VANISHING DIELECTRIC CONSTANT REGIME FOR THE NAVIER STOKES MAXWELL EQUATIONS

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Abstract. In this paper we rigorously justify the convergence of smooth solutions of the Navier-Stokes-Maxwell equations towards smooth solutions of the classical 2D parabolic MHD equations in the case of vanishing dielectric constant. The result is achieved by means of higher-order energy estimates.

1. Introduction

The classical Magnetohydrodynamics (MHD) equations for an electrically conducting, non magnetic, viscous incompressible fluid, e.g. plasma fluid, with all the physical constants equal to one in $\Omega \times (0, T)$ with $\Omega \subset \mathbb{R}^d$ ($d = 2, 3$) read as follows:

\begin{align*}
\partial_t u - \nu \Delta u + (u \cdot \nabla) u + \nabla p - (B \cdot \nabla) B &= 0, \\
\partial_t B - \mu \Delta B + (u \cdot \nabla) B - (B \cdot \nabla) u &= 0, \\
\text{div} B &= \text{div} u = 0.
\end{align*}

(1.1)

The system (1.1), widely studied in literature and used in the applications (see [13, 3]), models the evolution of the velocity $u \in \mathbb{R}^d$, the magnetic field $B \in \mathbb{R}^d$ and the scalar pressure $p \in \mathbb{R}$. Moreover, the system is accomplished with initial data, namely

\begin{align*}
 u(x, 0) = u_0(x), \quad B(x, 0) = B_0(x) \text{ on } \Omega \times \{t = 0\},
\end{align*}

(1.2)

and suitable boundary conditions on $\partial \Omega \times (0, T)$. The model (1.1) is not the only system of equations used to model this kind of fluids. Another interesting model for plasma fluids is given by the Navier-Stokes-Maxwell system (see [12]):

\begin{align*}
\partial_t u - \Delta u + (u \cdot \nabla) u + \nabla q &= j \times B, \\
\partial_t E - \text{curl} B &= -j, \\
\partial_t B + \text{curl} E &= 0, \\
\text{div} u &= 0, \\
\text{div} B &= 0, \\
E + (u \times B) &= j,
\end{align*}

(1.3)

where $E \in \mathbb{R}^3$ is the electric field and $j \in \mathbb{R}^3$ is the current density. In the case the domain $\Omega$ is two dimensional the cross products in the equations

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(1.3) make sense by considering \( u, B, E \) and \( j \) with values in \( \mathbb{R}^3 \). The goal of this paper is to recover in a rigorous way solutions of equations (1.1) from solutions of equations (1.3) in a suitable limit process, that as we will see fits in the framework of singular limits. In particular, we give a rigorous justification of this singular limit in the theory of magnetohydrodynamic equations. Before going into the mathematical details of this limiting process, in the next section we describe the physical principles that give rise to the models we are considering.

1.1. Singular limit and Statement of the Main Result. The system (1.1) is derived from the Navier-Stokes equations and the Maxwell equations by using the classical continuous mechanics theory and by making, as usual, smallness assumptions in order to simplify the equations taken into account. Specifically, the Maxwell equations for materials which are neither magnetic nor dielectric, read as follows (see [3]):

\[
\begin{align*}
\text{div } E &= \frac{\rho}{\varepsilon_0} \quad \text{(Gauss’ law)} \\
\text{div } B &= 0 \quad \text{(Solenoidal nature of } B) \\
\text{curl } E &= -\frac{\partial}{\partial t} B \quad \text{(Faraday’s law in differential form)} \\
\text{curl } B &= \mu_0 \left( j + \varepsilon_0 \frac{\partial}{\partial t} E \right) \quad \text{(Ampère - Maxwell equation)}
\end{align*}
\]

In addition we have

\[
\begin{align*}
\dot{j} &= \sigma (E + u \times B) \quad \text{(current density - Ohm’s law)} \\
F &= \rho E + j \times B \quad \text{(electrostatic force plus Lorentz force)}
\end{align*}
\]

Here \( \rho \) is the total charge density, \( E \) the total electric field, \( B \) the magnetic field, \( \varepsilon_0 \) the electric permittivity of free space, \( \mu_0 \) the permeability of free space and \( \sigma \) the conductivity. In MHD equations the Maxwell equations are considerably simplified. First, by assuming the quasineutrality regime in \( F \) the contribution of the electric force \( \rho E \) is small compared with the Lorentz force and then \( F \) could be assumed being equal only to \( j \times B \). Apparently, \( \rho \) plays a role only in the Gauss’ law, then we simply drop it. At this point we are left with the following form of the Maxwell equations

\[
\begin{align*}
\text{div } B &= 0 \\
\text{curl } E &= -\frac{\partial}{\partial t} B \\
\text{curl } B &= \mu_0 \left( j + \varepsilon_0 \frac{\partial}{\partial t} E \right) \quad \text{(1.5)}
\end{align*}
\]

and the relations

\[
\begin{align*}
\dot{j} &= \sigma (E + u \times B) \\
F &= j \times B.
\end{align*}
\]
If we set $\sigma = 1$, by using (1.5) we derive the Navier-Stokes-Maxwell system:

$$
\partial_t u - \Delta u + (u \cdot \nabla) u + \nabla q = j \times B
$$

$$
\mu_0 \varepsilon_0 \partial_t E - \text{curl} \, B = -\mu_0 j
$$

$$
\partial_t B + \text{curl} \, E = 0
$$

$$
div \, u = 0
$$

$$
div \, B = 0
$$

$$
E + (u \times B) = j.
$$

(1.6)

The last assumption in the MHD regime is that the displacement of the currents $\mu_0 \varepsilon_0 \partial_t E/\partial t$ is negligible. Indeed in a typical conductor the characteristic velocity is much smaller than the speed of the light then, the displacement of the currents can be considered small. This can be seen more clearly with a simple scaling argument. In order to get a somewhat deeper insight into the structure of possible solutions, we can identify characteristic values of relevant physical quantities: the reference time $t_{ref}$, the reference length $L_{ref}$, the reference velocity $u_{ref}$, and the characteristic values of other composed quantities $q_{ref}$, $B_{ref}$, $E_{ref}$, $j_{ref}$. Introducing new independent and dependent variables $X' = X/X_{ref}$, omitting the primes in the resulting equations and recalling that $\mu_0 \varepsilon_0 = c^{-2}$, where $c$ is the speed of light, we get the following dimensionless form of the Ampère - Maxwell equation

$$
\left(\frac{u_{ref}}{c}\right)^2 \partial_t E - \text{curl} \, B = -\bar{\nu} j
$$

(1.7)

with $\bar{\nu}$ being a dimensionless constant. Then, the displacement of the current is negligible because the characteristic velocity of the fluid is much smaller than the velocity of the light. Setting $\varepsilon = \left(\frac{u_{ref}}{c}\right)^2$ we have the following $\varepsilon$-dependent dimensionless version of the Navier-Stokes-Maxwell system

$$
\partial_t u^\varepsilon - \Delta u^\varepsilon + (u^\varepsilon \cdot \nabla) u^\varepsilon + \nabla q^\varepsilon = j^\varepsilon \times B^\varepsilon
$$

$$
\varepsilon \partial_t E^\varepsilon - \text{curl} \, B^\varepsilon = -j^\varepsilon
$$

$$
\partial_t B^\varepsilon + \text{curl} \, E^\varepsilon = 0
$$

$$
div \, u^\varepsilon = 0
$$

$$
div \, B^\varepsilon = 0
$$

$$
E^\varepsilon + (u^\varepsilon \times B^\varepsilon) = j^\varepsilon
$$

(1.8)

supplemented with the following initial data

$$
 u^\varepsilon(x, 0) = u_0^\varepsilon(x) \quad B^\varepsilon(x, 0) = B_0^\varepsilon(x) \quad E^\varepsilon(x, 0) = E_0^\varepsilon(x).
$$

(1.9)

At a formal level we can see, that as $\varepsilon \to 0$ we have that the Ampère - Maxwell equation reduces to the Ampère’s law

$$
\text{curl} \, B = j
$$

(1.10)

Then, if we combine Ohm’s law, Ampère’s law with the Faraday’s law we get the following equations for the magnetic field

$$
\partial_t B - \text{curl} \, \text{curl} \, B - \text{curl} \, (u \times B) = 0.
$$

(1.11)

and, concerning the equations for the velocity field, by using (1.10) we get

$$
\partial_t u - \Delta u + (u \cdot \nabla) u + \nabla p = \text{curl} \, B \times B.
$$

(1.12)
Then, by classical vector identities (1.11) is exactly the equations for the magnetic field in (1.1) and, up to redefine the pressure, (1.12) is the equations for $u$ in (1.1).

In this paper we rigorously justify the above formal limit in the case of $\Omega$ being the two dimensional torus. Our main theorem can be stated as follows.

**Theorem 1.1.** Let $\Omega = \mathbb{T}^2$ and $T > 0$, $s > 3$. Let $(u_0, B_0) \in H^s(\mathbb{T}^2; \mathbb{R}^2)$ be divergence-free vector field. Let $(u, B) \in C([0, T); H^s(\mathbb{T}^2; \mathbb{R}^2))$ be the unique smooth solutions of the Cauchy problem (1.1)-(1.2). Then, there exist $\bar{\varepsilon} > 0$ and $u^{\varepsilon}_0$, $B^{\varepsilon}_0$ and $E^{\varepsilon}_0$ in $H^s(\mathbb{T}^2; \mathbb{R}^3)$ such that for any $\bar{\varepsilon} < \varepsilon$ the unique smooth solutions $u^{\varepsilon}$, $B^{\varepsilon}$ and $E^{\varepsilon}$ of (1.8)-(1.9) satisfy:

$$u^{\varepsilon} \to u \text{ weakly}^* \text{ in } C([0, T); H^1(\mathbb{T}^2; \mathbb{R}^3)),$$

$$B^{\varepsilon} \to B \text{ weakly}^* \text{ in } C([0, T); H^1(\mathbb{T}^2, \mathbb{R}^3)),$$

where $u$ and $B$ are considered as three dimensional vector with vanishing third component.

1.2. **Different interpretations of the limit.** This type of limit may have different interpretations according to the different approaches. In particular it may be considered also in the context of the hydrodynamical limits of Vlasov-Maxwell equations or in the framework of hyperbolic to parabolic relaxation theory. In fact in the paper [9], the authors perform a formal analysis for the hydrodynamical limit from a two- species Vlasov-Maxwell-Boltzmann equations in the regime of $\varepsilon_0$ small. In particular they consider the following form of the scaled Vlasov-Maxwell Boltzmann system describing the dynamics of charged dilute particles,

$$\varepsilon \partial_t F^{\varepsilon} + v \cdot \nabla_x F^{\varepsilon} + (\varepsilon E^{\varepsilon} + v \times B^{\varepsilon}) \cdot \nabla_v G^{\varepsilon} = \frac{1}{\varepsilon} Q(F^{\varepsilon}, F^{\varepsilon}),$$

$$\varepsilon \partial_t G^{\varepsilon} + v \cdot \nabla_x G^{\varepsilon} + \left(\frac{E^{\varepsilon}}{\varepsilon} + \frac{v \times B^{\varepsilon}}{\varepsilon}\right) \cdot \nabla_v F^{\varepsilon} = \frac{1}{\varepsilon} Q(G^{\varepsilon}, F^{\varepsilon}),$$

$$\varepsilon \partial_t E^{\varepsilon} - \nabla \times B^{\varepsilon} = -\int_{\mathbb{R}^3} v G^{\varepsilon} dv, \quad \nabla \cdot B^{\varepsilon} = 0,$$

$$\partial_t B^{\varepsilon} - \nabla \times E^{\varepsilon}, \quad \nabla \cdot E^{\varepsilon} = \frac{1}{\varepsilon} \int_{\mathbb{R}^3} G^{\varepsilon} dv,$$

where $\varepsilon = \varepsilon_0$, $x$ is the position, $v$ the velocity, $F^{\varepsilon}$ is the total mass density, $G^{\varepsilon}$ the total charge density, $(E^{\varepsilon}, B^{\varepsilon})$ the electromagnetic field. Formally, as $\varepsilon \to 0$ one can recover the system (1.1), for details see Theorem 3.2 in [9]. Finally, we want to remark that the previous limit is also interesting from the point of view of the hyperbolic-parabolic relaxation limit since the system (1.6) can be seen as the relaxed version of the system (1.1). In fact, let us consider the following system
\[
\begin{align*}
\partial_t u - \Delta u + (u \cdot \nabla)u + \nabla q &= j \times B \\
\partial_t E - \text{curl} B &= -j \\
\partial_t B + \text{curl} E &= 0 \\
\text{div} u &= 0 \\
\text{div} B &= 0 \\
E + (u \times B) &= j.
\end{align*}
\] (1.15)

We perform now, the following diffusive scaling, namely for any \( \varepsilon > 0 \) we set
\[
\begin{align*}
\begin{align*}
&u^{\varepsilon}(x,t) = \frac{1}{\sqrt{\varepsilon}} u \left( \frac{x}{\sqrt{\varepsilon}}, \frac{t}{\varepsilon} \right) \\
&B^{\varepsilon} = \frac{1}{\sqrt{\varepsilon}} B \left( \frac{x}{\sqrt{\varepsilon}}, \frac{t}{\varepsilon} \right), \\
&E^{\varepsilon} = \frac{1}{\varepsilon} E \left( \frac{x}{\sqrt{\varepsilon}}, \frac{t}{\varepsilon} \right) \\
&j^{\varepsilon} = \frac{1}{\varepsilon} j \left( \frac{x}{\sqrt{\varepsilon}}, \frac{t}{\varepsilon} \right) \\
&q^{\varepsilon} = \frac{1}{\varepsilon} q \left( \frac{x}{\sqrt{\varepsilon}}, \frac{t}{\varepsilon} \right).
\end{align*}
\end{align*}
\] (1.16)

With the previous scaling the system (1.15) assumes the form (1.6) and, as \( \varepsilon \to 0 \), at a formal level we get the MHD equations. Let us recall that the diffusive scaling (1.16) has been widely investigated in the analysis of hyperbolic-parabolic relaxation limits for weak solutions of an hyperbolic system with strongly diffusive terms, see [10], [4], [7], [1]. For a general overview of the theory of the singular limits see the survey [5] and the paper [6], where the theory is completely set up.

1.3. Final Remarks and Plan of the paper. We want to conclude this Introduction by making some comments and pointing out some open questions.

- The regularity of the initial data can be clearly relaxed.
- An extension of this result in the whole space should be only technical. However, in the case of a bounded domain with no-slip boundary conditions the proof of Theorem 1.1 does not work.
- It could be possible to obtain a rate of convergence for the \((u^{\varepsilon}, B^{\varepsilon})\) by using a modulated energy argument as in [1].
- A very interesting problem would be the convergence in the topology of the initial data globally in time in two dimension and locally in time in three dimension.
- Concerning the three dimensional case, we strongly believe that this type of limit works in the case of small initial data for the (1.1).
- A very interesting open problem is the convergence on three dimension in the energy space.

The plan of the paper is as follows. In Section 2 we collect all the definitions and the technical results we are going to use through the paper. In Section 3 we recover all the a priori estimates necessary to prove our main result Theorem 1.1. Finally, Section 4 is devoted to the proof of the Theorem 1.1.

2. Preliminares

We briefly fix the notation, which is typical of space-periodic problems. In the sequel we shall use the customary Lebesgue spaces \(L^p(\Omega)\) and Sobolev
spaces $W^{k,p}(\Omega)$ and $H^s(\Omega) := W^{s,2}(\Omega)$, with $\Omega := [0, 2\pi]^2$; for simplicity we shall do not distinguish between scalar and vector valued functions. Since we shall work with periodic boundary conditions the spaces are made of periodic functions and in the Hilbertian case $p = 2$ we can easily characterize them by using Fourier Series on the 2D torus. We use $\| \cdot \|_p$ to denote the $L^p(T^2)$ norm and we impose the zero mean condition and on velocity, the pressure and the magnetic field. We will denote by $H^s(T^2)$, $s = 1, 2$, the classical Sobolev spaces. Moreover, $L^p(0, T; X)$ denotes the classical Bochner spaces endowed with the norm

$$
\| f \|_{L^p(0, T; X)} := \begin{cases} 
\left( \int_0^T \| f(t) \|_X \right)^{1/p} & \text{if } 1 \leq p < \infty, \\
\sup_{0 \leq t \leq T} \| f(t) \|_X & \text{if } p = +\infty,
\end{cases}
$$

Since we assumed divergence-free condition and zero average for $u$ and $B$ on $T^2$ the following norm equivalences hold,

$$
\| u \|_{H^2} \cong \| \Delta u \|_2, \quad \| u \|_{H^1} \cong \| \nabla u \|_2,
$$

$$
\| B \|_{H^2} \cong \| \Delta B \|_2, \quad \| B \|_{H^1} \cong \| \nabla B \|_2.
$$

We will use also the following standard inequalities:

- The Gagliardo-Nirenberg inequality, namely
  $$
  \| f \|_p \leq C \| \nabla f \|_r \| f \|_q^{1-\alpha},
  $$
  \hspace{1cm} (2.1)

  where
  $$
  \frac{1}{p} = \left( \frac{1}{r} - \frac{1}{2} \right) \alpha + \frac{1-\alpha}{q}
  $$
  and $\alpha \in [0, 1]$.

- The Kato-Ponce inequality, namely
  $$
  \| fg \|_{H^s} \leq C(\| f \|_\infty \| g \|_{H^s} + \| g \|_\infty \| f \|_{H^s})
  $$
  \hspace{1cm} (2.2)

  which holds for any $s > 0$.

Now, we recall some important results concerning the equations (1.1). Let us start with the definition of weak solutions for the Cauchy problem (1.1)-(1.2).

**Definition 2.1.** A pair $(u, B)$ is a weak solutions of the Cauchy problem (1.1)-(1.2) if

$u, B \in C([0, T); L^2_{weak}(T^2; \mathbb{R}^2)) \cap L^\infty((0, T); L^2(T^2; \mathbb{R}^2)) \cap L^2((0, T); H^1(T^2; \mathbb{R}^2))$

and the equations (1.1) are satisfied in the sense of distribution for any divergence-free test function belonging to the space $C_c^\infty([0, T); C^\infty_{per}(T^2; \mathbb{R}^2))$.

The following global regularity and uniqueness theorem has been proved in [13].

**Theorem 2.2.** Let $s > 3$ and $u_0, B_0 \in H^s(T^2; \mathbb{R}^2)$. There exists a unique global smooth solution $(u, B)$ of the Cauchy problem (1.1)-(1.2) such that:

$u \in C([0, T); H^s(T^2; \mathbb{R}^2))$, 

$B \in C([0, T); H^s(T^2; \mathbb{R}^2))$. 
Moreover, \((u, B)\) is also unique in the class of weak solutions in the sense of Definition 2.1.  

Concerning the Navier-Stokes-Maxwell system the global existence of smooth solutions has been proved in [12].

**Theorem 2.3.** Let \(s > 3\) and \(u_0^\varepsilon, B_0^\varepsilon\) and \(E_0^\varepsilon\) be in \(H^s(\mathbb{T}^2; \mathbb{R}^3)\), with \(u_0^\varepsilon\) and \(B_0^\varepsilon\) divergence-free. Let \(\varepsilon > 0\) fixed and arbitrary. Then, there exists a unique global smooth solution \((u^\varepsilon, B^\varepsilon, E^\varepsilon)\) of the Cauchy problem (1.8)-(1.9) with

\[
\begin{align*}
  u^\varepsilon &\in C([0, T); H^s(\mathbb{T}^2; \mathbb{R}^3)), \\
  B^\varepsilon &\in C([0, T); H^s(\mathbb{T}^2; \mathbb{R}^3)), \\
  E^\varepsilon &\in C([0, T); H^s(\mathbb{T}^2; \mathbb{R}^3)).
\end{align*}
\]

This result has been extended to the three-dimensional space with small initial data in [8]. We want to point out that the global existence of weak solutions à la Leray-Hopf is an open problem even in two dimensions, see [12].

3. A priori estimates

In this section we will recover the main a priori estimates necessary to prove Theorem 1.1. Let \(u_0^\varepsilon, B_0^\varepsilon\) and \(E_0^\varepsilon\) be smooth initial data and \(u^\varepsilon, B^\varepsilon\) and \(E^\varepsilon\) the unique global smooth solutions of the Cauchy problem (1.8)-(1.9). The first basic \(\varepsilon\)-independent a priori estimate for the system (1.8) is the classical energy estimate, see [12].

**Lemma 3.1.** Let \((u^\varepsilon, B^\varepsilon, E^\varepsilon)\) be a solution of the system (1.8), then the following differential equality holds.

\[
\frac{d}{dt} \left( \int |u^\varepsilon|^2 + |B^\varepsilon|^2 + \varepsilon |E^\varepsilon|^2 \right) + 2 \int |\nabla u^\varepsilon|^2 + |j^\varepsilon|^2 = 0. \tag{3.1}
\]

**Proof.** The proof is rather standard. We multiply the first three equations of (3.2) by \(u^\varepsilon, B^\varepsilon\) and \(E^\varepsilon\) respectively. We integrate by parts in space, by using the definition of \(j^\varepsilon\) and adding up everything we obtain (3.1). \(\square\)

The a priori estimates of Lemma 3.1 are clearly not enough to justify the limit as \(\varepsilon\) goes to zero. In order to get further a priori estimates we need to consider the following formulation of the system (1.8):

\[
\begin{align*}
  \partial_t u^\varepsilon - \Delta u^\varepsilon + (u^\varepsilon \cdot \nabla) u^\varepsilon + \nabla p^\varepsilon &= (B^\varepsilon \cdot \nabla) B^\varepsilon - \varepsilon \partial_t E^\varepsilon \times B^\varepsilon, \\
  \varepsilon \partial_t B^\varepsilon + \partial_t B^\varepsilon - \Delta B^\varepsilon + (u^\varepsilon \cdot \nabla) B^\varepsilon &= (B^\varepsilon \cdot \nabla) u^\varepsilon, \\
  \varepsilon \partial_t E^\varepsilon + E^\varepsilon - \text{curl} B^\varepsilon &= -(u^\varepsilon \times B^\varepsilon), \\
  \text{div} u^\varepsilon &= 0, \\
  \text{div} B^\varepsilon &= 0.
\end{align*}
\]

The initial data for the system (3.2) are

\[
\begin{align*}
  u^\varepsilon(x, 0) &= u_0^\varepsilon(x), \\
  B^\varepsilon(x, 0) &= B_0^\varepsilon(x), \\
  \partial_t B^\varepsilon(x, 0) &= \text{curl} E_0^\varepsilon(x), \\
  E^\varepsilon(x, 0) &= E_0^\varepsilon(x).
\end{align*}
\]
Note that the value of $\partial_t B^\varepsilon$ at time $t = 0$ is obtained from the system (1.8) and the pressure has been redefined. The next Lemma is the first main a priori estimate of the paper. Before stating it we define the following quantities

\begin{equation}
E_1(t) = \int \frac{|u^\varepsilon|^2}{2} + \frac{|B^\varepsilon + 2\varepsilon \partial_t B^\varepsilon|^2}{2} + 3\varepsilon|\nabla B^\varepsilon|^2 + \varepsilon^2|\partial_t B^\varepsilon|^2 + \varepsilon|\Delta u^\varepsilon|^2 \tag{3.3}
\end{equation}

\begin{equation}
D_1(t) = \int \varepsilon^2|\partial_t E^\varepsilon|^2 + \frac{1}{2}|\nabla u^\varepsilon|^2 + \frac{1}{2}|\nabla B^\varepsilon|^2 + \varepsilon|\partial_t B^\varepsilon|^2. \tag{3.4}
\end{equation}

**Lemma 3.2.** Let $(u^\varepsilon, B^\varepsilon, E^\varepsilon)$ be a smooth solutions of (1.8) in $\mathbb{T}^2 \times (0, T)$. There exists an absolute constant $C_1 > 0$ such that, if

\[ \|u^\varepsilon(t, \cdot)\|_\infty + \|B^\varepsilon(t, \cdot)\|_\infty \leq \frac{C_1}{\sqrt{\varepsilon}} \quad \text{for any } t \in [0, T) \tag{3.5} \]

then,

\[ \frac{d}{dt} E_1(t) + D_1(t) \leq 0 \quad \text{for any } t \in (0, T). \tag{3.6} \]

**Proof.** We multiply the first equation in (3.2) by $u^\varepsilon$, after integration by parts we get

\[ \frac{d}{dt} \int \frac{|u^\varepsilon|^2}{2} + \int |\nabla u^\varepsilon|^2 = \int (B^\varepsilon \cdot \nabla) B^\varepsilon \cdot u^\varepsilon - \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \cdot u^\varepsilon. \tag{3.7} \]

Then, we consider the second equation of (3.2) rewritten as follows

\[ 2\varepsilon \partial_t B^\varepsilon + \partial_t B^\varepsilon - \Delta B^\varepsilon + (u^\varepsilon \cdot \nabla) B^\varepsilon - \varepsilon \partial_t B^\varepsilon = (B^\varepsilon \cdot \nabla) u^\varepsilon. \tag{3.8} \]

We multiply (3.8) by $B^\varepsilon + 6\varepsilon \partial_t B^\varepsilon$, and after integrating by parts we get

\[ \frac{d}{dt} \left( \int \frac{|B^\varepsilon + 2\varepsilon \partial_t B^\varepsilon|^2}{2} + 3\varepsilon|\nabla B^\varepsilon|^2 + \varepsilon^2|\partial_t B^\varepsilon|^2 \right) + 4\varepsilon \int |\partial_t B^\varepsilon|^2 + \int |\nabla B^\varepsilon|^2 - \varepsilon \int \partial_t B^\varepsilon \cdot B^\varepsilon + 6\varepsilon \int \partial_t B^\varepsilon \cdot \text{curl}(B^\varepsilon \times u^\varepsilon)
\]

\[ = \int (B^\varepsilon \cdot \nabla) u^\varepsilon \cdot B^\varepsilon, \tag{3.9} \]

which can be reformulated as follows,

\[ \frac{d}{dt} \left( \int \frac{|B^\varepsilon + 2\varepsilon \partial_t B^\varepsilon|^2}{2} + 3\varepsilon|\nabla B^\varepsilon|^2 + \varepsilon^2|\partial_t B^\varepsilon|^2 \right) + \int |\nabla B^\varepsilon|^2 + \varepsilon \int |\partial_t B^\varepsilon|^2 + 3\varepsilon \left( \int |\partial_t B^\varepsilon + \text{curl}(B^\varepsilon \times u^\varepsilon)|^2 - \varepsilon \int \partial_t B^\varepsilon \cdot B^\varepsilon \right.
\]

\[ - 3\varepsilon \int |\text{curl}(B^\varepsilon \times u^\varepsilon)|^2 = \int (B^\varepsilon \cdot \nabla) u^\varepsilon \cdot B^\varepsilon. \]

Finally, we multiply the third equation of (3.2) by $\varepsilon \partial_t E^\varepsilon$ and, after an integration by parts we have

\[ \frac{d}{dt} \varepsilon \int \frac{|E^\varepsilon|^2}{2} + \varepsilon^2 \int |\partial_t E^\varepsilon|^2 - \int B^\varepsilon \cdot \varepsilon \partial_t \text{curl} E^\varepsilon = - \int (u^\varepsilon \times B^\varepsilon) \cdot \varepsilon \partial_t E^\varepsilon. \tag{3.10} \]

By using (1.3) and the following standard property of vector and scale products

\[ -(u^\varepsilon \times B^\varepsilon) \cdot \varepsilon \partial_t E^\varepsilon = u^\varepsilon \cdot (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \]
Lemma 3.3. Then, the following lemma holds.
We have that
\[ \int v^\varepsilon \cdot \nabla u^\varepsilon = \int u^\varepsilon \cdot (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon). \] (3.11)

By adding up (3.7), (3.9) and (3.11) we get
\[ \frac{d}{dt} \int |E^\varepsilon|^2 + \varepsilon \int |\partial_t B^\varepsilon \cdot B^\varepsilon = \int u^\varepsilon \cdot (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon). \] (3.12)

At this point we treat the term with negative sign in the right hand side.
We have that
\[ \int |\text{curl}(B^\varepsilon \times u^\varepsilon)|^2 \leq \int |(u^\varepsilon \cdot \nabla)B^\varepsilon|^2 + \int |(B^\varepsilon \cdot \nabla)u^\varepsilon|^2 \]
\[ \leq C(\|u^\varepsilon\|_\infty^2 + \|B^\varepsilon\|_\infty^2) \left( \frac{1}{2} \|\nabla u^\varepsilon\|_2^2 + \frac{1}{2} \|\nabla B^\varepsilon\|_2^2 \right), \]
where \( C > 0 \) is an absolute constant. Then (3.12) becomes an inequality and we get (3.6) with \( C_1 = \frac{1}{4\varepsilon}. \)

We need also higher order a priori estimates independent on \( \varepsilon. \) This will be done in the next Lemma. Let us define the following quantities
\[ E_2(t) = \int \frac{|\nabla u^\varepsilon|^2}{2} + \varepsilon \frac{\Delta u^\varepsilon}{2} + \frac{|\nabla B^\varepsilon + 2\partial_t \nabla B^\varepsilon|^2}{2} \]
\[ + \int 3\varepsilon |\Delta B^\varepsilon|^2 + \varepsilon^2 |\partial_t \nabla B^\varepsilon|^2 + \varepsilon \frac{|\nabla E^\varepsilon|^2}{2}. \]
\[ D_2(t) = \frac{1}{4} \left( \int |\Delta u^\varepsilon|^2 + |\Delta B^\varepsilon|^2 + \varepsilon |\partial_t \nabla u^\varepsilon|^2 + \varepsilon^2 |\partial_t \nabla E^\varepsilon|^2 \right). \]

Then, the following lemma holds.

Lemma 3.3. Let \((u^\varepsilon, B^\varepsilon, E^\varepsilon)\) be a smooth solutions of (1.8) - (1.9) in \( \mathbb{T}^2 \times (0, T). \) There exists an absolute constant \( C_2 > 0 \) such that if
\[ \|u^\varepsilon(t, \cdot)\|_\infty + \|B^\varepsilon(t, \cdot)\|_\infty \leq \frac{C_2}{\sqrt{\varepsilon}} \text{ for any } t \in [0, T) \] (3.13)
then, the following differential inequality holds,
\[ \frac{d}{dt} E_2(t) + D_2(t) \leq C(1 + E_1(t)) D_1(t) E_2(t). \] (3.14)

Proof. We start by multiplying the first equation of (3.2) by \(-\Delta u^\varepsilon\), after an integration by parts we get
\[ \frac{d}{dt} \int |\nabla u^\varepsilon|^2 + \int |\Delta u^\varepsilon|^2 = \int u^\varepsilon \cdot \nabla u^\varepsilon \cdot \Delta u^\varepsilon - \int B^\varepsilon \cdot \nabla B^\varepsilon \Delta u^\varepsilon \]
\[ + \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \cdot \Delta u^\varepsilon. \] (3.15)
The second estimate we perform is obtained by multiplying the first equation of (3.2) by $-\varepsilon \Delta \partial_t u^\varepsilon$
\[ \frac{d}{dt} \int \varepsilon \frac{|\nabla \partial_t u^\varepsilon|^2}{2} + \varepsilon \int |\nabla \partial_t u^\varepsilon|^2 = \varepsilon \int u^\varepsilon \cdot \nabla u^\varepsilon \cdot \Delta \partial_t u^\varepsilon \]
\[ + \varepsilon \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \Delta \partial_t u^\varepsilon \]  
\[ - \varepsilon \int B^\varepsilon \nabla B^\varepsilon \Delta \partial_t u^\varepsilon. \]  
(3.16)

Then, we multiply (3.8) by $-\Delta (B^\varepsilon + 6\varepsilon \partial_t B^\varepsilon)$ and we get
\[ \frac{d}{dt} \left( \int \frac{|\nabla B^\varepsilon + 2\varepsilon \partial_t \nabla B^\varepsilon|^2}{2} + 3\varepsilon |\Delta B^\varepsilon|^2 + \varepsilon^2 |\partial_t \nabla B^\varepsilon|^2 \right) + \int |\Delta B^\varepsilon|^2 
+ \varepsilon \int |2\partial_t \nabla B^\varepsilon + \frac{3}{2} \nabla \text{curl}(B^\varepsilon \times u^\varepsilon)|^2 + \frac{9}{4} \varepsilon \int |\nabla \text{curl}(B^\varepsilon \times u^\varepsilon)|^2 \]  
\[ + \varepsilon \int \partial_t B^\varepsilon \cdot \Delta B^\varepsilon = - \int \text{curl}(u^\varepsilon \times B^\varepsilon) \Delta B^\varepsilon. \]  
(3.17)

Finally, we multiply the third equation of (3.2) by $-\varepsilon \partial_t \Delta E^\varepsilon$ and we obtain
\[ \frac{d}{dt} \int \varepsilon \frac{|\nabla E^\varepsilon|^2}{2} + \varepsilon^2 \int |\partial_t \nabla E^\varepsilon|^2 \int \text{curl} B^\varepsilon \varepsilon \partial_t \Delta E^\varepsilon 
= \int (u^\varepsilon \times B^\varepsilon) \varepsilon \partial_t \Delta E^\varepsilon \]  
(3.18)

Concerning the third term of the left-hand side of (3.18) by using again (3.8), we have
\[ \varepsilon \int \text{curl} B^\varepsilon \partial_t \Delta E^\varepsilon = \varepsilon \int B^\varepsilon \partial_t \Delta \text{curl} E^\varepsilon = - \varepsilon \int B^\varepsilon \partial_t \Delta \partial_t B^\varepsilon \]
\[ = - \varepsilon \int B^\varepsilon \partial_t \Delta B^\varepsilon = - \varepsilon \int \Delta B^\varepsilon \partial_t B^\varepsilon. \]

Then (3.18) becomes
\[ \frac{d}{dt} \int \varepsilon |\nabla E^\varepsilon|^2 + \varepsilon^2 \int |\partial_t \nabla E^\varepsilon|^2 - \varepsilon \int \Delta B^\varepsilon \partial_t B^\varepsilon 
= \int (u^\varepsilon \times B^\varepsilon) \varepsilon \partial_t \Delta E^\varepsilon. \]  
(3.19)

By summing up (3.15), (3.16), (3.17) and (3.19) we get
\[ \frac{d}{dt} \mathcal{E}_2(t) + \int |\Delta u^\varepsilon|^2 + \varepsilon \int |\nabla \partial_t u^\varepsilon|^2 + \int |\Delta B^\varepsilon|^2 
+ \varepsilon^2 \int |\partial_t \nabla E^\varepsilon|^2 + \varepsilon \int |2\partial_t \nabla B^\varepsilon + \frac{3}{2} \nabla \text{curl}(B^\varepsilon \times u^\varepsilon)|^2 
- \frac{9}{4} \varepsilon \int |\nabla \text{curl}(u^\varepsilon \times B^\varepsilon)|^2 \leq (I) + (II) + (III) + (IV). \]  
(3.20)

Where the terms on the right-hand side are respectively
\[ (I) = \int (u^\varepsilon \cdot \nabla) u^\varepsilon \Delta u^\varepsilon - (B^\varepsilon \cdot \nabla) B^\varepsilon \Delta u^\varepsilon + (u^\varepsilon \cdot \nabla) B^\varepsilon \Delta B^\varepsilon - (B^\varepsilon \cdot \nabla) u^\varepsilon \Delta B^\varepsilon, \]
and (III) have that

We estimate all the previous terms separately. By integrating by parts we have that

\[
(II) = \varepsilon \int (u^\varepsilon \cdot \nabla) u^\varepsilon \Delta \partial_t u^\varepsilon,
\]

\[
(III) = \varepsilon \int (B^\varepsilon \cdot \nabla) B^\varepsilon \Delta \partial_t u^\varepsilon,
\]

\[
(IV) = \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \Delta u^\varepsilon + \varepsilon \int (u^\varepsilon \times B^\varepsilon) \partial_t \Delta E^\varepsilon + \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \varepsilon \Delta \partial_t u^\varepsilon.
\]

We estimate all the previous terms separately. By integrating by parts we have that

\[
(1) \leq C \int |\nabla u^\varepsilon|^3 + |\nabla B^\varepsilon|^2 |\nabla u^\varepsilon|
\]
\[
\leq \|\nabla u^\varepsilon\|_3^3 + \|\nabla B^\varepsilon\|_3^2 \|\nabla u^\varepsilon\|_2\]
\[
= C \|\nabla u^\varepsilon\|_3^3 \|\Delta u^\varepsilon\|_2 + \|\nabla B^\varepsilon\|_2 \|\nabla u^\varepsilon\|_2 \|\Delta B^\varepsilon\|_2
\]
\[
\leq C(\|\nabla u^\varepsilon\|_2^2 + \|\nabla B^\varepsilon\|_2^2) \|\nabla u^\varepsilon\|_2^2 + \frac{1}{32} \|\Delta u^\varepsilon\|_2^2 + \frac{1}{32} \|\Delta B^\varepsilon\|_2^2.
\]

(3.21)

Where we have used the Gagliardo-Nirenberg inequality (2.1) first with \( p = 3 \) and then with \( p = 4 \) and Young inequality. Next we estimate the terms (II) and (III) for which we simply use Young inequality,

\[
(II) \leq C \varepsilon \int |\nabla((u^\varepsilon \cdot \nabla) u^\varepsilon)|^2 + \frac{\varepsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2,
\]

(3.22)

\[
(III) \leq C \varepsilon \int |\nabla((B^\varepsilon \cdot \nabla) B^\varepsilon)|^2 + \frac{\varepsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2.
\]

(3.23)

The term (IV) is a little bit troublesome. We split (IV) into two parts, (IV)_1 and (IV)_2. First we consider (IV)_1 defined as follows

\[
(IV)_1 = \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \Delta u^\varepsilon + (u^\varepsilon \times B^\varepsilon) \varepsilon \partial_t \Delta E^\varepsilon
\]

By integrating by parts the second term in (IV)_1 we get

\[
(IV)_1 = \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \partial_k u^\varepsilon - \int (\partial_k u^\varepsilon \times B^\varepsilon) \varepsilon \partial_t \partial_k E^\varepsilon - \int (u^\varepsilon \times \partial_k B^\varepsilon) \varepsilon \partial_t \partial_k E^\varepsilon.
\]

We integrate again by parts only the second term in (IV)_1, then

\[
(IV)_1 = \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \partial_k u^\varepsilon + \int (\partial_k u^\varepsilon \times B^\varepsilon) \varepsilon \partial_t E^\varepsilon
\]
\[
+ \int (\partial_k u^\varepsilon \times \partial_k B^\varepsilon) \varepsilon \partial_t E^\varepsilon - \int (u^\varepsilon \times \partial_k B^\varepsilon) \varepsilon \partial_t \partial_k E^\varepsilon
\]
\[
= \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \partial_k u^\varepsilon - \int (\varepsilon \partial_t E^\varepsilon \times B^\varepsilon) \partial_k u^\varepsilon
\]
\[
+ \int (\partial_k u^\varepsilon \times \partial_k B^\varepsilon) \varepsilon \partial_t E^\varepsilon - \int (u^\varepsilon \times \partial_k B^\varepsilon) \varepsilon \partial_t \partial_k E^\varepsilon
\]
\[
= \int (\partial_k u^\varepsilon \times \partial_k B^\varepsilon) \varepsilon \partial_t E^\varepsilon - \int (u^\varepsilon \times \partial_k B^\varepsilon) \varepsilon \partial_t \partial_k E^\varepsilon
\]
\[
= (IV)_{11} + (IV)_{12},
\]
where standard vector identities have been used in the third line. Let us now estimate the term \((IV)_{11}\). By using Hölder inequality, Gagliardo Nirenberg inequality \((2.41)\) with \(p = 4\) and Young inequality we have

\[
(IV)_{11} \leq \epsilon C \int |\nabla u^\varepsilon| |\nabla B^\varepsilon| |\partial_t E^\varepsilon| \\
\leq \epsilon C \|\nabla u^\varepsilon\|_4 \|\nabla B^\varepsilon\|_4 \|\partial_t E^\varepsilon\|_2 \\
\leq \epsilon \sqrt{\lambda} \|\nabla u^\varepsilon\|_2 \|\nabla B^\varepsilon\|_2 \|\partial_t E^\varepsilon\|_2 + \frac{1}{\sqrt{\lambda}} \|\Delta u^\varepsilon\|_2 \|\Delta B^\varepsilon\|_2 \\
\leq \epsilon \sqrt{\lambda} \|\nabla u^\varepsilon\|_2 \|\nabla B^\varepsilon\|_2 \|\partial_t E^\varepsilon\|_2 + \frac{1}{\sqrt{\lambda}} \|\Delta u^\varepsilon\|_2 \|\Delta B^\varepsilon\|_2 \\
\leq C \sqrt{\lambda} \|\nabla u^\varepsilon\|_2 \|\nabla B^\varepsilon\|_2 \|\partial_t E^\varepsilon\|_2 + \frac{h}{\lambda} \|\Delta u^\varepsilon\|_2 + \frac{1}{h} \|\Delta B^\varepsilon\|_2 \\
\leq C \sqrt{\lambda} \|\nabla u^\varepsilon\|_2 \|\nabla B^\varepsilon\|_2 \|\partial_t E^\varepsilon\|_2 + \|\nabla B^\varepsilon\|_2 + 2\epsilon \delta_\varepsilon \|\nabla B^\varepsilon\|_2 + \frac{4\epsilon^2}{2} \|\partial_t \nabla B^\varepsilon\|_2^2 \\
+ \frac{h}{2\lambda} \|\Delta u^\varepsilon\|_2 + \frac{1}{2\lambda} \|\Delta B^\varepsilon\|_2^2
\]

and we conclude by choosing \(h\) and \(\lambda\) such that

\[
(IV)_{11} \leq C \epsilon^2 \|\partial_t E^\varepsilon\|_2^2 (\|\nabla u^\varepsilon\|_2^2 + \|\nabla B^\varepsilon\|_2^2 + 2\epsilon \delta_\varepsilon \|\nabla B^\varepsilon\|_2^2 + \|\partial_t \nabla B^\varepsilon\|_2^2) \\
+ \frac{1}{32} \|\Delta u^\varepsilon\|_2^2 + \frac{1}{32} \|\Delta B^\varepsilon\|_2^2. \quad (3.24)
\]

Next we estimate the term \((IV)_{12}\), by using again Hölder inequality, Gagliardo Nirenberg inequality \((2.41)\) with \(p = 4\) and Young inequality we have

\[
(IV)_{12} \leq C \epsilon \int |u^\varepsilon| |\nabla B^\varepsilon| |\partial_t \nabla E^\varepsilon| \\
\leq C \|u^\varepsilon\|_2 \|\nabla B^\varepsilon\|_2 \|\partial_t \nabla E^\varepsilon\|_2 + \frac{1}{32} \epsilon^2 \|\partial_t \nabla E^\varepsilon\|_2^2 \\
\leq C \|u^\varepsilon\|_2 \|\nabla u^\varepsilon\|_2 \|\nabla B^\varepsilon\|_2 \|\Delta E^\varepsilon\|_2^2 + \frac{1}{32} \epsilon^2 \|\partial_t \nabla E^\varepsilon\|_2^2 \\
\leq C \|u^\varepsilon\|_2 \|\nabla u^\varepsilon\|_2 \|\nabla B^\varepsilon\|_2 \|\Delta B^\varepsilon\|_2 + \frac{1}{32} \epsilon^2 \|\partial_t \nabla E^\varepsilon\|_2^2. \quad (3.25)
\]

Now, we consider the term \((IV)_2\). Again we integrate by parts to get

\[
(IV)_2 = -\int \epsilon (\partial_t \partial_h E^\varepsilon \times B^\varepsilon) \delta_\varepsilon \partial_t \partial_k u^\varepsilon - \int \epsilon (\partial_h E^\varepsilon \times \partial_k B^\varepsilon) \delta_\varepsilon \partial_k \partial_t u^\varepsilon \\
= (IV)_{21} + (IV)_{22}.
\]

The term \((IV)_{21}\) is estimated by using Hölder and Young inequality as follows,

\[
(IV)_{21} \leq C \epsilon \int |\partial_t \nabla E^\varepsilon| |\nabla B^\varepsilon| |\partial_t u^\varepsilon| \\
\leq C \epsilon \int \epsilon^2 |\partial_t \nabla E^\varepsilon|^2 |\nabla B^\varepsilon|^2 + \frac{\epsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2 \\
\leq C \epsilon \|B^\varepsilon\|_2 \epsilon^2 \|\partial_t \nabla E^\varepsilon\|_2^2 + \frac{\epsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2. \quad (3.26)
\]
Finally, we consider the term \((IV)_{22}\)

\[
(IV)_{22} \leq C\varepsilon^2 \int |\partial_t E^\varepsilon| \|\nabla B^\varepsilon| \|\nabla \partial_t u^\varepsilon| \\
\leq C\varepsilon \int \varepsilon^2 |\partial_t E^\varepsilon|^2 \|\nabla B^\varepsilon| + \frac{\varepsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2 \\
\leq C\varepsilon^3 \|\nabla B^\varepsilon\|_2^2 \|\partial_t E^\varepsilon\|_2^2 + \frac{\varepsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2 \\
\leq C\varepsilon^2 \|\nabla B^\varepsilon\|_2^2 \|\Delta B^\varepsilon\|_2^2 + \frac{\varepsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2 \\
\leq C\varepsilon^2 \|\partial_t E^\varepsilon\|_2^2 \|\nabla B^\varepsilon\|_2^2 \|\Delta B^\varepsilon\|_2^2 \\
+ \frac{\varepsilon}{32} \|\nabla \partial_t u^\varepsilon\|_2^2, \\
\tag{3.27}
\]

where we have used as in the other terms Hölder inequality, Gagliardo Nirenberg inequality \([4,1]\) with \(p = 4\) and Young inequality. By using the estimates \([3.22], [3.24]\) in \([3.21]\) and taking into account the definition of \(E_2(t)\) we get

\[
\frac{d}{dt} E_2(t) + \frac{\varepsilon^2}{4} \|\partial_t \nabla E^\varepsilon\|_2^2 + \frac{1}{4} \|\Delta u^\varepsilon\|_2^2 + \frac{\varepsilon}{4} \|\nabla \partial_t u^\varepsilon\|_2^2 + \frac{1}{4} \|\Delta B^\varepsilon\|_2^2 \\
+ \frac{\varepsilon}{2} \|\partial_t \nabla E^\varepsilon\|_2^2 + \frac{1}{2} \|\Delta u^\varepsilon\|_2^2 + \frac{1}{2} \|\Delta B^\varepsilon\|_2^2 - C\varepsilon \|\partial_t \nabla E^\varepsilon\|_2^2 \\
- \frac{9}{4} \varepsilon \int |\nabla \text{curl}(u^\varepsilon \times B^\varepsilon)|^2 - C\varepsilon \int |(\nabla((u^\varepsilon \cdot \nabla)u^\varepsilon))|^2 \\
- C\varepsilon \int |\nabla((B^\varepsilon \cdot \nabla))| \|B^\varepsilon\|_2^2 \leq C\varepsilon^2 \|\partial_t E^\varepsilon\|_2^2 \|E_2(t)\|_2 \|\nabla B^\varepsilon\|_2^2 \|E_2(t)\|_2 \\
C\varepsilon^2 \|\partial_t E^\varepsilon\|_2^2 \|\nabla B^\varepsilon\|_2^2 \|E_2(t)\|_2 + C(\|\nabla u^\varepsilon\|_2^2 + \|\nabla B^\varepsilon\|_2^2) \|E_2(t)\|_2 \\
\leq C(1 + E_1(t)) D_1(t) E_2(t).
\tag{3.28}
\]

As in the previous Lemma we need to estimate the term with negative sign on the left-hand side of \((3.28)\). By using the Kato inequality \([2,2]\) we have that

\[
\frac{9}{4} \int |\nabla \text{curl}(u^\varepsilon \times B^\varepsilon)|^2 + C \int |(\nabla(\text{div}(u^\varepsilon \otimes u^\varepsilon)))|^2 + C \int |\nabla(\text{div}(B^\varepsilon \otimes B^\varepsilon)))|^2 \\
+ C \|B^\varepsilon\|_2^2 \|\partial_t \nabla E^\varepsilon\|_2^2 \\
\leq C(\|u^\varepsilon\|_{H^4}^2 + \|u^\varepsilon \otimes u^\varepsilon\|_{H^2}^2 + \|B^\varepsilon \cdot B^\varepsilon\|_{H^2}^2 + \|B^\varepsilon\|_{L^\infty}^2 \|\partial_t \nabla E^\varepsilon\|_2^2) \\
\leq C(\|u^\varepsilon\|_{L^\infty}^2 + \|B^\varepsilon\|_{L^\infty}^2)(\|u^\varepsilon\|_{H^2}^2 + \|B^\varepsilon\|_{H^2}^2 + \|\partial_t \nabla E^\varepsilon\|_2^2) \\
\leq C(\|u^\varepsilon\|_{L^\infty}^2 + \|B^\varepsilon\|_{L^\infty}^2) \left(\frac{1}{2} \|\Delta u^\varepsilon\|_2^2 + \frac{1}{2} \|\Delta B^\varepsilon\|_2^2 + \frac{\varepsilon^2}{2} \|\nabla \partial_t E^\varepsilon\|_2^2\right). \\
\tag{3.29}
\]

Then by using \((3.29)\) in \((3.28)\) we get \((3.14)\) with \(C_2 = \sqrt{C_1}\). \(\Box\)
4. Proof of the main theorem

In this section we prove Theorem 1.1. We divide the proof in several steps.

Step 1. Construction on the initial data.

We set \( C_3 = \min\{C_1, C_2\} \). Let \((u_0, B_0)\) in \( H^s(\mathbb{T}^2; \mathbb{R}^2) \times H^s(\mathbb{T}^2; \mathbb{R}^2) \) be the divergence free initial data for (1.1). We need to construct the initial data for the system (1.8). By using a standard regularization argument, see for example [11], we obtain two smooth sequences \( u_\varepsilon^0 \) and \( B_\varepsilon^0 \). Moreover, by choosing \( \varepsilon \) small enough we get

\[
\|u_\varepsilon^0\|_\infty \leq \frac{C_4}{\sqrt{\varepsilon}} \quad \|B_\varepsilon^0\|_\infty \leq \frac{C_4}{\sqrt{\varepsilon}}.
\]

with \( C_4 < C_3 \). Then, we consider \( u_\varepsilon^0 \) and \( B_\varepsilon^0 \) embedded in \( \mathbb{R}^3 \) by setting the third component to zero. The initial datum \( E_\varepsilon^0 \) for the electric field will be constructed in two steps. First we solve

\[
\text{curl } E_0 = -\partial_t B|_{t=0}
\]

endowed with periodic boundary conditions. We again consider \( \partial_t B|_{t=0} \) as a three dimensional vector by setting the third component to zero and the value of \( \partial_t B \) at time \( t = 0 \) is obtained from the second equation of (1.1).

Once (4.1) has been solved we construct \( E_\varepsilon^0 \) by a simple regularization argument.

Step 2. Global in time estimates for \((u^\varepsilon, B^\varepsilon, E^\varepsilon)\).

First of all we prove the uniform \( L^\infty \) bounds for \( u^\varepsilon \) and \( B^\varepsilon \) required in Lemma 3.2 and 3.3. By Theorem 2.3 there exists a unique smooth solution \((u^\varepsilon, B^\varepsilon, E^\varepsilon)\) of (1.8) starting from the initial data we have constructed in Step 1. Let \( \delta < C_3 - C_4 \) and \( T_{\varepsilon, \delta} = \min\{T_{1, \varepsilon, \delta}, T_{2, \varepsilon, \delta}\} \) where \( T_{i, \varepsilon, \delta} \) are defined as follows:

\[
T_{1, \varepsilon, \delta} = \sup \left\{ 0 \leq t \leq T; \sup_{0 \leq \tau \leq t} \|u^\varepsilon(\tau)\|_\infty \leq \frac{C_4 + \delta}{2\sqrt{\varepsilon}} \right\},
\]

\[
T_{2, \varepsilon, \delta} = \sup \left\{ 0 \leq t \leq T; \sup_{0 \leq \tau \leq t} \|B^\varepsilon(\tau)\|_\infty \leq \frac{C_4 + \delta}{2\sqrt{\varepsilon}} \right\}.
\]

We have that \( T_{\varepsilon, \delta} > 0 \) because of the continuity in time with value in \( H^2(\mathbb{T}^2) \) of \( u^\varepsilon \) and \( B^\varepsilon \). We want to show that \( T_{\varepsilon, \delta} = T \). If \( T_{\varepsilon, \delta} < T \), then there exist \( \alpha > 0 \) such that for all \( t < T_{\varepsilon, \delta} + \alpha \)

\[
\|u^\varepsilon\|_\infty + \|B^\varepsilon\|_\infty < \frac{C_3}{\sqrt{\varepsilon}}.
\]

Moreover, by using Lemma 3.2 and Lemma 3.3 we get

\[
\|u^\varepsilon(T_{\varepsilon, \delta}, \cdot)\|_{H^1} + \|B^\varepsilon(T_{\varepsilon, \delta}, \cdot)\|_{H^1} + \sqrt{\varepsilon}\|u^\varepsilon(T_{\varepsilon, \delta}, \cdot)\|_{H^2} + \sqrt{\varepsilon}\|B^\varepsilon(T_{\varepsilon, \delta}, \cdot)\|_{H^2} \leq C_5.
\]
By using the definition of $T^{\varepsilon,\delta}$ and the Brezis-Gallouet inequality [2], we have:

$$\frac{C_4 + \delta}{\sqrt{\varepsilon}} = \|u^\varepsilon(T^{\varepsilon,\delta})\|_\infty + \|B^\varepsilon(T^{\varepsilon,\delta})\|_\infty \leq C\|B^\varepsilon\|_{H^1}(1 + \ln \|u^\varepsilon\|_{H^2}) + C\|u^\varepsilon\|_{H^1}(1 + \ln \|B^\varepsilon\|_{H^2})$$

(4.2)

where $C_6$ depends only on the initial data. Note that $\delta$ is a fixed number depending only on the constants $C_3$ and $C_4$. Then, there exists $\varepsilon$ depending only on the constant $C_6$, such that for any $\varepsilon < \varepsilon$ [4.2] is a contradiction.

So we can conclude that $T^{\varepsilon,\delta} = T$ and so, by applying Lemma 3.2 and the Lemma 3.3, $u^\varepsilon$ and $B^\varepsilon$ are uniformly bounded in $C([0,T); H^1(T^2))$, namely

$$\sup_{t \in [0,T]} (\|u^\varepsilon\|_{H^1} + \|B^\varepsilon\|_{H^1}) \leq C.$$

(4.3)

**Step 3. Passage to the limit.**

We are going to show that $(u^\varepsilon, B^\varepsilon)$ converge to the unique global smooth solutions of (1.1) with initial data (1.2). First, we note that since $T^{\varepsilon,\delta} = T$ there exists $(u^*, B^*) \in C([0,T); H^1(T^2; \mathbb{R}^3))$ such that up to a subsequence the following convergences hold

$$u^\varepsilon \to u^* \text{ weakly}^* \text{ in } C([0,T); H^1(T^2)),$$

$$B^\varepsilon \to B^* \text{ weakly}^* \text{ in } C([0,T); H^1(T^2)).$$

Moreover, by Lemma 3.2 and the global bound in $C([0,T); H^1(T^2; \mathbb{R}^3))$ we have also

$$\varepsilon \int \|\partial_t B^\varepsilon\|_2^2 \leq C.$$

(4.5)

Finally, by using the Gagliardo-Nirenberg inequality, [4.3] and the bound on $j$ in Lemma 3.1 we get easily that

$$\int \|E^\varepsilon\|_2^2 \leq C.$$

(4.6)

Where the constants $C > 0$ are independent on $\varepsilon$. We want to prove that $(u^*, B^*)$ is a weak solution of the system (1.1). Let us multiply the first equations of (3.2) by $\phi \in C_c([0,T); C_0^\infty(T^2))$ with $\text{div } \phi = 0$ and the second equations by $\psi \in C_c([0,T); C_0^\infty(T^2))$. Specifically, from the equation for the velocity we get:

$$\int \int -u^\varepsilon \partial_t \phi + \nabla u^\varepsilon \nabla \phi + ((u^\varepsilon \cdot \nabla)u^\varepsilon \phi) + \int u_0^\varepsilon \phi(x,0) - \int \int \text{curl } B^\varepsilon \times B^\varepsilon \phi = \int \int \varepsilon (\partial_t E^\varepsilon \times B^\varepsilon) \phi,$$

and from the equation for the magnetic field:

$$\int \int -B^\varepsilon \partial_t \psi + \nabla B^\varepsilon \nabla \psi - (u^\varepsilon \times B^\varepsilon) \text{curl } \psi + \int B_0^\varepsilon \psi(x,0) = \int \int \varepsilon \partial_t B^\varepsilon \psi.$$
By using (4.4) and (1.8) we can easily pass to the limit in all the terms of the previous equalities except the terms on the right-hand sides. We want to prove that

$$\varepsilon \int \int \partial_t E^\varepsilon \times B^\varepsilon \phi \to 0 \quad \text{as } \varepsilon \to 0,$$

$$\varepsilon \int \int \partial_t B^\varepsilon \psi \to 0 \quad \text{as } \varepsilon \to 0. \quad (4.7)$$

Let us start with the first term

$$\varepsilon \int \int \partial_t E^\varepsilon \times B^\varepsilon \phi = \varepsilon \int \int \partial_t (E^\varepsilon \times B^\varepsilon) \phi - \varepsilon \int \int E^\varepsilon \times \partial_t B^\varepsilon \phi$$

$$- \varepsilon \int \int (E^\varepsilon \times B^\varepsilon) \partial_t \phi - \varepsilon \int \int E^\varepsilon_0 \times B^\varepsilon_0 \phi(x, 0)$$

$$- \varepsilon \int \int E^\varepsilon \times \partial_t B^\varepsilon \phi.$$

Then by using the estimates (4.6), (4.3) and the uniform bounds on the initial data we get that

$$\varepsilon \left| \int \int \partial_t E^\varepsilon \times B^\varepsilon \phi \right| \to 0 \quad \text{as } \varepsilon \to 0.$$

Concerning the second one we have

$$\varepsilon \int \int \partial_t B^\varepsilon \phi = -\varepsilon \int \int \partial_t B^\varepsilon \partial_t \phi + \varepsilon \int \int \partial_t B^\varepsilon_0 \phi(x, 0)$$

$$= \varepsilon \int \int B^\varepsilon \partial_t \phi - \varepsilon \int \int B^\varepsilon_0 \partial_t \phi(x, 0)$$

$$+ \varepsilon \int \int \partial_t B^\varepsilon_0 \phi(x, 0).$$

Then, by using Lemma 3.1 and the uniform bounds on the initial data

$$\left| \varepsilon \int \int \partial_t B^\varepsilon \phi \right| \to 0 \quad \text{as } \varepsilon \to 0.$$

**Step 4. Identification of the limit.**

The final step of the proof is to prove that \((u^*, B^*)\) are the unique smooth solutions of (1.1)-(1.2). First we prove that \(u^*\) and \(B^*\) have vanishing third component because \(u_0^*\) and \(B_0^*\) are in \(\mathbb{R}^2\). Let \(\tilde{u} = (u_1^*, u_2^*)\) and \(\tilde{B} = (B_1^*, B_2^*)\). Since \(u^*\) and \(B^*\) do not depend on \(x_3\) we have that \(\text{div} \, \tilde{u} = \text{div} \, \tilde{B} = 0\) and the equations for \(u_3^*\) and \(B_3^*\) satisfied in the sense of distributions read as follows

$$\partial_t u_3^* - \Delta u_3^* + \tilde{u} \cdot \nabla u_3^* - \tilde{B} \cdot \nabla B_3^* = 0$$

$$\partial_t B_3^* - \Delta B_3^* + \tilde{u} \cdot \nabla B_3^* - \tilde{B} \cdot \nabla u_3^* = 0 \quad (4.8)$$

Because of (4.4) we can multiply the first equation by \(u_3^*\) and the second by \(B_3^*\). After integrating by parts and adding up we get

$$\frac{d}{dt} \left(\int |u_3^*|^2 + |B_3^*|^2\right) + 2 \int |\nabla u_3^*|^2 + 2 \int |\nabla B_3^*|^2 = 0, \quad (4.9)$$
by Gronwall lemma we have that \( u^*_3 \) and \( B^*_3 \) vanish. Then, \((u^*, B^*)\) are a weak solutions of the Cauchy problem (1.1)-(1.2). By using the uniqueness result of the Theorem 2.2 we get that \((u^*, B^*) = (u, B)\).

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