Noise and deviation effects in a bichromatic Raman white light cavity

Qingqing Sun,1 M. Selim Shahriar,2 and M. Suhail Zubairy1

1 Department of Physics and Institute of Quantum Studies, Texas A&M University, College Station, Texas 77843-4242
2 Departments of EECS and Physics and Astronomy, Northwestern University, Evanston, Illinois 60208-3118

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We analyze the effects of noise and parameter deviations in a bichromatic Raman type white light cavity, with potential applications in precision measurements such as gravitational wave detection. The results show that the dispersion variation induced by parameter deviation can be controlled within 10−4. The laser phase noise decreases the dispersion magnitude while the amplitude noise increases it. Although we can always adjust the parameters to satisfy the white light condition, both noises make the cavity transmission curve uneven.

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I. INTRODUCTION

In an Fabry-Perot cavity the round-trip phase delay is proportional to the frequency. Thus only certain discrete frequencies can be exactly resonant. If the cavity is filled with a medium which provides a negative dispersion and cancels the frequency dependence of the phase delay, a continuous range of spectrum can be resonant at the same time. Such a cavity is named as white light cavity (WLC) [1]. For precision measurements such as gravitational wave detection [2, 3, 4] and ring laser gyroscopes [5], the high sensitivity requires a high finesse Fabry-Perot cavity, at the price of a reduced bandwidth. WLC provides an effective way to increase the bandwidth and solves this dilemma.

The dispersion requirement for the medium is \( \partial_\nu n = -1/\nu \), where the refractive index \( n \) is a function of the frequency \( \nu \). This is the so called A-compensation or white light condition. A lot of systems are able to provide negative dispersion with small absorption or even gain [6, 7]. For example, for two-level atoms driven by a strong resonant field [8, 9], the probe dispersion is negative around the resonance. A variation of this scheme is the degenerate two-level system [10], in which there are two degenerate ground levels. Both the resonant drive field and the probe field interact with the two transitions simultaneously. The advantage of this scheme is that it does not require a very strong drive field. For a \( \Lambda \) system with a bichromatic drive field far from resonance [11, 12], the probe field experiences a gain-doublet and the dispersion is negative at the center. Another system is double-\( \Lambda \) system in which the driving field interacts with the transitions from both ground levels to one of the excited level, and the probe field interacts with the transitions from both ground levels to the other excited level [2]. Wicht et al. analyzed and compared these systems in detail [5]. Recently Savchenkov and co-workers demonstrated white light whispering gallery mode resonators [13]. For a resonator thick enough the modal spectrum becomes essentially continuous and the high quality factor is frequency-independent.

The idea of the gain-doublet scheme is proposed by Steinberg and Chiao during their pursuit of superluminal phenomena [14]. Wang et al. first realized it experimentally in a \( \Lambda \) system [11, 12]. Due to the negative dispersion, the group velocity can be superluminal or even negative. The ideal case of infinite group velocity is equivalent to the white light condition. The ability of this system to achieve the white light condition has been investigated by measuring the dispersion using a heterodyne technique [15], and by measuring the transmission spectrum [16]. A broadband cavity response has been observed.

In order to satisfy the white light condition we need to choose the parameters carefully. However, there are always deviations from the ideal values [2] and statistical noise. In this paper we discuss the effects of parameter deviations and laser phase and amplitude noises in the bichromatic Raman system.

II. PARAMETER DEPENDENCE OF THE SUSCEPTIBILITY

The level structure of the bichromatic Raman system is shown in Fig. 1. There are two drive fields with frequencies \( \nu_1 \) and \( \nu_2 \) and Rabi frequencies \( \Omega_1 \) and \( \Omega_2 \), respectively. They are far detuned from the transition \(|a\rangle \leftrightarrow |c\rangle \) with the detunings \( \Delta_0 + \Delta \) and \( \Delta_0 - \Delta \), where

\[
\Delta = (\nu_1 - \nu_2)/2 \\
\Delta_0 = \nu_{ac} - (\nu_1 + \nu_2)/2
\]

The probe field frequency \( \nu \) scans across the two Raman transitions. Such a gain doublet provides the negative dispersion at the center.

The susceptibility of the probe field can be written as

\[
\chi(\nu) = \frac{M_1}{(\nu - \nu_0 - \Delta) + i\Gamma} + \frac{M_2}{(\nu - \nu_0 + \Delta) + i\Gamma}, \quad (1)
\]

where \( \nu_0 = \frac{1}{2}(\nu_1 + \nu_2) - \omega_{bc} \) is the probe central frequency, \( M_1 = N(|\mu_{ab} \cdot \hat{e}|^2/2\hbar c)\langle |\Omega_1|^2/\Delta_0^2 \rangle \), \( (j = 1, 2) \), and \( \Gamma \) is the Raman transition line broadening. Usually we have...
In order to analyze the effect of the parameter deviations, we note that $M_j$ is proportional to both the pump field intensity $I_j$ and the number density $N$. Therefore the deviations of $I_j$ or $N$ lead to the variation of the absorption, dispersion and refractive index as

$$\frac{\delta (\partial_n)}{\partial_n} = \frac{\delta \alpha}{\alpha} = \frac{\delta M_1 + \delta M_2}{2M},$$

$$\delta n = \frac{1}{2} \frac{(-\delta M_1 + \delta M_2)\Delta}{\Delta^2 + 1^2}. \qquad (5)$$

The two intensity deviations can be independent from each other. From the proportionality between $M_j$ and $I_j$ we get

$$\frac{\delta (\partial_n)}{\partial_n} = \frac{\delta \alpha}{\alpha} = \frac{1}{2} \frac{\delta I_1}{I_1} + \frac{\delta I_2}{I_2}. \qquad (7)$$

It is easier to keep the white light condition if the relative intensity deviations of the two driving fields are of opposite signs.

On the other hand, number density deviation affects $M_1$ and $M_2$ simultaneously. Therefore

$$\frac{\delta (\partial_n)}{\partial_n} = \frac{\delta \alpha}{\alpha} = \frac{\delta N}{N}. \qquad (8)$$

From Eq. (6), the refractive index does not change under the number density deviation.

Next we consider the effect of drive frequency deviation. If the frequency $\nu_1$ is changed by the amount $\delta \nu_1$ and $\nu_2$ is changed by $\delta \nu_2$, the susceptibility would become

$$\chi(\nu) = \frac{M}{(\nu - \nu_0 - \Delta - \delta \nu_1) + i\Gamma + (\nu - \nu_0 + \Delta - \delta \nu_2) + i\Gamma}, \qquad (9)$$

From the susceptibility we can derive

$$\delta n = \frac{M(\Delta^2 - 1^2)}{2(\Delta^2 + 1^2)^2} (\delta \nu_1 + \delta \nu_2), \qquad (10)$$

$$\delta \alpha = \frac{\nu_0 M \Delta \Gamma}{c(\Delta^2 + 1^2)^2} (\delta \nu_1 - \delta \nu_2), \qquad (11)$$

$$\frac{\delta (\partial_n)}{\partial_n} = \frac{\Delta(\Delta^2 - 3\Gamma^2)}{\Delta^4 - 1^4} (\delta \nu_1 - \delta \nu_2). \qquad (12)$$

We consider the parameters from Ref. [10], i.e., $\Delta = 3.97 MHz$, $\Gamma = 1 MHz$ and $\lambda = 780 nm$. On substituting these values into the above expressions we obtain $\delta \nu_1 = 2.07 \times 10^{-10} (s) (\delta \nu_1 + \delta \nu_2)$, $\delta \alpha = 8.97 \times 10^{-10} (s/m) (\delta \nu_1 - \delta \nu_2)$, and $\delta (\partial_n)/\partial_n = -2.05 \times 10^{-7} (s) (\delta \nu_1 - \delta \nu_2)$. Compared to the double-Λ system [2], the dependence of refractive index on the drive frequency is smaller in our system. However the dependence of the dispersion and the absorption on the drive
frequency are much larger. If these two drive fields are generated from the same laser then the frequency deviations would be the same and there is no dispersion and absorption variations in this case.

Based on the same argument as in Ref. [2] we conclude that the variation results in bichromatic Raman type white light cavity can be controlled within $10^{-4}$. So in theory the white light cavity linewidth could be $10^3$ times broader than empty cavity. But of course one has to include the other imperfect effects such as the nonlinear shape of the dispersion curve, etc.

### III. EFFECT OF LASER PHASE AND AMPLITUDE NOISE

In the previous section, we calculated the effect of parameter deviations, or in a more strict sense, the deviation of the expectation value. Here we consider the noise effect from the drive fields. In other words, the expectation of the expectation value. Here we consider the noise source of the drive fields and the amplitude noises are responsible for the intensity fluctuations. We calculate the effect of these noise sources independently. For simplicity sake we assume that the separation between the two Raman peaks is much larger than the Raman linewidth and therefore we can calculate the two Raman transitions independently.

Following the expressions in Ref. [12], the effective Hamiltonian for this system can be written as

$$\hat{H} = \hat{H}_0 + \hat{H}_1 = -\hbar \omega_{ab} |b\rangle \langle b| - \hbar \omega_{ac} |c\rangle \langle c| - \hbar \Omega_p e^{-i\omega_{pt}} |a\rangle \langle b| - \hbar \Omega_1 e^{-i\omega_{1t}} |a\rangle \langle c| + H.c.$$  \hspace{1cm} (13)

A usual way to account for the effect of the laser phase noise is based on density matrix equations [17, 18], which is convenient if the coefficient matrices commute with each other. Here we follow a somewhat different approach as the usual methods are not easily applied. In particular, we consider the state vector instead of density matrix equations.

The state vector of the three-level atomic system is described by

$$|\psi\rangle = C_a(t) |a\rangle + C_b(t) e^{i\omega_{at} t} |b\rangle + C_c(t) e^{i\omega_{ct} t} |c\rangle,$$  \hspace{1cm} (14)

where $C_a(t)$, $C_b(t)$ and $C_c(t)$ are the slowly varying amplitudes. The equations of motion for the amplitudes of states $|a\rangle$ and $|b\rangle$ are

$$\dot{C}_a(t) = i\Omega_1 e^{-i\Delta_1 t} C_c + i\Omega_p e^{-i\Delta_p t} C_b,$$  \hspace{1cm} (15)

$$\dot{C}_b(t) = i\Omega_p e^{i\Delta_p t} C_a - \gamma C_b,$$  \hspace{1cm} (16)

where $\Delta_1 = \nu_1 - \omega_{ac}$ is the drive field detuning, $\Delta_p = \nu - \omega_{ab}$ is the probe detuning, and $\gamma$ is the decay rate from level $|b\rangle$. In order to produce gain for the probe field we set the atoms to be initially in the $|c\rangle$ state. To the lowest order of approximation we can take $C_c(0) \approx 1$ and $C_b(0) = 0$. It then follows on integrating Eq. (14), that

$$C_a(t) = \int_0^t i\Omega_1 e^{-i\Delta_1 t'} C_c(t') dt'.$$  \hspace{1cm} (17)

From Eq. (17) we obtain the formal solution

$$C_b(t) = \int_0^t i\Omega_p e^{i\Delta_p t'} C_a(t') e^{-\gamma(t-t')} dt'.$$  \hspace{1cm} (18)

The off-diagonal density matrix element $\rho_{ab}$ is equal to (apart from the phase factor $exp[-i\omega_{ab} t]$)

$$\langle C_a(t) C_b^* (t) \rangle = \int_0^t -i\Omega_p e^{-i\Delta_p t} \langle C_a(t) C_b^* (t') \rangle e^{-\gamma(t-t')} dt'$$

$$= \int_0^t -i\Omega_p e^{-i\Delta_p t'} e^{-\gamma(t-t')} dt' \int_0^t i\Omega_1 e^{-i\Delta_1 t''} dt'' \times$$

$$\times \int_0^t -i\Omega_p e^{i\Delta_p t'''} (\Omega_1(t'') \Omega_1^*(t''')) dt'''.$$  \hspace{1cm} (19)

In order to consider the effect of phase noise, we can write the drive Rabi frequency as $\Omega_1(t) = \Omega_1 e^{i\phi_1(t)}$. As well known the phase fluctuation of a laser is a Wiener-Levy process, i.e., the random phase with Gaussian statistics performs a Brownian motion.

$$\langle \phi_1(t) \rangle = 0,$$

$$\langle \phi_1(t) \phi_1(t') \rangle = D_1 (t+t' - |t-t'|),$$  \hspace{1cm} (20)

where $D_1$ is the phase induced bandwidth. This gives us the correlation

$$\langle \Omega_1(t) \Omega_1^*(t') \rangle = |\Omega_1|^2 \langle e^{i\phi_1(t) - i\phi_1(t')} \rangle = |\Omega_1|^2 e^{-D_1 |t-t'|}.$$  \hspace{1cm} (21)

On substituting from Eq. (21) into Eq. (19) we obtain

$$\langle C_a(t) C_b^* (t) \rangle \approx \frac{\Omega_p |\Omega_1|^2}{\Delta_0^2} \frac{e^{-i\Delta_p t}}{(\Delta_p - \Delta_1 + i(\gamma + D_1))}$$

$+$ other frequencies. \hspace{1cm} (22)

In the last step we used the far detuned condition $\Delta_0 \approx \Delta_1 \approx \Delta_p >> D_1, \gamma$ to ignore the small terms. There are also some terms with other frequencies which do not contribute to the probe susceptibility. We recall that the polarization $P = N_{\mu ab} \rho_{ab} = \chi_0 E_p^2$ where the population matrix element $\rho_{ab} = \langle C_a(t) C_b^* (t) \rangle e^{-i\omega_{ab} t}$. Therefore with both Raman transitions the probe susceptibility under phase noises is

$$\chi(\Delta_p) = \frac{M_1}{(\Delta_p - \Delta_1 + i(\gamma + D_1))} + \frac{M_2}{(\Delta_p - \Delta_2 + i(\gamma + D_2))}.$$  \hspace{1cm} (23)

This is Eq. (1) if we take $\Gamma_j = \gamma + D_j, (j = 1, 2)$. The inclusion of phase noise effectively increases the width of the gain peaks. From Eqs. (4) we find that larger $\Gamma$...
decreases the magnitude of the dispersion. In order to keep the white light condition we can adjust the parameters. For example, we can increase the field intensity to get larger $M_j$, or alternatively we can use a smaller $\Delta$. Although the dispersion condition can be restored, there is still an impact to the cavity transmission, as shown in Fig. 3. All the three curves are under white light condition with the same parameters except that $\Gamma$ increases from the lowest to the highest curve. We find that the transmission bandwidth is slightly increased but the curve becomes more uneven, which is not favorable.

Next we consider the effect of amplitude noise, $\Omega_1(t) = \Omega_1 + \delta \Omega_1(t)$. The Gaussian type fluctuation can be described by an Ornstein-Uhlenbeck stochastic process [20]

\[
\langle \delta \Omega_1(t) \rangle = 0,
\langle \delta \Omega_1(t) \delta \Omega_1(t') \rangle = I_{\Omega_1} A_1 e^{-A_1|t-t'|},
\]

where $I_{\Omega_1}$ is the variance of amplitude fluctuations and $A_1$ is the amplitude fluctuation induced bandwidth. Again by substituting from Eq. (24) into Eq. (19) we obtain

\[
\chi(\Delta_p) = \frac{M_1}{(\Delta_p - \Delta_1) + i\gamma} + \frac{I_{\Omega_1} A_1}{|\Omega_1|^2} \frac{M_1}{(\Delta_p - \Delta_1) + i(\gamma + A_1)} + \frac{M_2}{(\Delta_p - \Delta_2) + i\gamma} + \frac{I_{\Omega_2} A_2}{|\Omega_2|^2} \frac{M_2}{(\Delta_p - \Delta_2) + i(\gamma + A_2)},
\]

Similarly we have ignored the small terms in Eq. (26). In Eq. (26) both Raman transitions are included to find the susceptibility under amplitude noise. The net effect are the two additional terms which are similar to the original terms with only different coefficients and $\gamma$ changed to $\gamma + A_j$. Therefore both the dispersion and gain will increase in magnitudes. Still we can satisfy the white light condition by adjusting the parameters, for example we can decrease the drive field intensity. Similarly we will find the cavity transmission curve becomes uneven since the two additional terms have a larger linewidth $\gamma + A_j$.

\section{Conclusion}

In this paper we consider the impact of parameter deviations and laser phase and amplitude noises on a dichromatic Raman type white light cavity. We find the dispersion, which needs to satisfy the white light condition, can be controlled within $10^{-4}$ under the parameter deviations. Therefore a white light cavity could have $10^4$ times broader linewidth compared to an empty cavity at the same finesse.

The phase noise effectively increases the Raman linewidth by the diffusion $D$, causing a smaller dispersion. The amplitude noise introduces an additional term in the probe susceptibility and makes the dispersion larger. These opposite effects allow us to easily adjust the parameters to satisfy the white light condition. Both noises have the effect of making the transmission curve uneven for the white light cavity.

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