Signatures of the Galactic bar in high-order moments of proper motions measured by Gaia

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ABSTRACT

Our location in the Milky Way provides an exceptional opportunity to gain insight on the galactic evolution processes, and complement the information inferred from observations of external galaxies. Since the Milky Way is a barred galaxy, the study of motions of individual stars in the bulge and disc is useful to understand the role of the bar. The Gaia mission enables such study by providing the most precise parallaxes and proper motions to date. In this theoretical work, we explore the effects of the bar on the distribution of higher-order moments – the skewness and kurtosis – of the proper motions by confronting two simulated galaxies, one with a bar and one nearly axisymmetric, with observations from the latest Gaia data release (Gaia DR2). We introduce the code ASGAIA to account for observational errors of Gaia in the kinematical structures predicted by the numerical models. As a result, we find clear imprints of the bar in the skewness distribution of the longitudinal proper motion $\mu_\phi$ in Gaia DR2, as well as other features predicted for the next Gaia data releases.

Key words. Galaxy: structure – Galaxy: evolution – Galaxy: kinematics and dynamics – methods: numerical

1. Introduction

Bars are commonly observed in local disc galaxies, with fractions ranging from one- to two-thirds (Eskridge et al. 2000; Marinova & Jogee 2007; Sellwood 2014). The study of motions of individual stars in the Milky Way is key to understanding the signature of the bar on the kinematics of these galaxies. These effects have been reported on the motion of neutral hydrogen regions (de Vaucouleurs 1964), on the orbits of globular clusters (Boyliev & Bajkova 2017; Pérez-Villegas et al. 2018), on the vertex deviation (Zhao et al. 1994), the longitudinal asymmetry in the proper motion dispersion (Rattenbury et al. 2007a), and on the Oort constants (Comeron et al. 1994; Torra et al. 2000; Olling & Dehnen 2003; Minchev et al. 2007; Bovy 2017). Furthermore, the presence of the bar has been proposed as an explanation for the high-velocity peaks discovered by Nidever et al. (2012) in the bulge (Molloy et al. 2015), and the kinematics of the Hercules stream (Dehnen 2000; Gardner & Flynn 2010; Pérez-Villegas et al. 2017; Hunt et al. 2018) and other moving groups (Kalnajs 1991; Minchev et al. 2010).

In Palicio et al. (2018), we explored the higher order moments of the line-of-sight velocity distribution ($V_{LOS}$) to conclude that it is possible to infer the presence of the bar from the skewness (Zasowski et al. 2016) and the kurtosis distributions. In this work we extend our previous study to analyse the high-order moments of the proper motion, and make predictions for the results of the Gaia mission (de Bruijne 2012; Gaia Collaboration 2016), modelling observational errors and constraints. This paper is organised as follows. In Sect. 2 we introduce the numerical simulations to be used and the modifications adopted to improve the modelling of the Milky Way. In Sect. 3 we describe the code ASGAIA, which synthesises the stellar populations of the simulation particles including observational errors for Gaia. The results are discussed and summarised in Sects. 4 and 5, respectively.

2. Simulation data description

We make use of the two simulated galaxies introduced in Palicio et al. (2018) to explore the imprints of the bar on the distribution of proper motions. The initial conditions of these simulations consist on an exponential disc embedded in a $\sim10^{11} M_\odot$ dark matter halo, with a Toomre $Q$ parameter of 1.5. The simulations only differ in the distribution of baryonic matter: for one simulation the inner 7 kpc of the disc contains 30% of the total mass, while for the other this fraction is larger (50%). After 2.52 Gyr, the latter simulation develops a 4.5 kpc half-length bar with a pattern speed $\Omega_\phi \approx 30$ km s$^{-1}$ kpc$^{-1}$, while the former remains nearly axisymmetric with weak spiral arms, until the final time (~4.5 Gyr).

In order to compare the simulations to Milky Way observations, we rotate both galaxies to get an orientation angle of $\phi = 25^\circ$ with respect to the Sun-Galactic centre direction (Stanek et al. 1997; Freudenreich 1998; López-Corredoira et al. 2005; Rattenbury et al. 2007b; Shen et al. 2010; Wegg & Gerhard 2013; Cao et al. 2013; Nataf et al. 2015). This rotation is also applied to the unbarred galaxy to account for the orientation of the spiral arms. The density maps of the two simulations are shown in Fig. 1. We define the solar position at $R_0 = 8.0$ kpc from the Galactic centre, with a positive Galactic height of $Z_0 = 25$ pc. Since Gaia provides proper motions in the barycentric rest frame, we correct the velocities by adding the solar motion component $V_\odot = (U_\odot, V_\odot, W_\odot) = (11.10, 241.92, 7.25)$ km s$^{-1}$ kpc$^{-1}$ (Reid & Brunthaler 2004; Schönrich et al. 2010) to the velocities given in the galactocentric rest frame.
Fig. 1. Mass-density map for the barred (left panels) and the axisymmetric (right panels) models. The dashed black lines correspond to the edges of the bar and bulge areas defined in Sect. 2, while the blue lines represent the line of sight between $\ell = -45^\circ$ and $\ell = 45^\circ$ with steps of $15^\circ$. The Sun is denoted by a blue spot at $(X, Y, Z) = (0, -8.0, -0.025)$ kpc.

We adopt the metallicity distribution proposed by Portail et al. (2017) for the central regions of the Milky Way, which is specified by the relative contribution of four [Fe/H] bins: $A$ ($0 < [\text{Fe/H}] \leq 0.5$), $B$ ($-0.5 < [\text{Fe/H}] \leq 0$), $C$ ($-1 < [\text{Fe/H}] \leq -0.5$), and $D$ ($-1.5 < [\text{Fe/H}] \leq -1$). According to this model, the bar is dominated by metal-rich stars (the contribution of the A–D bin is $52 \pm 3\%$, $34 \pm 1\%$, $12 \pm 1\%$, $2 \pm 1\%$), while the disc is populated mainly by stars of lower metallicity ($38 \pm 3\%$, $47 \pm 1\%$, $14 \pm 1\%$, $1 \pm 1\%$). In the barred model, via visual inspection, we define the bar as the region inside the ellipse with $4.5$ kpc and $1.7$ kpc semi-axes, with a position angle of $25^\circ$. The same metallicity distribution is considered for the bulge of the axisymmetric model, defined as the region inside the inner $1.7$ kpc. We adopt $Z_0 = 0.0122$ (Asplund et al. 2006) as the solar metallicity.

In terms of ages we adopt a simple Gaussian model for the bar and bulge centred at $10$ Gyr, with an age dispersion of $3$ Gyr. For the disc the distribution of ages is described as a truncated Gaussian distribution with a mean age of $5$ Gyr, and $4$ Gyr of dispersion, similar to that used in Queiroz et al. (2018). We decided not to use the ages and metallicities from the self-consistent simulations because the age of the initial disc was fixed at $7$ Gyr, with solar metallicity as starting point for the chemical evolution.

3. ASGAIA code

In order to extract stellar population properties from the simulation particles, we developed the code ASGAIA, which allows us to track the statistics of the underlying stellar population in a more direct fashion than other codes, such as GALAXIA (Sharma et al. 2011) or SNAPDRAGONS (Hunt et al. 2015).

The main purpose of ASGAIA is to compare models of the Milky Way galaxy to observations, and in particular statistics derived from Gaia data, taking into account observational constraints. It estimates the magnitude in the $G$ band (Jordi et al. 2010) and the astrometric errors using the method described in Gaia Collaboration (2016) and in the Gaia Science Performance web pages. In this context, the magnitude in the $G$ band and the end-of-mission parallax error ($\sigma_\pi$) are approximated by third-order polynomials in $V$ and $I$.

The Gaia selection function is modelled by imposing an additional brightness restriction of $3 \leq G < 20$ mag. We exclude sources brighter than $G = 3$ mag because special observing modes are used for these sources (Martín-Fleitas et al. 2014; Sahlmann et al. 2016; Gaia Collaboration 2016).

The end-of-mission errors in position and proper motions are given by conversion factors which vary over the sky due to the Gaia scanning law. To a first approximation, we assume there are no correlations among the errors of the astrometric parameters.

To model the stellar populations, ASGAIA makes use of the same set of PARSEC isochrones (Marigo et al. 2008; Bertelli et al. 1994) and extinction maps as GALAXIA and SNAPDRAGONS, with the extinction corrections from the Schlegel $E(V - B)$ map (Schlegel et al. 1998) proposed by Bland-Hawthorn et al. (2010) and Sharma et al. (2014). The isochrones can be populated according to the Salpeter (Salpeter 1955) or the Kroupa (Kroupa 2001) initial mass functions (IMF), both truncated at the highest stellar mass of each isochrone.

For each simulation particle, ASGAIA provides the number of stars potentially observable by Gaia, with their mean parallax error at the end of the mission. These quantities are estimated directly from isochrone sampling, without creating mock catalogues, by reducing the computation time and the size of the output files. More details on ASGAIA will be provided in a forthcoming paper.

4. Results

We consider the $\ell - d_h$ (galactic longitude and plane-projected distance) projection introduced in Palicio et al. (2018) to show

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1 https://bitbucket.org/pedroap/asgaia.git

2 https://www.cosmos.esa.int/web/gaia/science-performance

3 http://stev.oapd.inaf.it/cgi-bin/cmd
the maps of the skewness and kurtosis. Since this face-on projection keeps the line of sight fixed, the distance uncertainties shift the sources along one axis, and the increasing size of the bins with \( d_b \) compensates for the decreasing number of observed stars. We restrict our study to the disc by imposing the cutoff in the galactic height \( |Z| < 1 \) kpc.

The skewness and kurtosis of the proper motions are calculated as

\[
\text{skew}(x) = \frac{\langle (x - \langle x \rangle)^3 \rangle}{\sigma^3}
\]

\[
\text{kurt}(x) = \frac{\langle (x - \langle x \rangle)^4 \rangle}{\sigma^4} - 3
\]

where \( \sigma \) refers to the standard deviation of the proper motion distribution and the rightmost term of Eq. (2) subtracts the kurtosis of a Gaussian distribution. The averages in these equations are weighted by the mass of the simulation particles or by the number of observed stars, depending on the case.

In order to illustrate the role of the higher order moments in the distribution, we select two disc regions in both simulations and compute their distributions of proper motions (Fig. 2). These regions correspond to two circular areas of radius 0.6 kpc, centred at \((\ell, d_b) = (20^\circ, 7.25 \text{ kpc})\) and \((\ell, d_b) = (-10^\circ, 4.5 \text{ kpc})\), with the constraint \( |Z| < 1 \) kpc (see Fig. 3). As the first column in Fig. 2 shows, the distribution of longitudinal proper motions in the barred model is clearly asymmetric, with a tail extended towards positive (negative) \( \mu_\ell \) values when the distribution is skewed positive (negative). In the axisymmetric model, only the distribution of the nearest region is significantly skewed, with skew(\( \mu_\ell \)) \approx -0.330.

Since the skewness of the latitudinal proper motion is almost zero for both galaxies, the histograms of \( \mu_b \) (last column in Fig. 2) illustrate more clearly the role of the kurtosis in the shape of distributions. As the kurtosis increases, the latitudinal proper motions are more concentrated around the peak, in contrast to the flatter distribution observed when kurt(\( \mu_b \)) is negative (lower right panel). This result agrees with the traditional, but controversial, interpretation of the kurtosis as an indicator of the peakedness of distributions, which has been proved to be generally untrue (Kaplansky 1945; Westfall 2014), although but still valid for some distribution families.

4.1. Ideal maps

Figure 3 illustrates the maps of the skewness and kurtosis of the proper motions extracted directly from the simulations. In these maps, the contribution of each particle is weighted by its mass, and no selection function is applied. The odd columns in Fig. 3 show the higher order moments of \( \mu_\ell \) (the proper motion along the direction of galactic longitude) for both simulations. As can be seen in the first panel, the largest \( |\text{skew}(\mu_\ell)\rangle \) values trace the contour of the bar, with opposite signs on opposite sides. On the contrary, the unbarred model predicts a wide positive (negative) skewed area at heliocentric distances longer (shorter) than \( R_0 \) (8 kpc). The major discrepancies are found between the leading edges and the minor axis of the bar,
where the axisymmetric model is skewed to the opposite side with respect to the barred model.

Regarding the kurtosis, the barred simulation shows a uniform distribution of \( \kurtosis(\mu_\ell) < 0 \) disrupted by an enhancement of positive values at the bar edges, similar to that observed for \( V_{\text{LOS}} \) (Palicio et al. 2018). In the axisymmetric model, the kurtosis is positive almost everywhere, with two regions of high kurtosis \( (\kurtosis(\mu_\ell) > 1) \) at \( (\ell, d_b) \approx (0^\circ, 5.5 \text{ kpc}) \) and \( (0^\circ, 11 \text{ kpc}) \), respectively.

The even columns in Fig. 3 summarise the results for the latitudinal proper motions \( \mu_b \). Due to the vertical symmetry in the two galaxies, the maps of the skewness show a flat distribution of skew\((\mu_b) \approx 0 \) almost everywhere, with no discrepancies between the models. On the other hand, the negative values of kurt\((\mu_b) \) in the bar region contrast with the uniform distribution of positive kurtosis predicted by the axisymmetric model. As can be seen in the second row of Fig. 3, two areas of opposite sign clearly define the bar \( (\kurtosis(\mu_b) < 0) \) and the disc \( (\kurtosis(\mu_b) > 0) \) regions. The kurtosis is highest beyond the bar at \( 0^\circ < \ell < 20^\circ \) \((\kurtosis(\mu_b) > 1.0)\), and lowest in the middle of both arms \((\kurtosis(\mu_b) < -0.5)\).

By rotating each particle of the axisymmetric model by a random angle, we verified that the spiral structure is not main factor responsible for the observed features. The obtained maps are completely indistinguishable from the original ones with spiral arms.

### 4.2. Realistic maps

In contrast to Palicio et al. (2018), we extend the longitudinal range towards \( \ell < 0^\circ \) to study the effects of the approaching side of the bar, which was omitted due to the lack of sources at negative longitudes in APOGEE DR14 (Abolfathi et al. 2018).

In order to estimate the number of observed stars \( N_{\text{obs}} \) and the mean proper motion error \( \sigma_\mu \) for each particle, we run ASGAIA assuming a Kroupa IMF and a science margin of 20%\(^4\). We multiply the mean proper motion errors by a factor of \((60/n)^{1.5}\) (Mor et al. 2015), where \( n = 22 \) is the number of months of data collection used in Gaia DR2, to correct the values estimated for the end of the mission. In order to compare the predictions with the observations, we make use of the optional cutoff in \( \sigma_\mu/\sigma \) implemented in ASGAIA.

Once the proper motion errors for all the particles are known, their contributions to the averages in Eqs. (1) and (2) are weighted by \( N_{\text{obs}} \), and smoothed with the Gaussian kernel

\[
K(\mu, \bar{\mu}, \sigma_\mu^2) = \frac{1}{\sqrt{2\pi}\sigma_\mu} \exp \left( \frac{(\mu - \bar{\mu})^2}{2\sigma_\mu^2} \right)
\]

where \( \mu \in [\mu_\ell, \mu_b] \) and \( \bar{\mu} \) is the proper motion of the particle. This procedure is averaged over 50 realisations of the heliocentric distances of the particles, blurred by a Gaussian distribution with dispersion \( \sigma_\sigma = \sigma_\sigma d_d^2 \).

The predictions for Gaia DR2 assuming different cutoffs in \( f = \sigma_\sigma/\sigma \) are shown in Fig. 4. In general, the inclusion of the proper motion errors blurs the features predicted in the ideal case, and reduces the absolute values of the higher order moments, which implies a higher Gaussianity in the distribution of proper motions. For the barred simulation, the high-skew\((\mu_\ell) \) area expected from Fig. 3 is not observed when \( f = 0.15 \), while for higher values of \( f \) we can discern a region with skew\((\mu_\ell) \geq 0.3 \) beyond the near bar arm \((d_b \geq 7 \text{ kpc})\). On the contrary, it is possible to identify the low-skewness region \((\text{skew}(\mu_\ell) < -0.3)\) at negative longitudes even for \( f = 0.15 \), although for \( f \geq 0.25 \) its shape is more consistent with the predictions.

For the axisymmetric model, we observe a low-skew\((\mu_\ell) \) region extended along the \( \ell \approx 0^\circ \) direction for \( f = 0.15 \). For higher values of \( f \), this structure becomes more circular and restricted to distances \( d_b \leq 8.0 \text{ kpc} \), being consistent with that predicted in the ideal case (Fig. 3). Although we can infer some small areas of positive skewness \((\text{skew}(\mu_\ell) \geq 0.30)\) at \( d_b \geq 8.0 \text{ kpc} \) for \( f > 0.20 \), we cannot conclude they are part of the high-skew\((\mu_\ell) \) region observed in Fig. 3 since they are not centred at \( \ell = 0^\circ \).

Regarding the latitudinal proper motions, both models are in agreement with the expected non-skewed distributions of \( \mu_b \),

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\(^4\) The science margin is a contingency factor introduced in Gaia Collaboration (2016) to account for the calibration errors and other non-ideal scenarios, such as crowded regions or background peculiarities. We assume the default value (20%) reported in literature.
Fig. 4. Maps of the higher order moments of $\mu_1$ (odd columns) and $\mu_b$ (even columns) predicted for the Gaia DR2 (22 months of observations). The same convention as in Fig. 3 is used. White areas, if present, correspond to empty bins. From top to bottom: $\sigma_\alpha/\pi = 0.15, 0.20, 0.25, \text{ and } 0.30$. 
skew(μ) region, however, is well defined in both simulations, with decreasing values of skew(μ) as f increases.

The additional observing time has no major effects on the skewness of the latitudinal proper motions. The distributions of skew(μ) show the homogeneous pattern similar to that of the n = 22 case, with weaker distortions at d_b ≥ 8 kpc for f ≤ 0.20 compared to Fig. 4.

As can be seen in Fig. 6, the reduction of the Gaia astrometric errors does not have a significant effect on the maps of the kurtosis, although it is possible to discern differences between the models in the distribution of kurt(μ). In the axisymmetric model, we can identify an almost circular region of high kurtosis (>1) in the area of skew(μ) < 0 (d_b < 8 kpc), and a more irregular region beyond the galactic centre in which kurt(μ) < −0.5.

On the contrary, the barred simulation shows an irregular area of lower kurtosis in the near bar arm, which is strongly affected by the imposed cutoff in f.

In general, the increment in the number of sources per bin due to the additional observing time predicts no qualitative effects on the maps for f ≤ 0.20, but an enhancement of the features revealed with n = 22 months. This is not the case of the positive kurt(μ) area found at ℓ > 0 for f = 0.30, in which the additional observing time increases the number of sources per bin from −10^5 to −10^−15 (see Figs. 5 and 7). Similarly, for f = 0.15 the increment from −10^5 to −10^−5 stars per bin makes it possible to infer part of the high-skew(μ) region expected beyond the near bar arm.

We estimate the significance of the observed features by propagating the errors in proper motions to the skewness and kurtosis. We can discern the areas of opposite sign in the skewness distribution of μ, for n = 22, f ≥ 0.20, with Δskew(μ) > 28σ (18σ) for the barred (axisymmetric) model. At the end of the mission, the estimated significance of Δskew(μ) is greater than 140σ for the barred simulation and 88σ for the axisymmetric model.

### 4.3. Observations

We compare our predictions with the latest Gaia Data Release (Gaia Collaboration 2018), which provides parallaxes, positions, and proper motions for more than 1.33 million sources observed during 22 months of mission. We make use of the distances estimated by Bailer-Jones et al. (2018) because the inverse of the parallax leads to biased distances (Kovalevsky 1998; Bailer-Jones 2015; Astraatmadja & Bailer-Jones 2016; Luri et al. 2018) for large relative parallax errors. These distances correspond to the mode (median) of the unimodal (bimodal) posterior probability distribution function (PDF) calculated using only the astrometric data, without invoking the photometric data of the sources or the extinction. The likelihood of this Bayesian model is assumed to be Gaussian, while the prior is the exponential distribution introduced in Bailer-Jones (2015), in which its length scale depends on the star position on the sky. We adopt one-half of the separation between the r_0 and r_0 parameters as an estimation of the uncertainty (δd). These quantities correspond to the bounds of the highest density interval (HDI) or the equal-tailed interval (ETI), depending on the shape of the posterior probability distribution (p = 0.6827). We refer to Sect. 2.2 in Bailer-Jones et al. (2018) for a further explanation of these parameters.

We focus on the same region of the disc as in the numerical models (−45° ≤ ℓ < 45°, 3 ≤ d_b < 12 kpc and |Z| < 1 kpc) with the additional restriction of 3 ≤ G < 20 mag. We exclude the stars with large fractional errors in proper motions by imposing...
Fig. 6. Same as Fig. 4, but at the end of the Gaia mission (60 months of observations).
\[ \delta \mu \leq 0.1 \mu, \quad \text{with} \quad \mu^2 = \mu_0^2 + \mu_1^2 \quad (\mu_0 \equiv \mu_\alpha \cos \delta) \quad \text{and} \]
\[
\delta \mu = \mu^{-1} \sqrt{\left(\mu_\alpha^2 \delta \mu_\alpha^2 + (\mu_\alpha \delta \mu_\alpha)^2 + 2 \rho (\mu_\alpha \delta \mu_\alpha) (\mu_\delta \delta \mu_\delta)\right)},
\]
where \( \rho \) is the correlation between the equatorial proper motions \( \mu_\alpha \) and \( \mu_\delta \). Once these constraints are applied, we create four subsets based on the relative distance errors \( f = 0.15, 0.20, 0.25, \) and 0.30, denoted as \( \text{Gaia} \ DR2_x \) with \( x = 100f \). These distance cutoffs are larger than the widely used 10% relative error because with such a restrictive constraint we get less than 100 stars in most of the bins beyond ~4 kpc. Therefore, it is necessary to use a more permissive distance error restriction to explore the most distant regions, with the caveat that some results may not be completely accurate at high \( f \). The contribution of each star to the averages involved in the computation of the higher order moments is weighted by the inverse of the distance uncertainty \((1/\delta \mu)\).

It is worth noting that our aim is to demonstrate whether it is possible to detect the predicted structures in the data available, not to reproduce them quantitatively. The comparison between the simulations and the \( \text{Gaia} \) proper motions must be understood in a qualitative way, since their particular values depend on bar parameters such as the shape or the pattern speed, whose study is beyond the scope of this paper.

The results for all the \( \text{Gaia} \) data subsets are summarised in Fig. 8. For the \( \text{Gaia} \ DR2 \) data set, we can discern the asymmetric low-skew(\( \mu_\ell \)) area expected from the barred simulation at \( \ell < 0^\circ \), while the high-skewness region is not observed due to the lack of sources beyond ~7 kpc. This longitudinal asymmetry in the pattern of skew(\( \mu_\ell \)) becomes more evident as \( f \) increases. On the contrary, the high-skewness region is not recovered, although minor areas of positive skew(\( \mu_\ell \)) can be inferred at \( \ell \gtrsim 15^\circ \) and \( d_0 \approx 9 \) kpc. The observed latitudinal proper motion patterns confirm the almost zero skew(\( \mu_\phi \)) map expected from the vertical symmetry of the Galaxy, with minor distortions in the distant regions. These distortions can be explained by the low number of sources contained in the farther bins. Figure 9 shows the maps of skew(\( \mu_\phi \)) for eight different subsampling realisations of the models with the same spatial distribution as \( \text{Gaia} \ DR2 \). As can be seen, the larger discrepancies from the flat skew(\( \mu_\phi \)) pattern are observed at the most distant regions, which correspond to the lower populated bins in the observations.

The distribution of the observed kurtosis evolves from a uniformly decreasing trend with distance (low \( f \)) to a more complex pattern (high \( f \)). For \( f = 0.30 \), the observations reveal an elliptical area of kurt(\( \mu_\ell \)) \( \lesssim 1.0 \), embedded in a region of higher kurtosis (kurt(\( \mu_\ell \)) \( > 1.5 \)). Though it is tempting to consider this elliptical shape evidence of the presence of a bar, the barred model does not reproduce the observed distribution of kurtosis, showing negative values in the bar region and an offset of \( \sim -2 \) in the disc of the disc. The discrepancy in kurtosis to three main factors:

1. Since the kurtosis involves the fourth-order moments, it requires a larger number of sources compared to the other lower order estimators, such as the dispersion or the skewness, to get reliable results.
2. The kurtosis constitutes a measurement of contribution of the outliers (Kaptons 1945; Ali 1974; Decarlo 1997; Westfall 2014), which in the case of the proper motions are not bounded, and are difficult to include in the models. The analysis in detail of the observed proper motions in the highly populated areas of Fig. 8 reveals a single-peaked distribution of \( \mu_\ell \) with a flattened maximum, while the distribution of \( \mu_\phi \) shows a much sharper mode.

3. We verified that the kurtosis is more sensitive to the distance and proper motions errors, and to the size of the bins, than the other estimators. This can be seen in the evolution of the maps as \( f \) increases. We must emphasise that in order to explore the regions beyond ~4 kpc, we have considered a distance cutoff larger than the usual 10%, which implicitly leads to larger errors and blurred features.

5. Summary

The analysis of the higher order moments of the proper motion can reveal signatures of the bar on the galactic kinematics. In particular, it is possible to discern the bar shape and orientation from the areas of opposite sign in skew(\( \mu_\ell \)), in contrast to the almost circular regions predicted by the axisymmetric model. Part of this structure, the low-skew(\( \mu_\ell \)) region, is observed in the most recent \( \text{Gaia} \) data release, although it requires a distance error cutoff that is less restrictive than the usual 10%.

On the contrary, the maps of the observed kurt(\( \mu_\ell \)) and kurt(\( \mu_\phi \)) show an area of positive kurtosis which differs significantly from the almost zero values predicted by the simulations. Increasing the relative distance error cutoff, we find a tentative elliptical structure compatible in location and orientation with the nearest bar arm. Based on our tests, we attribute the discrepancy in the kurtosis maps to a greater sensitivity of the fourth-order moment on the errors and outliers. Our simulations with the code ASGAIA suggest that the expected features in kurt(\( \mu \)) will not be much easily resolved in the \( \text{Gaia} \) end-of-mission data, but the contrast between the high- and low-skewness region in \( \mu_\ell \) will allow us to differentiate between the models.
Fig. 8. Maps of the skewness (odd rows) and kurtosis (even rows) of the observed longitudinal (first column) and latitudinal (second column) proper motions of Gaia DR2. The number of sources per bin is shown in the third column. Each block corresponds, from top to bottom, to the $f = \sigma_{\varpi}/\varpi$ cutoff of 0.15, 0.20, 0.25, and 0.30. The Galactic centre and the bar are denoted by the black spot at $d_b = R_0$ and the solid line, respectively. The half-length and orientation angle of the bar are set to 4.5 kpc and 25°, respectively.
Fig. 9. Maps of skew $(\mu_b)$ for eight different subsamplings of the models with the same spatial distribution as the Gaia DR2 subset. The first and second columns correspond to the barred simulation while the two last columns show the maps expected for the axisymmetric model. The number of observing months is set to $n = 22$ and the maximum relative parallax error is $f = 0.25$.

For the latitudinal proper motion, no features are expected in the distribution of skew$(\mu_b)$ since both galaxies are vertically symmetric. We also find significant effects induced by the selection function, which distorts the flat pattern of skew$(\mu_b)$, reduces the kurtosis, and makes the distributions of proper motions more Gaussian.

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