Gravity of two photon decay and its quantum coherence

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Abstract

A linear analytical solution is derived for the gravitational shock wave produced by a particle of mass $M$ that decays into a pair of null particles. The resulting space-time is shown to be unperturbed and isotropic, except for a discontinuous perturbation on a spherical null shell. Formulae are derived for the perturbation as a function of polar angle, as measured by an observer at the origin observing clocks on a sphere at distance $R$. The effect of the shock is interpreted physically as an instantaneous displacement in time and velocity when the shock passes the clocks. The time displacement is shown to be anisotropic, dominated by a quadrupole harmonic aligned with the particle-decay axis, with a magnitude $\delta \tau \sim GM/c^3$, independent of $R$. The velocity displacement is isotropic. The solution is used to derive the gravitational effect of a quantum state with a superposition of a large number of randomly oriented, statistically isotropic particle decays. This approach is shown to provide a well-controlled approximation to estimate the magnitude of gravitational fluctuations in systems composed of null point particles up to the Planck energy in a causal diamond of duration $\tau = 2R/c$, as well as quantum-gravitational fluctuations of black holes and cosmological horizons. Coherent large-angle quantum distortions of macroscopic geometry from fluctuations up to the Planck scale are shown to grow linearly with the duration, with a variance $\langle \delta \tau^2 \rangle \sim \tau P$ much larger than that produced in models without causal quantum coherence.

Keywords: quantum coherence, linearized gravity, general relativity, gravitational shock

(Some figures may appear in colour only in the online journal)
1. Introduction

One of the simplest exact solutions of Einstein’s equations is the planar gravitational shock wave produced by a point particle on a null trajectory [1, 2]. This idealized system has been applied to study the ‘memory effect’ at null infinity [3, 4], and extrapolated to quantum systems, including the back-reaction of particle emission on the horizon of a black hole [5–7].

Here, we analyze the solution for the spherical gravitational shock wave produced by a pair of oppositely-propagating point null particles originating from a single point mass at rest in a nearly-flat space-time background. We evaluate the effect of the shock on a sphere at a finite distance \( R \), and the observable distortion of space-time geometry on that sphere as function of direction and time, as observed at the origin.

In this system, the memory effect takes the form of an anisotropic distortion of time. The distortions can be characterized by a local measurement with a simple operational definition. Before the particle decays, a sphere of clocks is synchronized by an outgoing spherical pulse from the origin. After the particle decays, the gravity of the shock distorts the measured time on clocks in all directions, compared synchronously on the world line of an inertial observer at the origin.

We choose to study this system in particular because it is well suited to study the relationship of space-time with causally-coherent quantum states of gravitating mass-energy. Unlike the planar shock solution, all of the elements of the system are contained in a compact causal diamond of space-time. In this set-up, an entire quantum system, including preparation and measurement of a state and a measurement apparatus, can be incorporated into a gravitational solution: both the preparation of the state and the measurement of the gravitational perturbation response are localized on a single world line, in an interval of finite duration. In other words, the solution describes a locally-measurable timelike response to a nonlocal spacelike gravitational effect.

This solution is applied below to estimate the effect of causally-coherent quantum nonlocality on gravitational fluctuations. Our estimate of the gravitational fluctuations is based on the correspondence principle, the hypothesis that the quantum state of a whole system can be expressed as a superposition of consistent classical histories of matter and space-time. The main conclusions are thus insensitive to the unknown detailed structure of nonlocal quantum states in curved space-time [8, 9], as long as they are causally coherent.

Previous model systems do not have the causal structure required for this exercise. The initial conditions for the source in the classical planar shock solution [1, 2], a null point particle, cannot be set up causally in a quantum system: a definite direction for the particle momentum requires that its quantum state be delocalized everywhere on planes normal to the direction of travel. Similarly, the standard approach to nonlocality adopted in effective field theory, widely used to study gravitational fluctuations in cosmic inflation [10, 11], quantizes coherent, infinite plane wave modes, not superpositions of directional particle states confined to causal diamonds.

The angular structure of the spherical null gravitational shock displays a large-angle coherence that is not captured by such models based on nonlocal planar symmetry. The spherical null shock relates a causal, nonlocal effect of gravity to localized pointlike events. The anisotropic, coherent angular gravitational effects in relation to a point are confined to a null surface, and also extend to macroscopic separation. The solution is consistent with general relativity and quantum mechanics for particles up to the Planck mass, so it is a suitable approximation to estimate large-angle correlations of causally-coherent quantum gravity and its fluctuations in macroscopic systems.
Figure 1. Gravitational effect of a particle pair on observed time perturbations. At left, a point mass on world line $A$ decays at $t_0$ into oppositely directed null particles. A time $R/c$ later, the gravitational shockwave of the particles creates a coherent perturbation on the spherical boundary of a causal diamond of radius $R$, as shown at the right. Clocks on the surface are synchronized by an outwards pulse from $A$ just before $t_0$, and observed by $A$ by return light from the surface of the causal diamond after $t_0 + 2R/c$. The shock creates coherent time displacements with an even-parity directional variation of amplitude $\delta \tau \sim GM/c^3$ aligned with the particle trajectory, as shown by comparing on-axis clocks at $B$ and $C$ with those in equatorial directions.

The classical single-particle decay solution is used here to estimate coherent non-localized quantum-gravitational effects of quantum superpositions of matter states. We apply the classical solution to two quantum systems, an $S$-wave decay with an isotropic directional wave function, and the sequential isotropic decay of many such particles originating on the same world line. These solutions allow us to derive the large-angle correlations of the quantum-gravitational response to a many-particle state.

Assuming that relativity and quantum mechanics are valid and obey the correspondence principle, a superposition of these solutions approximately describes the coherent state of a quantum geometry, up to the point where the total mass of particles approaches that of a black hole for the duration defined by the measurement. The extrapolation to many particles provides a controlled estimate of macroscopic quantum fluctuations of causally-coherent, weak-field gravity for systems of any size. The estimate here shows a variance of large-angle, macroscopic distortions on the surface of a causal diamond that grows linearly with its duration, which agrees with recent estimates based on conformal descriptions of near-horizon vacuum states [12], but is much larger than estimates from field theory [10, 11] that do not include the same causal coherence. This difference is in principle measurable, and might have observable consequences.

2. Setup and general properties of the solution

Consider the system shown in figure 1. A particle of mass $M$ at the origin is surrounded by a set of clocks distributed on a sphere of radius $R$. The clocks are synchronized by a pulse from the origin prior to $t_0$. The clocks are on freely falling timelike geodesics.
At a time $t_0$, the particle decays into a pair of equal-momentum null point particles that propagate in opposite directions along the $z$ axis. The particles create an outgoing spherical gravitational shock wave that creates a direction-dependent discontinuity in timelike geodesics as it passes. Outside the shock wave, the solution is a Schwarzschild space-time of mass $M$; inside, the solution is a flat space-time.

When the shock passes through $R$, the sphere of clocks is perturbed. The shock creates an instantaneous displacement of position and velocity that depends on the angle from the particle axis. The bulk of the total displacement measured as a difference between clocks occurs on large angular scales, that is, in low spherical harmonics, dominated by a quadrupole or tidal term. The physical effect of the shock wave can be visualized as a coherent, anisotropic, discontinuous displacement of time on the order of $\delta \tau \sim GM/c^3$, together with an isotropic redshift discontinuity $\delta \tau/\tau \sim GM/Rc^2$ that represents the disappearance of gravitational redshift in the post-shock solution.

3. Spacetime geometry

3.1. Metric perturbation

Consider a particle with mass $M$ sitting at rest at position $z = t_0$ of global inertial coordinates $(t, x, y, z)$. At time $t = t_0$, the particle decays into two massless particles with energy $E = M/2$ that propagate in opposite directions along the $z$ axis. We assume that $M$ is small so that we may use the weak field approximation to determine the spacetime geometry. We will look for the solution to the linearized Einstein equations by considering a metric perturbation $h_{ab}$ such that $g_{ab} = \eta_{ab} + h_{ab}$. Choosing the Lorenz gauge $\nabla^a h_{ab} = 0$, we get a sourced wave equation for the metric perturbation

$$\nabla^c \nabla_c h_{ab} = \frac{16\pi G}{c^4} T_{ab},$$

(1)

where $\bar{h}_{ab}$ is the trace reversed metric perturbation

$$\bar{h}_{ab} = h_{ab} - \frac{1}{2} \eta_{ab} h$$

(2)

such that $h = \eta^{ab} h_{ab} = -\bar{h}$. (Going forward, we will drop the $G/c^4$ until units are needed). The spacetime diagram for this event is given by figure 2.
The stress–energy tensor for the system described is

\[ T_{\mu\nu} = M\delta(x)\delta(y) \left[ \delta(\zeta)H(-t)\delta^\mu_0 + \frac{1}{2} (\delta(\zeta + t)\delta_0^\mu + \delta(\zeta - t)k^\mu k^\nu)H(t) \right], \]

(3)

where \( k^\mu = t^\mu + z^\mu, P^\mu = t^\mu - z^\mu, \) and \( H(t) \) is a Heaviside step function (for simplicity we have set \( t_0 = 0 \)). For \( t < 0 \), this is the usual stress–energy for a point particle (at rest) given by

\[ T_{\mu\nu} = \gamma m v^\mu v^\nu \delta^{(3)}(x - x(\tau)). \]

For \( t > 0 \), this is the generalization of the previous formula to the massless limit, taking \( \gamma m \to E \).

We can solve this wave equation term by term by letting \( \bar{h}_{ab} = f_1(x')u_aib, \bar{h}^I_{ab} = f_1(x')u_aib, \bar{h}^{II}_{ab} = f_1(x')k_aib. \) We then have three sourced scalar wave equations with sources \( S_i \) which contain the information of the stress–energy tensor.

\[ \Box f_i = -4\pi S_i. \]

(4)

The retarded Green’s function for the \( \Box \) operator is

\[ G_R(t, \vec{x}, t', \vec{x}') = \frac{1}{2\pi} \delta((t - t')^2 + (\vec{x} - \vec{x}')^2)H(t - t'). \]

(5)

The solutions to equation (4) are given by

\[ f_i(x) = 4\pi \int d^4x' G(t, \vec{x}, t', \vec{x}')S_i(t', \vec{x}'). \]

(6)

The complete metric perturbation is then given by [3]

\[ h_{ab} = \frac{2M}{r} (\gamma_{ab} + 2t_aibH(-U) + \frac{2M}{t+z} l_aibH(U) + \frac{2M}{t-z} k_aibH(U)), \]

(7)

where \( U = t - r \) and \( r = (x^2 + y^2 + z^2)^{1/2} \). The step function behavior indicates that the spacetime will be that of a spherically propagating shock wave. Although at first glance it appears as though the spacetime inside the shock wave \( (U > 0) \) is not flat, one can make an appropriate coordinate transformation to show that the metric is indeed that of a flat spacetime. We have in null coordinates \( u = t - z, v = t + z \)

\[ ds^2(U > 0) = -du dv + \frac{2M}{u} du^2 + \frac{2M}{v} dv^2. \]

(8)

We now define new null coordinates as in [2]

\[ d\tilde{u} = dv - \frac{2M}{u} du \quad d\tilde{u} = du - \frac{2M}{v} dv. \]

(9)

Since we are in the linearized regime, we drop terms \( O(M^2) \). The spacetime metric in the new null coordinates becomes

\[ ds^2(U > 0) = -d\tilde{u} d\tilde{v}. \]

(10)

Aside from the discontinuity at \( u = 0, v = 0 \) in the new null coordinates \( \tilde{u}, \tilde{v}, \) we see that the spacetime is flat to the causal future of the decay event (henceforth referred to as ‘inside’ the shock wave). In the next section we will again demonstrate this by showing that the Riemann tensor vanishes inside the shock wave.
Figure 3. Two oppositely-propagating massless particles (blue) creating a spherically symmetric gravitational shock wave (red). The clocks sitting at radius $R$ experience an instantaneous displacement (not shown) and velocity kick $\Delta V$ as a function of angle $\theta$.

We briefly mention here that equation (7) agrees with the metric perturbation derived in [13] after carefully taking the limit $L \to 0$, $\epsilon \to M/2$, where $L$ corresponds to the width of the laser pulse considered in their work, and $\epsilon$ is the energy of each pulse. Note that while the metric perturbation can be made continuous in their system, the limit $L \to 0$ makes the metric perturbation have a discontinuous jump at $U = t - r = 0$ (figure 3).

3.2. Geodesic deviation

We now determine the relative motion of test bodies in this spacetime (note that in all calculations we raise and lower indices with $\eta_{ab}$). Consider a congruence of timelike geodesics that are initially ‘at rest’, with spatial deviation vector $D^a$. Define the tangent to the world line of a test clock by $T^a$. Initially, we have $T_0^a = t^a = (1, 0, 0, 0)$. The deviation evolves according to [14]

$$T^a \nabla_e (T^f \nabla_j D^b) = -R_{bcef} T^b T^d D^f.$$  \hspace{1cm} (11)

Since the clocks will be allowed to free-fall after the system is set up, the tangents to the world lines will pick up $O(M/r)$ corrections between the time of release and the time of the shock wave passing by. However, we can ignore this correction to the velocity when computing displacement/velocity kicks so long as the free-fall time is not too long since we only care about the leading order effect and the Riemann tensor is at least $O(M/r)$. The linearized Riemann tensor is given in terms of the metric perturbation by

$$R_{abcd} = 2 \nabla_{\{a} \nabla_{\mid b\mid} \mid d\mid c\}. \hspace{1cm} (12)$$

There will be three types of terms in the Riemann tensor components. One type will be proportional to a step function, which gives the usual gravitational tidal force. The second type will be proportional to a $\delta$ function, which results in a relative velocity kick. The third type will be proportional to the derivative of a $\delta$ function, which results in a relative displacement kick: this is the memory effect. We can write the displacement vector as

$$D^a = D_0^a + D_1^a + D_2^a + D_3^a,$$ \hspace{1cm} (13)

where the $(n)$ refers to the $1/r^n$ piece. We consider changes to $D^a$ to linear order in $M$ only. In what follows, we use the following convention for coordinate vectors: $\nabla^a z = z^a$, $\nabla^a t = -t^a \Rightarrow \nabla^a u = -k^a$, $\nabla^a v = -l^a$. 

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The curvature components proportional to a derivative of a $\delta$ function come from both derivatives acting on the step function.

$$\nabla_a H(U) = \delta(U) \nabla_a U$$  \hfill (14)

$$\nabla_a \nabla_a H(U) = \delta'(U) \nabla_a \nabla_a U + \delta(U) \nabla_a \nabla_a U.$$  \hfill (15)

Note that since we will ultimately be antisymmetrizing on pairs of indices, we can treat the covariant derivatives as coordinate derivatives in computing the Riemann tensor components. We focus attention on the first term for now. $\nabla_a U = -(t_a + r_a) = -K_a$. Note that at $t = r$, we have $u = r - z = r(1 - \cos \theta), v = r + z = r(1 + \cos \theta)$. Plugging into equation (12) gives

$$R_{abcd}^\delta = -\frac{4M}{r}(K_{[a}b[|i|,K_{d]}] + 2K_{[a}b[i|,K_{d}]}\delta'(t - r)$$

$$+ \frac{4M}{r}\left(\frac{1}{1 - \cos \theta}K_{[a}b|b|,K_{d]} + \frac{1}{1 + \cos \theta}K_{[a}b[j|,K_{d}]}\right)\delta'(t - r).$$  \hfill (16)

If we consider the components of $D^l$ in a parallelly propagated orthonormal frame, the left-hand side of equation (11) reads $d^2D^l/dr^2$. Integrating the geodesic deviation equation twice gives

$$(\Delta D_{(l)})_a = \frac{M}{r}(\theta_a \phi_b - \phi_a \theta_b)D^l_{(0)},$$  \hfill (17)

where $\theta_a, \phi_a$ are the unit tangent vectors on the sphere. Thus, there is an instantaneous relative displacement kick between two nearby stationary test bodies.

As shown in the appendix, we can decompose this tensor into a tensor harmonic mode sum. Specifically, the displacement kick can be decomposed into a sum over transverse ‘electric’ tensor harmonics. The coefficients of the mode sum are given by equation (67):

$$\Delta D = -\frac{M}{r}(\hat{\phi} \theta - \hat{\theta} \phi) \cdot D_{(0)} \sum_{l=2,\text{even}}^\infty \frac{2l + 1}{l(l - 1)(l + 1)(l + 2)}$$

$$\times \left(2 \cot \theta \frac{d}{d\theta} + l(l + 1)\right) P_l(\cos \theta),$$  \hfill (18)

where $\hat{\phi}, \hat{\theta}$ are angular unit vectors on the sphere. The quadrupolar mode ($l = 2$) gives

$$\Delta D_{l=2} = \frac{5M}{8r} \sin^2 \theta (\hat{\theta} \hat{\theta} \theta \phi - \phi \hat{\phi} \theta \phi) \cdot D_{(0)}.$$  \hfill (19)

We note here that one could attempt to ‘glue’ the two spacetime regions (Minkowski and Schwarzschild) together using the formalism developed by Israel and Barrabes [15]. The results of their work indicate that the Riemann tensor is at most $\delta$ function singular on the null boundary when the induced metric on the null hypersurface joining the two spacetimes can be made continuous. However, as shown in [4], there must be a change in the leading order metric (which is associated with memory) for the type of stress–energy considered here. Therefore, the metric cannot be made continuous here and there will be a $\delta'$ type singular behavior on the null hypersurface.

The curvature components proportional to a $\delta$ function come from the second term in equation (15) and the cross term when acting two derivatives on $h_{[ab]}^l$ in equation (7). Again, derivatives acting on $1/u, 1/v$ will not contribute since they are proportional to $k^a, l^a$ respectively. In addition to the terms mentioned above, there will be a term proportional to $\delta(t - r)$
that comes from integration by parts of the terms proportional to $\delta'(t-r)$ when integrating the geodesic deviation equation:

$$R_{abcd}^3 = \frac{4M}{r^2}(\theta_{[a}(\eta_{b]c} + 2l_{b]l[c}\theta_{d]} + \phi_{[a}(\eta_{b]c} + 2l_{b]l[c}\phi_{d]})$$

- \frac{4M}{r^2}(K_{[a}(\eta_{b]c} + 2l_{b]l[c}r_{d]} + r_{[a}(\eta_{b]c} + 2l_{b]l[c}K_{d]}))

- \frac{4M}{r^2(1-\cos \theta)}(\theta_{[a}k_{b]}k_{c}\theta_{d]} + \phi_{[a}k_{b]}k_{c}\phi_{d]})

- \frac{4M}{r^2(1+\cos \theta)}(\theta_{[a}l_{b]}l_{c}\theta_{d]} + \phi_{[a}l_{b]}l_{c}\phi_{d]})

+ \frac{4M}{r^2(1-\cos \theta)^2}K_{[a}k_{b]l_{c}]K_{d]} + \frac{4M}{r^2(1+\cos \theta)^2}K_{[a}l_{b]l_{c}]K_{d]}.

Again, keeping only the leading order behavior in $1/r$ and integrating the geodesic deviation equation once then gives

$$\Delta v_a^{(2)} = M r^2 \left[ r_a r_b + (\theta_a \theta_b - \phi_a \phi_b) \frac{1 + \cos^2 \theta}{1 - \cos^2 \theta} + \frac{2 \sin \theta \cos \theta}{1 - \cos^2 \theta} (r_a \theta_b + r_b \theta_a) \right] D_{(0)}^b. \quad (21)$$

Thus, there is an instantaneous relative velocity kick between two nearby stationary test bodies as measured in a parallelly propagated frame.

The curvature components proportional to a step function come from both derivatives hitting the pre-factors in equation (7). Only the first piece of $h_{ab}$ will contribute since $\nabla^a u = -k^a$, etc, and the antisymmetrization will kill these terms. The Riemann tensor associated with tidal forces is

$$R_{abcd}^{\text{tid}} = \frac{4M}{r^3}(\eta_{a[d] + 2l_{a[l]}d]}(\delta_{b]k_c - 3r_{b]}r_{c])H(-(t-r)). \quad (22)$$

Finally, equation (11) gives

$$\frac{d^2 D_{a}^{(3)}}{dt^2} = M r^3 (2r_a r_b - \theta_a \theta_b - \phi_a \phi_b) D_{(0)}^b H(-(t-r)). \quad (23)$$

This is the usual form of tidal forces in Newtonian gravity. Note that this term ‘turns off’ after the shock has passed a given test body.

4. Time displacement

Consider a system of synchronized clocks distributed on a sphere of radius $r$. After the passage of the gravitational shock wave, the clocks will no longer be synchronized due to the relative displacement kick. The desynchronization of clocks on the sphere can be determined via supertranslations at future null infinity, or $\mathcal{I}^+$ [16]. These are asymptotic symmetries (part of the BMS group) of asymptotically flat spacetimes [17, 18]. The generator of these symmetries is given by

$$\psi^a = T(x^A) \left( \frac{\partial}{\partial u} \right)^a - T(x^A) \left( \frac{\partial}{\partial r} \right)^a - \frac{1}{r} D^c T(x^A) \left( \frac{\partial}{\partial x^c} \right)^a + \cdots \quad (24)$$
which creates an infinitesimal shift in the retarded time
\[ u \rightarrow u - T(\theta, \phi). \] (25)

Here \( x^A \) are the position coordinates on the two-sphere. In four spacetime dimensions, it has been shown that (null) memory is purely of scalar type, and can be written in terms of these supertranslations [4]. The relation is given by
\[ \Delta_{AB} = \frac{1}{r} \left( \mathcal{D}_A \mathcal{D}_B - \frac{1}{2} q_{AB} \mathcal{D}^2 \right) T(\theta, \phi), \] (26)
where \( \mathcal{D}_A \) is the covariant angular derivative operator on the sphere [19].

From equation (18) we have
\[ \Delta_{\theta\theta} = \frac{2M}{r} \sum_{l=2,\text{even}}^{\infty} \frac{2l+1}{l(l+1)(l+2)} \left( \frac{d^2}{d\theta^2} + \frac{l(l+1)}{2(l+2)} \right) P_l(\cos \theta). \] (27)

From this one can easily read off the \( l > 1 \) contributions to \( T(\theta, \phi) \):
\[ T(\theta, \phi) = T_{0,1} + 2M \sum_{l=2,\text{even}}^{\infty} \frac{2l+1}{l(l+1)(l+2)} P_l(\cos \theta). \] (28)

The \( l = 0, 1 \) contributions are due to standard temporal and radial spatial translations. By setting up our system of clocks on the sphere to be initially synchronized, these two terms vanish.

Equation (28) is the main result of this paper, the angular pattern of time displacement recorded on the surface of the causal diamond. Since the weighting falls off as \( \sim 1/l^3 \), the \( l = 2 \) mode will be the dominant contribution. It has an angular dependence
\[ T_2(\theta) = \frac{5M}{24} (3 \cos^2 \theta - 1). \] (29)

5. Velocity kick

Previously, we considered the relative velocity induced between nearby observers in a parallelly propagated frame. However, we would also like to know the (global) radial velocity (away from the origin) of each clock on the sphere, as this will produce a longitudinal Doppler shift as measured by the observer at the origin. We can determine the induced velocity \( \mathcal{V}^r \) of each clock by solving the geodesic equation.
\[ \frac{d\mathcal{V}^r}{dt} + \Gamma^r_{tt} \mathcal{V}^t \mathcal{V}^x = 0, \] (30)
where we have chosen to parameterize the wordlines by the coordinate time \( t \). The tangent vector to the wordline of the clocks is initially given by that of a stationary observer, i.e. \( \mathcal{V}_0^r = \ell^r \). Since the leading order corrections to \( \ell^r \) are \( \mathcal{O}(M/r) \) and the linearized Christoffel symbols are also \( \mathcal{O}(M/r) \), we can use \( \mathcal{V}_0^r \) in equation (30). Therefore in our linearized regime we have
\[ \frac{d\mathcal{V}^r}{dt} \approx -\Gamma^r_{tt}, \] (31)
\[
\Gamma^\mu_\nu = \frac{1}{2}(2\partial_{h\mu} - \partial_{h\nu}h). \tag{32}
\]

We want to determine the instantaneous (globally measured) velocity kick, which comes from the Christoffel symbols proportional to delta functions. In Cartesian coordinates, we have
\[
\gamma^\mu = \gamma^\mu_0 + \frac{M}{x^2 + y^2} \left( \frac{r^2 + z^2}{r^2}, -x \frac{r^2 + z^2}{r^2}, -y \frac{r^2 + z^2}{r^2}, \frac{3r^2 - z^2}{r^2} \right). \tag{33}
\]

At this point we must discuss a subtle point about what the observer at the origin is measuring. As mentioned in section 3.1, the original coordinate chart \((t, x, y, z)\) is not well suited to describe the flat spacetime that the observer at the origin is making measurements in. We want to know how fast a given clock is moving away from the origin as measured in time \(\tilde{t}\).

We need to make the appropriate coordinate transformation to the coordinates \((\tilde{t}, \tilde{x}, \tilde{y}, \tilde{z})\) and re-parameterize the wordline of the clocks.
\[
\tilde{\gamma}^\mu = \frac{d\tilde{t}}{dt} \frac{\partial \tilde{x}^a}{\partial x^b} \gamma^b. \tag{34}
\]

Using equation (9) we find that
\[
\frac{\partial \tilde{x}^a}{\partial x^b} = \delta^a_b + \left( \frac{M}{u} + \frac{M}{v} \right) (x^a z_b - t^a t_b) + \left( \frac{M}{v} - \frac{M}{u} \right) (t^a z_b - x^a t_b). \tag{35}
\]

\[
\frac{d\tilde{t}}{dt} = \gamma^\mu \nabla_\mu \tilde{t} = \gamma^\mu \left( \eta_a \left( -1 + \frac{M}{u} + \frac{M}{v} \right) + z_a \left( \frac{M}{u} - \frac{M}{v} \right) \right). \tag{36}
\]

In what follows, we expand everything out to \(O(M/r)\). In the new coordinates \((\tilde{t}, \tilde{x}, \tilde{y}, \tilde{z})\) we have
\[
\tilde{\gamma}^\mu = \left( 1, \frac{1 + \cos^2 \theta}{r} \sin \theta \cos \phi, -\frac{1 + \cos^2 \theta}{r} \sin \theta \sin \phi, \frac{M}{r} \cos \theta \right). \tag{37}
\]

We note here that although we should have transformed \((r, \theta)\) into \((\tilde{r}, \tilde{\theta})\), the difference between these coordinates is \(O(M/r)\), so it is sufficient to use the original spherical polar coordinates to leading order (this is explained in more detail in the next section). As can be seen by equation (37), there is an inward relative velocity transverse to the \(\phi\) direction, with an outward velocity in the \(z\) direction. This distorts the sphere into an ellipsoidal shape. If one does a Taylor expansion about a particular point, they will recover the relative velocity kick between nearby observers derived in equation (21).

Projecting the velocity kick into the radial and transverse directions, we get
\[
\Delta V^r = -\frac{M}{r} \tag{38}
\]
\[
\Delta V^\theta = -\frac{2M}{r} \cot \theta. \tag{39}
\]

We find that the radial velocity kick is isotropic, while the transverse velocity kick is not isotropic and is badly divergent near the polar axes, which we discuss how to handle in the next section. This isotropic radial velocity kick can be decomposed into two parts, as demonstrated in [13]: an outward impulse purely due to the loss of mass in the spacetime, and an
inward impulse due to the propagating photon, whose gravity always points inwards and transverse to the $z$ axis (i.e. in the $-\hat{\rho}$ direction). The net radial impulse is toward the origin, and since it is independent of polar angle, only the angular velocity kick ‘knows’ about the location of the counter-propagating null particles—one can show that the relative kick in this direction given by the 2nd term in equation (21) agrees with the result of [11] in the appropriate limit. Although the angular component is divergent at the poles, one can expand for small $\cos \theta$ (i.e. near the equator) to get an approximate solution. We comment here that the full solution to the non-linear Einstein equations (with smoothed source) should be regular at the poles and should match on to this expansion around the equator in the weak field limit.

The effect of the radial velocity kick is to produce a Doppler shift in the clocks relative to the central observer. All the clocks appear to run faster after the shock has passed; this can be interpreted as an inward velocity kick from the shock, which is indistinguishable from the disappearance of the isotropic gravitational redshift relative to the central observer that was present in the pre-shock system. The longitudinal Doppler shift is first order in the (radial) velocity, but the profile is spherically symmetric and thus the observer gains no information about which way the two particles went. If one considers many such decays originating from the same point, there will be no fluctuations in this measurement. The transverse Doppler shift at leading order is second order in the (angular) velocity kick, so this will be a sub-leading effect (recall that $M/r \ll 1$ to satisfy the linearized regime).

We conclude that the anisotropic effects at leading order in $M/r$ are due to the time shift induced by the relative displacement kicks of the clocks, which give rise to measurable angular fluctuations.

6. Limits of validity

This solution is not exact. The linear approximation to gravity breaks down at large $M$, and because of quantum uncertainty, the point-particle approximation breaks down at small $M$. (We will continue to assume that the clocks are represented classically, as point-like tracers of local proper time; this does not affect our conclusions in the regime of interest.)

For a single particle decay, the linear approximation breaks down close to the axis. It leads to unphysical effects if the impact parameter is less than the Schwarzschild radius for mass $M$: the scattering angle becomes large, and the orbits of clocks carry them across the singularity on the axis. Putting back the units, from equation (7) we see that the linear approximation is valid only for

$$\frac{2GM}{c^2(t \pm z)} \ll 1$$

and at angles from the axis greater than

$$\theta^2 \gtrsim \frac{4GM}{Rc^2}.$$  

Thus, for any $M$ there is also a lower bound on $R$ (see figure 4).

Upon making the coordinate transformation given by equation (9), angles on the sphere will become distorted, i.e. $\tilde{\theta} \neq \theta$. However, one can show that the leading order difference satisfies

$$\cos \tilde{\theta} - \cos \theta \sim \frac{GM}{Rc^2} \ln \left( \frac{1 + \cos \theta}{1 - \cos \theta} \right).$$
So long as $R$ is much larger than the Schwarzschild radius and we are not too close to the poles, we may use $\theta \approx \tilde{\theta}$ in all of our formulas since the displacement and velocity kicks are $O(M/r)$, and the difference in angles will contribute at sub-leading order.

For many particles, the solution also requires $R$ to be much larger than the Schwarzschild radius for the whole central mass. For $N$ particles of mass $M$ on the same world line, we require

$$R \gtrsim R_{\text{min}} = 2GNM/c^2; \quad (43)$$

otherwise, the sphere of clocks is inside the Schwarzschild radius of the mass, forming a black hole.

So far, we have considered only the limits of the classical solution. In a real physical system, the quantum properties of a point particle add other constraints. The mass-energy of the particle is delocalized in space and time by an amount that depends on the character of its quantum state. For example, the de Broglie wavelength, $\lambda_M = \hbar/Mc$, gives the minimum spatial uncertainty of position for a massive particle that is localized in time. This value is shown in figure 4.

In the classical solution, the source is a single pointlike object with a definite trajectory. In quantum reality, it is a single quantum object whose wave function in space depends on its localization in time. Temporal coherence leads to correlations that are nonlocal in proper time, which affects the coherence of the metric distortion in the timelike direction.

The wave packet of particle location spreads out in space and time. The minimum spatial width of a location wave function for a measurement of duration $\tau$, or ‘standard quantum uncertainty’ [20, 21], is given by

$$\langle \Delta x^2 \rangle > \hbar \tau/NM \quad (44)$$
for a state of total mass $NM$. On the surface of a causal diamond with $R = c\tau$, the spatial uncertainty in the central world line leads to an angular quantum uncertainty,

$$\langle \Delta \Theta^2 \rangle \sim \langle \Delta x^2 \rangle / R^2 \sim (ct/R)(\hbar/NMc)^{-1} > \hbar/NMcR.$$  \hspace{1cm} (45)

Thus, the quantum bounds become important when both $M$ and $R$ are small. Figure 4 shows the range of classical and quantum validity in Planck units:

$$m_p \equiv \sqrt{\hbar G/c}, \hspace{0.5cm} r_p \equiv c r_p \equiv \sqrt{\hbar G/c^3} = \hbar/m_pc.$$ \hspace{1cm} (46)

7. Quantum superpositions

7.1. Quantum superposition of randomly oriented decays

In the region of validity shown in figure 4, the calculation far from the polar axis is a good approximation for both general relativity and quantum mechanics. In that regime, it can be reliably extrapolated to consider quantum states of the nonlocalized metric of a causal diamond. The entire setup, including the geometry itself and the sphere of clocks used to measure it, can be treated as a coherent quantum system.

If a decaying particle is a quantum system, the quantum nonlocality of the ‘spooky’ two-particle decay state also leads to a delocalized, Schrödinger-cat-like macroscopic superposition of space-times. As usual in quantum mechanics, there is no paradox: if the preparation of states is causal, the quantum coherence of the decaying-particle products entangles with the coherent causal diamonds of the distorted space-time, and the corresponding displacements of clocks.

Suppose the null particles from a decay are created in a quantum $S$-wave state, whose wave function is an isotropic superposition of all directions. This leads to a superposition of space-time distortion patterns. The wave function of the space-time includes a superposition of all the different orientations of the classical gravitational distortions, each one an eigenstate of the particle decay axis. Each metric in the superposition is coherent over a macroscopic causal diamond, starting with the decay and ending with the null incoming reflection from the boundary that carries the clock readings back to the observer. The wave function can be described as a sum of state amplitudes over histories, where the sum includes not just a worldline, but a whole causal diamond. A measurement of a particle axis will always find itself with a causal-diamond history consistent with it.

The classical solution shows that fractional distortion $\Delta$ of time displacement, as measured by observed clocks, varies coherently on the causal diamond surface of radius $R$ according to equation (29),

$$\Delta = \delta\tau/(c/R) = cT_2(\theta)/R \simeq \frac{5M}{24R}(3\cos^2 \theta - 1).$$ \hspace{1cm} (47)

The system with a single particle can be extrapolated by linear superposition to a system of many particles. If there are $N$ decaying particles of mass $M_i$ in the causal diamond, the large-angle coherence does not decrease from averaging their effects; instead, the amplitudes of their distortions linearly add. The coherent quantum state of time distortions on the sphere from $N$ such decays on the same world line can be written as a sum

$$|\Delta(\theta, \phi)\rangle = \sum_{i=1}^{N} \alpha_i |\vec{n}_i\rangle |\Delta(\theta, \phi)_i\rangle,$$ \hspace{1cm} (48)
where each element of the sum represents a decay along a different random axis \( \vec{n}_i \).

Each decay creates the same universal distortion pattern relative to its own axis. Their sum does not give a universal pattern, but it does give a universal power spectrum: the spherical harmonic distortion coefficients \( \alpha_{2m} \) from each decay pattern \( \Delta(\theta, \phi) \) add in quadrature. For example, for equal mass particles \( M = M_i \), the quadrupolar variances add to give fluctuations with a total quadrupolar variance

\[
\langle \Delta^2 \rangle_2 = \sum_{m=-2}^{2} \sum_{i=1}^{N} \alpha_{2m}(i)^2 \sim N(GM/Rc^2)^2,
\]

(49)

where \( \alpha_{2m}(i) \) denote the quadrupolar amplitudes for each decay, derived above (equation (29)). Note that for a given total mass \( NM \), the gravitational distortion decreases with \( N \) but increases with an adopted granularity scale \( M \). This result depends only on standard physics, and a conservative application of the quantum correspondence principle, that the gravity of a quantum system is the same as that of an identical classical one.

The same estimate applies to large-angle gravitational distortions created by noninteracting massless null particles that enter and leave the boundary of a volume with radius \( R \). For a gas with a mean occupation of \( N \) particles inside \( R \), equation (49) approximately gives the variance of large-angle gravitational fluctuations on the surface.

This framework is self-consistent until \( N \) is large enough that the gravity of the particles affects the mean curvature of the causal diamond. For consistency, in order not to form a black hole with radius less than \( R \), we require

\[
R < R_S = 2G(NM)/c^2
\]

(50)

so their number must not exceed

\[
N_{\text{max}} \sim c^3 R/2GM.
\]

(51)

For a gas of particles that saturates the bound \( N = N_{\text{max}} \), the quadrupolar gravitational redshift distortion,

\[
\langle \Delta^2 \rangle_2 \sim GM/2Rc^2,
\]

(52)

decreases with \( R \), which shows that a large system has a nearly-determinate, classical metric. Note that Planck’s constant \( \hbar \) does not appear in equation (52): although it is a quantum uncertainty, based on superposition of multiple decays, its magnitude is determined by the assumed discreteness scale, \( M \).

7.2. Coherent quantum-gravitational fluctuations

For particle states confined to a volume of size \( R \), extrapolation to \( N_{\text{max}} \) in equation (52) gives an estimate of the gravitational fluctuations created by randomly-oriented particle states with a UV cutoff \( M \). This applies approximately to the case of a system filled with particles whose density approximately saturates the bound, such as a cosmological solution or black hole on the scale of the horizon. For a UV cutoff at the Planck scale \( M = m_P \), equation (52) with \( R = c\tau \) becomes

\[
\langle \Delta^2 \rangle_2 \sim (\delta \tau^2)/\tau^2 \sim t_P/\tau.
\]

(53)

As expected, quantum-gravitational fluctuations are of the order of unity for \( \tau \) at the Planck scale. The surprising feature of equation (53) is the linear inverse dependence on \( \tau \) for durations
The gravitational effects of vacuum field fluctuations in effective field theory have long been studied in the context of inflationary universes (e.g. references [10, 11, 22]). In these systems, gravitational quantum uncertainty decreases as a higher power with scale: the typical relic metric fluctuation on the scale of an inflationary horizon of radius $c\tau$ is

$$\langle \Delta^2 \rangle_{\text{EFT}} \sim (t_P/\tau)^2.$$

(54)

The different results arise from different models of quantum coherence. The larger fluctuations in the decaying-particle system can be traced to the fact that a point particle creates a displacement that is coherent on scale $c\tau$ for a causal diamond of any duration $\tau$. The coherence scale in the effective field system is that of the particle wave function, $\sim \hbar/M_c$, so the variance is reduced by a factor $\sim 1/\tau$. Our classical solution explicitly shows that the physical gravitational effect corresponds to the former case: the gravity of a point particle imprints a large-angle, quasi-tidal coherent geometrical structure on macroscopic scales, much larger than the de Broglie wavelength of the particle.

For causally-coherent gravity, the large-angle, macroscopic distortion actually increases with duration, with variance

$$\langle \delta\tau^2 \rangle_2 \sim \tau t_P.$$

(55)

This scaling behavior follows directly from the classical solution via equation (49): the coherent large-angle memory of each Planck-energy single-particle state is independent of $R$, so the total distortion grows with the duration in the same way as a random walk.

Our semiclassical treatment meshes well with previous arguments that suggest macroscopic coherence of geometrical quantum states. For physical field states not to exceed the black hole mass in any volume, gravity requires macroscopic nonlocal coherence in the infrared [23–25]. Nonlocally coherent geometrical states (‘entanglement wedges’) are also key elements in recent resolutions of the black hole information paradoxes, incorporated into an account of fine-grained entropy [26]. Formal methods based on conformal descriptions of near-horizon states show that coherence can produce physical metric distortions comparable in amplitude to those estimated here, both for black hole horizons and causal diamond surfaces in flat space-time [12,27].

The time distortions on the causal diamond surface can be continuously extrapolated to provide a physical heuristic picture of what happens when a black hole evaporates. As a black hole evaporates (or is assembled) one particle at a time, each particle maps onto a coherent, mostly quadrupolar distortion that extends across the entire horizon surface, of the order of one Planck length in amplitude. A long-lived horizon is a superposition of a sequence of many such distortions. This simple picture of coherent horizon distortions agrees with a ‘quantum-first’ analysis of evaporation [28, 29]. In this view, states of Planck-scale ‘quantum foam’ are wave functions coherently spread everywhere across the horizon, no matter how large it is.

### 8. Conclusion

The Schrödinger-cat-like states of space-times with quantum decaying particles—superpositions of different geometries with macroscopically distinguishable physical properties, such as quadrupole moments of observable time distortions—show concretely how quantum-gravitational coherence works. The quantum construction uses particle-like states of matter, with superpositions of wave functions localized to causal diamonds, instead of quantized plane-wave states that extend to infinity, so it allows both preparation and measurement of states from a single world line. Directional indeterminacy of quantum
states is reconciled with gravity via a conventional correspondence principle, leading to quantum-geometrical states that are directionally coherent on null surfaces. It explicitly shows nonlocal, anisotropic effects of gravitational coherence manifested in a local measurement.

Our analysis shows that macroscopic coherence of quantum gravity has concrete physical consequences. Coherence leads to quantum-gravitational distortions on large angles and macroscopic scales, with variance that grows linearly with duration. The smaller variation predicted by effective field theory does not account for the physical effects of directional causal coherence.

The anisotropic distortion of time is a real physical effect, not a gauge artifact: in principle, it can be measured with actual clocks or laser interferometers. The permanent time displacement between the observer’s clock and any of the other clocks is an objective measurable quantity. Different states correspond to physically different geometries on macroscopic scales.

It is possible that the coherence of active quantum gravity could be measured not just in principle, but in an actual experiment. Although the distortions of physical black hole horizons are likely to be unobservable, a direct measurement of causal diamond distortions may be accessible to Michelson interferometers correlated to reveal spacelike coherence [30, 31]. The effect of coherent horizons would produce primordial perturbations during cosmic inflation of the order of equation (53), much larger than standard inflation theory, and could create new causally-coherent symmetries of angular correlations in cosmic microwave background anisotropy. These symmetries appear to be consistent with anomalous correlations measured in the CMB on large angular scales [32–35].

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Appendix A. Tensor spherical harmonics

In this section we lay out some properties of tensor spherical harmonics that will be used for the mode sum in section 3. Consider a field with spin \( s \). We can decompose any tensor on the sphere into a mode sum over rank \( s \) tensors weighted by spherical harmonics \( Y_{l,m} \) in the following manner

\[
\mathcal{Y}_{j,l,m} = \sum_{m_{l}=-l}^{l} \sum_{s} \langle l, m; s, m_{l}|j, m \rangle Y_{l,m_{l}} \tilde{t}_{s,m_{l}},
\]

\[
= \sum_{m_{l}=-l}^{l} \langle l, m - m_{l}; s, m_{l}|j, m \rangle Y_{l,m_{l}} \tilde{t}_{s,m_{l}},
\]

where the \( \tilde{t}_{s,m_{l}} \) are a basis of spin \( s \) unit tensors satisfying

\[
\tilde{t}_{s} \cdot \tilde{t}_{\beta} = \delta_{s,\beta}
\]

and the \( \langle j|_j \rangle \) are Clebsch–Gordon coefficients. For the case of gravitational radiation, we will be concerned with \( s = 2 \) tensor harmonics, specifically the transverse ones, which can be separated into ‘electric’ (\( E \)) and ‘magnetic’ (\( M \)) parts. Here, the dot product between spin 2 tensors.
is taken to mean

\[ A \cdot B = \sum_{i,j} A_{i,j} B_{i,j}. \]  

(59)

**Appendix B. Transverse tensor spherical harmonics**

As mentioned above, there are two types of transverse tensor harmonics.

\[ Y^{E}_{lm} = \sqrt{\frac{(l+1)(l+2)}{2(l+1)(2l+1)}} Y_{l+2,m}^{j} + \sqrt{\frac{3(l-1)(l+2)}{(2l-1)(2l+3)}} Y_{l,m}^{j} \]  

(60)

\[ Y^{M}_{lm} = \sqrt{\frac{l+2}{2l+1}} Y_{l-1,m} + \sqrt{\frac{l-1}{2l+1}} Y_{l+1,m}. \]  

(61)

These satisfy orthogonality conditions given by

\[ \int d\Omega Y^{E}_{lm} Y^{E*}_{l'm} = \delta_{ll'} \delta_{mm'} \]  

(62)

\[ \int d\Omega Y^{M}_{lm} Y^{M*}_{l'm} = \delta_{ll'} \delta_{mm'}. \]  

(63)

One can show using a series of recursion relations that the transverse harmonics have the following explicit form

\[ Y^{E}_{lm} = (\hat{\theta} \hat{\theta} - \hat{\phi} \hat{\phi}) \frac{1}{\sqrt{2(l+1)(l-1)(l+2)}} \left( 2 \frac{\partial^2}{\partial \theta^2} + l(l+1) \right) Y_{lm} \]  

(64)

\[ + (\hat{\theta} \hat{\phi} + \hat{\phi} \hat{\theta}) \sqrt{\frac{2}{l(l+1)(l-1)(l+2)}} \frac{im}{\sin \theta} \frac{\partial}{\partial \theta} \left( \frac{Y_{lm}}{\sin \theta} \right) \]

\[ Y^{M}_{lm} = - (\hat{\theta} \hat{\phi} - \hat{\phi} \hat{\theta}) \sqrt{\frac{2}{l(l+1)(l-1)(l+2)}} m \frac{\partial}{\partial \theta} \left( \frac{Y_{lm}}{\sin \theta} \right) \]  

(65)

\[ - (\hat{\theta} \hat{\phi} + \hat{\phi} \hat{\theta}) \frac{1}{\sqrt{2(l+1)(l-1)(l+2)}} \left( 2 \frac{\partial^2}{\partial \theta^2} + l(l+1) \right) Y_{lm}. \]

**Appendix C. Memory decomposition**

Now we will take the result from equation (17) and expand in a basis of transverse tensor harmonics. Note importantly that the transverse tensor harmonics are not defined for \( l < 2 \). In the case we are considering, we have axisymmetry, so only the \( m = 0 \) modes contribute. Looking at the form of equation (17), we see that we must have that

\[ \Delta D = \frac{M}{r} \left( \sum_{l=2}^{\infty} a_{l} Y^{E}_{l,0} \right) \cdot D_{0}. \]  

(66)
We can determine the $a_l$ using the orthogonality condition equation (60).

\[
 a_l = \int d\Omega \ Y_{l,0}^E \cdot (\hat{\theta} \hat{\theta} - \hat{\phi} \hat{\phi})
\]

\[
 = \sqrt{\frac{2}{l(l+1)(l-1)(l+2)}} \sqrt{\frac{2l+1}{4\pi}} \int d\Omega \left( \frac{d^2}{d\theta^2} + l(l+1) \right) P_l(\cos \theta)
\]

\[
 = - \sqrt{\frac{2\pi(2l+1)}{l(l+1)(l-1)(l+2)}} \int \cos \theta \left( 2 \cot \theta \frac{d}{d\theta} + l(l+1) \right) P_l(\cos \theta)
\]

\[
 = 2 \sqrt{\frac{2\pi(2l+1)}{l(l+1)(l-1)(l+2)}} \int \frac{d}{d\theta} \frac{x}{P_l(x)}
\]

\[
 = 4 \sqrt{\frac{2\pi(2l+1)}{l(l+1)(l-1)(l+2)}} (l \text{ even}). \quad (67)
\]

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