PRODUCTS OF MULTISYMPLECTIC MANIFOLDS
AND HOMOTOPY MOMENT MAPS

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Abstract. Multisymplectic geometry admits an operation that has no counterpart in
symplectic geometry, namely, taking the product of two multisymplectic manifolds en-
dowed with the wedge product of the multisymplectic forms. We show that there is an
\( L_\infty \)-embedding of the \( L_\infty \)-algebra of observables of the individual factors into the ob-
servables of the product, and that homotopy moment maps for the individual factors
induce a homotopy moment map for the product. As a by-product, we associate to every
multisymplectic form a curved \( L_\infty \)-algebra, whose curvature is the multisymplectic form
itself.

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Introduction

Multisymplectic forms are higher analogues of symplectic forms. More precisely, we will
refer to closed non-degenerate \((n+1)\)-forms as \(n\)-plectic forms, so that for \(n = 1\) we recover
the definition of a symplectic form. Although multisymplectic forms have been studied
for a long time, in part due to the role they play in field theory, it was only around 2010
that the algebraic structure underlying them was unveiled: in [1][9] it was realized that the
“observables” on a multisymplectic manifold carry the structure of an \( L_\infty \)-algebra, which in
the symplectic case reduces to the Poisson algebra of functions. Recall that an \( L_\infty \)-algebra
is the notion that one obtains from a Lie algebra when one requires the Jacobi identity to be
satisfied only up to a higher coherent chain homotopy. Given an \(n\)-plectic manifold \((M, \omega)\),
we denote by \( L_\infty (M, \omega) \) its associated \( L_\infty \)-algebra.

Given an action of a Lie group on a multisymplectic manifold \((M, \omega)\), homotopy moment
maps were introduced in [3] making use of \( L_\infty (M, \omega) \) in an essential way. Homotopy mo-
moment maps enjoy nice properties: cocycles in equivariant cohomology give rise to homotopy
moment maps, and the latter are well-behaved w.r.t loop space constructions, as shown in
[3]. In the setting of (higher) hamiltonian systems, one can show that homotopy moment
maps induce conserved quantities [10]. In the setting of (higher) prequantization, homotopy
moment maps can be lifted to higher prequantum bundles [4].
One feature of multisymplectic geometry, first explored in [12], is that it admits a natural operation which has no counterpart in symplectic geometry, namely the wedge product: let \((M_a, \omega_a)\) be a \(n_a\)-plectic manifold, and similarly let \((M_b, \omega_b)\) be a \(n_b\)-plectic manifold. Then

\[
(\tilde{M}, \tilde{\omega}) := (M_a \times M_b, \omega_a \wedge \omega_b)
\]

is also a multisymplectic manifold, since \(\omega\) is a non-degenerate \((n_a + n_b + 2)\)-form. Notice that while this structure is natural and always well-defined, the structure on \(\tilde{M}\) that is familiar from symplectic geometry – namely the sum \(\omega_a + \omega_b\) – is of little use since it is not a form of well-defined degree except in the case \(n_a = n_b\).

The main goal of this letter is to show that both the \(L_\infty\)-algebra of observables and homotopy moment maps are well-behaved with respect to the above wedge product operation in multisymplectic geometry. Actually, all our results are proven in the more general setting of closed forms, in which the non-degeneracy assumption is dropped.

More precisely, assuming that a Lie group \(G_C\), with Lie algebra \(g_C\), acts on \((M_C, \omega_C)\) with homotopy moment map \(f_C : g_C \to L_\infty(M_C, \omega_C)\), for \(C = a, b\):

1. We construct a homotopy moment map
   \[
   F : g_a \oplus g_b \to L_\infty(\tilde{M}, \tilde{\omega})
   \]
   for the product manifold \(\tilde{M}, \tilde{\omega}\), out of the homotopy moment maps \(f_C\) for the individual factors.
2. We construct an \(L_\infty\)-embedding
   \[
   H : L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b) \to L_\infty(\tilde{M}, \tilde{\omega})
   \]
   from the direct sum of the \(L_\infty\)-algebras of the factors, to the \(L_\infty\)-algebra of the product manifold.

We will see that the two questions addressed above are closely related. Indeed, rather than approaching directly question (2), we first construct \(F\) as in question (1), and using its explicit formula we are able to make an educated guess for \(H\) as in question (2) so that the following diagram of \(L_\infty\)-morphisms commutes:

\[
\begin{array}{ccc}
L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b) & \xrightarrow{H} & L_\infty(\tilde{M}, \tilde{\omega}) \\
\uparrow & & \downarrow \\
f^a \oplus f^b & \xrightarrow{F} & \tilde{M}, \tilde{\omega}
\end{array}
\]

We construct the homotopy moment map \(F\) out of \(f^a\) and \(f^b\) in §2 (see Thm. 2.3), making use of the machinery developed in [3] (see also [11]), and we compare our construction with the one given by [3] for homotopy moment maps arising from equivariant cocycles. Then in §3 we specialize to the case of iterated powers of the same multisymplectic form,
i.e. $(M,\omega^m)$, displaying explicit formulae for the case $(M,\omega^2)$ and discussing Hyperkähler manifolds as an example. In §3 we construct the $L_\infty$-embedding $H$ (by $L_\infty$-embedding we mean an $L_\infty$-morphism whose first component $H_1$ is injective). We do this in Thm. 4.2 using the formulae for $F$ as a guide. Finally in §5 we present an interesting by-product of this note, namely, the existence of a curved $L_\infty$-algebra that is naturally associated to every multisymplectic manifold, and whose “curvature” is the multisymplectic form. Being a genuinely curved $L_\infty$-algebra, it differs from the $L_\infty$-algebra of observables $L_\infty(M,\omega)$ introduced in [1][9].

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1. BACKGROUND ON HOMOTOPY MOMENT MAPS

In this section we briefly review the geometry of closed differential forms and the notion of homotopy moment map, which will be used through the rest of this note, following [3, 8]. We will call $(M,\omega)$ a pre-$n$-plectic manifold if $M$ is a manifold and $\omega$ a closed $(n+1)$-form.

1.1. Closed forms on manifolds and $L_\infty$-algebras.

Definition 1.1. Let $(M,\omega)$ be a pre-$n$-plectic manifold. A $(n−1)$-form $\alpha$ is said to be Hamiltonian if and only if there exists a vector field $v_\alpha \in \mathfrak{X}(M)$ such that

$$d\alpha = -\iota_{v_\alpha} \omega.$$  

We say then that $v_\alpha$ is a Hamiltonian vector field for $\alpha$. The set of Hamiltonian $(n−1)$-forms and Hamiltonian vector fields is respectively denoted by $\Omega^{n−1}_{\text{Ham}}(M)$ and $\mathfrak{X}_{\text{Ham}}(M)$.

A pre-$n$-plectic manifold $(M,\omega)$ is said to be $n$-plectic if for every $u \in TM$, the following non-degeneracy condition is satisfied: $\iota_u \omega = 0$ implies $u = 0$. In other words, $\omega$ is injective when seen as a bundle map $TM \to \wedge^n T^* M$. Notice that if $(M,\omega)$ is $n$-plectic, then for each Hamiltonian form $\alpha \in \Omega^{n−1}_{\text{Ham}}(M)$ there exists a unique Hamiltonian vector field $v_\alpha \in \mathfrak{X}_{\text{Ham}}(M)$. Further, a 1-plectic manifold is the same thing as a symplectic manifold.

Definition 1.2. Let $(M,\omega)$ be a pre-$n$-plectic manifold. We define the bilinear bracket $\{\cdot,\cdot\}_2 : \Omega^{n−1}_{\text{Ham}}(M) \times \Omega^{n−1}_{\text{Ham}}(M) \to \Omega^{n−1}_{\text{Ham}}(M)$ as follows

$$\{\alpha,\beta\}_2 = \iota_{v_\beta} \iota_{v_\alpha} \omega, \quad \alpha,\beta \in \Omega^{n−1}_{\text{Ham}}(M),$$

where $v_\alpha$ and $v_\beta$ are any Hamiltonian vector fields for $\alpha$ and $\beta$ respectively.

The bracket of two Hamiltonian forms is Hamiltonian, and it is well defined since it does not depends on the choice of Hamiltonian vector field among those which are associated with the given Hamiltonian forms. Although the bracket is skew-symmetric, it fails to satisfy the Jacobi identity (the failure is given by an exact form), and therefore it does not make the vector space of Hamiltonian forms into a Lie algebra. Of course one could consider the induced graded Lie bracket on the quotient of $\Omega^{n−1}_{\text{Ham}}(M)$ by the exact forms or by the closed forms, but doing so one loses a lot of information.

1The latter quotient is isomorphic to $\mathfrak{X}_{\text{Ham}}(M)$ as a graded Lie algebra.
In [3, Thm. 5.2], Rogers associated to any \( n \)-plectic manifold an \( L_\infty \)-algebra, depending exclusively on \( \omega \) and the de Rham differential \( d \). This was generalized to pre-\( n \)-plectic manifolds in [13, Thm. 6.7]. Let us first recall the general definition of \( L_\infty \)-algebra.

**Definition 1.3** ([7]). An \( L_\infty \)-algebra is a graded vector space \( L \) equipped with a collection \( \{l_k : L^\otimes k \to L \mid 1 \leq k < \infty \} \) of graded skew-symmetric linear maps with \( \deg l_k = 2 - k \), such that the following identity holds for \( m \geq 1 \) and homogeneous elements \( x_1, \ldots, x_m \in L \):

\[
\sum_{i+j=m+1, \ \sigma \in Sh_{i,m-i}} (-1)^\sigma (\omega)^{-1} l_j(l_i(x_{\sigma(1)}, \ldots, x_{\sigma(i)}), x_{\sigma(i+1)}, \ldots, x_{\sigma(m)}) = 0.
\]

Here \( Sh_{i,m-i} \) denotes the \((i, m-i)\)-unshuffles, i.e. permutations \( \sigma \) of \( \{1, \ldots, m\} \) such that \( \sigma(1) < \cdots < \sigma(i) \) and \( \sigma(i+1) < \cdots < \sigma(m) \), while \( \epsilon(\sigma) \) is the Koszul sign.

The definition of \( L_\infty \)-algebra may seem somehow arbitrary, however it admits a conceptual and elegant formulation in terms of a coalgebra equipped with a codifferential [3, 7], which we will not need in this note. We will be interested in a particular class of \( L_\infty \)-algebras:

**Definition 1.4.** A Lie \( n \)-algebra is an \( L_\infty \)-algebra \((L, l_k)\) such that the graded vector space \( L \) is concentrated in degrees \(-n+1, \ldots, -1, 0\).

For Lie \( n \)-algebras, by degree counting we have \( l_k = 0 \) for \( k > n + 1 \). For \( n = 1 \) we recover the definition of an ordinary Lie algebra. The \( L_\infty \)-algebra constructed in references [3, 7] starting from a pre-\( n \)-plectic or \( n \)-plectic manifold is indeed a particular instance of Lie \( n \)-algebra. The construction is the following.

**Definition 1.5.** Let \((M, \omega)\) be a pre-\( n \)-plectic manifold. There is a Lie \( n \)-algebra structure \( L_\infty(M, \omega) = (L, \{l_k\}_{k \geq 1}) \) on the graded vector space \( L \) whose non-trivial components are

\[
L_i = \begin{cases} 
\Omega^{n-1}_{\text{Ham}}(M) & \text{for } i = 0, \\
\Omega^{n-1+i}(M) & \text{for } 1 - n \leq i \leq -1.
\end{cases}
\]

The Lie \( n \)-algebra structure is given by the sequence of maps \( \{l_k\}_{k \geq 1} \) defined by

\[
l_1(\alpha) = \begin{cases} 
d\alpha & \text{if } \deg \alpha \leq -1, \\
0 & \text{if } \deg \alpha = 0,
\end{cases}
\]

and for all \( k \geq 2 \) by

\[
l_k(\alpha_1, \ldots, \alpha_k) = \begin{cases} 
0 & \text{if } \deg \alpha_1 \otimes \cdots \otimes \alpha_k \leq -1, \\
\zeta(k)(v_{\alpha_1} \wedge \cdots \wedge v_{\alpha_k}) & \text{if } \deg \alpha_1 \otimes \cdots \otimes \alpha_k = 0.
\end{cases}
\]

Above, \( v_{\alpha_i} \) is any Hamiltonian vector field associated to \( \alpha_i \in \Omega^{n-1}_{\text{Ham}}(M) \), and we define \( \zeta(k) := -(-1)^{k(k+1)/2} \) (so \( \zeta(k) = 1, 1, -1 - 1, 1, \ldots \) for \( k = 1, 2, 3, 4, 5, \ldots \)).

Notice that \( l_2(\cdot, \cdot) = \{\cdot, \cdot\}_2 \), so the \( L_\infty \)-algebra constructed above extends the bilinear bracket of Def. 1.3. We will often write \( \{\ldots\}_k \) instead of \( l_k, k \geq 1 \).

We introduce a further sequence of operations on \( L \), which turns out to be very handy for the purposes of this note:

\[\text{The Koszul sign depends on } x_1, \ldots, x_m \text{ too. For instance, if } \sigma \text{ is the transposition of } x_1 \text{ and } x_2, \text{ then the Koszul sign is } (-1)^{|x_1|+|x_2|}.\]
Definition 1.6. Let \((M, \omega)\) be a pre-\(n\)-plectic manifold. Let \(L\) denote the graded vector space underlying \(L_\infty(M, \omega)\).

For all \(k \geq 0\), we define the multilinear maps \([\ldots]_k : L^\otimes k \to \Omega^{n+1-k}(M)\) as follows:

\[
[\alpha_1, \ldots, \alpha_k]_k = \begin{cases} 0 & \text{if } \deg \alpha_1 \otimes \cdots \otimes \alpha_k \leq -1, \\
\varsigma(k) \iota(v_{\alpha_1} \wedge \cdots \wedge v_{\alpha_k})\omega & \text{if } \deg \alpha_1 \otimes \cdots \otimes \alpha_k = 0,
\end{cases}
\]

Remark 1.7. Notice that the operations \([\ldots]_k\) are labelled by integers \(k \geq 0\), unlike the operations introduced in Def. 1.5. The multilinear maps \([\ldots]_k\) are closely related to the multibrackets of \(L_\infty(M, \omega)\): for \(k \geq 1\),

\[
[\alpha_1, \ldots, \alpha_k]_k = \{\alpha_1, \ldots, \alpha_k\}_k - \delta_{k,1}d\alpha_1,
\]

where \(\delta\) denotes the Kronecker delta. In particular, for \(k \geq 2\), \([\ldots]_k\) and \(\{\ldots\}_k\) agree. In Prop. 5.3 we will see that the \([\ldots]_k\) extend to a curved \(L_\infty\)-algebra structure.

1.2. Homotopy moment maps and group actions. Let \((M, \omega)\) be a pre-\(n\)-plectic manifold and let \(G\) be a Lie group, with corresponding Lie algebra \(\mathfrak{g}\), that acts on \((M, \omega)\) preserving \(\omega\). The Lie group \(G\) acts on \(\Omega^n(M)\) from the left via \(g \cdot \omega \mapsto (\psi_g^{-1})^*\omega\), where \(\psi_g\) is the diffeomorphism associated to \(g\). The corresponding infinitesimal action is a Lie-algebra homomorphism from the Lie algebra \(\mathfrak{g}\) to the vector fields \(\mathfrak{X}(M)\) on \(M\), namely:

\[
v_- : \mathfrak{g} \to \mathfrak{X}(M), \quad x \mapsto v_x,
\]

where\(^3\)

\[
v_x|_p = \frac{d}{dt} \exp(-tx) \cdot p|_{t=0}, \quad \forall p \in M.
\]

We present now the concept of homotopy moment map, introduced in [3], which generalizes the comoment map construction that appears in symplectic geometry.

Definition 1.8. A homotopy moment map for the action of \(G\) on \((M, \omega)\) is an \(L_\infty\)-morphism \(f : \mathfrak{g} \to L_\infty(M, \omega)\) such that for all \(x \in \mathfrak{g}\)

\[
df_1(x) = -\iota_{v_x} \omega.
\]

An action is said to be Hamiltonian if it admits a homotopy moment map.

Remark 1.9. a) From equation (3), we see that a necessary (but not sufficient) condition for an action of \(G\) to be Hamiltonian is that, infinitesimally, it acts through Hamiltonian vector fields. Notice that \(f\) is not required to satisfy any equivariance properties.

b) Def. [3] is a generalization of the notion of comoment map for the action of a Lie group on a symplectic manifold. Indeed, for \(n = 1\) we recover the standard definition of a comoment map as a Lie-algebra homomorphism from the Lie algebra \(\mathfrak{g}\) to the Poisson algebra of functions on the symplectic manifold.

A homotopy moment map is a particular instance of \(L_\infty\)-morphism, and the latter is a fairly complicated object to handle in general. Luckily enough, we only need to consider \(L_\infty\)-morphisms having as source a Lie algebra, and as target a Lie \(n\)-algebra with the property that its higher brackets are non-trivial only in degree zero (this is Property (P) in [3, §3.2]). By [3, Prop. 3.8] (see also the text at the beginning of Section 5 there), \(f : \mathfrak{g} \to L_\infty(M, \omega)\)

\(^3\)The notation we chose for the vector field \(v_x\) (associated to \(x \in \mathfrak{g}\) by the infinitesimal action) is similar to the one chosen for Hamiltonian vector fields \(v_x\) of a Hamiltonian form \(\alpha\) (Def. 1.1). We hope this does not give rise to confusion.
being a $L_\infty$-morphism means that it consists of components $f_k \colon \wedge^k \mathfrak{g} \to \Omega^{n-k}(M)$ (for $k = 1, \ldots, n$) satisfying:

$$
\sum_{1 \leq i < j \leq k} (-1)^{i+j+1} f_{k-1}([x_i, x_j], x_1, \ldots, \widehat{x_i}, \ldots, \widehat{x_j}, \ldots, x_k) = df_k(x_1, \ldots, x_k) + \varsigma(k) i(v_{x_1} \wedge \cdots \wedge v_{x_k}) \omega
$$

for $2 \leq k \leq n$, as well as

$$
\sum_{1 \leq i < j \leq n+1} (-1)^{i+j+1} f_n([x_i, x_j], x_1, \ldots, \widehat{x_i}, \ldots, \widehat{x_j}, \ldots, x_{n+1}) = \varsigma(n+1) i(v_{x_1} \wedge \cdots \wedge v_{x_{n+1}}) \omega.
$$

As mentioned above, comoment maps for symplectic manifolds are particular cases of homotopy moment maps. Further examples of homotopy moment maps can be found in \[3\] and \[11\].

2. Homotopy moment maps for cartesian products $(M_a \times M_b, \omega_a \wedge \omega_b)$

Let $(M_C, \omega_C), C = a, b,$ be a pre-$n$-plectic manifold and let $G_C$ be a Lie group, with Lie algebra $\mathfrak{g}_C$, which acts on $(M_C, \omega_C)$ in a Hamiltonian way, with corresponding homotopy moment map $f_C : \mathfrak{g}_C \to L_\infty(M_C, \omega_C)$. Then $\varpi \equiv G_a \times G_b$ acts on the pre-$(n_a + n_b + 1)$-plectic manifold\(^4\)

$$(M \equiv M_a \times M_b, \omega \equiv \omega_a \wedge \omega_b).$$

The main theorem of this section is Theorem 2.3 where from the above data we explicitly construct a homotopy moment map $F : \mathfrak{g}_a \otimes \mathfrak{g}_b \to L_\infty(M, \omega)$.

2.1. The construction of $F$. We first recall a few facts from \[5\], §2 (see also \[11\]). Let $(M, \omega)$ be a pre-$n$-plectic manifold, and $G$ a Lie group acting on $M$ preserving $\omega$. The manifold $M$ and the Lie algebra $\mathfrak{g}$ give rise to a double complex

$$K := (\wedge \geq 1 \mathfrak{g}^* \otimes \Omega(M), d_\mathfrak{g}, d),$$

where $d_\mathfrak{g}$ is the Chevalley-Eilenberg differential of $\mathfrak{g}$ and $d$ is the de Rham differential of $M$.

We consider the total complex with differential

$$d_{tot} := d_\mathfrak{g} \otimes 1 + 1 \otimes d.$$

Hence, on an element of $\wedge \mathfrak{g}^* \otimes \Omega(M)$, $d_{tot}$ acts as $d_\mathfrak{g} + (-1)^k d$.

For any $G$-invariant $\sigma \in \Omega^N(M)$ define

$$\sigma^k : \wedge^k \mathfrak{g} \to \Omega^{N-k}(M), \quad (x_1, \ldots, x_k) \mapsto i(v_1 \wedge \cdots \wedge v_k) \sigma,$$

and

$$\tilde{\sigma} := \sum_{k=1}^N (-1)^k \sigma^k.$$

Since each $\sigma^k$ can be viewed as an element of $\wedge^k \mathfrak{g}^* \otimes \Omega^{N-k}(M)$, it follows that $\tilde{\sigma}$ can be viewed as an element of $K$ of total degree $N$. It turns out that $\tilde{\omega}$ is $d_{tot}$-closed, as a \(^4\)We will slightly abuse the notation, denoting a differential form on $M_C$ and its pullback to $M_a \times M_b$, via the canonical projection, by the same symbol.
Lemma 2.2. Let \( \varphi = \varphi_1 + \cdots + \varphi_n \), with \( \varphi_k \in \land^k g^* \otimes \Omega^{n-k}(M) \). Then: \( d_{\text{tot}} \varphi = \tilde{\omega} \) iff 
\[
f_k := \varsigma(k) \varphi_k : \land^k g \to \Omega^{n-k}(M),
\]
for \( k = 1, \ldots, n \), are the components of a homotopy moment map for the action of \( G \) on \( (M, \omega) \).

Now we apply the previous machinery to the manifolds \( M_a, M_b, M_a \times M_b \) and the data given at the beginning of this section. For each of these three manifolds we obtain a double complex, which we will denote by \( (K_a, d_{\text{tot}}^a) \), \( (K_b, d_{\text{tot}}^b) \) and \( (K, d_{\text{tot}}) \) respectively.

Lemma 2.2. Let \( \varphi^C \in K^C \) be of degree \( n_C \). If \( d_{\text{tot}}^C \varphi^C = \tilde{\omega}^C \) for \( C = a, b \), then \( d_{\text{tot}} \varphi = \omega_a \wedge \omega_b \) where
\[
\varphi = \frac{1}{2} (-\varphi_a \omega_b + (-1)^{n_a} \omega_a \varphi_b) + (\varphi_a \omega_b + (-1)^{n_a+1} \omega_a \varphi_b) \in K.
\]

Proof. First notice that
\[
\omega_a \wedge \omega_b = -\omega_a \omega_b + \omega_a \omega_b + \omega_a \omega_b.
\]
This is a consequence of \( \omega_a \omega_b = \omega_a \wedge \omega_b \) for \( \omega^C := \omega_C - \omega_C \).

Now we exhibit \( d_{\text{tot}} \)-primitives for each of the three summands in eq. (7).
\[
d_{\text{tot}}(\varphi^a \omega_b + (-1)^{n_a+1} \omega_a \varphi_b) = d_{\text{tot}}^a \varphi^a \omega_b + (-1)^{n_a} \varphi^a d_{\text{tot}}^b \omega_b + (-1)^{n_a+1} d_{\text{tot}}^a \omega_a \varphi_b + \omega_a d_{\text{tot}}^b \varphi_b
\]
\[
= 2\omega_a \omega_b
\]
where in the last equation we used our assumption and \( d_{\text{tot}}^C \tilde{\omega}^C = 0 \), which holds by [5, §2].

Further
\[
d_{\text{tot}}(\varphi^a \omega_b) = d_{\text{tot}}^a \varphi^a \omega_b + (-1)^{n_a} \varphi^a d_{\text{tot}}^b \omega_b = \omega_a \omega_b,
\]
where in the last equation to compute \( d_{\text{tot}}^b \omega_b = 0 \) we have to enlarge the double complex \( K^b \) to include \( \land^0(g_b)^* \otimes \Omega(M_b) \cong \Omega(M_b) \).

Similarly,
\[
d_{\text{tot}}((-1)^{n_a+1} \omega_a \varphi_b) = \omega_a \omega_b.
\]

Applying Prop. 2.1 the \( d_{\text{tot}} \)-primitive of \( \omega_a \wedge \omega_b \) obtained in Lemma 2.2 allows us to construct a homotopy moment map for the \( g \) action on \( (M, \omega_a \wedge \omega_b) \):

Theorem 2.3. Let \( G_C \) be a Lie group with Lie algebra \( g_C \), where \( C = a, b \). Let \( (M_C, \omega_C) \) be a pre-\( n_C \)-plectic manifold equipped with a \( G_C \) action admitting a homotopy moment map \( f^C : g_C \to L_\infty(M_C, \omega_C) \). Then the action of \( G_a \times G_b \) on \( (M, \omega) := (M_a \times M_b, \omega_a \wedge \omega_b) \) admits a homotopy moment map with components determined by graded skew-symmetry and the formulae (\( k = 1, \ldots, n_1 + n_2 + 1 \))

\[
F_k : (g_a \oplus g_b)^{\otimes k} \to L_\infty(M, \omega)
\]
\[
(x_1^a, \ldots, x_{n_1}^a, x_1^b, \ldots, x_{n_2}^b) \mapsto c_{m, l}^a f_m^a (x_1^a, \ldots, x_{n_1}^a) \wedge \iota_1, \ldots, l \omega_b
\]
\[
+ c_{m, l}^b \iota_1, \ldots, m \omega_a \wedge f_l^b (x_1^b, \ldots, x_{n_2}^b).
\]
where \( m, l \geq 0 \) with \( m + l = k \), \( x_i^a \in g_a \) and \( x_i^b \in g_b \). Here we define \( f_0^a = f_0^b = 0 \) and
\[
\omega_C = \frac{1}{i_l, \ldots, i_l} \left( v_{i_1}^C(x_i^1) \wedge \cdots \wedge v_{i_l}^C(x_i^l) \right) \omega_C.
\]
The coefficients are defined as follows for all \( m \geq 1, l \geq 1 \):
\[
c_{m,l}^a = \frac{1}{2} \zeta(m + l) \zeta(m)(-1)^{(m_a + 1 - m)l},
\]
\[
c_{m,l}^b = \frac{1}{2} \zeta(m + l) \zeta(l)(-1)^{(m_a + 1 - m)(l + 1)},
\]
and
\[
c_{m,0}^a = 1, \quad c_{0,l}^b = (-1)^{(l + 1)(m_a + 1)}.
\]
Recall that \( \zeta(k) = (-1)^{\frac{k(k + 1)}{2}} \).

Remark 2.4. The formula for \( F_k \) simplifies once written using the operations \([\ldots]\) introduced in Def. 1.6
\[
F_k(x_1^a, \ldots, x_m^a, x_1^b, \ldots, x_l^b) = c_{m,l}^a f_m(x_1^a, \ldots, x_m^a) \wedge [f_1^b(x_1^b), \ldots, f_l^b(x_l^b)]
\]
\[
+ c_{m,l}^b [f_1^a(x_1^a), \ldots, f_l^a(x_l^a)] \wedge f_1^b \left( x_1^b, \ldots, x_l^b \right),
\]
where for all \( m \geq 1, l \geq 1 \):
\[
c_{m,l}^a = \frac{1}{2} (-1)^{(m_a + 1)l},
\]
\[
c_{m,l}^b = \frac{1}{2} (-1)^{(m_a + 1)(l + 1) + m},
\]
and
\[
c_{m,0}^a = -1, \quad c_{0,l}^b = (-1)^{(l + 1)(m_a + 1)}.
\]
This is a straightforward consequence of \( \zeta(m) \zeta(l) \zeta(m + l) = (-1)^{m(l + 1)} \) for all integers \( m, l \geq 0 \).

Proof. Prop. 2.1 and Lemma 2.2 deliver a homotopy moment map \( F: g_a \oplus g_b \to L_\infty(M_a \times M_b, \omega) \) whose components \( F_k \), for \( k = 1, \ldots, n_a + n_b + 1 \), are given by
\[
F_k = \zeta(k) \varphi_k,
\]
where
\[
\varphi = \frac{1}{2} (-\varphi^a \omega^b + (-1)^{n_a} \omega^a \varphi^b) + (\varphi^a \omega^b + (-1)^{n_a + 1} \omega^a \varphi^b).
\]

Let us point out that
\[
\varphi_k \in \Lambda^k (g_a^* \oplus g_b^*) \otimes \Omega^{(n_a + n_b + 1 - k)} (M_a \times M_b).
\]
In order to prove the theorem we just have to write \( F_k \) using equation (8) and \( f_k^a = \zeta(k) \varphi_k^a \), \( f_k^b = \zeta(k) \varphi_k^b \). We do so evaluating the components of \( F \) on elements of \( g_a \) and of \( g_b \).

We have
\[
F_m(x_1^a, \ldots, x_m^a) = \zeta(m) \varphi_m(x_1^a, \ldots, x_m^a) = \zeta(m) \varphi_m^a(x_1^a, \ldots, x_m^a) \wedge \omega^b
\]
\[
= f_m^a(x_1^a, \ldots, x_m^a) \wedge \omega^b,
\]
using that \( \varphi_m^a = \zeta(m) f_m^a \) in the last equality. In the second equality we used eq. (8) (notice that on the r.h.s. of eq. (8), only the summand \( \varphi^a \omega^b \) gives a contribution). We conclude that
\[ c^{a}_{m,0} = 1, \quad m \geq 1. \]

Let us take now

\[
F_l(x_b^1, \ldots, x_b^l) = \varsigma(l)\varphi_l(x_b^1, \ldots, x_b^l) = \varsigma(l)(-1)^{n_a+1}(\omega_a\varphi_l^b)(x_b^1, \ldots, x_b^l) \\
= (-1)^{n_a+1}(\omega_a f_l^b)(x_b^1, \ldots, x_b^l) \\
= (-1)^{(a_l+1)(l+1)}\omega_a \wedge f_l^b(x_b^1, \ldots, x_b^l).
\]

The last equality holds since\footnote{We are slightly abusing the notation by denoting the product of two elements in the double-complexes \( K_C \) or \( K \) and the wedge product of forms by simply a space.}, if we pick a basis \( \{ \xi^b_{l1} \} \) of \( g_b^a \) and write \( f_l^b \) as a sum of terms of the form \( \xi^b_{l1} \wedge \cdots \wedge \xi^b_{l1} \otimes \beta \in \Lambda^l(g_b^a) \otimes \Omega^{(m-b-l)}(M_b) \), then

\[
(1 \otimes \omega_a)(\xi^b_{l1} \wedge \cdots \wedge \xi^b_{l1} \otimes \beta) = (-1)^{(n_a+1)l}\xi^b_{l1} \wedge \cdots \wedge \xi^b_{l1} \otimes (\omega_a \wedge \beta).
\]

We obtain

\[
e^{b}_{0,l} = (-1)^{(n_a+1)(l+1)} , \quad l \geq 1.
\]

For \( m, l \geq 1 \)

\[
F_{m+l}(x_a^1, \ldots, x_a^m, x_b^1, \ldots, x_b^l) \\
= \varsigma(m + l)\varphi_{m+l}(x_a^1, \ldots, x_a^m, x_b^1, \ldots, x_b^l) \\
= \varsigma(m + l)\frac{1}{2}(-\varphi_m^a(\omega_b)^l + (-1)^{n_a}(\omega_a)m \varphi_l^b)(x_a^1, \ldots, x_a^m, x_b^1, \ldots, x_b^l) \\
= \varsigma(m + l)\frac{1}{2}(-\varsigma(m)(-1)^{l-1}f_m^a \omega_b^l + (-1)^{n_a}(-1)^{m-1}\varsigma(l)\omega_a^m f_l^b)(x_a^1, \ldots, x_a^m, x_b^1, \ldots, x_b^l),
\]

where in the last equality we used eq. [3]. We have

\[
(f_m^a \omega_b^l)(x_a^1, \ldots, x_a^m, x_b^1, \ldots, x_b^l) = (-1)^{(n_a-m)l}f_m^a(x_a^1, \ldots, x_a^m) \wedge \omega_b^l(x_b^1, \ldots, x_b^l),
\]

using \( f_m^a \in \Lambda^a g_a^a \otimes \Omega^{n_a-m}(M_a) \) and \( \omega_b^l \in \Lambda^l g_b^a \otimes \Omega(M_b) \). Therefore

\[
e^{a}_{m,l} = \frac{1}{2}\varsigma(l+m)\varsigma(m)(-1)^{(n_a+1-m)l}.
\]

Similarly,

\[
(\omega_a^m f_l^b)(x_a^1, \ldots, x_a^m, x_b^1, \ldots, x_b^l) = (-1)^{(n_a+1-m)l}\omega_a^m(x_a^1, \ldots, x_a^m) \wedge f_l^b(x_b^1, \ldots, x_b^l),
\]

using \( \omega_a^m \in \Lambda^a g_a^a \otimes \Omega^{n_a+1-m}(M_a) \) and \( f_l^b \in \Lambda^l g_b^a \otimes \Omega(M_b) \). Hence

\[
e^{b}_{m,l} = \frac{1}{2}\varsigma(l+m)\varsigma(l)(-1)^{(n_a+1-m)(l+1)}.
\]

\[\square\]

**Example 2.5.** We spell out the homotopy moment map constructed in Thm. 23 in the case that \( M_a \) and \( M_b \) are pre-symplectic manifolds, i.e. \( n_a = n_b = 1 \). In that case \( f^a : g_a \to \)
$C^\infty(M_a)$ is an ordinary comoment map, just like $f^b$, and $(M, \omega)$ is a pre-3-plectic manifold. One obtains
\[
F_1(x_a \oplus x_b) = f^a(x_a) \cdot \omega_b + \omega_a \cdot f^b(x_b)
\]
\[
F_2(x_a \oplus x_b, y_a \oplus y_b) = \frac{1}{2} \left(-f^a(x_a) \cdot \nu f^b(y_b) \cdot \omega_b + \nu f^a(x_a) \cdot \omega_b \cdot f^b(y_b)\right) - (x \leftrightarrow y)
\]
\[
F_3(x_a \oplus x_b, y_a \oplus y_b, z_a \oplus z_b) = -\frac{1}{2} \left(f^a(x_a) \cdot \nu f^b(y_b) \cdot \omega_b \cdot f^b(z_b) + f^a(x_a) \cdot \nu f^a(x_a) \cdot \omega_b \cdot f^b(y_b)\right) + \text{c.p.}
\]
where $x_C, y_C, z_C \in \mathfrak{g}_C$ for $C = a, b$ and “c.p.” denotes cyclic permutations of $x, y, z$.

2.2. Non-associativity of the construction. The construction of homotopy moment maps for product manifolds given in Thm. 2.3 is not associative. More precisely: for $C = a, b, c$ let $G_C$ be a Lie group with Lie algebra $\mathfrak{g}_C$, acting on a pre-$n_C$-plectic manifold $(M_C, \omega_C)$ with homotopy moment map $f^C : \mathfrak{g}_C \to L_\infty(M_C, \omega_C)$. Denote by $f^a \ast f^b$ the homotopy moment map for the action of $G_a \times G_b$ on $(M_a \times M_b, \omega_a \wedge \omega_b)$ constructed in Thm. 2.3 Then
\[
(f^a \ast f^b) \ast f^c \neq f^a \ast (f^b \ast f^c),
\]
as one can see from a straightforward computation using the fact that $e_{m,l} = \pm \frac{1}{2}$ for $m \geq 1, l \geq 1$.

Indeed, the construction of the $d_{\text{tot}}$-primitives done in Lemma 2.2 is also not associative: denote by $\varphi^C$ the elements of $K^C$ corresponding to the homotopy moment maps $f^C$ (via Prop. 2.1). If we denote by $\varphi^a \ast \varphi^b$ the $d_{\text{tot}}$-primitive of $\omega_a \wedge \omega_b$ constructed in Lemma 2.2 then $(\varphi^a \ast \varphi^b) \ast \varphi^c$ and $\varphi^a \ast (\varphi^b \ast \varphi^c)$ are different primitives for $((\omega_a \wedge \omega_b) \wedge \omega_c) = (\omega_a \wedge (\omega_b \wedge \omega_c))$. The difference between these two primitives is
\[
\frac{1}{4}(-\varphi^a \omega_b \omega_c + \omega_a \omega_b \varphi^c) = d_{\text{tot}} \left(-\frac{1}{4} \varphi^a \omega_b \varphi^c\right).
\]
Hence the two homotopy moment maps appearing in eq. 22 are inner equivalent in the sense of Remark 7.10. This notion of inner equivalence is the one that arises naturally considering the complex $\Lambda^{p+1}(\mathfrak{g}_a \times \mathfrak{g}_b \times \mathfrak{g}_c)^* \otimes \Omega^p(M_a \times M_b \times M_c)$, and can be characterized as equivalence of $L_\infty$-morphisms (see Prop. A2).

Under quite restrictive conditions, there is another way to construct homotopy moment maps for product manifolds, which does have the property of being associative in the sense above.

Remark 2.6. Given an action of $G_a$ on the pre-$n_a$-plectic manifold $(M_a, \omega_a)$, the theorem Thm. 6.8] provides a map
\[
\Phi_{M_a} : \{\text{Closed extensions of } \omega_a \text{ in } C_{G_a}(M_a)\} \to \{\text{Homotopy moment maps for } (M_a, \omega_a)\},
\]
where $C_{G_a}(M_a) = (S^2 \mathfrak{g}_a^* \otimes \Omega(M_a))^G_a$ is the Cartan model for the equivariant cohomology of the $G_a$ action on $M_a$ (it is a differential graded algebra). This map is not surjective in general [8 §7.5]. It is also not injective in general: by the formulae in Thm. 6.8] it is clear that, if $\mathfrak{g}_a$ is an abelian Lie algebra, then the component lying in $(S^2 \mathfrak{g}_a^* \otimes \Omega^{m_a-3}(M_a))^G_a$ of a closed extension $\psi^a$ can not be recovered from the homotopy moment map $\Phi_{M_a}(\psi^a)$.\footnote{One could hope that redefining $\varphi^a \ast \varphi^b$ by adding a real multiple of $d_{\text{tot}}(\varphi^a \varphi^b)$ to it might remove this issue, but this is not the case.}
However, in the cases in which \( \Phi_{M_a} \) and \( \Phi_{M_b} \) are injective\(^7\), one can carry out the following construction: if homotopy moment maps \( f^C \) for \( (M_C, \omega_C) \) arising from closed extensions in the Cartan model \( (C = a, b) \) are given, then

\[
\Phi_{M_a \times M_b}(\psi^a \cdot \psi^b)
\]

is a homotopy moment map for \( (M_a \times M_b, \omega_a \wedge \omega_b) \), where \( \psi^C \) is determined by \( \Phi_{M_C}(\psi^C) = f^C \), and the dot denotes the product in the Cartan model \( C_{G_a \times G_b}(M_a \times M_b) \). This prescription has the property of being associative, in the sense above, for the simple reason that the algebra structure in the Cartan model is associative.

In the special case of pre-symplectic manifolds \( (M_a, \omega_a) \) and \( (M_b, \omega_b) \), the injectivity assumption is satisfied. The above prescription \((10)\) delivers a homotopy moment map \( H \) for \( (M_a \times M_b, \omega_a \wedge \omega_b) \), which as expected is different from the one \( F \) obtained in Ex. \ref{ex:product}. We have \( H_1 = F_1, H_2 = F_2 \), but

\[
H_3(x_a \oplus x_b, y_a \oplus y_b, z_a \oplus z_b) = \frac{2}{3} F_3(x_a \oplus x_b, y_a \oplus y_b, z_a \oplus z_b) - \frac{1}{6} \left( f^a(x_a)f^b([y_b, z_b]) + f^a([y_a, z_a])f^b(x_b) + c.p. \right)
\]

where \( x_C, y_C, z_C \in \mathfrak{g}_C \) for \( C = a, b \).

3. Application: homotopy moment maps for iterated powers \( (M, \omega^m) \)

In Section \ref{sec:application} we have shown how to build a homotopy moment map for the product manifold of two pre-multisymplectic manifolds, assuming that a homotopy moment map for the individual manifolds exist. Here we apply this construction to some specific examples of geometrical interest: powers of closed forms and Hyperkähler manifolds.

3.1. Restrictions. Let \( G \) be a Lie group with Lie algebra \( \mathfrak{g} \), acting on a pre-\( n \)-plectic manifold \( (M, \omega) \) with homotopy moment map \( f : \mathfrak{g} \to L_\infty(M, \omega) \). One obtains new actions, either restricting to a Lie subgroup of \( G \) or to an invariant submanifold of \( (M, \omega) \). We display homotopy moment maps for both cases.

\textbf{Lemma 3.1.} Let \( H \subset G \) be a Lie subgroup, and denote by \( j : \mathfrak{h} \hookrightarrow \mathfrak{g} \) the inclusion of its Lie algebra. The restricted action of \( H \) on \( (M, \omega) \) has homotopy moment map \( f \circ j : \mathfrak{h} \to L_\infty(M, \omega) \).

\textit{Proof.} The Lie algebra morphism \( j \) is in particular an \( L_\infty \)-morphism, so \( f \circ j \) also is. Since eq. \((3)\) holds for all \( x \in \mathfrak{g} \), in particular it holds for all \( x \in \mathfrak{h} \). \( \square \)

\textbf{Lemma 3.2.} Let \( N \xrightarrow{i} M \) a \( G \)-invariant submanifold of \( M \). Then the action \( G \circ (N, i^*\omega) \) is Hamiltonian with homotopy moment map \( i^* \circ f : \mathfrak{g} \to L_\infty(N, i^*\omega) \).

\textit{Proof.} According to Def. \ref{def:hamiltonian} we have to show that

\[
f^N := i^* \circ f : \mathfrak{g} \to L_\infty(N, i^*\omega)
\]

is an \( L_\infty \)-morphism such that

\[
-\iota_{(v_x)^N}i^*\omega = df^N_1(x), \quad \forall x \in \mathfrak{g},
\]

\(^7\)The same prescription does not seem to work without the injectivity assumption, for in that case it seems to depend on the choice of \( \psi^a \) and \( \psi^b \). In view of the formulation of [3, Thm. 6.8], the technical reason behind this is the following: if \( P^2_3 \in S^3_{i^*\omega} \) is a quadratic polynomial on the Lie algebra \( \mathfrak{g}_a \), then the total skew-symmetrization of \( P^2_3([\cdot, \cdot], [\cdot, \cdot]) : \mathfrak{g}^3_a \to \mathbb{R} \) does not seem to be determined by the total skew-symmetrization of \( P^2_3([\cdot, \cdot], [\cdot, \cdot]) : \mathfrak{g}^3_a \to \mathbb{R} \).
where \((v_x)^N\), which is a generator of the action on \(N\), denotes the restriction of the vector field \(v_x\) to \(N\).

Eq. (11) follows simply applying the pullback \(i^*\) to Eq. (3). To show that \(f^N\) is an \(L_\infty\)-morphism, let us introduce the following \(L_\infty\)-subalgebra of \(L_\infty(M,\omega)\):

\[
L^N(M,\omega) = C^\infty(M) \oplus \Omega^1(M) \oplus \cdots \oplus \Omega^{n-1}_{\Ham}(M),
\]

where

\[
\Omega^{n-1}_{\Ham}(M) = \{ \alpha \in \Omega^{n-1}_{\Ham}(M) : \exists \text{ a hamiltonian vector field of } \alpha \text{ tangent to } N \}.
\]

Since \(L_\infty(M,\omega)\) and \(L^N(M,\omega)\) are equal in every component except for the degree zero component, in order to see that \(L^N(M,\omega)\) is really a \(L_\infty\)-subalgebra of \(L_\infty(M,\omega)\), we only have to check that the binary bracket \(l_2\) of \(L_\infty(M,\omega)\) restricts to \(\Omega^{n-1}_{\Ham}(M)\). This is indeed the case since given any two Hamiltonian forms \(\alpha\) and \(\beta\) and respective Hamiltonian vector fields \(v_\alpha, v_\beta\), a Hamiltonian vector field for \(l_2(\alpha, \beta)\) is given by the Lie bracket \([v_\alpha, v_\beta]\), which of course is tangent to \(N\) whenever both \(v_\alpha\) and \(v_\beta\) are.

Notice that the homotopy moment map \(f: g \to L_\infty(M,\omega)\) takes values in \(L^N_\infty(M,\omega)\), that is,

\[
f_k(x) \in L^N(M,\omega), \quad \forall x \in g^\otimes k \quad k \geq 1.
\]

To prove this, since \(L_\infty(M,\omega)\) and \(L^N(M,\omega)\) are equal in every component but the zero one, we have to check equation (12) only in the \(k = 1\) case, that is, we have to prove that

\[
f_1(x) \in \Omega^{n-1}_{\Ham}(M), \quad \forall x \in g.
\]

It holds since a Hamiltonian vector field of \(f_1(x)\) is the generator of the action \(v_x\), which is tangent to \(N\) by assumption.

Next, notice that the pullback of forms

\[
i^*: L^N_\infty(M,\omega) \to L_\infty(N,i^*\omega)
\]

is a (strict) \(L_\infty\)-morphism, as a consequence of the facts that \(i^*\) commutes with the de Rham differential and due to the definition of \(\Omega^{n-1}_{\Ham}(M)\). We conclude that \(i^* \circ f: g \to L_\infty(N,i^*\omega)\) is a homotopy moment map. \(\square\)

3.2. Actions on \((M,\omega \wedge \omega)\). Let us consider two pre-multisymplectic manifolds \((M_C,\omega_C),\ C = a, b\). We assume that there is a Hamiltonian action of a Lie group \(G_C \hookrightarrow M_C\) with corresponding homotopy moment map \(f^C: g_C \to L_\infty(M_C,\omega_C)\). By Thm. 2.3 we know that there is also a Hamiltonian action

\[
(13) \quad G_a \times G_b \circ (M_a \times M_b, \omega_a \wedge \omega_b),
\]

with homotopy moment map \(F\) given by Thm. 2.3.

Assume now that \(G_a = G_b =: G\), whose Lie algebra we denote by \(g\). One can restrict the action (13) to the diagonal \(\Delta G = \{(g, g) : g \in G\}\) of \(G \times G\):

\[
\Delta G \circ (M_a \times M_b, \omega_a \wedge \omega_b).
\]

\(\text{However the map } L_\infty(M,\omega) \to L_\infty(N,i^*\omega)\text{ given by pullback of forms is not an } L_\infty\text{-morphism. This is the reason we need to introduce } L^N_\infty(M,\omega).\)
By Lemma 3.1, a homotopy moment map for this action is
\[ F \circ j : \Delta g \to L_\infty (M_a \times M_b, \omega_a \wedge \omega_b), \]
where
\[ j : \Delta g = \{(x,x) : x \in g\} \to g \oplus g \]
is the inclusion. By the isomorphism \( G \simeq \Delta G, g \mapsto (g,g) \) we can view eq. (14) as an action of the Lie group \( G \), and \( j \) as a map \( g \simeq \Delta g \to g \oplus g \).

Now we specialize even further, taking \( M_a = M_b = M, \omega_a = \omega_b = \omega \) and \( f^a = f^b \).

The diagonal \( \Delta M \) of \( M \times M \) is invariant under the action of \( \Delta G \). Therefore, using the inclusion
\[ i : \Delta M \hookrightarrow M \times M \]
and the identification \( M \simeq \Delta M \) we obtain by restriction an action of \( G \) on \( M \):
\[ G \simeq \Delta G \acts (\Delta M, i^* (\omega \wedge \omega)) \simeq (M, \omega \wedge \omega). \]

Of course, this is interesting only when \( \omega \) has even degree, for otherwise \( \omega \wedge \omega = 0 \). Lemma 3.2 states that this action is Hamiltonian with homotopy moment map given by
\[ i^* F \circ j : g \to L_\infty (M, \omega \wedge \omega), \]
where \( F \) is as in theorem 2.3.

Remark 3.3. If an action \( G \acts (M, \omega) \) is Hamiltonian, then the action \( G \acts (M, \omega^m), m \in \mathbb{N}, \) is also Hamiltonian. This follows from a slight variation of the above reasoning, allowing \( \omega_a \) and \( \omega_b \) to be different.

Remark 3.4. The above reasoning also leads to the following more general statement. Consider again, for \( C = a, b \), actions \( G_C \acts M_C \) with corresponding homotopy moment maps \( f^C \). Assume now that there is a manifold \( B \) and \( G_C \)-equivariant submersions \( \pi_C : M_C \to B \). Then the diagonal action of \( G \) on the fiber product \( M_a \times_B M_b = (\pi_a \times \pi_b)^{-1}(\Delta B) \), endowed with the pullback by the inclusion of \( \omega_a \wedge \omega_b \), admits a homotopy moment map.

The special case \( M_a = M_b = B \) with \( \pi_a = \pi_b = \text{Id} \) delivers \( (M, \omega \wedge \omega) \). Another interesting special cases arises when \( \pi_C : M_C \to B \) are principal \( G_C \)-bundles (in that case the action on \( B \) is trivial).

Making more explicit the formula for \( i^* F \circ j \), we obtain:

**Proposition 3.5.** Let \( G \) be a Lie group with Lie algebra \( g \), and fix an action of \( G \) on an \( n \)-plectic manifold \( (M, \omega) \) with homotopy moment map \( f : g \to L_\infty (M, \omega), \) where \( n \) is odd. Then the \( G \) action on \( (M, \omega \wedge \omega) \) has a homotopy moment map, with components \((k = 1, \ldots, 2n + 1)\)
\[ g^k \to L_\infty (M, \omega \wedge \omega) \]
\[ x^1 \otimes \cdots \otimes x^k \mapsto 2 \sum_{m=1}^{k} \sum_{\sigma \in Sh_m} (-1)^\sigma c^a_{m-k-m} f_m \left( x^{\sigma(1)}, \ldots, x^{\sigma(m)} \right) \wedge t_{\sigma(m+1), \ldots, \sigma(k)} \omega. \]

Remark 3.6. The above double sum consist of \( 2^k - 1 \) summands.
Proof. Fix \( k \geq 1 \) and \( x^1 \wedge \cdots \wedge x^k \in \wedge^k \mathfrak{g} \). Notice that
\[
j(x^1) \wedge \cdots \wedge j(x^k) \in \wedge^k (\mathfrak{g} \otimes \mathfrak{g})
\]
is the sum of \( 2^k \) monomials in a natural way. For instance, introducing the notation \( j(x) = x_a \otimes x_b \), one has \( j(x^1) \wedge j(x^2) = x_a^1 \wedge x^3_a + x^2_a \wedge x^3_b \). Let \( X \) denote one of these monomials, let \( m \) be the number of elements in \( X \) decorated by the index “a”, and \( l := k - m \). If \( m = 0 \) or \( l = 0 \), it is clear by Thm. 2.3 that \( (i^* (F_k))(X) = F(X) \wedge \omega \).

Hence we consider only the case that \( m, l \neq 0 \). \( X \) can be written as
\[
(-1)^\sigma x_a^{\sigma(1)} \wedge \cdots \wedge x_a^{\sigma(m)} \wedge x_b^{\sigma(m+1)} \wedge \cdots \wedge x_b^{\sigma(k)}
\]
for a unique \( \sigma \in Sh_{m,l} \). By Thm. 2.3 we have
\[
F_k(X) = (-1)^\sigma \left[ c_{m,l}^a f_m \left( x_a^{\sigma(1)}, \ldots, x_a^{\sigma(m)} \right) \wedge t_{\sigma(m+1)},\ldots,\sigma(k) \omega 
+ c_{m,l}^b f_l \left( x_b^{\sigma(m+1)}, \ldots, x_b^{\sigma(k)} \right) \right].
\]
Denote by \( Y \) the monomial obtained from \( X \) interchanging each index “a” with the index “b”. Notice that \( Y \) can be written as
\[
(-1)^\tau x_a^{\tau(1)} \wedge \cdots \wedge x_a^{\tau(l)} \wedge x_b^{\tau(l+1)} \wedge \cdots \wedge x_b^{\tau(k)}
\]
for a unique \( \tau \in Sh(l,m) \). One can check that the first summand of \( F_k(X) \) in eq. (16) agrees exactly with the second summand of \( F_k(Y) \). Hence
\[
(i^* (F_k))(X + Y) = 2 \left[ (-1)^\sigma c_{m,l}^a f_m \left( x_a^{\sigma(1)}, \ldots, x_a^{\sigma(m)} \right) \wedge t_{\sigma(m+1)},\ldots,\sigma(k) \omega 
+ (-1)^\tau c_{l,m}^b f_l \left( x_b^{\tau(1)}, \ldots, x_b^{\tau(l)} \right) \wedge t_{\tau(l+1)},\ldots,\tau(k) \omega \right].
\]
Pairing two by two as above all the summands of \( m(x^1) \wedge \cdots \wedge m(x^k) \) and summing up, we see that \( (i^* (F_k) \circ j)(x^1 \wedge \cdots \wedge x^k) \) equals the expression given in the statement of this proposition.

Not all the homotopy moment maps for \((M, \omega \wedge \omega)\) arise from homotopy moment maps for \((M, \omega)\) as in Prop. 3.5 as the following example shows.

Example 3.7. Consider the symplectic manifold \( M := S^1 \times S^1 \times \mathbb{S}^1 \times \mathbb{R} \) with canonical “coordinates” \( \theta_1, \theta_2, \theta_3, x_4 \), and symplectic form \( \omega = d\theta_1 \wedge d\theta_2 + d\theta_3 \wedge dx_4 \). The action of the circle on \( M \) with generator \( \frac{\partial}{\partial \theta_1} \) is by symplectomorphisms, but does not admit a moment map since \( d\theta_2 \) is not exact.

On the other hand \( \omega \wedge \omega = 2d\theta_1 \wedge d\theta_2 \wedge d\theta_3 \wedge dx_4 \) is exact with invariant primitive (for instance, as primitive take \( -2x_3 d\theta_1 \wedge d\theta_2 \wedge d\theta_3 \)). Therefore by [3, §8] there is a homotopy moment maps for \( \omega \wedge \omega \), constructed canonically using this primitive.

3.3. Hyperkähler manifolds. The results in this subsection are closely related to Martin Callies’ results in [2].

Definition 3.8. A Hyperkähler manifold is a Riemannian manifold \((M, g)\) equipped with three complex structures \( J_i : TM \to TM \), \( i = 1, 2, 3 \), which satisfy the quaternionic relations \( J_i^2 = J_1 J_2 J_3 = -1 \) and are covariantly constant with respect to the Levi-Civita connection \( \nabla \) associated to \( g \), that is, \( \nabla J_i = 0 \), \( i = 1, 2, 3 \). We say then that \((g, J_1, J_2, J_3)\) is a Hyperkähler structure on \( M \).
As a consequence of the definition of Hyperkähler manifold, $M$ is also equipped with three symplectic two-forms $\omega_i$, $i = 1, 2, 3$, as follows

$$\omega_i(u, v) = g(J_i u, v), \quad u, v \in \mathfrak{X}(M), \quad i = 1, 2, 3.$$  

**Remark 3.9.** Notice that $\omega_i$ is non-degenerate as a consequence of $g$ and $J$ being non-degenerate and it is closed as a consequence of $J_i$ being covariantly constant. In fact, we have $\nabla \omega_i = 0$ for $i = 1, 2, 3$.

If $a_i \in \mathbb{R}$, $i = 1, 2, 3$, with $\sum_{i=1}^3 a_i^2 = 1$, then $\sum_{i=1}^3 a_i J_i$ is a complex structure on $M$, and $g$ is Kähler respect to it, with Kähler form $\sum_{i=1}^3 a_i \omega_i$. Hence, a Hyperkähler manifold $M$ is equipped with a sphere of complex structures and Kähler forms.

A Hyperkähler manifold can be also characterized as a $4k$-dimensional (real) Riemannian manifold with Riemannian holonomy contained in $Sp(k)$, where $k \geq 1$. Since $Sp(k) \subset SU(2k)$, every Hyperkähler manifold is Calabi-Yau and Ricci-flat. Notice that the natural representation of $Sp(k)$ on $\mathbb{R}^{4k}$ preserves three complex structures $J_i$, $i = 1, 2, 3$, that satisfy the quaternionic relations $J_i^2 = J_1 J_2 J_3 = -1$.

It turns out that

$$\Omega := \sum_{i=1}^3 \omega_i \wedge \omega_i$$

is a 3-plectic form.

The following Lemma follows immediately from Def. 1.8 using Eq. (4) and (5) (or alternatively from Prop. 2.1).

**Lemma 3.10.** Suppose we are given an action of a Lie group $H$ on a manifold $N$ preserving pre-n-plectic forms $\Omega_1$ and $\Omega_2$, with homotopy moment maps $F_1$ and $F_2$ respectively. Then the action of $H$ on $(N, \Omega_1 + \Omega_2)$ has homotopy moment map $F_1 + F_2$.

**Proposition 3.11.** Let $G$ be a Lie group acting on the Hyperkähler manifold $M$. Assume that $(M, \omega_i)$ admits an equivariant moment map $f^i$, for $i = 1, 2, 3$. Then the $G$ action on the 3-plectic manifold $(M, \Omega)$ admits a homotopy moment map, constructed canonically out of $f^1, f^2, f^3$.

**Proof.** Since $f^i$ is a moment map for $\omega_i$, Prop. 3.9 provides a homotopy moment map $F^i$ for $\omega_i \wedge \omega_i$, for $i = 1, 2, 3$. A homotopy moment map for $\Omega$ is then given by $F^1 + F^2 + F^3$, by Lemma 3.10.

Not all homotopy moment maps for $\Omega$ arise as from moment maps for the $\omega_i$, as the following variation of Ex. 3.7 shows.

**Example 3.12.** Consider the Hyperkähler manifold $\mathbb{R}^4$ with the canonical metric and the complex structures $J_1, J_2, J_3$ given by quaternionic multiplication by $i, j, k \in \mathbb{H} = \mathbb{R}^4$. Dividing by the lattice $\mathbb{Z}^3 \times \{0\}$ we obtain a Hyperkähler structure on $M := S^1 \times S^1 \times S^1 \times \mathbb{R}$ (the product of the 3-torus with the real line), on which we have induced “coordinates” $\theta_1, \theta_2, \theta_3, x_4$. The symplectic structures on $M$ associated to the distinguished complex structures are

$$\omega_1 = d\theta_1 \wedge d\theta_2 + d\theta_3 \wedge dx_4, \quad \omega_2 = d\theta_1 \wedge d\theta_3 - d\theta_2 \wedge dx_4, \quad \omega_3 = d\theta_1 \wedge dx_4 + d\theta_2 \wedge d\theta_3.$$  

The action of the circle on $M$ with generator $\frac{\partial}{\partial \theta_1}$ preserves each $\omega_i$, however $\omega_1$ and $\omega_2$ have no moment map for this action. On the other hand, it is easily computed that $\Omega := \sum_{i=1}^3 \omega_i \wedge \omega_i = 6d\theta_1 \wedge d\theta_2 \wedge d\theta_3 \wedge dx_4$, and $\Omega$ admits a homotopy moment map as we explained in Ex. 3.7.
4. Embeddings of $L_\infty$-algebras associated to closed differential forms

Let $(M_C, \omega_C)$ be a pre-$n_C$-plectic manifold, $C = a, b$. We consider the pre-$n_a + n_b + 1$-plectic manifold

$$(M \equiv M_a \times M_b, \omega \equiv \omega_a \wedge \omega_b).$$

Being $(M_C, \omega_C)$ a pre-$n_C$-plectic manifold, it is equipped with a Lie $n_C$-algebra $L_\infty(M_C, \omega_C)$, constructed exclusively out of $\omega_C$ and the de Rahm differential $d$. The purpose of this section is to find an $L_\infty$-morphism

$$H: L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b) \rightsquigarrow L_\infty(M_a \times M_b, \omega_a \wedge \omega_b)$$

whose first component is an embedding. We will exhibit such a morphism in Thm. 4.2.

Remark 4.1. As in the previous section, we will slightly abuse notation, denoting a differential form on $M_C$ and its pullback to $M_a \times M_b$, via the canonical projection, by the same symbol. Similarly, given a vector field on $M_C$, we denote by the same symbol its horizontal lift to the product manifold $M_a \times M_b$.

Further, we denote by $l^a$ and $l^b$ the multi-brackets of $L_\infty(M_a, \omega_a)$ and $L_\infty(M_b, \omega_b)$ respectively, and by $l$ the multi-brackets of $L_\infty(M, \omega)$.

4.1. The construction of $H$ and its properties. The source of $H$ is $L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b)$, which, being a direct sum of $L_\infty$-algebras, is itself an $L_\infty$-algebra. We spell this out, assuming $n_b \geq n_a$. The underlying complex is

\[
C^\infty(M_b) \to \cdots \to C^\infty(M_a) \oplus \Omega^{n_b-n_a}(M_b) \to \cdots \to \Omega^{n_a-1}(M_a) \oplus \Omega^{n_b-1}(M_b).
\]

Its multibrackets $l^a_{k,b}$ (for $k \geq 1$) are defined by

$$l^a_{k,b} (\alpha_1 \oplus \beta_1, \ldots, \alpha_k \oplus \beta_k) = l^a_k (\alpha_1, \ldots, \alpha_k) \oplus l^b_k (\beta_1, \ldots, \beta_k)$$

where $\alpha_1 \oplus \beta_1, \ldots, \alpha_k \oplus \beta_k \in L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b)$. Notice that $L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b)$ is a Lie $N$-algebra, where $N := \text{Max}\{n_a, n_b\}$, while $L_\infty(M, \omega)$ - the target of $H$ - is a Lie $(n_a + n_b + 1)$-algebra.

We now argue that there is a natural candidate for the first component of an $L_\infty$-morphism as in (17). Given $\alpha \in \Omega^{n_a-1}_\text{Ham}(M_a)$ and $\beta \in \Omega^{n_b-1}_\text{Ham}(M_b)$, take hamiltonian vector fields $X_\alpha$ and $X_\beta$ for them, and consider $X_\alpha + X_\beta$ on $M_a \times M_b$. It is again a hamiltonian vector field, since

$$l(X_\alpha + X_\beta) \omega = -d[\alpha \wedge \omega + \omega_a \wedge \beta].$$

Hence there is a well-defined map

$$h: \Omega^{n_a-1}_\text{Ham}(M_a) \oplus \Omega^{n_b-1}_\text{Ham}(M_b) \to \Omega^{n_a+n_b}_\text{Ham}(M)$$

$$\alpha + \beta \mapsto \int \omega_a + \omega_b \wedge \beta.$$ 

Endow $\Omega^{n_a-1}_\text{Ham}(M_a) \oplus \Omega^{n_b-1}_\text{Ham}(M_b)$ with the bracket $l^a_{2} + l^b_{2}$, i.e., the sum of the binary brackets $l^a_2$ and $l^b_2$ on the two factors. Denoting all binary brackets by $\{\cdot, \cdot\}$ to ease the notation, we have

$$h\left(\{\alpha_1 \oplus \beta_1, \alpha_2 \oplus \beta_2\}\right) = \left\{h(\alpha_1 \oplus \beta_1), h(\alpha_2 \oplus \beta_2)\right\} + (-1)^{n_a}d[\alpha_1 \wedge d\beta_2 - \alpha_2 \wedge d\beta_1].$$

That is, $h$ does not preserve the binary brackets on the nose, but just up to an exact term. This a characteristic feature of the first component of an $L_\infty$-morphism. Indeed, in Thm. 4.2 we extend $h$ to an $L_\infty$-morphism from $L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b)$ to $L_\infty(M, \omega)$. The concrete expression of the $L_\infty$-morphism is motivated by the results of Section 2 and in
particular by Theorem 4.2.

We will use the square brackets introduced in Def. 1.6 for \( C = a,b \). Recall that \([\ldots]^C_k\) is defined for all \( k \geq 0 \), and that it vanishes unless all entries have degree zero (i.e., are Hamiltonian forms). Recall also that \([\ldots]^C_0 = -\omega_C\) and that for \( k \geq 1 \), by Remark 4.4,

\[ [\alpha_1, \ldots, \alpha_k]^C = \{\alpha_1, \ldots, \alpha_k\} - \delta_{k,1}d_C\alpha_1, \quad C = a,b, \]

where \( \{\alpha_1, \ldots, \alpha_k\} \) is the \( k \)-bracket of \( L_\infty(M_C, \omega_C) \) and \( d_C \) is the de Rham differential on \( M_C \).

**Theorem 4.2.** Let \((M_C, \omega_C)\) be pre-\( n_C \)-plectic manifolds. There is an \( L_\infty \)-morphism

\[ H: L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b) \leadsto L_\infty(M_a \times M_b, \omega_a \wedge \omega_b) \]

whose first component is injective. The components of \( H \) will be denoted by \( H_l \) \(( l \geq 1 \)). They are determined by graded skew-symmetry and the requirement that

\[
H_{k+m}(\alpha_1, \ldots, \alpha_k, \beta_1, \ldots, \beta_m) = \sum_{m_{1|} \delta_{k,1} \alpha_1}^a \delta_{m_{1|} \beta_1} \alpha_1 \wedge [\beta_1, \ldots, \beta_m]^b_m
\]

where \( k + m \geq 1 \), \( \alpha_1, \ldots, \alpha_k \in L_\infty(M_a, \omega_a) \), \( \beta_1, \ldots, \beta_m \in L_\infty(M_b, \omega_b) \), \([\ldots]^C_0 = -\omega_C\) and the coefficients are, for all \( i \leq 0 \):

\begin{align*}
t_{m,i}^a &= -\frac{1}{2} (-1)^{m(n_a+1+i)}, \quad m \geq 1 \\
t_{k,i}^b &= -\frac{1}{2} (-1)^{i(n_a+1)+k}, \quad k \geq 1 \\
\end{align*}

and

\begin{align*}
t_{0,i}^a &= -1, \\
t_{0,i}^b &= -(-1)^{i(n_a+1)}. \\
\end{align*}

Above, \( \delta \) denotes the Kronecker delta, and \(|\alpha_1|\) refers to the degree\(^9\) of \( \alpha_1 \) as an element of \( L_\infty(M_a, \omega_a) \).

**Remark 4.3.** Notice that \( H \), applied to a family of elements lying in \((L_\infty(M_a, \omega_a) \oplus \{0\}) \cup \{0\} \oplus L_\infty(M_b, \omega_b)\), vanishes unless: either exactly one element is of the form \( \alpha \oplus 0 \) and the remaining elements have degree zero, or exactly one element is of the form \( 0 \oplus \beta \) and the remaining elements have degree zero.

**Remark 4.4.** The first component \( H_1 \) is clearly injective for it is given by

\[ H_1(\alpha) = \alpha \wedge \omega_b \quad \text{and} \quad H_1(\beta) = (-1)^{\beta(n_a+1)} \omega_a \wedge \beta, \]

where \( \alpha \in L_\infty(M_a, \omega_a) \) and \( \beta \in L_\infty(M_b, \omega_b) \).

The restriction of \( H_1 \) to \( L_\infty(M_a, \omega_a) \oplus \{0\} \) is a strict morphism. This can be seen using Remark 4.3 since the higher components of \( H \) vanish if all entries lie in \( L_\infty(M_a, \omega_a) \oplus \{0\} \), or alternatively it can be seen directly using Lemma 4.4 below. The same holds for the restriction of \( H \) to \( \{0\} \oplus L_\infty(M_b, \omega_b) \).

---

\(^9\)This differs by \( n_a - 1 \) from the degree of \( \alpha_1 \) as a differential form.
Remark 4.5. Possibly up to signs, the $L_\infty$-morphism $H$ given Thm. [12] has the following property: for any action of a Lie group $G_C$ on $(M_C, \omega_C)$ with homotopy moment map $f^C$ ($C = a, b$), one has

$$F = H \circ (f^a \oplus f^b),$$

where $F$ is the homotopy moment map constructed in Thm. [2,3] out of $f^a$ and $f^b$. In other words, the diagram (2) commutes. Recall that the composition $\psi \circ \phi$ of two $L_\infty$-morphisms is given by $(\psi \circ \phi)_k = \sum_{l=1}^k \sum_{k_1 + \cdots + k_l = k} \pm \psi_l \circ (\phi_{k_1} \otimes \cdots \otimes \phi_{k_l})$.

Example 4.6. Let $n_a = n_b = 1$. That is, $(M_a, \omega_a)$ and $(M_b, \omega_b)$ are pre-symplectic manifolds, and so $(M, \omega)$ is a pre-3-plectic manifold. Consequently, the cochain complex $L$ underlying the Lie 3-algebra $L_\infty(M, \omega)$ is

$$C^\infty(M) \to \Omega^1(M) \to \Omega^2(M) \to \Omega^3_{\text{Ham}}(M).$$

On the other hand, $L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b) = C^\infty(M_a) \oplus C^\infty(M_b)$ is just a Lie-algebra. The higher components of the $L_\infty$-embedding of theorem [12] read

$$H_2(f_a \oplus f_b, g_a \oplus g_b) = \frac{1}{2} (f_a \wedge dg_b - df_a \wedge g_b - g_a \wedge df_b + dg_a \wedge f_b),$$

$$H_3(f_a \oplus f_b, g_a \oplus g_b, h_a \oplus h_b) = \frac{1}{2} (f_a \{g_b, h_b\}_2 + f_b \{g_a, h_a\}_2 - g_a \{f_b, h_b\}_2$$

$$- g_b \{f_a, h_a\}_2 + h_a \{f_b, g_b\}_2 + h_b \{f_a, g_a\}_2),$$

for all $f_C, g_C, h_C \in C^\infty(M_C)$, $C = a, b$. Notice that since $L_\infty(M_a, \omega_a) \oplus L_\infty(M_b, \omega_b)$ is a Lie algebra, we can use formulae [11] and [15] to double-check that $H$ is indeed an $L_\infty$-morphism.

4.2. The proof. We now turn to the proof of Thm. [12]. We will use repeatedly the following Lemma.

Lemma 4.7. For all $\alpha_1, \ldots, \alpha_k \in L_\infty(M_a, \omega_a)$ and $\beta_1, \ldots, \beta_m \in L_\infty(M_b, \omega_b)$, where $k, m \geq 0$ and $k + m \geq 1$, we have

$$[\alpha_1\omega_b, \ldots, \alpha_k\omega_b, \omega_a\beta_1, \ldots, \omega_a\beta_m]_{k+m} = (-1)^{m(n_a+1)}[\alpha_1, \ldots, \alpha_k]_k \wedge [\beta_1, \ldots, \beta_m]_m.$$

Proof. We may assume that all the $\alpha$ and $\beta$ have degree zero, for otherwise the equation is trivially satisfied. It is straightforward to verify that the hamiltonian vector field of $\alpha_\omega_b$ (w.r.t $\omega_a \wedge \omega_b$) equals the hamiltonian vector field $X_\alpha$ of $\alpha$ (w.r.t $\omega_a$), and the exact analogous statement holds for $\omega_a\beta$. The statement of the lemma follows from

$$t(X_{\alpha_1} \wedge X_{\alpha_2} \wedge \cdots \wedge X_{\alpha_k})(\omega_a \wedge \omega_b) = (-1)^{m(n_a+1-k)}t(X_{\alpha_1} \wedge \cdots \wedge X_{\alpha_k})\omega_a \wedge t(X_{\beta_1} \wedge \cdots \wedge X_{\beta_m})\omega_b$$

together with the identity $\varsigma(k)\varsigma(m)\varsigma(k + m) = -(-1)^{km}$.

According to the conditions that an $L_\infty$-morphism has to obey (see for instance [11], Def. 2.4), we have to check that the following relation holds for all $N \in \mathbb{N}_{>0}$ and for all
\[ \bar{x} = (x_1, \ldots, x_N) \in \left( L_\infty (M_a, \omega_a) \oplus L_\infty (M_b, \omega_b) \right)^{\otimes N}; \]

\[
(19) \quad \sum_{\substack{i+j=N+1 \\sigma \in Sh_{i,j}}} (-1)^{i(j-1)} (1)^{\ell} \in (\sigma, \bar{x}) \mathcal{H}_j \left( l_{ab}^i \left( x_{\sigma(1)}, \ldots, x_{\sigma(i)}, x_{\sigma(i+1)}, \ldots, x_{\sigma(N)} \right) \right) 
\]

\[
= \sum_{\ell=1}^{N} \sum_{\substack{N_1+\cdots+N_\ell=N \\ell_1 \leq \cdots \leq \ell_\ell}} (-1)^{\gamma(\ell, N)} \sum_{\sigma \in Sh_{N_1, \ldots, N_\ell}} (1)^{\epsilon(\sigma, \bar{x})} \epsilon \left( \rho, \bar{H} \right) 
\]

\[ l_\ell \left( H_{N_1}(x_{\sigma(1)}, \ldots, x_{\sigma(N_1)}), \ldots, H_{N_\ell}(x_{\sigma(N-N_\ell+1)}, \ldots, x_{\sigma(N)}) \right). \]

Here
- \( \gamma(\ell, N) = \frac{(\ell-1)}{2} + N_1(\ell-1) + N_2(\ell-2) + \cdots + N_{\ell-1} \).
- \( Sh_{N_1, \ldots, N_\ell} \subset Sh_{N_1, \ldots, N_\ell} \) is the set of \( (N_1, \ldots, N_\ell) \)-unshuffles such that \( \sigma(N_1 + \cdots + N_{\ell-1} + 1) < \sigma(N_1 + \cdots + N_{\ell-1} + N_\ell + 1) \) whenever \( N_\ell = N_{\ell+1} \).
- \( \bar{H} = (H_{N_1}, \ldots, H_{N_\ell}, x_{\sigma(1)}, \ldots, x_{\sigma(N)}) \) and \( \rho \) is the permutation of \( \{1, \ldots, \ell + N\} \) sending \( \bar{H} \) to \( (H_{N_1}, x_{\sigma(1)}, \ldots, x_{\sigma(N_1)}), \ldots, H_{N_\ell}, x_{\sigma(N-N_\ell+1)}, \ldots, x_{\sigma(N)} \).

As usual, \( (-1)^{\sigma} \) denotes the sign of the permutation \( \sigma \) and \( \epsilon(\sigma, \bar{x}) \) denotes the Koszul sign.

**Remark 4.8.** Notice that on the l.h.s. of eq. (19), the sign of the summand corresponding to \( i = N, j = 1 \) is \(+1\) (since the only permutation appearing is the identity).

On the r.h.s., the sign of the summand corresponding to \( \ell = N \) is \(+1\). Indeed \( N_1 = \cdots = N_\ell = 1 \), so that \( \gamma(\ell, N) = +1, \sigma = id \), and all \( H_{N_\ell} \) have degree zero. Further, the sign of the summand corresponding to \( \ell = 1 \) is also \(+1\), since \( \gamma(1, N) = +1, \sigma = id \) and \( \rho = id \).

**Proof of Thm. 4.2.** Let \( C = a, b \). We first check that \( H_j \) has degree \(-1 - j\). For \( j = 1 \) this is clear. For \( j = k + m \geq 2 \), we use that \([\ldots]_m^l \) as an operation on \( L_\infty (M_C, \omega_C) \), has degree \(-m\). Hence, for instance, if the elements \( \alpha_1, \beta_1, \ldots, \beta_m \) all have degree zero, then \( H_{k+m}(\alpha_1, \beta_1, \ldots, \beta_m) = \pm \frac{1}{2} \alpha_1[\beta_1, \ldots, \beta_m]_m^b \) is the product of a \( n_a - 1 \) and \( (n_b - 1) + (2 - m) \) form, that is, a \( n_a + n_b - m \) form, which therefore is an element of \( L_\infty (M_a \times M_b, \omega_a \wedge \omega_b) \) of degree \(-m = 1 - (1 + m) = 1 - j\).

The rest of the proof is devoted to checking that \( H \) is an \( L_\infty \)-morphism. Our strategy is as follows. We propose an educated ansatz for \( H \) depending on some arbitrary parameters and then we will impose on it the \( L_\infty \)-morphism conditions (19). Equations (19) will turn out to be an over-determined system of equations for the parameters of the ansatz, and we will show that a solution is given by eq. (15).

The ansatz is the following: for the first component of \( H \),

\[ H_1(\alpha) = s_{0,|\alpha|}^a \alpha \wedge (-\omega_b), \quad H_1(\beta) = s_{0,|\beta|}^b (-\omega_a) \wedge \beta. \]

For the higher components of \( H \), i.e. for \( k + m \geq 2 \), \( H_{k+m}(\alpha_1, \ldots, \alpha_k, \beta_1, \ldots, \beta_m) \) equals

\[
(20) \quad \frac{s_{m,|\alpha_1|}^a}{2} \delta_{k,1} \alpha_1 \wedge [\beta_1, \ldots, \beta_m]_m^b + \frac{s_{k,|\beta_1|}^b}{2} \delta_{m,1} [\alpha_1, \ldots, \alpha_k]_m^a \wedge \beta_1,
\]

where \( \alpha_1, \ldots, \alpha_k \in L_\infty (M_a, \omega_a) \) and \( \beta_1, \ldots, \beta_m \in L_\infty (M_b, \omega_b) \) are homogeneous elements of their respective graded spaces. Here \( s_{m,|\alpha_1|}^a \) depends on the number of \( \beta \)'s and the degree of \( \alpha_1 \), it cannot depend on the number of \( \alpha \)'s since if there is more than one the corresponding term in (20) is zero, and it cannot depend on the degree of the \( \beta \)'s since if \( |\beta_1 \otimes \cdots \otimes \beta_m| < 0 \) then the corresponding term in (20) is again zero. A similar discussion applies to \( s_{k,|\beta_1|}^b \).
We now apply condition \( (19) \) to our ansatz for \( H \) and elements \( \alpha_1, \ldots, \alpha_k, \beta_1, \ldots, \beta_m \). We are going to consider six different cases depending on \( k \) and \( m \), namely \( \{k \geq 1, m = 0\} \), \( \{k = 0, m \geq 1\} \), \( \{k = 1, m = 1\} \), \( \{k > 1, m > 1\} \), \( \{k = 1, m > 1\} \) and \( \{k > 1, m = 1\} \). We will use repeatedly Remark \(4.3\) and the fact that for \( i \geq 2 \) the multibrackets \( l_i \) vanish unless all entries have degree zero.

**Case \( \{k \geq 1, m = 0\} \).**

This case will allow us to calculate \( s_{0,i}^a \), \( i \leq 0 \). The condition \( (19) \) evaluated on \( \alpha_1, \ldots, \alpha_k \in L_\infty(M_a, \omega_a) \) reads

\[
(21) \quad H_1 \left( l_k^a (\alpha_1, \ldots, \alpha_k) \right) = l_k \left( H_1 (\alpha_1), \ldots, H_1 (\alpha_k) \right),
\]

as one sees using Rem. \(4.3\) together with Remark \(4.8\) to determine the signs.

Using now that

\[
H_1 \left( l_k^a (\alpha_1, \ldots, \alpha_k) \right) = -s_{0,2-k+|\alpha|}^a l_k^a (\alpha_1, \ldots, \alpha_k) \wedge \omega_b,
\]

\[
l_k \left( H_1 (\alpha_1), \ldots, H_1 (\alpha_k) \right) = (s_{0,0}^a \omega_a) \ldots (s_{0,|\alpha|}^a) l_k^a (\alpha_1, \ldots, \alpha_k) \wedge \omega_b,
\]

where \( |\alpha| = |\alpha_1 \cdots \otimes \alpha_k| \) and using Lemma \(4.4\) in the second equation when \( k \geq 2 \), we conclude that we can choose \( s_{0,i}^a = -1 \) for all \( i \leq 0 \).

**Case \( \{k = 0, m \geq 1\} \).**

This case will allow as to calculate \( s_{0,i}^b \), \( i \leq 0 \). The condition \( (19) \) evaluated on \( \beta_1, \ldots, \beta_m \in L_\infty(M_b, \omega_b) \), similarly to the case above, reads

\[
(22) \quad H_1 \left( t_m^b (\beta_1, \ldots, \beta_m) \right) = l_m \left( H_1 (\beta_1), \ldots, H_1 (\beta_m) \right).
\]

Using now that

\[
H_1 \left( t_m^b (\beta_1, \ldots, \beta_m) \right) = -s_{0,2-m+|\beta|}^b \omega_a \wedge t_m (\beta_1, \ldots, \beta_m),
\]

\[
l_m \left( H_1 (\beta_1), \ldots, H_1 (\beta_m) \right) = (s_{0,0}^b \omega_b) \ldots (s_{0,|\beta|}^b) (-1)^m (\omega_a \wedge l_m (\beta_1, \ldots, \beta_m),
\]

where \( |\beta| = |\beta_1 \cdots \otimes \beta_m| \) and using Lemma \(4.4\) in the second equation when \( m \geq 2 \), we conclude (taking \( m = 1 \)) that equation \( (21) \) implies \( s_{0,1+|\beta|} = (-1)^{m+1} s_{0,|\beta|}^b \) and therefore

\[
s_{0,i}^b = (-1)^{i+1} s_{0,0}^b, \quad i \leq 0.
\]

Plugging this into eq. \( (22) \) it can be easily verified that eq. \( (22) \) is solved by

\[
s_{0,i}^b = -(-1)^{i+1}, \quad i \leq 0.
\]

**Case \( \{k = 1, m = 1\} \).**

This case will allow as to find \( s_{1,i}^a \) and \( s_{1,i}^b \) for \( i \leq 0 \). The condition \( (19) \) evaluated on \( \alpha, \beta \), where \( \alpha \in L_\infty(M_a, \omega_a) \) and \( \beta \in L_\infty(M_b, \omega_b) \), reads

\[
(23) \quad -H_2 \left( l_i^a (\alpha, \beta) \right) = (-1)^{|\alpha|} H_2 \left( \alpha, l_i^b (\beta) \right) = l_1 \left( H_2 (\alpha, \beta) \right) + l_2 \left( H_1 (\alpha), H_1 (\beta) \right).
\]

(The l.h.s. corresponds to the summand \( i = 1, j = 2 \) in \( (19) \), and the signs for the r.h.s. follow from Remark \(4.8\)) Recall that by ansatz \( (20) \), for all \( A \in L_\infty(M_a, \omega_a) \) and \( B \in
In order to solve equation (23) we have to analyze the different cases in terms of the degree of \( \alpha \) and \( \beta \). If \( |\alpha| = |\beta| = 0 \) the l.h.s. of (23) is zero while the r.h.s. is
\[
-\frac{s_{1,0}^a}{2} d\alpha \wedge d\beta - (-1)^{n_\beta} \frac{s_{1,0}^b}{2} d\alpha \wedge d\beta + (-1)^{n_\alpha} d\alpha \wedge d\beta,
\]
as one sees using Lemma 1.7. Hence we can take
\[
(24) \quad s_{1,0}^a = (-1)^{n_\alpha}, \quad s_{1,0}^b = 1.
\]
Now, if \( |\alpha| = 0 \) and \( |\beta| < 0 \) the first and fourth term in equation (23) vanish, and that equation translates into
\[
-\frac{s_{1,|\beta|+1}^b}{2} [\alpha]_{1}^a \wedge l_{1}^b(\beta) = (-1)^{n_\beta} \frac{s_{1,|\beta|}^b}{2} [\alpha]_{1}^a \wedge l_{1}^b(\beta),
\]
implying that \( s_{1,|\beta|+1}^b = (-1)^{n_\beta+1} s_{1,|\beta|}^b \). Together with equation (24) this implies finally that
\[
s_{1,i}^b = (-1)^{i(n_\beta+1)}, \quad i \leq 0.
\]
By means of a completely analogous calculation for the case \( |\alpha| < 0 \) and \( |\beta| = 0 \) we obtain \( s_{i,|\alpha|+1}^a = -s_{i,|\alpha|}^a \), so we can choose
\[
s_{1,i}^a = (-1)^{n_\alpha+i}, \quad i \leq 0.
\]
Lastly, the case \( |\alpha| < 0 \) and \( |\beta| < 0 \) is trivial since both sides of equation (23) vanish.

**Case \( \{k > 1, m > 1\} \).**

This case will allow us to find \( s_{k,i}^a \) and \( s_{m,i}^b \) for \( i \leq 0 \) and \( k, m \geq 1 \). The condition (19) evaluated on \( (\alpha_0, \ldots, \alpha_k, \beta_1, \ldots, \beta_m) \), where \( \alpha_0, \ldots, \alpha_k \in L_\infty(M_a, \omega_a) \) and \( \beta_1, \ldots, \beta_m \in L_\infty(M_b, \omega_b) \), reduces to
\[
(25) \quad (-1)^km H_{m+1} \left( l_{k}^a(\alpha_0, \ldots, \alpha_k), \beta_1, \ldots, \beta_m \right) + (-1)^k H_{k+1} \left( \alpha_0, \ldots, \alpha_k, l_{m}^b(\beta_1, \ldots, \beta_m) \right)
= l_{k+m} \left( H_{1}(\alpha_0), \ldots, H_{1}(\alpha_k), H_{1}(\beta_1), \ldots, H_{1}(\beta_m) \right),
\]
where in the l.h.s. only the summands corresponding to \( i = k \) and \( i = m \) appear by Rem. 4.3 and for the r.h.s. we use Remark 4.8 to determine the signs (a term involving \( l_1 \) does not appear, again due to Rem. 4.3).

From Def. 1.5 it can be seen that equation (25) is only non-trivial if \( |\alpha| = |\beta| = 0 \). Therefore, we will assume henceforth that this is the case. The two terms on the l.h.s. of equation (25) can be written as follows:
\[
H_{m+1} \left( l_{k}^a(\alpha_0, \ldots, \alpha_k), \beta_1, \ldots, \beta_m \right) = \frac{s_{m,2-k}^a}{2} [\alpha_0, \ldots, \alpha_k]_k^a \wedge [\beta_1, \ldots, \beta_m]_m^b,
\]
\[
H_{k+1} \left( \alpha_0, \ldots, \alpha_k, l_{m}^b(\beta_1, \ldots, \beta_m) \right) = \frac{s_{k,2-m}^b}{2} [\alpha_0, \ldots, \alpha_k]_k^a \wedge [\beta_1, \ldots, \beta_m]_m^b.
\]
By Lemma 1.7 the r.h.s. of equation (25) can be written as
\[10\]The fact that necessarily \( |\alpha| = 0 \) was already used to determine the sign of the second term on the l.h.s. above.
\[ l_{k+m} (H_1(\alpha_1), \ldots, H_1(\alpha_k), H_1(\beta_1), \ldots, H_1(\beta_m)) = -(-1)^{m(n+1)} [\alpha_1, \ldots, \alpha_k]_k^a \land [\beta_1, \ldots, \beta_m]_m^b. \]

From the last three equations we obtain

\[ (-1)^{km} \frac{s_{m,2-k}^a}{2} + (-1)^{k} \frac{s_{k,2-m}^b}{2} = -(-1)^{m(n+1)}, \]

which is solved by

\[ s_{m,i}^a = -(-1)^{m(n+i+1)}, \quad s_{k,i}^b = -(-1)^{i(n+a+1)+k}, \quad m, k > 1, i \leq 0. \]

**Cases \( \{k = 1, m > 1\} \) and \( \{k > 1, m = 1\} \).**

Notice that this point we have already explicitly solved all the parameters \( s_{m,i}^a \) and \( s_{k,i}^b \) for all \( k, m \geq 0 \) and \( i \leq 0 \). Although this was obtained by separately analyzing different cases given by different values of \( k \) and \( m \), the result be summarized in a single formula, namely

\[ s_{m,i}^a = -(-1)^{m(n+i+1)}, \quad s_{k,i}^b = -(-1)^{i(n+1)+k}, \quad m, k > 0, i \leq 0. \]

However, there remain two cases to be considered, namely \( \{k = 1, m > 1\} \) and \( \{k > 1, m = 1\} \). Notice that we do not have any parameter left to be fixed, so checking those cases is really a constraint.

We consider first the case \( \{k = 1, m > 1\} \). At first, we also assume \( m > 2 \). The condition \( \{19\} \) evaluated on \( (\alpha, \beta_1, \ldots, \beta_m) \) reads

\[ (-1)^m H_{m+1}(\hat{l}_1^0(\alpha), \beta_1, \ldots, \beta_m) + \sum_{1 \leq p < q \leq m} (-1)^{p+q} H_m \left( \alpha, \hat{l}_1^0(\beta_q, \beta_p), \beta_1, \ldots, \hat{\beta}_p, \ldots, \hat{\beta}_q, \ldots, \beta_m \right) \]

\[ + H_2((\hat{l}_m(\beta_1, \ldots, \beta_m), \alpha) \]

\[ = l_{m+1}(H_1(\alpha), H_1(\beta_1), \ldots, H_1(\beta_m)) + l_1(H_{m+1}(\alpha, \beta_1, \ldots, \beta_m)). \]

(On the l.h.s. the first term corresponds to \( i = 1 \) in eq. \( \{19\} \), the second to \( i = 2 \), and the third to \( i = m \); not other values of \( i \) contribute by Remark \[4.3\].) On the r.h.s. only the terms corresponding to \( l_{m+1} \) and \( l_1 \) appear since the multibrackets of \( L_\infty(M_a \times M_b) \) with two or more entries vanish unless all the entries have degree zero, and the signs are given by Remark \[4.3\].) We may assume \( |\beta_1| = \cdots = |\beta_m| = 0 \), for otherwise both sides of the above equation vanish by Remark \[4.3\].

The first term on the l.h.s. of eq. \( \{27\} \) reads

\[ (-1)^m \frac{s_{m,|\alpha|+1}^a}{2} l_1(\alpha) \land [\beta_1, \ldots, \beta_m]. \]

The second term on the l.h.s. equals

\[ \frac{s_{m-1,|\alpha|}^a}{2} \alpha \land d[\beta_1, \ldots, \beta_m]. \]

\[ \text{\[11\]This assumption was already used to determine the sign of the second term on the l.h.s. above.} \]
To see this, we use the computation

\[(30) \quad \sum_{1 \leq p < q \leq m} (-1)^{p+q} L^q(\beta_p, \beta_q) \cdot \beta_1, \ldots, \hat{\beta}_p, \ldots, \hat{\beta}_q, \ldots, \beta_m \]

\[= \varsigma(m-1) \sum_{1 \leq p < q \leq m} (-1)^{p+q} t(X_{\beta_p} \beta_q) \wedge X_{\beta_1} \wedge \cdots \wedge X_{\beta_p} \wedge \cdots \wedge X_{\beta_q} \wedge \cdots \wedge X_{\beta_m} \omega_b \]

\[= \varsigma(m-1)(-1)^m dt(X_{\beta_1} \wedge \cdots \wedge X_{\beta_m}) \omega_b \]

\[= d[\beta_1, \ldots, \beta_m]. \]

where we used [3, Lemma 9.2] in the second equality and \(\varsigma(m-1)\varsigma(m) = (-1)^m\).

The third term on the l.h.s. reads

\[(31) \quad - \frac{s^b_{1,2-m} \alpha}{2} \wedge [\beta_1, \ldots, \beta_m] - \frac{s^a_{1,|\alpha|} \alpha}{2} \wedge [\beta_m(\beta_1, \ldots, \beta_m)], \]

where the second summand vanishes because of the assumption \(m > 2\).

The first term on the r.h.s. of eq. (27), using Lemma 4.7 and \(- s^b_{0,0} = - s^b_{0,0} = 1\), equals

\[(32) \quad (-1)^m(n_a+1) \alpha \wedge [\beta_1, \ldots, \beta_m]. \]

The last term on the r.h.s. is

\[(33) \quad \frac{s^a_{m,|\alpha|} l_1(\alpha \wedge [\beta_1, \ldots, \beta_m])}{2} = \frac{s^a_{m,|\alpha|}}{2} \left( d\alpha \wedge [\beta_1, \ldots, \beta_m] + (-1)^{n_a-1-|\alpha|} \alpha \wedge d[\beta_1, \ldots, \beta_m] \right). \]

The term in (29) cancels out with the second summand in (33). Further, using that \(l_1 \alpha - [\alpha] = d\alpha\) by Remark 1.7 and the fact that \([\alpha]\) vanishes if \(|\alpha| \neq 0\), one checks that the term (28) minus one half the term (32) equals \(\frac{s^a_{m,|\alpha|}}{2} d\alpha \wedge [\beta_1, \ldots, \beta_m]\), which is exactly the first summand in eq. (33). Finally, the term (31) cancels out with one half the term (32).

Now, if \(k = 1, m = 2\), then the term (29) is omitted (because the summand \(i = 2\) on the l.h.s. of condition (19) is already given by the term (31)), and in (31) the second summand no longer vanishes. We conclude that the case \(\{k = 1, m > 1\}\) indeed works out with the choice of parameters given in (26).

One check in a similar way that the same holds for the case \(\{k > 1, m = 1\}\). This concludes the proof that \(H\), as defined in the statement of the theorem, is an honest \(L_{\infty}\)-morphism. \(\square\)

5. A curved \(L_{\infty}\)-algebra associated to a closed differential form

Let \((M, \omega)\) be a pre-\(n\)-plectic manifold. We saw that one can associate to it an \(L_{\infty}\)-algebra \(L_{\infty}(M, \omega)\), whose definition we recalled in Def. 1.5. For \(k \geq 2\), the \(k\)-th multibracket of \(L_{\infty}(M, \omega)\) is essentially given by contracting with \(\omega\) the hamiltonian vector fields of \(k\) hamiltonian forms, while the unary bracket is defined differently, as the de Rham differential. On the other hand, contracting with \(\omega\) the hamiltonian vector fields of an arbitrary number of hamiltonian forms is a natural operation, which we introduced in Def. 1.6 using the notation \([\ldots]\), and which proved to be necessary to describe the \(L_{\infty}\)-embedding obtained in Thm. 1.2. In this section we show that the operation \([\ldots]\) can be extended to a curved \(L_{\infty}\)-algebra structure canonically associated to \((M, \omega)\), whose “curvature” is \(-\omega\).

Definition 5.1. A curved \(L_{\infty}\)-algebra is a \(\mathbb{Z}\)-graded vector space \(W\) equipped with a collection \((k \geq 0)\) of linear maps \(l_k: \otimes^k W \to W\) of degree \(2 - k\), graded antisymmetric, and
satisfying for every \( m \geq 0 \) and for every collection of homogeneous elements \( w_1, \ldots, w_m \in W \) the following relations:

\[
(34) \quad \sum_{i+j=m+1 \atop i \geq 0, j \geq 1} (-1)^{i(j-1)} \sum_{\sigma \in S_{i,m-i}} (-1)^{\sigma} \epsilon(\sigma) l_j(l_i(w_{\sigma(1)}, \ldots, w_{\sigma(i)}), w_{\sigma(i+1)}, \ldots, w_{\sigma(m)}) = 0.
\]

**Remark 5.2.** The zero-th bracket \( l_0 : \mathbb{R} \to W \) has degree 2, and is determined by the element \( l_0(1) \in W_2 \), which we refer to as the “curvature”. Writing \( D := l_1 \), the relations \((34)\) for \( m = 0 \) and \( m = 1 \) read as follows: \( D(l_0(1)) = 0 \), i.e. \( l_0(1) \) is a \( D \)-closed element, and \( D^2(x) + l_2(l_0(1), x) = 0 \) for all \( x \in W \), so \( D \) does not square to zero in general.

**Proposition 5.3.** Let \( \omega \in \Omega^{n+1}(M) \) be a pre-\( n \)-plectic form. Consider the graded vector space whose non-trivial components are

\[
C_i = \begin{cases} 
\langle \omega \rangle & \text{for } i = 2, \\
\Omega^n(M) & \text{for } i = 1, \\
\Omega^{n-1}(M) & \text{for } i = 0, \\
\Omega^{n-1+i}(M) & \text{for } 1 - n \leq i \leq -1,
\end{cases}
\]

where \( \langle \omega \rangle \) denote the one-dimensional real vector space generated by \( \omega \). We define multilinear maps \([\ldots]_k : C^\otimes k \to \Omega^{n+1-k}(M)\) as follows:

- for \( k \geq 0 \) and \( \alpha_1, \ldots, \alpha_k \) of degree zero:
  \[
  [\alpha_1, \ldots, \alpha_k] = \varsigma(k) \epsilon(v_{\alpha_1} \wedge \cdots \wedge v_{\alpha_k})\omega
  \]
- for \( k \geq 2 \) and \( \alpha_1, \ldots, \alpha_k \) of degree zero:
  \[
  [\alpha_1, \ldots, \alpha_i, -\omega, \alpha_{i+1}, \ldots, \alpha_k]_{k+1} = (-1)^i d[\alpha_1, \ldots, \alpha_k]_k,
  \]
where \( d \) denotes the de Rham differential.

Then \( C \), together with the above collection of multibrackets (all other multibrackets are declared to vanish) is a curved \( L_\infty \)-algebra. We denote it \( L^\text{curv}_\infty(M, \omega) \).

**Remark 5.4.** 1) In particular, the “curvature” is \([1]_0 = -\omega \) (where \( 1 \in C^\otimes 0 = \mathbb{R} \)). The differential \( D := [\cdot]_1 \) reads as follows, and gives rise to a chain complex:

\[
C^\infty(M) \xrightarrow{0} \cdots \xrightarrow{0} \Omega^{n-1}(M) \xrightarrow{d} \Omega^n(M) \xrightarrow{0} \langle \omega \rangle.
\]

**Remark 5.5.** Notice that for \( k \geq 1 \), the multibrackets \([\ldots]_k \) vanish, except possibly in two cases: all entries of have degree zero, or all entries of have degree zero except for one, which has degree 2 (hence is a multiple of \(-\omega\)).

**Proof.** For all \( k \geq 0 \), the multibracket \([\ldots]_k \) is graded skew-symmetric and of degree \( 2 - k \).

We need to check that the generalized Jacobi identities \((34)\) are satisfied, for all \( m \geq 0 \). For \( m = 0 \) we have \( D(-\omega) = 0 \) by degree reasons. So in the following we take \( m \geq 1 \) and homogeneous elements \( w_1, \ldots, w_m \in C \). We argue similarly to Rogers’ \cite{Rogers}. Proof of Thm. 5.2. By Rem. 5.3 we can assume that all \( w_i \) have degree zero or 2. Further, since \( C_2 = \langle \omega \rangle \) is one-dimensional and the l.h.s. of eq. \((34)\) is graded skew-symmetric by construction, we may assume that at most one \( w_i \) has degree 2. Hence we just need to consider two cases.

**Case 1:** all \( w_1, \ldots, w_m \) have degree zero.

Let \( \alpha_1, \ldots, \alpha_m \in C \) be elements of degree zero.

For \( m = 1 \) we have \([-\omega, \alpha_1] + D(D(\alpha_1)) = 0 \), since both terms vanish.
For $m = 2$ we have $[-\omega, \alpha_1, \alpha_2] - ([D\alpha_1, \alpha_2] - [D\alpha_2, \alpha_1]) + D[\alpha_1, \alpha_2] = 0$: the first and last term cancel out, while the two middle terms vanish.

Now we assume that $m \geq 3$, and consider the various summands of the sum $\sum_{i+j=m+1}$ on the l.h.s. of eq. (34).

- For $j = 1$ (so $i = m$): the corresponding summand vanishes, since $D[\alpha_1, \ldots, \alpha_m] = 0$, for $D$ vanishes in negative degrees.
- For $j = 2, \ldots, m - 2$ (so $i = m - 1, \ldots, 3$): the corresponding summand vanishes by degree reasons (see Rem. 5.5), since for $i \geq 3$ the bracket $[\ldots]_i$ takes elements of degree zero to elements of negative degree.
- For $j = m$ (so $i = 1$): the corresponding summand vanishes by degree reasons (see Rem. 5.5), since $D$ has degree one.
- For $j = m - 1$ (so $i = 2$): the corresponding summand is

$$
\sum_{\sigma \in S_{2, m-2}} (-1)^{\sigma} e(\sigma) [[\alpha_{\sigma(1)}, \alpha_{\sigma(2)}], \alpha_{\sigma(3)}, \ldots, \alpha_{\sigma(m)}]_{m-1} = -d[\alpha_1, \ldots, \alpha_m].
$$

The above equality is obtained from the computation (30), recalling Remark 1.7.

- For $j = m + 1$ (so $i = 0$): the corresponding summand is

$$
[-\omega, \alpha_1, \ldots, \alpha_m] = d[\alpha_1, \ldots, \alpha_m]
$$

and cancels out with the summand given by $j = m - 1$.

**Case 2: all $w_1, \ldots, w_m$ have degree zero except for one, which has degree 2.**

Fix $m \geq 1$, and let $\alpha_1, \ldots, \alpha_{m-1} \in C$ be elements of degree zero. We consider the various summands of the sum $\sum_{i+j=m+1}$ on the l.h.s. of eq. (34), applied to $\alpha_1, \ldots, \alpha_{m-1}, -\omega$. For $i = 0$, the corresponding summand vanishes, because $-\omega$ appears twice as an entry of the bracket $l_j$.

For all $i \geq 1$,

$$
[[-\omega, \alpha_1, \ldots, \alpha_{i-1}], \alpha_i, \ldots, \alpha_{m-1}]_j = 0.
$$

Indeed, by Remark 5.5, we may assume that the inner bracket has degree zero or 2, and in those cases it reads respectively $[-\omega, \alpha_1, \alpha_2, \alpha_3]_4$ (which is an exact form, so its Hamiltonian vector field vanishes) and $[-\omega, \alpha]_2$ (which vanishes). Further, except in the case $i = 2$,

$$
[[\alpha_1, \ldots, \alpha_i], \alpha_{i+1}, \ldots, \alpha_{m-1}, -\omega]_j = 0
$$

by degree reasons (again by Rem. 5.5).

Hence we need to consider only the summand on the l.h.s. of (34) corresponding to $i = 2$ (so $j = m - 1$, and necessarily $m \geq 2$). It is a sum over unshuffles $S_{2, m-2}$, however due to eq. (36) it reduces to

$$
\sum_{\sigma \in S_{2, m-3}} (-1)^{\sigma} e(\sigma) [[\alpha_{\sigma(1)}, \alpha_{\sigma(2)}], \alpha_{\sigma(3)}, \ldots, \alpha_{\sigma(m-1)}], -\omega]_{m-1}
$$

$$
= \sum_{\sigma \in S_{2, m-3}} (-1)^{\sigma} e(\sigma)(-1)^m d[[\alpha_{\sigma(1)}, \alpha_{\sigma(2)}], \alpha_{\sigma(3)}, \ldots, \alpha_{\sigma(m-1)}]_{m-2}
$$

$$
= - (-1)^m d(d[\alpha_1, \ldots, \alpha_{m-1}]) = 0.
$$

Notice that the second equality is just eq. (35).
In conclusion, a pre-$n$-plectic form $\omega$ on $M$ gives rise to both the $L_\infty$-algebra $L_\infty(M, \omega)$ of Def. 1.5 and the curved $L_\infty$-algebra $L_{\text{curv}}(M, \omega)$ of Prop. 5.3. The underlying graded vector spaces are the same in degrees $\leq 0$, but the one of $L_{\text{curv}}(M, \omega)$ also has components in degrees 1 and 2. Their higher brackets are almost identical, but the underlying chain complexes are very different and certainly not quasi-isomorphic.

**Remark 5.6.** The relation between $L_\infty(M, \omega)$ and $L_{\text{curv}}(M, \omega)$ is not clear at this stage. One can regard both as curved $L_\infty$-algebras, and ask if there is a natural morphism of curved $L_\infty$-algebras (see [6, Def. 6]) between them.

In the simplest case in which $\omega \in \Omega^2(M)$ is a symplectic form, we have that $L_\infty(M, \omega) = C^\infty(M)$ is a Lie algebra while $L_{\text{curv}}(M, \omega) = C^\infty(M) \oplus \Omega^1_{\text{Ham}}(M) \oplus \langle \omega \rangle$ is an $L_\infty$-algebra concentrated in degrees 0, 1, 2. There is no morphism $g: L_\infty(M, \omega) \to L_{\text{curv}}(M, \omega)$: the first condition such morphism would have to fulfill is an equality of certain maps from $\mathbb{R}$ to the degree two component of $L_{\text{curv}}(M, \omega)$, and this condition fails since $\omega \neq 0$. In the opposite direction, there is a strict morphism $f: L_{\text{curv}}(M, \omega) \to L_\infty(M, \omega)$, which is zero except for the restriction of the unary component $f_1$ to degree zero elements, which reads $f_1|_{C^\infty(M)} = \text{Id}_{C^\infty(M)}$. For an arbitrary pre-$n$-plectic form $\omega$, one can check that there exists no strict morphism $f: L_{\text{curv}}(M, \omega) \to L_\infty(M, \omega)$ such that $f_1$ is the identity in degrees $\leq 0$, and we do not know if there is a non-strict one with this property.

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