GLOBAL EXISTENCE OF SMALL DISPLACEMENT SOLUTIONS FOR HOOKEAN INCOMPRESSIBLE VISCOELASTICITY IN 3D

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In memory of Bob Glassey,
penetrating mathematician, inspiring teacher, patient mentor, and friend. -T.C.S.

Abstract. The initial value problem for incompressible Hookean viscoelastic motion in three space dimensions has global strong solutions with small displacements.

1. Introduction. This article establishes the global existence of strong solutions to the equations of motion for viscoelastic Hookean incompressible materials in $\mathbb{R}^3$, with small initial displacements. The equations of motion take the form

$$\begin{align*}
\frac{\partial}{\partial t} F + v \cdot \nabla F - \nabla v F &= 0 \quad \text{(1a)} \\
\frac{\partial}{\partial t} v + v \cdot \nabla v + \nabla \pi - \mu \nabla \cdot (FF^T) &= \nu \Delta v \quad \text{(1b)} \\
\nabla \cdot v &= 0, \quad \text{(1c)}
\end{align*}$$

in which $(F, v, \pi) : [0, T) \to \text{SL}(3) \times \mathbb{R}^3 \times \mathbb{R}$ represent the deformation gradient, velocity, and pressure, expressed in spatial coordinates. The central point of this article is that the restriction (3) placed on the size of the initial data $(F - I, v)|_{t=0}$ is to be uniform with respect to the Reynolds number $Re = \nu^{-1} > 1$. This system can also be viewed as the Oldroyd-B model at infinite Weissenberg number with conformation tensor $\sigma = FF^T$ arising in the theory of complex fluids.

Global existence of small displacement solutions for incompressible isotropic elastic materials $(\nu = 0)$ was obtained in [16] and [17]. Thus, the result in this paper establishes the stability of a nonlinear elastodynamic system under a viscous perturbation. Earlier versions of the results in this paper appeared in works of the first two authors [8], [9], [6]. The restriction to Hookean materials is made here only for...
technical simplification. A scalar analog involving a dissipative perturbation of a scalar nonlinear wave equation with nearly null structure was presented in [7].

On the other hand, the system reduces to the Navier-Stokes equations, under the hydrodynamical limit obtained by sending the elastic modulus \( \mu \to 0 \). In \( \mathbb{R}^3 \), the Navier-Stokes equations have a global strong solution for initial velocities which are small relative to \( \nu = \Re^{-1} \), see [10]. Of course, uniformity in \( \nu \) is lost (or at least unknown) for incompressible fluids in 3d, and therefore, one can think of the effect of the tangential component of the elastic stress, which is present only when \( \mu > 0 \), as a kind of elastic regularization. Unsurprisingly then, in this paper the smallness restriction on the initial data is sensitive to the size of \( \mu > 0 \), and this value will be fixed below.

There is an extensive literature on the existence of solutions to the equations of viscoelastic fluids, see for example [1], [2], [3], [4], [5], [11], [12], [13], [14]. However, none of these works examine the question of the uniformity in the Reynolds number.

The proof of the global existence theorem is based on the energy method for symmetric systems using rotational and scaling vector fields. The presence of the elastic stress term implies the local decay of energy inside a forward space-time cone of small aperture, beginning with the analysis of the linearized problem in Proposition 26. The scaling operator is vital in this step. Use of the rotational vector fields in three space dimensions yields strong Sobolev inequalities leading, in turn, to the basic interpolation estimates described in Section 5. For small displacements, the decay of local energy and the interpolation inequalities can be combined to bootstrap the nonlinear terms to obtain the requisite \textit{a priori} bounds for the energy. The precise null structure of the nonlinear terms in the Hookean case is crucial in completing this portion of the argument, see (61).

The challenge is to adapt this essentially hyperbolic method to a dissipative system. The energy provides control of the dissipative quantity \( \nu \int_0^t \| \nabla v(s) \|_{L^2} ds \), however, because the goal is to obtain estimates uniform in \( \nu \), this term, paradoxically, is of little use. In fact, dissipation complicates the local energy estimate by introducing extra terms and requiring an additional time integration in comparison to the case \( \nu = 0 \). The commutation properties of the scaling operator with the linearized operator is also disrupted by the presence of dissipation, see (9a), making it necessary to carefully monitor the use of the scaling operator. Consequently, norms will take into account the total number of derivatives as well as the number of instances of the scaling operator. The associated notation is explained in the next section, followed by a complete statement of the main result, Theorem 3.1. The proof of the theorem will be presented in the remaining sections.

2. Notation. Partial derivatives will be denoted by

\[
\nabla = (\partial_j)_{j=1}^3 \quad \text{and} \quad \partial = (\partial_t, \nabla).
\]

Define the antisymmetric matrices

\[
Z_1 = e_3 \otimes e_2 - e_2 \otimes e_3, \quad Z_2 = e_1 \otimes e_3 - e_3 \otimes e_1, \quad Z_3 = e_2 \otimes e_1 - e_1 \otimes e_2,
\]

where \( \{e_1, e_2, e_3\} \) represents the standard basis in \( \mathbb{R}^3 \). The rotational vector fields \( \Omega_\ell \) are defined as the Lie derivative with respect to the vector fields

\[
\Omega = x \wedge \nabla = (\Omega_\ell)_{\ell=1}^3 = ((Z_\ell x, \nabla))_{\ell=1}^3.
\]

Thus we have

\[
\bar{\Omega}_\ell \pi = \Omega_\ell \pi, \quad \text{for} \quad \pi : \mathbb{R}^3 \to \mathbb{R},
\]
\[ \tilde{\Omega}_t v = \Omega_t v - Z_t v, \quad \text{for} \quad v : \mathbb{R}^3 \to \mathbb{R}^3, \]
\[ \tilde{\Omega}_t F = \Omega_t F - [Z_t, F], \quad \text{for} \quad F : \mathbb{R}^3 \to \mathbb{R}^{3 \times 3}, \]
where \([\cdot, \cdot]\) denotes the commutator of two matrices. We will rely heavily on the decomposition
\[ \nabla = \omega \partial_r - \omega \wedge \Omega, \quad \omega = \frac{x}{r}. \tag{2} \]

We also define the scaling operators
\[ S_0 = \langle x, \nabla \rangle = r \partial_r \quad \text{and} \quad S = t \partial_t + r \partial_r. \]

For a more concise notation we shall write
\[ \Gamma = \{\nabla, \tilde{\Omega}\}. \]

The scaling operators are not included in \(\Gamma\) because their occurrence will be tracked separately as is evident in the following definition of the solution space:
\[ X^{p,q} = \left\{ U = (G, v) : \mathbb{R}^3 \to \mathbb{R}^{3 \times 3} \times \mathbb{R}^3 : \sum_{|a| + k \leq p \atop k \leq q} \| S^k_0 \Gamma^a U(t) \|_{L^2} < \infty \right\} \]
for integers \(0 \leq q \leq p\). This is a Hilbert space with inner product
\[ \langle U_1, U_2 \rangle_{X^{p,q}} = \sum_{|a| + k \leq p \atop k \leq q} \langle S^k_0 \Gamma^a U_1, S^k_0 \Gamma^a U_2 \rangle_{L^2}. \]

Thus, \(p\) indicates the total number of derivatives taken, while \(q\) indicates the number of occurrences of \(S_0\). Here, \(G = F - I\) plays the role of the displacement gradient, and \(v\) represents the velocity. We do not include the pressure in the solution space because it will be expressed as a function of \(U = (G, v)\), see (4c).

The energy associated with a solution \(U = (F - I, v) = (G, v)\) of the PDEs (1a), (1b) is given by
\[ \mathcal{E}_{p,q}[U](t) = \sum_{|a| + k \leq p \atop k \leq q} \left[ \frac{1}{2} \| S^k \Gamma^a U(t) \|_{L^2}^2 + \nu \int_0^t \| \nabla S^k \Gamma^a v(s) \|_{L^2}^2 \, ds \right]. \]

If \(U(0) = U_0\), then the energy at time \(t = 0\) will be denoted as
\[ \mathcal{E}_{p,q}[U_0] \equiv \mathcal{E}_{p,q}[U](0) = \frac{1}{2} \| U_0 \|_{X^{p,q}}^2. \]

We mention a few additional notational conventions. We write \(\langle t \rangle = (1 + t^2)^{1/2}\). Summation on repeated indices is understood. Although all indices are lowered, the first will be treated contravariantly, and the rest will act covariantly. For vector-valued functions \(v, \nabla v\) is the matrix-valued function with entries \((\nabla v)_{ij} = \partial_j v_i\). If \(F\) is a matrix-valued function, then \(\nabla \cdot F\) is the vector-valued function with components \((\nabla \cdot F)_i = \partial_j F_{ij}\). We will use \(F_{ij}\) to denote the \(j^{\text{th}}\) column of \(F\). We write \(A \lesssim B\) to mean that there exists a constant \(C > 0\) such that \(A \leq CB\). All constants explicit or implied are independent of \(0 \leq \nu \leq 1\).
3. Main results. Here now is a complete statement of the result to be proven. Since we shall consider small displacement gradients, we rewrite the system in terms of \( G = F - I \). We shall return to the original system in Theorem 3.2 below.

**Theorem 3.1.** Fix \( \mu = 1 \). Choose \( (p, q) \) with \( p \geq 11 \) and \( p \geq q > p^* \), where \( p^* = \left[ \frac{p + 5}{2} \right] \).

There are constants \( C_0, C_1 > 1 \) such that if \( v_0 \in X^{p,q} \) satisfies \( \nabla \cdot v_0 = 0 \) and \( C_0 \| v_0 \|_{X^{p^*,p^*}}^2 (1 + \| v_0 \|_{X^{p,q}}) < \varepsilon^2 \), then there is a unique pair \( (G, v) : [0, \infty) \times \mathbb{R}^3 \to \mathbb{R}^3 \times \mathbb{R}^3 \) such that

\[
U = (G, v) \in C([0, \infty); X^{p,q}) \cap \bigcap_{k=1}^q C^k((0, \infty), X^{p-k,q-k})
\]
and \( (G, v) \) satisfies the PDEs

\[
\partial_t G - \nabla v = \nabla v G - v \cdot \nabla G \tag{4a}
\]
\[
\partial_t v - \nabla \cdot G - \nu \Delta v = \nabla \cdot (GG^T) - v \cdot \nabla v - \nabla \pi \tag{4b}
\]

with pressure

\[
\pi = \Delta^{-1} \partial_i \partial_j [G_{ik}G_{jk} - v_i v_j] \tag{4c}
\]

and initial data \( (0, v_0) \).

Moreover, \( U = (G, v) \) satisfies the estimates

\[
E_{p,q}[U](t) \leq C_1 E_{p,q}[U_0](t)^{C_1 \varepsilon} \quad \text{and} \quad E_{p^*,p^*}[U](t) < \varepsilon^2, \tag{5}
\]
for \( t \in [0, \infty) \).

**Outline of Proof.** The strategy is the same as was used for the scalar model problem studied in [7]. The system (4a),(4b) is locally well-posed in \( X^{p,q} \). The norm in \( X^{p,q} \) can be controlled by an expression involving \( E_{p,q}[U](t) \), and thus, global existence follows by showing that \( E_{p,q}[U](t) \) remains finite. Here, we shall focus only on establishing the a priori estimates (5). The proof of these estimates will be spread across the remaining sections.

**Corollary 1.** The solution pair \( (G, v) \) given in Theorem 3.1 satisfies the constraints

\[
\nabla \cdot v = 0 \tag{6a}
\]
\[
\nabla \cdot G^T = 0 \tag{6b}
\]
\[
\partial_k G_{ij} - \partial_j G_{ik} = G_{lj} \partial_i G_{jk} - G_{lk} \partial_i G_{lj} \equiv Q_{ljk}(G, \nabla G). \tag{6c}
\]

**Proof.** Let \( \delta = \nabla \cdot v \) and \( \xi = \nabla \cdot G^T \). Then (4a),(4b),(4c) imply that

\[
\partial_t \xi - \nabla \delta = G^T \nabla \delta - v \cdot \nabla \xi
\]
\[
\partial_t \delta - \nabla \cdot \xi = v \cdot \nabla \delta + \delta^2.
\]

Since \( (\xi, \delta) \) vanishes initially, (6a),(6b) follow by uniqueness.

We will prove (6c) after the next result.

We now connect Theorem 3.1 to the original problem.

**Theorem 3.2.** If \( (G, v) \) is the solution pair given in Theorem 3.1, then \( F = I + G \) is the velocity gradient of the flow determined by \( v \) expressed in spatial coordinates, \( F : [0, \infty) \times \mathbb{R}^3 \to \text{SL}(3) \), and \( (F, v) \) satisfies (1a),(1b),(1c).
Proof. \((F,v)\) satisfies \((1a),(1b),(1c)\) by \((4a),(4b),(6a),(6b)\).

Since \(p > 3\), we have \(X^{p,q} \subset H^3\), and thus, the velocity vector field \(v \in C([0,\infty), X^{p,q})\) is a bounded \(C^0\) function on \(\mathbb{R}^3\) for each \(t \in [0,\infty)\), by the Sobolev lemma, and it is continuous in \(t\). As such it defines a flow on \(\mathbb{R}^3\) through

\[
D_t x(t,y) = v(t,x(t,y)), \quad x(0,y) = y.
\]

By \((6a)\), \(\nabla \cdot v = 0\), and so \(x(t,\cdot)\) is a one-parameter family of volume preserving deformations of \(\mathbb{R}^3\). The deformation gradient \(\bar{F}_{ij}(t,y) = (D_y x)_{ij}(t,y) = D_y x_i(t,y)\) is the unique solution of the system

\[
D_t \bar{F}(t,y) = \nabla v(t,x(t,y)) \bar{F}(t,y), \quad \bar{F}(0,y) = I. \tag{7}
\]

Since \(x(t,\cdot)\) is volume preserving, we see that \(\bar{F} : [0,\infty) \times \mathbb{R}^3 \to \text{SL}(3)\).

Since \(F\) solves \((1a)\), \(F(t,x(t,y))\) solves the initial value problem \((7)\), and so, \(F(t,x(t,y)) = \bar{F}(t,y)\).

The inverse \(y(t,\cdot)\) of the deformation \(x(t,\cdot)\) is called the reference or back-to-labels map, and it takes spatial points \(x\) to material points \(y\). Using this, we see that \(F(t,x) = \bar{F}(t,y(t,x))\), which shows that \(F\) is the deformation gradient in spatial coordinates. It follows that \(F : [0,\infty) \times \mathbb{R}^3 \to \text{SL}(3)\). \(\square\)

Proof of \((6c)\). Referring to the previous paragraphs, the deformation gradient satisfies the relation \(D_{y_j} \bar{F}_{ik}(t,y) = D_{y_k} \bar{F}_{ij}(t,y)\). Switching to spatial coordinates, this is equivalent to the compatibility condition \(F_{ik} \partial_i F_{ij} = F_{ij} \partial_i F_{ik}\). Since \(F = I + G\), this, in turn, implies \((6c)\). \(\square\)

4. Commutation. Using the following notation:

\[
U = (G,v), \quad G \in \mathbb{R}^{3 \times 3}, \quad v \in \mathbb{R}^3,
\]

we define

\[
A(\nabla)U = (\nabla v, \nabla \cdot G), \quad BU = (0,v),
\]

and the linearized operator

\[
LU = (I \partial_t - A(\nabla) - vB\Delta)U.
\]

We can then rewrite \((4a)\) and \((4b)\) as

\[
LU = N(U,\nabla U) + (0,-\nabla \pi), \tag{8a}
\]

where the nonlinearity is of the form

\[
N(U,\nabla U) = (N_1(U,\nabla U), N_2(U,\nabla U)) \tag{8b}
\]

with

\[
N_1(U,\nabla U) = \nabla v G - v \cdot \nabla G,
\]

\[
N_2(U,\nabla U) = \nabla \cdot (GG^T) - v \cdot \nabla v. \tag{8c}
\]

Lemma 4.1. Let \(p \geq 3\) and \(p \geq q \geq 1\). Suppose that

\[
(G,v,\pi) \in C([0,\infty); X^{p,q}) \cap \bigcup_{k=1}^q C^k((0,\infty),X^{p-k,q-k}).
\]

Then for any integer \(k\) and multi-index \(a\) such that \(0 \leq k \leq q\) and \(|a| + k \leq p\), there holds

\[
LS^k \Gamma^a U = (S+1)^k \Gamma^a LU + \nu \sum_{j=0}^{k-1} (-1)^{k-j} \binom{k}{j} B\Delta S^j \Gamma^a U \tag{9a}
\]
\[(S + 1)^k \Gamma^a N(U, \nabla U) = \sum_{a_1 + a_2 = a \atop k_1 + k_2 = k} \frac{a!}{a_1! a_2! k_1! k_2!} N(S^{k_1} \Gamma^{a_1} U, \nabla S^{k_2} \Gamma^{a_2} U) \]

\[(S + 1)^k \Gamma^a \nabla \pi = \nabla S^k \Gamma^a \pi. \quad (9c)\]

We remark that when \(k = 0\) the sum is empty in (9a).

**Proof.** The linear operator \(L\) defined in (8a) is translationally and rotationally invariant which implies that

\[L \Gamma^a U = \Gamma^a LU\]

The scaling operator \(S\), however, does not commute with \(L\). Since

\[\partial S = (S + 1) \partial\]
\[\Delta S = (S + 2) \Delta,\]

we have for any \(k > 0\)

\[LS^k = (S + 1)^k (\partial_t - A(\nabla)) - \nu B(S + 2)^k \Delta\]
\[= (S + 1)^k L + \nu B[(S + 1)^k - (S + 2)^k] \Delta.\]

We complete the proof of (9a) with

\[(S + 1)^k \Delta = [(S + 2) - 1]^k \Delta = \sum_{j=0}^k \binom{k}{j} (S + 2)^j (-1)^{k-j} \Delta\]
\[= (S + 2)^k \Delta + \sum_{j=0}^{k-1} (-1)^{k-j} \binom{k}{j} \Delta S^j.\]

The statement (9b) for the nonlinear terms is also a consequence of the Leibnitz-type formulas

\[\Gamma N_j(U, \nabla U) = N_j(\Gamma U, \nabla U) + N_j(U, \nabla \Gamma U),\]

\[(S + 1)N_j(U, \nabla U) = N_j(SU, \nabla U) + N_j(U, \nabla SU), \quad j = 1, 2.\]

The statement (9c) is also easily verified. \(\square\)

The appearance of the additional summand on the right-hand side of (9a) will force us to proceed by induction on \(k\).

**Lemma 4.2.** Let \(p \geq 3\) and \(p \geq q \geq 1\). Suppose that

\[(G, v) \in C([0, \infty); X^{p,q}) \cap \bigcap_{k=1}^q C^k([0, \infty), X^{p-k,q-k})\]

satisfy the constraints (6a),(6b),(6c). Then for any integer \(m\) and multi-index \(a\) such that \(0 \leq m \leq q\) and \(|a| + m \leq p\), there holds

\[\nabla \cdot S^m \Gamma^a v = 0\]
\[\nabla \cdot (S^m \Gamma^a G)^T = 0\]
\[\partial_k (S^m \Gamma^a G)_{ij} - \partial_j (S^m \Gamma^a G)_{ik} = \sum_{a_1 + a_2 = a \atop m_1 + m_2 = m} \frac{a!}{a_1! a_2! m_1! m_2!} Q_{ijk}(S^{m_1} \Gamma^{a_1} G, \nabla S^{m_2} \Gamma^{a_2} G) \equiv Q_{ijk}(G, \nabla G).\]
Proof. These statements follow by applying \((S+1)^m\Gamma^a\) to the equations (6a),(6b),(6c) and commuting with \(\nabla\). Our convention for computing \(\tilde{\Omega}_\ell^Q\) is
\[ (\tilde{\Omega}_\ell^Q)_{ijk} = \Omega^Q_{ijk} - (Z_t)_{ij}Q_{ijk} + Q_{ijk}(Z_t)_{lj} + Q_{ijl}(Z_t)_{jk}. \]

Lemma 4.3. Let \(p \geq 3\) and \(p \geq q \geq 1\). Suppose that
\([G, v] \in C([0, \infty); X^{p,q}) \cap \bigcap_{k=1}^q C^k((0, \infty), X^{p-k,q-k}).\]
If \(\pi\) is defined by (4c), then for any integer \(k\) and multi-index \(a\) such that \(0 \leq k \leq q\) and \(|a| + k \leq p - 1\), there holds
\[ S^k\Gamma^a\pi = (\nabla S^k\Gamma^a)_{ij} - v_i v_j. \]

Proof. Write \(\Delta \pi = \partial_i \partial_j [(GG^T)_{ij} - v_i v_j]\).
It is straight-forward to check that \(\Delta S \pi = (S + 2)\Delta \pi = \partial_i \partial_j S [(GG^T)_{ij} - v_i v_j]\)
and \(\Delta \tilde{\Omega}_k \pi = \tilde{\Omega}_k \Delta \pi = \partial_i \partial_j \tilde{\Omega}_k [(GG^T)_{ij} - v_i v_j]\).
It follows that
\[ \Delta S^k\Gamma^a\pi = \partial_i \partial_j S^k\Gamma^a [(GG^T)_{ij} - v_i v_j]. \]

5. Basic Inequalities. The results in this section will be used to estimate the nonlinear terms. This is the only place where the dimension \(n = 3\) enters the argument.

We introduce cut-off functions to distinguish two time-space regions, referred to as interior and exterior. Define
\[ \zeta(t, x) = \psi \left( \frac{|x|}{\sigma(t)} \right) \quad \text{and} \quad \eta(t, x) = 1 - \psi \left( \frac{2|x|}{\sigma(t)} \right), \]
where
\[ \psi \in C^\infty(\mathbb{R}), \quad \psi(s) = \begin{cases} 1, & s \leq 1/2 \\ 0, & s \geq 1 \end{cases}, \quad \psi' \leq 0, \quad \text{and} \quad \langle t \rangle = (1 + t^2)^{1/2}. \]
The parameter \(\sigma > 0\) in the definition of \(\zeta\) and \(\eta\) will be chosen later to be sufficiently small. Note that this is not a partition of unity. The cut-off functions satisfy the following inequalities:
\[ 1 \leq \zeta + \eta \quad \text{and} \quad 1 - \eta \leq \zeta^2 \]
and
\[ \langle r + t \rangle \left[ \partial_{tx} \zeta(t, x) + \partial_{tx} \eta(t, x) \right] \lesssim 1. \]

We define the following localized energy:
\[ \mathcal{Y}_{p,q}[U](t) = \sum_{|a| + k \leq p - 1} \| \zeta S^k\Gamma^a U(t) \|_{L^2}^2, \quad q < p. \]
This quantity will be estimated in Section 7.

The next three Lemmas were proven in [7], (with the slight notational difference that the quantity \(\mathcal{Y}_{p,q}\) is denoted by \(\mathcal{Y}_{p,q}^{\text{int}}\).)
Lemma 5.1 (Proposition 6.2, [7]). Suppose that $U = (G, v) : [0, T) \times \mathbb{R}^3 \to \mathbb{R}^{3 \times 3} \times \mathbb{R}^3$ satisfies (6a),(6b) and

$$\mathcal{Y}_{3,0}[U](t) + \mathcal{E}_{2,0}[U](t) < \infty.$$ 

Then using the weights (11a), we have

$$\| \zeta U(t) \|_{L^\infty} \lesssim \mathcal{Y}_{2,0}^{1/2}[U](t) + (t)^{-1} \mathcal{E}_{1,0}^{1/2}[U](t)$$ \quad (13)

$$\| r \zeta \nabla U(t) \|_{L^\infty} \lesssim \mathcal{Y}_{3,0}^{1/2}[U](t) + (t)^{-1} \mathcal{E}_{2,0}^{1/2}[U](t)$$ \quad (14)

$$\| r^{-1} \zeta U(t) \|_{L^2} \lesssim \mathcal{Y}_{1,0}^{1/2}[U](t) + (t)^{-1} \mathcal{E}_{0,0}^{1/2}[U](t).$$ \quad (15)

Lemma 5.2 (Lemma 7.1, [7]). Suppose that $U : [0, T) \times \mathbb{R}^3 \to \mathbb{R}^{3 \times 3} \times \mathbb{R}^3$. If

$$k_1 + k_2 + |a_1| + |a_2| \leq \bar{p} \quad \text{and} \quad k_1 + k_2 \leq \bar{q},$$

then we have

$$\| \zeta |S^{k_1} \Gamma U(t)| |S^{k_2} \Gamma a_{21}+1 U(t)| \|_{L^2} \lesssim \left( \mathcal{Y}_{k_1}^{1/2} \left( \frac{\bar{p}}{k_1+1} \right) \mathcal{Y}_{k_1}^{1/2} \left( \frac{\bar{q}}{k_1+1} \right) \right) \mathcal{E}_{\bar{p}+1, \bar{q}}^{1/2}[U](t),$$

provided the right-hand side is finite.

In the special case when $k_2 + |a_2| < \bar{p}$, we have

$$\| \zeta |S^{k_1} \Gamma a_{11} U(t)| |S^{k_2} \Gamma a_{21}+1 U(t)| \|_{L^2} \lesssim \left( \mathcal{Y}_{k_1}^{1/2} \left( \frac{\bar{p}}{k_1+1} \right) \mathcal{Y}_{k_1}^{1/2} \left( \frac{\bar{q}}{k_1+1} \right) \right) \mathcal{E}_{\bar{p}, \bar{q}}^{1/2}[U](t),$$

provided the right-hand side is finite.

Lemma 5.3 (Lemma 7.2, [7]). Suppose that $U : [0, T) \times \mathbb{R}^3 \to \mathbb{R}^{3 \times 3} \times \mathbb{R}^3$. If

$$k_1 + k_2 + |a_1| + |a_2| \leq \bar{p} \quad \text{and} \quad k_1 + k_2 \leq \bar{q},$$

then we have

$$\| \eta |S^{k_1} \Gamma a_{11} U(t)| |S^{k_2} \Gamma a_{21}+1 U(t)| \|_{L^2} \lesssim (t)^{-1} \mathcal{E}_{\bar{p}, \bar{q}}^{1/2}[U](t),$$

provided the right-hand side is finite.

In the special case when $k_2 + |a_2| < \bar{p}$, we have

$$\| \eta |S^{k_1} \Gamma a_{11} U(t)| |S^{k_2} \Gamma a_{21}+1 U(t)| \|_{L^2} \lesssim (t)^{-1} \mathcal{E}_{\bar{p}, \bar{q}}^{1/2}[U](t),$$

provided the right-hand side is finite.

This next result takes into account the constraints, and it will play a key role in assessing nonlinear interactions in (60).

**Proposition 1.** Suppose that $U = (G, v) : [0, T) \times \mathbb{R}^3 \to \mathbb{R}^{3 \times 3} \times \mathbb{R}^3$ satisfies (6a),(6b) and $\mathcal{E}_{2,0}[U](t) < \infty$, for all $t \in [0, T)$. Then

$$\| \eta G(t)^\top \omega \|_{L^\infty} + \| \eta \omega \cdot v(t) \|_{L^\infty} \lesssim (t)^{-3/2} \mathcal{E}_{2,0}^{1/2}[U](t).$$

**Proof.** Taking $U = (G, v)$ and $\omega = x/|x|$, define

$$\omega \otimes \omega U(t, x) = (\omega \otimes \omega G(t, x), \omega \otimes \omega v(t, x)).$$

Note that

$$\tilde{\Omega} \omega = 0,$$
and so
\[ \tilde{\Omega} \left[ \omega \otimes \omega U \right] = \omega \otimes \omega \tilde{\Omega} U. \]

The key point is that, from the gradient decomposition (2) and the constraints (10a), (10b), we have
\[ \sum_{|a| \leq 1} |\omega \otimes \omega \partial_r \tilde{\Omega}^a U| \lesssim \sum_{|a| \leq 1} \left[ (\partial_r \tilde{\Omega}^a G)^\top \omega + |\omega \cdot \partial_r \tilde{\Omega}^a v| \right] \lesssim \frac{1}{r} \sum_{|a| \leq 2} |\tilde{\Omega}^a U|. \] (16)

We appeal to the following inequality
\[ \|rU\|_{L^2} \lesssim \left( \sum_{|a| \leq 1} \|\partial_r \tilde{\Omega}^a U\|_{L^2} \sum_{|a| \leq 2} \|\tilde{\Omega}^a U\|_{L^2} \right)^{1/2} \]
which follows from Lemma 3.3 (3.14b) of [15]. Apply this to \( \eta \omega \otimes \omega U \). Since \( \langle t \rangle \lesssim r \) on the support of \( \eta \), we have
\[ \langle t \rangle^2 \left[ \| \eta G(t)^\top \omega \|_{L^2}^2 + \| \eta \omega \cdot v(t) \|_{L^2}^2 \right] \lesssim \| r \eta \omega \otimes \omega U \|_{L^2}^2 \lesssim \sum_{|a| \leq 1} \| \partial_r \tilde{\Omega}^a [\eta \omega \otimes \omega U] \|_{L^2} \lesssim \sum_{|a| \leq 2} \| \tilde{\Omega}^a [\eta \omega \otimes \omega U] \|_{L^2} \lesssim \sum_{|a| \leq 1} \| \omega \otimes \omega \partial_r [\eta \tilde{\Omega}^a U] \|_{L^2} \lesssim \sum_{|a| \leq 2} \| \tilde{\Omega}^a U \|_{L^2} \] (16).

Using (11c) and (16), this is bounded by
\[ \sum_{|a| \leq 1} \left[ \| \omega \otimes \omega \eta \partial_r \tilde{\Omega}^a U \|_{L^2} + (t)^{-1} \| \tilde{\Omega}^a U \|_{L^2} \right] \lesssim \langle t \rangle^{-1} \sum_{|a| \leq 2} \| \tilde{\Omega}^a U \|_{L^2} \lesssim \langle t \rangle^{-1} \mathcal{E}_{2,0}[U](t). \]

This shows that
\[ \| \eta G(t)^\top \omega \|_{L^2}^2 + \| \eta \omega \cdot v(t) \|_{L^2}^2 \lesssim \langle t \rangle^{-2} \mathcal{E}_{2,0}[U](t), \]
from which the Proposition follows. \( \square \)

Following our notational conventions, we may write \( (G^\top \omega)_j = \omega \cdot G_j \).

6. Estimates for the linearized system. In this section we provide estimates for solutions of the linearized system
\[ \begin{align*}
\partial_t G - \nabla v &= H \quad (17a) \\
\partial_t v - \nabla \cdot G - \nu \Delta v &= h \quad (17b) \\
\partial_t G_{ij} - \partial_j G_{ik} &= Q_{ijk} \quad i, j, k = 1, 2, 3. \quad (17c)
\end{align*} \]

Lemma 6.1. Assume that \( \sigma \) in (11a) is sufficiently small and that \( \nu \leq 1 \). Assume that the functions \( H, \nabla \cdot H, Q, \) and \( h \) all belong to the space \( L^2([0,T]; L^2(\mathbb{R}^3)) \), for some \( 0 < T < \infty \).

If \( U = (G, v) \) is a solution of (17a), (17b), (17c) such that
\[ \sup_{0 \leq t \leq T} \mathcal{E}_{1,1}[U](t) < \infty, \]
then for any \( 0 \leq \theta \leq 1, \)
\[
\int_0^T (t)^\theta \left[ \| \nabla U \|_{L^2}^2 + \nu^2 \| \Delta v \|_{L^2}^2 \right] dt \\
\leq \nu(T)^{\theta-2} \mathcal{E}_{1,0}(U)(T) + \int_0^T (t)^{\theta-2} \mathcal{E}_{1,1}(U)(t) dt \\
+ \int_0^T (t)^\theta \left[ 2\nu \langle \nabla \cdot G, \nabla \cdot H \rangle_{L^2} \\
+ \| \nabla Q \|_{L^2}^2 + \| \nabla H \|_{L^2}^2 + \| h \|_{L^2}^2 \right] dt.
\]

Proof. Multiplying (17a) and (17b) by and using that \( S = t\partial_t + r\partial_r \), we have that
\[
tv = -r\partial_r G + SG - tH \\
tv \cdot G + t\nu \Delta v = -r\partial_r v + Sv - th.
\]
Next, we multiply each equation by \( \zeta \) and take the \( L^2 \)-norm
\[
\| t \nabla v \|_{L^2}^2 \leq \| \zeta \partial_r G \|_{L^2}^2 + \| \zeta SG \|_{L^2}^2 + \| \zeta tH \|_{L^2}^2 \\
\| t \nabla \cdot G \|_{L^2}^2 + \nu^2 \| \zeta \Delta v \|_{L^2}^2 + 2\langle \zeta \nabla \cdot G, \zeta t\nu \Delta v \rangle_{L^2} \\
\leq \| \zeta \partial_r v \|_{L^2}^2 + \| \zeta Sv \|_{L^2}^2 + \| \zeta t h \|_{L^2}^2.
\]
Adding the two inequalities, we obtain
\[
t^2 \left[ \| \zeta \nabla \cdot G \|_{L^2}^2 + 2\nu \langle \zeta \nabla \cdot G, \zeta \Delta v \rangle_{L^2} + \nu^2 \| \zeta \Delta v \|_{L^2}^2 \right] \\
\leq \| \zeta \partial_r U \|_{L^2}^2 + \mathcal{E}_{1,1}(U)(t) + t^2 \left( \| \zeta t H \|_{L^2}^2 + \| \zeta H \|_{L^2}^2 \right),
\]
where \( U = (G, v) \).

Taking the divergence of (17a), we have
\[
\Delta v = \partial_t \nabla \cdot G - \nabla \cdot H
\]
and so we can write the inner product as
\[
2\nu \langle \zeta \nabla \cdot G, \zeta \Delta v \rangle_{L^2} = 2\nu \langle \zeta \nabla \cdot G, \zeta \partial_t \nabla \cdot G \rangle_{L^2} - 2\nu \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2}.
\]
The first term can be bounded below as follows:
\[
2\nu \langle \zeta \nabla \cdot G, \zeta \partial_t \nabla \cdot G \rangle_{L^2} \\
= \nu \int_{\mathbb{R}^3} \zeta^2 \partial_t | \nabla \cdot G |^2 dx \\
\geq \nu \partial_t \| \zeta \nabla \cdot G \|_{L^2}^2 - C \nu \int_{\mathbb{R}^3} \zeta(t)^{-1} | \nabla \cdot G |^2 dx \tag{20}
\]
where we have used Young’s inequality and the fact that by (11c), \( \partial_t \zeta^2 \leq C \zeta(t)^{-1} \), for some constant \( C \). Inserting (19) and (20) into (18) and using \( \| \nabla \cdot G(t) \|_{L^2}^2 \lesssim \mathcal{E}_{1,1}(U)(t) \), we have
\[
t^2 \left[ \nu \partial_t \| \zeta \nabla \cdot G \|_{L^2}^2 + \| \zeta \nabla \cdot G \|_{L^2}^2 + \nu^2 \| \zeta \Delta v \|_{L^2}^2 + \| \zeta \nabla v \|_{L^2}^2 \right] \\
\lesssim \| \zeta \partial_t U \|_{L^2}^2 + \mathcal{E}_{1,1}(U)(t) + 2\nu t^2 \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2} \\
+ t^2 \left( \| \zeta H \|_{L^2}^2 + \| \zeta h \|_{L^2}^2 \right). \tag{21}
\]
Choosing $0 \leq \theta \leq 1$, we multiply (21) by $(t)^{\theta-2}$, and then we integrate

$$
\int_0^T t^2(t)^{\theta-2} \left[ \frac{1}{2} \| \zeta \nabla \cdot G \|^2_{L^2} + \nu^2 \| \zeta \Delta v \|^2_{L^2} + \| \zeta \nabla v \|^2_{L^2} \right] dt
\leq \int_0^T (t)^{\theta-2} \left[ \| \zeta \partial_t U \|^2_{L^2} + \mathcal{E}_{1,1}[U](t) + 2\nu t^2 \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2} \right. \\
+ t^2 \left( \| \zeta H \|^2_{L^2} + \| \zeta h \|^2_{L^2} \right) \right] dt
- \int_0^T t^2(t)^{\theta-2} \nu \partial_t \| \zeta \nabla \cdot G \|^2_{L^2} dt.
$$

(22)

Next, we estimate the time-derivative term on the right hand side. Since

$$\partial_t(v(t)^{\theta-2}) = v(t)^{\theta-4}(2 + \theta^2) \leq 2\nu(t)^{\theta-2} \leq \frac{1}{4} t^2(t)^{\theta-2} + C \nu^2(t)^{\theta-2},$$

integration by parts yields

$$- \int_0^T t^2(t)^{\theta-2} \nu \partial_t \| \zeta \nabla \cdot G \|^2_{L^2} dt
\leq \frac{1}{4} \int_0^T t^2(t)^{\theta-2} \| \zeta \nabla \cdot G \|^2_{L^2} dt
\leq \frac{1}{4} \int_0^T t^2(t)^{\theta-2} \| \zeta \nabla \cdot G \|^2_{L^2} dt + C \int_0^T (t)^{\theta-2} \mathcal{E}_{1,1}[U](t) dt.$$

Substitution in (22) gives

$$\int_0^T t^2(t)^{\theta-2} \left[ \frac{1}{2} \| \zeta \nabla \cdot G \|^2_{L^2} + \nu^2 \| \zeta \Delta v \|^2_{L^2} + \| \zeta \nabla v \|^2_{L^2} \right] dt
\leq \int_0^T (t)^{\theta-2} \left[ \| \zeta \partial_t U \|^2_{L^2} + \mathcal{E}_{1,1}[U](t) + 2\nu t^2 \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2} \right. \\
+ t^2 \left( \| \zeta H \|^2_{L^2} + \| \zeta h \|^2_{L^2} \right) \right] dt.$$

By Lemma 6.2 (below), we can relpace the divergence term on the left-hand side by the full gradient

$$\int_0^T t^2(t)^{\theta-2} \left[ \| \zeta \nabla U \|^2_{L^2} + \nu^2 \| \zeta \Delta v \|^2_{L^2} \right] dt
\leq \int_0^T (t)^{\theta-2} \left[ \| \zeta \partial_t U \|^2_{L^2} + \mathcal{E}_{1,1}[U](t) + 2\nu t^2 \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2} \right. \\
+ t^2 \left( \| \zeta Q \|^2_{L^2} + \| \zeta H \|^2_{L^2} + \| \zeta h \|^2_{L^2} \right) \right] dt.$$

Using that $t^2 = (t^2 - 1)$ and $\| \zeta \nabla U(t) \|^2_{L^2} \lesssim \mathcal{E}_{1,1}[U](t)$, we can write

$$\int_0^T (t)^{\theta} \left[ \| \zeta \nabla U \|^2_{L^2} + \nu^2 \| \zeta \Delta v \|^2_{L^2} \right] dt
\leq \int_0^T (t)^{\theta-2} \left[ \| \zeta \partial_t U \|^2_{L^2} + \mathcal{E}_{1,1}[U](t) + \nu^2 \| \zeta \Delta v \|^2_{L^2} \right.
+ 2\nu t^2 \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2} \\
+ t^2 \left( \| \zeta Q \|^2_{L^2} + \| \zeta H \|^2_{L^2} + \| \zeta h \|^2_{L^2} \right) \right] dt.$$
Since $r \leq \sigma(t)$ on the support of $\zeta$, we have the following estimate:
\[
\int_0^T \langle t \rangle^{\theta-2} \|\zeta r \partial_t U\|_{L^2}^2 dt \leq \int_0^T \langle t \rangle^{\theta} \|\zeta \partial_t U\|_{L^2}^2 dt.
\]
For small enough $\sigma$, the last term can be absorbed on the left-hand side of the main inequality and thus, we obtain
\[
\int_0^T \langle t \rangle^{\theta} \left[ \|\zeta \nabla U\|_{L^2}^2 + \nu^2 \|\zeta \Delta v\|_{L^2}^2 \right] dt
\leq \int_0^T \langle t \rangle^{\theta-2} \left[ \mathcal{E}_{1,1}[U](t) + \nu^2 \|\zeta \Delta v\|_{L^2}^2 + 2\nu t^2 \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2}
+ t^2 (\|\zeta Q\|_{L^2}^2 + \|\zeta H\|_{L^2}^2 + \|\zeta h\|_{L^2}^2) \right] dt. \tag{23}
\]

The Laplacian term on the right has the following bound:
\[
\int_0^T \langle t \rangle^{\theta-2} \nu^2 \|\zeta \Delta v\|_{L^2}^2 dt = \int_0^T \langle t \rangle^{\theta-2} \nu^2 \frac{d}{dt} \int_0^t \|\zeta \Delta v\|_{L^2}^2 ds dt
= \langle T \rangle^{\theta-2} \nu^2 \int_0^T \|\zeta \Delta v\|_{L^2}^2 dt + \int_0^T (2-\theta) t \langle t \rangle^{\theta-4} \nu^2 \int_0^t \|\zeta \Delta v\|_{L^2}^2 ds dt \tag{24}
\leq \nu \langle T \rangle^{\theta-2} \mathcal{E}_{1,0}[U](T) + \nu \int_0^T \langle t \rangle^{\theta-2} \mathcal{E}_{1,0}[U](t) dt.
\]

Substituting (24) into (23) and using that $\nu \leq 1$, we arrive at
\[
\int_0^T \langle t \rangle^{\theta} \left[ \|\zeta \nabla U\|_{L^2}^2 + \nu^2 \|\zeta \Delta v\|_{L^2}^2 \right] dt
\leq \nu \langle T \rangle^{\theta-2} \mathcal{E}_{1,0}[U](T) + \int_0^T \langle t \rangle^{\theta-2} \mathcal{E}_{1,1}[U](t) dt
+ \int_0^T \langle t \rangle^{\theta} \left[ 2\nu \langle \zeta \nabla \cdot G, \zeta \nabla \cdot H \rangle_{L^2}
+ \|\zeta Q\|_{L^2}^2 + \|\zeta H\|_{L^2}^2 + \|\zeta h\|_{L^2}^2 \right] dt.
\]

\]

In the proof of Lemma (6.1), we used the following estimate:

Lemma 6.2. If $G \in H^1(\mathbb{R}^3, \mathbb{R}^{3 \times 3})$ and
\[
\partial_k G_{ij} - \partial_i G_{jk} = Q_{ijk} \tag{25}
\]
for $i, j, k = 1, 2, 3$ and $\|Q\|_{L^2} < \infty$, then
\[
\frac{1}{2} \|\nabla G\|_{L^2}^2 - \|\zeta \nabla \cdot G\|_{L^2}^2 \lesssim \langle t \rangle^{-2} \|G\|_{L^2}^2 + \|\zeta Q\|_{L^2}^2.
\]

Proof. The constraint (25) implies that
\[
-|\nabla \cdot G|^2 = -\partial_j G_{ij} \partial_k G_{ik}
= -\partial_k (\partial_j G_{ij} G_{ik}) + \partial_k \partial_k G_{ij} G_{ik}
= -\partial_k (\partial_j G_{ij} G_{ik}) + \partial_j (\partial_j G_{ik} + Q_{ijk}) G_{ik}
= -\partial_k (\partial_j G_{ij} G_{ik}) + \partial_j G_{ik} G_{ik} + \partial_j Q_{ijk} G_{ik}
= -\partial_k (\partial_j G_{ij} G_{ik}) + \partial_j (\partial_j G_{ik} G_{ik}) - \partial_j G_{ik} \partial_j G_{ik} + \partial_j Q_{ijk} G_{ik}
= -\partial_k (\partial_j G_{ij} G_{ik}) + \partial_j (\partial_j G_{ik} G_{ik}) - |\nabla G|^2 + \partial_j Q_{ijk} G_{ik}.
\]
Therefore, we have
\[ |\nabla G|^2 - |\nabla \cdot G|^2 = \partial_j (\partial_j G_{ik} G_{ik}) + \partial_j (\partial_j G_{ij} G_{ik}) - \partial_k (\partial_j G_{ij} G_{ik}). \]

We next multiply by \( \zeta^2 \) and integrate
\[
\left\| \zeta \nabla G \right\|_{L^2}^2 - \left\| \zeta \nabla \cdot G \right\|_{L^2}^2
= \int_{\mathbb{R}^3} \zeta^2 (\partial_j (\partial_j G_{ik} G_{ik}) - \partial_k (\partial_j G_{ij} G_{ik})) \, dx + \int_{\mathbb{R}^3} \zeta^2 \partial_j Q_{ijk} G_{ik} \, dx
\leq \int_{\mathbb{R}^3} \zeta(t)^{-1} |\nabla G| G \, dx + \int_{\mathbb{R}^3} \zeta(t)^{-1} |Q_{ijk}| |G| \, dx - \int_{\mathbb{R}^3} \zeta^2 Q_{ijk} \partial_j G_{ik} \, dx
\leq \frac{1}{2} \left\| \zeta \nabla G \right\|_{L^2}^2 + C(t)^{-2} \|G\|_{L^2}^2 + C\|\zeta Q\|_{L^2}^2,
\]
where we have used Young’s inequality and \(|\nabla \zeta^2| \leq \zeta(t)^{-1}\). The statement of the lemma follows immediately from this inequality.

\[ \square \]

We now establish a higher order version of Lemma 6.1. Define
\[
Z_{p,q}[U](t) = \sum_{|a| + k \leq p - 1} \left\| \zeta \Delta^{k} S^k \Gamma^a v(t) \right\|_{L^2}^2, \quad q < p. \tag{26}
\]

**Proposition 2.** Assume that \( \sigma \) in (11a) is sufficiently small and that \( \nu \leq 1 \). Fix \( 0 \leq q < p \). Suppose that
\[
S^k \Gamma^a H, \nabla \cdot S^k \Gamma^a H, S^k \Gamma^a Q, S^k \Gamma^a h \in L^2([0,T];X^{\nu-k-1,0}), \quad k = 0, \ldots, q,
\]
for some \( 0 < T < \infty \). If \( U = (G, v) \) is a solution of (17a),(17b),(17c) such that
\[
\sup_{0 \leq t \leq T} \mathcal{E}_{p,q+1}[U](t) < \infty,
\]
then for any \( 0 \leq \theta \leq 1 \),
\[
\int_0^T (t)^{\theta} \left[ Y_{p,q}[U](t) + \nu^2 Z_{p,q}[U](t) \right] \, dt
\leq \nu^2 \theta^2 \mathcal{E}_{p,q}[u](T) + \int_0^T (t)^{\theta - 2} \mathcal{E}_{p,q+1}[U](t) \, dt + \sum_{|a| + k \leq p - 1} \int_0^T (t)^{\theta} [2\nu (\zeta \Delta S^k \Gamma^a G, \zeta \nabla \cdot (S + 1)^k \Gamma^a H)]_{L^2}^2 + \|\zeta(S + 1)^k \Gamma^a Q\|_{L^2}^2 + \|\zeta(S + 1)^k \Gamma^a h\|_{L^2}^2 \, dt \bigg) \bigg).
\]

**Proof.** The proof proceeds by induction on \( q \). Applying the vector fields \( S^m \Gamma^a \), \( m \leq q, m + |a| \leq p - 1 \), to (17a),(17b),(17c) and using the commutation properties (9a),(9b),(10c), we obtain the PDEs
\[
\partial_t \tilde{G} - \nabla \tilde{v} = \tilde{H} \tag{27a}
\]
\[
\partial_t \tilde{v} - \nabla \cdot \tilde{G} - \nu \Delta \tilde{v} = \tilde{h}_0 \tag{27b}
\]
\[
\partial_k \tilde{G}_{ij} - \partial_j \tilde{G}_{ik} = \tilde{Q}_{ijk}. \tag{27c}
\]
where we have used the notation
\[
\tilde{G} = S^m \Gamma^a G \\
\tilde{v} = S^m \Gamma^a v \\
\tilde{H} = (S + 1)^m \Gamma^a H \\
\tilde{Q}_{ijk} = (S + 1)^m \Gamma^a Q_{ijk} \\
\tilde{h}_0 = (S + 1)^m \Gamma^a h - \sum_{j=0}^{m-1} (-1)^{m-j} \binom{m}{j} \nu B \Delta S^j \Gamma^a U.
\] (28)

Fix \( m = 0 \), and note that \( \tilde{h}_0 = \Gamma^a h \) (i.e. the sum is empty). Apply Lemma 6.1 to (27a), (27b), (27c) and sum over \( |a| \leq p - 1 \). This directly yields the result when \( q = 0 \).

Next, assume that the result holds for \( q = q' - 1 \), with \( q' < p \). Take \( m \leq q' \), \( m + |a| \leq p - 1 \), and note that
\[
\| \zeta \tilde{h}_0 \|_{L^2} \lesssim \| \zeta (S + 1)^m \Gamma^a h \|_{L^2} + \nu^2 Z_{p,q'} - 1[U](t).
\]

By the induction hypothesis, the quantity
\[
\nu^2 \int_0^T \langle t \rangle^\theta \xi \xi Z_{p,q'}-1[U](t) dt
\]
has the desired bound, so the result for \( q = q' \) follows by summation over \( m \leq q' \), \( m + |a| \leq p - 1 \).

7. Local energy decay. In this section we establish localized energy decay estimates for the nonlinear equation using a bootstrap argument and an application of Proposition 2. We remind the reader that the quantities \( Y_{p,q}[U](t) \) and \( Z_{p,q}[U](t) \) were defined in (12) and (26), respectively.

**Theorem 7.1.** Choose \((p,q)\) so that \( p^* = \left[ \frac{p+5}{2} \right] < q \leq p \). Suppose that \( U = (G,v) \in C([0,T]; X^{p,q}) \) is a solution of (4a), (4b), (4c) with
\[
\sup_{0 \leq t \leq T} E_{p,q}[U](t) < \infty,
\]
and
\[
\sup_{0 \leq t \leq T} E_{p^*,p^*}[U](t) \leq \varepsilon^2,
\] (29)
for some \( \varepsilon \) sufficiently small. Then
\[
\int_0^T \langle t \rangle^\theta [Y_{p^*,p^*-1}[U](t) + \nu^2 Z_{p^*,p^*-1}[U](t)] dt
\]
\[
\lesssim \begin{cases} 
\sup_{0 \leq t \leq T} (t)^{-\gamma} E_{p^*,p^*}[U](t), & 0 < \theta + \gamma < 1 \\
\log(e + T) \sup_{0 \leq t \leq T} E_{p^*,p^*}[U](t), & \theta = 1
\end{cases},
\] (30a)
and
\[
\int_0^T \langle t \rangle^\theta [Y_{p^*+1,p^*}[U](t) + \nu^2 Z_{p^*+1,p^*}[U](t)] dt
\]
\[
\lesssim \sup_{0 \leq t \leq T} \langle t \rangle^{-\gamma} E_{p^*,p^*}[U](t), \quad 0 < \theta + \gamma < 1. \quad (30b)
\]
Proof. Assume that the pair \((p, q)\) satisfies the hypotheses. Then

\[ p > p^* \geq 5. \]

Choose any pair \((\tilde{p}, \tilde{q})\) with

\[ \tilde{q} < \tilde{p} \leq p, \quad \tilde{q} < q. \]  

(31)

An application of Proposition 2 yields

\[ \int_0^T \langle t \rangle^\theta [Y_{\tilde{p}, \tilde{q}}(U)(t) + \nu^2 Z_{\tilde{p}, \tilde{q}}[U](t)] \, dt \]

\[ \lesssim \nu(T)^\theta - 2 \mathcal{E}_{\tilde{p}, \tilde{q}}[U](T) + \int_0^T \langle t \rangle^\theta - 2 \mathcal{E}_{\tilde{p}, \tilde{q} + 1}[U](t) \, dt + I, \]  

(32a)

where

\[ I = \sum_{|a| + k \leq \theta - 1} \int_0^T \langle t \rangle^\theta 2 \nu \langle \zeta \nabla \cdot S^k \Gamma^a G, \zeta \nabla \cdot (S + 1)^k \Gamma^a H \rangle_{L^2} \, dt, \]

(32b)

and

\[ J = \sum_{|a| + k \leq \theta - 1} \int_0^T \langle t \rangle^\theta \left[ \| \zeta (S + 1)^k \Gamma^a Q \|^2_{L^2} + \| \zeta (S + 1)^k \Gamma^a H \|^2_{L^2} + \| (S + 1)^k \Gamma^a h \|^2_{L^2} \right] dt, \]  

(32c)

with the following inhomogeneous terms:

\[ H = \nabla v G - v \cdot G \nabla \]

\[ h = \nabla \cdot (GG^T) - v \cdot \nabla v - \nabla \pi \equiv h_1 - \nabla \pi \]

(32d)

It follows from (9b) and (10c) that

\[ \| \zeta (S + 1)^k \Gamma^a H \|^2_{L^2} \lesssim \sum_{a_1 + a_2 = a, k_1 + k_2 = k} \| S^{k_1} \Gamma^{a_1} U | \nabla S^{k_2} \Gamma^{a_2} U \|^2_{L^2}, \]

\[ \lesssim \sum_{a_1 + a_2 = a, k_1 + k_2 = k} \| S^{k_1} \Gamma^{a_1} U | \nabla S^{k_2} S^{k_2} \Gamma^{a_2} U \|^2_{L^2}, \]

since \(|\zeta| \leq 1\). For the pressure term, we have by (9c) and Lemma 4.3,

\[ \| \zeta (S + 1)^k \Gamma^a \nabla \pi \|^2_{L^2} \leq \| (S + 1)^k \Gamma^a \nabla \pi \|^2_{L^2} \]

\[ = \| \nabla S^k \Gamma^a \nabla \pi \|^2_{L^2} \]

\[ = \| \nabla \Delta^{-1} \partial_i \partial_j S^k \Gamma^a [(GG^T)_{ij} - v_i v_j] \|^2_{L^2} \]

\[ \lesssim \sum_{a_1 + a_2 = a, k_1 + k_2 = k} \| S^{k_1} \Gamma^{a_1} U | \nabla S^{k_2} \Gamma^{a_2} U \|^2_{L^2}, \]

since the operators \(\Delta^{-1} \partial_i \partial_j\) are bounded on \(L^2\). From (32c), this proves that

\[ J \lesssim \int_0^T \langle t \rangle^\theta R^2_{p, q} \, dt, \]  

(33a)
with
\[ R_{p,q}^2 \equiv \sum_{k_1+k_2+|a_1|+|a_2| \leq \rho, k_1+k_2+|a_1|+|a_2| \leq \rho} \|S^{b_1} \Gamma^{a_1} U\| \|\nabla S^{b_2} \Gamma^{a_2} U\|_{L^2}^2. \] (33b)

Next, we turn to the estimation of the integral \( I \), defined in (32b). According to (32d) and (9b), we have, adopting the notation (28)
\[
\left| \nabla \cdot (S + 1)^k \Gamma^a H - \nabla \cdot [\nabla \tilde{v} G - v \cdot \nabla \tilde{G}] \right|
\lesssim \sum_{a_1+k=\rho, k_2+|a_1| \leq \rho} \nabla \cdot [\nabla S^{k_2} \Gamma^{a_2} \tilde{S}^{k_1} \Gamma^{a_1} G - S^{k_1} \Gamma^{a_1} v \cdot \nabla S^{k_2} \Gamma^{a_2} \tilde{G}].
\]

It follows that
\[
|I| \lesssim |I_1| + |I_2| + |I_3|,
\] (34)
with
\[
I_1 = \int_0^T (t)^{\theta} \nu\langle \zeta \nabla \cdot \tilde{G}, \zeta \nabla \cdot (\nabla \tilde{v} G) \rangle_{L^2} dt,
\]
\[
I_2 = \int_0^T (t)^{\theta} \nu\langle \zeta \nabla \cdot \tilde{G}, \zeta \nabla \cdot (v \cdot \nabla \tilde{G}) \rangle_{L^2} dt,
\]
and
\[
I_3 = \int_0^T (t)^{\theta} \nu \; R_{p,q} \; Y_{p,q}^{1/2} [U](t) \; dt. \tag{35}
\]

Let us first consider \( I_1 \). Using the standard Sobolev inequality, we have
\[
\|U\|_{L^\infty} + \|\nabla U\|_{L^\infty} \lesssim \mathcal{E}_{3,0}^{1/2} [U](t) \lesssim \mathcal{E}_{p^*,p'}^{1/2} [U](t) < \varepsilon,
\]
since \( p^* \geq 5 > 3 \). It follows that
\[
\nu\langle \zeta \nabla \cdot \tilde{G}, \zeta \nabla \cdot (\nabla \tilde{v} G) \rangle_{L^2} \lesssim \nu\|\zeta \nabla \tilde{U}\|_{L^2} \left( \|\nabla U\|_{L^\infty} \|\zeta \nabla \tilde{v}\|_{L^2} + \|U\|_{L^\infty} \|\zeta \nabla^2 \tilde{v}\|_{L^2} \right)
\lesssim \nu \varepsilon \; \mathcal{Y}_{p,q}^{1/2} [U](t) \left( \mathcal{Y}_{p,q}^{1/2} [U](t) + \|\zeta \nabla^2 \tilde{v}\|_{L^2} \right)
\lesssim \varepsilon \left( \mathcal{Y}_{p,q} [U](t) + \nu^2 \|\zeta \nabla^2 \tilde{v}\|_{L^2}^2 \right). \tag{36}
\]

For the final term in (36), we derive a coercivity inequality. Using integration by parts, we have
\[
\|\zeta \nabla^2 \tilde{v}\|_{L^2}^2 = \sum_{k,m} \int_{\mathbb{R}^3} \zeta^2 (\partial_k \partial_m \tilde{v}) (\partial_k \partial_m \tilde{v}) dx
= - \sum_{k,m} \int_{\mathbb{R}^3} (\partial_k \zeta^2) (\partial_m \tilde{v}) (\partial_k \partial_m \tilde{v}) dx
+ \sum_{k,m} \int_{\mathbb{R}^3} (\partial_m \zeta^2) (\partial_m \tilde{v}) (\Delta \tilde{v}) dx
+ \sum_{k,m} \int_{\mathbb{R}^3} \zeta^2 |\Delta \tilde{v}|^2 dx. \tag{37}
\]
Using (11c), we obtain $|\nabla \zeta^2| \lesssim \zeta(t)^{-1}$, and so (37) yields
\[
\|\zeta \nabla^2 \tilde{v}\|_{L^2} \lesssim \|\nabla \tilde{v}\|_{L^2} \|\zeta \Delta \tilde{v}\|_{L^2}^2 + \|\zeta \Delta \tilde{v}\|_{L^2}^2 \lesssim M^{-1} \|\zeta \Delta \tilde{v}\|_{L^2}^2 + M \epsilon^{-2} \|\nabla \tilde{v}\|_{L^2}^2 + \|\zeta \Delta \tilde{v}\|_{L^2}^2,
\]
for any $M > 0$. Choosing $M$ sufficiently large, we obtain the bound
\[
\|\zeta \nabla^2 \tilde{v}\|_{L^2} \lesssim \epsilon^{-2} \mathcal{E}_{\tilde{p}, \tilde{q}}[U](t) + \mathcal{Z}_{\tilde{p}, \tilde{q}}[U](t).
\]

Altogether, from (36) and (38), we conclude that
\[
|I_1| \lesssim \epsilon^{-2} \mathcal{E}_{\tilde{p}, \tilde{q}}[U](t) + \mathcal{Y}_{\tilde{p}, \tilde{q}}[U](t) + \nu^2 \mathcal{Z}_{\tilde{p}, \tilde{q}}[U](t).
\]

To estimate $I_2$, we write
\[
|\langle \zeta \nabla \cdot \tilde{G}, \zeta \nabla \cdot (v \cdot \nabla \tilde{G}) \rangle|_{L^2} = \left| \int_{\mathbb{R}^3} \zeta^2 (\nabla \cdot \tilde{G})_i \partial_k (v_m \partial_m \tilde{G}_{ik}) dx \right|
\]
\[
\leq \left| \int_{\mathbb{R}^3} \zeta^2 (\nabla \cdot \tilde{G})_i (\partial_k v_m)(\partial_m \tilde{G}_{ik}) dx \right| + \left| \int_{\mathbb{R}^3} \zeta^2 (\nabla \cdot \tilde{G})_i (v \cdot \nabla)(\nabla \cdot \tilde{G})_i dx \right|.
\]
The first term is easily estimated by
\[
\left| \int_{\mathbb{R}^3} \zeta^2 (\nabla \cdot \tilde{G})_i (\partial_k v_m)(\partial_m \tilde{G}_{ik}) dx \right| \leq \|\nabla U\|_{L^\infty} \|\zeta \Delta \tilde{U}\|_{L^2} \lesssim \epsilon \mathcal{Y}_{\tilde{p}, \tilde{q}}[U](t).
\]

For the second term, we use integration by parts and the fact that $\nabla \cdot v = 0$
\[
\left| \int_{\mathbb{R}^3} \zeta^2 (\nabla \cdot \tilde{G})_i (v \cdot \nabla)(\nabla \cdot \tilde{G})_i dx \right| = \frac{1}{2} \int_{\mathbb{R}^3} \zeta^2 \epsilon^{-2} (v \cdot \nabla)|\nabla \cdot \tilde{G}|^2 dx \leq \frac{1}{2} \int_{\mathbb{R}^3} \zeta^2 \|v \cdot \nabla\|_{L^2}^2 \|\nabla \tilde{G}\|_{L^2}^2 \lesssim \epsilon(t)^{-1} \int_{\mathbb{R}^3} \zeta\|U\|\|\nabla \tilde{G}\|^2 dx \lesssim \epsilon(t)^{-1} \|U\|_{L^\infty} \|\nabla \tilde{G}\|_{L^2} \|\zeta \nabla \tilde{G}\|_{L^2} \lesssim \epsilon(t)^{-1} \mathcal{E}_{\tilde{p}, \tilde{q}}[U](t) + \mathcal{Y}_{\tilde{p}, \tilde{q}}[U](t) \lesssim \epsilon(t)^{-2} \mathcal{E}_{\tilde{p}, \tilde{q}}[U](t) + \mathcal{Y}_{\tilde{p}, \tilde{q}}[U](t).
\]

This shows that
\[
I_2 \lesssim \epsilon(t)^{-2} \mathcal{E}_{\tilde{p}, \tilde{q}}[U](t) + \mathcal{Y}_{\tilde{p}, \tilde{q}}[U](t) + \nu^2 \mathcal{Z}_{\tilde{p}, \tilde{q}}[U](t).
\]

Since $\nu \leq 1$, we have by Young’s inequality, that
\[
I_3 \leq M^{-1} \int_0^T \langle t \rangle^\delta \mathcal{Y}_{\tilde{p}, \tilde{q}}[U](t) \, dt + M \int_0^T \langle t \rangle^\delta \mathcal{Z}_{\tilde{p}, \tilde{q}}[U](t) \, dt.
\]
Combining (34), (41), (39), and (40), we conclude that

\[ I \lesssim \int_0^T \langle t \rangle^{\alpha-2} \mathcal{E}_{\bar{p}, \bar{q}}[U](t) \]
\[ + (\varepsilon + M^{-1}) \int_0^T \langle t \rangle \left( \mathcal{Y}_{\bar{p}, \bar{q}}[U](t) + \nu^2 \mathcal{Z}_{\bar{p}, \bar{q}}[U](t) \right) dt \]
\[ + M \int_0^T \langle t \rangle^{\alpha} R_{\bar{p}, \bar{q}}^2 dt. \quad (42) \]

Upon assembling the estimates (35), (32a), (33a), (42), we obtain

\[
\int_0^T \langle t \rangle^{\alpha} [\mathcal{Y}_{\bar{p}, \bar{q}}[U](t) + \nu^2 \mathcal{Z}_{\bar{p}, \bar{q}}[U](t)] dt \\
\lesssim \nu \langle T \rangle^{\alpha-2} \mathcal{E}_{\bar{p}, \bar{q}}[U](T) + \int_0^T \langle t \rangle^{\alpha-2} \mathcal{E}_{\bar{p}, \bar{q}+1}[U](t) dt \\
+ (\varepsilon + M^{-1}) \int_0^T \langle t \rangle^\alpha \left( \mathcal{Y}_{\bar{p}, \bar{q}}[U](t) + \nu^2 \mathcal{Z}_{\bar{p}, \bar{q}}[U](t) \right) dt \\
+ M \int_0^T \langle t \rangle^{\alpha} R_{\bar{p}, \bar{q}}^2 dt.
\]

By taking \( \varepsilon \) sufficiently small and \( M \) sufficiently large, the middle integral can be absorbed on the left, resulting in

\[
\int_0^T \langle t \rangle^{\alpha} [\mathcal{Y}_{\bar{p}, \bar{q}}[U](t) + \nu^2 \mathcal{Z}_{\bar{p}, \bar{q}}[U](t)] dt \\
\lesssim \nu \langle T \rangle^{\alpha-2} \mathcal{E}_{\bar{p}, \bar{q}}[U](T) + \int_0^T \langle t \rangle^{\alpha-2} \mathcal{E}_{\bar{p}, \bar{q}+1}[U](t) dt + \int_0^T \langle t \rangle^{\alpha} R_{\bar{p}, \bar{q}}^2 dt. \quad (43)
\]

Recalling the definition (33b) and applying Lemmas 5.2, 5.3 we have that

\[
R_{\bar{p}, \bar{q}}^2 \lesssim \left( \mathcal{Y}_{\bar{p}', \bar{q}'}[U](t) + \langle t \rangle^{-2} \mathcal{E}_{\bar{p}', \bar{q}'}[U](t) \right) \mathcal{E}_{\bar{p}, \bar{q}}[U](t), \quad (44)
\]

where

\[
\bar{p}' = \left\lceil \frac{\bar{p} + 5}{2} \right\rceil, \quad \bar{q}' = \left\lceil \frac{\bar{q}}{2} \right\rceil.
\]

The estimates (43), (44) imply that

\[
\int_0^T \langle t \rangle^{\alpha} [\mathcal{Y}_{\bar{p}, \bar{q}}[U](t) + \nu^2 \mathcal{Z}_{\bar{p}, \bar{q}}[U](t)] dt \\
\lesssim \nu \langle T \rangle^{\alpha-2} \mathcal{E}_{\bar{p}, \bar{q}}[U](T) + \int_0^T \langle t \rangle^{\alpha-2} \mathcal{E}_{\bar{p}, \bar{q}+1}[U](t) dt \\
+ \int_0^T \langle t \rangle^{\alpha} \left( \mathcal{Y}_{\bar{p}', \bar{q}'}[U](t) + \langle t \rangle^{-2} \mathcal{E}_{\bar{p}', \bar{q}'}[U](t) \right) \mathcal{E}_{\bar{p}, \bar{q}}[U](t) dt. \quad (45)
\]

Now choose \((\bar{p}, \bar{q}) = (p^*, p^* - 1)\), which is consistent with the requirement (31). Since \( p^* \geq 5 \), there holds

\[
\bar{p}' = \left\lceil \frac{p^* + 5}{2} \right\rceil \leq p^*, \quad \bar{q}' = \left\lceil \frac{p^*}{2} \right\rceil \leq p^* - 1.
\]

In this case, our estimate (45) yields
By the assumption (29), we obtain

\[
\int_0^T \langle t \rangle^\theta \left[ \mathcal{Y}_{p^*,p^*} - 1[U](t) + \nu^2 \mathcal{Z}_{p^*,p^*} - 1[U](t) \right] dt \\
\lesssim \nu \langle T \rangle^{\theta - 2} \mathcal{E}_{p^*,p^*}[U](T) + \int_0^T \langle t \rangle^{\theta - 2} \mathcal{E}_{p^*,p^*}[U](t) dt \\
+ \int_0^T \langle t \rangle^\theta \left( \mathcal{Y}_{p^*,p^*} - 1[U](t) + \langle t \rangle^{-2} \mathcal{E}_{p^*,p^*}[U](t) \right) \mathcal{E}_{p^*,p^*}[U](t) dt.
\]

The last integral can be absorbed on the left, if \( \varepsilon \) is small enough, and we obtain finally

\[
\int_0^T \langle t \rangle^\theta \left[ \mathcal{Y}_{p^*,p^*} - 1[U](t) + \nu^2 \mathcal{Z}_{p^*,p^*} - 1[U](t) \right] dt \\
\lesssim \nu \langle T \rangle^{\theta - 2} \mathcal{E}_{p^*,p^*}[U](T) + \int_0^T \langle t \rangle^{\theta - 2} \mathcal{E}_{p^*,p^*}[U](t) dt. \\
(46)
\]

Choose \( \gamma \geq 0 \) so that \( 0 < \theta + \gamma \leq 1 \). From (46) we obtain

\[
\int_0^T \langle t \rangle^\theta \left[ \mathcal{Y}_{p^*,p^*} - 1[U](t) + \nu^2 \mathcal{Z}_{p^*,p^*} - 1[U](t) \right] dt \\
\lesssim \sup_{0 \leq t \leq T} \langle t \rangle^{-\gamma} \mathcal{E}_{p^*,p^*}[U](t) \left[ \langle T \rangle^{\theta + \gamma - 2} + \int_0^T \langle t \rangle^{\theta + \gamma - 2} dt \right],
\]

\( (30a) \)

from which the results (30a) follow directly.

Finally, going back to (45), we take \((\bar{p}, \bar{q}) = (p^* + 1, p^*)\), which is also consistent with (31). Note that

\( \bar{p} = p^* + 1 \leq p, \quad \bar{q} + 1 = p^* + 1 \leq p, \)

and

\( \bar{p}' = \left[ \frac{p^* + 6}{2} \right] \leq p^* , \quad \bar{q}' = \left[ \frac{p^* + 1}{2} \right] \leq p^* - 1, \)

since \( p^* \geq 5 \). We get from (45)

\[
\int_0^T \langle t \rangle^\theta \left[ \mathcal{Y}_{p^*+1,p^*} - 1[U](t) + \nu^2 \mathcal{Z}_{p^*+1,p^*} - 1[U](t) \right] dt \\
\lesssim \nu \langle T \rangle^{\theta - 2} \mathcal{E}_{p^*+q}[U](T) + \int_0^T \langle t \rangle^{\theta - 2} \mathcal{E}_{p^*+q}[U](t) dt \\
+ \int_0^T \langle t \rangle^\theta \left( \mathcal{Y}_{p^*,p^*} - 1[U](t) + \langle t \rangle^{-2} \mathcal{E}_{p^*,p^*}[U](t) \right) \mathcal{E}_{p^*,p^*}[U](t) dt.
\]
Let $\gamma \geq 0$ with $0 < \theta + \gamma < 1$. By (30a) and (29), this yields
\[
\int_0^T \langle t \rangle^\theta \left[ Y_{p^{\prime},1,p^{\prime}}[U](t) + \nu^2 Z_{p^{\prime},1,p^{\prime}}[U](t) \right] dt \\
\leq \sup_{0 \leq t \leq T} \langle t \rangle^{-\gamma} E_{p,q}[U](t) \left[ \langle T \rangle^{\theta+\gamma-2} + \int_0^T \langle t \rangle^{\theta+\gamma-2} dt \\
+ \int_0^T \langle t \rangle^{\theta+\gamma} Y_{p^{\prime},p^{\prime}-1}[U](t) dt \\
+ \sup_{0 \leq t \leq T} E_{p^{\prime},p^{\prime}}[U](t) \int_0^T \langle t \rangle^{\theta+\gamma-2} dt \right] \\
\leq \sup_{0 \leq t \leq T} \langle t \rangle^{-\gamma} E_{p,q}[U](t) \left[ 1 + \sup_{0 \leq t \leq T} E_{p^{\prime},p^{\prime}}[U](t) \right] \\
\leq \sup_{0 \leq t \leq T} \langle t \rangle^{-\gamma} E_{p,q}[U](t) \left[ 1 + \varepsilon^2 \right] \\
\leq \sup_{0 \leq t \leq T} \langle t \rangle^{-\gamma} E_{p,q}[U](t).
\]
This completes the proof of (30b).

8. Basic energy estimate. Here we record the basic energy estimate upon which our subsequent analysis will depend. We monitor the number of occurrences of the scaling operator inductively.

**Lemma 8.1.** Suppose that $U = (G, v) \in C((0,T); X^{p,q})$ is a solution of (4a),(4b), (4c). Then
\[
E_{p,q}[U](T) \lesssim E_{p,q}[U_0] \\
+ \sum_{a_1 + a_2 = a \atop k_1 + k_2 = k \atop |a_1| + |a_2| + k \leq p} \left| \int_0^T \langle N(S^{k_1}\Gamma_{a_1}U(t), \nabla S^{k_2}\Gamma_{a_2}U(t)), S^k\Gamma_{a}U(t) \rangle_{L^2} dt \right|. \tag{47}
\]

**Proof.** Taking the $L^2$ inner product of
\[
LU = \partial_t U - A(\nabla)U - \nu B\Delta U
\]
with $U = (G, v)$, we obtain
\[
\langle \partial_t U(t), U(t) \rangle_{L^2} - \langle A(\nabla)U(t), U(t) \rangle_{L^2} \\
- \langle \nu B\Delta U(t), U(t) \rangle_{L^2} = \langle LU(t), U(t) \rangle_{L^2}. \tag{48}
\]
The first term on the left of (48) vanishes
\[
\langle A(\nabla)U(t), U(t) \rangle_{L^2} = -\langle \nabla v(t), G(t) \rangle_{L^2} - \langle \nabla \cdot G(t), v(t) \rangle_{L^2} \\
= -\langle \nabla v(t), G(t) \rangle_{L^2} + \langle G(t), \nabla v(t) \rangle_{L^2} = 0.
\]
Using integration by parts, the third term on left of (48) can be written as
\[
\langle \nu B\Delta U(t), U(t) \rangle_{L^2} = \langle \nu \Delta v(t), v(t) \rangle_{L^2} = \int_{\mathbb{R}^3} \nu \partial_k^2 v_i(t)v_i(t) dx \\
= -\int_{\mathbb{R}^3} \nu \partial_k v_i(t) \partial_k v_i(t) dx = -\nu \| \nabla v(t) \|_{L^2}^2.
\]
Therefore, (48) becomes
\[ \frac{1}{2} \partial_t \|U(t)\|_{L^2}^2 + \nu \|\nabla v(t)\|_{L^2}^2 = \langle LU(t), U(t) \rangle_{L^2}. \]

Integration over time gives
\[ \frac{1}{2} \|U(T)\|_{L^2}^2 + \nu \int_0^T \|\nabla v(t)\|_{L^2}^2 dt = \frac{1}{2} \|U(0)\|_{L^2}^2 + \int_0^T \langle LU(t), U(t) \rangle_{L^2} dt, \]

which implies that for \( 0 \leq T < T_0 \)
\[ \mathcal{E}_{0,0}[U](T) = \mathcal{E}_{0,0}[U_0] + \int_0^T \langle LU(t), U(t) \rangle_{L^2} dt. \]

For \( p \geq q \geq 0 \), we apply the above estimate to higher order derivatives \( S^k \Gamma^a U \) and together with the commutation property (9a) we obtain
\[ \mathcal{E}_{p,q}[U](T) = \mathcal{E}_{p,q}[U_0] + I + \sum_{|a|+k \leq p \atop k \leq q} \int_0^T \langle (S + 1)^k \Gamma^a LU(t), S^k \Gamma^a U(t) \rangle_{L^2} dt, \quad (49) \]

where
\[ I = - \sum_{|a|+k \leq p \atop k \leq q} \sum_{j=0}^{k-1} \int_0^T \left\langle \left( -1 \right)^{k-j} \binom{k}{j} \nu B \Delta S^j \Gamma^a U(t), S^k \Gamma^a U(t) \right\rangle_{L^2} dt. \]

For \( q > 0 \) we show by integration by parts that
\[ \int_0^T \langle \nu B \Delta S^j \Gamma^a U(t), S^k \Gamma^a U(t) \rangle_{L^2} dt \]
\[ = \int_0^T \int_{\mathbb{R}^3} \nu \Delta (S^j \Gamma^a v(t))^j (S^k \Gamma^a v(t))^j dx dt \]
\[ = - \int_0^T \int_{\mathbb{R}^3} \nu \nabla (S^j \Gamma^a v(t))^j \cdot \nabla (S^k \Gamma^a v(t))^j dx dt \]
\[ \leq \int_0^T \nu \|\nabla S^j \Gamma^a v(t)\|_{L^2} \|\nabla S^k \Gamma^a v(t)\|_{L^2} dt \]
\[ \leq \left( \nu \int_0^T \|\nabla S^j \Gamma^a v(t)\|_{L^2}^2 dt \right)^{1/2} \left( \nu \int_0^T \|\nabla S^k \Gamma^a v(t)\|_{L^2}^2 dt \right)^{1/2}. \]

Therefore, we have
\[ I \lesssim \mathcal{E}^{1/2}_{p,q-1}[U](T) \mathcal{E}^{1/2}_{p,q}[U](T). \]

Applying Young’s inequality to the above bound and substituting into (49) give
\[ \mathcal{E}_{p,q}[U](T) \lesssim \mathcal{E}_{p,q}[U_0] + \mathcal{E}_{p,q-1}[U](T) + \lambda \mathcal{E}_{p,q}[U](T) \]
\[ + \sum_{|a|+k \leq p \atop k \leq q} \int_0^T \langle (S + 1)^k \Gamma^a LU(t), S^k \Gamma^a U(t) \rangle_{L^2} dt, \]

where \( \lambda \) is a small enough constant so that the corresponding energy term can be absorbed on the left. Induction on \( q \) further gives
Using (8a), (8b), and (8c), we can write the inner products in (47) as

\[ \mathcal{E}_{p,q}[U](T) \lesssim \mathcal{E}_{p,q}[U_0] + \sum_{|a|+k \leq p \atop k \leq q} \int_0^T \langle (S + 1)^k \Gamma^a LU(t), S^k \Gamma^a U(t) \rangle_{L^2} dt. \]  (50)

We recall that by Lemma 4.1, (9c)

\[ (S + 1)^k \Gamma^a LU = (S + 1)^k \Gamma^a N(U, \nabla U) + (0, -\nabla S^k \Gamma^a \pi). \]

Using integration by parts and the constraint (10a), we see that the pressure term vanishes

\[ -(\nabla S^k \Gamma^a \pi, S^k \Gamma^a v)_{L^2} = \langle S^k \Gamma^a \pi, \nabla \cdot S^k \Gamma^a v \rangle_{L^2} = 0. \]

Therefore, by (9b) we can write the energy inequality (50) as

\[ \mathcal{E}_{p,q}[U](T) \lesssim \mathcal{E}_{p,q}[U_0] + \sum_{|a|+k \leq p \atop k \leq q} \left| \int_0^T \langle N(S^{k_1} \Gamma^{a_1} U(t), \nabla S^{k_2} \Gamma^{a_2} U(t)), S^k \Gamma^a U(t) \rangle_{L^2} dt \right|. \]

9. **High energy estimates.** In this section we estimate the top order energy. Here it is crucial to avoid loss of derivatives.

**Proposition 3.** Choose \((p, q)\) so that \(5 \leq p^* = \left[ \frac{p+5}{2} \right] \leq q \leq p\). Suppose that \(U = (G, v) \in C([0, T_0), X^{p,q})\) is a solution of (4a),(4b),(4c) with

\[ \sup_{0 \leq t < T_0} \mathcal{E}_{p^*,p^*}[U](t) \leq \varepsilon^2, \]  (51)

for some \(\varepsilon\) sufficiently small. Then there exists a constant \(C_1 > 1\) such that

\[ \mathcal{E}_{p,q}[U](t) \leq C_1 \mathcal{E}_{p,q}[U_0](t)^{C_1}, \]

\[ \mathcal{E}_{p^*,p^*}[U](t) \leq C_1 \mathcal{E}_{p^*,p^*}[U_0](t)^{C_1}, \]

for \(0 \leq t < T_0\).

**Proof.** Using (8a), (8b), and (8c), we can write the inner products in (47) as

\[ \langle N(S^{k_1} \Gamma^{a_1} U(t), \nabla S^{k_2} \Gamma^{a_2} U(t)), S^k \Gamma^a U(t) \rangle_{L^2} \]

\[ = \langle \nabla S^{k_2} \Gamma^{a_2} v, S^{k_1} \Gamma^{a_1} G, S^k \Gamma^a G(t) \rangle_{L^2} \]

\[ - \langle S^{k_1} \Gamma^{a_1} v, \nabla S^{k_2} \Gamma^{a_2} G, S^k \Gamma^a G(t) \rangle_{L^2} \]

\[ + \langle \nabla \cdot (S^{k_1} \Gamma^{a_1} G S^{k_2} \Gamma^{a_2} G^T), S^k \Gamma^a v(t) \rangle_{L^2} \]

\[ - \langle S^{k_1} \Gamma^{a_1} v, \nabla S^{k_2} \Gamma^{a_2} v, S^k \Gamma^a v(t) \rangle_{L^2}. \]

We will first address the special case when \(a_1 = 0\) and \(k_1 = 0\), i.e. \(a_2 = a\) and \(k_2 = k\). Using the notation \(\vec{v} = S^k \Gamma^a v\) and \(\vec{G} = S^k \Gamma^a G\) introduced in (28), we start with

\[ -(v \cdot \nabla \vec{G}, \vec{G})_{L^2} = - \int_{\mathbb{R}^3} v_k \partial_k \vec{G}_{ij} \vec{G}_{ij} dx = - \frac{1}{2} \int_{\mathbb{R}^3} v_k \partial_k |\vec{G}|^2 dx = 0, \]

by (10a). Similarly, we see that \(\langle -v \cdot \nabla \vec{v}, \vec{v} \rangle_{L^2} = 0.\)

The remaining two terms are

\[ \langle \nabla \vec{v} G, \vec{G} \rangle_{L^2} + \langle \nabla \cdot (G G^T), \vec{v} \rangle_{L^2} \]

\[ = \int_{\mathbb{R}^3} [\partial_i \vec{G}_{jk} \vec{G}_{ik} + \partial_j (\vec{G}_{ik} G_{jk}) \vec{v}_i] dx \int_{\mathbb{R}^3} \partial_j (\vec{v}_i \vec{G}_{ik} G_{jk}) dx = 0. \]
This shows that all of the the terms in the sum with \( a_1 = 0 \) and \( k_1 = 0 \) cancel. Therefore we can write (47) as

\[
\mathcal{E}_{p,q}[U](T) \lesssim \mathcal{E}_{p,q}[U_0] + \sum_{|a_1 + a_2| + k_1 + k_2 \leq p} \int_0^T \| S^{k_1} \Gamma^{a_1} U(t) \| \| S^{k_2} \Gamma^{a_2 + 1} U(t) \|_{L^2} \mathcal{E}_{p,q}^{1/2}[U](t) \, dt, \tag{52}
\]

and thus, there is no derivative loss.

By (11b) and Lemmas 5.2 and 5.3, we get the bound

\[
\sum_{|a_1 + a_2| + k_1 + k_2 \leq p} \| S^{k_1} \Gamma^{a_1} u(t) \| S^{k_2} \Gamma^{a_2 + 1} u(t) \|_{L^2} \lesssim \sum_{|a_1 + a_2| + k_1 + k_2 \leq p} \| \xi S^{k_1} \Gamma^{a_1} u(t) \| S^{k_2} \Gamma^{a_2 + 1} u(t) \|_{L^2} + \sum_{|a_1 + a_2| + k_1 + k_2 \leq p} \| \eta S^{k_1} \Gamma^{a_1} u(t) \| S^{k_2} \Gamma^{a_2 + 1} u(t) \|_{L^2} \lesssim \mathcal{E}_{\frac{p}{\tau_2}, \frac{q}{\tau_2}}^{1/2}[U](t). \]

Inserting this into (52) yields

\[
\mathcal{E}_{p,q}[u](T) \lesssim \mathcal{E}_{p,q}[U_0] + \int_0^T \left[ \mathcal{E}_{\frac{p}{\tau_2}, \frac{q}{\tau_2}}^{1/2}[U](t) + \langle t \rangle^{-1} \mathcal{E}_{\frac{p}{\tau_2}, \frac{q}{\tau_2}}^{1/2} \langle \frac{p}{\tau_2} \rangle [U](t) \right] \mathcal{E}_{p,q}[U](t) \, dt.
\]

An application of Gronwall’s inequality produces

\[
\mathcal{E}_{p,q}[u](T) \lesssim \mathcal{E}_{p,q}[U_0] \exp \int_0^T \left[ \mathcal{E}_{\frac{p}{\tau_2}, \frac{q}{\tau_2}}^{1/2}[U](t) + \langle t \rangle^{-1} \mathcal{E}_{\frac{p}{\tau_2}, \frac{q}{\tau_2}}^{1/2} \langle \frac{p}{\tau_2} \rangle [U](t) \right] \, dt. \tag{53}
\]

We point out that (53) holds for any pair \((p, q)\) as long as \( p \geq q \geq \left[ \frac{p+5}{2} \right] \geq 5 \), which requires only \( p \geq 5 \).

Recalling the definition \( p^* = \left[ \frac{p+5}{2} \right] \), we obtain using Theorem 7.1

\[
\int_0^T \mathcal{E}_{p,q}^{1/2} \langle \frac{p}{\tau_2} \rangle [U](t) \, dt \leq \left( \int_0^T \langle t \rangle \mathcal{E}_{p^*, p^*-1}[U](t) \, dt \right)^{1/2} \left( \int_0^T \langle t \rangle^{-1} \, dt \right)^{1/2} \lesssim \left( \sup_{0 \leq t \leq T} \mathcal{E}_{p^*, p^*}[U](t) \langle e + T \rangle \right)^{1/2} \langle \log(e + T) \rangle^{1/2} \lesssim \sup_{0 \leq t \leq T} \mathcal{E}_{p^*, p^*}^{1/2}[U](t) \langle e + T \rangle.
\]

Likewise, we have the bound

\[
\int_0^T \langle t \rangle^{-1} \mathcal{E}_{\frac{p}{\tau_2}, \frac{q}{\tau_2}}^{1/2} \langle \frac{p}{\tau_2} \rangle [U](t) \, dt \lesssim \sup_{0 \leq t \leq T} \mathcal{E}_{\frac{p}{\tau_2}, \frac{q}{\tau_2}}^{1/2}[U](t) \langle e + T \rangle.
\]
Proposition 4. Choose low energy estimates.

Now thanks to the assumption (51), the inequality (53) implies that
$$E_{p,q}[u](T) \lesssim E_{p,q}[U_0] \exp[C_{T} \log(e + T)] \leq E_{p,q}[U_0][T]^{C_{1} \varepsilon}.$$ Returning to (53), we can repeat this argument with the pair $((p, q) = (p', p^*)$ because $p^* \geq 5$ implies that $p' \geq \left[\frac{p^* + 5}{2}\right]$. Therefore, we also obtain the bound
$$E_{p', p^*}[u](T) \lesssim E_{p', p^*}[U_0][T]^{C_{1} \varepsilon},$$ after a possible increase in the size of the constant $C_{1}$. Note however, that the choice of $C_{1}$ is independent of $\varepsilon$. Theorem 3 now follows.

10. Low energy estimates. Now we will estimate the lower energy where the focus will be to obtain the best possible temporal decay.

**Proposition 4.** Choose $(p, q)$ such that $p \geq 11$, and $p \geq q > p^*$, where $p^* = \left[\frac{p + 5}{2}\right]$. Suppose that $U = (G, v) \in C([0, T_0], Xu)$ is a solution of (4a), (4b), (4c) with
$$\sup_{0 \leq t < T_0} E_{p^*, p^*}[U](t) \leq \varepsilon^{2} \ll 1.$$

There exists a constant $C_{0} > 1$ such that
$$\sup_{0 \leq t < T_0} E_{p^*, p^*}[U](t) \leq C_{0} E_{p^*, p^*}[U_0] \left(1 + E_{p, q}^{1/2}[U_0]\right).$$

**Proof.** We start with (47) applied to $(p, q) = (p^*, p^*)$
$$E_{p^*, p^*}[U](T) \lesssim E_{p^*, p^*}[U_0]$$
$$+ \sum_{a_{1} + a_{2} = a} \int_{0}^{T} \left\langle N(S^{a_{1}} \Gamma^{a_{2}} U(t), \nabla S^{a_{2}} \Gamma^{a_{2}} U(t)), S^{k} \Gamma^{a_{2}} U(t)\right\rangle_{L^{2}} dt.$$ We have shown in Section (9) that the summation indices satisfy $|a_{2}| + k_{2} < p^*$, but we will not need this fact here.

Using the cut-off functions (11a) and the property (11b), we can bound the integral on the right-hand side by
$$\sum_{a_{1} + a_{2} = a} \int_{0}^{T} \left\langle N(S^{k} \Gamma^{a_{1}} U(t), \nabla S^{k} \Gamma^{a_{2}} U(t)), S^{k} \Gamma^{a_{2}} U(t)\right\rangle_{L^{2}} dt$$
$$\lesssim \sum_{a_{1} + a_{2} = a} \int_{0}^{T} \int_{\mathbb{R}^{3}} \zeta^{2} |S^{k} \Gamma^{a_{1}} U(t)| \left| \nabla S^{k} \Gamma^{a_{2}} U(t)\right| \left| S^{k} \Gamma^{a_{2}} U(t)\right| dx dt$$
$$+ \sum_{a_{1} + a_{2} = a} \int_{0}^{T} \left\langle \eta_{k} N(S^{k} \Gamma^{a_{1}} U(t), \nabla S^{k} \Gamma^{a_{2}} U(t)), S^{k} \Gamma^{a_{2}} U(t)\right\rangle_{L^{2}} dt$$
$$\equiv I_{1} + I_{2},$$
where $I_{1}$ and $I_{2}$ denote correspondingly the two integrals on the right and $T$ is in the range $0 \leq T < T_0$. 
We shall show that
\[ I_j \lesssim \mathcal{E}_{p^*, p^*}[U_0] \mathcal{E}^{1/2}_{p^*, q}[U_0] \quad j = 1, 2. \] (56)

The interior integral \( I_1 \) can be bounded by
\[
I_1 = \sum_{|\alpha_1 + \alpha_2| \leq |\alpha| \leq k} \int_0^T \int_{\mathbb{R}^3} \zeta^2 |\nabla S^{k_1} \Gamma^{\alpha_1} U| |\nabla S^{k_2} \Gamma^{\alpha_2} U| |S^k \Gamma U| \, dx \, dt
\]

\[
\lesssim \sum_{k_1 + k_2 + |\alpha_1| + |\alpha_2| \leq p^*} \int_0^T \| \zeta^2 |S^{k_1} \Gamma^{\alpha_1} U| |\nabla S^{k_2} \Gamma^{\alpha_2} U| \|_{L^2} \mathcal{E}^{1/2}_{p^*, p^*} [U](t) dt.
\]

In the case \( k_1 + |\alpha_1| < k_2 + |\alpha_2| + 1 \), i.e. \( k_1 + |\alpha_1| \leq \left\lceil \frac{p^*}{2} \right\rceil \), using (13), we have
\[
\| \zeta^2 |S^{k_1} \Gamma^{\alpha_1} U| \|_{L^\infty} \| \nabla S^{k_2} \Gamma^{\alpha_2} U \|_{L^2}
\]

\[
\lesssim \left[ \mathcal{Y}^{1/2}_{\left\lceil \frac{p^*}{2} \right\rceil} \left[ \frac{p^*}{2} \right] [U](t) + (t)^{-1} \mathcal{E}^{1/2}_{p^*, p^*} [U](t) \right]
\]

\[
\times \left[ \mathcal{Y}^{1/2}_{\left\lceil \frac{p^*}{2} \right\rceil} \left[ \frac{p^*}{2} - 1 \right] [U](t) + (t)^{-1} \mathcal{E}^{1/2}_{p^*, p^*} [U](t) \right].
\]

Recall that \( \left\lceil \frac{p^*+5}{2} \right\rceil \leq p^* \) since \( p^* \geq 11 \). Overall, for the interior low energy we have
\[
I_1 \lesssim \int_0^T \left[ \mathcal{Y}^{1/2}_{\left\lceil \frac{p^*}{2} \right\rceil} \left[ \frac{p^*}{2} \right] [U](t) + (t)^{-1} \mathcal{E}^{1/2}_{p^*, p^*} [U](t) \right]
\]

\[
\times \left[ \mathcal{Y}^{1/2}_{p^*-1} [U](t) + (t)^{-1} \mathcal{E}^{1/2}_{p^*, p^*} [U](t) \right] \mathcal{E}^{1/2}_{p^*, p^*} [U](t) dt
\]

\[
\lesssim \int_0^T \left[ \mathcal{Y}^{1/2}_{p^*-1} [U](t) + (t)^{-1} \mathcal{E}^{1/2}_{p^*, p^*} [U](t) \right]
\]

\[
\times \left[ \mathcal{Y}^{1/2}_{p^*-1} [U](t) + (t)^{-1} \mathcal{E}^{1/2}_{p^*, p^*} [U](t) \right] \mathcal{E}^{1/2}_{p^*, p^*} [U](t) dt
\]

\[
\lesssim \int_0^T \mathcal{Y}^{1/2}_{p^*, p^*} [U](t) \mathcal{Y}^{1/2}_{p^*-1} [U](t) \mathcal{E}^{1/2}_{p^*, p^*} [U](t) dt
\]

\[
+ \int_0^T (t)^{-1} \mathcal{Y}^{1/2}_{p^*-1} [U](t) \mathcal{E}^{1/2}_{p^*, p^*} [U](t) dt
\]

\[
+ \int_0^T (t)^{-2} \mathcal{E}^{3/2}_{p^*, p^*} [U](t) dt.
\]

Next, we are going to estimate these three integrals above. We will use Theorem 7.1 and Proposition 3. Furthermore, we will require that \( 2C_1 \varepsilon < 1 \).
The first integral can be estimated as follows:

\[
\int_0^T \gamma^{1/2}_{p^r,p^r-1}[U](t)\gamma^{1/2}_{p^r+1,p^r}[U](t)\|\mathcal{E}_{p^r,p^r}[U](t)\|_{H^s} dt \\
\lesssim \left( \sup_{0 \leq t \leq T} \langle t \rangle^{-C_1} \mathcal{E}_{p^r,p^r}[U](t) \right)^{1/2} \\
\times \int_0^T \langle t \rangle^{C_1/2} \gamma^{1/2}_{p^r,p^r-1}[U](t)\gamma^{1/2}_{p^r+1,p^r}[U](t) dt \\
\lesssim \mathcal{E}^{1/2}_{p^r,p^r}[U_0] \left( \int_0^T \langle t \rangle^{C_1/2} \gamma^{1/2}_{p^r,p^r-1}[U](t) dt \right)^{1/2} \left( \int_0^T \langle t \rangle^{C_1/2} \gamma^{1/2}_{p^r+1,p^r}[U](t) dt \right)^{1/2} \\
\lesssim \mathcal{E}^{1/2}_{p^r,p^r}[U_0] \left( \sup_{0 \leq t \leq T} \langle t \rangle^{-C_1} \mathcal{E}_{p^r,p^r}[U](t) \right)^{1/2} \left( \sup_{0 \leq t \leq T} \langle t \rangle^{-C_1} \mathcal{E}_{p^r,p^r}[U](t) \right)^{1/2} \\
\lesssim \mathcal{E}_{p^r,p^r}[U_0] \mathcal{E}_{p^r,p^r}^{1/2}[U_0].
\]

For the second integral, we have

\[
\int_0^T \langle t \rangle^{-1} \gamma^{1/2}_{p^r+1,p^r}[U](t)\mathcal{E}_{p^r,p^r}[U](t) dt \\
\lesssim \sup_{0 \leq t \leq T} \langle t \rangle^{-C_1} \mathcal{E}_{p^r,p^r}[U](t) \int_0^T \langle t \rangle^{-1+C_1} \gamma^{1/2}_{p^r+1,p^r}[U](t) dt \\
\lesssim \mathcal{E}_{p^r,p^r}[U_0] \int_0^T \langle t \rangle^{-1+C_1} \gamma^{1/2}_{p^r+1,p^r}[U](t) dt \\
\lesssim \mathcal{E}_{p^r,p^r}[U_0] \left( \int_0^T \langle t \rangle^{-2+C_1} \mathcal{E}_{p^r,p^r}[U](t) dt \right)^{1/2} \left( \int_0^T \langle t \rangle^{C_1} \gamma^{1/2}_{p^r+1,p^r}[U](t) dt \right)^{1/2} \\
\lesssim \mathcal{E}_{p^r,p^r}[U_0] \left( \sup_{0 \leq t \leq T} \langle t \rangle^{-C_1} \mathcal{E}_{p^r,p^r}[U](t) \right) \mathcal{E}_{p^r,p^r}^{1/2}[U_0].
\]

And finally, the third integral is bounded by

\[
\int_0^T \langle t \rangle^{-2} \mathcal{E}^{3/2}_{p^r,p^r}[U](t) dt \lesssim \left( \sup_{0 \leq t \leq T} \langle t \rangle^{-C_1} \mathcal{E}_{p^r,p^r}[U](t) \right)^{3/2} \int_0^T \langle t \rangle^{-2+C_1} \mathcal{E}_{p^r,p^r}[U](t) dt \\
\lesssim \mathcal{E}^{3/2}_{p^r,p^r}[U_0] \\
\lesssim \mathcal{E}_{p^r,p^r}[U_0] \mathcal{E}_{p^r,p^r}^{1/2}[U_0].
\]

Combining these estimates, we have proven (56), in the case \(j = 1\).

Now we turn to the estimation of \(I_2\). This is the crucial step, where we use the specific structure of the nonlinearity. By the definition of the exterior term

\[
I_2 = \sum \left| \int_0^T \langle \eta N(S^{k_1}_1 \Gamma^{\alpha_1} U(t), \nabla S^{k_2}_2 \Gamma^{\alpha_2} U(t)), S^{k}_k \Gamma^{\alpha} U(t) \rangle L^2 dt \right|.
\]

Referring to the definition of \(N(U, \nabla U)\) (see (8b),(8c)) and applying the constraint (10a) we note that, in components, the quadratic nonlinear terms are of the
form

\[ N_1(S^k_1 \Gamma^{a_1} U, \nabla S^k_2 \Gamma^{a_2} U)_{ij} = (S^k_1 \Gamma^{a_1} G)_{ij} \cdot \nabla (S^k_2 \Gamma^{a_2} v)_i \]
\[ - S^k_1 \Gamma^{a_1} v \cdot \nabla (S^k_2 \Gamma^{a_2} G)_{ij} \]
\[ N_2(S^k_1 \Gamma^{a_1} U, \nabla S^k_2 \Gamma^{a_2} U)_{i} = (S^k_1 \Gamma^{a_1} G)_{ij} \cdot \nabla (S^k_2 \Gamma^{a_2} G)_{ij} \]
\[ - S^k_1 \Gamma^{a_1} v \cdot \nabla (S^k_2 \Gamma^{a_2} v)_i, \]

where \( G_{ij} \) denotes the \( j \)th column of the matrix \( G \). Here and below, the indices satisfy \( a_1 + a_2 = a \), \( k_1 + k_2 = k \) with \( |a| + k \leq p^* \) and \( k \leq p^* \). Using the gradient decomposition (2), we can write

\[ |N(S^k_1 \Gamma^{a_1} U(t), \nabla S^k_2 \Gamma^{a_2} U(t))| \]
\[ \lesssim \left( |\omega \cdot S^k_1 \Gamma^{a_1} v| + |S^k_1 \Gamma^{a_1} G^\top \omega| \right) |\partial_r S^k_2 \Gamma^{a_2} U| \]
\[ + r^{-1} |S^k_1 \Gamma^{a_1} U| \|\Omega S^k_2 \Gamma^{a_2} U| \]
\[ = \left( |\omega \cdot S^k_1 \Gamma^{a_1} v| + \sum_j |\omega \cdot S^k_1 \Gamma^{a_1} G_{ij}| \right) |\partial_r S^k_2 \Gamma^{a_2} U| \]
\[ + r^{-1} |S^k_1 \Gamma^{a_1} U| \|\Omega S^k_2 \Gamma^{a_2} U| \]
\[ \lesssim |\omega \cdot S^k_1 \Gamma^{a_1} u| \ |\partial_r S^k_2 \Gamma^{a_2} U| + r^{-1} |S^k_1 \Gamma^{a_1} U| \|\Omega S^k_2 \Gamma^{a_2} U|, \]

where \( S^k_1 \Gamma^{a_1} u \) stands for either of

\[ S^k_1 \Gamma^{a_1} u = \begin{cases} (S^k_1 \Gamma^{a_1} G)_{ij} \\ S^k_1 \Gamma^{a_1} v \end{cases}. \]

Therefore, we obtain the bound

\[ I_2 \lesssim \sum_{a_1 + a_2 = a \atop |a| + k \leq p^*} \int_0^T \int_{\mathbb{R}^3} \eta \ |\omega \cdot S^k_1 \Gamma^{a_1} u| \ |\partial_r S^k_2 \Gamma^{a_2} U| \ |S^k \Gamma^a U| \ dx dt \]
\[ + \int_0^T \int_{\mathbb{R}^3} \eta \ r^{-1} |S^k_1 \Gamma^{a_1} U(t)| \ |\Omega S^k_2 \Gamma^{a_2} U(t)| \ |S^k \Gamma^a U(t)| \ dx dt \]
\[ \equiv I'_2 + I''_2. \]

By Lemma 5.3, we can bound \( I''_2 \) as follows:

\[ I''_2 \lesssim \sum_{a_1 + a_2 = a \atop |a| + k \leq p^*} \int_0^T \langle t \rangle^{-1} \|\partial_r S^k_1 \Gamma^{a_1} U(t)\| \ |\Omega S^k_2 \Gamma^{a_2} U(t)\| \ |S^k \Gamma^a U(t)| \ |S^k \Gamma^a U(t)| \ dx dt \]
\[ \lesssim \int_0^T \langle t \rangle^{-2} \mathcal{E}_{p^*} \{ U \}(t) \mathcal{E}_{H}^{1/2}(U)(t) dt. \]

We see that \( I'_2 \) is bounded by a sum of terms of the form

\[ \int_0^T \ |\eta \cdot S^k_1 \Gamma^{a_1} U(t)| \ |S^k_2 \Gamma^{a_2+1} U(t)| \ |S^k \Gamma^a U(t)| \ dx dt, \]

(59)
Recalling the constraints (10a),(10b), we see that Proposition 1 can be used to estimate $\|\eta \cdot S^{k_1} \Gamma^{a_1} u(t)\|_{L^\infty}$.

In the case $k_1 + |a_1| \leq \left[ \frac{p^*}{2} \right]$ and $k_2 + |a_2| \leq p^*$, Proposition 1 gives

$$\|\eta \cdot S^{k_1} \Gamma^{a_1} u(t)\|_{L^\infty} \leq \|S^{k_2} \Gamma^{a_2 + 1} U(t)\|_{L^2}$$

$$\lesssim \langle t \rangle^{-3/2} \mathcal{E}^{1/2}_{p^*,p^*} [U](t) $$

$$\lesssim \langle t \rangle^{-3/2} \mathcal{E}^{1/2}_{p^*,p^*}[U](t) \|U(t)\|_{p,q}$$

And in the case $k_2 + |a_2| \leq \left[ \frac{p^*}{2} \right]$ and $k_1 + |a_1| \leq p^*$, again by Proposition 1, we have

$$\|\eta \cdot S^{k_1} \Gamma^{a_1} u(t)\|_{L^\infty} \leq \|S^{k_2} \Gamma^{a_2 + 1} U(t)\|_{L^2}$$

$$\lesssim \langle t \rangle^{-3/2} \mathcal{E}^{1/2}_{p^*,p^*} [U](t) \mathcal{E}^{1/2}_{p^*,p^*}[U](t)$$

From the two cases above and (59) we conclude that

$$I_2' \lesssim \int_0^T \langle t \rangle^{-3/2} \mathcal{E}^{1/2}_{p^*,p^*}[U](t) \mathcal{E}^{1/2}_{p,q}[U](t) dt. \quad (60)$$

Therefore, from (57),(58), and (60), we have shown that

$$I_2 \lesssim \int_0^T \langle t \rangle^{-3/2} \mathcal{E}^{1/2}_{p^*,p^*}[U](t) \mathcal{E}^{1/2}_{p,q}[U](t) dt. \quad (61)$$

Now by Proposition 3, we obtain

$$I_2 \lesssim \mathcal{E}^{1/2}_{p^*,p^*}[U_0] \mathcal{E}^{1/2}_{p,q}[U_0] \int_0^T \langle t \rangle^{-3/2(1-C_1 \epsilon)} dt \lesssim \mathcal{E}^{1/2}_{p^*,p^*}[U_0] \mathcal{E}^{1/2}_{p,q}[U_0],$$

provided $C_1 \epsilon < 1/3$. This verifies (56), in the case $j = 2$.

By (54), (55), and the estimates (56), the proof of Proposition 3 is complete.

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