Ward Identities for Scale and Special Conformal Transformations in Inflation

Nilay Kundu,1 Ashish Shukla,2 and Sandip P. Trivedi2

1Harish-Chandra Research Institute, Chhatnag Road, Jhunsi, Allahabad, 211019, India
2Department of Theoretical Physics, Tata Institute of Fundamental Research, Colaba, Mumbai, 400005, India

E-mail: nilay.tifr@gmail.com, ashukla.phy@gmail.com, trivedi.sp@gmail.com

ABSTRACT: We derive the general Ward identities for scale and special conformal transformations in theories of single field inflation. Our analysis is model independent and based on symmetry considerations alone. The identities we obtain are valid to all orders in the slow roll expansion. For special conformal transformations, the Ward identities include a term which is non-linear in the fields that arises due to a compensating spatial reparametrization. Some observational consequences are also discussed.

KEYWORDS: de Sitter space, Slow roll model, Conformal symmetry, Scale and Special conformal transformations, Higher derivative terms.
1 Introduction

Inflation is the dominant paradigm to explain the approximate isotropy and homogeneity of the universe. It also gives rise to quantum perturbations which lead to the observed anisotropy in the Cosmic Microwave Background, and which seed the formation of large scale structure in the universe. During inflation, space-time is well approximated by four dimensional de Sitter space, which is a maximally symmetric FRW cosmology, with the symmetry group $SO(1,4)$. The time evolution of the inflaton and its back-reaction on the
metric breaks these symmetries, but this breaking is small if the slow roll conditions are satisfied.

We will refer to the $SO(1, 4)$ symmetry of de Sitter space as the conformal symmetry group. It includes translations and rotations along the spatial directions, as well as a scale transformation, and three special conformal transformations. In this paper, we explore the constraints imposed by these $SO(1, 4)$ symmetries on the perturbations produced during inflation. More specifically, we derive Ward identities arising due to the scale and special conformal transformations for the correlation functions of these perturbations. Our Ward identities incorporate the breaking of the $SO(1, 4)$ symmetry as well, and are valid to all orders in the slow roll parameters.

The analysis we carry out is based on symmetries alone, and is independent of specific models. As a result, the Ward identities we obtain can provide robust model independent checks of the central idea behind a large class of inflationary models, namely, that the inflationary dynamics (including the scalar sector) preserves approximate conformal invariance. These results should apply not only to slow roll models with different shapes of the inflationary potential, but also in situations where higher derivative corrections can become important, such as in string theory scenarios, with the Hubble scale during inflation being of order the string scale, which in turn is much smaller than the Planck scale.

The $SO(1, 4)$ symmetry is also the symmetry group of a 3-dimensional Euclidean conformal field theory, which is the motivation behind our calling it the conformal group. However, we should mention at the outset that we do not assume a dS/CFT type of correspondence in deriving our results. Rather the connection with a conformal field theory (with the breaking of conformal invariance also included) is only for the purpose of organizing our discussion of the symmetries.

This paper is organized as follows. Section 2 contains the basic setup. The central ideas and key results behind the derivation of the Ward identities are then discussed in section 3. For our analysis, it is useful to work with the late time wave function of the universe, when the modes of interest have exited the horizon. Constraints imposed by symmetries on the coefficient functions determining the wave function are discussed in section 4. The late time behaviour of the modes in the canonical slow roll model of inflation is discussed in subsection 6.1, and some aspects which arise when higher derivative corrections are incorporated are discussed in subsection 6.2. We end with conclusions in section 7. The three appendices contain important supplementary material.

The analysis we carry out is based on the seminal works [1] and [2]. It also develops ideas earlier reported in [3], [4] and [5]. There are many other references also of relevance. The use of conformal symmetry to constrain inflationary correlation functions has also been discussed in [6–19]. Approaches where the conformal symmetries are often thought of as being non-linearly realized include [20–39]. The idea of using time and spatial reparametrizations to derive Ward identities in the context of AdS was first discussed in [40].

**Notation:** Before proceeding, let us clarify the notation we will follow in this paper. A dot above a quantity represents a time derivative, e.g. $\dot{\phi} \equiv d\phi/dt$. Spatial three vectors are written in boldface, e.g. $\mathbf{x}, \mathbf{k}$, etc. Also, $k_a, k_b$, etc. represent the magnitudes of the vectors $\mathbf{k}_a, \mathbf{k}_b$, whereas $k_i, k_j$, etc. represent the $i^{th}, j^{th}$ components of $\mathbf{k}$. Unless otherwise
stated, the spatial indices $i, j$, etc. will be raised and lowered using the Kronecker delta, $\delta_{ij}$.

2 Essential Ideas

In this section, we will outline the essential ideas behind the derivation of the Ward identities. Our discussion will be general and not tied to any specific model. In sections 6.1 and 6.2, we will discuss the concrete cases of the canonical model of slow roll inflation, and the presence of higher derivatives, respectively.

The dynamical degrees of freedom in the theories we consider will be the metric and a single scalar field $\phi$. We work with the ADM form of the metric,

$$ds^2 = -N^2 dt^2 + h_{ij} (dx^i + N^i dt)(dx^j + N^j dt),$$  \hspace{1cm} (2.1)

with $N$ and $N^i$ being the lapse and shift functions respectively. We choose the gauge

$$N = 1, N^i = 0.$$  \hspace{1cm} (2.2)

This gauge is called the synchronous gauge.

The unperturbed background FRW solution is

$$ds^2 = -dt^2 + a^2(t) \delta_{ij} dx^i dx^j.$$  \hspace{1cm} (2.3)

The Hubble parameter is given by

$$H = \frac{\dot{a}}{a}.$$  \hspace{1cm} (2.4)

Including the metric perturbations, denoted by $\gamma_{ij}$, gives

$$h_{ij} = a^2(t) [\delta_{ij} + \gamma_{ij}].$$  \hspace{1cm} (2.5)

Similarly, expanding the inflaton about the background value $\bar{\phi}(t)$ gives

$$\phi = \bar{\phi}(t) + \delta \phi.$$  \hspace{1cm} (2.6)

The gauge choice, eq.(2.2), does not fix all the coordinate reparametrization invariance. There are two kinds of residual gauge transformations which can be carried out. These are spatial reparametrizations,

$$x^i \rightarrow x^i + v^i(x),$$  \hspace{1cm} (2.7)

under which

$$h_{ij} \rightarrow h_{ij} + \nabla_i v_j + \nabla_j v_i,$$  \hspace{1cm} (2.8)

or equivalently

$$\gamma_{ij} \rightarrow \gamma_{ij} + \frac{1}{a^2(t)} (\nabla_i v_j + \nabla_j v_i).$$  \hspace{1cm} (2.9)

1The discussion can be extended to include additional scalars. However, model independent observational predictions are not easy to make in such models.
We can also perform time reparametrizations

$$t \rightarrow t + \epsilon(x), \quad (2.10)$$

along with accompanying spatial reparametrizations of the form

$$x^i \rightarrow x^i + w^i(t, x) \quad (2.11)$$

with

$$w^i(t, x) = \partial_i \epsilon(x) \int^t dt' \frac{1}{a^2(t')}, \quad (2.12)$$

under which

$$\delta \phi \rightarrow \delta \phi + \dot{\phi}(t) \epsilon(x), \quad (2.13)$$

$$\gamma_{ij} \rightarrow \gamma_{ij} + 2 \delta \left( \frac{\dot{a}}{a} \right) \epsilon(x) + \left( \partial_i w_j + \partial_j w_i \right). \quad (2.14)$$

Using the homogeneity of the background FRW solution, we can expand the perturbations in a basis of modes carrying fixed comoving momenta. Let $\xi$ be a generic perturbation. Then

$$\xi(t, x) = \int \frac{d^3k}{(2\pi)^3} e^{i k \cdot x} \xi(t, k), \quad (2.15)$$

where the comoving momentum is $k$. We will be interested in the behaviour of the perturbations at late times, when the modes of interest have left the horizon,

$$k^2/a_2 \ll H^2. \quad (2.16)$$

Using the time reparametrization symmetry at late times, we can set

$$\delta \phi = 0. \quad (2.17)$$

In this gauge, the perturbations freeze out once they exit the horizon, i.e., they become time independent, since their subsequent evolution becomes dominated by a frictional term proportional to the Hubble parameter. The remaining gauge invariance now corresponds to spatial reparametrizations, eq.\((2.7)\). The choice of gauge eq.\((2.17)\), and the freeze out of modes will be discussed in greater detail for the canonical slow roll model in section 6.1, and in the presence of higher derivative terms in section 6.2.

In the gauge eq.\((2.17)\), all the remaining perturbations arise from the metric. We can decompose them as

$$\delta_{ij} + \gamma_{ij} = e^{2\zeta}[\delta_{ij} + \hat{\gamma}_{ij}], \quad (2.18)$$

where $\hat{\gamma}_{ij}$ is the traceless component. $\zeta$ determines the perturbations in the trace of the metric. To linear order in perturbations, we see from eq.\((2.18)\) that

$$\gamma_{ij} = 2\zeta \delta_{ij} + \hat{\gamma}_{ij}. \quad (2.19)$$

Going beyond the linear order, we will find that the definition given in eq.\((2.18)\) leads...
to a simplification in our discussion of symmetries. To be more specific, it will turn out
that the coefficient functions for the trace of the stress tensor will transform in a canonical
way with this choice of variables.

It will be useful to carry out our symmetry based analysis in terms of the wave function
of the universe. This wave function is actually a functional of the perturbations. Expanding
at late times, when the perturbations become time independent, we get

$$
\Psi[\gamma_{ij}] = \exp \left[ -\frac{1}{2} \int d^3 x d^3 y \zeta(x) \zeta(y) \langle T(x)T(y) \rangle 
- \int d^3 x d^3 y \zeta(x) \tilde{\gamma}_{ij}(y) \langle T(x)\tilde{T}^{ij}(y) \rangle 
- \frac{1}{2} \int d^3 x d^3 y d^3 z \zeta(x) \zeta(y) \zeta(z) \langle T(x)T(y)T(z) \rangle 
- \frac{1}{2} \int d^3 x d^3 y d^3 z \zeta(x) \tilde{\gamma}_{ij}(y) \zeta(z) \zeta(z) \langle T(x)\tilde{T}^{ij}(y) \tilde{T}^{kl}(z) \rangle 
- \frac{1}{2} \int d^3 x d^3 y d^3 z \zeta(x) \tilde{\gamma}_{ij}(y) \gamma_{kl}(z) \langle T(x)\tilde{T}^{ij}(y)\tilde{T}^{kl}(z) \rangle 
- \frac{1}{2} \int d^3 x d^3 y d^3 z \tilde{\gamma}_{ij}(x) \tilde{\gamma}_{kl}(y) \gamma_{mn}(z) \langle \tilde{T}^{ij}(x)\tilde{T}^{kl}(y)\tilde{T}^{mn}(z) \rangle 
+ \ldots \right].
$$

(2.20)

The quadratic terms in $\zeta$ and $\tilde{\gamma}_{ij}$ correspond to a Gaussian wave function; higher order
terms give rise to non-Gaussianity.

Invariance with respect to the residual gauge invariance, namely with respect to the spatial
reparametrization eq.(2.7), imposes constraints on the coefficient functions $\langle T(x)T(y) \rangle$, 
$\langle \tilde{T}^{ij}(x)\hat{T}^{kl}(y) \rangle$ etc, which appear in this expansion. In fact, these coefficient functions have
been written in a suggestive manner because the constraints take the form of Ward identities
which are satisfied by correlation functions of the stress-energy tensor in a conformal
field theory. This will be discussed further in section 4. Note that in eq.(2.20) we have also
included a mixed term between $\zeta$ and $\tilde{\gamma}_{ij}$ for generality, although such a term will vanish on
further gauge fixing the spatial reparametrization invariance suitably, as we will see later.
Let us also mention that as per our conventions, eq(2.19), $T$ is related to the trace of the
stress tensor $T_{ij}$ by

$$
T = 2T_{ii} \equiv 2\mathcal{T},
$$

(2.21)

so that the coefficient function for a general metric perturbation, $\gamma_{ij}$, is $T^{ij}$. Also, $\hat{T}_{ij}$ is
the traceless part of the stress-energy tensor $T_{ij}$.

The invariance with respect to spatial reparametrizations eq.(2.7) arises as follows.
The wave function as a functional of the late time value for a generic perturbation $\xi$ can
be written as a path integral
\[ \Psi[\xi] = \int_{\text{initial}}^{\xi} [\mathcal{D}\xi] e^{iS}, \]  
(2.22)
where the initial conditions will be taken to be the Bunch-Davies vacuum. The action \( S \) has a pre-factor \( 1/G \sim M_{Pl}^2 \). By suitably rescaling fields in terms of the Hubble parameter \( H \), we see that
\[ S = \frac{M_{Pl}^2}{H^2} \tilde{S}, \]  
(2.23)
where \( \tilde{S} \) contains the rescaled fields which have been made dimensionless by the rescaling.

Since no gravity waves have been detected so far, we know that \(^2\)
\[ \frac{H^2}{M_{Pl}^2} \leq 10^{-8}. \]  
(2.24)
Thus the path integral on the RHS of eq.(2.22) can be evaluated in the semi-classical limit, by solving the equations of motion subject to the boundary conditions at late and early times. In particular, in the gauge eq.(2.2), the \( N, N^i \) equations must also be imposed. These equations give rise to the invariance of the wave function under spatial reparametrizations, eq.(2.7), after fixing the gauge, eq.(2.17), at late times.

3 Ward Identities

We are now ready to discuss the derivation of the Ward identities. We will be interested in the Ward identities which arise due to scale and special conformal transformations. It is useful to first consider the case of de Sitter space, with the background metric
\[ ds^2 = -dt^2 + e^{2Ht} \delta_{ij} dx^i dx^j. \]  
(3.1)
This metric is well known to have an \( SO(1,4) \) symmetry with ten generators. Besides the three spatial translations, and three rotations along the spatial directions, this symmetry group includes scale transformations,
\[ x^i \rightarrow \lambda x^i, \quad t \rightarrow t - \frac{1}{H} \log(\lambda), \]  
(3.2)
and three special conformal transformations,
\[ x^i \rightarrow x^i - 2(b_j x^j)x^i + b^j \left( \sum_j (x^j)^2 - \frac{1}{H^2} e^{-2Ht} \right), \]  
\[ t \rightarrow t + \frac{2b_j x^j}{H}. \]  
(3.3)

The scale and special conformal symmetries give rise to Ward identities on the correlation functions of the perturbations. In de Sitter space these identities are met exactly;

\(^2\)We take \( M_{Pl} = \frac{1}{\sqrt{8\pi G}} \approx 10^{18}\text{GeV}. \)
in inflationary backgrounds, there are corrections that arise due to the evolving inflaton which breaks these symmetries. We will derive the resulting identities for the correlation functions to all orders in the slow roll parameters

\[ \epsilon_1 = -\frac{\dot{H}}{H^2}, \quad (3.4) \]

\[ \delta = \frac{\dot{H}}{2H} , \quad (3.5) \]

and

\[ \epsilon = \frac{1}{2} \frac{\ddot{\phi}^2}{H^2} , \quad (3.6) \]

The identities for the scale transformations are the analogues of the Callan-Symanzik equations in field theory, which incorporate the running of the coupling constants. Similarly, we get identities for the special conformal transformations also incorporating the evolving inflaton.

Before proceeding, let us note that in the canonical slow roll model, discussed in section 6.1, \( \epsilon \) and \( \epsilon_1 \) are related as

\[ \epsilon = \epsilon_1 . \quad (3.7) \]

But more generally, when higher derivatives are included, they will not be related in this way. Also, for the slow roll conditions to hold,

\[ \epsilon_1, \delta, \epsilon \ll 1. \quad (3.8) \]

The expectation values for the perturbations are obtained from the wave function in the standard manner. For example, for scalar perturbations \( \zeta \) these are given by

\[ \langle \zeta(x_1) \cdots \zeta(x_n) \rangle = \frac{1}{\mathcal{N}} \int [D\zeta] [D\hat{\gamma}_{ij}] |\Psi|^2 \zeta(x_1) \cdots \zeta(x_n) , \quad (3.9) \]

where \( \mathcal{N} \) denotes the overall normalization factor in the path integral,

\[ \mathcal{N} = \int [D\zeta] [D\hat{\gamma}_{ij}] |\Psi|^2 . \quad (3.10) \]

We will be interested in calculating these expectation values at late times, when the perturbations of interest have frozen out.

There is one important point which we must consider before we proceed. The sum over all metric perturbations \( \hat{\gamma}_{ij} \) on the RHS of eq.(3.9) is ill defined because we have not yet fixed the spatial reparametrization invariance symmetry. The integral on the RHS would diverge without fixing this symmetry. A conventional choice, which we will also make, is to take \( \hat{\gamma}_{ij} \) to be transverse,

\[ \partial_i \hat{\gamma}_{ij} = 0 , \quad (3.11) \]

besides also being traceless. With this further gauge fixing, the path integral on the RHS of eq.(3.9) becomes finite. Note that since \( \hat{\gamma}_{ij} \) freezes out at late times, the additional gauge
fixing required for eq. (3.11) can be achieved by a spatial reparametrization $x^i \rightarrow x^i + \epsilon^i(x)$ which preserves the synchronous gauge eq. (2.2).

Also note that after the additional gauge fixing, eq. (3.11), the resulting perturbations manifestly correspond to a scalar $\zeta$ with spin 0, and a tensor perturbation $\hat{\gamma}_{ij}$ which has spin 2, with respect to the rotations along the spatial directions.

It is worth commenting here that the underlying reason for this further gauge fixing is that we are working with local correlation functions in a theory of quantum gravity. These correlations are well defined perturbatively about the inflationary background, but only after gauge fixing, as discussed above.

### 3.1 Ward Identities for Scale Transformations

Under a scale transformation

$$x^i \rightarrow x^i + \lambda x^i, \lambda \ll 1,$$  

(3.12)

$\zeta$ and $\hat{\gamma}_{ij}$ transform as

$$\zeta \rightarrow \zeta + \lambda + \lambda x^i \partial_i \zeta,$$  

(3.13)

$$\hat{\gamma}_{ij} \rightarrow \hat{\gamma}_{ij} + \lambda x^k \partial_k \hat{\gamma}_{ij}$$  

(3.14)

(see appendix A). Note that the transversality condition, eq.(3.11), is preserved by this transformation.

We can now consider changing variables in the path integral on the RHS of eq.(3.9), with $\zeta$ and $\hat{\gamma}_{ij}$ transforming as given in eq.(3.13) and eq.(3.14), respectively. The measure in the path integral on the RHS of eq.(3.9) is invariant under spatial reparametrizations, and therefore under the change in eq.(3.12).

Naively, on the basis of what has been discussed so far, one might also conclude that the wave function $\Psi$ is invariant under this transformation, leading to the condition

$$\langle \delta(\zeta(x_1)) \cdots \zeta(x_n) \rangle + \cdots + \langle \zeta(x_1) \cdots \delta(\zeta(x_n)) \rangle = 0,$$  

(3.15)

where from eq.(3.13),

$$\delta \zeta = \lambda + \lambda x^i \partial_i \zeta.$$  

(3.16)

This is incorrect.

Under the transformation eq.(3.12), $\hat{\gamma}_{ij}$ transforms homogeneously, but $\zeta$ has a homogeneous and an inhomogeneous term in its transformation. The relations between the coefficient functions we obtain, as discussed in section 4, will ensure that terms in the wave function which are quadratic or higher order in the perturbations cancel amongst each other under this transformation. However, there is one term which arises from the leading term that is quadratic in $\zeta$ in eq.(2.20), to begin with, which needs to be handled with care and does not cancel, as is also discussed at the end of section 4.2. The quadratic terms in the wave function include

$$\Psi \sim \exp \left( -\frac{1}{2} \int d^3x d^3y \zeta(x) \zeta(y) \langle T(x) T(y) \rangle \right).$$  

(3.17)
After the transformation eq. (3.13), we get a piece arising from the inhomogeneous term in the transformation of $\zeta$,

$$
\zeta \rightarrow \zeta + \lambda + \cdots,
$$

(3.18)

which will now be linear in $\zeta$,

$$
\delta \Psi \sim \exp \left( -\lambda \int d^3x \, d^3y \, \zeta(x) \langle T(x)T(y) \rangle \right).
$$

(3.19)

This term will remain uncanceled. In contrast, the homogeneous term in the transformation of $\zeta$,

$$
\zeta \rightarrow \zeta + \lambda x^i \partial_i \zeta + \cdots
$$

(3.20)

will give rise to a term which is quadratic in $\zeta$; this will cancel against a term coming from the piece of $\Psi$ cubic in $\zeta$.

Before proceeding, let us note that in eq. (2.20) there is another quadratic term,

$$
\Psi \sim \exp \left( -\int d^3x \, d^3y \, \zeta(x) \hat{\gamma}_{ij}(y) \langle \hat{T}^i(x)\hat{T}^j(y) \rangle \right),
$$

(3.21)

involving both $\zeta$ and $\hat{\gamma}_{ij}$, which could also have potentially contributed an additional piece. However, in the gauge eq. (3.11), this term in the wave function vanishes. This follows after noting that symmetries require the momentum space coefficient function $\langle \hat{T}^i(k_1)\hat{T}^j(k_2) \rangle$ to be of the form

$$
\langle \hat{T}^i(k_1)\hat{T}^j(k_2) \rangle \sim (2\pi)^3 \delta^3(k_1 + k_2) \left( \frac{1}{3} \delta_{ij} - \frac{k_{1i}k_{1j}}{k_1^2} \right) \beta(k_1),
$$

(3.22)

where $\beta(k_1)$ is a dimension 3 function of $k_1$.

Keeping this uncanceled linear term, eq. (3.19), gives us then the correct Ward identity

$$
\langle \delta(\zeta(x_1)) \cdots \zeta(x_n) \rangle + \cdots + \langle \zeta(x_1) \cdots \delta(\zeta(x_n)) \rangle = 2\lambda \int d^3x \, d^3y \, \langle T(x)T(y) \rangle \langle \zeta(x_1) \cdots \zeta(x_n) \zeta(x) \rangle.
$$

(3.23)

We will be interested in the expectation values for $\zeta$ with non-zero momentum. Since $\lambda$ is a constant, we can drop the piece linear in $\lambda$ on the LHS of eq. (3.23), leading to the Ward identity

$$
\left( \sum_{a=1}^n \partial_{x_a} \right) \langle \zeta(x_1) \cdots \zeta(x_n) \rangle = 2 \int d^3x \, d^3y \, \langle T(x)T(y) \rangle \langle \zeta(x_1) \cdots \zeta(x_n) \zeta(x) \rangle.
$$

(3.24)
Expressing this in momentum space gives 3
\[
\left(3(n-1) + \sum_{a=1}^{n} k_a \frac{\partial}{\partial k_a}\right) \langle \zeta(k_1) \cdots \zeta(k_n) \rangle' = \]
\[= - \frac{1}{\langle \zeta(k_{n+1}) \zeta(-k_{n+1}) \rangle'} \langle \zeta(k_1) \cdots \zeta(k_{n+1}) \rangle' \bigg|_{k_{n+1} \to 0}. \tag{3.25}
\]
Similarly, for correlation functions of tensor perturbations \(\hat{\gamma}_{ij}\) we get
\[
\left(\sum_{a=1}^{n} x_a \frac{\partial}{\partial x_a}\right) \langle \hat{\gamma}_{ij_1}(x_1) \cdots \hat{\gamma}_{ij_n}(x_n) \rangle = \]
\[= 2 \int d^3x d^3y \langle T(x)T(y) \rangle \langle \hat{\gamma}_{ij_1}(x_1) \cdots \hat{\gamma}_{ij_n}(x_n) \zeta(x) \rangle, \tag{3.26}
\]
which in momentum space takes the form
\[
\left(3(n-1) + \sum_{a=1}^{n} k_a \frac{\partial}{\partial k_a}\right) \langle \hat{\gamma}_{ij_1}(k_1) \cdots \hat{\gamma}_{ij_n}(k_n) \rangle' = \]
\[= - \frac{1}{\langle \zeta(k_{n+1}) \zeta(-k_{n+1}) \rangle'} \langle \hat{\gamma}_{ij_1}(k_1) \cdots \hat{\gamma}_{ij_n}(k_n) \zeta(k_{n+1}) \rangle' \bigg|_{k_{n+1} \to 0}. \tag{3.27}
\]
Mixed identities involving both tensor and scalar perturbations can also be similarly obtained. These are given by
\[
\left(3(n-1) + \sum_{a=1}^{n} k_a \frac{\partial}{\partial k_a}\right) \langle \hat{\gamma}_{ij_1}(k_1) \cdots \hat{\gamma}_{im_j}(k_m) \zeta(k_{m+1}) \cdots \zeta(k_{n+1}) \rangle' = \]
\[= - \frac{1}{\langle \zeta(k_{n+1}) \zeta(-k_{n+1}) \rangle'} \langle \hat{\gamma}_{ij_1}(k_1) \cdots \hat{\gamma}_{im_j}(k_m) \zeta(k_{m+1}) \cdots \zeta(k_{n+1}) \rangle' \bigg|_{k_{n+1} \to 0}. \tag{3.28}
\]
Equations (3.25) and (3.27) are examples of Maldacena consistency conditions in the literature [1]. These are exact to all orders in the slow roll expansion.

The physical picture behind these relations is easy to state. The LHS of eq.(3.24) is the change of the n-point correlator under an overall change of scale. Exactly such a transformation is generated by a scalar perturbation \(\zeta(k_{n+1})\) in the limit of very long wavelength, \(k_{n+1} \to 0\), leading to the identity eq.(3.25).

Comments: The reader will note that the scale transformation eq.(3.12) is different from the isometry in de Sitter space, eq.(3.2). In de Sitter space, metric perturbations and also perturbations for test scalars freeze out at late times and become time independent. Thus, in effect, the scale transformation becomes eq.(3.12). In the inflationary case, once we choose the gauge where eq.(2.17) is met, we cannot make any time reparametrization,
Thus the only symmetries available are spatial reparametrizations.

Similarly, the special conformal transformations, which we will consider next, are different from the corresponding isometries in de Sitter space. However, again at late times, their action on time independent fields will be the same as for scales invariance obtained here is quite general. As mentioned above, it is valid to all orders in the slow roll expansion, and thus should hold even when the slow roll conditions are not valid. The assumptions one has used are that one can go to the gauge equation (2.17), and that the remaining metric perturbations in this gauge then freeze out due to the cosmological expansion. The residual spatial reparametrizations are then enough to give rise to the Ward identities above. A similar comment will also apply to the Ward identities of special conformal invariance we derive next.

### 3.2 Ward Identities for Special Conformal Transformations

We next turn to the special conformal transformations,

\[ x^i \rightarrow x^i + \alpha^i(x), \quad \alpha^i(x) = -2(b \cdot x)x^i + b^i x^2. \]  

(3.29)

Here there is an important extra subtlety. Consider the transformation of \( \zeta \) and \( \hat{\gamma}_{ij} \) under equation (3.29) (see appendix A),

\[ \zeta(x) \rightarrow \zeta(x) - 2(b \cdot x) + \alpha^i \partial_i \zeta(x), \]  

(3.30)

\[ \hat{\gamma}_{ij}(x) \rightarrow \hat{\gamma}_{ij}(x) + \alpha^m \partial_m \hat{\gamma}_{ij}(x) + 2 \mathcal{M}_{im}^b(x) \hat{\gamma}_{jm}(x) + 2 \mathcal{M}_{jm}^b(x) \hat{\gamma}_{im}(x), \]  

(3.31)

where \( \mathcal{M}_{ij}^b(x) \) is given by

\[ \mathcal{M}_{ij}^b(x) = x_i b_j - x_j b_i. \]  

(3.32)

It is easy to see that the transformation equation (3.31) does not preserve the transverse gauge condition equation (3.11) we have chosen for \( \hat{\gamma}_{ij} \). We must therefore carry out a compensating coordinate transformation

\[ x^i \rightarrow x^i + v^i(x), \]  

(3.33)

\[ v^i(x) = -\frac{6 b^m \hat{\gamma}_{im}(x)}{\partial^2}, \]

which then restores the transversality condition on \( \hat{\gamma}_{ij} \). Under this compensating transformation, \( \zeta \) and \( \hat{\gamma}_{ij} \) transform as

\[ \zeta(x) \rightarrow \zeta(x) - \frac{6 b^m \hat{\gamma}_{km}(x)}{\partial^2} \partial_k \zeta(x) - \frac{2 b^m \partial_i \hat{\gamma}_{jm}(x) \partial^j \hat{\gamma}_{im}(x)}{\partial^2} \hat{\gamma}_{ij}(x), \]  

(3.34)
In momentum space this takes the form
\[ \tilde{\gamma}_{ij}(x) \rightarrow \tilde{\gamma}_{ij}(x) - 6b^m \left[ \partial_i \left( \frac{\tilde{\gamma}_{jm}(x)}{2} \right) + \partial_j \left( \frac{\tilde{\gamma}_{im}(x)}{2} \right) \right] \]
\[ - 6b^m \left[ \tilde{\gamma}_{ik}(x) \partial_j \left( \frac{\tilde{\gamma}_{km}(x)}{2} \right) + \tilde{\gamma}_{jk}(x) \partial_i \left( \frac{\tilde{\gamma}_{km}(x)}{2} \right) \right] \]
\[ - 6b^m \partial_k \tilde{\gamma}_{ij}(x) \left( \frac{\tilde{\gamma}_{km}(x)}{2} \right) + 4b^m \tilde{\gamma}_{ab}(x) \partial_a \left( \frac{\tilde{\gamma}_{bm}(x)}{2} \right) (\delta_{ij} + \tilde{\gamma}_{ij}(x)) \].

(3.35)

The Ward identities then arise because of the combined transformations eq. (3.30) and eq. (3.34) for the transformation of \( \zeta \), and eq. (3.31) and eq. (3.35) for the transformation of \( \tilde{\gamma}_{ij} \). Note that the compensating transformation parameter \( \nu^i \) itself depends on \( \tilde{\gamma}_{ij} \). As a result, the compensating transformation becomes non-linear in the perturbations.

Once this subtlety requiring a compensating coordinate transformation is taken care of, the rest of the analysis follows along similar lines to that for the scale transformation case. The wave function \( \Psi \) is invariant under spatial reparametrizations, and therefore under the combined transformations eq. (3.29) and eq. (3.33). More correctly, this is true for all terms in the wave function which are quadratic or higher order in the perturbations. However, the inhomogeneous term in eq. (3.30), \(-2(b \cdot x)\), gives rise to a term in the change of the wave function which is linear in \( \zeta \). This term does not cancel. As a result we get a Ward identity for scalar perturbations of the form

\[ 4 \int d^3x d^3y (b \cdot x) \langle T(x)T(y) \rangle \zeta(x_1) \cdots \zeta(x_n) \zeta(y) \]
\[ + \langle \delta^C \zeta(x_1) \cdots \zeta(x_n) \rangle + \cdots + \langle \zeta(x_1) \cdots \delta^C \zeta(x_n) \rangle = 0, \]

(3.36)

where \( \delta^C \zeta \) denotes the complete homogeneous change in \( \zeta \) under eq. (3.30) and eq. (3.34),

\[ \delta^C \zeta(x) = (-2(b \cdot x)x^k + b^k x^2) \partial_k \zeta(x) - 6b^m \tilde{\gamma}_{km}(x) \partial_m \zeta(x) - 2b^m \partial_k \tilde{\gamma}_{jm}(x) \zeta_{ij}(x). \]

(3.37)

In momentum space this takes the form

\[ \langle \delta(\zeta(k_1)) \cdots \zeta(k_n) \rangle + \cdots + \langle \zeta(k_1) \cdots \delta(\zeta(k_n)) \rangle = \]
\[ - 2 \left( b \cdot \frac{\partial}{\partial k_{n+1}} \right) \frac{\langle \zeta(k_1) \cdots \zeta(k_{n+1}) \rangle}{\langle \zeta(k_{n+1}) \zeta(-k_{n+1}) \rangle} \bigg|_{k_{n+1} \rightarrow 0}, \]

(3.38)

where \( \delta(\zeta(k)) \) is given by

\[ \delta(\zeta(k)) = \tilde{\mathcal{L}}_k \zeta (k) + 6 b^m k^i \int \frac{d^3k}{(2\pi)^3} \frac{1}{k^2} \zeta(k - \tilde{k}) \tilde{\gamma}_{jm}(\tilde{k}) \]
\[ + 2 b^m k^i \int \frac{d^3k}{(2\pi)^3} \frac{1}{k^2} \tilde{\gamma}_{ij}(k - \tilde{k}) \tilde{\gamma}_{jm}(k). \]

(3.39)
and the operator $\tilde{L}^b_k$ is given by

$$\tilde{L}^b_k = 2 \left( k \cdot \frac{\partial}{\partial k} \right) \left( b \cdot \frac{\partial}{\partial k} \right) - \left( b \cdot k \right) \left( \frac{\partial}{\partial k} \cdot \frac{\partial}{\partial k} \right) + 6 \left( b \cdot \frac{\partial}{\partial k} \right).$$

(3.40)

Similarly, for the tensor perturbations we get the Ward identity

$$\langle \delta(\hat{\gamma}_{ij}(k_1)) \cdots \hat{\gamma}_{im}(k_n) \rangle + \cdots = -2 \left( b \cdot \frac{\partial}{\partial k_{n+1}} \right) \left( \hat{\gamma}_{ij}(k_1) \cdots \hat{\gamma}_{im}(k_n) \right) \frac{\partial}{\partial k_{n+1}} \left( \zeta(k_{n+1}) \zeta(-k_{n+1}) \right) \bigg|_{k_{n+1} \to 0},$$

(3.41)

where $\delta(\hat{\gamma}_{ij})$ is the complete change in $\hat{\gamma}_{ij}$ in momentum space, given by

$$\delta(\hat{\gamma}_{ij}(k)) = \tilde{L}^b_k \hat{\gamma}_{ij}(k) + 2 M^{b}_{im}(k) \hat{\gamma}_{jm}(k) + 2 \tilde{M}^{b}_{jm}(k) \hat{\gamma}_{im}(k)$$

$$+ 6b_m \frac{1}{k^2} \left( k_i \hat{\gamma}_{jm}(k) + k_j \hat{\gamma}_{im}(k) \right)$$

$$+ 6b_m \int \frac{d^3 k'}{(2\pi)^3} \frac{k_i' \hat{\gamma}_{km}(k')}{(k')^2} \left( k_j' \hat{\gamma}_{jk}(k - k') + k_j \hat{\gamma}_{ik}(k - k') \right)$$

$$+ 6b_m \int \frac{d^3 k'}{(2\pi)^3} \frac{k_j' \hat{\gamma}_{ij}(k')}{|k - k'|^2} \hat{\gamma}_{im}(k - k')$$

$$- 4b_m \delta_{ij} \int \frac{d^3 k'}{(2\pi)^3} \frac{k_u}{|k - k'|^2} \hat{\gamma}_{ab}(k') \hat{\gamma}_{bm}(k - k')$$

$$- 4b_m \int \frac{d^3 k'}{(2\pi)^3} \frac{d^3 k''}{(2\pi)^3} \frac{(k_u - k'_u)}{|k - k' - k''|^2} \hat{\gamma}_{ij}(k') \hat{\gamma}_{ab}(k'') \hat{\gamma}_{bm}(k - k' - k''),$$

(3.42)

where

$$\tilde{M}^{b}_{ij}(k) = b_j \frac{\partial}{\partial k^i} - b_i \frac{\partial}{\partial k^j}.$$

(3.43)

Finally, we can write the general Ward identity for the variation of a mixed correlator involving $m$ tensor perturbations $\hat{\gamma}_{ij}(k)$ and $(n-m)$ scalar perturbations $\zeta(k)$ as

$$\langle \delta(\hat{\gamma}_{ij}(k_1)) \cdots \hat{\gamma}_{im}(k_m) \zeta(k_{m+1}) \cdots \zeta(k_n) \rangle + \cdots$$

$$+ \langle \hat{\gamma}_{ij}(k_1) \cdots \delta(\hat{\gamma}_{im}(k_m)) \zeta(k_{m+1}) \cdots \zeta(k_n) \rangle$$

$$+ \langle \hat{\gamma}_{ij}(k_1) \cdots \hat{\gamma}_{im}(k_m) \delta(\zeta(k_{m+1})) \cdots \zeta(k_n) \rangle + \cdots$$

$$+ \langle \hat{\gamma}_{ij}(k_1) \cdots \hat{\gamma}_{im}(k_m) \zeta(k_{m+1}) \cdots \delta(\zeta(k_n)) \rangle$$

$$= -2 \left( b \cdot \frac{\partial}{\partial k_{n+1}} \right) \left( \hat{\gamma}_{ij}(k_1) \cdots \hat{\gamma}_{im}(k_m) \zeta(k_{m+1}) \cdots \zeta(k_{n+1}) \right) \frac{\partial}{\partial k_{n+1}} \left( \zeta(k_{n+1}) \zeta(-k_{n+1}) \right) \bigg|_{k_{n+1} \to 0},$$

(3.44)

where $\delta(\zeta(k))$ is given by eq.(3.39) and $\delta(\hat{\gamma}_{ij}(k))$ is given by eq.(3.42).

These identities are again exact, like the ones for scale transformations derived in section 3.1. They are valid to all orders in the slow roll expansion, and are one of the key results of this paper. Note that due to the non-linear nature of the transformations
eq. (3.34) and eq. (3.35), the resulting identities are in fact quite complicated. We will see in section 5, following [4], that the identity for the four point scalar perturbations in de Sitter space is indeed met.

It is important to note that both connected and disconnected contributions to the correlation functions may be important in the Ward identities. As mentioned in eq. (2.23), after suitable rescaling the action has a factor of $M_{Pl}^2/H^2$ in front of it. Since this ratio is large, eq. (2.24), the situation in cosmology is analogous to the large $N$ limit in AdS/CFT, with $M_{Pl}^2/H^2$ playing the role of $N^2$. Disconnected components in the Ward identities can then often dominate over connected ones. More accurately, the non-linear nature of the transformation in the compensating spatial reparametrization means that different number of fields will be present in correlation functions involved in the LHS of the Ward identities eq. (3.38), eq. (3.41). The suppression at large $N$ due to additional fields can be compensated for by including additional disconnected components. For more details and an explicit example see section 5.

Let us also note that in the Ward identity for scalar perturbations eq. (3.38), for the cases $n = 2, 3$, the extra terms in $\delta \zeta (k)$ due to the compensating spatial reparametrization can be neglected to the leading order in $H^2/M_{Pl}^2$. The extra terms are the last two terms on the RHS of eq. (3.39). This will become clearer from the discussion in section 5. As a result, for the cases $n = 2, 3$, the Ward identity eq. (3.38) takes the form,

\begin{equation}
\left( \sum_{a=1}^{2} \hat{L}_{k_a} b \right) \langle \zeta (k_1) \zeta (k_2) \rangle = -2 \left( b \cdot \frac{\partial}{\partial k_3} \right) \frac{\langle \zeta (k_1) \zeta (k_2) \zeta (k_3) \rangle}{\langle \zeta (k_3) \zeta (-k_3) \rangle'} \bigg|_{k_3 \to 0},
\end{equation}

and

\begin{equation}
\left( \sum_{a=1}^{3} \hat{L}_{k_a} b \right) \langle \zeta (k_1) \zeta (k_2) \zeta (k_3) \rangle = -2 \left( b \cdot \frac{\partial}{\partial k_4} \right) \frac{\langle \zeta (k_1) \zeta (k_2) \zeta (k_3) \zeta (k_4) \rangle}{\langle \zeta (k_4) \zeta (-k_4) \rangle'} \bigg|_{k_4 \to 0}.
\end{equation}

For the special case $b \propto k_3$ in eq. (3.45) and $b \propto k_4$ in eq. (3.46), we obtain the conformal consistency relations derived in eq. (37) of [26]. However, as we will see in section 5, for the case $n \geq 4$ in eq. (3.38) the extra terms in $\delta \zeta (k)$ due to the compensating spatial reparametrization cannot be neglected. Thus, the Ward identities obtained from eq. (3.38) for $b \propto k_{n+1}$, $n \geq 4$, have additional terms as compared to eq. (37) of [26].

This concludes our summary of some of the main results of this paper.

4 Conditions on the Coefficient Functions

In this section, we will show how the invariance of the wave function under the scale and special conformal transformations, eq. (3.12) and eq. (3.29), lead to conditions on the coefficient functions which are analogous to Ward identities in a conformal field theory. These Ward identities also incorporate the breaking of conformal invariance in the inflationary background.
We start with the Ward identities of spatial reparametrizations in general. These will give rise to conditions analogous to Ward identities of stress-energy conservation in a field theory. We then obtain the identities for scale and special conformal transformations.

In this section, it will be convenient to work with a general metric perturbation $\hat{\gamma}_{ij}$ without further imposing the transversality condition eq. (3.11). Once the constraints on the coefficient functions have been obtained for these general perturbations, they will lead to constraints on expectation values which can be calculated only after further gauge fixing, as explained in section 3 above.

### 4.1 Spatial Reparametrizations

Under a spatial reparametrization eq. (2.7), the perturbations $\zeta$ and $\hat{\gamma}_{ij}$ transforms as

$$\zeta \rightarrow \zeta + \frac{1}{3} \partial_i v_i + v^i \partial_i \zeta + \frac{1}{3} \partial_i v_j \hat{\gamma}_{ij}, \quad (4.1)$$

and

$$\hat{\gamma}_{ij} \rightarrow \hat{\gamma}_{ij} + \left( \partial_i v_j + \partial_j v_i - \frac{2}{3} \partial_a v_a \delta_{ij} \right) + \left( \hat{\gamma}_{ik} \partial_j v^k + \hat{\gamma}_{jk} \partial_i v^k \right)$$

$$+ v^k \partial_k \hat{\gamma}_{ij} - \frac{2}{3} \partial_a v_a \hat{\gamma}_{ij} - \frac{2}{3} \partial_a v_b \hat{\gamma}_{ab} (\delta_{ij} + \hat{\gamma}_{ij}), \quad (4.2)$$

See appendix A for some details of the derivation.

Now, for the invariance of the wave function under spatial reparametrizations, the terms proportional to the transformation parameter $v_i$ that get generated because of the transformations eq. (4.1), eq. (4.2), must cancel with one another. Consider first such terms which are linear in $\zeta$. These terms are produced by the first and second terms of the wave function, eq. (2.20). These are

$$\delta \left( - \frac{1}{2} \int d^3 x \ d^3 y \ \zeta(x) \zeta(y) \langle T(x) T(y) \rangle \right) \quad (4.3)$$

$$= - \frac{1}{6} \int d^3 x \ d^3 y \left[ \partial_i v_i(x) \zeta(y) + \zeta(x) \partial_i v_i(y) \right] \langle T(x) T(y) \rangle,$$

and

$$\delta \left( - \int d^3 x \ d^3 y \ \zeta(x) \hat{\gamma}_{ij}(y) \langle T(x) \hat{T}^{ij}(y) \rangle \right) \quad (4.4)$$

$$= - 2 \int d^3 x \ d^3 y \ \zeta(x) \partial_{y^i} v_j(y) \langle T(x) \hat{T}^{ij}(y) \rangle.$$

Mutual cancellation of the terms in eq. (4.3) and eq. (4.4) produces the Ward identity$^4$

$$\partial_i \langle \hat{T}^{ij}(x) T(y) \rangle + \frac{1}{6} \partial_j \langle T(x) T(y) \rangle = 0. \quad (4.5)$$

$^4$Note that unless otherwise stated, $\partial_i$ stands for the derivative with respect to $x^i$, i.e. $\partial / \partial x^i$. 

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Using
\[ T^{ij} = \hat{T}^{ij} + \frac{1}{3} \delta_{ij} \mathcal{T}, \]  
and eq.(2.21), this can also be written as
\[ \partial_i \langle T^{ij}(x)T(y) \rangle = 0. \]  
(4.7)

Similarly, canceling the extra terms in the wave function which are linear in \( \hat{\gamma}_{ij} \) gives
\[ \partial_i \langle T^{ij}(x)T^{kl}(y) \rangle = 0. \]  
(4.8)

Proceeding in a similar manner, and canceling terms linear in \( v_i \) and quadratic in \( \zeta \) gives
\[ \partial_i \langle \hat{T}^{ij}(x)T(y)T(z) \rangle = \frac{1}{2} \partial_j \left[ \delta^3(x - y) \right] \langle T(x)T(z) \rangle + \frac{1}{2} \partial_j \left[ \delta^3(x - z) \right] \langle T(x)T(y) \rangle 
- \frac{1}{6} \partial_j \langle T(x)T(y)T(z) \rangle. \]  
(4.9)

Eq.(4.9) can be rewritten in terms of the complete stress-energy tensor \( T^{ij} \) and its trace \( \mathcal{T} \) as
\[ \partial_i \langle T^{ij}(x)T(y)T(z) \rangle = \frac{1}{2} \partial_j \left[ \delta^3(x - y) \right] \langle T(x)T(z) \rangle + \frac{1}{2} \partial_j \left[ \delta^3(x - z) \right] \langle T(x)T(y) \rangle. \]  
(4.10)

Similarly, canceling terms proportional to \( \zeta \hat{\gamma}_{ij} \) produces the Ward identity
\[ \partial_i \langle T^{ij}(x)\hat{T}^{kl}(y)T(z) \rangle = \frac{1}{2} \partial_j \left[ \delta^3(x - y) \right] \langle \hat{T}^{kl}(x)T(z) \rangle 
+ \frac{1}{2} \partial_j \left[ \delta^3(x - z) \right] \langle T(x)\hat{T}^{kl}(y) \rangle 
+ \frac{1}{3} \partial_j \left[ \delta^3(x - y) \right] \langle \hat{T}^{kl}(y)T(z) \rangle 
- \delta_{ji} \partial_i \left[ \delta^3(x - y) \right] \langle T^{kl}(y)T(z) \rangle, \]  
(4.11)

and proportional to \( \hat{\gamma}_{ij} \hat{\gamma}_{kl} \) gives
\[ \partial_i \langle T^{ij}(x)\hat{T}^{kl}(y)\hat{T}^{mn}(z) \rangle = \partial_j \left[ \delta^3(x - z) \right] \langle \hat{T}^{mn}(x)\hat{T}^{kl}(y) \rangle 
+ \frac{2}{3} \partial_j \left[ \delta^3(x - z) \right] \langle \hat{T}^{kl}(y)\hat{T}^{mn}(z) \rangle 
- 2 \delta_{jn} \partial_i \left[ \delta^3(x - z) \right] \langle \hat{T}^{kl}(y)\hat{T}^{nm}(z) \rangle. \]  
(4.12)

### 4.2 Scale Transformations

We now turn to deriving conditions on the coefficient functions for the invariance of the wave function under scale transformations, eq.(3.12). The change in \( \zeta \) and \( \hat{\gamma}_{ij} \) under these transformations is given by eq.(3.13) and eq.(3.14) respectively.

The procedure we follow is the same as outlined above. Canceling the terms linear in
the transformation parameter $\lambda$ and quadratic in $\zeta$ gives
\[
\int d^3z \langle T(x)T(y)T(z) \rangle = \left[ x^i \frac{\partial}{\partial x^i} + y^j \frac{\partial}{\partial y^j} \right] \langle T(x)T(y) \rangle + 6 \langle T(x)T(y) \rangle, \tag{4.13}
\]
which in momentum space takes the form
\[
\lim_{k_3 \to 0} \langle T(k_1)T(k_2)T(k_3) \rangle = -\left( \sum_{a=1}^{2} k_a \frac{\partial}{\partial k_a} \right) \langle T(k_1)T(k_2) \rangle, \tag{4.14}
\]
where $k_a \equiv |k_a|$.

In general, the $n$-point correlation function of the $T$ operators will be related under scaling to the $(n-1)$-point correlation function through the relation
\[
\lim_{k_n \to 0} \langle T(k_1) \cdots T(k_n) \rangle = -\left( \sum_{a=1}^{n-1} k_a \frac{\partial}{\partial k_a} \right) \langle T(k_1) \cdots T(k_{n-1}) \rangle. \tag{4.15}
\]

Requiring the cancellation of the extra quadratic terms in $\hat{\gamma}_{ij}$ gives us the Ward identity
\[
\int d^3z \langle \hat{T}^{ij}(x)\hat{T}^{kl}(y)T(z) \rangle = \left[ x^i \frac{\partial}{\partial x^i} + y^j \frac{\partial}{\partial y^j} \right] \langle \hat{T}^{ij}(x)\hat{T}^{kl}(y) \rangle + 6 \langle \hat{T}^{ij}(x)\hat{T}^{kl}(y) \rangle, \tag{4.16}
\]
which translates in momentum space to
\[
\lim_{k_3 \to 0} \langle \hat{T}^{ij}(k_1)\hat{T}^{kl}(k_2)T(k_3) \rangle = -\left[ \sum_{a=1}^{2} k_a \frac{\partial}{\partial k_a} \right] \langle \hat{T}^{ij}(k_1)\hat{T}^{kl}(k_2) \rangle. \tag{4.17}
\]

The general form of the scaling Ward identity relating the $n$-point correlation function of $(n+1)$ $\hat{T}^{ij}$ operators and one insertion of $T$, to the $(n+1)$-point correlation function of the $\hat{T}^{ij}$ operators is
\[
\lim_{k_{n+1} \to 0} \langle \hat{T}^{i_{j_1}}(k_1) \cdots \hat{T}^{i_{j_{n-1}}}(k_{n-1})T(k_n) \rangle = \\
-\left[ \sum_{a=1}^{n-1} k_a \frac{\partial}{\partial k_a} \right] \langle \hat{T}^{i_{j_1}}(k_1) \cdots \hat{T}^{i_{j_{n-1}}}(k_{n-1})T(k_n) \rangle. \tag{4.18}
\]

One can also write the general scaling Ward identity relating the $(n+1)$-point correlation function involving $m$ insertions of $\hat{T}^{ij}$ and $(n+1-m)$ insertions of $T$, with the $n$-point correlation function of $m$ insertions of $\hat{T}^{ij}$ and $(n-m)$ of $T$, as
\[
\lim_{k_{n+1} \to 0} \langle \hat{T}^{i_{j_1}}(k_1) \cdots \hat{T}^{i_{j_m}}(k_m)T(k_{m+1}) \cdots T(k_{n+1}) \rangle = \\
-\left[ \sum_{a=1}^{n} k_a \frac{\partial}{\partial k_a} \right] \langle \hat{T}^{i_{j_1}}(k_1) \cdots \hat{T}^{i_{j_m}}(k_m)T(k_{m+1}) \cdots T(k_n) \rangle. \tag{4.19}
\]
One final comment. We began this subsection by considering terms which are quadratic in \( \zeta \), eq.(4.13). There is also a term which is linear in both \( \zeta \) and the transformation parameter \( \lambda \). Since \( \lambda \) is spatially constant, this term has support only at zero momentum in the wave function and we neglect it here. However, in deriving expectation values, this term which is uncanceled plays a crucial role, as was discussed in section 3.1 above.

4.3 Special Conformal Transformations

We will now derive Ward identities for the invariance of the wave function under special conformal transformations, eq.(3.29). The change in \( \zeta \) and \( \hat{\gamma}_{ij} \) under this is given by eq.(3.30) and eq.(3.31). Note that, as was mentioned at the beginning of this section, we are considering a general graviton perturbation here and have not fixed it to be transverse; as a result we do not have to worry about the fact that a special conformal transformation leads to the gauge eq.(3.11) not being preserved.

We start again with terms which are linear in \( b_i \) and quadratic in \( \zeta \). Invariance of \( \Psi \) then gives

\[
3 \mathbf{b} \cdot (x + y) \langle T(x)T(y) \rangle - \frac{1}{2} \left[ \alpha^i(x) \partial_x x^i + \alpha^i(y) \partial_y y^i \right] \langle T(x)T(y) \rangle = \int d^3z \left( \mathbf{b} \cdot \mathbf{z} \right) \langle T(x)T(y)T(z) \rangle,
\]

which in momentum space has the form

\[
\frac{1}{2} \left[ \mathcal{L}_b^{k_1} + \mathcal{L}_b^{k_2} \right] \langle T(k_1)T(k_2) \rangle = - \left( \mathbf{b} \cdot \frac{\partial}{\partial k_3} \right) \langle T(k_1)T(k_2)T(k_3) \rangle \bigg|_{k_3 \to 0},
\]

where \( \mathcal{L}_b^k \) is the operator

\[
\mathcal{L}_b^k = 2 \left( k \cdot \frac{\partial}{\partial k} \right) \left( \mathbf{b} \cdot \frac{\partial}{\partial k} \right) - \langle \mathbf{b} \cdot k \rangle \left( \frac{\partial}{\partial k} \frac{\partial}{\partial k} \right)
\]

\[
= (\mathbf{b} \cdot k) \left( -2 \frac{\partial^2}{k \partial k^2} + \frac{\partial}{\partial k} \right).
\]

In general, the \( n \)-point correlation function of \( T \) operators will be related to the \( (n-1) \)-point function under a special conformal transformation as

\[
\frac{1}{2} \left( \sum_{a=1}^{n-1} \mathcal{L}_b^{k_a} \right) \langle T(k_1) \cdots T(k_{n-1}) \rangle = - \left( \mathbf{b} \cdot \frac{\partial}{\partial k_n} \right) \langle T(k_1) \cdots T(k_n) \rangle \bigg|_{k_n \to 0}.
\]

Similarly, canceling the extra terms quadratic in \( \hat{\gamma}_{ij} \) gives

\[
[D_x^b + D_y^b] \langle \hat{T}^{ij}(x)\hat{T}^{kl}(y) \rangle = - \int d^3z \left( \mathbf{b} \cdot \mathbf{z} \right) \langle \hat{T}^{ij}(x)\hat{T}^{kl}(y)T(z) \rangle,
\]
where the action of the operator $\mathcal{D}_a^b$ is defined by

$$
\mathcal{D}_a^b \hat{T}^{ij}(x) = -3 (b \cdot x) \hat{T}^{ij}(x) + \frac{1}{2} \alpha^m(x) \partial_m \hat{T}^{ij}(x)
- \mathcal{M}_{mn}^b(x) \hat{T}^{ij}(x) - \mathcal{M}_{mj}^b(x) \hat{T}^{im}(x),
$$

(4.25)

with $\mathcal{M}_{ij}^b(x)$ as defined in eq.(3.32). The Ward identity eq. (4.24) can be expressed in the momentum space as

$$
[\hat{D}_k^b + \hat{D}_k^b] \langle \hat{T}^{ij}(k_1) \hat{T}^{kl}(k_2) \rangle = - \left( b \cdot \frac{\partial}{\partial k_3} \right) \langle \hat{T}^{ij}(k_1) \hat{T}^{kl}(k_2) \hat{T}(k_3) \rangle \bigg|_{k_3 \to 0},
$$

(4.26)

where the momentum space operator $\hat{D}_k^b$ is defined by

$$
\hat{D}_k^b \hat{T}^{ij}(k) = \frac{1}{2} L_b^j \hat{T}^{ij}(k) - \mathcal{M}_{nj}^b(k) \hat{T}^{ij}(k) - \mathcal{M}_{mj}^b(k) \hat{T}^{im}(k),
$$

(4.27)

with the operator $L_b^j$ as given in eq.(4.22), and $\mathcal{M}_{ij}^b(k)$ as given by eq.(3.43).

Following a similar procedure as outlined above, we get the Ward identity for special conformal transformations relating the $n$-point correlation function with $(n-1)$ insertions of $\hat{T}^{ij}$ and one insertion of $T$, to the $(n-1)$ point correlation function of $\hat{T}^{ij}$ to be

$$
\left( \sum_{a=1}^{n-1} \hat{D}_{ka}^b \right) \langle \hat{T}^{i_1j_1}(k_1) \cdots \hat{T}^{i_{n-1}j_{n-1}}(k_{n-1}) \rangle = - \left( b \cdot \frac{\partial}{\partial k_n} \right) \langle \hat{T}^{i_1j_1}(k_1) \cdots \hat{T}^{i_{n-1}j_{n-1}}(k_{n-1}) \hat{T}(k_n) \rangle \bigg|_{k_n \to 0}.
$$

(4.28)

In general, the Ward identity of special conformal invariance relating the $n$-point correlation function with $m$ insertions of $\hat{T}^{ij}$ and $(n-m)$ insertions of $T$, to the $(n+1)$-point correlation function with $m$ insertions of $\hat{T}^{ij}$ and $(n+1-m)$ insertions of $T$ is given by

$$
\left[ \sum_{a=1}^{m} \hat{D}_{ka}^b \right] + \frac{1}{2} \sum_{r=m+1}^{n} \left( L_k^r \right) \langle \hat{T}^{i_1j_1}(k_1) \cdots \hat{T}^{i_{m}j_{m}}(k_m) \hat{T}(k_{m+1}) \cdots \hat{T}(k_n) \rangle
- \left( b \cdot \frac{\partial}{\partial k_{n+1}} \right) \langle \hat{T}^{i_1j_1}(k_1) \cdots \hat{T}^{i_{m}j_{m}}(k_m) \hat{T}(k_{m+1}) \cdots \hat{T}(k_{n+1}) \rangle \bigg|_{k_{n+1} \to 0},
$$

(4.29)

where the operators $\hat{D}_{ka}^b$ and $L_k^r$ are given in eq.(4.27) and eq.(4.22) respectively.

Finally, as in the case of the scale transformations, there is one remaining term linear in $\hat{\gamma}_{ij}$ and $b_i$, with support at zero momentum, which is uncanceled. In calculating expectation values, section 3, this term will vanish once we choose the transverse gauge, eq.(3.11).

5 Explicit Checks of the Special Conformal Ward Identities

In this section, we present a few checks of the Ward identities of special conformal transformations, eq.(3.38) and eq.(3.41). Our analysis above has been to the leading order in
As a result, we see that the propagators like the action eq. (5.1) in the de Sitter limit. We substitute
\[
\zeta = -\frac{H}{\phi} \delta\phi,
\]
and take the limit \(\hat{\phi} \to 0\). Keeping only the leading terms, we get
\[
\left[ \sum_{a=1}^{2} \hat{\mathcal{L}}_{k_{a}}^{p} \right] \langle \delta\phi(k_{1})\delta\phi(k_{2}) \rangle = -\left\{ \left( 6 b^{n} k_{1}^{n} \int \frac{d^{3}\tilde{k}}{(2\pi)^{3}} \frac{1}{k^{2}} \langle \delta\phi(k_{1} - \tilde{k})\delta\phi(k_{2}) \tilde{\gamma}_{lm}(\tilde{k}) \rangle + (k_{1} \leftrightarrow k_{2}) \right) \right\}.
\]

Next, we introduce suitable factors of \(H/M_{Pl}\). The wave function eq. (2.20) arises from the action eq. (6.31), which has a factor of \(1/G \sim M_{Pl}^{2}\) in front of it. Thus, after suitably rescaling by powers of the Hubble parameter, \(\Psi\) will go like
\[
\Psi \sim \exp \left[ -\frac{M_{Pl}^{2}}{H^{2}} \left\{ \frac{1}{2} \int d^{3}x d^{3}y \delta\phi(x)\delta\phi(y) \langle O(x)O(y) \rangle + \frac{1}{2} \int d^{3}x d^{3}y \tilde{\gamma}_{ij}(x)\tilde{\gamma}_{kl}(y) \langle \tilde{T}^{ij}(x)\tilde{T}^{kl}(y) \rangle + \frac{1}{3!} \int d^{3}x d^{3}y d^{3}z \delta\phi(x)\delta\phi(y)\delta\phi(z) \langle O(x)O(y)O(z) \rangle + \frac{1}{3!} \int d^{3}x d^{3}y d^{3}z \delta\phi(x)\delta\phi(y)\delta\phi(z) \langle O(x)O(y)\tilde{T}^{ij}(z) \rangle + \cdots \right\} \right].
\]

As a result, we see that the propagators \(\langle \delta\phi \delta\phi \rangle\) or \(\langle \tilde{\gamma}_{ij}\tilde{\gamma}_{kl} \rangle\) behave like \(H^{2}/M_{Pl}^{2}\), while each vertex, e.g., the three point vertices \(\langle O(x)O(y)O(z) \rangle\) and \(\langle O(x)O(y)\tilde{T}^{ij}(z) \rangle\) in eq. (5.4), go like \(M_{Pl}^{2}/H^{2}\). With this, one can argue that
\[
\langle \delta\phi \delta\phi \tilde{\gamma}_{ij} \rangle \sim \frac{H^{4}}{M_{Pl}^{2}}.
\]

From eq. (5.5), it becomes clear that to leading order in \(H^{2}/M_{Pl}^{2}\), the correlation
\[...\]
function $\langle \delta \phi(\mathbf{k}_1 - \mathbf{\tilde{k}}) \delta \phi(\mathbf{k}_2) \hat{\gamma}_{im}(\mathbf{\tilde{k}}) \rangle$ in the RHS of eq.(5.3) is suppressed compared to $\langle \delta \phi(\mathbf{k}_1) \delta \phi(\mathbf{k}_2) \rangle$ in the LHS and eq.(5.3) reduces to
\[
\left[ \sum_{a=1}^{2} \hat{L}^b_{ka} \right] \langle \delta \phi(\mathbf{k}_1) \delta \phi(\mathbf{k}_2) \rangle = 0. \tag{5.6}
\]
This condition is the statement of conformal invariance of the two point function $\langle \delta \phi(\mathbf{k}_1) \delta \phi(\mathbf{k}_2) \rangle$ in de Sitter space, and it is easy to verify that it is met.

Next, let us consider the $n = 2$ scalar Ward identity, eq.(5.1), to the first non-trivial order in the slow roll approximation (but still to the leading order in $H^2/M^2_{Pl}$). The terms proportional to $\langle \zeta \zeta \hat{\gamma} \rangle$ and $\langle \hat{\gamma} \zeta \zeta \rangle$ in eq.(5.1) scale as $H^4/M^4_{Pl}$, and can be dropped compared to other terms, which scale as $H^2/M^2_{Pl}$, in the limit $H \ll M_{Pl}$. Eq.(5.1) then reduces to
\[
\left[ \sum_{a=1}^{2} \hat{L}^b_{ka} \right] \langle \zeta(\mathbf{k}_1) \zeta(\mathbf{k}_2) \rangle = -2 \left( b \cdot \frac{\partial}{\partial \mathbf{k}_3} \right) \left. \frac{1}{\langle \zeta(\mathbf{k}_3) \zeta(-\mathbf{k}_3) \rangle} \langle \zeta(\mathbf{k}_1) \zeta(\mathbf{k}_2) \zeta(\mathbf{k}_3) \rangle \right|_{k_a \to 0}. \tag{5.7}
\]
In the canonical slow-roll model we have
\[
\langle \zeta(\mathbf{k}_1) \zeta(\mathbf{k}_2) \rangle = (2\pi)^3 \delta^3(\mathbf{k}_1 + \mathbf{k}_2) \frac{H^2}{M^2_{Pl}} \frac{1}{4\epsilon} k_1^{-3+n_S}, \tag{5.8}
\]
and
\[
\langle \zeta(\mathbf{k}_1) \zeta(\mathbf{k}_2) \zeta(\mathbf{k}_3) \rangle = (2\pi)^3 \delta^3 \left( \sum_{a=1}^{3} k_a \right) \frac{H^4}{M^4_{Pl}} \frac{1}{4\epsilon^2} \frac{1}{\prod_a (2k_a)^3} \left[ (3\epsilon - 2\eta) \sum_{a=1}^{3} k_a^3 + 2\epsilon \left( \frac{1}{2} \sum_{a \neq b} k_a k_b^2 + \frac{4}{k_t} \sum_{a > b} k_a^2 k_b^2 \right) \right]. \tag{5.9}
\]
Working to the leading order in the slow roll parameters $\epsilon, \eta$ as well as the scalar tilt $n_S$, one finds that eq.(5.7) implies
\[
n_S = 2(\eta - 3\epsilon), \tag{5.10}
\]
which is the correct result, [1].

Note that the case $n = 3$ for the Ward identity eq.(3.38) in the slow roll approximation was discussed in detail in [5].

Next, we turn to the graviton two-point correlator and consider the Ward identity eq.(3.41). Again dropping terms which are subleading in $H^2/M^2_{Pl}$, and working in the de Sitter limit $\dot{\phi} \to 0$, we get,

---

5 The result eq.(5.9) is from [1], with $k_t = k_1 + k_2 + k_3$. 

---
\[
\left[ \sum_{a=1}^{2} \tilde{L}_{k,a}^b \right] \langle \tilde{\gamma}_{ij}(k_1)\tilde{\gamma}_{kl}(k_2) \rangle 
\]
\[
= - \left( 2 \tilde{M}_{im}(k_1)\langle \tilde{\gamma}_{jm}(k_1)\tilde{\gamma}_{kl}(k_2) \rangle + 2 \tilde{M}_{jm}(k_1)\langle \tilde{\gamma}_{im}(k_1)\tilde{\gamma}_{kl}(k_2) \rangle 
+ 2 \tilde{M}_{im}(k_2)\langle \tilde{\gamma}_{jm}(k_2)\tilde{\gamma}_{kl}(k_1) \rangle + 2 \tilde{M}_{jm}(k_2)\langle \tilde{\gamma}_{im}(k_2)\tilde{\gamma}_{kl}(k_1) \rangle 
+ \frac{6b^m}{k_1^2} (k_{11} \langle \tilde{\gamma}_{jm}(k_1)\tilde{\gamma}_{kl}(k_2) \rangle + k_{1j} \langle \tilde{\gamma}_{im}(k_1)\tilde{\gamma}_{kl}(k_2) \rangle) 
+ \frac{6b^m}{k_2^2} (k_{2k} \langle \tilde{\gamma}_{ij}(k_1)\tilde{\gamma}_{lm}(k_2) \rangle + k_{2l} \langle \tilde{\gamma}_{ij}(k_1)\tilde{\gamma}_{km}(k_2) \rangle) \right).
\]

The two-point graviton correlator is
\[
\langle \tilde{\gamma}_{ij}(k)\tilde{\gamma}_{kl}(-k) \rangle' = \frac{P_{ijkl}(k)}{k^3},
\]
where \(P_{ijkl}(k)\) is given in eq.(5.2) of [4]. An explicit calculation then shows that eq.(5.11) is indeed met. Note that the last two terms on the RHS of eq.(5.11) come from the compensating spatial reparametrization which maintains the transverse gauge for \(\tilde{\gamma}_{ij}\).

### 5.2 The Scalar Four Point Function

In this subsection, we consider the Ward identity eq.(3.38) for the case \(n = 4\). We will work to the leading order in \(H^2/M_P^2\), and to the leading order in \(\dot{\phi}/H\), i.e. in the de Sitter limit. Eq.(3.38) for the case of \(n = 4\) then gives
\[
\left[ \sum_{a=1}^{4} \tilde{L}_{k,a}^b \right] \langle \zeta(k_1)\zeta(k_2)\zeta(k_3)\zeta(k_4) \rangle 
\]
\[
\left\{ \frac{b^m k^i}{2} \int \frac{d^3 k}{(2\pi)^3} \frac{1}{k^2} \times 
\left[ 3 \langle \zeta(k_1 - \tilde{k})\zeta(k_2)\zeta(k_3)\zeta(k_4) \rangle \right] 
+ \langle \gamma_{ij}(k_1 - \tilde{k})\tilde{\gamma}_{jm}(\tilde{k})\zeta(k_2)\zeta(k_3)\zeta(k_4) \rangle \right\} 
\]
\[
= - \left\{ \frac{b}{\partial k_5} \frac{1}{\langle \zeta(k_5)\zeta(-k_5) \rangle} \langle \zeta(k_1)\cdots\zeta(k_5) \rangle \right\}_{k_5 \to 0}.
\]

We next write eq.(5.13) in terms of \(\delta \phi\) by using eq.(5.2), and take the de Sitter limit \(\dot{\phi} \to 0\). In this limit, the terms in eq.(5.13) that survive are
\[
\left[ \sum_{a=1}^{4} \tilde{L}_{k,a}^b \right] \langle \delta \phi(k_1)\delta \phi(k_2)\delta \phi(k_3)\delta \phi(k_4) \rangle 
\]
\[
= - \left\{ \frac{b^m k^i}{2} \int \frac{d^3 k}{(2\pi)^3} \frac{1}{k^2} \langle \delta \phi(k_1 - \tilde{k})\delta \phi(k_2)\delta \phi(k_3)\delta \phi(k_4)\tilde{\gamma}_{jm}(\tilde{k}) \rangle \right\} 
\]
\[
+ \langle k_1 \leftrightarrow k_2 \rangle + \langle k_1 \leftrightarrow k_3 \rangle + \langle k_1 \leftrightarrow k_4 \rangle \right\}.
\]
Introducing suitable factors of $H/M_{Pl}$ by rescaling the wave function, eq. (5.4), we see that for connected correlators,

$$\langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle \sim \frac{H^6}{M_{Pl}^6}; \quad \langle \delta \phi \tilde{\gamma}_{ij} \delta \phi \delta \phi \rangle \sim \frac{H^8}{M_{Pl}^8}. \quad (5.15)$$

From eq. (5.15), it seems that for the Hubble scale being much smaller compared to the Planck scale, $H \ll M_{Pl}$, the correlation function $\langle \delta \phi(k_1 - \tilde{k}) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \tilde{\gamma}_{im}(\tilde{k}) \rangle$ in the RHS of eq. (5.14) is suppressed compared to $\langle \delta \phi(k_1) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \rangle$ in the LHS. However, one should also consider disconnected contributions to the RHS of eq. (5.14) which may contribute to the same order of $H/M_{Pl}$ as the LHS. In particular, there is a disconnected contribution to the five point function $\langle \delta \phi \delta \phi \delta \phi \delta \phi \delta \phi \rangle$ in eq. (5.14), which goes as

$$\langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle \sim \frac{H^6}{M_{Pl}^6}, \quad (5.16)$$

and which is of the same order as $\langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle$. With these considerations, eq. (5.14) in the limit $H \ll M_{Pl}$ becomes

$$\left[ \sum_{a=1}^{4} \hat{\mathcal{L}}_{ka}^{b} \right] \langle \delta \phi(k_1) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \rangle \ni - \left\{ \left( 6 b^m k_1^i \int \frac{d^3 \tilde{k}}{(2\pi)^3} \frac{1}{k^2} \langle \delta \phi(k_1 - \tilde{k}) \delta \phi(k_2) \rangle \langle \tilde{\gamma}_{im}(\tilde{k}) \delta \phi(k_3) \delta \phi(k_4) \rangle \right) + \langle k_2 \leftrightarrow k_3 \rangle + \langle k_2 \leftrightarrow k_4 \rangle + \langle k_1 \leftrightarrow k_2 \rangle + \langle k_1 \leftrightarrow k_3 \rangle + \langle k_1 \leftrightarrow k_4 \rangle \right\}. \quad (5.17)$$

It is important to note that there are other possible disconnected contributions to the five point correlator $\langle \delta \phi(k_1 - \tilde{k}) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \tilde{\gamma}_{im}(\tilde{k}) \rangle$, such as

$$\langle \delta \phi(k_2) \delta \phi(k_3) \rangle \langle \tilde{\gamma}_{im}(\tilde{k}) \delta \phi(k_1 - \tilde{k}) \delta \phi(k_4) \rangle. \quad (5.18)$$

However, this requires $k_2 + k_3 = k_1 + k_4 = 0$, and will not contribute in general.

Eq. (5.17) gives the change in the four point correlator $\langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle$ under a special conformal transformation in the exact de Sitter limit. Using the relations

$$\langle \delta \phi(k_1) \delta \phi(k_2) \rangle = (2\pi)^3 \delta^3(k_1 + k_2) \langle \delta \phi(k_1) \delta \phi(k_2) \rangle' \ni \frac{H^2}{M_{Pl}^2} \frac{1}{2k_1^3}, \quad (5.19)$$

and

$$\langle \tilde{\gamma}_{im}(\tilde{k}) \delta \phi(k_3) \delta \phi(k_4) \rangle = -2 \langle \delta \phi(k_3) \delta \phi(-k_3) \rangle' \langle \delta \phi(k_4) \delta \phi(-k_4) \rangle' \langle \tilde{\gamma}_{im}(\tilde{k}) \tilde{\gamma}_{kl}(-\tilde{k}) \rangle' \langle \tilde{T}_{kl}(\tilde{k}) O(k_3) O(k_4) \rangle$$

$$\ni -2 \frac{H^4}{M_{Pl}^4} \langle \tilde{\gamma}_{im}(\tilde{k}) \tilde{\gamma}_{kl}(-\tilde{k}) \rangle' \langle \tilde{T}_{kl}(\tilde{k}) O(k_3) O(k_4) \rangle \frac{1}{(2k_1^2)(2k_4^2)}, \quad (5.20)$$
we can write eq.(5.17) as

\[
\left[ \sum_{a=1}^{4} \hat{C}_{k_a}^b \right] \langle \delta \phi(k_{1}) \delta \phi(k_{2}) \delta \phi(k_{3}) \delta \phi(k_{4}) \rangle = \\
\left[ \frac{H^6}{M_{Pl}^4} \delta_{pimn} \delta_{jk} \right] \left[ \frac{k_{1}^2 + k_{2}^2}{(k_{1} + k_{2})^5} \right] \left\{ \left( \frac{k_{1}^i}{k_{1}^3} + \frac{k_{2}^i}{k_{2}^3} \right) \left( \frac{\hat{T}_{kl}(k_{1} + k_{2})O(k_{3})O(k_{4})}{(2k_{3}^3)} \right) \right\} \\
+ \left[ \frac{k_{3}^i}{k_{3}^3} + \frac{k_{4}^i}{k_{4}^3} \right] \left( \frac{\hat{T}_{kl}(k_{3} + k_{4})O(k_{1})O(k_{2})}{(2k_{3}^3)(2k_{4}^3)} \right) \right\} \\
+ \left[ k_{2} \leftrightarrow k_{3} \right] + \left[ k_{2} \leftrightarrow k_{4} \right],
\]

where we have used the eq.(5.12).

Eq.(5.21) gives us the change in the scalar four point function under a special conformal transformation. We can verify this by performing an explicit check. The four point function \( \langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle \) was calculated in [4]. It is given by

\[
\langle \delta \phi(k_{1}) \delta \phi(k_{2}) \delta \phi(k_{3}) \delta \phi(k_{4}) \rangle = \int [\mathcal{D}\delta \phi] \delta \phi(k_{1}) \delta \phi(k_{2}) \delta \phi(k_{3}) \delta \phi(k_{4}) P[\delta \phi],
\]

where \( P[\delta \phi] \) is the probability distribution function

\[
P[\delta \phi] = \int [\mathcal{D}\gamma_{ij}] \left| \Psi[\delta \phi, \gamma_{ij}] \right|^2.
\]

An explicit expression for \( P[\delta \phi] \) was obtained starting from the wave function, eq.(5.4), in eq.(5.3) of [4]. It is given by

\[P[\delta \phi] = \exp \left[ \frac{M_{Pl}^2}{\hbar^2} \left( - \int \frac{d^3k_{1}}{(2\pi)^3} \delta \phi(k_{1}) \delta \phi(k_{2}) \left( O(-k_{1})O(-k_{2}) \right) \right) \right.
\]

\[+ \sum_{j=1}^{4} \int \frac{d^3k_{j}}{(2\pi)^3} \delta \phi(k_{j}) \left( \sum_{j=1}^{4} \frac{1}{2} \left( O(-k_{1})O(-k_{2}) \hat{T}_{ij}^l(k_{1} + k_{2}) \right) + \left( O(-k_{1})O(-k_{2}) \hat{T}_{ij}^l(k_{3} + k_{4}) \right) \right) \]

\[\left. + \frac{1}{2} \left( O(-k_{1})O(-k_{2}) \hat{T}_{ij}^l(k_{1} + k_{2}) \right) \left( O(-k_{3})O(-k_{4}) \hat{T}_{kl}^l(k_{3} + k_{4}) \right) \right] \right].
\]

From eq.(5.22) and eq.(5.24), we see that the four point function has two types of contributions,

\[
\langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle = \langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle_{CF} + \langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle_{ET}.
\]

\[\text{In [4], the term } \langle \hat{T}_{kl}O \rangle \text{ in the wave function appeared with a coefficient } 1/4 \text{ (see eq(2.36) of [4]). But in the present work we choose to have a } 1/2, \text{ which means we need to consistently replace}
\]

\[
\langle \hat{T}_{kl}O \rangle_{\text{here}} \rightarrow 2 \langle \hat{T}_{kl}O \rangle_{\text{here}}
\]

while using expressions from [4].
Here, \( \langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle_{CF} \) is the term proportional to \( \langle OOOO \rangle \),

\[
\langle \delta \phi(k_1) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \rangle_{CF} = \frac{1}{8} \frac{H^6}{M_P^6} \frac{1}{\prod_{a=1}^{4} k_a^3} \langle O(k_1)O(k_2)O(k_3)O(k_4) \rangle,
\]

and \( \langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle_{ET} \) is the term proportional to \( \langle OOT_{ij}' \rangle \langle OO \rangle \),

\[
\langle \delta \phi(k_1) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \rangle_{ET} = \frac{1}{4} \frac{H^6}{M_P^6} \frac{1}{\prod_{a=1}^{4} k_a^3} \left[ I(k_1, k_2, k_3, k_4) + I(k_1, k_3, k_2, k_4) + I(k_1, k_4, k_3, k_2) + I(k_1, k_2, k_1, k_4) \right. \\
\left. + I(k_2, k_4, k_3, k_1) + I(k_3, k_4, k_1, k_2) \right] \tag{5.27}
\]

where \( I(k_1, k_2, k_3, k_4) \) is given in eq.(E.13) of [4],

\[
I(k_1, k_2, k_3, k_4) = \int \frac{d^3k_5}{(2\pi)^3} \frac{d^3k_6}{(2\pi)^3} \frac{\langle \hat{T}_{ij}(k_5)\hat{T}_{kl}(k_6) \rangle}{k_5^2 k_6^2} \langle O(k_1)O(k_2)\hat{T}_{ij}(k_5) \rangle \langle O(k_3)O(k_4)\hat{T}_{kl}(k_6) \rangle. \tag{5.28}
\]

Now, the term \( \langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle_{CF} \) is invariant under a special conformal transformation, whereas the term \( \langle \delta \phi \delta \phi \delta \phi \delta \phi \rangle_{ET} \) does change. We therefore have

\[
\left[ \sum_{a=1}^{4} \hat{L}_{\frac{b}{k_a}}^b \right] \langle \delta \phi(k_1) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \rangle = \left[ \sum_{a=1}^{4} \hat{L}_{\frac{b}{k_a}}^b \right] \langle \delta \phi(k_1) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \rangle_{ET}. \tag{5.29}
\]

As discussed in appendix (E.2) of [4], we have

\[
\left[ \sum_{a=1}^{4} \hat{L}_{\frac{b}{k_a}}^b \right] \langle \delta \phi(k_1) \delta \phi(k_2) \delta \phi(k_3) \delta \phi(k_4) \rangle_{ET} = \frac{1}{4} \frac{H^6}{M_P^6} \frac{1}{\prod_{a=1}^{4} k_a^3} \left[ \delta^C I(k_1, k_2, k_3, k_4) + \delta^C I(k_1, k_3, k_2, k_4) + \delta^C I(k_1, k_4, k_3, k_2) + \delta^C I(k_1, k_2, k_1, k_4) \right. \\
\left. + \delta^C I(k_2, k_4, k_3, k_1) + \delta^C I(k_3, k_4, k_1, k_2) \right], \tag{5.30}
\]

with \( \delta^C I(k_1, k_2, k_3, k_4) \) given in eq.(E.23) of [4],

\[
\delta^C I(k_1, k_2, k_3, k_4) = 12b_m \int \frac{d^3k}{(2\pi)^3} \frac{P_{mkl}(k)}{k^5} k_j \langle O(k_1)O(k_2)\hat{T}_{ij}(k) \rangle \langle O(k_3)O(k_4)\hat{T}_{kl}(-k) \rangle. \tag{5.31}
\]

By using the Ward identity eq.(3.8) of [4] expressed in momentum space,

\[
k_j \langle \hat{T}_{ij}(k)\langle O(k'_1)O(k'_2) \rangle \rangle = \frac{1}{2} \left( k'_2 \langle O(k'_1 + k)O(k'_2) \rangle + k'_1 \langle O(k'_2 + k)O(k'_1) \rangle \right), \tag{5.32}
\]

we can calculate the RHS of eq.(5.30). This gives the result eq.(5.21) for the change in the four point function, and completes the check.
Late Time Behaviour of Modes

In this section, we elaborate on the late time behaviour of modes in the canonical model of slow roll inflation and also after including higher derivative terms in the action.

6.1 The Canonical Model of Slow Roll Inflation

We have discussed in section 2 that one can use the residual time reparametrization invariance, eq.(2.10), in the gauge eq.(2.2), to set $\delta \phi = 0$, and that the remaining perturbations all become time independent in this gauge, at late times. Here we demonstrate this behaviour explicitly in the canonical slow roll model of inflation. The behaviour in the presence of higher derivative terms is discussed in section 6.2.

The action for the canonical model of slow roll inflation is given by

$$ S = M_{Pl}^2 \int d^4x \sqrt{-g} \left( \frac{1}{2} R - \frac{1}{2} (\nabla \phi)^2 - V(\phi) \right). \quad (6.1) $$

In the canonical model, the Hubble parameter eq.(2.4) is given by

$$ H^2 = \frac{V}{3}. \quad (6.2) $$

The background $\bar{\phi}(t)$ satisfies the equation of motion

$$ \ddot{\bar{\phi}} + 3H \dot{\bar{\phi}} + V'(\bar{\phi}) = 0, \quad (6.3) $$

which in the slow roll approximation reduces to

$$ \dot{\bar{\phi}} \approx -\frac{V'}{3H}, \quad (6.4) $$

where $a'$ denotes a derivative with respect to the scalar field. Using eq.(6.2) and eq.(6.4), the slow roll parameters $\epsilon_1$, $\delta$ and $\epsilon$, defined in eq.(3.4), eq.(3.5) and eq.(3.6), can be expressed as

$$ \epsilon_1 = \epsilon = \frac{1}{2} \left( \frac{V'}{V} \right)^2, \quad \delta = \epsilon_1 - \frac{V''}{V}. \quad (6.5) $$

The slow roll conditions, eq.(3.8), are

$$ \left( \frac{V'}{V} \right)^2 \ll 1, \quad \frac{V''}{V} \ll 1. \quad (6.6) $$

For the purpose of convenience in calculations, it is helpful to further decompose the metric perturbation $\gamma_{ij}$, eq.(2.5), as follows

$$ \gamma_{ij} = [A \delta_{ij} + \partial_i \partial_j B + \partial_i C_j + \partial_j C_i + D_{ij}], \quad (6.7) $$

where $A, B$ transform as scalars, $C_i$ transforms like a 3-vector and $D_{ij}$ transforms as a rank-2 tensor under spatial rotations. Note that the perturbation $C_i$ is divergence-less, and
$D_{ij}$ is transverse and traceless,
\[ \partial_i C_i = 0, \partial_i D_{ij} = 0, \ D_{ii} = 0. \] (6.8)

The Einstein equations to linear order in the perturbations about the FRW inflationary background are given by (see appendix C)\(^7\)
\[ - V'(\bar{\phi}) \delta \phi = \frac{1}{2a^2} \nabla^2 A - \frac{1}{2} \ddot{\bar{A}} - 3 \left( \frac{\dot{a}}{a} \right) \dot{\bar{A}} - \frac{1}{2} \left( \frac{\dot{a}}{a} \right) \nabla^2 \ddot{B}, \] (6.9)
\[ 0 = A - a^2 \ddot{B} - 3a \dot{a} \dot{B}, \] (6.10)
\[ - \dot{\bar{A}} \delta \phi = \ddot{A}, \] (6.11)
\[ - \left( 2 \dot{\bar{\phi}} \delta \phi - V'(\bar{\phi}) \delta \phi \right) = \frac{3}{2} \ddot{\bar{A}} + 3 \left( \frac{\dot{a}}{a} \right) \dot{\bar{A}} + \frac{1}{2} \nabla^2 \ddot{B} + \left( \frac{\dot{a}}{a} \right) \nabla^2 \ddot{B}, \] (6.12)
for the scalar perturbations $A, B, \delta \phi$. The vector perturbations $C_i$ satisfy the equation
\[ \nabla^2 \dot{C}_i = 0. \] (6.13)

For the tensor perturbations $D_{ij}$ we get
\[ \ddot{D}_{ij} + 3 \left( \frac{\dot{a}}{a} \right) \dot{D}_{ij} - \frac{1}{a^2} \nabla^2 D_{ij} = 0. \] (6.14)

The equation of motion for $\delta \phi$ is
\[ \delta \ddot{\phi} + 3 \left( \frac{\dot{a}}{a} \right) \dot{\delta \phi} + V''(\bar{\phi}) \delta \phi - \frac{1}{a^2} \nabla^2 \delta \phi = - \frac{1}{2} \dot{\phi} \left( 3 \ddot{\bar{A}} + \nabla^2 \ddot{B} \right). \] (6.15)

Eq.(6.10) can be used to solve for $B$ in terms of $A$,
\[ B(t, x) = \int^t dt' \frac{1}{a(t')} \left( G_1(x) + \int^t dt'' a(t'') A(t'', x) \right) + G_2(x), \] (6.16)
where $G_1, G_2$ are arbitrary functions of $x$.

The late time behaviour of these equations can be obtained by dropping all spatial derivatives of the form $\nabla^2/a^2$ in eqs.(6.9), (6.14) and (6.15). In addition, due to the $1/a^3$ pre-factor in eq.(6.16), we get that
\[ B(t, x) \approx G_2(x) \text{ for } t \to \infty, \] (6.17)
so that all time derivatives of $B$ vanish at late times. Equations (6.9), (6.12) and (6.14) then simplify to
\[ V'(\bar{\phi}) \delta \phi = \frac{1}{2} \ddot{\bar{A}} + 3 \left( \frac{\dot{a}}{a} \right) \dot{\bar{A}}, \] (6.18)

\(^7\)For brevity, we present the equations in units with $M_{\text{Pl}}^2 = \frac{1}{8\pi G} = 1$. 

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\[
- \left(2 \dot{\phi} \delta \dot{\phi} - V'(\bar{\phi}) \delta \phi \right) = \frac{3}{2} \ddot{A} + 3 \left(\frac{\dot{a}}{a} \right) \dot{A}, \quad (6.19)
\]

\[
\ddot{D}_{ij} + 3 \left(\frac{\dot{a}}{a} \right) \dot{D}_{ij} = 0, \quad (6.20)
\]

and eq. (6.15) becomes

\[
\delta \ddot{\phi} + 3 \left(\frac{\dot{a}}{a} \right) \delta \dot{\phi} + V''(\bar{\phi}) \delta \phi + \frac{3}{2} \dot{\phi} \dot{A} = 0. \quad (6.21)
\]

As discussed in appendix C, the late time behaviour for \(A, \delta \phi\) is

\[
A(t, \mathbf{x}) = P_1(\mathbf{x}) - 2 \left(\frac{\dot{a}}{a} \right) P_2(\mathbf{x}), \quad (6.22)
\]

and

\[
\delta \phi(t, \mathbf{x}) = -\dot{\phi}(t) P_2(\mathbf{x}), \quad (6.23)
\]

where \(P_1, P_2\) are time independent functions of \(\mathbf{x}\). Also, the perturbations \(C, D_{ij}\) become time independent.

We can now carry out a time reparametrization

\[
t \to t + P_2(\mathbf{x}), \quad (6.24)
\]

along with the accompanying spatial reparametrization, eq. (2.11), which maintains the gauge choice eq. (2.2). Note that under the time reparametrization eq. (2.10), and the accompanying spatial reparametrization eq. (2.11), the perturbations change as

\[
\delta A = 2 \left(\frac{\dot{a}}{a} \right) \epsilon(\mathbf{x}), \quad (6.25)
\]

\[
\delta B = 2 \epsilon(\mathbf{x}) \int \frac{dt'}{a^2(t')}, \quad (6.26)
\]

\[
\delta C_i = 0, \quad (6.27)
\]

\[
\delta D_{ij} = 0, \quad (6.28)
\]

\[
\delta (\delta \phi) = \dot{\phi} \epsilon(\mathbf{x}). \quad (6.29)
\]

We see from eq. (6.23) and eq. (6.29) that the change eq. (6.24) sets the late time value of \(\delta \phi\) to vanish. In addition, using eq. (6.25) we see that the value of \(A\) is given by

\[
A \to A' = P_1(\mathbf{x}), \quad (6.30)
\]

while \(C, D_{ij}\) are unchanged and therefore continue to be time independent. \(B\) is changed by the the time reparametrization eq. (6.24), see eq. (6.26), but this change vanishes at late times, and thus \(B\) too continues to be time independent. Thus, we see that in the gauge
\( \delta \phi = 0 \) all the perturbations freeze out at late times \(^8\).

### 6.2 Higher Derivative Corrections

In the discussion above, we have considered the canonical model of slow roll inflation, with the action in eq. (6.1). The action for this model involves two-derivative terms. One of the main motivations of our work is to be able to use symmetry considerations in more complicated situations where explicit computations or models may be unavailable. An example is the possibility that the Hubble scale \( H \) during inflation is of order the string scale \( M_{st} \), so that higher derivative corrections to eq. (6.1) would be important. Given our limited knowledge of string theory in time dependent situations, explicit models or calculations for such a scenario are not possible today. But a symmetry based analysis should still be possible, as we discuss further in this section.

The more general situation we have in mind is the one with an effective action having higher order terms of the schematic form

\[
S = \frac{1}{16\pi G} \int d^4x \sqrt{-g} \left[ R + \left( \partial \phi \right)^2 - 2V + \frac{R^2}{\Lambda^2} + \frac{R^3}{\Lambda^4} + \frac{\left( \partial \phi \right)^4}{\Lambda^2} + \cdots \right]. \tag{6.31}
\]

The higher derivative terms are important because \( H \sim O(\Lambda) \). In eq. (6.31), \( \Lambda \) is the underlying cutoff scale, which would be of order the string scale \( M_{st} \) in string theory. The term \( R^2/\Lambda^2 \) schematically denotes four derivative terms, and so on. Also, the coefficients of each of the higher order terms can in general be a function of \( \phi \). Let us note that in the background solution the contribution from terms like \( (\partial \phi)^4 \) will be small, since the inflaton will be evolving slowly. However, these terms will be important in determining the behaviour of the perturbations, since the perturbations will start out with physical wavelengths \( \lambda \ll H^{-1} \), and then freeze out at a time when \( \lambda \approx H^{-1} \).

Let us note that \( H \sim O(\Lambda) \) is consistent with the bounds on the tensor perturbations, since \( \Lambda \) can be much smaller than \( M_{pl} \), as indeed happens in weakly coupled string theory. The condition \( \Lambda \ll M_{pl} \) also ensures that all quantum loop effects are small, and it is only tree level effects involving the higher derivative corrections which are important in the kind of scenario we have in mind.

In fact, considerations of the last few sections can be extended in a straightforward way to situations of this type. The crucial point is that even with the higher derivative terms present, one can argue that solutions with the same asymptotic behaviour as in the two-derivative case continue to exist. The underlying reason for this is that the asymptotic behaviour in the two-derivative case follows from gauge invariance. We will discuss this in more detail in the next subsection. Given this fact, the arguments leading to the Ward identities can be easily seen to apply in cases with higher derivative corrections as well. A further change of coordinates allows us to set \( \delta \phi \) to vanish, as discussed in section 2, and

---

\(^8\)The perturbations \( \zeta, \bar{\gamma}_{ij} \), which appear in section 2 and the discussion thereafter, are given by

\[
\zeta = \frac{1}{2} A + \frac{1}{6} \nabla^2 B, \quad \text{and} \quad \bar{\gamma}_{ij} = D_{ij} + \partial_i C_j + \partial_j C_i + \partial_i \partial_j B - \frac{1}{3} \delta_{ij} \nabla^2 B.
\]
the invariance of the wave function under the residual spatial reparametrizations in the synchronous gauge then leads to the Ward identities of interest.

### 6.2.1 Freezing of the Perturbations

We start with a discussion of the spin-2 component $D_{ij}$, eq.(6.7), which corresponds to gravity waves. In the two-derivative theory it satisfies the eq.(6.14). At late times, when $k^2/a^2$ becomes sufficiently small, this becomes eq.(6.20), which has the general solution eq.(C.18). In particular, $D_{ij}$ becomes time independent, satisfying eq.(C.19), since the additional solution proportional to $K_{ij}$ in eq.(C.18) dies out as $t \to \infty$. Higher derivative terms would result in contributions to the equation of motion with either additional spatial derivatives, and/or additional time derivatives. All terms with spatial derivatives will become small, since the physical wavelength $\lambda$ for fixed $k$ becomes large at late times. Thus the only terms which survive will have additional time derivatives. It is then clear that the solution eq.(C.19) will continue to hold even when higher derivative corrections are included.

However, in the presence of higher derivative terms there could be additional solutions which do not die out at large $t$. We will assume that the correct boundary conditions in the far past are such that any such solution is not “turned on” in the far future, leading to eq.(C.19).

Exponentially growing solutions would signify an instability. Our assumption that they are absent is consistent with the background inflationary solution being stable. There could be additional oscillatory solutions though, which are non-decaying. We cannot rule these out except by appealing to the initial conditions. However, the following possibility is worth mentioning in this context. The additional oscillatory solutions might be present if the higher derivative corrections in eq.(6.31) arise in the first place by integrating out massive particles with a mass $\sim \mathcal{O}(\Lambda)$. This could happen in an underlying theory where all particles, the massive ones and the graviton, satisfy second order equations of motion, leading to a well posed initial value problem. In this case, the graviton will indeed have the solution discussed above, eq.(C.19), with a second solution which decays, eq.(C.18). If $\Lambda \sim H$, these additional particles would also be produced during inflation, with a suitable Boltzmann suppression. However, the Ward identities we derive in section 3 will continue to hold in this case as well. The wave function in the presence of these fields will continue to be invariant under spatial reparametrizations, and thus after integrating these heavy fields out, eq.(3.9), the same Ward identities will follow for $\zeta$ and $\hat{\gamma}_{ij}$.

The discussion for spin-1 is even more straightforward. The solution found in the two-derivative case is pure gauge, since there are no physical degrees of freedom with spin 1. Starting from the unperturbed solution of the form eq.(2.3), and carrying out a spatial reparametrization

$$x^i \to x^i + \epsilon^i(x), \quad (6.32)$$

one gets

$$C_i = \epsilon_i - \partial_i \partial^{-2}(\partial \cdot \epsilon), \quad (6.33)$$

so that the most general time independent $C_i$ can be turned on with a suitable choice of $\epsilon^i(x)$. This makes it clear that a solution of the form eq.(C.17) must continue to exist in
the presence of higher derivative terms too.

Finally we come to the scalar perturbations. In the two-derivative theory, the late time behaviour for solutions was found to be eq. (6.22), eq. (6.17) and eq. (6.23), for $A, B$ and $\delta \phi$ respectively. We now argue, in analogy with the case of spin-1 above, that the existence of solutions exhibiting this behaviour follows from spatial and time reparametrizations which preserve the synchronous gauge eq. (2.2). Starting from eq. (2.3) and doing the transformation eq. (6.32) gives

$$B = 2 \partial^{-2}(\partial \cdot \epsilon),$$

so that the most general time independent $B$ can be turned on. Also, starting from eq. (2.3) and carrying out a transformation

$$x^i \rightarrow x^i (1 + \epsilon),$$

where $\epsilon$ is a constant, gives

$$A = 2 \epsilon.$$  \hspace{1cm} (6.36)

The late time behaviour of $A$ with higher derivative terms will still be determined by an equation where all spatial derivatives can be dropped. The solution eq. (6.36) then means that actually

$$A \rightarrow P_1(x)$$

will be a solution to the small perturbation equations.

Finally, doing the time reparametrization eq. (2.10) gives rise to the solution

$$A = 2H \epsilon(x), \delta \phi = \dot{\phi} \epsilon(x).$$

Putting all these solutions together, we get the general late time behaviour seen in eq. (6.22), eq. (6.17) and eq. (6.23).

Since these solutions in the spin-0 case arise just from gauge invariance, they will continue to be true even in the presence of the higher derivative terms. As in the case of the spin-2 mode, there could as well be additional solutions which do not decay, but we will assume that they are either not turned on due to the initial conditions, or are of oscillatory type arising due to additional massive particles, which do not invalidate the arguments for the Ward identities.

7 Conclusions

In this paper, we have derived the Ward identities that arise from scale and special conformal transformations for single field inflation. Our results are given in eq. (3.25) and eq. (3.38) for the scalar perturbations, and eq. (3.27) and eq. (3.41) for the tensor perturbations. Similar results for mixed correlators can also be easily obtained, see eq. (3.28) and eq. (3.44).

The Ward identities for the special conformal transformations also involve a contribution due to a compensating spatial reparametrization, as explained in section 3.2. The underlying reason for this is that we are working with local correlators in a quantum theory
of gravity. Such correlators can be defined in perturbation theory after suitable gauge fixing, but a compensating spatial reparametrization must then be carried out to preserve the gauge, for deriving the Ward identities of special conformal transformations [4]. The Ward identities for scale invariance do not require such a compensating transformation and are well known in the literature already, [1], and called the Maldacena consistency conditions.

The Ward identities we obtain also incorporate the breaking of the $SO(1, 4)$ symmetry. In fact, this breaking is incorporated to all orders in the slow roll parameters. The resulting relations can be thought of as being the analogues of the Callan-Symanzik equation, but now for both scale and special conformal transformations.

When the slow roll conditions are approximately valid, the Ward identities impose useful constraints on the correlation functions. The coefficient functions which appear in the wave function, and which transform in a manner analogous to correlation functions in a conformal field theory, can then be constrained order by order in the slow approximation, and the resulting constraints on the expectation values, in agreement with the Ward identities, can then be obtained. For the scalar three point function, which is observationally the most important one for non-Gaussianity, this was discussed in [5].

We work in a theory where the degrees of freedom are the metric and a scalar field. However, it is worth emphasizing that our results are also valid in situations where there are extra massive fields present during inflation, with masses of order the Hubble scale, or even higher. The wave function in the presence of such fields must still meet the equations of motion imposed by varying the shift and lapse functions, and thus must be invariant under the spatial reparametrizations discussed in section 4.1, in the gauge eq. (2.17) at late times. As a result, after the heavy fields are integrated out in deriving the expectation values for $\zeta$ and $\hat{\gamma}_{ij}$, in the step analogous to eq. (3.9), the same Ward identities as before, eq. (3.25), eq. (3.27), eq. (3.38) and eq. (3.41) are obtained.

In contrast, our results are not valid when there are additional scalar fields which are much lighter than the Hubble scale, as in multi-field models of inflation. In this case, it is well known that the results are model dependent, and do not follow just from the underlying symmetries.

It will be worth examining the Ward identities of scale and special conformal transformations also in situations where the conformal symmetries are badly broken. This happens, for instance, in DBI inflation [42], [43]. It can also happen if the initial state is not the Bunch-Davies vacuum, and breaks the conformal symmetries to a significant extent.

In the context of AdS physics, space-times where conformal symmetry is broken are important in the study of condensed matter physics and QCD. Examples include Lifshitz and hyperscaling violating geometries. The Ward identities for the stress tensor etc. can be obtained in such situations in a way completely analogous to what we have used above. Some discussion of the identities in such situations can be found in [44].

**The Scalar Three-Point Function:** Since the scalar three point function is of the greatest interest as a test of non-Gaussianity, let us end by commenting on it in some more detail. The Ward identities of interest here are eq. (3.25) and eq. (3.38) for $n = 3$, and relate the scalar 3 and 4 point correlators. These Ward identities were studied to the leading order in the slow roll expansion in [5]. The resulting relations in terms of coefficient functions are
given in eq.(3.24) and eq.(3.25) of [5],
\[
\left( \sum_{a=1}^{3} k_a \cdot \frac{\partial}{\partial k_a} \right) \langle O(k_1)O(k_2)O(k_3) \rangle = \left. \frac{\dot{\phi}}{H} \langle O(k_1)O(k_2)O(k_3)O(k_4) \rangle \right|_{k_4 \to 0}, \tag{7.1}
\]
and
\[
\mathcal{L}^b_{k_1} \langle O(k_1)O(k_2)O(k_3) \rangle' + \mathcal{L}^b_{k_2} \langle O(k_1)O(k_2)O(k_3) \rangle' + \mathcal{L}^b_{k_3} \langle O(k_1)O(k_2)O(k_3) \rangle' = 2 \frac{\dot{\phi}}{H} \left. \left\{ \langle O(k_1)O(k_2)O(k_3)O(k_4) \rangle' \right\} \right|_{k_4 \to 0}, \tag{7.2}
\]
with $\mathcal{L}^b_k$ defined in eq.(4.22). Note that in the leading slow roll approximation, the four point coefficient function $\langle OOOO \rangle$ can be calculated in the conformally invariant limit [4]. As a result of the factor of $\dot{\phi}$ on the RHS of eq.(7.1) and eq.(7.2), the three point function $\langle OOO \rangle$ will be suppressed. Converting to expectation values, one gets that
\[
\frac{\langle \zeta \zeta \zeta \rangle}{\langle \zeta \zeta \rangle^2} \sim \epsilon, \tag{7.3}
\]
where the slow roll parameter $\epsilon$ is given in eq.(3.6). Although the functional form one will get in general is different, this roughly corresponds to
\[
f_{NL} \sim \epsilon. \tag{7.4}
\]

It is well known that the parameter $r$ which measures the ratio of the power in the tensor to scalar perturbations is given by
\[
r \equiv \frac{P_t(k)}{P_\zeta(k)} = 16 \epsilon. \tag{7.5}
\]

Note that in theories which are not of the type described by a canonical model of inflation, eq.(6.1), e.g., those involving higher derivative corrections, $\epsilon_1$ and $\epsilon$ as defined in eq.(3.4) and eq.(3.6) need not be the same. In these theories also, eq.(7.3) with the definition of $\epsilon$ given in eq.(3.6) is still valid to leading order in the slow roll parameters. We see from eq.(7.4) and eq.(7.5) that there is therefore an interesting tie-in between the ratio of power in the scalar and tensor perturbations, and the non-Gaussianity. This connection is well known in the canonical slow roll models, but we see here that it is more general, since eq.(7.4) follows from symmetry considerations alone.

The estimate in eq.(7.3) should actually be thought of as a lower bound. A contribution due to an intermediate graviton (or the stress energy tensor running as an intermediate in the $\langle OOOO \rangle$ correlator) will give a contribution of this order to the non-Gaussianity.

\[9\text{The tensor and scalar power spectra } P_t(k), P_\zeta(k) \text{ are}
\]
\[
P_t(k) = \frac{H^2}{M_{Pl}^2} \frac{4}{k^3}, \text{ and } P_\zeta(k) = \frac{H^2}{M_{Pl}^2} \frac{1}{\epsilon} \frac{1}{4k^3}.
\]
However, as has been emphasized in [45], if there are additional particles of mass of order the Hubble scale which couple more strongly than the graviton, the contribution can be even bigger 10.

Keeping the above considerations in mind we can phrase this tie-in between the two scales as follows. If tensor perturbations are observed in the future, so that $\epsilon$ is known, we would have a firm prediction on a lower bound on non-Gaussianity that follows only from conformal invariance. On the other hand, if the non-Gaussianity is observed and found to be of a bigger magnitude than the bound on $\epsilon$ that arises from constraints on the tensor perturbations, eq.(7.5), then it would rule out the scenario of approximate conformal invariance. More correctly, it will rule out this scenario together with the assumption that particles which appear as intermediate states, and contribute to the non-Gaussianity, couple to the inflaton only with gravitational strength.

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A Transformation of Perturbations under Spatial Reparametrizations

In this appendix, we would like to give some details about the transformation properties of the perturbations under spatial reparametrizations. We consider the perturbed line element in the gauge eq.(2.2),

$$ds^2 = - dt^2 + h_{ij}(t, x) dx^idx^j,$$

(A.1)

with

$$h_{ij} \equiv a^2(t) g_{ij} = a^2(t) e^{2\zeta} [\delta_{ij} + \hat{\gamma}_{ij}],$$

(A.2)

where

$$\hat{\gamma}_{ii} = 0.$$  

(A.3)

Consider now a spatial reparametrization of the form eq.(2.7). The change in $h_{ij}$ under this transformation is

$$\delta h_{ij} = \nabla_i v_j + \nabla_j v_i.$$  

(A.4)

10Similarly, in theories where conformal invariance is violated to a significant extent, the non-Gaussianity can be bigger, e.g. in DBI inflation.
Eq. (A.4) implies
\[
\delta g_{ij} = \frac{1}{a^2(t)} \left[ \partial_i v_j + \partial_j v_i - 2 \Gamma^a_{ij} v_a \right]
\]
\[= \frac{1}{a^2(t)} \left[ \partial_i \left( h_{jk} v^k \right) + \partial_j \left( h_{ik} v^k \right) - v_a h^{ab} \left( \partial_i h_{jb} + \partial_j h_{ib} - \partial_b h_{ij} \right) \right] \tag{A.5}
\]
\[= g_{jk} \partial_i v^k + g_{ik} \partial_j v^k + v^k \partial_k g_{ij}, \]
where indices will now be raised and lowered by $\delta_{ij}$. Eq. (A.5) gives us
\[
\delta g_{ii} = 2 g_{ik} \partial_i v^k + v^k \partial_k g_{ii}. \tag{A.6}
\]
Putting $g_{ij}$ from eq. (A.2) in eq. (A.6) gives the change in $\zeta$ under spatial reparametrizations, eq. (2.7), as
\[
\delta \zeta = \frac{1}{3} \partial_i v_i + v^k \partial_k \zeta + \frac{1}{3} \partial_i v_j \hat{\gamma}_{ij}, \tag{A.7}
\]
which is the result quoted in eq. (4.1). Once we have calculated $\delta \zeta$, we can insert the full $g_{ij}$ in eq. (A.5) to get the change in $\hat{\gamma}_{ij}$ as
\[
\delta \hat{\gamma}_{ij} = \left( \partial_i v_j + \partial_j v_i - \frac{2}{3} \partial_a v_a \delta_{ij} \right) + \left( \hat{\gamma}_{ik} \partial_j v^k + \hat{\gamma}_{jk} \partial_i v^k + v^k \partial_k \hat{\gamma}_{ij} - \frac{2}{3} \partial_a v_a \hat{\gamma}_{ab} \left( \delta_{ij} + \hat{\gamma}_{ij} \right) \right). \tag{A.8}
\]
For simplicity, we call the terms in eqs. (A.7) and (A.8) which are proportional to the perturbations as the homogeneous pieces of the transformation, and the parts independent of the perturbations as the inhomogeneous pieces of the transformation.

Having obtained eq. (A.7) and eq. (A.8), we can calculate the changes $\delta \zeta$ and $\delta \hat{\gamma}_{ij}$ for the specific cases of scale transformations, eq. (3.12), special conformal transformations, eq. (3.29), and the compensating spatial reparametrization, eq. (3.33). For scale transformations, the change in $\zeta$ and $\hat{\gamma}_{ij}$ is given by eq. (3.13) and eq. (3.14) respectively. Similarly, for the special conformal transformations, the changes are given by eq. (3.30) and eq. (3.31), and for the compensating spatial reparametrization, the changes are eq. (3.34) and eq. (3.35).

### B The Scalar and Tensor Spectral Tilts

As a simple check on the Ward identities, we consider here the 2-point correlators. For scalar perturbations, the scaling Ward identity in eq. (3.25) relates the 2-point expectation value to the 3-point expectation value,
\[
\left( 3 + \sum_{a=1}^{2} k_a \frac{\partial}{\partial k_a} \right) \langle \zeta(k_1) \zeta(k_2) \rangle' = - \frac{1}{\langle \zeta(k_3) \zeta(-k_3) \rangle} \langle \zeta(k_1) \zeta(k_2) \zeta(k_3) \rangle' \bigg|_{k_3 \to 0}. \tag{B.1}
\]
The expression for $\langle \zeta(k_1) \zeta(k_2) \rangle$ is

$$
\langle \zeta(k_1) \zeta(k_2) \rangle = (2\pi)^3 \delta^3(k_1 + k_2) \frac{H^2}{M_{Pl}^2} \frac{1}{4\epsilon} k_1^{-3 + n_s}, 
$$

where $n_S$ is the scalar tilt. Thus, we get

$$
\left[ \sum_{a=1}^{2} k_a \frac{\partial}{\partial k_a} \right] \langle \zeta(k_1) \zeta(k_2) \rangle' = (3 - n_S) \langle \zeta(k_1) \zeta(-k_1) \rangle', 
$$

which on substituting back into the eq.(B.1) gives the well-known Maldacena consistency condition

$$
\lim_{k_3 \to 0} \langle \zeta(k_1) \zeta(k_2) \zeta(k_3) \rangle' = -n_S \langle \zeta(k_1) \zeta(-k_1) \rangle' \langle \zeta(k_3) \zeta(-k_3) \rangle'. 
$$

By using the expression for $\langle \zeta(k_1) \zeta(k_2) \zeta(k_3) \rangle$ from [1], we get\footnote{The slow roll parameter \( \eta \) is given by \( \eta \equiv \epsilon - \delta = \frac{3V''}{V'} \).}

$$
\lim_{k_3 \to 0} \langle \zeta(k_1) \zeta(k_2) \zeta(k_3) \rangle' = (6\epsilon - 2\eta) \langle \zeta(k_1) \zeta(-k_1) \rangle' \langle \zeta(k_3) \zeta(-k_3) \rangle'. 
$$

Putting the limit from eq.(B.5) into eq.(B.4) gives the expression for the scalar tilt as

$$
n_S = 2\eta - 6\epsilon, 
$$

which is indeed the correct expression, [1].

Similarly, consider the tensor Ward identity in eq.(3.27), with $n = 2$. This has the form

$$
\left( 3 + \sum_{a=1}^{2} k_a \frac{\partial}{\partial k_a} \right) \langle \tilde{\gamma}_s(k_1) \tilde{\gamma}_{s'}(k_2) \rangle' = -\frac{1}{\langle \zeta(k_3) \zeta(-k_3) \rangle'} \langle \tilde{\gamma}_s(k_1) \tilde{\gamma}_{s'}(k_2) \zeta(k_3) \rangle' \bigg|_{k_3 \to 0}. 
$$

In writing eq.(B.7), we have introduced the two polarization tensors for the graviton, $\epsilon^s_{ij}$, through the relation

$$
\tilde{\gamma}_{ij}(k) = \sum_{s=1}^{2} \epsilon^s_{ij}(k) \tilde{\gamma}_s(k). 
$$

Now, the expression for $\langle \tilde{\gamma}_s(k_1) \tilde{\gamma}_{s'}(k_2) \rangle$ has the form

$$
\langle \tilde{\gamma}_s(k_1) \tilde{\gamma}_{s'}(k_2) \rangle = (2\pi)^3 \delta^3(k_1 + k_2) \delta_{s,s'} \frac{H^2}{M_{Pl}^2} k_1^{-3 + n_T}, 
$$

where $n_T$ is the tensor tilt. By using the expression eq.(B.9) in eq.(B.7), we get

$$
\lim_{k_3 \to 0} \langle \tilde{\gamma}_s(k_1) \tilde{\gamma}_{s'}(k_2) \zeta(k_3) \rangle' = -n_T \delta_{s,s'} \langle \tilde{\gamma}_s(k_1) \tilde{\gamma}_s(-k_1) \rangle' \langle \zeta(k_3) \zeta(-k_3) \rangle'. 
$$

We can calculate the limit on the left side of eq.(B.10) by using the expression for the
correlator $\langle \hat{\gamma}_s(k_1)\hat{\gamma}_{s'}(k_2)\zeta(k_3) \rangle$ from [1]. This gives

$$
\lim_{k_3 \to 0} \langle \hat{\gamma}_s(k_1)\hat{\gamma}_{s'}(k_2)\zeta(k_3) \rangle' = 2\epsilon \delta_{s,s'} \langle \hat{\gamma}_s(k_1)\hat{\gamma}_{s}(-k_1) \rangle' \langle \zeta(k_3)\zeta(-k_3) \rangle'.
$$

(B.11)

Then by comparing eq.(B.10) and eq.(B.11), we get

$$
n_T = -2\epsilon,
$$

(B.12)

which is the correct expression for the tensor tilt.

C The Behaviour of Perturbations in Canonical Slow Roll

In this appendix, we provide some details of the analysis given in section 6.1. We follow [41] for our calculations. Our gauge choice, eq.(2.2), is same as the synchronous gauge of [41] (see section 5.3 (B)). The relevant equations are eqs.(5.3.28)-(5.3.33) for scalar perturbations, eq.(5.1.51) for vector perturbations, and eq.(5.1.53) for tensor perturbations.

The energy-momentum tensor for the inflaton can be calculated by varying the matter part of the action (6.1) with respect to the metric. It is given by

$$
T^{\mu\nu} = -g^{\mu\nu} \left( \frac{1}{2} (\nabla \phi)^2 + V(\phi) \right) + g^{\mu\alpha} g^{\nu\beta} \partial_\alpha \phi \partial_\beta \phi.
$$

(C.1)

This has the form of the energy-momentum tensor for a perfect fluid,

$$
T^{\mu\nu} = (\rho + P) u^\mu u^\nu + P g^{\mu\nu},
$$

(C.2)

with the energy density $\rho$, pressure $P$, and the four-velocity $u^\mu$ given by

$$
\rho = -\frac{1}{2} (\nabla \phi)^2 + V(\phi),
$$

(C.3)

$$
P = -\frac{1}{2} (\nabla \phi)^2 - V(\phi),
$$

(C.4)

$$
u^\mu = -[-(\nabla \phi)^2]^{-1/2} g^{\mu\nu} \partial_\nu \phi.
$$

(C.5)

For our purpose, we specialize to the case of single field slow roll inflation. We then have

$$
\bar{\rho} = \frac{1}{2} \dot{\bar{\phi}}^2 + V(\bar{\phi}),
$$

(C.6)

$$
\bar{P} = \frac{1}{2} \dot{\bar{\phi}}^2 - V(\bar{\phi}),
$$

(C.7)

$$
\bar{u}^0 = 1, \bar{u}^i = 0,
$$

(C.8)

for the homogeneous background $\bar{\phi}(t)$. By expanding eqs.(C.3)-(C.5) to linear order in the perturbation $\delta \phi$, we get

$$
\delta \rho = \dot{\bar{\phi}} \delta \phi + V'(\bar{\phi}) \delta \phi,
$$

(C.9)
\[ \delta P = \dot{\phi} \delta \dot{\phi} - V'(\bar{\phi}) \delta \phi, \quad (C.10) \]
\[ \delta u = - \frac{\delta \phi}{\bar{\phi}}, \quad (C.11) \]

where \( \delta u \) is defined through \( \delta u_i \equiv \partial_i \delta u + \delta u_V^i \), and \( \delta u_V^i = 0 \) for single field inflation. Also, for single field inflation, the anisotropic stresses in the perturbed energy-momentum tensor vanish,
\[ \pi^S = 0, \quad \pi^V_i = 0, \quad \pi^T_{ij} = 0. \quad (C.12) \]

By using the eqs. (C.6)-(C.12) above in the eqs. (5.3.28)-(5.3.33), eq. (5.1.51) and eq. (5.1.53) of [41], we obtain the perturbed Einstein equations eqs. (6.9)-(6.15) given in section 6.1 for the scalar, vector and tensor perturbations, along with the equation of motion for the background \( \bar{\phi}(t) \), eq. (6.3). Note that the perturbations \( G_j \) in eq. (5.1.51) of [41] vanish due to our gauge choice eq. (2.2).

We now provide some details for calculating the late time behaviour of the perturbations. To solve for the perturbation \( A \), we consider eq. (6.18). Inserting \( \delta \phi \) from eq. (6.11) into eq. (6.18), we get an equation purely for the perturbation \( A \),
\[ \ddot{A} + 2 \left( \frac{\dot{a}}{a} \right) \dot{A} = 0. \quad (C.13) \]

By using the background eq. (6.3) in eq. (C.13), we get
\[ \ddot{A} - 2 \left( \frac{\dot{\bar{\phi}}}{\bar{\phi}} \right) \dot{A} = 0. \quad (C.14) \]

The general solution to eq. (C.14) is
\[ A(t, x) = P_1(x) + P_2(x) \int^t dt' \dot{\bar{\phi}}^2(t'), \quad (C.15) \]

where \( P_1(x), P_2(x) \) are two arbitrary functions of \( x \). Eq. (C.15) on using the background equation
\[ \dot{H} \equiv \frac{d}{dt} \left( \frac{\dot{a}}{a} \right) = - \frac{1}{2} \dot{\bar{\phi}}^2 \quad (C.16) \]

becomes
\[ A(t, x) = P_1(x) - 2 \left( \frac{\dot{a}}{a} \right) P_2(x), \]

which is the solution quoted in eq. (6.22).

Once we have obtained the solution for \( A \), it is straightforward to obtain the solution for the perturbation \( \delta \phi \). From eq. (6.11) and eq. (6.22), it follows that
\[ \delta \phi(t, x) = - \dot{\bar{\phi}}(t) P_2(x), \]

as given in eq. (6.23). One can check explicitly that the solutions eq. (6.22), eq. (6.23) satisfy
the other equations, namely eq. (6.19) and eq. (6.21).

The equation for the perturbation $C_i$, eq. (6.13), has the general solution

$$C_i(t, x) = \partial^{-2} Q_i(x), \quad (C.17)$$

which shows that the perturbation $C_i$ is frozen for non-zero momentum modes, which are the ones of interest to us.

Finally, we consider eq. (6.20) for the tensor perturbations. The general solution is

$$D_{ij}(t, x) = \tilde{D}_{ij}(x) + K_{ij}(x) \int_t^\infty dt' \exp \left[ -3 \int_t^{t'} dt'' \left( \frac{\dot{a}}{a} \right) \right], \quad (C.18)$$

which in the late time limit also gets frozen,

$$D_{ij}(t, x) \approx \tilde{D}_{ij}(x) \text{ for } t \to \infty. \quad (C.19)$$

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