Point Source Confusion in SZ Cluster Surveys

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Abstract. We examine the effect of point source confusion on cluster detection in Sunyaev–Zel'dovich (SZ) surveys. A filter matched to the spatial and spectral characteristics of the SZ signal optimally extracts clusters from the astrophysical backgrounds. We calculate the expected confusion (point source and primary cosmic microwave background [CMB]) noise through this filter and quantify its effect on the detection threshold for both single and multiple frequency surveys. Extrapolating current radio counts, we estimate that confusion from sources below $\sim 100 \mu$Jy limits single–frequency surveys to $1\sigma$ detection thresholds of $Y \sim 3 \times 10^{-6}$ arcmin$^2$ at 30 GHz and $Y \sim 10^{-5}$ arcmin$^2$ at 15 GHz (for unresolved clusters in a 2 arcmin beam); these numbers are highly uncertain, and an extrapolation with flatter counts leads to much lower confusion limits. Bolometer surveys must contend with an important population of infrared point sources. We find that a three–band matched filter with 1 arcminute resolution (in each band) efficiently reduces confusion, but does not eliminate it: residual point source and CMB fluctuations contribute significantly the total filter noise. In this light, we find that a 3–band filter with a low–frequency channel (e.g, 90+150+220 GHz) extracts clusters more effectively than one with a high frequency channel (e.g, 150+220+300 GHz).

Key words.

1. Introduction

Galaxy cluster surveys based on the Sunyaev–Zel’dovich (SZ) effect (Sunyaev & Zeldovich 1970, Sunyaev & Zeldovich 1972) will soon supply large, homogeneous catalogs out to redshifts well beyond unity (Barbosa et al. 1996, Eke et al. 1996, Colafrancesco et al. 1997, Holder et al. 2000, Bartlett 2001, Kneissl et al. 2001, Benson, Reichardt & Kamionkowski 2002). Eagerly awaited, these surveys will probe dark energy and its evolution, and shed new light on galaxy formation (Haiman et al. 2001, Weller & Battye 2003). The instruments designed for these observations are of two types: dedicated interferometer arrays surveying at a single frequency (e.g., AMI, AMiBA, and SZA) and bolometer systems operating over several millimeter bands (e.g., ACBAR, ACT, APEX, Olimpo, Planck, SPT). Ground–based and balloon–borne instruments are expected to find up to several thousands of clusters, while the Planck mission will produce an essentially all–sky catalog of several $10^4$ clusters by the end of the decade.

An important issue facing these surveys is cluster detection in the presence of other astrophysical foregrounds/backgrounds. Except for the very nearby ones, clusters will appear as extended sources over arcminute scales. Power in diffuse Galactic emission (synchrotron, free–free and dust emission) and in the primary cosmic microwave background (CMB) anisotropy falls on these scales and the clusters can be efficiently extracted using an adapted spatial filter (Haeffner & Tegmark 1999). Fluctuations

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A list of experiment web pages is given at the end of the reference section.
caused by point sources (radio and infrared galaxies), on the other hand, are important on these scales and represent a potentially serious source of confusion for SZ cluster searches (Knox, Holder & Church 2004, White & Majumdar 2004, Aghanim, Hansen & Lagache 2004).

The two kinds of SZ survey instruments deal with this problem in different ways. Single frequency surveys must individually identify and remove point sources with high angular resolution (better than 1 arcminute) observations, which interferometers achieve by incorporating several long baselines in their antenna array. Operating at relatively low frequencies (15 GHz for AMI, 30 GHz for the SZA and 90 GHz for AMIBA), these surveys will contend with the radio galaxy population. Bolometer–based instruments will not have the angular resolution needed to spatially separate point sources from galaxy clusters; they must instead rely on spectral information. In their millimeter wavelength bands, these instruments will contend with the poorly known far–infrared point source population.

In this paper we quantify the effect of point source confusion on cluster detection in SZ surveys. We shall only consider the effect of the random field population, but we note that point sources are expected to preferentially reside in the clusters themselves, locally raising the effective noise level; we leave examination of this effect to a future work. White & Majumdar (2004) recently calculated the expected confusion due to IR point sources as a function of frequency, while Knox et al. (2004) and Aghanim et al. (2004) studied their influence on the measurement of SZ cluster parameters. We extend this work by considering cluster detection with an optimal filter spatially and spectrally (for multi–frequency surveys) matched to the thermal SZ signal (Haehnelt & Tegmark 1996, Herranz et al. 2002, Schafer et al. 2004). Using the matched filter, we quantify the confusion noise induced by extragalactic point sources for both single–frequency radio and multi–frequency bolometer SZ surveys.

We begin by briefly describing our matched filter and cluster detection routine, leaving details to Melin et al. (2005). In Section 3 we present our point source model, based on recent number counts in the radio and far–infrared. We then calculate the confusion noise through the filter to examine its importance for future SZ surveys (Section 4). In the last section, we summarize our main results and discuss implications for SZ surveying.
Fig. 1. Radial profiles of single frequency and multiple frequency matched filters for a cluster of $\theta = 1$ arcmin. In the left–hand panel we see the spatial weighting used by the single frequency filter to optimally extract the cluster from the background (radio point sources + CMB) and noise. The filter is arbitrarily normalized to unity at the origin and the beam has a 2 arcmin FWHM. The right–hand panel shows the elements of the 3–band filter with 150, 220 and 300 GHz channels. The three functions are arbitrarily normalized to the peak value of the 150 GHz filter (black curve), and each channel has a 1 arcmin FWHM beam. In this case we see how the filter uses both spatial and spectral information to optimally extract the cluster.

We now wish to use both spatial and spectral information (when available) to best extract clusters from our survey. Consider a cluster of characteristic size $\theta$ (in the following, we take this to be the core radius of a $\beta$–profile) and central $y$–value $y_o$ situated at an arbitrary point $x_i$ on the sky. We build a filter $\Psi_\theta(x)$ (in general a column vector in frequency space) that returns an estimate, $\hat{y}_o$, of $y_o$ when centered on the cluster:

$$\hat{y}_o = \int d^2x \, \Psi_\theta^t(x - x_i) \cdot M(x)$$  \hspace{1cm} (2)

where superscript $t$ indicates a transpose (with complex conjugation when necessary). Suppose that clusters of this characteristic size are described by an average angular form $T_\theta(x)$, by which we mean: $T_\theta(x) = \langle y(x)/y_o \rangle_C$, where the average is over many clusters of size $\theta$. We match the filter to this angular form $T_\theta$ and to the spectral shape of the SZ signal, requiring an unbiased estimate of the central $y$ value: $\langle \hat{y}_o \rangle = y_o$, where now the average is over both total noise and cluster (of size $\theta$) ensembles. The filter is then uniquely determined by further demanding a minimum variance estimate.

The result expressed in Fourier space (the flat sky approximation is reasonable on cluster angular scales) is (Haehnelt & Tegmark 1996, Herranz et al. 2002, Melin et al. 2005):

$$\Psi_\theta(k) = \sigma_\theta^2 P^{-1}(k) \cdot F_\theta(k)$$  \hspace{1cm} (3)

where

$$F_\theta(k) \equiv j_\nu T_\theta(k)$$  \hspace{1cm} (4)

$$\sigma_\theta = \left[ \int d^2k \, F_\theta^t(k) \cdot P^{-1} \cdot F_\theta(k) \right]^{-1/2}$$  \hspace{1cm} (5)

with $P(k)$ being the noise power spectrum, a matrix in frequency space with components $P_{ij}$ defined by $\langle N_i(k) N^*_j(k') \rangle_N = P_{ij}(k)\delta(k - k')$. Note that this last expression treats, again, the astrophysical foregrounds as stationary fields. The quantity $\sigma_\theta$ gives the total noise variance through the filter. We write the noise power spectrum as a sum $P_{ij} = P_{ij}^{\text{noise}} \delta_{ij} + B_i(k) B^*_j(k) P_{ij}^{\text{sky}}$, where $P_{ij}^{\text{noise}}$ represents the instrumental noise power, $B(k)$ the observational beam and $P_{ij}^{\text{sky}}$ gives the foreground power (non–SZ signal) between channels $i$ and $j$. As written, we assume uncorrelated instrumental noise between observation frequencies.

Our aim is to quantify the effect of point source confusion on cluster detection using this filter. To this end, we ignore diffuse Galactic emission, which is small on
cluster scales, and only include primary CMB temperature anisotropy and point source fluctuations in the sky power \( P_{ij} \). For our numerical results, we adopt a standard flat concordance CMB power spectrum \((\Omega_m = 1 - \Omega_M = 0.7, h = 0.7\), e.g., Spergel et al. 2003) and employ a cluster template based on the spherically symmetric \( \beta \)-model with core radius \( \theta \) and \( \beta = 2/3: T_\theta(x) = (1 + |x|^2/\theta^2)^{-(3\beta-1)/2} \).

Two examples of the matched filter for \( \theta = 1 \) arcmin are given in Fig. 1 one for a single frequency survey with a 2 arcmin beam (left–hand panel) and the other for a 3–band filter with 1 arcmin beams at 150, 220 and 300 GHz (right–hand panel). The filters are circularly symmetric because we have chosen a spherical cluster model, and the figure shows their radial profiles. We clearly see the spatial weighting used by the single frequency filter to optimally extract the cluster from the noise and from the point source and CMB backgrounds. The multiple frequency filter is a 3–element column vector containing filters for each individual frequency. Their radial profiles are shown in the right–hand panel arbitrarily normalized to the peak of the 150 GHz filter. The map from each band is filtered by the corresponding function and the results are then summed to produce the final filter output. We see here how the filter uses both spectral and spatial weighting to optimally extract the cluster signal.

3. Point Sources

Two different extragalactic point source populations affect SZ observations (see Figure 2). At frequencies below \( \sim 100 \) GHz, radio galaxies and quasars dominate the source counts, while at higher frequencies dusty IR galaxies become more important. The spectral dependence of source flux density in both populations is often modeled as a power law, \( S_\nu \propto \nu^\alpha \), with spectral index \( \alpha \). Radio sources tend to have falling spectra with \( \alpha < 0 \) (Herbig & Readhead 1992, Taylor et al. 2001, Mason et al. 2003), but flat and inverted spectra with \( \alpha \geq 0 \) appear more prominent with observing frequency (Bennett et al. 2003, Trushkin 2003). At millimeter wavelengths we observe the dust emission of IR galaxies in the Rayleigh–Jeans with rising spectra characterized by \( \alpha \sim 3–4 \) (Vlahakis, Dunne & Eales 2004). As will be seen, we need information on these extragalactic sources down to mJy flux densities and below; unfortunately, neither the distribution of \( \alpha \) nor the source counts are well known for either population at these flux densities and at frequencies of interest for SZ observations (\( \sim 10 – 300 \) GHz).

3.1. Radio Galaxies

Bennett et al. (2003) summarize the radio source counts at \( 30 – 40 \) GHz from WMAP \((S_\nu > 1 \) Jy), DASI \((S_\nu > 100 \) mJy, Kovac et al. 2002), VSA \((S_\nu > 50 \) mJy, Taylor et al. 2003, Cleary et al. 2004) and CBI \((S_\nu > 10 \) mJy, Mason et al. 2003). Fitting to these data, Knox et al. (2004) find

\[
\frac{dN}{dS_\nu} \bigg|_r = \frac{N_o}{S_o} \left( \frac{S_\nu}{S_o} \right) ^\gamma
\]

with \( N_o = 30 \) deg\(^{-2} \), \( S_o = 1 \) mJy and \( \gamma = -2.0 \). The integrated counts obtained from Eq. (6) are shown in Figure 2 as the lower solid red line, together with the observations from CBI and the VSA. The model fits the CBI counts well, but lies high relative to the VSA counts at the bright end; as shown in Bennett et al. (2003), the counts in fact steepen toward higher flux densities, so a pure power law only matches the data over a limited range.

We will be interested in the counts at flux densities near 100 \( \mu \)Jy for calculating the expected confusion noise.
in upcoming SZ surveys. This requires an extrapolation of the observed counts using Eq. (6) to much lower flux densities, which we view with caution. To get a handle on the uncertainty associated with this extrapolation, we consider an alternate model with a flattening slope toward the faint end:

\[
\frac{dN}{dS_\nu} \bigg|_{ir} = \frac{N_0}{S_0} \left(1 + \frac{S_\nu}{S_0}\right)^\gamma
\]

with the same values of \(N_0, S_0\) and \(\gamma\). These counts are shown as the red dashed line in Figure 2, which clearly provides an equally satisfactory fit to the observations. Comparing the confusion noise in the two models will give us a sense of the uncertainty in our estimates.

We adopt Eq. (6), alternatively Eq. (7), for the counts at \(\nu = 30\) GHz. Extrapolation to other frequencies suffers from uncertainty in the spectral index \(\alpha\) of the emission law. Typically negative, determinations of \(\alpha\) spread over a wide range, including positive values. Mason et al. (2003), for example, find an average \(\langle \alpha \rangle \approx -0.45\), between 1.4 and 30 GHz, with a dispersion \(\sigma_\alpha \approx 0.37\), which is roughly consistent with the observations of Taylor et al. (2001) between 1.4 and 15 GHz. The brighter sources seen over the higher frequency WMAP bands, on the other hand, show much flatter spectra, with a distribution centered on \(\alpha = 0\) and a dispersion of \(\sigma_\alpha \approx 0.3\) [Bennett et al. 2003; see also Trashkin 2003]. There is a pressing need for better understanding of the radio source population at CMB frequencies.

### 3.2. IR Galaxies

Dusty infrared luminous galaxies dominate the source counts at frequencies near 100 GHz and higher. The dust in these galaxies is typically heated to temperatures of several tens of Kelvin by their interstellar radiation field. Its emission can be characterized with a blackbody spectrum modified by a power–law emissivity: \(S_\nu \propto \nu^\beta B_\nu(T)\), where \(\beta \approx 1 - 2\). In the Rayleigh–Jeans this leads to a steeply rising power–law with spectral index \(\alpha \approx 3-4\), from which we see that source confusion from the IR population rises rapidly with frequency, the implications of which were recently discussed by White & Majumdar (2004).

Blank field counts around 10 mJy at 850 \(\mu\)m where obtained by Scott et al. (2002) and Borys et al. (2003) using the SCUBA instrument. As discussed by the latter authors, the counts are well described by a double power–law:

\[
\frac{dN}{dS_\nu} \bigg|_{ir} = \frac{N_0}{S_0} \left(1 + \frac{S_\nu}{S_0}\right)^{1.0} + \left(\frac{S_\nu}{S_0}\right)^{3.3}\] ^{-1}
\]

with \(N_0 = 1.5 \times 10^4\) deg\(^{-2}\) and \(S_0 = 1.8\) mJy. This model is shown in Figure 2 as the upper solid red line, along with data taken from the two surveys.

The SCUBA Local Universe Galaxy Survey (SLUGS, Vlahakis, Dunne & Eales 2004) finds a broad distribution for the dust emissivity index with \(\langle \beta \rangle \approx 1\) and a dispersion we take to be \(\sigma_\beta \approx 0.2\). According to the SLUGS observations, optical galaxies tend to have lower spectral indexes than IRAS–selected objects; we eye–balled the above numbers to be representative of the population as a whole.

### 4. Point Source Confusion

Point source confusion is caused by random fluctuations in the number of unresolved sources in the filter. We now study the contribution of this confusion to the overall filter noise, \(\sigma_n\), as a function of filter scale, \(\theta\). As mentioned above, we only consider uncorrelated instrumental noise, primary CMB anisotropy and point source terms to the power spectrum matrix \(P\), whose off–diagonal elements are then just sky terms (to be multiplied by the beam):

\[
P_{ij}^{sky}(k) = C_l = |k| + P_{ij}^{ps}
\]

where \(C_l\) is the CMB temperature angular power spectrum and \(P_{ij}^{ps}\) is the point source term. We quote power in units of CMB temperature equivalent and ignore spatial correlations of the point sources, which means that \(P_{ij}^{ps}\) is independent of \(k\).

To calculate the point source terms \(P_{ij}^{ps}\), we adopt the counts of Eq (6), alternatively Eq (7), at \(\nu_1 \equiv 30\) GHz and those of Eq (8) at \(\nu_2 \equiv 350\) GHz (850 \(\mu\)m). Unless otherwise specified, spectral indexes follow Gaussian distributions with \((\langle \alpha \rangle = 0, \sigma_\alpha = 0.3)\) for radio sources, and \((\langle \alpha \rangle = 3, \sigma_\alpha = 0.2)\) for IR galaxies (see previous section). Then we have

\[
P_{ij}^{ps} = \sigma_{\nu}^2 \cdot R_{ij}^{x} G_i \left(\sqrt{\nu_i^2/\nu_j^2/\nu_{ir}^2}\right) + \sigma_{\nu}^2 \cdot R_{ij}^{y} G_j \left(\sqrt{\nu_i^2/\nu_j^2/\nu_{ir}^2}\right)
\]

where (Scheuer 1957; Condon 1974)

\[
\sigma_{(r,ir)}^2 \equiv \left(\frac{\partial B_{\nu_1}/\partial T}{\partial B_{\nu_2}/\partial T}\right)^{-2} \int dS_\nu \left(\frac{dN}{dS_\nu}\right)_{(r,ir)}^{-1}
\]

(11)

gives the sky temperature variance due to radio or IR sources at the fiducial frequencies \(\nu_1\) and \(\nu_2\); conversion to CMB temperature units is made with the Planck function \(B_\nu\) at \(T_{cmb} = 2.725\) K (Mather et al. 1999). This also appears in the \(R\)–factors:

\[
R_{ij}^{(r,ir)} \equiv \frac{\left(\partial B_{\nu_1}/\partial T\right)^{-1}(\partial B_{\nu_2}/\partial T)^{-1}}{(\partial B_{\nu_1}/\partial T)^{-1}}
\]

(12)
Fig. 3. Noise (1σ) on the integrated Compton Y parameter as a function of filter scale. We assume 10 μK noise/beam and adopt 1 arcmin beams in all bands, except for the green 3–dot–dashed curve in the right–hand panel. At these frequencies, we only include IR sources below S_{lim} = 100mJy, following the counts of Eq. (8), and with a spectral index α = 3 and no dispersion. **Left Panel:** The black dotted line shows the sensitivity at 150 GHz, where the instrumental noise and point source confusion are comparable (see Figure 4). Confusion is effectively eliminated by a 2–band filter, as demonstrated by the red dot–dashed line lying just above the pure instrumental noise limit (black 3 dot–dashed curve). The upper solid green line shows the result when adding primary CMB anisotropy, in which case the 2–band filter is unable to cleanly separate the three astrophysical components. Addition of a third band at 300 GHz (blue dashed line) does not greatly improve the result, because both the 220 and 300 GHz channels are dominated by point sources, as shown in Figure 4 (see text). **Right Panel:** Artificially removing the point sources from the 300 GHz channel, we see (black dotted line) that the filter gains enough leverage on the three astrophysical signals to drop its noise to the instrumental limit (red dot–dashed line). Source confusion being greatly reduced at lower frequencies, a 3–band filter with 90 GHz (solid green line) performs better; this remains true even when we degrade the 90 GHz beam to a more realistic 2 arcmin FWHM (green 3–dot–dashed curve).

The function G accounts for spectral variations:

$$G_{(r,ir)}(x) = \int d\alpha \, N_{(r,ir)}(\alpha) \, x^{2\alpha}$$  \hspace{1cm} (13)

with N_{(r,ir)} being the normal distribution for radio and IR spectral indexes, respectively. These results assume that there is no correlation between flux density S_{\nu} and spectral index, α, so that the joint distribution is separable.

### 4.1. Single Frequency Surveys

Single frequency surveys can only use spatial information to control point source confusion. Operating at ν = 15 GHz and 30 GHz, respectively, AMI and SZA will contend primarily with the radio source population; AMiBA, on the other hand, must deal with both radio and IR sources at ν = 90 GHz. The former two interferometers include long baselines dedicated to identifying and removing point sources at high spatial frequency on the sky, where they are cleanly separated from the more extended cluster SZ emission. Point source confusion is then caused by the residual population below the subtraction threshold, S_{lim}. Apart from the beam convolution, point source confusion contributes to the filter variance σθ in the same manner as instrumental noise. Using the counts of Eq. 10
we find for the confusion power:

\[ P_{30,30}^{ps} = \sigma^2 = (12 \mu K \cdot \text{arcmin})^2 \left( \frac{S_{\text{lim}}}{100 \mu Jy} \right) \]  
\[ P_{15,15}^{ps} = \sigma^2 \cdot R_{15,15}^i \cdot G_\tau(1/2) \]
\[ > (48 \mu K \cdot \text{arcmin})^2 \left( \frac{S_{\text{lim}}}{100 \mu Jy} \right) \]

where the numerical value in the last line assumes \( G_\tau(1/2) = 1 \), while it most certainly is larger. These values are comparable to target sensitivities for interferometer surveys, implying that these instruments will have to subtract sources down to \( \sim 100 \mu Jy \) or better. Assuming a \( \theta_{\text{FWHM}} \sim 2 \) arcmin synthesized beam, we calculate the confusion limit on the integrated Compton Y parameter for unresolved clusters. We conclude that confusion from sources below 100 \( \mu Jy \) will limit SZ sensitivity to \( Y \sim 3 \times 10^{-6} \text{arcmin}^2 \) at 30 GHz and \( Y \sim 10^{-5} \text{arcmin}^2 \) at 15 GHz (both are at 1\( \sigma \)). The former limit is a factor \( \sim 5 \) greater than the confusion expected from primary CMB anisotropy in the concordence model for unresolved clusters (Melin, Bartlett & Delabrouille 2005).

Adopting the alternative model of Eq. (7), these confusion limits drop by a factor \( \sim 20 \), and the dependence of the variance on the source subtraction threshold approaches \( \propto S_{\text{lim}}^2 \). There is clearly a large uncertainty associated with extrapolation of the counts to faint flux densities. In this light, note that as long as the counts do not steepen toward lower flux densities, the confusion estimates are, fortunately, dominated by the counts at \( S_{\text{lim}} \), rather than at some unknown cut–off at even fainter levels.

### 4.2. Multiple Frequency Surveys

Planned bolometer–based surveys will operate over several millimeter and submillimeter bands, allowing them to use spectral information to extract clusters from the foregrounds. This will in fact be their only way to reduce the effects of point source confusion, because they will not have the spatial resolution\(^4\) needed for subtracting point sources from cluster images. In the multi–frequency case, we refer to the optimal spatio–spectral filter as a multi–filter.

Specifically, the multi–filter performs a weighted sum designed to remove foregrounds from the SZ cluster signal, as illustrated in the right–hand panel of Figure 4. Figure 3 helps to understand the filter’s workings and it will allow us to draw some important conclusions. The Figure shows the filter noise \( \sigma_\nu \) (1\( \sigma \)) in terms of the integrated

\[ \int (l+1)C_l/(2\pi) \]  

\[ \text{[\( \mu K \text{arcmin} \)]} \]

\[ \text{multipoles l} \]

\[ 100 \]  

\[ 1000 \]  

\[ 10000 \]

\[ 0.01 \]  

\[ 0.1 \]  

\[ 1 \]  

\[ 10 \]

\[ \text{primary CMB} \]  

\[ \text{instrumental noise} \]  

\[ \text{ir point sources (90 GHz)} \]  

\[ \text{ir point sources (150 GHz)} \]  

\[ \text{ir point sources (220 GHz)} \]  

\[ \text{ir point sources (300 GHz)} \]

\[ \text{Fig. 4. Power spectra of the primary CMB anisotropy (solid black line), point source confusion in different bands (as labeled) and instrumental noise; the latter corresponds to 10 \( \mu K \) noise/1 arcmin lobe, which we take here to be the same in all bands. Only IR sources with \( S_\nu < S_{\text{lim}} = 100 \) mJy are included, according to the counts of Eq. (8), and with \( \alpha = 3 \) and no dispersion. The figure shows the that the 300 GHz channel is dominated by sources, explaining why the 3–band filter with 90 GHz performs more efficiently than the one with 300 GHz (see Figure 3).} \]

\(^4\) Most planned surveys have arcminute resolution.

Compton Y parameter as a function of filter scale for various band and foreground combinations. This is calculated from the filter variance as \( \sigma_\nu = \sigma_\phi \int d^2x \ T_\phi(x) \). We take as representative of planned observations a survey with 10 \( \mu K \) instrumental noise per 1 arcmin lobe (FWHM) in all bands. We only include the IR source population (dominant at these frequencies) below \( S_{\text{lim}} = 100 \text{ mJy} \), assuming brighter sources are explicitly subtracted; this is well above the knee in the differential counts of Eq. (8). We further fix, for the present, the spectral index to \( \alpha = 3 \) with zero dispersion (\( G = 1 \)).

Consider first the case with just instrumental noise, point sources (no CMB) and two frequencies, one at \( \nu = 150 \text{ GHz} \) and the other at the thermal SZ null, \( \nu = 220 \text{ GHz} \). Point source confusion is severe in each individual band, as illustrated by Figure 4. The dotted line in the left panel of Figure 3 shows the total filter noise with just the 150 GHz band. When both bands are
used in the filter, the filter noise $\sigma_Y$ drops considerably (red dot–dashed line), approaching the pure instrumental noise limit for the 2–band filter, shown as the black dashed–3 dotted line. It is straightforward to show under these circumstances that the filter performs a direct subtraction of the point source signal from the 150 GHz channel by extrapolation of the 220 GHz signal using the known spectral index $\alpha$. What we see here is that the subtraction is perfect to the instrumental noise limit.

The sky of course also includes the CMB signal and other foregrounds, and the point source spectral index has a non–zero distribution, both of which complicate the subtraction. We discuss the second effect below and now add CMB anisotropy, keeping $\alpha$ fixed. The 2–band filter is no longer able to separately determine the three sky signals (SZ, point sources and CMB), with as a consequence a significant rise in total SZ noise, as shown by the solid green line. Surprisingly, the situation does not improve even when we include more information with a third observing band at $\nu = 300$ GHz (blue dashed line).

This interesting result is due to the fact that both the 220 and 300 GHz bands are dominated by point source confusion (see Figure 1) – neither provides good information the CMB anisotropy, so the filter remains unable to completely separate the three sky signals. We can test this conclusion by artificially removing point sources from the new channel at 300 GHz. The result is shown in the right–hand panel of the Figure as the black dotted line; the total SZ noise $\sigma_Y$ drops to a level comparable to the level induced just by instrumental noise (red dot–dashed line), indicating that once again the subtraction is almost perfect.

This has important consequences for SZ surveying. Observing at high frequencies, such as 300 GHz, is very difficult from the ground due to atmospheric effects; moving up in frequency, one approaches strong water vapor lines. What we have just seen suggests that including bands beyond the thermal SZ null may not be worth the effort, at least not for detecting clusters.

To further explore this issue, we replace the 300 GHz channel by a 90 GHz band. At this lower frequency, point source confusion is greatly reduced and gives the filter a better handle on CMB anisotropy; in fact, as shown in Figure 4, point source confusion is well below the instrumental noise level at 90 GHz. The green solid line in the right–hand panel of Figure 4 shows the new result: this three–band filter with 90 GHz performs significantly better than the one with 300 GHz. It is, however, unlikely that all three bands will have the same beam size, which we have taken as 1 arcmin throughout this discussion. The green 3–dot–dashed curve in the right–hand panel of the Figure shows the result for a three–band filter with a 2 arcmin beam at 90 GHz. Even with the larger beam at the lower frequency, the result remains qualitatively the same – the filter with 90 GHz performs better than the one with 300 GHz.

Multi–frequency surveys will certainly include 150 and 220 GHz bands to cover the maximum decrement and null of the thermal SZ signal. We conclude here that a 90 GHz band is a more valuable addition than one at 300 GHz for cluster extraction, despite a loss in angular resolution at the lower frequency.

As a final note, we consider the effects of dispersion in the source spectral index $\alpha$. With dispersion, the filter can no longer perform a perfect subtraction by extrapolation across bands; it must instead find appropriate frequency weights for a statistically optimal subtraction. In the point source power spectrum matrix $P^{ps}_{\nu,\nu}$, only the self power $P^{ps}_{\nu,\nu}$ remains unaffected; other diagonal elements will increase, while correlations between bands (in the off–diagonal elements) decrease. We therefore expect the filter’s performance to decline.

We examined the importance of this effect using the function $G_{\nu}$ defined in Eq. (13). Dispersions up to $\sigma_\alpha = 0.5$ increase matrix elements involving the 150 and 220 GHz bands of the power spectrum matrix by at most 20%, relative to their values with zero dispersion. The 90 GHz channel is of course the most affected: the auto–power element $P^{ps}_{90,90}$ increases by more than 50% for the same dispersion. Nevertheless, when running the filter combinations of Figure 3, we find only a small change in the filter noise curves, barely perceptible by eye. We conclude that even rather large variations in the frequency dependence of individual source spectra does not significantly increase confusion noise through the filter. In more general terms, this also suggests that our confusion estimates are not strongly dependent on the foreground model.

5. Discussion and Conclusion

Primary CMB anisotropy and extragalactic point sources are the most important foregrounds for SZ surveys. Point source confusion is a particularly critical issue because it rises rapidly on cluster angular scales. We have quantified its importance for both single frequency and multiple frequency surveys using current estimates of the radio and IR source counts and an optimal matched multi–filter for cluster extraction. Our main conclusion are:

- The expected confusion level from radio point sources is uncertain due to lack of information on the
counts at required flux densities: a power-law extrapolation of the observed counts (Eq. 6) leads to a confusion–limited SZ sensitivity at 30 GHz of $Y \sim 3 \times 10^{-6}$ arcmin$^2$ from unresolved sources below $S_{\text{lim}} = 100$ µJy (1σ for clusters unresolved by a 2 arcmin beam); at 15 GHz the corresponding sensitivity is $Y \sim 10^{-5}$ arcmin$^2$. An alternative model in which the counts flatten at low flux density (Eq. 7) predicts much lower confusion limits, reduced by a factor of $\sim 20$, in which case CMB confusion becomes the limiting factor (Melin, Bartlett & Delabrouille 2005).

Currently planned multiple frequency bolometer surveys (e.g., 10 µK instrumental noise/1 arcmin beam) greatly reduce the large confusion noise from IR sources and can attain 1σ sensitivity of $Y \sim 7 \times 10^{-7}$ arcmin$^2$ for unresolved clusters (see Figure 3). Nevertheless, both residual point source and CMB anisotropy confusion significantly increase the total filter noise, degrading survey sensitivity from the ultimate instrumental noise limit.

For multiple frequency surveys, observation bands below the thermal SZ null (e.g., 90+150+220 GHz) are more efficient for cluster extraction than observations at higher frequencies (e.g., 150+220+300 GHz), despite a potential loss of angular resolution in the 90 GHz channel (e.g., 2 arcmin beam instead of our fiducial 1 arcmin beam).

The minimum detectable cluster mass as a function of redshift, $M_{\text{det}}(z)$, is a key characteristic of a survey. To further illustrate the last point, we show $M_{\text{det}}(z)$ in Figure 5 for the 3–band multi–filter. In making this figure, we adopted simple self–similar relations for $Y(M, z)$ and $\theta_c(M, z)$ (Melin, Bartlett & Delabrouille 2005); given the potentially important theoretical uncertainty in these relations, the absolute positioning of the curves should be viewed with caution – more robust and more pertinent to our discussion are their relative positions. The 3–band filter with 90 GHz (black dashed line) gains mass sensitivity compared to the filter with 300 GHz (solid blue line), assuming 1 arcmin beams in all bands. It does not, however, reach the ideal noise limit (red dot–dashed line), due to residual point source and CMB confusion through the filter. A 3–band filter with lower angular resolution at 90 GHz (2 arcmin beam), a more probable observing situation, does somewhat worse, but still better than the 3–band filter with 300 GHz (and 1 arcmin beams in all bands). This is an important consideration given the difficulty imposed by atmospheric effects on observations at high frequencies.

With the $S/N > 5$ detection threshold [i.e., $5\sigma_Y(\theta)$], we find 15 clusters/deg$^2$ for the filter with 300 GHz (1 arcmin all bands), 30 clusters/deg$^2$ for the filter with 90 GHz and 1 arcmin beams, and 18 clusters/deg$^2$ for the 3–band filter with a 2 arcmin beam at 90 GHz. There are 47 detected clusters/deg$^2$ at the ultimate noise–limit of the 3–band filter with a 1 arcmin beam at 90 GHz. These numbers should be compared to the 85 clusters/deg$^2$ with mass $> 10^{14}$ solar masses with our model parameters.

An important consequence of our results is that SZ survey selection functions are affected by residual astrophysical confusion and are not uniquely determined by instrumental properties. Specifically, we have seen that even a 3–band bolometer survey with good angular resolution and optimal filter cluster extraction experiences a
mixture of residual point source and primary CMB confusion. Cluster catalog construction will therefore suffer from uncertainty in astrophysical foreground modeling (Melin, Bartlett & Delabrouille 2005).

In conclusion, our results support the expectation that future ground–based SZ surveys will provide rich cluster catalogs for cosmological studies. Confusion from point sources and primary CMB anisotropy can be greatly reduced by multi–frequency bolometer surveys, but some residual point source and CMB anistropy confusion noise will affect cluster detection and catalog construction.

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- ACT [http://www.hep.upenn.edu/~angelica/act.html]
- AMI [http://www.mrao.cam.ac.uk/telescopes/ami/index.html]
- AMiBA [http://www.asiaa.sinica.edu.tw/amiba]
- APEX [http://bolo.berkeley.edu/apexsz]
- SPT [http://astro.uchicago.edu/spt/]
- SZA [http://astro.uchicago.edu/sze]
- Olimpo [http://oberon.roma1.infn.it/]
- Planck [http://astro.estec.esa.nl/Planck/]

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