Fully-resolved array of simulations investigating the influence of the magnetic Prandtl number on MHD turbulence

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We explore the effect of the magnetic Prandtl number $P_m$ on energy and dissipation in fully-resolved direct numerical simulations of steady-state, mechanically-forced homogeneous magnetohydrodynamic turbulence in the range $1/32 < P_m < 32$. We compare the spectra and show that if the simulations are not fully resolved, the steepness of the scaling of the kinetic-to-magnetic dissipation ratio with $P_m$ is overestimated. We also present results of decaying turbulence with helical and nonhelical magnetic fields, where we find nonhelical reverse spectral transfer for $P_m < 1$ for the first time. The results of this systematic analysis have applications ranging from stars, planetary dynamos, and accretion disks.

I. INTRODUCTION

Turbulence is observed in an enormous variety of situations but fully understood in few. When an electrically-conducting fluid is exposed to a magnetic field, the turbulent dynamics can be described by the magnetohydrodynamic (MHD) equations, which dictate how the two main aspects of the fluid (the velocity and magnetic fields) interact. The seminal work on MHD was done by Hannes Alfvén [1], earning him the Nobel Prize. MHD offers valuable insights into astrophysical and geophysical phenomena, including the solar wind and the Earth’s magnetic field, and aids the development of industrial processes such as fusion reactors [2–6].

Physical properties of a magnetofluid affect its behaviour. One such property is the magnetic Prandtl number $P_m = \nu/\eta$, where $\nu$ is the kinematic viscosity and $\eta$ the magnetic resistivity, which is a material property of the fluid. We may also write $P_m = R_m/R_e$, where $R_m$ and $R_e$ are the magnetic and kinetic Reynolds numbers, quantifying respectively the turbulence of the magnetic and kinetic components of the fluid. In nature, extreme values of $P_m$ are commonplace: stellar and planetary interiors are in the range $P_m \sim 10^{-4}$ to $10^{-7}$ and smaller, while the interstellar medium and cosmological-scale magnetic fields have estimated values of $P_m \sim 10^{10}$ to $10^{14}$ [5, 7–11]. The achievable range of $P_m$ in direct numerical simulations (DNS) is highly restricted because of computational requirements and is often set to one, which is not representative of most magnetofluids. Extrapolating from simulations with $P_m$ in the vicinity of one is often necessary when connecting computational results to real-life applications. That said, the region around unity is not without its applications: black hole accretion disk models indicate that $P_m$ may transition from being very small in most of the disk, to being greater than one near the centre, which may explain the change of state from emission to accretion in these objects [12]. Estimates of $P_m$ in the solar wind and solar convective zone are $P_m \approx 5 [1, 13]$.

In this paper we present an array of 36 high-resolution DNS of mechanically-forced, homogeneous, incompressible magnetohydrodynamic turbulence without a mean magnetic field, with $1/32 < P_m < 32$. Additionally, we present 18 decaying simulations with $1/16 < P_m < 16$, in which we test the effect of $P_m$ on reverse spectral energy transfer (which includes any transfer of energy from small to large scales is not restricted to just inverse cascade). With our forced data we focus on the energy spectra, the ratios of the total kinetic and magnetic energies $E_K/E_M$, called the Alfvén ratio, and the kinetic and magnetic dissipation rates $\varepsilon_K/\varepsilon_M$. We also discuss resolution requirements in connection with recent theoretical findings.

In previous studies, an approximate scaling $\varepsilon_K/\varepsilon_M \approx P_m^q$ was found [14, 15]. The parameter $q$ varied depending on the magnetic helicity (which includes the knottedness of the magnetic field, and contributions from twist, writhe, and linkage [16, 17]) and whether $P_m$ was greater than or less than one. However, these papers only guaranteed full resolution of one dissipation scale. In other words, the largest wavenumber in the simulation, $k_{\text{max}}$, was greater than either the kinetic dissipation wavenumber $k_\nu = (\varepsilon_K/\nu^3)^{1/4}$ or the magnetic dissipation wavenumber $k_\eta = (\varepsilon_M/\eta^3)^{1/4}$, but not both. This is an issue because although a system’s energy is mostly concentrated in the largest length scales, the dissipation spectrum is proportional to the wavenumber squared. In hydrodynamic turbulence, in order to capture 99.5% of the dissipative dynamics, the condition $k_{\text{max}} > 1.25k_\nu$ must be fulfilled [18–20]. This was our definition of ‘fully-resolved’ and in all our forced simulations we had both $1.25k_\nu < k_{\text{max}}$ and $1.25k_\eta < k_{\text{max}}$. This paper also gives an explanation for the scaling which has not been done before.

Our set of forced simulations are an extensive dataset for DNS of homogeneous MHD turbulence, with 36 data points in the Re-Rm plane covering a square grid (see
Fig. 1). Re and Rm range from approximately 50 to 2300, allowing for a three order of magnitude range in magnetic Prandtl number. Each point was run on a 512^3 or 1024^3 lattice depending on individual resolution requirements, ensuring all data was fully resolved. This is the largest fully-resolved dataset for a Pm study.

Large values of magnetic helicity encourage reverse spectral transfer (RST), where energy is transferred to the largest length scales in the system, rather than to the small, dissipative scales, as in the usual Richardson-Kolmogorov phenomenology [21–24]. Whilst RST does not imply an inverse cascade, an inverse cascade is a type of RST. The second aspect of our study covers magnetofluids with nonzero magnetic helicity. We found RST in both helical and nonhelical turbulence down to Pm = 1/4, increasing as Rm increased, with Re playing little role. We thus confirm the results of recent simulations that found RST without helicity [25–27] and have seminal results showing RST occurring for Pm < 1.

II. SIMULATIONS

We carried out DNS of the incompressible MHD equations

\[ \partial_t u = - \nabla P - (u \cdot \nabla)u + (b \cdot \nabla)b + \nu \nabla^2 u + f, \]

\[ \partial_t b = \nabla \times (u \times b) + \eta \nabla^2 b, \]

\[ \nabla \cdot u = 0, \nabla \cdot b = 0 , \]

where \( u \) is the velocity field, \( b \) is the magnetic field in Alfvén units, \( P \) is the total pressure, the density is constant and set to 1, and \( f \) is a random force defined via a helical basis:

\[ f(k,t) = A(k)e_1(k,t) + B(k)e_2(k,t), \]

where \( e_1, e_2 = e_1 \cdot k = e_2 \cdot k = 0 \) and \( e_1 \) and \( e_2 \) are unit vectors satisfying \( ik \times e_1 = ke_1 \) and \( ik \times e_2 = -ke_2 \) [28–30]. \( A(k) \) and \( B(k) \) are variable parameters that allow the injection of helicity to be adjusted; we chose to force nonhelically. We solved the MHD equations numerically using a pseudospectral, fully-dealiased code (see [18, 31] for details) on a three-dimensional periodic domain. The initial fields were random Gaussian with magnetic and kinetic energy spectra of the form \( E_{M,K}(k, t = 0) = C k^4 \exp(-k^2/2k_0^2) \), where \( C \) is a positive real number and \( k_0 \) is the peak of the spectrum. In our forced simulations we set \( k_0 = 5 \) and forced the velocity field at the largest scales, \( 1 \leq k \leq 2.5 \). The nature of the forcing function and the forcing length scale do not greatly affect the dynamics [28, 32]. We also ran decaying simulations, where we were less interested in the inertial range energy spectra and more interested in RST, so we set the peak at \( k_0 = 40 \). There was no imposed magnetic guide field. The viscosity and resistivity of each simulation are given in Fig. 1; note that \( Rm \approx 0.65/\eta \) and \( Re \approx 0.65/\nu \). This value of 0.65 comes from the fact that

the rms velocity \( u \) and integral length scale \( L \) are relatively constant during the simulations, with \( Re = uL/\nu \) and \( Rm = uL/\eta \).

III. RESULTS

A. Energy

Figure 2a shows the time-averaged compensated kinetic energy spectra of selected simulations. In each of the three plots the solid line represents the same simulation, with \( Re=Rm \approx 2275 \) and \( Pm = 1 \). The top plot shows the spectra of four simulations where \( Re \) and \( Rm \) were increased with \( Pm = 1 \) kept constant. The middle plot compares data with \( Rm \approx 2275 \) and \( Pm \) increasing from 1 to 32 by decreasing \( Re \); while the bottom plot shows data with \( Re \approx 2275 \) and \( Pm \) being decreased from 1 to 1/32 via decreasing \( Rm \). When we increase \( Re \) but keep \( Pm \) constant, as in the top plot, we see that less energy is stored in the large scales of the velocity field, whereas if we increase \( Re \) but keep \( Rm \) constant and large-valued, as in the middle plot, the amount of energy in the large-scale velocity field is slightly enhanced. The spectrum most closely resembling the Kolmogorov \( k^{-5/3} \) scaling is the \( Pm = 1/32 \) run in the bottom plot, which seems to be below the dynamo action onset threshold,
and so the magnetic field (which was initially in equipartition with the velocity field) will eventually decay completely, leaving a purely hydrodynamic simulation.

The corresponding magnetic energy spectra are shown in Fig. 2b. The spectra are most heavily influenced by \( R_m \). In the top and bottom plots, \( R_m \) is varied while \( P_m \) and \( \text{Re} \) are respectively kept constant. The spectra produced in these two plots are relatively similar except in the \( R_m=73 \) case, where for \( P_m = 1 \) the magnetic field is sustained but for \( P_m = 1/32 \) it is decaying. In the second plot we see that increasing \( P_m \) with constant \( R_m \) may slightly augment the large-scale magnetic field. Whilst this appears to imply \( P_m \)-dependence of the energy spectra, the total energy spectra \( E_T(k) = E_K(k) + E_M(k) \) (equivalent to thinking in terms of Elsässer variables) appears to depend only on the maximum of \( \text{Re} \) or \( R_m \), and is thus independent of \( P_m \).

Figure 3 shows the time-averaged Alfvén ratios as a function of \( P_m \), grouped into sets of points with approximately equal \( R_m \). For fixed \( R_m \) the Alfvén ratios tend to decrease as \( P_m \) is increased, although the slope flattens at larger \( R_m \). Bearing in mind that \( R_m \) doubles with each set of points, we see that the data are converging onto an asymptotic high-\( R_m \) limit. For all values of \( P_m \), the ratio \( E_K/E_M \) decreases with increasing \( R_m \). These behaviours are in agreement with what was put forward in Ref. [33].

Figure 3: Time-averaged Alfvén ratios of simulations grouped according to resistivity, \( \eta \).

FIG. 3: Time-averaged Alfvén ratios of simulations grouped according to resistivity, \( \eta \).
B. Dissipation

Figure 4 shows the kinetic-to-magnetic dissipation ratios for our dataset. Our \( P_m > 1 \) data collapse onto the same line as \( R_m \) increases, implying asymptotic independence from \( R_m \) when \( P_m > 1 \). The scalings for nonhelical MHD with \( P_m < 1 \) and \( P_m > 1 \) that were proposed in Ref. [14] have been indicated. Since for \( P_m < 1 \) the kinetic dissipation scale was not properly resolved in the simulations reported in Ref. [14], it is probable that the measurement of \( \varepsilon_K \) was affected, and similarly \( \varepsilon_M \) when \( P_m > 1 \), so the steepness of the scaling of \( \varepsilon_K/\varepsilon_M \) with \( P_m \) appears exaggerated for both \( P_m < 1 \) and \( P_m > 1 \) compared to our results.

The total dissipation rate was controlled by the large-scale energy injection and is approximately constant across all of our simulations. In our mechanically-forced simulations \( \varepsilon_M \) is necessarily equal to the average net kinetic-to-magnetic energy transfer rate, so the ratio \( \varepsilon_K/\varepsilon_M \) can be used as a measure of the efficiency of dynamo action. Smaller values mean more energy is being transferred to and dissipated via the magnetic field. The collapse of our data onto one line as \( R_m \) increases in Fig. 4 shows that there is a maximum dynamo efficiency which is curtailed as the magnetic Prandtl number increases; that is, although a magnetic field is more easily sustained at large values of \( P_m \), it receives relatively less energy transfer from the velocity field. This is consistent with other work from a very different direction [34, 35] but within the same \( P_m \) range, that also supports a diminishing of the dynamo. At small values of \( P_m \), \( \varepsilon_M \) may far exceed \( \varepsilon_K \), meaning that if the kinetic-to-magnetic transfer rate is not able to match \( \varepsilon_M \), any magnetic field will eventually dissipate fully. This line onto which the data collapses has an inflexion point about \( P_m=1 \), however, the equivalent line when plotting \( \varepsilon_M/\varepsilon_T \ (\varepsilon_T = \varepsilon_K + \varepsilon_M) \) as a function of \( P_m \) shows no such inflexion. This serves as one explanation for the origin of the scaling behavior of the dissipation ratio.

To illustrate the importance of resolution we repeated on a 128\(^3\) lattice our simulations which had been done on a 512\(^3\) lattice; see Fig. 5. The low-resolution simulations miscalculated the dissipation ratios by up to 40\%, with the biggest discrepancies mostly occurring at high \( R_m \). Additionally, for \( P_m = 1/8 \), where dynamo action was not sustainable, the low-resolution dissipation ratio was more than 3 times the high-resolution ratio.

Analyses of triad interactions and shell-to-shell energy transfers show that energy is transferred from the velocity field at the forcing scale to the magnetic and velocity fields at all scales in a way that depends on the separation between the giving and receiving scales and the energy contained in the involved scales, amongst other things [29, 36–40]. Therefore it is reasonable to expect a consistent scaling of \( \varepsilon_K/\varepsilon_M \) with \( P_m \) that is not affected by whether \( P_m < 1 \) or \( P_m > 1 \), as we see in Fig. 4. Furthermore, when the velocity field is turbulent over a larger range of scales than the magnetic field, i.e. \( k_r > k_\eta \) and \( P_m < 1 \), then for a given \( R_m \) there should be a corresponding value of \( P_m \) below which more energy will be transferred to the dissipative part of the magnetic field, \( k > k_\eta \), than to \( k < k_\eta \). It thus seems natural that the magnetic field would become unsustainable at some critical value of \( P_m \), as put forward in Ref. [34]. The coupling between the small-scale velocity field and the large-scale magnetic field may be key to tipping the balance in favour of sustainable dynamo action for small values of \( P_m \) [41]. Indeed, this explains why the \( P_m = 1/8 \) result in Fig. 5 was so large: dynamo action in the low-resolution simulation was suppressed.

C. Reverse spectral transfer

In Fig. 2b the high-Rm data have more of a build-up of magnetic energy in the largest scales than the lower-Rm data. Inspired by this, we move on to examining the effect of \( R_m \) and \( P_m \) on RST by comparing simulations of decaying MHD turbulence with initially fully helical or nonhelical magnetic fields. We performed 9 pairs of simulations covering the range \( 1/16 \leq P_m \leq 16 \) in multiples of 4, with the extreme values of \( \nu \) and \( \eta \) being 0.005 and 0.0003125 (see Fig. 1). To facilitate RST, we set the peak of the initial energy spectra to \( k_0 = 40 \).

We define the energy in the first 3 wavenumbers of the magnetic field as \( E_3(t) = \int_{k_1}^{k_3} |E_M(k, t)|^2 \, dk \). Since the system is not subject to an external force, then if \( E_3(t) \) is constant or increasing, energy must be coming from smaller length scales. We measured \( E_3(t) \) until the simulation entered a power law decay of total energy and plotted the results in Fig. 6. We found that increasing \( P_m \) by increasing \( R_m \) enhances the growth rate of RST, with a stronger effect than increasing \( P_m \) by decreasing \( R_m \). This indicates that RST should be possible as long as there is adequate separation of \( k_1, k_2 \) and \( k_\eta \), where \( k_1 = 1 \) is the largest wavenumber in the system and \( k_\nu \) is
close to the value of $k_\eta$ or greater. In general the high-Rm simulations (top plot in Fig. 6) had the most RST. RST was absent at Pm = $1/16$ but present at Pm = $1/4$ for high enough Rm. As far as we are aware, nonhelical RST for Pm < 1 has not been seen in previous DNS, and may be of interest in geophysical applications [42].

IV. CONCLUSIONS

The fully-resolved simulations developed in this paper are a definitive dataset, improving confidence on the scaling and energy transfer properties of MHD in the near couple decade region of magnetic Prandtl number around unity. We have shown that many results rely on reaching a critical Rm before we find asymptotic dependence on Pm. Furthermore, underresolved simulations may exaggerate the scaling of properties such as $\varepsilon_K/\varepsilon_M$ by failing to account for all of the dissipative dynamics. Although our simulations feature simple geometry and do not take into account e.g. rotation, approaching complex physical problems from this angle may still have merit. In black hole accretion disks, luminosity is influenced by the dissipation ratios and DNS measurements could be a useful calibration tool. We reiterate that fully-resolved simulations such as ours are vital for accurately producing dynamo action and other effects incurred by nonunity Pm.

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