Some extensions of the Prékopa–Leindler inequality using Borell’s stochastic approach

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Abstract

We present an abstract form of the Prékopa–Leindler inequality that includes several known—and a few new—related functional inequalities on Euclidean spaces. The method of proof and also the formulation of the new inequalities are based on Christer Borell’s stochastic approach to Brunn–Minkowski type inequalities.

1 Introduction and main statement

The Brunn–Minkowski inequality asserts that for Borel subsets $A, B$ of $\mathbb{R}^n$ and $t \in [0, 1]$, the volume of the Minkowski combination

$$(1 - t)A + tB = \{(1 - t)a + tb : a \in A, b \in B\}$$

satisfies the inequality $|(1 - t)A + tB| \geq |A|^{1-t}|B|^t$, where $|E|$ denotes the volume of a Lebesgue-measurable subset $E$ of $\mathbb{R}^n$. There is a long story of functional generalizations of this inequality, that we do not recall here; let us just mention that Borell’s 1975 paper \cite{5} remains a milestone in the subject. A somewhat definitive form is given by the following theorem.

**Theorem 1.1** (Prékopa–Leindler inequality). Let $t \in [0, 1]$ and let $f_0, f_1, g : \mathbb{R}^n \to \mathbb{R} \cup \{+\infty\}$ be Borel functions such that, for every $x_0, x_1 \in \mathbb{R}^n$,

$$g((1 - t)x_0 + tx_1) \leq (1 - t)f_0(x_0) + tf_1(x_1).$$

Then

$$\int_{\mathbb{R}^n} e^{-g(x)} \, dx \geq \left(\int_{\mathbb{R}^n} e^{-f_0(x)} \, dx\right)^{1-t} \left(\int_{\mathbb{R}^n} e^{-f_1(x)} \, dx\right)^t.$$
Accepting the value $+\infty$ enables us to reach directly indicator functions $1_E = e^{-f_E}$, by letting $f_E$ be 0 on $E$ and $+\infty$ outside. However, we can restrict ourselves to Borel functions that are not Lebesgue-almost everywhere equal to $+\infty$. Such Borel functions $f$ will be said to be $L$-proper, which is equivalent to saying that $\int_{\mathbb{R}^n} e^{-f(x)} \, dx > 0$.

One can reasonably argue that the interest of the Prékopa–Leindler inequality resides not only in its consequences, which are numerous (some are recalled for instance in [8, 11]), but also in the emphasis it has put on log-concavity, and in the related techniques of proof it has originated, such as mass transportation or semi-group techniques, and more recently $L^2$-methods (as in [7]).

Here, we will concentrate on Borell’s stochastic approach [6] to the inequality above. It somehow reduces the inequalities under study to the convexity of $|\cdot|^2$, the square of the Euclidean norm on $\mathbb{R}^n$. It will allow us to obtain some unexpected inequalities, for instance that of the following proposition.

**Proposition 1.2.** Let $f_0, f_1, g_0, g_1$ be four Borel functions from $\mathbb{R}^n$ to $\mathbb{R} \cup \{+\infty\}$ such that, for every $x_0, x_1 \in \mathbb{R}^n$,

\[ g_0(2x_0/3 + x_1/3) + g_1(x_0/3 + 2x_1/3) \leq f_0(x_0) + f_1(x_1). \]

Then

\[ \left( \int_{\mathbb{R}^n} e^{-g_0(x)} \, dx \right) \left( \int_{\mathbb{R}^n} e^{-g_1(x)} \, dx \right) \geq \left( \int_{\mathbb{R}^n} e^{-f_0(x)} \, dx \right) \left( \int_{\mathbb{R}^n} e^{-f_1(x)} \, dx \right). \]

We will see that it is rather natural to arrive at this type of inequality using Borell’s stochastic approach, whereas it seems not to be the case with other methods, for instance those based on transportation methods. The point here is to split the values of the functions $f_i$’s at some points into the values of two functions $g_j$’s at some related points. This is not interesting in the case where the functions $f_i$’s take only the values $+\infty$ and 0, and the functional inequality above does not give anything new when applied to the case where the functions $e^{-f_i}$’s are indicators of sets, as we will explain in Section 4 below.

The previous proposition and its proof suggest actually more general inequalities. Writing the conclusion as

\[ \sum_j -\log \left( \int_{\mathbb{R}^n} e^{-g_j} \right) \leq \sum_i -\log \left( \int_{\mathbb{R}^n} e^{-f_i} \right), \]

we may think about an extension of the results, where the finite families of functions $f_i, g_j$ are replaced by families $f_s, g_t$ depending upon continuous parameters $s, t$ (as for instance in [2]). In the “basic assumption” (1.1), the two values $x_0, x_1$ on the right-hand side of the inequality will be replaced, for example, by a selection $x = \{x(s)\}_{s \in [0,1]}$ of points of $\mathbb{R}^n$, and the values...
On the left-hand side will be obtained from a linear transformation $A$ acting on this data $x$, i.e. $y = Ax$. So, roughly speaking, under appropriate assumptions on the operator $A$, we may expect that if for "all" $x = \{x(s)\}$ we have

$$\int_0^1 g_t((Ax)(t)) \, dt \leq \int_0^1 f_s(x(s)) \, ds$$

then it will follow that

$$\int_0^1 -\log\left(\int_{\mathbb{R}^n} e^{-g_t}\right) \, dt \leq \int_0^1 -\log\left(\int_{\mathbb{R}^n} e^{-f_s}\right) \, ds.$$  

Actually, there was no reason, when replacing the sums by integrals, to use the "uniform" distributions $dt$ and $ds$ rather than probability measures $\mu(dt)$ and $\nu(ds)$ on $[0,1]$, which include the discrete case when these measures are convex combinations of Dirac measures. Anyway, the main question is to understand what the appropriate conditions are to impose on the linear operator $A$.

Several points must be set before proceeding. We say that a real function $F$ on a measure space $(\Omega, \Sigma, \mu)$ is $\mu$-semi-integrable if at least one of $F^+ = \max(F,0)$ or $F^- = \max(-F,0)$ is $\mu$-integrable. The integral of $F$ takes then a definite value in $[-\infty, +\infty]$. This assumption is needed for $F(s) = -\log\left(\int_{\mathbb{R}^n} e^{-f_s}\right)$ in order to make sense of the preceding integrals.

We introduce the following abstract setting.

**Setting 1.** We are given

- Two measure spaces $X_1 = (\Omega_1, \Sigma_1, \mu_1)$ and $X_2 = (\Omega_2, \Sigma_2, \mu_2)$, where $\Sigma_i$ is a $\sigma$-algebra of subsets of $\Omega_i$ and $\mu_i$ is a finite measure, $i = 1, 2$. We assume that $\Omega_1$ is a Polish topological space, and $\Sigma_1$ is its Borel $\sigma$-algebra.

- An integer $n \geq 1$ and a continuous linear operator

  $$A : L^2(X_1, \mathbb{R}^n) \to L^2(X_2, \mathbb{R}^n),$$

  where the $L^2$-norms of the $\mathbb{R}^n$-valued functions are computed with respect to the Euclidean norm $| \cdot |$ on $\mathbb{R}^n$ and to the measures $\mu_1$ and $\mu_2$, respectively. We assume that

  (i) the operator $A$ satisfies the norm condition $\|A\| \leq 1$,

  (ii) the operator $A$ acts as identity operator on the constant vector valued functions, i.e., for any $v_0 \in \mathbb{R}^n$, the constant function $\Omega_1 \ni s \mapsto v_0$ is sent by $A$ to the constant function $\Omega_2 \ni t \mapsto v_0$.

- Two families $\{f_s\}_{s \in \Omega_1}$ and $\{g_t\}_{t \in \Omega_2}$ of Borel functions from $\mathbb{R}^n$ to $\mathbb{R} \cup \{+\infty\}$ satisfying
(iii) the functions \( (s, x) \mapsto f_s(x) \) and \( (t, x) \mapsto g_t(x) \) are measurable with respect to the \( \sigma \)-algebras \( \Sigma_i \otimes \mathcal{B}_{\mathbb{R}^n} \), \( i = 1, 2 \), respectively, the notation \( \mathcal{B}_{\mathbb{R}^n} \) being for the Borel \( \sigma \)-algebra of \( \mathbb{R}^n \).

(iv) the functions

\[
\Omega_1 \ni s \mapsto \log \left( \int_{\mathbb{R}^n} e^{-f_s(x)} \, dx \right) \quad \text{and} \quad \Omega_2 \ni t \mapsto \log \left( \int_{\mathbb{R}^n} e^{-g_t(x)} \, dx \right)
\]

are semi-integrable with respect to \( \mu_1, \mu_2 \), respectively.

Unfortunately, there is a tradeoff between the generality of the statement we can reach and the technical assumptions that are required in the proof. We will start with a fairly general situation. In most applications, the technical assumptions on the functions in the statement below are either easy to impose or to discard, as explained for instance in Remark 1.4 and as shown in Theorem 1.6 below. So, our most abstract version of the Prékopa–Leindler inequality reads as follows.

**Theorem 1.3.** Under Setting 1 with \( \mu_1 \) and \( \mu_2 \) having the same finite mass, \( \mu_1(\Omega_1) = \mu_2(\Omega_2) < +\infty \), we make the additional assumptions on the functions:

- for every \( s \in \Omega_1 \), the function \( f_s \) is non-negative, and for every \( t \in \Omega_2 \), the function \( g_t \) is non-negative and lower semicontinuous,
- for some \( \varepsilon_0 > 0 \), we have that

\[
(1.2) \quad \int_{\Omega_1} \log \left( \int_{\mathbb{R}^n} \exp \left( -f_s(x) - \varepsilon_0 |x|^2 \right) \, dx \right) \, d\mu_1(s) < +\infty.
\]

Then, if for every \( \alpha \in L^2(X_1, \mathbb{R}^n) \) we have

\[
(1.3) \quad \int_{\Omega_2} g_t((A\alpha)(t)) \, d\mu_2(t) \leq \int_{\Omega_1} f_s(\alpha(s)) \, d\mu_1(s),
\]

it follows that

\[
(1.4) \quad \int_{\Omega_2} -\log \left( \int_{\mathbb{R}^n} e^{-g_t(x)} \, dx \right) \, d\mu_2(t) \leq \int_{\Omega_1} -\log \left( \int_{\mathbb{R}^n} e^{-f_s(x)} \, dx \right) \, d\mu_1(s).
\]

**Remark 1.4.** We can easily relax the restrictions \( f_s(x), g_t(x) \geq 0 \). Suppose indeed that \( f_s(x) \geq -a(s), g_t(x) \geq -b(t) \), where \( a(s), b(t) \) are non-negative functions on \( \Omega_1, \Omega_2 \) that are \( \mu_1, \mu_2 \)-integrable respectively. Assuming, as we may, that \( \int_{\Omega_1} a \, d\mu_1 = \int_{\Omega_2} b \, d\mu_2 \), we see that the “basic assumption” (1.3) and the conclusion (1.4) are unchanged when passing from \( f_s, g_t \) to the non-negative functions \( f_s + a(s), g_t + b(t) \). So, in the theorem above, we are free to assume only that the functions are bounded from below in the way described in the latter discussion.
Remark 1.5. By classical arguments of measure theory, we may replace \( f_s \) and \( f_t \) l.s.c. such that \( f_s \leq f_t \) and \( \int_{\mathbb{R}^n} e^{-f_s} \leq \int_{\mathbb{R}^n} e^{-f_t} \), but we do not know how to do it on the \( g_t \) side in a way that (1.3) remains true. However, when the family \( \{ g_t \} \) consists of a single function \( g \), it is easy to replace \( g \) by a l.s.c. function. The real issue is with the values of the \( f_s \) functions that are equal to \(+\infty\). If \( f_s, g_t \) are merely non-negative Borel functions, with \( f_s \) locally bounded, it is possible to reduce the problem to continuous functions \( \{ f_s \} \) and \( \{ g_t \} \) by using convolution with non-negative compactly supported kernels, hence reducing this case to the preceding theorem.

On the other hand, it is hard to believe that our l.s.c. assumption is necessary for the validity of Theorem 1.3. We rather tend to think that the result is true for general Borel functions (as we can prove it in the “discrete case” of Theorem 1.6; see also Remark 4.5).

Suppose that the conditions of Setting 1 and Theorem 1.3 are satisfied for \( \{ f_s \} \) and \( \{ g_t \} \). Using the “norm condition” (i), we see that the basic assumption (1.3) remains true if we add the same multiple \( \varepsilon |x|^2 \) of \( |x|^2 \), \( \varepsilon > 0 \), to all the functions \( f_s \) and \( g_t \). We can see that after this addition, the other conditions of Setting 1 and Theorem 1.3 remain obviously true, with two exceptions that are either less obvious or not always true: the semi-integrability condition (iv) remains true because \( f_s \) and \( g_t \) are also assumed to be non-negative, thus \( \int_{\mathbb{R}^n} e^{-f_s(n(x)-\varepsilon|x|^2)} dx \leq C(\varepsilon) \) (and the same for \( g_t \)), and if we assume \( 0 < \varepsilon < \varepsilon_0 \), then the condition (1.2) remains true, with \( \varepsilon_0 \) replaced by \( \varepsilon_0 - \varepsilon \). It follows that the conclusion (1.4) holds if we replace the inside integration with respect to the Lebesgue measure on \( \mathbb{R}^n \) by integration with respect to the isotropic Gaussian probability measure \( \gamma_{n,\tau} \) on \( \mathbb{R}^n \) defined by \( d\gamma_{n,\tau}(x) = e^{-|x|^2/2\tau} dx/((2\pi\tau)^{n/2}) \), provided \( 2\tau > \varepsilon_0^{-1} \).

Actually, the proof of Theorem 1.3 will start with the Gaussian case and obtain the Lebesgue measure case from it, the Lebesgue case being the “flat” extremal case when \( \tau \to +\infty \). Note that, indeed, the (log of the) normalization constant \( (2\pi\tau)^{n/2} \) on the two sides of (1.4) cancels out since \( \mu_1 \) and \( \mu_2 \) have the same finite mass.

In many applications, \( X_1 \) and \( X_2 \) are finite probability spaces, and then we work with finite families of objects parameterized by \( \Omega_1 \) and \( \Omega_2 \), or rather by the supports \( \text{supp}(\mu_1) \) and \( \text{supp}(\mu_2) \); in particular, the mappings \( \alpha : \Omega_1 \to \mathbb{R}^n \) are families of \( |\Omega_1| \) vectors of \( \mathbb{R}^n \) and the linear operator

\[
A : (\mathbb{R}^n)^{|\Omega_1|} \to (\mathbb{R}^n)^{|\Omega_2|}
\]

is norm-one for the operator norm associated to the \( l^2 \)-norms weighted by the \( \mu_i \)’s, with the property that the vector \( (x, \ldots, x) \in (\mathbb{R}^n)^{|\Omega_1|} \) is sent to \( (x, \ldots, x) \in (\mathbb{R}^n)^{|\Omega_2|} \) for every \( x \in \mathbb{R}^n \). In this case, we can relax the technical assumptions that were made in Theorem 1.3.

Theorem 1.6. Under Setting 1, assume in addition that \( \mu_1 \) and \( \mu_2 \) are measures with finite support and with \( \mu_1(\Omega_1) = \mu_2(\Omega_2) < +\infty \). Then the
assumption (1.3) implies (1.4) with no further restriction on the functions \( \{f_s\} \) and \( \{g_t\} \).

Let us examine the first situations that one encounters when \( \Omega_1 \) and \( \Omega_2 \) are finite, with \( \mu_1(\Omega_1) = \mu_2(\Omega_2) = 1 \).

- The case \( |\Omega_1| = |\Omega_2| = 1 \) is trivial. One has necessarily \( A(x) = x \) by (ii), and the statement amounts to the monotonicity of the integral.

- Assume \( |\Omega_1| = 1 \) and \( |\Omega_2| = 2 \). So \( \Omega_2 = \{0, 1\} \), say, and \( \mu_2 = (1-t)\delta_0 + t\delta_1 \), \( t \in [0, 1] \). The map \( A : \mathbb{R}^n \to \mathbb{R}^n \times \mathbb{R}^n \) ought to be \( A(x) = (x, x) \), which satisfies both required conditions, and the statement asserts that if the functions \( g_0, g_1, f \) satisfy \( (1-t)g_0(x) + tg_1(x) \leq f(x) \) then \( (\int e^{-g_0})^{1-t}(\int e^{-g_1})^t \geq \int e^{-f} \). This is just Hölder’s inequality.

- Assume \( |\Omega_1| = 2 \) and \( |\Omega_2| = 1 \). Here \( \Omega_1 = \{0, 1\} \), say, and \( \mu_1 = (1-t)\delta_0 + t\delta_1 \), \( t \in [0, 1] \). Then we can take \( A : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n \) to be \( A(x_0, x_1) = (1-t)x_0 + tx_1 \) (actually this is the only possible choice, as explained in Remark 1.9). This map will satisfy the required assumptions, by the convexity of the norm squared. The statement asserts that if the functions \( g, f_0, f_1 \) satisfy \( g((1-t)x_0 + tx_1) \leq (1-t)f_0(x_0) + tf_1(x_1) \) for all \( (x_0, x_1) \in \mathbb{R}^n \times \mathbb{R}^n \), then \( \int e^{-g} \geq (\int e^{-f_0})^{1-t}(\int e^{-f_1})^t \). This is the Prékopa-Leindler inequality.

- Assume \( |\Omega_1| = |\Omega_2| = 2 \). This is the first case where something new appears. Let us illustrate this by an example. Assume \( \Omega_1 = \Omega_2 = \{0, 1\} \) and \( \mu_1 = \mu_2 = \frac{1}{2}\delta_0 + \frac{1}{2}\delta_1 \). Consider the map \( A : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n \times \mathbb{R}^n \) defined by

\[
A(x_0, x_1) = \left(2x_0/3 + x_1/3, x_0/3 + 2x_1/3\right).
\]

We are in Setting 1 since \( A(x, x) = (x, x) \) and \( |2x_0/3 + x_1/3|^2 + |x_0/3 + 2x_1/3|^2 \leq |x_0|^2 + |x_1|^2 \). The abstract statement then reduces exactly to Proposition 1.2 above.

In the next section, we present Borell’s approach and establish in Proposition 2.4 a Gaussian version of Theorem 1.3; the proof of this proposition can be considered as the heart of the present paper. In Section 3, we present the proofs of Theorems 1.3 and 1.6. Then, in the following section, we discuss some consequences of it. In Section 5 we present a generalization of Theorem 1.3 when the functions \( f_s \) and \( g_t \) live on Euclidean spaces of different dimensions. The result will include as particular cases the Brascamp–Lieb inequality (in the geometric form) and its reverse form devised by Franck Barthe [1]. Several technical proofs that have little geometric interest, and involve mostly measure theoretic arguments, are gathered in Section 6.
2 Borell stochastic approach and Gaussian inequality

Borell’s stochastic proof of the Prékopa–Leindler inequality relies on the representation formula given in the next lemma. Let \((B_r)_{r \geq 0}\) be a standard Brownian motion with values in \(\mathbb{R}^n\), starting at 0, with filtration \(\mathcal{F} = (\mathcal{F}_r)_{r \geq 0}\). Let \(P_r = e^{r \Delta/2}, r \geq 0\), be the heat semigroup on \(\mathbb{R}^n\) associated with this Brownian motion,

\[
(P_r f)(x) = \mathbb{E} f(x + B_r) = \int_{\mathbb{R}^n} f(x + y) e^{-|y|^2/(2r)} \frac{dy}{(2\pi r)^{n/2}}, \quad x \in \mathbb{R}^n,
\]

for \(f\) bounded and continuous on \(\mathbb{R}^n\) and \(r > 0\). An \(\mathbb{R}^n\)-valued drift \(u = \{u_r\}_{r \leq T}\) will be called of class \(D_2\) on \([0, T]\) if it is \(\mathcal{F}\)-progressively measurable on \([0, T]\) and

\[
\mathbb{E} \int_0^T |u_r|^2 \, dr < +\infty.
\]

Lemma 2.1. Let \(T > 0\) be fixed. For every bounded continuous real function \(f : \mathbb{R}^n \to \mathbb{R}\), we have

\[
(2.1) \quad - \log P_T (e^{-f})(0) = \inf_u \mathbb{E} \left[ f(B_T + \int_0^T u_r \, dr) + \frac{1}{2} \int_0^T |u_r|^2 \, dr \right],
\]

where the infimum is taken over \(\mathbb{R}^n\)-valued drifts \(\{u_r\}_{r \leq T}\) of class \(D_2\). Moreover, the infimum is attained.

Proof (see Borell [6]). We begin by assuming that \(f\) is bounded and has bounded derivatives of order \(\leq 2\). For a drift \(u = \{u_r\}_{r \leq T}\) of class \(D_2\), we define \(X^u_r := B_r + \int_0^r u_\rho \, d\rho\), which satisfies the stochastic differential equation

\[
X^u_0 = 0, \quad dX^u_r = dB_r + u_r \, dr
\]

on the interval \([0, T]\). For \(0 \leq r \leq T\), define \(f_r = f^T_r\) by \(e^{-f_r} = P_{T-r} e^{-f}\), that is to say

\[
(2.2) \quad f_r(x) = - \log(P_{T-r} e^{-f})(x), \quad x \in \mathbb{R}^n.
\]

The function \((r, x) \mapsto f_r(x)\) on \((0, T) \times \mathbb{R}^n\) satisfies the partial differential equation

\[
\partial_r f_r = - \frac{1}{2} \Delta f_r + \frac{1}{2} |\nabla f_r|^2.
\]

By a direct application of the Itô formula, we see that the process

\[
M_r := f_r(X^u_r) + \frac{1}{2} \int_0^r |u_\rho|^2 \, d\rho, \quad r \in [0, T],
\]

is a submartingale for any drift \(u\) in \(D_2\), since

\[
dM_r = \nabla f_r(X^u_r) \cdot dB_r + \frac{1}{2} |\nabla f_r(X^u_r) + u_r|^2 \, dr.
\]
This implies the “inequality case” of (2.1), namely, an upper bound of 
\(- \log(P_T e^{-f})(0)\) for every drift \(u\) in \(D_2\). Indeed, note that \(M_0 = f_0(X_0) = - \log P_T(e^{-f})(0)\) and \(f_T = f\), and so the inequality in (2.1) immediately follows by considering \(\mathbb{E} M_r\) at \(r = 0\) and \(r = T\). Moreover, if \(u_r = -\nabla f_r(X^u_r)\), i.e., if \(X^u_r\) is the process solving the stochastic differential equation

\[
(2.3) \quad X_0 = 0, \quad dX_r = dB_r - \nabla f_r(X_r) \, dr,
\]
then \(M_r\) becomes a martingale, thus giving an equality case in (2.1).

Assume now that \(f\) is bounded and continuous on \(\mathbb{R}^n\). Adding a constant to \(f\), we may suppose that \(f \geq 0\). Define \(f_r\) as in (2.2), and note that \(f_r\) is bounded above and \(\geq 0\). Since \(f\) is bounded, \(P_r e^{-f}\) is bounded away from 0, so the function \(f_{T-\varepsilon} = - \log(P_r e^{-f})\) has bounded derivatives of all orders, for every \(\varepsilon \in (0, T]\). Writing \(T_\varepsilon = T - \varepsilon\) and \(e^{-f_r} = P_{T_\varepsilon - r}(P_r e^{-f}) = P_{T_\varepsilon - r}(e^{-f_{T_\varepsilon}}), 0 \leq r \leq T_\varepsilon\), we are back to the “good setting” on \([0, T_\varepsilon]\). Hence the optimal representation by the martingale

\[
M_r = f_r(B_r + \int_0^r u_\rho \, d\rho) + \frac{1}{2} \int_0^r |u_\rho|^2 \, d\rho = M_0 + \int_0^r \nabla f_\rho(X_\rho) \cdot dB_\rho,
\]
with \(M_0 = f_0(0)\), \(u_\rho = -\nabla f_r(X_\rho)\) and \(X_r = B_r + \int_0^r u_\rho \, d\rho\), is valid for \(r \leq T_\varepsilon\). Since \(f_r \geq 0\), we see that \(\int_0^r |u_\rho|^2 \, d\rho \leq 2M_r\) and we obtain that

\[
\mathbb{E} |M_r - M_0|^2 = \mathbb{E} \left( \int_0^r |\nabla f_\rho(X_\rho)|^2 \, d\rho \right) = \mathbb{E} \left( \int_0^r |u_\rho|^2 \, d\rho \right) \leq 2 \mathbb{E} M_r = 2f_0(0).
\]

We have \(T^{-1} \mathbb{E} \left( \int_0^T |u_\rho|^2 \, d\rho \right) \leq \mathbb{E} \int_0^T |u_\rho|^2 \, d\rho \leq 2f_0(0)\), hence \(u \in D_2\), \(X_r\) converges a.s. and in \(L^2\) to \(X_T = B_T + \int_0^T u_\rho \, d\rho\). We see that \((M_r)_{r<T}\) is an \(L^2\)-bounded martingale, thus \(M_r\) converges in \(L^2\)-norm, as \(r \to T\), to a limit \(M_T\) such that \(\mathbb{E} M_T = M_0\). On the other hand, \(M_r\) converges almost surely to

\[
(2.4) \quad f(B_T + \int_0^T u_\rho \, d\rho) + \frac{1}{2} \int_0^T |u_\rho|^2 \, d\rho
\]
when \(r \to T\) since \(f_r\) converges locally uniformly to the bounded continuous function \(f\). This implies that \(M_T\) is equal to the expression in (2.3), hence the expectation of (2.1) is equal to \(M_0 = f_0(0)\), that is, it implies formula (2.1) with equality.

In the inequality case of (2.1), the drift \(u\) is in \(D_2\) by assumption, hence \((X^u_r)_{r<T}\) defined as above converges a.s. and in \(L^2\) to \(X^u_T\), as \(r \to T\). The submartingale \((M_r)_{r<T}\) is \(L_2\)-bounded, hence converges a.s. and in \(L^2\) to the expression in (2.4), and the result follows.

**Remark 2.2.** If \(f\) is bounded and upper semicontinuous on \(\mathbb{R}^n\), then for every \(x \in \mathbb{R}^n\) and \(\varepsilon > 0\), there is \(r_0 < T\) and a neighborhood \(V\) of \(x\) such that \((P_{T-r} e^{-f})(y) > e^{-f(x) - \varepsilon}\) for \(y \in V\), \(r_0 < r < T\), that is to say,
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(a) \( f_r(y) < f(x) + \varepsilon \). When \( f \) is lower semicontinuous, the inequality is reversed, (b) \( f_r(y) > f(x) - \varepsilon \). When \( f \) is u.s.c. it follows from (a) that in the inequality case of \( 2.1 \), the limit of \( (M_r)_{r<T} \) as \( r \to T \) is less than or equal to the expression in \( 2.1 \), so the inequality case remains true. For every bounded Borel function \( f \), we can find \( \tilde{f} \) u.s.c. such that \( \tilde{f} \leq f \) and \( \int_{\mathbb{R}^n} e^{-\tilde{f}} d\gamma \simeq \int_{\mathbb{R}^n} e^{-f} d\gamma \). This implies that the inequality case in \( 2.1 \) is true for every bounded Borel function \( f \).

We shall need more than the case of bounded functions. The proof of the next lemma will be given in Section 6; it requires a closer look at the argument given above.

**Lemma 2.3.** Formula \( 2.1 \) remains valid when \( f \) is continuous, bounded below and satisfies an exponential upper bound of the form

\[
(2.5) \quad f(x) \leq ae^{b|x|}, \quad a, b \geq 0, \quad x \in \mathbb{R}^n. 
\]

The “inequality case” in \( 2.1 \) is valid for any bounded below continuous function \( f \).

The next proposition provides a rather direct and simple link between Borell’s lemma and our Theorem.

**Proposition 2.4.** Under Setting 1, assume that \( f_s, g_t \) are continuous \( \geq 0 \) on \( \mathbb{R}^n \) (or bounded from below as in Remark 1.4), and that \( f_s \) satisfies the following exponential bound: there are non-negative measurable functions \( a(s), b(s) \) on \( \Omega_1 \) such that

\[
(2.6) \quad f_s(x) \leq a(s)e^{b(s)|x|}, \quad x \in \mathbb{R}^n.
\]

Then, for every isotropic Gaussian probability measure \( \gamma = \gamma_{n, \tau} \) on \( \mathbb{R}^n \), the basic assumption \( 1.3 \) implies that

\[
(2.7) \quad \int_{\Omega_2} - \log \left( \int_{\mathbb{R}^n} e^{-g_t(x)} d\gamma(x) \right) d\mu_2(t) \leq \int_{\Omega_1} - \log \left( \int_{\mathbb{R}^n} e^{-f_s(x)} d\gamma(x) \right) d\mu_1(s).
\]

As seen from the proof below of Theorem 1.6 (which indeed reduces the study to the situation of this Proposition), we can remove the additional assumptions on \( f_s \) and \( g_t \) when the measures \( \mu_1 \) and \( \mu_2 \) have finite support.

**Proof.** The proof will be an application of formula \( 2.1 \), as extended in Lemma 2.3 to the functions \( f_s \) and \( g_t \). We may assume that the right-hand side of \( 2.7 \) is not equal to \( +\infty \). The Gaussian measure \( \gamma = \gamma_{n, \tau} \) is the distribution of \( B_T \) for \( T = \tau > 0 \), so that

\[
- \log\left( \int_{\mathbb{R}^n} e^{-f_s(x)} d\gamma(x) \right) = - \log(P_T e^{-f_s})(0) < +\infty, \quad \mu_1\text{-a.e.}
\]
Let $\varepsilon > 0$ be given. By Lemma 2.3, for almost every $s \in \Omega_1$, we can introduce $U(s) \in D_2$, an almost optimal drift for the function $f_s$, $s \in \Omega_1$, namely, a drift $U(s) = \{U_r(s)\}_{0 \leq r \leq T}$ such that

$$\mathbb{E}\left[f_s\left(B_T + \int_0^T U_r(s) \, dr\right) + \frac{1}{2} \int_0^T |U_r(s)|^2 \, dr\right] < - \log(P_T e^{-f_s})(0) + \varepsilon.$$  

(2.8)

We will show later (Claim 6.3) that this process $\{U(s)\}_{s \in \Omega_1}$ can be chosen to be $\Sigma_1$-measurable. Note also that (2.8) and $f_s \geq 0$ ensure that

$$\mathbb{E} \int_0^T |U_r(s)|^2 \, d\mu_1(s) \leq 2 \left( \int_{\Omega_1} - \log(P_T e^{-f_s})(0) \, d\mu_1(s) + \varepsilon \mu_1(\Omega_1) \right) < +\infty.$$  

(2.9)

Assume that the Brownian motion $(B_r)$ is defined on a probability space $(E, \mathcal{A}, \mathbb{P})$. We have a $\mathbb{R}^n$-valued random process $U$, that will be denoted by one of

$$U(s, r, \omega) = U_r(s)(\omega) = U_r(s, \omega) = U_{r, \omega}(s), \quad s \in \Omega_1, \ r \in [0, T], \ \omega \in E.$$  

By (2.9), we know that

$$U \in L^2(\Omega_1 \times [0, T] \times E, \mathbb{R}^n) = L^2([0, T] \times E, L^2(\Omega_1, \mathbb{R}^n)).$$

We shall estimate $P_T(e^{-g_t})$ using the inequality case of formula (2.1) given by Lemma 2.3 with the drift $\{V_r(t)\}_{r \leq T} = \{AU_r(t)\}_{r \leq T}$, namely

$$V_{r, \omega}(t) := A(U_{r, \omega}(t)) = A(s \mapsto U_{r, \omega}(s))(t) \in \mathbb{R}^n, \quad t \in \Omega_2,$$

where $U_{r, \omega} \in L^2(X_1, \mathbb{R}^n)$ for almost every $r, \omega$. We shall use the basic assumption (1.3) on the families $\{f_s\}$ and $\{g_t\}$ for the random function $\alpha_\omega = B_T(\omega) + \beta_\omega$, where $\beta_\omega$ is defined by

$$\beta_\omega(s) := \int_0^T U_r(s, \omega) \, dr,$$

(2.11)

and where we consider $B_T(\omega)$ as a constant function of the $s$ variable. We know by (2.9) that $\beta_\omega$ (and $\alpha_\omega$) are in $L^2(X_1, \mathbb{R}^n)$ for almost every $\omega$. The constant functions condition (ii) on $A$ ensures that

$$(A\alpha_\omega)(t) = A(B_T(\omega) + \beta_\omega)(t) = B_T(\omega) + (A\beta_\omega)(t)$$

$$= B_T(\omega) + \int_0^T V_r(t, \omega) \, dr.$$  

(2.12)

As we said, we apply the inequality case of formula (2.1) for $g_t$ with the drift $\{V_r\}$ and then we integrate in $t$, in order to get that

$$\int_{\Omega_2} - \log(P_T e^{-g_t})(0) \, d\mu_2(t)$$

$$\leq \int_{\Omega_2} \mathbb{E}\left[g_t\left(B_T + \int_0^T V_r(t) \, dr\right) + \frac{1}{2} \int_0^T |V_r(t)|^2 \, dr\right] \, d\mu_2(t).$$

(2.10)
For future reference, we state an obvious consequence of (2.12),
\begin{equation}
(2.13) \quad g_t((A\alpha_\omega)(t)) = g_t(A(B_T(\omega) + \beta_\omega)(t)) = g_t(B_T(\omega) + (A\beta_\omega)(t)) = g_t(B_T(\omega) + \int_0^T V_r(t, \omega) \, dr).
\end{equation}

Using (1.3) and (2.13), we have on the set $E$ the pointwise inequality
\begin{equation}
(2.14) \quad \int_{\Omega_2} |V_r(t, \omega)|^2 \, d\mu_2(t) \leq \int_{\Omega_1} |U_r(s, \omega)|^2 \, d\mu_1(s).
\end{equation}

Finally
\begin{align*}
&\int_{\Omega_2} - \log(P_T e^{-g})(0) \, d\mu_2(t) \\
&\leq \int_{\Omega_1} \mathbb{E} \left[ f_s \left( B_T + \int_0^T U_r(s) \, dr \right) + \frac{1}{2} \int_0^T |U_r(s)|^2 \, dr \right] \, d\mu_1(s) \\
&< \int_{\Omega_1} - \log(P_T e^{-f})(0) \, d\mu_1(s) + \varepsilon \mu_1(\Omega_1).
\end{align*}

We conclude by letting $\varepsilon \to 0$.

As the reader has noticed, the proof is rather short, provided one has put forward the abstract properties contained in the four equations (2.10), (2.11), (2.13) and (2.14) that allow us to run Borell’s argument.

## 3 Proofs of Theorems 1.3 and 1.6

The proofs rely on Proposition 2.4. We shall explain how to pass from a Gaussian measure to the Lebesgue measure, and how to approximate our functions in order to meet the required technical assumptions (continuity and lower/upper bounds).

### 3.1 Proof of Theorem 1.6

Under Setting 1 in the discrete case, assume that $f_0, f_1, \ldots, f_p$ and $g_0, g_1, \ldots, g_q$ are Borel functions from $\mathbb{R}^n$ to $\mathbb{R} \cup \{+\infty\}$, and that for all points $x_0, x_1, \ldots, x_p$ in $\mathbb{R}^n$ we have
\begin{equation}
(3.1) \quad \sum_{j=0}^q \nu_j g_j \left( \sum_{i=0}^p a_{j,i} x_i \right) \leq \sum_{i=0}^p \mu_i f_i(x_i),
\end{equation}
where $\mu_i, \nu_j > 0$, $\sum_{i=0}^{p} \mu_i = \sum_{j=0}^{q} \nu_j = 1$, where the matrix $A = (a_{j,i})$ satisfies the norm condition (i) and the constant functions condition (ii), each $a_{j,i}$ being a $n \times n$ matrix acting from $\mathbb{R}^n$ to $\mathbb{R}^n$. We want to prove that

\begin{equation}
(3.2) \quad \sum_{j=0}^{q} -\nu_j \log \left( \int_{\mathbb{R}^n} e^{-g_j(x)} \, dx \right) \leq \sum_{i=0}^{p} -\mu_i \log \left( \int_{\mathbb{R}^n} e^{-f_i(x)} \, dx \right).
\end{equation}

If $\int_{\mathbb{R}^n} e^{-f_{i_0}} = 0$ for one $i_0$, then by the semi-integrability assumption (iv), the other $\int_{\mathbb{R}^n} e^{-f_i}$ are finite, the right-hand side of (3.2) is $+\infty$ and this case is obvious. We may therefore assume that all $f_i$ are L-proper. It follows that all $g_j, j = 0, \ldots, q$, are L-proper. Indeed, each set $A_i = \{ f_i < +\infty \}$ has positive Lebesgue measure, so we can find and fix a Lebesgue density point $x_i^{(0)}$ of $A_i$, for $i = 0, \ldots, p$. Then the set $U$ of $u \in \mathbb{R}^n$ such that $x_i^{(0)} + u \in A_i$ for all $i = 0, \ldots, p$, i.e., $U = \bigcap_{i=0}^{p} (A_i - x_i^{(0)})$, has positive measure. We know that $\sum_{i=0}^{p} a_{j,i} = I_n$ since $A$ preserves constant functions by (ii). We see from (3.1) that

\begin{align*}
\sum_{j=0}^{q} \nu_j g_j \left( u + \sum_{i=0}^{p} a_{j,i} x_i^{(0)} \right) &= \sum_{j=0}^{q} \nu_j g_j \left( \sum_{i=0}^{p} a_{j,i} (x_i^{(0)} + u) \right) \\
&\leq \sum_{i=0}^{p} \mu_i f_i (x_i^{(0)} + u) < +\infty
\end{align*}

for every $u \in U$, hence all $g_j$ are L-proper.

For $\varepsilon > 0$ and $i = 0, \ldots, p$, $j = 0, \ldots, q$, the functions $f_i, \varepsilon(x) = f_i(x) + \varepsilon |x|^2$, $g_j, \varepsilon(x) = g_j(x) + \varepsilon |x|^2$, still satisfy (3.1) by the assumption $\|A\| \leq 1$. We may reduce the problem to proving (3.2) for $f_i, \varepsilon; g_j, \varepsilon$, since we can pass to the limit as $\varepsilon \to 0$ in $\int_{\mathbb{R}^n} e^{-g_j(x) - \varepsilon |x|^2} \, dx$, $\int_{\mathbb{R}^n} e^{-f_i(x) - \varepsilon |x|^2} \, dx$, obtaining (3.2) by monotone convergence. In other words, we may keep $f_i, g_j$ but replace the Lebesgue measure in (3.2) by a Gaussian measure $d\gamma(x) = e^{-|x|^2} \, dx$. If $\int_{\mathbb{R}^n} e^{-g_{j_0}} \, d\gamma = +\infty$ for some $j_0$, then nothing to prove: the other integrals $\int_{\mathbb{R}^n} e^{-g_j} \, d\gamma$, $j \neq j_0$, are $> 0$ and the left-hand side of (3.2) is $-\infty$. Otherwise, for $N \in \mathbb{N}$, define $g_{j,N} = \min(g_j, N)$ and $f_{i,N} = \max(f_i, -N)$, that trivially satisfy (3.1), and observe that it is enough to give the proof for $f_{i,N}, g_{j,N}$; indeed, since $e^{-g_{j,0}} = e^{-\min(g_j, 0)} \leq e^{-g_j} + 1$ is integrable with respect to $d\gamma$, we may again pass to the (decreasing) limit in the integrals $\int_{\mathbb{R}^n} e^{-g_{j,N}} \, d\gamma$ as $N \to +\infty$, and use monotone convergence for $\int_{\mathbb{R}^n} e^{-f_{i,N}} \, d\gamma$.

Now we reduced the question to the case $g_j \leq N$ and $f_i \geq -N$. Thanks to the discrete situation, we may further assume that $f_{i_0}$ is bounded above by $2N/\mu_{i_0}$ for each $i_0$, since

\begin{align*}
\sum_{j=0}^{q} \nu_j g_j \left( \sum_{i=0}^{p} a_{j,i} x_i \right) - \sum_{i \neq i_0} \mu_i f_i (x_i) &\leq N + (1 - \mu_{i_0}) N < 2N,
\end{align*}

and for the same reason, we may also assume $g_{j_0}$ bounded below by $-2N/\nu_{j_0}$, while still keeping (3.1) true.
Finally, we restricted the problem to bounded Borel functions $f_i, g_j$ and a Gaussian measure $\gamma$. If all $f_i, g_j$ are translated by the same vector, then (3.1) remains true by the constant functions condition (ii), therefore (3.1) is stable by convolution with non-negative kernels. We may approximate in $L^1(\gamma)$-norm the functions $f_i, g_j$ by convolution with a compactly supported continuous non-negative kernel, keeping (3.1) and meeting the assumptions of Proposition 2.4. We obtain thus, for a sequence of continuous approximations $f_{i,k}$ and $g_{j,k}$, $k \in \mathbb{N}$, the inequality

$$\sum_{j=0}^{q} -\nu_j \log \left( \int_{\mathbb{R}^n} e^{-g_{j,k}} d\gamma \right) \leq \sum_{i=0}^{p} -\mu_i \log \left( \int_{\mathbb{R}^n} e^{-f_{i,k}} d\gamma \right).$$

Some subsequences of the sequence of continuous approximations tend almost everywhere to $f_i, g_j$ respectively, and we finish with the latter restricted problem by using the dominated convergence theorem.

This ends the proof of Theorem 1.6.

### 3.2 Proof of Theorem 1.3

Suppose that we try to obtain the conclusion (1.4) of Theorem 1.3 for $\{f_i\}$ and $\{g_i\}$ as a limit case of “good cases” for which the conclusion is known, say $\{f_{s,k}\}$ and $\{g_{t,k}\}$, $k \in \mathbb{N}$, such that $f_{s,k} \to f_s, g_{t,k} \to g_t$ when $k \to +\infty$. The next elementary lemma will help us to do it. Consider a measure space $(\Omega, \Sigma, \mu)$ and a measure $\nu$ on $(\mathbb{R}^n, \mathcal{B}_{\mathbb{R}^n})$, where $\mu$ and $\nu$ are $\sigma$-finite. Let $h_{s,k}(x), k \in \mathbb{N}$ and $h_s(x), s \in \Omega, x \in \mathbb{R}^n$ be $\Sigma \otimes \mathcal{B}_{\mathbb{R}^n}$-measurable from $\Omega \times \mathbb{R}^n$ to $\mathbb{R} \cup \{+\infty\}$. Define $H_k$ and $H$ by

$$e^{-H_k(s)} = \int_{\mathbb{R}^n} e^{-h_{s,k}(x)} d\nu(x), \quad e^{-H(s)} = \int_{\mathbb{R}^n} e^{-h_s(x)} d\nu(x).$$

These functions are $\Sigma$-measurable by the theory behind Fubini’s theorem. Note that

$$H^+(s) = \log^-(\int_{\mathbb{R}^n} e^{-h_s(x)} d\nu(x)), \quad H^-(s) = \log^+(\int_{\mathbb{R}^n} e^{-h_s(x)} d\nu(x)).$$

**Lemma 3.1.** Let $H_k(s), H(s)$ be defined by (3.3). Assume that $H_k$, $k \in \mathbb{N}$ and $H$ are $\mu$-semi-integrable.

(a) Suppose that $h_{s,k}(x) \not\geq h_s(x)$ pointwise on $\Omega \times \mathbb{R}^n$, and that $H_0(s) > -\infty$ for $\mu$-almost every $s \in \Omega$. Then:

(a1) $H_k(s) \not\geq H(s) \text{ } \mu$-a.e. and $\int_{\Omega} H(s) d\mu(s) \leq \limsup_k \int_{\Omega} H_k(s) d\mu(s)$.

(a2) If in addition $\int_{\Omega} H_0^-(s) d\mu(s) < +\infty$, then

$$\int_{\Omega} H(s) d\mu(s) = \lim_k \int_{\Omega} H_k(s) d\mu(s).$$
(b) Suppose that \( h_{s,k}(x) \searrow h_s(x) \) pointwise on \( \Omega \times \mathbb{R}^n \). Then:

(b1) \( H_k(s) \searrow H(s) \) pointwise on \( \Omega \), and

\[
\int_\Omega H(s) \, d\mu(s) \leq \liminf_k \int_\Omega H_k(s) \, d\mu(s).
\]

(b2) If in addition \( \int_\Omega H_0^+(s) \, d\mu(s) < +\infty \), then

\[
\int_\Omega H(s) \, d\mu(s) = \lim_k \int_\Omega H_k(s) \, d\mu(s).
\]

**Proof.** Apply successively the classical results of Integration Theory: the Fatou lemma, the monotone convergence theorem and the dominated convergence theorem. In case (a), we have \( e^{-h_{s,k}(x)} \searrow e^{-h_s(x)} \), and \( H_0(s) > -\infty \) allows us to apply dominated convergence to \( \nu \) and deduce that \( H_k(s) \nearrow H(s) \). Next, \( H_k^+(s) \nearrow H^+(s) \) and \( H_k^-(s) \searrow H^-(s) \). In \( \int_\Omega H = \int_\Omega H^+ - \int_\Omega H^- \) (that makes sense by the semi-integrability assumption), apply monotone convergence for \( H^+ \) and Fatou for \( H^- \). If \( \int_\Omega H_0^- \, d\mu < +\infty \), replace Fatou by dominated convergence for \( H^- \). The proof of (b) is similar and left to the reader. \( \square \)

**Proof of Theorem 3.3.** Since \( \mu_1 \) and \( \mu_2 \) have the same finite mass it is enough, as mentioned after the statement of the theorem, to have an inequality involving \( (P_T e^{-g_1})(0) \) and

\[
(P_T e^{-f_s})(0) = \int_{\mathbb{R}^n} e^{-f_s(x) - |x|^2/(2T)} \frac{dx}{(2\pi T)^{n/2}}, \quad 2T > 1/\varepsilon_0.
\]

The result will follow by letting \( T \to +\infty \). Indeed, \( f_s(x) + \varepsilon |x|^2 \) decreases to \( f_s(x), g_t(x) + \varepsilon |x|^2 \) decreases to \( g_t(x) \) when \( \varepsilon \searrow 0 \); for \( \varepsilon \in [0, \varepsilon_0] \), define \( F_\varepsilon(s), G_\varepsilon(t) \) as in (3.2), with \( \nu \) being the Lebesgue measure, that is to say, let \( e^{-F_\varepsilon(s)} = \int_{\mathbb{R}^n} e^{-f_s(x) - \varepsilon |x|^2} \, dx \) and use the similar expression for \( G_\varepsilon(t) \). By the semi-integrability condition (iv), \( G_0(t) \) is semi-integrable, and we may assume that \( G_0^-(t) \) is integrable, otherwise the left-hand side of (1.4) is \(-\infty\), an obvious case. We also know by the assumption (1.2) that \( F_\varepsilon^+(s) = \log^{-} (\int_{\mathbb{R}^n} e^{-f_s(x) - \varepsilon_0 |x|^2} \, dx) \) is integrable. This yields that \( F_\varepsilon(s) \) and \( G_\varepsilon(t) \) are semi-integrable for \( \varepsilon \in [0, \varepsilon_0] \). Use Lemma 3.1 (b) to see that \( F_\varepsilon(s) \to F(s) \), \( G_\varepsilon(t) \to G(t) \) for every \( s, t \). For the \( F \) side, we may use (b2) because \( F_\varepsilon^+ \) is integrable. We can therefore pass to the limit as \( \varepsilon \to 0 \) and conclude that

\[
\int_{\Omega_1} F_s(s) \, d\mu_1(s) = \int_{\Omega_1} -\log \left( \int_{\mathbb{R}^n} e^{-f_s(x) - \varepsilon |x|^2} \, dx \right) \, d\mu_1(s)
\]

\[
\to \int_{\Omega_1} -\log \left( \int_{\mathbb{R}^n} e^{-f_s} \right) \, d\mu_1(s).
\]

For the analogous expressions with \( g_t \), we use (b1) of Lemma 3.1.
Having reduced the problem to the Gaussian measure $\gamma = \gamma_{n, \tau}$, our goal is now to show how to relax the continuity assumption from Proposition 2.4. To this end, we shall introduce classical continuous approximations obtained by inf-convolution with large multiples of $x \mapsto |x|^2$. For working with these approximations, we shall need the existence of a selection $\alpha_0 \in L^2(X_1, \mathbb{R}^n)$ such that $\int_{\Omega_1} f_s(\alpha_0(s)) \, d\mu_1(s) < +\infty$, which is granted by Lemma 6.4 since we know by (1.2) that $s \mapsto \log\left( \int_{\mathbb{R}^n} e^{-f_s(x)} \, d\gamma(x) \right)$ is $\mu_1$-integrable when $2\tau > 1/\varepsilon_0$.

We fix $k > 0$ and define $f_{s,k}$ by the inf-convolution of $f_s$, $g_t$ with $h_k(x) = k|x|^2$,

$$ (3.4) \quad f_{s,k}(x) = \inf_{u \in \mathbb{R}^n} (f_s(x + u) + k|u|^2), \quad g_{t,k}(x) = \inf_{u \in \mathbb{R}^n} (g_t(x + u) + k|u|^2). $$

Clearly, $f_{s,k} \leq f_s$, $g_{t,k} \leq g_t$, and $f_{s,k}$, $g_{t,k}$ are continuous functions on $\mathbb{R}^n$. By Lemma 6.4, we may find negligible Borel sets $N_1 \in \Sigma_1$, $N_2 \in \Sigma_2$ such that $(s, x) \mapsto f_{s,k}(x)$, $(t, x) \mapsto g_{t,k}(x)$ are Borel functions on $(\Omega_1 \setminus N_1) \times \mathbb{R}^n$ and $(\Omega_2 \setminus N_2) \times \mathbb{R}^n$. We have that

$$ 0 \leq f_{s,k}(x) \leq f_s(\alpha_0(s)) + k|x - \alpha_0(s)|^2, \quad x \in \mathbb{R}^n, $$

fitting the exponential bound (2.5) needed to apply Proposition 2.4. Let $\alpha$ be in $L^2(X_1, \mathbb{R}^n)$. For any fixed $\varepsilon > 0$, we may find a measurable selection $u(s)$ (Lemma 6.4) such that

$$ f_s(\alpha(s) + u(s)) + k|u(s)|^2 - \varepsilon \leq f_{s,k}(\alpha(s)) \leq f_s(\alpha_0(s)) + k|\alpha(s) - \alpha_0(s)|^2. $$

Since $f_s \geq 0$, this shows that $u \in L^2(X_1, \mathbb{R}^n)$. We can write

$$ \int_{\Omega_2} g_{t,k}((A\alpha)(t)) \, d\mu_2(t) \leq \int_{\Omega_2} [g_t((A\alpha)(t) + (Au)(t)) + k|(Au)(t)|^2] \, d\mu_2(t), $$

which is bounded, using the basic assumption (1.3) and the norm condition $\|A\| \leq 1$, by

$$ \int_{\Omega_1} f_s(\alpha(s) + u(s)) + k|u(s)|^2 \, d\mu_1(s) \leq \int_{\Omega_1} f_{s,k}(\alpha(s)) \, d\mu_1(s) + \varepsilon \mu_1(\Omega_1). $$

Hence, $f_{s,k}$ and $g_{t,k}$ also satisfy the basic assumption. By Proposition 2.4, we conclude that

$$ \int_{\Omega_2} -\log\left( \int_{\mathbb{R}^n} e^{-g_{t,k}(x)} \, d\gamma(x) \right) \, d\mu_2(t) \leq \int_{\Omega_1} -\log\left( \int_{\mathbb{R}^n} e^{-f_{s,k}(x)} \, d\gamma(x) \right) \, d\mu_1(s). $$

When $k$ tends to infinity, $f_{s,k}$ increases to a l.s.c. function $\tilde{f}_s \leq f_s$, and $g_{t,k}(x)$ increases to $g_t(x)$ because $x \mapsto g_t(x)$ is l.s.c. on $\mathbb{R}^n$. We apply again Lemma 3.1 this time with $\nu = \gamma$, defining $F_k(s)$, $\tilde{F}(s) \leq F(s)$, $G_k(t)$, $G(t)$ from $f_{s,k}$, $\tilde{f}_s$, $f_s$, $g_{t,k}$, $g_t$ as in (3.3). Since the functions are $\geq 0$, $e^{-f_{s,k}(x)}$, $e^{-g_{t,k}(x)}$ are bounded by 1, we have $F_k(s)$, $G_k(t) \geq 0$ because $\gamma$ is a probability measure. Thus $F_0(s), G_0(t) > -\infty$ and $F_k(s) \rightarrow \tilde{F}(s), G_k(t) \rightarrow G(t)$ by (a). The conclusion follows, by (a1) for $F$, and by (a2) for $G$ since $G_0 = 0$. \qed
Remark 3.2. Assume that \( f_s, g_t \) are continuous \( \geq 0 \) on \( \mathbb{R}^n \). Let \( D \) be a countable dense subset of \( \mathbb{R}^n \). Since \( f_s \) and \( g_t \) are continuous on \( \mathbb{R}^n \), we may define the inf-convolution by

\[
  f_{s,k}(x) = \inf_{u \in D} (f_s(x + u) + k|u|^2), \quad g_{t,k}(x) = \inf_{u \in D} (g_t(x + u) + k|u|^2).
\]

It is now clear that \((s, x) \mapsto f_{s,k}(x), (t, x) \mapsto g_{t,k}(x)\) are \( \Sigma \otimes B_{\mathbb{R}^n} \)-measurable, as countable infima of measurable functions. Similarly, the possibility of selecting \( u(s) \) is now evident.

4 Other formulations and consequences

We start with a simple, natural situation where the assumptions of Theorem 1.3 are satisfied. Assume that \( \Omega \) is a Polish space, \( \Sigma \) its Borel \( \sigma \)-algebra and \( \mu \) a probability measure on \((\Omega, \Sigma)\). Take \( \Sigma_1 = \Sigma \), let \( \Sigma_2 \subset \Sigma \) be a sub-\( \sigma \)-algebra of \( \Sigma \), and let \( \mu_1 = \mu_2 = \mu \). Then the conditional expectation

\[
  A = \mathbb{E}[\cdot \mid \Sigma_2] : L^2(\Sigma, \mathbb{R}^n) \to L^2(\Sigma_2, \mathbb{R}^n) \subset L^2(\Sigma, \mathbb{R}^n)
\]

satisfies the norm condition (i) and the “constant functions condition” (ii) from Setting 1. An already interesting case is when we take \( \Sigma_2 \) to be trivial, \( \Sigma_2 = \{\emptyset, \Omega\} \), in which case \( A \) is simply the \( \mu \)-mean,

\[
  A\alpha = \int_{\Omega} \alpha(s) \, d\mu(s),
\]

and the space \( \Omega_2 \) can be then considered as being a one-point space, say \( \Omega_2 = \{0\} \). In this case, the family \( \{g_t\} \) consists of a single function \( g \) and Theorem 1.3 reads as:

**Corollary 4.1.** Let \( \Omega \) be a Polish space, \( \Sigma \) its Borel \( \sigma \)-algebra, \( \mu \) a probability measure on \((\Omega, \Sigma)\). Suppose that we are in Setting 1 with \((\Omega_1, \Sigma_1, \mu_1) = (\Omega, \Sigma, \mu)\) and \( \Omega_2 = \{0\} \). Let \( \{f_s\}_{s \in \Omega} \) satisfy the assumptions of Theorem 1.3 and let \( g \) be a bounded below l.s.c. function on \( \mathbb{R}^n \). If we have for every \( \alpha \in L^2(\Omega, \Sigma, \mu, \mathbb{R}^n) \) that

\[
  g \left( \int_{\Omega} \alpha(s) \, d\mu(s) \right) \leq \int_{\Omega} f_s(\alpha(s)) \, d\mu(s),
\]

then

\[
  -\log \left( \int_{\mathbb{R}^n} e^{-g} \right) \leq \int_{\Omega} -\log \left( \int_{\mathbb{R}^n} e^{-f_s} \right) \, d\mu(s).
\]

The Prékopa–Leindler inequality follows by taking \( \Omega \) to be a two point probability space, for instance \( \Omega = \{0, 1\} \), and taking \( \mu \) of the form \( \mu = (1-t)\delta_0 + t\delta_1 \) for some \( t \in [0, 1] \). If we replace the two point space (i.e., Bernoulli variables) by the unit circle \( S^1 = \{e^{i\theta} : \theta \in \mathbb{R}\} \) (i.e., Steinhaus variables), then we obtain:
Corollary 4.2. Under the assumptions of Corollary 4.1 with \( \Omega = S^1 \) and \( \mu = d\theta/(2\pi) \), let \( \{f_\xi\}_{\xi \in S^1} \) be non-negative (or properly bounded from below as in Remark 1.4) Borel functions on \( \mathbb{R}^n \) and let \( g \) be a bounded from below l.s.c. function on \( \mathbb{R}^n \). If for every \( \alpha \in L^2(S^1, \mathbb{R}^n) \), we have

\[
g \left( \int_0^{2\pi} \alpha(e^{i\theta}) \frac{d\theta}{2\pi} \right) \leq \int_0^{2\pi} f_{e^{i\theta}}(\alpha(e^{i\theta})) \frac{d\theta}{2\pi},
\]

then it follows that

\[
-\log \left( \int_{\mathbb{R}^n} e^{-g} \right) \leq \int_0^{2\pi} -\log \left( \int_{\mathbb{R}^n} e^{-f_{e^{i\theta}}} \right) \frac{d\theta}{2\pi}.
\]

A consequence of the previous Corollary is one of the Berndtsson’s plurisubharmonic extensions of the Prékopa theorem, the relatively easy “tube” case.

Corollary 4.3 (Berndtsson [3]). Let \( \varphi : \mathbb{C} \times \mathbb{C}^n \to \mathbb{R} \) be plurisubharmonic on \( \mathbb{C}^{n+1} \) and such that, for every \( z \in \mathbb{C} \) and \( w \in \mathbb{C}^n \), we have \( \varphi(z, w) = \varphi(z, \Re w) \). Then, the function

\[
\psi(z) = -\log \left( \int_{\mathbb{R}^n} e^{-\varphi(z,x)} \, dx \right)
\]

is subharmonic on \( \mathbb{C} \).

Proof. We will check that \( \psi \) is subharmonic at \( z = 0 \), say. We can assume that \( \varphi \) is bounded below for all \( z \) close to 0. We want to prove that \( \psi(0) \leq \int_0^{2\pi} \varphi(r e^{i\theta}) \frac{d\theta}{2\pi} \) for any fixed \( r > 0 \) small enough. We take \( r = 1 \) to simplify notations. Take \( g(x) = \varphi(0, x) \) and \( f_{e^{i\theta}}(x) := \varphi(e^{i\theta}, x) \) for \( x \in \mathbb{R}^n \subset \mathbb{C}^n \).

To conclude, it suffices to check that these functions satisfy the hypothesis in the previous corollary. Let \( \alpha \in L^2(S^1, \mathbb{R}^n) \) and let \( \widetilde{\alpha} \) be the harmonic extension of \( \alpha \) to the unit disc \( \mathbb{D} \). In particular \( \tilde{\alpha}(0) = \int_0^{2\pi} \alpha(e^{i\theta}) \frac{d\theta}{2\pi} \). We can write this \( \tilde{\alpha} \) as the real part \( \Re H \) of an holomorphic function \( H : \mathbb{D} \to \mathbb{C}^n \) such that \( H(0) = \tilde{\alpha}(0) \). We conclude by noticing that \( z \mapsto \varphi(z, H(z)) \) is subharmonic on \( \mathbb{D} \), and using \( \varphi(z, H(z)) = \varphi(z, \tilde{\alpha}(z)) \) we obtain that

\[
g \left( \int_0^{2\pi} \alpha(e^{i\theta}) \frac{d\theta}{2\pi} \right) = \varphi(0, H(0)) \leq \int_0^{2\pi} \varphi(e^{i\theta}, H(e^{i\theta})) \frac{d\theta}{2\pi} = \int_0^{2\pi} f_{e^{i\theta}}(\alpha(e^{i\theta})) \frac{d\theta}{2\pi}.
\]

Actually, it is easily seen and certainly known that the previous Corollary 4.1 can be deduced from the Prékopa–Leindler inequality, by discretizing \( \mu \) and by a simple induction procedure. Therefore, Corollary 4.1 and its
consequences only serves as motivation for the abstract setting above, but do not bring new information.

The situation is different with other instances of Theorem 1.3 such as Proposition 1.2 and the following general result. It seems difficult to guess the existence of such inequalities without having Borell’s proof in mind.

**Theorem 4.4.** Let $\mu$ be a Borel probability measure on $[0, 1]$ and set $m := \int t \, d\mu(t) \in [0, 1]$. Under Setting 1 with $\Omega_1 = \{0, 1\}$ and $\Omega_2 = [0, 1]$, $\mu_2 = \mu$, let $f_0$, $f_1$ and $\{g_t\}_{t \in [0, 1]}$ be bounded from below (as in Remark 4.5) Borel functions from $\mathbb{R}^n$ to $\mathbb{R} \cup \{\pm \infty\}$. Assume $g_t$ l.s.c. for every $t$ in $\Omega_2$. If for every $x_0, x_1 \in \mathbb{R}^n$ we have

$$\int_0^1 g_t((1-t)x_0 + tx_1) \, d\mu(t) \leq (1-m)f_0(x_0) + mf_1(x_1),$$

then it follows that

$$-\int_0^1 \log \left( \int_{\mathbb{R}^n} e^{-gt} \, d\mu(t) \right) \leq -(1-m)\log \left( \int_{\mathbb{R}^n} e^{-f_0} \right) - m\log \left( \int_{\mathbb{R}^n} e^{-f_1} \right).$$

The deduction of this result from Theorem 1.3 is as follows. Take $X_1 = (\Omega_1, \mu_1) = (\{0, 1\}, (1-m)\delta_0 + m\delta_1)$, $X_2 = (\Omega_2, \mu_2) = ([0, 1], \mu)$ and for $(v_0, v_1) \in \mathbb{R}^n \times \mathbb{R}^n \simeq L^2(X_1, \mathbb{R}^n)$ define $A(v_0, v_1) \in L^2(X_2, \mathbb{R}^n)$ by

$$A(v_0, v_1) : t \mapsto (1-t)v_0 + tv_1. $$

Then the constant functions condition (ii) is satisfied, as $A(v, v) \equiv v$, and by the convexity of the square of the Euclidean norm on $\mathbb{R}^n$, letting $H_i = L^2(X_1, \mathbb{R}^n)$, $i = 1, 2$, we have

$$\|A(v_0, v_1)\|_{H_2}^2 = \int_0^1 |(1-t)v_0 + tv_1|^2 \, d\mu(t)$$

$$\leq (1-m)|v_0|^2 + m|v_1|^2 = \|(v_0, v_1)\|_{H_1}^2. $$

**Remark 4.5.** It is possible to prove Theorem 4.4 without assuming $g_t$ l.s.c. and $f_i$ bounded from below, see Claim 6.1 for a sketch of proof.

As a particular case of the previous proposition, if we take only one function $g_t \equiv g : \mathbb{R}^n \to \mathbb{R}$, we have that when $\mu$ is a probability measure on $[0, 1]$ with barycenter $m$, and

$$(4.1) \ \forall x_0, x_1 \in \mathbb{R}^n, \ \int_0^1 g((1-t)x_0 + tx_1) \, d\mu(t) \leq (1-m)f_0(x_0) + mf_1(x_1), $$

then

$$\int_{\mathbb{R}^n} e^{-g} \geq \left( \int_{\mathbb{R}^n} e^{-f_0} \right)^{1-m} \left( \int_{\mathbb{R}^n} e^{-f_1} \right)^m.$$
The conclusion is independent of \( \mu \), so given the functions \( f_0, f_1, g \), one can try to find an optimal \( \mu \) for which the condition (4.1) holds. The classical Prékopa–Leindler inequality corresponds to the choice \( \mu = \delta_m \), and this is indeed the optimal choice when \( g \) is convex, as seen by using Jensen’s inequality in (4.1). Does the above result really improve on the Prékopa–Leindler inequality when \( g \) is non-convex?

Another particular case of the previous proposition (in the case of convex combination of two Dirac measures) is the following extension of Proposition 1.2.

**Proposition 4.6.** Fix \( s, t, r \in [0, 1] \) and set \( m := (1 - r)s + rt \in [0, 1] \). Let \( f_0, f_1, g_0, g_1 \) be four Borel functions from \( \mathbb{R}^n \) to \( \mathbb{R} \cup \{+\infty\} \) such that for every \( x_0, x_1 \in \mathbb{R}^n \),

\[
(1 - r)g_0((1 - s)x_0 + sx_1) + rg_1((1 - t)x_0 + tx_1) \leq (1 - m)f_0(x_0) + mf_1(x_1).
\]

Then

\[
\left( \int_{\mathbb{R}^n} e^{-g_0(x)} \, dx \right)^{1 - r} \left( \int_{\mathbb{R}^n} e^{-g_1(x)} \, dx \right)^{r} \geq \left( \int_{\mathbb{R}^n} e^{-f_0(x)} \, dx \right)^{1 - m} \left( \int_{\mathbb{R}^n} e^{-f_1(x)} \, dx \right)^{m}.
\]

**Proof.** Although the result is a particular case of Theorem 4.3 (with \( \mu = (1 - r)\delta_s + r\delta_t \)), it is better to go back to Theorem 1.6 since in the case of finitely many functions there are no technical conditions. We take \( \Omega_1 = \{0, 1\}, (1 - m)\delta_0 + m\delta_1 \) and \( \Omega_2 = \{0, 1\}, (1 - r)\delta_0 + r\delta_1 \), and the linear mapping \( A : H_1 \to H_2 \) with \( H_i := L^2(\Omega_i, \mathbb{R}^n) \) defined by

\[
A(x_0, x_1) := ((1 - s)x_0 + sx_1, (1 - t)x_0 + tx_1), \quad x_0, x_1 \in \mathbb{R}^n.
\]

We have \( A(v, v) = (v, v) \) for every \( v \in \mathbb{R}^n \) and we note that for \( x_0, x_1 \in \mathbb{R}^n \),

\[
(1 - r)|((1 - s)x_0 + sx_1|^2 + r|((1 - t)x_0 + tx_1|^2
\]

\[
+ ((1 - r)(s - 1) + rt(1 - t))|x_0 - x_1|^2 = (1 - m)|x_0|^2 + m|x_1|^2
\]

and so in particular

\[
(1 - r)|((1 - s)x_0 + sx_1|^2 + r|((1 - t)x_0 + tx_1|^2 \leq (1 - m)|x_0|^2 + m|x_1|^2
\]

which exactly means that \( \|A\| \leq 1 \).

Let us mention that Proposition 1.2 (and also the above results) do not give anything more than the Brunn–Minkowski inequality when applied to the case of indicator functions, i.e., to \( e^{-f_0} = 1_{A_0}, e^{-f_1} = 1_{A_1}, e^{-g_0} = 1_{2A_0/3 + A_1/3}, e^{-g_1} = 1_{A_0/3 + 2A_1/3} \). Indeed, by Brunn–Minkowski, one has that

\[
|2A_0/3 + A_1/3| \geq |A_0|^{2/3}|A_1|^{1/3}, \quad |A_0/3 + 2A_1/3| \geq |A_0|^{1/3}|A_1|^{2/3},
\]
and in this case, the result of Proposition 1.2 is obtained by taking the product of these two inequalities. It seems that the extra information comes from applying the results to “true” functions. This is consistent with the fact that we do not know how to reach our functional inequalities using other classical proofs of the Prékopa–Leindler inequalities. For instance, it is not clear that Proposition 1.2 can be proved using the mass transportation argument of McCann [12]; precisely, this transportation argument uses some form of “localization inside the integral” amounting to reducing the problem to sets (ellipsoids, actually) and eventually matrices.

**Example 4.7** (Gaussian self-improvement and generalized \( \tau \)-property). Let \( \alpha \in (0, 1) \). We shall comment on Proposition 4.6 in the case \( s = \alpha, t = 1 - \alpha = 1 - s \) and \( r = 1/2 \) (and so \( m = 1/2 \)). The goal is to get improved Gaussian inequalities by exploiting identity (4.2) instead of an inequality. Let \( f_0, f_1 \) be real Borel functions on \( \mathbb{R}^n \).

We start first with the case of the Prékopa–Leindler inequality and consider the following variant \( g \) of inf-convolution, defined for every \( x \in \mathbb{R}^n \) by

\[
g(x) = \inf \{(1 - \alpha)f_0(x_0) + \alpha f_1(x_1) + \alpha(1-\alpha)|x_0 - x_1|^2/2 : x = (1 - \alpha)x_0 + \alpha x_1\}.
\]

We assume that \( g(x) > -\infty \). Using the following particular case of (4.2),

\[
(4.3) \quad |(1 - \alpha)x_0 + \alpha x_1|^2 + \alpha(1 - \alpha)|x_0 - x_1|^2 = (1 - \alpha)|x_0|^2 + \alpha|x_1|^2,
\]

it follows that \( g(x) + |x|^2/2 \leq (1 - \alpha)(f_0(x_0) + |x_0|^2/2) + \alpha(f_1(x_1) + |x_1|^2/2) \) whenever \( x = (1 - \alpha)x_0 + \alpha x_1 \), and we obtain by Prékopa–Leindler that

\[
\int_{\mathbb{R}^n} e^{-g} \, d\gamma_n \geq \left(\int_{\mathbb{R}^n} e^{-f_0} \, d\gamma_n \right)^{1-\alpha} \left(\int_{\mathbb{R}^n} e^{-f_1} \, d\gamma_n \right)^{\alpha},
\]

where \( \gamma_n \) is the standard Gaussian measure \( \gamma_{n,1} \) on \( \mathbb{R}^n \). This infimal convolution inequality ensures the \( \tau \)-property from [10] for the Gaussian measure.

For \( \alpha, \beta, \lambda \in (0, 1) \), we may generalize \( g \) as

\[
g_{\alpha,\beta,\lambda}(x) = \inf \{(1 - \beta)f_0(x_0) + \beta f_1(x_1) + \lambda\alpha(1-\alpha)|x_0 - x_1|^2 : x = (1 - \alpha)x_0 + \alpha x_1\},
\]

the former \( g \) being equal to \( g_{\alpha,\alpha,1/2} \). The Prékopa–Leindler inequality does not seem to apply to values of the parameters other than triples of the form \( (\alpha, \alpha, 1/2) \). Combining

\[
g_{\alpha,\beta,\lambda}(x_\alpha) \leq (1 - \beta)f_0(x_0) + \beta f_1(x_1) + \lambda\alpha(1-\alpha)|x_0 - x_1|^2
\]

and the corresponding inequality for \( g_{1-\alpha,1-\beta,1-\lambda}(x_{1-\alpha}) \), we get, with \( g_0 = g_{\alpha,\beta,\lambda} \) and \( g_1 = g_{1-\alpha,1-\beta,1-\lambda} \), that

\[
g_0(x_\alpha) + g_1(x_{1-\alpha}) \leq f_0(x_0) + f_1(x_1) + \alpha(1-\alpha)|x_0 - x_1|^2.
\]
The identity in the case \(s = \alpha, t = 1 - \alpha\) and \(r = 1/2\) (thus \(m = 1/2\)) rewrites as
\[
|(1 - \alpha)x_0 + \alpha x_1|^2 + |\alpha x_0 + (1 - \alpha)x_1|^2 + 2\alpha(1 - \alpha)|x_0 - x_1|^2 = |x_0|^2 + |x_1|^2
\]
and so we find
\[
g_0(x_\alpha) + |x_\alpha|^2/2 + g_1(x_{1-\alpha}) + |x_{1-\alpha}|^2/2 \leq f_0(x_0) + |x_0|^2/2 + f_1(x_1) + |x_1|^2/2.
\]

Therefore, by Proposition 4.6 with \(s = \alpha, t = 1 - \alpha\) and \(r = 1/2 = m\), we arrive at the following generalized infimal convolution inequality:
\[
\left(\int_{\mathbb{R}^n} e^{-g_{\alpha,\beta,\lambda}} d\gamma_n\right) \left(\int_{\mathbb{R}^n} e^{-g_{1-\alpha,1-\beta,1-\lambda}} d\gamma_n\right) \geq \left(\int_{\mathbb{R}^n} e^{-f_0} d\gamma_n\right) \left(\int_{\mathbb{R}^n} e^{-f_1} d\gamma_n\right).
\]

**Example 4.8** (Exotic situation). All our examples so far of linear maps \(A\) are of “convex type”, meaning that
\[
\int_{\Omega_2} \varphi(A(\alpha)(t)) d\mu_2(t) \leq \int_{\Omega_1} \varphi(\alpha(s)) d\mu_1(s)
\]
for every convex function \(\varphi\) on \(\mathbb{R}^n\), while the norm condition \((i)\) on \(A\) ensures this property for \(\varphi(x) = k|x|^2\) only, \(k \geq 0\). Here is a “non convex” example, with \(\Omega_1 = \Omega_2 = \Omega = \{0, 1\}\) and \(\mu_1 = \mu_2 = \delta_0 + \delta_1\). The space \(L^2(\Omega, \mathbb{R}^n)\) is equal to \(\mathbb{R}^n \times \mathbb{R}^n\), the matrix \(A\) can be represented by blocks of size \(n \times n\),
\[
A = \begin{pmatrix} A_1 & B_1 \\ C_1 & D_1 \end{pmatrix}.
\]

By the constant functions condition \((ii)\), the image of the constant function equal to \(x \in \mathbb{R}^n\) is \((A_1 x + B_1 x, C_1 x + D_1 x) = (x, x)\), which is equivalent to \(A_1 + B_1 = C_1 + D_1 = I_n\), the identity matrix. One can thus write
\[
A = \begin{pmatrix} I - B & B \\ C & I - C \end{pmatrix}.
\]

Since \(\|A\| \leq 1\), each block must have norm \(\leq 1\), and this implies that the diagonal coefficients of \(B, C\) are in \([0, 1]\). The condition \(\|A\| \leq 1\) means that \(A^*A \leq I_{2n}\), which translates to
\[
\begin{pmatrix} B^*B + C^*C & -B^*B - C^*C \\ -B^*B - C^*C & B^*B + C^*C \end{pmatrix} \leq \begin{pmatrix} B + B^* & -B - C^* \\ -B^* - C & C + C^* \end{pmatrix}.
\]

In the simpler case \(C = B\), this amounts to \(2B^*B \leq B + B^*\), or \(\|Bx\|^2 \leq Bx \cdot x\), for every \(x \in \mathbb{R}^n\). For an elementary explicit example, take \(n = 2\) and
\[
B = \begin{pmatrix} b & \varepsilon \\ -\varepsilon & b \end{pmatrix}
\]
with \( b \in (0, 1) \) and \( b^2 + \varepsilon^2 \leq b \). We see that \( B = bI_2 - \varepsilon R \), with \( R \) the rotation by \( \pi/2 \) in the plane \( \mathbb{R}^2 \). Then, with \( b = 1/3 \) and \( \varepsilon = \sqrt{2}/3 \), if we know that

\[
g_0 \left( \frac{2}{3} x_0 + \frac{1}{3} x_1 - \frac{\sqrt{2}}{3} R(x_1 - x_0) \right) + g_1 \left( \frac{1}{3} x_0 + \frac{2}{3} x_1 + \frac{\sqrt{2}}{3} R(x_1 - x_0) \right) \\
\leq f_0(x_0) + f_1(x_1)
\]

for all \( x_0, x_1 \in \mathbb{R}^n \), we get the same conclusion as that of Proposition 1.2.

**Remark 4.9.** Following the previous construction, it is natural to ask if we can construct an “exotic” Prékopa–Leindler situation. The answer is no. Let \( \alpha \in [0, 1] \). The only \( n \times n \) (real) matrix \( B \) such that \(|(I_n - B)x + By|^2 \leq (1 - \alpha)|x|^2 + \alpha|y|^2\) for all \( x, y \in \mathbb{R}^n \) is \( B = \alpha I_n \) (try \( x = u + tv \), \( y = u - t(1 - \alpha)v \) and \( t \to 0 \)). In other words, there is no “exotic example” in the Prékopa–Leindler case. More generally, if \( B_1, \ldots, B_k \) are \( n \times n \) matrices such that \( \sum_{j=1}^k B_j = I_n \) and \( \sum_{j=1}^k B_j x_j \|^2 \leq \sum_{j=1}^k \alpha_j |x_j|^2 \), with \( \alpha_j \geq 0 \) and \( \sum_{j=1}^k \alpha_j = 1 \), then \( B_j = \alpha_j I_n \) for \( j = 1, \ldots, k \).

### 5 Generalized Brascamp–Lieb and reverse
Brascamp–Lieb inequalities

By slightly modifying Setting 1, it is possible to recover and extend, almost for free, the Brascamp–Lieb inequalities and their reverse forms. Let us mention that it has been known for some time that the Brascamp–Lieb inequalities can be recovered using Borell’s technique (see e.g. [9]).

If the functions \( \{f_s\} \) are defined on \( \mathbb{R}^m \) and \( \{g_t\} \) on \( \mathbb{R}^n \), with \( m \neq n \), then the linear operator \( A \) of Setting 1 should now act from \( L^2(X_1, \mathbb{R}^m) \) to \( L^2(X_2, \mathbb{R}^n) \) and the constant functions condition \( (ii) \) has to be revised. We shall do it by using projections from the larger space, \( \mathbb{R}^m \) or \( \mathbb{R}^n \), onto the smaller. To be precise, our *projections* are adjoint to isometries from the smaller space into the larger. For example, if \( n < m \) and if \( T \) is an isometry from \( \mathbb{R}^n \) into \( \mathbb{R}^m \), its adjoint \( Q = T^* \) is a mapping from \( \mathbb{R}^m \) onto \( \mathbb{R}^n \) such that \( QQ^* = \text{Id}_{\mathbb{R}^n} \), and \( Q^*Q \) is the orthogonal projection of \( \mathbb{R}^m \) onto the range of \( T \). Then, for \( v \in \mathbb{R}^m \), we can compare the image \( A(s \mapsto v) \) of the constant function \( \Omega_1 \ni s \mapsto v \) with the constant function \( \Omega_2 \ni t \mapsto Qv \). Actually, the new setting will be notably more complicated, introducing a family of projections \( Q(t), t \in \Omega_2 \), and comparing the image \( A(s \mapsto v) \) with the function \( t \mapsto Q(t)v \). We can also view the new setting as giving a measurable family of \( n \)-dimensional subspaces \( X(t) \) of \( \mathbb{R}^m \), parameterized by \( T(t) : \mathbb{R}^n \to X(t) \), and \( Q(t) = T(t)^* \) being the composition of the orthogonal projection \( \pi(t) \) of \( \mathbb{R}^m \) onto \( X(t) \) with the inverse map of \( T(t) \).

Except for what concerns the linear mapping \( A \), the modifications are straightforward, and will be just indicated without rewriting completely the modified assumption.
Setting 2. The definition of the measure spaces \(X_1 = (\Omega_1, \Sigma_1, \mu_1), X_2 = (\Omega_2, \Sigma_2, \mu_2)\) is as in Setting 1, in particular, \(\mu_1\) and \(\mu_2\) are finite measures. Two integers \(m, n \geq 1\) are given, and the linear operator \(A\) acts now as

\[
A : L^2(X_1, \mathbb{R}^m) \to L^2(X_2, \mathbb{R}^n)
\]

with \(\|A\| \leq 1\), where the norms are computed with respect to the Euclidean norm \(|\cdot|\) on \(\mathbb{R}^m, \mathbb{R}^n\) and to the measures \(\mu_1\) and \(\mu_2\), respectively. The constant functions condition is modified as follows:

(ii)\(_1\) If \(m \leq n\), there exists a \(\Sigma_1\)-measurable family \(\Omega_1 \ni s \mapsto P(s)\) of projections \(P(s)\) from \(\mathbb{R}^n\) onto \(\mathbb{R}^m\) such that, for every vector \(w_0 \in \mathbb{R}^n\),

\[
A(s \mapsto P(s)w_0)(t) = w_0 \text{ for } \mu_2\text{-almost every } t \in \Omega_2,
\]

(ii)\(_2\) If \(m \geq n\), there exists a \(\Sigma_2\)-measurable family \(\Omega_2 \ni t \mapsto Q(t)\) of projections \(Q(t)\) from \(\mathbb{R}^m\) onto \(\mathbb{R}^n\) such that, for every vector \(v_0 \in \mathbb{R}^m\),

\[
A(s \mapsto v_0)(t) = Q(t)v_0 \text{ for } \mu_2\text{-almost every } t \in \Omega_2.
\]

Note that formally, (ii)\(_2\) is the adjoint situation to (ii)\(_1\). Observe that (ii)\(_1\) implies that every \(w_0 \in \mathbb{R}^n\) can be reconstructed from the family of projections \(s \mapsto P(s)w_0 \in \mathbb{R}^m\).

For the conditions on \(\{f_s\}, \{g_t\}\), we need only replace \(\mathbb{R}^n\) by \(\mathbb{R}^m\) for what concerns \(f_s\) in the measurability condition (iii) and in the semi-integrability condition (iv).

We arrive at the following extension of Theorem 1.3

Theorem 5.1. Under Setting 2, we make the additional assumptions that the functions \(f_s, g_t\) are non-negative with \(g_t\) lower semicontinuous on \(\mathbb{R}^n\), that for some \(\varepsilon_0 > 0\) we have

\[
\int_{\Omega_1} \log^+ \left( \int_{\mathbb{R}^m} \exp\left(-f_s(x) - \varepsilon_0|x|^2\right) \, dx \right) \, d\mu_1(s) < +\infty,
\]

and that the measures \(\mu_1, \mu_2\) are such that \(m \cdot \mu_1(\Omega_1) = n \cdot \mu_2(\Omega_2) < +\infty\).

If for every \(\alpha \in L^2(X_1, \mathbb{R}^m)\), we have

\[
\int_{\Omega_2} g_t((A\alpha)(t)) \, d\mu_2(t) \leq \int_{\Omega_1} f_s(\alpha(s)) \, d\mu_1(s),
\]

then

\[
\int_{\Omega_2} -\log \left( \int_{\mathbb{R}^n} e^{-g_t} \, dx \right) \, d\mu_2(t) \leq \int_{\Omega_1} -\log \left( \int_{\mathbb{R}^m} e^{-f_s} \, dx \right) \, d\mu_1(s).
\]

Not only the argument for deriving Theorem 5.1 follows the proof of Theorem 1.3 but in its Gaussian version, Theorem 5.1 is already contained in Proposition 2.4. Indeed, after reducing to the Gaussian case, we further approximate as before the functions \(f_s\) and \(g_t\) by inf-convolution, in order
to be in a position to apply the proposition below, just as we did for proving Theorem 1.3. The assumption \( m \cdot \mu_1(\Omega_1) = n \cdot \mu_2(\Omega_2) \) is needed to pass to the limit from the Gaussian case for \( P_T, T \to +\infty \), in respective dimensions \( m \) and \( n \).

For the Gaussian version below, we will have not much to add, except maybe for the case \((ii)_2\) of Setting 2. So Proposition 2.4 almost includes all possible geometric situations around the Prékopa–Leindler inequality, including these generalized Brascamp–Lieb inequalities.

**Proposition 5.2.** Under Setting 2, assume that \( f_s, g_t \) are continuous \( \geq 0 \) on \( \mathbb{R}^m \) and \( \mathbb{R}^n \), respectively (or bounded from below as in Remark 1.4), and that the functions \( f_s \) satisfy the exponential bound (2.6) on \( \mathbb{R}^m \). Then, the basic assumption (5.2) implies that

\[
(5.3) \quad \int_{\Omega_2} -\log \left( \int_{\mathbb{R}^n} e^{-g_t(y)} d\gamma_{n,\tau}(y) \right) d\mu_2(t) \\
\leq \int_{\Omega_1} -\log \left( \int_{\mathbb{R}^m} e^{-f_s(x)} d\gamma_{m,\tau}(x) \right) d\mu_1(s).
\]

As before, in the case where the measures \( \mu_1 \) and \( \mu_2 \) have finite support, we can remove all the additional assumptions on \( f_s \) and \( g_t \).

**Proof.** We want to apply Proposition 2.4 but we have to deal with the fact that dimensions \( m \) and \( n \) are now different. We shall do it by reducing to the case when both dimensions are equal to \( \max(m,n) \).

In case \((ii)_1\), when \( m \leq n \), we “extend” \( f_s \) to \( \mathbb{R}^n \) by defining \( f_{s}(y) = f_s(P(s)y), y \in \mathbb{R}^n \), so that

\[
(5.4) \quad \int_{\mathbb{R}^n} e^{-f_s(y)} d\gamma_{n,\tau}(y) = \int_{\mathbb{R}^m} e^{-f_s(x)} d\gamma_{m,\tau}(x).
\]

For every \( \alpha \in L^2(X_1, \mathbb{R}^n) \), define \( \alpha_1 \in L^2(X_1, \mathbb{R}^m) \) by \( \alpha_1(s) = P(s)\alpha(s) \) and set \( A_1(\alpha) = A(\alpha_1) \). Then \( A_1 \) is linear from \( L^2(X_1, \mathbb{R}^n) \) to \( L^2(X_2, \mathbb{R}^n) \), and clearly \( \|A_1\| \leq \|A\| \leq 1 \). If \( w_0 \) is a fixed vector in \( \mathbb{R}^n \), then \( A_1(s \mapsto w_0) = A(s \mapsto P(s)w_0) = w_0 \) by \((ii)_1\), so \( A_1 \) satisfies the constant functions condition \((ii)\). Next, by the basic assumption of Theorem 5.1 applied to \( \alpha_1 \), we get that

\[
\int_{\Omega_2} g_t((A_1\alpha)(t)) d\mu_2(t) = \int_{\Omega_2} g_t((A\alpha_1)(t)) d\mu_2(t) \leq \int_{\Omega_1} f_s(\alpha_1(s)) d\mu_1(s)
\]

\[
= \int_{\Omega_1} f_s(P(s)\alpha(s)) d\mu_1(s) = \int_{\Omega_1} f_{1,s}(\alpha(s)) d\mu_1(s).
\]

We see that \( A_1, \{f_{1,s}\} \) and \( \{g_t\} \) satisfy the assumptions of Proposition 2.4 including the basic assumption (1.3) on \( \mathbb{R}^n \). The result follows therefore from (5.4) and from the conclusion of Proposition 2.4 for \( \{f_{1,s}\} \) and \( \{g_t\} \).
In case \((ii)_2\), when \(m \geq n\), let \(T(t)\) be the isometry from \(\mathbb{R}^n\) into \(\mathbb{R}^m\) adjoint to the projection \(Q(t)\), so that \(Q(t)T(t) = \text{Id}_{\mathbb{R}^n}\). The function \(g_t\) is extended to \(\mathbb{R}^m\) by setting \(g_{1,t}(x) = g_t(Q(t)x)\), \(x \in \mathbb{R}^m\). For \(\alpha \in L^2(X_1, \mathbb{R}^m)\), we set \((A_1\alpha)(t) = T(t)(A\alpha)(t)\) and get that \(Q(t)(A_1\alpha)(t) = (A\alpha)(t)\). We have that \(\|A_1\| = \|A\| \leq 1\). If \(a_0 = v_0\) is a constant function from \(\Omega_1\) to \(\mathbb{R}^m\), we know by \((ii)_2\) that \((A_1\alpha_0)(t) = Q(t)v_0\). Then \((A_1\alpha_0)(t) = T(t)(A\alpha_0)(t) = T(t)Q(t)v_0\), not equal to \(v_0\) in general. The constant functions condition \((ii)\) is not satisfied by \(A_1\), but still we have

\[
g_{1,t}(A_1(v_0 + \alpha)(t)) = g_{1,t}(v_0 + (A_1\alpha)(t)), \quad t \in \Omega_2,
\]

for every \(\alpha \in L^2(X_1, \mathbb{R}^m)\). This is because \(g_{1,t}(x_1) = g_{1,t}(x_2)\) when \(Q(t)x_1 = Q(t)x_2\), and because we have by \((ii)_2\) that

\[
Q(t)A_1(v_0 + \alpha)(t) = A(v_0 + \alpha)(t) = Q(t)v_0 + (A\alpha)(t) = Q(t)(v_0 + (A_1\alpha)(t)).
\]

The basic assumption \[(1.3)\] is satisfied for the families \(\{f_s\}, \{g_{1,t}\}\) of functions on \(\mathbb{R}^m\) and the mapping \(A_1\); since \(g_{1,t}((A_1\alpha)(t)) = g_t((A\alpha)(t))\), we get

\[
\int_{\Omega_2} g_{1,t}((A_1\alpha)(t)) \, d\mu_2(t) = \int_{\Omega_2} g_t(A\alpha)(t) \, d\mu_2(t) \leq \int_{\Omega_1} f_s(\alpha(s)) \, d\mu_1(s).
\]

We stressed during the proof of Proposition \[2.4\] that the equality \[(5.5)\] is enough to run the argument (see equation \[2.13\] and the lines around it). Finally, as before, observe that

\[
\int_{\mathbb{R}^n} e^{-g_t(y)} \, d\gamma_{m,t}(y) = \int_{\mathbb{R}^m} e^{-g_{1,t}(x)} \, d\gamma_{m,t}(x),
\]

and use Proposition \[2.4\] to get the desired conclusion.

**Remark 5.3.** The normalization \(\|A\| \leq 1\) can be replaced by the following assumptions. Let \(\kappa := \|A\| > 0\) and assume that \(\kappa^2 \cdot m \cdot \mu_1(\mathbb{R}^m) = n \cdot \mu_2(\mathbb{R}^n)\). If for every \(\alpha \in L^2(X_1, \mathbb{R}^m)\), we have

\[
\int_{\Omega_2} g_t((A\alpha)(t)) \, d\mu_2(t) \leq \kappa^2 \int_{\Omega_1} f_s(\alpha(s)) \, d\mu_1(s),
\]

then

\[
\int_{\Omega_2} - \log \left(\int_{\mathbb{R}^n} e^{-f_s} \, d\mu_2(t)\right) \, d\mu_1(s) \leq \kappa^2 \int_{\Omega_1} - \log \left(\int_{\mathbb{R}^m} e^{-f_s} \, d\mu_1(s)\right). \leqno{2.14}
\]

The reader will just look at inequality \[2.14\] and the inequality before it.

We shall examine now particular cases of Theorem \[5.1\]. We will see that it contains both the Brascamp–Lieb and reverse Brascamp–Lieb inequalities in their geometric form.
Let us take unit vectors \( u_1, \ldots, u_N \) in the Euclidean space \( \mathbb{R}^d \) and positive reals \( c_1, \ldots, c_N \) that decompose the identity of \( \mathbb{R}^d \), meaning that

\[
\sum_{i=1}^N c_i u_i \otimes u_i = \text{Id}_{\mathbb{R}^d}.
\]

This is equivalent to saying that \( x \cdot x = \sum_{i=1}^N c_i |u_i \cdot x|^2 \) for every \( x \in \mathbb{R}^d \). If we consider the one-point space \( E_1 = \{0\} \) equipped with the trivial probability measure \( \nu_1 \), and the measure space \( (E_2, \nu_2) = \left( \{1, \ldots, N\}, \sum_{i=1}^N c_i \delta_i \right) \), \( \nu_2(E_2) = \sum_{i=1}^N c_i = d \), then (5.6) is equivalent to saying that the mapping

\[
U : x \in \mathbb{R}^d \mapsto (x \cdot u_1, \ldots, x \cdot u_N)
\]

is an isometry from \( L^2(E_1, \nu_1, \mathbb{R}^d) \simeq \mathbb{R}^d \) into \( L^2(E_2, \nu_2, \mathbb{R}) \simeq \mathbb{R}^N \).

In order to recover the reverse Brascamp–Lieb inequalities, consider

\[
X_1 = (E_2, \nu_2), \quad m = 1, \quad X_2 = (E_1, \nu_1), \quad n = d,
\]

satisfying

\[
m \mu_1(\Omega_1) = \nu_2(E_2) = d = n \mu_2(\Omega_2).
\]

Define \( A : \mathbb{R}^N \simeq L^2(X_1, \mathbb{R}^m) \rightarrow \mathbb{R}^d \simeq L^2(X_2, \mathbb{R}^n) \) to be the linear operator

\[
A(t_1, \ldots, t_N) = \sum_{i=1}^N c_i t_i u_i, \quad t_i \in \mathbb{R}.
\]

Then \( A \) is adjoint to the into isometry \( U \) of (5.7) between our \( L^2 \) spaces, and \( A \) satisfies the condition \((ii)\) of Setting 2, with the family of projections \( P_i v = v \cdot u_i, \quad i \in \Omega_1 \), because we have by (5.6) that

\[
A(i \mapsto P_i v) = \sum_{i=1}^N c_i (v \cdot u_i) u_i = v.
\]

The conclusion reads as follows. If for every \( t_1, \ldots, t_N \in \mathbb{R} \) we have

\[
g \left( \sum_{i=1}^N t_i c_i u_i \right) \leq \sum_{i=1}^N c_i f_i(t_i) \quad \text{then} \quad \int_{\mathbb{R}^d} e^{-g} \geq \prod_{i=1}^N \left( \int_{\mathbb{R}} e^{-f_i} \right)^{c_i}.
\]

This is the reverse Brascamp–Lieb inequality of Barthe [1] in its geometric form. Actually, in the same way, we can see that the formulation above contains the “continuous” statement given in [2] (that can be easily derived by approximation, anyway).
In order to recover the classical Brascamp–Lieb inequalities, apply the theorem with \( X_1 = (E_1, \nu_1) \), \( m = d \), \( X_2 = (E_2, \nu_2) \), \( n = 1 \) and the linear operator \( A : L^2(X_1, \mathbb{R}^m) \simeq \mathbb{R}^d \to L^2(X_2, \mathbb{R}^n) \simeq \mathbb{R}^N \) defined by \( A(x) = (x \cdot u_1, \ldots, x \cdot u_N) \). Then \( A = U \), the into isometry \([5.7]\) between the corresponding \( L^2 \) spaces, and it satisfies the assumption \((ii)_2\) with the family of projections \( Q_i(x) = x \cdot u_j \), \( j \in \Omega_2 = \{1, \ldots, N\} \). The conclusion reads as follows: given \( f : \mathbb{R}^d \to \mathbb{R} \) and \( g_1, \ldots, g_N : \mathbb{R} \to \mathbb{R} \) such that

\[
\forall x \in \mathbb{R}^d, \quad \sum_{j=1}^N c_j g_j(x \cdot u_j) \leq f(x), \quad \text{we have} \quad \prod_{j=1}^N \left( \int_{\mathbb{R}} e^{-g_j} \right)^{c_j} \geq \int_{\mathbb{R}^d} e^{-f}.
\]

This is the geometric Brascamp–Lieb inequality, usually stated with the best possible \( f \), which is defined by the equality in place of inequality above, namely

\[
\int_{\mathbb{R}^d} \exp \left( - \sum_{j=1}^N c_j g_j(x \cdot u_j) \right) dx \leq \prod_{j=1}^N \left( \int_{\mathbb{R}} e^{-g_j} \right)^{c_j}.
\]

It is possible to state (and prove in the same way) a more general form of Theorem \([5.1]\) where each function \( f_s \) (resp. \( g_t \)) is defined on a different Euclidean space \( E_s \) (resp. \( F_t \)), and to deduce from it the multidimensional geometric Brascamp–Lieb inequalities. In this situation, we assume that all spaces \( E_s, F_t \) are subspaces of a given \( \mathbb{R}^\ell \). We may consider that the space \( E_s \) is \( \mathbb{R}^{m(s)} \) and that \( F_t \) is \( \mathbb{R}^{n(t)} \), with \( 1 \leq m(s), n(t) \leq \ell \) and we assume that

\[
\int_{\Omega_1} m(s) \, d\mu_1(s) = \int_{\Omega_2} n(t) \, d\mu_2(t).
\]

The mapping \( A \) is defined on the closed subspace \( H \) of \( L^2(X_1, \mathbb{R}^\ell) \) consisting of those \( \alpha \) with \( \alpha(s) \in E_s \) for every \( s \in \Omega_1 \). We assume that for every square integrable choice \( \alpha \in H \), the image \( A\alpha \in L^2(X_2, \mathbb{R}^\ell) \) is such that \( (A\alpha)(t) \) belongs to \( F_t \) for every \( t \in \Omega_2 \). We give projections \( P(s), Q(t) \) from \( \mathbb{R}^\ell \) onto \( E_s, F_t \) respectively. The constant functions condition says now that for every \( w_0 \in \mathbb{R}^\ell \), we have that

\[
A(s \mapsto P(s)w_0)(t) = Q(t)w_0.
\]

The proof mixes the two cases \((ii)_1\) and \((ii)_2\) of the proof of Theorem \([5.1]\). We leave this to the reader.

### 6 Technicalities

**Claim 6.1.** In Theorem \([4.4]\) we can remove the assumptions that \( g_t \) is l.s.c. and that \( f_i \geq 0 \) (or bounded from below), \( i = 0, 1 \).

**Sketch of proof.** As in the proof of Theorem \([4.3]\) we begin by replacing the Lebesgue measure in \( \int_{\mathbb{R}^n} e^{-f_i(x)} \, dx \) and \( \int_{\mathbb{R}^n} e^{-g_i(x)} \, dx \) by a Gaussian probability measure \( \gamma \). The justification is the same here for the \( g_t \) side, but is
easier for $f_i$, $i = 0, 1$, a simple application of monotone convergence. Next, as in the proof of Theorem 1.6, one can replace $g_t$ by $g_{t,N} = \min(g_t, N)$ and $f_i$ by $f_{i,N} = \max(f_i, -N)$: since $g_{t,N}$ increases to $g_t$ as $N \to +\infty$, the argument for

$$\int_{\Omega_2} \log\left(\int_{\mathbb{R}^n} e^{g_{t,N}} \, d\gamma\right) \, d\mu_2(t) \to \int_{\Omega_2} \log\left(\int_{\mathbb{R}^n} e^{g_t} \, d\gamma\right) \, d\mu_2(t)$$

is the same as at the end of the proof of Theorem 1.3 and for $f_{i,N}$, decreasing to $f_i$, the reason is monotone convergence again in $\int_{\mathbb{R}^n} e^{-f_{i,N}} \, d\gamma$, $i = 0, 1$. Then $0 \leq g_{t,N} \leq N$ and $f_{0,N}, f_{1,N} \geq -N$. As in the proof of Theorem 1.6, one can assume that $f_{0,N}, f_{1,N} \leq 2N/\beta$ with $\beta = \min(m, 1 - m)$. Finally, approximation by convolution reduces to the case of bounded continuous functions, and one can conclude by applying Proposition 2.4.

**Proof of Lemma 2.3** We may assume that $f \geq 0$. For some integer $N \geq 0$, let $\varphi(x) = \min(f(x), N) \geq 0$. As in [2,2], define $\varphi_r$ by $e^{-\varphi_r} = P_{T-r} (e^{-\varphi})$, $0 \leq r \leq T$ and let $\Phi_0 = \varphi_0(0)$, $F_0 = -\log P_T(e^{-f})(0) \geq \Phi_0 > 0$. Note that $\varphi \geq 0$ implies $\varphi_r \geq 0$. Since $\varphi$ is bounded and continuous, we may by Lemma 2.1 consider the optimal martingale corresponding to $\varphi$,

$$M_r = \varphi_r (B_r + \int_0^r u_\rho \, d\rho) + \frac{1}{2} \int_0^r |u_\rho|^2 \, d\rho = M_0 - \int_0^r u_\rho \cdot dB_\rho, \quad 0 \leq r \leq T,$$

with $M_0 = \Phi_0$, $u_\rho = -\nabla \varphi_r (X_r)$ and $X_r = B_r + \int_0^r u_\rho \, d\rho$. Define the square function $(S_r)_{0 \leq r \leq T}$ of the martingale $(M_r - M_0)_{0 \leq r \leq T}$ by

$$S_r = \left(\int_0^r |u_\rho|^2 \, d\rho\right)^{1/2}.$$ 

We know by [2,4] that $S_r, X_r$ and $M_r$ converge almost surely and in $L^2$ to $S_T, X_T$ and $M_T$. Observe that $|u_r|, S_r$ and $M_r$ are bounded random variables for each fixed $r < T$. Consider the exponential martingale $e^{\lambda M_r - \lambda^2 S_r^2/2}$ for $\lambda = 1/2$ and $0 \leq r < T$, namely

$$\exp(M_r/2 - S_r^2/8) = \exp(\varphi_r(X_r)/2 + S_r^2/4 - S_r^2/8) = \exp(\varphi_r(X_r)/2 + S_r^2/8).$$

By Fatou and the martingale property, we have that

$$\mathbb{E} \exp(S_r^2/8) \leq \mathbb{E} \exp(\varphi_r(X_r)/2 + S_r^2/8) \leq \lim_{r \to T} \mathbb{E} \exp(\varphi_r(X_r)/2 + S_r^2/8) = e^{\Phi_0/2}.$$

Let $Y_T = T^{-1/2} |X_T| \leq T^{-1/2} |B_T| + S_T$ and observe that in $\mathbb{R}^n$, one has $\mathbb{E} e^{\|B_T\|^2/4} = 2^{n/2}$. For every $\lambda > 0$, using Cauchy–Schwarz and the inequality $0 \leq \sigma^2 + \tau^2/c$ when $c, \sigma, \tau > 0$, we can write

$$(6.1) \quad \left(\mathbb{E} e^{\lambda Y_T}\right)^2 \leq \left(\mathbb{E} e^{2\lambda T^{-1/2}|B_T|}\right) \left(\mathbb{E} e^{2\lambda S_T}\right) = \left(\mathbb{E} e^{2\lambda |B_T|}\right) \left(\mathbb{E} e^{2\lambda S_T}\right) \leq e^{4\lambda^2 \mathbb{E} e^{\|B_T\|^2/4} e^{8\lambda^2} \mathbb{E} e^{S_T^2/8} = 2^{n/2} e^{12\lambda^2} \mathbb{E} e^{S_T^2/8} \leq 2^{n/2} e^{12\lambda^2 + \Phi_0/2} \leq e^{12\lambda^2 + (F_0+n)/2}. $$
We have by the exponential bound (2.5) that
\[
\delta := \mathbb{E}\{f(X_T) - \varphi(X_T)\} \leq \mathbb{E}(1_{\{f(X_T) > N\}} f(X_T))\leq a \mathbb{E}(1_{\{M_T > N\}} e^{b|X_T|}).
\]
Using (6.1) with \(f(6.2)\)
\[
\text{Lemma 2.3.}
\]
\[
\text{Lemma 6.2.}
\]
Assume that \(\varepsilon > 0\), this proves that for any given \(\varepsilon > 0\), when \(N\) is so large that \(\delta < \varepsilon\), the optimal drift \(u\) for \(\varphi\) gives
\[
\mathbb{E}\left[f\left(B_T + \int_0^T u_r \, dr\right) + \frac{1}{2} \int_0^T u_r^2 \, dr\right] - \varepsilon
\]
\[
\leq \mathbb{E}\left[\varphi\left(B_T + \int_0^T u_r \, dr\right) + \frac{1}{2} \int_0^T u_r^2 \, dr\right] = \Phi_0 \leq F_0.
\]
Conversely, since \(1 \geq P_T e^{-\min(f,N)} \geq P_T e^{-f}\) when \(N \to +\infty\), we may start by choosing \(N\) large enough, so that \(F_0 < \Phi_0 + \varepsilon\). For any drift \(u\) in \(D_2\), the inequality case for \(\varphi\) gives
\[
F_0 - \varepsilon < \Phi_0 \leq \mathbb{E}\left[\varphi\left(B_T + \int_0^T u_{\rho} \, d\rho\right) + \frac{1}{2} \int_0^T \left|u_{\rho}\right|^2 \, d\rho\right]
\]
\[
\leq \mathbb{E}\left[f\left(B_T + \int_0^T u_{\rho} \, d\rho\right) + \frac{1}{2} \int_0^T \left|u_{\rho}\right|^2 \, d\rho\right].
\]
This implies the inf formula (2.1) for the function \(f\). Observe that this final part does not use any upper bound on \(f\), proving thus the last claim of Lemma 2.3.

**Lemma 6.2.** Assume that \(\mu\) is a finite measure on \((\Omega, \Sigma)\), \(\nu\) a probability measure on \(\mathbb{R}^n\), \((s, x) \mapsto f_s(x)\) a \(\Sigma \otimes \mathcal{B}_{\mathbb{R}^n}\)-measurable function, and assume that \(s \mapsto \log \left(\int_{\mathbb{R}^n} e^{-f_s} \, d\nu\right)\) is \(\mu\)-integrable on \(\Omega\). For every \(\varepsilon > 0\), there exists a continuous function \(\psi \geq 0\) on \(\mathbb{R}^n\), tending to \(+\infty\) at infinity, such that \(0 \leq \psi(x) \leq |x|^2\) and
\[
\int_{\Omega} - \log \left(\int_{\mathbb{R}^n} e^{-f_s(x) - \psi(x)} \, d\nu(x)\right) \, d\mu(s) \leq \int_{\Omega} - \log \left(\int_{\mathbb{R}^n} e^{-f_s(x)} \, d\nu(x)\right) \, d\mu(s) + \varepsilon.
\]
**Proof.** Consider \(\chi(x) = |x|^2/(1 + |x|^2)\), for \(x \in \mathbb{R}^n\). Note that \(0 \leq \chi \leq 1\), that \(\chi\) tends to 1 at infinity, and that for every \(x\), \(\chi(x/k)\) decreases to 0 as \(k \to +\infty\). Write
\[
e^{-F(s)} := \int_{\mathbb{R}^n} e^{-f_s(x)} \, d\nu(x), \quad s \in \Omega, \quad \text{let} \quad I := \int_{\Omega} F(s) \, d\mu(s) < +\infty,
\]
apd when \(F(s) < +\infty\), let \(u_k(s)\) be defined by
\[
e^{-F(s) - u_k(s)} := \int_{\mathbb{R}^n} e^{-f_s(x) - \chi(x/k)} \, d\nu(x) \xrightarrow{k} e^{-F(s)}.
\]
Then $0 \leq u_k(s) \leq 1$ and $u_k$ converges $\mu$-almost everywhere to 0; since $\mu$ is finite, we can find $k_1 > 1$ such that

$$
\int_\Omega -\log \left( \int_{\mathbb{R}^n} e^{-f_s(x) - \chi(x/k_1)} \, d\nu(x) \right) \, d\mu(s) = \int_\Omega (F(s) + u_{k_1}(s)) \, d\mu(s) < I + \frac{\varepsilon}{2}.
$$

In the same way, we can find by induction an increasing sequence $(k_j)$ of integers such that for every integer $p \geq 1$,

$$
\int_\Omega -\log \left( \int_{\mathbb{R}^n} \exp\left( -f_s(x) - \sum_{j=1}^{p} \chi(x/k_j) \right) \, d\nu(x) \right) \, d\mu(s) < I + \sum_{j=1}^{p} 2^{-j} \varepsilon,
$$

and we can check that

$$
\psi(x) = \sum_{j=1}^{\infty} \chi(x/k_j) = \left( \sum_{j=1}^{\infty} \frac{1}{k_j^2 + |x|^2} \right) |x|^2 \leq \left( \sum_{j=1}^{\infty} k_j^{-2} \right) |x|^2
$$

does the job (note that $\sum_{j \geq 1} k_j^{-2} \leq \pi^2/6 - 1 < 1$ because $k_1 > 1$). \hfill \Box

**Claim 6.3.** The almost optimal drifts $\{U(s)\}_{s \in \Omega_1}$ in (2.5) can be chosen to be $\Sigma_1$-measurable with respect to $s \in \Omega_1$.

**Proof.** In the proof of Proposition 2.4 we may start, using Lemma 6.2, by replacing $f_s(x) \geq 0$ by $f_s(x) + \psi(x)$, where $\psi$ tends to $+\infty$ at infinity, without changing much the value of $\int_{\Omega_1} -\log \left( \int_{\mathbb{R}^n} e^{-f_s(x)} \, d\gamma(x) \right) \, d\mu_1(s)$ and without destroying the exponential bound (2.6) for $f_s(x) + \psi(x)$. We shall thus assume that $\psi(x) \leq f_s(x)$. Recall that $T = \tau > 0$ is fixed.

Let $\delta > 0$ be given and let $e^{-f_s} = P_{T-\tau}(e^{-f_s})$ as in (2.2). We may find a partition of $\Omega_1$ in countably many subsets $A_k \in \Sigma_1$, $k \in \mathbb{N}$, such that on the set $A_k$, the exponential bound (2.6) for $f_s$ is uniform,

$$
f_s(x) \leq a_k e^{b_k |x|}, \quad \text{and such that} \quad f_{s,0}(0) \leq F_k, \quad s \in A_k.
$$

It is enough to prove the measurability on each set $A_k$ separately. We can choose $N_k$ so large that

$$
a_k \sqrt{\frac{F_k}{N_k}} e^{12b_k^2 T + (F_k + n)/8} < \delta.
$$

By (6.2), we may replace $f_s$, $s \in A_k$, by $\varphi_s = \min(f_s, N_k)$ with an error $< \delta$ in the estimate of $-\log(P_T e^{-f_s})(0)$. The “almost optimal drift” $U(s) \in D_2$ for $f_s$ is chosen equal to the optimal drift for $\varphi_s$.

After this reduction, $\varphi_s$ is “constant at infinity” since $f_s \geq \psi$, hence $A_k \ni s \mapsto \varphi_s$ is a map to the separable Banach space $Z$ of continuous functions on $\mathbb{R}^n$ tending to a limit at infinity, equipped with the sup norm, and by the measurability assumption (iii), $s \mapsto \varphi_s(x)$ is $\Sigma_1$-measurable for every $x \in \mathbb{R}^n$. By a classical theorem of Lusin —that Hausdorff topologies weaker
than a Polish topology have the same Borel σ-algebra— this implies that $s \mapsto \varphi_s$ is $\Sigma_1$-measurable from $\Omega$ to $Z$. Next, consider the four mappings sending $f \in Z$ to $e^{-f}$, to $(f_r)_{0 \leq r \leq T}$ defined by (2.2), and, for any given $\varepsilon \in (0, T)$, to $(\nabla f_r)_{0 \leq r \leq T - \varepsilon}$ and $(\nabla^2 f_r)_{0 \leq r \leq T - \varepsilon}$. On every bounded subset $B$ of $Z$, these mappings are Lipschitz from $B$, equipped with the norm of $\varepsilon$, respectively to $Z$, to $C_b([0, T] \times \mathbb{R}^n)$, or to $C_b([0, T - \varepsilon] \times \mathbb{R}^n, \mathbb{R}^p)$, $p = n, n^2$. The Lipschitz constants depend on $B$, and on $\varepsilon$ for the last two. The map sending $f \in Z$ to the solution $X_{r,f}$ of the stochastic differential equation (2.3) is continuous, in the precise sense that for every bounded subset $B$ of $Z$, there is $\kappa = \kappa(B, \varepsilon)$ such that for every $\omega \in E$,

$$
\sup_{0 \leq r \leq T - \varepsilon} \left| X_{r,f}(\omega) - X_{r,g}(\omega) \right| \leq e^{\kappa T} \| f - g \|_\infty, \quad f, g \in B.
$$

Indeed, for every fixed $\omega$, we have the deterministic differential equation in the $r$ variable

$$
X'_{r,f}(\omega) - X'_{r,g}(\omega) = -\nabla f_r(X_{r,f}(\omega)) + \nabla g_r(X_{r,g}(\omega)).
$$

Writing $X'_{r,f} - X'_{r,g}$ as $- (\nabla f_r(X_{r,f}) - \nabla f_r(X_{r,g})) - (\nabla f_r(X_{r,g}) - \nabla g_r(X_{r,g}))$, using the Lipschitz properties mentioned above (implying that the second derivatives of $f_r$ are uniformly bounded for $f \in B$), we see that for every fixed $\theta > 0$, the function $D(r) = (|X_{r,f}(\omega) - X_{r,g}(\omega)|^2 + \theta^2)^{1/2}$ satisfies on $[0, T - \varepsilon]$ a differential inequality of the form $D' \leq \kappa(D + \| f - g \|_\infty)$, with $D(0) = \theta$. It follows that the “almost optimal” drift $U : (s, r) \mapsto -\nabla \varphi_{s,r}(X_{s,r})$ is $\Sigma_1$-measurable.

**Lemma 6.4.** Under Setting 1, assume that $f_s \geq 0$ and that for some $\varepsilon_0 > 0$, the function $\Omega_1 \ni s \mapsto -\log \left( \int_{\mathbb{R}^n} e^{-f_s(x) - \varepsilon_0 |x|^2} \, dx \right)$ is $\mu_1$-integrable. There exists then $\alpha \in L^2(X_1, \mathbb{R}^n)$ such that

$$
\int_{\Omega_1} f_s(\alpha(s)) \, d\mu_1(s) < +\infty.
$$

The inf-convolution $f_{s,k}$ in (3.4) is universally measurable, and there exists a $\mu_1$-negligible set $N \in \Sigma_1$ such that $(s, x) \mapsto f_{s,k}(x)$ is $\Sigma_1 \otimes \mathcal{B}_{\mathbb{R}^n}$-measurable on $(\Omega_1 \setminus N) \times \mathbb{R}^n$. It is possible to find for every $\alpha \in L^2(X_1, \mathbb{R}^n)$ and every $\varepsilon > 0$ a measurable selection $u(s)$ such that

$$
f_s(\alpha(s) + u(s)) + k|u(s)|^2 < f_{s,k}(\alpha(s)) + \varepsilon, \quad s \in \Omega_1 \setminus N.
$$

**Proof.** Let

$$
e^{-F(s)} = \kappa \int_{\mathbb{R}^n} e^{-f_s(x) - \varepsilon_0 |x|^2} \, dx = \int_{\mathbb{R}^n} e^{-f_s(x) - \varepsilon_0 |x|^2/2} \, d\nu(x),
$$

where $\kappa = (2\pi/\varepsilon_0)^{-n/2}$ is chosen so that $\kappa \int_{\mathbb{R}^n} e^{-\varepsilon_0 |x|^2/2} \, dx = 1$, making $\nu$ a probability measure. Consider the Borel set

$$
C = \{(s, x) : f_s(x) + \varepsilon_0 |x|^2/2 < F(s) + 1\}$$

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in the Polish space $\Omega_1 \times \mathbb{R}^n$. The projection of this set on $\Omega_1$ is an analytic set, and contains the Borel set $B := \{ F < +\infty \}$. We have $\mu_1(\Omega_1 \setminus B) = 0$. By the Jankoff–von Neumann selection theorem (see [4, Theorem 6.9.1]), we can find a universally measurable section $\sigma(s) = (s, \alpha(s)) \in C$ defined on $B$. We get that
\[ f_s(\alpha(s)) + \varepsilon_0|\alpha(s)|^2/2 < F(s) + 1, \]
from what the conclusions follow since $f_s \geq 0$.

Similarly, for every real $c$, the set $\{(s, x) : f_{s,k}(x) < c\}$ is the projection of the Borel set
\[ \{(s, x, u) : f_s(x + u) + k|u|^2 < c\}. \]
It follows that for every fixed $x$, the function $s \mapsto f_{s,k}(x)$ is universally measurable, hence $\mu_1$-equivalent to a Borel function on $\Omega_1$. Let $D$ be a countable dense set in $\mathbb{R}^n$. For every $d \in D$, there is a negligible set $N_d \subset \Sigma_1$ such that $s \mapsto f_{s,k}(d)$ is Borel outside $N_d$. Let $N = \bigcup_d N_d$. Since $x \mapsto f_{s,k}(x)$ is continuous, we get that $(s, x) \mapsto f_{s,k}(x)$ is Borel on $(\Omega_1 \setminus N) \times \mathbb{R}^n$.

Let $\alpha$ be Borel from $\Omega_1$ to $\mathbb{R}^n$. Then $\Omega_1 \setminus N$ is the projection of the Borel set
\[ \{ (s, u) : s \notin N, f_s(\alpha(s) + u) + k|u|^2 < f_{s,k}(\alpha(s)) + \varepsilon \}. \]
Consider as before a universally measurable section $\sigma(s) = (s, u(s))$ defined on $\Omega_1 \setminus N$. Then $u(s)$ provides the promised selection. \hfill \Box

**Remark 6.5.** Let $(\Omega, \Sigma)$ be a measurable space and let $\nu$ be a probability measure on $(\mathbb{R}^n, \mathcal{B}_{\mathbb{R}^n})$. Let $V$ be the set of bounded real $\Sigma \otimes \mathcal{B}_{\mathbb{R}^n}$-measurable functions $h(s, x) = h_s(x)$ satisfying that for every $\varepsilon > 0$, there exist two $\Sigma \otimes \mathcal{B}_{\mathbb{R}^n}$-measurable functions $\varphi(s, x) = \varphi_s(x)$, $\psi(s, x) = \psi_s(x)$, such that for every $s \in \Omega$, $\varphi_s \leq h_s \leq \psi_s$, $\varphi_s$ is u.s.c. on $\mathbb{R}^n$, $\psi_s$ is l.s.c. and $\int_{\mathbb{R}^n} (\psi_s - \varphi_s) \, d\nu < \varepsilon$. Then $V$ is a vector space of functions on $\Omega \times \mathbb{R}^n$, containing constants, stable by sup$(h_1, h_2)$ and stable by pointwise convergence of uniformly bounded sequences. Indeed, suppose that $h_k \in V$, $k \in \mathbb{N}$, and that $h_k(s, x) \to h(s, x)$ pointwise with $|h_k(s, x)| \leq 1$. For every $k$, let $\psi_{s,k} \geq h_{s,k}$ be l.s.c. and $\int_{\mathbb{R}^n} (\psi_{s,k} - h_{s,k}) \, d\nu < 2^{-k}$. Then, for every $s$, we have $\psi_{s,k} - h_{s,k} \to 0 \nu$-a.e. hence $\psi_{s,k} - h_s \to 0 \nu$-a.e. Next, for every $s$, $\chi_{s,n} = \sup_{k \geq n} \psi_{s,k}$ is l.s.c. and decreases to $h_s$ $\nu$-a.e. Let
\[ B_n = \{ s \in \Omega : \int_{\mathbb{R}^n} (\chi_n(s, x) - h(s, x)) \, d\nu(x) < \varepsilon \}. \]
Then $B_n \subset \Sigma$ increases to $\Omega$. Define $\psi(s, x) = \chi_n(s, x)$ when $s \in B_n \setminus B_{n-1}$, and similarly on the $\varphi$ side. We get that the pointwise limit $h$ belongs to $V$.

It follows that $V$ is the space of all bounded $\mathcal{A}$-measurable functions, for some sub-$\sigma$-algebra $\mathcal{A}$ of $\Sigma \otimes \mathcal{B}_{\mathbb{R}^n}$. Since $V$ contains all indicators of products $B \times C$, $B \in \Sigma$, $C \in \mathcal{B}_{\mathbb{R}^n}$, it follows that $\mathcal{A} = \Sigma \otimes \mathcal{B}_{\mathbb{R}^n}$. The result applies then to all $\mathcal{A}$-measurable functions $h$ such that $h_s$ is bounded for every $s$, by cutting $\Omega$ into pieces $B_k \in \Sigma$ where the bound of $h_s$ is in $[k, k+1)$. 

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Suppose that $h$ is bounded and $\geq 0$, and that $H(s) = \int_{\mathbb{R}^n} h(s, x) \, d\nu(x) > 0$ for every $s \in \Omega$. Applying the result to the function $H(s)^{-1} h(s, x)$, we find a function $\varphi(s, x)$ u.s.c. in $x$ such that $0 \leq \varphi \leq h$ and
\[
\log \left( \int_{\mathbb{R}^n} \varphi(s, x) \, d\nu(x) \right) > \log \left( \int_{\mathbb{R}^n} h(s, x) \, d\nu(x) \right) - \varepsilon
\]
for every $s$. Applying to $h(s, x) = e^{-f_s(x)}$, we get an l.s.c. in $x$ function $\psi_s(x)$ such that $f_s \leq \psi_s$ and $-\log \left( \int_{\mathbb{R}^n} e^{-\psi_s} \, d\nu \right) \leq -\log \left( \int_{\mathbb{R}^n} e^{-f_s} \, d\nu \right) + \varepsilon$. This shows that in Theorem 1.3, the function $f_s$ can be assumed to be a l.s.c. function.

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