Totally geodesic submanifolds of the complex quadric

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Abstract. In this article, relations between the root space decomposition of a Riemannian symmetric space of compact type and the root space decompositions of its totally geodesic submanifolds (symmetric subspaces) are described. These relations provide an approach to the classification of totally geodesic submanifolds in Riemannian symmetric spaces. In this way a classification of the totally geodesic submanifolds in the complex quadric $Q^m := \text{SO}(m+2)/\left(\text{SO}(2) \times \text{SO}(m)\right)$ is obtained. It turns out that the earlier classification of totally geodesic submanifolds of $Q^m$ by CHEN and NAGANO is incomplete: in particular a type of submanifolds which are isometric to 2-spheres of radius $\frac{1}{2}\sqrt{10}$, and which are neither complex nor totally real in $Q^m$, is missing.

1 Introduction

This article is concerned with the study of totally geodesic submanifolds in Riemannian symmetric spaces of compact type. Its objective is two-fold: First, we describe general relations between the roots and root spaces of such a symmetric space, and the roots resp. root spaces of its totally geodesic submanifolds. Second, we apply these results to obtain a classification of the totally geodesic submanifolds in the complex quadric $Q^m = \text{SO}(m+2)/\left(\text{SO}(2) \times \text{SO}(m)\right)$.

It should be mentioned that already CHEN and NAGANO gave a classification of the totally geodesic submanifolds of the complex quadric by “ad-hoc methods” in [CN1]. However that paper contains (besides some inaccuracies which are easily resolved) a more serious mistake, which causes two types of totally geodesic submanifolds to be missed. The submanifolds of the first of these two types are isometric to $\mathbb{CP}^1 \times \mathbb{RP}^1$; as it is explained in Section 3 their existence can be derived from the fact that $Q^2$ is holomorphically isometric to $\mathbb{CP}^1 \times \mathbb{CP}^1$ (via the Segre embedding). The manifolds of the second type are isometric to 2-spheres of radius $\frac{1}{2}\sqrt{10}$. They are neither complex nor totally real submanifolds of $Q^m$, and they are remarkable insofar as their geodesic diameter $\frac{\pi}{2}\sqrt{10}$ is strictly larger than the geodesic diameter $\frac{\pi}{\sqrt{2}}$ of $Q^m$.

In [CN2], Chen and Nagano introduced their $(M_+, M_-)$-method for the classification of totally geodesic submanifolds in Riemannian symmetric spaces of compact type, and via this method they again give a classification of the totally geodesic submanifolds in rank 2 symmetric spaces. However, the totally geodesic submanifolds of $Q^m$ which were missing from [CN1] are also missing here.

The approach to the classification of totally geodesic submanifolds taken here is as follows: It is well-known that in any symmetric space $M = G/K$, for given $p \in M$ and $U \subset T_p M$, there exists a totally geodesic submanifold $M'$ of $M$ with $p \in M'$ and $T_p M' = U$ if and only if $U$ is curvature-invariant (i.e. if $R(u,v)w \in U$ holds for every $u,v,w \in U$, where $R$ is the curvature tensor of $M$). Moreover, if we consider the decomposition $g = \mathfrak{k} \oplus \mathfrak{m}$ of the Lie algebra $g$ of $G$ induced by the symmetric space structure of $M$ (we then have the canonical isomorphism $\tau : \mathfrak{m} \to T_p M$), then $U \subset T_p M$ is curvature-invariant if and only if $m' : = \tau^{-1}(U) \subset \mathfrak{m}$ is a Lie triple system (i.e. if $[m', m', m'] \subset m'$ holds). Thus, the task of classifying the totally geodesic submanifolds of $M$ splits into two steps: (1) To classify the Lie triple systems in $\mathfrak{m}$, and (2) for each of the Lie triple systems $m'$ found in the first step, to construct a totally geodesic, connected, complete submanifold $M'$ of $M$ so that $p \in M'$ and $\tau^{-1}(T_p M') = m'$ holds.
In Section 2 Lie triple systems in Riemannian symmetric spaces of compact type are studied with regard to the theory of roots and root spaces. In particular, relations between the roots and root spaces of a Lie triple system and the roots resp. root spaces of the ambient symmetric space are derived. These relations turn out to be useful for the classification of the Lie triple systems, at least for the complex quadric, as will be seen.

The remainder of the article is concerned with the application of these general results to the complex quadric $Q^m = \text{SO}(m+2)/\left(\text{SO}(2) \times \text{SO}(m)\right)$ (a rank 2 Riemannian symmetric space); thereby a classification of the totally geodesic submanifolds of $Q^m$ is obtained. In Section 3 we describe some facts regarding the geometry of the complex quadric which are needed for the classification. These facts are mostly taken from the paper [IR] by H. Reckziegel; especially the concept of a $\mathcal{C}Q$-structure (see Definition 3.2), which is very useful for the formulation of the classification, was introduced there.

In Section 4 the main result of the present article, the classification of the Lie triple systems of the complex quadric, is obtained, see Theorem 4.1. The proof of this theorem is based on the combination of the general results on roots and root spaces of Lie triple systems from Section 2 with the specific description of the geometry of the complex quadric given in Section 3.

Finally, in Section 5 the totally geodesic submanifolds which correspond to the various Lie triple systems described in Theorem 4.1 are described; thereby the classification of the totally geodesic submanifolds of $Q^m$ is completed (see the table given in that section).

The results presented in the present paper were obtained by me in my dissertation under the advisorialship of Professor H. Reckziegel. I wish to express my sincerest gratitude for his enduring and intensive support.

2 The root space decomposition corresponding to a Lie triple system

In this section we suppose that $M = G/K$ is any Riemannian symmetric space of compact type. We consider the decomposition $g = t \oplus m$ of the Lie algebra $g$ of $G$ induced by the symmetric structure of $M$. Because $M$ is of compact type, the Killing form $\varpi : g \times g \to \mathbb{R}, (X,Y) \mapsto \text{tr}(\text{ad}(X) \circ \text{ad}(Y))$ is negative definite, and therefore $\langle \cdot, \cdot \rangle := -c \cdot \varpi$ gives rise to a Riemannian metric on $M$ for any $c \in \mathbb{R}_+$.\(^1\) In the sequel we suppose that $M$ is equipped with such a Riemannian metric.

**Definition 2.1** A linear subspace $m' \subset m$ is called a Lie triple system if $[m', m', m'] \subset m'$ holds.

As was explained in the introduction, the first step in classifying the totally geodesic submanifolds of $M$ is to classify the Lie triple systems of $m$. In this section we describe general results concerning the relationship between the roots resp. root spaces of $M$ and those of its totally geodesic submanifolds; in the case $M = Q^m$ these results will permit to classify the Lie triple systems of $Q^m$.

First we fix notations concerning flat subspaces, the roots and root spaces of $M$ (for the corresponding theory, see for example [LR], Section V.2): A linear subspace $a \subset m$ is called flat if $[a, a] = \{0\}$ holds. The maximal dimension of a flat subspace of $m$ is called the rank of $M$ (or of $m$) and is denoted by $\text{rk}(M)$. The flat subspaces $a \subset m$ with $\text{dim}(a) = \text{rk}(M)$ are called the Cartan subalgebras (or maximal flat subspaces) of $m$. We now fix a Cartan subalgebra $a \subset m$. Then we put for any linear form $\lambda \in a^*$
\[
m_\lambda := \{ X \in m \mid \forall Z \in a : \text{ad}(Z)^2X = -\lambda(Z)^2X \}
\]
and consider the root system
\[
\Delta(m, a) := \{ \lambda \in a^* \setminus \{0\} \mid m_\lambda \neq \{0\} \}
\]
of $m$ with respect to $a$. (The elements of $\Delta(m, a)$ are called roots of $m$ with respect to $a$, and for $\lambda \in \Delta(m, a)$, $m_\lambda$ is called the root space corresponding to $\lambda$.) As is well-known, we have
\[
m_0 = a
\]

\(^1\)The choice of the factor $c$ does not have any geometric significance. The only reason for considering such a factor is to accommodate the natural Riemannian metric on the complex quadric, see Equation 3.2 below.
and

\[ m = a \oplus \bigoplus_{\lambda \in \Delta_+} m_\lambda, \]

where \( \Delta_+ \subset \Delta(m,a) \) is any system of positive roots, i.e. we have \( \Delta_+ \cup (-\Delta_+) = \Delta(m,a) \) and \( \Delta_+ \cap (-\Delta_+) = \emptyset \).

Let us fix a Lie triple system \( m' \subset m \). It should be noted that \( m' \) does not need to be of compact type, and therefore the usual root theory for symmetric spaces is not applicable to \( m' \) directly. However, we will now see how the fact that \( m' \) is contained in the space \( m \) of compact type can be used to construct a root space decomposition for \( m' \). We base this construction on the fact (see [L1], Theorem IV.1.6, p. 145 and its proof) that \( m' \) can be decomposed into Lie triple systems

\[ m' = m'_{fl} \oplus m'_c \oplus m'_{nc}, \]

where \( m'_{fl} \) is flat, \( m'_c \) corresponds to a symmetric space of compact type and \( m'_{nc} \) corresponds to a symmetric space of non-compact type; moreover we have

\[ [[m', m'], m'_{fl}] = \{0\} \]

and

\[ [m', m'_{fl}] = \{0\}. \]

In fact, in the present situation \( m'_{nc} = \{0\} \) holds, as the following argument shows: Because the Riemannian symmetric space \( M \) is of compact type, its sectional curvature is \( \geq 0 \). The totally geodesic submanifold \( M' \) of \( M \) corresponding to \( m' \) therefore also has sectional curvature \( \geq 0 \). This means in particular that the Ricci curvature form of \( M' \) is positive semi-definite. On the other hand, if \( m'_{nc} \) were non-zero, it would correspond to a symmetric subspace of \( M' \) of non-compact type, whose Ricci curvature form would be negative definite, in contradiction to the preceding statement. Thus we in fact have

\[ m' = m'_{fl} \oplus m'_c. \]

Note that because \( m'_c \) is of compact type, the usual concepts of rank, Cartan subalgebras, roots and root systems are applicable to \( m'_c \).

In analogous application of the usual concepts we call the maximal dimension of a flat subspace of \( m' \) the rank of \( m' \), which we denote by \( \text{rk}(m') \). Moreover, we call a flat subspace \( a' \subset m' \) a Cartan subalgebra of \( m' \) if \( \text{dim}(a') = \text{rk}(m') \) holds.

We now fix a Cartan subalgebra \( a' \subset m' \); because of Equation (5) there exists a Cartan subalgebra \( a'_c \) of \( m'_c \) so that

\[ a' = m'_{fl} \oplus a'_c \]

holds. \( m'_c \) is of compact type, and therefore we have the usual root space decomposition with respect to \( a'_c \): We put for any \( \alpha_c \in (a'_c)^* \)

\[ (m'_c)_{\alpha_c} := \{ X \in m'_c \mid \forall Z \in a'_c : \text{ad}(Z)^2 X = -\alpha_c(Z)^2 X \} \]

and consider the root system

\[ \Delta(m'_c, a'_c) := \{ \alpha_c \in (a'_c)^* \setminus \{0\} \mid (m'_c)_{\alpha_c} \neq \{0\} \}, \]

then we have

\[ m'_c = a'_c \oplus \bigoplus_{\alpha \in \Delta_+(m'_c, a'_c)} (m'_c)_{\alpha_c}, \]

where \( \Delta_+(m'_c, a'_c) \) is any system of positive roots in \( \Delta(m'_c, a'_c) \).

Now we define for any \( \alpha_c \in (a'_c)^* \) the linear form \( \alpha \in (a')^* \) by \( \alpha|a'_c = \alpha_c \) and \( \alpha|m'_{fl} = 0 \). Then for any \( \alpha_c \in (a'_c)^* \setminus \{0\} \)

\[ m'_{\alpha_c} := \{ X \in m' \mid \forall Z \in a' : \text{ad}(Z)^2 X = -\alpha(Z)^2 X \} = (m'_c)_{\alpha_c} \]

holds, and therefore Equations (4), (6) and (7) show that we have the root space decomposition

\[ m' = a' \oplus \bigoplus_{\alpha \in \Delta_+(m', a')} m'_{\alpha_c}, \]
with respect to the root system
\[ \Delta(m', a') := \{ \alpha \mid \alpha_c \in \Delta(m'_c, a'_c) \} ; \]
\[ \Delta_+(m', a') \] is a system of positive roots in \( \Delta(m', a') \).

The following proposition describes relations between the root systems \( \Delta(m, a) \) and \( \Delta(m', a') \), as well as between the root spaces \( m'_e \) and \( m_\lambda \).

**Proposition 2.2** Let \( a \) be a Cartan subalgebra of \( m \) such that \( a' := a \cap m' \) is a Cartan subalgebra of \( m' \).

(a) The roots resp. root spaces of \( m \) and of \( m' \) are related by the following equations:

\[ m'_0 = a', \quad (9) \]
\[ \Delta(m', a') \subset \{ \lambda|a' \mid \lambda \in \Delta(m, a), \lambda|a' \neq 0 \} ; \quad (10) \]
\[ \forall \alpha \in \Delta(m', a') : m'_\alpha = \left( \bigoplus_{\lambda \in \Delta(m, a)} m_\lambda \right) \cap m'. \quad (11) \]

(b) We have \( \text{rk}(m') = \text{rk}(m) \) if and only if \( a' = a \) holds. If this is the case, then we have

\[ \Delta(m', a') \subset \Delta(m, a), \quad \forall \alpha \in \Delta(m', a') : m'_\alpha = m_\alpha \cap m' \quad (12) \]

**Proof.** Equation (12) follows by the usual argument: Because \( a' \) is flat, we have \( a' \subset m'_0 \). Conversely, let \( X \in m'_0 \) be given. Then we have for every \( Z \in a' : \text{ad}(Z)^2X = 0 \) and therefore \( 0 = \alpha(\text{ad}(Z)^2X, X) = -\alpha(\text{ad}(Z)X, \text{ad}(Z)X) \). Because the Killing form \( \alpha \) of \( g \) is negative definite, it follows that \( \text{ad}(Z)X = 0 \) holds. From this fact and \( [a', a'] = \{ 0 \} \), we see that \( [a' + IRX, a' + IRX] = \{ 0 \} \) holds, showing that \( a' + IRX \) is flat. Because of the maximality of \( a' \) we conclude \( X \in a' \).

Now let \( \Delta_+ \subset \Delta(m, a) \) be a system of positive roots of \( m \) and put \( \Delta'_+ := \Delta_+ \cup \{ 0 \} \). Then we have by (12) and (11)

\[ m = \bigoplus_{\lambda \in \Delta_+} m_\lambda. \quad (13) \]

Let \( \alpha \in \Delta(m', a') \) and \( X \in m'_e \) be given. We have \( X \in m \) and therefore Equation (12) shows that there exists a decomposition

\[ X = \sum_{\lambda \in \Delta_+} X_\lambda \quad (14) \]

with suitable (unique) \( X_\lambda \in m_\lambda \) for \( \lambda \in \Delta_+ \).

Because of \( X \in m'_e \) and Equation (14), we have

\[ \forall Z \in a' : \text{ad}(Z)^2X = -\alpha(Z)^2X = -\sum_{\lambda \in \Delta_+} \alpha(Z)^2X_\lambda. \quad (15) \]

On the other hand, we have \( X_\lambda \in m_\lambda \) for every \( \lambda \in \Delta_+ \) and therefore

\[ \forall Z \in a' : \text{ad}(Z)^2X = \sum_{\lambda \in \Delta_+} \text{ad}(Z)^2X_\lambda = -\sum_{\lambda \in \Delta_+} \lambda(Z)^2X_\lambda. \quad (16) \]

By comparing Equations (15) and (16) we obtain

\[ \forall Z \in a' : \sum_{\lambda \in \Delta_+} \alpha(Z)^2X_\lambda = \sum_{\lambda \in \Delta_+} \lambda(Z)^2X_\lambda \]

and therefore, because of the directness of the sum in Equation (14),

\[ \forall \lambda \in \Delta_+, Z \in a' : \alpha(Z)^2 \cdot X_\lambda = \lambda(Z)^2 \cdot X_\lambda. \]

Thus, we have \( X_\lambda = 0 \) for every \( \lambda \in \Delta_+ \) with \( \lambda^2|a'| \neq \alpha^2 \), and therefore Equation (14) shows

\[ X \in \bigoplus_{\lambda \in \Delta_+} m_\lambda = \bigoplus_{\lambda \in \Delta(m, a)} m_\lambda ; \]

for the last equality, one has to note that for any pair \( (\alpha_1, \alpha_2) \) of linear forms on \( a' \), \( \alpha_1^2 = \alpha_2^2 \) already implies \( \alpha_1 = \pm \alpha_2 \). This completes the proof of the inclusion “\( \subset \)” of Equation (14). Its converse inclusion follows immediately from the definitions of \( m_\lambda \) and \( m'_\alpha \).

For any given \( \alpha \in \Delta(m', a') \) we have \( m'_\alpha \neq \{ 0 \} \) and therefore (11) implies the existence of \( \lambda \in \Delta(m, a) \) with \( \alpha = \lambda|a' \); this observation proves (10).

It remains to verify (b). We suppose \( \text{rk}(m') = \text{rk}(m) \). Because \( a' \) and \( a \) are Cartan subalgebras of \( m' \) and \( m \) respectively, we then have \( \dim a' = \text{rk}(m') = \text{rk}(m) = \dim a \) and therefore \( a' = a \). The remaining statements of (b) now follow from (a).
Definition 2.3 Let \( a \) be a Cartan subalgebra of \( \mathfrak{m} \) so that \( a' := a \cap \mathfrak{m}' \) is a Cartan subalgebra of \( \mathfrak{m}' \). Also let \( \alpha \in \Delta(\mathfrak{m}', a') \) be given. Recall that by Proposition 2.2(a) there exists at least one root \( \lambda \in \Delta(\mathfrak{m}, a) \) with \( \lambda|\alpha' = \alpha \). We call \( \alpha \)

(a) elementary, if there is only one root \( \lambda \in \Delta(\mathfrak{m}, a) \) with \( \lambda|\alpha' = \alpha \);
(b) composite, if there are at least two different roots \( \lambda, \mu \in \Delta(\mathfrak{m}, a) \) with \( \lambda|\alpha' = \mu|\alpha' = \alpha \).

In the situation described in Definition 2.3, elementary roots play a special role: If \( \alpha \in \Delta(\mathfrak{m}', a') \) is elementary, then the root space \( \mathfrak{m}_\alpha' \) is contained in the root space \( \mathfrak{m}_\lambda ', \) where \( \lambda \in \Delta(\mathfrak{m}, a) \) is the unique root with \( \lambda|\alpha' = \alpha \).

As we will see in Proposition 2.4 below, this property causes restrictions for the possible positions (in relation to \( \alpha' \)) of \( \lambda \). The exploitation of these restrictions will play an important role in the classification of the Lie triple systems of the complex quadric in Section 4.

It should be mentioned that in the case \( \text{rk}(\mathfrak{m}') = \text{rk}(\mathfrak{M}) \) we have \( \alpha' = \alpha \), and therefore in that case every \( \alpha \in \Delta(\mathfrak{m}', a') \) is elementary (see Proposition 2.2(b)).

For any linear form \( \lambda \in a^* \) we now denote by \( \lambda^\sharp \) the Riesz vector corresponding to \( \lambda \), i.e. the vector \( \lambda^\sharp \in a \) characterized by \( \langle \cdot, \lambda^\sharp \rangle = \lambda \).

Proposition 2.4 Let \( a \) be a Cartan subalgebra of \( \mathfrak{m} \) so that \( a' := a \cap \mathfrak{m}' \) is a Cartan subalgebra of \( \mathfrak{m}' \). Also let \( \alpha \in \Delta(\mathfrak{m}', a') \) be given.

(a) If \( \alpha \) is elementary and \( \lambda \in \Delta(\mathfrak{m}, a) \) is the unique root with \( \lambda|\alpha' = \alpha \), then we have \( \lambda^\sharp \in \mathfrak{m}' \).

(b) If \( \alpha \) is composite and \( \lambda, \mu \in \Delta(\mathfrak{m}, a) \) are two different roots with \( \lambda|\alpha' = \alpha = \mu|\alpha' \), then \( \lambda^\sharp - \mu^\sharp \) is orthogonal to \( \alpha' \).

Proof. For (a). Let \( \alpha \in \Delta(\mathfrak{m}', a') \) be an elementary root and \( \lambda \in \Delta(\mathfrak{m}, a) \) be the root with \( \lambda|\alpha' = \alpha \). We fix \( X \in \mathfrak{S}(\mathfrak{m}_\alpha') \) arbitrarily. By Proposition 2.2(a) we have \( X \in \mathfrak{m}_\lambda' \). Thus there is exactly one \( \tilde{X} \in \mathfrak{t}_\lambda \) which is related to \( X \in \mathfrak{m}_\lambda' \) in the sense (see 122, Lemma VI.1.5, p. 62) that

\[ \forall Z \in a : \langle [Z, X] = \lambda(Z) \cdot \tilde{X} \quad \text{and} \quad [Z, \tilde{X}] = -\lambda(Z) \cdot X \rangle \quad (17) \]

holds, and then we also have

\[ [X, \tilde{X}] = \lambda^\sharp \quad (18) \]

We now fix \( Z \in a' \) so that \( \lambda(Z) = \alpha(Z) = -1 \) holds; then we have

\[ \mathfrak{m}' \ni \text{ad}(X)^2Z = [X, [X, Z]] = -[X, [X, Z]] \]

where \((*)\) follows from the fact that \( \mathfrak{m}' \) is a Lie triple system. Therefore we have \( \lambda^\sharp \in \mathfrak{m}' \cap a = a' \).

(b) is obvious. \( \square \)

Remark 2.5 Investigating root systems of Lie algebras, Eschenburg used concepts similar to the elementary/composite roots from Definition 2.3, see \( \text{E}, \) Abschnitt 91, p. 131ff. That situation is different from ours, because in contrary to symmetric spaces, the root spaces of Lie algebras are always 1-dimensional.

We also consider the Weyl group of a Lie triple system:

Definition 2.6 Let \( a' \) be a Cartan subalgebra of \( \mathfrak{m}' \). For \( \alpha \in \Delta(\mathfrak{m}', a') \) we denote by \( \mathfrak{R}_\alpha : a' \rightarrow a' \) the orthogonal reflection in the hyperplane \( \alpha^{-1}([0]) \). Then we call the group of orthogonal transformations of \( a' \) generated by \( \{ \mathfrak{R}_\alpha : \alpha \in \Delta(\mathfrak{m}', a') \} \) the Weyl group \( W(\mathfrak{m}', a') \) of \( \mathfrak{m}' \) (with respect to \( a' \)). \( W(\mathfrak{m}', a') \) also acts on \( (a')^* \) via the action \( (B, \alpha) \mapsto \alpha \circ B^{-1} \).

For \( m \) we use the analogous notations, where we omit the \( ' \) from the symbols.

The following proposition shows that various well-known facts concerning the Weyl group of a Riemannian symmetric space of compact type transfer to the present situation for \( \mathfrak{m}' \). It also gives a relation between the Weyl groups \( W(\mathfrak{m}', a') \) and \( W(\mathfrak{m}, a) \).
Proposition 2.7 Let $a$ be a Cartan subalgebra of $m$ so that $a' := a \cap m'$ is a Cartan subalgebra of $m'$.  
(a) We have $W(m', a') \subset W(m, a)$ (remember that $a' = a$ then holds).
(b) Let us denote by $K'$ the connected Lie subgroup of $G$ with Lie algebra $\mathfrak{k}' := [m', m']$ , then $K'$ is also a subgroup of $K$. Also let $B \in W(m', a')$ be given. Then there exists $g \in K'$ so that $B = \text{Ad}(g)a'$ holds.
(c) The Weyl group $W(m', a')$ leaves the root system $\Delta(m', a')$ invariant.

Proof. For (a). It suffices to show $R_{\alpha}' = (P_{\alpha} \circ \text{R}_{\alpha})a'$ for any given $\alpha \in \Delta(m', a')$, where $\lambda \in \Delta(m, a)$ is chosen so that $\lambda|a' = \alpha$ holds; the existence of such a $\lambda$ follows from Equation (10) in Proposition 2.4(a). Indeed, in this situation we have $\alpha^2 = P_{\alpha}m'$ and therefore for every $Z \in a'$

$$R_{\alpha}'(Z) = Z - 2(Z, \alpha^2)\alpha^2 = Z - 2(Z, P_{\alpha}(\lambda^2))P_{\alpha}(\lambda^2) = P_{\rho}(Z - 2(Z, \lambda^2)\lambda^2) = P_{\rho}(R_{\lambda}(Z)),$$

the equals sign marked (*) follows from the fact that $Z \in a'$ holds.

For (b). It suffices to show that for any given $\alpha \in \Delta(m', a')$, there exists $g \in K'$ so that $R_{\alpha}' = \text{Ad}(g)a'$ holds. For this purpose we choose $Z_0 \in a'$ so that $\alpha(Z_0) = 1$ holds, moreover we fix $X \in \mathfrak{s}(m'_a)$ and put

$$\tilde{X} := [Z_0, X] \in \mathfrak{t'},$$

(then $\tilde{X}$ is related to $X$ in the sense of $\mathcal{E}$, Lemma VI.1.5, p. 62) and

$$g := \text{Exp}(t_0X) \in K' \text{ with } t_0 := \pi \frac{\alpha}{\|\alpha^2\|},$$

where $\text{Exp} : g \rightarrow G$ denotes the exponential map of the Lie group $G$. We then have $\text{Ad}(g)a' = -\alpha^2$ (compare $\mathcal{E}$, Lemma VI.1.5(c), p. 62) and by a calculation similar to the one in the proof of $\mathcal{E}$, Lemma VI.1.5(c) on p. 63 for every $Z \in a'$ which is orthogonal to $\alpha^2$: $\text{Ad}(g)Z = Z$. Therefrom $\text{Ad}(g)a' = R_{\alpha}'$ follows.

For (c). It suffices to show that we have $\beta \circ B^{-1} \in \Delta(m', a')$ for any given $\beta \in \Delta(m', a')$ and $B \in W(m', a')$. By (b), there exists $g \in K'$ so that $B = \text{Ad}(g)a'$ holds. In particular, we have $\text{Ad}(g)a' = a'$, and below we will show

$$\text{Ad}(g)m' = m'.$$

(20)

Therefrom we obtain

$$\text{Ad}(g)m'_g = \{ \text{Ad}(g)X \mid X \in m' \}, \forall Z \in a' : \text{ad}(Z)^2X = -\beta(Z)^2X \}

= \{ X \in \text{Ad}(g)m' \mid \forall Z \in a' : \text{ad}(Z)^2(\text{Ad}(g)^{-1}X) = -\beta(Z)^2(\text{Ad}(g)^{-1}X) \}

= \{ X \in m' \mid \forall Z \in a' : \text{Ad}(g)^{-1}(\text{ad}(\text{Ad}(g)^{-1})Z_2X) = (\text{Ad}(g)^{-1}(-\beta(Z)^2X) \}

= \{ X \in m' \mid \forall Z \in a' : \text{ad}(\text{Ad}(g)^{-1})Z_2X = -\beta(Z)^2X \}

= \{ X \in m' \mid \forall Z \in a' : \text{ad}(\text{Ad}(g)^{-1})Z_2X = -(\beta \circ B^{-1})(Z)^2X \}

= \{ X \in m' \mid \forall Z \in a' : \text{ad}(\text{Ad}(g)^{-1})Z_2X = -(\beta \circ B^{-1})(Z)^2X \} = m'_{\beta \circ B^{-1}}.

Because of $\beta \in \Delta(m', a')$ we have $m'_{\beta} \neq \{0\}$ and therefore by the preceding calculation also $m'_{\beta \circ B^{-1}} \neq \{0\}$, whence $\beta \circ B^{-1} \in \Delta(m', a')$ follows.

For the proof of Equation $\mathcal{E}$, we may suppose without loss of generality that $B = R_{\alpha}'$ holds for some $\alpha \in \Delta(m', a')$. We now use the notations from the proof of (b), especially $g$ is now given by $\mathcal{E}$, let $Y \in m'$ be given and consider the function

$$f : \mathbb{R} \rightarrow m', \ t \mapsto \text{Ad}(\text{Exp}(t\tilde{X}))Y = \exp(t \text{ad}(\tilde{X}))Y,$$

where $\text{exp} : \text{End}(g) \rightarrow \text{GL}(g)$ is the usual exponential map of endomorphisms. $f$ solves the differential equation

$$y' = \text{ad}(\tilde{X})y.$$  (21)

Because $m'$ is a Lie triple system and we have $\tilde{X} \in \mathfrak{t}' = [m', m']$, we see that the endomorphism $\text{ad}(\tilde{X})$ leaves $m'$ invariant. Because we also have $f(0) = Y \in m'$, the solution $f$ of the differential equation $\mathcal{E}$ runs entirely in $m'$. In particular we have $\text{Ad}(g)Y = f(t_0) \in m'$. Thus we have shown $\text{Ad}(g)m' \subset m'$; because $\text{Ad}(g)$ is a linear isomorphism, we conclude $\mathcal{E}$. $\square$

3 The geometry of the complex quadric

We now turn our attention specifically to the complex quadric, which we also regard as a complex hypersurface in the complex projective space $\mathbb{C}P^{m+1}:

$$Q := Q^m := \left\{ [z_0, \ldots, z_{m+1}] \in \mathbb{C}P^{m+1} \mid \sum_k z_k^2 = 0 \right\}.$$  

We regard $\mathbb{C}P^{m+1}$ as a Hermitian manifold via the Fubini-Study metric $\langle \cdot, \cdot \rangle$ and the usual complex structure $J$. These data are characterized by the fact that the Hopf fibration $\pi : S^{2m+3} \rightarrow \mathbb{C}P^{m+1}$, $z \mapsto [z] := Cz$ (where
we regard the unit sphere \( S^{2m+3} \) as a submanifold of \( \mathbb{CP}^{m+2} \) becomes a Hermitian submersion, meaning that if we consider for \( z \in S(\mathbb{CP}^{m+2}) \) the horizontal space \( H_z := \ker(T_z \pi) \), then \( T_z \pi | H_z : H_z \to T_{\pi(z)} \mathbb{CP}^{m+1} \) is a complex linear isometry. It should be noted that via the mentioned structures, we also obtain complex inner products \( \langle \cdot, \cdot \rangle_q \) on the tangent spaces of \( \mathbb{CP}^{m+1} \):

\[
\forall p \in \mathbb{CP}^{m+1}, \ v, w \in T_p \mathbb{CP}^{m+1} : \langle v, w \rangle_q = \langle v, w \rangle + i \cdot \langle v, Jw \rangle.
\]

One objective of the present paper is to classify the totally geodesic submanifolds of \( Q \). To this end, we require some information about the geometry of \( Q \), which is now given. Most of the results stated in the present section are taken from the paper [R] by H. RECKZIEGEL; in particular the concept of a \( \mathbb{CP}Q \)-structure and its application to the study of the complex quadric were introduced there.

The following proposition describes the fundamental data concerning the intrinsic and extrinsic geometry of \( Q \subset \mathbb{CP}^{m+1} \). For \( p \in Q \) we denote by \( \mathbb{P}^1 Q := (T_p Q)^\perp \cap T_p \mathbb{CP}^{m+1} \) the normal space of \( Q \subset \mathbb{CP}^{m+1} \) at \( p \) and also consider the set of unit normal vectors \( \mathbb{P}N Q := \mathbb{S}(\mathbb{P}^1 Q) \). \( \mathbb{P}^1 Q \) is a “circle” in the sense that for \( \eta_0 \in \mathbb{P}^1 Q \), \( \mathbb{P}^1 Q = \{ \lambda \eta_0 \mid \lambda \in \mathbb{S}^1 \} \) holds.

**Proposition 3.1** Let \( p \in Q \) and \( \eta \in \mathbb{P}^1 Q \) be given.

(a) The shape operator \( A_\eta : T_p Q \to T_p Q \) of \( Q \subset \mathbb{CP}^{m+1} \) with respect to \( \eta \) is an orthogonal, anti-linear\(^4\) involution; moreover \( A_\eta \lambda = \lambda \cdot A_\eta \) holds for \( \lambda \in \mathbb{S}^1 \).

An explicit description of \( A_\eta \) is given in the following way: For \( z \in \pi^{-1}\{p\} \), we have \( H_z = (\mathbb{P}^1 Q) \), and the horizontal lift of \( T_p Q \) at \( z \) is given by \( H_z := H_z \cap (T_z \pi)^{-1}(T_p Q) = (\mathbb{P}^1 Q) \) (where \( \mathbb{P} \) denotes the usual conjugation of \( z \in \mathbb{CP}^{m+2} \)). There exists \( z \in \pi^{-1}\{p\} \) (depending on \( \eta \)), so that the following diagram commutes:

\[
\begin{array}{ccc}
H_z Q & \xrightarrow{\pi_\eta} & H_z Q \\
\pi_\eta | H_z Q & | & \pi_\eta | H_z Q \\
T_p Q & \xrightarrow{A_\eta} & T_p Q.
\end{array}
\]

(b) The curvature tensor \( R \) of \( Q \) at \( p \) is described via \( A_\eta \) by the equation

\[
R(u, v)w = \langle w, v \rangle_q u - \langle w, u \rangle_q v - 2 \langle J u, v \rangle J w + \langle v, A_\eta w \rangle_q A_\eta u - \langle u, A_\eta w \rangle_q A_\eta v.
\]

**Proof.** See [R], Section 3.

As Proposition 3.1(b) shows, the curvature tensor of the complex quadric \( Q \), and therefore the local geometric structure of this Riemannian manifold, is described entirely by the Riemannian metric of \( Q \), its complex structure \( J \) and the “circle of conjugations”

\[
\mathfrak{A}(Q, p) := \{ A_\eta \mid \eta \in \mathbb{P}^1 Q \} = \{ \lambda \cdot A_\eta_0 \mid \lambda \in \mathbb{S}^1 \},
\]

where \( \eta_0 \in \mathbb{P}^1 Q \) is fixed arbitrarily. In order to perform the investigation of this situation in a clearer manner, we formulate some relevant concepts and results in an abstract setting.

**Definition 3.2** Let \( V \) be a unitary space with complex inner product \( \langle \cdot, \cdot \rangle_q \) and complex structure \( J : V \to V \), \( v \mapsto i \cdot v \).

(a) A conjugation on \( V \) is an anti-linear involution \( A : V \to V \) which is orthogonal with respect to the induced real inner product \( \langle \cdot, \cdot \rangle := \text{Re}(\langle \cdot, \cdot \rangle_q) \).

(b) Let \( A \) be a conjugation on \( V \). Then we call the circle of conjugations \( \mathfrak{A} := \{ \lambda A \mid \lambda \in \mathbb{S}^1 \} \) a \( \mathbb{CP}Q \)-structure on \( V \). We call the pair \( (V, \mathfrak{A}) \) (or simply \( V \), if the implied \( \mathbb{CP}Q \)-structure is obvious) a \( \mathbb{CP}Q \)-space.

We now suppose that \( (V, \mathfrak{A}) \) and \( (V', \mathfrak{A}') \) are \( \mathbb{CP}Q \)-spaces.

(c) We call a unitary map \( B : V \to V' \) a \( \mathbb{CP}Q \)-isomorphism, if \( B \circ A \circ B^{-1} \in \mathfrak{A}' \) holds for every \( A \in \mathfrak{A} \). In the case \( (V', \mathfrak{A}') = (V, \mathfrak{A}) \) we speak of a \( \mathbb{CP}Q \)-automorphism. We denote the group of \( \mathbb{CP}Q \)-automorphisms of \( (V, \mathfrak{A}) \) by \( \text{Aut}(\mathfrak{A}) \).

\(^3\)Here and in the sequel, we regard the unit circle \( \mathbb{S}^1 \) also as a subset of \( \mathbb{P} \).

\(^4\)We call an \( \mathbb{R} \)-linear map \( A : V \to V \) on the \( \mathbb{C} \)-linear space \( V \) anti-linear, if \( A \circ J = -J \circ A \) holds.
Let us now consider $A$, anti-linear, we have $\text{Eig}(A)$, therefore real orthogonally diagonalizable. Because for any $A \in \mathfrak{A}$ holds. From (24) one can derive the following equations for every $v, w \in \mathcal{V}$ and the analogous decomposition for $w$:

$$\text{Re}_A(v, \text{Re}_A w) = (\text{Im}_A v, \text{Im}_A w) = \frac{1}{2}(v, w),$$

$$\text{Re}_A(v, \text{Im}_A w) = -(\text{Im}_A v, \text{Re}_A w).
$$
Proposition 3.5  

(a) $G$ acts transitively on $Q$. For given $p \in Q$, say $p = \pi(z)$ with $z \in S^{2m+3}$, the isotropy group of this action at $p$ is

$$K := \{ B \in G \mid B(W) = W \},$$

where $W \subset \mathfrak{g}^{m+2}$ is the complex-2-dimensional space spanned by $z$ and $\bar{z}$.

(b) The image of the isotropy representation $K \rightarrow U(T_qQ) , B \mapsto T_B\pi$ is equal to $\text{Aut}(\mathfrak{g}(Q,p))_0$.

(c) Let $S : \mathfrak{q}^{m+2} \rightarrow \mathfrak{q}^{m+2}$ the $\mathfrak{q}$-linear map characterized by $S|W = \text{id}_W$ and $S|((W^\perp) = -\text{id}_{W^\perp}$. Then we have $-S \in G$ and the involutive Lie group automorphism

$$\sigma : G \rightarrow G, B \mapsto S \circ B \circ S^{-1}$$

satisfies $\text{Fix}(\sigma)_0 = K$. Consequently $\sigma$ defines the structure of a Hermitian symmetric space on $Q$; its canonical covariant derivative is identical to the Levi-Civita covariant derivative of $Q$.

(d) The Hermitian symmetric space $Q$ is of compact type; it is irreducible for $m \neq 2$.

(e) The canonical decomposition $\mathfrak{g} = \mathfrak{k} \oplus \mathfrak{m}$ of the Lie algebra $\mathfrak{g} = \mathfrak{o}(m+2) \cong \text{End}_\mathbb{C}(\mathfrak{q}^{m+2})$ of $G$ with respect to $\sigma$ is given by

$$\mathfrak{k} = \{ X \in \mathfrak{g} \mid X(W) \subset W, X(W^\perp) \subset W^\perp \}$$

$$\mathfrak{m} = \{ X \in \mathfrak{g} \mid X(W) \subset W^\perp, X(W^\perp) \subset W \}.$$
Proof. For (b), see [R], Theorem 2. The remaining facts are well-known. □

Remark 3.6 The isotropy group $K$ mentioned in Proposition 3.5(a) is isomorphic to $\text{SO}(2) \times \text{SO}(m)$. Thus we obtain the conventional quotient space representation $\text{SO}(m+2)/\left(\text{SO}(2) \times \text{SO}(m)\right)$ of the complex quadric.

Let us now fix $p \in Q$ and consider the corresponding decomposition $g = t \oplus m$ as in Proposition 3.5(d). As is well-known, the space $m$ is linked to the tangent space $T_pQ$ by the linear isomorphism

$$\tau : m \rightarrow T_pQ, \ X \mapsto (\Psi(\cdot,p))_*X,$$

and we have

$$\forall B \in G : \tau \circ (\text{Ad}(B))|m = T_pB \circ \tau,$$
$$\forall X, Y, Z \in m : R(\tau(X), \tau(Y))\tau(Z) = -\tau([[X, Y], Z]),$$

where in the second equation, $R$ again denotes the curvature tensor of $Q$. In this way, $m$ becomes a $\mathbb{C}$-space via the complex structure $J$, the complex inner product $\langle \cdot, \cdot \rangle_Q$ and the $\mathbb{C}$-structure $\mathfrak{A} := \mathfrak{A}(Q, p)$, and we have $R(X, Y)Z = -[[X, Y], Z]$ for any $X, Y, Z \in m = T_pQ$. Note especially that for a linear subspace $m' \subset m$, the notions of $m'$ being a Lie triple system and of $m'$ being a curvature-invariant subspace (meaning that $R(X, Y)Z \in m'$ holds for every $X, Y, Z \in m'$) therefore coincide.

Via an explicit calculation, one can show that the real inner product $\langle \cdot, \cdot \rangle = \text{Re}(\langle \cdot, \cdot \rangle_Q)$ thereby induced on $m$ satisfies

$$\forall X, Y \in m : \langle X, Y \rangle = -\frac{1}{4m} \cdot \varkappa(X, Y),$$

where $\varkappa : g \times g \rightarrow \mathbb{R}$, $(X, Y) \mapsto \text{tr}(\text{ad}(X) \circ \text{ad}(Y))$ is the Killing form of $g$. Therefore the Riemannian metric on $Q$ is in accordance with the situation considered in Section 2.

We now suppose $m \geq 2$.

Proposition 3.7 (a) The Hermitian symmetric space $Q$ is of rank 2, and the Cartan subalgebras $\mathfrak{a}$ of $m$ are exactly the spaces

$$\mathfrak{a} = \mathbb{R}X \oplus \mathbb{R}JY$$

with $A \in \mathfrak{A}$, $X, Y \in \mathbb{S}(V(A))$, $\langle X, Y \rangle = 0$.

(b) Let $\mathfrak{a} = \mathbb{R}X \oplus \mathbb{R}JY$ be a Cartan subalgebra of $m$ as in (a). Then the following table gives besides $\lambda_0 := 0 \in \mathfrak{a}^*$ a system of positive roots $\lambda_k$ of $m$ with respect to $\mathfrak{a}$ (via their Riesz vectors $\lambda_k^\sharp$), together with the corresponding root spaces $m_{\lambda_k}$ and their multiplicities $n_{\lambda_k}$:

| $k$ | $\lambda_k^\sharp \in \mathfrak{a}$ | $m_{\lambda_k}$ | $n_{\lambda_k}$ |
|-----|-----------------|-----------------|--------------|
| 0   | 0               | $\mathbb{R}X \oplus \mathbb{R}JY$ | 2            |
| 1   | $\sqrt{2} \cdot JY$ | $J((\mathbb{R}X \oplus \mathbb{R}JY)\perp)$ | $m - 2$      |
| 2   | $\sqrt{2} \cdot X$  | $(\mathbb{R}X \oplus \mathbb{R}JY)\perp$ | $m - 2$      |
| 3   | $\sqrt{2} \cdot (X - JY)$ | $\mathbb{R}(JX + Y)$ | 1            |
| 4   | $\sqrt{2} \cdot (X + JY)$ | $\mathbb{R}(JX - Y)$ | 1            |

Here $\perp$ denotes the ortho-complement in $V(A)$. In the case $m = 2$ the roots $\lambda_1$ and $\lambda_2$ do not exist: their multiplicity is zero.

Proof. See [R], Sections 5 and 6. □

Thus we see that the Riemannian symmetric space $Q$ has (for $m \geq 3$) the following root diagram:

$$-\lambda_0^\sharp \bullet \quad \lambda_1^\sharp \bullet \quad \lambda_2^\sharp \bullet \quad -\lambda_3^\sharp \bullet \quad -\lambda_4^\sharp \bullet \quad \lambda_3^\sharp \bullet \quad \lambda_4^\sharp \bullet \quad -\lambda_0^\sharp$$

3 The geometry of the complex quadric
4 The classification of Lie triple systems in the complex quadric

We continue to consider the specific situation in the complex quadric $Q := Q^m$ with $m \geq 2$ described in the preceding section. Remember that $G := \text{SO}(m+2)$ acts transitively on $Q$; we consider the decomposition $g = t \oplus m$ of the Lie algebra of $G$ induced by the symmetric structure of $Q$ as was described in Proposition 3.10 and identify $m$ with $T_pQ$ as before. In this way we again regard $m$ as a $\mathfrak{Q}$-space via the $\mathfrak{Q}$-structure $\mathfrak{A} := \mathfrak{A}(Q,p)$.

In the present section, we will prove the following theorem:

**Theorem 4.1** A real linear subspace $\{0\} \neq m' \subseteq m$ is a Lie triple system if and only if it is of one of the types described in the following list:

1. $(\text{Geo})$ $m = \mathbb{R}v$ holds for some $v \in S(m)$.
2. $(G1,k)$ $m'$ is a $k$-dimensional $\mathfrak{Q}$-subspace of $m$ (see Definition 3.2(d) and Proposition 3.4(b)); here we have $2 \leq k \leq m - 1$.
3. $(G2,k_1,k_2)$ There exist $A \in \mathfrak{A}$ and linear subspaces $W_1,W_2 \subseteq V(A)$ of real dimension $k_1$ resp. $k_2$ so that $W_1 \perp W_2$ and $m' = W_1 \oplus JW_2$ holds; here we have $k_1,k_2 \geq 1$ and $k_1 + k_2 \leq m$.
4. $(G3)$ There exists $A \in \mathfrak{A}$ and an orthonormal system $(x,y)$ in $V(A)$ so that $m' = \mathbb{C}(x - Jy) \oplus \mathbb{R}(x + Jy)$ holds.
5. $(P1,k)$ There exists $A \in \mathfrak{A}$ so that $m'$ is a $k$-dimensional $\mathbb{R}$-linear subspace of $V(A)$; here we have $1 \leq k \leq m$.
6. $(P2)$ There exists $A \in \mathfrak{A}$ and $x \in S(V(A))$ so that $m' = \mathbb{C}x$ holds.
7. $(A)$ There exists $A \in \mathfrak{A}$ and an orthonormal system $(x,y,z)$ in $V(A)$ so that $m' = \mathbb{R}(2x + Jy) \oplus \mathbb{R}(y + Jx + \sqrt{3}Jz)$ holds; this type exists only for $m \geq 3$.
8. $(I1,k)$ $m'$ is a complex $k$-dimensional isotropic subspace of $m$ (see Definition 3.2(e) and Proposition 3.4(c)(i)); here we have $1 \leq k \leq \frac{m}{2}$.
9. $(I2,k)$ $m'$ is a totally real, real-$k$-dimensional isotropic subspace of $m$ (see Definition 3.2(e) and Proposition 3.4(c)(ii)); here we have $1 \leq k \leq \frac{m}{2}$.

The various types of curvature-invariant spaces have the following properties:

| type of $m'$ | dim$_{\mathbb{R}} m'$ | $m'$ complex or totally real | rk($m'$) | $m'$ maximal? |
|-------------|-------------------|-----------------------------|---------|---------------|
| (Geo)       | 1                 | totally real                | 1       | no            |
| (G1,k)      | $2k$              | complex                     | 2       | for $k = m-1 \geq 2$ |
| (G2,k_1,k_2)| $k_1 + k_2$      | totally real                | 2       | for $k_1 + k_2 = m \geq 3$ |
| (G3)        | 3                 | neither                     | 2       | only for $m = 2$ |
| (P1,k)      | $k$               | totally real                | 1       | for $k = m$   |
| (P2)        | 2                 | complex                     | 1       | only for $m = 2$ |
| (A)         | 2                 | neither                     | 1       | only for $m = 3$ |
| (I1,k)      | $2k$              | complex                     | 1       | for $2k = m \geq 4$ |
| (I2,k)      | $k$               | totally real                | 1       | no            |

**Remark 4.2** In the type specifications, the abbreviation “Geo” obviously stands for “geodesic”, as the Lie triple systems of this type correspond to the traces of geodesics in $Q$. The letters G, P, A and I stand for the words “generic” (because such spaces contain entire Cartan subalgebras of $Q$), “principal”, “arctan” (because such spaces bear a relation to the angle arctan($\frac{1}{2}$)) as will be described in Section 4.2) and “isotropic”, respectively.

**Proof of Theorem 4.1** Via Proposition 3.1(b) one verifies that the spaces mentioned in the theorem are indeed curvature-invariant and therefore Lie triple systems, and one also sees easily that the information in the table on the dimension of the spaces and on their being complex or totally real is correct. For the data on the rank of $m'$: Because the complex quadric has rank 2, we have rk($m'$) $\in \{1,2\}$ in any case, and rk($m'$) = 2 holds if and only if $m'$ contains a Cartan subalgebra of $m$. Via the explicit description of the Cartan subalgebras of $m$ in Proposition 3.7(a), one sees by this argument that $m'$ is of rank 2 if it is of one of the types $(G1,k)$, $(G2,k_1,k_2)$ or $(G3)$, and of rank 1 if it is of any other type given in the theorem.
To prove the statements in the table on the maximality of Lie triple systems, we presume that the list of Lie triple systems given in the theorem is complete; this fact will be proved in the remainder of the section. We then consider the various types individually:

(\text{Geo}, t) If $m'$ is of type (\text{Geo}, t), then $m'$ is contained in a Cartan subalgebra, i.e., in a Lie triple system of type $(G_2, 1, 1)$ and therefore cannot be maximal.

(G1, k) This type exists only for $m \geq 3$. If $m'$ is of type $(G_1, k)$ with $k \leq m - 2$, then $m'$ is contained in a space of type $(G_1, m - 1)$ and therefore cannot be maximal. On the other hand, the spaces of type $(G_1, m - 1)$ are of real codimension 2 in $m$. There exist no Lie triple systems of $m$ of real codimension 1 because of $m \geq 3$, and therefore the spaces of type $(G_1, m - 1)$ are then maximal.

(G2, k1, k2) If $m'$ is of type $(G_2, k_1, k_2)$ with $k_1 + k_2 < m$, then $m'$ is contained in a space of type $(G_2, k_1, m - k_1)$ and is therefore not maximal. Moreover, any space $m'$ of type $(G_2, 1, 1)$ is contained in a space of type $(G_3)$ and is therefore not maximal in the case $m = 2$. On the other hand, if $m'$ is of type $(G_2, k_1, k_2)$ with $k_1 + k_2 = m \geq 3$, then $m'$ is maximal: Assume to the contrary that there exists a Lie triple system $\widehat{m}'$ of $m$ with $m' \nsubseteq \widehat{m}' \subseteq m$. Then we have $\dim_{\mathbb{R}} \widehat{m}' > \dim_{\mathbb{R}} m = m$, and therefore $\widehat{m}'$ is of type $(G_1, k)$ for some $k$ (see the table in the theorem) and hence complex. Thus we have $\widehat{m}' \supset m' \oplus Jm' = m$, which is a contradiction.

(G3) For $m = 2$, the spaces of type (G3) have real codimension 1 in $m$ and are therefore maximal. On the other hand, for $m \geq 3$, the space $m'$ of type (G3) described in the theorem is contained in the space $\mathfrak{q}(x - Jy) \oplus \mathfrak{q}(x + Jy) = \mathfrak{q}x \oplus \mathfrak{q}y$ of type (G1, 2), and therefore cannot be maximal.

(P1, k) If $m'$ is of type $(P_1, k)$ with $k < m$, then $m'$ is contained in a space of type $(P_1, m)$ and therefore cannot be maximal. On the other hand, if $m'$ is of type $(P_1, m)$, then we have $m' = V(A)$ for some $A \in \mathfrak{a}$. An inspection of the table in the theorem shows that there exists no Lie triple system $\widehat{m}'$ of $m$ with $V(A) \nsubseteq \widehat{m}' \subseteq m$.

(P2) Let $m'$ be a Lie triple system of type (P2). In the case $m = 2$, $m'$ is maximal: Assume to the contrary that there exists a Lie triple system $\widehat{m}'$ of $m$ with $m' \nsubseteq \widehat{m}' \subseteq m$. Then $\widehat{m}'$ is of real dimension 3 and therefore of type (G3), so that there exists an orthonormal system $(x, y)$ in some $V(A)$, $A \in \mathfrak{a}$ with $\mathfrak{m}' = \mathfrak{q}(x - Jy) \oplus \mathfrak{r}(x + Jy)$. $m'$ is complex, and therefore we have $m' = m' \cap m \subseteq \widehat{m}' \cap \widehat{m}' = \mathfrak{q}(x - Jy)$, which is a contradiction because $\mathfrak{q}(x - Jy)$ is an isotropic subspace of $m$, whereas $m'$ is not. On the other hand, in the case $m \geq 3$, $m'$ is contained in a space of type (G1, 2) and therefore cannot be maximal.

(A) Let $m'$ be a Lie triple system of type (A), then we necessarily have $m \geq 3$. Using the notation in the definition of this type in the theorem, we see that $m'$ is contained in the Lie triple system $m'' := \mathfrak{q}x \oplus \mathfrak{q}y \oplus \mathfrak{q}z$ of type (G1, 3); therefore $m'$ cannot be maximal for $m \geq 4$. In the case $m = 3$, we again show the maximality of $m'$ by contradiction: Assume that $\widehat{m}'$ is a Lie triple system of $m$ with $m' \subseteq \widehat{m}' \subseteq m$. Because $m'$ contains vectors which are neither isotropic nor contained in some $V(A)$, $\widehat{m}'$ is of one of the types $(G_1, k)$, $(G_2, k_1, k_2)$ and (G3). If $\widehat{m}'$ is of type $(G_1, k)$, then $\widehat{m}'$ is a $\mathfrak{q}Q$-subspace of $m$ and therefore contains $m''$; because we have $\dim_{\mathbb{Q}} m'' = 3 = \dim_{\mathbb{Q}} m$, $\widehat{m}' = m'$ follows, a contradiction. If $\widehat{m}'$ is of type $(G_2, k_1, k_2)$, then $\widehat{m}'$ is totally real in $m$, and hence $m'$ is totally real, also a contradiction. Finally, if $\widehat{m}'$ is of type (G3), one obtains a contradiction to $m' \subset \widehat{m}'$.

(I1, k) Let $m'$ be a Lie triple system of type (I1, k). Proposition $84(c)$ shows that $m'$ is properly contained in a $\mathfrak{q}Q$-subspace $m''$ of $m$ of complex dimension $2k$. In the case $2k < m$ $m''$ is a Lie triple system of type $(G_1, 2k)$; because we have $\hat{U} \supset m'$ it follows that $m'$ is not maximal. In the case $2k = m = 2$, $m'$ is contained in a space of type (G3) and therefore not maximal either. In the case $2k = m \geq 4$, we once again prove the maximality of $m'$ by contradiction: Assume that $\widehat{m}'$ is a Lie triple system of $m$ with $m' \nsubseteq \widehat{m}' \subseteq m$. Then we have $\dim_{\mathbb{R}} \widehat{m}' > \dim_{\mathbb{R}} m' = 2k = m$, and therefore $\widehat{m}'$ is of type $(G_1, k')$ for some $k'$, and hence a $\mathfrak{q}Q$-subspace. Thus we have $m'' \subset \widehat{m}'$; because of $\dim_{\mathbb{Q}}(m'') = 2k = m$, we have $m'' = m$ and therefore $\widehat{m}' = m'$ follows, a contradiction.

(I2, k) If $m'$ is of type (I2, k), then $m'$ is contained in the space $m' \oplus Jm'$ of type (I1, k) (see Proposition $84(c)(iii)$) and therefore cannot be maximal.

It remains to prove that every Lie triple system in $m$ is of one of the types given in the theorem, and this is the objective of the remainder of the present section.
We make one preliminary observation:

**Lemma 4.3** Let $m'$ be a Lie triple system of $m$, and suppose that there exist $A \in \mathfrak{A}$ and $X,Y \in V(A) \setminus \{0\}$ with $JX,Y \in m'$ and $\langle X,Y \rangle \neq 0$. Then $m'$ is a complex linear subspace of $m$.

Proof. Let $R$ be the curvature tensor of $Q$ and let us fix $A \in \mathfrak{A}$. Then we have by Proposition 2.2(b) for any $Z \in m'$

$$R(JX,Y)Z = (Z,Y)\mathfrak{f} JX - (Z,JX)\mathfrak{f} Y + 2(X,Y)JZ + (Y,AZ)\mathfrak{f} AJX - (JX,AZ)\mathfrak{f} AY$$

$$= (Z,Y)\mathfrak{f} JX - (Z,JX)\mathfrak{f} Y + 2(X,Y)JZ + (Z,AJX)\mathfrak{f} JY - (JX,AJX)\mathfrak{f} AJY$$

Thus the root system $\Delta'$ with $W$ to $V$ also is a Cartan subalgebra of $m'$, because then $\Delta' \subset \mathbb{R}$ imposes restrictions on the subsets of $\Delta = \{ \lambda_1, \ldots, \lambda_4 \}$ is the system of positive roots of $\Delta$ described in Proposition 4.3(b). Further, we have by Equation 33

$$m' = a \oplus \bigoplus_{\alpha \in \Delta_+'} m_\alpha . \quad (32)$$

Moreover, the root system $\Delta'$ is invariant under the Weyl group $W(m',a')$ by Proposition 2.2(c), and this fact imposes restrictions on the subsets of $\Delta_+ = \{ \lambda_1, \ldots, \lambda_4 \}$ which can occur as $\Delta_+$. For example $\Delta_+ = \{ \lambda_1, \lambda_4 \}$ is impossible, because then $\Delta' = \Delta_+ \cup (-\Delta_+)$ would not be invariant under the reflection in the line orthogonal to $\lambda_1$.

By this consideration we see that $\Delta_+'$ must be one of the following eight sets:

$$\emptyset, \quad \{ \lambda_1 \}, \quad \{ \lambda_2 \}, \quad \{ \lambda_3 \}, \quad \{ \lambda_4 \}, \quad \{ \lambda_1, \lambda_2 \}, \quad \{ \lambda_3, \lambda_4 \}, \quad \{ \lambda_1, \lambda_2, \lambda_3, \lambda_4 \} .$$

We now inspect the eight possible cases of $\Delta_+'$ individually to show that the corresponding Lie triple systems $m'$ are all of one of the types $\mathfrak{G}_2, 1, k_2$ and $\mathfrak{G}_3$ as they are described in Theorem 4.1.

For this purpose, we note that by Proposition 3.7(a) there exist $A \in \mathfrak{A}$ and an orthonormal system $(X,Y)$ in $V(A)$ so that $a = \mathbb{R}X \oplus \mathbb{R}JY$ holds. Also, we put $m'_{\alpha} := \dim(m_\alpha)$ for $\alpha \in \Delta'$, and continually use the data on the root system $\Delta_+ = \{ \lambda_1, \ldots, \lambda_4 \}$ and the root spaces $m_\lambda$ given in Proposition 3.7(b).

The case $\Delta_+ = \emptyset$. By Equation 33 we have $m' = a = \mathbb{R}X \oplus \mathbb{R}JY$, and therefore, $m'$ is of type $\mathfrak{G}_2, 1, 1$ with $W_1 := \mathbb{R}X$, $W_2 := \mathbb{R}Y$.

The case $\Delta_+ = \{ \lambda_1 \}$. By Equation 33 we have $m' = a \oplus m_{\lambda_1}$; by 32 we have $m_{\lambda_1} \subset m_{\lambda_1} = J((\mathbb{R}X \oplus \mathbb{R}Y)^{1,1}V(A))$. It follows that $m'$ is of type $\mathfrak{G}_2, 1, 1 + n_{\lambda_1}$ with $W_1 := \mathbb{R}X$ and $W_2 := \mathbb{R}Y \oplus Jm_{\lambda_1}$.

The case $\Delta_+ = \{ \lambda_2 \}$. Analogously as in the case $\Delta_+ = \{ \lambda_1 \}$ we see that $m'$ is of type $\mathfrak{G}_2, 1, 1 + n_{\lambda_2}$, with $W_1 := \mathbb{R}X \oplus m_{\lambda_2}$ and $W_2 := \mathbb{R}Y$.

The case $\Delta_+ = \{ \lambda_3 \}$. By Equation 33 we have $m' = a \oplus m_{\lambda_3}$. We have $\emptyset \neq m_{\lambda_3} \subset m_{\lambda_3}$; because $m_{\lambda_3}$ is 1-dimensional, therefrom already $m_{\lambda_3} = m_{\lambda_3} = R(JY + X)$ follows. Thus we have

$$m' = a \oplus m_{\lambda_3} = \mathbb{R}X \oplus \mathbb{R}JY \oplus \mathbb{R}(JX + Y) = \mathbb{R}(X + JY) \oplus \mathbb{R}(X - JY) \oplus \mathbb{R}(JX + Y) \oplus \mathbb{R}(JX + Y) = \mathbb{R}(X + JY) \oplus \mathbb{R}(X - JY) ,$$

The case $\Delta_+ = \{ \lambda_4 \}$. By Equation 33 we have $m' = a \oplus m_{\lambda_4}$. We have $\emptyset \neq m_{\lambda_4} \subset m_{\lambda_4}$; because $m_{\lambda_4}$ is 1-dimensional, therefrom already $m_{\lambda_4} = m_{\lambda_4} = R(JX + Y)$ follows. Thus we have

$$m' = a \oplus m_{\lambda_4} = \mathbb{R}X \oplus \mathbb{R}JY \oplus \mathbb{R}(JX + Y) = \mathbb{R}(X + JY) \oplus \mathbb{R}(X - JY) \oplus \mathbb{R}(JX + Y) \oplus \mathbb{R}(JX + Y) = \mathbb{R}(X + JY) \oplus \mathbb{R}(X - JY) ,$$

The case $\Delta_+ = \{ \lambda_1, \lambda_2 \}$. By Equation 33 we have $m' = a \oplus m_{\lambda_1} \oplus m_{\lambda_2}$; by 32 we have $m_{\lambda_1} \subset m_{\lambda_1} \subset m_{\lambda_1} = J((\mathbb{R}X \oplus \mathbb{R}Y)^{1,1}V(A))$. It follows that $m'$ is of type $\mathfrak{G}_2, 1, 1 + n_{\lambda_1}$ with $W_1 := \mathbb{R}X \oplus \mathbb{R}Y \oplus Jm_{\lambda_1}$, $W_2 := \mathbb{R}Y \oplus Jm_{\lambda_1}$, and $W_3 := \mathbb{R}X \oplus \mathbb{R}Y$.
and therefore $m'$ is of type $(G3)$. 

The case $\Delta'_+ = \{\lambda_1\}$. Analogously as in the case $\Delta'_+ = \{\lambda_3\}$ we obtain $m' = \mathbb{R}(X - JY) \oplus \mathbb{C}(X + JY)$. By replacing $Y$ with $-Y$, we see that also in this case $m'$ is of type $(G3)$. 

The case $\Delta'_+ = \{\lambda_1, \lambda_2\}$. By Equation (33) we have

$$m' = a \oplus m'_3 \oplus m''_3 = W_1 \oplus J(W_2)$$

with $W_1 := \mathbb{R}X \oplus m'_3$ and $W_2 := \mathbb{R}Y \oplus J(m'_3)$. Together with Equation (32), the table in Proposition 3.7(b) shows that $J(m'_3), m''_3 \subset (\mathbb{R}X \oplus \mathbb{R}Y)^{-1}.V(A) \subset V(A)$ holds, and therefore we have $W_1, W_2 \subset V(A)$. 

We now show $W_1 \perp W_2$: Let $u \in W_2$ and $v \in W_1$ be given, and assume that $\langle u, v \rangle \neq 0$ holds. We have $Ju, v \in m'$ by Equation (34), and therefore Lemma 4.3 shows that $m'$ is a complex-linear subspace of $m$. Because we have $X + JY \in a \subset m'$, it follows that we also have $-Y + JX = J(X + JY) \in m'$. Hence we have $m_{\lambda_4} = \mathbb{R}(JX - Y) \subset m'$ (see Proposition 3.7(b)) and therefore $m'_4 = m_{\lambda_4} \cap m' = m_{\lambda_4} \ (\text{see Proposition 3.7(b)})$, whence $\lambda_4 \in \Delta'_+$ follows. But this is a contradiction to the hypothesis $\Delta'_+ = \{\lambda_1, \lambda_2\}$ defining the present case. 

Therefore $m'$ is of type $(G2,1 + n'_{\lambda_2},1 + n'_{\lambda_1})$ with the present choice of $W_1$ and $W_2$. 

The case $\Delta'_+ = \{\lambda_3, \lambda_4\}$. For $k \in \{3,4\}$ we have $\dim m_{\lambda_k} = 1$, and therefore the same argument as in the treatment of the case $\Delta'_+ = \{\lambda_3\}$ shows that $m'_{\lambda_k} = m_{\lambda_k}$ holds. Thus we have by Equation (33)

$$m' = a \oplus m'_{\lambda_3} \oplus m'_{\lambda_4} = (\mathbb{R}X \oplus \mathbb{R}JY) \oplus \mathbb{R}(JX + Y) \oplus \mathbb{R}(JX - Y)$$

$$= \mathbb{R}X \oplus \mathbb{R}JY \oplus JX \oplus \mathbb{R}Y = \mathbb{C}X \oplus \mathbb{C}Y .$$

Thus we have $m' = W \oplus JW$ with $W := \mathbb{R}X \oplus \mathbb{R}Y \subset V(A)$. Therefore $m'$ is a 2-dimensional $\mathbb{C}Q$-subspace and hence of type $(G1,2)$.

The case $\Delta'_+ = \{\lambda_1, \lambda_2, \lambda_3, \lambda_4\}$. By Equation (33) we have

$$m' = a \oplus m'_{\lambda_1} \oplus m'_{\lambda_2} \oplus m'_{\lambda_3} \oplus m'_{\lambda_4} ,$$

and by an analogous argument as for the case $\Delta'_+ = \{\lambda_3, \lambda_4\}$, we see that

$$m' \ni a \oplus m'_{\lambda_3} \oplus m'_{\lambda_4} = \mathbb{C}X \oplus \mathbb{C}Y$$

(36)

holds. In particular we have $X, JX \in m'$, whence it follows by Lemma 4.3 that $m'$ is a complex linear subspace of $m$. Therefrom $m'_{\lambda_1} = J(m'_{\lambda_2})$ follows, and thus we obtain from Equations (35) and (36):

$$m' = \mathbb{C}X \oplus \mathbb{C}Y \oplus J(m'_{\lambda_2}) \oplus m'_{\lambda_3} = W \oplus JW$$

with $W := \mathbb{R}X \oplus \mathbb{R}Y \oplus m'_{\lambda_2} \subset V(A)$. Therefore $m'$ is a $(2 + n'_{\lambda_2})$-dimensional $\mathbb{C}Q$-subspace and hence of type $(G1,2 + n'_{\lambda_2})$.

This completes the classification of the rank 2 Lie triple systems in $m$.

4.2 The case of rank 1

We first give a way to describe the position of vectors $v \in m$ in the Cartan subalgebra in which they lie. For this, let $v \in m \setminus \{0\}$ be given. Then there exists a Cartan subalgebra $a \subset m$ with $v \in a$ (see [L2], Theorem VI.1.2(b), p. 56), and by Proposition 3.7(a) there exist $A \in a$ and $X, Y \in S(V(A))$ with $a = \mathbb{R}X \oplus \mathbb{R}JY$. Because the Weyl group of $m$ acts transitively on the set of Weyl chambers in $a$ ([L2], Theorem VI.2.2, p. 67), there exists $g \in K$ so that $\text{Ad}(g)v$ lies in the closed Weyl chamber of $a$ bounded by the root vectors $\lambda_2^\perp$ and $\lambda_3^\perp$ as defined in Proposition 3.7(b):

- $\lambda_2^\perp$
- $\lambda_3^\perp$
- $\lambda_1^\perp$
In this situation, we call the angle \( \varphi \in [0, \frac{\pi}{4}] \) between the vectors \( \lambda_2^\prime = \sqrt{2} X \) and \( \text{Ad}(g)v \) the characteristic angle of \( v \) and denote it by \( \varphi(v) \). Because the action of the Weyl group on the set of Weyl chambers is simply transitive, this angle does not depend on the choice of \( g \) (with the aforementioned property).

**Proposition 4.4** Suppose \( v \in m \setminus \{0\} \).

(a) The angle \( \varphi(v) \in [0, \frac{\pi}{4}] \) is characterized by

\[
\langle v, \text{Ad}(g)v \rangle_\mathfrak{q} = \cos(2\varphi(v)) \cdot \|v\|^2 ,
\]

where the number \( \|\langle v, \text{Ad}(g)v \rangle_\mathfrak{q} \| \) does not depend on the choice of \( A \in \mathfrak{A} \). Therefore \( \varphi(v) \) is uniquely determined even in those cases where \( v \) is contained in more than one Cartan subalgebra.

(b) We have \( \varphi(cv) = \varphi(v) \) for any \( c \in \mathbb{R} \setminus \{0\} \).

(c) \( \varphi \) is invariant under \( \mathfrak{Q} \)-automorphisms of \( m \), in particular \( \varphi \) is \( \text{Ad}(K) \)-invariant.

(d) Let \( a \) be a Cartan subalgebra of \( m \) with \( v \in a \) and \( v' \in a \setminus \{0\} \) with \( \langle v, v' \rangle = 0 \). Then we have \( \varphi(v) = \varphi(v') \).

**Proof.** We first note that the map \( f : m \rightarrow \mathbb{R}, \ v \mapsto \|\langle v, \text{Ad}(g)v \rangle_\mathfrak{q} \| \) does not depend on the choice of \( A \in \mathfrak{A} \) and is invariant under \( \mathfrak{Q} \)-automorphisms, in particular (see Equation (29) and Proposition 4.5(b)) it is \( \text{Ad}(K) \)-invariant.

Now let \( v \in m \setminus \{0\} \) be given; without loss of generality we may suppose \( \|v\| = 1 \). Let \( a = \mathbb{R}X \oplus \mathbb{R}JY \ (X, Y \in \mathcal{S}(V(A)), \ A \in \mathfrak{A}) \) be a Cartan subalgebra of \( m \) with \( v \in a \), and let \( g \in K \) be such that \( \text{Ad}(g)v \) lies in the closed Weyl chamber of \( a \) bounded by \( \lambda_2^\prime \) and \( \lambda_2^\prime \). Then we have

\[
\text{Ad}(g)v = \cos(\varphi(v))X + \sin(\varphi(v))JY
\]

and therefore

\[
f(v) = f(\text{Ad}(g)v) = \left| \langle \cos(\varphi(v))X + \sin(\varphi(v))JY, \cos(\varphi(v))X + \sin(\varphi(v))JY \rangle_\mathfrak{q} \right|
\]

\[
= \|\cos(\varphi(v)) - \sin^2(\varphi(v))\| = \|\cos(2\varphi(v))\|
\]

for the equals sign marked (\( a \)) it should be noted that \( \langle X, X \rangle_\mathfrak{q} = \langle Y, Y \rangle_\mathfrak{q} = 1 \) and \( \langle X, Y \rangle_\mathfrak{q} = 0 \) holds. This proves (a). (b) is obvious and (c) follows from (a) via the fact that \( f \) is invariant under \( \mathfrak{Q} \)-automorphisms.

In the situation of (d), we consider the Weyl transformation \( B : a \rightarrow a \) obtained by first reflecting in the line perpendicular to \( \lambda_2^\prime \) and then reflecting in the line perpendicular to \( \lambda_2^\prime \). Then \( B \) is a rotation in the plane \( a \) by the angle \( \frac{\pi}{2} \), and therefore there exists \( c \in \mathbb{R} \setminus \{0\} \) so that \( v' = c \cdot Bv \) holds. We now have

\[
\varphi(v') = \varphi(c \cdot Bv) \overset{(b)}{=} \varphi(Bv) \overset{(c)}{=} \varphi(v)
\]

for the equals sign marked (\( a \)), see Proposition 2.2(b) and part (c) of the present proposition.

\( \square \)

**Remark 4.5** Via a somewhat different approach, such a characteristic angle has already been introduced in [7]. In Section 6 of [7] it is shown that the orbits of the isotropy action of \( \text{SO}(2) \times SO(m) \) on the unit sphere \( \mathcal{S}(T_pQ) \) (see Proposition 5.3(a),(b)) are exactly the sets \( M_t := \{v \in \mathcal{S}(T_pQ) | \varphi(v) = t \} \) with \( t \in [0, \frac{\pi}{4}] \). The orbits of the isotropy actions of rank-2-symmetric spaces on the unit sphere have been studied extensively by Takagi and Takahashi in [11]. There it is shown that \( (M_t)_{0 \leq t \leq \pi/4} \) is a family of isoparametric hypersurfaces in \( \mathcal{S}(T_pQ) \). It has \( g = 4 \) principal curvatures for \( m \geq 3 \); for \( m = 2 \) the number of principal curvatures is reduced to \( g = 2 \). The focal sets of \( (M_t)_{0 \leq t \leq \pi/4} \) are \( M_0 \) and \( M_{\pi/4} \).

**Proposition 4.6** Let \( m' \) be a Lie triple system in \( m \) of rank 1. Then all elements of \( m' \setminus \{0\} \) have one and the same characteristic angle \( \varphi_0 \in [0, \frac{\pi}{4}] \). If \( \dim(m') \geq 2 \) holds, then we have \( \varphi_0 \in \{0, \arctan(\frac{1}{3}), \frac{\pi}{4}\} \), and in the case \( \varphi_0 = \arctan(\frac{1}{3}) \), \( m' \) does not have any elementary roots (see Definition 2.3).

**Proof.** We consider the Lie subalgebra \( \mathfrak{r} := [m', m'] \) of \( \mathfrak{r} \) and the connected Lie subgroup \( K' \) of \( K \) with Lie algebra \( \mathfrak{r} \). We let \( Z_1, Z_2 \in m' \setminus \{0\} \) be given. Then \( RZ_1 \) and \( RZ_2 \) are Cartan subalgebras of \( m' \), and therefore there exists \( g \in K' \) with \( \text{Ad}(g)RZ_1 = RZ_2 \). By Theorem V.1.2(c) (note that \( m' \) has to be of compact type in this situation). Hence there exists \( c \in \mathbb{R} \setminus \{0\} \) with \( \text{Ad}(g)Z_1 = cZ_2 \), and therefore we have by Proposition 4.4(c),(b)

\[
\varphi(Z_1) = \varphi(\text{Ad}(g)Z_1) = \varphi(cZ_2) = \varphi(Z_2)
\]

This proves the first statement of the proposition.

We now suppose that \( \dim(m') \geq 2 \) holds and let any \( Z \in m' \setminus \{0\} \) be given. \( \mathfrak{r}' := \mathbb{R}Z \) is a Cartan subalgebra of \( m' \); \( \mathfrak{r}' \) is contained in a Cartan subalgebra \( a \) of \( m \) by [62]. Theorem V.1.2(b). We now consider the root systems \( \Delta' := \Delta(m', \mathfrak{r}') \) and \( \Delta := \Delta(m, a) \) of \( m' \) resp. \( m \) with respect to \( \mathfrak{r}' \) resp. \( a \). Because of \( \dim(m') > \text{rk}(m') \), we have \( \Delta' \neq \emptyset \). We consider any root \( \alpha \in \Delta' \). By Equation (10) in Proposition 2.4(a), \( \alpha \) has to be either elementary or composite in the sense of Definition 2.3.
If $\alpha$ is elementary and $\lambda \in \Delta$ is the unique root with $\lambda | a' = \alpha$, then $Z$ is co-linear to $\lambda^2$ by Proposition 4.4(a), and therefore we have $\varphi_0 = \varphi(Z) = \varphi(\lambda^2)$. Via Proposition 4.4(a) and the explicit representations of the root vectors $\lambda_i^\pm$ in Proposition 5.7(b) one easily calculates $\varphi(\lambda_i^+) = \varphi(\lambda_i^-) = 0$ and $\varphi(\lambda_i^\pm) = \varphi(\lambda_i^\pm) = \frac{\pi}{4}$. Because we have $\lambda \in \Delta = \{ \pm \lambda_1^1, \ldots, \pm \lambda_k^1 \}$, we thus see that $\varphi_0 \in \{ 0, \frac{\pi}{4} \}$ holds in the present case.

Now let us suppose that $\alpha$ is composite, and let $\lambda, \mu \in \Delta$ be two roots with $\lambda | a' = \alpha = \mu | a'$ and $\mu \neq \lambda$; we also have $\mu \neq -\lambda$ (because otherwise we would have $\alpha = 0 \notin \Delta$). By Proposition 2.2(b) we have
\[
\langle Z, \mu - \lambda \rangle = 0,
\]
whence
\[
\varphi_0 = \varphi(Z) = \varphi(\mu - \lambda^2)
\]
follows by Proposition 5.7(d).

We now denote by $W$ the Weyl group of $\Delta$, see Definition 2.9. Then we have for any $B \in W$
\[
B(\lambda^2) \neq \pm B(\mu^2)
\]
and by Equation 5.9 and Proposition 5.7(c)
\[
\varphi(Z) = \varphi(B(\mu^2) - B(\lambda^2)).
\]

$W$ acts transitively on the complementary subsets $\{ \pm \lambda_1^2, \pm \lambda_2^2 \}$ and $\{ \pm \lambda_2^3, \pm \lambda_1^3 \}$ of $\Delta$. Therefore there exists $B_1 \in W$ so that
\[
B_1(\lambda^2) \in \{ \lambda_1^2, \lambda_2^2 \}
\]
holds.

Let us first consider the case $B_1(\lambda^2) = \lambda_1^2$. Then we have $B_1(\mu^2) \in \{ \pm \lambda_2^2, \pm \lambda_1^3 \}$ by 5.8. In the case $B_1(\mu^2) \in \{ -\lambda_2^2, -\lambda_1^3 \}$ we let $B_2 \in W$ be the reflection in $(\lambda_2^2, -\lambda_1^3)$ and have
\[
B_2(\lambda_1^2) = \lambda_2^2, \quad B_2(\lambda_1^3) = \lambda_1^3, \quad B_2(-\lambda_1^3) = \lambda_2^2, \quad B_2(-\lambda_1^2) = \lambda_1^3;
\]
onc otherwise we put $B_2 := id_a \in W$. Thus with $B := B_2 \circ B_1 \in W$ we have
\[
B(\lambda^2) = \lambda_1^2 \quad \text{and} \quad B(\mu^2) \in \{ \lambda_1^2, \lambda_2^2, \lambda_1^3 \}.
\]

A calculation using Proposition 4.6(a) and the explicit presentation of $\lambda_i^\pm$ in Proposition 5.7(b) shows
\[
\varphi(\lambda_2^2 - \lambda_1^3) = \frac{\pi}{4}, \quad \varphi(\lambda_2^3 - \lambda_1^2) = \arctan(\frac{1}{2}) \quad \text{and} \quad \varphi(\lambda_2^3 - \lambda_1^2) = 0.
\]

In conjunction with Equations 5.9 and 10 these equations show that (under the case hypotheses that $\alpha$ is composite and $B_1(\lambda^2) = \lambda_1^2$) we have $\varphi(Z) \in \{ 0, \arctan(\frac{1}{2}) \}$.

We now turn to the case $B_1(\lambda^2) = \lambda_2^2$. By an analogous argument as in the case $B_1(\lambda^2) = \lambda_1^2$ we see that there exists $B \in W$ so that
\[
B(\lambda^2) = \lambda_2^2 \quad \text{and} \quad B(\mu^2) \in \{ \lambda_1^2, \lambda_2^2, \lambda_1^3 \}
\]
holds, and a further calculation shows
\[
\varphi(\lambda_1^2 - \lambda_2^3) = \arctan(\frac{1}{2}), \quad \varphi(\lambda_2^3 - \lambda_1^2) = 0 \quad \text{and} \quad \varphi(\lambda_2^3 - \lambda_1^2) = 0.
\]

These facts together with Equations 5.9 and 11 show that in the present case we have $\varphi(Z) \in \{ 0, \arctan(\frac{1}{2}) \}$.

This shows that in any case with $\dim(m') \geq 2$, $\varphi_0 \in \{ 0, \arctan(\frac{1}{2}), \frac{\pi}{4} \}$ holds. Moreover, we saw that if $m'$ has an elementary root, then in fact $\varphi_0 \in \{ 0, \frac{\pi}{4} \}$ holds.}

We now classify the Lie triple systems $m' \in m$ of rank 1. If $\dim(m') = 1$ holds, then $m'$ is of type $(\text{Geo})$. Thus we may now suppose $\dim(m') \geq 2$. We fix $Z \in S(m')$, then $a' := \mathbb{R}Z$ is a Cartan subalgebra of $m'$. As in the proof of Proposition 4.6, we choose a Cartan subalgebra $\mathfrak{a}$ of $m$ so that $a' = \mathfrak{a} \cap m'$ holds. By Proposition 3.7(a) there exist $A \in \mathfrak{A}$ and an orthonormal system $(X, Y)$ in $V(A)$ so that $\mathfrak{a} = \mathbb{R}X \oplus \mathbb{R}Y$ holds, and by changing the sign of $A$, $X$ and $Y$ as necessary, we can ensure that $Z$ lies in the closed Weyl chamber of $\mathfrak{a}$ bounded by $X$ and $X + JY$. Then we have
\[
Z = \cos(\varphi_0)X + \sin(\varphi_0)JY
\]
with the constant $\varphi_0 \in \{ 0, \arctan(\frac{1}{2}), \frac{\pi}{4} \}$ from Proposition 4.6. Moreover, we consider the root systems $\Delta' := \Delta(m', a')$ and $\Delta := \Delta(m, a)$ of $m'$ resp. $m$ with respect to $a'$ resp. $a$ and fix a system of positive roots $\Delta'_+ \subset \Delta'$. Then we have by Proposition 2.2(a)
\[
\Delta' \subset \{ \lambda | a' | \lambda \in \Delta, \lambda(Z) \neq 0 \}
\]
and
\[
m' = \mathbb{R}Z \oplus \bigoplus_{\alpha \in \Delta'_+} m'_\alpha
\]
with
\[
\forall \alpha \in \Delta'_+ : m'_\alpha = \left( \bigoplus_{\lambda \neq \alpha(Z)} \mathbb{R} \cdot m_\lambda \right) \cap m';
\]

moreover we have because of \( \text{dim}(m') > \text{rk}(m') \)

\[
\Delta' \neq \emptyset,
\]

and Proposition 3.6 shows that on \( m' \setminus \{0\} \), the characteristic angle function \( \varphi \) is equal to some constant \( \varphi_0 \in \{0, \arctan(\frac{1}{2}), \frac{\pi}{2}\} \). To complete the classification, we now treat the three possible values for \( \varphi_0 \) individually.

**The case \( \varphi_0 = 0 \).** Then we have \( Z = X \) by Equation (42). By Proposition 3.7(b) we have

\[
\lambda_1(X) = 0 \quad \text{and} \quad \lambda_2(X) = \lambda_3(X) = \lambda_4(X) = \sqrt{2};
\]

therefrom we conclude by (43) and (46)

\[
\Delta' = \{ \pm \alpha \} \quad \text{with} \quad \alpha(tZ) = \sqrt{2} \cdot t \quad \text{for} \quad t \in \mathbb{R}
\]

and by (44) and (45)

\[
m' = \mathbb{R}X \oplus m'_\alpha \quad \text{with} \quad \{0\} \neq m'_\alpha \subset m_{\lambda_2} \oplus m_{\lambda_3} \oplus m_{\lambda_4}.
\]

Immediately, we will show that

\[
\text{either} \quad m'_\alpha \subset (\mathbb{R}X)^{\perp,V(A)} \quad \text{or} \quad m'_\alpha = \mathbb{R} \cdot JX
\]

holds. Then we conclude: In the case \( m'_\alpha \subset (\mathbb{R}X)^{\perp,V(A)} \) we have \( m' = a' \oplus m'_\alpha \subset V(A) \), therefore \( m' \) is of type \( (P1, 1 + \dim(m'_\alpha)) \). On the other hand, in the case \( m'_\alpha = \mathbb{R} \cdot JX \) we have \( m' = a' \oplus m'_\alpha = \mathbb{R}X \), therefore \( m' \) is of type \( (P2) \).

We now prove (48): Let \( H \in m'_\alpha \) be given. Then we have by (47) and Proposition 3.7(b)

\[
H \in m_{\lambda_2} \oplus m_{\lambda_3} \oplus m_{\lambda_4} = \mathbb{R} \cdot JX \oplus (\mathbb{R}X)^{\perp,V(A)}
\]

and therefore there exist \( t \in \mathbb{R} \) and \( X' \in V(A) \) with \( X' \perp X \) so that \( H = t \cdot JX + X' \) holds. Via Proposition 3.1(b) we calculate

\[
\tilde{H} := \frac{1}{2} R(X, H)H = (\|X'||^2 + t^2) \cdot X - 2t \cdot JX'.
\]

Because \( m' \) is curvature-invariant, we have \( \tilde{H} \in m' \). As \( m' \) is orthogonal to \( \mathbb{R}JY \oplus m_{\lambda_1} = (\mathbb{R}X)^{\perp,V(A)} \) by Equation (17) and hence in particular to \( JX' \), we therefore have

\[
0 = \langle \tilde{H}, JX' \rangle = (-2t) \cdot \langle JX', JX' \rangle = (-2t) \cdot \|X'||^2.
\]

Therefore we have either \( t = 0 \), implying \( H = X' \in (\mathbb{R}X)^{\perp,V(A)} \); or else \( \|X'|| = 0 \), implying \( H = t \cdot JX \in \mathbb{R}JX \). Thus, we have shown

\[
m'_\alpha \subset (\mathbb{R}X)^{\perp,V(A)} \cup \mathbb{R} \cdot JX.
\]

Because \( m'_\alpha \) is a linear space, we in fact have

\[
\text{either} \quad m'_\alpha \subset (\mathbb{R}X)^{\perp,V(A)} \quad \text{or} \quad m'_\alpha \subset \mathbb{R} \cdot JX;
\]

if the second case holds, then we actually have \( m'_\alpha = \mathbb{R} \cdot JX \) because of \( m'_\alpha \neq \{0\} \). Thus (48) is shown.

**The case \( \varphi_0 = \arctan(\frac{1}{2}) \).** By Equation (52) we then have

\[
Z = \frac{2}{\sqrt{3}}X + \frac{1}{\sqrt{3}}JY,
\]

and from Proposition 3.7(b) we thus obtain

\[
\lambda_1(Z) = \frac{\sqrt{2}}{\sqrt{3}}, \quad \lambda_2(Z) = 2 \frac{\sqrt{2}}{\sqrt{3}}, \quad \lambda_3(Z) = \frac{\sqrt{2}}{\sqrt{3}} \quad \text{and} \quad \lambda_4(Z) = 3 \frac{\sqrt{2}}{\sqrt{3}}.
\]
Because of \( \varphi_0 = \arctan(\frac{1}{2}) \), Proposition 4.4 shows that there do not exist any elementary roots in \( \Delta' \); therefore we conclude from Equations (51) by (43) and (46)

\[
\Delta' = \{ \pm \alpha \} \quad \text{with} \quad \alpha(tZ) = \frac{\sqrt{2}}{\sqrt{3}} \cdot t \quad \text{for} \quad t \in \mathbb{R}
\]

and by (43) and (46)

\[
m' = \mathbb{R}Z \oplus m'_\alpha \quad \text{with} \quad \{0\} \neq m'_\alpha \subseteq m_{\lambda_1} \oplus m_{\lambda_2} .
\]  

We now show

\[
\forall H \in \mathbb{S}(m'_{\alpha}) \exists U \in \mathbb{S}(V(A)) : (H = \pm \frac{1}{\sqrt{3}}(Y + JX + \sqrt{3}JU) \quad \text{and} \quad U \perp X, Y ) .
\]  

Let \( H \in \mathbb{S}(m'_{\alpha}) \) be given. We have \( \varphi(H) = \varphi_0 = \arctan(\frac{1}{2}) \) and therefore by Proposition 4.4(a)

\[
|\langle H, A(H) \rangle| = \cos(2 \arctan(\frac{1}{2})) = \frac{3}{5} .
\]  

By (42) and Proposition 3.7(b) we have

\[
H \in m_{\lambda_1} \oplus m_{\lambda_2} = J(\mathbb{R}X \oplus \mathbb{R}Y)^{\perp V(A)} \oplus \mathbb{R}(JX + Y) .
\]  

Consequently there exist \( U' \in V(A) \) with \( U' \perp X, Y \) and \( t \in \mathbb{R} \) so that

\[
H = JU' + t \cdot (JX + Y) = tY + J(U' + tX)
\]  

and therefore also

\[
A(H) = tY - J(U' + tX)
\]  

holds. Via Equations (53) and (50) we obtain

\[
|\langle H, A(H) \rangle| = ||U'||^2 ,
\]  

and by plugging the latter equation into (41), we derive

\[
||U'||^2 = \frac{3}{5} .
\]  

We now obtain from Equation (55) and the preceding equation

\[
1 = ||H||^2 = 2t^2 + ||U'||^2 = 2t^2 + \frac{3}{5}
\]  

Thus we have shown that

\[
t = \varepsilon \frac{1}{\sqrt{5}} \quad \text{and} \quad ||U'|| = \sqrt{\frac{3}{5}}
\]  

holds with suitable \( \varepsilon \in \{ \pm 1 \} \). Consequently, we have \( U := \varepsilon \sqrt{\frac{3}{5}} \cdot U' \in \mathbb{S}(V(A)) \). Equation (56) shows that we have \( H = \varepsilon \frac{1}{\sqrt{5}}(Y + JX + \sqrt{3}JU) \), and therefore (56) is satisfied with this choice of \( U \).

Next we prove \( \dim m'_{\alpha} = 1 \): Let \( H_1, H_2 \in \mathbb{S}(m'_{\alpha}) \) be given; we will show \( H_2 = \pm H_1 \). By (53) there exist \( \varepsilon_1, \varepsilon_2 \in \{ \pm 1 \} \) and \( U_1, U_2 \in \mathbb{S}(V(A)) \) so that

\[
H_k = \varepsilon_k \frac{1}{\sqrt{5}} \cdot (Y + JX + \sqrt{3}JU_k)
\]  

holds for \( k \in \{ 1, 2 \} \). Under the assumption \( H_2 \neq \pm H_1 \) we could suppose without loss of generality that \( \varepsilon_1 = \varepsilon_2 = 1 \) holds, and then \( H_1 - H_2 = \sqrt{3/5} \cdot (U_1 - U_2) \in m'_{\alpha} \subset m' \) would be a non-zero vector; it is contained in \( JV(A) \) and therefore has the property \( \varphi(H_1 - H_2) = 0 \), in contradiction to \( \forall H \in m' \setminus \{0\} : \varphi(H) = \arctan(\frac{1}{2}) \).

Thus \( m'_{\alpha} \) is 1-dimensional, and therefore we have \( m' = a' \oplus m'_{\alpha} = \mathbb{R}Z \oplus \mathbb{R}H \) with any \( H \in S(m'_{\alpha}) \). Equations (50) and (53) now show that \( m' \) is a space of type \( \{ A \} \).

**The case \( \varphi_0 = \frac{\pi}{2} \).** In this case we have for every \( Z \in m' \setminus \{0\} : \cos(2 \varphi(Z)) = \cos(\frac{\pi}{2}) = 0 \) and therefore by Proposition 1.1(a) \( \langle Z, A(Z) \rangle = 0 \). This shows that \( m' \) is isotropic (see Definition 3.2(e)). Therefore the “complex closure” \( \tilde{m}' := m' + Jm' \subset m \) of \( m' \) is also isotropic by Proposition 3.4(c)(iii), and therefore a
curvature-invariant subspace of \( \mathfrak{m} \) of type \((I_1, k)\) with \( k := \dim_{\mathbb{C}} \hat{\mathfrak{m}}' \). Hence the quadratic form corresponding to the \( \mathbb{C} \)-bilinear form \( \beta : \hat{\mathfrak{m}}' \times \hat{\mathfrak{m}}' \rightarrow \mathbb{C} ; \ (Z_1, Z_2) \mapsto \langle Z_1, A(Z_2) \rangle_{\mathbb{C}} \) vanishes, and therefore we have \( \beta = 0 \). From this fact and Proposition 3.1(b) we see that for \( Z_1, Z_2, Z_3 \in \hat{\mathfrak{m}}' \), the curvature tensor \( R \) of \( Q \) is given by

\[
R(Z_1, Z_2)Z_3 = \langle Z_3, Z_2 \rangle_{\mathbb{C}} Z_1 - \langle Z_3, Z_1 \rangle_{\mathbb{C}} Z_2 - 2 \cdot \langle JZ_1, Z_2 \rangle JZ_3
+ \langle JZ_2, Z_3 \rangle JZ_1 - \langle JZ_1, Z_3 \rangle JZ_2 - 2 \cdot \langle JZ_1, Z_2 \rangle JZ_3 .
\]

Therefore the restriction of the curvature tensor of \( Q \) to \( \hat{\mathfrak{m}}' \) is the curvature tensor of a complex projective space of constant holomorphic sectional curvature 4.

If \( \mathfrak{m}' \) is a complex subspace of \( \mathfrak{m} \), we have \( \mathfrak{m}' = \hat{\mathfrak{m}}' \); therefore \( \mathfrak{m}' \) then is of type \((I_1, k)\). Otherwise, \( \mathfrak{m}' \) is a Lie triple system of \( \hat{\mathfrak{m}}' \); by the well-known classification of totally geodesic submanifolds in a complex projective space, it follows that \( \mathfrak{m}' \) is a totally real subspace of \( \hat{\mathfrak{m}}' \), and therefore a \( k \)-dimensional totally real, isotropic subspace of \( \mathfrak{m} \). Consequently, \( \mathfrak{m}' \) is then of type \((I_2, k)\).

This completes the proof of Theorem 4.1.

\[Q.E.D.\]

5 Totally geodesic embeddings into the complex quadric

We now wish to find out which (connected, complete) totally geodesic submanifolds \( M \) of \( Q \) correspond to the Lie triple systems \( \mathfrak{m}' \) classified in Theorem 4.1. The isometry type of the universal covering manifold \( \hat{M} \) of \( M \) (and therefore the local isometry type of \( M \)) is easily determined via the theorem of Cartan/Ambrose/Hicks by computing the restriction of the curvature tensor \( R \) of \( Q \) to \( \mathfrak{m}' \).

However, we want to know more: namely the exact global structure of \( M \) and the position of \( M \) in \( Q \). For this we need to construct totally geodesic isometric embeddings of suitable Riemannian manifolds into \( M \) explicitly, at least for one example per type of Lie triple system. We will do this below for all types of curvature invariant subspaces \( U \) except for the type \((A)\). In this way we will prove the following table:

| type of \( \mathfrak{m}' \) | with ... | isometry class of \( M \) | \( M \) complex or totally real? |
|--------------------------|-----------|-------------------------|-----------------------------|
| \((\text{Geo})\)         | \( \mathbb{R} \) or \( S^1_{1/2} \) | \( \text{totally real} \) |
| \((G_1, k)\)            | \( 2 \leq k \leq m - 1 \) | \( S^k_{1/\sqrt{2}} \times S^k_{1/\sqrt{2}} / \{ \pm \text{id} \} \) | complex |
| \((G_2, k_1, k_2)\)     | \( k_1, k_2 \geq 1 \), \( k_1 + k_2 \leq m \) | \( \mathbb{C} \mathbb{P}^1 \times \mathbb{R} \mathbb{P}^1 \) | totally real |
| \((G_3)\)               | \( 1 \leq k \leq m \) | \( S^k_{1/\sqrt{2}} \) | \( \text{not complex} \) |
| \((P_1, k)\)            | \( 1 \leq k \leq m \) | \( Q^1 \) | \( \text{totally real} \) |
| \((P_2)\)               | \( 1 \leq k \leq m \) | \( \mathbb{R}^k \) | \( \text{not complex} \) |
| \((A)\)                 | \( 1 \leq k \leq m \) | \( S^2 \) | \( \text{totally real} \) |
| \((I_1, k)\)            | \( 1 \leq k \leq m \) | \( \mathbb{C} \mathbb{P}^k \) | \( \text{complex} \) |
| \((I_2, k)\)            | \( 1 \leq k \leq m \) | \( \mathbb{R} \mathbb{P}^k \) | \( \text{totally real} \) |

Here \( S^k_r \subset \mathbb{R}^{k+1} \) denotes the \( k \)-sphere of radius \( r \). \( \mathbb{C} \mathbb{P}^k \) is equipped with the Fubini-Study metric of constant holomorphic sectional curvature 4 as usual, and \( \mathbb{R} \mathbb{P}^k \) is equipped with a Riemannian metric of constant sectional curvature 1.

Although it would be possible to describe the totally geodesic embeddings for the various types of Lie triple systems in the general case via the standard \( \mathbb{C} \)-structure of \( \mathbb{C}^{m+2} \) (see Example 3.3(b)), for simplicity’s sake we here give only one example per type of Lie triple system. That the embeddings given below indeed map onto totally geodesic submanifolds of \( Q \) is most easily seen via the fact that the connected components of the common fixed point set of a set of isometries is a totally geodesic submanifold (see for example [K], Theorem II.5.1, p. 59). To verify that the images correspond to the stated types of Lie triple systems, one has to use the description of these types in Theorem 4.1 and the explicit description of the shape operators \( A_q \) (which constitute the \( \mathbb{C} \)-structure \( \mathfrak{A} = \mathfrak{A}(Q^m, p) \) on \( T_p Q^m \) given in Proposition 3.1(a)).

**Types \((G_1, k)\) and \((P_2)\).** Let \( 1 \leq k < m \). Then

\[
Q^k \rightarrow Q^m, \ [z_0, \ldots, z_{k+1}] \mapsto [z_0, \ldots, z_{k+1}, 0, \ldots, 0]
\]

is a totally geodesic isometric embedding. Its image corresponds to a Lie triple system of type \((G_1, k)\) (for \( k \geq 2 \)) resp. \((P_2)\) (for \( k = 1 \)).
Types (G2, k1, k2), (P1, k) and (Geo). Let 0 ≤ k1, k2 with 1 ≤ k1 + k2 ≤ m. Then the map
\[ \tilde{f}_{k_1, k_2} : S_{1/\sqrt{2}}^{k_1/2} \times S_{1/\sqrt{2}}^{k_2/2} \to Q^m, \]
\[ ((x_0, \ldots, x_{k_1}), (y_0, \ldots, y_{k_2})) \mapsto [x_0, \ldots, x_{k_1}, i \cdot y_0, \ldots, i \cdot y_{k_2}, 0, \ldots, 0] \]
is a totally geodesic isometric immersion and a two-fold covering map onto its image with \( \tilde{f}^{-1}(f(x, y)) = \{ \pm(x, y) \} \). It therefore gives rise to a totally geodesic isometric embedding
\[ f_{k_1, k_2} : (S_{1/\sqrt{2}}^{k_1/2} \times S_{1/\sqrt{2}}^{k_2/2})/\{ \pm \text{id} \} \to Q^m. \]
The image of \( f \) corresponds to a Lie triple system of type (G2, k1, k2) (for \( k_1, k_2 \neq 0 \)) resp. of type (P1, k) (for \( k_2 = 0 \)).

The type (G2, 1, 1) warrants special attention: The Lie triple systems of this type are the Cartan subalgebras of \( \mathfrak{m} \), and therefore the corresponding totally geodesic submanifolds are the maximal flat tori of \( Q \). They can be described in the following way:

We abbreviate \( r := \frac{1}{\sqrt{2}} \) and consider the normal geodesics
\[ \tilde{\gamma}_1 : \mathbb{R} \to S_r(\mathbb{R}^{m+2}), t \mapsto r(\cos(\frac{t}{\sqrt{2}}), 0, r \sin(\frac{t}{\sqrt{2}}), 0, 0, \ldots, 0) \]
and \( \tilde{\gamma}_2 : \mathbb{R} \to S_r(\mathbb{R}^{m+2}), t \mapsto r(0, \cos(\frac{t}{\sqrt{2}}), 0, r \sin(\frac{t}{\sqrt{2}}), 0, 0, \ldots, 0) \)
and the map
\[ g : \mathbb{C} \to Q, t + is \mapsto \pi(\tilde{\gamma}_1(t) + J\tilde{\gamma}_2(s)) \]
g is an isometric covering map onto the maximal flat torus \( T \) of \( Q \) with \( z := [1, i, 0, \ldots, 0] \in T \) and \( T_z T = \pi_s(\mathbb{R}e_3 + i\mathbb{R}e_4) \) (where \( e_k \) is the \( k \)-th canonical basis vector of \( \mathbb{R}^{m+2} \)). The deck transformation group of \( g \) is given by the translations in \( \mathbb{C} \) by the elements of the lattice
\[ \Gamma := \mathbb{Z} \frac{1}{\sqrt{2}}(1 + i) \oplus \mathbb{Z} \frac{1}{\sqrt{2}}(1 - i). \]
It follows that the maximal tori of \( Q \) are isometric to the torus \( \mathbb{Q}/\Gamma \cong S_{1/\sqrt{2}} \times S_{1/\sqrt{2}} \).

Via the maximal tori of \( Q \), in particular the geodesics of \( Q \) can be described. The preceding description of the maximal tori especially gives a means to investigate which geodesics of \( Q \) are closed, and what their period is. One obtains the following results for the maximal geodesic \( \gamma_v : \mathbb{R} \to Q \) with \( \gamma_v(0) = v \in TQ \) in dependence on the characteristic angle \( \varphi(v) \in [0, \pi] \) introduced in Section 4.2:

If \( \tan(\varphi(v)) \) is rational, then \( \gamma_v \) is periodic.
More precisely, the minimal period \( L \) of \( \gamma_v \) then is
(a) for \( \varphi(v) = 0 \): \( L = \sqrt{2} \pi \).
(b) for \( \tan \varphi(v) = \frac{n_1}{n_2} \) with \( n_1, n_2 \in \mathbb{N} \) relatively prime and \( n_1, n_2 \) both odd: \( L = \frac{\pi}{\sqrt{2}} \sqrt{n_1^2 + n_2^2} \).
(c) for \( \tan \varphi(v) = \frac{n_1}{n_2} \) with \( n_1, n_2 \in \mathbb{N} \) relatively prime and either \( n_1 \) or \( n_2 \) even: \( L = \sqrt{2} \pi \sqrt{n_1^2 + n_2^2} \).

Of course, the totally geodesic submanifolds of \( Q \) of type (Geo) are the traces of the unit speed geodesics of \( Q \).

Types (I1, k) and (I2, k). Let 1 ≤ k ≤ \( \frac{m}{2} \). Then the map
\[ \mathbb{F}^k \to Q^m, [z_0, \ldots, z_k] \mapsto [z_0, \ldots, z_k, i z_0, \ldots, i z_k, 0, \ldots, 0] \]
is a totally geodesic isometric embedding. Its image corresponds to a Lie triple system of type (I1, k). If it is restricted to a totally geodesic \( \mathbb{R}P^k \) in \( \mathbb{F}^k \), one obtains another totally geodesic isometric embedding; the image of the latter embedding corresponds to a Lie triple system of type (I2, k).

Note that the totally geodesic submanifolds of \( Q \) of type (I1, k) are in fact \( k \)-dimensional complex projective subspaces of the ambient projective space \( \mathbb{F}^{m+1} \), and therefore also totally geodesic submanifolds of \( \mathbb{F}^{m+1} \).

Type (G3). The Segre embedding \( \psi : \mathbb{F}^1 \times \mathbb{F}^1 \to \mathbb{F}^3 \), \( ([z_0, z_1], [w_0, w_1]) \mapsto [z_0 w_0, z_0 w_1, z_1 w_0, z_1 w_1] \) (see for example [GH], p. 192) is an isometric embedding, whose image \( Q' := \psi(\mathbb{F}^1 \times \mathbb{F}^1) \) is holomorphically congruent to the standard complex quadric \( Q^2 \) in \( \mathbb{F}^3 \). If we let \( g : \mathbb{F}^3 \to \mathbb{F}^3 \) be the holomorphic isometry
with $f(Q') = Q^2$, and let $C \subset \mathbb{CP}^1$ be the trace of a closed geodesic in $\mathbb{CP}^1$ (then $C$ is isometric to $\mathbb{RP}^1$), the map
\[
\mathbb{CP}^1 \times C \hookrightarrow \mathbb{CP}^1 \times \mathbb{CP}^1 \xrightarrow{\psi} Q' \overset{2}{\rightarrow} Q^2 \rightarrow Q^m,
\]
(where the last arrow represents the standard embedding for the type $(G1,2)$ described above) is a totally geodesic isometric embedding. Its image corresponds to a Lie triple system of type $(G3)$.

**Type (A).** In this case it is not so easy to give a totally geodesic embedding. The obvious approach of calculating the image of a Lie triple system $m'$ of type (A) under the exponential map of $Q$ leads to a very complicated formula for the embedding of the corresponding totally geodesic submanifold. This formula does not provide any geometric insight, and for this reason we do not reproduce it here.

Rather, we prove in a different way that the totally geodesic submanifold $M$ of $Q$ corresponding to $m'$ is isometric to $S^{2\sqrt{10}/2}$. As described in Theorem 4.1 there exists $A \in \mathfrak{a}$ and an orthonormal system $(x, y, z)$ in $V(A)$ so that with $a := \frac{1}{\sqrt{2}}(2x + Jy)$ and $b := \frac{1}{\sqrt{2}}(y + Jx + \sqrt{3}Jz)$, $(a, b)$ is an orthonormal basis of $m'$. Via Proposition 5.1(b) one calculates
\[
\langle R(a, b), a \rangle = \frac{4}{5}.
\]
Because the curvature tensor of the Riemannian symmetric space $M$ is parallel, it follows that $M$ is a space of constant curvature $\frac{4}{5} = \frac{2}{5}$, and therefore $M$ is locally isometric to the sphere $S^2_{\frac{4}{5}}$. Hence $M$ is isometric either to the sphere $S^2_{\frac{4}{5}}$, or to the real projective space $\mathbb{RP}^2$ equipped with a Riemannian metric of constant sectional curvature $\frac{4}{5}$. To decide between these two cases, we calculate the length of closed geodesics in $M$. Let $v \in S(T_pM)$ be given. Because $M$ is a complete, totally geodesic submanifold of $Q$, the maximal geodesic $\gamma_v : \mathbb{R} \to Q$ of $Q$ with $\gamma_v(0) = p$ and $\dot{\gamma}_v(0) = v$ runs completely in $M$ and also is a geodesic of $M$. We have $\varphi(v) = \arctan(\frac{4}{5})$, therefore it follows from the preceding result on geodesics in $Q$ that $\gamma_v$ is periodic and that its minimal period is $\sqrt{2} \cdot \pi \cdot \sqrt{1^2 + 2^2} = \sqrt{10} \cdot \pi = 2\pi r$. This shows that $M$ is isometric to $S^2_{\frac{4}{5}}$.

**Remark 5.1** The types $(G3)$ and (A) of totally geodesic submanifolds are the ones which are missing from [CN1] and [CN2] as was described in the Introduction.

### 6 Conclusion

The present classification of the totally geodesic submanifolds of the complex quadric was made possible by a combination of the general relations between roots resp. root spaces of a symmetric space and the roots resp. root spaces of its totally geodesic submanifolds from Section 2 with specific results concerning the geometry of the complex quadric, especially the explicit description of its root spaces in Proposition 5.1(b). It seems likely to me that the same approach can be used to obtain a classification of totally geodesic submanifolds for the other two infinite series of rank 2 Riemannian symmetric spaces of compact type, namely the complex 2-Grassmannians $G_2(\mathbb{C}^m)$ and the quaternionic 2-Grassmannians $G_2(\mathbb{H}^n)$. Also one might be able to obtain at least some results on totally geodesic submanifolds in Riemannian symmetric spaces of higher rank via a refinement of the results from Section 2.

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