Resonant Directly Coupled Inductors–Capacitors Ladder Network Shows a New, Interesting Property Useful for Application in the Sensor Field, Down to Micrometric Dimensions

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Abstract: The study of ladder networks made by sequences of directly coupled inductor–capacitor single cells has led us to discover a new property, which may be of certain interest in the sensor field. In the case of n cells, the n-frequencies vector characterizing each node may allow for the identification of that capacitor (sensor), which has experienced a variation of its nominal value. This localization is possible independently from the observable node of the ladder network as proven by the application of the following multivariate data analysis techniques: principal component analysis and partial least square discriminant analysis. This property can be applied on a large scale down to micrometric dimensions in agreement with the technologic ability to shrink the capacitive sensor dimensions.

Keywords: ladder networks; capacitive sensor; sensor network; fingerprint; data analysis

1. Introduction

Passive ladder networks (L.N.s) made by a number of single cells showing both longitudinal and transversal impedances have been studied for a long time [1–6] due to their versatility in representing a good model for mechanical, chemical, thermal, and electronic systems and also because they have been frequently employed in passive filters [7,8]. In fact, the representation of complex dynamic systems by using the analogy of electrical networks has proven to be very useful in the realization of interfaces for monitoring integrated sensors, sensor systems, and microstructures, especially when the sensors work at the micro-dimensional level. In this analogy, the role of sensor activity is played by those electronic components, which present measurable time variability, such as inductors or capacitors. These kinds of electrical networks are called inductor–capacitor (L–C) networks and are often used in modeling a particular kind of information transmission. When the inductor (L) and capacitor (C) elements represent sensors operating in a real scenario, the content of each variation is a part of global
information conveyed by the whole network of electro-mechanical sensors. The interest in L.N.s today is still alive due to new applications, for example, in analog neural networks. Furthermore, we cannot exclude in the near future their possible implications in the study of the electric behavior of both DNA and RNA structures [9] and related aspects of epigenomics.

This paper, on the other hand, also considers these kinds of networks from another viewpoint: the search of the presence of links with Fibonacci numbers. In many cases these famous numbers are present as expression of impedances, voltages, and currents and may facilitate the rapid calculation of their amplitudes [4].

The particular structure of the directly coupled L–C single cell L.N. shows very strong peculiarities, which are shown in Figure 1, reported below, and taken from D’Amico et al. [5].

In the vertical axes we have, for example, the number of L–C cells from 1 to 100. In the horizontal axes, we have the normalized frequencies, which means that in the case of only one cell \( \omega_1 = 1/\sqrt{LC} \) is taken equal to 1. In the case of two L–C cells, the normalized \( \omega \) becomes \( \omega_1 = 0.618 \ldots \) and \( \omega_2 = 1.618 \ldots \) (which do represent the golden section and the golden ratio, respectively) and so on. Another interesting property is represented by the fact that these two frequencies are also present in the case of 7, 12, 17, 22 . . . and so on cells (i.e., starting from two cells the two solutions are present according to a period of five cells). Furthermore, the transfer function of this kind of L–C L.N. has the property to show all the \( \omega \)-solutions only in the normalized interval defined by 0 and 2 (as shown in Figure 1). Another property of this L–C L.N. can be seen by looking at this figure while partly shutting one’s eyes. It is possible to see many channels (finite number) that become narrower and narrower by increasing the number of cells. These are the forbidden bands similar to those that we have in a 1-dimensional (1D) array of atoms. This means that whatever the number of cells, the solutions \( \omega_1 \) will never enter these bands.

The novelty in this paper concerns the identification of a new property related to the L–C L.N. that can be of a certain utility in the field of sensor network. In this case we have imagined dealing with capacitive sensors for either mechanical or chemical quantities. In fact, measuring the frequencies vector in only one of the randomly selected nodes of a given L–C L.N., we have found that it is possible to determine the capacitor that has changed its value due to a given sensing action. Of course, the same property is evident if we consider the inductors as sensors. The result is the same due to the fact that the transfer function of this network is related to the ratio (K) between the longitudinal \( Z_1 = j\omega L \) and transversal impedance \( Z_2 = 1/j\omega C \).

In fact, being that \( K = \omega^2 LC \), the same changes of either C or L (not simultaneous changes) will produce the same result.
In this paper, we have investigated, as an example, the transfer function of seven L–C cells directly coupled forming a discrete L.N. and found a new interesting property useful for applications in the field of sensors. In fact, surprisingly, each node brings the information of each cell, and when one capacitor of a cell is changed, then the voltages in the seven nodes change also. Of course, each one changes in a different way, but the identification of the modified cell can be performed whatever the testing node. This new property is found to be of interest for the control of sensorial multi-points: this attitude is strategic when applied to the monitoring of networks developed at the micrometric level, when the ‘interrogation’ and the localization of the ‘sensor-points’ could be not so easy. We have estimated the resolution of this system as a final contribution to the knowledge of this peculiar discrete network. Definitively, the purpose of this work is the study of useful electrical properties of directly coupled L–C cells forming a discrete ladder network (L–C L.N.) to be applied to the sensor field.

2. Materials and Methods

A typical L–C L.N. is shown in Figure 2.

![Ladder network formed by n-L–C elementary cells.](image)

Figure 2. Ladder network formed by n-L–C elementary cells.

As shown in the literature [6], the transfer function of this L–C L.N., whatever the number of cell, can be easily determined by the use of the DFF triangle [4], which gives the modules of the coefficients of the polynomial at the denominator of the transfer function.

In the same paper, it is shown the following expression, which gives the voltage $V_b$ in each node $β$ of a n-length L.N. where $k(s)$ is the ratio of $Z_1/Z_2$ in the Laplace domain.

$$V_b = \frac{\sum_{j=0}^{n-\beta} b(n-\beta, j)k^j(s)}{\sum_{j=0}^{n} b(n, j)k^j(s)}V_{in} \quad (1)$$

This triangle is here reported in Table 1 and is framed to give the coefficients for a seven-cell L.N. (Figure 3), which is the number taken into account in this paper for the demonstration of the new property of this L.N.

Table 1. DFF triangle for a seven-cell L.N.

| Cell # | $X^0$ | $X^2$ | $X^4$ | $X^6$ | $X^8$ | $X^{10}$ | $X^{12}$ | $X^{14}$ |
|--------|-------|-------|-------|-------|-------|----------|----------|----------|
| 0      | 1     | -     | -     | -     | -     | -        | -        | -        |
| 1      | 1     | -1    | -     | -     | -     | -        | -        | -        |
| 2      | 1     | -3    | 1     | -     | -     | -        | -        | -        |
| 3      | 1     | -6    | 5     | -1    | -     | -        | -        | -        |
| 4      | 1     | -10   | 15    | -7    | 1     | -        | -        | -        |
| 5      | 1     | -15   | 35    | -28   | 9     | -1       | -        | -        |
| 6      | 1     | -21   | 65    | -84   | 45    | -11      | 1        | -        |
| 7      | 1     | -28   | 121   | -205  | 165   | -66      | 13       | -1       |
In order to obtain a general model to be used for any kind of L–C network with n-cell, a bottom-up strategy has been used, starting from the analysis of a single L–C cell. The starting condition (assumed as a reference) for this cell is given by the following values: \( L = 68 \text{ uH} \) and \( C = 47 \text{ nF} \) (see Figure 4).

Studying the transfer function of this cell and simulating the relative electronic circuit in MultiSim (National Instruments, Austin, TX, USA), we obtain the magnitude curve (Figure 5), which confirms the following theoretical resonance frequency:

\[
 f = \frac{1}{2\pi \sqrt{LC}} = \frac{1}{2\pi \sqrt{68 \times 10^{-6} \times 47 \times 10^{-9}}} = 89.02\text{KHz}
\]  

This frequency is characteristic of the elementary cell (Figure 5), and the calculus is here implemented for a n-cell ladder network.
3. Results

3.1. Fibonacci Relations in the L–C L.N.

In the case of seven L–C L.N. cells, we have the following denominator for the transfer function:

\[- \omega^{14} L^7 C^7 + 13 \omega^{12} L^6 C^6 - 66 \omega^{10} L^5 C^5 + 165 \omega^8 L^4 C^4 - 205 \omega^6 L^3 C^3 + 121 \omega^4 L^2 C^2 - 28 \omega^2 L C + 1 \tag{3}\]

which must be set equal to zero in order to determine the seven solutions. The seven solutions are represented by the seven resonant frequencies obtained by the following relationship [6]:

\[\omega^{(n)} = 2 \sin \left( \frac{(2i - 1)\pi}{(2n + 1)} \right) \tag{4}\]

where \( n \) represents the number of L–C cells, and \( i = 1, 2, \ldots, n \).

As a consequence, according to Equation (4), the normalized solutions are the following:

\[\omega_1 = 0.20906; \omega_2 = 0.61903; \omega_3 = 1; \omega_4 = 1.33832; \omega_5 = 1.61803; \omega_6 = 1.82713; \omega_7 = 1.9659.\]

In this kind of L–C L.N. we have noticed that starting from the case of two or more cells (5, 7, 12, 17, 22, \ldots) we always get, among the others, the following two solutions: the golden ratio, \( \phi = 1.618 \) and the gold section, \( 1/\phi = 0.618 \). So, even in the case under test, we have these two particular frequencies, which are related to the Fibonacci numbers, as expressed by the following relationships:

\[\phi = \log_{\infty} F_n / F_{(n-1)} \tag{5}\]

\[1/\phi = \log_{\infty} F_{(n-1)} / F_n \tag{6}\]

3.2. Sensor Localization Based on Frequency Patterns

When one of the capacitors (representing a sensor for instance) is for some reason changed (e.g., the third in the L.N. of Figure 7), all the frequency patterns of the L–C L.N. will change as a consequence.
of the variation of its transfer function. Depending on the node where the output is read, we will have a different set of frequencies.

![Figure 7. The L–C seven-cell L.N. with a variation of C in the third cell.](image)

We now prove that it is possible, whatever the observed node, to localize the transversal impedance, which has changed.

This unexpected property can be of a high utility in the sensor field where a sensor network made by capacitive sensors has to be kept under control independently from the observation point.

This property has been studied by principal component analysis (PCA) in order to have a sound description of it.

Table 2 shows the first step of the analysis: the array of the characteristic frequencies of the L–C L.N. in the standard condition taken as reference (without any variation of the values of L and C). The characteristic frequencies given by the seven poles (first 7 columns of the array reported in Table 2) and given by the six zeros (the last 6 columns reported in Table 2) have been calculated for each cell (the seven rows of the array reported in Table 2).

Table 2. Array of the poles and zeros (in KHz) of the transfer function of the circuit in Figure 6. The colors used for some of the ‘zero’ values reported in the cells are here used to put in evidence the cancellation action of zeros and poles coincidence; thus, each couple of identical color (orange, red, yellow) corresponds to a couple of coincident pole–zero.

| Poles | Cell # | P1   | P2   | P3   | P4   | P5   | P6   | P7   |
|-------|--------|------|------|------|------|------|------|------|
| 1     | 18.61  | 55.01| 89.02| 119.15| 144.04| 162.66| 174.18|
| 2     | 18.61  | 55.01| 89.02| 119.15| 144.04| 162.66| 174.18|
| 3     | 18.61  | 55.01| 0    | 119.15| 144.04| 162.66| 174.18|
| 4     | 18.61  | 55.01| 89.02| 119.15| 144.04| 162.66| 174.18|
| 5     | 18.61  | 0    | 89.02| 119.15| 144.04| 162.66| 174.18|
| 6     | 18.61  | 55.01| 0    | 119.15| 144.04| 162.66| 174.18|
| 7     | 18.61  | 55.01| 89.02| 119.15| 144.04| 162.66| 174.18|

| Zeros | Cell # | Z1   | Z2   | Z3   | Z4   | Z5   | Z6   |
|-------|--------|------|------|------|------|------|------|
| 1     | 21.46  | 63.13| 101.13| 133.26| 157.65| 172.86|
| 2     | 25.33  | 73.96| 116.60| 0    | 149.79| 170.84|
| 3     | 30.91  | 0    | 136.39| 0    | 160.43| 0    |
| 4     | 39.61  | 0    | 111.01| 0    | 0    | 0    |
| 5     | 0      | 0    | 0    | 0    | 0    | 0    |
| 6     | 0      | 0    | 0    | 0    | 0    | 0    |
| 7     | 0      | 0    | 0    | 0    | 0    | 0    |
Each row of the array in Table 2 is a pattern of frequencies, which is characteristic of the adopted configuration. These seven patterns show seven different magnitude plots (reported in Figure 8) with seven different colors. Each plot represents the behavior of the magnitude of the transfer function of the whole network when read by the $i$th cell ($i = 1, \ldots, 7$).

![Figure 8. Magnitude plots vs frequency of the seven patterns readable by the seven nodes of the seven cells of the L–C L.N.](image)

Thus, when C and L values are ‘static’ (meaning: fixed values), the $7 \times 13$ array representing the system is a static picture (Table 3). But, when the system is ‘dynamic’ because some elements are modified, how is the array modified? Is it possible to monitor and localize this variation by automatically checking the array variability with respect to the reference ‘picture’?

| Cell # | P1   | P2   | P3   | P4   | P5   | P6   | P7   |
|--------|------|------|------|------|------|------|------|
| 1      | 18.77| 55.44| 89.61| 119.72| 144.51| 162.92| 174.22|
| 2      | 18.77| 55.44| 89.61| 119.72| 144.51| 162.92| 174.22|
| 3      | 18.77| 55.44| 89.61| 119.72| 144.51| 162.92| 174.22|
| 4      | 18.77| 55.44| 89.61| 119.72| 144.51| 162.92| 174.22|
| 5      | 18.77| 55.44| 89.61| 119.72| 144.51| 162.92| 174.22|
| 6      | 18.77| 55.44| 89.61| 119.72| 144.51| 162.92| 174.22|
| 7      | 18.77| 55.44| 89.61| 119.72| 144.51| 162.92| 174.22|

To test this condition, the value of the capacitor of the third cell has been decreased, as an example, from 47 nF to 44 nF. Figure 9 shows the shift of the magnitude pattern given by this variation.

| Zeros |
|-------|
| Cell # | Z1   | Z2   | Z3   | Z4   | Z5   | Z6   |
|--------|------|------|------|------|------|------|
| 1      | 21.67| 63.69| 101.85| 133.87| 158.01| 172.98|
| 2      | 25.63| 74.69| 117.4| 0     | 150.34| 171  |
| 3      | 31.35| 0    | 90.01| 137.24| 0     | 167.61|
| 4      | 40.31| 0    | 112.3| 0     | 161.02| 0    |
| 5      | 0    | 56.33| 0    | 0     | 145.41| 0    |
| 6      | 0    | 0    | 92   | 0     | 0     | 0    |
| 7      | 0    | 0    | 0    | 0     | 0     | 0    |

$\text{Table 3. Array of the poles and zeros of the transfer function of the circuit in Figure 5 when the capacitance at node 7th has been changed from 47 nF to 44 nF.}$
Each row of the array in Table 2 is a pattern of frequencies, which is characteristic of the adopted configuration. These seven patterns show seven different magnitude plots (reported in Figure 8) with seven different colors. Each plot represents the behavior of the magnitude of the transfer function of the whole network when read by the \( i \)-th cell (\( i = 1, \ldots, 7 \)).

Figure 8. Magnitude plots vs frequency of the seven patterns readable by the seven nodes of the seven cells of the L–C L.N.

Thus, when \( C \) and \( L \) values are 'static' (meaning: fixed values), the \( 7 \times 13 \) array representing the system is a static picture (Table 2). But, when the system is 'dynamic' because some elements are modified, how is the array modified? Is it possible to monitor and localize this variation by automatically checking the array variability with respect to the reference 'picture'?

To test this condition, the value of the capacitor of the third cell has been decreased, as an example, from 47 nF to 44 nF. Figure 9 shows the shift of the magnitude pattern given by this variation.

Figure 9. Comparison of the magnitude plots vs frequency of the patterns readable at the seventh node of the L–C L.N. when the capacitance at the 7th cell shifts from 47 nF to 44 nF.

Now it is possible to obtain the array of the resonance frequencies for each node of the L.N. by varying each capacitor of the L.N. Table 4 reports an example: the array given by the variation of the capacitor in the 7th cell. This array is given by reading each node of the L.N.

Table 4. Root-mean-square error in cross validation (RMSECV) in the identification of the capacitance shifts (from \( C_1 \) to \( C_7 \)), as obtained from the partial least square discriminant analysis (PLS-DA) model by using the leave-one-out cross-validation criterion. Each row of the table reports the node (the point of observation for monitoring the 'sensor' variation) in the first column and the minimum detectable variation in that node, in the second column.

| Node | RMSECV [nF] |
|------|-------------|
| 1    | 0.36        |
| 2    | 0.19        |
| 3    | 0.17        |
| 4    | 0.31        |
| 5    | \( 2.08 \times 10^{-6} \) |
| 6    | 0.16        |
| 7    | 0.20        |

In Figure 10, three examples of the magnitude plot shifting for three different conditions: (a) \( C \) shift in cell 1 read by node 1; (b) \( C \) shift in cell 2 read by node 2; and (c) \( C \) shift in cell 5 read by node 5.

Using multivariate data analysis techniques, it is possible to face the complexity of the information content of the \( 7 \times 13 \) arrays. This approach allows the reduction of the problem dimension and the representation of a multidimensional issue on a 2- or 3-dimensional plane, which can effectively map the L.N. conditions. Principal component analysis is the simplest explorative (unsupervised) method to obtain this 'map'. The PCA elaboration of the seven-cell L–C L.N. of Figure 5 has given the scores plot reported in Figure 11.

The scores plot in Figure 11 appears to be like a map of the L.N.: the central 'corridor' is the reference condition of the L.N. corresponding to the starting value of 47 nF for the capacitor. Along the PC2, the shift of the \( C \) value is mapped, either increasing (towards the upper portion of the plot) or decreasing (towards the lower portion of the plot) the value of \( C \). Along the PC1, it is possible
to localize the cell. This ‘mapping’ action is better represented in Figure 12, where the same plot of Figure 11 is repeated with a figurative representation of the localization action, which can be performed using the PCA model of Figure 11 in finding out the variation that occurred.

![Figure 10](image-url)

**Figure 10.** Magnitude plot shifting for three different conditions: (a) C shift in cell 1 read by node 1; (b) C shift in cell 2 read by node 2; and (c) C shift in cell 5 read by node 5.

### Table 2

Array of the poles and zeros of the transfer function of the circuit in Figure 5 when the capacitance at node 7th has been changed from 47 nF to 44 nF.

| Cell # | P1          | P2          | P3          | P4          | P5          | P6          | P7          |
|--------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|
| 1      | 18.77       | 55.44       | 89.61       | 119.72      | 144.51      | 162.92      | 174.22      |
| 2      | 18.77       | 55.44       | 89.61       | 119.72      | 144.51      | 162.92      | 174.22      |
| 3      | 18.77       | 55.44       | 89.61       | 119.72      | 144.51      | 162.92      | 174.22      |
| 4      | 18.77       | 55.44       | 89.61       | 119.72      | 144.51      | 162.92      | 174.22      |
| 5      | 18.77       | 55.44       | 89.61       | 119.72      | 144.51      | 162.92      | 174.22      |
| 6      | 18.77       | 55.44       | 89.61       | 119.72      | 144.51      | 162.92      | 174.22      |
| 7      | 18.77       | 55.44       | 89.61       | 119.72      | 144.51      | 162.92      | 174.22      |

| Cell # | Z1          | Z2          | Z3          | Z4          | Z5          | Z6          |
|--------|-------------|-------------|-------------|-------------|-------------|-------------|
| 1      | 21.67       | 63.69       | 101.85      | 133.87      | 158.01      | 172.98      |
| 2      | 25.63       | 74.69       | 117.4       | 0           | 150.34      | 171         |
| 3      | 31.35       | 0           | 90.01       | 137.24      | 0           | 167.61      |
| 4      | 40.31       | 0           | 112.3       | 0           | 161.02      | 0           |
| 5      | 0           | 56.33       | 0           | 0           | 145.41      | 0           |
| 6      | 0           | 0           | 92          | 0           | 0           | 0           |
| 7      | 0           | 0           | 0           | 0           | 0           | 0           |

### Table 3

Root-mean-square error in cross validation (RMSECV) in the identification of the capacitance shifts (from C1 to C7), as obtained from the partial least square discriminant analysis (PLS-DA) model by using the leave-one-out cross-validation criterion. Each row of the table reports the node (the point of observation for monitoring the 'sensor' variation) in the first column and the minimum detectable variation in that node, in the second column.

| Node | RMSECV [nF] |
|------|-------------|
| 1    | 0.36        |
| 2    | 0.19        |
| 3    | 0.17        |
| 4    | 0.31        |
| 5    | 2.08 × 10^{-6} |
| 6    | 0.16        |
| 7    | 0.20        |
**Figure 11.** Score plot of the first two PCs of the principal component analysis (PCA) model built in the $7 \times 13$ data array of resonance frequency of the seven-cell L–C L.N. of Figure 5.

**Figure 12.** Representation of the localization action, which can be performed using the PCA model of Figure 11 in finding out the variation that occurred.

**Figure 11.** Score plot of the first two PCs of the principal component analysis (PCA) model built in the $7 \times 13$ data array of resonance frequency of the seven-cell L–C L.N. of Figure 5.

**Figure 12.** Representation of the localization action, which can be performed using the PCA model of Figure 11 in finding out the variation that occurred.
Considering the capability of the multivariate model to follow also the increasing/decreasing of the C value supposed to be modified, a supervised technique could be applied in order to test the performance of the model in the quantification of this change. A partial least square model has been calculated on the L.N., and the root-mean-square error in cross validation (RMSECV) has been estimated by applying the leave-one-out criterion. The rather interesting results are reported in Table 4. The RMSECV confirms the capability of the system to detect variations of capacitance down to $10^{-6}$ nF; thus, it could be used in the management of sensors with optimal resolution power, which is crucial when monitoring very small deviations of micrometric sensors’ responses.

4. Conclusions

Ladder networks have been employed in many applications in the engineering context, and in this paper, we have shown that another important property can be attributed to them in the special case when the L.N. is formed by longitudinal inductors and transversal capacitors.

The results obtained in this work demonstrate that one of the transversal elements, capacitors in this example, can be univocally identified by using the arrays of the resonance frequencies, which can be easily determined by the transfer function of the L.N. itself. Moreover, by analyzing these arrays with multivariate data analysis technique, it is possible to localize the element where in the L.N. the variation is occurring and to quantify this variation independently from the observation node. The model here presented has a general validity and can be used for any kind of network as far as the number of cells is concerned.

This method could be of particular utility in cases of complex network configurations, when the identification of the variation of single sensorial element is not easy, such as in the case of sensor networks operating at the micrometric dimensional level. Of course, there is an important aspect to be considered when dimensions of sensors are reduced, which deals with the possibility of keeping the overall performance analysis when operating frequencies become higher and higher. The identification of limits in this direction is a challenge for near-future technological work. Moreover, whenever the L.N. represents a sensor network, an automated localization system based on such model could be useful to speed up the identification process and the potential warning activation, especially in case of hazardous or extended areas.

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