The STAR Event Plane Detector

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Abstract

The Event Plane Detector (EPD) is an upgrade detector to the STAR experiment at RHIC, designed to measure the pattern of forward-going charged particles emitted in a high-energy collision between heavy nuclei. It consists of two highly-segmented discs of 1.2-cm-thick scintillator embedded with wavelength-shifting fiber, coupled to silicon photomultipliers and custom electronics. We describe the general design of the device, its construction, and performance on the bench and in the experiment.

Keywords: heavy ion collisions, event plane, reaction plane, scintillator

1. Introduction

Collisions between heavy nuclei at high energies produce the quark-gluon plasma (QGP), a new state of matter consisting of deconfined quarks and gluons last seen only microseconds after the Big Bang [1, 2]. Determining the initial geometry of each collision is a crucial step in decoding the complex physics of this novel system [3, 4]. Experimentally, this geometry is quantified in terms of “event planes” (EPs), and there exist well-established methods [5, 6] to extract these planes from patterns in the thousands of particles emitted from each event.

The STAR experiment [7] at Brookhaven National Laboratory’s Relativistic Heavy Ion Collider (RHIC) facility measures these collisions with a coordinated set of tracking, calorimetric, time-of-flight and other detector systems [7]. These components form nearly hermetic coverage of the collision generated when two opposing beams of nuclei collide at the center of the experiment. The Event Plane Detector measures charged particles emitted in the forward and backward directions, at angles 0.7° < θ < 13.5° relative to the initial directions of the beams. (Expressed in pseudorapidity, η = −ln [tan (θ/2)], the detector covers 2.14 < |η| < 5.09.)

The EPD system consists of two wheels, one of which is shown schematically in figure 1 Each of 12 “supersectors” is divided into 31 tiles. Each supersector is connected to a bundle of 31 optical fibers which transport the
Figure 1: A sketch of the EPD system. One of two EPD wheels is shown. The 31 tiles from each of 12 supersectors are connected via optical fiber bundles to silicon photomultipliers and amplification electronics. See text for details.

light from each tile to a silicon photomultiplier (SiPM). Signals from the SiPM are amplified and sent to the STAR digitizing and acquisition system [8]. In what follows, we discuss the design, construction, and bench tests of these components in detail. We then discuss the system’s performance as deployed in the STAR experiment and conclude.

2. Design and Construction

2.1. General Considerations

Materials
Event planes are extracted from the azimuthal patterns of emitted particles, and the species of the particles (protons, pions, etc) is unimportant; therefore, no particle identification capability is required. It is likewise not very important to know whether a detected particle originates directly from the collision vertex, or whether it is a daughter of a particle that decays in flight. Although the trajectories of charged particles are bent by STAR’s 0.5 T magnetic field, our simulations showed that this bending does not significantly affect EP determination. For these reasons, no tracking capability is required, and recording a single hit point for each particle is sufficient.

In addition to EP determination in offline analysis, the detector is used to trigger STAR’s data acquisition system online. This dictated a detector response time on order of nanoseconds.

These modest requirements prompted a design based on plastic scintillator (Eljen EJ-200) planes 1.2 cm thick. Relativistic charged particles passing through such planes produce a signal distribution with identifiable peaks corresponding to 1, 2, 3,... N minimally ionizing particles (MIPs) traversing the plastic simultaneously (though irreducible Landau fluctuations are significant).

This choice implies a relatively small addition to STAR’s material budget (detailed below) and relatively low cost. In addition, scintillator is straightforward to machine with CNC mills at university shops, and amenable to
considerable manual construction by teams of students, providing valuable hardware experience to young members of the field.

**Geometry**

Because event planes are determined by Fourier decomposition of the azimuthal (about the beam direction, henceforth called the longitudinal or $z$ direction) dependence of particle yields [5], it is best and most natural that an EPD have azimuthally symmetric geometry. The spatial positions of other detector systems in STAR dictated that the EPD sit at $z = \pm 3.75$ m, and coverage of pseudorapidity range $2.14 < |\eta| < 5.09$ is scientifically desired. These considerations prompted the chosen geometry of a disc of radius 0.9 m, with an inner hole of radius 4.6 cm. The vacuum pipe (radius 4 cm) carrying the nuclear beams passes through this inner hole. The two beams travel east and west; one EPD wheel is located on the west side of the experiment, and one on the east.

It was decided to construct each wheel from 12 separate wedges, or “supersectors.” This decision was driven by several considerations. In case of a major problem during machining (which occurred with two of the 32 wedges produced), only a limited number of tiles are ruined. Also, the EPD is mounted every year onto STAR using manlifts in a tight spacing with delicate cables and vacuum tubes nearby; larger pieces are more awkward and prone to cause problems. Finally, wedges on order 50 cm × 100 cm fit on standard CNC mills available in university machine shops and are convenient to handle during manual stages of construction.

**Segmentation**

Each disc was segmented into several tiles, each individually read out. Several considerations argued for a small number of large tiles. Naturally, for cost reasons and simplicity, the channel count should be kept as low as possible without degrading detector capabilities below experimental requirements. Furthermore, increasing the number of tiles means decreasing their size. Small tiles are difficult to work on manually, and it is difficult to respect the minimum bending radius of the wavelength shifting fibers used to transport light. Many small tiles also means loss of efficiency in the inevitable dead areas between active tiles.

Scientific performance requirements lead to competing considerations. The resolution with which an EP can be measured is ultimately limited by the physics of the nuclear collision itself; this limit is determined by models and previous measurements. The azimuthal segmentation of the EPD should not be so coarse as to degrade the EP resolution beyond this limit. In these collisions, the azimuthal pattern of particle emission is known to depend strongly on $\eta$, and it is important to measure this dependence. Therefore, sufficient segmentation in the radial direction is required. Finally, due to irreducible Landau fluctuations, it is difficult to distinguish an event in which a single MIP passes through a tile, from one in which multiple MIPs traversed it simultaneously. The impact of multiple-hits on offline analyses and online triggering must be determined from simulation.

Balancing these competing considerations resulted [9] in a segmentation scheme, detailed below, in which each wheel consists of 372 tiles.

### 2.2. Detailed design

Detailed dimensions and locations of the EPD tile with respect to the detector’s position within STAR are tabulated in table 1.

Supersectors were milled from sheets of 1.2 cm thick scintillator (Eljen-EJ200). The machine bit paths are shown in figure 2. Individual tiles are defined by 1.65-mm-wide “isolation grooves” that run the full depth of the scintillator. Within each tile is a rounded groove track 1.6 mm wide and 3.6 mm deep. These “fiber grooves” are filled with a wavelength shifting (WLS) optical fiber (S-type Kuraray Y-11(200)) wound three times around the groove, to optimize light collection then held in place by EJ-500 optical epoxy. Our prototype tests indicated that triple winding of the fibers increases the light output of the detector by a factor of two over a single loop, in rough agreement with previous observations [10].

Light collection of WLS fibers in similar channels has been reported [10] to be significantly better with epoxy, as compared with air coupling. Especially in our case, using a groove with fixed width, epoxy was also crucial to keep the fibers from springing out of the groove. The particular epoxy used (Eljen EJ-500) was extensively tested and found sufficiently radiation-hard for conditions at RHIC [11].

As they exit the grooved track of a tile, the WLS fibers are routed through a “central channel” that runs down the center of the supersector. The central channel increases in width and depth as it approaches the outer edge of the supersector. At this outer edge, the 31 individual fibers are bundled together in a “32-fiber connector” (one channel of which is empty). The connector and fiber bundle that mates to it are described in section 2.4.
Detailed sketch of one supersector, with scales given in cm. The central channel runs vertically in this figure, widening and deepening as it approaches the outer edge, to accommodate more WLS fibers. Straight isolation grooves, running approximately horizontal in this image, separate the tiles optically. Each tile contains a curved track groove near its periphery, into which a WLS fiber is glued. Except for at the tip (the part closest to the nuclear beam), each of the 16 “rows” contains two tiles per supersector. Dividing the tip (row 1) into two tiles would violate the minimum bending radius of the WLS fibers.

Figure 2:

2.3. Construction

Here, we detail the process for constructing a supersector. The scintillator wedge was machined with a CNC mill in two stages, described below. The toolpath included ramping fiber paths and isolation grooves rather deep (6 mm) compared to their width (1.6 mm). A high-strength carbide cutter was run at a high spin rate (8065 RPM) and low feed rate (3 inch/minute). A high flow rate of water and 5% oil was maintained by adding coolant lines to the CNC machine, and little material (30 mil) was removed with each tool pass. These precautions prevented scintillator melting as well as cracking that can result when small fragments get caught between the bit and the grooves. The large scintillator sheets were clamped for many hours during machining, and considerable care and experimentation was required to find a clamping scheme that avoided the micro-cracking which can easily occur with scintillator sheets under compression and vibration.

In the first machining stage, the isolation groove pattern is milled half-way through the 1.2 cm depth of the supersector. These grooves were filled with reflective epoxy (see section 2.5) after first washing the supersector thoroughly with water and gentle detergent (with special attention to clearing and wiping machining fluid from inside each deep groove) and then taping (Ultra-Low-Friction Tape with Teflon PTFE) its edge as a barrier against the epoxy running out of the groove; see figure 3. The supersector was held flat with distributed weights to prevent warping due to contraction of the drying epoxy over 2-3 days.

The supersector is returned to the CNC with its glued side facing the table. (Before clamping it to the table, it was important to carefully scratch away any dried epoxy meniscus that could slightly protrude from the groove and prevent a perfectly flat lie.) The remainder of the isolation grooves, the fiber grooves and ramps, and the central channel are machined in this second step.

After washing off residual machine fluids as before, the next steps are glue-related. Optically-isolating (reflective)
| Row | \( r_i \) (cm) | \( r_f \) (cm) | \( \eta_i \) | \( \eta_f \) |
|-----|----------------|----------------|-------------|-------------|
| 1   | 4.6            | 9.0            | 5.09        | 4.42        |
| 2   | 9.0            | 13.4           | 4.42        | 4.03        |
| 3   | 13.4           | 17.8           | 4.03        | 3.74        |
| 4   | 17.8           | 23.33          | 3.74        | 3.47        |
| 5   | 23.33          | 28.86          | 3.47        | 3.26        |
| 6   | 28.86          | 34.39          | 3.26        | 3.08        |
| 7   | 34.39          | 39.92          | 3.08        | 2.94        |
| 8   | 39.92          | 45.45          | 2.94        | 2.81        |
| 9   | 45.45          | 50.98          | 2.81        | 2.69        |
| 10  | 50.98          | 56.51          | 2.69        | 2.59        |
| 11  | 56.51          | 62.05          | 2.59        | 2.50        |
| 12  | 62.05          | 67.58          | 2.50        | 2.41        |
| 13  | 67.58          | 73.11          | 2.41        | 2.34        |
| 14  | 73.11          | 78.64          | 2.34        | 2.27        |
| 15  | 78.64          | 84.17          | 2.27        | 2.20        |
| 16  | 84.17          | 89.70          | 2.20        | 2.14        |

Table 1: Columns 2 and 3 list minimum and maximum radial distance from the beamline for each row of tiles. Columns 4 and 5 give minimum and maximum pseudorapidity values corresponding to a particle traveling in a straight line from the center of the STAR experiment, 375 cm in the longitudinal direction.

Epoxy and optically-coupling epoxy must be injected in closely-space grooves, and it is very difficult to remove epoxy from a deep groove in scintillator. To avoid contamination, various techniques were improvised which are too specialized for general interest. It is worth noting, however, that the aforementioned PTFE tape was quite useful here, due to its strength and low residue, as well as the fact that no epoxy sticks to it.

The end connector of the WLS fiber bundle (see section 2.4) was epoxied to the edge of the supersector, and the WLS fibers were glued into tile fiber grooves with Eljen EJ-500 optical cement. Once mixed, the cement remains usable for roughly 20 minutes. (The manufacturer cites a 60-minute working time, but injection by needle becomes difficult sooner.) Mixing tends to introduce small, undesirable bubbles that often do not come up quickly. We found it best to mix the cement in very small batches (~10 ml), and immediately degas it under the light vacuum of a roughing pump for up to 30 seconds, before pouring it smoothly into a 10-ml plastic syringe for injection. As discussed in section 2.5, it was important to remove any lubricant from the syringe first.

The WLS fiber groove was half-filled with cement before the fiber itself was slowly laid in, looping three times as mentioned above. This was a two-person job, with one person gently holding down a portion of fiber to keep it from popping out and causing bubbles, as shown in figure 3c. Soft wood or bamboo skewers were used, to avoid damaging the cladding of the fiber.

The cement is left to dry for 36-48 hours, and then the remaining isolation grooves and central channel are filled with reflective epoxy. This is similar to filling the isolation grooves from the first stage, but the volume of epoxy at this stage is much higher, and there is considerably more flow between regions to fill. It turned out best to partially fill the appropriate spaces with the white epoxy, allow to dry for 1-2 days (weighted down for flatness), and then complete the job. Importantly, a WLS fiber is encased in reflective epoxy from the point that it leaves its tile, until it reaches the connector at the outer radius of the supersector. Near the connector, half of the fibers rise above the face of the supersector, so there is something of a 5-mm “mound” of white epoxy in that region.

The sides of the supersector are polished gently with fine sandpaper followed by a damp microfiber rag with 1200-grit 5-micron Al₂O₃ lapping grains, until the sides are clear and smooth; see figure 3d.

Each supersector was finally wrapped in one layer of Tyvek (DuPont 105SB polyethylene fabric 7-mil thick) to increase light collection and two layers of 10-mil-thick black paper to shield from external light. (Directing bright light onto the face of a wrapped supersector will, however, generate some current in the SiPMs. For use in brightly-lit environment, additional wrapping would be needed. In STAR, however, the EPD is shielded from behind by its mounting structure, while the relatively dark other detector components lie ahead.)

[5]
Figure 3: Tape being removed from the edge after the reflective epoxy in the isolation grooves has dried. This is after the first machining stage; later milling and epoxying from the other side will result in complete optical isolation of adjacent tiles. Common dust is visible on the face of the scintillator. Immediately after the second milling stage, a WLS fiber is being cemented into its groove. PTFE tape is used to protect the face of the scintillator and isolation grooves. The sides have been polished with Al₂O₃; one sees the WLS fibers for the smaller tiles.
Mounting tolerances (discussed below) allot only about 1 mm for wrapping material, so the wrapping had to be tight; tight wrapping also prevents optical crosstalk. Even so, some places (e.g. near the connector) were regularly prone to light-leaks, so we began to paint those areas with several coats of reflective paint (Eljen EJ-510), prior to wrapping. Especially near the connector region, extra wrapping and light-shielding was used.

This construction process was relatively straightforward, and 30 supersectors were built with very few problems. One was a WLS fiber that broke while wrapping it into the groove of a tile in row 2. Tiles in row 2 are the smallest, and the circular fiber groove had a 2-cm diameter, much smaller than the 5-cm minimum diameter suggested by the manufacturer. Violating this minimum may lead to breaks or cracks in the fiber; while this occurred only once for the EPD, we would not use such low-radius bends for these fibers next time. Additionally, for these S-type fibers, up to 40% light loss is expected due to bending effects; our offline gain measurements confirm this expectation. Nevertheless, these small tiles— including the one for which the groove could only be partially filled (one-half of one turn) by unbroken WLS fiber— were all usable in practice.

2.4. Fiber bundles

Optical Fiber Connectors

All of the connectors for the EPD were 3D printed using black Polylactic Acid (PLA) plastic by an Ultimaker 2+. This includes the Fiber-to-Fiber Connectors (FFC), Fiber-to-SiPM Connectors (FSC) as well as other necessary pieces such as shields for connectors and a piece that split the clear optical fiber bunch into two sections (c.f. figure 1). After a connector was printed, the holes of the connector had to be drilled out using a drill press as the 3D printer did not have the precision necessary to make holes that would precisely fit the optical fibers. After this, the surface of the connector was polished as described below, as the outermost surface tended to break away easily, and would scratch the fibers during the fiber polishing process. Once this step was completed, the hex nuts were glued into the connectors so that the connecting screws could be used as the plastic was not robust enough to be threaded.

Design and construction of clear fiber bundles

Clear optical fiber bundles were constructed in order to connect the EPD wheel itself to the SiPMs (Hamamatsu S13360-1325PE MPPCs, (1.3 mm)$^2$, 25 µm pixels) that were used to read out the signal. The SiPMs are susceptible to radiation damage, so these were located a distance of 3 meters from the beam pipe, behind the magnet iron. The Wavelength Shifting fibers (WLS) embedded into the scintillator disks had a short attenuation length ($\lambda > 3.5$ m) and so the connection from the disk to the SiPMs was made with clear optical fibers with a longer attenuation length ($\lambda > 10$ m). The total length of the optical fiber assemblies was 5.5 m.

The clear optical fibers were Kuraray Clear-PS 1.15-mm-diameter multi-clad fiber. Each assembly had 31 optical fibers, which matched the distribution of wavelength shifting fibers in a given super-sector. The fibers were cut, inspected for cracks, and then stretched out into a laminar bundle, which was then wrapped in Tyvek in order to reduce friction, and slid into the protective UV-Resistant Versilon PVC Opaque Tubing. The main section of the tubing was 1/2” in inner diameter, 3/4” in outer diameter and 4.8-m long. First the fibers were fed through a fiber-to-connector piece, and then gently pushed into 31 holes of the fiber to fiber connector (FFC) piece. The assembly was glued together with Structural Adhesive (Slow-Set Epoxy, 3M 2158 by Scotch-Weld), which included shields that protected the connection between the FTC and FFC. The construction of the connector pieces is described in the connector section above.

The opposite side of the assembly would be split into a group of 15 and 16 fibers, as the read-out was done per half supersector. A 3D printed splitter was slid down the fibers and connected to the protective tubing via a hose clamp, checking their mapping using an LED light. Each section of fiber was then encased in a tube the same PVC material as the main body of the fiber with an inner diameter of 3/8” and an outer diameter of 1/2”. The fibers were fanned into a fiber-to-connector piece, then fibers were carefully routed into two 16 fiber to SiPM connectors (FSC). This was done by selecting a fiber using an LED light from the FFC end and then sliding it into the appropriate FSC channel. Once this was completed, each assembly was glued together with the epoxy. The design of this assembly an can be seen in figure 4. After the epoxy dried, the excess fiber was cut and all three ends of the fiber assembly were polished as described below.

Design and construction of WLS fiber bundles

The WLS fibers were constructed with Kurary Y-11(200) 1 mm-diameter fiber, which we have referred to as WLS fiber. Each fiber in the WLS bundle had to be a different length, in order to correspond to the geometry of the tile that
they were glued into. The length of the fiber within the central channel of the super sector was painted in reflective paint (Eljen EJ-510), which was also different for each set of tiles. It was found that the best method was to cut, then paint the fibers prior to the construction of the assembly. Each fiber was fed into the appropriate hole of the FFC fiber connector and then epoxied in. After the epoxy dried, the excess fiber on the connector end was trimmed and then the fibers were polished. On the far end the fibers were individually polished and the very end was painted in reflective paint.

**Polishing**

The optical coupling between the WLS and clear fiber connectors was extremely important, so the fiber assemblies were polished to improve the optical coupling. All polishing work was done with a flat glass plate underneath the polishing materials in order to insure flatness. First the connector and fiber assemblies were polished with 2500 grit paper. Once the largest features on the fibers were removed, we then used diamond lapping sheets, moving down through 30, 6, 3, and 1 µm grit sizes. At each stage, the fibers were inspected using a microscope.

**Testing and Final Assembly**

Each assembly (both clear and WLS) was tested by shining light via an LED through the assembly, and then measuring transmission through the assembly using a photodiode. Both the single fiber transmission and the average transmission over the entire assembly were examined.

The SiPM boards were designed to remain part of the clear fiber bundle assembly. A 3D spacer was designed in order to protect the SiPMs, this and the SiPM board were attached to the FSC ends of the fiber bundles as can be seen in the left and middle pictures in figure 4. The SiPM board then would connect to the Front End Electronics (FEE) board via an edge connector, which can be seen in the right of figure 4.

**2.5. Reflective Epoxy**

The success of this detector relies on the reflective consistency and strength of the isolating reflective epoxy. The procedure to produce, store, and use the epoxy was based largely on the detailed discussion by Olsson, *et al.* However, that manuscript is difficult to find in print, and was accompanied by passed-down clarification. Therefore, we hope it is useful to archive our procedure here.

We used D.E.R. 332 epoxy resin with Jeffamine D230 curing agent and TiO$_2$ powder (44 micron). For the mixing, we used a small ball mill with a thick glass 500 ml jar.

Insert 100 mg of resin into the jar together with 8-10 mixing balls (1/2′′ diameter); we found it important to use stainless steel balls to avoid discoloration of the white epoxy. Warm in a lab oven at 62°C for 3 hours, then remove and add 50 g of TiO$_2$ powder.

Tightly seal the jar and spin (our mill spun at 40 rpm, though Olsson suggests 20 rpm) on the ball mill for 3 hours. Remove from the mill, loosen the lid, and place jar back in the 62°C oven for 2 hours. Tighten the lid and repeat mixing on the ball mill for 3 hours, then once more loosen the lid and place in the oven for 2 hours.

Remove the jar from the oven, add 32 g of Jeffamine, and mix in the ball mill for 2-3 minutes. Portion the epoxy directly into syringes. The filled syringes should be used immediately or flash-frozen in liquid nitrogen and transferred...
to a freezer (about 20°C) for later use. These syringes may be re-warmed in the 62°C oven (∼15 minutes or until the epoxy flows) for up to several weeks afterward.

We used inexpensive 10 ml plastic syringes with a silicone rubber piston stop. We found that some batches of the syringes had a small amount of lubricant in the plunger which could slightly discolor the epoxy or optical cement. This is easily avoided by simply removing the plunger and wiping the stop before returning it and filling.

The reflecting epoxy was injected by hand through stainless steel dispensing needles (1’’ 21-gauge) coupled to the syringe by luer lock. Great care was taken to avoid air bubbles in the isolation grooves. Ten ml of warm epoxy flows smoothly through the needles; warming mid-way through use was sometimes helpful.

2.6. Mounting structure and material budget

Mounting the EPD in the STAR experiment is nontrivial, and several considerations went into its design. The experiment is fairly bristling with detector systems, and there is limited space outside of the nominal volume of the wheels themselves; see figure 5. Mounting infrastructure must allow close detector packing. Consideration must be given to installation procedures on manlifts in restricted areas near the beampipe; it must be manageable and the mounting position reproducible. Furthermore, it is important to keep the material budget down, as there are detectors (and future upgrade detectors) “downstream” of the EPD.

The mounting scheme is seen in figure 5. Each support assembly consists of six adjacent sextants milled from 3/8 inch-thick fiberglass-reinforced epoxy laminate sheets, FR-4. This material is stiff enough to support two supersectors
in each sextant, and the resin binder in FR-4 is especially flame resistant. Supersectors are placed in recesses milled into the front of the support structure and held in place with C-shaped brackets along the edges that use screws to pin the supersector in position and tabs along the center spoke of each sextant. The design is secure but introduces negligible mass between the EPD and the collision vertex.

Each sextant mounts on two of six mounting studs on the STAR magnet pole tip, as seen in figure 5c. The inner tips of the EPD come within 5 mm of the beampipe, as seen in figure 5d, and to minimize material in front of detectors further downstream, the support structure ends about 10 cm from the supersector tip.

Contribution to STAR's mass budget
The scintillator (polyvinyltoluene) has a radiation length of 42.54 cm [13] and the G10 of the support structure has a radiation length of 19.4 cm [14]. The scintillator is 1.2 cm thick. The depression of the support structure which holds the scintillator is 0.45 cm. Outside of this depression the support structure is 0.95 cm thick. Thus particles passing through the scintillator pass through 0.051 radiation lengths and particles passing outside of the scintillator pass through 0.049 radiation lengths.

3. Tests and Performance

Here, we describe bench tests performed in the lab, in parallel with construction, and performance of the system as deployed in the STAR experiment.

3.1. Bench tests of completed supersectors

Two bench tests were performed on each tile.

Cosmic ray test stand
Four supersectors were aligned in a compact vertical stack, between pairs of paddle scintillators read out by photomultiplier tubes and fed into a leading-edge discriminator. The noise rate in each paddle detector was on order 2 kHz, and the pulse width on order 10 ns, so a coincidence between them is a clean trigger for cosmic rays. Using external trigger detectors with areas on order 200 cm$^2$, we were able to simultaneously test about 20-28 tiles (5-7 tiles from each of the four supersectors) in a ∼ 10-hour-long run.

Spectra for four vertically-aligned tiles obtained in the test stand are shown in figure 6. Spectra were measured with LeCroy 2249A ADCs. The trigger detectors covered a range of tiles, so for a given stack of tiles, a signal above threshold in the top and bottom tiles (from supersectors 8 and 7, in this figure) was identified as a “vertical ray event.” Spectra from vertical rays were fitted with roughly the expected shape (Landau distribution) for reference.

The test stand system was relatively noisy and statistics were limited. These tests were intended mostly to flag gross problems and identified about 4 or 5 problem tiles, usually exhibiting low light efficiency; only two of the 930 tiles examined were deemed unacceptable for use.

Higher-statistics spectra are discussed in section 3.2.

Detector uniformity and isolation scan
The EPD is, to first order, a “hit detector,” and the fine segmentation means that regions of scintillator on order 20 cm$^2$ (tiles) are separately gain-equalized. Therefore, unlike scintillator sheets in an electromagnetic calorimeter [15] for example, uniformity of response as a function of position is not a big concern. Nevertheless, we performed extensive tests to measure the position dependence of the EPD response using a narrow beam of $\beta^−$ radiation from a 200-$\mu$Ci$^{90}$Sr source.

The source was mounted on the platform of a $x − y$ translation table driven by computer-controlled stepper motors. The platform could travel 80 cm in each direction. A supersector was held above the table with its face about 3 cm from the source, and the dark current of the biased SiPM was read out.

An automated program drove the source to a specified spot beneath the supersector, read out the dark current of all 31 SiPMs, 10 times, and recorded the average. It then drove the source to a position away from the supersector, read out all 31 channels 10 times, and recorded the average; in this way, the baseline current, which could in principle vary with time, could be subtracted. This procedure was repeated for a grid of points on the surface of the supersector. Grid spacing varied from about 5 mm to about 2 cm, and full scans ran for about 12 hours. We scanned most supersectors, at least coarsely.
Spectra (in ADC units) from the cosmic ray test stand. A coincidence between large external scintillator paddles triggered the CAMAC acquisition system. Above-threshold signals in the top (here, supersector 8) and bottom (supersector 7) tiles indicated a roughly vertical cosmic ray through tile 8. Landau fits are drawn for reference.

Representative results are shown in figure 7a. Each panel in figure 7a represents the increase in (i.e. background-subtracted, as discussed above) dark current of a single SiPM as a function of position of the $^{90}$Sr source. Uniformity of response over the face of a tile was very good in the radial direction and typically better than 25% in the direction perpendicular to radial, perfectly acceptable for our purposes.

The degree of optical isolation from light induced in a neighboring tile was excellent. Figure 7b shows the response of four adjacent tiles, as the source is moved along a line in the radial direction. The transition from one tile to the next takes place within about 1 cm, which is also about the size of the spot illuminated by the $^{90}$Sr source. Therefore, the level of true light signal “crosstalk” across these tiles is negligible. In figure 7c the source is moved across the face of tile 8 into tile 9, along a path perpendicular to their mutual border. Again, the isolation is excellent; any optical crosstalk is below the sensitivity of this technique. This figure also highlights the $\sim 20\%$ non-uniformity of response in this direction, typical of most tiles.

Crosstalk on the level of $\sim 5\%$ was observed between two tiles in two supersectors; this is believed to be the result of a drop of optical cement coupling a small length of WLS fiber exiting one tile onto the edge of a neighbor. This level of crosstalk has negligible impact on EP determination, as the signals are still associated with similar azimuthal angle.
(a) Response of tiles 5, 6, 7 and 9 in one supersector, as a function of source position. Colors indicate dark current increase in μA.

(b) Signals in radially adjacent tiles, as the $^{90}$Sr source scans in the radial direction.

(c) Signals from tiles 8 and 9, as the $^{90}$Sr source is moved in a path perpendicular to the central channel.

Figure 7: Detector response (dark current increase) as a function of position of a $^{90}$Sr source. See text for details.
3.2. Performance in STAR

The full Event Plane Detector was first installed and run in STAR during the 2018 RHIC campaign, with all 744 tiles performing well throughout the campaign. It was also installed for the 2019 campaign, in which it functioned equally well.

The silicon photomultipliers operate with a nominal bias voltage of 68 V. However, by changing the bias by $\pm 1$ V, the effective gain may be adjusted within about a factor of four, without losing linearity of response. We individually adjusted the bias voltage of each SiPM at the start of the campaign, so that the digitized energy loss peak for all tiles is found at the same ADC (analog-to-digital converter) value. Further fine time-dependent adjustments can be performed in offline analysis, but there is little need, as the hardware gains were quite stable over the several-month-long campaign.

Figure 8 illustrates the excellent uniformity of response of the EPD. Panel 8a shows the raw ADC spectra from 24 tiles in ring 4 (c.f. table 1). While no scaling of yields or gain adjustment (beyond initial bias voltage adjustments, discussed above) were performed, the spectra are nearly identical. The shaded regions represent calculations of the spectra when one (grey), two (red), three (green) or four (blue) particles pass through a tile simultaneously. The 1-, 2-,... N-particle distributions overlap considerably, so that for a given collision, the number of particles passing through a tile may only be probabilistically determined.

The amount of this overlap is driven by the width of the shaded regions. The one-particle contribution is a simple Landau distribution whose width is about 14-20% of the most probable value (MPV). This is consistent with irreducible physical energy loss fluctuations expected for a scintillator of this thickness [16, 17]. This indicates that broadening due to finite photoelectron statistics in the SiPM is not significant; our light-collection efficiency was more than adequate for our purposes. Landau fluctuations also dominate electronics noise effects. On the bench, the front-end amplifiers were verified [18] to have single-photoelectron resolution, and the overall effective noise in the STAR environment was equivalent to about 2 photoelectrons.

The EPD was utilized as a trigger detector starting in 2019. This required that the detector have a reasonable timing resolution, which can be seen in figure 9. The STAR Time Projection Chamber (TPC) [19] can precisely determine the collision vertex. We can compare this collision vertex to a determination by the EPD to find the timing difference can then be calculated at the spatial difference divided by the speed of light, which yields a timing resolution of 0.39 ns.

\[^2\]It is important to note that the calculated multiple-particle contributions are simply convolutions of the one-particle Landau distribution– their peak positions and widths are not independent parameters.
The red curve indicates the difference between the TPC vertex location and a similar quantity determined by the EPD, using the tile with fastest signal. The difference of 25.9 cm corresponds to a timing resolution of 0.89 ns. The blue curve uses the average time of the east versus west EPD, which improves the resolution to 0.39 ns.

Figure 9:

As discussed in section 1, the EPD was primarily built to determine the event planes of each collision. Therefore, without delving into the physics or analysis details, it is appropriate to conclude with an EP-related performance measure. The so-called second-order event plane angle for particles emitted to the west ($p_z > 0$) is the plane in which the majority of the signal lies:

$$
\Psi_{2,\text{West}} \equiv \frac{1}{2} \tan^{-1} \left( \frac{\sum_{i=1}^{372} w_i \cdot \sin(2\phi_i)}{\sum_{i=1}^{372} w_i \cdot \cos(2\phi_i)} \right),
$$

(1)

where the sum runs over all tiles on the west wheel, and $\phi_i$ is the azimuthal angle of the tile. In the simplest analysis, the ADC value for a given tile may be used as its weight, $w_i$, though alternate weighting schemes are often employed.

Figure 10 shows the correlation between the west EP angle defined in equation 1 and the east EP angle defined similarly. There is clearly a strong correlation between the momentum anisotropy in regions separated by many units of pseudorapidity, indicating a “global” anisotropy in the initial collision geometry. The strength of the correlation is a measure of the resolution $R_{\text{EP}}$ with which the “true” event plane is measured by the detector [5]. The EPD was built to replace STAR’s original event-plane detector in this $\eta$ region, the Beam-Beam Counter (BBC). Depending on the beam energy, event plane type, and other details, the EPD delivers $\sim 1.5 \rightarrow 2.5$ the first-order plane resolution of the BBC. The statistical uncertainty of an EP-dependent physics observable $X$ typically scales as $\delta X \sim N^{-1/2} \cdot R_{\text{EP}}^{-1}$, where $N$ represents a statistically relevant number (number of events, number of particles, etc). Hence, for EP-dependent studies, a two-fold increase in EP resolution is equivalent to a four-fold increase in event statistics.

4. Summary

A new upgrade detector has been constructed and deployed in the STAR experiment at RHIC. The Event Plane Detector provides STAR with significantly improved resolution for measuring the initial geometry of a heavy ion collision, a crucial element step for decoding the complex physics of the system’s evolution.

The design and construction of the EPD has been discussed in detail. The construction was carried out in university labs and machine shop by teams including many students and postdocs, providing valuable training in a field sometimes dominated by computer-based data analysis. Cosmic-ray tests of nearly 1,000 tiles indicated very few problems with light collection, and scanning at the centimeter scale with a radioactive source indicates excellent optical isolation of tiles and good uniformity of response.

The EPD has performed solidly in two RHIC campaigns thus far, with all channels functional. The single- and multiple-hit resolution is as expected for a scintillator of this thickness, and the uniformity of response is excellent. In
The event-plane angles measured in high-energy nuclear collisions with the east and west EPD wheels show a clear correlation. See text for details.

addition to quantitative improvements in event-plane-related measurements, the improvement in event plane resolution may have qualitative implications. Measurement of a subtle effect that would have previously required a twelve-month campaign (impractically long at RHIC) may be performed in just three months (a long run, but feasible) with the EPD upgrade.

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