Some sample path properties of $G$-Brownian motion

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Abstract

In this paper, we shall study the basic absolute properties of $G$-Brownian motion, i.e., those properties which hold for q.s. $\omega$. These include the characterization of the zero set and the local maxima of the $G$-Brownian motion paths. The key ingredient of our approach is an estimate of solutions to $G$-heat equations. We also show that the $G$-Brownian path is nowhere locally Hölder continuous of order $\gamma$ for any $\gamma > \frac{1}{2}$.

Keywords: $G$-Brownian motion, sample path properties.

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1 Introduction

Brownian motion was rigorously constructed to model the random walk of pollen particles in a liquid. After decades of development, Kac [3] established the connection between the expectations of stochastic functionals and the solutions of partial differential equations (PDEs for short), which is the famous Feynman-Kac formula. Impressed by this bridging relationship, Peng introduced the $G$-expectation theory (see [10, 11, 12]) through the following $G$-heat equation:

$$\partial_t u(t, x) - G(\partial^2_{xx} u(t, x)) = 0.$$ 

Almost immediately, the notion of $G$-Brownian motion and the corresponding stochastic calculus of Itô’s type were also established. For a detailed account and recent development of this theory we refer the reader to [2, 6, 9].

One important feature of $G$-expectation theory is that, the random variables are obliged to be quasi-continuous to be in $L^1_G(\Omega)$ from [1]. So one has to be careful when dealing with issues involving integrability, stopping times etc. Since the indicator functions of Borel sets are of priority in Lebesgue integration theory, an interesting question is whether the indication functions are in $L^1_G(\Omega)$.

In this paper, we shall prove the set \( \{ \omega : B_t = a \} \) is a polar set for each $t > 0$ and $a \in \mathbb{R}$. The proof is base on an estimate of solutions to $G$-heat equations, which is a useful tool for the study of $G$-expectation. In particular, we obtain that the indicator function $1_{B_t \in O} \in L^1_G(\Omega_t)$, where $O$ is some “regular” Borel set of $\mathbb{R}$. Moreover, for q.s. $\omega$, the $G$-Brownian motion path is monotonic in no time interval and the set of local maximum points for $G$-Brownian motion is dense. In addition, the $G$-Brownian path is nowhere locally Hölder continuous of order $\gamma$ for any $\gamma > \frac{1}{2}$ as the classical case.

This paper is organized as follow. In section 2, we recall some necessary notations and results of $G$-expectation theory. In section 3, we state our main results and some applications are given.

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2 Preliminaries

The main purpose of this section is to recall some preliminary results in G-framework which are needed in the sequel. More details can be found in Denis et al [1] and Peng [12].

Let \( \Omega = C_0(\mathbb{R}^+) \) be the space of all \( \mathbb{R} \)-valued continuous paths \((\omega_t)_{t \geq 0}\), with \( \omega_0 = 0 \), equipped with the distance

\[
\rho(\omega^1, \omega^2) := \sum_{i=1}^{\infty} 2^{-i} \left( \max_{t \in [0,i]} |\omega^1_t - \omega^2_t| \right) \wedge 1.
\]

Denote by \( \mathcal{B}(\Omega) \) the Borel \( \sigma \)-algebra of \( \Omega \). For each \( t \in [0, \infty) \), we also introduce the following spaces.

- \( \Omega_t := \{ \omega(\cdot \wedge t) : \omega \in \Omega \} \), \( \mathcal{F}_t := \mathcal{B}(\Omega_t) \),
- \( L^0(\Omega) := \text{the space of all } \mathcal{B}(\Omega)-\text{measurable real functions} \),
- \( L^0(\Omega_t) := \text{the space of all } \mathcal{F}_t-\text{measurable real functions} \),
- \( C_b(\Omega) := \text{all continuous bounded elements in } L^0(\Omega) \),
- \( C_b(\Omega_t) := C_b(\Omega) \cap L^0(\Omega_t) \).

In Peng [12], a G-Brownian motion is constructed on a sublinear expectation space \((\Omega, \mathbb{L}^1_G, \hat{\mathbb{E}}, (\hat{\mathbb{E}}_t)_{t \geq 0})\), where \( \mathbb{L}^p_G(\Omega) \) is a Banach space under the natural norm \( \|X\|_p = \hat{\mathbb{E}}[|X|^p]^{1/p} \). In this space the corresponding canonical process \( B_t(\omega) = \omega_t \) is a G-Brownian motion. Denis et al. [1] proved that \( L^0(\Omega) \supset L^p_G(\Omega) \supset C_b(\Omega) \) and there exists a weakly compact family \( \mathcal{P} \) of probability measures defined on \((\Omega, \mathcal{B}(\Omega))\) such that

\[
\hat{\mathbb{E}}[X] = \sup_{P \in \mathcal{P}} E_P[X], \quad X \in L^1_G(\Omega).
\]

Remark 2.1 Denis et al. [1] gave a concrete set \( \mathcal{P}_M \) that represents \( \hat{\mathbb{E}} \). Consider a 1-dimensional Brownian motion \( W_t \) on \((\Omega, \mathcal{F}, \mathbb{P})\), then

\[
\mathcal{P}_M := \{ P_\theta : P_\theta = P \circ X^{-1}, \quad X_t = \int_0^t \theta_s dW_s, \quad \theta \in L^2_F([0,T]; [\sigma^2, \sigma^2]) \}
\]

is a set that represents \( \hat{\mathbb{E}} \), where \( L^2_F([0,T]; [\sigma^2, \sigma^2]) \) is the collection of all \( \mathcal{F} \)-adapted measurable processes with \( \sigma^2 \leq |\theta_s|^2 \leq \sigma^2 \).

Now we introduce the Choquet capacity:

\[
c(A) := \sup_{P \in \mathcal{P}} P(A), \quad A \in \mathcal{B}(\Omega).
\]

Definition 2.2 A set \( A \subset \mathcal{B}(\Omega) \) is polar if \( c(A) = 0 \). A property holds “quasi-surely” (q.s.) if it holds outside a polar set.

Definition 2.3 A real function \( X \) on \( \Omega \) is said to be quasi-continuous if for each \( \varepsilon > 0 \), there exists an open set \( O \) with \( c(O) < \varepsilon \) such that \( X|_{\Omega\setminus O} \) is continuous.

Definition 2.4 We say that \( X : \Omega \to \mathbb{R} \) has a quasi-continuous version if there exists a quasi-continuous function \( Y : \Omega \to \mathbb{R} \) such that \( X = Y \), q.s.

Then \( L^p_G(\Omega) \) can be characterized as follows:

\[
L^p_G(\Omega) = \{ X \in L^0(\Omega) | \lim_{N \to \infty} \hat{\mathbb{E}}[|X|^p 1_{|X| \geq N}] = 0 \text{ and } X \text{ has a quasi-continuous version} \}.
\]
3 The main results

In this paper, we always assume $g^2 > 0$. Without loss of generality, assume $\sigma^2 = 1$. This section is devoted to study the sample path properties of $G$-Brownian motion, before that we need some estimates from the theory of fully nonlinear partial differential equations.

Lemma 3.1 Suppose $u^n$ is the solution of the following $G$-heat equation,

\[
\begin{cases}
\partial_t u^n(t, x) - G(\partial_{xx}^n u^n(t, x)) = 0, & (t, x) \in (0, T) \times \mathbb{R}, \\
u^n(0, x) = \exp\{-\frac{n(x-a)^2}{2}\},
\end{cases}
\]

where $n \geq 0$ and $a \in \mathbb{R}$. Then there exists some constant $\alpha \in (0, \frac{1}{2}]$ depending only on $G$ such that

\[u^n(t, x) \leq \frac{1}{(nt + 1)^\alpha} \exp\{-\frac{n(x-a)^2}{2(nt + 1)}\} \]

Proof. Set $v^n(t, x) = \frac{1}{(nt + 1)^\alpha} \exp\{-\frac{n(x-a)^2}{2(nt + 1)}\}$, here $\alpha$ is a positive constant which need to be determined in the following proof. Then we get

\[
\partial_t v^n(t, x) = -\frac{n\alpha}{nt + 1} v(t, x) + \frac{n^2(x-a)^2}{2(nt + 1)^2} v(t, x), \quad \partial_x v^n(t, x) = -\frac{n(x-a)}{nt + 1} v(t, x),
\]

\[
\partial_{xx} v^n(t, x) = -\frac{n}{nt + 1} v(t, x) + \frac{n^2(x-a)^2}{(nt + 1)^2} v(t, x).
\]

Consequently,

\[
\partial_t v^n(t, x) - G(\partial_{xx} v^n(t, x))
= -\frac{n\alpha}{nt + 1} v^n(t, x) + \frac{n^2(x-a)^2}{2(nt + 1)^2} v^n(t, x) - G\left(-\frac{n(x-a)}{nt + 1} v^n(t, x), \frac{n^2(x-a)^2}{(nt + 1)^2} v^n(t, x)\right)
\geq -\frac{n\alpha}{nt + 1} v^n(t, x) + \frac{n^2(x-a)^2}{2(nt + 1)^2} v^n(t, x) - G\left(-\frac{n(x-a)}{nt + 1} v^n(t, x), -\frac{n^2(x-a)^2}{(nt + 1)^2} v^n(t, x)\right)
= \frac{n}{2(nt + 1)} (\sigma^2 - 2\alpha) v^n(t, x) + \frac{n^2(x-a)^2}{2(nt + 1)^2} (1 - \sigma^2) v^n(t, x)
\geq 0,
\]

where $\alpha = \frac{1}{2} \sigma^2 \leq \frac{1}{2}$. Thus $v^n(t, x)$ is a bounded supersolution of PDE (1) for each $n \geq 0$. From the comparison theorem (see Appendix C in Peng [12]), we derive

\[u^n(t, x) \leq v^n(t, x),\]

which completes the proof. ■

Remark 3.2 We remark that the above results is non-trivial. Indeed if $g^2 < \sigma^2$, then the constant $\alpha$ appearing in the above results is strictly less that $\frac{1}{2}$ because of the nonlinearity.

Now we shall consider some simple Borel functions on $\Omega$.

Lemma 3.3 For each $a \in \mathbb{R}$, $1_{B_{1:a}}, 1_{B_{1:a}} \in L^1_{\mathcal{F}}(\Omega_t)$. 

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Applying Lemma 3.1 and nonlinear Feynman-Kac formula in Peng [12], we get,

\[ \mathbb{E}[\varphi^n(B_t) - 1_{B_t \leq 0}] \leq \mathbb{E}[\exp(-nB_t^2)]. \]

Then consider the following $G$-heat equation,

\[
\begin{cases}
\partial_t u^n(t,x) - G(\partial_{xx}^2 u^n(t,x)) = 0, & (t,x) \in (0,T) \times \mathbb{R}, \\
u^n(0,x) = \exp\{-nx^2\}.
\end{cases}
\]

Applying Lemma 3.3 and nonlinear Feynman-Kac formula in Peng [12], we get,

\[ \mathbb{E}[\exp(-nB_t^2)] = u^n(t,0) \leq \frac{1}{n^{q/2}}, \]

where $\alpha$ is given in Lemma 3.1. Thus sending $n \to \infty$, we have

\[ \lim_{n \to \infty} \mathbb{E}[\varphi^n(B_t) - 1_{B_t \leq 0}] \leq \lim_{n \to \infty} \frac{1}{n^{q/2}} = 0, \]

and we deduce $1_{B_t \leq 0} \in L^1_G(\Omega_t)$.

By a similar analysis, we also have

\[ \mathbb{E}[1_{B_t = 0}] \leq \lim_{n \to \infty} \mathbb{E}[\exp(-nB_t^2)] = 0. \]

Thus $1_{B_t \leq 0} = 1_{B_t < 0}$, q.s. and the proof is complete. \(\blacksquare\)

**Remark 3.4** If $\varphi^2 = 0$, it follows from Remark 2.1 that $c(B_t = 0) = 1$ and $1_{B_t < 0}$ is not in $L^1_G(\Omega_t)$.

Unlike the classical case, we cannot get $1_H \in L^1_G(\Omega_t)$ for any Borel set $H \in F_t$. Indeed Soner et al [14] constructed a counterexample. However, from Lemma 3.3 we immediately have the following theorem.

**Theorem 3.5** For the $G$-Brownian motion $B$, we have the following properties.

(i) Given a Borel set $O$ of $\mathbb{R}$. If there exists a sequence points $\{a_i\}_{i=1}^\infty$ such that $\partial O \subset \cup_{i=1}^\infty a_i$, then $1_{B_t \in O} \in L^1_G(\Omega_t)$.

(ii) For each $a \in \mathbb{R}$, the set $Z = \{t : B_t = a\}$ is q.s. closed and has zero Lebesgue measure.

**Proof.** (i) From Lemma 3.3, for each $a \in \mathbb{R}$, $1_{B_t = a} = 0$, q.s.. Then

\[ c(B_t \in \partial O) \leq \sum_{i=1}^\infty c(B_t = a_i) = 0. \]

Note that the set $\{\omega : B_t \in \partial O\}$ is a closed subset of $\Omega$. By Lemma 3.4 of Song [15], we deduce that $1_{B_t \in O}$ is quasi-continuous. Recalling the pathwise description of $L^1_G(\Omega_t)$, we get $1_{B_t \in O} \in L^1_G(\Omega_t)$.

(ii) From the continuity of $G$-Brownian motion paths, we get $Z$ is closed. Recalling $c(B_t = a) = 0$ for each $t > 0$, we obtain

\[ \mathbb{E}\int_0^\infty 1_Z(s) ds \leq \int_0^\infty \mathbb{E}[1_Z(s)] ds = 0. \]

It follows that $Z$ has q.s. zero Lebesgue measure, which is the desired result. \(\blacksquare\)

We also have the following result.
Lemma 3.6 For each $t > 0$,
\[ c(B_t^*) = 0 = 0, \]
where $B_t^* = \sup_{s \in [0, t]} B_s$.

**Proof.** Denote $\psi^n(x) = \exp\{-nx^2\}$ for each $n$. By Remark 2.1, we have
\[ \hat{E}[\psi^n(B_t^*)] = \sup_{\theta} E_P[\psi^n(M_t^{\theta,*})], \]
where $M_t^\theta = \int_0^t \theta_u dW_u$. From the time transformation for continuous martingale (see Theorem V.1.6 in Revuz and Yor [13]), there exists a Brownian motion $\hat{W}$ on $(\Omega, \mathcal{F}, P)$ (or an enlargement of this probability space) such that
\[ \hat{W}_{(M^\theta)_t} = M_t^\theta. \]
Since $\theta^2 \in [\sigma^2, \sigma^2]$, we have
\[ \int_0^t \theta_s^2 ds \geq \sigma^2 t. \]
Thus $\hat{W}_{(M^\theta)_t} \geq \hat{W}_{\sigma^2 t}$ for each $\theta$. Therefore we obtain
\[ \hat{E}[\psi^n(B_t^*)] \leq E_P[\psi^n(\hat{W}_{\sigma^2 t})] = E_P[\psi^n(|\hat{W}_{\sigma^2 t}|)], \]
since $\hat{W}_t \overset{d}{=} |\hat{W}_t|$. From Lemma 3.1, we get
\[ c(B_t^* = 0) \leq \lim_{n \to \infty} \hat{E}[\psi^n(B_t^*)] = 0, \]
which is the desired result. \[ \square \]

Under the framework of $G$-expectation, independence is noncommutative and it requires that the test functions are bounded Lipschitz. In the next lemma we will prove the consistency of independence notion under $G$-expectation with the classical independence notion in some sense.

Lemma 3.7 For each open subset $O$, closed subset $F$ of $\mathbb{R}$ and $t, s \geq 0$,
\[ c(B_t \in O, B_{t+s} - B_t \in O) = c(B_t \in O)c(B_{t+s} - B_t \in O), \]
\[ c(B_t \in F, B_{t+s} - B_t \in F) = c(B_t \in F)c(B_{t+s} - B_t \in F). \]

**Proof.** For each $n$, denote $\psi^n(x) = \frac{n^2(x, x)}{1 + n^2(x, x)/\theta}$. Then $\psi^n(x)$ is a Lipschitz function and $\psi^n \uparrow 1_O$. Then applying Theorem 1.10 of Chapter VI in Peng [12], we have Thus
\[ \hat{E}[1_O(B_t)] = \lim_{n \to \infty} \hat{E}[\psi^n(B_t)]. \]
Consequently,
\[ \hat{E}[1_O(B_t)1_O(B_{t+s} - B_t)] = \lim_{n \to \infty} \hat{E}[\psi^n(B_t)\psi^n(B_{t+s} - B_t)] = \lim_{n \to \infty} \hat{E}[\psi^n(B_t)] \lim_{n \to \infty} \hat{E}[\psi^n(B_{t+s} - B_t)] = \hat{E}[1_O(B_t)]\hat{E}[1_O(B_{t+s} - B_t)], \]
and the first equality holds true. The second equality can be proved in a similar way. \[ \square \]

Now we introduce the following nonlinear PDE:
\begin{align*}
\begin{cases}
\partial_t u^n(t, x) - G(\partial^2_{xx} u^n(t, x)) = 0, \ (t, x) \in (0, T) \times \mathbb{R}, \\
u^n(0, x) = \varphi^n(x),
\end{cases}
\end{align*}
(2)
where function $\varphi^n$ is given in the proof of Lemma 3.3. It is obvious $u^{n+1} \leq u^n$ for each $n$.

By the interior regularity of $u^n$ (see Krylov [3] and Wang [16]), there exists a constant $\gamma \in (0, 1)$ depending on $G$ such that for each $\epsilon > 0$, we can find some constant $C$ depending only on $\epsilon, \gamma$ and $G$ so that

$$\|u^n\|_{C^{1+\frac{\gamma}{2}}([\epsilon,T] \times \mathbb{R})} < C.$$ 

Then for each $\epsilon$, there exists a subsequence $\{u^{n'}\}_{n'=1}^\infty$ such $\partial_t u^{n'}, \partial_x u^{n'}$ and $\partial_{xx} u^{n'}$ are Cauchy sequences in $[\epsilon,T] \times \mathbb{R}$. Denoting $v(t,x) := \lim_{n \to \infty} u^n(t,x)$, we can get $\partial_t v, \partial_x v, \partial_{xx} v$ converge respectively to $\partial_t v, \partial_x v, \partial_{xx} v$ in $[\epsilon,T] \times \mathbb{R}$. Since $\epsilon$ is arbitrary, $v(t,x) \in C^{1,2}((0,T) \times \mathbb{R})$. Moreover, $v(t,x)$ is a solution of the following nonlinear PDE:

$$\begin{cases}
\partial_t v(t,x) - G(\partial_{xx}^2 v(t,x)) = 0, (t,x) \in (0,T) \times \mathbb{R}, \\
v(0,x) = 1_{x \leq 0}.
\end{cases}$$

In addition,

$$v(t,x) = \lim_{n \to \infty} u^n(t,x) = \lim_{n \to \infty} \mathbb{E}[\varphi^n(B_t + x)] = \mathbb{E}[1_{B_t + x \leq 0}],$$

which is the nonlinear Feynman-Kac formula.

**Lemma 3.8** For each $t > 0$, $v(t, \cdot) : \mathbb{R} \mapsto (0, 1)$ is a strictly decreasing function.

**Proof.** Applying Theorems 10 and 31 in Denis, Hu and Peng [1] yields that

$$\lim_{x \to +\infty} v(t,x) = 0, \quad \lim_{x \to -\infty} v(t,x) = 1.$$ 

For each $x < y$, we have

$$v(t,x) - v(t,y) = \mathbb{E}[1_{B_t + x \leq 0}] - \mathbb{E}[1_{B_t + y \leq 0}] \geq - \mathbb{E}[-1_{y < B_t \leq -x}] > 0.$$ 

The last estimate comes from Corollary 3.5 of Li [9] and we establish the desired result. ■

Now we shall study the local maxima of the $G$-Brownian motion paths.

**Definition 3.9** Given a function $f : [0, \infty) \mapsto \mathbb{R}$. A number $t$ is called a point of local maximum, if there exists a number $\delta > 0$ such that

$$f(s) \leq f(t), \quad \forall s \in [(t - \delta)^+, t + \delta].$$

**Theorem 3.10** For $q.s.$ $\omega$, the $G$-Brownian motion $B$ is monotone in no interval.

**Proof.** Denote by $F$ the set of all paths $\omega$ with the property that $B_t(\omega)$ as a function of $t$ is monotone in some time interval. Then we have

$$F = \bigcup_{s,t \in Q} \{ \omega : B \text{ is monotone in } [s,t]\},$$

where $Q$ is the set of all rational points in $[0, \infty)$. Therefore it suffices to show that in any such interval, say in $[0, 1]$, the path $B$ is $q.s.$ not monotone. By virtue of the symmetry of $G$-Brownian motion, it suffices to prove the set

$$A = \{ \omega : B \text{ is decreasing on } [0, 1]\}$$

is a polar set. But $A = \bigcap_n A_n$, where

$$A_n = \bigcap_{i=1}^n \{ \omega : B_{\frac{i}{n}} - B_{\frac{i-1}{n}} \leq 0 \}.$$
From the Lemmas 3.7 and 3.8 we conclude that
\[ c(A_n) = \Pi_n c(\{ \omega : B_{\frac{n}{2^k}} - B_{\frac{n}{2^{k+1}}} \leq 0 \}) = \rho^n, \]
where \( \rho = \hat{E}[1_{B_t \leq 0}] = \hat{E}[1_{B_s \leq 0}] < 1 \) for each \( s, t \). Thus \( c(A) \leq \lim_{n \to \infty} c(A_n) = 0 \), which completes the proof. ■

Note that if \( f \) is a continuous function which is monotone in no interval, then set of points of local maximum for \( f \) is dense (see Chapter 2.9 in [4]). Thus the following corollary is a direct result of theorem 3.10.

**Corollary 3.11** The set of points of local maximum for the \( G \)-Brownian motion \( B \) is dense in \([0, \infty)\) q.s..

Then we shall show the nowhere differentiability of \( G \)-Brownian paths.

**Lemma 3.12** For each \( t > 0, a \in \mathbb{R} \) and \( \epsilon > 0 \), we have
\[ c(|B_t - a| \leq \epsilon) \leq \exp(\frac{1}{2} \frac{\epsilon^{2\alpha}}{t^{\alpha}}), \]
where \( \alpha = \frac{\sigma^2}{2} \).

**Proof.** By Lemma 3.11 we obtain for each \( a \in \mathbb{R} \) and \( n \geq 0 \),
\[ \hat{E}[\exp(-\frac{n(B_t - a)^2}{2})] \leq \frac{1}{(1 + nt)^\alpha}. \]
Thus for each \( n \) and \( \epsilon > 0 \), we obtain that
\[ \hat{E}[1_{|B_t - a| \leq \epsilon}] \leq \exp(\frac{n\epsilon^2}{2}) \hat{E}[\exp(-\frac{n(B_t - a)^2}{2})] \leq \exp(\frac{n\epsilon^2}{2}) \frac{1}{(1 + nt)^\alpha}. \]
Therefore, taking \( n = \frac{1}{\gamma} \) yields that,
\[ c(|B_t - a| \leq \epsilon) \leq \exp(\frac{1}{2} \frac{\epsilon^{2\alpha}}{t^{\alpha}}), \]
which completes the proof. ■

**Theorem 3.13** The \( G \)-Brownian path is q.s. nowhere locally Hölder continuous of order \( \gamma \) for any \( \gamma > \frac{1}{2} \). In particular, the \( G \)-Brownian path is nowhere differentiable and has infinite variation on any interval.

**Proof.** We shall only have to prove that the \( G \)-Brownian path is q.s. nowhere locally Hölder continuous of order \( \gamma \) on interval \([0, 1]\) as the classical case. Fix a \( \gamma > \frac{1}{2} \), we can find an integer \( l \) so that \( l > \frac{1}{(2\gamma - 1)} \). For each \( \beta > 0 \), we consider
\[ A_n = \{ \omega : \text{there is a point } s \in [0, 1] \text{, such that } |B_t(\omega) - B_s(\omega)| < \beta |t - s|^{\gamma} \text{ whenever } |t - s| < \frac{l}{n} \}. \]
It is obvious that \( A_n \) is increasing to \( \bigcup_{n=1}^{\infty} A_n = \lim_{n \to \infty} A_n \). Note that any locally \( \gamma \)-Hölder continuous path \((\omega_s)_{s \in [0, 1]}\) belongs to some \( A_n \) with some \( \beta > 0 \). Then it suffice to prove \( c(\bigcup_{n=1}^{\infty} A_n) \) is polar for each \( \beta > 0 \).
For each \(0 \leq k \leq n\), we set
\[
Z_k := \max_{1 \leq i \leq l} |B_{k+i} - B_{k+i-1}|\quad \text{and} \quad D_n := \{\omega : \text{there is a constant } k \text{ such that } Z_k(\omega) \leq 2\beta \frac{l^\gamma}{n^\gamma}\}.
\]

It is easy to check that \(A_n \subset D_n\). Indeed, for each \(\omega \in A_n\) that is locally Hölder continuous at \(s\), if \(k\) is chosen to be the largest integer such that \(k \leq ns\), then
\[
Z_k(\omega) \leq 2\beta \frac{l^\gamma}{n^\gamma}.
\]

Thus from Theorem 1.10 of Chapter VI in Peng [12], we get
\[
c(\cup_{n=1}^\infty A_n) = \lim_{n \to \infty} c(A_n) \leq \liminf_{n \to \infty} c(D_n) \leq \liminf_{n \to \infty} \sum_{k=0}^n c(Z_k(\omega) \leq 2\beta \frac{l^\gamma}{n^\gamma}).
\]

In the spirit of Lemma 3.7, we obtain,
\[
\sum_{k=0}^n c(Z_k(\omega) \leq 2\beta \frac{l^\gamma}{n^\gamma}) = nc(Z_0(\omega) \leq 2\beta \frac{l^\gamma}{n^\gamma}) \leq nc(|B_{k+1} - B_k| \leq 2\beta \frac{l^\gamma}{n^\gamma}) \leq nc(|B_{n+2\gamma-1} - B_{n+2\gamma-2}| \leq 2\beta l^\gamma).
\]

Then by Lemma 3.12, we get that
\[
c(\cup_{n=1}^\infty A_n) \leq \liminf_{n \to \infty} nc(|B_{n+2\gamma-1} - B_{n+2\gamma-2}| \leq 2\beta l^\gamma) \leq \liminf_{n \to \infty} n[\exp(\frac{1}{2}(\frac{2\beta l^\gamma}{n^\gamma}))^{2\alpha n}] = 0,
\]

since \(l > \frac{1}{\alpha(2\gamma-1)}\). The proof is complete. 

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