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Computing Abductive Explanations for Boosted Trees

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Abstract

Boosted trees is a dominant ML model, exhibiting high accuracy. However, boosted trees are hardly intelligible, and this is a problem whenever they are used in safety-critical applications. Indeed, in such a context, provably sound explanations for the predictions made are expected. Recent work have shown how subset-minimal abductive explanations can be derived for boosted trees, using automated reasoning techniques. However, the generation of such well-founded explanations is intractable in the general case. To improve the scalability of their generation, we introduce the notion of tree-specific explanation for a boosted tree. We show that tree-specific explanations are provably sound abductive explanations that can be computed in polynomial time. We also explain how to derive a subset-minimal abductive explanation from a tree-specific explanation. Experiments on various datasets show the computational benefits of leveraging tree-specific explanations for deriving subset-minimal abductive explanations.

1 INTRODUCTION

The deployment of ML models in a large spectrum of applications has triggered the fast-growing development of eXplainable AI (XAI) (see for instance (Frosst and Hinton, 2017; Wang and Rudin, 2015; Guidotti et al., 2019; Hooker et al., 2019; Huysmans et al., 2011; Ignatiev et al., 2019a; Kim et al., 2018; Lundberg and Lee, 2017; Miller, 2019; Molnar, 2019; Shih et al., 2019b)). Models with high prediction performance are usually considered as poorly intelligible (Molnar, 2019; Arrieta et al., 2020; Lundberg et al., 2020; Caruana et al., 2020; Rudin et al., 2021). Among them is the family of boosted trees (Friedman, 2001), which is among the state-of-the-art ML models when dealing with tabular data (Borisov et al., 2021).

Motivations. The design of efficient methods for interpreting ML models and explaining their decisions (i.e., deriving local explanations) is acknowledged as an issue of the utmost importance when ML models are to be used in safety-critical applications (Marques-Silva and Ignatiev, 2022). Since most existing approaches to explaining ML models deliver model-agnostic explanations, they cannot be used in any high-risk context because the explanations that are generated are unsound: one can find "counterexamples" for them, i.e., pairs of instances that have the same explanation but are nevertheless classified differently by the model (Ignatiev et al., 2019b). In particular, (Ignatiev, 2020) shows that the amount of "counterexamples" can be high when using some of the most popular approaches for computing model-agnostic explanations, namely LIME (Ribeiro et al., 2016), Anchors (Ribeiro et al., 2018), and SHAP (Lundberg and Lee, 2017).

In order to avoid the generation of unsound explanations, a number of alternative approaches, falling under the formal XAI umbrella (Marques-Silva and Ignatiev, 2022), have shown how ML models of various types (including "black" boxes) can be associated with Boolean circuits (alias transparent or “white” boxes), exhibiting the same input-output behaviours (see among others (Narodytska et al., 2018; Shih et al., 2018b, 2019a)). Thanks to such mappings, XAI queries about classifiers, including the generation of explanations, can be delegated to the corresponding circuits (see for instance (Darwiche and Hirth, 2020; Barceló et al., 2020; Parmentier and Vidal, 2021)). The price to be paid for ensuring that the explanations that are generated are sound is a certain lack of scalability (the derivation of explanations is often NP-hard in the broad sense).

Ensemble methods (bagging, boosting, stacking, etc.) have already been considered in such a perspective. Unlike what happens for decision trees, the derivation of abductive explanations is not a computationally easy task when tree ensembles are considered. An abductive explanation for an instance given a classifier is a subset of the characteristics of the instance that is enough to justify how the instance has been classified. In order to avoid the presence of useless characteristics in explanations and consider the instance itself as a valuable explanation, subset-minimal abductive explanations (alias sufficient reasons (Darwiche

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and Hirth, 2020)) are often targeted. (Choi et al., 2020; Izza and Marques-Silva, 2021; Audemard et al., 2022a) show how to derive abductive explanations for random forests (Breiman, 2001). As to boosted trees, (Ignatiev et al., 2019b) provides an SMT (satisfiability modulo theory) encoding scheme for boosted trees and shows how to use an SMT solver to compute sufficient reasons based on the encoding scheme. The corresponding XAI tool is called XPlainer (https://github.com/alexeyignatiev/xplainer). (Ignatiev et al., 2022) presents another encoding scheme, based on MaxSAT (maximum satisfiability), and indicates how to exploit a MaxSAT solver to compute sufficient reasons based on it. The associated tool is called XReason (https://github.com/alexeyignatiev/xreason). Deciding whether a given explanation is sound is intractable for boosted trees. Accordingly, though XReason typically exhibits better performances than XPlainer, its scalability is still an issue.

**Contributions.** Considering boosted trees, the main contribution of this paper is a new approach to derive sufficient reasons, that is more efficient in practice than SOTA methods, as identified in the literature. To reach the objective, we introduce the notion of tree-specific explanation (TS-explanation for short) given a boosted tree.

TS-explanations elaborate on the notion of majority reasons for random forests, introduced in (Audemard et al., 2022a). Both are (possibly redundant) abductive explanations that can be computed efficiently thanks to a greedy algorithm. The main differences between the present work and the one described in (Audemard et al., 2022a) are as follows. In (Audemard et al., 2022a), the computation of majority reasons is not used as a preprocessing to the computation of sufficient reasons, unlike what is done here. More importantly, majority reasons are about random forests, not gradient boosted trees (which is usually acknowledged as a more accurate, yet more opaque, model). Finally, the work presented in (Audemard et al., 2022a) concerns only binary classification and Boolean features, while in the present work, none of those restrictions is required.

Notably, our approach applies to boosted trees as they have been learned, and whatever the learning algorithm used to generate them. Thus, many boosted tree learning algorithms can be used upstream. Those algorithms may differ in a number of aspects, including the method used to compute gradients (standard gradient algorithm vs. Newton-Raphson), the use of subsampling, the use of a regularization function (lasso or ridge), the handling of categorical features, etc. The combination of techniques achieves several trade-offs in terms of accuracy of the resulting trees and the computation time required to generate them. In particular, XGBoost (Chen and Guestrin, 2016), LightGBM (Ke et al., 2017) and CatBoost (Prokhorenkova et al., 2018) that implement some of the combinations above generate boosted trees that can be used as inputs for our approach for computing explanations.

This is also the case of AdaBoost\(^1\) (Freund and Schapire, 1997; Schapire and Freund, 2014).

To be more precise, in the following we show that TS-explanations are abductive explanations that can be computed in polynomial time. This heavily contrasts with sufficient reasons, which cannot be derived in polynomial time (unless P = NP) when boosted trees are considered. TS-explanations are provably sound: no "counterexamples" for them may exist. While TS-explanations are not subset-minimal abductive explanations in the general case, we show that they are close to sufficient reasons in practice. Furthermore, because sufficient reasons can be derived from TS-explanations, computing TS-explanations can be exploited as a preprocessing step in the derivation of sufficient reasons. Experiments on various datasets show that leveraging TS-explanations for generating sufficient reasons is a valuable approach.

The proofs of the propositions given in the paper are reported to a final appendix. A description of the datasets and the code used in our experiments are provided as a supplementary material, available at www.cril.fr/expektation/aiats23.zip.

## 2 PRELIMINARIES

For an integer \(n\), let \([n] = \{1, \ldots, n\}\). We consider a finite set \(\{A_1, \ldots, A_n\}\) of attributes (aka features) where each attribute \(A_i (i \in [n])\) takes its value in a domain \(D_i\). Three types of attributes are taken into account: numerical (the domain \(D_i\) is a totally ordered set of numbers, typically real numbers \(\mathbb{R}\), or integers \(\mathbb{Z}\)), categorical (the domain \(D_i\) is a set of values that are not specifically ordered, e.g., \(D_i = \{b(\text{blue}), w(\text{white}), r(\text{red})\}\), or Boolean (the domain \(D_i\) is \(\mathbb{B} = \{0, 1\}\)). An instance \(x\) is a vector \((v_1, \ldots, v_n)\) where each \(v_i (i \in [n])\) is an element of \(D_i\). \(x\) is also viewed as a term, i.e., a conjunctively-interpreted set of literals \(t_x = \{(A_i = v_i) : i \in [n]\}\), stating that each attribute \(A_i\) takes the corresponding value \(v_i\). Each pair \(A_i = v_i\) is called a characteristic of the instance. \(X\) denotes the set of all instances.

In the binary case, a classifier \(f\) is defined as a mapping from \(X\) to \([0, 1]\). When \(f(x) = 1\), \(x\) is said to be a positive instance, otherwise it is a negative instance. The set of all positive instances forms a target concept, and the set of all negative instances is the complementary concept. More generally, in the multi-class case, more than one concept (together with the complementary concept) is considered. A classifier \(f\) is then defined as a mapping from \(X\) to \([m]\) with \(m > 1\). Each integer from \([m]\) identifies a class and

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\(^1\)In this case, in order to recover the same format of boosted trees as the one used by the other boosted tree learning algorithms, the coefficients associated with the trees generated by AdaBoost must be propagated to the leaves of those trees using a simple product.
when \( f(x) = j \) with \( j \in [m] \), the instance \( x \) is said to be classified as an element of class \( j \).

**Trees and Forests.** A regression tree over \( \{A_1, \ldots, A_n\} \) is a binary tree \( T \), each of its internal nodes being labeled with a Boolean condition on an attribute from \( \{A_1, \ldots, A_n\} \), and leaves are labeled by real numbers. The conditions are typically of the form \( A_i > v_j \) with \( v_j \) a number when \( A_i \) is a numerical attribute, \( A_i = v_j \) when \( A_i \) is a categorical attribute, and \( A_i \) (or equivalently \( A_i = 1 \)) when \( A_i \) is a Boolean attribute. The weight \( w(T, x) \in \mathbb{R} \) of \( T \) for an input instance \( x \in \mathcal{X} \) is given by the label of the leaf reached from the root as follows: at each node go to the left or right child depending on whether or not the condition labelling the node is satisfied by \( x \). \( w(T, x) \) can also be viewed as the “output” of \( T \) on \( x \). In the binary classification case, a decision tree over \( \{A_1, \ldots, A_n\} \) is a regression tree over \( \{A_1, \ldots, A_n\} \) where leaves are labeled in \{0, 1\} (Breiman et al., 1984; Quinlan, 1986).

A forest over \( \{A_1, \ldots, A_n\} \) associated with a class \( j \in [m] \) is an ensemble of trees \( F^j = \{T^j_1, \ldots, T^j_p\} \), where each \( T^j_k \) is a regression tree over \( \{A_1, \ldots, A_n\} \), and such that the weight \( w(F^j, x) \in \mathbb{R} \) for an input instance \( x \in \mathcal{X} \) is given by

\[
w(F^j, x) = \sum_{k=1}^{p_j} w(T^j_k, x).
\]

A random forest over \( \{A_1, \ldots, A_n\} \) is a forest over \( \{A_1, \ldots, A_n\} \) that consists only of decision trees (Breiman, 2001).

In the binary classification case, a boosted tree \( BT \) over \( \{A_1, \ldots, A_n\} \) is a forest \( F = \{T_1, \ldots, T_p\} \). In a multi-class context, a boosted tree \( BT \) over \( \{A_1, \ldots, A_n\} \) is a collection of \( m \) forests \( BT = \{F^1, \ldots, F^m\} \) over \( \{A_1, \ldots, A_n\} \) (Freund and Schapire, 1997; Schapire and Freund, 2014; Friedman, 2001). The size of a forest \( F^j \) is given by \( |F^j| = \sum_{k=1}^{p_j} |T^j_k| \), where \( |T^j_k| \) is the number of nodes occurring in \( T^j_k \). The size of a boosted tree \( BT \) is given by \( |BT| = \sum_{j=1}^{m} |F^j| \).

In the binary classification case, an instance \( x \) is considered as a positive instance when \( w(F, x) > 0 \) and as a negative instance otherwise. We note \( BT(x) = 1 \) in the first case and \( BT(x) = 0 \) in the second case. In a multi-class context, an instance \( x \) is classified as an element of class \( j \in [m] \), noted \( BT(x) = j \), if and only if \( w(F^j, x) > w(F^i, x) \) for every \( i \in [m] \setminus \{j\} \). If \( w(F^j, x) = w(F^i, x) \) for every \( i, j \in [m] \), then \( BT(x) \) is defined as a preset element of \( [m] \) (e.g., a most frequent class in the dataset used to learn \( BT \)). Whatever the case (binary or multi-class), computing \( BT(x) \) can be achieved in polynomial time in \(|BT| + n\).

**Example 1.** As an example of binary classification, consider four attributes: \( A_1, A_2 \) are numerical, \( A_3 \) is categorical, and \( A_4 \) is Boolean. The boosted tree \( BT = \{F\} \) in

![Figure 1: A boosted tree \( BT = \{F\} \) consisting of a single forest \( F = \{T_1, T_2, T_3\} \). In each tree, the left (dashed) arc (resp. the right (plain) arc) outgoing from any node labelled by a condition \( c \) corresponds to the case \( c \) is false (resp. true).](image-url)

![Figure 1 is composed of a single forest \( F \), which consists of three regression trees \( T_1, T_2, T_3 \). Consider \( x = (A_1 = 4, A_2 = 3, A_3 = b, A_4 = 1) \). We have \( w(T_1, x) = 0.3, w(T_2, x) = 0.5, \) and \( w(T_3, x) = 0.1 \). So \( w(F, x) = 0.9, \) and \( x \) is classified as a positive instance by \( F \), thus it is classified as such by \( BT: BT(x) = 1 \).](image-url)
Algorithm 1: $SR(x,f)$

1. $t \leftarrow t_x$
2. foreach $c_i \in t_x$ do
3.    if $\text{implicant}(t \setminus \{c_i\}, x, f)$ then $t \leftarrow t \setminus \{c_i\}$
4. return $t$

reason for $x$ given $BT$.

Sufficient reasons are usually preferred to other abductive explanations since they are more simple: they do not contain any characteristics of the instance at hand that are not useful to explain the prediction made by $f$.

Computing Sufficient Reasons. In order to compute a sufficient reason for an input instance $x$ given a classifier $f$, one can take advantage of a simple greedy algorithm (see Algorithm 1). Starting with $t = t_x$, this algorithm considers all the characteristics $c_i = (A_i = v_i)$ of $x$ in a specific order and, at each step, tests whether $t$ deprived of $c_i$ is still an abductive explanation for $x$ given $f$. If the test is positive, $c_i$ is removed from $t$, otherwise it is kept. Once all the characteristics $c_i$ of $x$ have been considered, the resulting term $t$ is by construction a sufficient reason for $x$ given $f$.

The computationally demanding step in this greedy algorithm is the call to function $\text{implicant}$ that tests whether $t$ deprived of $c_i$ is still an abductive explanation for $x$ given $f$, i.e., any instance covered by $t \setminus \{c_i\}$ is classified in the same way as $x$ by $f$. Though this test can be achieved in polynomial time for some families of classifiers $f$ (including decision trees) (Izza et al., 2020; Huang et al., 2021), it is intractable in general. Indeed, it is $\text{coNP}$-hard when $f$ is a random forest (Audemard et al., 2022a). Similarly, when $f$ is a boosted tree $BT$, we easily get that:

Proposition 1. Let $BT$ be a boosted tree over $\{A_1, \ldots, A_n\}$ and $x \in X$. Let $t \subseteq t_x$. Deciding whether $t$ is an abductive explanation for $x$ given $BT$ is $\text{coNP}$-complete. $\text{coNP}$-hardness still holds in the restricted case every $A_i (i \in [n])$ is Boolean and $BT$ consists of a single forest.

In order to achieve the $\text{implicant}$ test when $f$ is a boosted tree $BT$, several approaches can be followed. (Ignatiev et al., 2019b) took advantage of an SMT (SAT modulo theory) encoding of the boosted tree and then on an SMT solver to compute sufficient reasons. More recently, (Ignatiev et al., 2022) pointed out a more sophisticated encoding based on MaxSAT and exploited a MaxSAT solver to compute sufficient reasons. Though this latter approach exhibited better performances in practice, its scalability is still an issue (the datasets considered in the experiments presented in (Ignatiev et al., 2022) contain at most 60 attributes).

3 COMPUTING TS-EXPLANATIONS

Worst / Best Instances. As explained before, when the classifier at hand is a regression tree, a forest, or (more generally) a boosted tree $BT$, the classification of an instance $x \in X$ depends on the weights of the tree(s) of the classifier for the instance. Because of this weight-based mechanism, the notion of abductive explanation $t$ for $x$ can be characterized via the notion of worst/best instance extending $t$. Let us start with the binary case:

Definition 1. Let $BT = \{F\}$ be a boosted tree over $\{A_1, \ldots, A_n\}$ and $x \in X$. Let $t \subseteq t_x$.

- A worst instance extending $t$ given $F$ is an instance $x' \in X$ such that $t \subseteq t_{x'}$ and $x' = \arg\min_{x'' \in X : t \subseteq t_{x''}} \{w(F, x'')\}$.
- A best instance extending $t$ given $F$ is an instance $x' \in X$ such that $t \subseteq t_{x'}$ and $x' = \arg\max_{x'' \in X : t \subseteq t_{x''}} \{w(F, x'')\}$.

In this definition, the condition $t \subseteq t_{x'}$ is used to characterize the set of instances $x''$ of interest, i.e., those covered by $t$. $W(t, F)$ (resp. $B(t, F)$) denotes the set of worst (resp. best) instances extending $t$ given $F$, and $w_t(t, F)$ (resp. $w_t(t, F)$) denotes the weight of any worst (resp. best) instance covered by $t$ given $F$.

Intuitively, a worst/best instance extending a given term $t$ is one of minimal/maximal weight. If such a weight is positive/negative, then so is the weight of any instance covered by $t$. Accordingly, we have:

Proposition 2. In the binary case, let $BT = \{F\}$ be a boosted tree over $\{A_1, \ldots, A_n\}$ and $x \in X$. Let $t \subseteq t_x$.

- If $BT(x) = 1$, then $t$ is an abductive explanation for $x$ given $BT$ if and only if any $x' \in W(t, F)$ is such that $BT(x') = 1$.
- If $BT(x) = 0$, then $t$ is an abductive explanation for $x$ given $BT$ if and only if any $x' \in B(t, F)$ is such that $BT(x') = 0$.

Example 3. For our running example, $t = \{(A_1 = 4), (A_4 = 1)\}$ is an abductive explanation for $x = (A_1 = 4, A_2 = 3, A_3 = b, A_4 = 1)$ given $BT = \{F\}$ because any worst instance covered by $t$, i.e., any $x'$ satisfying $(A_1 = 4) \land (A_2 \leq 1) \land (A_3 = b) \land (A_4 = 1)$ is such that $w(F, x') = 0.3$ (hence $w(F, x') > 0$) (see Table 1).

In the multi-class case, a similar notion of worst instance can be stated.$^3$

Definition 2. Let $BT = \{F^1, \ldots, F^m\}$ be a boosted tree over $\{A_1, \ldots, A_n\}$ and $x \in X$ such that $BT(x) = i$. Let $t \subseteq t_x$. Given $BT$ and $x$, a worst instance extending $t$ is an instance $x' \in X$ such that

\footnotesize
$^3$A notion of best instance could also be defined but it is useless for our purpose.
Then we have:

**Proposition 3.** Let \( BT = \{ F^1, \ldots, F^m \} \) be a boosted tree over \( \{A_1, \ldots, A_n\} \) and \( x \in X \) such that \( BT(x) = i \). Let \( t \subseteq t_x \). \( t \) is an abductive explanation for \( x \) given \( BT \) if and only if for any worst instance \( x' \) extending \( t \) given \( BT \) and \( x \), \( w(F^i, x') - \max_{j \in [m] \setminus \{i\}} w(F^j, x') > 0 \) holds.

Propositions 1 and 2 (or 3) show together that identifying a worst (resp. best) instance \( x' \in X \) extending a term \( t \subseteq t_x \) given a boosted tree \( BT \) is intractable. Indeed, if it were not the case, we could check in polynomial time whether \( t \) is an abductive explanation for \( x \) given \( BT \) by testing whether \( x' \) is classified by \( BT \) in the same way as \( x \).

### Computing Worst/Best Instances for Trees

Interestingly, when the classifier consists of a regression tree \( T \), identifying an element of \( W(t, T) \) (resp. \( B(t, T) \)) is easy: there exists a simple, linear-time, algorithm to compute \( w_{\ell}(t, T) \) and \( w_{\ell}(t, T) \), and as a by-product, to derive a worst instance and a best instance extending \( t \) given \( T \). Basically, the algorithm consists of freezing in \( T \) every arc corresponding to a condition not satisfied by \( t \), which can be done in time linear in the size of the input. A valid root-to-leaf path in the resulting tree is a root-to-leaf path of \( T \) not containing any frozen arc. The weight \( w_{\ell}(t, T) \) of \( T \) for a worst (resp. best) instance extending \( t \) simply is the minimal (resp. maximal) weight labelling a leaf of a valid root-to-leaf path in the resulting tree, and it can be determined in time linear in the size of the input. Any \( x' \) satisfying the conditions associated with a valid root-to-leaf path leading to a minimal (resp. maximal) weight leaf and satisfying \( t \subseteq t_x' \) is a worst (resp. best) instance extending \( t \) given \( T \).

**Example 4.** Considering our running example again, let us identify worst instances extending \( t = \langle A_1 = 4, A_4 = 1 \rangle \) for each of the trees \( T_1, T_2, \) and \( T_3 \). On Figure 2, every frozen arc (and the corresponding subtree) is watermark displayed; the minimal weight leaves are bold, and the arcs of the corresponding root-to-leaf paths are bold. We have:

- Every \( x' \in X \) satisfying \( (A_1 = 4) \wedge (A_2 > 1) \wedge (A_3 \neq b) \wedge (A_4 = 1) \) is an element of \( W(t, T_3) \).
- Every \( x' \in X \) satisfying \( (A_1 = 4) \wedge (A_2 \leq 1) \wedge (A_4 = 1) \) is an element of \( W(t, T_2) \).

**Table 1:** Weights of \( BT \) for instances \( x' \) extending \( t \).

| \( A_1 = 4 \) | \( A_2 > 1 \) | \( A_3 = b \) | \( A_4 = 1 \) | \( w(T_1, x') \) | \( w(T_2, x') \) | \( w(T_3, x') \) | \( w(F, x') \) |
|---|---|---|---|---|---|---|---|
| 1 | 0 | 0 | 1 | 0.4 | 0.3 | 0.2 | 0.9 |
| 1 | 0 | 1 | 1 | 0.4 | 0.3 | -0.4 | 0.3 |
| 1 | 1 | 0 | 1 | -0.3 | 0.5 | 0.3 | 0.5 |
| 1 | 1 | 1 | 1 | 0.3 | 0.5 | 0.1 | 0.9 |

**Figure 2:** Worst instances and the corresponding weights for the regression trees used in \( BT \).

### Tree-Specific Explanations

We are now ready to define the notion of \( TS \)-explanation \( t \) for an instance \( x \) given a boosted tree \( BT \). We start with the binary case, i.e., when \( BT \) consists of a single forest \( F \):

**Definition 3.** Let \( F = \{T_1, \ldots, T_p\} \) be a forest over \( \{A_1, \ldots, A_n\} \) and \( x \in X \).

- If \( F(x) = 1 \), then \( t \) is a tree-specific explanation for \( x \) given \( F \) if and only if \( t \) is a subset of \( t_x \) such that \( \sum_{k=1}^{p} w_{\ell}(t, T_k) > 0 \) and no proper subset of \( t \) satisfies the latter condition.
- If \( F(x) = 0 \), then \( t \) is a tree-specific explanation for \( x \) given \( F \) if and only if \( t \) is a subset of \( t_x \) such that \( \sum_{k=1}^{p} w_{\ell}(t, T_k) \leq 0 \) and no proper subset of \( t \) satisfies the latter condition.

More generally, in the multi-class setting, TS-explanations can be defined as follows:

**Definition 4.** Let \( BT = \{F^1, \ldots, F^m\} \) be a boosted tree over \( \{A_1, \ldots, A_n\} \) where each \( F^j \) (\( j \in [m] \)) contains \( p_j \) trees, and \( x \in X \) such that \( BT(x) = i \). \( t \) is a tree-specific explanation for \( x \) given \( BT \) if and only if \( t \) is a subset of \( t_x \) such that for every \( j \in [m] \setminus \{i\} \), we have \( \sum_{k=1}^{p_j} w_{\ell}(t, T_k^j) > \sum_{k=1}^{p_i} w_{\ell}(t, T_k^i) \), and no proper subset of \( t \) satisfies the latter condition.

A first key property that makes TS-explanations valuable is that they are abductive explanations:

**Proposition 4.** Let \( BT \) be a boosted tree over \( \{A_1, \ldots, A_n\} \) and \( x \in X \). If \( t \) is a TS-explanation for \( x \) given \( BT \), then \( t \) is an abductive explanation for \( x \) given \( BT \).
Accordingly, each time the test \( \forall j \in [m] \setminus \{i\}, \sum_{k=1}^{p_1} w_{ij}(t, T_k^i) > \sum_{k=1}^{p_2} w_{ij}(t, T_k^j) \) succeeds, it is ensured that \( t \) is an abductive explanation for \( x \) given \( BT \). However, the condition is only sufficient: when the test fails, it can be the case that \( t \) is an abductive explanation for \( x \) given \( BT \) nevertheless. Testing the condition \( \forall j \in [m] \setminus \{i\}, \sum_{k=1}^{p_1} w_{ij}(t, T_k^i, x) > \sum_{k=1}^{p_2} w_{ij}(t, T_k^j, x) \) thus amounts to making an incomplete implicant test.

It is easy to check that TS-explanations coincide with sufficient reasons for regression trees. Unsurprisingly, given the complexity shift pointed out in Proposition 1, this equivalence does not hold for forests or boosted trees. Thus, in the general case, a TS-explanation \( t \) for \( x \) given \( BT \) is not a sufficient reason for \( x \) given \( BT \): \( t \) may contain characteristics of \( x \) that could be removed without questioning the classification achieved by \( BT \).

**Example 5.** Considering our running example again, the sufficient reason \( t = \{(A_1 = 4), (A_4 = 1)\} \) for \( x = (A_1 = 4, A_2 = 3, A_3 = b, A_4 = 1) \) given \( BT = \{F\} \) is not a TS-explanation for \( x \) given \( BT \). Indeed, we have \( w_{ij}(t, T_1) = -0.3, w_{ij}(t, T_2) = 0.3, \) and \( w_{ij}(t, T_3) = -0.4, \) hence \( w_{ij}(t', T_1) + w_{ij}(t', T_2) + w_{ij}(t', T_3) = -0.4 < 0 \) while \( w(F, x) = 0.9 > 0 \). Contrastingly, the sufficient reason \( t' = \{(A_2 = 3), (A_1 = 4)\} \) for \( x \) given \( BT \) is also a TS-explanation for \( x \) given \( BT \). We have \( w_{ij}(t', T_1) = -0.3, w_{ij}(t', T_2) = 0.5, \) and \( w_{ij}(t', T_3) = 0.1, \) hence \( w_{ij}(t', T_1) + w_{ij}(t', T_2) + w_{ij}(t', T_3) = 0.3 > 0 \).

Though subset-minimality is required in both cases, the fact that TS-explanations and sufficient reasons do not coincide (in general) can be easily explained by the fact that TS-explanations consider the trees separately: it can be easily the case that two distinct trees \( T_k^i \) and \( T_k^j \) belonging to the same forest \( F_j \) do not share any worst instance extending a given term \( t \). In symbols, we may have \( W(t, T_k^i) \cap W(t, T_k^j) = \emptyset \).

**Example 6.** For our running example, no worst instance extending \( t = \{(A_1 = 4), (A_4 = 1)\} \) given \( T_2 \) or given \( T_3 \). Indeed, every worst instance extending \( t = \{(A_1 = 4), (A_4 = 1)\} \) given \( T_1 \) must satisfy \( A_2 > 1 \), while every worst instance extending \( t = \{(A_1 = 4), (A_4 = 1)\} \) given \( T_2 \) or \( T_3 \) must satisfy the complementary condition \( A_2 \leq 1 \).

In the worst case, the number of useless characteristics in a TS-explanation can be equal to the number \( n \) of attributes:

**Proposition 5.** Let \( BT \) be a boosted tree over \( \{A_1, \ldots, A_n\} \) and \( x \in X \). It can be the case that the unique TS-explanation for \( x \) given \( BT \) consists of \( t_x \), itself, while \( \emptyset \) is the unique sufficient reason for \( x \) given \( BT \). This holds even in the restricted case \( BT \) consists of a single forest and every attribute is Boolean.

A second key property that makes TS-explanations valuable is that they can be computed efficiently. Indeed, the greedy algorithm \( TS \) given by Algorithm 2 can be used to derive in time \( \mathcal{O}(n|BT|) \) a TS-explanation for \( x \) given \( BT \) in the multi-class case.

**Proposition 6.** Let \( BT \) be a boosted tree over \( \{A_1, \ldots, A_n\} \) and \( x \in X \). \( TS(x, BT) \) returns a TS-explanation for \( x \) given \( BT \).

**Algorithm 2:** \( TS(x, BT) \)

```plaintext
1. \( t \leftarrow t_x \)
2. \( j \leftarrow BT(x) \)
3. foreach \( c_i \in t_x \) do
   4. if \( \exists k \in [m] \setminus \{j\} \) s.t. \( \sum_{t=1}^{p_1} w_{ij}(t \setminus \{c_i\}, T_k^j) \leq \sum_{t=1}^{p_2} w_{ij}(t \setminus \{c_i\}, T_k^j) \) then
      5. \( t \leftarrow t \setminus \{c_i\} \)
5. return \( t \)
```

Clearly enough, an algorithm closely similar to \( TS \) can be designed to handle the binary classification case (in that case, at each iteration, one just needs to test the sign of \( \sum_{t=1}^{p_1} w_{ij}(t, T_k) \) when \( x \) is positive, and the sign of \( \sum_{t=1}^{p_1} w_{ij}(t, T_k) \) when \( x \) is negative). The same performance guarantees as in the multi-class case are ensured.

Interestingly, when dealing with boosted trees, the greedy algorithm \( SR \) (Algorithm 1) for deriving sufficient reasons can be exploited to remove useless characteristics in TS-explanations, i.e., to generate sufficient reasons from TS-explanations. Viewed from a different angle, the computation of a TS-explanation for an instance \( x \) given a boosted tree \( BT \) can be exploited as a preprocessing step in \( SR \). This combination is given by the pipeline

\[
SR(TS(t_x, BT), BT).
\]

The rationale for this preprocessing step is the fact that \( TS \) is a polynomial-time algorithm, while \( SR \) is not. As the experiments reported in Section 4 will show it, \( TS \) may remove in a very efficient way many useless characteristics of \( x \), thus avoiding many calls to the computationally expensive function \( \text{implicant} \).

## 4 EXPERIMENTS

**Empirical Protocol.** The empirical protocol was as follows. We have considered 50 datasets, which are standard benchmarks (adult, farm-ads, ...) coming from the well-known repositories Kaggle (www.kaggle.com), OpenML (www.openml.org), and UCI (archive.ics.uci.edu/ml/). For these datasets, the number of classes varies from 2 to 9 classes, the number of attributes (features) from 10 to 100001, and the number of instances from 345 to 48842. Categorical features have been treated as numbers. This
choice has been motivated by the fact that most of the time the types of the attributes are not documented in the datasets. As to numerical features, no data preprocessing has taken place; these features have been binarized on-the-fly by the learning algorithm that has been used, namely XGBoost (Chen and Guestrin, 2016) that learns gradient boosted trees. XGBoost has been used without any tuning. Since our purpose is to be able to explain the classification achieved by the boosted trees as they have been learned, hyper-parameters have not been optimized but set to their default values (in particular, 100 trees per class have been considered and the maximum depth of each tree was set to 6).

For every dataset, a 10-fold cross validation process has been achieved. Ten boosted trees have been learned per dataset. The mean accuracy per dataset varies from 53.23% up to 100% (in average, it is equal to 88.5%). Ten instances have been picked up uniformly at random in the test set associated with the training set used to learn each boosted tree. This led to 100 instances per dataset, giving a total of 5000 instances for which explanations about the way they were classified have been sought for. To get such explanations, we ran implementations of the algorithms presented in the previous sections: SR implemented as XReason (with its default parameters), our own implementation of TS, and an implementation TS+XReason of the pipeline of the two. In order to implement this pipeline, we had to modify XReason in such a way that it can use as input any abductive explanation for the instance at hand, and not only the instance itself. By default, XReason starts by removing some useless characteristics of the input instance using a core-guided mechanism. Though beneficial when XReason is used alone, this step turns out to be counterproductive when XReason is combined with TS. Indeed, in our experiments, the number of instances (out of 5000) "solved" by TS+XReason with this treatment switched on is 4016, while it is equal to 4097 when the treatment was switched off. Hence, in our experiments, the treatment has been switched off when TS was run upstream to XReason, and switched on when XReason was used alone. We have also modified XReason to make it provide the abductive explanation that is available when the time limit is reached (in this case, the returned explanation is not guaranteed to be subset-minimal). In our experiments, for each instance \(x\), TS has been called 1000 times: at each run, an elimination ordering of the characteristics of \(x\) (as considered at line 3 of Algorithm 2) has been picked up uniformly at random, and a shortest TS-explanation among those generated for the 1000 runs was finally returned.

All the experiments have been conducted on a computer equipped with Intel(R) XEON E5-2637 CPU @ 3.5 GHz and 128 Gib of memory. For each algorithm, a timeout (TO) of 100 seconds per instance has been considered. This was deemed as a reasonable time bound for providing an explanation to a human user.

| Dataset         | #Cls. | #Feat. | #Feat. Used | #Inst. | Acc. |
|-----------------|-------|--------|-------------|--------|------|
| gina_agnostic   | 2     | 970    | 477.90(±10.46) | 3468   | 95.13(±1.35) |
| malware         | 2     | 1084   | 88.60(±1.85)   | 6248   | 99.96(±0.26) |
| ad_data         | 2     | 1558   | 78.70(±1.24)   | 3279   | 97.78(±0.84) |
| christine       | 2     | 1636   | 1277.20(±8.06) | 5418   | 73.81(±1.82) |
| cnae            | 9     | 856    | 132.30(±4.24)  | 1079   | 91.48(±1.64) |
| gisette         | 2     | 5000   | 783.60(±1.33)  | 7000   | 97.83(±0.56) |
| arcene          | 2     | 1000   | 143.50(±5.90)  | 200    | 80.50(±7.23) |
| dexter          | 2     | 2000   | 104.50(±4.54)  | 600    | 91.83(±3.69) |
| allBooks        | 8     | 8206   | 315.90(±8.70)  | 590    | 87.12(±3.73) |
| farm-ads        | 2     | 54876  | 714.10(±16.70) | 4143   | 90.27(±1.15) |
| dorothela       | 2     | 100000 | 222.20(±10.85) | 1150   | 93.91(±2.55) |

Table 2: A focus on 10 datasets.

**Results.** A synthesis of the results we obtained is provided on Figure 3. On those two scatter plots, each dot corresponds to an instance among the 5000 instances tested.

Figure 3 (a) is about computation times. The \(x\)-coordinate (resp. \(y\)-coordinate) of a dot is the time (in seconds) required by TS+XReason (resp. XReason) to compute an abductive explanation for the associated instance. By construction, this abductive explanation is a sufficient reason for the instance when the computation stops before the time limit.

In light of Figure 3 (a), two observations can be made. On the one hand, the run times of TS+XReason are significantly smaller than those of XReason. On the other hand, the time limit has been reached much more often by XReason than by TS+XReason.

Figure 3 (b) is about the size of the abductive explanations that are generated, and more precisely, about reduction rates, where the reduction rate achieved by an explanation \(t\) for an instance \(x\) over \(n\) attributes is given by \(1 - \frac{n - |t|}{d}\) where \(d\) is the number of attributes that are dropped by XGBoost. For example, if \(|t| = 10\), \(n = 100\), and \(d = 20\) (meaning that only \(n - d = 80\) attributes are used in the boosted tree), the reduction rate is 87.5%. Indeed, size is one of the criteria to be considered when evaluating the intelligibility of an explanation: everything else being equal, shortest explanations are easier to understand than longer explanations. For each dot corresponding to an instance \(x\), the \(x\)-coordinate (resp. \(y\)-coordinate) of the dot is the reduction rate of the explanation for \(x\) generated by TS+XReason (resp. by XReason). Different dot representations for instances have been used in this figure, depending on the fact that a sufficient reason for the instance at hand has been computed (or not) within the time limit by any of the two programs, or by both of them.

Figure 3 (b) shows that TS+XReason leads in general to much better reduction rates than those obtained by XReason, thus to much smaller explanations. One can...

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*In general, the intelligibility of an explanation does not reduce to its size and an accurate evaluation of it cannot be achieved in a context-independent way (Doshi-Velez and Kim, 2017; Narayanan et al., 2018), since intelligibility typically depends on the explainer (i.e., the person who asked for an explanation) (Miller, 2019).*
observe that the number of sufficient reasons that have been (provably) derived by TS+XReason in at most 100 seconds is significantly higher than the number of sufficient reasons that have been (provably) derived by XReason. More in detail, out of 5000 abductive explanations, 3476 sufficient reasons have been obtained in due time by the two programs, while 621 have been obtained in due time by TS+XReason alone, 8 have been obtained in due time by XReason alone. This gives a win rate of more than 98% for the pipeline. Overall, a significant amount of 621 – 8 = 613 sufficient reasons have been gained by taking advantage of TS as a preprocessing to XReason. For 895 abductive explanations that have been generated, there are no subset-minimality guarantees whatever TS+XReason or XReason was used to derive them.

In order to evaluate the impact of picking a shortest TS-explanation out of 1000 instead of using only the one that has been computed first, we have considered a variant of TS that derives only one TS-explanation. We observed that the performances of the pipelines TS+XReason are similar in the two cases. Thus, when a single TS-explanation is considered, the reduction rate decreases a bit on average (−4.25%), leading to slightly longer explanations. On the contrary, computation time decreases a bit on average (−7.65%). Focusing on the harder instances (those for which the pipeline required more than 10s to terminate), the reduction rate decreases a bit more on average (−5.14%) but the computation time increases slightly on average (+5.04%). Hence the ability to compute many TS-explanations almost "for free" and to keep a smallest one is valuable but not the main cause for the efficiency of the pipeline.

To complete the scatter plots, Tables 2 and 3 report some details about 10 datasets out of 50 (the ones based on the largest numbers of attributes). The columns of Table 2 give, from left to right, the name of the dataset, the number of classes and features in it, the mean number of features used in the boosted trees that have been generated, the number of instances in the dataset, the mean accuracy of the boosted trees. For each dataset, Table 3 presents the results obtained on 100 instances by TS+XReason and XReason in terms
of mean run times (given in seconds) number of TOs and number of sufficient reasons computed in due time, and then in terms of mean reduction rates. For TS+XReason, we report the mean run times and mean reduction rates achieved by TS alone, and then by the pipeline TS+XReason where XReason is run on the abductive explanation generated by TS. The 100 instances tested per dataset are divided into two subsets, each one corresponding to a line: those instances for which a TO occurs (in that case, the abductive explanation that is generated may be redundant) and those for which a sufficient reason has been computed within the time limit. Whenever every instance or no instance out of 100 has been solved by the pipeline TS+XReason and by XReason alone before the time limit has been reached, only one line has been kept.

For some instances, it can be observed that the pipeline TS+XReason does not succeed in computing a sufficient reason in due time (this happens e.g., for every instance of the dataset ‘christine’, see Table 3). Even if XReason does not do better for this dataset, this can be considered as a limitation of the approach. It is also worth noting that when computing a sufficient reason, deriving first a TS-explanation is sometimes a waste of time. In our experiments, this is reflected by the 8 instances for which XReason alone succeeded to compute a sufficient reason in due time, while TS+XReason failed.

However, the advantages offered by the pipeline are significant in practice most of the time (the two scatter plots and the table show clear benefits in terms of computation time and explanation size). Thus, TS+XReason appears as a better algorithm than XReason for the purpose of computing sufficient reasons. This is particularly salient in the multi-class case (both in terms of computation times and sufficient reasons found). TS also appears as a valuable algorithm for generating abductive explanations because of its efficiency (the cumulated run times over 1000 runs per instance are bounded by a few seconds). The main disadvantage of considering TS-explanations instead of sufficient reasons is that TS-explanations may contain redundant characteristics (so shorter reasons may exist in the worst case). However, our experiments show that the reduction rates achieved by TS are, in practice, close to those achieved by TS+XReason, and often significantly higher than those achieved by XReason.\(^5\) This holds both for instances for which a sufficient reason has been derived in due time and for instances for which the explanation that is derived may be redundant. This discrepancy can be explained by the fact that the implicant test performed by the TS algorithm is incomplete. As a consequence, a characteristics of the input instance can be kept while it would be removed if XReason was used instead. Removing such a characteristics during one of the first iterations of the greedy algorithm may have a strong impact on the search space and may prevent from removing many other characteristics later.

### 5 OTHER RELATED WORK

Because of their intrinsic interpretability, trees have been considered in ML and data mining for a long time and for various purposes (including classification and regression, but also reinforcement learning (Silva et al., 2020)). Trees are first-class components (weak learners) of ensemble methods. Trees have been used in various ways to resolve the tension between generalization and interpretability of black box models, for instance by mimicking the input-output functions discovered by deep neural networks (Frosst and Hinton, 2017), or by designing deep models that are more interpretable (Wu et al., 2018, 2020).

From a formal XAI perspective, decision trees have been investigated in depth (Audemard et al., 2022c; Izza et al., 2022). Decision trees support in polynomial time a number of XAI queries that are intractable for other ML models, including random forests and boosted trees (Audemard et al., 2021). Among those queries is the generation of a sufficient reason for a given instance, that is the query we focused on in this paper.

### 6 CONCLUSION

We have introduced a new notion of abductive explanation for boosted trees, called tree-specific (TS) explanations. In the worst case, TS-explanations can be arbitrarily larger than sufficient reasons. However, unlike sufficient reasons, their generation is tractable. We have presented a polynomial-time algorithm TS for computing TS-explanations, and proved its correctness. Because a sufficient reason can be extracted from a TS-explanation, TS can be used as a preprocessing step for greedy algorithms deriving sufficient reasons. Empirically, we have shown that TS+XReason significantly improves the state-of-the-art. Finally, in practice, the abductive explanations computed by TS are often close to sufficient reasons. This shows that TS is also useful alone, as an efficient generator of provably sound, valuable abductive explanations.

Various perspectives for extending this work can be envisioned. Thus, instead of considering the characteristics of the input instance randomly (line 3 of TS), it would make sense to design heuristics for making more informed choices, exploiting the derivation process user preferences about the characteristics. This can be a way to derive preferred explanations (Audemard et al., 2022b), with the user in the loop. From a practical side, it would be useful to implement algorithms for deriving preferred explanations. We plan to add such algorithms to PyXAI (www.cril.fr/pyxai/), the Python library for XAI we develop.

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\(^5\)Please keep in mind that an instance may have exponentially TS-explanations / sufficient reasons and that the two algorithms we consider compute only one of them.
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A  MISSING PROOFS

Proof of Proposition 1

Proof.

- Membership to coNP: we consider the complementary problem and show that it belongs to NP. In order to determine whether \( t \) is not an abductive explanation for \( x \) given \( BT \), it is enough to guess an instance \( x' \in X \) such that \( t \subseteq t_{x'} \) and to check that \( BT(x') \neq BT(x) \). Since the class associated by \( BT \) to any input instance can be computed in time polynomial in the size of the instance and the size of the instance, the conclusion follows.

- coNP-hardness: it has been shown in (Audemard et al., 2022a) (Proposition 3) that deciding whether \( t \) is an abductive explanation for \( x \) given a random forest \( RF \) over Boolean attributes is coNP-complete. Thus, it is enough to show that we can associate in polynomial time any random forest \( RF = \{T_1, \ldots, T_p\} \) over Boolean attributes \( A_1, \ldots, A_n \) to a boosted tree \( BT = \{F\} \) with \( F = \{T'_1, \ldots, T'_p\} \) such that for any \( x \in X \), we have \( RF(x) = 1 \) if and only if \( BT(x) = 1 \).

The reduction is easy: each \( T'_i \) (\( i \in [p] \)) is obtained in linear time from \( T_i \) by replacing every 0-leaf (resp. 1-leaf) of \( T_i \) by a leaf labelled by \(-w\) (resp. \( w\)) where \( w \) is a (fixed) positive number (e.g., \( w = 0.5 \)). By construction, we have \( RF(x) = 1 \) if and only if \( \sum_{i=1}^p T_i(x) > \frac{w}{2} \) if and only if \( \sum_{j=1}^n T_j(x) > 0 \) if and only if \( BT(x) = 1 \).

Proof of Proposition 2

Proof. Suppose that \( BT(x) = 1 \), i.e., \( w(F, x) > 0 \). By definition, \( t \) is an abductive explanation for \( x \) given \( BT \) if and only if any \( x' \in X \) such that \( t \subseteq t_{x'} \) satisfies \( BT(x') = 1 \). Since any \( x'' \in W(t, F) \) satisfies \( t \subseteq t_{x''} \), we must have \( BT(x'') = 1 \). Conversely, suppose that for any \( x'' \in W(t, F) \) we have \( BT(x'') = 1 \). Then we have \( w(F, x'') > 0 \). By definition of \( W(t, F) \), for any \( x' \in X \) such that \( t \subseteq t_{x'} \), we have \( w(F, x') \geq w(F, x'') \). Since \( BT(x'') = 1 \), we have \( w(F, x'') > 0 \), hence by transitivity of \( \geq \), we get that \( w(F, x') > 0 \), or equivalently that \( BT(x') = 1 \).

Similarly, consider the case when \( BT(x) = 0 \), i.e., \( w(F, x) \leq 0 \). By definition, \( t \) is an abductive explanation for \( x \) given \( BT \) if and only if any \( x' \in X \) such that \( t \subseteq t_{x'} \) satisfies \( BT(x') = 0 \). Since any \( x'' \in B(t, F) \) satisfies \( t \subseteq t_{x''} \), we must have \( BT(x'') = 0 \). Conversely, suppose that for any \( x'' \in B(t, F) \) we have \( BT(x'') = 0 \). Then we have \( w(F, x'') \leq 0 \). By definition of \( B(t, F) \), for any \( x' \in X \) such that \( t \subseteq t_{x'} \), we have \( w(F, x') \leq w(F, x'') \). Since \( BT(x'') = 0 \), we have \( w(F, x'') \leq 0 \), hence by transitivity of \( \leq \), we get that \( w(F, x') \leq 0 \), or equivalently that \( BT(x') = 0 \).

Proof of Proposition 3

Proof. If \( t \) is an abductive explanation for \( x \) given \( BT \), then for every \( x' \) extending \( t \) we must have \( BT(x') = i \), that is \( w(F^i, x') > w(F^j, x') \) for every \( j \in [m] \setminus \{i\} \). This is equivalent to state that \( w(F^i, x') - \max_{j \in [m] \setminus \{i\}} w(F^j, x') > 0 \). Since any worst instance \( x' \) extending \( t \) given \( BT \) and \( x \) is an instance that extends \( t \), we have

\[
w(F^i, x') - \max_{j \in [m] \setminus \{i\}} w(F^j, x') > 0,
\]

as expected.

Conversely, suppose that for any worst instance \( x' \) extending \( t \) given \( BT \) and \( x \), we have \( w(F^i, x') - \max_{j \in [m] \setminus \{i\}} w(F^j, x') > 0 \). By definition, if \( x' \) is a worst instance extending \( t \) given \( BT \) and \( x \), then for any \( x'' \in X \) that extends \( t \), we have

\[
w(F^i, x') - \max_{j \in [m] \setminus \{i\}} w(F^j, x') \leq w(F^i, x'') - \max_{j \in [m] \setminus \{i\}} w(F^j, x'').
\]

Hence, if \( w(F^i, x') - \max_{j \in [m] \setminus \{i\}} w(F^j, x') > 0 \), we also have that

\[
w(F^i, x'') - \max_{j \in [m] \setminus \{i\}} w(F^j, x'') > 0,
\]

showing that \( BT(x'') = i \).
Proof of Proposition 4

Proof. Towards a contradiction, suppose that \( BT(x) = i \in [m] \) and there exists an instance \( x' \) extending \( t \) and such that \( BT(x') = j \in [m] \) with \( j \neq i \). This implies that \( w(F^j, x') > w(F^k, x') \) for every \( k \in [m] \setminus \{j\} \). So, for \( k = i \), we have \( w(F^j, x') > w(F^i, x') \).

Since \( t \) is a tree-specific explanation for \( x \) given \( BT \), \( t \) is a subset of \( t_x \) such that for every \( k \in [m] \setminus \{i\} \), we have \( \sum_{l=1}^{p_k} w_l(t, T_i^l) > \sum_{l=1}^{p_k} w_l(t, T_i^k) \). In particular, for \( k = j \), we have \( \sum_{l=1}^{p_j} w_l(t, T_i^j) > \sum_{l=1}^{p_j} w_l(t, T_i^j) \).

However, by definition of the utmost instances, for every \( x' \) extending \( t \), we have \( w(T_i^j, x') \geq w_l(t, T_i^j) \) for every \( T_i^j \in F^i \) and \( w(T_i^k, x') \leq w_l(t, T_i^k) \) for every \( T_i^k \in F^k \) with \( k \in [m] \setminus \{i\} \). In particular, we have \( w(T_i^j, x') \leq w_l(t, T_i^j) \) for every \( T_i^j \in F^j \).

Finally, we get that \( w(F^j, x') = \sum_{l=1}^{p_j} w(T_i^j, x') \leq \sum_{l=1}^{p_j} w_l(t, T_i^j) < \sum_{l=1}^{p_j} w_l(t, T_i^j) \leq \sum_{l=1}^{p_j} w(T_i^j, x') = w(F^i, x') \). A contradiction.

Proof of Proposition 5

Proof. Consider \( BT = \{F\} \) with \( F = \{T_i^+, T_i^- : i \in [n]\} \) where for each \( i \in [n] \),

\[
T_i^+ = \begin{cases} A_i = 1 \\ -0.5 \\ 0.5 \end{cases}, \quad T_i^- = \begin{cases} A_i = 1 \\ -0.5 \end{cases}
\]

Consider the instance \( x = (0, \ldots, 0) \). We have \( w(F, x) = 0 \), hence \( F(x) = 0 \). Consider any \( i \in [n] \), let \( \{A_i = 1\} \in t_x \) and \( t = t_x \setminus \{A_i = 1\} \). For every \( j \in [n] \setminus \{i\} \), we have \( B(t, T_j^+) = B(t, T_j^-) = \{x\} \). We also have \( B(t, T_i^-) = \{x\} \).

Furthermore, \( B(t, T_i^+) = \{x'\} \) where \( x' \) is the instance that coincides with \( x \), except that \( (A_i = 1) \in t_x \). Accordingly, \( \sum_{j=1}^{n} (w(t, T_j^+) + w(t, T_j^-)) = 1 > 0 \), showing that \( t \) is not a tree-specific explanation for \( x \) given \( F \). Since the weights of the utmost instances extending a term \( t \) given \( BT = \{F\} \) vary monotonically when \( t \) is deprived of some of its elements and since \( \sum_{j=1}^{n} (w(t, T_j^+) + w(t, T_j^-)) = 0 \), we can conclude that \( t_x \) is the unique tree-specific explanation for \( x \) given \( F \). Contrastingly, since for every \( x' \in X \), we have \( F(x') = 0 \), \( \emptyset \) is the (unique) sufficient reason for \( x \) given \( F \).

Proof of Proposition 6

Proof. The proof consists of two points. First, we check that for every \( j \in [m] \setminus \{i\} \) (where \( BT(x) = i \)), we have \( \sum_{l=1}^{p_j} w_l(t_x, T_k^j) > \sum_{k=1}^{p_k} w_l(t_x, T_k^k) \) holds. Since \( x \) is the unique instance that extends \( t_x \), for any tree \( T_k^j \) of \( BT \), \( x \) is also a worst and a best instance extending \( t_x \) given \( T_k^j \). Thus, for each \( k \in [p_i] \), we have \( w_l(t_x, T_k^j) = w_l(T_k^j, x) \) and for each \( k \in [p_j] \), we have \( w_l(t_x, T_k^j) = w_l(T_k^j, x) \). Accordingly, \( \sum_{k=1}^{p_i} w_l(t_x, T_k^j) > \sum_{k=1}^{p_j} w_l(t_x, T_k^j) \) is equivalent to \( \sum_{k=1}^{p_i} w(T_k^j, x) > \sum_{k=1}^{p_j} w(T_k^j, x) \), which is equivalent to \( w(F^j, x) > w(F^i, x) \) and finally to \( BT(x) = i \), which holds.

The second point consists in verifying that if \( t, t' \) verify \( t \subset t' \subset t_x \), and for every \( j \in [m] \setminus \{i\} \), we have \( \sum_{l=1}^{p_i} w_l(t', T_k^j) \leq \sum_{l=1}^{p_i} w_l(t, T_k^j) \) holds, then \( \sum_{k=1}^{p_i} w_l(t, T_k^j) \leq \sum_{k=1}^{p_i} w_l(t, T_k^j) \) holds as well. This comes directly from the fact that when \( t \subset t' \), we have \( w_l(t, T_k^j) \leq w_l(t', T_k^j) \) for each \( k \in [p_i] \) and we have \( w_l(t, T_k^j) \geq w_l(t', T_k^j) \) for each \( k \in [p_j] \).