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Theory and experiment testing flux-line cutting physics

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Abstract

We discuss predictions of five proposed theories for the critical state of type-II superconductors accounting for both flux cutting and flux transport (depinning). The theories predict different behaviours for the ratio $E_x/E_z$ of the transverse and parallel components of the in-plane electric field produced just above the critical current of a type-II superconducting slab as a function of the angle of an in-plane applied magnetic field. We present experimental results measured using an epitaxially grown YBCO thin film favouring one of the five theories, i.e. the extended elliptic critical-state model. We conclude that when the current density $J$ is neither parallel nor perpendicular to the local magnetic flux density $B$, both flux cutting and flux transport occur simultaneously when $J$ exceeds the critical current density $J_c$, indicating an intimate relationship between flux cutting and depinning. We also conclude that the dynamical properties of the superconductor when $J$ exceeds $J_c$ depend in detail upon two nonlinear effective resistivities for flux cutting ($\rho_c$) and flux flow ($\rho_f$) and their ratio $r = \rho_c/\rho_f$.

(Some figures in this article are in colour only in the electronic version)

1. Introduction

To understand the physics of how magnetic flux enters a type-II superconductor under the influence of applied currents and fields is important not only for fundamental reasons but also for potential applications. It is well known that magnetic flux enters in the form of quantized vortices \cite{1}, each carrying magnetic flux $\phi_0 = \hbar/2e$ concentrated within an area of the order of $\lambda^2$, where $\lambda$ is the London penetration depth. In the case of greatest practical interest, when the intervortex spacing is much smaller than $\lambda$, the macroscopic magnetic flux density $B$ (averaged over a few intervortex spacings) has magnitude $B = n\phi_0$, where $n$ is the local areal density of vortices.

The orientation of $B$ serves as a local reference direction. The Lorentz force per unit volume on the vortex array is $F = J \times B$. When $F$ exceeds the local pinning force density $F_p$, the vortices generally move with a velocity $v$ in the direction of $F$, thereby producing an electric field \cite{2} $E = B \times v$. In most cases of practical interest, such as in superconducting magnets, the magnetic induction in the superconductor produced by the self-fields is perpendicular to the current direction. To calculate quantities of practical interest, such as ac losses, one may then use the well-known critical-state theory \cite{3–7}, which assumes that $B$ and $J$ are perpendicular to each other and $E$ is perpendicular to $B$. This critical-state theory characterizes the threshold for depinning in terms of a critical current density $J_{c\perp} = F_p/B$, where here we use the subscript $\perp$ as a reminder that this refers to the case where $J$ is perpendicular to $B$.  

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It has been known for many years, however, that when a type-II superconducting wire in a parallel magnetic field carries a current above the wire’s critical current, a finite electric field appears along the length of the wire [8]. Inside the wire, there must be a place where $J$, $E$, and $B$ are parallel, not perpendicular. This parallel component of the electric field cannot be understood in terms of the collective motion of an array of unbroken vortices but can be understood as a consequence of flux-line cutting, the intersection and cross-joining of locally nonparallel vortices [5, 8]. This is the analogue of the process of vortex-line reconnection in turbulent superfluid $^4$He, recently filmed by Paoletti et al [9]. Flux-line cutting can be triggered by the helical vortex expansion instability [10], in which initially straight vortex lines subjected to a sufficiently large current density are susceptible to the growth of helical perturbations. In this paper we use $J_{\parallel}$ to denote the critical current at the threshold for flux-line cutting, where we use the subscript $\parallel$ as a reminder that this refers to the case where $J$ is parallel to $B$.

Although the behaviour of type-II superconductors is well understood for the case where $J$ is perpendicular to $B$, the theory for the case where $J$ has components both perpendicular and parallel to $B$ is still in a state of development. Such a theory is needed, for example, to calculate the ac losses in power transmission cables consisting of helically wound superconductors when $J$ is still in a state of development. Such an approach has been referred to as the generalized double critical-state model (GDCSM) [10].

In this paper, we report in section 7 measurements of applied magnetic fields tilted out of plane but without in-plane components, which can drive the vortices either inward or outward in the radial direction, but also parallel components, which can lead to local helical instabilities and subsequent flux-line cutting [10]. It is the purpose of this paper to contribute towards the development of a critical-state theory accounting for both flux transport and flux cutting.

In sections 2–6 we discuss the different predictions of five theoretical critical-state models for how the critical current density $J$, and the electric field $E$ (for $J$ just above $J_c$) should vary with the angle between $J$ and $B$. While there has been previous experimental work on flux cutting in thin films with applied magnetic fields tilted out of plane but without in-plane angular rotation [12, 13], we report in section 7 measurements with angular rotation of in-plane applied fields to test the theoretical predictions of the five models. We compare the experimental results with the predictions in section 8, and we summarize our conclusions in section 9.

2. Generalized double critical-state model (GDCSM)

In an attempt to describe the fundamentals of the behaviour of a type-II superconductor subjected to time-varying fields and currents in situations where the current density $J$ is not perpendicular to $B$, a theory was proposed in [14–18]. This approach has been referred to as the generalized double critical-state model (GDCSM).

Consider an infinite type-II superconducting slab centred on the $yz$ plane. Suppose that in the absence of an applied current, an applied magnetic field produces a magnetic flux density $B_0 = B_0 \hat{z} \alpha_0$ in the slab, where $\alpha_0 = \hat{y} \sin \alpha_0 + \hat{z} \cos \alpha_0$. Consider now what happens when the slab carries an average current density $J$. As a consequence of the self-field, vortices may be introduced, altering the magnetic flux density inside the slab to $B(x) = B(x) \hat{z} \alpha$, where $\alpha(x) = \hat{y} \sin \alpha(x) + \hat{z} \cos \alpha(x)$. The current density $J$ also depends upon $x$.

Referring now to figure 1, let us resolve the current density and the electric field into components parallel and perpendicular to $B$: $J = J_\parallel \hat{y} + J_\perp \hat{z} = J_0 \hat{z} + J_\perp \hat{\beta}$ and $E = E_\parallel \hat{y} + E_\perp \hat{z} = E_0 \hat{\alpha} + E_\perp \hat{\beta}$, where $\hat{\beta} = \hat{y} \cos \alpha - \hat{z} \sin \alpha = \hat{\alpha} \times \hat{\beta}$. In high-$\kappa$ superconductors when $B_0$ is sufficiently above $B_{c1}$, it is a good approximation to take $B = \mu_0 H$ inside the superconductor. In the steady state, Ampère’s and Faraday’s laws ($J = \nabla \times H$, $\nabla \times E = 0$, with all quantities independent of time) then yield [18]

\begin{align*}
J_\parallel &= J \cos \phi = \frac{B}{\mu_0} \frac{d \alpha}{dx}, \\
J_\perp &= J \sin \phi = -\frac{1}{\mu_0} \frac{dB}{dx}, \\
\frac{dE_\parallel}{dx} &= 0, \\
\frac{dE_\perp}{dx} &= 0, \\
E_\parallel \frac{d \alpha}{dx} + \frac{dE_\perp}{dx} &= 0.
\end{align*}

The GDCSM was based on the fundamental ideas that a nonvanishing $E_\perp$ can occur only when the magnitude of $J_\parallel$ is above $J_{c\parallel}$, the critical current density for flux depinning, and that a nonvanishing $E_\parallel$ can occur only when the magnitude of $J_\parallel$ is above $J_{c\parallel}$, the critical current density for flux cutting. It was assumed in [18] that the superconducting material was isotropic and that the pinning centres were
isotropically distributed, such that \( J_{c\perp} \) and \( J_{c\parallel} \) could depend upon the temperature \( T \) but only upon the magnitude \( B \) of the magnetic induction \( B \) inside the sample. For thin samples, the current-induced self-field is much smaller than the applied magnetic induction \( B_0 \), so that \( J_{c\perp} \) and \( J_{c\parallel} \) were taken as constants independent of \( x \). The possible complications of surface pinning or surface barriers were ignored. One of the most important assumptions of the GDCSM was that flux depinning and flux cutting do not affect each other; i.e. it was implicitly assumed that \( J_{c\perp} \) was independent of \( J_1 \) and \( J_0 \) was independent of \( J_{c\perp} \).

Figure 2 provides a graphical display of the behaviour of the vortex array as a function of \( J_{c\perp} = J \sin \phi \) and \( J_{c\parallel} = J \cos \phi \) according to the GDCSM. In the middle of the open rectangle, the 0 zone, for which \( |J_{c\perp}| < J_{c\perp} \) and \( |J_{c\parallel}| < J_{c\parallel} \), neither flux transport (depinning) nor flux-line cutting occurs; i.e. both \( E_{c\perp} \) and \( E_{c\parallel} \) are zero. Flux transport (without flux-line cutting) occurs only in the zones labelled by \( T_+ \left( J_{c\perp} > J_{c\perp} \right) \) and \( E_{c\perp} > 0 \) or \( T_- \left( J_{c\perp} < -J_{c\perp} \right) \) and \( E_{c\perp} < 0 \). Flux-line cutting (without flux transport) occurs only in zones labelled by \( C_+ \left( J_{c\perp} > J_{c\perp} \right) \) and \( E_{c\parallel} > 0 \) or \( C_- \left( J_{c\parallel} < -J_{c\parallel} \right) \) and \( E_{c\parallel} > 0 \). Simultaneous flux transport \((|J_{c\perp}| > J_{c\perp} \) and \( |E_{c\parallel}| > 0 \) and flux-line cutting \((|J_{c\parallel}| > J_{c\parallel} \) and \( |E_{c\perp}| > 0 \)) occurs only in the zones labelled by \( C_+ T_+ \), \( C_- T_+ \), \( C_+ T_- \), and \( C_- T_- \).

According to the GDCSM, for given values of \( J_{c\perp} \) and \( J_{c\parallel} \), the critical current density \( J_c \) at the first onset of a nonvanishing electric field depends upon the angle \( \phi \). For \( \phi = \pi/2 \) (\( J \perp B \)), the critical current density for the onset of an electric field is the usual depinning critical current density, such that \( J_c = J_{c\perp} \). On the other hand, for \( \phi = 0 \) (\( J \parallel B \)), the critical current density for the onset of an electric field is the current density at the threshold for flux-line cutting, and \( J_c = J_{c\parallel} \). For other values of \( \phi \), we have

\[
J_c = \frac{J_{c\perp}}{| \sin \phi |}, \quad | \tan \phi | \geq \tan \phi_c, \quad (7)
\]

\[
= \frac{J_{c\parallel}}{| \cos \phi |}, \quad | \tan \phi | \leq \tan \phi_c, \quad (8)
\]

where \( \tan \phi_c = J_{c\perp}/J_{c\parallel} \). As is evident from figure 2 and (7) and (8), this model predicted that \( J_c \) as a function of \( \phi \) has cusp-like maxima at \( \phi = \pm \phi_c \) and \( \phi = \pm (\pi - \phi_c) \), where \( J_c = \sqrt{J_{c\perp}^2 + J_{c\parallel}^2} \). For example, the dashed curve in figure 3 maps the magnitude of \( J \) as a function of \( \phi \) as the tip of the vector \( J \) traces the boundary of the 0 zone shown in figure 2. The rectangular shape of the 0 zone in figure 2 arises from the assumptions of the GDCSM [14–18] that (a) the threshold \( J_{c\perp} \) for depinning is independent of the current density \( J_1 \) parallel to the vortices and (b) the threshold \( J_{c\parallel} \) for flux-line cutting is independent of the current density \( J_1 \) perpendicular to the vortices.

Another prediction of the GDCSM [18] was that, in accord with figure 2, measurements of the angle of the electric field \( E \) just above the critical current as a function of the angle \( \phi \) between \( J \) and \( B_0 \) would show sharp changes at \( |\phi| = \phi_c = \tan(J_{c\perp}/J_{c\parallel}) \) and \( |\phi| = \pi - \phi_c \). If \( J \) is constrained by geometry to flow only in the \( z \) direction, then above the critical current density, where \( J = J_{c\perp} \) and \( B = B_0(\hat{y} \sin \alpha_0 + \hat{z} \cos \alpha_0) \), we have \( \phi = -\alpha_0 \), so that \( E = E_\parallel \hat{y} + E_\perp \hat{z} = E_\parallel \hat{a} + E_\perp \hat{b} \), where \( \hat{a} = \hat{y} \sin \alpha_0 + \hat{z} \cos \alpha_0 \) and \( \hat{b} = \hat{y} \cos \alpha_0 - \hat{z} \sin \alpha_0 \). The GDCSM prediction was that when
Plots of the electric field ratio $E_y/E_z$ versus $\alpha_0$ for five theoretical models accounting for flux-line cutting. The predictions of the GDCSM and the Brandt–Mikitik model (BMM) (dashed line, equation (9) and (10)) and the original elliptic critical-state model (OECSM, dot-dashed line, equation (20)) are all shown for

$$
\tan \phi = J_{\perp}/J_{\parallel} = 0.4, \text{ for which } \phi = \tan^{-1}(J_{\perp}/J_{\parallel}) = 21.8^\circ.
$$

Also shown is the behaviour of $E_y/E_z$ predicted by the extended elliptic critical-state model (EECSM, solid line, equation (24)) for an assumed value of $r = 0.04$, and that of the Badía-Majós, López, and Ruiz model (BLRM, dotted line, equation (25)) for $\tan^2 \phi = (J_{\perp}/J_{\parallel})^2 = 0.02$.

The dashed curve in figure 4 shows the behaviour of $E_y/E_z$ predicted by the GDCSM.

3. Brandt and Mikitik model (BMM), extending the GDCSM model

Brandt and Mikitik [19] proposed an extension (here called the BMM) of the GDCSM, in which the threshold for flux-line cutting is reduced as a function of the magnitude of $J_{\perp}$ and the threshold for depinning is reduced as a function of the magnitude of $J_{\parallel}$. If these thresholds were bent enough, the shape of the surface of $J_{\parallel}(\phi)$ could be made to resemble an ellipse, as suggested by figure 1 of [19], thereby eliminating the cusp-like behaviour predicted by the GDCSM. In fact, if the BMM $J_{\parallel}(\phi)$ curve had the shape of an ellipse, it would be in exact agreement with the solid curve shown in figure 3.

However, the BMM retained the assumption of the GDCSM that the electric field $E$ is parallel to the $J_{\parallel}$ axis on the flux-cutting-threshold portions of the $J_{\parallel}(\phi)$ curve closest to the $J_{\parallel}$ axis and that $E$ is parallel to the $J_{\perp}$ axis on the flux-transport-threshold portions of the $J_{\perp}(\phi)$ curve closest to the $J_{\perp}$ axis. Thus, in common with the GDCSM, the BMM predicts a 90° change in the direction of $E$ when $\phi$ passes through the point of intersection of the curves representing the thresholds for flux cutting and flux transport. If this intersection occurs when $|J_{\perp}/J_{\parallel}| = J_{\perp}/J_{\parallel}$, then the shape of the $E_y/E_z$ curve agrees exactly with that of the GDCSM, as shown in figure 4.

4. Original elliptic critical-state model (OECSM)

Experimental results of Fisher et al [20, 21] on the time evolution of the static magnetic moment of a superconducting plate subjected to an alternating magnetic field applied perpendicular to a dc magnetic field were found not to be well described theoretically by calculations based on the GDCSM. However, Romero-Salazar and Pérez-Rodríguez [22–24] introduced an elliptic critical-state model, which they found yielded good theoretical agreement with the experiments of [20, 21].

Figure 5 provides a graphical display of the behaviour of the vortex array as a function of $J_{\parallel} = J \sin \phi$ and $J_{\parallel} = J \cos \phi$ according to the elliptic critical-state model [22–24]. We interpret this behaviour as follows: in the 0 zone inside the ellipse described by

$$
\frac{\sin^2 \phi}{J_{\perp}(B)^2} + \frac{\cos^2 \phi}{J_{\parallel}(B)^2} = \frac{1}{J_c(B, \phi)^2} \tag{11}
$$

Figure 4.

Figure 5.
neither flux transport (depinning) nor flux cutting occurs \((E_\perp = 0\) and \(E_z = 0\)). Flux transport, for which the vortices are depinned \((E_z \neq 0)\), occurs everywhere outside the ellipse (except when \(J_z = 0\) in zones with labels including the symbol \(T_z(\perp J_z > 0)\) or \(T_z(\perp J_z < 0)\). Flux-line cutting, for which \(E_z \neq 0\), occurs everywhere outside the ellipse (except when \(J_z = 0\)) in zones with labels including the symbol \(C_z(\perp E_z > 0)\) or \(C_z(\perp E_z < 0)\). In this model, both flux transport and flux-line cutting occur simultaneously nearly everywhere outside the ellipse of \(J_c(\phi)\) versus \(\phi\). The solid curve in figure 3 gives an example of the behaviour of \(J_c\) versus \(\phi\) using the elliptic critical-state model.

We note here that the behaviour at the critical current according to the elliptic critical-state model (see figure 5) requires that flux depinning and flux cutting be interdependent. To formulate this, we introduce the following new notation for the critical current densities at the thresholds for flux depinning \(J_{cd}(B, \phi)\) and flux cutting \(J_c(B, \phi)\), where \(\phi\) is the angle between \(J\) and \(B\), as in figure 1. Our interpretation of the underlying physics of the elliptic critical-state model [22–24] is that (a) the threshold \(J_{cd}\) for depinning is a monotonically decreasing function of the magnitude of \(J_z\), decreasing from \(J_{cd}\) when \(J_z = 0\) to zero when \(J_z = J_{cd}\), and (b) the threshold \(J_c\) for flux-line cutting is a monotonically decreasing function of the magnitude of \(J_z\), decreasing from \(J_c\) when \(J_z = 0\) to zero when \(J_z = J_{cd}\). In summary, at the critical current density, \(J = J_c(B, \phi)\), and \(J\) lies on the ellipse of (12), as shown in figure 5, such that \(|J_z| = J_{cd}(B, T) = J_{cd}(B, \phi)\sin \phi|, |J_y| = J_{cc}(B, T) = J_c(B, \phi)|\cos \phi|, and

\[
J_c(B, \phi) = \frac{J_{cd}(B)}{\sqrt{\sin^2 \phi + \tan^2 \phi \cos^2 \phi}}, (13)
\]

where \(\tan \phi_e = J_{cd}(B) / J_{cd}(B)\). Note that within this model

\[
J_{cd}(B) = J_{y}(B, \pi/2)\text{ and } J_{cc}(B) = J_{y}(B, 0).
\]

Further fundamental assumptions of the original elliptic critical-state model [22–24] are that the electric field obeys

\[
E(J) = 0, \quad J \leq J_c(B, \phi), (14)
\]

\[
= \rho[J - J_c(B, \phi)], \quad J > J_c(B, \phi), (15)
\]

and that the components of \(E\) perpendicular and parallel to \(B\) obey [22–24]

\[
E_\perp / E = J_\perp / J_{\perp}, (16)
\]

\[
E_\parallel / E = J_\parallel / J_{\parallel}. (17)
\]

If the current is constrained by geometry to flow only in the \(z\) direction, then at the critical current density, when \(J = \hat{z} J_c\) and \(B = B_0(\hat{y} \sin \alpha_o + \hat{z} \cos \alpha_o)\), we have \(\phi = -\alpha_o\), such that \(J_y = J_c \cos \alpha_0\) and \(J_z = -J_c \sin \alpha_0\) (see figure 1) and

\[
E_\perp / E = -(J_\perp / J_{\perp}) \sin \alpha_0, (18)
\]

\[
E_\parallel / E = (J_\parallel / J_{\parallel}) \cos \alpha_0. (19)
\]

Since \(E = E_y \hat{y} + E_z \hat{z} = E_\perp \hat{\alpha} + E_\parallel \hat{\beta}\) and \(E_\parallel / E_\perp = -(J_\perp / J_{\perp}) / \tan \alpha_0\), we have

\[
\frac{E_y}{E_z} = \frac{(E_\parallel / E_\perp) \tan \alpha_o + 1}{(E_\parallel / E_\perp) - \tan \alpha_o} = \frac{(\tan \phi_e - 1) \tan \alpha_0}{\tan \phi_e + \tan^2 \alpha_0}, (20)
\]

where \(\tan \phi_e = J_{\parallel}(B) / J_{\parallel}(B)\). Experiments generally yield \(\tan \phi_e < 1\). According to this form of the elliptic critical-state model, as a function of \(\tan \alpha_0, E_z / E_\parallel\) has extrema (a maximum and a minimum) when \(\tan \alpha_0 = \mp \tan \phi_e\), where \(E_z / E_\parallel = \pm 1 - \tan \phi_e / 2 \tan \phi_e\). The dot-dashed curve in figure 4 shows the behaviour of \(E_z / E_\parallel\) predicted by the OECSM [22–24], (20).

5. Extended elliptic critical-state model (EECSM)

However, the OECSM [22–24] suffers from an important deficiency. By summing the squares of (16) and (17), we obtain

\[
\left(\frac{E_\perp}{E}\right)^2 + \left(\frac{E_\parallel}{E}\right)^2 = 1 = \left(\frac{J_\perp}{J_{\perp}}\right)^2 + \left(\frac{J_\parallel}{J_{\parallel}}\right)^2. (21)
\]

The right-hand side can be equal to one only when \(J_\parallel = J_{\parallel}\), as can be seen by making use of (18), (19), and (11). However, when \(J = J_c\), we must have \(E = 0\). Therefore, additional equations are required in order to apply the elliptic critical-state model to finite values of the electric field when \(J > J_c\), where the dynamical processes of flux transport and flux cutting become important.

We therefore propose an extension of the elliptic critical-state model to account for dissipative processes when \(J > J_c\) by writing

\[
E_\perp = \rho_1 J_\perp, (22)
\]

\[
E_\parallel = \rho_1 J_\parallel, (23)
\]

where \(\rho_1\) is a nonlinear function of \(J, B, \alpha_0, T\) and with a positive value describing flux flow and \(\rho_2\) is another nonlinear function of \(J, B, \alpha_0, T\) and with a positive value describing flux cutting. In the absence of flux creep, \(\rho_1\) is zero when \(|J_\parallel|\) is less than the threshold \(J_{\parallel}\) for depinning, and \(\rho_1\) is zero when \(|J_\parallel|\) is less than the threshold \(J_{\parallel}\) for flux cutting. To clarify what we mean by a threshold for flux-line cutting, consider starting with the sample carrying a current for which \(J_0 = 0\) and \(0 < J_\parallel < J_{\parallel}\), such that \(E = 0\). If \(J_\parallel\) is increased above the threshold value \(J_{\parallel}\), flux-line cutting begins \((E_\parallel > 0)\). In other words, when \(J > J_c(\phi)\), flux cutting and flux transport occur simultaneously; the thresholds for flux cutting and flux transport are intimately linked.

If the current is constrained by geometry to flow only in the \(z\) direction, then at the critical current density, when \(J = \hat{z} J_c\) and \(B = B_0(\hat{y} \sin \alpha_o + \hat{z} \cos \alpha_o)\), we have \(\phi = \alpha_o\), such that \(J_y = J_c \cos \alpha_0\) and \(J_z = J_c \sin \alpha_0\) (see figure 1) and

\[
E_\perp / E = -(J_\perp / J_{\perp}) \sin \alpha_0, (18)
\]

\[
E_\parallel / E = (J_\parallel / J_{\parallel}) \cos \alpha_0. (19)
\]

where now \(r = \rho_c / \rho_1\), which must be a positive number.
Note that (24) has the same mathematical form as (20), except that \( \tan \phi_o \) is replaced by \( r \). According to this extension of the theory, \( E_y/E_z \) does not depend at all upon \( \tan \phi_o = J_{\perp}/J_{\parallel} \) but instead depends upon \( r \), the ratio of the effective flux-cutting resistivity to the effective flux-flow resistivity. If \( r \) is independent of \( \tan \alpha_0 \), \( E_y/E_z \) has extrema (a maximum and a minimum) when \( \tan \alpha_0 = \mp \sqrt{r} \), where \( E_y/E_z = \pm (1 - r)/2\sqrt{r} \). The parameter \( r \) thus plays a crucial role in describing the dynamical properties of the mixed state above the critical current density \( J_c \). Unfortunately, experiments to date typically do not report values of \( \rho_c \) and \( \rho_t \), from which \( r = \rho_c/\rho_t \) could be independently measured.

The solid curve in figure 4 shows the behaviour of \( E_y/E_z \) predicted by this EECSM (24) for an assumed value of \( r = 0.04 \).

6. Badía-Majós, López, and Ruiz model (BLRM)

In [25], Badía-Majós et al argued that for \( J \) just above \( J_c(\phi) \), the direction of the electric field should be perpendicular to the \( J_c(\phi) \) curve. Under the same conditions leading to equations (20) and (24), their model (here called the BLRM) leads to the expression

\[
\frac{E_y}{E_z} = \frac{1}{J_c(\alpha_0)} \frac{dJ_c(\alpha_0)}{d\alpha_0} = \frac{(\tan^2 \phi_c - 1) \tan \alpha_0}{\tan^2 \phi_c + \tan^2 \alpha_0},
\]

where the latter equation applies when \( J_c(\phi) \) is given by the ellipse of (12) (see figure 5) and \( \tan \phi_c = J_{\perp}/J_{\parallel} \). The dotted curve in figure 4 shows the behaviour of \( E_y/E_z \) predicted by the BLRM for an assumed value of \( \tan^2 \phi_c = (J_{\perp}/J_{\parallel})^2 = 0.02 \).

7. Experiment

We next report experiments to test the fundamental assumptions of the above-described theories. While the predictions have been made for an infinite superconducting slab, we have carried out experiments on a current-carrying superconducting film of finite dimensions subjected to an in-plane magnetic field. We have assumed that the effects of finite dimensions and self-fields are small enough that the theoretically predicted effects dominate and the experiments can determine which of the proposed theories is correct.

A sketch of the measured device, a YBCO film of thickness 500 nm, is shown in figure 6. The track is of width \( w_y = 200 \mu m \), and two sets of voltage taps are positioned along its length, \( w_z = 3000 \mu m \) apart from each other. The voltage/current taps are labelled A, B, C, D, E, F, G, H, K, L, A’, B’. A two-axis goniometer [26] was employed to measure the longitudinal and transverse voltage simultaneously by a four-terminal technique, using the two channels of the employed voltmeter, while a magnetic field was swept in-plane. For all measurements the current \( I \) was injected through the taps A and B and taken out through A’ and B’, such that the current direction was (A, B) \( \rightarrow \) (A’, B’), i.e. in the positive z direction. The current was applied in short pulses to minimize sample heating. Longitudinal and transverse voltages were measured using combinations of the taps C, . . . , L.

The applied field was oriented to be in the plane of the film, such that angle \( \theta \) between the applied field and the film normal \( \vec{n} \) was as close as possible to 90°, as described below. The current density \( J \) was constrained to flow in the z direction, while the angle \( \alpha = \alpha_0 \) of the applied magnetic induction \( B_0 \) was oriented as shown in figure 1, such that the angle of \( J \) relative to \( B_0 \) was \( \phi = -\alpha_0 \).

In order to align the sample such that \( B_0 \parallel ab \), measurements of \( J_c(\theta) \) were performed at \( \phi = \pm 90^\circ \), corresponding to maximum Lorentz force (\( B_0 \perp J \)). The angle \( \theta = 90^\circ \) (where \( B_0 \parallel ab \)) was assumed to be reached where \( J_c(\theta) \) reached a maximum, and the following in-plane scans were performed with this value of \( \theta \).

For the reported measurements, \( J_c \) was determined from \( V_c(I) \) curves only, where \( V_c \) is the voltage measured along the length of the track (e.g. by using taps C and G). For each value of \( \alpha_0, I_c \) was determined as the current where \( V_c \) reaches the selected voltage criterion \( V_c \). The transverse voltage \( V_y(I) \) was measured simultaneously (e.g. using taps G and H). The voltages were then converted to electric fields \( E_z = V_c/w_z \) and \( E_y = V_y(I)/w_y \) in order to obtain \( E_y/E_z \) as a function of \( \alpha_0 \).

Figure 7 presents plots of \( E_y/E_z \) versus \( \alpha_0 \) obtained at \( T = 85 \) K and \( \mu_0 H = 1 \) T for voltage criteria \( V_c = 15 \) \( \mu V \) (square symbols), 30 \( \mu V \) (dots), 60 \( \mu V \) (triangles), and 150 \( \mu V \) (inverted triangles). Note that the scatter in the values of \( E_y/E_z \) becomes smaller with increasing values of \( V_c \). In the raw data, \( E_y/E_z \) reached zero at a value of \( \alpha_0 = +3^\circ \). This could be understood by the fact that the alignment of the in-plane angle was performed by visual inspection prior to sample mounting. Consequently, we shifted the curves by \(-3^\circ \) in \( \alpha_0 \), so that \( E_y/E_z = 0 \) at \( \alpha_0 = 0^\circ \) in all the plots shown here and later. The solid curve in figure 7 shows the function...
to flux transport in the absence of flux-line cutting.

Figure 7. The measured ratio $E_y/E_z$ versus $\alpha_0$ at $T = 85$ K and $\mu 0H = 1$ T. The solid curve is $E_y/E_z = -\cot \alpha_0$ (9), expected due to flux transport in the absence of flux-line cutting.

\[ E_y/E_z = -\cot \alpha_0 \] (9)

$E_y/E_z$ is the result that would be expected for no flux-line cutting, i.e. when $E_1 = 0$, $E \perp B_0$, and $E = E_y \hat{y} + E_z \hat{z} = E_\perp \hat{\beta} = E_\perp (\hat{y} \cos \alpha_0 - \hat{z} \sin \alpha_0)$. (Note from figure 1 that in this experiment $\phi = -\alpha_0$, so that when $\alpha_0 > 0$, we have $E_z > 0$, $E_y < 0$, and $E_\perp < 0$.)

Similar measurements were also performed at $T = 77.35$ K and $\mu 0H = 8$ T for $V_c = 15$ $\mu$V (square symbols) and 60 $\mu$V (triangles), and the results are shown in figure 8. Note that, as in figure 7, the scatter in the values of $E_y/E_z$ becomes smaller with increasing values of the voltage criterion $V_c$.

The data presented in figures 7 and 8 show results measured at constant $E_z$, but we also did an analysis making use of the saved $V(I)$ data of both voltmeter channels to construct corresponding plots of $E_y/E_z$ versus $\alpha_0$ at constant $E_{tot} = \sqrt{E_y^2 + E_z^2}$. While there were some differences from the results for constant $E_z$ for the smallest values of $V_c$, these were not significant for the larger values of $V_c$.

Figure 8. The measured ratio $E_y/E_z$ versus $\alpha_0$ at $T = 77.35$ K and $\mu 0H = 8$ T. The solid curve is $E_y/E_z = -\cot \alpha_0$ (9), expected due to flux transport in the absence of flux-line cutting.

8. Comparison with theoretical predictions

Shown in figure 9 are the critical current densities $J_c$ versus $\alpha_0$ measured at $T = 85$ K and $\mu 0H = 1$ T (inverted triangles) and at $T = 77.35$ K and $\mu 0H = 8$ T (open circles), both with the voltage criterion $V_c = 60$ $\mu$V, which corresponds to $E_z = 20$ mV m$^{-1}$. The corresponding solid curves are fits to the data using the elliptic critical-state model: at $T = 85$ K and $\mu 0H = 1$ T, $J_c = 2.65 \times 10^9$ A m$^{-2}$ and $J_{\perp} = 0.895 \times 10^9$ A m$^{-2}$ at 85 K and $J_{\perp} = 7.86 \times 10^9$ A m$^{-2}$ and $J_{\perp} = 2.06 \times 10^9$ A m$^{-2}$ at 77.35 K.

\[ J_c = 2.65 \times 10^9 \text{ A m}^{-2} \]

\[ J_{\perp} = 0.895 \times 10^9 \text{ A m}^{-2} \]

\[ J_{\perp} = 7.86 \times 10^9 \text{ A m}^{-2} \]

\[ J_{\perp} = 2.06 \times 10^9 \text{ A m}^{-2} \]

Figure 9. Critical current density $J_c(V_c = 60 \mu$V, $E_z = 20$ mV m$^{-1}$) versus the angle $\alpha_0$ of the in-plane applied field at 85 K and 1 T (inverted triangles) and 77.35 K and 8 T (open circles). The corresponding solid curves are fits using the elliptic model (12) with $J_{\perp} = 2.65 \times 10^9$ A m$^{-2}$ and $J_{\perp} = 0.895 \times 10^9$ A m$^{-2}$ at 85 K and $J_{\perp} = 7.86 \times 10^9$ A m$^{-2}$ and $J_{\perp} = 2.06 \times 10^9$ A m$^{-2}$ at 77.35 K.

The measured ratio $E_y/E_z = -\cot \alpha_0$ (9), the result that would be expected for no flux-line cutting, i.e. when $E_1 = 0$, $E \perp B_0$, and $E = E_y \hat{y} + E_z \hat{z} = E_\perp \hat{\beta} = E_\perp (\hat{y} \cos \alpha_0 - \hat{z} \sin \alpha_0)$. (Note from figure 1 that in this experiment $\phi = -\alpha_0$, so that when $\alpha_0 > 0$, we have $E_z > 0$, $E_y < 0$, and $E_\perp < 0$.)
\[ \rho = \frac{r}{\alpha} = \frac{\text{constant}}{\text{angle}} \text{ (dotted curve, equation (25)) using the measured } \tan \phi \text{ versus } \alpha \text{ (dotted line, equation (25)) with } \tan \phi = J_{\perp} / J_{\parallel} = 0.338 \text{, the EECSM with } r = \rho_s / \rho_l = 0.090 \text{ (solid line, equation (24)), and the GDCSM and BMM with } \tan \phi = J_{\perp} / J_{\parallel} = 0.338 \text{ (dashed line, equations (9) and (10)).} \]

\[ \alpha_0 \text{ favour the EECSM and the BLRM but do not support the OECSM, the GDCSM, or the BMM.} \]

Figure 11 shows comparisons of the measurements of \( E_x / E_z \) versus \( \alpha_0 \) at \( T = 77.35 \text{ K} \) and \( 8 \text{ T} \) (using the voltage criterion \( V_c = 60 \text{ } \mu \text{V} \)) with the predictions of the OECSM (dot-dashed curve, equation (20)) and the BLRM (dotted curve, equation (25)) using the measured \( \tan \phi_e = J_{e\perp} / J_{e\parallel} = 0.262 \), the EECSM using \( r = \rho_s / \rho_l = 0.026 \) assumed to be independent of \( \alpha_0 \) (solid curve, equation (24)), and the GDCSM and BMM using the measured \( \tan \phi_e = J_{e\perp} / J_{e\parallel} = 0.262 \) (dashed curve, equations (9) and (10)). The theoretical curve for the EECSM can partially account for the large values for the magnitude of the measured \( E_x / E_z \), but the OECSM and the BLRM cannot. The large magnitudes of the experimental values of \( E_x / E_z \) at 77.35 K and 8 T cannot be understood with any of the proposed models without modification.

Although we cannot at present provide a justification for the following assumption, if we assume the following form for theoretical values of \( E_x / E_z \),

\[ \frac{E_x}{E_z} = c \frac{(r - 1) \tan \alpha_0}{r + \tan^2 \alpha_0} \quad (26) \]

we obtain a considerably better fit to the data at 77.35 K and 8 T, as shown in figure 12, where the fit parameters were found to be \( r = 0.080 \) and \( c = 1.936 \).

9. Conclusions

The purpose of this paper has been to compare five theoretical models describing the critical state of type-II superconductors when the current density \( J \) is at an arbitrary angle with respect to the local magnetic flux density \( B \) and then to use experimental measurements of the angular dependence of the critical current density \( J_c \) and the electric field \( E \) (for \( J \) just above \( J_c \)) as a test of these theories.

For simplicity, the geometry of an infinite, macroscopically isotropic type-II superconducting slab of finite thickness centred on the \( yz \) plane was used for calculating the predictions of the five theories. However, the experiments were performed using a thin YBCO film subjected to in-plane currents and magnetic fields, but we assumed that the effects of finite dimensions and self-fields were small enough that the experiments would be able to make a clear distinction among the five theories.
Measurements of the angular dependence of the critical current density \( J_c \) showed that the cusp-like behaviour predicted by the generalized double critical-state model (GDCSM) was not verified. Instead, the angular dependence of \( J_c \) showed a behaviour very similar to that assumed by both the original elliptical critical-state model (OECSM) and the extended elliptical critical-state model (EECSM).

Measurements of the angular dependence of the ratio of the transverse to the longitudinal components of the electric field \( E_y/E_z \) at 85 K and 1 T for \( J \) just above \( J_c \) also showed that the sawtooth-like behaviour predicted by the GDCSM and the Brandt–Mikitik model (BMM) was not verified. While all three elliptical critical-state models predict a smooth angular dependence of \( E_y/E_z \), as found experimentally, the magnitude of \( E_y/E_z \) predicted by the OECSM was too small to account for the experimental values. On the other hand, both the EECSM with \( r = \rho_c/\rho_l = 0.090 \) and the Badía-Majos–López–Ruiz model (BLRM) were found to be in reasonable agreement with the data at 85 K and 1 T. However, the EECSM has the advantage that it is applicable for currents \( J \) well above \( J_c(\phi) \), while the BLRM is currently limited to \( J \) just above \( J_c(\phi) \).

None of the five models was found to provide a good description of the data for \( E_y/E_z \) at 77.35 K and 8 T. A small value of \( r = \rho_c/\rho_l = 0.026 \) within the EECSM can account roughly for the large magnitudes of \( E_y/E_z \), but the resulting theoretical curve does not provide a good fit to the shape of the data. By adding an additional fit parameter to the theoretical expression for \( E_y/E_z \) within the EECSM, better agreement with the magnitude and shape of the data for \( E_y/E_z \) at 77.35 K and 8 T can be obtained, but at present we have no theoretical justification for this assumption. Further theoretical and experimental work to investigate the influence of finite dimensions and self-fields will be needed to shed light on this problem. Our theory assumes homogeneity of the electric field \( E \), but this needs to be confirmed, since earlier experiments measuring the local electric field in the longitudinal geometry found strong inhomogeneities in \( E \) along the sample length [33–37].

The experimental results in this paper call attention to two important features that to date have not been generally recognized. First, when \( J \) is neither parallel nor perpendicular to the local magnetic flux density \( B \), both flux cutting and flux transport occur simultaneously when \( J \) exceeds the critical current density \( J_c \). This indicates the intimate relationship between flux cutting and depinning. Second, the dynamical properties of the superconductor when \( J \) exceeds \( J_c \) depend in detail upon two effective resistivities, \( \rho_c \) and \( \rho_l \), and their ratio \( r = \rho_c/\rho_l \). The consequence of this is that to provide a full description of the properties of type-II superconductors in the resistive state, both \( \rho_c \) and \( \rho_l \) should be measured. It can be shown that in cylindrical geometry, values of \( r < 1 \) are responsible for the paramagnetic moment generated along the length of a current-carrying type-II superconductor above its critical current when it is subjected to a longitudinal applied magnetic field [8].

It seems likely that the angular dependence of the critical current density in type-II superconductors will depend upon the details of the underlying pinning structure, and it is possible that in many cases \( J_c(\phi) \), which can be obtained experimentally, will not be given precisely by the elliptic form given in (11) and (12). For example, \( J_c(\phi) \) may even take the form of a super-ellipse, as suggested in [25] and [32]. In other words, although one should not take the elliptic model too seriously, it seems likely that \( J_c(\phi) \) generally has roughly the shape shown in figure 5, and that it is a general principle that both flux cutting and flux transport occur simultaneously when \( J > J_c(\phi) \).

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