Metric Inequalities with Scalar Curvature.

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Abstract

We establish several inequalities for manifolds with positive scalar curvature and, more generally, for the scalar curvature bounded from below. In so far as geometry is concerned these inequalities appear as generalisations of the classical bounds on the distances between conjugates points in surfaces with positive sectional curvatures.

The techniques of our proofs is based on the Schoen-Yau descent method via minimal hypersurfaces, while the overall logic of our arguments is inspired by and closely related to the torus splitting argument in Novikov’s proof of the topological invariance of the rational Pontryagin classes.

1 Formulation of the Key Inequalities.

Our point of departure is the following inequality for torical bands which are smooth manifolds homeomorphic to tori times intervals.

**Torical \( \frac{2\pi}{n} \)-Inequality.** Let \( V \) be an \( n \)-dimensional torical band, \( V = \mathbb{T}^{n-1} \times [-1, +1] \), where the boundary is

\[
\partial(V) = \partial_- \cup \partial_+ = \partial_- (V) \cup \partial_+ (V) = (\mathbb{T}^{n-1} \times \{-1\}) \cup (\mathbb{T}^{n-1} \times \{+1\}).
\]

Let \( g \) be a smooth Riemannian metric on \( V \), where the scalar curvature is bounded from below by a positive constant \( \sigma > 0 \),

\[
\text{Sc}(g) \geq \sigma > 0.
\]

Then the distance between the two boundary components of \( V \) satisfies

\[
\left[ \ominus \leq 2\pi \sqrt{\frac{n-1}{\sigma n}} \right] \quad \text{dist}_g = \text{dist}_g(\partial_- (V), \partial_+ (V)) \leq 2\pi \sqrt{\frac{n-1}{\sigma n}} \left( < \frac{2\pi}{\sqrt{\sigma}} \right).
\]

On Normalisation of \( \text{Sc} \). We use the customary normalisation of the scalar curvature, where the unit spheres satisfy

\[
\text{Sc}(S^n) = n(n-1).
\]

Thus, by scaling, the inequality \( \left[ \ominus \leq 2\pi \sqrt{\frac{n-1}{\sigma n}} \right] \) for a non specified \( \sigma > 0 \) reduces to that for \( \text{Sc}(V) \geq n(n-1) \), where it reads

\[
\left[ \ominus \leq \frac{2\pi}{n} \right] \quad \text{dist}_g = \text{dist}_g(\partial_- (V), \partial_+ (V)) \leq \frac{2\pi}{n}.
\]
In particular, 

**all torical bands in the unit sphere, satisfy**

\[ \text{dist}(\partial_-, \partial_+) \leq \frac{2\pi}{n}. \]

This is obvious for \( n = 2 \), where \( [\Theta_2 \leq \frac{2\pi}{2}] \) is sharp as well as obvious. One also expects a two line proof of a stronger inequality for all \( n \), but to my surprise, I was unable to directly prove even the corresponding inequality for principal curvatures of \((n-1)\)-tori embedded to \( S^n \), where this inequality is formulated below in terms of focal coradii as follows.

**Normal Tubes, Normal Bands and \( \text{rad}^O(Y) \).** The **normal focal radius** of a smooth submanifold \( Y \) in a Riemannian manifold \( X \), denoted \( \text{rad}^O(Y) = \text{rad}^O(Y \subset X) \) is the maximal \( r \) such that the normal exponential map \( \exp: T_\perp(Y) = T(Y)/\ker(Y) \to X \) is one-to-one on the subset of vectors \( \nu \in T_\perp(Y) \), such that \( \|\nu\| < r \). In other words, this is the maximal \( r \) such that the normal \( r \)-tube around \( Y \), called normal \( r \)-band if \( \text{codim}(Y) = 1 \), that is the open \( r \)-neighbourhood \( U_r(Y) \subset X \) for \( r = \text{rad}^O \), normally projects to \( Y \) and fibers \( U_r(Y) \) into \( r \)-balls of dimension \( \dim(X) - \dim(Y) \).

**Examples.** (a) The normal focal radii and the geodesic curvatures of sub-spheres

\[ S^m(\rho) = S^m_s(\rho) \subset S^n = S^n(1) \subset \mathbb{R}^{n+1}, \rho \leq 1, \]

centered at points \( s \in S^n \) are

\[ r = \text{rad}^O_s(S^m(\rho)) = \arcsin \rho \text{ and } \text{curv}_{S^n}(S^m(\rho)) = \frac{\sqrt{1 - \rho^2}}{\rho} = \tan r. \]

(b) The Clifford torus \( \mathbb{T}_{Cl}^n \subset S^{2n-1} \subset (\mathbb{R}^2)^n \), that is the product of \( n \) circles of radii \( \frac{1}{\sqrt{n}} \) in the plane, satisfies:

\[ \text{rad}^O(\mathbb{T}_{Cl}^n) = \arcsin \frac{1}{\sqrt{n}}. \]

Conjecturally, \( \mathbb{T}_{Cl}^n \) has maximal \( \text{rad}^O \) among all \( n \)-tori smoothly embedded to \( S^{2n-1} \).

**Normal Radius Inequality for \( \mathbb{T}^{n-1} \subset S^n \).** If a smooth hypersurface \( Y \) in the unit \( n \)-sphere is homeomorphic to the \((n-1)\)-torus, then

\[ \Theta \leq \frac{\pi}{n}. \]

\[ \text{rad}^O(Y) \leq \frac{\pi}{n}. \]

This inequality—this will become clear later on—is non-sharp.

---

1It would be more in the spirit of "focal" to require the normal exponential map to be **locally** one-to-one, but this, probably, makes no difference in the present context for \( X = S^n \).

2This projection sends each \( x \in U_r(Y) \) to the unique(!) nearest point in \( Y \).
Conjecturally, the sharp constant must be asymptotic for $n \to \infty$ to
\[
\frac{\text{const}}{n^\alpha} \quad \text{for some } \alpha > 1.
\]

On Sharpness of $\left[ \bigotimes \leq \frac{2\pi}{n} \right]$. This inequality agrees with the obvious one in the 2-sphere (where the conventionally defined scalar curvature equals twice the sectional curvature) where the widths of the bands between concentric circles as well as the distances between opposite sides of (all) quadrilaterals are bounded by $\frac{2\pi}{n} = \pi = \text{diam}(S^2)$ and where these inequalities become sharp for doubly punctured spheres and for quadrilaterals which degenerate to geodesic digons joining opposite points in $S^2$.

And if $n \geq 2$, we shall see in the next section that the extremal bands, where $\text{dist}_{\phi} = \frac{2\pi}{n}$, also have constant scalar curvatures and their opposite sides collapse to points, but they do not have constant sectional curvatures for $n > 2$ anymore.

**Quadratic Decay Theorem.** Let $X$ be a complete Riemannian manifold, and let
\[
\min_{B(R)} \text{Sc}(X)
\]
denote the minimum of the scalar curvature (function) of $X$ on the ball $B(R) = B_{x_0}(R) \subset X$ for some centre point $x_0 \in X$.

If $X$ is homeomorphic to $\mathbb{T}^{n-2} \times \mathbb{R}^2$, then there exists a constant $R_0 = R_0(X, x_0)$, such that
\[
\left[ \leq \frac{4\pi^2}{R^2} \right] \quad \min_{B(R)} \text{Sc}(X) \leq \frac{4\pi^2}{(R - R_0)^2} \quad \text{for all } R \geq R_0.
\]

**Outline of the Proof.** Let $X_0 \subset X$ corresponds to the torus $\mathbb{T}^{n-2} \times \{0\} \subset \mathbb{T}^{n-2} \times \mathbb{R}^2$ under the homeomorphism $\mathbb{T}^{n-2} \times \mathbb{R}^2 \leftrightarrow X$ and let $R_0 = \text{diam}(X_0)$. Then the $(R - R_0)$-neighbourhood $U_{R - R_0}(X_0) \subset X$ is contained in the ball $B_{x_0}(R)$ for $x_0 \in X_0$.

If $U_{R - R_0}(X_0)$ is homeomorphic to $\mathbb{T}^{n-1} \times (-1, +1)$, then $\left[ \leq \frac{4\pi^2}{R^2} \right]$ follows from the torical $\frac{2\pi}{n}$-inequality and if the topology of $U_{R - R_0}(X_0)$ is more complicated, then we apply a generalisation of the $\frac{2\pi}{n}$-inequality from section 4.

On Uniformly Positive Scalar Curvature. The obvious corollary to $\left[ \leq \frac{4\pi^2}{R^2} \right]$ is non-existence of complete metrics with $\text{Sc} \geq \sigma > 0$ on $\mathbb{T}^{n-2} \times \mathbb{R}^2$.

Notice that there are similar results for other manifolds $X$ proven with Dirac operators twisted with suitable "almost flat" bundles over $X$ [GL 1983], [HaPS 2015].

However, for all I know, one can’t rule out metrics with uniformly positive scalar curvature on $\mathbb{T}^{n-2} \times \mathbb{R}^2$ with the present day Dirac operator methods.  

**Examples of Metrics on $\mathbb{T}^{n-2} \times \mathbb{R}^2$ with Quadratic Decay of Scalar Curvature.**

Let $g = dt^2 + \varphi(t)^2 d\theta^2$, $t \in [0, \infty)$, $\theta \in [0, 2\pi]$, be a radial (rotationally symmetric) metrics on $\mathbb{R}^2$. Then
\[
\text{Sc}(g)(t) = -\frac{2\varphi''(t)}{\varphi(t)};
\]

Bernhard Hanke indicated to me how one can do this, see section 7.
thus, the metrics
\[ g_{fl} + dt^2 + t^{2\alpha}d\theta^2 \]
on \mathbb{R}^2 \times \mathbb{T}^{n-2}, where \( g_{fl} \) are flat on \( \mathbb{T}^{n-2} \) and where \( 0 < \alpha < 1 \), do the job.

1.1 On Generalisations and Proofs: Admissions and and Acknowledgements

Simple generalisations of everything we stated so far is proven in section 2.

Then, in the following sections, we formulate and prove further generalisations and refinements of these. Also we indicate additional applications and articulate several conjectures.

Our approach is based on the Schoen-Yau dimension descent argument [SY-Str 1979], [SY 2017] accompanied by torical symmetrization [GL 1983] and/or symmetrization by reflection [Gr 2014*].

However, some of our arguments have certain limitations which are indicated below.

1. Problem with Singularities. Applications of minimal hypersurfaces \( Y \subset X \) to \( Sc \geq 0 \) depends on the regularity of these \( Y \) which is known to hold for all \( Y \) if \( n = \text{dim}(X) \leq 7 \) and for generic ones for \( n = 8 \) by a Nathan Smale theorem [NS 1993] More recently, Lokhamp [Loh 2016] and Schoen and Yau [SY 2017] suggested ways of bypassing the singularity problem.

As far as I understand, the regularity results by Schoen and Yau in [SY 2017], such as theorem 4.6, suffice for the needs of the present paper and this is, probably, true about the corresponding results by Lokhamp. But since I have not studied these papers in depth, I can vouch for the validity of our proofs only for \( n \leq 8 \), where the singularity problem does not exist.

2. Doubling, Reflecting and Smoothing. Some results concerning closed Riemannian manifolds \( X \) with \( S_t \geq 0 \) generalise to manifolds \( X \) with boundary and, accordingly, to bands of the form \( X \times [-1,1] \).

For instance if the boundary \( \partial = \partial X \) is mean curvature convex, i.e. if \( \text{mn.curv}(\partial) > 0 \), then \( X \) admits a full fledged theory of minimal hypersurfaces \( Y \subset X \) with (free) boundary \( \partial Y \subset \partial X \) and the Schoen-Yau descent method applies.

Alternatively, one may take the double
\[ \tilde{X} = X \cup_{\partial} X \]
and show (see [GL 1980], and section 11.4) that

the natural continuous (but not necessarily smooth, not even \( C^1 \)) Riemannian metric \( \tilde{g} = g&g \) on \( \tilde{X} \) can be \( C^0 \)-approximated by smooth \( C^\infty \)-smooth metrics \( \tilde{g}_{\epsilon} \) with no decrease of the scalar curvature of \( \tilde{g} \). (The scalar curvature of \( \tilde{g} \) is unambiguously defined away from \( \partial \), which naturally embeds as a hypersurface in \( \tilde{X} \).)

Thus

all results for closed manifolds \( X \), including those obtained with the Dirac operator methods, extends to manifolds with mean curvature convex boundaries.

(Analysis of extremal cases, e.g. showing that every metric \( g \) on \( X = \mathbb{T}^{n-1} \times [0,1] \), where \( \text{mn.curv}(\partial(X)) = 0 \), is Riemannian flat, needs an additional care.)
Next, let \( X \) be a manifold with corners, such, for instance, as the Cartesian product of several manifolds with boundaries, such as the \( n \)-cube

\[
\Box^n = [0,1] \times \ldots \times [0,1],
\]

or an \( V \) diffeomorphic to \( \Box^n \).

Schoen-Yau descent, probably, applies to such \( X \), where one may encounter complications with singularities of minimal hypersurfaces, \( Y \subset V \) with \( \partial Y \subset \partial X \), at the corners of \( X \) on the boundary \( \partial X \).  

There is an alternative approach applicable to those \( X \), which serve as fundamental domains of reflection groups \( \Gamma \) acting on manifolds \( \tilde{X} \) without boundaries. 

For instance, if \( X \) is diffeomorphic to the \( n \)-cube \([0,1]^n\), then \( \tilde{X} \) is naturally homeomorphic to the Euclidean space \( \mathbb{R}^n \) acted on by the group \( \Gamma \) (isomorphic to \( \mathbb{Z}^n \times \mathbb{Z}_2^n \)) generated by reflections of \( \mathbb{R}^n \) in the hyperplanes \( \{ x_i = 0 \} \) and \( \{ x_i = 1 \}, i = 1, \ldots, n \), in \( \mathbb{R}^n \).

This \( \tilde{X} \) carries a unique path metric \( \tilde{g} \), which is equal to the original Riemannian metric \( g \) on \( X \subset X \), where \( X \) is embedded to \( \tilde{X} \) as a fundamental domain.

In general, unlike the case where \( X \) is isometric to \([0,1]^n\), rather than only diffeomorphic to it, the metric \( \tilde{g} \) is non-smooth at the boundary \( \partial X \subset \tilde{X} \) (as well as at the boundaries of the \( \Gamma \)-translates of \( X \)). In fact, this metric is continuous (but not, in general, \( C^1 \)-smooth) at the smooth points of \( \partial X \) which correspond to the interior points in the \( (n-1) \)-faces of \([0,1]^n\), and it is only piecewise continuous at the edges.

In fact the metric \( \tilde{g} \) is Riemannian continuous if and only the dihedral angles between the \( (n-1) \)-faces of \( X \) along the "edges" (corresponding to the \( (n-2) \)-faces of \([0,1]^n\)) equal \( \frac{\pi}{2} \) and then \( \tilde{g} \) is \( C^1 \) (only) if the \( (n-1) \)-faces are totally geodesic with respect to this metric.

It follows from the Approximation/Reflection Lemma in section 4.9 in [Gr 2014*] that

if the the faces of \( X \) are mean curvature convex and if the dihedral angles between these faces along the corners in \( X \) are bounded by \( \frac{\pi}{2} \), then \( X \) carries smooth(!) \( \Gamma \)-invariant metrics \( \tilde{g}_\varepsilon, \varepsilon \to 0 \), which are, in some weak sense converge to the original metric \( g \) on \( X \subset \tilde{X} \) and such the scalar curvatures of \( \tilde{g}_\varepsilon \) are bounded from below by \( Sc(g) \) on \( X \subset \tilde{X} \).

Granted this, many (all?) properties of closed (and complete) manifolds with \( Sc \geq \sigma \) generalise to manifolds with suitable corners, e.g.

non-existence of cubical (i.e. diffeomorphic to \([0,1]^n\)) domains in Riemannian manifolds \( X \) with \( Sc(X) \geq 0 \) (e.g. in \( X = \mathbb{R}^n \)), such that the \( (n-1) \)-faces of these domains have \text{min.curv} > 0 and the dihedral angles between these faces are \( \leq \frac{\pi}{2} \), see [Gr 2014*]).

However – this was pointed out by the referee of the present paper – the way it was written in the original version of this paper was unsatisfactory.

We discuss in section 11.8 what should be done about it.

3 Acknowledgements. I want to express my gratitude to the anonymous referee for the time and effort he/she has spent reading this article. Besides point-

\[^4\text{Possibly, an adequate regularity of minimizing hypersurfaces at the corner points is known to some people, but I could not locate such result in the literature.}\]
ing out inadequacy of the first version of our treatment of smoothing multiple corners and of minimal hypersurfaces in non-compact manifolds, the referee has indicated many other inconsistencies and errors in the paper – more than 60 in the first draft of the paper and more than 100 in the present version. Also he/she has made several insightful suggestions which necessitated the appearance of the appendix (section 11) in this article.

2 Bounds on Widths of Over-torical and Related Riemannian Bands.

A band is a manifold $V$ with two distinguished disjoint non-empty subsets in the boundary $\partial(V)$, denoted

$$\partial_\pm = \partial_\pm(V) \subset \partial V$$

A band is called proper if $\partial_\pm$ are unions of connected components of $\partial V$ and

$$\partial_\pm \cap \partial_\pm = \partial V.$$  

Band maps $\nu \to \nu'$ are those continuous ones which respect these $\pm$-boundaries, $\partial_\pm \to \partial_\pm'$.

If $V$ is endowed with a Riemannian metric then the width of a band is the distance between $\partial_-$ and $\partial_+$, that is the infimum of length of curves in $V$ between $\partial_-$ and $\partial_+$.

A compact proper orientable band is called over-torical if it admits a band map to the toric band,

$$f: V \to \mathbb{T}^{n-1} \times [-1,+1], \ n = \text{dim}(V),$$

with non-zero degree.

Another way to put it is by saying that the relative fundamental class $[V] \in H^n(V, \partial V; \mathbb{Q})$ decomposes to the product

$$[V] = h_1 \wedge \ldots \wedge h_{n-1} \wedge h_n$$

where $h_i, \ i = 1, \ldots, n-1$, are (absolute) 1-dimensional cohomology classes, $h_i \in H^1(V; \mathbb{Q})$, and $h_n \in H^1(V, \partial V; \mathbb{Q})$ is the (relative) class, of the differential of a function $V \to [-1,+1]$ such that $\partial_\pm \to \pm 1$.

If $V$ is non-orientable, then overtorical means that an orientable finite cover of $V$ is overtorical.

**Toric Symmetrization.** There exists a quasi-functorial symmetrization "operator" from Riemannian over-torical bands to torical ones

$$\text{Sym}: V \to \mathbb{T}^{n-1}$$

where $V$ admits a free isometric action of the torus $\mathbb{T}^{n-1}$ and such that

$$\text{width}(V) \geq \text{width}(V')$$

and

$$\text{Sc}(V) > \sigma \Rightarrow \text{Sc}(V) > \sigma.$$
Proof. This is proven in a slightly different form in [GL 1983] for \( n \leq 7 \) by induction as it is explained below.

(Earlier, such symmetrization for \( n = 3 \) was used by Fisher-Colbrie and Schoen [FCS 1980], while the proof for \( n = 8 \) is essentially the same as for \( n \leq 7 \) due to Nathan’s Smale generic regularity theorem.)

Induction Step. Let \( V_k \) be a \( \mathbb{T}^k \) invariant Riemannian band, \( k = 0, \ldots, n - 2 \), which admits a \( \mathbb{T}^k \)-equivariant band map to the torical band

\[
f_k : V_k \to \mathbb{T}^{n-1} \times [-1, +1]
\]

where \( \mathbb{T}^k \) acts on \( \mathbb{T}^{n-1} \times [-1, +1] \) via the standard (coordinate) embedding \( \mathbb{T}^k \subset \mathbb{T}^{n-1} \) and such that \( \text{deg}(f_k) \neq 0 \).

Let \( Y_k \subset V_k \) be a volume minimising hypersurface which is homologous to the \( f_k \)-pullback of \( \mathbb{T}^{n-2} \times [-1, +1] \subset \mathbb{T}^{n-1} \times [-1, +1] \) for the torus \( \mathbb{T}^{k+1} \supset \mathbb{T}^k \), where "homologous" refers to the relative group \( H_{n-1}(V_k; \partial V_k = \partial_1 \cup \partial_2) \).

It is easy to see that this \( Y_k \) is \( \mathbb{T}^k \)-invariant and that the lowest eigenfunction \( \phi(y) \) of the second variation operator \( L \) on \( Y_k \),

\[
L = -\Delta + \frac{1}{2} (Sc(Y_k) - Sc(V_k|Y_k) - \|\text{curv}_{V_k}(Y_k)\|)^2
\]

is also \( \mathbb{T}^k \)-invariant. (Here, \( \Delta \) is the Laplacian on \( Y_k \), that is \( \sum_i \frac{\partial^2}{\partial y_i^2} \) and \( \text{curv}_{V_k}(Y) \) denotes the second fundamental form of \( Y_k \subset V_k \).)

Then we let \( V_{k+1} = Y_k \times \mathbb{T}^1 \) with the metric \( dy^2 + \phi^2 dt^2 \), where a simple computation shows that if the scalar curvature of \( V_k \) restricted to \( Y_k \) is \( \geq \sigma \), then the scalar curvature of \( V_{k+1} \) is also bounded from below by \( \sigma \).

It is also clear that \( V_{k+1} \) admits a \( \mathbb{T}^{k+1} \)-equivariant band map of degree \( \text{deg}(f_k) \) to the torical band and that \( \text{width}(V_{k+1}) \geq \text{width}(V_k) \).

Thus, the inductive step is completed and the existence of torical symmetrization follows. (See [GL 1983] for details).

Remark on Singularities. \( \mathbb{T}^n \)-invariant minimal hypersurfaces in \( V_k \) correspond to hypersurfaces in the quotient manifolds \( V_k/\mathbb{T}^k \), which are minimal with respect to the quotient metrics with obvious conformal weights. Then theorem 4.6 in [SY 2017] says, in effect, that even if some hypersurfaces \( Y_k \) were singular, say for \( n - k \geq 8 \), the final \( \mathbb{T}^{n-1} \)-symmetric \( V_{n-1} = \mathcal{V} \) are non-singular.

(Schoen and Yau formulate their theorem for closed manifolds but the needed regularity for manifolds \( V \) with boundaries trivially reduces to that for doubles of \( V \).)

\( 2\pi \)-Inequality for Over-Torical Bands. Overtorical bands with scalar curvatures \( \geq n(n-1)(= Sc(S^n)) \) satisfy

\[
[\text{dist}_a \leq \frac{2\pi}{n}] \quad \text{width}(V) \leq \frac{2\pi}{n}.
\]

Proof. Torical symmetrization reduces the general case to that of \( \mathbb{T}^{n-1} \)-invariant metrics \( y \), on torical bands, where

\[
g = dt^2 + \sum_i \varphi_i(t)^2 dr_i^2, \quad i = 2, 3, \ldots, n.
\]
Then one easily computes
\[
\text{Sc}(g)(t, \tau_2, ..., \tau_n) = -2 \sum_i \varphi''(t) - 2 \sum_{i < j} \frac{\varphi_i'(t)}{\varphi_j(t)} \cdot \frac{\varphi_j(t)}{\varphi_i(t)}
\]
and shows that the the longest \(t\)-interval where this function remains defined for \(\text{Sc}(g) \geq \sigma > 0\) is achieved with \(\varphi_2 = ... = \varphi_n = \varphi\), where the proof follows by simple computation on p.401 in [GL 1983] which is reproduced below in the description of optimal (maximal) torical bands with \(\text{Sc} \geq \sigma\).

Proof of Propositions from Section 1. The inequality \([\text{dist}_n \leq \frac{2\pi}{n}]\) implies everything we have stated so far, where in the case of the quadratic decay theorem one needs to observe that the domains \(U_{R-R_0}(X_0) \subset X\) (defined following the statement of this theorem) are, in an obvious sense, open overtorical bands to which the above \(\frac{2\pi}{n}\)-Inequality applies.

Notice at this point that this argument automatically delivers the following

Generalisation of The Quadratic Decay Theorem. If a complete orientable Riemannian \(n\)-manifold \(X\) admits a proper continuous map \(X \to \mathbb{T}^{n-2} \times \mathbb{R}^2\) of non-zero degree, then the minima of the scalar curvature of \(X\) over concentric \(R\)-balls in \(X\) satisfy

\[
\left[\frac{4\pi^2}{\pi^2}\right]^* \min_{B(R)} \text{Sc}(X) = \frac{4\pi^2}{(R-R_0)^2} \text{ for some } R_0 \geq 0 \text{ and all } R \geq R_0.
\]

Optimality of \(\frac{2\pi}{n}\). Every smooth manifold \(V = Y \times [-1, 1]\) admits a Riemannian metric \(g = g_e\) with \(\text{Sc}(g) \geq n(n-1)\) and the \(g\)-distance between the two boundary components \(Y \times \{-1\}\) and \(Y \times \{1\}\) in \(V\) equal \(2\pi/n - \varepsilon\) for a given \(\varepsilon > 0\).

For instance, if \(Y = S^1\), then the spherical suspension \(V = \Theta(Y)\) serves this purpose for all \(\varepsilon > 0\).

More generally, given a Riemannian metric \(g_0\) on \(Y\) and a real function \(\varphi(t)\), let \(g = dt^2 + \varphi(t)^2g_0\) be the metric on \(Y \times [-l, l]\). If \(g_0\) is flat then

\[
\sigma = \text{Sc}(g) = -2(n-1)\varphi'' + (n-1)(n-2)\frac{\varphi'^2}{\varphi},
\]

or

\[
\frac{\sigma}{n-1} = -2\left(\frac{\varphi''}{\varphi} + \frac{\varphi'^2}{\varphi^2}\right) - n\frac{\varphi'^2}{\varphi^2},
\]

that is

\[-2f' - nf'^2 = \frac{\sigma}{n-1} \text{ for } f = \frac{\varphi'}{\varphi}\]

Now let \(\sigma = \text{Sc}(S^n) = n(n-1)\) and rewrite the above as

\[
\frac{f'}{1+f^2} = (\arctan f)' = \frac{n}{2},
\]

and

\[
f = f(t) = \tan \frac{n}{2} t
\]

which is a function defined on the \(\frac{2\pi}{n}\)-interval \((-\frac{\pi}{n}, +\frac{\pi}{n})\).

This settles the matter for flat manifolds \(Y\) and the general case follows by rescaling general metrics in \(Y\) with a large constants.
3 Toric Bands in Spheres and Lower Bounds on Lipschitz Constants of Map $X \to S^n$ in terms of $Sc(X)$.

Suppose, there is a toric band of width $d$ in the unit $n$-sphere $S^n$ that is a domain $V \subset S^n$ which is homeomorphic to $T^{n-1} \times [-1,1]$ and such that the distance between the two boundary components $\partial_\pm(V)$ of $V$ is equal to $d$ and let $f$ be a continuous map of non-zero degree from an oriented Riemannian $n$-manifold $X$ to $S^n$.

Recall that saying "degree" presupposes that $f$ is locally constant at infinity, i.e. constant on each boundary component of $X$ and, if $X$ is non-compact, on every component of the complement to some (large) compact subset in $X$, and let us additionally assume that the (finite) $f$-image of the so defined infinity does not intersect $V$. (This is relevant only if $\partial X$ is disconnected and/or if $X$ is disconnected at infinity.)

Then the pullback $V = f^{-1}(V) \subset X$ is a Riemannian over-torical band, such that the distance between the two parts $\partial_\pm(V)$ of its boundary is $\geq \lambda^{-1}d$, and the inequality

$$d = \text{width}(V) \leq 2\pi \sqrt{\frac{n-1}{\sigma n}}$$

(this is $[\text{dist}_\pm \leq \frac{2\pi d}{n}]$ formulated for $\sigma = n(n-1)$ in the previous section) shows that

$$O^2_{lip} \quad [Sc(X) \geq \sigma] \Rightarrow \left[ \text{Lip}(f) \geq \frac{d}{2\pi} \sqrt{\frac{\sigma n}{n-1}} \right],$$

where, recall,

$$\text{Lip}(f) = \sup_{x_1 \neq x_2} \frac{\text{dist}_{S^n}(f(x_1), f(x_2))}{\text{dist}_X(x_1, x_2)}.$$ 

Notice that the $\frac{2\pi}{n}$-inequality $[\text{dist}_\pm \leq \frac{2\pi}{n}]$, that is (essentially) $O^2_{lip}$ applied to the identity map, shows that torical bands in $S^n$ have widths $d \leq \frac{2\pi}{n}$.

Conjecturally, the maximal widths $d$ for large $n \to \infty$ must be asymptotic to $\frac{1}{n^{1+\alpha}}$ for some $\alpha > 0$.

Round Tori and in $S^n$ and in $\mathbb{R}^n$. Let us show that this $\alpha$ must be $\leq \frac{1}{2}$ by exhibiting embedded tori $T^{n-1}$ with bands of width $= \frac{1}{n^{1/2}}$ around them, where we use the following terminology.

Over-Torical Width $\text{width}_{\bot}(X)$. This is defined for Riemannian manifolds $X$ as the supremum of numbers $d$, such that $X$ admits an equidimensional locally isometric (not necessarily globally one-to-one) immersion from an overtorical Riemannian band of width $d$.

For instance, it is obvious that

$$\text{width}_{\bot}(S^2) = \pi.$$ 

More significantly, since the Clifford torus in $S^3$ has $\text{rad}^\circ = \frac{\pi}{4}$, (see section 1)

$$\text{width}_{\bot}(S^3) \geq \frac{\pi}{2}$$

and consequently,
all continuous maps $f$ from a Riemannian (possibly incomplete) 3-manifold $X$ with $\text{Sc}(X) \geq 6 = \text{Sc}(S^3)$ to $S^3$ which are constant at infinity and have $\deg(f) \neq 0$, satisfy

$$\text{Lip}(f) \geq \frac{3}{4}.$$  

This improves the inequality $\text{Lip}(f) \geq \frac{3}{8\pi}$ from [GL 1983] but falls short of the conjectural bound $\text{Lip}(f) \geq 1$.

Another natural conjecture is the equality

$$\text{width}_{\text{T}}(S^3) = \frac{\pi}{\sqrt{2}}.$$  

Moreover, one expects that all (possibly incomplete) 3-manifolds $X$ with sectional curvatures $\geq 1$ satisfy

$$\text{width}_{\text{T}}(X) \leq \frac{\pi}{\sqrt{2}}.$$  

Starting from $n = 4$, codimension one tori in $S^n$ can’t be rotationally invariant any more; we construct certain "roundish" ones with relatively large focal coradii $r = \text{rad}^\bigcirc$, i.e. with the normal exponential maps of these tori is one-to-one within distance $\leq r$ from them.

We construct these tori in the unit Euclidean $n$-balls (rather than in the unit spheres) by induction as follows.

Given codimension one tori $Y_1 \subset B^{n_1} \subset \mathbb{R}^{n_1}$, and $Y_2 \subset B^{n_2} \subset \mathbb{R}^{n_2}$ with focal coradii $r_1$ and $r_2$, take $c_1, c_2 > 0$, such that

$$c_1^2 + c_2^2 = 1 \text{ and } c_1 r_1 = c_2 r_2,$$

observe that the product of the $c_i$-scaled $Y_i$ in $\mathbb{R}^{n_i}$ is contained in the unit ball

$$Y_x = c_1 Y_1 \times c_2 Y_2 \subset B^{n_1+n_2} \subset \mathbb{R}^{n_1+n_2} = \mathbb{R}^{n_1} \times \mathbb{R}^{n_2}.$$  

and

$$\text{rad}^\bigcirc(Y_x) = r_x = c_1 r_1 = c_2 r_2.$$  

Then let

$$Y_{x,\delta} = \frac{1}{1 + \delta}(Y_x + \delta \subset B^{n_1+n_2}$$

be the $\frac{1}{1+\delta}$-scaled boundary of the $\delta$-neighbourhood of $Y_x$ in $\mathbb{R}^{n_1+n_2}$ with $\delta = \frac{1}{2} r_x$ and observe that

$$\text{rad}^\bigcirc(Y_{x,\delta}) = \frac{r_x}{2 + r_x}.$$  

In particular, if a torus $Y = Y_1 = Y_2 = Y(n) \subset B^n$ has normal focal radius $r = r(n)$, the resulting $Y(2n) = (Y \times Y)_+ \subset B^{2n}$ satisfies

$$r(2n) = \frac{r(n)}{2\sqrt{2} + r(n)}$$  

and the normal focal radius of

$$Y(2n+1) = ((c_1 Y(n)) \times (c_2 Y(n+1)))_+ \subset B^{2n+1}.$$  

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satisfies a similar relation.

Then, starting from $Y(2) = S^1 \subset \mathbb{R}^2$ with $r(2) = 1$ one obtains $Y(4), Y(4), \ldots$, such that
\[
\begin{align*}
r(4) &\geq \frac{1}{2^2 + 1} > \frac{1}{4} = \frac{2}{4^2}, \\
r(8) &> \frac{1}{8\sqrt{2} + 1} = \frac{1}{2^2 \sqrt{2} + 1} > \frac{1}{13},
\end{align*}
\]
and, in general,
\[
r(n) \geq cn^{-\frac{3}{2}},
\]
where a (very) rough estimate is $c > 1$ for $n = 2^i$ and $c > \frac{1}{3}$ for all $n$.

Eventually, since the normal bands around these tori $Y(n)$, can be transported from $B^n$ to $S^n$ by the obvious expanding map $B^n \to S^n$, we conclude that
\[
width_f(S^n) \geq 2c \cdot n^{-\frac{3}{2}}
\]
which combined with $\bigcirc_{Lip}$ implies the following.

**Spherical Lipschitz Bound Theorem.** If the scalar curvature of a (possibly incomplete) Riemannian $n$-manifold is bounded from below by $\frac{n(n-1)}{2} = Sc(S^n)$, then all continuous maps $f$ from $X$ to the sphere $S^n$ (and also to the hemisphere to $S^n$) of non-zero degrees\(^5\) satisfy
\[
\text{Lip}(f) > \frac{c}{\pi \sqrt{n}} \text{ for the above } c > \frac{1}{3}.
\]

(This $c$ is not optimal; but since this inequality is unlikely to be qualitatively sharp anyway there is no point in fiddling with constants.)

**Remarks.** (a) If $X$ is a complete spin\(^6\) manifold, then the sharp spherical Lipschitz bound $\text{Lip}(f) \geq 1$ is known to hold for these maps $f : X \to S^n$ by the work of Llarull [Ll 1998]. This is accomplished by carefully analysing the algebraic Schrödinger-Lichnerowicz-Weitzenboeck formula for the Dirac operator on $X$ twisted with the spin bundle $S^+(S^n)$ pulled back to $X$ and applying the index theorem.

In fact, this Dirac operator proof rules out smooth proper maps $f : X \to U \subset S^n$ of non-zero degrees, which strictly decrease areas of surfaces $S \subset X$ (such $f$ may have $\text{Lip}(f) > 1$) and where the complements to the (open) subsets $U \subset S^n$ are zero dimensional, or, more generally, where all connected subsets $A \subset S^n \setminus U$ are trees and/or closed curves with trivial (i.e. identity) Levi-Civita monodromy transformations around them (see section 10).

(b) It remains unknown:
- if the spin condition is essential for ruling out maps $f$ for which $\text{area}(f(S)) < \text{area}(S)$,
- if the completeness condition is essential for $\text{Lip}(f) \geq 1$,
- if one may allow closed curves in $S^n \setminus U$ with nontrivial Levi-Civita monodromies even if $X$ complete and spin. (See section 10 for further questions of this kind.)

\(^5\)Here such a map $X \to S^n$ is supposed to be constant at infinity, including $\partial X$ and to be proper from the interior of $X$ to that of $S^n$.

\(^6\)In fact, it suffices to have the universal covering of $X$ spin – we return to this later on; here we recall that an orientable smooth manifold $X$ is spin if the restrictions of the tangent bundle $T(X)$ to all surfaces $S \subset X$ are trivial bundles.
(c) The above inequality $\text{Lip}(f) \geq \frac{c}{\sqrt{n}}$ (which applies to incomplete non-spin manifolds) improves upon $\text{Lip}(f) \geq \frac{1}{6n}$ in [GL 1983].

This gains in significance as $n \to \infty$, where the proof for $n \geq 9$ depends on the controlled singularity results by Lohkamp and Schoen-Yau, which the present author has not studied in detail.

(d) The above estimates of torical width of $S^n$ and of focal radii of tori in $S^n$ raise a multitude of questions concerning $\text{width}_+(X)$, $\text{rad}^0(Y \subset X)$ and their generalisations for various $X$ and $Y$. These will be briefly discussed in section 7.

4. $\frac{4\pi}{n}$-Bound on Width and Related Inequalities for Iso-Enlargeable Bands.

Hypersphericity and Iso-Enlargeability. An oriented Riemannian manifold $X$ is called \textit{hyperspherical} if it admits continuous maps $f$ to $S^n$, $n = \dim(X)$ with arbitrarily small $\text{Lip}(f) > 0$, which are constant at infinity which have non-zero degrees.

A Riemannian manifold $X$ is called \textit{iso-enlargeable} if there exists a sequence of Riemannian manifolds $\tilde{X}_i$ of dimension $n = \dim(X)$ and of locally isometric maps $\tilde{X}_i \to X$, such that $\tilde{X}_i$ admit continuous maps constant at infinity $f_i : \tilde{X}_i \to S^n$, such that

$$\text{deg}(f_i) \neq 0 \text{ and } \text{Lip}(f_i) \to 0 \text{ for } i \to \infty.$$ 

\textbf{Examples.} (a) The archetypical hyperspherical manifolds are the Euclidean spaces $\mathbb{R}^n$.

(b) Complete simply connected manifolds $X$ with non-positive sectional curvatures $\kappa$ are also hyperspherical.

This follows from (a), since the the inverse exponential maps $\exp^{-1} : X \to \mathbb{R}^n = T_{x_0}(X)$ satisfy $\text{Lip}(\exp^{-1}) \leq 1$ for $\kappa(X) \leq 0$.

(c) If a compact manifold $X$ is fibered over an $\tilde{X}$, where $\kappa(\tilde{X}) \leq 0$ and where the fibers also admit metrics with $\kappa \leq 0$ then the universal covering of $X$ is hyperspherical by an easy argument.

(d) Compact locally symmetric spaces $Y$ that have no (local) factors isometric to real and/or complex hyperbolic spaces are enlargeable but \textit{not overtorical}, since the homology groups $H_1(Y)$ are \textit{finite} for these $Y$.

Instances of such $Y$ are compact quotients $H_n^2/\Gamma$ of quaternion hyperbolic spaces (here the sectional curvature $\kappa(Y) < 0$) and compact quotients $SO(n)/SL(n)/\Gamma$, $n \geq 3$ (here $\kappa(Y) \leq 0$).

\textbf{Remark/Question.} If the, locally isometric maps $\tilde{X}_i \to X$ in the definition of iso-enlargeability are required to be \textit{covering maps}, which is equivalent to completeness of $\tilde{X}_i$ in the case where $X$ itself is complete (e.g. compact), then $X$ is called \textit{enlargeable}, see [GL 1983], [Dr 2000], [DFW 2003], [HaSch 2006], [BH 2009], [Han 2011].

The inequality $\text{Lip}(f) \geq \frac{c}{\sqrt{n}}$ with $c = 1/3$ gains over $\text{Lip}(f) \geq \frac{1}{6n}$ only for $n \geq 6$ but a more precise evaluation of $\text{rad}^0(Y(n))$ shows this gain for all $n$. 

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It is obvious that

\[ \text{enlargeable} \Rightarrow \text{iso-enlargeable}, \]

Also one may expect that the reverse implication holds for compact manifolds, since sequences \( \tilde{X}_i \) (sub)converge in a natural way to some \( \tilde{X} \), where the maps \( \tilde{X}_i \to X \) (sub)converge to a covering map \( \tilde{X} \to X \) and where properly scaled maps \( \tilde{X}_i \to S^n \) (sub)converge to Lipschitz maps \( \tilde{f}_i : \tilde{X} \to S^n \).

But, in general, these \( \tilde{f}_i \) are neither constant at infinity nor do they have non-zero degree, at least not in the ordinary sense (even if \( \tilde{f}_i : \tilde{X}_i \to X \) were covering maps to start with). Thus enlargeability of compact iso-enlargeable manifolds remains problematic even for compact \( n \)-aspherical manifolds \( X \).

(Examples of enlargeable manifolds with non-hyperspherical universal coverings exhibited in [BH 2009] tilts one toward accepting a possibility of iso-enlargeable but non-enlargeable compact manifolds \( X \).)

On the other hand, there is the following relation between iso-enlargeability and the overtorical width \( \hat{\text{width}}(X) \) which was defined in the previous section.

If \( X \) is compact, then

\[ [\hat{\text{width}}(X) = \infty] \Leftrightarrow [X \text{ is iso-enlargeable}]. \]

In fact, the (quantitative form of the obvious) implication "\( \Leftarrow \)" has been already established the previous section.

Now, to prove "\( \Rightarrow \)" we observe that the maps \( f : V \to \mathbb{T}^{n-1} \times [-1, 1] \) used in the definition of "over-torical" can be assumed Lipschitz, where, moreover, the corresponding maps (coordinate projections) \( V \to [-1, 1] \) can be arranged to have their Lipschitz constants equal to

\[ \frac{2}{\text{width}(V)}. \]

These \( f \), by passing to the \( \mathbb{Z}^{n-1} \)-coverings \( \tilde{V} \to V \), become Lipschitz maps \( \tilde{f} : \tilde{V} \to \mathbb{R}^{n-1} \times [-1, 1] \) which, by scaling \( \varepsilon : \mathbb{R}^{n-1} \to \mathbb{R}^{n-1} \), turn to maps

\[ \tilde{f}: \tilde{V} \to \mathbb{R}^{n-1} \times [-1, 1] \]

with Lipschitz constants arbitrarily close to \( \frac{2}{\text{width}(V)} \) and which remain proper with degrees \( \neq 0 \).

Finally, we compose these \( \tilde{f} \) with the obvious map \( \mathbb{R}^{n-1} \times [-1, 1] \to S^n \) of degree one and \( Lip = \pi \) and obtain maps

\[ \tilde{F}_\varepsilon : \tilde{V} \to S^n, \]

where \( deg(\tilde{F}) \neq 0 \) and \( Lip(\tilde{F}) \leq \frac{2\pi}{\text{width}(V)} + \varepsilon' \)

with arbitrarily small \( \varepsilon' \), and the implication

\[ [\hat{\text{width}}(X) = \infty] \Rightarrow [X \text{ is iso-enlargeable}]. \]

is thus established.

\*\*A manifold is called \textit{aspherical} if its universal covering is contractible.\*\*
**$\mathcal{V}$-Width and $\mathcal{IE}$-Width.**

Given a class $\mathcal{V}$ of Riemannian bands $V$ define $\text{width}_V(X)$ of a Riemannian manifold $X$ as we did it for $\text{width}_T$, namely, as the supremum of numbers $d$, such that $X$ admits an equidimensional locally isometric (not necessarily globally one-to-one) immersion from a band $V \in \mathcal{V}$ with $\text{width}(V) = d$.

Here, we are concerned with the class of iso-enlargeable orientable bands $V$ which admits proper maps (i.e. boundary to boundary) $f : V \rightarrow Y \times [-1, 1]$, where $Y$ must be compact orientable iso-enlargeable manifolds without boundaries\(^9\) and where $\deg(f) \neq 0$.

**Iso-enlargeable $\frac{2\pi}{n}$-Inequality.** The iso-enlargeable widths of $n$-dimensional Riemannian manifolds $X$ are bounded by the over-torical widths as follows.

$$\text{width}_T(X) \leq \text{width}_{\mathcal{IE}}(X) \leq 2\text{width}_T(X).$$

Consequently, if $Sc(X) \geq \sigma > 0$, then

$$\text{width}_{\mathcal{IE}}(X) \leq 4\pi \sqrt{\frac{n-1}{\sigma n}}.$$

**Proof.** The inequality $\text{width}_T \leq \text{width}_{\mathcal{IE}}$ is obvious.

To prove $\text{width}_{\mathcal{IE}} \leq 2\text{width}_T$ let us show that iso-enlargeable bands $V$ with width $d$ contain over-torical ones with width $d/2$.

In fact, since the above $Y$ is iso-enlargeable, there exist locally isometric immersions of $(n-1)$-dimensional over-torical bands $Y_D$ to $Y$ with $\text{width}(Y_D) \geq D$ for all $D > 0$. Then the pullbacks\(^{10}\) of $Y_D \times [-1, 1]$ under the maps $f : V \rightarrow Y \times [-1, 1]$ come with natural maps

$$f^{-1}(Y_D \times [-1, 1]) \rightarrow [0, D] \text{ and } f^{-1}(Y_D \times [-1, 1]) \rightarrow [0, d],$$

both with $\text{Lip} \leq 1$.

Then the pull back of the circle of radius $d/2$ in $[0, D] \times [0, d]$ under the pair of these maps (which may be assumed smooth and transversal to this circle) serves as the required over-torical band of width $\geq d/2$.

Finally, we recall the $\frac{2\pi}{n}$-inequality for over-torical bands in section 2 and obtain our $\frac{4\pi}{n}$-inequality for iso-enlargeable bands.

**Improvement.** The $\frac{2\pi}{n}$-inequality for compact iso-enlargeable bands $V$ can be upgraded to $\text{width}_{\mathcal{IE}}(V) \leq 2\pi \sqrt{\frac{n-1}{\sigma n}}$ as it is explained at the end of section 11.\(^6,11\) Accordingly, the curvature decay estimate below can be improved by the factor of 2.

**Iso-enlargeable $[\frac{8\pi^2}{n}]$-Decay Theorem.** Let a manifold $X$ admit a proper map of non-zero degree to the total space $X$ of a two dimensional vector bundle

---

\(^9\)A more general definition of iso-enlargeability for bands with no reference to closed manifolds is given in section 11.7.

\(^{10}\)Even if $g : A \rightarrow B$ is a non-injective map, we speak of the $f$-pullback of $A$ for a map $f : C \rightarrow B$, where $f^{-1}(A)$ is understood as the set of pairs $\{(a,c) \mid g(a) \in f^{-1}(c) \}$.

\(^{11}\)The proof in the original version of this paper was incorrect, as it was pointed out to me by the referee.
If the bundle $X \to Y$ is trivial then the scalar curvatures of all complete Riemannian metrics $g$ in $X$ restricted to concentric balls $B(R) = B_{x_0}(R) \subset X$ satisfy

$$\left[ \frac{8\pi^2}{R^2} \right]_{B(R)} \min_{B(R)} Sc(X) \leq \frac{8\pi^2}{(R - R_0)^3}$$

for some $R_0 = R_0(X, g, x_0)$ and all $R \geq R_0$.

Proof. This follows word for word the argument for the quadratic decay theorem in section 1 and its generalisation in section 2 with "iso-enlargeable " for "over-torical".

What happens to nontrivial bundles $X \to Y$? The above argument applies to non-trivial bundles, where the (total spaces of the) corresponding circle bundles are iso-enlargeable, which is so, for instance by the above (c) for $Y$ which admit metrics with non-positive sectional curvatures.

In general, the examples in [BH 2009] indicate a possibility of non-enlargeable circle bundles over enlargeable $Y$; yet, it seems hard(er) to find such examples, where the corresponding $X$ would admit complete metrics with $Sc \geq \sigma > 0$.

Remarks and Questions. (a) Let $V$ be an $n$-dimensional manifold with sectional curvatures $\kappa(V) \geq 1$ which admits a proper map $\Phi : V \to [0, d]^n$ given by $n$ functions $\phi_i(v)$ with $\text{Lip}(\phi_i) \leq 1$ and such that $\text{deg}(\Phi) \neq 0$.

Is the maximal $d$ for these $V$ achieved by the regular cube $\Box$ in the hemisphere $S^n_+$ with the boundary $\partial \Box \subset S^{n-1} = \partial S^n_+$?

(b) The same question for spherical simplices $\Delta \subset S^n_+$ with $\partial \Delta \subset S^{n-1}$:

do these simplices have maximal distances between opposite faces among all simplices with $\kappa \geq 1$?

From $\mathcal{V}$-manifolds to to $\mathcal{V}$-Enlargeable ones.

$[\mathcal{V} \to \mathcal{V}E]$: Given a "natural" class $\mathcal{V}$ of manifolds one defines an, a priori larger, class $\mathcal{V}E$ of $\mathcal{V}$-enlargeable manifolds $X$ by the condition

$$\text{width}_\mathcal{V} = \infty.$$  

Thus, for instance the class $\mathcal{T}$ of over-torical manifolds leads to the class $\mathcal{T}E \supsetneq \mathcal{T}$ of $\mathcal{T}$-enlargeable manifolds, which, as we know, is equal to the class $\mathcal{IE}$ of iso-enlargeable manifolds.

On the other hand, if we depart from the class $\mathcal{IE} = \mathcal{TE}$, then the new class $\mathcal{IEE}$ defined by $\text{width}_{\mathcal{IE}} = \infty$ will coincide with $\mathcal{IE}$.

In the following section, following Schoen-Yau and Schick, we define class $\mathcal{SYS} \supsetneq \mathcal{T}$, where the corresponding class $\mathcal{SYS}E$ of $\mathcal{SYS}$-enlargeable manifolds is strictly greater than the class of iso-enlargeable ones.

5 Schoen-Yau-Schick Manifolds and $\mathcal{SYS}$-Bands.

Schoen-Yau Definition. [SY-Str 1979], [SY 2017]. A compact orientable $n$-manifold $X$ is $\mathcal{SYS}$, if there exist $n - 2$ integer homology classes $h_1, h_2, ..., h_{n-2} \in H_1(X)$, such that their intersection consecutive

$$h_1 \sim h_2 \sim ... \sim h_{n-2} \in H_2(X)$$
is non-spherical, i.e. it is not contained in the image of the Hurewicz homomorphism $\pi_2(X) \to H_2(X)$, or, equivalently, it doesn’t lift to the universal covering of $X$.

Schick Definition. [Sch 1998] A homology class $h \in H_n(K)$, where $K = K(\Pi,1)$ is the Eilenberg-MacLane space for an Abelian group $\Pi$, is called SYS, if its consecutive cap-products with some cohomology classes $h_1, h_2, \ldots, h_{n-2} \in H^1(K, \mathbb{Z})$ are non-zero,

$$\cdots((h \cap h_1) \cap h_2) \cap \ldots \cap h_{n-2} = h \cap (h_1 \smile \ldots \smile h_{n-2}) \neq 0 \in H_2(K).$$

(Geometrically speaking, generic 2-dimensional intersections of the $n$-cycles $C \subset K$ representing $h$ with $(n-2)$-codimensional pullbacks of generic points of, some, say piecewise linear, maps $K \to \mathbb{R}^{n-2}$ are non-homologous to zero.)

Then a manifold $X$ is SYS if the Abel classifying map $X \to K(\Pi,1)$ for $\Pi = H_1(X)$ sends the fundamental class $[X] \in H_n(X)$ to a SYS class in this $K(\Pi,1)$.

(Recall that, by definition, the spaces $K(\Pi,1)$ have contractible universal coverings and fundamental groups isomorphic to $\Pi$. The standard finite dimensional approximations to these $K$ are products of tori and lens spaces $L_i = S^{n_i}/\mathbb{Z}_{d_i}$, where the latter, observe, carry natural metrics with $Sc > 0$.

Abel’s $X \to K$ maps, which are unique up-to homotopy, are characterised by inducing isomorphisms on the 1-dimensional homology groups.)

Historical Remark. In 1979 Schoen and Yau proved that SYS manifolds (defined slightly differently in [SY - Str 1979] with incorporation of some spin manifolds) of dimensions $n \leq 7$ carry no metrics with $Sc > 0$. Then, in the recent paper [SY 2017], they published the proof for all $n$.

Meanwhile, Schick [Sch 1998] has shown that no available Dirac operator methods can rule out $Sc > 0$ on these manifolds.

Examples.

- $\bullet_1$ Overtorical manifolds are SYS.
- $\bullet_2$ Let $X$ be obtained by a surgery applied on a closed curve $C$ in the $n$-torus as in [Sch1998].
  If $n \geq 4$, then $X$ is SYS if and only if $C$ represents a divisible homology class in $H_1(T^n)$.
  (Such an $X$ is over-torical if and only if $C$ is homologous to zero.)
- $\bullet_3$ If a compact orientable manifold $X$ admits a map $f$ of degree one to a SYS manifold that $X$ is SYS.
  But if $\deg(f) > 1$ then $X$ is not necessarily SYS, unlike the case of the overtorical and iso-enlargeable manifolds. For instance if the curve $C$ in $\bullet_2$ is $m$-divisible, than the some $m$-sheeted covering of $X$ is non-SYS.
  Probably, these non-SYS coverings carry metrics with $Sc > 0$.
- $\bullet_4$ Products of SYS manifolds by overtorical ones are SYS.
  But products SYS $\times$ SYS and SYS $\times$ [iso-enlargeable] are, in general, not SYS.

SYS-Bands. A band $V$ is called SYS if it admits a band map $(\partial_+ \to \partial_-)$ of degree $\pm 1$ to $Y \times [-1, 1]$ where $Y$ is a compact SYS manifold.\textsuperscript{12}

\textsuperscript{12} A more general definition of SYS for bands with no reference to closed manifolds is given in section 11.7.
Accordingly, define the \( \text{SYS-width} \) of \( \text{width}_{\text{SYS}}(X) \) of Riemannian manifolds \( X \) based on the class \( \text{SYS} \) as we did it for \( \mathcal{I} \) in the previous section.

**4π-inequality for SYS-Bands.** All Riemannian manifolds \( X \) with \( \text{Sc}(X) \geq \sigma > 0 \) satisfy

\[
\text{width}_{\text{SYS}}(X) \leq 4\pi \sqrt{\frac{n-1}{\sigma n}}.
\]

Consequently, compact manifolds without boundaries, which have

\[
\text{width}_{\text{SYS}}(X) = \infty
\]

admit no metrics with positive scalar curvatures.

Proof. By symmetrising a SYS-band \( V \rightarrow Y \times [-1, 1] \) as in the proof of the ovetorical \( \frac{2\pi}{n} \)-Inequality in section 2 (now \( Y \) plays the role of the torus \( T^{n-1} \) in section 2) we arrive at \( V_{\sigma-3} \) with \( T^{n-3} \)-invariant metric with \( \text{Sc} \geq \sigma \), such that

the quotient space \( Y^3 = V_{\sigma-3}/T^{n-3} \) is an orientable 3-manifold with the boundary decomposed into two (possibly disconnected) disjoint parts say

\[
\partial Y^3 = S_+ \cup S_-, \quad \text{where} \quad \text{dist}_{Y^3}(S_+, S_-) \geq d
\]

for \( d \) equal to the distance between the two boundary components in \( V \), and where the Schoen-Yau-Schick property of \( Y \) implies that

if a closed surface \( S \subset Y^3 \) separates \( S_- \) from \( S_+ \), then the homomorphism

\[
\pi_1(S) \rightarrow \pi_1(Y^3)
\]

has infinite image.

Therefore the \( d/2 \)-equidistance surface to \( S_+ \) (or to \( S_- \)) contains a circle \( C \) which has infinite order in \( \pi_1(Y^3) \) and, by the Poincaré duality, the covering \( \tilde{V}^3 \) of \( Y^3 \) with the cyclic \( \pi_1(Y^3) \) generated by the (homotopy class of) \( C \) contains a relative 2-cycle \( \tilde{C}^1 \) with non-zero intersection index with the lift \( \tilde{C} \) of \( C \) to \( \tilde{V}^3 \).

Take the pull back of the cycle \( \tilde{C}^1 \) to the corresponding covering \( \tilde{V}_{\sigma-3} \) of

\[
V_{\sigma-3} = (V_{\sigma-3}/T^{n-3}) \times T^{n-3},
\]

write this pullback cycle as

\[
\tilde{C}^1 \times T^{n-3} \subset \tilde{V}_{\sigma-3},
\]

and symmetrize the minimal cycle in the \( (n-1) \)-homology class of \( \tilde{C}^1 \times T^{n-3} \).

Since \( \text{dist}(\tilde{C}, \partial \tilde{V}^3) = \text{dist}(C, \partial Y^3) \geq d/2 \), the quotient surface of the resulting \( \tilde{V}_{\sigma-2} \) contains a point within distance \( \geq d/2 \) from its boundary, which implies (compare p. 310 in [GL 1983]) that

\[
d/2 \leq 2\pi \sqrt{(n-1)/\sigma n}.
\]

QED.

**Question.** Can one replace the above \( 4\pi \sqrt{\frac{n-1}{\sigma n}} \) by \( 2\pi \sqrt{\frac{n-1}{\sigma n}} \)?

\(^{13}\)Relative means relative to \( \partial \tilde{V}^3 + \partial_\infty \tilde{V}^3 \) where \( \partial_\infty \) stands for the complement of a large ball in \( \tilde{V}^3 \).
6  **SYSE-Enlargeable Manifolds and Codimension Two Depth Inequalities.**

A Riemannian manifold $X$ is called **SYSE-Enlargeable** if it has infinite SYSE-width.

For instance, SYS manifolds and iso-enlargeable manifolds are **SYSE-Enlargeable**.

What is more interesting is that if an $n$-manifold $X$ admits a proper Lipschitz map $\phi$ (Lipschitz means $\text{Lip}(\phi) < \infty$) to an iso-enlargeable manifold of dimension $n-2$, say $\phi : X \to \overline{X}$, such that the homological pullback $\phi^*([x]) \in H_2(X)$, $[x] = 1 \in H_0(X) = \mathbb{Z}$, is nonspherical (as in the first definition of SYS in the previous section), then $X$ is **SYSE-enlargeable**.

Therefore, by the above $\frac{4\pi}{n}$-inequality,

If such an $X$ is compact, then it admits no metric with $\text{Sc} > 0$.

Thus, for example,

products $X$ of SYS manifolds by compact iso-enlargeable ones (e.g. those which admit metrics with $\kappa(X_2) \leq 0$) admit no metrics with positive scalar curvatures.

(These $X$, in general, are neither iso-enlargeable nor SYS.)

**$\frac{4\pi}{n}$-Inequality for SYSE-Bands.** Denote by $\text{SYSE}$ the class of SYSE-enlargeable manifolds, say that a compact band $V$ is SYSE if it admits a map of degree $\pm 1$ to $Y \times [-1,1]$, where $Y$ is SYSE and accordingly define $\text{width}_{\text{SYSE}}(X)$ for Riemannian manifold $X$ (see $[\mathcal{V} \sim \mathcal{V}]$ in section 4).

Then by arguing as in the proof of the iso-enlargeable $\frac{4\pi}{n}$-inequality in section 4 we conclude that

$$\text{width}_{\text{SYSE}}(X) \leq \text{width}_{\text{SYSE}}(X) \leq 2\text{width}_{\text{SYS}}(X)$$

for all Riemannian manifolds $X$.

Consequently,

if $\text{Sc}(X) \geq \sigma > 0$ then

$$\text{width}_{\text{SYSE}}(X) \leq 8\pi \sqrt{\frac{n-1}{\sigma n}}.$$  

**Question.** Can one improve $8\pi$ to $2\pi$ or, at least, to $4\pi$?

**Depth Inequalities.** Define the depth of a homology class $h$ in a Riemannian manifold $X$ with boundary as the supremum of $d \geq 0$ such that $h$ can be represented by a cycle positioned within distance $d$ from the boundary of $X$.

(If $X$ is incomplete, we include the points obtained by completion of $X$ in the boundary of $X$.)

Let $Y$ be a closed $(n-2)$-dimensional manifold and $p : X \to Y$ be a disc bundle, e.g. the trivial one $X = Y \times B^2$.

Let $X$ be a compact $n$-manifold with boundary and $f : X \to \overline{X}$ be a proper continuous map where proper, means boundary $\to$ boundary. Let $h = f^*([Y]) \in H_{n-2}(X)$ be the homology pull-back of the homology class of the zero section $Y = Y_0 \subset \overline{X}$. 

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Let $\mathcal{X}_\varepsilon \subset \mathcal{X}$ be the complement of the open $\varepsilon$-neighbourhood of $Y_0$ in $\mathcal{X}$ and observe that the boundary of $\mathcal{X}_\varepsilon$ consists of two components, call them $\partial_\varepsilon$, which are canonically homeomorphic to the total space of the circle bundle associated to $\mathcal{X} \to Y$, denoted $p : Y_0 \to Y$.

Let $\partial_\varepsilon = \partial_\varepsilon(X) \subset \partial\mathcal{X}$ be the two parts of the boundary of $\mathcal{X}$ which are sent by the map $f : \mathcal{X} \to \mathcal{X}$ to $\partial_\varepsilon$ and to $\partial_\varepsilon$ correspondingly.

Observe that $\mathcal{X} = Y_0 \times [\varepsilon, 1]$;
- If $Y$ is iso-enlargeable then $Y_0$ is also iso-enlargeable.
- if the fibration $p : \mathcal{X} = Y$ is trivial, $\mathcal{X} = Y \times B^2$, and
  - if $Y$ is over-toric then also $Y_0$ is over-toric,
  - if $Y$ is SYS then $Y_0$ is also SYS,
  - if $Y$ is SYSE then $Y_0$ is also SYSE.

Now let the fibration $p : \mathcal{X} \to Y$ be trivial and let $Se(\mathcal{X}) \geq n(n - 1) = Se(S^n)$.

Observe that the band-width $\frac{k\pi}{n}$-inequalities, (for $k = 2, 4, 8$ see sections 2.4,5) imply the following bounds on the depths of $h \in H_{n-2}(X)$ by the argument that we have already used several times, e.g. in the proofs of the quadratic decay inequality in section 1.

$[\hat{T}]$. If $Y$ is over-toral, i.e. if it admits a map to the torus $\mathbb{T}^{n-2}$ with degree $\neq 0$, then
$$\text{depth}(h) \leq \frac{2\pi}{n}.$$  

This is the only case where our inequality is (known to be) sharp.

$[\mathcal{I}[\mathcal{E}]]$. If $Y$ is iso-enlargeable, e.g. if it admits a metric with non-positive sectional curvature, then
$$\text{depth}(h) \leq \frac{4\pi}{n}.$$  

(Here the fibration $p$ need not be trivial.)

$[\mathcal{S}[\mathcal{Y}[\mathcal{S}]]]$. If $Y$ is SYS and if the map $f : \mathcal{X} \to \mathcal{X}$ has $\deg(f) = \pm 1$, then
$$\text{depth}(h) \leq \frac{4\pi}{n}.$$  

(The simplest example of a non-overtoric SYS manifold $Y$ for $n - 2 \geq 4$ is obtained from the $(n - 2)$-torus by attaching a 2-handle based on a $k$-multiple of closed curve in this torus where $k \neq \pm 1$. In this case one only need $\deg(f)$ to be non-divisible by $k$.)

$[\mathcal{S}[\mathcal{Y}[\mathcal{S}[\mathcal{E}]]]]$. If $Y$ is SYSE and if the map $f : \mathcal{X} \to \mathcal{X}$ has $\deg(f) = \pm 1$, then
$$\text{depth}(h) \leq \frac{8\pi}{n}.$$  

\footnote{This can improved to $\text{depth}(h) \leq \frac{2\pi}{n}$ with the corresponding width inequality in section 11.7, which, probably can be also used to improve the width inequality in the SYS case as well.}

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(Recall, this was stated earlier, here as everywhere in this paper the above inequalities are established unconditionally for $n \leq 8$, while the case $n \geq 9$ relies on the recent partial regularity results by Lohkamp and by Schoen and Yau which the present author has not studied in detail.)

On nontrivial bundles $p : X \to Y$. Here, similarly to where we addressed this issue in section 4, one may drop the triviality of $p$ assumption, if, for instance, $Y$ admits a metric with $\kappa \leq 0$.

No reasonable assumption of this kind, however, seems in view for SYS and SYSE manifolds.

In fact, circle bundles over many SYS manifolds, say on those obtained by surgery on closed curves in $T^n$ (see $\bullet_2$ in section 5) are very likely to carry metrics with $\Sc > 0$ and so the above inequality can’t hold with any constant for non-trivial fibrations $p : X \to Y$.

On Complete Manifolds and Dirac Operators. The inequality $\text{depth}(h) < \infty$ implies that the interiors of the manifolds $X$ in $[\mathcal{IE}]_\circ$ and $[\mathcal{SYSE}]_\circ$ admit no complete metrics $g$ with $\Sc(g) \geq \sigma > 0$.

(The inequality $\text{depth}(h) < \infty$ in the remaining cases follow from these two.)

Strangely enough, even if $X$ is spin, this was proven by the Dirac operator methods for enlargeable and related manifolds $Y$ [GL1983], [HPS2015] only under additional geometric assumptions on $X$ in spirit of "bounded geometry".

(To be honest, I am not 100% certain this is the case for [HPS2015]. The main result is stated in this paper for closed manifolds and I have not followed the proofs in sufficient details to understand what is actually proven there for complete non-compact manifolds.)

Question. Do all products manifolds $Y \times \mathbb{R}^2$, and, more generally, the total spaces of all $\mathbb{R}^2$-bundles admit complete metrics $g$ with $\Sc(g) \geq 0$?

Do, for example, such metrics $g$ exist for compact manifolds $Y$ which admit metrics with strictly negative sectional curvatures?

If there are no such $g$ among rotationally symmetric warped product metrics, then, probably, no complete metric $g$ on $Y \times \mathbb{R}^2$ has $\Sc(g) \geq 0$, where the best candidates of this kind of manifolds with no complete metrics on them with $\Sc \geq 0$ are non-trivial $\mathbb{R}^2$-bundles over surfaces of genera $\geq 2$.

7 External Curvature, Focal Radius and Depth in Codimension $> 2$

Observe that by Gauss theoremae egregium the scalar curvature of hypersurfaces $Y \subset S^n$, $n \geq 2$, with principal curvatures $c_i = c_i(y)$, $y \in Y$, $i = 1, \ldots, n-1$, satisfies

$$Sc(Y) = Sc(S^{n-1}) + \left(\sum_i c_i\right)^2 - \sum_i c_i^2 \geq (n-1)(n-2) - \sum_i c_i^2.$$  

---

15Bernhard Hanke told me that the results from [HPS2015] apply to complete manifolds by the $C^*$-arguments in Roe’s partitioned index theorem and in [HS 2007].

16Figuring this out does not seem hard, but I have not tried doing this.
It follows that if an \((n - 1)\)-dimensional manifold \(Y\) admits no metric with \(Sc > 0\), that the suprema of the principal curvatures of all smooth immersions from \(Y\) to the unit sphere \(S^n\) satisfy

\[
\sup_{i,y} |c_i(y)| \geq \sqrt{n - 2}
\]

This is significantly weaker than the \(\frac{\pi}{n}\)-inequality for the normal radius of \(T^{n-1} \subset S^n\), which implies that \(\sup_{i,y} c_i(y) \geq (1 + \varepsilon_n) \frac{n}{2}\). But it applies to such manifolds, for instance, as certain exotic spheres \(Y\) of dimensions \(8m + 1\) and \(8m + 2\) which carry no metrics with \(Sc > 0\) by a theorem of Hitchin [H1974], yet are immersible (but not embeddable!)\(^{17}\) to \(S^n\) by Smale-Hirsch theorem.

Besides, this sup \(c_i\) inequality obviously generalises to \(Y\) in \(S^n\) of all codimensions \(k\) where it reads

\[
\sup_{i,j,y} |c_{ij}(y)| \geq \frac{\sqrt{n - k - 1}}{k}, \quad i = 1, \ldots, n - 1, \quad j = 1, \ldots, k, \quad y \in Y,
\]

for all \(Y\) which admit no metric with \(Sc > 0\).

Then, obviously, the same holds true for Riemannian manifolds \(X \supset Y\) with sectional curvatures \(\kappa \geq 1\).

More interestingly, a similar inequality holds for immersions to unit Euclidean balls \(B(1) \subset \mathbb{R}^n\). Namely,

if an \((n - k)\)-dimensional \(Y\) admits no metric with \(Sc > 0\), then the principal curvatures of all smooth immersions \(Y \rightarrow B(1) \subset \mathbb{R}^n\) are bounded from below by

\[
\sup_{i,j,y} |c_{ij}(y)| \geq \frac{1}{\text{const}} \frac{\sqrt{n - k - 1}}{k} \]

for some universal positive constant \(\text{const} \leq 100\).

Proof. The Euclidean case reduces to the spherical one, since the standard projective map \(\mathbb{R}^n \supset B(1) \rightarrow S^n\) distorts curvatures of the curves in \(B(1)\) by a bounded amount. (Compare Lemma (C′) in 3.2.3 in [Gr 1986]).

Remark. This sup \(c_{i,j}\)-inequality also holds in the balls in the hyperbolic spaces with sectional curvature \(\kappa = -1\).

Also, the following weaker form of this inequality holds for the unit balls in all \(n\)-dimensional Riemannian manifolds \(X\) with \(-1 \leq \kappa(X) \leq 1\).

\[
\sup_{i,j,y} |c_{ij}(y)| \geq \frac{1}{\text{const}} \frac{\sqrt{n - k - 1}}{k} - \text{const}'
\]

In fact – this is obvious by today’s standards – the exponential maps \(\exp : T_x(X) \subset B(1) \rightarrow X\) in these \(X\) can be approximated by maps with controlled distortion of curvatures of the curves in \(B(1)\).

Discussion. There is a huge gap between the above lower bounds on the curvatures of submanifolds in \(S^n\) (and/or in \(B(1) \subset \mathbb{R}^n\)) and the observed curvatures in the available examples \(Y \subset S^n\).

\(^{17}\) According to textbooks’ terminology, a smooth map \(A \rightarrow B\) is an immersion if it is locally one-to-one and the inverse map is smooth, while embeddings are immersions which are globally one-to-one and, if \(Y\) is non-compact, are additionally required to be homeomorphisms from \(Y\) to their (possibly, non-closed in \(B\)) images.
Probably, certain homogeneous submanifolds $Y \subset S^n$, such as
- real and complex projective spaces Veronese represented by symmetric/Hermitian forms of rank one,
- Grassmannians Plücker embedded to exterior powers of linear spaces,
- the same Grassmannians represented by projectors in spaces of operators,

give a fair idea of embeddings with economical $c_{ij}$.

For instance, the curvature of the obvious embedding of the product of spheres

$$Y = S^{n_1} \times S^{n_2} \times \ldots \times S^{n_k} \subset S^{n_1+n_2+\ldots+n_j+j-1} = \partial B(1) \subset \mathbb{R}^{n_1+n_2+\ldots+n_j+j}$$

has $\max c_{ij} = \sqrt{k}$ and it is plausible (?) that

no embedding/immersion of this $Y$ to $S^n$ may have a (significantly) smaller curvatures $c_{ij}$.

Notice that above local bound $\max c_{ij} \geq \sqrt{n/k}$ is non-vacuous only if all spheres are one dimensional, while the only known improvement of this bound is the inequality $\max c_{ij} \geq n$ which was established in the previous section only for codimensions 1 and 2 and only for SYSE-manifolds $Y$ (e.g. for $Y$ which admits metrics with $\kappa \leq 0$.)

This, for instance, leaves the following questions open.

(a) Does the torus

$$S^1 \times S^1 \times \ldots \times S^1_{n-3}$$

embed to $S^n$ with the principal curvature $c_{ij} \leq 100/n$?

(b) Does the product

$$S^1 \times S^1 \times \ldots \times S^1_{n-3} \times S^2$$

embed to $S^n$ with the principal curvature $c_i \leq 10$?

In fact, we are more interested in depth of homology and cohomology classes in Riemannian manifolds $V$ rather than in their curvatures, where,

by definition, $\text{depth}(h) \geq d$ for an $h \in H^*(V)$ if the restriction of $h$ to the subset $V_{-d} \subset V$ of the points within distance $\geq d$ from the boundary of $V$ (including the infinity for non-compact $V$, as in the previous section) does not vanish.

Problem. Bound "complexity" of an $h$ in terms of $d = \text{depth}(h)$.

For instance, let the sectional curvature of $V$ be bounded from below by $\kappa(V) \geq 1$ and let $h$ be induced by a continuous map from the fundamental cohomology class of a product of spheres,

$$h = f^*[Y] \text{ for } f : V \to Y = S^{n_1} \times S^{n_2} \times \ldots \times S^{n_k}.$$ 

Does the depth of $h$ necessarily tend to zero for $k \to \infty$?

8 Symmetrization of Riemannian Manifolds with Point-wise Control of the Scalar Curvature.

Step 1 in Symmetrization by Reflections. Let $X$ be a compact Riemannian manifold, with a (possibly empty) boundary, and let $(Y_0, \partial Y_0) \subset (X, \partial X)$ be
a cooriented hypersurface which is strictly locally volume minimising, i.e. all sufficiently close to \( Y \) hypersurfaces \((Y, \partial Y) \subset (X, \partial X)\) different from \( Y_0 \) satisfy
\[
\text{vol}_{n-1}(Y) > \text{vol}_{n-1}(Y_0).
\]

Let \( U \subset X \) be a (small) neighbourhood of \( Y_0 \) in \( X \) which is divided by \( Y_0 \) into two "halves", denoted \( U_- \subset U \), and let \( Y_{\pm \varepsilon} \subset U_\pm \) be hypersurfaces homologous to \( Y_0 \) in \( U_\pm \) which minimise the functionals
\[
Y \mapsto \text{vol}_{n-1}(Y) - \varepsilon \cdot \text{vol}_n(U_{\pm \varepsilon})
\]
where
\[
U_{\pm \varepsilon} = U(Y_{\pm \varepsilon}) \subset U_\pm
\]
denote the regions bounded by \( Y_{\pm \varepsilon} \) and \( Y_0 \).

By the basic regularity theorems of Simons-Federer-Almgren-Allard these \( Y_{\pm \varepsilon} \) do exist for small \( \varepsilon \geq 0 \) and they are smooth away from closed subsets of Hausdorff codimension \( \geq 7 \).

Moreover, if \( n = \dim(X) = 8 \), then, according to [NS 1993],\(^{18}\) these \( Y_\varepsilon(\varepsilon) \) everywhere smooth for an open dense set of \( \varepsilon > 0 \) [NS 1993].\(^{19}\)

The mean curvatures of all these \( Y_{\pm \varepsilon} \) at the regular points satisfies
\[
\text{mean.curv}(Y_{\pm \varepsilon}) = \varepsilon
\]
and the dihedral angles between the tangent spaces to \( Y_{\pm \varepsilon} \) and those to \( \partial X \) at all regular points of \( Y_{\pm \varepsilon} \) on the boundary \( \partial Y_{\pm \varepsilon} \) are \( \leq \frac{\pi}{2} \). (If the boundary \( \partial X \subset X \) is totally geodesic then \( Y_{\pm \varepsilon} \) is normal to \( \partial X \).)

**On non-strictly minimal \( Y_0 \).** If \( Y_0 \) is non-strictly volume minimising, then there are hypersurfaces in \( X \) with the same volume as \( Y_0 \), which lie \( \varepsilon \)-close to \( Y_0 \) for all small \( \varepsilon \). These do not intersect \( Y_0 \) and each of them lies on one side of \( Y_0 \), where it plays the role of \( Y_{-\varepsilon} \) or of \( Y_{+\varepsilon} \).

Alternatively, one may slightly perturb the metric in \( X \), such that \( Y_0 = Y_{0,\varepsilon} \) becomes strictly minimising. Then this \( \varepsilon \), which goes through the following stages of symmetrisation, is sent to 0 at the end of the symmetrisation process.

Let
\[
U_{[\varepsilon,\varepsilon]} = U_{-\varepsilon} \cup U_{+\varepsilon}
\]
and let \( \tilde{U}_{[\varepsilon,\varepsilon]} \) be obtained by reflecting \( U_{[\varepsilon,\varepsilon]} \) in the two parts \( Y_{\varepsilon} \) of the (relative) boundary of \( U_{[\varepsilon,\varepsilon]} \) in \( X \) (i.e. with the exclusion of \( U_{[\varepsilon,\varepsilon]} \cap \partial X \)), denoted
\[
\partial_\# U_{[\varepsilon,\varepsilon]} = Y_{-\varepsilon} \cup Y_{+\varepsilon}.
\]

In other words, \( \tilde{U}_{[\varepsilon,\varepsilon]} \) is a space, which is acted upon by the semidirect product group \( \Gamma = \mathbb{Z} \rtimes \mathbb{Z}_2 \), such that
- \( \tilde{U}_{[-\varepsilon,\varepsilon]} / \Gamma = U_{[-\varepsilon,\varepsilon]} \),
- there is an embedding \( E : U_{[-\varepsilon,\varepsilon]} \to \tilde{U}_{[-\varepsilon,\varepsilon]} \), which is inverse to the quotient map \( Q : \tilde{U}_{[-\varepsilon,\varepsilon]} \to U_{[-\varepsilon,\varepsilon]} \),
\[
Q \circ E = \text{Id} : U_{[-\varepsilon,\varepsilon]} \to U_{[-\varepsilon,\varepsilon]}.
\]

\(^{18}\)What we need is not formulated in [NS 1993] but the argument from [NS 1993] does apply.
\(^{19}\)I am not certain this is formulated in [NS 1993].
• the group $\Gamma$ is generated by two involutions (reflections) of $\tilde{U}_{[-\varepsilon,\varepsilon]}$, one of them fixing $E(Y_{\varepsilon}) \subset E(\partial_u U_{[-\varepsilon,\varepsilon]})$ and the other one $E(Y_{\varepsilon}) \subset E(\partial_u U_{[-\varepsilon,\varepsilon]})$.

Thus, the action of our $\Gamma = \Gamma_x$ on $\tilde{U}_{[-\varepsilon,\varepsilon]}$ mimics the action of the same group on the line $(\infty, \infty)$, which is generated by the transformations

$$t \mapsto \pm \varepsilon - t$$

and where $\tilde{U}_{[-\varepsilon,\varepsilon]}$ admits a $\Gamma$-equivariant map to $(\infty, \infty)$, such that the pullback of $[-\varepsilon, \varepsilon] \subset (-\infty, \infty)$ is equal to $E(U_{[-\varepsilon,\varepsilon]}) \subset \tilde{U}_{[-\varepsilon,\varepsilon]}$.

In particular, the action of the group $\mathbb{Z} = 2\varepsilon \mathbb{Z} \subset \Gamma$ on $\tilde{U}_{[-\varepsilon,\varepsilon]}$ is free and the quotient space is equal to the double of $U_{[-\varepsilon,\varepsilon]}$,

$$\tilde{U}_{[-\varepsilon,\varepsilon]}/[2\varepsilon \mathbb{Z}] = U_{[-\varepsilon,\varepsilon]} \bigcup_{\partial_u U_{[-\varepsilon,\varepsilon]}} U_{[-\varepsilon,\varepsilon]},$$

where the boundary of this double is the double of the region $U_{[-\varepsilon,\varepsilon]} \cap \partial X$ across the boundary of this region in $\partial X$,

$$\partial \left( U_{[-\varepsilon,\varepsilon]} \bigcup_{\partial_u U_{[-\varepsilon,\varepsilon]}} U_{[-\varepsilon,\varepsilon]} \right) = \left( U_{[-\varepsilon,\varepsilon]} \cap \partial X \right) \bigcup_{\partial'} \left( U_{[-\varepsilon,\varepsilon]} \cap \partial X \right)$$

for

$$\partial' = \partial (U_{[-\varepsilon,\varepsilon]} \cap \partial X) = \partial_u U_{[-\varepsilon,\varepsilon]} \cap \partial X.$$

The Riemannian metric on $U_{[-\varepsilon,\varepsilon]} \subset X$, that is the restriction of the metric of $X$ to $U_{[-\varepsilon,\varepsilon]} \subset X$, naturally induces a $\Gamma$-invariant path metric in $\tilde{U}_{[-\varepsilon,\varepsilon]}$, call it $\tilde{g}_\varepsilon$; if the hypersurfaces $Y_{\varepsilon} \subset X$ are non-singular, e.g. if $n = \dim(X) \leq 7$, then this metric is $C^0$-Riemannian.

And if, moreover, the minimal hypersurface $X_0 \subset X$ is non-singular, e.g. for $n \leq 7$, then the spaces $(\tilde{U}_{[-\varepsilon,\varepsilon]}, \tilde{g}_\varepsilon)$ Hausdorff converge to a smooth Riemannian manifold, which we denote

$$\lim_{\varepsilon \to 0} (\tilde{U}_0, \tilde{g}_0) = \lim_{\varepsilon \to 0} (\tilde{U}_{[-\varepsilon,\varepsilon]}, \tilde{g}_\varepsilon),$$

which is isometrically acted upon by the group $\mathbb{R} \times \mathbb{Z}_2 = \lim_{\varepsilon \to 0} \Gamma_\varepsilon$ for the above $\Gamma_\varepsilon \subset \mathbb{R} \times \mathbb{Z}_2$, where the action of $\mathbb{R} \subset \mathbb{R} \times \mathbb{Z}_2$ is free.

In fact, $\tilde{U}_0 = Y_0 \times \mathbb{R}$ and

$$\tilde{g}_0 = dy^2 + \tilde{\phi}(y)^2 dt^2$$

where $\tilde{\phi}$ is a smooth function on $Y_0$, which, probably, is equal to $\phi$ from section 2, which was defined there via the second differential (variation) of the function $Y \mapsto vol_{n-1}(Y)$.

In general, the spaces $(\tilde{U}_{[-\varepsilon,\varepsilon]}, \tilde{g}_\varepsilon)$ Hausdorff converge away from the $\Gamma_\varepsilon$-orbits of the $\delta$-neighbourhoods of the singularity of $E(Y_0) \subset \tilde{U}_{[-\varepsilon,\varepsilon]}$, where $\delta = \delta_\varepsilon \to 0$ for $\varepsilon \to 0$.

Then $(\tilde{U}_0, \tilde{g}_0)$ stands for the metric completion of the resulting (smooth Riemannian) limit space for $\varepsilon, \delta \to 0$.

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20This is, of course, easy to check but we do not need it here. In any case, we prefer the Hausdorff limit definition of $\tilde{g}_0$, since it is less demanding on the regularities of $X$ and $Y_0$. 

21This is, of course, easy to check but we do not need it here. In any case, we prefer the Hausdorff limit definition of $\tilde{g}_0$, since it is less demanding on the regularities of $X$ and $Y_0$. 

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Question. Does $\mathbb{R}$ act freely on $\tilde{U}_0$ in the case where the minimal hypersurface $Y_0 \subset X$ has singularities?

Consecutive Torical Symmetrization of $(n-m)$-Overtorical Manifolds. A compact oriented $n$-dimensional Riemannian manifold $X$ with (possibly empty) boundary is called $(n-m)$-overtorical, if it comes along with a continuous map $f : X \to \mathbb{T}^{n-m}$, such that the "homological pullback" of a point $\theta_0 \in \mathbb{T}^{n-m}$, denoted $f^*[\theta_0] \in H_m(X, \partial X)$, doesn’t vanish.

(To clarify, recall that if $f_0$ is a smooth map homotopic to $f$, then the pullbacks $f_0^{-1}(\theta) \subset X$ of generic $\theta \in \mathbb{T}^{n-m}$ are smooth oriented submanifolds of dimensions $m$ which are homologous to $f^*[\theta_0]$, i.e. $[f_0^{-1}(\theta)] = f^*[\theta_0]$).

Alternatively, $f^*[\theta_0]$ can be defined as the Poincare dual of the image of the fundamental cohomology class $[\mathbb{T}^{n-m}]^* \in H^{n-m}(\mathbb{T}^{n-m}; \mathbb{Z})$ under the cohomology homomorphism $f^* : H^{n-m}(\mathbb{T}^{n-m}; \mathbb{Z}) \to H^{n-m}(X; \mathbb{Z})$.

For instance, $\mathbb{T}^{n-m} \times B$ is $(n-m)$-overtorical for all compact $m$-dimensional manifolds $B$, possibly with a boundary.

If $X$ is $(n-m)$-overtorical and if $Y_0 \subset X$ represents the homology class in $H_{n-1}(X, \partial X)$ corresponding to the (homological) $f$-pullback of a codimension 1 torus in $\mathbb{T}^{n-m}$, then the manifold $X(\varepsilon) = \tilde{U}_{[-\varepsilon, \varepsilon]} / 2\varepsilon \mathbb{Z}$ is also $(n-m)$-overtorical for all sufficiently small $\varepsilon > 0$.

In fact, this has nothing to do with minimality of $Y_0$. It is, obviously, true for all hypersurfaces $Y_0 \subset X$ in suitable homology classes in $H_{n-1}(X, \partial X)$ and their small neighbourhoods $U_{[\varepsilon, \varepsilon]} \subset X$ say with smooth boundaries or even with singular boundaries, provided the singular loci have codimensions $\geq 2$.

Now let us iterate

$$X \mapsto X(\varepsilon_1) \mapsto X(\varepsilon_1, \varepsilon_2) \mapsto X(\varepsilon_1, \varepsilon_2, ..., \varepsilon_i) \mapsto ..., $$

where each step

$$X(\varepsilon_1, \varepsilon_2, ..., \varepsilon_i) \mapsto X(\varepsilon_1, \varepsilon_2, ..., \varepsilon_i, \varepsilon_{i+1})$$

depends on the choice of a codimension 1 subtorus in the corresponding torus $\mathbb{T}^{n-m}$, where each minimal $Y_0, \subset X(\varepsilon_1, ..., \varepsilon_i)$ and the corresponding $Y_{s\varepsilon_i} \subset X(\varepsilon_1, ..., \varepsilon_i)$ are taken in the non-singular loci of $X(\varepsilon_1, ..., \varepsilon_i)$ modulo their complements (which have positive codimensions).

It should be noted that the $(n-m)$-tori serving $X(\varepsilon_1, ..., \varepsilon_i)$ and $X(\varepsilon_1, ..., \varepsilon_j)$ with $j \neq i$ are not canonically isomorphic. However, it make sense of taking a generic infinite sequence of these subtori, and then to send all $\varepsilon_i \to 0$.

Let us incorporate the relevant properties of the resulting limit space, call it $\tilde{X}_\infty$, in the following.

Definition of $\mathbb{R}^{n-m} \rtimes O(n-m)$-Symmetrization. Given an $(n-m)$-overtorical manifold $X$, call an oriented manifold $\tilde{X}_{sm}$ with (possibly empty) boundary an $\mathbb{R}^{n-m} \rtimes O(n-m)$-symmetrization of $X$ if it satisfies the following nine conditions.

• $\tilde{X}_{sm}$ is isometrically acted upon by $\mathbb{R}^{n-m} \rtimes O(m)$, that is the isometry group of $\mathbb{R}^{n-m}$, such that the orbits of this action are equal to the $\mathbb{R}^{n-m}$-orbits.
The action of $\mathbb{R}^{n-m}$ on $\tilde{X}_{sm}$ is free.

The quotient map $\tilde{X}_{sm} \to \tilde{X}_{sm}/\mathbb{R}^{n-m}$ admits an inverse, say $E_\infty : \tilde{X}_{sm}/\mathbb{R}^{n-m} \to \tilde{X}_{sm}$, where the image $E_\infty(\tilde{X}_{sm}/\mathbb{R}^{n-m}) \subset \tilde{X}_{sm}$ is normal to the $\mathbb{R}^{n-m}$-orbits in $\tilde{X}_{sm}$.

There exists a continuous map

$$\tilde{\varphi}_\infty : \tilde{X}_{sm} \to X,$$

with the following properties.

The map $\tilde{\varphi}_\infty$ is $\mathbb{R}^{n-m} \rtimes O(n - m)$-invariant.

The corresponding map $\varphi_\infty$ from the quotient manifold $\tilde{X}_{sm}/\mathbb{R}^{n-m}$ to $X$,

$$\varphi_\infty = \tilde{\varphi}_\infty/\mathbb{R}^{n-m} : \tilde{X}_{sm}/\mathbb{R}^{n-m} \to X,$$

sends the fundamental homology class

$$[\tilde{X}_{sm}/\mathbb{R}^{n-m}] \in H^m(\tilde{X}_{sm}/\mathbb{R}^{n-m}, \partial \tilde{X}_{sm}/\mathbb{R}^{n-m})$$

to $f^*[\theta_0] \in H^m(X, \partial X)$.

The map $\tilde{\varphi}_\infty$ is 1-Lipschitz.

The map $\tilde{\varphi}_\infty$ is scalar curvature non-increasing.

$$Sc(X)(\tilde{\varphi}_\infty(\tilde{x})) \leq Sc(\tilde{X}_{sm})(\tilde{x}), \quad \tilde{x} \in \tilde{X}_{sm},$$

The map $\tilde{\varphi}_\infty$ sends $\partial \tilde{X}_{sm} \to \partial X$ and it is mean curvature non-increasing.

$$\mu \text{curv}(\partial X)(\tilde{\varphi}_\infty(\tilde{x})) \leq \mu \text{curv}(\partial \tilde{X}_{sm})(\tilde{x}), \quad \tilde{x} \in \partial \tilde{X}_{sm}.$$ 

In short, $\cdot_6 - \cdot_9$ say that symmetrization $X \mapsto \tilde{X}_\infty$ must be the topology and distance in $X$ non-increasing and, at the same time,

the scalar and mean curvatures non-decreasing.

**Symmetrization Theorem.** Every $(n - m)$-overtrical manifold $X$ of dimension $n \leq 7$ admits an $\mathbb{R}^{n-m} \rtimes O(n - m)$-symmetrization.

**Proof.** If $n \leq 7$, then there is no serious problem with singularities, and the above limit space $\tilde{X}_\infty$ satisfies the above conditions $\cdot_1 - \cdot_9$.

In fact, even though the natural metrics on $X(\varepsilon_1, \ldots, \varepsilon_i)$ are only piecewise smooth, the limit space $\tilde{X}_{sm}$ of the $\mathbb{Z}^{n-m}$-covers of $X(\varepsilon_1, \ldots, \varepsilon_i)$ for $\varepsilon_i \to 0$, $i = 1, 2, \ldots$, is a smooth Riemannian manifold with boundary.

Then everything becomes fairly obvious, except for $\cdot_8$ and $\cdot_9$.

To prove these what we use is that, at every symmetrization step $X \mapsto X(\varepsilon)$, the Riemannian metric on $X(\varepsilon)$, which is, a priori, only continuous and which may have a corner at the boundary, can be

$C^\infty$-smoothed with an arbitrarily small decrease of the scalar curvature of $X$ as well as of the mean curvature of $\partial X$.

This is explained in section 11.2.

Then the proof follows by semicontinuity of the scalar curvature and mean curvatures (the latter is essentially obvious) under $C^0$-limits of Riemannian metrics, see [Gr 2014*] and [Bam 2016].
About \( n > 7 \). It is not impossible that the Symmetrization Theorem remains valid for all \( n \) but \( \tilde{X}_\infty \) can be used for this purpose only for \( m \leq 6 \).

For instance, suppose \( X \) is homeomorphic to \( \mathbb{T}^1 \times S^7 \). If our minimizing hypersurface \( Y \subset X \) in the homology class of \( S^7 \subset X \) has a singularity, then, clearly, the space \( \tilde{X}_\infty \) is also singular because \( \tilde{X}_\infty / \mathbb{R}^1 \cong Y \).

On the other hand if \( X \) is homeomorphic to, say, \( \mathbb{T}^{n-m} \times S^m \) for \( m \leq 6 \), then \( \tilde{X}_\infty \) and \( \tilde{X}_\infty / \mathbb{R}^{n-m} \) can be, a priori, non-singular.

This makes the Symmetrization Theorem plausible for all \( n \) and \( m \leq 6 \).

And the techniques (results?) from [SY 2017], probably, yield the symmetrization theorem for all \( n \) and \( m \leq 2 \).

Almost Symmetrization. This means that the conditions \( \bullet_8 \) and \( \bullet_9 \) need to be satisfied up to an arbitrarily small error \( \epsilon > 0 \):

\[
Sc(X)(\tilde{\phi}_\infty(\tilde{x})) \leq Sc(X_{\text{sm}})(\tilde{x}) + \epsilon
\]

and

\[
\min_{\partial X}(\tilde{\phi}_\infty(\tilde{x})) \leq \min_{\partial X}(\tilde{\phi}_{\text{X}_\infty}(\tilde{x})) + \epsilon
\]

Now, since by [NS 1993] minimal hypersurface in generic 8-manifolds are non-singular, the argument used for \( n \leq 7 \), implies the following.

Almost Symmetrization Theorem for \( n = 8 \). All \((n - m)\)-overtorical manifolds of dimension \( n \leq 8 \) admit almost \( \mathbb{R}^{n-m} \times O(n-m) \)-symmetrizations.

9 Application of Symmetrization to Manifolds with Positive and with Negative Scalar Curvatures.

Let \( V \) be a Riemannian band and let \( Z_0 \subset V \) be a closed hypersurface which separates \( \partial V \) from \( \partial_\ast V \) and, thus, divides \( V \) into two halves \( V_+ = \partial_\ast(V) \). Let

- the mean curvatures of \( \partial_\ast V \) are bounded from below by some constants \( M_\ast \);
- the scalar curvature of \( V \) is bounded by a given function \( \sigma = \sigma(d) \) of the signed distance \( d = d(v) \) from \( v \) to \( Z_0 \), that is

\[
Sc(V)(v) \geq \sigma(\text{dist}_\ast(v, Z_0)),
\]

where

\[
\text{dist}_\ast(v, Z_0) = \text{dist}(v, Z_0) \quad \text{for} \quad v \in V_+ \quad \text{and} \quad \text{dist}_\ast(v, Z_0) = -\text{dist}(v, Z_0) \quad \text{for} \quad v \in V_-.
\]

Since \( \mathbb{R}^{n-1} \times O(n-1) \)-symmetric metrics on \( \mathbb{R}^{n-1} \times [-l, l] \) cane be written as

\[
\hat{g} = \hat{\phi}^2 g_{E^n} + dt^2
\]

where \( g_{E^n} \) is the flat Euclidean metric on \( \mathbb{R}^{n-1} \) and where the scalar curvature of \( \hat{g} \), which depends only on \( t \in [-l, l] \), satisfies

\[
Sc(\hat{g}) = -2(n-1) \frac{\hat{\phi}''}{\hat{\phi}} - (n-1)(n-2) \frac{(\hat{\phi}')^2}{\hat{\phi}^2};
\]

the net effect of \( \mathbb{R}^{n-1} \times O(n-1) \)-symmetrization of \( V \) can be stated in concrete terms as follows.
Symmetrization of Bands. If the above band $V$ is $\mathbb{R}^{n-1} \times O(n-1)$-symmetrisable, then there exists a smooth function $\tilde{\varphi}(t) = \tilde{\varphi}_\sigma(t)$, on the segment $[-l, +l]$ such that

$$\pm l \geq \text{dist}(Z, \partial_{\pm} V),$$

$$\frac{\tilde{\varphi}'(-l)}{\tilde{\varphi}(-l)} \geq -\frac{M_\epsilon}{n-1}, \quad \frac{\tilde{\varphi}'(l)}{\tilde{\varphi}(l)} \leq \frac{M_\epsilon}{n-1}$$

and

$$-2(n-1)\frac{\tilde{\varphi}''(t)}{\tilde{\varphi}} - (n-1)(n-2)\frac{\tilde{\varphi}'(t)^2}{\tilde{\varphi}(t)^2} \geq \sigma(t),$$

that is

$$2f'(t) - nf(t)^2 \geq \frac{\sigma(t)}{n-1} \quad \text{for } f(t) = \frac{\tilde{\varphi}'(t)}{\tilde{\varphi}(t)} \text{ and all } t \in [-l, l].$$

Symmetrization Corollary for $Sc \geq 0$. Let $V$ be an isoenlargeable band and $Z_0 \subset V$ be a hypersurface which separates $\partial_{-}(V)$ from $\partial_{+}(V)$. Let $Sc(V) \geq 0$ and let

$$Sc(V) \geq \sigma_0 > 0 \text{ on the } \delta_0 \text{-neighbourhood of } Z_0.$$

Then the distance from $Z$ to the boundary $\partial V$ is bounded by a constant which depends only on the dimension of $V$, on $\sigma_0 > 0$ and on $\delta_0 > 0$,

$$\text{dist}(Z, \partial V) \leq C = C_n(\sigma_0, \delta_0).$$

Moreover, this remains true

if the inequality $Sc(V) \geq 0$ is replaced by $Sc(V) \geq -\epsilon$ for a small positive $\epsilon \leq \varepsilon_n(\sigma_0, \delta_0) > 0$.

Proof. If $\sigma(t) \geq \sigma_0$ for $t \in [-\delta_0, \delta_0] \subset [-l, l]$ and $\sigma(t) \geq -\epsilon$ for all $t \in [-l, l]$, where $\epsilon \ll \delta_0, \sigma_0$, then the inequality $\mathfrak{D}_t$ implies that

$$l \leq C = C_n(\sigma_0, \delta_0)$$

and the proof follows.

Notice that no condition $\text{mean.curv}(\partial_{\pm}(V)) \geq M_\pm$ has been used at this point.

Sub-corollary for Complete Manifolds with $Sc \geq 0$. Open isoenlargeable bands carry no complete metrics with scalar curvatures $Sc > 0$.

Moreover,

complete metrics with $Sc \geq 0$ on such bands are Riemannian flat.

In fact, a deformation theorem by Kazdan and Warner together with the Cheeger-Gromoll splitting theorem imply that if such a band admits no complete metric with $Sc > 0$ then every complete metric with $Sc \geq 0$ is flat.

Representative Example. If a compact manifold $Z$ admits a metric with negative sectional curvature, then there is no complete metrics with $Sc \geq 0$ on the connected sums

$$X = (Z \times \mathbb{R}) \# P_1.$$
for compact manifolds $P_i$.

(A similar result is proven in 6.12 and 6.13 of [GL 1983] for spin manifolds $X$.)

**Symmetrization Corollary for $Sc \geq \sigma < 0$.** To get a perspective look at the following

**Model Example.** Let $V_{[-l,l]}$ be the band of width $2l$ between concentric horospheres in the hyperbolic space $H^n$ of constant curvature $-1$, which is the product

$$V_{[-l,l]} = \mathbb{R}^{n-1} \times [-l,l] \subset \mathbb{R}^{n-1} \times (-\infty, \infty) = H^n,$$

where the hyperbolic metric in these coordinates is $g_{hyp} = e^{2t}g_{Eu} + dt^2$.

The scalar curvature of $g_{hyp}$ in these coordinates, in agreement with $H^n$, is

$$Sc(V_{[-l,l]}) = -n(n-1),$$

while the mean curvatures of the boundaries $\partial V_{[-l,l]} = \mathbb{R}^{n-1} \times \{ \pm l \}$ are

$$\text{mean.curv}(\partial V_{[-l,l]}) = \pm (n-1).$$

Such a band becomes compact if divided by the action of $Z^{n-1} \subset \mathbb{R}^{n-1}$ for

$$\mathbb{R}^{n-1} \times [a,b]/Z_{n-1} = \mathbb{T}^{n-1} \times [a,b].$$

Now, let $V$ be a compact Riemannian overtorical band, where the scalar curvature and the mean curvatures of the boundaries satisfy

$$Sc(V) \geq -n(n-1),$$

$$\text{mean.curv}(\partial_-(V)) \geq -(n-1),$$

$$\text{mean.curv}(\partial_+(V)) \geq (n-1).$$

then, in fact,

$$Sc(V) = -n(n-1),$$

$$\text{mean.curv}(\partial_-(V)) = -(n-1),$$

$$\text{mean.curv}(\partial_+(V)) = (n-1).$$

**Proof.** If either of the above three inequalities is strict (i.e. $"\geq"$) at some point, then, by slightly conformally perturbing the metric of $V$ (see section 11.2), one can make all three strict at all points.

This, by symmetrization, would result in a function $\hat{f} = \frac{f'}{f}$ on some segment $[-l,l]$, $l > 0$, such that

$$f(-l) < 1, \quad f(l) > 1$$

and

$$2f' < -n(f^2 - 1)$$

which is, obviously, impossible. QED.

**Sub-corollary: Weak Rigidity of $H^n/Z^{n-1}$.** Let $X = H^n/Z^{n-1}$, where $H^n$ is the hyperbolic space with the sectional curvature $\kappa(g_{hyp}) = -1$, and the group $Z^{n-1}$ discretely and isometrically acts on $H^n$ by parabolic transformations, i.e. preserving a horosphere in $H^n$. If $n \geq 3$, then all discrete isometric actions of $Z^{n-1}$ on $H^n$ are parabolic.

---

21If $n \geq 3$ then all discrete isometric actions of $Z^{n-1}$ on $H^n$ are parabolic.
If a Riemannian metric on \( X \), which coincides with the hyperbolic one (descended from \( H^n \) to \( X \)) outside a compact subset in \( X \), satisfies

\[
Sc(g) \geq Sc(H^n) = -n(n - 1)
\]

then

\[
Sc(g) = -n(n - 1)
\]
everywhere on \( X \).

**Soap Bubbles and Rigidity of Bands.** A sharper version of the above sub-corollary, namely the implication

\[
\exists \int M \quad Sc(g) \geq -n(n - 1) \Rightarrow \kappa(g) = -1
\]

follows from the existence of stable minimal bubbles in \( X \), which are closed hypersurfaces \( Y \) which separate the two ends in \( X \) and which minimise the functional

\[
Y \mapsto vol_{n-1}(Y) - (n - 1)vol(X_{vY}),
\]

where \( X_{vY} \subset X \) is the part of \( X \) which is bounded by \( Y \) and which has \( vol < \infty \).

**Proof.** The relation \([\@.1]\) for \( n \leq 8 \) follows from \( \@[M] \) below by taking \( M = n - 1 \).

\( \@[M] \). Let a compact Riemannian band \( V \) admit a function \( M = M(v) \) such that

\[
M|_{\partial V} \leq -\text{mean.curv}(\partial V) \quad \text{and} \quad M|_{\partial V} \geq \text{mean.curv}(\partial V)
\]

and

\[
\frac{n}{n - 1} M^2 - 2\|dM\| + Sc(V) \geq 0.
\]

If \( n = \text{dim}(V) \leq 8 \), then either

- there is a closed hypersurface \( Y_0 \subset V \), which separates \( \partial V \) from \( \partial_0 V \) and which admits a metric with \( Sc > 0 \),

or

- \( V \) decomposes into the (warped) product, \( V = Y \times [-l, l] \) with the metric

\[
\varphi(t)^2g_Y + dt^2,
\]

where the Riemannian metric \( g_Y \) on \( Y \) has zero Ricci curvature.

This is shown for \( n \leq 7 \) in section 5.2.5 in [Gr 1996] and the case \( n = 8 \) can be taken care of with a help of ideas from [NS 1993].

But it seems that the regularisation techniques of [Loh 2016] and/or of [SY 2017] do not apply, at least not directly, to this case and the validity of the above statement for \( n \geq 9 \) remains quite problematic.

On the other hand \([\@.1]\), where the implied \( Y_0 \) is the \( n - 1 \) torus, must follow from these techniques which are, in principle, applicable whenever torical symmetrization works.

**On Min-Oo Rigidity Theorem.** By adapting an idea of Witten to a "hyperbolically modified" Dirac operator, Min-Oo [Mi 1989] proved a version of the positive mass theorem for \( H^n \). In particular he has shown the following.
If a complete spin manifold $X$ is isometric to $H^n$ outside a compact subset and if $Sc(X) \geq -n(n-1)$ then $X$ is isometric to $H^n$.

Since compact perturbations of $H^n$ can be periodically extended by discrete actions of isometry groups $\Gamma$ on $H^n$, e.g. for the above parabolic $Z^n$, \[\text{[MRT]}\] follows from $[\Omega]$. Thus, \[\text{[MRT]}\] remains valid without assuming $X$ is spin (but with some reservations for $n \geq 9$).

Moreover, this is shown in [AndMinGal 2007], that [MRT] combined with an argument from [Loh 1999] implies the positive mass theorem for $H^n$ and the spin condition can be disposed of in the context of the full Min-Oo-(Wang Chruściel-Herzlich) theorem (unconditionally for $n \leq 8$).

**Proving Rigidity by Symmetrization.** The rigidity of bands $V$ in the symmetrization context says that the universal coverings of the extremal bands, where our $\frac{2\pi}{n}$-inequality becomes an equality, must be $\mathbb{R}^{n-1} \rtimes O(n-1)$-invariant.

We shall indicate below the proof of this for $n \leq 7$, where the dimension $n = 8$ needs a little effort, and where the regularisation as developed in [Loh 2016] and in [SY 2017] for $n \geq 9$ may need an additional refinement to yield rigidity.

Now, assuming minimal varieties are non-singular, we observe that the symmetrization process strictly enlarges the scalar curvature of $V$, unless the minimal hypersurfaces $Y \subset V$ used for this process are totally geodesic.

In fact, by the second variation formula in the form given to it in [SY - Inc 1979], the corresponding operator $L$ from section 2 is strictly positive, which implies increase of the scalar curvature under symmetrization. And this also work for symmetrization by reflection in section 2 if one replaces the smoothing of edges argument by an appeal to the corresponding operator $L$.

Thus, one represent all our homology classes in $H_{n-1}(V, \partial V)$ by totally geodesic submanifolds. This strongly restricts the geometry of $V$ but does not, at least not obviously, imply the required $\mathbb{R}^{n-1} \rtimes O(n-1)$-symmetry of $V$.

However, by applying the same argument to the soap bubbles $Y_{\epsilon} \subset X$ which lie close to minimal $Y$ and minimise the functional $Y \rightarrow vol_{n-1}(Y) - \epsilon \cdot vol_n U_{\epsilon}$ as in section 8 one sees that no minimal $Y$ can be locally strictly minimising in either of the two halves it divides $V$ into.

This shows, that minimal $Y$ in all homology classes, besides being totally geodesic, are "freely movable" in $V$, namely, they serve as fibers of a fibrations of $V$ over the circle.

Then the required $\mathbb{R}^{n-1} \rtimes O(n-1)$-symmetry of $V$ easily follows.\[22\]

10 **Comparison with Results Obtained with Twisted Dirac Operators.**

Besides the method of of minimal hypersurfaces, a non-trivial information on geometry (and topology) of Riemannian manifolds $X$ with $Sc(X) \geq \sigma$, $\sigma \in (-\infty, \infty)$, can be obtained by confronting

\[22\]Since I have not written this down in detail, I might have missed some hidden difficulty in this apparently quite innocuous argument.
I: Atiyah-Singer type index theorems for Dirac operators which yield non-zero harmonic spinors on $X$

with

II: the twisted Schroedinger-Lichnerowicz-Weitzenboeck formula for manifolds with lower bounds on their scalar curvatures which rules out, or significantly restricts, such spinors.

Comparison of (partly overlapping) results obtainable with minimal hypersurfaces and with Dirac operators exposes limitations of both methods and exhibits wide gaps in our understanding of scalar curvatures; this begs for a new approach.

Let us briefly demonstrate this on a few simple examples.\footnote{See [Ros 2007], [BER 2014], [Gr2017] for more elaborated techniques and examples.}

(1) Spin, Spinor Bundles and Dirac Operators. Since the fundamental group of the special (i.e. orientation preserving) orthogonal group $SO(n)$ for $n \geq 3$ is $\mathbb{Z}/2\mathbb{Z}$, there are exactly two different orientable bundles of rank $n \geq 3$ over closed connected surfaces. The trivial bundle is, by definition, spin and the non-trivial one is non-spin.

An orientable manifold $X$ is called spin if the restrictions of the tangent bundle $T(X)$ to all surfaces $S \subset X$ are spin (i.e. trivial).\footnote{"Spin" makes sense also for non-orientable bundles and manifolds but we do not need them at this point.}

For instance, all orientable hypersurfaces $X^n \subset \mathbb{R}^{n+1}$ are spin, all 3-manifolds are spin and simply connected n-manifolds with trivial second homotopy groups are spin.

The simplest non-spin manifolds are the complex projective spaces $\mathbb{C}P^n$ of even complex dimensions and connected sums of other manifolds with these $\mathbb{C}P^n$.

The spinor bundle of a Riemannian spin manifold $X$ of dimension $n$, denoted $S(X)$, is a unitary vector bundle of vector bundle of rank $2n$ with a unitary connection associated to the Levi-Civita connection in $T(X)$. If $n$ is even, the bundle $S(X)$ splits, $S = S^+ \oplus S^-$.

The Dirac operator is a canonically defined first order differential operator $D$ represented as a certain "natural" linear combination of covariant derivatives which act on $S(X)$. (See [BHMM 2015] for definitions, basic results and geometric applications of the Dirac operator.)

When $n$ is even the Dirac operator splits: $D = D^+ \oplus D^-$, where the operators $D^+$ and $D^-$ are mutually adjoint for $D^+ : C^\infty(S^+) \to C^\infty(S^-)$ and $D^- : C^\infty(S^-) \to C^\infty(S^+)$ and where $\text{ind}(D) = \text{dim}(\ker D^+) - \text{dim}(\ker D^-)$. The solutions of $D(s) = 0$ are called harmonic spinors on $X$.

Twisted Dirac operator. Given a complex vector bundle $L = (L, \nabla)$ with a linear connection, one naturally defines

$$D^\pm_{\otimes L} : C^\infty(S^\otimes L) \to C^\infty(S^\otimes L),$$

where the sections of $S^\otimes L$ in the kernel of $D_{\otimes L} = D^-_{\otimes L} \oplus D^+_{\otimes L}$ are called $L$-twisted harmonic spinors.

(2) Chern character and Todd Genus. The Chern character of a complex vector bundle $L$ over $X$ is a certain polynomial in the Chern classes $c_i \in H^i(X; \mathbb{Z})$.
of $L$ in the rational cohomology $H^\ast(X; \mathbb{Q})$ starting from $c_0 = \text{rank}(L)$,

$$
ch(L) = c_0 + c_1 + \frac{1}{2}(c_1^2 + c_2) + \frac{1}{6}c_1^3 + c_1c_2 + 3c_3 + \ldots + \frac{1}{n!}(c_1^3 + \ldots + k_ic_i) + \ldots
$$

where, observe, all $k_i \neq 0$. The basic properties of $ch$ (which essentially define it) are additivity and multiplicativity:

$$
ch(L_1 \oplus L_2) = ch(L_1) + ch(L_2) \quad \text{and} \quad ch(L_1 \otimes L_2) = ch(L_1) \cdot ch(L_2).
$$

The $\hat{A}$-genus is another polynomial, now in the Pontryagin classes $p_i = p_i(T(X)) \in H^\ast(X; \mathbb{Q})$,

$$
\hat{A}(X) = 1 - \frac{1}{24}p_1 + \frac{1}{5760}(-4p_2 + 7p_1^2) + \frac{1}{967680}(-16p_3 + 44p_2p_1 - 31p_1^3) + \ldots
$$

where again the coefficients at $p_i \in H^{4i}(X; \mathbb{Z})$ are non-zero.

(3) **Topological Index $I$.** Let $\hat{X}$ be an oriented Riemannian spin $\Gamma$-manifold, which means $\hat{X}$ is acted upon by a group $\Gamma$ and let $L_1 = (\hat{L}_1, \nabla_1)$ and $L_2 = (\hat{L}_2, \nabla_2)$ be complex vector bundles with unitary connections such that $\Gamma$ acts on $\hat{L}_1$ and on $\hat{L}_2$ by fiber-wise unitary (linear isometric) connection preserving transformations compatible with the action of $\Gamma$ on $X$, such that the following conditions are satisfied.

(i) The action of $\Gamma$ on $\hat{X}$ is *proper, isometric and orientation preserving*, where "proper" means that there are at most finitely many $\gamma \in \Gamma$, such that for all compact subsets $K \subset \hat{X}$ the intersections $K \cap \gamma(K)$ are empty for all but finitely many $\gamma \in \Gamma$.

(ii) There exists a unitary connection preserving $\Gamma$-equivariant isomorphism between the bundles $\hat{L}_1$ and $\hat{L}_2$ at infinity, that is on the complement to a $\Gamma$-invariant subset $V \subset \hat{X}$ such that $V/\Gamma$ is compact.

Let

$$
I = I(\hat{X}, \hat{L}_1 \oplus \hat{L}_2) = (\hat{A} \cdot (ch(\hat{L}_1) - ch(\hat{L}_2)))[\hat{X}/\Gamma]
$$

be defined by representing $\hat{A}$, $ch(\hat{L}_1)$ and $ch(\hat{L}_2)$ by the Chern-Weil differential forms on $\hat{X}$, call them $\alpha, \lambda_1, \lambda_2 \in \Lambda^\ast(\hat{X})$ which, clearly, are $\Gamma$-invariant and where $\lambda_1 - \lambda_2$ vanishes outside $V$.

Since the form $\iota = \alpha \wedge (\lambda_1 - \lambda_2)$ vanishes outside $V$, since it is $\Gamma$-invariant and since the action of $\Gamma$ on $\hat{X}$ is proper, $\iota$ descends to a form $\hat{\iota}$ on the quotient space $\hat{X}/\Gamma$, which vanishes outside a compact subset and defines the cohomology class $[\hat{\iota}] = (\hat{A} \cdot (ch(\hat{L}_1) - ch(\hat{L}_2))) \in H^n(\hat{X}/\Gamma; \mathbb{R})$.

Then the index $I = [\hat{X}/\Gamma]$ can be defined as the integral

$$
\int_{\hat{X}/\Gamma} \hat{\iota} = \int_{\Delta} \hat{\iota}
$$

for a fundamental domain $\Delta \subset \hat{X}$.

\footnote{We do not assume the action of $\Gamma$ on $\hat{X}$ to be free and the space $\hat{X}/\Gamma$ may be singular but our forms are defined on it anyway.}
(4) Atiyah’s $L_2$-Index Theorem. Let the following conditions be satisfied.

(a) The manifold $\tilde{X}$ is complete.

(b) The connections in $\tilde{L}_1$ and in $\tilde{L}_2$ are unitarizable. This means these bundles admit unitary structures, i.e. fiberwise Hermitian scalar products (…), preserved by the parallel transport in these connections.

(c) The above unitary structures, (which are unique up to scaling) are $\Gamma$-invariant.

(d) The operators $D_{\tilde{L}_1}^2$ and $D_{\tilde{L}_2}^2$ are uniformly positive at infinity/Γ, where a differential operator $D$ on sections $s = s(\tilde{x})$ of a unitary bundle on a manifold $\tilde{X}$ with a $\Gamma$ action is called uniformly positive at infinity/Γ, if

$$\int_{\tilde{X}} (D(s(\tilde{x})), s(\tilde{x}))_2 d\tilde{x} \geq c \cdot \int_{\tilde{X}} \|s(\tilde{x})\|^2$$

for a constant $c > 0$ and all sections $s$ with compact supports outside a certain subset $V \subset \tilde{X}$ such that $V/\Gamma$ is compact.

If the topological index $I = I = I(\tilde{X}, \tilde{L}_1 \oplus \tilde{L}_2)$ does not vanish, then there exists either an $L_1$- or $L_2$-twisted harmonic square integrable spinor on $\tilde{X}$.

In fact, the von-Neumann dimensions of the kernels $\hat{K}_{1,2}$ of the operators $D_{\tilde{L}_1,2}^\pm$ satisfy

$$\dim_\Gamma(\hat{K}_1^\pm) - \dim_\Gamma(\hat{K}_1^-) - \dim_\Gamma(\hat{K}_2^+) + \dim_\Gamma(\hat{K}_2^-) = I(\tilde{X}, \tilde{L}_1 \oplus \tilde{L}_2).$$

About the Proof. The equality

$$\dim_\Gamma(\ker D_{\tilde{L}_1}^+) - \dim_\Gamma(\ker D_{\tilde{L}_2}^-) = I(\tilde{X}, \tilde{L})$$

in the case of compact $\tilde{X}/\Gamma$ is proven in [At 1976].

(If $\tilde{X}/\Gamma$ is compact only a single bundle $\tilde{L} = \tilde{L}_1$ is needed, since one may take the trivial bundle of rank zero for $\tilde{L}_2$; then the conditions (a) and (d) are irrelevant.)

The case of non-compact manifolds with no $\Gamma$-actions is treated in [GL 1983].

The compatibility of the two arguments was pointed out in [Gr 1986], where one finds further references.

Suggestion. It would be interesting to remove or to relax some of the conditions in the formulation of the index theorem.

spin-Example. Let $\tilde{X}$ be the universal covering $X$ of a manifold $X$. If $X$ is spin then the spin bundle $S(X)$ and the Dirac operator in it are defined and lift $\Gamma$-equivariantly to $X = \tilde{X}$ for the Galois action of $\Gamma = \pi_1(X)$ on $\tilde{X}$.

But if $X$ is non-spin, yet $\tilde{X}$ is spin, then the group which acts on $S(\tilde{X})$ is the semidirect product $\mathbb{Z}_2 \rtimes \Gamma$ where $\mathbb{Z}_2$ acts by the $\pm 1$-involution on spinors which corresponds to the Galois involutive transformation on the double covering of the principal bundle associated to the tangent bundle $T(\tilde{X})$.

Thus,

*Atiyah’s $L_2$-index theorem applies to the Galois coverings $\tilde{X}$ of non-spin manifolds $X$ whenever these $\tilde{X}$ are spin.*
(5) Twisted Schroedinger-Lichnerowicz-Weitzenboeck Formula. This formula relates the squares of $L$-twisted Dirac operators with the rough Laplacians $\nabla^* \nabla$ in the bundles $L = (L, \nabla)$ on $X$ with unitary connections, where, recall, the operators $\nabla^* \nabla$ acts on sections of $L$; they are (non-strictly) positive

$$\int \nabla^* \nabla = \int ||\nabla||^2;$$

thus their kernels consist of $\nabla$-parallel sections of $L$ and $\text{rank}(\ker(\nabla^* \nabla)) \leq \text{rank}(L)$.

Here is the formula.

$$D^2_{\text{gal}} = \nabla^* \nabla + \frac{1}{4} \text{Sc}(x) \cdot Id + \mathcal{R} ,$$

where $\mathcal{R}$ is a linear self adjoint endomorphism (zero order operator) of $\mathbb{S} \times L$ defined by the operator valued curvature form $R$ of $L$ coupled by the Clifford multiplication in $\mathbb{S}$ as follows.

$$\mathcal{R}(s \otimes l) = \frac{1}{2} \sum_{1 \leq i,j \leq n} e_i e_j s \otimes R(e_i \wedge e_j)(l),$$

where $Id : \mathbb{S} \times L$ is the identity operator, where $e_i \in T_x(X) \subset T(X)$ is an orthonormal frame at the point $x \in X$, where the above formula applies and where $s \in \mathbb{S}_x$ and $l \in L_x$.

Since the Clifford multiplication operators $e_i : s \mapsto e_is$ are unitary,

$$||\mathcal{R}(s \otimes l)|| \leq \frac{n(n-1)}{4} ||s|| \cdot ||l||$$

where $||R||$ is the supremum of the norms of the curvature operator over all unit bivectors in the tangent spaces $T_x(X)$.

It follows then the norm of the operator $\mathcal{R}$ is bounded by

$$||\mathcal{R}|| \leq \text{const}_n ||R||$$

for

$$\text{const}_n = \frac{n(n-1)}{4} \sqrt{\text{rank}(\mathbb{S})} = n(n-1)2^{n-2}.$$

(6) Let $\bar{X}$ be a $\Gamma$-manifold with $\Gamma$-invariant bundles $\bar{L}_1, \bar{L}_2$, such that the assumptions (a), (b) and (c) in the above Atiyah’s $L_2$-index theorem are satisfied. Let, moreover, the norms of the curvature operators $R_1$ and $R_2$ of the (unitary) connections in $\bar{L}_1$ and $\bar{L}_2$ be bounded by

$$\text{Sc}(\bar{X})(\tilde{x}) \geq \varepsilon + 4 \text{const}_n \cdot \max(||R_1||_2, ||R_2||_2)$$

for the above $\text{const}_n = n(n-1)2^{n-2}$, some $\varepsilon > 0$ and all $\tilde{x} \in \bar{X} \setminus V$ for a subset $V \subset \bar{X}$ with compact quotient $V/\Gamma$.

Then the above (4) and (5) yield the following.

**Theorem.** If the topological index

$$I = I(\bar{X}, \bar{L}_1 \otimes \bar{L}_2) = \hat{A} \cdot (\text{ch}(\bar{L}_1) - \text{ch}(\bar{L}_2))(X/\Gamma)$$

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doesn’t vanish, then there exists a point \( \hat{x} \in \hat{X} \), where
\[
\text{Sc}(\hat{X})(\hat{x}) \leq 4\text{const}_n \cdot \max(\|R_1\|_{\hat{x}}, \|R_2\|_{\hat{x}}).
\]

(7) Area Enlargeable Manifolds  Recall that an \( n \)-dimensional Riemannian manifold \( X \) is called area enlargeable if it admits a sequence of orientable coverings \( \tilde{X}_i \to X \) and of smooth maps \( f_i: \tilde{X}_i \to S^n \) which are
- \( \bullet_1 \) constant at infinity,
- \( \bullet_2 \) have non-zero degree,
- \( \bullet_3 \) contract the areas of the surfaces \( \Sigma \subset \tilde{X}_i \) by
\[
\text{area}(f_i(\Sigma)) \leq \alpha_i \text{area}(\Sigma) \text{ for } \alpha_i \to 0
gives rise to a point \( \hat{x} \in \hat{X} \).

Observe that area enlargeability is a weaker condition than enlargeability, where instead of \( \bullet_3 \) one requires \( \text{Lip}(f_i) \to 0 \) (see section 4), and that area enlargeability, similarly to enlargeability, is a homotopy invariant of compact manifolds \( X \).

Let us show of that area enlargeability is incompatible with \( \text{Sc} > 0 \).

[\square] Complete area enlargeable manifolds \( X \) the universal coverings of which are spin can’t have \( \text{Sc}(X) \geq \varepsilon > 0 \).

**Proof.** Let’s first assume that \( n = 2m \) and let \( L \) be a complex vector bundle of some rank \( N \) over \( S^n \) with non-zero Chern class \( c_m \in H^n(S^n) \).

Let \( X \) be the universal covering \( \tilde{X} \) acted upon by \( \Gamma = \pi_1(X) \), let \( L_1 \) be the trivial bundle \( X \times \mathbb{C}^N \) and let \( L_i \) be induced from \( L \) by the composed map
\[
X = \tilde{X} \to \tilde{X}_i \to S^n.
\]

It is easy to see that non-vanishing of \( c_m \) implies non-vanishing of the topological index \( I \) and that the curvature of \( L_i \) tends to zero for \( i \to \infty \).

Therefore, the above (6) applies to \((X, L_1, L_i)\) for a sufficiently large \( i \) and yields the proof for even \( n \), while the case of \( n = 2m - 1 \) reduces to \( n = 2m \) by taking \( X \times S^1 \).

(8) Llarull’s Rigidity Theorem. The above, as it is shown in [Li 1998] can be rendered sharp by taking the positive (or negative) spin bundle \( \mathbb{S}^+(S^n) \) for \( L \).

The Chern character of \( \mathbb{S}^+(S^n) \) for \( n = 2m \) is equal to the fundamental cohomology class \( [S^n] \in H^n(S^n) \) and the norm of the Levi-Civita connection in this bundle equals \( \frac{1}{2} \) — all this is more or less obvious.

What is less obvious (see Li 1998), [Min-Oo 2002] is that the lowest eigenvalue of the operator \( \mathcal{R} \) on \( \mathbb{S} \otimes \mathbb{S}^+ \) on \( S^n \) is equal \( -\frac{n(n-1)}{4} \), which, by (6) (and a trifle of linear algebra) implies the following

\[ \square \] Let \( X \) be a Riemannian manifold, such that
- \( X \) is complete,
- \( \text{Sc}(X)(x) \geq \varepsilon > 0 \) for all \( x \) outside a compact subset in \( X \).
- the universal covering \( \tilde{X} \) of \( X \) is spin.

Let a continuous map \( f: X \to S^n \) satisfy the following conditions.

\(^{26}\) "Area enlargeable" appears as "\( \Lambda^2 \)-enlargeable" in [GL 1983], where the coverings \( \tilde{V}_i \) are assumed spin.
(\ast_{f_\infty}) f \text{ is constant at infinity (i.e. constant outside a compact subset in } X); \\
(\ast_{deq}) f \text{ has non-zero degree;}
(\ast_{C^1}) f \text{ is } C^1\text{-smooth;}
(\ast_{ar}) \text{ The map } f \text{ (non-strictly) decreases integrals of the scalar curvature of } X \text{ over all smooth surfaces } \Sigma \subset X. \text{ (Since } S^n \text{ has constant scalar curvature } n(n-1)\text{ this amounts to the inequality}

\[ \int_S Sc(X)(\sigma)d\sigma \geq n(n-1)\text{area}(f(\Sigma)). \]

Then

The map \( f \) is a homothety: there exists a constant \( \lambda > 0 \), such that

\[ \text{dist}_{S^n}(f(x_1), f(x_2)) = \lambda \cdot \text{dist}_X(x_1, x_2) \text{ for all } x_1, x_2 \in X. \]

**About the Proof.** Here, the Dirac operator on \( X \) is twisted with the bundles \( L = L_1 \), which is induced by \( f : X \to S^n \) from \( S^*(S^n) \), and where one takes the trivial bundle of the same rank as \( L \) for \( L_2 \).

In this case, the formula for \( \mathcal{R} : S \otimes L \to S \otimes L \) from the above (5), that is

\[ \mathcal{R}(s \otimes l) = \frac{1}{2} \sum_{1 \leq i < j \leq n} e_i e_j s \otimes R(e_i \wedge e_j)(l), \]

written in the frames of vectors \( e_i \in T_x \), which simultaneously diagonalize the Riemannian metric of \( X \) and the metric induced by \( f \) from \( S^n \) effectively describes the action of \( \mathcal{R} \) on the corresponding (Clifford) basis in \( S(X) \otimes f'(S^*(S^n)) \), which is \( \{ e_1, e_2, \ldots, e_n, \otimes e_1, e_2, \ldots, e_n \} \). Then a straightforward computation in [Li 1998] (and/or a more conceptual argument in [Min-Oo 2002]) shows that the spectrum of \( \mathcal{R} \) is bounded from below by \( -\frac{n(n-1)}{4} \) and the above (6) applies.

The above settles the case of even \( n \).

If \( n \) is odd one uses area contracting maps \( X \times S^1(R) \to S^{n+1} \) for large \( R \) where the corresponding \( \mathcal{R} \) is still bounded by by \( \frac{1}{4}(n(n+1) = \frac{1}{4}Sc(S^n)) \) because the natural splitting of metric in \( X \times S^1 \to S^{n+1} \) (see [Li 1998]).

Alternatively, one can construct (non-split) metrics \( g_\varepsilon \) for on \( X \times S^1 \to S^{n+1} \), for all \( \varepsilon > 0 \), with \( Sc(g_{\varepsilon}) \geq (n + 1)(n + 2) - \varepsilon = Sc(S^{n+1}) - \varepsilon \), such that area non-increasing maps \( X \to S^n \) suspend to area non-increasing maps \( (X \times S^1, g_\varepsilon) \to S^{n+1} \).

**Generalisation.** It is shown in [GS 2002] that the above remain valid for \( S^n \) if the standard metric \( g \) on \( S^n \) is replaced by \( g' \) with positive curvature operator. This, shows, in particular, that Llarull’s theorem is stable under small perturbations of the spherical metric \( g_0 \).

**(9) Discussion.** There are two drawbacks of the above results compared to what can be done with minimal hypersurfaces.

I. Spin. In the original paper [Li 1998] the manifold \( X \) was assumed spin, which we have relaxed to requiring the universal covering of \( X \) to be spin. Yet, we still can’t prove, \( \square \) or even \( \square \) for all complete manifolds.

II. Completeness. Neither \( \square \) or \( \circ \) hold true as they stand for incomplete manifolds and it is unclear what their correct reformulations should be.
And even if the area decreasing condition for maps \( f : X \to S^n \) is strengthened to \( \text{Lip}(f) \leq 1 \), one can’t get any bound on \( Sc(X) \) with Dirac operator methods for incomplete \( X \), while minimal hypersurface do allow such bounds (see section 3).

On the other hand, the Dirac operator results also have two advantages over those achieved with minimal hypersurfaces.

[i] **Area Versus Length.** Application of minimal hypersurfaces depends on distance rather than area estimates of metrics involved.

[ii] **Non-Abelian Symmetries.** Dirac operator effectively accommodates symmetries of underlying (model) manifolds.

For instance, one can not prove with minimal hypersurfaces that no metric \( g \geq g_0 \) on \( S^n \), where \( g_0 \) is the standard metric with the sectional curvature 1, can have \( Sc(g) \geq n(n-1) = Sc(g_0) \).  

**Specific Problem.** Let \( Z \subset S^n \) be a closed subset of codimension \( k \geq 2 \), let \( X \) be an orientable \( n \)-dimensional Riemannian manifold and let

\[
\inf_{x \in X} Sc(X)(x) < n(n-1) = Sc(S^n) .
\]

**Example.** If \( Z \) is a piecewise smooth one-dimensional subset (graph) with trivial Levi-Civita holonomies along all its cycles, e.g. a disjoint union of trees, and if \( X \) complete, then – compare with remark (a) in section 3, 

\[
\inf_{x \in X} Sc(X)(x) < n(n-1) = Sc(S^n) .
\]

**Proof.** Let \( \epsilon : S^n \to S^n \) be an arbitrarily small perturbation of the identity map which sends a small neighbourhood of \( Z \) to \( Z \). Then the bundle \( L \) on \( X \) which is induced from \( S^1(S^n) \) by the composed map \( \epsilon \circ f : X \to S^n \) is trivial at infinity and the above proof of \( \bigcirc \) applies.

More generally, the same argument applies to closed subsets \( Z \subset S^n \) admit sequences of maps \( \epsilon_i : S^n \to S^n \)

such that

- the maps \( \epsilon_i \) converge, for \( i \to \infty \), to the identity map in the \( C^1 \)-topology.

**Questions.** (a) Can one more effectively describe these \( Z \) e.g. those of the topological dimension zero?

(b) Does the above inequality \( \inf_x Sc(X)(x) < n(n-1) \) hold true for smooth closed curves \( Z \subset S^n \), \( n \geq 3 \), with non-trivial holonomy?.

(c) Does \( S^n \) minus a point admit a incomplete metric \( g \geq g_0 \) with \( Sc(g) > n(n-1) = Sc(g_0) \) (where \( g_0 \) is the spherical metric)?

Such a proof may be possible for \( n = 3 \) with suitable boundary conditions for minimizing surfaces.
Let us generalise the class of overtorical manifolds \( X \), where non-zero multiples of the fundamental cohomology classes, denoted \([X]^\circ \in H^n(X;\mathbb{Z})\), decompose into products of one dimensional classes,

\[
k[X]^\circ = h_1 \cdots h_n, \ h_i \in H^1(X;\mathbb{Z}),
\]

as follows.

**10 Oversymplectic Manifolds.** A compact orientable \( n \)-dimensional manifold \( X \) is oversymplectic if a multiple of the fundamental cohomology class of \( X \), decomposes into product of one and two dimensional classes,

\[
k \cdot [X]^\circ = h_1 \cdots h_m,
\]

and such an \( X \) is called \([\theta 0]\)-oversymplectic, if

the classes \( h_i \) vanish in the cohomology of the universal covering \( \tilde{X} \) under the natural homomorphism \( H^*(X) \rightarrow H^*(\tilde{X}) \).

Notice that \([\theta 0]\) is automatic for 1-dimensional classes.

Also note that if \( n = 2m \), then, by grouping 1-dimensional \( h_i \) into pairs, one can make all \( h_i \in H^2(X;\mathbb{Z}) \), \( i = 1, \ldots, m \), and if \( n = 2m + 1 \) all but one among \( h_i \) can be brought to \( H^2(X;\mathbb{Z}) \).

Moreover, the a priori different 2-dimensional classes \( h_i \), can be replaced by a single one, namely by a generic linear combination \( h \) of \( h_i \), since \( \omega_i \cdot h_i = k \cdot h^{m_i} \).

It follows that \( X \) of dimension \( n = 2m \) is oversymplectic if and only if it admits a map of non-zero degree to the complex projective space \( \mathbb{C}P^m \), where the condition \([\theta 0]\) says in effect that the pull back of the symplectic (K"ahler) 2-form on \( \mathbb{C}P^m \) to the universal covering \( \tilde{X} \) of \( X \) is exact.

And if \( n = 2m + 1 \) is odd, there is such a map \( X \times S^1 \rightarrow \mathbb{C}P^m \).

Observe that \([\theta 0]\)-oversymplecticity, similarly to overtoricity and to iso-enlargeability of manifolds \( X \) is inherited by \( X' \) which admit maps \( X' \rightarrow X \) of non-zero degrees and also by the products \( X' = X \times \mathbb{T}^k \).

Still, \([\theta 0]\)-oversymplecticity seems significantly different from iso-enlargeability, and, probably, there are many examples of \([\theta 0]\)- \([\theta 0]\)-oversymplectic manifolds, even among projective algebraic ones, which are not (iso)enlargeable.

The reason we brought forth this oversymplecticity is the following proposition.

\((\star \theta 0)\) *If \( X \) is \([\theta 0]\)-oversymplectic, then it admits no metric with \( Sc > 0 \), provided the universal covering \( \tilde{X} \) is spin.*

(This, as it was mentioned earlier, implies that the only possibility for \( Sc(X) \geq 0 \) is \( X \) being flat.

Also recall that vanishing of the second homotopy group \( \pi_2(X) \) implies that \( \tilde{X} \) is spin and observe that \( \pi_2(X) = 0 \) also implies \([\theta 0]\).)

*Proof of \((\star)\).* Let \( n = 2m \) and \( \tilde{l} \) be the lift of the canonical line bundle of \( \mathbb{C}P^m \) to \( \tilde{X} \). Because of \([\theta 0]\), this bundle is trivial there are the \( p \)-th order roots \( \sqrt[p]{\tilde{l}} \) for all \( p = 1, 2, \ldots \), which are represented by the \( p \)-sheeted coverings of the total space of the circle bundles associated to \( \tilde{l} \).

\(^{28}\) \( \tilde{X} \) is spin if and only if the restrictions of the tangent bundle \( T(X) \) to all 2-spheres in \( X \) are trivial; if \( n \geq 5 \) this is the same as triviality of the normal bundles of embedded 2-spheres in \( X \).
And albeit the Galois’ actions of the fundamental group $\Gamma = \pi_1(X)$ on $\bar{X}$ and on $\bar{t}$ does not extend to $\sqrt{\bar{t}}$, the semidirect product $\mathbb{Z}_p \times \Gamma$ does act on $\sqrt{\bar{t}}$.

Since $\bar{X}$ is spin, the twisted Dirac operator $D_{\bar{t}} \sqrt{\bar{t}}$, i.e. $D$ with coefficients in $\sqrt{\bar{t}}$, is defined and the corresponding space of harmonic $L_2$-spinors is acted upon by the group $\mathbb{Z}_p \times \mathbb{Z}_2 \times \Gamma$.

Then an elementary computation shows that the topological index $D_{\bar{t}} \sqrt{\bar{t}}$ does not vanish for infinitely many $p$ and then, by the Atiyah $L_2$-index theorem, $D_{\bar{t}} \sqrt{\bar{t}}$-harmonic $L_2$-spinors exist for arbitrarily large $p$.

But since the curvatures of the bundles $\sqrt{\bar{t}}$ tend to 0 for $p \to \infty$, uniform positivity of the scalar curvature of $\bar{X}$ would not allow such spinors for large $p$ according to the twisted Schroedinger- Lichnerowicz-Weitzenboeck vanishing theorem. QED.

11 Continuation of Discussion. On the surface of things, $(\star \tilde{t} 0)$ generalizes Schoen-Yau theorem on non-existence of metrics with $Sc > 0$ on torotical manifolds, but...

(1) Here again there is an annoying spin condition in the statement of $(\star \tilde{t} 0)$, which, for all we know must be unnecessary.

(2) More seriously, we can say preciously little about incomplete manifolds. For instance,

one can’t bound with the present day techniques the width of product bands $(Y \times [-1, 1], g)$ with metrics $g$ which have $Sc(g) \geq \sigma > 0$ for $[\tilde{t} 0]$-oversymplectic manifolds $Y$.

(The same can be said about all other non-$\Sigma Y \Sigma E$-manifolds $Y$ which are known not to admit metrics with $Sc > 0$).

Because of this,

one is unable to rule out complete metrics with $Sc > 0$ on $Y \times \mathbb{R}$ and complete metrics with $Sc \geq \sigma > 0$ on $X \times \mathbb{R}^2$ for $[\tilde{t} 0]$-oversymplectic manifolds $Y$.

What is not hard to show, however, is the following

$(\star \times \mathbb{R})$ Products $X = Y \times \mathbb{R}$ carry no complete metrics $g$ with $Sc(g) \geq \sigma > 0$ for all $[\tilde{t} 0]$-oversymplectic manifolds $Y$ the universal coverings of which are spin.

Sketch of the Proof. Since $X = (X, g)$ is complete and two-ended, it admits a proper 1-Lipschitz function onto $\mathbb{R}$, which we call it $\phi : X \to \mathbb{R}$.

Let $X' = X \times \mathbb{R}$ and let

$$\Phi_\varepsilon = (\varepsilon \cdot \phi, \varepsilon \cdot \phi') : X' \to \mathbb{R}^2$$

where $\phi' : X' = X \times \mathbb{R} \to \mathbb{R}$ is the coordinate projection.

Let $l'_\varepsilon$ be the $\Phi_\varepsilon$-pullback of $l_0$ to $X'$ and let $l^\circ_\varepsilon$ be the formal difference between $l'_\varepsilon$ and the trivial complex line bundle with the trivial connection.

Let $l_0$ be a complex line bundle over $\mathbb{R}^2$ with a unitary connection, which is isomorphic to the trivial bundle outside a compact subset in $\mathbb{R}^2$ and such that the curvature $\omega_0$ of $l_0$ is $\omega_0 = p_0(t_1, t_2)dt_1 \wedge dt_2$ for a non vanishing function $p_0 \geq 0$.

Let $dim(Y) = 2m$, let $l$ be the line bundle over $X'$ induced by the composed map $X' \to Y \to \mathbb{C}P^m$ from the canonical line bundle and let

$$l^\circ_\varepsilon = l \otimes l^\circ_\varepsilon.$$
Pass to the universal covering $\tilde{X}$ and observe as earlier, that Atiyah’s $L^2$-index theorem, applied to the Dirac operator twisted with $\sqrt{L}$ and combined with Schroedinger- Lichnerowicz-Weitzenboeck vanishing theorem for small $\varepsilon << \sigma$ and for $p \to \infty$, rules out $Sc \geq \sigma > 0$ for complete metrics on $X$. QED

Generalisation to Non-Compact $X$. The above (\#) generalises to complete $[0,1]$-oversymplectic manifolds $X$, where the fundamental class of $X$ in the cohomology with compact supports, denoted $H^*(X, [\infty])$, decomposes into 1- and 2-classes also with compact supports and where these classes must vanish in the cohomology $H^{1,2}(\tilde{X}, [\infty])$. For instance, if $X$ of dimension $2m$ admits a proper map of non-zero degree to a complement of a subset $Z \subset \mathbb{C}P^m$, this condition is satisfied if $H_1(Z) = 0$ and the symplectic form of $\mathbb{C}P^m$ vanishes on $Z$.

12 Min-oo - Goette - Semmelmann Rigidity Theorem. A (very) special case of this theorem (2.10 in [GS 2001]) reads as follows.

Let $X$ be a compact orientable Riemannian manifold of dimension $2m$ and let $f : X \to \mathbb{C}P^m$ be a $C^1$-smooth area non-increasing spin map of non-zero degree where $f$ is called spin if the restriction of the tangent bundle $T(X)$ to $\Sigma \subset X$ is trivial if an only the restriction $T(\mathbb{C}P^m)|_{f(\Sigma)}$ is trivial for all surfaces $\Sigma \subset X$.

For instance, if $m$ is odd and $X$ is spin then all maps $X \to \mathbb{C}P^m$ are spin.

If
\[
Sc(X)(x) \geq Sc(\mathbb{C}P^m)(f(x)) \quad \text{for all } x \in X,
\]
then $f$ is an isometry.

About the Proof. The $R$-term in the Schroedinger-Lichnerowicz-Weitzenboeck formula (5)) for $D$ twisted with line bundles $l$ shows (see [Hit 1974]) that if the curvature form $\omega$ of an $l$ (where the cohomology class of $2\pi \omega$ equals the Chern class $c_1(l)$) on a Riemannian manifold of dimension $2m$ diagonalises as
\[
\sum_{i=1, \ldots, m} \lambda_i e_{2i-1} \land e_{2i}
\]
for an orthonormal frame $e_1, e_2, \ldots, e_{2m}$, then
\[
||R|| \leq 4 \sum \lambda_i.
\]

If $l$ equals the (anti)canonical bundle $l_0 = \wedge^m T(\mathbb{C}P^m)$ then, its curvature form for the Levi- Civita connection of the Fubini Studi metric $g_0$ has
\[
\lambda_1 = \lambda_2 = \ldots = \lambda_m = m + 1
\]
and $g_0 = m(m + 1)$.

On the other hand, an easy homological computation shows that the topological index $I(D, l_0)$ does not vanish on $\mathbb{C}P^m$ and since $\deg(f) \neq 0$ it doesn’t vanish on $X$ either. This shows that $f$ can’t be strictly area decreasing, while the equality case needs an additional argument (see [GS 2001]).

The above applies, strictly speaking, to odd $m$, where $\mathbb{C}P^m$ is spin, and if $m$ is even, one twists $D$ with the virtual square root of $l_0$ (see [Hit 1974], [Min-Oo 1995], [GS 2001]).

\[\text{This } [\infty] \text{ stands for the complement to a (large) non-specified compact subset in } X.\]
(13) (Interpolating between \((
abla \uparrow 0)\) with \((\otimes)\) Unlike the (obvious) implication \(\bigcirc \Rightarrow \Box\) the (sharp) theorem \((\otimes)\) by no means implies (rough) \((\nabla \uparrow 0)\).

But an obvious combination of the proofs of these theorems brings the two together as follows.

Let \(X\) be a complete oriented Riemannian \(2m\)-manifold and \(f : X \to \mathbb{C}P^m \setminus Z\) be a proper \(C^1\)-smooth area non-increasing map of non-zero degree, where \(Z \subset \mathbb{C}P^m\) a smooth submanifold on which the symplectic form of \(\mathbb{C}P^m\) vanishes and which has \(H_1(Z) = 0\).

Let the composed map \(\tilde{X} \to X \to \mathbb{C}P^m \setminus Z \subset \mathbb{C}P^m\) from the universal covering of \(X\) to \(\mathbb{C}P^m\), call it \(\tilde{f} : \tilde{X} \to \mathbb{C}P^m\), be spin.

\((\otimes \uparrow 1_p)\) If the \(\tilde{f}\)-pullback of the generator \(c \in H^2(\mathbb{C}P^m;\mathbb{Z})\), that is \(\tilde{f}^*(c) \in H^2(\tilde{X};\mathbb{Z})\), is divisible by a positive integer \(p\), then

\[
\inf_x Sc(X)(x) < \frac{1}{p} Sc(\mathbb{C}P^m),
\]

unless \(X\) is compact, \(Z\) is empty, \(p = 1\) and \(f\) is an isometry.

One can only wonder if there is anything of this kind that may come from minimal hypersurfaces.

11 Appendix

In this section, following the suggestions by the referee, we explain in a greater detail the following.

(a) Smoothing hypersurfaces with no decrease of their mean curvatures.

(b) Smoothing Riemannian metrics with with no decrease of their scalar curvatures.

In the case (a) the principal step of smoothing consists of "rounding corners" of piecewise smooth hypersurfaces which makes our hypersurfaces \(C^1\)-smooth.

In the case (b) one \(C^1\)-smooths continuous piecewise smooth Riemannian metrics by similarly "rounding them by bending" along their singular loci.

Both rounding constructions, however simple, depend on specific geometric properties of the mean curvature and the scalar curvature correspondingly.

Then, in both cases, the final step of smoothing \(C^1 \leadsto C^\infty\) follows by homotopy extension construction for solutions of general differential inequalities which is explained in section 11.1 below.

Next, we

(c) elucidate some properties of on minimal hypersurfaces in open manifolds needed for the width inequalities.

Finally, as it was suggested by the referee, we

(d) summarise topological obstruction for \(Sc > 0\) on closed manifolds which follow from our inequalities

and

(e) highlight several conjectures mentioned in the main body of the article.
11.1 Universal Constructions of Smoothing and Bending

A. Linear Smoothing Operators. The most common kind of smoothing in linear analysis is achieved by applying convolution-like operators to objects you want to smooth.

For instance, let $X$ be a Riemannian manifold and $Y \subset X$ be a compact $C^1$-smooth cooriented hypersurface. Let $U \ni Y$ be a small $C^\infty$-split neighbourhood of $Y$, say

$$U = Y \times (-\delta, \delta),$$

where $Y$ is represented by a graph of $C^1$-smooth function $f(y)$ and let $Y_\varepsilon$, $\varepsilon > 0$ be the graphs of the $\varepsilon$-smoothed functions $f_\varepsilon(y)$, for $f(y)/\text{uni} \overset{\int}{\to} f_\varepsilon(y)$, for

$$f(y) \mapsto f_\varepsilon(y) = \int_Y K_\varepsilon(y, y') f(y') dy'.$$

Then, for the usual $K_\varepsilon$, $Y_\varepsilon \rightarrow C^1 Y$ for $\varepsilon \rightarrow 0$ and, since the mean curvature of $Y$ is linearly expressible in terms of the second derivatives of $f$, the mean curvatures of $Y_\varepsilon$ satisfy almost the same bounds as those of $Y$, whenever the latter are defined.

For instance, if $Y$ is piecewise $C^2$, or more generally if the above ($C^1$-smooth) function $f$ is $C^{1,1}$, i.e. $df$ is Lipschitz, and if

$$\text{mn.curv}(Y)(y) \geq \phi(y)$$

for a continuous function $\phi$ on $U \ni Y$ and almost all $y \in Y$, then

$$\text{mn.curv}(Y_\varepsilon)(y_\varepsilon) \geq \phi(y_\varepsilon) + o(1), \varepsilon \rightarrow 0,$$

for all $y_\varepsilon \in Y_\varepsilon$. (A slightly different format of this smoothing is suggested on pp. 939 and 949 in section 3.4 and 5.7 in [Gr 2014].)

Similarly, $C^{1,1}$-smooth Riemannian metrics $g$ on a manifold $X$ can be $C^1$-approximated by $C^\infty$-smooth $g_\varepsilon$ such that if $Sc(g)(x) \geq \phi(x)$, then

$$Sc(g_\varepsilon) \geq \phi(x) + o(1),$$

because the operator $g \mapsto Sc(g)$ is linear in the second derivatives of $g$.

B. Smoothing by Local Bending. Smoothing a function $f$ on $V$, where for instance, the second derivatives jump across a double sided hypersurface $\Sigma \subset V$, can be achieved by deforming, we call it bending, $f$ on one side of $V$, say to the "left" of $\Sigma$, such that the derivatives on the left side become equal to the derivatives on the right other side of $\sigma$ at all points $v \in \Sigma$.

Linearity of the differential inequality we want to keep preserved by such bending, e.g. of $\text{mn.curv} > \phi$ or $Sc > \phi$, is not indispensable. What is essential for $C^1 \rightarrow C^\infty$ smoothing is the connectivity rather than convexity of the subsets in the sets of values of derivatives of functions and/or of metrics defined by the required inequalities.

Let us formulate the relevant general bending property of solutions of such inequalities in terms of "cut-offs of deformations", where "connectivity", is hidden the concept of "deformation/homotopy".
Let $Z \to V$ be a smooth fibration and let $Z^{[r]}$ be that space of the $r$-jets of germs of $C^r$-smooth sections $f: V \to Z$.

Let $J^r_f: V \to Z^{[r]}$ denote the $r$-th jet of $f$ and recall that by the definition of jets,

$$J^r_f(v) = J^r_{f_1}(v) \text{ if and only the values of the sections } f_1 \text{ and } f_2 \text{ as well as of all their partial derivative of orders } 1,2,...,r, \text{ in some local coordinates, are equal at } v.$$

In fact, this property defines jets as well as the spaces $Z^{[r]}$.

Let $\Sigma \subset V$ be a piecewise smooth subset,\(^30\) let $U \ni \Sigma$ be a neighbourhood of $\Sigma$ in $V$ and let $\mathcal{R} \subset Z^{[r]}$ be an open subset.

\textbf{★ Cut-off Homotopy Lemma.} Let $f_t: V \to Z$, $t \in [0,1]$, be a $C^r$-continuous family of smooth sections, such that

(i) $J^r_{f_t}(V) \subset \mathcal{R}$ for all $t \in [0,1]$ and

(ii) $J^r_{f_t}(v)$ is constant in $t$ for all $v \in \Sigma$.

Then there exists a smaller neighbourhood $\tilde{U} \subset U$ of $\Sigma$ and another $C^r$-continuous family of smooth sections $f_t: V \to Z$, such that, similarly to $f_t$,

$$J^r_{f_t}(V) \subset \mathcal{R} \text{ for all } t \in [0,1]$$

and

$f_t$ is equal to $f_t$ on $\tilde{U}$

while at the same time

$f_t$ is constant in $t$ outside $U$,

i.e. $f_t(v) = f_0(v)$ for all $t$ and all $v \in V \setminus U$.

Moreover, if $f_t$ was constant in the neighbourhood of a closed subset $V_0 \subset V$ then $f_t$ can be taken constant in $t$ on $V_0$.

\textit{Remark.} The general case of the lemma easily reduces to that where $V$ is compact and $\Sigma$ is a smooth submanifold of codimension one.

\textbf{Warning and Perturbative Generalisation.} The conclusion of ★ by no means holds true in general without assumption (ii). However,

"constant" in (ii) can be replaced by "almost constant" as follows.

\textbf{★′} Let $f_{t,\theta}, t, \theta \in [0,1]$ be a two parameter $C^r$-continuous family of sections $V \to Z$ where $f_{t,0}$ satisfies (ii). Then there exists an $\varepsilon_0 > 0$, such that the conclusion of ★ holds for $f_{t,\theta}$ for all $\theta \leq \varepsilon_0$.

This follows from ★ and from what is called microflexibility of differential inequalities defined by open subsets in the jet spaces, which is, of course, fully trivial.

(More interestingly, there are classes of flexible maps, e.g. smooth immersions $V^n \to \mathbb{R}^{n+1}$, which are defined with certain $\mathcal{R}$, where extension of homotopies $f_t$ (called regular homotopies for immersions) is possible for all $f_t$. But the proofs of this in interesting cases don’t, unlike ★ and ★′, reduce to generalities but depend on specific constructions adapted to specific properties of particular $\mathcal{R}$. See [Gr 1986] and references therein.)

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\(^30\)Probably, what follows holds true for all closed subsets $\Sigma \subset V$.

\(^31\)This is a reformulation of the weak flexibility lemma given as an exercise on p. 111 in [Gr 1986].
1-D Example. Let \( V = [0, \infty) \) and \( Z = [0, \infty) \times \mathbb{R} \to [0, \infty) \) be the trivial fibration. Then sections of \( Z \) correspond to real functions \( f(v), v \geq 0 \),

\[
Z^{[r]} = [0, \infty) \times \mathbb{R}^{r+1}
\]

and the \( r \)-jets are maps

\[
J^{r-1}_f = \left( f, \frac{df}{dv}, \ldots, \frac{d^r f}{dv^r} \right) : [0, \infty) \to \mathbb{R}^{r+1}.
\]

\* Given continuous functions \( a_0(v), a_r(v), b_0(v) > a_0(v), \ldots, b_r(v) > a_r(v) \), a number \( \delta > 0 \) and a real function \( f(v), v \geq 0 \), such that

\[
a_i(v) < \frac{d^i f(v)}{dv^i} < b_i(v) \quad \text{for } i = 0, \ldots, r \text{ and all } v \geq 0,
\]

there exists a function \( \bar{f}(x) \), which also satisfies these inequalities,

\[
a_i(v) < \frac{d^i \bar{f}(v)}{dv^i} < b_i(v) \quad \text{for } i = 0, \ldots, r \text{ and all } v \geq 0,
\]

and such that

\[
\frac{d^r \bar{f}(0)}{dv^r} = c_r \quad \text{and} \quad \bar{f}(v) = f(v) \quad \text{for } v \geq \delta,
\]

where \( c_r \) is a given number in the interval \( a_r(0) < c_r < b_r(0) \).

The essential and essentially obvious case of this example is where \( r = 1 \), \( a_0 = a_1 = 0 \) and \( b_0 = b_1 = \infty \). When this is understood, all of \* becomes obvious as well.\[32\]

1 Mean Curvature Example. Let \( Y \subset X \) be a piecewise smooth \( C^1 \)-hypersurface, where the singular locus is a smooth hypersurface \( \Sigma \subset Y \) (i.e. \( \dim(\Sigma) = \dim(Y) - 1 \)), where the two smooth parts, say \( V_1 \) and \( V_2 \) of \( Y \) meet. This \( Y \) can be obviously \( C^\infty \)-smoothed along \( \Sigma \) by deforming \( V_1 \) and \( V_2 \) near \( \Sigma \) such that they would \( C^\infty \)-match at \( \Sigma = V_1 \cap V_2 \) and with almost no decrease of their mean curvatures.\[33\]

Then \* – here \( r = 2 \) – allows an extension of these deformations/homotopies to all of \( Y = V_1 \cup V_2 \), such that the resulting smoothed hypersurface, say \( \tilde{Y} = \tilde{Y}_\varepsilon \), for given positive continuous function \( \varepsilon = \varepsilon(x) > 0 \) on \( X \), satisfies

- The \( C^1 \)-distance between \( \tilde{Y}_\varepsilon \) and \( Y \) is \( \leq \varepsilon \).
- \( \tilde{Y}_\varepsilon \) coincides with \( Y \) outside the \( \varepsilon \)-neighbourhood of \( \Sigma \).
- The mean curvatures of \( \tilde{Y}_\varepsilon \), satisfy the same, up to \( \varepsilon \), inequalities as the mean curvatures of \( Y \).

In particular, if \( \text{nn.curv}(Y)(y) \geq \phi(y) \) for a continuous function \( \phi \) on \( X \supset Y \), then \( \text{nn.curv}(\tilde{Y}_\varepsilon)(\tilde{y}) \geq \phi(\tilde{y}) + \varepsilon(\tilde{y}) \).

Similarly one can smooth more general piecewise smooth \( C^1 \)-hypersurfaces and also piecewise smooth \( C^1 \)-Riemannian metrics with negligible decrease of their scalar curvatures.

\[32\] This "obvious" presupposes familiarity with the basic geometry of the jet spaces.

\[33\] This deformation at a point \( \sigma \in \Sigma = V_1 \cap V_2 \) does not \( C^2 \)-significantly move a neighbourhood \( U_1 \subset V_1 \) of \( \sigma \in V_1 \), unless \( \text{nn.curv}(V_1)(\sigma) < \text{nn.curv}(V_2)(\sigma) \) and the same applies to \( V_2 \).
11.2 $\varepsilon$-Redistribution of Curvature

In smoothing and bending constructions it is easier deal with with strict inequalities, such as $Sc > 0$, rather than with non strict ones, such as $Sc \geq 0$.

Below are two simple (and, probably, known) propositions which allows one to relax "partially strict" inequalities.

**Redistribution of the Mean Curvature.** Let $X$ be a $C^\infty$-smooth Riemannian $n$-manifold and $V \subset X$ a domain with cosimplicial corners, i.e. each point at the boundary of $V$ admits a neighbourhood in $V$ which is diffeomorphic to a neighbourhood in the positive "octant" $\mathbb{R}^n_+ \subset \mathbb{R}^n$.

Let $\partial_i \subset \partial = \partial V$ denote the $(n-1)$-faces of $V$ and $\partial_{ij}$ be the $(n-2)$-faces which we call edges. Let $\phi_i$ and $\psi_{ij}$ be smooth functions on $X$, such that

(i) the mean curvatures of the $(n-1)$-faces of $V$ satisfy

$$\text{mn.curv}(\partial_i)(x) \geq \phi_i(x),$$

for all $\partial_i$ and all $x \in \partial_i$;

(ii) the dihedral angles between the $(n-1)$-faces $\partial_i, \partial_j \subset \partial V$, satisfy

$$\angle_x(\partial_i, \partial_j) \leq \psi_{ij}(x)$$

for all (non-empty) edges $\partial_{ij} = \partial_i \cap \partial_j$ and all $x \in \partial_{ij}$.

$(\star_>)$ If $V$ is compact and the boundary $\partial V$ of $V$ is connected, then either

$$\text{mn.curv}(\partial_i)(x) = \phi_i(x) \quad \text{and} \quad \angle_x(\partial_i, \partial_j) = \psi_{ij}(x)$$

for all points $x \in \partial V$ (where these equalities make sense),

or there exists an arbitrarily small $C^\infty$-perturbation $V'$ of $V$ (by a $C^\infty$-diffeomorphism close to the identity), such that

$$\text{mn.curv}(\partial_i')(x) > \phi_i(x) \quad \text{and} \quad \angle_x(\partial_i', \partial_j') < \psi_{ij}(x)$$

for all $\partial_i' \subset \partial V'$ and $\partial_{ij}' = \partial_i' \cap \partial_j'$ and all $x \in \partial_i'$ and $x \in \partial_{ij}'$ correspondingly.

**Sketches of Three Different Proofs.** (1) Fredholm+Unique Continuation.

To get the idea, let $Y = \partial V$ be smooth and let $\phi_0(x)$ be a smooth function on $X$ which extends the function $y \mapsto \text{mn.curv}(\partial V)(y)$ from $Y = \partial V$ to $X$. Let $U_0 \subset X$ be a neighbourhood of a point $y_0 \in Y$.

If a smooth function $\phi_0'$ is sufficiently $C^\infty$-close to $\phi_0$, then there exists

$(\star_-)$ a $C^\infty$-perturbation $Y'$ of the hypersurface $Y = \partial V$, such that

$$\text{mn.curv}(Y')(x) = \phi_0'(x)$$

for all $x \in Y' \setminus U_0$.

This follows by the implicit function theorem for the operator $Y \mapsto \text{mn.curv}(Y)$, since

- the linearisation $L = L_{\mathcal{M},Y}$ of $\mathcal{M}$ at $Y$, being Fredholm, has finite codimensional image;

- the adjoint operator of $L$ (which happens to be equal to $L$) has the unique continuation property for connected hypersurfaces $Y$.

\[34\)This property (obviously) fails to be true if $\partial V$ is disconnected and $(\star)$ doesn’t have to hold anymore.
This \((\ast_\varepsilon)\) also holds for certain domains where the boundary \(\partial V\) is non-smooth. For instance if \(V\) has no corners, i.e. if there is no triple intersections of faces, \(\partial_i \cap \partial_j \cap \partial_k\), then a version of \((\ast_\varepsilon)\), which is significantly stronger than \((\ast_{\varepsilon,1})\), follows by by perturbing the faces \(\partial_i\) one by one.

But if the linearized boundary value problem loses regularity at the corners (this, probably, doesn’t happen if all dihedral angles \(\angle(\partial_i, \partial_j)\) are \(90^\circ\)), then it becomes unclear if \((\ast_\varepsilon)\) remains true.

However, \((\ast_{\varepsilon,1})\) is taken care of by the following.

**Local Mnc-Lemma.**\(^{35}\) Let \(Y\) be a smooth hypersurface in a Riemannian manifold \(X\) of dimension \(n\).

Then there exists a continuous function \(\varepsilon = \varepsilon_{X,Y}(y) > 0\), on \(Y\), which is also continuous with respect to the \(C^\infty\)-topology in the space of hypersurfaces \(Y \subset X\) with the following property.

Let \(S_y(\varepsilon) = S_y^{n-2}(\varepsilon) \subset Y\) be the \(\varepsilon\)-sphere around a point \(y \in Y\) for some positive \(\varepsilon \leq \varepsilon\) and let \(\delta > 0\) be a positive number.

Then there exists a diffeomorphism \(\phi : Y \rightarrow X\), such that

\[\ast_{\varepsilon}\phi\] is \(\delta\)-close to the identity diffeomorphism \(id : Y \rightarrow Y \subset X\) in the \(C^2\)-topology;

\[\ast_{\varepsilon,1}\] the diffeomorphism \(\phi\) is equal to the identity outside a narrow band around the sphere \(S_y(\varepsilon)\),

\[\phi(y) = y,\]

unless

\[v \in B_y(\varepsilon) \setminus (S_y(\varepsilon) \cup B_y(\varepsilon'))\], where \(\varepsilon' = \varepsilon \left(1 - \frac{1}{10^{100}}\right)\),

and where \(B_y(\varepsilon)\) is the ball bounded by \(S_y(\varepsilon)\);

\[\ast_{\varepsilon,2}\] the diffeomorphism \(\phi\) strictly increases the mean curvature of \(Y\) in the interior of \(B_y(\varepsilon)\) close to \(S_y(\varepsilon)\), namely at all points

\[v \in B_y(\varepsilon) \setminus (S_y(\varepsilon) \cup B_y(\varepsilon''))\] for \(\varepsilon'' = \varepsilon \left(1 - \frac{1}{10^{100}}\right)\).

The proof of the lemma is accomplished by applying the initial stage of bending the hypersurface \(Y \setminus B_y(\varepsilon'')\) near its boundary, which is described in the next section and where the existence of the initial bending we need here is fully obvious.

**(2) Spread of Positivity.** The above lemma allows an extension of the strict inequality \(\text{min.curv}(Y)(y) > \psi(y)\) from (controllably small) balls of radii \(\varepsilon'\) in hypersurfaces \(Y \subset X\) to larger balls of radii

\[\varepsilon = \varepsilon' \left(1 - \frac{1}{10^{100}}\right)^{-1}\]

and, consequently, from arbitrary open subsets \(U' \subset Y\) to larger \(U \subset Y\), without moving the complements \(Y \setminus U\).

**Localization Corollary.** The local lemma allows perturbations \(Y'\) required by \((\ast_{\varepsilon,1})\) to be localised in a given domain \(U \subset Y\), which, in turn, yields \((\ast_{\varepsilon,2})\) for non-compact \(Y\).

\(^{35}\)Albeit 100% elementary, this lemma heavily relies on the specifically Riemannian/Pythagorean nature of our problem.
(3) Variational Proof of ($\ast \ast$). One can also construct a perturbation of $\partial = \partial V$ with a required control over $\text{mn.curv}(\partial)$, say in the smooth (no edges) case, by minimizing the functional 

$$V \mapsto \text{vol}_{n-1}(\partial V) - \int_V \varphi'(x)dx$$

for a suitably chosen function $\varphi'(x)$.

To see what such a $\varphi'(x)$ should be, let $\mu(x)$ be a smooth extension of the mean curvature function from $\partial$ to $X$ and let $\delta(x)$ be the signed distance function to $\partial$, i.e. $\delta(x) = \text{dist}(x, \partial)$ for $x \in V$ and $\delta(x) = -\text{dist}(x, \partial)$ for $x \in X \setminus V$.

Observe that the original $V$ locally strictly and stably minimizes the functional

$$V \mapsto \text{vol}_{n-1}(\partial V) - \int_V \varphi(x)dx \text{ for } \varphi(x) = \lambda \delta(x) - \mu(x)$$

where $\lambda = \lambda(X, \partial)$ is a sufficiently large constant, namely $\lambda \gg \sup_{\partial} \text{curv}^2(\partial) + \sup_X |\text{Ricci}(X)|$, see section 10.2 in [Gr 2012].

Thus, the functional $V \mapsto \text{vol}_{n-1}(\partial V) - \int_V \phi'(x)$ has a unique local minimum $V'$ whenever $\varphi'$ is sufficiently close to the above $\varphi$, and where, observe,

$$\text{mn.curv}(\partial V')(x) = \varphi'(x) \text{ for all } x \in \partial V'.$$

Then it is not hard to arrange such a $\varphi'$ that would make the mean curvature of $V$ increase outside $U_0$ (compare section 11.9).

Redistribution of the Scalar Curvature. Let, besides the above functions $\phi_i$ and $\psi_{ij}$ on $X$, we are given a continuous function $\sigma(x)$ such that the scalar curvature of the Riemannian metric $g$ in $X$ satisfies

$$\text{Sc}(g)(x) \geq \sigma(x) \text{ for all } x \in X.$$  

If $V$ is connected (non-compact is allowed) then either

$$\text{Sc}(g)(x) = \sigma(x) \text{ for all } x \in V, \text{mn.curv}(\partial_i)(x) = \phi_i(x), \text{ and } \angle_x(\partial_i, \partial_j) = \psi_{ij}(x),$$

where the latter two equalities hold for all points $x \in \partial V$, where they make sense.

Moreover,

one can keep $g' = g$ on a given closed subset in $X$ on which $\text{Sc}(g)(x) > \sigma(x)$.

Sketches of two Proofs. [1] If $V$ is compact with smooth boundary, the (linearization of the) operator $f \mapsto \text{Sc}(f^2g)$, $f > 0$ is Fredholm with the unique continuation property and the above argument via linearization applies.

[2] The initial stage of what is called "intrinsic bending" in section 11.5 yields the following simple proposition that fully accomplishes our purpose. (As in the mean curvature case, the existence of initial intrinsic bending is obvious.)

Local Sc-Lemma. Let $X = (X, g)$ be a smooth $n$-dimensional Riemannian manifold. Then there exists a continuous function $\varepsilon = \varepsilon_g(x) > 0$ on $X$, which is also continuous with respect to the $C^\infty$-topology in the space of Riemannian metrics $g$ on $X$, with the following property.
Let $S_\epsilon(x) = S^n_\epsilon(x) \subset X$ be the $\epsilon$-sphere around a point $x \in X$ for some positive $\epsilon \leq \delta$ and let $\delta > 0$ be a positive number.

Then there exists a smooth Riemannian metric, $g'$ on $X$, such that

- $g'$ is $\delta$-close to $g$ in the $C^3$-topology;
- $g'$ is equal to $g$ in a narrow band around the sphere $S_\epsilon(x)$.

unless

\[ x \in B_\epsilon(x) \setminus (S_\epsilon(x) \cup B_\epsilon(x')), \text{ where } \epsilon' = \epsilon \left(1 - \frac{1}{10^{10}}\right), \]

and where $B_\epsilon(x)$ is the ball bounded by $S_\epsilon(x)$;

- the scalar curvature of $g'$ is strictly greater than that of $g$ in the interior of $B_\epsilon(x)$ close to $S_\epsilon(x)$, namely at all points

\[ v \in B_\epsilon(x) \setminus (S_\epsilon(x) \cup B_\epsilon(x'')) \text{ for } \epsilon'' = \epsilon \left(1 - \frac{1}{10^{10}}\right). \]

11.3 Rounding and Smoothing Hypersurfaces with no Decrease of their Mean Curvatures.

Let $X = X^n$ be a $C^\infty$-smooth Riemannian manifold of dimension $n$ e.g. $X = \mathbb{R}^n$, and let $Y = Y^{n-1} \subset X$ be a cooriented hypersurface which is $Y$ is locally $C^\infty$-diffeomorphic to a convex polyhedral hypersurface in $\mathbb{R}^n$.

In other words, $Y$ is piecewise $C^\infty$-smooth with all dihedral angles between the tangent spaces of the smooth regions $Y_i \subset Y$ at their meeting points in the singular locus of $Y$ being strictly less than $\pi$.

\[ \angle_{i,j} = \angle(T_y(Y_i), T_y(Y_j)) < \pi. \]

For instance, the boundaries $Y$ of finite intersections of domains $U_i \subset X$ with smooth boundaries which all intersect transversally are of this kind.

Let us agree that the mean curvatures of cooriented hypersurfaces are evaluated with the outward looking normal vectors, where this sign convention makes mean curvatures of boundaries of convex domain positive.

- $[\varepsilon]-$Rounding.

Move $Y$ inward equidistantly by $\varepsilon$ and then by the same $\varepsilon$ outward.

If $Y$ is a compact closed hypersurface and $\varepsilon > 0$ is sufficiently small, then the resulting hypersurface, call it $Y \pm \varepsilon$, is $C^1$-smooth and piecewise $C^\infty$-smooth.

To see this clearly, let $Y_{-\varepsilon}$ be the inward $\varepsilon$-equidistant hypersurface to $Y$, which, in the case $Y = \partial U$, is equal to the boundary of the $\varepsilon$-neighbourhood of the complement $X \setminus U$.

Observe that if $\varepsilon$ is small, than

$Y_{-\varepsilon}$ has the same corner pattern as $Y$.

Now the piecewise structure of $Y \pm \varepsilon$, that is the outward $\varepsilon$-equidistant to $Y_{-\varepsilon}$, can be seen with the normal (nearest point) projection $Y_{+\varepsilon} \to Y_{-\varepsilon}$, call it $p_{-\varepsilon}: Y \pm \varepsilon \to Y_{-\varepsilon}$, where each $y \in Y_{+\varepsilon}$ is sent by $p_{-\varepsilon}$ to the unique ($\varepsilon$ is small!) nearest point in $Y_{-\varepsilon}$.
the smooth pieces of \( Y_{\varepsilon} \) are the \( p_{-1} \)-pullbacks of the \((k-1)\)-codimensional "faces" \( y_{-1}^{n-k} \subset Y_{-1} \), \( k = 1, 2, ..., n \).

For instance, if \( Y \) is the boundary of the intersection of smooth domains with transversally meeting boundaries, then

these faces correspond to meeting points of \( k \)-tuples of such boundaries.

Observe that the subset \( Y_{\varepsilon}^{n-1} = p_{-1}^{-1}(Y_{-1}^{n-1}) \subset Y_{\varepsilon} \) satisfies

\[
Y_{\varepsilon}^{n-1} = Y \cap Y_{\varepsilon}
\]

and that it is also equal to the set of points \( y \in Y \), such that \( \text{dist}(y, \text{sing}(Y_{\varepsilon})) > \varepsilon \), where \( \text{sing}(Y_{\varepsilon}) \) is the set of points where \( Y \) is non-smooth, i.e., union of what we call the edges or \((n-2)\)-faces of \( Y_{\varepsilon} \).

Also observe that that the mean curvatures of the \( C^2 \)-smooth pieces \( Y_{\varepsilon}^{n-k} = p_{-1}^{-1}(Y_{-1}^{n-k}) \) of \( Y_{\varepsilon}^{n-k} \) for \( k \geq 2 \) are large positive,

\[
\text{mn.curv}(Y_{\varepsilon}^{n-k})(y) \geq C_k \text{dist}(y, \text{sing}(Y_{\varepsilon}^{n-k})) + O(1) \quad \text{for } k \geq 2 \text{ and } \varepsilon \to 0.
\]

Thus, the normal (nearest point) projection \( p_{\varepsilon} : Y \to Y_{\varepsilon} \), which is defined for small \( \varepsilon \geq 0 \), is mean curvature non-decreasing,

\[
\text{mn.curv}(Y_{\varepsilon})(p_{\varepsilon}(y)) \geq \text{mn.curv}(Y)(y)
\]

for all \( y \in Y \) and small \( \varepsilon > 0 \).

**From \( C^1 \) to \( C^\infty \).**

According to \( \star \) from section 11.1, the \( C^1 \)-hypersurfaces \( Y_{\varepsilon} \) can be \( C^1 \)-approximated by \( C^\infty \)-smooth ones, call them \( Y'_{\varepsilon} \), such that

* \( Y'_{\varepsilon} \) coincide with \( Y_{\varepsilon} \) outside the \( \varepsilon' \)-neighbourhood of the singular locus of \( Y_{\varepsilon} \) (where \( C^\infty \)-pieces of \( Y_{\varepsilon} \) meet) where \( 0 < \varepsilon' << \varepsilon \) can be taken arbitrarily small.

* The normal (nearest point) projection \( p'_{\varepsilon} : Y \to Y'_{\varepsilon} \) is defined for small \( \varepsilon \) and it moves \( Y \) inward.

* The mean curvature is almost non-decreasing under this projection,

\[
\text{mn.curv}(Y'_{\varepsilon})(p'_{\varepsilon}(y)) \geq \text{mn.curv}(Y)(y) + O(\varepsilon').
\]

Finally, one can, if one wishes, \( C^\infty \)-approximate \( Y'_{\varepsilon} \) by \( Y'' \), where mean curvatures \( \geq \) than those at (suitably) corresponding points of the original \( Y \) and where, moreover, \( \text{mn.curv}(Y''(y)) > \text{mn.curv}(Y) \), unless (a connected component of) \( Y \) was smooth to start with.

For instance, if the mean curvature of \( Y \) were \( \geq 0 \) at the regular points of \( Y \) then one can obtain a smooth approximation \( Y'' \) of \( Y \) also with \( \text{mn.curv} \geq 0 \).

In fact, with a little care, (arguing as in compare 11.6) one can arrange our \( C^\infty \)-smooth \( Y'_{\varepsilon} \) itself, such that

\[
\text{mn.curv}(Y'_{\varepsilon})(p'_{\varepsilon}(y)) \geq \text{mn.curv}(Y)(y),
\]

but this is not essential for the present paper.
Smoothing non-compact $Y$.

If $Y$ is a non-compact hypersurface, then instead of small constant $\varepsilon$ one takes a small and fast decaying function $\varepsilon = \varepsilon(y) > 0$.

A direct construction of satisfactory $Y_{\varepsilon}$ with variable $\varepsilon$, however trivial, is cumbersome. A better approach is via a local version of [$\varepsilon_{\tau}$]-rounding by bending procedure described below.

**Bending Hypersurfaces Near their Boundaries**

Smoothing the edge, where two smooth hypersurfaces $Y_1$ and $Y_2$ in $X$ meet, can be achieved by **inward bending** of one of them say of $Y_1$ near its boundary $\partial Y_1 = Y_1 \cap Y_2$, such that

- the bending doesn’t decrease the mean curvature of $Y_1$,
- the bending increases the dihedral angle from the original $\angle (Y_1, Y_2) < \pi$ to $\angle (Y_1, Y_2) = \pi$,

where $\varepsilon > 0$, which can be chosen arbitrarily small, signifies that

- the bent hypersurface $Y_1\varepsilon$ coincides with $Y_1$ within distance $\geq \varepsilon$ from $\partial Y_1$ and
- $Y_1\varepsilon$ is everywhere $\varepsilon$-close to $Y_1$.

The technical advantage of such a bending is that it is easily **localisable**: you need to bend $Y_1$ only at the points you want to.

Namely, let $Y_1, Y_2 \subset X$ be smooth cooriented hypersurfaces meeting at their common boundaries, $\partial Y_1 = \partial Y_2 = Y_1 \cap Y_2$, denote this intersection $Y_{12}$, and let $\alpha : Y_{12} \rightarrow [0, 2\pi]$ be a smooth function, bounded from below by the dihedral angles between $Y_1$ and $Y_2$ at all points in $Y_{12}$,

$$\alpha(y) \geq \angle (Y_1, Y_2), \ y \in Y_{12}.$$

Then, for all $\varepsilon > 0$, there exists a smooth embedding $\phi = \phi_\varepsilon : Y_1 \rightarrow X$ with the following properties.

- $\text{min.\,curv}(\phi(Y_1), y) \geq \text{min.\,curv}(Y_1, y)$ for all $y \in Y_1$;
- $\phi(y) = y$ for all $y \in Y_{12}$;
- $\angle (\phi(Y_1), Y_2) = \alpha(y)$ for all $y \in Y_{12}$;
- the map $\phi$ is $\varepsilon$-close to the original embedding $Y_1 \rightarrow X$ (in the $C^0$-topology);
- the map $\phi$ coincides with the embedding $Y_1 \rightarrow X$ at the points $y \in Y_1$ within distance $\geq \varepsilon$ from the the subset $Y_{12} \subset Y_{12} \subset Y_1$, where $\alpha(y') > \angle (Y_1, Y_2)$.
- The intersection of the image $\phi(Y_1) \subset X$ with $Y_2$ is equal to $Y_{12}$.

**About the Proof.** This easily accomplished by an isotopy of $Y_1$ which, moreover, moves the equidistant hypersurfaces $Y_{12, \varepsilon} \subset Y_1$ (of dimensions $n - 2$) by at most $\varepsilon$ in the $C^\infty$ topology.

**Remarks**.

(a) The condition $\bullet_5$ can be sharpened as follows.

- the (open) subset $Y_{\phi\varepsilon} \subset Y_1$ of the points $y \in Y_1$, where $\phi(y) \neq y$, lies $\varepsilon$-close to $Y_{12}$ and the closure of $Y_{\phi\varepsilon}$ intersects the (closed) subset $Y_{\varepsilon, \varepsilon} \subset Y_{12}$, where $\alpha(y) = \angle (Y_1, Y_2)$, only at the boundary of $Y_{\varepsilon, \varepsilon}$ in $Y_{12}$.

Achieving this, which is unneeded for our applications anyway, requires a little bit of extra effort.

(b) If one doesn’t insist on $\bullet_6$, then one can bend/rotate $Y_1$ by an arbitrary "angle" in the interval $[\angle (Y_1, Y_2), \infty)$ in the spirit of the Frizzing Lemma in [LM 1984].
11.4 Rounding Edges of Riemannian Doubles with no Decrease of their Scalar Curvatures.

Let \( V = (V, g) \) be a smooth Riemannian \( n \)-manifold with boundary and let \( W = V \cup \partial V \V \) be the double of \( V \). This \( W \) carries a natural continuous Riemannian metric, call it \( \tilde{g} = g \& g \), which equals \( g \) on both \( V \)-halves of \( W \).

Let the boundary \( \partial V \) has positive mean curvature and let us explain following [GL 1980] how \( \tilde{g} \) can be \( C^0 \)-approximated by smooth metrics with their scalar curvatures bounded from below by \( Sc(g) \).

\( [\ast_{\varepsilon, \varepsilon}]^D \)-Rounding.

Let \( V_{-\varepsilon} \subset V \) be the complement of the \( \varepsilon \)-neighbourhood of \( \partial V \subset V \) and

\[ W_{\varepsilon} \subset V \times \mathbb{R} \]

be the boundary of the \( \varepsilon \)-neighbourhood of \( V_{-\varepsilon} = V_{-\varepsilon} \times \{0\} \subset V \times \mathbb{R} \).

This \( W_{\varepsilon} \) consists of two \( \varepsilon \)-equidistant copies of \( V_{\varepsilon} \) and of a semicircular part \( W_0 = \partial V \times S^1_\varepsilon \), that is a half of the boundary of the \( \varepsilon \)-neighbourhood of \( \partial V \subset V \times \mathbb{R} \), as depicted in figure 8 on p. 227 in [GL 1980].

If \( V \) is compact and \( \varepsilon \to 0 \), then the principal curvatures \( \lambda_1, \ldots, \lambda_n \) of \( W_0 \) are evaluated in terms of the principal curvatures \( \mu_1, \ldots, \mu_{n-1} \) of the boundary \( \partial V \subset V \) as follows.\(^{36}\)

\[ \lambda_i = (\lambda_i + O(\varepsilon)) \cdot \cos \theta + o(\varepsilon) \text{ for } i = 1, \ldots, n - 1 \text{ and } \lambda_n = \varepsilon^{-1} + O(1), \]

where \( -\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2} \) denotes the angular parameter of the (right) semicircle \( S^1_\varepsilon \).

Then the scalar curvature of \( W_0 \), which is expressed by the Gauss theorem egegrium satisfies

\[ Sc(W_0)(v, \theta) = Sc(V)(v) + (2\varepsilon^{-1} mn(v) + O(1)) \cdot \cos \theta + o(1), \]

where \( mn(v) = mn.curv(\partial V)(v) \), where \( v \in \partial V \) and \( -\frac{\pi}{2} \leq \theta \leq \frac{\pi}{2} \).

Now we bring into play the inequality

\[ mn.curv(\partial(V)) > 0 \]

and see that the scalar curvature of \( W_0 \) is bounded from below by that of \( V \) up to an error \( \to 0 \). And since the part of the hypersurface \( W_\varepsilon \), which is parallel to \( V \) has the same scalar curvature as \( V \), the scalar curvature of \( W_\varepsilon \) is everywhere bounded from below, up to an error \( \to 0 \), by that of \( V \).

From \( C^1 \) to \( C^\infty \).

The submanifold \( W_\varepsilon \subset V \times \mathbb{R} \) has the same type of regularity as \( Y_{\ast \varepsilon} \) from the previous section, namely, it is \( C^1 \) and piecewise \( C^\infty \), and, similarly to \( Y_{\ast \varepsilon} \), it can be \( C^\infty \)-smoothed by applying \( \ast \) from section 11.1 with a negligible decrease of the scalar curvature, where, moreover, this smoothing can be performed equivariantly for the obvious involution of \( W = V \cup \partial V \). (And as in the case of \( Y_{\ast \varepsilon} \).

\(^{36}\)We correct here a minor error from [GL 1980].

\(^{37}\)In fact, \( \lambda_n = \varepsilon^{-1} + o(1) \), but this is unneeded for our present purpose.
Non-Compact Manifolds, $C^0$-Approximation and $C^\infty$-Smoothing.

Similarly to how that was done in the previous section, one extends the above to non-compact manifolds $V$ with a use of small positive functions $\varepsilon(v)$, $v \in \partial V$ instead of constant $\varepsilon$.

Besides controlling scalar curvature of $W_\varepsilon$, we want the metric on $W_\varepsilon$ to be $C^0$-close to $\tilde{g}$ on $W$ for the former brought to the latter by a suitable diffeomorphism $W_\varepsilon \rightarrow W$.

Firstly, such a diffeomorphism is constructed from $W_J$ to the $\varepsilon_\pi^2$-neighbourhood $U \subset W$ of $\partial V \subset W$ with a use of normal decompositions of $W_J$ and $U$ as $\partial V \times [-\varepsilon_\pi^2, \varepsilon_\pi^2]$ and then it is extended to all of $W_\varepsilon$.

11.5 "Intrinsic Bending" of Riemannian Manifolds along the Boundaries with no Decrease of their Scalar Curvatures.

The rounding construction from [GL 1980], which we presented in the previous section, was described in the normal coordinates in [Al 1985] and, a more general form of it appears in [Mia 2002] in [BMN 2010] and in [McFszk 2012].

Let us present a construction of "bending" (Theorem 5 from [BMN 2010]) following [Gr 2014*].

$\mathcal{C}_\varepsilon$-Family. Let $h$ be a smooth Riemannian metric on a manifold $Y$, let $A_{old}, A_{new}$ be smooth quadratic differential forms (i.e. symmetric 2-tensors) on $Y$ and let

$$(++) . \quad h_\varepsilon(t) = h + tA_{new} + \frac{t^2}{2\varepsilon}(A_{old} - A_{new}), \quad 0 \leq t \leq \varepsilon.$$  

Then clearly,

$*$

$0 \quad h_\varepsilon(0) = h$

while

$1 \quad \frac{dh_\varepsilon(0)}{dt} = A_{new}$ and $\frac{dh_\varepsilon(\varepsilon)}{dt} = A_{old}.$

Assume at this point that $Y$ is compact. Then

$*$

$2 \quad$ the metrics $h_\varepsilon(t)$ $C^\infty$-converge to $h$ for $\varepsilon \rightarrow 0$, where this convergence is uniform in $t \in [0, \varepsilon]$. In fact,

$$h_\varepsilon(t) = h + o(\varepsilon).$$

38In fact, the required smoothing can be easily done directly in this case, as it is indicated in [GL 1980], where, in truth – this was pointed out by the referee – it is only claimed that $\inf \text{Sc}(W) \geq \frac{1}{2} \inf \text{Sc}(V)$ and removing "$\frac{1}{2}$" from this inequality without an appeal to 11.1 requires a bit of attention.

39It was pointed out by the referee of the present paper that the smoothing proposition 3.1 in [Mia 2002], due to an extra term in there, doesn’t imply the corresponding edge smoothing results from [GL 1980] and in [Al 1985], and, in the report on the corrected version of this paper, the referee pointed out that what we call "bending" is proven in [BMN 2010].
which means that the $C^r$-distances from $h_\varepsilon(t)$ to $h$ satisfy

$$
\|h_\varepsilon(t) - h\|_{C^r} = o(\varepsilon) \text{ for all } r = 0, 1, 2, \ldots.
$$

In particular, the deformation $h \sim h_\varepsilon(t)$ is almost circular in $t$ for small $\varepsilon$,

$$
h_\varepsilon(\varepsilon) \to h \text{ for } \varepsilon \to 0.
$$

Also,

$$
*3 \quad \frac{d^2 h_\varepsilon(t)}{dt^2} = \frac{1}{\varepsilon} (A_{old} - A_{new}) \text{ for all } (y, t) \in Y \times [0, \varepsilon].
$$

Now, let us incorporate the family $h_\varepsilon(t)$ into family of Riemannian metrics

$$
g_\varepsilon = h_\varepsilon(t) + dt^2
$$
on the manifold $Y \times [0, \varepsilon]$.

Then, clearly,

[i] the second fundamental forms of the two boundary parts $Y \times \{0\}$ and $Y \times \{\varepsilon\}$ in the manifold $Y \times [0, \varepsilon]$ with the metric $g_\varepsilon$ are equal to $A_{new}$ and $A_{old}$ correspondingly, where these forms are evaluated on the (same unit) vector field $\frac{d}{dt}$.

Furthermore, the scalar curvature of this metric satisfies,

[ii]  $Sc(g_\varepsilon)(y, t) = \frac{1}{\varepsilon} \text{trace}(A_{new} - A_{old}) + O(1)$.

Indeed, the Ricci curvature $Ricci_\varepsilon$ of $g_\varepsilon$ at the field $\frac{d}{dt}$ is expressed in terms of $A_\varepsilon(t) = \frac{dh_\varepsilon(t)}{dt}$ by Hermann Weyl’s formula

$$
Ricci_\varepsilon\left(\frac{d}{dt}, \frac{d}{dt}\right) = \text{trace}\left(\frac{d}{dt} A_\varepsilon(t)^*\right) + (A_\varepsilon(t)^*)^2,
$$

where $A_\varepsilon^*(t)$ denote the (selfadjoint shape) operators associated to the quadratic forms $A_\varepsilon(t)$ via the metrics $h_\varepsilon(t)$ on $Y$.

Therefore, in view of $*2$ and $*3$,

$$
Ricci_\varepsilon \left(\frac{d}{dt}, \frac{d}{dt}\right) = \frac{1}{\varepsilon} \text{trace}(A_{old} - A_{new}) + O(1)
$$

and [ii] follows by the Gauss theorem egregium for the hypersurfaces $Y \times \{t\}$ in the manifold $Y \times [0, \varepsilon]$ with the metric $g_\varepsilon$.

**Bending Lemma.** Let $X = (X, g)$ be a smooth (possibly non-compact) Riemannian manifold with boundary $Y = \partial X$ and let $A_{old}$ denote the second fundamental form of $Y$ with respect to the inward normal field. (Notice that the boundaries of convex domains have positive definite second forms for such fields.) Let $A_{new}$ be another smooth quadratic form on $Y$.

If

$$
\text{trace}(A_{new}) < \text{trace}(A_{old})
$$

then there exits a family of $C^\infty$-smooth metrics $g_\varepsilon = g_{new, \varepsilon}$, $\varepsilon > 0$, on $X$, such that
The restrictions of the Riemannian metrics \( g_\varepsilon \) to \( Y = \partial X \subset X \) are equal to such restrictions of \( g \) for all \( \varepsilon > 0 \).

The second fundamental forms of \( Y \in X \) with respect to \( g_{\text{new},\varepsilon} = g_\varepsilon \), are equal to \( A_{\text{new}} \) for all \( \varepsilon > 0 \).

The scalar curvatures of \( g_\varepsilon \) are bounded from below by those of \( g \),

\[
Sc(g_\varepsilon) \geq Sc(g).
\]

The metrics \( g_\varepsilon \) \( C^0 \)-converge to \( g \) for \( \varepsilon \rightarrow 0 \).

The metrics \( g_\varepsilon \) are equal to \( g \) within distance \( \geq \varepsilon \) from \( Y \).

**Proof** Let \( \varepsilon << \varepsilon \) be a (very small) positive number, such that the \( \varepsilon \)-neighbourhood \( U_\varepsilon \) of \( Y \) normally splits,

\[
U_\varepsilon = Y \times [0,\varepsilon],
\]

where, by the definition of "normally", the hypersurfaces \( Y \times \{t\} \) are \( t \)-equidistant to \( Y = Y \times \{0\} \in X \).

Let us replace the metric \( g \) in \( U_\varepsilon \) by the above \( g_\varepsilon \).

Observe that the Riemannian form \( g_\varepsilon \) on the hypersurface \( Y \times \{\varepsilon\} \) as well as second fundamental form of \( Y \times \{\varepsilon\} \) with respect to \( g_\varepsilon \) are \( \varepsilon \)-close to the \( g \)-related forms. Therefore, according to \( \star \) from section 11.1 applied to sections of the bundle of quadratic forms on the tangents to submanifolds \( Y \times \{t\} \in X \), the form \( g_\varepsilon \) extends to all of \( X \) with the required properties except \( \text{[III]} \); this can be guaranteed by \( \star \) only up to an arbitrarily small error. Yet, this error can be taken care of by redistribution of the scalar curvature from section 11.2.

(If our "redistribution" is obtained with a use of the Fredholm + unique continuation properties of the operator \( f \mapsto Sc(f^2 g) \), then \( V \) needs to be compact and also the condition \( \text{[V]} \) suffer. But none of this happens if we rely on the Local Sc-Lemma.)

**Half Way \([\varepsilon \leftrightarrow \varepsilon]\)-Rounding and Making Doubles with \( Sc \geq \sigma \).** If \( X = \partial X \) has strictly positive mean curvature, then the above applies to \( A_{\text{new}} = 0 \) and allows a "bending" (of the Riemannian metric in) \( X \) near the boundary \( Y = \partial X \), which makes \( Y \) totally geodesic and such that

the scalar curvature of \( X_{\text{bent}} = (X, g_{\text{new}}) \) is bounded from below by the scalar curvature of the original metric \( g \).

Then the metric \( g_{\text{new}} \& g_{\text{new}} \) on the double \( (X, g_{\text{new}}) \cup_Y (X, g_{\text{new}}) \) is \( C^1 \)-smooth and, by \( \star \), it can be \( C^\infty \)-smoothed keeping its scalar curvature bounded from below by \( Sc(g_{\text{new}}) \) which itself is bounded from below by \( S(g) \) according to the above Bending Lemma.

**VI \(_{\text{loc}}\) Localisation of Bending.** Let the form \( A_{\text{new}} \) be equal to \( A_{\text{old}} \) on a (now possibly non-empty) compact subset \( Y_0 \subset Y = \partial X \) and the inequality \( \text{trace}(A_{\text{new}}) < \text{trace}(A_{\text{old}}) \) holds in the complement \( Y \setminus Y_0 \).

If \( X \) is connected and the complement \( Y \setminus Y_0 \) is non-empty, then there exists a family \( g_{\varepsilon}^* \), which satisfies the above \([\text{I}]-[\text{IV}]\) and where \([\text{V}]\) is strengthened to the following

**[V.]** The metrics \( g_\varepsilon \) are equal to \( g \) within distance \( \geq \varepsilon \) from \( Y \setminus Y_0 \).

\(^{40}\)There is no circularity here, since Local Sc-Lemma, albeit being a special case of the Bending Lemma, admits an independent (and obvious) proof.
About the Proof. Construction of $g^\varepsilon$, which satisfies this condition (parallel to the condition $\bullet_5$ in 11.3 for bending hypersurfaces with controlled mean curvatures) is achieved by an obvious smooth cut off of the above $g$, where the arising error term in $Sc(g^\varepsilon)$ can be compensated due to the $\frac{1}{\varepsilon}$-contribution in the positivity of the scalar curvature.

11.6 Minimal Hypersurfaces in Non-compact Manifolds.

Let us return to $M$-bubbles from section 9: these are closed cooriented hypersurfaces in Riemannian manifolds, say $Y_{\min} \subset X$, which locally minimise the functional

$$Y \mapsto vol_{n-1}(Y) - \int_{U_{\ast}} M(x)dx,$$

where $M$ is a function defined in a neighbourhood of $U_{\ast} \supset Y_{\min}$ and where $U_{\ast} \subset U$ is the interior part of $U_{\ast}$.

Unconditionally, the existence of such a $Y_{\min}$, possibly a singular one if $n = \dim(X) \geq 8$, is ensured only for closed manifolds $X$.

And if $X$ is a compact manifold with boundary, then the existence of $Y_{\min}$ follows from a suitable bound on the mean curvature of the boundary as in section 9.

$$M_{\partial_{-}X} \leq -mean.curv(\partial_{-}X) \text{ and } M_{\partial_{+}X} \geq mean.curv(\partial_{+}X)$$

where $\partial_\pm$ are the parts of the boundary of $X$ positioned in the interior/exterior region of $X$ with respect to $Y_{\min}$. (This makes sense since the decomposition $\partial X = \partial_{-}X \cup \partial_{+}X$ depends only on the homology class of $Y_{\min}$.)

Now we look for this kind of condition for non-compact manifolds, where our motivations are twofold:

(A) Finding geometric conditions on $X$, such that a given hypersurface $Y \subset X$ would admit a metric with positive scalar curvature.

(B) Finding least demanding constraints on a perturbation $g^\varepsilon$ of a Riemannian metric $g$ on $X$, such that a hypersurface $Y \subset X$ would admit an $\varepsilon$-close to it hypersurface with the mean curvature with respect to $g^\varepsilon$ being close to $mn.curv(g)(Y)$.

An obvious (over-optimistic?) conjecture in the direction of (A) is as follows.

(A?) Let $X$ be a complete Riemannian manifold of dimension $\geq 6$ and let $M(x)$ be a continuous function on $X$, such that

$$\frac{n}{n-1} M(x)^2 - 2\|dM(x)\| + Sc(X)(x) \geq 0.$$

Then every closed cooriented hypersurface $Y_0 \subset X$, for which the inclusion homomorphism between the fundamental groups

$$\pi_1(Y_0) \to \pi_1(X)$$

is injective, admits a a metric with $Sc > 0$.

(This generalises Conjecture 1.24 in [Ros 2007] for $X = Y_0 \times S^1$ and $M = 0$ and a similar conjecture – I recall seeing it in a paper by Rosenberg and/or Stolz – for complete $X$ homeomorphic to $Y_0 \times \mathbb{R}$.)
Motivating Example. Let let $X$ be a complete two-ended Riemannian manifold and let $Y_0$ be a smooth closed hypersurface, such that the following four conditions are satisfied.

$\circ$ $Y_0$ is connected and it separates the two ends of $X$. Thus, both components of the complement $X \setminus Y_0$ are infinite and both are one-ended. For instance, $X$ is homeomorphic to $Y_0 \times \mathbb{R}$.

(We agree that the only "infinities of" $X \setminus Y_0$ which count are parts of the "infinity of" $X").

$\circ$ There exist $\pi_1(Y_0) \to \pi_1(X)$ is injective then the covering of $X$ with the fundamental group equal to the image $\pi_1(Y_0) \subset \pi_1(X)$ has this property.

$\circ$ The inclusion homology homomorphism $H_1(Y_0) \to H_1(X)$ is an isomorphism. (If the inclusion homomorphism between the fundamental groups $\pi_1(Y_0) \to \pi_1(X)$ is injective then the covering of $X$ with the fundamental group equal to the image $\pi_1(Y_0) \subset \pi_1(X)$ has this property.)

$\circ$ The inclusion homomorphism between the fundamental groups $\pi_1(Y_0) \to \pi_1(X)$ is injective.

(If the inclusion homomorphism between the fundamental groups $\pi_1(Y_0) \to \pi_1(X)$ is injective then the covering of $X$ with the fundamental group equal to the image $\pi_1(Y_0) \subset \pi_1(X)$, but the roles played by $H_1$ and $\pi_1$ in the arguments below are different.)

$[\text{vol} = \infty]$ Both connected components of the complement $X \setminus Y_0$, call them $X_\pm \subset X$, have infinite volumes.

$[\text{spin}]$ Manifold $X$ is spin.

$[\odot_{\lambda,\rho}]$ There exist constants $\lambda, \rho > 0$, such that all balls in $X$ of radii $r \leq \rho$ are $\lambda$-Lipschitz contractible in $X$ (but not necessarily within themselves), i.e. there exist $\lambda$-Lipschitz maps $\phi = \phi_{x,r} : B_x(r) \times [0, r] \to X$, $x \in X$, $r \in [0, \rho]$,

where the maps $\phi(\ldots, 0)$ are the original imbeddings $B_x(r) \subset X$ and such that the maps $\phi(\ldots, r) : B_x(r) \to X$ are constant.

(Coverings of closed manifolds, obviously, satisfy this condition.)

$[\bullet]$ If the scalar curvature of $X$ is everywhere bounded from below by $\sigma_- \in (-\infty, +\infty)$ and $\text{Sc}(X)(x) \geq \sigma_+ > 0$ in the $\varepsilon$-neighbourhood of $Y_0 \subset X$, such that

$[\sigma_+ \gg |\sigma_-|]$

$$\sigma_+ \geq 2 \varepsilon \left[ \frac{|\sigma_-|(n-1)}{n} \right].$$

Then $Y_0$ admits a metric with $\text{Sc} > 0$, provided $6 \leq \text{dim}(X) \leq 8$.

Prior to explaining the proof, a few remarks are in order. $[\text{\#}]$ The spin condition can be significantly relaxed and, possibly, fully removed. (We shall explain this in the course of the proof of $[\bullet]$.)

$[\text{\#}]$ The condition $[\odot_{\lambda,\rho}]$ implies $[\text{vol} = \infty]$ as we shall see in the course of the proof of $[\bullet]$; however, the two play opposite roles in the proof of $[\bullet]$. But in any case, we would rather get rid of $[\odot_{\lambda,\rho}]$ altogether.

$[\text{\#}]$ The main function of the inequality $\text{dim}(X) \geq 6$ is to rule out 4-manifolds $Y_0$, where there are topological obstructions to the existence of metrics with $\text{Sc} > 0$ which have no counterparts for other dimensions, see [Ros 2007] and references therein.
The inequality \(\dim(X) \leq 8\) is, most likely, unnecessary – it is due to our inability to handle singularities of minimal hypersurfaces in manifolds of dimensions \(\geq 9\).

**Proof of \\[\bullet\].** **Step 1.** The inequality \(\sigma_+ \gg |\sigma_-|\) implies that there exists a function \(M(x)\), which vanishes on \(Y_0\) which is positive on one of the components of \(X \setminus Y_0\), say on \(X_+\) and negative on \(X_-\), which is constant 2ε-far from \(Y_0\) and such that
\[
\frac{n}{n-1} M(x)^2 - 2|dM(x)| + S\sigma(X)(x) > 0
\]
at all points \(x \in X\).

**Step 2.** Since \(\text{vol}(X_+) = \infty\), the integrals of \(M\) over both components \(X_\pm\) of \(X \setminus Y_0\) are ±infinite. Therefore, there exists a compact connected subset \(V_0 \subset X\), which contains \(Y_0\) and such that
\[
\int_{V_0 \cap X} M(x) dx > \text{vol}_{n-1}(Y_0).
\]
Consequently, every closed hypersurface \(Y'\) in the complement \(X \setminus V_0\), which is homologous to \(Y_0\) satisfies
\[
\text{vol}_{n-1}(Y') - \int_{X_\pm \setminus \infty} M(x) dx \geq \text{vol}_{n-1}(Y_0) - \int_{X_\pm \setminus \infty} M(x) dx + \mu_0,
\]
where
- \(\infty_+\) denotes a unspecified subset in \(X_+\), which has a sufficiently large compact complement; in particular, \(\infty_+\) doesn’t intersect \(V_0\),
- \(X'_+ \subset X\) is the (infinite) connected component of \(X \setminus Y'\) which contains \(\infty_+\),
- \(\mu_0 = \mu_0(V_0)\) is a positive constant.

Since the difference
\[
\int_{X'_+ \setminus \infty} M(x) dx - \int_{X_+ \setminus \infty} M(x) dx
\]
does not depend on the choice of \(\infty_+ \subset X_+\), the above inequality is unambiguous.

It follows that

**\(Y_{\text{min}}\) can’t escape from \(V_0\):**

all closed hypersurfaces \(Y' \subset X\), which are homologous to \(Y_0\) and which almost (up to \(\mu_0\)) minimize the functional
\[
Y' \mapsto \text{vol}_{n-1}(Y') - \int_{X'_+} M(x) dx =_{\text{def}} \text{vol}_{n-1}(Y') - \int_{X'_+ \setminus \infty} M(x) dx
\]
intersect \(V_0\).

And since these \(Y'\), because of the above \([\bullet] Y_0\) and \([\circ \circ]_{H_1}\), are connected, the minimization process for this functional converges (in the sense of the geometric measure theory) to a minimum, call it \(Y_{\text{min}} \subset X\): this is a possibly infinite hypersurface in \(X\) of *finite volume*, where this \(Y_{\text{min}}\) *doesn’t fully escape* \(V_0\). Namely

- \(Y_{\text{min}}\) is *proper*, i.e. it is a closed as a subset in \(X\), but it *may be non-compact* (hence, unbounded for complete \(X\));
• \( \text{vol}_{n-1}(Y_{\min}) \leq \text{vol}(Y_0) < \infty \)

• The hypersurface \( Y_{\min} \) has non-empty intersection with \( V_0 \).

(Notice that completeness of \( X \) is non-essential at this point.)

**Step 3.** Let us bring forth the above local Lipschitz contractibility condition \([\odot_{\lambda,\rho}]\), invoke the cone/filling inequality 3.4.C from [Gr 1983]. This shows that \([\odot_{\lambda,\rho}]\) implies the following filling inequalities \([\odot_{n-2}^{n-1}]\) and \([\odot_{n-1}^{n}]\).

\([\odot_{n-2}^{n-1}]\) All \((n-2)\)-cycles \( \beta \) in all \( \rho \)-balls, \( \beta = \beta_{n-2} \subset B_\rho(\rho) \subset X \), \( n = \text{dim}(X) \), bound \((n-1)\)-chains \( \alpha \subset X \), such that

\[
\text{vol}_{n-1}(\alpha) \leq c \cdot \text{vol}_{n-2}(\beta)^{\frac{n-1}{n-2}},
\]

for some constant \( c = c(n, \lambda, \rho) \).

\([\odot_{n-1}^{n}]\) All subdomains \( U \subset B_\rho(\rho) \) satisfy

\[
\text{vol}_n(U) \leq c' \cdot \text{vol}_{n-1}(\partial U)^{\frac{n}{n-1}},
\]

for some \( c' = c'(n, \lambda, \rho) \).

Then these inequalities easily yield the following lower bound on the volume of the balls in the minimizer \( Y_{\min} \subset X \),

\[
\text{vol}_{n-1}(Y_{\min} \cap B_\rho(\rho)) \geq \nu(n, c, c') = \nu(n, \lambda, \rho) > 0
\]

for all \( x \in Y_{\min} \).\(^{41}\)

Since \( Y_{\min} \) is connected, the above volume bound \( \text{vol}_{n-1}(Y_{\min}) \leq \text{vol}(Y_0) \) implies a bound on its diameter,

\[
\text{diam}(Y_{\min}) \leq R = \frac{2\rho \cdot \text{vol}_{n-1}(Y_0)}{\nu} < \infty.
\]

Then, by combining this inequality with the above intersection property for our minimizer, \( Y_{\min} \cap V_0 \neq \emptyset \), we conclude that

\( Y_{\min} \subset X \) IS TRAPPED\(^{42}\) IN THE \( R \)-NEIGHBOURHOOD OF \( V_0 \).

And since \( X \) is complete, \( Y_{\min} \) is compact.

**Step 4.** By the classical regularity theorem(s) of Simons-Federer-Almgren-Allard this \( Y_{\min} \) is a smooth hypersurface for \( \text{dim}(X) \leq 7 \); if \( n = 8 \), then the regularity is achieved by a small perturbation of the Riemannian metric in \( X \).\(^{43}\)

Then, the inequality \( \frac{n}{n-2} M(x)^2 - 2\|dM(x)\| + Sc(X)(x) > 0 \), implies that the induced metric in \( \hat{Y}_{\min} \) is conformal to a metric with \( Sc > 0 \) by the \( M \)-version of the Schoen-Yau argument (see §5.2 in [Gr 1995]).

**Step 5.** If \( Y_{\min} \) is smooth and \( \text{dim}(Y_{\min}) \geq 5 \) then the kernel of the inclusion homomorphism

\[
\pi_1(Y_{\min}) \twoheadrightarrow \pi_1(X) = \pi_1(Y)
\]

\(^{41}\)This is explained in [Gr 1983], where the corresponding inequalities are formulated for the functional \( Y \rightarrow \text{vol}_{n-1}(Y) \) and where \( X \supset Y \) is often required to be compact. But all (relevant) arguments from [Gr 1983] apply in the present case.

\(^{42}\)This means "contained".

\(^{43}\)The argument from [NS 1993] easily generalises to our \( Y_{\min} \).
can be "killed" by 2-dimensional surgery that results in another hypersurface, say \( Y \subset X \), which is also homologous to \( Y_0 \) and which admits a metric with \( \text{Sc} \geq 0 \).

If, moreover, the inclusion homomorphism \( \pi_1(Y_0) \to \pi_1(X) \) is an isomorphism, and \( X \) is spin, then \( Y \) is spin-bordant to \( Y_0 \) in the classifying space of \( \pi_1(Y_0) \) and the existence of metric with \( \text{Sc} > 0 \) on \( Y_0 \), follows from the theorem 1.5 in [St 2001]. (Possibly – I am not certain – this theorem also covers the non-spin case.)

Finally, since the homomorphism \( \pi_1(Y_0) \to \pi_1(X) \) is injective according to [\( \circ \)/uni\(21AA\)], all of the above applies to the covering space \( \tilde{X} \to X \) with the fundamental group \( \pi_1(\tilde{X}) = \pi_1(Y_0) \). QED.

**Discussion.** The above argument can be generalised, refined and made effective, which would result in specific inequalities for the "relative size" of pairs \((X, M(x))\), where \( \text{Sc}(X)(x) \) is suitably bounded from below in terms of \( M(x) \) and where certain hypersurfaces \( Y_0 \subset X \) admit no metrics with \( \text{Sc} > 0 \).

However, it remains unclear if the condition \([\odot, \lambda, \rho]\), or anything of this kind, is truly necessary.

In fact, we do know that no such condition is needed for the bounds on the width of overtorical and similar band-shaped manifolds to which our symmetrization with point-wise control of the scalar curvature applies (see sections 7 and 8).

Also, even the present form of \([\bullet]\) remains problematic for manifolds \( X \) with \( \text{dim}(X) \geq 9 \).

### 11.7 Bounds on Widths of Non-Compact Riemannian Bands.

The band inequalities in sections 2, 4, 5 generalise to certain *non-compact complete* bands.

**Case 1.** Let \( V \) be a proper (see section 2) band with compact boundaries
\[
\partial V = \partial_- \cup \partial_+
\]

The concepts of "overtorical", "isoenlargeable", and "SYS" make sense for these \( V \), where the instances of such non-compact bands are, topologically, obtained from compact ones by removing isolated points from their interiors.

*proper bands* \( V \) with compact boundaries which have \( \text{Sc}(V) \geq \sigma > 0 \) satisfy the same width bound as their compact counterparts in sections 2, 4, 5.

**Proof.** Let \( V' \subset V \) be a compact manifold obtained by cutting of the infinity of \( V \) far away from \( \partial V \). Thus \( V' \) has an extra set of components, call their union \( \partial' \), where one can make make the distance \( \text{dist}(\partial(V'), \partial') \) as large as one wants.

Thus we arrange such a \( V' \), where the the \( \rho \)-neighbourhood \( U^\rho_\rho \subset V' \) of \( \partial' \subset V' \) for a large \( \rho \) does not disturb the essential topology of \( V \):

[\( \star \)] the subset \( U^\rho_\rho \subset V' \) does not intersect \( \partial = \partial V \) and, moreover, \( V' \setminus U^\rho_\rho \) is in the same topological largeness class as \( V \), namely overtorical, "isoenlargeable or SYS correspondingly.

Clearly, this property is inherited by minimal hypersurfaces constructed in the suitable homology classes as in section 2, 4, 5, where the final stage of the symmetrization goes through if \( \rho \) is sufficiently large.
For instance, $\rho \geq \frac{4\pi}{\sqrt{\sigma}}$ is sufficient for this purpose but this bound doesn’t seem sharp. QED

**Case II.** Let $V$ be a proper complete orientable $n$-dimensional band, such that $V$ admits a proper 1-Lipschitz map $\psi : V \to \mathbb{R}^{n-1}$, such that the restriction of $\psi$ to $\partial_-$ (and hence, on $\partial_+$) has degree $d \neq 0$.

If the scalar curvature of $V$ is bounded from below by $\text{Sc}(V) \geq \sigma > 0$, then the width of $V$ is bounded as follows.

$$\text{width}(V) = \text{dist}(\partial_-, \partial_+) \leq 2\pi \sqrt{\frac{n-1}{\sigma n}}.$$

**Proof.** Let $S^{n-3}(R) \subset \mathbb{R}^{n-1}$ be a very large codimension 2 sphere say of radius $\geq 100^{n-1}$ and let

$$\Sigma = \partial V \cap \psi^{-1}(S^{n-3}(R)) \subset V,$$

where one may assume if one wishes – this is not truly necessary – that the map $\psi$ is transversal to the sphere $S^{n-3}(R)$.

This $\Sigma$, which has codimension 2 in $V$, is meant to serve as the boundary condition for a minimizing hypersurface, $Y$, namely, the boundary of $Y$ must be contained in $\Sigma$ and the relative homology class of $Y$ in $H_{n-1}(V, \Sigma)$ must be equal to the homology pullback of the $(n-1)$-ball bounded by this sphere.

To avoid unnecessary non-compactness problems, we cut off $V$ and thus $Y$, by taking a large $V' \subset V$ which contains $\psi^{-1}(S^{n-3}(R))$, say the $\psi$-pullback of the $R'$-neighbourhood $U = U(R, R') \subset \mathbb{R}^{n-1}$ of the sphere $S^{n-3}(R) \subset \mathbb{R}^{n-1}$ for $R' \geq 100R$.

This $Y$ serves as the first step of the inductive symmetrization, except that unlike the original $V$ it is compact and has extra part of the boundary, namely, the $\psi$-pullback of the boundary of $U$.

Thus, in order to have a proper inductive scheme, one should drop the completeness assumption on $V$, and require instead that

$V$ admits a proper 1-Lipschitz map to the $R_n$-ball in $\mathbb{R}^{n-1}$ for a sufficiently large $R_n$, say for $R_n \geq 1000^n$, such that the restriction of $\psi$ to $\partial_-$ has degree $d \neq 0$.

At this point, we invite the reader to fill in the details in the above argument.

**Corollary: Sharp Bound on Widths of Iso-Enlargeable Bands.**

Compact Iso-enlargeable bands $V$ (e.g., those homeomorphic to $V_0 \times [-1, 1]$ where $V_0$ admits a metric with non-positive curvature) with their scalar curvatures $\geq \sigma$ satisfy the $\frac{2\pi}{\sigma}$-Inequality.

$$\text{width}(V) \leq 2\pi \sqrt{\frac{n-1}{\sigma n}}.$$

---

44 There is no such problem if $V$ has locally bounded geometry, e.g., if it is a covering space of a compact band, then the minimizing $Y$ is compact since locally bounded geometry implies uniform local Lipschitz contractibility ($[\psi, \rho]$ from the previous section.)
Proof. It follows from the definition of iso-enlargeability of $V$ that there exist Riemannian bands $V_R$ for all $R > 0$, such that

- there exist locally isometric band maps $V_R \to V$,
- there exist proper 1-Lipschitz maps from $V_R$ to the $R$-balls in $\mathbb{R}^{n-1}$, such that the restrictions of $\psi$ to $\partial_\pm$ have (equal) degrees $\neq 0$.

Thus, the above applies and the proof follows.

Remark. Minimal hypersurfaces with mixed boundary conditions in our argument are similar to those in §12 in [GL 1983], where, in fact, a non-sharp version of the above inequality is proven.

On the Definition of Iso-enlargeability. These $\bullet_1$ and $\bullet_2$ can be taken for the definition of iso-enlargeability of bands as it was mentioned in footnote 9 in section 4.

11.8 Stable Enlargeability and Stable Bounds on the Scalar Curvature.

Let $X$ be an orientable Riemannian manifold of dimension $n$ and $P$ an orientable pseudomanifold of dimension $N$.

Let us consider three different cases indexed by $i = 0, 1, 2$, each associated with a map

$$f = f_i : X \times P \to B \subset \mathbb{R}^{n+N-1}, \ i = 0, 1, 2,$$

where $B$ is an open unit ball, and where $f$ is a smooth proper, such that

- the restrictions of $f$ to the submanifolds $X_p = X \times \{p\} \subset P$, $p \in P$, are $\lambda$-Lipschitz for some constant $\lambda > 0$ and
- if $i = 0$, then the map $f$ has non-zero degree;
- if $i = 1$, then the cap product of the pullback of the fundamental cohomology class of $B$ with compact support with the fundamental class of $X \times P$,

$$f^*[B]^{n+N-1} \cap [X \times P]_{N+n} \in H_1(X \times P),$$

does not vanish when taken with $\mathbb{Q}$-coefficients, i.e. under the homomorphism $H_1(X \times P) \to H_1(X \times P)$;
- if $i = 2$ then the cap product class

$$f^*[B]^{n+N-2} \cap [X \times P]_{N+n} \in H_2(X \times P)$$

is aspherical, i.e. it is not contained in the image of the the Hurewicz homomorphism, or, equivalently, it does not lift to the universal covering of $X \times P$.

Then the infimum of the scalar curvature of $X$ is bounded by

$$\varepsilon_X = \inf_{x \in X} Sc(X)(x) \leq \varepsilon \lambda^2$$

where $\varepsilon > 0$ depends only on $n$ and $N$.

Proof. First, let $P$ be a manifold and let us endow it with a very (arbitrarily) large metric which has scalar curvature $\geq -\delta$ for a given arbitrarily small $\delta > 0$. This makes $Sc(X \times P) \geq \kappa - \delta$ and, at the same time, the Lipschitz constant of $f$ as close to $\lambda$ as you wish.

45Geometrically, this class is represented by (possibly singular) surfaces in $X \times P$, which are the $f_1$-pullbacks of generic points $b \in B$. 

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Then, the proof follows either by arguing as in the proof of the spherical Lipschitz bound theorem in section 3 with a torical band in $B$ and a use of width inequalities for compact bands or doing it more directly with open bands as in the previous section. (This directly applies to $i = 0, 2$ and the case $i = 1$ trivially reduces to $i = 0$.)

In general, if $P$ is a pseudomanifold, we take a similarly large metric in $P$, where $Sc ≥ δ$ on all $N$-faces $Q$ of $P$. Then, clearly, there exist

(*) a face $Q$,

(****) a (large) open subset $X' ⊂ X$,

such that the above applies to the restriction $f'$ of the map $f$ to some the subproduct $X' × Q' ⊂ f^{-1}(B') ∩ (X' × Q)$ for some open subset $Q' ⊂ Q$

$$f': X' × Q' → B'.$$

Complaint. One can’t help but to be annoyed by the the dimension being brought up by incorporating purely topological parameters $P$ into the geometry of $X × P$, only to be immediately brought down by constructing a decreasing chain of minimal hypersurfaces.$^{46}$

11.9 Mean Curvature Stability of Polyhedral Domains.

Let $Y$ be a closed smooth cooriented hypersurface in a Riemannian manifold $X = (X, g)$ and let $g_ε$ be a family of smooth Riemannian metrics on $X$ which $C^0$-converge to $g$ for $ε → 0$. It is shown in section 10.2 of [Gr 2012] that such small perturbations $g_ε$ can be accompanied by small perturbations of $Y$ which only slightly change the mean curvature of $Y$. Namely we have the following perturbation stability property

If $X$, there exists a family of diffeomorphisms $ψ_ε: X → X$, $ε > 0$, such that

(1) the diffeomorphisms $ψ_ε$, $ε → 0$, converge to the identity map $id: X → X$ in the $C^0$-topology;

(2) the $(n - 1)$-volumes of the hypersurfaces $Y_ε = ψ_ε(Y) ⊂ X$ with respect to $g_ε$ converge to $vol_{n-1}(Y)$ for $g$;

(3) the $g_ε$-mean curvatures of $Y_ε$ converge to $mn.curv_κ(Y)$.

For instance, if $mn.curv(Y) > c$ for some number $c ∈ (-∞, +∞)$, then the hypersurfaces $Y_ε$ satisfy the same inequality for all sufficiently small $ε > 0$.

The essential steps in the proof of this can be seen as $ε$-minimatised versions of the first three steps in the proof of [●] in section 11.6, which now take place in a small tubular neighbourhood $U ⊃ Y$.

Step. 1+2. Take a suitable function $M_ε(x)$ in $U$ for which $Y$ strictly minimizes the functional

$$Y ↦ vol_{n-1}(Y) - ∫_{U_s} M_ε(x)dx,$$

$^{46}$If $X$ is complete and the universal covering $X$ of $X$ is spun, then the bound

$$inf_{x∈X} Sc(X)(x) ≤ ε^{p-2}$$

for $i = 0, 1$ (but not for $i = 2$) follows by applying a suitable index theorem for the $P$-family of Dirac operators on $X$, keeping the $P$-parameters at their proper place.
where $U_+ \subset U$ is the part of $U$ positioned inward of $Y$, such that the corresponding minimizer $Y_\varepsilon$ of this functional for $g_\varepsilon$. (Such an $M$ on $Y$ must be equal to $\text{mn.curv}(Y)$)

**Step 3.** Observe that the filling inequalities $[\circ \, n_{-1}]$ and $[\circ \, n_{-1}]$ are stable under small perturbations $g_\varepsilon$ of $g$ and conclude that $Y_\varepsilon$ is trapped in $U_\varepsilon$.

(This $\varepsilon$ may be slightly larger than the above one.)

Then the smoothness of $Y_\varepsilon$ ($n \geq 8$ included) follows from Almgren’s optimal isoperimetric inequality (see [Alm 1986]), which also allows a construction of diffeomorphisms $\psi_\varepsilon : X \to X$ which send $Y \to Y_\varepsilon$ (see [Gr 2012] for details).

**Warning.** The hypersurfaces $Y_\varepsilon$ do not, in general, $C^1$-converge to $Y$ and, conceivably, there are examples (I have not scrutinised the literature), where there are no diffeomorphisms $\psi_\varepsilon$ having the norms of their differentials (and/or of their inverses) bounded by $1 + \varepsilon$.

On the other hand, one can control some Hölder norm of $\psi_\varepsilon$ according to Reifenberg’s topological disk theorem.

Also Reifenberg’s flatness condition implies relative versions of the filling inequalities $[\circ \, n_{-1}]$ and $[\circ \, n_{-1}]$ from the previous section that is useful for smoothing "intrinsic edges and corners" in manifolds with $Sc \geq \sigma$. (see the next section and [Gr 2014*]).

**Localization of $[\circ \, n]$.**

$[\circ \, n_{\varepsilon}]$. If the metrics $g_\varepsilon$ are equal to $g$ on a neighbourhood $U_0 \subset X$ of compact subset $X_0 \subset X$ then the above diffeomorphisms $\psi_\varepsilon$ can be taken equal to the identity map on another (smaller) neighbourhood $U_\varepsilon \supset X_0$.

**About the Proof.** This is achieved with suitable functions $M_\varepsilon$ defined on the complement of $X \setminus U_\varepsilon$. And here, as on other localization occasions, we leave the actual proof to the reader, since the corresponding localised properties are only marginally used in the present paper.

**Stability Relative to $\partial X$.**

In this paper, we need a relative version of $[\circ \, n]$, and also of $[\circ \, n_{\varepsilon}]$, where $X$ is a manifold with boundary and our hypersurface $Y \subset X$ has $\partial Y \subset \partial X$.

The above argument applies (almost) word for word to such $Y$, where, additionally, one has to keep track of the dihedral angles between (the tangent spaces of) $Y$ and $\partial X$ along $\partial Y \subset \partial X$.

For instance, if these angles on the inward side of $Y$ satisfy $\angle_{in}(Y, \partial X) < \frac{\pi}{2}$, then also $\angle_{in}(Y_\varepsilon, \partial X) < \frac{\pi}{2}$.

This together with Bending Lemma (section 11.5) combined with $\varepsilon$-redistribution of curvature (section 11.2) yield the following.

**\$\varepsilon\$-Flattening Corollary.** Let $X$ be a Riemannian manifold with smooth boundary and let $Y \subset X$ me a compact smooth cooriented hypersurface, where $\partial Y \subset \partial X$ and such that $mn.curv(Y) > 0$ and the inward (with respect to the coorientation of $Y$) dihedral angles between $Y$ and $\partial X$ are everywhere $\leq \frac{\pi}{2}$.

Then there exists a family of smooth Riemannian metrics $g_\varepsilon$, $\varepsilon > 0$, on $X$, such that
•1 the hypersurface \( Y \) is totally geodesic in \( X \) with respect to \( g_\varepsilon \) for all \( \varepsilon > 0 \);
•2 \( \text{mn.curv}_{g_\varepsilon}(\partial X) \geq \text{mn.curv}_g(\partial X) \) and the inward dihedral angles with respect to \( g_\varepsilon \) between \( Y \) and \( \partial X \) are everywhere \( \leq \frac{\pi}{2} \) for all \( \varepsilon > 0 \);
•3 the scalar curvatures of \( g_\varepsilon \) are bounded from below at all points \( x \in X \) by \( \text{Sc}(g)(x) \);
•4 the metrics \( g_\varepsilon \) are equal to \( g \) outside the \( \varepsilon \)-neighbourhood (with respect to \( g \)) of the union \( Y \cup \partial X \);
•5 the quadratic forms \( g_\varepsilon - g \) are positive semidefinite for all \( \varepsilon > 0 \).

•? On Convergence \( g_\varepsilon \to g \).

Ideally, one would like to have \( C^0 \)-convergence \( g_\varepsilon \to g \) for \( \varepsilon \to 0 \) but all we are able to show is that only the negative part of the difference \( g_\varepsilon - g \) tends to zero, which, by small perturbations of \( g_\varepsilon \), allows one to make \( g_\varepsilon - g \) positive semidefinite.

To see where the problem resides, let us return to a closed smooth cooriented hypersurface \( Y \) in a Riemannian manifold \( X = (X, g) \) at the beginning of this section, and a family of smooth Riemannian metrics let \( g_\varepsilon \) on \( X \) which \( C^0 \)-converge to \( g \) for \( \varepsilon \to 0 \).

Assume, for simplicity’s sake, that \( \text{mn.curv}(Y) = 0 \) and let \( Y_\varepsilon \) be the perturbations of \( Y \) which have \( \text{mn.curv}(Y_\varepsilon) \to 0 \) and which themselves uniformly converge to \( Y \).

We do know that these \( Y_\varepsilon \) are diffeomorphic to \( Y \) but we do not expect their Riemannian metrics \( h_\varepsilon = g_{\varepsilon Y} \) induced from \( g_\varepsilon \) to converge to \( h = g_{Y} \). All we can say is that the \( g \)-normal projections \( Y_\varepsilon \to Y \), besides being homotopic to diffeomorphisms, are \((1+o(1))\)-Lipschtz. This eventually transforms to the above •1.

And albeit our construction of \( g_\varepsilon \) can’t deliver the \( C^0 \)-convergence \( g_\varepsilon \to g \), probably, one can show that the distance functions \( \text{dist}_{g_\varepsilon} \) on \( X \times X \) uniformly converge to \( \text{dist}_g \) for \( \varepsilon \to 0 \).

On Stability of Piecewise Smooth Hypersurfaces.

Here, as everywhere in this paper, "piecewise smooth" hypersurfaces \( Y \) in \( X \) are, by definition, locally diffeomorphic to polyhedral hypersurfaces in \( \mathbb{R}^n \), \( n = \text{dim}(X) \).

If \( X \) comes with a Riemannian metric \( g \), these \( Y \), if they are cooriented, are characterised by the mean curvatures of their \( n-1 \)-faces and the dihedral angles between these faces.

Apparently, as indicated (without proof) in section 4.8 in [Gr 2014*] these \( Y \) satisfy a piecewise-smooth version of the above \([\circ]_1 \).

This means that,

given an \( \varepsilon \)-family of smooth Riemannian metrics on \( X \), which \( C^0 \)-converge to a metric \( g \) as in \([\circ]_1 \),

\[
g_\varepsilon \underset{\varepsilon \to 0}{\to} g,
\]

there exists a family of piecewise smooth homeomorphisms \( \psi_\varepsilon : X \to X \) such that

• \( \psi_\varepsilon \) are smooth on the \((n-1)\)-faces of \( Y \) away from the \((n-3)\)-faces,
• \( \psi_\varepsilon \) converge to the identity map \( \text{id} : X \to X \) in the \( C^0 \)-topology;
• the \((n-1)\)-volumes of the hypersurfaces \( Y_\varepsilon = \psi_\varepsilon(Y) \subset X \) with respect to \( g_\varepsilon \) converge to \( \text{vol}_{n-1}(Y) \) for \( g \).
• the $g_\varepsilon$-mean curvatures of the faces of $Y_\varepsilon$ converge to $\text{mn.curv}_g$ of the corresponding faces of $Y$;

• the $g_\varepsilon$-dihedral angles between the faces of $Y_\varepsilon$ converge to the $g$-dihedral angles between the corresponding faces of $Y_\varepsilon$.

The relative version of this in manifolds $X$ with corners (i.e. with piecewise smooth boundaries), which also seems to follow by the available techniques\textsuperscript{47}, would automatically yield smoothing of metrics on manifolds obtained by reflections of manifolds with corners with no decrease of their scalar curvatures (see section 4.8 in [Gr 2014*]).

On the other hand, one can prove the existence of such smoothings in the essential cases by some roundabout argument as we shall explain in the next section.\textsuperscript{48}

11.10 Flattening of Faces and Regularisation of Reflections.

□-Flattening Lemma. Let $X = (X, g)$ be a Riemannian manifold with corners, where all faces of the boundary $\partial X$ have positive mean curvatures and where the dihedral angles between the pairs of $(n-1)$-faces in $\partial X$, wherever they meet, are \(\leq \frac{\pi}{2}\).

Then there exists a family of smooth metrics $g_\delta$, $\delta > 0$, such that

1. the faces of $\partial X$ are totally geodesic with respect to $g_\delta$ for all $\delta > 0$;

2. all dihedral angles in $\partial X$ with respect to $g_\delta$ are $\frac{\pi}{2}$ for all $\delta > 0$;

3. the scalar curvatures of $g_\delta$ are bounded from below at all $x \in X$ by $\text{Sc}(g)(x)$;

4. the metrics $g_\delta$ coincide with $g$ outside the $\delta$-neighbourhood of the boundary $\partial X$;

5. the differences $g_\delta - g$ are positive semidefinite for all $\delta > 0$.

This is a special case of the Approximation/Reflection Lemma in section 4.9 in [Gr 2014*] where this is proven not only for $g$ itself, but for metrics $g_\varepsilon$ which $C^0$-converge to $g$.\textsuperscript{49}

Granted that, one can reflect $X$ around the faces (see 2 in section 11.1) smoothly the metric in the resulting manifold $\tilde{X}$ by using Cut-off Homotopy Lemma (★ in 11.1) and applying a corresponding inequality for manifolds (bands) without corners.

Thus, for instance, one shows in [Gr 2014*] that

Riemannian manifolds $X$ with $\text{Sc}(X) > 0$ can’t contain mean curvature convex (e.g. convex) cubical domains $Q$, where all dihedral angles, are non-obtuse.

Below is another Example.

\textsuperscript{47}The local version of this must be also true

\textsuperscript{48}An unpleasant technical difficulty in the proof of the mean curvature stability in the piecewise smooth case, which one has to ? go around, is the absence ? of $C^1$ regularity theorem for minimal $Y \subset X$ at the singular boundary points of $X$.

\textsuperscript{49}This lemma is formulated in [Gr 2014*] only for $\text{Sc}(g) > 0$ and without formulating the above (4) and (5). However the proof of this lemma indicated in [Gr 2014*] automatically deliver these properties .
Sub-Rectangular $\frac{2\pi}{n}$-Inequality. Let $X$ be a Riemannian $n$-manifold, let $Q \subset X$ be a domain diffeomorphic to the $n$-cube $[-1,1]^n$ and let $Q^+_i \subset \partial Q \subset Q$, $i = 1,\ldots,n$, denote the pairs of opposite codimension 1 faces in $Q$ which correspond to such pairs in the cube.

Let

(i) the faces $Q^+_i$ for $i = 1,\ldots,n-1$, are mean curvature convex, i.e.

$\text{mn.curv}(Q^+_i) \geq 0$,

(ii) the dihedral angles $\angle_{x_i,x_j} = \angle(Q^+_i, Q^+_j)$ between these faces are non-obtuse at all points in the $(n-2)$-"edges" where these faces meet,

$\angle_{x_i,x_j} \leq \pi/2$, for all $i, j = 1,\ldots,n-1, i \neq j$,

(iii) the scalar curvature of $X$ satisfies $Sc(X) > n(n-1)$.

Then the distance between the two remaining opposite faces satisfy

$\left[\square_x \left< \frac{2\pi}{n} \right]\right] \text{dist}_x = \text{dist}_X(Q^+_n, Q^-_n) < \frac{2\pi}{n}$.

Proof. Reflect $Q$, but now only only in the faces $Q^+_i$ with $i < n$. Thus we construct a torical band with $Sc > \sigma$ and apply $\left[\square_\sigma \right]$ to this band.

Flattening and Gluing with $Sc > 0$.

The proof of the Approximation/Reflection Lemma in [Gr 2014*] proceeds by induction on the number of faces with application of Reifenberg’s flatness property of minimal varieties at each step of induction.

But if the boundary of $X$ consists of only two (possibly disconnected) $(n-1)$-faces then the $\square$-Flattening Lemma follows from the $\square_\epsilon$-Flattening Corollary from the previous section.

Indeed if $Y \subset X$ is a totally geodesic hypersurface normal to $\partial X$, then the intrinsic bending delivered by the proof of the Bending Lemma from section 11.5 does not disturb $Y$ and we have both $Y$ and $\partial X$ totally geodesic as well as mutually normal.

This also applies if the set of $(n-1)$-faces one can be divided into two subsets of mutually disjoint ones, i.e. if the incidence graph $\mathcal{I}$ between the faces is bipartite.

And assuming no three $(n-1)$-faces meet, $\mathcal{I}$ can be artificially made bipartite by subdividing the faces.

This is done by creating "new narrow" $(n-1)$-faces positioned close to the $(n-2)$-faces on one side of them. ( The $(n-2)$ faces are assumed two-sided , i.e. coorientable in $\partial X$.)

Observe that the the dihedral angles between the "new" $(n-1)$-faces and the "old" ones are equal to $\pi$, which, however, leads to no problem due to the possible localization of bending (section 11.5 ) and of $\left[\square_\epsilon \right]$ (section 11.7).

Now let us explain how one can get rid of "higher order corners" in $X$ by paying the price of a change of their topologies. In fact this "price" limits the application of such gluing to $\dim(X) = 3$.

Given an $n$-dimensional cosimplicial manifold $X$ with corners, e.g. diffeomorphic to the $n$-cube $[0,1]^n$, one may double it over the set of its (preliminarily
cut off) highest order corners, where the maximal numbers, say $m$, of the $(n-1)$-faces in $\partial X$ meet.

For instance, if $X = [0, 1]^n$ then $m = n$ where these highest corners are the ordinary vertices in $[0, 1]^n$.

The resulting double, call it $X^{[1]}$ has a natural corner structure where the highest corners have order $m^{[1]} = m - 1$. Thus we can continue unless we arrive at $X^{[m]}$ with smooth boundary (see section 1.1 in [Gr 2014*]).

Geometrically, if $X$ is the ordinary cube $[0, 1]^n \subset \mathbb{R}^n$, (almost but not quite exactly) this can be achieved by cutting the faces of this cube of dimensions $\leq n - 2$ by hyperplanes and then by reflecting the resulting polyhedron around its (new as well as old) $(n - 1)$-faces.

Now we want to stop at $X^{[m]}$, for $m \leq n - 2$, such that the only singularities are $(n - 2)$-dimensional faces, "edges", where pairs of $(n - 1)$-faces meet.

GLUING/SURGERY LEMMA. Let $g$ be a Riemannian metric on $X$, for which all faces have $mn\text{curv}_g > 0$ and all dihedral angles are $\leq \alpha \leq \pi$.

Then $X^{[m \leq n-2]}$ admits a smooth metric $g^{[m]}$, where the faces also have $mn\text{curv}_{g^{[m]}} > 0$ and all dihedral angles are $\leq \alpha$, and such that the scalar curvature of $g^{[m]}$ is bounded from below (in a natural sense) by that of $g$.

For instance, if $\text{Sc}(g) > 0$, then also $\text{Sc}(g^{[m]}) > 0$.

Sketch of the Proof. Let first $X$ be diffeomorphic to the 3-cube $[0,1]^3$. By consecutively applying the Cut-off Homotopy Lemma at a vertex $p \in [0,1]^3$ to the three 2-faces at $p$, one can "infinitesimally straighten" these faces at $p$, i.e. make them geodesic at $p$, while keeping $mn\text{curv} \geq 0$.

If there are two 3-manifolds, $X$ and $X'$ with such vertices, one can arrange the connected sum

$$(X,p)\#(X',p')$$

by "gluing" them with an arbitrarily small decrease of their scalar curvatures by the same construction as it is done for the ordinary connected sum in [GL 1980*], where one can preliminarily enlarge the scalar curvature of the two at the points $p$ and $p'$ by means of the Cut-off Homotopy Lemma (as it is done on p. 111 in [Gr 1986] in a similar context.)

Then the required double of our cubical $X$ is achieved by "infinitesimally straightening" the faces at all eight vertices in $X$ and then taking the double with a "gluing metric" at all vertices.

The above applies to 0-faces (vertices) $p$ of all $X$ for all $n = \text{dim}(X)$. In general, if $P$ is an $m$-face for $0 < m \leq n - 2$, one "infinitesimally straighten" the $(n-1)$-faces normally to $P$, where a face $P' \supset P$ is regarded infinitesimally straight normally to $P$ if the second fundamental form of $P \subset X$ vanishes on the tangent subspaces $T_x \subset T_x(P')$ normal to $P \subset P'$ at all points $x \in P$, where, observe, $\text{rank}(T_x) = \text{dim}(P') - \text{dim}(P) \geq 2$.

Clarifying Topological Remark. To see what makes the difference between dimensions $n = 3$ and $n \geq 4$, let $V$ be an $n$-dimensional manifold $X$ minus an open tubular neighbourhood of a closed submanifold $Y$.

If $X$ carries a metric with $\text{Sc} > 0$ and $\text{codim}(Y) \geq 3$, then the double $W = V \cup_{XV} V$ also carries such metric.

Now, if $X$ is ovetorical and the submanifold $Y$ can be homotoped to a single point in $X$, e.g. $Y$ is a finite union of points in $X$, then $W$ is also ovetorical.
But if, for instance, $X = \mathbb{T}^n$ and $Y$ is the union of $n$ disjoint circles which generate $H_1(X)$, then $W$ is not overtorical. In fact, the corresponding $W$ in this case does carry a metric with positive scalar curvature.

11.11 Non-existence Results and Conjectures.

Following a suggestion by the referee, we briefly overview in this section a few constrains, some of which proved in the main body of this article and some conjectural, on the topology of manifolds which carry metrics with $Sc > 0$.\footnote{Unsolved problems on $Sc > 0$ are collected in [Gr 2017] and [Gr 2017*].}

Say that a closed oriented manifold $X$ is SYS (Schoen-Yau-Schick) over a cohomology class $h$ in a topological space $K$, where

$$h \in H^{n-2}(K; \mathbb{Z}), \ n = \dim(X),$$

if there is a continuous map $A : X \to K$, such that the 2-dimensional homology class in $X$ which is the Poincaré dual of the cohomology pullback $A^*(h) \in H^{n-2}(X; \mathbb{Z})$ of $h$,

$$A^*(h) = PD(A^*(h)) \in H_2(X),$$

is non-spherical, i.e. it is not contained in the image of the Hurewicz homomorphism $\pi_2(X) \to H_2(X)$.

For example, "SYS over the fundamental cohomology class of the torus $\mathbb{T}^{n-2}$" is the same as "SYS$^n$" defined in section 5.

Let us generalise the Schoen-Yau theorem ([SY - Str 1979] for $n \leq 7$ and [SY 2017] for all $n$) on non-existence of metrics with positive scalar curvatures on SYS-manifolds and (some case of) theorem 13.8 in [GL 1983] as follows.

**SYS-Non-existence Theorem.** Let $K$, be a manifold which admits a complete metric with non-positive sectional curvature and let $X$ be a closed manifold which is SYS over an integer cohomology class $h \in H^{n-2}(K)$ which does not vanish in $h \in H^{n-2}(K; \mathbb{Q})$.

Then $X$ admits no metric with positive scalar curvature.

**Proof.** Start with the case where $K$ is compact oriented of dimension $n-2 = \dim(X) - 2$ and $h \in H^{n-2}(K; \mathbb{Z})$ is the fundamental class of $K$. Let $\hat{K}$ be the universal covering of $K$ and $\hat{X}$ be the covering of $X$ induced by the above map $A : X \to K$.

Since $\hat{K}$ has non-positive curvature, it admits proper $\lambda$-Lipschitz maps $F_\lambda$ to the unit ball $B = B^{n-2}(1) \subset \mathbb{R}^{n-2}$ of degree 1 for all $\lambda > 0$ and then, when $\lambda \to 0$, the proof follows from the stable SYS-bound on the scalar curvature from section 6 applied to the composed maps

$$\hat{X} \xrightarrow{\hat{A}} \hat{K} \to B$$

in the role of $f = f_\lambda$ and $X = X \times \{p\}$, where $\{p\}$ a single point space for $P$.

Now let us turn to the case of a complete orientable $K$ of dimension $m \geq n-2$ and let $h \in H^{n-2}(K; \mathbb{Z})$. Assume $K$ is parallelizable, otherwise, pass to the total space of the normal (for an embedding $K \to \mathbb{R}^M$) vector bundle $T^4(K) \to K$, which (by an easy argument) also carries a metric with non-positive sectional curvatures.

50 Unsolved problems on $Sc > 0$ are collected in [Gr 2017] and [Gr 2017*].
In this case, there exists continuous proper maps \( F_\lambda : \tilde{K} \times K \rightarrow B = B^m(1) \), \( \varepsilon > 0 \), which are \( \lambda \)-Lipschitz (diffeomorphisms) on all "slices" \( \tilde{K} \times k, k \in K \); these maps are constructed as above with the use of inverse exponential maps in \( \tilde{K} \) at the points over \( k \in K \), where the tangent spaces \( T_k(\tilde{K}) \) are identified with a single \( \mathbb{R}^m \) with a use of a frame in \( T(K) \) as it is done in section 13 in [GL 1983].

Let \( P \subset K \) be a subpseudomanifold of codimension \( n - 2 \), which represents the Poincare dual of \( h \) (which is a homology class with, a priori, infinite support) and let \( f_\epsilon : \tilde{X} \times P \rightarrow B \) be the maps obtained by composing \( \tilde{A} : \tilde{X} \rightarrow \tilde{K} \) and the restriction of \( F_\lambda \) to \( \tilde{X} \times P \),

\[
\tilde{f} = f_\lambda(\tilde{x},p) = F_\lambda(\tilde{A}(\tilde{x}),p).
\]

Clearly, this map \( f : X \times P \rightarrow B \), satisfies the assumptions on \( f \) in section 11.6, and stable SYSE-bound on the scalar curvature from 11.6 applies. QED.

**Conjecture A.** If a closed manifold \( X \) is SYS over a non-torsion cohomology class \( h \) in an aspherical space \( K \), then \( X \) admits no metrics with \( \Sc > 0 \).

This conjecture may be unrealistically strong but the special case of this, where \( K \) admits a complete (possibly singular) metric with non-positive curvature seems within reach.

Recall (see section 10) that a closed oriented manifold \( X \) is called \([\tilde{\uparrow}^0]\)-oversymplectic if

- a multiple of the fundamental cohomology class of \( X \) decomposes into product of one and two dimensional classes,

\[
k \cdot [X] = h_1 \sim ... \sim h_m,
\]

and

- \( X \) the classes \( h_i \) vanish in the cohomology of the universal covering \( \tilde{X} \).

Also recall (see section 10) that \([\tilde{\uparrow}^0]\)-oversymplectic manifolds, the universal covers of which are spin, carry no metrics with \( \Sc > 0 \).

Probably, the spin condition is redundant; moreover, one may merge this with the above A as follows.

**Conjecture B.** Products of manifolds \( X \) as in the above A by \([\tilde{\uparrow}^0]\)-oversymplectic ones admit no metrics with \( \Sc > 0 \).

### 11.12 A Few Geometric Problems and Conjectures.

**Conjecture C.** If a closed manifold \( V_0 \) of dimension \( n - 1 \geq 5 \), admits no metric with \( \Sc > 0 \) then Riemannian bands \( V \) diffeomorphic to \( V_0 \times [-1,1] \) which have \( \Sc(V) \geq \sigma > 0 \), satisfy the sharp width inequality,

\[
\text{width}(V) \leq 2\pi n \sqrt{\frac{n - 1}{\sigma n}}.
\]

**Conjecture D.** Let \( g_0 \) stands for the standard Riemannian metric on the unit sphere \( S^n \) with the sectional curvature 1.
If a Riemannian metric $g$ on $S^n$ minus a point satisfies

$$g \geq g_0 \text{ and } Sc(g) \geq Sc(g_0) = n(n-1),$$

then $g_0 = g$.

(If $g$ is complete, this follows, by the relative index theorem for the Dirac operator, see [Li 1998] and (8) in section 10)

CONJECTURE D'. Let $X$ be closed $n$-manifold, such that $X$ minus a point admits no complete metric with $Sc > 0$.

Let $V$ be obtained by removing a small open $n$-ball from $X$, i.e. $V = X \setminus B_{x_0}(\varepsilon)$, and let $g$ be a metric on $V$ with $Sc(g) \geq \sigma > 0$. If the $\rho$-neighbourhood with respect to $g$ of the boundary sphere $S^{n-1} = \partial V = \partial B_{x_0}(\varepsilon)$ is homeomorphic to $S^{n-1} \times [0,1]$, then

$$\rho \leq \frac{20}{\sqrt{\sigma}}.$$

(If $X$ is a SYS-manifold, then metrics $g$ with $Sc(g) \geq \sigma$ on $V$ do satisfy this inequality as it follows by Schoen-Yau’s kind of argument adapted to manifolds with boundaries as in section 11.6.

On the other hand, the conjecture must be vacuous for simply connected manifolds $X$, since $X \setminus \{x_0\}$ for such an $X$ contracts to an $(n-2)$-subpolyhedron in $X \setminus \{x_0\}$, which, most probably, implies that $X \setminus \{x_0\}$ admits a complete metric with $Sc > 0$.)

CONJECTURE E. Let $V$ be a Riemannian manifold homeomorphic to $T^2 \times [-1,1]$ with sectional curvature everywhere $\geq 1$. Then (this was already mentioned in section 3)

$$\text{width}(V) = \text{dist}(\partial_-(V), \partial_+(V)) \leq \pi/2,$$

(The simplest unsettled case is where $V$ is a domain in $S^3$ or, more generally if it admits an isometric embedding or immersion into $S^3$.

Below is a far reaching generalisation of the spherical case of E.

CONJECTURE $E_{\infty}$. Let $Y \subset S^N$, $N = n, n+1, \ldots, \infty$, be a submanifold homeomorphic to the product of $n$ closed manifolds of dimensions $\geq 1$, e.g. homeomorphic to the $N$-torus and let $U \supset Y$ be a neighbourhood of $Y$ in $S^N$ which admits a retraction to $Y$. Then

$$\text{dist}(Y, \partial U) \leq \arcsin \frac{1}{\sqrt{n}}.$$

But, in reality, one has no estimate for this distance even for high codimensional tori in spheres, which suggests the following conjecture opposite to $E_{\infty}$.

CONJECTURE $-E$. Every compact smooth manifold $Y^n$ of dimension $n$ admits a smooth embedding to the sphere $S^{2n}$ such that all principal curvatures of the image satisfy

$$\text{curv}(Y^n \subset S^{2n}) \leq \text{const} < \infty,$$

say for $\text{const} = 1000$.

It is hard to believe in the validity of either $E_{\infty}$ or $-E$, but something in between may be true, e.g. the following.
Conjecture E\textsubscript{7ν}. The minimal constant $\beta$, such that the $n$-torus admits an smooth immersion to $S^{n+1}$ with principal curvatures $\leq \beta$ is asymptotic, for $n \to \infty$, to

$$\text{const} \cdot n^\beta \text{ for some } \beta > 1.$$ 

Problem F. Let $U \subset \mathbb{R}^N$ and $V \subset \mathbb{R}^n$, $n \leq N$, be open subsets, e.g. balls $B^N(r)$ and $B^n(R)$, $R \geq r$. Evaluate the minimal $\beta = \beta(U,V) > 0$, such that $V$ admits a smooth locally expanding immersion/embedding$^{51}$ to $U$ with the principal curvatures $\leq \beta$.

In Conclusion. The above A - F are only tips of the iceberg of what we don’t know about the scalar curvature and nearabouts.

(An outline of this "iceberg" is given in [Gr 2017].)

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$^{51}$A a smooth map $f : V \to U$ is locally expanding if the differential $Df : T(V) \to T(U)$ doesn’t decrease the norms of the tangent vectors, $\|Df(\tau)\| \geq \|\tau\|$ for all $\tau \in T(V)$.  

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