The Importance of Silicon Detectors for the Higgs Boson Discovery and the Study of its Properties

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Recent studies are presented demonstrating the important role played by silicon detectors in the discovery of the Higgs boson. CMS is planning to replace its silicon detectors in an extended technical stop of the LHC in the winter of 2016. We present results showing that this replacement will significantly increase the sample of Higgs bosons that will be reconstructed enabling precision studies of this particle.

Keywords: Higgs; Silicon; Pixel Detectors.

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1. Introduction

In 2012 the ATLAS and CMS experiments announced to the world the discovery of a new boson\textsuperscript{1}. Both collaborations have continued to measure the properties of the new particle using the whole data sample delivered by the LHC during its first run (run1). In this run the CMS experiment collected $pp$ collision data corresponding to an integrated luminosity of about 5.1 $fb^{-1}$ and 19.7 $fb^{-1}$ at the center-of-mass energy of $\sqrt{s} = 7$ and 8 TeV respectively. A similar amount of data was collected by ATLAS. The data have already allowed precision measurements of the Higgs Boson mass. Spin-parity studies favour the scalar, $J^P = 0^+$ hypothesis\textsuperscript{2}. Furthermore the production and decay properties of the new particle appear to be consistent with those expected of the SM Higgs boson\textsuperscript{3}. In this review we focus on the importance of silicon sensors in this discovery and the need to replace them to maintain the performance needed to allow precision measurements in the challenging environment of the LHC hadron collider.

The LHC is currently undergoing a shutdown that began on 14 February 2013. Repairs are ongoing to consolidate the high-current splices and allow the machine to run very closely to the design energy of 14 TeV. In addition the luminosity will increase from the record of $7 \times 10^{34} cm^{-2}s^{-1}$ achieved in run1 to over $1 \times$
In this paper we describe the importance of silicon detectors in this discovery. We first briefly discuss the CMS detector and especially its pixel detector. We then summarise the status of studies of the Higgs boson using two pairs of same-flavor, opposite-charge, well-identified and isolated leptons, $e^+e^-$ and $\mu^+\mu^-$, compatible $H \rightarrow ZZ$, where one or both the $Z$ bosons can be off-shell. Finally, we discuss the challenges that the higher LHC luminosity brings and describe the impact of the replacement of the current pixel detector on the Higgs physics program, focusing as an example on the $H \rightarrow ZZ \rightarrow 4\ell$ channel.

2. CMS

CMS, which is described in detail in [3], is one of the two multipurpose experiments at the LHC. It is 21.6 m long, 15 m in diameter, and weighs about 12,500 t. The apparatus is characterised by a very large superconducting solenoid of 6m internal diameter, providing a 3.8 T magnetic field. The CMS inner tracker consists of silicon pixel and strip detectors. The inner tracker, lead tungstate crystal electromagnetic calorimeter (ECAL), and brass/scintillator hadron calorimeter (HCAL) are all located inside the solenoid magnet. Muons are detected in gas-ionization detectors embedded in the iron flux return placed outside the solenoid. Extensive forward calorimetry complements the coverage provided by the barrel and endcap detectors. The experiment uses a coordinate system with the origin at the nominal interaction point, the $x$ axis pointing to the center of the LHC ring, the $y$ axis pointing up with repeat to the LHC ring, and the $z$ axis along the beam direction using a right-handed convention. The polar angle $\theta$ is measured from $z$ axis and the azimuthal angle $\phi$ is measured in the $x$–$y$ plane. The pseudorapidity is defined as $\eta = -\ln[\tan(\theta/2)]$.

The inner tracker measures charged particle trajectories within the range $|\eta| < 2.5$. It consists of 1440 silicon pixel modules arranged into 3 barrel layers and 2 endcap disks on each side. The silicon tracker includes 10 barrel layers and a total of 10 end caps disks instrumented with 15148 modules. It provides an impact parameter resolution of 15 $\mu$m and a transverse momentum ($p_T$) resolution of about 1.5% for 100 GeV particles. The ECAL contains 75848 lead tungstate crystals and provides coverage of $|\eta| < 1.479$ in the barrel region (EB), and 1.479 < $|\eta| < 3.0$ in the two endcap regions (EE). A preshower detector consisting of two planes of silicon sensors interleaved with a total of 3 radiation lengths of lead is located in front of the EE. The ECAL energy resolution for electrons with transverse energy $E_T > 45$ GeV from the $Z \rightarrow e^+e^-$ decays is better than 2% in the central region of the EB ($|\eta| < 0.8$), and is between 2% and 5% elsewhere. For low-bremsstrahlung electrons that have 94% or more of their energy contained within a $3 \times 3$ array of crystals, the energy resolution improves to 0.5% for $|\eta| < 0.8$. The HCAL is a sampling calorimeter with brass as the passive material and plastic scintillator tiles serving as active material, providing coverage of $|\eta| < 2.9$. A hadron forward

$10^{34} \text{cm}^{-2} \text{s}^{-1}$. 

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calorimeter extends the coverage up to $|\eta| < 5.2$. Muons are detected in the pseudo-rapidity range $|\eta| < 2.4$, with detection planes made using three technologies: drift tubes, cathode strip chambers, and resistive-plate chambers. The global fit of the muon tracks matched to the tracks reconstructed in the silicon tracker results in an average transverse momentum resolution that varies between 1.8% at $p_T = 30$ GeV to 2.3% at $p_T = 50$ GeV.

2.1. The CMS pixel detector and its impact on tracking

With about 66 million $100\mu m \times 150\mu m$ detector elements, the pixel system is a crucial component of the all-silicon CMS inner tracker\cite{8} playing a critical role in tracking, vertex reconstruction, and the High Level Trigger (HLT). It was designed to record with high efficiency and precision the first three space-points near the interaction region in operating conditions up to the nominal instantaneous luminosity of $1 \times 10^{34} cm^{-2}s^{-1}$ and 25 ns colliding bunch spacing. Under these conditions, an average of about 25 simultaneous overlapping events, or pile up, are expected per bunch crossing. Track reconstruction in such a high-occupancy environment is challenging since it is difficult to obtain a high track-finding efficiency, while keeping the fraction of fake tracks small. Fake tracks are tracks that may be formed from a combination of unrelated hits or from a particle trajectory that is badly reconstructed through the inclusion of spurious hits. The detector performance during run 1 of the LHC was extremely robust and it was able to handle the record luminosity of $7 \times 10^{33} cm^{-2}s^{-1}$ and 50 ns bunch crossing that lead to a higher than expected average pile up of 37.

The pixel detector consists of cylindrical barrel layers at radii of 4.4, 7.3 and 10.2 cm, and two pairs of endcap disks at $z = 34.5$ and 46.5 cm. Its 1440 modules cover an area of about 1 m$^2$ and have 66 million pixels. The pixel system performs zero-suppression in the readout chips of the sensors, through a pixel threshold corresponding to an equivalent charge of about 3200 electrons. Offline, pixel clusters are formed from adjacent pixels and must have a minimum charge equivalent to 4000 electrons while a minimum ionizing particle deposits usually around 21000 electrons. A fast hit reconstruction algorithm is used during track seeding and pattern recognition. A more precise algorithm, based on cluster shapes templates that can take into account the deterioration due to radiation exposure\cite{9} is used in the final track fit.

The pixel efficiency is determined from the fraction of tracks which has a hit found within 500 $\mu m$ of the predicted position of the track in the layer under study. The efficiency measured using isolated tracks originating from the primary vertex with $p_T > 1$ GeV is $> 99\%$, as shown in Fig.\cite{1} In this measurement we have excluded the 2.4% of the pixel modules known to be defective. We have also required the tracks to be reconstructed with a minimum of 11 hits in the strip detector and to have no additional trajectories within 5 mm to reduce the effects due to high track density. The module hit efficiency has been found to decrease as function of
the instantaneous luminosity, as shown in the right plot of Fig. 1. This is caused by a dynamic inefficiency which increases with hit rate and originates from limitations in the buffering of the readout chip. Therefore the pixel modules in the innermost layer of the BPIX, layer 1 are the most affected.

The resolution of the pixel detector is measured in the middle barrel layer by comparing the predicted position with the measured hit for tracks with $p_T > 12$ GeV, which are not affected by multiple scattering in the other layers. The resolution of the transverse coordinate is around 9.4 $\mu$m. The resolution in the longitudinal, which depends on the angle of the track relative to the sensor and the amount of charge sharing, varies between 29 and 40 $\mu$m.

The tracking software at CMS, referred to as the Combinatorial Track Finder (CTF), is based on the Kalman filter and allows both pattern recognition and track fitting. The seed generation starts in the pixel detectors which have a low fraction of hits per channel (0.002 - 0.02%) due to their high granularity. In addition the pixel detector offers a 3-D space point facilitating track finding and reconstruction. Once the seeds are selected, the CFT starts estimating the track parameters provided by the trajectory seed, and then builds track candidates by adding hits from successive detector layers, and updating the fit parameters at each layer. The CFT uses the location and uncertainty of the detected hits. In addition the amount of material crossed allows to estimate the effects of multiple Coulomb scattering and energy loss. Finally, the track trajectory is refitted using a Kalman filter from the inside outwards. The average track-reconstruction efficiency is 94% in the barrel region ($|\eta| < 0.9$) of the tracker and 85% at higher pseudorapidity. Most of the inefficiency
is caused by hadrons undergoing nuclear interactions in the tracker material. The track fake rate is reduced by requiring a minimum number of layers that have hits, a good $\chi^2$/degrees of freedom in the fit, and compatibility with the primary interaction vertex.

The primary-vertex reconstruction determines the location of all proton-proton interaction vertices in an event. The resolution in jet-enriched samples approaches $10 \, \mu m$ in $x$ and $12 \, \mu m$ in $z$ for primary vertices using at least 50 tracks.

CMS has also developed tracks and primary vertices reconstruction based solely on pixel hits which is used for for the High Level Trigger (HLT) that processes events at rates of up to 100 kHz. The pixel only algorithms are extremely fast, because they use only three layers and they take advantage of the low occupancy and high 3-D spatial resolution of the pixel detector. The maximum efficiency for the pixel tracks is 85%.

3. The $H \rightarrow 4$ leptons studies

$H \rightarrow ZZ \rightarrow 4\ell$ was the golden channel for the Higgs discovery in 2012. Since this final state is fully reconstructed and well measured, it continues to be critical to the detailed study of the properties of the Higgs boson. The branching fraction of the $H \rightarrow ZZ \rightarrow 4\ell$ is of $O(10^{-4})$ for $m_H = 125$ GeV. Therefore it is important to maintain a high lepton selection efficiency over a range of momenta, to maximise the sensitivity for a Higgs boson of 125 GeV. In particular identification of low $p_T$ electrons and muon is critical since the lowest momentum lepton in this decay has $p_T$ well below 20 GeV, as shown in the left plot of Fig. 2 for the $4\mu$ final state. CMS has been able to identify muons and electrons with momentum above 7 and 5 GeV respectively. In addition since the signal appears as a narrow resonance on top of a smooth background it is important to reach the best possible four-lepton mass resolution. Several techniques have been deployed to calibrate the lepton momentum scale and resolution to a level such that the systematic uncertainty in the measured value of $m_H$ is far below the statistical uncertainty. The CMS particle flow (PF) algorithm, which combines information from all sub-detectors, is used to reconstruct jets, missing transverse energy, and to determine lepton isolation observables.

The electron identification is optimised using a multivariate discriminant that combines observables sensitive to the bremsstrahlung along the electron trajectory, the momentum-energy matching between the electron trajectory and the associated supercluster, as well as ECAL-shape observables. The selection is divided in six regions of the electron $p_T$ and $|\eta|$ due to the different performance. The calibration of the energy response is performed using a regression technique trained on a simulated dielectron sample with the pileup conditions matching the ones measured on data. This improves the resolution of the reconstructed invariant mass by 30% for $H \rightarrow ZZ \rightarrow 4e$. The precision of the electron momentum measurement is dominated by the ECAL and the tracker at high energies and low $p_T$ respectively. The magnitude
of the electron momentum is determined by combining the two estimates with a multivariate regression function that takes as input the corrected ECAL energy from the supercluster regression, the track momentum estimate, their respective uncertainties, the ratio of the corrected ECAL energy over the track momentum as obtained from the track fit, the uncertainty in this ratio, and the electron category, based on the amount of bremsstrahlung. The absolute electron momentum scale is calibrated using known resonances in data such as the \(J/\psi\), \(\Upsilon(nS)\), and \(Z\). The relative momentum scale between data and simulation is consistent within 0.2% in the central barrel and up to 0.3% in the end cap.

Muon candidates are required to have a transverse momentum \(p_T > 5\) GeV and \(|\eta| < 2.4\). The reconstruction of the so called global muons combines information from both the silicon tracker and the muon system. To maximise the acceptance of low \(p_T\) muons that may not penetrate the entire muon system tracker muons are accepted. These are tracks that are tracks with matching hits in the muon chambers. The \(p_T\) resolution for muons varies between 1.3 to 2.0% in the barrel, and up to 6% in the endcaps due to multiple scattering of muons in the tracker material. The momentum scale and resolution for muons is studied using different resonances over different \(p_T\) ranges. The agreement between the observed and simulated mass scales is within 0.1% for \(|\eta| < 2.4\).

Lepton isolation is required to discriminate leptons from the Higgs boson decay from leptons produced in hadronic processes which are usually part of jets. Leptons from in-flight decays of hadrons and muons from cosmic rays are suppressed by requiring that leptons are originating from the same primary vertex.

At least one of the four-lepton candidates must have \(p_T > 20\) GeV and another one is required to have \(p_T > 10\) GeV. The first \(Z\), denoted as \(Z_1\), is selected by choosing the opposite-charge lepton pairs in the event with an invariant mass closer to the \(Z\) mass and in the range \(40 < m_{Z_1} < 120\) GeV. Photons from final state radiation (FSR) are taken into account forming the \(Z\)-boson candidate if their inclusion makes the lepton pair mass closer to the nominal \(Z\)-boson mass. The remaining leptons are considered for the second \(Z\) pair, \(Z_2\), if their invariant mass is \(12 < m_{Z_2} < 120\) GeV. We also require the four selected leptons to have \(m_{\ell_1\ell_2} > 4\) GeV to reduce the contribution of lepton from hadronic decays. The detection efficiencies, including geometrical acceptance, for a Higgs boson with \(m_H = 126\) GeV are about 20\%, 29\%, and 42\% for the \(4\ell, 2\ell 2\mu,\) and \(4\mu\) channels respectively. The resolution of the Gaussian core of the mass distribution, estimated from simulated signal samples with a double-sided Crystal-Ball function fit, is about 2.0, 1.6, 1.2 GeV for the \(4\ell, 2\ell 2\mu,\) and \(4\mu\) respectively. The uncertainty in the four-lepton mass is estimated on a per-event basis using sum in quadrature of the individual mass uncertainty contributions from each lepton and any identified FSR photon candidate due to their momentum uncertainty.

The production of Higgs boson through the Vector Boson Fusion mechanism can be be distinguished from gluon fusion, which is about one order of magnitude larger, by requiring two high momentum jets at high \(\eta\) and with large large separation \(\Delta\eta\).
These two jets are the remnants of the incoming proton beams. Therefore the 4 lepton events are separated in events with zero or one jets and events with two jets. A linear discriminant which uses $\Delta \eta$ and the invariant mass of the two leading jets ($m_{jj}$) is used to distinguished gluon fusion from VBF events.

The expected yield and shape of the irreducible $ZZ$ background is evaluated by simulation using GG2ZZ\textsuperscript{11} for the $gg \rightarrow ZZ$ contribution and POWHEG\textsuperscript{12} $q\bar{q} \rightarrow ZZ$. The Next-to-Leading Order (NLO) cross section for $q\bar{q} \rightarrow ZZ$ production and the Leading Order (LO) cross section for $gg \rightarrow ZZ$ production are calculated with MCFM\textsuperscript{13}. The reducible background due to $Z +$ jets, $t\bar{t}$, and $WZ +$ jets are determined from data using two different methods. One of the methods estimates the background using same-sign leptons, the other uses opposite sign leptons passing relaxed identification requirements when compared to those used in the analysis.

The reconstructed four-lepton invariant mass distribution for the combined $4e, 2e2\mu$, and $4\mu$ channels shown in the right plot of Fig. 2 displays a peak around 126 GeV over the expectations from background processes.

![Fig. 2. Left: Momentum distribution of the 4 leptons in the $H \rightarrow ZZ \rightarrow 4\mu$ final state. Right: Distribution of the four-lepton reconstructed mass for the sum of the $4e, 2e2\mu$, and $4\mu$ channels. Points with error bars represent the data, shaded histograms represent the backgrounds, and the unshaded histogram represents the signal expectation for a mass hypothesis of $m_H = 126$ GeV. Signal and the $ZZ$ background are normalized to the SM expectation; the $Z + X$ background to the estimation from data.g.]

The 4$\ell$ final state is extremely powerful since the invariant masses of the lepton pairs, $m_{Z_1}$ and $m_{Z_2}$ and all five angles ($\Omega = \Theta^*, \phi_1, \theta_1, \phi_2, \Phi$) defined in Fig. 3 can be measured offering the possibility to probe in detail the properties of the Higgs boson including its spin-parity. Currently we do not have enough data to probe directly the tensor structure of the Higgs boson decay. Nonetheless we are able to build discriminants to compare the probability for the signal spin-parity hypothesis ($0^+$)
with respect to alternate $J^P$ hypothesis. The Higgs boson signal and background yields and the properties of the Higgs boson such as its mass and width, and the spin-parity quantum numbers, are determined with unbinned maximum-likelihood fits performed to the selected events. The fits include probability density functions for five signal components (gluon fusion, VBF, WH, ZH and ttH production modes) and three background processes ($q\bar{q} \rightarrow ZZ$, $gg \rightarrow ZZ$ and $Z + X$). The probability distribution of the of the angular and mass observables ($\Omega, m_{Z_1}, m_{Z_2}$) and the $m_{4\ell}$ distribution are used to enhance the signal to background discrimination. The normalization of these components and systematic uncertainties are introduced in the fits as nuisance parameters, assuming log-normal a priori probability distributions, and are profiled during the minimization. The shapes of the probability density functions for the event observables are also varied within alternative ones, according to the effect induced by experimental or theoretical systematic uncertainties.

Several discriminant are built and optimised according to specific result to be extracted. Kinematic discriminants denoted as $D_{skg}^{{\text{kin}}}$ and $D_{JP}^{{\text{JP}}}$ are defined based on the event probabilities depending on the background and the signal spin-parity ($J^P$) hypotheses under consideration respectively. The distribution of the kinematic discriminant versus the four-lepton reconstructed mass $m_{4\ell}$ in the low-mass region is shown in Fig. 4. A signal-like clustering of events stands out at high values of
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$D_{bkg}^{\text{kin}}$ and for $m_{4\ell}$ around 126 GeV. The signal significance, and the measurement of the Higgs boson signal strength, $\mu = \sigma / \sigma_{\text{SM}}$, defined as the measured cross section times branching fraction into $ZZ$, relative to the expectation for the SM Higgs boson, is measured using 3D likelihood functions which include the $m_{4\ell}$, $D_{bkg}^{\text{kin}}$, and $p_{T}^{4\ell}$ separately for 0/1 jets and 2 jets events. Using the full run 1 data set we find a local significance of 6.8$\sigma$, consistent with the expected sensitivity of 6.7 $\sigma$ at a mass of $m_{4\ell} = 125.7$ GeV. The mass is measured using a 3D likelihood function with the per-event mass uncertainty. The mass is obtained through profile scan of the 3D likelihood function versus the SM boson mass performed under the assumption that its width is much smaller than the detector resolution. The combination of the 7 and 8 TeV data yields $m_{H} = 125.6 \pm 0.4(\text{stat.}) \pm 0.2(\text{syst.})$ GeV. The systematic uncertainties account for the effect on the mass scale of the lepton momentum scale and resolution, shape systematics in the $P(D_{bkg}^{\text{kin}}, m_{4\ell})$ probability density functions, signal and background modelling, and normalization systematics due to acceptance and efficiency uncertainties. Other measurements using 2D and 1D likelihood scan provide consistent results.

![Distribution of the kinematic discriminant $P(D_{bkg}^{\text{kin}})$ versus the four-lepton reconstructed mass $m_{4\ell}$](image1.png)

![Distribution of the test statistic for the SM pseudoscalar boson hypothesis (yellow) tested against the alternative $0^+$ hypothesis (blue). The arrow indicates the observed value](image2.png)

The spin-parity hypothesis tests, are performed with 2D-likelihood functions based on $D_{bkg}$ and $D^{J\Pi}$. Several alternative spin-parity model have been tested by forming the ratio of signal plus background likelihoods for two signal hypotheses $q = -2 \ln (L_{J\Pi} / L_{0^+})$. The expected distribution of $q$ for the pseudoscalar hypothesis (blue histogram) and the SM Higgs boson (orange histogram) are shown in Fig.
Similar distributions for the test statistic $q$ are obtained for other alternative hypotheses. The pseudo-experiments are generated using the nuisance parameters fitted in data. The pseudoscalar ($0^-$) and all spin-one hypotheses tested are excluded at the 99.9% or higher CL. All tested spin two models are excluded at the 95% or higher CL. The $0^+$ hypothesis is consistent with the data.

4. The Phase1 pixel upgrade

Three long shutdowns, designated as LS1, LS2, and LS3 will be used to increase the luminosity of the LHC. In LS1, which is currently underway, the centre of mass energy will reach almost 14 TeV. In the period through LS2 (2018), the injector chain will be upgraded to deliver brighter bunches into the LHC. In LS3 ($\approx$ 2022), the LHC itself will be upgraded with new low-$\beta$ triplets and crab-cavities to optimise the bunch overlap at the interaction region. We expect that the machine will deliver $1 \times 10^{34} \text{cm}^{-2}\text{s}^{-1}$ soon after LS1. Furthermore it is anticipated that the peak luminosity will be close to $2 \times 10^{34} \text{cm}^{-2}\text{s}^{-1}$ before LS2, and perhaps significantly higher after LS2. Currently the machine plan is to operate at 25 ns after LS1, but further 50 ns operation is not excluded. Therefore CMS must be prepared to operate for the rest of this decade with average pile up of 50 as a baseline. The performance of the current pixel detector will degrade in these conditions. For example, the hit efficiency will worsen due to limits in the internal readout chip buffers and single event upsets. At the nominal L1A accept rate of 100 kHz, the data loss will increase to 16% in the innermost layer as the luminosity goes up by a factor of two (for 25 ns bunch crossing) to $2 \times 10^{34} \text{cm}^{-2}\text{s}^{-1}$.

The tracking efficiency of the current pixel detector is excellent, but slowly degrades as the number of pile up events increases until it reaches a pile up of 40 when it begins to rapidly degrade due to filling buffers on the readout chip. There is also a noticeable dip in the efficiency in the pseudorapidity region near $|\eta| = 1.5$ where the bulkhead with the BPIX services overlap with FPIX. The impact of material is also noticeable in the deterioration of momentum resolution of tracks that pass through the BPIX cooling pipes.

CMS is planning to replace the current pixel detector in an extended technical stop between 2016 and 2017. The design specification of the new pixel detector [15] denoted as Phase 1 pixel detector, is that it should achieve at $2 \times 10^{34} \text{cm}^{-2}\text{s}^{-1}$ the same or better performance that the current pixel detector reaches at low luminosities of Run1. The upgrade detector will reuse some of the current infrastructure and adopt DC-DC power converters and higher bandwidth electronics. The production and maintenance of the Phase 1 detector will be simpler since both barrel and forward pixel use only a module type with 16 readout chip organised in a $2 \times 8$ layout. A new smaller diameter beam pipe has been recently installed to allow the placement of the inner pixel layer closer to the interaction region. A new pixel readout chip (ROC) [16] has been designed to minimize data loss due to latencies and limited buffering in high luminosity running. The column drain speed and the buffer depth
for both the data (hits) and time stamp attached to the data will be increased. The size of the buffers has been optimised with detailed data flow simulations in the ROC. The new ROC has 24 time stamp buffer cells (12 for the present ROC) and 80 data buffer cells (32 for the present ROC). The data loss due to buffer overflows at fluences up to 600 MPix/sec/cm$^2$ is less than 0.5%. In addition the digital readout removes the need for the complex decoding of a multilevel analog signal. The power distribution system in the ROC has changed substantially and several signals have been rerouted and better shielded. These changes lead to a decrease in absolute threshold from the current 2800 down to 2000 electrons. The new ROC has already undergone a couple of submission and the preliminary testing results are very positive.

![Fig. 5. The amount of material in the pixel detector shown in units of radiation length (left), and in units of nuclear interaction length (right) as a function of $\eta$; this is given for the current pixel detector (green histogram), and the Phase 1 upgrade detector (black points). The shaded region at high $\eta$ is outside the region for track reconstruction.](image)

The Phase 1 pixel detector with four pixel-hit coverage over the $\eta$ range and a innermost layer at smaller radius improves pattern recognition and track reconstruction. The addition of the fourth barrel layer at a radius of 16 cm also yields some safety margin in case the first silicon strip layer of the Tracker Inner Barrel (TIB) degrades more rapidly than expected. It also provides the necessary redundancy in pattern recognition and contributes to reducing fake rates in high pile up environment. The material in the tracking region has been significantly reduced by adopting two-phase CO$_2$ cooling, light-weight mechanical support, and by moving the electronic boards and connections out of the tracking volume. These improvements lead to a reduction in the radiation length and nuclear interaction length of the present and upgrade pixel detectors as a function of $\eta$ as shown in Fig. 5.

5. Impact of the Phase 1 pixel detector on Higgs physics

The improvement that the new pixel detector brings are higher efficiencies, lower fake rates, lower dead-time and data-loss, and an extended lifetime of the detector.
The expected tracking efficiency and fake rate of the upgraded pixel detector for several pileup scenarios in simulated \( \bar{t}t \) events are shown in Fig. 6.

![Graph](image)

**Fig. 6.** Average tracking efficiency (left) and average track fake rate (right) for the \( \bar{t}t \) sample as a function of the average pileup. Results were determined using the expected ROC data loss expected for each given average pileup, and for the current pixel detector (blue squares) and for the upgrade pixel detector (red dots).

The Phase 1 detector performance remains excellent at high luminosity. This translates in higher efficiency and lower fake rates for the reconstruction of \( b \)-tagged jets which will have an impact on the measurement of \( H \rightarrow b\bar{b} \). It is also impressive the impact that the new detector has on \( H \rightarrow ZZ \) with \( Z \rightarrow \mu^+\mu^- \) and \( Z \rightarrow e^+e^- \). To evaluate the Physics impact on the latter we have used similar techniques to the one develop for the Higgs discovery paper and therefore the analysis is optimised for a Higgs boson in the mass range \( 110 < m_H < 160 \) GeV produced in proton-proton collision at a center-of-mass energies of 7-8 TeV. The analysis has not yet been optimised to the collision environment expect in run 2 where the LHC will provide a higher center-of-mass energy of 14 TeV and larger pile up. As a benchmark, we have used similar selections as described in and have used a Higgs boson MC sample with \( m_H = 125 \) GeV. The analysis relies on the reconstruction and identification of leptons well isolated from other particles in the event. The Monte Carlo event were generated for the current pixel detector and for the upgrade detector at an average pileup of 50.

The Phase-1 pixel detector significantly improves the impact parameter (IP) measurement of the individual leptons, with respect to the current detector. This improves the vertex assignment and the vertex reconstruction itself. The former is crucial for this analysis, since leptons are required to originate from the primary vertex. This constraint is set by requiring the impact parameter (IP) to be least than 4 times it error. The new detector reduces the RMS on IP by 50%. In addition the tracking improvements due the Phase 1 pixel detector increase the number of leptons passing all the selection requirements. In a large fraction of the events, the number of selected leptons increases to four. The introduction of the Phase 1 Pixel
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Detector, with respect to the current detector scenario, lead to an important gain in signal efficiency. The efficiency ratios, for every step of the analysis, are shown by the cut flow charts in Fig. 7 for the $H \rightarrow 2\mu 2\epsilon$ channel. The efficiency for this channel increases by 48%. One obtains similar gains for $r H \rightarrow 4\mu$ and $H \rightarrow 4\epsilon$ for which we observe improvements in the selection efficiency varying from 41% to 51% respectively.

6. Conclusions

The discovery of the Higgs boson has opened a new chapter in particle physics. The LHC experiments will continue to study the properties of the new particle and determine if this particle couples to new physics. The increase luminosity the LHC during Run 2 brings many challenges. The CMS collaboration has designed an upgraded pixel detector that should perform in this environment as well or better than the current detector does at lower luminosities. The improvements that the new detector brings to Higgs physics are substantial and will have a significant impact on the future CMS physics program.

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