int_{t \land t_0}^t ds \int dy \left( \partial_x K(x,y,s) + \partial_x \tilde{K}(x,y,s) \right)^2 a_\varepsilon(y)^2 \right. \\
&\quad + \left. \int_{t \land t_0}^t ds \int dy \left( \partial_x K^*(x,y,s) + \partial_x k(x,y,s) \right)^2 a_\varepsilon(y)^2 \right),
\end{align*}
\]

(4.19)

Therefore, from (4.4), for \( R > 1 \) and \( |x| > R + \varepsilon^{-\beta} \),

\[
\begin{align*}
\int_0^{t \land t_0} ds \int dy \left( \partial_x K(x,y,s) \right)^2 a_\varepsilon(y)^2 &\leq C \int_0^{t \land t_0} ds \int_{-\varepsilon^{-\beta}}^{\varepsilon^{-\beta}} dy e^{-s^{-\frac{1}{4}}|x-y|} \\
&\leq C \int_0^{t \land t_0} ds \frac{1}{s^{-\frac{1}{4}}} e^{-Rs^{-\frac{1}{4}}} \leq C \left( \frac{t \land t_0}{R} \right)^{\frac{1}{4}}.
\end{align*}
\]

(4.20)

Similar computations yield, from (4.5) and (4.8) respectively,

\[
\begin{align*}
\int_0^{t \land t_0} ds \int dy \left( \partial_x \tilde{K}(x,y,s) \right)^2 a_\varepsilon(y)^2 &\leq C \frac{t \land t_0}{R},
\end{align*}
\]

(4.21)

\[
\begin{align*}
\int_{t \land t_0}^t ds \int dy \left( \partial_x k(x,y,s) \right)^2 a_\varepsilon(y)^2 &\leq \frac{C}{R}.
\end{align*}
\]

(4.22)
With the aid of (4.9) we estimate the term involving \( \partial_x K^* \) in (4.19). Observe that \( m'(x) \leq e^{-|x|} \), and then
\[
\int_{t \wedge t_0}^t ds \left( \frac{m'(x)^2}{8\pi s} \right) \int dy \left( \varphi(y) \text{sign}(y) - e^{-\frac{x^2}{8s}} \text{sign}(y) \right)^2 a_\varepsilon(y)^2 \\
\leq C e^{-2|x|} \left( \log t - \log(t \wedge t_0) + \frac{t}{2} \right).
\]
(4.23)

Finally,
\[
\int_{t \wedge t_0}^t ds \int dy \left( \frac{\varphi(y)}{\sqrt{2\pi s}} \right)^2 a_\varepsilon(y)^2 \leq C \int_{t \wedge t_0}^t ds \frac{x^2}{s^3} e^{-\frac{x^2}{2s}} \leq C \frac{1}{x^2},
\]
(4.24)
\[
\int_{t \wedge t_0}^t ds \int dy \left( \frac{(x+y)}{\sqrt{2\pi s}} \right)^2 e^{-\frac{(x+y)^2}{2s}} I_{\{\text{sign}(xy)=1\}} a_\varepsilon(y)^2 \leq C \frac{1}{|x|}.
\]
(4.25)

From (4.20)-(4.25), (4.18) follows for \( R > \varepsilon^{-\frac{11+\gamma}{10}} \delta^{-2} + 1 \). □

The continuity of the process \( H(x,t) \) in both variables follows from Proposition 4.2. We can also obtain estimates for the supremum of \( H \).

**Proposition 4.4.** Consider the set \( T_\varepsilon \) as defined in (3.10) with \( T > 0 \) and \( \gamma > 0 \). Then the process \( H(x,t) \) satisfies the following properties.

(i) For each \( \xi > 0 \) there exists a constant \( C > 0 \) such that, for any \( \varepsilon \in (0,1) \),
\[
\mathbb{E} \sup_{(x,t) \in T_\varepsilon} |H(x,t)| < C \varepsilon^{-\frac{\gamma}{4} - \xi}.
\]
(4.26)

(ii)
\[
\mathbb{P} \left( \sup_{(x,t) \in T_\varepsilon} \varepsilon^{\frac{\gamma}{4} + \xi} |H(x,t)| < \infty \right) = 1.
\]
(4.27)

(iii) There exist \( \zeta > 0 \) and a constant \( C > 0 \) such that,
\[
\mathbb{P} \left( \sup_{(x,t) \in T_\varepsilon} |H(x,t)| > \varepsilon^{-\frac{\gamma}{4} - \xi} \right) \leq C e^{-\varepsilon^{-\zeta}}.
\]
(4.28)

**Proof.** We omit the details of the proof: item (i) follows from Proposition 4.2 and Lemma 4.3 adapting the proof of Proposition 3.3. Items (ii) and (iii) follow from (4.15) and (4.26), proceeding again as in the demonstration of Proposition 3.3. □

5. Stability of \( m \)

In this section we prove the stability of the front \( m \) up to times of the order \( \varepsilon^{-\gamma} \), with \( \gamma < \frac{2}{3} \). A precise statement is given in Proposition 5.2.

**Lemma 5.1.** There exists a constant \( M > 0 \) such that for any \( T \geq 0 \),
\[
\sup_{x \in \mathbb{R}} \int_0^T dt \int dy |\partial_x \partial_y K(x,y,t)| \leq M \sqrt{T}.
\]
(5.1)
Proof. It follows simply by integration of the expression (4.3) for the kernel $K$, and estimation of each term with the aid of (4.1), (4.5), (4.8), and (4.10). Recall the definition of $t_0$ in Proposition 4.1, and observe indeed that, from (4.3), (4.4), and (4.5),
\[
\int_0^{T \wedge t_0} dt \int dy \left| \partial_x \partial_y K(x,y,t) \right| \leq C \int_0^{T \wedge t_0} dt \int dy \left( t^{-\frac{3}{4}} + t^{-\frac{1}{2}} \right) e^{-t^{-\frac{1}{4}|x-y|}} \leq C \left( (T \wedge t_0)^{\frac{1}{2}} + (T \wedge t_0)^{\frac{1}{2}} \right).
\]
If $T > t_0$, from (4.3) and (4.8),
\[
\int_{T \wedge t_0}^T dt \int dy \left| \partial_x \partial_y k(x,y,t) \right| \leq C \int_{T \wedge t_0}^T dt \frac{1}{t} \int dy e^{-\mu t^{-\frac{1}{4}|x-y|}} \leq CT^{\frac{1}{2}},
\]
and we are left with the estimation of the term containing $K^*$, which can be done by integration of the five terms in (4.10). Call $I_1, \ldots, I_5$ the resulting integrals. To conclude the proof, it is easy to see that
\[
|I_1 + I_2| \leq C \int_{T \wedge t_0}^T dt t^{-\frac{1}{2}} \leq CT^{\frac{1}{2}}, \quad |I_3| \leq C \int_{T \wedge t_0}^T dt x t^{-\frac{1}{2}} e^{-\frac{x^2}{8t}} \leq CT^{\frac{1}{2}},
\]
\[
|I_4 + I_5| \leq C \int_{T \wedge t_0}^T dt \frac{1}{t} \leq CT^{\frac{1}{2}}.
\]
The lemma is thus proved.

**Proposition 5.2.** There exists a time $T_\varepsilon(\omega)$ such that the equation (2.1) with initial condition $\overline{m}$ has a unique continuous bounded solution $u(x,t)$ for $t \leq T_\varepsilon$. Moreover, given $T > 0$, $\gamma < \frac{2}{3}$, and $\xi \in \left(0, \frac{1}{2} - \frac{3\gamma}{4}\right)$, there exists a set $B_\varepsilon(T,\xi) \in \mathcal{F}$ such that
\[
P\{B_\varepsilon(T,\xi)\} \to 1 \text{ as } \varepsilon \to 0,
\]
and for $\omega \in B_\varepsilon(T,\xi)$ and $\varepsilon$ sufficiently small, $u(x,t)$ satisfies,
\[
\sup_{(x,t) \in \mathcal{E}} |u(x,t) - \overline{m}(x)| < \varepsilon^{\frac{1}{4} - \frac{\gamma}{2} - \frac{\xi}{2}}, \quad \sup_{(x,t) \in \mathcal{E}} |u(x,t) - \overline{m}(x) - \sqrt{\varepsilon} H(x,t)| < \varepsilon^{1-\gamma-\xi},
\]
where the set $\mathcal{E}$ is defined in (3.10). In particular, $P\{T_\varepsilon > \varepsilon^{-\gamma}T\} \to 1$ as $\varepsilon \to 0$.

**Proof.** Recall that the equation (2.1) has to be understood in the sense of its integral version (2.2). We already know from Proposition 3.4 that, for each $\omega \in \Omega$, there exists a positive time $T_\varepsilon(\omega)$ such that the equation (2.2) admits a unique continuous solution $u$ for $t \leq T_\varepsilon(\omega)$. From (3.12), we also know that $\|\sqrt{\varepsilon}Y\|_{\infty,t} < \infty$ if $t \leq \varepsilon^{-4} T$. We will exhibit a set $B_\varepsilon(T,\xi) \in \mathcal{F}$ such that, if $\omega \in B_\varepsilon(T,\xi)$, then the corresponding solution $u$ with initial condition $\overline{m}$ satisfies (5.2), which in particular implies (from the proof of Proposition 3.4 for this particular initial condition and $\omega$) that we can take $T_\varepsilon(\omega) > \varepsilon^{-\gamma}T$, for $\gamma < \frac{2}{3}$. To complete the proof, we need then to show
the existence of the set $B_{\varepsilon}(T, \xi)$, whose probability goes to 1 as $\varepsilon \to 0$, and such that (5.2) and (5.3) hold on $B_{\varepsilon}(T, \xi)$. This will be done for the solution to the integral equation (4.2) with $f = 0$, which is equivalent to (2.2) with $u_{0} = \overline{m}$.

In the sequel we shall use the rescaled variables $(x, \varepsilon^{-\gamma} t)$, with $(x, t) \in \mathcal{T} = \{(x, t) : x \in \mathbb{R}, t \in [0, T]\}$, to parametrize the elements in $\mathcal{T}_{\varepsilon}$. Define the set

$$B_{\varepsilon}(T, \xi) = \left\{ \omega : \sup_{(x, t) \in \mathcal{T}} \varepsilon^{2+\frac{7}{3}}|H(x, \varepsilon^{-\gamma} t)| \leq \frac{1}{2} \right\}.$$  

From (4.28), $\mathbb{P}(B_{\varepsilon}(T, \xi)) \to 1$ as $\varepsilon \to 0$. To prove that (5.2) holds on this set, observe that a simple time scaling in equation (4.2) gives, after (4.11),

$$v(x, \varepsilon^{-\gamma} t) = -\varepsilon^{-\gamma} \int_{0}^{t} ds \int dy \partial_{x} \partial_{y} K(x, y, \varepsilon^{-\gamma} (t - s)) \left(3\overline{m}v^{2} + v^{3}\right)(y, \varepsilon^{-\gamma} s) + \sqrt{\varepsilon} H(x, \varepsilon^{-\gamma} t).$$

(5.4)

In terms of $D_{\varepsilon}(x, t) = \varepsilon^{\frac{1}{2} - \frac{5\gamma}{3} - \frac{4}{3}} v(x, \varepsilon^{-\gamma} t)$, the previous equation reads,

$$D_{\varepsilon}(x, t) = \varepsilon^{\frac{1}{2} - \frac{5\gamma}{3} - \frac{4}{3}} \int_{0}^{t} ds \int dy \partial_{x} \partial_{y} K(x, y, \varepsilon^{-\gamma} (t - s))$$

$$\times \left(3\overline{m}D_{\varepsilon}^{2} + \varepsilon^{\frac{1}{2} - \frac{5\gamma}{3} - \frac{4}{3}} D_{\varepsilon}^{3}\right)(y, s) + \varepsilon^{\frac{1}{2} + \frac{2}{3}} H(x, \varepsilon^{-\gamma} t).$$

Recall that $D_{\varepsilon}(x, 0) = 0$ and define next the stopping time,

$$T^{*} = \inf\{t > 0 : \|D_{\varepsilon}(\cdot, t)\|_{\infty} \geq 1\}.$$

From (5.1) we obtain then that for any $\tau \leq T^{*}$,

$$\|D_{\varepsilon}(\cdot, \tau)\|_{\infty} \leq \varepsilon^{\frac{1}{2} - \frac{5\gamma}{3} - \frac{4}{3}} C\tau^{\frac{1}{2}} \left(3 + \varepsilon^{\frac{1}{2} - \frac{5\gamma}{3} - \frac{4}{3}}\right) + \sup_{x \in \mathbb{R}, t \leq \tau} \varepsilon^{\frac{1}{2} + \frac{2}{3}} |H(x, \varepsilon^{-\gamma} t)|.$$

This inequality implies that $T^{*} > T$ for $\omega \in B_{\varepsilon}(T, \xi)$, for otherwise, evaluating at $T^{*}$ we would get,

$$1 \leq CT^{\frac{1}{2}} \varepsilon^{\frac{1}{2} - \frac{5\gamma}{3} - \frac{4}{3}} + \frac{1}{2},$$

which cannot be true for sufficiently small $\varepsilon$, under the assumptions on $\gamma$ and $\xi$. But $T^{*} > T$ is precisely (5.2).

To prove (5.3), we notice that on the set $B_{\varepsilon}(T, \xi)$, from (5.4) and since (5.2) holds on that set,

$$\sup_{(x, t) \in \mathcal{T}} |v(x, \varepsilon^{-\gamma} t) - \sqrt{\varepsilon} H(x, \varepsilon^{-\gamma} t)|$$

$$\leq 4\varepsilon^{-\gamma + \frac{1}{2} - \frac{5\gamma}{3} - \frac{4}{3}} \sup_{(x, t) \in \mathcal{T}} \left| \int_{0}^{t} ds \int dy \partial_{x} \partial_{y} K(x, y, \varepsilon^{-\gamma} (t - s)) \right|$$

$$\leq CT^{\frac{1}{2}} \varepsilon^{-1 - \gamma - \frac{2\gamma}{3}} ,$$

which implies (5.3), for $\varepsilon$ sufficiently small. □
The previous result shows that, with probability going to 1, the solution $u$ to the stochastic Cahn-Hilliard equation with initial condition $\bar{m}$ remains close to it for times of the order of $\varepsilon^{-\gamma}$ if $\gamma < \frac{2}{3}$. It also gives an idea about the fluctuations. To make it precise, we recall the notion of center of a front, already considered in [11, 10, 8] to study the front fluctuations for the Allen-Cahn and phase field equations. Motivation and properties can be found in those articles and some of the references therein.

Recall the definition (1.4) of $M$, and consider

$$M_\delta = \{ m \in C^0(\mathbb{R}) : \text{dist}(m, M) = \inf_{x_0 \in \mathbb{R}} \| m - m_{x_0} \| \leq \delta \},$$

and for $m \in M_\delta$ define the center of $m$ as the real number $\xi$ such that

$$\langle m - \bar{m}_\xi, \bar{m}_\xi' \rangle = 0.$$

The following result is proved in [11].

**Lemma 5.3.** There exists $\delta_0 > 0$ such that, if $\delta \leq \delta_0$ and $m \in M_\delta$, then $m$ has a unique center $\zeta \in \mathbb{R}$. If $x_0$ is such that $\| m - m_{x_0} \|_\infty < \delta$, then there exists a constant $C$ depending only on $\delta$ such that

(i) $|x - \zeta| \leq C \| m - m_{x_0} \|_\infty$,

(ii) $\zeta = x_0 - \frac{3}{4} \langle m - m_{x_0}, m'_{x_0} \rangle - \frac{9}{16} \langle m - m_{x_0}, m'_{x_0} \rangle \langle m - m_{x_0}, m''_{x_0} \rangle + R$,

where the remainder $R \leq C \| m - m_{x_0} \|_\infty^2$.

**Proof.** From (5.2), in the set $B_\varepsilon(T, \xi)$ the solution $u(\cdot, t)$ has a unique center $z_\varepsilon(t)$ for any $t \leq \varepsilon^{-\gamma} T$ and any $\varepsilon$ sufficiently small. It satisfies,

$$z_\varepsilon(t) = -\frac{3}{4} \langle u(\cdot, t) - \bar{m}, \bar{m}' \rangle + R_\varepsilon,$$

where, for any given $\xi > 0$,

$$\sup_{t \leq \varepsilon^{-\gamma} T} |R_\varepsilon| \leq C \varepsilon^{1 - \frac{2}{3} - \xi}.$$

**Lemma 5.4.** Let $u$ be the solution to (2.1) with initial condition $\bar{m}$, $T > 0$, and $\gamma \in (0, \frac{2}{3})$. Then, on a set whose probability goes to 1 as $\varepsilon \to 0$, $u(\cdot, t)$ has a unique center $z_\varepsilon(t)$ for any $t \leq \varepsilon^{-\gamma} T$ and any $\varepsilon$ sufficiently small. It satisfies,

$$z_\varepsilon(t) = -\frac{3}{4} \langle u(\cdot, t) - \bar{m}, \bar{m}' \rangle + R_\varepsilon,$$

where, for any given $\xi > 0$,

$$\sup_{t \leq \varepsilon^{-\gamma} T} |R_\varepsilon| \leq C \varepsilon^{1 - \frac{2}{3} - \xi}.$$

**Proof.** From (5.2), in the set $B_\varepsilon(T, \xi)$ the solution $u(\cdot, t)$ has a unique center $z_\varepsilon(t)$ for any $t \leq \varepsilon^{-\gamma} T$. Moreover, by item (ii) of Lemma 5.3 with $x_0 = 0$ and (5.2), the center $z_\varepsilon(t)$ satisfies (5.5). \qed

**6. The Process $H$**

We proceed now to establish some properties of the process $H$ defined in (4.11), that will be useful to study the fluctuations of the center $z_\varepsilon(t)$ of $u$, as suggested by (5.5) and (5.3).

**Lemma 6.1.** The process $H(x, t)$ may be decomposed as

$$H(x, t) = H_1(x, t) + H_2(x, t),$$

where

$$H_1(x, t) = -\frac{3}{4} \langle u(\cdot, t) - \bar{m}, \bar{m}' \rangle,$$

and

$$H_2(x, t) = R_\varepsilon,$$

with

$$\sup_{t \leq \varepsilon^{-\gamma} T} |R_\varepsilon| \leq C \varepsilon^{1 - \frac{2}{3} - \xi}.$$
where

\[ (i) \quad H_2(x, t) = -\frac{1}{2} \mathcal{m}'(x) \int_0^t \int_0^t \frac{e^{-\frac{y^2}{2(t-s)}} \text{sign}(y) a_\varepsilon(y)}{\sqrt{2\pi(t-s)}} \, dy \, dW_{y,s}. \]

\[ (ii) \quad \text{For each } \xi > 0, T > 0, \text{ and } \gamma < \frac{2}{3}, \text{ the process } H_1(x, t) \text{ satisfies,} \]

\[ \lim_{\varepsilon \to 0} \mathbb{P}(\sup_{(x,t) \in T_\varepsilon} |H_1(x, t)| > \varepsilon^{-\xi}) = 0. \quad (6.2) \]

**Proof.** From (4.11) and (4.3) we may write,

\[ H(x, t) = 1_{{[t \leq t_0]}} \int_0^t \int_0^t \partial_x \left( K_\infty + \tilde{K} \right)(x, y, t-s) a_\varepsilon(y) \, dy \, dW_{y,s} \]

\[ + 1_{{[t > t_0]}} \left( \int_0^{t-t_0} \int_0^t (T_1 + T_3 + T_4)(x, y, t-s) a_\varepsilon(y) \, dy \, dW_{y,s} \right) \]

\[ + \int_0^t \int_0^t \partial_x k(x, y, t-s) a_\varepsilon(y) \, dy \, dW_{y,s} \]

\[ + \int_0^t \int_0^t \partial_x (K_\infty + \tilde{K})(x, y, t-s) a_\varepsilon(y) \, dy \, dW_{y,s} \]

\[ + \mathcal{m}'(x) \int_0^t \int_0^t \frac{1}{2\sqrt{2\pi(t-s)}} \text{sign}(y) e^{-\frac{y^2}{2(t-s)}} a_\varepsilon(y) \, dy \, dW_{y,s} \]

\[ + H_2(x, t). \]

The term \( T_j \) above \( (j = 1, 3, 4) \) is defined as the first, third and fourth term in the kernel \( \partial_x K^* \) in (4.9), respectively. Call \( H_1(x, t) \) the process given by all the terms but the last one on the right hand side above and let us show that \( H_1 \) so defined satisfies (ii), thus concluding the proof.

From the proof of (4.15) one can see that only term of order \( t^{\frac{1}{2}} \) is precisely the one coming from that part of \( \partial_x K^* \) which is now in \( H_2(x, t) \), see (A.11). Therefore,

\[ \mathbb{E}H_1(x, t)^2 \leq C \left( \log(1 + t) + 1 \right), \quad (6.3) \]

for some constant \( C \) independent of \( x, t \). Also, from (4.20)-(4.25), it is clear that the estimate (4.18) is valid for \( H_1 \) as well: given \( \delta > 0 \), for any \( \varepsilon \) sufficiently small,

\[ R > \varepsilon^{-\frac{11}{10}} \delta^{-2} + 1 \quad \Rightarrow \quad \sup_{|x| \geq R+\varepsilon^{-\beta}, t \leq \varepsilon^{-\gamma}T} \mathbb{E}H_1(x, t)^2 \leq \delta^2. \quad (6.4) \]

On the other hand, given \( h > 0 \),

\[ \mathbb{E} \left( H_2(x+h, t) - H_2(x, t) \right)^2 \]

\[ = \frac{1}{4} (\mathcal{m}'(x+h) - \mathcal{m}'(x))^2 \int_0^t \int_0^t \frac{e^{-\frac{y^2}{2(t-s)}} a_\varepsilon(y)}{2\pi s} \, dy \, ds \leq Ch t^{\frac{1}{2}}, \quad (6.5) \]
\[
\mathbb{E}\left( H_2(x, t + h) - H_2(x, t) \right)^2
= \frac{\overline{m}'(x)^2}{4} \int_t^{t+h} ds \int dy \frac{e^{-\frac{y^2}{2\pi(t+h-s)}}}{2\pi(t+h-s)} a_\varepsilon(y)^2
+ \frac{\overline{m}'(x)^2}{4} \int_0^t ds \int dy \left( \frac{e^{-\frac{y^2}{2\pi(t+h-s)}}}{\sqrt{2\pi(t+h-s)}} - \frac{e^{-\frac{y^2}{2\pi(t-s)}}}{\sqrt{2\pi(t-s)}} \right)^2 a_\varepsilon(y)^2
\leq C \left( \int_0^h \frac{ds}{\sqrt{s}} + \int_0^t \frac{ds}{\sqrt{2(s+h)}} + \frac{1}{\sqrt{2s+h}} \right) \leq Ch^{\frac{3}{2}}.
\]

From (6.1), (4.16), and (6.5) we have,
\[
\mathbb{E}\left( H_1(x+h, t) - H_1(x, t) \right)^2 \leq Ch \left( t^2 (1 + h^2 + h\cdot x^2) + \log (1 + h^{-1} t^2) \right). \tag{6.7}
\]

Analogously, from (4.17) and (6.6),
\[
\mathbb{E}\left( H_1(x, t + h) - H_1(x, t) \right)^2 \leq C \left( h^4 + h^2 + (h + h^2) t^2 \right). \tag{6.8}
\]

With the aid of (6.7), (6.8), and (6.2), proceeding as in the proof of (4.26), it follows that, for any \( \xi > 0 \) and sufficiently small \( \varepsilon \),
\[
\mathbb{E}\left( \sup_{x \in T_\varepsilon} |H_1(x, t)| \right) < \varepsilon^{-\frac{\xi}{2}}.
\]

Finally, from (6.3) and Borell’s inequality (as in (3.16)), (ii) follows. \( \square \)

We consider next the asymptotics for the scaled process \( \varepsilon^{\frac{3}{2}} H(x, \varepsilon^{-\gamma} t) \), which yields the leading term for \( u(x, \varepsilon^{-\gamma} t) - \overline{m}(x) \) (see Proposition 5.2).

**Proposition 6.2.** For any \( x, x' \in \mathbb{R} \) and \( t > t' \geq 0 \),
\[
\lim_{\varepsilon \to 0} \varepsilon^{\frac{3}{2}} \mathbb{E}(H(x, \varepsilon^{-\gamma} t)H(x', \varepsilon^{-\gamma} t')) = \frac{\overline{m}'(x)\overline{m}'(x')}{2\sqrt{2\pi}} \left( \sqrt{t + t'} - \sqrt{t - t'} \right). \tag{6.9}
\]

**Proof.** Changing variables in (4.12) we obtain,
\[
\mathbb{E}(H(x, \varepsilon^{-\gamma} t)H(x', \varepsilon^{-\gamma} t')) = \int_0^{\varepsilon^{-\gamma} t'} ds \int dy \partial_x K(x, y, s) \partial_x K(x', y, s + \varepsilon^{-\gamma}(t - t')) a_\varepsilon(y)^2 \tag{6.10}
\]
Recall formula (4.3) for \( K \), observe that, as \( \varepsilon \to 0 \), we only need to consider \( \varepsilon^{-\gamma} t' > t_0 \), split the time integral above according \( s \leq t_0 \) or not, and call \( \mathcal{E}_1 \) and \( \mathcal{E}_2 \) the resulting terms. Let us consider first the latter. From (4.3),
\[
\mathcal{E}_2 = \int_0^{\varepsilon^{-\gamma} t'} ds \int dy \left( \partial_x K^*(x, y, s) + \partial_x K(x, y, s) \right) a_\varepsilon(y)^2 \times (\partial_y K^*(x', y, s + (t - t') \varepsilon^{-\gamma}) + \partial_y K(x', y, s + (t - t') \varepsilon^{-\gamma})). \tag{6.11}
\]
Substituting \( \partial_x K^* \) and \( \partial_y K^* \) by the expressions in (4.9), we write \( \mathcal{E}_2 \) as a sum of integrals. Let us single out the integral corresponding to the product
of each second term in the right hand side of (4.9), and denote it by $\mathcal{E}_{22}$,

$$
\mathcal{E}_{22} = \frac{m'(x)m'(x')}{4} \int_{t_0}^{e^{-y'}} ds \int dy \frac{e^{-\frac{y^2}{2\pi} e^{-\frac{y^2}{2(s+\varepsilon^{-\gamma}(t-t'))}} a_\varepsilon(y)^2}}{\sqrt{2\pi}s \sqrt{2\pi(s + (t - t')\varepsilon^{-\gamma})}} \tag{6.12}
$$

To conclude the proof, we will show that $\mathcal{E}_{22}$ is the only term that contributes to the limit in (6.9), that is,

(i) $\lim_{\varepsilon \to 0} \varepsilon^{\frac{\gamma}{2}} \mathcal{E}_{22} = \frac{1}{2\sqrt{2\pi}} m'(x)m'(x')(\sqrt{t+t'} - \sqrt{t-t'})$;

(ii) $\lim_{\varepsilon \to 0} \varepsilon^{\frac{\gamma}{2}} (\mathcal{E}_2 - \mathcal{E}_{22}) = 0$;

(iii) $\lim_{\varepsilon \to 0} \varepsilon^{\frac{\gamma}{2}} \mathcal{E}_1 = 0$.

**Proof of (i).** Let us compute the integral in (6.12), but taking $a_\varepsilon = 1,$

$$
\int_{t_0}^{e^{-y'}} ds \int dy \frac{e^{-\frac{y^2}{2\pi} e^{-\frac{y^2}{2(s+\varepsilon^{-\gamma}(t-t'))}}} (1 - a_\varepsilon(y)^2)}{\sqrt{2\pi}s \sqrt{2\pi(s + (t - t')\varepsilon^{-\gamma})}} = 2 \int_{t_0}^{t+e^{-y'}} ds \frac{\varepsilon^{-\gamma}(t+t') - \sqrt{2t_0 + \varepsilon^{-\gamma}(t-t')}}{2\sqrt{2\pi}} \tag{6.13}
$$

Then, (i) follows once we show that

$$
\lim_{\varepsilon \to 0} \varepsilon^{\frac{\gamma}{2}} \int_{t_0}^{e^{-y'}} ds \int dy \frac{e^{-\frac{y^2}{2\pi} e^{-\frac{y^2}{2(s+\varepsilon^{-\gamma}(t-t'))}} (1 - a_\varepsilon(y)^2)}}{\sqrt{2\pi}s \sqrt{2\pi(s + (t - t')\varepsilon^{-\gamma})}} = 0. \tag{6.14}
$$

To do this, we split the spatial integral in (6.14) according to $|y| \leq \varepsilon^{-\frac{\gamma}{2}}$ or not. For the first case, from the properties of $a$, we know that, given $\eta > 0$, $\left|1 - a_\varepsilon(y)^2\right| < \eta$ for $\varepsilon$ sufficiently small. Computing the integral integral as above we get,

$$
\varepsilon^{\frac{\gamma}{2}} \int_{t_0}^{e^{-y'}} ds \int_{|y| \leq \varepsilon^{-\frac{\gamma}{2}}} dy \frac{e^{-\frac{y^2}{2\pi} e^{-\frac{y^2}{2(s+\varepsilon^{-\gamma}(t-t'))}} (1 - a_\varepsilon(y)^2)}}{\sqrt{2\pi}s \sqrt{2\pi(s + (t - t')\varepsilon^{-\gamma})}} \leq C\eta. \tag{6.15}
$$

In the other case, we have,

$$
\varepsilon^{\frac{\gamma}{2}} \int_{t_0}^{e^{-y'}} ds \int_{|y| > \varepsilon^{-\frac{\gamma}{2}}} dy \frac{e^{-\frac{y^2}{2\pi} e^{-\frac{y^2}{2(s+\varepsilon^{-\gamma}(t-t'))}} (1 - a_\varepsilon(y)^2)}}{\sqrt{2\pi}s \sqrt{2\pi(s + (t - t')\varepsilon^{-\gamma})}} \leq C \varepsilon^{\frac{\gamma}{2}} \int_{t_0}^{e^{-y'}} ds \frac{e^{-\frac{\beta s}{2\pi}}}{\sqrt{2\pi s}} \leq C e^{-\frac{\beta s}{2\pi}} \to 0 \quad \text{as} \quad \varepsilon \to 0, \tag{6.16}
$$

since $\gamma < \beta$, and (i) follows.
Proof of (ii). We need to consider all the terms in (6.11) except $E_{22}$. From Hölder’s inequality and (A.10) we have,

\[
\left| \int_{t_0}^{\varepsilon^{-\gamma}t'} ds \int dy \partial_x k(x,y,s) \partial_{x'} k(x',y,s + \varepsilon^{-\gamma}(t-t')) a_\varepsilon(y)^2 \right|
\leq \left( \int_{t_0}^{\varepsilon^{-\gamma}t'} ds \int dy \left( \partial_x k(x,y,s) \right)^2 a_\varepsilon(y)^2 \right)^{1/2}
\times \left( \int_{t_0+\varepsilon^{-\gamma}(t-t')}^{\varepsilon^{-\gamma}t} ds \int dy \left( \partial_{x'} k(x',y,s) \right)^2 a_\varepsilon(y)^2 \right)^{1/2}
\leq C \left( \log(\varepsilon^{-\gamma}t) + \sqrt{\varepsilon^{-\gamma}t} \right)^{1/2}.
\]

Analogously, from (A.11) and (A.10),

\[
\left| \int_{t_0}^{\varepsilon^{-\gamma}t'} ds \int dy \partial_x K^*(x,y,s) \partial_{x'} K^*(x',y,s + \varepsilon^{-\gamma}(t-t')) a_\varepsilon(y)^2 \right|
\leq \left( \int_{t_0}^{\varepsilon^{-\gamma}t'} ds \int dy \left( \partial_x K^*(x,y,s) \right)^2 a_\varepsilon(y)^2 \right)^{1/2}
\times \left( \int_{t_0+\varepsilon^{-\gamma}(t-t')}^{\varepsilon^{-\gamma}t} ds \int dy \left( \partial_{x'} K^*(x',y,s) \right)^2 a_\varepsilon(y)^2 \right)^{1/2}
\leq C \left( \log(\varepsilon^{-\gamma}t) + \sqrt{\varepsilon^{-\gamma}t} \right)^{1/2}.
\]

Finally, to estimate the terms coming from $\partial_x K^* \partial_{x'} K^*$ in (6.11), we observe that, from (4.9), Hölder’s inequality and (A.11),

\[
\left| \int_{t_0}^{\varepsilon^{-\gamma}t'} ds \int dy \partial_x K^*(x,y,s) \frac{\partial'(x') \varphi(y) a_\varepsilon(y)^2}{2\sqrt{2\pi}(s + \varepsilon^{-\gamma}(t-t'))} \right|
\leq C \left( \log(t'\varepsilon^{-\gamma}) + (\varepsilon^{-\gamma}t')^{1/2} \right) \left( \log(\varepsilon^{-\gamma}t) \right)^{1/2},
\]

\[
\left| \int_{t_0}^{\varepsilon^{-\gamma}t'} ds \int dy \partial_x K^*(x,y,s) \frac{x' \varphi(y) e^{-\frac{x'^2}{8(s + \varepsilon^{-\gamma}(t-t'))}} a_\varepsilon(y)^2}{8 \sqrt{2\pi}(s + \varepsilon^{-\gamma}(t-t'))^{3/2}} \right|
\leq C \left( \log(\varepsilon^{-\gamma}t) + (t'\varepsilon^{-\gamma})^{1/2} \right)^{1/2},
\]

\[
\left| \int_{t_0}^{\varepsilon^{-\gamma}t'} ds \int dy \partial_x K^*(x,y,s) \frac{(x' + y) e^{-\frac{(x'^2+y^2)}{8(s + \varepsilon^{-\gamma}(t-t'))}} a_\varepsilon(y)^2}{4 \sqrt{2\pi}(s + \varepsilon^{-\gamma}(t-t'))^{3/2}} \right|
\leq C \left( \log(\varepsilon^{-\gamma}t) + (t'\varepsilon^{-\gamma})^{1/2} \right)^{1/2}.
\]

Observe that (6.17), (6.18), (6.19), (6.20), and (6.21) go to zero when multiplied by $\varepsilon^{\frac{3}{2}}$, as well as the remaining terms (which are similarly estimated), and (ii) follows.
Proof of (iii). From Hölder’s inequality,
\[
|E_1| = \left| \int_0^{t_0} ds \int dy \partial_x K(x, y, s) \partial_{x'} K(x', y, s + \varepsilon^{-\gamma}(t - t')) a_\varepsilon(y)^2 \right| \leq \left( \int_0^{t_0} ds \int dy (\partial_x K(x, y, s))^2 a_\varepsilon(y)^2 \right)^{\frac{1}{2}} \times \left( \int_0^{t_0} ds \int dy (\partial_{x'} K(x', y, s + \varepsilon^{-\gamma}(t - t')))^2 a_\varepsilon(y)^2 \right)^{\frac{1}{2}}.
\]

The first factor on the right hand side above is bounded by a constant, as can be seen from (4.3), (A.8) and (A.9). For the last factor, from (4.3) we have that, if \( s \geq t_0 \),
\[
|\partial_{x'} K(x', y, s)|^2 \leq 2 |\partial_{x'} K^*(x', y, s)|^2 + 2 |\partial_{x'} k(x', y, s)|^2.
\]
From (A.10), we obtain,
\[
\int_{\varepsilon^{-\gamma}(t - t')}^{\varepsilon^{-\gamma}(t - t') + t_0} ds \int dy (\partial_{x'} k(x', y, s))^2 a_\varepsilon(y)^2 \leq C.
\]
Finally, we need to integrate \( K^* \). As in (A.11), from (4.9),
\[
\int_{\varepsilon^{-\gamma}(t - t')}^{\varepsilon^{-\gamma}(t - t') + t_0} ds \int dy (\partial_{x'} K^*(x', y, s))^2 a_\varepsilon(y)^2 \leq C \int_{\varepsilon^{-\gamma}(t - t')}^{\varepsilon^{-\gamma}(t - t') + t_0} ds \left( \frac{1}{s} + \frac{1}{s^2} + \frac{1}{s^2} \right) \leq C.
\]
From the previous estimates, \( |E_1| \leq C \), which implies (ii), and concludes the proof. \( \square \)

The previous proposition implies that, as \( \varepsilon \to 0 \), the scaled process \( \varepsilon^{\frac{1}{4}} H(x, t\varepsilon^{-\gamma}) \) converges in the sense of finite dimensional distributions to the process \((8\pi)^{-\frac{1}{4}} \tilde{m}'(x)r(t)\), where \( r(t) \) is the one dimensional Gaussian process with covariance (2.4). Recall now the decomposition of \( H \) given in Lemma 6.1, and denote by \( h_2 \) the temporal part of \( H_2 \), i.e.,
\[
h_2(t) = \int_0^t \frac{e^{-\frac{y^2}{8(t - s)}}}{2\sqrt{2\pi(t - s)}} \text{sign}(y) e^{-\frac{y^2}{8(t - s)}} a_\varepsilon(y) dW_{y,s}. \tag{6.22}
\]
We show next that \( h_2 \), when suitably scaled, converges weakly in \( C(\mathbb{R}_+) \) (equipped with the topology of uniform convergence in compacts) to the process \( r \).

**Lemma 6.3.** As \( \varepsilon \to 0 \), the real process
\[
h^{(\varepsilon)}(t) = \varepsilon^{\frac{1}{4}} h_2(\varepsilon^{-\gamma} t) \tag{6.23}
\]
converges weakly in \( C(\mathbb{R}_+) \) to \((8\pi)^{\frac{1}{2}} r(t)\).
Proof. From (6.13) and (6.14) with \( t_0 = 0 \), it follows that
\[
\lim_{\epsilon \to 0} \mathbb{E}(h(\epsilon)(t) h(\epsilon)(t')) = (8\pi)^{-\frac{1}{2}} (\sqrt{t + t'} - \sqrt{t - t'}) ,
\]
which implies \( h(\epsilon)(t) \to r(t) \), in the sense of finite dimensional distributions. From (6.6) we also know that
\[
\mathbb{E}(h(\epsilon)(t + h) - h(\epsilon)(t))^2 = \epsilon^{\frac{2}{3}} \mathbb{E}(h_2(\epsilon^\gamma(t + h)) - h_2(\epsilon^{-\gamma} t))^2 \leq C \epsilon^{\frac{2}{3}} (h \epsilon^{-\gamma})^{\frac{1}{2}} = Ch^\frac{1}{2} ,
\]
which, together with the fact \( h(\epsilon)(0) = 0 \) implies that the corresponding family of laws is tight, and then the weak limit has to be \( r \). \( \square \)

Proof of Theorem 2.1. The statement concerning the uniqueness and existence of a solution \( u \) to the Cahn–Hilliard equation (2.1), or, equivalently (as already discussed), to the integral equation (4.2) follows from Proposition 5.2, just by taking \( B(\epsilon, \gamma, T) = B_\epsilon(T, \xi) \) with any \( \xi \) small enough.

To prove item (i), given \( \eta > 0 \) we fix \( \xi \in (0, \frac{1}{2} - \frac{3\gamma}{4}) \) such that \( 2\xi < \eta \) and we let \( B_\epsilon(T, \xi) \) be as in Proposition 5.2. Consider \( \delta_0 \) as in Lemma 5.3 and define the process \( \zeta_\epsilon(t) = z_\epsilon(t \wedge \tau) \), where
\[
\tau = \inf\{t > 0 : u(\cdot, t) \notin \mathcal{M}_{\delta_0}\}
\]
and \( z_\epsilon(t) \) is the center of \( u(\cdot, t) \) (which is well defined, as follows from Lemma 5.4). The process \( \zeta_\epsilon(t) \) is clearly continuous and adapted to \( \mathcal{F}_t \); note also that \( B_\epsilon(T, \xi) \subset \{ \tau > \epsilon^{-\gamma} T \} \) for any \( \epsilon \) sufficiently small. Let now,
\[
\nu_\epsilon(t) = -\frac{3}{4} (u(\cdot, t) - \bar{m}, \bar{m}') ,
\]
which is an approximation to \( \zeta_\epsilon(t) \). Indeed, from (5.5), on the set \( B_\epsilon(T, \xi) \),
\[
\sup_{t \leq \epsilon^{-\gamma} T} ||\bar{m}_{\zeta_\epsilon}(t) - \bar{m}_{\nu_\epsilon}(t)||_\infty \leq \epsilon^{1 - \frac{2}{3} - 2\xi} . \quad (6.24)
\]
Observe next that, from (6.1) and (6.22), after recalling that \( \langle m', m' \rangle = \frac{4}{3} \),
\[
\nu_\epsilon(t) = -\frac{3}{4} (u(\cdot, t) - \bar{m} - \sqrt{\epsilon}H, \bar{m}') - \frac{3}{4} (\sqrt{\epsilon}h_1, \bar{m}') + \sqrt{\epsilon}h_2(t) .
\]
Therefore, by (5.3) and (6.2), there is a set \( \tilde{B}_\epsilon(T, \xi) \subset B_\epsilon(T, \xi) \), with \( \mathbb{P}(\tilde{B}_\epsilon(T, \xi)) \to 1 \) as \( \epsilon \to 0 \), such that
\[
\sup_{t \leq \epsilon^{-\gamma} T} |\nu_\epsilon(t) - \sqrt{\epsilon}h_2(t)| \leq \epsilon^{1 - \gamma - \xi} + \epsilon^{\frac{1}{2} - \xi} \quad \forall \omega \in \tilde{B}_\epsilon(T, \xi) ,
\]
and then, for any \( \epsilon \) small enough,
\[
\sup_{t \leq \epsilon^{-\gamma} T} ||\bar{m}_{\nu_\epsilon}(t) - \bar{m}_{\sqrt{\epsilon}h_2(t)}||_\infty \leq \epsilon^{1 - \gamma - 2\xi} + \epsilon^{\frac{1}{2} - 2\xi} \quad \forall \omega \in \tilde{B}_\epsilon(T, \xi) . \quad (6.25)
\]
Now, by triangle inequality we may write,
\[ \| u(\cdot, t) - m \zeta_{\epsilon}(t) \|_{\infty} \leq \| m \zeta_{\epsilon}(t) - m \nu_{\epsilon}(t) \|_{\infty} + \| m \nu_{\epsilon}(t) - m \sqrt{\epsilon} h_{2}(t) \|_{\infty} + \| u(\cdot, t) - m \sqrt{\epsilon} h_{2}(t) \|_{\infty}. \] (6.26)

For this last term, from (6.1) and (6.22) we have in turn,
\[ \| u(\cdot, t) - m \sqrt{\epsilon} h_{2}(t) \|_{\infty} \leq \| u(\cdot, t) - m \sqrt{\epsilon} H \|_{\infty} + \| m + \sqrt{\epsilon} H - m \sqrt{\epsilon} h_{2}(t) \|_{\infty} \leq \| u(\cdot, t) - m \sqrt{\epsilon} H \|_{\infty} + \| m - \sqrt{\epsilon} m' h_{2} - m \sqrt{\epsilon} h_{2}(t) \|_{\infty} + \sqrt{\epsilon} \| H_{1} \|_{\infty}. \] (6.27)

The first and last terms on this last line are bounded with the aid of (5.3) and (6.2), while for the middle one we have, for some \( \theta \in \mathbb{R} \),
\[ |m - m' \sqrt{\epsilon} h_{2}(t)| = \frac{\epsilon}{2} |m''(\theta)| h_{2}^{2}(t), \] (6.28)
and, from Lemma 6.3, we know that
\[ \lim_{\epsilon \to 0} \mathbb{P}( \sup_{t \leq \epsilon^{-\gamma} T} \epsilon |h_{2}^{2}(t)| > \epsilon^{1-\frac{2}{4}-2\xi} ) = 0. \] (6.29)

Item (i) follows now from (6.26), (6.24), (6.25), (6.27), (6.28), and (6.29).

The convergence of \( X_{\epsilon}(t) = \epsilon^{-\frac{1}{2} + \frac{2}{4}} \zeta_{\epsilon}(\epsilon^{-\gamma} t) \) follows from the above estimates and Lemma 6.3 after writing
\[ \zeta_{\epsilon}(t) = (\zeta_{\epsilon}(t) - \nu_{\epsilon}(t)) + (\nu_{\epsilon} - \sqrt{\epsilon} h_{2}(t)) + \sqrt{\epsilon} h_{2}(t), \]
which proves (ii).

7. The one dimensional process \( r \)

In the next proposition we summarize some properties of \( r \), that follow at once from the form of the covariance function.

**Proposition 7.1.** The one dimensional Gaussian process with covariance given by (2.4) satisfies,

(i) It has (a modification with) continuous paths.

(ii) It is a self similar process of order \( \frac{1}{4} \), that is, for any given \( a > 0 \),
\[ \{ r(at) \}_{t \geq 0} \overset{\text{law}}{=} \{ a^{\frac{1}{4}} r(t) \}_{t \geq 0}. \]

We also obtain several representations of the process \( r \), in terms of fractional Brownian motion, the solution to the \( 1 - D \) stochastic heat equation and a stochastic integral with respect to Brownian motion, that may be of independent interest.

Let us recall that a two sided fractional-Brownian motion with Hurst parameter \( H \), is a one dimensional Gaussian process \( \nu^{(H)}(t) \) characterized by its covariance function,
\[ \mathbb{E}(\nu^{(H)}(t)\nu^{(H)}(s)) = \frac{1}{2} \left( |t|^{2H} + |s|^{2H} - |t - s|^{2H} \right). \]
Define the odd part of $\nu^H(t)$ as usual,

$$\nu^H_O(t) = \frac{1}{2}(\nu^H(t) - \nu^H(-t)). \hspace{1cm} (7.1)$$

We refer to [22] for an introduction and properties of fractional Brownian motion.

Next, consider $h(x, t)$ the solution of the stochastic heat equation for $x \in \mathbb{R}$, with zero initial condition,

$$\begin{cases}
\partial_t h = \frac{1}{2} \partial_x^2 h + \dot{W}, \\
h(x, 0) = 0,
\end{cases}$$

where $\dot{W} = \dot{W}_{x,t}$ is a space-time white noise.

Proposition 7.2. The process $r(t)$ satisfies,

$$\begin{align*}
\{r(t)\}_{t \geq 0} \overset{\text{law}}{=} & \left\{2 \nu^H_O(t)\right\}_{t \geq 0}, \\
\{r(t)\}_{t \geq 0} \overset{\text{law}}{=} & \left\{(2\pi)^{\frac{1}{4}}h(0, t)\right\}_{t \geq 0}.
\end{align*}$$

Proof. Both statements follow by computing covariances, since all the processes involved are Gaussian. Indeed, the process $h(x, t)$ is given by

$$h(x, t) = \int_0^t e^{-\frac{(x-y)^2}{2(t-s)}} \sqrt{\frac{2}{\pi(t-s)}} \, db_y(s),$$

and the covariance is easily computed,

$$\begin{align*}
\mathbb{E}(h(0, t) h(0, t')) &= \int_0^{t \wedge t'} ds \int dy \frac{e^{-\frac{y^2}{2(t-s)}}}{\sqrt{2\pi(t-s)}} \frac{e^{-\frac{y^2}{2(t'-s)}}}{\sqrt{2\pi(t'-s)}} \\
&= \frac{1}{\sqrt{2\pi}} \left(\sqrt{t + t'} - \sqrt{t + t'} - 2(t \wedge t')\right).
\end{align*}$$

We also obtain a representation as an integral with respect to Brownian motion.

Proposition 7.3. The process $r$ can be represented as the following integral with respect to Brownian motion $b$,

$$r(t) = c \int_0^t \frac{u^{\frac{1}{4}}}{(t^2 - u^2)^{\frac{1}{4}}} db(u), \hspace{1cm} (7.2)$$

where $c = \left(\frac{1}{2}B(\frac{3}{4}, \frac{3}{4})\right)^{-\frac{1}{2}}$, with $B(\cdot, \cdot)$ the usual Euler beta function.

Proof. Suppose that $t \geq t' \geq 0$. Then, Formula 9.121(4), p.1040 in [19] reads,

$$(t + t')^\rho - (t - t')^\rho = 2 \rho t' t^{\rho-1} F\left(-\frac{\rho-1}{2}, -\frac{\rho-2}{2}, \frac{3}{2}, \frac{t'^2}{t^2}\right), \hspace{1cm} (7.3)$$
where $F$ is the hypergeometric Gauss function. Taking $\rho = \frac{1}{2}$, and using for $F$ the Integral Formula 9.11.1, p.1040 in [19] we obtain,

$$F\left(\frac{1}{4}, \frac{3}{4}, \frac{3}{2}; \frac{t^2}{2}\right) = \frac{1}{B\left(\frac{3}{4}, \frac{3}{4} \right)} \int_0^1 ds \, s^{-\frac{1}{4}} (1-s)^{-\frac{1}{4}} \left(1 - \frac{s \cdot t^2}{t^2}\right)^{-\frac{1}{4}}. \quad (7.4)$$

The change of variables $u = t' s^{\frac{1}{2}}$ in this last integral, together with (7.3) yields,

$$\sqrt{t + t'} - \sqrt{t - t'} = \frac{2}{B\left(\frac{3}{4}, \frac{3}{4} \right)} \int_0^{t'} du \, \frac{\, u^{\frac{1}{2}}}{(t^2 - u^2)^{\frac{1}{2}} (t^2 - u^2)^{\frac{1}{2}}}, \quad (7.5)$$

which proves (7.2), since the integral on the right hand side above is just the covariance of the process given by the stochastic integral in (7.2). □

**Appendix A.**

**A.1. Proof of Proposition 3.2.** From (2.3) and (3.2)

$$\mathbb{E} Y(x,t)^2 = \int_0^t ds \, dy \, a_\varepsilon(y)^2 \frac{1}{t-s} \phi'\left(\frac{x-y}{(t-s)^{\frac{1}{4}}}\right)^2 \geq \int_0^t ds \, \frac{1}{s^{\frac{1}{4}}} \int dz \, a_\varepsilon^2(x-s^{\frac{1}{4}} z) \phi'(z)^2 \leq t^{\frac{1}{4}} \|\phi'||^2_2, \quad (A.1)$$

and then (3.7) follows from (3.3).

Before proving the remaining estimates, we remark that (3.4) implies that

$$|\phi'(x + H) - \phi'(x)| \leq C \frac{H}{1 + H}. \quad (A.2)$$

We then have,

$$\mathbb{E} (Y(x+h,t) - Y(x,t))^2$$

$$\leq \int_0^t ds \, \frac{1}{s^{\frac{1}{4}}} \int dz \, a_\varepsilon^2(x-s^{\frac{1}{4}} z) \left[\phi'(z + s^{-\frac{1}{4}}h) - \phi'(z)\right]^2 \leq \int_0^t ds \, \frac{1}{s^{\frac{1}{4}}} \int dz \left[\phi'(z + s^{-\frac{1}{4}}h) - \phi'(z)\right]^2 \leq 2 \int_0^t ds \, \frac{1}{s^{\frac{1}{4}}} \int dz \phi'(z) \left[\phi'(z) - \phi'(z + s^{-\frac{1}{4}}h)\right] \leq C \int_0^t ds \, \frac{1}{s^{\frac{1}{4}}} \frac{h}{s^{\frac{1}{2}} + h} = 4 C h \log (1 + h^{-1} t^{\frac{1}{4}}),$$

where the last inequality follows from (3.3) and (A.2) with $H = s^{-\frac{1}{4}} h$. This proves the estimate (3.8).
We next have, after changing variables in the time integrals,
\[
\mathbb{E} (Y(x, t + h) - Y(x, t))^2 = \int_0^h ds \int dy \frac{a_x(y)^2}{s} \phi' \left( \frac{x - y}{s^{1/4}} \right)^2 \\
+ \int_0^t ds \int dy a_x^2(y) \left[ \frac{1}{(s + h)^{1/2}} \phi' \left( \frac{x - y}{(s + h)^{1/2}} \right) - \frac{1}{s^{1/2}} \phi' \left( \frac{x - y}{s^{1/2}} \right) \right]^2.
\]

Let us denote by \( I_1 \) and \( I_2 \) the integrals on the right hand side. The first integral can be bounded as in (A.1) to obtain
\[
I_1 \leq C h^{1/4}. \tag{A.4}
\]

For the second one, we observe that \( I_2 \leq I_{21} + I_{22} \) with
\[
I_{21} = 2 \int_0^t ds \int dy \left( \frac{1}{s^{1/2}} - \frac{1}{(s + h)^{1/2}} \right)^2 \phi' \left( \frac{x - y}{s^{1/2}} \right)^2,
\]
\[
I_{22} = 2 \int_0^t ds \int dy \frac{1}{s + h} \left[ \phi' \left( \frac{x - y}{(s + h)^{1/2}} \right) - \phi' \left( \frac{x - y}{s^{1/2}} \right) \right]^2.
\]

Now, after the change of variables \( z = s^{-1/2}(x - y) \) and then \( s = h\tau \) we get,
\[
I_{21} = 2 \| \phi' \|_2^2 h^{1/4} \int_0^{h^{-1}t} d\tau \frac{1}{\tau^{1/2}} \left( 1 - \frac{\tau^{1/2}}{(\tau + 1)^{1/2}} \right)^2 \leq C h^{1/4}, \tag{A.5}
\]
where we used that the last integral in the right-hand side is bounded above by \( \int_0^\infty d\tau (1 + \tau)^{-1} \tau^{-1/2} < +\infty \). Next, denoting \( A = s^{-1/2}(s + h)^{1/2} \) and using (3.5),
\[
I_{22} = 2 \int_0^t ds \int dz \frac{1}{(s + h)^{1/2}} \left[ \phi'(z) - \phi'(Az) \right]^2 \leq C \int_0^t ds \frac{(A - 1)^2}{(s + h)^{1/2}}
\]
\[
= Ch^{1/4} \int_0^{h^{-1}t} d\tau \left[ (1 + \tau)^{1/4} - \tau^{1/4} \right] \leq C h^{1/4}, \tag{A.6}
\]
having used that the last integral is bounded by \( \int_0^\infty d\tau (1 + \tau)^{-1/4} \tau^{-1/2} < +\infty \). The estimate (3.9) follows from (A.4), (A.5), and (A.6). \( \square \)

A.2. Proof of Proposition 4.2. From (4.3) and recalling \( \|a_c\|_\infty \leq 1 \), we have that
\[
\mathbb{E} H(x, t)^2 = \int_0^t ds \int dy \left[ \partial_x K(x, y, s)a_c(y) \right]^2
\]
\[
\leq 2 \int_0^{t \wedge t_0} ds \int dy \left[ (\partial_x K_\infty(x, y, s))^2 + (\partial_x \tilde{K}(x, y, s))^2 \right] + 2 \int_{t \wedge t_0}^t ds \int dy \left[ (\partial_x K^*(x, y, s))^2 + (\partial_x k(x, y, s))^2 \right]. \tag{A.7}
\]
Now, from \((4.4)\) we get that
\[
\int_0^{t \wedge t_0} ds \int dy \left( \partial_x K_{\infty}(x, y, s) \right)^2 \leq C \int_0^{t \wedge t_0} ds \frac{1}{s} \int dy \, e^{-\left(\frac{t}{2}\right)^2 |x-y|} \leq C \int_0^{t \wedge t_0} ds \frac{1}{s^2} \int dz \, e^{-|z|} = C(t \wedge t_0)^{\frac{1}{2}}. \tag{A.8}
\]
Analogously, from \((4.5)\) and \((4.8)\),
\[
\int_0^{t \wedge t_0} ds \int dy \left( \partial_x \bar{K}(x, y, s) \right)^2 \leq C(t \wedge t_0)^{\frac{1}{2}}, \tag{A.9}
\]
\[
\int_0^t ds \int dy \left( \partial_x k(x, y, s) \right)^2 \leq C((t_0 \wedge t)^{\frac{1}{2}} - t^{-\frac{1}{2}}). \tag{A.10}
\]
We are left with the estimation of the integral of \((\partial_x K^*)^2\); that gives the leading term (as \(t \to \infty\)). With the aid of formula \((4.6)\), after recalling that \(\bar{m}', \varphi, \text{ and } z \mapsto ze^{-z^2}\) are bounded and integrable functions, we obtain,
\[
\int_{t \wedge t_0}^t ds \int dy \left( \partial_x K^*(x, y, s) \right)^2 \leq C \left( \bar{m}'(x)^2 \left( \log \frac{t}{t \wedge t_0} - t^{-\frac{1}{2}} - (t_0 \wedge t)^{\frac{1}{2}} \right) + \frac{1}{t \wedge t_0} - \frac{1}{t} \right), \tag{A.11}
\]
and \((4.15)\) follows from \((A.7), (A.8), (A.9), (A.10)\), and the above estimate.

To prove the rest of the proposition, let us use formula \((4.14)\) for \(H\), to write
\[
\mathbb{E}(H(x + h, t) - H(x, t))^2 \leq 2 \mathbb{E}(Y(x + h, t) - Y(x, t))^2 + 2 \mathbb{E}(G'(V''(m)H)(x + h, t) - G(V''(m)H)(x, t))^2. \tag{A.12}
\]
Recalling \((3.21)\) (with the substitution \(s \to t - s\)) and using \(V''(m) \leq 3m^2 + 1 \leq 4\), we estimate the last expectation above by Cauchy Schwartz inequality,
\[
\mathbb{E}(G(V''(m)H)(x + h, t) - G(V''(m)H)(x, t))^2 \leq J(x, t)^2, \tag{A.13}
\]
where
\[
J(x, t) = 4 \int_0^t ds \int dy \left| \partial_y^2 G(x + h, y, s) - \partial_y^2 G(x, y, s) \right| (\mathbb{E}H(y, t-s)^2)^{\frac{1}{2}}.
\]
From \((4.15)\) we have \((\mathbb{E}H(y, t-s)^2)^{\frac{1}{2}} \leq C \left(1 + m'(y) (t-s)^{\frac{1}{2}} \mathbb{1}_{\{t-s > 1\}} \right)\). Then, by formula \((3.2)\) for \(\partial_y^2 G\), after changing variable \(y = x - s^{\frac{1}{4}} z\) we get,
\[
J(x, t) \leq C \int_0^t ds \frac{1}{s^{\frac{1}{2}}} \int dz \left| \phi''(z + s^{-\frac{1}{4}} h) - \phi''(z) \right| + Ct^{\frac{1}{2}} \int_0^{(t-1)^+} \frac{1}{s^{\frac{1}{2}}} \int dz \left| \phi''(z + s^{-\frac{1}{4}} h) - \phi''(z) \right| m'(x - s^{\frac{1}{4}} z),
\]
which implies, as \( \mathfrak{m} \) is bounded,
\[
J(x, t) \leq C \int_0^t ds \left( \frac{1}{s^2} \int dz \left| \phi''(z + s^{-\frac{1}{2}}h) - \phi''(z) \right| \right.
\]
\[
+ Ct^{\frac{1}{2}} \int_0^{1 \wedge (t - 1)_+} ds \frac{1}{s^2} \int dz \left| \phi''(z + s^{-\frac{1}{2}}h) - \phi''(z) \right|
\]
\[
+ Ct^{\frac{1}{2}} \int_{1 \wedge (t - 1)_+}^{(t - 1)_+} ds \frac{1}{s^2} \int dz \left| \phi''(z + s^{-\frac{1}{2}}h) - \phi''(z) \right| \mathfrak{m}'(x - s^{\frac{3}{2}} z),
\]
(A.14)

Now, by (3.1) with \( H = s^{-\frac{1}{2}}h \) and \( k = 2 \),
\[
\int dz \left| \phi''(z + s^{-\frac{1}{2}}h) - \phi''(z) \right| \leq Cs^{-\frac{1}{2}} h,
\]
while, by (3.6) and using that \( \mathfrak{m}' \) vanishes exponentially fast at \( \pm \infty \),
\[
\int dz \left| \phi''(z + s^{-\frac{1}{2}}h) - \phi''(z) \right| \mathfrak{m}'(x - s^{\frac{3}{2}} z) \leq Cs^{-\frac{1}{2}} h^2 (1 + |x|) h.
\]

Using the above estimates in the right hand side of (A.14) we obtain,
\[
J(x, t) \leq Ct^\frac{1}{2} (h^2 + (1 + |x|) h).
\]
(A.15)

Estimate (4.16) follows now from (A.12), (3.8), (A.13), and (A.15).

A similar reasoning proves (4.17). Indeed, by formula (4.14) for \( H \) we have in this case,
\[
\mathbb{E}(H(x, t + h) - H(x, t))^2 \leq 2 \mathbb{E}(Y(x, t + h) - Y(x, t))^2
\]
\[
+ 2 \mathbb{E}(\mathcal{G}(V''(\mathfrak{m}))H)(x, t + h) - \mathcal{G}(V''(\mathfrak{m}))H)(x, t))^2,
\]
(A.16)

with now (as before, recalling (3.21), that \( V''(\mathfrak{m}) \leq 3\mathfrak{m}^2 + 1 \leq 4 \), changing \( s \to t - s \), and using Cauchy Schwartz inequality),
\[
\mathbb{E}(\mathcal{G}(V''(\mathfrak{m})H)(x, t + h) - \mathcal{G}(V''(\mathfrak{m})H)(x, t))^2 \leq 2J_1(x, t)^2 + 2J_2(x, t)^2,
\]
(A.17)

where
\[
J_1(x, t) = 4 \int_0^h ds \int dy \left| \partial_y^2 G(x, y, s) \right| (\mathbb{E}H(y, t + h - s)^2)^\frac{1}{2}
\]
and
\[
J_2(x, t) = 4 \int_0^t ds \int dy \left| \partial_y^2 G(x, y, s + h) - \partial_y^2 G(x, y, s) \right| (\mathbb{E}H(y, t - s)^2)^\frac{1}{2}.
\]

Proceeding as in (A.13), from (3.2), (3.3) and (4.15) we obtain
\[
J_1(x, t) \leq 4 \sup_{z \in \mathbb{R}, \tau \leq t + h} \left( \mathbb{E}H(y, \tau)^2 \right)^\frac{1}{2} \int_0^h ds \frac{1}{s^2} \int dz \left| \phi''(z) \right|
\]
\[
\leq Ch^\frac{1}{2} (1 + h^\frac{1}{2} + t^\frac{1}{2})
\]
(A.18)
Recalling \( (4.15) \) implies \( (\mathbb{E}H(y, t - s)^2)^{\frac{1}{2}} \leq 1 + m'(y)(t - s)^{\frac{1}{2}} \mathbb{I}_{\{t - s > 1\}} \), we now have,

\[
J_2(x, t) \leq 4 \int_0^t ds \frac{1}{(s + h)^{\frac{1}{4}}} \int dy \left| \phi''\left(\frac{x - y}{(s + h)^{\frac{1}{4}}} \right) - \phi''\left(\frac{x - y}{s^{\frac{1}{4}}} \right) \right| \\
+ 4 \int_0^t ds \left( \frac{1}{s^{\frac{1}{4}}} - \frac{1}{(s + h)^{\frac{1}{4}}} \right) \int dy \left| \phi''\left(\frac{x - y}{s^{\frac{1}{4}}} \right) \right| \\
+ 4 t^\frac{1}{2} \int_0^{(t-1)+} ds \frac{1}{(s + h)^{\frac{1}{4}}} \int dy \left| \phi''\left(\frac{x - y}{(s + h)^{\frac{1}{4}}} \right) \right| m'(y) \\
+ 4 t^\frac{1}{2} \int_0^{(t-1)+} ds \left( \frac{1}{s^{\frac{1}{4}}} - \frac{1}{(s + h)^{\frac{1}{4}}} \right) \int dy \left| \phi''\left(\frac{x - y}{s^{\frac{1}{4}}} \right) \right| m'(y).
\]

We change variables \( y = x - (s + h)^{\frac{1}{4}} z \) in the first and third integral and \( y = x - s^{\frac{1}{4}} z \) in the second integral, and shorthand \( A = \left( \frac{s + h}{s^{\frac{1}{4}}} \right) \) to obtain,

\[
J_2(x, t) \leq 4 \int_0^t ds \frac{1}{(s + h)^{\frac{1}{4}}} \int dz \left| \phi''(z) - \phi''(Az) \right| \\
+ 4 \int_0^t ds \frac{1}{s^{\frac{1}{4}}} \left( 1 - \frac{s^{\frac{1}{4}}}{(s + h)^{\frac{1}{4}}} \right) \int dz \left| \phi''(z) \right| \\
+ 4 t^\frac{1}{2} \int_0^{(t-1)+} ds \frac{1}{(s + h)^{\frac{1}{4}}} \int dz \left| \phi''(z) - \phi''(Az) \right| m'(x - (s + h)^{\frac{1}{4}} z) \\
+ 4 t^\frac{1}{2} \int_0^{(t-1)+} ds \left( \frac{1}{s^{\frac{1}{4}}} - \frac{1}{(s + h)^{\frac{1}{4}}} \right) \int dy \left| \phi''\left(\frac{x - y}{s^{\frac{1}{4}}} \right) \right| m'(y).
\]

We denote by \( J_{21}, J_{22}, J_{23}, J_{24} \) the four integrals on the right hand side. By \( (3.5) \) and noticing

\[
A - 1 = \left( \frac{s + h}{s^{\frac{1}{4}}} \right)^{\frac{3}{4}} - s^{\frac{3}{4}} = \frac{(s + h)^{\frac{3}{4}} - s^{\frac{3}{4}}}{s^{\frac{3}{4}}((s + h)^{\frac{1}{4}} + s^{\frac{1}{4}})} \\
= \frac{h}{s^{\frac{3}{4}}((s + h)^{\frac{1}{4}} + s^{\frac{1}{4}})((s + h)^{\frac{1}{4}} + s^{\frac{1}{4}})} \leq \frac{h^{\frac{3}{4}}}{s^{\frac{3}{4}}},
\]

\[
J_{21} \leq C \int_0^t ds \frac{1}{(s + h)^{\frac{1}{4}}} \left( \frac{h^{\frac{1}{4}}}{s^{\frac{3}{4}}} \right) = Ch^{\frac{1}{2}} \int_0^{h^{-1}t} d\tau \frac{1}{\tau^{\frac{3}{4}}(1 + \tau)^{\frac{1}{4}}} \leq Ch^{\frac{1}{2}},
\]

while, as \( \phi'' \) is integrable,

\[
J_{22} \leq C \int_0^t ds \frac{1}{s^{\frac{1}{4}}} \left( 1 - \frac{s^{\frac{1}{4}}}{(s + h)^{\frac{1}{4}}} \right) = Ch^{\frac{1}{2}} \int_0^{h^{-1}t} d\tau \frac{(1 + \tau^{\frac{1}{4}} - \tau^{\frac{1}{4}})}{\tau^{\frac{3}{4}}(1 + \tau)^{\frac{1}{4}}} \leq Ch^{\frac{1}{2}}.
\]

To estimate \( J_{23} \) we observe that \( (3.5) \) implies \( |\phi''(z) - \phi''(Az)| \leq C^{\frac{1}{4}} A^{-1} \), and \( dz \)-integration of \( m'(x + (s + h)^{\frac{1}{4}} z) \) gives an extra factor \( (s + h)^{-\frac{1}{4}} \).
Therefore,
\[
J_{23} \leq C t^\frac{1}{4} \int_0^t ds \frac{1}{(s+h)^{\frac{3}{4}}} \left( \frac{h}{s} \right)^{\frac{3}{4}} = C(ht)^{\frac{1}{4}} \int_0^{h^{-1}t} d\tau \frac{1}{\tau^{\frac{3}{4}}(1+\tau)^{\frac{3}{4}}} \leq C(ht)^{\frac{1}{4}}.
\]
Analogously, as \( \phi'' \) is bounded and \( \overline{m}' \) is integrable we finally have,
\[
J_{24} \leq C(ht)^{\frac{1}{4}} \int_0^{h^{-1}t} d\tau \frac{(1+\tau)^{\frac{3}{4}} - \tau^{\frac{3}{4}}}{\tau^{\frac{3}{4}}(1+\tau)^{\frac{3}{4}}} \leq C(ht)^{\frac{1}{4}}.
\]
We conclude that
\[
J_2(x,t) \leq C\left(h^\frac{1}{2} + (ht)^{\frac{1}{4}}\right). \tag{A.20}
\]
The estimate (4.17) follows from (A.16), (3.9), (A.17), (A.18), and (A.20).

Acknowledgements

We are indebted to Errico Presutti for stimulating and helpful discussions on the subject of this article. S.B. gratefully acknowledges the kind hospitality and support of the Department of Mathematics of the University of Rome La Sapienza, and of the SPDEs programme held at the Isaac Newton Institute, where part of this research was conducted.

References

[1] Adler, R.J. (1990). An introduction to continuity, extrema, and related topics for general Gaussian processes IMS Lecture Notes - Monograph Series. 12. Hayward, CA: Institute of Mathematical Statistics. vii, 160 p.
[2] Alikakos, N., Bates, P.W. and Fusco, G. (1991). Slow motion for the Cahn-Hilliard equation in one space dimension. J. Differential Equations, 90, 81–135.
[3] Allen, S. and Cahn, J. (1979). A microscopic theory for antiphase boundary motion and its application to antiphase domain coarsening. Acta Metall., 27, 1084–1095.
[4] Antonopoulou, D. C., Blemker, D. and Karali, G. D. (2012). Front motion in the one-dimensional stochastic Cahn-Hilliard equation. SIAM J. Math. Anal., 44, 3242–3280.
[5] Antonopoulou, D. C. and Karali, G. D. (2011). Existence of solution for a generalized stochastic Cahn-Hilliard equation on convex domains. Discrete Contin. Dyn. Syst. Ser. B., 16, 31–55.
[6] Bates, P. W. and Xun, J. (1994). Metastable patterns for the Cahn-Hilliard equation, Part I. J. Differential Equations, 111, 421–457.
[7] Bates, P. W. and Xun, J. (1995). Metastable patterns for the Cahn-Hilliard equation: Part II. Layer dynamics and slow invariant manifold J. Differential Equations, 117, 165–216.
[8] Bertini, L., Brassesco, S. and Buttà, P. (2008). Soft and hard wall in a stochastic reaction diffusion equation. Arch. Ration. Mech. Anal., 190, 307–345.
[9] Bertini, L., Brassesco, S., Buttà, P. and Presutti, E. (2002). Front fluctuations in one dimensional stochastic phase field equations. Ann. Henri Poincaré, 3, 29–86.
[10] Brassesco, S., Buttà, P., De Masi, A. and Presutti, E. (1998). Interface fluctuations and couplings in the \( d = 1 \) Ginzburg-Landau equation with noise. J. Theoret. Probab., 11, 25–80.
[11] Brassesco, S., De Masi, A. and Presutti, E. (1995). Brownian fluctuations of the interface in the \( d = 1 \) Ginzburg-Landau equation with noise. Annal. Inst. H. Poincaré, 31, 81–118.
[12] Bricmont, J., Kupiainen, A. and Taskinen, J. (1999). Stability of Cahn-Hilliard fronts. Comm. Pure Appl. Math., LII, 839–871.

[13] Cahn, J. W. (1961). On spinodal decomposition. Acta Metallurgica, 9, 795–801.

[14] Cahn, J. W. and Hilliard J. E. (1958). Free energy of a nonuniform system. I. Interfacial free energy. J. Chem. Phys., 28, 258–267.

[15] Cahn, J. W. and Hilliard J. E. (1959). Free energy of a nonuniform system II, Thermodynamic basis. J. Chem. Phys., 30, 1121–1124.

[16] Cardon-Weber, C. (2001). Cahn-Hilliard stochastic equation: existence of the solution and of its density. Bernoulli, 7, 777–816.

[17] Da Prato, G. and Debussche, A. (1996). Stochastic Cahn-Hilliard equation. Nonlinear Anal., 26, 241–263.

[18] Funaki, T. (1995). The scaling limit for a stochastic PDE and the separation of phases. Prob. Theory Relat. Fields, 102, 221–288.

[19] Gradshteyn, I. S. and Ryzhik, I. M. (1980). Table of integrals, series, and products. Corrected and enlarged edition edited by Alan Jeffrey. Incorporating the fourth edition edited by Yu. V. Geronimus [Yu. V. Geronimus] and M. Yu. Tseytlin [M. Yu. Tseitlin], Translated from the Russian. Academic Press [Harcourt Brace Jovanovich, Publishers], New York-London-Toronto, Ont., xv+1160 pp.

[20] Hohenberg, P. C. and Halperin, B. I. (1977). Theory of dynamic critical phenomena. Rev. Mod. Phys., 49, 435–479.

[21] Howard, P. (2007). Asymptotic behavior near transition fronts for equations of generalized Cahn-Hilliard form. Comm. Math. Phys., 269, 765–808.

[22] Mandelbrot, B. B. and Van Ness, J. W. (1968). Fractional Brownian motions, fractional noises and applications. SIAM Rev., 10, 422–437.

Lorenzo Bertini, Dipartimento di Matematica, SAPIENZA Università di Roma, P.le Aldo Moro 5, 00185 Roma, Italy
E-mail address: bertini@mat.uniroma1.it

Stella Brassesco, Departamento de Matemáticas, Instituto Venezolano de Investigaciones Científicas, Apartado Postal 20632, Caracas 1020-A, Venezuela
E-mail address: sbailles@ivic.gob.ve

Paolo Buttà, Dipartimento di Matematica, SAPIENZA Università di Roma, P.le Aldo Moro 5, 00185 Roma, Italy
E-mail address: butta@mat.uniroma1.it