Partial regularity of weak solutions and life-span of smooth solutions to a biological network formulation model

Xiangsheng Xu

Received: 14 February 2020 / Accepted: 6 July 2020 / Published online: 21 July 2020
© Springer Nature Switzerland AG 2020

Abstract
In this paper we study partial regularity of weak solutions to the initial boundary value problem for the system

\[ -\text{div}[(I + m \otimes m)\nabla p] = S(x), \quad \partial_t m - D^2 m - E^2 (m \cdot \nabla p) \nabla p + |m|^{2(\gamma - 1)} m = 0, \]

where \( S(x) \) is a given function and \( D, E, \gamma \) are given numbers. This problem has been proposed as a PDE model for biological transportation networks. The mathematical difficulty is due to the fact that the system in the model features both a quadratic nonlinearity and a cubic nonlinearity. The regularity issue seems to have a connection to a conjecture by De Giorgi (Congetture sulla continuità delle soluzioni di equazioni lineari ellittiche autoaggiunte a coefficienti illimitati, Unpublished, 1995). We also investigate the life-span of classical solutions. Our results show that local existence of a classical solution can always be obtained and the life-span of such a solution can be extended as far away as one wishes as long as the term \([m(x, 0)]_{\infty, \Omega} + \|S(x)\|_{L^p, \Omega}^2\) is made suitably small, where \( N \) is the space dimension and \([\cdot]_{q, \Omega}\) denotes the norm in \( L^q(\Omega) \).

Keywords Biological network formulation · Cubic nonlinearity · Life-span of smooth solutions · Partial regularity of weak solutions

Mathematics Subject Classification Primary 35A01 · 35A09 · 35M33 · 35Q99

1 Introduction

Network formulation and transportation networks are fundamental processes in living systems [1]. The angiogenesis of blood vessels, leaf venation, and creation of neural pathways in nervous systems are some of the well known examples. Tremendous interest has been shown for these phenomena from different scientific communities such as biologists, engineers, physicists, and computer scientists. Of particular interest is their property

---

This article is part of the section “Applications of PDEs” edited by Hyeonbae Kang.

Xiangsheng Xu
xxu@math.msstate.edu

1 Department of Mathematics and Statistics, Mississippi State University, Mississippi State, MS 39762, USA
of optimal transport of fluids and other materials. The development of mathematical models for transportation networks and network formulation is a growing field. We would like to refer the reader to [2] for a comprehensive review and analysis of existing models.

In this paper we are interested in the mathematical analysis of a PDE model first proposed by Hu and Cai in [14] that describes the pressure field of a network using a Darcy’s type equation and the dynamics of the conductance network under pressure force effects. More precisely, let $\Omega$ be the network region, a bounded domain in $\mathbb{R}^N$, and $T$ a positive number. Set $\Omega_T = \Omega \times (0, T)$. We study the behavior of solutions to the system

$$-\text{div}[(I + m \otimes m) \nabla p] = S(x) \quad \text{in} \ \Omega_T,$$

$$\partial_t m - D^2 \Delta m - E^2 (m \cdot \nabla p) \nabla p + |m|^{2(\gamma - 1)} m = 0 \quad \text{in} \ \Omega_T,$$

coupled with the initial boundary conditions

$$p(x, t) = 0, \quad (x, t) \in \Sigma_T \equiv \partial \Omega \times (0, T),$$

$$m(x, t) = 0, \quad (x, t) \in \Sigma_T,$$

$$m(x, 0) = m_0(x), \quad x \in \Omega$$

for given function $S(x)$ and physical parameters $D, E, \gamma$ to be specified at a later time. Here the scalar function $p = p(x, t)$ is the pressure due to Darcy’s law, while the vector-valued function $m = (m_1(x, t), \ldots, m_N(x, t))^T$ is the conductance vector. The function $S(x)$ is the time-independent source term. Values of the parameters $D, E$, and $\gamma$ are determined by the particular physical applications one has in mind. For example, in leaf venation we have $\gamma \in \left[\frac{3}{2}, 1\right]$ [14].

In general nonlinear problems do not possess classical solutions. A suitable notion of a weak solution must be obtained for (1.1)–(1.5). It turns out [10] that we can introduce the following:

**Definition 1.1** Let $\Omega, T$ be given as before. A pair $(m, p)$ is said to be a weak solution to (1.1)–(1.5) in $\Omega_T$ if:

(D1) \[ m \in L^\infty \left(0, T; \left(W_0^{1, 2}(\Omega) \cap L^{2\gamma}(\Omega)\right)^N \right), \quad p \in L^\infty \left(0, T; W_0^{1, 2}(\Omega)\right), \quad (m \cdot \nabla p) \in L^\infty \left(0, T; L^2(\Omega)\right), \quad \partial_t m \in L^2 \left(0, T; (L^2(\Omega))^N \right); \]

(D2) \[ m(x, 0) = m_0 \text{ in } C \left([0, T]; (L^2(\Omega))^N \right); \]

(D3) Equations (1.1) and (1.2) are satisfied in the sense of distributions. That is, for a.e. $t \in (0, T)$ we have
The proof in [10] was based upon the formal gradient flow structure with respect to a suitable energy functional of the system, from which followed the estimates

\[
\int_{\Omega} \nabla p \nabla \psi \, dx + \int_{\Omega} (m \cdot \nabla p)(m \cdot \nabla \psi) \, dx = \int_{\Omega} S(x) \psi \, dx
\]

for each \( \psi \in W^{1,2}_0(\Omega) \) with \( (m \cdot \nabla \psi) \in L^2(\Omega) \),

\[
\int_{\Omega} \partial_{\alpha} m_i \psi \, dx + D^2 \int_{\Omega} \nabla m_i \nabla \psi \, dx + \int_{\Omega} |m|^{2(\gamma-1)} m_i \phi \, dx = E^2 \int_{\Omega} (m \cdot \nabla p) \partial_{\alpha_i} \phi \, dx
\]

for each \( \phi \in W^{1,2}_0(\Omega) \cap L^{2\gamma}(\Omega) \) such that \( \partial_{\alpha_i} \phi \in L^2(\Omega) \), \( i = 1, \ldots, N \).

**Lemma 1.2** [10] Assume:

(H1) \( \Omega \) is a bounded domain in \( \mathbb{R}^N \) with Lipschitz boundary \( \partial \Omega \);

(H2) \( S(x) \in L^2(\Omega) \);

(H3) \( D, E \in (0, \infty), \gamma \in [1, \infty) \); and

(H4) \( m_0 \in \left( W^{1,2}_0(\Omega) \cap L^{2\gamma}(\Omega) \right)^N \).

Then (1.1)–(1.5) has a weak solution.

The proof in [10] was based upon the formal gradient flow structure with respect to a suitable energy functional of the system, from which followed the estimates

\[
\frac{1}{2} \int_{\Omega} |m(x, \tau)|^2 \, dx + D^2 \int_{\Omega_\tau} |\nabla m|^2 \, dx + E^2 \int_{\Omega_\tau} (m \cdot \nabla p)^2 \, dx
\]

\[
+ \int_{\Omega_\tau} |m|^{2\gamma} \, dx + 2E^2 \int_{\Omega_\tau} |\nabla p|^2 \, dx \tau
\]

\[
= \frac{1}{2} \int_{\Omega} |m_0|^2 \, dx + 2E^2 \int_{\Omega} S(x) \, p \, dx \tau,
\]

\[
\int_{\Omega_\tau} |\partial_{\alpha_i} m|^2 \, dx + \frac{D^2}{2} \int_{\Omega_\tau} |\nabla m(x, \tau)|^2 \, dx + \frac{E^2}{2} \int_{\Omega} (m \cdot \nabla p)^2 \, dx
\]

\[
+ \frac{E^2}{2} \int_{\Omega} |\nabla p|^2 \, dx + \frac{1}{2\gamma} \int_{\Omega} |m|^{2\gamma} \, dx
\]

\[
= \frac{D^2}{2} \int_{\Omega} |\nabla m_0|^2 \, dx + \frac{E^2}{2} \int_{\Omega} (m_0 \cdot \nabla p_0)^2 \, dx + \frac{1}{2\gamma} \int_{\Omega} |m_0|^{2\gamma} \, dx
\]

\[
+ \frac{E^2}{2} \int_{\Omega} |\nabla p_0|^2 \, dx,
\]

where \( \tau \in (0, T], \Omega_\tau = \Omega \times (0, \tau) \), and \( p_0 \) is the solution of the boundary value problem

\[
- \text{div} \left[ (I + m_0 \otimes m_0) \nabla p_0 \right] = S(x), \quad \text{in } \Omega,
\]

\[
p_0 = 0 \quad \text{on } \partial \Omega.
\]

We refer the reader to [1, 2, 11, 17, 26, 27] for additional results concerning modeling, numerical simulations, and various properties of solutions. However, the general regularity theory remains fundamentally incomplete in high space dimensions. In particular, it is not known whether or not weak solutions develop singularities in space dimension \( N \geq 3 \).

In [18], Jian-Guo Liu and the author studied the partial regularity of weak solutions. In this context, we assume:
\((A1)\) \(S(x) \in L^q(\Omega)\) for some \(q > \frac{N}{2}\);
\((A2)\) \(D, E \in (0, \infty), \gamma \in \left(\frac{1}{2}, \infty\right)\); and
\((A3)\) \(m_0 \in \left(W^{1,2}_0(\Omega) \cap L^\infty(\Omega)\right)^N\).

It is not difficult to see from our proof below that the conclusion of Lemma 1.2 remains valid if we replace \((H2)–(H4)\) in the lemma by the assumptions \((A1)–(A3)\). The authors in [18] considered the following quantities:

\[ p_{y,r}(t) = \int_{B_r(y)} p(x,t)dx = \frac{1}{|B_r(y)|} \int_{B_r(y)} p(x,t)dx, \quad (1.9) \]

\[ m_{x,r}(t) = \int_{B_r(y)} m(x,t)dx, \quad (1.10) \]

\[ m_{z,r} = \int_{Q_r(z)} m(x,t)dxdt, \quad (1.11) \]

\[ A_r(z) = \frac{1}{r^N} \max_{t \in [r^{1/2}, r^{3/2}]} \int_{B_r(y)} (p(x,t) - p_{y,r}(t))^2dx, \quad (1.12) \]

\[ E_r(z) = \frac{1}{r^{N+2}} \int_{Q_r(z)} |m - m_{x,r}|^2dxdt + A_r(z) + r^{2\beta}, \quad (1.13) \]

where \(\beta, r > 0, z = (y, \tau) \in \Omega_T\), \(B_r(y)\) is the ball centered at \(y\) with radius \(r\), and \(Q_r(z)\) is the cylinder \(B_r(y) \times (\tau - \frac{1}{2}r^2, \tau + \frac{1}{2}r^2)\). Here and in what follows it is understood that if \(Q_r(z)\) (resp. \(B_r(y)\)) is not contained in \(\Omega_T\) (resp. \(\Omega\)) we replace \(Q_r(z)\) by \(Q_r(z) \cap \Omega_T\) (resp. \(B_r(y) \cap \Omega\)). A result of [18] asserts that \(p \in C([0,T]; L^2(\Omega))\), and thus \((1.12)\) makes sense. The main result of [18] can be stated as follows:

**Lemma 1.3** [18] Let \((H1), (A1)–(A3)\) be satisfied and \((m, p)\) be a weak solution of \((1.1)–(1.5)\). Assume:

\[(A4)\] \(N = 2\) or \(3\).

If \(z \in \Omega_T\) is such that

\[ \liminf_{r \to 0} E_r(z) = 0 \quad \text{and} \quad \limsup_{r \to 0} m_{z,r} < \infty, \quad (1.14) \]

then \(z\) is a regular point. That is, there is a neighborhood of \(z\) in which \(m\) is Hölder continuous. Furthermore, the set of all non-regular points, i.e., singular points, which we denote by \(\mathcal{S}\), has parabolic Hausdorff dimension \(N\).

The proof in [18] is argument by contradiction. In the first part of this paper we shall investigate the partial regularity issue from a different perspective. To introduce our results, we let
\[
\text{osc}_{B_r(y)} p = \text{ess sup}_{x_1, x_2 \in B_r(y)} \{p(x_1, t) - p(x_2, t)\}
\]
for \( y \in \overline{\Omega} \) and a.e. \( t \in (0, T) \), and
\[
\delta_r(y) = \text{ess sup}_{0 \leq t \leq T} \text{osc}_{B_r(y)} p.
\]

To see that \( \delta_r(y) \) is well-defined, we invoke Proposition 2.1 in [18] which states
\[
p \in L^\infty(\Omega_T).
\]

**Theorem 1.4** Let (H1), (A1)–(A3) be satisfied and \( (m, p) \) be a weak solution of (1.1)–(1.5). If \( y \in \overline{\Omega} \) is such that
\[
\delta_r(y) \to 0 \quad \text{as} \quad r \to 0,
\]
then for each \( n > 0 \) there is a \( r > 0 \) with
\[
|m|^{2n} \in L^\infty(0, T; L^2(B_r(y))) \cap L^2(0, T; W^{1,2}(B_r(y))), \quad \text{and}
\]
\[
|m|^{2n} (m \cdot \nabla p)^2 \in L^1(\Lambda_r(y)),
\]
where
\[
\Lambda_r(y) = B_r(y) \times (0, T).
\]

If \( N = 2 \), we obtain from [26] that
\[
\left( \text{osc}_{B_r(y)} p \right)^2 \ln \frac{R}{r} \leq c \int_{B_R(y)} |\nabla p|^2 \, dx + \int_{B_R(y)} (m \cdot \nabla p)^2 \, dx + cR^2
\]
for a.e \( t \in (0, T) \) and \( 0 < r \leq R \). Here and in what follows the letter \( c \) denotes a positive number whose value can always be computed from the given data at least in theory. Thus (1.18) does hold. In fact, this theorem is essentially Proposition 3.2 in [26]. To find conditions under which (1.18) is true for \( N > 2 \) turns out to be very challenging. The following theorem addresses this issue.

**Theorem 1.5** Let (H1), (A1)–(A4) all hold and \( (m, p) \) be a weak solution of (1.1)–(1.5). If \( y \in \Omega \) is such that
\[
\limsup_{r \to 0} \max_{0 \leq t \leq T} |m_{y,r}(t)| < \infty, \quad \text{and}
\]
\[
\limsup_{r \to 0} \text{ess sup}_{0 \leq t \leq T} \frac{1}{p^{N-2}} \int_{B_r(y)} |\nabla m(x, t)|^2 \, dx < \infty.
\]
then (1.18) holds at \( y \). Furthermore, the point \( z = (y, \tau) \) satisfies (1.14) for each \( \tau \in (0, T) \). That is, \( \{y\} \times (0, T) \) are all regular points.

On account of (A4), (1.23) and (1.24) imply (1.18) only when \( N \leq 3 \). The first conclusion in this theorem will be formulated as Theorem 3.2 in Sect. 3.
Note that by its definition the set of regular points is always open. We have not been able to obtain the Hausdorff measure of $\mathcal{S}$ in the context of this theorem. However, if $N = 2$, then (1.24) is satisfied for all $y \in \Omega$. As for (1.23) in this case, we can infer from the argument given in [8], p. 104) that

$$\max_{r \in [0,T]} |m_{y,r}(t)| < \max_{r \in [0,T]} |m_{y,R}(t)| + c \ln \frac{R}{r} \quad \text{for all } 0 < r \leq R. \quad (1.25)$$

That is, for each $\varepsilon > 0$ we have

$$\lim_{r \to 0} \max_{r \in [0,T]} |m_{y,r}(t)| = 0. \quad (1.26)$$

A recent result of the author [27] indicates that $\mathcal{S}$ is empty when $N = 2$ and some additional assumptions on $\partial \Omega$ and the given data are satisfied.

There are two very interesting mathematical features associated with the system. The first one concerns the elliptic coefficient matrix $A \equiv I + m \otimes m$ in the first equation. Remember that the existing regularity theory for elliptic equations requires that the largest eigenvalue $\lambda_1$ of $A$ and the smallest one $\lambda_2$ be suitably “balanced”. A typical example of such assumptions is that $\lambda_1 \leq c\lambda_2$ and $\lambda_2$ is an $A_2$-weight [12]. That is, we have

$$\int_{B_r(y)} \lambda_2 dx \int_{B_r(y)} \frac{1}{\lambda_2} dx \leq c \quad \text{for each ball } B_r(y) \subset \Omega. \quad (1.27)$$

The matrix $A$ here satisfies

$$|\xi|^2 \leq (A \xi \cdot \xi) \leq (1 + |m|^2)|\xi|^2 \quad \text{for each } \xi \in \mathbb{R}^N. \quad (1.28)$$

Thus if $m$ is not locally bounded a priori, our case lies outside the scope of the standard elliptic regularity theory. Our situation seems to be related to a conjecture by De Giorgi [4] (also see [22]), which, in our context, roughly says that

$$\underset{0 \leq t \leq T}{\text{ess sup}} \int_{\Omega} \exp \sqrt{1 + |m|^2} \ dx < \infty \quad \text{implies} \quad p \in L^\infty(0, T; C_{loc}(\Omega)). \quad (1.29)$$

This is indeed true if the space dimension is 2 [26]. Unfortunately, the membership of $p$ in $L^\infty(0, T; C_{loc}(\Omega))$ is not enough to bridge the gap to the local boundedness of $m$. As we shall see in Sect. 3, we need to strengthen the assumption to $p \in L^\infty(0, T; C^\alpha_{loc}(\Omega))$ for some $\alpha \in (0, 1)$ in order to show that $m$ is locally bounded. The second one is the tri-linear term $(m \cdot \nabla p) \nabla p$ in the system, which actually represents a cubic nonlinearity. Currently, there has not been much research work done on this type of nonlinearities.

In the second part of this paper we study the existence of a weak solution that possesses the additional property

$$(D4) \quad \|m\|_{\infty, \Omega} < \infty \quad \text{and} \quad \sup_{0 \leq t \leq T} \|\nabla p\|_{q, \Omega} < \infty \quad \text{for each } q > 1.$$  

We would like to remark that if $N = 2$ then the two conditions in (D4) are equivalent (see Lemma 2.7 below).

**Theorem 1.6** Let (A2) hold. If $\partial \Omega$ is $C^{2,\alpha}$, $S(x) \in C^\alpha(\Omega)$, and $m_0 \in (C^{2,\alpha}(\Omega))^N$ for some $\alpha \in (0, 1)$, then a weak solution to (1.1)–(1.5) with the additional property (D4) is also a classical one.
The proof of this proposition will be presented at the end of Sect. 2.

**Theorem 1.7**  Let (A1)–(A3) hold. Assume:

(H5) \( m_0 \) is Hölder continuous on \( \Omega \);
(H6) \( \partial \Omega \) is \( C^1 \).

Then there is a positive number \( T \) determined by the given data such that (1.1)–(1.5) has a weak solution \((m, p)\) with the property (D4) on \( \Omega_T \).

The next theorem reveals how the life-span of a classical solution depends on the size of given data.

**Theorem 1.8**  Let the assumptions of Theorem 1.7 be satisfied. For each \( T > 0 \) there is a positive number \( \delta = \delta(T) \) such that (1.1)–(1.5) has a weak solution on \( \Omega_T \) with the property (D4) whenever \( \|S(x)\|_{\mathcal{W}^{1,q}_0} + \|m_0\|_{\infty, \Omega} \leq \delta \).

We believe that the fact that the number \( \delta \) in the theorem has to depend on \( T \) is related to the time-independence of the source term \( S(x) \). If \( S \) is not identically 0, then we always have \( \|S\|_{q, \Omega \times (0, \infty)} = \infty \) for any \( q > 1 \). We speculate that if the source term \( S \) is a function of both time and space and \( \|S\|_{q, \Omega \times (0, \infty)} \) is suitably small for some \( q > 1 \) we may be able to prove the existence of a classical solution on \( \Omega \times [0, \infty) \) [17]. However, we must point out that the time-dependence of \( S \) will cause (1.6) to fail, and thus a new existence theorem other than the one in [10] is needed.

Nonlinearities in partial differential equations often play a rather peculiar role in blow-up of solutions. In this connection we would like to mention the well known Fujita phenomenon. It roughly says that for certain types of nonlinearities solutions exists globally for some data, while for some other data solutions blow up no matter how small or smooth these data are [7]. Note that Theorem 1.8 is neither a global existence result nor a blow-up result. As we mentioned earlier, many regularity problems associated with (1.1)–(1.5) remain open.

The rest of the paper is organized as follows: in Sect. 2 we collect some preparatory lemmas. Here we take or refine some relevant classical results. In Sect. 3 we investigate regularity and partial regularity of weak solutions. We show that \( p \in L^\infty(0, T; C^3(\overline{\Omega})) \) leads to Hölder continuity of \( m \). The proof of Theorem 1.5 is also given here. Section 4 is devoted to the proof of Theorems 1.7 and 1.8. A successive approximation scheme is employed for the second theorem. The mathematical challenge here is that one must show that the entire approximate sequence converges in a suitable sense.

2 Preliminaries

In this section we prepare some background results. Some of them are well-known and some of them are a refinement of known results so that they fit our purpose.

Our first result is an elementary inequality whose proof is contained in [21, p. 146–148].

**Lemma 2.1**  Let \( x, y \) be any two vectors in \( \mathbb{R}^N \). Then:

(i) \( \text{For } \gamma \geq 1, \)

SN Partial Differential Equations and Applications
\[
\left( (|x|^{2^{j-2}}x - |y|^{2^{j-2}}y) \cdot (x - y) \right) \geq \frac{1}{2^{2^{j-1}}} |x - y|^{2^{j}};
\]

(ii) For \( \frac{1}{2} < \gamma \leq 1 \),
\[
(|x| + |y|)^{2-2\gamma} \left( (|x|^{2^{j-2}}x - |y|^{2^{j-2}}y) \cdot (x - y) \right) \geq (2\gamma - 1)|x - y|^2.
\]

For each \( q \geq 1 \) we define the Banach space \( L_q^*(\Omega) \), where \( \Omega \subseteq \mathbb{R}^N \), by
\[
L_q^*(\Omega) = \left\{ f : \text{there is a number } c \geq 0 \text{ such that } |\{ x \in \Omega : |f(x)| \geq t \} | \leq \frac{c^q}{t^q} \text{ for all } t > 0 \right\}.
\]
The smallest \( c \) such that the above inequality holds is the norm of \( f \) in \( L_q^*(\Omega) \). We easily see
\[
\|f\|_{L_q^*(\Omega)} \leq \|f\|_{L^q(\Omega)},
\]
(2.1)

Moreover, for each measurable subset \( \Omega \subseteq \mathbb{R}^N \) and each \( \varepsilon \in (0, q - 1] \) we have from \( [3] \) that
\[
\int_{\Omega} |f|^q - \epsilon dx \leq \frac{q}{\varepsilon} |\Omega|^\frac{q}{q-\epsilon} \left( \|f\|_{L_q^*(\Omega)} \right)^{q-\epsilon}.
\]
(2.2)

The next two lemmas deal with sequences of nonnegative numbers which satisfy certain recursive inequalities.

**Lemma 2.2** Let \( \{y_n\}, n = 0, 1, 2, \ldots \), be a sequence of positive numbers satisfying the recursive inequalities
\[
y_{n+1} \leq cb^n y_n^{1+\alpha} \quad \text{for some } b > 1, c, \alpha \in (0, \infty).
\]
If
\[
y_0 \leq c^{-\frac{1}{b} - \frac{1}{\alpha}},
\]
then \( \lim_{n \to \infty} y_n = 0 \).

This lemma is well-known. See, e.g., [5, p. 12]. Here we give a brief proof. We can easily show
\[
y_{n+1} \leq c \frac{(b+\alpha)^{n+1} - 1}{b^{n+1} - 1} \frac{(1+\alpha)^{n+1} - 1}{(1+\alpha)^{n+1} - 1} y_n^{1+\alpha} b^{n+1} = c^{-\frac{1}{b} - \frac{1}{\alpha}} \left( \frac{c}{b^{\frac{1}{\alpha}}} y_0 \right)^{1+\alpha} b^{\frac{n+1}{\alpha}}.
\]
(2.3)

Therefore, if \( b > 1 \) and \( c^{\frac{1}{b}} b^\frac{1}{\alpha} y_0 \leq 1 \), then we have that \( \lim_{n \to \infty} y_n = 0 \).

**Lemma 2.3** Let \( \alpha, \lambda \in (0, \infty) \) be given and \( \{b_k\} \) a sequence of nonnegative numbers with the property
\[
b_k \leq b_0 + \lambda b_{k-1}^{1+\alpha} \quad \text{for } k = 1, 2, \ldots.
\]
If \( 2\lambda(2b_0)^{\alpha} < 1 \), then
\[ b_k \leq \frac{b_0}{1 - \lambda(2b_0)^2} \leq 2b_0 \text{ for all } k \geq 0. \]

This lemma can easily be established via induction.

**Lemma 2.4** Let \( \Omega \) be a bounded domain in \( \mathbb{R}^N \) with Lipschitz boundary \( \partial \Omega \). Assume that \( w \) is a weak solution of the initial boundary value problem

\[
\begin{align*}
\partial_t w - D^2\Delta w &= \text{div} g + g_0 \quad \text{in } \Omega_T, \\
w &= 0 \quad \text{on } \Sigma_T, \\
w(x, 0) &= w_0(x),
\end{align*}
\]

where \( w_0 \) is Hölder continuous on \( \overline{\Omega} \) and \(|g|^2, g_0 \in L^q(\Omega_T)\) for some \( q > 1 + \frac{N}{2} \). Then \( w \) is Hölder continuous on \( \overline{\Omega_T} \). That is, there is a number \( \beta \in (0, 1) \) such that

\[
\sup_{(x_1,t_1), (x_2,t_2) \in \Omega_T} \frac{|w(x_1, t_1) - w(x_2, t_2)|}{|x_1 - x_2| + |t_1 - t_2|^{\beta}} < \infty.
\]

This result is well-known, and it can be found, for example, in [16]. Next, we cite a result from [23, p. 82].

**Lemma 2.5** Let \((H6)\) hold and assume

\begin{enumerate}[\text{(L1)}]
\item \( A(x) \) is an \( N \times N \) matrix whose entries are continuous functions on \( \overline{\Omega} \), satisfying the uniform ellipticity condition

\[
\lambda |\xi|^2 \leq (A(x)\xi \cdot \xi) \leq \frac{1}{\lambda} \text{ on } \Omega \text{ for some } \lambda > 0.
\]
\end{enumerate}

If \( u \) is a weak solution to the boundary value problem

\[
-\text{div}(A\nabla u) = \text{div} g + g_0 \quad \text{in } \Omega, \\
u = 0 \quad \text{on } \partial \Omega,
\]

then for each \( q > 1 \) there is a positive \( c = c(N, q, \Omega) \) with the property

\[
\|\nabla u\|_{q, \Omega} \leq c \left( \|g\|_{q, \Omega} + \|g_0\| \right).
\]

We can easily infer from the preceding two lemmas that \((D4)\) can be replaced by

\begin{enumerate}[\text{(D4)}]
\item \( \|m\|_{\infty, \Omega_T} < \infty \) and there is a \( q > 1 + \frac{N}{2} \) such that \( \sup_{0 \leq \tau \leq T} \|\nabla p\|_{2q, \Omega} < \infty \).
\end{enumerate}

**Lemma 2.6** Let \( w \) be a weak solution of the initial boundary value problem
\[ \partial_t w - D^2 \Delta w + |w|^{2(\gamma - 1)} w = g \quad \text{in } \Omega_T, \quad (2.4) \]

\[ w = 0 \quad \text{on } \Sigma_T, \quad (2.5) \]

\[ w(x, 0) = m_0(x) \quad \text{on } \Omega. \quad (2.6) \]

Then there is a positive number \( c = c(N) \) such that
\[
\|w\|_{\infty, \Omega_T} \leq c \left( \|m_0\|_{\infty, \Omega} + |\Omega_T|^{\frac{1}{4}} \sup_{0 \leq t \leq T} \|g\|_{N, \Omega} \right). 
\]

**Proof** Even though (2.4) is a system, the classical method due to De Giorgi is still applicable. Here we give an outline of the proof. Set
\[
M = \|m_0\|^2_{\infty, \Omega}. 
\]
Then define
\[
k_n = k - \frac{k}{2^n} + M, \quad n = 0, 1, 2, \ldots,
\]
where \( k > 0 \) is a number to be determined. Let
\[
A_n(t) = \{ x \in \Omega : |w|^2(x, t) \geq k_n \}.
\]
Without loss of generality, assume \( N > 2 \). Use \((|w|^2 - k_n)^+ w\) as a test function in (2.4) to derive, with the aid of the Gagliardo–Nirenberg–Sobolev inequality, that
\[
\begin{align*}
\frac{1}{4} \frac{d}{dt} & \int_{\Omega} \left[ (|w|^2 - k_n)^+ \right]^2 dx + D^2 \int_{\Omega} (|w|^2 - k_n)^+ |\nabla w|^2 dx \\
& + \frac{D^2}{2} \int_{\Omega} |\nabla (|w|^2 - k_n)^+|^2 dx \\
& \leq \int_{\Omega} (g \cdot w)(|w|^2 - k_n)^+ dx \\
& \leq \|(|w|^2 - k_n)^+\|_{\frac{2N}{N-2}} \| (g \cdot w) \chi_{A_n(t)} \|_{\frac{2N}{N-2}} \\
& \leq c \| \nabla (|w|^2 - k_n)^+ \|_2 \| (g \cdot w) \chi_{A_n(t)} \|_{\frac{2N}{N-2}} \\
& \leq \frac{D^2}{4} \int_{\Omega} |\nabla (|w|^2 - k_n)^+|^2 dx + c \| (g \cdot w) \|_{N, \Omega}^2 |A_n(t)|,
\end{align*}
\]
from whence follows
\[
\begin{align*}
\sup_{0 \leq t \leq T} \int_{\Omega} \left[ (|w|^2 - k_n)^+ \right]^2 dx + \int_{\Omega_T} |\nabla (|w|^2 - k_n)^+|^2 dx dt \\
& \leq c \sup_{0 \leq t \leq T} \| (g \cdot w) \|_{N, \Omega}^2 \int_0^T |A_n(t)| dt.
\end{align*}
\]
Use the Gagliardo–Nirenberg–Sobolev inequality again to obtain
\[
\int_{\Omega_T} \left[ (|w|^2 - k_n)^+ \right]^{\frac{2N}{N-2}} \, dx \, dt \\
= \int_0^T \int_\Omega \left[ (|w|^2 - k_n)^+ \right] \frac{4}{N} \left( \left[ (|w|^2 - k_n)^+ \right]^{\frac{N}{2}} \right) dt \\
\leq c \int_0^T \int_\Omega \left| \nabla (|w|^2 - k_n)^+ \right|^2 \, dx \, dt \left( \sup_{0 \leq t \leq T} \int_\Omega \left[ (|w|^2 - k_n)^+ \right]^2 \right)^{\frac{N}{2}} \\
\leq c \sup_{0 \leq t \leq T} \| (g \cdot w) \|_{N, \Omega}^{1+\frac{N}{2}} \left( \int_0^T |A_n(t)| \, dt \right)^{1+\frac{N}{2}}.
\] (2.10)

Set
\[
y_n = \int_0^T |A_n(t)| \, dt = \{|(x, t) \in \Omega_T : |w|^2(x, t) \geq k_n\}.
\]

We can easily show that
\[
y_{n+1} = \int_0^T |A_{n+1}(t)| \, dt \\
\leq c \frac{4^{\frac{N}{2}(n+1)}}{k^{\frac{2N}{N-2}}} \sup_{0 \leq t \leq T} \| (g \cdot w) \|_{N, \Omega}^{1+\frac{N}{2}} y_n^{1+\frac{N}{2}}.
\] (2.11)

This puts us in a position to apply Lemma 2.2. Upon doing so, we arrive at
\[
\| |w| |_{\infty, \Omega} \leq k + M,
\] (2.12)
provided that
\[
k = cy_0^{\frac{1}{2N}} \sup_{0 \leq t \leq T} \| (g \cdot w) \|_{N, \Omega} \\
\leq cy_0^{\frac{1}{2N}} \| w \|_{\infty, \Omega} \sup_{0 \leq t \leq T} \| g \|_{N, \Omega} \\
\leq e \| |w| |_{\infty, \Omega} + c(e)y_0^{\frac{1}{2N}} \sup_{0 \leq t \leq T} \| g \|_{N, \Omega}^2.
\] (2.13)

Use this in (2.12) to yield the desired result.
This completes the proof. \(\square\)

**Lemma 2.7** Let (H2), (H3), (H5), and (H6) hold and \((m, p)\) be a weak solution of (1.1)–(1.5). Assume \(N = 2\). Then \(\| m \|_{\infty, \Omega_T} < \infty\) if and only if \(\sup_{0 \leq t \leq T} \| \nabla p \|_{q, \Omega} < \infty\) for each \(q > 1\).

**Proof** Suppose that \(\| m \|_{\infty, \Omega_T} < \infty\). Then Eq. (1.1) is uniformly elliptic. A result in [19] asserts that there is a \(q > 2\) such that
\[ \| \nabla p \|_{q, \Omega} \leq c \| S(x) \|_{x \in \Omega}. \quad (2.14) \]

This together with an argument in [28] (also see [16, p. 182]) implies that \( m \) is Hölder continuous on \( \overline{\Omega_T} \). Thus Lemma 2.5 becomes applicable to (1.1). This yields the desired result.

Now assume that \( \sup_{0 \leq t \leq T} \| \nabla p \|_{q, \Omega} < \infty \) for each \( q > 1 \). Fix \( \tau \in (0, T] \). By Lemma 2.6, there is a positive number \( c = c(N) \) such that

\[
\| m \|_{\infty, \Omega \times (0, \tau)} \leq c \left( \| m_0 \|_{\infty, \Omega} + \| \Omega \times (0, \tau) \|^{1/q} \sup_{0 \leq t \leq \tau} \| (m \cdot \nabla p) \nabla p \|_{N, \Omega} \right)
\leq c + c \tau^{1/q} \| m \|_{\infty, \Omega \times (0, \tau)} \sup_{0 \leq t \leq \tau} \| \nabla p \|^2_{l, \Omega}
\leq c + c \tau^{1/q} \| m \|_{\infty, \Omega \times (0, \tau)}, \quad (2.15)
\]

where \( c \) is independent of \( \tau \). Hence we can choose \( \tau \) so that

the coefficient of \( \| m \|_{\infty, \Omega \times (0, \tau)} \) on the right-hand side of (2.15) \( \equiv c \tau^{1/q} < 1 \). \quad (2.16)

This immediately gives \( \| m \|_{\infty, \Omega \times (0, \tau)} < \infty \). Obviously, \( [0, T] \) can be divided into a finite number of subintervals with each one of them having length less than \( \tau \). Apply the preceding argument successively to each one of the subintervals, starting with \( [0, \tau] \). The desired result follows.

Before we conclude this section, we offer the proof of Theorem 1.6.

**Proof of Theorem 1.6** We will only give an outline of the proof, leaving many well-known technical details out. Assume (D4) and (H3). By the Calderon–Zygmund inequality for parabolic equations [16], we have

\[ \partial_t m, \Delta m \in (L^q(\Omega_T))^N \quad \text{for each } q > 1. \]

Differentiate both sides of (1.2) with respect to each one of the space variables and apply Lemma 2.4 to the resulting equations in a suitable way to conclude that \( \nabla m \) is Hölder continuous on \( \overline{\Omega_T} \). As a result, the classical Schauder estimates [9, p. 107] become applicable to (1.1). Upon applying, we yield that \( p \in L^\infty(0, T; C^{2,\alpha}(\overline{\Omega})) \) for some \( \alpha \in (0, 1) \). Differentiate (1.1) with respect to \( t \) to obtain

\[
- \text{div} ((I + m \otimes m) \nabla \partial_t p) = \text{div}(\partial_t m \otimes m \nabla p) + \text{div}(m \otimes \partial_t m \nabla p) \quad \text{in } \Omega_T. \quad (2.17)
\]

This puts us in a position to use Lemma 2.5, from which follows

\[ \nabla \partial_t p \in (L^q(\Omega_T))^N \quad \text{for each } q > 1. \]

Differentiate both sides of (1.2) with respect to \( t \) and apply the Calderon–Zygmund inequality to the resulting equation to obtain

\[
\frac{\partial_t^2 m}{\partial t^2}, \Delta \partial_t m \in (L^q(\Omega_T))^N \quad \text{for each } q > 1.
\]

Now the right-hand side of (2.17) is Hölder continuous in the space variables, and hence we can apply the Schauder estimates to it to get
\[ \partial_t p \in L^q(0, T; C^{2,\alpha}(\overline{\Omega})) \quad \text{for each } q > 1. \]

This implies that \( \nabla p \) is Hölder continuous on \( \overline{\Omega}_T \). On the other hand, owing to (H3), the term \( |m|^{2(\gamma-1)}m \) is also Hölder continuous. We can conclude from the parabolic Schauder estimates [15] that \( m \) is a classical solution of (1.2).

### 3 Partial regularity of weak solutions

We begin this section by proving Theorem 1.4. To this end, we introduce the following notation. For \( -\infty < \ell < L < \infty \) denote by \( \theta_{\ell,L}(s) \) the function

\[
\theta_{\ell,L}(s) = \begin{cases} 
L & \text{if } s \geq L, \\
\ell & \text{if } s < \ell, \\
\text{if } \ell < s < L, 
\end{cases}
\]

(3.1)

**Proof of Theorem 1.4** We only need to consider the case where \( N > 2 \). Let \( y \) be given as in the theorem. First we assume that \( y \) is an interior point. We will show that for each \( n > 0 \) there is a \( r \in (0, \text{dist}(y, \partial\Omega)) \) such that

\[
|m|^{2(1+n)}(1+\frac{r}{\text{dist}(y, \partial\Omega)}) \in L^1(\Lambda_2(y)) \quad \text{whenever } |m|^{2(1+n)} \in L^1(\Lambda_r(y)).
\]

(3.2)

By iterating this result, we obtain our theorem.

To see (3.2), for \( r \in (0, \text{dist}(y, \partial\Omega)) \) selected as below we pick a \( C^\infty \) cut-off function with the properties

\[
\eta = 1 \quad \text{on } B_\frac{1}{2}(y),
\]

(3.3)

\[
\eta = 0 \quad \text{outside } B_r(y),
\]

(3.4)

\[
0 \leq \eta \leq 1 \quad \text{on } \mathbb{R}^N,
\]

(3.5)

\[
|\nabla \eta| \leq \frac{c}{r} \quad \text{on } \mathbb{R}^N.
\]

(3.6)

Given \( n > 0, L > 1 \), we easily see that the function \( \left[ \theta_{1,L}(|m|^2) \right]^n m \eta^2 \) is a legitimate test function for (1.2). Upon using it, we obtain

\[
\frac{1}{2} \frac{d}{dt} \int_\Omega \left[ \theta_{1,L}(s) \right]^n d\eta^2 dx + D^2 \int_\Omega \left[ \theta_{1,L}(|m|^2) \right]^n |\nabla m|^2 \eta^2 dx
\]

\[
+ \frac{nD^2}{2} \int_\Omega \left[ \theta_{1,L}(|m|^2) \right]^{n-1} |\nabla \theta_{1,L}(|m|^2)|^2 \eta^2 dx + \int_\Omega |m|^2 |\theta_{1,L}(|m|^2)|^n \eta^2 dx
\]

\[
= E^2 \int_\Omega (m \cdot \nabla p)^2 \left[ \theta_{1,L}(|m|^2) \right]^n \eta^2 dx - D^2 \int_\Omega \left[ \theta_{1,L}(|m|^2) \right]^n \nabla m \cdot 2\eta \nabla \eta dx
\]

\[
\leq E^2 \int_\Omega (m \cdot \nabla p)^2 \left[ \theta_{1,L}(|m|^2) \right]^n \eta^2 dx + \frac{D^2}{2} \int_\Omega \left[ \theta_{1,L}(|m|^2) \right]^n |\nabla m|^2 \eta^2 dx + \frac{c}{r^2} \int_\Omega \left[ \theta_{1,L}(|m|^2) \right]^n |m|^2 dx.
\]

(3.7)
Here we have used the fact that
\[ \nabla m m = \frac{1}{2} \nabla |m|^2, \quad \nabla \theta_{1,L}(|m|^2) = 0 \quad \text{on } \{ |m|^2 \geq L \} \cup \{ |m|^2 \leq 1 \}. \]  
(3.8)

Integrate (3.7) to obtain

\[
\begin{align*}
\text{ess} \sup_{0 \leq t \leq T} \int_{B_{r}(y)}^{\overline{m}} \left[ \theta_{1,L}(s) \right]^{n} d\eta^2 dx + n \int_{\Lambda_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n-1} \left| \nabla \theta_{1,L}(|m|^2) \right| \eta^2 dx dt \\
\leq c \int_{B_{r}(y)} (m \cdot \nabla p)^2 \left[ \theta_{1,L}(|m|^2) \right]^{n} \eta^2 dx dt + \frac{c}{r^2} \int_{\Lambda_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} |m|^2 dx dt \\
+ \int_{B_{r}(y)} \int_{0}^{\overline{m}} \left[ \theta_{1,L}(s) \right]^{n} d\eta^2 dx.
\end{align*}
\]  
(3.9)

To bound the first term on the right hand side of (3.9), we keep (1.17) in mind and use \( \left[ \theta_{1,L}(|m|^2) \right]^{n} (p - p_{y,r}(t)) \eta^2 \) as a test function in (1.1) to derive

\[
\begin{align*}
\int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} |\nabla p|^2 \eta^2 dx + \int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} (m \cdot \nabla p)^2 \eta^2 dx \\
= -\int_{B_{r}(y)} \nabla p \left[ \theta_{1,L}(|m|^2) \right]^{n} (p - p_{y,r}(t)) 2\eta \nabla \eta dx \\
- n \int_{B_{r}(y)} \nabla p (p - p_{y,r}(t)) \left[ \theta_{1,L}(|m|^2) \right]^{n-1} \nabla \theta_{1,L}(|m|^2) \eta^2 dx \\
- n \int_{B_{r}(y)} (m \cdot \nabla p) m \left[ \theta_{1,L}(|m|^2) \right]^{n-1} \nabla \theta_{1,L}(|m|^2) (p - p_{y,r}(t)) \eta^2 dx \\
- \int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} (p - p_{y,r}(t)) (m \cdot \nabla p) m 2\eta \nabla \eta dx \\
+ \int_{B_{r}(y)} S(x) \left[ \theta_{1,L}(|m|^2) \right]^{n} (p - p_{y,r}(t)) \eta^2 dx \\
\leq \frac{1}{2} \int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} |\nabla p|^2 \eta^2 dx + \frac{c \sigma^2(y)}{r^2} \int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} dx \\
+ c \delta^2_r \int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n-2} |\nabla \theta_{1,L}(|m|^2)|^2 \eta^2 dx \\
+ \frac{1}{2} \int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} (m \cdot \nabla p)^2 \eta^2 dx \\
+ \frac{c \sigma^2(y)}{r^2} \int_{B_{r}(y)} |m|^2 \left[ \theta_{1,L}(|m|^2) \right]^{n} dx \\
+ \delta_r(y) \| S(x) \|_{X_{B_{r}(y)} \} \left( \int_{B_{r}(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} \eta^2 dx \right)^{\frac{n}{n-2}} dx \\
+ c \delta^2_r(y) \int_{B_{r}(y)} |m|^2 \left[ \theta_{1,L}(|m|^2) \right]^{n-2} |\nabla \theta_{1,L}(|m|^2)|^2 \eta^2 dx.
\end{align*}
\]  
(3.10)
Remember that $\theta_{1,L}(|m|^2) \geq 1$. Thus we always have
\[
\left[ \theta_{1,L}(|m|^2) \right]^{n-2} \leq \left[ \theta_{1,L}(|m|^2) \right]^{n-1}.
\] (3.11)

We can easily see from (3.8) that
\[
|m|^2 \left[ \theta_{1,L}(|m|^2) \right]^{n-2} |\nabla \theta_{1,L}(|m|^2)|^2 = \left[ \theta_{1,L}(|m|^2) \right]^{n-1} |\nabla \theta_{1,L}(|m|^2)|^2.
\] (3.12)

Use the Gagliardo–Nirenberg–Sobolev inequality to estimate
\[
\delta_r(y)||S(x)||_{L^2,B_r(y)} \left( \int_{B_r(y)} \left[ \left[ \theta_{1,L}(|m|^2) \right]^{\frac{n+1}{2}} \eta^2 \right]^{\frac{2}{n+1}} \frac{dx}{r^{2(n+1)}} \right)^{\frac{n+1}{n+2}} \leq \delta_r(y)||S(x)||_{L^2,B_r(y)} \left( \int_{B_r(y)} \left[ \theta_{1,L}(|m|^2) \right]^{\frac{n+1}{2}} \eta^2 \right) \leq \delta_r(y)||S(x)||_{L^2,B_r(y)} \left( \int_{B_r(y)} \frac{dx}{r^{2(n+1)}} \right)^{\frac{n+1}{n+2}} \leq \delta_r(y)||S(x)||_{L^2,B_r(y)} \left( \int_{B_r(y)} \nabla \left[ \theta_{1,L}(|m|^2) \right]^{\frac{n+1}{2}} \eta^2 \right)^{\frac{n+1}{n+2}} \leq \delta_r(y)||S(x)||_{L^2,B_r(y)} \left( \int_{B_r(y)} \left[ \theta_{1,L}(|m|^2) \right]^{\frac{n+1}{2}} \eta^2 \right)^{\frac{n+1}{n+2}} \] (3.13)

Keeping those in mind, we integrate (3.10) with respect to $t$ over $(0, T)$ and then use (3.9) in the resulting inequality to derive
\[
\int_{\Lambda_r(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} |\nabla p|^2 \eta^2 \frac{dxdt}{r^2} + \int_{\Lambda_r(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} (m \cdot \nabla p)^2 \eta^2 \frac{dxdt}{r^2} \leq \frac{c \delta_r^2(y)}{r^2} \int_{\Lambda_r(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n} dxdt + \frac{c \delta_r^2(y)}{r^2} \int_{\Lambda_r(y)} |m|^2 \left[ \theta_{1,L}(|m|^2) \right]^{n} dxdt + \frac{c \delta_r(y)||S(x)||_{L^2,B_r(y)}}{r^2} \int_{\Lambda_r(y)} \left[ \theta_{1,L}(|m|^2) \right]^{n+1} dxdt + c \delta_r(y)n^2 \] (3.14)

By (1.18), we can choose $r \in (0, \text{dist}(y, \partial\Omega))$ so that
\[
c \delta_r(y)n \leq \frac{1}{2}.
\] (3.15)
With this in hand, we can combine (3.9) with (3.14) to deduce

\[
\text{ess sup}_{0 \leq t \leq T} \int_{B_r(y)} |\theta_{1,L}(s)|^n \eta^2 dx \\
+ n \int_{\Lambda_r(y)} \left[ \theta_{1,L}(m^2) \right]^{n-1} |\nabla \theta_{1,L}(m^2)|^2 \eta^2 dx dt \\
\leq \frac{c\delta_r^2(y)}{r^2} \int_{\Lambda_r(y)} \left[ \theta_{1,L}(m^2) \right]^n dx dt + c \frac{r^2}{r^2} \int_{\Lambda_r(y)} \left[ \theta_{1,L}(m^2) \right]^n dx dt \\
+ \int_{B_r(y)} m^2 \eta^2 dx + \frac{c\delta_r(y)}{r^2} \int_{\Lambda_r(y)} \left[ \theta_{1,L}(m^2) \right]^{n+1} dx dt.
\]

(3.16)

Taking \( L \to \infty \) in (3.16) yields

\[
\text{ess sup}_{0 \leq t \leq T} \int_{B_r(y)} |m^{2(n+1)}| \eta^2 dx + \int_{\Lambda_r(y)} |\nabla \left( m^{n+1} \eta \right)|^2 dx dt \\
\leq c(r) \int_{\Lambda_r(y)} |m^{2(n+1)}| dx dt + c.
\]

(3.17)

Now we are in a position to apply the Gagliardo–Nirenberg–Sobolev inequality to derive

\[
\int_{Q^r(y)} |m^{2(n+1)}|^{(1+\frac{2}{N})} dx dt \\
\leq \int_{\Lambda_r(y)} \left( m^{n+1} \eta \right)^{(2+\frac{2}{N})} dx dt \\
\leq \int_0^T \left( \int_{B_r(y)} \left( m^{n+1} \eta \right)^{\frac{2N}{N-2}} dx \right)^{\frac{N-2}{2}} \left( \int_{B_r(y)} \left| m^{2(n+1)} \eta^2 \right| dx \right)^{\frac{1}{2}} dt \\
\leq \left( \text{ess sup}_{0 \leq t \leq T} \int_{B_r(y)} |m^{2(n+1)}| \eta^2 dx \right) \int_{\Lambda_r(y)} |\nabla \left( m^{n+1} \eta \right)|^2 dx dt \\
\leq \left( c(r) \int_{\Lambda_r(y)} |m^{2(n+1)}| dx dt + c \right)^{1+\frac{2}{N}} < \infty.
\]

If \( y \in \bar{\Omega} \),

the only change you need to make is that in the test function for (1.2) we substitute \( p \) for \( p - p_\omega(x,t) \). Everything else is exactly the same.

This completes the proof. \( \square \)

**Theorem 3.1** Let (H1), (A1)–(A3) be satisfied and \((p, m)\) be a weak solution of (1.1)–(1.5). Assume that \( m_0 \) is H"older continuous on \( \bar{\Omega} \).

If \( p \in L^\infty(0, T; C^\alpha(\Omega)) \) for \( \alpha \in (0, 1) \), then \( m \in \left( C^\beta(\bar{\Omega}_T) \right)^N \) for some \( \beta \in (0, 1) \).

**Proof** In view of Lemma 2.2 in [28], it is enough for us to show that there exist \( c, \beta > 0 \) such that
To this end, let \( y \) be given as in the theorem and choose a smooth cut-off function \( \eta \) as in (3.3)–(3.6). If \( \partial \Omega \cap B_r(y) = \emptyset \), then we use \((p - p_{y,r})\eta^2\) as a test function in (1.1) to obtain

\[
\int_{B_r(y)} |\nabla \eta|^2 \eta^2 \, dx + \int_{B_r(y)} (\mathbf{m} \cdot \nabla \eta)^2 \eta^2 \, dx
\]

\[
= - \int_{B_r(y)} \nabla p (p - p_{y,r}) \nabla \eta \eta \, dx - \int_{B_r(y)} (\mathbf{m} \cdot \nabla \eta) (p - p_{y,r}) \nabla \eta \eta \, dx
\]

\[
+ \int_{B_r(y)} S(x) (p - p_{y,r}) \eta^2 \, dx
\]

\[
\leq \frac{1}{2} \int_{B_r(y)} |\nabla \eta|^2 \eta^2 \, dx + \frac{1}{2} \int_{B_r(y)} (\mathbf{m} \cdot \nabla \eta)^2 \eta^2 \, dx
\]

\[
+ cr^{N-2+2s} + cr^{-2+2s} \int_{B_r(y)} |\mathbf{m}|^2 \, dx + cr^{N-2+2s} - \frac{N}{q} + s,
\]

where \( q \) is given as in (A1). This yields

\[
\int_{B_r(y)} |\nabla \eta|^2 \eta^2 \, dx + \int_{B_r(y)} (\mathbf{m} \cdot \nabla \eta)^2 \eta^2 \, dx \leq cr^{N-2+2s} + cr^{-2+2s} \int_{B_r(y)} |\mathbf{m}|^2 \, dx.
\]

(3.22)

Here without any loss of generality we have assumed that \( 2 - \frac{N}{q} \geq s \).

Theorem 1.4 together with the finite covering theorem implies that

\[
|\mathbf{m}|^2 \in L^\infty(0, T; L^q(\Omega)) \quad \text{for each } s \geq 1.
\]

(3.23)

Consequently,

\[
\int_{B_r(y)} |\mathbf{m}|^2 \, dx \leq \left( \int_{B_r(y)} |\mathbf{m}|^{2s} \, dx \right)^{\frac{1}{s}} \leq c(s)r^{\frac{N(s-1)}{s}} \quad \text{for each } s > 1.
\]

(3.24)

Use this in (3.22) to derive

\[
\int_{B_r(y)} |\nabla \eta|^2 \eta^2 \, dx + \int_{B_r(y)} (\mathbf{m} \cdot \nabla \eta)^2 \eta^2 \, dx \leq cr^{N-2+2s} + cr^{-2+2s} - \frac{N}{q}.
\]

(3.25)

Similarly,

\[
\int_{B_r(y)} |\mathbf{m}|^{2^{b-1}} \, dx \leq \left( \int_{B_r(y)} |\mathbf{m}|^{(2^{b-1})s} \, dx \right)^{\frac{1}{s}} \leq c(s)r^{\frac{N(s-1)}{s}} = cr^{N-2+2s} - \frac{N}{q}.
\]

(3.26)

Choose \( s \) so large that \( 2s - \frac{N}{q} > 0 \). Then take \( \beta = \frac{1}{2} \left( 2s - \frac{N}{q} \right) \). If \( \partial \Omega \cap B_r(y) \neq \emptyset \), we substitute \( p \) for \( p - p_{y,r}(t) \) in the test function for (1.1) and the subsequent calculations are almost identical. This completes the proof. □
It is known from [18] that $p \in L^\infty(\Omega_T)$ no matter what the space dimension is. Local boundedness estimates for $p$ turn out to be a much more delicate issue. From here on in this section we will assume $N = 2, 3$. We must impose this restriction on the space dimension in order for the Moser–De Giorgi type of arguments to work. For simplicity, we will only consider the case where

$$N = 3. \tag{3.27}$$

The other case is similar and a little bit simpler.

**Theorem 3.2** Let (H1), (A1)–(A3), and (3.27) hold and $(m, p)$ a weak solution of (1.1)–(1.5). Assume that $y \in \Omega$ satisfies (1.23) and (1.24). Then there is a $b \in (0, \dist(y, \partial \Omega))$ with

$$\omega_p(y, t) = \osc_{B_b(y)} p \leq c \rho^\beta \quad \text{for all } \rho \in (0, \dist(y, \partial \Omega)). \tag{3.28}$$

We shall adapt an idea from [25]. For this purpose we first consider subsolutions of certain homogeneous elliptic equations.

**Definition 3.3** Let $m$ be given as in (D1). We say that $v$ is a subsolution of the equation

$$-\div [(I + m \otimes m) \nabla v] = 0 \quad \text{in } \Omega \tag{3.29}$$

if:

(D5) \quad $v \in W^{1,2}(\Omega)$, $(m \cdot \nabla v) \in L^2(\Omega)$;

(D6) \quad $\int_\Omega \nabla v \nabla \xi dx + \int_\Omega (m \cdot \nabla v)(m \cdot \nabla \xi) dx \leq 0$ for all $\xi \in W^{1,2}_0(\Omega)$ with $\xi \geq 0$ and $(m \cdot \nabla \xi) \in L^2(\Omega)$.

**Claim 3.4** Assume that (3.27) holds and $m \in L^\infty(0, T; (W^{1,2}(\Omega))^3) \cap C([0, T]; (L^2(\Omega))^3)$. Let $y \in \Omega$ be such that (1.23) and (1.24) hold. If $v$ be a subsolution to (3.29), then we can find a positive number $c$ with the property

$$\esssup_{B_r(y)} v \leq c \left( \int_{B_r(y)} (v^+)^3 \right)^{\frac{1}{3}} \quad \text{for } r \in (0, \dist(y, \partial \Omega)). \tag{3.30}$$

**Proof** Fix a $r \in (0, \dist(y, \partial \Omega))$. Set

$$r = \frac{r}{2^j} + \frac{r}{2^{j+1}}, \quad j = 0, 1, 2, \ldots \tag{3.31}$$

$$k_j = k \cdot \frac{k}{2^j}, \quad j = 0, 1, 2, \ldots, \tag{3.32}$$

where $k$ is a positive number to be determined. Then choose a sequence of smooth functions $\eta_j$ so that
\[ \eta_j = 1 \quad \text{on } B_{r_{j+1}}(y), \quad (3.33) \]
\[ \eta_j = 0 \quad \text{outside } B_{r_j}(y), \quad (3.34) \]
\[ |\nabla \eta_j| \leq \frac{c2^j}{r} \quad \text{on } \mathbb{R}^N, \quad j = 0, 1, \ldots. \quad (3.35) \]

Use \((v - k_{j+1})^+ \eta_j^2\) as a test function in (3.29) to obtain

\[ \int_{B_{r_j}(y)} |\nabla (v - k_{j+1})^+|^2 \eta_j^2 dx + \int_{B_{r_j}(y)} \nabla v (v - k_{j+1})^+ 2\eta_j \nabla \eta_j dx \]
\[ + \int_{B_{r_j}(y)} (m \cdot \nabla (v - k_{j+1})^+) \eta_j^2 dx \]
\[ + \int_{B_{r_j}(y)} (m \cdot \nabla v)(v - k_{j+1})^+ 2\eta_j (m \cdot \nabla \eta_j) dx \leq 0. \quad (3.36) \]

from whence follows

\[ \int_{B_{r_j}(y)} |\nabla (v - k_{j+1})^+|^2 \eta_j^2 dx \]
\[ \leq \frac{c4^j}{r^2} \int_{B_{r_j}(y)} [(v - k_{j+1})^+]^2 dx + \frac{c4^j}{r^2} \int_{B_{r_j}(y)} |m|^2 [(v - k_{j+1})^+]^2 dx. \quad (3.37) \]

Remember that \(N = 3\). We deduce from Poincaré’s inequality that

\[ \int_{B_{r_j}(y)} |m|^2 [(v - k_{j+1})^+]^2 dx \]
\[ \leq 2 \int_{B_{r_j}(y)} |m - m_{y,r}(t)|^2 [(v - k_{j+1})^+]^2 dx \]
\[ + 2 |m_{y,r}(t)|^2 \int_{B_{r_j}(y)} [(v - k_{j+1})^+]^2 dx \]
\[ \leq 2 \left( \int_{B_{r_j}(y)} |m - m_{y,r}(t)|^6 dx \right) ^{\frac{1}{6}} \left( \int_{B_{r_j}(y)} [(v - k_{j+1})^+]^3 dx \right) ^{\frac{2}{3}} \]
\[ + 2 \left( \int_{B_{r_j}(y)} [(v - k_{j+1})^+]^2 dx \right) \]
\[ \leq \left( c \int_{B_{r_j}(y)} |\nabla m|^2 dx + cr \right) \left( \int_{B_{r_j}(y)} [(v - k_{j+1})^+]^3 dx \right) ^{\frac{2}{3}} \]
\[ \leq cr \left( \int_{B_{r_j}(y)} [(v - k_{j+1})^+]^3 dx \right) ^{\frac{2}{3}}. \quad (3.38) \]

Here we have used (1.23) and (1.24). Plug (3.38) into (3.37) to derive
\[
\int_{B_{r}(y)} |\nabla (v - k_{j+1})|^{2} \eta_{j}^{2} \, dx \leq \frac{c_{4j}}{r} \left( \int_{B_{r}(y)} [(v - k_{j+1})^{+}]^{3} \, dx \right)^{\frac{1}{3}} \tag{3.39}
\]

We compute from the Gagliardo–Nirenberg–Sobolev inequality that

\[
\left( \int_{B_{r+1}(y)} [(v - k_{j+1})^{+}]^{6} \, dx \right)^{\frac{1}{3}} \leq \left( \int_{B_{r}(y)} [(v - k_{j+1})^{+} \eta_{j}]^{6} \, dx \right)^{\frac{1}{3}} 
\leq c \int_{B_{r}(y)} |\nabla [(v - k_{j+1})^{+} \eta_{j}]|^{2} \, dx \leq c_{4j} \left( \int_{B_{r}(y)} [(v - k_{j+1})^{+}]^{3} \, dx \right)^{\frac{1}{3}} \tag{3.40}
\]

Let

\[
Y_{j} = \int_{B_{r}(y)} [(v - k_{j})^{+}]^{3} \, dx \tag{3.41}
\]

Then we have

\[
Y_{j} \geq \frac{k^{3}}{8^{j+1}} |\{ v \geq k_{j+1} \}|. \tag{3.42}
\]

We infer from (3.40) that

\[
y_{j+1} \leq \left( \int_{B_{r+1}(y)} [(v - k_{j+1})^{+}]^{6} \, dx \right)^{\frac{1}{3}} |\{ v \geq k_{j+1} \}|^{\frac{1}{3}} 
\leq \frac{c(16 \sqrt{2})^{\frac{j}{3}}}{k^{2} r^{2}} Y_{j}^{\frac{1}{3}} \tag{3.43}
\]

We are in a position to apply Lemma 2.2, from whence follows

\[
\text{ess sup}_{B_{r}(y)} v \leq k = c \left( \int_{B_{r}(y)} (v^{+})^{3} \, dx \right)^{\frac{1}{3}} \tag{3.44}
\]

\[\Box\]

**Claim 3.5** Let the assumptions of Claim 3.4 hold. If \( v \) is a weak solution of (3.29), then there exist \( c > 0, \alpha \in (0, 1) \) with the property

\[
\text{osc}_{B_{r}(y)} v \leq c (\frac{\rho}{r})^{\alpha} \text{osc}_{B_{r}(y)} v \quad \text{for all } 0 < \rho \leq r. \tag{3.45}
\]

**Proof** Let \( v, y \) be given as in the theorem. Set

\[
M(\rho) = \text{ess sup}_{B_{\rho}(y)} v, \tag{3.46}
\]

SN Partial Differential Equations and Applications
We introduce two functions due to Moser [20]:

\[ w_1 = \ln \frac{M(2\rho) - m(2\rho)}{2(M(2\rho) - v)}, \quad w_2 = \ln \frac{M(2\rho) - (2\rho)}{2(2\rho - m(2\rho))}. \]  

(3.48)

It is easy to verify that both \( w_1 \) and \( w_2 \) are subsolutions of (3.29). There are only two possibilities: either

\[ \{|w_1^+ = 0\} \cap B_\rho(y)\big| = \left\{ v \leq \frac{M(2\rho) + m(2\rho)}{2ic}\right\} \cap B_\rho(y) \geq \frac{1}{2} |B_\rho(y)|, \quad (3.49) \]

or

\[ \{|w_2^+ = 0\} \cap B_\rho(y)\big| = \left\{ v \geq \frac{M(2\rho) + m(2\rho)}{2ic}\right\} \cap B_\rho(y) \geq \frac{1}{2} |B_\rho(y)|. \quad (3.50) \]

Assume that the first possibility is in force. This puts us in a position to use formula (7.45) in [9, p. 164]. Doing so yields

\[ \int_{B_\rho(y)} |w_1^+|^2 dx \leq c\rho^2 \int_{B_\rho(y)} |\nabla w_1^+|^2 dx. \]  

(3.51)

Let \( \eta \) be a smooth cut-off function given as in (3.3)–(3.6) with \( r = 2\rho \). We use \( \frac{\eta^2}{M(2\rho) - v} \) as a test function in (3.29) to derive

\[ \int_{B_{2\rho}(y)} \frac{\eta^2}{(M(2\rho) - v)^2} |\nabla v|^2 dx + \int_{B_{2\rho}(y)} \frac{\eta^2}{(M(2\rho) - v)^2} (\mathbf{m} \cdot \nabla v)^2 dx \]

\[ = - \int_{B_{2\rho}(y)} \frac{1}{M(2\rho) - v} \nabla v^2 \eta^2 \nabla \eta dx - \int_{B_{2\rho}(y)} \frac{1}{M(2\rho) - v} (\mathbf{m} \cdot \nabla v) 2\eta \nabla \eta dx. \]  

(3.52)

It immediately follows that

\[ \int_{B_\rho(y)} |\nabla w_1|^2 dx \leq c\rho + \frac{c}{\rho^2} \int_{B_{2\rho}(y)} |\mathbf{m}|^2 dx. \]  

(3.53)

We use (1.23) and (1.24) to estimate

\[ \int_{B_{2\rho}(y)} |\mathbf{m}|^2 dx \leq 2 \int_{B_{2\rho}(y)} |\mathbf{m} - \mathbf{m}_{2\rho}(t)|^2 dx + 2 |\mathbf{m}_{2\rho}(t)|^2 \rho^3 \]

\[ \leq c\rho^2 \left( \int_{B_{2\rho}(y)} |\mathbf{m} - \mathbf{m}_{2\rho}(t)|^6 dx \right)^{\frac{1}{6}} + c\rho^3 \]  

(3.54)

\[ \leq c\rho^2 \int_{B_{2\rho}(y)} |\nabla \mathbf{m}|^2 dx + c\rho^3 \leq c\rho^3. \]

This together with (3.53) implies

\[ \int_{B_\rho(y)} |\nabla w_1|^2 dx \leq c\rho. \]  

(3.55)
We compute from Claim 3.4, (3.51), and Poincaré’s inequality that

\[
\text{ess sup}_{B_{r/2}(y)} w_1 \leq c \left( \int_{B_r(y)} (w_1^+)^3 dx \right)^{\frac{1}{3}} \\
\leq c r \left( \int_{B_r(y)} |\nabla w_1^+|^2 dx \right)^{\frac{1}{2}} + c \left( \int_{B_r(y)} (w_1^+)^2 dx \right)^{\frac{1}{2}} \leq c.
\]  

(3.56)

By the definition of \( w_1 \), we have

\[
\text{osc}_{B_{r/2}(y)} v = M(\rho/2) - m(\rho/2) \leq \left( 1 - \frac{1}{2e^c} \right) \text{osc}_{B_r(y)} v. \tag{3.57}
\]

If the second possibility holds, we use \( w_2 \) instead and everything else is the same. Our theorem follows from Lemma 8.23 in [9, p. 201].

We are ready to prove Theorem 3.2.

**Proof of Theorem 3.2**  Let \( y \) be given as in the theorem. Fix a \( r \in (0, \text{dist}(y, \partial \Omega)) \). We decompose \( p \) into two functions \( v \) and \( u \) on \( B_r(y) \), where \( v \) is the weak solution of the boundary value problem

\[
-\text{div}[(I + m \otimes m) \nabla v] = 0 \quad \text{in } B_r(y),
\]

\[
v = p \quad \text{on } \partial B_r(y),
\]

and \( u = p - v \). Obviously, \( u \) satisfies

\[
-\text{div}[(I + m \otimes m) \nabla u] = S(x) \quad \text{in } B_r(y),
\]

\[
u = 0 \quad \text{on } \partial B_r(y).
\]

As a result, we can apply Proposition 2.1 in [18] to the above problem.

This yields

\[
\text{ess sup}_{B_r(y)} |u| \leq cr^{\frac{1}{q}-\frac{1}{2}} \left( \int_{B_r(y)} |S(x)|^q dx \right)^{\frac{1}{q}}. \tag{3.62}
\]

Obviously, we can apply Claim 3.5 to \( v \). Keeping this in mind, we calculate for \( \rho \in (0, r) \) that
The theorem follows from Lemma 2.1 in [8, p. 86]. □

**Proof of Theorem 1.5** Let \( y \in \Omega \) be given as in the theorem. Then Theorem 3.2 holds, and so does Theorem 1.4. To establish Theorem 1.5, it is enough for us to show that there is a positive number \( b \) such that

\[
\int_{Q_r(z)} |m - m_{c,r}|^2 dx dt \leq cr^{2\beta} \text{ for } r \text{ sufficiently small,}
\]  
(3.64)

where \( z = (y, \tau) \). Indeed, if the above inequality holds, we can infer from the proof of Theorem 1.2 in [8, p. 70] that

\[
\limsup_{r \to 0} |m_{c,r}| < \infty.
\]  
(3.65)

This together with Theorem 3.2 and (3.64) implies (1.14).

We can further weaken (3.64). In fact, we only need to show that there is a \( \sigma \in (0, 1) \) such that

\[
\int_{Q_r(z)} |m - m_{c,r}|^{1+\sigma} dx dt \leq cr^{2\beta} \text{ for } r \text{ sufficiently small.}
\]  
(3.66)

This is due to the following estimate

\[
\int_{Q_r(z)} |m - m_{c,r}|^2 dx dt \leq \left( \int_{Q_r(z)} |m - m_{c,r}|^{1+\sigma} dx dt \right)^{\frac{1}{1+\sigma}} \left( \int_{Q_r(z)} |m - m_{c,r}|^{1+\sigma} dx dt \right)^{\frac{\sigma}{1+\sigma}}
\]  
(3.67)

In view of Theorem 1.4, we can choose \( \sigma > 0, r > 0 \) so small that

\[
\frac{2\beta}{1+\sigma} - \frac{3\sigma}{1+\sigma} > 0 \quad \text{and} \quad \int_{Q_r(z)} |m|^{\frac{1+\sigma}{\sigma-\beta}} dx dt < \infty.
\]  
(3.68)

To prove (3.66), we pick a \( r > 0 \) so that \( Q_{2r}(z) \subset \Omega_T \). We decompose \( m \) on \( Q_r(z) \) as follows: Solve the linear problem

\[
\partial_t w - D^2 \Delta w = 0 \quad \text{in } Q_r(z),
\]  
(3.69)
We proceed to estimate \( \mathbf{n} \). Let \( \mathbf{n} = \mathbf{m} - \mathbf{w} \). Denote by \( n_i \) the \( i \)-th component of \( \mathbf{n} \). Then \( n_i \) satisfies

\[
\partial_t n_i - D^2 \Delta n_i = E^2 (\mathbf{m} \cdot \nabla p) \partial_x p - |\mathbf{m}|^{2\gamma - 2} m_i \quad \text{in } Q_t(z),
\]

\[
n_i = 0 \quad \text{on } \partial_p Q_t(z)
\]

(3.71)

By slightly modifying the proof of Claim 1 in [24], we conclude that there exist \( c > 0 \), \( \delta \in (0, 1) \) depending only on \( D, \sigma \) such that

\[
\int_{Q_t(z)} |\mathbf{w} - \mathbf{w}_{\varepsilon, \rho}|^{1+\sigma} \, dx \, dt \leq c \left( \frac{p}{r} \right)^{5+\delta} \int_{Q_t(z)} |\mathbf{w} - \mathbf{w}_{\varepsilon, \rho}|^{1+\sigma} \, dx \, dt \quad \text{for all } 0 < \rho \leq r.
\]

(3.73)

We proceed to estimate \( \mathbf{n} \). Theorem 3.2 combined with Theorem 1.4 and the proof of Theorem 3.1 implies that (3.25) still holds. With this in mind, we use \( \theta_{-L,L}(n_i) \) as a test function in (3.71) to obtain

\[
\max_{t \in [\tau - r^2/2, \tau + r^2/2]} \int_{B_r(z)} \theta_{-L,L}(s) \, ds \, dx + D^2 \int_{Q_t(z)} |\nabla \theta_{-L,L}(n_i)|^2 \, dx \, dt \\
\leq cL \int_{\tau - r^2/2}^{\tau + r^2/2} \int_{B_r(z)} |(\mathbf{m} \cdot \nabla p)| |\nabla p| \, dx \, dt + cL \int_{\tau - r^2/2}^{\tau + r^2/2} \int_{B_r(z)} |\mathbf{m}|^{2\gamma - 1} \, dx \\
\leq cL r^{3+2\beta} \quad \text{for some } \beta > 0 \text{ and } r \text{ suitably small.}
\]

(3.74)

We calculate from the Gagliardo–Nirenberg–Sobolev inequality that

\[
\int_{\tau - r^2/2}^{\tau + r^2/2} \int_{B_r(z)} |\theta_{-L,L}(n_i)|^{2+4\gamma} \, dx \, dt \\
\leq \int_{\tau - r^2/2}^{\tau + r^2/2} \left( \int_{B_r(z)} |\theta_{-L,L}(n_i)|^6 \, dx \right)^{\frac{1}{3}} \left( \int_{B_r(z)} |\theta_{-L,L}(n_i)|^2 \, dx \right)^{\frac{1}{3}} \, dt \\
\leq c \left( \max_{t \in [\tau - r^2/2, \tau + r^2/2]} \int_{B_r(z)} |\theta_{-L,L}(n_i)|^2 \, dx \right)^{\frac{3}{5}} \int_{Q_t(z)} |\nabla \theta_{-L,L}(n_i)|^2 \, dx \\
\leq c L^{5 \left( \frac{5(3+2\beta)}{5(3+2\beta)} \right)} \frac{5(3+2\beta)}{L^2},
\]

from whence follows

\[
|\{ |n_i| \geq L \}| \leq c L^{5 \left( \frac{5(3+2\beta)}{5(3+2\beta)} \right)} \frac{5(3+2\beta)}{L^2}. \]

(3.76)

We infer from (2.2) that

\[
\int_{Q_t(z)} |\mathbf{n}|^{\frac{5}{2} - \varepsilon} \leq \frac{c}{\varepsilon} r^{5+2\beta(\frac{5}{2} - \varepsilon)}, \quad \varepsilon \in (0, \frac{2}{3}).
\]

(3.77)

We pick an \( \varepsilon \) so that
For 0 < \rho \leq r we calculate

\[
\int_{Q_r(\varepsilon)} |\mathbf{m} - \mathbf{m}_{\varepsilon, \rho}|^{1+\sigma} \, dx \, dt \\
\leq c \int_{Q_r(\varepsilon)} |\mathbf{w} - \mathbf{w}_{\varepsilon, r}|^{1+\sigma} \, dx \, dt + c \int_{Q_r(\varepsilon)} |\mathbf{n} - \mathbf{n}_{\varepsilon, \rho}|^{1+\sigma} \, dx \, dt
\]

\leq c \left( \frac{\rho}{r} \right)^{5+\delta} \int_{Q_r(\varepsilon)} |\mathbf{w} - \mathbf{w}_{\varepsilon, r}|^{1+\sigma} \, dx \, dt + c \int_{Q_r(\varepsilon)} |\mathbf{n}|^{1+\sigma} \, dx \, dt

\leq c \left( \frac{\rho}{r} \right)^{5+\delta} \int_{Q_r(\varepsilon)} |\mathbf{m} - \mathbf{m}_{\varepsilon, r}|^{1+\sigma} \, dx \, dt + r^{5+2\beta(1+\sigma)}.
\tag{3.79}
\]

We conclude (3.66) from Lemma 2.1 from [8, p. 86]. The proof is complete. \hfill \square

4 Proof of Theorems 1.7 and 1.8

Proof of Theorem 1.7 For each \varepsilon > 0 we define

\[
[m]_\varepsilon = (\theta_{-\varepsilon, \varepsilon}(m_1), \ldots, \theta_{-\varepsilon, \varepsilon}(m_N))^T.
\tag{4.1}
\]

Then we have

\[
\mathbf{m}_0 + [\mathbf{m} - \mathbf{m}_0]_\varepsilon = \mathbf{m} \text{ on the set where } |\mathbf{m} - \mathbf{m}_0| \leq \varepsilon.
\tag{4.2}
\]

Replace \mathbf{m} by \mathbf{m}_0 + [\mathbf{m} - \mathbf{m}_0]_\varepsilon in (1.1) and write the resulting equation in the form

\[
-\text{div}[(I + \mathbf{m}_0 \otimes \mathbf{m}_0)\nabla p] = \text{div}(\mathbf{m}_0 \otimes [\mathbf{m} - \mathbf{m}_0]_\varepsilon \nabla p) + \text{div}([\mathbf{m} - \mathbf{m}_0]_\varepsilon \otimes \mathbf{m}_0 \nabla p) + \text{div}([\mathbf{m} - \mathbf{m}_0]_\varepsilon \otimes [\mathbf{m} - \mathbf{m}_0]_\varepsilon \nabla p) + S(x) \text{ in } \Omega_T.
\tag{4.3}
\]

Claim 4.1 If \varepsilon is sufficiently small, then (4.3) coupled with (1.3)–(1.5) has a weak solution satisfying (D4).

Proof A solution will be constructed via the Leray–Schauder theorem [9, p. 280]. For this purpose we define an operator \mathcal{B} from \(L^\infty(\Omega_T))^N\ into itself as follows: For each \mathbf{m} \in (L^\infty(\Omega_T))^N we say \mathcal{B}(\mathbf{m}) = \mathbf{w} if \mathbf{w} is the unique solution of the initial boundary value problem

\[
\partial_t \mathbf{w} - D^2 \Delta \mathbf{w} = E^2((\mathbf{m}_0 + [\mathbf{m} - \mathbf{m}_0]_\varepsilon) \cdot \nabla p) \nabla p - |\mathbf{m}|^{2(\gamma-1)} \mathbf{m} \text{ in } \Omega_T,
\tag{4.4}
\]

\[
\mathbf{w} = 0 \text{ on } \Sigma_T,
\tag{4.5}
\]

\[
\mathbf{w}(x, 0) = \mathbf{m}_0(x) \text{ on } \Omega,
\tag{4.6}
\]

where \(p\) solves (4.3) coupled with (1.3). The latter problem has a unique solution if \varepsilon is
sufficiently small. To see this, first observe that the elliptic coefficients on the left-hand side of (4.3) are continuous. Therefore, we are in a position to apply Lemma 2.5, from whence follows that for each \( q > 1 \) there is a positive number \( c \) determined only by \( q, m_0, N \), and \( \Omega \) such that
\[
\| \nabla p \|_{q, \Omega} \leq c \| g_e \otimes m_0 \nabla p \|_{q, \Omega} + c \| g_e \otimes g_e \nabla p \|_{q, \Omega} + c \| S(x) \|_{q, \Omega} \leq c(\varepsilon + \varepsilon^2)\| \nabla p \|_{q, \Omega} + c.
\]
(4.7)

Now fix a \( q > 2(1 + \frac{N}{2}) \). We have
\[
\| \nabla p \|_q \leq c
\]
if we choose \( \varepsilon \) so that the coefficient \( c(\varepsilon + \varepsilon^2) \) in (4.7) is strictly less than 1. From here on we assume that this is the case. Subsequently, Lemma 2.4 becomes applicable to (4.4). Upon using it, we obtain that \( w \) is Hölder continuous on \( X_T \). Therefore, we can claim that \( B \) is well-defined, continuous, and precompact. It remains to be seen that there is a positive number \( c \) such that
\[
\| m \|_{\infty, \Omega_T} \leq c
\]
for all \( m \in (L^\infty(\Omega_T)) \) and \( \sigma \in (0, 1] \) satisfying
\[
m = \sigma B(m).
\]
This equation is equivalent to the following problem
\[
-\text{div}[(I + m_0 \otimes m_0) \nabla p] = \text{div}(m_0 \otimes [m - m_0]_e \nabla p) + \text{div}([m - m_0]_e \otimes m_0 \nabla p) + \text{div}([m - m_0]_e \otimes [m - m_0]_e \nabla p) + S(x) \text{ in } \Omega_T,
\]
\[
\partial_t m - D^2 \Delta m = E^2 \sigma((m_0 + [m - m_0]_e) \cdot \nabla p) \nabla p - \sigma|m|^{2(\sigma - 1)} m \text{ in } \Omega_T,
\]
\[
m = 0 \text{ on } \Sigma_T,
\]
\[
p = 0 \text{ on } \Sigma_T,
\]
\[
m(x, 0) = \sigma m_0(x) \text{ on } \Omega.
\]
(4.10)

(4.11)
(4.12)
(4.13)
(4.14)

We still have (4.8). As a result, the right-hand side of (4.11) is bounded in \( L^2(\Omega_T) \). Recall that \( \frac{q}{2} > 1 + \frac{N}{2} \). Hence (4.9) follows from Lemma 2.4. This completes the proof of the claim.

To continue the proof of Theorem 1.7, by the Hölder continuity of \( m \) on \( \overline{\Omega_T} \), we can find a positive number \( T_0 \leq T \) such that
\[
|m(x, t) - m_0(x)| \leq c\varepsilon^2 \leq \varepsilon \text{ on } \Omega_{T_0},
\]
where \( \varepsilon \) is the Hölder exponent of \( m \). We see from (4.2) that (4.3) reduces to (1.1) on \( \Omega_{T_0} \), where (D4)' holds true.
The proof is complete. □

**Proof of Theorem 1.8** Fix $T > 0$. We construct a sequence of functions $\{(w_k, p_k)\}$ on $\Omega_T$ as follows: Set

$$w_0 = m_0.$$ The function $p_0$ is the unique solution of the boundary value problem

$$-\text{div}[(I + m_0 \otimes m_0)\nabla p_0] = S(x) \quad \text{in } \Omega, \quad (4.15)$$

$$p_0 = 0 \quad \text{on } \partial \Omega. \quad (4.16)$$

Suppose that $w_{k-1}$, $p_{k-1}$, $k = 1, 2, \ldots$, are known. We define $p_k$ to be the unique solution of the boundary value problem

$$-\Delta p_k = \text{div}[(w_{k-1} \cdot \nabla p_{k-1})w_{k-1}] - \Delta p_0 - \text{div}[(m_0 \cdot \nabla p_0)m_0] \quad \text{in } \Omega_T, \quad (4.17)$$

$$p_k = 0 \quad \text{on } \Sigma_T, \quad (4.18)$$

while $w_k$ solves the problem

$$\partial_t w_k - D^2\Delta w_k + |w_k|^{2(n-1)}w_k = E^2(w_{k-1} \cdot \nabla p_{k-1})\nabla p_{k-1} \quad \text{in } \Omega_T, \quad (4.19)$$

$$w_k = 0 \quad \text{on } \Sigma_T, \quad (4.20)$$

$$w_k(x, 0) = m_0(x) \quad \text{on } \Omega. \quad (4.21)$$

The uniqueness of a solution to the preceding problem can easily be inferred from Lemma 2.1. Obviously, if $\{(w_{k-1}, p_{k-1})\}$ satisfies (D4), so does $\{(w_k, p_k)\}$. The sequence $\{(w_k, p_k)\}$ is well-defined.

It follows from Lemma 2.6 that there is a positive number $c = c(N, \Omega)$ with

$$a_k \equiv \|w_k\|_{\infty, \Omega_T} \leq c\left(\|m_0\|_{\infty, \Omega} + T^{\frac{1}{2n}} \sup_{0 \leq t \leq T} \||w_{k-1}||\nabla p_{k-1}|^2\|_{N, \Omega}\right) \quad (4.22)$$

$$\leq c\|m_0\|_{\infty, \Omega} + cT^{\frac{1}{2n}}a_{k-1}b_{k-1}^2,$$

where

$$b_k = \sup_{0 \leq t \leq T} \|\nabla p_k\|_{2N, \Omega}.$$ 

On the other hand, we can deduce from Lemma 2.5 that there is a positive number $c = c(N, \Omega)$ such that

$$\|\nabla p_k\|_{2N, \Omega} \leq c\|w_{k-1}\|_{\infty, \Omega}^2 \|\nabla p_{k-1}\|_{2N, \Omega} + c\|\nabla p_0\|_{2N, \Omega}.$$ 

It immediately follows

$$b_k \leq c a_{k-1}^2 b_{k-1} + c\|\nabla p_0\|_{2N, \Omega}. \quad (4.23)$$
Define
\[ d_k = a_k + b_k. \]

Adding (4.23) to (4.22), we derive
\[ d_k \leq c\left(1 + T^{\frac{1}{\alpha}}\right)d_{k-1}^2 + cd_0. \]  
(4.24)

Observe from (4.15)–(4.16) that
\[ \| \nabla p_0 \|_{2\gamma, \Omega} \leq c\| S(x) \|_{\mathcal{F}, \Omega}. \]

In view of Lemma 2.3, if
\[ c d_0^2 \left(1 + T^{\frac{1}{\alpha}}\right) \leq c \left(\| m_0 \|_{\infty, \Omega} + \| S(x) \|_{\mathcal{F}, \Omega}\right)^2 \left(1 + T^{\frac{1}{\alpha}}\right) < 1 \]
then
\[ d_k = \| w_k \|_{\infty, \Omega} + \sup_{0 \leq t \leq \tau} \| \nabla p_k \|_{2\gamma, \Omega} \leq c \left(\| m_0 \|_{\infty, \Omega} + \| S(x) \|_{\mathcal{F}, \Omega}\right) = C_0. \]  
(4.25)

We must show that the whole sequence \{w_k, p_k\} converges in a suitable sense. To this end, we conclude from (4.19) that
\[ \tilde{c}_t(w_k - w_{k-1}) - D^2\Delta (w_k - w_{k-1}) + |w_k|^{2(\gamma-1)}w_k - |w_{k-1}|^{2(\gamma-1)}w_{k-1} = E^2[(w_{k-1} \cdot \nabla p_{k-1})\nabla p_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})\nabla p_{k-2}] \text{ in } \Omega_T, \]  
(4.26)

By Lemma 2.1, we have
\[ \left( |w_k|^{2(\gamma-1)}w_k - |w_{k-1}|^{2(\gamma-1)}w_{k-1} \right) \cdot (w_k - w_{k-1}) \geq 0. \]

Use \( w_k - w_{k-1} \) as a test function in (4.26) and keep the above inequality and (4.25) in mind to derive
\[ \frac{1}{2} \frac{d}{dt} \int_{\Omega} |w_k - w_{k-1}|^2 dx + D^2 \int_{\Omega} |\nabla (w_k - w_{k-1})|^2 dx \]
\[ \leq E^2 \int_{\Omega} [(w_{k-1} \cdot \nabla p_{k-1})\nabla p_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})\nabla p_{k-2}] (w_k - w_{k-1}) dx \]
\[ \leq c \left( \int_{\Omega} [(w_{k-1} \cdot \nabla p_{k-1})\nabla p_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})\nabla p_{k-2}]^{\frac{2\gamma}{\gamma-1}} dx \right)^{\frac{\gamma-1}{2}} \]
\[ + \frac{D^2}{2} \int_{\Omega} |\nabla (w_k - w_{k-1})|^2 dx. \]  
(4.27)

We write
\[ (w_{k-1} \cdot \nabla p_{k-1})\nabla p_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})\nabla p_{k-2} \]
\[ = (w_{k-1} - w_{k-2}) \cdot \nabla p_{k-1} + (w_{k-2} \cdot (\nabla p_{k-1} - \nabla p_{k-2}))\nabla p_{k-1} \]
\[ + (w_{k-2} \cdot \nabla p_{k-2})(\nabla p_{k-1} - \nabla p_{k-2}). \]  
(4.28)
Use this in (4.27) to obtain
\[
\frac{d}{dt} \int_{\Omega} |w_k - w_{k-1}|^2 \, dx + \int_{\Omega} |\nabla (w_k - w_{k-1})|^2 \, dx
\leq c \left( \int_{\Omega} |w_{k-1} - w_{k-2}|^{2N} \, dx \right)^{\frac{q+1}{2q}} \left( \int_{\Omega} |\nabla p_{k-1}|^N \, dx \right)^{\frac{q}{2}}
+ c \|w_{k-2}\|_{\infty, \Omega_r}^2 \left( \|\nabla p_{k-1}\|_{L^2(N, \Omega)}^2 + \|\nabla p_{k-2}\|_{L^2(N, \Omega)}^2 \right) \cdot \left( \int_{\Omega} |\nabla p_{k-1} - \nabla p_{k-2}|^{2N} \, dx \right)^{\frac{q+1}{2q}}
\leq c C_0^4 \left( \int_{\Omega} |\nabla (w_{k-1} - w_{k-2})|^2 \, dx + \int_{\Omega} |\nabla p_{k-1} - \nabla p_{k-2}|^2 \, dx \right). \tag{4.29}
\]

By (4.17), we have
\[
- \Delta(p_k - p_{k-1}) = \operatorname{div}[(w_{k-1} \cdot \nabla p_{k-1})w_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})w_{k-2}] \quad \text{in } \Omega_T, \tag{4.30}
\]
\[
k = 2, 3, \ldots.
\]

Upon using \(p_k - p_{k-1}\) as a test function in the above equation, we arrive at
\[
\int_{\Omega} |\nabla (p_k - p_{k-1})|^2 \, dx
\leq \int_{\Omega} |(w_{k-1} \cdot \nabla p_{k-1})w_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})w_{k-2}| \, dx
\leq \frac{1}{2} \int_{\Omega} |(w_{k-1} \cdot \nabla p_{k-1})w_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})w_{k-2}|^2 \, dx
+ \frac{1}{2} \int_{\Omega} |\nabla (p_k - p_{k-1})|^2 \, dx. \tag{4.31}
\]

We represent
\[
(w_{k-1} \cdot \nabla p_{k-1})w_{k-1} - (w_{k-2} \cdot \nabla p_{k-2})w_{k-2} = ((w_{k-1} - w_{k-2}) \cdot \nabla p_{k-1})w_{k-1} + (w_{k-2} \cdot (\nabla p_{k-1} - \nabla p_{k-2}))w_{k-1}
+ (w_{k-2} \cdot \nabla p_{k-2})(w_{k-1} - w_{k-2}). \tag{4.32}
\]

We calculate
\[
\int_{\Omega} |((w_{k-1} - w_{k-2}) \cdot \nabla p_{k-1})w_{k-1}|^2 \, dx
\leq \|w_{k-1}\|_{\infty, \Omega_r}^2 \left( \int_{\Omega} |w_{k-1} - w_{k-2}|^{2N} \, dx \right)^{\frac{q+1}{2q}} \left( \int_{\Omega} |\nabla p_{k-1}|^{N} \, dx \right)^{\frac{q}{2}} \tag{4.33}
\leq c C_0^4 \int_{\Omega} |\nabla (w_{k-1} - w_{k-2})|^2 \, dx.
\]

Similarly, we have
\[
\int_{\Omega} |(w_{k-2} \cdot \nabla p_{k-2})(w_{k-1} - w_{k-2})|^2 \, dx \leq c C_0^4 \int_{\Omega} |\nabla (w_{k-1} - w_{k-2})|^2 \, dx. \tag{4.34}
\]
Plug the preceding estimates into (4.31) to derive
\[ \int_{\Omega} \left| \nabla (p_k - p_{k-1}) \right|^2 dx \leq c C_0^4 \left( \int_{\Omega} \left| \nabla (w_{k-1} - w_{k-2}) \right|^2 dx + \int_{\Omega} \left| \nabla p_{k-1} - \nabla p_{k-2} \right|^2 dx \right). \] (4.35)

Let
\[ \eta_k = \int_{\Omega} \left| \nabla (w_k - w_{k-1}) \right|^2 dx dt + \int_{\Omega} \left| \nabla p_k - \nabla p_{k-1} \right|^2 dx dt. \] (4.36)

Add (4.35) to (4.29) and integrate the resulting equation over \((0, T)\) to yield
\[ \eta_k \leq c C_0^4 \eta_{k-1}. \] (4.37)

This implies
\[ \eta_k \leq (c C_0^4)^{k-1} \eta_1. \] (4.38)

Hence if
\[ c C_0^4 < 1, \] (4.39)

then the two series’s
\[ \nabla w_0 + \nabla w_1 - \nabla w_0 + \cdots + \nabla w_k - \nabla w_{k-1} + \cdots \] and
\[ \nabla p_0 + \nabla p_1 - \nabla p_0 + \cdots + \nabla p_k - \nabla p_{k-1} + \cdots \] (4.40) (4.41)

converge in \(L^2(0, T; (W^{1,2}(\Omega))^N)\) and \(L^2(0, T; (W^{1,2}(\Omega)))\), respectively.

It immediately follows that the two sequences \(\{w_k\}\) and \(\{p_k\}\) also converge in \(L^2(0, T; (W^{1,2}(\Omega))^N)\) and \(L^2(0, T; W^{1,2}(\Omega))\), respectively. We can also deduce from (4.25) and Lemma 2.4 that \(\{w_k\}\) is uniformly convergent on \(\bar{\Omega}_T\). We can let \(k \to \infty\) in (4.17) and (4.19). Note from (4.25) that (4.39) is valid if we make the term \(\|m_0\|_{\infty, \Omega} + \|S(x)\|_{L^\infty, \Omega}\) suitably small. The proof is complete.

**References**

1. Albi, G., Artina, M., Fornasier, M., Markowich, P.: Biological transportation networks: modeling and simulation. Anal. Appl. (Singap.) **14**, 185–206 (2016)
2. Albi, G., Burger, M., Haskovee, J., Markowich, P., Schlottbom, M.: Continuum modeling of biological network formulation. In: Bellomo, N., Degond, P., Tamdor, E. (eds.), Active Particles Vol. I—Theory, Models, Applications, Series: Modelling and Simulation in Science and Technology. Birkhäuser-Springer, Boston (2017)
3. Benilan, P., Brezis, H., Crandall, M.C.: A semilinear equation in \(L^1(\mathbb{R}^N)\). Ann. Scuola Norm. Sup. Pisa Cl. Sci. **2**, 523–555 (1975)
4. De Giorgi, E.: Congetture sulla continuità delle soluzioni di equazioni lineari ellittiche autoaggiunte a coefficienti illimitati, Unpublished (1995)
5. DiBenedetto, E.: Degenerate Parabolic Equations. Springer, New York (1993)
6. Evans, L.C., Gariepy, R.F.: Measure Theory and Fine Properties of Functions. CRC Press, Boca Raton (1992)
7. Galaktionov, V.A., Pohozaev, S.I.: Existence and blow-up for higher-order semilinear parabolic equations: majorizing order-preserving operators. Indiana Univ. Math. J. 51, 1321–1338 (2002)
8. Gianquinta, M.: Multiple Integrals in the Calculus of Variations and Nonlinear Elliptic Systems. Princeton University Press, Princeton (1983)
9. Gilbarg, D., Trudinger, N.S.: Elliptic Partial Differential Equations of Second Order. Springer, Berlin (1983)
10. Haskovec, J., Markowich, P., Perthame, B.: Mathematical analysis of a PDE system for biological network formulation. Commun. Partial Differ. Equ. 40, 918–956 (2015)
11. Haskovec, J., Markowich, P., Perthame, B., Schlottbom, M.: Notes on a PDE system for biological network formulation. Nonlinear Anal. 138, 127–155 (2016)
12. Heinonen, J., Kilpeläinen, T., Martio, O.: Nonlinear Potential Theory of Degenerate Elliptic Equations, Oxford Mathematical Monographs. Clarendon Press, Oxford (1993)
13. Hu, D.: Optimization, adaptation, and initialization of biological transport networks. Workshop on multi scale problems from physics, biology, and material sciences, May 28–31, Shanghai (2014)
14. Hu, D., Cai, D.: Adaptation and optimization of biological transport networks. Phys. Rev. Lett. 111, 138701 (2013)
15. Krylov, N.V.: Lectures on Elliptic and Parabolic Equations in Hölder Soaces, Graduate Studies in Math., vol. 12. AMS, Providence (1991)
16. Ladyzenskaja, O.A., Solonnikov, V.A., Ural’ceva, N.N.: Linear and Quasi-linear Equations of Parabolic Type, Tran. Math. Monographs, vol. 23. AMS, Providence (1968)
17. Li, B.: On the blow-up criterion and global existence of a nonlinear PDE system in biological transport networks. Kinet. Relat. Models 12, 1131–1162 (2019)
18. Liu, J.-G., Xu, X.: Partial regularity of weak solutions to a PDE system with cubic nonlinearity. J. Differ. Equ. 264, 5489–5526 (2018)
19. Meyers, N.G.: An $L^p$ estimate for the gradient of solution of second order elliptic divergence equations. Ann. Scuola Norm. Pisa III(17), 189–206 (1963)
20. Moser, J.: A new proof of De Giorgi’s theorem concerning the regularity problem for elliptic differential equations. Commun. Pure Appl. Math. 13, 457–468 (1960)
21. Oden, J.T.: Qualitative Methods in Nonlinear Mechanics. Prentice-Hall Inc, New Jersey (1986)
22. Omminen, J., Zhong, X.: Continuity of solutions of linear, degenerate elliptic equations. Ann. Scuola Norm. Sup. Pisa Cl. Sci. (5) 6, 103–116 (2007)
23. Rodrigues, J. R.: Obstacle Problems in Mathematical Physics, North-Holland Math. Studies, vol. 134. North-Holland, Amsterdam (1987)
24. Xu, X.: Partial regularity of solutions to a class of degenerate systems. Trans. Am. Math. Soc. 349, 1973–1992 (1997)
25. Xu, X.: A local partial regularity theorem for weak solutions of degenerate elliptic equations and its application to the thermistor problem. Differ. Integ. Equ. 12, 83–100 (1999)
26. Xu, X.: Regularity theorems for a biological network formulation model in two space dimensions. Kinet. Relat. Models 11, 397–408 (2018)
27. Xu, X.: Global existence of strong solutions to a biological network formulation model in 2 + 1 dimensions. Discrete Contin. Dyn. Syst. Ser. A. arXiv:1911.01970v2 [math.AP] (2019) (to appear)
28. Yuan, G.: Regularity of solutions of the thermistor problem. Appl. Anal. 53, 149–157 (1994)