Autoresonant excitation of space-time quasicrystals in plasma

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We demonstrate theoretically and numerically that a warm fluid model of a plasma supports space-time quasicrystalline structures. These structures are highly nonlinear, two-phase, ion acoustic waves that are excited autoresonantly when the plasma is driven by two small amplitude chirped-frequency ponderomotive drives. The waves exhibit density excursions that substantially exceed the equilibrium plasma density. Remarkably, these extremely nonlinear waves persist even when the small amplitude drives are turned off. We derive the weakly nonlinear analytical theory by applying Whitham’s averaged variational principle to the Lagrangian formulation of the fluid equations. The resulting system of coupled weakly nonlinear equations is shown to be in good agreement with fully nonlinear simulations of the warm fluid model. The analytical conditions and thresholds required for autoresonant excitation to occur are derived and compared to simulations. The weakly nonlinear theory guides and informs numerical study of how the two-phase quasicrystalline structure “melts” into a single phase traveling wave when one drive is below a threshold. These nonlinear structures may have applications to plasma photonics for extremely intense laser pulses, which are limited by the smallness of density perturbations of linear waves.

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I. INTRODUCTION

Photonic crystals [1–4] built from conventional materials are routinely employed to focus, polarize, and manipulate light pulses. A periodic array of alternating dielectrics and plasmas called plasma photonic crystals (PPCss) has been the subject of much interest [5–19] owing to its optical properties. Besides crystals, Levine and Steinhardt [20] introduced quasicrystals—materials with properties that are ordered in space but do not possess an exact periodicity. Photonic quasicrystals have been studied extensively [21–28]. Moreover, the optical properties of photonic time crystals with a refractive index varying periodically in time have been investigated in Refs. [29–36]. The optical properties of the structures possessing periodicity both in space and time have been studied in Refs. [36–43].

Plasma photonic crystals have a major drawback where the plasmas are contained within solid material: They break down at high field intensity and are, therefore, incapable of controlling the laser pulses that are essential for many high energy density science applications. Purely plasma based structures, on the other hand, can withstand high intensity pulses. Many concepts for plasma-based optical elements have been proposed and built [44]. Plasma channels [45] routinely focus lasers for particle acceleration experiments. Over two decades ago, it was realized that resonant interactions [46] could be used for compression of intense pulses (replacing large compressor gratings). Plasma mirrors [47–50] are routinely used [51,52] at the National Ignition Facility (NIF) to improve performance in inertial fusion experiments. Laser-sculpted plasma grating structures [53,54] as well as polarization control using plasma structures [55–58] have been investigated. A significant challenge of plasma gratings is that their efficacy depends on the maximum variation in the index of refraction that can be achieved at the required spatial scale. Plasma density is well below critical density, and the density modulation should be as large as possible. This naturally leads to an exploration of nonlinear waves.

In this paper, we propose formation and control of space-time quasicrystalline structures in plasma through excitation of strongly nonlinear large amplitude multiphase ion acoustic waves that modulate plasma density in the desired way. It is known that a linear standing wave of the form \( U(x,t) \propto \cos(kx) \cos(\omega t) \), which is periodic in both time and space, is formed by superposing two linear traveling waves of the same frequency \( \omega \), but propagating in the opposite direction. Nonlinearity of the media in some cases allows a generalization of linear standing waves to a waveform \( U(x,t) = F(kx - \omega t, kx + \omega t) \), where \( F \) is a \( 2\pi \)-periodic nonlinear function of two phase variables and is also periodic in time and space. Recently, it was demonstrated that such nonlinear structures could be formed in plasma in the form of electron plasma [59] and ion acoustic [60] waves. It is also known that even more complex multiphase constructs of the form \( U(x,t) = F(\theta_1, \theta_2, \ldots, \theta_N) \), where each phase is \( \theta_i = k_i x - \omega_i t \), exist in other physical systems described by integrable nonlinear wave equations, such as the Korteweg-de Vries (KdV), nonlinear...
Schrödinger (NLS), and sine-Gordon (SG) equations [61]. Generally, multiphase functions \( F \) are very nontrivial and can be described by a complex analysis based on the inverse scattering transform (see, for example, Ref. [62] for the KdV case). The multiphase waves are \( 2\pi \) periodic in each of the phase variables, but if at least two of \( k_i \) or \( \omega \) are not commensurate, function \( F \) is not exactly periodic in time and/or space and, thus, comprise a family of nontrivial space-time quasicrystals. But how can one excite such a multiphase wave in a given physical system? Because of the complexity of the wavefront, a direct realization of a multiphase wave requires setting up precise initial conditions, making it an impractical, if not impossible, strategy for experiments even in the case of just two phases \( \theta_1, \theta_2 \). A possible way to circumvent the experimental difficulty of setting up the precise initial conditions is exploiting phase locking with small amplitude chirped-frequency traveling waves. In the past this approach was used in exciting multiphase solutions for integrable systems: KdV [63], NLS [64], SG [65], and the periodic Toda lattice [66]. The autoresonant excitation was also demonstrated for single phase large amplitude ion acoustic waves [67,68]. This suggests that perhaps the autoresonance could be used in a more general way to excite multiphase solutions for ion acoustic waves.

Here, we demonstrate, using a warm fluid plasma model, that a two-phase, strongly nonlinear ion acoustic wave can be generated and controlled. The wave is created by starting from zero and autoresonantly driving the system with two small amplitude chirped-frequency ponderomotive traveling waves. We show that slow passage of the driving waves through resonances in the plasma results in the continuing autoresonant (phase locked with both drives) excitation of the wave. The system sustains this double autoresonance as the driving frequencies vary in time by increasing the amplitude of the excited wavefront, creating an extremely large amplitude space-time quasicrystal in plasma. This result is surprising and suggests some degree of integrability in the problem. We conjecture that this integrability is related to the fact that in the limit of small amplitude, ion acoustic waves are reduced to the KdV-type equation [69]. Since there exist many continuous physical systems approximated by the KdV, NLS, and SG equations, we expect that autoresonant space-time quasicrystals can be formed similarly in all these systems.

The paper is organized as follows. In Sec. II, we formulate the problem within a warm fluid plasma model and present a fully nonlinear numerical solution. In Sec. III, by using the Lagrangian formulation of the fluid equations and applying Whitham’s averaged variational principle [70], we derive an analytical weakly nonlinear theory and demonstrate that it agrees well with the fully nonlinear simulations. In Sec. IV, we use our weakly nonlinear theory to study how to choose the parameters required to excite a two-phase autoresonant solution as well as discuss its threshold nature. Finally, in Sec. V, we summarize and discuss our results.

II. FORMULATION OF THE PROBLEM AND THE NUMERICAL RESULTS

We start with a warm fluid model of ion acoustic waves in plasma described by the following system of continuity, momentum, and Poisson’s equations:

\[
\begin{align*}
\frac{\partial n_i}{\partial t} + n_i \frac{\partial u_i}{\partial x} &= 0, \\
\frac{\partial u_i}{\partial t} + n_i \frac{\partial u_i u_x}{\partial x} &= -\frac{\partial \phi_x}{\partial x} - D_n \frac{\partial^2 n_i}{\partial x^2}, \\
\frac{\partial \phi_x}{\partial t} &= e^{\sigma_x u_x} - n.
\end{align*}
\]

Here \( n \) is the ion density, \( u \) is the ion fluid velocity, \( D_n = 3u_{th}^2 \) where \( u_{th} \) is the ion thermal velocity, \( \phi \) is the electric potential, and \( \sigma_x \) is the driving potential. All variables and parameters are dimensionless, such that the time is measured in terms of the inverse plasma Debye frequency \( \omega_p^{-1} = \sqrt{m_i/m_e} \omega_p^{-1} \), the distance in terms of the Debye length \( \lambda_d = u_t/\omega_p \), and, consequently, the velocities are measured in terms of the modified electron thermal velocity \( \sqrt{m_e/m_i} u_e \).

The plasma density and the electric potential are normalized with respect to the unperturbed plasma density and \( k_B T_e/e \), respectively. The driving potential consists of two small amplitudes \( (\varepsilon_1, \varepsilon_2) \) traveling waves and has the following form:

\[
\phi_d = \varepsilon_1 \cos(\theta_{d,1}) + \varepsilon_2 \cos(\theta_{d,2}),
\]

where the traveling wave drives have driving phases \( \theta_{d,i} = k_i x - \int \omega_{d,i}(t) dt \) with slowly varying driving frequencies \( \omega_{d,i}(t) = -d\theta_{d,i}/dt \) \( (i = 1, 2) \).

We can solve the system of the nonlinear equations (1)–(3) numerically using the water bag model method similar to the procedure described in Refs. [60,68].

To be specific, let us consider two driving counter propagating traveling waves with \( k_1 = -0.5 \) and \( k_2 = 1 \). We use linearly chirped driving frequencies for \( t \leq 0 \) and arctan drive for \( t > 0 \) \( (i = 1, 2) \):

\[
\omega_{d,i} = \begin{cases} \omega_{a,i} + \alpha t, & t \leq 0, \\ \omega_{a,i} + \alpha t \arctan \left( \frac{t}{T_i} \right), & t > 0. \end{cases}
\]

Here, \( \omega_{a,i}(k_i) \) \( (i = 1, 2) \) are the frequencies given by the linear ion acoustic wave dispersion relation:

\[
\omega_{a,i}(k_i) = |k_i| \sqrt{\frac{1}{1 + k_i^2} + \Delta^2},
\]

and we use equal chirp rates \( \alpha_1 = \alpha_2 = 2.5 \times 10^{-5} \) for \( t \leq 0 \) and \( T_i = 2\Delta \omega_i / \alpha_i \) \( (i = 1, 2) \), \( \Delta \omega_1 = 0.07 \) for \( t > 0 \). We also slowly build up the driving amplitudes as \( \varepsilon_i = \varepsilon_i[0.5 + \arctan(t/T_i)/\pi], \varepsilon_i = 16\varepsilon_i^{3/4} \) \( (i = 1, 2) \) to have a smoother entrance into the autoresonant regime. The ion thermal velocity is chosen as \( u_{th} = 0.003 \).

The results of the numerical simulations are presented in Fig. 1. Figure 1(a) shows a colormap of the electron density \( n_e(x, t) \) approximated by \( e^{\theta(x, t)} \) as a function of \( x \) and \( t \), where we introduced a slow time variable \( \tau = \sqrt{\alpha \Omega t} \). We can clearly see in Fig. 1(a) a crystal-like quasi-periodic spatiotemporal structure representing a large amplitude \( (\delta n_e/n_e \sim 1) \) two-phase strongly nonlinear ion acoustic wave excited by the two driving counter propagating traveling waves. Figures 1(b) and 1(c) show a colormap of \( n_e(x, t) \approx e^{\theta(x, t)} \) but when driven by just one of the driving components with \( k_1 = -0.5 \) and \( k_2 = 1 \), respectively. We can see that an excitation of a
FIG. 1. The colormap of the electron density $n_e(x, \tau)$ as a function of slow time $\tau = \sqrt{\alpha_1 t}$ and coordinate $x$. (a) Two-phase autoresonant ion acoustic wave excited by two driving counter propagating traveling waves with $k_1 = -0.5$ and $k_2 = 1$ obtained by solving the fully nonlinear equations (1)–(3). (b) Autoresonant single phase ion acoustic wave driven by the first driving component in (a) with $k_1 = -0.5$. (c) Autoresonant single phase ion acoustic wave driven by the second driving component in (a) with $k_2 = 1$. The red-vertical line indicates the termination of the drive at $\tau = 12$.

A single phase large amplitude ion acoustic wave creates traveling wave-type spatiotemporal photonic plasma structures. In these single phase solutions the phases remain constant along the characteristic directions given by the phase velocity of the driving waves. The same two characteristic directions can also be seen in the two-phase wave solution in Fig. 1(a). We start our simulations at $\tau = -7$ and stop the driving at $\tau = 12$ (which is indicated by the red vertical line in Fig. 1). At $\tau = 0$ both driving waves pass the linear resonances and then the system enters the autoresonant regime and its excitation amplitude increases to preserve the resonances with the drives. This can be seen in Fig. 2, which shows the maximum value over $x$ of the ion fluid velocity $u(x, \tau)$ versus slow time $\tau = \sqrt{\alpha_1 t}$. Note that the crystal-like structure is preserved in time after we turn off the drive at $\tau = 12$, suggesting formation of some fundamental mode of the system.

The limiting factor as to what amplitudes we can excite the ion acoustic waves is determined by the kinetic wave breaking [60,68,71,72]. For the cold plasma this occurs when the ion fluid velocity exceeds the absolute value of the phase velocity of at least one of the driving waves. As we can see in Fig. 2, the maximum amplitude of the ion fluid velocity $u$ stays below the absolute value of the phase velocities of the driving waves; we thereby avoid the wave-breaking limit for the parameters chosen in our example.

In the next section, we are going to cast the problem into the Lagrangian form and develop an adiabatic, weakly nonlinear theory using Whitham’s averaged variational principle...
employ to excite multiphase waves suggest that it should be possible to use Whitham’s averaged variational principle [70] to derive weakly nonlinear analytical results for our problem.

We proceed by writing the following ansatz describing the two-phase $\theta_1 = k_1 x - \int \omega_1(t) \, dt$, $\theta_2 = k_2 x - \int \omega_2(t) \, dt$ solutions for the potentials $\sigma, \psi, \varphi$:

\[
\begin{align*}
\sigma &= \tilde{A}_{10} \sin(\theta_1) + \tilde{A}_{01} \sin(\theta_2) \\
&\quad + \tilde{A}_{11} \sin(\theta_1 + \theta_2) + \tilde{A}_{1,-1} \sin(\theta_1 - \theta_2) \\
&\quad + \tilde{A}_{20} \sin(2\theta_1) + \tilde{A}_{02} \sin(2\theta_2), \\
\psi &= \tilde{B}_{10} \sin(\theta_1) + \tilde{B}_{01} \sin(\theta_2) \\
&\quad + \tilde{B}_{11} \sin(\theta_1 + \theta_2) + \tilde{B}_{1,-1} \sin(\theta_1 - \theta_2) \\
&\quad + \tilde{B}_{20} \sin(2\theta_1) + \tilde{B}_{02} \sin(2\theta_2), \\
\varphi &= \tilde{C}_{00} + \tilde{C}_{10} \cos(\theta_1) + \tilde{C}_{01} \cos(\theta_2) \\
&\quad + \tilde{C}_{11} \cos(\theta_1 + \theta_2) + \tilde{C}_{1,-1} \cos(\theta_1 - \theta_2) \\
&\quad + \tilde{C}_{20} \cos(2\theta_1) + \tilde{C}_{02} \cos(2\theta_2).
\end{align*}
\]

Here, we view the amplitudes $\tilde{A}_{10}, \tilde{A}_{01}, \tilde{B}_{10}, \tilde{B}_{01}, \tilde{C}_{10}, \tilde{C}_{01}$ as the first-order coefficients, while the amplitudes $\tilde{A}_{20}, \tilde{A}_{02}, \tilde{B}_{20}, \tilde{B}_{02}, \tilde{C}_{20}, \tilde{C}_{11}, \tilde{C}_{1,-1}, \tilde{B}_{11}, \tilde{B}_{1,-1}, \tilde{C}_{11}, \tilde{C}_{1,-1}$, and $\tilde{C}_{00}$ as the second-order coefficients. It is also convenient to write the driving potential $\psi_d$ in the form with explicit phase mismatches $\Phi_1 = \theta_1 - \theta_2$ (1, 2) between phases of the solutions $\theta_1, \theta_2$ and the driving phases $\theta_{1,1}, \theta_{2,2}$:

\[
\psi_d = \varepsilon_1 \cos(\theta_1 - \Phi_1) + \varepsilon_2 \cos(\theta_2 - \Phi_2).
\]

Furthermore, here and in the following it is assumed that the phases $\theta_1, \theta_2$ are varying rapidly, while all the coefficients in our ansatz and $\Phi_1, \Phi_2$ are slow functions of time.

In the linear case without phase mismatches we have the following solutions:

\[
\begin{align*}
\sigma &= \tilde{A}_{10} \sin(\theta_1) + \tilde{A}_{01} \sin(\theta_2), \\
\psi &= \tilde{B}_{10} \sin(\theta_1) + \tilde{B}_{01} \sin(\theta_2), \\
\varphi &= \tilde{C}_{00} \cos(\theta_1) + \tilde{C}_{01} \cos(\theta_2),
\end{align*}
\]

where the amplitudes $C_{10}$ and $C_{01}$ satisfy

\[
\begin{align*}
C_{10} \left( \frac{k_1^2}{\omega_1^2 - \Delta^2 k_1^2} - 1 - k_1^2 \right) &= \varepsilon_1, \\
C_{01} \left( \frac{k_2^2}{\omega_2^2 - \Delta^2 k_2^2} - 1 - k_2^2 \right) &= \varepsilon_2,
\end{align*}
\]

and the amplitudes $\tilde{A}_{10}, \tilde{A}_{01}, \tilde{B}_{10}, \tilde{B}_{01}$ are expressed through $C_{10}$ and $C_{01}$ as follows:

\[
\begin{align*}
\tilde{A}_{10} &= \frac{k_1}{\omega_1^2 - \Delta^2 k_1^2} C_{10}, \\
\tilde{A}_{01} &= \frac{k_2}{\omega_2^2 - \Delta^2 k_2^2} C_{01}, \\
\tilde{B}_{10} &= \frac{\omega_1}{\omega_1^2 - \Delta^2 k_1^2} C_{10}, \\
\tilde{B}_{01} &= \frac{\omega_2}{\omega_2^2 - \Delta^2 k_2^2} C_{01}.
\end{align*}
\]
The next crucial step is to find the averaged Lagrangian density over the rapidly varying phases \( \theta_1, \theta_2 \):
\[
L = (L(\theta_1, \theta_2, t))_{\theta_1, \theta_2} = \int L(\theta_1, \theta_2, t) \frac{d\theta_1}{2\pi} \frac{d\theta_2}{2\pi},
\]
(24)
which will depend only on slow variables: the amplitudes of various harmonics and the phase mismatches.

After long but straightforward calculations one can obtain the average of Eq. (10) over the rapidly varying phases. This derivation of the averaged Lagrangian can be found in Appendix A.

Weakly nonlinear equations

Now, having obtained the averaged Lagrangian, we can derive the weakly nonlinear equations that describe the evolution of the wave amplitude by applying Whitham’s variational procedure [70].

First, we take variations with respect to the phases:
\[
\frac{d}{dt} \left( \frac{\partial L}{\partial \theta_1} \right) - \frac{\partial L}{\partial \Phi_1} = 0,
\]
(25)
\[
\frac{d}{dt} \left( \frac{\partial L}{\partial \theta_2} \right) - \frac{\partial L}{\partial \Phi_2} = 0.
\]
(26)

Keeping the lowest significant order terms and using the linear relations (20)–(23), we get
\[
\frac{d}{dt} \left( \frac{\omega_0 k_1^2}{(\omega_0^2 - \Delta^2 k_1^2)^2} C_{10} \right) = \epsilon_1 C_{10} \cos (\Phi_1),
\]
(27)
\[
\frac{d}{dt} \left( \frac{\omega_0 k_2^2}{(\omega_0^2 - \Delta^2 k_2^2)^2} C_{01} \right) = \epsilon_2 C_{01} \cos (\Phi_2).
\]
(28)

Likewise, we can obtain from the variations with respect to the first-order amplitudes [see Eqs. (B42)–(B47) in Appendix B]:
\[
\left( \frac{k_1^2}{(\omega_0^2 - \Delta^2 k_1^2)} - 1 \right) C_{10}
\]
\[
= C_{10} P(k_1, \omega_1) C_{10} + C_{01} C_{10} Q(k_1, \omega_1; k_2, \omega_2) C_{01} + \epsilon_1 \cos (\Phi_1),
\]
(29)
\[
\left( \frac{k_2^2}{(\omega_0^2 - \Delta^2 k_2^2)} - 1 \right) C_{01}
\]
\[
= C_{01} P(k_2, \omega_2) C_{01} + C_{01} C_{10} Q(k_1, \omega_1; k_2, \omega_2) C_{10} + \epsilon_2 \cos (\Phi_2),
\]
(30)

where the functions \( P(k_1, \omega_1) \) and \( Q(k_1, \omega_1; k_2, \omega_2) \) are defined in Appendix C.

Expanding around the linear ion acoustic dispersion relation \( \omega_1 = \omega_{1,i} + \Delta \omega_1 \) (\( i = 1, 2 \)), we get from Eqs. (29) and (30) the following expressions:
\[
\Delta \omega_1 = -\frac{(\omega_0^2 - \Delta^2 k_1^2)^2}{2\omega_0 k_1^4} P(k_1, \omega_1) C_{10}^2
\]
\[
= -\frac{(\omega_0^2 - \Delta^2 k_2^2)^2}{2\omega_0 k_2^4} Q(k_1, \omega_1; k_2, \omega_2) C_{01}^2,
\]
(31)
\[
\Delta \omega_2 = -\frac{(\omega_0^2 - \Delta^2 k_2^2)^2}{2\omega_0 k_2^4} P(k_2, \omega_2) C_{21}^2
\]
\[
= -\frac{(\omega_0^2 - \Delta^2 k_1^2)^2}{2\omega_0 k_1^4} Q(k_1, \omega_1; k_2, \omega_2) C_{10}^2.
\]
(32)

The above expressions (31) and (32) show that due to the nonlinear nature of the system, the waves acquire frequency shifts (the first two terms), which can be adjusted to the chirped driving frequencies continuously (see the last term), yielding control of the wave amplitudes.

Assuming linear driving frequency chirps \( \omega_{d,i} = \omega_{a,i} + \alpha_i t \) \((i = 1, 2)\) and defining
\[
I_1 = \frac{2\omega_0 k_1^2}{(\omega_0^2 - \Delta^2 k_1^2)^2} C_{10}^2,
\]
(33)
\[
I_2 = \frac{2\omega_0 k_2^2}{(\omega_0^2 - \Delta^2 k_2^2)^2} C_{01}^2,
\]
(34)
\[
a = \frac{(\omega_0^2 - \Delta^2 k_1^2)^4}{4\omega_0^4 k_1^4} P(k_1, \omega_1),
\]
(35)
\[
b = \frac{(\omega_0^2 - \Delta^2 k_2^2)^4}{4\omega_0^4 k_2^4} P(k_2, \omega_2),
\]
(36)
\[
c = \frac{(\omega_0^2 - \Delta^2 k_2^2)^4}{4\omega_0^4 k_2^4} Q(k_1, \omega_1; k_2, \omega_2),
\]
(37)
\[\epsilon_1 = 2\frac{(\omega_0^2 - \Delta^2 k_1^2)}{|k_1|} \epsilon_1, \quad \epsilon_2 = 2\frac{(\omega_0^2 - \Delta^2 k_2^2)}{|k_2|} \epsilon_2,\]

we can rewrite Eqs. (27), (28), (31), and (32) to obtain the following system of weakly nonlinear evolution equations:
\[
\frac{dI_1}{dt} = \epsilon_1 \sqrt{I_1} \sin (\Phi_1),
\]
(38)
\[
\frac{dI_2}{dt} = \epsilon_2 \sqrt{I_2} \sin (\Phi_2),
\]
(39)
\[
\frac{d\Phi_1}{dt} = a I_1 + b I_2 + \alpha_1 t + \epsilon_1 \sqrt{2\omega_0 I_1} \cos (\Phi_1),
\]
(40)
\[
\frac{d\Phi_2}{dt} = b I_1 + c I_2 + \alpha_2 t + \epsilon_2 \sqrt{2\omega_0 I_2} \cos (\Phi_2).\]
(41)

Here, in principle, the linear frequency chirps \( \alpha_i t \) \((i = 1, 2)\) can be replaced by any other functions of time as long as these functions are sufficiently slow. In fact, we use the arctan frequency chirp drive defined in Eq. (5) in our simulations.

The numerical solution of the weakly nonlinear system (38)–(41) is presented in Figs. 2–4. We use the drive and other parameters identical to those used in the numerical solution of the fully nonlinear problem described in the previous section, which is presented in Figs. 1(a) and 2. As can be seen in Fig. 2 and by comparison between Figs. 1(a) and 3, the analytically derived weakly nonlinear system is indeed a good approximation of the fully nonlinear problem. We further observe in Fig. 2 the absence of the low frequency modulation in the weakly nonlinear solution after we stop driving at \( r = 12 \).
FIG. 3. The colormap of the electron density \( n_e(x, \tau) \) as a function of slow time \( \tau = \sqrt{\alpha_1} t \) and coordinate \( x \) for a two-phase autoresonant ion acoustic wave excited by two driving counter propagating traveling waves with \( k_1 = -0.5 \) and \( k_2 = 1 \) obtained by solving the weakly nonlinear reduced dynamical equations (38)–(41). The red-vertical line indicates the termination of the drive at \( \tau = 12 \). The parameters used in the simulation are the same as in Figs. 1(a), 2, and 4.

The reason is that in this case \( I_1, I_2 = \text{const} \), as evident from Eqs. (38)–(39), which implies that all the slowly evolving amplitudes are constant as well, while Eqs. (11)–(13) show that it is the slowly evolving amplitudes that are directly responsible for the low frequency modulation.

The nature of the autoresonant excitation and phase locking is demonstrated in Fig. 4, which shows the effective actions \( I_1, I_2 \) (top subplot) and the phase mismatches \( \Phi_1, \Phi_2 \) (bottom subplot) as functions of slow time \( \tau = \sqrt{\alpha_1} t \). We can clearly see that as the system passes the linear resonance at \( \tau = 0 \), the phase mismatches are locked around zero, while the effective actions \( I_1, I_2 \) both enter the autoresonant regime and grow in amplitude. At \( \tau = 12 \) we turn off the drives and so the effective actions remain constant. In the absence of the drives, the phase mismatches are not meaningfully defined, therefore \( \Phi_1, \Phi_2 \) are shown in the figures only until \( \tau = 12 \).

We can explicitly test whether our assumption regarding the form of the ansatz used [see Eqs. (11)–(13)] is justified by performing the spectral analysis. Figure 5 shows the spectral distribution of the harmonics of the ion fluid velocity \( u(x, \tau) \) in \( k \) space at two moments of time: \( \tau = 3 \) (pink line) and \( \tau = 12 \) (blue line), both in linear scale (top subplot) and in logarithmic scale (bottom subplot). We can see that the spectrum falls off dramatically with the increase in \( |k| \); only a handful of harmonics have a noticeable weight and can be considered excited. At \( \tau = 3 \) the excited harmonics correspond to the ones used in the ansatz, so we see a very good agreement between the weakly nonlinear and the fully nonlinear solutions, as evident in Fig. 2. At \( \tau = 12 \) we can see that harmonics with \( |k| = 2 \) and \( |k| = 2.5 \), which are beyond the ones used in the ansatz, acquire some small but not non-negligible weights, so the agreement between the weakly nonlinear theory utilizing the ansatz given by Eqs. (11)–(13) and the fully nonlinear theory is not as good as at \( \tau = 3 \), though it is still decent. Thus, by checking the spectrum of the solutions, one can verify whether the ansatz is adequate for the parameters used in the simulations, and if necessary the ansatz can be extended to include more harmonics and more precise weakly analytical theory can be developed.

FIG. 4. The effective actions \( I_1, I_2 \) (top subplot) and the phase mismatches \( \Phi_1, \Phi_2 \) (bottom subplot) vs slow time \( \tau = \sqrt{\alpha_1} t \) obtained by solving the weakly nonlinear reduced dynamical equations (38)–(41). The parameters used in the simulation are the same as in Figs. 1(a), 2, and 3.
by the following Hamiltonian for the effective action (1)–(3) at \( \tau = 3 \) (pink line) and \( \tau = 12 \) (blue line) in linear (top subplot) and logarithmic (bottom subplot) scales. The parameters used in the simulations are the same as in Figs. 1(a), 2, 3, and 4.

**IV. THE CONDITIONS FOR DOUBLE AUTORESONANCE**

Equations (38)–(41) have the same form as a weakly nonlinear system studied in Ref. [73]. Such a system is described by the following Hamiltonian for the effective action \( (I_1, I_2) \) and angle \((\Phi_1, \Phi_2)\) variables:

\[
H = \omega_1 I_1 + \omega_2 I_2 + \frac{1}{2} a I_1^2 + b I_1 I_2 + \frac{1}{2} c I_2^2 + f(I_1, I_2, \Phi_1, \Phi_2, t),
\]

where

\[
f(I_1, I_2, \Phi_1, \Phi_2, t) = \epsilon_1 \sqrt{\frac{I_1}{2\omega_1}} \cos (\Phi_1) + \epsilon_2 \sqrt{\frac{I_2}{2\omega_2}} \cos (\Phi_2).
\]

As shown in Ref. [73], the possibility of double autoresonance is determined by the signs of \( D = ac - b^2 \) and \( \alpha_1 \alpha_2 \): for the double autoresonance to occur, they must have the same sign. From Eqs. (38)–(41), we see that in the case of the double autoresonance the asymptotic large \( t \) solutions for the actions are given by

\[
\begin{align*}
\dot{I}_1 &= \frac{b \alpha_2 - c \alpha_1}{D} I_1, \\
\dot{I}_2 &= \frac{b \alpha_1 - a \alpha_2}{D} I_2.
\end{align*}
\]

(44)

Thus, in addition, for the double autoresonance to actually happen the asymptotic actions \( \dot{I}_1, \dot{I}_2 \) defined above must be positive.

There are two possible situations, depending on whether \( k_1 \) and \( k_2 \) have the same sign: (1) If \( k_1 k_2 > 0 \), we have \( b < 0, a < 0, c < 0 \). In this case \( D \) can have both positive and negative values. Figure 6 shows the lines for \( D = 0 \) in the plane formed by the absolute values of the phase velocities of the driving waves \((\omega_1 / |k_1|, \omega_2 / |k_2|)\) for different values of the ion thermal velocity \( u_{th} \). We can see that the ion thermal velocity \( u_{th} \), though not an extremely sensitive parameter, nevertheless determines the regions of positive and negative values of \( D \). Thus the cold ion model should be used carefully and the thermal ion velocity should in general be taken into account. In the region where \( D > 0 \), for the double autoresonance to occur \( \alpha_1 \alpha_2 \) must be positive. In addition, for positive \( \dot{I}_1, \dot{I}_2 \) we must have \(|b|/|a| < \alpha_2 / \alpha_1 < |c|/|b|\). In contrast, if \( D < 0 \), we must have \( \alpha_1 \alpha_2 < 0 \). However, in this case it is impossible for both \( \dot{I}_1 \) and \( \dot{I}_2 \) to be positive at the same time. Thus, if \( k_1 k_2 > 0 \), the double autoresonance is possible only in the region where \( D > 0 \); in this region we also must have \( \alpha_1 \alpha_2 > 0 \) and \(|b|/|a| < \alpha_2 / \alpha_1 < |c|/|b|\). (2) The second possibility is \( k_1 k_2 < 0 \), then we have \( b > 0, a < 0, c < 0 \). In this case \( D \) is always positive, and, consequently, for double autoresonance we must have \( \alpha_1 \alpha_2 > 0 \). In addition, to have positive \( \dot{I}_1, \dot{I}_2 \) only the case when both \( \alpha_1, \alpha_2 \) are positive works. Thus, in the case where \( k_1 k_2 < 0 \), the double autoresonance is possible when \( \alpha_1, \alpha_2 > 0 \). We do not deal with the degenerate case of \( k_1 = k_2 \) in this paper.
FIG. 7. Melting of a two-phase quasicrystal into a single phase quasicrystal around the threshold in the fully nonlinear model. The colormaps show the electron density \( n_e(x, \tau) \) in the \((x, \tau)\) plane for a two-phase ion acoustic wave excited by two driving counter propagating traveling waves with \( k_1 = -0.5 \) and \( k_2 = 1 \) obtained by solving the fully nonlinear equations (1)–(3) for various values of \( \bar{\varepsilon}_2 \): just above the threshold \((\bar{\varepsilon}_2/\bar{\varepsilon}_1 = 0.338, \text{top subplot})\), just below the threshold \((\bar{\varepsilon}_2/\bar{\varepsilon}_1 = 0.337, \text{middle subplot})\), and below the threshold \((\bar{\varepsilon}_2/\bar{\varepsilon}_1 = 0.32, \text{bottom subplot})\). The parameters used in the simulations are otherwise the same as in Figs. 1(a), 2, and 3. The red-vertical line indicates the termination of the drive at \( \tau = 12 \).

Thresholds

The important dynamical characteristic of the autoresonance is that when starting from zero, the chirped-driven system is captured into resonance only if the driving amplitudes exceed a certain threshold [73]. Thus, if we increase the amplitudes of the drives, the autoresonant excitation of the quasicrystals occurs abruptly, resembling a phase transition.

The thresholds can be analyzed by reducing the problem to the motion of pseudoparticles in an anharmonic slowly varying potential well, similar to the way it was done in Ref. [74] for the single phase weakly nonlinear theory. However, unlike the threshold for the autoresonance of a single phase ion acoustic wave (see Ref. [67]), the general analytical result for the double autoresonance thresholds is difficult to obtain and the thresholds are complicated functions of \( \alpha_1, \alpha_2, a(k_1), b(k_1, k_2), c(k_2) \). Nonetheless, it is possible to find the thresholds numerically. As an example let us use the same parameters as in Figs. 1(a), 2, 3, and 4, fix the value of \( \bar{\varepsilon}_1 \), and solve numerically both the fully and weakly nonlinear equations while sweeping through values of \( \bar{\varepsilon}_2 \). The results of these simulations are presented in Figs. 7 and 8. Figure 7 shows a colormap of the electron density \( n_e(x, \tau) \approx e^{\varphi(x, \tau)} \) obtained by solving the fully nonlinear equations (1)–(3) for various values of \( \bar{\varepsilon}_2 \): just above the threshold \( \bar{\varepsilon}_2 = 0.338\bar{\varepsilon}_1 \) (top subplot), just below the threshold \( \bar{\varepsilon}_2 = 0.337\bar{\varepsilon}_1 \) (middle subplot), and below the threshold \( \bar{\varepsilon}_2 = 0.32\bar{\varepsilon}_1 \) (bottom subplot), while Fig. 8 shows a colormap of the electron density \( n_e(x, \tau) \approx e^{\varphi(x, \tau)} \) obtained by solving the weakly nonlinear equations (38)–(41) for various values of \( \bar{\varepsilon}_2 \): just above the threshold \( \bar{\varepsilon}_2 = 0.339\bar{\varepsilon}_1 \) (top subplot), just below the threshold \( \bar{\varepsilon}_2 = 0.338\bar{\varepsilon}_1 \) (middle subplot), and below the threshold \( \bar{\varepsilon}_2 = 0.32\bar{\varepsilon}_1 \) (bottom subplot). We can see from these figures that the crystallization is indeed an abrupt phenomenon akin to a phase transition. For the fully nonlinear simulations the threshold lies between \( \bar{\varepsilon}_2/\bar{\varepsilon}_1 = 0.337 \) and \( \bar{\varepsilon}_2/\bar{\varepsilon}_1 = 0.338 \), while for the weakly nonlinear simulations the threshold lies between \( \bar{\varepsilon}_2/\bar{\varepsilon}_1 = 0.338 \) and \( \bar{\varepsilon}_2/\bar{\varepsilon}_1 = 0.339 \). Such a good agreement for the value of the threshold is another proof that our weakly nonlinear theory is applicable. To better illustrate the threshold nature of the double autoresonance we also produced an animation showing the crystallization of a
The necessity of the phase locking for the autoresonance is demonstrated in Fig. 9, which shows the effective actions $I_1, I_2$ (top subplots) and the phase mismatches $\Phi_1, \Phi_2$ (bottom subplots) vs slow time $\tau = \sqrt{\alpha_1 t}$ obtained by solving the weakly nonlinear reduced dynamical equations (38)–(41). The parameters used in the simulations are the same as in Figs. 1(a), 2, and 3 except for parameter $\bar{\varepsilon}_2$, which is equal to $\bar{v}_2 = 0.338\bar{v}_1$ (left side) and $\bar{v}_2 = 0.339\bar{v}_1$ (right side). The animation is available in the Supplemental Material [75].

The necessity of the phase locking for the autoresonance is demonstrated in Fig. 9, which shows the effective actions $I_1, I_2$ and the phase mismatches $\Phi_1, \Phi_2$ as functions of slow time $\tau = \sqrt{\alpha_1 t}$ just below the threshold ($\bar{v}_2/\bar{v}_1 = 0.338$, left side) and just above the threshold ($\bar{v}_2/\bar{v}_1 = 0.339$, right side). One can clearly see that just below the threshold the second action $I_2$ does not enter the autoresonant regime and the growth of the amplitude saturates, while the phase mismatch $\Phi_2$ increases with time signifying the absence of phase locking. In contrast, just above the threshold both phases are locked and the amplitudes $I_1, I_2$ increase in time similar to the case shown in Fig. 4.

V. CONCLUSIONS

We have demonstrated by means of nonlinear numerical simulations that it is possible to create quasicrystalline spatiotemporal structures in plasma by exciting large amplitude two-phase ion acoustic waves nonlinearly phased locked into the corresponding small amplitude traveling wave drives with chirped frequencies. We have used the Lagrangian formulation and Whitham’s averaged variational method to derive analytical results describing the weakly nonlinear evolution of the system. We have applied the weakly nonlinear analytical theory to determine the parameters necessary for the successful excitation and control of multiphase waves. The nonlinearly excited quasicrystalline structures remain even after we turn off the drive. Thus, the space-time quasicrystalline structure in plasma can be excited and then used independently for the purpose of plasma photonics experiments. While our warm fluid model does not have dissipation or noise due to collisions or Landau damping, for example, and, generally speaking, its long-time stability must be addressed by kinetic or particle-in-cell (PIC) simulations, it is apparent that, depending on the time scales of the problem, this structure can be considered as at least a dissipative space-time crystal. We also note that we do not address in this paper whether the driven space-time crystal is a “true” time crystal in the sense of spontaneous symmetry breaking as
proposed in Refs. [76,77]; for more discussion regarding this see Refs. [35,78,79].

It is expected that, using our technique, similar structures can be driven in other systems, for example dust acoustic waves in complex plasmas [80]. We expect that multiphase solutions when the number of drives exceeds two are also possible; however, it will be harder to analyze such a system analytically. Finally, we point out that beyond any practical application as a plasma photonic (or accelerating) structure, the possibility of exciting multiphase solutions for in general non-integrable warm ion acoustic waves system is in itself an important fundamental result in the field of nonlinear dynamics. These techniques developed for the excitation of large amplitude ion acoustic waves may be applied to other partial differential equation systems that can support multiphase nonlinear waves.

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APPENDIX A: THE AVERAGED LAGRANGIAN DENSITY

The averaged Lagrangian density

\[
\tilde{L} = \langle L(\theta_1, \theta_2, t) \rangle_{\theta_1, \theta_2} = \int L(\theta_1, \theta_2, t) \frac{d\theta_1}{2\pi} \frac{d\theta_2}{2\pi}
\]

is equal to the sum of the following terms:

\[
\left( \frac{1}{2} \phi^2 \right)_{\theta_1, \theta_2} = \frac{1}{4} k_1^2 \sigma_1^2 + \frac{1}{4} k_2^2 \sigma_2^2 + \frac{1}{4} (k_1 + k_2)^2 C_1^2 + \frac{1}{4} (k_1 - k_2)^2 C_1^2 - \frac{1}{4} k_1^2 C_2^2 + \frac{1}{4} k_2^2 C_2^2,
\]

\[(A2)\]

\[\langle \varphi \rangle_{\theta_1, \theta_2} = C_{00},\]

\[(A3)\]

\[\left( \frac{1}{6} \psi^3 \right)_{\theta_1, \theta_2} = \frac{1}{4} C_{00} \left[ C_{10} + \frac{1}{2} C_{10} \right] + \frac{1}{4} \left( C_{00} + \frac{1}{2} C_{20} \right) C_{10} + \frac{1}{4} \left( C_{10} + \frac{1}{2} C_{00} \right) C_{20} + \frac{1}{4} \left( C_{10} + \frac{1}{2} C_{00} \right) C_{00},\]

\[(A4)\]

\[\left( \frac{1}{24} \psi^4 \right)_{\theta_1, \theta_2} = \frac{1}{64} C_{10}^4 + \frac{1}{16} C_{10}^4 + \frac{1}{64} C_{10}^4,
\]

\[(A5)\]

\[\left( -\frac{1}{2} \psi \sigma_x + \psi \sigma_y \right)_{\theta_1, \theta_2} = \frac{1}{2} \left( -\omega_1 k_1 \tilde{B}_{10} \tilde{A}_{10} + \frac{1}{2} \omega_2 k_1 \tilde{B}_{01} \tilde{A}_{01} + 2 \omega_1 k_2 \tilde{B}_{20} \tilde{A}_{20} + 2 \omega_2 k_2 \tilde{B}_{20} \tilde{A}_{20} \right) + \frac{1}{2} \left( \omega_1 - \omega_2 \right) (k_1 - k_2) \tilde{B}_{11} \tilde{A}_{11},\]

\[(A6)\]

\[\left( -\frac{1}{2} \psi_x^2 + \varphi \left( 1 + \sigma_x \right) \right)_{\theta_1, \theta_2} = -C_{00} - \frac{1}{4} k_1^2 \tilde{B}_{10}^2 - \frac{1}{4} k_2^2 \tilde{B}_{01}^2 - k_1^2 \tilde{B}_{20}^2 - k_2^2 \tilde{B}_{20}^2 - \frac{1}{4} (k_1 + k_2)^2 \tilde{B}_{11}^2 - \frac{1}{4} (k_1 - k_2)^2 \tilde{B}_{11}^2,
\]

\[(A7)\]

\[\left( \frac{1}{2} \psi_y^2 \left( 1 + \frac{1}{3} \sigma_y \right) \right)_{\theta_1, \theta_2} = -\frac{\Delta^2}{4} \tilde{A}_{10} - \frac{\Delta^2}{4} k_1^2 \tilde{A}_{10}^2 - \frac{\Delta^2}{4} k_2^2 \tilde{A}_{10}^2 - \frac{\Delta^2}{4} k_1^2 \tilde{A}_{10}^2 - \frac{\Delta^2}{4} k_2^2 \tilde{A}_{10}^2 - \frac{\Delta^2}{4} k_1^2 \tilde{A}_{10}^2 - \frac{\Delta^2}{4} k_2^2 \tilde{A}_{10}^2 - \frac{\Delta^2}{4} k_1^2 \tilde{A}_{10}^2 - \frac{\Delta^2}{4} k_2^2 \tilde{A}_{10}^2,
\]

\[(A8)\]
APPENDIX B: THE VARIATIONS AND THE AMPLITUDES

In this Appendix we calculate the variations of the averaged Lagrangian with respect to the various amplitudes and express all the second-order amplitudes \( \tilde{A}_{20}, \tilde{A}_{12}, \tilde{B}_{20}, \tilde{B}_{02}, \tilde{C}_{20}, \tilde{C}_{02}, \tilde{A}_{11}, \tilde{A}_{1-1}, \tilde{B}_{11}, \tilde{B}_{1-1}, \tilde{C}_{11}, \tilde{C}_{1-1} \) through the first-order amplitudes \( C_{10} \) and \( C_{01} \).

To express the second-order amplitudes through \( C_{10} \) and \( C_{01} \) let us first calculate the variations of the averaged Lagrangian density with respect to the second-order amplitudes:

\[
\frac{\partial L}{\partial C_{00}} = C_{00} + \frac{1}{4} C_{01}^2 + \frac{1}{4} C_{10}^2 = 0, \quad \text{(B1)}
\]

\[
\frac{\partial L}{\partial C_{20}} = 2k_1^2 C_{20} + \frac{1}{2} C_{20} + \frac{1}{8} C_{10}^2 - k_1 \tilde{A}_{20} = 0, \quad \text{(B2)}
\]

\[
\frac{\partial L}{\partial C_{02}} = 2k_2^2 C_{02} + \frac{1}{2} C_{02} + \frac{1}{8} C_{20}^2 - k_2 \tilde{A}_{02} = 0, \quad \text{(B3)}
\]

\[
\frac{\partial L}{\partial C_{11}} = \frac{1}{2} (k_1 + k_2)^2 C_{11} + \frac{1}{4} C_{11} C_{10}
- \frac{1}{4} (k_1 + k_2) \tilde{A}_{11} = 0, \quad \text{(B4)}
\]

\[
\frac{\partial L}{\partial C_{1-1}} = \frac{1}{2} (k_1 - k_2)^2 C_{1-1} + \frac{1}{4} C_{11} C_{10}
- \frac{1}{4} (k_1 - k_2) \tilde{A}_{1-1} = 0, \quad \text{(B5)}
\]

\[
\frac{\partial L}{\partial \tilde{A}_{20}} = 2 \omega_1 k_2 \tilde{B}_{20} - k_1 C_{20} - \frac{1}{4} k_1^2 \tilde{B}_{10}^2 - \frac{\Delta^2}{4} k_1^2 \tilde{A}_{10}^2
- 2 \Delta^2 k_1^2 \tilde{A}_{20} = 0, \quad \text{(B6)}
\]

\[
\frac{\partial L}{\partial \tilde{A}_{02}} = 2 \omega_2 k_2 \tilde{B}_{02} - k_2 C_{02} - \frac{1}{4} k_2^2 \tilde{B}_{01}^2 - \frac{\Delta^2}{4} k_2^2 \tilde{A}_{01}^2
- 2 \Delta^2 k_2^2 \tilde{A}_{02} = 0, \quad \text{(B7)}
\]

From Eqs. (B2), (B3), (B6), (B7), (B10), and (B11) we obtain

\[
\tilde{A}_{20} = \frac{k_1^3 (4k_1^2 + 1) \tilde{B}_{10}^2 + 2 \omega_1 k_1 (4k_1^2 + 1) \tilde{A}_{10} \tilde{B}_{10} - k_1 C_{20} + \Delta^2 k_1^3 (4k_1^2 + 1) \tilde{A}_{10}^2}{8 \left[ (\omega_1^2 - \Delta^2 k_1^2)(4k_1^2 + 1) - k_1^2 \right]}, \quad \text{(B15)}
\]

\[
\tilde{A}_{02} = \frac{k_2^3 (4k_2^2 + 1) \tilde{B}_{01}^2 + 2 \omega_2 k_2 (4k_2^2 + 1) \tilde{A}_{01} \tilde{B}_{01} - k_2 C_{02} + \Delta^2 k_2^3 (4k_2^2 + 1) \tilde{A}_{01}^2}{8 \left[ (\omega_2^2 - \Delta^2 k_2^2)(4k_2^2 + 1) - k_2^2 \right]}, \quad \text{(B16)}
\]

\[
\tilde{B}_{20} = \frac{\omega_1 k_1^3 (4k_1^2 + 1) \tilde{B}_{10}^2 + 2k_1 \tilde{A}_{10} \tilde{B}_{10} - \omega_1 C_{20} + \Delta^2 \omega_1 k_1^3 (4k_1^2 + 1) \tilde{A}_{10}^2 + 2 \Delta^2 k_1^3 (4k_1^2 + 1) \tilde{A}_{10} \tilde{B}_{10}}{8 \left[ (\omega_1^2 - \Delta^2 k_1^2)(4k_1^2 + 1) - k_1^2 \right]}, \quad \text{(B17)}
\]

\[
\tilde{B}_{02} = \frac{\omega_2 k_2^3 (4k_2^2 + 1) \tilde{B}_{01}^2 + 2k_2 \tilde{A}_{01} \tilde{B}_{01} - \omega_2 C_{02} + \Delta^2 \omega_2 k_2^3 (4k_2^2 + 1) \tilde{A}_{01}^2 + 2 \Delta^2 k_2^3 (4k_2^2 + 1) \tilde{A}_{01} \tilde{B}_{01}}{8 \left[ (\omega_2^2 - \Delta^2 k_2^2)(4k_2^2 + 1) - k_2^2 \right]}, \quad \text{(B18)}
\]

\[
\tilde{C}_{20} = \frac{k_1^3 \tilde{B}_{10}^2 + 2 \omega_1 k_1 \tilde{A}_{10} \tilde{B}_{10} - \omega_1 C_{20} + \Delta^2 k_1^3 \tilde{A}_{10}^2 + \Delta^2 k_1^3 \tilde{B}_{10}^2}{4 \left[ (\omega_1^2 - \Delta^2 k_1^2)(4k_1^2 + 1) - k_1^2 \right]}, \quad \text{(B19)}
\]

\[
\tilde{C}_{02} = \frac{k_2^3 \tilde{B}_{01}^2 + 2 \omega_2 k_2 \tilde{A}_{01} \tilde{B}_{01} - \omega_2 C_{02} + \Delta^2 k_2^3 \tilde{A}_{01}^2 + \Delta^2 k_2^3 \tilde{B}_{01}^2}{4 \left[ (\omega_2^2 - \Delta^2 k_2^2)(4k_2^2 + 1) - k_2^2 \right]}, \quad \text{(B20)}
\]

From Eqs. (B4), (B5), (B8), (B9), (B12), and (B13) we obtain

\[
\tilde{A}_{11} = \frac{k_1 k_2 (k_1 + k_2)^2 (k_1 + k_2)^2 + 1) \tilde{B}_{10} - (k_1 + k_2) C_{01} C_{10}}{2 \left[ (\omega_1 + \omega_2)^2 - \Delta^2 (k_1 + k_2)^2 \right] \left[ (k_1 + k_2)^2 + 1 \right] (k_1 + k_2)^2}
+ \frac{(\omega_1 + \omega_2) k_1 k_2 (k_1 + k_2)^2 + 1) (\tilde{A}_{10} \tilde{B}_{10} - \tilde{A}_{10} \tilde{B}_{01})}{2 \left[ (\omega_1 + \omega_2)^2 - \Delta^2 (k_1 + k_2)^2 \right] \left[ (k_1 + k_2)^2 + 1 \right] (k_1 + k_2)^2}
\]
Finally, by using Eqs. (20)–(23), we can express all the second-order amplitudes through $C_{10}$ and $C_{01}$:

\[ \tilde{A}_{1-1} = \frac{\Delta^2k_1k_2(k_1 + k_2)(k_1 + k_2)^2 + 1}{2[\omega_1^2 + \omega_2^2 - \Delta^2(k_1 + k_2)^2][(k_1 + k_2)^2 + 1] - (k_1 + k_2)^2} \]

\[ \tilde{B}_{1-1} = \frac{\Delta^2k_1k_2[(k_1 + k_2)^2 + 1]B_{10}B_{10} + (\omega_1 - \omega_2)k_1k_2(k_1 + k_2)(\tilde{A}_{10}B_{10} + \tilde{A}_{10}B_{10})}{2[\omega_1^2 + \omega_2^2 - \Delta^2(k_1 + k_2)^2][(k_1 + k_2)^2 + 1] - (k_1 + k_2)^2} \]

\[ \tilde{C}_{1-1} = \frac{\Delta^2k_1k_2([k_1 + k_2]^2 + 1][B_{10}B_{10} - (\omega_1 - \omega_2)\omega_1\omega_2C_{10} + k_1k_2(k_1 + k_2)(\tilde{A}_{10}B_{10} + \tilde{A}_{10}B_{10})]}{2[\omega_1^2 + \omega_2^2 - \Delta^2(k_1 + k_2)^2][(k_1 + k_2)^2 + 1] - (k_1 + k_2)^2} \]

Finally, by using Eqs. (20)–(23), we can express all the second-order amplitudes through $C_{10}$ and $C_{01}$:
Note that in the limiting case of cold ions ($\Delta = 0$) and with two identical counter propagating traveling waves (i.e., a standing wave with $k_1 = -k$, $k_2 = k$, $\omega_1 = \omega_2 = \omega_0$, $\epsilon_1 = \epsilon_2 = \epsilon$) the above amplitudes coincide with the amplitudes derived in Ref. [60], as expected. In particular, the amplitudes $a_1$, $a_2$, $A$, $b_1$, $b_2$, $c_0$, $c_1$, $c_2$, $C$ from Ref. [60] are related to the amplitudes in this paper as follows:

$$
\tilde{A}_{10} = -\frac{a_1}{2}, \quad \tilde{A}_{01} = \frac{a_1}{2}, \quad \tilde{A}_{20} = -\frac{a_2}{2}, \quad \tilde{A}_{02} = \frac{a_2}{2}, \quad \tilde{A}_{1,-1} = -A .
$$

$$
\tilde{B}_{10} = -\frac{b_1}{2}, \quad \tilde{B}_{01} = -\frac{b_1}{2}, \quad \tilde{B}_{20} = -\frac{b_2}{2}, \quad \tilde{B}_{02} = -\frac{b_2}{2},
$$

$$
C_{00} = \frac{c_0}{2}, \quad C_{11} = \frac{c_0}{2}, \quad C_{10} = \frac{c_1}{2}, \quad C_{01} = \frac{c_1}{2}, \quad C_{1,-1} = C, \quad C_{20} = \frac{c_2}{2}, \quad C_{02} = \frac{c_2}{2} .
$$

To derive weakly nonlinear equations we also need to calculate the variations of $\tilde{L}$ with respect to the first-order amplitudes:

$$
\frac{\partial \tilde{L}}{\partial C_{10}} = -\frac{1}{2} k_1 \tilde{A}_{10} + \frac{1}{2} (1 + k_1^2)C_{10} + \frac{1}{2} C_{10} \left( \frac{1}{8} C_{20}^2 + \frac{1}{4} C_{10}^2 + C_{00} + \frac{1}{2} C_{20} \right) + \frac{1}{4} C_{01}(C_{1,-1} + C_{11}) + \frac{\epsilon_1}{2} \cos(\Phi_1) = 0 ,
$$

$$
\frac{\partial \tilde{L}}{\partial C_{01}} = -\frac{1}{2} k_2 \tilde{A}_{01} + \frac{1}{2} (1 + k_2^2)C_{01} + \frac{1}{2} C_{01} \left( \frac{1}{8} C_{20}^2 + \frac{1}{4} C_{10}^2 + C_{00} + \frac{1}{2} C_{20} \right) + \frac{1}{4} C_{10}(C_{1,-1} + C_{11}) + \frac{\epsilon_2}{2} \cos(\Phi_2) = 0 ,
$$

$$
\frac{\partial \tilde{L}}{\partial B_{10}} = -\frac{1}{2} k_1 (1 + k_1^2)\tilde{B}_{10} + \frac{k_1 k_2 (1 + k_2^2)\tilde{B}_{10}}{4} + \frac{1}{2} k_1 (\omega_1 - k_1^2 \tilde{B}_{20})\tilde{A}_{10} - \frac{1}{4} k_1 k_2 (1 + k_1^2)\tilde{A}_{1,-1} + (k_1 + k_2)\tilde{A}_{11}\tilde{B}_{11} = 0 ,
$$

$$
\frac{\partial \tilde{L}}{\partial B_{01}} = -\frac{1}{2} k_2 (1 + k_2^2)\tilde{B}_{01} - \frac{1}{2} k_1 k_2 (1 + k_1^2)\tilde{A}_{1,-1} + (k_1 + k_2)\tilde{A}_{11}\tilde{B}_{11} = 0 ,
$$

$$
\frac{\partial \tilde{L}}{\partial A_{10}} = -\frac{1}{2} k_1 C_{10} + \frac{1}{2} (k_1 \omega_1 - k_1^2 \tilde{B}_{20})\tilde{B}_{10} - \frac{1}{4} k_1 k_2 (1 + k_1^2)\tilde{B}_{1,-1} + (k_1 + k_2)\tilde{B}_{11}\tilde{B}_{11} = 0 ,
$$

$$
\frac{\partial \tilde{L}}{\partial A_{01}} = -\frac{1}{2} k_2 C_{01} + \frac{1}{2} (k_2 \omega_2 - k_2^2 \tilde{B}_{02})\tilde{B}_{01} - \frac{1}{4} k_1 k_2 (1 + k_1^2)\tilde{B}_{1,-1} + (k_1 + k_2)\tilde{B}_{11}\tilde{B}_{11} = 0 ,
$$

$$
= \frac{\Delta^2}{4} k_1^2 (1 + k_1^2)\tilde{A}_{10} - \Delta^2 k_1 k_2 (1 + k_1^2)\tilde{A}_{1,-1} + (k_1 + k_2)\tilde{A}_{11}\tilde{A}_{11} = 0 ,
$$

$$
= \frac{\Delta^2}{4} k_1^2 (1 + k_1^2)\tilde{A}_{10} - \Delta^2 k_1 k_2 (1 + k_1^2)\tilde{A}_{1,-1} + (k_1 + k_2)\tilde{A}_{11}\tilde{A}_{11} = 0 .
$$

\[023150-13\]
APPENDIX C: FUNCTIONS $P(k_1, \omega_1)$ AND $Q(k_1, \omega_1; k_2, \omega_2)$

Function $P(k_1, \omega_1)$ is defined through

$$C_{10}^2 P(k_1, \omega_1) = -\frac{1}{8} C_{10}^2 + \frac{1}{2} C_{20} - \frac{2 \omega_1 k_1^4}{(\omega_1^2 - \Delta^2 k_1^2)} \tilde{A}_{20} - \frac{k_1^3 (\omega_1^2 + \Delta^2 k_1^2)}{(\omega_1^2 - \Delta^2 k_1^2)^2} \tilde{A}_{02},$$

(C1)

or, equivalently due to symmetry, through

$$C_{01}^2 P(k_2, \omega_2) = -\frac{1}{8} C_{01}^2 + \frac{1}{2} C_{02} - \frac{2 \omega_2 k_2^4}{(\omega_2^2 - \Delta^2 k_2^2)} \tilde{B}_{02} - \frac{k_2^3 (\omega_2^2 + \Delta^2 k_2^2)}{(\omega_2^2 - \Delta^2 k_2^2)^2} \tilde{B}_{02},$$

(C2)

while $Q(k_1, \omega_1; k_2, \omega_2)$ is defined through

$$C_{01} C_{10} Q(k_1, \omega_1; k_2, \omega_2) = \frac{1}{2} \left\{ C_{1,-1} + C_{11} - \frac{k_1 k_2 (\omega_1 \omega_2 + \Delta^2 k_1 k_2)}{(\omega_1^2 - \Delta^2 k_1^2)(\omega_2^2 - \Delta^2 k_2^2)} [(k_1 - k_2) \tilde{A}_{1,-1} + (k_1 + k_2) \tilde{A}_{11}] \\
- \frac{k_1 k_2 (k_1 \omega_2 + k_2 \omega_1)}{(\omega_1^2 - \Delta^2 k_1^2)(\omega_2^2 - \Delta^2 k_2^2)} [(k_1 - k_2) \tilde{B}_{1,-1} + (k_1 + k_2) \tilde{B}_{11}] \right\}.$$  

(C3)

Here, the amplitudes $\tilde{A}_{20}, \tilde{A}_{02}, \tilde{B}_{20}, \tilde{B}_{02}, C_{20}, C_{02}, \tilde{A}_{11}, \tilde{A}_{1,-1}, \tilde{B}_{1,-1}, \tilde{B}_{11}, C_{11}, C_{1,-1}$ should be expressed through $C_{10}, C_{01}, k_1, k_2, \omega_1, \omega_2, \Delta$ using Eqs. (B27)–(B38), so that $P(k_1, \omega_1), Q(k_1, \omega_1; k_2, \omega_2)$ are functions of $k_1, k_2, \omega_1, \omega_2, \Delta$ only.

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