Nonequilibrium phases and segregation for skyrmions on periodic pinning arrays
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Phys. Rev. B 98, 134418 — Published 11 October 2018
DOI: 10.1103/PhysRevB.98.134418
I. INTRODUCTION

Numerous systems can be modeled as a collection of interacting particles that are coupled to an underlying periodic substrate. The ratio of the number of particles to the number of substrate minima, known as the filling factor, can be an integer, a rational fraction, or an irrational fraction. As a function of filling factor, different types of crystalline, partially disordered, and disordered states can arise depending on the symmetry of the underlying substrate\(^1\).\(^2\). Commensuration effects arise for certain integer or rational filling factors that strongly affect the static and dynamic phases\(^3\).\(^4\). Examples of systems exhibiting commensuration behavior include atoms on ordered substrates\(^5\), colloids interacting with two-dimensional periodic substrates\(^1\),\(^6\)–\(^9\), vortices in type-II superconductors with periodic pinning arrays\(^2\),\(^10\)–\(^14\), and vortices in Bose Einstein condensates with optical trap arrays\(^15\),\(^16\). Under an applied drive, a rich variety of distinct sliding phases appear\(^4\). The critical driving force \(F_c\) needed to induce depinning typically exhibits a maximum at commensurate fillings, while incommensurate fillings contain localized regions with a lower depinning threshold that produce a flow of soliton-like excitations at depinning, followed at increasing driving forces by additional dynamical phases as the other particles depin in a multi-step depinning process\(^1\),\(^2\),\(^4\),\(^9\),\(^17\)–\(^25\). These systems also exhibit a variety of different types of sliding phases, including the soliton-like motion of interstitials or vacancies, grain boundary flow, chains of flowing particles moving around pinned particles, disordered or strongly fluctuating flow phases, and coherent moving crystal phases. Transitions between the sliding phases can be characterized by changes in the velocity-force curves, fluctuations, and structure of the particles\(^17\).

Vortices in type-II superconductors pass through a particularly rich set of static and dynamic phases when interacting with a periodic substrate. Commensuration effects produce peaks in the critical current or the force needed to depin vortices at certain integer\(^2\),\(^9\),\(^12\)–\(^14\),\(^26\) and rational filling factors\(^27\)–\(^29\). The pinning lattice consists of localized sites that can capture one or more vortices. Additional vortices that are not in the pinning sites sit in the interstitial regions between occupied pinning sites, and the combination of directly pinned vortices and indirectly pinned interstitial vortices produces the variety of dynamical phases found in simulations\(^18\),\(^27\),\(^30\)–\(^35\) and experiments\(^1\),\(^26\),\(^36\),\(^37\).

Skyrmions in chiral magnets\(^38\)–\(^43\) have many similarities to superconducting vortices. The skyrmions are particle-like magnetic textures that form triangular lattices, can be driven with an applied current, and also exhibit depinning and sliding phases\(^40\),\(^44\)–\(^50\). One of the key differences between skyrmions and superconducting vortices is that the skyrmion dynamics is strongly influenced by a Magnus force, produced by the skyrmion topology, which generates velocity components perpendicular to the forces experienced by the skyrmion\(^40\),\(^44\),\(^46\),\(^47\). Due to the Magnus force, the skyrmions move at an angle called the skyrmion Hall angle \(\theta_{sk}\) with respect to the direction of the externally applied drive. As a skyrmion passes through a pinning site, its trajectory describes an arc which reduces the effective pinning threshold and also shifts the position of the skyrmion in a side jump effect. As a result, the skyrmion Hall angle varies with applied current. In the presence of pinning, \(\theta_{sk} = 0\) at the depinning threshold, and as the skyrmion velocity increases with increasing current, \(\theta_{sk}\) also increases until it saturates to the clean or intrinsic value \(\theta_{sk}^{int}\) at high drives. This behavior was first observed in particle-based simulations\(^51\)–\(^54\) and was subsequently verified in experiments\(^55\)–\(^57\). Continuum-based simulations with pinning also show that the skyrmion Hall angle...
is drive dependent\textsuperscript{58,59}, which provides further evidence that particle-based simulations capture many of the essential features of the skyrmion dynamics.

With the recent advances in creating nanostructured materials that support skyrmions, it should be possible to create carefully controlled periodic structures or pinning arrays for skyrmions, and in this work we use particle-based simulations to investigate the dynamics of skyrmions in square pinning arrays. In addition to the skyrmion physics, we address the general question of how the collective dynamics of particle assemblies on periodic substrates change in the presence of a non-dissipative Magnus force, and what new dynamic phases arise that are absent in the overdamped limit. Previous work on individual skyrmions moving over two-dimensional periodic substrates showed that the Magnus force strongly affects the dynamics\textsuperscript{52}. Specifically, the drive dependence of the skyrmion Hall angle produces quantized steps in $\theta_{sk}$ as a function of driving current when the skyrmion locks to different symmetry directions of the substrate\textsuperscript{52}.

In this work we study collectively interacting skyrmions on a periodic substrate, where new dynamics emerge that are not present for an isolated skyrmion. In the overdamped limit, we find interstitial flow, disordered flow, and moving crystal flow phases, in agreement with previous work on vortices in periodic pinning arrays\textsuperscript{17,18,52,36,37}. Upon introducing a nonzero Magnus force, these same three phases persist in the form of an interstitial flow that can lock to various symmetry angles of the substrate, a disordered flow phase, and a moving crystal phase. When both the substrate strength and the Magnus force are sufficiently large, we observe a transition to a moving clustered or segregated state that is similar to the skyrmion cluster state found in continuum-based simulations with strong pinning\textsuperscript{60}. In our case, the clustering instability arises from the strong velocity dependence of $\theta_{sk}$ that appears when the pinning is strong. The skyrmions form bands traveling at different relative velocities, and these bands move toward one another. We observe a similar clustering effect for strong randomly placed pinning which will be described elsewhere. When the pinning is weak, the clustering effect is lost and we observe an Aubry type transition\textsuperscript{61,62} on the square pinning lattice, where the pinned skyrmion lattice transitions to a floating triangular skyrmion lattice with a much lower depinning threshold. As the filling factor changes, we find several commensurate-incommensurate transitions leading to the stabilization of different types of pinned skyrmion crystalline states that are identical to those that occur in the overdamped limit since the ground configurations are not affected by the Magnus force. We also show that it is possible to have different types of moving segregated states such as a diagonal stripe phase in which the stripes move at an angle with respect to the major symmetry axis of the pinning substrate.

The paper is organized as follows. In Section II, we describe our simulation. In Section III we illustrate the dynamic phases with emphasis on the phase separated states, and we construct a dynamical phase diagram as a function of drive and pinning strength. Directional locking effects occur due to the periodicity of the pinning. In Section IV we study the effect of changing the relative strength of the Magnus force on the dynamic phases. The effect of varying the filling factor appears in Section V. In Section VI we consider the effect of changing the pinning density while holding the filling factor constant. We summarize our results in Section VII.

II. SIMULATION

We utilize a particle-based model for skyrmions based on a modified Thiele equation that takes into account skyrmion-skyrmion and skyrmion-pin interactions\textsuperscript{47,51-54,64}. This model has previously been shown to capture several features of skyrmion dynamics including the orientation of skyrmion lattices, pinning phenomena, and the drive dependence of the skyrmion Hall angle when pinning is present. We consider a two-dimensional system of size $L \times L$ with periodic boundary conditions in the $x$- and $y$-directions containing $N_{sk}$ skyrmions and $N_p$ pinning sites. The filling factor is $\alpha = N_{sk}/N_p$. For most of this work we hold the number of pinning sites fixed and vary $N_{sk}$, which can be achieved experimentally by changing the applied magnetic field.

The skyrmion dynamics are governed by the following equation of motion\textsuperscript{47}:

$$\alpha_d \dot{v}_i + \alpha_m \ddot{z} \times v_i = F_\text{ss}^i + F_\text{pp}^i + F_\text{D}^i. \quad (1)$$

The velocity of skyrmion $i$ is $v_i = \text{d}r_i/\text{d}t$, while $\alpha_d$ and $\alpha_m$ are the damping and Magnus terms, respectively. The damping term can be written as $\alpha_d = -\alpha \eta_0 D$ where $\alpha$ is the Gilbert damping coefficient and $D = \frac{\xi}{8\gamma_{\text{dw}}}$. Here $\xi$ is the skyrmion diameter, $\gamma_{\text{dw}} = \pi\sqrt{A/K_{\sigma}}$, and $A$ is the spin-wave exchange stiffness, and $K_{\sigma}$ is the effective perpendicular magnetic anisotropy. The skyrmion-skyrmion interaction force is repulsive and takes the form\textsuperscript{47}:

$$F_\text{ss}^i = \sum_{j=1}^{N_{sk}} K_1(|r_{ij}|) \hat{r}_{ij},$$

where $K_1$ is the modified Bessel function, $r_{ij} = |r_i - r_j|$ is the distance between skyrmions $i$ and $j$, and $\hat{r}_{ij} = (r_i - r_j)/r_{ij}$. The unit of force $F_0$ is equal to the skyrmion-skyrmion repulsive force per length at a separation of $l_0 = \frac{\xi}{\sqrt{K_{\sigma}}}$ where the skyrmion density $n_{sk} = N_{sk}/L^2$. The driving force $F_\text{D}^i = F_D \dot{x}$ represents an applied current. The magnitude of the current that would produce a force of magnitude $F_D$ is given by $J = (e/h)F_D$. In the absence of pinning the skyrmions move at the intrinsic skyrmion Hall angle $\theta_{sk}^{\text{int}} = \tan^{-1}(\alpha_m/\alpha_d)$ with respect to the driving direction. The pinning sites are modeled as localized parabolic potentials with a fixed radius $R_p$ and strength $F_p$:

$$F_p^i = \sum_{k=1}^{N_p} \frac{(F_p r_{ik}^p/R_p) \Theta(R_p - r_{ik}^p) r_{ik}^p}{r_{ik}^p}$$

where $r_{ik}^p = |r_i - r_k^p|$, $F_{ik}^p = (r_i - r_k^p)/r_{ik}^p$, and $\Theta$ is the Heaviside step function. This same pinning model was previously used to study
the statics and dynamics of superconducting vortices in periodic pinning arrays\textsuperscript{18,27,30,32–34}.

The initial skyrmion positions are obtained by simulated annealing, in which we start from a high temperature liquid state and gradually cool to $T = 0$. After annealing we gradually increase the driving force in increments of $\delta F_D = 0.002$, waiting 20000 simulation time steps between increments to ensure that the system has reached a steady state. For small values of $F_p$ we have tested increments as small as $\delta F_D = 1 \times 10^{-6}$ to verify that the results are not affected by the choice of $\delta F_D$. We measure $\langle v_i \rangle = N_{sk}^{-1}\sum_{i=1}^{N_{sk}} v_i^i$ in the directions parallel and perpendicular to the drive, respectively, where $v_i^i = v_i \cdot \hat{x}$ and $v_i^\perp = v_i \cdot \hat{y}$, and we use these quantities to obtain the velocity ratio $R = \langle V_\perp \rangle/\langle V_\parallel \rangle$ and the measured skyrmion Hall angle $\theta_{sh} = \tan^{-1}(R)$. We also measure a quantity related to the standard deviation of the skyrmion velocities in the parallel and perpendicular directions, $\delta V_\parallel = \sqrt{\langle \sum_{i=1}^{N_{sk}} (v_i^i)^2 \rangle/ N_{sk}}$ and $\delta V_\perp = \sqrt{\langle \sum_{i=1}^{N_{sk}} (v_i^\perp)^2 \rangle/ N_{sk}}$. To quantify the amount of ordering in the skyrmion lattice, we use the fraction of sixfold-coordinated skyrmions, $P_6 = N_{sk}^{-2}\sum_{i=1}^{N_{sk}} \delta(6-z_i)$, where $z_i$ is the coordination number of skyrmion $i$ obtained from a Voronoi tessellation. For a perfect triangular lattice, $P_6 = 1$. We fix $L = 36$, $R_p = 0.35$, and $N_p = 256$ while varying $F_p$, $\alpha_m/\alpha_d$, and $N_{sk}$, except in Section VI where we consider varied pinning density $n_p = N_p/L^2$.

### III. Dynamic Phases and Clustering

In Fig. 1(a) we plot the velocity-force curve $\langle V_i \rangle$ versus $F_D$ for a system with $f = 1.0117$, a pinning density of $n_p = 0.1975$, $F_p = 2.0$, and $\alpha_m/\alpha_d = 9.96$. The $\langle V_i \rangle$ versus $F_D$ curve (not shown) has the same shape but is larger in magnitude. Figure 1(b) shows the mean square deviations in the instantaneous velocities for both the parallel $\delta V_\parallel$ and perpendicular $\delta V_\perp$ directions versus $F_D$, while Fig. 1(c) shows the corresponding fraction of six-fold coordinated skyrmions $P_6$ versus $F_D$. The vertical dashed lines highlight the five different dynamic phases that arise. Phase I is a pinned state with $\langle V_i \rangle = \langle V_\parallel \rangle = 0$. As illustrated in Fig. 2(a) at $F_D = 0$, the skyrmions form a commensurate square lattice with a small number of additional skyrmions in the interstitial regions between pinning sites. Phase II consists of interstitial flow, in which only the interstitial skyrmions depin and move around the commensurate skyrmions, which remain pinned. The flow in phase II exhibits a series of directional locking effects which we explore in detail in Section III A. The value of $\langle V_i \rangle$ is small but finite, and there are jumps in $\delta V_\parallel$, $\delta V_\perp$, and $P_6$ at both ends of the interval $0.15 < F_D < 0.7$ where phase II occurs, as shown in Fig. 1. Within phase II the overall lattice structure is similar to that of phase I since most of the skyrmions remain pinned. Upward jumps in $\langle V_\parallel \rangle$, $\delta V_\parallel$, and $\delta V_\perp$ mark the onset of the disordered flow phase III, which appears in the interval $0.7 \leq F_D \leq 2.01$, and consists of a combination of pinned and flowing skyrmions as illustrated in Fig. 2(b) at $F_D = 1.0$.

Near $F_D = 2.0$ there is a transition to the clustered or segregated state, shown in Fig. 2(c) at $F_D = 3.0$, where the skyrmions clump into a dense stripe. We call this the segregated or phase separated phase PS. There is an upward jump in $\delta V_\parallel$ at the III-PS transition, and $\delta V_\parallel$ remains larger than $\delta V_\perp$ throughout the PS phase due to the alignment of the stripe with the driving direction. This phase separated state is very similar to that observed in continuum-based simulations of skyrmions moving over random pinning\textsuperscript{60}, and we find that the phase separation occurs only when the pinning is sufficiently strong, in agreement with the continuum-based results. The creation of the segregated state in the continuum models was attributed to the emission of spin waves that produce an effective attraction between the skyrmions\textsuperscript{60}. In our system, no spin waves are present, and the segregation occurs due to the velocity dependence of the skyrmion Hall angle in the presence of pinning. If different regions of the system are moving at different relative
FIG. 2: Skyrmion (blue dots) and pinning site (red circles) locations at one instant in time for the system in Fig. 1 with \( f = 1.0117, F_p = 2.0, n_p = 0.1975 \), and \( \alpha_m/\alpha_d = 9.96 \).

(a) The pinned phase I at \( F_D = 0 \). (b) The disordered flow phase III at \( F_D = 1.0 \). (c) The segregated or phase separated phase PS at \( F_D = 3.0 \). (d) The moving crystal phase MC at \( F_D = 5.5 \).

velocities, each region will have a different skyrmion Hall angle, causing the skyrmions in adjacent regions to gradually move toward one another. In Fig. 2(c), the bottom three rows of the stripe form a square lattice structure that is partially commensurate with the pinning sites, so that in this region of the stripe, the local filling factor is close to \( f_{\text{loc}} = 1 \). The net skyrmion velocity is reduced close to commensuration, so the value of \( \theta_{sk} \) is smaller in this region. The upper region of the stripe is denser with \( f_{\text{loc}} > 1 \), and this incommensurate state has a higher net skyrmion velocity and a correspondingly larger value of \( \theta_{sk} \). As a result, there are velocity and \( \theta_{sk} \) differentials across the sample, causing the larger \( \theta_{sk} \) skyrmions to collide with the smaller \( \theta_{sk} \) skyrmions. The skyrmions develop a nonuniform density profile that permits the commensurate and incommensurate regions to slide past each other in the driving direction, preserving a nonuniform velocity profile and producing an increased velocity variation \( \delta V_{||} \) in the PS phase, as shown in Fig. 1(b). At larger values of \( F_D \), \( \theta_{sk} \) begins to saturate as shown in previous simulations\(^{51-54,58,59} \) and experiments\(^{55} \), destroying the spatial differential in \( \theta_{sk} \) and allowing the skyrmions to form a moving crystal state (MC), as illustrated in Fig. 2(d) at \( F_D = 5.5 \). The PS-MC transition is accompanied by drops in \( \delta V_{||} \) and \( \delta V_{\perp} \), which become nearly isotropic, along with an upward jump in \( P_b \) to a value just below \( P_b = 1.0 \). The drops in \( \delta V_{||} \) and \( \delta V_{\perp} \) in the MC phase occur since the skyrmions are all moving at the same velocity.

### A. Directional locking

In Fig. 3(a,b) we plot the differential mobility \( d\langle V_{||}\rangle/dF_D \) and the velocity ratio \( R = \langle V_{\perp}\rangle/\langle V_{||}\rangle \) versus \( F_D \) for the system in Fig. 1. Pronounced peaks appear in \( d\langle V_{||}\rangle/dF_D \) across the I-II and II-III transitions, along with smaller peaks at the III-PS and PS-MC transitions. The velocity ratio is zero in phase I, and increases in phases II and III until it is close to the intrinsic value \( R_{\text{int}} = \alpha_m/\alpha_d \) near the onset of the PS state. Within phase II, a series of steps appear in \( R \) when the interstitial skyrmion flow passes through a sequence of directionally locked states as \( F_D \) increases, similar to the previously studied directional locking of skyrmion motion on square arrays in the single skyrmion limit\(^{52} \). These locking effects occur due to the velocity dependence of the skyrmion Hall angle in the presence of pinning, which causes the direction of skyrmion motion to rotate with increasing \( F_D \). Due to the underlying symmetry of the pinning potential the rotation is not continuous; instead, the motion becomes locked at integer values of \( R \). The steps in Fig. 3(b) appear at \( R = 2, 3, 4, 5 \) and \( 6 \), but all higher locking plateaus are cut off when the system enters phase III. Within phase III, \( R \) increases smoothly, and small dips in \( R \) appear at the III-PS and PS-MC transitions together with small peaks in the differential mobility in Fig. 3(a).
In Fig. 4(a) we plot $\theta_{sk} = \tan^{-1}(R)$ versus $F_D$, showing more clearly that $\theta_{sk}$ is quantized in phase II. The integer ratio $R = 3$ corresponds to the step at $\theta_{sk} = 71.56^\circ$, and there are also steps for the $R = 4$, $R = 5$, and $R = 6$ ratios, with the latter corresponding to the step at $\theta_{sk} = 80.53^\circ$. Much smaller steps appear at some rational fractional values of $R$ similar to what was observed in the single skyrmion limit. In Fig. 4(b) we show $\theta_{sk}$ versus $F_D$ across the III-PS and PS-MC transitions. There is a drop in $\theta_{sk}$ at the III-PS transition caused when the more slowly moving commensurate skyrmions block the flow of the faster moving incommensurate skyrmions, reducing the net velocity in the perpendicular direction and thereby reducing both $R$ and $\theta_{sk}$. When the PS structure destabilizes at the PS-MC transition, the skyrmions begin to move at a uniform velocity in the MC phase, eliminating the blocking of the flow of faster skyrmions by slower skyrmions, and causing $\theta_{sk}$ to increase.

Some experimental techniques cannot directly access the real-space position of the skyrmions but instead measure the structure factor $S(k) = N_{sk}^{-1} \sum_i N_i \exp(-i \mathbf{k} \cdot \mathbf{r}_i)^2$. Figure 5(a) shows that $S(k)$ in phase I for the system in Fig. 1(a) has square symmetry since the skyrmions are predominantly localized in the square pinning array. In the interstitial flow phase II, $S(k)$ also has strong square ordering since most of the skyrmions remain pinned. In the disordered flow phase III, where a combination of pinned and flowing skyrmions appear, $S(k)$ exhibits a smearing due to the positional disorder, as shown in Fig. 5(b); however, there is still significant weight at the square lattice wavevectors due to the pinned skyrmions. In the PS phase illustrated in Fig. 5(c), $S(k)$ contains a series of peaks along the $k_y$ axis, indicative of smectic or stripe like ordering. An additional ring-like structure appears at larger values of $k$ due to the partial disordering of the skyrmions within the stripe. In the MC phase, $S(k)$ reveals strong triangular ordering, as highlighted in Fig. 5(d). These results show that the different phases have distinct signatures in both real and reciprocal space, and that transitions between the phases are associated with changes in $\theta_{sk}$ and the transport properties.

**B. Varied pinning strength**

We next consider the evolution of the phases for the system in Fig. 1 for varied pinning strength $F_p$. In Fig. 6 we plot $\langle V_\parallel \rangle$, $\delta V_\parallel$, $\delta V_\perp$, and $P_\parallel$ versus $F_D$ for samples with $f = 1.0117$, $n_p = 0.1975$, and $\alpha_m/\alpha_d = 9.96$ at a larger $F_p = 3.0$. The III-PS and PS-MC transitions both shift to higher values of $F_D$ compared to the $F_p = 2.0$ case. Although the overall behavior is similar for both values of $F_p$, in Fig. 6 we find a reentrant pinned phase falling between phases II and III over the range $0.7 < F_D < 1.35$. In the $F_D = 0$ pinned phase I, the interstitial skyrmions are pinned by the interactions with skyrmions located at the pinning sites. The interstitial skyrmions depin and experience a series of di-
reentrant directional locking transitions in phase II, but the stronger pinning sites are able to capture and repin the interstitial skyrmions when the changing direction of motion causes the skyrmions to pass directly over the pinning sites, producing the reentrant pinned phase $I_{re}$. For lower $F_p$, each pinning site can capture only one skyrmion, so the reentrant pinning does not occur; however, for $F_p > 2.5$, a sufficiently large value of $F_D$ can shift the already pinned skyrmion far enough to the edge of the pinning site to permit a second skyrmion to enter the other side of the pinning site and become trapped in phase $I_{re}$. At $F_D > 1.3$ for the $F_p = 3.0$ system, the drive is strong enough to depin the doubly occupied pinning sites, and the system transitions to disordered phase III flow. In general, we find that the same phases persist as $F_p$ is further increased, with the width of the $I_{re}$ region increasing. When $F_p$ becomes sufficiently large, the interstitial skyrmions become trapped in doubly-occupied pinning sites all the way down to $F_D = 0$, causing phase II to disappear. We also find that the jump in $P_e$ at the PS-MC transition becomes less sharp for stronger $F_p$.

In Fig. 7 we plot $\langle V_\parallel \rangle$, $\delta V_\parallel$, $\delta V_L$, and $P_e$ versus $F_D$ for the same system in Fig. 6 but at a weaker $F_p = 0.75$. We again observe phases I, II, III, PS, and MC; however, a diagonal phase separated state called phase DPS now appears between phases II and III. In the DPS phase, $\langle V_\parallel \rangle$ gradually decreases with increasing $F_D$ as shown in Fig. 7(a). We illustrate the DPS flow at $F_D = 0.25$ in Fig. 8(a), where the skyrmions form a series of dense bands at an angle to the driving direction. One distinction between the DPS and PS phases is that in the DPS phase there is a combination of pinned skyrmions and moving skyrmions, whereas in the PS phase, all the skyrmions are moving. At higher driving the system undergoes uniform disordered phase III flow before transitioning into the PS phase shown in Fig. 8(b) for $F_D = 1.5$. In general, as $F_p$ decreases, the width of the stripe in the PS phase increases. Near $F_D = 2.0$, the system transitions into the MC phase.

In Fig. 9 we plot $\langle V_\parallel \rangle$, $\delta V_\parallel$, $\delta V_L$, and $P_e$ versus $F_D$ for the system in Fig. 6 at $F_p = 0.2$, where phase II is lost and the system transitions directly from phase I to phase DPS. At lower values of $F_p$ such as this, the repulsion between the interstitial skyrmions and the skyrmions at the pinning sites is strong enough that when the interstitial skyrmions depin, their motion causes the skyrmions in the neighboring pinning sites to depin as well, destroying the interstitial flow phase II. The PS phase is also lost and phase III is followed immediately by the MC phase. As $F_p$ decreases, the spatial width of the bands in the DPS phase increases, as illustrated in Fig. 8(c) for the system in Fig. 9 at $F_D = 0.075$. The disordered flow phase III in the same system is much more uniform than the phase III flow found at higher values of $F_p$, as shown in Fig. 8(d) at $F_D = 0.55$. The DPS-III transition is relatively sharp and appears as a jump down in $\delta V_\parallel$ and $\delta V_L$ along with a jump up in $P_e$. There is also a dip in $\langle V_\parallel \rangle$ indicating a drop in the average velocity of the skyrmions in the direction of drive at the DPS-III transition, as shown more clearly in the zoomed-in plot.

**Fig. 6:** (a) $\langle V_\parallel \rangle$ vs $F_D$ for a system with $f = 1.0117$, $\eta_p = 0.1975$, $\alpha_m/\alpha_d = 9.96$, and larger $F_p = 3.0$. (b) The corresponding $\delta V_\parallel$ (blue) and $\delta V_L$ (red) vs $F_D$. (c) The corresponding $P_e$ vs $F_D$. Dashed lines indicate the boundaries between the phases. I: pinned; II: interstitial flow; $I_{re}$: reentrant pinned; III: disordered flow; PS: phase separated; MC: moving crystal.

**Fig. 7:** (a) $\langle V_\parallel \rangle$ vs $F_D$ for a system with $f = 1.0117$, $\eta_p = 0.1975$, and $\alpha_m/\alpha_d = 9.96$ at $F_p = 0.75$ where a diagonal phase separated state, phase DPS, appears as illustrated in Fig. 8(a). (b) The corresponding $\delta V_\parallel$ (blue) and $\delta V_L$ (red) vs $F_D$. (c) The corresponding $P_e$ vs $F_D$. Dashed lines indicate the phase boundaries. I: pinned; II: interstitial flow; DPS: diagonal phase separated; III: disordered flow; PS: phase separated; MC: moving crystal.
of Fig. 10(a). This dip creates a regime of negative differential conductivity where $d\langle V_\parallel \rangle/dF_D < 0$, illustrated in Fig. 10(b).

When $F_p < 0.02$, in the absence of driving there is a transition from a commensurate solid where the skyrmions are predominantly located at the pinning sites to a floating solid where the skyrmions form a triangular lattice that is only weakly coupled to the pinning lattice. This transition is accompanied by a drop in the depinning threshold force $F_c$. In Fig. 11(a,b,c) we show $\langle V_\parallel \rangle$, $\delta V_\parallel$, $\delta V_\perp$, and $P_0$ versus $F_D$ for the system in Fig. 6 at $F_p = 0.015$. Here $P_0$ is close to 1.0 for all values of $F_D$, so the skyrmions depin directly from a weakly pinned floating solid into a moving crystal. The depinning transition is elastic so all of the skyrmions keep their same neighbors. Additionally, both $\delta V_\parallel$ and $\delta V_\perp$ are small and vary only weakly with $F_D$ due to the slow rotation of the skyrmion lattice with increasing $F_D$ that occurs as the triangular lattice remains oriented with the direction of motion.

By conducting a series of simulations for varied $F_p$ and $F_D$, and examining the changes in the transport signatures and structural properties, we can construct a dynamical phase diagram as a function of $F_D$ versus $F_p$, as shown in Fig. 12 for a system with $f = 1.0117$, $n_p = 0.1975$, $\alpha_m/\alpha_d = 9.96$, and $F_p = 0.2$. Here phase II is lost and the system depins directly from phase I to phase DPS. (b) The corresponding $\delta V_\parallel (\text{blue})$ and $\delta V_\perp (\text{red})$ vs $F_D$. (c) The corresponding $P_0$ vs $F_D$. Dashed lines indicate the phase boundaries. I: pinned; DPS: diagonal phase separated; III: disordered flow; MC: moving crystal.

FIG. 8: (a,b) Skyrmion (blue dots) and pinning site (red circles) locations at one instant in time for the system in Fig. 7 with $f = 1.0117$, $n_p = 0.1975$, $\alpha_m/\alpha_d = 9.96$, and $F_p = 0.75$. (a) The diagonal phase separated state DPS at $F_D = 0.25$, where multiple diagonal phase separated bands appear. (b) The phase separated PS state at $F_D = 1.5$, where the skyrmion density is more uniform. The pinning sites are not shown for clarity. (c,d) Skyrmion and pinning site locations for a system with $f = 1.0117$, $n_p = 0.1975$, $\alpha_m/\alpha_d = 9.96$, and $F_p = 0.2$. (c) The DPS phase at $F_D = 0.075$, where only one band of skyrmions forms. (d) Phase III flow at $F_D = 0.55$. The pinning sites are not shown for clarity.
FIG. 10: (a) A blowup of $\langle V_{||} \rangle$ vs $F_D$ for the system in Fig. 9 with $f = 1.0117$, $n_p = 0.1975$, $\alpha_m/\alpha_d = 9.96$, and $F_p = 0.2$ in the region containing the I-DPS and DPS-III transitions. A dip in $\langle V_{||} \rangle$ appears at the DPS-III transition, producing negative differential conductivity, $d\langle V_{||} \rangle/dF_D < 0$. (b) $d\langle V_{||} \rangle/dF_D$ vs $F_D$ for the same system. For clarity, this data has been subjected to a running average in order to reduce the noise.

FIG. 11: (a) $\langle V_{||} \rangle$ vs $F_D$ for a system with $f = 1.0117$, $n_p = 0.1975$, and $\alpha_m/\alpha_d = 9.96$ at $F_p = 0.015$, where the skyrmions depin elastically from a floating triangular solid to a MC state. (b) The corresponding $\delta V_{||}$ (blue) and $\delta V_\perp$ (red) vs $F_D$. (c) The corresponding $P_6$ vs $F_D$.

III flow before reaching the MC state. In Fig. 13(b) we plot $P_6$ vs $F_p$ at $F_D = 0$, showing that $P_6$ drops across the IC-PC transition from $P_6 \approx 1.0$ in the IC state to $P_6 \approx 0.75$ in the PC state. The dynamic phase diagram shown in Fig. 13(a) is similar to that observed for weak random pinning, with the pinned crystal depinning elastically into a moving crystal, where the pinned commensurate crystal in the periodic pinning array is replaced by a disordered pinned glassy state in the random pinning array. We note that Ref. 51 focused on random pinning in the limit below the pinning strength at which dynamical segregation occurs. The PC-IC transition and the associated drop in $F_c$ are similar to what is observed in the system in Fig. 9 with $f = 1.0117$, $n_p = 0.1975$, and $\alpha_m/\alpha_d = 9.96$, showing the pinned phase I, the interstitial flow phase II, the reentrant pinned phase $I_{re}$, the disordered phase III, the phase separated state PS, the diagonal phase separated state DPS, and the moving crystal state MC.

FIG. 12: Dynamic phase diagram as a function of $F_D$ vs $F_p$ for the system in Fig. 1 with $f = 1.0117$, $n_p = 0.1975$, and $\alpha_m/\alpha_d = 9.96$, showing the pinned phase I, the interstitial flow phase II, the reentrant pinned phase $I_{re}$, the disordered phase III, the phase separated state PS, the diagonal phase separated state DPS, and the moving crystal state MC.

FIG. 13: (a) A blow up of the weak pinning region in the dynamic phase diagram from Fig. 12 as a function of $F_D$ vs $F_p$ showing the transition in the pinned phase I from a pinned commensurate solid (PC) to an incommensurate floating solid (IC) near $F_p = 0.02$. This transition also produces a jump down in $F_c$. (b) $P_6$ vs $F_p$ at $F_D = 0$ in the same system showing a drop in $P_6$ across the IC-PC line.
at an Aubry transition of the type found in colloidal systems with periodic substrates as the coupling of the colloids to the substrate is decreased.

**IV. CHANGING THE STRENGTH OF THE MAGNUS FORCE**

We next consider how the dynamical phases evolve when the pinning strength is held fixed but the ratio of the Magnus term to the dissipative term is varied. We use $f = 1.0117$ and $n_p = 0.1975$, and set $F_p = 1.5$, since as indicated in Fig. 12, phases I, II, III, PS, and MC all appear for this pinning strength when $\alpha_m/\alpha_d = 9.96$. In Fig. 14 we plot $\delta V_{//}$ and $\delta V_\perp$ versus $F_D$ since these measures best highlight the transition between the different phases. At $\alpha_m/\alpha_d = 6.591$ in Fig. 14(a), phases I, II, III and MC are present while the PS phase is absent, and in general for this value of $F_p$, the PS phase only occurs for $\alpha_m/\alpha_d > 7.0$. In Fig. 14(b) at $\alpha_m/\alpha_d = 13.3$, all five phases appear and the PS-MC transition shifts up to $F_D = 3.65$. Figure 14(c) shows $\alpha_m/\alpha_d = 26.7$, where the PS phase is larger in extent and a reentrant phase III appears between the PS and the MC phases. At $\alpha_m/\alpha_d = 39.98$ in Fig. 14(d), both the PS phase and the reentrant phase III have increased in extent. In each case, in the PS phase $\delta V_{//}$ is always larger than $\delta V_\perp$, while in the MC phase $\delta V_{//} \approx \delta V_\perp$.

In Fig. 15 we show a dynamic phase diagram for the system in Fig. 14 at $F_p = 1.5$ as a function of $F_D$ versus $\alpha_m/\alpha_d$, where we highlight phases I, II, III, PS, and MC. The value of $F_D$ at which the MC phase appears increases linearly with increasing Magnus force for $\alpha_m/\alpha_d > 4.0$, while for $\alpha_m/\alpha_d \leq 4.0$ it remains roughly constant. The

PS phase occurs when $\alpha_m/\alpha_d > 7.0$, and it grows in extent with increasing $\alpha_m/\alpha_d$, indicating that the PS phase is produced by the dynamics associated with the Magnus force. The I-II transition occurs at a nearly constant value of $F_D$ since the depinning of the interstitial skyrmions is determined by the magnitude of the skyrmion-skyrmion interaction force, which is independent of $\alpha_m/\alpha_d$. In contrast, the II-III transition shifts to lower $F_D$ as $\alpha_m/\alpha_d$ increases from zero, since an increase in the Magnus force gives the skyrmions a stronger tendency to move in the direction perpendicular to the drive, increasing the probability that a moving interstitial skyrmion will depin a pinned skyrmion and produce the onset of disordered phase III flow. For $\alpha_m/\alpha_d \leq 1.0$, a different set of dynamical phases arise that are similar to those found in previous simulations of vortices interacting with periodic pinning, since the behavior in this limit is associated with strong damping. A detailed study of this regime will appear elsewhere.

**V. VARIED FILLING FACTOR**

We next consider the evolution of the different phases when the ratio of the number of skyrmions to the number of pinning sites is varied. We hold the pinning density fixed at $n_p = 0.1975$, and set $F_p = 2.0$ and $\alpha_m/\alpha_d = 9.96$. In Fig. 16 we show the $F_D = 0$ skyrmion and pinning site locations at different filling factors. At $f = 0.5$ in Fig. 16(a), the skyrmions form a commensurate checkerboard pattern in which every other pinning site is occupied. A partially disordered state appears for $f = 1.65$ in Fig. 16(b). At $f = 2.0$ in Fig. 16(c), we find an ordered commensurate square lattice with one skyrmion per pinning site and one skyrmion in each interstitial plaquette.
FIG. 16: Skyrmion (blue dots) and pinning site (red circles) locations for the system in Fig. 1 with \( n_p = 0.1975 \) and \( \alpha_m/\alpha_d = 9.96 \) at \( F_p = 2.0 \) and \( F_D = 0 \). (a) \( f = 0.5 \), where an ordered checkerboard state appears. (b) \( f = 1.65 \). (c) \( f = 2.0 \), where there is another ordered state. (d) \( f = 3.0 \), where a partially ordered dimer state occurs.

Figure 16(d) shows that at \( f = 3.0 \), there is a partially ordered dimer state. In general, the \( F_D = 0 \) ordering of the skyrmions as function of filling factor on a square pinning lattice is same as that observed for vortices in type-II superconductors with square pinning arrays\(^{2,13,27-29}\). Although the dynamics of the skyrmions is different from that of the vortices, the Magnus force has no effect on the static pinned configurations. The skyrmion arrangements in Fig. 16 were obtained through simulated annealing; however, in an experimental system, pinned configurations could be prepared using other means such as a rapid quench. In that case, the Magnus dynamics would be relevant to the quench dynamics and could alter the pinned configurations compared to those of quenched superconducting vortices.

In general, we find that the PS phase appears for filling factors of \( f > 0.6 \), and that the extent of the PS phase increases as \( f \) increases. In Fig. 17 we plot \( \langle V|| \rangle \), \( \delta V|| \), \( \delta V\perp \), and \( P_6 \) versus \( F_D \) for a sample with \( f = 2.5 \), showing the extended range of the PS phase. At the higher filling factors, some additional smaller changes occur in the PS phase, such as the increase in \( P_6 \) near \( F_D = 5.0 \) in Fig. 17(c), which also correlates with a smaller decrease in \( \delta V|| \) in Fig. 17(b). There is also a small jump in \( \langle V|| \rangle \) which correlates with a peak in \( \delta V|| \) and \( \delta V\perp \) near \( F_D = 1.0 \). Figure 18(a) shows the pinned configuration at \( F_D = 0 \), where we find a partially ordered incommensurate state instead of the square lattice that appears near

FIG. 17: (a) \( \langle V|| \rangle \) vs \( F_D \) for the system in Fig. 16 with \( n_p = 0.1975 \), \( \alpha_m/\alpha_d = 9.96 \), \( F_p = 2.0 \) and \( f = 2.5 \). (b) The corresponding \( \delta V|| \) (blue) and \( \delta V\perp \) (red) vs \( F_D \). III: disordered flow; PS: phase separated; MC: moving crystal. (c) The corresponding \( P_6 \) vs \( F_D \). The letters a to d indicate the values of \( F_D \) at which the images in Fig. 18 were obtained.

FIG. 18: Skyrmion (blue dots) and pinning site (red circles) locations at one instant in time for the system in Fig. 17 with \( n_p = 0.1975 \), \( \alpha_m/\alpha_d = 9.96 \), and \( F_p = 2.0 \) at \( f = 2.5 \). (a) A uniform distribution of skyrmions and pinning sites at \( F_D = 0 \). (b) The PS phase at \( F_D = 2.75 \). (c) The latter part of the PS phase at \( F_D = 6.0 \). (d) The MC phase at \( F_D = 7.25 \). Note that due to the periodic boundary conditions, the upper portion of the stripe region in panel (c) appears at the bottom of the figure.
for the system in Fig. 16 at \( F_D = 2.75 \) in the PS phase. A skyrmion density gradient forms, with a square skyrmion lattice at a local filling factor \( f_{\text{loc}} \approx 1 \) in the lower portion of the stripe, a denser square skyrmion lattice rotated by 45° with respect to the pinning lattice at a filling factor \( f_{\text{loc}} \approx 2 \) between the lower and middle portions of the stripe, a disordered high density skyrmion arrangement in the center of the stripe, and a lower density disordered skyrmion arrangement at the top of the stripe. The density profile in Fig. 18(b) suggests that there should be steps in the skyrmion density corresponding to integer local filling factors. Similar steps in the particle density were previously proposed to occur in a density gradient of superconducting vortices on periodic pinning arrays\(^{66,67}\), and such steps also have similarities to the so-called wedding cake density profiles for cold atoms on periodic optical lattices\(^{68}\). The distinction between these other systems and the skyrmion system is that, for the skyrmions, the effect is entirely dynamical in nature and occurs only in the moving state. If the drive were suddenly removed, the PS structure would rapidly relax back into a uniform pinned crystal state. Figure 18(c) shows the skyrmion structure at a higher drive of \( F_D = 6.0 \) in the PS phase. The step feature in the lower portion of the stripe is diminished while the upper portion of the stripe is now more ordered, which is why \( P_b \) is slightly higher at this value of \( F_D \). The ordering in the upper half of the stripe (which is most apparent on the bottom of the figure due to the periodic boundary conditions) also shows characteristic arcs similar to those found in conformal crystals, such as two-dimensional crystals of repulsive particles subjected to a density gradient\(^{69–71}\). When the drive is high enough, the velocity differential between the skyrmions diminishes until the clustering instability is lost and the system forms a triangular lattice, as illustrated in Fig. 18(d) at \( F_D = 7.25 \).

In Fig. 19 we plot \( \langle V_\parallel \rangle, \delta V_\parallel, \delta V_\perp \), and \( P_b \) versus \( F_D \) for the system in Fig. 16 at \( f = 0.56 \), where only three phases appear. Phases I, III, and MC are present while phases II and PS are lost. At low skyrmion densities such as this, the skyrmion-skyrmion interactions are weak, so that even if there are regions where skyrmions are moving faster or slower than average, skyrmions from other regions can easily move around them, preventing the density gradient required to produce the PS phase from occurring. Figure 20 shows the dynamic phase diagram as a function of \( F_D \) versus filling factor \( f \) for the system in Fig. 16. A large increase in the pinned phase I occurs when \( f < 1 \) due to the disappearance of skyrmions from the interstitial locations, so that all of the skyrmions in the system are directly pinned by pinning sites. There are small peaks in the critical depinning force at \( f = 1.0 \) and \( f = 2.0 \), similar to what is observed for the depinning of vortices in type-II superconductors with periodic pinning\(^{2,9,12–14}\). For this value of \( F_p \) and pinning site density, these commensuration peaks are weak; however, as \( F_p \) decreases, the peaks become much more pronounced since the commensurate depinning threshold is dominated by the pinning strength and decreases linearly with \( F_p \), but the incommensurate depinning threshold is dominated by the skyrmion-skyrmion interactions and decreases faster than linearly with \( F_p \). A similar effect occurs for superconducting vortex systems with periodic pinning\(^{9,72,73}\). Figure 20 also shows that the PS phase appears for \( f > 0.6 \) and increases in extent with increasing \( f \). The extent of phase II decreases with increasing

**FIG. 19:** (a) \( \langle V_\parallel \rangle \) vs \( F_D \) for the system in Fig. 16 with \( n_p = 0.1975, \alpha_m/\alpha_d = 9.96, \) and \( F_p = 2.0 \) at a filling factor of \( f = 0.56 \), where only phases I (pinned), III (disordered flow), and MC (moving crystal) appear. (b) The corresponding \( \delta V_\parallel \) (blue) and \( \delta V_\perp \) (red) vs \( F_D \). (c) The corresponding \( P_b \) vs \( F_D \).

**FIG. 20:** Dynamic phase diagram as a function of \( F_D \) vs \( f \) for the system in Fig. 16 with \( n_p = 0.1975, \alpha_m/\alpha_d = 9.96, \) and \( F_p = 2.0 \). For clarity, the reentrant phase I region falling between \( 2.04 \leq f \leq 2.4 \) is marked only by lines and not with data points. I: pinned; II: interstitial flow; III: disordered flow; PS: phase separated; MC: moving crystal.
phase I is then followed by a transition to a reentrant pinned phase I to the interstitial flow phase II, which finally transitions into the disordered phase III flow. The system in Fig. 20 with $n_p = 0.1975$, $\alpha_m/\alpha_d = 9.96$, and $F_p = 2.0$ showing a reentrant pinning effect, $I_{re}$. (b) A blowup of the dynamic phase diagram from Fig. 20 as a function of $F_D$ vs $f$ showing the reentrant pinning which occurs for $2.04 \leq f < 2.4$. 

Since the increase in the number of skyrmions flowing through the interstitial regions causes skyrmions at the pinning sites to be dislodged at lower drives, triggering a transition to the phase III flow.

We observe a reentrant pinning regime in Fig. 20 for $2.04 \leq f \leq 2.4$, where the skyrmions enter phase II flow but then form a new pinned configuration when the drive is increased. In Fig. 21(a) we plot both $\langle V_\parallel \rangle$ and $\langle V_\perp \rangle$ versus $F_D$ at $f = 2.33$ showing a transition from the initial pinned phase I to the interstitial flow phase II, which is then followed by a transition to a reentrant pinned phase $I_{re}$ before the system returns to phase II flow and finally transitions into the disordered phase III flow. The reentrant pinned phase can be viewed as an example of a clogging effect. In Fig. 16(d), the $f = 3.0$ configuration is composed of alternating interstitial dimers, which first begin to form when $f > 2.0$. For $2.04 \leq f < 2.4$, a fraction of the system contains interstitial dimers at $F_D = 0$. In this regime, at the initial depinning transition when the effect of the Magnus force is negligible, the dimers align with the drive along a symmetry direction of the pinning lattice. As the drive increases and the Magnus force begins to rotate the direction of motion of the skyrmions, the dimers also rotate to follow the flow. A dimer that has rotated beyond a critical angle can become trapped if it abruptly becomes oriented perpendicular to the driving direction in the interstitial region between pinning sites. This “dimer bridge” blocks the flow locally, and if all the skyrmion dimers in the system form such dimer bridges, the flow stops completely, producing the reentrant pinned phase $I_{re}$. When the drive is increased further, some of the dimer bridges break apart and the system can reenter phase II flow. At even higher drives, the skyrmions at the pinning sites depin and disordered phase III flow appears. In Fig. 21(b) we show a blow up of the dynamic phase diagram from Fig. 20 as a function of $F_D$ versus $f$ over the range $1.9 < f < 3.0$, where we highlight phase I, II, and III flow. Many of the phases in Fig. 20 are absent in the overdamped limit, where the PS phase does not occur and the MC phase is replaced by a moving smectic. The reentrant pinning phenomena is also lost in the overdamped limit since the dimers all remain aligned with the driving direction, whereas a finite Magnus force causes the dimers to move at an angle to the driving direction, making them more likely to create a clogged configuration.

### VI. VARIED PINNING DENSITY

We next consider the effect of changing the pinning density $n_p$ while fixing $f = 1.0117$, $F_p = 2.0$, and $\alpha_m/\alpha_d = 9.96$. In general, we find that the PS phase appears for sufficiently large $n_p$, and that the DPS phase can also arise. In Fig. 22 we plot $\langle V_\parallel \rangle$, $\delta V_\parallel$, $\delta V_\perp$, and $P_6$ versus $F_D$ for a system with $n_p = 0.436$. The pinned phase occurs for $F_D < 0.155$, while phase II appears in the range $0.155 \leq F_D < 0.575$. In the DPS phase, which extends over the range $0.575 \leq F_D < 1.35$, $\langle V_\parallel \rangle$ is con-
DPS stripe orientations as illustrated in Fig. 24(a,b). The letters a, b, and c indicate the values of \( F \) curves from Fig. 22(b) highlighting the subphases DPS\(_1\) and DPS\(_2\) within the DPS phase. The subphases have different stripe orientations as illustrated in Fig. 24(a,b). The letters a, b, and c indicate the values of \( F \) at which the images in Fig. 24 were obtained. The vertical dashed lines are guides to the eye to show the different phases. II: interstitial flow; DPS\(_1\) and DPS\(_2\): the two subphases of the diagonal phase separated state; III: disordered flow; PS: phase separated.

As illustrated in Fig. 23, which shows a blowup of \( \delta V \) versus \( F_D \) from Fig. 22(b) over the range \( 0.45 < F_D < 2.5 \), there are two subphases in the DPS phase, DPS\(_1\) and DPS\(_2\), that are distinguished by different stripe orientations. The II-DPS\(_1\) transition appears as an upward jump in both \( \delta V_{||} \) and \( \delta V_{\perp} \) while at the DPS\(_1\)-DPS\(_2\) transition near \( F_D = 0.85 \), there is a sharp jump down in \( \delta V_{||} \) accompanied by a jump up in \( \delta V_{\perp} \). In Fig. 24(a), we show the DPS\(_1\) subphase for the \( n_p = 0.436 \) system in Fig. 22 at \( F_D = 0.7 \). The skyrmions form dense bands at an angle of nearly 45° with respect to the driving direction. At \( F_D = 1.0 \) in the DPS\(_2\) subphase, the bands are oriented at a steeper angle of 67° with respect to the driving direction, as illustrated in Fig. 24(b). The jumps in \( \delta V_{||} \) and \( \delta V_{\perp} \) near \( F_D = 0.85 \) in Fig. 23 are associated with a reorientation of the stripes at the DPS\(_1\)-DPS\(_2\) transition. After the reorientation occurs, the stripes are aligned closer to the perpendicular direction, causing \( \delta V_{\perp} \) to jump up while \( \delta V_{||} \) jumps down, as shown in Fig. 23 near \( F_D = 0.84 \). Near \( F_D = 1.22 \), the stripes start to break up, and the system enters a uniform density disordered flow phase III, illustrated in Fig. 24(c) at \( F_D = 1.8 \). In the PS phase, a stripe aligned with the driving direction appears, similar to the state illustrated earlier; however, as \( F_D \) increases, the stripe breaks into two parallel stripes, as shown in Fig. 24(d) at \( F_D = 4.47 \). For \( 6.7 < F_D < 7.1 \), the two stripes broaden and merge into a single density modulation extending across the entire sample, as shown at \( F_D = 7.0 \) in Fig. 24(e), and finally the density even out and the MC phase emerges, as illustrated in Fig. 24(f) at \( F_D = 7.5 \).

In Fig. 25 we plot the dynamic phase diagram as a function of \( F_D \) vs \( n_p \) for the system in Fig. 22 with \( f = 1.0117, F_p = 2.0, \alpha_m/\alpha_d = 9.96, \) and \( n_p = 0.436 \) obtained at values of \( F_D \) marked by the letters a to f in those figures. (a) At \( F_D = 0.7 \) in the DPS\(_1\) subphase, the stripes are aligned at an angle of nearly 45° with respect to the driving direction. (b) At \( F_D = 1.0 \) in the DPS\(_2\) subphase, the stripes are aligned at an angle of nearly 67° with respect to the driving direction. (c) Disordered phase III flow at \( F_D = 1.8 \). (d) At \( F_D = 4.47 \) in the PS phase, there are two moving stripes aligned with the driving direction. (e) At \( F_D = 7.0 \), close to the PS-MC transition, the two stripes begin to merge. (f) The MC phase at \( F_D = 7.5 \).
function of $F_D$ versus $n_p$ for the system in Fig. 22 with $f = 1.0117$, $F_p = 2.0$, and $\alpha_m/\alpha_d = 9.96$. The pinned phase I disappears at small $n_p$ since the distance between the directly pinned skyrmions increases as the pinning density decreases, and therefore the strength of the caging potential experienced by the interstitial skyrmions due to the skyrmion-skyrmion interactions also decreases until the interstitial skyrmions can no longer be trapped. The PS phase only occurs for $n_p > 1.7$ and grows in extent with increasing $n_p$, similar to the results for varied skyrmion density, where the PS phase emerges only for sufficiently high skyrmion density, indicating that the PS phase results from collective skyrmion interactions. The DPS phase appears when $n > 0.235$, and there is an additional line within the DPS phase (not shown) separating the two different orientations DPS$_1$ and DPS$_2$ illustrated in Fig. 24(a,b). The III-PS transition falls at a nearly constant value of $F_D = F_p = 2.0$, indicating that the PS phase forms once $F_D > F_p$ and all the skyrmions depin.

We observe similar results for skyrmions interacting with triangular pinning arrays. In general, the PS phases are more pronounced and exhibit shaper transitions when the pinning is in a periodic array rather than randomly placed; however, the PS phase is a robust feature of skyrmions in systems with strong pinning and strong Magnus force, regardless of the pinning arrangement.

VII. SUMMARY

We have examined the nonequilibrium phases of skyrmions interacting with periodic arrays of pinning sites using a particle-based model for the skyrmions in which the dynamics is governed by both damping and Magnus terms. As a function of system parameters, we find a rich variety of distinct nonequilibrium phases and transitions between these phases which produce clear signatures in the velocity-force curves, fluctuations, and skyrmion ordering. There are pronounced differences between these phases and the collective nonequilibrium phases found for overdamped particles moving over periodic substrates, such as vortices in type-II superconductors or colloids on optical trap arrays. The Magnus force causes the skyrmions to move at an angle with respect to the external drive; however, when pinning is present this skyrmion Hall angle becomes drive dependent. As a result, when the pinning is sufficiently strong, the velocity can become spatially heterogeneous, with skyrmions in different portions of the sample experiencing different effective skyrmion Hall angles, producing an instability that leads to the formation of a clustered or phase separated state. When the drive is high enough, the effectiveness of the pinning diminishes and the skyrmions enter a uniform moving crystal phase. In addition to the phase separated state we find a pinned phase, an interstitial flow phase in which pinned and interstitial skyrmions coexist, a disordered flow phase, and a moving crystal state. When the pinning is weak or the Magnus force is small, the phase separated state is lost. The segregated phase we observe is very similar to that found in recent continuum-based simulations of skyrmions in the strong substrate limit, indicating that the dynamical clustering effects can be captured without taking the internal modes of the skyrmions into account. We also find distinct types of moving phase separated states when the stripe-like clusters form at different orientations with respect to the pinning lattice symmetry. For decreasing pinning strength, we observe a transition from a commensurate or partially commensurate state to a floating solid, which is similar to the Aubry transition found in colloidal systems. For stronger pinning there are a series of commensurate-incommensurate transitions where different types of skyrmion crystalline states can be stabilized as a function of the ratio of the number of skyrmions to the number of pinning sites. These states are the same.

| Name                        | Label     | Characteristic features                                      |
|-----------------------------|-----------|--------------------------------------------------------------|
| No skyrmions moving:        |           |                                                              |
| Pinned                      | I         | Pinned square lattice containing interstitials               |
| Reenetrant Pinned           | I$_{re}$  | Reenetrantely pinned square lattice containing interstitials |
| Pinned Commensurate         | PC        | Same as Phase I (Pinned)                                    |
| Incommensurate Floating Solid| IC       | Pinned triangular lattice floating over the substrate        |
| Moving and pinned skyrmions coexist: |       |                                                              |
| Interstitial Flow           | II        | Motion of only interstitial skyrmions between pinning rows   |
| Disordered Flow             | III       | Individual skyrmions repeatedly pin and depin               |
| Diagonal Phase Separated    | DPS       | Moving skyrmions clump into dense stripes at angle to drive  |
| Diagonal Phase Separated subphase 1| DPS$_1$ | Moving skyrmion stripes aligned $\sim 45^\circ$ from drive  |
| Diagonal Phase Separated subphase 2| DPS$_2$ | Moving skyrmion stripes aligned $\sim 67^\circ$ from drive  |
| All skyrmions moving:       |           |                                                              |
| Phase Separated             | PS        | Skyrmions clump into dense stripes aligned with drive        |
| Moving Crystal              | MC        | Moving triangular crystal containing grain boundaries        |

TABLE I: List of dynamic phases and their characteristic features.
as those observed in an overdamped system since the Magnus force does not change the pinned ground state configurations.

Acknowledgments

We gratefully acknowledge the support of the U.S. Department of Energy through the LANL/LDRD program for this work. This work was carried out under the auspices of the NNSA of the U.S. DoE at LANL under Contract No. DE-AC52-06NA25396 and through the LANL/LDRD program.

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