Causal Inference for Chatting Handoff

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Abstract

Aiming to ensure chatbot quality by predicting chatbot failure and enabling human-agent collaboration, Machine-Human Chatting Handoff (MHCH) has attracted lots of attention from both industry and academia in recent years. However, most existing methods mainly focus on the dialogue context or assist with global satisfaction prediction based on multi-task learning, which ignore the grounded relationships among the causal variables, like the user state and labor cost. These variables are significantly associated with handoff decisions, resulting in prediction bias and cost increasement. Therefore, we propose Causal-Enhance Module (CEM) by establishing the causal graph of MHCH based on these two variables, which is a simple yet effective module and can be easy to plug into the existing MHCH methods. For the impact of users, we use the user state to correct the prediction bias according to the causal relationship of multi-task. For the labor cost, we train an auxiliary cost simulator to calculate unbiased labor cost through counterfactual learning so that a model becomes cost-aware. Extensive experiments conducted on four real-world benchmarks demonstrate the effectiveness of CEM in generally improving the performance of existing MHCH methods without any elaborated model crafting.

1 Introduction

In recent years, with the rapid development of deep learning (He et al., 2016; Ren et al., 2015), more and more service-oriented organizations have deployed chatbots to alleviate the problem of limited service resources. Although these chatbots can respond in real-time and save labor cost, they suffer from inappropriate responses and invalid conversations due to the limited quantity of available high-quality training data and the inherent biases (Xu et al., 2019; Liang et al., 2022) of neural networks. Moreover, the human utterances sometimes are elusive since they are rich in acronyms, slang words, and even content without logic or grammar, which are too obscure for a chatbot to comprehend. To alleviate these drawbacks, researchers introduced a human-agent collaboration mechanism named Machine-Human Chatting Handoff (MHCH) to allow a human to take over the dialogue while a robot agent feel confused so that a dialogue can be continued to avoid a bad user

Figure 1: An example of MHCH. Handoff label includes two types "normal" & "transferable", which denotes whether the chatbot should be transferred to human service.
experience and reduce the risk of customer churn (Liu et al., 2021a,b). As shown in Fig.1, when a chatbot try to address the user’s needs by giving an inappropriate response, the user will feel disappointed, and give a low global satisfaction score for current dialogue, which means a service failure and may lead to customer loss. If deploying with MHCH mechanism, a human can take over the dialogue and give a satisfactory response to meet the user’s needs, thus ensuring the user experience and service quality (Radziwill and Benton, 2017).

In fact, a high-quality MHCH service should consider multiple factors, such as dialogue context, local sentiments, global satisfaction, user state, and labor cost, etc. However, most existing MHCH methods mainly concerned on the dialogue context (Liu et al., 2021a) or assisting with global satisfaction prediction under the multi-task learning setting (Liu et al., 2021b), ignoring the grounded relationships among the other causal variables of MHCH, like the user state and human cost.

To address above issues and improve the performance of MHCH, we propose a general Causal-Enhance Module (CEM), which can be plugged into existing MHCH networks (Liu et al., 2021a,b), to incorporate the considerations of other potential causal variables of MHCH. Specifically, we first analyzes MHCH task based on causal graph by mining all potential causal variables and deduce that user states and labor cost are the other two causal variables that should be considered for high-quality customer service. Then, to incorporate the consideration of user state, we train a user state network mainly driven by local sentiments to maintain the changes of user state during the dialogue and adjust the handoff predictions by correcting the prediction bias according to the causal relationship between user states and handoff decisions. To minimize the labor cost of customer service while maintaining the same service quality, we construct a counterfactual-based cost simulator to regress the cost of a dialogue as an auxiliary task, which can make the MHCH backbone become cost-aware.

2 Related Work

Machine-Human Chatting Handoff. The research on MHCH is originated in 2018. Using the idea of reinforcement learning, Huang et al. (2018) proposed a dialogue robot to choose an assistant. Rajendran et al. (2019) utilize a reinforcement learning framework to maximize success rate and minimize human workload. Liu et al. (2021a,b) regraded the MHCH as a classification problem and focused on identifying which sentence should be transferred to the human service.

Causal inference and counterfactual learning. For structural causal models (Halpern et al., 2005), related studies (Heskes, 2013; Claassen et al., 2014; Xia et al., 2021) utilize graph neural networks for directed acyclic graph structure learning. For Rubin causal models, Rubin (2006) and Bengio et al. (2019) use neural networks to approximate the propensity scores, matching weights, etc., which can satisfy the covariate balancing (Kallus, 2020; Kuang et al., 2017); The representation learning (Huang et al., 2020b; Liang et al., 2020) can also be used to matched the covariate balance between the test group and the reference group (Shalit et al., 2017; Louizos et al., 2017; Lu et al., 2020). Several studies (Yoon et al., 2018; Yuan et al., 2019; Liu et al., 2020) uses counterfactual methods based on the generative models over the observed distributions to causal inference.

Multi-task learning in dialogue systems. Xu et al. (2020) uses multi-task learning for auxiliary pre-training tasks of dialogue data. Qin et al. (2020) combines dialogue behavior recognition and sentiment classification. Ide and Kawahara (2021) proposes a model which includes generation and classification tasks.

The contributions of our CEM can be summarized as follows:

- We conduct causal analysis based on causal graph for MHCH and identify the other two causal variables: user state and human cost, which should be considered to build high-quality MHCH service.

- To consider the impact of user state, the user state is applied to correct the handoff prediction bias according to the causal relationship between user states and handoff decisions.

- To minimize the labor cost of customer service while maintaining the same service quality, we construct a counterfactual-based cost simulator to regress the cost of a dialogue as an auxiliary task, which can make the MHCH backbone become cost-aware.
3 Preliminary

A given dialogue $D = [u_1, u_2, \ldots, u_L]$ contains $L$ utterances and have a label sequence $Y^h = [y^h_1, \ldots, y^h_L]$, where $y^h_t$ is the handoff label of $u_t, 1 \leq t \leq L$. The handoff labels $\Gamma$ have two kinds of labels, i.e.,"normal" and "transferable", where "normal" means that the utterance is no need to transfer, and "transferable" means that the utterance needs to be transferred to the manual service. The dialogue $D$ also have a global satisfaction label \{"satisfactory", "neutral", "dissatisfied"\}. Then, the local sentiment of each utterance $u_t$ is measured by an open-source tool SnowNLP, which includes three labels \{"positive", "neutral", "negative"\}.

4 Methodology

In this section, we analyse the impact of variables on MHCH from a fundamental view of causality. Then we present our CEM framework that eliminates the bad effect of ignored causal variables.

4.1 Causal analysis of MHCH

Causal graph is a directed acyclic graph where a node denotes a variable and an edge denotes a causal relation between two nodes (Pearl, 2009). It is widely used to describe the process of data, which can guide the design of predictive models (Zhang et al., 2021). Fig.2(a) shows the causal graph of MHCH. The rationality of this causal graph is explained as follows:

- D denote the dialogue $D = [u_1, \ldots, u_L]$.
- $Y = [p_1, p_2, \ldots, p_L]$ is the prediction of MHCH, where $p_t, 1 \leq t \leq L$ is the probability of that the handoff label of $u_t$ is "transferable".
- LS is the local sentiments of each utterance in a dialogue.
- GS represents the user's subjective evaluation of the current dialogue.
- US is a state for a given dialogue. Unlike GS, it is a variable that describes the objective
state of the user. We can model US through local sentiments.

- C is the labor cost caused by wrong prediction of MHCH.

- Edge $D \rightarrow Y$: The MHCH can judge when to transfer to manual service according to the dialogue content. Therefore, the dialogue can affect the prediction of MHCH.

- Edge $Y \rightarrow C$: The labor cost depends on the prediction of MHCH. If we do not need to transfer to human service, there will not be labor cost.

- Edges $D \rightarrow LS \rightarrow GS$: The dialogue quality of chatbot will affect users’ sentiment, and then affect users’ evaluation of the services.

- Edge $LS \rightarrow US$: The user state can be modeled from local sentiments.

- Edge $US \rightarrow Y$: In Fig.1, the user state can affect MHCH to judge whether the service should be transferred to manual service.

However, instead of Fig.2(a), the existing common solutions, which are mainly based on multi-task methods, e.g., service satisfaction analysis (SSA) (Song et al., 2019), adopt the causal graph as Fig.2(b), which models the relationship of $D \rightarrow LS \rightarrow GS$. Specifically, they consider two neural networks for a multi-task of SSA and MHCH, i.e., train a user network (UN) for SSA and a MHCH network for MHCH as shown in Fig.2(d). Since there is an encoder network that share weights between the two tasks to integrate information, the local sentiment can assist MHCH network by sharing dialogue features. Although such modeling is simple and has good performance on MHCH tasks, it is established through a simplified causal graph without considering the factors of user and cost, so it can not completely show the overall picture as shown in Fig.2(a). Therefore, we design a new causal graph as seen in Fig.2(c) to consider further factors, e.g. user state and labor cost to bridge the MHCH network and UN. Based on the new causal graph, a novel CEM (full) model (Fig.2(g)) as well as its variants CEM(U) and CEM(C) will be introduced in the following sections.

4.2 User State

As shown in Fig.2(e), we can use local sentiment, which is the output of UN, to restore user state. Since user state has a strong correlation with relative time (Ding and Li, 2005), we can measure the user state of $u_t$ by Eq.(1) with the weighted sum of local sentiment.

$$US_t = \sum_{t=1}^{L} UN(D) \times \beta_t,$$

where $UN(D) \in R^{L \times 3}$ is the local sentiment from UN when given $D$ as input. And the weight $\beta_t$ is

$$\beta_t = \text{softmax}([\frac{1}{L}, \ldots, \frac{t-1}{L}, \frac{t}{L}, 0, \ldots, 0])$$

**Soft Adjustment.** In Fig.2(a), if we establish the causal relationship between user state and MHCH task directly, $D$ will become a confounder to $Y$ due to the intervention of user state. To solve this problem, a simple way is to ignore the causal relationship $US \rightarrow Y$.

However, the utterance sometime can not affect directly whether it is necessary to transfer to human service since the complexity of the language. And the user state restored by the local sentiment can help decision of MHCH. For example, in Fig.1, the information of the sentiment is more important than those of utterance. Therefore, we can use another strategy to use user state for adjustment the decision of MHCH network. In particular, we can mask the neutral local sentiment since the neutral sentiments are confusing and therefore not highly recognizable, which means that neutral sentiment’s impact on MHCH Song et al. (2019) task is lower.

Moreover, the dimensions of $US$ is three, which do not match the two-dimension output $Y$ of the MHCH network. While masking the neutral sentiments, we can propose de-neutral soft adjustment shown in Fig.2(e), whose specific operation is as follows:

$$y^h_D = \text{softmax}(\text{Mask}_n(US_D) \odot \text{MHCH}(D)),$$

where $\text{Mask}_n$ is the masking operator for neutral sentiment. MHCH is the model using to modeling the causal relationship of $D \rightarrow Y$. $y^h_D$ is the predicted result of $D$. $\odot$ represents a product operation at the element level, which makes the probability of "positive" times the probability of "normal" and makes the probability of "negative" times the probability of "transferable". This adjustment can modify the normal probability with positive sentiment and the transferable probability with negative sentiment.
we only need to estimate the relative cost, which

\[
\hat{y} = \text{argmax}_{y} P(y|\hat{x})
\]

where \(Y\) represents the ground truth of the MHCH task and \(C\) denotes the labor cost of \(D\). \(P_{Y|h}(Y|h|D)\) is the probability calculation function for MHCH. \(F_{c}\) represents the cost calculation function. \(P_{Y|h}\) can be defined as follows:

\[
P_{Y|h}(Y|h|D) = \prod_{t=1}^{L} P(y^h_t = y^h_t|u_t), \tag{5}
\]

where \(y^h_t\) is the prediction of MHCH network for \(u_t\), and \(y^h_t\) is the ground truth of MHCH network for \(u_t\). Then let \(\zeta\) represent the upper limit of the cost of one utterance in human service. Since we only need to estimate the relative cost, which means that it does not need to obtain a specific and accurate estimated value. Therefore, \(\zeta\) is set to 1 by default. \(F_{c}\) can be defined as follows:

\[
F_{c}(Y^h, D) = \sum_{t=1}^{L} \zeta \cdot P(y^h_t = 1|u_t). \tag{6}
\]

In datasets, if the label corresponding to the data \(u_t\) is “transferable”, \(P(y^h_t = 1|u_t) = 1\), otherwise \(P(y^h_t = 1|u_t) = 0\). Next, we pretrain the cost simulator based on Eq.(10), so that the predicted cost measured by the output of the MHCH network is close to the real labor cost.

\[
\mathcal{L}_{\text{c pre}} = -\text{MSE} \left( \hat{C} - C \right), \tag{7}
\]

where \(\hat{C}\) represents the cost predicted by the simulator, and \(C\) represents the ground truth of cost. After supervised pre-training, the cost simulator can become cost-aware and can give a counterfactual cost.

On the trained cost simulator, we begin to train the MHCH model, and calculate the counterfactual cost of each \(D\) through \(F_{c}\). Since we want to make labor cost as low as possible, the loss function \(\mathcal{L}_{c}\) of the counterfactual cost simulator is defined as:

\[
\mathcal{L}_{c} = -\sum_{i=1}^{|
\Psi|} \hat{C}
\]

\[
= -\frac{1}{L} \sum_{i=1}^{|
\Psi|} \sum_{t=1}^{L} \zeta \cdot P(y^h_{i,t} = 1|u_{i,t}). \tag{8}
\]

where \(\Psi\) is the dataset size. Overall, the total loss \(\mathcal{L}(\Theta)\) of CEM for the multi-task MHCH is

\[
\mathcal{L}(\Theta) = \mathcal{L}_{h} + \eta_{h} \cdot \mathcal{L}_{s} + \eta_{c} \cdot \mathcal{L}_{c} + \delta \|\Theta\|_2^2. \tag{9}
\]
We evaluate our approach on four datasets in

\[ \text{Dataset and Experimental Settings} \]

5 Experiments

5.1 Dataset and Experimental Settings

We evaluate our approach on four datasets including Clothing (Liu et al., 2021a), Makeup1 (Liu et al., 2021a), Clothes (Liu et al., 2021b), and Makeup2 (Liu et al., 2021b). The statistics of the data are shown in Table 2. To verify the effectiveness of CEM and fairly compare with the baselines on the same datasets, we evaluate the performance of our CEM on the classification model DAMI (Liu et al., 2021a) by using Clothing and Makeup1 while test the performance of CEM on the multi-task model RSSN (Liu et al., 2021b) with Clothes and Makeup2, for the reason that these models are state-of-the-art. Because DAMI only models the relationship of \( D \rightarrow Y \), not \( D \rightarrow LS \rightarrow GS \), it is not possible to use DAMI to get \( US \), so we only add cost adjustment on DAMI named as CEM-DAMI (C).

5.2 Evaluation Metrics

Following prior works Liu et al. (2021a,b), we adopt F1, Macro F1 (Mac.F1) and GT-T (Golden Transfer within Tolerance) as accuracy metrics for evaluating the MHCH task. GT-T takes into account the tolerance property of the MHCH task through a tolerance range \( T \), which allows for "biased" predictions within it. The \( T \) can be ranged from 1 to 3 corresponding to GT-I, GT-II, and GT-III.

Furthermore, to verify that CEM can effectively control the cost, we compare the labor cost of different models. It is obvious that the higher the accuracy, the lower the labor cost. To eliminate the impact of model accuracy, we only compare the invalid cost which is more meaningful than the full cost. Therefore, we compute the invalid cost as follows:

\[
\text{IC} = \frac{\sum_{i=t}^{L} \sum_{j=1}^{T} (\hat{y}_{i,j}^h \neq y_{i,j} \text{transferable})}{\sum_{i=t}^{L} \sum_{j=1}^{T} (\hat{y}_{i,j}^h \neq y_{i,j})}
\]

where IC is the abbreviation of invalid cost.

5.3 Implementation Details

We use TensorFlow\(^1\) to implement our method with one RTX2080 GPU card. Back-propagation is used to compute gradients and the Adam optimizer (Kingma and Ba, 2014) is used for parameter updates. The dimension of word embedding is set as 200. The total vocabulary size of datasets is 48.5K. Other trainable model parameters are initialized by sampling values from initializer. Hyper-parameters of CEM and baselines are tuned on the validation set. \( \eta \) is set as 0.3. The sizes of model units are based on the baselines setting and remain the same in the comparison experiments. The \( L_2 \) regularization weight is \( 10^{-4} \) in DAMI and \( 3 \times 10^{-5} \) in RSSN. The batch size is set as 32. The number of epochs is set as 30 in DAMI and CEM-DAMI(C), and set as 80 in RSSN, CEM-RSSN(C), CEM-RSSN(U) and CEM-RSSN. Finally, we train the models with a learning rate of \( 7.5 \times 10^{-3} \) in DAMI and \( 1.5 \times 10^{-3} \) in RSSN. Following the data processing setting in Liu et al. (2021a), the datasets are divided into training set, validation set, and test set with an ratio of 8:1:1.

5.4 Results on Clothing and Makeup1

The experimental results of models on Clothing and Makeup1 are shown in Table 1. In Clothing, CEM-DAMI outperforms most baselines, and is slightly weaker than DAMI on GT-T metrics. In Makeup1, CEM-DAMI is the best performing model. This experimental result shows that incorporating cost into models does not reduce model accuracy.

\( IC \) of DAMI with the adjustment of CEM is significantly reduced in both Clothing and Makeup1 as shown in Table 4. We can conclude based on Table 1 and Table 4 that CEM-DAMI(C) can achieve competitive performance with lower labor cost, which means that our cost simulator can reduce labor cost while maintaining the model performance.

5.5 Results on Clothes and Makeup2

The experimental results of the methods on Clothes and Makeup2 are shown in Table 3. The cost results are shown in Figure 4. From Table 3, we can

\(^1\)https://www.tensorflow.org/

| Statistics items | Clothing | Makeup1 | Clothes | Makeup2 |
|------------------|----------|---------|---------|---------|
| # (Dialogues)    | 3500     | 4000    | 10000   | 3540    |
| # (Frustrated dialogues) | -       | -       | 2302    | 1180    |
| # (Neutral dialogues) | -       | -       | 6399    | 1180    |
| # (Satisfied dialogues) | -       | 1299    | 1180    | -       |
| # (Transferable utterances) | 6713   | 7446    | 16921   | 7668    |
| # (Neutral utterances) | 28901  | 32488   | 237891  | 86778   |
| Avg # (Utterances per dialogues) | 10.18  | 9.98    | 25.48   | 26.68   |
We compare different weight $\eta$ in Eq.9 to explore the impact of the cost simulator on MHCH models. According to the experimental results shown in Table 3, CEM-RSSN (U) can effectively improve model performance by modeling and tracking user state which is highly-correlated with user’s tolerances for invalid responses. Besides, similar with the results on Clothing and Makeup1, CEM-RSSN (C) still can achieve competitive performance even the cost simulator is not designed to improve the accuracy of the model.

Finally, We also compare the cost of RSSN and CEM-RSSN through multiple experiments, and perform two sided t-test to verify the whether the significant difference between RSSN and CEM-RSSN over metrics. The results shown in Fig.4 mean that CEM can significantly reduce labor cost while improving model performance.

### 5.6 Parameter Sensitivity

We compare different weight $\eta_c$ in Eq.9 to explore the impact of the cost simulator on MHCH models.

| Models | Clothes | Makeup2 |
|--------|---------|---------|
| HAN (Yang et al., 2016) | 59.8 | 78.7 | 71.7 | 73.1 | 74 | 54.3 | 75.4 | 68.5 | 70.1 | 71.3 |
| BERT+LSTM (Devlin et al., 2018) | 60.4 | 78.9 | 73.4 | 74.9 | 75.9 | 42.2 | 84.2 | 72.9 | 66.4 | 77.6 |
| HEC (Kumar et al., 2018) | 59.8 | 78.7 | 71.2 | 72.3 | 73 | 57.1 | 76.8 | 68 | 69.5 | 70.5 |
| DialogueRNN (Majumder et al., 2019) | 60.8 | 79.2 | 73.1 | 74.6 | 75.6 | 58.3 | 77.4 | 68.8 | 70.5 | 71.6 |
| CASA (Raheja and Tetreault, 2019) | 62 | 79.8 | 73.6 | 75 | 75.9 | 58.4 | 77.5 | 70.6 | 72.7 | 73.9 |
| LSTM-LCA (Dai et al., 2020) | 62.6 | 80.1 | 72.4 | 73.9 | 74.8 | 57.4 | 77 | 70.2 | 71.7 | 72.6 |
| CESTa (Wang et al., 2020) | 60.6 | 79.1 | 73.4 | 74.8 | 75.6 | 59.3 | 78 | 69.6 | 71.2 | 72.2 |
| DAMI (Liu et al., 2021a) | 66.7 | 82.2 | 74.2 | 75.9 | 77.1 | 61.1 | 79 | 73.3 | 74.4 | 75.2 |
| MT-ES (Ma et al., 2018) | 61.7 | 79.7 | 74.6 | 75.9 | 76.8 | 57.1 | 76.9 | 69.9 | 71.7 | 72.8 |
| JointBiLSTM (Bodigutla et al., 2020) | 62 | 79.9 | 75 | 76.1 | 76.9 | 59.3 | 78 | 70.1 | 72 | 73.1 |
| DCR-Net (Qin et al., 2020) | 62.1 | 79.9 | 71.4 | 72.8 | 73.7 | 58.8 | 77.7 | 70 | 72.1 | 73.4 |
| RSSN (Liu et al., 2021b) | 67.1 | 82.5 | 75.8 | 77.1 | 78 | 63.5 | 80.2 | 74.9 | 76.5 | 77.7 |
| CEM-RSSN (U) | 66.6 | 82.4 | 79.8 | 80.5 | 81 | 67.6 | 82.8 | 80.2 | 81.1 | 81.8 |
| CEM-RSSN (C) | 66.1 | 82.1 | 78.6 | 79.6 | 80.2 | 65.2 | 81.6 | 77.3 | 78.2 | 78.9 |
| CEM-RSSN (full) | 67.9 | 82.9 | 79.6 | 80.7 | 81.4 | 64.8 | 80.9 | 79.4 | 81.1 | 82.3 |
| JointBiLSTM (Bodigutla et al., 2020) | 62 | 79.9 | 75 | 76.1 | 76.9 | 59.3 | 78 | 70.1 | 72 | 73.1 |
| CEM-DAMI (C) | 53.4 | 56.1 |
| CEM-DAMI (C) | 53.4 | 56.2 |

We observe that our CEM can effectively improve the performance of RSSN, especially on GT-I, GT-II, and GT-III. We investigate the effects of user state and cost simulator through ablation experiments. According to the experimental results shown in Table 3, CEM-RSSN (U) can effectively improve model performance by modeling and tracking user state which is highly-correlated with user’s tolerances for invalid responses. Besides, similar with the results on Clothing and Makeup1, CEM-RSSN (C) still can achieve competitive performance even the cost simulator is not designed to improve the accuracy of the model.

Finally, We also compare the cost of RSSN and CEM-RSSN through multiple experiments, and perform two sided t-test to verify the whether the significant difference between RSSN and CEM-RSSN over metrics. The results shown in Fig.4 mean that CEM can significantly reduce labor cost while improving model performance.

Figure 3: The impact of the cost simulator over different $\eta_c \in [0, 1]$. This experiment is about CEM-RSSN on Clothes and Makeup2 dataset. Cost is IC which is defined in Eq.(10). F1 and GT-I is the metrics about the MHCH accuracy.

We take the value of $\eta_c$ from 0 to 1, and the experimental results about CEM-RSSN on Clothes and Makeup2 are shown in Fig.3. It can be seen that the different $\eta_c$ has little effect on the green (GT-I) and orange lines (F1), which indicates the stability of CEM in cost control.

Comparing the metric values under different weight $\eta_c$ on both two datasets, it can be found that when the weight exceeds a certain threshold, the larger the weight, the higher the labor cost and the lower the accuracy, indicating the labor cost is associated with the accuracy of models. Besides, it also shows that the trade-off between the accuracy and labor cost can be achieved by adjusting the loss weight, so as to obtain a model with low
Figure 4: Comparison of labor cost (%) and GT-T in Clothes and Makeup2. Cost is IC defined in Eq.(10). We obtain multiple sets of results of RSSN and CEM-RSSN through multiple experiments, draw the box plots of Cost and GT-T, and perform two sided t-test to verify the whether the significant difference between RSSN and CEM-RSSN over four metrics.

cost and high accuracy. Meanwhile, when the $\eta_c$ is lower than a certain threshold, the effect of the cost simulator can be ignored, which will affect the performance of CEM. Finally, we chose 0.01 as the value of $\eta_c$ to make a better trade-off in our experiments.

6 Conclusions

In this paper, we propose a novel CEM module for the MHCH task where we use causal inference to enhance the models of the MHCH task, and takes into account the labor cost. And the empirical results on four datasets and two types of models indicate that CEM improves models accuracy consistently and effectively saves invalid labor cost. Since there are minor modifications to the model architecture and loss function on the existing MHCH method and achieve the significant improvement, CEM can be easily plugged into the different MHCH methods.

7 Future works

Based on CEM, we can consider the following future work:

(1) In fact, when CEM is used to enhance the existing MHCH method, there is no additional parameters. From the perspective of inference speed and model deployment, this is the advantage. However, the consideration of user state and labor cost in CEM is mainly based on intuition to construct explicit transformations, which can not ensure the good enough performance. Therefore, we can consider adding neural networks to CEM in the future.

(2) For MHCH task, the conventional neural networks are generally used, such as fully connected neural networks, LSTM, BiLSTM etc. This makes the structure of the model lack of careful consideration, which has the potential to greatly improve the performance of MHCH. Specifically, we should consider a lot of fine-tuning methods for the neural network to ensure their performance, including the use of structure search techniques (He et al., 2021; Liu et al., 2018; Huang et al., 2020a), elaborate modules (Hu et al., 2018; Huang et al., 2020b), specific parameters (Liang et al., 2020), etc.

(3) Compared with other artificial intelligence fields, such as image segmentation and image classification, the data volume shown in Table.2 is not very large. However, the quality and quantity of data have a huge impact on their training, so the data driven cost simulator may have bias in its estimation of labor cost. Therefore, we can consider data augment methods (Cubuk et al., 2018; Lin et al., 2021) to effectively improve model training.
Limitations

Although we have fully demonstrated the effectiveness of CEM experimentally, we ignore the analysis for CEM from the mathematical point of view of causal inference. This makes it impossible for us to guarantee that CEM can be used in more complex and sophisticated MHCH methods in the future, or other applications in more extensive fields. Moreover, since the cost simulator is trained by neural network, we can not ensure whether the cost given by the simulator can not have a well enough performance to reflect the truth labor cost.

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A The detail of baselines

We compare our proposed approach with the following state-of-the-art dialogue classification models and multi-task models, which mainly come from MHCH, SSA and other similar tasks. We briefly categorize these baselines and introduce them below.

**Baselines for the MHCH task.** **HRN** (Lin et al., 2015): It uses a bidirectional LSTM to encode utterances and then fed these utterance features into a standard LSTM for context representation. **HAN** (Yang et al., 2016): HAN is a hierarchical network with two levels of attention mechanisms on word-level and utterance-level. **BERT** (Devlin et al., 2018): It uses a pre-trained BERT model to construct the single utterance representations for classification. **HEC** (Kumar et al., 2018): It builds a hierarchical recurrent neural network using bidirectional LSTM as a base unit and the conditional random field (CRF) as the top layer to classify each utterance into its corresponding dialogue act. **CRF-ASN** (Chen et al., 2018): It extends the structured attention network to the linear-chain conditional random field layer, which takes both contextual utterances and corresponding dialogue acts into account. **HBLSTM-CRF** (Kumar et al., 2018): It is a hierarchical recurrent neural network using bidirectional LSTM as a base unit and two projection layers to combine utterances and contextual information. **DialogueRNN** (Majumder et al., 2019): It is a method based on RNNs that keeps track of the individual party states throughout the conversation and uses the information for emotion classification. **CASA** (Raheja and Tetreault, 2019): It leverages the effectiveness of a context-aware self-attention mechanism to capture utterance level semantic text representations on prior hierarchical recurrent neural network. **LSTMLCA** (Dai et al., 2020): It is a hierarchical model based on the revised self-attention to capture intra-sentence and inter-sentence information. **CESTa** (Wang et al., 2020): It employs LSTM and Transformer to encode context and leverages a CRF layer to learn the emotional consistency in the conversation. **DAMI** (Liu et al., 2021a): It utilizes difficulty-assisted encoding to enhance the representations of utterances, and a matching inference mechanism is introduced to capture the contextual matching features.

**Multi-task baselines.** **MT-ES** (Ma et al., 2018): It proposes a joint framework that unifies the two highly pertinent tasks. **JointBiLSTM** (Bodigutla et al., 2020): It minimizes an adaptive multi-task loss function in order to jointly predict turn-level Response Quality labels provided by experts and explicit dialogue-level ratings provided by end users. **DCR-Net** (Qin et al., 2020): It considers the cross-impact and model the interaction between the two tasks by introducing a co-interactive relation layer. **RSSN** (Liu et al., 2021b): It integrates both dialogue satisfaction estimation and handoff prediction in one multi-task learning framework.