Strong Existence and Higher Order Fréchet Differentiability of Stochastic Flows of Fractional Brownian Motion Driven SDEs with Singular Drift

David Baños1 · Torstein Nilssen2 · Frank Proske3

Received: 29 April 2019 / Revised: 18 August 2019 / Published online: 6 September 2019
© Springer Science+Business Media, LLC, part of Springer Nature 2019

Abstract
In this paper we present a new method for the construction of strong solutions of SDE’s with merely integrable drift coefficients driven by a multidimensional fractional Brownian motion with Hurst parameter $H < \frac{1}{2}$. Furthermore, we prove the rather surprising result of the higher order Fréchet differentiability of stochastic flows of such SDE’s in the case of a small Hurst parameter. In establishing these results we use techniques from Malliavin calculus combined with new ideas based on a “local time variational calculus”. We expect that our general approach can be also applied to the study of certain types of stochastic partial differential equations as e.g. stochastic conservation laws driven by rough paths.

Keywords SDEs · Compactness criterion · Irregular drift · Malliavin calculus · Stochastic flows · Sobolev derivative

Mathematics Subject Classification 60H10 · 49N60

1 Introduction
Consider a fractional Brownian motion $B_t^H$, $t \geq 0$ with Hurst parameter $H \in (0, 1)$ on a probability space $(\Omega, \mathcal{F}, P)$, that is a centered Gaussian process with a covariance structure $R_H(t, s)$ given by
\[ R_H(t, s) = \mathbb{E}[B_t^H B_s^H] = \frac{1}{2} \left( s^{2H} + t^{2H} - |t - s|^{2H} \right) \]

for all \( t, s \geq 0 \). The fractional Brownian motion, which is a Brownian motion in the case \( H = \frac{1}{2} \), enjoys the property of self-similarity, that is
\[
\{B_{\alpha t}^H \}_{t \geq 0} \overset{\text{law}}{=} \{ (\alpha^H B)^H_t \}_{t \geq 0}
\]
for all \( \alpha > 0 \). In fact the fractional Brownian motion, which has a version with \( H - \varepsilon \)-Hölder continuous paths for every \( \varepsilon \in (0, H) \), is the only stationary Gaussian process satisfying the latter property. On the other hand this process is neither a Markov process nor a (weak) semimartingale and it is a very irregular process in the sense of rough paths for small Hurst parameters. See e.g. [43] and the references therein for more information about fractional Brownian motion.

In this article we aim at analysing solutions \( X^x \) of the stochastic differential equation (SDE)
\[
X^x_t = x + \int_0^t b(s, X^x_s) ds + B_t^H, \quad 0 \leq t \leq T, \quad x \in \mathbb{R}^d, \tag{1.1}
\]
where \( B^H \) is a \( d \)-dimensional fractional Brownian motion, whose components are one-dimensional independent fractional Brownian motions as defined above, with Hurst parameter \( H \in (0, \frac{1}{2}) \) with respect to a \( P \)-augmented filtration \( \mathcal{F} = \{ \mathcal{F}_t \}_{0 \leq t \leq T} \) generated by \( B^H \) and where \( b : [0, T] \times \mathbb{R}^d \rightarrow \mathbb{R}^d \) is a Borel-measurable function.

If we impose a global Lipschitz and a linear growth condition uniformly in time on the drift coefficient \( b \) in (1.1), we can use the Picard iteration scheme to obtain a unique global strong solution to the SDE (1.1), that is an \( \mathcal{F} \)-adapted solution \( X^x_t \) to (1.1), which is a measurable \( L^2(\Omega) \)-functional of the driving noise.

However, a variety of important applications of such SDE’s to stochastic control theory (in the case of \( H = \frac{1}{2} \)) (see [28]) or to the statistical mechanics of infinite particle systems (see [29]) show that the use of SDE’s with regular coefficients in the sense of Lipschitzianity as models for random phenomena is not suitable and that one is forced to study such equations with coefficients which are irregular, that is discontinuous or merely measurable.

One objective of our paper is the construction of unique strong solutions to the SDE (1.1) driven by rough paths in the case of multidimensional fractional noise \( B^H \) for Hurst parameters \( H < \frac{1}{2} \) and drift coefficients
\[
b \in L^1(\mathbb{R}^d; L^\infty([0, T], \mathbb{R}^d)) \cap L^\infty(\mathbb{R}^d; L^\infty([0, T], \mathbb{R}^d)). \tag{1.2}
\]
In proving this new result, we employ tools from Malliavin Calculus and local time techniques.

The analysis of strong solutions to (1.1) has been a very active field of research in various branches of mathematics over the last decades. A foundational result in this direction of research was first obtained by Zvonkin in the beginning of the 1970ties [51], who showed the existence of a unique strong solution of one-dimensional Brownian motion driven SDE’s (1.1), when the drift coefficient \( b \) is merely bounded and measurable. A few years later on, the latter result was generalised by Veretennikov [48] to the multidimensional case.

More recently, Krylov and Röckner [29] gave the construction of unique strong solutions to (1.1) under integrability conditions on the (time-inhomogeneous) drift coefficient \( b \). See also the articles [24] or [23]. In this context, we shall also mention the generalization of Zvonkin’s result to the case of stochastic evolution equations in Hilbert spaces with bounded and measurable drift coefficients [14], where the authors use solutions to infinite-dimensional
Kolmogorov equations to recast the singular drift term of the evolution equation in terms of a more regular expression (“Itô–Tanaka–Zvonkin trick”).

In all of the above mentioned works the common technique of the authors for the construction of strong solutions rests on the so-called Yamada–Watanabe principle (see [50]), which entails strong uniqueness of solutions to SDE’s, if pathwise uniqueness of (weak) solutions holds.

In fact, in order to ensure strong uniqueness of solutions, the above authors construct weak solutions to SDE’s, which are not necessarily Brownian functionals, by means e.g. of [23,24], Skorokhod embedding combined with Krylov’s estimates and verify pathwise uniqueness by using solutions of parabolic partial differential equations (see e.g. [48,51] or [29]).

We remark that the techniques of these authors for proving pathwise uniqueness are not applicable to SDE’s driven by fractional Brownian motion, since the fractional Brownian is neither a Markov process nor a semimartingale for Hurst parameters \( H \neq \frac{1}{2} \).

Further, we emphasise that our method, which is not only limited to Markov or semimartingale solutions of SDE’s, gives a direct construction of strong solutions and provides a construction principle, which can be considered the converse to that of Yamada–Watanabe: We prove the existence of strong solutions and uniqueness in law to guarantee strong uniqueness.

The SDE (1.1) for fractional Brownian initial noise has been already studied by various authors in the literature:

The case \( d = 1 \) for Hurst parameters \( H \in (0, 1) \) was treated in [42], where the authors prove strong uniqueness for linear growth drift in the case \( H < \frac{1}{2} \) by invoking a method based on the comparison theorem. See also [41].

Let us also mention the recent work of Catellier, Gubinelli [10], which in fact came to our attention, after the first draft. In their striking paper, which extends the results of Davie [16] to the case of a fractional Brownian noise, the authors study the problem, which fractional Brownian paths actually regularize solutions to the SDE (1.1) for \( H \in (0, 1) \). The (unique) solutions constructed in [10] are path by path with respect to time-dependent vector fields \( b \) in the Besov–Hölder space \( B_{\infty, \infty}^\alpha \), \( \alpha \in \mathbb{R} \), where in the distributional case the drift term of the SDE is given by a non-linear Young type of integral based on an averaging operator. In proving existence and uniqueness results the authors use the theorem of Arzela–Ascoli, Leray–Schauder–Tychonoff fixed point theorem and a comparison principle in connection with an average translation operator. Further, Lipschitz-regularity of solutions with respect to initial values under certain conditions is shown. In this context, we also refer to the PhD thesis of Catellier [9], where the author e.g. constructed (weak controlled) solutions to rough transport equations for vector fields \( b \) satisfying a linear growth condition and \( \text{div}(b) \in L^\infty([0, T] \times \mathbb{R}^d) \) by using rough path theory. Further, it is worth mentioning the paper of Chouk, Gubinelli [11]. Here the authors analyze modulated non-linear Schrödinger equations and improve well-posedness of such equations by means of the irregularity of the modulation. Their methods rest on rough path theory (see e.g. [33]) and an extension of Strichartz estimates to the case of Brownian modulation. See also [12] in connection with the Korteweg-de Vries equation.

Finally, we refer to other recent works by Hu et al. [26], which pertains to the study of the Brox diffusion, and Butkovski and Mytnik [8], where the authors obtain results on the regularization by (space time white) noise of solutions to a non-Lipschitz stochastic heat equation and the associated flow. Moreover, path by path unique solutions in the sense of Davie [16] are shown.

The techniques used in our paper are based on Malliavin calculus and are very different from those in the above mentioned papers—in spite of some (first impression) similarities.
regarding our estimates in Propositions 3.3 and 3.4 to the article of Davie [16], which is limited to the case of Brownian motion and whose approach doesn’t carry over to our situation. Further, the existence and uniqueness results for strong solutions to (1.1) for all (multidimensional) vector fields \( b \) as in (1.2) established in this paper are not covered by the work [10], since in this case the drift part of the SDE is given by a generalized integral based on a type of non-linear Young integral defined via the topology of the Besov–Hölder space. Moreover, our method- and this is a characteristic feature of our article-allows for the proof of higher order differentiability of stochastic flows associated with such solutions, provided the Hurst parameter is small enough.

Another crucial objective of our article is the study of the regularity of stochastic flows of the SDE (1.1), that is the regularity of

\[
(x \mapsto -\rightarrow X^x_t)
\]

in the initial condition \( x \in \mathbb{R}^d \), when the vector field \( b \) is discontinuous.

The motivation for this study comes from the deterministic case:

\[
\frac{d}{dt} X^x_t = u(t, X^x_t), \quad t \geq 0, \quad X^x_0 = x,
\]

(1.3)

where \( u : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R}^d \) is a vector field. Here, the solution \( X : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R}^d \) to (1.3) may e.g. stand for the flow of fluid particles with respect to the velocity field of an incompressible inviscid fluid whose dynamics is described by an incompressible Euler equation

\[
u_t + (Du)u + \nabla P = 0, \quad \nabla \cdot u = 0,
\]

(1.4)

where \( P : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R} \) is the pressure field.

Solutions of (1.4) may be singular. Therefore a better understanding of the regularity of solutions of equation (1.4) requires the study of flows of ODE’s (1.3) driven by irregular vector fields.

If \( u \) is Lipschitz continuous it is well-known that the unique flow \( X : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R}^d \) in (1.3) is Lipschitzian. The latter classical result was generalized by Di Perna and Lions in their celebrated paper [19] to the case \( u \in L^1([0, T]; W^{1,p}_{loc}) \) and \( \nabla \cdot u \in L^1([0, T]; L^\infty) \), for which the authors construct a unique generalized flow \( X \) to (1.3). Later on the latter result was extended by Ambrosio [2] to the case of vector fields of bounded variation.

However, it turns out that the superposition of the ODE (1.3) by a Brownian noise \( B \), that is

\[
\frac{d}{dt} X_t = u(t, X_t) dt + dB_t, \quad s, t \geq 0, \quad X_s = x \in \mathbb{R}^d
\]

(1.5)

has a strong regularising effect on its flow \( \mathbb{R}^d \ni x \mapsto \varphi_{s,t}(x) \in \mathbb{R}^d \).

Using techniques similar to those in this paper, but without arguments based on local time, it was shown in Mohammed et al. [38] for merely \( \text{bounded measurable} \) drift coefficients \( u \) that \( \varphi_{s,t} \) is a stochastic flow of Sobolev diffeomorphisms with

\[
\varphi_{s,t}(\cdot), \varphi^{-1}_{s,t}(\cdot) \in L^2(\Omega, W^{1,p}(\mathbb{R}^d; w))
\]

for all \( s, t \) and \( p \in (1, \infty) \), where \( W^{1,p}(\mathbb{R}^d; w) \) is a weighted Sobolev space with weight function \( w : \mathbb{R}^d \rightarrow [0, \infty) \).

As an application of this result the authors constructed Sobolev differentiable unique (weak) solutions of the (Stratonovich) stochastic transport equation with multiplicative noise of the form

\[
\Box \text{ Springer}
\]
\[
\begin{aligned}
d_t v(t, x) + (u(t, x) \cdot Dv(t, x))dt + \sum_{i=1}^d e_i \cdot Dv(t, x) \circ dB^i_t &= 0 \\
u(0, x) &= u_0(x),
\end{aligned}
\]

where \(u\) is bounded and measurable, \(u_0 \in C^1_b\) and where \(\{e_i\}_{i=1}^d\) is a basis of \(\mathbb{R}^d\).

By adopting ideas in Mohammed et al. \[38\], we mention that the latter result on the existence of stochastic flows of Sobolev diffeomorphisms was extended in \[46\] to the case of globally integrable \(u \in L^{r,q}\) for \(r/d + 2/q < 1\) (\(r\) for the spatial variable and \(q\) for the temporal variable) and applied to the study of the regularity of solutions to Navier–Stokes-equations. Compare also to \[20\], where the authors employ techniques based on solutions of backward Kolmogorov equations.

If the Brownian motion in (1.5) is replaced by a rougher noise given by \(B^H\) for \(H < \frac{1}{2}\), we find in this paper for \(u \in L^1(\mathbb{R}^d; L^\infty([0, T], \mathbb{R}^d)) \cap L^\infty(\mathbb{R}^d; L^\infty([0, T], \mathbb{R}^d))\) the rather surprising result which generalises the classical result of Kunita \[30\] for smooth coefficients, that the stochastic flow \(X : [0, \infty) \times \mathbb{R}^d \rightarrow \mathbb{R}^d\) is higher order Fréchet differentiable in the spatial variable, that is

\[
(x \mapsto X^k_t(\omega)) \in C^k(\mathbb{R}^d)
\]
a.s. for all \(t\) and for \(k \geq 1\), provided \(H = H(k)\) is small enough.

In view of the above discussion in the case of Brownian noise driven stochastic flows, the latter result raises the fundamental question whether rough noise in the sense of \(B^H\) or a related noise with very irregular path behaviour may considerably regularise solutions of PDE’s as e.g. transport equations, conservation laws or even Navier–Stokes equations by perturbation. We are confident that there is an affirmative answer for a class of interesting PDE’s.

Finally, we comment on that the method for the construction of higher order Fréchet differentiable stochastic flows of (1.1), which is—as mentioned above—different from common techniques based on Markov processes and semimartingales, is inspired by the works \[25,36–38\] in the case of (1.1) with initial Lévy noise and \[21,39\] in the case of stochastic partial differential equations.

More precisely, in order to construct strong solutions to (1.1) we apply a compactness criterion for square integrable Brownian functionals from \[15\] to solutions \(X^\mu_t\) of

\[
dX^\mu_t = b_n(t, X^\mu_t)dt + dB^H_t,
\]

where \(b_n, n \geq 0\) are smooth coefficients converging to \(b\) in \(L^1(\mathbb{R}^d; L^\infty([0, T], \mathbb{R}^d)) \cap L^\infty(\mathbb{R}^d; L^\infty([0, T], \mathbb{R}^d))\) and show that \(X^\mu_t\) converges to a solution \(X_t\) of (1.1) in \(L^2(\Omega)\) for all \(t\).

If, for a moment, we assume that \(b\) is time-homogeneous, then in proving the existence and the higher order Fréchet differentiability of the corresponding stochastic flow we make use of a “local time variational calculus” argument of the form

\[
\int_{\Delta_{s,t}^{m}} \varepsilon(s) D^{\alpha} f(B^H_s) ds = \int_{(\mathbb{R}^d)^m} D^{\alpha} f(z) L (t, z) dz = (-1)^{|\alpha|} \int_{(\mathbb{R}^d)^m} f(z) D^{\alpha} L (t, z) dz,
\]

for \(B^H = (B^H_{s_1}, \ldots, B^H_{s_m})\) and smooth functions \(f : (\mathbb{R}^d)^m \rightarrow \mathbb{R}\), where \(L (t, z)\) is a spatially differentiable local time on the simplex \(\Delta_{s,t}^{m} = \{(s_1, \ldots, s_m) \in [0, T]^m : \theta < s_1 < \cdots < s_m < t\}\), weighted by a function \(\varepsilon(s_1, \ldots, s_m)\) (\(D^\alpha\) is the partial derivative of order \(|\alpha|\) for a multi-index \(\alpha\) of natural numbers, see Sect. 3). Actually, we generalise the above argument to time dependent smooth functions \(f : [0, T]^m \times (\mathbb{R}^d)^m \rightarrow \mathbb{R}\) and hence the intuition of the above “local time” argument is somehow not tangible any longer. In other
words, we show that there exists a well-defined object \( \Lambda_{\alpha}(\theta, t, z) \) in \( L^2(\Omega) \) the size of which can be estimated by means of a norm of \( f \) and not by its derivative such that the following integration by parts formula holds true

\[
\int_{\Delta_{\alpha, t}} D^\alpha f(s, B^H_s) ds = \int_{(\mathbb{R}^d)^m} \Lambda_{\alpha}(\theta, t, z) dz, \quad P - a.s. \tag{1.7}
\]

where the above formula coincides with (1.6) for time-homogeneous functions.

We expect that our approach can be also applied to the study of solutions of the following stochastic equations:

\[
dX_t = (AX_t + b(X_t))dt + QdW_t,
\]

for (mild) solutions \( X_t \), where \( A \) is a densely defined linear operator (of parabolic type) on a separable Hilbert space \( H \), \( b : H \rightarrow H \) is an irregular function, \( Q \) a Hilbert–Schmidt operator and \( W \) a (non-Hölder continuous) “cylindrical” Gaussian noise.

On the other hand, using our method we may also examine equations of the type

\[
dX_t = dA_t + dB^H_t,
\]

where \( A_t \) is a process of bounded variation which arises from limits of the form

\[
\lim_{n \to \infty} \int_0^t b_n(X_s) ds
\]

for coefficients \( b_n, n \geq 0 \). See [7] in the Brownian case and the works [3,6], where the authors study fractional Brownian motion driven SDE’s in \( \mathbb{R}^d \) with a distributional vector field \( b \) given by the Dirac delta function in zero, \( \delta_0 \in B^\infty_{\infty, \infty} \). As for applications of our results to the analysis of rough singular PDE’s, we also refer to [40].

Our paper is organised as follows: In Sect. 2 we introduce the mathematical framework of the article and define in Sect. 3 the random field \( \Lambda_{\alpha} \) of (1.7), which we show to be high-order differentiable in the spatial variable for small Hurst parameters. In Sect. 4 we establish the existence of a unique strong solution to the SDE (1.1) under integrability conditions on the drift coefficient \( b \). Section 5 is devoted to the study of the regularity properties of stochastic flows of (1.1).

2 Framework

In this section we recollect some specifics on fractional calculus, fractional Brownian noise and occupation measures which will be extensively used throughout the article. The reader might consult [34,35] or [18] for a general theory on Malliavin calculus for Brownian motion and [43, Chapter 5] for fractional Brownian motion. Whereas for occupation measures one may review [22] or [27]. We present the results in one dimension for simplicity inasmuch as we will treat the multidimensional case componentwise.

2.1 Fractional Calculus

We establish here some basic definitions and properties on fractional calculus. A general theory on this subject may be found in [32,47].
Let \( a, b \in \mathbb{R} \) with \( a < b \). Let \( f \in L^p([a, b]) \) with \( p \geq 1 \) and \( \alpha > 0 \). Define the left- and right-sided Riemann–Liouville fractional integrals by

\[
I^\alpha_{a^+} f(x) = \frac{1}{\Gamma(\alpha)} \int_a^x (x - y)^{\alpha-1} f(y) dy
\]

and

\[
I^\alpha_{b^-} f(x) = \frac{1}{\Gamma(\alpha)} \int_x^b (y - x)^{\alpha-1} f(y) dy
\]

for almost all \( x \in [a, b] \) where \( \Gamma \) is the Gamma function.

Moreover, for a given integer \( p \geq 1 \), let \( I^\alpha_{a^+}(L^p) \) (resp. \( I^\alpha_{b^-}(L^p) \)) denote the image of \( L^p([a, b]) \) by the operator \( I^\alpha_{a^+} \) (resp. \( I^\alpha_{b^-} \)). If \( f \in I^\alpha_{a^+}(L^p) \) (resp. \( f \in I^\alpha_{b^-}(L^p) \)) and \( 0 < \alpha < 1 \) then define the left- and right-sided Riemann–Liouville fractional derivatives by

\[
D^\alpha_{a^+} f(x) = \frac{1}{\Gamma(1-\alpha)} \frac{d}{dx} \int_a^x \frac{f(y)}{(x-y)^{\alpha}} dy
\]

and

\[
D^\alpha_{b^-} f(x) = \frac{1}{\Gamma(1-\alpha)} \frac{d}{dx} \int_x^b \frac{f(y)}{(y-x)^{\alpha}} dy.
\]

The left- and right-sided derivatives of \( f \) defined above have the following representations

\[
D^\alpha_{a^+} f(x) = \frac{1}{\Gamma(1-\alpha)} \left( \frac{f(x)}{(x-a)^\alpha} + \alpha \int_a^x \frac{f(y) - f(x)}{(x-y)^{\alpha+1}} dy \right)
\]

and

\[
D^\alpha_{b^-} f(x) = \frac{1}{\Gamma(1-\alpha)} \left( \frac{f(x)}{(b-x)^\alpha} + \alpha \int_x^b \frac{f(y) - f(x)}{(y-x)^{\alpha+1}} dy \right).
\]

Finally, observe that by construction, the following formulas hold

\[
I^\alpha_{a^+}(D^\alpha_{a^+} f) = f
\]

for all \( f \in I^\alpha_{a^+}(L^p) \) and

\[
D^\alpha_{a^+}(I^\alpha_{a^+} f) = f
\]

for all \( f \in L^p([a, b]) \) and similarly for \( I^\alpha_{b^-} \) and \( D^\alpha_{b^-} \).

### 2.2 Shuffles

Let \( m \) and \( n \) be integers. We define \( S(m, n) \) as the set of shuffle permutations, i.e. the set of permutations \( \sigma : \{1, \ldots, m+n\} \to \{1, \ldots, m+n\} \) such that \( \sigma(1) < \cdots < \sigma(m) \) and \( \sigma(m+1) < \cdots < \sigma(m+n) \).

We define the \( m \)-dimensional simplex for \( 0 \leq \theta < t \leq T \),

\[
\Delta^m_{\theta,t} := \{(s_m, \ldots, s_1) \in [0, T]^m : \theta < s_m < \cdots < s_1 < t \}.
\]

The product of two simplices can be written as the following union

\[
\Delta^m_{\theta,t} \times \Delta^n_{\theta,t} = \bigcup_{\sigma \in S(m,n)} \{(w_{m+n}, \ldots, w_1) \in [0, T]^{m+n} : \theta < w_{\sigma(m+n)} < \cdots < w_{\sigma(1)} < t \} \cup \mathcal{N},
\]
where the set $\mathcal{N}$ has null Lebesgue measure. In this way, if $f_i : [0, T] \to \mathbb{R}, i = 1, \ldots, m+n$ are integrable functions we have

$$\int_{\Delta_{\theta, t}^m} \prod_{j=1}^{m} f_j(s_j) ds_m \ldots ds_1 \int_{\Delta_{\theta, t}^n} \prod_{j=m+1}^{m+n} f_j(s_j) ds_{m+n} \ldots ds_{m+1}$$

$$= \sum_{\sigma \in S(m,n)} \int_{\Delta_{\theta, t}^{m+n}} \prod_{j=1}^{m+n} f_{\sigma}(s_j) ds_{m+n} \ldots d w_1.$$

(2.1)

We can generalize the above technical lemma, the use of which shall be clear in Sect. 5. The reader may skip this lemma and proof until Sect. 5.

**Lemma 2.1** Let $n, p$ and $k$ be non-negative integers, $k \leq n$. Assume we have integrable functions $f_j : [0, T] \to \mathbb{R}, j = 1, \ldots, n$ and $g_i : [0, T] \to \mathbb{R}, i = 1, \ldots, p$. We may then write

$$\int_{\Delta_{\theta, t}^n} f_1(s_1) \ldots f_k(s_k) \int_{\Delta_{\theta, t}^p} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 f_{k+1}(s_{k+1}) \ldots f_n(s_n) ds_n \ldots ds_1$$

$$= \sum_{\sigma \in A_{n,p}} \int_{\Delta_{\theta, t}^{n+p}} h_{\sigma}^1(w_1) \ldots h_{n+p}^\sigma(w_{n+p}) d w_{n+p} \ldots d w_1,$$

where $h_{\sigma}^1 \in \{f_j, g_i : 1 \leq j \leq n, 1 \leq i \leq p\}. Above A_{n,p} denotes a subset of permutations of \{1, \ldots, n+p\} such that \#A_{n,p} \leq C^{n+p}$ for an appropriate constant $C \geq 1$, and we have defined $s_0 = \theta$.

**Proof** The result is proved by induction on $n$. For $n = 1$ and $k = 0$ the result is trivial. For $k = 1$ we have

$$\int_{\Delta_{\theta, t}^n} f_1(s_1) \int_{\Delta_{\theta, s_1}^p} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 ds_1$$

$$= \int_{\Delta_{\theta, t}^{n+1}} f_1(w_1) g_1(w_2) \ldots g_p(w_{p+1}) d w_{p+1} \ldots d w_1,$$

where we have put $w_1 = s_1, w_2 = r_1, \ldots, w_{p+1} = r_p$.

Assume the result holds for $n$ and let us show that this implies that the result is true for $n + 1$. Either $k = 0, 1$ or $2 \leq k \leq n + 1$. For $k = 0$ the result is trivial. For $k = 1$ we have

$$\int_{\Delta_{\theta, t}^{n+1}} f_1(s_1) \int_{\Delta_{\theta, s_1}^p} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 f_2(s_2) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_1$$

$$= \int_{\Delta_{\theta, t}^n} f_1(s_1) \left( \int_{\Delta_{\theta, s_1}^p} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 f_2(s_2) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_2 \right) ds_1.$$

The result follows from (2.1) coupled with $\#S(n, p) = \frac{(n+p)!}{n!p!} \leq C^{n+p} \leq C^{(n+1)+p}$. For $k \geq 2$ we have from the induction hypothesis.
\begin{align*}
&\int_{\Delta_{b,t}^{n+1}} f_1(s_1) \ldots f_k(s_k) \int_{\Delta_{b,t}^{p}} g_1(r_1) \ldots g_p(r_p) dr_p \\
&\quad \ldots dr_1 f_{k+1}(s_{k+1}) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_1 \\
&\quad = \int_{\theta} f_1(s_1) \int_{\Delta_{b,t}^{n+1}} f_2(s_2) \ldots f_k(s_k) \int_{\Delta_{b,t}^{p}} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 \\
&\quad \times f_{k+1}(s_{k+1}) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_2 ds_1 \\
&\quad = \sum_{\sigma \in A_{n,p}} \int_{\theta} f_1(s_1) \int_{\Delta_{b,t}^{n+1}} h_1^a(w_1) \ldots h_{n+p}^\sigma(w_{n+p}) dw_{n+p} \ldots dw_1 ds_1 \\
&\quad = \sum_{\bar{\sigma} \in A_{n+1,p}} \int_{\Delta_{b,t}} h_{1+1}^\bar{\sigma}(w_1) \ldots \tilde{h}_{un+1+p}^\bar{\sigma} dw_1 \ldots dw_{n+1+p},
\end{align*}

where $A_{n+1,p}$ is the set of permutations $\bar{\sigma}$ of $\{1, \ldots, n+1+p\}$ such that $\bar{\sigma}(1) = 1$ and $\bar{\sigma}(j+1) = \sigma(j)$, $j = 1, \ldots, n+p$ for some $\sigma \in A_{n,p}$.

**Remark 2.2** Notice that the set $A_{n,p}$ in the above lemma also depends on $k$ but we shall not need this fact.

### 2.3 Fractional Brownian Motion

Let $B^H = \{B_t^H, t \in [0, T]\}$ be a $d$-dimensional *fractional Brownian motion* with Hurst parameter $H \in (0, 1/2)$ defined on a probability space $(\Omega, \mathcal{A}, \mathbb{P})$. In other words, $B^H$ is a centered Gaussian process with covariance structure

\[
(R_H(t, s))_{i,j} := \mathbb{E}[B_t^{H,(i)} B_s^{H,(j)}] = \frac{1}{2} \left(t^{2H} + s^{2H} - |t-s|^{2H}\right), \quad i, j = 1, \ldots, d.
\]

Observe that $\mathbb{E}[|B_t^H - B_s^H|^2] = d|t-s|^{2H}$ and hence $B^H$ has stationary increments and Hölder continuous trajectories of index $H - \varepsilon$ for all $\varepsilon \in (0, H)$. Observe moreover that the increments of $B^H$, $H \in (0, 1/2)$ are not independent. This fact makes computations more difficult. Another difficulty one encounters is that $B^H$ is not a semimartingale, see e.g. [43, Proposition 5.1.1).

Now we give a brief survey on how to construct fractional Brownian motion via an isometry. Since the construction can be done componentwise we present here for simplicity the one-dimensional case. Further details can be found in [43].

Denote by $\mathcal{E}$ the set of step functions on $[0, T]$ and denote by $\mathcal{H}$ the Hilbert space defined as the closure of $\mathcal{E}$ with respect to the inner product

\[
\langle 1_{[0,t]}, 1_{[0,s]} \rangle_{\mathcal{H}} = R_H(t, s).
\]

The mapping $1_{[0,t]} \mapsto B_t$ can be extended to an isometry between $\mathcal{H}$ and the Gaussian subspace of $L^2(\Omega)$ associated with $B^H$. Denote such isometry by $\varphi \mapsto B^H(\varphi)$. We recall the following result (see [43, Proposition 5.1.3]) which gives an integral representation of $R_H(t, s)$ when $H < 1/2$:

**Proposition 2.3** Let $H < 1/2$. The kernel

\[
K_H(t, s) = c_H \left( \left( \frac{t}{s} \right)^{H-\frac{1}{2}} (t-s)^{-\frac{1}{2}} + \left( \frac{1}{2} - H \right) s^{\frac{1}{2} - H} \int_s^t u^{H-\frac{1}{2}} (u-s)^{H-\frac{1}{2}} du \right),
\]

\(\square\) Springer
where \( c_H = \sqrt{\frac{2H}{(1-2H)\beta(1-2H,H+1/2)}} \) being \( \beta \) the Beta function, satisfies
\[
R_H(t,s) = \int_0^{1/s} K_H(t,u)K_H(s,u)du. \tag{2.2}
\]

The kernel \( K_H \) can also be represented by means of fractional derivatives as follows
\[
K_H(t,s) = c_H \Gamma\left(H + \frac{1}{2}\right) s^{\frac{1}{2}-H} \left( D_{T-}^{\frac{1}{2}-H} u^{H-\frac{1}{2}} \right)(s).
\]

Consider the linear operator \( K_H^*: \mathcal{E} \to L^2([0,T]) \) defined by
\[
(K_H^*(\varphi))(s) = K_H(T,s)\varphi(s) + \int_s^T (\varphi(t) - \varphi(s)) \frac{\partial K_H}{\partial t}(t,s)dt
\]
for every \( \varphi \in \mathcal{E} \). Observe that \((K_H^* 1_{[0,t]})(s) = K_H(t,s)1_{[0,t]}(s)\), then from this fact and (2.2) we see that \( K_H^* \) is an isometry between \( \mathcal{E} \) and \( L^2([0,T]) \) which can be extended to the Hilbert space \( \mathcal{H} \).

For a given \( \varphi \in \mathcal{H} \) one can show the following two representations for \( K_H^* \) in terms of fractional derivatives
\[
(K_H^* \varphi)(s) = c_H \Gamma\left(H + \frac{1}{2}\right) s^{\frac{1}{2}-H} \left( D_{T-}^{\frac{1}{2}-H} u^{H-\frac{1}{2}} \varphi(u) \right)(s)
\]
and
\[
(K_H^* \varphi)(s) = c_H \Gamma\left(H + \frac{1}{2}\right) \left( D_{T-}^{\frac{1}{2}-H} \varphi(s) \right) + c_H \left( \frac{1}{2} - H \right) \int_s^T \varphi(t)(t-s)^{-\frac{3}{2}} \left( 1 - \left( \frac{t}{s} \right)^{H-\frac{1}{2}} \right) dt.
\]

One can show that \( \mathcal{H} = I_{T-}^{\frac{1}{2}-H} (L^2) \) (see [17] and [1, Proposition 6]).

Given the fact that \( K_H^* \) is an isometry from \( \mathcal{H} \) into \( L^2([0,T]) \) the \( d \)-dimensional process \( W = \{W_t, t \in [0,T]\} \) defined by
\[
W_t := B^H((K_H^*)^{-1}(1_{[0,t]})) \tag{2.3}
\]
is a Wiener process and the process \( B^H \) has the following representation
\[
B^H_t = \int_0^t K_H(t,s) dW_s, \tag{2.4}
\]
see [1].

Henceforward, we will denote by \( W \) a standard Wiener process on a given probability space \( (\Omega, \mathcal{F}, P) \) equipped with the natural filtration \( \mathcal{F} = \{\mathcal{F}_t\}_{t \in [0,T]} \) generated by \( W \) augmented by all \( \mathcal{P} \)-null sets and \( B := B^H \) the fractional Brownian motion with Hurst parameter \( H \in (0, 1/2) \) given by the representation (2.4).

Next, we give a version of Girsanov’s theorem for fractional Brownian motion which is due to [17, Theorem 4.9]. Here we present the version given in [41, Theorem 3.1] but first we need to define an isomorphism \( K_H \) from \( L^2([0,T]) \) onto \( I_{0+}^{H+\frac{1}{2}} (L^2) \) associated with the kernel \( K_H(t,s) \) in terms of the fractional integrals as follows, see [17, Theorem 2.1]
\[
(K_H \varphi)(s) = I_{0+}^{2H} s^{\frac{1}{2}-H} I_{0+}^{\frac{1}{2}-H} s^{H-\frac{1}{2}} \varphi, \quad \varphi \in L^2([0,T]).
\]
From this and the properties of the Riemann–Liouville fractional integrals and derivatives the inverse of $K_H$ is given by

$$(K_H^{-1} \varphi)(s) = s^{\frac{1}{2} - H} D_{0+}^{\frac{1}{2} - H} s^{H - \frac{1}{2}} D_{0+}^2 \varphi(s), \quad \varphi \in L_{0+}^{H + \frac{1}{2}} (L^2).$$

It follows that if $\varphi$ is absolutely continuous, see [41], one can show that

$$(K_H^{-1} \varphi)(s) = s^{H - \frac{1}{2}} I_{0+}^{\frac{1}{2} - H} s^{\frac{1}{2} - H} \varphi'(s). \quad (2.5)$$

**Theorem 2.4** (Girsanov’s theorem for fBm) Let $u = \{u_t, t \in [0, T]\}$ be an $\mathcal{F}$-adapted process with integrable trajectories and set $\tilde{B}_t^H = B_t^H + \int_0^t u_s ds, \quad t \in [0, T]$. Assume that

(i) $\int_0^T u_s ds \in L^{H+\frac{1}{2}}_0 ([0, T]), \quad P$-a.s.

(ii) $E[\xi_T] = 1$ where

$$\xi_T := \exp \left\{- \int_0^T K_H^{-1} \left( \int_0^s u_r dr \right) (s) dW_s - \frac{1}{2} \int_0^T K_H^{-1} \left( \int_0^s u_r dr \right)^2 (s) ds \right\}.$$

Then the shifted process $\tilde{B}_t^H$ is an $\mathcal{F}$-fractional Brownian motion with Hurst parameter $H$ under the new probability $\tilde{P}$ defined by $d\tilde{P} = \xi_T \frac{dP}{\xi_T}$.

**Remark 2.5** For the multidimensional case, define

$$(K_H \varphi)(s) := ((K_H \varphi)^{(1)}(s), \ldots, (K_H \varphi)^{(d)}(s))^*, \quad \varphi \in L^2([0, T]; \mathbb{R}^d),$$

where $*$ denotes transposition. Similarly for $K_H^{-1}$ and $K_H^*$. 

Finally, we want to use a crucial property of the fractional Brownian in this paper, which is referred to in the literature as strong (two-sided) local non-determinism (see e.g. [44] or [49]). This property will essentially help us to overcome the limitations of not having independent increments of the underlying noise: There exists a constant $K > 0$, depending only on $H$ and $T$, such that for any $t \in [0, T], 0 < r < t$ and for $i = 1, \ldots, d$,

$$\text{Var} \left[ B_{s}^{H,i} \mid B_{s}^{H,i} : |t - s| \geq r \right] \geq K r^{2H}. \quad (2.6)$$

### 3 An Integration by Parts Formula

Let $m$ be an integer and consider a $f : [0, T]^m \times (\mathbb{R}^d)^m \to \mathbb{R}$ of the form

$$f(s, z) = \prod_{j=1}^m f_j(s_j, z_j), \quad s = (s_1, \ldots, s_m) \in [0, T]^m, \quad z = (z_1, \ldots, z_m) \in (\mathbb{R}^d)^m,$$

where $f_j : [0, T] \times \mathbb{R}^d \to \mathbb{R}, \; j = 1, \ldots, m$ are smooth functions with compact support. Moreover, consider an integrable $\alpha : [0, T]^m \to \mathbb{R}$ of the form

$$\alpha(s) = \prod_{j=1}^m \alpha_j(s_j), \quad s \in [0, T]^m, \quad (3.2)$$

where $\alpha_j : [0, T] \to \mathbb{R}, \; j = 1, \ldots, m$ are integrable functions.
Denote by $\alpha_j$ a multi-index and $D^{\alpha_j}$ its corresponding differential operator. For $\alpha = (\alpha_1, \ldots, \alpha_m)$ considered as an element of $\mathbb{N}_0^d \times m$ so that $|\alpha| := \sum_{j=1}^m \sum_{l=1}^d \alpha_j^{(l)}$, we write

$$D^{\alpha} f(s, z) = \prod_{j=1}^m D^{\alpha_j} f_j(s_j, z_j).$$

The aim of this section is to derive an integration by parts formula of the form

$$\int_{\Delta^m_{\Theta, t}} D^{\alpha} f(s, B_s) ds = \int_{(\mathbb{R}^d)^m} \Lambda^{f}_{\alpha}(r, t, z) dz,$$

(3.3)

where $B := B^H$, for a suitable random field $\Lambda^{f}_{\alpha}$. In fact, we have

$$\Lambda^{f}_{\alpha}(\theta, t, z) = (2\pi)^{-dm} \int_{(\mathbb{R}^d)^m} \int_{\Delta^m_{\Theta, t}} \prod_{j=1}^m f_j(s_j, z_j)(-iu_j)^{\alpha_j} \exp\{-iu_j(B_{s_j} - z_j)\} ds_j du_j.$$

(3.4)

We start by defining $\Lambda^{f}_{\alpha}(\theta, t, z)$ as above and show that it is a well-defined element of $L^2(\Omega)$.

Introduce the following notation: given $(s, z) = (s_1, \ldots, s_m, z_1, \ldots, z_m) \in [0, T]^m \times (\mathbb{R}^d)^m$ and a shuffle $\sigma \in S(m, m)$ we write

$$f_\sigma(s, z) := \prod_{j=1}^{2m} f_{\sigma(j)}(s_j, z_{\sigma(j)}),$$

and

$$x_\sigma(s) := \prod_{j=1}^{2m} x_{\sigma(j)}(s_j),$$

where $[j]$ is equal to $j$ if $1 \leq j \leq m$ and $j - m$ if $m + 1 \leq j \leq 2m$.

For a multiindex $\alpha$ we define

$$\Psi^{f}_{\alpha}(\theta, t, z) := \prod_{l=1}^d \sqrt{(2|\alpha^{(l)}|)!} \sum_{\sigma \in S(m, m)} \int_{\Delta^m_{\Theta, t}} f_\sigma(s, z) \prod_{j=1}^{2m} \frac{1}{|s_j - s_{j-1}|^{|H(d+2\sum_{l=1}^d \alpha_j^{(l)}|)}} ds_1 \ldots ds_{2m},$$

respectively,

$$\Psi^{x}_{\alpha}(\theta, t) := \prod_{l=1}^d \sqrt{(2|\alpha^{(l)}|)!} \sum_{\sigma \in S(m, m)} \int_{\Delta^m_{\Theta, t}} x_\sigma(s) \prod_{j=1}^{2m} \frac{1}{|s_j - s_{j-1}|^{|H(d+2\sum_{l=1}^d \alpha_j^{(l)}|)}} ds_1 \ldots ds_{2m}. $$

**Theorem 3.1** Suppose that $\Psi^{f}_{\alpha}(\theta, t, z)$, $\Psi^{x}_{\alpha}(\theta, t) < \infty$. Then, defining $\Lambda^{f}_{\alpha}(\theta, t, z)$ as in (3.4) gives a random variable in $L^2(\Omega)$ and there exists a universal constant $C = C(T, H, d) > 0$ such that

\[ \square \] Springer
\[ E \left[ \left| \Lambda^f_{a}(\theta, t, z) \right|^2 \right] \leq C^{m+|\alpha|} \Psi_\alpha^f(\theta, t, z). \quad (3.5) \]

Moreover, we have
\[ \left| E \left[ \int \int f^f_{a}(\theta, t, z)dz \right] \right| \leq C^{m/2+|\alpha|/2} \prod_{j=1}^{m} \left\| f_j \right\|_{L^1(\mathbb{R}^d; L^\infty([0, T]))} (\Psi_\alpha^\infty(\theta, t))^{1/2}. \quad (3.6) \]

**Proof** For notational convenience we consider \( \theta = 0 \) and set \( \Lambda^f_{a}(t, z) = \Lambda^f_{a}(0, t, z) \).

For an integrable function \( g : (\mathbb{R}^d)^m \rightarrow \mathbb{C} \) we can write
\[
\left| \int (\mathbb{R}^d)^m g(u_1, \ldots, u_m)du_1 \ldots du_m \right|^2 \\
= \int (\mathbb{R}^d)^m g(u_1, \ldots, u_m)du_1 \ldots du_m \int (\mathbb{R}^d)^m \overline{g(u_{m+1}, \ldots, u_{2m})} du_{m+1} \ldots du_{2m} \\
= \int (\mathbb{R}^d)^m g(u_1, \ldots, u_m)du_1 \ldots du_m (-1)^{dm} \\
\int (\mathbb{R}^d)^m \overline{g(-u_{m+1}, \ldots, -u_{2m})} du_{m+1} \ldots du_{2m},
\]

where we used the change of variables \( (u_{m+1}, \ldots, u_{2m}) \mapsto (-u_{m+1}, \ldots, -u_{2m}) \) in the third equality.

This gives
\[
\left| \Lambda^f_{a}(t, z) \right|^2 \\
= (2\pi)^{-2dm}(-1)^{dm} \int (\mathbb{R}^d)^{2m} \int_{\Lambda^m_{0,t}} \prod_{j=1}^{m} f_j(s_j, z_j)(-iu_j)^{\alpha_j} e^{-i(u_j, B_{s_j} - z_j)} ds_1 \ldots ds_m \\
\times \int \int_{\Lambda^m_{0,t}} \prod_{j=m+1}^{2m} f_j(s_j, z_j)(-iu_j)^{\alpha_j} e^{-i(u_j, B_{s_j} - z_j)} ds_{m+1} \ldots ds_{2m} du_1 \ldots du_{2m} \\
= (2\pi)^{-2dm}(-1)^{dm} \sum_{\sigma \in S(m, m)} \int (\mathbb{R}^d)^{2m} \left( \prod_{j=1}^{m} e^{-i(z_j, u_j + u_{j+m})} \right) \\
\times \int \int_{\Lambda^m_{0,t}} f_\sigma(s, z) \prod_{j=1}^{2m} u_{\alpha^{(j)}}^{\sigma^{(j)}} \exp \left\{ -\sum_{j=1}^{2m} (u_{\sigma(j)}, B_{s_j}) \right\} ds_1 \ldots ds_{2m} du_1 \ldots du_{2m},
\]

where we used (2.1) in the last step.

Taking the expectation on both sides yields
\[
E \left[ \left| \Lambda^f_{a}(t, z) \right|^2 \right] = (2\pi)^{-2dm}(-1)^{dm} \sum_{\sigma \in S(m, m)} \int (\mathbb{R}^d)^{2m} \left( \prod_{j=1}^{m} e^{-i(z_j, u_j + u_{j+m})} \right) \\
\times \int \int_{\Lambda^m_{0,t}} f_\sigma(s, z) \prod_{j=1}^{2m} u_{\alpha^{(j)}}^{\sigma^{(j)}} \exp \left\{ -\frac{1}{2} \text{Var} \left[ \sum_{j=1}^{2m} (u_{\sigma(j)}, B_{s_j}) \right] \right\} \\
\times ds_1 \ldots ds_{2m} du_1 \ldots du_{2m}.
\]
\[ \begin{align*}
&= (2\pi)^{-2dm} \left(-1\right)^{dm} \sum_{\sigma \in S(m,m)} \int_{(\mathbb{R}^d)^{2m}} \left( \prod_{j=1}^{m} e^{-i\langle z_j, u_j + u_{j+m} \rangle} \right) \\
&\times \int_{\Delta_{0,t}^{2m}} f_\sigma(s, z) \prod_{j=1}^{2m} \prod_{l=1}^{d} u_{\sigma(j)}^{a_{\sigma(j)}} \exp \left\{ -\frac{1}{2} \sum_{l=1}^{d} \operatorname{Var} \left[ \sum_{j=1}^{2m} u_{\sigma(j)}^{(l)} B_{s_l}^{(l)} \right] \right\} \\
&\times ds_1 \ldots ds_{2m} du_1^{(1)} \ldots du_{2m}^{(1)} du_1^{(d)} \ldots du_{2m}^{(d)} \\
&= (2\pi)^{-2dm} \left(-1\right)^{dm} \sum_{\sigma \in S(m,m)} \int_{(\mathbb{R}^d)^{2m}} \left( \prod_{j=1}^{m} e^{-i\langle z_j, u_j + u_{j+m} \rangle} \right) \\
&\times \int_{\Delta_{0,t}^{2m}} f_\sigma(s, z) \prod_{j=1}^{2m} \prod_{l=1}^{d} u_{\sigma(j)}^{a_{\sigma(j)}} \prod_{l=1}^{d} \exp \left\{ -\frac{1}{2} \left( u_{\sigma(j)}^{(l)} \right)^{1 \leq j \leq 2m} Q \left( u_{\sigma(j)}^{(l)} \right)^{1 \leq j \leq 2m} \right\} ds_1 \ldots ds_{2m} \\
&\times du_{\sigma(1)}^{(1)} \ldots du_{\sigma(2m)}^{(1)} \ldots du_{\sigma(1)}^{(d)} \ldots du_{\sigma(2m)}^{(d)}, \hspace{1cm} (3.7)
\end{align*} \]

where \(*\) denotes transposition and

\[ Q = Q(s) := (E[B_{s_i}^{(1)} B_{s_j}^{(1)}])_{1 \leq i, j \leq 2m}. \]

Further, we see that

\[ \begin{align*}
&\int_{\Delta_{0,t}^{2m}} f_\sigma(s, z) \int_{(\mathbb{R}^d)^{2m}} \prod_{j=1}^{2m} \prod_{l=1}^{d} u_{\sigma(j)}^{a_{\sigma(j)}} \prod_{l=1}^{d} \exp \left\{ -\frac{1}{2} \left( u_{\sigma(j)}^{(l)} \right)^{1 \leq j \leq 2m} Q \left( u_{\sigma(j)}^{(l)} \right)^{1 \leq j \leq 2m} \right\} \\
&\times du_{\sigma(1)}^{(1)} \ldots du_{\sigma(2m)}^{(1)} \ldots du_{\sigma(1)}^{(d)} \ldots du_{\sigma(2m)}^{(d)} ds_1 \ldots ds_{2m} \\
&= \int_{\Delta_{0,t}^{2m}} f_\sigma(s, z) \int_{(\mathbb{R}^d)^{2m}} \prod_{j=1}^{2m} \prod_{l=1}^{d} u_{\sigma(j)}^{a_{\sigma(j)}} \\
&\times \prod_{l=1}^{d} \exp \left\{ -\frac{1}{2} \langle Qu^{(l)}, u^{(l)} \rangle \right\} \\
&\times du_{1}^{(1)} \ldots du_{2m}^{(1)} \ldots du_{1}^{(d)} \ldots du_{2m}^{(d)} ds_1 \ldots ds_{2m} \\
&= \int_{\Delta_{0,t}^{2m}} f_\sigma(s, z) \prod_{l=1}^{d} \int_{\mathbb{R}^{2m}} \left( \prod_{j=1}^{2m} u_{\sigma(j)}^{a_{\sigma(j)}} \right) \exp \left\{ -\frac{1}{2} \langle Qu^{(l)}, u^{(l)} \rangle \right\} \\
&\times du_{1}^{(l)} \ldots du_{2m}^{(l)} ds_1 \ldots ds_{2m}, \hspace{1cm} (3.8)
\end{align*} \]

where

\[ u^{(l)} := (u_j^{(l)})_{1 \leq j \leq 2m}. \]
where $e_i, i = 1, \ldots, 2m$ is the standard ONB of $\mathbb{R}^{2m}$.

We also get that

$$
\int_{\mathbb{R}^{2m}} \left( 2^m \prod_{j=1}^{2m} \left| \mathcal{L}^{(j)} \right| \right) \exp \left\{ -\frac{1}{2} \left\langle Qu^{(l)}, u^{(l)} \right\rangle \right\} \, du_1^{(l)} \ldots du_2^{(l)} = (2\pi)^m E \left[ \prod_{j=1}^{2m} \left| \mathcal{L}^{(j)} \right| \right],
$$

where

$$
Z \sim \mathcal{N}(0, I_{2m \times 2m}).
$$

We know from Lemma A.9, which is a type of Brascamp–Lieb inequality that

$$
E \left[ \prod_{j=1}^{2m} \left| \mathcal{L}^{(j)} \right| \right] \leq \sqrt{\text{perm} \left( \sum \right)} = \sqrt{\sum_{\pi \in S_{2^m}} \prod_{i=1}^{2^m} a_i \pi(i)},
$$

where $\text{perm} \left( \sum \right)$ is the permanent of the covariance matrix $\sum = (a_{ij})$ of the Gaussian random vector

$$
\left( \left\langle \mathcal{L}^{(1)} \right\rangle, \ldots, \left\langle \mathcal{L}^{(1)} \right\rangle \right), \left\langle \mathcal{L}^{(2)} \right\rangle, \ldots, \left\langle \mathcal{L}^{(2)} \right\rangle,
$$

$a_{(1)}$ times

$$
\ldots, \left\langle \mathcal{L}^{(2m)} \right\rangle, \ldots, \left\langle \mathcal{L}^{(2m)} \right\rangle,
$$

$a_{(2m)}$ times

$$
|\alpha^{(l)}| := \sum_{j=1}^{m} a_j^{(l)} \text{ and where } S_n \text{ stands for the permutation group of size } n.
$$

In addition, using an upper bound for the permanent of positive semidefinite matrices (see [5]) or direct computations we get that

$$
\text{perm} \left( \sum \right) = \sum_{\pi \in S_{2^m}} \prod_{i=1}^{2^m} a_i \pi(i) \leq \left( 2 \left| \alpha^{(l)} \right| \right)^{2^m} \prod_{i=1}^{2^m} a_{ii}. \quad (3.9)
$$
Let now $i \in \{ \sum_{r=1}^{j-1} \alpha^{(l)}_{(r)} + 1, \sum_{r=1}^{j} \alpha^{(l)}_{(r)} \}$ for some arbitrary fixed $j \in \{1, \ldots, 2m\}$. Then

$$a_{ii} = E(\{Q^{-1/2}Z, e_j\} | Q^{-1/2}Z, e_j).$$

Further using substitution, we also have that

$$E(\{Q^{-1/2}Z, e_j\} | Q^{-1/2}Z, e_j)$$

$$= \left( \det Q \right)^{1/2} \frac{1}{(2\pi)^m} \int_{\mathbb{R}^{2m}} u_j^2 \exp \left( -\frac{1}{2} \langle Qu, u \rangle \right) du_1 \ldots du_{2m}$$

$$= \left( \det Q \right)^{1/2} \frac{1}{(2\pi)^m} \int_{\mathbb{R}} v^2 \exp \left( -\frac{1}{2} v^2 \right) dv \frac{1}{\sigma_j^2}$$

We now want to use Lemma A.10. Then we get that

$$\int_{\mathbb{R}^{2m}} u_j^2 \exp \left( -\frac{1}{2} \langle Qu, u \rangle \right) du_1 \ldots du_m$$

$$= \frac{(2\pi)^{2m-1/2}}{(2\pi)^{1/2} \left( \det Q \right)^{1/2}} \int_{\mathbb{R}} v^2 \exp \left( -\frac{1}{2} v^2 \right) dv \frac{1}{\sigma_j^2}$$

where $\sigma_j^2 := \text{Var}[B_{s_j}^H | B_{s_1}^H, \ldots, B_{s_{2m}}^H]$ without $B_{s_j}^H$.

We now want to use strong local non-determinism of the form [see (2.6)]: For all $t \in [0, T]$, $0 < r < t$: $\text{Var}[B_t^H | B_s^H, |t - s| \geq r] \geq K r^{2H}$.

The latter implies that

$$\left( \det Q(s) \right)^{1/2} \geq K^{(2m-1)/2} \frac{s_1^H s_2^H \ldots s_{2m}^H - s_{2m-1}^H}{s_2^H \ldots s_{2m}^H}$$

as well as

$$\sigma_j^2 \geq \min \{ s_j - s_{j-1}^H, s_{j+1}^H - s_j^H \}.$$  

Thus

$$\prod_{j=1}^{2m} \sigma_j^{-2\alpha^{(l)}_{(j)}} \leq K^{-2|\alpha^{(l)}|} \prod_{j=1}^{2m} \frac{1}{\min \{ s_j - s_{j-1}^H, s_{j+1}^H - s_j^H \}^{2H\alpha^{(l)}_{(j)}}}$$

$$\leq C |\alpha^{(l)}| \prod_{j=1}^{2m} \frac{1}{s_j - s_{j-1}^{4H\alpha^{(l)}_{(j)}}}$$

for a constant $C$ only depending on $H$ and $T$.

Hence, it follows from (3.9) that

$$\text{perm} \left( \sum_{i=1}^{2|\alpha^{(l)}|} a_{ii} \right) \leq \left( 2 |\alpha^{(l)}| \right)! \prod_{i=1}^{2|\alpha^{(l)}|} a_{ii}$$

$$\leq \left( 2 |\alpha^{(l)}| \right)! \prod_{j=1}^{2m} \left( \left( \det Q \right)^{1/2} \frac{1}{(2\pi)^m} \left( \frac{1}{\sigma_j^2} \right) \right)^{\alpha^{(l)}_{(j)}}$$
Taking the supremum over

Therefore we obtain from (3.7) and (3.8) that

So

Finally, we show estimate (3.6). Using the inequality (3.5), we find that

Therefore we obtain from (3.7) and (3.8) that

Finally, we show estimate (3.6). Using the inequality (3.5), we find that

for a constant $M$ depending on $d$.

Finally, we show estimate (3.6). Using the inequality (3.5), we find that

Taking the supremum over $[0, T]$ for each function $f_j$, i.e.

$$
\left| f_{\sigma(j)}(s_j, z_{\sigma(j)}) \right| \leq \sup_{s_j \in [0, T]} \left| f_{\sigma(j)}(s_j, z_{\sigma(j)}) \right|, \ j = 1, \ldots, 2m
$$
one obtains that
\[ \left| E \left[ \int_{(\mathbb{R}^d)^m} \Lambda_{\alpha}^{\infty} f(\theta, t, z) dz \right] \right| \leq C^{m+|\alpha|} \max_{\sigma \in S(m, m)} \int_{(\mathbb{R}^d)^m} \left( \prod_{j=1}^{2m} \left\| f_{\sigma(j)}(\cdot, z_{\sigma(j)}) \right\|_{L^\infty([0, T])} \right)^{1/2} \, dz \]
\times \left( \prod_{j=1}^{d} \sqrt{2(2^d)}! \sum_{\sigma \in S(m, m)} \int_{\Delta_{\alpha, t}} \left\| f_{\sigma(j)}(\cdot, z_{\sigma(j)}) \right\|_{L^\infty([0, T])} \, dz \right)^{1/2} \cdot (\Psi_\alpha^{\infty}(\theta, t))^{1/2} \]
\[ = C^{m+|\alpha|} \int_{(\mathbb{R}^d)^m} \prod_{j=1}^{m} \left\| f_j(\cdot, z_j) \right\|_{L^\infty([0, T])} \, dz \cdot (\Psi_\alpha^{\infty}(\theta, t))^{1/2} \]
\[ = C^{m+|\alpha|} \prod_{j=1}^{m} \left\| f_j(\cdot, z_j) \right\|_{L^1((\mathbb{R}^d, L^\infty([0, T])))} \cdot (\Psi_\alpha^{\infty}(\theta, t))^{1/2}. \]

\[ \square \]

We remark that \textit{a priori} one can not interchange the order of integration in (3.4). Indeed, for \( m = 1, f \equiv 1 \) one gets an integral of the Donsker–Delta function which is not a random variable in the usual sense. To overcome this define for \( R > 0 \),
\[ \Lambda_{\alpha, R}^f(\theta, t, z) := (2\pi)^{-dm} \int_{B(0, R)} \int_{\Delta_{\alpha, t}} \prod_{j=1}^{m} f_j(s_j, z_j)(-iu_j)^{\alpha_j} e^{-i(u_j, B_{s_j} - z_j)} ds du, \]
where \( B(0, R) := \{ v \in (\mathbb{R}^d)^m : |v| < R \} \). Clearly we have
\[ |\Lambda_{\alpha, R}^f(\theta, t, z)| \leq C_R \int_{\Delta_{\alpha, t}} \prod_{j=1}^{m} |f_j(s_j, z_j)| ds \]
for an appropriate constant \( C_R \). Let us assume that the above right-hand side is integrable over \( (\mathbb{R}^d)^m \).

Similar computations as above show that \( \Lambda_{\alpha, R}^f(\theta, t, z) \to \Lambda_{\alpha}^f(\theta, t, z) \) in \( L^2(\Omega) \) as \( R \to \infty \) for all \( \theta, t \) and \( z \).

Lebesgue’s dominated convergence theorem and the fact that the Fourier transform is an automorphism on the Schwarz space yield
\[ \lim_{R \to \infty} \int_{(\mathbb{R}^d)^m} \Lambda_{\alpha, R}^f(\theta, t, z) dz = \int_{(\mathbb{R}^d)^m} \Lambda_{\alpha}^f(\theta, t, z) dz \]
\[ = \lim_{R \to \infty} (2\pi)^{-dm} \int_{(\mathbb{R}^d)^m} \int_{B(0, R)} \int_{\Delta_{\alpha, t}} \prod_{j=1}^{m} f_j(s_j, z_j)(-iu_j)^{\alpha_j} e^{-i(u_j, B_{s_j} - z_j)} ds du dz \]
\[ = \lim_{R \to \infty} \int_{\Delta_{\alpha, t}} \int_{B(0, R)} (2\pi)^{-dm} \int_{(\mathbb{R}^d)^m} \prod_{j=1}^{m} f_j(s_j, z_j)e^{iu_j z_j}(-iu_j)^{\alpha_j} e^{-i(u_j, B_{s_j})} dz du ds dz du. \]
\[
\lim_{R \to \infty} \int_{\Delta_{0,t}} \int_{B(0,R)} \prod_{j=1}^{m} \widehat{f}_j(s, -u_j)(-iu_j)^{\alpha_j} e^{-i(u_j, B_{s_j})_{\mathbb{R}^d}} du ds \\
= \int_{\Delta_{0,t}} D^\alpha f(s, B_s) ds
\]

which is exactly (3.3).

Next, we give a crucial estimate which shows why fractional Brownian motion actually regularises (1.1). It is based on integration by parts and the aforementioned properties of the local-time \( L \). The estimate we obtain can be presented in a more explicit way when

\[
\varpi_j(s) = (K_H(s, \theta) - K_H(s, \theta'))^{\varepsilon_j}, \quad \theta < s < t
\]
or,

\[
\varpi_j(s) = (K_H(s, \theta))^{\varepsilon_j}, \quad \theta < s < t
\]

for every \( j = 1, \ldots, m \) with \((\varepsilon_1, \ldots, \varepsilon_m) \in \{0, 1\}^m\) and we will see why these choices are important in the next section.

**Proposition 3.2** Let \( B^H, H \in (0, 1/2) \) be a standard \( d \)-dimensional fractional Brownian motion and functions \( f \) and \( \varpi \) as in (5.8), respectively as in (3.2). Let \( \theta, \theta', t \in [0, T], \theta' < \theta < t \) and

\[
\varpi_j(s) = (K_H(s, \theta) - K_H(s, \theta'))^{\varepsilon_j}, \quad \theta < s < t
\]

for every \( j = 1, \ldots, m \) with \((\varepsilon_1, \ldots, \varepsilon_m) \in \{0, 1\}^m\) for \( \theta, \theta' \in [0, T] \) with \( \theta' < \theta \). Let \( \alpha \in (\mathbb{N}_0^d)^m \) be a multi-index. If

\[
H < \frac{1}{2} - \gamma
\]

for all \( j \), where \( \gamma \in (0, H) \) is sufficiently small, then there exists a universal constant \( C \) (depending on \( H, T \) and \( d \), but independent of \( m, \{f_i\}_{i=1,\ldots,m} \) and \( \alpha \)) such that for any \( \theta, t \in [0, T] \) with \( \theta < t \) we have

\[
\left| E \int_{\Delta_{0,t}} \left( \prod_{j=1}^{m} D^{\alpha_j} f_j(s_j, B_{s_j}^H) \varpi_j(s_j) \right) ds \right| \\
\leq C^{m+|\alpha|} \prod_{j=1}^{m} \left\| f_j(\cdot, z_j) \right\|_{L^1(\mathbb{R}^d; L^\infty([0,T]))} \left( \frac{\theta - \theta'}{\theta' \theta} \right)^{\gamma \sum_{j=1}^{m} \varepsilon_j} \theta \left( H - \frac{1}{2} - \gamma \right)^{\sum_{j=1}^{m} \varepsilon_j} \times \frac{1}{\Gamma \left( -H (2md + 4|\alpha|) + 2 \left( H - \frac{1}{2} - \gamma \right) \sum_{j=1}^{m} \varepsilon_j + 2m \right)}^{1/2}.
\]

**Proof** By definition of \( \Lambda^{\varpi_f}_\alpha \), (3.4) it immediately follows that the integral in our proposition can be expressed as

\[
\int_{\Delta_{0,t}} \left( \prod_{j=1}^{m} D^{\alpha_j} f_j(s_j, B_{s_j}^H) \varpi_j(s_j) \right) ds = \int_{\mathbb{R}^{dm}} \Lambda^{\varpi_f}_\alpha(\theta, t, z) dz.
\]
Taking expectation and using Theorem 3.1 we obtain
\[
\left| E \int_{\tilde{\Delta}_{m,t}^2} \left( \prod_{j=1}^{m} D^{\alpha_j} f_j(s_j, B^{H}_{s_j}) x_j(s_j) \right) ds \right| \leq C^{m+|\alpha|} \prod_{j=1}^{m} \| f_j(\cdot, z_j) \|_{L^1(\mathbb{R}^d; L^\infty([0,T]))} : (\Psi^\infty_\alpha(\theta, t))^{1/2},
\]
where in this situation
\[
\Psi^\infty_\alpha(\theta, t) := \prod_{l=1}^{d} \sqrt{\left(2|\alpha^{(l)}|\right)!} \sum_{\sigma \in S(m,m)} \int_{\tilde{\Delta}_{0,t}^2} \prod_{j=1}^{2m} (K_H(s_j, \theta) - K_H(s_j, \theta r))^{\epsilon(\sigma(j))} \frac{1}{|s_j - s_{j-1}|^H (d+2 \sum_{l=1}^{d} \alpha^{(l)}(\sigma(j)))} ds_1 \ldots ds_{2m}.
\]
We want to apply Lemma A.5. For this, we need that \(-H(d + 2 \sum_{l=1}^{d} \alpha^{(l)}(\sigma(j))) + (H - \frac{1}{2} - \gamma) \epsilon(\sigma(j)) > -1\) for all \(j = 1, \ldots, 2m\). The worst case is, when \(\epsilon(\sigma(j)) = 1\) for all \(j\). So \(H < \frac{1 - \gamma}{(d+2 \sum_{l=1}^{d} \alpha^{(l)}(\sigma(j)))}\) for all \(j\). Hence, we have
\[
\Psi^\infty_\alpha(\theta, t) \leq \sum_{\sigma \in S(m,m)} \left( \frac{\theta - \theta r}{\theta_0} \right)^{\epsilon(\sigma(j))} \frac{\theta^H (H - \frac{1}{2} - \gamma) \sum_{j=1}^{2m} \epsilon(\sigma(j))}{\theta^{H - \frac{1}{2} - \gamma}} \sum_{j=1}^{2m} \epsilon(\sigma(j)) + 2m \times \prod_{l=1}^{d} \sqrt{\left(2|\alpha^{(l)}|\right)!} \Pi_\gamma(2m)(t - \theta)^{-H(2md + 4|\alpha|)} \left(1 - H(2md + 4|\alpha|) + (H - \frac{1}{2} - \gamma) \sum_{j=1}^{2m} \epsilon(\sigma(j)) + 2m \right)
\]
where \(\Pi_\gamma(m)\) is defined as in Lemma A.5. The latter can be bounded above as follows
\[
\Pi_\gamma(2m) \leq \frac{\prod_{j=1}^{2m} \Gamma \left(1 - H \left(d + 2 \sum_{l=1}^{d} \alpha^{(l)}(\sigma(j))\right)\right)}{\Gamma \left(-H (2md + 4|\alpha|) + (H - \frac{1}{2} - \gamma) \sum_{j=1}^{2m} \epsilon(\sigma(j)) + 2m \right)}.
\]
Observe that \(\sum_{j=1}^{2m} \epsilon(\sigma(j)) = 2 \sum_{j=1}^{m} \epsilon_j\). Therefore, we have that
\[
(\Psi^\infty_\alpha(\theta, t))^{1/2} \leq C^m \left( \frac{\theta - \theta r}{\theta_0} \right)^{\epsilon_j} \theta^H (H - \frac{1}{2} - \gamma) \sum_{j=1}^{m} \epsilon_j + \frac{1}{4} \left( \prod_{l=1}^{d} \sqrt{\left(2|\alpha^{(l)}|\right)!} \right)^{1/4} (t - \theta)^{-H(2md + 4|\alpha|)} \left(1 - H(2md + 4|\alpha|) + (H - \frac{1}{2} - \gamma) \sum_{j=1}^{m} \epsilon_j + 2m \right)^{1/2},
\]
where we used \(\prod_{j=1}^{2m} \Gamma \left(1 - H \left(d + 2 \sum_{l=1}^{d} \alpha^{(l)}(\sigma(j))\right)\right) \leq C^m\) for a large enough constant \(C > 0\) and \(\sqrt{a_1} + \ldots + \sqrt{a_m} \leq \sqrt{a_1} + \ldots + \sqrt{a_m}\) for arbitrary non-negative numbers \(a_1, \ldots, a_m\).
Proposition 3.3 Let $B^H, H \in (0, 1/2)$ be a standard $d$-dimensional fractional Brownian motion and functions $f$ and $\kappa$ as in (5.8), respectively as in (3.2). Let $\theta, t \in [0, T]$ with $\theta < t$ and
\[
x_j(s) = (K_H(s, \theta))^{\varepsilon_j}, \theta < s < t
\]
for every $j = 1, \ldots, m$ with $(\varepsilon_1, \ldots, \varepsilon_m) \in \{0, 1\}^m$. Let $\alpha \in (\mathbb{N}^d_0)^m$ be a multi-index. If
\[
H < \frac{1}{2} - \gamma \left( d - 1 + 2 \sum_{l=1}^d \alpha_j^{(l)} \right)
\]
for all $j$, where $\gamma \in (0, H)$ is sufficiently small, then there exists a universal constant $C$ (depending on $H, T$ and $d$, but independent of $m, \{f_i\}_{i=1,\ldots,m}$ and $\alpha$) such that for any $\theta, t \in [0, T]$ with $\theta < t$ we have
\[
\left| E \int \Delta_{\theta,t} \left( \prod_{j=1}^m D^{\alpha_j} f_j(s_j, B^H_{s_j}) \kappa_j(s_j) \right) ds \right|
\leq C^{m+|\alpha|} \prod_{j=1}^m \| f_j(\cdot, z_j) \|_{L^1([0,T])} \| f_j(\cdot, z_j) \|_{L^\infty([0,T])} \theta^{(H-\frac{1}{2}) \sum_{j=1}^m \varepsilon_j}
\times \left( \prod_{l=1}^d (2 |\alpha^{(l)}|) \right)^{1/4} (t - \theta)^{-H(md + 2|\alpha|)} (-H \gamma) \sum_{j=1}^m \varepsilon_j + m \Gamma \left( -H (2md + 4 |\alpha|) + 2 (H - \frac{1}{2} - \gamma) \sum_{j=1}^m \varepsilon_j + 2m \right)^{1/2}.
\]

Proof The proof is similar to the previous proposition. \qed

Remark 3.4 We mention that
\[
\prod_{l=1}^d \left( 2 |\alpha^{(l)}| \right)! \leq (2 |\alpha|)! C^{|\alpha|}
\]
for a constant $C$ depending on $d$. Later on in the paper, when we deal with the existence of strong solutions, we will consider the case
\[
\alpha_j^{(l)} \in \{0, 1\} \text{ for all } j, l
\]
with
\[
|\alpha| = m.
\]

4 Existence and Uniqueness of Global Strong Solutions

As outlined in the introduction the object of study is a time-inhomogeneous SDE with additive $d$-dimensional fractional Brownian noise $B^H$ with Hurst parameter $H \in (0, 1/2)$, i.e.
\[
dX_t = b(t, X_t)dt + dB^H_t, \quad X_0 = x \in \mathbb{R}^d, \quad t \in [0, T],
\]
where $b : [0, T] \times \mathbb{R}^d \to \mathbb{R}^d$ is a Borel-measurable function. We will study Eq. (1.1) when the drift coefficient $b$ belongs to $L^1(\mathbb{R}^d; L^\infty([0,T], \mathbb{R}^d)) \cap L^\infty(\mathbb{R}^d; L^\infty([0,T], \mathbb{R}^d))$. We will introduce the following short notation for the following functional spaces
Theorem 4.1 Let \( b \in L^{1,\infty}_\infty \). Then if \( H < \frac{1}{2(\gamma + d)} \), \( d \geq 1 \) there exists a unique (global) strong solution \( X = \{X_t, t \in [0, T]\} \) of Eq. (1.1). Moreover, for every \( t \in [0, T] \), \( X_t \) is Malliavin differentiable in the direction of the Brownian motion \( W \) in (2.3).

The proof of Theorem 4.1 is based on the following steps:

1. First, we construct a weak solution \( X \) to (1.1) by means of Girsanov’s theorem, that is we introduce a probability space \((\Omega, \mathfrak{F}, \mathbb{P})\) that carries a fractional Brownian motion \( B^H \) and a process \( X \) such that (1.1) is fulfilled. However, a priori \( X \) is not adapted to the filtration \( \mathcal{F} = \{\mathcal{F}_t\}_{t \in [0, T]} \) generated by \( B^H \).

2. Next, we approximate the drift coefficient \( b \) a.e. by a sequence of functions (which always exists by standard approximation results) \( b_n \subset C^\infty_c([0, T] \times \mathbb{R}^d) \), \( n \geq 0 \) (actually it suffices to look at approximating coefficients which are only smooth with respect to the space variable) such that

\[
b_n(t, x) \longrightarrow b(t, x) \tag{4.2}
\]

as \( n \to \infty \) for a.e. \((t, x) \in [0, T] \times \mathbb{R}^d\) with \( \sup_{n \geq 0} \|b_n\|_{L^1_\infty} < \infty \) and such that \( |b_n(t, x)| \leq M < \infty \), \( n \geq 0 \) a.e. for some constant \( M \). By standard results on SDEs, we know that for each smooth coefficient \( b_n, n \geq 0 \), there exists unique strong solution \( X^n \) to the SDE

\[
dX^n_t = b_n(t, X^n_t)du + dB^H_t, \quad 0 \leq t \leq T, \quad X^n_0 = x \in \mathbb{R}^d. \tag{4.3}
\]

We then show that for each \( t \in [0, T] \) the sequence \( X^n_t \) converges weakly to the conditional expectation \( \mathbb{E}[X_t|\mathcal{F}_t] \) in the space \( L^2(\Omega; \mathcal{F}_t) \) of square integrable, \( \mathcal{F}_t \)-measurable random variables.

3. It is well known, see e.g. [43], that for each \( t \in [0, T] \) the strong solution \( X^n_t \), \( n \geq 0 \), is Malliavin differentiable, and that the Malliavin derivative \( D_s X^n_t \), \( 0 \leq s \leq t \), with respect to \( W \) in (2.3) satisfies

\[
D_s X^n_t = K_H(t, s)I_d + \int_s^t b'_n(u, X^n_u)D_s X^n_udu, \tag{4.4}
\]

where \( b'_n \) denotes the Jacobian of \( b_n \) and \( I_d \) the identity matrix in \( \mathbb{R}^{d \times d} \). In the next step we then employ a compactness criterion based on Malliavin calculus to show that for every \( t \in [0, T] \) the set of random variables \( \{X^n_t\}_{n \geq 0} \) is relatively compact in \( L^2(\Omega) \), which then admits the conclusion that \( X^n_t \) converges strongly in \( L^2(\Omega; \mathcal{F}_t) \) to \( \mathbb{E}[X_t|\mathcal{F}_t] \). Further we see that \( \mathbb{E}[X_t|\mathcal{F}_t] \) is Malliavin differentiable as a consequence of the compactness criterion.

4. In the last step we show that \( \mathbb{E}[X_t|\mathcal{F}_t] = X_t \), which implies that \( X_t \) is \( \mathcal{F}_t \)-measurable and thus a strong solution on our specific probability space.

We turn to the first step of our scheme which is to construct weak solutions of (1.1) by using Girsanov’s theorem in this context. Let \((\Omega, \mathfrak{F}, \mathbb{P})\) be some given probability space which
Lemma 4.2 Let $\tilde{B}^H_t$ be a $d$-dimensional fractional Brownian motion with respect to $(\Omega, \mathcal{F}, \tilde{P})$. Then

$$
\int_0^t |b(s, \tilde{B}^H_s)|ds \in L^2_0([0, T]), \quad \tilde{P} - a.s.
$$

**Proof** Using the property that $D_{0+}^{H+\frac{1}{2}} I_{0+}^{H+\frac{1}{2}} (f) = f$ for $f \in L^2([0, T])$ we need to show that

$$
D_{0+}^{H+\frac{1}{2}} \left( \int_0^t |b(s, \tilde{B}^H_s)|ds \right) (t) \leq \frac{1}{\Gamma(\frac{1}{2} - H)} \left( \frac{1}{t^{H+\frac{1}{2}}} \int_0^t |b(u, \tilde{B}^H_u)|du 
+ \left( H + \frac{1}{2} \right) \int_0^t (t - s)^{-H + \frac{1}{2}} \int_s^t |b(u, \tilde{B}^H_u)|duds \right) \frac{1}{\Gamma(\frac{1}{2} - H) \frac{1}{2} - H} \|b\|_{L^\infty}.
$$

Hence, for some finite constant $C_H > 0$ we have

$$
\left| D_{0+}^{H+\frac{1}{2}} \left( \int_0^t |b(s, \tilde{B}^H_s)|ds \right) (t) \right|^2 \leq C_H \|b\|^2_{L^\infty} t^{1-2H}.
$$

As a result,

$$
\int_0^T \left| D_{0+}^{H+\frac{1}{2}} \left( \int_0^t |b(s, \tilde{B}^H_s)|ds \right) (t) \right|^2 dt \leq C_H \|b\|^2_{L^\infty} \int_0^T t^{1-2H} dt < \infty, \quad \tilde{P} - a.s.
$$

since $H \in (0, 1/2)$.

Lemma 4.3 Let $\tilde{B}^H_t$ be a $d$-dimensional fractional Brownian motion with respect to $(\Omega, \mathcal{F}, \tilde{P})$. Then for every $\mu \in \mathbb{R}$ we have

$$
\tilde{E} \left[ \exp \left\{ \mu \int_0^T \left| K_H^{-1} \left( \int_0^T b(r, \tilde{B}_r^H)dr \right) (s) \right|^2 ds \right\} \right] \leq C_{H,d,\mu,T} (\|b\|_{L^\infty})
$$

for some continuous increasing function $C_{H,d,\mu,T}$ depending only on $H, d, T$ and $\mu$.

In particular,

$$
\tilde{E} \left[ \mathcal{E} \left( \int_0^T K_H^{-1} \left( \int_0^T b(r, \tilde{B}_r^H)dr \right) s dW_s \right) \right]^p \leq C_{H,d,\mu,T} (\|b\|_{L^\infty}),
$$

where $\tilde{E}$ denotes expectation under $\tilde{P}$ and $*$ denotes transposition.
**Proof** Denote by $\theta_s := K_H^{-1} \left( \int_0^s |b(r, \tilde{B}^H_r)|dr \right)(s)$. Then using relation (2.5) we have

$$|\theta_s| = |s^{H-\frac{1}{2}}I_{0+}^{\frac{1}{2}-H} s^{\frac{1}{2}-H} |b(s, \tilde{B}^H_s)||
= \frac{1}{\Gamma\left(\frac{1}{2} - H\right)} s^{H-\frac{1}{2}} \int_0^s (s - r)^{-\frac{1}{2} - H} r^{\frac{1}{2} - H} |b(r, \tilde{B}^H_r)|dr 
\leq \|b\|_{L^\infty} \frac{1}{\Gamma\left(\frac{1}{2} - H\right)} s^{H-\frac{1}{2}} \int_0^s (s - r)^{-\frac{1}{2} - H} r^{\frac{1}{2} - H} dr 
= \|b\|_{L^\infty} \frac{\Gamma\left(\frac{3}{2} - H\right)}{\Gamma\left(1 - 2H\right)} s^{\frac{1}{2} - H} 
\leq \|b\|_{L^\infty} \frac{\Gamma\left(\frac{3}{2} - H\right)}{\Gamma\left(1 - 2H\right)} T^{\frac{1}{2} - H}.

Squaring both sides we have the following estimate

$$|\theta_s|^2 \leq C_H \|b\|^2_{L^\infty} T^{1 - 2H} \quad P - a.s., \quad (4.5)$$

where $C_H := \frac{\Gamma\left(\frac{3}{2} - H\right)^2}{\Gamma\left(1 - 2H\right)^2}$.

Then we get the following estimate

$$E\left[\exp\left\{\mu \int_0^T |\theta_s|^2 \, ds\right\}\right] \leq \exp\left\{\|\mu\| C_H T^{2(1-H)} \|b\|^2_{L^\infty}\right\}.$$

By Girsanov’s theorem, see Theorem 2.4, the process

$$B_t^H := X_t - x - \int_0^t b(s, X_s)ds, \quad t \in [0, T] \quad (4.6)$$

is a fractional Brownian motion on $(\Omega, \mathfrak{A}, P)$ with Hurst parameter $H \in (0, 1/2)$, where $\frac{dP}{dP^\xi_T} = \xi_T$. Hence, because of (4.6), the couple $(X, B^H)$ is a weak solution of (1.1) on $(\Omega, \mathfrak{A}, P)$.

Henceforth, we confine ourselves to the filtered probability space $(\Omega, \mathfrak{A}, P)$, $\mathcal{F} = \{\mathcal{F}_t\}_{t \in [0, T]}$ which carries the weak solution $(X, B^H)$ of (1.1).

**Remark 4.4** As outlined in the scheme above, the main challenge to establish existence of a strong solution is now to show that $X$ is $\mathcal{F}$-adapted. Indeed, in that case $X_t = \mathcal{F}_t(B^H)$ for some family of measurable functionals $\mathcal{F}_t$, $t \in [0, T]$ on $C([0, T]; \mathbb{R}^d)$, and for any other stochastic basis $(\tilde{\Omega}, \tilde{\mathfrak{A}}, \tilde{P}, \tilde{B})$ one gets that $X_t := \mathcal{F}_t(\tilde{B})$, $t \in [0, T]$, is a $\tilde{B}$-adapted solution to SDE (1.1). But this means exactly the existence of a strong solution to SDE (1.1).

**Remark 4.5** It is worth to remark that one actually has existence of weak solutions for any $H \in (0, 1/2)$ and that weak solutions for bounded $b$ are weakly unique since the estimates from Lemma 4.3 also hold with $X$ in place of $\tilde{B}^H$. For this reason, the main challenge is to show that when $H$ is small enough such solutions are in fact strong. Then weak uniqueness implies strong uniqueness. See [45].

We now turn to the second step of our procedure.
Lemma 4.6 Let \{b_n\}_{n \geq 0} \subset C^\infty_c([0, T] \times \mathbb{R}^d) be an approximating sequence of b in the sense of (4.2). Denote by \(X^n = \{X^n_t, t \in [0, T]\}\) the corresponding solutions of (1.1) if we replace \(b\) by \(b_n, n \geq 0\). Then for every \(t \in [0, T]\) and bounded continuous function \(\varphi: \mathbb{R}^d \to \mathbb{R}\) we have that

\[
\varphi(X^n_t) \xrightarrow{n \to \infty} \mathbb{E} [\varphi(X_t) | \mathcal{F}_t],
\]

weakly in \(L^2(\Omega; \mathcal{F}_t)\).

**Proof** For a moment let us just, without loss of generality, assume that \(x = 0\). First we show that

\[
\mathcal{E} \left( \int_0^t K_H^{-1} \left( \int_0^s b_n(r, B^H_r) dr \right)^* (s) dW_s \right) \to \mathcal{E} \left( \int_0^t K_H^{-1} \left( \int_0^s b(r, B^H_r) dr \right)^* (s) dW_s \right)
\]

in \(L^p(\Omega)\) for all \(p \geq 1\). To see this, note that

\[
K_H^{-1} \left( \int_0^s b_n(r, B^H_r) dr \right)(s) \to K_H^{-1} \left( \int_0^s b(r, B^H_r) dr \right)(s)
\]

in probability for all \(s\). Indeed, similar computations as in Lemma 4.3 give

\[
\mathbb{E} \left[ K_H^{-1} \left( \int_0^s b_n(r, B^H_r) dr \right)(s) - K_H^{-1} \left( \int_0^s b(r, B^H_r) dr \right)(s) \right] \\
\leq \frac{s^{H-1/2}}{\Gamma(\frac{1}{2} - H)} \int_0^s (s - r)^{-1/2 - H} r^{1/2 - H} \mathbb{E} |b_n(r, B^H_r) - b(r, B^H_r)| |dr \\
= \frac{s^{H-1/2}}{\Gamma(\frac{1}{2} - H)} \int_0^s (s - r)^{-1/2 - H} r^{1/2 - H} \int_{\mathbb{R}^d} \mathbb{E} |b_n(r, y) - b(r, y)| (2\pi r^{2H})^{-d/2} ddyr \to 0
\]

as \(n \to \infty\) since \(b_n(t, x) \to b(t, x)\) for a.e. \((t, x)\).

Moreover, \(\left\{ K_H^{-1} \left( \int_0^s b_n(r, B^H_r) dr \right) \right\}_{n \geq 0}\) is bounded in \(L^2([0, t] \times \Omega; \mathbb{R}^d)\). This is directly seen from (4.5) in Lemma 4.3.

Consequently

\[
\int_0^t K_H^{-1} \left( \int_0^s b_n(r, B^H_r) dr \right)^* (s) dW_s \to \int_0^t K_H^{-1} \left( \int_0^s b(r, B^H_r) dr \right)^* (s) dW_s
\]

and

\[
\int_0^t \left| K_H^{-1} \left( \int_0^s b_n(r, B^H_r) dr \right)(s) \right|^2 ds \to \int_0^t \left| K_H^{-1} \left( \int_0^s b(r, B^H_r) dr \right)(s) \right|^2 ds
\]

in \(L^2(\Omega)\) since the latter is bounded \(L^p(\Omega)\) for any \(p \geq 1\), see Lemma 4.3.

Using the estimate \(|e^x - e^y| \leq e^{x+y}|x - y|\), Hölder’s inequality and the bounds in Lemma 4.3 it is clear that (4.7) holds.
Similarly, one also shows that
\[
\exp \left\{ \left\langle \alpha, \int_s^t b_n(r, B^H_t) \right\rangle \right\} \rightarrow \exp \left\{ \left\langle \alpha, \int_s^t b(r, B^H_t) \right\rangle \right\}
\]
in \( L^p(\Omega) \) for all \( p \geq 1, 0 \leq s \leq t \leq T, \alpha \in \mathbb{R}^d \).

To conclude the proof we note that the set
\[
\Sigma_t := \left\{ \exp \left\{ \sum_{j=1}^k \left\langle \alpha_j, B^H_t - B^H_{t_j-1} \right\rangle \right\} \right\} : \left\{ \alpha_j \right\}_{j=1}^k \subset \mathbb{R}^d, 0 = t_0 < \cdots < t_k = t, k \geq 1 \}
\]
is a total subspace of \( L^2(\Omega, \mathcal{F}_t, P) \) and we may thus restrict ourselves to show the convergence
\[
\lim_{n \to \infty} \mathbb{E} \left[ (\varphi(X^n_t) - \mathbb{E}[\varphi(X_t)|\mathcal{F}_t]) \xi \right] = 0
\]
for all \( \xi \in \Sigma_t \). To this end, we notice that \( \varphi \) is of linear growth and hence \( \varphi(B^H_t) \) has all moments. Consequently we have the following convergence
\[
\mathbb{E} \left[ \varphi(X^n_t) \exp \left\{ \sum_{j=1}^k \left\langle \alpha_j, B^H_t - B^H_{t_j-1} \right\rangle \right\} \right] \\
= \mathbb{E} \left[ \varphi(X^n_t) \exp \left\{ \sum_{j=1}^k \left\langle \alpha_j, X^n_{t_j} - X^n_{t_j-1} - \int_{t_j}^{t_{j+1}} b_n(s, X^n_s) ds \right\rangle \right\} \right] \\
= \mathbb{E} \left[ \varphi(B^H_t) \exp \left\{ \sum_{j=1}^k \left\langle \alpha_j, B^H_t - B^H_{t_j-1} - \int_{t_j}^{t_{j+1}} b_n(s, B^H_s) ds \right\rangle \right\} \mathcal{E} \right. \\
\times \left. \left( \int_0^t K^{-1}_H \left( \int_0^t b_n(r, B^H_r) dr \right)^* (s) dW_s \right) \right] \\
\rightarrow \mathbb{E} \left[ \varphi(B^H_t) \exp \left\{ \sum_{j=1}^k \left\langle \alpha_j, B^H_t - B^H_{t_j-1} - \int_{t_j}^{t_{j+1}} b(s, B^H_s) ds \right\rangle \right\} \mathcal{E} \right. \\
\times \left. \left( \int_0^t K^{-1}_H \left( \int_0^t b(r, B^H_r) dr \right)^* (s) dW_s \right) \right] \\
= \mathbb{E} \left[ \varphi(X_t) \exp \left\{ \sum_{j=1}^k \left\langle \alpha_j, B^H_t - B^H_{t_j-1} \right\rangle \right\} \mathcal{E} \right. \\
= \mathbb{E} \left[ \mathbb{E}[\varphi(X_t)|\mathcal{F}_t] \exp \left\{ \sum_{j=1}^k \left\langle \alpha_j, B^H_t - B^H_{t_j-1} \right\rangle \right\} \right].
\]

\( \square \)

We continue to proving the third step of our scheme. This is the most challenging part. The following result is based on a compactness criterion for subsets of \( L^2(\Omega) \) which is summarised in the Appendix.
**Lemma 4.7** Let \( \{b_n\}_{n \geq 0} \subset C^\infty_c([0, T] \times \mathbb{R}^d) \) an approximating sequence of \( b \) in the sense of (4.2). Fix \( t \in [0, T] \) and denote by \( X^n_t \) the corresponding solutions of (1.1) if we replace \( b \) by \( b_n \), \( n \geq 0 \). Then there exists \( \alpha \) \( \in (0, 1/2) \) such that

\[
\sup_{n \geq 0} \int_0^t \int_0^t \frac{E[\|D_\theta X^n_t - D_{\theta'} X^n_t\|^2]}{\|\theta' - \theta\|^{1 + 2\alpha}} d\theta' d\theta \leq \sup_{n \geq 0} C_{H, d, T}(\|b_n\|_{L^\infty}, \|b_n\|_{L^1}) < \infty
\]

and

\[
\sup_{n \geq 0} \|D. X^n_t\|_{L^2(\Omega \times [0, T], \mathbb{R}^{d \times d})} \leq \sup_{n \geq 0} C_{H, d, T}(\|b_n\|_{L^\infty}, \|b_n\|_{L^1}) < \infty
\]  

(4.8)

for some continuous function \( C_{H, d, T} : [0, \infty) \rightarrow [0, \infty) \). Here, \( \cdot \) denotes the maximum norm in \( \mathbb{R}^{d \times d} \).

**Proof** Fix \( t \in [0, T] \) and take \( \theta, \theta' > 0 \) such that \( 0 < \theta' < \theta < t \). Using the chain rule for the Malliavin derivative, see [43, Proposition 1.2.3], we have

\[
D_\theta X^n_t = K_H(t, \theta) I_d + \int_0^t b'_n(s, X^n_s) D_\theta X^n_s ds,
\]

where the above equality is meant in the \( L^p \)-sense with respect to time. Here, \( b'_n(s, z) = \left( \frac{\partial}{\partial z_j} b^{(i)}(s, z) \right)_{i, j = 1, \ldots, d} \) denotes the Jacobian matrix of \( b_n \) and \( I_d \) the identity matrix in \( \mathbb{R}^{d \times d} \). Thus we have

\[
D_{\theta'} X^n_t - D_{\theta} X^n_t = K_H(t, \theta') I_d - K_H(t, \theta) I_d
\]

\[
+ \int_0^t b'_n(s, X^n_s) D_{\theta'} X^n_s ds - \int_0^t b'_n(s, X^n_s) D_{\theta} X^n_s ds
\]

\[
= K_H(t, \theta') I_d - K_H(t, \theta) I_d
\]

\[
+ \int_0^t b'_n(s, X^n_s) D_{\theta'} X^n_s ds + \int_0^t b'_n(s, X^n_s) (D_{\theta'} X^n_s - D_{\theta} X^n_s) ds
\]

\[
= K_H(t, \theta') I_d - K_H(t, \theta) I_d + D_{\theta'} X^n_t - K_H(\theta, \theta') I_d
\]

\[
+ \int_0^t b'_n(s, X^n_s) (D_{\theta'} X^n_s - D_{\theta} X^n_s) ds.
\]

Using Picard iteration applied to the above equation we may write

\[
D_{\theta'} X^n_t = K_H(t, \theta') I_d - K_H(t, \theta) I_d
\]

\[
+ \sum_{m=1}^{\infty} \int_{\Delta_0^m} \prod_{j=1}^{m} b'_n(s_j, X^n_{s_j}) (K_H(s_m, \theta') I_d - K_H(s_m, \theta) I_d) ds_m \cdots ds_1
\]

\[
+ \left( I_d + \sum_{m=1}^{\infty} \int_{\Delta_0^m} \prod_{j=1}^{m} b'_n(s_j, X^n_{s_j}) ds_m \cdots ds_1 \right) (D_{\theta'} X^n_t - K_H(\theta, \theta') I_d).
\]

On the other hand, observe that one may again write

\[
D_{\theta'} X^n_t = K_H(\theta, \theta') I_d = \sum_{m=1}^{\infty} \int_{\Delta_0^m} \prod_{j=1}^{m} b'_n(s_j, X^n_{s_j}) (K_H(s_m, \theta') I_d) ds_m \cdots ds_1.
\]
Altogether, we can write
\[ D_{\theta'}X^n_t - D_{\theta}X^n_t = I_1(\theta', \theta) + I_2^n(\theta', \theta) + I_3^n(\theta', \theta), \]
where
\[ I_1(\theta', \theta) := KH(t, \theta')I_d - KH(t, \theta)I_d \]
\[ I_2^n(\theta', \theta) := \sum_{m=1}^\infty \int_{\Delta^m_{\theta', \theta}} \prod_{j=1}^m b'_n(s_j, X^n_s) (KH(s_m, \theta')I_d - KH(s_m, \theta)I_d) \, ds_m \cdots ds_1 \]
\[ I_3^n(\theta', \theta) := \left( I_d + \sum_{m=1}^\infty \int_{\Delta^m_{\theta', \theta}} \prod_{j=1}^m b'_n(s_j, X^n_s) ds_m \cdots ds_1 \right) \times \left( \sum_{m=1}^\infty \int_{\Delta^m_{\theta', \theta}} \prod_{j=1}^m b'_n(s_j, X^n_s) (KH(s_m, \theta')I_d) ds_m \cdots ds_1. \right) \]

It follows from Lemma A.4 that
\[ \int_0^t \int_0^t \frac{\|I_1(\theta', \theta)\|^2_{L^2(\Omega)}}{|\theta' - \theta|^{1+2\beta}} \, d\theta d\theta' < \int_0^t \int_0^t \frac{|KH(t, \theta') - KH(t, \theta)|^2}{|\theta' - \theta|^{1+2\beta}} \, d\theta d\theta' < \infty \quad (4.9) \]
for a suitably small \( \beta \in (0, 1/2). \)

Let us continue with the term \( I_2^n(\theta', \theta). \) Then Girsanov’s theorem, Cauchy–Schwarz inequality and Lemma 4.3 imply
\[
\begin{align*}
E[\|I_2^n(\theta', \theta)\|^2] &\leq \tilde{C}(\|b_n\|_{L^\infty}) \\
&\times E\left[ \left\| \sum_{m=1}^\infty \int_{\Delta^m_{\theta', \theta}} \prod_{j=1}^m b'_n(s_j, x + B_{s_j}^H) \left( KH(s_m, \theta')I_d - KH(s_m, \theta)I_d \right) ds_m \cdots ds_1 \right\|^{4} \right]^{1/2},
\end{align*}
\]
where \( \tilde{C} : [0, \infty) \to [0, \infty) \) is the function from Lemma 4.3. Taking the supremum over \( n \) we have
\[ \sup_{n \geq 0} \tilde{C}(\|b_n\|_{L^\infty}) =: C_1 < \infty. \]

Then,
\[
\begin{align*}
E[\|I_2^n(\theta', \theta)\|^2] &\leq C_1 \left( \sum_{m=1}^\infty \sum_{i=1}^d \sum_{l_1, \ldots, l_{m-1}=1}^d \left\| \int_{\Delta^m_{\theta', \theta}} \frac{\partial}{\partial x_{l_1}} b_{n}^{(i)}(s_1, x + B_{s_1}^H) \right\| \right)^2 \\
&\times \frac{\partial}{\partial x_{l_2}} b_{n}^{(i)}(s_2, x + B_{s_2}^H) \cdots \\
&\cdots \frac{\partial}{\partial x_{l_{m-1}}} b_{n}^{(i)}(s_m, x + B_{s_m}^H) \left( KH(s_m, \theta') - KH(s_m, \theta) \right) ds_m \cdots ds_1 \left\| L^4(\Omega, \mathbb{R}) \right\|^2.
\end{align*}
\]
Now look at the expression
\[ J_2^n(\theta', \theta) := \int_{\Delta_{\theta', \theta}^n} \frac{\partial}{\partial x_j} b_n^{(i)}(s_1, x + B_{s_1}^H) \cdots \frac{\partial}{\partial x_j} b_n^{(m-1)}(s_m, x + B_{s_m}^H) \times (K_H(s_m, \theta') - K_H(s_m, \theta)) \, ds. \] (4.10)

Then, shuffling \( J_2^n(\theta', \theta) \) as shown in (2.1), one can write \((J_2^n(\theta', \theta))^2\) as a sum of at most \(2^{2m}\) summands of length \(2m\) of the form
\[ \int_{\Delta_{\theta', \theta}^{2m}} g_1^n(s_1, B_{s_1}^H) \cdots g_{2m}^n(s_{2m}, B_{s_{2m}}^H) ds_{2m} \cdots ds_1, \] (4.11)
where for each \( l = 1, \ldots, 2m, \)
\[ g_l^n(\cdot, B_{s_1}^H) \in \left\{ \frac{\partial}{\partial x_j} b_n^{(i)}(\cdot, x + B_{s_1}^H), \frac{\partial}{\partial x_j} b_n^{(i)}(\cdot, x + B_{s_1}^H) \times (K_H(\cdot, \theta') - K_H(\cdot, \theta)) \right\}. \]

Repeating this argument once again, we find that \( J_2^n(\theta', \theta)^4 \) can be expressed as a sum of, at most, \(2^{4m}\) summands of length \(4m\) of the form
\[ \int_{\Delta_{\theta', \theta}^{4m}} g_1^n(s_1, B_{s_1}^H) \cdots g_{4m}^n(s_{4m}, B_{s_{4m}}^H) ds_{4m} \cdots ds_1, \] (4.12)
where for each \( l = 1, \ldots, 4m, \)
\[ g_l^n(\cdot, B_{s_1}^H) \in \left\{ \frac{\partial}{\partial x_j} b_n^{(i)}(\cdot, x + B_{s_1}^H), \frac{\partial}{\partial x_j} b_n^{(i)}(\cdot, x + B_{s_1}^H) \times (K_H(\cdot, \theta') - K_H(\cdot, \theta)) \right\}. \]

It is important to note that the function \((K_H(\cdot, \theta') - K_H(\cdot, \theta))\) appears only once in term (4.10) and hence only four times in term (4.12). So there are indices \( j_1, \ldots, j_4 \in \{1, \ldots, 4m\} \) such that we can write (4.12) as
\[ \int_{\Delta_{\theta', \theta}^{4m}} \left( \prod_{j=1}^{4m} b_j^n(s_j, B_{s_j}^H) \right) \prod_{i=1}^{4m} (K_H(s_j, \theta') - K_H(s_j, \theta)) \, ds_{4m} \cdots ds_1, \]
where
\[ b_l^n(\cdot, B_{s_1}^H) \in \left\{ \frac{\partial}{\partial x_j} b_n^{(i)}(\cdot, x + B_{s_1}^H), i, j = 1, \ldots, d \right\}, \quad l = 1, \ldots, 4m. \]

The latter enables us to use the estimate from Proposition 3.2 with \( \sum_{j=1}^{4m} e_j = 4, \sum_{l=1}^d a_{[\sigma(l)]}^{(l)} = 1 \) for all \( j, |\alpha| = 4m \) and Remark 3.4. Therefore we get that
\[ E(J_2^n(\theta', \theta))^4 \leq \left( \frac{\theta - \theta'}{\theta \theta'} \right)^{4\gamma} \theta^4 (H - \frac{1}{2} - \gamma) C^{4m} \| b_n \|_{L_\infty}^{4m} A_m^{\gamma}(H, d, |t - \theta|) \]
whenever \( H < \frac{1}{2(d+2)} \) and \( \gamma \in (0, H) \), where
\[ A_m^{\gamma}(H, d, |t - \theta|) := \frac{(8m!)^{1/4} (t - \theta)^{-H(4m(d+2)) - 4(H - \frac{1}{2} - \gamma) + 4m} \Gamma \left( -H(d + 2)8m + 8 \left( H - \frac{1}{2} - \gamma \right) + 8m \right)^{1/2}. \]
Altogether, we see that

\[
\mathbb{E} \left[ \| I^n_{\gamma}(\theta', \theta) \|^2 \right] \leq \left( \frac{\theta - \theta'}{\theta \theta'} \right)^{2\gamma} \theta^2 (H - \frac{1}{2} - \gamma) \left( \sum_{m=1}^{\infty} d^{m+1} C_m \| b_n \|^m_{L^1_{\infty}} A^\gamma_m (H, d, |T|)^{1/4} \right)^2.
\]

Since \( H < \frac{1}{2(d + 2)} \), we see that the latter sum is convergent. Hence, we can find a continuous function \( C_{H, d, T} : [0, \infty)^2 \to [0, \infty) \) such that there is a suitably small \( \gamma \) for \( \gamma \in (0, H) \) provided that \( H < \frac{1}{2(d + 2)} \). It is easy to see that we can choose \( \gamma \in (0, H) \) such that there is a suitably small \( \beta \in (0, 1/2) \), \( 0 < \beta < \gamma < H < 1/2 \) so that it follows from Lemma A.4 that

\[
\int_0^t \int_0^t \left| \frac{\theta - \theta'}{\theta \theta'} \right|^{2\gamma} |\theta|^2 (H - \frac{1}{2} - \gamma) |\theta - \theta'|^{-1 - 2\beta} d\theta' d\theta < \infty,
\]

for every \( t \in (0, T]\). We now turn to the term \( I^n_{\gamma}(\theta', \theta) \). Observe that term \( I^n_{\gamma}(\theta', \theta) \) is the product of two terms, where the first one will simply be bounded uniformly in \( \theta, t \in [0, T] \) under expectation. This can be shown by following meticulously the same steps as we did for \( I^n_{\gamma}(\theta', \theta) \) and observing that in virtue of Proposition 3.3 with \( \epsilon_j = 0 \) for all \( j \) the singularity in \( \theta \) vanishes. Again Girsanov’s theorem, Cauchy–Schwarz inequality several times and Lemma 4.3 lead to

\[
\mathbb{E}[\| I^n_{\gamma}(\theta', \theta) \|^2] \leq \tilde{C}(\| b_n \|_{L^\infty}) I_d + \sum_{m=1}^{\infty} I_{\sum_{l=1}^{m-1}} \sum_{j=1}^{m} b_{n}^{l}(s_j, x + B_{s_j}^{H}) ds_m \cdots ds_1 \| L^8(\Omega, \mathbb{R}^{d \times d}) \times \sum_{m=1}^{\infty} I_{\sum_{l=1}^{m-1}} \sum_{j=1}^{m} b_{n}^{l}(s_j, x + B_{s_j}^{H}) K_{H}(s_m, \theta') ds_m \cdots ds_1 \| L^4(\Omega, \mathbb{R}^{d \times d})^2,
\]

where \( \tilde{C} : [0, \infty) \to [0, \infty) \) denotes the corresponding function obtained from Lemma 4.3 which satisfies

\[
\sup_{n \geq 0} \tilde{C}(\| b_n \|_{L^\infty}) =: C_2 < \infty.
\]

Again, we have

\[
\mathbb{E}[\| I^n_{\gamma}(\theta', \theta) \|^2] \leq C_2 \left( 1 + \sum_{m=1}^{\infty} \sum_{i,j=1}^{d} \sum_{l=1}^{d} \left\| \int_{\Delta_{l_i}}^{\Delta_{l_{i,j}}} \frac{\partial}{\partial x_{l_i}} b_n^{(i)}(s_1, x + B_{s_1}^{H}) \cdots \right\|^2 \right) \times \left( \sum_{m=1}^{\infty} \sum_{i,j=1}^{d} \sum_{l=1}^{d} \left\| \int_{\Delta_{l_i}}^{\Delta_{l_{i,j}}} \frac{\partial}{\partial x_{l_i}} b_n^{(i)}(s_1, x + B_{s_1}^{H}) \right\|^2 \right) \times \left( \sum_{m=1}^{\infty} \sum_{i,j=1}^{d} \sum_{l=1}^{d} \left\| \int_{\Delta_{l_i}}^{\Delta_{l_{i,j}}} \frac{\partial}{\partial x_{l_i}} b_n^{(i)}(s_1, x + B_{s_1}^{H}) \right\|^2 \right) \times \left( \sum_{m=1}^{\infty} \sum_{i,j=1}^{d} \sum_{l=1}^{d} \left\| \int_{\Delta_{l_i}}^{\Delta_{l_{i,j}}} \frac{\partial}{\partial x_{l_i}} b_n^{(i)}(s_1, x + B_{s_1}^{H}) \right\|^2 \right).
\]
Using exactly the same reasoning as for \( I^n_3(\theta', \theta) \) we see that the first factor can be bounded by some finite constant \( C_3(\|b_n\|_{L_1,\infty}) \) depending on \( H, d, T \) and \( \|b_n\|_{L_1,\infty} \), i.e.

\[
E[\|I^n_3(\theta', \theta)\|^2] \leq C_3(\|b_n\|_{L_1,\infty}) \left( \sum_{m=1}^{\infty} \frac{d^m}{m!} \sum_{i,j=1,\ldots,d} \int_{\Delta_{\theta',\theta}^m} \frac{\partial}{\partial x_j} b_n^{(i)}(s_1, x + B_{s_1}^H) \cdots \frac{\partial}{\partial x_j} b_n^{(m-1)}(s_m, x + B_{s_m}^H) K_H(s_m, \theta') ds_m \cdots ds_1 \right)^2.
\]

As before, look at

\[
J^n_3(\theta', \theta) := \int_{\Delta_{\theta',\theta}^m} \frac{\partial}{\partial x_j} b_n^{(i)}(s_1, x + B_{s_1}^H) \cdots \frac{\partial}{\partial x_j} b_n^{(m-1)}(s_m, x + B_{s_m}^H) K_H(s_m, \theta') ds_m \cdots ds_1.
\]

(4.14)

We can express \( J^n_3(\theta', \theta) \) as a sum of, at most, \( 2^8m \) summands of length \( 4m \) of the form

\[
\int_{\Delta_{\theta',\theta}^m} g^n_1(s_1, B_{s_1}^H) \cdots g^n_{4m}(s_{4m}, B_{s_{4m}}^H) ds_1 \cdots ds_{4m},
\]

(4.15)

where for each \( l = 1, \ldots, 4m \),

\[
g^n_l(\cdot, B_{s}^H) = \left\{ \frac{\partial}{\partial x_j} b_n^{(i)}(\cdot, x + B_{s}^H) : i, j = 1, \ldots, d \right\},
\]

where the factor \( K_H(\cdot, \theta') \) is repeated four times in the integrand of (4.15). Now we can simply apply Proposition 3.3 with \( \sum_{j=1}^{4m} \varepsilon_j = 4 \), \( \sum_{i=1}^{d} \alpha_{i(\sigma(j))} = 1 \) for all \( j, |\alpha| = 4m \) and Remark 3.4 and obtain that

\[
E[\|J^n_3(\theta', \theta)\|^4] \leq \theta^4(H^{-1/2}) C^{4m} \|b_n\|_{L_1,\infty}^{4m} A_0^0(H, d, |\theta - \theta'|),
\]

whenever \( H < \frac{1}{2(2+d)} \) where \( A_0^0(H, d, |\theta - \theta'|) \) is defined as in (4) by inserting \( \gamma = 0 \).

As a result,

\[
E[\|I^n_3(\theta', \theta)\|^2] \leq \theta^2(H^{-1/2}) \left( \sum_{m=1}^{\infty} \frac{d^m}{m!} \|b_n\|_{L_1,\infty}^m A_0^0(H, d, |\theta - \theta'|)^{1/4} \right)^2.
\]

Note that the above series converges, because \( H < \frac{1}{2(2+d)} \).

Since the exponent of \(|\theta - \theta'| \) appearing in \( A_0^0(b_n, H, d, |\theta - \theta'|) \) is strictly positive by assumption, we can find a small enough \( \varepsilon > 0 \) and a continuous function \( C_{H,d,T} : [0, \infty)^2 \rightarrow [0, \infty) \) such that

\[
\sup_{n \geq 0} E[\|I^n_3(\theta', \theta)\|^2] \leq \sup_{n \geq 0} C_{H,d,T}(\|b_n\|_{L_1,\infty}, \|b_n\|_{L_1,\infty})|\theta|^2(H^{-1/2})|\theta - \theta'|^{\varepsilon}
\]

provided \( H < \frac{1}{2(2+d)} \). Then again, it is easy to see that we can choose \( \beta \in (0, 1/2) \) small enough so that it follows from Lemma A.4 that

\[
\int_0^t \int_0^t |\theta |^2(H^{-1/2})|\theta - \theta'|^{\varepsilon-1-2\beta} d\theta' d\theta < \infty,
\]

(4.16)

for every \( t \in [0, T] \).
Altogether, taking a suitable $\beta$ so that (4.9), (4.13) and (4.16) are finite, we have

$$\sup_{n \geq 0} \int_0^t \int_0^t E[\|D_{\theta'}X^n_t - D_{\theta''}X^n_t\|^2] \, d\theta' \, d\theta \leq \sup_{n \geq 0} C_{H,d,T}(\|b_n\|_{L^\infty}, \|b_n\|_{L^1}) < \infty$$

for some continuous function $C_{H,d,T} : [0, \infty)^2 \to [0, \infty)$.

Similar computations show that

$$\sup_{n \geq 0} \|D_nX^n_t\|_{L^2(\Omega \times [0,T], \mathbb{R}^{d \times d})} \leq \sup_{n \geq 0} C_{H,d,T}(\|b_n\|_{L^\infty}, \|b_n\|_{L^1}) < \infty.$$

\[\square\]

**Corollary 4.8** Let $\{b_n\}_{n \geq 0} \subset C_c^\infty([0, T] \times \mathbb{R}^d)$ the approximating sequence of $b$ in the sense of (4.3). Denote by $X^n_t$ the corresponding solutions of (4.2) if we replace $b$ by $b_n$, $n \geq 0$.

Then for every $t \in [0, T]$ and bounded continuous function $\phi : \mathbb{R}^d \to \mathbb{R}$ we have

$$\phi(X^n_t) \xrightarrow{n \to \infty} \phi(E[X_t|\mathcal{F}_t])$$

strongly in $L^2(\Omega; \mathbb{F}_t)$. In addition, $E[X_t|\mathcal{F}_t]$ is Malliavin differentiable for every $t \in [0, T]$.

**Proof** This is an immediate consequence of the relative compactness from Corollary A.3 in connection with Lemma 4.7 and because of Lemma 4.6 we can identify the limit as being $E[X_t|\mathcal{F}_t]$, then the convergence holds for any bounded continuous function as well. The Malliavin differentiability of $E[X_t|\mathcal{F}_t]$ is shown by taking $\phi = I_d$ and estimate (4.8) together with [43, Proposition 1.2.3]. \[\square\]

Finally, we can prove the main result of this section.

**Proof of Theorem 4.1** It remains to prove that $X_t$ is $\mathcal{F}_t$-measurable for every $t \in [0, T]$ and by Remark 4.4 it then follows that there exists a strong solution in the usual sense that is Malliavin differentiable. Indeed, let $\phi$ be a globally Lipschitz continuous function, then by Corollary 4.8 we have, for a subsequence $n_k, k \geq 0$, that

$$\phi(X^n_{t_k}) \to \phi(E[X_t|\mathcal{F}_t]), \quad P - a.s.$$  

as $k \to \infty$.

On the other hand, by Lemma 4.6 we also have

$$\phi(X^n_t) \rightharpoonup E[\phi(X_t)|\mathcal{F}_t]$$

weakly in $L^2(\Omega; \mathbb{F}_t)$. By the uniqueness of the limit we immediately have

$$\phi \left( E[X_t|\mathcal{F}_t] \right) = E[\phi(X_t)|\mathcal{F}_t], \quad P - a.s.$$  

which implies that $X_t$ is $\mathcal{F}_t$-measurable for every $t \in [0, T]$.

Finally, to show uniqueness it is enough to show that two given strong solutions are weakly unique, indeed, one can follow the same argument as in [45, Chapter IX, Exercise (1.20)] which asserts that strong existence and uniqueness in law imply pathwise uniqueness. The argument does not rely on the process being a semimartingale. Since our solutions are, by construction, strong and uniqueness in law follows from Novikov’s condition from Lemma 4.3 replacing $B^H$ by $X$ then pathwise uniqueness follows. \[\square\]
5 Stochastic Flows and Regularity Properties

Henceforward, we will denote by $X_t^{s,x}$ the solution to the following SDE driven by a fractional Brownian motion with $H < 1/2$}

$$dX_t^{s,x} = b(t, X_t^{s,x})dt + dB_t^H, \quad s, t \in [0, T], \quad s \leq t, \quad X_s^{s,x} = x \in \mathbb{R}^d. \quad (5.1)$$

We will then assume the hypotheses from Theorem 4.1 on $b$ and $H$, that is $b \in L^{1,\infty}_{\infty,\infty}$ and $H < \frac{1}{2(d+2)}$. The next result tells us that if $H = H(k)$ is small enough we may gain regularity on $x \mapsto X_t^{s,x}$. In particular, it shows that the strong solution constructed in the former section, in addition to being Malliavin differentiable, is also once weakly differentiable with respect to $x$ since $k = 1$. See the authors in [4], who treated the case $k = 2$.

**Theorem 5.1** Let $b \in C_c^{\infty}([0, T] \times \mathbb{R}^d)$. Fix integers $p \geq 2$ and $k \geq 1$. Then, if $H < \frac{1}{(d-1+2k)}$, we have

$$\sup_{s,t \in [0,T]} \sup_{x \in \mathbb{R}^d} \mathbb{E}\left[ \left\| \frac{\partial^k}{\partial x^k} X_t^{s,x} \right\|^p \right] \leq C_{k,d,H,p,T}(\|b\|_{L^\infty}, \|b\|_{L^1}),$$

where $C_{k,d,H,p,T} : [0, \infty)^2 \rightarrow [0, \infty)$ is a continuous function, depending on $k, d, H, p$ and $T$.

**Proof** For notational convenience, let us assume that $s = 0$ and denote the corresponding solution by $X^x_t$, $0 \leq t \leq T$ with respect to the vector field $b \in C_c^{\infty}((0, T) \times \mathbb{R}^d)$. Since the stochastic flow associated with the smooth vector field $b$ is smooth, too (compare to e.g. [30]), we find that

$$\frac{\partial}{\partial x} X^x_t = I_{d \times d} + \int_s^t D_b(u, X^x_u) \cdot \frac{\partial}{\partial x} X^x_u du, \quad (5.2)$$

where $D_b(u, \cdot) : \mathbb{R}^d \rightarrow L(\mathbb{R}^d, \mathbb{R}^d)$ is the derivative of $b$ with respect to the space variable.

By employing Picard iteration, we obtain that

$$\frac{\partial}{\partial x} X^x_t = I_{d \times d} + \sum_{m \geq 1} \int_{\Delta^m_{0,t}} D_b(u, X^x_{u_1}) \ldots D_b(u, X^x_{u_m}) du_m \ldots du_1, \quad (5.3)$$

where

$$\Delta^m_{0,t} = \{(u_m, \ldots, u_1) \in [0, T]^m : \theta < u_m < \cdots < u_1 < t\}.$$

Using dominated convergence, we can differentiate both sides with respect to $x$ and see that

$$\frac{\partial^2}{\partial x^2} X^x_t = \sum_{m \geq 1} \int_{\Delta^m_{0,t}} \frac{\partial}{\partial x} [D_b(u, X^x_{u_1}) \ldots D_b(u, X^x_{u_m})] du_m \ldots du_1.$$

On the other hand the Leibniz and chain rule give

$$\frac{\partial}{\partial x} [D_b(u_1, X^x_{u_1}) \ldots D_b(u_m, X^x_{u_m})]$$

$$= \sum_{r=1}^m D_b(u_1, X^x_{u_1}) \ldots D^2 b(u_r, X^x_{u_r}) \frac{\partial}{\partial x} X^x_{u_r} \ldots D_b(u_m, X^x_{u_m}),$$

where $D^2 b(u, \cdot) = D(D_b(u, \cdot)) : \mathbb{R}^d \rightarrow L(\mathbb{R}^d, L(\mathbb{R}^d, \mathbb{R}^d))$. 
So (5.3) implies that

$$
\frac{d^2}{dx^2} X_t^x = \sum_{m_1 \geq 1} \sum_{r=1}^{m_1} \int_{\Delta_{0, t}} Db(u_1, X_{u_1}^x) \ldots D^2 b(u_r, X_{u_r}^x) \\
\times \left( I_d \times d + \sum_{m_2 \geq 1} \int_{\Delta_{0, u_r}} Db(v_1, X_{v_1}^x) \ldots Db(v_{m_2}, X_{v_{m_2}}^x) dv_{m_2} \ldots dv_1 \right) \\
\times Db(u_{r+1}, X_{u_{r+1}}^x) \ldots Db(u_{m_1}, X_{u_{m_1}}^x) du_{m_1} \ldots du_1
$$

\[= \sum_{m_1 \geq 1} \sum_{r=1}^{m_1} \int_{\Delta_{0, t}} Db(u_1, X_{u_1}^x) \ldots D^2 b(u_r, X_{u_r}^x) \ldots Db(u_{m_1}, X_{u_{m_1}}^x) du_{m_1} \ldots du_1 \]

\[+ \sum_{m_1 \geq 1} \sum_{r=1}^{m_1} \sum_{m_2 \geq 1} \int_{\Delta_{0, u_r}} Db(u_1, X_{u_1}^x) \ldots D^2 b(u_r, X_{u_r}^x) \\
\times Db(v_1, X_{v_1}^x) \ldots Db(v_{m_2}, X_{v_{m_2}}^x) Db(u_{r+1}, X_{u_{r+1}}^x) \ldots Db(u_{m_1}, X_{u_{m_1}}^x) \\
\times dv_{m_2} \ldots dv_1 du_{m_1} \ldots du_1
\]

\[= : I_1 + I_2. \quad (5.4)\]

Next we apply Lemma A.11 (in connection with Lemma 2.1) to the term $I_2$ in (5.4) and obtain that

$$I_2 = \sum_{m_1 \geq 1} \sum_{r=1}^{m_1} \sum_{m_2 \geq 1} \int_{\Delta_{0, t}} \mathcal{H}_{m_1+m_2}^X(u) du_{m_1+m_2} \ldots du_1 \quad (5.5)$$

for $u = (u_1, \ldots, u_{m_1+m_2})$, where the integrand $\mathcal{H}_{m_1+m_2}^X(u) \in \mathbb{R}^d \otimes \mathbb{R}^d \otimes \mathbb{R}^d$ has entries given by sums of at most $C(d)^{m_1+m_2}$ terms, which are products of length $m_1+m_2$ of functions belonging to the set

$$\left\{ \frac{\partial^{\gamma(1)+\ldots+\gamma(d)}}{\partial^{\gamma(1)} x_1 \ldots \partial^{\gamma(d)} x_d} b^{(r)}(u, X_u^x), \ r = 1, \ldots, d, \ \gamma(1) + \ldots + \gamma(d) \leq 2, \ \gamma(l) \in \mathbb{N}_0, \ l = 1, \ldots, d \right\}.$$

Here it is crucial to note that second order derivatives of functions in those products of functions on $\Delta_{0, t}^{m_1+m_2}$ in (5.5) only appear once. So the total order of derivatives $|\alpha|$ of those products of functions in connection with Lemma A.11 in the Appendix is

$$|\alpha| = m_1 + m_2 + 1. \quad (5.6)$$

We now choose $p, c, r \in [1, \infty)$ such that $cp = 2^d$ for some integer $q$ and $\frac{1}{r} + \frac{1}{c} = 1$. Then we can use Hölder’s inequality and Girsanov’s theorem (see Theorem 2.4) in combination with Lemma 4.3 and find that

$$E[\|I_2\|^p] \leq C(\|b\|_{L_\infty}) \left( \sum_{m_1 \geq 1} \sum_{r=1}^{m_1} \sum_{m_2 \geq 1} \sum_{i \in I} \left\| \int_{\Delta_{0, t}} \mathcal{H}_{i}^{BH}(u) du_{m_1+m_2} \ldots du_1 \right\| \right)^p,$$

(5.7)
where $C : [0, \infty) \rightarrow [0, \infty)$ is a continuous function depending on $p$. Here $\#I \leq K^{m_1 + m_2}$ for a constant $K = K(d)$ and the integrands $\mathcal{H}_I^{B^H}(u)$ take the form

$$
\mathcal{H}_I^{B^H}(u) = \prod_{l=1}^{m_1 + m_2} h_l(u_l), \ h_l \in \Lambda, \ l = 1, \ldots, m_1 + m_2
$$

where

$$
\Lambda := \left\{ \frac{\partial^{\gamma_1} + \ldots + \partial^{\gamma_d}}{\partial x_1 \ldots \partial x_d} b^{(r)}(u, x + B^H_t), \ \ r = 1, \ldots, d, \right\}
$$

As before here functions with second order derivatives only appear once in those products. Let

$$
J := \left( \int_{\Delta_0} 2^q \mathcal{H}_I^{B^H}(u) du_{m_1 + m_2} \ldots du_1 \right)^{2^q}
$$

By employing Lemma 2.1 once more in the Appendix, successively, we find that $J$ can be represented as a sum of, at most of length $K(q)^{m_1 + m_2}$ with summands of the form

$$
\int_{\Delta_0} 2^q (m_1 + m_2) \prod_{l=1}^{2^q (m_1 + m_2)} f_l(u_l) du_{2^q (m_1 + m_2)} \ldots du_1,
$$

where $f_l \in \Lambda$ for all $l$.

Here the number of factors $f_l$ in the above product, which have a second order derivative, is exactly $2^q$. So the total order of the derivatives involved in (5.8) in connection with Lemma A.11 (where one in that lemma formally replaces $X^\gamma_x$ by $x + B^H_t$ in the corresponding terms) is

$$
|\alpha| = 2^q (m_1 + m_2 + 1).
$$

We now want to apply Theorem 3.3 for $m = 2^q (m_1 + m_2)$ and $\varepsilon_j = 0$ and see that

$$
E \left[ \int_{\Delta_0} 2^q (m_1 + m_2) \prod_{l=1}^{2^q (m_1 + m_2)} f_l(u_l) du_{2^q (m_1 + m_2)} \ldots du_1 \right]
\leq C^{m_1 + m_2} \left( \|b\|_{L_\infty} \right)^{2^q (m_1 + m_2)}
\times \frac{((2^q (m_1 + m_2 + 1))!)^{1/4}}{\Gamma(-H (2d 2^q (m_1 + m_2) + 42^q (m_1 + m_2 + 1)) + 22^q (m_1 + m_2))^{1/2}}
$$

for a constant $C$ depending on $H, T, d$ and $q$.

Hence the latter in combination with (5.7) yields that

$$
E[\|I_2\|^p]
\leq C \left( \|b\|_{L_\infty} \right) \left( \sum_{m_1 \geq 1} \sum_{m_2 \geq 1} K^{m_1 + m_2} \left( \|b\|_{L_\infty} \right)^{2^q (m_1 + m_2)}
\times \frac{((2^q (m_1 + m_2 + 1))!)^{1/4}}{\Gamma(-H (2d 2^q (m_1 + m_2) + 42^q (m_1 + m_2 + 1)) + 22^q (m_1 + m_2))^{1/2}} \right)^p
$$

for a constant $K$ depending on $H, T, d, p$ and $q$.

Since $\frac{1}{2(d+3)} \leq \frac{1}{2(d+3)^{m_1 + m_2}}$ for $m_1, m_2 \geq 1$, it follows that the above sum converges, whenever $H < \frac{1}{2(d+3)}$. 

\section*{Journal of Dynamics and Differential Equations (2020) 32:1819–1866 1853

\section*{\textcopyright Springer}
On the other hand one obtains by using the same reasoning as before a similar estimate for $E[\|I_1\|^p]$. Altogether the proof follows for $k = 2$. Let us now explain the generalization of the previous line of reasoning to the case $k \geq 2$: In this case, we get that

$$\frac{\partial^k}{\partial x^k} X^x_t = I_1 + \ldots + I_{2^k-1},$$

(5.10)

where each $I_i$, $i = 1, \ldots, 2^{k-1}$ is a sum of iterated integrals over simplices of the form $\Delta_{0,u}$, $0 < u < t$, $j = 1, \ldots, k$ with integrands, which have at most one product factor $D^k b$, whereas the other factors are of the form $D^j b$, $j \leq k - 1$.

In what follows we need the following notation: For given multi-indices $m. = (m_1, \ldots, m_k)$ and $r := (r_1, \ldots, r_{k-1})$ we define

$$m_j := \sum_{i=1}^j m_i$$

and

$$\sum_{m \geq 1, \sum_{m_j \leq m_j} l_{j=1}^{k-1} := \sum_{m_1 \geq 1} \sum_{m_2 \geq 1} \ldots \sum_{m_{k-1} \geq 1} \sum_{m_k \geq 1}.$$  

In the sequel, we restrict ourselves without loss of generality to the estimation of the summand $I_{2^k-1}$ in (5.10). In the same way as in the case $k = 2$, we get by invoking Lemma A.11 (in connection with Lemma 2.1) that

$$I_{2^k-1} = \sum_{m \geq 1, \sum_{m_j \leq m_j} l_{j=1}^{k-1} \leq m} \int_{\Delta_{0,u}} \mathcal{H}^{X}_{m_1+\ldots+m_k}(u) du m_1 + m_2 \ldots m_1$$

(5.11)

for $u = (u_{m_1+\ldots+m_k}, \ldots, u_1)$, where the integrand $\mathcal{H}^{X}_{m_1+\ldots+m_k}(u) \in \otimes_{j=1}^{k+1} \mathbb{R}^d$ has entries given by sums of at most $C(d)m_1+\ldots+m_k$ terms, which are products of length $m_1 + \ldots m_k$ of functions, which are elements in

$$\left\{ \frac{\partial^{r_1+\ldots+\gamma(d)}}{\partial x_1^{r_1} \ldots \partial x_d^{\gamma}} b^{(r)}(u, X^x_u), \quad r = 1, \ldots, d, \right\}$$

$$\gamma^{(l)} + \ldots + \gamma^{(d)} \leq k, \gamma^{(l)} \in \mathbb{N}_0, \quad l = 1, \ldots, d \}.$$ 

Just as in the case $k = 2$ we can employ Lemma A.11 in the Appendix and obtain that the total order of derivatives $|\alpha|$ of those products of functions is

$$|\alpha| = m_1 + \ldots + m_k + k - 1.$$  

(5.12)

Then we follow the line of reasoning as before and choose $p, c, r \in [1, \infty)$ such that $cp = 2^q$ for some integer $q$ and $\frac{1}{r} + \frac{1}{c} = 1$ and get by making use of Hölder’s inequality and Girsanov’s theorem (see Theorem 2.4) in connection with Lemma 4.3 that
where $C : [0, \infty) \rightarrow [0, \infty)$ is a continuous function depending on $p$. Here $|I| \leq K^{m_1+\ldots+m_k}$ for a constant $K = K(d)$ and the integrands $H_i^{B_H}(u)$ are of the form

$$H_i^{B_H}(u) = \prod_{l=1}^{m_1+\ldots+m_k} h_l(u_l), \; h_l \in \Lambda, \; l = 1, \ldots, m_1 + \ldots + m_k,$$

where

$$\Lambda := \begin{cases} \frac{\partial^{(r)}}{\partial x_1^{(r_1)} \ldots \partial x_d^{(r_d)}} b^{(r)}(u, x + B_H^u), & r = 1, \ldots, d, \\ \gamma^{(1)} + \ldots + \gamma^{(d)} \leq k, \; \gamma^{(l)} \in \mathbb{N}_0, \; l = 1, \ldots, d. \end{cases}$$

Define

$$J = \left( \int_{\Delta_{0,t}} H_i^{B_H}(u) du_{m_1+\ldots+m_k} \ldots du_1 \right)^{2q}.$$

Once more, repeated application of Lemma 2.1 in the Appendix shows that $J$ can be written as a sum of, at most of length $K(q)^{m_1+\ldots+m_k}$ with summands of the form

$$\int_{\Delta_{0,t}}^{2q(m_1+\ldots+m_k)} \prod_{l=1}^{2q(m_1+\ldots+m_k)} f_l(u_l) du_2q(m_1+\ldots+m_k) \ldots du_1, \quad (5.14)$$

where $f_l \in \Lambda$ for all $l$.

By using Lemma A.11 again (where one in that Lemma formally replaces $X_i^x$ by $x + B_H^u$ in the corresponding expressions) we find that the total order of the derivatives in the products of functions in (5.14) is given by

$$|x| = 2q(m_1 + \ldots + m_k + k - 1). \quad (5.15)$$

Then Proposition 3.3 for $m = 2q(m_1 + \ldots + m_k)$ and $\varepsilon_j = 0$ implies that

\[
\begin{align*}
E \left[ \int_{\Delta_{0,t}}^{2q(m_1+\ldots+m_k)} \prod_{l=1}^{2q(m_1+\ldots+m_k)} f_l(u_l) du_2q(m_1+\ldots+m_k) \ldots du_1 \right] \\
\leq C^{m_1+\ldots+m_k} \left( \|b\|_{L^1(\mathbb{R}^d)} \right)^{2q(m_1+\ldots+m_k)} \\
\times \frac{((2q(m_1+\ldots+m_k+k-1)))^{1/4}}{\Gamma(-H(2q(m_1+\ldots+m_k+42q(m_1+\ldots+m_k+k-1))+22q(m_1+\ldots+m_k)))^{1/2}}
\end{align*}
\]

for a constant $C$ depending on $H, T, d$ and $q$. 

\[\text{Springer}\]
So it follows from (5.13) that
\[
E[\|I_{2k-1}\|^p] \\
\leq C(\|b\|_{L^\infty}) \left( \sum_{m_1 \geq 1} \ldots \sum_{m_k \geq 1} K^{m_1 + \ldots + m_k} (\|b\|_{L^\infty})^{2^a(m_1 + \ldots + m_k)} \right) \times \\
\left( (2(2^a(m_1 + \ldots + m_k + k-1)) \right)^{1/4} \Gamma(-H(2d2^a(m_1 + \ldots + m_k + k-1) + 22q(m_1 + \ldots + m_k))^{1/2})^{1/2} )^p
\]
for a constant K depending on H, T, d, p and q.

Since we required that \( H < \frac{1}{2(d-1+2k)} \) the above sum converges. So the proof follows. \( \square \)

The following is the main result of this section and shows that the fractional Brownian motion \( B^H \) creates a regularising effect on the solution as a function of the initial condition.

**Theorem 5.2** Assume \( b \in L^{1,\infty}_{\infty,\infty} \). Let \( U \subset \mathbb{R}^d \) and open and bounded subset and \( X = \{X_t, t \in [0, T]\} \) the solution of (1.1). Then for a small enough Hurst parameter \( H \), that is \( H < \frac{1}{2(d-1+2k)} \), it follows that
\[
X_t \in \bigcap_{p>1} L^2(\Omega, W^{k,p}(U)).
\]

**Proof** First of all, approximate the irregular drift vector field \( b \) by a sequence of functions \( b_n : [0, T] \times \mathbb{R}^d \to \mathbb{R}^d, n \geq 0 \) in \( C^\infty_c([0, T] \times \mathbb{R}^d, \mathbb{R}^d) \) in the sense of (4.2). Denote by \( X^{n,x} = \{X^{n,x}_t, t \in [0, T]\} \), the corresponding solution to (1.1) starting from \( x \in \mathbb{R}^d \) when \( b \) is replaced by \( b_n \).

Observe that for any test function \( \varphi \in C^\infty_c(U, \mathbb{R}^d) \) and fixed \( t \in [0, T] \) the set of random variables
\[
(X_t^{n,x}, \varphi) := \int_U (X^{n,x}_t, \varphi(x))_{\mathbb{R}^d} dx, \ n \geq 0
\]
is relatively compact in \( L^2(\Omega) \). To show this, we use the compactness criterion from Appendix, in Corollary A.3 in terms of the Malliavin derivative. Since the Malliavin derivative is a closed linear operator we have
\[
E \left[ \int_0^T |D^\theta (X_t^{n,x}, \varphi)|^2 d\theta \right] \leq d \|\varphi\|^2_{L^2(\mathbb{R}^d, \mathbb{R}^d)} \lambda(\text{supp } \varphi) \sup_{x \in U} \left[ \int_0^T \|D^\theta X_t^{n,x}\|^2 d\theta \right],
\]
where \( D^\theta \) denotes the Malliavin derivative in the direction of \( W^{(j)} \), \( \lambda \) the Lebesgue measure on \( \mathbb{R}^d \), \( \text{supp } \varphi \) the support of \( \varphi \) and \( \| \cdot \| \) a matrix norm. Then taking the sum over all \( j = 1, \ldots, d \) and using Lemma 4.7 we obtain
\[
\sup_{n \geq 0} \|D^\theta (X_t^{n,x}, \varphi)\|^2_{L^2(\Omega \times [0,T])} \leq C \|\varphi\|^2_{L^2(\mathbb{R}^d, \mathbb{R}^d)} \lambda(\text{supp } \varphi).
\]
In a similar manner we have
\[ \sup_{n \geq 0} \int_0^T \int_0^T \mathbb{E} \left[ \frac{\| D\phi'(X_{t-}^n, \varphi) - D\phi(X_{t-}^n, \varphi) \|}{|\theta' - \theta|^{1 + 2\beta}} \right] d\theta d\theta' < \infty \]
for some \( \beta \in (0, 1/2) \). Hence \( \langle X_t^n, \varphi \rangle, n \geq 0 \) is relatively compact in \( L^2(\Omega) \). Let us denote by \( Y_t(\varphi) \) its limit after taking (if necessary) a subsequence.

Following exactly the same reasoning as in Lemma 4.6 one can show that
\[ \langle X_t^n, \varphi \rangle \xrightarrow{n \to \infty} \langle X_t, \varphi \rangle \]
weakly in \( L^2(\Omega) \). Then by uniqueness of the limit we can establish that
\[ Y_t(\varphi) = \langle X_t, \varphi \rangle \]
in \( L^2(\Omega) \).

Note that there exists a subsequence \( n(j) \) such that \( \langle X_t^{n(j)}, \varphi \rangle \) converges for every \( \varphi \), that is, \( n(j) \) is independent of \( \varphi \).

We have that \( X_t^{n(i)} \) is bounded in the Sobolev norm \( L^2(\Omega, W^{k, p}(U)) \) for each \( n \geq 0 \). Indeed, by Proposition 5.1 we have
\[
\sup_{n \geq 0} \| X_t^{n(i)} \|^2_{L^2(\Omega, W^{k, p}(U))} = \sup_{n \geq 0} \sum_{i=0}^{k} \mathbb{E} \left[ \left\| \frac{\partial^i}{\partial x^i} X_t^{n(i)} \right\|_{L^p(U)}^2 \right]
\leq \sum_{i=0}^{k} \left( \int_{U} \sup_{n \geq 0} \left\| \frac{\partial^i}{\partial x^i} X_t^{n,x} \right\|_p^p dx \right)^{\frac{2}{p}} < \infty
\]
for a small enough \( H < 1/2 \).

Since \( L^2(\Omega, W^{k, p}(U)), p \in (1, \infty) \) is reflexive we get that the set \( \{X_t^{n,x}\}_{n \geq 0} \) is weakly compact in \( L^2(\Omega, W^{k, p}(U)) \). Thus, there exists a subsequence \( n(j), j \geq 0 \) such that
\[ X_t^{n(j)} \xrightarrow{w} Y \in L^2(\Omega, W^{k, p}(U)). \]

On the other hand, we have proven that \( X_t^{n,x} \rightarrow X_t^x \) strongly in \( L^2(\Omega) \), so by uniqueness of the limit we can conclude that
\[ X_t = Y \in L^2(\Omega, W^{k, p}(U)), \quad P - a.s. \]

Moreover, we have for all \( A \in \mathcal{F}, \varphi \in C_c(\mathbb{R}^d), \alpha = (\alpha^{(1)}, \ldots, \alpha^{(d)}) \in \mathbb{N}_0^d \) with \( |\alpha| = \alpha^{(1)} + \ldots + \alpha^{(d)} \leq k \) that
\[
E \left[ 1_A \left\{ X_t^{n,j}; D^\alpha \varphi \right\} \right]
= (-1)^{|\alpha|} E \left[ 1_A \left\{ D^\alpha X_t^{n,j}; \varphi \right\} \right]
\xrightarrow{j \to \infty} (-1)^{|\alpha|} E \left[ 1_A \left\{ D^\alpha Y; \varphi \right\} \right]
\]
and thus
\[ \langle X_t, D^\alpha \varphi \rangle = (-1)^{|\alpha|} \langle D^\alpha Y, \varphi \rangle, \quad P - a.s. \]
\[ \square \]
Funding This work was financially supported by STORM, Research Council of Norway (Project No. 274410) and STOCONINF, Research Council of Norway (Project No. 250768).

Compliance with Ethical Standards

Conflict of interest The authors declare that they have no conflict of interest.

Appendix A: Technical Results

The following result which is due to \[15, \text{Theorem 1}\] provides a compactness criterion for subsets of $L^2(\Omega)$ using Malliavin calculus.

**Theorem A.1** Let $\{(\Omega, A, P) : H\}$ be a Gaussian probability space, that is $(\Omega, A, P)$ is a probability space and $H$ a separable closed subspace of Gaussian random variables of $L^2(\Omega)$, which generate the $\sigma$-field $A$. Denote by $D$ the derivative operator acting on elementary smooth random variables in the sense that

$$D(f(h_1, \ldots, h_n)) = \sum_{i=1}^{n} \partial_i f(h_1, \ldots, h_n)h_i, \quad h_i \in H, \ f \in C^\infty_b(\mathbb{R}^n).$$

Further let $\mathbb{D}^{1,2}$ be the closure of the family of elementary smooth random variables with respect to the norm

$$\|F\|_{1,2} := \|F\|_{L^2(\Omega)} + \|DF\|_{L^2(\Omega; H)}.$$

Assume that $C$ is a self-adjoint compact operator on $H$ with dense image. Then for any $c > 0$ the set

$$G = \{ G \in \mathbb{D}^{1,2} : \|G\|_{L^2(\Omega)} + \|C^{-1}DG\|_{L^2(\Omega; H)} \leq c \}$$

is relatively compact in $L^2(\Omega)$.

In order to formulate compactness criteria useful for our purposes, we need the following technical result which also can be found in \[15\].

**Lemma A.2** Let $v_s, s \geq 0$ be the Haar basis of $L^2([0, T])$. For any $0 < \alpha < 1/2$ define the operator $A_\alpha$ on $L^2([0, T])$ by

$$A_\alpha v_s = 2^{k\alpha}v_s, \text{ if } s = 2^k + j$$

for $k \geq 0, 0 \leq j \leq 2^k$ and

$$A_\alpha 1 = 1.$$

Then for all $\beta$ with $\alpha < \beta < (1/2)$, there exists a constant $c_1$ such that

$$\|A_\alpha f\| \leq c_1 \left\{ \|f\|_{L^2([0,T])} + \left( \int_0^T \int_0^T \frac{|f(t) - f(t')|^2}{|t - t'|^{1+2\beta}} dt \, dt' \right)^{1/2} \right\}.$$

A direct consequence of Theorem A.1 and Lemma A.2 is now the following compactness criteria. See \[15\] for a proof.
**Corollary A.3** Let a sequence of $\mathcal{F}_t$-measurable random variables $X_n \in \mathbb{D}^{1,2}$, $n = 1, 2 \ldots$, be such that there exists a constant $C > 0$ with

$$\sup_n E[|X_n|^2] \leq C,$$

$$\sup_n E \left[ \|D_t X_n\|^2_{L^2([0,T])} \right] \leq C$$

and there exists a $\beta \in (0, 1/2)$ such that

$$\sup_n \int_0^T \int_0^T E \left[ \|D_t X_n - D_{t'} X_n\|^2 \right] \frac{dt \, dt'}{|t - t'|^{1 + 2\beta}} < \infty$$

where $\| \cdot \|$ denotes any matrix norm.

Then the sequence $X_n$, $n = 1, 2 \ldots$, is relatively compact in $L^2(\Omega)$.

For the use of the above result we will need to exploit the following technical results.

**Lemma A.4** Let $H \in (0, 1/2)$ and $t \in [0, T]$ be fixed. Then, there exists a $\beta \in (0, 1/2)$ such that

$$\int_0^t \int_0^t \frac{|K_H(t, \theta') - K_H(t, \theta)|^2}{|\theta' - \theta|^{1 + 2\beta}} d\theta d\theta' < \infty$$

(A.1)

**Proof** Let $\theta, \theta' \in [0, t]$, $\theta' < \theta$ be fixed. Write

$$K_H(t, \theta) - K_H(t, \theta') = c_H \left[ f_t(\theta) - f_t(\theta') + \left( \frac{1}{2} - H \right) (g_t(\theta) - g_t(\theta')) \right],$$

where $f_t(\theta) := \left( \frac{l}{\theta} \right)^{H-\frac{1}{2}} (t - \theta)^{H-\frac{1}{2}}$ and $g_t(\theta) := \int_\theta^t \frac{f_u(\theta)}{u} du$, $\theta \in [0, t]$.

We will proceed to estimating $K_H(t, \theta) - K_H(t, \theta')$. First, observe the following fact,

$$\frac{y^{-\alpha} - x^{-\alpha}}{(x - y)^\gamma} \leq C \frac{y^{-\alpha - \gamma}}{(x - y)^\gamma}$$

for every $0 < y < x < \infty$ and $\alpha := \left( \frac{1}{2} - H \right) \in (0, 1/2)$ and $\gamma < \frac{1}{2} - \alpha$. This implies

$$f_t(\theta) - f_t(\theta') = \left( \frac{l}{\theta} (t - \theta) \right)^{H-\frac{1}{2}} - \left( \frac{l}{\theta'} (t - \theta') \right)^{H-\frac{1}{2}} \leq C \left( \frac{l}{\theta} (t - \theta) \right)^{H-\frac{1}{2} - \gamma} \frac{\theta^\gamma (t - \theta')^\gamma}{\theta'^\gamma (t - \theta')^\gamma} \leq C \frac{(\theta - \theta')^\gamma}{(\theta')^\gamma} (t - \theta)^{H-\frac{1}{2} - \gamma} \leq C \frac{(\theta - \theta')^\gamma}{(\theta')^\gamma} (t - \theta)^{H-\frac{1}{2} - \gamma} \leq C \frac{(\theta - \theta')^\gamma}{(\theta')^\gamma} t^{\frac{1}{2} - \gamma} (t - \theta)^{H-\frac{1}{2} - \gamma}.$$

Further,

$$g_t(\theta) - g_t(\theta') = \int_\theta^t \frac{f_u(\theta) - f_u(\theta')}{u} du - \int_\theta^{\theta'} \frac{f_u(\theta')}{u} du \leq \int_\theta^t \frac{f_u(\theta) - f_u(\theta')}{u} du$$
As a result, we have for every $\gamma \in (0, H), \ 0 < \theta' < \theta < t < T,$

$$(K_H(t, \theta) - K_H(t, \theta'))^2 \leq C_{H,T} \frac{(\theta - \theta')^{2\gamma}}{(\theta')^{2\gamma}} \theta^{2H-1-2\gamma} (t-\theta)^2 H-1-2\gamma,$$

for some constant $C_{H,T} > 0$ depending only on $H$ and $T$.

Thus

$$\int_0^t \int_0^\theta \frac{(K_H(t, \theta) - K_H(t, \theta'))^2}{|\theta - \theta'|^{1+2\beta}} d\theta' d\theta \leq C \int_0^t \int_0^\theta \frac{|\theta - \theta'|^{-1-2\beta+2\gamma}}{\theta^{2H-1-2\gamma}} \theta^{2H-1-2\gamma} (t-\theta)^2 H-1-2\gamma d\theta' d\theta$$

$$= C \int_0^t \int_0^\theta \theta^{2H-1-4\gamma} (t-\theta)^2 H-1-2\gamma \int_0^\theta |\theta - \theta'|^{-1-2\beta+2\gamma} (\theta')^{-2\gamma} d\theta' d\theta$$

$$= C \int_0^t \int_0^\theta \theta^{2H-1-4\gamma} (t-\theta)^2 H-1-2\gamma \frac{\Gamma(-2\beta + 2\gamma) \Gamma(-2\gamma + 1)}{\Gamma(-2\beta + 1)} \theta^{-2\beta} d\theta$$

$$\leq C \int_0^t \theta^{2H-1-4\gamma - 2\beta} (t-\theta)^2 H-1-2\gamma d\theta$$

$$= C \frac{\Gamma(2H - 2\gamma) \Gamma(2H - 4\gamma - 2\beta)}{\Gamma(4H - 6\gamma - 2\beta)} t^{4H-6\gamma-2\beta-1} < \infty,$$

for appropriately chosen small $\gamma$ and $\beta$.

On the other hand, we have that

$$\int_0^t \int_0^\theta \frac{(K_H(t, \theta) - K_H(t, \theta'))^2}{|\theta - \theta'|^{1+2\beta}} d\theta' d\theta \leq C \int_0^t \int_0^\theta \theta^{2H-1-4\gamma} (t-\theta)^2 H-1-2\gamma \int_0^\theta |\theta - \theta'|^{-1-2\beta+2\gamma} (\theta')^{-2\gamma} d\theta' d\theta$$

$$\leq C \int_0^t \int_0^\theta \theta^{2H-1-6\gamma} (t-\theta)^2 H-1-2\gamma \int_0^\theta |\theta - \theta'|^{-1-2\beta+2\gamma} d\theta' d\theta$$

$$= C \int_0^t \theta^{2H-1-6\gamma} (t-\theta)^2 H-1-2\gamma d\theta$$

$$\leq C t^{4H-6\gamma-2\beta-1}.$$

Hence

$$\int_0^t \int_0^\theta \frac{(K_H(t, \theta) - K_H(t, \theta'))^2}{|\theta - \theta'|^{1+2\beta}} d\theta' d\theta < \infty.$$
Lemma A.5 Let $H \in (0, 1/2)$, $\theta, t \in [0, T]$, $\theta < t$ and $(\varepsilon_1, \ldots, \varepsilon_m) \in [0, 1]^m$ be fixed. Assume $w_j + (H - 1/2 - \gamma) \varepsilon_j > -1$ for all $j = 1, \ldots, m$. Then exists a finite constant $C = C(H, T) > 0$ such that

$$\int_{\Delta_{\varepsilon_1, \varepsilon_2, \ldots, \varepsilon_m}^m} \prod_{j=1}^m (K_H(s_j, \theta) - K_H(s_j, \theta'))^{\varepsilon_j} |s_j - s_{j-1}|^{w_j} ds$$

$$\leq C^m \left( \frac{\theta - \theta'}{\theta \theta'} \right)^\gamma \sum_{j=1}^m \theta \left( H - \frac{1}{2} - \gamma \right) \sum_{j=1}^m \varepsilon_j \prod_{j=1}^m (t - \theta)' \sum_{j=1}^m w_j + \left( H - \frac{1}{2} - \gamma \right) \sum_{j=1}^m \varepsilon_j + m$$

for $\gamma \in (0, H)$, where

$$\Pi_{\gamma}(m) := \prod_{j=1}^{m-1} \frac{\Gamma \left( \sum_{l=1}^j w_l + (H - \frac{1}{2} - \gamma) \sum_{l=1}^{j-1} \varepsilon_l + j \right) \Gamma \left( w_{j+1} + 1 \right)}{\Gamma \left( \sum_{l=1}^j w_l + (H - \frac{1}{2} - \gamma) \sum_{l=1}^{j-1} \varepsilon_l + j + 1 \right)}.$$

Observe that if $\varepsilon_j = 0$ for all $j = 1, \ldots, m$ we obtain the classical formula.

Remark A.6 Observe that

$$\Pi_{\gamma}(m) \leq \prod_{j=1}^m \frac{\Gamma(w_j + 1)}{\Gamma \left( \sum_{j=1}^m w_j + (H - \frac{1}{2} - \gamma) \sum_{j=1}^{m-1} \varepsilon_j + m \right)} \leq \frac{\prod_{j=1}^m \Gamma(w_j + 1)}{\Gamma \left( \sum_{j=1}^m w_j + (H - \frac{1}{2} - \gamma) \sum_{j=1}^{m-1} \varepsilon_j + m \right)},$$

since the function $\Gamma$ is increasing on $(1, \infty)$.

Proof First, we recall the following well-known formula: for given exponents $a, b > -1$ and some fixed $s_{j+1} > s_j$ we have

$$\int_{\theta}^{s_{j+1}} (s_{j+1} - s_j)^a (s_j - \theta)^b ds_j = \frac{\Gamma(a + 1) \Gamma(b + 1)}{\Gamma(a + b + 2)} (s_{j+1} - \theta)^{a+b+1}.$$

We recall from Lemma A.1 that for every $\gamma \in (0, H)$, $0 < \theta' < \theta < s_j < T$,

$$K_H(s_j, \theta) - K_H(s_j, \theta') \leq C_{H,T} \frac{(\theta - \theta')^\gamma}{(\theta \theta')^\gamma} \theta^{H - \frac{1}{2} - \gamma} (s_j - \theta)^{H - \frac{1}{2} - \gamma},$$

for some constant $C_{H,T} > 0$ depending only on $H$ and $T$. In view of the above arguments we have

$$\int_{\theta}^{s_1} |K_H(s_1, \theta) - K_H(s_1, \theta')|^{\varepsilon_1} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1} ds_1$$

$$\leq C_{\varepsilon_1} \frac{(\theta - \theta')^{\gamma \varepsilon_1}}{(\theta \theta')^{\gamma \varepsilon_1}} \theta^{H - \frac{1}{2} - \gamma} \varepsilon_1 \int_{\theta}^{s_2} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1} \left( H - \frac{1}{2} - \gamma \right) \varepsilon_1 ds_1$$

$$= C_{\varepsilon_1} \frac{(\theta - \theta')^{\gamma \varepsilon_1}}{(\theta \theta')^{\gamma \varepsilon_1}} \theta^{H - \frac{1}{2} - \gamma} \varepsilon_1 \Gamma \left( \hat{w}_1 \right) \Gamma \left( \hat{w}_2 \right) (s_2 - \theta)^{w_1 + w_2 + \left( H - \frac{1}{2} - \gamma \right) \varepsilon_1 + 1},$$

where

$$\hat{w}_1 := w_1 + \left( H - \frac{1}{2} - \gamma \right) \varepsilon_1 + 1, \quad \hat{w}_2 := w_2 + 1.$$ 

Integrating iteratively we obtain the desired formula. \qed
Finally, we give a similar estimate which is used in Lemma 4.7.

**Lemma A.7** Let $H \in (0, 1/2)$, $\theta, t \in [0, T]$, $\theta < t$ and $(\varepsilon_1, \ldots, \varepsilon_m) \in \{0, 1\}^m$ be fixed. Assume $w_j + (H - \frac{1}{2}) \varepsilon_j > -1$ for all $j = 1, \ldots, m$. Then exists a finite constant $C > 0$ such that

$$
\int_{\Delta_{\theta, t}} \prod_{j=1}^m (K_H(s_j, \theta))^{\varepsilon_j} |s_j - s_{j-1}|^{w_j} ds 
\leq C^m \theta^{(H - \frac{1}{2}) \sum_{j=1}^m \varepsilon_j} \Pi_0(m) (t - \theta)^{\sum_{j=1}^m w_j + (H - \frac{1}{2}) \sum_{j=1}^m \varepsilon_j + m}
$$

for $\gamma \in (0, H)$, where $\Pi_0$ is given as in (A.2). Observe that if $\varepsilon_j = 0$ for all $j = 1, \ldots, m$ we obtain the classical formula.

**Remark A.8** Observe that

$$
\Pi_0(m) \leq \frac{\prod_{j=1}^m \Gamma(w_j + 1)}{\Gamma\left(\sum_{j=1}^m w_j + (H - \frac{1}{2}) \sum_{j=1}^m \varepsilon_j + m\right)},
$$

due to the fact that $\Gamma$ is increasing on $(1, \infty)$.

**Proof** By similar arguments as in the proof of Lemma A.1 it is easy to derive the following estimate

$$
|K_H(s_j, \theta)| \leq C_{H,T} |s_j - \theta|^{H - \frac{1}{2}} \theta^{H - \frac{1}{2}}
$$

for every $0 < \theta < s_j < T$ and some constant $C_{H,T} > 0$. This implies

$$
\int_{\theta}^{s_2} (K_H(s_1, \theta))^{\varepsilon_1} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1} ds_1
\leq C_{H,T} \theta^{(H - \frac{1}{2}) \varepsilon_1} \int_{\theta}^{s_2} |s_2 - s_1|^{w_2} |s_1 - \theta|^{w_1 + (H - \frac{1}{2}) \varepsilon_1} ds_1
= C_{H,T} \theta^{(H - \frac{1}{2}) \varepsilon_1} \frac{\Gamma\left(w_1 + w_2 + (H - \frac{1}{2}) \varepsilon_1 + 1\right) \Gamma\left(w_2 + 1\right)}{\Gamma\left(w_1 + w_2 + (H - \frac{1}{2}) \varepsilon_1 + 2\right)} (s_2 - \theta)^{w_1 + w_2 + (H - \frac{1}{2}) \varepsilon_1 + 1}
$$

Integrating iteratively one obtains the desired estimate. □

The next auxiliary result can be found in [31].

**Lemma A.9** Assume that $X_1, \ldots, X_n$ are real centered jointly Gaussian random variables, and $\Sigma = (E[X_j X_k])_{1 \leq j, k \leq n}$ is the covariance matrix, then

$$
E[|X_1| \ldots |X_n|] \leq \sqrt{\text{perm}(\Sigma)},
$$

where $\text{perm}(A)$ is the permanent of a matrix $A = (a_{ij})_{1 \leq i, j \leq n}$ defined by

$$
\text{perm}(A) = \sum_{\pi \in S_n} \prod_{j=1}^n a_{j, \pi(j)}
$$

for the symmetric group $S_n$.

The next result corresponds to Lemma 3.19 in [13]:

Springer
Lemma A.10 Let $Z_1, \ldots, Z_n$ be mean zero Gaussian variables which are linearly independent. Then for any measurable function $g : \mathbb{R} \to \mathbb{R}_+$ we have that
\[
\int_{\mathbb{R}^n} g(v_1) \exp \left( -\frac{1}{2} \text{Var} \left[ \sum_{j=1}^n v_j Z_j \right] \right) dv_1 \ldots dv_n
\]
\[
= \frac{(2\pi)^{(n-1)/2}}{(\det \text{Cov}(Z_1, \ldots, Z_n))^{1/2}} \int_{\mathbb{R}} g \left( \frac{v}{\sigma_1} \right) \exp \left( -\frac{1}{2} \frac{v^2}{\sigma_1^2} \right) dv,
\]
where $\sigma_1^2 := \text{Var}[Z_1 | Z_2, \ldots, Z_n]$.

Lemma A.11 Let $n$, $p$ and $k$ be non-negative integers, $k \leq n$. Assume we have functions $f_j : [0, T] \to \mathbb{R}$, $j = 1, \ldots, n$ and $g_i : [0, T] \to \mathbb{R}$, $i = 1, \ldots, p$ such that
\[
f_j \in \left\{ \frac{\partial^\alpha_j}{\partial x_1^{\alpha_j(1)} \ldots \partial x_d^{\alpha_j(d)}} b^{(r)}(u, X_u^x), \quad r = 1, \ldots, d \right\}, \quad j = 1, \ldots, n
\]
and
\[
g_i \in \left\{ \frac{\partial^\beta_i}{\partial x_1^{\beta_i(1)} \ldots \partial x_d^{\beta_i(d)}} b^{(r)}(u, X_u^x), \quad r = 1, \ldots, d \right\}, \quad i = 1, \ldots, p
\]
for $\alpha := (\alpha_j^{(l)}) \in \mathbb{N}_0^{d \times n}$ and $\beta := (\beta_i^{(l)}) \in \mathbb{N}_0^{d \times p}$, where $X^x$ is the strong solution to
\[
X_t^x = x + \int_0^t b(u,X_u^x) du + B_t^H, \quad 0 \leq t \leq T
\]
for $b = (b^{(1)}, \ldots, b^{(d)})$ with $b^{(r)} \in S(\mathbb{R}^d)$ for all $r = 1, \ldots, d$. So (as we shall say in the sequel) the product $g_1(r_1) \cdots g_p(r_p)$ has a total order of derivatives $|\beta| = \sum_{i=1}^p \sum_{l=1}^d \beta_i^{(l)}$. We know from Lemma 2.1 that
\[
\int_{\Delta_{n,t}^\theta} f_1(s_1) \ldots f_k(s_k) \int_{\Delta_{p,s_k}^\theta} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 f_{k+1}(s_{k+1}) \ldots f_n(s_n) ds_n \ldots ds_1
\]
\[
= \sum_{\sigma \in \Lambda_{n,p}} \int_{\Delta_{n+p}^\theta} h_{\sigma,1}(w_1) \cdots h_{n+p}^\sigma (w_{n+p}) dw_{n+p} \ldots dw_1,
\]
where $h_{\sigma,1} \in \{ f_j, g_i : 1 \leq j \leq n, 1 \leq i \leq p \}$, $\Lambda_{n,p}$ is a subset of permutations of $\{1, \ldots, n + p\}$ such that $\#\Lambda_{n,p} \leq C^{n+p}$ for an appropriate constant $C \geq 1$, and $s_0 = \theta$. Then the products
\[
h_{\sigma,1}^\sigma (w_1) \cdots h_{n+p}^\sigma (w_{n+p})
\]
have a total order of derivatives given by $|\alpha| + |\beta|$.

Proof The result is proved by induction on $n$. For $n = 1$ and $k = 0$ the result is trivial. For $k = 1$ we have
\[
\int_0^t f_1(s_1) \int_{\Delta_{p,s_1}^\theta} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 ds_1
\]
\[
= \int_{\Delta_{p+1}^\theta} f_1(w_1) g_1(w_2) \ldots g_p(w_{p+1}) dw_{p+1} \ldots dw_1,
\]
where we have put \( w_1 = s_1, w_2 = r_1, \ldots, w_{p+1} = r_p \). Hence the total order of derivatives involved in the product of the last integral is given by \( \sum_{l=1}^{d} \alpha^{(l)}_i + \sum_{l=1}^{d} \sum_{i=1}^{p} \beta^{(l)}_i = |\alpha| + |\beta| \).

Assume the result holds for \( n \) and let us show that this implies that the result is true for \( n + 1 \). Either \( k = 0, 1 \) or \( 2 \leq k \leq n + 1 \). For \( k = 0 \) the result is trivial. For \( k = 1 \) we have

\[
\int_{\Delta_{n+1}^0} f_1(s_1) \int_{\Delta_{p}^0} f_k(s_k) g_1(r_1) ds_1 \ldots g_p(r_p) dr_p \ldots dr_1 f_2(s_2) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_1
\]

\[
= \int_{\theta}^l f_1(s_1) \int_{\Delta_{n+1}^0} f_2(s_2) \ldots f_k(s_k) g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1
\]

\[
\times f_{k+1}(s_{k+1}) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_2 ds_1
\]

\[
= \sum_{\sigma \in A_{n+1,p}} \int_{\theta}^l f_1(s_1) \int_{\Delta_{n+1}^0} h_1^\sigma(w_1) \ldots h_n^\sigma(w_{n+p}) dw_{n+p} \ldots dw_1 ds_1.
\]

From (2.1) we observe by using the shuffle permutations that the latter inner double integral on diagonals can be written as a sum of integrals on diagonals of length \( p + n \) with products having a total order of derivatives given by \( \sum_{l=1}^{d} \sum_{j=2}^{n+1} \alpha^{(l)}_j + \sum_{l=1}^{d} \sum_{i=1}^{p} \beta^{(l)}_i \). Hence we obtain a sum of products, whose total order of derivatives is \( \sum_{l=1}^{d} n^{(l)} + \sum_{l=1}^{d} \sum_{i=1}^{p} \beta^{(l)}_i + \sum_{l=1}^{d} \alpha^{(l)}_1 = |\alpha| + |\beta| \).

For \( k \geq 2 \) we have (in connection with Lemma 2.1) from the induction hypothesis that

\[
\int_{\Delta_{n+1}^0} f_1(s_1) \ldots f_k(s_k) \int_{\Delta_{p}^0} g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1 f_{k+1}(s_{k+1}) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_1
\]

\[
= \int_{\theta}^l f_1(s_1) \int_{\Delta_{n+1}^0} f_2(s_2) \ldots f_k(s_k) g_1(r_1) \ldots g_p(r_p) dr_p \ldots dr_1
\]

\[
\times f_{k+1}(s_{k+1}) \ldots f_{n+1}(s_{n+1}) ds_{n+1} \ldots ds_2 ds_1
\]

\[
= \sum_{\sigma \in A_{n+1,p}} \int_{\theta}^l f_1(s_1) \int_{\Delta_{n+1}^0} h_1^\sigma(w_1) \ldots h_n^\sigma(w_{n+p}) dw_{n+p} \ldots dw_1 ds_1.
\]

where each of the products \( h_1^\sigma(w_1) \ldots h_n^\sigma(w_{n+p}) \) have a total order of derivatives given by

\[
\sum_{l=1}^{d} \sum_{j=2}^{n+1} \alpha^{(l)}_j + \sum_{l=1}^{d} \sum_{i=1}^{p} \beta^{(l)}_i.
\]

Thus we get a sum with respect to a set of permutations \( A_{n+1,p} \) with products having a total order of derivatives which is

\[
\sum_{l=1}^{d} n^{(l)} + \sum_{l=1}^{d} \sum_{i=1}^{p} \beta^{(l)}_i + \sum_{l=1}^{d} \alpha^{(l)}_1 = |\alpha| + |\beta|.
\]

References

1. Alòs, E., Mazet, O., Nualart, D.: Stochastic calculus with respect to Gaussian processes. Ann. Probab. 29(3), 766–801 (2001)
2. Ambrosio, L.: Transport equation and Cauchy problem for BV vector fields. Invent. Math. 158, 227–260 (2004)
3. Amine, O., Baños, D., Proske, F.: Regularity properties of the stochastic flow of a skew fractional Brownian motion. arXiv:1805.04889v1 (2018)
4. Amine, O., Coffie, E., Harang, F., Proske, F.: A Bismut–Elworthy–Li formula for singular SDE’s driven by a fractional Brownian motion and applications to rough volatility modeling. arXiv:1805.11435v1 [math.PR] (2018)
5. Anari, N., Gurvits, L., Gharan, S., Saberi, A.: Simply exponential approximation of the permanent of positive semidefinite matrices. In: 58th Annual IEEE Symposium on Foundations of Computer Science (2017)

6. Baños, D., Ortiz-Latorre, S., Pilipenko, A., Proske, F.: Strong solutions of SDE's with generalized drift and multidimensional fractional Brownian initial noise. arXiv:1705.01616v2 [math.PR] (2018)

7. Bass, R., Chen, Z.-Q.: Brownian motion with singular drift. Ann. Probab. 31(2), 791–817 (2003)

8. Butkovski, O., Mytnik, L.: Regularization by noise and flows for a stochastic heat equation. arXiv:1610.02553 (2016)

9. Catellier, R.: Perturbations Irréguilières et Systèmes Différentiels Rugueux. Ph.D. Thesis, University of Paris Dauphine (Sept. 2014)

10. Catellier, R., Gubinelli, M.: Averaging along irregular curves and regularisation of ODE's. Stoch. Process. Appl. 126(8), 2323–2366 (2016)

11. Chouk, K., Gubinelli, M.: Nonlinear PDE's with modulated dispersion I: nonlinear Schrödinger equations. Commun. Partial Differ. Equ. 40(11), 2047–2081 (2015)

12. Chouk, K., Gubinelli, M.: Nonlinear PDE's with modulated dispersion II: Korteweg–de Vries equation. arXiv:1406.7675 (2014)

13. Cuzick, J., DuPreez, P.: Joint continuity of Gaussian local times. Ann. Probab. 10(3), 810–817 (1982)

14. Da Prato, G., Flandoli, F., Priola, E., Röckner, M.: Strong uniqueness for stochastic evolution equations in Hilbert spaces with bounded and measurable drift. Ann. Probab. 41(5), 3306–3344 (2013)

15. Da Prato, G., Malliavin, P., Nualart, D.: Compact families of Wiener functionals. C. R. Acad. Sci. Paris 315(Série I), 1287–1291 (1992)

16. Davie, A.M.: Uniqueness of solutions of stochastic differential equations. In: International Mathematics Research Notices, vol. 2007 (2007)

17. Decreusefond, L., Üstünel, A.S.: Stochastic analysis of the fractional Brownian motion. Potential Anal. 10, 177–214 (1998)

18. Di Nunno, G., Øksendal, B., Proske, F.: Malliavin Calculus for Lévy Processes with Applications to Finance. Springer, Berlin (2008)

19. DiPerna, R.J., Lions, P.L.: Ordinary differential equations, transport theory and Sobolev spaces. Invent. Math. 98, 511–547 (1989)

20. Fedrizzi, E., Flandoli, F.: Noise prevents singularities in linear transport equations. J. Funct. Anal. 264(6), 1329–1354 (2013)

21. Geman, D., Horowitz, J.: Occupation densities. Ann. Probab. 8(1), 1–67 (1980)

22. Gyöngy, I., Krylov, N.V.: Existence of strong solutions for Itô’s stochastic equations via approximations. Probab. Theory Relat. Fields 105, 143–158 (1996)

23. Gyöngy, I., Martinez, T.: On stochastic differential equations with locally unbounded drift. Czechoslov. Math. J. 51(4), 763–783 (2001)

24. Haadem, S., Proske, F.: On the construction and Malliavin differentiability of solutions of Lévy noise driven SDE's with singular coefficients. J. Funct. Anal. 266(8), 5321–5359 (2014)

25. Hu, Y., Khoa, L., Mytnik, L.: Stochastic differential equations for Brox diffusion. Stoch. Process. Appl. 127(7), 2281–2315 (2017)

26. Karatzas, I., Shreve, S.E.: Brownian Motion and Stochastic Calculus, 2nd edn. Springer, Berlin (1998)

27. Kunita, H.: Stochastic Flows and Stochastic Differential Equations. Cambridge University Press, Cambridge (1990)

28. Li, W., Wei, A.: A Gaussian inequality for expected absolute products. J. Theor. Probab. 25(1), 92–99 (2012)

29. Lizorkin, P.I.: Fractional Integration and Differentiation, Encyclopedia of Mathematics. Springer, Berlin (2001)

30. Lyons, T.J., Caruana, M., Lévy, T.: Differential equations driven by rough paths. École d’Été de Probabilités de Saint-Flour XXXIV–2004

31. Malliavin, P.: Stochastic calculus of variations and hypoelliptic operators. In: Proceedings of International Symposium on Stochastic Differential Equations, Kyoto 1976, pp. 195–263. Wiley, London (1978)

32. Malliavin, P.: Stochastic Analysis. Springer, Berlin (1997)
36. Menoukeu-Pamen, O., Meyer-Brandis, T., Nilssen, T., Proske, F., Zhang, T.: A variational approach to the construction and Malliavin differentiability of strong solutions of SDE’s. Math. Ann. 357(2), 761–799 (2013)
37. Meyer-Brandis, T., Proske, F.: Construction of strong solutions of SDE’s via Malliavin calculus. J. Funct. Anal. 258, 3922–3953 (2010)
38. Mohammed, S.E.A., Nilssen, T., Proske, F.: Sobolev differentiable stochastic flows for SDE’s with singular coefficients: applications to the transport equation. Ann. Probab. 43(3), 1535–1576 (2015)
39. Nilssen, T.: Quasi-linear stochastic partial differential equations with irregular coefficients-Malliavin regularity of the solutions. Stoch. Partial Differ. Equ. Anal. Comput. 3(3), 339–359 (2015)
40. Nilssen, T.: Rough linear PDE’s with discontinuous coefficients-existence of solutions via regularization by fractional Brownian motion. arXiv:1509.01154v3 (2018)
41. Nualart, D., Ouknine, Y.: Regularization of differential equations by fractional noise. Stoch. Process. Appl. 102(1), 103–116 (2002)
42. Nualart, D., Ouknine, Y.: Stochastic differential equations with additive fractional noise and locally unbounded drift. In: Stochastic Inequalities and Applications, Volume 56 of the Series Progress in Probability, pp. 353–365 (2003)
43. Nualart, D.: The Malliavin Calculus and Related Topics, 2nd edn. Springer, Berlin (2010)
44. Pitt, L.D.: Local times for Gaussian vector fields. Indiana Univ. Math. J. 27, 309–330 (1978)
45. Revuz, D., Yor, M.: Continuous Martingales and Brownian Motion, 3rd edn. Springer, Berlin (1999)
46. Rezakhanlou, F.: Regular flows for diffusions with rough drifts. arXiv:1405.5856v1 [math.PR] (2014)
47. Samko, S.G., Kilbas, A.A., Marichev, O.L.: Fractional Integrals and Derivatives, Theory and Applications. Gordon and Breach, New York (1993)
48. Veretennikov, A.Y.: On the strong solutions of stochastic differential equations. Theory Probab. Appl. 24, 354–366 (1979)
49. Xiao, Y.X.: Fractal and smoothness properties of space–time Gaussian models. Front. Math. China 6, 1217–1248 (2011)
50. Yamada, T., Watanabe, S.: On the uniqueness of solutions of stochastic differential equations. J. Math. Kyoto Univ. I 1, 155–167 (1971)
51. Zvonkin, A.K.: A transformation of the state space of a diffusion process that removes the drift. Math. USSR (Sbornik) 22, 129–149 (1974)

Publisher’s Note Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.