Evaluation of the credibility of the Brazilian inflation targeting system using mixed causal-noncausal models

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Abstract

This paper uses predictive densities obtained via mixed causal-noncausal autoregressive models to evaluate the statistical sustainabil-
ity of Brazilian inflation targeting system with the tolerance bounds. The probabilities give an indication of the short-term credibility of the targeting system without requiring modelling people’s beliefs. We also investigate the added value of including experts predictions of key macroeconomic variables.

Keywords: inflation rate, noncausal models, forecasting, predictive densities, probabilities, credibility.

JEL. C22, C53
1 Introduction

Since the mid 1990s, with the introduction of the Real Plan in July 1994 and later in 1999 with the inflation targeting policy, the actual Brazilian inflation rate has been rather stable, especially compared to previous hyper-inflation period of the 70s and 80s. The annual inflation computed with the Extended National Consumer Price Index (IPCA\textsuperscript{4}), the reference variable for the Brazilian inflation targeting system, is 6.07\% on average between January 1997 and October 2020. Figure 1 displays the IPCA annual inflation rate from January 1997 to October 2020 together with the upper and lower tolerance bounds set by Brazil’s National Monetary Council. These tolerance bounds were 2 to 2.5 percentage points from the target inflation until 2017 and are now 1.5 percentage points above and below the target. With the noticeable exception of years 2001-2003 and 2015-2016, the Central Bank of Brazil (BCB) succeeded to ensure that the IPCA’s annual inflation remains within or close to the tolerance interval. As such, since January 2017, the actual inflation rate was often less than 4\% and is expected to remain stable and within the bounds.

\textsuperscript{4}The IPCA targets population families with household income ranging from 1 to 40 minimum wages. This income range guarantees a 90\% coverage of families living in 13 geographic zones: metropolitan areas of Belém, Fortaleza, Recife, Salvador, Belo Horizonte, Vitória, Rio de Janeiro, São Paulo, Curitiba, Porto Alegre, as well as the Federal District and the cities of Goiânia and Campo Grande. Basket items include Food and Beverages, Housing, Household Articles, Wearing Apparel, Transportation, Health and Personal Care, Personal Expenses, Education and Communication.
The question raised in this paper is whether staying in the tolerance bounds is statistically sustainable, namely what is the probability that in the near future the actual inflation stays on track and what was in real time the probability to go outside the BCB defined limits in the period analyzed. To do so we use the time series properties of the Brazilian inflation rate. We consider a mixed causal-noncausal model (hereafter MAR(\(r,s\))), namely a process with both a lag polynomial of order \(r\) as in the usual autoregressive AR(\(r\)) model but also with a lead polynomial of order \(s\). Not only the introduction of a forward component makes sense for modelling the inflation rate as many economic models link the actual inflation with its future expected value but the MAR model allows to parsimoniously fit nonlinear features observed in such series. This paper therefore first identifies the MAR(\(r,s\)) model on IPCA annual inflation. It is found that the annual inflation rate follows a MAR(1,1) with a Student’s \(t\) distribution with 3.25 degrees of freedom. This estimation allows us, extending the results developed in Hecq and Voisin (2021, 2022), to evaluate the probabilities that the inflation rate stays on track in the future, namely the probabilities that inflation remains within the announced target bounds.

Most of the literature on central banks credibility measures whether people think that the central bank will meet their target or not (Blinder, 2000). This implies the need for modelling people’s expectations regarding future inflation. As shown by Issler and Soares (2019), this is not straightforward to compute and can lead to significantly varying results based on the method employed. This paper instead investigates the probabilities that actual inflation will remain within the announced bounds. The measure we propose does not require the modelling of people’s beliefs and is based on the statistical properties and the dynamics of historical inflation. Hence, the first novelty of this paper is to forecast, using causal and noncausal models, the probability to stay within bounds during rather stable periods. Indeed, MAR models have previously mostly been implemented to foresee the probability of a crash during explosive episodes (e.g. Hecq and Voisin 2021, 2022; Fries and Zakoian, 2019). The second contribution of this paper is to evaluate those probabilities for longer horizons, namely from 1 to 6 step-ahead. Thirdly, we add real time forecasts of Brazilian experts on key macroeconomic variables to the results obtained from the MAR(r,s). This is the so-called MARX model proposed by Hecq et al. (2020).

The rest of the paper is as follows. In Section 2 provides the notation for MAR models and estimates by maximum likelihood the MAR model on
IPCA annual inflation. We use an increasing sample (recursive estimation) and the results provide some evidence that the parameters are rather stable in pseudo-real time. Section 3 summarizes the two main methods that have been developed to forecast with MAR models. These are the simulation based approach of Lanne et al. (2012) and the sample based framework of Gouriéroux and Jasiak (2016). Hecq and Voisin (2021, 2022) have shown that the algorithm proposed by Gouriéroux and Jasiak (2016), the sampling importance resampling (SIR) algorithm, performs better in stable periods rather than during locally explosive episodes. Since this paper investigates ”normal” times, it allows us to illustrate the virtues of the SIR algorithm. Section 4 provides the estimated probabilities for the inflation to stay within announced bounds at various horizons. In Section 5 we add the information of experts for indicators of Brazilian economic development and we study to what extent using a MARX (Hecq et al., 2020) with those additional regressors instead of the purely autoregressive MAR affects probabilities. Section 6 compares our short-term credibility measure with existing credibility indices presented in Issler and Soares (2019). Section 7 concludes.

2 Mixed causal-noncausal models

2.1 Notation

An MAR(r, s) process $y_t$ depends on its $r$ lags as for usual autoregressive processes but also on its $s$ leads in the following multiplicative form

$$\Phi(L)\Psi(L^{-1})y_t = \varepsilon_t,$$

with $L$ is the backshift operator, i.e., $L y_t = y_{t-1}$ gives lags and $L^{-1} y_t = y_{t+1}$ produces leads. When $\Psi(L^{-1}) = (1 - \varphi_1 L^{-1} - ... - \varphi_s L^{-s}) = 1$, namely when $\varphi_1 = ... = \varphi_s = 0$, the process $y_t$ is a purely causal autoregressive process, denoted AR(r,0) or simply AR(r) model $\Phi(L)y_t = \varepsilon_t$. The process is a purely noncausal AR(0,s) model $\Psi(L^{-1})y_t = \varepsilon_t$, when $\phi_1 = ... = \phi_r = 0$ in $\Phi(L) = (1 - \phi_1 L - ... - \phi_r L^r)$. The roots of both the causal and noncausal polynomials are assumed to lie outside the unit circle, that is $\phi(z) = 0$ and $\varphi(z) = 0$ for $|z| > 1$ respectively. These conditions imply that the series $y_t$ admits a two-sided moving average (MA) representation

$$y_t = \sum_{j=-\infty}^{\infty} \psi_j \varepsilon_{t-j},$$

such that $\psi_j = 0$ for all $j < 0$ implies a purely causal process $y_t$ (with respect to $\varepsilon_t$) and a purely noncausal model when $\psi_j = 0$ for all $j > 0$ (Lanne and Saikkonen, 2011).
Error terms $\varepsilon_t$ are assumed i.i.d. (and not only weak white noise) non-Gaussian to ensure the identifiability of the causal and the noncausal part (Breidt et al., 1991). There is a increasing literature making use of MAR models; see among others Karapanagiotidis (2014), Hencic and Gouriéroux (2015), Gouriéroux and Jasiak (2016), Lof and Nyberg (2017), Hecq and Sun (2021), Bec et al. (2020), Gourieroux et al. (2021), Gourieroux et al. (2021a).

2.2 Estimation results on IPCA

Let $\pi_t$ denote the inflation rate in Brazil at time $t$. The hybrid New Keynesian Phillips Curve (NKPC) regression is such as

$$\pi_t = \gamma_f \mathbb{E}_t[\pi_{t+1}] + \gamma_b \pi_{t-1} + \beta x_t + \varepsilon_t,$$

where $\mathbb{E}_t[\cdot]$ the conditional expectation at time $t$, $x_t$ is a measure for marginal costs, which is not directly observable (a potential proxy can be the output gap) and $\varepsilon_t$ an i.i.d. error term. Adding and subtracting $\gamma_f \pi_{t+1}$ and rearranging terms, gives

$$\pi_t = \gamma_f \pi_{t+1} + \gamma_b \pi_{t-1} + \beta x_t + \gamma_f \left( \mathbb{E}_t[\pi_{t+1}] - \pi_{t+1} \right) + \varepsilon_t,$$

where the newly defined disturbance term $\eta_{t+1}$ consists of three different parts: (i) the expectation error $(\mathbb{E}_t[\pi_{t+1}] - \pi_{t+1})$ which is assumed i.i.d. following the literature on rational expectations models, (ii) the marginal costs variable $x_t$ and (iii) an i.i.d. error term $\varepsilon_t$. Hence, the time series properties of $\eta_{t+1}$ will depend on those of $x_t$, but $x_t$ is assumed to be adequately approximated by a finite-order autoregression (Lanne and Luoto, 2013). Subsequently, the newly obtained equation is divided by $\gamma_f$ and lagged by one period to obtain $(1 - \gamma_f^{-1}L + \gamma_b^{-1}L^2)\pi_t = -\gamma_f^{-1}\eta_t$. Next, $a(z) \equiv (1 - \gamma_f^{-1}z + \gamma_b^{-1}z^2)$ can be written as the product of two polynomials, i.e., $a(z) = (1 - \phi z)(1 - \phi^* z)$ with $|\phi| < 1$ and $|\phi^*| > 1$ for plausible values of $\gamma_f$ and $\gamma_b$ leading to a stable mixed causal noncausal formulation. See Lanne and Luoto (2013) for details. The MAR models we consider in this paper are not a direct mapping of the NKPC but rather an estimation of the dynamics emanating from the transformations of the Philips curve mentioned above.
We have used the MARX package developed by Hecq et al. (2017) and found on the whole sample an MAR(1,1) with a Student’s t with 3.25 degrees of freedom. Standard errors computed as in Hecq et al. (2016) are in brackets.

\[(1 - 0.58 L)(1 - 0.94 L^{-1})\pi_t = \varepsilon_t, \quad \varepsilon_t \sim t(3.25)\] (1)

To analyse the stability of the estimation we recursively estimate the orders of the MAR(r,s) model and the corresponding coefficients with an expanding window. The initial sample goes from January 1997 to April 2005 (100 data points) and the last one goes to January 2020 (277 data points). Note that at each point the model identified was an MAR(1,1), we hence only provide the graphs of the recursive estimates of the lag coefficient, the lead coefficient and the degrees of freedom of the Student’s t distribution in Figure 2 with the corresponding 95% confidence interval.

We can see that adding data points does not affect the value of the estimated coefficients. Over the 177 points added, the value of the lag coefficients slightly decreases from 0.62 to 0.58 whereas the lead coefficient varies between 0.936 and 0.948 and stabilises around 0.944 towards the end of the sample. The degrees of freedom vary between 3 and 3.7 and converges towards 3.25 towards the end of the sample. Hence, the slightly different models estimated in real time for recursive out of sample forecasts will not significantly affect the calculated probabilities and they will therefore be comparable.

3 Predicting the probabilities to stay in the bounds

With Cauchy- and Levy-distributed errors, the conditional density of an MAR(r,s) process admits closed-form expressions, this is however not the case for Student’s t distributed processes (Gouriéroux and Zakoian, 2017). Assuming Student’s t errors offers more flexibility than the Cauchy distribution, which might be too extreme, especially for inflation series that are not particularly volatile. Hence, in the absence of closed-form expressions for the predictive density, two approximations methods have been developed. The first one is based on simulations and was proposed by Lanne.
Figure 2: Recursive estimates of the coefficients based on end point of sample and their 95% C.I.

et al. (2012). The second one employs past realised values instead of simulations and was proposed by Gouriéroux and Jasiak (2016). However, as the latter becomes too computationally demanding when the forecast horizon increases, Gouriéroux and Jasiak (2016) proposed a Sampling Importance
Resampling (henceforth SIR) algorithm facilitating longer horizon forecasts with this method. While the algorithm does not always work for extreme events, it provides accurate results when the variables are rather stable, which is the case with the inflation series that we investigate here. Overall, both approaches use the decomposition of the mixed process into a causal and a noncausal component as such

\[ u_t \equiv \Phi(L) \pi_t \]
\[ v_t \equiv \Psi(L^{-1}) \pi_t. \]

(2)

The process \( u_t \) is the purely noncausal component of the errors, on which we will focus. In this analysis, since the inflation series is an MAR(1,1), the process \( u_t \) is a purely noncausal process of order 1,

\[ \Psi(L^{-1}) u_t = \varepsilon_t \]
\[ u_t = \psi u_{t+1} + \varepsilon_t. \]

(3)

3.1 Simulations-based approach

The purely noncausal component of the errors, \( u_t \), can be expressed as an infinite sum of future error terms in its MA representation. The stationarity of the process ensures the existence of an integer \( M \) large enough to approximate this infinite representation as such (Lanne et al., 2012),

\[ u_t \approx \sum_{i=0}^{M} \psi^i \varepsilon_{t+i}, \]

(4)

Let \( lb_t \) and \( ub_t \) be the lower and upper bound for inflation in Brazil assessed for time \( t \). We are interested in the conditional probabilities that inflation will be within the bounds at a given horizon \( h \), where \( T \) is the last observed point in the sample,

\[ P\left( lb_{T+h} \leq \pi_{T+h} \leq ub_{T+h} | F_T \right) = P\left( \pi_{T+h} \leq ub_{T+h} | F_T \right) - P\left( \pi_{T+h} \leq lb_{T+h} | F_T \right) \]
\[ = E_T \left[ 1(\pi_{T+h} \leq ub_{T+h}) - 1(\pi_{T+h} \leq lb_{T+h}) \right] \]

(5)

The indicator function \( 1() \) is equal to 1 when the condition is met and 0 otherwise.
Since $\pi_t = \phi \pi_{t-1} + u_t$, by recursive substitution and using the approximation equation (4), we obtain,

$$
\pi_{T+h} = \phi^h \pi_T + \sum_{i=0}^{h} \phi^i u_{T+i} - 1 + u_T 
\approx \phi^h \pi_T + \sum_{i=0}^{h} \sum_{j=0}^{M-h-i} \phi^i \psi^j \varepsilon_{T+i+j},
$$

(6)

where $M$ is the truncation parameter introduced in Equation (4). Substituting this approximation in (5), an approximation of the conditional probabilities is the following,

$$
P\left(lb_{T+h} \leq \pi^*_T + ub_{T+h} \mid F_T\right) \approx \mathbb{E}_T\left[1\left(\pi_T + \sum_{i=0}^{h} \sum_{j=0}^{M-h-i} \phi^i \psi^j \varepsilon_{T+i+j} \leq ub_{T+h}\right) - 1\left(\pi_T + \sum_{i=0}^{h} \sum_{j=0}^{M-h-i} \phi^i \psi^j \varepsilon_{T+i+j} \leq lb_{T+h}\right)\right]
$$

(7)

Given the information set known at time $T$, the indicator functions in (7) are only functions of the $M$ future errors, $\varepsilon^*_+ = (\varepsilon^*_{T+1}, \ldots, \varepsilon^*_{T+M})$. Let $q(\varepsilon^*_+)$ be the function providing the value of the difference between the two indicator functions. Furthermore, let $\varepsilon^*_+(j) = (\varepsilon^*(j)_{T+1}, \ldots, \varepsilon^*(j)_{T+M})$, with $1 \leq j \leq N$, be the $j$-th simulated series of $M$ independent errors, randomly drawn from the errors distribution, here a Student’s $t(3.25)$. Assuming that the number of simulations $N$ and the truncation parameter $M$ are large enough, the probability that the inflation rate (which follows an $MAR(1,1)$ process) will remain within the bounds in $h$ months can be approximated as such (Lanne et al., 2012).

$$
P\left(lb_{T+h} \leq \pi^*_T + h \leq ub_{T+h} \mid F_T\right) \approx \mathbb{E}_T\left[q(\varepsilon^*_+)\right] 
\approx \frac{N^{-1} \sum_{j=1}^{N} q(\varepsilon^*_+(j)) g(u_T - \sum_{i=1}^{M} \psi^i \varepsilon^*_T + (j))}{N^{-1} \sum_{j=1}^{N} g(u_T - \sum_{i=1}^{M} \psi^i \varepsilon^*_T + (j))},
$$

(8)

where $g$ is the pdf of the Student’s $t(3.25)$ distribution.

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6See Appendix A for more detailed derivations of the estimator.
Hecq and Voisin (2021) results show that with Cauchy-distributed errors, this approach is a good estimator of theoretical probabilities but are significantly sensitive to the number of simulations \(N\) during locally explosive episodes. For Student’s \(t\) distributions however, results cannot be compared to theoretical ones, but as the number of simulations gets larger, the derived densities converge to a unique function. Overall Hecq and Voisin (2021) show that:

(i) for degrees of freedom close to 3 and

(ii) during stable episodes, this approach yields consistent results that are not significantly sensitive to the number of simulations, as long as it is reasonably large. Hence, choosing the right number of simulations per iteration should not be a worry in this analysis.

3.2 Sample-based approach

As an alternative to using simulations, Gouriéroux and Jasiak (2016) employ all past observed values of the process to approximate the marginal distributions of noncausal processes. They propose the following sample-based approximation of the predictive density of an MAR(0,1),

\[
\begin{align*}
l(u_{T+1}^*, \ldots, u_{T+h}^* | \mathcal{F}_T) &\approx g(u_T - \psi u_{T+1}^*) \cdots g(u_{T+h-1}^* - \psi u_{T+h}^*) \sum_{i=2}^{T} g(u_{T+h}^* - \psi u_i) \sum_{i=2}^{T} g(u_T - \psi u_i),
\end{align*}
\]

where \(g\) is the pdf of a Student’s \(t\) distribution with 3.25 degrees of freedom.

Given a correctly identified model and based on the equivalence of the information sets \((\pi_1, \ldots, \pi_T, \pi_{T+1}, \ldots, \pi_{T+h})\) and \((v_1, \varepsilon_2, \ldots, \varepsilon_{T-1}, u_T, u_{T+1}, \ldots, u_{T+h})\) (Gouriéroux and Jasiak 2016), where \(v_t = \pi_t - \psi \pi_{t+1}\), the predictive density of the \(MAR(1,1)\) process \(\pi_t\) can be obtained by substituting the filtered noncausal process \(u_t\) by the mixed process \(\pi_t\) in (9),

\[
\begin{align*}
l(\pi_{T+1}^*, \ldots, \pi_{T+h}^* | \mathcal{F}_T) &\approx g\left( (\pi_T - \phi \pi_{T-1}) - \psi (\pi_{T+1}^* - \phi \pi_T) \right) \times \cdots \\
&\quad \cdots \times g\left( (\pi_{T+h-1}^* - \phi \pi_{T+h-2}) - \psi (\pi_{T+h}^* - \phi \pi_{T+h-1}) \right) \\
&\quad \times \sum_{i=2}^{T} g\left( \pi_{T+h}^* - \psi (\pi_{T+h-1}^* - \phi \pi_{T+h-2}) - \psi (\pi_{T+h-2}^* - \phi \pi_{T+h-3}) \right) \\
&\quad \cdots \times \sum_{i=2}^{T} g\left( \pi_T - \phi \pi_{T-1} - \psi (\pi_{T-1} - \phi \pi_{T-2}) \right).
\end{align*}
\]

Evidently, evaluating the conditional joint density over all possible outcomes becomes considerably computationally demanding as the forecast horizon increases. This is why Gouriéroux and Jasiak (2016) developed a Sampling

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\(^7\)See Appendix B for more detailed derivations of the estimator.
Importance Resampling (henceforth SIR) algorithm to counter this computational limitation. We provide details and describe the algorithm in the subsequent Section. We will therefore employ estimator (10) for a forecast horizon of 1 (see (11)) and will use the SIR algorithm for horizons of 3 and 6 months.

\[
I(\pi^*_T | F_T) \approx g((\pi_T - \phi \pi_{T-1}) - \psi(\pi^*_T - \phi \pi_T)) \sum_{i=2}^{T} g(\pi^*_T - \phi \pi_{T-1} - \psi(\pi_i - \phi \pi_{i-1}))), \quad (11)
\]

This estimator provides predicted probabilities that are a combination of theoretical probabilities and probabilities induced by past events; results are therefore case-specific and are based on a learning mechanism (Hecq and Voisin, 2021). For values close to the median this approach provides accurate and similar results to theoretical probabilities (when available) and to the simulations-based method of Lanne et al. (2012) for one-step ahead forecasts. Discrepancies widen as the level of the series increases.

### 3.3 Sampling Importance Resampling algorithm

As previously mentioned, estimator (10) developed by Gouriéroux and Jasiak (2016) is substantially computationally demanding to employ for long forecast horizons and simulating from this distribution is rather intricate. The authors then proposed a SIR algorithm to counter this. The algorithm consists in simulating potential paths of future noncausal components \(u_t\)’s from an instrumental misspecified model from which it is easier to simulate. The distribution (10) of interest is then recovered using a weighted resampling of the simulations and the relation (3) between the inflation rate \(\pi_t\) and its noncausal component \(u_t\). Gouriéroux and Zakoïan (2013) note that a Markov process in reverse time is also a Markov process – of the same order – in calendar time with non-linear dynamics. Hence, since in this analysis \(u_t\) is a non-causal MAR(0,1) process, it could be expressed as a causal AR(1) process, with non-linear dynamics. For a study on misspecified causal analysis of noncausal processes see Gourieroux and Jasiak (2018). Following Gouriéroux and Jasiak (2016), we employ a Gaussian AR(1) model as instrumental model for the algorithm,

\[
u_t = \tilde{\rho} u_{t-1} + \tilde{\epsilon}_t.
\quad (12)
\]

The parameter \(\tilde{\rho}\) is estimated using standard OLS on the observed values \(u_t\) filtered from the initial MAR(1,1) process \(\pi_t\). The errors \(\tilde{\epsilon}_t \sim \mathcal{IN}(0, \tilde{\sigma}^2)\),
where $\hat{\sigma}^2$ is the MAR residuals variance,  $\hat{\cdot}$ indicates estimation from the instrumental model, and  $\check{\cdot}$ from the initial $MAR(1,1)$ model. The conditional predictive density for the instrumental process is as follows,

$$
\begin{align*}
\check{F}(\tilde{u}_T^{*+1}, \ldots, \tilde{u}_T^{*+H}|u_T) & = \check{l}(u_T^{*+1}|u_T^{*+H-1})\check{l}(u_T^{*+H-1}|u_T^{*+H-2})\ldots\check{l}(u_T^{*+1}|u_T) \\
& = f(u_T^{*+H} - \tilde{\rho}u_T^{*+H-1})f(u_T^{*+H-1} - \tilde{\rho}u_T^{*+H-2})\ldots f(u_T^{*+1} - \tilde{\rho}u_T),
\end{align*}
$$

(13)

where $\check{F}$ is the predictive conditional distribution of future $u_t$'s from the instrumental model and $f$ the $pdf$ of a normal distribution with mean zero and variance $\hat{\sigma}^2$. Even though this model is clearly misspecified, the resampling step should automatically correct for the induced misspecifications [Gouriéroux and Jasiak (2016)]. The algorithm for $h$-step ahead predictions is as follows (see also Gourieroux et al., 2021a),

1. **Sampling:** Draw $K$ series of $h$ independent values $\tilde{\varepsilon}$ from a normal distribution $N(0, \hat{\sigma}^2)$. Using the recursive equation (12) and the last observed value $u_T$, compute the $K$ simulated paths $(\tilde{u}_T^{*+1}, \ldots, \tilde{u}_T^{*+H})$, respectively stacked in $\tilde{U}^{i}$s, $i = 1, \ldots, K$.

2. **Importance:** Denote $\Pi(\tilde{U}^i)$ the conditional density (10) evaluated at the path $(\tilde{u}_T^{i+1}, \ldots, \tilde{u}_T^{*+H})$. Compute the weights $w_i = \check{\Pi}(\tilde{U}^{i}) / \check{F}(\tilde{U}^{i})$ with $i = 1, \ldots, K$. Namely, the ratio between the value of the density the algorithm intends to recover and the value of the instrumental density.

3. **Resampling:** Draw with probability weighting based on the previously computed weights and replacement $S$ paths $(\tilde{u}_T^{s+1}, \ldots, \tilde{u}_T^{*+H})$, $s = 1, \ldots, S$, from the $K$ simulated series in the sampling step, with respective weights $w_i$.

Once the set of $S$ re-sampled $\tilde{U}^{i}$s is obtained, each simulated path $(\tilde{u}_T^{s+1}, \ldots, \tilde{u}_T^{*+H})$, $s = 1, \ldots, S$ can be transformed into the corresponding future path for the variable of interest $(\pi_T^{s+1}, \ldots, \pi_T^{*+H})$ using on the causal relation in Equation (3).

As stated by Gouriéroux and Jasiak (2016), if the number of initial simulations $K$ is large enough, simulating from the instrumental Gaussian model and applying the SIR algorithm is equivalent to simulating directly from the distribution of interest. It avoids simulating from a too complicated distribution, or avoids the simulation of too many extreme values.
Voisin (2021) find that this approach may not function well during extreme events as the instrumental density becomes too different from the one to recover. The instrumental density (derived from normally distributed errors) is unimodal while the predictive density of a purely noncausal process during an explosive episode is bi-modal with a significantly larger range. This implies that during extreme events the instrumental conditional density is sometimes zero where the target distribution is not. This implies that during extreme episode the distribution derived from the algorithm may not converge to the target one since parts of the distribution are not simulated in the first step of the algorithm, regardless of the number of simulations. Further research should be done to improve the algorithm in such cases. However, we focus here on stable periods and this limit of the algorithm does therefore not affect our analysis.

4 Forecasting with MAR model

Using the model estimated in Section 2, we first perform 1-, 3- and 6-months forecasts of the probabilities to remain within the bounds with expanding window from November 2016 to January 2020. We first analyse the impact of the choice of forecasting method as well as the impact of the forecast horizon on the probabilities. As shown previously in Figure 2, the estimation of the model is stable and particularly so after 2016. Therefore, re-estimating the model with expanding window at each point of forecasts does not have a significant impact on the results and represents a good real-time forecasting analysis. We can hence obtain 39 pseudo real-time probability forecasts for each of the three horizons and each of the two methods.

Figure 3 depicts the differences between the predictions made with the simulations based method (solid line) of Lanne et al. (2012) and the SIR algorithm (dashed line) employing the sample-based method of Gouriéroux and Jasiak (2016). Graph (a) shows the 1-month ahead forecasts performed with increasing sample at each point. Graph (b) and (c) correspond to 3- and 6-months ahead forecasts respectively. All forecasts are performed at the same 39 points, starting in November 2016. Note that as the analysis does not regard extreme episodes, the 1-step ahead density forecasts obtained with the SIR algorithm and the sample-based method of Gouriéroux

8Employing 1,000,000 simulations at each iteration.
9Employing 100,000 simulations in the first step and 10,000 resampling forecasts.
and Jasiak (2016) were identical. For a thorough analysis of their respective performance see Hecq and Voisin (2021). Since they perform similarly and because the SIR algorithm is less computationally demanding we only present the SIR results alongside the simulations-based results (LLS).

Figure 3: Probability forecasts for inflation to remain within the bounds

We can see that the differences between the two methods increase with the horizon. For one-step ahead forecasts, both approaches yield almost the same results at each point in time, while for the 6-months ahead forecasts they differ on average by 0.09, with the SIR probabilities always larger than LLS. This indicates that LLS predicts more volatile fluctuations in the inflation rate than the SIR for longer horizons, hence suggesting lower probabilities to remain within the bounds. Furthermore, we can see that while probabilities vary significantly at a 1-month horizon (from 0.08 to 1), they converge around 0.6 for both methods as the horizon increases to 6 months. That is, as the forecast horizon increases, the uncertainty prevails, regardless of being within or outside the bounds at the moment of the forecast, which yields almost 50/50 chance to meet the target at at 6-months horizon. This is because we are investigating a period during which there is no explosive episodes. Inflation is relatively stable though close to the lower bound of the target.

Figure 4 displays the probabilities obtained from LLS at the three horizons and indicates the months in which the inflation rate was outside the announced bounds (shaded areas). While uncertainty increases with the horizon, we can see that the 1-step ahead forecasts are below 0.6 most of

\footnote{Results available upon request.}

\footnote{Table 1 in Appendix C summarizes the results.}
the times inflation is outside the bounds and quickly corrects its predictions once inflation is back within the target bounds. Increasing the horizon increases the uncertainty and this is why the probabilities converge to 0.6 as every scenario is possible in between the point at which predictions are performed and the horizon investigated.

![Figure 4: Probability forecasts for inflation to remain within the bounds with different forecasts horizons](image)

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5  MARX model

5.1 Model representation

MAR models with additional strictly exogenous variables have been introduced by Hecq et al. (2020). The so called MARX model allows to estimate the effects of covariates without aggregating them in the error term as in the MAR\((r, s)\) model of Section 2. The MAR\((r, s, q)\) for a stationary time series \(\pi_t\) (here, the annual IPCA inflation rate) reads as follows

\[
\phi(L)\varphi(L^{-1})\pi_t - \beta'X_t = \varepsilon_t, \tag{14}
\]

where \(\phi(L)\) and \(\varphi(L^{-1})\) are the lag and lead polynomials of order \(r\) and \(s\) with \(r + s = p\) and \(q\) is the number of strictly exogenous variables. We still assume that the roots of both polynomials lie outside the unit circle. When \(q = 0\), the process reduces to a standard MAR\((r, s)\). In case \(q > 0\), the
process no longer has a strictly stationary solution solely in terms of \( \varepsilon_t \), but involves additionally \( X_t \) (consisting of \( q \) exogenous variables). That is,

\[
\pi_t = \gamma(L, L^{-1})\varepsilon_t + \gamma(L, L^{-1})\beta'X_t = \sum_{j=-\infty}^\infty \gamma_j z_{t-j},
\]

(15)

where \( z_{t-j} = \varepsilon_{t-j} + \sum_{i=1}^q \beta_i x_{i,t-j} \) and \( \gamma(L, L^{-1}) \) is an operator satisfying \( \gamma(L, L^{-1})\phi(L)\varphi(L^{-1}) = 1 \) such that \( \pi_t \) has a two-sided MA-representation augmented with past, current and future values of \( X_t \). Consequently, denoting \( \tilde{x}_{i,t} = \beta_i x_{i,t} \), \( \pi_t \) consists of a two-sided MA representation and the sum of \( q \) processes \( \tilde{x}_{i,t} \) that are passed through a two-sided linear filter with coefficients resulting from inverting the product \( [\phi(L)\varphi(L^{-1})] \). Similarly to the MAR, the MARX can be decomposed in \( u \) and \( v \) components, namely the noncausal and causal components respectively,

\[
u_t \equiv \phi(L)\pi_t \leftrightarrow \varphi(L^{-1})u_t - \beta'X_t = \varepsilon_t,
\]

(16)

\[
v_t \equiv \varphi(L^{-1})\pi_t \leftrightarrow \phi(L)v_t - \beta'X_t = \varepsilon_t.
\]

(17)

This \( (u, v) \) representation is useful to simulate variable and to forecast MAR processes. See [Hecq et al. (2020)] for details on the model.

### 5.2 Data

We evaluate to what extent key drivers of inflation identified by the BCB, have an influence on the probability that inflation stays within the target bounds. The variables we consider are the year-on-year percentage change in industrial production\(^{12}\) \((ip_t)\), the year-on-year percentage change in the Real/US$ exchange rate \((ex_t)\) where the rate refers to the last working day of the period and the year-on-year percentage change in the Selic target interest rate \((ir_t)\). We denote \( X_t = (ip_t, ex_t, ir_t) \) the stacked stationary exogenous variables at time \( t \). We use published indicators of the three variables (retrieved from FRED and from the Central Bank of Brazil databases). For coherence and comparison purpose we use the same sample as for Section\(^2\), namely from January 1997 to January 2020.

### 5.3 Estimation results

The aim of this section is to analyse the added value of augmenting the MAR(1,1) model identified in Section\(^3\) with exogenous variables. Hence,

\(^{12}\)We prefer to use the industrial production index as a measure of economic activity over the GDP that is available quarterly.
we identify the MARX(1,1,q) model best fitting the data, using the strategy proposed in Hecq et al. (2020). We first estimate an ARDL model using a maximum likelihood approach and find that BIC favors an ARDL(2,0,0,0), namely an AR(2) with only contemporaneous values of the three regressors. The increase of the goodness of fit is however not substantial, the $R^2$ increases from 0.977 to 0.980. The estimated model is the following (HCSE standard errors in brackets),

$$\pi_t = 0.16 + 1.46 \pi_{t-1} - 0.50 \pi_{t-2} + 2.21 i_{t-1}p_t + 0.87 e x_t + 0.23 i r_t + \eta_t.\$$

All three regressors have a significant impact on annual inflation and only their contemporaneous values are selected. The value of the Jarque and Bera normality test is 185.3 with a $p-value < 0.0001$.

Following the methodology described in Hecq et al. (2020) we compare all MARX(1,1,3) considering all possible time indices of the exogenous variables (namely their lag, lead or contemporaneous value). The model maximizing the likelihood function is the following MARX(1,1,3) with a $t(3.39)$ (standard errors in brackets),

$$(1 - 0.50 L)(1 - 0.97 L^{-1})\pi_t = 0.14 - 1.64 i p_{t+1} - 0.53 e x_{t+1} - 0.04 i r_{t+1} + \varepsilon_t.\tag{18}$$

That is, the model maximizing the likelihood function includes the lead of the three exogenous variables. The year-on-year inflation rate is therefore influenced by anticipations in the key economic variables considered here. The coefficients might not represent actual effects but instead corrections of the effect already captured by the coefficient on the lead of the inflation rate. We do not focus on that.\footnote{We acknowledge the fact that these regressors might not be fully strictly exogenous. Yet, we provide this analysis to illustrate the use of MARX models and take advantage of the availability of frequent forecasts for these variables which enables using MARX models to forecast without needing to predict the exogenous variables separately.}

\subsection*{5.4 Predictions with Focus data}

Hecq et al. (2020) find that the forecasts obtained in a MARX are superior to the ones of a MAR model when the future values of the regressors are
known. The gain diminishes when the regressors must be forecasted as well, using an ARMA model for instance. The choice of exogenous variables in this analysis was motivated by the fact that those variables are forecasted and updated on a daily basis by experts in the Focus database maintained by the Brazilian Central Bank. Previous periods are re-evaluated until the official numbers are published and forecasts for future periods are available at various horizons. This allows to perform forecasts using MARX models without modelling and forecasting separately the exogenous variables.

In this study, when performing predictions, we take the overall median of experts’ forecasts for the future values of $X$ in real time. This means for instance that in May 2019 we take the forecasts of the explanatory variables for the next months made at the end of May 2019. Furthermore, to ensure coherence in the data, we also replace the last three data points (in this example we replace March, April and May 2019) by the last vintages available at the point at which the forecast is preformed.

Alike the MARX process $\pi_t$, the MA representation of the noncausal component $u_t$ is also augmented by contemporaneous and future values of $X_t$,

$$u_t = \varphi(L^{-1})^{-1} [\beta'X_t + \varepsilon_t]$$

$$= \sum_{i=0}^{\infty} \psi^i [\beta'X_{t+i} + \varepsilon_{t+i}]. \tag{19}$$

In analogy to Equation (4), the method of Lanne et al. (2012) – if possibly extended to MARX models – would require a truncation parameter $M$ large enough to approximate (19). This implies that $M$ future values of the exogenous variables would be needed to perform forecasts with such approach. Lanne et al. (2012) suggest using $M=50$ which represents more than four years of monthly predictions.

On the other hand, the method of Gouriéroux and Jasiak (2016) only requires as many predictions of the exogenous variables as the forecast horizon.

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14See https://www.bcb.gov.br/en/monetarypolicy/marketexpectations. The Brazilian survey on economic forecasters is unique. Everyday, a set of experts (from banks, fund managers, brokers, consulting companies, etc) give their evaluation on the future of inflation rate as well as for several key macroeconomic variables regarding the Brazilian economy. Most variables are published before the release of the Brazilian consumer price index, which is made public around the 10th of the subsequent month. Some variables have some delays and they also often continue to be forecasted for several vintages after the end of the corresponding month.
This makes this approach the most suitable for this analysis. As explained in Section 4, for one-step ahead forecasts, the estimator (11) can be employed, but as the forecast horizon increases the SIR algorithm alleviates the computational limitations of the estimator. The SIR approach simulates the noncausal component of the process using a purely causal instrumental model and then transforms those simulations into simulations of the variable of interest using the causal relation between $\pi_t$ and $u_t$ described in (2).

We use the following instrumental model for the SIR algorithm,

$$u_t = \rho u_{t-1} + \eta_1 i_p t + \eta_2 e x_t + \eta_3 i_r t + \epsilon_t,$$

(20)

where $\epsilon_t \sim N(0, \sigma^2)$. This instrumental model is the pseudo causal model obtained by inverting the time indices in the noncausal representation of $u_t$. The parameters are obtained using standard OLS on the whole sample.

As mentioned, to resemble a real time forecast, we replace the values for the last three observations (from $T-2$ to $T$) by the evaluations made by experts for the exogenous variables at time $T$, and we take the six consecutive months forecasts made at the same point in time. Alike Section 4, we perform 1-, 3- and 6-months ahead forecasts at the end of each month from November 2016 to January 2020. The SIR algorithm is employed the same way as for the MAR. We re-estimate the model every time, yet we fix the time indices of the variables to be the ones in model (18). Figure 5 shows the recursive estimations of each coefficient as the sample expands. We see that estimations is stable for all coefficients and predictions are thus easily comparable from one point in time to another.

Figure 6 shows point forecasts obtained from the MAR model of Section 4 (dashed lines) compared to the point forecasts obtained with the MARX model (dotted lines). Forecasts at the different horizons are compared to realized inflation rate (black solid line) and the announced target bounds (grey solid lines). We can see that the inclusion of exogenous variables does not significantly alter the predictions, especially for short-term horizons. An explanation to this is that forecasts of yearly changes in the exogenous variables around that time were very close to 0 as we are investigating a stable period. We can however notice that when the inclusion of exogenous variables has an impact, it becomes increasingly noticeable at larger horizons. We can therefore expect that during unstable and more volatile periods the inclusion of exogenous variables should influence more significantly forecasts and predictive densities. Another explanation is that inflation might
already be influenced by expectations of the exogenous variables. Hence, their inclusion might most of the time not be enough to significantly alter predictions.

6 Short-term credibility

There is a long tradition of evaluating the credibility of central banks. Svensson (2000) for instance measures credibility as the distance between expected and targeted inflation. A commonly used definition of central bank credibility is the following: a central bank is credible if people believe it will do what it says (Blinder, 2000). This definition however implies the need for modelling people’s beliefs, which is not straightforward and can induce significantly different results based on the assumptions and model construction (see the reference list in Issler and Soares, 2019). Some construct the credi-
### Figure 6: MAR vs MARX

Inflation credibility as an inverse function of the gap between expectation and target, using different ad-hoc thresholds for what is considered credible or not (see next page).
among others [Cecchetti and Krause, 2002 and Mendonça and Souza, 2007]. Bomfim and Rudebusch (2000) construct expected inflation as a weighted average of the target and past inflation rate and interpret credibility as the weight of the latter. Dovern et al. (2012) use professional forecasters’ predictions and interpret the discrepancies between them as an indication of lack of credibility. Issler and Soares (2019) propose a bias-corrected measure of inflation expectation using survey data and construct a credibility index based on whether the target falls within the confidence interval of their expectation measure.

We take a different stand-point and measure credibility not from the perspective of people’ beliefs but from the dynamics in past inflation rates. That is, we use the probabilities that inflation remains within the target bounds as an indication of whether the bounds are credible or not based on past fluctuations in realized inflation. This measure therefore only relies on the statistical and dynamic properties of inflation and not on people’s beliefs. Undoubtedly, the measure may have limitations as to the amount of information it is derived from, but it can nevertheless provide valuable information regarding the probabilities for the target to be met. To retain and employ all the dynamics in realised inflation rates, we use monthly year-on-year inflation rate, which implies that our forecasts are based on shorter time horizons than the one-year-ahead expectations used in most of the aforementioned methods to build the credibility indices. We therefore measure short-term credibility and not long-term, which explains the discrepancies obtained with other approaches. Indeed, short-term predictions carry more shocks than one-year ahead forecasts.

For comparison purposes we use the same time span as the analysis of Issler and Soares (2019), namely from January 2007 to April 2017. Figure 7 compares our short-term credibility measurement with distinct indices presented in Issler and Soares (2019). IS is the index built by Issler and Soares (2019) themselves, DM is the index developed by Mendonça and Souza (2007), CK the index by Cecchetti and Krause (2002), DGMS by Mendonça and Souza (2009) and LL by Levieuge et al. (2018). The short-term credibility index is the 1-month ahead simulations-based probabilities (LLS) that inflation will remain within the announced target bounds (the red solid line). Apart from CK and DMGS which suggest almost full credibility during the whole period, we can notice that the main differences between the 3 other credibility indices and ours are for the years 2012-2014. As mentioned, this is explained by the fact that inflation forecasts used for the construc-
tion of the credibility indices are often of long horizons. The forecasts series are usually smoother than actual inflation and therefore carry less short-term shocks that our series contains. Hence, for instance between 2013 and 2014, there was a turning point in the inflation rate, where inflation started decreasing again towards the target. Since our method is based on the directions of the variations in inflation, it estimated the central bank to be rather credible as it seemed likely that they would keep inflation between the tolerance bounds. This was indeed the case until the end of 2014 and then inflation started increasing again. The 12-months ahead forecasts did not capture this short-term return to the target and the central bank was estimated not credible during this time which can also explain the slight lag towards full credibility at the end of the sample. Furthermore, our method does not investigate whether people trust the central bank to reach its goals but instead it investigates whether it seems likely to happen at short horizons based on realized inflation rates, which can also explain some of the discrepancies.

Overall, while our short-term credibility index might be affected by short-term shocks in the inflation rate, it does not require any modelling of people’s beliefs, or does not require any ad-hoc decisions for thresholds of credibility, which can provide significantly different credibility indices as shown in Figure 7.

Figure 7: Comparison credibility indices

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7 Conclusion

This paper investigates the probabilities that the Brazilian inflation rate remains within the target bounds determined by the central bank. We estimate mixed causal-noncausal models with leads and lags of the inflation rate and the first noticeable results are the stability of the parameters estimation over time. Contrary to usual practice when employing mixed causal noncausal models, which consists in forecasting bubble bursts, we choose the stable period between 2017 and 2020 for the forecasting exercise. We perform 1-, 3- and 6-months ahead probability forecasts. For short-horizons forecasts we correctly track probabilities to stay in the target bounds and interpret those results as the short-term credibility of the inflation targeting system based on historical inflation without the need to model people’s beliefs. In longer horizon, probabilities seem to converge to a 50/50 result. We augment the univariate model with key economic variables and results show that during stable times, the addition of those variables do not impact significantly the predictions obtained from the univariate model. We then compare our measure of short-term credibility of the central bank with existing indices in the literature. We find that in spite of the discrepancies due to the difference in horizons, our approach provides similar information.
Appendix

A Simulations-based estimator

Let \( g(\varepsilon^*_+|u_T) \) be the conditional joint distribution of the \( M \) future errors \( (\varepsilon^*_{T+1}, \ldots, \varepsilon^*_{T+M}) \), which using Bayes’ Theorem can be expressed as follows,

\[
g(\varepsilon^*_+|u_T) = \frac{l(u_T|\varepsilon^*_+)}{l(u_T)} g(\varepsilon^*_+),
\]

where \( g \) is the pdf associated with the error terms and \( l \) denotes the densities associated with the process \( u_t \). Thus, for any function \( q \), the conditional expectation of such function of future error terms can be re-written as follows,

\[
\mathbb{E}\left[q(\varepsilon^*+)|u_T\right] = \int q(\varepsilon^*_+) g(\varepsilon^*_+|u_T) d\varepsilon^*_+ \approx \frac{\mathbb{E}_{\varepsilon^*_+}\left[g\left(u_T - \sum_{i=1}^{M} \psi^i \varepsilon^*_T+i\right)\right]}{l(u_T)}.
\]

The conditional distribution \( l(u_T|\varepsilon^*_+) \) can be obtained from the error distribution \( g \). Yet, since it is conditional on \( \varepsilon^*_+ \) instead of \( u^*_{T+1} \), we can only obtain an approximation. Using this approximation and the Iterated Expectation theorem, the marginal distribution of \( u_T \) can be approximated as follows,

\[
l(u_T) = \mathbb{E}_{\varepsilon^*_+}\left[l(u_T|\varepsilon^*_+)\right] \approx \mathbb{E}_{\varepsilon^*_+}\left[g\left(u_T - \sum_{i=1}^{M} \psi^i \varepsilon^*_T+i\right)\right].
\]

Overall, by plugging the aforementioned approximation in (21), we obtain

\[
\mathbb{E}\left[q(\varepsilon^*+)|u_T\right] \approx \frac{\mathbb{E}_{\varepsilon^*_+}\left[q(\varepsilon^*_+) g\left(u_T - \sum_{i=1}^{M} \psi^i \varepsilon^*_T+i\right)\right]}{\mathbb{E}_{\varepsilon^*_+}\left[g\left(u_T - \sum_{i=1}^{M} \psi^i \varepsilon^*_T+i\right)\right]}.
\]

B Sample-based estimator for \( h \)-step ahead forecasts

The joint conditional predictive density (as named by Gouriéroux and Jasiak, 2016) or the causal transition distribution (as named by Gouriéroux and
of the $h$ future values of an $MAR(0,1)$ process, $(u^*_{T+1}, \ldots, u^*_{T+h})$, which is a Markov process of order one, can be obtained given the value of the last observed point $u_T$. While the interest is on predicting the future given contemporaneous and past information, it is only possible, by the model definition, to derive the density of a point conditional on its future point. Bayes’ Theorem is applied repeatedly until all conditional pdf’s are conditioned on the value of future points. The resulting predictive density of an $h$-step ahead forecast is as follows,

$$l(u^*_{T+1}, \ldots, u^*_{T+h}|u_T)$$

$$= l(u_T, u^*_{T+1}, \ldots, u^*_{T+h-1}|u^*_{T+h}) \times \frac{l(u^*_{T+h})}{l(u_T)}$$

$$= \left\{ l(u_T|u^*_{T+1}, \ldots, u^*_{T+h})l(u^*_{T+1}|u^*_{T+2}, \ldots, u^*_{T+h}) \ldots l(u^*_{T+h-1}|u^*_{T+h}) \right\}$$

$$\times \frac{l(u^*_{T+h})}{l(u_T)},$$

(22)

where $l$ denotes densities associated with the noncausal process $u_t$. The process $u_t$ is a Markov process of order one, hence the conditioning information set of the densities can be reduced to a single future point. Furthermore, Equation (2) states that $\varepsilon_t = u_t - \psi u_{t+1}$, thus, given the value of $u_{t+1}$, the conditional density of $u_t$ is equivalent to the density of $\varepsilon_t$ (which is known) evaluated at the point $u_t - \psi u_{t+1}$. Since $u_\tau = \psi u_{\tau+1} + \varepsilon_\tau$ and because $u_{\tau+1}$ and $\varepsilon_\tau$ are independent for all $1 \leq \tau \leq T$, we have $f_{u_\tau|u_{\tau+1}}(x) = f_{\varepsilon_t+\psi u_{t+1}|u_{t+1}}(x) = f_{\varepsilon_t|u_{t+1}}(x - \psi u_{t+1}) = f_{\varepsilon_t}(x - \psi u_{t+1})$. For simplicity, the density distributions related to $u_t$ (resp. $\varepsilon_t$) are just denoted by $l$ (resp. $g$).

In the absence of closed-form expressions for the marginal distributions $l(u^*_{T+h})$ and $l(u_T)$ (when errors are Student’s $t$ distributed for instance), the predictive density (22) can be approximated by substituting them with their sample counterparts using all past realised filtered values of $u_t$ (Gouriéroux and Jasiak, 2016),

$$l(u^*_{T+1}, \ldots, u^*_{T+h}|\mathcal{F}_T)$$

$$\approx g(u_T - \psi u^*_{T+1}) \ldots g(u^*_{T+h-1} - \psi u^*_{T+h}) \frac{N^{-1} \sum_{i=2}^{T} g(u^*_{T+h} - \psi u_i)}{N^{-1} \sum_{i=2}^{T} g(u_T - \psi u_i)},$$

(23)

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C Results

Table 1: Probabilities to remain within the bounds at the forecasted points indicated based on different forecast horizon

| Dates       | Dec-16 | Jan-17 | Feb-17 | Mar-17 | Apr-17 | May-17 | Jun-17 | Jul-17 | Aug-17 | Sep-17 | Oct-17 |
|-------------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|--------|
| 1-month LLS | 0.540  | 0.659  | 0.991  | 0.996  | 0.997  | 0.994  | 0.877  | 0.201  | 0.143  | 0.079  | 0.156  |
| 1-month SIR | 0.542  | 0.660  | 0.996  | 0.997  | 1.000  | 0.996  | 0.921  | 0.271  | 0.194  | 0.121  | 0.188  |
| 3-months LLS| 0.491  | 0.694  | 0.887  | 0.827  | 0.894  | 0.771  | 0.612  | 0.351  | 0.369  |
| 3-months SIR| 0.498  | 0.720  | 0.916  | 0.914  | 0.900  | 0.862  | 0.721  | 0.471  | 0.482  |
| 6-months LLS| 0.500  | 0.580  | 0.663  | 0.664  | 0.671  | 0.628  | 0.580  | 0.663  | 0.664  | 0.671  | 0.628  |
| 6-months SIR| 0.553  | 0.626  | 0.717  | 0.742  | 0.759  | 0.720  | 0.626  | 0.717  | 0.742  | 0.759  | 0.720  |

Probabilities for inflation to remain between the bounds. LLS correspond to the simulations-based approach proposed by Lanne et al. (2012), 1,000,000 were employed. SIR correspond to the sampling importance resampling algorithm based on the sample-based approach proposed by Courtroux and Jasiak, 100,000 simulations were used in the first step, and 10,000 in the resampling step. Shaded columns represent months during which inflation was below the bounds.
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