Metastable Memristive Lines for Signal Transmission and Information Processing

V. A. Slipko\textsuperscript{1,2} and Y. V. Pershin\textsuperscript{3,4}

\textsuperscript{1}Department of Physics and Technology, V. N. Karazin Kharkov National University, Kharkov 61022, Ukraine
\textsuperscript{2}Institute of Physics, Opole University, Opole 45-052, Poland
\textsuperscript{3}Department of Physics and Astronomy and Smart State Center for Experimental Nanoscale Physics, University of South Carolina, Columbia, South Carolina 29208, USA
\textsuperscript{4}Nikolaev Institute of Inorganic Chemistry SB RAS, Novosibirsk 630090, Russia

Traditional studies of memristive devices have mainly focused on their applications in non-volatile information storage and information processing. Here, we demonstrate that the third fundamental component of information technologies – the transfer of information – can also be employed with memristive devices. For this purpose, we introduce a metastable memristive circuit. Combining metastable memristive circuits into a line, one obtains an architecture capable of transferring a signal edge from one space location to another. We emphasize that the suggested transmission lines employ only resistive components. Moreover, their networks (for example, Y-connected lines) have an information processing capability.

PACS numbers:

Currently, the term memristive device\textsuperscript{1} (memristor) is primarily used to denote resistive switching memories that have been considered the most promising candidates for replacing the state-of-the-art memory technology. Moreover, it has been established that memristive networks (the networks of memristive devices) are useful to implement neuromorphic\textsuperscript{2,3}, digital\textsuperscript{4,5} and some unconventional computing architectures\textsuperscript{6}. The main advantages of computing with memristors (as well as with memcapacitors\textsuperscript{7,9}) are related, in particular, to their ability to store and process information on the same physical platform, massively-parallel dynamics of memristors in networks\textsuperscript{6}, sub-nanosecond computing times\textsuperscript{10} and low power consumption. Computing with memory circuit elements\textsuperscript{7} (memcomputing\textsuperscript{11}) is thus a promising alternative to the conventional von Neumann computing\textsuperscript{12}.

The information transfer is another important aspect of modern information technologies. Typically, the signal transmission is considered in the framework of transmission line models having a wide applicability range\textsuperscript{13,14}. The conventional transmission line models employ reactive components – capacitors and inductors – for signal transmission. The transmission line losses are taken into account by resistors. Recently, reconﬁgurable transmission lines utilizing memcapacitors\textsuperscript{7,8} instead of capacitors were suggested\textsuperscript{17}. Transmission characteristics of such lines and thus their functionality can be pre-programmed on demand\textsuperscript{17}.

The present Letter introduces a different approach to signal transmission uniquely based on the resistive devices. Fig. 1(a) presents its basic block – a metastable memristive circuit – combining a resistor R and memristor M. This circuit employs the most common type of memristors characterized by the bipolar threshold-type switching\textsuperscript{18}. According to the selected connection polarity of M in Fig. 1(a), $R_M$ increases at positive voltages across M, $V_M > V_t$. Here, $R_M$ is the memristance (memory resistance) of M changing between $R_{on}$ and $R_{off}$ (the low- and high-resistance states of memristor), and $V_t$ is the threshold voltage. Moreover, $R$ (the resistance of R in Fig. 1(a) circuit) is selected so that at $R_M = R_{on}$, $V_M$ is slightly below $V_t$ (see Fig. 1(b)). This circuit configuration can be referred to as a metastable state. The circuit can spend an extended time in this state prior being driven out by an input signal or its ﬂuctuation triggering an abrupt (accelerated\textsuperscript{19}) switching of M. The final state of the circuit (see Fig. 1(c)) is perfectly stable and thus can be referred to as the ground state.

Next, let us consider a chain (line) of metastable memristive circuits presented in Fig. 2. We argue that under appropriate conditions, this line can transfer a signal edge from one space location to another. Indeed, as it is shown below, there is a certain parameter space where

*Electronic address: pershin@physics.sc.edu

FIG. 1: (a) Metastable memristive circuit. Here, $V_p$ is a power supply voltage. (b) Metastable state of the circuit in (a) is realized when the voltage across M is slightly below its threshold voltage $V_t$. (c) The stable (ground) state corresponds to $R_M = R_{off}$. The red (dashed) line represents the transition from the metastable to the ground state.
Below we investigate numerically the dynamics of pulse edge propagation along the line and develop a theory of this phenomenon. In particular, we formulate a time-nonlocal equation describing an infinite line and find its solution in a certain limit.

In our calculations, we use the following model of first-order bipolar memristive system with threshold

$$I = \frac{V}{R_M}, \quad \frac{dR_M}{dt} = f(V, R_M),$$

$$f(V, R_M) = \begin{cases} \text{sign}(V)\beta (|V| - V_t) & \text{if } |V| \geq V_t \\ 0 & \text{otherwise} \end{cases},$$

where $I$ is the current, $V$ is the voltage, $R_M$ is the memristance changing continuously between $R_{on}$ and $R_{off}$, $\beta$ is the constant defining the rate of change of $R_M$, and $\text{sign}(\ldots)$ is the sign of the argument. According to the above equations, the memristance $R_M$ changes only when $|V| > V_t$, and the direction of change is defined by the device connection and applied voltage polarities.

To describe the line dynamics, we set up a system of equations based on Kirchoff’s rules supplemented by Eqs. (1) for the evolution of memristive components. The voltages across memristive systems $M_i$ are chosen as unknown variables. The equation for $i$-th metastable circuit ($i = 1, 2, \ldots, N$) reads

$$\left(\frac{1}{r_i} + \frac{1}{r_{i+1}} + \frac{1}{R_i} + \frac{1}{R_{M,i}}\right) V_i - \frac{V_{i-1}}{r_i} - \frac{V_{i+1}}{r_{i+1}} = \frac{V_p}{R_i}.$$  

The boundary conditions for the 1-st and $N$-th circuits are selected as follows: $V_0 = V_{in}$ is the input voltage voltage (see Fig. 2), and $r_{N+1} = \infty$. Generally, $2N$ equations (1), (3) for $2N$ variables $V_1, V_2, \ldots, V_N, R_{M,1}, R_{M,2}, \ldots, R_{M,N}$ supplemented with initial conditions (specifically, the initial memristances) fully define the transmission line dynamics.

In what follows we consider a homogeneous metastable memristive line with $r_i = r, R_i = R, R_{M,i}(t = 0) = R_{on}$ for $i = 1, \ldots, N$. Let us take a closer look at the memristive line dynamics triggered by a rectangular voltage pulse shown in Fig. 3(b). Fig. 3 presents a numerical solution of the line equations found with a set of parameters specified in the figure caption. In particular, Fig. 3(a) demonstrates that the switchings of memristors occur sequentially with almost the same time interval between adjacent switchings. The time dependencies of voltages (see Fig. 3(b)) are similarly shifted with respect to each other. Their waveforms (neglecting the boundary effects noticeable in $V_1$ and $V_2$ lines) are essentially the same. Moreover, taking a closer look at any of these voltages, say $V_i$, one can notice that a slow increase of $V_i$ changes to a fast increase followed by a slow increase. These stages of voltage growth are mainly associated with the switchings of $i - 1, i, i + 1$ memristors, respectively.

It is amply clear that the dynamics in the central part of the line is determined solely by the line properties but not by the boundary conditions (for example, the input...
pulse waveform or coupling to the external circuit). Next, we consider the dynamics of pulse edge propagation in the limit of an infinite line as we are not interested in the boundary effects. It is evident that we can safely assume that $V_i$ and $V_{i+1}$ are simply time-shifted with respect to each other, namely, $V_{i+1}(t) = V_i(t - \tau)$, where $\tau$ is the pulse edge propagation time per metastable circuit (time interval between adjacent switchings). Then, the system of coupled equations (3) reduces to a single time-nonlocal equation of the form

$$\left(\frac{2}{r} + \frac{1}{R} + \frac{1}{R_{M,i}}\right) V_i(t) - \frac{V_i(t - \tau)}{r} - \frac{V_i(t + \tau)}{r} = \frac{V_p}{R}.$$  \hspace{1cm} (4)

Eq. (4) together with Eq. (1) thus describe the pulse edge propagation in an infinite line. Unfortunately, even the set of Eqs. (1), (4) is rather complicated one, not only because Eq. (4) includes retarded and advanced times, but also because it is nonlinear. Even for one of the simplest possible $f(V,M)$ given by Eq. (2) we cannot solve the system (1), (4) analytically.

In fact, an approximate solution to the problem can be obtained in the limit of independent dynamics. In this limit, we assume that at each instant of time only one memristor is changing its state (switching). To proceed, let’s focus on Eqs. (3) for $(i - 1)$, $i$-th and $(i + 1)$ metastable circuits:

$$\left(\frac{2}{r} + \frac{1}{R} + \frac{1}{R_{M,i-1}}\right) V_{i-1} - \frac{V_{i-2}}{r} - \frac{V_i}{r} = \frac{V_p}{R}, \hspace{1cm} (5)$$

$$\left(\frac{2}{r} + \frac{1}{R} + \frac{1}{R_{M,i}}\right) V_i - \frac{V_{i-1}}{r} - \frac{V_{i+1}}{r} = \frac{V_p}{R}, \hspace{1cm} (6)$$

$$\left(\frac{2}{r} + \frac{1}{R} + \frac{1}{R_{M,i+1}}\right) V_{i+1} - \frac{V_i}{r} - \frac{V_{i+2}}{r} = \frac{V_p}{R}. \hspace{1cm} (7)$$

Next, the following approximations are made: (i) the voltages at $(i - 2)$ and $(i + 2)$ nodes are replaced by some constant values, $V_{i-2} = V_{off}$, $V_{i+2} = V_{on}$, and (ii) it is assumed that $(i - 1)$ and $(i + 1)$ memristors are in the $R_{off}$ and $R_{on}$ states, respectively, that is $R_{M,i-1} = R_{off}$ and $R_{M,i+1} = R_{on}$. Here, $V_{on}$ and $V_{off}$ are given by

$$V_{on(off)} = \frac{R_{on(off)}}{R_{on(off)} + R_p} V_p \hspace{1cm} (8)$$

representing the voltages in the line with all memristors in either $R_{on}$ or $R_{off}$ state. The above approximations make possible to truncate the system of equations (3).

From the truncated system of equations (5), (6), (7) we find

$$V_i(R_{M,i}) = \frac{V_p Y_1 R_{M,i}}{Y_2 R_{M,i} + 1}, \hspace{1cm} (9)$$

$$V_{i+1}(R_{M,i}) = \frac{V_i(R_{M,i})}{r Y_{on}} + \gamma_{on} V_p, \hspace{1cm} (10)$$

$$V_{i-1}(R_{M,i}) = \frac{V_i(R_{M,i})}{r Y_{off}} + \gamma_{off} V_p. \hspace{1cm} (11)$$

We note that Eq. (11) can be used to find the switching time $T$ of every memristor in the line. For this purpose, one should just substitute $R_{M,i} = R_{off}$ in the right-hand side of Eq. (11). We have found a very good agreement between the results of exact numerical calculations and analytical solution (9), (11). Fig. 4 presents $R_{M,i}(t)$ and $V_i(t)$ found using the analytical model. Eqs. (9) and (11) determine the time dependence of voltage across the switching memristor. The pairs of Eqs. (10), (11) and Eqs. (11), (10) can be used to obtain the voltage across
i-th memristor in the situation when \((i - 1)\) memristor is switching, and, correspondingly, when \((i + 1)\) memristor is switching.

In the above consideration, the \(i\)-th memristor starts switching at \(t = 0\). Therefore, the time \(\tau\) it takes for the switching edge to move from \(i\)-th to \((i + 1)\) metastable circuit along the line can be found as the time when a suitable condition to start the switching of \((i + 1)\) memristor is established, namely, when

\[
V_{t+1}(R_{M,i}^\tau) = V_t.
\]

By using Eqs. (17), (10), and (9) we determine the value of \(R_{M,i}^\tau\) such that the condition (17) is satisfied:

\[
R_{M,i}^\tau = \frac{rY_{on}(V_t - \gamma_{on}V_p)}{Y_{2rY_{on}(V_t - \gamma_{on}V_p)} - Y_{1}V_p}.
\]

Plugging this value of \(R_{M,i}^\tau\) into the right-hand side of Eq. (16) we get \(\tau\). Note that the switching time \(T\) is always longer than the pulse edge propagation time per metastable circuit, \(\tau\).

In conclusion, in this Letter we introduced metastable memristive states, circuits and lines. The signal transmission through metastable transmission lines was investigated using both numerical and analytical approaches. An approximate analytical solution was found in the framework of a single memristor switching approximation. Thus, we have established an innovative approach to signal transmission, which is unique in being based on only resistive components. Moreover, one can also envisage purely capacitive transmission lines, where the capacitive components replace the corresponding resistive ones. However, this idea needs further investigation.

Furthermore, we note that metastable memristive lines can also find applications in the area of information processing. For example, the time delays introduced by these lines could be of use in the development of race logic architectures. Moreover, capacitively Y-connected lines (see Fig. 5 for an example) are capable to implement some boolean logic operations, such as AND and OR. Some additional information regarding this idea is provided in Fig. 5 caption.

This work has been partially supported by the Russian Scientific Foundation grant No. 15-13-20021. VAS acknowledges the support by the Erasmus Mundus Action 2 ACTIVE programme (Agreement No. 2013-2523/001-001 EMA2).

1. L. O. Chua and S. M. Kang, Proceedings of IEEE 64, 209 (1976).
2. Y. V. Pershin and M. Di Ventra, Neural Networks 23, 881 (2010).
3. M. Prezioso, F. Merrikh-Bayat, B. D. Hoskins, G. C. Adam, K. K. Likharev, and D. B. Strukov, Nature 521, 61 (2015).
4. J. Borghetti, G. S. Snider, P. J. Kuekes, J. J. Yang, D. R. Stewart, and R. S. Williams, Nature 464, 873 (2010).
5. Y. V. Pershin, L. K. Castelano, F. Hartmann, V. Lopez-Richard, and M. D. Ventra, IEEE Trans. Circ. Syst. II 63, 558 (2016).
6. Y. V. Pershin and M. Di Ventra, Phys. Rev. E 84, 046703 (2011).
7. M. Di Ventra, Y. V. Pershin, and L. O. Chua, Proc. IEEE 97, 1717 (2009).
8. F. L. Traversa, F. Bonani, Y. V. Pershin, and M. D. Ventra, Nanotechnology 25, 285201 (2014).
9. Y. V. Pershin, F. L. Traversa, and M. D. Ventra, Nanotechnology 26, 225201 (2015).
10. A. C. Torrezan, J. P. Strachan, G. Medeiros-Ribeiro, and R. S. Williams, Nanotechnology 22, 485203 (2011).
11. M. Di Ventra and Y. V. Pershin, Nature Physics 9, 200 (2013).
12. J. Backus, Comm. Assoc. Comp. Machin. 21, 613 (1978).
13. L. Goleniewski and K. W. Jarrett, Telecommunications Essentials, Second Edition: The Complete Global Source (2Nd Edition) (Addison-Wesley Professional, 2006).
14. F. Martín, Artificial Transmission Lines for RF and Microwave Applications, Wiley Series in Microwave and Optical Engineering (Wiley, 2015).
15. T. I. Christophe Caloz, Electromagnetic Metamaterials: Transmission Line Theory and Microwave Applications (Wiley-IEEE Press, 2005), 1st ed.
16. A. Wallraff, D. I. Schuster, A. Blais, L. Frunzio, R.-S. Huang, J. Majer, S. Kumar, S. M. Girvin, and R. J. Schoelkopf, Nature 431, 162 (2004).
17. Y. V. Pershin, V. A. Slipko, and M. D. Ventra, Appl. Phys. Lett. 107, 253101 (2016).
18. Y. V. Pershin and M. Di Ventra, Advances in Physics 60, 145 (2011).
19. Y. V. Pershin, V. A. Slipko, and M. Di Ventra, Phys. Rev. E 87, 022116 (2013).
20. O. Svelto, Principles of Lasers (2009), 4th ed., ISBN 0306457482.
21. Y. V. Pershin, S. La Fontaine, and M. Di Ventra, Phys. Rev. E 80, 021926 (2009).
22. A. Madhavan, T. Sherwood, and D. Strukov, IEEE Micro 35, 48 (2015).