ON THE STRUCTURE OF THE ESSENTIAL SPECTRUM
OF ELLIPTIC OPERATORS ON METRIC SPACES

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ABSTRACT. We give a description of the essential spectrum of a large class of operators on metric measure
spaces in terms of their localizations at infinity. These operators are analogues of the elliptic operators on
Euclidean spaces and our main result concerns the ideal structure of the $C^*$-algebra generated by them.

1. Introduction

1.1. The question we consider in this paper is whether the essential spectrum of an operator can be de-
scribed in terms of its “localizations at infinity”. Later on we give a precise mathematical meaning to this
notion along the following lines: we first define a $C^*$-algebra $\mathcal{E}$ which should be thought as the minimal
$C^*$-algebra which contains the resolvents of the operators we want to study, then we point out a remarkable
class of geometrically defined ideals $\mathcal{E}_{(\kappa)}$ in $\mathcal{E}$, where $\kappa$ are certain ultrafilters on $X$, and finally we define
the localization of an operator in $\mathcal{E}$ at $\kappa$ as its image in the quotient $C^*$-algebra $\mathcal{E}_\kappa = \mathcal{E}/\mathcal{E}_{(\kappa)}$. For the
moment we shall stick to the naive interpretation of localizations at infinity of an operator $H$ as “asymptotic
operators” obtained as limits of translates of $H$ to infinity, but we stress that translations have no meaning
for the class of spaces of interest here and very soon we shall abandon this point of view.

We begin with the case $X = \mathbb{R}^d$. Note that we are interested only in operators $H$ which are self-adjoint
(Hamiltonians of quantum systems). Denote $U_a$ the unitary operator of translation by $a \in X$ in $L^2(X)$,
so that $(U_a f)(x) = f(x + a)$. We say that $H_\kappa$ is an asymptotic Hamiltonian of $H$ if there is a sequence
$a_n \in X$ with $|a_n| \to \infty$ such that $U_{a_n} H U_{a_n}^*$ converges in strong resolvent sense to $H_\kappa$. Then we have
$\text{Sp}_{\text{ess}}(H_\kappa) = \bigcup_\kappa \text{Sp}(H_\kappa)$ for very large classes of Schrödinger operators. We refer to the paper [HM]
of Helffer and Mohamed as one of the first dealing with this question in a general setting and to that of Last
and Simon [LaS] for the most recent results obtained by similar techniques (geometric methods involving
partitions of unity) and for a complete list of references. We mention that the importance of the asymptotic
operators has been emphasized in a series of papers in the nineties by Rabinovich, Roch, and Silbermann and
summarized in their book [RRS] (see also [CL]; we thank B. Simon for this reference). They are especially
concerned with the case $X = \mathbb{Z}^d$ and treat differential operators on $L^p(\mathbb{R}^d)$ with the help of a discretization
method.

Results of this nature have also been obtained in [GI1, GI3] by a quite different method where the description
of localizations at infinity in terms of asymptotic operators is not so natural and rather looks like an accident.
To explain this point, we recall one result. Let $X$ be an abelian locally compact non-compact group, define
$U_a$ as above, and for any character $\kappa$ of $X$ let $V_k$ be the operator of multiplication by $k$ on $L^2(X)$. Let $\mathcal{E} \equiv
\mathcal{E}(X)$ be the set of bounded operators $T$ on $L^2(X)$ such that $\|V_k^{-1} T V_k - T\| \to 0$ and $\|T - \text{ess} T\| \to 0$
when $k \to 1$ and $a \to 0$. A self-adjoint operator $H$ satisfying $(H - i)^{-1} \in \mathcal{E}$ is said to be affiliated to $\mathcal{E}$; it
is easy to see that this class of operators is very large. Let $\delta = \delta(X)$ be the set of ultrafilters on $X$ finer than
the Fréchet filter. If $H$ is affiliated to $\mathcal{E}$ then for each $\kappa \in \delta$ the limit $\lim_{a \to \kappa} U_a H U_a^* = H_\kappa$ exists in the
strong resolvent sense and we have $\text{Sp}_{\text{ess}}(H) = \bigcup_{\kappa \in \delta} \text{Sp}(H_\kappa)$. Thus the essential spectrum of an operator
affiliated to $\mathcal{E}$ is determined by its asymptotic operators.

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The proof goes as follows. The space $\mathcal{E}$ is in fact a $C^*$-algebra canonically associated to $X$, namely the crossed product $\mathcal{C}(X) \rtimes X$ of the algebra $\mathcal{C}(X)$ of bounded uniformly continuous functions on $X$ by the natural action of $X$. Moreover, the space $\mathcal{K} \equiv \mathcal{K}(X)$ of compact operators on $L^2(X)$ is an ideal of $\mathcal{E}$. Note that by ideal in a $C^*$-algebra we mean "closed bilateral ideal" and we call morphism a $*$-homomorphism between two $*$-algebras. It is easy to see that for each $x \in \delta$ and each $T \in \mathcal{E}$ the strong limit $\tau_x(T) := \lim_{n \to \infty} U_n T U_n^*$ exists and that the so defined $\tau_x$ is an endomorphism of $\mathcal{E}$ so its kernel $\ker \tau_x$ is an ideal of $\mathcal{E}$ which clearly contains $\mathcal{K}$. The main fact is $\tau_{x \in \delta} \ker \tau_x = \mathcal{K}$ and this is the only nontrivial part of the proof. From here we immediately deduce the preceding formula for the essential spectrum of the operators affiliated to $\mathcal{E}$. Indeed, it suffices to recall that the essential spectrum of an operator in a $C^*$-algebra like $\mathcal{E}$ which contains $\mathcal{K}$ is equal to the spectrum of the image of the operator in the quotient algebra $\mathcal{E} / \mathcal{K}$.

We shall call $\mathcal{E}$ the elliptic $C^*$-algebra of the group $X$. It is probably not clear that this has something to do with the elliptic operators, but the following fact justifies the terminology. The $C^*$-algebra generated by a set of self-adjoint operators on a given Hilbert space is by definition the smallest $C^*$-algebra which contains the resolvents of these operators. Let $X = \mathbb{R}^d$ and let $\hbar$ be a real elliptic polynomial of order $m$ on $X$. Then $\mathcal{E}$ is the $C^*$-algebra generated by the self-adjoint operators of the form $\hbar(|\nabla|) + S$ where $S$ runs over the set of symmetric differential operators of order $< m$ whose coefficients are $C^\infty$ functions which are bounded together with all their derivatives. We stress that although $\mathcal{E}(X)$ is generated by a small class of elliptic differential operators, the class of self-adjoint operators affiliated to it is quite large and contains many singular perturbations of the usual elliptic operators. This is obvious from the description of $\mathcal{E}$ we gave before and many explicit examples may be found in [DG1, GI3].

1.2. Our purpose is to extend the framework and the results stated above to the case when $X$ is a metric space without any group structure or group action and for which the notion of differential operator is not a priori defined. To each measure metric space $X = (X, d, \mu)$ satisfying some quite general conditions we associate a $C^*$-algebra $\mathcal{E} \equiv \mathcal{E}(X)$ of operators on $L^2 := L^2(X, \mu)$ and to each $x \in \delta(X)$ we associate an ideal $\mathcal{E}(x)$ of $\mathcal{E}$ such that $\cap_{x \in \delta} \mathcal{E}(x)$ is the space $\mathcal{K}$ of compact operators on $L^2$ if the metric space $X$ has a certain amenability property, namely the Property A of Guoliang Yu [Yu]. The $\mathcal{E}(x)$ are analogues of the $\ker \tau_x$ and the image of an operator $T \in \mathcal{E}$ in the quotient algebra $\mathcal{E} / \mathcal{E}(x)$ is the analogue of $\tau_x(T)$. The ideal $\mathcal{E}(x)$ is defined in terms of the behavior of the operators at a region at infinity which contains $x$.

Our interest in this question was roused by a recent paper of E. B. Davies [Dav] in which a $C^*$-algebra $\mathcal{C}(X)$, called standard algebra, is associated to each metric measure space $X$ as above. Davies points out a class of ideals of $\mathcal{C}$ and describes their role in understanding the essential spectrum of the operators affiliated to $\mathcal{C}$. This algebra is much larger than $\mathcal{E}$ if $X$ is not discrete. If $X$ is an abelian group as above, then $\mathcal{C}$ is the set of bounded operators $T$ on $L^2$ such that $||V^n T V^k - T|| \to 0$ when $k \to 1$. It is clearly impossible to give a complete description of the essential spectrum of such operators only in terms of their behavior at infinity in the configuration space $X$ (consider for example the case $X = \mathbb{R}$). A more precise description of $\mathcal{C}$ and of its relation with $\mathcal{E}$ may be found in Section 7.

In Section 6 we show that if $X$ is a unimodular amenable group then we have $\mathcal{E}(X) = \mathcal{C}(X) \rtimes X$ as in the abelian case. Thus we may recover as a corollary of our main result (Theorem 2.5) the results in [GI1, GI3] for locally compact abelian groups and those of Roe [Ro2] in the case of finitely generated discrete (non-abelian) groups (see also [RRR]). Amenability is not really necessary: in fact, the natural objects here are the reduced crossed products and then Yu’s Property A is sufficient.

1.3. From a more general point of view, the main point of the approach sketched above is to shift attention from one operator to an algebra of operators. Instead of studying the essential spectrum (or other qualitative spectral properties, like the Mourre estimate) of a self-adjoint operator $H$ on a Hilbert space $\mathcal{H}$, we consider a $C^*$-algebra $\mathcal{E}$ of operators on $\mathcal{H}$ which contains $\mathcal{K} = K(\mathcal{H})$ and such that $H$ is affiliated to it and try to find an "efficient" description of the quotient $C^*$-algebra $\mathcal{E} / \mathcal{K}$. For this, we look for a family of ideals $\mathcal{J}(x)$ of $\mathcal{E}$ such that $\cap_{x \in \delta} \mathcal{J}(x) = \mathcal{K}$ because then we have a natural embedding

\[
\mathcal{E} / \mathcal{K} \hookrightarrow \prod_{x \in \delta} \mathcal{E} / \mathcal{J}(x)
\]
and, in our concrete situation, we think of this as an efficient representation of \( \mathcal{E} / J \) if the ideals \( J_\kappa \) are in some sense maximal and have a geometrically simple interpretation. This is in an important point and we shall get back to it later on. For the moment note that any representation like (1.1) has useful consequences in the spectral theory of the operators \( T \in \mathcal{E} \), for example if \( T \) is normal and \( T_\kappa \) is the projection of \( T \) in \( \mathcal{E} / J_\kappa \) then its essential spectrum is given by

\[
\text{Sp}_{\text{ess}}(T) = \bigcup_\kappa \text{Sp}(T_\kappa).
\]

Arbitrary ideals \( J \subset \mathcal{E} \) also play a role in the spectral analysis of the operators \( T \in \mathcal{E} \). For example, if we denote \( T / J \) the image of \( T \) in the quotient algebra \( \mathcal{E} / J \) then clearly \( \text{Sp}(T / J) \subset \text{Sp}(T) \) and if \( J \) contains the compacts then \( \text{Sp}(T / J) \subset \text{Sp}_{\text{ess}}(T) \). It is natural in our framework to call the quotient operator \( T / J \) localization of \( T \) at \( J \) (see Section 4.4 for the meaning of this operation in the abelian case).

Observe that \( \text{Sp}(T / J) \) becomes smaller when \( J \) increases, which allows a better understanding of parts of the spectrum of \( T \). In particular, it will become clear later on that by taking large \( J \) one can isolate the contribution to the essential spectrum of \( T \) of the localization of \( T \) to small regions at infinity.

We refer to [ABG, BG1, BG2, DG2, Geo] for a general discussion concerning the operation of localization with respect to an ideal and for applications in the spectral theory of many-body systems and quantum field theory but we shall mention here an example which is relevant also in the present context. Let \( H \) be the Hamiltonian of a system of non-relativistic particles interacting through two-body potentials and let \( V_{jk} \) be the potential linking particles \( j \) and \( k \). For each partition \( \sigma \) of the system of particles let \( H_\sigma \) be the Hamiltonian obtained by replacing by zero the \( V_{jk} \) such that \( j, k \) belong to different clusters of \( \sigma \). Then the HVZ theorem says that \( \text{Sp}_{\text{ess}}(H) = \bigcup_\sigma \text{Sp}(H_\sigma) \) where \( \sigma \) runs over the set of two-cluster partitions. In fact, this is an immediate consequence of the preceding algebraic formalism: the \( N \)-body \( C^\ast \) -algebra is easy to describe and \( H_\sigma \) is the localization of \( H \) at a certain ideal which appears very naturally in this context. The point is that we do not have to take some limit at infinity to get \( H_\sigma \), although this could be done (this would mean that we use “geometric methods”). The ideals which are involved in the representation (1.1) in this case are minimal in a precise sense. In particular, the preceding decomposition of the spectrum is very rough (you do not see the contribution of \( k \)-cluster partitions with \( k > 2 \)).

In connection with the algebraic approach sketched above, we would like to emphasize the previous work of J. Bellissard, who was one of the first to stress the advantage of considering \( C^\ast \) -algebras generated by Hamiltonians in the context of solid state physics [Be1, Be2], and that of H. O. Cordes, who studied \( C^\ast \) -algebras of pseudo-differential operators on manifolds and their quotients with respect to the ideal of compact operators [Cor] already in the seventies.

1.4. Now let’s get back to our problem. Assuming we have chosen the “correct” algebra \( \mathcal{E}(X) \), we must find the relevant ideals. In the group case, this is easy, because there is a natural class of ideals associated to translation invariant filters [GI1]. Proposition 6.6 gives a characterization of these filters which involves only the metric structure of \( X \) (in fact, only the coarse structure associated to it [Ro1]). Thus what we call coarse filters in a metric space are analogs of the invariant filters in a group. To each coarse filter \( J_\xi \) we then associate an ideal \( J_\xi \) defined in terms of the behavior of the operators at a certain region at infinity defined by \( \xi \), cf. (2.6). These are the geometric ideals which play the main role in or analysis.

Recall that the set of ultrafilters finer than the Fréchet filter is a compact subset \( \delta(X) \) of the Stone-Čech compactification \( \beta(X) \) of \( X \). Any filter \( \xi \) finer than Fréchet can be thought as a closed subset of \( \delta(X) \) by identifying it with the set \( \xi^\ast \) of ultrafilters finer than it, and then the sets \( F \in \xi \) can be thought as traces on \( X \) of neighborhoods of this closed set in \( \beta(X) \). The sets \( \xi^\ast \) with \( \xi \) coarse will be called coarse subsets of \( \delta(X) \) (they are closed). If \( X \) is a group then \( X \) acts on \( \delta(X) \), the coarse subsets are the closed invariant subsets of \( \delta(X) \), and the small invariant sets are parametrized as follows: to each \( \kappa \in \delta(X) \) we associate the smallest closed invariant set containing \( \kappa \) (i.e. the closure of the orbit which passes through it). But this can be easily expressed in group independent terms: if \( \kappa \in \delta(X) \) let \( \text{col}(\kappa) \) be the finer coarse filter included in \( \kappa \) and let \( \hat{\kappa} := \text{col}(\kappa)^\ast \) be the smallest coarse set containing \( \kappa \). Then the \( \text{col}(\kappa) \) are the large coarse filters, the \( \hat{\kappa} \) the small coarse sets, and the \( \delta(\kappa) := J_\text{col}(\kappa) \) are the large coarse ideals which should allow us to compute the essential spectrum of the operators in \( \mathcal{E} \). Heuristically speaking, \( \delta(\kappa) \) consists of the operators in \( \mathcal{E} \) which
vanish at $\tilde{\mathcal{K}}$. For example, if $X$ is discrete, so $\mathcal{E}$ contains the bounded functions $\varphi$ on $X$, we have $\varphi \in \mathcal{E}_{(\infty)}$ if and only if the continuous extension of $\varphi$ to $\beta(X)$ is zero on $\tilde{\mathcal{K}}$.

We stress that this strategy denotes a certain bias toward the role played by the behavior at infinity in $X$ (thought as physical or configuration space): we think that it has a dominant role since we hope that our choices of ideals is sufficient to describe the quotient $\mathcal{E}/\mathcal{K}$. There is no a priori reason for this to be true: there are physically natural situations in which ideals defined in terms of behavior at infinity in momentum or phase space must be taken into account [GI1]. However, it does not seem so clear to us how to define such physically meaningful objects in the present context (there is no natural phase space).

Anyway, the situation is not simple even at the level of geometrically defined ideals. Indeed, the ideals $\mathcal{E}_{(\infty)}$ are defined in terms of the behavior of the operators in $\mathcal{E}$ at $\tilde{\mathcal{K}}$, but it is not completely clear how to express the intuitive idea that an operator $T$ vanishes on $\tilde{\mathcal{K}}$. Our choice is the more restrictive one, but there is a second one which is also quite natural and leads to a distinct class of ideals $\mathcal{G}_{\kappa}$, cf. (5.27) and (5.28). One has $\mathcal{E}_{(\infty)} \subset \mathcal{G}_{\kappa}$ strictly in general but equality holds if the space $X$ has the Property A.

In general the ideals $\mathcal{G}_{\kappa}$ do not suffice to compute $\mathcal{K}$, i.e. we do not have $\bigcap_{\kappa \in \mathcal{E}} \mathcal{G}_{\kappa} = \mathcal{K}$. In fact an ideal $\mathcal{G}$ which contains the compacts appears naturally in the algebra $\mathcal{E}$, the so-called ghost ideal, and this ideal could contain a projection of infinite rank, hence be strictly larger than the compacts. The construction of such a projection is due to Higson, Laforgue and Skandalis [HLS] and is important in the context of the Baum-Connes conjecture. They consider the simplest case of discrete metric spaces with bounded geometry (the number of points in a ball of radius $r$ is bounded independently of the center of the ball) when $\mathcal{E}$ is the uniform Roe $C^*$-algebra. More information concerning this question may be found in the papers [CW1, CW2, Wa] by Chen and Wang where the ideal structure of the uniform Roe algebra [Ro1] is studied in detail. Their idea of using kernel truncations with the help of positive type functions in case $X$ has Yu’s Property A plays an important role in our proofs, as we shall see in Section 3. But before going into details on these matters we shall describe in the next section in precise terms the framework and the main results of this paper.

As explained before, a representation like (1.1) involving ideals which are as large as possible will provide the most detailed information on the structure of the essential spectrum of the observables affiliated to $\mathcal{E}$. Thus the fact that $\bigcap_{\kappa \in \mathcal{E}} \mathcal{G}_{\kappa} \neq \mathcal{K}$ shows that in general the large ideals are not sufficient to compute the essential spectrum. We leave open the question whether $\bigcap_{\kappa \in \mathcal{E}} \mathcal{G}_{(\kappa)} = \mathcal{K}$ holds even if $\bigcap_{\kappa \in \mathcal{E}} \mathcal{G}_{\kappa} \neq \mathcal{K}$.

### 2. Main results

A metric space $X = (X,d)$ is proper if each closed ball $B_d(r) = \{y \mid d(x,y) \leq r\}$ is a compact set. This implies the local compactness of the topological space $X$ but is much more because local compactness means only that the small balls are compact. In particular, if $X$ is not compact, then the metric cannot be bounded. We are interested in proper non-compact metric spaces equipped with Radon measures $\mu$ with support equal to $X$, so $\mu(B_d(r)) > 0$ for all $x \in X$ and all $r > 0$, and which satisfy (at least) the following condition

$$V(r) := \sup_{x \in X} \mu(B_d(r)) < \infty \text{ for all } r > 0. \quad (2.3)$$

We shall always assume that a metric measure space $(X,d,\mu)$ satisfies these conditions. On the other hand, for the proof of our main results we need the following supplementary condition:

$$\inf_x \mu(B_d(1/2)) > 0. \quad (2.4)$$

The choice of $1/2$ in (i) is, of course, rather arbitrary, and an assumption of the form $\inf_x \mu(B_d(r)) > 0$ for all $r > 0$ would be more natural. Each time we use (2.4) we shall mention it explicitly.

To simplify the notations we set $d\mu(x) = dx$, $L^2(X) = L^2(X,\mu)$, and $B_d = B_d(1)$. We denote $\mathcal{B}(X)$ the $C^*$-algebra of all bounded operators on $L^2(X)$ and $\mathcal{K}(X)$ the ideal of $\mathcal{B}(X)$ consisting of compact operators. For $A \subset X$ we denote $1_A$ its characteristic function and if $A$ is measurable then we use the same notation for the operator of multiplication by $1_A$ in $L^2(X)$. 

Several versions of Yu’s Property A appear in the literature (see [Ro1, Definition 11.35] and [Tu] for the discrete case), we have chosen that which was easier to state and use in our context. Later on we shall state and use a more abstract version which can easily be reformulated in terms of positive type functions on $X^2$. See page 21 here and [Ro1, Ch. 3] for the relation with amenability in the group case.

**Definition 2.1.** We say that the metric measure space $(X, d, \mu)$ has Property A if for each $\varepsilon, r > 0$ there is a Borel map $\phi : X \to L^2(X)$ with $\|\phi(x)\| = 1$, $\text{supp} \phi(x) \subset B_x(s)$ for some number $s$ independent of $x$, and such that $\|\phi(x) - \phi(y)\| < \varepsilon$ if $d(x, y) < r$.

**Definition 2.2.** We say that $X = (X, d, \mu)$ is a class A space if $(X, d)$ is a proper non-compact metric space and $\mu$ is a Borel measure on $X$ such that: (i) $\mu(B_x(r)) > 0$ and $\sup_x \mu(B_x(r)) < \infty$ for each $r > 0$, (ii) $\inf_x \mu(B_x(1/2)) > 0$, (iii) $(X, d, \mu)$ has property A.

Since $X$ is locally compact the spaces $C_c(X)$ and $C_c(X)$ of continuous functions on $X$ which tend to zero at infinity or have compact support respectively are well defined. We use the slightly unusual notation $\mathcal{C}(X)$ for the set of bounded uniformly continuous functions on $X$ equipped with the sup norm. Then $\mathcal{C}(X)$ is a $C^*$-algebra and $\mathcal{C}_c(X)$ is an ideal in it. We embed $\mathcal{C}(X) \subset \mathcal{B}(X)$ by identifying $\varphi \in \mathcal{C}$ with the operator $\varphi(Q)$ of multiplication by $\varphi$ (this is an embedding because the support of $\mu$ is equal to $X$). We shall however use the notation $\varphi(Q)$ if we think that this is necessary for the clarity of the text.

Functions $k : X^2 \to \mathbb{C}$ on the product space $X^2 = X \times X$ are also called kernels on $X$. We say that $k$ is a controlled kernel if there is a real number $r$ such that $d(x, y) > r \Rightarrow k(x, y) = 0$. With the terminology of [HPR], a kernel is controlled if it is supported by an entourage of the bounded coarse structure on $X$ coming from the metric. We denote $\mathcal{C}_{trl}(X^2)$ the set of bounded uniformly continuous controlled kernels and to each $k \in \mathcal{C}_{trl}(X^2)$ we associate an operator $Op(k)$ on $L^2(X)$ by $(Op(k)f)(x) = \int_X k(x, y)f(y)dy$. It is easy to check (see Section 3) that the set of such operators is a $\ast$-subalgebra of $\mathcal{B}(X)$. Hence

$$\mathcal{E}(X) = \mathcal{E}(X, d, \mu) = \text{norm closure of} \{Op(k) \mid k \in \mathcal{C}_{trl}(X^2)\}$$

is a $C^*$-algebra of operators on $L^2(X)$. We shall say that $\mathcal{E}(X)$ is the elliptic algebra of $X$.

**Remark 2.3.** The following alternative presentation of the framework clarifies the role of the metric. Fix a couple $X = (X, \mu)$ consisting of a locally compact non-compact topological space $X$ equipped with a Radon measure $\mu$ with support equal to $X$. This fixes the Hilbert space $L^2(X)$. Then to each proper metric compatible with the topology of $X$ and such that $\sup_x \mu(B_x(r)) < \infty$ for all $r$ we associate a $C^*$-algebra $\mathcal{E}(X, d)$ of operators on $L^2(X)$ which contains $\mathcal{H}(X)$. It is interesting to note that $\mathcal{E}(X, d)$ depends only on the coarse equivalence class of the metric. Recall that two metrics $d, d'$ are coarse equivalent if there are positive increasing functions $u, v$ such that $d \leq u(d')$ and $d' \leq v(d)$. This can also be expressed in terms of coarse structures on $X$ [STY, page 810].

There is an obvious $\mathcal{C}(X)$-bimodule structure on $\mathcal{E}(X)$ and we have

$$\mathcal{H}(X) = \mathcal{C}_c(X)\mathcal{E}(X) = \mathcal{E}(X)\mathcal{C}_c(X) \subset \mathcal{E}(X).$$

As explained in the introduction we are interested in a “geometrically meaningful” representation of the quotient $C^*$-algebra $\mathcal{E}(X)/\mathcal{H}(X)$. For this we introduce the class of “coarse ideals” described below.

If $F \subset X$ and $r > 0$ is real we denote $F(r)$ the set of points $x$ which belong to the interior of $F$ and are at distance larger than $r$ from the boundary, more precisely $\inf_{y \notin F} d(x, y) > r$. A filter $\xi$ of subsets of $X$ will be called coarse if $F \in \xi \Rightarrow F(r) \in \xi$ for all $r$. Note that the set of complements of a coarse filter is a coarse ideal of subsets of $X$ in the sense of [HPR]. The Fréchet filter, i.e. the set of sets with relatively compact complement, is clearly coarse, we denote it $\infty$. There is a trivial coarse filter, namely $\xi = \{X\}$, which is of no interest for us. All the other coarse filters are finer than $\infty$.

To each coarse filter $\xi$ on $X$ we associate an ideal of $\mathcal{E}(X)$ by defining

$$\mathcal{J}_\xi(X) = \{T \in \mathcal{E}(X) \mid \inf_{F \in \xi} \|1_F T\| = 0\} = \{T \in \mathcal{E}(X) \mid \inf_{F \in \xi} \|T 1_F\| = 0\}$$

(2.6)
where the inf is taken only over measurable $F \in \mathcal{I}$. We shall see that the set $\mathcal{I}_\xi(X)$ of $\varphi \in \mathcal{C}(X)$ such that $
exists \xi \varphi = 0$ is an ideal of $\mathcal{C}(X)$ and $\mathcal{J}_\xi(X) = \mathcal{I}_\xi(X)\mathcal{G}(X) = \mathcal{G}(X)\mathcal{I}_\xi(X)$.

Let $\beta(X)$ be the set of all ultrafilters of $X$ (this is the Stone-Čech compactification of the discrete space $X$) and let $\delta(X)$ be the set of ultrafilters finer than the Fréchet filter. For each $\kappa \in \beta(X)$ we denote $\text{co}(\kappa)$ the largest coarse filter contained in $\kappa$ and we set $\mathcal{C}_\kappa(X) = \mathcal{I}_{\text{co}(\kappa)}(X)$ and $\mathcal{G}_\kappa(X) = \mathcal{J}_{\text{co}(\kappa)}(X)$. These are ideals in $\mathcal{C}(X)$ and $\mathcal{G}(X)$ respectively and we have

$$\mathcal{G}_\kappa(X) = \mathcal{C}_\kappa(X)\mathcal{G}(X) = \mathcal{G}(X)\mathcal{C}_\kappa(X). \tag{2.7}$$

If $X$ is of class $A$ then from Theorem 5.9 we get a second description of these ideals.

**Proposition 2.4.** If $X$ is a space of class $A$ then for any $\kappa \in \delta(X)$ we have

$$\mathcal{G}_\kappa(X) = \{T \in \mathcal{G}(X) \mid \lim_{x \to \kappa} \|1_{B_x(r)}T\| = 0 \forall r > 0\}. \tag{2.8}$$

Then to each ultrafilter $\kappa \in \delta(X)$ we associate the quotient $C^*$-algebra

$$\mathcal{G}_\kappa(X) = \mathcal{G}(X)/\mathcal{G}_\kappa(X) \tag{2.9}$$

and call it *localization of* $\mathcal{G}(X)$ *at* $\kappa$. We denote $\kappa.T$ the image of $T \in \mathcal{G}(X)$ through the canonical morphism $\mathcal{G}(X) \to \mathcal{G}_\kappa(X)$ and we say that $\kappa.T$ is the *localization of* $T$ *at* $\kappa$. Our main result is:

**Theorem 2.5.** If $X$ is a class $A$ space then $\bigcap_{\kappa \in \delta(X)} \mathcal{G}_\kappa(X) = \mathcal{H}(X)$, hence

$$\mathcal{G}(X)/\mathcal{H}(X) \hookrightarrow \prod_{\kappa \in \delta(X)} \mathcal{G}_\kappa. \tag{2.10}$$

In particular, the essential spectrum of any normal operator $T \in \mathcal{G}(X)$ is equal to the closure of the union of the spectra of its localizations at infinity:

$$\text{Sp}_{\text{ess}}(T) = \bigcup_{\kappa \in \delta(X)} \text{Sp}(\kappa.T). \tag{2.11}$$

In view of applications to self-adjoint operators affiliated to $\mathcal{G}(X)$, we recall [ABG] that an *observable affiliated to* a $C^*$-algebra $\mathcal{A}$ is a morphism $H : C_0(\mathbb{R}) \to \mathcal{A}$. We set $\varphi(H) := H(\varphi)$. If $\mathcal{P} : \mathcal{A} \to \mathcal{B}$ is a morphism between two $C^*$-algebras then $\varphi \mapsto \mathcal{P}(\varphi(H))$ is an observable affiliated to $\mathcal{B}$ denoted $\mathcal{P}(H)$. So $\mathcal{P}(\varphi(H)) = \varphi(\mathcal{P}(H))$. If $\mathcal{A}$ and $\mathcal{B}$ are realized on Hilbert spaces $\mathcal{H}_a, \mathcal{H}_b$, then any self-adjoint operator $H$ on $\mathcal{H}_a$ affiliated to $\mathcal{A}$ defines an observable affiliated to $\mathcal{A}$, but the observable $\mathcal{P}(H)$ is not necessarily associated to a self-adjoint operator on $\mathcal{H}_b$ because the natural operator associated to it could be non-densely defined (in our context, it often has domain equal to $\{0\}$). The spectrum and essential spectrum of an observable are defined in an obvious way [ABG].

Now clearly, if $H$ is an observable affiliated to $\mathcal{G}(X)$ then $\kappa.H$ defined by $\varphi(\kappa.H) = \varphi(H)$ is an observable affiliated to $\mathcal{G}_\kappa(X)$. This is the *localization of* $H$ *at* $\kappa$ and we have

$$\text{Sp}_{\text{ess}}(H) = \bigcup_{\kappa \in \delta(X)} \text{Sp}(\kappa.H). \tag{2.12}$$

We shall not give in this paper affiliation criteria specific to the algebra $\mathcal{G}(X)$ but the results of Section 6 and the examples form [GI3] should convince the reader that the class of operators affiliated to $\mathcal{G}(X)$ is very large. On the other hand, if $H$ is a positive self-adjoint operator such that $e^{-H} \in \mathcal{G}(X)$ then $H$ is affiliated to $\mathcal{G}(X)$. Or this condition is certainly satisfied by the Laplace operator associated to a large class of Riemannian manifolds due to known estimates on the heat kernel of the manifold. We thank Thierry Coulhon for an e-mail exchange on this question.

In connection with Proposition 2.4 we mention that in Section 5 we consider a second class of ideals $\mathcal{G}_\kappa(X)$ in $\mathcal{G}(X)$ which are similar to the $\mathcal{G}_\kappa(X)$. More precisely, let $\mathcal{G}_\kappa(X)$ be defined as the right hand side of (2.8) for any $\kappa \in \delta(X)$. Then $\mathcal{G}_\kappa(X)$ is an ideal of $\mathcal{G}(X)$ and $\mathcal{G}_\kappa(X) \subset \mathcal{G}_\kappa(X)$ where equality holds if $X$ is a space of class $A$ but the inclusion is strict in general. We say that $\mathcal{G}_\kappa$ is the *ghost envelope* of $\mathcal{G}_\kappa$. Thus for each ultrafilter $\kappa \in \delta(X)$ we may have two distinct contributions to the essential spectrum of $H$ associated to $\kappa$: first the spectrum of the localization $\kappa.H = H/\mathcal{G}_\kappa(X)$ at $\kappa$ and second the spectrum of $H/\mathcal{G}_\kappa(X)$, which is a subset of the first one.
In particular, besides the smallest ideal $\mathcal{I}(X)$ of $\mathcal{E}(X)$ there is a second “small” ideal which appears quite naturally in the theory. This is the ghost ideal defined by
\[
\mathcal{G}(X) = \{ T \in \mathcal{E}(X) \mid \lim_{r \to \infty} \| 1_{B_x(r)} T \| = 0 \text{ for all } r > 0 \}.
\] (2.13)

The operators $T \in \mathcal{G}(X)$ vanish everywhere at infinity in the configuration space $X$ but could be not compact. The role of the Property A is to ensure that $\mathcal{G}(X) = \mathcal{I}(X)$. For discrete metric spaces of bounded geometry, this phenomenon is studied in detail by Chen and Wang, see [CW1, CW2, Wa] and references therein. Proposition 5.10 shows, among other things, that our definition of the ghost ideal in the discrete case coincides with theirs.

Observe that in general, if $H$ is an observable affiliated to $\mathcal{E}(X)$ then the ghost spectrum of $H$, i.e. the spectrum of the quotient observable $H/\mathcal{G}(X)$, is strictly included in the essential spectrum of $H$.

### 3. The elliptic $C^*$-algebra

In this section $X = (X, d, \mu)$ is a metric space $(X, d)$ equipped with a measure $\mu$ and such that:
- $(X, d)$ is a locally compact not compact metric space and each closed ball is a compact set,
- $\mu$ is a Radon measure on $X$ with support equal to $X$ and $\sup_x \mu(B_x(r)) = V(r) < \infty \forall r > 0$.

If $k$ is a controlled kernel let $d(k)$ be the least number $r$ such that $d(x, y) > r \Rightarrow k(x, y) = 0$. Recall that
\[
C_{trl}(X^2) = \{ k : X^2 \to \mathbb{C} \mid k \text{ is a bounded uniformly continuous controlled kernel} \}.
\] (3.14)

If $k \in C_{trl}(X^2)$ then $Op(k)$ is the operator on $L^2(X)$ given by $(Op(k)f)(x) = \int_X k(x, y)f(y)dx$. From
\[
\|Op(k)\|^2 \leq \sup_x \int |k(x, y)|dy \cdot \sup_y \int |k(x, y)|dx,
\] (3.15)

which is the Schur estimate, we get
\[
\|Op(k)\| \leq V(d(k)) \sup |k|.
\] (3.16)

If $k, l \in C_{trl}(X^2)$ then we denote $k^*(x, y) = \overline{k(y, x)}$ and $(k \ast l)(x, y) = \int k(x, z)l(z, y)dz$. Clearly $Op(k^* \ast Op(k^*) \ast Op(k)Op(l) = Op(k \ast l)$. The following simple fact is useful.

**Lemma 3.1.** If $k, l \in C_{trl}(X^2)$ then $k \ast l \in C_{trl}(X^2)$, we have $d(k \ast l) \leq d(k) + d(l)$, and
\[
\sup |k \ast l| \leq \sup |k| \cdot \sup |l| \cdot \min\{V(d(k)), V(d(l))\}.
\]

**Proof:** If we set $s = d(k)$ and $t = d(l)$ then clearly
\[
|(k \ast l)(x, y)| \leq \sup |k| \cdot \sup |l| \cdot \mu(B_x(s) \cap B_y(t))
\]
which gives both estimates from the statement of the lemma. To prove the uniform continuity we use
\[
|(k \ast l)(x, y) - (k \ast l)(x', y)| \leq \sup_x |k(x, z) - k(x', z)| \int \|l(z, y)\|dz
\]
\[
\leq \sup_z |k(x, z) - k(x', z)| \cdot \sup |l| \cdot V(t)
\]
and a similar inequality for $|(k \ast l)(x, y) - (k \ast l)(x, y')|$. Thus $C_{trl}(X^2)$, when equipped with the usual linear structure and the operations $k^*$ and $k \ast l$, becomes a $*$-algebra and $k \mapsto Op(k)$ is a morphism into $\mathcal{B}(X)$ hence its range is a $*$-subalgebra of $\mathcal{B}(X)$. Hence the elliptic algebra $\mathcal{E}(X)$ defined in (2.5) is a $C^*$-algebra of operators on $L^2(X)$.

The uniform continuity assumption involved in the definition (3.14) of $C_{trl}(X)$ hence in that of $\mathcal{E}(X)$ is important because thanks to it we have $\mathcal{E}(X) = C(X) \rtimes X$ if $X$ is a unimodular locally compact group, cf. Sections 6 and 7. Here $C(X)$ is the $C^*$-algebra of right uniformly continuous functions on $X$ on which $X$ acts by left translations and $\rtimes$, denotes the reduced crossed product. In particular, the equality $C(X) \rtimes X = \mathcal{E}(X)$ gives a description of the crossed product independent of the group structure of $X$. 
We say that $T \in \mathcal{B}(X)$ is a controlled operator if there is $r > 0$ such that if $F, G$ are closed subsets of $X$ with $d(F, G) > r$ then $1_F T 1_G = 0$; let $d(T)$ be the smallest $r$ for which this holds (see [Ro1]; this class of operators has also been considered in [Dav] and in [GG2]). Observe that the $Op(k)$ with $k \in C_{+1}(X^2)$ are controlled operators but if $X$ is not discrete then there are many others and most of them do not belong to $\mathcal{E}(X)$. The norm closure of the set of controlled operators will be discussed in Section 7.

Since the kernel of $\varphi(Q) Op(k)$ is $\varphi(x) k(x, y)$ and that of $Op(k) \varphi(Q)$ is $k(x, y) \varphi(y)$, we clearly have

$$C(X) \mathcal{E}(X) = \mathcal{E}(X) \mathcal{C}(X) = \mathcal{E}(X).$$

This defines a $C(X)$-bimodule structure on $\mathcal{E}(X)$. We note that, as a consequence of the Cohen-Hewitt theorem, if $A$ is a $C^*$-subalgebra of $C(X)$ then the set $\mathcal{A}E(X)$ consisting of products $AT$ of elements $A \in A$ and $T \in \mathcal{E}(X)$ is equal to the closed linear subspace of $\mathcal{E}(X)$ generated by these products.

**Proposition 3.2.** We have $\mathcal{H}(X) = C_0(X) \mathcal{E}(X) = \mathcal{E}(X) C_0(X) \subset \mathcal{E}(X)$.

**Proof:** If $\varphi \in C_c$ and $k \in C_{+1}$ then the operator $\varphi Op(k)$ has kernel $\varphi(x) k(x, y)$ which is a continuous function with compact support on $X^2$, hence $\varphi Op(k)$ is a Hilbert-Schmidt operator. Thus we have $C_0(X) \mathcal{E}(X) \subset \mathcal{H}(X)$ and by taking adjoints we also get $\mathcal{E}(X) C_0(X) \subset \mathcal{H}(X)$. Conversely, an operator with kernel in $C_c(X^2)$ clearly belongs to $C_c(X) \mathcal{E}(X)$ for example.

$\mathcal{E}(X)$ is a non-degenerate $C_0(X)$-bimodule and there is a natural topology associated to such a structure, we call it the local topology on $\mathcal{E}(X)$. Its utility will be clear from Section 6.

**Definition 3.3.** The local topology on $\mathcal{E}(X)$ is the topology associated to the family of seminorms $\|T\|_\theta = \|T \theta(Q)\| + \|\theta(Q) T\|$ with $\theta \in C_0(X)$.

This is the analog of the topology of local uniform convergence on $C(X)$. Obviously one may replace the $\theta$ with $1_A$ where $A$ runs over the set of compact subsets of $X$. If $T \in \mathcal{E}(X)$ and $\{T_\alpha\}$ is a net of operators in $\mathcal{E}(X)$ we write $T_\alpha \to T$ or $lim_\alpha T_\alpha = T$ locally if the convergence takes place in the local topology. Since $X$ is $\sigma$-compact there is $\theta \in C_0(X)$ with $\|\theta\| > 0$ for all $x \in X$ and then $\| \cdot \|_\theta$ is a norm on $\mathcal{E}(X)$ which induces on bounded subsets of $\mathcal{E}(X)$ the local topology.

The local topology is finer than the $*$-strong operator topology inherited from the embedding $\mathcal{E}(X) \subset \mathcal{B}(X)$. We may also consider on $\mathcal{E}(X)$ the (intrinsically defined) strict topology associated to the smallest essential ideal $\mathcal{K}(X)$; this is weaker than the local topology and finer than the $*$-strong operator topology, but coincides with the last one on bounded sets.

**Lemma 3.4.** The involution $T \mapsto T^*$ is locally continuous on $\mathcal{E}(X)$. The multiplication is locally continuous on bounded sets.

**Proof:** Since $\|T^*\|_\theta = \|T\|_\theta$ the first assertion is clear. Now assume $S_\alpha \to S$ locally and $\|S_\alpha\| \leq C$ and $T_\alpha \to T$ locally. If $\theta \in C_0$ then $T \theta$ is a compact operator so there is $\theta' \in C_0$ such that $T \theta = \theta' K$ for some compact operator $K$. Then we have $(S_\alpha T_\alpha - ST) \theta = S_\alpha (T_\alpha - T) \theta + (S_\alpha - S) \theta' K$. □

The ghost ideal is defined as follows:

$$\mathcal{G}(X) := \{ T \in \mathcal{E}(X) \mid \lim_{x \to \infty} \|1_{B_x(r)} T\| = 0 \, \forall r \} = \{ T \in \mathcal{E}(X) \mid \lim_{x \to \infty} \|T 1_{B_x(r)}\| = 0 \, \forall r \}. \quad (3.17)$$

The fact that $\mathcal{G}$ is an ideal of $\mathcal{E}$ follows from the equality stated above which in turn is proved as follows: for each $\varepsilon > 0$ there is a controlled kernel $k$ such that $\|T - Op(k)\| < \varepsilon$ hence if $R = r + d(k)$ we have

$$\|T 1_{B_x(r)}\| < \varepsilon + \|Op(k) 1_{B_x(r)}\| = \varepsilon + \|1_{B_x(R)} Op(k) 1_{B_x(r)}\| < 2\varepsilon + \|1_{B_x(R)} T\|$$

which is less than $3\varepsilon$ for large $x$.

We have $\mathcal{H}(X) \subset \mathcal{G}(X)$ because $\lim_{x \to \infty} 1_{B_x(r)} = 0$ strongly on $L^2$. It is known that the inclusion is strictly in general [HLS, p. 349]. In the rest of this section we prove that equality holds if $X$ is of class $A$. We begin with some general useful remarks.
Lemma 3.6. If (2.4) is satisfied and $T$ is a controlled operator, then
\[
\|T\| \leq N(d(T) + 1)^{1/2} \sup_{x \in X} \|1_{B_x}T\|.
\] (3.18)

Proof: Set $R = d(T) + 1$. Then for any $f \in L^2$ we have
\[
\|Tf\| \leq \sum_{z \in Z} \|1_{B_z}Tf\| = \sum_{z \in Z} \|1_{B_z}T1_{B_z(r)}f\| \leq \sup_{z \in Z} \|1_{B_z}T\|^2 \sum_{z \in Z} \|1_{B_z(r)}f\|^2
\]
and from Lemma 3.5 we get $\sum_{z \in Z} 1_{B_z(r)} \leq N(R)$.

Lemma 3.7. Assume that (2.4) is satisfied and let $T \in \mathcal{B}(X)$. If $\lim_{x \to \infty} \|1_{B_z(r)}T\| = 0$ holds for $r > 0$. Then it holds for all $r > 0$. In particular, we have
\[
\mathcal{B}(X) = \{T \in \mathcal{E}(X) \mid \lim_{x \to \infty} \|1_{B_z}T\| = 0\} = \{T \in \mathcal{E}(X) \mid \lim_{x \to \infty} \|T1_{B_z}\| = 0\}.
\] (3.19)

Proof: Let $r > 1$, $\varepsilon > 0$ and let $F$ be a finite subset of $Z$ such that $\|1_{B_z}T\| < \varepsilon/N(r)$ if $z \in Z \setminus F$. We consider points $x$ such that $d(x, F) > r + 1$ and denote $Z(x, r)$ the set of $z \in Z$ such that $B_z \cap B_x(r) \neq \emptyset$. Then $Z(x, r)$ has at most $N(r)$ elements and $B_x(r) \subset \cup_{z \in Z(x, r)} B_z$ hence $\|1_{B_z}T\| \leq N(r) \max_{z \in Z(x, r)} \|1_{B_z}T\| < \varepsilon$ because $F \cap Z(x, r) = \emptyset$.

An operator $T \in \mathcal{B}(X)$ is called locally compact if for any compact set $K$ the operators $1_{K} T$ and $T 1_{K}$ are compact. Clearly any operator in $\mathcal{E}(X)$ is locally compact.

Lemma 3.8. Assume that (2.4) is satisfied. If $T \in \mathcal{B}(X)$ is a controlled locally compact operator such that $\|1_{B_z}T\| \to 0$ as $x \to \infty$ then $T$ is compact.

Proof: Choose $o \in X$ and let $1_R$ be the characteristic function of the ball $B_o(R)$. Then $1_R T$ is compact so it suffices to show that $1_R T$ converges in norm to $T$ as $R \to \infty$. Clearly $T - 1_R T$ is controlled with $d(T - 1_R T) \leq d(T)$ hence from Lemma 3.6 we get
\[
\|T - 1_R T\| \leq C \sup_{x \in X} \|1_{B_x}(1 - 1_R)T\| \leq C \sup_{d(x, o) > R - 1} \|1_{B_x}T\|
\]
which proves the lemma.

Now we use an idea from [CW1] (truncation of kernels with the help of functions of positive type) and the technique of the proof of Theorem 5.1 from [Pi].

Let $\mathcal{H}$ be an arbitrary separable Hilbert space (in Definition 2.1 we took $\mathcal{H} = L^2(X)$) and let $\phi : X \to \mathcal{H}$ be a Borel function such that $\|\phi(x)\| = 1$ for all $x$. Define $M_\phi : L^2(X) \to L^2(X; \mathcal{H}) = L^2(X) \otimes \mathcal{H}$ by $(M_\phi f)(x) = f(x) \phi(x)$. Then $M_\phi$ is a linear operator with $\|M_\phi\| = 1$ and its adjoint $M_\phi^* : L^2(X; \mathcal{H}) \to L^2(X)$ acts as follows: $(M_\phi^* F)(x) = (\phi(x) F)(x)$. Let $T \mapsto T_\phi$ be the linear continuous map on $\mathcal{B}(X)$ given by $T_\phi = M_\phi^* (T \otimes 1) M_\phi$. Clearly $\|T_\phi\| \leq \|T\|$. Let $k : X^2 \to \mathbb{C}$ be a locally integrable function. We say that an operator $T \in \mathcal{B}(X)$ has integral kernel $k$ if $(f | T g) = \int_{X^2} k(x, y) f(x) g(y) d\nu dx dy$ for all $f, g \in C_c(X)$. If $k$ is a Schur kernel, i.e. $\sup_x \int_X \|k(x, y)\| + $
that we may replace \( \| \cdot \| \) by \( \langle \cdot, \cdot \rangle \) and get the

\[ \sum_{x \in X} \| x \|^2 = \sum_{x \in X} \langle x, x \rangle = \sum_{x \in X} \| x \|_2^2 \]

for any \( x \in X \). This shows that \( X \) is a Hilbert space.

Theorem 3.12. If \( T \) has kernel \( k \) then \( T \) has kernel \( k_\phi(x, y) = \langle \phi(x), \phi(y) \rangle k(x, y) \). In particular, if \( T \) is a
Schur, Hilbert-Schmidt, or compact operator, then \( T \) has the same property.

Lemma 3.9. If \( k \) is a Hilbert-Schmidt operator if and only if \( \| k \|_2^2 \) is finite for all \( k \in L^2(X \times X) \).

Lemma 3.10. Assume that \( \langle x, y \rangle = 0 \) if \( d(x, y) > r \). Then for each \( T \in \mathcal{B}(X) \) the operator \( T \) is controlled, more precisely: if \( F, G \) are closed subsets of \( X \) with \( d(F, G) > r \) then \( 1_F T \to 1_G = 0 \).

Proof: We have to prove that \( \langle 1_F f | T \phi g \rangle = 0 \) for all \( f, g \in L^2(X) \) and \( T \in \mathcal{B}(X) \). The map \( T \to T \) is continuous for the weak operator topology and the set of finite range operators is dense in \( \mathcal{B}(X) \) for this topology. Thus it suffices to assume that \( T \) is Hilbert-Schmidt (or even of rank one) and then the assertion is clear by Lemma 3.9.

Lemma 3.11. Let \( T \in \mathcal{B}(X) \). If \( T \) is locally compact then \( T \) is locally compact. If \( \| 1_{B_x(r)} T \| \to 0 \) as \( x \to \infty \), then \( \| 1_{B_x(r)} T \phi \| \to 0 \) as \( x \to \infty \).

Theorem 3.12. If \( X \) is a class \( \mathcal{A} \) space then \( \mathcal{K}(X) = \mathcal{H}(X) \).

Proof: Let \( T \in \mathcal{G}(X) \) and \( \phi \) as above. Then \( T \) is locally compact hence \( T \phi \) is locally compact, and we have \( \| 1_{B_x} T \| \to 0 \) as \( x \to \infty \) by Lemma 3.11. Moreover, if \( \phi \) is as in Lemma 3.10 then \( T \phi \) is controlled so, by Lemma 3.8, \( T \phi \) is compact. Thus it suffices to show that any \( T \in \mathcal{E}(X) \) is a norm limit of operators \( T \phi \) with \( \phi \) of the preceding form. Since \( T \to T \) is a linear contraction, it suffices to show this for operators of the form \( T = Op(k) = (\int \phi(x) \phi(y) dx \otimes dy) \). Then \( T = T \phi \) is an operator with kernel \( k(x, y) (1 - \langle \phi(x), \phi(y) \rangle) \). Hence, if we denote \( M = \sup |k|, d = \| k \|_2 \), from (3.15) we get

\[ \| T - T \phi \| \leq M \sup_x \int_{B_x(d)} |1 - \langle \phi(x), \phi(y) \rangle| dy. \]

Until now we did not use the fact that \( \mathcal{H} = L^2(X) \) in Definition 2.1. If we are in this situation note that we may replace \( \phi(x) \) by \( |\phi(x)| \) and then \( \langle \phi(x), \phi(y) \rangle \) is real. More generally, assume that the \( \phi(x) \) belong to a real subspace of the (abstract) Hilbert space \( \mathcal{H} \) so that \( \langle \phi(x), \phi(y) \rangle \) is real for all \( x, y \). Then

\[ 1 - \langle \phi(x), \phi(y) \rangle = \| \phi(x) - \phi(y) \|^2 / 2 \]

so we have

\[ \| T - T \phi \| \leq (M/2) \sup \int_{B_x(d)} \| \phi(x) - \phi(y) \|^2 dy. \]

Since \( X \) has Property A, one may choose \( \phi \) such that this be smaller than any given number.

4. COARSE FILTERS ON \( X \) AND IDEALS OF \( C(X) \)

4.1. Filters. We recall some elementary facts; for the moment \( X \) is an arbitrary set. A \emph{filter} on \( X \) is a nonempty set \( \xi \) of subsets of \( X \) which is stable under finite intersections, does not contain the empty set, and has the property: \( G \supset F \in \xi \Rightarrow G \in \xi \). If \( Y \) is a topological space and \( \phi : X \to Y \) then \( \lim_{\xi} \phi = y \) or \( \lim_{x \to \xi} \phi(x) = y \) means that \( y \in Y \) and \( V \) is a neighborhood of \( y \) then \( \phi^{-1}(V) \in \xi \).

The set of filters on \( X \) is equipped with the order relation given by inclusion. Then the trivial filter \( \{ X \} \) is the smallest filter and the lower bound of any nonempty set \( F \) of filters exists: \( \cap F = \cap_{\xi \in F} \xi \). A set \( F \) of filters is called \emph{admissible} if \( \cap_{\xi \in F} F \notin \emptyset \) if \( F \in \xi \) for all \( \xi \) and \( F \times X = X \) but for a finite number of indices \( \xi \). If \( F \) is admissible then the upper bound \( \sup F \) exists: this is the set of sets of the form \( \cap_{\xi \in F} F \) where \( F \times X \) for all \( \xi \) and \( F \times X = X \) for a finite number of indices \( \xi \).

Let \( \beta(X) \) be the set of ultrafilters on \( X \). If \( \xi \) is a filter let \( \xi \) be the set of ultrafilters finer than it. Then \( \xi = \inf \xi \). We equip \( \beta(X) \) with the topology defined by the condition: a nonempty subset of \( \beta(X) \) is
closed if and only if it is of the form $\xi^\dagger$ for some filter $\xi$. Note that for the trivial filter consisting of only one set we have $\{X\}^\dagger = \beta(X)$. Then $\beta(X)$ becomes a compact topological space, this is the Stone-Čech compactification of the discrete space $X$, and is naturally identified with the spectrum of the $C^*$-algebra of all bounded complex functions on $X$. There is an obvious dense embedding $X \subseteq \beta(X)$, any bounded function $\varphi : X \to \mathbb{C}$ has a unique continuous extension $\beta(\varphi)$ to $\beta(X)$, and any map $\phi : X \to Y$ has a unique extension to a continuous map $\beta(\phi) : \beta(X) \to \beta(Y)$.

More generally, if $Y$ is a compact topological space, each map $\phi : X \to Y$ has a unique extension to a continuous map $\beta(\phi) : \beta(X) \to Y$. The following simple fact should be noticed: if $\xi$ is a filter and $o$ is a point in $Y$ then $\lim_{\xi} \phi = o$ is equivalent to $\beta(\phi)|\xi^\dagger = o$. Indeed, $\lim_{\xi} \phi = o$ is equivalent to $\lim_{\xi} \phi = o$ for any $x \in \xi^\dagger$ (for the proof, observe that if this last relation holds then for each neighborhood $V$ of $o$ the set $\phi^{-1}(V)$ belongs to $\kappa$ for all $x \in \xi^\dagger$, hence $\phi^{-1}(V) \subseteq \cap_{x \in \xi^\dagger} \kappa = \xi$).

Now assume that $X$ is a locally compact non-compact topological space. Then the Fréchet filter is the set of complements of relatively compact sets; we denote it $\infty$, so that $\lim_{x \to \infty} \phi(x) = y$ has the standard meaning. Let $\delta(X) = \infty^\dagger$ be the set of ultrafilters finer than it. Thus $\delta(X)$ is a compact subset of $\beta(X)$ and we have $\delta(X) \subseteq \beta(X) \setminus X$ (strictly in general):

$$\delta(X) = \{ \kappa \in \beta(X) : \text{if } K \subseteq X \text{ is relatively compact then } K \notin \kappa \}.$$ 

Indeed, if $\kappa$ is an ultrafilter then for any set $K$ either $K \in \kappa$ or $K^c \in \kappa$. If we interpret $\kappa$ as a character of $\ell^\infty(X)$ then $\kappa \in \delta(X)$ means $\kappa(\varphi) = 0$ for all $\varphi \in C_c(X)$.

4.2. Coarse filters. Now assume that $X$ is a metric space. If $F \subseteq X$ then $F$ is its closure and $F^c = X \setminus F$ its complement. We set $d_F(x) := \inf_{y \in F} d(x,y)$. Note that $d_F = d_F^{-}$ and $|d_F(x) - d_F(y)| \leq d(x,y)$. If $r > 0$ let $F(r) := \{ x : d(x,F) \leq r \} = \cup_{x \in F} B_x(r)$ be the neighborhood “of order” $r$ of $F$.

If $r > 0$ we denote $F^{(r)}$ the set of points $x$ such that $d(x,F^c) > r$. This is an open subset of $X$ included in $F$ and at distance $r$ from the boundary of $F$ (so if $F$ is too thin, $F^{(r)}$ is empty). In other terms, $x \in F^{(r)}$ means that there is $r' > r$ such that $B_x(r') \subseteq F$. In particular, $(F^{(r)})_r \subseteq F$ and for an arbitrary pair of sets $F,G$ we have $(F \cap G)^{(r)} = F^{(r)} \cap G^{(r)}$ and $F \subseteq G \Rightarrow F^{(r)} \subseteq G^{(r)}$.

We say that a filter $\xi$ is coarse if for any $F \in \xi$ and $r > 0$ we have $F^{(r)} \in \xi$. We emphasize that this should hold for all $r > 0$. If for each $F \in \xi$ there is $r > 0$ such that $F^{(r)} \in \xi$ then the filter is called round.

Equivalently, $\xi$ is coarse if for each $F \in \xi$ and $r > 0$ there is $G \in \xi$ such that $G_{(r)} \subseteq F$ and $G$ is round if for each $F \in \xi$ there are $G \in \xi$ and $r > 0$ such that $G_{(r)} \subseteq F$.

Our terminology is related to the notion of coarse ideal introduced in [HPR] (our space $X$ being equipped with the bounded metric coarse structure). More precisely, a coarse ideal is a set $\mathcal{I}$ of subsets of $X$ such that $B \subseteq A \in \mathcal{I} \Rightarrow B \in \mathcal{I}$ and $A \in \mathcal{I} \Rightarrow A_{(r)} \in \mathcal{I}$ for all $r > 0$. Clearly $\mathcal{I} \mapsto \mathcal{I}^c := \{ A^c : A \in \mathcal{I} \}$ is a one-one correspondence between coarse ideals and filters.

Coarse filters on groups are very natural objects: if $X$ is a group, then a round filter is coarse if and only if it is translation invariant (Proposition 6.6).

The Fréchet filter is coarse because if $K$ is relatively compact then $K_{(r)}$ is compact for any $r$ (the function $d_K$ is proper under our assumptions on $X$). The trivial filter $\{X\}$ is coarse.

More general examples of coarse filters are constructed as follows [Dav, GI1]. Let $L \subseteq X$ be a set such that $L_{(r)} \neq X$ for all $r > 0$. Then the filter generated by the sets $L_{(r)}^\dagger = \{ x : d(x,L) > r \}$ when $r$ runs over the set of positive real numbers is coarse (indeed, it is clear that the $L_{(r)}^\dagger$ generate a coarse ideal). If $L$ is compact the associated filter is $\infty$. If $X = \mathbb{R}$ and $|L| = -\infty, 0|$ then the corresponding filter consists of neighborhoods of $+\infty$ and this example has obvious $n$-dimensional versions. If $L$ is a sparse set (i.e. the distance between $a \in L$ and $L \setminus \{a\}$ tends to infinity as $a \to \infty$) then the ideal in $\mathcal{C}(X)$ associated to it (cf. below) and its crossed product by the action of $X$ (if $X$ is a group) are quite remarkable objects, cf. [GI1]. It should be clear however that most coarse filters are not associated to any set $L$. 
Let $X$ be an Euclidean space and let $G(X)$ be the set of finite unions of strict vector subspaces of $X$. The sets $L_{\ell}(r)$ when $L$ runs over $G(X)$ and $r$ over $\mathbb{R}_+$ form a filter basis and the filter generated by it is the Grassmann filter $\gamma$ of $X$. This is a translation invariant hence coarse filter which plays a role in a general version of the $N$-body problem, see [GI3, Section 6.5]. The relation $\lim_{r} \varphi = 0$ means that the function $\varphi$ vanishes when we are far from any strict affine subspace.

**Lemma 4.1.** If $F$ is a nonempty set of coarse filters then $\inf F$ is a coarse filter. If $F$ is admissible then $\sup F$ is a coarse filter.

**Proof:** If $F \subseteq \inf F = \cap_{\xi \in F} \xi$ then for any $r > 0$ and $\xi$ we have $F^{(r)} \subseteq \xi$ and so $F^{(r)} \subseteq \cap_{\xi \in F} \xi$. Now assume for example that $F \subseteq \xi$ and $G \subseteq \eta$ with $\xi, \eta \in F$ and let $r > 0$. Then there are $F' \subseteq \xi$ and $G' \subseteq \eta$ such that $F' \subseteq F$ and $G' \subseteq G$ hence $(F' \cap G')^{(r)} \subseteq F^{(r)} \cap G^{(r)} \subseteq F \cap G$. The argument sets of the form $\cap_{\xi} F_{\xi}$ with $F_{\xi} = X$ but for a finite number of indices $\xi$ is similar. \qed

**Lemma 4.2.** A coarse filter is either trivial, and then $\xi^1 = \beta(X)$, or finer than the Fréchet filter, and then $\xi^1 \subseteq \delta(X)$.

**Proof:** Assume that $\xi$ is not finer than the Fréchet filter. Then there is a compact set $K$ such that $K^c \not\subseteq \xi$. Hence for any $F \subseteq \xi$ we have $F \not\subseteq K^c$ so $F \cap K \neq \emptyset$. Note that the closed sets in $\xi$ form a basis of $\xi$ (if $F \subseteq \xi$ then the closure of $F^{(2)}$ belongs to $\xi$ and is included in $F^{(1)}$ hence in $F$). The set $\{ F \cap K : F \subseteq \xi \}$ is a filter basis consisting of closed sets in the compact set $K$ hence there is $a \subseteq K$ such that $a \subseteq F$ for all $F \subseteq \xi$. Then if $F \subseteq \xi$ and $r > 0$ there is $G \subseteq \xi$ such that $G^{(r)} \subseteq F$ and since $a \subseteq G$ we have $B_a(r) \subseteq G^{(r)} \subseteq F$. But $X = \cup_r B_a(r)$ so $X \subseteq F$. \qed

### 4.3. Coarse ideals of $\mathcal{C}(X)$

We now recall some facts concerning the relation between filters on $X$ and ideals of $\mathcal{C}(X)$. To each filter $\xi$ on $X$ we associate an ideal $\mathcal{I}_\xi(X)$ of $\mathcal{C}(X)$:

$$\mathcal{I}_\xi(X) := \{ \varphi \in \mathcal{C}(X) \mid \lim_{\xi} \varphi = 0 \} \quad (4.20)$$

If $\xi$ is the Fréchet filter then $\lim_{\xi} \varphi = 0$ means $\lim_{x \to \infty} \varphi(x) = 0$ in the usual sense and so the corresponding ideal is $\mathcal{C}_0(X)$. The ideal associated to the trivial filter clearly is $\{ 0 \}$. We also have:

$$\xi \subseteq \eta \Rightarrow \mathcal{I}_\xi(X) \subseteq \mathcal{I}_\eta(X) \quad (4.21)$$

$$\mathcal{I}_{\xi \cap \eta}(X) = \mathcal{I}_\xi(X) \cap \mathcal{I}_\eta(X) = \mathcal{I}_\xi(X) \mathcal{I}_\eta(X) \quad (4.22)$$

The round envelope $\xi^o$ of $\xi$ is the finer round filter included in $\xi$. Clearly this is the filter generated by the sets $F^{(r)}$ when $F$ runs over $\xi$ and $r$ over $\mathbb{R}_+$. Note that $\mathcal{I}_\xi(X) = \mathcal{I}_{\xi^o}(X)$, i.e. for $\varphi \in \mathcal{C}(X)$ we have $\lim_{\xi} \varphi = 0$ if and only if $\lim_{\xi^o} \varphi = 0$. Indeed, if $\varepsilon > 0$ let $F$ be the set of points were $|\varphi(x)| < \varepsilon/2$ and let $r > 0$ be such that $|\varphi(x) - \varphi(y)| < \varepsilon/2$ if $d(x, y) \leq r$. Then $|\varphi(x)| < \varepsilon$ if $x \in F^{(r)}$.

We recall a well-known description of the spectrum of the algebra $\mathcal{C}(X)$ in terms of round filters.

**Proposition 4.3.** The map $\xi \mapsto \mathcal{I}_\xi(X)$ is a bijection between the set of all round filters on $X$ and the set of all ideals of $\mathcal{C}(X)$.

An ideal $\mathcal{I}$ of $\mathcal{C}(X)$ will be called coarse if for each positive $\varphi \in \mathcal{I}$ and $r > 0$ there is a positive $\psi \in \mathcal{I}$ such that

$$d(x, y) \leq r \text{ and } \psi(y) < 1 \Rightarrow \varphi(x) < 1. \quad (4.23)$$

**Lemma 4.4.** Let $F, G$ be subsets of $X$ such that $G^{(r)} \subseteq F$. Then the function $\theta = d_{F^c} (d_{F^c} + d_G)^{-1}$ belongs to $\mathcal{C}(X)$ and satisfies the estimates $1_G \leq \theta \leq 1_F$ and $|\theta(x) - \theta(y)| \leq 3r^{-1}d(x, y)$. In particular, a filter $\xi$ is coarse if and only if for any $F \subseteq \xi$ and any $\varepsilon > 0$ there is $G \subseteq \xi$ and a function $\theta$ such that $1_G \leq \theta \leq 1_F$ and $|\theta(x) - \theta(y)| \leq \varepsilon d(x, y)$. \hfill \qed
Proof: If \( a \in G \) and \( b \notin F \) then \( r < d(a, b) \leq d(x, a) + d(x, b) \) for any \( x \). By taking the lower bound of the right hand side over \( a, b \) we get \( r \leq d_G(x) + d_F(x) \equiv D(x) \). Hence if \( d(x) \equiv d_F(x) \) then
\[
|\theta(x) - \theta(y)| \leq \frac{|d(x) - d(y)|}{D(x)} + d(y) \frac{|D(x) - D(y)|}{D(x) D(y)} \leq \frac{d(x, y)}{r} + \frac{|D(x) - D(y)|}{D(x) D(y)} \leq \frac{d(x, y)}{3r}.
\]

To prove the last assertion, notice that if such a \( \theta \) exists for some \( \varepsilon < 1/r \) and if \( x \in G \) and \( d(x, y) \leq r \) then \( \theta(x) = 1 \) and \( |\theta(x) - \theta(y)| < 1 \) hence \( \theta(y) > 0 \) so \( y \in F \). Thus \( G(r) \subseteq F \).

Proposition 4.5. The filter \( \xi \) is coarse if and only if the ideal \( \mathcal{I}_\xi(X) \) is coarse.

Proof: Assume \( \xi \) is not trivial and coarse and let \( \varphi \in \mathcal{I}_\xi \) positive and \( r > 0 \). Then \( \mathcal{O}_\varphi := \{ \varphi < 1 \} \subseteq \xi \) hence there is \( G \in \xi \) such that \( G(2r) \subseteq \mathcal{O}_\varphi \). By using Lemma 4.4 we construct \( \psi \in \mathcal{C} \) such that \( 0 \leq \psi \leq 1 \), \( \psi|_G = 0 \), and \( \psi|_{G(r)} = 1 \). Clearly \( \psi \in \mathcal{I}_\xi \). If \( \psi(y) < 1 \) then \( y \in G(r) \) hence if \( d(x, y) \leq r \) then \( x \in G(r) \) so \( \varphi(x) < 1 \). Thus \( \mathcal{I}_\xi \) is coarse. Reciprocally, assume that \( \mathcal{I}_\xi \) is a coarse ideal and let \( F \in \xi \) and \( r > 0 \). There is \( \varphi \in \mathcal{I}_\xi \) positive such that \( \mathcal{O}_\varphi \subseteq F \) and there is a positive function \( \psi \in \mathcal{I}_\xi \) such that (4.23) holds, But then \( \mathcal{O}_\psi \in \xi \) and \( \mathcal{O}_\psi \cap F \subseteq \mathcal{O}_\varphi \) so \( \xi \) is coarse.

4.4. Coarse envelope. If \( \xi \) is a filter then the family of coarse filters included in \( \xi \) is admissible, hence there is a largest coarse filter included in \( \xi \). We denote it \( \text{co}(\xi) \) and call it coarse envelope (or cover) of \( \xi \). A set \( F \) belongs to \( \text{co}(\xi) \) if and only if \( F(r) \in \xi \) for any \( r > 0 \) (the set of such \( F \) is a filter, see page 11).

By Lemma 4.2 we have only two possibilities: either \( \text{co}(\xi) = \{ X \} \) or \( \text{co}(\xi) \supseteq \infty \). Since \( \text{co}(\xi) \subseteq \xi \), we see that either \( \xi \) is finer than Fréchet, and then \( \text{co}(\xi) \supseteq \infty \), or not, and then \( \text{co}(\xi) = \{ X \} \).

To each ultrafilter \( \mathcal{U} \in \beta(X) \) we associate a compact subset \( \mathcal{U} \subseteq \beta(X) \) by the rule
\[
\mathcal{U} := \text{co}(\mathcal{U}) = \text{set of ultrafilters finer than the coarse envelope of } \mathcal{U}.
\]

Thus we have either \( \mathcal{U} \in \delta(X) \) and then \( \mathcal{U} \subseteq \delta(X) \), or \( \mathcal{U} \notin \delta(X) \) and then \( \mathcal{U} = \beta(X) \). On the other hand, we have \( \bigcup_{\mathcal{U} \in \delta(X)} \mathcal{U} = \delta(X) \) because \( \mathcal{U} \in \mathcal{U} \).

More explicitly, if \( \mathcal{U}, \mathcal{V} \in \delta(X) \) then \( \mathcal{U} \in \mathcal{V} \) means: if \( F \) is a set such that \( F(r) \in \mathcal{U} \) for all \( r \), then \( F \in \mathcal{V} \) (which is equivalent to \( F \cap G \neq \emptyset \) for all \( G \in \mathcal{V} \)).

If \( \mathcal{U} \) is an ultrafilter on \( X \) then \( C_\mathcal{U}(X) \) is the coarse ideal of \( C(X) \) defined by
\[
C_\mathcal{U}(X) = \text{co}(\mathcal{U}) = \{ \varphi \in C(X) | \lim_{\text{co}(\mathcal{U})} \varphi = 0 \}.
\]

The quotient \( C_\mathcal{U}(X) = C(X)/\text{co}(\mathcal{U}) \) will be called localization of \( C(X) \) at \( \mathcal{U} \). If \( \varphi \in C(X) \) then its image in the quotient is denoted \( \varphi_{\mathcal{U}} \) and is called localization of \( \varphi \) at \( \mathcal{U} \). The next comments give another description of these objects and will make clear that localization means extension followed by restriction.

Observe that \( \varphi \in C(X) \) belongs to \( C_\mathcal{U}(X) \) if and only if the restriction of \( \beta(\varphi) \) to \( \mathcal{U} \) is zero. Hence two bounded uniformly continuous functions are equal modulo \( C_\mathcal{U}(X) \) if and only if their restrictions to \( \mathcal{U} \) are equal. Thus \( \varphi \mapsto \beta(\varphi)|_{\mathcal{U}} \) induces an embedding \( C_\mathcal{U}(X) \to C(\mathcal{U}) \) which allows us to identify \( C_\mathcal{U}(X) \) with an algebra of continuous functions on \( \mathcal{U} \). From this we deduce
\[
\bigcap_{\mathcal{U} \in \delta(X)} C_\mathcal{U}(X) = C(X).
\]

Indeed, \( \varphi \) belongs to the left hand side if and only if \( \beta(\varphi)|_{\mathcal{U}} = 0 \) for all \( \mathcal{U} \in \delta(X) \). But the union of the sets \( \mathcal{U} \) is equal to \( \delta(X) \) hence this means \( \beta(\varphi)|_{\delta(X)} = 0 \) which is equivalent to \( \varphi \in C_\mathcal{U}(X) \).

A maximal coarse filter is a coarse filter which is maximal in the set of coarse filters equipped with inclusion as order relation. This set is inductive (the union of an increasing set of coarse filters is a coarse filter) hence each coarse filter is majorated by a maximal one. Dually, we say that a subset \( T \subseteq \delta(X) \) is coarse if it is of the form \( T = \mathcal{U}^\dagger \) for some coarse filter \( \mathcal{U} \). Note that if \( T \) is a minimal coarse set then \( T = \mathcal{U} \) for any ultrafilter \( \mathcal{U} \in T \). In general the coarse sets of the form \( \mathcal{U} \) with \( \mathcal{U} \in \delta(X) \) are not minimal.
5. Ideals of \( \mathcal{E}(X) \)

There are two classes of ideals in \( \mathcal{E}(X) \), which can be defined in terms of the behavior at infinity of the operators. For any filter \( \xi \) on \( X \) we define

\[
\mathcal{J}_\xi(X) = \{ T \in \mathcal{E}(X) \mid \inf_{F \in \xi} \|1_T F\| = 0 \}, \quad (5.27)
\]

\[
\mathcal{G}_\xi(X) = \{ T \in \mathcal{E}(X) \mid \lim_{x \to \xi} \|1_{B_x(r)} T\| = 0 \forall r \}. \quad (5.28)
\]

Here \( \inf_{F \in \xi} \|1_T F\| \) is the lower bound of the numbers \( \|1_T F\| \) when \( F \) runs over the set of measurable \( F \in \xi \) and we define \( \inf_{F \in \xi} \|T1_F\| \) similarly. Note that \( \|1_T F\| \leq \|1_G T\| \) and \( \|T1_F\| \leq \|T1_G\| \) if \( F \subseteq G \) are measurable. Recall also that \( \lim_{x \to \xi} \|1_{B_x(r)} T\| = 0 \) means: for each \( \varepsilon > 0 \) there is \( G \in \xi \) such that \( \|1_{B_x(r)} T\| < \varepsilon \) for all \( x \in G \). Observe that for the Fréchet filter \( \xi = \infty \) we have

\[
\mathcal{K} = \mathcal{J}_\infty \quad \text{and} \quad \mathcal{K} \subseteq \mathcal{G}_\infty = \mathcal{Y}
\]

where \( \mathcal{Y}(X) \) is the ghost ideal introduced in (3.17). That \( \mathcal{G}_\infty = \mathcal{K} \) follows from the fact that \( 1_{K} T \) is compact (or use (5.30) and Proposition 3.2). The equality \( \mathcal{G}_\infty(X) = \mathcal{Y}(X) \) is just a change of notation.

**Lemma 5.1.** If \( T \in \mathcal{E} \) and \( \xi \) is a coarse filter then \( \inf_{F \in \xi} \|1_T F\| = \inf_{F \in \xi} \|1_T F\| \).

**Proof:** If \( \inf_{F \in \xi} \|1_T F\| = a + \varepsilon > 0 \) then there is \( F \in \xi \) such that \( \|1_T F\| < a + \varepsilon \). We may choose \( k \in C_{1,1} \) such that \( \|T - O_p(k)\| < \varepsilon \) and then \( \|1_T O_p(k)\| < a + 2 \varepsilon \). Assume that \( k(x, y) = 0 \) if \( d(x, y) \geq r \) and let \( G \in \xi \) such that \( G(r) \subseteq F \). Then \( k(x, y)1_G(y) = 1_G(y)k(x, y)1_G(y) \) hence \( O_p(k)1_G = 1_G(k_o)O_p(k)1_G \) so \( \|O_p(k)1_G\| \leq \|O_p(k)1_G\| < a + 2 \varepsilon \) and so \( \|T1_G\| < a + 3 \varepsilon \). □

**Lemma 5.2.** For any filter \( \xi \) the set \( \mathcal{G}_\xi \) is an ideal of \( \mathcal{E} \) and we have \( \mathcal{J}_{co(\xi)} \subseteq \mathcal{G}_\xi \). If \( \xi \) is coarse then \( \mathcal{J}_\xi \) is also an ideal of \( \mathcal{E} \) and \( \mathcal{J}_\xi \subseteq \mathcal{G}_\xi \).

**Proof:** \( \mathcal{G}_\xi \) is obviously a closed right ideal in \( \mathcal{E} \) so it will be an ideal if show that \( \lim_{x \to \xi} \|T1_{B_x(r)}\| = 0 \) for all \( T \in \mathcal{G}_\xi \). Choose \( \varepsilon > 0 \) and let \( S \) be a controlled operator such that \( \|S - T\| < \varepsilon \). Then there is \( R \) such that \( S1_{B_x(r)} = 1_{B_x(r)}S1_{B_x(r)} \) and there is \( F \in \xi \) such that \( \|1_{B_x(r)} T\| < \varepsilon \) for all \( x \in F \), hence

\[
\|T1_{B_x(r)}\| < \varepsilon + \|S1_{B_x(r)}\| \leq \varepsilon + \|1_{B_x(r)} S\| < 2 \varepsilon + \|1_{B_x(r)} T\| < 3 \varepsilon.
\]

If \( T \in \mathcal{J}_{co(\xi)} \) then for any \( \varepsilon > 0 \) there is \( F \) such that \( F(r) \in \xi \) for all \( r \) such that \( \|1_T F\| < \varepsilon \). So if we fix \( r \) and take \( G = F(r) \in \xi \) then \( G \in \xi \) and \( \|1_{B_x(r)} T\| < \varepsilon \) for all \( x \in G \). Thus \( T \in \mathcal{G}_\xi \). Clearly \( \mathcal{J}_\xi \) is a closed right ideal in \( \mathcal{E} \). That it is an ideal if \( \xi \) is coarse follows from Lemma 5.1. □

**Proposition 5.3.** If \( \xi \) is a coarse filter on \( X \) then \( \mathcal{J}_\xi \) is an ideal of \( \mathcal{E} \) and we have

\[
\mathcal{J}_\xi = \mathcal{I}_{\xi} \mathcal{E} = \mathcal{E} \mathcal{I}_{\xi}.
\]

**Proof:** We now prove the first equality in (5.30) (the second one follows by taking adjoints). Clearly \( \varphi \in \mathcal{I}_{\xi} \) if and only if for each \( \varepsilon > 0 \) there is \( F \in \xi \) such that \( \|1_T F\| < \varepsilon \) hence if and only if \( \inf_{F \in \xi} \|1_T F\| = 0 \). This implies \( \mathcal{I}_{\xi} \mathcal{E} \subseteq \mathcal{J}_\xi \) and so it remains to be shown that for each \( T \in \mathcal{J}_\xi \) there are \( \varphi \in \mathcal{I}_{\xi} \) and \( S \in \mathcal{E} \) such that \( T = \varphi S \). If \( \xi \) is trivial this is clear, so we may suppose that \( \xi \) is finer than \( \infty \).

Choose a point \( o \in X \) and let \( K_n = B_o(n) \) for \( n \geq 1 \) an integer. We get an increasing sequence of compact sets such that \( \bigcup_n K_n = X \) and \( K_n \in \xi \). We construct by induction a sequence \( F_1 \supseteq G_1 \supseteq F_2 \supseteq G_2 \ldots \) of sets in \( \xi \) such that:

\[
F_n \subseteq K_n, \quad \|1_{F_n} T\| \leq n^{-2}, \quad d(G_n, F_n^c) > 1, \quad d(F_{n+1}, G_n^c) > 1.
\]

We start with \( F_1 \in \xi \) such that \( \|1_{F_1} T\| \leq 1 \), we set \( F_1 = F_1 \cap K_1^c \) and then we choose \( G_1 \in \xi \) such that \( d(G_1, F_1^c) > 1 \). Next, we choose \( F_2 \in \xi \) with \( \|1_{F_2} T\| \leq 1/4 \) and \( G_1 \subseteq G_1 \in \xi \) with \( G_1^c \subseteq G_1 \) and \( d(G_1, G_1^c) > 1 \). We take \( F_2 = F_2 \cap G_1 \cap K_2^c \), so \( d(F_2, G_1^c) > 1 \), and then we choose \( G_2 \in \xi \) with \( G_2 \in F_2 \) such that \( d(G_2, F_2^c) > 1 \), and so on.
Now we use Lemma 4.4 and for each \( n \) we construct a function \( \theta_n \in \mathcal{C} \) such that \( 1_{\mathcal{G}_n} \leq \theta_n \leq 1_{\mathcal{F}_n} \) and 
\( \| \theta_n(x) - \theta_n(y) \| \leq 3d(x, y) \). Then either \( B_a \cap F_1 = \emptyset \) or there is a unique \( m \) such that \( B_a \cap F_m \neq \emptyset \) and 
\( B_a \cap F_{m+1} = \emptyset \) and in this case \( \theta_n = 1 \) on \( B_a \) if \( n < m \) and \( \theta_n = 0 \) on \( B_a \) if \( n > m \). Let \( \theta(x) = \sum_{n} \theta_n(x) \). 
Thus \( \theta(x) = 0 \) on \( F_1 \) and if \( B_a \cap F_m \neq \emptyset \) and \( B_a \cap F_{m+1} = \emptyset \) we get 
\[ \theta(x) = \sum_{n \leq m} \theta_n(x) = m - 1 + \theta_m(x). \] (5.31)

Then \( \theta : X \to \mathbb{R}_+ \) is well defined and for \( d(x, y) < 1 \) and a conveniently chosen \( m \) we have 
\[ |\theta(x) - \theta(y)| = |\theta_m(x) - \theta_m(y)| \leq 3d(x, y). \]

Thus \( \theta \) is a measurable set and if we denote 
\[ S = \left( \sum_{n \leq m} \theta_n \right)^{-1} \left( \sum_{n \leq m} \theta_n \right). \]

On the other hand \( \| \theta_n T \| \leq \| 1_{F_1} T \| \leq n^{-2} \). Thus if \( \theta_0 = 1 \) then the limit of \( \sum_{n \leq m} \theta_n T \) as \( m \to \infty \) exists in norm and defines an element \( S \) of \( \mathcal{E} \). Then 
\[ T = \left( \sum_{n \leq m} \theta_n \right)^{-1} \left( \sum_{n \leq m} \theta_n \right) \to (1 + \theta)^{-1} S \]

because \( \left( \sum_{n \leq m} \theta_n \right)^{-1} \to (1 + \theta)^{-1} \) strongly on \( L^2(X) \). If \( \varphi := (1 + \theta)^{-1} \) then \( 0 \leq \varphi \leq 1 \) and 
\[ |\varphi(x) - \varphi(y)| \leq |\theta(x) - \theta(y)| \leq 3d(x, y) \text{ if } d(x, y) < 1. \]

Thus \( \varphi \in \mathcal{C} \). If \( x \in B_a \) with \( B_a \cap F_m \neq \emptyset \) and \( B_a \cap F_{m+1} = \emptyset \) then (5.31) gives 
\[ \varphi(x) = (1 + m - 1 + \theta_m(x))^{-1} \leq 1/m \]

hence \( \varphi(x) \leq 1/m \) on \( F_m \). Thus \( \lim_{x \to \xi} \varphi = 0 \) and \( T = \varphi S \) with \( \varphi \in \mathcal{I}_x \) and \( S \in \mathcal{E} \).

We make now more precise the relation between \( \mathcal{I}_x \) and \( \mathcal{E}_x \).

**Lemma 5.4.** If (2.4) holds, \( T \in \mathcal{E} \) is controlled, \( \xi \) is coarse, and \( \lim_{x \to \xi} \| 1_{B_x} T \| = 0 \), then \( T \in \mathcal{I}_x \).

**Proof:** Assume (2.4) is satisfied and let \( T \in \mathcal{B}(X) \) be a controlled operator. Let \( Z \) be as in Lemma 3.5 and let us set \( a = d(T) + 1 \), so that \( 1_{B_x} T = 1_{B_x} T 1_{B_x(a)} \) for all \( x \). If \( F \) is a measurable set and if we denote 
\[ Z(F) \text{ the set of } z \in Z \text{ such that } B_z \cap F \neq \emptyset \text{ then for any } f \in L^2(X) \text{ we have} \]
\[ \| 1_F T f \|^2 \leq \sum_{z \in Z(F)} \| 1_{B_x} T f \|^2 = \sum_{z \in Z(F)} \| 1_{B_x} T 1_{B_x(a)} f \|^2 \leq \]
\[ \sup_{z \in Z(F)} \| 1_{B_x} T \|^2 \sum_{z \in Z(F)} \| 1_{B_x(a)} f \|^2 \leq \sup_{z \in Z(F)} \| 1_{B_x} T \|^2 \sup_{z \in Z(F)} \| 1_{B_x(a)} \| \| f \|^2 \]

so \( \| 1_F T \| \leq N(a)^{1/2} \sup_{z \in Z(F)} \| 1_{B_x} T \| \). Thus for any controlled operator we have \( \inf_{F \in \mathcal{E}} \| 1_F T \| = 0 \) if 
\( \lim_{x \to \xi} \| 1_{B_x} T \| = 0 \). If \( T \in \mathcal{E}(X) \) this means \( T \in \mathcal{I}_x \).

**Proposition 5.5.** If \( X \) is a class \( A \) space then for any filter \( \xi \) finer than Fréchet we have \( \mathcal{I}_{\mathcal{E}(\xi)} \subset \mathcal{E}_x \). If \( \xi \) is coarse and \( T \in \mathcal{E} \) then 
\[ T \in \mathcal{I}_x \iff \lim_{x \to \xi} \| 1_{B_x} \| = 0 \iff \lim_{x \to \xi} \| 1_{B_x} T \| = 0. \] (5.32)

**Proof:** We use the same techniques as in the proof of Theorem 3.12. Let \( T \in \mathcal{E}(X) \) and let us assume 
that \( \lim_{x \to \xi} \| T 1_{B_x} \| = 0 \). Then as we saw in Section 3 we have \( (T 1_{B_x}) \| = T 1_{B_x} \) hence for conveniently chosen \( \phi \) the operator \( T \phi \in \mathcal{E}(X) \) is controlled and \( \lim_{x \to \xi} \| T \phi 1_{B_x} \| = 0 \). From Lemma 5.4 we get 
\( T \phi \in \mathcal{I}_x(X) \) which is closed, so since \( T \phi \to T \in \mathcal{E}(X) \) norm as \( \phi \to 1 \), we get \( T \in \mathcal{I}_x \).

**Remark 5.6.** The relation (5.32) is not true in general if Property A is not satisfied. Indeed, if we take 
\( \xi = \infty \) then this would mean \( \mathcal{E} = \mathcal{E}_x \), which does not hold in general.

We now seek for a more convenient description of \( \mathcal{E}_{\mathcal{E}(\xi)} \) for not coarse filters.

**Remark 5.7.** The following observations are easy to prove and will be useful below. Let \( F \) be any subset of \( X \) and let \( r, s > 0 \). Then \( F^{(r+s)} \subset (F^{(r)})^{(s)} \) and if \( 0 < r < s \) then \( F^{(s)} \subset F^{(r)} \) and \( F \subset (F^{(s)})^{(r)} \).
Proposition 5.8. Assume that (2.4) is satisfied and let $T$ be a controlled operator and $\xi$ a filter finer than the Fréchet filter. Then $\inf_{F \in \mathfrak{co}(\xi)} \|1_F T\| = 0$ if and only if $\lim_{x \to \xi} \|1_{B_x}(r) T\| = 0$ for all $r > 0$.

Proof: If $T \in \mathcal{B}(X)$ and $\inf_{F \in \mathfrak{co}(\xi)} \|1_F T\| = 0$ then the first few lines of the proof of Lemma 5.4 give $\lim_{x \to \xi} \|1_{B_x}(r) T\| = 0$ for all $r > 0$, which is more than required. Now let $T$ be a controlled operator and let us set $a = d(T) + 1$. If $F$ is a measurable set and $Z(F)$ is as in the proof of Lemma 5.4 then $d(F, Z(F)) \leq 1$ hence for any $r > 0$ we have

$$F(r) \subset Z(F)(r+1) = \bigcup_{z \in Z(F)} B_z(r+1)$$

hence for any $f \in L^2$ we have

$$\|1_{F(r)} T f\|^2 \leq \sum_{z \in Z(F)} \|1_{B_z(r+1)} T f\|^2 = \sum_{z \in Z(F)} \|1_{B_z(r+1)} T 1_{B_z(r+1)} f\|^2 \leq \sup_{z \in Z(F)} \|1_{B_z(r+1)} T\|^2 \sum_{z \in Z(F)} \|1_{B_z(r+2)} f\|^2 \leq \sup_{z \in F(r)} \|1_{B_z(r+1)} T\|^2 \|N(r+1) f\|^2.$$

If $x \in F(r)$ and $y \in F$ is such that $d(x, y) \leq 1$ then $B_x(r+1) \subset B_y(r+2)$ hence we obtain

$$\|1_{F(r)} T\| \leq N(r+1)^{1/2} \sup_{x \in F} \|1_{B_x(r+2)} T\| \leq N(r+1)^{1/2} \sup_{x \in F} \|1_{B_x(r+2)} T\| \leq \sup_{x \in X} \|1_{G \cap B_x T}\|.$$

Observe also that for an arbitrary measurable set $G$ we have the estimate

$$\|1_G T\| \leq N(a)^{1/2} \sup_{x \in X} \|1_{G \cap B_x T}\|.$$

This follows from Lemma 3.6 after noticing that $d(1_G T) \leq d(T)$.

Now assume that $\lim_{x \to \xi} \|1_{B_x}(r) T\| = 0$ for all $r > 0$ and let us fix $\varepsilon > 0$. Then for each $r > 0$ there is $F^r \in \xi$ such that

$$\|1_{B_x(r+2)} T\| \leq \varepsilon N(r+1)^{-1/2}N(a)^{-1/2} \quad \forall x \in F^r.$$

For each $f \in L^2$ and each number $s > 0$ the map $x \mapsto 1_{B_x(s)} f \in L^2$ is strongly continuous, hence the function $x \mapsto \|1_{B_x(s)} T f\|$ is lower semi-continuous, so we may assume that $F^r$ is closed, hence measurable. Then the $G^r := F^r \cap \xi$ is closed and $\|1_{G^r} T\| \leq N(a)^{-1/2}$ because of (5.33). Moreover, if $\alpha < r$ then $G^r(\alpha) = (G^r)(\alpha) \cap F^r$ hence $G^r(\alpha) \in \xi$. Now fix $\alpha > 1$ and let $G = \bigcup_{r > \alpha} G^r(\alpha)$. This is a union of open set hence it is open and contains all the $G^r(\alpha)$, which belong to $\xi$, hence belongs to $\xi$. If $s > 0$ and we choose some $r > s + \alpha$ then $G^s(\alpha)(\alpha) \supset G^s(\alpha)(\beta) \cap G^s(\alpha)(\gamma) \in \xi$ (Remark 5.7). Thus we see that $G^s(\alpha) \in \xi$ for all $s > 0$, which means that $G \in \mathfrak{co}(\xi)$. In order to estimate the norm of $1_{G} T$ we use (5.34) and observe that if $G \cap B_x \neq \emptyset$ the there is $r > \alpha$ such that $G^r(\alpha) \cap B_x \neq \emptyset$ hence $B_x \subset (G^r(\alpha))(1)$. But it is easy to check that $(G^r(\alpha))(1) \subset G_r$ because $\alpha > 1$, hence $B_x \subset G_r$, and then

$$\|1_{G \cap B_x} T\| \leq \|1_{B_x} T\| \leq \|1_{G} T\| \leq \varepsilon N(a)^{-1/2}.$$

Finally, from (5.34) we get $\|1_G T\| \leq \varepsilon$.

\[\square\]

Theorem 5.9. Let $X$ be a class $A$ space and let $\xi$ be a filter finer than Fréchet on $X$. If $T \in \mathcal{E}$ then:

$$T \in \mathcal{F}_{co(\xi)} \iff \lim_{x \to \xi} \|1_{B_x}(r) T\| = 0 \quad \forall r > 0 \iff \lim_{x \to \xi} \|1_{B_x}(r) T\| = 0 \quad \forall r > 0. \quad (5.35)$$

Proof: This is a repetition of the proof of Proposition 5.5. For example, let $\lim_{x \to \xi} \|1_{B_x}(r) T\| = 0$ for all $r > 0$. Since $1_{B_x(r+1)} T \in \mathcal{E}(X)$ is controlled and $\lim_{x \to \xi} \|1_{B_x(r+1)} T\| = 0$ for all $r$. From Proposition 5.8 we clearly get $T \in \mathcal{F}_{co(\xi)}$ which is closed. So $T \in \mathcal{F}_{co(\xi)}$ because $T \in \mathcal{E}$ in norm as $T \to 1$. 

The ideals of $\mathcal{E}(X)$ which are of real interest in our context are defined as follows

$$\mathcal{N} \in \mathcal{E}(X) \Rightarrow \mathcal{N}(\mathcal{N}) := \mathcal{F}_{co(\mathcal{N})}(X) := \{T \in \mathcal{E}(X) \mid \inf_{F \in \mathcal{N}(\mathcal{N})} \|1_F T\| = 0\}. \quad (5.36)$$
By Proposition 5.3 this can be expressed in terms of the ideals of $\mathcal{C}(X)$ introduced in (4.25) as follows:

$$\mathcal{B}(\mathcal{C}(X)) = \mathcal{B}(\mathcal{C}(X)) \mathcal{B}(X) = \mathcal{B}(X) \mathcal{C}(\mathcal{C}(X)),$$

(5.37)

**Proof of Theorem 2.5:** Assume that $T \in \mathcal{B}(\mathcal{C}(X))$ for all $x \in \mathcal{C}(X)$; we have to show that $T$ is a compact operator (the converse being obvious). If $x \in \mathcal{C}(X)$ and $r > 0$ then for any $\varepsilon > 0$ there is $F \in \text{co}(\mathcal{C}(X))$ such that $\|1_F T\| < \varepsilon$ and there is $G \in \mathcal{C}(X)$ such that $G \subseteq F$, hence for any $x \in G$ we have $\|1_x T\| < \varepsilon$. This proves that $\lim_{x \to \infty} \|1_x T\| = 0$. Now define $\theta(x) = \|1_x T\|$, we obtain a bounded function on $X$ such that $\lim_{x \to \infty} \theta(x) = 0$ for any $x \in \mathcal{C}(X)$. The continuous extension $\beta(\theta) : \beta(\mathcal{C}(X)) \to \mathbb{R}$ has the property $\beta(\theta)(x) = \lim_{x \to \infty} \theta(x)$ thus $\beta(\theta)$ is zero on the compact subset $\mathcal{C}(X)$ of $\beta(\mathcal{C}(X))$ hence we have $\lim_{x \to \infty} \theta(x) = 0$ according to a remark from Section 4.1. Thus we have $\lim_{x \to \infty} \|1_{B_x(r)} T\| = 0$, which means that $T$ belongs to the ghost ideal $\mathcal{G}$. Now the compactness of $T$ follows from Theorem 3.12.

We end this section with some remarks on the case of discrete spaces with bounded geometry. Assume that $X$ is an infinite set equipped with a metric $d$ such that the number of points in a ball is bounded by a number independent of the center of the ball. We equip $X$ with the counting measure, so $L^2(X) = l^2(X)$, and embed $X \subseteq l_2(X)$ by identifying $x = 1_x \equiv 1_x$. Then any operator $T \in \mathcal{B}(X)$ has a kernel $k_T(x, y) = x(T y)$ and $\mathcal{B}(X)$ is the closure of $X$ such that $(x(T y)) = 0$ if $d(x, y) > r(T)$ (this is the uniform Roe algebra). Observe that for each $T \in \mathcal{B}$ and each $\varepsilon > 0$ there is an $r$ such that $\langle x | T y \rangle < \varepsilon$ if $d(x, y) > r$. If $\xi$ is a filter on $X$ and $f : X \to \mathbb{C}$ we write $\lim_{x \to \xi} f(x, y) = 0$ if for each $\varepsilon > 0$ there is $F \in \xi$ such that $|f(x, y)| < \varepsilon$ if $x, y \in F$.

**Proposition 5.10.** Let $X$ be discrete with bounded geometry. Then if $\xi$ is a filter and $T \in \mathcal{B}$ we have

$$T \in \mathcal{G}_\xi \iff \lim_{x \to \xi} \sup_{y, z \in B_x(r)} |\langle y | T z \rangle| = 0 \quad \forall r > 0.$$

(5.38)

Moreover, if $\xi$ is coarse then

$$\mathcal{G}_\xi = \{ T \in \mathcal{B} \mid \lim_{x \to \xi} \langle x | T y \rangle = 0 \}.$$

(5.39)

**Proof:** By definition, we have $T \in \mathcal{G}_\xi$ if and only if $\lim_{x \to \xi} \|T 1_{B_x(r)}\| = 0$ for all $r$. Since the norm of the operator $T 1_y$ is equal to the norm of the vector $T y$, we have

$$\sup_{y \in B_x(r)} \|T y\| \leq \|T 1_{B_x(r)}\| \leq \sum_{z \in B_x(r)} \|T y\| \leq V(r) \sup_{y \in B_x(r)} \|T y\|.$$  

Thus $T \in \mathcal{G}_\xi$ if and only if $\lim_{x \to \xi} \sup_{y \in B_x(r)} \|T y\| = 0$ for all $r$, in particular the property from the right hand side of (5.38) is satisfied. Conversely, let $T \in \mathcal{B}$ satisfying this condition and let $\varepsilon > 0$. Choose an operator $S$ such that $\|S - T\| < \varepsilon$ and such that $(x | S y) = 0$ if $d(x, y) > R$ for some fixed $R$. Then we have $|\langle S y | a \rangle| \leq \sum_z |\langle S y | z \rangle| |\langle z | a \rangle| \leq \|S\| \|S\| \sum_{z \in B_y(R)} \|\langle z | T y \rangle\| \leq \varepsilon \|T\| + \|S\| \|S\| \sum_{z \in B_y(R)} \|\langle z | T y \rangle\|$

So for each $\varepsilon > 0$ there are $C, R < \infty$ with $\|T y\|^2 \leq \varepsilon \|T\|^2 + C \|z\| \|T y\|$ for all $y$. Hence:

$$\sup_{y \in B_x(r)} \|T y\|^2 \leq \varepsilon \|T\|^2 + C \{ \langle z \rangle \mid y \in B_x(r), z \in B_y(R) \}$

$$\leq \varepsilon \|T\|^2 + C \sup_{y, z \in B_x(r)} \|z\| \leq \varepsilon \|T\| \varepsilon.$$  

This proves the converse implication in (5.38).

Now assume that $\xi$ is coarse. If $T$ is as in the right hand side of (5.39) then for each $\varepsilon > 0$ there is $F \in \xi$ such that $|\langle y | T z \rangle| < \varepsilon$ if $y, z \in F$ and for each $r$ there is $G \in \xi$ such that $G \subseteq F$. Then if $y \in G$ we have $B_y(r) \subseteq F$ hence $\sup_{y, z \in B_x(r)} |\langle y | T z \rangle| < \varepsilon$ so $T \in \mathcal{G}_\xi$ by (5.38). Reciprocally, let $T \in \mathcal{G}_\xi$ and let $\varepsilon, r > 0$. 
By (5.38), there is $F \in \xi$ such that if $y, z \in B_{r}(r)$ for some $x \in F$ then $|\langle y|Tz\rangle| \leq \varepsilon$. Let us choose $r$ such that $|\langle y|Tz\rangle| < \varepsilon$ if $d(y, z) > r$ and let $G \in \xi$ such that $G_{(r)} \subset F$. If $y, z \in G$ then either $d(y, z) > r$ and then $|\langle y|Tz\rangle| < \varepsilon$, or $d(y, z) \leq r$ and then $|\langle y|Tz\rangle| < \varepsilon$ because $y, z \in B_{r}(r)$ and $y, z \in G \subset F$. Thus we found $G \in \xi$ such that $|\langle y|Tz\rangle| < \varepsilon$ if $y, z \in G$.

Finally, for the convenience of the reader we summarize the construction of the ghost projection of Higson, Laforgue, and Skandalis. Note that $\mathcal{G}(X)$ is a $C^{*}$-algebra of operators on $L_{2}(X)$ independent of the metric of $X$. Assume that $X$ is a disjoint union of finite sets $X_{n}$ with $1 \leq n \leq \infty$ such that the number $v_{n}^{2}$ of elements of $X_{n}$ tends to infinity with $n$. Then $L_{2}(X) = \bigoplus_{n}L_{2}(X_{n})$, the vector $e_{n} = \sum_{x \in X_{n}}x/v_{n}$ is a unit vector in $L_{2}(X_{n})$, and $\pi := \sum_{n}|e_{n}\rangle\langle e_{n}|$ is an orthogonal projection in $L_{2}(X)$ such that $\langle x|\pi y \rangle = 0$ if $x, y$ belong to different sets $X_{n}$ and $\langle x|\pi y \rangle = v_{n}^{2}$ if $x, y \in X_{n}$. Thus $\pi$ is an infinite rank projection and $\pi \in \mathcal{G}(X)$. All this is easy, but the choice of the metric is not: see page 348 in [HLS].

6. **Locally compact groups**

6.1. **Crossed products.** In this section we assume that $X$ is a locally compact topological group with neutral element $e$ and $\mu$ is a left Haar measure. We write $d\mu(x) = dx$ and denote $\Delta$ the modular function defined by $d(\gamma y) = \Delta(\gamma)dx$ or $dx^{-1} = \Delta(x)^{-1}dx$ (with slightly formal notations). There are left and right actions of $X$ on functions $\varphi$ defined on $X$ given by $(a.\varphi)(x) = \varphi(a^{-1}x)$ and $(\varphi.a)(x) = \varphi(ax)$.

The left and right regular representation of $X$ are defined by $\lambda_{a}f = a.f$ and $\rho_{a}f = \sqrt{\Delta(a)}f.a$ for $f \in L^{2}(X)$. Then $\lambda_{a}$ and $\rho_{a}$ are unitary operators on $L^{2}(X)$ which induce unitary representation of $X$ on $L^{2}(X)$. These representations commute: $\lambda_{a}\rho_{b} = \rho_{b}\lambda_{a}$ for all $a, b \in X$. Moreover, for $\varphi \in L^{\infty}(X)$ we have $\lambda_{a}\varphi(Q)\lambda_{a}^{-1} = (a.\varphi)(Q)$ and $\rho_{a}\varphi(Q)\rho_{a}^{-1} = (\varphi.a)(Q)$.

The convolution of two functions $f, g$ on $X$ is defined by

$$(f * g)(x) = \int f(y)g(\gamma^{-1}x)dy = \int f(xy^{-1})\Delta(y)^{-1}g(y)dy.$$  

For $\psi \in L^{1}(X)$ let $\lambda_{\psi} = \int \psi(y)\lambda_{y}dy \in \mathcal{B}(X)$. Then $\|\lambda_{\psi}\| \leq \|\psi\|_{L^{1}}$ and $\psi * g = \lambda_{\psi}g$ for $g \in L^{2}$.

We recall the definition of the $*$-algebra $L^{1}(X)$: the product is the convolution product $f * g$ and the involution is given by $f^{*}(x) = \Delta(x)^{-1}\tilde{f}(x^{-1})$; the factor $\Delta^{-1}$ ensures that $\|f^{*}\|_{L^{1}} = \|f\|_{L^{1}}$. The enveloping $C^{*}$-algebra of $L^{1}(G)$ is the group $C^{*}$-algebra $C^{*}(X)$. The norm closure in $\mathcal{B}(X)$ of the set of operators $\lambda_{\psi}$ with $\psi \in L^{1}(X)$ is the reduced group $C^{*}$-algebra $C_{r}^{*}(X)$. There is a canonical surjective morphism $C^{*}(X) \to C_{r}^{*}(X)$ which is injective if and only if $X$ is amenable.

**Lemma 6.1.** If $T \in C_{r}^{*}(X)$ then $\rho_{a}T = T\rho_{a}$ for $a \in X$. If $X$ is not compact then $C_{r}^{*}(X) \cap \mathcal{K}(X) = \{0\}$.

**Proof:** The first assertion is clear because $\rho_{a}\lambda_{b} = \lambda_{b}\rho_{a}$. If $X$ is not compact, then $\rho_{a} \to 0$ weakly on $L^{2}(X)$ hence if $T \in C_{r}^{*}(X)$ is compact $\|Tf\| = \|T\rho_{a}f\| \to 0$ hence $\|Tf\| = 0$ for all $f \in L^{2}(X)$.

In what follows by uniform continuity we mean “right uniform continuity”, so $\varphi : X \to \mathbb{C}$ is uniformly continuous if for any $\varepsilon > 0$ there is a neighborhood $V$ of $e$ such that $xy^{-1} \in V \Rightarrow |\varphi(x) - \varphi(y)| < \varepsilon$ (see page 60 in [RS]). Let $C(X)$ be the $C^{*}$-algebra of bounded uniformly continuous complex functions. If $\varphi : X \to \mathbb{C}$ is bounded measurable then $\varphi \in C(X)$ if and only if $\|\lambda_{a}\varphi(Q)\lambda_{a}^{-1} - \varphi(Q)\| \to 0$ as $a \to e$.

We consider now crossed products of the form $A \rtimes X$ where $A \subset C(X)$ is a $C^{*}$-subalgebra stable under (left) translations (so $a.\phi \in A$ if $\phi \in A$; only the case $A = C(X)$ is of interest later). We refer to [Wil] for generalities on crossed products. The $C^{*}$-algebra $A \rtimes X$ is the enveloping $C^{*}$-algebra of the Banach $*$-algebra $L^{1}(X; A)$, where the algebraic operations are defined as follows:

$$(f * g)(x) = \int f(y)g(\gamma^{-1}x)dy, \quad f^{*}(x) = \Delta(x)^{-1}x\tilde{f}(x^{-1}).$$
Thus $C^*(X) = \mathbb{C} \times X$. If we define $\Lambda : L^1(X; \mathcal{A}) \to \mathcal{B}(X)$ by $\Lambda(\phi) = \int \phi(a) \lambda_y da$ it is easy to check that this is a continuous $*$-morphism hence it extends uniquely to a morphism $\mathcal{A} \times X \to \mathcal{B}(X)$ for which we keep the same notation $\Lambda$. A short computation gives for $\phi \in C_c(X; \mathcal{A})$ and $f \in L^2(X)$

$$\Lambda(\phi)(f)(x) = \int \phi(x, xy^{-1}) \Delta(y)^{-1} f(y) dy$$

where for an element $\phi \in C_c(X; \mathcal{A})$ we set $\phi(x, a) = \phi(a)(x)$. Thus $\Lambda(\phi)$ is an integral operator with kernel $k(x, y) = \phi(x, xy^{-1}) \Delta(y)^{-1}$ or $\Lambda(\phi) = Op(k)$ with our previous notation.

The next simple characterization of $\Lambda$ follows from the density in $C_c(X; \mathcal{A})$ of the algebraic tensor product $\mathcal{A} \otimes_{a alg} C_c(X)$: there is a unique morphism $\Lambda : \mathcal{A} \times X \to \mathcal{B}(X)$ such that $\Lambda(\phi \otimes \psi) = \varphi(Q) \lambda_\psi$ for $\varphi \in \mathcal{A}$ and $\psi \in C_c(X)$. Here we take $\phi = \varphi \otimes \psi$ with $\varphi \in \mathcal{A}$ and $\psi \in C_c(X)$, so $\phi(a) = \varphi \psi(a)$. Note that the kernel of the operator $\varphi(Q) \lambda_\psi$ is $k(x, y) = \varphi(x) \psi(xy^{-1}) \Delta(y)^{-1}$.

The reduced crossed product $\mathcal{A} \rtimes_r X$ is a quotient of the full crossed product $\mathcal{A} \rtimes X$ in the precise definition is of no interest here. Below we give a description of it which is more convenient in our setting. As usual, we embed $\mathcal{A} \subset \mathcal{B}(X)$ by identifying $\varphi = \varphi(Q)$ and if $\mathcal{M}, \mathcal{N}$ are subspaces of $\mathcal{B}(X)$ then $\mathcal{M} \cdot \mathcal{N}$ is the closed linear subspace generated by the operators $MN$ with $M \in \mathcal{M}$ and $N \in \mathcal{N}$.

**Theorem 6.2.** The kernel of $\Lambda$ is equal to that of $\mathcal{A} \rtimes X \to \mathcal{A} \rtimes_r X$, hence $\Lambda$ induces a canonical embedding $\mathcal{A} \rtimes_r X \subset \mathcal{B}(X)$ whose range is $\mathcal{A} \cdot C^*_r(X)$. This allows us to identify $\mathcal{A} \rtimes_r X = \mathcal{A} \cdot C^*_r(X)$.

We thank Georges Skandalis for showing us that this is an easy consequence of results from the thesis of Athina Magare. Indeed, it suffices to take $A = A$ and $B = C_0(X)$ in [Mag, Proposition 1.3.12] by taking into account that the multiplier algebra of $C_0(X)$ is $C_0(X)$, and then to use $C_0(X) \rtimes X = \mathcal{M}(X)$ (Takai’s theorem, cf. [Mag, Example 1.3.4]) and the fact that the multiplier algebra of $\mathcal{M}(X)$ is $\mathcal{B}(X)$.

The crossed product of interest here is $\mathcal{C} \rtimes_r X \subset \mathcal{B}(X)$ (see Definition 3.3 here and [GI3, page 447]) is defined by the family of seminorms of the form $\|T\|_\Lambda = \|1_T T\| + \|T 1_A\|$ with $\Lambda \subset C$ compact.

The following is an extension of [GI3, Proposition 5.9] in the present context (see also pages 30–31 in the preprint version of [GI1] and [Ro2]). Recall that any bounded function $\varphi : X \to \mathbb{C}$ extends to a continuous function $\beta(\varphi)$ on $\beta(X)$. If $\varepsilon \in \beta(X)$ we define $\varphi_{\varepsilon} : X \to \mathbb{C}$ by

$$\varphi_{\varepsilon}(x) = \beta(x^{-1}) \varphi(\varepsilon) = \lim_{a \to \varepsilon} \varphi(ax). \tag{6.40}$$

**Lemma 6.3.** If $\varphi \in C(X)$ then for any $\theta \in C_c(X)$ the set $\{\theta \varphi_{a} \mid a \in X\}$ is relatively compact in $C_c(X)$ and the map $a \mapsto \theta \varphi_{a}$ in $C_c(X)$ is norm continuous. In particular, for any $\varepsilon \in \beta(X)$ the limit in (6.40) exists locally uniformly in $x$ and we have $\varphi_{\varepsilon} \in C(X)$.

**Proof:** By the Ascoli-Arzel\`a theorem, to show the relative compactness of the set of functions of the form $\theta \varphi_{a}$ it suffices to show that the set is equicontinuous. For each $\varepsilon > 0$ there is a neighborhood $V$ of $e$ such that $|\varphi(x) - \varphi(y)| < \varepsilon$ if $xy^{-1} \in V$. Then $|\varphi(ax) - \varphi(ay)| < \varepsilon$ for all $a \in X$, which proves the assertion. In particular, $\lim_{a \to \varepsilon} \varphi_{a}$ exists in norm in $C_c(X)$, hence the limit in (6.40) exists locally uniformly in $x$. Moreover, we shall have $|\varphi_{\varepsilon}(x) - \varphi_{\varepsilon}(y)| < \varepsilon$ so $\varphi_{\varepsilon}$ belongs to $C(X)$. Finally, we show that for any compact set $K$ and any $\varepsilon > 0$ there is a neighborhood $V$ of $e$ such that $\sup_{x \in X} |\varphi(xa) - \varphi(x)| < \varepsilon$ for all $a \in V$. For this, let $U$ be an open cover of $K$ such that the oscillation of $\varphi$ over any $U \in U$ is $< \varepsilon$ and note that there is an neighborhood $V$ of $e$ such that for any $x \in K$ there is $U \in U$ such that $xV \subset U$ (use the Lebesgue property for the left uniform structure).

**Proposition 6.4.** For each $T \in C(X) \rtimes_r X$ and each $a \in X$ we have $\tau_a(T) := \rho_a T \rho_a^* \in C(X) \rtimes_r X$ and the map $a \mapsto \tau_a(T)$ is locally continuous on $X$ and has locally relatively compact range. For each ultrafilter
\( x \in \beta(X) \) and each \( T \in \mathcal{C}(X) \times \tau \), \( X \) the limit \( \tau_{\omega}(T) := \lim_{\omega \to \tau} \tau_{a}(T) \) exists in the local topology of \( \mathcal{C}(X) \times \tau \), \( X \). The so defined map \( \tau_{\omega} : \mathcal{C}(X) \times \tau \to \mathcal{C}(X) \times \tau \) is a morphism uniquely determined by the property \( \tau_{\omega}(\varphi(Q)\lambda_{\psi}) = \varphi_{\omega}(Q)\lambda_{\psi} \).

**Proof:** If \( T = \varphi(Q)\lambda_{\psi} \) then \( \rho_{a}T\rho_{a}^{*} = (\varphi(a))(Q)\lambda_{\psi} \) is an element of \( \mathcal{C}(X) \times \tau \) and so \( \tau_{a} \) is an automorphism of \( \mathcal{C}(X) \times \tau \). If we take \( \psi \) with compact support and \( \Lambda \) is a compact set then \( \lambda_{\psi}\Lambda_{1} = 1_k\lambda_{\psi}\Lambda \) where \( K = (supp\psi)\Lambda \) is also compact. Then \( \tau_{a}(T)\Lambda_{1} = (\varphi(a))(Q)1_{K}\lambda_{\psi}\Lambda_{1} \) and the map \( a \mapsto (\varphi(a))(Q)1_{K} \) is norm continuous, cf. Lemma 6.3. This implies that \( a \mapsto \tau_{a}(T) \) is locally continuous on \( X \) for any \( T \). To show that the range is relatively compact, it suffices again to consider the case \( T = \varphi(Q)\lambda_{\psi} \) with \( \psi \) with compact support and to use \( \tau_{a}(T)\Lambda_{1} = (\varphi(a))(Q)1_{K}\lambda_{\psi}\Lambda_{1} \) and the relative compactness of the \( \{(\varphi(a))(Q)1_{K} \mid a \in X \} \) established in Lemma 6.3. The other assertions of the proposition follow easily from these facts.

6.2. **Elliptic \( C^{*} \)-algebra.** Let \( X \) be a locally compact non-compact topological group. Since we do not require that \( X \) be metrizable, we have to adapt some of the notions used in the metric case to this context. Of course, we could use the more general framework of coarse spaces [Ro1] to cover both situations, but we think that the case of metric groups is already sufficiently general. So the reader may assume that \( X \) is equipped with an invariant proper distance \( d \). Our leftist bias in Section 6.1 forces us to take \( d \) right invariant, i.e. \( d(x, y) = d(xz, yz) \) for all \( x, y, z \). If we set \( |x| = d(x, e) \) then we get a function \( | \cdot | \) on \( X \) such that \( |x^{-1}| = |x|, |xy| \leq |x| + |y|, \) and \( d(x, y) = |xy^{-1}| \). The balls \( B(r) \) defined by relations of the form \( |x| \leq r \) are a basis of compact neighborhoods of \( e \), a function on \( X \) is \( d \)-uniformly continuous if and only if it is right uniformly continuous, etc.

Note that \( B_{x}(r) = B(r)x \) so in the non-metrizable case the role of the balls \( B_{x}(r) \) is played by the sets \( V_{x} \) with \( V \) compact neighborhoods of \( e \). Recall that the range of the modular function \( \Delta \) is a subgroup of the multiplicative group \([0, \infty[ \) hence it is either \( \{ 1 \} \) or unbounded. Since \( \mu(Vx) = \mu(V)\Delta(x) \) our assumption (2.3) is satisfied only if \( X \) is unimodular and in this case we have \( \mu(Vx) = \mu(V) \) for all \( x \).

We emphasize the importance of the condition that the metric be proper. Fortunately, it has been proved in [HP] that a locally compact group is second countable if and only if its topology is generated by a proper right invariant metric.

For coherence, in the non metrizable case we are forced to say that a kernel \( k : X^{2} \to \mathbb{C} \) is controlled if there is a compact set \( K \subset X \) such that \( k(x, y) = 0 \) if \( xy^{-1} \notin K \). The symbol \( d(k) \) should be defined now as the smallest compact set \( K \) with the preceding property. On the other hand, \( k \) is uniformly continuous if it is right uniformly continuous, i.e. if for any \( \varepsilon > 0 \) there is a neighborhood \( V \) of \( e \) such that \( |k(ax, by) - k(x, y)| < \varepsilon \) for all \( a, b \in V \) and \( x, y \in X \). Then the Schur estimate (3.15) gives \( ||Op(k)|| \leq sup |k| sup_{a} \mu(Ka) \) so only if \( X \) is unimodular we have a simple estimate \( ||Op(k)|| \leq \mu(K) ||k|| \).

To summarize, if \( X \) is unimodular then \( C_{un}(X^{2}) \) is well defined and Lemma 3.1 remains valid if we set \( V(d(k)) = \mu(d(k)) \) so we may define the elliptic algebra \( \mathcal{E}(X) \) as in (2.5). But in fact, what we get is just a description of the crossed product \( C(X) \rtimes \tau X \) independent of the group structure of \( X \):

**Proposition 6.5.** If \( X \) is unimodular then \( \mathcal{E}(X) = \mathcal{C}(X) \times \tau X = \mathcal{C}(X) \cdot C^{*}(X) \).

**Proof:** From the results presented in Section 6.1 and the fact that \( \Delta = 1 = \tau \) we get that \( \mathcal{C}(X) \times \tau X \) is the closed linear space generated by the operators \( Op(k) \) with kernels \( k(x, y) = \varphi(x)\psi(xy^{-1}) \), where \( \varphi \in \mathcal{C}(X) \) and \( \psi \in \mathcal{C}_{c}(X) \). Thus \( \mathcal{C}(X) \times \tau X \subset \mathcal{E}(X) \). To show the converse, let \( k \in \mathcal{C}_{un}(X^{2}) \) and let \( \tilde{k}(x, y) = k(x, xy^{-1}) \) hence \( k(x, y) = \tilde{k}(x, xy^{-1}) \). If \( K = K^{-1} \subset X \) is a compact set such that \( k(x, y) \neq 0 \Rightarrow xy^{-1} \in K \) then \( sup \tilde{k} \subset X \times K \). Fix \( \varepsilon > 0 \) and let \( V \) be a neighborhood of the origin such that \( |\tilde{k}(x, y) - \tilde{k}(x, z)| < \varepsilon \) if \( yz^{-1} \in V \). Then let \( Z \subset K \) be a finite set such that \( K \subset \bigcup_{z \in Z} Vz \) and let \( \{ \theta_{z} \} \) be a partition of unity subordinated to this covering. If \( \tilde{l}(x, y) = \sum_{z \in Z} \tilde{k}(x, z)\theta_{z}(y) \) or \( \tilde{l}(x, y) = \sum_{z \in Z} \tilde{k}(x, z)\theta_{z}(y) \leq \varepsilon \),

\[
|\tilde{k}(x, y) - \tilde{l}(x, y)| = \sum_{z \in Z} |(\tilde{k}(x, y) - \tilde{k}(x, z))\theta_{z}(y)| \leq \sum_{z \in Z} |(\tilde{k}(x, y) - \tilde{k}(x, z))\theta_{z}(y)| \leq \varepsilon
\]
because \(\text{supp} \theta_z \subset V_z\). Now let us set \(l(x, y) = \overline{l}(x, xy^{-1}) = \sum_{z \in Z} k(x, z) \theta_z(xy^{-1}).\) If \(l(x, y) \neq 0\) then \(\theta_z(xy^{-1}) \neq 0\) for some \(z\) hence \(xy^{-1} \in V_z \subset VK\). In this construction we may choose \(V \subset U\) where \(U\) is a fixed compact neighborhood of the origin. Then we will have \(l(x, y) \neq 0 \Rightarrow xy^{-1} \in UK\) which is a compact set independent of \(l\) and from (3.16) we get \(\|Op(k) - Op(l)\| \leq C \sup |k - l| \leq C\varepsilon\) for some constant \(C\) independent of \(\varepsilon\). But clearly \(Op(l) \in \mathcal{C}(X) \times_{\tau} X\).

Thus if \(X\) is a unimodular group then we may apply Proposition 6.4 and get endomorphisms \(\tau_{\varepsilon}\) of \(\mathcal{B}(X)\) indexed by \(\varepsilon \in \delta(X)\). These will play an important role in the next subsection.

We make now some comments on the relation between amenability and Property A in the case of groups. First, the Property A is much more general than amenability, cf. the discussion in [NY] for the case of discrete groups. To show that amenability implies Property A we choose from the numerous known equivalent descriptions that is most convenient in our context [Pat, page 128]: \(X\) is amenable if and only if for any \(\varepsilon > 0\) and any compact subset \(K\) of \(X\) there is a positive function \(\varphi \in C_c(X)\) with \(\|\varphi\| = 1\) such that \(\|\rho_a \varphi - \varphi\| < \varepsilon\) for all \(a \in K\). Now let us set \(\phi(x) = \rho^*_a \varphi\), so \(\phi(x)(z) = \Delta(x)^{-1/2} \varphi(z x^{-1})\). We get a strongly continuous function \(\phi : L^2(X) \to \mathcal{L}(X)\) such that \(\|\phi(x)\| = 1\), \(\sup \text{supp} \phi(x) = (\sup \text{supp} \varphi)x\), and \(\|\phi(x) - \phi(y)\| = \|\rho_{xy^{-1}} \varphi - \varphi\| \leq \varepsilon\) if \(xy^{-1} \in K\). In the metric case we get a function as in Definition 2.1, so the metric version of the Property A is satisfied.

6.3. Coarse filters in groups. A filter \(\xi\) on a locally compact non-compact group \(X\) is called round if the sets of the form \(V G = \{xy \mid x \in V, y \in G\}\), where \(V\) runs over the set of neighborhoods of \(e\) and \(G\) over \(\xi\), are a basis of \(\xi\). And \(\xi\) is (left) invariant if \(x \in X, F \in \xi \Rightarrow x F \in \xi\). Naturally, \(\xi\) is coarse if for any \(F \in \xi\) and any compact set \(K \subset X\) there is \(G \in \xi\) such that \(K G \subset F\).

The simplicity of the next proof owes much to a discussion with H. Rugh. In our initial argument Proposition 6.6 was a corollary of Proposition 4.5.

Proposition 6.6. A filter \(\xi\) is coarse if and only if it is round and invariant.

Proof: Note first that \(\xi\) is invariant if and only if for each \(H \subset \xi\) and each finite \(N \subset X\) there is \(G \in \xi\) such that \(H \supset NG\). This is clear because \(NG \subset H\) is equivalent to \(G \subset \bigcap_{\alpha \in N} x^{-1} H\). Now assume that \(\xi\) is also round. Then for any \(F \in \xi\) there is a neighborhood \(V\) of \(e\) and a set \(H \subset \xi\) such that \(F \subset VH\). If \(K\) is any compact set then there is a finite set \(N\) such that \(VN \supset K\). Then there is \(G \in \xi\) such that \(H \supset NG\). So \(F \subset VNG \supset KH\).

Proposition 6.7. Let \(X\) be unimodular and let \(\xi\) be a coarse filter. Then for any \(T \in \mathcal{F}(\xi)\) we have \(\lim_{a \to \xi} \tau_a(T) = 0\) locally. If \(X\) is amenable then the converse assertion holds, so

\[
\mathcal{F}(\xi) = \{T \in \mathcal{B}(X) \mid \lim_{a \to \xi} \tau_a(T) = 0\ \text{locally}\} = \{T \in \mathcal{B}(X) \mid \tau_\varepsilon(T) = 0 \forall \varepsilon \in \xi^\dagger\}. 
\]

Moreover, if \(X\) is amenable then for any compact neighborhood \(V\) of \(e\) and any \(T \in \mathcal{B}(X)\) we have:

\[
T \in \mathcal{F}(\xi) \Leftrightarrow \lim_{a \to \xi} \|T 1_{V a}\| = 0 \Leftrightarrow \lim_{a \to \xi} \|\tau_a(T) 1_V\| = 0
\]

Proof: We have \(1_{V a}(Q) = \rho^*_a 1_{V}(Q)\rho_a\) hence \(\|T 1_{V a}\| = \|T \rho^*_a 1_{V}(Q)\rho_a\| = \|\tau_a(T) 1_{V}(Q)\|\) hence for \(T \in \mathcal{F}(\xi)\) we have \(\lim_{a \to \xi} \tau_a(T) = 0\) locally. If \(X\) is amenable then Proposition 5.5 in the metric case and a suitable modification in the non-metrizable group case gives (6.41). Then (6.42) is easy.

Theorem 6.8. Let \(X\) be a unimodular amenable locally compact group. Then for each \(\varepsilon \in \delta(X)\) and for each \(T \in \mathcal{B}(X)\) the limit \(\tau_\varepsilon(T) := \lim_{a \to \xi} \rho_a T \rho^*_a\) exists in the local topology of \(\mathcal{B}(X)\), in particular in the strong operator topology of \(\mathcal{B}(X)\). The maps \(\tau_\varepsilon\) are endomorphisms of \(\mathcal{B}(X)\) and \(\tau_\varepsilon \in \mathcal{F}(\xi)\) with \(\mathcal{F}(X)\) as kernel, hence the essential spectrum of any normal operator \(H \in \mathcal{B}(X)\) or any observable \(H\) affiliated to \(\mathcal{B}(X)\) is given by \(\text{Sp}_{\text{ess}}(H) = \bigcup_{\varepsilon \in \delta(X)} \text{Sp}(\tau_\varepsilon(H))\).
Proof: We have seen in Section 4.4 that \( \bigcup_{\varepsilon \in \delta(X)} \tilde{\varepsilon} = \delta(X) \) and from (6.41) we get
\[
\mathcal{E}(\varepsilon)(x) = \bigcap_{\varepsilon \in \tilde{\varepsilon}} \ker \tau_{\varepsilon} \quad \text{for each } \varepsilon \in \delta(X).
\]
(6.43)
On the other hand, we have shown before that \( \bigcap_{\varepsilon \in \delta(X)} \mathcal{E}(\varepsilon)(X) = \mathcal{K}(X) \) is a consequence of Property A, hence of amenability.

Remark 6.9. Recall that after (2.9) we defined the localization \( \varepsilon.T \) at \( \varepsilon \in \delta(X) \) of some \( T \in \mathcal{E} \) as the quotient of \( T \) in \( \mathcal{E}_{\varepsilon} = \mathcal{E}/\mathcal{E}(\varepsilon) \). If \( T \) is normal then from (6.43) we get \( \text{Sp}(\varepsilon.T) = \bigcup_{\varepsilon \in \tilde{\varepsilon}} \text{Sp}(\tau_{\varepsilon}(T)) \) but many of the operators \( \tau_{\varepsilon}(T) \) which appear here are unitary equivalent, in particular have the same spectrum. Indeed, note that there is a natural (left) action of \( X \) on \( \beta(X) \) which leaves \( \delta(X) \) invariant and \( \tilde{\varepsilon} \) is the minimal closed invariant subset of \( \delta(X) \) which contains \( \varepsilon \). And if \( \chi \in \delta(X) \) and \( a \in X \) then by using \( a\chi = \lim_{b \to \chi} ab \) we get \( \tau_{a\chi}(T) = \rho_a \tau_{\chi}(T) \rho_a^* \).

7. Quasi-controlled operators

In this section we describe briefly other \( C^* \)-algebras of operators which are analogs of \( \mathcal{E}(X) \). We emphasize that our choice of \( \mathcal{E}(X) \) was determined by our desire to mimic the crossed product \( \mathcal{C}(X) \rtimes X \) which is a very natural object in the abelian group case, but there are of course many other possibilities. For example, we could allow bounded Borel (instead of uniformly continuous) kernels in (3.14). The \( C^* \)-algebra generated by such kernels is strictly larger than \( \mathcal{E} \) (even if we require the kernels to be continuous, see Example 7.2) but an analogue of Theorem 2.5 remains true. It is not clear to us if this algebra is really significant in applications, the set of observables affiliated to \( \mathcal{E} \) being already very large.

We now consider the \( C^* \)-algebra obtained as norm closure of the set of controlled operator. This notion has been introduced in the metric case in Section 3 but in fact it makes sense in the general framework of coarse spaces \( X \) and geometric Hilbert \( X \)-modules [Ro1]. In particular, if \( X \) is a locally compact group an operator \( T \in \mathcal{B}(X) \) is controlled if there is a compact set \( \Lambda \subset X \) such that if \( F, G \) are closed subsets of \( X \) with \( F \cap (\Lambda G) = \emptyset \) then \( 1_F T 1_G = 0 \). If \( X \) is a metric group with a metric as in Section 6.2 this is equivalent to the definition of Section 3. We denote \( \mathcal{E}(X) \) the norm closure of the set of controlled operators and we call quasi-controlled operators its elements. If \( X \) is a proper metric space this is the “standard algebra” from [Dav]. If \( X \) is a discrete metric space with bounded geometry then \( \mathcal{E}(X) = \mathcal{E}(X) \) is the “uniform Roe \( C^* \)-algebra” from [Ro1, CW1, CW2, Wa]. Clearly \( \mathcal{E}(X) \supset \mathcal{E}(X) \).

One may define analogs of the ideals \( \mathcal{J}_\varepsilon \) and \( \mathcal{G}_\varepsilon \). Indeed, form the proof of Lemma 5.1 it follows that if \( \varepsilon \) is a coarse filter on \( X \) then the set \( \mathcal{J}_{\varepsilon}(X) \) of \( T \in \mathcal{E}(X) \) such that \( \inf_{T \in \varepsilon} \|1_F T\| = 0 \) is an ideal of \( \mathcal{E}(X) \). And if \( \varepsilon \) is an arbitrary filter then the set \( \mathcal{G}_{\varepsilon}(X) \) of \( T \in \mathcal{E}(X) \) such that \( \lim_{x \to \varepsilon} \|1_{\Lambda x} T\| = 0 \) for each compact set \( \Lambda \) is also an ideal of \( \mathcal{E}(X) \). But if \( X \) is not discrete this class of ideals is too small to allow one to describe the quotient \( \mathcal{E}(X)/\mathcal{K}(X) \) even in simple cases. For example, if \( X = \mathbb{R} \) then the operators in \( \mathcal{E} \) may have an anisotropic behavior in momentum space (see Proposition 7.4 and [Gi2]).

In order to clarify the difference between \( \mathcal{E}(X) \) and \( \mathcal{E}(X) \) we consider the case when \( X \) is an abelian group. We first recall a result from [Gi3]. Let \( X^* \) be the dual group and for \( p \in X^* \) let \( \nu_p \) be the unitary operator on \( L^2(X) \) given by \( (\nu_p f)(x) = p(x)f(x) \). To any Borel function \( \psi \) on \( X^* \) we associate an operator \( \psi(P) = F\psi\mathcal{F} \) on \( L^2(X) \), where \( \mathcal{F} \) is the operator of multiplication by \( \psi \) on \( L^2(X^*) \) and \( F \) is the Fourier transformation.

Proposition 7.1. If \( X \) is an abelian group then \( \mathcal{E}(X) = \mathcal{C}(X) \rtimes X = \mathcal{C}(X) \rtimes \mathbb{R} \) is the set of operators \( T \in \mathcal{B}(X) \) such that \( \|\nu_p T \nu_p^{-1} - T\| \to 0 \) and \( \|\nu_p \mathcal{L} - T\| \to 0 \) if \( p \to e \) in \( X^* \) and \( a \to e \) in \( X \).

The equality \( \mathcal{E}(X) = \mathcal{C}(X) \rtimes X \) has been proved before in a more general setting. Proposition 7.1 gives in fact a description of the crossed product \( \mathcal{C}(X) \rtimes X \) if \( X \) is abelian. If we accept it, then we get the following easy proof of the inclusion \( \mathcal{E}(X) = \mathcal{C}(X) \rtimes X \). The operators \( \nu_p \mathcal{L} \mathcal{P}(k) \nu_p^* \) and \( \mathcal{L} \mathcal{P}(k) \) have kernels \( p(x)k(x, y)\mathcal{P}(y) = p(xy^{-1})k(x, y) \) and \( k(xa^{-1}, y) \). Hence from (3.16) we get
\[
\|\nu_p \mathcal{L} \mathcal{P}(k) \nu_p^* - \mathcal{L} \mathcal{P}(k)\| \leq \sup_{x y^{-1} \in K} |p(xy^{-1}) - 1| |k(x, y)| \mu(K)
\]
which tends to zero as \( p \to e \) in \( X^* \). Similarly \( \| (\lambda_a - 1)Op(k) \| \to 0 \) as \( a \to e \) in \( X \). Hence \( Op(k) \in C(X) \times X \) for each \( k \in C_{11}(X^2) \).

The next example shows the role played by the uniform continuity condition in the definition of \( \mathcal{E}(X) \).

**Example 7.2.** If \( X = \mathbb{R} \) then we identify \( X^* = \mathbb{R} \) by setting \( p(x) = e^{ipx} \). Then the elliptic algebra can be described in very simple terms. Indeed, if \( \lambda_a, \nu_a \) are the unitary operators on \( L^2(\mathbb{R}) \) given by \( (\lambda_a f)(x) = f(x - a) \) and \( (\nu_a f)(x) = e^{ipx} f(x) \), we have

\[
\mathcal{E}(\mathbb{R}) = \{ T \in \mathcal{B}(\mathbb{R}) \mid \| (\lambda_a - 1)T^{(x)} \| \to 0 \text{ and } \| \nu_a T \nu_a^* - T \| \to 0 \text{ as } a \to 0 \}.
\]

Here \( T^{(x)} \) means that the relation holds for \( T \) and \( T^* \). If we take \( k(x, y) = \varphi(x)\theta(x - y) \) with \( \varphi \in C(\mathbb{R}) \) and \( \theta \in C_c(\mathbb{R}) \) then \( Op(k) = \varphi(Q)\psi(P) \in \mathcal{E}(\mathbb{R}) \) with \( \psi \) the Fourier transform (conveniently normalized) of \( \theta \). The advantage now is that we can see what happens if \( \varphi \) is only bounded and continuous. Then it is easy to check that \( \varphi(Q)\psi(P) \in \mathcal{E}(\mathbb{R}) \) if and only if \( \| (\varphi(Q + a) - \varphi(Q))\psi(P) \| \to 0 \) when \( a \to 0 \). For example, if \( \varphi(x) = e^{ix^2} \) the last condition is equivalent to \( \| (e^{iQ} - 1)\psi(P) \| \to 0 \), which is equivalent to \( \psi(P) = \eta(\mathbb{R})S \) for some \( \eta \in C_c(\mathbb{R}) \) and \( S \in \mathcal{B}(\mathbb{R}) \). But then \( \psi(P) \) is compact as a norm limit of operators of the form \( \zeta(Q)\psi(P) \) with \( \zeta \in C_c(\mathbb{R}) \), which is not true if \( \psi \neq 0 \). Thus, the operator associated to a kernel of the form \( k(x, y) = e^{ix^2}\theta(x - y) \) with \( \theta \in C_c(\mathbb{R}) \) and not zero does not belong to \( \mathcal{E}(\mathbb{R}) \).

To describe \( \mathcal{E}(X) \), we need an analogue of Lemma 3.5 in the group context.

**Lemma 7.3.** Let \( \omega \) be a compact neighborhood of \( e \) and \( Z \) a maximal \( \omega \)-separated subset of \( X \) (i.e. if \( a, b \) are distinct elements of \( Z \) then \( (\omega a) \cap (\omega b) = \emptyset \)). Then for any compact set \( K \supset \omega^{-1} \omega \) we have \( KZ = X \) and for any \( a \in Z \) the number of \( z \in Z \) such that \( (Kz) \cap (Ka) \neq \emptyset \) is at most \( \mu(\omega \omega^{-1} K) / \mu(\omega) \).

**Proof:** That such maximal \( Z \) exist follows from Zorn lemma. By maximality, \( (\omega x) \cap (\omega Z) \neq \emptyset \) for any \( x \), hence \( x \in \omega^{-1} \omega Z \), so \( X = KZ \) if \( K \supset \omega^{-1} \omega \). Now fix \( a \in Z \) and let \( N \) be the number of points \( z \in Z \) such that \( (Kz) \cap (Ka) \neq \emptyset \). For each such \( z \) we have \( z \in K^{-1}Ka \) hence \( \omega z \subset \omega K^{-1} Ka \). But the sets \( \omega z \) are pairwise disjoint and have the same measure \( \mu(\omega) \) so \( N \mu(\omega) \leq \mu(\omega K^{-1} Ka) = \mu(\omega K^{-1} K) \). \( \square \)

If \( X \) is an abelian group then a \( Q \)-regular operator is an operator \( T \in \mathcal{B}(X) \) which satisfies only the first condition from Proposition 7.1, i.e. is such that the map \( p \mapsto \nu_p T \nu_p^* \) is norm continuous. These operators form a \( C^* \)-algebra which contains \( \mathcal{E}(X) \), strictly if \( X \) is not discrete, which seems to depend on the group structure of \( X \). But in fact this is not the case, it depends only on the coarse structure of \( X \).

**Proposition 7.4.** If \( X \) is an abelian group then \( \mathcal{E}(X) = \{ T \in \mathcal{B}(X) \mid \lim_{p \to e} \| \nu_p T \nu_p^* - T \| = 0 \} \).

For the proof, it suffices to use [GG2, Propositions 4.11 and 4.12] (arXiv version) and Lemma 7.3.

Now let \( L^\omega \mathcal{E}(X) \) be the set of locally compact operators in \( \mathcal{E}(X) \). Obviously \( L^\omega \mathcal{E} \) is a \( C^* \)-algebra and \( \mathcal{E} \subset L^\omega \mathcal{E} \subset \mathcal{E} \) strictly in general. Indeed, let \( X \) be an abelian group, \( \varphi \) a bounded continuous function on \( X \), and \( \psi \in C(X^*) \). Then \( \varphi(Q)\psi(P) \) belongs to \( \mathcal{E} \) but not to \( L^\omega \mathcal{E} \) in general, and if \( \psi \in C_c(X^*) \) it belongs to \( L^\omega \mathcal{E} \) but not to \( \mathcal{E} \) in general, cf. Example 7.2. Note that an operator \( T \in \mathcal{E} \) is locally compact if and only if \( \lim_{a \to e} \lambda_a T^{(x)} = T^{(x)} \) in the local topology of \( \mathcal{E} \).

Finally, we mention another \( C^* \)-algebra which is of a similar nature to \( \mathcal{E}(X) \) and makes sense and is useful in the context of arbitrary locally compact spaces \( X \) and arbitrary geometric Hilbert \( X \)-modules, see [GG2, Ro1]. Let us say that \( S \in \mathcal{B}(\mathcal{H}) \) is quasilocal (or “decay preserving”) if for each \( \varphi \in C_c(X) \) there are operators \( S_1, S_2 \in \mathcal{B}(\mathcal{H}) \) and functions \( \varphi_1, \varphi_2 \in C_c(X) \) such that \( S \varphi(Q) = \varphi_1(Q) S_1 \) and \( \varphi(Q) S = S_2 \varphi_2(Q) \). The set of quasilocal operators is a \( C^* \)-algebra which contains strictly \( \mathcal{E}(X) \) if \( X \) is a locally compact non-compact abelian group. Indeed, if \( \psi \in L^\infty(X^*) \) has compact support then \( \psi(P) \) is quasilocal (because \( \psi(P) \varphi(Q) \) and \( \varphi(Q) \psi(P) \) are compact) but it belongs to \( \mathcal{E}(X) \) if and only if \( \psi \) is continuous.

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