Lyapunov stability of flowing MHD plasmas surrounded by resistive walls

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Abstract

A general stability condition for plasma-vacuum systems with resistive walls is derived by using the Frieman Rotenberg lagrangian stability formulation [Rev. Mod. Phys. 32, 898 (1960)]. It is shown that the Lyapunov stability limit for external modes does not depend upon the gyroscopic term but upon the sign of the perturbed potential energy only. In the absence of dissipation in the plasma such as viscosity, it is expected that the flow cannot stabilize the system.

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1 Introduction

In a previous theorem [1] a general instability statement was proved concerning static plasmas surrounded by resistive walls. This statement is related to the problem of resistive wall modes (RWM) in the magnetohydrodynamic (MHD) literature. In particular, the impact of plasma rotation on the mode has been investigated theoretically in Refs.[2]-[8] and experimentally in Refs.[9]-[11]. See also Ref.[12] for mode calculations in a cylindrical case and the recent review paper of Ref.[13]. In the present paper we show that the general Lyapunov analysis can be extended to stationary plasmas surrounded by resistive walls even if their resistivity is time-dependent as investigated in Ref.[14].

In section II we discuss the Lagrangian stability investigation of Ref.[15] in the context of free boundary displacements through an interface between plasma and vacuum. The Lyapunov functional is constructed in section III while conclusions and discussions are left to section IV.

2 Stability equation

The linearized Lagrangian displacement vector $\xi$ about an ideal MHD equilibrium with flow obeys the equations derived in Ref.[15]:

$$\rho_0 \ddot{\xi} + 2 \rho_0 v_0 \cdot \nabla \xi + F \xi = 0,$$

(1)

where $\rho_0$ is the equilibrium mass density and $v_0$ the flow velocity. The antisymmetric $2 \rho_0 v_0 \cdot \nabla$ operator is sometime called the "gyroscopic" operator and $F$ is given by

$$F \xi = \nabla (\gamma p_0 \nabla \cdot \xi + \nabla p_0 - B \cdot Q) + B \cdot \nabla Q + Q \cdot \nabla B + \nabla \cdot (\rho_0 v_0 \cdot \nabla v_0 - \rho_0 v_0 v_0 \cdot \nabla \xi),$$

(2)

where $p_0$ is the equilibrium pressure and $B$ the equilibrium magnetic field. $Q = \nabla \times (\xi \times B)$ is the perturbed magnetic field. The operator $F$ of Eq.(2) contains in particular flow terms so generalizing the corresponding operator of the static case [16].

After fixing the gauge by annihilating the scalar potential, the vector potential $A$ in the region outside the plasma is governed by Ohm's law

$$\nabla \times \nabla \times A = -\sigma A$$

(3)
where $\sigma$ is the space and time dependent conductivity in the outer region. $\sigma$ vanishes for a true vacuum.

At the interface between the plasma and the outer region, we must fulfil the condition

$$n \times A = -(n \cdot \xi)B_0$$

(4)

where $B_0$ is the equilibrium magnetic field at the vacuum side of the interface whose normal vector is $n$. $A$ has to vanish at infinity or be normal to superconducting walls, if there are any. Equations (1) to (4) reduce to the equations (1) to (3) of Ref. [14] if the flow vanishes.

The gyroscopic operator $2 \rho_0 v_0 \cdot \nabla$ is antisymmetric and the scalar product $2 \int \xi \cdot (\rho_0 v_0 \cdot \nabla) \xi d\tau$ as a volume integral vanishes for $n \cdot \xi = 0$ at the plasma boundary. If $n \cdot \xi \neq 0$ at the interface the scalar product vanishes also if the mass density vanishes at the boundary. To make sure that this is true we use

$$\nabla \times (\xi \times \rho_0 v_0) = \rho_0 v_0 \cdot \nabla \xi - \xi \cdot \nabla \rho_0 v_0 - \rho_0 v_0 \nabla \cdot \xi,$$

(5)

$$\nabla (\xi \cdot \rho_0 v_0) = \rho_0 v_0 \cdot \nabla \xi + \rho_0 v_0 \times \nabla \times \xi + \xi \cdot \nabla \rho_0 v_0 + \xi \times \nabla \times \rho_0 v_0.$$  

(6)

Note that the term $\xi \nabla \cdot (\rho_0 v_0)$ has vanishing contribution to Eq. (5) because of the equilibrium continuity equation. Adding equations (5) and (6) we obtain

$$\nabla (\xi \cdot \rho_0 v_0) = 2 \rho_0 v_0 \cdot \nabla \xi - \rho_0 v_0 \nabla \cdot \xi - \nabla \times (\xi \times \rho_0 v_0) + \rho_0 v_0 \times \nabla \times \xi + \xi \times \nabla \times \rho_0 v_0.$$  

(7)

After taking the scalar product of Eq. (7) with $\eta$ and using

$$\nabla \cdot [\eta \times (\xi \times \rho_0 v_0)] = (\xi \times \rho_0 v_0) \cdot \nabla \times \eta - \eta \cdot \nabla \times (\xi \times \rho_0 v_0),$$  

(8)

$$\nabla \cdot [(\eta \cdot \rho_0 v_0)\xi] = (\eta \cdot \rho_0 v_0) \nabla \cdot \xi + \xi \cdot \nabla (\eta \cdot \rho_0 v_0),$$  

(9)

we integrate over the plasma volume and transform the volume integrals of the divergences to surface integrals at the interface to obtain

$$\int_v \eta \cdot (\rho_0 v_0 \cdot \nabla) \xi d\tau = -\int_v \xi \cdot (\rho_0 v_0 \cdot \nabla) \eta d\tau$$

(10)

if either $n \cdot \xi = n \cdot \eta = 0$ for internal modes or $\rho_0 v_0 = 0$ at the interface for external modes.
3 Lyapunov functional

Taking the scalar product of Eq.(1) with $\dot{\xi}$ and Eq.(3) with $\dot{A}$ and integrating over the plasma volume and the vacuum region respectively we obtain

$$\frac{d(K + W)}{dt} = -(\sigma \dot{A}, \dot{A})$$  \hspace{1cm} (11)

where

$$W = \frac{\langle \xi, F\xi \rangle_p + (A, \nabla \times \nabla \times A)_{or}}{2},$$

$$K = \frac{\langle \rho \dot{\xi}, \dot{\xi} \rangle_p}{2},$$

the subscripts $p$ and $or$ being related to the plasma and the outer region respectively. The parentheses denote the scalar products

$$(\eta, \mu)_p = \int_p (\eta, \mu) d\tau,$$

$$(\eta, \mu)_{or} = \int_{or} (\eta, \mu) \tau.$$

Since $\sigma$ is positive, the quantity $K + W$ has a negative time derivative for external modes according to Eq.(11). This allows us to apply the method of Lyapunov, which states that if $K + W$ has no definite sign, then the system is "Lyapunov unstable". For internal modes with $A = 0$ the condition is only sufficient. The Hermitian form $W$ could be minimized in the same way as the $\delta W$ of the energy principle [16] for static MHD equilibria, but no numerical code for minimizing $W$ has been developed yet. For a straight tokamak with homogeneous axial flow and without walls $W$ is indefinite if it is indefinite in the static case. This follows from the fact that the stability property does not depend upon the inertial frame chosen. Therefore, according to the above Lyapunov study the introduction of resistive walls cannot stabilize the plasma-wall system with finite constant plasma velocity. One should note, however, that Lyapunov stability is equivalent to spectral stability if all modes of the spectrum are considered. This is not in agreement of the result of Ref.[6]. In general, the entire spectrum of the plasma-wall system is not as easy to investigate as the determination of the sign of $W$.

Eq.(11) reduces to Eq.(4) of Ref.[1, 14] if the velocity terms in $F$ vanish. It extends the Lyapunov functional introduced in Ref.[1, 14] to the present
general flow case. This means that if $W$ is positive definite the system is stable, but if it is indefinite the system is unstable. So the gyroscopic operator does not affect stability of external modes but growth rates, eigenvalues and eigenfunctions only.

4 Discussion and conclusions

The question of stability of external modes for toroidal ideal plasmas with flows surrounded by resistive walls is decided by the sign of the symmetric potential operator only, which is a drastic simplification so that numerical investigation of stability becomes only slightly more difficult than in the static case for which many codes have been developed.

Moreover the Lyapunov stability property holds also for internal modes if a dissipation operator is added to the gyroscopic operator in (1) since this addition would not change the sign of the right hand side of (11). However, if we add a viscosity to the physical system under investigation then (1) would be modified by such an operator acting on $\dot{\xi}$ but also by another operator acting on $\xi$ which represents the ”circulatory” forces as considered in Ref.17. The operator on $\dot{\xi}$ is proportional to the viscosity itself but the ”circulatory” operator goes with viscosity times the velocity $v_0$. Only the latter operator can modify the stability property, so a minimum velocity is needed for this operator to be able to stabilize the system. However, the quantitative investigation of such situations is difficult as explained in Ref.17 and Ref.18. We should also mention that the plasma viscosity is a tensor known only in the collisional regime while a convincing derivation for the weak collisionality regime of fusion plasmas has not been done yet. Therefore, it may turn out that the stability of hot plasmas must be treated by kinetic equations like Vlasov or Fokker-Planck for which the present stability procedure does not apply.

Finally, if for physical interpretations of the experiment, eigenmodes and growth rates of (1) to (4) (and possibly nonlinear effects) are needed, then the investigation of such situations will be much more difficult especially for toroidal plasmas. Numerical techniques for the search of complex eigenvalues must be developed in the first place. (See e.g. [19]).
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