Using Soft Constraints To Learn Semantic Models Of Descriptions Of Shapes

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Abstract—The contribution of this paper is to provide a semantic model (using soft constraints) of the words used by web-users to describe objects in a language game; a game in which one user describes a selected object of those composing the scene (see figure 1), and another user has to guess which object has been described. The given description needs to be non ambiguous and accurate enough to allow other users to guess the described shape correctly.

To build these semantic models the descriptions need to be analyzed to extract the syntax and words’ classes used (see [1] for details). We have modeled the meaning of these descriptions using soft constraints as a way for grounding the meaning.

The descriptions generated by the system look into account the context of the object to avoid ambiguous descriptions, and allowed users to guess the described object correctly 72% of the times.

I. INTRODUCTION

Language can be seen as a system learnt and used by humans for communicating and learning, which covers a wide range of their daily activities. It is a social phenomenon resulting in an evolving system of great complexity. Language is inextricably linked to human capability to converse, learn, reason and make decisions in an environment of imprecision, uncertainty and lack of information. It is viewed here as a complex reality to be represented step by step, in an incremental fashion.

In that respect, the most relevant feature of language is its “meaning” (its “use” according to Wittgenstein [2]), and that does not only include the meaning/use of isolated words, but also the meaning/use of expressions as a whole. In general, the meaning/use of the words integrating an expression is only grasped in relation with the other words and within the meaning/use of the expression as a whole in a context [3].

This work is part of an ongoing project called Smart-Bees. Smart-Bees is a project which aims to study how machines can learn and communicate in human-like ways, from a Computing with Words, Actions and Perceptions (CW-AP) perspective [4], [5]. Users share a common environment and play different “language-games”, in this case they share a blackboard with geometric shapes of different colors, sizes and positions, and play guessing and describing games. In the describing game, given an image with one selected object that users try to describe the selected object to other users in a non-ambiguous way (see figure 1). In the guessing game, on the contrary, given a description and an image users try to guess which object was described.

This project has its roots in Wittgenstein’s ideas about Meaning and Language [2], [6], Zadeh’s ideas on Linguistic Variables, Computing with Words and Generalized Constraints [7], [8], [9], [10], [11], Trillas’ ideas on Words and Fuzzy Sets [12], [13], Roy’s ideas on meaning grounding [14], [15], [16], [17], [18], and Guadarrama’s works on Computing with Words, Actions and Perceptions [4], [19], [20].

To learn semantic models from descriptions of shapes given by users several steps are needed; to collect descriptions of shapes from web-users; to learn the lexicon and syntax used in that descriptions; to link that lexicon and syntax with the features of the shapes to learn the semantics; to generate new descriptions using the syntax and semantic learned; to test them with web-users. The final goal is to learn concepts, words and some sort of syntax and semantics, building a model grounded in the shared perceptions.

Fig. 1
THE GREEN CIRCLE IN THE FRONT

The contribution of this paper is to provide a semantic model (using soft constraints) of the words used by web-users to describe objects in a language game; a game in which one user describes the selected object among those composing the scene, and another user has to guess which object has been described (see figure 1). The given description needs to be non ambiguous and accurate enough to allow other users to guess the described object correctly.

So far the system has 40 registered users, from 15 different countries, who had provided 360 descriptions using 150
different words and had allowed the system to learn some lexicon (30 words), some syntax (20 patterns), and some semantics (7 word’s classes grounded) for the shape description task. The method proposed in this paper is performing quite well obtaining 100% correct spelled words, 88% syntactically correct sentences and 72% of semantically correct sentences; however users spelled on average correctly 97% of the words, wrote 93% of syntactically correct sentences and provided 75% of semantically correct sentences.

The rest of the paper is structured as follows. In Section II we describe related works and compare them with this one. In Section III we present our model of the meaning of words based on soft constraints, in Section IV we present the learning algorithm to learn the soft constraints from the data, and in Section V we present how the new descriptions are generated. Finally Section VI presents the main results and Section VII the main conclusions of the paper.

II. RELATED WORKS

The experiment presented here has been inspired in the DESCRIBER system done by Roy in [15], where he presented a similar problem of learning the descriptions provided by one user about an scene composed by non-overlapping squares and rectangles. Nevertheless we have turned the experiment more realistic in several aspects: allowing different users to provide descriptions (web-users not familiar with the experiment), including more kind of shapes (triangles, circles, ovals) and allowing them to overlap (making harder the segmentation and the descriptions). Also it is important to remark that in the previous experiment the only user was a native English speaker, who provided very consistent descriptions, without spelling or syntactical errors and very few ambiguous descriptions, while in own experiment we have a variety of users from 15 different countries with only few being non-English native speakers.

In that case the system they proposed was using bi-grams for the syntax learning and Gaussian mixtures for the semantic learning, obtaining a 81.3% of correct descriptions. But they have only one user who spelled correctly 100% of the words, wrote 100% of syntactically correct sentences and was able to provide 89% of semantically correct sentences, in comparison with our case that we start with 40 users from 15 different countries who on average spelled correctly 97% of the words, wrote 93% of syntactically correct sentences, and were able to provide only 75% of semantically correct sentences.

The problem of learning grounded words has been studied in [15], [16], [17], [21], [22], the problem of social learning have been studied in [23], [24]. The need to extend Fuzzy Logic to cope with the problems of CW-AP has been recently remarked in [4], [25], [26], [27], [28].

These previous works may be contrasted with this one in two aspects. First, we see language learning as an integrated process where sensory-action learning, social learning and supervised learning are interleaved and combined. Second, we start from a multi-user perspective, where different users and agents interact and share their knowledge.

The main difference of our approach with respect to other published works is the path taken, that is, the movement from manipulation of measurements to manipulation of perceptions, and from syntax-based systems to semantics-based systems. Other approaches underestimate the importance of imprecision inherent in language [29] and in perception [30] and have tried to reduce it to simple forms of uncertainty, instead of dealing with it through a general theory of uncertainty [11].

III. SEMANTIC MODELS OF WORDS USING SOFT CONSTRAINTS

The meaning of a word is its use in language, and therefore it is context-dependent. Actually, words are grounded in actions and perceptions, and its use is learnt in a semi-supervised environment. Let us summarize the main problems that have been faced in this work:

- There are several misspelled words, some rare-words, that need to be corrected or discarded.
- Different users use different words, different syntactic patterns and in some cases with different meanings.
- The same object can be described in many different ways, depending on the context and on the intention of the user.
- Descriptions made should be understandable by other users, so it should be truthful, precise, context-relevant and non-ambiguous.
- There are few examples for each word, and not all the possible combinations are seen.
- Semi-supervised problem, only a small part of the data can be supervised.

To collect human descriptions of shapes and to test the results, we have set up an interactive website. The system learns from the descriptions provided by humans and use the method described in this paper to produce its own descriptions.

https://www3.softcomputing.es/smart-bees

These are some examples of simple descriptions given by users: “the green rectangle”, “big green triangle”, “brown rectangle”. And these are examples of compound descriptions: “light green rectangle at the bottom”, “pink circle behind dark green square”, “the shape under the green one”, “light blue circle in the middle”, “orange circle behind the yellow circle”, “green small square in the background”, “the dark orange rectangle behind the triangle”.

In this paper we will focus on the semantic learning, once the lexicon and syntax have been learnt (see paper [11] also presented in this conference), and on the generation of new descriptions and their validation. Using the results from [11] we transformed the original problem of pairs of descriptions and shapes into a problem of sets of pairs of words and shapes. In which each set represents a class of words extracted by the syntax.

Thus, each shape will be associated with all the words used in the description, and therefore it will have multiple
labels attached. Given a set of words’ classes associated with a set of objects, we need to learn when each word of the class is used based on the features of the shapes (see section IV). This problem is similar to a multiple labeling problem, in which for each object and each words’ class we need to decide which labels are applicable and to which degree.

Given a set of pairs of words (taken as labels) and shapes (taken as objects) we need to learn why, when and how each label is used according to the features of the shapes, to the relations between shapes and to the grammatical rules. To calculate the degree of matching between a description and a selected object in a scene is very important, since it will be used later to calculate the degree of ambiguity, by comparing it with the matching degrees between the description and the other shapes forming the scene.

A. Modeling the Meaning of Propositions

As Zadeh suggested in [26] and in [31] every proposition can be represented by a generalized constraint.

\[ \text{“p” } \Rightarrow \text{X is } R \]

Where \( X \) is a relevant variable constrained by \( R \).

Example

“John is Tall” \( \Rightarrow \) Height(John) is Tall

Where Height(John) is a projection of some attributes of John. And Tall is a constraint on the values of the attributes of John.

B. Modeling the Meaning of Descriptions

In our case, given a description of an object ‘\( x \)’ it can be represented by a set of constraints. For example:

- “The blue square”
  \( \text{Color}(x) \) is \textit{Blue} and \( \text{Shape}(x) \) is \textit{Square}

- “The big dark green triangle in the background”
  \( \text{Color}(x) \) is \textit{Dark Green} and \( \text{Shape}(x) \) is \textit{Triangle} and \( \text{Position}(x) \) is \textit{Background}

Where \textit{Color}, \textit{Shape} and \textit{Position} are projections of the features of \( x \), and \textit{Blue}, \textit{Square}, \textit{Dark Green}, \textit{Triangle}, \textit{Background} are constraints on the values of the projected features.

Thus from the descriptions provided by the users and their corresponding images, the system learns which projections are associated with which words, and which constraints represent their meaning.

C. Learning process

The general phases of the learning process are listed bellow:

- Learning the Lexicon: in this phase it is needed to select relevant words and filter misspelled words (it is presented in [II])
- Learning the Syntax: in this phase it is required to group words according to their role in the sentence, and learn a grammar (it is presented in [II], and briefly shown in [III-D]).
- Segmentation of images to extract objects and features, and pair the segmented objects with descriptions (this is presented in section IV-A).
- Learning the Semantics: Generate a model for each word belonging to the cluster in the projected space according to the features selected (this phase is presented in section IV).
- Generation sentences: in this phase syntactically and semantically correct sentences are generated for new images (this phase is presented in section V).
- Evaluation of results: Once all the sentences are generated an evaluation process is performed, in which the users try to understand the sentences and select the corresponding object (this phase is presented in section VI).

Let us recall the results of the lexical and syntax learning phases from the paper [II]. Words with frequency smaller than 10 have been filtered, and remained 30 words which after clustering formed 7 words’ classes (shown in III-D), and generated a syntax composed by 20 patterns shown in table I.

D. Classes of words

Class 1 = \{ THE, A \}
Class 2 = \{ BACKGROUND, FRONT \}
Class 3 = \{ CIRCLE, OVAL, TRIANGLE, RECTANGLE, ELLIPSE, SQUARE \}
Class 4 = \{ ON, IN, AT, BEHIND \}
Class 5 = \{ LIGHT, BIG, DARK \}
Class 6 = \{ TOP, BOTTOM, RIGHT, LEFT \}
Class 7 = \{ PINK, BLUE, GREEN, ORANGE, RED, YELLOW, PURPLE, VIOLET, BROWN \}

| Frequency | Pattern |
|-----------|---------|
| 18.89%    | 7 3     |
| 6.94%     | 1 7 3   |
| 6.39%     | 1 3     |
| 5.83%     | 3       |
| 3.89%     | 7 3 4 1 2|
| 3.33%     | 5 7 3   |
| 3.06%     | 2 7 3   |
| 2.50%     | 1 7 3 4 1 6|
| 2.22%     | 7 3 4 1 6|
| 1.66%     | 7       |
| 1.11%     | 6 3     |
| 1.11%     | 1 7 3 1 7 3|
| 0.83%     | 1 7     |
| 0.83%     | 1 5 7 3 |
| 0.83%     | 2 5 7 3 |
| 0.83%     | 3 4 1 2 |
| 0.83%     | 3 4 1 6 |
| 0.83%     | 7 3 4 1 3|
| 0.83%     | 1 3 4 1 6 6|
| 0.83%     | 5 7 3 4 1 2|

Table I

Most frequent patterns
IV. LEARNING THE SEMANTICS

The system needs to learn why those specific words were used to describe that object in that context (image). For that we analyzed images to segment and extract objects and measure their features. We used a scaffolding learning: starting from simple descriptions before learning compound descriptions; of the 360 descriptions with all their words in the lexicon, 75% are simple and 25% are compound.

Words belonging to the same class have different meanings; for example given a class of words = {'BLUE', 'RED', 'GREEN', 'YELLOW'...} we assume that each word have a different meaning, and therefore should be represented by different model, even though, in some cases different words can be applied to the same object to some extent.

A. Shapes’ segmentation

A fuzzy edge detector was used to find the edges of the shapes, then using a filling transformation to found the regions inside the edges, and finally using a color-based clustering and an overlapping detection we grouped the regions into shapes. After obtaining a set of candidate shapes – comprised by a set of pixels – they were matched with the selected object and its corresponding description.

For each shape a set of 20 features were measured, including:

- Average RGB: Red, Green, Blue.
- Average YCbCr: Y is the luma component, and Cb and Cr are the blue-difference and red-difference chroma components.
- Bounding Box: Coordinates of the bounding box.
- Height and width.
- Center of gravity: position of the center of gravity.
- Bounding Ellipse: Orientation and size of the bounding ellipse.
- Major Minor: length of the major and minor axis of the bounding ellipse.
- Extension: proportion of the bounding box filled.
- Height to width ratio.
- Area: number of pixels.
- Holes: proportion of holes in the object.
- ...

B. Multi-classification problem

It is important to notice that different users describe differently the same objects, even they used different words and different syntax. So the training data could contain different labels for the same object or no label at all. Some objects have only labels for some of the word’s classes but nor for all; for example “The blue square” only specify that the color is blue and the shape is square but say nothing about the size or position of the object described.

There are also many objects that have not being described by any user, so we also have many un-labeled objects.

The system learn which projection (relevant features) is appropriate for each class of words and which constraints (relevant values) are associated with each word. For every class of words we assume that one projection is shared by all the words in the class. For every word in a class we assume that it is represented by one constraint over the projection of the class.

To obtain a robust classifier in despite of the aforementioned problems we have decided to use fuzzy decision trees for their robustness and flexibility. And also because they also do feature selection during the learning process.

C. Fuzzy decision Trees

A different set of features could be relevant for each class of words. So we used fuzzy decision trees [32] to classify the objects according to their labels and cross validation to prune the tree and select the most relevant features. In figure 2 can be seen the fuzzy decision tree of Class 2.

The features selected for each class are the following:

| Class  | Features         |
|--------|------------------|
| Class 1| –                |
| Class 2| Holes Minor      |
| Class 3| Ext HW-ratio     |
| Class 4| –                |
| Class 5| G                |
| Class 6| X Area           |
| Class 7| Cr Cb            |

From the features selected we can see that none is related to Class 1 nor to Class 3, that means that from the current features their meaning remains unground (or unlearned). This is due to the fact that those classes are more related to the syntax that to the semantics, nevertheless the fuzzy decision tree learns that the most frequent word should be used by default.

The decision trees for each class are the following:

- Class 1: If true then ‘THE’
- Class 2: See figure 2
- Class 3: See figure 3
- Class 4: If true then ‘IN’
- Class 5: If \( g \leq 0.64 \) then ‘LIGHT’ else ‘DARK’
- Class 6: See figure 4
- Class 7: See figure 5
D. Fuzzy Labels

Once the fuzzy decision trees are built for each word’s class we can calculate the degree of matching between every object and every word obtaining a soft constraint for each label. For example in the case of class 7 (colors) and class 3 (shapes) we obtain the fuzzy labels plotted in figures 6 and 7 respectively.

E. Degree of matching of descriptions

The degree of matching between one description and one object depends on the degree of matching of each word composing the description and on an aggregation function (in our case the minimum).

Once the projections (relevant features) and the soft constraints (fuzzy labels) have been learnt for each word’s class we can transform every description into generalized constraints using the syntax, as follows:

\[
\mu_M(x, D) = \bigcap \mu_{\text{label}_i}(x) ; \forall \text{ label}_i \in \text{pattern}(D)
\]

where \text{pattern}(D) is the sequence of labels of a given description, and \( \mu_{\text{label}_i} \) is the fuzzy label representing each word of the description.
F. Degree of ambiguity

The degree of ambiguity of one description in one scene depends on the degrees of matching between the description and the objects of the scene. Because if there are more than one object with high degree of matching then the description could refer to various objects and be ambiguous.

In every scene there are several objects, and any given description can be ambiguous if it is applicable to several of these objects. We can calculate the degree of ambiguity $\sigma_A$ of a description $D$ in an scene $S$ by:

$$\sigma_A(D, x, S) = \sup_{y \neq x, y \in S} \mu_M(y, D)$$

where $x$ is the object with highest degree of matching and $\mu_M(y, D)$ represents the degree of matching between the description $D$ and the other objects $y \neq x$ present in the scene. Thus the higher the degree of matching with the other objects the higher the degree of ambiguity, because the description would not be discriminative enough.

V. Generating descriptions

For generating descriptions the system will look for short, truthful and non-ambiguous descriptions, and will follow the next algorithm:

1) Given an scene with one selected object.
2) Segment it, extract the objects and their features.
3) Get the most frequent short syntax pattern.
4) For each word’s class find the label with the highest degree of matching.
5) Build the description and calculate the degree of ambiguity.
6) If the description is non-ambiguous return the description with the highest degree of matching; else go to step 5 and look for the next pattern and repeat the process.

For example, in the scene seen in figure 8 the system segment it and found 7 objects with their 20 features, starting by most frequent short pattern (1 3 7) it calculates the degree of matching for each label in Class 1, Class 3 and in Class 7; it finds that **The** $\in$ **Class1**, **Rectangle** $\in$ **Class3** and **Red** $\in$ **Class7** have the highest degree of matching

$$\mu_M(x, D) = \min(\mu_{\text{The}}(x), \mu_{\text{Red}}(x), \mu_{\text{Rectangle}}(x))$$

$$\mu_M(x, D) = \min(1, 0.68, 0.74) = 0.68$$

$$\sigma_A(D, x, S) = \sup_{y \neq x, y \in S} \mu_M(y, D)) = 0.11$$

Nevertheless, in the scene seen in figure 1 when the system calculates the degree of matching starting by most frequent short pattern (1 3 7) it finds out that the degree of ambiguity is high.

$$\mu_M(x, D) = \min(\mu_{\text{Green}}(x), \mu_{\text{Circle}}(x))$$

$$\mu_M(x, D) = \min(1, 0.78, 0.57) = 0.57$$

$$\sigma_A(D, x, S) = \sup_{y \neq x, y \in S} \mu_M(y, D)) = 0.53$$

But it turns out that the ambiguity degree is also high, thus the system keep trying with other patterns until it finds one with lower degree of ambiguity (1 3 7 4 1 2) while maintaining a high degree of matching, in this case:

$$\mu_M(x, D) = \min(\mu_{\text{Green}}(x), \mu_{\text{Circle}}(x), \mu_{\text{Front}}(x))$$

$$\mu_M(x, D) = \min(1, 0.78, 0.57, 1, 1, 0.61) = 0.57$$

$$\sigma_A(D, x, S) = \sup_{y \neq x, y \in S} \mu_M(y, D)) = 0.07$$

VI. Results

To compare this work with the previous one [15] and to check the influence of the different options considered in the paper we have defined three methods:

- **Method 1:** In this case we used the algorithm and features proposed in this paper but without using the degree of ambiguity to avoid ambiguous descriptions.
- **Method 2:** In this case we used the algorithm and features proposed by Roy in his paper [15].
- **Method 3:** In this case we used the algorithm and features proposed in this paper and used the degree of ambiguity to avoid ambiguous descriptions.

For the scene shown in figure 1 the descriptions generated by the three methods are:

- **Method 1:** **GREEN CIRCLE**
- **Method 2:** **THE LIGHT GREEN CIRCLE**
- **Method 3:** **THE GREEN CIRCLE IN THE FRONT**

and for the scene shown in figure 8 are:

- **Method 1:** **THE RED RECTANGLE**
- **Method 2:** **THE PINK RECTANGLE**
- **Method 3:** **THE RED RECTANGLE**

![Fig. 8 THE RED RECTANGLE](image-url)
After generating the descriptions for the 350 scenes using the three methods we included them in the web-page, so the users can try to guess which objects are being described. To warranty the fairness of the experiment the users don’t know which descriptions are generated automatically by the system and which ones come from other users. Actually which description is shown to each user is selected randomly among all. Counting as correct that descriptions that other users guessed right we obtained the results showed in figure 9.

In figure 9 can be seen that the Method 1 is performing bellow average, it obtains 49% of the descriptions correct, and it is ranked #39 which means that other 4 users are performing even worse. The Method 2 is performing a little bit better obtaining 57% of the descriptions correct (while below the results presented in the previous work 81.3%) and it is ranked #35. The Method 3 is performing quite well obtaining 72% of the descriptions correct (just a little bit over the average of users) and it is ranked #27.

VII. CONCLUSIONS

So far the system has 40 registered users, from 15 different countries, who had provided 360 descriptions using 150 different words and had allowed the system to learn some lexicon (30 words), some syntax (20 patterns), and some semantics (7 word’s classes grounded) for the shape description task. The best method it is performing quite well obtaining 100% correct spelled words, 88% syntactically correct sentences and 72% of semantically correct sentences; despite the variety of users, who spelled correctly 97% of the words, wrote 93% of syntactically correct sentences and provided 75% of semantically correct sentences.

We have provided a semantic model (using soft constraints) of the words used by web-users to describe objects for other users in a describing game. The descriptions generated took into account the context of the object to avoid ambiguous descriptions, allowing users to guess the described object correctly. A future work is to study the construction of complex phrases, those referring to more than one object.

With the approach taken in this work the possibility to study semantic models for specific words used by specific users in specific contexts is opened. This can be seen as a step in the development of Computing with Words whose relevance have been highlighted by Zadeh in [10], [26].

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