Area estimates and rigidity of capillary $H$–surfaces in three-manifolds with boundary

José M. Espinar† and Harold Rosenberg‡

† Instituto de Matematica Pura y Aplicada, 110 Estrada Dona Castorina, Rio de Janeiro 22460-320, Brazil; e-mail: jespinar@impa.br
‡ Instituto de Matematica Pura y Aplicada, 110 Estrada Dona Castorina, Rio de Janeiro 22460-320, Brazil; e-mail: rosen@impa.br

Abstract

We obtain a bound for the area of a capillary $H$–surface in a three-manifold with umbilic boundary and controlled sectional curvature. We then analyze the geometry when this area bound is realized, and obtain rigidity theorems. As a side product, we obtain existence of totally geodesic embedded surfaces in hyperbolic three-manifolds under the assumption of the existence of a $H$–surface realizing the area bound, in particular, under the existence of a totally umbilic $H$–surface.

Key Words: Capillary surfaces; Rigidity of three-manifold with boundary; hyperbolic manifold with boundary.

1 Introduction

In a recent paper, L. Mazet and H. Rosenberg [5] showed that a minimal two sphere $\Sigma$ satisfies a lower area bound when immersed in a Riemannian manifold of sectional curvatures bounded between 0 and 1. Moreover, in the case that equality is achieved, they were able to characterize the Riemannian manifold and the two sphere as either the standard three sphere $S^3$ with $\Sigma$ totally geodesic or a quotient of the product manifold $S^2 \times \mathbb{R}$ endowed with the standard product metric with $\Sigma$ and $S^2 \times \{t\}$. These results were motivated by Klingenberg’s length estimate for closed geodesics in Riemannian surfaces of curvature between 0 and 1, and Calabi’s characterization theorem when the equality is achieved (cf. [6]). The authors [5] also proved a rigidity result for hyperbolic cusps.
In this note, we will extend the area estimate and rigidity results to capillary surfaces of constant mean curvature immersed in a Riemannian manifold with umbilic boundary and controlled sectional curvatures. In the past few years, other area estimates have been established under different hypothesis on the surfaces, for example free boundary surfaces, or in the Riemannian manifolds, for example a bound on the scalar curvature. We invite the reader to see the papers of L. Ambrozio [1], S. Brendle [2], A. Fraser and R. Schoen [3] and F. Marques and A. Neves [4].

2 Notation

First, we will fix the notation we will use along the paper.

Let \((M, \partial M)\) be a complete Riemannian 3−manifold with boundary and Riemannian metric \(\langle \cdot, \cdot \rangle\). Denote by \(\nabla\) the Levi-Civita connection associated to \(\langle \cdot, \cdot \rangle\) in \(M\), \(K_{sec}\) its sectional curvatures and \(Ric\) the Ricci tensor.

Let \(\eta\) be the inward unit normal along \(\partial M\). We say that \(\partial M\) is umbilic, with umbilicity factor \(\alpha \in \mathbb{R}\), if \(II_{\partial M} = \alpha I_{\partial M}\), where \(I_{\partial M}\) and \(II_{\partial M}\) are the first and second fundamental forms of \(\partial M\) in \(M\). Here, the second fundamental form is computed with respect to the inward orientation \(\eta\), i.e.,

\[
II_{\partial M}(X, Y) = -\langle \nabla_X \eta, Y \rangle, \quad X, Y \in \mathfrak{X}(\partial M),
\]

in particular, \(\partial M\) is totally geodesic if \(\alpha = 0\). Along this paper, \(\eta\) will always stand by the inward normal along \(\partial M\).

Now, let \(\Sigma\) be an oriented compact surface with boundary \(\partial \Sigma\) and unit normal \(N\), \(N\) chosen so that \(\|\vec{H}\| N = \vec{H}\) when \(\vec{H} \neq 0\); \(\vec{H} = 2HN\), where \(\vec{H}\) and \(H\) are the mean curvature vector and mean curvature function respectively. If \(H\) is constant along \(\Sigma\), we say that \(\Sigma\) is a \(\vec{H}\)−surface.

Also, denote by \(II_{\Sigma}\) the second fundamental form of \(\Sigma\) in \(M\) with respect to \(N\) and by \(K_e\) and \(K_\Sigma\) its extrinsic and Gaussian curvature, the extrinsic curvature \(K_e\) is nothing but the product of the principal curvatures. Associated to the mean and extrinsic curvatures one can define the skew curvature as \(\Phi = \sqrt{H^2 - K_e}\) that measures how far the surface is from being umbilic. Throughout this paper, we will denote by \(|\Sigma|\) and \(|\partial \Sigma|\) the area of \(\Sigma\) and the length of \(\partial \Sigma\) respectively.

We assume that \(\Sigma \subset M\) and \(\partial \Sigma \subset \partial M\). We say that \(\Sigma\) is a capillary surface of angle \(\beta\) in \(M\) if the outer conormal \(\nu\) along \(\partial \Sigma\) and the unit normal along \(\partial M\) make a constant angle \(\beta\) along \(\partial \Sigma\), i.e., there exists a constant \(\beta \in [0, \pi/2)\) so that \(\langle \nu, \eta \rangle = -\cos \beta\). In particular, when \(\beta = 0\) or, equivalently, \(\Sigma\) meets orthogonally \(\partial M\), we say that \(\Sigma\) is a free boundary surface.
3 Outline of the paper: results and examples

We obtain a lower bound for the area of a capillary $H$—disk immersed in a Riemannian 3—manifold of sectional curvatures between 0 and 1. We prove

**Lemma 4.1.** Let $(\mathcal{M}, \partial \mathcal{M})$ be a complete orientable Riemannian 3—manifold with boundary. Let $\Sigma \subset \mathcal{M}$ be a compact oriented $H$—disk ($H \geq 0$) with boundary $\partial \Sigma \subset \partial \mathcal{M}$. Assume that

- The sectional curvatures of $\mathcal{M}$ satisfy $K_{\text{sect}} \leq 1$,
- $\partial \mathcal{M}$ is umbilic, with umbilicity factor $\alpha \in \mathbb{R}$,
- $\Sigma$ is a capillary disk of angle $\beta \in [0, \pi/2)$,

then,

$$2\pi \leq (1 + H^2) |\Sigma| + \frac{\alpha + (H + \max_{\partial \Sigma} \Phi) \sin \beta}{\cos \beta} |\partial \Sigma|.$$ 

Moreover, equality holds if, and only if, $\Sigma$ is umbilic, $K_{\Sigma} = 1 + H^2$ and $K_{\text{sect}} \equiv 1$ along $\Sigma$.

When $\Sigma$ is a free boundary disk and $\partial \mathcal{M}$ is totally geodesic, the above inequality reads as

$$2\pi \leq (1 + H^2) |\Sigma|$$

and equality holds if, and only if, $\Sigma$ is umbilic, $K_{\Sigma} = 1 + H^2$ and $K_{\text{sect}} \equiv 1$ along $\Sigma$.

Now, let us describe the model cases of Riemannian manifolds $(\mathcal{M}, \partial \mathcal{M})$ where free boundary disks achieve the equality. In this case we have two different models:

- **Model 1:** Let $\mathbb{S}^3 \subset \mathbb{R}^4$ be the standard unit three-sphere embedded in the four dimensional Euclidean Space with the standard Euclidean metric $\langle \cdot, \cdot \rangle_0$. Then, the upper hemisphere, given by

$$\mathbb{S}^3_+ := \left\{ (x_1, x_2, x_3, x_4) \in \mathbb{S}^3 : x_4 \geq 0 \right\},$$

is a complete manifold with constant sectional curvatures equal to 1 and totally geodesic boundary

$$\partial \mathbb{S}^3_+ = \left\{ (x_1, x_2, x_3, x_4) \in \mathbb{S}^3 : x_4 = 0 \right\},$$

which is isometric to a two-sphere $\mathbb{S}^2$. From now on, we denote by $\mathbb{S}^n(r)$ the standard $n$—dimensional sphere of constant sectional curvatures $1/r^2$.

For any $x \in \partial \mathbb{S}^3_+$, let $\mathcal{B}_x(R)$ be the geodesic ball of the standard three-sphere $\mathbb{S}^3$ centered at $x$ of radius $R$. Fix $H \geq 0$ a constant and set $R_H = \frac{\pi}{2} - \arctg H$. Then, we have

$$D_H := \partial \mathcal{B}_x(R_H) \cap \mathbb{S}^3_+$$
is a umbilic $H$–disk orthogonal to $\partial S^3_+$ such that

$$|D_H| = \frac{2\pi}{1 + H^2}.$$  

- **Model 2:** Let $S^2_+$ be the upper hemisphere of the standard 2–sphere, i.e.,

$$S^2_+ := \{(x_1, x_2, x_3) \in S^2 : x_3 \geq 0\}.$$  

Clearly, $\mathbb{R} \times S^2_+$ endowed with the standard product metric is a complete manifold with sectional curvatures between 0 and 1 and totally geodesic boundary

$$\partial (\mathbb{R} \times S^2_+) = \mathbb{R} \times \partial S^2_+.$$  

For any $t \in \mathbb{R}$, $D_t = \{t\} \times S^2_+$ is a totally geodesic minimal disk orthogonal to $\mathbb{R} \times \partial S^2_+$ such that

$$|D_t| = 2\pi.$$  

The conclusion of the rigidity result says that, under the existence of a free boundary $H$–disk achieving the equality, the manifold $M$ must be locally isometric to one of the models above.

**Theorem 4.1.** Let $(M, \partial M)$ be a complete orientable Riemannian 3–manifold with boundary. Assume that $M$ has sectional curvatures $0 \leq K_{\text{sect}} \leq 1$ and $\partial M$ is connected and totally geodesic. If there exists a compact oriented embedded $H$–disk $\Sigma \subset M$ orthogonal to $\partial M$ such that

$$|\Sigma| = \frac{2\pi}{1 + H^2}.$$  

Then:

- If $H > 0$, the mean convex side of $M \setminus \Sigma$, call this component $\mathcal{U}$, is isometric to $B_x(R_H) \cap S^3_+ \subset S^3$ with the standard metric, $R_H = \frac{\pi}{2} - \arctg H$ and $x \in \partial S^3_+$. Moreover, $\Sigma$ is a disk $D_H$ described in the Model 1.

- If $H = 0$, $M$ is isometric either to $S^3_+$ with its standard metric of constant sectional curvature one, or a quotient of $\mathbb{R} \times S^2_+$ with the standard product metric. Moreover, $\Sigma$ is a disk $D_H$ or $D_t$ as described in the Models 1 and 2.

Section 5 is devoted to capillary $H$–surfaces immersed in a complete manifold with sectional curvatures less or equal to $-1$ and umbilic boundary. We first obtain an area bound.
Lemma 5.1. Let \( (\mathcal{M}, \partial \mathcal{M}) \) be a complete orientable Riemannian 3–manifold with boundary. Let \( \Sigma \subset \mathcal{M} \) be a compact oriented \( H \)–surface \((H \geq 0)\) with boundary \( \partial \Sigma \subset \partial \mathcal{M} \). Assume that

- The sectional curvatures of \( \mathcal{M} \) satisfy \( K_{\text{sect}} \leq -1 \),
- \( \partial \mathcal{M} \) is umbilic, with umbilicity factor \( \alpha \in \mathbb{R} \),
- \( \Sigma \) is a capillary surface of angle \( \beta_i \in [0, \pi/2) \) at each connected component \( \partial \Sigma_i \) of the boundary \( \partial \Sigma \),

then,

\[
-2\pi \chi(\Sigma) + \sum_{i=1}^{k} \frac{\alpha + \sin \beta_i (H + \max_{\partial \Sigma} \Phi))}{\cos \beta_i} |\partial \Sigma_i| \geq (1 - H^2) |\Sigma|,
\]

where \( k \) is the number of connected components of \( \partial \Sigma \). Moreover, equality holds if, and only if, \( \Sigma \) is umbilic, \( K_\Sigma = H^2 - 1 \) and \( K_{\text{sect}} \equiv -1 \) along \( \Sigma \).

As we did in Section 4, we will describe the model cases when the equality is achieved by a free boundary \( H \)–surface, \( H \in [0, 1] \), in a complete manifold with \( K_{\text{sect}} \leq -1 \) and totally geodesic boundary.

In both cases, \( H = 1 \) and \( H \in [0, 1) \), \( \mathcal{M} \) will be a hyperbolic manifold with totally geodesic boundary and \( \Sigma \) will be a constant intrinsic curvature umbilical \( H \)–surface orthogonal to \( \partial \mathcal{M} \).

Model 3: We begin with the case \( H \in [0, 1) \). Let \( S \) be a closed oriented surface of curvature \( -1 \). \( S \) is a quotient of \( \mathbb{H}^2 \) by a cocompact Fuchsian group \( \Gamma \) of isometries of \( \mathbb{H}^2 \). Consider \( P_0 = \mathbb{H}^2 \) as isometrically embedded in \( \mathbb{H}^3 \) as a totally geodesic plane, with \( n \) a unit normal vector field to \( P_0 \) in \( \mathbb{H}^3 \).

We parametrize \( \mathbb{H}^3 \) in Fermi coordinates by \( F: \mathbb{R} \times P_0 \to \mathbb{H}^3 \), where

\[
F(t, x) := \exp_x(tn(x)),
\]

here \( \exp \) denotes the exponential map in \( \mathbb{H}^3 \). The metric of \( \mathbb{H}^3 \) in these coordinates is \( dt^2 + \cosh^2(t)g_{-1} \), where \( g_{-1} \) is the standard hyperbolic metric of curvature \( -1 \). Observe that

\[
P_t := \{ F(t, x) : x \in H_0 \}
\]

is an equidistant surface of \( P_0 \) of constant mean curvature \( \tgh(t) \).

The group \( \Gamma \) extends to isometries of \( \mathbb{H}^3 \): for \( \gamma \in \Gamma \), \( t \in \mathbb{R} \) and \( x \in H_0 \), define

\[
\gamma(F(t, x)) = F(t, \gamma(x)).
\]
The extended action leaves each $P_t$ invariant and $P_t/\Gamma = S_t$ is a constant sectional curvature umbilical surface in $\mathbb{H}^3/\Gamma$. $\mathcal{N} = \mathbb{H}^3/\Gamma$ is homeomorphic to $\mathbb{R} \times S$.

Let $\beta$ be a simple closed geodesic of $S$; $\beta$ lifts to a complete geodesic $\tilde{\beta}$ of $P_0$. $F(\mathbb{R} \times \tilde{\beta})$ is a totally geodesic plane in $\mathbb{H}^3$ which quotients to a totally geodesic annulus $A(\tilde{\beta})$ in $\mathcal{N}$.

Let $\beta_1, \ldots, \beta_k$, where $k$ is the genus of $S$, be pairwise disjoint simple closed geodesics of $S$, separating $S$ in two components. Let $\Sigma_0$ be one of the components. $\Sigma_0$ lifts to $\tilde{\Sigma}_0 \subset P_0$, $\tilde{\Sigma}_0$ bounded by $\bigcup_{i=1}^k \tilde{\beta}_i$. Note that $F_t(\tilde{\Sigma}_0) = F(t, \tilde{\Sigma}_0) \subset P_t$ is a constant intrinsic curvature surface, of constant mean curvature $\tgh(t)$. The boundary of $F_t(\tilde{\Sigma}_0)$ meets the totally geodesic planes $F(\mathbb{R} \times \tilde{\beta}_i)$ orthogonally.

The quotient of $M = \left\{ F_t(\tilde{\Sigma}_0) : t \in \mathbb{R} \right\}$ is then a hyperbolic three manifold $\mathcal{M} = M/\Gamma$, of constant sectional curvatures $-1$, bounded by totally geodesic annuli $\partial \mathcal{M} = \bigcup_{i=1}^k A(\beta_i)$. $\mathcal{M}$ is foliated by the equidistant surfaces $\Sigma_t$, the quotient of $F_t(\tilde{\Sigma}_0)$. Each $\Sigma_t$ meets $\partial \mathcal{M}$ orthogonally. Moreover, the mean curvature of $\Sigma_t$ is given by $H = \tgh(t)$, $t \geq 0$.

Observe that the totally umbilic surface $\Sigma_t$, $t \geq 0$, separates $\mathcal{N}/\Gamma$ into two components, say $\mathcal{H}_t$ is the mean convex side. Note that the mean curvature vector along $\Sigma_t$ points into the component where $\Sigma_0$ is contained. When $t = 0$ and $\Sigma_0$ is minimal, both components are isometric and we denote the component containing $\Sigma_t$, for $t > 0$, as $\mathcal{H}_t$. Finally, we will denote by $\mathcal{H}(t) = \mathcal{H}_0 \cap \mathcal{H}_t$, for all $t > 0$. Observe that $\mathcal{H}(t)$ is nothing but the connected component of $\mathcal{M} \setminus (\Sigma_0 \cup \Sigma_t)$ whose boundary is mean convex.

**Model 4:** Finally, we describe the case $H = 1$. Consider a horosphere $H_0$ of $\mathbb{H}^3$ and a $\mathbb{Z}^2$ group $\Gamma$ of parabolic isometries leaving $H_0$ invariant. Let $n$ be a unit normal vector field to $H_0$ in $\mathbb{H}^3$, pointing to the mean convex side of $H_0$. $\mathbb{H}^3$ has the Fermi coordinates $F : \mathbb{R} \times H_0 \to \mathbb{H}^3$, where

$$F(t, x) := \exp_x(tn(x)),$$

here $\exp$ denotes the exponential map in $\mathbb{H}^3$. The metric of $\mathbb{H}^3$ in these coordinates is $dt^2 + e^{2t}g_e$, where $g_e$ is the standard Euclidean metric of curvature $0$.

As before, $\Gamma$ acts on $\mathbb{H}^3$, leaving each horosphere

$$\mathcal{H}_t = \{ F(t, x) : x \in H_0 \}$$

invariant. Each $\mathcal{H}_t$ has mean curvature 1. $\mathcal{N} = \mathbb{H}^3/\Gamma$ is a hyperbolic three manifold of constant sectional curvatures $-1$ isometric to $\mathbb{R} \times \mathbb{T}^2$ with the metric $dt^2 + e^{-2t}g_e$, where $g_e$ is the standard flat metric of $\mathbb{T}^2 = H_0/\Gamma$, a 2—torus.

Let $\beta_1$ and $\beta_2$ be disjoint simple closed geodesics of $\mathbb{T}^2$, and let $\Sigma_0$ be one of the annuli of $\mathbb{T}^2$ bounded by $\beta_1 \cup \beta_2$. $\Sigma_0$ lifts to $\tilde{\Sigma}_0 \subset H_0$, $\tilde{\Sigma}_0$ bounded by $\tilde{\beta}_1 \cup \tilde{\beta}_2$, where $\tilde{\beta}_i$ is the lift of $\beta_i$ to $H_0$, a horocycle for each $i = 1, 2$. Note that $F_t(\tilde{\Sigma}_0) = F(t, \tilde{\Sigma}_0) \subset H_t$ is a flat
surface, of constant mean curvature 1. The boundary of \( F_t(\tilde{\Sigma}_0) \) meets the totally geodesic planes \( F(\mathbb{R} \times \beta_i) \) orthogonally, \( i = 1, 2 \).

The quotient of \( M = \left\{ F_t(\tilde{\Sigma}_0) : t \in \mathbb{R} \right\} \) is then a hyperbolic three manifold \( \mathcal{M} = M/\Gamma \) with totally geodesic boundary \( \partial \mathcal{M} = \bigcup_{i=1}^2 F(\mathbb{R} \times \tilde{\beta}_i)/\Gamma \). \( \mathcal{M} \) is foliated by the equidistant surfaces \( \Sigma_t \), the quotient of \( F_t(\tilde{\Sigma}_0) \). Each \( \Sigma_t \) meets \( \partial \mathcal{M} \) orthogonally. Each \( \Sigma_t = F(t, \tilde{\Sigma}_0)/\Gamma \) is a flat constant mean curvature one annulus meeting \( \partial \mathcal{M} \) orthogonally.

Observe that the flat torus \( \Sigma_0 \) separates \( \mathcal{N} \) into two components. We denote by \( P \) the mean convex side of \( \Sigma \), which is parabolic.

The conclusion of the rigidity result in this case is quite surprising under the existence of a free boundary \( H \)–surface \( \Sigma, H \in (0, 1) \), achieving the equality in the area estimate. It says that we can find an embedded totally geodesic minimal surface \( \Sigma_m \) orthogonal to \( \partial \mathcal{M} \) in the mean convex side of \( \mathcal{M} \setminus \Sigma \) such that a domain in \( \mathcal{M} \setminus \Sigma \) must be isometric to the model \( \mathcal{H}(t) \) constructed above, whose boundary components are isometric to \( \Sigma \) and \( \Sigma_m \). When \( H = 1 \), the mean convex side of \( \mathcal{M} \setminus \Sigma \) is isometric to the model \( \mathcal{P} \), and \( \Sigma \) is one of the \( \Sigma_t \), as expected. Specifically,

**Theorem 5.1.** Let \( (\mathcal{M}, \partial \mathcal{M}) \) be a complete orientable Riemannian 3–manifold with boundary. Assume that \( \mathcal{M} \) has sectional curvatures \( K_{\text{sect}} \leq -1 \) and \( \partial \mathcal{M} \) is totally geodesic. Assume that there exists a compact oriented embedded \( H \)–surface \( \Sigma \subset \mathcal{M}, H \in (0, 1] \), orthogonal to \( \partial \mathcal{M} \) with non-positive Euler characteristic. Then:

- If \( H \in (0, 1) \), \( \Sigma \) separates and \( |\Sigma| = \frac{2\pi |\chi(\Sigma)|}{1 - H^2} \), \( \chi(\Sigma) < 0 \), then there exists a totally geodesic minimal surface \( \Sigma_m \), orthogonal to \( \partial \mathcal{M} \) and an isometry

\[
F : \left( [0, \text{arctgh} \, H] \times \Sigma, dt^2 + \cosh^2 (t \, g_{-1}) \right) \to \mathcal{M},
\]

where \( g_{-1} \) denotes the standard metric of constant curvature \(-1\), such that

- \( F(0, \Sigma) = \Sigma \) and \( F(\text{arctgh} \, H, \Sigma) = \Sigma_m \), and
- \( F(t, \Sigma) = \Sigma_t \) is an embedded totally umbilic \( H \)–surface, \( H = \text{tgh}(\text{arctgh} \, H - t) \), orthogonal to \( \partial \mathcal{M} \) for all \( t \in [0, \text{arctgh} \, H] \).

Moreover, if \( \Sigma_m \) is non-orientable, a tubular neighborhood of \( \Sigma_m \) is foliated by its equidistants \( \Sigma_t \).

- If \( H = 1 \) and \( \chi(\Sigma) = 0 \), the mean convex side of \( \mathcal{M} \setminus \Sigma \), call this component \( \mathcal{U} \), is isometric to \( [0, +\infty) \times \Sigma \) endowed with the product metric \( g = dt^2 + e^{-2t} g_e \), where \( g_e \) is the standard Euclidean metric of curvature \( 0 \). That is, \( \mathcal{U} \) is isometric to a cusp hyperbolic end \( \mathcal{P} \) corresponding to Model 4 and \( \Sigma \) is a slice.
The results above extend to compact $H-$surfaces without boundary. The area estimate takes the following form

**Lemma 5.2.** Let $\mathcal{M}$ be a complete orientable Riemannian 3–manifold with sectional curvatures $K_{\text{sect}} \leq -1$. Let $\Sigma \subset \mathcal{M}$ be a closed oriented $H-$surface, $H \in (0,1)$, of genus $g(\Sigma) \geq 2$. Then,

$$4\pi(g(\Sigma) - 1) \geq (1 - H^2) |\Sigma| .$$

Moreover, equality holds if, and only if, $\Sigma$ is umbilic, $K_{\Sigma} = H^2 - 1$ and $K_{\text{sect}} \equiv -1$ along $\Sigma$.

As a first consequence of the above area estimate we have that, when $H^2 < 1$, $\Sigma$ has genus at least two. Observe that Model 3 has a counterpart without boundary. Let $S$ be the quotient of $\mathbb{H}^2$ by a cocompact Fuchsian group $\Gamma$ of isometries of $\mathbb{H}^2$. Consider Fermi coordinates $F : \mathbb{R} \times P_0 \to \mathbb{H}^3$, where $P_0 \equiv \mathbb{H}^2$ is a isometrically embedded totally geodesic plane in $\mathbb{H}^3$.

**Model 5:** $\mathcal{M} = \{F_t(P_0) : t \in \mathbb{R}\}/\Gamma$ is a complete hyperbolic three-manifold without boundary. One can see that $\mathcal{M}$ is foliated by the equidistant surfaces $\Sigma_t$, the quotient of $F_t(\tilde{\Sigma}_0)$. Each $\Sigma_t$ is a constant intrinsic curvature surface, of constant mean curvature $\text{tgh}(t)$.

Again, $\Sigma_t$, which is a totally umbilic surface, separates $\mathcal{M}$ into two components. As we did in Model 3, we will denote by $\tilde{\mathcal{H}}(t)$, $t > 0$, the connected component of $\mathcal{M}\setminus(\Sigma_0 \cup \Sigma_t)$ whose boundary is mean convex.

In the case we get the equality in the area estimate above, we can obtain the existence of an embedded totally geodesic surface.

**Theorem 5.2.** Let $\mathcal{M}$ be a complete orientable Riemannian 3–manifold with sectional curvatures $K_{\text{sect}} \leq -1$. Assume that there exists a compact oriented embedded $H-$surface $\Sigma \subset \mathcal{M}$, $H \in (0,1)$, $\Sigma$ separates $\mathcal{M}$, with negative Euler characteristic such that

$$|\Sigma| = \frac{2\pi |\chi(\Sigma)|}{1 - H^2} ,$$

then there exists an embedded totally geodesic minimal surface $\Sigma_m$ and an isometry $F : ([0, \text{arctgh} H] \times \Sigma, dt^2 + \cosh^2(t) \ g_{-1}) \to \mathcal{M}$, where $g_{-1}$ denotes the standard metric of constant curvature $-1$, such that

- $F(0, \Sigma) = \Sigma$ and $F(\text{arctgh} H, \Sigma) = \Sigma_m$, and
\( F(t, \Sigma) = \Sigma_t \) is an embedded totally umbilic \( H \)–surface, \( H = \tgh(\arctgh H - t), \) for all \( t \in (0, \arctgh H) \).

Moreover, if \( \Sigma_m \) is non-orientable, a tubular neighborhood of \( \Sigma_m \) is foliated by its equidistants \( \Sigma_t \).

Remark 3.1. The case \( H = 1 \) was done by L. Mazet and H. Rosenberg in [5].

It is remarkable that the minimal case can not be classified. Observe that any embedded totally geodesic surface in a hyperbolic three-manifold satisfy the area estimate given above and, at a first glance, we have no chance to know the structure of the three-manifold. Nevertheless, the above result says that the existence of a totally umbilic \( H \)–surface \( \Sigma \) embedded in a hyperbolic three-manifold determines the mean convex side up to we reach a totally geodesic surface.

4 Manifolds with umbilic boundary and \( 0 \leq K_{\text{sect}} \leq 1 \)

In this section we will study capillary \( H \)–disks immersed in a three-manifold with umbilic boundary and sectional curvatures between 0 and 1. First, we obtain a lower bound for the area of such a capillary \( H \)–disk. Second, we obtain rigidity of the three-manifold with boundary assuming that the \( H \)–disk is orthogonal to the boundary of the three-manifold and achieves the bound for the area. In the latter case, we assume the boundary of the three-manifold is totally geodesic.

4.1 Area estimate

In this section, we will obtain a lower bound for the area of a capillary \( H \)–disk immersed in a Riemannian 3–manifold whose boundary is contained in the boundary of the manifold. Such a lower bound will depend on the sectional curvatures of the 3–manifold, the second fundamental form of the boundary of the 3–manifold, the mean curvature of the \( H \)–disk and the length of the boundary of the disk. Let us now be more precise.

Lemma 4.1. Let \((M, \partial M)\) be a complete orientable Riemannian 3–manifold with boundary. Let \( \Sigma \subset M \) be a compact oriented \( H \)–disk \((H \geq 0)\) with boundary \( \partial \Sigma \subset \partial M \). Assume that

- The sectional curvatures of \( M \) satisfy \( K_{\text{sect}} \leq 1 \),
- \( \partial M \) is umbilic, with umbilicity factor \( \alpha \in \mathbb{R} \),
- \( \Sigma \) is a capillary disk of angle \( \beta \in [0, \pi/2) \),
then,
\[ 2\pi \leq (1 + H^2) |\Sigma| + \frac{\alpha + (H + \max_{\partial \Sigma} \Phi) \sin \beta}{\cos \beta} |\partial \Sigma|. \]

Moreover, equality holds if, and only if, \( \Sigma \) is umbilic, \( K_{\Sigma} = 1 + H^2 \) and \( K_{\text{sect}} \equiv 1 \) along \( \Sigma \).

**Proof.** First, by the Gauss equation and the Arithmetic-Geometric Inequality, we obtain
\[ K_{\Sigma} = K_e + K_{\text{sect}} \leq H^2 + 1, \]
hence, integrating over \( \Sigma \), the Gauss-Bonnet Formula yields
\[ 2\pi = \int_{\Sigma} K_{\Sigma} \, d\Sigma + \int_{\partial \Sigma} k_g \leq (1 + H^2) |\Sigma| + \int_{\partial \Sigma} k_g. \tag{4.1} \]

Second, let \( t \) denote a unit tangent vector field along \( \partial \Sigma \), clearly, \( t \in \mathfrak{X}(\partial M) \), and let \( n = Jt \) the rotation of angle \( \pi/2 \) on \( \partial M \).

On the one hand, since \( \{t, n\} \) is an orthonormal frame along \( \partial \Sigma \), we have
\[ 2H_{\partial M} = -\langle t, \nabla_t \eta \rangle - \langle n, \nabla_n \eta \rangle, \]
and since \( \partial M \) is umbilic, we obtain
\[ -\langle t, \nabla_t \eta \rangle = \alpha. \]

On the other hand, by the capillary condition, \( -\eta = \cos \beta \nu + \sin \beta N \) along \( \partial \Sigma \), hence
\[ -\langle t, \nabla_t \eta \rangle = \cos \beta \langle t, \nabla_t \nu \rangle + \sin \beta \langle t, \nabla_t N \rangle = \cos \beta k_g - \sin \beta II_{\Sigma}(t, t). \]

Therefore, combining both equations we get
\[ \cos \beta k_g = \alpha + \sin \beta II_{\Sigma}(t, t) \text{ along } \partial \Sigma. \tag{4.2} \]

Finally, since \( \Sigma \) has constant mean curvature \( H \), we have that \( II_{\Sigma}(t, t) \leq H + \Phi \) and hence, substituting (4.2) into (4.1) yields
\[ 2\pi \cos \beta \leq (1 + H^2) \cos \beta |\Sigma| + (\alpha + (H + \max_{\partial \Sigma} \Phi) \sin \beta) |\partial \Sigma|, \tag{4.3} \]
as claimed.

Moreover, equality holds if and only if, equality holds in (4.1), that is, \( K_{\Sigma} = H^2 + 1 \), which implies that \( \Sigma \) is umbilic and \( K_{\text{sect}} \equiv 1 \) along \( \Sigma \). From the Gauss Equation, we deduce \( K_{\Sigma} = 1 + H^2. \) \( \square \)
4.2 Rigidity

Now, we will characterize Riemannian manifolds \((M, \partial M)\) with totally geodesic boundary and sectional curvatures \(0 \leq K_{\text{sect}} \leq 1\) assuming the existence of an oriented \(H\)–disk meeting \(\partial M\) orthogonally and of least area. According to Lemma 4.1, if \(\Sigma \subset M\) is an oriented \(H\)–disk such that \(\partial \Sigma \subset \partial M\) and meets \(\partial M\) orthogonally, then

\[
|\Sigma| \geq \frac{2\pi}{1 + H^2},
\]

where we are assuming that \(\partial M\) is totally geodesic in \(M\). Hence, we can announce

**Theorem 4.1.** Let \((M, \partial M)\) be a complete orientable Riemannian 3–manifold with boundary. Assume that \(M\) has sectional curvatures \(0 \leq K_{\text{sect}} \leq 1\) and \(\partial M\) is connected and totally geodesic. If there exists a compact oriented embedded \(H\)–disk \(\Sigma \subset M\) orthogonal to \(\partial M\) such that

\[
|\Sigma| = \frac{2\pi}{1 + H^2}.
\]

Then:

- If \(H > 0\), the mean convex side of \(M \setminus \Sigma\), call this component \(U\), is isometric to \(B_2(R_H) \cap S^3_+ \subset S^3\) with the standard metric, \(R_H = \frac{\pi}{2} - \arctg H\) and \(x \in \partial S^3_+\). Moreover, \(\Sigma\) is a disk \(D_H\) described in the Model 1.

- If \(H = 0\), \(M\) is isometric either to \(S^3_+\) with its standard metric of constant sectional curvature one, or a quotient of \(\mathbb{R} \times S^2_+\) with the standard product metric. Moreover, \(\Sigma\) is a disk \(D_H\) or \(D_t\) as described in the Models 1 and 2.

**Proof.** In order to get the rigidity result, we follow similar arguments to those included in [5, Theorem 1]. Denote by \(N\) the unit normal along \(\Sigma\) pointing to the mean-convex side of \(M \setminus \Sigma\), denote this component by \(W\). In particular, if \(\Sigma\) is minimal we can consider any component of \(M \setminus \Sigma\). Consider the variation \(F : (-\epsilon, \epsilon) \times \Sigma \to M\) given by \(F_t(p) = \exp_p(tN(p))\), where \(\exp\) is the exponential map in \(M\). Note that, since \(\Sigma\) is orthogonal to \(M\), the normal \(N\) along the boundary \(\partial \Sigma \subset \partial M\) is a tangent vector in \(\partial M\) hence, since \(\partial M\) is totally geodesic, for all \(p \in \partial \Sigma\) we have

\[
F_t(p) \in \partial M \quad \text{for all} \quad t \in (-\epsilon, \epsilon).
\]

Set \(\Sigma_t = F_t(\Sigma) \subset M\) and denote by \(H_t\) and \(F_t := \sqrt{H_t^2 - K_t}\) the mean and skew curvature for all \(t \in (-\epsilon, \epsilon)\), respectively. It is clear that for \(\epsilon > 0\) small enough, \(\Sigma_t\) is an embedded disk such that \(\Sigma_t \cap \partial M = \partial \Sigma_t\). Moreover, by the discussion above, \(\Sigma_t \subset M\) and \(\partial \Sigma_t \subset \partial M\). Also, by the Gauss Lemma, \(\Sigma_t\) is orthogonal to \(M\) for all \(t \in (-\epsilon, \epsilon)\), \(\epsilon\) small enough. Define

\[
\epsilon_0 := \sup \{\epsilon > 0 : F : [0, \epsilon) \times \Sigma \to M \text{ is embedded and } \Sigma_t \cap \partial M = \partial \Sigma_t\} > 0.
\]
Let us pullback the metric $\langle \cdot, \cdot \rangle$, via $F$, to $[0, \epsilon_0) \times \Sigma$, that is, $g = F^* \langle \cdot, \cdot \rangle$ and 

$$F : ([0, \epsilon_0) \times \Sigma, g) \rightarrow (\mathcal{M}, \langle \cdot, \cdot \rangle)$$

is a local isometry. Clearly, the pullback metric $g$ can be written as $g = g_t \, dt^2$, where $g_t$ is a smooth family of metrics on $\Sigma$, in other words, $g_t$ is the induced metric of $\Sigma_t \subset \mathcal{M}$.

First, since $\Sigma_0 \equiv \Sigma$ achieves the equality in Lemma 4.1, $(\Sigma_0, g_0)$ is umbilic, $K_{\text{sect}} \equiv 1$ along $\Sigma_0$ and it isometric to a hemisphere of constant Gaussian curvature $1 + H^2$ with its standard metric, i.e., $\Sigma \equiv S_+^2 \left( \frac{1}{\sqrt{1+H^2}} \right)$.

Second, by the Gauss-Bonnet formula and the Gauss Equation, we have

$$2\pi = \int_{\Sigma_t} K_{\Sigma_t} + \int_{\partial \Sigma} k_g^t$$

$$= \int_{\Sigma} (H_t + \Phi_t)(H_t - \Phi_t) + \int_{\Sigma} K_{\text{sect}} + \int_{\partial \Sigma} k_g^t$$

$$\leq |\Sigma_t| + \int_{\Sigma_t} H_t^2 - \int_{\Sigma_t} \Phi_t^2 + \int_{\partial \Sigma} k_g^t,$$

and, bearing in mind that $\partial \mathcal{M}$ is totally geodesic and $\Sigma_t$ orthogonal to $\partial \mathcal{M}$, we get $\int_{\partial \Sigma} k_g^t = 0$, which yields that

$$\int_{\Sigma_t} \Phi_t^2 \leq |\Sigma_t| - 2\pi + \int_{\Sigma_t} H_t^2$$

for all $t \in [0, \epsilon_0)$. (4.4)

For each $p \in \Sigma$, we denote $\gamma_p$ the geodesic in $\mathcal{M}$ with initial conditions $\gamma_p(0) = p$ and $\gamma'_p(0) = N(p)$. Therefore, $F_t(p) = \gamma_p(t)$. Set

$$G(t) := |\Sigma_t| - 2\pi + \int_{\Sigma_t} H_t^2$$

for all $t \in [0, \epsilon_0)$.

Then, by the First Variation Formula and the First Variation of the Mean Curvature

$$\frac{\partial H_t}{\partial t} = \text{Ric}(N_t) + 2H_t^2 + 2\Phi_t^2 \geq 0$$

for all $t \in [0, \epsilon_0)$, and hence $h_p(t) = H_t(p)$ is a nondecreasing function of $t$ such that $h_p(t) \geq 0$ for all $t \in [0, \epsilon_0)$ and all $p \in \Sigma$. Thus, we obtain

$$G'(t) = \int_{\Sigma_t} 2H_t \left( \frac{\partial H_t}{\partial t} - H_t^2 - 1 \right) - \int_{\partial \Sigma_t} \langle \gamma'_p(t), \eta \rangle$$

$$= \int_{\Sigma_t} H_t \left( 2\Phi_t^2 + \text{Ric}(N_t) - 2 \right)$$

$$\leq 2 \int_{\Sigma_t} H_t \Phi_t^2$$
where we have used that Ric$(N_t)$ $- 2 \leq 0$ and $H_t \geq 0$, by the curvature hypothesis, and $\langle \gamma'_p(t), \eta \rangle = 0$, since $\gamma'_p(t) \in T_{\gamma(t)} \partial M$ and $\eta$ is normal along $\partial M$.

Therefore, since $\Sigma_t$ is a compact disk, for all $\bar{\epsilon} \in (0, \epsilon_0)$ there exists a constant $C > 0$ (depending on $\bar{\epsilon}$) such that $|H_t| \leq C$ for all $(t, p) \in [0, \bar{\epsilon}) \times \Sigma$. Thus,

$$G'(t) \leq 2CG(t) \text{ for all } t \in [0, \bar{\epsilon}),$$

and, by Gronwall’s Lemma, we get

$$G(t) \leq G(0)e^{2Ct} \text{ for all } t \in [0, \bar{\epsilon}).$$

Since $\Sigma_0$ is totally umbilic, $(1 + H^2) |\Sigma_0| = 2\pi$ and $G(0) = 0$, then

$$G(t) \leq 0 \text{ for all } t \in [0, \bar{\epsilon}).$$

But, $G(t) \geq 0$ for all $t \in [0, \bar{\epsilon})$ by (4.4) which implies that $G(t) \equiv 0$ for all $t \in [0, \bar{\epsilon})$.

Continuing the argument, we obtain that $G(t) \equiv 0$ for all $t \in [0, \epsilon_0)$.

Therefore, for all $t \in [0, \epsilon_0)$ we have

(a.1) $\Sigma_t$ is umbilic,

(a.2) $H_t(\text{Ric}(N_t) - 2) = 0$,

(a.3) $2 \frac{\partial H_t}{\partial t} = \text{Ric}(N_t) + 2H_t^2$.

We assert that if the mean curvature is positive at a point of an equidistant then it is positive at any point of this equidistant. More precisely,

Claim 1: Let $(p, t) \in (0, \epsilon_0) \times \Sigma$ be such that $H_t(p) > 0$, then $H_t(q) > 0$ for all $q \in \Sigma$.

Proof of Claim 1. The proof is as in [5, Claim 2], but we include it here for the sake of completeness. Consider $t \in (0, \epsilon_0)$ and assume that $H_t(p) > 0$ and set

$$\Omega := \{q \in \Sigma : H_t(q) > 0\}.$$

By continuity, $\Omega$ is a nonempty open subset of $\Sigma$. Let us see that $\Omega$ is closed. By continuity of the Ricci curvature and (a.2), we have that $\text{Ric}_{(t, q)}(N_t) = 2$ for all $q \in \overline{\Omega}$. Thus, item (a.3) implies that

$$\frac{\partial H_t}{\partial t} \geq 2 > 0 \text{ for all } q \in \overline{\Omega},$$

and therefore $H_t(q) > H \geq 0$, in other words, $q \in \Omega$. Thus, $\Omega$ is open and closed in $\Sigma$ so $\Omega \equiv \Sigma$ as claimed. 

\[\square\]
Now, we will consider two cases, either $H = 0$ or $H \neq 0$.

**Case A:** If $H > 0$, the mean convex side of $M \setminus \Sigma$, call this component $U$, is isometric to the totally geodesic ball $B_x(R_H) \cap S^3_+ \subset S^3$ with the standard metric, $R_H = \frac{\pi}{2} - \arctg H$ and $x \in \partial S^3_+$. Moreover, $\Sigma$ is a disk $D_H$ described in the Model 1.

**Proof of Case A.** In this case, by Claim 1, we obtain $H_t > 0$ for all $t \in [0, \epsilon_0)$ and hence $\text{Ric}(N_t) = 2$, which implies that the sectional curvature of any two plane orthogonal to $\Sigma_t$ is one for all $t \in [0, \epsilon_0)$.

On the one hand, item (a.3) gives

$$\frac{\partial H_t}{\partial t} = 1 + H_t^2 \text{ for all } t \in [0, \epsilon_0).$$

The above equation implies that

$$\frac{\partial}{\partial t} \arctg H_t = 1 \text{ for all } t \in [0, \epsilon_0),$$

then, by the Fundamental Theorem of Calculus, fixing $t \in [0, \epsilon_0)$, we get

$$\arctg H_t(p) = \arctg H + t \text{ for all } p \in \Sigma,$$

that is, $\Sigma_t$ has constant mean curvature

$$H_t = \tan(\arctg H + t) \text{ for all } t \in [0, \epsilon_0). \quad (4.5)$$

On the other hand, by the First Variation of the Area, we have

$$\frac{\partial}{\partial t} |\Sigma_t| = -2 \tan(\arctg H + t) |\Sigma_t| \text{ for all } t \in [0, \epsilon_0),$$

which implies that

$$|\Sigma_t|^{1/2} = \sqrt{1 + H^2} \cos (t + \arctg H) |\Sigma|^{1/2} \text{ for all } t \in [0, \epsilon_0),$$

or, in other words,

$$|\Sigma_t| = 2\pi \cos^2 (t + \arctg H) \text{ for all } t \in [0, \epsilon_0). \quad (4.6)$$

Thus, the Gauss-Bonnet Formula, (4.5) and (4.6), we have

$$2\pi = \int_{\Sigma_t} K_{\Sigma_t} \leq (1 + H_t^2) |\Sigma_t|$$

$$= 2\pi \left(1 + \tan^2(t + \arctg H)\right) \cos^2 (t + \arctg H)$$

$$= 2\pi$$

14
which tells us that the sectional curvature of the two plane tangent to $\Sigma_t$ is equals to 1 for all $t \in [0, \epsilon_0)$, and therefore

$$K_{\Sigma_t} = 1 + \tan^2 (t + \arctg H) = \cos^{-2} (t + \arctg H) \quad \text{for all} \quad t \in (\bar{\delta}, \epsilon_0).$$

Hence, $\Sigma_t$ is isometric to $S^2 (\cos (t + \arctg H))$ for each $t \in [0, \epsilon_0)$. In this case, $\epsilon_0 = \frac{\pi}{2} - \arctg H$ and $F_{\epsilon_0}(\Sigma)$ is a point. Therefore, $[0, \frac{\pi}{2} - \arctg H) \times \Sigma$ with the pullback metric

$$g = dt^2 + \sin^2 (t + \arctg H) g_{+1}$$

is isometric to $B_{x}(R_{H}) \cap S^3_+$, for $R_{H} = \frac{\pi}{2} - \arctg H$ and some point $F_{\frac{\pi}{2} - \arctg H}(\Sigma) := x \in \partial S^3_+$. Here, $g_{+1}$ denotes the standard metric $S^2$ of constant curvature one. Denote by $I : B_{x}(R_{H}) \cap S^3_+ \to S^3 \times [0, \frac{\pi}{2} - \arctg H) \times \Sigma$ such an isometry.

So, $\tilde{F} = F \circ I : B_{x}(R_{H}) \cap S^3_+ \to \mathcal{M}$ is a local isometry, and, since $B_{p}(R_{H}) \cap S^3_+$ is simply connected and $\tilde{F}$ is injective on $\Sigma$, then $\tilde{F}$ is a global isometry onto its image, that is, the mean convex side of $\mathcal{M} \setminus \Sigma$ is isometric to $B_{p}(R_{H}) \cap S^3_+$ with the standard metric of constant curvatures one. Hence, Claim A is proved.

Now, we prove:

**Case B:** If $H = 0$, then $\mathcal{M}$ is isometric either to $S^3_+$ with its standard metric of constant sectional curvature one, or to a quotient of $\mathbb{R} \times S^2_+$ with the standard product metric.

**Proof of Case B.** Claim 1 and (a.2) yield that

(i) either, $H_t > 0$ and $\text{Ric}(N_t) = 2$ on $[0, \epsilon_0) \times \Sigma$,

(ii) or, $H_t = 0$ and $\text{Ric}(N_t) = 0$ on $[0, \epsilon_0) \times \Sigma$.

In case (i), arguing as in Case A, we can conclude that each side of $\mathcal{M} \setminus \Sigma$ is isometric to $B_{y}(\frac{\pi}{2}) \cap S^3_+$, $y = \pm x \in \partial S^3_+$, with the standard metric. Hence, $\mathcal{M}$ must be isometric to $S^3_+$ with the standard metric.

In case (ii), the First Variation Formula says $|\Sigma_t| = 2\pi$ for all $t \in [0, \epsilon_0)$. Therefore, $\Sigma_t$ is totally geodesic and the Gaussian curvature equals to one. Thus, the sectional curvatures of any two plane orthogonal to $\Sigma_t$ are zero, and for the two plane tangent to $\Sigma_t$ is one. Thus, the pullback metric $g$ on $(0, \epsilon_0) \times \Sigma$ can be written as $g = dt^2 + g_{+1}$.

Therefore, $\epsilon_0 = +\infty$ and $(0, +\infty) \times \Sigma$ endowed with the pullback metric is isometric to $(0, +\infty) \times S^2_+$ with the standard product metric. As above, since both sides are mean convex, $\mathbb{R} \times \Sigma$ is isometric to $\mathbb{R} \times S^2_+$ with the standard product metric. Moreover, since $F : \mathbb{R} \times S^2_+ \to \mathcal{M}$ is a local isometry, it is a covering map. This concludes the proof of Case B.

This concludes the proof of Theorem 4.1.
5 Manifolds with umbilic boundary and $K_{\text{sect}} \leq -1$

In this section we will study compact capillary $H$-surfaces of non-positive Euler characteristic immersed in a three-manifold with umbilic boundary and sectional curvatures less or equal to $-1$. First, we obtain an upper bound for the area of such capillary $H$-surfaces. Second, we obtain rigidity of the three-manifold with boundary assuming that the $H$-surface is orthogonal to the boundary of the three-manifold and achieves the bound for the area. In the latter case, we assume the boundary of the three-manifold is totally geodesic.

5.1 Area Estimate

The area estimate will follow the lines of Lemma 4.1.

**Lemma 5.1.** Let $(\mathcal{M}, \partial \mathcal{M})$ be a complete orientable Riemannian 3-manifold with boundary. Let $\Sigma \subset \mathcal{M}$ be a compact oriented $H$-surface ($H \geq 0$) with boundary $\partial \Sigma \subset \partial \mathcal{M}$. Assume that

- The sectional curvatures of $\mathcal{M}$ satisfy $K_{\text{sect}} \leq -1$,
- $\partial \mathcal{M}$ is umbilic, with umbilicity factor $\alpha \in \mathbb{R}$,
- $\Sigma$ is a capillary surface of angle $\beta_i \in [0, \pi/2)$ at each connected component $\partial \Sigma_i$ of the boundary $\partial \Sigma$,.

then,

$$-2 \pi \chi(\Sigma) + \sum_{i=1}^{k} \frac{\alpha + \sin \beta_i (H + \max_{\partial \Sigma} \Phi))}{\cos \beta_i} |\partial \Sigma_i| \geq (1 - H^2) |\Sigma|,$$

where $k$ is the number of connected components of $\partial \Sigma$. Moreover, equality holds if, and only if, $\Sigma$ is umbilic, $K_\Sigma = H^2 - 1$ and $K_{\text{sect}} \equiv -1$ along $\Sigma$.

**Proof.** As we did in Lemma 4.1, by the Gauss-Bonnet formula and the hypothesis, we get

$$2 \pi \chi(\Sigma) = \int_{\Sigma} K_\Sigma + \int_{\partial \Sigma} k_g$$

$$= \int_{\Sigma} H^2 - \int_{\Sigma} \Phi^2 + \int_{\Sigma} K_{\text{sect}} + \sum_{i=1}^{k} \int_{\partial \Sigma_i} k_g$$

$$\leq (H^2 - 1) |\Sigma| + \sum_{i=1}^{k} \frac{\alpha + \sin \beta_i (H + \max_{\partial \Sigma} \Phi))}{\cos \beta_i} |\partial \Sigma_i| ,$$

as claimed. \qed
The area estimate obtained above is still valid when \( H > 1 \), however it does not give information. We will see here how to construct annuli of constant mean curvature \( H > 1 \) orthogonal to the boundary in the Model 3. We will use the notation we have introduced there.

Let \( \gamma \) be the minimizing geodesic in \( \Sigma_0 \) joining two different boundary components \( \beta_i \) and \( \beta_j \). Then, \( \gamma \) lifts to a geodesic \( \tilde{\gamma} \subset \Sigma_0 \subset P_0 \) that minimizes the distance between \( \tilde{\beta}_i \) and \( \tilde{\beta}_j \), where \( d \) denotes the hyperbolic distance, that is, the points at distance \( r \) in \( \mathbb{H}^3 \). This surface is contained in \( \mathcal{M} \) with constant mean curvature bigger than one, depending on \( r \), and orthogonal to the boundary \( \partial \mathcal{M} \).

### 5.2 Rigidity

Now, we will characterize Riemannian manifolds \( (\mathcal{M}, \partial \mathcal{M}) \) with totally geodesic boundary and sectional curvatures \( K_{\text{sect}} \leq -1 \) assuming the existence of an oriented \( H \)–surface meeting \( \partial \mathcal{M} \) orthogonal and of greatest area. By Lemma 5.1, if \( \Sigma \subset \mathcal{M} \) is an oriented compact \( H \)–surface, \( H^2 \leq 1 \), such that \( \partial \Sigma \subset \partial \mathcal{M} \) and meets \( \partial \mathcal{M} \) orthogonally, then

\[
(1 - H^2) |\Sigma| \leq 2\pi |\chi(\Sigma)|,
\]

where we are assuming that \( \partial \mathcal{M} \) is totally geodesic in \( \mathcal{M} \). Note that, in the case \( \chi(\Sigma) = 0 \), Lemma 5.1 says that if there exists a \( H \)–surface \( \Sigma, H^2 \leq 1 \), orthogonal to the boundary with \( \chi(\Sigma) = 0 \) then \( \Sigma \) has constant mean curvature \( H = 1 \), it is umbilic, \( K_\Sigma = 0 \) and \( K_{\text{sect}} \equiv -1 \) along \( \Sigma \), without any area information.

It is remarkable that we can not characterize the manifold when \( \Sigma \) is minimal. We will explain this in more detail after the proof of the following:

**Theorem 5.1.** Let \( (\mathcal{M}, \partial \mathcal{M}) \) be a complete orientable Riemannian 3–manifold with boundary. Assume that \( \mathcal{M} \) has sectional curvatures \( K_{\text{sect}} \leq -1 \) and \( \partial \mathcal{M} \) is totally geodesic. Assume that there exists a compact oriented embedded \( H \)–surface \( \Sigma \subset \mathcal{M}, H \in (0, 1] \), orthogonal to \( \partial \mathcal{M} \) with non-positive Euler characteristic. Then:

- If \( H \in (0, 1) \), \( \Sigma \) separates and \( |\Sigma| = \frac{2\pi |\chi(\Sigma)|}{1 - H^2}, \chi(\Sigma) < 0 \), then there exists a totally geodesic minimal surface \( \Sigma_m \) orthogonal to \( \partial \mathcal{M} \) and an isometry
  \[
  F : ([0, \text{arctgh} H] \times \Sigma, dt^2 + \cosh^2(t) g_{-1}) \to \mathcal{M},
  \]
  where \( g_{-1} \) denotes the standard metric of constant curvature \(-1\), such that
  - \( F(0, \Sigma) = \Sigma \) and \( F(\text{arctgh} H, \Sigma) = \Sigma_m \), and
  - \( F(t, \Sigma) = \Sigma_t \) is an embedded totally umbilic \( H \)–surface, \( H = \text{tgh}(\text{arctgh} H - t) \), orthogonal to \( \partial \mathcal{M} \) for all \( t \in [0, \text{arctgh} H) \).
Moreover, if $\Sigma_m$ is non-orientable, a tubular neighborhood of $\Sigma_m$ is foliated by its equidistants $\Sigma_t$.

- If $H = 1$ and $\chi(\Sigma) = 0$, the mean convex side of $M \setminus \Sigma$, call this component $U$, is isometric to $[0, +\infty) \times \Sigma$ endowed with the product metric $g = dt^2 + e^{-2t}g_e$, where $g_e$ is the standard Euclidean metric of curvature 0. That is, $U$ is isometric to a cusp hyperbolic end $\mathcal{P}$ corresponding to Model 4 and $\Sigma$ is a slice.

Proof. As we did in Theorem 4.1, let $N$ be the unit normal pointing to the mean convex side of $M \setminus \Sigma$ and consider the variation $F : [0, \epsilon_0) \times \Sigma \to M$, where

$$\epsilon_0 := \sup \{ \epsilon > 0 : F : [0, \epsilon) \times \Sigma \to M \text{ is embedded and } \Sigma_t \cap \partial M = \partial \Sigma_t \} > 0.$$ 

As we observed in Theorem 4.1, $\Sigma_t \subset M$, $\Sigma_t \cap \partial M = \partial \Sigma_t$ for all $t \in [0, \epsilon_0)$, where $\Sigma_t = F_t(\Sigma)$. Let $g = F^*\langle , \rangle$ be the pullback metric of $M$ into $[0, \epsilon_0) \times \Sigma$ and, hence, we can write $g = dt^2 + g_t$. Since $\Sigma_0 = \Sigma$ achieves the equality in Lemma 5.1, then

- either $H = 1$ and $\chi(\Sigma) = 0$,
- or $\Sigma_0$ is umbilic, $K_{\Sigma} = H^2 - 1 < 0$ and $K_{\text{sect}} = -1$ along $\Sigma_0$, in other words, $g_0 := \frac{1}{\sqrt{1-H^2}}g_{-1}$, where $g_{-1}$ is the standard metric of constant sectional curvature $-1$.

Now, as we did in Theorem 4.1, we study the behavior of the function $G(t)$ that satisfies

$$\int_{\Sigma_t} \Phi_t^2 \leq G(t) := 2\pi|\chi(\Sigma)| - |\Sigma_t| + \int_{\Sigma_t} H_t^2 \text{ for all } t \in [0, \epsilon_0).$$

By the First Variation Formula and the First Variation of the Mean Curvature

$$2\frac{\partial H_t}{\partial t} = \text{Ric}(N_t) + 2H_t^2 + 2\Phi_t^2,$$

we obtain

$$G'(t) = \int_{\Sigma_t} 2H_t \left( \frac{\partial H_t}{\partial t} - H_t^2 + 1 \right) = \int_{\Sigma_t} H_t \left( 2\Phi_t^2 + \text{Ric}(N_t) + 2 \right)$$

for all $t \in [0, \epsilon_0)$. Define

$$\bar{\epsilon} = \sup \{ \epsilon \in (0, \epsilon_0) : H_t(p) \neq 0 \text{ for all } p \in \Sigma_t \},$$

18
then, for any \( \epsilon' \in (0, \bar{\epsilon}) \), there exists \( C \geq 0 \) such that \( C \geq H_t(p) > 0 \) for all \( (t, p) \in [0, \epsilon'] \times \Sigma \) and, therefore

\[
G'(t) \leq 2C \int_{\Sigma_t} \Phi^2_t \leq 2C G(t) \text{ for all } t \in [0, \epsilon'],
\]

which, by Gronwall’s Lemma, implies \( G(t) \leq 0 \) for all \( t \in [0, \epsilon'] \), where we have used that \( G(0) = 0 \) and hence \( G(t) = 0 \) for all \( t \in [0, \epsilon'] \). Hence, for all \( t \in [0, \epsilon'] \) we have

(b.1) \( \Sigma_t \) is umbilic,

(b.2) \( \text{Ric}(N_t) + 2 = 0 \), which implies that the sectional curvature of any two plane orthogonal to \( \Sigma \) is equal to \(-1\),

(b.3) \( \frac{\partial H_t}{\partial t} = H_t^2 - 1. \)

Now, we divide the proof into two cases. First, the case \( H \in (0, 1) \):

**Case A:** If \( H \in (0, 1) \), \( \Sigma \) separates and \( |\Sigma| = \frac{2\pi |\chi(\Sigma)|}{1 - H^2} \), \( \chi(\Sigma) < 0 \), then there exists a totally geodesic minimal surface \( \Sigma_m \) orthogonal to \( \partial \mathcal{M} \) and an isometry

\[
F : ([0, \text{arctgh } H) \times \Sigma, dt^2 + \cosh^2(t) g_{-1}) \rightarrow \mathcal{M},
\]

where \( g_{-1} \) denotes the standard metric of constant curvature \(-1\), such that

- \( F(0, \Sigma) = \Sigma \) and \( F(\text{arctgh } H, \Sigma) = \Sigma_m \), and
- \( F(t, \Sigma) = \Sigma_t \) is an embedded totally umbilic \( H \)-surface, \( H = \text{tgh}(\text{arctgh } H - t) \), orthogonal to \( \partial \mathcal{M} \) for all \( t \in [0, \text{arctgh } H) \).

Moreover, if \( \Sigma_m \) is non-orientable, a tubular neighborhood of \( \Sigma_m \) is foliated by its equidistants \( \Sigma_t \).

**Proof of Case A.** On the one hand, by item (b.3) we have

\[
H_t(p) = \text{tgh}(\text{arctgh } H - t) \text{ for all } p \in \Sigma,
\]

that is, \( \Sigma_t \) has constant mean curvature \( H_t = \text{tgh}(\text{arctgh } H - t) \) for all \( t \in [0, \epsilon'] \).

On the other hand, by the First Variation of the Area, we have

\[
\frac{\partial}{\partial t} |\Sigma_t| = -2 \text{tgh}(\text{arctgh } H - t) |\Sigma_t| \text{ for all } t \in [0, \epsilon'],
\]

which implies that

\[
|\Sigma_t| = 2\pi |\chi(\Sigma)| \cosh^2(\text{arctg } H - t) \text{ for all } t \in [0, \epsilon'].
\]
Thus, by the Gauss-Bonnet Formula substituting (5.2) and (5.3), we have

\[ 2\pi \chi(\Sigma) = \int_{\Sigma_t} K_{\Sigma_t} \leq (H_t^2 - 1) |\Sigma_t| = -2\pi |\chi(\Sigma)|, \]

which tells us that the sectional curvature of the two plane tangent to \(\Sigma_t\) is equal to \(-1\) for all \(t \in [0, \epsilon]\), and therefore

\[ K_{\Sigma_t} = \tgh^2(\text{arctgh } H - t) - 1 = -\cosh^{-2}(\text{arctgh } H - t) \text{ for all } t \in [0, \epsilon]. \]

Now, we can argue with \(\Sigma_{\epsilon'}\) and obtain \(\epsilon' < \epsilon < \epsilon_2 \leq \epsilon_0\) such that the above discussion is valid. Therefore, we can continue the process as far \(H_t \geq 0\), that is, \(\epsilon_0 = \text{arctgh } H\) if \(H \in (0,1)\).

Set \(\Sigma_m = F_{\arctgh H}(\Sigma)\), then \(\Sigma_m\) is a totally geodesic minimal surface such that \(|\Sigma_m| = 2\pi |\chi(\Sigma)|\).

Therefore, \([0, \arctgh H] \times \Sigma\) with the pullback metric \(g = dt^2 + \cosh^2(t) g_{-1}\) is isometric to \(\mathcal{H}(\arctgh H)\) endowed with the hyperbolic metric given by Model 3. Denote by \(I : \mathcal{H}(\arctgh H) \to [0, \arctgh H] \times \Sigma\) this global isometry. So, \(\bar{F} = F \circ I : \mathcal{H}(\arctgh H) \to \mathcal{M}\) is a local isometry and \(\bar{F}\) is injective on \(\Sigma\).

**Claim 1:** \(F\) is injective on \([0, \arctgh H] \times \Sigma\).

**Proof of Claim 1.** Define

\[ \bar{\epsilon} = \sup \{\epsilon \in [0, \arctgh H] : F\text{ is injective on }[0, \epsilon] \times \Sigma\}. \]

Clearly, \(\bar{\epsilon} > 0\) since \(F_0(\Sigma) = \Sigma\) is embedded, so injective. If \(\bar{\epsilon} = \arctgh H\), we finish. We now prove \(F\) is injective on \([0, \arctgh H] \times \Sigma\). Suppose the contrary. Then there are distinct points \(p, q \in \Sigma\) such that 1 or 2 holds:

1. \(F(\bar{\epsilon}, p) = F(0, p)\) or \(F(0, q)\),
2. \(F(\bar{\epsilon}, p) = F(\bar{\epsilon}, q)\).

In case 1, we can construct a closed curve \(C\) meeting \(\Sigma\) in exactly one point, which contradicts that \(\Sigma\) separates \(\mathcal{M}\). To construct \(C\) when \(F(\bar{\epsilon}, p) = F(0, p)\), take \(C(t) = F(t, p)\), \(0 \leq t \leq \bar{\epsilon}\). When \(F(\bar{\epsilon}, p) = F(0, q)\), let \(\Gamma(t)\) be a curve joining \(q\) to \(p\) on \(\Sigma\), \(0 \leq t \leq \bar{\epsilon}\). Then define \(C(t) = F(t, \Gamma(t))\), \(0 \leq t \leq \bar{\epsilon}\). Thus case 1 can not occur.

Consider case 2, \(F(\bar{\epsilon}, p) = F(\bar{\epsilon}, q)\). Let \(U\) and \(V\) be disjoint neighborhoods of \(p\) and \(q\), respectively, in \(\{\bar{\epsilon}\} \times \Sigma\), such that \(F(\bar{\epsilon}, p)\) is in the intersection of \(F(\bar{\epsilon}, U)\) and \(F(\bar{\epsilon}, V)\). We distinguish two possibilities here depending on the direction of the mean curvature vectors; \(\bar{H}_{F(\bar{\epsilon}, U)}, \bar{H}_{F(\bar{\epsilon}, V)}\). We can assume that \(U\) and \(V\) are disjoint neighborhoods of \((\bar{\epsilon}, p)\) and \((\bar{\epsilon}, q)\) on each of which \(F\) is injective. For future use we extend \(U\) and \(V\) to neighborhoods \(\bar{U}\) and \(\bar{V}\) in \([0, \bar{\epsilon}] \times \Sigma\) on each of which \(F\) is injective.

20
Suppose first that $\tilde{H}_{F(\bar{\epsilon}, p)} = \tilde{H}_{F(\bar{\epsilon}, q)}$. Then $F(\bar{\epsilon}, U)$ is on one side of $F(\bar{\epsilon}, V)$ at $F(p, c)$ (where they are tangent) and they have the same mean curvature vector so $F(\bar{\epsilon}, U) = F(\bar{\epsilon}, V)$. Consequently, $\Sigma$ is a non trivial covering space of the embedded surface $F(\bar{\epsilon}, \Sigma)$. But, $F(\bar{\epsilon}, \Sigma)$, $\bar{\epsilon}$ near $\bar{\epsilon}$, is a graph over $F(\bar{\epsilon}, \Sigma)$ in the trivial normal bundle of $F(\bar{\epsilon}, \Sigma)$ in $\mathcal{M}$. This is impossible when the covering space is non trivial.

Now suppose that $\tilde{H}_{F(\bar{\epsilon}, p)} = -\tilde{H}_{F(\bar{\epsilon}, q)}$. At $F(\bar{\epsilon}, p)$, $F(\bar{\epsilon}, U)$ is strictly mean convex towards $\tilde{H}_{F(\bar{\epsilon}, p)}$ and $F(\bar{\epsilon}, V)$ is strictly mean convex towards $-\tilde{H}_{F(\bar{\epsilon}, q)}$. $F(\bar{U})$ is on the mean concave side of $F(\bar{\epsilon}, U)$ near $F(\bar{\epsilon}, p)$. $F(V)$ is on the mean concave side of $F(\bar{\epsilon}, V)$ near $F(\bar{\epsilon}, p)$. So, any neighborhood of $F(\bar{\epsilon}, p)$ contains an open set on the mean concave side of $F(\bar{\epsilon}, V)$ which is contained in the mean concave side of $F(\bar{\epsilon}, V)$. Hence $F(\bar{U} \setminus U)$ intersects $F(V \setminus V)$ which contradicts $F$ injective on $[0, \bar{\epsilon}) \times \Sigma$.

We now know that $F$ is injective on $[0, \arctgh{H}) \times \Sigma$. The surface $\{\arctgh{H}\} \times \Sigma$ is a minimal surface so it may be the case that $\{\arctgh{H}\} \times \Sigma$ is a two sheeted covering space of the non-orientable embedded surface $F(\{\arctgh{H}\}, \Sigma) := \Sigma_m$. Hence, a tubular neighborhood of $\Sigma_m$ foliated by its equidistants.

This finishes the proof of Claim A.

Second, and last, when $H = 1$:

**Case B:** If $H = 1$, the mean convex side of $\mathcal{M} \setminus \Sigma$ is isometric to $[0, +\infty) \times \Sigma$ endowed with the product metric $g = dt^2 + e^{-2t}g_e$.

**Proof of Case B.** We follow [5, Theorem 2]. In this case, the mean curvature of each $\Sigma_t$ is constant and it is equal to one, that is, $H_t = 1$ for all $t \in [0, \bar{\epsilon})$. Thus, we can let $\bar{\epsilon}$ tend to $\epsilon_0$ and we get that $\Sigma_t$ has constant mean curvature $1$, it is umbilic, $K_{\Sigma} = 0$ for all $t \in [0, \epsilon_0)$ and, moreover, $[0, \epsilon_0) \times \Sigma$ endowed with the pullback metric $g$ has constant sectional curvature equals to $-1$ for any two plane. Also, one can see that $g = dt^2 + e^{-2t}g_e$, $g_e$ the standard Euclidean metric, and $\epsilon_0 = +\infty$. In this case, one can prove that, following [5, Theorem 2], the mean convex side of $\mathcal{M} \setminus \Sigma$ is, in fact, isometric to $[0, +\infty) \times \Sigma$ endowed with the product metric $g = dt^2 + e^{-2t}g_e$.

This concludes the proof of Theorem 5.1.

We remark that in the minimal case, i.e., $H = 0$, by the First Variation Formula of the Mean curvature we obtain that $|H_t(p)| > 0$ for all $(t, p) \in [0, \epsilon']$. Nevertheless, the mean curvature vector $\tilde{H}(p)$ points in the opposite direction of the normal given by the flow $\frac{d}{dt}F_t(p)$. Hence, by our definition of the mean curvature function, $H_t$ is negative for $N_t$. In other words, in the minimal case, $N_t = \frac{d}{dt}F_t(p)$ and hence, (5.1) is not satisfied. Recall that, in order to obtain (5.1), we needed that $H_t$ was positive for all $t$. 

21
5.3 Area estimate and rigidity of compact $H$–surfaces without boundary

One can easily see that results stated above for compact $H$–surfaces with boundary can be extended to closed surfaces. First, the area estimate

**Lemma 5.2.** Let $\mathcal{M}$ be a complete orientable Riemannian 3–manifold with sectional curvatures $K_{\text{sect}} \leq -1$. Let $\Sigma \subset \mathcal{M}$ be a closed oriented $H$–surface, $H \in [0, 1)$, of genus $g(\Sigma) \geq 2$. Then,

$$4\pi (g(\Sigma) - 1) \geq (1 - H^2) |\Sigma|.$$

Moreover, equality holds if, and only if, $\Sigma$ is umbilic, $K_\Sigma = H^2 - 1$ and $K_{\text{sect}} \equiv -1$ along $\Sigma$.

In the case we get the equality in the area estimate above, we can classify the three-manifold

**Theorem 5.2.** Let $\mathcal{M}$ be a complete orientable Riemannian 3–manifold with sectional curvatures $K_{\text{sect}} \leq -1$. Assume that there exists a compact oriented embedded $H$–surface $\Sigma \subset \mathcal{M}$, $H \in (0, 1)$, $\Sigma$ separates $\mathcal{M}$, with negative Euler characteristic such that

$$|\Sigma| = \frac{2\pi |\chi(\Sigma)|}{1 - H^2},$$

then there exists a totally geodesic minimal surface $\Sigma_m$ and an isometry

$$F : ([0, \text{arctgh} H] \times \Sigma, dt^2 + \cosh^2 (t) g_{-1}) \to \mathcal{M},$$

where $g_{-1}$ denotes the standard metric of constant curvature $-1$, such that

- $F(0, \Sigma) = \Sigma$ and $F(\text{arctgh} H, \Sigma) = \Sigma_m$, and
- $F(t, \Sigma) = \Sigma_t$ is an embedded totally umbilic $H$–surface, $H = \text{tgh}(\text{arctgh} H - t)$, for all $t \in [0, \text{arctgh} H)$.

Moreover, if $\Sigma_m$ is non-orientable, a tubular neighborhood of $\Sigma_m$ is foliated by its equidistants $\Sigma_t$.

The proof of the above result is completely analogous to Theorem 5.1.

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