Research Article

Uniform Bounds of Aliasing and Truncated Errors in Sampling Series of Functions from Anisotropic Besov Class

Peixin Ye and Yongjie Han
School of Mathematics and LPMC, Nankai University, Tianjin 300071, China

Correspondence should be addressed to Peixin Ye; yepx@nankai.edu.cn

Received 1 May 2013; Accepted 11 June 2013

1. Introduction
Since Shannon introduced the sampling series in the landmark paper [1], the Shannon sampling theorem has been a fundamental result in the field of information theory, in particular telecommunications and signal processing; see [2–7] and the references therein. The theorem states that a bandlimited signal can be exactly recovered from an infinite sequence of its samples if the bandlimit is no greater than half the sampling rate. The theorem also leads to a formula for reconstruction of the original function from its samples. When the function is not bandlimit, the reconstruction exhibits imperfections known as aliasing. Moreover, in practice, the signal and the sampled values are not the accurate functional values. So several types of errors such as aliasing errors, truncated errors, jitter errors, and amplitude errors appear when the Shannon sampling series is applied to approximate a signal in real life. These types of errors have been widely studied under the assumption that signals satisfy some decay conditions at infinity; see [8–13]. On the other hand, one can avoid assumptions upon the decay rate of the initial signals by using localized sampling; see [14–19]. Recently the uniform bounds for truncated Shannon series based on local sampling are derived for nonbandlimited functions from Sobolev classes without decay assumption; see [18, 19]. In this paper we study errors in truncated multivariable Shannon sampling series via localized sampling by considering nonbandlimited functions from anisotropic Besov classes.

It is well known that the sampling theorem is usually formulated for functions of a single variable. Consequently, the theorem is directly applicable to time-dependent signals. However, the sampling theorem can be extended in a straightforward way to functions of arbitrarily many variables. The multivariable sampling theorem can be used in the reconstruction of some types of images such as gray-scale images.

We begin our discussion with the definitions of some function spaces. Let \( L_p(\mathbb{R}^d) \), \( 1 \leq p \leq \infty \), be the space of all \( p \)th power Lebesgue integrable functions on \( \mathbb{R}^d \) equipped with the usual norm

\[
\|f\|_{L_p} := \left( \int_{\mathbb{R}^d} |f(t)|^p \, dt \right)^{1/p}
\]

for \( 1 \leq p < \infty \) and

\[
\|f\|_{L_{\infty}} := \text{ess sup}_{t \in \mathbb{R}^d} |f(t)|.
\]

Set \( Z_d = \{1, 2, \ldots, d\} \). For any vector \( \mathbf{v} := (v_j : j \in Z_d) \) with positive coordinates we say an entire function \( h \) is of
exponential type $v$ provided that for every $\varepsilon > 0$ there exists a positive number $c$ such that for all complex vectors $z := (z_j : j \in \mathbb{Z}_d) \in \mathbb{C}^d$ we have the bound

$$|h(x)| \leq c \exp \left( \sum_{j \in \mathbb{Z}_d} (v_j + \varepsilon) |z_j| \right).$$

Denote by $E_v(\mathbb{C}^d)$ the space of all entire functions of exponential type $v$. Let $B_v(\mathbb{R}^d)$ be the subset of $E_v(\mathbb{C}^d)$ which are bounded on $\mathbb{R}^d$. Set

$$B^p_v(\mathbb{R}^d) := B_v(\mathbb{R}^d) \cap L_p(\mathbb{R}^d), \quad 1 \leq p \leq \infty.$$ (4)

Every vector $v = (v_j : j \in \mathbb{Z}_d) \in \mathbb{R}^d$ determines the rectangle

$$I^d_v := \prod_{j \in \mathbb{Z}_d} [-v_j, v_j].$$ (5)

According to the Schwartz theorem [20],

$$B^p_v(\mathbb{R}^d) = \{ f \in L_p(\mathbb{R}^d) : \text{supp } \hat{f} \subseteq I^d_v \},$$ (6)

where $\hat{f}$ is the Fourier transform of $f$ in the sense of distribution. For the case $p = 2$, it is the classical Paley-Wiener theorem.

Now we define anisotropic Besov space. Suppose that $k \in \mathbb{N}$ and $t \in \mathbb{R}^d$. For $f \in L_p(\mathbb{R}^d)$, we define the $k$th partial difference of $f$ in the $l$th coordinate direction $e_l$ at the point $t \in \mathbb{R}^d$ with step $x_l \in \mathbb{R}$ by the formula

$$\Delta^k_{x_l} f (t) = \sum_{i=1}^{k} (-1)^{i+k} \binom{k}{i} f(t + ix_l e_l).$$ (7)

Let $l = (l_1, \ldots, l_d) \in \mathbb{N}^d$, $r = (r_1, \ldots, r_d) \in \mathbb{R}^d$, and $l_i > r_i$ for $i \in Z_d, 1 \leq p$, and $\theta \leq \infty$. We say $f \in B^p_v(\mathbb{R}^d)$ if $f \in L_p(\mathbb{R}^d)$, and the following seminorm is finite:

$$\|f\|_{B^p_v} := \left\{ \begin{array}{ll}
\left( \int_{\mathbb{R}^d} \left( \frac{\|\Delta^l_{x_l} f\|_{L_p}^\theta}{|x_l|^{\alpha \\ (1+\theta)}} \right) dx_l \right)^{1/\theta}, & 1 \leq \theta < \infty, \\
\sup_{|x_l| \neq 0} \frac{\|\Delta^l_{x_l} f\|_{L_p}}{|x_l|^\alpha}, & \theta = \infty,
\end{array} \right. \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad \quad i = 1, \ldots, d.$$ (8)

The linear space $B^p_v(\mathbb{R}^d)$ is a Banach space with the norm

$$\|f\|_{B^p_v} := \|f\|_{L_p} + \sum_{i \in \mathbb{Z}_d} \|f\|_{B^p_v}$$ (9)

and is called an anisotropic Besov space. We introduce the notation $g(r) = (\sum_{j=1}^{d} (1/r_j))^{-1}$ which plays an important role in our error estimates. In this paper, we assume $g(r) > 1/p$, which ensures that $B^p_v(\mathbb{R}^d)$ is embedded into $C(\mathbb{R}^d)$ by a Sobolev-type embedding theorem, and therefore function values are well defined; see [20].

Now we make some illustrations about why we choose Besov spaces as the hypothesis function spaces; that is, why we assume the signals come from Besov spaces. Firstly in studying the aliasing errors for nonbandlimited functions, one often uses Lipschitz or Sobolev regularity to replace the strong bandlimited assumption. In this way one can derive some reasonable convergence rates as the distance between the sampling periods tends to zero. However the aliasing and truncation errors by local sampling for these nonbandlimited functions have not been thoroughly studied. In particular errors by localized sampling approximation for these spaces of functions with measured values have never been considered. In this paper, using the tools in the study of mean $\sigma$-dimension width for Besov classes and the related imbedding theorems, we can consider anisotropic Besov spaces which include Lipschitz or Sobolev spaces as special cases. Thus our results immediately lead to the results for these two types of hypothesis function spaces. Of course the results on these two spaces are also novel. On the other hand, from the viewpoint of approximation theory it is worth studying the Besov class, since the best possible orders of approximation by bandlimited functions are known for Besov classes from the corresponding results of mean $\sigma$-dimension width theory. Note that a convergent Shannon series is a bandlimited function. So it is natural to ask if one can use Shannon interpolation formula to realize the best approximation for these spaces. In what follows we will give an affirmative answer to this question.

By the way for later use we recall the classical Sobolev space $W^p_v(\mathbb{R}^d)$ which consists of functions $f \in L_p(\mathbb{R}^d)$ such that for all multi-index vector $l = (l_1, \ldots, l_d) \in \mathbb{N}^d$, with $|l| = \sum_{j=1}^{d} l_j \leq r$, the distributional partial derivative

$$\partial^l f := \partial^{\|l\|} f$$ (10)

belongs to $L_p(\mathbb{R}^d)$.

The remaining part of this paper is organized as follows. In Section 2, we consider errors in truncated Shannon sampling series with exactly functional values based on localized sampling. In Section 3 we firstly generalize part of the results in Section 2 to the sampling series with measured sampled values and then give some applications.

In what follows, let $k$, $t$, and so forth denote vector variables living in $\mathbb{R}^d$, and write $k/v := (k_1/v_1, \ldots, k_d/v_d)$ and $v \cdot t := (v_1 t_1, \ldots, v_d t_d)$. We use the same symbol $C$ for possibly different positive constants. These constants are independent of $N \in \mathbb{N}^d$ and $v \in \mathbb{R}^d$. Denote by $[x]$ the largest integer not exceeding $x$.

### 2. The Exactly Functional Values Case

The famous Shannon sampling theorem states every function $f \in B^p_v(\mathbb{R})$ can be completely reconstructed from its sampled
values taken at instances \([k/v]\) \(k \in \mathbb{Z}\) (cf. [1]). In this case the representation of \(f\) is given by

\[
f(t) = (S_f)(t) = \sum_{k=-\infty}^{+\infty} f \left( \frac{k}{v} \right) \text{sinc}(vt - k),
\]

(11)

where \(\text{sinc}(t) = \sin \pi t/\pi t, \ t \neq 0,\) and \(\text{sinc}(0) = 1\). Series (11) converges absolutely and uniformly on \(\mathbb{R}\).

In [10], the authors establish multidimensional Shannon sampling theorem by extending (11) to the case \(f \in B^p_{\infty}(\mathbb{R}^d)\), \(1 < p < \infty\), and \(d > 1\). They obtained the following theorem.

**Theorem A.** Let \(f \in B^p_{\infty}(\mathbb{R}^d)\), \(1 \leq p < \infty\). Then for any \(t \in \mathbb{R}^d\)

\[
f(t) = (S_f)(t) := \sum_{k \in \mathbb{Z}^d} f \left( \frac{k}{v} \right) \text{sinc}(v \cdot t - k),
\]

(12)

where \(\text{sinc}(t) = \prod_{i=1}^{d} \text{sinc}(t_i)\). The series on the right-hand side of (12) converges absolutely and uniformly on \(\mathbb{R}^d\).

Shannon's expansion requires us to know the exact values of a signal \(f\) at infinitely many points and to sum an infinite series. In practice, only finitely many samples are available, and hence the symmetric truncation error

\[
\left| f(t) - \sum_{|k| \leq N_0} \cdots \sum_{|k| \leq N_1} f \left( \frac{k}{v} \right) \text{sinc}(v \cdot t - k) \right|
\]

(13)

has been widely studied under the assumption that \(f\) satisfies some decay condition. Among others, in [11] the uniform truncation error bounds are determined for \(f \in B^p_{\infty}(\mathbb{R})\) with a decay condition. In [12] the uniform bounds of truncation error and aliasing error are derived for functions belonging to the Besov class \(B^p_{\infty}(\mathbb{R}^d)\) with the same decay condition as in [11]. Since their results are the motivations of our works, we restate them as follows. Throughout the paper we denote the unit ball of the space \(B^p_{\infty}(\mathbb{R}^d)\) by \(\mathcal{H}(B^p_{\infty}(\mathbb{R}^d))\).

**Theorem B** (see [12]). Let \(f \in \mathcal{H}(B^p_{\infty}(\mathbb{R}^d))\), \(1 \leq \theta \leq \infty\), and \(r \in \mathbb{R}^d\) satisfy the decay condition inequality

\[
|f(t)| \leq \frac{A}{(1 + |t|^2)^{\delta}},
\]

(14)

where \(A > 0\) and \(0 < \delta \leq 1\) are constants and \(|t|^2 = (t_1^2 + \cdots + t_d^2)^{1/2}\). For \(\sigma > 0\) define the associated \(v = (v_1, \ldots, v_d)\) by setting \(v_j = \sigma^{(\theta)/r_j}\) for \(j \in Z_d\). If \(v_j > (1/2)e^{2i/3}\) for \(i \in Z_d\), then

\[
|f(t) - (S_tf)(t)| \leq C \cdot \sigma^{-g(t)} \ln^d \sigma.
\]

(15)

**Theorem C** (see [12]). Let \(f \in \mathcal{H}(B^p_{\infty}(\mathbb{R}^d))\), \(1 \leq \theta \leq \infty\), satisfy the decay condition (14). Then for any \(N = (N_1, \ldots, N_d) \in \mathbb{N}^d\) with \(N_i > (1/2)e^{2i/3}\), \(i = 1, \ldots, d\), one has

\[
\left| f(t) - \sum_{i=1}^{d} f \left( \frac{k}{v} \right) \text{sinc}(v \cdot t - k) \right| \leq C \left( \sum_{i=1}^{d} \ln N_i \right)^{d-1 + (n/\sigma)} n_i.
\]

(16)

Now we truncate the series on the right-hand side of (12) based on localized sampling. That is, if we want to estimate \(f(t)\), we only sum over values of \(f\) on a part of \(\mathbb{Z}^d/v\) near \(t\). Thus for any \(N \in \mathbb{N}^d\) we consider the finite sum

\[
(S_{v,N}f)(t) := \sum_{k \in \mathbb{Z}^d} f \left( \frac{k}{v} \right) \text{sinc}(v \cdot t - k)
\]

(17)

as an approximation to \(f(t)\). In this way we can derive the uniform bounds for the associated truncation error

\[
(E_{v,N}f)(t) := f(t) - (S_{v,N}f)(t)
\]

(18)

and aliasing error

\[
|f(t) - (S_vf)(t)|
\]

(19)

without any assumption about the decay of \(f \in \mathcal{H}(B^p_{\infty}(\mathbb{R}^d))\).

Our main result of this section is the following uniform bound of the aliasing error

\[
|f(t) - (S_vf)(t)|.
\]

(20)

**Theorem 1.** Let \(f \in \mathcal{H}(B^p_{\infty}(\mathbb{R}^d))\) with \(1 < p < \infty\), \(1 \leq \theta \leq \infty\), and \(r_i > d\) for \(i \in Z_d\). For \(\sigma > e\), define \(v \in \mathbb{R}\) in the same manner as in "Theorem B"; then one has

\[
|f(t) - (S_vf)(t)| \leq C \cdot \sigma^{-g(t)+1/p} \ln^d \sigma.
\]

(21)

We firstly note that due to the localized sampling the function in Theorem 1 does not need to satisfy any decay assumption at infinity. Next we make a comment on the bound \(\sigma^{-g(t)+1/p} \ln^d \sigma\). It is known from the results of mean \(\sigma\)-dimension Kolmogorov widths for Besov class \(\mathcal{H}(B^p_{\infty}(\mathbb{R}^d))\) that

\[
\inf_{g \in \mathcal{H}(\mathbb{R}^d)} \sup_{f \in \mathcal{H}(B^p_{\infty}(\mathbb{R}^d))} \|f - g\|_{\infty} \geq C \sigma^{-g(t)+1/p}.
\]

(22)

Thus the bound in Theorem 1 is optimal up to the logarithmic factor \(\ln^d \sigma\); see [21]. As a consequence of Theorem 1, we show that, using truncated sampling series (17), we can still achieve this near optimal bound.
Theorem 2. Let \( f \in \mathcal{U}(B^p_{p\theta}(\mathbb{R}^d)) \), with the same \( p, \theta, \) and \( r \) as in Theorem 1. For \( \sigma > e \), define \( v \) as in Theorem B. Then for \( N = (N_1, \ldots, N_d) \in \mathbb{N}^d \) with \( N_j = \lfloor (g^{(r_j)})^p \rfloor + 1 \), one has
\[
(E_{rN}f)(t) \leq C \cdot \sigma^{-g(r+1)/p} \ln \sigma. \tag{23}
\]

To prove Theorem 1 we will choose an intermediate function which is a good approximation for both \( f \) and \( S_k f \). Now we describe how to choose this function. For more details, one can see [21, 22].

For any positive real number \( u > 0 \), we define the function
\[
g_u(x) = A_u (\text{sinc} \pi^{-1} ux)^{2s}, \quad x \in \mathbb{R}, 2s > 1, \tag{24}
\]
where the constant \( A_u \) is taken such that \( \int_{\mathbb{R}} g_u(x)dx = 1 \).

Suppose \( u_j > 0 \), \( j \in Z_d \). For any \( f \in B^p_{p\theta}(\mathbb{R}^d) \), set
\[
\left( T^a_{u_j} f \right)(t) := \int_{\mathbb{R}} g_{u_j}(x_j) \left( (-1)^{j+1} \left( \Delta_{x_j}^l \right) f \right)(t) + f(t) \; dx_j
\]
\[
= \int_{\mathbb{R}} g_{u_j}(x_j) \sum_{i=1}^{l_j} d_i f \left( t_1, \ldots, t_{j-1}, t_j + ix_j, t_{j+1}, \ldots, t_d \right) dx_j, \tag{25}
\]
where \( \sum_{i=1}^{l_j} d_i = 1 \).

When \( t \in \mathbb{R} \) and \( j \in Z_d \), we let
\[
G_{u_j}(x) := \sum_{i=1}^{l_j} d_i \frac{g_{u_j}(x_i)}{i} \tag{26}
\]
and observe from formulas (25) and (26) that \( T^a_{u_j} \) has the alternative representation
\[
\left( T^a_{u_j} f \right)(t) := \int_{\mathbb{R}} G_{u_j}(x_j) f \left( t + ix_j e_j \right) dx_j, \quad x \in \mathbb{R}^d. \tag{27}
\]
We define the value of a kernel \( G_u \) at \( x := (x_1, x_2, \ldots, x_d) \) by
\[
G_u(x) := \prod_{i \in \mathbb{Z}^d} G_{u_i}(x_i) \tag{28}
\]
and introduce the operator
\[
T^a_u := T^a_{u_1} \circ \cdots \circ T^a_{u_d}. \tag{29}
\]
Consequently, \( T^a_u \) is given by
\[
\left( T^a_u f \right)(t) = \int_{\mathbb{R}^d} G_u(x) f(t + x) \; dx, \quad t \in \mathbb{R}^d. \tag{30}
\]
It is known from [20] that \( T^a_u f \in B^p_{2\theta p}(\mathbb{R}^d) \). We will exploit the following properties of \( T^a_u f \) in the proof of Theorem 1.

Lemma 3. Let \( f \in \mathcal{U}(B^p_{p\theta}(\mathbb{R}^d)) \), \( 1 \leq p \), and \( \theta \leq \infty \). For \( \sigma > 0 \), define \( u \in \mathbb{R}^d \) with \( u_j = g^{(r_j)} \), for \( j \in Z_d \); then one has
\[
\| f - T^a_u f \|_{L^p} \leq C \cdot \sigma^{-g(r+1)/p}. \tag{31}
\]

Proof. When \( p = \infty \), the inequality was proved in [12]. By the imbedding relationship
\[
\mathcal{U}(B^p_{p\theta}(\mathbb{R}^d)) \subset C \cdot \mathcal{U}(B^{p'}_{\infty}(\mathbb{R}^d)), \tag{32}
\]
where \( p' = (1 - (1/p)\sum_{j=1}^{d} (1/r_j))p \) (see [20] for more details) we can derive the corresponding inequalities for the case \( 1 \leq p < \infty \) from that of \( p = \infty \).

Lemma 4 (see [22]). If \( f \in L_p(\mathbb{R}^d) \), \( 1 \leq p \leq \infty \), and \( u \in \mathbb{R}^d \), then
\[
\| T^a_u f \|_{L^p} \leq 2^n \| f \|_{L^p}, \tag{33}
\]
where \( \alpha := \sum_{k \in Z_d} l_k \).

For \( 1 \leq p < \infty \), let \( l^p(\mathbb{Z}^d) \) be the Banach space of all infinite bounded \( p \)-summable sequences \( y = \{ y_k \}_{k \in \mathbb{Z}^d} \) such that the norm
\[
\| y \|_p := \left( \sum_{k \in \mathbb{Z}^d} |y_k|^p \right)^{1/p} \tag{34}
\]
is finite.

Lemma 5 (see [10]). Let \( y = \{ y_k \} \in l^p(\mathbb{Z}^d) \), \( 1 < p < \infty \). Then the series
\[
L_y(y,t) := \sum_{k \in \mathbb{Z}^d} y_k \text{sinc} (v \cdot t - k) \tag{35}
\]
converges uniformly on \( \mathbb{R}^d \) to a function in \( B^p_{\infty}(\mathbb{R}^d) \).

We also need the following bound for sinc series:
\[
\left( \sum_{k \in \mathbb{Z}^d} |\text{sinc} (v \cdot t - k)|^q \right)^{1/q} \leq \left( \frac{q}{q-1} \right)^d \tag{36}
\]
for \( d \geq 1 \), \( q > 1 \), \( v = (v_1, \ldots, v_d) \), and \( v_i > 1 \), \( i = 1, \ldots, d \).

For \( f \in B^p_{\infty}(\mathbb{R}^d) \), one has the following Marcinkiewicz-type inequality.

Lemma 7 (see [20, 23]). Let \( f \in B^p_{\infty}(\mathbb{R}^d) \), \( 1 < p < \infty \). Then one has
\[
\left( \prod_{i=1}^{d} v_i^{-1} \sum_{k \in \mathbb{Z}^d} \left| f \left( \frac{k}{v} \right) \right|^p \right)^{1/p} \leq C \| f \|_{L^p}. \tag{37}
\]

The next lemma presents a Marcinkiewicz-type inequality for functions from Sobolev spaces.
Lemma 8 (see [10]). Let \( f \in W^l_p(\mathbb{R}^d) \), \( 1 \leq p < \infty \), and \( l \geq d \). Then
\[
\left( \frac{1}{|k|} \sum_{k \in \mathbb{Z}^d} \left| f \left( \frac{k}{v} \right) \right|^p \right)^{1/p} \leq C \left( \|f\|_{L_p} + \frac{1}{v} \sum_{i=1}^d \left\| \frac{\partial f}{\partial x_i} \right\|_{L_p} \right)
\]
\[
+ \sum_{1 \leq j < q} \frac{1}{v_j} \left\| \frac{\partial^2 f}{\partial x_i \partial x_j} \right\|_{L_p} \)
\]
\[
+ \cdots + \frac{1}{v_{i_1}} \left\| \frac{\partial^{i_1} f}{\partial x_{i_1} \cdots \partial x_{d}} \right\|_{L_p} \right).
\]

Lemma 9 (see [20, 24]). Let \( l = (l_1, \ldots, l_d) \in \mathbb{N}^d \), \( r = (r_1, \ldots, r_d) \in \mathbb{R}^d \), \( 1 \leq p, \theta \leq \infty \), \( 1 - \sum_{i=1}^d l_i/r_i > 0 \), and \( r' := (1 - \sum_{i=1}^d l_i/r_i) r \). For \( f \in B^{l_p}(\mathbb{R}^d) \), it follows that there exists a constant \( C \) depending on \( r, r', p, \) and \( \theta \) but independent of \( f \), such that
\[
\left\| \frac{\partial^{|l|} f}{\partial x^{|l|}} \right\|_{B_r^p} \leq C \|f\|_{B_r^p}.
\]

Proof of Theorem 1. It is known from Lemma 9 (letting \( l_i = 1 \) for \( i \in Z_d \)) that the fact \( f \in H(B^{p_0}(\mathbb{R}^d)) \) with \( r_i > d, i \in Z_d \) implies \( f \in W^d_p(\mathbb{R}^d) \); therefore by Lemma 8
\[
\left\| f \left( \frac{k}{v} \right) \right\|_{L^p} \leq C a^{1/p}.
\]
And hence by Lemma 5,
\[
(S_v f)(t) = \sum_{k \in \mathbb{Z}^d} f \left( \frac{k}{v} \right) \text{ sinc}(v \cdot t - k)
\]
converges uniformly on \( \mathbb{R}^d \).

Set \( u = \sqrt{2} s \) and \( 2s > d + \max\{|r_i|, i = 1, \ldots, d\} \). So \( T^u_v f \in B^p_r(\mathbb{R}^d) \) as mentioned above. By Theorem A we have \( T^u_v f = S_v(T^u_v f) \).

Thus
\[
(T^u_v f)(t) - (S_v f)(t) = \sum_{k \in \mathbb{Z}^d} \left( T^u_v f \left( \frac{k}{v} \right) - f \left( \frac{k}{v} \right) \right) \text{ sinc}(v \cdot t - k).
\]

Using the triangle inequality we obtain
\[
|f(t) - (S_v f)(t)|
\]
\[
\leq |f(t) - (T^u_v f)(t)| + |(T^u_v f)(t) - (S_v f)(t)| \]
\[
\leq |f(t) - (T^u_v f)(t)| + |S_v(T^u_v f - f)(t)|
\]
\[
+ |S_v(T^u_v f - f)(t) - S_v(T^u_v f - f)(t)|.
\]

By Lemma 3,
\[
|f(t) - (T^u_v f)(t)| \leq C a^{-g(|t|)1/p}.
\]

It is clear that
\[
|S_v(T^u_v f - f)(t)|
\]
\[
= \left| \sum_{v \cdot t \in k \cap \mathbb{N}^d} (T^u_v f - f) \left( \frac{k}{v} \right) \text{ sinc}(v \cdot t - k) \right|.
\]

Applying Hölder’s inequality with exponent \( p_0 \), we get
\[
|S_v(T^u_v f - f)(t)|
\]
\[
\leq \left( \sum_{v \cdot t \in k \cap \mathbb{N}^d} \left| (T^u_v f - f) \left( \frac{k}{v} \right) \right|^{p_0} \right)^{1/p_0}
\]
\[
\cdot \left( \sum_{v \cdot t \in k \cap \mathbb{N}^d} \left| \text{ sinc}(v \cdot t - k) \right|^{q_0} \right)^{1/q_0}
\]
\[
\leq C \left( \prod_{i=1}^d 2^{N_i + 1} \right)^{1/p_0} a^{-g(|t|)1/p} \cdot p_0^d,
\]
where \( 1/p_0 + 1/q_0 = 1 \), and the second inequality follows from (44) and Lemma 6.

Next we estimate \( |S_v(T^u_v f - f)(t) - S_v(N(T^u_v f - f)(t))| \). By Hölder’s inequality,
\[
|S_v(T^u_v f - f)(t) - S_v(N(T^u_v f - f)(t))|
\]
\[
\leq \left( \sum_{v \cdot t \in k \cap \mathbb{N}^d} \left| (T^u_v f - f) \left( \frac{k}{v} \right) \right|^{p_0} \right)^{1/p}
\]
\[
\cdot \left( \sum_{v \cdot t \in k \cap \mathbb{N}^d} \left| \text{ sinc}(v \cdot t - k) \right|^{q_0} \right)^{1/q}
\]
\[
\leq \left( \prod_{i=1}^d 2^{N_i + 1} \right)^{1/p} a^{-g(|t|)1/p} \cdot p_0^d,
\]
where \( 1/p + 1/q = 1 \).

By Lemma 7 and Lemma 4, we obtain
\[
\left\| \left( T^u_v f \right) \left( \frac{k}{v} \right) \right\|_{L_p} \leq C a^{1/p} \|T^u_v f\|_{L_p}
\]
\[
\leq C a^{1/p} \|f\|_{L_p} \leq C a^{1/p}.
\]

It follows from (40), (48), and Minkowski inequality
\[
\left\| \left( T^u_v f - f \right) \left( \frac{k}{v} \right) \right\|_{L_p} \leq C a^{1/p}.
\]

Set \( h(t) := \sum_{v \cdot t \in k \cap \mathbb{N}^d} \left| \text{ sinc}(v \cdot t - k) \right|^{1/q} \). Note that \( h(t + m/v) = h(t) \), for all \( t \in \mathbb{R}^d \) and \( m \in \mathbb{Z}^d \). Thus to give an upper estimate for \( h(t) \) on \( \mathbb{R}^d \), we only need to bound it on \( \prod_{i=1}^d [0, 1/v_i] \). Note that
\[
\left\{ k : k \notin l^d \right\} \subset \bigcup_{i=1}^d \left\{ k : k_i \notin [-N_i, N_i] \right\}.
\]
A straightforward computation shows that for \( t_i \in [0, 1/v_i] \)

\[
\left( \sum_{k \in \mathbb{Z}} \left| \text{sinc}(v_i t_i - k) \right|^q \right)^{1/q} \\
\leq \left( C \sum_{k \in (-N_i, N_i]} \frac{1}{|k|^q} \right)^{1/q} \\
\leq \left( C \int_{N_i}^{\infty} t^{-q} \right)^{1/q} \\
\leq CN_i^{-1/p}.
\]

Therefore

\[
|S_v(T^d_u f - f)(t) - S_{v,N}(T^d_u f - f)(t)| \leq C \sigma^{1/p} \left( \sum_{i=1}^{d} N_i^{-1/p} \right).
\]

It follows from (46) and (52) that

\[
|(T^d_u f - S_v f)(t)| \\
\leq C \left( \prod_{i=1}^{d} (2N_i + 1) \right)^{1/p} \sigma^{-g(\tau)+1/p} P_0^d + \sigma^{1/p} \left( \sum_{i=1}^{d} N_i^{-1/p} \right).
\]

We choose \( N_i = [(\sigma^{g(\tau)})^p + 1] \) and \( P_0 = \sum_{i=1}^{d} \ln(2N_i + 1) \). It is easy to see that \( P_0 > 1 \) and \( \left( \prod_{i=1}^{d} (2N_i + 1) \right)^{1/p} = e \). A simple computation gives

\[
P_0^d \leq C \left( \ln \prod_{i=1}^{d} N_i \right)^d \leq C \ln^d \sigma.
\]

Note that \( N_i \geq \sigma^{g(\tau)/p} \). Thus we have

\[
\sum_{i=1}^{d} N_i^{-1/p} \leq C \sigma^{-g(\tau)}.
\]

Collecting the above results we obtain

\[
|(T^d_u f)(t) - (S_v f)(t)| \leq C \cdot \sigma^{-g(\tau)+1/p} \ln^d \sigma.
\]

Combining (44) and (56), we prove the theorem.

**Proof of Theorem 2.** By the triangle inequality, we have

\[
(E_{v,N} f)(t) \leq |f(t) - (S_v f)(t)| \\
+ |(S_v f)(t) - (S_{v,N} f)(t)|.
\]

By the arguments similar to those used in the proof of Theorem 1, we obtain

\[
| (S_v f)(t) - (S_{v,N} f)(t) | \\
\leq \left( \sum_{v+t \in \mathbb{Z}^d} \left| f \left( \frac{k}{v} \right) \right|^p \right)^{1/p} \\
\cdot \left( \sum_{v+t \in \mathbb{Z}^d} \left| \text{sinc}(v \cdot t - k) \right|^q \right)^{1/q}.
\]

where we use \( N_i = [(\sigma^{g(\tau)})^p + 1] \) in the last inequality.

Combining Theorem 1 and (58), we complete the proof of Theorem 2.

\[\square\]

### 3. The Measured Sampled Values Case

In practice, the sampled values of a signal may not be exactly the functional values and may have to be quantized. Typical errors arising from these facts are jitter errors and amplitude errors. Using the key idea of quasi-interpolation which adopts integer translations of a basic function and integer errors arising from these facts are jitter errors and amplitude errors.

In practice, the sampled values of a signal may not be exactly the functional values and may have to be quantized. Typical errors arising from these facts are jitter errors and amplitude errors. Using the key idea of quasi-interpolation which adopts integer translations of a basic function and integer errors arising from these facts are jitter errors and amplitude errors.
We write $\Omega(f, \lambda)$ for $\Omega_k(f, \lambda)$ if no confusion arises. The error modulus $\Omega(f, \lambda)$ provides a quantity for the quality of signal's measured sampling values. When the functionals in $\lambda$ are concrete, we may get some reasonable estimates for $\Omega(f, \lambda)$.

Sampling series with measured sampled values has been studied in [8] for bandlimited functions but without truncation. The truncation errors are considered for functions from Lipschitz class with a decay condition in [13]. Now we recall a typical result in [13].

Denote by $\text{Lip}_c(1; C(\mathbb{R}^d))$ the set of all continuous functions $f$ satisfying

$$|f(x) - f(y)| \leq L \left(|x_1 - y_1| + \cdots + |x_d - y_d|\right)$$

for all $x = (x_1, \ldots, x_d)$ and $y = (y_1, \ldots, y_d) \in \mathbb{R}^d$. Set $k/v := (k_1/v_1, \ldots, k_d/v_d)$, $v \cdot t := (v_1, \ldots, v_d)$, and $\|t\|_\infty := \max(t_1, \ldots, t_d)$.

**Theorem D.** Let $f \in \text{Lip}_c(1; C(\mathbb{R}^d))$ satisfy the decay condition

$$|f(t)| \leq M_f \|t\|_{\infty}^{-\gamma}, \quad \|t\|_{\infty} \geq 1,$$

for some $0 < \gamma \leq 1$. Let $\lambda = \{\lambda_k\}$ be any sequence of continuous linear functionals. For each $v \geq e^2$ one has for the truncation error at $t \in \mathbb{R}^d$

$$|f(t) - \sum_{k \in \mathbb{Z}^d, |k| \leq N} \lambda_k f \left(\frac{k}{v}\right) \text{sinc}(v \cdot t - k)| \leq C v^{-1} \ln^d v,$$

provided $N := \lfloor (v^{1/\gamma} - 1)/2 \rfloor$, where $[x]$ is the smallest integer that is greater or equal to a given $x \in \mathbb{R}$, and $\Omega(f, \lambda) \leq \omega v^{-1}$.

In [9] the author obtain the uniform bound of symmetric truncation error for functions from isotropic Besov space with a similar decay condition. Now we will provide the estimation for the truncation error

$$\left(\mathcal{E}_{v,N}^f(t)\right) := |f(t) - \left(\mathcal{S}_{v,N}^f\right)(t)|$$

without any assumption about the decay of $f \in B_{\sigma}(\mathbb{R}^d)$.

**Theorem 10.** Let $f \in \mathcal{H}(B_{\sigma}(\mathbb{R}^d))$, with the same $p$, $\theta$, and $r$ as in Theorem 1. For $\sigma > e$, define $v$ as in Theorem B. Let $\lambda = \{\lambda_k\}$ be any sequence of continuous linear functionals. For each $v$ one has

$$\left(\mathcal{E}_{v,N}^f(t)\right) \leq C \cdot \sigma^{-g(\sigma) + 1} / \ln^d \sigma,$$

provided $N_i := \lfloor \sigma^{g(\sigma) + 1} \rfloor$ and $\Omega(f, \lambda) \leq C_0 \sigma^{-g(\sigma) + 1}$ for some constant $C_0 > 0$.

**Proof.** By the triangle inequality, we have

$$\left(\mathcal{E}_{v,N}^f(t)\right) \leq |f(t) - \left(\mathcal{S}_v f\right)(t)| + \left|\left(\mathcal{S}_v f\right)(t) - \left(\mathcal{S}_{v,N}^f\right)(t)\right|$$

$$\leq |f(t) - \left(\mathcal{S}_v f\right)(t)| + I_1 + I_2,$$

where

$$I_1 := \left|\sum_{\nu \cdot k \in \Omega} f \left(\frac{k}{v}\right) \text{sinc}(v \cdot t - k)\right|,$$

$$I_2 := \left|\sum_{\nu \cdot k \in \Omega} \left(f \left(\frac{k}{v}\right) - \lambda_k f \left(\frac{\nu}{v}\right)\right) \text{sinc}(v \cdot t - k)\right|.$$

Similar to (52), we have

$$I_1 \leq C_0 \sigma^{1/p} \left(\sum_{i=1}^d N_i^{-1/p}\right).$$

Using Hölder’s inequality we obtain

$$I_2 \leq \left(\sum_{\nu \cdot k \in \Omega} \left|f \left(\frac{k}{v}\right) - \lambda_k f \left(\frac{\nu}{v}\right)\right|^{p_0}\right)^{1/p_0} \cdot \left(\sum_{\nu \cdot k \in \Omega} \left|\text{sinc}(v \cdot t - k)\right|^{q_0}\right)^{1/q_0}\left(\prod_{i=1}^d (2N_i + 1)\right)^{1/p_0} \Omega(f, \lambda) \cdot \sigma^d,$$

where $1/p_0 + 1/q_0 = 1$. Now we select the same $N_i$ and $p_0$ as in the proof of Theorem 1. Similar to (55), we have $\sum_{i=1}^d N_i^{-1/p} \leq C \sigma^{-g(\sigma) + 1}$. Thus

$$I_1 \leq C \sigma^{-g(\sigma) + 1}/p_0.$$ 

A simple computation gives $(\prod_{i=1}^d (2N_i + 1))^{1/p_0} = e$ and $p_0 \leq C \ln \prod_{i=1}^d N_i \leq C \ln \sigma$. Notice that $\Omega(f, \lambda) \leq C_0 \sigma^{-g(\sigma) + 1}$. Collecting these results, we obtain

$$I_2 \leq C \sigma^{-g(\sigma) + 1}/p_0 \ln^d \sigma,$$

which completes the proof.

Finally we apply Theorem 10 to some practical examples. The first one is that the measured sampled values are given by averages of a function. For $f \in C_0(\mathbb{R}^d)$ we define the modulus of continuity

$$\omega(f, \tau) := \sup_{|h| \leq \tau} \|f(\cdot + h) - f(\cdot)\|_{\infty},$$

where $\tau$ may be any positive number.
Corollary 11. Let \( f \in \mathcal{U}(B^p_{\rho_0}([\mathbb{R}^d]), \) with the same \( p, \theta, \) and \( r \) as in Theorem 1. For \( \sigma > e, \) define \( v, N, \) as in Theorem 10. Suppose the sampled values \( f_k \) of \( f \) are obtained by the rule
\[
f_k := \frac{1}{2\pi} \int \frac{1}{h} \int f \left( t + \frac{k}{v} \right) dt,
\]
(76)
where \( h \) are numbers satisfying \( 0 < h \leq \tau \) for all \( k \in \mathbb{Z}^d \) and \( \tau > 0. \) If \( \tau < 1/2 \) and \( \omega(f, \tau) \leq \min\{\epsilon((t-g(r)+1/p), C_0\sigma^{-g(\sigma)+1/p}) \), then
\[
(\mathcal{E}_vNf)(t) \leq C \cdot \omega(f, \tau)^{g(\sigma)-1/p} \ln^d \frac{1}{\omega(f, \tau)}.
\]
(77)
Proof. Let \( \lambda = \{\lambda_k\}_{k \in \mathbb{Z}} \) be the sequence of the linear functionals on \( C_0([\mathbb{R}^d]) \) and \( g \) a continuous function on \( \Gamma_h. \)
Define
\[
\lambda_k G := \frac{1}{2\pi} \int \frac{1}{h} \int g \left( t + \frac{k}{v} \right) dt.
\]
(78)
Then \( f_k = \lambda_k f (\cdot + k/v) \).
Clearly, \(|f(t + k/v) - f(k/v)| \leq \omega(f, \tau). \) Therefore
\[
\Omega_v(f, \lambda) = \sup_{k \in \mathbb{Z}} \left| \lambda_k f \left( t + \frac{k}{v} \right) - f \left( \frac{k}{v} \right) \right|
\]
(80)
Note that the function \( x \mapsto x^{g(\sigma)-1/p} \ln^d(1/x) \) is monotonically increasing for \( x \in (0, \epsilon((t-g(r)+1/p)) \). The corollary follows from Theorem 10.

The second example is an estimate for the combination of all four errors existing in sampling series: the amplitude error, the time-jitter error, the truncation errors, and the aliasing errors. We give some explanation for the amplitude error and the time-jitter error.

We assume the amplitude error results from quantization, which means the functional value \( f(t) \) of a function \( f \) at moment \( t \) is replaced by the nearest discrete value or machine number \( \bar{f}(t) \). The quantization size is often known before hand or can be chosen arbitrarily. We may assume that the local error at any moment \( t \) is bounded by a constant \( \epsilon > 0 \); that is, \(|\bar{f}(t) - f(t)| \leq \epsilon. \) The time-jitter error arises if the sampled instances are not met correctly but might differ from the exact ones by \( \tau' \), \( k \in \mathbb{Z}; \) we assume \(|\tau'_k| \leq \tau' \) for all \( k \) and some constant \( \tau' > 0. \) The combined error is defined to be
\[
(E_N f)(t) := f(t) - \sum_{v, t-k \in [-N, N]} \left[ \frac{1}{v} \left( k + \tau'_k \right) \right] \text{sinc}(vt - k).
\]
(81)

Corollary 12. Let \( f \in \mathcal{U}(B^p_{\rho_0}([\mathbb{R}]), 1 < p < \infty, 1 \leq \theta \leq \infty, r > 1, \) and \( v > e. \) Then
\[
\|E_N f\|_\infty \leq C \nu^{-r+1/p} \ln v,
\]
(82)
provided \( N = \lfloor v + 1 \rfloor, \) \(|f(t) - \bar{f}(t)| \leq c_1 \nu^{-r+1/p}, \) and \( \omega(f, \tau') \leq c_2 \nu^{-r+1/p}, \) where \( c_1, c_2 \) are positive constants, and \( c_1 + c_2 \leq C_0. \)

Proof. We define
\[
\lambda_k = \frac{\bar{f}(k/v + \tau'_k)}{f(k/v + \tau'_k)} \delta \left( \cdot - \tau'_k \right),
\]
(83)
where \( \delta \) is the Dirac distribution. Then \( \lambda = \{\lambda_k\}_{k \in \mathbb{Z}} \) is a sequence of linear functional on \( C_0([\mathbb{R}]). \) It is clear that \( \lambda_k f (\cdot + k/v) = \bar{f}(k/v + \tau'_k). \) Then
\[
\left| \lambda_k f \left( \cdot + \frac{k}{v} \right) - f \left( \frac{k}{v} \right) \right|
\]
(84)
Thus \( \Omega(f, \lambda) \leq C_0 \nu^{-r+1/p}. \) By Theorem 10 we get the desired result.

Acknowledgments

This work was supported by the National Natural Science Foundation of China (Grant nos. 10971251, 11101220, and 11271199) and the Program for New Century Excellent Talents at University of China (NCET-10-0513).

References

[1] C. E. Shannon, “A mathematical theory of communication,” The Bell System Technical Journal, vol. 27, pp. 379–423, 1948.
[2] P. L. Butzer, W. Engels, and U. Scheben, “Magnitude of the truncation error in sam-pling expansions of bandlimited signals,” IEEE Transactions on Acoustics, Speech, and Signal Processing, vol. 30, no. 6, pp. 906–912, 1982.
[3] A. I. Zayed, Advances in Shannon’s Sampling Theory, CRC Press, Boca Raton, FL, USA, 1993.
[4] S. D. Casey and D. E. Walnut, “Systems of convolution equations, deconvolution, Shannon sampling, and the wavelet and Gabor transforms,” SIAM Review, vol. 36, no. 4, pp. 537–577, 1994.
[5] P. L. Butzer, G. Schmeisser, and R. L. Stens, “An introduction to sampling analysis,” in Nonuniform Sampling, Theory and Practice, F. Marvasti, Ed., pp. 17–121, Kluwer Academic, New York, NY, USA, 2001.
[6] S. Smale and D.-X. Zhou, “Shannon sampling and function reconstruction from point values,” Bulletin of the American Mathematical Society, vol. 41, no. 3, pp. 279–305, 2004.
[7] S. Smale and D.-X. Zhou, “Shannon sampling. II. Connections to learning theory,” Applied and Computational Harmonic Analysis, vol. 19, no. 3, pp. 285–302, 2005.
Abstract and Applied Analysis

[8] P. L. Butzer and J. Lei, “Approximation of signals using measured sampled values and error analysis,” Communications in Applied Analysis, vol. 4, no. 2, pp. 245–255, 2000.

[9] P. X. Ye, “Error analysis for Shannon sampling series approximation with measured sampled values,” Research Journal of Applied Sciences, Engineering and Technology, vol. 5, no. 3, pp. 858–864, 2013.

[10] J. J. Wang and G. S. Fang, “A multidimensional sampling theorem and an estimate of the aliasing error,” Acta Mathematicae Applicatae Sinica, vol. 19, no. 4, pp. 481–488, 1996.

[11] X. M. Li, “Uniform bounds for sampling expansions,” Journal of Approximation Theory, vol. 93, no. 1, pp. 100–113, 1998.

[12] L. Jingfan and F. Gensun, “On uniform truncation error bounds and aliasing error for multidimensional sampling expansion,” Sampling Theory in Signal and Image Processing, vol. 2, no. 2, pp. 103–115, 2003.

[13] P. L. Butzer and J. Lei, “Errors in truncated sampling series with measured sampled values for not-necessarily bandlimited functions,” Functiones et Approximatio, vol. 26, pp. 25–39, 1998.

[14] H. D. Helms and J. B. Thomas, “Truncation error of sampling-theorem expansions,” Proceedings of The IRE, vol. 50, no. 2, pp. 179–184, 1962.

[15] D. Jagerman, “Bounds for truncation error of the sampling expansion,” SIAM Journal on Applied Mathematics, vol. 14, no. 4, pp. 714–723, 1966.

[16] C. A. Micchelli, Y. Xu, and H. Zhang, “Optimal learning of bandlimited functions from localized sampling,” Journal of Complexity, vol. 25, no. 2, pp. 85–114, 2009.

[17] A. Ya. Olenko and T. K. Pogány, “Universal truncation error upper bounds in sampling restoration,” Georgian Mathematical Journal, vol. 17, no. 4, pp. 765–786, 2010.

[18] P.-X. Ye and Z.-H. Song, “Truncation and aliasing errors for Whittaker-Kotelnikov-Shannon sampling expansion,” Applied Mathematics B, vol. 27, no. 4, pp. 412–418, 2012.

[19] P. X. Ye, B. H. Sheng, and X. H. Yuan, “Optimal order of truncation and aliasing errors for multi-dimensional whittaker-shannon sampling expansion,” International Journal of Wireless and Mobile Computing, vol. 5, no. 4, pp. 327–333, 2012.

[20] S. M. Nikolskii, Approximation of Functions of Several Variables and Embedding Theorems, Springer, New York, NY, USA, 1975.

[21] Y. Jiang and Y. Liu, “Average widths and optimal recovery of multivariate Besov classes in \( L_p(R^d) \),” Journal of Approximation Theory, vol. 102, no. 1, pp. 155–170, 2000.

[22] C. A. Micchelli, Y. S. Xu, and P. X. Ye, “Cucker-Smale learning theory in Besov spaces,” in Advances in Learning Theory: Methods, Models and Applications, J. Suykens, G. Horvath, S. Basu et al., Eds., pp. 47–68, IOS Press, Amsterdam, The Netherlands, 2003.

[23] R. P. Boas, Jr., Entire Functions, Academic Press, New York, NY, USA, 1954.

[24] G. Fang, F. J. Hicken nell, and H. Li, “Approximation on anisotropic Besov classes with mixed norms by standard information,” Journal of Complexity, vol. 21, no. 3, pp. 294–313, 2005.

[25] H. G. Burchard and J. Lei, “Coordinate order of approximation by functional-based approximation operators,” Journal of Approximation Theory, vol. 82, no. 2, pp. 240–256, 1995.