DESIGN OF LOW-COST, COMPACT AND WEATHER-PROOF WHOLE SKY IMAGERS FOR HIGH-DYNAMIC-RANGE CAPTURES

Soumyabrata Dev, Florian M. Savoy, Yee Hui Lee, Stefan Winkler

1 School of Electrical and Electronic Engineering, Nanyang Technological University (NTU), Singapore
2 Advanced Digital Sciences Center (ADSC), University of Illinois at Urbana-Champaign, Singapore

ABSTRACT

Ground-based whole sky imagers are popular for monitoring cloud formations, which is necessary for various applications. We present two new Wide Angle High-Resolution Sky Imaging System (WAHRSIS) models, which were designed especially to withstand the hot and humid climate of Singapore. The first uses a fully sealed casing, whose interior temperature is regulated using a Peltier cooler. The second features a double roof design with ventilation grids on the sides, allowing the outside air to flow through the device. Measurements of temperature inside these two devices show their ability to operate in Singapore weather conditions. Unlike our original WAHRSIS model, neither uses a mechanical sun blocker to prevent the direct sunlight from reaching the camera; instead they rely on high-dynamic-range imaging (HDRI) techniques to reduce the glare from the sun.

Index Terms— WAHRSIS, ground-based sky camera, clouds, HDR imaging

1. INTRODUCTION

There is a growing interest in using whole sky imagers for monitoring clouds. These imagers are used in geoscience and remote sensing for applications such as solar energy prediction [1], attenuation analysis in satellite-to-ground communication links [2], estimation of cloud fraction and other microphysical properties [3]. Such imagers complement the information obtained from satellite images [4]. They provide a higher resolution of a specific area and an upwards pointing view, which facilitates sky/cloud segmentation [5, 6].

Commercially available sky imagers (TSI-440, TSI-880) manufactured by Yankee Environmental Systems1 are used by a number of research groups [7]. However, these devices are expensive, provide poor image resolution, and offer only limited control flexibility. This motivated us to build our own imagers using off-the-shelf components. Other researchers have done likewise [8, 9].

In an earlier publication [10], we proposed the initial Wide Angle High-Resolution Whole Sky Imaging System (WAHRSIS) model. It uses a mechanical sun blocker that follows the sun to reduce glare in the images. Its mounting structure and motors reduce the visible sky region quite significantly (cf. Figure 6a). After extensive usage of this model, two additional operational problems became apparent: (i) Since the motors moving the sun blocker are exposed to rain, they have started to rust and do not work anymore; (ii) The enclosure heats up when placed in the sun, and the temperature inside often exceeds the recommended operating range of the electronic devices.

In this paper, we introduce two improved WAHRSIS models that were designed to solve all of the above issues. We achieve a considerable reduction in size without compromising on performance. Instead of using a conventional sun blocker to reduce sun glare in the image, we employ High-Dynamic-Range Imaging (HDRI) techniques 2.

The rest of the paper is organized as follows: Section 2 discusses the design of both WAHRSIS models. Temperature measurements inside the devices are carried out in Section 3. Section 4 presents the high-dynamic-range imaging procedure. Section 5 concludes the paper.

2. DESIGN

A sky imager essentially comprises a DSLR camera with a fish-eye lens, which are placed inside a weather-proof casing with a transparent dome. A single board computer instructs the camera to take pictures at user-defined intervals, stores the captured images in an on-board hard drive, and may even send them to a server.

In this section, we detail the mechanical design of the new WAHRSIS models. They were designed to withstand the hot and humid climate of Singapore and run for extended periods of time without interruption or human intervention.

Two strategies were implemented. The first model is a fully sealed imager with a Peltier cooler to control the internal temperature. The second model has a double roof, which

1This research is funded by the Defence Science and Technology Agency (DSTA), Singapore.
Send correspondence to Y.H. Lee, E-mail: eyhlee@ntu.edu.sg.
1http://www.yesinc.com/

2The source code for the several simulations in this paper is available online at https://github.com/Soumyabrata/HDRCaptures.
isolates the casing from direct sunlight. It also features ventilating grids, allowing the outside air to flow through the device. The compact size of both models minimizes the volume of air to control and also enhances their portability. The transformers and power strip are placed outside the main device in another polystyrene box as they are less sensitive to high temperatures and also generate heat themselves.

The total component cost of our new WAHRSIS models is less than US$ 2000 each, as specified in Table 1.

| Items                | Sealed model | Ventilated model |
|----------------------|--------------|------------------|
| DSLR camera          | 677          | 677              |
| Fish-eye lens        | 733          | 733              |
| Single-board PC      | 68           | 68               |
| Mechanical items     | 212          | 221              |
| Peltier cooler       | 65           | -                |
| Miscellaneous        | 140          | 70               |
| **Total cost**       | **$1895**    | **$1769**        |

Table 1: Breakdown of the costs of the sealed and ventilated WAHRSIS models (in US$). The mechanical items consist of the frame, box, screws etc., whereas miscellaneous items include the extension power cord, the power adapter etc.

2.1. Sealed WAHRSIS Model

The sealed WAHRSIS model consists of a hermetically-sealed plastic box with sunlight-reflecting paint on it, as shown in Fig. 1. A thermoelectric Peltier cooler is placed at the bottom of the casing. When electricity is provided, the side facing inside the box gets cold while the outside face gets hot. Fans are placed at both sides to dissipate the cold or heat produced. The on-board computer controls the cooler operation using temperature and humidity sensors.

Fig. 1: Sealed WAHRSIS design. (a) DSLR camera, (b) dome, (c) ODROID board, (d) casing, (e) thermoelectric cooler with fans.

2.2. Ventilated WAHRSIS Model

The ventilated WAHRSIS model consists of a casing made of galvanized steel, as shown in Fig. 2. This material reflects the sun light well and prevents rusting and corrosion. Ventilation grids are placed on each side, allowing ambient air to flow inside while preventing rainwater from entering. A metallic sheet is placed a few centimeters on top of the box, along with the transparent dome for the camera lens. The air in between acts as insulator, which protects the case from being heated by direct sunlight.

Fig. 2: Ventilated WAHRSIS design. (a) Dome, (b) shelter, (c) air vent cover, (d) casing.

3. TEMPERATURE CONTROL

Singapore has a typical tropical climate, i.e. hot and humid conditions throughout the year, with average low/high temperatures of 25°C/33°C, respectively. A box placed outside in the sun tends to heat up quickly, so we need to make sure the maximum operating temperature of the camera, lens, and the other electronic components of 40°C is not exceeded.

For the sealed box, we set two distinct thresholds for the operation of the Peltier cooler: we switch it on when the inside temperature reaches 37°C, and off again when it falls below 32°C.

Fig. 3: Temperature recorded over the course of a day inside both models.
In order to investigate the efficacy of the two designs, both WAHRSIS models were placed on a rooftop at the Nanyang Technological University of Singapore. We measured the temperature inside the devices on a typical day in March 2015 with several hours of sunshine. Fig. 3 shows the results.

In both models, the temperature never exceeds 40°C. During daytime, the interior temperature remains lower in the sealed model than in the ventilated model because of its active cooling. Temperature variations are also smoother in the sealed box as a result of the controlled environment. Yet the grids of the ventilated model are also surprisingly effective at passive cooling. An important point is that we never noticed condensation inside the boxes. We thus conclude that both models can work well in tropical regions.

4. HIGH DYNAMIC RANGE IMAGING

The new WAHRSIS models presented here do not have a physical sun blocking mechanism. Instead, we use HDRI techniques to reduce the over-exposure resulting from sun glare. This avoids occlusions from the sun-blocker and its support structure in the captured images (which significantly complicate subsequent computer vision tasks), while at the same time keeping the number of saturated pixels in the circumsolar region to a minimum.

The imaging system of our WAHRSIS models consists of a Canon EOS 600D digital SLR camera with a sensor resolution of $5184 \times 3456$ pixels and a Sigma 4.5mm F2.8 EX DC circular fisheye lens that captures nearly 180 degrees of the sky hemisphere. Both imagers use an ODROID-C1 single board computer; with its 1.5 GHz processor and 1 GB RAM, this board is powerful enough to perform on-board image processing tasks.

![Fig. 4: Low-dynamic-range (LDR) images captured at different exposure levels.](image)

Subsequently, we use the algorithm by Debevec and Malik [11] to create a High-Dynamic-Range (HDR) radiance map from the three LDR images. As their exposure times are known, we can compute the camera response curve of the imaging system using samples obtained from the different LDR images. This is shown in Fig. 5. The dynamic range of the resulting HDR radiance map is 15 bits, which represents a significant improvement over the 8-bit LDR images.

![Fig. 5: Response curve of the HDRI system, computed from three LDR images with different exposure settings.](image)

The camera offers an automatic exposure bracketing (AEB) mode, which allows us to capture three (or more) images in burst mode with different exposure settings. We put the camera in aperture-priority mode to fix the aperture at the smallest available setting, and consequently the AEB function will vary the shutter speed only. For sky images we observed that the default exposure is usually somewhat too bright, so we choose $\{-3, -1, +1\}$ exposure value (EV) offsets for the bracketing. Fig. 4 shows three Low-Dynamic-Range (LDR) images captured in this fashion.

![Fig. 6: Effect of sun glare with different strategies. The white rectangle outlines the circumsolar region, which is enlarged in the bottom row. Saturated pixels are shown in pink.](image)
In order to visualize the HDR image, we convert the high-dynamic-range radiance map to an LDR image via tone-mapping using an adaptive equalization process. Fig. 6c shows the resulting image, along with those obtained from a sky imager with a mechanical sun blocker and a normal single-exposure image. In order to visualize the efficacy of our proposed approach, we zoom in on the circumsolar region in each of the three images to look at the amount of detail visible around the sun. Although the sun-blocker is effective at reducing sun glare, the occlusion is significant. Without a sun-blocker, the number of saturated pixels is very high in a normal single-exposure image. Fusing multiple exposures into an HDR image is indeed a good solution for minimizing the effects of over-exposure.

5. CONCLUSIONS

We introduced two new models of WAHRIS, low-cost whole sky imagers built with off-the-shelf components. One features a sealed casing with thermoelectric cooling, while the other uses a ventilated casing. Measurements and extensive outdoor testing have proven their ability to maintain temperatures at acceptable levels in the Singapore weather over prolonged periods.

Unlike our original WAHRIS version [10] and commercial sky imagers, neither of the two new models uses a mechanical sun blocker. Instead, they rely on the fusion of multiple exposures to create a high-dynamic-range image and minimize over-saturation of pixels near the circumsolar region. Table 2 summarizes the main improvements introduced by the two new models over the first.

| WAHRIS Properties      | Previous model | Sealed model | Ventilated model |
|-------------------------|----------------|--------------|------------------|
| Glare reduction method  | Sun blocker    | HDRI         | HDRI             |
| Occlusion severity      | Moderate       | Nil          | Nil              |
| Weatherability          | Limited        | Good         | Good             |
| Portability             | Limited        | Good         | Good             |
| Image resolution        | High           | High         | High             |
| Total cost (in US$)     | $2525          | $1895        | $1769            |

Table 2: Comparison of the different WAHRIS models.

We are using the captured images for sky/cloud segmentation and classification into different cloud types [12], and we are deploying multiple sky cameras in order to estimate cloud base height [13]. Our future work includes extending these methods to HDR images.

6. ACKNOWLEDGMENTS

Darko Jokic (Hochschule für Technik Rapperswil, Switzerland) designed and built the sealed WAHRIS model during his internship at NTU Singapore. Charles Wong (NTU Singapore) designed and built the ventilated WAHRIS model as part of his final year project.

7. REFERENCES

[1] C.-L. Fua and H.-Y. Cheng, “Predicting solar irradiance with all-sky image features via regression,” Solar Energy, vol. 97, pp. 537–550, November 2013.
[2] F. Yuan, Y. H. Lee, and Y. S. Meng, “Comparison of cloud models for propagation studies in Ka-band satellite applications,” in Proc. International Symposium on Antennas and Propagation (ISAP), 2014.
[3] D. D. Turner and R. E. Holz, “Retrieving cloud fraction in the field-of-view of a high-spectral resolution infrared radiometer,” IEEE Geoscience and Remote Sensing Letters, vol. 2, no. 3, pp. 287–291, July 2005.
[4] A. B. Davis and A. Marshak, “Optical remote sensing of dense isolated clouds with high-resolution satellite- and ground-based imagers,” in Proc. IEEE International Geoscience and Remote Sensing Symposium (IGARSS), 2002.
[5] S. Dev, Y. H. Lee, and S. Winkler, “Systematic study of color spaces and components for the segmentation of sky/cloud images,” in Proc. IEEE International Conference on Image Processing (ICIP), 2014.
[6] S. Dev, Y. H. Lee, and S. Winkler, “Multi-level semantic labeling of sky/cloud images,” in Proc. IEEE International Conference on Image Processing (ICIP), 2015.
[7] C. N. Long, J. M. Sabburg, J. Calbé, and D. Pages, “Retrieving cloud characteristics from ground-based daytime color all-sky images,” Journal of Atmospheric and Oceanic Technology, vol. 23, no. 5, pp. 633–652, 2006.
[8] J. Sabburg and J. Wong, “Evaluation of a ground-based sky camera system for use in surface irradiance measurement,” Journal of Atmospheric and Oceanic Technology, vol. 16, no. 6, pp. 752–759, June 1999.
[9] J. E. Shields, M. E. Karr, R. W. Johnson, and A. R. Burden, “Day/night whole sky imagers for 24-h cloud and sky assessment: History and overview,” Applied Optics, vol. 52, no. 8, pp. 1605–1616, March 2013.
[10] S. Dev, F. Savoy, Y. H. Lee, and S. Winkler, “WAHRIS: A low-cost, high-resolution whole sky imager with near-infrared capabilities,” in Proc. IS&T/SPIE Infrared Imaging Systems, 2014.
[11] P. E. Debevec and J. Malik, “Recovering high dynamic range radiance maps from photographs,” in Proc. 24th Annual Conference on Computer Graphics and Interactive Techniques (ACM SIGGRAPH), 1997.
[12] S. Dev, Y. H. Lee, and S. Winkler, “Categorization of cloud image patches using an improved texton-based approach,” in Proc. IEEE International Conference on Image Processing (ICIP), 2015.
[13] F. M. Savoy, J. C. Lemaître, S. Dev, Y. H. Lee, and S. Winkler, “Cloud base height estimation using high-resolution whole sky imagers,” in Proc. IEEE International Geoscience and Remote Sensing Symposium (IGARSS), 2015.