Deep Neural Networks for Rotation-Invariance Approximation and Learning

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Abstract

Based on the tree architecture, the objective of this paper is to design deep neural networks with two or more hidden layers (called deep nets) for realization of radial functions so as to enable rotational invariance for near-optimal function approximation in an arbitrarily high dimensional Euclidian space. It is shown that deep nets have much better performance than shallow nets (with only one hidden layer) in terms of approximation accuracy and learning capabilities. In particular, for learning radial functions, it is shown that near-optimal rate can be achieved by deep nets but not by shallow nets. Our results illustrate the necessity of depth in neural network design for realization of rotation-invariance target functions.

Keywords: Deep nets, rotation-invariance, learning theory, radial-basis functions

1 Introduction

In this era of big data, data-sets of massive size and with various features are routinely acquired, creating a crucial challenge to machine learning in the design of learning strategies for data management, particularly in realization of certain data features. Deep learning is a state-of-the-art approach for the purpose of realizing such features, including localized position information, geometric structures of data-sets, and data sparsity. For this and other reasons, deep learning has recently received much attention, and has been successful in various application domains, such as computer vision, speech recognition, image classification, fingerprint recognition and earthquake forecasting.

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Affine transformation-invariance, and particularly rotation-invariance, is an important data feature, prevalent in such areas as statistical physics [18], early warning of earthquakes [28], 3-D point-cloud segmentation [27], and image rendering [22]. Theoretically, neural networks with one hidden layer (to be called shallow nets) are incapable of embodying rotation-invariance features in the sense that its performance in handling these features is analogous to the failure of algebraic polynomials [13] in handling this task [14]. The primary goal of this paper is to construct neural networks with at least two hidden layers (called deep nets) to realize rotation-invariant features by deriving “fast” approximation and learning rates of radial functions as target functions.

Recall that a function \( f \) defined on the \( d \)-dimensional ball, \( \mathbb{B}^d(R) \) with radius \( R > 0 \) where \( d \geq 2 \), is called a radial function, if there exists a univariate real-valued function \( g \) defined on the interval \([0, R]\) such that \( f(x) = g(|x|^2) \), for all \( x \in \mathbb{B}^d(R) \). For convenience, we allow \( \mathbb{B}^d(R) \) to include the Euclidian space \( \mathbb{R}^d \) with \( R = \infty \). Hence, all radial-basis functions (RBF’s) are special cases of radial functions. In this regard, it is worthwhile to mention that the most commonly used RBF’s are the multiquadric \( g(r) = (r^2 + c)^{1/2} \) and Gaussian \( g(r) = e^{-cr^2} \), where \( c > 0 \). For these and some other RBF’s, existence and uniqueness of scattered data interpolation from the linear span of \( \{ f(x - x_k) : k = 1, \cdots, \ell \} \), for arbitrary distinct centers \( \{x_1, \cdots, x_\ell \} \) and for any \( \ell \in \mathbb{N} \), are assured. The reason for the popularity of the multiquadric RBF is fast convergence rates of the interpolants to the target function [1], and that of the Gaussian RBF is that it is commonly used as the activation function for constructing radial networks that possess the universal approximation property and other useful features (see [21], [25], [35], [39], [40], [9]) and references therein). The departure of our paper from constructing radial networks is that since RBF’s are radial functions, they qualify to be target functions for our general-purpose deep nets with general activation functions. Hence, if the centers \( \{x_1, \cdots, x_\ell \} \) of the desired RBF have been chosen and the coefficients \( a_1, \cdots, a_\ell \) have been pre-computed, then the target function

\[
\sum_{k=1}^{\ell} a_k f(x - x_k)
\]

can be realized by using one extra hidden layer for the standard arithmetic operations of additions and multiplications and an additional outer layer for the input of RBF centers and coefficients to the deep net constructed in this paper.

The main results of this paper are three-fold. We will first derive a lower bound estimate for approximating radial functions by deep nets. We will then construct a deep net with four hidden layers to achieve this lower bound (up to a logarithmic multiplicative factor) to illustrate the power of depth in realizing rotation-invariance. Finally, based on the prominent approximation ability of deep nets, we will show that implementation of the empirical risk minimization (ERM) algorithm in deep nets facilitates fast learning rates and is independent of dimensions. The presentation of this paper is organized as follows.
Main results will be stated in Section 2 where near-optimal approximation order and learning rate of deep nets are established. In Section 3, we will establish our main tools for constructing deep nets with two hidden layers for approximation of univariate smooth functions. Proofs of the main results will be provided in Section 4. Finally, derivations of the auxiliary lemmas that are needed for our proof of the main results are presented in Section 5.

2 Main Results

Let $\mathbb{B}^d := \mathbb{B}^d(1)$ denote the unit ball in $\mathbb{R}^d$ with center at the origin. Then any radial function $f$ defined on $\mathbb{B}^d$ is represented by $f(x) = g(|x|^2)$ for some function $g : [0, 1] \to \mathbb{R}$. Here and throughout the paper, the standard notation of the Euclidean norm $|x| := [(x^{(1)})^2 + \cdots + (x^{(d)})^2]^{1/2}$ is used for $x := (x^{(1)}, \ldots, x^{(d)}) \in \mathbb{R}^d$. In this section, we present the main results on approximation and learning of radial functions $f$.

2.1 Deep nets with tree structure

Consider the collection

$$S_{\phi,n} := \left\{ \sum_{j=1}^{n} a_j \phi(w_j \cdot x + b_j) : a_j, b_j \in \mathbb{R}, w_j \in \mathbb{R}^d \right\},$$

of shallow nets with activation function $\phi : \mathbb{R} \to \mathbb{R}$, where $x \in \mathbb{B}^d$. The deep nets considered in this paper are defined recursively in terms of shallow nets according to the tree structure, as follows:

**Definition 1** Let $L, N_1, \ldots, N_L \in \mathbb{N}$, $N_0 = d$, and $\phi_k : \mathbb{R} \to \mathbb{R}$, $k = 0, 1, \ldots, L$, be univariate activation functions. Set

$$H_{\vec{\alpha},0}(x) = \sum_{j=1}^{N_0} a_{j, \vec{\alpha},0} \phi_0(w_{j, \vec{\alpha},0} x^{(j)} + b_{j, \vec{\alpha},0}), \quad x = (x^{(1)}, \ldots, x^{(d)}), \vec{\alpha} = \prod_{i=1}^{L} \{1, 2, \ldots, N_i \}.$$

Then a deep net with the tree structure of $L$ layers can be formulated recursively by

$$H_{\vec{\alpha},k}(x) = \sum_{j=1}^{N_k} a_{j, \vec{\alpha},k} \phi_k(H_{j, \vec{\alpha},k-1}(x) + b_{j, \vec{\alpha},k}), \quad 1 \leq k \leq L, \vec{\alpha} = \prod_{i=k+1}^{L} \{1, 2, \ldots, N_i \},$$

where $a_{j, \vec{\alpha},k}, b_{j, \vec{\alpha},k}, w_{j, \vec{\alpha},0} \in \mathbb{R}$ for each $j \in \{1, 2, \ldots, N_k \}, \vec{\alpha} \in \prod_{i=k+1}^{L} \{1, 2, \ldots, N_i \}$, and $k \in \{0, 1, \ldots, L \}$. Let $\mathcal{H}_L^{\text{tree}}$ denote the set of output functions $H_L = H_{\vec{\alpha},L}$ for $\vec{\alpha} \in \emptyset$ at the $L$-th layer.
Figure 1: Tree structure of deep nets with six layers

Note that if the initial activation function is chosen to be \( \phi_0(t) = t \) and \( b_{j,\alpha,0} = 0 \), then \( \mathcal{H}_{1}^{\text{tree}} \) is the same as the shallow net \( \mathcal{S}_{\phi_1,N_1} \). Figure 2.1 exhibits the structure of the deep net defined in Definition 1, showing sparse and tree-based connections among neurons. Due to the concise mathematical formulation, this definition of deep nets \([6]\) has been widely used to illustrate its advantages over shallow nets. In particular, it was shown in \([23]\) that deep nets with the tree structure can be constructed to overcome the saturation phenomenon of shallow nets; in \([19]\) that deep nets, with two hidden layers, tree structure, and finitely many neurons, can be constructed to possess the universal approximation property; and in \([12,26]\) that deep nets with the tree structure are capable of embodying tree structures for data management. In addition, a deep net with the tree structure was constructed in \([5]\) to realize manifold data.

As a result of the sparse connections of deep nets with the tree structure, it follows from Definition 1 and Figure 1 that there are a total of

\[
A_L := 2 \sum_{k=0}^{L} \Pi_{\ell=0}^{L-k} N_{L-\ell} + \Pi_{\ell=0}^{L} N_{L} \tag{2}
\]

free parameters for \( H_L \in \mathcal{H}_L^{\text{tree}} \). For \( \alpha, \mathcal{R} \geq 1 \), we introduce the notation

\[
\mathcal{H}_{L,\alpha,\mathcal{R}}^{\text{tree}} := \{ H_L \in \mathcal{H}_L^{\text{tree}} : |a_{j,\vec{\alpha},k}|, |b_{j,\vec{\alpha},k}|, |w_{j,\vec{\alpha},0}| \leq \mathcal{R} (A_L)^\alpha, \\
0 \leq k \leq L, 1 \leq j \leq N_k, \vec{\alpha} \in \prod_{i=k+1}^{L} \{1, 2, \ldots, N_i\} \}. \tag{3}
\]

For functions in this class, the parameters of deep nets are bounded. This is indeed a necessity condition, since it follows from the results in \([19,20]\) there exists some \( h \in \mathcal{H}_2^{\text{tree}} \),
with finitely many neurons but infinite capacity (pseudo-dimension). The objective of this paper is to construct deep nets of the form (3) for some \( \alpha \) and \( \mathcal{R} \), for the purpose of approximating and learning radial functions.

2.2 Lower bounds for approximation by deep nets

In this subsection, we show the power of depth in approximating radial functions, by showing some lower bound results for approximation by deep nets under certain smoothness assumption on the radial functions.

Definition 2 For \( A \subset \mathbb{R} \), \( c_0 > 0 \) and \( r = s + v \), with \( s \in \mathbb{N}_0 := \{0\} \cup \mathbb{N} \) and \( 0 < v \leq 1 \), let \( \text{Lip}_{A}^{(r,c_0)} \) denote the collection of univariate \( s \)-times differentiable functions \( g : A \rightarrow \mathbb{R} \), whose \( s \)-th derivatives satisfy the Lipschitz condition

\[
|g^{(s)}(t) - g^{(s)}(t_0)| \leq c_0 |t - t_0|^v, \quad \forall \ t, t_0 \in A. \tag{4}
\]

In particular, for \( A = \mathbb{I} := [0,1] \), let \( \text{Lip}_{\mathbb{I}}^{(s,r,c_0)} \) denote the set of radial functions \( f(x) = g(|x|^2) \) with \( g \in \text{Lip}_{\mathbb{I}}^{(r,c_0)} \).

We point out that the above Lipschitz continuous assumption is standard for radial basis functions (RBF’s) in Approximation Theory, and was adopted in [13,14] to quantify the approximation abilities of polynomials and ridge functions. For \( U, V \subseteq L_p(\mathbb{B}^d) \) and \( 1 \leq p \leq \infty \), we denote by

\[
\text{dist}(U, V, L_p(\mathbb{B}^d)) := \sup_{f \in U} \text{dist}(f, V, L_p(\mathbb{B}^d)) := \sup_{f \in U, g \in V} \|f - g\|_{L_p(\mathbb{B}^d)}
\]

the deviations of \( U \) from \( V \) in \( L_p(\mathbb{B}^d) \). The following main result shows that shallow nets are incapable of embodying the rotation-invariance property.

Theorem 1 Let \( d \geq 2 \), \( n, L \in \mathbb{N} \), \( c_1 > 0 \), \( \mathcal{R}, \alpha \geq 1 \) and \( \mathcal{H}^{\text{tree}}_{L,\alpha, \mathcal{R}} \) be defined by (3) with \( \tilde{n} = A_L \) free parameters, and \( A_L \) be given by (2). Suppose that \( \phi_j \in L^{(1,c_1)}_{\mathbb{R}} \) satisfies \( \|\phi_j\|_{L_\infty(\mathbb{R})} \leq 1 \) for every \( j \in \{0,1,\ldots,L\} \). Then for \( c_0 > 0 \), \( r = s + v \) with \( s \in \mathbb{N}_0 \) and \( 0 < v \leq 1 \),

\[
\text{dist}(\text{Lip}_{\mathbb{I}}^{(s,r,c_0)}, \mathcal{S}_{\phi_1,n}, L_\infty(\mathbb{B}^d)) \geq C_1^s (d+2)n^{-r/(d-1)}, \tag{5}
\]

and

\[
\text{dist}(\text{Lip}_{\mathbb{I}}^{(s,r,c_0)}, \mathcal{H}^{\text{tree}}_{L,\alpha, \mathcal{R}}, L_\infty(\mathbb{B}^d)) \geq C_2^s (L^2 \tilde{n} \log_2 \tilde{n})^{-r}, \quad L \geq 2, \tag{6}
\]

where \( (d+2)n \) is the number of parameters for the shallow net \( \mathcal{S}_{\phi_1,n} \) and the constants \( C_1^s \) and \( C_2^s \) are independent of \( n, \tilde{n} \) or \( L \).

The proof of Theorem [1] is postponed to Section 4. Observe that Theorem 1 exhibits an interesting phenomenon in approximation of radial functions by deep nets, in that the depth plays a crucial role, by comparing (5) with (6). For instance, the lower bound \( (\tilde{n} \log \tilde{n})^{-r} \) for deep nets is a big improvement of the lower bound \( \tilde{n}^{-r/(d-1)} \) for shallow nets, for dimensions \( d > 2 \).
### 2.3 Near-optimal approximation rates for deep nets

In this subsection, we show that the lower bound \( (6) \) is achievable up to a logarithmic factor by some deep net with \( L = 3 \) layers for certain commonly used activation functions that satisfy the following smoothness condition.

**Assumption 1** The activation function \( \phi \) is assumed to be infinitely differentiable, with both \( \|\phi'\|_{L^\infty(\mathbb{R})} \) and \( \|\phi\|_{L^\infty(\mathbb{R})} \) bounded by 1, such that \( \phi^{(j)}(\theta_0) \neq 0 \) for some \( \theta_0 \in \mathbb{R} \) and all \( j \in \mathbb{N}_0 \), and that

\[
|\phi(-t)| = \mathcal{O}(t^{-1}), \quad |1 - \phi(t)| = \mathcal{O}(t^{-1}), \quad t \to \infty.
\]

It is easy to see that all of the logistic function: \( \phi(t) = \frac{1}{1+e^{-t}} \), the hyperbolic tangent function: \( \phi(t) = \frac{1}{2}(\tanh(t) + 1) \), the arctan function: \( \phi(t) = \frac{1}{\pi} \arctan(t) + \frac{1}{2} \), and the Gompertz function: \( \phi(t) = e^{-e^{-t}} \), satisfy Assumption 1 in which we essentially impose three conditions on the activation function \( \phi \), namely: infinite differentiability, non-vanishing of all derivatives at the same point, and the sigmoidal property (7). On the other hand, we should point out that such strong assumptions are stated only for the sake of brevity, but can be relaxed to Assumption 2 in Section 3 below. In particular, the infinite differentiability condition on \( \phi \) can be replaced by some much weaker smoothness property as that of the target function \( f \). The following is our second main result, which shows that deep nets can be constructed to realize the rotation-invariance property of \( f \) by exhibiting a dimension-independent approximation error bound, which is much smaller than that for shallow nets.

**Theorem 2** Let \( n \geq 2 \), \( c_0 > 0 \), and \( r = s + v \) with \( s \in \mathbb{N}_0 \) and \( 0 < v \leq 1 \). Then under Assumption 1 for \( R, \alpha \geq 1 \),

\[
9^{-r}C_2^s (n \log n)^{-r} \leq \text{dist}(\text{Lip}^{(\alpha,r,c_0)}, \mathcal{H}^{\text{tree}}_{3,\alpha,R, L^\infty(\mathbb{R})^{d}}) \leq C_3^s n^{-r},
\]

where \( \mathcal{H}^{\text{tree}}_{3,\alpha,R} \) is defined by (3) with \( L = 3 \), \( N_0 = d, N_1 = 6, N_2 = s + 3, N_3 = 3n + 3, \alpha = 48(3 + r(r + 1) + r(s + 1)!7(r + 1)) \), and the constant \( C_3^s \) is independent of \( n \).

Note that the deep net in Theorem 2 has the number of free parameters satisfying

\[
6d(s + 3)(3n + 3) \leq \tilde{n} = A_3 \leq 54d(s + 3)(3n + 3).
\]

It follows from (8) that, up to a logarithmic factor, there exists a deep net with \( L = 3 \) and some commonly used activation functions that achieves the lower bound \( (6) \) established in Theorem 1.

We would like to mention an earlier work [21] on approximating radial functions by deep ReLU networks, where it was shown that for each \( f \in \text{Lip}^{(\alpha,1,c_0)} \), there exists a fully
[Text content]
holds with confidence at least $1 - \delta$. Furthermore,
\begin{equation}
C_7^* m^{-\frac{2r}{2r+1}} \leq \sup_{f_\rho \in \text{Lip}(r,c_0)} E \{ \mathcal{E}(\pi_M f_{D,n,\phi}) - \mathcal{E}(f_\rho) \} \leq C_8^* m^{-\frac{2r}{2r+1}} \log(m+1),
\end{equation}
where, as usual, $[a]$ denotes the integer part of $a > 0$ and the constants $C_5^*, C_6^*, C_7^*, C_8^*$ are independent of $\delta, m$ and $n$.

We emphasize that the learning rate in (10) is independent of the dimension $d$, and is much better than the optimal learning rate $m^{-\frac{2r}{2r+1}}$ for learning $(r,c_0)$-smooth (but not necessarily radial) functions on $\mathbb{R}^d$ [10,15,16]. For shallow nets, it follows from (6) that to achieve a learning rate similar to (11), we need at least $[m\frac{d}{2r+1}]$ neurons to guarantee the $O(m^{-\frac{2r}{2r+1}})$ bias. For $d \geq 3$, since $m\frac{d}{2r+1} \geq m\frac{1}{2r+1}$, the capacity of neural networks is large. Consequently, it is difficult to derive a satisfactory variance, so that derivation of a similar almost optimal learning rates as (11) for ERM on shallow nets is also difficult. Thus, Theorem 3 demonstrates that ERM on deep nets can embody the rotation-invariance property by deducing the learning rate of order $m^{-\frac{2r}{2r+1}}$.

3 Approximation by Deep Nets without Saturation

Construction of neural networks to approximate smooth functions is a classical and longstanding topic in approximation theory. Generally speaking, there are two approaches, one by constructing neural networks to approximate algebraic polynomials, and the other by constructing neural networks with localized approximation properties. The former usually requires extremely large norms of weights [24,32] and the latter frequently suffers from the well-known saturation phenomenon [2,3], in the sense that the approximation rate cannot be improved any further, when the regularity of the target function goes beyond a specific level. The novelty of our method is to adopt the ideas from both of the above two approaches to construct a deep net with two hidden layers with controllable norms of weights and without saturation, by considering the “exchange-invariance” between polynomials and shallow nets, the localized approximation of neural networks, a recently developed “product-gate” technique [33], and a novel Taylor formula. For this purpose, we need to impose differentiability and the sigmoid property on activation functions, as follows.

**Assumption 2** Let $c_0 > 0$, $r_0 = s_0 + v_0$ with $s_0 \geq 2$ and $0 < v_0 \leq 1$. Assume that $\phi \in \text{Lip}_R^{(r_0,c_0)}$ is a sigmoidal function with $\|\phi\|_{L_\infty(\mathbb{R})}, \|\phi\|_{L_\infty(\mathbb{R})} \leq 1$, such that $\phi^{(j)}(\theta_0) \neq 0$ for all $j = 0, 1, \ldots, s_0$, for some $\theta_0 \in \mathbb{R}$.

It is obvious that Assumption 2 is much weaker than the smoothness property of $\phi$ in Assumption 1. Furthermore, it removes the restriction (7) on the use of sigmoid functions as activation function, by considering only the general sigmoidal property:

$\phi(-t) \to 0$, \hspace{1cm} and \hspace{1cm} $\phi(t) \to 1$, \hspace{1cm} when \hspace{1cm} $t \to \infty$. 

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In view of this property, we introduce the notation

\[ \delta_{\phi}(A) := \sup_{t \geq A} \max(|1 - \phi(t)|, |\phi(-t)|), \]

(12)

where \( A \geq 1 \), and observe that \( \lim_{A \to \infty} \delta_{\phi}(A) = 0. \)

3.1 Exchange-invariance of univariate polynomials and shallow nets

In this subsection, a shallow net with one neuron is constructed to replace a univariate homogeneous polynomial together with a polynomial of lower degree. It is shown in the following proposition that such a replacement does not degrade the polynomial approximation property.

**Proposition 1** Under Assumption 2 with \( c_0 > 0, r_0 = s_0 + v_0 \) and \( \theta_0 \in \mathbb{R} \), let \( k \in \{0, \ldots, s_0\} \) and \( p_k(t) = \sum_{i=0}^{k} u_i t^i \) with \( u_k \neq 0 \). Then for an arbitrary \( \varepsilon \in (0, 1) \),

\[ |p_k(t) - u_k \frac{k!}{\mu_k^{(k)}(\theta_0)} \phi(\mu_k t + \theta_0) - p_{k-1}^*(t)| \leq \varepsilon, \quad \forall t \in [-1, 1], \]

(13)

where

\[ \mu_k := \mu_{k, \varepsilon} := \begin{cases} \min \left\{ 1, \frac{\varepsilon |\phi(\theta_0) (k+1)}{|u_k| \max_{0 \leq i \leq s_0} |\phi^{(k+1)}(t)|} \right\}, & \text{if } 0 \leq k \leq s_0 - 1, \\ \min \left\{ 1, \frac{\varepsilon |\phi(\theta_0) |\Gamma(s_0+v_0+1)}{s_0! (v_0+1)! |u_{s_0}|} \right\}, & \text{if } k = s_0, \end{cases} \]

(14)

\( p_{k-1}^*(t) = 0 \) and

\[ p_{k-1}^*(t) := \sum_{i=0}^{k-1} u_i^* t^i := \sum_{i=0}^{k-1} \left( u_i - \frac{u_k k! \phi^{(i)}(\theta_0)}{\phi^{(k)}(\theta_0) \mu_k^{k-i+1}} \right) t^i. \]

(15)

The proof of Proposition 1 requires the following Taylor representation which is an easy consequence of the classical Taylor formula

\[ \psi(t) = \sum_{i=0}^{\ell-1} \frac{\psi^{(i)}(t_0)}{i!} (t - t_0) + \frac{1}{(\ell - 1)!} \int_{t_0}^{t} \psi^{(\ell)}(u) (t-u)^{\ell-1} du \]

with remainder in integral form, and using the formula \( \int_{t_0}^{t} (t - u)^{\ell-1} du = \frac{(t-t_0)^\ell}{\ell} \). To obtain the Taylor polynomial of degree \( k \), this formula does not require \( \psi \) to be \((k+1)\) times differentiable. This observation is important throughout our analysis.

**Lemma 1** Let \( \ell \geq 1 \) and \( \psi \) be \( \ell \) times differentiable on \( \mathbb{R} \). Then for \( t, t_0 \in \mathbb{R} \),

\[ \psi(t) = \psi(t_0) + \frac{\psi'(t_0)}{1!} (t - t_0) + \cdots + \frac{\psi^{(\ell)}(t_0)}{\ell!} (t - t_0)^\ell + r_{\ell}(t), \]

(16)

where

\[ r_{\ell}(t) = \frac{1}{(\ell - 1)!} \int_{t_0}^{t} \left[ \psi^{(\ell)}(u) - \psi^{(\ell)}(t_0) \right] (t-u)^{\ell-1} du. \]

(17)
We are now ready to prove Proposition 1.

**Proof of Proposition 1.** Since \( \mu_k \in (0, 1] \) from its definition, we may apply Lemma 1 with \( t_0 = \theta_0 \) and \( \ell = k \) to obtain

\[
\phi(\mu_k t + \theta_0) = \sum_{i=0}^{k} \frac{\phi^{(i)}(\theta_0)}{i!} (\mu_k t)^i + r_{k, \mu_k}(t),
\]

where \( r_{0, \mu_0} = \phi(\mu_k t + \theta_0) - \phi(\theta_0) \) and

\[
r_{k, \mu_k}(t) := \frac{1}{(k-1)!} \int_{\theta_0}^{\mu_k t + \theta_0} \left[ \phi^{(k)}(u) - \phi^{(k)}(\theta_0) \right] (\mu_k t + \theta_0 - u)^{k-1} du
\]

(18) for \( k \geq 1 \). It follows that

\[
t^k = \frac{k!}{\mu_k \phi^{(k)}(\theta_0)} \phi(\mu_k t + \theta_0) + q_{k-1}(t) - \frac{k!}{\mu_k \phi^{(k)}(\theta_0)} r_{k, \mu_k}(t),
\]

where

\[
q_{k-1}(t) = \frac{-k!}{\mu_k \phi^{(k)}(\theta_0)} \sum_{i=0}^{k-1} \frac{\phi^{(i)}(\theta_0)}{i!} (\mu_k t)^i,
\]

so that

\[
p_k(t) = u_k \frac{k!}{\mu_k \phi^{(k)}(\theta_0)} \phi(\mu_k t + \theta_0) + p_{k-1}(t) - u_k \frac{k!}{\mu_k \phi^{(k)}(\theta_0)} r_{k, \mu_k}(t),
\]

with \( p_{k-1} \) defined by (15). What is left is to estimate the remainder \( u_k \frac{k!}{\mu_k \phi^{(k)}(\theta_0)} r_{k, \mu_k}(t) \). To this end, we observe, for the case \( k = 0 \), from the definition of \( \mu_0 \), that for any \( t \in [-1, 1] \),

\[
\left| u_0 \frac{1}{\phi(\theta_0)} r_{0, \mu_0}(t) \right| \leq \frac{|u_0|}{\max_{\theta_0 - 1 \leq \tau \leq \theta_0 + 1} |\phi'(\tau)| \mu_0 |t|} \leq \frac{1}{|\phi(\theta_0)|} \varepsilon |\phi(\theta_0)| = \varepsilon.
\]

For \( 1 \leq k \leq s_0 - 1 \), we may apply the estimate

\[
\left| \phi^{(k)}(\mu_k u + \theta_0) - \phi^{(k)}(\theta_0) \right| \leq \max_{\theta_0 - 1 \leq \tau \leq \theta_0 + 1} |\phi^{(k+1)}(\tau)| |\mu_k u|, \quad \forall \ u \in [0, t], \ t \in [-1, 1]
\]

to compute, for any \( t \in [-1, 1] \),

\[
\left| u_k \frac{k!}{\mu_k \phi^{(k)}(\theta_0)} r_{k, \mu_k}(t) \right| = \frac{k!}{\mu_k \phi^{(k)}(\theta_0)} \int_0^t \left[ \phi^{(k)}(\mu_k u + \theta_0) - \phi^{(k)}(\theta_0) \right] (t-u)^{k-1} du
\]

\[
\leq k(k+1) \varepsilon \int_0^1 u(1-u)^{k-1} du = k(k+1) \varepsilon \frac{\Gamma(2) \Gamma(k)}{\Gamma(k+2)} = \varepsilon.
\]

Finally, for \( k = s_0 \), we may apply the Lipschitz property of \( \phi^{(s_0)} \) to obtain

\[
\phi^{(s_0)}(\mu_k u + \theta_0) - \phi^{(s_0)}(\theta_0) \leq c_0 |\mu_k u| v_0, \quad \forall \ u \in [0, t], \ t \in [-1, 1],
\]

so that for any \( t \in [-1, 1] \), we have

\[
\left| u_{s_0} \frac{s_0!}{\mu_{s_0} \phi^{(s_0)}(\theta_0)} r_{s_0, \mu_{s_0}}(t) \right| = \frac{s_0 u_{s_0}}{\phi^{(s_0)}(\theta_0)} \int_0^t \left[ \phi^{(s_0)}(\mu_{s_0} u + \theta_0) - \phi^{(s_0)}(\theta_0) \right] (t-u)^{s_0-1} du
\]

\[
\leq \frac{\mu_{s_0}^{s_0} c_0 s_0 |u_{s_0}|}{\phi^{(s_0)}(\theta_0)} \int_0^1 u_{s_0} (1-u)^{s_0-1} du \leq \frac{\mu_{s_0}^{s_0} c_0 s_0 |u_{s_0}|}{\phi^{(s_0)}(\theta_0)} \frac{\Gamma(s_0 + 1) \Gamma(s_0)}{\Gamma(s_0 + 1 + v_0)} \leq \varepsilon.
\]

This completes the proof of Proposition 1. \( \square \)
Approximation of univariate polynomials by neural networks and the product gate

Our second tool, to be presented in the following proposition, shows that the approximation capability of shallow nets is not worse than that of polynomials of the same order (degree + 1) as the cardinality of weights of the shallow nets.

**Proposition 2** Under Assumption 2 with \( r_0 = s_0 + v_0 \) and \( \theta_0 \in \mathbb{R} \), let \( k \in \{0, \ldots, s_0\} \) and \( p_k(t) = \sum_{i=0}^{k} u_i t^i \). Then for an arbitrary \( \varepsilon \in (0, 1) \), there exists a shallow net

\[
h_{k+1}(t) := \sum_{j=1}^{k+1} a_j \phi(w_j \cdot t + \theta_0)
\]

with \( 0 < w_j \leq 1 \) and

\[
|a_j| \leq \tilde{C}_1 \left\{ \begin{array}{ll}
\left( 1 + \sum_{i=0}^{k} |u_i| \right)^{(k+1)!} \varepsilon^{-(k+1)!}, & \text{if } 0 \leq k \leq s_0 - 1, \\
\left( 1 + \sum_{i=0}^{s_0} |u_i| \right)^{(1+s_0/v_0)s_0!} \varepsilon^{-(1+s_0/v_0)s_0!}, & \text{if } k = s_0,
\end{array} \right.
\]

for \( 1 \leq j \leq k + 1 \), such that

\[
|p_k(t) - h_{k+1}(t)| \leq \varepsilon, \quad \forall \ t \in [-1, 1],
\]

where \( \tilde{C}_1 \geq 1 \) is a constant depending only on \( \phi, \theta_0, v_0 \) and \( s_0 \), to be specified explicitly in the proof of the derivation.

We remark, however, that to arrive at a fair comparison with polynomial approximation, the polynomial degree \( k \) should be sufficiently large, so that the norm of weights of the shallow nets could also be extremely large. In the following discussion, we require \( k \) to be independent of \( \varepsilon \) in order to reduce the norm of the weights. Based on Proposition 2, we are able to derive the following proposition, which yields a “product-gate” property of deep nets.

**Proposition 3** Under Assumption 3 with \( r_0 = s_0 + v_0 \) and \( \theta_0 \in \mathbb{R} \), for \( \varepsilon \in (0, 1) \), there exists a shallow net

\[
h_3(t) := \sum_{j=1}^{3} a_j \phi(w_j \cdot t + \theta_0)
\]

with

\[
0 < w_j \leq 1, \quad |a_j| \leq \tilde{C}_2 \left\{ \begin{array}{ll}
\varepsilon^{-6}, & \text{if } s_0 \geq 3, \\
\varepsilon^{-6/v_0}, & \text{if } s_0 = 2
\end{array} \right.
\]

for \( j = 1, 2, 3 \), such that for any \( U, U' \in [-1, 1] \),

\[
|UU' - (2h_3((U + U')/2) - h_3(U)/2 - h_3(U')/2)| \leq \varepsilon,
\]

where \( \tilde{C}_2 \) is a constant depending only on \( s_0, v_0, \phi \) and \( \theta_0 \).
For $\varepsilon > 0$, we apply Proposition 2 to the polynomial $t^2$ to derive a shallow net

$$h_3(t) = \sum_{j=1}^{3} a_j \varphi(w_j \cdot t + \theta_0)$$

with $0 < w_j \leq 1$ and

$$|a_j| \leq \tilde{C}_1 \left\{ \begin{array}{ll} 2^6 \varepsilon^{-6}, & \text{if } s_0 \geq 3, \\ 2^{s_0} \varepsilon - \frac{6}{s_0}, & \text{if } s_0 = 2 \end{array} \right.$$  \hspace{1cm} (23)

for $j = 1, 2, 3$, such that

$$|t^2 - h_3(t)| \leq \varepsilon, \quad t \in [-1, 1].$$  \hspace{1cm} (24)

Since

$$UU' = \frac{4\left(U+U'\right)^2 - U^2 - (U')^2}{2}$$

and $U, U' \in [-1, 1]$ implies $(U + U')/2 \in [-1, 1]$, we have

$$|h_3((U + U')/2) - ((U + U')/2)| \leq \varepsilon, \quad |h_3(U) - U^2| \leq \varepsilon, \quad |h_3(U') - (U')^2| \leq \varepsilon.$$

This completes the proof of Proposition 3 by scaling $\varepsilon$ to $\varepsilon/3$. \hfill \Box

To end this subsection, we present the proof of Proposition 2.

**Proof of Proposition 2.** Observe that

$$\max \left\{ \frac{1}{\min(1,a)} \right\} = \max \left\{ 1, \frac{1}{a} \right\}$$

for $a > 0$ and max \left\{ $1, \frac{|u_k|}{\varepsilon}$ \right\} \leq \max \left\{ 1, \left( \frac{|u_k|}{\varepsilon} \right)^{1/\nu_0} \right\}$. For the case $k = s_0$, the constant $\mu_k = \mu_{k,\varepsilon}$ defined by (14) satisfies

$$\frac{1}{\mu_k} \leq C_{\phi, s_0} \max \left\{ 1, \left( \frac{|u_k|}{\varepsilon} \right)^{1/\nu_0} \right\},$$

where $C_{\phi, s_0}$ is a constant depending on $\phi$ and $s_0$ and given by

$$C_{\phi, s_0} = \max \left\{ \max_{1 \leq k \leq s_0-1} \frac{\| \varphi^{(k+1)} \| C_{\theta_0-1, \theta_0+1} }{\| \varphi^{(k)} \| (k+1)!} \right\}.$$

For $0 \leq i \leq k-1$, the $i$-th coefficient of the polynomial $p_{k-1}^*$ is bounded by

$$|u_i| + \frac{|u_k|k! |\phi^{(i)}(\theta_0)|}{|\phi^{(k)}(\theta_0)|} C_{\phi, s_0} \max \left\{ 1, \left( \frac{|u_k|}{\varepsilon} \right)^{k-i} \right\} \leq \left( 1 + \frac{\sum_{i=0}^{k-1} \frac{|\phi^{(i)}(\theta_0)|}{|\phi^{(k)}(\theta_0)|} k! \right) (1 + C_{\phi, s_0}^k \| u \|_1 \max \left\{ 1, \left( \frac{\| u \|_1}{\varepsilon} \right)^{k/\nu_0} \right\} \leq \tilde{C}_k \| u \|_1 \max \left\{ 1, \left( \frac{\| u \|_1}{\varepsilon} \right)^{k/\nu_0} \right\},$$

where $\| u \|_1 = \sum_{i=0}^{k} |u_i|$ and the constant $\tilde{C}_k$ is given by

$$\tilde{C}_k = \left( 1 + \frac{\sum_{i=0}^{k-1} \frac{|\phi^{(i)}(\theta_0)|}{|\phi^{(k)}(\theta_0)|} + 1}{|\phi^{(k)}(\theta_0)|} \right) (1 + C_{\phi, s_0}^k).$$
Also, the coefficient of $\phi(\mu_k t + \theta_0)$ in (13) satisfies
\[
\left| \frac{u_k}{\mu_k^k \phi^{(k)}(\theta_0)} \right| \leq \tilde{C}_k \|u\|_1 \max \left\{ 1, \left( \frac{\|u\|_1}{\epsilon} \right)^{\frac{1}{2k}} \right\}.
\]

Denote $C^\prime_{s_0} = \max_{0 \leq k \leq s_0} \tilde{C}_k(k+1)^{k/v_0}$. Then it follows from Proposition 1 with $\epsilon$ scaled to $\frac{\epsilon}{k+1}$, that
\[
\max_{-1 \leq t \leq 1} |p_k(t) - a_1\phi(w_1 t + \theta_0) - p_{k-1}^*(t)| \leq \frac{\epsilon}{k+1},
\]
where $p_{k-1}^*(t) = \sum_{t_i=0}^{k-1} c_i t_i$ satisfies $|c_i| \leq C^\prime_{s_0} \|u\|_1^{k+1} \frac{k}{\epsilon} - \frac{k}{\epsilon} \alpha$ for $i = 0, \ldots, k-1, w_1 \in (0, 1]$ and $|a_1| \leq C^\prime_{s_0} \|u\|_1 \frac{k}{\epsilon} - \frac{k}{\epsilon} \alpha$. If the leading term of $p_{k-1}^*(t)$ is $c_{i_0} t^{i_0}$ with $0 \leq i_0 \leq k-1$, then we may apply Proposition 1 with $\frac{\epsilon}{k+1}$ and $v_0 = 1$ again to obtain
\[
\max_{-1 \leq t \leq 1} |p_{k-1}^*(t) - a_2\phi(w_2 t + \theta_0) - p_{i_0-1}^*(t)| \leq \frac{\epsilon}{k+1},
\]
where $w_2 \in (0, 1]$, and $a_2$ as well as the coefficient $c^*_{i_0}$ of $p_{i_0-1}^*(t) = \sum_{i=0}^{i_0} c^*_i t^i$ are bounded above by
\[
C^\prime_{s_0} \left( k C^\prime_{s_0} \|u\|_1^{k+1} \frac{k}{\epsilon} - \frac{k}{\epsilon} \alpha \right)^{i_0-1} \leq k^k \left( C^\prime_{s_0} \|u\|_1^{k+1} \frac{k}{\epsilon} - \frac{k}{\epsilon} \alpha \right)^{i_0-1} \leq k^k \left( C^\prime_{s_0} \|u\|_1^{k+1} \frac{k}{\epsilon} - \frac{k}{\epsilon} \alpha \right)^{i_0-1}.
\]

Then our conclusion follows by mathematical induction with the constant $\tilde{C}_1$ given by $\tilde{C}_1 = k^{k+1} (C^\prime_{s_0})^k$. The case $k \leq s_0 - 1$ can be easily verified with the same procedure. This completes the proof of Proposition 2. \hfill \Box

### 3.3 Approximating smooth functions by products of polynomials and neural networks

In this subsection, we discuss the approximation of continuous functions on $\mathbb{J} := [0, 1/2]$ by sums of the products of Taylor polynomials and shallow nets. Let $n \in \mathbb{N}$ and $t_j = \frac{j}{2^n}$ with $j = 0, 1, \ldots, n$ be the equally spaced points on $\mathbb{J}$. For an arbitrary $t \in \mathbb{J}$, there is some $j_0$, such that $t_{j_0} \leq t < t_{j_0+1}$ ($t_{n-1} \leq t \leq t_n$ when $t = 1/2$). Since
\[
-4A n(t - t_j) + A \leq -A \quad \text{for} \quad j = 0, 1, \ldots, j_0 - 1,
\]
and
\[
-4A n(t - t_j) + A > A \quad \text{for} \quad j = j_0 + 1, j_0 + 2, \ldots, n,
\]
we may derive from (12) the following localized approximation property:

\[
\left\{ \begin{array}{ll}
|\phi(-4An(t - t_j) + A)| & \leq \delta_\phi(A), & \text{if} \ j \leq j_0 - 1, \\
|\phi(-4An(t - t_j) + A) - 1| & \leq \delta_\phi(A), & \text{if} \ j_0 + 1 \leq j \leq n.
\end{array} \right.
\]

(25)

For a purpose of approximation theory, we need the following error estimate of the Taylor expansion which is an easy consequence of Lemma 1.
Lemma 2 Let $\psi \in Lip^{(r,c'_0)}_s$ with $r = s + v$, $s \in \mathbb{N}_0$, $0 < v \leq 1$ and $c'_0 > 0$. Define

$$T_{s,\psi,\tilde{i}}(t) := \sum_{j=0}^{s} \frac{\psi^{(j)}(\tilde{i})}{j!} (t - \tilde{i})^j.$$

Then

$$|\psi(t) - T_{s,\psi,\tilde{i}}(t)| \leq \frac{c'_0}{s!}|t - \tilde{i}|^r, \quad \forall \ t, \tilde{i} \in \mathbb{J}. \quad (26)$$

With the localized approximation property \([25]\) and Lemma 2, we now define

$$\Phi_{n,s,g,A}(t) := \sum_{j=0}^{n} T_{s,g,j}(t)b_{A,j}(t), \quad (27)$$

where

$$b_{A,0}(t) := \phi(-4Ant + A),$$

and

$$b_{A,j}(t) := \phi(-4An(t - t_j + A)) - \phi(-4An(t - t_{j-1} + A)), \quad 1 \leq j \leq n.$$  

Note that each term in the approximant \([27]\) is the product of a Taylor polynomial and a shallow neural network function, with the special case of $s = 0$ already considered in \([2]\). We provide an error estimate for $\Phi_{n,s,g,A}$ in the following proposition.

Proposition 4 If $g \in Lip^{(r,c'_0)}_s$ with $r = s + v, s \in \mathbb{N}_0, 0 < v \leq 1, c'_0 > 0$ and $\phi$ is a bounded sigmoidal function, then

$$|g(t) - \Phi_{n,s,g,A}(t)| \leq \tilde{C}_3 (n\delta_0(A) + n^{-r}), \quad \forall \ t \in \mathbb{J},$$

where

$$\tilde{C}_3 := 2 \left( \frac{r'_0 + c'_0 \|\phi\|_{L^\infty(B)}}{s!} + \|g\|_{L^\infty(B)} \right).$$

Proof. For $t \in \mathbb{J}$, let $j_0$ be the integer that satisfies $t_{j_0} \leq t < t_{j_0+1}$ for $0 \leq j_0 \leq n - 2$, and $t_{j_0} \leq t \leq t_{j_0+1}$ for $j_0 = n - 1$, while $t_{n-1} \leq t \leq t_n$ if $t = 1/2$. Then by separating $\sum_{j=0}^{n}$ into $\sum_{j=0}^{j_0} + \sum_{j=j_0+1}^{n}$, it follows from \((27)\) that

$$\Phi_{n,s,g,A}(t) = \sum_{j=0}^{j_0} (T_{s,g,j}(t) - T_{s,g,t_{j+1}}(t))\phi(-4An(t - t_j + A))$$

$$+ \sum_{j=j_0+1}^{n-1} (T_{s,g,j}(t) - T_{s,g,t_{j+1}}(t)) (\phi(-4An(t - t_j + A)) - 1)$$

$$+ T_{s,g,t_{n-1}}(t) (\phi(-4An(t - t_n + A) + A) - 1) + T_{s,g,t_{n+1}}(t),$$

where the last term appears because the term $T_{s,g,t_{j_0+1}}(t)b_{A,j_0+1}(t)$ is separated in \((27)\) into the above summations. It follows by considering the term with $j = j_0$ from the first
such that 

\[ |g(t) - \Phi_{n,s,g,A}(t)| \leq \sum_{j=0}^{j_0-1} |T_{s,g,t_j}(t) - T_{s,g,t_{j+1}}(t)| |\phi(-4An(t-t_j) + A)| \]

+ \sum_{j=j_0+1}^{n-1} |T_{s,g,t_j}(t) - T_{s,g,t_{j+1}}(t)| |\phi(-4An(t-t_j) + A) - 1|

+ |T_{s,g,t_n}(t)| |\phi(-4An(t-t_n) + A) - 1| + |T_{s,g,t_{j_0+1}}(t) - g(t)|

+ |T_{s,g,t_{j_0}}(t) - g(t) + g(t) - T_{s,g,t_{j_0+1}}(t)| |\phi(-4An(t-t_{j_0}) + A)|.

Noting (25) and Lemma 2, we have

\[ |g(t) - \Phi_{n,s,g,A}(t)| \leq (2n-1) \max_{0 \leq j \leq n} |T_{s,g,t_j}(t)| \delta_\phi(A) + \frac{c_0'}{s!} (1 + 2 \|\phi\|_{L_\infty(\mathbb{R})}) n^{-r}. \]

On the other hand, since (26) implies

\[ \max_{0 \leq j \leq n} |T_{s,g,t_j}(t)| \leq \frac{c_0'}{s!} + \|g\|_{L_\infty(\mathbb{J})}, \]

we have

\[ |g(t) - \Phi_{n,s,g,A}(t)| \leq (2n-1) \left( \frac{c_0'}{s!} + \|g\|_{L_\infty(\mathbb{J})} \right) \delta_\phi(A) + \frac{c_0'}{s!} (1 + 2 \|\phi\|_{L_\infty(\mathbb{R})}) n^{-r}. \]

This completes the proof of Proposition 4. □

3.4 Approximation of univariate functions by neural networks with two hidden layers

Based on Propositions 2, 3 and 4, we prove the following theorem on the construction of deep nets with two hidden layers for the approximation of univariate smooth functions.

**Theorem 4** Let \( g \in Lip_\phi^{r,c_0'} \) with \( c_0' > 0, r = s + v, s \in \mathbb{N}_0, 0 < v \leq 1 \). Then under Assumption 3 with \( c_0 > 0, r_0 = s_0 + v_0, 0 < v_0 \leq 1 \), and \( s_0 \geq \max\{s,2\} \), for an arbitrary \( 0 < \varepsilon \leq 1 \), there exists a deep net of the form

\[ H_{3(n+3),s+3,A}(t) = \sum_{j=1}^{3n} a_j^* \phi \left( \sum_{i=1}^{s+3} a_{j,i}^* \phi(w_{j,i}^*t + \theta_{j,i}^*) + \theta_j^* \right), \quad t \in \mathbb{J} \quad (28) \]

that satisfies \( |\theta_j^*|, |\theta_{j,i}^*| \leq 1 + 3An + |\theta_0|, |w_{j,i}^*| \leq 4An \) and

\[ |a_j^*|, |a_{j,i}^*| \leq \tilde{C}_4 \]

\[ \begin{aligned}
\varepsilon^{-7(s+1)!}, & \quad \text{if } s_0 \geq 3, s_0 > s \\
\varepsilon^{-\frac{7}{20}(s+1)!}, & \quad \text{if } s_0 \geq 3, s_0 = s, \\
\varepsilon^{-\frac{2s_0+6}{5}(s+1)!}, & \quad \text{if } s_0 = 2, s_0 > s, \\
\varepsilon^{-\frac{s_0+6}{5}(s+1)!}, & \quad \text{if } s_0 = 2, s_0 = s \end{aligned} \quad (29) \]

such that

\[ |g(t) - H_{3(n+3),s+3,A}(t)| \leq \tilde{C}_4 (n\delta_\phi(A) + n^{-r} + n\varepsilon), \quad \forall \ t \in \mathbb{J}, \quad (30) \]

for some constant \( \tilde{C}_4 \) independent of \( \varepsilon, n \) and \( A \).
The main novelty of the above theorem is that \((30)\) holds for an arbitrary \(r > 0\) and the parameters of the deep net \((28)\) are controllable, provided that the activation function satisfies Assumption 2 with \(r_0 \geq r\). This deviates Theorem 4 from the classical results in \([2,3,24,32,34]\), in which either \(0 < r \leq 1\) is required or extremely large parameters are needed. We remark that since the goal of this paper is to approximate radial functions, we only need error estimates for approximation of univariate functions, though the approach in this paper can be extended to the realization of more general multivariate functions by standard arguments.

Proof of Theorem 4 The proof of this theorem is divided into three steps: first to decouple the product, then to approximate the Taylor polynomials, and finally to deduce the approximation errors, by applying Propositions 3, 2, and 4, respectively.

Step 1: Decoupling products. From Assumption 2 the definition of \(b_{A,j}\), and Lemma 2 we observe that
\[
|b_{A,j}(t)| \leq 2, \quad |T_{s,g,t_j}(t)| \leq \|g\|_{L_\infty} + c_0', \quad \forall \ t, t_j \in \mathbb{J}.
\]

By denoting
\[
B_1 := 4\|g\|_{L_\infty} + c_0' + 2
\]
we have, for an arbitrary \(t \in \mathbb{J}\), \(b_{A,j}(t)/B_1, T_{s,g,t_j}(t)/B_1 \in [-1/4,1/4]\). It then follows from Proposition 3 with \(U = b_{A,j}(t)/B_1\) and \(U' = T_{s,g,t_j}(t)/B_1\) that a shallow net
\[
h_3(t) := \sum_{j=1}^{3} a_j \phi(w_j \cdot t + \theta_0)
\]
can be constructed to satisfy the conditions \(0 < w_j \leq 1\) and the bound \((21)\) for \(a_j\) that depends only on \(\varepsilon\), such that
\[
\left| T_{s,g,t_j}(t) b_{A,j}(t) - B_1^2 \left( 2h_3 \left( \frac{T_{s,g,t_j}(t) + b_{A,j}(t)}{2B_1} \right) - \frac{h_3 \left( \frac{b_{A,j}(t)}{B_1} \right)}{2} - \frac{h_3 \left( \frac{T_{s,g,t_j}(t)}{B_1} \right)}{2} \right) \right| \leq B_1^2 \varepsilon. \tag{31}
\]
Furthermore, it follows from \((21)\) and \(\|\phi'\|_{L_\infty} \leq 1\) that for any \(\tau, \tau' \in \mathbb{J}\),
\[
|h_3(\tau) - h_3(\tau')| \leq \sum_{j=1}^{3} |a_j| |\tau - \tau'| \leq 3\tilde{C}_2|\tau - \tau'| \begin{cases} \varepsilon^{-6}, & \text{if } s_0 \geq 3, \\ \varepsilon^{-\frac{6}{s_0}}, & \text{if } s_0 = 2. \end{cases} \tag{32}
\]

Step 2: Approximating Taylor polynomials. Since \(t, t_j \in \mathbb{J}\), we have \(t - t_j \in [-1,1]\). Let \(\varepsilon_1 \in (0,1/4]\) to be determined later. Then, for any fixed \(j \in \{1,2,\ldots,n\}\), it follows from Proposition 2 with \(p_s(t - t_j) = T_{s,g,t_j}(t)/B_1 = \sum_{i=0}^{s} \frac{g^{(i)}(t)}{i!B_1^i} (t - t_j)^i\) that there exists a shallow net
\[
h_{s+1,j}(t) := \sum_{i=1}^{s+1} a_{i,j} \phi(w_{i,j} \cdot t - w_{i,j} t_j + \theta_0) \tag{33}
\]
with $0 < w_{i,j} \leq 1$ and
\[
|a_{i,j}| \leq \tilde{C}_5 \left\{ \begin{array}{ll}
\varepsilon_1^{-1(s+1)!}, & \text{if } s_0 > s, \\
\varepsilon_1^{-1(s_0/v_0+1)s_0!}, & \text{if } s_0 = s,
\end{array} \right.
\] (34)

where $\tilde{C}_5 := \tilde{C}_1 \left( 1 + \sum_{i=0}^{s} \left( \frac{\|g^{(i)}\|_{\infty}}{d_{B_1}} \right)^{(s_0/v_0+1)s_0!} \right)$, such that
\[
|T_s, t_j (t)/B_1 - h_{s+1, j}(t)| \leq \varepsilon_1, \quad 1 \leq j \leq n, \forall \ t \in \mathbb{J}.
\] (35)

**Step 3: Construction of deep nets with error bounds.** Define
\[
H_{3n+3, s+3, A}(t) := \sum_{j=0}^{n} H_{A,j}(t)
\] (36)

with
\[
H_{A,j}(t) := B_1^2 \left[ 2h_3 \left( \frac{h_{s+1, j}(t)}{2} + \frac{b_{A,j}(t)}{2B_1} \right) - h_3 \left( \frac{h_{s+1, j}(t)}{2} \right) - \frac{b_{A,j}(t)}{2B_1} \right].
\] (37)

Then it follows from (37) and (31) that
\[
\left| H_{3n+3, s+3, A}(t) - \Phi_{n, s, g, A}(t) \right| \leq \sum_{j=0}^{n} \left| H_{A,j}(t) - T_s, t_j (t) b_{A,j}(t) \right|
\]
\[
\leq \sum_{j=0}^{n} \left| H_{A,j}(t) - B_1^2 \left( 2h_3 \left( \frac{T_s, t_j (t) + b_{A,j}(t)}{2B_1} \right) - h_3 \left( \frac{b_{A,j}(t)}{2B_1} \right) \right) \right|
\]
\[
+ (n + 1) B_1^2 \varepsilon.
\] (38)

Also, since $0 < \varepsilon_1 \leq 1/4$ and $T_s, t_j (t)/B_1 \leq 1/4$, it follows from (35) and (32) that
\[
\left| h_3(h_{s+1, j}(t)) - h_3(T_s, t_j (t)/B_1) \right| \leq 3 \tilde{C}_2 \varepsilon_1 \left\{ \begin{array}{ll}
\varepsilon^{-6}, & \text{if } s_0 \geq 3, \\
\varepsilon^{-\frac{9}{v_0}}, & \text{if } s_0 = 2,
\end{array} \right.
\]

and
\[
\left| h_3 \left( \frac{h_{s+1, j}(t)}{2} + \frac{b_{A,j}(t)}{2B_1} \right) - h_3 \left( \frac{T_s, t_j (t) + b_{A,j}(t)}{2B_1} \right) \right| \leq 3 \tilde{C}_2 \varepsilon_1 \left\{ \begin{array}{ll}
\varepsilon^{-6}, & \text{if } s_0 \geq 3, \\
\varepsilon^{-\frac{9}{v_0}}, & \text{if } s_0 = 2.
\end{array} \right.
\]

Therefore, plugging the above two estimates into (38), we obtain for any $t \in \mathbb{J}$
\[
\left| H_{3n+3, s+3, A}(t) - \Phi_{n, s, g, A}(t) \right| \leq (n + 1) B_1^2 \varepsilon + \frac{9 \tilde{C}_2 B_1^2}{2} \varepsilon_1 \left\{ \begin{array}{ll}
\varepsilon^{-6}, & \text{if } s_0 \geq 3, \\
\varepsilon^{-\frac{9}{v_0}}, & \text{if } s_0 = 2.
\end{array} \right.
\] (39)

From the above argument, we may set $\varepsilon_1 = \left\{ \begin{array}{ll}
\varepsilon^{\frac{7}{9}}, & \text{if } s_0 \geq 3, \\
\varepsilon^{\frac{1 + \frac{6}{v_0}}{9}}, & \text{if } s_0 = 2,
\end{array} \right.$ so that (39) implies that for any $t \in \mathbb{J}$
\[
\left| H_{3n+3, A}(t) - \Phi_{n, s, g, A}(t) \right| \leq (n + 1)(B_1^2 + \frac{9}{8} \tilde{C}_2 B_1^2) \varepsilon.
\]
Applying this together with Proposition 4, we may conclude, for any \( t \in J \), that
\[
|g(t) - H_{3n,s+3,A}(t)| \leq |g(t) - \Phi_{n,s,g,A}(t)| + |\Phi_{n,s,g,A}(t) - H_{3n,s+3,A}(t)|
\]
\[
\leq (\tilde{C}_3 + B_2^2 + 9\tilde{C}_2B_2^2/8)((n + 1)\delta_\phi(A) + n^{-r} + (n + 1)\varepsilon).
\]

What is left is to find bounds of the parameters in \( H_{3n,s+3,A} \). This can be done by applying (36), (37), (33), the definition of \( b_{A,j} \), (21) and (34) to yield
\[
H_{3n+3,s+3,A}(t) = \sum_{j=1}^{3n+3} a_j^* \phi \left( \sum_{i=1}^{s+3} a_{j,i}^* \phi(w_{j,i}^* t + \theta_{j,i}^*) + \theta_j^* \right),
\]
by considering \( |\theta_j^*|, |\theta_{j,i}^*| \leq 1 + 3An |\theta_0|, |w_{j,i}^*| \leq 4An \), with \( a_j^*, a_{j,i}^* \) to satisfy (29) for the constant \( \tilde{C}_4 := \tilde{C}_3 + B_2^2 + 9\tilde{C}_2B_2^2/8 + 1 \), which is independent of \( \varepsilon, n \) or \( A \). This completes the proof of Theorem 4.

\( \square \)

4 Proofs of Main Results

This section is devoted to proving our main results, to be presented in three subsections, namely: Proof of Theorem 1, Proofs of Theorem 2, and Proof of Theorem 3, respectively.

4.1 Proof of Theorem 1

Our proof of Theorem 1 will require two mathematical tools on relationships among covering numbers [36, 37], lower bounds of approximation, and an upper bound estimate for the covering number of \( H_{tree}^{L,\alpha,R} \). It is well-known that the approximation capability of a class of functions depends on its “capacity” (see, for example, [20]). In the following lemma, we will establish some relationship between covering numbers and lower bound of approximation, when the target function is radial.

**Lemma 3** Let \( N \in \mathbb{N} \) and \( V \subseteq L_\infty(\mathbb{B}^d) \). If
\[
N(\varepsilon,V) \leq C_1^d C_2^d N^\beta \frac{N^\beta}{\varepsilon}, \quad \forall 0 < \varepsilon \leq 1
\]
with \( \beta, C_1^d, C_2^d > 0 \), then
\[
dist(Lip^{(\phi,r,co)}, V, L_\infty(\mathbb{B}^d)) \geq C_3^d \left[ N \log_2(N + C_4^d) \right]^{-r},
\]
where \( N(\varepsilon,V) \) denotes the \( \varepsilon \)-covering number of \( V \) in \( L_\infty(\mathbb{B}^d) \), which is the least number of elements in an \( \varepsilon \)-net of \( V \), \( C_4^d = C_3^d = \frac{C_0^d}{8} (\beta + 2r + 4)^r \) and \( C_4^d = 2C_1^d + 4C_2^dC_0^{-1}(\beta + 2r + 4)^r \).

The proof of Lemma 3 is motivated by [20], where a relation between the pseudo-dimension and lower bounds of approximating smooth functions was established. We postpone its proof to Section 5. The second relationship is a tight bound for covering numbers [6].
Lemma 4. Let \( L \in \mathbb{N}, c_1 > 0 \), and assume that \( \phi_j \in \text{Lip}^{(1,c_1)}_{R} \) to satisfy \( \|\phi_j\|_{L^\infty(B^d)} \leq 1 \), for \( j = 0, \ldots, L \). Then for any \( 0 < \varepsilon \leq 1 \),
\[
    \mathcal{N}(\varepsilon, \mathcal{H}^\text{tree}_{L,\alpha,R}) \leq \left( \frac{2L+5/2}{\varepsilon} c_1 L^{1/2} \frac{2^{L+1}}{A_{R,\alpha,L}} \right)^{2A_L},
\]
where \( A_{R,\alpha,L} := \mathcal{R}(A_L)^\alpha \) and \( A_L \) is defined by (4).

We are now ready to prove Theorem 1 by applying the above two lemmas.

Proof of Theorem 1. In view of Lemma 4, condition (40) is satisfied by \( V = \mathcal{H}^\text{tree}_{L,\alpha,R} \) with \( \tilde{C}_1 = 1 \), \( N = 2A_L \), \( \beta = (L + 1) \), and \( C_2 = 2L+5/2c_1^{L+1/2}R^{L+1} \). Then it follows from (41) that
\[
    \text{dist}(\text{Lip}^{(r,c_0)}, \mathcal{H}^\text{tree}_{L,\alpha,R}, L^\infty(B^d)) \leq \frac{c_0}{8} (\alpha L + \alpha + 2r + 4)^{-r}
    \times \left[ 2A_L \log_2 \left( 2A_L + 2 + 2^{L+9/2}c_0^{-1} c_1^{L+3/2} R^{L+1} (\alpha L + \alpha + 2r + 4)^r \right) \right]^{-r}.
\]

Noting that
\[
    \log_2 \left( 2A_L + 2 + 2^{L+9/2}c_0^{-1} c_1^{L+3/2} R^{L+1} (\alpha L + \alpha + 2r + 4)^r \right)
    \leq \log_2 \left( 4A_L + 8c_0^{-1} (2\alpha + 2r + 4)^r (2c_1 \mathcal{R})^{L+3/2} L^r \right)
    \leq [1 + \log_2 (4 + 8c_0^{-1} (2\alpha + 2r + 4)^r)] \log_2 (A_L + (2c_1 \mathcal{R})^{L+3/2} L^r),
\]
we may conclude that
\[
    \text{dist}(\text{Lip}^{(r,c_0)}, \mathcal{H}^\text{tree}_{L,\alpha,R}, L^\infty(B^d)) \geq \tilde{C}_1' \left[ L A_L \log_2 \left( A_L + (2c_1 \mathcal{R})^{L+3/2} L^r \right) \right]^{-r},
\]
where
\[
    \tilde{C}_1' := \frac{c_0 8^{-r} (\alpha + r + 2)^{-r}}{8} [1 + \log_2 (4 + 8c_0^{-1} (2\alpha + 2r + 4)^r)]^{-r}.
\]

Next, for \( a > 0 \) and \( \tilde{n} \geq 2 \), it follows from direct computation that
\[
    \log_2 (\tilde{n} + a) \leq \log_2 [\tilde{n}(1 + a)] \leq [1 + \log_2 (1 + a)] \log_2 \tilde{n},
\]
which together with \( a = (2c_1 \mathcal{R})^{L+3/2} L^r \) and \( \tilde{n} = A_L \), yields
\[
    \log_2 (\tilde{n} + (2c_1 \mathcal{R})^{L+3/2} L^r) \leq [1 + \log_2 ((2c_1 \mathcal{R})^{L+3/2} L^r + 1)] \log_2 \tilde{n}
    \leq \log_2 \tilde{n} + (L + 3/2) \log_2 (2c_1 \mathcal{R} + 1) \log_2 \tilde{n} + r \log_2 L \log_2 \tilde{n}
    \leq [1 + \log_2 (2c_1 \mathcal{R} + 1) + r] (L + 3) \log_2 \tilde{n}
    \leq 4[1 + r + \log_2 (2c_1 \mathcal{R} + 1)] L \log_2 \tilde{n}.
\]

So, we have from (43) that
\[
    \text{dist}(\text{Lip}^{(r,c_0)}, \mathcal{H}^\text{tree}_{L,\alpha,R}, L^\infty(B^d)) \geq C_2' (L^2 \tilde{n} \log_2 \tilde{n})^{-r},
\]
where
\[
    C_2' = \frac{c_0 8^{-r} (\alpha + r + 2)^{-r}}{8} [1 + \log_2 (4 + 8c_0^{-1} (2\alpha + 2r + 4)^r)]^{-r}.
\]
where \( C_2' := \tilde{C}'_2[4(1 + r + \log_2(2e_1 R + 1))]^{-r} \). This completes the proof of (6).

The proof (5) is easier. Let \( \mathbb{S}^{d-1} \) denote the unit sphere in \( \mathbb{R}^d \), and consider the manifold

\[
\mathcal{M}_n := \left\{ \sum_{i=1}^n a_i \phi_i(x) : \phi_i \in \mathbb{S}^{d-1}, \phi_i \in L^2([-1, 1]), a_i \in \mathbb{R} \right\}
\]

of ridge functions. It is easy to see that \( \mathcal{S}_{\phi_i,n} \subset \mathcal{M}_n \). Then it follows from [13, Theorem 4] there exist an integer \( \tilde{C}'_2 \) and some positive real number \( \tilde{C}'_3 \), such that for any \( f \in \text{Lip}(r,c_0) \),

\[
\text{dist}(f, \mathcal{S}_{\phi_i,n}, L_2(\mathbb{B}^d)) \geq \text{dist}(f, \mathcal{M}_{n-1, L_2(\mathbb{B}^d)}) \geq \tilde{C}'_2 \text{dist}(f, \mathcal{P}_C, L_2(\mathbb{B}^d)),
\]

where \( \mathcal{P}_s(\mathbb{B}^d) \) denotes the set of algebraic polynomials defined on \( \mathbb{B}^d \) of degrees not exceeding \( s \). But it was also proved in [14, Theorem 1] (with a scaling of constants in [14, P.105]), that

\[
\text{dist}(\text{Lip}(r,c_0), \mathcal{P}_C, L_2(\mathbb{B}^d)) \geq \tilde{C}'_4 n^{r/(d-1)},
\]

where \( \tilde{C}'_4 \) is a constant depending only on \( \tilde{C}'_2, c_0, n \) and \( r \). Therefore we have

\[
\text{dist}(\text{Lip}(r,c_0), \mathcal{S}_{\phi_i,n}, L_\infty(\mathbb{B}^d)) \geq \text{dist}(\text{Lip}(r,c_0), \mathcal{S}_{\phi_i,n}, L_2(\mathbb{B}^d)) \geq C_1' \tilde{n}^{r/(d-1)}
\]

with \( C_1' := \frac{\tilde{C}'_2 \tilde{C}'_4}{(d + 2)} \) by noting \( \tilde{n} = (d + 2)n \). This establishes (5) and completes the proof of Theorem 1 \( \Box \)

### 4.2 Proof of Theorem 2

We shall show that based on Assumption 2 Theorem 2 is a consequence of the following more general result, which we will first establish.

**Theorem 5** Let \( A \geq 1 \). Under Assumption 2 with \( r_0 = s_0 + v_0 \), \( s_0 \geq 2 \) and \( 0 < v_0 \leq 1 \). Then for any \( f \in \text{Lip}(r,c_0) \) with \( r \leq r_0 \) and any \( n \in \mathbb{N} \), there is a deep net

\[
H_{3n+3,s+3,6,d,A} = \sum_{j=1}^{3n+3} a_j^* \phi \left( \sum_{i=1}^{s+3} a_j^i \phi \left( \sum_{k=1}^{d} a_k^{j,i} \phi \left( \sum_{\ell=1}^{d} a_{k,\ell,j,i}^{*} \phi \left( w_{k,\ell,j,i}^{*} x^{(f)} + \theta_{k,\ell,j,i} \right) + \theta_{k,j,i} \right) + \theta_{j,i} \right) + \theta_{j}^{*} \right) + \theta_{j}^{*}.
\]

with \( |w_{k,\ell,j,i}^{*}| \leq 1 \), \( |\theta_{k,\ell,j,i}^{*}|, |\theta_{k,j,i}^{*}|, |\theta_{j,i}^{*}|, |\theta_{j}^{*}| \leq 1 + 3An + |\theta_0| \) and \( |a_j^*|, |a_j^{i}|, |a_k^{j,i}|, |a_{k,\ell,j,i}^{*}| \)

bounded by

\[
\tilde{C}_1 = \begin{cases} 
(An^2)^{48} n^{48(r+1)(1+7(s+1))}, & \text{if } s_0 \geq 3, s_0 > s \\
(An^2)^{48} n^{48(r+1)(1+\frac{7}{9})(s+1)),} & \text{if } s_0 = 3, s \geq 3, \\
(An^2)^{48} n^{\frac{6v_0+42}{v_0}(r+1)} & \text{if } s_0 = 2, s_0 > s, \\
(An^2)^{48} n^{\frac{6v_0+42}{v_0}(r+1)} & \text{if } s_0 = s = 2,
\end{cases}
\]

such that

\[
\|f - H_{3n+3,s+3,6,d,A}\|_{L_\infty(\mathbb{B}^d)} \leq \tilde{C}_2(n\delta_0(A) + n^{-r}),
\]

where \( \delta_0(A) \) is defined by (12) and \( \tilde{C}_1, \tilde{C}_2 \) are constants independent of \( n \) or \( A \).
**Proof.** We divide the proof into four steps: first to approximate $|x|^2$, next to unify the activation function, then to construct the deep net, and finally to derive bounds of the parameters.

**Step 1: Approximation of $|x|^2$.** Since $f \in Lip_{(r,c_0)}$, there exists some $g^* \in Lip_{(r,c_0)}$ such that $f(x) = g^*(|x|^2)$. Set $g(\cdot) := g^*(2\cdot)$. Then $f(x) = g(|x|^2/2)$ with $g \in Lip_2$. By Theorem 1 for any $0 < \varepsilon \leq 1$, there is a deep net of form (28) such that

$$|f(x) - H_{3n+3,s+3,\epsilon}(|x|^2/2)| \leq \tilde{C}_4(n\delta_\phi(A) + n^{-r} + n\varepsilon), \quad \forall \ x \in \mathbb{B}.$$

(46)

We will first treat components $x^{(\ell)}$ of $x = (x^{(1)}, \ldots, x^{(d)})$ separately. Let $0 < \varepsilon_1 \leq \frac{1}{272}$ to be determined below, depending on $\epsilon$. By Proposition 2 applied to the quadratic polynomial $t^2$, there exists a shallow net

$$h_3(t) := \sum_{k=1}^3 a_k \phi(w_k \cdot t + \theta_0)$$

with $0 < w_k \leq 1$ and $|a_k| \leq \tilde{C}_1 \left\{ \begin{array}{ll} 2^6 \varepsilon_1^{-6}, & \text{if } s_0 \geq 3, \\ 2^6 \varepsilon_1^{-6}, & \text{if } s_0 = 2 \end{array} \right.$

such that

$$|t^2 - h_3(t)| \leq \varepsilon_1, \quad \forall \ t \in \mathbb{R}.$$  

(47)

Hence, by setting

$$h_{3d}(x) := \sum_{\ell=1}^d h_3(x^{(\ell)})/2 = \sum_{k=1}^3 \left( \sum_{\ell=1}^d \frac{a_k}{2} \phi(w_k \cdot x^{(\ell)} + \theta_0) \right),$$

(48)

it follows from (47) that

$$||x|^2/2 - h_{3d}(x)|| \leq d\varepsilon_1/2, \quad \forall \ x \in \mathbb{B}.$$  

(49)

Hence, by the assumption $\|\phi\|_{L_{\infty}(\mathbb{R})} \leq 1$, we have, for $x \in \mathbb{B}$,

$$\sum_{\ell=1}^d \frac{a_k}{2} \phi(w_k \cdot x^{(\ell)} + \theta_0) \leq \frac{1}{2} \sum_{\ell=1}^d |a_k| \leq \tilde{C}_1 d \left\{ \begin{array}{ll} 2^6 \varepsilon_1^{-6}, & \text{if } s_0 \geq 3, \\ 2^6 \varepsilon_1^{-6}, & \text{if } s_0 = 2 \end{array} \right.$$  

(50)

In the following, we denote the above bound by $B$ and note that $B \geq 1$.

**Step 2: Unifying the activation function.** From (48), we note that $h_{3d}$ is a deep net with one hidden layers. In this step, we will apply Proposition 2 to unify the activation functions. For any $\varepsilon_2 \in (0, 1)$ to be determined, it follows from Proposition 2 applied to the linear function $t$, with $k = 1$ and $s_0 \geq 2$, that there exists a shallow net

$$h_2^*(t) := \sum_{k'=1}^2 a_k \phi(w_{k'} \cdot t + \theta_0)$$

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with
\[ 0 < w_{k'} \leq 1, \quad \text{and} \quad |a_{k'}| \leq 4\tilde{C}_1\varepsilon_2^{-6}, \] (51)
such that
\[ |t - h_2(t)| \leq \varepsilon_2, \quad \forall \ t \in [-1, 1]. \] (52)
Inserting \( t = \sum_{\ell=1}^{d} \frac{a_k}{B} \phi(w_k \cdot x^{(\ell)} + \theta_0) \) into (52), we have, for \( x \in \mathbb{B}^d \),
\[ \left| \sum_{\ell=1}^{d} \frac{a_k}{2} \phi(w_k \cdot x^{(\ell)} + \theta_0) - Bh_2 \left( \frac{\sum_{\ell=1}^{d} a_k \phi(w_k \cdot x^{(\ell)} + \theta_0)}{2B} \right) \right| \leq B\varepsilon_2. \] (53)
Write
\[ h_{6,d}(x) = \sum_{k=1}^{3} \sum_{k'=1}^{2} B_{ak'} \phi \left( w_{k'} \frac{\sum_{\ell=1}^{d} a_k \phi(w_k \cdot x^{(\ell)} + \theta_0)}{2B} + \theta_0 \right) \]
\[ =: \sum_{k=1}^{6} a_k' \phi \left( \sum_{\ell=1}^{d} a_k' \phi(w_k \cdot x^{(\ell)} + \theta_0) + \theta_0 \right). \] (54)
It then follows from (51) and (50) that \( 0 < w_{k'} \leq 1, \)
\[ |a_{k'}| \leq d\tilde{C}_1^2 \varepsilon_2^{-6} \left\{ \begin{array}{ll}
2^6 \varepsilon_1^{-6}, & \text{if } s_0 \geq 3, \\
\frac{6}{\varepsilon_0^6}, & \text{if } s_0 = 2,
\end{array} \right. \quad \text{and} \quad |a_k''| \leq \frac{|a_k|}{2} \leq \tilde{C}_1 \left\{ \begin{array}{ll}
\frac{2^5 \varepsilon_1^{-6}}{v_0^2}, & \text{if } s_0 \geq 3, \\
\frac{6}{\varepsilon_0^6}, & \text{if } s_0 = 2.
\end{array} \right. \]
Furthermore, (53) together with (50) yields the following bound valid uniformly for \( x \in \mathbb{B}^d \)
\[ |h_{3d}(x) - h_{6,d}(x)| = \left| \sum_{k=1}^{3} \sum_{\ell=1}^{d} \frac{a_k}{2} \phi(w_k \cdot x^{(\ell)} + \theta_0) - Bh_2 \left( \frac{\sum_{\ell=1}^{d} a_k \phi(w_k \cdot x^{(\ell)} + \theta_0)}{2B} \right) \right| \]
\[ \leq 3B\varepsilon_2 = 3\tilde{C}_1 \varepsilon_2 \left\{ \begin{array}{ll}
2^6 \varepsilon_1^{-6}, & \text{if } s_0 \geq 3, \\
\frac{6}{\varepsilon_0^6}, & \text{if } s_0 = 2.
\end{array} \right. \]
Setting \( \varepsilon_2 = 2^{-\frac{6}{6+s_0}} \frac{1}{3d\tilde{C}_1} \left\{ \begin{array}{ll}
\varepsilon_1^7, & \text{if } s_0 \geq 3, \\
\frac{6}{\varepsilon_0^6}, & \text{if } s_0 = 2,
\end{array} \right. \)
the above estimate yields
\[ |h_{3d}(x) - h_{6,d}(x)| \leq \varepsilon_1, \quad \forall \ x \in \mathbb{B}^d, \] (55)
and the parameters of \( h_{6,d}(x) \) satisfy
\[ 0 < w_{k'} \leq 1, \quad |a_k'|, |a_k''| \leq \tilde{C}_4 \left\{ \begin{array}{ll}
\varepsilon_1^{-48}, & \text{if } s_0 \geq 3, \\
\frac{6}{v_0^6 + 42} \varepsilon_1^6, & \text{if } s_0 = 2,
\end{array} \right. \] (56)
where \( \tilde{C}_4 \) is a constant depending only on \( v_0, \tilde{C}_1 \) and \( d \). Based on (49) and (55), we obtain
\[ ||x||^2 / 2 - h_{6,d}(x) | \leq \frac{d + 2}{2} \varepsilon_1, \quad \forall \ x \in \mathbb{B}^d. \] (57)
Since $\varepsilon_1 \leq \frac{1}{3\pi^2}$, we have
\[
\|h_{6,d}\|_{L_\infty(B^d)} \leq 1. \tag{58}
\]

**Step 3: Constructing the deep net.** Based on (54) and (28), we define
\[
H_{3n+3, s+3, 6, d, A} := H_{3n+3, s+3, A} \circ h_{6,d}(x)
\]
(59)
\[
= \sum_{i=1}^{3n+3} \sum_{j=1}^{s+3} a_{j,i}^* \left( \sum_{k=1}^{6} a_{k,j,i}^* \left( \sum_{l=1}^{d} a_{k,j,i}^* \phi \left( w_{k,j,i}^* x^l + \theta_0 \right) + \theta_0 \right) + \theta_j^* \right).
\]

In view of (46), we get
\[
|f(x) - H_{3n+3, s+3, 6, d, A}(x)| \leq \bar{C}_4(n \delta_0(A) + n^{-r} + n \varepsilon)
\]
\[
+ |H_{3n+3, s+3, A}(|x|^2/2) - H_{3n+3, s+3, A}(h_{6,d}(x))|, \quad \forall x \in B^d.
\tag{60}
\]

Recalling (35) with $\varepsilon_1 = 1$ and $|b_{A,l,t}(t)/B_1| \leq 1/4$, we have
\[
|h_{s+1,j}(t)| \leq 1, \quad \text{and} \quad \frac{|h_{s+1,j}(t)|}{2} + \frac{b_{A,j,t}}{2b_1} \leq 2, \quad t \in J.
\]

This together with (37) implies
\[
\sum_{i=1}^{s+3} |a_{j,i}^* \phi(w_{j,i}^* t + \theta_j^*)| \leq 2.
\]

Thus, from Theorem 4, we have, for $0 < t \leq 1/2$,
\[
\sum_{i=1}^{s+3} |a_{j,i}^* \phi(w_{j,i}^* t + \theta_j^*) + \theta_j^*)| \leq 3 + 3An + |\theta_0|, \quad |w_{j,i}^* t + \theta_j^*)| \leq 5An + |\theta_0| + 1. \tag{61}
\]

Thus, for $0 < \varepsilon < 1$, $0 < \varepsilon_1 < \frac{1}{3\pi^2}$ and $x \in B^d$, (58), (61), (29), (57) and $||\phi'||_{L_\infty(\mathbb{R})} \leq 1$ yield
\[
|H_{3n+3, s+3, A}(|x|^2/2) - H_{3n+3, s+3, A}(h_{6,d}(x))|
\]
\[
= \left| \sum_{j=1}^{3n+3} a_j^* \left( \sum_{i=1}^{s+3} a_{j,i}^* \phi(w_{j,i}^* |x|^2/2 + \theta_j^*) + \theta_j^* \right) \right| - \left| \sum_{j=1}^{3n+3} a_j^* \left( \sum_{i=1}^{s+3} a_{j,i}^* \phi(w_{j,i}^* h_{6,d}(x) + \theta_j^*) + \theta_j^* \right) \right|
\]
\[
\leq \sum_{j=1}^{3n+3} |a_j^*| \left| \sum_{i=1}^{s+3} a_{j,i}^* \phi(w_{j,i}^* |x|^2/2 + \theta_j^*) \right| - \sum_{i=1}^{s+3} |a_{j,i}^*| \phi(w_{j,i}^* h_{6,d}(x) + \theta_j^*)
\]
\[
\leq \sum_{j=1}^{3n+3} |a_j^*| \sum_{i=1}^{s+3} |a_{j,i}^*| \left| |x|^2/2 - h_{6,d}(x) \right|
\]
\[
\leq \bar{C}_5 An^2 \varepsilon_1 \left\{ \begin{array}{ll}
\varepsilon^{-7(s+1)!}, & \text{if } s_0 \geq 3, s_0 > s \\
\varepsilon^{-7(s+1)!}, & \text{if } s_0 = s \geq 3, \\
\varepsilon^{-q(s+1)!}, & \text{if } s_0 = 2, s_0 > s, \\
\varepsilon^{-q(s+1)!}, & \text{if } s_0 = s = 2.
\end{array} \right.
\]
where $\tilde{C}_5 \geq 1$ is a constant independent of $\varepsilon$, $\varepsilon_1$, $n$ or $A$. Now we determine $\varepsilon_1$ by

$$
\varepsilon_1 = \frac{1}{\tilde{C}_5(d + 2)An^2} \begin{cases} 
\varepsilon^{1+7(s+1)!}, & \text{if } s_0 \geq 3, s_0 > s \\
\varepsilon^{1+\frac{7}{5}(s+1)!}, & \text{if } s_0 = s \geq 3,
\varepsilon^{1+\frac{m+6}{5}(s+1)!}, & \text{if } s_0 = 2, s_0 > s, \\
\varepsilon^{1+\frac{\theta_0}{5}(s+1)!}, & \text{if } s_0 = s = 2
\end{cases},
$$

(62)

we have

$$
|H_{3n+3,s+3,A}(x^2) - H_{3n+3,s+3,A}(h_{6,d}(x))| \leq \varepsilon, \quad \forall x \in \mathbb{R}^d.
$$

(63)

Inserting (63) into (60) and setting $\varepsilon = n^{-r-1}$, we get

$$
|f(x) - H_{3n+3,s+3,d,A}(x)| \leq \tilde{C}_2(n\delta_\phi(A) + n^{-r}), \quad \forall x \in \mathbb{B}^d,
$$

where $\tilde{C}_2$ is a constant independent of $n$ or $A$.

**Step 4: Bounding parameters.** Theorem 4 with $\varepsilon = n^{-r-1}$ shows that $|\theta_j^*|, |\theta_{j,i}^*| \leq 1 + 3An + |\theta_0|$, and

$$
|a_j^*|, |a_{j,i}^*| \leq \tilde{C}_4 \begin{cases} 
n^{7(r+1)(s+1)!}, & \text{if } s_0 \geq 3, s_0 > s \\
n^{\frac{7}(s+1)!}, & \text{if } s_0 = s \geq 3,
n^{\frac{m+6(r+1)}{5}(s+1)!}, & \text{if } s_0 = 2, s_0 > s, \\
n^{\frac{\theta_0}{5}(s+1)!}, & \text{if } s_0 = s = 2.
\end{cases}
$$

Furthermore, (59), (56), (54), (62) and $\varepsilon = n^{-r-1}$ shows that $|w_{k,j,i}^*| \leq 1$ and $|a_{k,j,i}^*, |a_{k,j,i}^{**}|$ can be bounded by

$$
\tilde{C}_1 \begin{cases} 
(An^2)^{48}n^{48(r+1)(1+7(s+1)!)} & \text{if } s_0 \geq 3, s_0 > s \\
(An^2)^{48}n^{48(r+1)(1+\frac{7}{5}(s+1)!)}, & \text{if } s_0 = s \geq 3,
(An^2)^{6\theta_0+42+\theta_0}, & \text{if } s_0 = 2, s_0 > s,
(An^2)^{6\theta_0+42+\theta_0}, & \text{if } s_0 = s = 2,
\end{cases}
$$

where $\tilde{C}_1$ is a constant independent of $A$ or $n$. This completes the proof of Theorem 5 for

$$
\theta_{k,j,i}^*, \theta_{k,j,i}^{**}, w_{k,j,i}^* = w_{k,j,i}^{**}, a_{k,j,i}^*, a_{k,j,i}^{**}, \quad \square
$$

To prove Theorem 2 we may apply Theorem 5 as follows.

**Proof of Theorem 2** The lower bound is obvious in view of Theorem 1. To prove the upper bound, we observe that under Assumption 1, a constant $\tilde{C}_6$ depending only on $\phi$ exists such that

$$
\delta_\phi(A) \leq \tilde{C}_6 A^{-1}, \quad \forall A \geq 1.
$$

Set $A = n^{r+1}$. Then Assumption 1 implies Assumption 2 with $s_0 \geq \max\{3, s + 1\}$. Hence, it follows from Theorem 5 that there exists a deep net $H_{3n+3,s+3,d,A}$ with $|w_{k,j,i}^*| \leq 1$, $|\theta_{k,j,i}^*, |\theta_{k,j,i}^{**}, |\theta_{j,i}^*, |\theta_{j,i}^{**} \leq 1 + 3n^{r+2} + |\theta_0|$, and

$$
|a_j^*|, |a_{j,i}^*, |a_{k,j,i}^*, |a_{k,j,i}^{**} \leq \tilde{C}_1 n^{48(3+r)(1+r)(s+1)!/(r+1)}.
$$
such that
\[ \| f - H_{3n+3s+36d,A} \|_{L_\infty(B^d)} \leq \bar{C}_2(n^{-r} + n^{-r}). \]

This completes the proof of Theorem 2 \(^2\) with \( C_3^* = 2\bar{C}_2, \ R = \max\{|\theta_0| + 4, \bar{C}_1\} \) and \( \alpha = 48(3 + r(r + 1) + r(s + 1)!7(r + 1)) \). □

### 4.3 Proof of Theorem 3

To prove Theorem 3, we need the following well-known oracle inequality that was proved in \(^6\).

**Lemma 5** Let \( \rho_X \) be the marginal distribution of \( \rho \) on \( X \) and \( (L^2_{\rho_X}, \| \cdot \|_\rho) \) denote the Hilbert space of square-integrable functions on \( X \) with respect to \( \rho_X \). Set \( E_D(f) := \frac{1}{m} \sum_{i=1}^{m} (f(x_i) - y_i)^2 \), let \( H \) be a collection of continuous functions on \( X \) and define

\[ f_{D,H} = \arg \min_{f \in H} E_D(f). \]  

(64)

Suppose there exist constants \( n', U > 0 \), such that

\[ \log N(\varepsilon, H) \leq n' \log \frac{U}{\varepsilon}, \quad \forall \varepsilon > 0. \]  

(65)

Then for any \( h^* \in H \) and \( \varepsilon > 0 \),

\[ \text{Prob}\{\| \pi_M f_{D,H} - f_{\rho} \|_\rho > \varepsilon + 2\| h^* - f_{\rho} \|_\rho \} \leq \exp \left\{ n' \log \frac{16UM}{\varepsilon} - \frac{3m\varepsilon}{512M^2} \right\}. \]

Now we apply Lemma 5, Lemma 4, and Theorem 2 to prove Theorem 3.

**Proof of Theorem 3** Let \( H = \mathcal{H}^{\text{tree}, \alpha, R}_{3n} \) be the class of deep nets given in Theorem 2. Then, there are totally \( A_3 = \bar{C}_7 n \) free parameters in \( H = \mathcal{H}^{\text{tree}, \alpha, R}_{3n} \). Since \( |y| \leq M \) almost surely, we have \( \| f_{\rho} \|_{L_\infty(B^d)} \leq M \). Then, for \( f_{\rho} \in \text{Lip}^{(\alpha, r, c_0)} \), it follows from Theorem 2 that there exists a \( h \in \mathcal{H}^{\text{tree}, \alpha, R}_{3n} \) such that

\[ \| h - f_{\rho} \|_{L_\infty(B^d)} \leq \bar{C}_8 n^{-r} \]

where \( \bar{C}_7, \bar{C}_8 \) are constants independent of \( n \) and \( \varepsilon \). It follows that

\[ \| h \|_{L_\infty(B^d)} \leq M + \bar{C}_8. \]

By considering \( n' = 2(\log_2 e)\bar{C}_7 n, \ U = \frac{12}{7} R^5 (\bar{C}_7 n)^{5a} \), we see from (42) with \( L = 3, \ A_L = \bar{C}_7 n \) and \( c_1 = 1 \) in Lemma 4 that

\[ \log N(\varepsilon, \mathcal{H}^{\text{tree}, \alpha, R}_{3n}) \leq n' \log \frac{U}{\varepsilon}. \]
Next take $\bar{C}_9 := \max\{6\bar{C}_8^2, 2^{1/2}MR^5(\bar{C}_7)^{5\alpha}\}$ and $C_{10} := \left(\frac{3\bar{C}_9}{2048M^2\bar{C}_7(5\alpha+2r)\log_2 e}\right)^{\frac{1}{2r+1}}$.

Note that
\[2\|h - f_\rho\|^2 \leq 2\|h - f_\rho\|^2_{L_\infty(B^4)} \leq 2\bar{C}_8^2n^{-2r} \leq \bar{C}_9n^{-2r} \log n.
\]

Then by setting $n = \left[\frac{C_{10}m^{\frac{1}{2r+1}}}r\right]$, it follows from Lemma 5 with $h^* = h$ that for
\[\varepsilon \geq \bar{C}_9n^{-2r} \log n \geq 2\|h - f_\rho\|^2_\rho,
\]
we have
\begin{align*}
\text{Prob}\{&\|\pi_M f_{D,n,\phi} - f_\rho\|^2 > 2\varepsilon\} \leq \text{Prob}\{\|\pi_M f_{D,n,\phi} - f_\rho\|^2 > \varepsilon + 2\|h - f_\rho\|^2_\rho\} \\
\leq & \exp\left\{2(\log_2 e)\bar{C}_7n \log \frac{M2^{2r}R^5(\bar{C}_7)^{5\alpha}}{\varepsilon} - \frac{3m\varepsilon}{512M^2}\right\} \\
&+ \exp\left\{-\frac{3m^2}{16(4M + \bar{C}_8)^2(6\bar{C}_8^2n^{-2r} + \varepsilon)}\right\} \\
\leq & \exp\left\{2(\log_2 e)\bar{C}_7(5\alpha + 2r)n \log n - \frac{3m\varepsilon}{512M^2}\right\} + \exp\left\{-\frac{3m\varepsilon}{32(4M + \bar{C}_8)^2}\right\} \\
\leq & \exp\left\{-\frac{3m\varepsilon}{1024M^2}\right\} + \exp\left\{-\frac{3m\varepsilon}{32(4M + \bar{C}_8)^2}\right\} \leq 2\exp\left\{-\frac{3m\varepsilon}{64(4M + \bar{C}_8)^2}\right\} \\
\leq & 3\exp\left\{-\frac{3m\varepsilon^{2r+1}}{2[64(4M + \bar{C}_8)^2 + 3\bar{C}_9(\bar{C}_7)^{2r}]\log(n+1)}\right\}.
\end{align*}

(66)

Then setting
\[3\exp\left\{-\frac{3m\varepsilon^{2r+1}}{2[64(4M + \bar{C}_8)^2 + 3\bar{C}_9(\bar{C}_7)^{2r}]\log(n+1)}\right\} = \delta,
\]
we obtain
\[\varepsilon = \frac{2}{3}[64(4M + \bar{C}_8)^2 + 3\bar{C}_9(\bar{C}_7)^{2r}m^{-2r}]\log(n+1)\log \frac{3}{\delta},\]
which satisfies (66). Thus, it follows from (67) that with confidence at least $1 - \delta$, we have
\[\|\pi_M f_{D,n,\phi} - f_\rho\|^2_\rho \leq C_5^* \delta^{-\frac{2r}{2r+1}}\log(n+1)\log \frac{3}{\delta} \leq C_5^* m^{-\frac{2r}{2r+1}}\log(m+1)\log \frac{3}{\delta},\]
where $C_5^* := \frac{8}{3}[64(4M + \bar{C}_8)^2 + 3\bar{C}_9(\bar{C}_7)^{2r}]$. This proves (10) by noting the well-known relation
\[\mathcal{E}(f) - \mathcal{E}(f_\rho) = \|f - f_\rho\|^2_\rho.
\] (68)

To prove the upper bound of (11), we may apply the formula
\[E[\xi] = \int_{0}^{\infty} \text{Prob}[\xi > t]dt
\] (69)
with \( \xi = \mathcal{E}(\pi_M f_{D,n,\phi}) - \mathcal{E}(f_\rho) \). From (66), (67) and (69), we have

\[
E \{ \mathcal{E}(\pi_M f_{D,n,\phi}) - \mathcal{E}(f_\rho) \} = \int_0^\infty \text{Prob}[\mathcal{E}(\pi_M f_{D,n,\phi}) - \mathcal{E}(f_\rho)] > \varepsilon |d\varepsilon
\]

\[
= \left( \int_{C_0 n^{-2r} \log n} + \int_{C_0 n^{-2r} \log n} \right) \text{Prob}[\mathcal{E}(\pi_M f_{D,n,\phi}) - \mathcal{E}(f_\rho)] > \varepsilon |d\varepsilon
\]

\[
\leq \bar{C}_{g n} n^{-2r} \log n + 3 \int_{C_0 n^{-2r} \log n} \exp \left\{ - \frac{3m 2^r}{2(64(4M + \bar{C}_g)^2 + 3\bar{C}_9(\bar{C}_{10})^{-2r}) \log(n + 1)} \right\} d\varepsilon
\]

\[
\leq \bar{C}_{g n} n^{-2r} \log n + 6(64(4M + \bar{C}_g)^2 + 3\bar{C}_9(\bar{C}_{10})^{-2r}) m^{-\frac{2^r}{2r+1}} \log(n + 1) \int_0^\infty e^{-t} dt
\]

\[
\leq C_7^* m^{-\frac{2^r}{2r+1}} \log(m + 1),
\]

where

\[
C_7^* = 6(64(4M + \bar{C}_g)^2 + 3\bar{C}_9(\bar{C}_{10})^{-2r}) + \bar{C}_9[(\bar{C}_{10})^{-2r} + 1].
\]

Finally, to prove the lower bound of (11), we note that since \( x_1, \ldots, x_m \) are independent random variables, so are \( |x_1|^2, \ldots, |x_m|^2 \). Thus, the data set \( \{ (|x_i|^2, y_i) \}_{i=1}^m \) is independently drawn according to some distribution \( \rho \) defined on \( \mathbb{I} \times [-M, M] \). From [10, Theorem 3.2], there exists some \( \rho_0^* \) with the regression function \( g_\rho \in \text{Lip}_r(\rho_0^*) \), such that the learning rates of all estimates based on \( m \) sample points are not smaller than \( C_7^* m^{-\frac{2^r}{2r+1}} \). Setting \( f_\rho(x) = g_\rho(|x|^2) \), we may conclude that the lower bound of (11) holds. This completes the proof of Theorem 3. \( \square \)

5 Proof of Lemma 3

The proof of Lemma 3 depends on the following two lemmas. They involve the \( \varepsilon \)-packing number of \( V \) defined by

\[
\mathcal{M}(\varepsilon, V) := \max \{ s : \exists f_1, \ldots, f_s \in V, ||f_i - f_j||_{L_\infty(B^d)} \geq \varepsilon, \forall i \neq j \}
\]

The first lemma which can be found in [10, Lemma 9.2]) establishes a trivial relation between \( \mathcal{N}(\varepsilon, V) \) and \( \mathcal{M}(\varepsilon, V) \).

**Lemma 6** For \( \varepsilon > 0 \) and \( V \subseteq L_\infty(B^d) \), we have

\[
\mathcal{M}(2\varepsilon, V) \leq \mathcal{N}(\varepsilon, V) \leq \mathcal{M}(\varepsilon, V).
\]

To state the second lemma, for \( N^* \in \mathbb{N} \), consider the set \( E_{N^*} \) of all vectors \( \varepsilon := (\varepsilon_1, \ldots, \varepsilon_{N^*}) \) for \( \varepsilon_1, \ldots, \varepsilon_{N^*} = \pm 1 \), so that the cardinality \( |E_{N^*}| \) of the set \( E_{N^*} \) is given by

\[
|E_{N^*}| = 2^{N^*}.
\]

(70)

Let \( \tilde{g} \) be a real-valued compactly supported function that vanishes outside \((-1/2, 1/2)\) and satisfies both \( \max_{t \in [-1/2, 1/2]} |\tilde{g}(t)| = c_0/2 \) and \( \tilde{g} \in \text{Lip}_r(c_0 2^{2r-1}) \). Also, partition the
unit interval \( I \) as the union of \( N^* \) pairwise disjoint sub-intervals \( A_j \) of equal length \( 1/N^* \) and centers at \( \{\xi_j\} \) for \( j = 1, \ldots, N^* \). Consider the dilated/scaled functions \( \tilde{g}_j(t) := (N^*)^{-r}\tilde{g}(N^*(t - \xi_j)) \) defined on \( I \). Then based on the set 

\[
\mathcal{G}_E := \left\{ g^*(t) = \sum_{j=1}^{N^*} \epsilon_j \tilde{g}_j(t) : \epsilon = (\epsilon_1, \ldots, \epsilon_{N^*}) \in E^{N^*} \right\}
\]

of univariate functions, we introduce the collection 

\[
\mathcal{F}_E := \{ f(x) = g(|x|^2) : g \in \mathcal{G}_E \}.
\]

of radial functions defined on the \( \mathbb{B}^d \).

**Lemma 7** Let \( N^* \in \mathbb{N} \). Then 

\[
\mathcal{F}_E \subset \text{Lip}^{(s,v,c_0)}.
\]

and in addition, for any \( f \neq f_1 \in \mathcal{F}_E \),

\[
\|f - f_1\|_{L_{\infty}(\mathbb{B}^d)} \geq c_0(N^*)^{-r}.
\]

**Proof.** To prove (73), observe that since 

\[
|N^*(t - \xi_j) - N^*(t - \xi_{j'})| = N^*|\xi_j - \xi_{j'}| \geq 1, \quad \forall \ j \neq j',
\]

it is not possible for both \( N^*(t - \xi_j) \) and \( N^*(t - \xi_{j'}) \) to be in \((-1/2, 1/2)\). Hence, it follows from the support assumption \( \text{supp}\tilde{g} \subset (-1/2, 1/2) \) of \( \tilde{g} \) that for an arbitrary \( t \in I \), there is at most one \( j_0 \in \{1, 2, \ldots, N^*\} \) such that \( (\tilde{g}_{j_0})^{(s)}(t) \neq 0 \). Then the justification of (73) can be argued in two separate cases.

First, for an arbitrary \( g^* \in \mathcal{G}_E \), if \( t, t' \in A_{j_1} \) for some \( j_1 \in \{1, 2, \ldots, N^*\} \), then in view of \( \text{supp}\tilde{g} \subset (-1/2, 1/2) \), \( r = s + v \), \( |\epsilon_j| = 1 \), and \( \tilde{g} \in \text{Lip}^{r, c_02^{1+s}} \), we have 

\[
(\tilde{g})^{(s)}(N^*(t - \xi_j)) = (\tilde{g})^{(s)}(N^*(t' - \xi_j)) = 0, \quad \forall \ j \neq j_1
\]

and 

\[
|g^* - (g^*)^{(s)}(t) - (g^*)^{(s)}(t')| = \left| \sum_{j=1}^{N^*} \epsilon_j [(\tilde{g})^{(s)}(N^*(t - \xi_j)) - (\tilde{g})^{(s)}(N^*(t' - \xi_j))] \right|
\]

\[
\leq (N^*)^{-r+s} \left| \sum_{j=1}^{N^*} \epsilon_j [(\tilde{g})^{(s)}(N^*(t - \xi_j)) - (\tilde{g})^{(s)}(N^*(t' - \xi_j))] \right|
\]

\[
= (N^*)^{-r+s} |\epsilon_{j_1} [(\tilde{g})^{(s)}(N^*(t - \xi_{j_1})) - (\tilde{g})^{(s)}(N^*(t' - \xi_{j_1}))]|
\]

\[
\leq (N^*)^{-r+s} c_02^{1+s}|N^*(t - \xi_{j_1}) - N^*(t' - \xi_{j_1})|^v \leq c_0|t - t'|^v.
\]

Next, if \( t \in A_{j_2} \) and \( t' \in A_{j_3} \) with \( j_2 \neq j_3 \), then 

\[
(\tilde{g})^{(s)}(N^*(t - \xi_j)) = (\tilde{g})^{(s)}(N^*(t - \xi_{j'})) = 0, \quad \forall j \neq j_2, j' \neq j_3.
\]
We may choose the endpoints $\eta_{j_2} \in A_{j_2}$ and $\eta_{j_3} \in A_{j_3}$ so that $\eta_{j_2}$ and $\eta_{j_3}$ are on the segment between $t$ and $t'$. This together with $\text{supp}(\tilde{g}) \subset [-1, 2, 1/2]$ implies that

$$|t - \eta_{j_2}| + |t' - \eta_{j_3}| \leq |t - t'|$$

and

$$(\tilde{g})^{(s)}(N^*(\eta_{j_2} - \xi_{j_2})) = (\tilde{g})^{(s)}(N^*(\eta_{j_3} - \xi_{j_3})) = 0.$$ 

Thus, it follows from $r = s + v$, $|\epsilon_j| = 1$, $\tilde{g} \in Lip(r, c2^{-1+v})$ and Jensen’s inequality, that

$$| (g^*)^{(s)}(t) - (g^*)^{(s)}(t') | \leq \sum_{j=1}^{N^*} | (\tilde{g}^*)^{(s)}(N^*(t - \xi_j)) - (\tilde{g})^{(s)}(N^*(t - \xi_j)) |$$

$$\leq (N^*)^{-r+v} \sum_{j=1}^{N^*} | (\tilde{g})^{(s)}(N^*(t - \xi_j)) | + (N^*)^{-r+v} | (\tilde{g})^{(s)}(N^*(t' - \xi_j)) |$$

$$= (N^*)^{-r+v} | (\tilde{g})^{(s)}(N^*(t - \xi_j)) - (\tilde{g})^{(s)}(N^*(\eta_{j_2} - \xi_{j_2})) |$$

$$+ (N^*)^{-r+v} | (\tilde{g})^{(s)}(N^*(t' - \xi_j)) - (\tilde{g})^{(s)}(N^*(\eta_{j_3} - \xi_{j_3})) |$$

$$\leq c_0 2^{v-1} \left( |t - \eta_{j_2}| + |t' - \eta_{j_3}| \right) = c_0 2^{v} \left( \frac{|t - \eta_{j_2}| + |t' - \eta_{j_3}|}{2} \right) = c_0 |t - t'|^v.$$

From the above arguments, we know that (73) holds in view of (72).

Finally, to prove (74), let $f, f_1 \in \mathcal{F}_E$ be two different functions. Then there exist $\epsilon, \epsilon' \in E^{N^*}$ with $\epsilon \neq \epsilon'$ such that

$$f(x) - f_1(x) = \sum_{j=1}^{N^*} \epsilon_j \tilde{g}_j(|x|^2) - \sum_{j=1}^{N^*} \epsilon'_j \tilde{g}_j(|x|^2) = (N^*)^{-r} \sum_{j=1}^{N^*} (\epsilon_j - \epsilon'_j) \tilde{g}(N^*|x|^2 - \xi_j)).$$

Therefore, we have

$$\|f - f_1\|_{L_\infty(B^d)} = (N^*)^{-r} \max_{x \in B^d} \left| \sum_{j=1}^{N^*} (\epsilon_j - \epsilon'_j) \tilde{g}(N^*|x|^2 - \xi_j)) \right|$$

$$= (N^*)^{-r} \max_{t \in \mathbb{R}} \left| \sum_{j=1}^{N^*} (\epsilon_j - \epsilon'_j) \tilde{g}(N^*(t - \xi_j)) \right|$$

$$= (N^*)^{-r} \max_{j' = 1, 2, \ldots, N^*} \max_{A_{j'}} \left| \sum_{j=1}^{N^*} (\epsilon_j - \epsilon'_j) \tilde{g}(N^*(t - \xi_j)) \right|$$

$$= (N^*)^{-r} \max_{j' = 1, 2, \ldots, N^*} \left\{ \max_{\epsilon_j - \epsilon'_j \neq 2, \epsilon_j - \epsilon'_j \neq -2} \left| 2 \tilde{g}(N^*(t - \xi_{j'})) \right|, \max_{\epsilon_j - \epsilon'_j \neq -2} \left| -2 \tilde{g}(N^*(t - \xi_{j'})) \right| \right\}.$$
Noting that \( \{ t = N^\ast (\tau - \zeta_j) : \tau \in A_j \} = [-1/2, 1/2] \) for each \( j \in \{1, \ldots, N^\ast \} \) and \( \max_{t \in [-1/2,1/2]} |\tilde{g}(t)| = c_0/2 \), we obtain
\[
\| f - f_1 \|_{L^\infty(\mathbb{R}^d)} = 2(N^\ast)^{-r} \max_{t \in [-1/2,1/2]} |\tilde{g}(t)| = c_0(N^\ast)^{-r}.
\]
Thus, (74) holds. This completes the proof of Lemma 7. \( \square \)

We now return to the proof of Lemma 3.

**Proof of Lemma 3.** Let \( \nu > 0 \) to be determined later, and denote
\[
\delta := \delta_\nu := \text{dist}(\mathcal{F}_E, V, L^\infty(\mathbb{R}^d)) + \nu.
\]
For every \( f \in \mathcal{F}_E \), choose a function \( Pf \in V \), so that
\[
\| f - Pf \|_{L^\infty(\mathbb{R}^d)} \leq \delta.
\]
Observe that \( Pf \) is not necessarily unique. Define \( \mathcal{S}_E := \{ Pf : f \in \mathcal{F}_E \} \subseteq V \). Then for \( f^* = Pf \) and \( f_1^* = Pf_1 \) with \( f \neq f_1 \in \mathcal{F}_E \), we have
\[
\| f^* - f_1^* \|_{L^\infty(\mathbb{R}^d)} = \| Pf - Pf_1 \|_{L^\infty(\mathbb{R}^d)} \geq \| f - f_1 \|_{L^\infty(\mathbb{R}^d)} - \| Pf - f \|_{L^\infty(\mathbb{R}^d)} - \| Pf_1 - f_1 \|_{L^\infty(\mathbb{R}^d)}.
\]
which together with (74) implies
\[
\| f^* - f_1^* \|_{L^\infty(\mathbb{R}^d)} \geq c_0(N^\ast)^{-r} - 2\delta.
\]
We claim that \( \delta > \frac{c_0}{4} (N^\ast)^{-r} \), where \( N^\ast \) is given by
\[
N^\ast = \left[ (\beta + 2r + 4)N \log_2(2C_1' + 4C_2'(\beta + 2r + 4)^r/c_0 + N) \right].
\]
To prove the claim, suppose to the contrary that
\[
\delta \leq \frac{c_0}{4} (N^\ast)^{-r}.
\]
Then (77) implies
\[
\| f^* - f_1^* \|_{L^\infty(\mathbb{R}^d)} \geq \frac{c_0}{2} (N^\ast)^{-r}.
\]
That is, \( Pf \neq Pf_1 \) is consequence of \( f \neq f_1 \), so that in view of (70),
\[
|\mathcal{S}_E| = |\mathcal{F}_E| = |E^{N^\ast}| = 2^{N^\ast}.
\]
Consider \( \varepsilon_0 = \frac{c_0}{2} (N^\ast)^{-r} \). Then we obtain
\[
\mathcal{M}(\varepsilon_0, V) \geq 2^{N^\ast}.
\]
On the other hand, since \( \mathcal{S}_E \subseteq V \), it follows from (40) and Lemma 6 that
\[
\mathcal{M}(\varepsilon_0, V) \leq \mathcal{N}(\varepsilon_0/2, V) \leq C_1' \left( \frac{2C_2'N\beta}{\varepsilon_0} \right)^N = C_1' \left( 4C_2'N\beta(N^\ast)^r/c_0 \right)^N.
\]
Combining the above two inequalities, we have

$$2^{N^*} \leq C'_1 \left(4C'_2 N^\beta (N^*)^r / c_0 \right)^N. \quad (80)$$

The choice of $N^*$ in (78) tells us that (80) holds, but it implies that

$$N^* \geq \frac{c_0}{4} \left[ (\beta + 2r + 4) N \log_2 (2C'_1 + 4C'_2 (\beta + 2r + 4)^r / c_0 + N) \right]^{-r}.$$

In view of (73), we have

$$\text{dist} \left( \text{Lip} \left( D_{\delta,\alpha,\mu}, c_0 \right), V, L_\infty (B^d) \right) \geq \frac{\delta}{2} > \frac{c_0}{8} \left[ (\beta + 2r + 4) N \log_2 (2C'_1 + 4C'_2 (\beta + 2r + 4)^r / c_0 + N) \right]^{-r}.$$

with $C'_3 = \frac{c_0}{8} (\beta + 2r + 4)^{-r}$ and $C'_4 = 2C'_1 + 4C'_2 c_0^{-1} (\beta + 2r + 4)^r$. This completes the proof of Lemma 3.

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