Numerical simulation of solid - liquid two - phase flow deposition on the surface of tube bundle

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Abstract. Based on finite volume method, the Reynolds number of fluid affecting solid-liquid two phase deposition on the outer surface of tubes has been predicted. A 3D geometric model of fluid flow cross tube bundles is established. The particle trajectory was tracked by Euler - Lagrange model. The results show that: different Reynolds number of fluid impact dynamic pressure which is consistent with the distribution of fouling deposition. That is to say, dynamic pressure can be treated as indicator when monitor the fouling deposition on the surface of tube bundle. The deposition rate of particles is positively correlated with dynamic pressure. In addition, based on this geometry model, with the increment of Reynolds number, average accretion rate tend to stabilize to $\frac{\Delta p}{\Delta t}$, rather than increase indefinitely. The location of the most serious accretion rate is always on the joint between the pipe and the shell, especially, on the surface of windward.

1. Introduction
It is reported that 90% of heat exchangers occur fouling deposition with different degree [1]. The fouling of boiler or heat exchanger is a substance that is attached to the heating surface in solid form. According to the main chemical composition, scaling is divided into calcium and magnesium scale, silicate scale, iron oxide scale, copper scale and phosphate scale. In this study, calcium carbonate is selected to be main scaling. The calcium carbonate scale deposited on the equipment in the form of dense crystal. The fouling accumulates on the heat transfer surface. Comparing to metal, owing to low thermal conductivity, fouling reduces the heat transfer coefficient severely. The selection of fouling characteristics often depends on the experience of field operation which is inaccurate to reflect the real situation of scaling in the heat exchanger. Tubular heat exchanger is a kind of general heat exchanger which consists of shell and tube. When the fluid is swept across the tube bundles, the solid particles will have a serious deposition effect on the surface of the upstream tube bundle.

Kern [2] developed the earliest deposition model, mass balance model, where the change of fouling thermal resistance over time is the scaling model of the difference between deposition rate and decomposition rate. Wood [3] reviewed the theoretical and experimental research on particles deposition in turbulent flow. A simple analytical method is presented for calculation of deposition to both smooth and rough surfaces. Mahmood Izadi et al. [4] adopted RSM to simulate particle deposition of calcium carbonate inter water in a horizontal tube domain. They developed monitoring system for fouling phenomenon which can be used to monitor fouling in a wide range of tubular heat exchangers. Xu[5] et al. constructed a mathematical model in view of the CaCO$_3$ fouling process in...
the inner tube. Guo [6] developed a two-phase flow mathematical model of particle dynamics coupled with turbulent kinetic energy.

In this work, based on numerical simulation method, compare fouling accretion rate with Reynolds number of fluid. Then compare different boundary condition effect fouling accretion rate on the outer surface of tube bundle.

2. Numerical simulation

2.1. Governing equations

In this study, CFD modelling is done with commercial software ANSYS FLUENT 15.0. The governing equations for conservation of mass and momentum are solved with control volume based discretization method along with a pressure-based solver algorithm. The motion state of incompressible fluid is solved by navier-stokes equations:

$$\frac{\partial p}{\partial t} + \nabla \cdot \left( \rho \mathbf{u} \right) = 0$$  \hspace{1cm} (1)

In the continuity equation, \( \rho \) is the density of fluid which is considered as a constant, \( t \) and \( u \) represent time and velocity respectively. In the equation of motion, \( p \) is pressure and \( g \) is gravitational acceleration, \( F \) is external body force.

$$\frac{\partial}{\partial t} \left( \rho \mathbf{u} \right) + \nabla \cdot \left( \rho \mathbf{u} \mathbf{u} \right) = - \nabla p + \nabla \cdot \left( \mu \nabla \mathbf{u} \right) + \rho g + F$$  \hspace{1cm} (2)

In this work, standard k-\( \varepsilon \) turbulence model is used, which allows determination of both the turbulent length scale and the time scale by solving two separate transport equations, one for the dissipation kinetic energy, and one for the dissipation rate[7]. Turbulent viscosity is calculate by combining k-\( \varepsilon \) according to:

$$\frac{\partial}{\partial t} \left( \rho k \right) + \frac{\partial}{\partial x_i} \left( \rho k u_i \right) = \frac{\partial}{\partial x_j} \left( \mu \frac{\partial k}{\partial x_j} \right) +$$

\( G_k - \rho \varepsilon - Y_k + S_k \)  \hspace{1cm} (3)

$$\frac{\partial}{\partial t} \left( \rho \varepsilon \right) + \frac{\partial}{\partial x_i} \left( \rho \varepsilon u_i \right) = \frac{\partial}{\partial x_j} \left( \mu \frac{\partial \varepsilon}{\partial x_j} \right) +$$

\( C_{\mu} \frac{\varepsilon}{k} \left( G_{\varepsilon} + C_{\mu} \varepsilon \right) - C_{\mu} \rho \varepsilon^2 + S_\varepsilon \)  \hspace{1cm} (4)

2.2. Geometric model and boundary condition

The schematic of computational domain is shown below figure1. The specific size is shown in table 2.

![Fig. 1. Front view of geometry model](image-url)
Fig. 2. Diameter distribution of particle.

Table 1. The size of geometry model

| Num. | Parameter/symbol | unit | value |
|------|------------------|------|-------|
| 1    | Diameter of tube/R | mm   | 20    |
| 2    | transverse space/d₁| mm   | 30    |
| 4    | vertical spacing/h | mm   | 30    |
| 5    | Distance/d₂       | mm   | 35    |
| 6    | Distance/d₃       | mm   | 25    |

Table 2. Boundary condition:
The inlet velocity of the particle is consistent with the fluid and distributed uniformly.

| Type          | value                      |
|---------------|----------------------------|
| Inlet         | Velocity inlet 2.5–5m/s    |
| Outlet        | Pressure outlet            |
| Shell wall    | No slip                   |
| Tube          | No slip                   |

The materials and properties of continuity and discrete phase show in Table 3. The diameter distribution of particles obey Rosin-Rammler model as shown in Figure 2. The maximum diameter is 200μm, the minimum diameter is 60μm and the mean diameter is 131μm.

| Parameters | Continuity phase | Discrete phase |
|-----------|------------------|----------------|
| Material  | water (liquid)   | Calcium carbonate |
| Density   | 998.2kg/m³       | 2800kg/m³       |
| Viscosity | 0.001003Pa·s    | -               |
| Mass rate | -                | 200mg/l         |

In this simulation, Euler-Lagrange method is adopted to consider fluid as continuous phase and particles as discrete phase. This method is suitable for dilute discrete phase occupying less volume (≤10%). Owing to the complexity of two phase flow, some assumptions need to be raised:

i. The particles are sphere;
ii. Ignoring the effect of pipe diameter changes;
iii. Ignoring the interaction between particles.
Model predicts the trajectory of a discrete phase particle (or droplet or bubble) by integrating the force balance on the particle, which is written in a Lagrange reference frame [8]. This force balance equates the particle inertia with the forces acting on the particle.

The dispersion of particles due to turbulence in the fluid phase can be predicted using the stochastic tracking model. The stochastic tracking (random walk) model includes the instantaneous turbulent velocity fluctuations on the particle trajectories through the use of stochastic methods [9].

When the flow is turbulent, model will predict the trajectories of particles using the mean fluid phase velocity, $\bar{u}$, in the trajectory equations.

### 2.3 Equation of motion for particles

Euler-Lagrange model predicts the trajectory of a discrete phase particle by integrating the force balance on the particle, which is written in a Lagrange reference frame. This force balance equates the particle inertia with the forces acting on the particle, and can be written as:

$$\frac{d\overrightarrow{u}_p}{dt} = F_D(u - u_p) + \frac{g(\rho_p - \rho)}{\rho_p}$$

(5)

where $F_D(u - u_p)$ is the drag force per unit particle mass and

$$F_D = \frac{18\mu C_D Re}{\rho_p d_p^2 24}$$

(6)

Here, $\bar{u}$ is the fluid phase velocity, $u_p$ is the particle velocity, $\mu$ is the molecular viscosity of the fluid, $\rho$ is the fluid density, $\rho_p$ is the density of the particle, and $d_p$ is the particle diameter.

### 2.4 Turbulent dispersion of particles

The dispersion of particles due to turbulence in the fluid phase can be predicted using the stochastic tracking model [10]. The stochastic tracking (random walk) model includes the effect of instantaneous turbulent velocity fluctuations on the particle trajectories through the use of stochastic methods.

### 2.5 Laws for drag coefficients

Spherical drag law is used to depict interaction between fluid and particles

$$C_D = a_1 + \frac{a_2}{Re} + \frac{a_3}{Re^2}$$

(7)

where $a_1$, $a_2$ and $a_3$ are constants that apply over several ranges of Re, which are equal to 0.5191, -1662.5 and $5.1467 \times 10^6$ respectively in this simulation.

In this simulation, the particle deposition rate adopts the Eq5. the expression of particle relaxation time is shown as Eq6.

$$u_p = \frac{N_d / \mu}{N_0 / \eta_0}$$

(5)

$$\tau_p = \frac{(\rho_p - \rho) \cdot d_p^2 \cdot u^2}{18 \cdot \rho \cdot v^2}$$

(6)

### 3. Results and discuss

This simulation on kinetic theory of granular simplifies solid-liquid two phase flow reasonably. The particle deposition mathematical model can predict the surface deposition rate accurately.

#### 3.1 Reliability of the numerical simulation
In the present investigation, unstructured mesh of 5 boundary layers is applied to calculate accurately. From the picture, the conclusion can be drawn that an unstructured grid with 432,045 is sufficient and accurate. In addition, the result is that deviation between simulation and kern’s mass balance model is within 15%. For immature and complicated two phase flow model, this deviation is acceptable.

3.2. Accretion rate and dynamic pressure
The study predicts the distribution of facet average accretion rate and dynamic pressure on the outer surface of tubes. The results show that, dynamic pressure of the surface of tubes is related closely to particle deposition. That is to say, dynamic pressure is a parameter to reflect location of fouling deposition.

The linear regression equation is obtained by regression analysis of deposition rate and dynamic pressure:

\[ Y = (D - 5789.78) \times 8288.04 \quad (7) \]

Where, \( Y \) is accretion rate, \( kg/m^2 \cdot s \);
\( D \) is dynamic pressure, Pa.

In working condition, dynamic pressure is easier and low cost to be supervised than fouling deposition.
The accretion rate doesn’t increase with the increment of fluid Reynolds number. In this geometry model, Re within the range of 39928-59892, the accretion rate increase at linearly. The facet average accretion rate tends to be stable to around, however, when the Re exceeds 598892. The aligned arrangement of tube bundles may be a reason for steady facet average accretion on the back row, which is in line with reality that the accretion rate of back tube bundles stabilizes.

The figure7 shows that the prediction of sedimentary condition on the joint between with tube bundles and shell. In this place, the flow forms a vortex that promotes particle deposition, where the maximum accretion rate access 110kg/m$^2$·s. In addition, the first two rows and the middle tubes occurs much less deposiment than the later and tubes near the wall.
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