Variational approximation for heteroscedastic linear models and matching pursuit algorithms

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Abstract Modern statistical applications involving large data sets have focused attention on statistical methodologies which are both efficient computationally and able to deal with the screening of large numbers of different candidate models. Here we consider computationally efficient variational Bayes approaches to inference in high-dimensional heteroscedastic linear regression, where both the mean and variance are described in terms of linear functions of the predictors and where the number of predictors can be larger than the sample size. We derive a closed form variational lower bound on the log marginal likelihood useful for model selection, and propose a novel fast greedy search algorithm on the model space which makes use of one-step optimization updates to the variational lower bound in the current model for screening large numbers of candidate predictor variables for inclusion/exclusion in a computationally thrifty way. We show that the model search strategy we suggest is related to widely used orthogonal matching pursuit algorithms for model search but yields a framework for potentially extending these algorithms to more complex models. The methodology is applied in simulations and in two real examples involving prediction for food constituents using NIR technology and prediction of disease progression in diabetes.

Keywords Bayesian model selection · Heteroscedasticity · Matching pursuit · Variational approximation

1 Introduction

Consider the heteroscedastic linear regression model

\[ y_i = x_i^T \beta + \sigma_i \epsilon_i, \quad i = 1, \ldots, n, \]  

(1)

where \( y_i \) is a response, \( x_i = (x_{i1}, \ldots, x_{ip})^T \) is a corresponding \( p \)-vector of predictors, \( \beta = (\beta_1, \ldots, \beta_p)^T \) is a vector of unknown mean parameters, \( \epsilon_i \sim N(0, 1) \) are independent errors and

\[ \log \sigma_i^2 = z_i^T \alpha, \]

where \( z_i = (z_{i1}, \ldots, z_{iq})^T \) is a \( q \)-vector of predictors and \( \alpha = (\alpha_1, \ldots, \alpha_q)^T \) are unknown variance parameters. In this model the standard deviation \( \sigma_i \) of \( y_i \) is being modeled in terms of the predictors \( z_i \); this heteroscedastic model may be contrasted with the usual homoscedastic model which assumes \( \sigma_i \) is constant. We take a Bayesian approach to inference for this model and consider a prior distribution \( p(\theta) \) on \( \theta = (\beta^T, \alpha^T)^T \) of the form \( p(\theta) = p(\beta)p(\alpha) \) with \( p(\beta) \) and \( p(\alpha) \) both normal, \( N(\mu_\beta^0, \Sigma_\beta^0) \) and \( N(\mu_\alpha^0, \Sigma_\alpha^0) \) respectively. It is possible to consider hierarchical extensions for the priors on \( p(\beta) \) and \( p(\alpha) \) but we do not consider this here.

We will consider a variational Bayes approach for inference (see Sect. 2 for the details). The term variational approximation refers to a wide range of different methods where the idea is to convert a problem of integration into an optimization problem. In Bayesian inference, variational approximation provides a fast alternative to Monte Carlo methods for approximating posterior distributions in complex models, especially in high-dimensional problems. In the heteroscedastic linear regression model, we will consider a variational approximation to the joint posterior distribution of \( \beta \) and \( \alpha \) as \( q(\beta, \alpha) = q(\beta)q(\alpha) \), where \( q(\beta) \) and
$q(\alpha)$ are both normal densities, $N(\mu_{q\beta}, \Sigma_{q\beta})$ and $N(\mu_{q\alpha}, \Sigma_{q\alpha})$ respectively. It is also possible to give a variational treatment in which independence is not assumed between $\beta$ and $\alpha$ (John Ormerod, personal communication) but this complicates the variational optimization somewhat. We attempt to choose the parameters in the variational posterior $\mu_{q\beta}$, $\mu_{q\alpha}$, $\Sigma_{q\beta}$ and $\Sigma_{q\alpha}$ to minimize the Kullback-Leibler divergence between the true posterior distribution $p(\beta, \alpha | y)$ and $q(\beta, \alpha)$. This results in a lower bound on the log marginal likelihood $\log p(y)$—a key quantity in Bayesian model selection. The first contribution of our paper is the derivation of a closed form for the lower bound and the proposal of an iterative scheme for maximizing it. This lower bound maximization plays a crucial role in the variable selection problem discussed in Sect. 3.

Variable selection is a fundamental problem in statistics and machine learning, and a large number of methods have been proposed for variable selection in homoscedastic regression. The traditional variable selection approach in the Bayesian framework consists of building a hierarchical Bayes model and using MCMC algorithms to estimate posterior model probabilities (George and McCulloch 1993; Smith and Kohn 1996; Raftery et al. 1997). This methodology is computationally demanding in high-dimensional problems and there is a need for fast alternatives in some applications. In high-dimensional settings, alternative approaches include the family of greedy algorithms (Tropp 2004; Zhang 2009), also known as matching pursuit (Mallat and Zhang 1993) in signal processing. Greedy algorithms are closely related to the Lasso (Tibshirani 1996) and the LARS algorithm (Efron et al. 2004). See Zhao and Yu (2007), Efron et al. (2004) and Zhang (2009) for excellent comparisons of these families of algorithms. In the statistical context, greedy algorithms have been proven to be very efficient for variable selection in linear regression under the assumption of homoscedasticity, i.e. where the variance is assumed to be constant (Zhang 2009).

In many applications the assumption of constant variance may be unrealistic. Ignoring heteroscedasticity may lead to serious problems in inference, such as misleading assessments of significance, poor predictive performance and inefficient estimation of mean parameters. In some cases, learning the structure in the variance may be the primary goal. See Chan et al. (2006), Carroll and Ruppert (1988) and Ruppert et al. (2003), Chap. 14, for a more detailed discussion on heteroscedastic modeling. Despite a large number of works on heteroscedastic linear regression and overdispersed generalized linear models in which overdispersion is modeled to depend on the covariates (Efron 1986; Nelder and Pregibon 1987; Davidian and Carroll 1987; Smyth 1989; Yee and Wild 1996; Rigby and Stasinopoulos 2005), methods for variable selection seem to be somewhat overlooked. Yau and Kohn (2003) and Chan et al. (2006) consider Bayesian variable selection using MCMC computational approaches in heteroscedastic Gaussian models. They discuss extensions involving flexible modeling of the mean and variance functions. Cottet et al. (2008) consider extensions to overdispersed generalized linear and generalized additive models. These approaches are computationally demanding in high-dimensional settings. A general and flexible framework for modeling overdispersed data is also considered by Yee and Wild (1996) and Rigby and Stasinopoulos (2005). Methods for model selection, however, are less well developed. A common approach is to use information criteria such as generalized AIC and BIC together with forward stepwise methods (see, for example, Rigby and Stasinopoulos 2005, Sect. 6). We compare our own approaches to such methods later. A main contribution of the present paper is to propose a novel fast greedy algorithm for variable selection in heteroscedastic linear regression. We show that the proposed algorithm is in homoscedastic cases similar to currently used methods while having many attractive properties and working efficiently in high-dimensional problems. An efficient R program is available on the authors’ websites.

In Sect. 4 we apply our algorithm to the analysis of the diabetes data (Efron et al. 2004) using heteroscedastic linear regression. This data set consists of 64 predictors (constructed from 10 input variables for a “quadratic model”) and 442 observations. We show in Fig. 1 the estimated coefficients corresponding to selected predictors as functions of iteration steps in our algorithm, for both the mean and variance models. The algorithm stops after 11 forward selection steps with 8 and 7 predictors selected for the mean and variance models respectively.

The rest of the paper is organized as follows. The closed form of the lower bound and the iterative scheme for maximizing it are presented in Sect. 2. We present in Sect. 3 our novel fast greedy algorithm, and compare it to existing greedy algorithms for homoscedastic regression. In Sect. 4 we apply our methodology to the analysis of two benchmark data sets. Experimental studies are presented in Sect. 5. Section 6 contains conclusions and future research. Technical derivation is relegated to the Appendices.

### 2 Variational Bayes

We now give a brief introduction to the variational approximation method. For a more detailed exposition see, for example, Jordan et al. (1999), Bishop (2006), Chap. 10, or see Ormerod and Wand (2010) for a statistically oriented introduction. The term variational approximation refers to a wide range of different methods where the idea is to convert a problem of integration into an optimization problem.
Here we will only be concerned with applications of variational methods in Bayesian inference and only with a particular approach sometimes referred to as parametric variational approximation. Write $\theta$ for all our unknown parameters, $p(\theta)$ for the prior distribution and $p(y|\theta)$ for the likelihood. For Bayesian inference, decisions are based on the posterior distribution $p(\theta|y) \propto p(\theta)p(y|\theta)$. A common difficulty in applications is how to compute quantities of interest with respect to the posterior. These computations often involve the evaluation of high-dimensional integrals. Variational approximation proceeds by approximating the posterior directly. Formally, we consider a family of distributions $q(\theta|\lambda)$ where $\lambda$ denotes some unknown parameters, and attempt to choose $\lambda$ so that $q(\theta|\lambda)$ is closest to $p(\theta|y)$ in some sense. In particular, we attempt to minimize the Kullback-Leibler divergence

$$\int \log \frac{q(\theta|\lambda)}{p(\theta|y)} p(\theta|y) q(\theta|\lambda) d\theta$$

with respect to $\lambda$. Using the identity

$$\log p(y) = \int \log \frac{p(\theta)p(y|\theta)}{q(\theta|\lambda)} q(\theta|\lambda) d\theta + \int \log \frac{q(\theta|\lambda)}{p(\theta|y)} q(\theta|\lambda) d\theta,$$

where $p(y) = \int p(\theta)p(y|\theta)d\theta$, we see that minimizing the Kullback-Leibler divergence is equivalent to the maximization of

$$\int \log \frac{p(\theta)p(y|\theta)}{q(\theta|\lambda)} q(\theta|\lambda) d\theta.$$  \hspace{1cm} (3)

Here (3) is a lower bound (often called the free energy in physics) on the log marginal likelihood $\log p(y)$ due to the non-negativity of the Kullback-Leibler divergence term in (2). The lower bound (3), when maximized with respect to $\lambda$, is often used as an approximation to the log marginal likelihood $\log p(y)$. The error in the approximation is the Kullback-Leibler divergence between the approximation $q(\theta|\lambda)$ and the true posterior. The approximation is useful, since $\log p(y)$ is a key quantity in Bayesian model selection.

For our heteroscedastic linear model, the lower bound (3) can be expressed as

$$L = T_1 + T_2 + T_3,$$

where

$$T_1 = \int \log [p(\beta,\alpha)|q(\beta)q(\alpha)] q(\beta)q(\alpha) d\beta d\alpha,$$

$$T_2 = \int \log [p(y|\beta,\alpha)q(\beta)q(\alpha)] q(\beta)q(\alpha) d\beta d\alpha,$$

$$T_3 = -\int \log [q(\beta)q(\alpha)] q(\beta)q(\alpha) d\beta d\alpha.$$
\[-\frac{1}{2} \sum_{i=1}^{n} z_i^T \mu_\alpha^q - \frac{1}{2} \sum_{i=1}^{n} \left( y_i - x_i^T \mu_\beta^q \right)^2 + x_i^T \Sigma_\beta^q x_i \right) \exp\left(z_i^T \mu_\alpha^q - \frac{1}{2} z_i^T \Sigma_\alpha^q z_i \right). \tag{4}
\]

This needs to be maximized with respect to \( \mu_\beta^q, \mu_\alpha^q, \Sigma_\beta^q, \Sigma_\alpha^q \). We consider an iterative scheme in which we maximize with respect to each of the blocks of parameters \( \mu_\beta^q, \mu_\alpha^q, \Sigma_\beta^q, \Sigma_\alpha^q \) with the other blocks held fixed.

Write \( X \) for the design matrix with \( i \)th row \( x_i^T \) and \( D \) for the diagonal matrix with \( i \)th diagonal element \( 1/\exp(z_i^T \mu_\alpha^q - \frac{1}{2} z_i^T \Sigma_\alpha^q z_i) \). Maximization with respect to \( \mu_\beta^q \) with other terms held fixed leads to

\[\mu_\beta^q = \left( X^T D X + \Sigma_\beta^0 \right)^{-1} \left( \Sigma_\beta^0 \mu_\beta^0 + X^T D y \right).\]

Maximization with respect to \( \Sigma_\beta^q \) with other terms held fixed leads to

\[\Sigma_\beta^q = \left( \Sigma_\beta^0 \right)^{-1} + X^T D X \right)^{-1}.

Handling the parameters \( \mu_\alpha^q \) and \( \Sigma_\alpha^q \) in the variational posterior for \( \alpha \) is more complex. We proceed in the following way. If no parametric form for the variational posterior \( q(\alpha) \) is assumed (that is, if we do not assume that \( q(\alpha) \) is normal) but only assume the factorization \( q(\alpha) = q(\beta) q(\alpha) \) then the optimal choice for \( q(\alpha) \) for a given \( q(\beta) = N(\mu_\beta, \Sigma_\beta) \) is (see Ormerod and Wand 2010, for example)

\[q(\alpha) \propto \exp \left( E(\log[p(\theta) p(y|\theta)]) \right), \tag{5}\]

where the expectation is with respect to \( q(\beta) \). Similar to the derivation of the lower bound (4), it is easy to see that

\[q(\alpha) \propto \exp \left( -\frac{1}{2} \sum_{i=1}^{n} z_i^T \alpha \right. \left. - \frac{1}{2} \sum_{i=1}^{n} \left( y_i - x_i^T \mu_\beta^q \right)^2 + x_i^T \Sigma_\beta^q x_i \right) \exp\left(z_i^T \mu_\alpha^q - \frac{1}{2} z_i^T \Sigma_\alpha^q z_i \right) - \frac{1}{2}(\alpha - \mu_\alpha^0)^T \Sigma_\alpha^0 (\alpha - \mu_\alpha^0),\]

which takes the form of the posterior (apart from a normalization constant) for a Bayesian generalized linear model with gamma response and log link, coefficient of variation \( \sqrt{2} \), and responses \( w_i = (y_i - x_i^T \mu_\beta^q)^2 + x_i^T \Sigma_\beta^q x_i \) with the log of the mean response being \( z_i^T \alpha \). The prior in this gamma generalized linear model is \( N(\mu_\alpha^0, \Sigma_\alpha^0) \). If we use a quadratic approximation to \( \log q(\alpha) \) then this results in a normal approximation to \( q(\alpha) \). We choose the mean and variance of the normal approximation simply by the posterior mode and the negative inverse Hessian of the log posterior at the mode for the gamma generalized linear model described above. The computations required are standard ones in fitting a Bayesian generalized linear model (see Appendix). Write \( Z \) for the design matrix in the variance model with \( i \)th row \( z_i^T \) and write \( W(\alpha) \) (as a function of \( \alpha \)) for the diagonal matrix \( \text{diag}(\frac{1}{2} w_i \exp(-z_i^T \alpha)) \). With \( \mu_\alpha^q \) the posterior mode, we obtain for \( \Sigma_\alpha^q \) the expression

\[\Sigma_\alpha^q = \left( Z^T W(\mu_\alpha^0) Z + \Sigma_\alpha^0 \right)^{-1}.\]

Our optimization over \( \mu_\alpha^q \) and \( \Sigma_\alpha^q \) is only approximate, so that we only retain the new values in the optimization if they result in an improvement in the lower bound (4). The advantage of our approximate approach is the closed form expression for the update of \( \Sigma_\alpha^q \) once \( \mu_\alpha^q \) is found, so that explicit numerical optimization for a possibly high-dimensional covariance matrix is avoided.

The explicit algorithm for our method is the following.

Algorithm 1 Maximization of the variational lower bound

1. Initialize parameters \( \mu_\alpha^0, \Sigma_\alpha^0 \).
2. \( \mu_\beta^q \leftarrow (X^T D X + \Sigma_\beta^0)^{-1}(\Sigma_\beta^0 \mu_\beta^0 + X^T D y) \) where \( D \) is the diagonal matrix with \( i \)th diagonal entry \( 1/\exp(z_i^T \mu_\alpha^q - 1/2 z_i^T \Sigma_\alpha^q z_i) \). \( \Sigma_\beta^q \leftarrow (X^T D X + \Sigma_\beta^0)^{-1} \).
3. Obtain \( \mu_\alpha^q \) as the posterior mode for a gamma generalized linear model with normal prior \( N(\mu_\alpha^0, \Sigma_\alpha^0) \), gamma responses \( w_i = (y_i - x_i^T \mu_\beta^q)^2 + x_i^T \Sigma_\beta^q x_i \), coefficient of variation \( \sqrt{2} \) and where the log of the mean is \( z_i^T \alpha \).
4. \( \Sigma_\alpha^q \leftarrow (Z^T W Z + \Sigma_\alpha^0)^{-1} \) where \( W \) is diagonal with \( i \)th diagonal element \( w_i \exp(-z_i^T \mu_\alpha^q)/2 \).
5. If the updates done in steps 3 and 4 do not improve the lower bound (4) then their old values are retained.
6. Repeat steps 2–6 until the increase in the variational lower bound (4) is less than some user specified tolerance.
The minimized KL divergence is small, thus leading to a good approximation. The experimental study in Sect. 5 suggests that the maximized lower bound is very tight.

Before presenting our strategy for ranking variational lower bounds, we discuss here the model prior. Suppose we have a current model with predictors \( x_i, i \in C \subset D = \{1, \ldots, p\} \) in the mean model and \( z_i, i \in V \subset E = \{1, \ldots, q\} \) in the variance model. The subsets \( C \) and \( V \) give indices for the currently active predictors in the mean and variance models. Let \( \pi^\mu \) (\( \pi^\sigma \)) be the prior probability for inclusion of \( x_j \) (\( z_j \)) in the mean (variance) model, and write \( \pi^\mu = (\pi^\mu_1, \ldots, \pi^\mu_p)^T \), \( \pi^\sigma = (\pi^\sigma_q, \ldots, \pi^\sigma_q)^T \). We assume that the inclusions of predictors are independent a priori with

\[
p(C | \pi^\mu) = \prod_{i \in C} \pi^\mu_i \prod_{i \notin C} (1 - \pi^\mu_i),
\]

\[
p(V | \pi^\sigma) = \prod_{j \in V} \pi^\sigma_j \prod_{j \notin V} (1 - \pi^\sigma_j),
\]

and the prior probability of a model \( m \) with index sets \( C \) and \( V \) in its mean and variance models is assumed to be

\[
p(m) = p(C, V | \pi^\mu, \pi^\sigma) = p(C | \pi^\mu) p(V | \pi^\sigma).
\]  

If no such detailed prior information is available for each individual predictor (which is the situation we consider in this paper), one may assume that \( \pi^\mu_1 = \cdots = \pi^\mu_p = \pi^\mu \) and \( \pi^\sigma_1 = \cdots = \pi^\sigma_q = \pi^\sigma \) (we note a slight abuse of notation here). Then

\[
p(C | \pi^\mu) = \pi^\mu |^{|C|} (1 - \pi^\mu)^{|-C|},
\]

\[
p(V | \pi^\sigma) = \pi^\sigma |^{|V|} (1 - \pi^\sigma)^{|-V|},
\]

where hyperparameters \( \pi^\mu, \pi^\sigma \in [0, 1] \) are user-specified. One can encourage parsimonious models by setting small \((< 1/2)\) \( \pi^\mu \) and \( \pi^\sigma \). The smaller the \( \pi^\mu \) and \( \pi^\sigma \), the smaller prior probabilities are put on complex models. By setting \( \pi^\mu = \pi^\sigma = 1/2 \), one can set a uniform prior on the models. Another option is to put uniform distributions on \( \pi^\mu \) and \( \pi^\sigma \). Then

\[
p(C) = \int_0^1 p(C | \pi^\mu) d\pi^\mu \propto \left( \frac{p}{|C|} \right)^{-1},
\]

\[
p(V) = \int_0^1 p(V | \pi^\sigma) d\pi^\sigma \propto \left( \frac{q}{|V|} \right)^{-1}.
\]

This prior agrees with the one used in the extended BIC proposed by Chen and Chen (2008). It has the advantage of requiring no hyperparameter while still encouraging parsimony. We recommend using this as the default prior.
We now consider adding a single variable in either the mean or the variance model, and then a one-step update to the current variational lower bound in the proposed model as a computationally thrifty way of ranking the predictors for possible inclusion. In our one-step update, we consider a variational approximation in which the variational posterior distribution factorizes into separate parts for the added parameter and the parameters in the current model, as well as for the factorization of mean and variance parameters in Sect. 2.

We stress that this factorization is only assumed for the purpose of ranking predictors for inclusion. Once a variable has been selected for inclusion, the posterior distribution is approximated using the method outlined in Sect. 2. Write $\beta_C$ for the parameters in the current mean model and $X_C$ for the corresponding design matrix, and $\alpha_V$ for the parameters in the current variance model with $Z_V$ the corresponding design matrix. Write $x_{Ci}$ for the $i$th row of $X_C$ and $z_{Vi}$ for the $i$th row of $Z_V$.

### 3.1 Ranking predictors in the mean model

Let us consider first the effect of adding the predictor $x_j$, $j \in D \setminus C$, to the mean model. We write $\beta_j$ for the coefficient of $x_j$ and we consider a variational approximation to the posterior of the form

$$q(\theta) = q(\beta_C)q(\beta_j)q(\alpha_V),$$

with $q(\beta_C) = N(\mu^q_{\beta_C}, \Sigma^q_{\beta_C})$, $q(\alpha_V) = N(\mu^q_{\alpha_V}, \Sigma^q_{\alpha_V})$ and $q(\beta_j) = N(\mu^q_{\beta_j}, (\sigma^q_{\beta_j})^2)$. Suppose that we have fitted a variational approximation for the current model (i.e. the model without $x_j$) using the method of Sect. 2. We now consider fitting the extended model with $\mu^q_{\beta_C}, \Sigma^q_{\beta_C}, \mu^q_{\alpha_V}$ and $\Sigma^q_{\alpha_V}$ fixed at the optimized values obtained for the current model, and consider just one step of a variational algorithm for maximizing the variational lower bound in the new model with respect to the parameters $\mu^q_{\beta_j}, (\sigma^q_{\beta_j})^2$. In effect for our variational lower bound (4), we are assuming that the variational posterior distribution for $(\beta_C^T, \beta_j)^T$ is normal with mean $(\mu^q_{\beta_C}, \mu^q_{\beta_j})^T$ and covariance matrix

$$\begin{bmatrix}
\Sigma^q_{\beta_C} & 0 \\
0 & (\sigma^q_{\beta_j})^2
\end{bmatrix}.$$

Substituting these forms into (4) and further assuming $\mu^0_{\beta} = 0$, $\mu^0_{\alpha} = 0$, $\Sigma^0_{\beta} = \sigma^2_{\beta} I$ and $\Sigma^0_{\alpha} = \sigma^2_{\alpha} I$ (see the remarks at the end of Sect. 2), we obtain the lower bound

$$L = L_{\text{old}} + \frac{1}{2} \frac{1}{\sigma^2_{\beta}} \log \left( \frac{(\sigma^q_{\beta_j})^2}{\sigma^2_{\beta}} \right) - \frac{(\sigma^q_{\beta_j})^2}{2\sigma^2_{\beta}} - \frac{(\mu^q_{\beta_j})^2}{2\sigma^2_{\beta}} \sum_{i=1}^{n} x_{ij}^2 (\sigma^q_{\beta_j})^2 + x_{ij}^2 (\mu^q_{\beta_j})^2 - 2x_{ij} (\mu^q_{\beta_j}) (y_i - x_{ij}^T \mu^q_{\beta_C}),$$

where $L_{\text{old}}$ is the previous lower bound for the current model without predictor $j$. Here we are writing $x_{ij}$ for the value of predictor $j$ for observation $i$. Optimizing the above bound with respect to $\mu^q_{\beta_j}$ and $(\sigma^q_{\beta_j})^2$ and writing $\hat{\mu}^q_{\beta_j}$ and $(\hat{\sigma}^q_{\beta_j})^2$ for the optimizers gives

$$\hat{\mu}^q_{\beta_j} = \left( \frac{n}{\sigma^2_{\beta}} + \sum_{i=1}^{n} \frac{x_{ij}^2}{\exp(z_{Vi}^T \mu^q_{\alpha_V} - 1/2 z_{Vi}^T \Sigma^q_{\alpha_V} z_{Vi})} \right)^{-1} \sum_{i=1}^{n} x_{ij} (y_i - x_{ij}^T \mu^q_{\beta_C}) \exp(z_{Vi}^T \mu^q_{\alpha_V} - 1/2 z_{Vi}^T \Sigma^q_{\alpha_V} z_{Vi})$$

and

$$(\hat{\sigma}^q_{\beta_j})^2 = \left( \frac{n}{\sigma^2_{\beta}} + \sum_{i=1}^{n} \frac{x_{ij}^2}{\exp(z_{Vi}^T \mu^q_{\alpha_V} - 1/2 z_{Vi}^T \Sigma^q_{\alpha_V} z_{Vi})} \right)^{-1}.$$

Substituting these back into the lower bound (10) gives

$$L_{\text{old}} + \frac{1}{2} \frac{1}{\sigma^2_{\beta}} \log \left( \frac{(\hat{\sigma}^q_{\beta_j})^2}{\sigma^2_{\beta}} \right) + \frac{1}{2} \left( \frac{\hat{\mu}^q_{\beta_j}}{\sigma^q_{\beta_j}} \right)^2.$$

If the variance model contains only an intercept, this result agrees with greedy selection algorithms where predictors are ranked according to the correlation between a predictor and the residuals from the current model (see, e.g. Zhang 2009). We will discuss this point in detail in Sect. 3.5. Later we write the optimized value of (10) as $L^M(C, V)$, the superscript $M$ means the lower bound associated with the model for mean.

### 3.2 Ranking predictors in the variance model

So far we have considered only the addition of a predictor in the mean model. We now attempt a similar analysis of the effect of inclusion of a predictor in the variance model. With the mean model fixed, suppose that we are considering adding a predictor $z_j$, $j \in E \setminus V$, to the variance model. We consider a normal approximation to the posterior $q(\theta) = q(\beta_C)q(\alpha_V)q(\alpha_j)$ with $q(\beta_C) = N(\mu^q_{\beta_C}, \Sigma^q_{\beta_C})$, $q(\alpha_V) = N(\mu^q_{\alpha_V}, \Sigma^q_{\alpha_V})$ and $q(\alpha_j) = N(\mu^q_{\alpha_j}, (\sigma^q_{\alpha_j})^2)$.

The variational lower bound is

$$L_{\text{old}} + \frac{1}{2} \frac{1}{\sigma^2_{\alpha}} \log \left( \frac{(\sigma^q_{\alpha_j})^2}{\sigma^2_{\alpha}} \right) - \frac{(\sigma^q_{\alpha_j})^2}{2\sigma^2_{\alpha}} - \frac{(\mu^q_{\alpha_j})^2}{2\sigma^2_{\alpha}} \sum_{i=1}^{n} z_{ij}^2 (\mu^q_{\beta_C}).$$


\[-\frac{1}{2} \sum_{i=1}^{n} \left\{ \frac{1}{\exp(z_{ij}^T \mu_{V}^q - \frac{1}{2} z_{ij}^T \Sigma_{V}^q z_{ij})} \right\} - \frac{1}{\exp(z_{ij1}^T \mu_{V}^q - \frac{1}{2} z_{ij1}^T \Sigma_{V}^q z_{ij1})} \right\} \] 

\[\times \left( (y_i - x_{Ci}^T \mu_{PC}^q)^2 + x_{Ci}^T \Sigma_{PC}^q x_{Ci} \right), \tag{14}\]

where \(L_{\text{old}}\) is the lower bound for the current model without predictor \(z_j\). To obtain good values for \(\hat{\mu}_{qj}^q\) and \((\sigma_{qj}^2)\), we use an approximation similar to the one used for the variance parameters in Sect. 2. If we do not assume a normal form for \(q(\alpha_j)\) but just the factorization \(q(\theta) = q(\beta_C)q(\alpha_V)q(\alpha_j)\) and with the current \(q(\beta_C)\) and \(q(\alpha_V)\) fixed, then the optimal \(q(\alpha_j)\) is

\[q(\alpha_j) \propto \exp(E(\log p(\alpha_j) + \log p(\gamma|\theta))),\]

where the expectation is with respect to \(q(\beta_C)q(\alpha_V)\). We have that

\[E(\log p(\alpha_j) + \log p(\gamma|\theta)) = E \left( -\frac{1}{2} \log 2\pi - \frac{1}{2} \log \sigma_{\alpha}^2 - \frac{\alpha_j^2}{2\sigma_{\alpha}^2} - \frac{n}{2} \log 2\pi \right.\]

\[\left. - \frac{1}{2} \sum_{i=1}^{n} z_{ij1}^T \alpha_V - \frac{1}{2} \sum_{i=1}^{n} z_{ij} \alpha_j \right.\]

\[\left. - \frac{1}{2} \sum_{i=1}^{n} \exp(z_{ij1}^T \alpha_V + z_{ij} \alpha_j) \right) \]

\[= -\frac{1}{2} \log 2\pi - \frac{1}{2} \log \sigma_{\alpha}^2 - \frac{\alpha_j^2}{2\sigma_{\alpha}^2} - \frac{n}{2} \log 2\pi \]

\[\left. - \frac{1}{2} \sum_{i=1}^{n} z_{ij1}^T \mu_{V}^q - \frac{1}{2} \sum_{i=1}^{n} z_{ij} \alpha_j \right.\]

\[\left. - \frac{1}{2} \sum_{i=1}^{n} \exp(z_{ij1}^T \mu_{V}^q + z_{ij} \alpha_j - \frac{1}{2} \Sigma_{V}^q z_{ij1} \alpha_j) \right), \tag{15}\]

We make a normal approximation \(N(\hat{\mu}_{qj}^q, (\sigma_{qj}^q)^2)\) to the optimal \(q(\alpha_j)\) via the mode and negative inverse second derivative of (15). Differentiating with respect to \(\alpha_j\), we obtain

\[-\frac{\alpha_j}{\sigma_{\alpha}^2} - \frac{1}{2} \sum_{i=1}^{n} z_{ij} + \frac{1}{2} \sum_{i=1}^{n} \frac{z_{ij} v_{i}}{\exp(z_{ij} \alpha_j)} \]

where \(v_{i} = \frac{(y_i - x_{Ci}^T \mu_{PC}^q)^2 + x_{Ci}^T \Sigma_{PC}^q x_{Ci}}{\exp(z_{ij1}^T \mu_{V}^q - \frac{1}{2} z_{ij1}^T \Sigma_{V}^q z_{ij1})} \)

Approximating \(\exp(-z_{ij} \alpha_j) \approx 1 - z_{ij} \alpha_j\) (i.e. using a Taylor series expansion about zero), setting the derivative to zero and solving gives

\[\hat{\mu}_{qj}^q = \left( \frac{1}{2} \sum_{i=1}^{n} z_{ij} (v_{i} - 1) \right) / \left( \frac{1}{\sigma_{\alpha}^2} + \frac{n}{2} \Sigma_{V}^q \right). \tag{16}\]

To get more accurate estimation of the mode, some optimization procedure may be used here with (16) used as an initial point. In our R implementation, the Newton method was used because (15) has its second derivative available in a closed form (see (17) below). We found that (16) is a very good approximation as the Newton iteration very often stops after a small number of iterations (with a stopping tolerance as small as \(10^{-10}\)).

Differentiating (15) once more, and finding the negative inverse of the second derivative at \(\hat{\mu}_{qj}^q\) gives

\[(\sigma_{qj}^q)^2 = \left( \frac{1}{\sigma_{\alpha}^2} + \frac{n}{2} \Sigma_{V}^q \right)^{-1} \left( \frac{2 \sum_{i=1}^{n} z_{ij}^2 v_{i}}{\exp(z_{ij1} \alpha_j)} \right). \tag{17}\]

We can plug these values back into the lower bound in order to rank different predictors for inclusion in the variance model. Once again we note the computationally thrifty nature of the calculations. We write the optimized value of (14) as \(L_j^D(C, V)\), the superscript \(D\) means the lower bound associated with the model for standard deviance.

3.3 Summary of the algorithm

We summarize our variable selection algorithm below. We write \(L(C, V)\) for the optimized value of the lower bound (4) with the predictor set \(C\) in the mean model and the predictor set \(V\) in the variance model. Write \(C+\) for the set \(C \cup \{j\}\) and \(V_+\) for the set \(V \cup \{j\}\).

**Algorithm 2** Variational approximation ranking (VAR) algorithm

1. Initialize \(C\) and \(V\) and set \(L_{\text{opt}} := L(C, V)\).
2. Repeat the following steps until stop
   (a) Store \(C_{\text{old}} := C\), \(V_{\text{old}} := V\).
   (b) Let \(j^* := \arg \max_j \{L_j^M(C, V) + \log p(C_{+j}, V)\}\). If \(L_j^M + \log p(C_{+j}, V) > L_{\text{opt}} + \log p(C, V)\) then set \(C := C_{+j}\), \(L_{\text{opt}} := L(C_{+j}, V)\).
   (c) Let \(j^* := \arg \max_j \{L_j^D(C, V) + \log p(C_{+j}, V_{+j})\}\). If \(L_j^D + \log p(C_{+j}, V_{+j}) > L_{\text{opt}} + \log p(C, V)\) then set \(V := V_{+j}\), \(L_{\text{opt}} := L(C, V_{+j})\).
   (d) If \(C = C_{\text{old}}\) and \(V = V_{\text{old}}\) then stop, else return to (a).

3.4 Forward-backward ranking algorithm

The ranking algorithm described above can be regarded as a forward greedy algorithm because it considers adding at each step another predictor to the current model. Hereafter
we refer to this algorithm as forward variational ranking algorithm or fVAR in short. Like the other forward greedy algorithms that have been widely used in many scientific fields, the fVAR works well in most of the examples that we have encountered. However, a major drawback with the forward selection algorithms is that if a predictor has been wrongly selected then it cannot be removed anymore. A natural remedy for this is to add a backward elimination process in order to correct mistakes made in the earlier forward selection. We present here a recipe for ranking predictors for exclusion in the mean and variance models.

Let $C$, $V$ be the current sets of predictors in the mean and variance models respectively. With $j \in C$, we write $C_{-j}$ for the set $C \setminus \{j\}$ and consider now the effect of removing the predictor $x_j$ to the lower bound. In order to reduce computational burden, we need some way to avoid the need to do lower bound maximization for each model $C_{-j}$ when ranking $x_j$ for exclusion. Similar as before, we consider a variational approximation using the factorization (9) for the variational posterior distribution. Following steps (10)–(13), we can approximately write the lower bound for the current model (i.e. the model contains $x_j$) as the sum of the lower bound for the model without $x_j$ and a $x_j$-based term

$$L(C, V) \approx L(C_{-j}, V) + \Gamma_{C_{-j}, V}^M(j),$$

(18)

with

$$\Gamma_{C_{-j}, V}^M(j) := \frac{1}{2} \log \left( \frac{\hat{\sigma}_j^q}{\sigma_j^q} \right)^2 + \frac{1}{2} \frac{(\hat{\mu}_{aj}^q)^2}{\sigma_a^2} - \frac{(\hat{\mu}_{aj}^q)^2}{2\sigma_a^2},$$

(19)

where $\hat{\mu}_{aj}^q$, $\hat{\sigma}_j^q$ are as in (11) and (12) with $C$ replaced by $C_{-j}$. All the relevant quantities needed in the calculation of $\Gamma_{C_{-j}, V}^M(j)$ are fixed at optimized values maximizing the lower bound for the current model. The subscripts $C_{-j}$, $V$ emphasize that the quantities needed are adjusted correspondingly when the predictor $j$ is removed from the mean model. The most plausible candidate for exclusion from the current mean model then is

$$j^* = \text{argmax}_{j \in C} \{L(C_{-j}, V) + \log p(C_{-j}, V)\}$$

$$= \text{argmin}_{j \in C} \{\Gamma_{C_{-j}, V}^M(j) - \log p(C_{-j}, V)\}. \quad (20)$$

We now rank the predictors for exclusion in the variance model. Following the arguments in Sect. 3.2 and the above, we can write

$$L(C, V) \approx L(C_{-j}, V_{-j}) + \Gamma_{C, V_{-j}}^D(j),$$

(21)

with

$$\Gamma_{C, V_{-j}}^D(j) := \frac{1}{2} \log \left( \frac{\hat{\sigma}_j^q}{\sigma_j^q} \right)^2 - \frac{(\hat{\mu}_{aj}^q)^2}{2\sigma_a^2},$$

(22)

where $\hat{\mu}_{aj}^q$, $\hat{\sigma}_j^q$ are as in (16)–(17) with $V$ replaced by $V_{-j}$. The most plausible candidate for exclusion from the current variance model then is

$$j^* = \text{argmax}_{j \in V} \{L(C, V_{-j}) + \log p(C, V_{-j})\}$$

$$= \text{argmin}_{j \in V} \{\Gamma_{C, V_{-j}}^D(j) - \log p(C, V_{-j})\}. \quad (23)$$

Algorithm 3 Forward-backward variational approximation ranking algorithm

1. Initialize $C$ and $V$, and set $L_{\text{opt}} = L(C, V)$.
2. Forward selection: as in Step 2 in Algorithm 2.
3. Backward elimination: Repeat the following steps until stop
   (a) Store $C_{\text{old}} := C$, $V_{\text{old}} := V$.  
   (b) Find $j^*$ as in (20). If $L(C_{-j^*}, V) + \log p(C_{-j^*}, V) > L_{\text{opt}} + \log p(C, V)$ then set $C = C_{-j^*}$, $L_{\text{opt}} = L(C_{-j^*}, V)$. 
   (c) Find $j^*$ as in (23). If $L(C, V_{-j^*}) + \log p(C, V_{-j^*}) > L_{\text{opt}} + \log p(C, V)$ then set $V = V_{-j^*}$, $L_{\text{opt}} = L(C, V_{-j^*})$. 
   (d) If $C = C_{\text{old}}$ and $V = V_{\text{old}}$ then stop, else return to (a).

Hereafter we refer to this algorithm as fbVAR.

In some applications where $X \equiv Z$, it might be meaningful to restrict the search for inclusion in the variance model to those predictors that have been included in the mean model. To this end, in the forward selection we just need to restrict the search for the most plausible candidate $j^*$ in Step 2(c) of Algorithm 2 to set $C$, i.e. $j^* = \text{argmax}_{j \in C} \{L_D^D(C, V) + \log p(C, V_j)\}$. Also, when considering the removal of a candidate $j$ from the mean model in the backward elimination, we need to remove $j$ from the variance model as well if $j \in V$, i.e. Step 3(b) of Algorithm 3 must be modified to

3(b') Let $j^* = \text{argmin}_{j \in C} \{\Gamma_{C_{-j}, V_{-j}}^M(j) - \log p(C_{-j}, V_{-j})\}$. If $L(C_{-j^*}, V_{-j^*}) + \log p(C_{-j^*}, V_{-j^*}) > L_{\text{opt}} + \log p(C, V)$ then set $C = C_{-j^*}$, $V = V_{-j^*}$, $L_{\text{opt}} = L(C_{-j^*}, V_{-j^*})$. 

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Later we compare with the variable selection approaches for heteroscedastic regression implemented in the GAMLSS (generalized additive model for location, scale and shape) package (Rigby and Stasinopoulos 2005). The GAMLSS framework allows to model the mean and other parameters (like the standard deviation, skewness and kurtosis) of the response distribution as flexible functions of predictors. Variable selection is done with stepwise selection using a generalized AIC or BIC as the stopping rule. The GAMLSS uses a Fisher scoring algorithm to maximize the likelihood for ranking every predictor for inclusion/exclusion rather than only the most plausible one as in the VAR algorithm, which leads to a heavy computational burden for large-\( p \) problems.

3.5 The ranking algorithm for homoscedastic regression

In order to get more insight into our VAR algorithm, we discuss in this section the algorithm for the homoscedastic linear regression model. In the case of constant variance, the variance parameter \( \alpha \) now becomes scalar, we rename the quantities \( \Sigma_0^0, \Sigma_\alpha^0 \) as \( (\sigma^0_\alpha)^2, (\sigma^q_\alpha)^2 \) respectively. The optimal choice (5) for \( p(\alpha) \) becomes

\[
q(\alpha) \propto \exp \left( -\frac{n}{2} \alpha - \frac{1}{2} v e^{-\alpha} - \frac{1}{2} \frac{\alpha^2}{(\sigma^0_\alpha)^2} \right)
\]

where \( v := \sum_{i=1}^{n} \left( x_i^T \mu_q^\alpha \right)^2 + x_i^T \Sigma_\alpha^q x_i \).

Using the approximation \( \exp(-\alpha) \approx 1 - \alpha \), it is easy to see that the mean and variance of the normal approximation are

\[
\mu_q^\alpha = \frac{v - n}{v + 2/(\sigma^0_\alpha)^2} \quad \text{and} \quad (\sigma_q^\alpha)^2 = \left( \frac{v}{2} e^{-\mu^\alpha_q} + \frac{1}{(\sigma^0_\alpha)^2} \right)^{-1}
\]

respectively. We now can replace Steps 4 and 5 in Algorithm 1 by these two closed forms so that the computations can be reduced greatly. Similar to the discussion in Sect. 3.2, the Newton method may be used here in order to get a more accurate estimate of the mode. In our experience, however, this is not necessary here.

For the variable selection problem, we now just need to rank the predictors for inclusion/exclusion in the mean model. Assume that we are using the uniform model prior, i.e. \( p(C, V) \equiv \text{constant} \), or a model prior as in (7), the ranking of predictors then follows the ranking of lower bounds. We further assume that the design matrix \( X \) has been standardized such that \( \sum_j x^2_j = n \), the optimizer \( (\sigma^0_j)^2 \) in (12) does not depend on \( j \), and the ranking of the lower bound (13) follows the ranking of \( | \sum_{i=1}^{n} x_{ij} (y_i - \mu^\alpha_q C_j) | \) (i.e. it follows the ranking of the absolute correlation of the predictors with the standardized residuals from the current model). This result agrees with frequentist matching pursuit and greedy algorithms where predictors are ranked according to the correlation between a predictor and the residuals from the current model (Mallat and Zhang 1993; Zhang 2009; Efron et al. 2004). This is also similar to computationally thrifty path following algorithms (Efron et al. 2004; Zhao and Yu 2007).

For the existing frequentist algorithms for variable selection, extra tuning parameters, such as the shrinkage parameter in penalization procedures, the number of iterations in matching pursuit and the stopping parameter \( \epsilon \) in greedy algorithms, need to be chosen. And their performance depends critically on the method used to choose these tuning parameters. Our method does not require any extra tuning parameters. The final model is chosen when the lower bound (plus the log model prior) is maximized—a widely used stopping rule in Bayesian model selection with variational Bayes (Beal and Ghahramani 2003, 2006).

Unlike many commonly used greedy algorithms, our Bayesian framework is able to incorporate prior information (if available) on models and/or to encourage parsimonious models if desired. Besides involving extra tuning parameters, penalized estimates are often biased (Friedman 2008; Efron et al. 2004). While our method can penalize non-zero coefficients through the prior if desired, it does not rely on shrinkage of coefficients to do variable selection, so that in principle it might produce better estimation of non-zero coefficients. Simulation studies in Sect. 5 confirm this point. Note that we do not consider models of all sizes, the algorithm stops when important predictors have been included in the model, so that computations in Algorithm 1 just involve matrices with low-dimension. This is another advantage which makes our method potentially valuable for variable selection in high-dimensional problems. Our experience shows that the VAR algorithm is as fast as the LARS algorithm in problems with thousands of predictors.

4 Applications

Example 1 (Biscuit dough data) The biscuit dough data is a benchmark “large \( p \), small \( n \)” data set that was originally designed and analyzed in Osborne et al. (1984). The purpose of this study was to investigate the practical benefit of using near-infrared (NIR) spectroscopy in the food processing industries. In their experiment, the aim was to predict biscuit dough constituents based on near-infrared spectrum of dough samples. The four constituents of interest were fat, sucrose, flour and water. Two data sets (training set \( D^T \) and prediction or validation set \( D^F \)) were made up in the same manner in which the percentages of four constituents were exactly calculated. These percentages serve as response variables. There were 39 samples in the training set and 31 in the prediction set. The NIR spectrum of
dough pieces was measured at equally spaced wavelengths from 1100 to 2498 nanometers (nm) in steps of 2 nm. Following Brown et al. (2001), we removed the first 140 and last 49 wavelengths because they were thought to contain little useful information. From remaining wavelengths ranging from 1380 to 2400 nm, every second wavelength was considered, which increases the step size to 4 nm. The final data sets consist of 256 predictors and four responses which were treated separately in four univariate linear regression models rather than in a single multivariate model.

The most popular and easiest way to check heteroscedasticity is to use plotting techniques. When the OLS fit is valid, plotting studentized residuals against fitted values is a powerful technique to use (Carroll and Ruppert 1988). In our current case of “large p, small n”, we first used the adaptive Lasso (aLasso) of Zou (2006) to select likely predictors and then applied the above technique to the selected predictors. We name this method aLasso-OLS. Figure 2 shows the plots of aLasso-OLS studentized residuals versus fitted values (where homoscedasticity was assumed), and also the corresponding plots resulting from our fbVAR algorithm\(^1\) (where heteroscedasticity was assumed) for the response variables sucrose \((Y_2)\) and water \((Y_4)\); all were calculated based on the training set. The plots for the other responses were not shown because the need for a heteroscedastic model was not visually obvious. We can see that in general fitting the homoscedastic regression model to these responses was not appropriate here. Looking at the aLasso-OLS plot for \(Y_4\), for example, there was clear evidence that (absolute values of) residuals decrease when fitted values increase, and the heteroscedastic model estimated by the VAR method gave a more satisfying residual plot. For the response \(Y_2\), the VAR did not select any predictor (except the intercept) for inclusion in the mean model, although several predictors were selected for the variance model. This “non-null” variance model reflects the heteroscedasticity which is visualizable in the aLasso-OLS plot for \(Y_2\). The null model for the mean model was quite a surprise, since all the works analyzing \(Y_2\) assuming the homoscedastic linear model that we are aware of in the literature reported non-null models. The aLasso in our analysis selected only one predictor, the 130th. Among the plots of all 4 responses against all selected predictors, the plot of \(Y_2\) against the selected predictor (by the aLasso of course) looked very random compared to the others. This in some sense supported visually the null model for \(Y_2\).

\(^1\)We did not apply the restriction here, because there was no good reasons to restrict the search for inclusion in the variance model to the predictors in the mean model. The search combined both forward and backward moves and the uniform model prior (i.e. \(\pi_{\mu} = \pi_{\sigma} = 1/2\)) was used.

We then employed the resulting models to make predictions and used the validation set \(D^v\) to examine the appropriateness of assuming heteroscedasticity for this biscuit dough data. The usefulness of a model was measured by two criteria: one was the mean squared error of prediction defined as

\[
\text{MSE} = \frac{1}{|D^v|} \sum_{(x,y) \in D^v} \| y - \hat{y}(x) \|^2
\]

and the other was the partial prediction score

\[
\text{PPS} = \frac{1}{|D^v|} \sum_{(x,y) \in D^v} -\log \hat{p}(y|x),
\]

where \(\hat{p}(.)\) is the density estimated under the model. It is understood that the smaller the MSE and PPS, the better the model. The MSE and PPS evaluated on the 31 samples of the validation set for the aLasso and VAR methods are summarized in Table 1. Except for the case of \(Y_2\) (sucrose), the heteroscedastic models estimated by the VAR method had a big improvement over the homoscedastic models estimated by the aLasso. The poor predictive performance of the VAR (and the aLasso as well) on \(Y_2\) was probably due to the reasons discussed above: there was no linear relationship between the NIR spectrum and the sucrose constituent.

This biscuit dough data was also carefully analyzed in Brown et al. (2001) using a Bayesian wavelet regression framework. They first used a wavelet transformation to transform the original predictors to wavelet coefficients and then applied a Bayesian (homoscedastic) regression approach to regress the responses on the derived wavelet coefficients. Prediction was done using Bayesian model averaging (BMA) over a set of 500 likely models, and MSE values were reported to be 0.06, 0.45, 0.35 and 0.05 respectively. This methodology seems not comparable to ours because (i) it was conducted based on wavelet coefficients rather than the original predictors and (ii) prediction was done using BMA rather than a single selected model.

Because the four response variables are percentages and sum to 100, an anonymous reviewer raised a concern about spurious correlations between them. While this may be a concern for a multivariate analysis, we treated the four responses separately in four univariate linear regression models rather than in a single multivariate model, so that compositional effects would not be a problem here. To justify this, we considered the following transformation (Aitchison 1986) of the responses

\[
U_i = \log \frac{Y_i}{Y_3}, \quad i = 1, 2, 4.
\]

The choice of \(Y_3\) for denominator was natural because the flour is a major constituent (Brown et al. 2001). After fitting the regression models with these three new responses,
Stat Comput (2012) 22:497–512

The fitted and predicted values were transformed back to the original scale via

\[ Y_i = \frac{100 \exp(U_i)}{\sum \exp(U_i) + 1}, \quad i = 1, 2, 4 \]

and

\[ Y_3 = \frac{100}{\sum \exp(U_i) + 1}. \]

The MSE evaluated on the validation set for the aLasso were 4.71, 13.43, 7.07, 1.45 and for the VAR method were 2.16, 5.22, 3.36, 0.57. We did not report PPS because it is not clear how to properly calculate PPS in the case of heteroscedastic regression for such transformed data. Comparing to the result in Table 1, it seems that the above transformation which is to account for potential compositional effects does not give a positive impact overall. This result also agrees with the analysis of Brown et al. (2001).

Example 2 (diabetes data) In the second application we applied the VAR method to analyzing a benchmark data set on progression of diabetes (Efron et al. 2004). Ten baseline variables, age, sex, body mass index, average blood pressure and six blood serum measurements, were obtained for each of \( n = 442 \) diabetes patients, as well as the response of interest \( y \), a quantitative measure of disease progression one year after baseline. We constructed a (heteroscedastic, if necessary) linear regression model to predict \( y \) from these ten input variables. In the hope of improving prediction accuracy, we considered a “quadratic model” with 64 predictors. We distinguish between input variables and predictors, for example, in a quadratic regression model on two input variables age and income, there are five predictors (age, income, age × age, income × income and age × income).

The analysis of the full data set showed clear evidence of heteroscedasticity. See again Fig. 1 for the solution paths resulting from our VAR algorithm with the uniform model.
prior (where only forward selection was implemented and the search for inclusion in the variance model was restricted). The VAR and GAMLSS both selected some predictors to include in the variance model. Furthermore, there was quite a clear pattern in the plot of the OLS studentized residuals indicating heteroscedasticity (results not shown). Interestingly, when fitting \( y \) with only ten input variables as the predictors, diagnostics and the selected model by VAR both showed no evidence of heteroscedasticity. This result agreed with the homoscedasticity assumption often used for this diabetes data set.

To assess predictive performance, we randomly selected 300 instances to form the training set, with the remainder serving as the validation set. Of 64 predictors, the VAR selected 13 to include in the mean model and 12 to include in the variance model, while the GAMLSS selected 23 and 7 respectively. Under the assumption of constant variance, the aLasso selected 43 predictors. On the validation set, the models estimated by aLasso, GAMLSS and VAR had PPS of 5.50, 15.93, 5.41 and MSE of 3264.95, 3506.32, 2993.16 respectively. In order to reduce the uncertainty in training-validation separation, we recorded the MSE and PPS over 50 such random partitions, and obtained the averaged MSE for aLasso, GAMLSS and VAR of 3715.08 (641.56), 4069.81 (1681.70), 3082.78 (774.85) and the averaged PPS of 5.84 (0.15), 56.72 (11.52), 5.76 (0.16) respectively. The numbers in brackets are standard deviations. The GAMLSS method performed poorly in this example but it should be stressed that we have only used the default implementation (i.e. stepwise selection with both forward and backward moves and the generalized AIC used as the stopping rule) in the GAMLSS R package. Further experimentation with tuning parameters in the information criterion might produce better results.

5 Experimental studies

In this section, we present experimental studies for our method. We first compare the accuracy of our variational approximation algorithm to that of MCMC in approximating a posterior distribution. We then compare the VAR method for variable selection to the aLasso and GAMLSS in both heteroscedastic and homoscedastic regression. In the examples described below, the EBIC prior (8) was used as a default prior. This prior has very little impact in low-dimensional cases but considerable impact in high-dimensional cases in terms of encouraging parsimony (Chen and Chen 2008).

The accuracy of the variational approximation In this example we demonstrate the accuracy of the variational approximation for describing the posterior distribution in a heteroscedastic model, without considering the model selection aspects. We considered a data set described in Weisberg (2005), see also Smyth (1989). The data were concerned with the hydrocarbon vapours which escape when petrol is pumped into a tank. Petrol pumps are fitted with vapour recovery systems, which may not be completely effective and “sniffer” devices are able to detect if some vapour is escaping. An experiment was conducted to estimate the efficiency of vapour recovery systems in which the amount of hydrocarbon vapour given off, in grams, was measured, along with four predictor variables. The four predictor variables were initial tank temperature \((x_1)\), in degrees Fahrenheit, the temperature of the dispensed gasoline \((x_2)\), in degrees Fahrenheit, the initial vapour pressure in the tank \((x_3)\), in pounds per square inch, and the initial vapour pressure of the dispensed gasoline \((x_4)\), in pounds per square inch. Smyth (1989) considers fitting a heteroscedastic linear model with the mean model

\[
\mu = \beta_1 g_1 + \beta_2 g_2 + \beta_3 g_3 + \beta_4 x_2 + \beta_5 g_1 x_4 + \beta_6 g_3 x_4
\]

and the variance model

\[
\log \sigma^2 = \alpha_0 + \alpha_1 x_2 + \alpha_2 x_4,
\]

where \(g_1\), \(g_2\) and \(g_3\) are three binary indicator variables for different ranges of \(x_1\) and \(g_{12} = g_1 + g_2\). In fitting the mean model the last three terms are orthogonalized with respect to the first three, so that the coefficients of the indicators are simply group means for the corresponding subsets of \(x_1\), and in the variance model \(x_2\) and \(x_4\) were mean centered. We considered our variational approximation to the posterior distribution in a Bayesian analysis where the priors were multivariate normal with mean zero and covariance 10000I for both \(\beta\) and \(\alpha\). Figure 3 shows estimated marginal posterior densities for all parameters in the mean and variance models. The top two rows show the mean parameters and the bottom row the variance parameters. The solid lines are kernel density estimates of the marginal posteriors constructed from MCMC samples and the dotted lines are the variational approximate posterior marginals. The mean and variance from the variational approximation were used to define a multivariate Cauchy independence proposal for a Metropolis-Hastings scheme to generate the MCMC samples. 100,000 iterations were drawn, with 1,000 discarded as "burn in". One can see that for the mean parameters, the variational approximation is nearly exact. For the variance parameters, point estimation is very good, but there is a slight tendency for the variational approximation to underestimate posterior variances. The final lower bound is \(-326.68\), with agreement to two decimal places within the first two iterations and convergence after 5 iterations. Compared to \(-326.5\), the marginal likelihood computed using the MCMC method of Chib and Jeliazkov (2001), this lower bound is very tight.
Fig. 3 Estimated marginal posterior densities for coefficients in the mean and variance models for the sniffer data. Solid lines are kernel estimates from MCMC samples from the posterior and dashed lines are variational approximate marginal posterior densities.

Heteroscedastic case We present here a simulation study for our VAR method for simultaneous variable selection and parameter estimation in heteroscedastic linear regression models, and compare its performance to that of the GAMLSS and aLasso methods. Data sets were generated from the model

\[ y = 2 + x^T \tilde{\beta} + \sigma e^{\frac{1}{2} x^T \tilde{\alpha} \epsilon}, \]

with \( \tilde{\beta} = (3, 1.5, 0, 0, 2, 0, 0, 0)^T \), \( \epsilon \sim N(0, 1) \). Predictors \( x \) were first generated from normal distributions \( N(0, \Sigma) \) with \( \Sigma_{ij} = 0.5| i-j | \) and then transformed into the unit interval by the cumulative distribution function \( \Phi(.) \) of the standard normal. The reason for making the transformation was to control the magnitude of noise level, i.e. the quantity \( \sigma e^{\frac{1}{2} x^T \tilde{\alpha} \epsilon} \). Let \( \tilde{\beta} = (2, \tilde{\beta}^T)^T \) and \( \alpha = (\log \sigma^2, \tilde{\alpha}^T)^T \) be the mean and variance parameters respectively, where \( \tilde{\alpha} = (0, 3, 0, 0, -3, 0, 0, 0)^T \). Note that the true predictors in the variance model were among those in the mean model. This prior information was employed in the GAMLSS and VAR.

The performance was measured by correctly-fitted rates (CFR), numbers of zero-estimated coefficients (NZC) (for both mean and variance models), mean squared error (MSE) of predictions and partial prediction score (PPS) averaged over 100 replications. MSE and PPS were evaluated based on independent prediction sets generated in the same manner as the training set. We compared the performance of the VAR and GAMLSS methods (when heteroscedasticity was assumed) to that of the aLasso (when homoscedasticity was assumed). The simulation results are summarized in Table 2 for various factors sample size \( n \), \( n_P \) (size of prediction sets \( D^P \)) and \( \sigma \). As shown, the VAR method did a good job and outperformed the others.

We also considered a “large \( p \), small \( n \)” case in which \( \tilde{\beta} \) and \( \tilde{\alpha} \) in model (24) were vectors of dimension 500 with most of the components zero except \( \tilde{\beta}_{50} = \tilde{\beta}_{100} = \).
Table 2 Small-\(p\) case: CFR, NZC, MSE and PPS averaged over 100 replications. The numbers in parentheses are NZC. The true number of non-zero coefficients in the mean model was 5 and in the variance model was 6.

| \(n = n_P\) | \(\sigma\) | \(\alpha\) | aLasso | GAMLSS | VAR  |
|-----------|---------|---------|--------|--------|------|
| 50        | 0.5     | CFR in mean | 64 (4.56) | 36 (4.06) | 80 (4.88) |
|           |        | CFR in var. | nil | 70 (5.74) | 80 (5.96) |
|           |        | MSE       | 0.56 | 0.49 | 0.48 |
|           |        | PPS       | 1.17 | 0.89 | 0.87 |
| 1         |        | CFR in mean | 22 (4.72) | 38 (4.60) | 56 (5.00) |
|           |        | CFR in var. | nil | 50 (5.88) | 60 (6.22) |
|           |        | MSE       | 2.45 | 2.29 | 2.24 |
|           |        | PPS       | 2.01 | 1.78 | 1.69 |
| 100       | 0.5     | CFR in mean | 74 (4.50) | 30 (3.98) | 88 (4.84) |
|           |        | CFR in var. | nil | 64 (5.62) | 90 (5.90) |
|           |        | MSE       | 0.52 | 0.48 | 0.48 |
|           |        | PPS       | 1.12 | 0.87 | 0.77 |
| 1         |        | CFR in mean | 36 (4.68) | 42 (4.30) | 66 (4.76) |
|           |        | CFR in var. | nil | 58 (5.72) | 76 (5.84) |
|           |        | MSE       | 2.20 | 2.08 | 2.03 |
|           |        | PPS       | 1.83 | 1.62 | 1.51 |
| 200       | 0.5     | CFR in mean | 94 (4.90) | 48 (4.14) | 100 (5.00) |
|           |        | CFR in var. | nil | 70 (5.70) | 94 (5.94) |
|           |        | MSE       | 0.48 | 0.46 | 0.46 |
|           |        | PPS       | 1.06 | 0.87 | 0.74 |
| 1         |        | CFR in mean | 56 (4.36) | 36 (4.06) | 88 (4.88) |
|           |        | CFR in var. | nil | 82 (5.80) | 100 (6.00) |
|           |        | MSE       | 2.01 | 1.93 | 1.92 |
|           |        | PPS       | 1.77 | 1.52 | 1.42 |

Table 3 Large-\(p\) case: CFR, NZC, MSE and PPS averaged over 100 replications. The numbers in parentheses are NZC. The true number of non-zero coefficients in the mean model was 490 and in the variance model was 496.

| \(n = n_P\) | \(\sigma\) | \(\alpha\) | \(\text{VAR}\) | aLasso |
|-----------|---------|---------|----------------|--------|
|           |         | CFR in mean | 80 (489.75) | 90 (495.90) | 5.40 | 1.91 | 20 (491.80) | 11.65 | 2.66 |
| 100       | 0.5     | CFR in var. | 70 (489.05) | 65 (495.80) | 20.29 | 2.31 | 0 (495.75) | 35.11 | 3.28 |
| 150       | 0.5     | MSE       | 100 (490.00) | 95 (495.90) | 13.77 | 0.85 | 40 (491.95) | 20.02 | 3.41 |
| 200       | 1       | PPS       | 95 (489.95) | 85 (495.85) | 28.97 | 1.52 | 5 (495.05) | 43.19 | 3.69 |

\(\cdots = 5\), \(\cdots = 5\), \(\cdots = 5\), \(\cdots = 5\) and \(\cdots = 5\). The simulation results are summarized in Table 3. Note that the GAMLSS is not applicable when \(n < p\), and moreover that in the case with \(n \geq p\) and with large \(p\) the current implementation version of the GAMLSS is much more time consuming compared to the VAR and even not working with \(p\) as large as 500, since the package was not designed for such applications. We are not aware of any existing methods for variable selection in heteroscedastic linear models for “large \(p\), small \(n\)” case.

Homoscedastic case We also considered a simulation study when the data come from homoscedastic models. Data sets were generated from the linear model (24) with \(\tilde{\alpha} \equiv 0\), i.e.

\[ y = 2 + x^T \tilde{\beta} + \sigma \epsilon \]

with predictors \(x\) generated from normal distributions \(N(0, \Sigma)\) with \(\Sigma_{ij} = 0.5^{|i-j|}\). We were concerned with simulating a sparse, high-dimensional case. To this end, \(\tilde{\beta}\) was set to be a vector of 1000 dimensions with the first 5 entries

\(\cdots = 5\), \(\cdots = 5\), \(\cdots = 5\), \(\cdots = 5\) and \(\cdots = 5\).
were 5, −4, 3, −2, 2 and the rest were zeros. We used the modified ranking algorithm discussed in Sect. 3.5 with both forward and backward moves and the default prior (8). The performance was measured as before by CFR, NZC and MSE but MSE was defined as the squared error between the true vector $\hat{\beta}$ and its estimate. The simulation results are summarized in Table 4. The big improvement of the VAR over the aLasso in this example is surprising and probably due to the reasons discussed in Sect. 3.5.

**Remarks on calculations** The VAR algorithm was implemented using R and the code is freely available on the authors’ websites. The weights used in the aLasso were assigned as usual as $1/|\hat{\beta}_j|$ with $\hat{\beta}_j$ being the MLE (when $p < n$) or the Lasso estimate (when $p \geq n$) of $\beta_j$. The tuning parameter $\lambda$ was selected by 5-fold cross-validation. The implementation of the aLasso and GAMLSS was carried out with the help of the R packages glmnet and gamlss.

### 6 Concluding remarks

We have presented in this paper a strategy for variational lower bound maximization in heteroscedastic linear regression, and a novel fast greedy algorithm for Bayesian variable selection. In the homoscedastic case with the uniform model prior, the algorithm reduces to widely used matching pursuit algorithms. The suggested methodology has proven efficient, especially for high-dimensional problems.

Benefiting from the variational approximation approach—a fast deterministic alternative and complement to MCMC methods for computation in high-dimensional problems—our methodology has potential for Bayesian variable selection in more complex frameworks. A potential research direction is to extend the method to simultaneous variable selection and number of experts selection in flexible regression density estimation with mixtures of experts (Geweke and Keane 2007; Villani et al. 2009). This research direction is currently in progress. Another potential research direction is to extend the method to grouped variable selection.

### Appendix A

Below we write $E_q(\cdot)$ for an expectation with respect to the variational posterior. In the notation of Sect. 1 we have

\[
T_1 = \frac{p+q}{2} \log 2\pi - \frac{1}{2} \log |\Sigma^0_{\beta}| - \frac{1}{2} \log |\Sigma^0_{\alpha}| - \frac{1}{2} E_q((\beta - \mu^0_{\beta})^T \Sigma^{-1}_{\beta} (\beta - \mu^0_{\beta})) - \frac{1}{2} E_q((\alpha - \mu^0_{\alpha})^T \Sigma^{-1}_{\alpha} (\alpha - \mu^0_{\alpha})) - \frac{1}{2} \text{tr}(\Sigma^{-1}_{\beta}\Sigma^{-1}_{\alpha}) - \frac{1}{2} \text{tr}(\Sigma^{-1}_{\beta}\Sigma^{-1}_{\alpha}) - \frac{1}{2} (\mu^0_{\beta} - \mu^0_{\alpha}) (\mu^0_{\beta} - \mu^0_{\alpha}) - \frac{1}{2} (\mu^0_{\alpha} - \mu^0_{\beta}) (\mu^0_{\alpha} - \mu^0_{\beta}),
\]

\[
T_2 = - \frac{n}{2} \log 2\pi - \frac{1}{2} E_q \left( \sum_{i=1}^{n} \frac{z_i^T \alpha}{\exp(z_i^T \alpha)} \right) - \frac{1}{2} E_q \left( \sum_{i=1}^{n} \frac{(y_i - x_i^T \beta)^2}{\exp(z_i^T \alpha)} \right) = - \frac{n}{2} \log 2\pi - \frac{1}{2} \sum_{i=1}^{n} z_i^T \mu^0_{\alpha} - \frac{1}{2} \sum_{i=1}^{n} z_i^T \mu^0_{\beta} + \frac{1}{2} \sum_{i=1}^{n} x_i^T \Sigma^{-1}_{\beta} x_i + \frac{1}{2} \sum_{i=1}^{n} (y_i - x_i^T \mu^0_{\beta})^2 \exp(z_i^T \mu^0_{\alpha} - \frac{1}{2} z_i^T \Sigma^{-1}_{\alpha} z_i)
\]

and

\[
T_3 = \frac{p+q}{2} \log 2\pi + \frac{1}{2} \log |\Sigma^q_{\beta}| + \frac{1}{2} \log |\Sigma^q_{\alpha}| + \frac{1}{2} E_q((\beta - \mu^q_{\beta})^T \Sigma^{-1}_{\beta} (\beta - \mu^q_{\beta})) + \frac{1}{2} E_q((\alpha - \mu^q_{\alpha})^T \Sigma^{-1}_{\alpha} (\alpha - \mu^q_{\alpha}))
\]
\[ p + q + \frac{1}{2} \log 2\pi + \frac{1}{2} \log |\Sigma_{\beta}| + \frac{1}{2} \log |\Sigma_{\alpha}| + \frac{p + q}{2}. \]

In evaluating \( T_2 \) above we made use of the independence of \( \beta \) and \( \alpha \) in the variational posterior and of the moment generating function for the multivariate normal variational posterior distribution for \( \alpha \). Putting the terms together, the variational lower bound simplifies to (4).

### Appendix B

Denote by \( W(\alpha) \) the diagonal matrix \( \text{diag}(\frac{1}{2} w_i \exp(-z_i^T \alpha)) \), then

\[
u(\alpha) := \frac{\partial \log q(\alpha)}{\partial \alpha} = -\frac{1}{2} \sum_i z_i + Z^T W(\alpha) - \Sigma_{\alpha}^{-1}(\alpha - \mu_{\alpha})
\]

and

\[
A(\alpha) := \frac{\partial^2 \log q(\alpha)}{\partial \alpha \partial \alpha^T} = -Z^T W(\alpha) Z - \Sigma_{\alpha}^{-1}.
\]

The Newton method for estimating the mode is as follows.

- **Initialization:** Set starting value \( \alpha^{(0)} \).
- **Iteration:** For \( k = 1, 2, \ldots \), update
  \[
  \alpha^{(k)} = \alpha^{(k-1)} + A^{-1}(\alpha^{(k-1)}) \nu(\alpha^{(k-1)})
  \]
  until some stopping rule is satisfied, such as \( \|\alpha^{(k)} - \alpha^{(k-1)}\| < \epsilon \) with some pre-specified tolerance \( \epsilon \).

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