A Finite State and Data-Oriented Method for Grapheme to Phoneme Conversion

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Abstract
A finite-state method, based on leftmost longest-match replacement, is presented for segmenting words into graphemes, and for converting graphemes into phonemes. A small set of hand-crafted conversion rules for Dutch achieves a phoneme accuracy of over 93%. The accuracy of the system is further improved by using transformation-based learning. The phoneme accuracy of the best system (using a large rule and a ‘lazy’ variant of Brill’s algorithm), trained on only 40K words, reaches 99%.

1 Introduction
Automatic grapheme to phoneme conversion (i.e. the conversion of a string of characters into a string of phonemes) is essential for applications of text to speech synthesis dealing with unrestricted text, where the input may contain words which do not occur in the system dictionary. Furthermore, a transducer for grapheme to phoneme conversion can be used to generate candidate replacements in a (pronunciation-sensitive) spelling correction system. When given the pronunciation of a misspelled word, the inverse of the grapheme to phoneme transducer will generate all identically pronounced words. Below, we present a method for developing such grapheme to phoneme transducers based on a combination of hand-crafted conversion rules, implemented using finite state calculus, and automatically induced rules.

The hand-crafted system is defined as a two-step procedure: segmentation of the input into a sequence of graphemes (i.e. sequences of one or more characters typically corresponding to a single phoneme) and conversion of graphemes into (sequences of) phonemes. The composition of the transducer which performs segmentation and the transducer defined by the conversion rules, is a transducer which converts sequences of characters into sequences of phonemes.

Specifying the conversion rules is a difficult task. Although segmentation of the input can in principle be dispensed with, we found that writing conversion rules for segmented input substantially reduces the context-sensitivity and order-dependence of such rules. We manually developed a grapheme to phoneme transducer for Dutch data obtained from CELEX (Baayen et al., 1993) and achieved a word accuracy of 60.6% and a phoneme accuracy of 93.6%.

To improve the performance of our system, we used transformation-based learning (TBL) (Brill, 1995). Training data are obtained by aligning the output of the hand-crafted finite state transducer with the correct phoneme strings. These data can then be used as input for TBL, provided that suitable rule templates are available. We performed several experiments, in which the amount of training data, the algorithm (Brill’s original formulation and ‘lazy’ variants (Samuel et al., 1998)), and the number of rule templates varied. The best experiment (40K words, using a ‘lazy’ strategy with a large set of rule templates) induces over 2000 transformation rules, leading to 92.6% word accuracy and 99.0% phoneme accuracy. This result, obtained using a relatively small set of training data, compares well with that of other systems.

2 Finite State Calculus
As argued in Kaplan and Kay (1994), Karttunen (1995), Karttunen et al. (1997), and elsewhere, many of the rules used in phonology and morphology can be analysed as special cases of regular expressions. By extending the language of regular expressions with operators which capture the interpretation of linguistic rule systems, high-level linguistic descriptions can be compiled into finite state automata directly. Furthermore, such automata can be combined with other finite state automata performing low-level tasks such as tokenization or lexical lookup, or more advanced tasks such as shallow parsing. Composition of the individual components into a single transducer may lead to highly efficient processing.

The system described below was implemented using FSA Utilities, a package for implementing and manipulating finite state automata, which provides possibilities for defining new regular expression oper-
the empty string
[\mathcal{R}_1, \ldots, \mathcal{R}_n] \quad \text{concatenation}
\{\mathcal{R}_1, \ldots, \mathcal{R}_n\} \quad \text{disjunction}
\mathcal{R}^* \quad \text{optionality}
\text{ignore}(\mathcal{A}, \mathcal{B}) \quad \text{ignore: A interspersed with elements of B}
\mathcal{A} \times \mathcal{B} \quad \text{cross-product: the transducer which maps all strings in A to all strings in B.}
\text{identity}(\mathcal{A}) \quad \text{identity: the transducer which maps each element in A onto itself.}
\mathcal{T} \circ \mathcal{U} \quad \text{composition of the transducers} \ \mathcal{T} \text{ and } \mathcal{U}.
\text{macro}(\text{Term}, \mathcal{R}) \quad \text{use Term as an abbreviation for } \mathcal{R} \text{ (where Term and R may contain variables).}

Figure 1: A fragment of FSA regular expression syntax. A and B are regular expressions denoting recognizers, T and U transducers, and R can be either.

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level of representation for the actual grapheme to phoneme conversion rules.

While there are many letter-combinations which are realized as a single phoneme (ch, ng, aa, bb, ..), it is only rarely the case that a single letter is mapped onto more than one phoneme (x), or that a letter receives no pronunciation at all (such as word-final n in Dutch, which is elided if it is proceeded by a schwa). As the number of cases where multiple letters have to be mapped onto a single phoneme is relatively high, it is natural to model a letter to phoneme system as involving two subtasks: segmentation and conversion. Segmentation splits an input string into graphemes, where each grapheme typically, but not necessarily, corresponds to a single phoneme.

Segmentation is defined as:

```
macro(segmentation, replace(  
[identity(graphemes), \( x \rightarrow \),],[],[])  
).
```

The macro graphemes defines the set of graphemes. It contains 77 elements, some of which are:

```
a, aa, au, ai, aai, e, ee, ei, eu, eau, 
eeu, i, ie, iee, ieu, ij, o, oe, oei,
```

Segmentation attaches the marker ‘-‘ to each grapheme. Segmentation, as it is defined here, is not context-sensitive, and thus the second and third arguments of replace are simply empty. As the set of graphemes contains many elements which are substrings of other graphemes (i.e. e is a substring of ei, eau, etc.), longest-match is essential: the segmentation of beiaardier (carillon player) should be b-ei-aa-r-d-ie-r- and not b-ei-a-a-ar-d-i-e-r-. This effect can be obtained by making the segment itself part of the target of the replace statement. Targets are identified using leftmost longest-match, and thus at each point in the input, only the longest valid segment is marked.

The set of graphemes contains a number of elements which might seem superfluous. The grapheme aai, for instance, translates as aj, a sequence which could also be derived on the basis of two graphemes aa and i. However, if we leave out the segment aai, segmentation (using leftmost longest match) of words such as waaien (to blow) would lead to the segmentation w-aa-ie-n, which is unnatural, as it would require an extra conversion rule for ie. Using the grapheme aai allows for two conversion rules which always map aai to aj and ie goes to i.

Segmentation as defined above provides the intuitively correct result in almost all cases, given a suitably defined set of graphemes. There are some cases which are less natural, but which do not necessarily lead to errors. The grapheme eu, for instance, almost always goes to ‘!’, but translates as ‘e,j,’ in (loan-) words such as museum and petroleum. One might argue that a segmentation e-u- is therefore required, but a special conversion rule which covers these exceptional cases (i.e. eu followed by m) can easily be formulated. Similarly, ng almost always translates as N, but in some cases actually represents the two graphemes n-g-, as in aaneengesloten (connected), where it should be translated as NG. This case is harder to detect, and is a potential source of errors.

### 3.2 The Conversion Rules

The g2p operator is designed to facilitate the formulation of conversion rules for segmented input:

```
macro(g2p(Target,LtCont,RtCont),  
replace([Target, - x +],  
[ignore(LtCont,{-,+}), {+,-}],  
ignore(RtCont,{-,+}))  
).
```

The g2p-operator implements a special purpose version of the replace-operator. The replacement of the marker ‘-‘ by ‘+‘ in the target ensures that g2p-conversion rules cannot apply in sequence to the same grapheme. Second, each target of the g2p-operator must be a grapheme (and not some substring of it). This is a consequence of the fact that the final element of the left-context must be a marker and the target itself ends in ‘-‘. Finally, the ignore statements in the left and right context imply that the rule contexts can abstract over the potential presence of markers.

An overview of the conversion rules we used for Dutch is given in Figure 2. As the rules are applied in sequence, exceptional rules can be ordered before the regular cases, thus allowing the regular cases to be specified with little or no context. The special_vowel_rules deal with exceptional translations of graphemes such as eu or cases where i or ij goes to ‘@‘. The short_vowel_rules treat single vowels preceding two consonants, or a word final consonant. One problematic case is e, which can be translated either as ‘E‘ or ‘@‘. Here, an approximation is attempted which specifies the context where e goes ‘E‘, and subsumes the other case under the general rule for short vowels. The special_consonant_rules address devoicing and a few other exceptional cases. The default_rules supply a default mapping for a large number of

\[\text{Note that the input and output alphabet are not disjoint, and thus rules applying in sequence to the same part of the input are not excluded in principle.}\]
graphemes. The target of this rule is a long disjunction of grapheme-phoneme mappings. As this rule-set applies after all more specific cases have been dealt with, no context restrictions need to be specified.

Depending somewhat on how one counts, the full set of conversion rules for Dutch contains approximately 80 conversion rules, more than 40 of which are default mappings requiring no context. Compilation of the complete system results in a (minimal, deterministic) transducer with 747 states and 20,123 transitions.

3.3 Test results and discussion

The accuracy of the hand-crafted system was evaluated by testing it on all of the words without diacritics in the CELEX lexical database which have a phonetic transcription. After several development cycles, we achieved a word accuracy of 60.6% and a phoneme accuracy (measured as the edit distance between the phoneme string produced by the system and the correct string, divided by the number of phonemes in the correct string) of 93.6%.

There have been relatively few attempts at developing grapheme to phoneme conversion systems using finite state technology alone. Williams (1994) reports on a system for Welsh, which uses no less than 700 rules implemented in a rather restricted environment. The rules are also implemented in a two-level system, PC-KIMMO. Antworth (1990), but this still requires over 400 rules. Möbius et al. (1997) report on full-fledged text-to-speech system for German, containing around 200 rules (which are compiled into a weighted finite state transducer) for the grapheme-to-phoneme conversion step. These numbers suggest that our implementation (which contains around 80 rules in total) benefits considerably from the flexibility and high-level of abstraction made available by finite state calculus.

One might suspect that a two-level approach to grapheme to phoneme conversion is more appropriate than the sequential approach used here. Somewhat surprisingly, however, Williams concludes that a sequential approach is preferable. The formulation of rules in the latter approach is more intuitive, and rule ordering provides a way of dealing with exceptional cases which is not easily available in a two-level system.

While further improvements would definitely have been possible at this point, it becomes increasingly difficult to do this on the basis of linguistic knowledge alone. That is, most of the rules which have to be added deal with highly idiosyncratic cases (often related to loan-words) which can only be discovered by browsing through the test results of previous runs. At this point, switching from a linguistics-oriented to a data-oriented methodology, seemed appropriate.

4 Transformation-based grapheme to phoneme conversion

Brill (1993) demonstrates that accurate part-of-speech tagging can be learned by using a two-step process. First, a simple system is used which assigns the most probable tag to each word. The results of the system are aligned with the correct tags for some corpus of training data. Next, (context-sensitive) transformation rules are selected from a pool of rule patterns, which replace erroneous tags by correct tags. The rule with the largest benefit on the training data (i.e. the rule for which the number of corrections minus the number of newly introduced mistakes, is the largest) is learned and applied to the training data. This process continues until no more rules can be found which lead to improvement (above a certain threshold).

Transformation-based learning (TBL) can be applied to the present problem as well. In this case, the base-line system is the finite state transducer described above, which can be used to produce a set of phonemic transcriptions for a word list. Next, these results are aligned with the correct transcriptions. In combination with suitable rule patterns, these data can be used as input for a TBL process.

4.1 Alignment

TBL requires aligned data for training and testing. While alignment is mostly trivial for part-of-speech tagging, this is not the case for the present task. Aligning data for grapheme-to-phoneme conversion amounts to aligning each part of the input (a sequence of characters) with a part of the output (a sequence of phonemes). As the length of both sequences is not guaranteed to be equal, it must be possible to align more than one character with a single phoneme (the usual case) or a single character with more than one phoneme (the exceptional case, i.e. ‘x’). The alignment problem is often solved by allowing ‘null’ symbols in the phoneme string, and introducing ‘compound’ phonemes, such as ‘ks’ to account for exceptional cases where a single character must be aligned with two phonemes.

As our finite state system already segments the input into graphemes, we have adopted a strategy where graphemes instead of characters are aligned with phoneme strings (see Lawrence and Kaye, 1986 for a similar approach). The correspondence

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3 It should be noted that we only considered words which do not contain diacritics. Including those is unproblematic in principle, but would lead to a slight increase of the number of rules.

4 Hoste et al. (2000b) compare TBL to C5.0 (Quinlan, 1993) on a similar task, i.e. the mapping of the pronunciation of one regional variant of Dutch into another.
between graphemes and phonemes is usually one to one, but it is no problem to align a grapheme with two or more phonemes. Null symbols are only introduced in the output if a grapheme, such as word-final 'n', is not realized phonologically.

For TBL, the input actually has to be aligned both with the system output as well as with the correct phoneme string. The first task can be solved trivially: since our finite state system proceeds by first segmenting the input into graphemes (sequences of characters), and then transduces each grapheme into a sequence of phonemes, we can obtain aligned data by simply aligning each grapheme with its corresponding phoneme string. The input is segmented into graphemes by doing the segmentation step of the finite state transducer only. The corresponding phoneme strings can be identified by applying the conversion transducer to the segmented input, while simply aligning each grapheme with its corresponding phoneme string. An example is shown in figure 3, where GR represents the grapheme segmented string, and SP the (system) phoneme strings produced by the finite state transducer. Note that the final SP cell contains only a boundary marker, indicating that the grapheme 'n' is translated into the null phoneme.

For the alignment between graphemes (and, idio-

5 Typical cases are loan words (umpires) and letter words (i.e. abbreviations) (abc).
| method     | training data (words) | phoneme accuracy | word accuracy | induced rules | CPU time (in minutes) |
|------------|-----------------------|------------------|---------------|---------------|-----------------------|
| Base-line  |                       | 93.6             | 60.6          |               |                       |
| Brill 20K  |                       | 98.0             | 86.1          | 447           | 162                   |
| Brill 40K  |                       | 98.4             | 88.9          | 812           | 858                   |
| lazy(5) 20K|                       | 97.6             | 83.5          | 337           | 43                    |
| lazy(5) 40K|                       | 98.2             | 87.0          | 701           | 190                   |
| lazy(5) 60K|                       | 98.4             | 88.3          | 922           | 397                   |
| lazy(10) 20K|                      | 97.7             | 84.3          | 368           | 83                    |
| lazy(10) 40K|                      | 98.2             | 87.5          | 738           | 335                   |
| lazy(10) 60K|                      | 98.4             | 88.9          | 974           | 711                   |
| lazy(5)+ 20K|                      | 98.6             | 89.8          | 1225          | 186                   |
| lazy(5)+ 40K|                      | 99.0             | 92.6          | 2221          | 603                   |

Figure 4: Experimental Results using training data produced by graph2phon

4.2 The experiments

For the experiments with TBL we used the µ-TBL-package [Lager, 1999]. This Prolog implementation of TBL is considerably more efficient (up to ten times faster) than Brill’s original (C) implementation. The speed-up results mainly from using Prolog’s first-argument indexing to access large quantities of data efficiently.

We constructed a set of 22 rule templates which replace a predicted phoneme with a (corrected) phoneme on the basis of the underlying segment, and a context consisting either of phoneme strings, with a maximum length of two on either side, or a context consisting of graphemes, with a maximal length of 1 on either side. Using only 20K words (which corresponds to almost 180K segments), and Brill’s algorithm, we achieved a phoneme accuracy of 98.0% (see figure 3) on a test set of 20K words of unseen data. Going to 40K words resulted in 98.4% phoneme accuracy. Note, however, that in spite of the relative efficiency of the implementation, CPU time also goes up sharply.

The heavy computation costs of TBL are due to the fact that for each error in the training data, all possible instantiations of the rule templates which correct this error are generated, and for each of these instantiated rules the score on the whole training set has to be computed. Samuel et al. (1998) therefore propose an efficient, ‘lazy’, alternative, based on Monte Carlo sampling of the rules. For each error in the training set, only a sample of the rules is considered which might correct it. As rules which correct a high number of errors have a higher chance of being sampled at some point, higher scoring rules are more likely to be generated than lower scoring rules, but no exhaustive search is required. We experimented with sampling sizes 5 and 10. As CPU requirements are more modest, we managed to perform experiments on 60K words in this case, which lead to results which are comparable with Brill’s algorithm applied to 40K words.

Apart from being able to work with larger data sets, the ‘lazy’ strategy also has the advantage that it can cope with larger sets of rule templates. Brill’s algorithm slows down quickly when the set of rule templates is extended, but for an algorithm based on rule sampling, this effect is much less severe. Thus, we also constructed a set of 500 rule templates, containing transformation rules which allowed up to three graphemes or phoneme sequences as left or right context, and also allowed for disjunctive contexts (i.e. the context must contain an ‘a’ at the first or second position to the right). We used this rule set in combination with a ‘lazy’ strategy with sampling size 5 (lazy(5)+ in figure 4). This led to a further improvement of phoneme accuracy to 99.0%, and word accuracy of 92.6%, using only 40K words of training material.

Finally, we investigated what the contribution was of using a relatively accurate training set. To this end, we constructed an alternative training set, in which every segment was associated with its most probable phoneme (where frequencies were obtained from the aligned CELEX data). As shown in figure 3, the initial accuracy for such a system is much lower than that of the hand-crafted system. The experimental results, for the ‘lazy’ algorithm with sampling size 5, show that the phoneme accuracy for training on 20K words is 0.3% less than for the corresponding experiment in figure 4. For 40K words, the difference is still 0.2%, which, in both cases, corresponds to a difference in error rate of around 10%. As might be expected, the number of induced rules

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6 The statistics for less time consuming experiments were obtained by 10-fold cross-validation and for the more expensive experiments by 5-fold cross-validation.
is much higher now, and thus CPU-requirements also increase substantially.

5 Concluding remarks

We have presented a method for grapheme to phoneme conversion, which combines a hand-crafted finite state transducer with rules induced by a transformation-based learning. An advantage of this method is that it is able to achieve a high level of accuracy using relatively small training sets. For instance, uses a memory-based learning strategy to achieve 90.1% word accuracy on the same task, but used 90% of the CELEX data (over 300K words) as training set and a (character/phoneme) window size of 9. achieve a word accuracy of 95.7% and a phoneme accuracy of 99.5% on the same task, using a combination of machine learning techniques, as well as additional data obtained from a second dictionary.

Given the result of [Roche and Schabes (1997)], an obvious next step is to compile the induced rules into an actual transducer, and to compose this with the hand-crafted transducer. It should be noted, however, that the number of induced rules is quite large in some of the experiments, so that the compilation procedure may require some attention.

5 Concluding remarks

We have presented a method for grapheme to phoneme conversion, which combines a hand-crafted finite state transducer with rules induced by a transformation-based learning. An advantage of this method is that it is able to achieve a high level of accuracy using relatively small training sets. Busser (1998), for instance, uses a memory-based learning strategy to achieve 90.1% word accuracy on the same task, but used 90% of the CELEX data (over 300K words) as training set and a (character/phoneme) window size of 9. achieve a word accuracy of 95.7% and a phoneme accuracy of 99.5% on the same task, using a combination of machine learning techniques, as well as additional data obtained from a second dictionary.

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