Influence of the implant-abutment connection design and diameter on the screw joint stability

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PURPOSE. This study was conducted to evaluate the influence of the implant-abutment connection design and diameter on the screw joint stability. MATERIALS AND METHODS. Regular and wide-diameter implant systems with three different joint connection designs: an external butt joint, a one-stage internal cone, and a two-stage internal cone were divided into seven groups (n=5, in each group). The initial removal torque values of the abutment screw were measured with a digital torque gauge. The postload removal torque values were measured after 100,000 cycles of a 150 N and a 10 Hz cyclic load had been applied. Subsequently, the rates of the initial and postload removal torque losses were calculated to evaluate the effect of the joint connection design and diameter on the screw joint stability. Each group was compared using Kruskal-Wallis test and Mann-Whitney U test as post-hoc test (α=0.05).

RESULTS. The postload removal torque value was high in the following order with regard to magnitude: two-stage internal cone, one-stage internal cone, and external butt joint systems. In the regular-diameter group, the external butt joint and one-stage internal cone systems showed lower postload removal torque loss rates than the two-stage internal cone system. In the wide-diameter group, the external butt joint system showed a lower loss rate than the one-stage internal cone and two-stage internal cone systems. In the two-stage internal cone system, the wide-diameter group showed a significantly lower loss rate than the regular-diameter group (P<.05). CONCLUSION. The results of this study showed that the external butt joint was more advantageous than the internal cone in terms of the postload removal torque loss. For the difference in the implant diameter, a wide diameter was more advantageous in terms of the torque loss rate. [J Adv Prosthodont 2014;6:126-32]

KEY WORDS: Postload removal torque value; External butt joint connection; Internal connection; Platform switching

INTRODUCTION

One of the most common mechanical problems in implant prostheses is the joint loosening and fracture that occur in the screw joint portion between the implant fixture and the abutment.1,2 Joint loosening, along with the mechanical failure of the implant prosthesis, may cause biological complications such as tissue inflammation around the implants, gingival growth, and fistula formation. In particular, joint loosening in an implant treatment restored with the concept of immediate loading may cause harmful stress to the alveolar bone prior to the osseointegration, leading to the failure of the osseointegration.3

The fixture-abutment connection type for the implant system, which is widely used in clinical practice at present, is mainly classified into the external butt joint and the internal cone.

In the external butt joint connection type, stress is mainly applied to the abutment screw when a bending force is applied to the superstructure. In the internal cone connection type, the load is mainly transferred via the internal slope of the fixture. Such difference in the load transfer mechanism has been known to affect the stability of the implant connection part.4-8 In general, unlike the external butt joint that requires a second surgery after fixture instal-
lation, the internal cone has one-stage products that expose the collar, which is the membrane-penetrating region of the fixture, as well as two-stage products. The advantages of the two-stage implant are that it predicts a more esthetic outcome in the anterior region, protects the fixture from external force during the osseointegration, and manufactures a temporary denture in the case of poor bone quality. On the other hand, the advantages of the one-stage implant are that it does not require a second surgery, there is no microgap between the fixture and the abutment in the subgingival region, and the fulcrum length from the joint connection to the load point is short.

The implant diameter should be selected by considering the teeth defect pattern, depth and width of the residual alveolar bone, rehabilitation space, emergence profile, and occlusion. Implants with wide diameters are mainly used in cases of insufficient edentulous bone height, failure of osseointegration, or required reinstallation due to fixture fracture. Due to the advantages of wide-diameter implants, however, such as the emergence profile improvement, increased contact area between the fixture and the alveolar bone, increased fracture resistance, and wide stress distribution, it is clinically preferred in the posterior region, which has a wide bone width.

On the other hand, the platform-switching concept is a method that uses a regular abutment in a fixture with a wide diameter. The conduct of platform-switching on implants with external butt joint connections has been known to minimize marginal bone absorption resulting in gingival recession and interdental papilla loss, which commonly occur after abutment fastening by placing the fixture-abutment connection part that is a route of bacterial invasion, more internally via the use of a fixture larger than the abutment. The aforementioned implant systems that are currently used in clinical practice have various connection types and various diameters of their fixtures, abutments, and abutment screws. Unfortunately, studies on the effect of such factors on the stability of the connection part associated with screw loosening have rarely been conducted.

Accordingly, this study was conducted to investigate the effect of the implant-abutment connection design and diameter on the screw joint stability in implant systems with a two-stage external butt joint and one- and two-stage internal cones by comparing the removal torque loss of the abutment screw after repeated loads.

**MATERIALS AND METHODS**

In this study, the USII system with an external butt joint, the SSII system with a one-stage 8° internal cone, and the GSII system with a two-stage 11° internal cone from Osstem Implant (Osstem, Pusan, Korea) were used (Fig. 1). A fixture with two types of diameter was used in each system. A cement-retained abutment and WC/CTa (coated with tungsten carbide/carbon) screws were used (Table 1 and Table 2). A fixture with a 1.8 mm-high collar was used in the one-stage implant SSII system, and an abutment with a 2.0 mm-high collar was used in the other systems to maintain the same height at the load point. The subjects were divided into a total of seven groups according to the abutment-fixture connection type and diameter, including platform-switching type samples that used a regular abutment in their fixture with a wide diameter in the USII system.

The implant fixture was fixed to the separately manufactured jig, and the abutment was fastened to the implant. Then a 30 Ncm tightening torque was applied to each abutment screw using a digital torque gauge (MGT12E, MARK-10 Co., Hicksville, NY, USA) for standardization according to the manual of each manufacturer. Ten minutes later, the same tightening torque was applied again to compensate for the preload loss due to the surface sinking.

![Fig. 1. Sectional views of the implant fixture, abutment, and abutment screw assemblies.](Image)
Then the removal torque of each abutment screw was measured using a digital torque gauge. To minimize the change in the removal torque due to the repeated fastening, a total of 35 fixtures, abutments, and abutment screws were used in each system (five per experiment group).

The implant fixture was fixed to jig in a repeated load device (Instron 8841, Instron Co., England), and the abutment was fastened with an abutment screw by applying a 30 Ncm tightening torque, as in the measurement of the initial removal torque. Then, a machined stainless steel metal tube with disc shape was attached to abutment using a resin-class temporary cement (Premier Implant Cement, Premier Dental Products Co., La Vista, NE, USA) (Fig. 2).

A sine-type repeated load with a maximum 150 N, a minimum 10 N, and a 10 Hz cycle was applied to the metal tube, 5 mm away from the center axis of the implant. Then, 10^4 cycles and a 30 Ncm tightening torque were applied again for the simulation of more actual clinical situations. With the same method, 10^5 cycles of repeated load were applied, and the removal torque was measured using a digital torque gauge. The removal torque loss was calculated according to the following formula.

\[
\text{Postload Removal Torque Loss (\%)} = \left( 1 - \frac{\text{Postload Removal Torque value}}{\text{Initial Removal Torque Value}} \right) \times 100
\]

Table 1. Features of the experimental implant fixtures

| Group | Implant system | Diameter (mm) | Interface | Platform          |
|-------|----------------|---------------|-----------|-------------------|
| I     | USII regular   | 4.0           | External hex butt joint | 2.7 mm hexagon   |
| II    | USII wide      | 5.0           | External hex butt joint | 3.4 mm hexagon   |
| III   | USII T-wide    | 5.0           | External hex butt joint | 2.7 mm hexagon   |
| IV    | SSII regular   | 4.1           | 8° Morse taper    | 2.9 mm octagon   |
| V     | SSII wide      | 4.8           | 8° Morse taper    | 2.9 mm octagon   |
| VI    | GSII standard  | 4.0           | 11° Morse taper   | 2.5 mm hexagon   |
| VII   | GSII standard  | 5.0           | 11° Morse taper   | 2.5 mm hexagon   |

Table 2. Features of the experimental implant abutments and abutment screws

| Group | Abutment Screw Diameter (mm) | Abutment Screw Collar height (mm) | Abutment height (mm) | Composition (Coating) | Screw Diameter (mm) |
|-------|-----------------------------|----------------------------------|----------------------|-----------------------|---------------------|
| I     | 5.0                         |                                  |                      | Ti-6Al-4V (coated with tungsten carbide / carbon) | 2.0 |
| II    | 6.0                         |                                  |                      | Ti-6Al-4V (coated with tungsten carbide / carbon) | 2.5 |
| III   | 5.0                         | 2.0                              |                      | Ti-6Al-4V (coated with tungsten carbide / carbon) | 2.0 |
| IV    | 4.8                         | 2.0                              | 5.5                  | Ti-6Al-4V (coated with tungsten carbide / carbon) | 2.0 |
| V     | 6.0                         |                                  |                      | Ti-6Al-4V (coated with tungsten carbide / carbon) | 2.0 |
| VI    | 5.0                         |                                  |                      | Ti-6Al-4V (coated with tungsten carbide / carbon) | 2.0 |
| VII   | 6.0                         |                                  |                      | Ti-6Al-4V (coated with tungsten carbide / carbon) | 2.0 |

Fig. 2. Schematic diagram of testing conditions.
Statistical analysis was performed using SPSS ver. 18.0 (SPSS, Chicago, IL, USA). To analyze measurements taken at each group were compared using Kruskal-Wallis test. When the Kruskal-Wallis test was statistically significant, multiple comparison analysis was performed as a post-hoc test, using the Mann-Whitney U test. Values of $P<.05$ were taken to indicate statistical significance.

RESULTS

The mean and standard deviation of the removal torque before and after the load in each implant system was presented in Table 3. The initial removal torque was higher in Group II than in Group VII ($P<.05$), and no significant difference was found among the other groups ($P>.05$). The postload removal torque was highest to lowest in the regular-diameter comparison ($P<.05$) in the following groups, in this order: VI, IV, and I; and in the wide-diameter comparison ($P<.05$) in this order: VII, V, and II. No significant difference was found between Group III and Group II in the USII system ($P>.05$). The different lowercase superscript letters in the initial and uppercase superscript letters in the postload are significantly different ($P<.05$).

The mean and standard deviation of the removal torque loss in each system before and after the load are presented in Table 4. For the regular diameter, the postload removal torque loss was higher in Group VI than in Groups I and IV ($P<.05$), but no significant difference was found between Group I and Group IV ($P>.05$). For the wide diameter, the removal torque loss was higher in Groups V and VII than in Group II ($P<.05$), but no significant difference was found between Group V and Group VII ($P>.05$). In the comparison of the implant diameters, the postload removal torque loss was higher in Group VI than in Group VII ($P<.05$), but no significant difference in the removal torque loss was found among the other groups ($P>.05$). In addition, there was no significant difference between Group III and Group II in the USII system ($P>.05$). The different lowercase superscript letters in the torque loss denote significant differences ($P<.05$).

**Table 3.** Mean value ± SD of the initial and postload removal torques (Ncm)

| Group | Implant diameter (mm) | Initial | Postload |
|-------|-----------------------|---------|----------|
| I     | 4.0                   | 26.0 ± 0.8abc | 24.6 ± 1.5b |
| II    | 5.0                   | 28.3 ± 1.4c  | 25.6 ± 1.6b |
| III   | 5.0                   | 26.5 ± 1.4abc| 24.2 ± 0.7c |
| IV    | 4.1                   | 25.1 ± 1.1abc| 20.8 ± 0.7a |
| V     | 4.8                   | 26.8 ± 0.4abc| 19.5 ± 2.6b |
| VI    | 4.0                   | 24.8 ± 0.9abc| 12.5 ± 0.6a |
| VII   | 5.0                   | 24.1 ± 0.9a  | 15.6 ± 1.1a |

Within the same column, the means with the same superscript letters are not statistically different from one another ($P>.05$).

**DISCUSSION**

Screw loosening is caused by an inappropriate tightening torque, the surface sinking phenomenon, screw deformation and preload loss due to overload, and vibration due to the functional load. The preload, which is a compressed force that occurs between the abutment and the fixture due to the tightening torque, increases as the tightening torque increases and the friction coefficient of the screw decreases. If the tightening torque is applied to the abutment screw, or if the external load is applied to the implant superstructure, the surface roughness wear is smoothed due to the compressed force. This settling effect reduces the preload, which leads to screw loosening. To compensate for the preload loss caused by surface sinking, in actual clinical practice, the tightening torque must be applied again 10 minutes after a new screw is fastened, and the tightening torque must be regularly and repeatedly applied after the functioning of the implant prosthesis. In this study, based on previous reports, the tightening torque was repeatedly applied 10 minutes after the screw was fastened, and after 10,000 cycles of repeated loads to compensate for the surface sinking caused by the functional load.

For the external butt joint connection type, the stress caused by all the external loads, except for the tightening torque and the load of the implant major axis, is applied to the screw. The external hexagon of the external butt joint was developed to provide the abutment direction upon the fixture installation and the superstructure manufacturing, and it was difficult to achieve resistance against the lateral force. In addition, the fulcrum length for the lateral force was longer compared to the internal cone connection type, and most external hexagons have a gap in the hexagon between the abutment and the fixture, and mainly depend on the friction caused by the preload for the torsion stress. Therefore, it is very important to apply the appropriate preload to stabilize the connection parts in the external butt joint.

On the other hand, in the internal-cone-connection-type implant system, the tightening torque is driven by not...
only the screw height but also the wedge effect due to the conical abutment sinking, and the load is mainly supported by the internal slope of the fixture. Therefore, the stress that occurs in the abutment screws has been known to be relatively smaller than that in the external butt joint. In the internal cone implant system, however, the tensile force of the abutment screw, that is, the preload, was reported to have been slightly reduced due to the slight sinking of the abutment caused by the vertical component of the load. In the external butt joint implant system, the preload loss was reported to have been relatively smaller due to the vertical support of the upper fixture.

Despite the same internal cone connection type, in the SSII system that was used in this study, unlike in the GSII system, as the upper shoulder of the fixture collar came in contact with the superstructure, and thus acquired additional support against the vertical load, the abutment sinking became relatively restricted. In this study, however, the load support effect of the aforementioned shoulder was not achieved due to the different study method. Therefore, this restriction should be considered when the results of this study are interpreted.

The preload, which is a contributing factor to the stability of the screw connection parts, is affected by various factors associated with the elongation of the abutment screw. The measurement of the removal torque of the abutment screw is one of the methods for indirect comparison of preloads. By measuring the initial removal torque, the reductions in the degree of the preload caused by the tightening torque can be compared. The factors that affect the initial removal torque include friction, surface sinking, and abutment sinking. By measuring the removal torque and calculating the loss rate after the repeated loads that are clinically more important, the reduced preloads due to the external load, that is, the joint stability against the functional load, can be indirectly compared. The joint stability against the functional load is affected by the surface sinking of the implant system, the joint micro-movement, the abutment screw deformation, and the abutment sinking.

In this study, the initial removal torque was higher in the USII system than in the GSII and SSII systems for both the regular and wide diameters. This is because more preload might have been occurred in the USII system with the external butt joint connection type, which may have led to increased friction. The compressed force was higher in the external butt joint, wherein the tightening torque was mainly converted into the compressed force via the screw elongation, than in the internal cone when the same torque was applied.

On the other hand, unlike previous study results in which the joint stability was superior in the internal cone than in the external butt joint, the postload removal torque loss was lowest in the USII system for both the regular and wide diameters, and increased in the order of the SSII system and the GSII system, although the difference was not statistically significant. The aforementioned difference in the results is likely to be attributable to the experimental devices or load point and differences in the load condition such as the repeated load number. Further verification is required. In this study, the high removal torque loss in the internal cone connection type was mainly attributable to the preload loss caused by the abutment sinking. The removal torque loss was lower in the SSII system than in the GSII system, although both systems were of the internal cone connection type. The aforementioned result is likely to be attributable to the one-stage implant with a 1.8 mm collar reduced fulcrum length.

Theoretically, if the implant system diameter increases, the preload loss caused by the bending load during the functional movement relatively decreases due to the increased area between the abutment and the fixture. It was reported that the joint opening due to the fulcrum load was lower in the wide-diameter implant system than in the regular-diameter implant system in a repeated load experiment in which a strain gauge was used. When the fulcrum load at the upper fixture was applied to a 10 mm-tall metal tube, the external force that was applied to the abutment screw was calculated in the moment form using the following formula:

\[
F_s = \frac{[(F_h \times 10) - (F_v \times L_v)]}{(0.5 \times d)}
\]

wherein \(F_s\) is the external force applied to the abutment screw, \(F_h\) is the horizontal component of the load, \(F_v\) is the vertical component of the load, \(L_v\) is the distance from the vertical component of the load to the fulcrum point, and \(d\) is the fixture diameter.

Theoretically, the external force applied to the abutment screw decreases as the fixture diameter increases. In the comparison of the implant diameters in this study, no significant difference in the postload removal torque loss was found between the USII and SSII systems. The reason for the lack of reduction of the loss in the USII and SSII systems despite the increased diameter is unclear. In this study, a 30 Ncm tightening torque was applied in the USII system with a wide diameter, as in the other test groups, despite its larger abutment screw diameter. If the abutment screw diameter increases, relatively less screw elongation could occur when the same tightening torque is applied. Therefore, it is likely that the preload loss due to the surface sinking caused by the tightening torque and the repeated load could occur more in the wide-diameter implant system with less screw elongation, and result in the partial removal of the moment reduction effect caused by the increased diameter. The relatively increased lateral wall thickness is likely to be attributable to the reduction in the removal torque loss in the wide-diameter GSII system.

Platform-switching has been reported to reduce marginal bone resorption by concentrating the stress more internally during the dynamic function, in addition to the biological effects that are achieved by placing the fixture-abutment connection more internally. The results of this study showed, however, no significant differences in the removal torque and the loss rate after repeated loads between
Group III, which corresponded to the platform-switching USII system, and Group II, which corresponded to the wide-diameter USII system. The aforementioned result indicates that no significant difference in the external force applied to the abutment screw was found, as platform-switching uses an abutment with the same diameter shown in a finite element analysis, in which no significant differences in the stress distribution and the joint opening were found according to the platform-switching.

In this study, the screw joint stability was indirectly compared via the removal torque loss after repeated loads. Unlike in the external butt joint wherein the joint stability is wholly maintained by the preload caused by the tensile force of the abutment screw, the internal cone connection type achieved additional joint stability from the wedge effect caused by the abutment sinking and the screw preload. Therefore, it is more appropriate to interpret the results of this study by restricting them to the screw loosening of the abutment rather than to directly associating them with the clinical failure of the fixture-abutment connection. In addition, a further comparative study on the wedge effect of the internal-cone-connection-type on the joint stability is required.

CONCLUSION

In this study, the results of this study showed that the external butt joint was more advantageous than the internal cone in terms of the postload removal torque loss. For the difference in the implant diameter, a wide diameter was more advantageous in terms of the torque loss rate. The results of this study showed that the implant-abutment connection design and diameter affect the screw joint stability. As preload loss due to the functional load could occur in any implant system, regular examination and the re-torque process for an appropriate tightening torque are required.

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