RiFNet: Automated rib fracture detection in postmortem computed tomography

Victor Ibanez1 · Samuel Gunz1 · Svenja Erne1 · Eric J. Rawdon2 · Garyfalia Ampanozi1 · Sabine Franckenberg1,3 · Till Sieberth1 · Raffael Affolter1 · Lars C. Ebert1 · Akos Dobay1

Accepted: 20 September 2021 / Published online: 28 October 2021 © The Author(s) 2021

Abstract
Imaging techniques are widely used for medical diagnostics. In some cases, a lack of medical practitioners who can manually analyze the images can lead to a bottleneck. Consequently, we developed a custom-made convolutional neural network (RiFNet = Rib Fracture Network) that can detect rib fractures in postmortem computed tomography. In a retrospective cohort study, we retrieved PMCT data from 195 postmortem cases with rib fractures from July 2017 to April 2018 from our database. The computed tomography data were prepared using a plugin in the commercial imaging software Syngo.via whereby the rib cage was unfolded on a single-in-plane image reformation. Out of the 195 cases, a total of 585 images were extracted and divided into two groups labeled “with” and “without” fractures. These two groups were subsequently divided into training, validation, and test datasets to assess the performance of RiFNet. In addition, we explored the possibility of applying transfer learning techniques on our dataset by choosing two independent noncommercial off-the-shelf convolutional neural network architectures (ResNet50 V2 and Inception V3) and compared the performances of those two with RiFNet. When using pre-trained convolutional neural networks, we achieved an $F_1$ score of 0.64 with Inception V3 and an $F_1$ score of 0.61 with ResNet50 V2. We obtained an average $F_1$ score of $0.91 \pm 0.04$ with RiFNet. RiFNet is efficient in detecting rib fractures on postmortem computed tomography. Transfer learning techniques are not necessarily well adapted to make classifications in postmortem computed tomography.

Keywords Deep learning · Convolutional neural networks · Computed tomography · Forensic sciences · PMCT

Introduction
Deep learning (DL) describes a type of machine learning technique mostly used for image classification. Although the technique has existed since the 1980s [1–3], it was only in the last decade that deep learning has attracted more widespread attention. This renewed interest in deep learning originates from the evolution of graphics processing units (GPUs) and their ability to process heavy calculations.

Today, most of the deep learning open-source frameworks take advantage of GPU acceleration for image analysis. Coupled with the burgeoning quantity of data collected through online service providers, deep learning is now widely used in a variety of applications that range from improving user experience to improving medical diagnosis to guiding self-driving vehicles.

DL techniques applied to image analysis consist of convolutional neural networks (CNNs). Features such as edges and ridges are extracted from the data using mathematical filters with various structures. The features are stored in a series of abstract images called feature maps, which are no different from a tensor in their representation. Such a tensor constitutes the basis for the input layer of a fully connected neural network by converting the tensor into a one-dimensional array or vector.

Developments with CNNs have already been made in computed tomography (CT)-based volume measurements of pericardial effusion [4], automated segmentation for CT.
volumes of livers [5], and automated tumor volumetry in brain tumors [6–8]. Two recent reviews on applications of machine learning [9] and deep learning [10] in postmortem forensic radiology constitute a comprehensive reference on the topic.

Rib fractures resulting from blunt force trauma or chest compression due to resuscitation attempts are common and important findings in forensic case assessment. The automation of rib fracture detection on CT images can greatly facilitate the work of forensic radiologists [11], whose ability to detect these fractures may be compromised due to the extremely high volumes of images they need to process in a day [12, 13]. In particular, an autopsy might fail to detect, for example, incomplete rib fractures, making postmortem computed tomography (PMCT) even more valuable [11]. Various groups have applied CNNs to automate fracture detection, including their localization in some cases, on X-ray radiographs, magnetic resonance imaging (MRI) and CT imaging [14–24]. Open-source projects focusing on CNNs such as Inception or ResNet constitute an attractive solution for researchers to implement custom-built models based on existing CNNs that have been previously trained on a large set of images found on the Internet. This is particularly the case in radiology and medical imaging. For instance, Mawatari et al. retrained GoogLeNet to detect hip fractures on pelvic radiographs [17]. In a recent study by Weikert et al., the authors trained a CNN based on the ResNet architecture to detect rib fractures on trauma CT scans [20]. In contrast, Jin et al. [21] decided to introduce a volumetric CNN by customizing U-Net [25], and Hu et al. combined a 2D with a 3D CNN [24]. However, all these studies have been realized with clinical CT data.

Among incomplete rib fractures, it is particularly important to correctly identify so-called “buckle rib fractures”, which are typically symmetrically distributed fractures along the midclavicular lines, commonly observed after cardiopulmonary resuscitation (see Fig. 1a, b, and c for more details) [26]. Thus, the correct detection and classification of rib fractures by a machine learning algorithm can be of both clinical and forensic relevance [27, 28].

CT bone reading is a tool available in the commercial imaging software Syngo.via [29]. The tool can unfold volumetric rib CT data by representing a single-in-plane image reformation of the rib cage. A spider-like image is produced with the vertebral column in the middle, with the 12 ribs distributed on each side. The ribs can be rotated around their

---

**Fig. 1** Rib unfolding. (a) Multi-planar view of a so-called buckle rib fracture (subgroup of incomplete rib fractures). Inset lower left: Rib unfolding view of a buckle rib fracture with no interrupted cortical line but obvious kinking. (b) Multi-planar view of an incomplete rib fracture; outer cortical line interrupted. Inset lower left: Rib unfolding view of an incomplete rib fracture with interrupted cortical line. (c) Multi-planar view of two complete rib fractures in the middle and the back of the rib. Inset lower left: Rib unfolding view of three complete rib fractures. In contrast to the two other fractures (a and b), both cortical lines are interrupted in complete fractures. (d) Rib unfolding with no rib fractures and 12 ribs on either side of the vertebral column. The cross-sectional images (a, b, and c) were extracted with bone window settings (center 450 HU, width 1,500 HU), while the window settings used for the unfolded rib images (d) and the insets (a, b, and c) were 1,000 HU for the center and 2,500 HU for the width.
transversal axis for interpretation. Fractures on one or multiple ribs can therefore be easily visualized on a single image (see Fig. 1d for more details).

The transfer learning technique consists of taking a validated architecture and deploying it to solve another classification problem. With this technique only the last layer (output layer) is modified to match the actual number and type of categories present in the new study. While using transfer learning on our single unfolded reformatted images to detect rib fractures we encountered several limitations. We address them in the Materials and Methods (see the transfer learning section). Due to those limitations, we decided to develop a new architecture.

In this paper, we introduce a specifically designed CNN architecture, called RiFNet (Rib Fracture Network), to improve rib fracture detection in single unfolded reformatted images (see Fig. 2 for a general workflow). To train, validate, and test RiFNet, we performed a retrospective cohort study. We selected a total of 195 cases from July 2017 up to April 2018 from our database. These cases served as a proxy to generate 585 postmortem computed tomography (PMCT) images with and without rib fractures. In comparison, Weikert et al. trained their model on 511 CT images collected between January and December 2018 [20], while Jin et al. collected 7,473 annotated rib fractures from 900 patients during the same period [21]. The performance of our classifier is presented in the Results section. We also compared the performance of our in-house architecture to two standard open-source off-the-shelf CNN architectures. For this purpose, we chose a residual learning network (ResNet50 V2) [30] and an improved version of Inception (Inception V3) [31].
Materials and methods

Ethics

The data used in this retrospective cohort study (retrospective evaluation of medicolegal scan data with new methods, publication in anonymized form) are in accordance with Swiss laws and ethical standards. Ethics approval for this study was waived by the Ethics Committee of the Canton of Zurich (KEK ZH-No. 15–0686).

Case selection

A total of 340 consecutive postmortem cases were retrospectively retrieved from July 2017 up to April 2018 from our database. We excluded (A) cases with signs of advanced decomposition (based on the radiological alteration index (RA-Index) defined by Egger et al. [32]), (B) cases with organ explantation, (C) cases of severe trauma with extensive damage to the corpse such as amputation or exenteration, (D) cases with deviating scanning protocol, (E) cases without PMCT data, (F) cases in which the rib fracture was present in the volumetric CT data and the autopsy, but not visible in the rib unfolding tool or in which the rib defect was in the cartilaginous part of the rib, and (G) cases that are still under investigation. One case was excluded due to a gunshot defect in one of the accessory ribs, which could not be displayed in the rib unfolding tool. Applying the exclusion criteria, a total of 195 remaining cases were included (55 females with a median age of 64 and 140 males with a median age of 54). All these cases underwent whole-body native PMCT and were subjected to standard forensic autopsy. In our final study group, 85 cases showed only acute rib fractures, 84 had no rib fractures, and 26 had old fractures, with or without acute fractures. Both complete and incomplete rib fractures were included, independent of their location. This information was directly derived from the autopsy reports.

Image treatment prior to classification

The value of a single voxel on PMCT images corresponds to the X-ray attenuation relative to water, given in Hounsfield units (HU). Each pixel has a value depth of 12 bits with values ranging from -1,000 (X-ray density of air) to 3,096 HU, with 0 being the X-ray density of water. Extracted images were encoded at a value depth of 8 bits. The technical parameters of the CT scans can be found in Flach et al. [33]. The rib fracture images were extracted from volumetric CT data (see Fig. 1a-d for more details) using the Syngo.via rib unfolding tool CT Bone Reading (Siemens Healthineers GmbH, Erlangen, Germany) with bone window settings (center 450 HU, width 1,500 HU) for the cross-sectional images. The window settings for the unfolding tool were 1,000 HU for the center and 2,500 HU for the width.

Data mining

Imaging findings were used to label each case as either with or without rib fractures. The readout of the CT data and the labeling were performed by a medical student under the supervision of a board-certified forensic pathologist with nine years of forensic imaging experience. The data were retrieved from the multimodality image reading software Syngo.via. Each dataset represented the whole rib cage that was unfolded using the rib unfolding tool CT Bone Reading. In some cases, the reconstruction was insufficient, e.g. following mis-segmentation. Nevertheless, we included these cases as artifacts that have a distinct appearance compared to rib fractures. These images were labeled accordingly depending on whether mis-segmentation occurred on a rib cage with fractures or without fractures. Ringl et al. [29] also observed similar cases of faulty recognition and attempted to correct the segmentation with more than four affected ribs per image. We exported three images for each of the 195 cases, with random axial rib rotations (rotation about the vertical axis) to generate more diversity (data augmentation), and all graphics and lines hidden. The pictures were stored as portable graphic (PNG) documents with a resolution of 500×1,000 pixels. Finally, a total of 255 images with new rib fractures, 252 images without rib fractures, and 78 images with old rib fractures with or without new fractures were collected and used for performance testing.

Model architecture

Our model was developed in Python using the high-level machine learning API Keras (https://keras.io) based on the GPU version of TensorFlow version 2.0 [34]. The model was developed in close collaboration with the team responsible for the data mining (see section data mining above). The first building block of the RifNet architecture is comprised of five convolution layers, each with a max-pooling layer. The number of output filters doubles for each convolution layer from eight to a final number of 128 output filters. For the convolution operation, we used a kernel size of $3 \times 3$, followed by a max-pooling operation with a kernel size of $2 \times 2$. A flattened layer serves as the transition from the first to the second building block. The second building block consists of a fully connected neural network composed of two dense layers with 500 nodes each, a dropout layer with a dropout rate of 0.5, and an output layer. Figure 3 shows the RifNet architecture. To introduce nonlinearity, we used a rectified linear unit (ReLU) activation function for all layers, except the final layer, where we used a sigmoid activation function.
to generate binary output indicating the presence or absence of a fracture. Hence, the current version of our model does not count the number of fractures, nor identify their location. We used the adaptive moment estimation (Adam) algorithm for optimization and the binary cross-entropy loss function. The learning rate was set to 0.00015, and the batch size was set to 15. Our model was trained over 30 epochs. The architectures were trained and tested on an NVIDIA RTX 2080 Titan with 11 GB GDDR6 memory.

**Transfer learning**

As already mentioned in the introduction, transfer learning describes the process of training a custom dataset on a pretrained network. Several approaches exist. The most common process is to retrain the output layer while keeping all the hidden layers frozen. Another option is to specifically train some of the hidden layers. If the computing resources are sufficient, there is the option to completely retrain a pretrained network by unfreezing the whole network and readjusting the weights of the nodes to match the custom dataset more specifically. Here, we applied this technique to compare RiFNet with two standard architectures: Inception V3 [31] and ResNet50 V2 [30]. These two architectures were pretrained on a massive dataset called ImageNet [35] inside TensorFlow and Keras. First, we trained the networks on the original size of our images (500 × 1,000) and then on the downscaled version using OpenCV with a cubic interpolation function (224 × 224 for ResNet50 V2 and 299 × 299 for Inception V3) with all the above-mentioned approaches. These two networks were trained multiple times with a learning rate ranging from 0.001 to 0.000001 and a batch size ranging from 10 to 20 for up to 300 epochs in each training attempt. However, due to the early stopping function implemented in Keras, most of our training sessions stopped before reaching 300 epochs. Inception V3 was compiled with the RMSprop optimizer, while ResNet50 V2 was compiled with the Adam optimizer. Additionally, we added two to four dense layers with 500 nodes each, and a dropout layer with a rate of 0.2 to 0.6.

**Training, validation, and prediction**

For training, validation, and prediction, we selected 252 CT images with no fractures and 255 with fractures. We assessed the robustness of our architecture using a cross-validation approach (Fig. 4). First, we split our data into test data (15%, 77 images) and training/validation data (85%, 430 images). Then, we split the training/validation dataset into five equal parts (folds) with the stratified K-fold function from Keras, where four folds (344 images) represent the training dataset and one-fold (86 images) represents the validation dataset. Both steps were repeated five times, resulting in a total of 25 training, validation, and prediction processes. For MobileNet, we computed the recall, precision and $F_1$ score using the confusion matrix. For RiFNet, we calculated the mean values of the recall, the precision and the $F_1$ score over the whole iteration process, which can be summarized by the following equations:
where m denotes the number of training sessions and n denotes the number of cross-validations.

Results

In a first attempt, we relied on the idea that transfer learning using large pretrained CNNs such as Inception V3 or ResNet50 V2 would be a good strategy. However, this operation requires rescaling the images to the size used to train these CNNs. Training Inception V3 and ResNet50 V2 on our original image size (500 × 1,000) did not work due to a lack of computational power. When we downscaled the images (224 × 224 for ResNet50 V2 and 299 × 299 for Inception V3) and retrained the output layer by keeping the hidden layers unchanged, the validation accuracy remained at approximately 0.5 for all possible combinations of parameters described in the transfer learning section. After allowing the weights of the architecture to be adjusted, we noticed that the networks quickly overfitted our data even before the validation accuracy started to increase. Therefore, by adjusting the weights only on the batch normalization layers, we achieved a recall on unseen test data of 0.63 and 0.61, a precision of 0.65 and 0.62 and an F1 score of 0.64 and 0.61 for Inception V3 and ResNet50 V2, respectively. With RiFNet, we achieved an overall mean recall of 0.93 ± 0.05 and a mean precision of 0.89 ± 0.03, leading to a mean F1 score of 0.91 ± 0.04. Figure 5 shows the training progress, and Fig. 6 the prediction evaluation of RiFNet using violin plots. Table 1 gives an overview of the overall performance analysis. We also tested whether downscaling the images can potentially cause a loss of features (e.g. rib fractures). For this part, we repeated the cross-validation process and trained RiFNet with a lower image size (224 × 224). We found that the mean F1 score dropped by 14% (0.77 ± 0.06).

Discussion

Detection of rib fractures in PMCT is important not only in clinical but also in forensic imaging. We developed a tool based on a CNN architecture that can detect rib fractures on PMCT images. These images were obtained using

Fig. 4 The cross-validation process. A total of 25 independent training sessions were computed using the same dataset to assess the robustness of the RiFNet architecture. This operation was performed by first splitting the whole data into training/validation datasets on one side and testing dataset on the other side (training and testing set labelled 1 to 5). Subsequently, for each training process, the images have been reshuffled in a fivefold cross-validation process. The performance of the architecture was computed by averaging all 25 runs
the rib unfolding tool CT Bone Reading in Syngo.via. The authors who developed the tool reported a higher reader performance and overall sensitivity when using the tool (81.1%) compared to the standard (80.3%) [29]. Based on these results, we estimated that the information on the rib fractures contained in a single-in-plane image reformation of the rib cage is comparable to the standard transverse, coronal, and sagittal orientations. By using RiFNet, we correctly classified 89 out of 100 rib fractures on average, and only five to 13 out of 100 images were incorrectly classified (see Supplementary Fig. S1 for false positive and false negative examples). These results were better than those obtained with two standard open-source off-the-shelf CNN architectures. The discrepancy between Inception V3 and ResNet50 V2 on one side and RiFNet on the other side can be partially explained by the fact that

**Fig. 5** Left: Model accuracy over 30 epochs. For each of the 25 training sessions the training and validation accuracy is plotted, as well as the mean training (max. 1.0) and validation accuracy (max. 0.87).

**Fig. 6** Evaluation of 25 predictions on unseen data viewed as violin plots. RiFNet achieved an overall classification accuracy mean value of 91 ± 4%, a mean F1 score value of 91 ± 4%, a mean precision value of 89 ± 3%, and a mean recall value of 93 ± 5%
Methods to reduce the number of false positives warrant further investigation.

Conclusion

The use of deep learning techniques in medical imaging has gained much momentum in recent years. The constant development of existing frameworks such as TensorFlow, PyTorch, or Keras provides the scientific community with a series of pretrained CNNs. With our current study, we concluded that these pretrained CNNs are not necessarily adaptable for all types of problems encountered in medical imaging, especially with the whole-body PMCT imaging, where it is common to work with large datasets with high resolution to ensure that every anomaly can be detected. Retraining existing CNNs is only possible with substantially more powerful computing resources than those required to deploy the pretrained versions. We addressed this gap by developing a custom-made solution for PMCT imaging.

Key points

1. RiFNet addresses a gap to facilitate the work of forensic radiologists.
2. RiFNet can achieve a classification accuracy of 91%.
3. RiFNet is an easily adaptable solution for postmortem computed tomography images.
4. RiFNet outperforms pretrained ResNet50 V2 and Inception V3.

Supplementary Information The online version contains supplementary material available at https://doi.org/10.1007/s12024-021-00431-8.

Acknowledgements AD and LE express their gratitude to the Emma Louise Kessler Foundation for founding this research. We thank two anonymous referees for their constructive suggestions.

Author contributions VI programmed RiFNet and did the analysis. AD and LE conceptualized the study. AD helped with the analysis and wrote the manuscript. SE and GA selected the cases and prepared the data. SG programmed an earlier version of RiFNet and did part of the analysis. ER did part of the analysis. RA set up the IT infrastructure. Every author contributed to the manuscript.

Funding Open access funding provided by University of Zurich.

Source Code The source code of the model can be made available upon request.

Open Access This article is licensed under a Creative Commons Attribution 4.0 International License, which permits use, sharing, adaptation, distribution and reproduction in any medium or format, as long as you give appropriate credit to the original author(s) and the source, provide a link to the Creative Commons licence, and indicate if changes
were made. The images or other third party material in this article are included in the article’s Creative Commons licence, unless indicated otherwise in a credit line to the material. If material is not included in the article’s Creative Commons licence and your intended use is not permitted by statutory regulation or exceeds the permitted use, you will need to obtain permission directly from the copyright holder. To view a copy of this licence, visit http://creativecommons.org/licenses/by/4.0/.

References

1. LeCun Y. Learning process in an asymmetric threshold network. In: Bienenstock E, Soulié FF, Weisbuch G, editors. Disordered systems and biological organization. NATO ASI Series (Series F: Computer and Systems Sciences). Proceedings. Berlin, Heidelberg: Springer; 1986. 233–40.

2. LeCun Y, Boser B, Denker JS, Henderson D, Howard RE, Hubbard W, et al. Backpropagation applied to handwritten zip code recognition. Neural Comput. 1989;1:541–51.

3. LeCun Y, Bengio Y, Hinton G. Deep learning. Nature. 2015;521:436–44.

4. Ebert LC, Ampanozi G, Ruder TD, Hatch G, Thali MJ, Germert T. CT based volume measurement and estimation in cases of pericardial effusion. J Forensic Leg Med. 2012;19:126–31.

5. Uematsu S, Shimizu A, Watanabe H, Kobatake H, Nawano S. An automated segmentation algorithm for CT volumes of livers with atypical shapes and large pathological lesions. Ieice Trans Info Syst. 2014;E97d:951–63.

6. Gaonkar B, Maccyszyn L, Bilello M, Sadaghati MI, Akbari H, Atthiah MA, et al. Automated tumor volumetry using computer-aided image segmentation. Acad Radiol. 2015;22:653–61.

7. Gibson E, Giganti F, Hu Y, Bonnati E, Bandula S, Gurusamy K, et al. Automatic multi-organ segmentation on abdominal CT with dense v-networks. IEEE Trans Med Imaging. 2018;37:1822–34.

8. Kamnitsas K, Ledig C, Newcombe VFJ, Simpson JP, Kane AD, Menon DK, et al. Automatic multi-organ segmentation on abdominal CT with dense V-networks. Med Im Anal. 2017;36:61–78.

9. Pena-Solorzano CA, Albrecht DW, Based RB, Burke MD, Dimmock MR. Findings from machine learning in clinical medical imaging applications- Lessons for translation to the forensic setting. Forensic Sci Int. 2020;316.

10. Dobay A, Ford J, Decker S, Ampanozi G, Franchenberg S, Affolter R, et al. Potential use of deep learning techniques for postmortem imaging. Forensic Sci Med Pathol. 2020;16:671–9.

11. Schulze C, Hoppe H, Schweitzer W, Schwendener N, Grabherr R, et al. Automatic detection and localization of distal radius fractures: Deep learning system versus radiologists. Eur J Radiol. 2020;126:108925.

12. Kim DH, MacKinnon T. Artificial intelligence in fracture detection: transfer learning from deep convolutional neural networks. Clin Radiol. 2018;73:439–45.

13. Mawatari T, Hayashida Y, Katsuragawa S, Yoshimatsu Y, Hamamura T, Anai K, et al. The effect of deep convolutional neural networks on radiologists' performance in the detection of hip fractures on digital pelvic radiographs. Eur J Radiol. 2020;130.

14. Kitamura G, Chung CY, Moore BE 2nd. Ankle fracture detection utilizing a convolutional neural network ensemble implemented with a small sample, de novo training, and multi-view incorporation. J Digit Imaging. 2019;32:672–7.

15. Burns JE, Yao JH, Munoz H, Summers RM. Automated detection, localization, and classification of traumatic vertebral body fractures in the thoracic and lumbar spine at CT. Radiology. 2016;278:64–73.

16. Weikert T, Noordtzi J, Bremerich J, Stielteps B, Parmar V, Cyriac J, et al. Assessment of a deep learning algorithm for the detection of rib fractures on whole-body trauma computed tomography. Korean J Radiol. 2020;21:891–9.

17. Jin L, Yang J, Kuang K, Ni B, Gao Y, Sun Y, et al. Deep-learning assisted detection and segmentation of rib fractures from CT scans: Development and validation of FraCNet. EBioMedicine. 2020;62.

18. Zhou QQ, Wang J, Tang W, Hu ZC, Xia YZ, Li XS, et al. Automatic detection and classification of rib fractures on thoracic CT using convolutional neural network: accuracy and feasibility. Korean J Radiol. 2020;21:869–79.

19. Meng XH, Wu DJ, Wang Z, Ma XL, Dong XM, Liu AE, et al. A fully automated rib fracture detection system on chest CT images and its impact on radiologist performance. Skeletal Radiol. 2021;50:1821–8.

20. Hu Y, He X, Zhang R, Guo L, Gao L, Wang J. Slice grouping and aggregation network for auxiliary diagnosis of rib fractures. Biomed Signal Process Cont. 2021:67.

21. Ronneberger O, Fischer P, Brox T. U-Net: Convolutional networks for biomedical image segmentation. In: Navab N, Hornegger J, Wells WM, Frangi AF, editors. Medical image computing and computer-assisted intervention – MICCAI. Cham: Springer; 2015. p. 234–41.

22. Yang KM, Lynch M, O’Donnell C. “Buckle” rib fracture: An artifact following cardio-pulmonary resuscitation detected on postmortem CT. Leg Med. 2011;13:233–9.

23. Cattaneo C, Marinelli E, Di Giancamillo A, Di Giancamillo M, Travetti O, Vigano L, et al. Sensitivity of autopsy and radiological examination in detecting bone fractures in an animal model: implications for the assessment of fatal child physical abuse. Forensic Sci Int. 2006;164:131–9.

24. Glemser PA, Pfleiderer M, Heger A, Tremer J, Krauskopf A, Schlemmer HP, et al. New bone post-processing tools in forensic imaging: a multi-reader feasibility study to evaluate detection time and diagnostic accuracy in rib fracture assessment. Int J Legal Med. 2017:131:489–96.

25. Ringli H, Lazar M, Topker M, Woitek R, Prosch H, Asenbaum U, et al. The ribs unfolded - a CT visualization algorithm for fast detection of rib fractures: effect on sensitivity and specificity in trauma patients. Eur Radiol. 2015;25:1865–74.

26. He K, Zhang X, Ren S, Sun J. Deep residual learning for image recognition. Paper presented at the 2016 IEEE Conference on Computer Vision and Pattern Recognition (CVPR). 2016.

27. Szegedy C, Vanhoucke V, Ioffe S, Shlens J, Wojna Z. Rethinking the inception architecture for computer vision. 2016 IEEE Conference on Computer Vision and Pattern Recognition (CVPR). 2016. 2818–26.

28. Egger C, Vaucher P, Doenz F, Palmiere C, Mangin P, Grabherr S. Development and validation of a postmortem radiological alteration index: the RA-Index. Int J Legal Med. 2012;126:559–66.
33. Flach PM, Gascho D, Schweitzer W, Ruder TD, Berger N, Ross SG, et al. Imaging in forensic radiology: an illustrated guide for postmortem computed tomography technique and protocols. Forensic Sci Med Pathol. 2014;10:583–606.

34. Abadi Mi, Barham P, Chen J, Chen Z, Davis A, Dean J, et al. TensorFlow: A system for large-scale machine learning. In: Proceedings of the 12th USENIX Conference on Operating Systems Design and Implementation. USENIX Association. 2016. 265–83.

35. Howard AG, Zhu M, Chen B, Kalenichenko D, Wang W, Weyand T, et al. MobileNets: Efficient convolutional neural networks for mobile vision applications. 2017.

Publisher’s Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.