Hot accretion flow with anisotropic viscosity

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ABSTRACT

In extremely low accretion rate systems, the ion mean-free path can be much larger than the gyroradius. Therefore, gas pressure is anisotropic with respect to magnetic field lines. The effects of pressure anisotropy can be modeled by an anisotropic viscosity with respect to magnetic field lines. Angular momentum can be transferred by anisotropic viscosity. In this paper, we investigate hot accretion flow with anisotropic viscosity. We consider the case that anisotropic viscous stress is much larger than Maxwell stress. We find that the flow is convectively unstable. We also find that the mass inflow rate decreases towards a black hole. Wind is very weak; its mass flux is 10−15% of the mass inflow rate. The inward decrease of inflow rate is mainly due to convective motions. This result may be useful to understand the accretion flow in the Galactic Center Sgr A* and M 87 galaxy.

Key words. accretion, accretion disks – black hole physics – hydrodynamics – ISM: jets and outflows – conduction

1. Introduction

Hot accretion flows, such as advection-dominated accretion flows (ADAFs; Narayan & Yi 1994, 1995; Abramowicz et al. 1995) are of great interest because they are likely operating in low-luminosity active galactic nuclei (AGN), that is, the major- ity of galaxies at least in the nearby Universe, hard and quiescent states of black hole X-ray binaries (see Yuan & Narayan 2014, for the latest review). Many numerical simulations have been carried out to study the structure of hot accretion flows (e.g., Igumenschev & Abramowicz 1999, 2000; Stone et al. 1999; Stone & Pringle 2001; Machida et al. 2001; Hawley & Balbus 2002; Pang et al. 2001; Yuan et al. 2012a).

One of the most important findings by numerical simulations in this field is the discovery of strong wind launched from the accretion flow (Yuan et al. 2012b; Narayan et al. 2012; Li et al. 2013; Sadowski et al. 2016). This result was soon confirmed by the 3 million seconds of Chandra observation of the accretion flow around the super massive black hole in the Galactic Center, combined with modeling of the detected iron emission lines (Wang et al. 2013). Begelman (2012) and Gu (2015) analytically address the reason for the existence of wind in hot accretion flows.

In extremely-low-accretion-rate hot accretion flow, such as the accretion flow in the Galactic Center, Sgr A*, and M 87, the Coulomb mean-free path of both ions and electrons is much larger than the typical length-scale of the accretion flow, \( \sim GM/c^2 \) (Mahadevan & Quataert 1997; Foucart et al. 2016), where \( M \equiv \) black hole mass, \( G \equiv \) gravitational constant, and \( c \equiv \) speed of light. At first glance, the plasma is collisionless. However, particle-in-cell simulations of shear flows have shown that the effective collision rate of particles can be increased by wave-particle interactions (Kunz et al. 2014; Hellinger & Trávníček 2015; Riquelme et al. 2015; Sironi & Narayan 2015). This conclusion is supported by measurements in the solar wind, which show that the gas is not totally collisionless (e.g. Kasper et al. 2002; Hellinger et al. 2006; Kulsrud 2004). This is what we shall call the weakly collisional accretion flow. In weakly collisional accretion flow, non-ideal processes such as conduction and pressure anisotropy are likely to be important (Chandra et al. 2015; Foucart et al. 2016).

Previous works (Tanaka & Menou 2006; Johnson & Quataert 2007; Quataert 2008; Parrish & Stone 2005, 2007; Sharma et al. 2008; Bu et al. 2011, 2016; Foucart et al. 2016) have shown that thermal conduction can affect the dynamics of accretion flow significantly. Thermal conduction can transport energy from the inner (hotter) to the outer (cooler) regions. If the energy flux carried by thermal conduction is substantial, the temperature of the gas in the outer regions can be increased above the virial temperature. Thus, gas in the outer regions is able to escape from the gravitational potential of the central black hole and form outflows, significantly decreasing the mass accretion rate. Bu et al. (2016) studied the effects of thermal conduction on wind properties and found that, in the presence of conduction, the energy flux carried by wind (or outflow) can be increased by a factor of \( \sim 10 \).

In weakly collisional accretion flow, pressure parallel to magnetic field is different from that perpendicular to magnetic field (Chandra et al. 2015). Previous works show that anisotropic pressure can affect the properties of accretion flow significantly. For example, if the pressure is anisotropic, the growth rate of magneto-rotational instability (MRI; Balbus & Hawley 1991, 1998) can be increased (Quataert et al. 2002; Sharma et al. 2003).

Recently, studies show that the effects of pressure anisotropy can be modeled by an anisotropic viscosity with respect to magnetic field lines (Balbus 2004; Islam & Balbus 2005; Islam 2014; Chandra et al. 2015; Foucart et al. 2016). Therefore, in weakly collisional accretion flow, even without viscous stress induced by MRI, the angular momentum of gas can be transferred. The
purpose of this paper is to study weakly collisional hot accretion flow. We mainly focus on accretion flow in which anisotropic viscous stress is much larger than Maxwell stress. Especially, we pay attention to a question that whether wind can be produced. We are interested in wind production because wind is not only an important ingredient of accretion physics but also plays an important role in AGN feedback (Ostriker et al. 2010).

In Sect. 2, we present the basic equations and the simulation models. In Sect. 3, we present the main results. We discuss and summarize our results in Sect. 4.

2. Numerical method and models

2.1. Equations

In spherical coordinates (r, θ, φ), we solve the following magneto-hydrodynamic (MHD) equations using ZEUS-2D code (Stone & Norman 1992a, b):

\[
\frac{d\rho}{dt} + \rho \nabla \cdot \mathbf{v} = 0, \quad \frac{d\mathbf{v}}{dt} = -\nabla p + \rho \nabla \Phi + \frac{1}{4 \pi} (\nabla \times \mathbf{B}) \times \mathbf{B} + \nabla \cdot \mathbf{\Pi},
\]

(1)

\[
\rho \frac{d(e/\rho)}{dt} = -\nabla \cdot \mathbf{v} + \Pi \nabla \cdot \mathbf{v} + \eta J^2,
\]

(2)

\[
\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B} - \eta \mathbf{J}),
\]

(3)

where \(\rho\) is density, \(\mathbf{v}\) is velocity, \(p\) is gas pressure, \(e\) is gas internal energy, \(\mathbf{B}\) is magnetic field, \(\mathbf{J} = (c/4\pi \nabla \times \mathbf{B})\) is current density, and \(\Phi\) is gravitational potential. We use pseudo-Newtonian potential (Paczynski & Wiita 1980) to mimic the general relativistic effects, \(\Phi = -GM/(r - R_0)\), where \(R_0 = 2GM/c^2\) is the Schwarzschild radius. We adopt an adiabatic equation of state \(p = (\gamma - 1)e\), and set \(\gamma = 5/3\).

In Eqs. (2) and (3), we use anisotropic viscous stress tensor \(\mathbf{\Pi}\) to model the effects of ion pressure anisotropy (Braginskii 1965):

\[
\mathbf{\Pi} = -3\nu \left[ \frac{\mathbf{b} \cdot \nabla \mathbf{v} - \frac{\nabla \cdot \mathbf{v}}{3}}{3} \right] \left[ \mathbf{b} b^\perp - \frac{1}{3} I \right],
\]

(5)

where \(\mathbf{b} = \mathbf{B}/|\mathbf{B}|\) is a unit vector in the direction of magnetic field, and \(I\) is the unit tensor. The viscous stress can be written as

\[
\Delta \mathbf{P} = -3\nu \left[ \frac{\mathbf{b} \cdot \nabla \mathbf{v} - \frac{\nabla \cdot \mathbf{v}}{3}}{3} \right] = \mathbf{P}_b - \mathbf{P}_s,
\]

(6)

where \(\mathbf{P}_b = \mathbf{P} + \Delta \mathbf{P}_b\) is pressure along magnetic field line and \(\mathbf{P}_s = \mathbf{P} + \Delta \mathbf{P}_s\) is pressure perpendicular to magnetic field line, in which \(\Delta \mathbf{P}_s\) are deviations from \(\mathbf{P}\) in the directions along and perpendicular to magnetic field, respectively. \(\Delta \mathbf{P}_b\) and \(\Delta \mathbf{P}_s\) vary with time and give rise to a shear viscosity and a bulk viscosity, respectively. Chandra et al. (2015) show that there is a relation between \(\Delta \mathbf{P}_b\) and \(\Delta \mathbf{P}_s\). The relation is that \(\Delta \mathbf{P}_b = -2\Delta \mathbf{P}_s\). The magnitude of shear viscosity and bulk viscosity is comparable, so we use the same coefficient for both shear and bulk viscosity. In Eq. (6), \(\nu\) is viscous coefficient, we adopt \(\nu = \phi c_s^2/r_\mathbf{k}\) (Foucart et al. 2016), \(\phi\) is a constant, \(c_s\) is sound speed, and \(r_\mathbf{k}\) is effective ion mean-free-time between Coulomb scatterings, which is roughly equal to the orbital time of the accretion flow. In this paper, we take \(\nu = \phi r_\mathbf{k}^{1/2}\) (by assuming the gas has virial temperature, \(c_s^2 = GM/r, r_\mathbf{k} \approx \sqrt{r^3/(GM)}\)) as our fiducial diffusion coefficient.

2.2. Initial conditions and numerical method

The initial condition is an equilibrium torus with constant specific angular momentum given by Stone & Pringle (2001). In this paper, we assume \(G = M = 1\). The initial torus center is located at \(R_0 = 100R_0\). Time is expressed in units of the orbital time at \(100R_0\).

The computational domain is from \(R_{in} = 1.35\) to \(R_{out} = 400R_0\), in the radial direction and from \(\theta = 0\) to \(\theta = \pi\) in the angular direction. We use logarithmically spaced grids in the radial direction. In the angular direction, the grids are uniformly spaced. The axisymmetric boundary conditions are used at \(\theta = 0\) and \(\theta = \pi\). Outflow boundary conditions are adopted at both the inner and outer radial boundaries. Our numerical resolution is \(168 \times 88\).

2.3. Models

The magnetic field which threads the torus initially is generated by a vector potential, that is, \(\mathbf{B} = \nabla \times \mathbf{A}\). Initializing the magnetic field in this way guarantees that it will be divergence free. In this work, we take \(A\) to be purely azimuthal. We consider two magnetic field configurations: dipolar \(A_\phi = \rho^2/\beta_0\) and quadrupolar \(A_\phi = r \cos(\theta) \rho^2/\beta_0, \beta_0 = P_{gas}/P_{mag}\).

Table 1 lists the main parameters in all models presented here, initial magnetic field topology, initial plasma parameter \(\beta_0\), viscous coefficient \(\phi\), and final time \(t_f\) at which each simulation is stopped (all times in this paper are in units of the orbital time at \(R_0 = 100R_0\)).

3. Results

We analyze the properties of hot accretion flow at the quasi-steady state, that is, the net accretion rate is independent of radius. The angle integrated mass inflow and outflow rates, \(M_{in}\) and \(M_{out}\), are defined as follows.

\[
M_{in}(r) = 2\pi r^2 \int_0^\infty \rho \min(v_r, 0) \sin \theta d\theta d\phi,
\]

(7)

\[
M_{out}(r) = 2\pi r^2 \int_0^\infty \rho \max(v_r, 0) \sin \theta d\theta d\phi,
\]

(8)

Notes. (*) Final time at which each simulation is stopped and time is in units of the orbital time at \(R_0 = 100R_0\).
and the net mass accretion rate is,

$$M_{\text{acc}}(r) = M_{\text{in}}(r) + M_{\text{out}}(r). \quad (9)$$

We note that the above rates are obtained by time-averaging the integrals rather than integrating the time averages.

### 3.1. A fiducial model – Run B

Model B ($\beta_0 = 10^8$, $\phi = 0.02$) is chosen as our fiducial model. In model B, the initial magnetic field is very weak. When quasi-steady state is achieved, the Maxwell stress is much weaker than the anisotropic viscosity. We define the viscous coefficient induced by Maxwell stress as

$$\alpha = -B_r B_\phi / 4\pi p.$$

Figure 1 shows the time-averaged log $\alpha$ for Run B. From this figure, it is clear that in the whole computational domain, $\alpha$ is much smaller than the anisotropic viscosity coefficient ($\phi = 0.02$). Therefore, in this model, angular momentum transfer is dominated by anisotropic viscosity.

The time-averaged mass fluxes of model B are shown in Fig. 2 (black lines). The time-averaged net accretion rate is independent of radius which indicates the flow has reached a quasi-steady state. Both the inflow and outflow rates decrease inwards, consistent with those found in previous works (e.g., Stone & Pringle 2001; Yuan et al. 2012a, 2015). We need to note that in previous works (e.g., Stone & Pringle 2001; Yuan et al. 2012a, 2015), the angular momentum transfer is induced by Maxwell stress. The inward decrease of mass inflow rate in those works is due to mass loss via real outflow (wind). This is not the case in which Maxwell stress is negligibly small. Below we show that in the case that Maxwell stress is small, mass inflow decreases inward because the accretion flow is convective.

Figure 2 shows that there is a significant mass outflow rate, but this does not mean it is real outflow (wind). The reasons are as follows. According to Eq. (8), when we calculate the mass outflow rate, we include all the gas which has a positive radial velocity. The accretion flow is turbulent. In a turbulent accretion flow, there are real outflow (wind) and turbulent outflow. Real outflow means that the flows are systematically outward moving gas. Turbulent outflow means that the outflow is not real outflow but an outward moving portion of a turbulent eddy.

What is the reason for the inward decrease of mass inflow rate? Does wind exist? To study whether or not wind exists, let us first directly look at the velocity field shown in Fig. 3. In the region $45^\circ \leq \theta \leq 90^\circ$, turbulent motion dominates. In the region close to the rotational axis, gas is inflowing. It is different from previous simulation results. Previous works show that if the angular momentum is transferred by Maxwell stress (magnetic field is strong), the region close to the rotational axis is filled by jet (e.g., Sadowski et al. 2016; Narayan et al. 2012). In the region $\theta \approx 32^\circ$, there is outward moving gas; this portion of outward moving gas returns and becomes inflow at $r \approx 100 R_s$. From Fig. 3, it is hard to find real outflow (wind).

Following Yuan et al. (2015), we now use a much more precise trajectory method to study whether or not winds exist. The details of this approach can be found in Yuan et al. (2015), here we only briefly introduce it. Trajectory is obtained by connecting the positions of the same “test particle” at different times. This concept is related with the Lagrangian description of fluid. We note that this is different from the streamline which is obtained
by connecting the velocity vector of different test particles with infinitely short distance at a given time. This concept is associated with the Euler description of fluid motion. Trajectory is only equivalent to the streamline for strictly steady motion, which is not the case for accretion flow since it is always turbulent. To get the trajectory, we first need to choose a virtual “test particle” in the simulation domain. They are of course not real particles, but some grids representing fluid elements. Their locations and velocity at a certain time \( t \) are obtained directly from the simulation data. We can then obtain their location at time \( t + \delta t \) from the velocity vector and \( \delta t \). We do this work using software called “VISIT”.

Using a trajectory approach, we can discriminate easily between particles that are real outflows (i.e., winds) and those that are undergoing turbulent motions. We can also calculate the mass fluxes of wind by combining this with the information of density and velocity of wind. For details, see Yuan et al. (2015).

The inward decrease of inflow rate is again due to turbulent motions induced by convection as is the case found in Run B. With a weaker viscous stress, the evolution of torus proceeds much slowly. Therefore, it takes roughly 40 orbits for the torus to achieve a quasi-steady state. In model C, the Maxwell stress is also much smaller than the anisotropic viscosity. We find that when quasi-steady state is achieved, the mass inflow rate also decreases inwards. The reason for the inward decrease of mass inflow rate is mainly due to turbulent motions induced by convection as is the case found in Run B.

3.3. Dependence on the initial magnetic field topology

In order to study whether or not the results depend on the initial magnetic field configuration, we run model D. In this model, the initial magnetic field is quadrupolar. As in models B and C, we find that when the Maxwell stress is much smaller than the anisotropic viscosity, the mass inflow rate decreases inwards. The inward decrease of inflow rate is again due to turbulent motions induced by convection.

Beckwith & Hawley (2008) studied the effects of magnetic field topology on the evolution of black hole accretion flow.
Their results show that the qualitative properties of the accretion flow are independent of initial magnetic field configuration, but jet launching is sensitive to it, that is, a dipolar topology field model has stronger jets than a quadrupolar field model. In the case of extremely weak magnetic field ($\beta = 10^8$), there is no jet (see Fig. 3). Therefore, we can conclude that the properties of accretion flow are independent of initial magnetic field topology when the magnetic field is extremely weak.

3.4. Dependence on magnetic field strength

In order to study the dependence on the magnetic field strength, we run models A and E. The difference between models A(E) and B is the initial magnetic field strength. The initial magnetic field energy in Run A with $\beta_0 = 10^4$, is 4 orders of magnitude higher than that in Run B. In model E, $\beta_0 = 200$, the initial magnetic energy in this model is 6 orders of magnitude higher than that in Run B.

Figure 6 shows log $\alpha$ in Run A. In the region $12^\circ \leq \theta \leq 168^\circ$, $\alpha < \phi$, anisotropic viscosity is much larger than the Maxwell stress. In regions $\theta \leq 12^\circ$ and $\theta \geq 168^\circ$, Maxwell stress is much larger than anisotropic viscosity.

The mass accretion rate of Run A is shown in Fig. 2. Both mass inflow and outflow rates decrease towards the black hole. In order to investigate why mass inflow rate decreases inwards, we plot Fig. 7. This Figure shows the velocity vectors for Run A. It is clear that in this model, real outflow (wind) is much stronger than that in Run B. Winds dominate in the region $0^\circ \leq \theta \leq 24^\circ$, in the region $24^\circ \leq \theta \leq 45^\circ$, there is a turbulent eddy, and in the region $45^\circ \leq \theta \leq 90^\circ$, turbulent motions dominate.

In order to precisely study the mass flux of wind, we plot the trajectories of gas particles in Fig. 8. From this Figure, we can see that wind dominates in the region $\theta \leq 24^\circ$ which is consistent with that found in Fig. 7. Our quantitative calculation shows that the mass flux of wind is 15% of the mass outflow rate calculated by Eq. (8). Winds are present in the region $\theta \leq 24^\circ$. In this region, the gas density is very small; therefore, the mass flux of wind is still small. The mass outflow rate calculated by Eq. (8) is dominated by turbulent motions. Therefore, as in models B and C, turbulent motions induced by convection cause the mass inflow rate of model A to decrease inward.

For comparison, we also present results from a control run E. In this model the Maxwell stress is comparable to the anisotropic viscosity. We also use the trajectory method to study whether or not winds exist. Figure 9 shows the trajectories of 88 “test particles” starting from $40R_s$ in model E. It is clear that strong wind exists in the region $0^\circ < \theta < 45^\circ$ and $135^\circ < \theta < 180^\circ$. Our quantitative calculation shows that the mass flux of real outflow (wind) is about 70% of the total outflow rate calculated by Eq. (8). Wind is very strong in run E. This is consistent with previous numerical simulations (Yuan et al. 2015), which studied hot accretion flow with large Maxwell stress.

4. Summary and discussion

In hot, dilute plasmas, the mean-free path of ions can be large compared to the typical scalelength of accretion flow. When the ion mean-free path is larger than its gyroradius, pressure is anisotropic with respect to magnetic field lines. The effects of pressure anisotropy can be modeled by anisotropic viscosity. In non-relativistic limit, the anisotropic viscous stress is reduced to Braginskii viscosity (Braginskii 1965). Angular momentum of the accretion flow can be transferred by anisotropic viscosity.
In this work, we perform two-dimensional global MHD simulations of hot accretion flow. We investigate hot accretion flow in which anisotropic viscous stress is stronger than Maxwell stress. We find that the flow is convectively unstable. We also find that the mass inflow rate decreases towards the black hole. Wind is very strong in run E. The inward decrease of inflow rate is mainly due to convective motions. This result may be useful to understand the accretion flow in the Galactic Center Sgr A* and the accretion flow in the galaxy M 87 (Akiyama et al. 2015).

Many observations show that wind is highly prevalent in AGNs and black hole X-ray binaries. The Blandford & Payne (1982) mechanism, which needs large-scale open magnetic field lines, is usually invoked to account for the origin of wind. But, it is still unclear whether or not large scale magnetic fields exist in accretion flows (Beckwith et al. 2009). Recently, Yuan et al. (2012b) introduced a micro-Blandford & Payne mechanism to explain the origin of wind without large-scale open magnetic fields. We extend previous work to cases with very weak magnetic field. Our results show that even with extremely weak magnetic field, wind can be present in the accretion flow with anisotropic viscosity.

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Appendix A: Artificial resistivity

The Zeus code has issues with losing energy from the grid. In the MHD simulation, there will be numerical dissipation in magnetic field. In order to convert the magnetic energy dissipated in current sheet into thermal heating, we include explicit artificial resistivity in our Eqs. (3) and (4). Following Stone & Pringle (2001), the coefficient of artificial resistivity is given by:

$$\eta = \frac{Q(\Delta x)^2}{\sqrt{\rho}} |J|.$$  \hfill (A.1)

Here, $\Delta x$ is the grid spacing, $\rho$ is gas density, $J$ is current density, and $Q$ is a constant.

In Stone & Pringle (2001), the authors have done some tests. They find that for $Q = 0$ the change in the total energy in the flow is 0.6%. If $Q = 0.1$ this change is reduced to 0.08%. They conclude that with an artificial resistivity, conservation of total energy is improved because energy losses due to numerical reconnection are reduced. In this paper, we set $Q = 0.1$. In Fig. A.1, we plot the time evolution of total energy and its individual components (internal, kinetic, gravitational and magnetic energies) for model B. It is clear that the total energy (solid line) is almost constant. Also, the magnetic energy is several orders of magnitude smaller than other components of energy. The effect of numerical magnetic energy loss on the total energy evolution of the accretion flow is negligible.

Fig. A.1. Time evolution of total energy and its individual components (internal, kinetic, gravitational and magnetic energies) for model B.