The Rique-Number of Graphs*

Michael A. Bekos¹, Stefan Felsner², Philipp Kindermann³, Stephen Kobourov⁴, Jan Kratochvíl⁵, and Ignaz Rutter⁶

¹ Department of Mathematics, University of Ioannina, Ioannina, Greece
bill@uoi.gr

² Institut für Mathematik, Technische Universität Berlin, Berlin, Germany
felsner@math.tu-berlin.de

³ Fachbereich IV - Informatikwissenschaften, Universität Trier, Trier, Germany
kindermann@uni-trier.de

⁴ Department of Computer Science, University of Arizona, Tucson, Arizona, USA
kobourov@cs.arizona.edu

⁵ Department of Applied Mathematics, Charles University, Prague, Czech Republic
honza@kam.mff.cuni.cz

⁶ Fakultät für Informatik und Mathematik, Universität Passau, Passau, Germany
rutter@fim.uni-passau.de

Abstract. We continue the study of linear layouts of graphs in relation to known data structures. At a high level, given a data structure, the goal is to find a linear order of the vertices of the graph and a partition of its edges into pages, such that the edges in each page follow the restriction of the given data structure in the underlying order. In this regard, the most notable representatives are the stack and queue layouts, while there exists some work also for deques.

In this paper, we study linear layouts of graphs that follow the restriction of a restricted-input queue (rique), in which insertions occur only at the head, and removals occur both at the head and the tail. We characterize the graphs admitting rique layouts with a single page and we use the characterization to derive a corresponding testing algorithm when the input graph is maximal planar. We finally give bounds on the number of needed pages (so-called rique-number) of complete graphs.

Keywords: linear layout · restricted-input queue · rique-number

1 Introduction

Linear graph layouts form an important methodological tool, since they provide a key-framework for defining different graph-parameters (including the well-known cutwidth [1], bandwidth [13] and pathwidth [33]). As a result, the corresponding literature is rather rich; see [34]. Such layouts typically consist of an order of the vertices of a graph and an objective over its edges that one seeks to optimize.

In the closely-related area of permutations and arrangements, back in 1973, Pratt [31] introduced and studied several variants of linear layouts that one can

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derive by leveraging different data structures to capture the order of the vertices (e.g., stacks, queues and deques).

Formally, given \( k \) data structures \( D_1, \ldots, D_k \), a graph \( G \) admits a \((D_1, \ldots, D_k)\)-layout if there is a linear order \( \prec \) of the vertices of \( G \) and a partition of the edges of \( G \) into \( k \) sets \( E_1, \ldots, E_k \), called pages, such that for each page \( E_i \) in the partition, each edge \((u, v)\) of \( E_i \) is processed by the data structure \( D_i \) by inserting \((u, v)\) to \( D_i \) at \( u \) and removing it from \( D_i \) at \( v \) if \( u \prec v \) in the linear layout. If the sequence of insertions and removals is feasible, then \( G \) is called a \((D_1, \ldots, D_k)\)-graph. We denote the class of \((D_1, \ldots, D_k)\)-graphs by \( D_1 + \ldots + D_k \). For a certain data structure \( D \), the \( D \)-number of a graph \( G \) is the smallest \( k \) such that \( G \) admits a \((D_1, \ldots, D_k)\)-layout with \( D = D_1 = \ldots = D_k \). This graph parameter has been the subject of intense research for certain data structures, as we discuss below.

1. If \( D \) is a stack (abbreviated by \( S \)), then insertions and removals only occur at the head of \( D \); see Fig. 1a. It is known that a non-planar graph may have linear stack-number, e.g., the stack-number of \( K_n \) is \( \lceil n/2 \rceil \) \[12\]. A central result here is by Yannakakis, who back in 1986 showed that the stack-number of planar graphs is at most 4 \[35\], a bound which was only recently shown to be tight \[10\]. Certain subclasses of planar graphs, however, allow for stack-layouts with fewer than four stacks, e.g., see \[8, 14, 20, 19, 23, 25, 28, 29, 30, 32\].

2. If \( D \) is a queue (abbreviated by \( Q \)), then insertions only occur at the head and removals only at the tail of \( D \); see Fig. 1b. In this context, a breakthrough by Dujmović et al. \[18\] states that the queue-number of planar graphs is at most 49, improving previous results \[5, 15, 16, 17\]. Even though this bound was recently improved to 42 \[9\], the exact queue-number of planar graphs is not yet known; the current-best lower bound is 4 \[9\]. Again, several subclasses allow for layouts with significantly fewer than 42 queues, e.g., see \[2, 21, 26, 32\].

3. If \( D \) is a double-ended queue or deque (abbreviated by \( DEQ \)), then insertions and removals can occur both at the head and the tail of \( D \); we denote the deque-number of a graph \( G \) by \( deq(G) \). This definition implies that \( S + S \subseteq DEQ \subseteq S + S + Q \). A characterization by Auer et al. \[4\] (stating that a graph has deque-number 1 if and only if it is a spanning subgraph of a planar graph with a Hamiltonian path) implies that the first containment is strict, because a maximal planar graph with a Hamiltonian path but not a Hamiltonian

Fig. 1: Different linear layouts of the complete graph \( K_4 \). The data structures are depicted in the states that corresponds to the dashed vertical line.

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2. If \( D \) is a queue (abbreviated by \( Q \)), then insertions only occur at the head and removals only at the tail of \( D \); see Fig. 1b. In this context, a breakthrough by Dujmović et al. \[18\] states that the queue-number of planar graphs is at most 49, improving previous results \[5, 15, 16, 17\]. Even though this bound was recently improved to 42 \[9\], the exact queue-number of planar graphs is not yet known; the current-best lower bound is 4 \[9\]. Again, several subclasses allow for layouts with significantly fewer than 42 queues, e.g., see \[2, 21, 26, 32\].

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cycle (e.g., the Goldner-Harary graph [22]) admits a DEQ-layout, but not an 
(S, S)-layout. The second containment is also strict because (S, S, Q)-graphs 
can be non-planar (e.g., $K_6$ [3]). Hence, $S + S \subseteq DEQ \subsetneq S + S + Q$ holds.

Our contribution. In this work, we focus on the case where the data struc-
ture $D$ is a restricted-input queue or rique (abbreviated by RIQ), in which insertions 
occur only at the head, and removals occur both at the head and the tail of $D$; see Fig. 1c. We first characterize the graphs with rique-number 1 as those 
admitting a planar embedding with a so-called strongly 1-sided subhamiltonian 
path, that is, a Hamiltonian path $v_1, \ldots, v_n$ in some plane extension of the 
embedding such that each edge $(v_i, v_j)$ with $1 < i < j \leq n$ leaves $v_i$ on the same 
side of the path; see Fig. 2. This characterization allows us to derive an inclusion 
relationship similar to the one above for deques (namely, $S, Q \subseteq RIQ \subsetneq S + Q$; see 
Observation 2) and corresponding recognition algorithms for graphs with rique-
number 1 under some assumptions (Theorem 3). Then, we focus on bounds 
on the rique-number of a graph $G$, which we denote by $riq(G)$. Our contribution 
is an edge-density bound for the graphs with rique-number $k$ (Theorem 5), and a 
lower and an upper bound on the rique-number of complete graphs (Theorem 6).

2 Preliminaries

We start with definitions that are central in Section 3. Given a rique-layout, 
we call an edge $(u, v)$ a head-edge (tail-edge), if $(u, v)$ is removed at $v$ from the 
head (tail) of the RIQ. A strongly 1-sided Hamiltonian path of a plane graph is 
a Hamiltonian path $v_1, \ldots, v_n$ such that each edge $(v_i, v_j)$ with $1 < i < j \leq n$ 
leaves $v_i$ on the same side of the path, say w.l.o.g. the left one, i.e., between 
$(v_{i-1}, v_i)$ and $(v_i, v_{i+1})$ in clockwise order around $v_i$ (see Fig. 2). A plane graph 
is strongly 1-sided Hamiltonian if it contains a strongly 1-sided Hamiltonian path. 
A planar graph is strongly 1-sided Hamiltonian if it admits a planar embedding 
that contains a strongly 1-sided Hamiltonian path. A planar (plane) graph $G$ is 
strongly 1-sided subhamiltonian if there exists a planar (plane) supergraph $H$ of 
$G$ that is strongly 1-sided Hamiltonian.
Another key-tool that we leverage in Section 4 is the SPQR-tree. This data structure, introduced by Di Battista and Tamassia [6,7], compactly represents all planar embeddings of a biconnected planar graph; see Fig. 3 for an example. It is unique and can be computed in linear time [24]. We assume familiarity with SPQR-trees; for a brief introduction refer to Appendix A.

3 Characterization of Graphs with Rique-Number 1

In this section, we discuss properties of graphs with rique-number 1. We first characterize these graphs in Lemma 1 in terms of the following forbidden pattern.

P.1 Three edges \( \langle e_a, e_b, e_c \rangle \) with \( e_a = (a, a') \), \( e_b = (b, b') \) and \( e_c = (c, c') \) form Pattern P.1 in a linear layout if and only if \( a \prec b \prec c \prec b' \prec \{a', c'\} \); see Fig. 4.

**Lemma 1.** A graph has rique-number 1 if and only if it admits a linear order avoiding Pattern P.1.

**Proof.** Let \( G \) be a graph with rique-number 1 and assume for a contradiction that a linear order of it contains Pattern P.1. The edge \( e_a \) is inserted into data structure \( R\bar{I}Q \) before the edge \( e_b \) is inserted, but removed after \( e_b \) is removed. Hence, \( e_b \) cannot be removed at the tail of \( R\bar{I}Q \), so it has to be removed at its head. However, the edge \( e_c \) is inserted after the edge \( e_b \) is inserted, but also removed after \( e_b \) is removed, so \( e_b \) also cannot be removed at the head; a contradiction.

![Fig. 4: Forbidden Pattern P.1](image-url)
Fig. 5: Ordering of the edges around a vertex $v_i$. For the other direction, assume that $G$ has rique-number greater than 1. We will prove that every linear order of $G$ contains Pattern P.1. Let $\prec$ be such an order. Since $G$ has rique-number greater than 1 and all insertions into a RIQ happen on the same side, at some time $b'$ there is an edge $e_b$ to be removed that is neither at the head nor at the tail of RIQ. Since $e_b$ is not at the head, there is some other edge $e_c$ that was inserted into RIQ after $e_b$ and is still there at time $b'$. Since $e_b$ is not at the tail, there is some other edge $e_a$ that was inserted into RIQ before $e_b$ and still is there. Then, $\langle e_a, e_b, e_c \rangle$ form Pattern P.1.

We are now ready to completely characterize the graphs with rique-number 1.

**Theorem 1.** A graph $G$ has rique-number 1 if and only if $G$ is planar strongly 1-sided subhamiltonian.

**Proof.** First, assume that $G$ can be embedded so that it contains a strongly 1-sided subhamiltonian path $v_1, \ldots, v_n$. For a contradiction, assume further that $\langle e_a = (a, a'), e_b = (b, b'), e_c = (c, c') \rangle$ form Pattern P.1 in the order $v_1, \ldots, v_n$. Note that $e_a$, $e_b$, and $e_c$ leave $a$, $b$, and $c$ on the left side, respectively. If $e_b$ enters $b'$ from the left, then $e_b$ crosses $e_c$ as $b \prec c \prec b' \prec c'$. So, $e_b$ has to enter $b'$ from the right. Then, however, $e_b$ crosses $e_a$ since $a \prec b \prec b' \prec a'$; a contradiction. So, by Lemma 1, $G$ has rique-number 1.

Assume now that $G$ has rique-number 1. By Lemma 1, $G$ admits a linear order $v_1, \ldots, v_n$ avoiding Pattern P.1. W.l.o.g. we assume that $G$ contains all edges in $\{(v_1, v_2), \ldots, (v_{n-1}, v_n)\}$ and prove that $G$ is strongly 1-sided Hamiltonian.

Consider a vertex $v_i$. We order the edges around $v_i$ counter-clockwise as follows; see Fig. 5. (i) The edge $(v_i, v_{i+1})$ (for $i < n$); (ii) the outgoing head-edges of $v_i$, ordered in increasing order by the index of the target vertex; (iii) the outgoing tail-edges of $v_i$, ordered in decreasing order by the index of the target vertex; (iv) the incoming head-edges of $v_i$, ordered in increasing order by the index of the source vertex; (v) the edge $(v_{i-1}, v_i)$ (for $i > 1$); (vi) the incoming tail-edges of $v_i$, ordered in increasing order by the index of the source vertex. This ensures that all edges leave $v_i$ on the correct side of the Hamiltonian path. It remains to be shown that this embedding is plane. To this end, assume that there are two edges $(v_i, v_j)$ and $(v_k, v_l)$ that cross. W.l.o.g. we assume that $i < k$.

If $(v_k, v_l)$ is a head-edge, then it leaves and enters $v_k$ and $v_l$ on the same side of the Hamiltonian path as $(v_i, v_j)$ leaves $v_i$. Hence, $(v_i, v_j)$ and $(v_k, v_l)$ cross.
only if \((v_i, v_j)\) also enters \(v_j\) on the same side. So, \((v_i, v_j)\) is also a head-edge with \(i < k < j < \ell\). However, since \((v_i, v_j)\) entered \(RIQ\) at the head before \((v_k, v_\ell)\), it cannot leave \(RIQ\) at the head before \((v_k, v_\ell)\); a contradiction.

If \((v_k, v_\ell)\) is a tail-edge, then \((v_i, v_j)\) leaves \(v_i\) on the same side of the Hamiltonian path as \((v_k, v_\ell)\) leaves \(v_k\), but \((v_k, v_\ell)\) enters \(v_\ell\) on the other side. If \((v_i, v_j)\) is a head-edge, then we must have \(i < k < j\). However, since \((v_i, v_j)\) entered \(RIQ\) at the head before \((v_k, v_\ell)\), it cannot leave \(RIQ\) at the head before \((v_k, v_\ell)\); a contradiction. Otherwise \((v_i, v_j)\) is a tail-edge, and we must have \(i < k < \ell < j\). However, since \((v_i, v_j)\) entered \(RIQ\) at the head before \((v_k, v_\ell)\), it cannot leave \(RIQ\) at the tail after \((v_k, v_\ell)\); a contradiction.

It follows that no two edges cross, as desired. This concludes the proof. \(\square\)

The definition of a rique implies \(X \subseteq RIQ \subseteq S + Q\), where \(X \in \{S, Q\}\). By Theorem 1, both inclusions are strict, as \(K_4 \in RIQ\) (see Fig. 1c) but it admits neither a stack-layout (since it is not outerplanar [12]) nor a queue-layout (since any linear order yields a 2-rainbow [27]), and \(K_6\) admits an \((S, Q)\)-layout [3] but is not planar and therefore \(K_6 \notin RIQ\).

Observation 2. \(X \subseteq RIQ \subseteq S + Q\), where \(X \in \{S, Q\}\)

4 Recognition of graphs with Rique-Number 1

With the characterization of Theorem 1 at hand, we now turn our focus to the recognition problem, where we present two algorithms: (i) the first one is simple and tests whether a plane graph is strongly 1-sided Hamiltonian, while (ii) the second one is more elaborate and tests whether a planar graph is strongly 1-sided Hamiltonian. Even though our algorithms do not solve the general case of testing whether a graph has rique-number 1 (or equivalently by Theorem 1 whether it is strongly 1-sided subhamiltonian), they can be leveraged for testing, e.g., whether a maximal planar graph or a 3-connected planar graph has rique-number 1.

Theorem 3. Given a plane \(n\)-vertex graph \(G\), there is an \(O(n^2)\)-time algorithm to test whether \(G\) is plane strongly 1-sided Hamiltonian.

Proof. After guessing the first edge of the path, for which there are \(O(n)\) choices, we assume that we have computed a subpath \(\pi = v_1, \ldots, v_i, 2 \leq i < n\) of a strongly 1-sided Hamiltonian path of \(G\). We claim that the next vertex \(v_{i+1}\) is uniquely determined by \(\pi\). Consider the edges of \(G\) incident to \(v_i\) in counterclockwise order, starting from the edge after \((v_{i-1}, v_i)\). Let \(e\) be the first edge in this order, whose other endpoint does not lie on \(\pi\). We choose this endpoint as \(v_{i+1}\). This is correct, since choosing an endpoint of an edge preceding \(e\) visits a vertex twice, whereas choosing an endpoint of an edge succeeding \(e\) would imply that \(e\) leaves the resulting path on the wrong side. The above argument shows that, after guessing an initial edge, the remainder of the 1-sided Hamiltonian path is uniquely defined, if it exists. Since a single starting edge can be tested in \(O(n)\) time, the overall time complexity of our algorithm is \(O(n^2)\). \(\square\)
Corollary 1. Given a maximal planar graph $G$ with $n$ vertices, there is an $O(n^2)$-time algorithm to test whether $G$ has rique-number 1.

Theorem 4. Given a planar $n$-vertex graph $G$, there is an $O(n^4)$-time algorithm to test whether $G$ is planar strongly 1-sided Hamiltonian.

Proof. To prove the statement, we assume that the endpoints $s, t$ of the Hamiltonian path are specified as part of the input and we show that testing whether $G$ admits a planar embedding containing a strongly 1-sided Hamiltonian $st$-path can be done in $O(n^2)$ time. In the positive case, we say that $G$ is $st$-1-sided.

If $G$ is not biconnected, then for $G$ to be $st$-1-sided its block-cut tree must be a path $B_1, c_1, B_2, \ldots, c_k, B_{k+1}$, such that $s \in B_1$ and $t \in B_{k+1}$ (or vice versa; here $k$ denotes the number of cutvertices of $G$). We set $c_0 = s$ and $c_{k+1} = t$ and claim that $G$ is $st$-1-sided if and only if each block $B_i$ is $c_i-1$-1-sided for $i = 1, \ldots, k+1$. The necessity is clear, we prove the sufficiency. Let $E_i$ be a planar embedding of $B_i$ containing a strongly 1-sided Hamiltonian $c_i-1$-path $p_i$ for $i = 1, \ldots, k+1$. We modify the embedding $E_i$ such that the first edge of $p_i$ lies on the outer face, and combine $E_{i-1}$ and $E_i$ in such a way that the first edge of $p_i$ follows the last edge of $p_{i-1}$ in counterclockwise order around $c_i$. Then the path $p$ obtained by concatenating $p_i$, $i = 1, \ldots, k+1$ is a strongly 1-sided Hamiltonian path in the resulting embedding $E$ of $G$; see Fig. 6.

Hence, we may assume that $G$ consists of a single block. Since the case where $G$ consists of a single edge can be handled trivially, we focus on the case where $G$ is biconnected. To determine whether $G$ is $st$-1-sided, we use a dynamic program based on an SPQR-tree $T$ of $G$. We root $T$ at an edge incident to $t$ and for each node $\mu$ of $T$ with poles $u, v$, we want to answer the following questions: If $s \notin \pert(\mu)$, we want to know for each of the two ordered pairs of poles $(x, y) \in \{(u, v), (v, u)\}$ whether $\pert(\mu)$ has an embedding with $x, y$ on the outer face such that it contains a strongly 1-sided Hamiltonian path from $x$ to $y$ that starts with the edge that follows the parent edge counterclockwise around $x$; in the positive case. We define the set $L(\mu)$ as those ordered pairs $(x, y)$ where this is the case. For a pair $(x, y) \in L(\mu)$, we denote by $E_{\mu}(x, y)$ the corresponding embedding of $\pert(\mu)$ and by $P_{\mu}(x, y)$ the corresponding path. If $s \in \pert(\mu)$,
then for each \( x \in \{u, v\} \) and \( Y \subseteq \{u, v\} \setminus \{x\} \) we want to know whether \( \text{pert}(\mu) \) has an embedding \( E_\mu(x, Y) \) such that \( u, v \) are incident to the outer face and there is a strongly 1-sided path \( P_\mu(x, Y) \) from \( s \) to \( x \) that visits all vertices of \( \text{pert}(\mu) - Y \). As above, for node \( \mu \), we define \( L(\mu) \) as the set of all pairs \( (x, Y) \) where this is possible.

Consider the root \( r \) of \( T \) and let \( \mu \) be its child with poles \( u, t \). Then \( G \) is \( st \)-1-sided if and only if and only if \((t, \emptyset) \in L(\mu) \). The necessity is clear. For the sufficiency, observe that \( P_\mu(t, \emptyset) \) is a strongly 1-sided \( st \)-path in the embedding of \( G \) obtained from \( E_\mu(t, \emptyset) \) by adding the edge \( ut \) in the outer face. We compute the set \( L(\mu) \) for each node \( \mu \) of \( T \) (together with corresponding embeddings of \( \text{pert}(\mu) \) and paths) by a bottom-up traversal of \( T \) as follows. Let \( \mu \) be a node of \( T \) in this traversal with poles \( u, v \). If \( \mu \) is not a leaf in \( T \), we denote by \( \mu_1, \ldots, \mu_k \) its children, and we assume that \( L(\mu_i) \) has already been computed for \( i = 1, \ldots, k \). We next distinguish cases based on the type of \( \mu \).

**Case 1: \( \mu \) is a Q-node.** If \( u \neq s \neq v \), then \( L(\mu) = \{(u, v), (v, u)\} \). And for \((x, y) \in L(\mu) \) the embedding \( E_\mu(x, y) \) and the path \( P_\mu(x, y) \) are trivial; see Fig. 7a. Otherwise, assume w.l.o.g., \( s = v \). Then \( L(\mu) = \{(v, \{u\}), (u, \emptyset)\} \). Again for \((x, Y) \in L(\mu) \), \( E_\mu(x, Y) \) and \( P_\mu(x, Y) \) can be defined trivially; see Fig. 7b.

**Case 2: \( \mu \) is a P-node.** Assume first that \( s \notin \text{pert}(\mu) \); see Fig. 8a. We show how to test whether \((v, u) \in L(\mu) \). The case of \((u, v) \) is symmetric. First \((v, u) \in L(\mu) \) requires \( k = 2 \) and that only one of the children, say \( \mu_1 \), is not a Q-node. If so, \((v, u) \in L(\mu_1) \) and only if \((v, u) \in L(\mu_1) \). Also, \( P_\mu(v, u) = P_{\mu_1}(v, u) \) and \( E_\mu(v, u) \) is obtained by embedding the edge represented by \( \mu_2 \) to the left of \( E_{\mu_1}(v, u) \).

Now, consider the case that \( s \in \text{pert}(\mu) \). Assume first that \( s \) is a pole of \( \mu \); see Fig. 8a. Then, any 1-sided path of \( \mu \) unavoidably visits the other pole. In fact, only a single child can be traversed, i.e., \( k = 2 \), and one child, say \( \mu_2 \), is a Q-node. If this is not the case, \( L(\mu) = \emptyset \). Otherwise, \( L(\mu) = L(\mu_1) \). For \((x, Y) \in L(\mu_1) \), we set \( p_\mu(x, Y) = p_{\mu_1}(x, Y) \) and we define \( E_\mu(x, Y) \) as the embedding obtained from \( E_{\mu_1}(x, Y) \) by putting the edge represented by \( \mu_2 \) to its left parallel to it.

Assume now that \( s \) is not a pole and it lies, w.l.o.g., in \( \text{pert}(\mu_1) \). Let \((x, Y) \) be a pair with \( x \in \{u, v\} \), \( Y \subseteq \{u, v\} \setminus \{x\} \). W.l.o.g., we assume \( x = u \). The case \( x = v \) is analogous. Then either \( Y = \{v\} \) or \( Y = \emptyset \). If \( v \in Y \) (see Fig. 8b), then \((u, Y) \in L(\mu_1) \) and \( k = 2 \) and \( \mu_2 \) is a Q-node. In that case, we set \( P_\mu(u, Y) = P_{\mu_1}(u, Y) \) and we define \( E_\mu(u, Y) \) as the embedding obtained from \( E_{\mu_1}(u, Y) \) by embedding the edge represented by \( \mu_2 \) to its left. If \( Y = \emptyset \) (see Fig. 8c), then we distinguish cases based on whether there is a second child, say \( \mu_2 \), that is not a Q-node. If there is none, then \( \mu_2 \) is a Q-node.

![Fig. 7: The tuples of \( L(\mu) \) for a Q-node; the corresponding paths are red.](image)
In this case, we define $P_{\mu}(u, v) = P_{\mu_1}(u, v) \cdot P_{\mu_2}(v, u)$ if and only if $(u, v) \in L(\mu)$. In these cases, we set $P_{\mu}(u, \emptyset) = P_{\mu_1}(u, \emptyset)$ or $P_{\mu}(u, \emptyset) = P_{\mu_1}(v, \{u\}) \cdot (v, u)$. The embedding $E_{\mu}(u, \emptyset)$ is obtained by embedding the edge represented by $\mu_2$ on the left side of $E_{\mu_1}(u, \emptyset)$ or $E_{\mu_1}(v, \{u\})$, respectively. Otherwise $\mu_2$ is not a Q-node. It is then necessary that $k \leq 3$ and if $\mu_3$ exists, it must be a Q-node. Now, $(u, \emptyset) \in L(\mu)$ if and only if $(v, \{u\}) \in L(\mu_1)$ and $(v, u) \in L(\mu_2)$. In this case, we define $P_{\mu}(u, \emptyset) = P_{\mu_1}(v, \{u\}) \cdot P_{\mu_2}(v, u)$ and the embedding $E_{\mu}(u, \emptyset)$ is obtained by embedding $E_{\mu_2}(v, u)$ to the left of $E_{\mu_1}(v, \{u\})$ and the edge represented by $\mu_3$, if it exists, to the left of that.

**Case 3: $\mu$ is an S-node.** Let the children of $\mu$ be numbered so that $v$ is a pole of $\mu_1$. Further, we denote by $v_i$ the pole shared by $\mu_i$ and $\mu_{i+1}$ for $i = 1, \ldots, k-1$. To ease the presentation, we also write $v_0 = v$ and $v_{k+1} = u$.

We start with the case that $s \notin \text{pert}(\mu)$; see Fig. 9a. We show how to test whether $(v, u) \in L(\mu)$; the case of $(u, v)$ is analogous. Then $(v, u) \in L(\mu)$ if and only if $(v_{i-1}, v_i) \in L(\mu_i)$ for $i = 1, \ldots, k$. In that case, $P_{\mu}(v, u)$ is obtained by concatenating $P_{\mu_i}(v_{i-1}, v_i)$ for $i = 1, \ldots, k$, while $E_{\mu}(v, u)$ is obtained by merging $E_{\mu_i}(v_{i-1}, v_i)$ for $i = 1, \ldots, k$.

Now, consider the case that $s \in \text{pert}(\mu)$. Consider a pair $(x, Y)$ as above. We show the case $x = u$, the case $x = v$ can be handled analogously. If $s = v$, then we cannot visit $s$, and we proceed as in the case of $(v, u)$ where $s$ is not in pert($\mu$). Now consider the case that $s$ is not a pole; see Figs. 9b to 9d. Let $i$ be the smallest index so that $s$ belongs to pert($\mu_i$) (observe that $s$ belongs to more than one pertinent graphs if and only if it is a vertex of skel($\mu$)). If $i > 2$, then $L(\mu) = \emptyset$, i.e., there is no path from $s$ to $x$ that visits $v_1$; see Fig. 9b. Similarly,
for $i = 2$ we have $(u, Y) \in L(\mu)$ if and only if $\mu_1$ is a Q-node, $Y = \{v\}$, $(v_2, \emptyset) \in L(\mu_2)$, and $(v_{j-1}, v_j) \in L(\mu_j)$ for $j = 3, \ldots, k$; see Fig. 9c. In this case, $P_\mu(x, Y)$ is composed by concatenating $P_{\mu_2}(v_2, \emptyset)$ with $P_{\mu_j}(v_{j-1}, v_j)$ for $j = 3, \ldots, k$, while the embedding $E_\mu(x, Y)$ is obtained by merging the edge representing $\mu_1$ with $E_{\mu_2}(v_2, \emptyset)$ with the embeddings of $E_{\mu_j}(v_{j-1}, v_j)$ for $j = 3, \ldots, k$ If $i = 1$, $(u, Y) \in L(\mu)$ if and only if $(v_1, Y) \in L(\mu_1)$ and $(v_{j-1}, v_j) \in L(\mu_j)$ for $j = 2, \ldots, k$; see Fig. 9d. In this case $P_\mu(x, Y)$ is composed by concatenating $P_{\mu_1}(v_1, Y)$ with $P_{\mu_j}(v_{j-1}, v_j)$ for $j = 2, \ldots, k$ and the embedding $E(x, Y)$ is obtained by merging the embeddings $E_{\mu_1}(v_1, Y)$ and $E_{\mu_j}(v_{j-1}, v_j)$ for $j = 2, \ldots, k$ so that $u$ and $v$ lie on the outer face.

**Case 4: $\mu$ is an R-node.** If $s \notin \text{pert}(\mu)$, then $P_\mu(v, u)$ must traverse every vertex in $\text{pert}(\mu)$, starting with the edge $e$ counterclockwise following the parent edge, with all other edges of $\text{pert}(\mu)$ to the left of $P_\mu(v, u)$. Since $v$, $u$, and $e$ lie on a common face, $P_\mu(v, u)$ follows only this face, so $\text{skel}(\mu)$ is outerplanar; a contradiction, as the skeleton of an R-node is triconnected.

Now, consider the case that $s \in \text{pert}(\mu)$. We start with the case that $s$ is a vertex of $\text{skel}(\mu)$; see Fig. 10. The path $P_\mu(u, Y)$ certainly must traverse the
pertinent graphs of all children that are not Q-nodes and possibly also some of the Q-nodes. To model this, we consider the auxiliary plane graph obtained from skel(µ) by replacing each virtual edge that corresponds to a non-Q-node child by a path of length 2. We now employ the algorithm from Theorem 3 for both embeddings of the auxiliary graph. We try every edge incident to s as a possible starting edge and check when we arrive at u whether all vertices except the vertices in Y have been visited. If this is successful, let v₁,...,vₗ be the corresponding path in skel(µ) and let µᵢ be the child corresponding to the virtual edge {vi,vi+1} for i = 1,...,l − 1. If further (vi,vi+1) ∈ L(µᵢ) for i = 1,...,l − 1, then (v,u) ∈ L(µ). In that case, P_µ(v,u) is obtained by concatenating P_µ(vᵢ,vᵢ+1) for i = 1,...,l − 1 and E_µ(v,u) is obtained from the embedding of the auxiliary graph by replacing each path of length 2 that represents a non-Q-node child µᵢ by E_µ(vᵢ,vᵢ+1). If this test is not successful we repeat the above steps with the flipped embedding of the auxiliary graph.

Otherwise s is contained in a child ν of µ with poles u',v'; see Fig. 11. We consider the same auxiliary graph H as above. Let s' be the vertex on the length-2 path between u' and v' in H. We add the edge (u',v') to H embedded either to the left or to the right of the path (u',s',v'); this way we obtain two different embeddings of the resulting graph. We now employ the algorithm from Theorem 3 for both embeddings. Again, we try both starting edges incident to s and for each of them, we check when we arrive at x whether all vertices except possibly the vertices in Y have been visited. This way, we obtain up to four solutions, depending on the starting edge and whether we use the edge (u',v')
or not. Let $x' \in \{u', v'\}$ such that $(s, x')$ is the starting edge of one such solution. If the path uses the edge $(u', v')$, then we have to check whether $(x', \emptyset) \in L(v)$; otherwise, we have to check whether $(x', \{u', v'\} \setminus \{x'\}) \in L(v)$. If the check is successful, then we compute the corresponding path $P_{\mu}(v, u)$ and embedding $E_{\mu}(v, u)$ as in the case $s \notin \text{pert}(\mu)$. This finishes the description of the R-node.

We conclude by mentioning that the running time stems from the fact that in an R-node that contains $s$, we try $O(n)$ starting edges for the path, where each try takes $O(n)$ time. Therefore, for a fixed pair of endvertices $s, t$ testing the existence of an embedding that is $st$-sided takes $O(n^2)$ time. Since there are $O(n^2)$ pairs of endvertices to try, the overall running time is $O(n^4)$. 

\section{The Rique-number of Complete Graphs}

In this section, we provide bounds on the density of graphs admitting $k$-page RIQ-layouts and on the rique-number of complete graphs.

**Theorem 5.** Any graph $G$ that admits a $k$-page RIQ-layout cannot have more than $(2n + 2)k - k^2 + (n - 3)$ edges.

\textbf{Proof.} Let $v_1, \ldots, v_n$ be the linear order of the vertices and let $E_1, \ldots, E_k$ be the pages of a $k$-page RIQ-layout of $G$. Since, by Theorem 1, each page is a planar graph, it has at most $3n - 6$ edges. Since, however, the $n - 1$ so-called spine edges $(v_i, v_{i+1}), i = 1, \ldots, n - 1$ can be added as head-edges to every page, every page has at most $2n - 5$ non-spine edges. Next, we argue that there exists a $k$-page RIQ-layout $E'_1, \ldots, E'_k$ of $G$ such that each vertex $v_i, 1 \leq i \leq k$ contains edges only on pages $E'_1, \ldots, E'_i$. We start with $E'_i = E_i$, for each $1 \leq i \leq k$.

For $1 \leq i \leq k$, assume that the first $i - 1$ vertices $v_1, \ldots, v_{i-1}$ only have edges in $E'_1, \ldots, E'_{i-1}$ and consider the next vertex $v_i$ (see Fig. 12). If $v_i$ also only has edges in $E'_1, \ldots, E'_{i-1}$, then the claim follows. Otherwise, let $(v_i, v_j), i + 1 \leq j \leq n$ be the edge with $j$ maximal that does not lie in $E'_1, \ldots, E'_{i-1}$ and assume w.l.o.g. that $(v_i, v_j) \in E'_i$. By our assumption, there is no edge that stems from $v_i, \ldots, v_{i-1}$. Further, the edge $(v_i, v_j)$ blocks any possible tail-edge between two vertices in $v_{i+1}, \ldots, v_{j-1}$ in $E'_i$. Hence, all tail-edges that end in a vertex in $v_{i+1}, \ldots, v_{j-1}$ in $E'_i$ stem from $v_i$. Thus, we can add all edges from $v_i$ to $v_{i+1}, \ldots, v_{j-1}$ to $E'_i$ as tail-edges. Since all edges from $v_1, \ldots, v_{i-1}$ to $v_i$ lie in $E'_i, E'_{i+1}, E'_{i+1}$, by the choice of $j$, so do all edges from $v_i$ to $v_{i+1}, \ldots, v_n$. Thus, $E'_{i+1}, \ldots, E_k$ contain no edge of $v_i$. Since any page $E'_i, 1 \leq i \leq k$ contains edges
of at most $n - i + 1$ vertices, it has at most $2(n - i + 1) - 5 = 2n - 2i - 3$ non-spine edges. Hence, the number of edges in $E'_1, \ldots, E'_k$ is at most
\[ n - 1 + \sum_{i=1}^{k} (2n - 2i - 3) = (2n - 4)k - k^2 + (n - 1). \]

We are now ready to present our bounds on the rique-number of $K_n$.

**Theorem 6.**
\[ 0.2929(n - 2) \approx (1 - \frac{1}{\sqrt{2}})(n - 2) \leq \text{rique}(K_n) \leq \lceil n/3 \rceil \approx 0.3333n \]

**Proof.** Let $k = \text{rique}(K_n)$. As $K_n$ has $n(n - 1)/2$ edges, Theorem 5 implies:
\[ (2n - 4)k - k^2 + (n - 1) \geq \frac{n(n - 1)}{2} \Leftrightarrow k^2 - (2n - 4)k + \left(\frac{n^2}{2} - \frac{3n}{2} + 1\right) \leq 0 \]

The inequality above then gives the claimed lower bound as follows:
\[ k \geq n - 2 - \frac{\sqrt{2}}{2} \sqrt{(n - 2)(n - 3)} \geq n - 2 - \frac{\sqrt{2(n - 2)}}{2} = (1 - \frac{1}{\sqrt{2}})(n - 2) \]

We now show how to compute a layout of $K_n$ with $\lceil n/3 \rceil$ pages. Assume w.l.o.g. that $n$ is divisible by 3. Take an arbitrary stack layout of the clique on vertices $v_{n/3+1}, \ldots, v_n$ on $n/3$ pages [12]. Then put on page $i$ all edges of vertex $v_i$ as tail-edges; see Fig. 13.

We conclude this section with a few more insights on the rique-number of complete graphs, which we derived by adjusting a formulation of the book embedding problem as a SAT instance [11]; for details see Appendix B. This adjustment allowed us to obtain bounds on the rique-number of $K_n$ for values of $n$ in $[4, \ldots, 27]$; see Table 1 and Figs. 14 and 15 for page-minimal layouts of $K_7$ and $K_{11}$. 

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**Table 1:** A summary of our results on the rique-number of $K_n$

| $n$     | 4  | 5–7 | 8–11 | 12–14 | 15–17 | 18–21 | 22   | 23–24 | 25   | 26–28 |
|---------|----|-----|------|-------|-------|-------|------|-------|------|-------|
| $\text{rique}(K_n)$ | 1  | 2   | 3    | 4     | 5     | 6     | 6 or 7 | 7     | 7 or 8 | 8     |
6 Conclusions and Open Problems

In this work, we continued the study of linear layouts of graphs in relation to known data structures, in particular, in relation to the restricted-input deque. Several problems are raised by our work: (i) the most important one is the complexity of the recognition of graphs with rique-number 1, (ii) another quite natural problem is to further narrow the gap between our lower and upper bounds on the rique-number of $K_n$; our experimental results indicate that there exist room for improvement in the upper bound, (iii) for complete bipartite graphs, we did not manage to obtain improved bounds (besides the obvious ones that one may derive from their stack- or queue-number), (iv) another interesting question regards the rique-number of planar graphs, which ranges between 2 and 4 (i.e., the upper bound by their stack-number); the same problem can be studied also for subclasses of planar graphs (e.g., planar 3-trees).

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A Omitted Material from Section 2

The SPQR-tree $T$ of a biconnected graph $G = (V, E)$ is a tree such that each node $\mu$ of $T$ is associated with a multigraph $\operatorname{skel}(\mu)$, called the skeleton of $\mu$, and whose edges can be either real edges or virtual edges, and whose vertex sets are subsets of $V$. The leaves of the SPQR-tree are Q-nodes, whose skeleton consists of two vertices that are joined by one real edge and by one virtual edge that represents the rest of the graph. The internal nodes of $T$ are either S-, P- or R-nodes, depending on their skeleton. The skeleton of an S-node is a simple cycle of virtual edges, the skeleton of a P-node consists of two vertices that are joined by at least three parallel virtual edges, and the skeleton of an R-node is a triconnected graph consisting of virtual edges. Each edge $\mu \nu$ of $T$ is associated with two virtual edges, one in $\operatorname{skel}(\mu)$ and one in $\operatorname{skel}(\nu)$ that have the same endpoints in such a way that we obtain for each node $\mu$ a bijection between the virtual edges of $\operatorname{skel}(\mu)$ and the edges of $T$ incident to $\mu$. Further no two S-nodes and no two P-nodes are adjacent in $T$.

For an edge $\mu \nu$ of $T$, the skeletons $\operatorname{skel}(\mu)$ and $\operatorname{skel}(\nu)$ can be joined by identifying the endpoints of the virtual edges corresponding to the edge $\mu \nu$ and then removing the virtual edge that corresponds to $\mu \nu$. The key property of the SPQR-tree of $G$ is that by joining along all tree edges, we obtain the graph $G$. If each skeleton is further equipped with a planar embedding, then joining them yields a planar embedding of $G$, and in fact all planar embeddings of $G$ can be obtained in this way. Note that, due to the restricted nature of the skeletons, the embedding choices for skeletons are limited: S- and Q-nodes have a unique planar embedding, whereas in a P-node we can arbitrarily permute the order of the virtual edges and an R-node has a unique planar embedding up to reflection. Rooting the SPQR-tree at a Q-node corresponding to some reference edge $st$, defines for each non-root node $\mu$ a unique parent edge in $\operatorname{skel}(\mu)$, namely the virtual edge that corresponds to the edge connecting $\mu$ to its parent. We call the endpoints of the parent edge of $\operatorname{skel}(\mu)$ the poles of $\mu$. If we additionally restrict the choices of the planar embeddings of the skeletons so that the parent edge is incident to the outer face, the SPQR-tree represents exactly those planar embeddings of $G$ where the reference edge $st$ is incident to the outer face. The pertinent graph $\operatorname{pert}(\mu)$ of a node $\mu$ is the subgraph represented by $\mu$ and all its children; it can be obtained by joining $\mu$ and all nodes below $\mu$. The pertinent graph of the root is $G$ itself.

B Omitted Material from Section 4

In our formulation, there exist three different types of variables, denoted by $\sigma$, $\phi$ and $\chi$, with the following meanings: (i) for a pair of vertices $u$ and $v$, variable $\sigma(u, v)$ is true, if and only if $u$ is to the left of $v$ along the spine, (ii) for an edge $e$ and a page $i$, variable $\phi_i(e)$ is true, if and only if edge $e$ is assigned to page $i$ of the book, and (iii) for a pair of edges $e$ and $e'$, variable $\chi(e, e')$ is true, if and only if $e$ and $e'$ are assigned to the same page. Hence, there exist
in total \(O(n^2 + m^2 + pm)\) variables, where \(n\) denotes the number of vertices of the graph, \(m\) its number of edges, and \(p\) the number of available pages. A set of \(O(n^3 + m^2)\) clauses ensures that the underlying order is indeed linear, and that no two edges of the same page cross; for details we point the reader to [11]. In our formulation, we neglected the clauses ensuring that edges of the same page do not cross, and we introduced clauses ensuring the absence of Pattern P.1 of Lemma 1. In particular, for every triplet of edges \((a, a'), (b, b')\) and \((c, c')\), we can guarantee that they do not form Pattern P.1 by the following clause:

\[
\sigma(a, b) \land \sigma(b, c) \land \sigma(c, b') \land \sigma(b', a') \land \sigma(b', c') \rightarrow
\neg(\chi(((a, a'), (b, b')) \land \chi((b, b'), (c, c'))) \land \chi((a, a'), (c, c')))
\]

With the aforementioned formulation we were able to derive bounds on the rique-number of \(K_n\) for values of \(n\) in \([4, \ldots, 27]\); see Table 1 for an overview and Figs. 14 and 15 for page-minimal drawings of \(K_7\) and \(K_{11}\). For \(K_{22}\) and \(K_{25}\), we could not find the exact number and stopped the computation after 1 week.