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Fog-Cloud Computing Traffic Model Affecting the Occurrence of Latency on the Ubiquitous Sensor Network

Chonnikan Sangmek\(^1\) and Nathaphon Boonnam\(^2\)*

**Abstract**

The fog-cloud computing traffic model overviews working elements in forming fog-cloud computing with three main layers: Ubiquitous Sensor Networks, Fog Computing, and Cloud Computing. We present a possible method of data transmission that focuses on either measuring or manipulating or both in the system divided into 7 USNs and using latency measurement to demonstrate transmission efficiency. This paper considers the latency test into four prominent cases: internet connection, traffic model, number of devices, and packet by equipment used for testing consisting of microcontroller board, sensor, actuator, and uses fog node two types: pocket Wi-Fi and router. In the latency test, we found that the factor causing the higher latency in the system was the packet size. The main factor consists of the different characteristics of working, fog nodes, and the number of connected devices. Therefore, the packet has correlated directly with the latency depending on the size of the packet increases. The resulting latency is the main factor affecting the work of the system.

**Keywords:** Ubiquitous Sensor Network; Fog-Cloud Computing; Traffic Model; Latency; Packet

**Introduction**

At present, the technology has been applied in diverse forms to improve productivity and labor reduction. One of the critical technologies playing a role for a future network is an Internet of Things (IoT) [4], which has the Ubiquitous Sensor Network (USN) as one of the general IoT components [3]. The type of USNs is always the most concerned part of users. When researchers selected the USNs type, it does not fit the system control requirements as it may cause problems. USNs are essential to controlling, measuring, and storing data in the system. The majority of the mechanism for the control system is the microcontroller board. One uses as an intermediary to controlling the sensor or actuator for measuring and manipulating. When the sensor or actuator has worked together with the microcontroller board representing the characteristic of USNs, there have different kinds of measuring and manipulating in wireless type. We divided 7 USNs from the working of three communication protocols consisting of CoAP, MQTT, and RxTx; it has presented in the form of architecture design [6]. Latency is a problem occurring with data transmission performance in each USNs by things that affect the system’s operation, such as latency of command for controlling, sending, receiving, and storing data. They harm productivity that requires automatic control. In addition, performance
evaluation of latency in the data transmission is the thing that tells us to factors affecting the operation of the system.

The concept of this paper has focused on the latency that occurs in measuring, manipulating, or data transmission in each USNs of the fog-cloud computing traffic model. The characteristics of working are the main factor effect with the occur latency in the USNs. The latency test has a method to test data transmission from the literature review by using USNs according to the actual use in the trial. The latency test divides into four prominent cases: internet connection, traffic model, number of devices, and packet. The forecasting of these working patterns may be a factor in the high latency in each USNs which may cause problems in the automatic controls system. This paper is focused on presenting the factors affecting latency and improved the fog-cloud computing traffic model for an extension of the research on [6]. We studied many related works for ubiquitous sensor networks, fog-cloud computing traffic model, a factor associated with the latency, and currently presenting the improved fog-cloud computing architecture design of USNs. The latency test of the traffic model had used two types of fog node connections: a mobile pocket Wi-Fi and a router via testing four cases consisting of the latency test of internet connection, traffic model, the number of devices, and a packet. Finally, we concluded the factors affecting the occur latency in the representation of our traffic model.

Related Works
Andrey K and Andrey P (2011) described the internet of things as a future network concept. There is no clear IoT definition today. However, IoT includes the Ubiquitous Sensor Network (USN) and Web of Things (WoT). Essential USN applications include building automation, industrial automation, logistics, transportation, body, intrabody sensor nodes and RFIDs, military, agriculture, environment data, and related applications. The USN is one of the general IoT components. The IoT bases on the USN because IoT composes of a tremendously huge number of nodes [5]. So they studied the USN traffic models well. ITU-T identified that USNs describe networks of intelligent sensor nodes that could be deployed ”anywhere, anytime, by anyone and anything.” The technology has tremendous potential as it could generate applications such as a wide range of civilian and military fields, environment and habitat monitoring, real-time healthcare, landmine detection, and intelligent transport systems. The USN identifies a layer of equipment that collects interest data [2].

Josef H et al. (2016) tested the packets between the station nodes that were interconnected using a wireless network to determine latency. It depends on the size of data with data transmission between the device and the internet service provider. The test had the measurement of latency repeated 100 times for each time measurement 200 packets. They had explained that the measure of latency in wireless networks depends on the size of the transmitted data by parameters of wireless networks. Commonly measured parameters are throughput, latency, available capacity, capacity, signal to noise ratio, and received signal level. Latency is an important performance parameter of wireless networks defined as the elapsed time. The source node sends a message to receive a message on the destination node expressed in milliseconds, including delays within the transmission protocol and holds on devices’
working. However, the latency did not affect the quality of the transmitted data. On the other hand, high latency can significantly affect the quality of work with a data connection to the network because of the latency causing a longer response time interval.

Sabin B et al. (2017) tested the latency of devices that prioritized and non-prioritized the number of 100 nodes. They found that the system that improved the latency by prioritized has more reliability than the non-prioritized scheme, and the number of nodes increased the higher latency. The internet of things networks had used a vast number of sensor or actuator nodes for different monitoring and sensing purposes [13]. In real-world IoT applications, they planned to applied network simulator tools to analyze the performance of the proposed scheme having corresponded [15].

Sucharitha V et al. (2019) identified that the fog topology is one thing that mitigates the scope for congestion in the network and reduces the negative impacts on the response time due to the increase in the size of the topology when the addition of more devices. They sustainably postulate that the fog-based model was desirable for adoption because it supported effective scalability with reduced latency and better response time. Data storage from sensor devices imports into cloud services having number increasing steadily. It made the data transmission or data management respond the sake on the Internet of Things (IoT) that may be a delay in handling the data sending to the cloud service [14]. Cloud computing collaborating with fog computing, which is between the device on the edge network with the cloud center, offers a more efficient solution to deal with these limitations. Fog computing is architecture geographically distributed computing with the various devices in the different edge network connecting ubiquitously to provide flexible management for computing, communications, and storage [14]. The most foremost characteristic of fog computing is the extension of the cloud service to the edge network and the connection from the users to the cloud.

Chonnikan S and Nathaphon B (2019) presented a ubiquitous sensor network that can occur from the sensor or actuator at least one device connects with a microcontroller board. They explained the details of the situation with the microcontroller board to define the fog-cloud computing traffic model in wireless type to measure, manipulate, or work together. They had divided the traffic model for transmission data of microcontroller board into 7 USNs in the form architecture design [6]. There have many examples to create USN fog-cloud traffic model and expanding USNs [7],[10],[12]. The traffic model was a structure in each step for creating a suitable system into USNs in wireless type data transmission via the cloud service. When they had built a wireless sensor network in a ubiquitous sensor network, it was required to use the fog computing layer as an intermediary to transmission data and a microcontrollers board [1]. They found the results from a latency test of each traffic model having the factor that affected the system consisting of the different working requirements in the traffic model and many connections devices keeping high latency.

Therefore, in this paper, we offer the fog-cloud computing traffic model that new improvement from [6]. This study will support users for noticing the working and components of USNs in an easy-to-understand format and use USNs suitable according to the requirement of the system for measuring and manipulating. We
divided the testing of latency in wireless networks affecting the speed of data transmission from the related work above consisting of different working, the number of nodes increased, network connection, and size of the sent data or packet (see also [6],[9],[13],[15]). We realize the factors related to latency on the ubiquitous sensor network having details in the next section.

**Fog-Cloud Computing Traffic Model**

This section is an improvement of the fog-cloud computing traffic model from [6]. The improved traffic model has a format that is easier to understand than the old version and helps users know the working and components of USNs. We present the usage of microcontroller boards in the wireless types to send data from the ubiquitous sensor network layer via the fog computing layer for storing data to the cloud computing layer in the form of possible USNs. The fog computing and cloud computing layers had to work simultaneously to distribute the internet signal to send data to store and display data into the cloud computing layer. It had the operation essentially three components of the system: the ubiquitous sensor network, fog computing, and cloud computing for measuring and manipulating by emphasizing processes in the wireless type as shown in Figure 1.

![Figure 1 Fog-Cloud Computing Traffic Model](image)

We present an overview of working elements in the form of fog-cloud computing having three main layers. These consist of ubiquitous sensor networks, fog computing, and cloud computing for measuring and manipulating by emphasizing operation in wireless type. The ubiquitous sensor networks layer is the bottom-most layer responsible for measuring, manipulating, collecting, and sending data to the fog node in the fog computing layer. The fog computing layer is the intermediate layer that can reduce the latency for sending data to cloud computing when using fog nodes with a powerful internet signal. The cloud computing layer is the top layer that can display real-time data, data storage, notification, and control system via app or web with details of each layer as follows:
USN Layer

There was a demonstration of possible usage models for measuring or manipulating controlled by the board microcontroller in a wireless type. The usability of all proposed based on consideration from applying the scenario happened to present in the traffic model dividing into 7 USNs. Three usability types consisted of CoAP, MQTT, and RxTx, which control seven traffic models from practical applications. USN 1 to 7 represents the node or board microcontroller, and ≥ represents the number of user devices that may be one or more than one device, such as sensor ≥ one and actuator ≥ one, respectively.

1 CoAP consists of 3 USNs: USN 1 was a measurement that used sensor devices for only store data; USN 2 was measurement and manipulation that used a sensor device for measuring and sensor values for controlling the actuator; USN 3 was manipulating using the values received from the analysis or custom values to control the actuator.

2 MQTT consists of 3 USNs: USN 4 was a manipulation that used a microcontroller board for transmitted data receiving from sensor devices to data storage and transceiving data into MQTT broker as an intermediary control the actuator to operate according to the measured values from the sensor device or according to custom values; USN 5 was measurement and manipulation that installed a sensor device or actuator to work together with the microcontroller board for notification through the application or web; USN 6 was manipulation the system that used controlling the microcontroller board through the application or web.

3 RxTx consists of 1 USN: USN 7 was manipulation to connect type wired between microcontroller boards via RxTx channel to control the actuator in the system.

Fog Computing Layer

According to the USN layer’s actual use, the application layer has three operations types: CoAP, MQTT, and RxTx. The network layer focused on using connections from the board microcontroller via Wi-Fi signal; therefore, the connection type was wireless for connecting to the fog node in the form of a router. It distributed the Wi-Fi signal to devices used to measure or manipulate and transmit data into the cloud computing layer.

Cloud Computing Layer

We presented the deployment models in the cloud computing layer in a private cloud used only for organizations or personal. The user permanently accesses the system data to manage and use the system. We focused on PaaS services, free platforms that users can use privately, or set access rights for relevant people. The system brings the data stored in the form of a .csv file or the other formats to use in the analysis for managing the system and use the real-time display via the free platform service. Without wasting time creating your platform and using the service via platforms for displaying real-time data, the user may create the applications or web as appropriate for use.

The above details are part of the characteristics of the improved fog-cloud computing traffic model in the USN’s layer. It is an improvement picture from research
presented in 2019 [6] to show the correct attributes according to the actual use and to make it easier for users to understand the operation.

**The Latency Test of Ubiquitous Sensor Networks**

We evaluated the data transmission efficiency for each USN to find conclusions from a literature review about latency tests stating that latency is an important performance parameter for wireless networks [9]. It is a factor that directly affects or not because other additional factors may affect the data transmission efficiency. This paper focused on the four factors mentioned in the Related Works section with the actual situation as shown in Figure 2.

![Figure 2 Implementation in Different Situations with Device](image)

The latency test had used the Arduino IDE program to set the command program for testing and run the command program to the ESP8266 board. It is the main board for working and transmitting data received from the sensor and actuators.
according to the characteristics work of each USNs and used the cloud services that are available for free [11]. Five platforms were available for free consisting of Ubidots, ThingSpeak™, Xively, Plotly, and Timbits. When we considered in suitable cloud service, ThingSpeak™ was selected because we can use it for real-time data visualization, store data in .csv file format, and available for free. In addition, as the notification, we used LINE Notify and Blynk applications for sending message and control USN, respectively.

This paper has differed from [6] as we used two types of fog node connections consisting of pocket Wi-Fi and a router. In the previous article, we only used pocket Wi-Fi to connect to the microcontroller board. There are 4 cases of data transmission efficiency testing, consisting of (1) the latency test of internet connection, (2) the latency test of traffic model, (3) the latency test of the number of devices, and (4) the latency test of a packet. The test results on all four topics, we are aware of the problems and factors affecting the occurrence of high latency for each usage form which can be summarized as follows:

The Latency of Internet Connection
The latency test of an internet connection is a test to compare the efficiency of the nodes divided into two sets of work differences, including the node disconnecting with the sensor or actuator and the node connected to the sensor or actuator. There were three types for testing:
1. The node is connected to the fog node to send data into the cloud service.
2. The node had connected to the fog node but no store data.
3. The node has no connection to the internet but uses the display through the serial monitor of Arduino IDE.

There are details for the test results as follows.

Send Data to Cloud Service
The internet connection with pocket Wi-Fi had the latency in the range 2,010-2,150 ms., which is higher than connecting with a router in the range 2,010-2,050 ms. The nodes connected to sensors have a higher latency than the otherwise ones, as shown in Figure 3.

Figure 3 The Latency of Send Data to Cloud Service via Pocket Wi-Fi and Router
Connection to Fog Node and Node that Non-connect to the Fog Node

We did not send data to the cloud service but connected to the fog node resulting in reduced latency, and the nodes connected to sensors had high latency. There had no connection to the fog node. We found that the nodes connected to the sensor devices still had a higher latency, as shown in Figure 4.

![Figure 4](image)

The Latency Test of Traffic Model

We tested the different features of 7 USNs to compare the transmission performance for each USNs by connecting the device according to the USNs characteristics specifying in the fog-cloud computing traffic model. We have divided the test into two cases using a connection via pocket Wi-Fi and a router. The result shows pocket Wi-Fi having latency in the range of 2,000-6,500 ms, and the router has latency in 2,000-5,000 ms, respectively. In the comparison, we found that the router is working efficiently than the pocket Wi-Fi because it reduced the latency occurring for each traffic model in different according to tasking and acts as an intermediary that affects the increase and decrease of latency, as shown in Figure 5.

![Figure 5](image)

The specified sensors or actuators in USNs can be connected to the microcontroller board from 1 device, supporting the entire operation. Here, we used the ESP8266 board working with a maximum of 7 sensors to test four sets for comparing the data transmission efficiency. Each connection time increases the number of devices. The result shows pocket Wi-Fi having a latency range of 2,050-2,350 ms, and the router has a latency range of 2,020-2,080 ms, respectively. We found that
increasing the number of devices is causes the latency value to change. The router is the intermediate that causes the latency to increase and decrease as the internet connection and the traffic model test. So, the latency test depending on the number of devices that have used fog node two types that different found that the router has low latency, as shown in Figure 6.

**Figure 6** The Result of Latency Test the Increased the Number of Devices via Pocket Wi-Fi and Router

The Latency Test of a Packet
We used packets transmitted results in the range 200-1,600 packets [9] expecting to be a stable period of packet transmission. We found that working characteristics, the number of devices, and the fog node are factors causing the different data sizes. According to the fog node, the resulting latency would have increased if we increased the data size, as shown in Figure 7.

**Figure 7** Test of Packet via Pocket Wi-Fi and Router

Factors Affecting the Occur Latency in the System
From the above results, we can conclude that three factors affected the efficiency of data transmission in the system: (1) the different working characteristics, (2) the number of sensors or actuators connected to the node, and (3) the fog node that used a connection between USN and cloud computing. It had affected the size of
the packet occurring when we increased the size of the data; there will be increased latency accordingly.

The r-squared value of the number of devices was the suitable model since the latency occurs from the changes in the packet size, about 99.98% having an r-squared value in the acceptable range. The r-squared value is between 0-1 and should approach 1, which is generally extraordinary. The sufficient value should be more than 0.8. Therefore, if we want to predict the latency when the packet size increases, we must use the linear regression equation:

\[ \text{Latency} = (10.222 \times \text{Packet}) - 3.7449. \]

Proving the relation of the packet with latency, we had compared data the size of a packet using fog node in router type due with low latency in the range of 200, 400, 600, and up to 1600. We used data from the latency test of a packet that occurs by the number of devices in use from devices 1 to 7 to compare and display data in the type of box plot graphs. We found that packet size increases had resulted in high latency as well. We can conclude that the packet and latency had related, as shown in Figure 8.

![Figure 8 Relationship of Packet and Latency Concerning Number of Devices](image)

We can summarize the cause that affects the occurrence latency in the system, which had detail as follows.

1. The fog node has contributed to the latency reduction.
2. The characteristic of working has contributed to the latency that different.
3. The number of devices is the reason that causes higher latency when it has an equipment connection massively.
4. The characteristic of working and the number of devices that use has affected the size of the packet.
5. The size of the packet has affects the occurrence latency.
Conclusion and Discussion

We have shown that the fog–cloud computing traffic model utilized the benefit for measuring or manipulating and deploying according to the actual use in wireless type. We have improved the image of the fog-cloud computing traffic model to make it easier for users to understand the operation from the picture. There was a consideration from the actual working divided into 7 USNs from three communication protocols: CoAP, MQTT, and RxTx. The traffic model is a method that helps users understand the type of system and data management that we can deploy for working actual use. We have also presented latency that affects the operation of the traffic model. The latency test of our previous research has split the latency test into two types: the latency of traffic model and the latency depending on the number of devices and used fog node from the pocket Wi-Fi only. In this paper, we have used fog nodes, two different types, to compare the performance of the transmits of data via four cases of data transmission efficiency testing. It consists of the latency test of internet connection, the latency test of traffic model, the latency test depending on the number of devices, and the latency test of a packet.

We found that the size of the packet affects the latency from three main factors that result in the size of the packet increase consisting of characteristics of work, number of devices, and fog node. The size of a packet is an essential factor that affects the increased latency because the size of a packet that increases will result in a latency increase. The high latency has affected the quality of working in the system. The user needs to have a method to manage the latency that occurs in the system by using the traffic model suitable for working through the fog-cloud computing to use fog nodes and mist computing help with system operations and reduce latency in the system. The fog node is a vital intermediary for sending data between the USN and cloud computing layers. It can help the control system operate efficiently and without problems for measuring and manipulating the system.

The fog-cloud computing traffic model is a new knowledge from this research that supports users to understand the model of USNs for measuring and manipulating before working actual use. The latency test plays an essential role in the traffic model in that users or developers can define the number of devices in an appropriate area. Therefore, we must find the efficiency of signal distribution per area to determine equipment installation distance in the future. The important is for the user to understand the working of USN on the fog-cloud computing traffic model before implementing and designing the system to deployment for controlling USN according to the requirement and resulting in the system having good working efficiency, appropriate control, and works on USN.

Declarations

Availability of data and materials
The data used to support the findings of this study are available from the corresponding author upon request.

Competing interests
The authors declare that they have no competing interests.
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Authors’ contributions
This paper is completed under the supervision of author NB. CS wrote the paper and is responsible for the test and the architecture design. The grammar of the paper was reviewed and modified by NB. Finally, NB gives some modification suggestions. All authors have read and approved the final manuscript.

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