TRA VIS at PARSEME Shared Task 2020: How good is (m)BERT at seeing the unseen?

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Abstract

This paper describes the TRA VIS system built for the PARSEME Shared Task 2020 on semi-supervised identification of verbal multiword expressions. TRA VIS is a fully feature-independent model, relying only on the contextual embeddings. We have participated with two variants of TRA VIS, TRA VIS\textsubscript{multi} and TRA VIS\textsubscript{mono}, where the former employs multilingual contextual embeddings and the latter uses monolingual ones. Our systems are ranked second and third among seven submissions in the open track, respectively. Thorough comparison of both systems on eight languages reveals that despite the strong performance of multilingual contextual embeddings across all languages, language-specific contextual embeddings exhibit much better generalization capabilities.

1 Introduction

Multiword expressions (MWEs) are, most commonly, defined as a group of words which act as a single lexical unit and display idiomaticity at lexical, syntactic, semantic or pragmatic levels (Baldwin and Kim, 2010). As the name suggests, verbal MWEs (VMWEs) are MWEs with a verb as the head in their canonical form. Identification of VMWEs tend to be more challenging than that of other MWEs, as they exhibit more syntactic/morphological variation (due to inflection of the verb), their components can be interrupted by other words (he made a serious mistake) and furthermore their order may vary (the decision was hard to take) (Savary et al., 2017). Yet, their identification is equally important as it is a prerequisite to fully address a number of downstream tasks, such as machine translation, information retrieval or syntactic parsing.

This year’s shared task is built upon the observation that the existing models fail when it comes to identify the VMWEs which are not seen during the training. Hence, the aim of this year’s shared task is updated to identify the unseen VMWEs in running text and the organizers provide annotated corpora with varying sizes in 14 different languages.

In this paper, we present two variants of TRA VIS, TRA VIS\textsubscript{multi} and TRA VIS\textsubscript{mono}, which were submitted to the open track of the shared task, where additional resources were allowed. TRA VIS follows the tradition of approaching VMWE identification as a token classification task. To this end, it employs the, now standard, contextual embeddings model, BERT (Devlin et al., 2019), which has seen very limited application to this task. Due to the multilingual nature of the shared task, we also pay special attention to the performance on different languages. The variants of TRA VIS are named after this concern, highlighting the type of the contextual embeddings in terms of their pre-training languages: TRA VIS\textsubscript{multi} only uses the multilingual-BERT, which is trained on 104 languages, whereas TRA VIS\textsubscript{mono} uses the available language-specific BERT model for each language. Hence, the aim of the current submission is twofold: (i) we investigate the generalizability capabilities of pre-trained language models on identification of VMWEs (ii) we provide a thorough comparison of the multilingual-BERT against language-specific BERTs to understand the limitations of the former, if there is any, hoping to guide the future multilingual research on VMWEs.

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2 Background

Treating MWE identification as a sequence tagging problem has been one of the most popular approaches (Zampieri et al., 2019). To this end, Schneider et al. (2014) propose new tagging schemes for VMWE by extending the BIO format to allow the annotation of discontinuous and nested MWEs. Gharbieh et al. (2017) constitutes the first study which adopts this approach and applies deep learning models including feedforward, recurrent and convolutional networks. Later, a number of studies adopting a recurrent neural network with an optional CRF classifier have been proposed (Klyueva et al., 2017; Taslimipoor and Rohanian, 2018; Zampieri et al., 2018; Berk et al., 2018). Zampieri et al. (2019) further study the effects of different word representations on this architecture by using the Veyn model of (Zampieri et al., 2018). Rohanian et al. (2019) specifically target the challenge caused by discontinuity of verbal MWEs and propose a neural model which combines convolutional network and self-attention mechanism to deal with long-range relations.

3 System Description

Below, we briefly introduce the BERT language model, which constitutes the backbone of our model, followed by the introduction of the proposed models.

3.1 BERT

Bidirectional Encoder Representations from Transformers (BERT) (Devlin et al., 2019) is a transformer-based deep bidirectional language model which has quickly become a new standard in NLP. It is pre-trained on a large unannotated corpus with two training objectives: (i) prediction of the missing words in a context (ii) given a sentence pair, determine if the second sentence follows the first one. These general pre-training objectives allow BERT to learn general enough representations which can be adjusted to any particular task through fine-tuning. In fine-tuning, a task-specific classification layer is added on the top of BERT and the whole model is, further, trained on the target task, updating the parameters of the BERT as well.

Originally, two different BERT models were released with different number of layers in their architecture: BERT-base (12-layer, 768-hidden, 12-heads, 110M parameters) and BERT-large (24-layer, 1024-hidden, 16-heads, 340M parameters). Additionally, a multilingual BERT (henceforth mBERT) was released, sharing the same architecture with the BERT-base model but trained on the concatenation of Wikipedias of 104 languages. Yet, since mBERT does not have any cross-lingual objectives nor trained on aligned data, its cross-lingual abilities and its limitations have, since, become a research topic (Karthikeyan et al., 2019).

3.2 Proposed Model(s)

We approach identification of VMWEs as a token classification problem. Our architecture follows the standard fine-tuning strategy employed for similar sequence tagging problems as described in the original BERT paper (Devlin et al., 2019). Briefly, we use BERT as our encoder with a linear layer connected to its hidden states on top to perform token level classification. In cases where the input token is split into several sub-tokens by the BERT’s internal tokenizer, we pass the representation of the first sub-token to the linear layer classifier as the representation of the input token.

As stated earlier, there are two variants of TRAVIS where the only difference between them is the BERT model employed, otherwise completely identical. The first variant, TRAVIS-multi, uses mBERT as the encoder whereas the second variant, TRAVIS-mono, employs language specific BERT models and covers the following 8 languages: DE, FR, IT, PL, RO, SV, TR, ZH.

The motivation behind these two variants is the general finding that the monolingual models usually outperform mBERT (Nozza et al., 2020); yet, most languages still lack their own monolingual model.

1Our original shared task submission for TRAVIS-mono also included predictions for EL and HI. However, we later discovered that the predictions for these languages were completely erroneous due to an error in the tokenization process. Therefore, we confine ourselves to the remaining eight languages in the current system description paper and we ask reader to dismiss the published results on the web-site for these two languages.
| System              | Langs | Unseen MWE-based | Global MWE-based | Global Token-based |
|---------------------|-------|------------------|------------------|--------------------|
|                     |       | P    R    F1 | P    R    F1 | P    R    F1      |
| MTLB-STRUCT         | 14/14 | 36.24 | 41.12 | 38.53 | 71.26 | 69.05 | 70.14 | 77.69 | 70.9 | 74.14 |
| TRAVIS-multi        | 13/14* | 28.11 | 33.29 | 30.48 | 60.65 | 57.62 | 59.1 | 70.39 | 60.08 | 64.83 |
| TRAVIS-mono         | 10/14 | 24.33 | 28.01 | 26.04 | 49.5 | 43.48 | 46.3 | 55.92 | 45.01 | 49.88 |
| Seen2Unseen         | 14/14 | 16.14 | 11.95 | 13.73 | 63.36 | 62.69 | 63.02 | 66.33 | 61.63 | 63.89 |
| FipsCo              | 3/14  | 4.31  | 5.21  | 4.72  | 11.69 | 8.75  | 10.01 | 13.26 | 8.51 | 10.37 |
| HMSid               | 1/14  | 1.98  | 3.81  | 2.61  | 4.56  | 4.85  | 4.7  | 4.74  | 4.84  | 4.79  |
| MultiVitamBooster   | 7/14  | 0.05  | 0.07  | 0.06  | 0.19  | 0.09  | 0.12  | 3.49  | 1.26  | 1.85  |
| TRAVIS-multi        | 13/13 | 30.27 | 35.85 | 32.83 | 65.31 | 62.05 | 63.64 | 75.81 | 64.70 | 69.82 |
| TRAVIS-mono         | 8/8^1 | 43.86 | 49.91 | 46.69 | 74.87 | 74.77 | 74.82 | 80.76 | 76.94 | 78.80 |

Table 1: The official results of the all participating teams in the open track, ranked according to the F-score on unseen MWE identification. The bottom part presents our results when averaged over the languages covered. *The missing language is Portuguese, for which we failed to submit a result by the time of the shared task deadline due to a bug in the script.

as training such a language-specific BERT is computationally expensive. Hence, we believe that it is important to compare these models to gain insight regarding their performance for the future multilingual research, especially on low resource languages.

As for labelling, we follow a procedure similar to (Taslimipoor and Rohanian, 2018) and convert the PARSEME annotations into IOB-like labels. The PARSEME labels consist of VMWE’s consecutive number in the sentence and its category, e.g. 2:LVC.full denotes that the token with this tag is the first token of the 2\textsuperscript{nd} VMWE in that sentence, which is a light verb construction, whereas the other components of that VMWE are labeled with merely 2. We modify these labels so that the initial token receives B- and the respective category and other tokens receives I- plus that category. All other tokens, which are not a part of any VMWE, receive O tag.

4 Experimental Design

Our implementation is based on the Transformers library of Huggingface (Wolf et al., 2019). All monolingual BERT models as well as mBERT are obtained through Huggingface’s model hub\(^2\). In languages with several available BERT models, we opted for the most downloaded cased one. The complete list of the models used in the first submission are provided in Appendix A.

We train all models for four epochs using the Adam optimizer (Kingma and Ba, 2014) with a learning rate of 5e-5. The sequence length is set to 400 during training, but at the time of the inference we use BERT’s maximum sequence limit which is 512. As the fine-tuning procedure is prone to high variance, we run all our models four times and used the run with the best development performance to obtain the final predictions for the test sets.

5 Results and Discussion

TRAVIS variants ranked 2\textsuperscript{nd} and 3\textsuperscript{rd} in the general ranking, according to the target metric of the unseen MWE-based F-score. Table 1 summarizes the official results of all participating teams in the open track. Additionally, global MWE- and token-based scores are presented in order to give an overall idea about the participating teams\(^3\). In what follows, we discuss our results with a focus on performance in the discovery of the unseen VMWEs, following the main aim of the shared task.

Although TRA VIS\(_{\text{multi}}\) ranks higher than TRA VIS\(_{\text{mono}}\) in Table 1, it is because the official results are obtained by averaging the performance of the systems over all languages, independent of the number of the languages covered in the submission. When the results are averaged only over the languages

\(^2\)https://huggingface.co/models

\(^3\)The details of each measure can be found in (Savary et al., 2017).
Table 2: Average performance comparison of our two submissions on the following set of languages: DE, FR, IT, PL, RO, SV, TR, ZH. Following the updated definition of the shared task, any VMWE in the training or development set are regarded as seen.

covered in each submission (last two rows of Table 1), it becomes clear that TRA VIS mono performs better on average, achieving an increase of 14 F-score. However, to draw a more healthy comparison, we also compared the averaged performances of these variants on the same set of languages, which is provided in Table 2. The results show that TRA VIS mono still significantly outperforms TRA VIS multi by 6 F-score even when evaluated on the same set of languages. It must also be noted that this difference in performance is not due to a significant increase in one or several languages but consistent across all the common eight languages where TRA VIS multi only achieves better performance for Swedish by 1.4 F-score, otherwise outperformed by 8 points in F-score on average.

These results are in line with the previous findings that language specific BERT models perform better on the respective language. However, it must be highlighted that the biggest gain of the language-specific models is in the discovery of the unseen VMWEs. As far as those eight languages are concerned, both models show similar performance for the seen VMWEs with TRA VIS mono 87.17 and TRA VIS multi 85.69 F-score, respectively (Table 2). Hence, it is evident that language-specific BERTs are particularly better at generalizing to unseen VMWEs.

However, the performance of mBERT cannot be simply dismissed, as the TRA VIS multi also achieves consistent results across languages. Although the results are not directly comparable as the set of the languages is different and the datasets have, possibly, been modified over time, TRA VIS multi achieves an average of 10% increase in F-score over SHOMA (Taslimipoor and Rohanian, 2018), the best performing system of the previous PARSEME Shared Task (2018), in the identification of the unseen MWEs.

Language-wise, TRA VIS mono achieved the best performance in the open track of the shared task for the six of the eight languages it covers which are: FR, IT, PL, RO, TR, ZH. These languages represent various language families suggesting that the performance of TRA VIS is stable typologically. As for TRA VIS multi, Irish (GA) turns out to be the most challenging language with only 2.6% F-score. However, that is probably due to the size of the dataset that contains only 100 VMWEs in the training portion which is too limited to fine-tune mBERT in a meaningful way. The language-wise comparison of our submissions with the best performing system is provided in Figure 1.

Finally, a general advantage of employing contextual embeddings is being completely feature-independent. Hence, the proposed model only requires a training data annotated for the positions of the target VMWEs, rendering it easily adaptable to other low resource languages where obtaining other linguistics features, such as POS-tags or dependency trees, can be challenging.

6 Conclusion

In this paper, we try to answer two questions: (i) how generalizable is the performance of contextual embeddings in VMWE identification, and (ii) if the pre-training language plays an important role or, in other words, the multilingual contextual embeddings are good enough. To this end, we offer a computational model, TRA VIS, which treats VMWE identification as a sequence classification task and employs various BERT models.

The results indicate that language-specific models perform particularly well on the identification of the unseen VMWEs by outperforming the multilingual embeddings by 6% in F-score when compared on the same set of languages. Yet, the multilingual-BERT also exhibits strong multilingual abilities, suggested by the average of 32% F-score in identification of the unseen VMWEs which is significantly higher than results obtained in the previous editions of the PARSEME shared tasks.
Figure 1: Language-wise comparison of our submissions and the first-ranked system (MTLB-STRUCT) on unseen MWEs.

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### Appendix A

| Language          | Model name                                    |
|-------------------|-----------------------------------------------|
| German            | bert-base-german-cased                        |
| French (Martin et al., 2019) | camembert-base                              |
| Italian           | bert-base-italian-cased                       |
| Polish            | dkleczek/bert-base-polish-cased-v1            |
| Romanian          | bert-base-romanian-cased-v1                  |
| Swedish (Malmsten et al., 2020) | bert-base-swedish-cased                     |
| Turkish           | bert-base-turkish-128k-cased                 |
| Chinese           | bert-base-chinese                             |

Table 3: The list of the monolingual BERT models used in the experiments. The model name denotes the model identifier of the corresponding model on Huggingface’s model hub (huggingface.com/models)