Comparison of Short-Segment Pedicle Instrumentation with Supplemental Hook Fixation under Axial Compression in Relation to Graft Positioning and Posterior Ligamentous Integrity: A Biomechanical Study on the Calf Spine

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Study Design: Biomechanical study.
Purpose: This study investigates the benefits of supplemental hook fixation (SHF) on short-segment pedicle instrumentation (SSPI) in relation to anterior strut graft positioning. In addition, it seeks to determine whether the integrity of the posterior ligamentous complex (PLC) affects the stability of the spinal construct.

Overview of Literature: Implant and/or bone failure with progressive kyphotic deformity after SSPI is common. To prevent this, several approaches are available, including SHF, anterior strut grafting, use of longer spinal constructs, and extension of the fusion to additional adjacent segments.

Methods: A total of eight calf spines were instrumented with SSPI (n=4) and SHF (n=4) with strain gauges on the implants. Strain measurements were performed under axial compression in the following order: intact spine, corpectomy, ventral positioned strut grafting, posterior positioned strut grafting, ventral positioned grafting with resected PLC, and corpectomy with resected PLC.

Results: The SHF group showed slightly lower strain values than SSPI in instrumented corpectomy-only specimens, but there were no statistically significant differences between them (p>0.05). The SHF group was significantly more stable than SSPI when strut grafting is employed, regardless of the location of the grafts (p<0.000). In the SSPI group, ventral positioning of the graft contributed significantly to the stability (p=0.000). There was no statistically significant difference between the ventral or posterior positioning of the graft in the SHF group (p=0.187). In addition, the integrity of the PLC did not affect stability in either group (p>0.005).

Conclusions: Although not statistically significant, our investigation demonstrated that the most stable method was the SHF along with ventral positioned strut graft. However, if the SSPI is the treatment of choice, ventral positioned strut graft support will be useful in minimizing the risk of implant failure and progressive kyphotic deformity.

Keywords: Lumbar vertebrae; Spinal fractures; Biomechanics; Bone grafting; Instrumentation

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Introduction

Short-segment pedicle instrumentation (SSPI) has been widely used for the treatment of instability after thoracolumbar burst fractures and spinal tumor resections [1-3]. It usually provides excellent initial correction of kyphotic deformity, but a significant loss of correction with progressive kyphotic deformity, implant, and/or bony failure may occur afterward [1,4-8]. Several methods have been recommended to prevent failure, including supplemental hook fixation (SHF), anterior strut grafting and/or instrumentation, use of longer spinal constructs, and extension of the fusion to additional adjacent segments [1,9-16]. De Peretti et al. [12] proposed the addition of laminar hooks (2HS-1SH method) and concluded that screw and hook fixation is effective for stabilizing burst fractures of the thoracolumbar junction. A combination of SHF with SSPI preserves the bone tissue and implant by decreasing the amount of load transfer in the bone–screw interface [4,10,14].

The use of an anterior strut graft significantly increases the overall stiffness of the spinal construct while graft positioning anterior to the neutral axis of the spine provides a more optimal load sharing when posterior stability is obtained [9,17]. The posterior ligamentous complex (PLC) helps maintain stability by resisting excessive motion [18-21]. The individual contributions of PLC ligaments to stability have been previously investigated [22-24]; however, to the best of our knowledge, there is no information regarding their role in posterior spinal instrumentation and/or anterior strut graft procedures. Therefore, the current study has three main goals: first, to confirm the benefits (if any) of SHF to SSPI; second, to determine the effects of anterior strut grafting on SSPI and SHF regarding graft positioning; lastly, to determine whether the integrity of PLC impacts the stability of the spinal construct in terms of the type of instrumentation with and without the strut grafting. With the interpretation of these results, the study would be insightful for choosing the most stable method.

Materials and Methods

Eight calf spine specimens (6–9 months old) were used as the spine models. The specimens were kept at −80°C until each test was performed. Five and seven vertebral segments proximal to the sacrum were used for the SSPI/short segment (group 1) and SHF/long segment (group 2) groups, respectively. The proximal and distal vertebral segments were fixed in cylindrical molds using general purpose polyester. Sequential water cooling was done to avoid overheating of the specimens throughout the curing period of the polyester molds.

A stainless steel version of a standard type posterior spinal instrumentation system (YSS 316-L/4441Q; Hipokrat Co., Izmir, Turkey) with two crosslinks was used for the instrumentation. Six general purpose strain gauges (Type: FLA-1-11-1L; TML Tokyo Sokki Kenkyujo Co. Ltd., Tokyo, Japan) were used for each specimen. Four strain gauges were placed at the neck of the pedicle screws and two at the midline of each rod (Fig. 1). Room temperature and humidity were maintained at 22°C–24°C and 40%–60% rH, respectively, during the experiments. A 10-channel strain indicator (P-350; Vishay Instruments Co., Malvern, PA, USA) and a universal testing device (Autograph AG-50kNG; Shimadzu Co., Kyoto, Japan) were used for the tests (Fig. 1). The axial loading ratio was maintained...
between 0.5–0.05 mm/min to avoid elastic relaxation of the system. Strain measurements were performed for each specimen in the following order: (1) calibration value, (2) 400 N, (3) 500 N, and (4) 600 N of axial loading. These values were selected to simulate loading conditions of the upper body weight in the standing position. Six tests were performed for each specimen: (1) intact spine (instrumented), (2) corpectomy (instrumented), (3) corpectomy (instrumented) and ventral/anterior positioned strut graft, (4) corpectomy (instrumented) and posterior positioned strut graft, (5) corpectomy (instrumented), anterior positioned strut graft, and resected PLC, and (6) corpectomy (instrumented) and resected PLC. Ventral/anterior graft positioning was performed by placing the strut graft in the anterior column and posterior positioning was performed by placing the strut graft in the middle column (of Dennis). PLC resections were performed by resecting the supraspinous ligament, interspinous ligament, facet capsule ligament, and ligamentum flavum.

Statistical analyses were performed using the Shapiro-Wilk test for normality of data distribution (selected for small “n” number) and Mann-Whitney U-test for non-parametric comparison of groups (SPSS ver. 16.0; SPSS Inc., Chicago, IL, USA). A p-value of <0.05 was considered to be statistically significant.

**Results**

**1. General comparison of short-segment pedicle instrumentation and supplemental hook fixation groups**

Table 1 summarizes the data of the SSPI (group 1) and SHF (group 2) groups. A general comparison of these two groups demonstrated significantly lower strain values for the SHF group in test 3 (corpectomy and ventral strut graft), test 4 (corpectomy and posterior strut graft), and test 5 (corpectomy, anterior strut graft, and resected PLC) (p=0.000) (Table 1, Fig. 2). Tests 1 (intact spine), 2 (cor-
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did not differ significantly \( (p>0.05) \). Lower strain measurements indicate a more stable construct.

2. The effect of graft positioning

To determine the effect of graft positioning, we compared the measurements from ventral positioned specimens with the posterior positioned specimens in both groups (Table 2). In the SSPI group, ventral positioning of the strut graft resulted in significantly lower strain measurements \( (p=0.000) \). In the SHF group, ventral positioning showed slightly lower strain measurements, but this was not statistically significant \( (p=0.187) \) (Table 2, Fig. 3). In group 2, ventral positioning of the strut graft shows slightly lower strain ratios, but these were not statistically significant. Data expressed are strain measurements; strain is a unitless quantity: strain=dL/(L original dimension).

| Variable                      | Test 3: corpectomy and ventral strut graft | Test 4: corpectomy and posterior strut graft | p-value* |
|-------------------------------|------------------------------------------|---------------------------------------------|----------|
|                               | Mean±SD | Median | Min–max | Mean±SD | Median | Min–max |          |
| Group 1: short-segment pedicle instrumentation | 10.3969±7.6930 | 10.3706 | 0.76–24.32 | 37.9126±10.4894 | 34.5186 | 26.25–58.77 | 0.000\* |
| Group 2: supplemental hook fixation | 2.3408±2.3836 | 0.9239 | 0.28–6.83 | 3.1711±3.4832 | 1.0694 | 0.59–10.42 | 0.187    |

In group 2, ventral positioning of the strut graft shows slightly lower strain ratios, but these were not statistically significant. Data expressed are strain measurements; strain is a unitless quantity: strain=dL/(L original dimension). SD, standard deviation.

*By Mann-Whitney test. \*In group 1, ventral positioning resulted in significantly lower strain measurement.

3 with test 5 in both groups (Tables 3, 4). None of the comparisons demonstrated a statistically significant difference \( (p>0.05) \).

Discussion

This study investigated the contribution of long-segment instrumentation with the supplemental hook method to SSPI application, the influence of anterior strut graft to SSPI and supplemental hook instrumentation, the importance of strut graft location, and the role of posterior ligamentous structures in these applications. Significantly increased strain values (decreased stability) were recorded in the corpectomy specimens than in the intact spine. However, in the corpectomy-only specimens (instrumented), when the SSPI and SHF groups were compared, the supplemental hook group showed lower strain values without a statistically significant difference between them \( (p>0.05) \) (Table 1). Our results demonstrated that SHF method was significantly more stable than SSPI application when anterior strut grafting is employed, regardless of the location of the strut grafts \( (p=0.000) \) (Table 1). In SSPI applications, ventral positioning of the strut graft significantly influences the stability \( (p=0.000) \) (Table 2). In supplemental hook applications, there was no significant difference between ventral or posterior positioning of the strut graft due to better stability \( (p=0.187) \) (Table 2). Independent of the type of instrumentation, the posterior ligamentous structures did not contribute to stability \( (p=0.005) \) (Tables 3, 4).

Unacceptable failure rates of short segment fixation with progressive kyphotic deformity have been previously reported [4,6,7,25]. Other studies have reported that supplemental hook applications significantly contribute to stability and help reduce the failure rates [1,5,13,14,16]. De Peretti et al. [11] evaluated the “2-hook screw–1-screw
hook” instrumentation by regional and mean kyphosis angle measurements and emphasized the benefits of SHF. Argenson et al. [13,14,16] reported similar results in his clinical trials and stressed the efficiency of screw–hook fixation. Chiba et al. [1] reported that SHF decreases the bending moments of pedicle screws by 50% in flexion and extension. Leduc et al. [5], in on a series of studies based on 25 patients, reported that the 2HS-1SH construct provided significant correction and minimized the risk of failure. In our study, when we compared the data of the SSPI and supplemental hook groups in corpectomy-applied spines, we found lower strain value readings in the supplemental hook group that indicate a more stable fixation; although, these results were not statistically significant (p=0.166) (Table 1). The comparisons made after strut graft application demonstrated that supplemental hook application provided a significantly more stable fixation (p=0.000) (Table 1). Ventral positioning of the strut graft in the supplemental hook-applied specimens led to lower strain readings than posterior positioning, but the difference was not statistically significant (p=0.187) (Table 2). Thus, our data are consistent with that of previous clinical and biomechanical studies.

According to Benzel [17], the location of the strut graft significantly affects the biomechanical efficacy of the construct. Ventral placement of the graft is biomechanically prudent while positioning the graft dorsally (in the middle column of Denis) provides good axial load-bearing, but a suboptimal ability to prevent kyphosis [17]. Benzel [17] also noted that if the dorsal stability can be achieved, placing the strut graft in a slightly more ventral location may be optimal for better load distribution between the graft and dorsal elements. Polly et al. [26] investigated the biomechanical effects of interbody cages and variations in posterior rod diameter in a simulated single-level spinal fusion. They reported that the presence of interbody cages and their sagittal positioning significantly influences overall construct stiffness and leads to an increased strain on the cage with more anterior positions. They were also inversely related to rod strain. In our study, although there was no statistically significant difference between ventral and posterior positioning of the graft in SHF group (p=0.187), ventral positioning of the graft in the SSPI group showed significantly lower strain measurements than the posterior placement of the graft (p=0.000) (Table 2). These results are consistent with those reported by Polly et al. [26].

The role of the posterior ligamentous structures to stability is well-known. Several studies have examined the contribution of each individual ligament. Gillespie and Dickey [20] reported that the supraspinous/interspinous ligament complex was the largest contributor to resist the flexion motion (35.9%) followed by the intervertebral disc (25.2%) and the ligamentum flavum (24.7%). Alapan et al. [23], using a finite element model, found that multiple ligament injuries resulted in a change of the instantaneous center of rotation in all planes as well as load transfer and sharing characteristics of the segment. Li et al. [22], using a cadaveric model, showed that the rupture of the supraspinous ligament or ligamentum flavum resulted in a significant decrease in segmental stability than in the intact and fracture models, particularly in flexion-extension motion. We investigated the role of the posterior ligamentous structures in short segment and supplemental hook instrumentation models. It appears that no study has previously investigated the role of posterior ligaments in posterior instrumentation. Regardless of the instrumentation type, we found no significant differences between the intact and injured groups (p>0.05) (Tables 3, 4).

There are some limitations associated with this study. First, due to its availability, we chose to use the calf spine model. Although most biomechanical spine models cannot simulate all biomechanical properties of the human spine, Wilke et al. [27,28] suggested that the calf spine

### Table 3. Comparison of test 2 and test 6 to determine the effect of PLC according to groups

| Variable                      | Test 2: corpectomy | Test 6: corpectomy and resected PLC | p-value*
|-------------------------------|--------------------|------------------------------------|-------------
|                               | Mean±SD            | Median                            | Min–max     | Mean±SD            | Median                            | Min–max     | p-value*
| Group 1: short-segment pedicle instrumentation | 28.79±5.265        | 24.9554                            | 2.08–79.47  | 20.72±13.8854      | 21.0010                            | 2.29–44.99  | 0.575
| Group 2: supplemental hook fixation | 15.13±14.9398      | 6.4657                            | 2.27–43.36  | 12.57±14.2062      | 3.4935                            | 1.71–40.02  | 0.113

Resection of PLC did not result in significant difference in either groups. Data expressed are strain measurements; strain is a unitless quantity: strain=ΔL/(original dimension).

PLC, posterior ligamentous complex; SD, standard deviation.

*p=0.000, **p=0.001, ***p=0.005.
can be considered on a limited basis as a model for the human spine in certain in vitro tests. Second, we used only axial loading tests. The axial loading pattern applies a compressive flexural load on the specimen. As with many other spine surgery clinics, we routinely use a custom-fitted thoraco-lumbo-sacral orthosis (TLSO), which restricts flexion/extension, lateral bending, and rotational movements effectively at least 3 months postoperatively. Considering the use of a TLSO, we only included axial loading patterns in the study. However, flexion/extension, lateral bending, and rotational as well as fatigue tests are critical for determining all physiologic loading conditions. Furthermore, the third limitation of the study is that the in vivo conditions differ from the in vitro environment, due to the absence of soft tissues such as muscles.

In conclusion, our investigation showed that under axial loading conditions, the most stable method was the SHF in combination with anterior positioned strut graft; however, anterior or posterior positioning did not differ significantly in the supplemental hook group. However, if the short segment fixation is the treatment of choice, ventral positioned strut graft support will be useful in minimizing the risk of implant failure and progressive kyphotic deformity.

No potential conflict of interest relevant to this article was reported.

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Conception and design: SKM, HB; data collection and assembly of data: SKM; administrative support: HB; data analysis and interpretation: SKM; manuscript drafting: SKM, HB; and critical revision of manuscript and supervision: SKM, HB.

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