1 Introduction

The Lattice Boltzmann Equation (LBE) was introduced at the turn of the 80’s mainly to cope with two major drawbacks of its ancestor, the Lattice Gas Cellular Automaton (LGCA) [1]. Ever since, it has undergone a number of refinements and extensions which have taken it to the point where it can successfully compute a number of non-trivial flows, ranging from homogeneous incompressible turbulence to multiphase flows in porous geometries [2, 3, 4, 5]. Yet, when compared with advanced computational fluid dynamics (CFD) methods, it is apparent that there’s still some way to go before LBE can achieve full ‘engineering status’. This applies especially to flows in complex geometries where highly irregular, possibly adaptive, meshes are a must. At the same time, it is also clear that, being sharply aimed at macroscopic fluid dynamics, LBE does not share the same degree of physical fidelity of ‘true’ microscopic methods, such as Direct Simulation Montecarlo (DSMC), let alone Molecular Dynamics (MD). The question, central to the ‘leit motiv’ of this Conference, comes quite naturally: is LBE a powerful blend of the micro-macro worlds keeping the best of the two, or rather just an unremarkable hybrid giving up microfidelity with no corresponding computational returns to outdo ‘conventional’ CFD? In this paper we shall bring arguments in favour of the former alternative.

2 The Lattice Boltzmann equation

The LBE is a minimal discrete Boltzmann equation reproducing Navier-Stokes hydrodynamics in the limit of small Knudsen numbers, i.e. particle mean free path much smaller than typical macroscopic variation scales [3].

With reference to the earliest 24-speed, single-energy, four-dimensional FCHC (Face Centered HyperCube) lattice defined by the condition [3]

$$\sum_{k=1,4} c_{ik}^2 = 2 , \ c_{ik} = (0, \pm 1),$$

the LBE takes the form of a set of first-order explicit finite difference equations:

$$f_i(x_k + c_{ik}, t + 1) - f_i(x_k, t) = \sum_{j=1}^{24} A_{ij} (f_j - f_e^j)$$ (1)

where $f_i, i = 1, 24$ is a set of 24 populations moving along a corresponding set of discrete speeds $c_{ik}$ and the index $k = 1, 4$ runs over the spatial dimensions.

The eq.(1) is naturally interpreted as a multi-relaxation scheme in which non-equilibrium gradients are brought back to the local equilibrium $f_e^j$ by scattering events mediated by the matrix $A_{ij}$. The local equilibrium populations are chosen in the form of a discretized Maxwellian expanded to second order in the Mach number in order to retain convective effects.
\[
f_i^e = \frac{\rho}{24} \left( 1 + 2c_{ik}u_k + 2(c_{ik}c_{kl} - \frac{1}{2}\delta_{kl})u_ku_l \right)
\]

Under the constraint of point-wise mass and momentum conservations \(\sum_i A_{ij} = \sum_i c_{ik}A_{ij} = 0\) the equation (1) describes the motion of a four-dimensional fluid. The reason for working in four-dimensions is that no single-energy discrete lattice exists in three-dimensions ensuring isotropy of the fourth order tensor \(T_{klmn} = \sum_i c_{ik}c_{il}c_{im}c_{in}\). Such an isotropy is compelling in order to recover rotational invariance of the momentum flux tensor at a macroscopic level. With these preparations, fluid variables (density, speed and momentum flux tensor) are defined as follows:

\[
\rho = \sum_{i=1}^{24} f_i, \quad \rho u_k = \sum_{i=1}^{24} f_i c_{ik}, \quad P_{kl} = \sum_{i=1}^{24} f_i c_{i,k}c_{i,l}
\]

and can be shown to obey the Navier-Stokes equations in the continuum limit.

In the recent time, the FCHC model has been superseded by the so-called BGK (after Bathnagar, Gross and Krook in continuum kinetic theory) versions, in which the scattering matrix \(A_{ij}\) is replaced by a diagonal form \(-\omega\delta_{ij}\). Here \(\omega\) is the inverse relaxation time controlling the flow viscosity according to the simple relation

\[
\nu \sim (-1/\omega - 1/2).
\]

The resulting numerical scheme is linearly stable for all positive values of \(\nu\) \((-2 < \omega < 0\), which means that arbitrarily high Reynolds numbers \(Re = UL/\nu\), \(U\) and \(L\) being typical macroscopic flow speed and size respectively, can be attained by choosing \(\omega\) sufficiently close to \(-2\).

Current practice shows however that non linear instabilities set in if the viscosity is lowered below a given threshold \(\nu_{NL} > 0\). This nonlinear viscosity threshold is associated with the violation of the positivity constraint on the discrete populations \(f_i > 0\) and it is typically triggered whenever the fluid flow develops sharp gradients comparable in scale with the lattice pitch \(\Delta\). The result is that, like any other floating-point based method, LBE is exposed to numerical diseases whenever the lattice is not fine enough to resolve the shortest physical scales.

3 LBE in perspective

LBE is a minimal hyperbolic superset of the Navier-Stokes equations, where minimal means: “the least amount of information from velocity space” required to recover the correct continuum space-time symmetries (Galilean, translational and rotational invariance). Symbolically, we write \(K = H \oplus M\) where \(K\) is the kinetic space spanned by the discrete populations \(f_i\), \(H\) is the subspace spanned by hydrodynamic fields and \(M\) the subspace associated with mesoscopic fields. Along with the hydrodynamic fields (density, flow, temperature) LBE also tracks
the momentum-flux tensor as well as a number of higher-order moments of
the distribution function that were dubbed 'ghost-fields' since, although key
to secure the correct spatial symmetries, they do not relate explicitly to any
hydrodynamic quantity. They represent genuinely mesoscopic information.

The fact that the momentum flux tensor is also carried along, means that
LBE is more than a plain Navier-Stokes solver. This property is of no use for
the direct simulation of fluid turbulence but it becomes very valuable when it
comes to turbulence modeling since it permits straightforward and cheap im-
plementations of stress-tensor dependent effective viscosities such as those used
in algebraic turbulence models [8, 9]. Ghost fields are an inevitable overhead,
somehow the price to pay to formulate hydrodynamics in a fully covariant form.
It should be appreciated that this covariant (read hyperbolic) formulation brings
about two interesting numerical implications: i) diffusion does not require sec-
ond order space derivatives, ii) convection takes place along constant streamlines
defined by the condition \( \Delta x_{ki} = c_{ki} \Delta t \). Both features prove extremely benefi-
cial for the amenability of LBE to parallel computing. Ideally, one would like to
draw some further benefit from ghost fields, namely use the mesoscopic scales to
do 'some good' to the hydrodynamic ones. As they stand, unfortunately ghost
fields don’t seem to provide any beneficial effect on the non-linear stability prop-
erties of the scheme. However, they can be manipulated to construct subgrid
turbulence models [3] which, regretfully enough, have not been implemented
so far. So, to date, one must conclude that no positive feedback between the
mesoscopic and the macroscopic components of LBE has been put in operation.

In CFD parlance we would classify LBE as a "Strictly synchronous, first
order in time, second order in space, fully explicit finite difference scheme".

Within this wide class of CFD schemes, the main hallmarks of LBE are

- Point-wise conservativeness to machine round-off
- Unconditional linear stability
- Diffusion-dispersion freedom
- Finite hyperbolicity
- High compute density (operations/grid point)

Main pro’s are:
- Amenability to parallel computing
- Easy handling of grossly irregular geometries (e.g., porous media)
- Ease of use and physical soundness

Counteracting con’s
• Uniform-grid boundness

• Computational redundance (ghost fields)

One may notice that all of these points, both pro’s and con’s are technical in nature rather than fundamental. This reflects the historical focus of LBE on fluid-dynamics, and-to a good extent- the author’s own bias as well.

Happily enough, some researchers have wisely turned an eye also to the ’fundamental’ direction, and worked out ways to extend the method so as to embed genuinely mesoscopic physics. Remarkable work along this line has been performed in the recent past [11, 12, 13, 14] and interesting attempts to ’walk upwards’ the BBGKY hierarchy are just starting to appear [15].

4 Success

As of today, almost ten years after its inception, the body of LBE calculations is simply too wide to be covered by any single comprehensive paper. Best approximation, and yet already partially outdated, is the recent review paper by Qian et al [4].

In a way, this is probably the best sign of success.

Many of these calculations may have been successfully performed by other CFD methods as well, but probably, not all of them. It looks like some multiphase flows calculations appear to come by much more easily-if not more efficiently-using LBE rather than ‘conventional’ grid-based techniques. Particularly enticing to the physicist’s taste is the fact most of the new physics can be encoded into suitable generalizations of local equilibria and/or phenomenological source terms reflecting the assumptions on the underlying microscopic physics. Whether there is more to this explicit link between physics and numerics than esthetical satisfaction is difficult to say; for sure, it is an extremely pleasing feature of the method. An indisputable fact is the success of LBE applications on (virtually any kind of) parallel computers. As a recent first-hand example, our group in Rome is currently running turbulent channel flow LBE simulations at sustained speeds in excess of 10 Gflops using massively parallel SIMD machines [17]. And even at the industrial level, LBE high amenability to parallel computing has opened the way to complex flow calculations such as those performed at Shell Research.

5 Open problems and future developments

Two major stumbling blocks have been holding back engineering and physics LBE applications:

• Uniform-grid boundness
• Non linear stability of thermohydrodynamic schemes

While the former limitation has been basically overcome in the recent years, the latter is still with us. Let us comment in some more detail.

5.1 Uniform Grid

To the best of the author’s knowledge, to date, nobody knows how to extend synchronous LBE schemes of the form given by eq. (1) to generalized coordinates and/or irregular mesh distributions. This is a major stumbling block, as it rules out a host of important real-life engineering applications.

The problem has been (partially) circumvented by marrying LBE with standard Finite-Volume and, more recently, Finite-Difference techniques [17].

The basic idea is to focus on the continuum version of LBE, namely

\[
\partial_t + c_{ik} \partial_k f_i(x_k, t) = \sum_{j=1}^{24} A_{ij} (f_j - f_j^e)
\]  

(4)

and recognize that this is nothing but a set of hyperbolic partial differential equations, which can handled by any of the commonly available discretization techniques.

Manifestly, by adopting a generic time marching and space discretization scheme, the synchronization between discrete speeds and the spatial stencil is generally spoiled (\(\Delta x_{ik} \neq c_{ik} \Delta t\)). So, one may refer to these extensions as to asynchronous LBE (ALBE). This is precisely where the geometrical flexibility comes from, since the spatial stencil is now set free from the symmetry requirements imposed to the discrete speeds. The price for geometrical freedom is the need to interpolate between the particle positions generated by the discrete speeds and the sites of the spatial grid. Besides sheer computational extra costs (easily offset by conspicuous savings in the number of grid points), this interpolation may introduce numerical diffusion effects which are still awaiting for a definitive assessment.

All in all, it is fair to say that much of the initial gap between LBE and advanced CFD in terms of handling complex geometries is going to close up in the near future.

5.2 Non-linear stability

When discussing non-linear stability, it is useful to bear in mind that the discrete grid sets an intrinsic lower bound to the flow viscosity (upper bound on Reynolds number) that can be used in the numerical simulation of the Navier-Stokes equations. This lower bound is given by:

\[ \nu_{\Delta} = u_{\Delta} \Delta \]

where \(u_{\Delta}\) is the velocity field at the grid scale \(\Delta\).
This limit, a real sort of *Numerical Uncertainty Principle* (NUP) cannot be violated by any *direct* simulation method of the Navier-Stokes equations without incurring numerical bankruptcy or, worse, fake physical results. Isothermal LBE calculations can systematically be brought down to viscosities pretty close to the NUP value, with most empirical evidences for a non-linear viscosity threshold within a 50 percent higher than the NUP value.

For 'hot', thermodynamic calculation the situation is much less clear. According to some researchers, the stability threshold undergoes a severe deterioration which makes LBE's totally unsuited to thermohydrodynamic computations \[10\]. That may indeed be the case since thermal LBE schemes are highly remnant of high-order finite differences stencils whose exposure to numerical instabilities is pretty well known. However, a lot more quantitative work is required, before any conclusive statement can be drawn in this respect.

In particular two promising ideas are worth being mentioned here. The first consists of using higher-order expansions in the Mach number of local equilibria \[18\]. A close inspection of these schemes reveals the appearance of *negative definite* equilibrium populations; at a first glance, this may sound like complete nonsense, but, with a little bit of optimism, one might observe that negative populations do not hurt stability as long as they stay negative all the time. In this case, one may just reinterpret them as 'holes' or 'antiparticles' and hope their presence help decrease the non-linear viscosity threshold by partially relaxing the constraint that all populations be positive. In fact, a blend of particles and antiparticles could prove more stable; the compelling condition being that they don't transform one into another, i.e. populations should not change sign under any flow condition. A second, more solid, possibility is to use full Maxwellian equilibria rather than Mach number expansions \[19\]. The obvious advantage is that all equilibrium populations are positive by definition. The price is computational overhead since the Lagrangian multipliers of the local maxwellian cannot be assigned a priori but need be recomputed on the fly, thus implying a small non-linear algebraic problem at each lattice site and each time step. Alternatively, a pre-computed table look-up could also be employed.

Whether or not these ideas will prove successfull remains to be seen; for sure they look promising and deserve thorough exploration before discrete-speed models are ruled out for thermohydrodynamic applications.

### 6 Conclusions

As mentioned in the Introduction, LBE was generated as an off-spring of lattice Gas Cellular Automata (LGCA). Most of the excitement behind LGCA was driven by the "Grand-Dream":

\[\text{LGCA} : \text{Turbulence} = \text{Ising Model} : \text{Phase Transitions}\]

Ten years later, all reasonable indications are that the "Grand-Dream" has turned into a "Grande-Illusion" (but, who knows for the future?).
LBE was born on a much less ambitious footing; just provide a useful tool to investigate fluid dynamics and, maybe mesoscopic phenomena, on parallel machines. And in that respect, it appears hard to deny that, even though much remains to be done, the method has indeed lived up to the initial expectations. As for the future, competition with macroscopic CFD does not promise any spectacular breakthrough; here LBE should probably be regarded as "yet another finite difference scheme", very easy to use and implement, very rewarding on parallel computers, but with no compelling edge over existing methods. The situation may turn for the best on two conditions: i) relax uniform grid constraint and ii) make intelligent use of mesoscopic information to access higher Reynolds number flows. The former goal is partially achieved, the latter is currently left unexplored.

Use of LBE for truly mesoscopic fluid dynamics problems appears to be the "golden avenue" for the future: whenever a reliable mesoscopic LBE scheme can be put at work, the resulting computational gain over existing microscopic methods (Direct Simulation Monte Carlo, Molecular Dynamics) will not score factors but (several) orders of magnitude.

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