4d Deformed Special Relativity from Group Field Theories

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We derive a scalar field theory of the deformed special relativity type, living on non-commutative $\kappa$-Minkowski spacetime and with a $\kappa$-deformed Poincaré symmetry, from the SO(4,1) group field theory defining the transition amplitudes for topological BF-theory in 4 space-time dimensions. This is done at a non-perturbative level of the spin foam formalism working directly with the group field theory (GFT). We show that matter fields emerge from the fundamental model as perturbations around a specific phase of the GFT, corresponding to a solution of the fundamental equations of motion, and that the non-commutative field theory governs their effective dynamics.

I. INTRODUCTION

The progress toward a quantum theory of gravity, in the past twenty years or so, has been substantial. On the theory side, many different approaches, the most notable being probably string theory, have been developed and achieved considerable successes [1].

Group field theories [2, 3] are quantum field theories over group manifolds, characterized by a non-local pairing of field arguments in the action, which can be seen as a generalization of matrix models [4]. The combinatorics of the field arguments in the interaction term of the group field theory (GFT) action follows that of (D-2) faces of a D-simplex, with the GFT field itself interpreted as a (second) quantization of a (D-1)-simplex. The kinetic term of the action governs the gluing of two D-simplices along a common (D-1)-simplex. Because of this combinatorial structure, the GFT Feynman diagrams, themselves cellular complexes, are dual to D-dimensional simplicial complexes. Thus GFTs can be seen as a simplicial “third quantization” of gravity [5], in which a discrete spacetime emerges as a Feynman diagram of the theory in perturbative expansion. The field arguments assign group-theoretic data to these cellular complexes, and the GFT perturbative expansion in Feynman amplitudes define uniquely and completely a so-called spin foam model [6]. Spin foam models [7], in turn, can be understood as a covariant formulation of the dynamics of loop quantum gravity [8] and as a new algebraic implementation of discrete quantum gravity approaches, such as Regge calculus [9] and dynamical triangulations [10]. This makes GFTs a very useful tool, and suggests that they may provide the fundamental definition of a dynamical theory of spin networks, and be of great help in investigating non-perturbative and collective properties of their quantum dynamics [2, 3, 11].

In recent years, moreover, the possibility of testing experimentally Planck scale effects using astrophysical or cosmological observations has been investigated to a great extent and led to a whole set of approaches to possible quantum gravity phenomenology [12]. The general idea is that there exist several physical amplifying mechanisms, e.g. in gamma-ray bursts, cosmic rays, or gravitational wave physics, that could bring quantum gravity effects, even if suppressed by (negative) powers of the Planck energy or by (positive) powers of the Planck length, within reach of near future (if not current, e.g. the on-going GLAST experiment) experiments. The most studied effects are that of a breaking (e.g. Einstein-Aether theory) or of a deformation (e.g.

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Deformed Special Relativity) of fundamental spacetime symmetries, like the Lorentz or Poincaré invariance [12]. This last case is implemented in the context of non-commutative models of spacetime, with symmetry groups implemented by means of appropriate Hopf algebras [13]. In many of the interesting cases, in particular those we are concerned with in this work, spacetime coordinates, turned into operators, have Lie algebra-type commutation relations, with a corresponding momentum space given instead by a group manifold, following the general principle [13] that non-commutativity in configuration space is related to curvature in momentum space, a sort of “co-gravity” [13]. One class of models that have attracted much attention in this context is given by so-called Deformed (or Doubly) Special Relativity [12, 14], based on the idea of introducing a second invariant scale, given by the Planck length (or energy) and assumed to encode quantum gravity effects in a semi-classical and flat spacetime, on top of the velocity scale of usual Special Relativity, while maintaining the relativity principle, and thus a 10-dimensional transformation group relating the observations made by inertial observers. In one particular incarnation of DSR, spacetime is non-commutative and its structure is of $\kappa$-Minkowski type [15]. This is the spacetime we are concerned with here. In fact, it is now clear that these effective models of quantum gravity can in principle be falsified. Unfortunately, we are still lacking any fundamental formulation of quantum gravity that, on top of being clearly defined at the Planck scale, can produce unambiguously any of the effective models that have been proposed, thus producing falsifiable predictions.

Very interesting results have been obtained in the 3d context [16, 17, 18] where it has been shown that effective models with quantum group symmetries and a non-commutative spacetime structure (although different from the DSR one) arise very naturally when considering the coupling of point particles to a spin foam model for 3d quantum gravity, in the Riemannian setting, with the physics of these particles being that of non-commutative field theories on Lie algebra spaces. While no similarly solid links between spin foam models and non-commutative field theories have been discovered in the 4d context, several arguments have been put forward suggesting that these links should exist and that the relevant effective models in 4d should indeed be of the DSR type [19, 20].

For reasons that should become apparent in the following, group field theories are a natural framework for establishing such links, and for actually deriving effective non-commutative models of quantum gravity from more fundamental (if tentative) descriptions of quantum spacetime. Once more, in 3d this is technically easier to do, and it has been shown recently [21] that one can indeed derive the same effective field theory obtained in [17] directly from GFT model corresponding to the spin foam model on which that earlier work was based. The procedure used, moreover, appears not to depend too much in the details of the 3d model considered, but only on general properties of the GFT formalism. We will review briefly these results in the next section.

What we do in this paper is to apply the same procedure to the more technically challenging case of four spacetime dimensions, and Lorentzian signature, and derive from a group field theory model related to 4-dimensional quantum gravity an effective non-commutative field theory of the DSR type and living on $\kappa$-Minkowski spacetime.

As said, not only this is the first example of a derivation of a DSR model for matter from a more fundamental quantum gravity model, and one further example of the link between non-commutative geometry and quantum gravity formulated in terms of spin foam/loop quantum gravity ideas, but it is of great interest from the point of view of quantum gravity phenomenology. It is also interesting, more generally, as another possible way of bridging the gap between quantum gravity at the Planck scale and effective physics at low energies and macroscopic distances.

II. A BRIEF REVIEW OF 3D GROUP FIELD THEORY AND EFFECTIVE THEORIES

The group field theory generating the Ponzano-Regge spinfoam amplitudes for 3d quantum gravity was written by Boulatov [22]. The field $\phi : SU(2)^3 \rightarrow \mathbb{C}$ is required to be gauge invariant under the diagonal right action of $SU(2)$:

$$\phi(g_1, g_2, g_3) = \phi(g_1g, g_2g, g_3g), \quad \forall g \in SU(2).$$

(1)
The action defining this 3d group field theory involves a trivial propagator and the tetrahedral interaction vertex:

\[ S_{3d}[\phi] = \frac{1}{2} \int [dg]^3 \phi(g_1, g_2, g_3)\phi(g_3, g_2, g_1) - \frac{\lambda}{4!} \int [dg]^6 \phi(g_1, g_2, g_3)\phi(g_3, g_4, g_5)\phi(g_5, g_2, g_6)\phi(g_6, g_4, g_1). \]  

(2)

This field theory generates Feynman diagrams which are identified to 3d triangulations. Moreover the evaluation of these Feynman diagrams gives exactly the Ponzano-Regge amplitude associated to the corresponding triangulation.

We can require the field to satisfy a reality condition, \( \phi(g_1, g_2, g_3) = \phi(g_3, g_2, g_1) \), ensuring the quadratic kinetic term to be real. Further symmetry requirements under permutations of the field arguments can be imposed. For example, a symmetry under even permutations combined with complex conjugation under odd permutations leads to the corresponding perturbative expansion to involve only orientable complexes (see e.g. [23, 24]). However, no specific condition is needed for the definition of the model, nor for our procedure and results to apply, so we do not discuss this issue further.

As it was shown in [21], we can identify a specific type of fluctuations of the group field \( \phi \) as matter degrees of freedom propagating on some effective flat non-commutative background. More precisely, this effective dynamics is given by a non-commutative quantum field theory invariant under a quantum deformation of the Poincaré group. The procedure is simple: we look at some two-dimensional variations of the \( \phi \)-field around classical solutions (as we work in a time-less setting, we could call these solutions “instantons”) of the group field theory.

The equation of motion of the group field theory for this model are given by:

\[ \phi(g_3, g_2, g_1) = \frac{\lambda}{3!} \int dg_4 dg_5 dg_6 \phi(g_3, g_4, g_5)\phi(g_5, g_2, g_6)\phi(g_6, g_4, g_1). \]  

(3)

Calling \( \phi^{(0)} \) a generic solution to this equation, we look at field variations \( \delta\phi(g_1, g_2, g_3) \equiv \psi(g_1 g_2^{-1}) \) which do not depend on the group element \( g_2 \) and which we call “two-dimensional variations”. This leads to an effective action describing the dynamics of the 2d variations \( \psi \) around the background solution \( \phi^{(0)} \):

\[ S_{\text{eff}}[\psi] = S_{3d}[\phi^{(0)}] + \psi - S_{3d}[\phi^{(0)}]. \]  

(4)

This effective action will not contain any (infinite, in general) constant term (which we cancel by means of the counter-term \( S_{3d}[\phi^{(0)}] \)), nor linear terms since \( \phi^{(0)} \) is a classical solution. The first term will be a non-trivial quadratic, i.e. kinetic, term for the variation \( \psi \), as we will see below.

We consider a specific class of classical solutions, named “flat” solutions:

\[ \phi^{(0)}(g_1, g_2, g_3) = \sqrt{\frac{3!}{\lambda}} \int dg \delta(g_1 g)F(g_2 g_3)\delta(g_3 g), \quad F : G \to \mathbb{R}. \]  

(5)

As shown in [21], this ansatz gives solutions to the field equations as soon as \( \int F^2 = 1 \) (or \( F = 0 \)). Also, this type of solutions can be considered as a “regularized or smoothed” version of a function \( \phi^{(0)}(g_1, g_2, g_3) = \sqrt{\frac{3!}{\lambda}} \int dg \delta(g_1 g)\delta(g_2 g)\delta(g_3 g) \), formally still a solution of the field equations (but giving divergent terms when inserted in the equations) and representing a quantum space in which all possible SU(2) holonomies are flat, i.e. a “quantum flat space”. There exists other solutions [25] but they are not relevant to the present discussion. It is then straightforward to compute the effective action:

\[ S_{\text{eff}}[\psi] = \frac{1}{2} \int \psi(g)K(g)\psi(g^{-1}) - \frac{\mu}{3!} \int [dg]^3 \psi(g_1)\psi(g_2)\psi(g_3)\delta(g_1 g_2 g_3) - \frac{\lambda}{4!} \int [dg]^4 \psi(g_1)\psi(g_2)\psi(g_3)\delta(g_1 g_2 g_3), \]  

(6)

with the kinetic term and the 3-valent coupling given in term of \( F \):

\[ K(g) = 1 - 2 \left( \int F \right)^2 - \int dhF(h)F(hg), \quad \frac{\mu}{3!} = \sqrt{\frac{\lambda}{3!}} \int F. \]

As it was shown in [17, 18, 21, 26, 27, 28], such an action defines a non-commutative quantum field theory invariant under a quantum deformation of the Poincaré group ISU(2).
First of all, in order to understand this correspondence, one should interpret the above action as written in momentum space: SU(2) \sim ℂ^4 is a curved momentum space with a group structure and the constraints \( \delta(g_1g_2g_3) \) and \( \delta(g_1...g_4) \) express momentum conservation in the interaction. This also implies that the effective theory itself is a group field theory. The explicit duality between this group field theory and the non-commutative field theory, i.e. the same field theory written in terms of a non-commutative configuration space, is then achieved through a non-commutative Fourier transform mapping functions on SU(2) to functions on \( \mathbb{R}^3 \) endowed with a non-commutative \( \ast \)-product, on \( \mathbb{R}^3 \), dual to the convolution product on SU(2). Following this Fourier transform, the SU(2) momentum conservation maps to a deformed conservation law on \( \mathbb{R}^3 \) and the kinetic term \( K(g) \) becomes the differential operator defining the field’s dynamics in terms of derivatives on \( \mathbb{R}^3 \) (the Laplacian in the simplest case). The details of this mapping do not concern us here, as we are more interested in the general procedure and in how the specific kinetic terms look like, but it will be described in some detail in the following sections for the 4-dimensional Lorentzian case, which is of direct relevance for DSR.

In order to get an action invariant 3d rotations, \( \psi(g) \rightarrow \psi(hgh^{-1}) \), we usually assume that the function \( F(g) \) is invariant under conjugation \( F(g) = F(hgh^{-1}) \). Such functions are linear combination of the SU(2) characters:

\[
F(g) = \sum_{j \in \mathbb{N}/2} F_j \chi_j(g), \quad F_0 = \int F, \quad F_j = \int dg F(g) \chi_j(g),
\]

where the \( F_j \)'s are the Fourier coefficients of the Peter-Weyl decomposition on the field. The (spin) \( j \in \mathbb{N}/2 \) label the irreducible representations of SU(2), which have dimension \( d_j \equiv (2j + 1) \). The normalization constraints now reads:

\[
\int F^2 = 1 = \sum_j F_j^2.
\]

The kinetic term is easily written in term of the \( F_j \)'s and the characters \( \chi_j(g) \):

\[
K(g) = 1 - 3F_0^2 - \sum_{j \geq 0} \frac{F_j^2}{d_j} \chi_j(g) = \sum_{j \geq 0} F_j^2 \left( 1 - \frac{\chi_j(g)}{d_j} \right) - 2F_0^2 \equiv Q^2(g) - M^2.
\]

It is easy to check that \( Q^2(g) \geq 0 \) is always positive (since \( |\chi_j(g)| \leq d_j \)) and vanishes at the identity \( g = 1 \).

We interpret this term as the “Laplacian” of the theory while the 0-mode \( F_0 \) defines the mass \( M^2 = 2F_0^2 \).

The standard choice is given by the 3-dimensional representation labeled by \( j = 1 \). We parameterize SU(2) group elements as two by two matrices:

\[
g = \cos \theta + i \sin \theta \hat{u} \cdot \vec{\sigma},
\]

where \( \theta \in [0, 2\pi] \) is the class angle (half of the rotation angle), \( \hat{u} \in ℂ^2 \) is the rotation axis and the \( \vec{\sigma} \)'s are the (Hermitian) Pauli matrices. The 3d momentum is usually defined as the projection of the group element on the Lie algebra \( su(2) \):

\[
\vec{p} = \frac{1}{2i} \text{tr} g \vec{\sigma} = \sin \theta \hat{u},
\]

so that the Laplacian would be given by a term \( p^2 = \sin^2 \theta \). Now the characters are functions of the class angle:

\[
\chi_j(g) = \frac{\sin d_j \theta}{\sin \theta}.
\]

So that the spin-1 case allows to recover the \( p^2 \) kinetic term:

\[
\chi_1(g) = \frac{\sin 3\theta}{\sin \theta} = 1 + 2 \cos 2\theta = 3 - 4p^2.
\]
Finally, choosing a classical solution given entirely by the character \( \chi_1(g) \) up to a constant shift,
\[
F(g) = a + b\chi_1(g), \quad \int F = a^2 + b^2 = 1,
\]
we obtain a simple kinetic term with the Laplacian and a mass:
\[
\mathcal{K}(g) = \frac{4}{3}(1 - a^2) \bar{p}^2 - 2a^2.
\]

Clearly, other choices are possible and they may give rise to higher order differential operators and thus to more complicated kinetic terms.

We conclude this review section by a short remark on the possibility relaxing the classical solution condition. Consider a background field given the flat ansatz
\[
\phi = \text{SL}(2, \mathbb{R}) \quad \text{or} \quad \text{Spin}(4) (\text{and SO}(5)) \quad \text{in the Riemannian case and}
\]
\[
\phi = \text{Spin}(4) (\text{and SO}(4, 1)) \quad \text{in the Lorentzian case.}
\]
The relevant groups for 4d quantum gravity are \( G = \text{Spin}(4) \) (and \( \text{SO}(5) \)) in the Riemannian case and \( G = \text{SL}(2, \mathbb{C}) \) (and \( \text{SO}(4, 1) \)) in the Lorentzian case. In this section, we focus on the compact group case. We will deal with the non-compact group case relevant to Lorentzian gravity in the next section. It will require proper and careful regularization to avoid divergencies due to the non-compact nature of the group.
We generalize the “flat solution” ansatz of the 3d group field theory to the four-dimensional case \[21\]:

\[
\phi^{(0)}(g_1) \equiv 3 \sqrt{\frac{4!}{\lambda}} \int dg \delta(g_1 g) F(g_2 g) \tilde{F}(g_3 g) \delta(g_4 g).
\] (16)

It is straightforward to check that this provides a solution to the classical equations of motion as soon as \((\int F \tilde{F})^3 = 1\). We let aside for a moment this normalization condition, and we compute the effective action for two-dimensional variations around such background configurations for arbitrary functions \(F\) and \(\tilde{F}\):

\[
S_{\text{eff}}[\psi] \equiv S_{4d}[\phi^{(0)} + \psi(g_1 g_4^{-1})] - S_{4d}[\phi^{(0)}].
\]

We obtain an effective action with a linear term proportional to \(\psi(\mathbb{I})\), a non-trivial quadratic kinetic term and interaction vertices of order 3 to 5:

\[
S_{\text{eff}}[\psi] = 3 \sqrt{\frac{4!}{\lambda}} \psi(\mathbb{I}) \int F \int \tilde{F} \left[ 1 - \left( \int F \tilde{F} \right)^3 \right] + \frac{1}{2} \int \psi(g) \psi(g^{-1}) \mathcal{K}(g) - 3 \sqrt{\frac{\lambda}{4!}} \int F \int \tilde{F} \int \psi(g_1) \psi(g_3) \delta(g_1 g_3) \left[ \int F \int \tilde{F} + \int dh F(h g_3) \tilde{F}(h) \right] - \left( 3 \sqrt{\frac{\lambda}{4!}} \right)^2 \int F \int \tilde{F} \int \psi(g_1) \psi(g_4) \delta(g_1 g_4) - \frac{\lambda}{5!} \int \psi(g_1) \psi(g_5) \delta(g_1 g_5),
\]

with the new kinetic operator given by:

\[
\mathcal{K}(g) = \left[ 1 - 2 \left( \int F \int \tilde{F} \right)^2 \int F \int \tilde{F} \int \psi(h) \delta(h g) \tilde{F}(h) \int dh F(h g) \tilde{F}(h) \right].
\] (18)

Taking into account the normalization condition \((\int F \tilde{F})^3 = 1\) and thus working with an exact solution \(\phi_0\) of the equations of motion, we see that the linear term vanishes exactly due to this condition. We also notice that, if we were to relax this normalization condition and work with a “partial solution requirement” as in the 3d case, the linear term could still be made to vanish and with the same condition \((\int F \tilde{F}) = 0\) (or with \(\int F = 0\)). However, in this 4d case, this other condition makes also all new terms (among which the non-trivial kinetic term) vanish. Another possibility could be to renormalize the coupling constant \(\lambda\) by re-absorbing in it the factors \(\int F \int \tilde{F}\), and then impose the same condition of vanishing integral in some limiting procedure. The interest and consequences of doing this, however, are not clear at the present stage.

At any rate, we obtain an effective field theory for the field \(\psi\) defined on two copies of the initial group manifold, but reduced by means of the symmetry requirement to a function of a single group element, with a non-trivial quadratic propagator. The group \(G\) is now interpreted again as the momentum space for the quanta corresponding to this field, with the \(\delta(g_1 g_4)\) factors in the action imposing momentum conservation in the field interactions. And again, after introducing a suitable Fourier transform, such effective group field theory appears as the dual of a non-commutative field theory. This same duality implies that position space field theory is defined in terms of functions on \(\mathbb{R}^d\), with \(d\) the dimension of the group \(G\), endowed with a suitable star product structure, or, equivalently, by elements of the enveloping algebra for the Lie algebra of the same group \(G\), i.e. non-commutative fields living on a non-commutative spacetime given by the same Lie algebra. The non-commutativity reflects the curvature of the group manifold and the non-abelian group multiplication leads to a deformation of the addition of momenta. We will show how this works in detail in the next section for the non-compact group \(G = SO(4,1)\) and for a group field theory more closely related to 4d quantum gravity.

We conclude this section by considering the special case when the function \(\tilde{F}\) is fixed to be the \(\delta\)-distribution while \(F\) is kept arbitrary as long as \(F(\mathbb{I}) = 1\). This ansatz clearly satisfies the normalization condition \(\int F \tilde{F} = 1\) and thus provides a solution to the classical field equations. Calling \(c \equiv \int F\), the effective action
takes has a simpler expression:

\[
S_{\text{eff}}[\psi] = \frac{1}{2} \int \psi(g)\psi(g^{-1}) \left[ 1 - 2e^2 - 2F(g)F(g^{-1}) \right] - c \left( \frac{3}{\sqrt{4!}} \right) \int \psi(g_1)\psi(g_2)\delta(g_1..g_3) [c + F(g_3)]
- c \left( \frac{3}{\sqrt{4!}} \right)^2 \int \psi(g_1)\psi(g_4)\delta(g_1..g_4) - \frac{\lambda}{5!} \int \psi(g_1)\psi(g_5)\delta(g_1..g_5). \tag{19}
\]

IV. DEFORMED SPECIAL RELATIVITY AS A GROUP FIELD THEORY

The term "Deformed Special Relativity" (DSR) has been used to describe many different theories. We are here interested in the original construction which described a non-commutative space-time, of the Lie algebra type \((\kappa\text{-Minkowski)}\) together with some deformed Poincaré symmetries. In particular these latter are consistent with the existence of another universal scale (the Planck mass/momentum) than the speed of light.

When dealing with such theory, the literature has often emphasized its non-commutative geometry aspect. Moreover it is also known since some time [13] that a Fourier transform from a non-commutative space-time of the Lie algebra type leads to a (curved) momentum space with a (non-abelian) group structure. From this perspective, it is clear that a scalar field theory over \(\kappa\text{-Minkowski}\) can also be interpreted as a group field theory, where the group is the momentum space (contrary to the usual GFT approach for quantum gravity models where the group is usually considered as the configuration space). This aspect of DSR was certainly known but never exploited before from the group field theory perspective. In fact having this in mind will allow us to derive a DSR scalar field theory from a group field theory describing the BF quantum amplitudes in the next section.

Before doing so, we recall the definition of the \(\kappa\text{-Minkowski}\) space and its associated momentum space, the AN group. The construction can be done in any dimension. This means that we can also obtain, in principle, an effective field theory on \(\kappa\text{-Minkowski}\) spacetime in any dimension from a group field theory, using our procedure. However, we focus on the 4d case which is directly relevant for quantum gravity. We then review the construction of scalar field theory on \(\kappa\text{-Minkowski}\), emphasizing the group field theory aspect.

A. \(\kappa\text{-Minkowski} and the AN momentum space

As a vector space, the \(\kappa\text{-Minkowski}\) space-time is isomorphic to \(\mathbb{R}^n\) and is defined as the Lie algebra \(\mathfrak{an}_{n-2}\), which is a subalgebra of the Lorentz algebra \(\mathfrak{so}(n-1,1)\). In the following, we work with the signature \((-,+,...,+\)). The \(n\)-1 generators of \(\mathfrak{an}_{n-2}\) are given by:

\[
X_0 = \frac{1}{\kappa} J_{n0}, \quad X_k = \frac{1}{\kappa} (J_{nk} + J_{0k}), \quad k = 1,...,n-2, \tag{20}
\]

where the \(J_{\mu\nu}\) are the generators of the Lorentz algebra \(\mathfrak{so}(n-1,1)\). It is easy to see that \(\mathfrak{an}_{n-2}\) is therefore encoded by the following commutation relations:

\[
[X_0, X_k] = -\frac{i}{\kappa} X_k, \quad [X_k, X_l] = 0, \quad k, l = 1,...,n. \tag{21}
\]

Their explicit matrix elements in the fundamental \((n\text{-dimensional})\) representation of \(\mathfrak{so}(n-1,1)\) are [29]:

\[
X_0 = \frac{i}{\kappa} \begin{pmatrix} 0 & 0 & 1 \\ 0 & 0 & 0 \\ 1 & 0 & 0 \end{pmatrix}, \quad X_k = \frac{i}{\kappa} \begin{pmatrix} 0 & t x & 0 \\ x & 0 & x \\ 0 & -t x & 0 \end{pmatrix}, \tag{22}
\]

where \(t x\) are the \((n-2)\)-dimensional basis vectors \((1,0,...,0), (0,1,0,...), \) and so on. For explicit calculations, it is convenient to notice that the matrices \(X_k\) are nilpotent with \((X_k)^3 = 0\). There are indeed \(n\)-2 abelian
and nilpotent generators, hence the name AN_{n-2}. The corresponding exponentiated group elements are:

\[ e^{i k_0 X_0} = \begin{pmatrix} \cosh \frac{k_0}{\kappa} & 0 & -\sinh \frac{k_0}{\kappa} \\ 0 & 1 & 0 \\ -\sinh \frac{k_0}{\kappa} & 0 & \cosh \frac{k_0}{\kappa} \end{pmatrix}, \quad e^{ik_i X_i} = \begin{pmatrix} 1 + \frac{k_i^2}{2\kappa^2} & -\frac{k_i}{\kappa} & \frac{k_i^2}{2\kappa^2} \\ -\frac{k_i}{\kappa} & 1 & \frac{k_i}{\kappa} \\ -\frac{k_i^2}{2\kappa^2} & -\frac{k_i}{\kappa} & 1 - \frac{k_i^2}{2\kappa^2} \end{pmatrix}, \]

where 1 is the \((n-2) \times (n-2)\) identity matrix. We parameterize generic AN_{n-2} group elements as

\[ h(k_0, k_i) = e^{i k_0 X_0} e^{i k_i X_i}. \]

As we will see in the next subsection, this group element can be interpreted as the non-commutative plane-wave and the coordinates on the group \(k_\mu\) as the wave-vector (and therefore related to the momentum).

To multiply group elements in this parametrization, we check that:

\[ e^{i k_0 X_0} e^{i k_i X_i} = e^{i (e^{k_0/\kappa}) k_i X_i} e^{i k_0 X_0}. \]

This is the exponentiated version of the commutation relation between \(X_0\) and the \(X_i\)'s. This allows to derive the multiplication law for AN_{n-2} group elements:

\[ h(k_0, k_i) h(q_0, q_i) = h(k_0 + q_0, e^{-q_0/\kappa} k_i + q_i), \]

which defines a deformed non-commutative addition of the wave-vectors:

\[ (k \oplus q)_0 \equiv k_0 + q_0, \quad (k \oplus q)_i \equiv e^{-q_i/\kappa} k_i + q_i. \]

This also gives the inverse group elements:

\[ h^{-1}(k_0, k_i) = h(-k_0, -e^{k_0/\kappa} k_i), \]

which defines the opposite momentum \(S(k_\mu)\) for the non-commutative addition:

\[ S(k_0) = -k_0, \quad S(k_i) = -e^{k_0/\kappa} k_i. \]

The relation between the SO\((n-1, 1)\) group and AN_{n-2} is given by the Iwasawa decomposition (see e.g. \[29, 30\]):

\[ \text{SO}(n-1, 1) = \text{AN}_{n-2} \text{SO}(n-2, 1) \cup \text{AN}_{n-2} \mathcal{M} \text{SO}(n-2, 1), \]

where the two sets are disjoint and \(\mathcal{M}\) is the following diagonal matrix,

\[ \mathcal{M} = \begin{pmatrix} -1 & 0 \\ 0 & 1 \end{pmatrix}. \]

To understand the geometric meaning of this decomposition, we look at the map between AN_{n-2} and the de Sitter space-time \(dS_{n-1}\) defined as the coset SO\((n-1, 1)/\text{SO}(n-2, 1)\). We introduce a reference space-like vector \(v^{(0)} \equiv (0, \ldots, 0, 1) \in \mathbb{R}^n\). The little group of this vector is the Lorentz group SO\((n-2, 1)\) and the action of SO\((n-1, 1)\) on it sweeps the whole de Sitter space.

Looking at the action of AN_{n-2} on \(v^{(0)}\), using the plane-wave parametrization \[24\], we define the vector \(v \equiv h(k_\mu) v^{(0)}\) with explicit coordinates:

\[ \begin{align*}
v_0 &= -\sinh \frac{k_0}{\kappa} + \frac{k_0^2}{2\kappa^2} e^{k_0/\kappa}, \\
v_i &= -\frac{k_i}{\kappa}, \\
v_n &= \cosh \frac{k_0}{\kappa} - \frac{k_0^2}{2\kappa^2} e^{k_0/\kappa}. \end{align*} \]
We easily check that $v_A v^A = -v_0^2 + v^2 + v_n^2 = 1$. However, since $v_0 + v_n = \exp(-k_0/\kappa)$, this action of $\text{AN}_{n-2}$ on $v^{(0)}$ sweeps only the half of the de Sitter space defined by the condition $v_+ = v_0 + v_n > 0$. Assuming this condition, we can reverse the previous relation and express the $\text{AN}_{n-2}$ group element in terms of the $n$-vector $v$:

$$h(k_\mu) = \begin{pmatrix} v_n + \frac{v^2}{v_0 + v_n} & \frac{t v}{v_0 + v_n} & 0 \\ \frac{v^2}{v_0 + v_n} & \frac{1}{v_0 + v_n} & v \\ v_0 - \frac{v^2}{v_0 + v_n} & -\frac{t v}{v_0 + v_n} & v_n \end{pmatrix}, \quad \text{with } h(k_\mu)^{-1} = \begin{pmatrix} v_n + \frac{v^2}{v_0 + v_n} & -\frac{t v}{v_0 + v_n} & -v_0 \\ \frac{v^2}{v_0 + v_n} & \frac{1}{v_0 + v_n} & v \\ v_0 + \frac{v^2}{v_0 + v_n} & \frac{t v}{v_0 + v_n} & v_n \end{pmatrix}. \quad (31)$$

To recover the full de Sitter space, we need to use the other part of the Iwasawa decomposition. Considering the action of $\mathcal{M}$, we obtain:

$$h(k_\mu) \mathcal{M} v^{(0)} = -v \quad h(k_\mu) = \begin{pmatrix} -v_0 - \frac{v^2}{v_0 + v_n} & \frac{t v}{v_0 + v_n} & -v_0 \\ -v & \frac{1}{v_0 + v_n} & -v \\ -v_0 + \frac{v^2}{v_0 + v_n} & \frac{t v}{v_0 + v_n} & -v_n \end{pmatrix}. \quad (32)$$

Thus the action of the $\mathcal{M}$ operator simply maps the $n$-vector $v_A$ in its opposite $-v_A$. Clearly that allows to complete the other side of de Sitter space with $v_+ < 0$. Let us point out that the left action $\mathcal{M} h(k_\mu)$ would still map $v_0 \rightarrow -v_0$ and $v_n \rightarrow -v_n$ but would leave the other components invariant $v \rightarrow v$.

To summarize, an arbitrary point $v$ on the de Sitter space-time is uniquely obtained as:

$$v = (-)^\epsilon h(k_\mu) v^{(0)} = h(k_\mu) \mathcal{M}^\epsilon v^{(0)}, \quad \epsilon = 0 \text{ or } 1, \quad h \in \text{AN}_{n-2}. \quad (33)$$

The sign $(-)^\epsilon$ corresponds to the two components of the Iwasawa decomposition. The coset space $\text{SO}(n - 1, 1)/\text{SO}(n - 2, 1)$ is isomorphic to the de Sitter space and is covered by two patches, each of these patches being isomorphic to the group $\text{AN}_{n-2}$.

We introduce the set $\text{AN}_{n-2}^\epsilon \equiv \text{AN}_{n-2} \cup \text{AN}_{n-2} \mathcal{M}$, such that the Iwasawa decomposition reads $\text{SO}(n - 1, 1) = \text{AN}^\epsilon \text{SO}(n - 2, 1)$ and that $\text{AN}^\epsilon$ is isomorphic to the full de Sitter space (without any restriction on the sign of $v_+$). Actually, $\text{AN}_{n-2}^\epsilon$ is itself a group. Indeed we first easily check the commutation relation between the $\mathcal{M}$ operator and $\text{AN}_{n-2}$ group elements:

$$\mathcal{M} h(k_\mu) = h(k_\mu, -k_\mu)(-\mathcal{M}),$$

where commuting $\mathcal{M}$ with $h$ sends the 5-vector $v_A$ to $(v_0, -v, v_n)$. This implies the group multiplication on $\text{AN}^\epsilon$:

$$h(k_\mu) \mathcal{M}^\alpha h(q_\rho) \mathcal{M}^\beta = h(k \oplus (-)^\alpha q) \mathcal{M}^{\alpha + \beta}, \quad (34)$$

with $\alpha, \beta = 0, 1$. Finally, we point out that $\text{AN}_{n-2}^\epsilon$ is a group but not a Lie group (because of the discrete $\mathbb{Z}_2$ component).

In the following we will focus on $n = 5$ case looking at $\text{SO}(4,1)$ and its subgroup $\text{AN}_3$ relevant for 4d Deformed Special Relativity and quantum gravity. Consider the action of the Lorentz transformations $\text{SO}(3,1)$ on $\text{AN}_3$. This is not simple when seen from the 4d perspective, i.e. from the point of view of $\text{AN}_3$ itself. However, it amounts to the obvious linear action of $\text{SO}(3,1)$ on the de Sitter space-time $dS_4$, $\Lambda \triangleright v = \Lambda v$, leaving the fifth component $v_4$ invariant. This leads to a non-linear action of $\Lambda \in \text{SO}(3,1)$ on $\text{AN}_3$ (see e.g. (30)):

$$\Lambda \triangleright h(k_\mu) \mathcal{M}^\epsilon \equiv \Lambda h(k_\mu) \mathcal{M}^\epsilon \tilde{\Lambda}^{-1} = h(k'_\mu) \mathcal{M}^\epsilon, \quad (35)$$

where $\tilde{\Lambda}$, a priori different from $\Lambda$, is the unique Lorentz transformation ensuring that the resulting group element lives in $\text{AN}^\epsilon_3 \equiv \text{AN}_3 \cup \text{AN}_3 \mathcal{M}$. An important point is that it is impossible to neglect the effect of $\mathcal{M}$. Indeed the Lorentz transformation mixes the two parts of the Iwasawa decomposition: the subgroup $\text{AN}_3$ is not invariant under the $\text{SO}(3,1)$ action but the group $\text{AN}^\epsilon_3$ is.
It is possible to compute the “counter-boost” $\tilde{A}$ for infinitesimal Lorentz transformations \([30]\). This leads to the $\kappa$-Poincaré algebra presented as a non-linear realization of the Poicaré algebra in terms of $k_\mu$:

$$
[M_i, k_j] = \epsilon_{ijk} k_k, \quad [M_i, k_0] = 0, \quad [k_\mu, k_\nu] = 0
$$

$$
[N_i, k_j] = \delta_{ij} \left( \sinh \frac{k_0}{\kappa} - \frac{k^2}{2\kappa^2} \epsilon_{k0/\kappa} \right), \quad [N_i, k_0] = k_i \epsilon_{k0/\kappa}
$$

(36)

Finally, we will need an integration measure on $AN_3$ in order to define a Fourier transform. The group $AN_3$ is provided with two invariant Haar measures:

$$
\int dh_L = \int d^4 k_\mu, \quad \int dh_R = \int e^{+3k_0/\kappa} d^4 k_\mu,
$$

(37)

which are respectively invariant under the left and right action of the group $AN_3$. Let us point out that:

$$
\int d(h^{-1})_L = \int dh_R.
$$

We can easily derive this measure from the 5d perspective using the parametrization \([31]\):

$$
\kappa^4 \int \delta(v_A v^A - 1) \theta(v_0 + v_4) d^5 v_A = \int d^4 k_\mu = \int dh_L,
$$

(38)

where the $\theta(v_+)$ function imposes the $v_+ > 0$ restriction. Indeed the SO(4,1) action on the reference vector $v^{(0)}$ generates the whole de Sitter space,

$$
v = g \triangleright v^{(0)} = h\mathcal{M}^* \Lambda \triangleright v^{(0)} = h\mathcal{M}^* \triangleright v^{(0)}.
$$

Therefore the natural measure on $AN_3$ inherited from the Haar measure on SO(4,1) is left-invariant.

A crucial issue is the Lorentz invariance of the measure. Even though the measure $dh_L = d^4 k_\mu$ looks Lorentz invariant, it is not, as the action of the Lorentz group on the coordinates $k_\mu$ is non-trivial and non-linear. Actually, one can show this action does not leave the measure invariant. What causes the problem is the restriction $v_+ > 0$ (needed when inducing the measure on $AN_3$ from the Lorentz invariant measure on $dS_4$, which indeed breaks Lorentz invariance. In order to get a Lorentz invariant measure, we need to glue back the two patches $v_+ < 0$ and $v_+ > 0$ (and actually also the $v_+ = 0$ patch) and define the measure on the whole de Sitter space. In other words, we write the same measure as a measure on $AN_3^c = AN_3 \cup AN_3 \mathcal{M} \sim dS$:

$$
\int dh_L \equiv \int_{AN_3} dh^+_L + \int_{AN_3 \mathcal{M}} dh^-_L = \int \delta(v_A v^A - 1) d^5 v.
$$

(39)

Another way to circumvent this problem and obtain a Lorentz invariant measure is to consider a space without boundary and work on the so-called elliptic de Sitter space\(^1\) $dS/\mathbb{Z}_2$ where we identify $v_A \leftrightarrow -v_A$, which amounts to identifying the group elements $h(k_\mu) \leftrightarrow h(k_\mu) \mathcal{M}$. This space is indeed isomorphic to $AN_3^c$ as a manifold. One way to achieve nicely this restriction at the field theory level is to consider only fields on de Sitter space (or on $AN_3^c$) which are invariant under the parity transformation $v_A \leftrightarrow -v_A$ \([31]\). In this case, we recover the measure $d^4 k_\mu$ on $AN_3 \sim AN_3^c/\mathbb{Z}_2 \sim dS/\mathbb{Z}_2$.

\(^1\) Considering deformed special relativity in three dimensions with Euclidean signature, the group field theory on SU(2) has a similar feature \([27]\). SU(2) being isomorphic to the sphere $S^3$ is indeed also covered by two patches. Note however than in this case the standard choice of coordinates is not breaking the Lorentz symmetries. To get rid of one patch, we identify the two patches and consider instead $SO(3) = SU(2)/\mathbb{Z}_2$ as in \([18, 28]\).
B. DSR Field Theory (in a nutshell)

We now present a DSR scalar field theory first as a group field theory. Then we recall how we can recover the scalar field theory on $\kappa$-Minkowski using a generalized Fourier transform. For simplicity, we shall restrict to the case $n = 5$, so that we shall consider the non-compact and non-semi-simple groups $G = AN^c_5, AN_3$.

We consider the real scalar field $\phi : G \to \mathbb{R}$, and define the (free) action

$$\mathcal{B}(\phi) = \int dh_L \phi(h) K(h) \phi(h), \quad \forall h \in G,$$

(40)

where $K(h)$ is the propagator and $dh_L$ is the left invariant measure. Contrary to the usual group field theory philosophy, we interpret $G$ as the momentum space.

First let us discuss the possible choices of propagators. We demand $K(h)$ to be a function on $G$ invariant under the Lorentz transformations. We have showed in the previous subsection how the Lorentz group is acting on $G$. It is then clear that any function $K(h) = f(v_4(h))$ is a good candidate, since $v_4$ is by construction a Lorentz invariant quantity. Two main choices have been studied in the literature.

$$K_1(h) = (\kappa^2 - \pi_4(h)) - m^2, \quad K_2(h) = \kappa^2 - (\pi_4(h))^2 - m^2, \quad \pi_4 = \kappa v_4.$$

(41)

The freedom in choosing the propagator is related to the ambiguity in choosing what we call momentum. To have a precise candidate for the notion of momentum, one needs to define first position and define momentum either as the eigenvalue of the translation operator applied to the plane-wave and/or the conserved charged. We now present a DSR scalar field theory first as a group field theory. Then we recall how we can recover a Lorentzian field theory on the coordinates $\mathbb{R}^4$, when a restriction to symmetric fields is imposed.

The generalized Fourier transform relates functions on the group $\mathcal{C}(G)$ and elements of the enveloping algebra $U(\mathfrak{a}n_3)$. It is defined respectively for $G = AN^c_5, AN_3$ as

$$\hat{\phi}(X) = \int_{AN_3} dh_L h(k_\mu) \phi^+(k) + \int_{AN_3 M} dh_L h(k_\mu) \phi^-(k), \quad X \in \mathfrak{a}n_3, \quad \hat{\phi}(X) \in U(\mathfrak{a}n_3)$$

(42)

$$\hat{\phi}(X) = \int_{AN_3} dh_L h(k_\mu) \phi(k), \quad X \in \mathfrak{a}n_3, \quad \hat{\phi}(X) \in U(\mathfrak{a}n_3)$$

(43)

where we used the non-abelian plane-wave $h(k_\mu)$. The inverse Fourier transform can also be introduced, if one introduces a measure $d^4X$. For the details we refer to [26, 31]. The group field theory action on $G$ can now be rewritten as a non-commutative field theory on $\kappa$-Minkowski (to simplify the notation we restrict our attention to $G = AN_3$ and thus we implicitly consider symmetric fields).

$$\mathcal{B}(\phi) = \int dh_L \phi(h) K(h) \phi(h) = \int d^4X \left( \partial_\mu \hat{\phi}(X) \partial^\mu \hat{\phi}(X) + m^2 \hat{\phi}^2(X) \right).$$

(44)

The Poincaré symmetries are naturally deformed in order to be consistent with the non-trivial commutation relations of the $\kappa$-Minkowski coordinates. More exactly, if the Poincaré transformations act in the standard on the coordinates$^2$

$$T_\mu \triangleright X_\nu = \delta_{\mu\nu}, \quad N_i \triangleright X_j = \delta_{ij}X_0, \quad N_i \triangleright X_0 = X_i$$

$$R_i \triangleright X_j = \epsilon_{ij}^kX_k, \quad R_i \triangleright X_0 = 0,$$

(45)

$^2 T_\mu, N_i, R_i$ are respectively translations, boosts and rotations.
its action on the product of coordinates has to be modified in order to be consistent with the non-trivial commutation relation (21), that is we demand that

\[ T \triangleright [X_\mu, X_\nu] = C^{\alpha}_{\mu \nu} T \triangleright X_\alpha, \quad \forall T = T_\mu, R_i, N_i, \]

and \( C^{\alpha}_{\mu \nu} \) is the structure constant of an \( \mathfrak{an}_3 \). To implement this one needs to deform the coalgebra structure of the Poincaré algebra, that is one deforms the coproduct\(^3\) \( \Delta \)

\[
\begin{align*}
\Delta T_\mu &= T_\mu \otimes 1 + 1 \otimes T_\mu - \kappa^{-1} T_0 \otimes T_\mu \\
\Delta N_i &= N_i \otimes 1 + 1 \otimes N_i - \kappa^{-1} T_0 \otimes N_i + \kappa^{-1} \epsilon^{ijk} T_k \otimes R_j \\
\Delta R_i &= R_i \otimes 1 + 1 \otimes R_i. \tag{47}
\end{align*}
\]

Thanks to this new coproduct, the Poincaré transformations and the commutation relations (21) are consistent, i.e. (46) is true. Moreover, using the coproduct, we can act on the plane-wave and deduce the realization of the Poincaré transformations in terms of the coordinates \( k_\mu \). We recover precisely the \( \kappa \)-algebra (36) as one could have guessed. Finally, as we mentioned earlier, the "physical" notion of momentum \( \pi_\mu \) can be identified from the action of the translations on the plane-wave

\[ T_\mu \triangleright h(k_\nu) = \pi_\mu h(k_\nu). \]

Direct calculation \([31]\), using again the coproduct shows that

\[ \pi_\mu = \kappa v_\mu. \]

We have therefore a non-linear relation between the wave-vector \( k_\mu \) and the momentum \( \pi_\mu \). Moreover, using the 5d bicovariant differential calculus, it was also shown that the conserved charges, for the free action \([14]\), associated to the translations are precisely \( \pi_\mu \). With this choice of momentum the propagator \( K_2(h) \) becomes simply \( K_2(h) = \pi_\mu \pi^\mu - m^2 \), thanks to the de Sitter constraint \( \pi_A \pi^A = \kappa^2 \).

V. DERIVING DEFORMED SPECIAL RELATIVITY FROM GROUP FIELD THEORY

We now come to the main issue we address in this paper: to obtain a field theory on \( \kappa \)-Minkowski (or equivalently on \( \mathcal{AN}_3 \) momentum space) from a 4d group field theory, in particular from one that could be related to 4d Quantum Gravity. We have already shown the general construction leading from a generic 4d GFT to an effective QFT based on the same group manifold. Now the task is to specialize that construction to the case of physical interest.

We start from the group field theory describing topological BF-theory for the non-compact gauge group \( \text{SO}(4,1) \).

There are several reasons of interest in this model. First of all, the McDowell-Mansouri formulation (as well as related ones \([20]\)) of General Relativity with cosmological constant defines 4d gravity as a BF-theory for \( \text{SO}(4,1) \) plus a potential term which breaks the gauge symmetry from \( \text{SO}(4,1) \) down to the Lorentz group \( \text{SO}(3,1) \). On the one hand, this leads to the idea of understanding gravity as a phase of a fundamental topological field theory, an idea that has been put forward several times in the past. On the other hand, it suggests to try to define Quantum Gravity in the spin foam context as a perturbation of a topological spin foam model for \( \text{SO}(4,1) \) BF theory. These ideas could also be implemented directly at the GFT level. If one does so, the starting point would necessarily be a GFT for \( \text{SO}(4,1) \) of the type we use below. Second, as this model describes \( \text{SO}(4,1) \) BF theory in a "3rd quantized" setting, we expect any classical solution of the

\(^3\) Indeed, we have for example for a translation

\[ T_\mu \triangleright (X_\alpha X_\beta) = T_\mu \triangleright m(X_\alpha \otimes X_\beta) = m[(\Delta T_\mu \triangleright (X_\alpha \otimes X_\beta)], \tag{46} \]

where \( m \) is the multiplication.
GFT equations to represent quantum de Sitter space on some given topology, analogously to what happens with Minkowski space in the $SO(3,1)$ case. Such configurations would most likely be present (and physically relevant) also in a complete non-topological gravity model obtained starting from the topological one. Third, and partly as a consequence of the above, to start from the spinfoam/GFT model for $SO(4,1)$ BF-theory seems to be the correct arena to build a spin foam model for 4d quantum gravity plus particles on de Sitter space \[33\], treating particles as arising from topological curvature defects for an $SO(4,1)$ connection, along the lines of what has been already achieved in 3d gravity \[18\].

We do not describe the structure of the corresponding spin foam path integral, as the spin foam (perturbative) formulation plays no role in our construction. We start instead directly with the relevant group field theory, and work only at the level of the GFT action. As in the compact group case, we consider a gauge invariant field on $SO(4,1)^\times 4$:

$$
\phi(g_1,g_2,g_3,g_4) = \phi(g_1g,g_2g,g_3g,g_4g), \quad \forall g \in SO(4,1),
$$

and the group field action is given by:

$$
S_{4d} = \frac{1}{2} \int [dg]^3 \phi(g_1,g_2,g_3,g_4)\phi(g_4,g_3,g_2,g_1) - \lambda \int [dg]^9 \phi(g_1,g_2,g_3,g_4)\phi(g_4,g_5,g_6,g_7)\phi(g_7,g_3,g_8,g_9)\phi(g_9,g_6,g_2,g_{10})\phi(g_{10},g_8,g_5,g_1).
$$

Because of the symmetry requirement, one of the field arguments in redundant, and one can effectively work with a field depending on only three group elements. This is indicated schematically above, where, we integrate only over three group elements in the kinetic term and nine in the interaction term in order to avoid redundant integrations, which would lead to divergences due to the non-compactness of the group $SO(4,1)$. More precisely, considering the kinetic term, we can fix one of the four group elements, say $g_4$, to an arbitrary value (usually the identity $I$) and integrate over the remaining three group elements without changing anything to the final result. Similarly, the restriction to only nine integrations in the interaction term can be understood as a partial gauge fixing, avoiding redundancies and associated divergences.

Starting with this group field theory, we want to derive the DSR field theory as a sector of the full theory. We follow the same strategy as in the three-dimensional case and as outlined earlier for the 4-dimensional case: we search for classical solutions of the $SO(4,1)$ group field theory and study specific two-dimensional field variations around it. We will naturally obtain an effective field theory living on $SO(4,1)$. On top of this, we want then to obtain, from such effective field theory, one that is restricted to the $AN_3$ (or $AN_3^c$) homogeneous space (subgroup). There are three main strategies following which this could be achieved, a priori:

- We could derive first an effective field theory on $SO(4,1)$ and then study the possibility and mechanism for a decoupling of the $AN_3$ degrees of freedom from the ones living on the Lorentz $SO(3,1)$ sector of the initial $SO(4,1)$ group.

- We could try to identify some special classical solutions of the fundamental $SO(4,1)$ group field theory, which are such that the effective matter field would naturally result in being localized on $AN_3^c$.

- We could modify the initial $SO(4,1)$ group field theory action in such a way that, after the same procedure, the resulting effective matter field is automatically localized on $AN_3^c$ (or $AN_3$).

Anticipating the results of this section, we will see that the first strategy leads naturally to a DSR kinetic term, depending only on $AN_3$ degrees of freedom, and thus with an exact decoupling of the $SO(3,1)$ modes. However, the interaction term still couples the two sets of modes. This leads to the suggestion that the reduction to a pure $AN_3$ theory can be a dynamical effect, and we will show the effective pure $AN_3$ theory. As for the second strategy, we will see that it does not work as simply as stated, and it requires necessarily a modification of the initial group field theory action, i.e. to some version of the third strategy. We will discuss some ways in which this can be implemented, but we will see that the simplest way to achieve this is to start directly with a group field theory for BF-theory with gauge group $AN_3$. 
1. Deformed Special Relativity as a Phase of SO(4,1) GFT

Let us start from the action above defining the group field theory for the SO(4,1) BF-theory. The first task is to write the field equations and identify classical solutions. This works as in the compact group case presented in section III. We use the same ansatz:

\[ \phi^{(0)}(g_i) = 3 \sqrt{\frac{4!}{\Lambda}} \int_{SO(4,1)} dg \, \delta(g_1 g) F(g_2 g) \bar{F}(g_3 g) \delta(g_4 g), \]

where the functions \( F \) and \( \bar{F} \) must satisfy the normalization condition \( \int F \bar{F} = 1 \). Moreover, we also require that \( \int F \) and \( \int \bar{F} \) be finite in order to get a meaningful effective action for the 2d field variations around the classical solutions.

The ansatz that we choose is tailored to lead us to the DSR field theory \(^4\):

\[ F(g) = \alpha(v_4(g) + a) \delta(g), \quad \bar{F}(g) = \delta(g). \] (50)

The function \( v_4 \) is defined as matrix element of the Lorentz subgroup of \( SO(3,1) \) Lorentz subgroup. \( \delta(g) \) is a cut-off function providing a regularization of \( F \), so that it becomes an \( L^1 \) function. We first check the normalization condition \( \int F \bar{F} = \alpha(a+1) \delta(1) = 1 \), and, assuming that \( \delta(1) = 1 \), we require \( \alpha = (a+1)^{-1} \) in order for it to be satisfied.

Then we can derive the effective action around such classical solutions for 2d field variations just as in the compact group case given in [19]:

\[ S_{eff}[\psi] = \frac{1}{2} \int \psi(g) \psi(g^{-1}) \left[ 1 - 2c^2 - \vartheta^2 \left( \frac{2c(a + v_4)}{(a+1)^2} \right)^2 \right] - c \left( A \right) \int \psi(g_1) \psi(g_3) \delta(g_1 g_3) \left[ c + F(g_3) \right] \]

\[ - c \left( A \right) \int \psi(g_4) \delta(g_4 g_3) - \frac{\Lambda}{2} \int \psi(g_1) \psi(g_3) \delta(g_1 g_3), \] (51)

where \( c = \int F \). Thus the last issue to address in order to properly define this action is to compute the integral of \( F \). The function \( v_4(g) \) is invariant under the Lorentz group \( SO(3,1) \). Using the Iwasawa decomposition \( g = hA \Lambda \) with \( h \in AN^c_3 \) and \( A \in SO(3,1) \), it is easy to see that the matrix element \( v_4(g) \) actually only depends on \( h \). Therefore it is natural to split the cut-off function \( \delta(g) \) in factors independently regularizing the integrals over \( AN^c_3 \) and over \( SO(3,1) \):

\[ \delta(g) = \chi(h) \theta(A). \] (52)

To keep calculations simple, we assume that we choose the function \( \theta(A) \) to be a Gaussian function, or any other function peaked on \( A = \I \), such that \( \theta(1) = 1 \) and \( \int \theta = 1 \). Then using the isomorphism between \( AN^c_3 \) and the de Sitter space \( v_4 v^4 = 1 \), we choose the cut-off function on \( AN^c_3 \) to be \( L^1 \) and symmetric under \( v_4 \leftrightarrow -v_4 \): the simplest choice is to bound \( |v_0| \leq V \), which automatically also bounds \( v_4 \) and \( v \). We get:

\[ c = \int F = \int dh \chi(h) \frac{a + v_4(h)}{a + 1} = \int \left[ d^5 v_A \right] \delta(v^2 - v_0^2 - 1) \chi(v_A) \frac{a + v}{a + 1} = \frac{a}{2} \int_{ds} \chi, \] (53)

since \( v_4 \) is an odd function on the de Sitter space. For our simplest choice of \( \chi \)-function imposing a straightforward bound on \( v_0 \), we easily evaluate:

\[ \int_{ds} \chi(v) = 4\pi \int_{-V}^{V} dv_0 \sqrt{1 + v_0^2} \int_{-\sqrt{1 + v_0^2}}^{\sqrt{1 + v_0^2}} dv_4 \sqrt{1 + v_0^2 - v_4^2} = \frac{4\pi^2}{3} V(V^2 + 3). \] (54)

---

\(^4\) We can also choose a more symmetric ansatz with \( F(g) = \bar{F}(g) \) which would correspond to a group field satisfying the reality condition. The resulting calculations would be more involved, and this is why we do not discuss in detail this choice. However, it can be easily checked that, with a similar regularization, the final result would be the same.
For more generic choices of cut-off functions $\chi$, the last factor $\int_{dS} \chi$ is at most quartic$^5$ in the cut-off value $V$.

If we want to remove the cut-off and re-absorb all the infinities due to the non-compactness of the group, we could now send the cut-off $V$ to $\infty$, and then we also send the factor $a$ to 0, scaling it as $a \propto 1/V^3$. In this way, we keep $c$ finite. This is the simplest method to achieve the result, but of course others can be considered. We point out that this renormalization is done at the classical level in the definition of our classical solution and not at the quantum level like in quantum field theory. In other words, this regularization is necessary in order to obtain a true and well-defined classical solution of the equations of motion, and meaningful variations around it.

After all these regularization details, in the double scaling limit$^6$ $a \to 0$ and $L \to \infty$ while keeping $c$ finite, we have derived an effective theory for a field $\psi(g)$ living on $SO(4,1)$:

$$S_{ef}[\psi] = \frac{1}{2} \int \psi(g)\psi(g^{-1}) \left[ 1 - 2c^2 - 2c\chi(h)\theta(\lambda)^2 \right] - 3\sqrt{\frac{\lambda}{4!}} \int \psi(g_1)\psi(g_2) \delta(g_1g_2) \left[ c^2 + cF(g_1) \right]$$

$$-c \left( 3\sqrt{\frac{\lambda}{4!}} \right)^2 \int \psi(g_1)\psi(g_4) \delta(g_1g_4) - \frac{\lambda}{5!} \int \psi(g_1)\psi(g_5) \delta(g_1g_5).$$

We recognize the correct kinetic term for a DSR field theory. However, the effective matter field is a priori still defined on the full $SO(4,1)$ momentum manifold. The only remaining issue is therefore to understand the “localization” process of the field $\psi$ to $AN_5^c$. Having done this, we would truly have derived a scalar field theory in deformed special relativity from the group field theory defining topological $SO(4,1)$ BF-theory, and thus a sector of 4d quantum gravity.

Let us consider the second strategy envisaged above. A possible solution to the localization issue is, the strategy goes, to use the classical solution $F$ itself to localize the field on the $AN_5^c$ manifold. For example, one may require that the regularizing function $\theta(\Lambda)$ forces the $SO(3,1)$ group element to be, say, the identity element, $\Lambda = I$. The simplest choice is to use a delta function on $SO(3,1)$. This however causes two problems. First, both $\theta(\Lambda)$ and $\theta(\Lambda)^2$ appear in the action above, and of course the square of the $\delta$-distribution is not well-defined. One can devise methods to overcome this purely mathematical problem, by using suitable “smoothed”delta distributions, which achieve the same localization, but are $L^2$ functions. The second problem is however more fundamental. By construction, this method forces the group element $g$ to lay in $AN_5^c$ only in the terms containing some factors $F(g)$, i.e. depending in a non-trivial way (not as an overall constant) on the classical solution chosen. Thus the mass term and most of the interaction terms are completely transparent to this way of projecting on $AN_5^c$. We conclude that it is not enough to use the classical solution to achieve this reduction from the full group $SO(4,1)$ to the sub-manifold $AN_5^c$.

We then look more carefully at the first strategy outlined above. We see immediately that the kinetic term (containing the differential operator defining the propagation of the field degrees of freedom, as well as the symplectic structure in a canonical setting), does not show any dependence on the Lorentz sector. Indeed, through our choice of classical solution, we obtained a kinetic term in $v_4(g)$ which depends only on the $\Lambda$ part $h$ of the group element $g = h\Lambda$. This suggests that the $SO(3,1)$ degrees of freedom are non-dynamical and that the restriction of the domain of definition of the field $\psi$ to $AN_5^c$ group elements defines a dynamically stable phase of the theory. This would be trivially true if not for the fact that the interaction term does, a priori, depend also on the Lorentz degrees of freedom, and couples them among the different interacting fields. One way to make this manifest is, for example, to assume that the perturbation field $\psi$ has a product $^5$

$^5$ As an example, for a cut-off function $\chi$ implementing directly a bound on $v_4$ and the 3-vector $v$, we have:

$$\int_{dS} \chi(v) = 4\pi \int_{-V}^{+V} dv_4 \int_{-V}^{+V} dt \frac{v^2}{2\sqrt{v^2 + v_4^2 - 1}} \propto V^3 \ln V.$$  

$^6$ Obviously, we do not need to take the limit. We could keep $a, L, c$ all finite and define a solution parameterized by these constants. As a result, we would simply get extra constant terms in the action, e.g. terms in $a^2$ and $av_4(h)$ in the propagator. The limiting procedure is implemented only in order to get a simpler form of the action.
structure $\psi(g) = \tilde{\psi}(h)\Psi(\Lambda)$. We see that, as far as the kinetic term is concerned, the only contribution from the Lorentz sector is a constant multiplicative term $\int_{SO(3,1)} d\Psi(\Lambda)\Psi(\Lambda)$. Therefore we get an exactly DSR-like and $\kappa$-Poincaré invariant free field theory. On the other hand, the vertex term couples Lorentz and $AN_3$ degrees of freedom, and thus the $\psi$ and $\Psi$ parts of the field $\phi$; thus the $\kappa$-Poincaré symmetry is broken and the pure DSR-like form lost.

The above also shows that, if we were to choose the dependence of the perturbation field on the Lorentz sector to be trivial, i.e. $\Psi(\Lambda) \equiv 1$, and thus to start from a perturbation field defined only on the $AN_3$ subgroup, we would indeed obtain a nice DSR field theory, but with an interaction term that would be more complicated that a simple polynomial interaction. This would be due to the integrations over the Lorentz group manifold that, through the delta function, would complicated the couplings between the $AN_3$ variables on which the fields depend. Of course, it would be a possible DSR field theory nevertheless.

Still, because of the form of the kinetic term, we conjecture a reduction to the $AN_3$ sector to happen dynamically. This dynamical reduction could be obtained in two main ways. First, one could expect that transition (scattering) amplitudes involving only real particles defined on $AN_3$, i.e. with momenta in this submanifold, will not lead to creation of particles with Lorentz degrees of freedom as well, due to the form of the propagator, even if in principle they would be allowed by the enlarged momentum conservation law coming from the interaction term, which is defined on the full $SO(4,1)$ group. A second possibility is that a proper canonical analysis of the effective field theory we have obtained would show that the $SO(3,1)$ modes are pure gauge and can simply fixed from the start and thus drop from the action altogether. We leave a more detailed analysis of this issue for future work. Whether or not the restriction to $AN_3$ is obtained automatically, in one of the above ways, or by some other procedure that will be revealed by a more detailed analysis, what is certain is that a restricted theory obtained from the above and living on $AN_3^c$ only is dynamically stable. In fact, if we consider only excitations of the field in $AN_3^c$, we will never obtain excitations in $SO(3,1)$ due to momentum conservation $\delta(g_1..g_n)$ since $AN_3^c$ is a subgroup. Therefore $AN_3^c$ is stable under the dynamics of the field theory, and thus a restriction to fields on $AN_3^c$ is consistent.

One can compare this situation to the case of a 2d field theory written in momentum space where the propagator depends on $p_x$ and not on $p_y$:

$$S_{eg}[\psi] = \int d^2\vec{p}(-p_x^2)\psi(-\vec{p})\psi(\vec{p}) + \int [d^2\vec{p}]^n \delta \left( \sum_i p^{(i)}_x \right) \prod_i \psi(p^{(i)}_x).$$

The momentum $p_y$ does not enter the propagator and it defines a pure gauge degree of freedom, as it can be checked by straightforward canonical analysis. Therefore, we can restrict ourselves to the sector $p_y = 0$ without affecting the dynamics of the field, nor any physical content of the theory.

Then, restricting ourselves to group elements $g_i = h_i \in AN_3^c$, we have the (non-commutative) field theory:

$$S_{final}[\psi] = \frac{1}{2} \int dh \psi(h)\psi(h^{-1}) \left[ 1 - 2c^2 - 2cv_4(h)^2\chi(h)^2 \right] - 3\sqrt{\frac{\lambda}{4!}} \int \psi(h_1)\psi(h_3) \delta(h_1..h_3) \left[ c^2 + cv_4(h_3)\chi(h_3) \right]$$

$$-c \left( 3\sqrt{\frac{\lambda}{4!}} \right)^2 \int \psi(h_1)\psi(h_4) \delta(h_1..h_4) - \Delta \left( \frac{\lambda}{5!} \right)^2 \int \psi(h_1)\psi(h_5) \delta(h_1..h_5),$$

where the left-invariant measure on $AN_3^c$ is inherited from the Haar measure on $SO(4,1)$. We argue that this is the theory that encodes the full dynamics of 2d perturbations, as emergent matter fields, of the $SO(4,1)$ GFT, around the special classical solution we have chosen. We have thus finally derived the scalar field theory for deformed special relativity with a $\kappa$-deformed Poincaré symmetry from the $SO(4,1)$ group field theory defining the transition amplitudes for the topological BF-theory. To summarize, this was achieved in three steps:

1. Identify the correct regularized classical solution(s) to the initial group field theory.

2. Look at the two-dimensional field variations around such a classical solution and write the effective action describing their dynamics.
3. Localize the field variations on the $\text{AN}_5^c$ group manifold relevant to deformed special relativity.

An important remark is that we have a field theory already with an in-built cut-off in momentum space due to the regularizing function $\chi(h)$, necessary to define the classical solution to the group field theory. Of course we can always send this cut-off to infinity by the double scaling limit $V \rightarrow \infty$, $a \rightarrow 0$. At the quantum level, we would anyway have to introduce such a momentum cut-off to define the perturbative expansion of the quantum field theory in term of Feynman diagrams. Here, on the other hand, the momentum cut-off is not included to regularize the Feynman diagrams, i.e. the discrete quantum histories of the theory, but it appears naturally in our derivation of the effective field theory on $\text{AN}_5^c$ from the initial group field theory on $\text{SO}(4,1)$. Indeed, we insist on the fact that the classical solution around which we study the group field variation can not be defined without this momentum cut-off.

We conclude this case mentioning the open issue of the role of the $\text{SO}(3,1)$ degrees of freedom. As we noticed above, they would actually couple non-trivially to the $\text{AN}_5^c$ momentum, within the full $\text{SO}(4,1)$ theory, through the non-abelian momentum conservation $\delta(g_{1}g_{2}...) = \delta(h_{1}A_{1}h_{2}A_{2}...)$. We argued that they may correspond to pure gauge degrees of freedom, and consequently restricted the model to the pure $\text{AN}_5^c$ sector. Another possibility may be to use them to take into account spin degrees of freedom, and thus define an emergent matter field theory for spinning particles. In general, if it turns out that our conjecture is incorrect, it would be interesting to show what is their physical effect.

2. Starting from a restricted GFT: the $\text{AN}_3$ case

Having followed in detail the first strategy outlined above, and having shown the non-viability of the second, we now describe the third, and obtain a DSR-like field theory in a different way. Accordingly, instead of localizing the field variation on $\text{AN}_5^c$ in the final step, having first derived an effective field theory on $\text{SO}(4,1)$, we could modify our starting group field theory action in such a way that the effective field theory for perturbations is automatically localized on $\text{AN}_5^c$.

The first case we deal with is the simplest one in which we choose our initial fundamental theory to be itself a group field theory for 4d BF theory with $\text{AN}_5^c$ gauge group. We can then perform the same analysis as in section I and then choose the same classical solution we have used in the previous section (now seen as a function on the $\text{AN}_5^c$ subgroup of $\text{SO}(4,1)$ only. This naturally to a field theory on $\text{AN}_5^c$ describing a scalar field with a deformed special relativity kinematics. The drawback is that the link with 4d quantum gravity is now more obscure. It is still possible that such group field theory is related to the quantization of the McDowell-Mansouri formulation of 4d gravity, but the exact relation is unclear. It still defines a topological spin foam model, thus lacking any local gravity degree of freedom; moreover, it lacks information contained in $\text{SO}(4,1)$ BF, e.g. the cosmological constant, and its classical solutions have no immediate spacetime interpretation, contrary to that case.

Still, it represents the easiest route to a DSR field theory from GFT. The only issue that one has to be careful with in this case is the question of the measure since we have to decide whether to use the left or right invariant measure. Since the left-invariant measure is the one inherited from the Haar measure on $\text{SO}(4,1)$, it seems to be the natural one to use. As before, we introduce the gauge invariant group field on $(\text{AN}_3^c)^{\times 4}$:

$$\phi(h_1, ..., h_4) = \phi(h_1h^{-1}, ..., h_4h^{-1}), \quad \forall h \in \text{AN}_3^c,$$

and the corresponding action:

$$S_{an}[\phi] = \frac{1}{2} \int [dh]^3 \phi(h_1, h_2, h_3, h_4)\phi(h_4, h_3, h_2, h_1)$$

$$\quad - \frac{\lambda}{3!} \int [dh]^9 \delta(h_1, h_2, h_3, h_4)\phi(h_4, h_5, h_6, h_7)\phi(h_7, h_3, h_8, h_9)\phi(h_9, h_6, h_2, h_{10})\phi(h_{10}, h_8, h_5, h_1),$$

where we have used everywhere the left-invariant measure $dh_L$ on $\text{AN}_5^c$. As before we check that the “flat solution” ansatz,

$$\phi^{(0)} \equiv \sqrt[3]{\frac{4\pi^2}{\lambda}} \int dh_{(L)} \delta(h_1h^{-1})F(h_2h^{-1})F(h_3h^{-1})\delta(h_4h^{-1}),$$

(57)
provides a classical solution to the group field theory as soon as \( \int F \tilde{F} = 1 \). Thus we should choose the same ansatz for the arbitrary functions:

\[
F(h) = \frac{v_4(h) + a}{a + 1} \chi(h), \quad \tilde{F}(h) = \delta(h),
\]

where we choose exactly the same regularizing function \( \chi(h) \) as in the previous section, e.g. the one imposing the bound \( v_0(h)^2 \leq V^2 \). We then look at the effective action for two-dimensional field variation \( \phi^{(0)} + \psi(h_1 h_4^{-1}) \) around the classical solution. Using the left-invariance of the measure, we end up of course with the same effective scalar field theory living on \( \text{AN}^3 \).

As said, this gives the shortest path from a four-dimensional group field theory and deformed special relativity. The natural question in this context is nevertheless the physical meaning/relevance of 4d BF-theory with gauge group AN\(^5\), from a 4d quantum gravity standpoint, as we discussed.

We may attempt to strengthen the link with the SO(4, 1) theory, while remaining within the third strategy outlined above, and go beyond the purely \( \text{AN}^3 \) case. In fact, there seems to be the possibility of intermediate schemes: we could start from a restricted GFT on SO(4, 1), i.e. one based on the action \( \text{III} \) but with some appropriate modification of the kinetic and vertex terms tailored to give a \( \text{AN}_3 \) effective theory for the perturbations. One could hope also that this restricted GFT would still be close to a group field theory quantization of the McDowell-Mansouri action for gravity. We mention here only one such restriction, leaving a more detailed study for future work: instead of projecting all the group elements of the group field \( \phi(g_1, g_2, g_3, g_4) \) on the \( \text{AN}_3 \) subgroup, we could simply constrain the group elements \( g_1 \) and \( g_4 \) to lay in this submanifold. It is easy to see that this automatically localizes the field variations \( \psi(g_1 g_4^{-1}) \) on \( \text{AN}^5 \), and thus, in the end, a DSR field theory, by the same procedure explained above. The physical content of such modified GFT remains unclear, however. It seems to us that issue of the physical meaning of a group field theory partially or totally projected on \( \text{AN}^3 \) can only come from a more thorough study of the spinfoam/GFT quantization of the McDowell-Mansouri reformulation of General Relativity. Therefore, we do not discuss any such mixed scheme any further.

VI. GFT VS EMERGENT ANALOG GRAVITY MODELS

We conclude by pointing out the similarity of the procedure we have used in our GFT context, for deriving effective matter field theories, with the one that is customary in condensed matter analog gravity models, for deriving effective field theories for quasi-particles on emergent geometries. Indeed, we can see that they are fully analogous and that the differences are mostly of a purely technical nature. In fact, GFTs have been argued to be a natural framework to discuss about "emergent gravity" ideas, and in particular to use ideas from statistical physics and condensed matter theory to bridge the gap between the microscopic description of quantum spacetime provided by GFTs and the continuum physics we are accustomed to. Our results can be therefore motivated also from this perspective, and acquire thus an additional reason of interest on top of those mentioned in the introduction (this aspect is also discussed in [34]). Here we limit ourselves to presenting the main points of this perspective, and to showing in which sense our procedure resembles the one used in the context of condensed matter analog gravity models, and where it differs from it.

Let us first of all clarify what we mean by emergence. We call "emergent" some degrees of freedom which are only defined in a given regime, and there in terms of more fundamental degrees of freedom. For example, emergent degrees of freedom can be perturbations around some given vacuum state, like in our GFT results, or collective degrees of freedom. In general, the classical theories for these emergent degrees of freedom only give effective theories upon quantization, in other words their quantum counterpart would be meaningful only in a limited regime. A complete quantization procedure can therefore take place only on the fundamental degrees of freedom. A symmetry is called "emergent" if it applies to emergent degrees of freedom only and thus is valid only in the same limited regime in which they can be consistently defined. In general, the emergent symmetry is not related to or part of the symmetries of the fundamental system. Moreover, if the emergent symmetry is not already among the fundamental symmetries, then it is never exact but it is realized only approximately in the effective theory.
Condensed matter theory offers several specific examples of systems in which the collective behavior of the microscopic constituents in some hydrodynamic approximation gives rise to effective emergent geometries as well as matter fields (superfluid Helium-3, Bose-Einstein condensates, etc) [32]. Thus it supports the idea that gravity and matter may emerge from fundamental systems which do not have a geometric or gravitational nature per se, at least in their fundamental formulation (like GFTs).

The emergence of gravity and (generically) curved geometries in analog condensed matter models takes place usually in the hydrodynamic regime, which in turn is often obtained in some mean field approximation around a background configuration of the fluid. What happens is that the collective parameters describing the fluid and its dynamics in these background configurations (e.g. the density and velocity of the fluid in the laboratory frame) can be recast as the component functions of an effective metric field. This is not cosmetics. Indeed, in some very special systems and approximations the hydrodynamic equations governing the dynamic of the effective metrics, when recast in geometric terms, can also be seen to reproduce known geometrodynamic theories, at least in part, ranging from Newtonian gravity to (almost) GR. This first type of results is so far limited to special systems, peculiar approximations, and ultimately not fully satisfactory, as it has not been possible yet to reproduce, say, the Einstein-Hilbert dynamics in any, however idealized, condensed matter system. On the contrary, it is a very general result that the effective dynamics of perturbations around the same background configurations turns out to be given by matter field theories in curved spacetimes, whose geometry is indeed the one identified by the effective metrics obtained from the collective background parameters of the fluid. Moreover, the effective theories have often relativistic (if approximate) symmetries, even if the fundamental theory may be invariant only under galilean symmetries. In this sense, we can speak of matter and Lorentz symmetry as emerging. It is this type of results that we managed to reproduce, so far, in a GFT context, including the results of this paper.

The general scheme of what goes on in all these condensed matter systems, concerning the emergence of effective matter field theories, is well captured by the following “meta-model” (see [32] for details and for the exact assumptions entering the model).

One considers (for simplicity) a scalar field $\phi(x)$, encoding the kinematical variables of the system (fluid) under consideration (e.g. velocity and density of a condensate in the hydrodynamic approximation) on a classical continuum spacetime $M$ of dimension $d$, with a dynamics governed by the lagrangian $L(\phi, \partial_\mu \phi, h_{\mu\nu})$ function of $\phi$ and its derivatives $\partial_\mu \phi$ with respect to coordinates on $M$. Note that if we introduce derivatives, we need to introduce tensors such as a metric $h_{\mu\nu}$ to contract indices. A priori we do not make any assumption on the signature of this metric tensor.

We introduce the solution $\phi_0(x)$ of the equations of motion induced by $L$, and then perturbations around $\phi_0(x)$:

$$\phi(x) = \phi_0(x) + \phi_1(x).$$

Expanding the Lagrangian around the classical solution chosen, we obtain:

$$L(\phi, \partial_\mu \phi, h_{\mu\nu}) = L(\phi_0, \partial_\mu \phi_0, h_{\mu\nu}) + \frac{\partial L}{\partial (\partial_\mu \phi)}|_{\phi_0} \partial_\mu \phi_1 + \frac{\partial L}{\partial \phi}|_{\phi_0} \phi_1 + \frac{\partial^2 L}{\partial (\partial_\mu \phi) \partial (\partial_\nu \phi)}|_{\phi_0} \partial_\mu \phi_1 \partial_\nu \phi_1 + \frac{\partial^2 L}{\partial \phi \partial \phi}|_{\phi_0} \phi_1 \phi_1 + \ldots$$

We can make a measure $[d\mu] = m dx^d = m dx$ on $M$ (where $m$ depends on the metric $h_{\mu\nu}$, of course), and define an action for the fundamental field $\phi$, which in turns implies an action for the perturbations [33]:

$$\mathcal{B}[\phi] = \int_M [d\mu] L = \mathcal{B}[\phi_0, m] + \frac{\epsilon^2}{2} \int_M [d\mu] \left[ \frac{\partial^2 L}{\partial (\partial_\mu \phi) \partial (\partial_\nu \phi)} |_{\phi_0} \partial_\mu \phi_1 \partial_\nu \phi_1 + \left( \frac{\partial^2 L}{\partial \phi \partial \phi} |_{\phi_0} - \partial_\mu \left( \frac{\partial^2 L}{\partial (\partial_\nu \phi) \partial (\partial_\mu \phi)} \right) \right) |_{\phi_0} \phi_1 \phi_1 \right].$$

The usual approach in the emergent gravity framework is to identify the emergent (inverse) metric $g^{\mu\nu}$ and measure $[dx^d]$ (depending both on $\phi_0$) in (62) as

$$(dx^d \sqrt{|g|}) g^{\mu\nu} = [dx^d] g^{\mu\nu} \equiv [d\mu] \frac{\partial^2 L}{\partial (\partial_\mu \phi) \partial (\partial_\nu \phi)} |_{\phi_0} = m dx^d \frac{\partial^2 L}{\partial (\partial_\mu \phi) \partial (\partial_\nu \phi)} |_{\phi_0}.$$
where \( g = \text{det} g_{\mu\nu} \). The equation of motion for the perturbations from the action \([62]\) read

\[
\partial_{\mu} \left[ \frac{\partial^2 \mathcal{L}}{\partial (\partial_{\mu} \phi) \partial (\partial_{\mu} \phi)} \partial_{\nu} \phi_1 \right] - \left( \frac{\partial^2 \mathcal{L}}{\partial \phi \partial \phi} - \partial_{\mu} \left( \frac{\partial^2 \mathcal{L}}{\partial (\partial_{\mu} \phi) \partial (\partial_{\mu} \phi)} \right) \right) \phi_1 = 0. \quad (64)
\]

They can be rewritten as

\[
(\Box_{\phi_0} - V_{\phi_0}(\phi_1)) \phi_1 = 0, \quad (65)
\]

with the operator \( \Box_{\phi_0} = g^{\mu\nu} \partial_{\mu} \partial_{\nu} \), for the effective (inverse) metric \( \sqrt{-g} g^{\mu\nu} = \frac{\partial^2 L}{\partial (\partial_{\mu} \phi) \partial (\partial_{\mu} \phi)} |_{\phi_0} \), and we have a potential \( V(\phi_1) \) also depending on the background field \( \phi_0 \). Note that the d’Alembertian operator is then a self-adjoint operator with respect to the measure \([dx^4]\). It is the possible to invert to obtain the effective metric and from this the other tensors characterizing the effective spacetime geometry. Notice that both the “fundamental” field and the quasi-particle one live on a 4-dimensional spacetime of trivial topology, although endowed with a different metric in general. We refer to the literature for further details and applications of the above general result. The main point to notice here is that one generically obtains an effective spacetime geometry to which the quasi-particles couple, depending only in its precise functional form on the fundamental Lagrangian \( L \) and on the classical solution \( \phi_0 \) chosen; they do not couple to the initial (laboratory) flat background metric.

This is the type of mechanism we have reproduced in a Group Field Theory context. Assuming that a given GFT model (Lagrangian) describes the microscopic dynamics of a discrete quantum spacetime, and that some solution of the corresponding fundamental equations can be interpreted as identifying a given quantum spacetime configuration, we have obtained an effective macroscopic continuum field theory for matter fields from it, and shown that the effective matter field theories that we obtain most easily from GFTs are quantum field theories on non-commutative spaces of Lie algebra type. Let us notice that, while the correspondence between classical solutions of the fundamental equations and effective geometries is a priori unexpected in condensed matter systems, which are non-geometric in nature, so that they are referred to as analog gravity models, in the GFT case the situation is different. We have here models which are non-geometric and far from usual geometrodynamics in their formalism, but which at the same time are expected to encode quantum geometric information and indeed to determine, in particular in their classical solutions, a (quantum and therefore classical) geometry for spacetime \([2,3]\), also at the continuum level, the issue being how they exactly do so. We are, in other words, far beyond a pure analogy.

However, there are also a number of differences which could be of interest, between the condensed matter context and the GFT one we have analyzed. Some are more of a technical nature. The definition of the emerging metric \([63]\) comes from derivatives of the scalar field, in particular from its kinetic term. In the GFT we consider, the kinetic term is trivial, in that it does not contain derivatives of the field. We are however dealing with a non-local theory (contrary to the lagrangian \( L \)), because of the combinatorics of group convolutions in the interaction term, and the propagator \( K(g) \) is then generated from this non-local potential.

Usually in analog models one works with a space-time which is topologically \( \mathbb{R}^4 \). This background is used to define the fundamental field \( \phi \), but also the perturbations \( \phi_1 \) do see the same topological structure. What emerges and differs from the background structure is only the metric that should be added on the vector space \( \mathbb{R}^4 \) to turn it into a metric space. In the GFT model, the fundamental field is defined on a very large space \( SO(4,1)^{\times 4} \sim \mathbb{R}^{40} \) or \( AN_4^{\times 4} \sim \mathbb{R}^{16} \) according to whether we consider the group to be \( SO(4,1) \) or \( AN_3 \), and both are non-commutative spaces. We then look at 2d perturbations defined on the space \( SO(4,1) \sim \mathbb{R}^{10} \) or \( AN_4 \sim \mathbb{R}^4 \), which are again non-commutative spaces of a similar type but of much lower dimension. This dimensional reduction is natural in GFT models as well as from the point of view of point particles coupled to gravity at the spin foam (GFT perturbative expansion) level. However, we are not aware of a similar phenomenon in usual analog models. As a consequence, the symmetries of the fundamental theory are clearly larger than the “emerging” \( \kappa \)-Poincaré symmetry. This latter arose because of the dimension reduction and the specific choice of classical solution. It is quite possible that different solutions would then generate different symmetry groups. For example by choosing a different vector \( v_0 \), we can have access to different subgroups of \( SO(4,1) \). This feature is similar to some situations in analog models, where choosing different solutions can generate different metrics and therefore different space-time with different symmetry groups. For example in BEC, one can generate the Schwarzschild space-time, FRW
space-time or Minkowski space-time according to the chosen features of the background condensate. What is not considered, again, is that the choice of solution could have also the additional dimension reduction effect we could see in GFT models. For example, if the perturbation was defined on \( \mathbb{R}^{10} \sim SO(4,1) \), introducing the specific solution encoded in \( F \) reduces the dynamical field content to fields living on \( \mathbb{R}^4 \). Similarly, our choice of a perturbation field living on a subspace of the spacetime in which the fundamental GFT field lives has again no analog in condensed matter systems.

At a more conceptual level, we point out a further, important difference between our procedure and the situation in condensed matter analog models. Quasi-particle dynamics on effective emergent metrics is obtained, in analog gravity models, from the hydrodynamics of the fundamental system, i.e. from what is already an effective theory with respect to the fundamental description of the microscopic dynamics of the system (e.g. the non-relativistic quantum field theory for the atoms of Helium in superfluid Helium-3). In our GFT context, on the other hand, we have applied a similar procedure directly to the fundamental microscopic field theory. One practical reason for this is simply that no coherent effective description of GFT models has been developed, even though its necessity has been argued for \[11\]; another is that we have made crucial use of the fundamental definition of GFTs as field theories on group manifolds (suitably reinterpreted as momentum space) in order to obtain our effective matter fields living on non-commutative spaces of Lie algebra type. In fact, in the end this is why we have obtained non-commutative field theories for the emergent matter, as opposed to ordinary field theories, and one could speculate that this feature would be lost if the procedure was applied in some (to be sought for) effective GFT dynamics corresponding to some ordinary, continuum, classical geometrodynamics, thus such that it has lost memory of most of the quantum properties of spacetime at the Planck scale.

## Conclusion

We have derived a scalar field theory of the deformed special relativity type, with a \( \kappa \)-deformed Poincaré symmetry, from the \( SO(4,1) \) group field theory defining the transition amplitudes for topological BF-theory in 4 spacetime dimensions. This was done directly at the GFT level, thus bypassing the corresponding spin foam formulation, in such a way that matter fields emerge from the fundamental model as perturbations around a specific phase of it, corresponding to a solution of the fundamental equations of motion, and the non-commutative field theory governs their effective dynamics. Not only this is the first example of a derivation of a DSR model for matter from a more fundamental quantum gravity model, and one further link between non-commutative geometry and quantum gravity formulated in terms of spin foam/loop quantum gravity ideas, but it is of great interest from the point of view of quantum gravity phenomenology, as we have pointed out in the introduction. It represents, in fact, another possible way of bridging the gap between quantum gravity at Planck scale and effective (and testable) physics at low energies.

Obviously, there are many questions left unanswered in this work. Some concern purely technical details of our procedure. We have mentioned them in the bulk of this paper, so we do not repeat them. We mention here briefly a few more general ones of these open issues.

The first concern the role of the \( SO(3,1) \) degrees of freedom in the group field theory we started from, as well as in the one we have obtained as describing the dynamics of matter. From the GFT point of view it is utterly unclear why \( AN_3^c \) should be the relevant group for the perturbations as opposed to some other subgroup of \( SO(4,1) \). One can pose this same question in terms of the classical solution we have perturbed around. What is the physical meaning of the solution we have chosen? This is unclear at present, contrary to the 3d case, where the solutions used an be related to flat geometries. As mentioned, we expect it to be related to de Sitter space, but more work is needed to understand the details of the correspondence. Related to this, it would be interesting to investigate the role of the cosmological constant in this GFT context. To start with, it seems that here the presence of a cosmological constant is encoded only in the group manifold used in the starting GFT, i.e. \( SO(4,1) \), but we have little control of how this is done. Second, we have motivated the choice of starting with this GFT model also by analogy with the McDowell-Mansouri (and related) formulation of General Relativity as a \( SO(4,1) \)-gauge theory, but this works only for a strictly positive cosmological constant. It is then natural to ask what happens if we start from \( SO(3,2) \) in place of \( SO(4,1) \) in the original model and then carry out the same procedure for extracting an effective matter field theory. Further investigations are needed to establish a better link between our initial GFT model, classical...
solutions and effective field theory on the one hand, and a spin foam formulation of the Freidel-Starodubtsev classical gravity theory [20] and the particle observable insertions à la Kowalski-Glikman-Starodubtsev [20] on the other, which represent another path to deriving an effective deformed special relativity from spin foam models. Last, we have obtained a scalar field theory for matter, and thus we should now look for extensions of our procedure and result that could give instead matter fields with non-zero spin e.g. Dirac fermions or vector fields. Moreover, we have provided an example of the emergence of spacetime (deformed) isometries from GFT, but it is natural to wonder if also gauge symmetries and thus gauge fields can be seen as emerging from some fundamental (GFT) quantum gravity model. Higher spins have already encoded in 3d GFT in [36], but never in 4d and in the usual sense of coupling matter degrees of freedom to quantum gravity ones, instead of having the first emerge from the second, as in the present work. Therefore, this is an area of research that is still wide open to be explored. We leave all these questions for future work.

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