There are errors in Table 1. The shading is misaligned and certain numbers are out of order. Please see the correct version of Table 1 here:

**Table 1. Block Order.** Blocks were performed from top to bottom, with two extra blocks in the rotated session. Trial numbers during training are larger in the rotated as compared to the aligned sessions. Passive localization tasks always follow the active localization tasks, since the robot moved the hand to the same arc-location in the passive condition as that produced by the participant in the active version. Before every localization task, training was reinforced, to minimize any decay in learning.

| task                    | aligned | rotated |
|-------------------------|---------|---------|
| training                | 50      | 90      |
| no-cursor reaches       | -       | 21      |
| training                | -       | 60      |
| active delayed          | 25      | 25      |
| no-cursor reaches       | 21      | 21      |
| training                | 10      | 60      |
| passive delayed         | 25      | 25      |
| no-cursor reaches       | 21      | 21      |
| training                | 10      | 60      |
| active online           | 25      | 25      |
| no-cursor reaches       | 21      | 21      |
| training                | 10      | 60      |
| passive online          | 25      | 25      |
| no-cursor reaches       | 21      | 21      |