The impact of high spatial frequency atmospheric distortions on weak-lensing measurements

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Accepted 2011 December 1. Received 2011 November 18; in original form 2011 September 9

ABSTRACT
High-precision cosmology with weak gravitational lensing requires a precise measure of the point spread function across the imaging data where the accuracy to which high spatial frequency variation can be modelled is limited by the stellar number density across the field. We analyse dense stellar fields imaged at the Canada–France–Hawaii Telescope to quantify the degree of high spatial frequency variation in ground-based imaging point spread functions and compare our results to models of atmospheric turbulence. The data show an anisotropic turbulence pattern with an orientation independent of the wind direction and wind speed. We find the amplitude of the high spatial frequencies to decrease with increasing exposure time as $t^{-1/2}$, and find a negligibly small atmospheric contribution to the point spread function ellipticity variation for exposure times $t > 180$ s. For future surveys analysing shorter exposure data, this anisotropic turbulence will need to be taken into account as the amplitude of the correlated atmospheric distortions becomes comparable to a cosmological lensing signal on scales less than $\sim 10$ arcmin. This effect could be mitigated, however, by correlating galaxy shear measured on exposures imaged with a time separation greater than 50 s, for which we find the spatial turbulence patterns to be uncorrelated.

Key words: gravitational lensing: weak – cosmology: observations.

1 INTRODUCTION
Over the next decade we will see all sky surveys being undertaken to address key science questions ranging from cataloguing all near-Earth objects to mapping the dark Universe. These surveys include the Large Synoptic Survey Telescope (LSST; LSST Science Collaboration 2009), Euclid (Laureijs et al. 2011) and the Panoramic Survey Telescope and Rapid Response System (PanSTARRS; Kaiser et al. 2010). By observing the growth of dark matter structures over cosmic time, weak lensing may provide the most interesting constraints on the dynamical properties of dark energy. Alongside modifications to General Relativity, this dark energy is hypothesized as an explanation for the accelerated expansion of the Universe (see for example Huterer 2010 and references therein). The observational measurement of weak gravitational lensing is however far from trivial. In fact, it is the technique that sets the most stringent requirements on the optical design of future instrumentation as we require accurate knowledge of the point spread function (PSF). The PSF also needs to be minimal in terms of its size and ellipticity. Dark matter typically induces a 1 per cent change in the ellipticity of lensed distant galaxies. It is this distortion that we measure to constrain cosmology. In contrast, the telescope, camera and atmosphere can introduce image distortions up to the 10 per cent level. The main challenge in weak lensing is therefore to distinguish the cosmological distortion from instrumental and atmospheric distortions in order to recover the underlying dark matter signal. A significant effort is underway to improve the accuracy of weak-lensing measurements both from a software (Kitching et al. 2011) and hardware perspective (LSST Science Collaboration 2009). Furthermore, ambitious space-based surveys are proposed in order to remove atmospheric seeing and obtain diffraction-limited observations (Laureijs et al. 2011).

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For ground-based observatories, the varying refractive index in the turbulent layers of the atmosphere produces two effects. It blurs the images of point sources and also introduces an instantaneous ellipticity at the 10 per cent level (de Vries et al. 2007). This can be viewed as a superposition of speckles. As the exposure time increases, these speckles de-corrrelate, producing a circular distortion pattern. Telescope optics and the camera distortion then induce an additional smoothing term and an anisotropic distortion across the camera field of view. The combined observed PSF size is roughly given by adding the size of the atmospheric PSF in quadrature with the size of the instrument PSF. Optimal instrumentation design therefore aims to minimize the instrument contribution so that the resulting PSF is atmosphere dominated. Image distortions are encompassed by the PSF as imaged by stellar point sources. Using colour and size information, stars can be separated from galaxies and used to model the PSF. For weak-lensing measurements to date, the PSF model is typically an interpolation between stars, using a low-order polynomial model to obtain a PSF at each galaxy location. This assumes however that the PSF does not vary rapidly on small scales (Paulin-Henriksson et al. 2008).

In this paper, we measure and analyse the image distortion induced in short-exposure observations by atmospheric aberrations. This is of particular relevance to the PanSTARRS and upcoming LSST ground-based surveys. Both these surveys will image more than 20 000 deg\(^2\) with LSST achieving a depth of \(r \sim 27.5\) over 10 years. As transient objects are a key science goal for both these ambitious surveys, repeat short-exposure observations are required. For LSST, each region of the sky will be imaged close to 1000 times in exposures separated by \(30\) s. We select exposures taken in sub-arcsecond seeing conditions in our sample of stellar fields imaged and archived by the CFHT and listed in Table 1. We then analyse nine other samples with exposure times ranging from 1 to \(300\) s.

We first looked at this issue by analysing a set of 10-s and 30-s exposure images of a dense stellar field from the Subaru Telescope taken in one night. The conclusion from this paper was that the spurious small-scale power induced by the atmosphere would not be a significant factor in the co-added data of future massive surveys based on the finding that the atmospheric distortion in exposures separated by \(\sim 120\) s was found to be uncorrelated. This analysis was extended by Asztalos et al. (2007) with an analysis of 15-s exposure images from the Gemini South Telescope where evidence was presented for a correlation between the atmospheric distortion and the ground-based wind speed and direction with a consequence that the co-addition of exposures taken with the same observing site prevailing wind may not de-corrrelate as concluded by Wittman (2005).

An investigation of the image ellipticity of atmospheric aberrations in simulated short-exposure data is presented by de Vries et al. (2007). Using ray-tracing and Fourier methods, they simulate a turbulent atmosphere with a single-layer Kolmogorov power spectrum, finding significant 10 per cent ellipticities in the instantaneous atmospheric PSF. They also investigate the time dependence of the atmospherically induced ellipticities. Assuming a constant wind speed they show that the amplitude of the atmospheric ellipticity decreases with time as \(t^{-1/2}\). This simulation work has been extended by Wittman (2005) first looked at this issue by analysing a set of 10-s and 30-s exposure images of a dense stellar field from the Subaru Telescope taken in one night. The conclusion from this paper was that the spurious small-scale power induced by the atmosphere would not be a significant factor in the co-added data of future massive surveys based on the finding that the atmospheric distortion in exposures separated by \(\sim 120\) s was found to be uncorrelated. This analysis was extended by Asztalos et al. (2007) with an analysis of 15-s exposure images from the Gemini South Telescope where evidence was presented for a correlation between the atmospheric distortion and the ground-based wind speed and direction with a consequence that the co-addition of exposures taken with the same observing site prevailing wind may not de-corrrelate as concluded by Wittman (2005).

Wittman (2005) extended this work to investigate the time dependence of the atmospheric ellipticity. They recover the de Vries et al. (2007) result that as exposure time increases, the atmospheric PSF becomes rounder. Using a principal component analysis (PCA), they model the simulated short-exposure PSF across the LSST field of view and, keeping only the most significant 20 eigenmodes of that PCA analysis, they simulate what is described as a realistic PSF-convolved LSST image. They conclude that a typical stellar density is sufficient to model the PCA-derived PSF and demonstrate their ability to remove that PSF distortion from galaxy shape measurement. By limiting the PSF to only 20 eigenmodes, however, this analysis suppresses the random and high spatial frequency variation that we investigate in this study.

In this paper, we assess the impact of atmospheric distortions on weak-lensing surveys by analysing short-exposure images of high-density stellar regions with the wide-field MegaCam Imager on the Canada–France–Hawaii Telescope (CFHT). It is of particular importance to revisit this issue as a significant improvement in the accuracy of weak-lensing shape measurement has recently been found when data are analysed using individual exposures compared to the analysis of stacked exposures (Miller et al., in preparation). Weak-lensing data in the future will therefore not be analysed from a co-addition of exposures where all atmospheric turbulent effects have de-correlated, as it has been to date. With a wide range of exposure times, wind speeds and directions, we test the findings of de Vries et al. (2007) that the atmospheric ellipticity decreases with time as \(t^{-1/2}\) and also the findings of Asztalos et al. (2007) that the atmospheric ellipticity is correlated with the wind speed and direction. Our results complement efforts to accurately simulate these effects (Chang et al., in preparation) and inform the hardware and software design of future ground-based surveys accordingly.

This paper is organized as follows. In Section 2 we describe the data and analysis methods, presenting the results and analysis in Section 3 and conclusions in Section 4.

## 2 DATA AND METHODS

We analyse the CFHT PSF using a series of observations of dense stellar fields imaged and archived by the CFHT and listed in Table 1. We select exposures taken in sub-arcsecond seeing conditions in the band over a range of exposure times. Our main sample of 60 exposures imaged in 74 s were taken during three different observing runs sampling a wide range of wind speeds and directions. We also analyse nine other samples with exposure times ranging from 1 to 450 s with each set observed on different nights.

### Table 1. Table of CFHT archive data used in this analysis, listing the exposure time, total number of exposures used, the CFHT Proposal ID which can be used to query the CFHT Science Data Archive, and the range of observation dates.

| Exp. time | No. of exp. | Proposal ID | Date         |
|----------|-------------|-------------|--------------|
| 1.0      | 28          | 08AH22      | 2008-4-14/5-7|
| 2.0      | 7           | 03BF99      | 2004-1-19/23 |
| 10.0     | 33          | 06BH48      | 2006-8-19/22 |
| 30.0     | 9           | 03BF99      | 2004-1-19/23 |
| 45.0     | 5           | 03BQ97      | 2003-9-30    |
| 74.0     | 60          | 08AH22      | 2008-4-14/5-8|
| 180.0    | 9           | 03BL06      | 2003-10-3    |
| 300.0    | 11          | 08AH53      | 2008-2-13/14 |
| 450.0    | 12          | 07BC02      | 2007-11-14/1-10|
The data were processed and stellar object catalogues produced as described in Hoekstra et al. (2006), yielding a typical stellar density of 7 stars arcmin\(^{-2}\), and in all data sets a significantly greater stellar density than that available in extragalactic imaging survey data taken out of the Galactic plane. We parametrize the PSF in terms of stellar ellipticity as measured by weighted quadrupole moments
\[
Q_{ij} = \frac{\int d^2\theta W(\theta) I(\theta) \delta \theta}{\int d^2\theta W(\theta) I(\theta)},
\]
where \(I(\theta)\) is the surface brightness of the star, \(\theta\) is the angular distance from the star centre and \(W\) is a Gaussian weight function of scalelength \(r_e\), where \(r_e\) is the measured dispersion of the PSF (Kaiser, Squires & Broadhurst 1995). For a perfect ellipse, the weighted quadrupole moments are related to the weighted ellipticity parameters \(\epsilon_{\theta}\) by
\[
\begin{pmatrix}
\epsilon_1 \\
\epsilon_2
\end{pmatrix} = \frac{1}{R^2} \begin{pmatrix}
Q_{11} - Q_{22} \\
2Q_{12}
\end{pmatrix},
\]
where \(R\) is related to object size and given by
\[
R = \sqrt{Q_{11} + Q_{22}}.
\]
If the weight function \(W(\theta) = 1\) in equation (1), the ellipticity or polarization \(|\epsilon| = (1 - \beta^2)/(1 + \beta^2)\), where \(\beta\) is the axial ratio of the ellipse (see Bartelmann & Schneider 2001). We note that for the purposes of this study, the quadrupole moment description of the PSF that we adopt is sufficient. For a detailed weak-lensing analysis, however, many techniques now determine either a set of orthonormal two-dimensional (2D) basis functions or a 2D pixel-based model to describe the PSF (Kitcing et al. 2011). Both these methods would be more challenging to model in the presence of a high-order spatial frequency variation.

In each exposure the variation of the PSF ellipticity \(\epsilon_{\theta,\text{PSF}}\) and size \(R\) across the field of view is considered to have two components: a smoothly varying second-order polynomial over position, \(\epsilon_{\theta,\text{model}}(x, y)\) and \(R(x, y)\) for each chip and higher spatial varying residuals with
\[
\delta \epsilon_i = \epsilon_{\theta,\text{PSF}} - \epsilon_{\theta,\text{model}},
\]
\[
\delta R^2 = R_{\text{PSF}}^2 - R_{\text{model}}^2.
\]
With a typical number density of stellar objects imaged in an high-Galactic latitude field (40 per MegaCam chip, compared with over 700 in this analysis), the chipwise second-order polynomial model would be the most complex model that could be accurately fitted to lensing survey data (Rowe 2010).

3 ANALYSIS AND RESULTS

Fig. 1 shows a typical PSF pattern for a 74-s exposure as imaged by MegaCam at CFHT. The field of view is a square degree with a pixel scale of 0.186 arcsec and an 9 × 4 CCD pattern which is visible. The left- and right-hand panels show the variation in the amplitude of the average PSF \(\epsilon_1\) and \(\epsilon_2\), respectively, across the field of view. Each grid point in the grey-scale map contains on average 5 stars and spans 0.3 × 0.3 arcmin. In an image of a typical field, out of the Galactic plane, we would find ~1 usable star in every ~5 grid points (~0.4 stars arcmin\(^{-2}\)). The upper panels show the observed ellipticity variation. The middle panels show the second-order chipwise polynomial model fit to the data. The lower panels reveal the residual ellipticity \(\delta \epsilon_{1}\) and \(\delta \epsilon_{2}\) components. Fig. 2 shows the size variation for the same exposure with the size residuals (right-hand panel) showing the same high spatial frequencies and a preferred direction as the ellipticity residuals. For the rest of the paper, we focus mainly on the ellipticity variation, but come back to the size variation in Section 4, where we show that the high spatial frequency variation of the PSF size is as detrimental to the weak-lensing shape measurement as the variation in ellipticity.

In order to investigate the high spatial frequency variation of the PSF, we measure the two-point correlation function of the residual PSF ellipticities in Fig. 3, showing the average systematic residual PSF correlation functions \(\xi_{\pm}\) (upper two panels) and \(\xi_{\pm}\) (lower panel) where

\[
\xi_{\pm}^{\epsilon}(\theta) = \langle \epsilon_i(\theta') \epsilon_j(\theta' + \theta) \rangle \pm \langle \epsilon_i(\theta') \epsilon_j(\theta') \rangle
\]

and \(\epsilon_{\pm}\) are the tangential and rotated ellipticity parameters rotated into the reference frame joining each pair of correlated objects. The average is taken over all exposures in our sample split by exposure length. Fig. 3 shows the amplitude of the residuals for four sets of decreasing exposure time, revealing a characteristic shape to
Figure 2. A typical PSF size pattern for the same 74-s exposure shown in Fig. 1. The left-hand panel shows the variation in PSF size $R$ across the field with the grey-scale in arcsec. The right-hand panel shows the residual variation in size after a second-order polynomial model has been removed. The ripple pattern in size follows the same structure as the ellipticity residuals. The right-hand grey-scale is in units of $10^{-3}$ arcsec$^2$.

Figure 3. The $\xi_+(\theta)$ and $\xi_-(\theta)$ correlation function estimates for the PSF ellipticity data, with best-fitting von Kármán models overlaid on the $\xi_+$ results and the corresponding $\xi_-$ prediction plotted over the measured $\xi_-$ results (see Section 3.1 and Appendix A). Upper panel: the $t = 1$ s (solid line: best-fitting model) and $t = 7.5$ s (dashed line: best-fitting model) $\xi_+(\theta)$ results. Middle panel: the $t = 74$ s (solid line: best-fitting model) and $t = 450$ s (dashed line: best-fitting model) $\xi_+(\theta)$ results. Lower panel: the $t = 1$ s, and $t = 7.5$ s, $\xi_-(\theta)$ results (the longer exposure PSF patterns showed $\xi_-$ consistent with zero on all scales).

the correlation function that we find for all exposure times, $\xi_+$ is positively correlated $\theta < 2$ arcmin, anti-correlated $2 < \theta < 7$ arcmin, then positively correlated until it becomes consistent with zero $\theta > 15$ arcmin. This characteristic shape is also seen in the results of Wittman (2005). $\xi_-$ is measured with significance only for the shortest exposures (shown in the lower panel) and is positively correlated for all scales $\theta < 15$ arcmin.

The residual PSF correlation functions measured between consecutive 1, 10 and 74 s exposures were found to be consistent with zero. We can therefore conclude that the atmospheric turbulence distortion de-correlates in $\lesssim 50$ s, where the time-scale is set by the CFHT MegaCam readout, overheads, slew and acquisition time. This is in agreement with the findings of Wittman (2005), who set a de-correlation time $< 120$ s, limited by the Subaru readout time.

3.1 Comparison to a simple, isotropic turbulence model

The von Kármán model for isotropic atmospheric turbulence predicts a projected, 2D power spectrum

$$P(l) \propto \left( l^2 + \frac{1}{\theta_0^2} \right)^{-11/6},$$

(7)

where the angle $\theta_0$ defines the outer scale of the spectrum (e.g. Sasiela 1994). In this model, a physically motivated modification of the scale-free Kolmogorov spectrum, turbulent structures in images of the sky become uncorrelated at separations greater than $\theta_0$. As shown in Appendix A, the isotropic $\xi_+$ correlation function for such a spectrum may then be written as

$$\xi_+(\theta) \propto \theta^{5/6} K_{-5/6}(2\pi \theta/\theta_0),$$

(8)

where $K_{\nu}(x)$ is the modified Bessel function of the second kind (Arfken & Weber 2005). Numerical approximation of these functions is simple via the useful series expansion of Kostroun (1980). The functional form of $\xi_-$ is given in equation (A4). This expression is significantly more complicated than the $\xi_+$ case and was found to be prone to numerical instabilities.

We now investigate whether the model given in equation (8) is able to reproduce the correlation function results seen in Fig. 3. We restrict ourselves to fitting only the $\xi_+$ model, which can be simply calculated and carries almost all the detectable signal. We go on to compare predictions for $\xi_-$ based on these fitting results to measurements of $\xi_-$ in the data. In Fig. 3 we have overlaid the best-fitting von Kármán models to the $\xi_+$ correlation function estimates for each of the example $t = 1, 7.5, 74$ and 450 s exposure data sets. The Levenberg–Marquardt algorithm (e.g. Press et al. 1986) was used to determine the maximum-likelihood parameter fits to the overall amplitude of the expression in equation (8), and for the outer scalelength $\theta_0$. In the lower panel of Fig. 3 we use the best-fitting values of $\theta_0$ from the $\xi_+$ models to generate a von Kármán prediction for the $\xi_-$ signal in the $t = 1$ and 7.5 s exposure data.

It can be seen that the von Kármán model gives a reasonable fit to the inner slope of $\xi_+$ for the three $t = 1, 7.5$ and 74 s exposure data sets in Fig. 3. For these three sets, we also found broadly consistent best-fitting values of the outer scale in the range $\theta_0 = 2.62–3.22$ arcmin. These results suggest a turbulent origin for the small-scale correlated ellipticity measurements in these images, but in all three cases the von Kármán model fails to capture both the trough on scales $\theta \approx 4$ arcmin, and the second peak in correlation near 10 arcmin. The discrepancy is also marked in the comparison between the $\xi_-$ model and the data. Here, a very distinct excess ‘bump’ is seen, again peaking around $\theta \approx 4$ arcmin in the 1-s exposure-time data. However, as the amplitude of the $\xi_-$ correlation is consistently smaller than that of $\xi_+$, these results are noisier.

We discuss potential origins for these features in Section 4. For the $t = 450$ s data, we found a model amplitude consistent with zero, indicative of the weakness of the signal for this long-exposure data.
residual correlation as a function of 2D vector angular separation $\theta$. Results are shown for two representative angular scales with $\xi_+$ measured at $\theta = 0.7$ arcmin (upper), where the von Kármán atmospheric turbulence model provides a good fit to the data, and at $\theta = 4.9$ arcmin, which corresponds to the first negative dip in the correlation function. We find that the de Vries et al. (2007) model (shown as dot–dashed) is a good fit to the data, but note that for this analysis, we were unable to select a significant sample size of exposures with a constant wind speed as is assumed in the de Vries et al. (2007) theory. We conclude that the scatter we see in the results must be in part driven by the range of wind speeds within our sample.

Fig. 4 also allows us to compare the amplitude of the atmospheric turbulence to the expected cosmological signal in the CFHT Lensing Survey (CFHTLenS$^1$). For both angular scales $\theta$ shown, we overplot two horizontal bars that indicate the amplitude of the two-point shear correlation function $\xi_+$ for two low-redshift tomographic bins with a mean redshift $z = 0.37$ and 0.54, determining the exposure time below which the cosmological signal becomes lower than the residual atmospheric PSF signal.

3.2 Dependence of the amplitude of the atmospheric distortion on exposure time

A key result from the simulations of de Vries et al. (2007) showed that the ellipticity introduced by atmospheric aberrations decreases with time as $t^{-1/2}$, assuming a constant wind speed. The two-point correlation function of the atmospheric variations $\xi_+$ is therefore expected to decrease in amplitude as $t^{-1}$. Fig. 4 shows the average two-point correlation function $|\xi_+|$ as a function of the exposure time. Results are shown for two representative angular scales with $\xi_+$ measured at $\theta = 0.7$ arcmin (upper), where the von Kármán atmospheric turbulence model provides a good fit to the data, and at $\theta = 4.9$ arcmin, which corresponds to the first negative dip in the correlation function. We find that the de Vries et al. (2007) model (shown as dot–dashed) is a good fit to the data, but note that for this analysis, we were unable to select a significant sample size of exposures with a constant wind speed as is assumed in the de Vries et al. (2007) theory. We conclude that the scatter we see in the results must be in part driven by the range of wind speeds within our sample.

In order to compare the turbulence patterns observed to the wind direction, we quantify the direction of the atmospheric turbulence using correlation as a function of vector separation and direction on the sky, rather than the commonly used, azimuthally averaged functions $\xi_+(\theta) = \xi_+(|\theta|)$. We calculate the $\xi_+$ residual correlation as a function of vector angular separation $\theta$ using the discrete Fourier transform to find the power spectrum of the $\delta\varepsilon_1$ and $\delta\varepsilon_2$ images (examples of which are shown in Fig. 1), then employing the Wiener–Khinchin theorem to generate images of $\xi_+(\theta)$.

Four example results are shown in Fig. 5 revealing a non-isotropic function. The example exposure shown in Fig. 1 is the same as presented in the upper right-hand panel of Fig. 5. A comparison of these two figures shows that the elliptical $\xi_+(\theta)$ has a central dipole with a major axis along the direction of the ripples seen in the $\delta\varepsilon_1$ maps of Fig. 1. For other exposures, however, we see what appears to be a superposition of ripple patterns (see for example the upper left and lower right panels of Fig. 5), potentially arising from different turbulent layers in the atmosphere. In these cases, the orientation of the central dipole indicates the average ripple direction. Based on these comparisons over the full data set, we use the orientation of the central dipole to determine an effective ripple orientation, and we measure this orientation using the quadrupole moments in equation (2) with $r_z = 2.3$ arcmin. Applying this method to all exposures with $t \leq 74$ s, where the amplitude of the atmospheric turbulence is sufficiently high, we can then compare this ripple direction to the wind direction relative to the image (shown by

\[ \frac{\delta\varepsilon_1}{\delta\varepsilon_2} \]

Figure 5. The $\xi_+$ residual correlation as a function of 2D vector separation $\theta$ for four example 74-s exposures. The dominant direction of the PSF residuals can be compared to the wind direction shown as an arrow inset. The upper left panel shows an example exposure with a wind speed of 14 ms$^{-1}$. The upper right panel shows the exposure shown in Fig. 1 and has a wind speed of 6 ms$^{-1}$. The lower left panel has a wind speed of 2 ms$^{-1}$ and the lower right panel has a wind speed of 11 ms$^{-1}$.
C. Heymans et al.

Figure 6. A comparison of the wind direction and the PSF residual direction as a function of the ground wind speed measured at the start of each observation for three samples grouped by exposure time with $t \leq 10$ s (stars), $10 < t \leq 45$ s (circles) and $t = 74$ s (crosses).

The measured residual ellipticity correlation in our $t = 10$ s data set compared to the expected WMAP7 cosmological two-point shear correlation signal for three tomographic bins with a mean redshift $z = 0.37$, 0.54 and 0.79 (solid lines, the lowest amplitude corresponds to the lowest redshift bin). The data oscillate between positive and negative correlation which we indicate on this log–log plot using filled points where the data are negative, which is primarily between the two dashed vertical lines.

4 CONCLUSIONS: IMPACT FOR WEAK-Lensing OBSERVATIONS

In this study we have analysed short-exposure observations of dense stellar fields to quantify the high spatial frequency variation of the PSF which we attribute to atmospheric effects. We have shown that in short exposures with $t \leq 30$ s, the atmosphere contributes a significant correlated anisotropy to the PSF on angular scales of $\theta < 10$ arcmin that would dominate the cosmological signal measured in the lower redshift bins of a cosmological tomographic analysis. On these angular scales, the high spatial frequency of the atmospheric aberration is too rapid to model with a typical stellar density and standard methods.

This does not mean, however, that multiple short-exposure images cannot be combined in a way that reduces the cumulative impact of this (random) atmospheric anisotropy on estimates of gravitational shear in the final analysis. We found that the turbulent patterns in consecutive exposures are statistically uncorrelated when separated by time-scales of $\leq 50$ s. Our observations motivate the combination of information from multiple short-exposure images in a way that takes advantage of this fact. Examples of such approaches might be cross-correlating shear estimates from different exposures to estimate the shear autocorrelation, or combining images into a stacked, co-added image. If stacking, great care must taken to retain control and knowledge of changes in the PSF due to interpolation and stacking of dithered data. Rowe, Hirata & Rhodes (2011) present an example of a linear image stacking approach that seeks to preserve this information.

As well as finding that consecutive exposures are uncorrelated, we have confirmed the predictions of de Vries et al. (2007) in finding that the amplitude of atmospheric distortion patterns decreases with time as $t^{-1.2}$. Our results also show that this effect is not a significant source of error for the CFHTLenS survey, where for the first time a lensing survey is analysing the 600-s exposures individually (Miller et al., in preparation), as compared to previous analyses using a stack (Fu et al. 2008).

Fig. 7 compares the measured residual ellipticity correlation in our $t = 10$ s data set with the expected cosmological signal for three tomographic bins with a mean redshift $z = 0.37, 0.54$ and 0.79. This is the closest data set analysed to the proposed $t = 15$ s exposures for LSST. This figure shows that our findings agree to some extent with those of Jee & Tyson (2011), who focus on angular scales $\theta > 10$ arcmin and find that the PSF can be modelled to high accuracy on these scales. For smaller angular scales, however, atmospheric turbulence effects will be a significant source of systematic error in a weak-lensing analysis if not corrected for. Furthermore, as a result of the anisotropic nature of the residual correlation function shown in Fig. 5, the effect of atmospheric turbulence may leak to larger scales.

For a future generation all-sky lensing survey, Amara & Réfrégier (2007) derive a requirement on the variance of systematic errors to be below $\sigma_{\text{sys}}^2 < 10^{-7}$ such that experiments are limited by statistical noise rather than systematic errors (see also van Waerbeke et al. 2006 for a similar conclusion). To reach this goal, Paulin-Henriksson et al. (2008) show that this requires $\sigma[R_{\text{PSF}}] \lesssim 10^{-3}$ for each ellipticity component and $\sigma[R_{\text{gal}}] \lesssim 10^{-3} R_{\text{gal}}$ for $\epsilon_{\text{PSF}} \approx 0.05$ and a typical galaxy/PSF size ratio of $R_{\text{gal}}/R_{\text{PSF}} \gtrsim 1.5$. For the $t = 10$ s data, we
measure
\[ \sigma[\varepsilon_{\text{PSF}}] = \sqrt{\langle \delta \varepsilon_i^2 \rangle} = (9.9 \pm 1.7) \times 10^{-3}, \tag{9} \]
\[ \frac{\sigma[R_{\text{PSF}}^2]}{R^2} = \sqrt{\langle \delta R_i^2 \rangle / \langle R^2 \rangle} = (9.6 \pm 2.0) \times 10^{-3}, \tag{10} \]
where the error is calculated from the scatter between the 33 exposures in the \( t = 10 \) s data set showing the variance within the set, not the error on the mean. These measurements are an order of magnitude larger in both size and ellipticity compared to the requirements quoted in Amara & Réfrégier (2007).

Using equation (15) of Paulin-Henriksson et al. (2008) we can calculate the variance of the systematic errors we would expect from the residual atmospheric size and ellipticity variation that we measure from the \( t = 10 \) s data set: we find \( \sigma_{\text{sys}}^2 \sim 10^{-5} \). This value can be interpreted as the systematic variance produced in multiple 10-s exposures if: (i) the turbulent PSF cannot be modelled due to insufficient stellar density and (ii) no attempt is made to combine shear estimates from multiple exposures for which the turbulence patterns are mutually statistically independent. We note that this calculation depends on the accuracy of both PSF ellipticity and PSF size characterization, and these are affected by atmospheric turbulence.

We note that while the expectation of the turbulent contribution to \( \varepsilon_{\text{PSF}} \) across multiple exposures is zero, assuming any static component is removed, this is not the case for \( R_{\text{PSF}}^2 \). This has implications for plans to cross-correlate using only shear estimates from different exposures to suppress PSF model errors. The utility of such a scheme is that the ellipticity cross-terms \( \delta \varepsilon_i \delta \varepsilon_j \) (for \( i \neq j \)) have a zero expectation value, and the variance of this product is the square of the individual variances. This product variance decreases \( \propto 1 / \sqrt{N_{\text{exp}}} \), where \( N_{\text{exp}} \) is the total number of exposures being cross-correlated, and therefore \( \sigma[\varepsilon_{\text{PSF}}] \) decreases rapidly as \( \propto 1 / \sqrt{N_{\text{exp}}} \) in the cross-correlation.

However, the same approach does not reduce uncertainty in \( R_{\text{PSF}}^2 \) at the same rate because this quantity has an unknown expectation value which must be characterized. Instead, \( \sigma[R_{\text{PSF}}^2] \propto 1 / \sqrt{N_{\text{exp}}} \). This differing behaviour in the combination of multiple exposures must be considered when comparing the results in equations (9) and (10) to the required levels for the estimation of cosmic shear. The characterization of turbulent variation in \( R_{\text{PSF}}^2 \) therefore assumes added importance for upcoming surveys. Combined with \( N_{\text{exp}} \), the single-exposure value quoted in equation (10) can be used to estimate this important effect for surveys using multiple exposures of duration \( t \approx 10 \) s, assuming atmospheric conditions similar to those at CFHT.

Both the results of this paper and of Wittman (2005) show an oscillatory pattern in the residual \( \xi_\theta \) correlation function at \( \theta > 2.5 \) arcmin, a pattern which is not consistent with the model predicted by a simple, isotropic von Kármán spectrum (see Fig. 3). Wittman (2005) describes this ringing as an artefact of the interpolation scheme used to model the PSF on each individual chip which for the Supreme-Cam camera used in these observations has a chip size of 13.65 \times 6.83 arcmin\(^2\). In this analysis, we apply a similar, lower-order chipwise PSF model, where for MegaCam the chip size is 12.70 \times 6.35 arcmin\(^2\). We thus agree with Wittman (2005) that one possible origin for the ‘ringing’ is oversubtraction of a chipwise PSF model for the telescope optics, as the first dip occurs at a close to half the shorter dimension of the chip.

However, it is less clear why chipwise fitting would cause an excess at 10 arcmin. In addition, looking at the \( \xi_\theta(\theta) \) (i.e. not circularly averaged) two-point correlation functions (e.g. Fig. 5), we see that the oscillatory pattern is anisotropic in nature but often not aligned with the x-y chip grid. This alignment would be something to be expected if it were an artefact of the chipwise PSF model removal. We therefore offer an alternative suggestion that these ripples have an atmospheric origin, related to anisotropy in the atmospheric power spectrum (cf. Fig. 5), which cannot be generated by simple isotropic models such as the von Kármán. This conclusion is supported by the finding that the residual patterns are uncorrelated between exposures. However, without further data, or access to imaging with chips of differing dimensions, it remains difficult to say definitively which interpretation is correct.

Although not performed explicitly in this study, it is worthwhile mentioning the separation of the correlated turbulence signal into ‘E’ and ‘B’ mode contributions (see e.g. Crittenden et al. 2002). The atmospheric PSF pattern for a turbulent sky may contain both E and B modes; if this PSF is not properly modelled, any shear catalogue will therefore contain an imprint of this pattern. An E/B-mode decomposition of the cosmic shear signal on the scales where atmospheric turbulence patterns are correlated might therefore detect this effect in the form of a non-zero B mode. However, telescope optical aberrations, which also contribute strongly to PSF anisotropy across most angular scales of interest for lensing, tend to generate a more significant E mode than B mode (Hoekstra 2004). In addition, cosmological effects can also generate B modes (e.g. Schneider, Van Waerbeke & Mellier 2002; Vale et al. 2004). The absence of strong B modes in cosmic shear measurements therefore remains a problematic indicator of the absence of systematic errors due to PSF anisotropy, and the potential presence of B modes in turbulent PSF patterns does not alter this fact.

Finally, when considering our full sample of data, we have found little evidence for a strong and consistent relationship between the preferred direction of anisotropic correlations in atmospheric distortion and the ground-based wind velocity. We do not necessarily expect to find such a relationship, as all the turbulent layers responsible for the atmospheric PSF pattern are not necessarily correlated with the ground conditions. However, we do find that consecutive observations seem to yield similar angular offsets between wind direction and turbulent PSF pattern orientation: such effects might lead to an over-interpretation of the correlation between wind direction and PSF pattern orientation in more limited data sets. In all, these results do not strongly motivate the use of the ground-based wind direction and speed as an input to a PCA-type model of the atmospheric part of the PSF on short-exposure data. However, it may still be useful in modelling out repeatable PSF distortions due to telescope motion under wind (see e.g. Jarvis & Jain 2004). Once again, this motivates data analysis strategies that take advantage of the turbulent pattern being uncorrelated between successive exposures.

ACKNOWLEDGMENTS

We thank Chihway Chang, Phil Marshall and the rest of the CFHTLenS collaboration for convincing us to write this analysis into a paper and for many useful discussions along the way. We also thank the anonymous referee for helpful comments and the CFHT QSO team and PIs of the various data sets used in this analysis; Jerome Bouvier, Catherine Dougados, Eugene Magnier, Alan McConnachie and John Johnson. CH and BR acknowledge support from the European Research Council under the EC FP7 grant numbers 240185 (CH) and 240672 (BR). HH acknowledges support from Marie Curie IRG grant 230924 and the Netherlands...
Organisation for Scientific Research grant number 639.042.814. TE is supported by the Deutsche Forschungsgemeinschaft through project ER 3273/1-1 and the Transregional Collaborative Research Centre TR 33 – ‘The Dark Universe’. TK was supported by a RAS 2010 Fellowship. This study uses data from the CFHT Science Data Archive hosted and supported by the Canada Astronomy Data Centre operated by the National Research Council of Canada with the support of the Canadian Space Agency.

All authors assisted with the development and writing of this paper. CH and BR co-led the statistical analysis, HH conceived the project and led the data mining, catalogue production and data analysis, LM motivated the project and led the visualization of the effect.

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APPENDIX A: CORRELATION FUNCTIONS FOR THE VON KÁRMÁN POWER SPECTRUM

As in the case of cosmological shear, the ellipticity correlation functions \( \xi_\perp(\theta) \) and \( \xi_\parallel(\theta) \) (see Bartelmann & Schneider 2001) due to atmospheric effects can be related to power spectrum of the von Kármán model as

\[
\xi_\perp(\theta) \propto \int_0^\infty l \, dl \, J_0(2\pi l \theta) \left[ l^2 + \frac{1}{l_0^2} \right]^{-11/6}, \tag{A1}
\]

where \( J_0(x) \) is the \( v \)-th order Bessel function, and where we assume that the spatial power spectrum of ellipticity distortions due to turbulence follows \( P(l) \) as given in equation (7). Using these expressions, we calculate the \( \xi_\parallel \) correlation function as

\[
\xi_\parallel(\theta) \propto \theta^{5/6} K_{-5/6}(2\pi \theta / \theta_0), \tag{A3}
\]

where \( K_{-5/6}(x) \) is the modified Bessel function of the second kind (Arfken & Weber 2005). The expression for \( \xi_\parallel \) is more complicated:

\[
\xi_\parallel(\theta) \propto \theta^{-7/6} \left( 6 \theta_0^2 + \pi^2 \theta^2 \right) I_{-11/6}(2\pi \theta / \theta_0) - \frac{13\pi}{6} \theta_0 \theta^{-1/6} I_{-11/6}(2\pi \theta / \theta_0) \nonumber \\
+ \theta^{-7/6} \left( \frac{5}{36} \theta_0^2 - \pi^2 \theta^2 \right) I_{-11/6}(2\pi \theta / \theta_0) \nonumber \\
+ \frac{13\pi}{6} \theta_0 \theta^{-1/6} I_{-23/6}(2\pi \theta / \theta_0) - \theta_0^{-1/6} \theta^{-4} \frac{385}{432} \theta_0^2 - 70 \pi^2 \theta^2 \right) \Gamma(-7/6). \tag{A4}
\]

This result will be used below to derive the projected direction of ground wind on telescope images.

The pixel y-axis of the MegaCam instrument mounted on CFHT rotates to align with the celestial North Pole. In the horizontal coordinate system defined at the telescope, celestial North Pole has the altitude–azimuth coordinates \((a_1, A_1)\) in this coordinate system. The points \( N \) and \( T \) on the celestial sphere can be connected by the arc of a great circle of constant right ascension. The y-axis of CFHT images will align with this meridian.

The direction of ground wind is measured at CFHT and supplied with the astronomical images in degrees relative to compass north along the ground. In the horizontal coordinate system at CFHT, this direction can therefore be expressed as \( W = (0, A_w) \), where \( A_w \) is the measured wind direction. We may then define a second
Atmospheric distortions

The great circle passing through \( W \) and \( T \). The angle \( \theta \) at which this great circle intersects the meridian through \( T \) and \( N \) is therefore the projected direction of ground wind on the telescope image, relative to the CCD \( y \)-axis.

The spherical law of cosines gives the following result for this projected wind direction angle \( \theta \):

\[
\cos(\theta) = \frac{\cos(\gamma) - \cos(\alpha) \cos(\beta)}{\sin(\alpha) \sin(\beta)},
\]

(B2)

where from equation (B1) we have

\[
\cos(\alpha) = \cos(a_t) \cos(A_w - A_t),
\]

(B3)

\[
\cos(\beta) = \cos(a_t) \cos(\phi) \cos(A_t) + \sin(a_t) \sin(\phi),
\]

(B4)

\[
\cos(\gamma) = \cos(A_w) \cos(\phi).
\]

(B5)

However, the expressions above do not provide the sign of \( \theta \), i.e. whether \( W \) lies to the west or east of the meridian through \( T \) and \( N \), the \( y \)-axis on the telescope image. This information is needed to correctly calculate the angular separation between the wind direction and the primary PSF residual direction as described in Section 3.3.

The positive direction on the CCD \( x \)-axis of MegaCam can be associated with positive hour angle \( H \) in the equatorial coordinate system. If we define the positive \( \theta \) direction as that moving clockwise from the \( y \)-axis, then it is straightforwardly seen that

\[
\text{sgn}(\theta) = \text{sgn}(H_w - H_t),
\]

(B6)

where \( \text{sgn}(x) \) is the signum function, \( H_w \) is the hour angle of the wind direction vector \( W \) and \( H_t \) is the hour angle of the telescope pointing direction \( T \) at the local sidereal time of observation. The telescope hour angle \( H_t \) is provided by CFHT as metadata alongside all astronomical images, so it remains solely to determine \( H_w \).

Using standard formulae for the conversion of horizontal to equatorial spherical coordinates, the declination \( \delta_w \) of the wind vector \( W \) is given by

\[
\sin(\delta_w) = \cos(\phi) \cos(A_w).
\]

(B7)

The hour angle of \( W \) is then given by

\[
H_w = \arcsin \left[ \frac{-\sin(A_w)}{\cos(\delta_w)} \right]
\]

= \arcsin \left[ \frac{-\sin(A_w)}{\sqrt{1 - \cos^2(\phi) \cos^2(A_w)}} \right].
\]

(B8)

When substituted into equation (B6) this allows the sign of \( \theta \) to be calculated. In combination with the determination of the magnitude of \( \theta \) from equation (B2), the projected direction of ground wind on a telescope image pointing in the direction \( T \) is fully specified.

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