PAYLOAD CALIBRATION

Absolute time calibration of LAXPC aboard AstroSat

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Abstract. The AstroSat mission carries several high-energy detectors meant for fast timing studies of cosmic sources. In order to carry out high precision multi-wavelength timing studies, it is essential to calibrate the absolute time stamps of these instruments to the best possible accuracy. We present here the absolute time calibration of the AstroSat LAXPC instrument, utilising the broad-band electromagnetic emission from the Crab Pulsar to cross calibrate against Fermi-LAT and ground based radio observatories Giant Metrewave Radio Telescope (GMRT) and the Ooty Radio Telescope (ORT). Using the techniques of pulsar timing, we determine the fixed timing offsets of LAXPC with respect to these different instruments and also compare the offsets with those of another AstroSat instrument, CZTI.

Keywords. Pulsars—instrumentation—multi-wavelength astronomy.

1. Introduction

Multiwavelength observations are key to unravelling the physical processes ongoing in a variety of astrophysical sources. Such observations commonly involve multiple instruments situated at different locations. The target sources being studied often have time variable intensity and spectrum, so to characterise their properties it is essential to synchronise the intrinsic time stamps at various observatories being used. Even if the reference time information is obtained from a common source like the Global Positioning System, there could be internal delays in data processing electronics which need to be measured to achieve the necessary synchronisation. In this paper we report the result of our attempt to calibrate the timing offset of the AstroSat LAXPC instrument with respect to ground based Indian radio observatories, namely the Ooty Radio Telescope (ORT) and the Giant Metrewave Radio Telescope (GMRT), the Large Area Telescope (LAT) instrument aboard the Fermi gamma-ray observatory. Results of a similar timing offset calibration experiment for another AstroSat instrument, the Cadmium Zinc Telluride Imager (CZTI), have been reported in Basu et al. (2018), and are also included here for comparison.

This work is motivated by our ongoing effort to characterise the multi-wavelength properties of the Giant Radio Pulses (GRP) emitted by radio pulsars from time to time. In order to phase align these pulses between radio and X-ray bands an accurate alignment of the time stamps across the instruments is required. We therefore begin by measuring the timing offsets between the instruments involved in our experiment, the results of which we report here. We aim to obtain the offsets precise enough to track every pulse in the radio and X-ray bands unambiguously. The GRP arrives randomly within the ~3 ms wide on-pulse window in the average pulse profile (Heiles et al. 1970; Manchester et al. 2005). Our desirable uncertainty on the offset measurement is one-tenth of the pulse width, i.e. less than 300 μs.
Our aim can be achieved by timing and monitoring pulsars over a long span of time. Since our experiment involves telescopes operational at low-frequency radio wavelengths to γ-rays, we have chosen the Crab pulsar (PSR J0534+2200) as our target source. The Crab pulsar emits pulsed emission across the whole electromagnetic spectrum from radio to very high-energy γ-rays. At L-band (around 1.4 GHz) the Crab pulsar has two distinct components in its profile: the main-pulse (MP) and a relatively weaker inter-pulse (IP). The components are highly aligned across the spectrum except for some intrinsic emission delay. The MP at high energies leads the radio main pulse by 241 ± 29 μs (>30 MeV; Kuiper et al. 2003), 344 ± 40 μs (2–30 keV; Rots et al. 2004), (280 ± 40 μs) (Kuiper et al. 2003), 235 ± 33 μs (10-600 keV; Terada et al. 2008) and 275 ± 15 μs (20–100 keV; Molkov et al. 2009). It is essential to account for these intrinsic delays while computing the time of arrival (TOA) of the pulses (discussed in Section 3.5).

The results obtained from our experiment presented in this paper would allow us to time-align the Radio and X-ray time series data, enabling us to search for X-ray photon count enhancements coincident with the GRP. In Section 2 we discuss the instruments used for the experiment, in Section 3 we discuss the methodology adopted to measure the timing offsets and finally conclude the paper by presenting the results in Section 4.

2. Instruments and observations

We performed multi-epoch, multi-frequency observations using Indian facilities like the Giant Metre-wave Radio Telescope (GMRT), the Ooty Radio Telescope (ORT) operational at radio wavelength, and two payloads aboard AstroSat, the Cadmium Zinc Telluride Imager (CZTI), and the Large Area Proportional Counter (LAXPC). We have also made use of the publicly available data from Fermi-LAT operational at high-energy γ-rays (~20 MeV–300 GeV).

2.1 AstroSat

AstroSat, India’s first space-based observatory was launched in October 2015 with five payloads on board (Singh et al. 2014). These are the Cadmium Zinc Telluride Imager (CZTI; Bhalerao et al. 2017), the Large Area X-ray Proportional Counter (LAXPC; Yadav et al. 2016), the Soft X-ray Telescope (SXT; Singh et al. 2016), the Ultra Violet Imaging Telescope (UVIT; Hutchings 2014) and the Scanning Sky Monitor (SSM) allowing observations covering a wide frequency range from 1300 Å to 380 keV.

2.1.1 LAXPC. The LAXPC is the prime X-ray detector on AstroSat, operating in the energy range 3–80 keV. LAXPC consists of three proportional counter units filled with primarily Xenon gas at a pressure of about 2 atmosphere, presenting a combined effective area of ~6000 cm² at energies below 20 keV, declining to ~2500 cm² at 80 keV (Antia et al. 2017). This large effective area, along with high timing resolution (10 μs) makes this an excellent instrument for X-ray timing studies, including those of pulsars. A collimator restricts the Field of View (FoV) of LAXPC to approximately 1° × 1°. LAXPC detectors record event mode data, with each event tagged with an instrument time stamp derived from a System Time Base Generator (STBG) driven by a temperature controlled crystal oscillator. Once every 16 seconds, a synchronising pulse is sent to all AstroSat instruments including the on-board Spacecraft Positioning System (SPS), which provides time in UTC based on the Global Positioning System. All the instruments record their current time stamp at the arrival of the synchronising pulse and these values are collected in a Time Correlation Table which is used in offline analysis to convert, by interpolation, the instrument time stamps assigned to the recorded events to UTC time stamps (Bhattacharya 2017).

2.1.2 CZTI. The Cadmium Zinc Telluride Imager extends the high-energy coverage of AstroSat to ~380 keV, starting from ~20 keV. It consists of a solid state, pixellated CZT detector array of total geometric area ~976 cm², with a collimator and a Coded Aperture Mask situated above it. The Coded Mask and the collimator provide a 4.6° × 4.6° imaging Field-of-View at energies below ~100 keV and gradually become transparent at higher energies. The CZTI records photon events time stamped at 20 μs resolution by its internal clock. These time stamps are converted to UTC time stamps during offline analysis in the same manner as for the LAXPC instrument. The CZTI has carried out extensive studies of the Crab pulsar at high energies, including that of its polarization (Vadawale et al. 2018).

2.1.3 Orbit determination. Comparing time stamps across observatories requires the arrival times to be referred to a common reference system, for which we adopt the Solar System Barycentre. The event time
stamps recorded by AstroSat are referred to the corresponding Barycentric arrival times, using the knowledge of the orbit of the satellite. The orbital position and velocity of AstroSat are measured by an on-board 10-channel Spacecraft Positioning System (SPS) unit that operates on signals received from the Global Positioning System (GPS) satellites. These measurements are regularly calibrated against those obtained by ranging from the AstroSat ground station. The housekeeping data stream of AstroSat provides the orbital position values sampled every 128 milliseconds, with an accuracy of better than 5 metres. The error budget in the barycentric correction arising from the uncertainties in the orbital position is thus limited to less than 0.017 $\mu$s. We have ignored this contribution in the reported uncertainties in our final results, which are much larger.

2.2 Fermi-LAT

The Fermi-LAT is a high-energy $\gamma$-ray telescope sensitive to the photons with the energy from below 20 MeV to more than 300 GeV (Atwood et al. 2009a). It monitors $\gamma$-ray pulsars with a cadence of one-sixth of its duty-cycle. Individual photon events are recorded with a time resolution better than 1 $\mu$s (Smith et al. 2008). We use data of the Crab pulsar retrieved from the public archive\(^1\) of the Fermi mission.

2.3 The Giant Metrewave Radio Telescope (GMRT)

The GMRT (Swarup et al. 1991) is an “Y”-shaped interferometer with thirty, 45-m steerable dishes operational at low-frequency radio-wavelengths. Fourteen antennas are arranged in a compact array within a radius of 1 km, the remaining antennas are arranged in three arms. The observations were carried out by combining all 14 antennas and the first arm antennas in a tied array with an overall gain of 3.5 K/Jy. The Crab pulsar was observed using the GMRT at seven different epochs (shown with green markers in Fig. 1). The typical timing accuracy\(^2\) at ORT is 318 $\mu$s. The noise-free template was created in PSRCHIVE\(^3\) by fitting an optimal number of Gaussian waveform to a high S/N observed pulse profile. The TOAs obtained from our high cadence observations were then used to create a phase connected solution. Further analysis was done offline described in Section 3.

2.4 The Ooty Radio Telescope (ORT)

The ORT is a 30 m wide offset parabolic cylindrical antenna in the east-west direction. It is 530 m long in the north-south direction sensitive to a single polarisation and operational at 334.5 MHz (Swarup et al. 1971). The gain of the telescope is 3.3 K/Jy and the system temperature is 150 K. The pulsar observations back-end at ORT is called as PONDER (Naidu et al. 2015), which starts recording the data on arrival of the rising edge of the minute pulse obtained from the GPS system. PONDER performs coherent de-dispersion in real-time and produce time-stamped folded pulse-profiles in ASCII format. PSR J0534+2200 was observed for 15 minutes daily as a part of a larger pulsar monitoring program (Krishnakumar et al. 2018) and the high cadence pulsar glitch monitoring program at the ORT (Basu et al. 2019). In this paper, we have used the data from September 01, 2015 (MJD 57226) to January 14, 2017 (MJD 57767).

3. Methodology

The method for the absolute time calibration relies on the technique of pulsar timing. The technique of pulsar timing (Edwards et al. 2006) compares the observed TOAs with the predicted TOAs obtained from a simple rotation model of the pulsars. We perform the analysis in multiple steps in an iterative manner until the best solution is achieved.

3.1 ORT analysis

As mentioned earlier in Section 2.4, coherently de-dispersed time-stamped profiles are obtained from the ORT. The TOA of a pulse was computed using the software package PSRCHIVE (Hotan et al. 2004) from every profile by cross-correlating with a noise-free template of the pulse profile in the frequency domain described in Taylor (1992). The typical timing accuracy\(^2\) at ORT is 318 $\mu$s. The noise-free template was created in PSRCHIVE\(^3\) by fitting an optimal number of Gaussian waveform to a high S/N observed pulse profile. The TOAs obtained from our high cadence observations were then used to create a phase connected solution. Such a high cadence is especially practical because it allows for a more accurate determination of the pulsar's position and velocity, which in turn helps in refining the orbit of the spacecraft.

\(^1\)https://fermi.gsfc.nasa.gov/cgi-bin/ssc/LAT/LATDataQuery.cgi.

\(^2\)We refer the median of the TOA errors as the “typical timing accuracy”.

\(^3\)http://psrchive.sourceforge.net/.

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important for the Crab pulsar to obtain a reliable phase
connected solution because of the strong timing noise.
The timing noise is observed as systematic wandering
in the TOA residuals after removal of the standard
spin-down model (Cordes & Helfand 1980). The
TOAs were further segmented with a time span of a
month to produce the monthly ephemeris from our
data by fitting the spin-down model in the high pre-
cision pulsar timing package TEMPO2 4 (Hobbs
et al. 2006). The monthly ephemeris with precise rotation
parameters was used to re-fold the time-series data to
obtain the precise TOAs. The Crab nebula provides a
strong scattering screen to the radio waves emitted
from the pulsar. The effect of scatter broadening is
pronounced at 334.5 MHz and can contribute to the
timing residuals as a systematic. Hence, in case of the
Crab pulsar, it is difficult to de-couple the effect of
timing noise from the scatter broadening, which in our
analysis has been taken care by using the publicly
available data from Fermi-LAT.

3.2 Fermi-LAT analysis

The $\gamma$-ray pulse profiles are free from the propagation
effects, therefore the Fermi-LAT (Atwood et al. 2009b) archival data5
were used to model the timing noise which is a frequency-independent phenomenon.
We use all the events in the energy range 0.1 to 300
GeV within a radius of 3$^o$ around PSR J0534+2200. The event data were split using Fermi science tool6
into smaller event data each of 7 days duration. These
time stamps were referred to the solar system
barycentre (SSB) adopting JPL planetary ephemeris
DE200 and folded using the Fermi-plugin (Ray et al. 2011) of TEMPO2 using the ephemeris obtained from
the ORT timing solutions. The standard template was
constructed in a similar manner as explained in Section
3.1. However, to account for the intrinsic delay
between the radio and the $\gamma$-ray pulse profile the
templates were aligned with an appropriate shift
mentioned in the Section 1 The TOAs were computed
from every pulse profile by cross-correlating the
standard template. The timing accuracy was 309 $\mu$s.
The timing analysis was performed using TEMPO2.
The timing noise at this band was modelled with the
combination of eight sine waves to obtain the white
timing residuals using the FITWAVES tool in
TEMPO2.

3.3 Re-analysis of the ORT data

The timing solution with modelled timing noise from
the Fermi-LAT TOAs was applied on the ORT TOAs.
At this stage, the TOAs affected from the scatter
broadening were removed from our analysis and
monthly ephemeris were re-generated. Hence, the
rotation parameters were obtained which are free from
timing noise and the scatter broadening effects. We
refer to this timing solution as the “iteration-2”
solution. The iteration-2 solutions were used to re-fold
the ORT time-series data and produce TOAs follow-
ing similar steps as explained in Section 3.1.

3.4 GMRT analysis

The raw voltage data obtained from the GMRT
were also coherently de-dispersed offline with our

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4https://bitbucket.org/psrsoft/tempo2/src/master/.
5https://fermi.gsfc.nasa.gov/cgibin/ssc/LAT/LATDataQuery.cgi.
6https://fermi.gsfc.nasa.gov/ssc/data/analysis/scitools/overview.
.html.
pipeline discussed in Naidu et al. (2015). The values of the dispersion measure (DM) were taken from the Jodrell Bank monthly ephemeris\(^7\) (Lyne et al. 1993) nearest to the epoch of observations. The de-dispersed time-series were further folded using the iteration-2 monthly ephemeris obtained from the ORT data. The GMRT offline analysis also supplies with de-dispersed 64 channel sub-banded data with 32 sub-integrations. The standard template was constructed from the highest S/N observed profile following the same method explained in Section 3.1. The template of the pulse profile from the GMRT data was aligned with the ORT templates and then the TOAs were computed following the method discussed in Section 3.1. The timing accuracy obtained at GMRT is 162 $\mu$s. The dynamic pulsar wind within nebular filaments leads to the variation in the electron density along the line of sight, which results in time variation of the DM. The typical variation in DM is of the order of 0.01 pc cm\(^{-3}\), which incorporates a change in time of arrival by 21 $\mu$s and 370 $\mu$s at 1390 MHz and 334.5 MHz respectively. Therefore it is essential to correct for DM variations to obtain reliable and precise estimates of the offsets. The TOAs computed from the ORT data in Section 3.3 and from the GMRT data were used to measure the DM at different epochs. The fixed offset between the data acquisition pipelines at the ORT and GMRT were known from previous measurements (Surnis et al. 2018). Hence, the DM was estimated after accounting for this delay between GMRT and ORT using the JUMP parameter in TEMPO2. It may be noted that only 8 observations were nearly simultaneous between ORT and GMRT. Therefore, 8 different estimates of DM at 8 different epochs were obtained (Fig. 4 of Basu et al. 2018). The DM was further used to perform the offline coherent de-dispersion to obtain the de-dispersed time series data, which were folded using the iteration-2 timing solutions. The TOAs from the GMRT data were finally produced by following the methods described above.

3.5 AstroSat-CZTI and LAXPC analysis

The CZTI has four detectors arranged in four quadrants. There are no relative offsets between individual quadrants. Hence data from all the four quadrants were combined and the time tags of the photons were converted to SSB adopting the JPL planetary ephemeris DE200 and using the satellite position in the code asl\(^8\)bary. The barycentre recorded events were folded to construct the pulse profile using iteration-2 timing solution obtained in Section 3.3 using our own codes. Further, the standard template was created following the same method as described in Section 3.1. In case of LAXPC, the event files were created by combining the data from three consecutive orbits, which were then barycentred using the asl\(^8\)bary and folded using the iteration-2 timing solution obtained in the Section 3.3. The standard templates were created following a similar method as mentioned above. The templates obtained from the CZTI and the LAXPC were appropriately shifted with respect to those obtained from the GMRT, ORT and Fermi-LAT to take into account the intrinsic energy-dependent emission delays. Finally, the TOAs were computed for the CZTI profiles and the LAXPC profiles using the templates thus constructed. This method of incorporating the known energy-dependent intrinsic emission delays in the template construction allows us to find the true clock offsets between two instruments directly from the TOA differences between them.

3.6 Offset measurements

The TOAs from all the telescopes were collated together to compute the offsets between the different telescopes. These TOAs were analysed using a timing model obtained by merging the pulsar rotation model, which gave the phase connected solution, with a constrained DMMODEL in TEMPO2. The DMMODEL is obtained from the DM time series, fitted from simultaneous observations at the ORT and the GMRT using the procedure described in Section 3.4. Inclusion of DMMODEL terms in the timing model accounts for the DM offsets from the chosen reference DM. The timing residuals obtained by applying this timing model to TOAs from all the telescopes have been shown in the upper panel of Fig. 1. The systematic trend as a function of time in these residuals for all telescopes is due to the timing noise of the pulsar. The residuals represent the difference between the predicted and the observed TOAs. As the TOA from each telescope additionally consists of a clock offset which is fixed with respect to the observation epoch, the residuals of a pair of telescopes are seen as parallel tracks in the diagram. Thus, fitting a constant

\(^7\)http://www.jb.man.ac.uk/pulsar/crab.html.  
\(^8\)http://astrosat-ssc.iucaa.in/?q=data_and_analysis.
difference to residuals of a pair of telescope in Fig. 1 determines the timing offsets between the telescopes.

The timing model, described above, was merged with the timing noise model obtained in Section 3.2. This reference timing solution after accounting for the timing noise and the DM variation is given in Table 1.

Finally, we use the JUMP feature of TEMPO2 to measure the offsets between the telescopes discussed in Section 4.

### 4. Results

TEMPO2 allows one to measure the offsets between different telescopes using the JUMP feature. Utilising this, we estimate the offset between the GMRT and CZTI to be \(-4716 \pm 50 \mu s\) and that between GMRT and LAXPC to be \(-5689 \pm 23 \mu s\). The measured offset between the GMRT and ORT is \(-29639 \pm 50 \mu s\), between GMRT and \textit{Fermi-LAT} is \(-5368 \pm 56 \mu s\). These clock offsets have been further tabulated in Table 2. The phase aligned pulse profile after accounting for the offsets has been presented in the Fig. 2. In the bottom panel of Fig. 1, we present the timing residuals obtained after removing the timing offsets between them. The trend-free residuals imply that all the pulsar parameters and clock offsets have been properly modelled. The clock offset between the LAXPC and the CZTI instruments aboard AstroSat is found to be 969 \(\pm 51 \mu s\). The uncertainties in the offsets are obtained from those of the parameters fitted to the TOA using the JUMP function. The results presented here meet the desired accuracy (see Section 1) for a multi-wavelength investigation of the GRP from the Crab pulsar with the instruments used in this paper.

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#### Table 1. Table presents the reference timing solution of the Crab pulsar after considering the effect of DM variation and the timing noise.

| Pulsar parameter   | Value                              |
|--------------------|------------------------------------|
| RAJ (hh:mm:ss)     | 05:34:31.973                       |
| DECJ (dd:mm:ss)    | +22:00:52.06                       |
| F0 (Hz)            | 29.6607409(4)                      |
| F1 (Hz s\(^{-1}\))| \(-3.6937842(9) \times 10^{-10}\)  |
| F2 (Hz s\(^{-2}\))| 1.1905(3) E\(-20\)                |
| PEPOCH (MJD)       | 57311.000000136                    |
|POSEPOCH (MJD)      | 40675                              |
| DMEPOCH (MJD)      | 57311.000000136                    |
| DM (pc cm\(^{-3}\))| 56.7957                            |
| PMRA (mas/year)    | \(-14.7\)                          |
| PMDEC (mas/year)   | 2                                 |
| WAVE_OM (year\(^{-1}\))| 0.0054325986245627               |
| Solar system planetary ephemeris | DE200 |
| WAVEPOCH (MJD)     | 57311.000000136                    |
| START (MJD)        | 57278                              |
| FINISH (MJD)       | 58026                              |

#### Table 2. The table summarises the clock offsets of different telescopes given in the first column with respect to the GMRT.

| Instrument | Clock-offsets in \(\mu s\) |
|------------|-----------------------------|
| AstroSat-CZTI | \(-4716 \pm 50\)         |
| AstroSat-LAXPC | \(-5689 \pm 23\)         |
| Fermi-LAT   | \(-5368 \pm 56\)         |
| ORT         | \(-29639 \pm 50\)        |

#### Figure 2. The multi-wavelength pulse profiles of the Crab pulsar. The pulse profiles were aligned after correcting the clock-offsets between the telescopes.
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