Abstract—We design new continuous phase modulation (CPM) formats which are based on the combination of a proper precoder with binary input and a ternary CPM. The proposed precoder constrains the signal phase evolution in order to increase the minimum Euclidean distance, and to limit the bandwidth expansion due to the use of a ternary CPM. The resulting schemes are highly spectrally efficient and outperform classical binary and quaternary CPMs in terms of coded and uncoded performance.

Index Terms—Continuous phase modulation, spectral efficiency, precoding.

I. INTRODUCTION

Continuous phase modulations (CPMs) are advanced modulation formats which are often employed in satellite communications thanks to their immunity against nonlinear distortions, stemming from the constant envelope, their claimed power and spectral efficiency, and their recursive nature which allows to employ them in serially concatenated schemes. CPMs have been included in the DVB-RCS2 standard [1], with the aim of enabling the use of cheaper amplifier components in modems, and hence lower cost terminals.

The spectral efficiency (SE) is one of the main figures of merit for satellite communications. In this letter, we design new binary schemes with a much larger SE than classical CPMs. They are based on the combination of a proper precoder with binary input and a ternary CPM format.

The use of a precoder in conjunction with a CPM modulator is rarely considered in the literature. To our knowledge, it has been recently investigated to improve the robustness of classical binary CPMs to a modulation index mismatch in [2] and to have a simple (albeit suboptimal) symbol-by-symbol detection architecture in shaped-offset quadrature phase-shift keying (SOQPSK) modulation [3]. In [4], an improved multi-h CPM is proposed which increases the minimum Euclidean distance of binary CPMs but without taking care of the bandwidth. The state transitions of the phase trellis are controlled by employing a set of modulation indexes in the same symbol interval, depending on the information symbol to be transmitted.

This paper is organized as follows. In Section II we introduce the system model. The proposed schemes and the corresponding detectors are described in Section III. Numerical results are reported in Section IV where we show how the proposed schemes outperform binary and quaternary CPMs both in terms of uncoded performance and SE. Finally, conclusions are drawn in Section V.

II. SYSTEM MODEL

The complex envelope of a CPM signal can be written as

\[ s(t, a) = \sqrt{\frac{E_b}{T}} \exp \left\{ j2\pi h \sum_n a_n q(t - nT) \right\}, \]

where \( E_b \) is the average energy per information symbol, \( T \) the symbol interval, \( h = r/p \) the modulation index (\( r \) and \( p \) are relatively prime integers), \( q(t) \) is the phase-smoothing response, and its derivative is the frequency pulse, assumed of duration \( LT \) and area 1/2. The symbols \( a \) take on values in the alphabet \( \{ \pm 1, \pm 3, \ldots, \pm (M - 1) \} \) if \( M \) is even, and in the alphabet \( \{ 0, \pm 2, \pm 4, \ldots, \pm (M - 1) \} \) if \( M \) is odd.

In the generic time interval \([nT, nT + T]\), the CPM signal is completely defined by symbol \( a_n \) and state \( \sigma_n = (\omega_n, \theta_n) \) [5], where

\[ \omega_n = (a_{n-1}, a_{n-2}, \ldots, a_{n-L+1}) \]

is the correlative state and \( \theta_n \) is the phase state which takes on values evenly spaced around the unit circle, and can be recursively defined as

\[ \theta_n = [\theta_{n-1} + \pi h a_{n-L+1}]_{2\pi}, \]

where \([\cdot]_{2\pi}\) denotes the "modulo 2\(\pi\)" operator.

Our aim is to improve the SE of classical binary CPM schemes through the design of a suitable precoder. A classical binary CPM modulator, can be represented as depicted in Fig. 1(a). Information bits \( \{ b_n \} \), belonging to the alphabet \( \{ 0, 1 \} \), are directly mapped into symbols \( \{ a_n \} \) belonging to the alphabet \( \{ \pm 1 \} \), and then go at the input of a binary CPM modulator. The scheme proposed in this paper is instead based on the combination of a precoder, which receives at its input the alphabet \( \{ 0, \pm 2 \} \), and a ternary CPM. This precoded scheme is shown in Fig. 1(b).

We consider a transmission over an additive white Gaussian noise (AWGN) channel. The complex envelope of the received signal thus reads

\[ r(t) = s(t, a) + w(t), \]

where \( w(t) \) is a complex-valued white Gaussian noise process with independent components, each with two-sided power spectral density \( N_0/2 \).
closely related to the IR. Furthermore, the proposed scheme with the increase of lobe is related to the phase hopping that becomes important based on the observation that the width of the main spectral use of a ternary modulation instead of a binary one. This is of the minimum Euclidean distance, which dominates the complexity of the detection algorithm.

and does not guarantees an overall improvement of the SE. size, but this results in an expansion of the spectrum occupancy the effect of the precoding on the bandwidth occupancy. of time and per unity of bandwidth, we are also considering the SE, i.e., the amount of information transmitted per unity I

\[ \text{SE} = \frac{I}{BT} \quad \text{[bit/s/Hz]}, \]  

where \( I \) is the information rate (IR), i.e., the amount of information transmitted per channel use, and \( B \) is the bandwidth occupied by the transmitted signal. This normalization is required to capture the different bandwidth occupancy of different modulation formats. In other words, by considering the SE, i.e., the amount of information transmitted per unity of time and per unity of bandwidth, we are also considering the effect of the precoding on the bandwidth occupancy.

A simple way to increase the IR is to increase the alphabet size, but this results in an expansion of the spectrum occupancy and does not guarantees an overall improvement of the SE. Moreover, this leads to an increase in the computational complexity of the detection algorithm.

The design of the proposed precoder is based on the increase of the minimum Euclidean distance, which dominates the performance at high signal-to-noise ratio (SNR) and is hence closely related to the IR. Furthermore, the proposed scheme is also able to limit the spectral occupancy increase due to the use of a ternary modulation instead of a binary one. This is based on the observation that the width of the main spectral lobe is related to the phase hopping that becomes important with the increase of \( M \) or \( h \) \[6\]. In the case of ternary CPMs, this spectral widening is mainly due to the transitions from 2 to -2 and vice versa. In summary, the challenge is to design a precoder in such a way to ensure simultaneously:

- an increase of the minimum distance (in order to increase the IR);
- the absence of transitions from 2 to -2 and vice versa (in order to limit the bandwidth expansion).

To design a precoder which increases the minimum Euclidean distance, we consider the upper bound given by the distance between paths in the phase tree which have a common starting phase and have a merge after a finite number of time intervals \[6\]. The idea is to design a precoder which can delay the first inevitable merge. This is the same principle used for the multi-\( h \) CPMs \[3, 7\].

The joint phase tree of the precoder/modulator is time varying and we denote by \( \varphi_n \) the phase state in the \( n \)th symbol interval and by \( \varphi_n(i) \) the \( i \)th value that it can assume.\[1\] We introduce the proposed precoded CPM with an example.

\[ \begin{align*}
\text{Mapper} & \quad 0 \rightarrow -1 \\
& \quad 1 \rightarrow 1 \\
\text{Precoder} & \quad a_n \\
\text{Binary} & \quad \text{CPM} \\
\text{Modulator} & \quad \text{s}(t, a) \\
\text{Ternary} & \quad \text{CPM} \\
\text{Modulator} & \quad \text{s}(t, a)
\end{align*} \]

Fig. 1. Compared schemes. (a) Classical binary CPM. (b) Proposed scheme.

III. PROPOSED PRECODER AND CORRESPONDING DETECTOR

The SE is defined as

\[ \text{SE} = \frac{I}{BT} \quad \text{[bit/s/Hz]}, \]  

where \( I \) is the information rate (IR), i.e., the amount of information transmitted per channel use, and \( B \) is the bandwidth occupied by the transmitted signal. This normalization is required to capture the different bandwidth occupancy of different modulation formats. In other words, by considering the SE, i.e., the amount of information transmitted per unity of time and per unity of bandwidth, we are also considering the effect of the precoding on the bandwidth occupancy.

A simple way to increase the IR is to increase the alphabet size, but this results in an expansion of the spectrum occupancy and does not guarantees an overall improvement of the SE. Moreover, this leads to an increase in the computational complexity of the detection algorithm.

The design of the proposed precoder is based on the increase of the minimum Euclidean distance, which dominates the performance at high signal-to-noise ratio (SNR) and is hence closely related to the IR. Furthermore, the proposed scheme is also able to limit the spectral occupancy increase due to the use of a ternary modulation instead of a binary one. This is based on the observation that the width of the main spectral lobe is related to the phase hopping that becomes important with the increase of \( M \) or \( h \) \[6\]. In the case of ternary CPMs, this spectral widening is mainly due to the transitions from 2 to -2 and vice versa. In summary, the challenge is to design a precoder in such a way to ensure simultaneously:

- an increase of the minimum distance (in order to increase the IR);
- the absence of transitions from 2 to -2 and vice versa (in order to limit the bandwidth expansion).

To design a precoder which increases the minimum Euclidean distance, we consider the upper bound given by the distance between paths in the phase tree which have a common starting phase and have a merge after a finite number of time intervals \[6\]. The idea is to design a precoder which can delay the first inevitable merge. This is the same principle used for the multi-\( h \) CPMs \[3, 7\].

The joint phase tree of the precoder/modulator is time varying and we denote by \( \varphi_n \) the phase state in the \( n \)th symbol interval and by \( \varphi_n(i) \) the \( i \)th value that it can assume.\[1\] We introduce the proposed precoded CPM with an example.

\[ \begin{align*}
\text{Mapper} & \quad 0 \rightarrow -1 \\
& \quad 1 \rightarrow 1 \\
\text{Precoder} & \quad a_n \\
\text{Binary} & \quad \text{CPM} \\
\text{Modulator} & \quad \text{s}(t, a) \\
\text{Ternary} & \quad \text{CPM} \\
\text{Modulator} & \quad \text{s}(t, a)
\end{align*} \]

Fig. 1. Compared schemes. (a) Classical binary CPM. (b) Proposed scheme.

We consider the phase tree for a CPM with \( h = \frac{1}{4} \) and rectangular (REC) frequency pulse with \( L = 1 \) (full response), which includes the phase state values \( \{0, \pi/2, \pi, 3\pi/2\} \), and is shown in Fig. 2. From each state, we have two branches corresponding to the bits “0” and “1”. The bit “0” is encoded as 0, whereas the bit “1” is encoded as 2 or -2 based on the following rules:

- two adjacent states \( \varphi_n(i) \) and \( \varphi_n(i+1) \) should have different encoding of the bit “1” (in order to delay the first merge);
- also the two successive states \( \varphi_n(i) \) and \( \varphi_{n+1}(i) \) should have different encoding of the bit “1” (to avoid the alternation 2 → -2 and vice versa, which imply phase transitions causing a bandwidth expansion).

With this construction, at each time instant \( t = nT > (L+1)T \) all phase values in the tree are possible, but for every phase state the encoding of the bit “1” in the even-numbered symbol intervals is different from that in the odd-numbered symbol intervals. In this sense the tree is time-varying.

In order to derive the precoder equation, we now consider a possible path in the trellis: at the time instant \( t = nT \) the bit “0” is encoded as “0”, while the encoding of the bit “1” depends on the encoding of the previous “1” and on the number of time intervals \( d \) that are between them. The following precoder satisfies the required constraints for all values of \( p > 2 \) and \( L \):

\[ a_n = b_n a_{n-d} (-1)^{d+1}, \]

where \( b_n \) is the bit transmitted in the symbol interval \( n \) and \( a_{n-d} \) is the latest symbol such that \( |a_{n-d}| = 2 \).

In the considered example, the minimum distance is governed by the error event \( e_{min} = (2, -2) \) of length \( 2T \) for binary CPMs, and by the error event \( \tilde{e}_{min} = (2, 0, -2) \) of length \( 3T \) for the proposed precoded scheme. The multiplicity of the error events with minimum distance is the same in both cases. In general, the first merge in the phase tree occurs at time \( t = (L+1)T \) for the binary CPM case and at time \( t = (L+2)T \) for the proposed scheme when \( p > 2 \).

We now consider the corresponding detection algorithms, which are described by means of the detector phase trellis. In each time interval, although ternary, the transmitted symbol is drawn from one of two binary alphabets \( \{-2, 0\} \) or \( \{0, 2\} \). When \( h \) has an even denominator, the detector trellis can be directly derived from the phase tree, and detection can be performed with the same complexity of the corresponding binary CPM.
When $p$ is odd, the phase evolution at the transmitter can no more be used to derive the detector trellis since we do not have a one-to-one correspondence between the transmitted bit sequences and phase trajectories. The phase evolution for the case of a full response CPM with REC frequency pulse and $h = 1/3$ is shown in Fig. 3. Even if the transmitted symbol is drawn from one of two binary alphabets $\{-2, 0\}$ or $\{0, 2\}$, each state in the phase tree has three outgoing edges: we can not associate a transmitted bit sequence to each phase trajectory. This can be overcome by properly constructing the trellis with an even number of phase states equal to $2p$. For each physical phase state value $\phi \in \{0, 2\pi h, \ldots, (p-1)2\pi h\}$, we introduce $\phi^{(a)}$ and $\phi^{(b)}$ which have different encoding of the bit “1”. Then, for the proposed scheme $\phi_n$ belongs to $\{\phi^{(a)}, 2\pi h^{(a)}, \ldots, 2\pi(p-1)h^{(a)}\}$, where $\phi^{(b)} = \{0^{(b)}, 2\pi h^{(b)}, \ldots, 2\pi(p-1)h^{(b)}\}$. In Fig. 4 we show the detector trellis for the scheme of Fig. 3. For this example, in the first symbol interval the edge going out from the state $0^{(a)}$ encodes the bit “1” as 2, while that from the state $0^{(b)}$ encodes it as $-2$. The role of the two states changes in the following symbol interval. It is worth noticing that the derived trellis satisfies the required constraints on the encoding of the bit “1” between adjacent and successive states.

IV. Simulation Results

In this section, we consider the performance of the proposed scheme, compared to classical binary and quaternary CPMs. We first evaluate the bit error rate (BER) in uncoded transmissions. Then, we consider the performance in terms of SE, which in practice can be achieved by adopting a suitable channel code. Due to lack of space, we limit our results to CPM formats with REC frequency pulse. In particular, we consider frequency pulse of length $T$ (1REC) and $2T$ (2REC).

### A. Uncoded Performance

We consider the uncoded performance of the proposed system in case of transmission over an AWGN channel. Particularly, we evaluate the asymptotic performance for high values of $E_b/N_0$, where $E_b$ is the mean energy per information bit. Let us denote by $e = a - \hat{a}$ the sequence representing the difference between the transmitted sequence $a$ and the erroneous one $\hat{a}$. Without loss of generality, we will assume that any considered error event starts at time $n = 0$. We will also denote the normalized squared Euclidean distance as $d^2(e)$.

$$d^2(e) = \frac{1}{E_b}||s(t, a) - s(t, \hat{a})||^2.$$  

The BER for the optimal maximum a posteriori probability (MAP) sequence detector is well approximated by $P_b \approx \frac{n_{e_{min}}}{\log_2(S)} e_{min}^{e_{min}} \left( \sqrt{d^2_{min}E_b/N_0} \right)$, where $S$ is equal to $M$ for classical CPMs and is equal to 2 for the proposed scheme, $d_{min} = \min_e d(e)$, $e_{min} = \arg\min_e d(e)$, $n_{e_{min}}$ is the number of bit errors (i.e., on the sequence $\{b_n\}$ caused by the error event $e_{min}$, $e_{min} = 2 \prod_{i=0}^{R_{e_{min}}-1} (S - e_{min}/2)$, $R_{e_{min}}$ is the span of symbol times where $e_{min}$ is different from zero and $Q(x)$ is the Gaussian $Q$ function. Now, it only remains to identify the error events corresponding to $d_{min}$. This can be done by working on the phase tree, as described in [6].

For fixed $h$ indexes and frequency pulses, we compute $\phi_n$ for several classical binary and quaternary schemes and for the proposed one. The results are summarized in Table I, where we report $d^2_{min}$ and the gain in dB that the proposed scheme achieves at BER=$10^{-4}$ with respect to the classical formats. The BER simulations, not reported here for a lack of space, confirm the analytic results, and show the large performance gain of the proposed scheme with respect to the classical CPMs for the cases listed in Table I.

### B. Spectral Efficiency

The CPM bandwidth is theoretically infinite because the power spectral density of a CPM signal has rigorously an infinite support. To define the signal bandwidth, we consider a frequency division multiplexed (FDM) system where each user employs a CPM. In order to avoid boundary effects, we assume a system with an infinite number of users which transmit at the same power, employ the same modulation format and are equally spaced in frequency. Under these conditions, the frequency spacing is a measure of the signal bandwidth.
Particularly, we let the user interfere and define the system bandwidth as the frequency separation which maximizes the SE achievable by a single user detector. The reader is referred to [2] for further details on this bandwidth definition.

To compute \( I \) in (2), we can use the simulation-based technique described in [10], which only requires the existence of an optimal MAP symbol detector for the channel (1). This problem is an instance of mismatched detection [11], since we are interested in the computation of the IR when the actual channel is a FDM system with interfering users, while the receiver is a single user receiver which is designed according to the channel (1). The simulation-based method described in [10] allows to evaluate the achievable IR as

\[
I = E \left\{ \log \frac{p(r|a)}{p(r)} \right\}, \quad \text{[bit/ch.use]},
\]

where \( r \) is a suitable vector of sufficient statistics extracted from the continuous-time received signal. In (4), the probability density functions \( p(r|a) \) and \( p(r) \) can be evaluated recursively through the forward recursion of the optimal MAP symbol detection algorithm for the channel (1).

We plot the optimized SE [9] as a function of \( E_b/N_0 \). The performance of the proposed scheme is compared to binary and quaternary CPMs. Fig. 5 shows the SE of a full response CPM format (1REC). It can be observed that the precoded scheme results in higher SEs than the binary CPMs, and compared to the quaternary formats has better performance for \( h = 1/4 \) and the same performance \( h = 1/5 \). The same conclusion is drawn in the case of the 2REC formats considered in Fig. 6. We observe that the proposed scheme performs better than the binary case. Compared to the quaternary CPM formats, it performs better in the case \( h = 2/7 \) and allows to reach the same performance for \( h = 1/5 \). In some cases, the quaternary formats allow to achieve higher asymptotic SE, but the corresponding SNR region has no practical interest.

Finally, we compare the considered schemes in terms of the computational complexity of the corresponding detectors. In the case of classical CPMs, the optimal detector has a computational complexity which is proportional to \( pM^L \), while the optimal detector for the proposed scheme has a complexity proportional to \( p2^L \) if \( p \) is even, and to \( p2^{L+1} \) if \( p \) is odd. Therefore, compared to the binary CPMs, the proposed scheme has the same receiver complexity if \( p \) is even, while the complexity increases in the case of odd values of \( p \). Interestingly, the proposed scheme has always less or equal complexity than the quaternary formats since:

\[
p \times \left( \sum_{l=1} \frac{L}{2} 2^l \right) \leq p \times 4^L, \quad \forall p, \forall L
\]

Prop. sch. compl. \quad Quat. CPM compl.

V. CONCLUSIONS

We proposed a new family of binary formats given by the combination of a precoder with a ternary CPM. The new schemes are very attractive form the SE point of view, achieving better results than classical formats. Moreover, the corresponding detection algorithms have less or equal computational complexity than the quaternary formats.

REFERENCES

[1] Digital Video Broadcasting (DVB), “Second Generation DVB Interactive Satellite System; Part 2: Lower Layers for Satellite standard. DVB Document A155-2,” Mar. 2011.

[2] M. Messai, G. Colavolpe, K. Amis, and F. Guilloud, “Binary continuous phase modulations robust to a modulation index mismatch,” 2015, to be published on IEEE Trans. on Commun.

[3] E. Perrins and M. Rice, “A new performance bound for PAM-based CPM detectors,” IEEE Trans. Comm., vol. 53, no. 10, pp. 1688 – 1696, Oct. 2005.

[4] J. P. Fonseka, “Nonlinear continuous phase frequency shift keying,” IEEE Trans. Comm., vol. 39, no. 10, pp. 1473–1481, Oct. 1991.

[5] B. E. Rimoldi, “A decomposition approach to CPM,” IEEE Trans. Inform. Theory, vol. 34, pp. 260–270, Mar. 1988.

[6] J. B. Anderson, T. Aulin, and C.-E. W. Sundberg, Digital Phase Modulation. New York: Plenum Press, 1986.

[7] T. Aulin and C.-E. W. Sundberg, “On the minimum Euclidean distance for a class of signal space codes,” IEEE Trans. Inform. Theory, vol. 28, no. 1, pp. 43–55, Jan. 1982.

[8] E. Perrins and M. Rice, “A new performance bound for PAM-based CPM detectors,” IEEE Trans. Comm., vol. 53, no. 10, pp. 1688 – 1696, Oct. 2005.

[9] A. Barbieri, D. Fertonani, and G. Colavolpe, “Spectrally-efficient continuous phase modulations,” IEEE Trans. Wireless Comm., vol. 8, pp. 1564–1572, Mar. 2009.

[10] D. M. Arnold, H.-A. Loeliger, P. O. Vontobel, A. Kavčič, and W. Zeng, “Simulation-based computation of information rates for channels with memory,” IEEE Trans. Inform. Theory, vol. 52, no. 8, pp. 3498–3508, Aug. 2006.

[11] N. Merhav, G. Kaplan, A. Lapidoth, and S. Shamai, “On information rates for mismatched decoders,” IEEE Trans. Inform. Theory, vol. 40, no. 6, pp. 1953–1967, Nov. 1994.