THE DIRICHLET PROBLEM FOR SUBLINEAR ELLIPTIC EQUATIONS WITH SOURCE

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ABSTRACT. We present a necessary and sufficient condition on nonnegative Radon measures \( \mu \) and \( \nu \) for the existence of a positive continuous solution of the Dirichlet problem for the sublinear elliptic equation \(-\Delta u = \mu u^q + \nu \) with prescribed nonnegative continuous boundary data in a general domain. Moreover, two-sided pointwise estimates of Brezis–Kamin type for positive bounded solutions and the uniqueness of a positive continuous \( L^p \)-solution are investigated.

1. INTRODUCTION

This paper deals with the existence, uniqueness and two-sided pointwise estimates of positive continuous solutions of the Dirichlet problems for sublinear elliptic equations involving nonnegative Radon measures.

Unless otherwise explicitly stated, we always assume that \( \Omega \) is a domain in \( \mathbb{R}^n \) (\( n \geq 2 \)) possessing the Green function \( G_\Omega \) for the Dirichlet Laplacian \(-\Delta \) and that it is regular for the Dirichlet problem for the Laplace equation. When \( \Omega \neq \mathbb{R}^n \), we write \( \delta_\Omega(x) \) for the Euclidean distance from a point \( x \in \Omega \) to the Euclidean boundary \( \partial \Omega \) of \( \Omega \). The boundary and closure of \( \Omega \) in the one point compactification \( \mathbb{R}^n \cup \{\infty\} \) are denoted by \( \partial^\infty \Omega \) and \( \overline{\Omega} \), respectively. By \( \mathcal{M}_+(\Omega) \), we denote the set of all nonnegative Radon measures on \( \Omega \). Also, \( C_+ (\partial^\infty \Omega) \) stands for the set of all nonnegative continuous functions on \( \partial^\infty \Omega \).

Let \( \mu, \nu \in \mathcal{M}_+(\Omega) \) and \( f \in C_+ (\partial^\infty \Omega) \). We consider the Dirichlet problem

\[
\begin{cases}
-\Delta u = \mu u^q + \nu \\
u > 0 \\
u = f
\end{cases}
\quad \text{in } \Omega,
\]

in the sublinear case \( 0 < q < 1 \). It will be understood in the integral sense:

\[
u(x) = G_\Omega [u^q d\mu](x) + G_\Omega [v](x) + H_f(x)
\quad \text{for all } x \in \Omega,
\]

with \( H_f \) being the Perron–Wiener–Brelot solution of the Dirichlet problem

\[
\begin{cases}
\Delta h = 0 \\
h = f
\end{cases}
\quad \text{on } \partial^\infty \Omega,
\]

and \( G_\Omega [\psi d\mu] \) standing for the Green potential of \( \psi d\mu \) defined by

\[
G_\Omega [\psi d\mu](x) := \int_\Omega G_\Omega (x,y) \psi(y) d\mu(y)
\quad \text{for } x \in \Omega.
\]

When \( \psi \equiv 1 \), we simply write \( G_\Omega [\mu] \).

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A variety of classes of solutions of the Dirichlet problem for sublinear elliptic equations with measurable coefficient $a(x)$ and zero boundary values such as

$$
\begin{cases}
-\Delta u = a(x)u^p & \text{in } \Omega, \\
u > 0 & \text{in } \Omega, \\
u = 0 & \text{on } \partial^\infty \Omega,
\end{cases}
$$

have been investigated by many authors. See [2, 5–9, 15, 16, 18–21] for example. Among these, Mâagli and Masmoudi [16] gave a sufficient condition for the existence of a continuous solution of (1.4) in the case where $\Omega$ is an unbounded domain with compact smooth boundary in $\mathbb{R}^n$ ($n \geq 3$). They also gave two-sided pointwise estimates:

$$
c^{-1} \frac{\delta_{\Omega}(x)}{||x||^{n-1}} \leq u(x) \leq cG_\Omega[a](x) \quad \text{for all } x \in \Omega,
$$

where $c > 1$ is a constant. In [5], Brezis and Kamin established a necessary and sufficient condition for the existence of a bounded solution of (1.4) when $\Omega = \mathbb{R}^n$. They also obtained the uniqueness result and the sharp pointwise estimates:

$$
c^{-1} G_{\mathbb{R}^n}[a](x)^{\frac{1}{q-1}} \leq u(x) \leq cG_{\mathbb{R}^n}[a](x) \quad \text{for all } x \in \mathbb{R}^n.
$$

See also Cao and Verbitsky [8, 9], who characterized the existence of a larger class of solutions, satisfying Brezis–Kamin type estimates in terms of Wolff potentials, to similar homogeneous problems (1.4) with the $p$-Laplace and fractional Laplace operators in $\mathbb{R}^n$.

Our first result on (1.1) is related to [16] and [5], but is new even when $\nu \equiv 0$, or $f \equiv 0$, or $\mu, \nu$ are measurable functions. An important notion in our approach is the following Kato type class of measures. By $B(x, r)$, we denote the open ball of center $x$ and radius $r$.

**Definition 1.1.** Let $\mu \in \mathcal{M}_+(\Omega)$. We say that $\mu$ satisfies the $G_\Omega$-Kato condition if

$$
\lim_{r \to \text{d}+} \left( \sup_{x \in \Omega} \int_{B(x, r)} G_\Omega(x, y) \, d\mu(y) \right) = 0,
$$

(1.5)

$$
\lim_{r \to \text{d}+} \left( \sup_{x \in \Omega} \int_{B(0, 1/r)} G_\Omega(x, y) \, d\mu(y) \right) = 0.
$$

(1.6)

Note that (1.6) has no meaning when $\Omega$ is bounded. Also, if $\mu$ satisfies the $G_\Omega$-Kato condition, then $G_\Omega[\mu] \in L^{\infty}(\Omega)$ (see Lemma 2.2). The $G_\Omega$-Kato condition was utilized earlier by the first named author [12] in the study of the Dirichlet problem for $\Delta u = a(x)u^{-p}$ with $p > 0$. In this work, we show that such $G_\Omega$-Kato conditions characterize continuity of the corresponding Green potentials (see Lemma 2.3), and consequently the existence of continuous solutions of (1.1) as follows.

We say that $u$ is minimal in a class $\mathcal{F}$ of positive functions in $\Omega$ if $u \leq v$ in $\Omega$ for any $v \in \mathcal{F}$. For a function $\psi$ defined on a set $E$, we denote by $||\psi||_E$ the usual supremum norm of $\psi$ on $E$.

**Theorem 1.2.** Let $0 < q < 1$. Assume that $f \in C_+(\partial^\infty \Omega)$ and $\mu, \nu \in \mathcal{M}_+(\Omega)$ satisfy

$$
||f||_\infty + ||G_\Omega[\mu]||_\infty + ||G_\Omega[\nu]||_\infty > 0.
$$

(1.7)

Then (1.1) has a solution $u \in C(\overline{\Omega}^\infty)$ if and only if both of $\mu$ and $\nu$ satisfy the $G_\Omega$-Kato condition. Moreover, in this case, (1.1) has a minimal solution in $C(\overline{\Omega}^\infty)$.

Condition (1.7) cannot be removed to ensure the existence of a positive solution. For the sufficiency in Theorem 1.2, we present two different proofs, based on the Schauder fixed point theorem and the method of successive approximations, with the help of equivalent
conditions to the $G_\Omega$-Kato condition, a lower bound estimate for solutions and an iterated inequality for Green potentials established recently by Grigor’yan and Verbitsky [10], which are also useful to show the necessity part of Theorem 1.2.

Needless to say, the continuous solution of (1.1) obtained in Theorem 1.2 is bounded. The next theorem yields in particular the Brezis–Kamin type estimates of such a solution.

**Theorem 1.3.** Let $0 < q < 1$, let $f \in C_+ (\partial^\infty \Omega)$ and let $\mu, \nu \in \mathcal{M}_+(\Omega)$. If $u$ is a bounded solution of (1.1), it enjoys the following estimates.

(i) Lower estimate:

$$u(x) \geq c_1 G_\Omega[\mu](x)^{\frac{1}{1-q}} + G_\Omega[\nu](x) + H_f(x) \quad \text{for all } x \in \Omega.$$  

(ii) Upper estimate:

$$u(x) \leq c_2^q G_\Omega[\mu](x) + G_\Omega[\nu](x) + H_f(x) \quad \text{for all } x \in \Omega.$$  

(iii) Uniform estimate: $\|u\|_\infty \leq c_2$.

Here $c_1 := (1-q)^{\frac{1}{1-q}}$ and $c_2 := \max \left\{ 1, \left( \|G_\Omega[\mu]\|_\infty + \|G_\Omega[\nu]\|_\infty + \|f\|_\infty \right)^{\frac{1}{1-q}} \right\} < +\infty$.

**Remark 1.4.** Note that if (1.1) has a bounded solution, then $G_\Omega[\mu]$ and $G_\Omega[\nu]$ must be in $L^\infty (\Omega)$ in light of (1.2) and Lemma 3.1.

In our present study, we are also interested in integrability properties of continuous solutions of (1.1). The lower estimate in Theorem 1.3 gives a hint of conditions for the existence of a solution in $C(\overline{\Omega}^\infty) \cap L^q(\Omega, d\mu)$. This is related to Verbitsky [21], where the existence of a solution in $L^q(\Omega, d\mu)$ of (1.1) was characterized in terms of $G_\Omega[\mu] \in L^{\frac{q}{1-q}}(\Omega, d\mu)$ in the case where $\mu \equiv 0$ and $\nu \equiv 0$, and to [18, 20], where the second named author and Verbitsky characterized the existence and uniqueness of a solution in $W^{1,2}_0(\Omega) \cap L^q_{\text{loc}}(\Omega, d\mu)$ of (1.1) with $\mu \equiv 0$ in terms of

$$G_\Omega[\mu] \in L^{\frac{1+q}{1-q}}(\Omega, d\mu) \quad \text{and} \quad G_\Omega[\nu] \in L^{1+q}(\Omega, d\mu).$$

Here $W_0^{1,2}(\Omega)$ is the homogeneous Sobolev (or Dirichlet) space defined as the closure of $C_0^\infty (\Omega)$ with respect to the seminorm

$$\|u\|_{W_0^{1,2}(\Omega)} := \|\nabla u\|_{L^2(\Omega)}.$$  

For (1.1) with $\mu \equiv 0$, it was further shown that the existence of a solution in $W_0^{1,2}(\Omega) \cap L^q_{\text{loc}}(\Omega, d\mu)$ is equivalent to the existence of a solution in $L^{1+q}(\Omega, d\mu)$. Note that solutions $u$ of (1.1) with $\mu, \nu$ satisfying the $G_\Omega$-Kato condition do not always satisfy $\|\nabla u\|_{L^2(\Omega)} < +\infty$ (see Corollary 6.4).

**Theorem 1.5.** Under the same assumptions as in Theorem 1.2. Let $\gamma > q$. Then (1.1) has a solution $u \in C(\overline{\Omega}^\infty) \cap L^\gamma(\Omega, d\mu)$ if and only if both of $\mu$ and $\nu$ satisfy the $G_\Omega$-Kato condition and

$$G_\Omega[\mu] \in L^{\frac{q}{\gamma-q}}(\Omega, d\mu), \quad G_\Omega[\nu] + H_f \in L^\gamma(\Omega, d\mu).$$

Moreover, in this case, we have the following.

(i) Problem (1.1) has a minimal solution in $C(\overline{\Omega}^\infty) \cap L^\gamma(\Omega, d\mu)$.

(ii) Assume that either $\gamma = q$ or $\gamma = q + 1$ and $f \equiv 0$ holds. Then (1.1) has exactly one solution in $C(\overline{\Omega}^\infty) \cap L^\gamma(\Omega, d\mu)$. 
This paper is organized as follows. In Section 2, we provide equivalent conditions to the $G_{\Omega}$-Kato condition and prove the equicontinuity of a family of certain Green potentials, which is one of key tools in our approaches. In Section 3, we prove Theorem 1.3. Two different proofs of Theorem 1.2 are given in Section 4. In Section 5, we address the uniqueness of a positive continuous $L^p$-solution and prove Theorem 1.5. In the final section 6, we give supplementary remarks on Hölder continuous solutions and the existence of a positive $C^1$-solution whose Dirichlet integral diverges.

2. Preliminaries

We use the symbol $c$ to denote an absolute positive constant whose value may vary at each occurrence. For two positive functions $f$ and $g$, we write $f \lesssim g$ if $f(x) \leq cg(x)$ for some positive constant $c$ independent of variable $x$.

In the study of the stationary Schrödinger equation $\Delta u = \mu u$ in $\mathbb{R}^n$, Boukricha–Hansen–Hueber [3] gave necessary and sufficient conditions on $\mu \in \mathcal{M}_+(\mathbb{R}^n)$ for $G_{\mathbb{R}^n}[\mu] \in C(\mathbb{R}^n)$. We modify their arguments to provide equivalent conditions to the $G_{\Omega}$-Kato condition. For the sake of convenience, we make the notational convention that $B(z,r) = (\mathbb{R}^n \cup \{\infty\}) \setminus B(0,1/r)$ and

$$
(2.1) \quad \int_{\Omega \cap B(z,r)} G_{\Omega}(x,y) \, d\mu(y) = \int_{\Omega; B(0,1/r)} G_{\Omega}(x,y) \, d\mu(y),
$$

when $z = \infty$. Since $G_{\Omega}(\cdot,y)$ vanishes continuously on $\partial^\infty\Omega$ for each $y \in \Omega$ by the assumption that $\Omega$ is regular for the Dirichlet problem, we note that $G_{\Omega}[\mu]$ is extended to $\overline{\Omega}^\infty$ as a lower semicontinuous function on $\overline{\Omega}^\infty$, by assigning its value 0 on $\partial^\infty\Omega$.

Lemma 2.1. Let $\mu \in \mathcal{M}_+(\Omega)$. Then the following are equivalent:

(a) $\mu$ satisfies the $G_{\Omega}$-Kato condition,

(b) $\lim_{r \to 0^+} \left( \sup_{x \in \Omega} \int_{\Omega \cap B(z,r)} G_{\Omega}(x,y) \, d\mu(y) \right) = 0$ for any $z \in \overline{\Omega}^\infty$,

(c) $\lim_{r \to 0^+} \left( \sup_{z \in \overline{\Omega}^\infty} \left( \sup_{x \in \Omega} \int_{\Omega \cap B(z,r)} G_{\Omega}(x,y) \, d\mu(y) \right) \right) = 0$.

Proof. (a) $\Rightarrow$ (b). Let $z \in \overline{\Omega}$. We see from the domination principle ([1, Theorem 5.1.11]) that

$$
\sup_{x \in \Omega} \int_{\Omega \cap B(z,r)} G_{\Omega}(x,y) \, d\mu(y) = \sup_{x \in \Omega; B(z,r)} \int_{\Omega \cap B(z,r)} G_{\Omega}(x,y) \, d\mu(y)
\leq \sup_{x \in \Omega; B(z,r)} \int_{\Omega \cap B(x,2r)} G_{\Omega}(x,y) \, d\mu(y).
$$

By (1.5), the right hand side goes to zero as $r \to 0^+$. The case $z = \infty$ of (b) is equivalent to (1.6) by our convention (2.1). Hence (b) follows.

(b) $\Rightarrow$ (c). We only consider the case where $\Omega$ is unbounded. An argument below can be modified easily to the case of bounded domains. Let $\varepsilon > 0$. For each $z \in \overline{\Omega}^\infty$, we find $r_z > 0$ such that

$$
\sup_{x \in \Omega} \int_{\Omega \cap B(z,2r_z)} G_{\Omega}(x,y) \, d\mu(y) < \varepsilon.
$$

Since $\overline{\Omega}^\infty$ is compact, there exist $z_1, \ldots, z_{\ell-1} \in \Omega$ and $z_\ell = \infty$ such that $\overline{\Omega}^\infty \subset \bigcup_{i=1}^\ell B(z_i, r_i)$, where $r_i := r_{z_i}$ and $B(z_i, r_i) := (\mathbb{R}^n \cup \{\infty\}) \setminus B(0,1/r_i)$. Let $\delta := \min\{r_1, \ldots, r_\ell, 1/(2r_\ell)\}$.
and let \( w \in \overline{\Omega}^\infty \). Then there is \( j \in \{1, \ldots, \ell\} \) such that \( w \in B(z_j, r_j) \). If \( j \in \{1, \ldots, \ell - 1\} \), then \( B(w, \delta) \subset B(w, r_j) \subset B(z_j, 2r_j) \), and so

\[
\sup_{x \in \Omega} \int_{\Omega \cap B(w, \delta)} \Omega(x, y) d\mu(y) \leq \sup_{x \in \Omega} \int_{\Omega \cap B(z_j, 2r_j)} \Omega(x, y) d\mu(y) < \varepsilon.
\]

If \( j = \ell \), then \( B(w, \delta) \subset (\mathbb{R}^n \cup \{\infty\}) \setminus \overline{B(0, 1/(2r_\ell))} = B(z_\ell, 2r_\ell) \), and so

\[
\sup_{x \in \Omega} \int_{\Omega \cap B(w, \delta)} \Omega(x, y) d\mu(y) \leq \sup_{x \in \Omega} \int_{\Omega \cap B(z, 2r_\ell)} \Omega(x, y) d\mu(y) < \varepsilon.
\]

These yield that

\[
\sup_{w \in \Omega} \left( \sup_{x \in \Omega} \int_{\Omega \cap B(w, \delta)} \Omega(x, y) d\mu(y) \right) < \varepsilon,
\]

and hence (c) follows.

(c) \( \Rightarrow \) (a). This follows by taking \( x = z \in \Omega \) and \( z = \infty \).

As above, the finite covering argument yields the following.

**Lemma 2.2.** Let \( \mu \in \mathcal{M}_+(\Omega) \) satisfy the \( \Omega \)-Kato condition. Then \( G_\Omega[\mu] \in L^\infty(\Omega) \).

The restriction of \( \mu \) to a Borel set \( E \) is denoted by \( \mu|_E \).

**Lemma 2.3.** Let \( \mu \in \mathcal{M}_+(\Omega) \) and \( c_3 > 0 \). Then the following are equivalent:

(a) \( \mu \) satisfies the \( \Omega \)-Kato condition,
(b) \( G_\Omega[\mu|_E] \in C(\overline{\Omega}^\infty) \) for any Borel subset \( E \) of \( \Omega \),
(c) \( G_\Omega[\mu] \in C(\overline{\Omega}^\infty) \),
(d) the family \( \{G_\Omega[\psi d\mu] : \psi \in \Psi\} \) is equicontinuous on \( \overline{\Omega}^\infty \), where

\[
\Psi := \{\psi \in L^\infty(\Omega) : 0 \leq \psi \leq c_3 \text{ a.e. on } \Omega\}.
\]

Moreover, in this case, \( G_\Omega[\psi d\mu] \) vanishes continuously on \( \partial^\infty \Omega \) for each \( \psi \in \Psi \).

**Proof.** (d) \( \Rightarrow \) (c). Trivial.

(c) \( \Rightarrow \) (b). As mentioned in front of Lemma 2.1, \( G_\Omega[\mu|_E] \) has a lower semicontinuous extension to \( \overline{\Omega}^\infty \). Also, \( G_\Omega[\mu|_E] = G_\Omega[\mu] - G_\Omega[\mu|_{\Omega \setminus E}] \) and the right hand side is upper semicontinuous on \( \overline{\Omega}^\infty \). Therefore \( G_\Omega[\mu|_E] \in C(\overline{\Omega}^\infty) \).

(b) \( \Rightarrow \) (a). Let \( z \in \Omega \). Observe that \( \mu(\{z\}) = 0 \) since \( \mu(\{z\})G_\Omega(z, z) \leq G_\Omega[\mu](z) < +\infty \). By the absolutely continuity of integrals, we have

\[
\lim_{r \to 0+} \int_{\Omega \cap B(z, r)} G_\Omega(x, y) d\mu(y) = 0 \quad \text{for each } x \in \overline{\Omega}^\infty.
\]

This is true for \( z \in \partial^\infty \Omega \) by the same reasoning. Since \( G_\Omega[\mu|_{\Omega \setminus B(z, r)}] \in C(\overline{\Omega}^\infty) \) for each \( r > 0 \), the Dini theorem ensures that the convergence in (2.2) is uniform for \( x \in \overline{\Omega}^\infty \). Thus (a) follows from Lemma 2.1.

(a) \( \Rightarrow \) (d). We only consider the case \( \Omega \neq \mathbb{R}^n \). The case \( \Omega = \mathbb{R}^n \) can be handled similarly if replacing \( \delta_\Omega(z) \) to 1 below. Let \( \psi \in \Psi \), let \( z \in \Omega \), let \( 0 < \kappa < 1 \) and let \( \varepsilon > 0 \). Applying the Harnack inequality to the positive harmonic function \( G_\Omega(\cdot, y) \) on \( \Omega \setminus \{y\} \), we see that there exists a function \( c : (0, 1) \to (0, +\infty) \) satisfying \( c(\kappa) \to 0 \) as \( \kappa \to 0 \), and

\[
\frac{1}{1 + c(\kappa)}G_\Omega(z, y) \leq G_\Omega(x, y) \leq \{1 + c(\kappa)\}G_\Omega(z, y)
\]
for all \( x \in B(z, \kappa^2 \delta_\Omega(z)) \) and \( y \in \Omega \setminus B(z, \kappa \delta_\Omega(z)) \). Therefore, for all \( x \in B(z, \kappa^2 \delta_\Omega(z)) \),

\[
\int_{\Omega \setminus B(z, \kappa \delta_\Omega(z))} |G_\Omega(x, y) - G_\Omega(z, y)| \, d\mu(y) \leq c(\kappa)\|G_\Omega[\mu]\|_\infty,
\]

and so by Lemma 2.2,

\[
\int_{\Omega \setminus B(z, \kappa \delta_\Omega(z))} |G_\Omega(x, y) - G_\Omega(z, y)| \, d\mu(y) \leq \frac{\varepsilon}{2},
\]

whenever \( \kappa \) is small enough. Also, it follows from Lemma 2.1 that

\[
\int_{B(z, \kappa \delta_\Omega(z))} G_\Omega(x, y) \, d\mu(y) \leq \frac{\varepsilon}{4} \quad \text{for all } x \in \Omega,
\]

if \( \kappa \) is sufficiently small. These estimates imply that

\[
|G_\Omega[\psi \, d\mu](x) - G_\Omega[\psi \, d\mu](z)| \leq c_3 \int_\Omega |G_\Omega(x, y) - G_\Omega(z, y)| \, d\mu(y) \leq c_3 \varepsilon,
\]

whenever \( x \in B(z, \kappa^2 \delta_\Omega(z)) \) and \( \kappa \) is sufficiently small. Thus \( G_\Omega[\psi \, d\mu] \) is continuous at \( z \) uniformly for \( \psi \in \Psi \). If \( z \in \partial \Omega \), then by Lemma 2.1 there exists \( r > 0 \) such that

\[
\int_{\Omega \cap B(z, r)} G_\Omega(x, y) \, d\mu(y) < \varepsilon \quad \text{for all } x \in \Omega.
\]

Since \( G_\Omega[\mu \, d\mu](z, r) \in C(\overline{\Omega} \cap B(z, r)) \) and vanishes at \( z \), we see that \( G_\Omega[\mu] \) vanishes continuously at \( z \). Hence \( G_\Omega[\psi \, d\mu](x) \to 0 \) uniformly for \( \psi \in \Psi \) as \( x \to z \). In the same way, we can show that \( G_\Omega[\psi \, d\mu](x) \to 0 \) uniformly for \( \psi \in \Psi \) as \( x \to \infty \). Hence (d) is proved.

\section{3. Proof of Theorem 1.3}

The following lower estimate for supersolutions of sublinear elliptic equations and iterated inequality for Green potentials established recently by Grigor’yan and Verbitsky \cite{10} are helpful tools in our approaches.

\textbf{Lemma 3.1 (\cite[Theorem 1.3]{10}).} Let \( 0 < q < 1 \) and \( \mu \in \mathcal{M}_+ (\Omega) \). If \( u \in L_{\text{loc}}^q (\Omega, d\mu) \) is a positive solution of the integral inequality \( u \geq G_\Omega[u^q \, d\mu] \) in \( \Omega \), then

\[
u(x) \geq (1 - q)^{-\frac{1}{q}} G_\Omega[\mu](x)^{\frac{1}{1-q}} \quad \text{for all } x \in \Omega.
\]

\textbf{Lemma 3.2 (\cite[Lemma 2.5]{10}).} Let \( \mu \in \mathcal{M}_+ (\Omega) \) and \( s \geq 1 \). Then

\[
G_\Omega[\mu](x)^s \leq sG_\Omega[G_\Omega[\mu]]^{s-1} \, d\mu(x) \quad \text{for all } x \in \Omega.
\]

\textbf{Proof of Theorem 1.3.} Let \( u \) be any bounded solution of (1.1). Then

\[
u(x) = G_\Omega[u^q \, d\mu](x) + G_\Omega[v](x) + H_f(x) \quad \text{for } x \in \Omega.
\]

Note from the maximum principle that \( H_f(x) \leq \|f\|_\infty \) for \( x \in \Omega \). If \( \|u\|_\infty \geq 1 \), then

\[
\|u\|_\infty \leq \|u\|_{\text{loc}} \|G_\Omega[\mu]\|_\infty + \|G_\Omega[v]\|_\infty + \|f\|_\infty \
\]

\[
\leq \|u\|_{\text{loc}} \left( \|G_\Omega[\mu]\|_\infty + \frac{\|G_\Omega[v]\|_\infty + \|f\|_\infty}{\|u\|_\infty} \right).
\]

Therefore we obtain the uniform estimate \( \|u\|_\infty \leq c_2 \). Substituting this into

\[
u(x) \leq \|u\|_{\text{loc}}^q G_\Omega[\mu](x) + G_\Omega[v](x) + H_f(x) \quad \text{for } x \in \Omega,
\]
we can get the upper estimate. Thanks to Lemmas 3.1 and 3.2, we get the lower estimate
\[ u(x) \geq (1 - q)^{\frac{q}{p}} G_\Omega \left[ G_\Omega [\mu]^{\frac{q}{p}} d\mu \right](x) + G_\Omega [v](x) + H_f(x) \]
(3.2)
\[ \geq (1 - q)^{\frac{q}{p}} (1 - q) G_\Omega [\mu](x)^{\frac{1}{1-q}} + G_\Omega [v](x) + H_f(x), \]
as desired. 

\[ \square \]

4. **Proof of Theorem 1.2**

First, we give a proof of the necessity in Theorem 1.2. For the sufficiency, we present two different proofs based on the Schauder fixed point theorem and the method of successive approximations.

4.1. **A proof of the necessity.**

**Proof of Theorem 1.2 (necessity).** Suppose that (1.1) has a solution \( u \in C(\overline{\Omega}^\infty) \). Then \( G_\Omega [u^q d\mu] = u - G_\Omega [v] - H_f \) on \( \overline{\Omega} \). Since the right hand side is upper semicontinuous on \( \overline{\Omega} \), we have \( G_\Omega [u^q d\mu], G_\Omega [v] \in C(\overline{\Omega}^\infty) \). Appealing to Lemma 2.3, the measures \( u^q d\mu \) and \( v \) satisfy the \( G_\Omega \)-Kato condition. In order to show that \( \mu \) satisfies the \( G_\Omega \)-Kato condition, we need an additional argument. Let \( z \in \overline{\Omega} \) and \( r > 0 \). For the sake of simplicity, we write \( \omega_r := \mu |_{\partial \Omega \cap B(z, r)} \). Using Lemmas 3.1 and 3.2, we get for all \( x \in \Omega \),

\[ G_\Omega [u^q d\omega_r](x) \geq (1 - q)^{\frac{q}{p}} G_\Omega [G_\Omega [\mu]^{\frac{q}{p}} d\omega_r](x) \]
\[ \geq (1 - q)^{\frac{q}{p}} G_\Omega [G_\Omega [\omega_r]^{\frac{q}{p}} d\omega_r](x) \]
\[ \geq (1 - q)^{\frac{q}{p}} G_\Omega [\omega_r](x)^{\frac{1}{1-q}}. \]

Since \( u^q d\mu \) satisfies the \( G_\Omega \)-Kato condition as mentioned above, we have

\[ \lim_{r \to 0^+} \left( \sup_{x \in \Omega} G_\Omega [\omega_r](x) \right) = 0. \]

Therefore, by Lemma 2.1, \( \mu \) satisfies the \( G_\Omega \)-Kato condition as well. 

\[ \square \]

4.2. **A proof based on the Schauder fixed point theorem.** In the rest of this section, we assume that \( \mu, v \in M_+(\Omega) \) satisfy the \( G_\Omega \)-Kato condition. We note from Lemma 2.2 that \( G_\Omega [\mu], G_\Omega [v] \in L^\infty(\Omega) \).

Taking Theorem 1.3 into account, we consider the following function class. Let

\[ w_0(x) := (1 - q)^{\frac{q}{p}} G_\Omega [\mu](x)^{\frac{1}{1-q}} + G_\Omega [v](x) + H_f(x) \quad \text{for } x \in \Omega. \]

We see from (1.7) and the minimum principle that \( w_0 \) is positive on \( \Omega \). With the constant \( c_2 \) defined by (1.8), we let

\[ \mathcal{B} := \{ w \in C(\overline{\Omega}^\infty) : w_0(x) \leq w(x) \leq c_2 \text{ for } x \in \Omega \}, \]

and consider the operator on \( \mathcal{B} \) defined by

\[ T_f[w](x) := \begin{cases} 
G_\Omega [w^q d\mu](x) + G_\Omega [v](x) + H_f(x) & \text{for } x \in \Omega, \\
 f(x) & \text{for } x \in \partial^\infty \Omega.
\end{cases} \]

We equip \( C(\overline{\Omega}^\infty) \) with the uniform norm \( \| \cdot \|_\infty \), so that it is complete. Also, we see that \( \mathcal{B} \) is closed and convex in \( C(\overline{\Omega}^\infty) \).

**Lemma 4.1.** \( T_f[\mathcal{B}] \subset \mathcal{B} \).
Proof. Let \( w \in \mathcal{B} \). Since \( \Omega \) is regular for the Dirichlet problem, we have \( H_f \in C(\overline{\Omega}) \) and \( H_f(x) \to f(\xi) \) as \( x \to \xi \in \partial^\omega \Omega \). This and Lemma 2.3 derive \( T_f[w] \in C(\overline{\Omega}) \). Also, since \( w(x) \geq w_0(x) \geq (1 - q)^{1/2} G_\Omega[\mu](x)^{-1/2} \), we can obtain \( w_0(x) \leq T_f[w](x) \leq c_2 \) for all \( x \in \Omega \) by repeating similar arguments to (3.1) and (3.2). Thus the lemma follows. \( \square \)

**Lemma 4.2.** \( T_f[\mathcal{B}] \) is relatively compact in \( C(\overline{\Omega}) \).

**Proof.** Observe from \( H_f \in C(\overline{\Omega}) \) and Lemma 2.3 that \( T_f[\mathcal{B}] \) is equicontinuous on \( \overline{\Omega} \). Since \( T_f[\mathcal{B}] \) is uniformly bounded by Lemma 4.1, this lemma follows from the Ascoli–Arzelà theorem. \( \square \)

**Lemma 4.3.** \( T_f \) is continuous on \( \mathcal{B} \).

**Proof.** Let \( w_1, w_2 \in \mathcal{B} \). Using the inequality

\[
|a^q - b^q| \leq |a - b|^q \quad \text{for all } a, b \geq 0,
\]

we have for all \( x \in \Omega \),

\[
|T_f[w_1](x) - T_f[w_2](x)| \leq \int G_\Omega(x, y)|w_1(y) - w_2(y)|^q d\mu(y)
\]

\[
\leq \|G_\Omega[\mu]\|_{\infty} \|w_1 - w_2\|_q.
\]

Taking the supremum for \( x \in \Omega \) on the left hand side yields the continuity of \( T_f \) on \( \mathcal{B} \). \( \square \)

**Proof of Theorem 1.2 (sufficiency).** By virtue of Lemmas 4.1, 4.2 and 4.3, we can apply the Schauder fixed point theorem to get \( u \in \mathcal{B} \) satisfying \( T_f[u] = u \) on \( \Omega \). Since \( u(x) \geq w_0(x) > 0 \) for all \( x \in \Omega \), this is the desired one. \( \square \)

### 4.3. A proof based on the method of successive approximations.

An idea of the following proof is based on Verbitsky [21] and the second named author and Verbitsky [18].

**Proof of Theorem 1.2 (sufficiency).** We define a sequence \( \{u_j\} \) inductively by

\[
u_0(x) := (1 - q)^{1/2} G_\Omega[\mu](x)^{1/2},
\]

\[
u_j(x) := G_\Omega[u_{j-1}^q d\mu](x) + G_\Omega[\nu](x) + H_f(x) \quad \text{for } j \in \mathbb{N}.
\]

Then \( u_1 > 0 \) in \( \Omega \) by (1.7). Also, by Lemma 3.2, we have for all \( x \in \Omega \),

\[
u_1(x) \geq G_\Omega[u_0^q d\mu](x) = (1 - q)^{1/2} G_\Omega[\nu][\mu]^{1/2} d\mu(x)
\]

\[
\geq (1 - q)^{1/2} (1 - q) G_\Omega[\mu](x)^{1/2} = u_0(x).
\]

By induction, we see that \( \{u_j\} \) is nondecreasing. Also,

\[
\left\|u_j\right\|_{\infty} \leq \left\|u_{j-1}\right\|_{\infty} \left\|G_\Omega[\mu]\right\|_{\infty} + \left\|G_\Omega[\nu]\right\|_{\infty} + \left\|f\right\|_{\infty} \quad \text{for } j \in \mathbb{N}.
\]

Since \( G_\Omega[\mu], G_\Omega[\nu] \in L^\infty(\Omega) \) by Lemma 2.2, this implies that \( \{u_j\} \subset L^\infty(\Omega) \) and

\[
\left\|u_j\right\|_{\infty} \leq \left\|u_{j-1}\right\|_{\infty} \left\|G_\Omega[\mu]\right\|_{\infty} + \left\|G_\Omega[\nu]\right\|_{\infty} + \left\|f\right\|_{\infty},
\]

which derives \( \|u_j\|_{\infty} \leq c_2 \) by the same way as in (3.1). Therefore \( \{u_j\} \) converges pointwisely to a positive \( u \in L^\infty(\Omega) \). The monotone convergence theorem shows that \( u(x) = G_\Omega[u^q d\mu](x) + G_\Omega[\nu](x) + H_f(x) \) for all \( x \in \Omega \), which also yields \( u \in C(\overline{\Omega}) \) and \( u = f \) on \( \partial^\omega \Omega \) by Lemma 2.3. This completes the proof. \( \square \)

**Remark 4.4.** The solution \( u \) obtained in the above proof is minimal in the sense that \( u \leq v \) in \( \Omega \) for any solution \( v \in C(\overline{\Omega}) \) of (1.1). In fact, \( u_0 \leq v \in \Omega \) by Lemma 3.1, and, in view of the definition of \( u_j \), we can get inductively that \( u_j \leq u \) in \( \Omega \).
5. Proof of Theorem 1.5

We first recall some basic notion of Sobolev spaces (see [11, 17] for example). The Sobolev space $W^{1,2}(\Omega)$ consists of all functions $u \in L^2(\Omega)$ such that $||\nabla u|| \in L^2(\Omega)$, where $\nabla u$ is the vector of weak partial derivatives of $u$ of order 1. The corresponding local space $W^{1,2}_{\text{loc}}(\Omega)$ is the set of all functions $u$ in $\Omega$ such that the restriction $u|_D \in W^{1,2}(D)$ for every relatively compact open subset $D$ of $\Omega$. By $W^{1,2}_0(\Omega)$ and $W^{1,2}_{\text{loc}}(\Omega)$, we denote the closures of $C_0^\infty(\Omega)$ with respect to the usual Sobolev norm and the seminorm $(1.9)$, respectively. Then $W^{1,2}_0(\Omega) \subset W^{1,2}_{\text{loc}}(\Omega) \subset W^{1,2}_{\text{loc}}(\Omega)$. It is known that $u \in W^{1,2}_{\text{loc}}(\Omega)$ has a quasicontinuous representative $\tilde{u}$, namely, $\tilde{u} = u$ a.e. in $\Omega$ and, for each $\varepsilon > 0$, there is an open set $\partial \subset \Omega$ such that $\text{cap}_2(\partial) < \varepsilon$ and the restriction $\tilde{u}|_{\Omega \setminus \partial}$ is finite and continuous on $\Omega \setminus \partial$.

Let $W^{-1,2}(\Omega)$ denote the dual space to $W^{1,2}_0(\Omega)$. The following result is due to Brezis and Browder [4] (cf. [17, Theorem 2.39]).

Lemma 5.1 ([4]). Let $\mu \in W^{-1,2}(\Omega) \cap \mathcal{M}_+(\Omega)$ and $u \in W^{1,2}_0(\Omega)$. Then $\tilde{u} \in L^1(\Omega, d\mu)$ and

$$\langle \mu, u \rangle = \int_{\Omega} \tilde{u} \, d\mu.$$

Lemma 5.2 ([20, Lemma 5.4]). Let $0 < q < 1$ and $\mu, \nu \in \mathcal{M}_+(\Omega)$. Suppose that there exists a positive supersolution $u \in L^q_{\text{loc}}(\Omega, d\mu) \cap W^{1,2}_0(\Omega)$ of $-\Delta u = \mu u + \nu \in \Omega$. Then $-\Delta u \in W^{-1,2}(\Omega) \cap \mathcal{M}_+(\Omega)$ and $\nu \in W^{-1,2}(\Omega)$.

Lemma 5.3. Assumptions are the same as in Theorem 1.5. If $u, v \in C(\overline{\Omega}) \cap L^q(\Omega, d\mu)$ are solutions of $(1.1)$ such that $u \leq v$ in $\Omega$, then $u = v$ in $\Omega$.

Proof. When $\mu(\Omega) = 0$, the equation in $(1.1)$ becomes $-\Delta u = \nu$, and therefore the uniqueness of $(1.1)$ is well known. Let us consider the case $\mu(\Omega) > 0$. Since $u$ and $v$ are bounded and superharmonic in $\Omega$, it follows from [11, Corollary 7.20] that $\tilde{u}, \tilde{v} \in W^{1,2}_{\text{loc}}(\Omega)$ and

$$\int_{\Omega} \nabla \tilde{u} \cdot \nabla \phi \, dx = \int_{\Omega} \tilde{u} \phi \, d\mu + \int_{\Omega} \phi \, dv, \tag{5.1}$$

$$\int_{\Omega} \nabla \tilde{v} \cdot \nabla \phi \, dx = \int_{\Omega} \tilde{v} \phi \, d\mu + \int_{\Omega} \phi \, dv \tag{5.2}$$

for all $\phi \in C_0^\infty(\Omega)$. Note also that $\tilde{u} = f = u$ on $\partial^\infty\Omega$.

Let $D$ be a relatively compact open subset of $\Omega$ which is regular for the Dirichlet problem. Then the restrictions $\tilde{u}, \tilde{v} \in W^{1,2}(D) \cap C(\overline{D})$. Set

$$w := \tilde{u} - H^D_u \quad \text{and} \quad w := \tilde{v} - H^D_u,$$

where $H^D_u$ stands for the Perron–Wiener–Brelot solution of $(1.3)$ with $\Omega = D$ and $f = u$. Note that $w$ and $w$ depend on $D$, as we take limits of those as $D \to \Omega$ at the last step. We see from [11, Corollary 9.29] that $w, \tilde{w} \in W^{1,2}_0(D) \cap C(\overline{D})$ and these are positive in $D$ by the minimum principle. Moreover, since $\Delta (w - \tilde{w}) = \Delta (u - u) = \mu (u - u') \geq 0$ in $D$ in the distributional sense, we have $w \leq \tilde{w}$ in $D$ by the maximum principle. Also, $(5.1)$ and $(5.2)$ yield that for all $\phi \in C_0^\infty(D)$,

$$\int_D \nabla w \cdot \nabla \phi \, dx = \int_D u \phi \, d\mu + \int_D \phi \, dv, \tag{5.3}$$

$$\int_D \nabla \tilde{w} \cdot \nabla \phi \, dx = \int_D u' \phi \, d\mu + \int_D \phi \, dv \tag{5.4}.$$
By Lemma 5.2, we see that Radon measures $\mu^q d\mu$, $u^q d\mu$ and $v$ belong to $\dot{W}^{-1,2}(D)$. Thus Lemma 5.1 ensures that (5.3) and (5.4) are valid for all $\phi \in \dot{W}^{1,2}_0(D) \cap C(D)$. Applying (5.3) with $\phi = w$ and (5.4) with $\phi = w$, we have

$$
\int_D \nabla w \cdot \nabla w \, dx = \int_D u^q w \, d\mu + \int_D w \, dv,
$$

and

$$
\int_D \nabla w \cdot \nabla w \, dx = \int_D u^q w \, d\mu + \int_D w \, dv.
$$

Subtracting in each side, we get

(5.5) 
$$
\int_D (u^q w - u^q w) \, d\mu = \int_D (w - w) \, d\nu \leq 0.
$$

By the definitions of $w$ and $w$, we see that

(5.6) 
$$
\int_D u^q w - u^q w = u^q u^q (u^{1-q} - u^{1-q}) + H_u^D (u^q - u^q) - u^q (H_u^D - H_u^D) \text{ in } D.
$$

Thus, by (5.5) and (5.6),

$$
\int_D u^q u^q (u^{1-q} - u^{1-q}) \, d\mu + \int_D H_u^D (u^q - u^q) \, d\mu \leq \int_D u^q (H_u^D - H_u^D) \, d\mu.
$$

Note that $0 \leq H_u^D (u^q - u^q) \leq \|u\|_{\infty} u^q$ and $0 \leq u^q (H_u^D - H_u^D) \leq \|u - u\|_{\infty} u^q$ in $D$, and $u^q \in L^1(\Omega, d\mu)$ by assumption. Since $H_u^D \to H_u^D = H_u^f$ and $H_u^{1,2} \to H_u = H_f$ as $D$ expands to $\Omega$ (see [1, Theorem 6.3.10]), it follows from the monotone convergence and the Lebesgue dominated convergence theorems that

$$
\int_\Omega u^q u^q (u^{1-q} - u^{1-q}) \, d\mu + \int_\Omega H_f (u^q - u^q) \, d\mu \leq 0.
$$

Both integrands on the left hand side are nonnegative. Therefore $u = u$ $\mu$-a.e. in $\Omega$. By the integral representations (1.2) of $u$ and $u$, we conclude that $u = u$ in $\Omega$. This completes the proof. $\square$

We need the following characterization of weighted norm inequalities established by Verbitsky.

**Lemma 5.4** ([21, Theorem 1.1]). Let $p > 1$, let $0 < r < p$ and let $\mu \in \mathcal{M}_+(\Omega)$. Then there exists a constant $c > 0$ such that

$$
\|G_{\Omega}[\psi \, d\mu]\|_{L^r(\Omega, d\mu)} \leq c \|\psi\|_{L^p(\Omega, d\mu)} \text{ for } \psi \in L^p(\Omega, d\mu)
$$

if and only if $G_{\Omega}[\mu] \in L^{\frac{pr}{p-r}}(\Omega, d\mu)$.

We are now ready to prove Theorem 1.5.

**Proof of Theorem 1.5.** The necessity follows immediately from (1.2) and the lower estimate in Theorem 1.3. Let us show the sufficiency. As in the proof of Theorem 1.2 in Section 4.3, we construct a nondecreasing sequence $\{u_j\}$ converging to a solution $u \in C(\bar{\Omega})$ of (1.1). We claim that $\{u_j\} \subset L^r(\Omega, d\mu)$. In fact, $u_0 \in L^2(\Omega, d\mu)$ by assumption. If $u_{j-1} \in L^2(\Omega, d\mu)$, then Lemma 5.4 with $r = \gamma$ and $p = \frac{\gamma}{\gamma - 1}$ gives

$$
\|u_j\|_{L^r(\Omega, d\mu)} \leq \|G_{\Omega}[u_{j-1}^q \, d\mu]\|_{L^r(\Omega, d\mu)} + \|G_{\Omega}[\nu] + H_f\|_{L^r(\Omega, d\mu)}
$$

$$
\lesssim \|u_{j-1}\|_{L^r(\Omega, d\mu)}^q + \|G_{\Omega}[\nu] + H_f\|_{L^r(\Omega, d\mu)} < +\infty.
$$

Thus the claim follows by induction. Moreover, since $u_{j-1} \leq u_j$, we have in the same manner as in (3.1)

$$
\|u_j\|_{L^r(\Omega, d\mu)} \lesssim (1 + \|G_{\Omega}[\nu] + H_f\|_{L^r(\Omega, d\mu)})^{\frac{1}{\gamma - 1}} < +\infty.
$$
Letting \( j \to +\infty \), we get \( u \in L^7(\Omega, d\mu) \), as desired.

Finally, we show the uniqueness. As mentioned in Remark 4.4, problem (1.1) has a minimal solution \( u \in C(\overline{\Omega}) \cap L^7(\Omega, d\mu) \). Let \( u \in C(\overline{\Omega}) \cap L^7(\Omega, d\mu) \) be any solution of (1.1). Then \( u \leq u \) in \( \Omega \). If \( \gamma = q \), then \( u = u \in \Omega \) by Lemma 5.3. On the other hand, if \( \gamma = q + 1 \) and \( f \equiv 0 \), then \( u = u \in W^{1,2}_0(\Omega) \) by [18, Theorem 1.1]. Therefore \( u = u \) in \( \Omega \) by their continuity and [20, Theorem 6.3]. This completes the proof. \( \square \)

6. REMARKS

In this section, we suppose that the dimension \( n \geq 3 \).

6.1. Hölder continuous solution. Let \( 0 < \alpha < 1 \). By \( C^{0,\alpha}(\Omega) \), we denote the set of all \( \alpha \)-Hölder continuous functions in \( \Omega \). Also, \( C^{0,\alpha}(\Omega) \) stands for the set of all functions \( u \in C^{0,\alpha}(E) \) for every compact subset \( E \) of \( \Omega \).

**Corollary 6.1.** Let \( 0 < q < 1 \), let \( f \in C(\partial^\alpha \Omega) \) and let \( \mu, \nu \in \mathcal{M}(\Omega) \) satisfy (1.6) and (1.7). Assume that there exist \( \alpha \in (0,1) \) and \( c_4 > 0 \) such that the inequality

\[
\omega(B(x,r) \cap \Omega) \leq c_4^{-n-2+\alpha} \quad \text{for all } x \in \Omega \text{ and } r > 0
\]

holds for both of \( \omega = \mu \) and \( \omega = \nu \). Then there exists a solution \( u \in C^{0,\alpha}_{\text{loc}}(\Omega) \cap C(\overline{\Omega}) \) of (1.1).

**Proof.** Using the formula:

\[
\int_{B(x,r)} \|x-y\|^{2-n} d\omega(y) = r^{2-n} \omega(B(x,r)) + (n-2) \int_0^r t^{1-n} \omega(B(x,t)) \, dt,
\]

and \( G_\Omega(x,y) \leq \|x-y\|^{2-n} \), we see from (6.1) that \( \mu \) and \( \nu \) satisfy (1.5). By Theorem 1.2, there exists a solution \( u \in C(\overline{\Omega}) \) of (1.1). Let \( D \) be a relatively compact open subset of \( \Omega \) and let \( \omega := u^\alpha|_D + \nu|_D \). Then the local Riesz decomposition theorem for superharmonic functions shows that there exists a positive harmonic function \( h \) on \( D \) such that \( u(x) = h(x) + G_\mathbb{R}^n[\omega](x) \) for all \( x \in D \). By the way, we have for all \( x \in \mathbb{R}^n \) and \( r > 0 \),

\[
\omega(B(x,r)) \leq \|u\|_{C^{0,\alpha}_{\text{loc}}(B(x,2r))] + \nu(B(x,r) \cap D) \leq cr^{n-2+\alpha},
\]

where a constant \( c \) depends only on \( c_4, q, f, \mu, \nu \). Therefore it follows from [13, Lemma 6.1] that \( G_\mathbb{R}^n[\omega] \in C^{0,\alpha}_{\text{loc}}(D) \), and so \( u \in C^{0,\alpha}_{\text{loc}}(D) \). \( \square \)

6.2. Solution whose Dirichlet integral diverges. Recall that if \( \Omega \) is a bounded Lipschitz domain in \( \mathbb{R}^n \), then there exist positive constants \( c \) and \( \beta \leq 1 \) such that

\[
G_\Omega(x,y) \leq c \left( \frac{\delta_\Omega(x)}{\|x-y\|} \right)^\beta \left( \frac{\delta_\Omega(y)}{\|x-y\|} \right)^\beta \|x-y\|^{2-n} \quad \text{for all } x, y \in \Omega.
\]

See [14, Section 2] for example. If \( \Omega \) has a \( C^{1,1} \)-boundary, then we can take \( \beta = 1 \). For \( \alpha \in \mathbb{R} \), let

\[
d\mu_\alpha(x) := \delta_\Omega(x)^{-\alpha} \, dx.
\]

**Lemma 6.2.** Let \( \Omega \) be a bounded Lipschitz domain in \( \mathbb{R}^n \) \( (n \geq 3) \) and let \( \beta \) be as above. If \( \alpha < 1 + \beta \), then \( \mu_\alpha \) satisfies the \( G_\Omega \)-Kato condition.
\[
\Omega \cap B(x, r) \quad G_\Omega(x, y) \, d\mu (y) \\
= \int_{\Omega \cap B(x, \rho(x))} G_\Omega(x, y) \delta_\Omega(y) \, dy + \int_{\Omega \cap B(x, r) \setminus B(x, \rho(x))} G_\Omega(x, y) \delta_\Omega(y) \, dy \\
=: I_1 + I_2.
\]

If \( \rho(x) = r \), then \( I_2 = 0 \) and

\[
I_1 \lesssim \int_{\Omega \cap B(x, \rho(x))} \|x - y\|^{2-n} \delta_\Omega(y)^{-\alpha} \, dy \lesssim \delta_\Omega(x)^{-\alpha} r^2 \lesssim \begin{cases} r^2 & \text{if } \alpha \leq 0, \\ r^{2-\alpha} & \text{if } \alpha > 0. \end{cases}
\]

We consider the case \( \rho(x) = \delta_\Omega(x)/2 \). Then \( I_1 \lesssim \delta_\Omega(x)^{2-\alpha} \lesssim r^{2-\alpha} \). Let \( N \) be the smallest natural number such that \( r \leq 2^N \delta_\Omega(x) \) and take \( \eta \in \partial \Omega \) so that \( \|\eta - x\| = \delta_\Omega(x) \). Then \( B(x, 2^k \delta_\Omega(x)) \subset B(\eta, 2^{k+1} \delta_\Omega(x)) \) for every integer \( k \geq 0 \). Recall that if \( \tau > -1 \), then

\[
\int_{\Omega \cap B(\xi, R)} \delta_\Omega(x)^{\tau} \, dx \lesssim R^{n+\tau} \quad \text{for } \xi \in \partial \Omega \text{ and } R > 0.
\]

These, together with (6.2), yield that

\[
I_2 \lesssim \int_{\Omega \cap B(x, r) \setminus B(x, \rho(x))} \|x - y\|^{2-n} \delta_\Omega(y)^{\beta-\alpha} \, dy \\
\lesssim \sum_{k=0}^N (2^k \delta_\Omega(x))^{2-n-\beta} \int_{\Omega \cap B(x, 2^k \delta_\Omega(x)) \setminus B(x, 2^{k+1} \delta_\Omega(x))} \delta_\Omega(y)^{\beta-\alpha} \, dy \\
\lesssim \sum_{k=0}^N (2^k \delta_\Omega(x))^{2-n-\beta} (2^{k+1} \delta_\Omega(x))^{n+\beta-\alpha} \\
\lesssim \delta_\Omega(x)^{2-\alpha} \sum_{k=0}^N 2^{k(2-\alpha)} \lesssim r^{2-\alpha}.
\]

Therefore, in any cases, \( \mu_\alpha \) satisfies the \( G_\Omega \)-Kato condition (1.5). \( \square \)

**Lemma 6.3.** Assume that \( \Omega \) is a bounded \( C^{1,1} \)-domain in \( \mathbb{R}^n \) \((n \geq 3)\). Let \( 0 < q < 1 \), let \( \gamma > 0 \) and let \( \alpha \in \mathbb{R} \). Then problem

\[
\begin{cases}
-\Delta u = \mu_\alpha u^q & \text{in } \Omega, \\
u > 0 & \text{in } \Omega, \\
u = 0 & \text{on } \partial \Omega,
\end{cases}
\]

has a solution \( u \in L^q_{\text{loc}}(\Omega) \) with

\[
\int_{\Omega} \|\nabla u\|^2 u^{\gamma-1} \, dx < +\infty
\]

if and only if

\[
\alpha < \frac{2\gamma + 1 + q}{\gamma + 1}.
\]

**Proof.** In light of [18, Theorem 1.1], it suffices to show that

\[
\int_{\Omega} G_\Omega[\mu_\alpha](x)^{\frac{\gamma+q}{\gamma+1}} \, d\mu_\alpha(x) < +\infty \iff \alpha < \frac{2\gamma + 1 + q}{\gamma + 1}.
\]
Suppose to the contrary that $\alpha \geq (2\gamma + 1 + q)/(\gamma + 1)$. Then

$$(2 - \alpha) \frac{\gamma + q}{1 - q} - \alpha \leq -1.$$ 

Since

$$G_\Omega[\mu_\alpha](x) \gtrsim \int_{\Omega \cap B(x, \delta_\Omega(x)/2)} \|x - y\|^{2-n} \delta_\Omega(y)^{-\alpha} dy \gtrsim \delta_\Omega(x)^{2-\alpha}$$

for all $x \in \Omega$, we have

$$\int_{\Omega} G_\Omega[\mu_\alpha](x) \frac{y^q}{y} d\mu_\alpha(x) \gtrsim \int_{\Omega} \delta_\Omega(x)^{(2-\alpha)\frac{y^q}{y} - \alpha} dx = +\infty.$$

Note that $\alpha < 2$. Let $x \in \Omega$. We split $G_\Omega[\mu_\alpha](x) = I_1 + I_2$, where

$$I_1 := \int_{B(x, \delta_\Omega(x)/2)} G_\Omega(x, y) d\mu_\alpha(y),$$

$$I_2 := \int_{\Omega \setminus B(x, \delta_\Omega(x)/2)} G_\Omega(x, y) d\mu_\alpha(y).$$

It is easy to see that $I_1 \lesssim \delta_\Omega(x)^{2-\alpha}$. Also, in a manner similar to the proof of Lemma 6.2, we can estimate $I_2$ as follows. Let $N$ be the smallest natural number such that $\text{diam} \Omega \leq 2^N \delta_\Omega(x)$. Then, by (6.2) with $\beta = 1$,

$$I_2 \lesssim \sum_{k=0}^{N} (2^{k} \delta_\Omega(x))^{-n} \delta_\Omega(x)^{1-\alpha} \int_{B(x, 2^{k} \delta_\Omega(x))} \delta_\Omega(y)^{-\alpha} dy.$$

Therefore $G_\Omega[\mu_\alpha](x) \lesssim F_\alpha(x)$, and so

$$\int_{\Omega} G_\Omega[\mu_\alpha](x) \frac{y^q}{y} d\mu_\alpha(x) \lesssim \int_{\Omega} F_\alpha(x) \frac{y^q}{y} \delta_\Omega(x)^{-\alpha} dx < +\infty.$$

Thus the lemma is proved. \hfill $\Box$

**Corollary 6.4.** Assume that $\Omega$ is a bounded $C^{1,1}$-domain in $\mathbb{R}^n$ ($n \geq 3$). Let $0 < q < 1$, let $\gamma > 0$ and let

$$\frac{2\gamma + 1 + q}{\gamma + 1} \leq \alpha < 2.$$ 

Then (6.3) has a solution $u \in C^1(\Omega) \cap C(\overline{\Omega})$, but fails to have a solution $u \in L^q_{\text{loc}}(\Omega)$ with (6.4).

**Proof.** By Lemma 6.2 and Theorem 1.2, there exists a solution $u \in C(\overline{\Omega})$ of (6.3). Since $\mu_\alpha u^q \in L^\infty_{\text{loc}}(\Omega)$, we observe that $u \in C^1(\Omega)$. The second assertion follows from Lemma 6.3. \hfill $\Box$

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