New Coherence and RIP Analysis for Weak Orthogonal Matching Pursuit

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Abstract

In this paper we define a new coherence index, named the global 2-coherence, of a given dictionary and study its relationship with the traditional mutual coherence and the restricted isometry constant. By exploring this relationship, we obtain more general results on sparse signal reconstruction using greedy algorithms in the compressive sensing (CS) framework. In particular, we obtain an improved bound over the best known results on the restricted isometry constant for successful recovery of sparse signals using orthogonal matching pursuit (OMP).

Index Terms

Compressive sensing, mutual coherence, global 2-coherence, restricted isometry property, weak orthogonal matching pursuit (WOMP), orthogonal matching pursuit (OMP)

I. INTRODUCTION

Compressive sensing (CS) [1], [2] is a newly developed and fast growing field of research. It provides a new sampling scheme that breaks the traditional Shannon-Nyquist sampling rate [3] given that the signal of interest is sparse in a certain basis or tight frame. More specifically, for a vector \( a \in \mathbb{R}^d \), let \( \|a\|_0 \) denote the \( \ell_0 \) “norm” of \( a \), which counts the number of nonzero entries of \( a \). We say \( a \) is \( k \)-sparse if \( \|a\|_0 \leq k \). CS has established conditions for finding the unique sparse solution of the following \( \ell_0 \) minimization problem

\[
\min_{a} \|a\|_0 \text{ subject to } f = \Phi a, \tag{1}
\]

where \( \Phi \in \mathbb{R}^{n \times d} (n \ll d) \) and \( f \in \mathbb{R}^n \). To ensure that the \( k \)-sparse solution is unique, we need the following restricted isometry property introduced by Candes and Tao in [4].

**Definition 1.1** (Restricted Isometry Property (RIP)). A matrix \( \Phi \) satisfies the restricted isometry property of order \( k \) with the restricted isometry constant (RIC) \( \delta_k \) if \( \delta_k \in (0, 1) \) is the smallest constant such that

\[
(1 - \delta_k)\|a\|_2^2 \leq \|\Phi a\|_2^2 \leq (1 + \delta_k)\|a\|_2^2 \tag{2}
\]

holds for all \( k \)-sparse signal \( a \).
It has been shown in [4] that if $\delta_{2k} < 1$, then the $\ell_0$ minimization problem has a unique $k$-sparse solution. However, solving an $\ell_0$ minimization problem is in general NP-hard. One solution to this problem is to relax the $\ell_0$ “norm” to the $\ell_1$ norm. Candès has shown in [5] if $\delta_{2k} < \sqrt{2} - 1$, then $\ell_1$ minimization is equivalent to $\ell_0$ minimization. Another alternative is to use heuristic greedy algorithms to approximate the solution of the $\ell_0$ minimization problem. Orthogonal matching pursuit (OMP) is one of the simplest and most popular algorithms of this type. For the analysis of greedy algorithms, the metric chosen for the sensing matrix are usually coherence indices rather than the RIC.

For simplicity, from now on, we always assume that the columns of the matrix (dictionary) $\Phi$ are normalized such that for any column $\phi \in \Phi$, $\|\phi\|_2 = 1$.

**Definition I.2.** The mutual coherence $M(\Phi)$ of a matrix $\Phi$ is defined by

$$M(\Phi) := \max_{\phi_i, \phi_j \in \Phi, i \neq j} |\langle \phi_i, \phi_j \rangle|,$$  \hspace{1cm} (3)

where $\langle \cdot, \cdot \rangle$ represents the usual inner product.

It has been shown that if $(2k - 1)M < 1$, then OMP can recover every $k$-sparse signal exactly in $k$ iterations [6]. Recently, researchers have started to investigate the performance of OMP using RIP. Davenport and Wakin [7] have proved that $\delta_{k+1} < \frac{1}{3\sqrt{k}}$ is sufficient for OMP to recover any $k$-sparse signal in $k$ iterations. Mo and Shen [8] improve the bound to $\delta_{k+1} < \frac{1}{1+\sqrt{k}}$. They also give an example that OMP fails to recover a $k$-sparse signal in $k$ steps when $\delta_{k+1} = \frac{1}{\sqrt{k}}$. This leaves a question if their bound can be further improved.

It is then natural to examine the relationship between the mutual coherence $M$ and the RIC $\delta_k$, since the bound for $M$ is already sharp. However, approaching this directly was not fruitful and this motivated us to define a new coherence index, namely the global 2-coherence, and establish a bridge connecting the mutual coherence, the global 2-coherence, and the RIC. Then by using this connection, we analyze the performance of weak orthogonal matching pursuit (WOMP), a weak version of OMP. In particular, we extend the results given in [9] to show that $\delta_k + \sqrt{k}\delta_{k+1} < 1$ is sufficient for OMP to recover any $k$-sparse signal in $k$ iterations, which provides an improved bound over the best known result given in [8] and confirms that it is not yet optimal. As mentioned above, the results presented in this paper is an extension of [9], where we introduced a new algorithm to CS, called orthogonal matching pursuit with thresholding (OMPT), and showed its reconstruction stability and robustness.

## II. Global 2-Coherence

We first define a new coherence index, the global 2-coherence, $\nu_k(\Phi)$ for a given dictionary $\Phi$. Then based on this new coherence index, we establish the connections among the coherence indices and the RIC $\delta_k$.

**Definition II.1.** Denote by $[d]$ the index set $\{1, 2, \ldots, d\}$. The global 2-coherence of a dictionary $\Phi \in \mathbb{R}^{n \times d}$ is defined as

$$\nu_k(\Phi) := \max_{i \in [d]} \max_{\Lambda \subseteq [d] \setminus \{i\}} \left( \sum_{j \in \Lambda} |\langle \phi_i, \phi_j \rangle|^2 \right)^{1/2},$$  \hspace{1cm} (4)
where \( \phi_i, \phi_j \) are columns from the dictionary \( \Phi \).

The global 2-coherence \( \nu_k(\Phi) \) defined above is a generalization of the mutual coherence defined in Definition \ref{def:mcoherence} and the coherence indices defined in \[10\], \[11\]. In particular, when \( k = 1 \), \( \nu_1 \) is exactly the mutual coherence.

The following lemma describes the relations among the mutual coherence \( M \), the 2-coherence \( \nu_k \), and the restricted isometry constant \( \delta_k \).

**Lemma II.2.** For \( k > 1 \), we have

\[
M \leq \nu_k - 1 \leq \sqrt{k-1} \nu_{k-1} \leq (k-1) M. \tag{5}
\]

The next lemma is needed to proceed to our main results.

**Lemma II.3.** Let \( \Lambda \subset [d] \) with \( |\Lambda| = k \). Let \( f = \Phi a + w \) with \( \text{supp}(a) = \Lambda \) and \( \|w\|_2 \leq \epsilon \). In addition, assume that there exits \( \Omega \subseteq \Lambda \) with \( |\Omega| = m \), such that

\[
\langle \Phi a, \phi_i \rangle = 0, \text{ for } i \in \Lambda \setminus \Omega.
\]

Then

\[
\max_{i \in [d] \setminus \Lambda} \|\langle f, \phi_i \rangle\| \leq \nu_k \|a\|_2 + \epsilon,
\]

\[
\max_{i \in \Lambda} \|\langle f, \phi_i \rangle\| \geq \frac{\sqrt{1 - \delta_k}}{\sqrt{m}} \|\Phi a\|_2 - \epsilon.
\]

### III. Main Results

We first begin with a well known greedy algorithm, the weak orthogonal matching pursuit (WOMP), which was defined in \[12\]. Here we present a simple version in Algorithm \ref{alg:womp} where the weak parameter \( \rho \) is a constant for each iteration. Notice that when \( \rho = 1 \), WOMP becomes standard OMP.

Let us consider the case where a sparse signal is contaminated by a perturbation. Specifically, let \( \Lambda \subset [d] \) with \( |\Lambda| = k \). We consider a signal \( f = \Phi a + w \), where \( a \in \mathbb{R}^d \) with \( \text{supp}(a) = \Lambda \) and \( \|w\|_2 \leq \epsilon \).

**Theorem III.1.** Denote by \( a_{\min} \) the nonzero entry of \( a \) with the least magnitude, and \( \hat{a}_{\text{womp}} \) the recovered representation of \( f \) in \( \Phi \) by WOMP after \( k \) iterations. If

\[
\sqrt{k \nu_k} < \rho(1 - \delta_k)
\]

and the noise level obeys

\[
\epsilon < \frac{\rho(1 - \delta_k) - \sqrt{k \nu_k}}{1 + \rho} |a_{\min}|,
\]

then

a) \( \hat{a}_{\text{womp}} \) has the correct sparsity pattern

\[
\text{supp}(\hat{a}_{\text{womp}}) = \text{supp}(a);
\]
Algorithm 1 Weak Orthogonal Matching Pursuit (WOMP)

1: **Input:** weak parameter \( \rho \in (0, 1] \), dictionary \( \Phi \), signal \( f \), and the noise level \( \epsilon \).

2: **Initialization:** \( r_0 := f \), \( x_0 := 0 \), \( \Lambda_0 := \emptyset \), \( s := 0 \).

3: while \( \|r_s\|_2 > \epsilon \) do

4: Find an index \( i \) such that

\[
|\langle r_s, \phi_i \rangle| \geq \rho \cdot \max_{\phi} |\langle r_s, \phi \rangle|,
\]

where \( \phi \) is any column of \( \Phi \);

5: Update the support:

\[
\Lambda_{s+1} = \Lambda_s \cup \{i\};
\]

6: Update the estimate:

\[
x_{s+1} = \arg \min_z \|f - \Phi_{\Lambda_{s+1}} z\|_2;
\]

7: Update the residual:

\[
r_{s+1} = f - \Phi_{\Lambda_{s+1}} x_{s+1};
\]

8: \( s = s + 1 \);

9: end while

10: **Output:** If the algorithm is stopped after \( k \) iterations, then the output estimate \( \hat{a} \) of \( a \) is \( \hat{a}_{\Lambda_k} = x_k \) and \( \hat{a}_{\Lambda^c_k} = 0 \).

\[b) \] \( \hat{a}_{\text{womp}} \) approximates the ideal noiseless representation

\[
\|\hat{a}_{\text{womp}} - a\|_2^2 \leq \frac{\epsilon^2}{1 - \delta_k}.
\] (8)

From Lemma II.2, it follows that

**Corollary III.2.** Let \( f = \Phi a \) with \( \|a\|_0 = k \). If one of the following conditions is satisfied,

a) \( \sqrt{k} \delta_{k+1} < \rho(1 - \delta_k) \),

b) \( \sqrt{k} \nu_k < \rho(1 - \nu_{k-1} \sqrt{k - 1}) \),

c) \( kM < \rho(1 - (k - 1)M) \),

then, \( a \) is the unique sparsest representation of \( f \) and moreover, WOMP recovers \( a \) exactly in \( k \) iterations.

The performance of WOMP decreases as \( \rho \) decreases. Now if we set \( \rho = 1 \) in WOMP, then we obtain immediately the following corollary for OMP.
Corollary III.3. Let $f = \Phi \alpha$ with $\|\alpha\|_0 = k$. If
\[\delta_k + \sqrt{k} \delta_{k+1} < 1,\] 
then, $\alpha$ is the unique sparsest representation of $f$ and moreover, OMP recovers $\alpha$ exactly in $k$ iterations.

Remark III.4. The condition in (9) gives an improved bound on the restricted isometry constant compared to the bound obtained in [8] for OMP for successful recovery after $k$ iterations, where the bound was $\delta_{k+1} < \frac{1}{\sqrt{k+1}}$.

IV. Conclusion

In this paper, we have introduced a new generalized coherence index, the global 2-coherence, and established two connections among the mutual coherence, the global 2-coherence, and the restricted isometry constant. Based on these relations, we analyzed the performance of WOMP as well as OMP for their recovery ability of sparse representations in both ideal noiseless and noisy cases. In particular, for the noiseless case, we showed an improved bound over the best known results on the restricted isometry constant for successful recovery using OMP.

APPENDIX

Proof of Lemma II.2. It is easy to show that $\nu_k$ increases with $k$ while $\frac{\nu_k}{\sqrt{k}}$ decreases with $k$. Therefore, the first and the last relations follow immediately.

We now prove the second inequality.

\[\nu_{k-1}(\Phi) = \max_{i \in [d]} \max_{|\Lambda| \leq k-1 \atop |\Lambda| \subseteq \Lambda \subseteq [d] \setminus \{i\}} \left( \sum_{j \in \Lambda} \langle \phi_i, \phi_j \rangle^2 \right)^{\frac{1}{2}}\]
\[= \max_{|\Lambda| \leq k} \max_{i \in \Lambda} \left( \sum_{j \in \Lambda \setminus \{i\}} \langle \phi_i, \phi_j \rangle^2 \right)^{\frac{1}{2}}\]
\[= \max_{|\Lambda| \leq k} \|\Phi_A^T \Phi_A - I\|_{\infty, 2},\]
where $\Phi_A \in \mathbb{R}^{n \times |\Lambda|}$ is a submatrix of $\Phi$ with columns indexed in $\Lambda$.

On the other hand, according to Proposition 2.5 in [13], one has
\[\delta_k = \max_{|\Lambda| \leq k} \|\Phi_A^T \Phi_A - I\|_{2, 2}\]
\[\geq \max_{|\Lambda| \leq k} \|\Phi_A^T \Phi_A - I\|_{\infty, 2}\]
\[= \nu_{k-1}(\Phi),\]
which completes the proof for the second inequality.
Next we prove the third inequality. Consider the Gram matrix $G = \Phi^T \Lambda \Phi$, where its entries $g_{ij} = \langle \phi_i, \phi_j \rangle$.

Clearly its diagonal entries $g_{ii} = 1$. Then by the Gershgorin Circle Theorem, each eigenvalue $\lambda$ of $G$ is in at least one of the disks $\{ z : |z - 1| \leq R_i \}$, where $R_i = \sum_{j \neq i} |g_{ij}|$. Equivalently, we have

\[
1 - R_i \leq \lambda \leq 1 + R_i
\]

for some $i$. Therefore,

\[
\delta_k \leq \max_i R_i = \max_i \sum_{j \neq i} |g_{ij}|
\]

\[
\leq \max_i \sqrt{k - 1} \left( \sum_{j \neq i} |g_{ij}|^2 \right)^{\frac{1}{2}}
\]

\[
\leq \sqrt{k - 1} \nu_{k-1}.
\]

**Proof of Lemma II.3** For $i \in [d] \setminus \Lambda$, we have

\[
| \langle f, \phi_i \rangle | = | \langle \Phi a + w, \phi_i \rangle |
\]

\[
\leq | \langle \Phi a, \phi_i \rangle | + | \langle w, \phi_i \rangle |
\]

\[
\leq \nu_k \| a \|_2 + \| w \|_2 \| \phi_i \|_2
\]

\[
\leq \nu_k \| a \|_2 + \epsilon.
\]

Taking maximum on both sides completes the proof of the first inequality.

Now for $i \in \Lambda$,

\[
\max_{i \in \Lambda} | \langle f, \phi_i \rangle | = \max_{i \in \Lambda} | \langle \Phi a + w, \phi_i \rangle |
\]

\[
\geq \max_{i \in \Lambda} | \langle \Phi a, \phi_i \rangle | - \max_{i \in \Lambda} | \langle w, \phi_i \rangle |
\]

\[
\geq \frac{\sqrt{1 - \delta_k}}{\sqrt{m}} \| \Phi a \|_2 - \max_{i \in \Lambda} \| w \|_2 \| \phi_i \|_2
\]

\[
\geq \frac{\sqrt{1 - \delta_k}}{\sqrt{m}} \| \Phi a \|_2 - \epsilon.
\]

This completes the proof of the second inequality.

**Proof of Theorem III.1** First, we show that WOMP recovers the correct support of $a$.

We start with the first iteration. Note that $r_0 = f$. We need to show

\[
\max_{i \in [d] \setminus \Lambda} | \langle f, \phi_i \rangle | < \rho \max_{i \in \Lambda} | \langle f, \phi_i \rangle |.
\]

By Lemma II.3 we have

\[
\max_{i \in [d] \setminus \Lambda} | \langle f, \phi_i \rangle | \leq \nu_k \| a \|_2 + \epsilon,
\]

\[
\max_{i \in \Lambda} | \langle f, \phi_i \rangle | \leq \nu_k \| a \|_2 + \epsilon,
\]

\[
\max_{i \in [d] \setminus \Lambda} | \langle f, \phi_i \rangle | < \rho \max_{i \in \Lambda} | \langle f, \phi_i \rangle |.
\]
and

\[
\max_{i \in \Lambda} |\langle f, \phi_i \rangle| \geq \frac{1 - \delta_k}{\sqrt{k}} \|\Phi a\|_2 - \epsilon \\
\geq \frac{1 - \delta_k}{\sqrt{k}} \|a\|_2 - \epsilon.
\]  

(12)

Now since \(\|a\|_2 \geq \sqrt{k}|a_{\min}|\), by imposing conditions (6) and (7), we get

\[
\nu_k \|a\|_2 + \epsilon < \rho \left( \frac{1 - \delta_k}{\sqrt{k}} \|a\|_2 - \epsilon \right),
\]

and relation (10) follows from the two bounds (11) and (12). Hence, WOMP only selects one atom from \(\{\phi_i\}_{i \in \Lambda}\) in the first iteration.

Now we argue that by repeatedly applying the above procedure, we are able to correctly recover the support of \(a\). In fact, we have for the \(s\)-th iteration

\[
r_s = f - P_{\Lambda_s}(f) \\
= \Phi a + w - (P_{\Lambda_s}(\Phi a) + P_{\Lambda_s}(w)) \\
= (I - P_{\Lambda_s})\Phi a + (I - P_{\Lambda_s})w \\
= \Phi a_s + w_s
\]

where

\[\Phi a_s = (I - P_{\Lambda_s})\Phi a\]

and

\[w_s = (I - P_{\Lambda_s})w.\]

Therefore, \(\langle \Phi a_s, \phi_i \rangle = 0\) for \(i \in \Lambda_s\). Note that \((k - s)\) components of \(a_s\) are the same as that of \(a\). Then the result follows from the inequality \(\|a_s\|_2 \geq \sqrt{k-s}|a_{\min}|\) and Lemma II.3 for \(s\)-th iteration. In addition, the orthogonal projection step guarantees that the procedure will not repeat the atoms already chosen in previous iterations. Therefore, the correct support of the noiseless representation \(a\) can be recovered exactly after \(k\) iterations.

Next, by following the idea of the proof of Theorem 5.1 in [6] and using the relation \(\sigma_{\min} \geq 1 - \delta_k\), where \(\sigma_{\min}\) denotes the smallest singular value of \(\Phi\), we are able to prove the error bound (8).

\[\blacksquare\]

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