Lower bounds for the volume with upper bounds for the Ricci Curvature in dimension three

Vicent Gimeno

Abstract

In this note, we provide several lower bounds for the volume of a geodesic ball within the injectivity radius in a 3-dimensional Riemannian manifold assuming only upper bounds for the Ricci curvature.

1. Introduction

One of the central topics in Riemannian geometry is the relation between the curvature of a Riemannian metric defined on a manifold and the behavior of the volume of geodesic balls. Curvature, geodesics and balls have an extremely rich relationship. A celebrated and well-known result states (see, for instance, [2]) that if an \( n \)-dimensional Riemannian manifold \( (M,g) \) has the sectional curvatures \( \text{sec}_M(\Pi) \) of any tangent plane \( \Pi \) bounded from above by a constant \( \kappa \),

\[
\text{sec}_M(\Pi) \leq \kappa,
\]

then, for any point \( p \in M \), the volume \( V(p, t) \) of the geodesic ball of radius \( t \) centered at \( p \) is bounded from below by

\[
V_M(p, t) \geq V_{M^\kappa}(t) \tag{1.1}
\]

for any \( t \leq \min\{\text{inj}(p), \pi/\sqrt{\kappa}\} \), where \( V_{M^\kappa}(t) \) is the volume of the geodesic ball of radius \( t \) in the simply-connected real space form \( M^\kappa \) of dimension \( n \) and constant sectional curvature \( \kappa \). This inequality was obtained by Bishop and Günter and it has associated a rigidity result: if equality is attained in inequality (1.1), the geodesic ball of radius \( t \) in \( M \) centered at \( p \in M \) is isometric to the geodesic ball of radius \( t \) in \( M^\kappa \).

Another classical result authored by Bishop and Gromov, (see [2]) states that whenever the Ricci curvatures are bounded from below by

\[
\text{Ric} \geq (n - 1)\kappa,
\]

the volume of the geodesic ball of radius \( t \) is bounded from above by

\[
V_M(p, t) \leq V_{M^\kappa}(t)
\]

for any \( t > 0 \).

Furthermore, Calabi and Yau (see [11]) proved that for any complete and non-compact Riemannian manifold with

\[
\text{Ric} \geq 0,
\]
there exists a constant $C$ such that the volume of the geodesic ball is bounded from below by

$$V_M(p, t) \geq C t.$$ 

We would like to stress here that, in the above theorems, upper bounds are imposed only on the sectional curvature, and for the Ricci curvature only lower bounds are used. The goal of this paper is to obtain lower bounds for the volume of geodesics balls when the Ricci curvature is bounded from above. This objective is achieved in dimension three. The results of this paper are detailed in the following section.

2. Main results

Our first result is a Bishop–Günter type inequality but using bounds on the Ricci curvature:

**Theorem 2.1.** Let $(M, g)$ be a 3-dimensional Riemannian manifold. Suppose

$$\text{Ric} \leq 2\kappa.$$ 

Then, for any $p \in M$ and for any $t \leq \min\{\text{inj}(p), \pi/\sqrt{\kappa}\}$, the volume $V_M(p, t)$ of the geodesic ball of radius $t$ centered at $p$ is bounded from below by

$$V_M(p, t) \geq V_{M^2}(t),$$

(2.1)

where $V_{M^2}(t)$ is the volume of the geodesic ball of radius $t$ in the simply-connected real space form $M^3_\kappa$ of dimension three and constant sectional curvature $\kappa$.

The hypothesis of the above theorem implies global upper bounds in the Ricci curvature. In the following theorem, we are assuming that the positive upper bound of the Ricci curvature has finite $L_1$-norm in $M$. More precisely, for any point $q \in M$, let us denote by $K^+: M \to \mathbb{R}$ the function

$q \mapsto K^+(q) = \max \{0, \max \{\text{Ric}(v, v) : v \in T_q M \text{ with } \|v\| = 1\} \}$

Under the hypothesis of finite $L_1$-norm of this $K^+$ function, we obtain the following theorem

**Theorem 2.2.** Let $(M, g)$ be a 3-dimensional Riemannian manifold. Suppose

$$\int_M K^+ dV_g = C < \infty.$$ 

Then, for any $p \in M$ and for any $t \leq \text{inj}(p)$, the volume $V_M(p, t)$ of the geodesic ball of radius $t$ centered at $p$ is bounded from below by

$$V_M(p, t) \geq \frac{4}{3} \pi t^3 - Ct^2.$$ 

An immediate consequence of the above theorem is the following corollary when we restrict ourselves to manifolds with pole.

**Corollary 2.3.** Let $(M, g)$ be a 3-dimensional Riemannian manifold with a point $p \in M$ with empty cut locus $\text{Cut}(p) = \emptyset$, suppose

$$\sup_M \text{Ric} < \infty.$$ 

Then $M$ has infinite total volume, that is,

$$\text{vol}(M) = \infty.$$
Remark 1. Observe that in the above Corollary, and in the main results of this paper, the assumption that $M$ contains a point with empty cut locus cannot be removed. Indeed, Lohkamp proved in [8] that each manifold $M^n$, $n \geq 3$, admits a complete metric with negative Ricci curvature and finite volume, $\text{vol}(M) < \infty$.

Remark 2. The Hypothesis of dimension three is used in the proof of Theorem 2.1 (see Section 3) because in such a case the integral of the (intrinsic) scalar curvature of the 2-dimensional geodesic spheres is a topological invariant via the Gauss–Bonnet Theorem. We would like to remark here that the assumption that $M$ has dimension three cannot be removed. For $n > 3$, upper bounds on the Ricci curvature are not enough to state the result. See, for instance, [6] where the ‘$\sqrt{\text{Ric}}$’ curvature is used to obtain Günter type inequalities for any dimension. The Bishop–Gromov theorem cannot be reversed: the statement that if $\text{Ric} \leq (n-1)\kappa$, then $V(p,t) \geq V_{M_2^n}(t)$ is not true for $n > 3$. Consider, for example, the complex hyperbolic space $(\mathbb{C}H^n, g_b)$ of dimension 2 endowed with the metric $g_b$ of constant holomorphic sectional curvature $-4b$. The Ricci tensor and the volume of a geodesic ball of radius $t$ are given by (see, for instance, [5])

$$\text{Ric} = -2b(N+1)g_b, \quad V(t) = \frac{1}{N!} \left(\frac{\pi}{b}\right)^N \left(\sinh(t\sqrt{b})\right)^{2N}.$$

(2.2)

Then there exists a constant $B(N)$ such that

$$V(t) \leq B(N) e^{2N\sqrt{bt}}.$$

But observe that (2.2) is compatible with the bound

$$\text{Ric} \leq (n-1)\kappa, \quad \kappa = -\frac{2b(N+1)}{2N-1},$$

and

$$V_{M_2^n}(t) = \frac{C_n}{\sqrt{-\kappa}} \int_0^t \sinh^{2N-1}(-\kappa s) ds.$$ 

Hence, there exists another constant $C(N)$ such that

$$V_{M_2^n}(t) \geq C(N) e^{\frac{2(N+1)}{2N-1} \sqrt{bt}}, \quad \text{for } t \geq 1.$$ 

Since $\sqrt{2(N+1)} \sqrt{2N-1} > 2N$ for $N > 1$ (dimension $2N > 3$), then there exists $t$ large enough such that

$$V(t) < V_{M_2^n}(t).$$

Remark 3. In some cases, the use of upper bounds for the Ricci curvature is more appropriate than the use of upper bounds for the sectional curvature. There are several examples where the bounds obtained in Theorem 2.1 are better than the bounds obtained when the classical Bishop–Günter inequality is used. Every Berger sphere is one of these examples. Let $SU(2)$ be the special unitary group of $2 \times 2$ matrices,

$$SU(2) := \{ A \in M_{2 \times 2}(\mathbb{C}) : \det(A) = 1, A^\dagger = A^{-1} \}$$

$$= \left\{ \begin{pmatrix} z_1 & z_2 \\ -\overline{z}_2 & \overline{z}_1 \end{pmatrix} : |z_1|^2 + |z_2|^2 = 1 \right\}$$

$$= S^3(1).$$

The Lie algebra $\mathfrak{su}(2)$ is given by

$$\mathfrak{su}(2) = \text{span}_\mathbb{R} \{X_1, X_2, X_3\}$$
with
\[ X_1 := \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}, \quad X_2 := \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad X_3 := \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}. \]

For \(0 < \epsilon < 1\), let \(g_\epsilon\) be the metric such that \(\{X_1, X_2, X_3\}\) is an orthonormal basis, then, (see [10]), the sectional curvatures of any tangent plane \(\pi\) are bounded therefore by \(\text{sec}_M(\pi) \leq 4 - 3\epsilon^2\) and \(\text{Ric} \leq 4 - 2\epsilon^2\).

Since \(0 < \epsilon < 1\), we have \(2 - \epsilon^2 \leq 4 - 3\epsilon^2\) and the bound given by Theorem 2.1,
\[ V_M(p, t) \geq V_{M^3_{2-\epsilon^2}}(t), \quad \text{for} \quad t \leq \min \left\{ \text{inj}(p), \frac{\pi}{\sqrt{2-\epsilon^2}} \right\}, \quad (2.3) \]
is better than the bound given by the classical inequality obtained by using the Bishop–Günter inequality, that is,
\[ V_M(p, t) \geq V_{M^3_{4-3\epsilon^2}}(t), \quad \text{for} \quad t \leq \min \left\{ \text{inj}(p), \frac{\pi}{\sqrt{4-3\epsilon^2}} \right\}. \quad (2.4) \]

**Remark 4.** Croke in [4] proved that for any complete \(n\)-dimensional manifold \((M, g)\) the volume of the geodesic ball of radius \(t\) centered at \(p \in M\) is bounded from below by
\[ V(p, t) \geq \frac{2^{n-1}\omega_n^{n-1}}{n^{n-1}} t^n, \quad \text{for} \quad t \leq \frac{1}{2} \text{inj}(M) \]
with \(\omega_n\) the volume of the unit \(n\)-sphere in \(\mathbb{R}^{n+1}\). In the particular case of dimension three,
\[ V(p, t) \geq \left(\frac{4}{3}\right)^{\frac{3}{\pi}} t^3, \quad \text{for} \quad t \leq \frac{1}{2} \text{inj}(M). \]

By using Theorem 2.1, if \(\text{Ric} \leq 2\kappa\) in the geodesic ball of radius \(t\) centered at \(p\), we can provide the following improvement:
\[ V(p, t) \geq V_{M^3_{2\kappa}}(t) > \left(\frac{4}{3}\right)^{\frac{3}{\pi}} t^3, \quad \text{for} \quad t \leq \min\{\text{inj}(p), \pi/\sqrt{\kappa}\}. \]

In [1], Berger proved that for a compact \(n\)-dimensional manifold \((M, g)\),
\[ \text{vol}(M) \geq \frac{\omega_n}{\pi n} \text{inj}(M)^n. \]

When \(n = 3\), this equation can be rewritten as
\[ \text{vol}(M) \geq \frac{2}{\pi} \text{inj}(M)^3. \quad (2.5) \]

Since \(M\) is compact, there exists a constant \(\kappa\) such that \(\text{Ric}(v, v) \leq \kappa g(v, v)\) for any \(v \in T_p M\) and any \(p \in M\). Then by using Theorem 2.1,
\[ \text{vol}(M) \geq V_{M^3_2}(R), \quad R = \min\{\text{inj}(M), \pi/\sqrt{\kappa}\} \]
hence, when \(\kappa \leq 0\), we can provide the following improvement of (2.5)
\[ \text{vol}(M) \geq \frac{4\pi}{3} \text{inj}(M)^3. \]
3. Proof of the main results

The proof of the main results follows from Proposition 3.3 which is an adaptation of the area variation formula for geodesic balls in dimension three taking into account that the total integral of the scalar curvature in a geodesic sphere is a topological invariant (for 2-dimensional spheres).

Let \((M,g)\) be an \(n\)-dimensional Riemannian manifold, let \(p \in M\) be a point of \(M\) and let \(\text{inj}(p)\) denote the injectivity radius of \(p\). Let \(B_{\text{inj}(p)}(0)\) be the ball of radius \(\text{inj}(p)\) centered at \(0\) in \(T_p M\), let \(B_{\text{inj}(p)}(p) = \exp_p(B_{\text{inj}(p)}(0))\) the geodesic ball of radius \(\text{inj}(p)\) centered at \(p\), then the exponential map

\[
\exp_p : B_{\text{inj}(p)}(0) \rightarrow B_{\text{inj}(p)}(p),
\]

is a diffeomorphism. The radial vector field \(\partial r\) is globally defined on \(B_{\text{inj}(p)}(p) \setminus \{p\}\) and is given by

\[
\partial r : B_{\text{inj}(p)}(p) \setminus \{p\} \rightarrow TM \setminus \{p\}, \quad q \mapsto \partial r(q) = \frac{d}{dt} \exp_p(r(q)\theta(q)t)|_{t=1}.
\]

Namely, \(\partial r(q)\) is the tangent vector to the arc-length parametrized geodesic curve from \(p\) to \(q\).

Let us denote by \(dV_g\) the Riemannian volume form associated to \(g\). The volume \(V_M(p,t)\) of the geodesic ball \(B_t(p)\) of radius \(t\) centered at \(p\) is given by

\[
V_M(p,t) = \int_{B_t(p)} dV_g.
\]

The vector field \(\partial r\) coincides with the gradient \(\nabla r\) of the polar radius function \(r\) on \(B_{\text{inj}(p)}(p) \setminus \{p\}\), that is, \(\partial r = \nabla r\), and furthermore \(|\nabla r| = |\partial r| = 1\). Moreover since the geodesic sphere \(S_t(p)\) of radius \(t\) centered at \(p\) is a level set of \(r\), that is, \(S_t(p) = r^{-1}(t)\) then the vector field \(\nabla r\) is a unit vector field normal and pointed outward to \(S_t(p)\).

The volume \(A_M(p,t)\) of the geodesic sphere \(S_t(p)\) of radius \(t\) centered at \(p\), is given therefore by

\[
A_M(p,t) = \int_{S_t(p)} \nabla r \cdot dV_g,
\]

where \(\nabla r \cdot dV_g\) is the contraction of the Riemannian volume form \(dV_g\) with the vector field \(\nabla r\). In order to simplify the notation, we will make use of

\[
dA_g := \nabla r \cdot dV_g.
\]

Note that for \(0 < t < \text{inj}(p)\), the function

\[
t \mapsto V_M(p,t)
\]

is smooth and with derivative \(A_M(p,t)\). The second fundamental form \(\alpha\) of the inclusion map from \(S_t(p)\) to \(M\) is given in terms of the Hessian \(\text{Hess}_r\) of the geodesic distance function \(r\) to the pole \(p\) because for any two vector fields \(X,Y \in \mathfrak{X}(S_t(p))\)

\[
\alpha(X,Y) = \langle \nabla_X Y, \nabla r \rangle \nabla r = \langle X(\langle Y, \nabla r \rangle) - \langle Y, \nabla_X \nabla r \rangle \rangle \nabla r
\]

\[
\quad = -\langle Y, \nabla_X \nabla r \rangle \nabla r = -\text{Hess}_r(X,Y) \nabla r.
\]

The mean curvature vector field \(\bar{H}\) of \(S_t(p)\) is given therefore in terms of the Laplacian \(\Delta_M r\) of the distance function to \(p\) because for any \(q \in S_t(p)\) and any orthonormal basis \(\{E_i\}_{i=1}^{n-1}\) of \(T_q S_t(p)\)

\[
\bar{H} = \sum_{i=1}^{n-1} \alpha(E_i, E_i) = -\sum_{i=1}^{n-1} \text{Hess}_r(E_i, E_i) \nabla r = -\Delta_M r \nabla r.
\]
The following proposition states the first and second variation formula for the area function $t \mapsto A_M(t)$.

**Proposition 3.1** (See [7, pp. 4 and 8]). Let $(M, g)$ be a Riemannian manifold, suppose $p \in M$ and $t < \text{inj}(p)$. Then:

(i) the first derivative $A'_M(p, t)$ with respect to $t$ of the volume $A_M(p, t)$ of the geodesic sphere $S_t(p)$ of radius $t$ centered at $p$ is given by

$$A'_M(p, t) = \int_{S_t(p)} \Delta_M r \, dA_g = \int_{S_t(p)} \text{Hess}_g \, dA_g;$$

(ii) the second derivative $A''_M(p, t)$ with respect to $t$ of the volume $A_M(p, t)$ of the geodesic sphere $S_t(p)$ of radius $t$ centered at $p$ is given by

$$A''_M(p, t) = \int_{S_t(p)} \left( -\text{Ric}(\nabla r, \nabla r) - \|\text{Hess}_g r\|^2 + (\Delta_M r)^2 \right) \, dA_g.$$

Let us choose now an orthonormal basis $\{E_1, \ldots, E_{n-1}, \nabla r\}$ of $T_pM$ which diagonalizes $\text{Hess}_g r$, that is,

$$\text{Hess}_g r(E_i, E_j) = \begin{cases} \lambda_i & \text{if } i = j \\ 0 & \text{if } i \neq j \end{cases}.$$ 

Then,

$$-\|\text{Hess}_g r\|^2 + (\Delta_M r)^2 = - \sum_{i=1}^{n-1} \lambda_i^2 + \left( \sum_{i=1}^{n-1} \lambda_i \right)^2$$

$$= - \sum_{i=1}^{n-1} \lambda_i^2 + \left( \sum_{i=1}^{n-1} \lambda_i \right) \left( \sum_{j=1}^{n-1} \lambda_j \right)$$

$$= - \sum_{i=1}^{n-1} \lambda_i^2 + \sum_{i,j=1}^{n-1} \lambda_i \lambda_j = \sum_{i \neq j}^{n-1} \lambda_i \lambda_j.$$ 

Taking into account that $\alpha(E_i, E_j) = -\text{Hess}_g r(E_i, E_j) \nabla r$ and using the Gauss formula (see, for instance, [9])

$$-\|\text{Hess}_g r\|^2 + (\Delta_M r)^2 = \sum_{i \neq j}^{n-1} \left( \sec_{S_t(p)}(E_i, E_j) - \sec_\text{inj}(E_i, E_j) \right).$$

Finally, it is easy to check that

$$-\text{Ric}(\nabla r, \nabla r) - \|\text{Hess}_g r\|^2 + (\Delta_M r)^2 = \text{scal}_{S_t(p)} + \text{Ric}(\nabla r, \nabla r) - \text{scal}_M,$$

where $\text{scal}_M$ is the scalar curvature function of $M$, $\text{Ric}(\nabla r, \nabla r)$ is the Ricci tensor evaluated in $\nabla r$, and $\text{scal}_{S_t(p)}$ is the intrinsic scalar curvature of the sphere $S_t(p)$. Then

$$A''_M(p, t) = \int_{S_t(p)} (\text{scal}_{S_t(p)} + \text{Ric}(\nabla r, \nabla r) - \text{scal}_M) \, dA_g. \quad (3.1)$$

When the dimension of $M$ is 3, the geodesic sphere $S_t(p)$ of radius $t$ centered at $p$ has dimension two and the scalar curvature is given in terms of the Gaussian curvature $K_G$,

$$\text{scal}_{S_t(p)} = 2K_G$$
and by the Gauss–Bonnet theorem
\[ \int_{S_t(p)} \text{scal}_{S_t(p)} dA_g = 2 \int_{S_t(p)} K_g dA_g = 4\pi \chi(S_t(p)) = 8\pi, \]
therefore we can state the following corollary to Proposition 3.1.

**Corollary 3.2.** Let \((M, g)\) be a 3-dimensional Riemannian manifold, let \(p \in M\) be a point of \(M\). Then for any \(0 < t < \text{inj}(p)\), the second derivative \(A_M''(p, t)\) with respect to \(t\) of the volume \(A_M(p, t)\) of the geodesic sphere \(S_t(p)\) of radius \(t\) centered at \(p\) is given by
\[ A_M''(p, t) = 8\pi - \int_{S_t(p)} (\text{scal}_M - \text{Ric}(\nabla r, \nabla r)) dA_g, \]
where \(\text{scal}_M\) is the scalar curvature function of \(M\), and \(\text{Ric}(\nabla r, \nabla r)\) is the Ricci tensor evaluated in \(\nabla r\).

Since \(V_M(p, t) = A_M(p, t)\),
\[ V_M''(p, s)|_{s=t} - V_M''(p, t_0) = \int_{t_0}^{t} A_M''(p, s) ds \]
Therefore using the above corollary,
\[ V_M''(p, t) - \int_{S_{t_0}(p)} HdA_g = 8\pi(t - t_0) \]
\[ - \int_{t_0}^{t} \int_{S_{s}(p)} (\text{scal}_M - \text{Ric}(\nabla r, \nabla r)) dA_g ds. \quad (3.2) \]
Taking the limit \(t_0 \to 0\), we obtain the following

**Proposition 3.3.** Let \((M, g)\) be a 3-dimensional Riemannian manifold, let \(p \in M\) be a point of \(M\). Then for any \(0 < t < \text{inj}(p)\)
\[ \int_{B_t(p)} (\text{scal}_M - \text{Ric}(\nabla r, \nabla r)) dV_g + V_M''(p, t) = 8\pi t. \]

**Proof.** the Proposition follows taking the limit \(t_0 \to 0\) in equation (3.2) because in dimension three
\[ \lim_{t_0 \to 0} \int_{S_{t_0}(p)} HdA_g = \lim_{t_0 \to 0} \int_{S_{t_0}(p)} \Delta_M r dA_g = 0. \]
Indeed, in, for example, [3], it is proved that
\[ H(p) = \frac{n - 1}{t} + O(t), \quad A_M(p, t) = C_n - 1 t^{n-1} + O(t^{n+1}), \quad \text{as} \quad t \to 0. \quad \square \]

**Corollary 3.4.** Let \(\mathbb{M}_\kappa^3\) be the 3-dimensional simply-connected real space form of constant sectional curvature \(\kappa\), then
\[ 4\kappa V_{\mathbb{M}_\kappa^3}(t) + V_{\mathbb{M}_\kappa^3}''(t) = 8\pi t. \]

From Proposition 3.3, we can prove the main results of the paper.

### 3.1. Proof of Theorem 2.1
The statement and proof of Theorem 2.1 is as follows.
THEOREM. Let \((M, g)\) be a 3-dimensional Riemannian manifold. Suppose 
\[
\text{Ric} \leq 2\kappa.
\]
Then, for any \(p \in M\) and for any \(t \leq \min\{\inj(p), \pi/\sqrt{\kappa}\}\), the volume \(V_M(p, t)\) of the geodesic ball of radius \(t\) centered at \(p\) is bounded from below by 
\[
V_M(p, t) \geq V_{M_2^3}(t), \tag{3.3}
\]
where \(V_{M_2^3}(t)\) is the volume of the geodesic ball of radius \(t\) in the simply-connected real space form \(\mathbb{M}^3_\kappa\) of dimension 3 and constant sectional curvature \(\kappa\).

Proof. Let \(\{\nabla r, E_1, E_2\}\) be an orthonormal basis of \(T_q M\). Since \(\text{Ric} \leq 2\kappa\), 
\[
\text{scal}_M - \text{Ric}(\nabla r, \nabla r) = \text{Ric}(E_1, E_1) + \text{Ric}(E_2, E_2) \leq 4\kappa
\]
By using Proposition 3.3 and Corollary 3.4,
\[
4\kappa V_M(p, t) + V_M'(p, t) \geq \int_{B_1(p)} (\text{scal}_M - \text{Ric}(\nabla r, \nabla r))dV_g + V_M''(p, t) \tag{3.4}
\]
\[
= 8\pi t = 4\kappa V_{M_2^3}(t) + V_{M_2^3}'(t).
\]
Let us denote by \(Z(t) := V_M(p, t) - V_{M_2^3}(t)\), and by 
\[
\text{sn}_\kappa(t) := \begin{cases} 
\sinh(\sqrt{-\kappa}t) & \text{if } \kappa < 0 \\
t & \text{if } \kappa = 0 \\
\sin(\sqrt{\kappa}t) & \text{if } \kappa > 0,
\end{cases}
\]
inequality (3.4) can be rewritten as 
\[
Z''(t) \geq -4\kappa Z(t) = \frac{\text{sn}_4\kappa(t)}{\text{sn}_4\kappa(t)} Z(t),
\]
which implies 
\[
\frac{d}{dt}(Z(t)\text{sn}_4\kappa(t) - Z(t)\text{sn}_4'(t)) \geq 0.
\]
Since \(Z(t)\text{sn}_4\kappa(t) - Z(t)\text{sn}_4'(t)\) is a non-decreasing function, 
\[
Z'(t)\text{sn}_4\kappa(t) - Z(t)\text{sn}_4'(t) \geq \lim_{t \to 0} (Z'(t)\text{sn}_4\kappa(t) - Z(t)\text{sn}_4'(t)) = 0.
\]
Therefore 
\[
\frac{d}{dt} \left( \frac{Z(t)}{\text{sn}_4\kappa(t)} \right) \geq 0
\]
then, taking into account that \(V_{M_2^3}(t) \sim Ct^3 + O(t^4)\), \(V_M(p, t) \sim Ct^3 + O(t^4)\), and \(\text{sn}_4\kappa(t) \sim t + O(t^3)\) when \(t\) tend to zero, 
\[
\frac{Z(t)}{\text{sn}_4\kappa(t)} \geq \lim_{t \to 0} \left( \frac{Z(t)}{\text{sn}_4\kappa(t)} \right) = \lim_{t \to 0} \left( \frac{V_M(p, t)}{\text{sn}_4\kappa(t)} - \frac{V_{M_2^3}(t)}{\text{sn}_4\kappa(t)} \right) = 0.
\]
Therefore 
\[
Z(t) \geq 0 \implies V_M(p, t) \geq V_{M_2^3}(t).
\]

3.2. Proof of Theorem 2.2

The statement and proof of Theorem 2.2 is as follows.
THEOREM. Let $(M, g)$ be a 3-dimensional Riemannian manifold. Suppose
\[ \int_M K_+ dV_g = C < \infty. \]
Then, for any $p \in M$ and for any $t \leq \text{inj}(p)$, the volume $V_M(p, t)$ of the geodesic ball of radius $t$ centered at $p$ is bounded from below by
\[ V_M(p, t) \geq \frac{4}{3} \pi t^3 - Ct^2. \]

Proof. Let $\{\nabla r, E_1, E_2\}$ be an orthonormal basis of $T_q M$. Since $\text{Ric} \leq K_+$,
\[ \text{scal}_M - \text{Ric}(\nabla r, \nabla r) = \text{Ric}(E_1, E_1) + \text{Ric}(E_2, E_2) \leq 2K_+(q). \]
By using Proposition 3.3,
\[
V''_M(p, t) = 8\pi t - \int_{B_t(p)} (\text{scal}_M - \text{Ric}(\nabla r, \nabla r)) dV_g
\geq 8\pi t - 2 \int_M K_+ dV_g = 8\pi t - 2C
\]
and the theorem follows integrating twice and taking into account that $V_M(p, 0) = V'_M(p, 0) = 0$,
\[ V_M(p, t) \geq \frac{4}{3} \pi t^3 - Ct^2. \]
\[ \square \]

References
1. M. BERGER, ‘Une borne inférieure pour le volume d’une variété riemannienne en fonction du rayon d’injectivité’, Ann. Inst. Fourier (Grenoble) 30 (1980) 259–265.
2. I. CHAVEL, Riemannian geometry—a modern introduction, Cambridge Tracts in Mathematics 108 (Cambridge University Press, Cambridge, 1993).
3. B.-Y. CHEN and L. VANHECKE, ‘Differential geometry of geodesic spheres’, J. reine angew. Math. 325 (1981) 28–67.
4. C. B. CROKE, ‘Some isoperimetric inequalities and eigenvalue estimates’, Ann. Sci. Éc. Norm. Supér. (4) 13 (1980) 419–435.
5. A. GRAY, Tubes, 2nd edn, Progress in Mathematics 221 (Birkhäuser, Basel, 2004). (With a preface by Vicente Miquel.)
6. B. R. KLOECKER and G- KUPERBERG, ‘A refinement of Günther’s candle inequality’, Asian J. Math. 19 (2015) 121–134.
7. P. LI, Geometric analysis, Cambridge Studies in Advanced Mathematics 134 (Cambridge University Press, Cambridge, 2012).
8. J. LOHKAU, ‘Metrics of negative Ricci curvature’, Ann. of Math. (2) 140 (1994) 655–683.
9. B. O’NEILL, Semi-Riemannian geometry with applications to relativity, Pure and Applied Mathematics 103 (Academic Press Inc. [Harcourt Brace Jovanovich Publishers], New York, NY, 1983).
10. P. PETERSEN, Riemannian geometry, Graduate Texts in Mathematics 171 (Springer, New York, NY, 1998).
11. S.-T. YAU, ‘Some function-theoretic properties of complete riemannian manifold and their applications to geometry’, Indiana Univ. Math. J. 25 (1976) 659–670.
Vicent Gimeno  
Department of Mathematics  
Universitat Jaume I-IMAC  
Castelló E-12071  
Spain  
gimenov@mat.uji.es