Intrinsic time-uncertainties and decoherence: comparison of 4 models

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Four models of energy decoherence are discussed from the common perspective of intrinsic time-uncertainty. The four authors — Milburn, Adler, Penrose, and myself — have four different approaches. The present work concentrates on their common divisors at the level of the proposed equations rather than at the level of the interpretations. General relationships between time-uncertainty and energy-decoherence are presented in both global and local sense. Global and local master equations are derived. (The local concept is favored.)

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I. INTRODUCTION

Let me begin with an incomplete list of people who formulated ideas related to the possible role of time or space-time uncertainties in the destruction of quantum coherence. Certainly Feynman mentioned the idea first, and a Hungarian group developed a first vague model. From Penrose to Steve Adler and during twenty years, many independent investigations shared the central idea and disagreed on the motivations. In the rest of the present contribution I single out four authors: Penrose, myself, Milburn, and Adler. They have four different motivations: Penrose exposes the conceptual uncertainty of location in space-time, I attribute an ultimate uncertainty to the Newtonian gravitational field, Milburn assumes that Planck-time is the smallest time, and Adler derives quantum theory in the special limit of a hypothetic fundamental dynamics. The four authors also have four different mathematical apparatuses, four different interpretations, metaphysics, e.t.c., but the four models have common divisors and my present intention is to find and emphasize them. The reader shall see that the Milburn master equation is identical to the simplest effective equation derived by Adler in his dynamical theory, and Penrose’s equation is a special case of my master equation.

II. ENERGY DECOHERENCE

Decoherence means the destruction of interference. When it happens to energy eigenstates, we talk about energy decoherence. Decoherence diminishes coherent dispersion like $\Delta E$ in case of energy decoherence. Too large coherent dispersions mean that the system exhibits strong quantum features. On the contrary, if the coherent dispersions are reasonably small the system looks like a classical one. Since decoherence can diminish coherent dispersions we think that decoherence is instrumental in the emergence of classicality in quantum systems. Decoherence of various observables may be correlated or anti-correlated. Decoherence of the local energy will induce decoherence of location of massive objects. There is no definite rule as to what observable is the primary one to induce decoherence of the others and to cause eventual classicality of the macroscopic variables. There is no apriori rule as to what are the macroscopic observables and what is the threshold for classically small dispersions. Yet, a consistent decoherence model, even if it is phenomenological, would make suggestions for the primarily decohering observables and for the dynamics of their dispersions. Total energy is a possible choice to start with, and it leads us to the concept of local energies as the primarily decohering observables. Energy decoherence has intimate relationship with the intrinsic uncertainty of time, elucidated below in subsections I A and I B.

Decoherence is, similarly to many other irreversible mechanisms, fueled by the complexity of the exact dynamics, like in the Adler theory (Sec IV). The other three theories discussed later in Secs III, V, VI derive decoherence from non-dynamic mechanisms. They assume inherent randomness of time. The typical effect is a simple exponential decay of coherence at a certain decoherence time scale $t_D$. This exponential rule has been met by almost all dynamic models as well as by the four ones singled out for the present discussion. The Milburn-Adler decoherence-time is on the scale of the Planck-time $\tau_{Pl}$, the Diósi-Penrose theory assumes non-relativistic
decoherence-time. I shall abandon the complex details of these theories and wish to compare them at the level of their ultimate phenomenological equations.

A. Global time uncertainty and decoherence

Let me illustrate the naive phenomenology of energy decoherence emerging from time uncertainty. For simplicity, suppose that the initial state of a quantum system is a superposition of only two energy eigenstates of the total Hamiltonian $H$:

$$|\psi\rangle = c_1 |\varphi_1\rangle + c_2 |\varphi_2\rangle .$$

(1)

The evolution of the state in time $t$ reads:

$$|\psi(t)\rangle = c_1 \exp(-i\hbar^{-1}E_1 t)|\varphi_1\rangle + c_2 \exp(i\hbar^{-1}E_2 t)|\varphi_2\rangle .$$

(2)

Following our purposes, we add a certain uncertainty $\delta t$ to $t$:

$$t \rightarrow t + \delta t ,$$

(3)

and substitute it into the Eq.(2). To be concrete, suppose $\delta t$ is a Gaussian random variable of zero mean and of dispersion proportional to the mean time $t$ itself:

$$M[(\delta t)^2] = \tau t ,$$

(4)

where $\tau$ is a certain time-scale to measure the strength of time-uncertainties. We can evaluate the evolution of the density matrix:

$$\rho(t) \equiv M \langle |\psi(t)\rangle \langle\psi(t)| \rangle =$$

$$= |c_1|^2 |\varphi_1\rangle \langle\varphi_1| + |c_2|^2 |\varphi_2\rangle \langle\varphi_2| +$$

$+ \{c_1^* c_2 \exp(i\hbar^{-1}\Delta E t) M \langle \exp(i\hbar^{-1}\Delta E \delta t) \rangle |\varphi_2\rangle \langle\varphi_1| +$$

$+ \text{h.c.} \} .$$

The stochastic mean on the r.h.s. yields:

$$M \langle \exp(i\hbar^{-1}\Delta E \delta t) \rangle = e^{-t / tD} ,$$

(5)

which means that the off-diagonal term of $\rho(t)$ decays exponentially with the decoherence time

$$t_D = \frac{\hbar^2}{\tau} \frac{1}{(\Delta E)^2} .$$

(6)

It is easy to see that all off-diagonal elements of a generic initial density matrix would decay exponentially. The compact form of the evolution equation contains a typical double-commutator term in addition to the standard commutator on the r.h.s. of the von Neumann equation:

$$\frac{d\rho}{dt} = -i\hbar^{-1}[H, \rho] - \frac{1}{2} \tau \hbar^{-2}[H, [H, \rho]] .$$

(7)

The direct proof of this master equation is simple. The reader is referred to the proof of the more general case [12].

I anticipate that the above master equation will be obtained from slightly different concepts. In Sec III the time uncertainty $\delta t$ follows the Poisson statistics and the Eq.(3) is obtained in the proper time-coarse-grained limit. In Sec IV the Eq.(3) is exactly derived from the uncertainties of the Planck-constant. The corresponding mathematics is trivial. Gaussian randomness $\delta t$ can mathematically be delegated to the randomness $\delta \hbar^{-1}$ since in the solutions of the Schrödinger—von-Neumann equation the Planck-constant and the time appear always in the product form $\hbar^{-1} t$. For the physics of the above two versions, see Secs III and IV.

B. Local time uncertainty and decoherence

It is straightforward to consider a local generalization of total-energy decoherence. We drop the concept of global uncertainty $\delta t$ of global time $t$ in favor of local uncertainties $\delta t_r$ of the local time $t_r$:

$$t_r \rightarrow t + \delta t_r ,$$

(8)

where $r$ labels spatial cells. Let, by assumption, the $\delta t_r$ be Gaussian random variables of zero mean and of spatial correlation proportional to the time $t$ itself:

$$M[\delta t_r \delta t'_{r'}] = \tau_{rr'} t ,$$

(9)

where $\tau$ is a certain Galileo invariant spatial correlation function. Let us write the total Hamiltonian as the sum $H = \sum_r H_r$ of local ones. The solution of the von Neumann equation takes this form:

$$\rho(t) = \rho(0) - i\hbar^{-1} \sum_r [H_r t_r, \rho(0)] -$$

$$- \frac{1}{2} \hbar^{-2} \sum_{r,r'} [H_r t_r, [H_{r'} t_{r'}, \rho(0)]] ,$$

(10)

plus higher order terms in $t$. Let us take the stochastic mean of the r.h.s., using $M[H_r] = t$ and $M[t_r t_r] = \tau_{rr} t + t^2$. This leads to the following master equation at $t \rightarrow 0$:

$$\frac{d\rho}{dt} = -i\hbar^{-1}[H, \rho] - \frac{1}{2} \hbar^{-2} \sum_{r,r'} \tau_{rr'} [H_r, [H_{r'}, \rho]] .$$

(11)

Since the matrix $\tau$ is non-negative the above class of master equations will, as expected, decohere the superpositions of local-energy eigenstates.

III. MILBURN: DISCRETE TIME UNCERTAINTY

Milburn assumes discrete global time which is of the form $n \tau t_l$. The integer $n$ is random with Poisson distribution of mean value

$$M[n] = t / \tau t_l .$$

(12)
TABLE I: Decoherence times for the Milburn master equation.

| Energy Superpositions | Decoherence Time |
|-----------------------|------------------|
| $\Delta E = 1eV$ (atomic superpositions) | $t_D \sim 10^{18}s$ (irrelevant in atomic physics) |
| $\Delta E = 1GeV$ (high energy superpositions) | $t_D \sim 10^{-5}s$ (would be irrelevant for nuclear forces) |
| $\Delta E = 1J$ (macroscopic superpositions) | $t_D \sim 10^{-25}s$ (excludes superposition of macro-energies) |

Hence time, too, becomes intrinsically uncertain while $t$ stands for the respective mean value of the random time. Milburn assumes, furthermore, that the random structure of time is not accessible to us and we can only observe the physics averaged for the random fluctuations of time.

It is straightforward to write down the master equation governing the evolution of the state $\rho$. First, we write down the change of the state in a single step of the discrete time:

$$
\rho \rightarrow \exp(-i\hbar^{-1}H\tau_{Pl})\rho \exp(i\hbar^{-1}H\tau_{Pl}) .
$$

Consider an infinitesimal interval $dt$ of mean time. During it, the above step occurs with the infinitesimal probability $dt/\tau_{Pl}$, otherwise the state remains unchanged. Taking the averaged change of $\rho$ during $dt$, we obtain the Milburn master equation:

$$
\frac{d\rho}{dt} = \frac{1}{\tau_{Pl}}[\exp(-i\hbar^{-1}H\tau_{Pl})\rho \exp(i\hbar^{-1}H\tau_{Pl}) - \rho] .
$$

Let us expand the r.h.s. up to the first order in the Planck-time:

$$
\frac{d\rho}{dt} = -i\hbar^{-1}[H, \rho] - \frac{1}{2}\tau_{Pl}\hbar^{-2}[H, [H, \rho]] .
$$

The expansion is valid at the condition $\Delta E\tau_{Pl} \ll h$. Recall that the above equation is identical with Eq. (5) at the choice $\tau = \tau_{Pl}$. Its basic feature is that the off-diagonal elements of $\rho$ in energy representation will decay at the characteristic decoherence time (7):

$$
t_D = \frac{\hbar^2}{\tau_{Pl}(\Delta E)^2} .
$$

This scale suggests plausible physics, at least at a quick glance. The intrinsic time-uncertainty does practically not decohere atomic superpositions, while large energy superpositions would decay at extreme short times (Tab. I).

IV. ADLER: EMERGENT QUANTUM MECHANICS

In Adler’s theory, the deepest level of dynamics is classical. The generalized coordinates are complex $N \times N$ hermitian matrices $\{q_r\}$. Their labels $r$ can be taken as, e.g., labels of spatial cells. The dynamics is defined by the Lagrangian:

$$
L[\{q_r\}, \{\dot{q}_r\}] = \text{Tr}L[\{q_r\}, \{\dot{q}_r\}] .
$$

It is also called trace Lagrangian, generating trace dynamics for $q_r$. Following the standard method, Adler introduces the canonical momenta:

$$
p_r = \frac{\partial L}{\partial q_r} ,
$$

and the Hamilton function:

$$
H = \text{Tr} \sum_r p_r \dot{q}_r - L .
$$

If the Lagrange function $L$ is constructed from the generalized coordinates $q_r$, from the velocities $\dot{q}_r$, from complex number coefficients, and we exclude matrix coefficients then we can prove that the following matrix is a conserved dynamic quantity [21]:

$$
\sum_r [q_r, p_r] = \bar{C} = \text{const}.
$$

The proof is straightforward. We can write:

$$
\frac{d\bar{C}}{dt} = \frac{d}{dt} \sum_r \left[ q_r, \frac{\partial L}{\partial \dot{q}_r} \right] = \sum_r \left( \left[ q_r, \frac{\partial L}{\partial q_r} \right] + \left[ \dot{q}_r, \frac{\partial L}{\partial \dot{q}_r} \right] \right) ,
$$

where we applied the Euler-Lagrange equation. The r.h.s. vanishes. Indeed, from the unitary invariance of $L$ under, say, the infinitesimal variation $\delta q_r = i[\Lambda, q_r]$ and $\delta \dot{q}_r = i[\Lambda, \dot{q}_r]$ where $\Lambda$ is an arbitrary hermitian matrix, we have:

$$
0 = \delta L = i\text{Tr} \sum_r \left( [\Lambda, q_r] \frac{\partial L}{\partial q_r} + [\Lambda, \dot{q}_r] \frac{\partial L}{\partial \dot{q}_r} \right) .
$$

After cyclic permutations under the trace operation, we recognize the r.h.s. of Eq. (22) which must vanish because of the arbitrariness of the hermitian matrix $\Lambda$.

The conservation rule $d\bar{C}/dt = 0$ is classical but it inspires something which looks quantum mechanical. If we were able to prove that each term $[q_r, p_r]$ of the l.h.s. of Eq. (21) is constant on its own then we would choose those constants as $i\hbar$ each. Provided furthermore that the choice $[q_r, p_r] = 0$ is also possible for all $r \neq s$, we would obtain the structure of Heisenberg quantum mechanics from the underlying classical matrix dynamics. Adler was able to show that the equipartition mechanism of the classical Gibbs-statistical physics will indeed provide the desired solutions. In a suitable statistical average, an effective theory emerges with the approximate commutation relations:

$$
[q_r^{\text{eff}}, p_s^{\text{eff}}] = \delta_{rs} \times \text{const} .
$$
One sets \( \text{const} = i\hbar \). The classical dynamics of the effective variables turns out to be the emergent unitary dynamics:

\[
\dot{q}_r = i\hbar^{-1}[H_{\text{eff}}, q_r], \quad \dot{p}_r = i\hbar^{-1}[H_{\text{eff}}, p_r].
\]

(25)

Hence, one has derived an emergent quantum-canonical structure and unitary dynamics. Adler exploits that this structure is statistically blurred. At a closer look, the emergent quantum mechanics contains some irreversibility. It will be easy to see the resulting master equation in Schrödinger representation. We start from the effective von Neumann equation \( \dot{\rho} = -i\hbar^{-1}[H_{\text{eff}}, \rho] \) and we observe that \( \hbar \) is the statistical mean of a fluctuating parameter. Let us reintroduce the fluctuations of \( \hbar \):

\[
\hbar^{-1} \rightarrow \hbar^{-1} + \delta\hbar^{-1},
\]

(26)

and let us approximate them by a certain white-noise satisfying

\[
\mathbf{M}[\delta\hbar^{-1}] = \hbar^{-2}\tau/t,
\]

(27)

where the precise meaning of \( \delta\hbar^{-1} \) is the fluctuation of \( \hbar^{-1} \)'s average over the period \( t \). Let us insert Eq.\ref{eq:26} into the von Neumann equation and let us average over \( \delta\hbar^{-1} \). The resulting master equation reads:

\[
\frac{d\rho}{dt} = -i\hbar^{-1}[H_{\text{eff}}, \rho] - \frac{1}{2}\tau\hbar^{-2}\{H_{\text{eff}}, [H_{\text{eff}}, \rho]\}.
\]

(28)

This is again the master equation of energy decoherence.

In the light of numerous experimental evidences, Adler gives a detailed analysis of the possible parametrization, including the natural choice \( \tau = \tau_{\text{Pl}} \). To date, this is perhaps the most complete available discussion of the observable scales of energy decoherence.

On the top of the exact Heisenberg structure\cite{24, 25}, the trace dynamics is more likely to superpose local fluctuations than global ones. Therefore global fluctuations \( \delta\hbar^{-1} \) are replaced by correlated local fluctuations \( \delta\hbar^{-1} \). The corresponding master equation will be of the form\cite{12} with the correlation matrix yet to be specified from the equilibrium trace dynamics.

\[\text{FIG. 2: The superposition of two different mass distributions (lumps), corresponding to separate wave packets } \varphi_1 \text{ and } \varphi_2.\]

(Fig.2) If the mass \( M \) is large enough, the two wave packets represent two very different mass distributions. Penrose postulates the following decay time \( t_D \) for the balanced superposition of two lumps:

\[
t_D = \hbar/\Delta E_{\text{grav}},
\]

(29)

where \( E_{\text{grav}} \) is the energy we must, hypothetically, supply to the system in order to separate the two lumps against gravitational forces:

\[
E_{\text{grav}} = |U_{11} + U_{22} - U_{12}|.
\]

(30)

The quantity \( E_{\text{grav}} \) is the Newton self-energies \( U_{11} + U_{22} \) of the two lumps minus their interaction energy \( U_{12} \).

This is the Penrose proposal. As far as I know, there has been no microscopic definition of the mass distributions of the lumps which enter the calculation of the Newtonian energies. Penrose assumes the macroscopic density for the lumps and does not resolve it for atomic scales. This way one can calculate the decoherence time for various situations. Since the gravitational self- or mutual energies of atomic systems are very small, the calculated \( t_D \)'s will be extremely long. The atomic superpositions will never decay in the Penrose theory. Massive superpositions, on the other hand, would never be formed because they would decay immediately. If, for example, one considers a rigid ball of density \( \sim 1 \text{ g/cm}^3 \) then a plausible critical size \( R_{\text{crit}} \sim 10^{-5}\text{cm} \) follows, to separate microscopic from macroscopic scales. Its vague interpretation is the following\cite{3}. Let us prepare the ball of radius \( R \) in a wave packet as narrow as \( \Delta r \sim R \). Then we compare the order of dynamical time scale of the wave packet widening with the order of decoherence time\cite{29}. We shall see that for small balls \( R \ll R_{\text{crit}} \) the unitary dynamics dominates while for large balls \( R \gg R_{\text{crit}} \) decoherence is quicker and wins over the unitary dynamics.

Penrose also emphasizes the difference between the unitary evolution and the decay (reduction) of superpositions, denoted by \( \mathbf{U} \) and \( \mathbf{R} \) resp., in his works. While the contrary features of \( \mathbf{U} \) and \( \mathbf{R} \) have been extensively discussed, the details of evolution during reduction \( \mathbf{R} \) have remained unspecified. Regarding the generic form of state evolution, Penrose writes down the formal sequence \( \mathbf{U}, \mathbf{R}, \mathbf{U}, \mathbf{R}, \ldots \) while he does not construct a dif-
eral evolution equation – master equation – incorporating both $U$ and $R$.

**VI. DIÓSI: UNCERTAINTY OF LOCAL TIME**

In terms of local time uncertainties \( \Phi \), this theory introduces the following universal correlation:

$$\tau_{rr'} = \text{const} \times \frac{Gh}{|r - r'| c^{-4}} , \quad (31)$$

where $G$ is the Newton constant and $c$ is the velocity of light. Let me explain the underlying arguments. According to the theory of general relativity, the uncertainties of local time can be represented by the fluctuations of the $g_{00}$ component of the metric tensor. If the average space-time is flat, which we assume for simplicity, then $M[g_{00}] = 1$ and, in Newtonian limit, $\delta g_{00} \approx -2c^{-2}\Phi$ where $\Phi$ is the Newton potential. The uncertainty of local time becomes directly related to the uncertain Newton potential $\Phi$:

$$\delta \tau_r \equiv \delta \int_0^t dt' g_{00}^{1/2}(r, t') \approx -c^{-2} \int_0^t dt' \Phi(r, t') . \quad (32)$$

If we knew the correlation of local uncertainties of the Newtonian gravity, we could calculate the fluctuations of local time uncertainties. According to heuristic calculations \[22\], the local gravitational acceleration $g = -\nabla \Phi$ has an inherent uncertainty, totally uncorrelated in space and time:

$$M[g(r, t)g(r', t')] = \text{const} \times Gh \delta(r - r') \delta(t - t') . \quad (33)$$

This implies the following correlation function for the Newton potential:

$$M[\Phi(r, t)\Phi(r', t')] = \text{const} \times \frac{Gh}{|r - r'|} \delta(t - t') . \quad (34)$$

Inserting Eq. \(32\) into Eq. \(31\) and using Eq. \(31\), we arrive at the correlation \(31\) of local time-uncertainties. Let us emphasize that the relativistic time-correlation function \(31\) is equivalent with the non-relativistic gravity-correlation \(31\). As we shall see, the speed of light $c$ cancels from the quantum master equation.

Now we can derive the master equation valid on the averaged space-time. We start from the general equation \[12\] with the local-time correlation \[31\]. This latter is proportional to $c^3$ which makes it extremely small. In the total energy, it is only the Einstein energy which appreciates the time-fluctuations. We write its local decomposition as $c^2 \sum_r f(r)$ where $f(r)$ is the operator of local mass density. Then we identify $H_r$ in the general master equation \[12\] by $H_r = c^2 \sum_r f(r)$, yielding:

$$\frac{d\rho}{dt} = -i\hbar^{-1}[H_r, \rho]$$

$$- \frac{G}{2} \hbar^{-1} f(r) \frac{d\rho}{dt} \int \frac{d^3r'}{|r - r'|}[f(r), [f(r'), \rho]] . \quad (35)$$

This is the master equation we were looking for. [We replaced $\sum_r$ by $\int d^3r$, and ignored the numeric factor on the r.h.s. of Eq. \(34\).] Observe that the $c$ has been canceled and the result is perfect nonrelativistic. This gives us the hint that we can perform an equivalent nonrelativistic proof of the above master equation, starting from the von Neumann equation $\dot{\rho} = -i\hbar^{-1}[H - \sum_r \Phi(r, t)f(r)]$, Taylor-expanding the solution upto $O(t^2)$ and calculating the stochastic mean by substituting the gravity-correlation \[31\].

I am going to show that the above master equation yields exactly the Penrose decay \[20\], \[30\]. Let us start from the balanced superposition of the two massive lumps (Fig. 2):

$$\rho = \frac{1}{2} |\varphi_1 + \varphi_2 \rangle \langle \varphi_1 + \varphi_2| . \quad (36)$$

We assume that the wave packets $\varphi_1$ and $\varphi_1$ are approximate eigenstates of the mass density operator:

$$f(r)|\varphi_n\rangle = f_n(r)|\varphi_n\rangle , \quad n = 1, 2; \quad (37)$$

where $f_1(r)$ and $f_2(r)$ are the (c-number) mass distributions of the two lumps, respectively. Using these functions on the r.h.s. of the master equation \(36\), we can write the contribution of the double-commutator term to the decay of the interference term between the two lumps into this form:

$$\frac{d}{dt} \langle \varphi_1 | \rho | \varphi_2 \rangle = -E_{\text{grav}} \hbar^{-1} \langle \varphi_1 | \rho | \varphi_2 \rangle . \quad (38)$$

The decay time is $t_D = \hbar / E_{\text{grav}}$ with

$$E_{\text{grav}} = \int \int \frac{d^3r' \delta(r - r')}{|r - r'|} [\tilde{f}_1(r) - \tilde{f}_2(r)][\tilde{f}_1(r') - \tilde{f}_2(r')] , \quad (39)$$

i.e., it is completely identical to the Penrose proposal \[20\], \[30\].

**A. Digression**

I would like to digress about the status of the model. An earliest criticism came from Ghirardi, Grassi and Rimini \[23\]. The non-relativistic mass distribution $f(r)$ is a basic ingredient of my model (as well as of Penrose’s). In case of point-like constituents of position operator $r_k$ and mass $m_k$, the operator of mass distribution would be $f(r) \equiv \sum_k m_k \delta(r - r_k)$. Newton self-energy would diverge hence my master equation would also diverge. I needed a short length cutoff which I chose to be the nuclear size. The choice was naive, optimistic — and wrong. The authors of Ref. \[23\] pointed out that the model can not be valid below the scale $\sim 10^{-5}$cm and they suggested a higher cutoff. The short-length cutoff $\sim 10^{-5}$cm can most easily be implemented by the corresponding spatial coarse-graining of the mass density.
Apart from this modification, the whole mathematics and physics of the model remains the same; the original master equation needs no reformulation at all.

The Penrose proposal avoids the cutoff-difficulty only because it uses the coarse-grained macroscopic mass density from the beginning, without discussing its microscopic definition. What happens to the Penrose model if we extend it for the microscopically structured mass distributions of the two lumps, respectively? It faces the same problem that my model did. To calculate Newtonian self-energies, one needs a short-length cutoff. Where should we get it from? Certainly it may be the phenomenological cutoff 10^{-5}cm imposed by Ghiurari, Grassi and Rimini [24] on my model. Ref. [7] shows Penrose's awareness of the difficulty as well as his preliminary ideas to circumvent it. I am afraid that the proposed solution can still not stand on its own without defining what happens to the Newtonian interaction at short distances.

May I clarify an important and obvious misunderstanding in Ref. [6], also in some subsequent works like, e.g., in Ref. [24]. The claim is that my model differs from Penrose's because I define the decoherence time through the inverse of the Newton interaction potential:

\[ t_D = \frac{\hbar}{|U_{12}|} \]  

(40)

This claim is obviously incorrect. A possible source of the misunderstanding was discovered by the late Jeeva Anandan in 1998 [25]: I had displayed a trivially mistaken version [Eq.(12) in Ref. [8]] of Eq. (39), contrary to the otherwise correct master equation. Yet in the same work I had published the correct equation [Eq.(14)] as well. My longer paper [9] had published correct equations (4.16-17) in coincidence with Penrose's [26, 30], respectively.

The concrete part of the Penrose model, meaning his decay-time equation [26, 30] and its applications, represents a special case of the concrete part of my model, i.e., my master equation [8, 9] and its applications. The Penrose model proposes exactly the same decay times for the balanced superpositions of two lumps as my model does. This coincidence extends for more general superpositions as well [26]. The Penrose model, however, has no dynamical equation. From the above exact coincidences I have got the following impression. The potential dynamics, underlying the Penrose decay of massive superpositions, can not differ from my master equation or, at least, it must build on this master equation.

VII. CONCLUDING REMARKS

The purpose of this ‘review’ was limited. It could not capture all aspects of the chosen four models. Discussion of interpretational details was restricted to the minimum. The virtue of my work is that I presented the four models from a common perspective which is intrinsic time-uncertainty. To sketch the four models on the same canvas might cause conflicts with the interpretations of the other three authors themselves. To reduce the risk of misunderstanding, I tried to concentrate on the concrete parts (equations) of the four models. I suggest the interested reader to complete his/her knowledge from the original references.

Let me close this work by another very incomplete list of experimental proposals. Their diversity is spectacular. These proposals mention or suggest that the tiny decoherence effects, like those predicted by the above discussed theories, might (or should) be detected in the spatial motion of a test body on a satellite [3], in proton decay [27], by atom interferometer [17, 27], in the motion of a nano-mirror [28, 31] or other nano-object coupled to quantum optical devices [32], and in very large interferometers [33]. There are quite recent works [34, 35] particularly concentrating on the experimental aspects of energy decoherence, including local energy decoherence [36, 37, 38]. Without consistent (maybe highly phenomenological) models, the attractive new experimental options would not be used to target such basic quantum issue as universal decoherence.

VIII. ACKNOWLEDGMENTS

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