ON CONTINUOUS EXPANSIONS OF CONFIGURATIONS OF POINTS IN EUCLIDEAN SPACE

HOLUN CHENG, SER PEOW TAN AND YIDAN ZHENG

Abstract. For any two configurations of ordered points \( p = (p_1, \ldots, p_N) \) and \( q = (q_1, \ldots, q_N) \) in Euclidean space \( \mathbb{E}^d \) such that \( q \) is an expansion of \( p \), there exists a continuous expansion from \( p \) to \( q \) in dimension \( 2d \); Bezdek and Connelly used this to prove the Kneser-Poulsen conjecture for the planar case. In this paper, we show that this construction is optimal in the sense that for any \( d \geq 2 \) there exists configurations of \( (d+1)^2 \) points \( p \) and \( q \) in \( \mathbb{E}^d \) such that \( q \) is an expansion of \( p \) but there is no continuous expansion from \( p \) to \( q \) in dimension less than \( 2d \). The techniques used in our proof are completely elementary.

1. Introduction and statement of results.

Let \( \mathbb{E}^d \) be the Euclidean space of dimension \( d \geq 2 \), where we identify and represent the points of \( \mathbb{E}^d \) by their position vectors. \( \mathbb{E}^d \) is endowed with the standard inner product \( u \cdot v \) and norm \( |u| = \sqrt{u \cdot u} \).

Suppose that \( d < f \), then \( \mathbb{E}^f \cong \mathbb{E}^d \times \mathbb{E}^{f-d} \) and we have the standard projections \( \pi_1 : \mathbb{E}^f \to \mathbb{E}^d \) and \( \pi_2 : \mathbb{E}^f \to \mathbb{E}^{f-d} \) given by
\[
\pi_1(u_1, \ldots, u_f) = (u_1, \ldots, u_d), \quad \pi_2(u_1, \ldots, u_f) = (u_{d+1}, \ldots, u_f),
\]
and the standard inclusion \( \iota : \mathbb{E}^d \to \mathbb{E}^f \) given by
\[
\iota(u) = (u_1, \ldots, u_d, 0, \ldots, 0).
\]
Note that \( \pi_1 \circ \iota = \text{id} \) on \( \mathbb{E}^d \), and for \( u, v \in \mathbb{E}^f \),
\[
\begin{align*}
|u| &= |\pi_1(u)| + |\pi_2(u)|, \\
|u| &= |\pi_1(u) + \pi_2(u)|, \\
|u| &= |\pi_1(u)|^2 + |\pi_2(u)|^2.
\end{align*}
\]

Let \( p = (p_1, \ldots, p_N) \) and \( q = (q_1, \ldots, q_N) \) be two configurations of \( N \) ordered points in \( \mathbb{E}^d \), where \( p_i, q_i \in \mathbb{E}^d \) for \( i = 1, \ldots, N \), and suppose \( f > d \).

Definition 1.1. (Expansions in \( \mathbb{E}^d \)) \( q \) is an expansion of \( p \) if
\[
|p_i - p_j| \leq |q_i - q_j|, \quad 1 \leq i < j \leq N.
\]

Definition 1.2. (Continuous expansions in \( \mathbb{E}^f \)) We say that there is a continuous expansion from \( p \) to \( q \) in \( \mathbb{E}^f \) if there exists a family of continuous functions (continuous motions)
\[
f_i : [0, 1] \to \mathbb{E}^f, \quad i = 1, \ldots N
\]
such that for $1 \leq i < j \leq N$ and $0 \leq t_1 < t_2 \leq 1$,

1. $f_i(0) = \iota(p_i)$, $f_i(1) = \iota(q_i)$;
2. $|f_i(t_1) - f_j(t_1)| \leq |f_i(t_2) - f_j(t_2)|$.

Note that if there is a continuous expansion from $p$ to $q$ in $\mathbb{E}^d$, then $q$ is necessarily an expansion of $p$ in $\mathbb{E}^d$, but an expansion may not admit a continuous expansion in the same or a higher dimension. The following result by R. Alexander [1] shows that any expansion admits a continuous expansion in twice the dimension.

**Theorem 1.3.** [1], see also [3]. Suppose that $q = (q_1, \ldots, q_N)$ is an expansion of $p = (p_1, \ldots, p_N)$ in $\mathbb{E}^d$. Then the family of functions $f_i : [0, 1] \rightarrow \mathbb{E}^{2d}$, $i = 1, \ldots, N$, given by

$$f_i(t) = \left( \frac{p_i + q_i}{2} + \frac{(\cos \pi t)p_i - q_i}{2}, \frac{(\sin \pi t)p_i - q_i}{2} \right)$$

is a continuous expansion from $p$ to $q$ in $\mathbb{E}^{2d}$.

**Proof.** We reproduce the proof here for completeness. Clearly, $f_i$ is continuous for $i = 1, \ldots, N$ and $f_i(0) = \iota(p_i)$, $f_i(1) = \iota(q_i)$. Expanding, $4|f_i(t) - f_j(t)|^2 = |(p_i - p_j) - (q_i - q_j)|^2 + |(p_i - p_j) + (q_i - q_j)|^2 + 2(\cos \pi t)|(p_i - p_j)^2 - |q_i - q_j|^2|.$ Since $q$ is an expansion of $p$, $|p_i - p_j|^2 - |q_i - q_j|^2 \leq 0$ for all $i \neq j$. Therefore $|f_i(t) - f_j(t)|$ is non-decreasing on $[0, 1]$. □

Bezdek and Connelly used the above in [3], together with results of Csikós [5] to prove the Kneser-Poulsen conjecture [7] for the plane. More specifically, they showed that if there is a piecewise analytic expansion from $p$ to $q$ in dimension $d + 2$, then the Kneser-Poulsen conjecture holds for balls centered at $p$ and $q$, that is, the volume of the union of the balls $B(p_i, r_i)$ is less than or equal to the volume of the union of the balls $B(q_i, r_i)$, where $r_i > 0$. Similarly, the same method shows that the conjecture holds if the number of balls $N \leq d + 3$, generalizing a result of Gromov in [6]. This raises the question, as pointed out in [3], of whether it is possible to find continuous expansions in dimensions less than $2d$ for all expansions of $q$ of $p$ in dimension $d$. If so, then the approach of Bezdek and Connelly can be applied to prove the Kneser-Poulsen conjecture in more general settings. Our main result is a negative answer to this question, specifically, we have:

**Theorem 1.4.** (Main Theorem) There exists configurations $p = (p_1, \ldots, p_N)$ in $\mathbb{E}^d$ with expansions $q = (q_1, \ldots, q_N)$, where $N = (d + 1)^2$, which do not admit continuous expansions in dimensions less than $2d$.

**Remark:** The example we construct is in fact the same as that constructed independently by Belk and Connelly in [2], and in both cases, based on the example constructed in [3] for the planar case. However, our proof is more elementary and uses only basic linear algebra and some simple rigidity results. Indeed, our proof shows that away from the endpoints, any continuous expansion cannot be embedded into dimension less than $2d$ at any time $t \in (0, 1)$.

The configurations $p$ and $q$ are built from the $(d + 1)$ vertices $v_0, \ldots, v_d$ of the regular $d$-simplex $\sigma_d \subset \mathbb{E}^d$, together with the vertices of the inward and outward flaps associated to the faces of $\sigma_d$, specifically, each face $F^i$ ($i = 0, \ldots, d$) of $\sigma_d$ may be pushed orthogonally towards or away from the center of $\sigma_d$ by a distance
s > 0, to obtain flaps $F^i_{\text{inw}}$ and $F^i_{\text{out}}$ respectively (note that Belk and Connelly had a slightly different definition for flaps in [2]). The configuration $p$ consists of the vertices of $\sigma_d$ and of the inward flaps $F^i_{\text{inw}}$ and the configuration $q$ consists of the corresponding vertices of $\sigma_d$ and of the outward flaps $F^i_{\text{out}}$. Note that each flap has $d$ vertices so that $p$ and $q$ consists of $(d + 1)^2$ points. The rest of the paper will be devoted to explaining this construction ([2]), showing that $q$ is an expansion of $p$ ([3]), and proving that there is no continuous expansion from $p$ to $q$ in $E_f$ for $f < 2d$ ([4]).

**Acknowledgements.** This work arose from an undergraduate honors project of the third author under the supervision of the first and second authors. The authors are grateful to Jean-Marc Schlenker for helpful conversations, and also for bringing their attention to [2] arising from his correspondence with R. Connelly.

2. Regular simplices with flaps

Let $\sigma := \sigma_d \subset E^d$ be the regular simplex with vertices $u_i$, $i = 0, \ldots, d$ and center at the origin $O$ such that $|u_i| = 1$ for all $i$ (see figure 1). Then

$$u_i \cdot u_j = -\frac{1}{d}, \quad i \neq j$$

(4)

**Figure 1.** The simplex $\sigma_2$ and $\sigma_3$

see for example Coxeter [4], or Parks and Wills [8] for an elementary proof. Denote by $F^i$ the face of $\sigma$ which does not contain the vertex $u_i$. Then the norm of $F^i$, the outward facing unit normal $n_i$ to $F^i$ is the vector $-u_i$.

Fix $s > 0$. For each face $F^i$, $i = 0, \ldots, d$, define the outward $i$th flap of depth $s$ to be $F^i$ translated by $sn_i = -u_i$, that is,

$$F^i_{\text{out}} := F^i - su_i.$$  

Similarly, the inward $i$th flap of depth $s$ is given by

$$F^i_{\text{inw}} := F^i + su_i.$$  

Each flap has $d$ vertices and if we denote the vertices of $F^i_{\text{out}}$ by $c^i_j$ and those of $F^i_{\text{inw}}$ by $b^i_j$, where $j \neq i$ (see figure 2 for the case when $d = 2$ and 3), then we have, for $i, j \in \{0, \ldots, d\}$, $i \neq j$,

$$c^i_j = u_j + sn_i = u_j - su_i,$$

(5)

$$b^i_j = u_j - sn_i = u_j + su_i.$$  

(6)
The configurations \( p \) and \( q \) we are interested in consists of the vertices of the regular simplex with inward and outward flaps respectively, defined by

\[
p = \{u_i\} \cup \{b_{ij}\}, \quad q = \{u_i\} \cup \{c_{ij}\}, \quad i, j \in \{0, 1, \ldots, d\}, \quad i \neq j
\]  

(7)

where \( p \) and \( q \) are ordered so that the correspondence between the elements from the indexing is preserved. We have:

**Theorem 2.1.** Suppose that \( p \) and \( q \) are configurations in \( \mathbb{E}^d \) consisting of the vertices of the regular simplex with inward and outward flaps defined as in (7). Then

(a) \( q \) is an expansion of \( p \) in \( \mathbb{E}^d \);
(b) there does not exist a continuous expansion from \( p \) to \( q \) in \( \mathbb{E}^f \) for \( f < 2d \).

We will prove (a) in the next section and (b) in the following section. We note that although (a) was claimed in [2], no proof was given, we give a proof here for completeness. Also our proof of (b) is independent of, and more elementary than that given in [2].

### 3. Proof that \( q \) is an expansion of \( p \)

We only need to consider the distances between vertices on \( \sigma \) and vertices on the flaps, or between vertices on the flaps. In the first case, we have

\[
|u_k - b_{ij}| = |u_k - c_{ij}|, \quad \text{if} \quad k \neq i,
\]

since \( u_k \subset F^i \), and

\[
|u_i - b_{ij}| < |u_i - c_{ij}|
\]

since by reflecting on the face \( F^i \), we see there is a broken path from \( u_i \) to \( b_{ij} \) of length \( |u_k - c_{ij}| \). The argument works if we replace \( \sigma \) by any simplex.
In the second case, we have, for \( i \neq j, k \neq l \),
\[
|b_j^i - b_k^k|^2 = |(u_j + su_i) - (u_l + su_k)|^2 \\
= |u_j - u_l|^2 + 2s(u_j - u_l) \cdot (u_i - u_k) + s^2|u_i - u_k|^2
\]
\[
|c_j^j - c_k^k|^2 = |u_j - u_l|^2 - 2s(u_j - u_l) \cdot (u_i - u_k) + s^2|u_i - u_k|^2
\]
\[
\implies |b_j^i - b_k^k|^2 - |c_j^j - c_k^k|^2 = 4s(u_j - u_l) \cdot (u_i - u_k)
\]
If \( i = k, \) or \( j = l, \) or \( i, j, k, l \) are all distinct, then
\( 4s(u_j - u_l) \cdot (u_i - u_k) = 0 \) by (4) so that
\[
|b_j^i - b_k^k| = |c_j^j - c_k^k|.
\]
If \( i = l \) or \( j = k, \) then
\[
4s(u_j - u_l) \cdot (u_i - u_k) = 4s(\frac{1}{d} - 1) < 0
\]
by (4), hence in all cases,
\[
|b_j^i - b_k^k| \leq |c_j^j - c_k^k|.
\]

Remark: In the case where we start with any simplex instead of \( \sigma_d, \) then
\[
|b_j^i - b_k^k|^2 - |c_j^j - c_k^k|^2 = 4s(u_j - u_l) \cdot (n_k - n_i).
\]
Again, if \( i = k, \) or \( j = l, \) or \( i, j, k, l \) are all distinct, then
\( 4s(u_j - u_l) \cdot (n_k - n_i) = 0, \)
and if \( i = l \) or \( j = k, \) then
\( 4s(u_j - u_l) \cdot (n_k - n_i) < 0, \) so Theorem 2.1(a) holds if we replace the regular simplex with any simplex.

4. Proof that there is no continuous expansion in dimension \( < 2d \)

The main tools we use are some basic linear algebra as described in [1] and the fact that the configurations \( p \) and \( q \) contain several sub-configurations which are rigid under continuous expansion since the pair-wise distances are preserved in the sub-configurations. We first outline the strategy of our proof, note that it suffices to show that there is no continuous expansion in dimension \( 2d - 1. \)

(I) We will assume for a contradiction that there exists a continuous expansion from \( p \) to \( q \) in \( \mathbb{E}^{2d-1}; \)

(II) we construct for each face \( F_k \) a displacement vector function
\[
d_k : [0, 1] \longrightarrow \mathbb{E}^{2d-1} \cong \mathbb{E}^d \times \mathbb{E}^{d-1};
\]
such that \( d_k(t) \) is orthogonal to \( F_k \) and \( |d_k(t)| = s \) for all \( t \in [0, 1]; \)

(III) show that there is some \( t_0 \in [0, 1] \) such that the projection \( \pi_2(d_k(t_0)) \) to \( \mathbb{E}^{d-1} \) is non-zero for all \( k \in \{0, 1, \ldots, d\}; \)

(IV) show that the set \( \{w_k = \pi_2(d_k(t_0))\} \subset \mathbb{E}^{d-1} \) consists of pairwise obtuse vectors;

(V) show that this is not possible to give the required contradiction.

(I) Consider \( \mathbb{E}^{2d-1} \cong \mathbb{E}^d \times \mathbb{E}^{d-1} \) and define the projections \( \pi_1 : \mathbb{E}^{2d-1} \rightarrow \mathbb{E}^d \) and \( \pi_2 : \mathbb{E}^{2d-1} \rightarrow \mathbb{E}^{d-1} \) and the inclusion \( t : \mathbb{E}^d \rightarrow \mathbb{E}^{2d-1} \) as in [1].

Suppose that there is a continuous expansion from \( p \) to \( q \) in \( \mathbb{E}^{2d-1} \cong \mathbb{E}^d \times \mathbb{E}^{d-1}. \)
Let \( f_k, g_j^i : [0, 1] \rightarrow \mathbb{E}^{2d-1}, i, j, k \in \{0, \ldots, d\}, i \neq j, \) be the continuous motions of \( u_k \) and \( b_j^i \) respectively which define the continuous expansion from \( p \) to \( q. \) Since
Throughout the motion, that is
\[ \sigma \]

\[ 6 \quad H. \text{CHENG, S. P. TAN, Y. ZHENG} \]

We also have

\[ \text{Proposition 4.1.} \]
\[ \text{Suppose that } (u_1, u_2, u_3, u_4), (v_1, v_2, v_3, v_4) \subset \mathbb{E}^n \text{ are configurations such that} \]
\[ |u_i - u_j| = |v_i - v_j| \quad \text{for all } i \neq j. \]  

(10)

If \((u_1, u_2, u_3, u_4)\) is a parallelogram, then \((v_1, v_2, v_3, v_4)\) is also a parallelogram and \((v_1, v_2, v_3, v_4) \cong (u_1, u_2, u_3, u_4)\).

\[ \text{Proof.} \]

Let \(w\) and \(w'\) be the midpoints of \((u_2, u_4)\) and \((v_2, v_4)\) respectively. We have \(\Delta(u_1, u_2, u_4) \cong \Delta(v_1, v_2, v_4)\), hence \(|w - u_1| = |w' - v_1|\) (see figure 3). Similarly, \(\Delta(u_2, u_3, u_4) \cong \Delta(v_2, v_3, v_4)\), so \(|u_3 - w| = |v_3 - w'\). Also, by \(10\)
\[ |v_3 - v_1| = |u_3 - u_1| \quad \text{and since } (u_1, u_2, u_3, u_4) \text{ is a parallelogram, } |u_3 - u_1| = |u_3 - w| + |w - u_1|. \]

\[ \text{Hence, } v_1, w' \text{ and } v_3 \text{ are collinear, and } (v_1, v_2, v_3, v_4) \text{ lies on a plane with} \]

the diagonal from \(v_1\) to \(v_3\) bisecting the diagonal from \(v_2\) to \(v_4\). A similar argument shows that the diagonal from \(v_2\) to \(v_4\) bisects the diagonal from \(v_1\) to \(v_3\), so that \((v_1, v_2, v_3, v_4)\) is a parallelogram. Now \(10\) implies \((v_1, v_2, v_3, v_4) \cong (u_1, u_2, u_3, u_4)\).  

\[ \square \]

Now, for distinct \(i, j, k \in \{0, \ldots, d\}\), consider the continuous family of configurations
\[ (f_i(t), f_j(t), g^k_i(t), g^k_j(t)), \quad t \in [0, 1]. \]

By assumption, this is a continuous expansion, but the pairwise distances between points in the initial configuration
\[ (f_i(0), f_j(0), g^k_i(0), g^k_j(0)) = ((\iota(u_i), \iota(u_j), \iota(u_j + su_k), \iota(u_i + su_k)) \]

and those of the final configuration
\[ (f_i(1), f_j(1), g^k_i(1), g^k_j(1)) = ((\iota(u_i), \iota(u_j), \iota(u_j - su_k), \iota(u_i - su_k)) \]

Figure 3. The configurations \((u_1,u_2,u_3,u_4)\) and \((v_1,v_2,v_3,v_4)\)
are equal since they form congruent rectangles. Since the initial configuration describes a rectangle, it follows from proposition 4.1 that all intermediate configurations are congruent rectangles. Hence,

\[ g^k_i(t) - \iota(u_j) = g^k_i(t) - \iota(u_i), \quad \forall \ i \neq j \neq k \neq i. \]

We can define \( d_k(t) : [0, 1] \to \mathbb{R}^{d-1} \) by

\[ d_k(t) := g^k_i(t) - \iota(u_j), \quad \text{for any} \quad j \neq k, \]

then

\[ |d_k(t)| = |g^k_j(t) - \iota(u_j)| = |g^k_j(0) - \iota(u_j)| = s \]

and \( d_k(t) \cdot (\iota(u_j - u_i)) = 0 \) for all \( i \neq j \neq k \neq i \), hence, \( d_k(t) \) is orthogonal to \( \iota(F^k) \), since \( \{\iota(u_j - u_i)\}, i \neq j \neq k \neq i \) spans \( \iota(F^k) \).

(III) For \( k = 0, \ldots, d \), let

\[ \pi_1(d_k(t)) := v_k(t) \in \mathbb{R}^d, \quad \pi_2(d_k(t)) := w_k(t) \in \mathbb{R}^{d-1} \]

so that \( d_k(t) = (v_k(t), w_k(t)) \). Since \( d_k(t) \cdot (u_i - u_j) = v_k(t) \cdot (u_i - u_j) = 0 \) for all \( i \neq j \neq k \neq i \), \( v_k(t) \) is orthogonal to \( F^k \subseteq \mathbb{R}^d \), so \( v_k(t) = a_k(t)u_k, \quad a_k(t) \in \mathbb{R} \), and furthermore, \( |a_k(t)| \leq s \) since \( |v_k(t)|^2 + |w_k(t)|^2 = |d_k(t)|^2 = s^2 \) by [3]. By the intermediate value theorem, since \( a_k(0) = s \) and \( a_k(1) = -s \), \( a_k(t) \) takes all values in \([-s, s] \), so in particular, there exists some \( t_0 \in [0, 1] \) such that \( a_k(t_0) = 0 \), so that \( v_k(t_0) = 0 \). Hence \( |w_k(t_0)|^2 = s^2 \), in particular, \( w_k(t_0) \neq 0 \) (in fact, we only need that \( |a_k(t_0)| < s \) to get \( w_k(t_0) \neq 0 \)).

Now for \( i \neq j \neq k \neq i \), we have \( \triangle(\iota(u_i), g^i_j(0), g^i_k(0)) \cong \triangle(\iota(u_i), g^i_j(1), g^i_k(1)) \) since

\[ g^i_j(0) - \iota(u_i) = \iota(su_j), \quad g^i_k(0) - \iota(u_i) = \iota(su_k), \]

\[ g^i_j(1) - \iota(u_i) = \iota(-su_j), \quad g^i_k(1) - \iota(u_i) = \iota(-su_k), \]

so all the triangles \( \triangle(\iota(u_i), g^i_j(t), g^i_k(t)), t \in [0, 1] \) are congruent. In particular,

\[ (g^i_j(t) - \iota(u_i)) \cdot (g^i_k(t) - \iota(u_i)) = d_k(t) \cdot d_j(t) = d_k(0) \cdot d_j(0) = su_k \cdot su_j = -s^2 \quad (11) \]

for all \( t \in [0, 1] \) by [4]. Now using \( v_k(t_0) = 0 \) and applying [2] to [11] gives

\[ -s^2 = d_k(t_0) \cdot d_j(t_0) = v_k(t_0) \cdot v_j(t_0) + w_k(t_0) \cdot w_j(t_0) = w_k(t_0) \cdot w_j(t_0) \quad (12) \]

for all \( j \neq k \). In particular, we see that \( w_j(t_0) \neq 0 \) for all \( j = 0, \ldots, d \) (again, we really only need that \( |a_k(t_0)| < s \) to obtain this conclusion).

(IV) We need to show that \( w_i(t_0) \cdot w_j(t_0) < 0 \) for all distinct \( i, j \in \{0, \ldots, d\} \). Recall that \( d_i(t) = (v_i(t), w_i(t)) = (a_i(t)u_i, w_i(t)) \). Since \( w_i(t_0) \neq 0 \) and by [3]

\[ s^2 = |d_i(t_0)|^2 = |v_i(t_0)|^2 + |w_i(t_0)|^2 = |a_i(t_0)|^2 + |w_i(t_0)|^2 \]

we have

\[ -s < a_i(t_0) < s, \quad \text{for all} \quad i = 0, \ldots, d. \quad (13) \]

Now by [4], for \( i \neq j \),

\[ d_i(t_0) \cdot d_j(t_0) = v_i(t_0) \cdot v_j(t_0) + w_i(t_0) \cdot w_j(t_0). \]
\( \mathbf{d}_i(t_0) \cdot \mathbf{d}_j(t_0) = \mathbf{d}_i(0) \cdot \mathbf{d}_j(0) = -\frac{s^2}{d} \) and

\[ \mathbf{v}_i(t_0) \cdot \mathbf{v}_j(t_0) = a_i(t_0)a_j(t_0)\mathbf{u}_i \cdot \mathbf{u}_j = -\frac{a_i(t_0)a_j(t_0)}{d}, \]

where by (13), \(|\mathbf{v}_i(t_0) \cdot \mathbf{v}_j(t_0)| < \frac{s^2}{d}\). It follows that \( \mathbf{w}_i(t_0) \cdot \mathbf{w}_j(t_0) < 0 \) for all distinct \( i, j \in \{0, \ldots, d\} \).

Remark: In proving the conclusion in (IV) holds, we only really require that the outward normals \( \mathbf{n}_i, i = 0, \ldots, d \) of \( \sigma_d \) are pairwise obtuse, that is, \( \mathbf{n}_i \cdot \mathbf{n}_j < 0 \) for all distinct \( i, j \in \{0, \ldots, d\} \). Hence we may replace the regular simplex with one for which the above holds.

(V) Recall that \( \mathbf{u}_1, \mathbf{u}_2 \in \mathbb{E}^n \) are obtuse if \( \mathbf{u}_1 \cdot \mathbf{u}_2 < 0 \). The lemma below states that we cannot have a collection of \( n + 2 \) pairwise obtuse vectors in \( \mathbb{E}^n \).

**Lemma 4.2.** For any set \( \{\mathbf{u}_1, \ldots, \mathbf{u}_{n+2}\} \) of \( n + 2 \) vectors in \( \mathbb{E}^n \), \( \mathbf{u}_i \cdot \mathbf{u}_j \geq 0 \) for some \( i \neq j \), that is, the vectors cannot be all pairwise obtuse.

**Proof.** We prove by induction on the dimension \( n \). The result is clearly true when \( n = 1 \) since for any 3 vectors \( \mathbf{u}_1, \mathbf{u}_2, \mathbf{u}_3 \in \mathbb{E}^1 \), either at least one of the vectors is \( \mathbf{0} \), or two are in the same direction so have positive dot product. Assume the lemma is true for \( n \) and suppose for a contradiction that there exists \( \mathbf{u}_1, \ldots, \mathbf{u}_{n+3} \in \mathbb{E}^{n+1} \) that are all pairwise obtuse. Without loss of generality, we may assume that none of \( \mathbf{u}_i \) are zero, and that \( \mathbf{u}_{n+3} = (-1, 0, \ldots, 0) \). Write \( \mathbb{E}^{n+1} \cong \mathbb{E}^1 \times \mathbb{E}^n \) and consider the projections \( \pi_1 : \mathbb{E}^{n+1} \to \mathbb{E}^1 \) and \( \pi_2 : \mathbb{E}^{n+1} \to \mathbb{E}^n \) respectively as in [1]. For \( i = 1, \ldots, n+2 \), let \( \mathbf{v}_i := \pi_1(\mathbf{u}_i) \in \mathbb{E}^1 \cong \mathbb{R} \), \( \mathbf{w}_i := \pi_2(\mathbf{u}_i) \in \mathbb{E}^n \), see figure 4. Note that \( \mathbf{v}_i > 0 \) since \( \mathbf{u}_i \cdot \mathbf{u}_{n+3} < 0 \), so \( \mathbf{v}_i \cdot \mathbf{v}_j > 0 \) for \( i, j \in \{1, \ldots, n+2\} \). Then we have, from (2), for distinct \( i, j \in \{1, \ldots, n+2\} \),

\[ \mathbf{u}_i \cdot \mathbf{u}_j = \mathbf{v}_i \cdot \mathbf{v}_j + \mathbf{w}_i \cdot \mathbf{w}_j. \]

**Figure 4.** Projection of \( \mathbb{E}^{n+1} \) vectors into \( \mathbb{E}^n \) space
By assumption, $\mathbf{u}_i \cdot \mathbf{u}_j < 0$, and $\mathbf{v}_i \cdot \mathbf{v}_j > 0$ from the above, so

$$\mathbf{w}_i \cdot \mathbf{w}_j < 0.$$  

Hence $\{\mathbf{w}_1, \ldots, \mathbf{w}_{n+2}\}$ is a collection of pairwise obtuse vectors in $\mathbb{E}^n$ contradicting the induction hypothesis. \hfill \Box

Applying lemma 4.2 to the set $\{\mathbf{w}_0, \mathbf{w}_1, \ldots, \mathbf{w}_d\} \subset \mathbb{E}^{d-1}$ in (IV) we get the required contradiction which concludes the proof of Theorem 2.1 from which Theorem 1.4 follows. \hfill \Box

**Concluding remarks.** The method of proof above works if we construct $\mathbf{p}$ and $\mathbf{q}$ from any simplex in $\mathbb{E}^d$ whose pairwise norms are obtuse. It also shows that any intermediate configuration in a continuous expansion from $\mathbf{p}$ to $\mathbf{q}$ cannot be embedded in a space of dimension less than $2d$. An interesting open question is, for each $d$, what is the smallest number of points in the configurations $\mathbf{p}$ and $\mathbf{q}$ for which there is no continuous expansion in $\mathbb{E}^{2d-1}$. We have shown that $N = (d+1)^2$ suffices, but this may not be optimal. Finally, it is also interesting to ask if we can find configurations $\mathbf{p}$, and expansions $\mathbf{q}$ of $\mathbf{p}$ such that the continuous expansion given by Theorem 1.3 is essentially, up to some trivial motions, the only continuous expansion in dimension $2d$.

**References**

[1] R. Alexander, *Lipschitzian mappings and total mean curvature of polyhedral surfaces. I*. Trans. Amer. Math. Soc. 288 (1985), no. 2, 661–678.

[2] M. Belk, R. Connelly, *Making contractions continuous: a problem related to the Kneser-Poulsen conjecture*. Preprint (2007).

[3] K. Bezdek, R. Connelly, *Pushing disks apart—the Kneser-Poulsen conjecture in the plane*. J. Reine Angew. Math. 553 (2002), 221–236.

[4] H.S.M. Coxeter, *Regular polytopes*. Second edition The Macmillan Co., New York; Collier-Macmillan Ltd., London 1963 xx+321 pp.

[5] B. Csikós, *On the volume of the union of balls*. Discrete Comput. Geom. 20 (1998), no. 4, 449–461.

[6] M. Gromov, *Monotonicity of the volume of intersection of balls*. Geometrical aspects of functional analysis (1985/86), 14, Lecture Notes in Math., 1267, Springer, Berlin, 1987.

[7] M. Kneser, *Einige Bemerkungen ber das Minkowskische Flächenmass*. Arch. Math. (Basel) 6 (1955), 382–390.

[8] H. R.Parks, D.C. Wills, *An elementary calculation of the dihedral angle of the regular n-simplex*. Amer. Math. Monthly 109 (2002), no. 8, 756–758.