Generalized Kerr spacetime with an arbitrary mass quadrupole moment: geometric properties versus particle motion

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Abstract
An exact solution of Einstein’s field equations in empty space first found in 1985 by Quevedo and Mashhoon is analyzed in detail. This solution generalizes Kerr spacetime to include the case of matter with an arbitrary mass quadrupole moment and is specified by three parameters, the mass $M$, the angular momentum per unit mass $a$ and the quadrupole parameter $q$. It reduces to the Kerr spacetime in the limiting case $q = 0$ and to the Erez–Rosen spacetime when the specific angular momentum $a$ vanishes. The geometrical properties of such a solution are investigated. Causality violations, directional singularities and repulsive effects occur in the region close to the source. Geodesic motion and accelerated motion are studied on the equatorial plane which, due to the reflection symmetry property of the solution, also turns out to be a geodesic plane.

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1. Introduction
The problem of describing the gravitational field of astrophysical bodies is of central importance in general relativity, both as an issue of principle and as a foundation for explaining the results of observations. It is an issue of principle because general relativity is believed to be the most accurate theory of the gravitational field. Consequently, Einstein’s theory should accept the existence of exact solutions that correctly describe the gravitational field of realistic
sources. On the other hand, the explanation of effects observed at the astrophysical level is extremely important.

Astrophysical bodies are characterized in general by a non-spherically symmetric distribution of mass. In many cases, like ordinary planets and satellites, it is possible to neglect the deviations from spherical symmetry; it seems instead reasonable to expect that deviations should be taken into account in the case of strong gravitational fields.

The general metric describing the gravitational field of a rotating deformed mass was found in 1991 by Quevedo and Mashhoon [1, 2] and involves an infinite set of gravitoelectric and gravitomagnetic multipoles. This is a stationary axisymmetric solution was found in 1991 by Quevedo and Mashhoon [1, 2] and involves an infinite set of properties of the general solution [1, 2], we concentrate for the sake of simplicity on the special case that involves only three parameters: the mass \( M \), the angular momentum per unit mass \( a \), and the mass quadrupole parameter \( q \) of the source. This special case was first found by Quevedo and Mashhoon in 1985 [6]. Hereafter, this solution will be denoted as the QM solution.

The corresponding line element in prolate spheroidal coordinates \((t, x, y, \phi)\) with \( x \geq 1, -1 \leq y \leq 1\) is given by [7]

\[
dx^2 = -f(dt - \omega d\phi)^2 + \frac{\sigma^2}{f} \left( e^{2\gamma}(x^2 - y^2)^2 \left( \frac{d\alpha^2}{x^2 - 1} + \frac{dy^2}{1 - y^2} \right) + (x^2 - 1)(1 - y^2) d\phi^2 \right),
\]

where \( f, \omega \) and \( \gamma \) are functions of \( x \) and \( y \) only and \( \sigma \) is a constant. They have the form

\[
f = \frac{R}{L} e^{-2qP_2Q_1},
\]

\[
\omega = -2a - 2\sigma \frac{M}{R} e^{2qP_2Q_1};
\]

\[
e^{2\gamma} = \frac{1}{4} \left( 1 + \frac{M}{\sigma} \right)^2 \frac{R}{x^2 - 1} e^{x^2},
\]

where

\[
R = a_+a_0 + b_+b_0, \quad L = a_0^2 + b_0^2,
\]

\[
M = ax(1 - y^2)(e^{2qP_2} + e^{2qP_1})a_0 + y(x^2 - 1)(1 - \alpha^2 e^{2q(\delta_2, \delta_3)}) b_0,
\]

\[
\gamma = \frac{1}{2} (1 + q)^2 \ln \frac{x^2 - 1}{x^2 + y^2} + 2q(1 - P_2)Q_1 + q^2(1 - P_2) \left( 1 + P_2 \right) \left( Q_1^2 - Q_2^2 \right) + \frac{1}{2} (x^2 - 1)(2Q_3^2 - 3xQ_1Q_2 + 3Q_0Q_2 - Q_3^2) \right).
\]

Here \( P_l(y) \) and \( Q_l(x) \) are Legendre polynomials of the first and second kind, respectively. Furthermore,

\[
a_\pm = x(1 - \alpha^2 e^{2q(\delta_2, \delta_3)}) \pm (1 + \alpha^2 e^{2q(\delta_2, \delta_3)}),
\]

\[
b_\pm = \alpha y(e^{2qP_2} + e^{2qP_1}) \mp \alpha(e^{2qP_2} - e^{2qP_1}),
\]

\[
\delta_\pm = \frac{1}{2} \ln \frac{(x \pm y)^2}{x^2 - 1} + \frac{3}{2}(1 - y^2 \mp xy) + \frac{3}{4} [x(1 - y^2) \mp y(x^2 - 1)] \ln \frac{x - 1}{x + 1},
\]

the quantity \( \alpha \) being a constant:

\[
\alpha = \frac{\sigma - M}{a}, \quad \sigma = \sqrt{M^2 - a^2}.
\]
The Geroch–Hansen [8, 9] moments are given by

\[ M_{2k+1} = J_{2k} = 0, \quad k = 0, 1, 2, \ldots \] (1.6)

\[ M_0 = M, \quad M_2 = -Ma^2 + \frac{2}{15} qM^3 \left( 1 - \frac{a^2}{M^2} \right)^{3/2}, \ldots \] (1.7)

\[ J_1 = Ma, \quad J_3 = -Ma^3 + \frac{4}{15} qM^3 a \left( 1 - \frac{a^2}{M^2} \right)^{3/2}, \ldots \] (1.8)

The vanishing of the odd gravitoelectric \((M_n)\) and even gravitomagnetic \((J_n)\) multipole moments is a consequence of the reflection symmetry of the solution about the hyperplane \(y = 0\), which we will refer to as the ‘symmetry’ (or equivalently ‘equatorial’) plane hereafter. From the above expressions, we see that \(M\) is the total mass of the body, \(a\) represents the specific angular momentum and \(q\) is related to the deviation from the spherical symmetry. All higher multipole moments can be shown to depend only on the parameters \(M, a\) and \(q\).

We limit our analysis here to the case \(\sigma > 0\), i.e. \(M > a\). In the case \(\sigma = 0\), the solution reduces to the extreme Kerr spacetime irrespective of the value of \(q\) [2]. The case \(\sigma\) complex, i.e. \(a > M\), requires a different definition of the quadrupole parameter in order to have real Geroch–Hansen moments and can be better discussed by using Weyl cylindrical coordinates. We will not explore this case here.

In this work, we analyze some geometric and physical properties of the QM solution. The limiting cases contained in the general solution suggest that it can be used to describe the exterior asymptotically flat gravitational field of a rotating body with arbitrary quadrupole moment. This is confirmed by the analysis of the motion of particles on the equatorial plane. It turns out that the whole geometric structure of the QM spacetime is drastically changed in comparison with Kerr spacetime, leading to a number of previously unexplored physical effects strongly modifying the features of particle motion, especially near the gravitational source. In fact, the QM solution is characterized by a naked singularity at \(x = 1\), whose existence critically depends on the value of the quadrupole parameter \(q\). In the case \(q = 0\) (Kerr solution), \(x = 1\) represents instead an event horizon. This bifurcating behavior accounts for the above-mentioned drastic changes with respect to the Kerr metric.

Due to the very complicated form of the metric most of the analysis will be performed numerically.

2. Limiting cases

The QM solution reduces to the Kerr spacetime in the limiting case \(q \to 0\) and to the Erez–Rosen spacetime when \(a \to 0\). Furthermore, it can be shown that the general form of the QM solution (see appendix A) is equivalent, up to a coordinate transformation, to the exterior vacuum Hartle–Thorne solution once linearized to first order in the quadrupole parameter and to second order in the rotation parameter.

2.1. Kerr solution

For vanishing quadrupole parameter, we recover the Kerr solution, with functions

\[ f_K = \frac{c^2 x^2 + d^2 y^2 - 1}{(cx + 1)^2 + d^2 y^2}, \quad \omega_K = 2a(cx + 1)(1 - y^2) \]

\[ \gamma_K = \frac{1}{2} \ln \left( \frac{c^2 x^2 + d^2 y^2 - 1}{c^2 (x^2 - y^2)} \right). \] (2.1)
where

\[ c = \frac{\alpha}{M}, \quad d = \frac{a}{M}, \quad c^2 + d^2 = 1, \]  

(2.2)

so that \( \alpha = (c - 1)/d \). Transition of this form of Kerr metric to the more familiar one associated with Boyer–Lindquist coordinates is accomplished by the map

\[ x = \frac{r - M}{\alpha}, \quad y = \cos \theta, \]  

(2.3)

so that \( x = 1 \) corresponds to the outer horizon \( r = r_+ = M + \alpha \).

To first order in \( q \), the QM solution becomes

\[ f = f_K - 2q[P_2 Q_2 f_K + \Lambda_+ \delta_+ + \Lambda_- \delta_-] + O(q^2), \]

\[ \omega = \omega_K + 2acq \left[ 2P_2 Q_2 \frac{c(x^2 - y^2) + x(1 - y^2)}{c^2 x^2 + d^2 y^2 - 1} + \Psi_+ \delta_+ + \Psi_- \delta_- \right] + O(q^2), \]

\[ \gamma = \gamma_K + q \left[ 2(1 - P_2) Q_1 + \ln \left( \frac{x^2 - 1}{x^2 - y^2} \right) \right. \]

\[ + \left. a d \frac{c(x^2 - y^2) + 1 - y^2}{c^2 x^2 + d^2 y^2 - 1}(\delta_+ + \delta_-) \right] + O(q^2), \]  

(2.4)

where

\[ \Lambda_\pm = d^2 (x \pm y) \frac{[(x \mp y + 1)^2 - y^2]}{[(cx + 1)^2 + d^2 y^2]^2}, \]

\[ \Psi_\pm = \frac{x \pm y}{(c^2 x^2 + d^2 y^2 - 1)^2} \left( cd^2 (x \mp y)^2(1 \pm xy) + c(x^2 - 1)(1 \mp xy) \right. \]

\[ + \left. (x \mp y)[c^2(x^2 - 1) + d^2(1 - y^2)] \right]. \]  

(2.5)

This approximate metric could be used to describe the exterior field of an arbitrarily rotating mass source with a small quadrupole moment. The lowest Geroch–Hansen multipole moments in this case coincide with those of the exact solution as given in equations (1.7) and (1.8). Differences will appear in higher moments where all terms containing \( q^2 \) and higher exponents must be neglected.

It is interesting to mention that in the limiting case \( a \to M \), the QM metric leads to the extreme Kerr black hole solution, regardless of the value of the quadrupole \( q \) [6]. This can be easily seen both at the level of the multipole moments (1.7) and (1.8) and by directly computing the limiting metric. The latter determines in turn the limit of applicability of the QM solution, since for values in the range \( a/M > 1 \) the multipole moments and the metric both become complex. As stated in the introduction we will not consider such a situation here.

### 2.2. Erez–Rosen solution

Similarly, for vanishing rotation parameter we recover the Erez–Rosen solution [10–12]. It is a solution of the static Weyl class of solutions (i.e. \( \omega = 0 \)) with functions

\[ f_{ER} = \frac{x - 1}{x + 1} e^{-2qP_2 Q_2}, \quad \gamma_{ER} = \hat{\gamma}, \]  

(2.6)

which reduce to

\[ f_S = \frac{x - 1}{x + 1}, \quad \gamma_S = \frac{1}{2} \ln \left( \frac{x^2 - 1}{x^2 - y^2} \right), \]  

(2.7)

when \( q = 0 \), corresponding to the Schwarzschild solution.
To the first nonvanishing order in \(a/M\) we find

\[
f = f_{\text{ER}} \left\{1 + \frac{1}{2(x^2 - 1)(x - 1)^2} [(x + y)(y - 1) e^{i\delta} - (x - y)(y + 1) e^{i\delta} - 2(x^2 - y^2) e^{i(\delta, \phi)} \left(\frac{a}{M}\right)^2 \right\} + O((a/M)^4),
\]

\[
\omega = -2M \left\{1 + \frac{e^{2\theta} P_2}{2(x - 1)} [(x + y)(y - 1) e^{i\delta} - (x - y)(y + 1) e^{i\delta}] \left(\frac{a}{M}\right)^2 + O((a/M)^3)\right\},
\]

\[
\gamma = \gamma_{\text{ER}} + \frac{1}{4} \left\{1 - \frac{1}{2(x^2 - 1)} [(1 - y^2)(e^{i\phi} + e^{-i\phi}) + 2(x^2 - y^2) e^{i(\phi, \delta, \phi)}] \left(\frac{a}{M}\right)^2 + O((a/M)^4).\right\}
\]

(2.8)

This approximate solution can be interpreted as a generalization of the Lense–Thirring spacetime [13, 14], which is obtained in the limit \(q \to 0\) by retaining terms up to the linear order in \(a/M\). Consequently, the approximate solution (2.8) could be used to investigate the exterior gravitational field of slowly rotating deformed bodies. A similar approximate solution, accurate to second order in the rotation parameter and to first order in the quadrupole moment, was found long ago by Hartle and Thorne [15].

### 2.3. Hartle–Thorne solution

The Hartle–Thorne metric describing the exterior field of a slowly rotating slightly deformed object is given by

\[
ds^2 = -\left(1 - \frac{2M}{R}\right) \left[1 + 2k_1 P_2(\cos \theta) + 2 \left(1 - \frac{2M}{R}\right)^{-1} \frac{J^2}{R^4} (2 \cos^2 \Theta - 1) \right] \, dt^2
\]

\[
+ \left(1 - \frac{2M}{R}\right)^{-1} \left[1 - 2k_2 P_2(\cos \theta) - 2 \left(1 - \frac{2M}{R}\right)^{-1} \frac{J^2}{R^4} \right] \, dR^2
\]

\[
+ R^2 (d\Theta^2 + \sin^2 \Theta \, d\phi^2) [1 - 2k_3 P_2(\cos \Theta)] - 4 \frac{J}{R} \sin^2 \Theta \, dt \, d\phi,
\]

(2.9)

where

\[
k_1 = \frac{J^2}{MR^3} \left(1 + \frac{M}{R}\right) - \frac{5}{8} \frac{Q - J^2/M}{M} Q_1^2 \left(\frac{R}{M} - 1\right),
\]

\[
k_2 = k_1 - \frac{6J^2}{R^4},
\]

\[
k_3 = k_1 + \frac{J^2}{MR^3} - \frac{5}{4} \frac{Q - J^2/M}{M^2} \left(1 - \frac{2M}{R}\right)^{-1/2} Q_{1/2}^2 \left(\frac{R}{M} - 1\right).
\]

(2.10)

Here \(Q_m^p\) are the associated Legendre functions of the second kind and the constants \(M, J\) and \(Q\) are the total mass, angular momentum and mass quadrupole moment of the rotating star, respectively.

It is interesting to find out the connection between the Hartle–Thorne solution and the QM solution in the appropriate limit. To this end, it is necessary to start with the general form of the QM solution as given in appendix A containing an additional parameter, the Zipoy–Voorhees [16, 17] constant parameter \(\delta\). For our purposes it is convenient to set such a parameter as \(\delta = 1 + sq\), where \(s\) is a real number. For \(s = 0\), i.e. \(\delta = 1\), we recover the solution (1.1)–(1.5).
To first order in the quadrupole parameter $q$ and to second order in the rotation parameter $a/M$, the metric functions turn out to be

$$f \simeq \frac{x - 1}{x + 1} \left[ 1 - q \left( 2P_z Q_z - s \ln \frac{x - 1}{x + 1} \right) \right] - \frac{x^2 + x - 2y^2}{(x + 1)^3} \left( \frac{a}{M} \right)^2,$$

$$\omega \simeq 2M \frac{1 - y^2}{x - 1} \left( \frac{a}{M} \right),$$

$$\gamma \simeq \hat{\gamma} (1 + 2sq) - \frac{1}{2} \frac{1 - y^2}{x^2 - 1} \left( \frac{a}{M} \right)^2,$$

where $\hat{\gamma}$ is defined in equation (1.3) and terms of the order of $q(a/M)$ have also been neglected.

Introduce first Boyer–Lindquist coordinates $(t, r, \theta, \phi)$ through the transformation

$$t = t, \quad x = r - \frac{M}{\sigma}, \quad y = \cos \theta, \quad \phi = \phi.$$  

Then set $s = -1$ and $M = M'(1 + q)$. The further transformation

$$t = t, \quad r = r(R, \Theta), \quad \theta = \theta(R, \Theta), \quad \phi = \phi$$

with

$$r = R + M'q + \frac{3}{2} M'q \sin^2 \theta \left[ \frac{R}{M'} - 1 + \frac{1}{2} \frac{R^2}{M'^2} \left( 1 - 2 \frac{M'}{R} \right) \ln \left( 1 - 2 \frac{M'}{R} \right) \right]$$

$$- \frac{a^2}{2R} \left[ \left( 1 + 2 \frac{M'}{R} \right) \left( 1 - \frac{M'}{R} \right) - \cos^2 \Theta \left( 1 - 2 \frac{M'}{R} \right) \left( 1 + 3 \frac{M'}{R} \right) \right],$$

$$\theta = \Theta - \sin \Theta \cos \Theta \left[ \frac{3}{2} q \left( 2 + \frac{R}{M'} - 1 \right) \ln \left( 1 - 2 \frac{M'}{R} \right) \right] + \frac{a^2}{2R} \left( 1 + 2 \frac{M'}{R} \right) \left( 1 + 2 \frac{M'}{R} \right),$$

finally gives the mapping between the general form of QM solution and the Hartle–Thorne metric (2.9) with parameters

$$M = M' = M(1 - q), \quad J = -Ma, \quad Q = \frac{J^2}{M} + \frac{4}{5} M^3 q.$$  

Note that the previous transformation is obtained simply by combining the corresponding transformation from Kerr to Hartle–Thorne solution as given by Hartle and Thorne themselves in [15] and that from Erez–Rosen to Hartle–Thorne solution as found by Mashhoon and Theiss in [18].

3. Geometric properties of the solution

The solution admits two Killing vectors associated with translation in time and rotation about the symmetry axis. The timelike Killing vector $\partial_t$ changes its causality property when $f = 0$, defining a hypersurface which in the Kerr limiting case is called an ergosurface as the boundary of the ergosphere (or equivalently ergoregion). Using this terminology also in this case we compare in figures 1 and 2 the ergoregions of Kerr solution and QM solution (for different values of the quadrupole parameter), respectively. The situation is completely different. In fact, while in the Kerr case such a hypersurface is the boundary of a simply connected domain, in the case of the QM solution this property is no longer true, as soon as the magnitude of the quadrupole parameter exceeds a certain critical value (for example, for the choice $a/M = 0.5$, the range of Kerr-like behavior corresponds to $-1 \lesssim q \lesssim 1.21$).

The spacelike Killing vector $\partial_\phi$ also changes its causality condition in some regions, leading to the existence of closed timelike curves in the QM solution. These regions are depicted in figure 3 for different values of the quadrupole parameter.
In order to investigate the structure of singularities in the QM metric, we have to consider the curvature invariants. Since the solution is a vacuum one, there exist just two independent quadratic scalar invariants, the Kretschmann invariant $K_1$ and the Chern–Pontryagin invariant $K_2$ defined by

$$K_1 = R^α_βγ δ R_α^βγ δ, \quad K_2 = * R^α_βγ δ R_α^βγ δ,$$

(3.1)

where the star denotes the dual. The behavior of curvature invariants as functions of $x$ for selected values of $y$, $a/M$ and $q$ is shown in figure 4. It turns out that $K_1$ diverges when approaching $x = 1$ along the direction $y = 0$, but it is finite there moving along a different path. Furthermore, the invariant $K_2$ vanishes identically for $y = 0$. Therefore, the metric has a directional singularity at $x = 1$ (see e.g. [19]).

It is now interesting to investigate what kind of hypersurface is $x = 1$. Consider the normal to a $x = \text{const}$ hypersurface. The behavior of its norm $g^{xx}$ when approaching $x = 1$ discriminates between its character being either null or timelike depending on the value of the quadrupole parameter. The limit of $g^{xx}$ as $x \to 1$ also depends on $y$. For instance, approaching $x = 1$ along any direction on the equatorial plane $y = 0$ gives

$$g^{xx} \sim (x - 1)^{1+q/2-q^2/4},$$

(3.2)

implying that the singular hypersurface $x = 1$ is null when $|q - 1| < \sqrt{5}$ and timelike otherwise. On the other hand, moving along the axis $y = 1$ gives

$$g^{xx} \sim \begin{cases} (x - 1)^{1+q}, & q > 0 \\ (x - 1), & -1 < q < 0 \\ (x - 1)^{-q}, & q < -1, \end{cases}$$

(3.3)

implying that the singular hypersurface $x = 1$ is always null. The corresponding careful analysis for the Erez–Rosen solution ($a = 0$) is contained in appendix A of [30].
Figure 2. The shape of the ergoregion is shown for \( a/M = 0.5 \) and different values of the quadrupole parameter: \( q = [-10, -1, 1, 10] \), from (a) to (d), respectively. For \( q = -1 \) and \( q = 1 \), the shape is similar to the Kerr case, i.e. the regions are simply connected.

A similar discussion can be done also for the metric determinant. Approaching \( x = 1 \) along any direction on the equatorial plane \( y = 0 \) gives

\[
\sqrt{-g} \sim (x - 1)^{-q/2 + q^2/4},
\]

implying that the volume element vanishes approaching the singular hypersurface \( x = 1 \) when \( q < 0, q > 2 \) and diverges otherwise. On the other hand, moving along the axis \( y = 1 \) gives

\[
\sqrt{-g} \sim \begin{cases} 
(x - 1)^{-q}, & q > 0 \\
\text{const}, & -1 < q < 0 \\
(x - 1)^{q+1}, & q < -1.
\end{cases}
\]
We note that if the presence of the quadrupole moment totally changes the situation with respect to the Kerr spacetime, the smooth horizon of the Kerr solution becoming a singular hypersurface in the QM solution, the properties of the naked singularity are also different with respect to the limiting case of the Erez–Rosen spacetime.

Finally, the spectral index $S$ (see appendix B for the definition of $S$ in terms of Weyl scalars) shows that the solution is algebraically general. The real part of $S$ is plotted in figure 5 as a function of $x$ for $y = 0$ and selected values of $a/M$ and $q$. The imaginary part is identically zero in this case. A numerical analysis of the spectral index for different values of the quadrupole moment shows that $S \to 1$ as $x \to \infty$, i.e. it is algebraically special. We conclude that the asymptotic behavior of the spacetime is dominated by the Kerr spacetime which is algebraically special of type D. This is in agreement with the expectation which follows from the analysis of relativistic multipole moments, according to which any stationary axisymmetric asymptotically flat vacuum solution of Einstein’s equations must approach the Kerr metric asymptotically [20].

Note that drawing a Penrose diagram would help to easily understand the global aspects of the geometry of the QM solution. However, due to the rather involved form of the metric functions it is a very hard task to construct it. Analytic calculations can be performed only in the case of small values of the quadrupole parameter $q$. But even in this simplest case it is possible to show that the resulting conformal diagram is closely similar to the corresponding one for a Kerr naked singularity (see, e.g., figure 6.4 of [21]).

4. Geodesics

The geodesic motion of test particles is governed by the following equations:

$$i = \frac{E}{f} + \frac{\omega f}{\sigma^2 X^2 Y^2} (L - \omega E),$$

$$\dot{\phi} = \frac{f}{\sigma^2 X^2 Y^2} (L - \omega E),$$
Figure 4. The behavior of the Kretschmann invariant $K_1$ as a function of $x$ is shown for the choice of parameters $a/M = 0.5$ and $q = 10$ for different values of $y$: (a) $y = 0$ and (b) $y = 0.5$. Part (c) shows instead the behavior of the Chern–Pontryagin invariant $K_2$ for the same choice of parameters as in (b). Parts (b) and (c) show how both the invariants $K_1$ and $K_2$ change their signs as $x$ approaches unity. This is a manifestation of the appearance of repulsive gravity regions, typical of naked singularity solutions. When $x \to \infty$, the invariants $K_1$ and $K_2$ both vanish, as expected.
Figure 5. The behavior of the real part of the speciality index $S$ as a function of $s$ is shown for the choice of parameters $a/M = 0.5$, $q = 10$ and $y = 0$. In this case ($y = 0$), we also have $\text{Im}(S) = 0$.

\[
\ddot{y} = -\frac{1}{2} \frac{Y^2}{X^2} \left[ \frac{f_y}{f} - 2 \gamma_y + \frac{2y}{X^2 + Y^2} \right] \dot{x}^2 + \left[ \frac{f_x}{f} - 2 \gamma_x - \frac{2x}{X^2 + Y^2} \right] \dot{y},
\]
\[
\dot{y}^2 = \frac{1}{2} \left[ \frac{f_y}{f} - 2 \gamma_y - \frac{2y}{X^2 + Y^2} \right] \dot{x}^2 - \frac{1}{2} \frac{e^{-2y}}{2 \sigma^2 X^2 Y^2 (X^2 + Y^2)} \left[ f^2 (L - \omega E)^2 + E^2 \sigma^2 X^2 Y^2 \right] f_y + 2 (L - \omega E) f^3 \left[ y (L - \omega E) - E Y^2 \omega_y \right],
\]
\[
\dot{x}^2 = -\frac{X^2}{Y^2} \dot{y}^2 + \frac{e^{-2y} X^2}{\sigma^2 (X^2 + Y^2)} \left[ E^2 - \mu^2 f - \frac{f^2}{\sigma^2 X^2 Y^2} (L - \omega E)^2 \right], \tag{4.1}
\]

where Killing symmetries and the normalization condition have been used. Here $E$ and $L$ are the energy and angular momentum of the test particle, respectively, $\mu$ is the particle mass and dot denotes differentiation with respect to the affine parameter; furthermore, the notation

\[
X = \sqrt{x^2 - 1}, \quad Y = \sqrt{1 - y^2} \tag{4.2}
\]

has been introduced.

Let us consider the motion on the symmetry plane $y = 0$. If $y = 0$ and $\dot{y} = 0$ initially, equation (4.1) ensures that the motion will be confined on the symmetry plane, since $f_y$, $\omega_y$, and $\gamma_y$ all vanish at $y = 0$, so that $\ddot{y} = 0$ too. Equations (4.1) thus reduce to

\[
i = \frac{E}{f} + \frac{\omega f}{\sigma^2 X^2} (L - \omega E), \quad \dot{\phi} = \frac{f}{\sigma^2 X^2} (L - \omega E),
\]
\[
\dot{x}^2 = \frac{e^{-2y} X^2}{\sigma^2 (1 + X^2)} \left[ E^2 - \mu^2 f - \frac{f^2}{\sigma^2 X^2} (L - \omega E)^2 \right]. \tag{4.3}
\]
Figure 6. The behavior of the effective potential \( V \) as a function of \( x \) is shown for the choice of parameters \( a/M = 0.5 \) and \( L/(\mu M) = 10 \) for different values of the quadrupole parameter: (a) \( q = 0 \), (b) \( q = 10 \) and (c) \( q = -10 \).

where metric functions are meant to be evaluated at \( y = 0 \). The motion turns out to be governed by the effective potential \( V \) defined by the equation

\[
V^2 - \mu^2 f - \frac{f^2}{\sigma^2 X^2} (L - \omega V)^2 = 0. \tag{4.4}
\]

In fact, for \( E = V \), the rhs of equation (4.3) vanishes.

The behavior of \( V \) as a function of \( x \) is shown in figure 6. Repulsive effects occur for decreasing values of \( x \) approaching \( x = 1 \). It is worth mentioning that the repulsive effect of the naked singularity has also been investigated by Herrera [22] in the case of a quasispherical spacetime but without taking into account the rotation of the source.

The case of a geodesic particle at rest will be analyzed below. Circular geodesics will be discussed in detail in the next section, where accelerated orbits are also studied.
4.1. Particle at rest

For the QM solution which is characterized by the presence of a naked singularity, it is even possible to satisfy the conditions for a geodesic particle to be at rest for certain values of the quadrupole moment. This effect can be explained when the attractive behavior of gravity is balanced by a repulsive force exerted by the naked singularity. Usually, repulsive effects are interpreted as a consequence of the presence of an effective mass which varies with distance and can thus become negative. The consideration of the corresponding post-Newtonian limit shows that an effective mass can be indeed introduced, depending on the distance from the source and the value of the Geroch–Hansen quadrupole moment [23]. We see that in the case of the corresponding exact solution under consideration a similar situation takes place.

A particle at rest is characterized by the four-velocity:

\[ U = \frac{1}{\sqrt{f}} \partial_t. \] (4.5)

The corresponding four-acceleration \( a(U) = \nabla_U U \) is given by

\[ a(U) = \frac{e^{-2\gamma}}{2\sigma^2(X^2 + Y^2)} [X^2 f_x \partial_x + Y^2 f_y \partial_y]. \] (4.6)

On the symmetry plane \( y = 0 \), we have \( f_y = 0 \), so that the geodesic condition \( a(U) = 0 \) implies \( f_x = 0 \). The pairs \((x, q)\) satisfying this condition are shown in figure 7 for a fixed value of \( a/M \). As an example, for \( a/M = 0.5 \) and \( q = 10 \) we get \( x \approx 1.588 \) as the equilibrium position. In this case the corresponding energy and angular momentum per unit mass of the particle are given by \( E/\mu \approx 0.553 \) and \( L/(\mu M) \approx 0.257 \), respectively. No equilibrium positions exist for \( q \leq 0 \).

Figure 7. The pairs \((x, q)\) allowing a test particle to be at rest in the QM spacetime are shown for \( a/M = 0.5 \). Part (b) is a detail of part (a) close to \( x = 1 \). No equilibrium positions exist for \( q \leq 0 \).
5. Circular orbits on the symmetry plane

Let us introduce the ZAMO (zero angular momentum observers) family of fiducial observers, with four-velocity:

\[ n = N^{-1}(\partial_t - N^\phi \partial_\phi); \]  

(5.1)

here \( N = (-g^{tt})^{-1/2} \) and \( N^\phi = g_{t\phi}/g^{\phi\phi} \) are the lapse and shift functions, respectively. A suitable orthonormal frame adapted to ZAMOs is given by

\[ e^t = n, \quad e^x = \frac{1}{\sqrt{g_{xx}}} \partial_x, \quad e^y = \frac{1}{\sqrt{g_{yy}}} \partial_y, \quad e^\phi = \frac{1}{\sqrt{g^{\phi\phi}}} \partial_\phi, \]  

(5.2)

with dual

\[ \omega^t = N dt, \quad \omega^x = \sqrt{g_{xx}} dx, \quad \omega^y = \sqrt{g_{yy}} dy, \quad \omega^\phi = \sqrt{g^{\phi\phi}} (d\phi + N^\phi dt). \]  

(5.3)

The four-velocity \( U \) of uniformly rotating circular orbits can be parametrized either by the (constant) angular velocity with respect to infinity \( \zeta \) or, equivalently, by the (constant) linear velocity \( \nu \) with respect to ZAMOs:

\[ U = \Gamma_1 [\partial_t + \zeta \partial_\phi] = \gamma (e^t + \nu e^\phi), \quad \gamma = (1 - \nu^2)^{-1/2}, \]  

(5.4)

where \( \Gamma_1 \) is a normalization factor which assures that \( U^\alpha U_\alpha = -1 \) given by

\[ \Gamma_1 = [N^2 - g_{\phi\phi}(\zeta + N^\phi)^2]^{1/2} = \frac{\nu}{N} \]  

(5.5)

and

\[ \zeta = -N^\phi + \frac{N}{\sqrt{g^{\phi\phi}}} \nu. \]  

(5.6)

We limit our analysis to the motion on the symmetry plane \( (y = 0) \) of the solution (1.1)–(1.5). Note both \( y = 0 \) and \( x = x_0 \) are constants along any given circular orbit, and that the azimuthal coordinate along the orbit depends on the coordinate time \( t \) or proper time \( \tau \) along that orbit according to

\[ \phi - \phi_0 = \zeta t = \Omega_U \tau_U, \quad \Omega_U = \Gamma \zeta, \]  

(5.7)

defining the corresponding coordinate and proper time orbital angular velocities \( \zeta \) and \( \Omega_U \).

These determine the rotation of the spherical frame with respect to a nonrotating frame at infinity.

The spacetime Frenet–Serret frame along a single timelike test particle worldline with four-velocity \( U = E_0 \) and parametrized by the proper time \( \tau_U \) is described by the following system of evolution equations [24]:

\[ \frac{DE_0}{d\tau_U} = \kappa E_1, \quad \frac{DE_1}{d\tau_U} = \kappa E_0 + \tau_1 E_2, \quad \frac{DE_2}{d\tau_U} = -\tau_1 E_1 + \tau_2 E_3, \quad \frac{DE_3}{d\tau_U} = -\tau_2 E_2. \]  

(5.8)

The absolute value of the curvature \( \kappa \) is the magnitude of the acceleration \( a(U) \equiv DU/d\tau_U = \kappa E_1 \), while the first and second torsions \( \tau_1 \) and \( \tau_2 \) are the components of the Frenet–Serret angular velocity vector:

\[ \omega_{\text{FS}} = \tau_1 E_3 + \tau_2 E_1, \quad \|\omega_{\text{FS}}\| = \left[ \tau_1^2 + \tau_2^2 \right]^{1/2}, \]  

(5.9)

with which the spatial Frenet–Serret frame \( \{E_0\} \) rotates with respect to a Fermi–Walker transported frame along \( U \). It is well known that any circular orbit on the symmetry plane of
Figure 8. The geodesic linear velocities $v_{(\text{geo})}^\pm$ are plotted in (a) as functions of the quadrupole parameter $q$ for a fixed distance parameter $x = 4$ from the source and $a/M = 0.5$. Co-rotating and counter-rotating circular geodesics exist for $q_1 < q < q_3$ and $q_2 < q < q_1$, respectively, with $q_1 \approx -105.59$, $q_2 \approx -36.29$ and $q_3 \approx 87.68$ for this choice of parameters. The behavior of $v_{(\text{geo})}^\pm$ as functions of $x$ is shown in (b) for different values of $q = \{-80, -30, -10, 0, 2, 4, 10, 50\}$. The thick curves correspond to the Kerr case ($q = 0$). Curves corresponding to a great positive value of the quadrupole parameter in the allowed range exhibit both a local maximum ($v_{(\text{geo})}^+$) and a local minimum ($v_{(\text{geo})}^-$). For decreasing values of $q$ the local minimum first disappears; for $q$ further decreasing also the local maximum disappears (the curves are thus ordered from left to right for increasing values of $q$). Curves corresponding to negative values of $q$ never present extrema as in the case of Kerr spacetime ($q = 0$), the lightlike condition being reached at greater values of the ‘radial’ distance for decreasing values of $q$.

A reflection symmetric spacetime has zero second torsion $\tau_2$, while the geodesic curvature $\kappa$ and the first torsion $\tau_1$ are simply related by

$$\tau_1 = -\frac{1}{2\gamma^2} \frac{d\kappa}{dv}. \quad (5.10)$$

On the symmetry plane there exists a large variety of special circular orbits [25–28]; particular interest is devoted to the co-rotating ($+$) and counter-rotating ($-$) timelike circular geodesics whose linear velocity is

$$v_{(\text{geo})}^\pm \equiv v_\pm = \frac{fC \pm [f^2\omega^2 - \sigma^2(x^2 - 1)]\sqrt{D}}{\sqrt{x^2 - 1}\sigma [f \omega_x [f^2\omega^2 + \sigma^2(x^2 - 1)] + 2f (f^2 \omega_x \sigma - \sigma^2 x)]}, \quad (5.11)$$

where

$$C = -2\sigma^2(x^2 - 1)\omega f_x - f [\omega_x [f^2\omega^2 + \sigma^2(x^2 - 1)] - 2\sigma^2 x \omega],$$
$$D = f^4\omega^2 - \sigma^2 f_x [f_x (x^2 - 1) - 2xf]. \quad (5.12)$$
Figure 9. The linear velocity $v_{(gmp)}$ corresponding to the ‘geodesic meeting point observers’ is plotted in (a) as a function of the quadrupole parameter $q$ for the fixed distance parameter $x = 4$ from the source and $a/M = 0.5$. The behavior of $v_{(gmp)}$ as a function of $x$ is shown in (b) for different values of $q = [-50, -10, 0, 2, 5, 10, 30, 80]$. It exists only in those ranges of $x$ where both $v^+_{(geo)}$ and $v^-_{(geo)}$ exist (solid black lines). These ranges are listed below: $q = -50, x \gtrsim 4.23$; $q = -10, x \gtrsim 3.36$; $q = 0, x \gtrsim 2.92$; $q = 2, 1.0012 \lesssim x \lesssim 1.13$ and $x \gtrsim 2.79$; $q = 5, 1.21 \lesssim x \lesssim 1.64$ and $x \gtrsim 2.48$; $q = 10, x \gtrsim 1.54$; $q = 50, x \gtrsim 2.44$; $q = 80, x \gtrsim 3.83$.

All quantities in the previous expressions are meant to be evaluated at $y = 0$. The corresponding timelike conditions $|v_\pm| < 1$ together with the reality condition $D \geq 0$ identify the allowed regions for the ‘radial’ coordinate where co-counter-rotating geodesics exist.

Other special orbits correspond to the ‘geodesic meeting point observers’ defined in [27], with

$$v_{(gmp)} = \frac{v_+ + v_-}{2}.$$ (5.13)

A Frenet–Serret (FS) intrinsic frame along $U$ [24] is given by

$$E_0 \equiv U = \gamma [n + ve_\phi], \quad E_1 = e_\zeta, \quad E_2 = e_\zeta, \quad E_3 \equiv E_\phi = \gamma [vn + e_\phi].$$ (5.14)

It is also convenient to introduce the Lie relative curvature of each orbit [27]:

$$k_{(lie)} = -\partial_t \ln \sqrt{\mathcal{g}_{\phi\phi}}$$

$$= e^{-\gamma} \sqrt{x^2 - 1} \left\{ \frac{\sigma^2 [(x^2 - 1) f_x - 2xf] + f^2 \omega (2f \omega_x + \omega f_x)}{\sigma^2 (x^2 - 1) - f^2 \omega_x^2} \right\}. \quad (5.15)$$

It then results in

$$\kappa = k_{(lie)} \gamma^2 (v - v_+)(v - v_-),$$

$$\tau_1 = k_{(lie)} v_{(gmp)} \gamma^2 (v - v_{(cri)}) (v - v_{(cri)-}),$$ (5.16)
The linear velocity $v_{(ext)}$ corresponding to the ‘extremely accelerated observers’ is plotted in (a) as a function of the quadrupole parameter $q$ for fixed distance parameter $x = 4$ from the source and $a/M = 0.5$. The behavior of $v_{(ext)}$ as a function of $x$ is shown in (b) for different values of $q = [-50, -10, 0, 5, 10, 30, 80]$. The dashed curve corresponds to the case $q = 0$. It exists only in those ranges of $x$ where both $v_{(geo)}$ and $v_{(geo)}$ exist (see figure 9).

where

$$v_{(crit)\pm} = \frac{\gamma - v_\pm + \gamma s v_s}{\gamma - \gamma s}, \quad v_{(crit)+} v_{(crit)-} = 1 \quad (5.17)$$

identify the so-called extremely accelerated observers [27, 29]: $v_{(ext)} \equiv v_{(crit)-}$, which satisfies the timelike condition in the regions where timelike geodesics exist, while $v_{(crit)+}$ is always spacelike there.

The geodesic velocities (5.11) are plotted in figure 8 both as functions of the quadrupole parameter $q$ for a fixed ‘radial’ distance (see (a)) and as functions of $x$ for different values of $q$ (see (b)). In the first case (a) we have shown how the quadrupole moment affects the causality condition: there exist a finite range of values of $q$ wherein timelike circular geodesics are allowed: $q_1 < q < q_3$ for co-rotating and $q_2 < q < q_3$ for counter-rotating circular geodesics. The critical values $q_1$, $q_2$, and $q_3$ of the quadrupole parameter can be (numerically) determined from equation (5.11). The difference from the Kerr case is clear instead from (b): the behavior of the velocities differs significantly at small distances from the source, whereas it is quite similar for large distances.

A similar discussion concerning the linear velocity $v_{(gmp)}$ of ‘geodesic meeting point observers’ as well as $v_{(ext)}$ of ‘extremely accelerated observers’ is given in figures 9 and 10, respectively.

The behaviors of both the acceleration $\kappa$ and the first torsion $\tau_1$ as functions of $v$ are shown in figures 11 and 12 for different values of the quadrupole parameter and fixed $x$ as well as for different values of the ‘radial’ distance and fixed $q$. A number of interesting effects do occur.
Figure 11. The acceleration $\kappa$ for circular orbits at $y = 0$ is plotted in part (a) as a function of $\nu$ for $a/M = 0.5$, $x = 4$ and different values of the quadrupole parameter: $q = [-500, -250, -100, 0, 80, 250, 500]$. The curves are ordered from top to bottom for increasing values of $q$. The values of $\nu$ associated with $\kappa = 0$ correspond to geodesics, i.e. $\nu^{\text{geo}}$. The behavior of $\kappa$ as a function of $\nu$ for different $x$ is shown in parts (b) and (c) for fixed values of the quadrupole parameter: (b) $q = 1$, $x = [1.1, 1.25, 1.5, 2.5, 4]$ and (c) $q = 100$, $x = [2.5, 3, 4, 10]$.

For instance, from figures 11(a) and (b) one recognizes certain counterintuitive behaviors of the acceleration, in comparison with our Newtonian experience. These effects have their roots also in the Kerr solution and are well known and studied since the 1990s [27]. For instance, for negative values of $q$ ($q = -500, -250$), we see that by increasing the speed $\nu$ (for positive values over that corresponding to the local minimum) the acceleration also increases; hence, in order to maintain the orbit, the particle (a rocket, say) should accelerate outward. This is counterintuitive in the sense that for a circular orbit at a fixed radius increasing the speed corresponds to an increase of the centrifugal acceleration and therefore to maintain the orbit
Figure 12. The first torsion $\tau_1$ for circular orbits at $y = 0$ is plotted as a function of $\nu$ for $a/M = 0.5$, $x = 4$ and different values of the quadrupole parameter: (a) $q = [0, 100, 250, 500, 750]$, (b) $q = [-1000, -750, -500, -250, -150]$ and (c) $q = [-150, -80, 0]$. The curves are ordered from left to right for increasing/decreasing values of $q$ in part (a)/part (b), respectively. Part (c) shows the changes of behavior occurring in the different regions $q < q_1$, $q_1 < q < q_2$ and $q > q_2$ (see figure 8).

‘classically’ one would expect to supply an acceleration inward. All such effects have been analyzed in the past decades in the Kerr spacetime as a function of the radius of the orbit, i.e. the distance from the black hole. The novelty here is represented by figure 11(a) where the various curves do not correspond to different orbital radii (i.e. different values of the coordinate $x$, as it is for the cases (b) and (c)), but to different values of the quadrupole parameter $q$ at a fixed radial distance. Therefore, the conclusion is that a spacecraft orbiting around an extended body—according to general relativity and the QM solution—should expect counterintuitive engine acceleration to remain on a given orbit. Outward or inward extra acceleration for an increase of the speed critically depends on the quadrupole moment (i.e. the physical structure) of the source, a fact that should be taken into account.
Figure 12 shows instead that at a fixed radius one can always find a value of the quadrupole parameter and a value of the speed at which the first torsion vanishes. Since the second torsion identically vanishes, in these conditions the Frenet–Serret frame becomes also a Fermi–Walker frame: in fact the Frenet–Serret angular velocity represents the rate of rotation of the Frenet–Serret frame with respect to a Fermi–Walker one. In [27] (see section 6, equation (6.22)), the precession of a test gyroscope (Fermi–Walker dragged along a circular orbit) has been related to the first torsion of an observer-adapted Frenet–Serret frame. The same discussion repeated here together with a simple inspection of figure 12 allows us to include the effects of the presence of the quadrupole parameter $q$.

6. Concluding remarks

In this work we investigated some properties of the QM spacetime which is a generalization of Kerr spacetime, including an arbitrary mass quadrupole moment. Our results show that a deviation from spherical symmetry, corresponding to a non-zero gravitoelectric quadrupole moment, completely changes the structure of spacetime. A similar behavior has been found in the case of the Erez–Rosen spacetime [30]. A naked singularity appears that affects the ergosphere and introduces regions where closed timelike curves are allowed. Whereas in the Kerr spacetime the ergosphere corresponds to the boundary of a simply connected region of spacetime, in the present case the ergosphere is distorted by the presence of the quadrupole and can even become transformed into multiply-connected regions. All these changes occur near the naked singularity.

The presence of a naked singularity leads to interesting consequences in the motion of test particles. For instance, repulsive effects can take place in a region very close to the naked singularity. In that region stable circular orbits can exist. The limiting case of static particle is also allowed, due to the balance of the gravitational attraction and the repulsive force exerted by the naked singularity.

We have studied the family of circular orbits on the symmetry plane of the QM solution, analyzing all their relevant intrinsic properties, namely Frenet–Serret curvature and torsions. We have also selected certain special circular orbits, like the ‘geodesic meeting points’ orbits (i.e. orbits which contain the meeting points of two oppositely rotating circular geodesics) and the ‘extremely accelerated’ orbits (i.e. orbits with respect to which the relative velocities of two oppositely rotating circular geodesics are opposite), whose kinematical characterization was given in the 1990s [27] with special attention to Kerr spacetime. Here we have enriched their properties specifying the dependence on the quadrupole parameter.

The question about the stability of the QM solution is important for astrophysical purposes. In this context, we have obtained some preliminary results by using the variational formulation of the perturbation problem as developed explicitly by Chandrasekhar [31] for stationary axisymmetric solutions. A numerical analysis performed for fixed values of the parameters entering the QM metric shows that it is unstable against perturbations that preserve axial symmetry. One can indeed expect that, once an instability sets in, the final state of gravitational collapse will be described by the Kerr spacetime, the multipole moments of the initial configuration decaying during the black hole formation. Nevertheless, a more detailed analysis is needed in order to completely establish the stability properties of this solution.

Finally, we mention the fact that it is possible to generalize the metric investigated in this work to include the case of a non-spherically symmetric mass distribution endowed with an electromagnetic field [32]. The resulting exact solution of Einstein–Maxwell equations turns out to be asymptotically flat, contains the Kerr–Newman black hole spacetime as a special case and is characterized by two infinite sets of gravitational and electromagnetic multipole
moments. For a particular choice of the parameters, the solution is characterized by the presence of a naked singularity. It would be interesting to explore repulsive effects generated by the electromagnetic field of the naked singularity also in this case. This task will be treated in a future work.

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Appendix A. General form of QM solution with arbitrary Zipoy–Voorhees parameter

The general form of QM solution with arbitrary Zipoy–Voorhees parameter $\delta$ is given by equation (1.1) with functions

$$f = \frac{R}{L} e^{-2qP_5 Q_2},$$
$$\omega = -2a - 2\sigma \frac{M}{R} e^{2qP_5 Q_2},$$
$$e^{2\gamma} = \frac{1}{4} \left(1 + \frac{M}{\sigma}\right)^2 \frac{R}{(x^2 - 1)^2} e^{2q\hat{\delta} \phi},$$

where $\hat{\delta}$ is the same as in equation (1.3), while

$$R = a_+ a_- + b_+ b_-, \quad L = a_+^2 + b_+^2,$$
$$M = (x + 1)^{\delta - 1} [x(1 - y^2)(\lambda + \mu)a_+ + y(x^2 - 1)(1 - \lambda + \mu)b_+].$$

The functions $a_\pm$ and $b_\pm$ are now given by

$$a_\pm = (x \pm 1)^{\delta - 1} [x(1 - \lambda + \mu) \pm (1 + \lambda + \mu)],$$
$$b_\pm = (x \pm 1)^{\delta - 1} [x(\lambda + \mu) \mp (\lambda - \mu)],$$

with

$$\lambda = \alpha (x^2 - 1)^{1-\delta} (x + y)^{2-\delta} e^{2q\delta \phi},$$
$$\mu = \alpha (x^2 - 1)^{1-\delta} (x - y)^{2-\delta} e^{2q\delta \phi}.$$

The functions $\delta_\pm$ and the constants $\alpha$ and $\sigma$ are instead the same as in equations (1.4) and (1.5), respectively.

This solution reduces to the solution (1.1)–(1.5) for $\delta = 1$.

Appendix B. Newman–Penrose quantities

Let us adopt here the metric signature $(+, -, -, -)$ in order to use the Newman–Penrose formalism in its original form and then easily get the necessary physical quantities [31]. The Weyl–Lewis–Papapetrou metric is thus given by

$$\text{d}s^2 = f (\text{d}t - \omega \text{d}\phi)^2 - \frac{\sigma^2}{f} \left[ e^{2\gamma} (x^2 - y^2) \left( \frac{\text{d}x^2}{x^2 - 1} + \frac{\text{d}y^2}{1 - y^2} \right) + (x^2 - 1)(1 - y^2) \text{d}\phi^2 \right].$$

(B.1)
Introduce the following tetrad:

\[
\begin{align*}
I &= \sqrt{\frac{f}{2}} \left[ dt \left( \omega + \frac{\sigma XY}{f} \right) d\phi \right], \\
N &= \sqrt{\frac{f}{2}} \left[ dt \left( \omega - \frac{\sigma XY}{f} \right) d\phi \right], \\
M &= \frac{1}{\sqrt{2}} \sqrt{\frac{\sigma}{f}} e^{\nu} \sqrt{X^2 + Y^2} \left[ \frac{dx}{X} + i \frac{dy}{Y} \right],
\end{align*}
\]

where

\[
X = \sqrt{x^2 - 1}, \quad Y = \sqrt{1 - y^2}.
\]

The nonvanishing spin coefficients are

\[
\begin{align*}
\kappa &= -A \left[ -\frac{XY}{f} (X f_x + iY f_y) + \frac{f}{\sigma} (X \omega_x + iY \omega_y) + xY - iyX \right], \\
\tau &= -\pi^* = \frac{A}{\sigma} (xY - iyX), \\
\nu &= -A \left[ \frac{XY}{f} (X f_x - iY f_y) + \frac{f}{\sigma} (X \omega_x - iY \omega_y) - xY - iyX \right], \\
\alpha &= AXY \sigma^4 \left[ -\frac{1}{2f} (X f_x - iY f_y) + X \gamma_x - iY \gamma_y - \frac{f}{2\sigma} \left( \frac{\omega_x}{Y} - 1 \frac{\omega_y}{X} \right) + \frac{xX + iyY}{X^2 + Y^2} \right], \\
\beta &= AXY \sigma^4 \left[ \frac{1}{2f} (X f_x + iY f_y) - X \gamma_x - iY \gamma_y - \frac{f}{2\sigma} \left( \frac{\omega_x}{Y} + 1 \frac{\omega_y}{X} \right) - \frac{xX - iyY}{X^2 + Y^2} \right],
\end{align*}
\]

The nonvanishing Weyl scalars are

\[
\psi_0 = AXY \left[ \tau (X f_x + iY f_y) + 2f (X \kappa_x + iY \kappa_y) - \frac{f^2}{\sigma XY} (\kappa + \tau)(X \omega_x + iY \omega_y) \right] + 2\kappa\beta + \tau (\kappa - \tau), \\
\psi_2 = \frac{1}{6} A^2 X^2 Y^2 \frac{f}{\sigma} \left[ \frac{f}{\sigma} \left( f_x \omega_y - f_y \omega_x \right) - X^2 (f_{xx} - 2f \gamma_{xx}) \\ + 3i \frac{f}{\sigma} (f_x \omega_y - f_y \omega_x) - X^2 (f_{xx} - 2f \gamma_{xx}) - Y^2 (f_{yy} - 2f \gamma_{yy}) + \frac{f^3}{\sigma^2} \left( \frac{\omega_x}{Y} + \frac{\omega_y}{X} \right) \right], \\
\psi_4 = AXY \left[ -\pi (X f_x - iY f_y) + 2f (X \nu_x - iY \nu_y) - \frac{f^2}{\sigma XY} (\nu + \pi)(X \omega_x - iY \omega_y) \right] + 2i\alpha + \pi (\nu - \pi).
\]

Finally the two scalar invariants of the Weyl tensor whose ratio defines the speciality index have the following expressions in terms of the Newman–Penrose curvature quantities:

\[
I = \psi_0 \psi_4 + 3\psi_2^2, \quad J = \psi_0 \psi_2 - \psi_2^3, \quad S = \frac{27 f^2}{I^3}.
\]
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