On the averaging principle for stochastic delay differential equations with jumps

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Abstract

In this paper, we investigate the averaging principle for stochastic delay differential equations (SDDEs) and SDDEs with pure jumps. By the Itô formula, the Taylor formula, and the Burkholder-Davis-Gundy inequality, we show that the solution of the averaged SDDEs converges to that of the standard SDDEs in the sense of pth moment and also in probability. Finally, two examples are provided to illustrate the theory.

Keywords: averaging principle; stochastic delay differential equations; Poisson random measure; $L^p$ convergence

1 Introduction

The averaging principle for dynamical system is important in problems of mechanics, control and many other areas. It was first put forward by Krylov and Bogolyubov [1], then by Gikhman [2] and Volosov [3] for non-linear ordinary differential equations. With the developing of the theory of stochastic analysis, many authors began to study the averaging principle for stochastic differential equations (SDEs). See, for instance, Khasminskii [4], Khasminskii and Yin [5], Golec and Ladde [6], Veretennikov [7, 8], Givon et al. [9], Tan and Lei [10].

On the other hand, in real phenomena, many real systems may be perturbed by abrupt pulses or extreme events and these systems with white noise are not always appropriate to interpret real data in a reasonable way. A more natural mathematical framework for these phenomena has been taken into account other than purely Brownian perturbations. It is recognized that SDEs with jumps are quite suitable to describe such discontinuous systems. In the meantime, the averaging method for a class of stochastic equations with jumps has received much attention from many authors and there exists some literature [11–14] concerned with the averaging method for SDEs with jumps.

Motivated by the above discussion, in this paper we study the averaging principle for a class of stochastic delay differential equations (SDDEs) with variable delays and jumps. To the best of our knowledge, the published papers on the averaging method are concentrated on the case of SDEs, there are few results concerning the averaging principle for SDDEs with jumps. What is more, associated with all the work mentioned above, we pay special attention to the fact that most authors just focus on the mean-square convergence of the solution of the averaged stochastic equations and that of the standard stochastic equations. They do not consider the general $p$th ($p > 2$) moment convergence case. In order to close this gap, the main aim of this paper is to study the solution of the averaged...
SDDEs converging to that of the standard SDDEs in the sense of pth moment. By using
the Itô formula, the Taylor formula, and stochastic inequalities, we give the proof of the
pth moment convergence results. It should be pointed out that we will not get the pth
moment convergence results by using the proof of [11–14] and we need to develop sev-
eral new techniques to deal with the pth moment case and the term with Poisson random
measure. The results obtained are a generalization and improvement of some results in
[11–14].

The rest of this paper is organized as follows. In Section 2, we prove that the solution of
the averaged SDDEs converges to that of the standard SDDEs in the sense of pth moment
and also in probability; in Section 3 we also consider the above results as regards the pure
jump case. Finally, we give two examples to illustrate the theory in Section 4.

2 Averaging principle for Brownian motion case

Let $(\Omega, \mathcal{F}, P)$ be a complete probability space equipped with some filtration $(\mathcal{F}_t)_{t \geq 0}$ satisfying
the usual conditions. Here $w(t)$ is an $m$-dimensional Brownian motion defined on the
probability space $(\Omega, \mathcal{F}, P)$ adapted to the filtration $(\mathcal{F}_t)_{t \geq 0}$. Let $\tau > 0$ and $C([-\tau, 0]; \mathbb{R}^n)$
denote the family of all continuous functions $\psi$ from $[-\tau, 0] \to \mathbb{R}^n$. The space $C([-\tau, 0]; \mathbb{R}^n)$
is assumed to be equipped with the norm $\| \psi \| = \sup_{-\tau \leq t < 0} |\psi(t)|$. $C^\infty_{\mathcal{F}_0}([-\tau, 0]; \mathbb{R}^n)$
denote the family of all almost surely bounded, $\mathcal{F}_0$-measurable, $C([-\tau, 0]; \mathbb{R}^n)$ valued ran-
don variables $\xi = \{\xi(\theta) : -\tau \leq \theta \leq 0\}$. Let $p \geq 2$, $L^p_{\mathcal{F}_0}([-\tau, 0]; \mathbb{R}^n)$ denote the family of all
$\mathcal{F}_0$ measurable, $C([-\tau, 0]; \mathbb{R}^n)$-valued random variables $\psi = \{\psi(\theta) : -\tau \leq \theta \leq 0\}$ such that
$E \sup_{-\tau \leq \theta < 0} |\psi(\theta)|^p < \infty$.

Consider the following SDDEs:

$$dx(t) = f(t, x(t), x(\delta(t))) \, dt + g(t, x(t), x(\delta(t))) \, dw_t,$$

where $f : [0, T] \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n$ and $g : [0, T] \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^{n \times m}$ are both Borel-measurable
functions. The function $\delta : [0, T] \to R$ is the time delay which satisfies $-\tau \leq \delta(t) \leq t$. The
initial condition $x_0$ is defined by

$$x_0 = \xi = \{\xi(t) : -\tau \leq t \leq 0\} \in L^p_{\mathcal{F}_0}([-\tau, 0]; \mathbb{R}^n),$$

that is, $\xi$ is an $\mathcal{F}_0$-measurable $C([-\tau, 0]; \mathbb{R}^n)$-valued random variable and $E\|\xi\|^p < \infty$.

To study the averaging method of (1), we need the following assumptions.

(H2.1) For all $x_1, y_1, x_2, y_2 \in \mathbb{R}^n$ and $t \in [0, T]$, there exist two positive constants $k_1$ and $k_0$ such that

$$|f(t, x_1, y_1) - f(t, x_2, y_2)|^2 + |g(t, x_1, y_1) - g(t, x_2, y_2)|^2 \leq k_1 (|x_1 - x_2|^2 + |y_1 - y_2|^2)$$

and

$$|f(t, 0, 0)|^2 + |g(t, 0, 0)|^2 \leq k_0.$$

Clearly, condition (2) together with (3) implies the linear growth condition

$$|f(t, x, y)|^2 + |g(t, x, y)|^2 \leq K (1 + |x|^2 + |y|^2),$$

where $K = \max\{k_1, k_0\}$. 

In fact, we have, for any $x, y \in \mathbb{R}^n$,
\[ |f(t, x, y)|^2 \leq |f(t, x, y) - f(t, 0, 0)|^2 + |f(t, 0, 0)|^2 \leq k_1(1 + |x|^2 + |y|^2) + k_0 \leq \max\{k_1, k_0\}(1 + |x|^2 + |y|^2). \]

Similar to the above derivation, we have
\[ |g(t, x, y)|^2 \leq \max\{k_1, k_0\}(1 + |x|^2 + |y|^2), \]
which implies condition (4).

Theorem 2.1 Under condition (H2.1), (1) has a unique solution in $L^p$, $p \geq 2$. Moreover, we have
\[ E \sup_{0 \leq t \leq T} |x(t)|^p < C. \]

The proof of Theorem 2.1 is given in the Appendix.

Next, let us consider the standard form of SDDEs (1),
\[ x_i(t) = \xi_i(t) + \epsilon \int_0^t f_i(s, x_i(s), x_i(\delta(s))) \, ds + \sqrt{\epsilon} \int_0^t g_i(s, x_i(s), x_i(\delta(s))) \, dw_i, \tag{5} \]
where the coefficients $f, g$ have the same conditions as in (2), (4) and $\epsilon \in [0, \epsilon_0]$ is a positive small parameter with $\epsilon_0$ a fixed number.

Let $\tilde{f}(x, y) : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n$ and $\tilde{g}(x, y) : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^{n \times n}$ be measurable functions, satisfying condition (H2.1). We also assume that the following conditions are satisfied.

(H2.2) For any $x, y \in \mathbb{R}^n$, there exist two positive bounded functions $\varphi_i(T_i)$, $i = 1, 2$, such that
\[ \frac{1}{T_i} \int_0^{T_i} |a(s, x, y) - \tilde{a}(x, y)|^p \, ds \leq \varphi_i(T_i)(1 + |x|^p + |y|^p), \]
where $a = f, g$ and $\lim_{T_i \to \infty} \varphi_i(T_i) = 0$.

Then we have the averaging form of the corresponding standard SDDEs
\[ y_i(t) = \xi_i(t) + \epsilon \int_0^t \tilde{f}_i(s, y_i(s), y_i(\delta(s))) \, ds + \sqrt{\epsilon} \int_0^t \tilde{g}_i(s, y_i(s), y_i(\delta(s))) \, dw_i. \tag{6} \]

Obviously, under condition (H2.1), the standard SDDEs (5) and the averaged SDDEs (6) has a unique solution on $t \in [0, T]$, respectively.

Now, we present and prove our main results, which are used for revealing the relationship between the $x_i(t)$ and $y_i(t)$.

Theorem 2.2 Let the conditions (H2.1), (H2.2) hold. For a given arbitrary small number $\delta_1 > 0$, there exist $L > 0$, $\epsilon_1 \in (0, \epsilon_0]$, and $\beta \in (0, 1)$ such that
\[ E|x_i(t) - y_i(t)|^p \leq \delta_1, \quad \forall t \in [0, L\epsilon^{-\beta}], \tag{7} \]
for all $\epsilon \in (0, \epsilon_1]$. 

Proof. For simplicity, denote the difference \( e(t) = x(t) - y(t) \). From (5) and (6), we have

\[
e(t) = e \int_0^t \left[ f\left(x(s), x_e(s), \delta(s)\right) - \tilde{f}\left(y(s), y_e(s), \delta(s)\right) \right] ds \\
+ \sqrt{e} \int_0^t \left[ g\left(s, x(s), x_e(s), \delta(s)\right) - \tilde{g}\left(y(s), y_e(s), \delta(s)\right) \right] dw_s.
\]

By the Itô formula (see [15]), we have, for \( p \geq 2 \),

\[
|e(t)|^p \\
= pe \int_0^t |e(s)|^{p-2} e(s)^T \left[ f\left(x(s), x_e(s), \delta(s)\right) - \tilde{f}\left(y(s), y_e(s), \delta(s)\right) \right] ds \\
+ \frac{pe}{2} \int_0^t |e(s)|^{p-2} |g(s, x(s), x_e(s), \delta(s)) - \tilde{g}(y(s), y_e(s), \delta(s))|^2 ds \\
+ \frac{p(p-2)e}{2} \int_0^t |e(s)|^{p-4} |e(s)^T \left[ g\left(s, x(s), x_e(s), \delta(s)\right) - \tilde{g}\left(y(s), y_e(s), \delta(s)\right) \right] |^2 ds \\
+ p\sqrt{e} \int_0^t |e(s)|^{p-2} e(s)^T \left[ g\left(s, x(s), x_e(s), \delta(s)\right) - \tilde{g}\left(y(s), y_e(s), \delta(s)\right) \right] dw_s.
\]

(8)

Using the basic inequality \( 2ab \leq a^2 + b^2 \) and taking expectation on both sides of (8), it follows that, for any \( u \in [0, T] \),

\[
E \sup_{0 \leq s \leq u} |e(s)|^p \\
\leq pe E \int_0^u |e(t)|^{p-1} \left| f\left(t, x(t), x_e(t), \delta(t)\right) - \tilde{f}\left(y(t), y_e(t), \delta(t)\right) \right| dt \\
+ \frac{p(p-1)e}{2} \int_0^u |e(t)|^{p-2} \left| g\left(t, x(t), x_e(t), \delta(t)\right) - \tilde{g}\left(y(t), y_e(t), \delta(t)\right) \right|^2 dt \\
+ E \sup_{0 \leq s \leq u} \int_0^t p\sqrt{e} |e(s)|^{p-2} e(s)^T \left[ g\left(s, x(s), x_e(s), \delta(s)\right) - \tilde{g}\left(y(s), y_e(s), \delta(s)\right) \right] dw_s \\
= peI_1 + \frac{p(p-1)e}{2} I_2 + I_3.
\]

(9)

By the Young inequality, it follows that for any \( e_1 > 0 \)

\[
I_1 \leq E \int_0^u \left[ \frac{(p-1)e_1}{p} |e(t)|^p \right. \\
+ \left. \frac{1}{pe_1^{p-1}} |f\left(t, x(t), x_e(t), \delta(t)\right) - \tilde{f}\left(y(t), y_e(t), \delta(t)\right)|^p \right] dt,
\]

(10)

where the second term of (10) can be written by

\[
|f\left(t, x(t), x_e(t), \delta(t)\right) - \tilde{f}\left(y(t), y_e(t), \delta(t)\right)|^p \\
= |f\left(t, x(t), x_e(t), \delta(t)\right) - f\left(t, y(t), y_e(t), \delta(t)\right)|^p \\
+ |f\left(t, y(t), y_e(t), \delta(t)\right) - \tilde{f}\left(y(t), y_e(t), \delta(t)\right)|^p.
\]
For any $\epsilon_2 > 0$, we derive that

$$
|f(t, x_0(t), x_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p
\leq \left[1 + \epsilon_2^{\frac{1}{p-1}}\right]^{p-1} \left(\frac{1}{\epsilon_2^p} \left|e_0^0\right|^{\frac{p}{p-1}} + \left|e_0^1\right|^p\right)^{\frac{p}{p-1}}
+ \left|f(t, y_0(t), y_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p \right).
$$

(11)

By (H2.1), we have

$$
|f(t, x_0(t), x_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p
\leq \left[1 + \epsilon_2^{\frac{1}{p-1}}\right]^{p-1} \left(\frac{1}{\epsilon_2^p} \left|e_0^0\right|^{\frac{p}{p-1}} + \left|e_0^1\right|^p\right)^{\frac{p}{p-1}}
+ \left|f(t, y_0(t), y_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p \right).
$$

Letting $\epsilon_2 = (\sqrt{2k_1})^{p-1}$ yields

$$
|f(t, x_0(t), x_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p
\leq (1 + \sqrt{2k_1})^{p-1} \left[\sqrt{2k_1} \sup_{0 \leq \sigma \leq t} |e_0^0(\sigma)|^p
+ \left|f(t, y_0(t), y_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p \right].
$$

(12)

Inserting (12) into (10), we have

$$
I_1 \leq \int_0^\mu \left\{ \left[\frac{p-1}{p} \left|e_0^0(t)\right|^p + \frac{1}{pe_1^{p-1}}(1 + \sqrt{2k_1})^{p-1} \left[\sqrt{2k_1} \sup_{0 \leq \sigma \leq t} |e_0^0(\sigma)|^p
+ \left|f(t, y_0(t), y_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p \right]\right]\right\} dt.
$$

(13)

By setting $e_1 = 1 + \sqrt{2k_1}$, we get

$$
I_1 \leq 2(1 + \sqrt{2k_1})E \int_0^\mu \sup_{0 \leq \sigma \leq t} |e_0^0(\sigma)|^p dt
+ \left[\sqrt{2k_1} \sup_{0 \leq \sigma \leq t} |e_0^0(\sigma)|^p
+ \left|f(t, y_0(t), y_0(\delta(t))) - \tilde{f}(y_0(t), y_0(\delta(t)))|^p \right] dt.
$$

(14)
Next, we will estimate $I_2$ of (9). Using the Young inequality again, it follows that for any $\varepsilon_3 > 0$

$$I_2 \leq E \int_0^u \left[ \frac{(p-2)\varepsilon_3}{p} |e_\varepsilon(t)|^p 
+ \frac{2}{p\varepsilon_3^{p-2}} \left( 1 + \sqrt{2k_1} \right)^{p-1} \left( \frac{\sqrt{2k_1}}{p} \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p 
+ \left| g(t, y_x(t), y_x(\delta(t))) - \tilde{g}(y_x(t), y_x(\delta(t))) \right|^p \right) \right] dt. \quad (15)$$

Similar to the computation of (12), we can obtain

$$\left| g(t, y_x(t), y_x(\delta(t))) - \tilde{g}(y_x(t), y_x(\delta(t))) \right|^p \leq (1 + \sqrt{2k_1})^{p-1} \left( \frac{\sqrt{2k_1}}{p} \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p 
+ \left| g(t, y_x(t), y_x(\delta(t))) - \tilde{g}(y_x(t), y_x(\delta(t))) \right|^p \right). \quad (16)$$

Substituting (16) into (15),

$$I_2 \leq E \int_0^u \left[ \frac{(p-2)\varepsilon_3}{p} |e_\varepsilon(t)|^p 
+ \frac{2}{p\varepsilon_3^{p-2}} (1 + \sqrt{2k_1})^{p-1} \left( \frac{\sqrt{2k_1}}{p} \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p 
+ \left| g(t, y_x(t), y_x(\delta(t))) - \tilde{g}(y_x(t), y_x(\delta(t))) \right|^p \right) \right] dt.$$

Letting $\varepsilon_3 = (1 + \sqrt{2k_1})^2$, we get

$$I_2 \leq (1 + \sqrt{2k_1})^2 E \int_0^u \left[ 2 \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p 
+ \left| g(t, y_x(t), y_x(\delta(t))) - \tilde{g}(y_x(t), y_x(\delta(t))) \right|^p \right] dt.$$

From condition (H2.2), it follows that

$$I_2 \leq 2(1 + \sqrt{2k_1})^2 E \int_0^u \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p dt 
+ (1 + \sqrt{2k_1})^2 \varphi_2(u) \left( 1 + E \sup_{-\tau \leq t \leq 0} |y_x(t)|^p + 2E \sup_{0 \leq t \leq u} |y_x(t)|^p \right). \quad (17)$$

On the other hand, by the Burkholder-Davis-Gundy inequality, we have

$$I_3 \leq 3E \left[ \int_0^u p^2 \varepsilon |x_\varepsilon(t)|^{2p-2} \left| g(t, x_\varepsilon(t), x_\varepsilon(\delta(t))) - \tilde{g}(y_x(t), y_x(\delta(t))) \right|^2 ds \right]^{\frac{1}{2}} 
\leq 3E \left[ \sup_{0 \leq t \leq u} |x_\varepsilon(t)|^p \int_0^u p^2 \varepsilon |x_\varepsilon(t)|^{2p-2} \left| g(t, x_\varepsilon(t), x_\varepsilon(\delta(t))) - \tilde{g}(y_x(t), y_x(\delta(t))) \right|^2 ds \right]^{\frac{1}{2}}.$$
By Theorem 2.1, we have that for each $t \geq 0$, if $E \| \xi \|^p < \infty$, then $E |y_\epsilon(t)|^p < \infty$. Hence condition (H2.2) implies that

$$
E \sup_{0 \leq t \leq u} |y_\epsilon(t)|^p \leq c_1 \epsilon u \left( 1 + E \| \xi \|^p + 2C \right) + c_1 \epsilon u \int_0^u \sup_{0 \leq \sigma \leq t} |y_\epsilon(\sigma)|^p \, dt.
$$

Finally, by the Gronwall inequality, we have

$$
E \sup_{0 \leq t \leq u} |y_\epsilon(t)|^p \leq c_2 \epsilon u \left( 1 + E \| \xi \|^p + 2C \right)e^{c_1 \epsilon u}.
$$

Choose $\beta \in (0, 1)$ and $L > 0$ such that for every $t \in [0, Le^{-\beta}] \subseteq [0, T]$,

$$
E \sup_{t \in [0, Le^{-\beta}]} |x_\epsilon(t) - y_\epsilon(t)|^p \leq cLe^{1-\beta},
$$

where $c = c_2 \left( 1 + E \| \xi \|^p + 2C \right)e^{c_1 Le^{-\beta}}$. Consequently, given any number $\delta_1$, we can choose $\epsilon_1 \in [0, \epsilon_0]$ such that for each $\epsilon \in [0, \epsilon_1]$ and for $t \in [0, Le^{-\beta}]$,

$$
E \sup_{t \in [0, Le^{-\beta}]} |x_\epsilon(t) - y_\epsilon(t)|^p \leq \delta_1.
$$

The proof is completed. $\square$

With Theorem 2.2, it is easy to show the convergence in probability between $x_\epsilon(t)$ and $y_\epsilon(t)$.
Corollary 2.1 Let the conditions (H2.1) and (H2.2) hold. For a given arbitrary small number \( \delta_2 > 0 \), there exists \( \varepsilon_2 \in [0, \varepsilon_0] \) such that for all \( \varepsilon \in (0, \varepsilon_2] \), we have

\[
\lim_{\varepsilon \to 0} P \left( \sup_{0 < t < L - \beta} \left| x_\varepsilon(t) - y_\varepsilon(t) \right| > \delta_2 \right) = 0,
\]

where \( L \) and \( \beta \) are defined by Theorem 2.2.

Proof By Theorem 2.2 and the Chebyshev inequality, for any given number \( \delta_2 > 0 \), we can obtain

\[
P \left( \sup_{0 < t < L - \beta} \left| x_\varepsilon(t) - y_\varepsilon(t) \right| > \delta_2 \right) \leq \frac{1}{\delta_2^2} E \left( \sup_{0 < t < L - \beta} \left| x_\varepsilon(t) - y_\varepsilon(t) \right|^p \right) \leq \frac{cL^{1-\beta}}{\delta_2^2}.
\]

Let \( \varepsilon \to 0 \), and the required result follows.

3 Averaging principle for pure jump case

In this section we turn to the counterpart for SDDEs with jumps. We further need to introduce some notations.

Let \( \tau > 0 \), and \( D([\tau, 0]; \mathbb{R}^n) \) denote the family of all right-continuous functions with left-hand limits \( \varphi \) from \( [\tau, 0) \to \mathbb{R}^n \). The space \( D([\tau, 0]; \mathbb{R}^n) \) is assumed to be equipped with the norm \( \| \varphi \| = \sup_{\tau \leq s \leq 0} |\varphi(s)| \). \( D_{\mathcal{F}_0}^\beta([\tau, 0]; \mathbb{R}^n) \) denotes the family of all almost surely bounded, \( \mathcal{F}_0 \)-measurable, \( D([\tau, 0]; \mathbb{R}^n) \) valued random variables \( \xi = \{ \xi(\theta) : -\tau \leq \theta \leq 0 \} \). Let \( p \geq 2 \), \( L_{\mathcal{F}_0}^p([\tau, 0]; \mathbb{R}^n) \) denote the family of all \( \mathcal{F}_0 \)-measurable, \( D([\tau, 0]; \mathbb{R}^n) \)-valued random variables \( \varphi = \{ \varphi(\theta) : -\tau \leq \theta \leq 0 \} \) such that \( E \sup_{\tau \leq \theta < 0} |\varphi(\theta)|^p < \infty \).

Let \((Z, \mathcal{B}(Z))\) be a measurable space and \( \pi(\text{d}v) \) a \( \sigma \)-finite measure on it. Let \((\bar{\nu} = \bar{\nu}(t), t \geq 0)\) be a stationary \( \mathcal{F}_t \)-Poisson point process on \( Z \) with characteristic measure \( \pi \). Then, for \( A \in \mathcal{B}(Z - \{0\}) \), here 0 \( \in \) the closure of \( A \), the Poisson counting measure \( N \) is defined by

\[
N([0, t] \times A) := \sum_{0 < s \leq t} I_A(\bar{\nu}(s)) = \# (0 < s \leq t, \bar{\nu}(s) \in A).
\]

By [16], we find that there exists a \( \sigma \)-finite measure \( \pi \) such that

\[
E[N(t, A)] = \pi(A)t, \quad \text{P}(N(t, A) = n) = \frac{e^{(t-\pi(A))\nu(A)t^n}}{n!},
\]

where \( N(t, A) := N([0, t] \times A) \). This measure \( \pi \) is said the Lévy measure. Then the compensated Poisson random measure \( \tilde{N} \) is defined by

\[
\tilde{N}([0, t] \times A) := N([0, t] \times A) - t\pi(A), \quad t > 0.
\]

We refer to Ikeda and Watanable [16] and Applebaum [17] for the details of Poisson point processes and Lévy processes.

In this section, we consider the SDDEs with pure jumps:

\[
dx(t) = f(t, x(t), x(\delta(t))) \, dt + \int_Z h(t, x(t), x(\delta(t)), \nu)\bar{\nu}(ds, dv),
\]

(19)
where \( f : [0, T] \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n \) and \( h : [0, T] \times \mathbb{R}^n \times \mathbb{R}^n \times Z \to \mathbb{R}^n \) are both Borel-measurable functions. The initial condition \( x_0 \) is defined by

\[
x_0 = \xi = [\xi(t) : -\tau \leq t \leq 0] \in L^2_{\mathbb{F}_0}([-\tau, 0]; \mathbb{R}^n).
\]

To guarantee the existence and uniqueness of the solution, we introduce the following conditions on the jump term.

(H3.1) For all \( x_1, y_1, x_2, y_2 \in \mathbb{R}^n \) and \( \nu \in Z \), there exist two positive constants \( k_2 \) and \( k_3 \) such that

\[
\left| h(t, x_1, y_1, \nu) - h(t, x_2, y_2, \nu) \right|^2 \pi(\nu) \leq k_2 |x_1 - x_2|^2 + |y_1 - y_2|^2,
\]

\[
\left| h(t, x, y, \nu) \right|^2 \pi(\nu) \leq k_3 (1 + |x|^2 + |y|^2).
\]

(H3.2) For all \( x_1, x_2, y_1, y_2 \in \mathbb{R}^n \), \( \nu \in Z \) and \( p > 2 \), there exists \( L > 0 \) such that

\[
\left| h(t, x_1, y_1, \nu) - h(t, x_2, y_2, \nu) \right|^2 \leq L |x_1 - x_2|^2 + |y_1 - y_2|^2 |\nu|^2.
\]

with \( \int_Z |\nu|^p \pi(\nu) < \infty \).

**Theorem 3.1** Under conditions (H2.1), (H3.1), and (H3.2), (19) has a unique solution in \( L^p, p \geq 2 \). Moreover, we have

\[
E \sup_{0 \leq t \leq T} |x(t)|^p < C.
\]

**Proof** Similar to the proof of [18], we find that (19) has a unique solution in \( L^p \). \( \square \)

Let us consider the standard form of SDDEs with pure jumps (19),

\[
x_\varepsilon(t) = \xi(t) + \varepsilon \int_0^t f(s, x_\varepsilon(s), x_\varepsilon(\delta(s))) \, ds
\]

\[
+ \sqrt{\varepsilon} \int_0^t \int_Z h(s, x_\varepsilon(s), x_\varepsilon(\delta(s)), \nu) \tilde{N}(ds, d\nu),
\]

where the coefficients \( f, h \) have the same conditions as in (H2.1), (H3.1), and (H3.2) and \( \varepsilon \in [0, \varepsilon_0] \) is a positive small parameter with \( \varepsilon_0 \) is a fixed number.

Let \( \tilde{f}(x, y) : \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}^n \) and \( \tilde{h}(x, y, \nu) : \mathbb{R}^n \times \mathbb{R}^n \times Z \to \mathbb{R}^n \) be measurable functions, satisfying conditions (H2.1), (H3.1), and (H3.2). We also assume that the following inequalities are satisfied.

(H3.3) For any \( x, y \in \mathbb{R}^n \) and \( \nu \in Z \), there exists a positive bounded function \( \psi_3(T_1) \), such that

\[
\frac{1}{T_1} \int_0^{T_1} \int_Z \left| h(t, x, y, \nu) - \tilde{h}(x, y, \nu) \right|^p \pi(\nu) \, dt \leq \psi_3(T_1) (1 + |x|^p + |y|^p),
\]

where \( \lim_{T_1 \to \infty} \psi_3(T_1) = 0 \).
Then the averaging form of (19) is given by

\[ y_\varepsilon(t) = \xi(t) + \varepsilon \int_0^t \tilde{f}(y_\varepsilon(s), y_\varepsilon(\delta(s))) \, ds \\
+ \sqrt{\varepsilon} \int_0^t \int_Z \tilde{h}(y_\varepsilon(s), y_\varepsilon(\delta(s)), \nu) \tilde{N}(ds, d\nu). \]  

\[ (24) \]

Obviously, under conditions (H2.1), (H3.1), and (H3.2), the standard SDDEs with pure jumps (23) and the averaged SDDEs with pure jumps (24) have unique solutions on \( t \in [0, T] \), respectively.

Now, we present and prove our main results.

**Theorem 3.2** Let the conditions (H2.1) and (H3.1)-(H3.3) hold. For a given arbitrary small number \( \delta_3 > 0 \) and \( p \geq 2 \), there exist \( L > 0 \), \( \varepsilon_3 \in (0, \varepsilon_0] \), and \( \beta \in (0, 1) \) such that

\[ E|x_\varepsilon(t) - y_\varepsilon(t)|^p \leq \delta_3, \quad \forall t \in [0, L \varepsilon^{-\beta}], \]  

\[ (25) \]

for all \( \varepsilon \in (0, \varepsilon_3] \).

**Proof** For simplicity, denote the difference \( e_\varepsilon(t) = x_\varepsilon(t) - y_\varepsilon(t) \). From (23) and (24), we have

\[ e_\varepsilon(t) = \varepsilon \int_0^t \left[ f(s, x_\varepsilon(s), x_\varepsilon(\delta(s))) - \tilde{f}(y_\varepsilon(s), y_\varepsilon(\delta(s))) \right] ds \\
+ \sqrt{\varepsilon} \int_0^t \int_Z \left[ h(s, x_\varepsilon(s), x_\varepsilon(\delta(s)), \nu) - \tilde{h}(y_\varepsilon(s), y_\varepsilon(\delta(s)), \nu) \right] \tilde{N}(ds, d\nu). \]  

\[ (26) \]

By the Itô formula (see [17, 19]), we obtain

\[ |e_\varepsilon(t)|^p \]

\[ = p \varepsilon \int_0^t |e_\varepsilon(s)|^{p-2} e_\varepsilon(s)^T \left[ f(s, x_\varepsilon(s), x_\varepsilon(\delta(s))) - \tilde{f}(y_\varepsilon(s), y_\varepsilon(\delta(s))) \right] ds \\
+ \int_0^t \int_Z \left[ |e_\varepsilon(s) + \sqrt{\varepsilon} \left[ h(s, x_\varepsilon(s), x_\varepsilon(\delta(s)), \nu) - \tilde{h}(y_\varepsilon(s), y_\varepsilon(\delta(s)), \nu) \right] \right]^p \\
- |e_\varepsilon(s)|^p - p\sqrt{\varepsilon} |e_\varepsilon(s)|^{p-2} e_\varepsilon(s)^T \left[ h(s, x_\varepsilon(s), x_\varepsilon(\delta(s)), \nu) - \tilde{h}(y_\varepsilon(s), y_\varepsilon(\delta(s)), \nu) \right] \\
- \tilde{h}(y_\varepsilon(s), y_\varepsilon(\delta(s)), \nu)] \nu(d\nu) ds \\
+ \int_0^t \int_Z \left[ |e_\varepsilon(s) + \sqrt{\varepsilon} \left[ h(s, x_\varepsilon(s), x_\varepsilon(\delta(s)), \nu) - \tilde{h}(y_\varepsilon(s), y_\varepsilon(\delta(s)), \nu) \right] \right]^p \\
- |e_\varepsilon(s)|^p \right] \tilde{N}(ds, d\nu). \]  

\[ (27) \]

Using the basic inequality \( 2ab \leq a^2 + b^2 \) and taking expectations on both sides of (27), it follows that

\[ E \sup_{0 \leq t \leq u} |e_\varepsilon(t)|^p \]

\[ \leq p \varepsilon E \int_0^u |e_\varepsilon(t)|^{p-1} \left| f(t, x_\varepsilon(t), x_\varepsilon(\delta(t))) - \tilde{f}(y_\varepsilon(t), y_\varepsilon(\delta(t))) \right| dt \]
\[ \begin{align*}
+ & p \sqrt{\lambda} E \sup_{0 \leq u \leq U} \int_0^t \int_Z |e_\epsilon(s)|^{p-2} e_\epsilon(s)^\top [h(s, x_\epsilon(s), x_\epsilon(\delta(s)), v) \\
- & \tilde{h}(y(s), y_\epsilon(\delta(s)), v)] N(ds, dv) \\
+ & E \sup_{0 \leq u \leq U} \int_0^t \int_Z \left[ |e_\epsilon(s)| + \sqrt{\lambda} \left[ h(s, x_\epsilon(s), x_\epsilon(\delta(s)), v) - \tilde{h}(y(s), y_\epsilon(\delta(s)), v) \right] \right]^p \\
- & |e_\epsilon(s)|^p - p \sqrt{\lambda} |e_\epsilon(s)|^{p-2} e_\epsilon(s)^\top [h(s, x_\epsilon(s), x_\epsilon(\delta(s)), v) \\
- & \tilde{h}(y(s), y_\epsilon(\delta(s)), v)] \right] N(ds, dv) \\
= & p \varepsilon I_1 + J_2 + J_3. \quad (28)
\end{align*} \]

By the Burkholder-Davis-Gundy inequality, there exists a positive constant \( c_p \) such that

\[ J_2 \leq c_p E \left[ \int_0^u \int_Z p^2 \varepsilon |e_\epsilon(t)|^{2p-2} |h(t, x_\epsilon(t), x_\epsilon(\delta(t)), v) \\
- \tilde{h}(y(t), y_\epsilon(\delta(t)), v)|^2 \pi(dv) dt \right]^{\frac{1}{2}} \]

\[ \leq c_p E \left[ \sup_{0 \leq u \leq U} |e_\epsilon(t)|^p \int_0^u \int_Z p^2 \varepsilon |e_\epsilon(t)|^{p-2} |h(t, x_\epsilon(t), x_\epsilon(\delta(t)), v) \\
- \tilde{h}(y(t), y_\epsilon(\delta(t)), v)|^2 \pi(dv) dt \right]^{\frac{1}{2}}. \]

Next, the Young inequality implies that

\[ J_2 \leq c_p \left[ E \sup_{0 \leq u \leq U} |e_\epsilon(t)|^p \right]^{\frac{1}{2}} \left[ \frac{1}{\varepsilon_4} E \int_0^u \int_Z p^2 \varepsilon |e_\epsilon(t)|^{p-2} |h(t, x_\epsilon(t), x_\epsilon(\delta(t)), v) \\
- \tilde{h}(y(t), y_\epsilon(\delta(t)), v)|^2 \pi(dv) dt \right]^{\frac{1}{2}} \]

\[ \leq \frac{c_\varepsilon \varepsilon_4}{2} E \sup_{0 \leq u \leq U} |e_\epsilon(t)|^p + \frac{c_p \varepsilon_4^2}{2} E \int_0^u \int_Z |e_\epsilon(t)|^{p-2} |h(t, x_\epsilon(t), x_\epsilon(\delta(t)), v) \\
- \tilde{h}(y(t), y_\epsilon(\delta(t)), v)|^2 \pi(dv) dt, \]

where \( \varepsilon_4 > 0 \). By setting \( \varepsilon_4 = c_p^{-1} \), we get

\[ J_2 \leq \frac{1}{2} E \sup_{0 \leq u \leq U} |e_\epsilon(t)|^p + \frac{c_\varepsilon \varepsilon_4}{2} E \int_0^u \int_Z |e_\epsilon(t)|^{p-2} |h(t, x_\epsilon(t), x_\epsilon(\delta(t)), v) \\
- \tilde{h}(y(t), y_\epsilon(\delta(t)), v)|^2 \pi(dv) dt. \]

Similar to the estimate of \( I_2 \), we have

\[ J_2 \leq \frac{1}{2} E \sup_{0 \leq u \leq U} |e_\epsilon(t)|^p + c_\varepsilon E \left[ \int_Z (1 + |v|^p) \pi(dv) \right] \int_0^u E \sup_{0 \leq \sigma \leq t} |e_\epsilon(\sigma)|^p dt \\
+ \frac{c_\varepsilon}{2} E \int_0^u \int_Z |h(t, y_\epsilon(t), y_\epsilon(\delta(t)), v) - \tilde{h}(y(t), y_\epsilon(\delta(t)), v)|^p \pi(dv) dt. \]
where \( c_3 = c_2^2 p^2 (1 + \sqrt{2L})^2 \). Condition (H3.3) implies that

\[
J_2 \leq \frac{1}{2} E \sup_{0 \leq t \leq u} |e_\varepsilon(t)|^p + c_3 \left[ \int_Z \left( 1 + |v|^p \right) \pi(\text{d}v) \right] \int_0^u E \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p \text{d}t
+ \frac{c_3}{2} u \varphi_3(u) \left( 1 + E \sup_{-r \leq t \leq 0} |y_\varepsilon(t)|^p + 2E \sup_{0 \leq t \leq u} |y_\varepsilon(t)|^p \right).
\]  

Finally, let us estimate \( J_3 \). Since \( \bar{N}(dt, du) \) is a martingale measure and \( N(dt, du) = \bar{N}(dt, du) + \pi(du) \text{d}t \), we have

\[
J_3 = E \int_0^u \int_Z \left[ f(e_\varepsilon(t) + \bar{h}_\varepsilon(t)) - f(e_\varepsilon(t)) - f'(e_\varepsilon(t)) \bar{h}_\varepsilon(t) \right] \pi(\text{d}v) \text{d}t,
\]

where \( f(x) = |x|^p \) and \( \bar{h}_\varepsilon(t) = \sqrt{\varepsilon} \left[ h(t, x_\varepsilon(t), x_\varepsilon(\delta(t)), v) - \bar{h}(y_\varepsilon(t), y_\varepsilon(\delta(t)), v) \right] \). By the Taylor formula, there exists a positive constant \( M(p) \) such that

\[
f(e_\varepsilon(t) + \bar{h}_\varepsilon(t)) - f(e_\varepsilon(t)) - f'(e_\varepsilon(t)) \bar{h}_\varepsilon(t)
\]

\[
= |e_\varepsilon(t) + \bar{h}_\varepsilon(t)|^p - |e_\varepsilon(t)|^p - p|e_\varepsilon(t)|^{p-2} e_\varepsilon(t) \bar{h}_\varepsilon(t)
\]

\[
\leq M(p) |e_\varepsilon(t) + \bar{h}_\varepsilon(t)|^{p-2} |\bar{h}_\varepsilon(t)|^2.
\]

Applying the basic inequality \(|a + b|^{p-2} \leq 2^{p-3}(|a|^{p-2} + |b|^{p-2})\), we have

\[
J_3 \leq M(p) 2^{p-3} E \int_0^u \int_Z \left[ |e_\varepsilon(t)|^{p-2} |\bar{h}_\varepsilon(t)|^2 + |\bar{h}_\varepsilon(t)|^p \right] \pi(\text{d}v) \text{d}t.
\]

Similar to \( J_3 \), we derive that

\[
J_3 \leq c_4 \varepsilon \left[ \int_Z \left( 1 + |v|^p \right) \pi(\text{d}v) \right] \int_0^u E \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p \text{d}t
+ \frac{c_4}{2} u \varphi_3(u) \left( 1 + E \sup_{-r \leq t \leq 0} |y_\varepsilon(t)|^p + 2E \sup_{0 \leq t \leq u} |y_\varepsilon(t)|^p \right),
\]  

where \( c_4 = 2M(p) 2^{p-3}(1 + \sqrt{2L})^p \). Combing (29) and (30), we have

\[
E \sup_{0 \leq t \leq u} |e_\varepsilon(t)|^p \leq c_5 \varepsilon \int_0^u E \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p \text{d}t
+ c_5 \varepsilon \left( 1 + E \sup_{-r \leq t \leq 0} |y_\varepsilon(t)|^p + 2E \sup_{0 \leq t \leq u} |y_\varepsilon(t)|^p \right),
\]
where
\[
c_5 = 4p(1 + \sqrt{2k_1}) + 2(c_3 + c_4) \left[ \int_{Z} (1 + |v|^p) \pi(dv) \right],
\]
\[
c_6 = 2p(1 + \sqrt{2k_1})u\varphi_1(u) + (c_3 + 2c_4)u\varphi_2(u).
\]

By Theorem 3.1, we have the following fact: for each \( t \geq 0 \), if \( E\|\xi\|^p < \infty \), then \( E|y_\varepsilon(t)|^p < \infty \). Hence, condition (H3.3) implies that
\[
E \sup_{0 \leq t \leq u} |e_\varepsilon(t)|^p \leq c_5\varepsilon(1 + E\|\xi\|^p + 2C) + c_6\varepsilon E \int_{0}^{u} \sup_{0 \leq \sigma \leq t} |e_\varepsilon(\sigma)|^p dt.
\]

By the Gronwall inequality, we obtain
\[
E \sup_{0 \leq t \leq u} |e_\varepsilon(t)|^p \leq c_5\varepsilon(1 + E\|\xi\|^p + 2C)e^{c_6\varepsilon u}.
\]

Consequently, given any number \( \delta_3 \), we can choose \( \varepsilon_3 \in [0, \varepsilon_0] \) such that for each \( \varepsilon \in [0, \varepsilon_3] \) and for \( t \in [0, L\varepsilon^{-\beta}] \),
\[
E \sup_{t \in [0,L\varepsilon^{-\beta}]} |x_\varepsilon(t) - y_\varepsilon(t)|^p \leq \delta_3.
\]

The proof is completed. \( \Box \)

Similarly, we have the following results as regards the convergence in probability between \( x_\varepsilon(t) \) and \( y_\varepsilon(t) \).

**Corollary 3.1** Let the conditions (H2.1) and (H3.1)-(H3.3) hold. For a given arbitrary small number \( \delta_4 > 0 \), there exists \( \varepsilon_4 \in [0, \varepsilon_0] \) such that for all \( \varepsilon \in [0, \varepsilon_4] \), we have
\[
\lim_{\varepsilon \to 0} P\left( \sup_{0 \leq t \leq L\varepsilon^{-\beta}} |x_\varepsilon(t) - y_\varepsilon(t)| > \delta_4 \right) = 0,
\]
where \( L \) and \( \beta \) are defined by Theorem 3.2.

**Remark 3.1** When the time delay \( \delta(t) = t \), (19) will reduce to SDEs with jumps, which have been studied by [11–14]. In particularly, if \( p = 2 \) in (25), then we have the mean-square sense convergence of the standard solution of (23) and the averaged solution of (24). So the corresponding results in [11–14] are generalized and improved.

**Remark 3.2** In [10], Tan and Lei studied the averaging method for SDDEs under non-Lipschitz conditions. In particular, we see that the Lipschitz condition is a special case of non-Lipschitz conditions which are studied by many scholars [20–23]. Similarly, by applying the proof of Theorem 3.2, we can prove the standard solution of (23) converges to the averaged solution of (24) in the \( p \)th moment under non-Lipschitz conditions. In other words, we obtain a more general result on the averaging principle for SDDEs with jumps than Theorem 3.2.
4 Examples

In this section, we construct two examples to demonstrate the averaging principle results.

Example 4.1 Let \( \tilde{N}(dt, dv) \) be a compensated Poisson random measures and is given by

\[
\pi(du) dt = \lambda f(v) dv dt,
\]

where \( \lambda > 0 \) is a constant and

\[
f(v) = \frac{1}{\sqrt{2\pi v}} e^{-\frac{\ln v^2}{2}},
\]

is the density function of a lognormal random variable. Consider the following SDEs with pure jumps:

\[
dx(t) = \varepsilon f(t, x(t)) dt + \sqrt{\varepsilon} \int_0^\infty \phi(v) h(t, x(t)) \tilde{N}(dt, dv),
\]

with initial data \( x(0) = x_0 \), where \( \delta(t) = t \). Here \( f(t, x(t)) = \sin tx(t) \) and \( h(t, x(t)) = -x(t) \log x(t) \). Let

\[
\tilde{f}(t, y(t)) = \frac{1}{\pi} \int_0^\pi f(t, y(t)) dt = \frac{2}{\pi} y(t)
\]

and

\[
\tilde{h}(t, y(t), v) = \frac{1}{\pi} \int_0^\pi \phi(v) h(t, y(t)) dt = -\phi(v) y(t) \log y(t).
\]

Hence, we have the corresponding averaged SDEs with pure jumps

\[
dy(t) = \frac{2}{\pi} \tilde{f}(t, y(t)) dt - \sqrt{\varepsilon} \int_0^\infty \phi(v) \tilde{h}(t, y(t), v) \tilde{N}(dt, dv).
\]

Now, we impose the non-Lipschitz condition on (32).

(H4.1) For all \( x, y \in \mathbb{R}^n \), \( v \in \mathbb{Z} \), and \( p \geq 2 \),

\[
|f(t, x) - f(t, y)|^p \vee \int_{\mathbb{Z}} |h(t, x, v) - h(t, y, v)|^p \pi(dv) \leq \rho(|x - y|^p),
\]

where \( \rho(\cdot) \) is a concave nondecreasing function from \( \mathbb{R}_+ \) to \( \mathbb{R}_+ \) such that \( \rho(0) = 0, \rho(u) > 0 \) for \( u > 0 \) and \( \int_0^1 \frac{du}{\rho(u)} = \infty \).

Let us return to (32). It is easy to see that \( h(t, \cdot) \) is a nondecreasing, positive and concave function on \([0, \infty]\) with \( h(t, 0) = 0 \). Moreover, by a straightforward computation, we have

\[
\int_0^1 \frac{1}{h(t, u)} du = -\int_0^1 \frac{1}{u \log u} du = -\lim_{t \to 0} \int_x^1 \frac{1}{u \log u} du = -\lim_{t \to 0} \int_0^\infty \frac{1}{v} dv = \infty.
\]

Hence, the coefficients of (32) and (33) satisfy our condition (H4.1). Similar to the proof of [20–23], we find that (32) and (33) have unique solutions in \( L^p \), \( p \geq 2 \), respectively.

Similar to the proof of Theorem 3.2, we find that the standard solution of (32) converges to the averaged solution of (33) in the sense of the \( p \)th moment.
**Corollary 4.1** Let the conditions (H2.2), (H3.3), and (H4.1) hold and \( \delta(t) = t \). For a given arbitrary small number \( \delta_5 > 0 \) and \( p \geq 2 \), there exist \( L > 0 \), \( \varepsilon \in (0, \varepsilon_0] \), and \( \beta \in (0, 1) \) such that

\[
E|x_\varepsilon(t) - y_\varepsilon(t)|^p \leq \delta_5, \quad \forall t \in [0, Le^{-\beta}],
\]

for all \( \varepsilon \in (0, \varepsilon_5] \).

The proof of Corollary 4.1 is given in the Appendix.

**Remark 4.1** Similarly to Corollary 4.1, we can show the convergence in probability of the standard solution of (32) and the averaged solution of (33).

**Example 4.2** Let \( w_t \) be a one-dimensional Brownian motion and the compensated Poisson random measure \( \tilde{N}(dt, dv) \) is defined by Example 4.1. Of course \( \tilde{N}(dt, dv) \) and \( w_t \) are assumed to be independent. Consider the following linear SDDEs with jumps:

\[
\begin{align*}
\quad dx_\varepsilon(t) &= \varepsilon [ax_\varepsilon(t) + bx_\varepsilon(t - \tau)] dt + 2\sqrt{\varepsilon} \sin^2 \tau x_\varepsilon(t - \tau) dw_t \\
&\quad + c\sqrt{\varepsilon} \int_0^\infty v\varepsilon(t)\tilde{N}(dt, dv),
\end{align*}
\]

with initial data \( x_\varepsilon(t) = \xi(t) \), when \( t \in [-\tau, 0] \), \( \tau \) is a fixed delay, where \( \delta(t) = t - \tau \), \( T = N\tau \), \( N \in \mathbb{Z}^+ \), \( a, b, c \in \mathbb{R} \). Here

\[
\begin{align*}
\quad f(t, x_\varepsilon(t), x_\varepsilon(t - \tau)) &= ax_\varepsilon(t) + bx_\varepsilon(t - \tau), \\
\quad g(t, x_\varepsilon(t), x_\varepsilon(t - \tau)) &= 2\sqrt{\varepsilon} \sin^2 \tau x_\varepsilon(t - \tau)
\end{align*}
\]

and

\[
\quad h(t, x_\varepsilon(t), x_\varepsilon(t - \tau), \nu) = cvx_\varepsilon(t).
\]

Let

\[
\begin{align*}
\quad \tilde{f}(y_\varepsilon(t), y_\varepsilon(t - \tau)) &= \frac{1}{\pi} \int_0^\pi f(t, y_\varepsilon(t), y_\varepsilon(t - \tau)) dt = ay_\varepsilon(t) + by_\varepsilon(t - \tau), \\
\quad \tilde{g}(y_\varepsilon(t), y_\varepsilon(t - \tau)) &= \frac{1}{\pi} \int_0^\pi g(t, y_\varepsilon(t), y_\varepsilon(t - \tau)) dt = y_\varepsilon(t - \tau), \\
\quad \tilde{h}(y_\varepsilon(t), y_\varepsilon(t - \tau), \nu) &= \frac{1}{\pi} \int_0^\pi h(t, y_\varepsilon(t), y_\varepsilon(t - \tau), \nu) dt = cvy_\varepsilon(t).
\end{align*}
\]

Hence, we have the corresponding averaged SDDEs with jumps

\[
\begin{align*}
\quad dy_\varepsilon(t) &= \varepsilon [ay_\varepsilon(t) + by_\varepsilon(t - \tau)] dt + \sqrt{\varepsilon} y_\varepsilon(t - \tau) dw_t \\
&\quad + c\sqrt{\varepsilon} \int_0^\infty vy_\varepsilon(t)\tilde{N}(dt, dv).
\end{align*}
\]

When \( t \in [0, \tau] \), the explicit solution of SDDEs with jumps is given by

\[
\begin{align*}
\quad y_\varepsilon(t) &= \phi_0(t) \left\{ \xi(0) + \varepsilon b \int_0^\tau \phi_0^{-1}(s)\xi(s - \tau) ds + \sqrt{\varepsilon} \int_0^\tau \phi_0^{-1}(s)\xi(s - \tau) dw_s \right\},
\end{align*}
\]
where
\[
\phi_0(t) = \exp \left\{ at + \int_0^t \int_0^\infty \left[ \ln (1 + c \sqrt{v}) - c \sqrt{v} \right] \pi (dv) \, ds \right. \\
+ \left. \int_0^t \int_0^\infty \ln (1 + c \sqrt{v}) \tilde{N}(dt, dv) \right\}.
\]

When \( t \in [\tau, 2\tau] \), the explicit solution of SDDEs with jumps is given by
\[
y_n(t) = \phi_\tau(t) \left\{ y_\tau(t) + \varepsilon b \int_\tau^t \phi_\tau^{-1}(s) y_n(s - \tau) \, ds + \sqrt{\varepsilon} \int_\tau^t \phi_\tau^{-1}(s) y_n(s - \tau) \, dw_s \right\},
\]
where
\[
\phi_\tau(t) = \exp \left\{ at - \int_\tau^t \int_0^\infty \left[ \ln (1 + c \sqrt{v}) - c \sqrt{v} \right] \pi (dv) \, ds \right. \\
+ \left. \int_\tau^t \int_0^\infty \ln (1 + c \sqrt{v}) \tilde{N}(dt, dv) \right\}.
\]

Repeating this procedure over the interval \([\tau, 3\tau], [3\tau, 4\tau], \text{etc.}\) we can obtain the explicit solution \( y_n(t) \) on the entire interval \([0, T]\). On the other hand, it is easy to find that the conditions of Theorems 2.2 and 3.2 are satisfied, so the solution of averaged SDDEs with jumps (36) will converge to that of the standard SDDEs with jumps (37) in the sense of the \( p \)th moment and in probability.

5 Conclusion
In this paper, we study the averaging method for SDDEs and SDDEs with pure jumps. By applying the Itô formula, the Taylor formula, and the BDG inequality, we prove that the solution of the averaged SDDEs converges to that of the standard SDDEs in the sense of the \( p \)th moment and also in probability. Finally, two examples are provided to demonstrate the proposed results.

Appendix

Proof of Theorem 2.1 Let \( x^n(t) = \xi(0) \) for \( t \in [0, T] \) and define the sequence of successive approximations to (1)
\[
x^n(t) = \xi(0) + \int_0^t f(s, x^{n-1}(s), x^{n-1}(\delta(s))) \, ds + \int_0^t g(s, x^{n-1}(s), x^{n-1}(\delta(s))) \, dw_s.
\]

The proof will be split into the following steps.

Step 1. Let us show that \( \{x^n(t)\}_{n \geq 1} \) is bounded. Let \( f^n(t) = f(t, x^n(t), x^n(\delta(t))), g^n(t) = g(t, x^n(t), x^n(\delta(t))) \). From (40), by the inequality \( |a + b + c|^p \leq 3^{p-1}(|a|^p + |b|^p + |c|^p) \), we have
\[
E \sup_{0 \leq s \leq t} |x^n(s)|^p \leq 3^{p-1}E \|\xi\|^p + 3^{p-1}E \left[ \int_0^t |f^n_s| \, ds \right]^p + 3^{p-1}E \sup_{0 \leq s \leq t} \left| \int_0^s g^n_{\sigma} \, dw_\sigma \right|^p.
\]

Using the Hölder inequality and the BDG inequality, we get
\[
E \sup_{0 \leq s \leq t} |x^n(s)|^p \leq 3^{p-1}E \|\xi\|^p + 3^{p-1}E \int_0^t |f^n_s| \, ds + 3^{p-1}E \int_0^t |g^n_{\sigma}| \, dw_\sigma.
\]
By condition (H2.1), we obtain

\[ E \sup_{0 \leq s \leq t} |x^p(s)|^p \leq c_1 + c_2 \int_0^t E \sup_{0 \leq \sigma \leq s} |x^p(t)|^p \, ds. \]

For any \( r \geq 1 \), we have

\[ \max_{1 \leq n \leq r} E \sup_{0 \leq t \leq s} |x^p(s)|^p \leq c_1 + c_2 E \| \xi \|_p^p + \max_{1 \leq n \leq r} E \sup_{0 \leq \sigma \leq s} |x^p(t)|^p \, ds. \]

From the Gronwall inequality, we derive that

\[ E \sup_{0 \leq t \leq T} |x^p(t)|^p \leq (c_1 + c_2 T E \| \xi \|_p^p) e^{c_2(T)}. \]

**Step 2.** Let us show that \( \{x^p(t)\}_{n \geq 1} \) is Cauchy. For \( n \geq 1 \) and \( t \in [0, T] \), we derive that, from (40),

\[ x^{n+1}(t) - x^n(t) = \int_0^t f^{n,n-1}_s \, ds + \int_0^t g^{n,n-1}_s \, dw_s, \]

where

\[ f^{n,n-1}_s = f(s, x^n(s), x^n(\delta(s))) - f(s, x^{n-1}(s), x^{n-1}(\delta(s))), \]

\[ g^{n,n-1}_s = g(s, x^n(s), x^n(\delta(s))) - g(s, x^{n-1}(s), x^{n-1}(\delta(s))). \]

By the Hölder inequality and the BDG inequality, we have

\[ E \left( \sup_{0 \leq s \leq t} |x^{n+1}_s(s) - x^n(s)|^p \right) \leq c_3 \int_0^t E \left( \sup_{0 \leq \sigma \leq s} |x^n(\sigma) - x^{n-1}(\sigma)|^p \right) \, ds. \]

Setting \( \varphi_n(t) = E \sup_{0 \leq s \leq t} |x^{n+1}(s) - x^n(s)|^p \), we have

\[
\begin{align*}
\varphi_n(t) & \leq c_3 \int_0^t \varphi_{n-1}(s_1) \, ds_1 \leq c_3^2 \int_0^t ds_1 \int_0^{s_1} \varphi_{n-2}(s_2) \, ds_2 \\
& \leq \cdots \\
& \leq c_3^n \int_0^t ds_1 \int_0^{s_1} ds_2 \cdots \int_0^{s_{n-1}} \varphi_0(s_n) \, ds_n. 
\end{align*}
\]

(41)

By (41) and \( \varphi_0(t) \leq c_4 K E \| \xi \|_p = \tilde{c}_4 \), we obtain

\[ E \left( \sup_{0 \leq s \leq t} |x^{n+1}(s) - x^n(s)|^p \right) \leq \tilde{c}_4 \frac{(c_4 t)^n}{n!}. \]

(42)

Hence (42) implies that for each \( t \), \( \{x^p(t)\}_{n \geq 1} \) is a Cauchy sequence on \([t_0, T]\).

**Step 3. Uniqueness.** Let \( x(t) \) and \( y(t) \) be two solutions of (1). Then, for \( t \in [0, T] \), we have

\[ E \sup_{0 \leq s \leq t} |x(s) - y(s)|^p \leq c \int_0^t E \sup_{0 \leq u \leq s} |x(u) - y(u)|^p \, ds. \]

(42)
Therefore, the Gronwall inequality implies
\[ E \sup_{0 \leq s \leq t} |x(s) - y(s)|^p = 0, \quad t \in [t_0, T]. \]

The above expression means that \( x(t) = y(t) \) for all \( t \in [0, T] \).

**Existence.** We derive from (42) that \( \{x^n(t)\}_{n=1,2,...} \) is a Cauchy sequence. Hence there exists a unique \( x(t) \) such that \( x^n(t) \to x(t) \) as \( n \to \infty \). For all \( t \in [0, T] \), taking the limits on both sides of (40) and letting \( n \to \infty \), we then can show that \( x(t) \) is the solution of (1). So the proof of Theorem 2.1 is complete. \( \square \)

**Proof of Corollary 4.1** The key technique to prove this corollary is already presented in the proofs of Theorems 2.2 and 3.2, so we here only highlight some parts which need to be modified. We use the same notations as in the proofs of Theorems 2.2 and 3.2. It is easy to see that inequality (11) should become

\[
|f(t, x_t(t)) - \tilde{f}(y_t(t))|^p \leq \left[ 1 + \epsilon_2^{\frac{1}{p-1}} \right]^{p-1} \left( \frac{1}{\epsilon_2} \rho \big( |x_t(t) - y_t(t)|^p \big) \right) + |f(t, y_t(t)) - \tilde{f}(y_t(t))|^p. \tag{43}
\]

In fact, since the function \( \rho(\cdot) \) is concave and increasing, there must exist a positive number \( k^p \) such that

\[ \rho(x) \leq k^p(1 + x), \quad \text{on } x \geq 0. \]

Hence,

\[
|f(t, x_t(t)) - \tilde{f}(y_t(t))|^p \leq \left[ 1 + \epsilon_2^{\frac{1}{p-1}} \right]^{p-1} \left( \frac{k^p}{\epsilon_2} (1 + |x_t(t) - y_t(t)|^p) \right) + |f(t, y_t(t)) - \tilde{f}(y_t(t))|^p.
\]

Letting \( \epsilon_2 = k^{p-1} \), we get

\[
|f(t, x_t(t)) - \tilde{f}(y_t(t))|^p \leq (1 + k)^{p-1} \left[ k(1 + |x_t(t) - y_t(t)|^p) \right] + |f(t, y_t(t)) - \tilde{f}(y_t(t))|^p. \tag{44}
\]

Inserting (44) into (43), it follows that

\[
I_1 \leq E \int_0^u \left\{ \left( \frac{p-1}{p} \epsilon_1 \right)^p |e_t(t)|^p + \frac{1}{p-1} \left[ k(1 + |e_t(t)|^p) \right] \right\} dt.
\]

By setting \( \epsilon_1 = 1 + k \), we have

\[
I_1 \leq 2(1 + k)E \int_0^u (1 + |e_t(t)|^p) dt + E \int_0^u |f(t, y_t(t)) - \tilde{f}(y_t(t))|^p dt.
\]
Similarly, $J_2$ and $J_3$ can be estimated as $I_i$. Finally, all of required assertions can be obtained in the same way as the proof of Theorems 2.2 and 3.2. The proof is therefore complete.

Competing interests
The authors declare that they have no competing interests.

Authors' contributions
All authors contributed equally to the manuscript and typed, read and approved the final manuscript.

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