Laplacian Filtered Loop-Star Decompositions and Quasi-Helmholtz Laplacian Filters: Definitions, Analysis, and Efficient Algorithms

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Abstract—Quasi-Helmholtz decompositions are fundamental tools in integral equation modeling of electromagnetic problems because of their ability of rescaling solenoidal and non-solenoidal components of solutions, operator matrices, and radiated fields. These tools are however incapable, per se, of modifying the refinement-dependent spectral behavior of the different operators and often need to be combined with other preconditioning strategies. This paper introduces the new concept of filtered quasi-Helmholtz decompositions proposing them in two incarnations: the filtered Loop-Star functions and the quasi-Helmholtz Laplacian filters. Because they are capable of manipulating large parts of the operators’ spectra, new families of preconditioners and fast solvers can be derived from these new tools. A first application to the case of the frequency and $h$-refinement preconditioning of the electric field integral equation is presented together with numerical results showing the practical effectiveness of the newly proposed decompositions.

Index Terms—Integral equations, quasi-Helmholtz decompositions, quasi-Helmholtz projectors, preconditioning, EFIE.

I. INTRODUCTION

INTEGRAL equation formulations are effective numerical strategies for modeling radiation and scattering by perfectly electrically conducting objects [1]–[3]. Their effectiveness primarily derives from the fact that they only require the scatterers’ surfaces to be discretized, automatically impose radiation conditions and, thanks to the advent of fast algorithms [4], give rise to linear-in-complexity approaches when solved with iterative schemes—provided that the conditioning of the linear system matrices resulting from their discretizations is independent of the number of unknowns [5]. Among the well-established formulations, the electric field integral equation (EFIE) plays a crucial role, both in itself and within combined field formulations [6]. The EFIE, lamentably, becomes ill-conditioned when the frequency is low or the discretization density high [7]. These phenomena—respectively known as the low-frequency and $h$-refinement breakdowns—cause the solution of the EFIE to become increasingly challenging to obtain, as the number of iterations of the solution process grows unbounded, which jeopardizes the possibility of achieving an overall linear complexity.

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Traditional approaches to tackle the low-frequency breakdown rely on standard quasi-Helmholtz decompositions such as Loop-Star/Tree bases [8]–[12] that, despite curing the low-frequency behavior, worsen the $h$-refinement ill-conditioning of the EFIE [11] because of the derivative nature of the change of basis [12]. A way to circumvent the issue is the use of hierarchical strategies both on structured [13], [14] and unstructured meshes [15]–[18]. These schemes, when designed properly, can solve both the low-frequency and the $h$-refinement problems but still rely on the construction on an explicit, basis-based, quasi-Helmholtz decomposition that requires the cumbersome detection of topological loops whenever handles are present in the geometry. A popular alternative strategy leverages Calderón identities to form a second kind integral equation out of the EFIE. Calderón approaches concurrently solve the low-frequency and the $h$-refinement breakdowns without calling for an explicit quasi-Helmholtz decomposition [19]–[26]. In their standard incarnations they do, however, require the use of a dual discretization and global loop handling, because global loops reside in the static null-space of the Calderón operator. The introduction of implicit quasi-Helmholtz decompositions via the so-called quasi-Helmholtz projectors [27], when combined with Calderón approaches, led to the design of several well-conditioned formulations, free from static nullspaces (see [7], [27]–[29] and references therein) and, in some incarnations, free from the need of performing a barycentric refinement [30]. Quasi-Helmholtz projectors have shown to be an effective and efficiently computable tool for performing quasi-Helmholtz decompositions, but, by themselves, they can only tackle the low-frequency breakdown and must be combined with Calderón-like strategies that involve multiple operators, to obtain $h$-refinement spectral preconditioning effects. A set of tools as versatile as the projectors that could also manipulate the operator spectra beyond a simple rescaling would thus be desirable.

This paper introduces such a new family of tools. The contribution of this work is in fact threefold: (i) we will introduce the concept of Laplacian-filtered Loop-Star decompositions, a new quasi-Helmholtz decomposition approach that will allow for a finer tuning of the operator spectrum with respect to their standard Loop-Star counterparts. (ii) Just like standard Loop-Star bases give rise to the quasi-Helmholtz projectors, a suitable choice of projections on the filtered Loop-Star spaces will give rise to a new family of mathematical objects,
the quasi-Helmholtz Laplacian filters, that will not require handling basis functions and explicit decompositions, while still providing the spectral tuning properties of (i). (iii) We will obtain new frequency and $h$-refinement preconditioners for the EFIE based on (i) and (ii) that represent a natural first application of the newly proposed techniques. We believe, however, that the applicability of the new spectral filters will extend beyond EFIE preconditioning in further investigations. The contribution will be further enriched by a section devoted to efficient implementations of the newly defined tools that will be obtained by leveraging strategies developed in the context of polynomial preconditioning approaches and in graph wavelet theory [31]–[34]. Numerical results will then corroborate and confirm our theoretical considerations.

The paper is organized as follows: the background material and the notation are presented in Section II, the new Laplacian filtered Loop-Star decompositions and the quasi-Helmholtz Laplacian filters are presented in Section III and Section IV, respectively, along with their main properties. Various strategies for computing the filters, in practical scenarios, are detailed in Section V. Preconditioners tackling simultaneously the low-frequency and $h$-refinement breakdowns of the EFIE are then derived in Section VI. Finer details relating to the implementation and computation of the filters and preconditioners are then presented in Section VII. Illustrations of the effectiveness of the schemes are provided in Section VIII, before concluding in Section IX.

Preliminary results from this work were presented in the conference contributions [35], [36].

II. NOTATION AND BACKGROUND

Let $\Gamma$ be a smooth surface modeling the boundary of a perfectly electrically conducting (PEC), closed scatterer enclosed in a homogeneous background medium with permittivity $\varepsilon$ and permeability $\mu$. The boundary $\Gamma$ can be multiply connected and contain holes. We denote by $\mathbf{n}(r)$ the outward pointing normal field at $r$. When illuminated by a time-harmonic incident electric field $E^i$, a surface current density $J$ is induced on $\Gamma$ that satisfies the electric field integral equation (EFIE)

$$\mathcal{T}J = T_s J + T_h J = -\mathbf{n} \times E^i,$$  \hspace{1cm} (1)

where

$$\mathcal{T}_s J = \mathbf{n}(r) \times \frac{i}{k} \int_{\Gamma} \frac{e^{ik\left|\mathbf{r} - \mathbf{r}'\right|}}{4\pi \left|\mathbf{r} - \mathbf{r}'\right|} J(r')dS(r'), \hspace{1cm} (2)$$

$$\mathcal{T}_h J = -\mathbf{n}(r) \times \frac{1}{ik} \int_{\Gamma} \frac{e^{ik\left|\mathbf{r} - \mathbf{r}'\right|}}{4\pi \left|\mathbf{r} - \mathbf{r}'\right|} \nabla \cdot J(r')dS(r'), \hspace{1cm} (3)$$

and $k$ is the wavenumber of the electromagnetic wave in the background medium. Equation (1) can be solved numerically by approximating $\mathcal{T}$ with triangular elements of average edge length $h$ and by approximating the current density as $J \approx \sum_{n=1}^{N} J_n f_n$ with the Rao-Wilton-Glisson basis functions $\{f_n\}_n$ [37], in which $N$ is the number of edges in the mesh, $j$ is the vector of the coefficients of the expansion, and $f_n$ is defined as

$$f_n(r) = \begin{cases} \frac{r - r_+^{n}}{2A_+^{n}} & \text{if } r \in c_+^{n} \\ \frac{r - r_-^{n}}{2A_-^{n}} & \text{if } r \in c_-^{n} \end{cases}, \hspace{1cm} (4)$$

where the notation of Fig. 1 was employed and where $A_+^{n}$ is the area of the cell $c_+^{n}$.

The final step to obtain the discretized EFIE is to test (1) with the rotated RWG functions $\{\mathbf{n} \times f_n\}$, which results in the linear system

$$Tj = (T_s + T_h)j = v,$$  \hspace{1cm} (5)

in which $[T_s]_{mn} = \langle \mathbf{n} \times f_m, T_s(f_n) \rangle$, $[T_h]_{mn} = \langle \mathbf{n} \times f_m, T_h(f_n) \rangle$, $[v]_m = \langle \mathbf{n} \times f_m, -\mathbf{n} \times E^i \rangle$, and $(\mathbf{a}, \mathbf{b}) = \int_{\Gamma} a \cdot b ds$. The EFIE can also be discretized on the dual mesh using dual functions defined on the barycentric refinement. Both Buffa-Christiansen [38] and Chen-Wilton [39] elements can be used for this dual discretization. For the sake of brevity, we will omit the explicit definitions of the dual elements that will be denoted by $\{g_n\}_n$ in the following; the reader can refer to [7] and references therein for a more detailed treatment. We will also need the definition of the standard and dual Gram matrices whose entries are $[G]_{imn} = \langle f_m, f_n \rangle$ and $[G^\perp]_{imn} = \langle g_m, g_n \rangle$. While they are not required for the discretization of the EFIE itself, we introduce the patch and pyramids scalar basis functions sets $\{p_n\}$ and $\{\lambda_n\}$, respectively composed of $N_S$ and $N_L$ functions, that will be required for some of the following developments. These functions are defined as

$$p_m(r) = \begin{cases} A_m^{1} & \text{if } r \in c_m \\ 0 & \text{otherwise} \end{cases}, \hspace{1cm} (6)$$

and

$$\lambda_m(r) = \begin{cases} 1 & \text{if } r = v_m \\ 0 & \text{if } r = v_n, n \neq m \end{cases}, \hspace{1cm} (7)$$

where $\{v_n\}_n$ are the vertices of the mesh. The number of these functions can be deduced from the mesh properties: $N_S$ is the number of mesh triangles and $N_L$ is the number of mesh vertices. The Gram matrices corresponding to these bases are $G_p$ for the patch functions and $G_p$ for the pyramids with $[G_p]_{imn} = \langle p_m, p_n \rangle$ and $[G^\perp]_{imn} = \langle \lambda_m, \lambda_n \rangle$. The dual of these functions, living in the barycentric refinement of the original mesh will also be required, and their definitions, omitted here for conciseness, can be found in [30]. The $N_L$ dual patches will be designated as $\{\tilde{p}_n\}_n$, the $N_S$ dual pyramids as $\{\tilde{\lambda}_n\}$, and the corresponding gram matrices as $G^\perp_p$ and $G^\perp$ with $[G^\perp_p]_{imn} = \langle \tilde{p}_m, \tilde{p}_n \rangle$ and $[G^\perp]_{imn} = \langle \tilde{\lambda}_m, \tilde{\lambda}_n \rangle$.

Because this contribution deals with discrete quasi-Helmholtz decompositions we will recall some of their properties. The continuous solution $J$ can be decomposed into a solenoidal, irrotational, and (on non simply-connected manifolds) harmonic components

$$J = \nabla \times \mathbf{n} \lambda + \nabla \times \mathbf{\phi} + h.$$  \hspace{1cm} (8)
defined on the two triangles $c_i^+$ and $c_i^-$ that are formed with their common edge $e_i$ and the vertices $r_i^+$ and $r_i^-$, respectively.

When $J$ is discretized by the approximate expansion in RWG functions, a discrete counterpart of (8) holds for the coefficient vector $j$

$$j = \Lambda l + \Sigma \sigma + Hh,$$

where $\Lambda \in \mathbb{R}^{N \times N_L}$ and $\Sigma \in \mathbb{R}^{N \times N_S}$ are the Loop-to-RWG and Star-to-RWG transformation matrices [9], [12], [40]–[42] defined, following the convention of Fig. 1 and the definition of the RWG in (4), as

$$[\Lambda]_{mn} = \begin{cases} 
1 & \text{if node } n \text{ equals } v_m^+, \\
-1 & \text{if node } n \text{ equals } v_m^-, \\
0 & \text{otherwise,}
\end{cases}$$

and

$$[\Sigma]_{mn} = \begin{cases} 
1 & \text{if the cell } n \text{ equals } c_m^+, \\
-1 & \text{if the cell } n \text{ equals } c_m^-, \\
0 & \text{otherwise.}
\end{cases}$$

With these definitions $\Lambda^T \Lambda$ and $\Sigma^T \Sigma$ are respectively the vertices- and the cells-based graph Laplacians [12]. The explicit use of the change of basis matrix $H$ will not be required and we omit here its explicit definition, for the sake of conciseness, which could however be found in [7] and references therein.

With the definitions above, the standard quasi-Helmholtz projectors [12], [27] are defined as

$$P_\Sigma = \Sigma (\Sigma^T \Sigma)^+ \Sigma^T,$$

$$P_{AH} = I - P_\Sigma, $$

for the primal ones,

$$P_\Lambda = \Lambda (\Lambda^T \Lambda)^+ \Lambda^T,$$

$$P_{\Sigma H} = I - P_\Lambda,$$

for the dual ones, and

$$P_H \equiv P_H = I - P_\Sigma - P_\Lambda$$

for the projector to quasi-harmonic subspace, where $^+$ denotes the Moore-Penrose pseudo-inverse.

III. LAPLACIAN FILTERED LOOP-STAR DECOMPOSITIONS

In this section, we will extend the notion of Loop-Star bases by introducing the concept of filtered (generating) functions. We will first treat graph-based decompositions (a direct generalization of the standard case) and we will then move on to their Gram matrix normalized counterparts that will be more effective in treating problems involving inhomogeneous meshes.

A. The Standard Case

Consider the singular value decomposition (SVD) [43] of a matrix $X \in \mathbb{R}^{N \times N}$,

$$X = U X S_X V_X^T \quad (15)$$

where $X$ is a placeholder for either $\Sigma$ or $\Lambda$, $U_X \in \mathbb{R}^{N \times N}$, $V_X \in \mathbb{R}^{N \times N}$, and $S_X \in \mathbb{R}^{N \times N}$. The matrices $U_X$ and $V_X$ are unitary and $S_X$ is a block diagonal matrix with the singular values $\sigma_{X,i}$ of $X$ as entries (in decreasing order). Clearly the SVD of $(X^T X)$ is $V_X S_X^2 S_X V_X^T$, and, by defining the diagonal matrix $L_{X,n}$, with $1 \leq n \leq N$, such that

$$[L_{X,n}]_{ii} = \begin{cases} 
\sigma_{X,i} & \text{if } i > N_x - n, \\
0 & \text{otherwise,}
\end{cases} \quad (16)$$

we define the filtered graph Laplacians

$$(X^T X)_n := V_X L_{X,n} S_X V_X^T, \quad (17)$$

from which we introduce the filtered Loop-to-RWG and filtered Star-to-RWG matrices we propose in this work

$$\Sigma_n = \Sigma (\Sigma^T \Sigma)^+ (\Sigma^T \Sigma)_n, \quad (18)$$

$$\Lambda_n = \Lambda (\Lambda^T \Lambda)^+ (\Lambda^T \Lambda)_n. \quad (19)$$

These matrices contains the coefficients of sets of linearly dependent filtered Loop-Star functions.

Properties: We now study some properties of the filtered Loop-Star matrices. Because $\Sigma^T \Lambda = 0$ [7], we have $\forall n, m$

$$\Sigma_n^T \Lambda_m = (\Sigma^T \Sigma)_n (\Sigma^T \Sigma)^+ (\Sigma^T \Sigma)_m = 0. \quad (20)$$

Otherwise said, the new filtered Loop-Star functions are coefficient-orthogonal ($l^2$-orthogonal) like their non-filtered, standard counterparts.

From the definition of $L_{X,n}$ in (16), it follows that

$$L_{X,n} L_{X,m} = L_{X,\min(n,m)}. \quad (17)$$

Thus from (17)

$$(X^T X)_n (X^T X)_m = V_X L_{X,n} S_X V_X^T V_X L_{X,m} S_X V_X^T$$

$$= V_X L_{X,n} L_{X,m} S_X V_X^T = V_X L_{X,\min(n,m)} L_{X,\min(n,m)} S_X V_X^T \quad (21)$$

$$= (X^T X)^{2\min(n,m)}.$$

We thus have

$$\Sigma_n^T \Sigma_n = (\Sigma^T \Sigma)_n (\Sigma^T \Sigma)^+ (\Sigma^T \Sigma)_n = (\Sigma^T \Sigma)^+(\Sigma^T \Sigma)(\Sigma^T \Sigma)^+ (\Sigma^T \Sigma)_n$$

$$= (\Sigma^T \Sigma)^+(\Sigma^T \Sigma)(\Sigma^T \Sigma)_{\min(n,m)} (\Sigma^T \Sigma)_{\min(n,m)} \quad (22)$$

$$= \Sigma^T_{\min(n,m)} \Sigma_{\min(n,m)}. \quad (23)$$

Similarly,

$$\Lambda_n^T \Lambda_n = \Lambda_{\min(n,m)}^T \Lambda_{\min(n,m)}. \quad (23)$$

Given integers such that $m < n < p < q$, the property

$$(\Sigma_m - \Sigma_n)^T (\Sigma_p - \Sigma_q) =$$

$$\Sigma_m^T (\Sigma_p - \Sigma_q) - \Sigma_n^T (\Sigma_p - \Sigma_q) = 0; \quad (24)$$

Fig. 1: Convention used for the RWGs: each function is defined on the two triangles $c_i^+$ and $c_i^-$ that are formed with their common edge $e_i$ and the vertices $r_i^+$ and $r_i^-$, respectively.
holds and, similarly,

\[ (\Lambda_m - \Lambda_n)^T (\Lambda_p - \Lambda_q) = 0. \]  

(25)

Properties (24) and (25) show that non-intersecting differences of filtered Star or Loop bases are mutually orthogonal (and thus generate linearly independent spaces), a property that will be useful to build invertible changes of basis, as will be shown in Section VI-A.

B. Generalization for Non-homogeneously Meshed Geometries

When the filtered Loop-Star decompositions are to be used on geometries with non-homogenous discretizations, both the standard discretizations of the EFIE and the graph Laplacian matrices may lead to suboptimal performance and a proper normalization with Gram matrices must be employed. In this context, we define the normalized EFIE electromagnetic operator matrices

\[ \tilde{T} = G^{-1/2}T\Gamma G^{-1/2}, \]  

(26)

\[ \tilde{T}_s = G^{-1/2}T_s G^{-1/2}, \]  

(27)

\[ \tilde{T}_h = G^{-1/2}T_h G^{-1/2}, \]  

(28)

and the normalized Loop and Star matrices

\[ \tilde{\Sigma} = G^{-1/2}\Sigma G_{p}^{-1/2}, \]  

(29)

\[ \tilde{\Lambda} = G^{1/2}\Lambda G_{\lambda}^{-1/2}. \]  

(30)

Following the same strategy as in (18) and (19), the normalized filtered Loop-Star matrices are consistently defined as

\[ \tilde{\Sigma}_n = \tilde{\Sigma} \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)^{-1} \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)_n, \]  

(31)

\[ \tilde{\Lambda}_n = \tilde{\Lambda} \left( \tilde{\Lambda}^T \tilde{\Lambda} \right)^{-1} \left( \tilde{\Lambda}^T \tilde{\Lambda} \right)_n. \]  

(32)

When dealing with dual Loop-Star decomposition matrices, the normalization is different from that of the primal ones, and the dually-normalized Loop and Star transformation matrices are defined as

\[ \tilde{\Sigma} = G^{1/2}\Sigma G_{\lambda}^{-1/2}, \]  

(33)

\[ \tilde{\Lambda} = G^{-1/2}\Lambda G_{p}^{1/2}, \]  

(34)

and the associated filtered decomposition matrices as

\[ \tilde{\Sigma}_n = \tilde{\Sigma} \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)^{-1} \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)_n, \]  

(35)

\[ \tilde{\Lambda}_n = \tilde{\Lambda} \left( \tilde{\Lambda}^T \tilde{\Lambda} \right)^{-1} \left( \tilde{\Lambda}^T \tilde{\Lambda} \right)_n. \]  

(36)

Properties: The primal and dual normalized Loop-Star bases keep satisfying the orthogonality properties

\[ \tilde{\Lambda}^T \tilde{\Sigma} = G_{\lambda}^{-1/2} \tilde{\Lambda}^T G^{1/2} G^{-1/2} \Sigma G_{p}^{1/2} = 0, \]  

(37)

\[ \tilde{\Sigma}^T \tilde{\Lambda} = G_{p}^{1/2} \Sigma^T G^{-1/2} G^{1/2} \Lambda G_{\lambda}^{-1/2} = 0, \]  

(38)

because \( \Sigma^T \Lambda = 0 \). Moreover, because (21) holds, we obtain, similarly to Section III-A, that

\[ \tilde{\Sigma}^T_n \tilde{\Sigma}_n = \Sigma^T_{\min(n,m)} \Sigma_{\min(n,m)}, \]  

(39)

\[ \tilde{\Lambda}^T_n \tilde{\Lambda}_n = \Lambda^T_{\min(n,m)} \Lambda_{\min(n,m)}, \]  

(40)

\[ \tilde{\Sigma}^T_n \tilde{\Lambda}_n = \Sigma^T_{\min(n,m)} \Lambda_{\min(n,m)}, \]  

(41)

\[ \tilde{\Sigma}^T_n \tilde{\Lambda}_n = \Sigma^T_{\min(n,m)} \Sigma_{\min(n,m)}. \]  

(42)

Using these properties and the same reasoning as previously, the counterparts of the properties of the non-normalized filtered Loop-Star matrices can be obtained. In particular the counterparts of (24) and (25) can be obtained by replacing each matrix with its normalized ("tilde") counterpart.

IV. QUASI HELMHOLTZ LAPLACIAN FILTERS

Although explicit quasi-Helmholtz decomposition bases are useful in applications in which a direct access to the Helmholtz components of the current is required, oftentimes, especially when the main target is preconditioning and regularization, implicit Helmholtz decompositions can be more efficient. An implicit Helmholtz decomposition was obtained in [27], where the concept of quasi-Helmholtz projector was introduced. Following a similar philosophy, and leveraging the filtered Loop-Star functions introduced above, we can now define quasi-Helmholtz Laplacian filters.

A. The Standard Case

The idea behind the projectors was to obtain a basis-free quasi-Helmholtz decomposition that would not worsen the conditioning of the original equation. If we follow the definitions (12) and (13) by replacing the standard Star basis with the new filtered sets, we obtain

\[ \Sigma_n \left( \Sigma^T \Sigma \right)_n \Sigma^T = \Sigma \left( \Sigma^T \Sigma \right)^{-1} \left( \Sigma^T \Sigma \right)_n \]  

(43)

and, similarly,

\[ \Lambda_n \left( \Lambda^T \Lambda \right)_n \Lambda^T = \Lambda \left( \Lambda^T \Lambda \right)^{-1} \Lambda^T. \]  

(44)

This justifies the following definitions of the new primal filters

\[ P_{\Sigma}^n = \Sigma \left( \Sigma^T \Sigma \right)^{-1} \Sigma^T, \]  

(45)

\[ P_{\Lambda}^{AH} = \Lambda \left( \Lambda^T \Lambda \right)_n \Lambda^T + I - P_{\Sigma} - P_{\Lambda}, \]  

(46)

and dual filters

\[ P_{\Sigma}^{AH} = \Sigma \left( \Sigma^T \Sigma \right)_n \Sigma^T + I - P_{\Lambda} - P_{\Sigma}. \]  

(47)

The reader should note that, in the special case of simply connected geometries \( P_{\Lambda}^{AH} = \Lambda \left( \Lambda^T \Lambda \right)_n \Lambda^T \) and \( P_{\Sigma}^{AH} = \Sigma \left( \Sigma^T \Sigma \right)_n \Sigma^T \) since \( P_{\Lambda} + P_{\Sigma} = I \). Moreover, by construction,

\[ P_{\Sigma}^{N} = P_{\Sigma}, \]  

(49)

\[ P_{\Lambda}^{N} = P_{\Lambda}, \]  

(50)
and thus
\[
\mathbf{P}^{\Lambda H}_{\Sigma H} = \mathbf{P}^{\Lambda} + \mathbf{I} - \mathbf{P}^{\Sigma} - \mathbf{P}^{\Lambda} = \mathbf{P}^{\Lambda H},
\]
\[
\mathbf{P}^{\Sigma H} = \mathbf{P}^{\Sigma} + \mathbf{I} - \mathbf{P}^{\Lambda} - \mathbf{P}^{\Sigma} = \mathbf{P}^{\Sigma H},
\]
which means that, with these definitions, the quasi-Helmholtz Laplacian filters converge to the standard quasi-Helmholtz projectors when the Laplacian is unfiltered \((n = N_{x})\).

**Properties:** From these definitions, a few useful properties of the quasi-Helmholtz Laplacian filters can be derived and will be summarized here. First, the filters still behave as projectors since
\[
\mathbf{P}^{\Sigma}_{n} \mathbf{P}^{\Sigma}_{n} = \Sigma_{n} \left( \Sigma^{T} \Sigma \right)_{n}^{+} \Sigma^{T} \Sigma \left( \Sigma^{T} \Sigma \right)_{n}^{+} \Sigma^{T} = \Sigma_{n} \left( \Sigma^{T} \Sigma \right)_{n}^{+} \Sigma^{T} = \mathbf{P}^{\Sigma},
\]
\[
\mathbf{P}^{\Lambda}_{n} \mathbf{P}^{\Lambda}_{n} = \Lambda_{n} \left( \Lambda^{T} \Lambda \right)_{n}^{+} \Lambda^{T} \Lambda \left( \Lambda^{T} \Lambda \right)_{n}^{+} \Lambda^{T} = \Lambda_{n} \left( \Lambda^{T} \Lambda \right)_{n}^{+} \Lambda^{T} = \mathbf{P}^{\Lambda},
\]

Moreover, \(\forall m < n < p < q\), we have the following orthogonality property
\[
\left( \mathbf{P}^{\Sigma}_{m} - \mathbf{P}^{\Sigma}_{n} \right) \left( \mathbf{P}^{\Sigma}_{p} - \mathbf{P}^{\Sigma}_{q} \right) = \left( \Sigma_{m} \left( \Sigma^{T} \Sigma \right)_{m}^{+} \Sigma^{T} - \Sigma_{n} \left( \Sigma^{T} \Sigma \right)_{n}^{+} \Sigma^{T} \right) \left( \Sigma_{p} \left( \Sigma^{T} \Sigma \right)_{p}^{+} \Sigma^{T} - \Sigma_{q} \left( \Sigma^{T} \Sigma \right)_{q}^{+} \Sigma^{T} \right) = \Sigma_{m} \left( \Sigma^{T} \Sigma \right)_{m}^{+} \Sigma^{T} - \Sigma_{n} \left( \Sigma^{T} \Sigma \right)_{n}^{+} \Sigma^{T}
\]
\[
+ \Sigma_{p} \left( \Sigma^{T} \Sigma \right)_{p}^{+} \Sigma^{T} - \Sigma_{q} \left( \Sigma^{T} \Sigma \right)_{q}^{+} \Sigma^{T} = \mathbf{0},
\]
where (21) has been used. In a similar way, one can prove that
\[
\left( \mathbf{P}^{\Lambda}_{m} - \mathbf{P}^{\Lambda}_{n} \right) \left( \mathbf{P}^{\Lambda}_{p} - \mathbf{P}^{\Lambda}_{q} \right) = \mathbf{0}.
\]

Moreover, given that \(\mathbf{P}^{\Lambda H} = \mathbf{P}^{\Lambda H} = \mathbf{P}^{\Lambda} - \mathbf{P}^{\Lambda}_{m}\) and \(\mathbf{P}^{\Sigma H} = \mathbf{P}^{\Sigma H} = \mathbf{P}^{\Sigma} - \mathbf{P}^{\Sigma}_{m}\) \(\forall m, n\)—which can be deduced from (46) and (48)—the remaining properties
\[
\left( \mathbf{P}^{\Lambda H} - \mathbf{P}^{\Lambda H} \right) \left( \mathbf{P}^{\Lambda H} - \mathbf{P}^{\Lambda H} \right) = \mathbf{0},
\]
\[
\left( \mathbf{P}^{\Sigma H} - \mathbf{P}^{\Sigma H} \right) \left( \mathbf{P}^{\Sigma H} - \mathbf{P}^{\Sigma H} \right) = \mathbf{0}
\]
follow. All the properties listed above, will be useful when building invertible transforms, similarly to their basis-based counterpart (24).

**B. Generalization for Non-homogeneously Meshed Geometries**

The definitions of the normalized Loop and Star matrices in (29) and (30) suggest the following definition for the associated normalized quasi-Helmholtz projectors
\[
\hat{\mathbf{P}}^{\Sigma} = \hat{\Sigma} \left( \hat{\Sigma}^{T} \hat{\Sigma} \right)^{+} \hat{\Sigma}^{T} = \Lambda \left( \Lambda^{T} \Lambda \right)^{+} \Lambda^{T}.
\]

Moreover, as is proved in Appendix A, the complementarity property
\[
\hat{\mathbf{P}}^{\Sigma} = I - \hat{\mathbf{P}}^{\Lambda}
\]
holds on simply connected geometries; on general geometries and together with definitions (31) and (32), this justifies the following definition for the normalized quasi-Helmholtz Laplacian filters
\[
\hat{\mathbf{P}}^{\Sigma} = \hat{\Sigma} \left( \hat{\Sigma}^{T} \hat{\Sigma} \right)^{+} \hat{\Sigma}^{T},
\]
\[
\hat{\mathbf{P}}^{\Lambda} = \Lambda \left( \Lambda^{T} \Lambda \right)^{+} \Lambda^{T}.
\]

By analogy, we can define the normalized dual quasi-Helmholtz projectors as
\[
\hat{\mathbf{P}}^{\Lambda} = \hat{\Lambda} \left( \hat{\Lambda}^{T} \hat{\Lambda} \right)^{+} \hat{\Lambda}^{T},
\]
\[
\hat{\mathbf{P}}^{\Sigma} = \hat{\Sigma} \left( \hat{\Sigma}^{T} \hat{\Sigma} \right)^{+} \hat{\Sigma}^{T},
\]
with the property
\[
\hat{\mathbf{P}}^{\Lambda} = I - \hat{\mathbf{P}}^{\Sigma}
\]
holding on simply connected geometries (see Appendix A for the proof). Thus, dually to the primal case, we define, on general geometries,
\[
\hat{\mathbf{P}}^{\Lambda} = \hat{\Lambda} \left( \hat{\Lambda}^{T} \hat{\Lambda} \right)^{+} \hat{\Lambda}^{T},
\]
\[
\hat{\mathbf{P}}^{\Sigma} = \hat{\Sigma} \left( \hat{\Sigma}^{T} \hat{\Sigma} \right)^{+} \hat{\Sigma}^{T} + I - \hat{\mathbf{P}}^{\Lambda} - \hat{\mathbf{P}}^{\Sigma}.
\]

**Properties:** Since the primal and dual normalized Loop-Star bases still satisfy the orthogonality properties (37) and (38) and because of the properties (39)-(42), the same reasoning yields all counterparts of the properties (53)-(62), after replacing each matrix with its normalized (“tilde”) counterpart.

**V. Efficient Filtering Algorithms**

The definitions of the filtered Loop and Star functions and of the quasi-Helmholtz Laplacian filters in Sections III and IV involve an SVD which, while ensuring a clear and compact theoretical treatment, is in general computationally inefficient. This section will be devoted to presenting algorithms allowing for SVD-free matrix-vector products for the filtered graph Laplacians \(\left( \Sigma^{T} \Sigma \right)_{n}\) and \(\left( \Lambda^{T} \Lambda \right)_{n}\), which are the two key operations on both approaches presented in the previous section. Moreover, while our treatment will deal with the graph matrices \(\Sigma\) and \(\Lambda\), it is intended that substantially the same strategies can be applied when replacing those matrices with their normalized counterparts \(\Sigma\) and \(\Lambda\) with
minor modifications. In fact the additional products with the inverse square roots of (well-conditioned) Gram matrices can be obtained efficiently by using matrix function strategies [44].

A. Power Method Filtering

For filters with a filtering index that is independent on the total number of degrees of freedom, preconditioned inverse power methods [43] yield the last singular vectors and singular values of the $\Sigma^T \Sigma$ and $\Lambda^T \Lambda$ matrices at the price of a constant number of matrix-vector products. Given that the matrices involved are sparse, the resulting method is linear in complexity and the filtered projectors can be efficiently obtained. These schemes are well known and we do not provide extensive details here for the sake of brevity. We just mention that a special care should be put into using this schemes in the presence of degenerate spectra (arising from symmetries for example); under these conditions, the scheme presented in the following section should rather be preferred.

B. Butterworth Matrix Filters

An alternative strategy for the previous scenario, i.e. when a filter is needed that has filtering index which is independent on the total number of degrees of freedom, is provided by a matrix function and filtering approach. Given a scalar (squared) Butterworth filter of positive order $m$ and cutoff parameter $x_c > 0$, characterized by

$$f_{m, x_c}(x) = (1 + (x/x_c)^m)^{-1}, \quad x \geq 0,$$

the spectrum of a symmetric positive matrix $A \in \mathbb{R}^{N \times N}$ composed of the set of singular values $\{\sigma_i(A)\}$, can be filtered by generalizing $f_{m, x_c}$ to matrix arguments and applying it to $A$, yielding the filtered matrix

$$A_{\text{filt}} := f_{m,x_c}(A) = (1 + (A/x_c)^m)^{-1} ,$$

with singular values $\{f_{m,x_c}(\sigma_i(A))\}_i$. The filtered matrix $(\Sigma^T \Sigma)_n$ can now be expressed as

$$(\Sigma^T \Sigma)_n = (\Sigma^T \Sigma) \lim_{m \to \infty} f_{m, \sigma_n(\Sigma^T \Sigma)} (\Sigma^T \Sigma).$$

(75)

The presence of high exponents in (75) may render its computation unstable. Hence we propose to use the following factorization formula that leverages the roots of unity

$$\lim_{m \to \infty} \prod_{k=1}^{m} \left( \frac{\Sigma^T \Sigma}{\sigma_n(\Sigma^T \Sigma)} - e^{(2k+1)i\pi/N} I \right)^{-1}.$$

(76)

For practical purposes the infinite products in this expression can be truncated at the desired precision. Regarding the value of $\sigma_n(\Sigma^T \Sigma)$, an approximation can be obtained either with ad-hoc heuristics or by the approximation $\sigma_n(\Sigma^T \Sigma) \approx (N_s - n)/\| \Sigma^T \Sigma \|^T$. Finally, when the filtering point is a constant with respect to the number of unknowns, a multigrid approach is effective in providing the inverse required by (76).

C. Filter Approximation via Chebyshev Polynomials

When the filtering index is proportional to the number of unknowns, the computational burden of the two methods above can become high. In this regime we can leverage the ideas of polynomial preconditioning and graph wavelets [31–34] and adopt a method based on a polynomial expansion of the spectral filter.

Because we are interested in cases in which the filtering index is proportional to the number of degrees of freedom (for instance, $n = N_S/2$) we can leverage a polynomial approximation of $f_{m, x_c}$ on the interval $[0, \sigma_N(\Sigma^T \Sigma)]$; a natural basis for this approximation is that of the Chebyshev polynomials $\{T_n(x)\}_n$, defined by the recurrence relation

$$T_n(x) = \begin{cases} 1 & \text{if } n = 0 \\ 2xT_{n-1}(x) - T_{n-2}(x) & \text{if } n = 1 \\ \text{otherwise} \end{cases}$$

(77)

The approximated filtered matrix now reads

$$(\Sigma^T \Sigma)_n \approx -\frac{c_0}{2} I + \sum_{k=1}^{n_c} c_k T_{k} \left( \frac{\Sigma^T \Sigma}{\sigma_n(\Sigma^T \Sigma)} \right),$$

(78)

where the $c_n$ are the expansion coefficients of $f_{m, \sigma_n(\Sigma^T \Sigma)}$ in the basis of the first $n_c + 1$ Chebyshev polynomials. Algorithms for their computation can be found, among others, in [45]. Because the cutoff frequency of this filter is proportional to the number of unknowns and so is the domain size, the order of the polynomial that is required to obtain a given approximation of the Butterworth filter, will not need to be changed with increasing discretizations. In other words, the filters obtained by following this approach will require the same number of sparse matrix-vector multiplication for increasing discretization when the filtering index will be proportional to the number of degrees of freedom. It should be noted that in the transition region between the filters described in the previous two sections (constant filtering index) and the scenario described here (filtering index will be proportional to the number of degrees of freedom) the Chebyshev approach decreases in efficiency and further treatments may be required [34].

VI. A First Application Case Scenario: Laplacian Filter Based Preconditioning

As a first application case scenario of the new filters introduced here, we will develop two families of preconditioners for the EFIE in (5). This equation is known to suffer from ill-conditioning both for decreasing frequency and average mesh length $h$ (phenomena known as the low-frequency and $h$-refinement breakdowns, respectively, see [7] and references therein). In the following we will cure both breakdowns by developing preconditioners based both on filtered functions decompositions and on quasi-Helmholtz Laplacian filters.

The reader should note that in this Section and in the subsequent ones, we will study the singular value spectrum of potentially singular matrices. When dealing with such matrices, the condition number will be defined as $\text{cond}(A) = \|A\| \|A^+\|$. Moreover, inverse powers of singular matrices in the following will always denote the corresponding positive power of the pseudoinverse of the matrix.
A. Filtered Bases Approach

The primal and dual Laplacians can be used to precondition the single layer and the hypersingular operator [1], [18], [46], [47], thus \( V_\Lambda \) and \( V_\Sigma \) followed by a diagonal preconditioning are valid bases for regularizing the vector and scalar potential parts of the EFIE. In particular, for \( T_h \), this results from the fact that an operator spectrally equivalent to the single layer can be obtained from \( T_h \). In fact, noticing that \( T_h = \Sigma R \Sigma^T \) [48], where \( R \) is the patch-function discretization of the single layer operator, i.e. \( [R]_{mn} = (p_m, S p_n) \) with

\[
(\mathcal{S}_p)(r) := \int_{\Gamma} \frac{e^{ik||r-r'||}}{4\pi ||r-r'||} p(r')dS(r'),
\]

and defining \( \tilde{R} := G_p^{-1/2} R G_p^{-1/2} \), we obtain \( \tilde{T}_h = \tilde{\Sigma} \tilde{R} \tilde{\Sigma}^T \).

The equivalence between \( (\tilde{\Sigma}^T \tilde{\Sigma})^+ \tilde{\Sigma}^T \tilde{T}_h \tilde{\Sigma} (\tilde{\Sigma}^T \tilde{\Sigma})^+ \) and \( \tilde{R} \tilde{T} \) thus follows. To conclude the reasoning, we note that, because

\[
(\tilde{\Sigma}^T \tilde{\Sigma})^{1/4} \tilde{R} (\tilde{\Sigma}^T \tilde{\Sigma})^{1/4} = \tilde{V}_\Sigma \left( \tilde{S}_\Sigma^T \tilde{S}_\Sigma \right)^{1/4} \tilde{V}_\Sigma \tilde{V}_\Sigma^T \tilde{V}_\Sigma \left( \tilde{S}_\Sigma^T \tilde{S}_\Sigma \right)^{1/4} \tilde{V}_\Sigma^T,
\]

is well conditioned for increasing discretization—as a consequence of the results proven in [47], since \( \tilde{\Sigma}^T \tilde{\Sigma} \) is a valid discretization of a Laplacian matrix [49]—we have

\[
\left. \begin{array}{l}
\text{cond} \left( \tilde{V}_\Sigma \left( \tilde{S}_\Sigma^T \tilde{S}_\Sigma \right)^{1/4} \tilde{V}_\Sigma^T \tilde{\Sigma}^T \tilde{T}_h \tilde{\Sigma} \right) = 1, \quad h \to 0.
\end{array} \right\}
\]

This preconditioning strategy can be slightly altered to leverage the filtered basis presented in Section III by introducing an additional Laplacian in (81) and adjusting the exponent of \( \tilde{S}_\Sigma^T \tilde{S}_\Sigma \) accordingly. In particular, we have

\[
\tilde{\Sigma} \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)^+ \tilde{V}_\Sigma \tilde{S}_\Sigma^T \tilde{S}_\Sigma \tilde{V}_\Sigma \left( \tilde{S}_\Sigma^T \tilde{S}_\Sigma \right)^{3/4} \tilde{V}_\Sigma^T = 1, \quad h \to 0.
\]

Finally, thanks to the properties introduced in Section III, we have

\[
\tilde{V}_\Sigma \tilde{S}_\Sigma^T \tilde{S}_\Sigma \tilde{V}_\Sigma = \sum_{i=2}^{N_{S,\alpha}} \tilde{S}_{\alpha-i-1} \left[ D_{\Sigma} \right]^{-3/4}_{N_{S,\alpha} - \alpha - 1 + 1} + \tilde{S}_{\alpha} \tilde{S}_\Sigma^T \tilde{S}_\Sigma \tilde{V}_\Sigma \tilde{D}_{\Sigma,\alpha}^{-3/4} \tilde{V}_\Sigma^T.
\]

with \( f_{\tilde{v}}(i) = N_{S} - \alpha^{\log_{\alpha}(N_{S} - i + 1)} + 1 \). Note that the construction of this matrix only requires explicit knowledge of \( \log_{\alpha}(N_{S}) \) terms of \( D_{\Sigma} \). Few passages—omitted here—suffice to show that

\[
\text{cond} \left( \tilde{D}_{\Sigma,\alpha}^1 \tilde{V}_\Sigma \tilde{S}_\Sigma^T \tilde{T}_h \tilde{S}_\Sigma \tilde{V}_\Sigma \tilde{D}_{\Sigma,\alpha}^1 \right) = 0(\alpha) = O(1), \quad h \to 0.
\]

This approach would require the computation of the matrix \( \tilde{V}_\Sigma \tilde{S}_\Sigma \tilde{V}_\Sigma \tilde{S}_\Sigma \), which are prohibitively expensive to obtain. A key observation, however, is that we do not need to use the entire diagonal of \( \tilde{S}_\Sigma \), but a logarithmic sampling of it will suffice. In other words, define \( D_{\Sigma} \) the vector containing the entries of the diagonal of \( \tilde{S}_\Sigma^T \tilde{S}_\Sigma \) and define the block diagonal matrix

\[
\tilde{D}_{\Sigma,\alpha} = \text{diag} \left( [D_{\Sigma}]_{N_{S} - N_{S,\alpha} + 1}^N, [D_{\Sigma}]_{N_{S} - N_{S,\alpha} + 1}^{N_{S,\alpha}}, \ldots, [D_{\Sigma}]_{N_{S}}^1 \right),
\]

where \( N_{S,\alpha} = \alpha^{\log_{\alpha}(N_{S})} \), \( N_{S,\alpha}^\text{rem} = N_{S} - (1 - N_{S,\alpha}) \), and \( I_n \) is the identity matrix of size \( n \), or, more programatically,

\[
\left. \begin{array}{l}
[D_{\Sigma}]_{\alpha} = [D_{\Sigma}]_{f_{\tilde{v}}(i)},
\end{array} \right\}
\]

and

\[
\tilde{\Sigma} \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)^+ \tilde{V}_\Sigma \tilde{D}_{\Sigma,\alpha}^{-3/4} \tilde{V}_\Sigma^T = O(1), \quad h \to 0.
\]

A similar reasoning for \( \tilde{T}_h \) following from the preconditioning of the hypersingular operator, leads to

\[
\left. \begin{array}{l}
\text{cond} \left( \tilde{S}_\Lambda^T \tilde{S}_\Lambda \right)^{-1/4} \tilde{V}_\Lambda \tilde{A}^T \tilde{T}_h \tilde{A} \tilde{V}_\Lambda \left( \tilde{S}_\Lambda^T \tilde{S}_\Lambda \right)^{-1/4} = O(1)
\end{array} \right\}
\]

and

\[
\left. \begin{array}{l}
\text{cond} \left( \tilde{A}_p \tilde{T}_h \tilde{A}_p \right) = O(1), \quad h \to 0.
\end{array} \right\}
\]
where
\[
\tilde{A} \left( \tilde{A}^T \tilde{A} \right) + \tilde{V}_\alpha \tilde{D}_{\alpha}^{-1/4} \tilde{V}_\alpha^T = \sum_{i=2}^{N_{\alpha}} \left( \tilde{A}_{\alpha,i-1} - \tilde{A}_\alpha \right) \left[ D_{\alpha} \right]_{N_{\alpha},-\alpha i-1+1}^{-1/4} + \left( \tilde{A} - \tilde{A}_\alpha \right) \left[ D_{\alpha} \right]_{N_{\alpha},-\alpha i-1+1}^{-1/4} =: \tilde{A}_{p,\alpha},
\]
and
\[
\tilde{D}_{\alpha} = \text{diag} \left( \left[ D_{\alpha} \right]_{N_{\alpha}-N_{\alpha}+1}^{N_{\alpha} \text{rem}}, \ldots, \left[ D_{\alpha} \right]_{N_{\alpha} \text{rem}} I_{1} \right),
\]
with \( N_{\alpha} = N_{\alpha} - (1 - N_{\alpha})(1 - \alpha)^{-1} \). \( \tilde{A} \) the vector containing the elements of the diagonal of \( \tilde{S}^T \tilde{A} \), and \( N_{\alpha} = \alpha \log_{10}(N_{\alpha}) \).

The previous preconditioners can then be combined to obtain a complete regularization of the EFIE system, for both low-frequency and h-refinement breakdowns, that reads
\[
\tilde{W}_j^T \tilde{T} \tilde{W}_j = \tilde{W}_j^T \tilde{V},
\]
where \( \tilde{\nu} = G^{-1/2} \tilde{v}, j = G^{-1/2} \tilde{W}_j, \tilde{W} = \left[ -\sqrt{c_{\alpha}} \tilde{A}_{p,\alpha}, \sqrt{c_{\alpha}} \tilde{S} \right], c_{\alpha} = \| \tilde{S}^T \tilde{A} \tilde{h} \|_{\tilde{S} \tilde{p},\alpha}^{-1}, c_{\alpha} = \| \tilde{A}_{p,\alpha} \|_{\tilde{h} \tilde{A}_{p,\alpha}}^{-1} \), and where we assume that the appropriate number of columns have been removed from \( \tilde{S} \) and \( \tilde{A}_{p,\alpha} \) (e.g. 1 column must be removed from each for a simply connected, closed scatterer) to account for the linear dependence in the underlying Loop and Star bases [8], as is done in standard Loop-Star preconditioning. The reader should note that, as in the case of standard Loop-Star functions, this operations will create a small number of isolated singular values, that however will not impact the convergence properties of the preconditioned equation. This effect will not be present instead in the scheme of next Section. The h-refinement regularization effect of this preconditioner can be deduced from the previous derivations for each of the potentials [50]. The low frequency regularization, can be demonstrated following the same reasoning as for standard Loop-Star approaches [7], since the new filtered bases retain the crucial properties that make Loop-Star so adapted low-frequency regularization in the first place—\( \tilde{A}_{p,\alpha} \tilde{T}_h = 0, \tilde{T}_h \tilde{A}_{p,\alpha} = 0 \), and \( \tilde{A}_{p,\alpha} \tilde{S}_{p,\alpha} = 0 \). Finally, we have
\[
\text{cond} \left( \tilde{W}_j^T \tilde{W} \right) = O(1), \text{ when } h \to 0, k \to 0.
\]

**B. Quasi-Helmholtz Filters Approach**

In several application scenarios, an explicit quasi-Helmholtz decomposition, such as the Loop-Star decomposition, is not necessary, and quasi-Helmholtz projects [7] could be used instead. Similarly, instead of using filtered Loop-Star preconditioning approaches, basis-free approaches, based on the quasi-Helmholtz Laplacian filters, will often be more effective. This Section will explore this approach that, as an additional advantage, will also have the avoidance of the burden of global-loop detection for multiply connected scatterers.

Following the same philosophy as in Section VI-A, we will form preconditioners for the solenoidal part of \( \tilde{T}_s \) and for \( \tilde{T}_h \) that will then be combined into a full EFIE preconditioner. We can transition from a basis-based Helmholtz decomposition to a projector based Helmholtz decomposition by leveraging the correspondences between \( \tilde{S} \) and \( \tilde{A} \) and their respective projectors \( \tilde{P}^\Sigma \) and \( \tilde{P}^\Lambda \). In particular, because \( \tilde{B}_\Sigma \) was a valid preconditioner for \( \tilde{T}_h \) (equations (89) and (90)), \( [\tilde{B}_\Sigma \ 0] \), once applied left and right to \( \tilde{T}_h \) will yield a block diagonal matrix which is well conditioned away from its large nullspace. This, in turns, means that \( [\tilde{C}_\Sigma \ 0] \), with \( \tilde{C}_\Sigma = \tilde{S} \left( \tilde{S}^T \tilde{S} \right)^{+} \tilde{V}_\Sigma \tilde{D}_{\Sigma}^{-5/4} \tilde{V}_\Sigma^T \tilde{D}_{\Sigma}^{1/2} \), will also yield a well-conditioned (up to its nullspace) matrix. Finally, because multiplications by unitary matrices do not compromise conditioning properties, we can form the preconditioner
\[
\tilde{S} \left( \tilde{S}^T \tilde{S} \right)^{+} \tilde{V}_\Sigma \tilde{D}_{\Sigma}^{-5/4} \tilde{V}_\Sigma^T \tilde{D}_{\Sigma}^{1/2} 0 \tilde{U}_\Sigma = \tilde{S} \left( \tilde{S}^T \tilde{S} \right)^{+} \tilde{V}_\Sigma \tilde{D}_{\Sigma}^{-1/4} \tilde{V}_\Sigma^T \tilde{S}^T \tilde{S}.
\]

This allows us to form the preconditioner \( \tilde{Q}_{p,\alpha}^\Sigma \) of additive Schwarz type, based on quasi-Helmholtz filters
\[
\tilde{S} \left( \tilde{S}^T \tilde{S} \right)^{+} \tilde{V}_\Sigma \tilde{D}_{\Sigma}^{-1/4} \tilde{V}_\Sigma^T \tilde{S} = \sum_{i=2}^{N_{\alpha}} \left( \tilde{P}_i^\Sigma \tilde{P}_i^\Sigma - \tilde{P}_{i-1}^\Sigma \tilde{P}_{i-1}^\Sigma \right) \left[ D_{\Sigma} \right]_{N_{\alpha},-\alpha i+1}^{-1/4} + \left( \tilde{P}_i^\Sigma - \tilde{P}_{i-1}^\Sigma \right) \left[ D_{\Sigma} \right]_{N_{\alpha},-\alpha i+1}^{-1/4}
\]
for which
\[
\text{cond} \left( \tilde{Q}_{p,\alpha}^\Sigma \tilde{T}_h \tilde{Q}_{p,\alpha}^\Sigma \right) = O(1), \text{ when } h \to 0.
\]

Similarly, a preconditioner for the solenoidal part of \( \tilde{T}_s \) is
\[
\tilde{Q}_{p,\alpha}^\Lambda = \sum_{i=2}^{N_{\alpha}} \left( \tilde{P}_i^\Lambda \tilde{P}_i^\Lambda - \tilde{P}_{i-1}^\Lambda \tilde{P}_{i-1}^\Lambda \right) \left[ D_{\Lambda} \right]_{N_{\alpha},-\alpha i+1}^{-1/4} + \left( \tilde{P}_i^\Lambda - \tilde{P}_{i-1}^\Lambda \right) \left[ D_{\Lambda} \right]_{N_{\alpha},-\alpha i+1}^{-1/4}
\]
for which
\[
\text{cond} \left( \tilde{Q}_{p,\alpha}^\Lambda \tilde{T}_s \tilde{Q}_{p,\alpha}^\Lambda \right) = O(1), \text{ when } h \to 0.
\]

The full EFIE preconditioner is then an appropriate linear combination of the solenoidal and non-solenoidal preconditioners above to cure also the low-frequency breakdown. In particular we define
\[
\tilde{Q} = \sqrt{\tilde{A}_{p,\alpha}^\Lambda} \tilde{Q}_{p,\alpha}^\Lambda + i \sqrt{\tilde{B}_\Sigma} \tilde{Q}_{p,\alpha}^\Sigma + \sqrt{\tilde{B}_\Sigma} \tilde{P}^H,
\]
where \( \tilde{P}^H = I - \tilde{P}^\Sigma - \tilde{P}^\Lambda \) and
\[
b_{\Lambda} = \left\| \tilde{Q}_{p,\alpha}^\Lambda \tilde{T}_s \tilde{Q}_{p,\alpha}^\Lambda \right\|^{-1} \text{,}
\]
\[
b_{\Sigma} = \left\| \tilde{Q}_{p,\alpha}^\Sigma \tilde{T}_h \tilde{Q}_{p,\alpha}^\Sigma \right\|^{-1} \text{,}
\]
\[
b_{\Sigma} = \left\| \tilde{P}^\Sigma \tilde{T}_h \tilde{P}^\Sigma \right\|^{-1} \text{,}
\]
account for the frequency-scaling of the operators and the diameter of \( \Gamma \). The preconditioned EFIE system is
\[
\tilde{Q} \tilde{T} \tilde{Q}_{p,\alpha} = \tilde{Q} \tilde{\nu},
\]
with \( j = G^{-1/2} \tilde{Q}_{j \alpha} \).
VII. IMPLEMENTATION RELATED DETAILS AND FURTHER IMPROVEMENTS

In addition to the efficient filtering algorithms presented in Section V, obtaining a fast and efficient implementation of the proposed preconditioning scheme based on filtered projectors requires that particular attention be given to parts of their implementation. First, all the terms of the form $T_hQ_{p,a}^\Lambda$, $Q_{p,a}^\Lambda T_h$, $P^HT_h$, or $T_hP^H$ must be explicitly set to $0$ to avoid numerical instabilities. Further treatments on the right hand side and on the solution vector, are required to ensure that the solution of the system remains accurate until arbitrarily low frequencies. These treatments are straightforward generalization of those required for standard quasi-Helmholtz preconditioning techniques that can be found in [7].

The condition numbers obtained when employing the schemes introduced in Section VI-A and Section VI-B, while stable, can be further brought down by slightly modifying the preconditioners. The diagonal preconditioning based on the theoretical Laplacian eigenvalues can be altered to instead employ matrix norms; the new preconditioners then become

$$Q_{p,a}^\Sigma = \sum_{l=2}^{N_{S,a}} (P_{\alpha l-1}^\Sigma - P_{\alpha l-1-1}^\Sigma) b_l + \left(P^\Sigma - P_{\alpha N_{S,a}-1}^\Sigma\right) b_{N_{S,a}+1},$$

where

$$b_l = \left\| \left( P_{\alpha l-1}^\Sigma - P_{\alpha l-1-1}^\Sigma \right)^T T_h \left( P_{\alpha l-1}^\Sigma - P_{\alpha l-1-1}^\Sigma \right) \right\|^{-1/2}, \quad 2 \leq l \leq N_{S,a}, \quad (108)$$

$$b_{N_{S,a}+1} = \left\| \left( P^\Sigma - P_{\alpha N_{S,a}-1}^\Sigma \right)^T T_h \left( P^\Sigma - P_{\alpha N_{S,a}-1}^\Sigma \right) \right\|^{-1/2}. \quad (109)$$

The same modification can be performed for $Q_{p,a}^\Lambda$ that becomes

$$Q_{p,a}^\Lambda = \sum_{l=2}^{N_{L,a}} (P_{\alpha l-1}^\Lambda - P_{\alpha l-1-1}^\Lambda) d_l + \left(P^\Lambda - P_{\alpha N_{L,a}-1}^\Lambda\right) d_{N_{S,a}+1}, \quad (111)$$

with

$$d_l = \left\| \left( P_{\alpha l-1}^\Lambda - P_{\alpha l-1-1}^\Lambda \right)^T T_s \left( P_{\alpha l-1}^\Lambda - P_{\alpha l-1-1}^\Lambda \right) \right\|^{-1/2}, \quad 2 \leq l \leq N_{L,a}, \quad (112)$$

$$d_{N_{S,a}+1} = \left\| \left( P^\Lambda - P_{\alpha N_{L,a}-1}^\Lambda \right)^T T_s \left( P^\Lambda - P_{\alpha N_{L,a}-1}^\Lambda \right) \right\|^{-1/2}. \quad (113)$$

To ensure that the overall complexity of the algorithm is not increased, the values of $\{b_l\}$ and $\{d_l\}$ can be efficiently computed using, for example, power methods. The reader should note that the preconditioning approach delineated above requires filter profiles with support both proportional to and independent from the number of unknowns, which can be efficiently obtained with the approaches described in Section V. As said in the previous Section, filters in the transition region could be less efficient to obtain, as the Chebyshev approach decreases in efficiency away from the middle of the spectrum [34]. All preconditioning real case scenarios presented here, however, are not impacted by this fact as shown in Section VIII.

VIII. NUMERICAL RESULTS

All numerical results presented in this section have been obtained with non-normalized matrices ($\Lambda$, $\Sigma$) to illustrate that graph matrices are often enough for practical cases. Equally good or superior performance, however, can be obtained by using normalized matrices (\(A\), \(S\)) instead. In the first set of examples we have leveraged perfect filters obtained by SVD before presenting results based on SVD-free approaches. The filtered Loop-Star preconditioning approach presented in Section VI-A leverages the spectral equivalences between the appropriately scaled filtered bases and $T_s$ and $T_h$. To numerically illustrate these equivalences, the spectra of these operators and their preconditioned counterparts are illustrated in Figures 2 and 3. These spectra correspond to a smoothly deformed sphere (see Fig. 2 and 3), and the ordering of the singular values is obtained by projection against the graph Laplacians’ eigenvectors. The original spectrum of $T_s$ and $T_h$ show the expected $\xi^{-1/2}$ and $\xi^{1/2}$—with $\xi$ the spectral index—behaviors, predicted by pseudo-differential operator theory. Given the construction of the preconditioners, it is then not surprising that the preconditioned operators show a spectrum bounded (and away from zero) with the expected variations in the spectrum.

To illustrate that the preconditioning schemes based on filtered bases do regularize the EFIE, the condition number of

![Fig. 2: Spectrum of the solenoidal part of the vector potential, its preconditioner, and its preconditioned counterpart. These spectra have been obtained for a smoothly-deformed sphere with a maximum diameter of 7.17 \(m\) (see insert), a frequency of 100 Hz, and for two different average edge lengths 0.31 m and 0.20 m. The spectra have been normalized so that their first singular value is one, for readability. Perfect filters built out of SVD have been used in these results.](image-url)
the original and preconditioned schemes will be compared for varying frequencies and discretizations. First, the conditioning of a filtered Loop-Star preconditioned EFIE for the NASA almond [51] is reported in Figure 4. The low frequency and dense discretization breakdowns of the original equations are apparent, while the preconditioned equation (corresponding to (96)) shows a constant conditioning. This is in contrast with the standard Loop-Star approach that does regularize the low frequency conditioning breakdown, but actually worsens the dense discretization behavior of the equation.

Fig. 3: Spectrum of the non-solenoidal part of the scalar potential, its preconditioner, and its preconditioned counterpart. These spectra have been obtained for a smoothly-deformed sphere with a maximum diameter of 7.17 m (see insert), a frequency of $10^6$ Hz, and for two different average edge lengths 0.31 m and 0.20 m. The spectra have been normalized so that their first singular value is one, for readability. Perfect filters built out of SVD have been used in these results.

A similar study has been performed with the filtered projectors schemes. In Figures 5 and 6 the spectra of the dominant solenoidal and non-solenoidal parts of the EFIE operators are displayed alongside their preconditioners. The preconditioning performance on the overall EFIE system is illustrated in Figure 7 for a torus. The approach yields satisfactory conditioning that remains stable in both low frequency and dense discretization, which in turns shows that the scheme can also handle multiply-connected geometries.

Finally, a conditioning study of the NASA almond is reported in Figure 8 that has been obtained using Chebyshev-interpolated filters (78) corresponding to Butterworth filters of order 100, expanded into 200 Chebyshev polynomials. The coefficients of the filters are obtained via the norm estimates detailed in (108) and (111) and the cutting point of the filters is determined using the approximate Laplacian spectrum described bellow (76). The excellent stability of preconditioned scheme for a structure such as the NASA almond showcases the effectiveness of the scheme when using the fast techniques presented in this paper.

Fig. 4: Condition number of the EFIE (5), Loop-Star EFIE, and filtered Loop-Star EFIE (96) as a function of discretization for several frequencies. The condition number has been obtained after eliminating the isolated singular values, which have minimal impact on the convergence, arising from the deletion of one column from each of the preconditioning matrices. The solid lines correspond to a simulating frequency of $10^6$ Hz and the dotted lines to a frequency of $10^4$ Hz. The simulated structure is the NASA almond re-scaled to be enclosed in a bounding box of diameter 1.09 m. Perfect filters built out of SVD have been used in these results.

Fig. 5: Spectrum of the solenoidal part of the vector potential, its preconditioner, and its preconditioned counterpart. These spectra have been obtained for a smoothly-deformed sphere with a maximum diameter of 7.17 m (see insert), a frequency of $10^6$ Hz, and for two different average edge lengths 0.31 m and 0.20 m. The spectra have been normalized so that their first singular value is one, for readability. Perfect filters built out of SVD have been used in these results.
A new family of strategies has been introduced for performing filtered quasi-Helmholtz decompositions of electromagnetic integral equations: the filtered Loop-Star decompositions and the quasi-Helmholtz Laplacian filters. These new tools are capable of manipulating large parts of the operators’ spectra to obtain new families of preconditioners and fast solvers. A first application to the case of frequency and $h$-refinement preconditioning of the electric field integral equation has been presented and numerical results have shown the practical effectiveness of the newly proposed tools.

**IX. Conclusion**

In this appendix, we show that the properties $\tilde{P}^A + \tilde{P}^\Sigma = I$ and $\tilde{G}^A + \tilde{G}^\Sigma = I$ hold true on simply connected geometries. To this end, we first prove that the normalized coefficients $\tilde{j}$ of the RWG functions can be decomposed with $\tilde{\Lambda}$ and $\tilde{\Sigma}$, similarly as in (9) where we assume that the proper number of columns from the matrices have been removed as is standard to ensure a full column rank, such that

$$\tilde{j} = G^{-\frac{1}{2}}j = \tilde{\Lambda}l + \tilde{\Sigma}s$$  \hspace{1cm} (114)

in which $\tilde{l}$ and $\tilde{s}$ are the coefficient vectors of the normalized Loop and Star parts in this decomposition. Since $G$, $G_p$, and $G_\chi$ are invertible matrices, we have $\text{rank}(\tilde{\Sigma}) = \text{rank}(\Sigma)$ and $\text{rank}(\tilde{\Lambda}) = \text{rank}(\Lambda)$. Moreover, since $\tilde{\Lambda}^T\tilde{\Sigma} = 0$, we also obtain that $\tilde{\Lambda}$ and $\tilde{\Sigma}$ have their column linearly independent, which yields $\text{rank}(\tilde{\Lambda} \tilde{\Sigma}) = \text{rank}(\Lambda) + \text{rank}(\Sigma) = N$, from which the existence and (unicity) of (114) follows.

Subsequently, using (114), we can form a new set of normalized projectors to retrieve $\tilde{\Lambda}l$ and $\tilde{\Sigma}s$ separately. The
first step is to apply \( \tilde{\Lambda}^T \) and \( \tilde{\Sigma}^T \) to (114) to express \( \tilde{j} \) in the two different bases

\[
\tilde{\Lambda}^T \tilde{j} = \tilde{\Lambda}^T \tilde{\Lambda} \tilde{j}, \quad (115)
\]

\[
\tilde{\Sigma}^T \tilde{j} = \tilde{\Sigma}^T \tilde{\Sigma} \tilde{s}, \quad (116)
\]

since \( \tilde{\Lambda}^T \tilde{\Sigma} = \mathbf{0} \) and \( \tilde{\Sigma}^T \tilde{\Lambda} = \mathbf{0} \), given (20). Subsequently, we express the coefficients of the normalized Loop and Star bases as a function of \( \tilde{j} \)

\[
\tilde{i} = \left( \tilde{\Lambda}^T \tilde{\Lambda} \right)^+ \tilde{\Lambda}^T \tilde{j}, \quad (117)
\]

\[
\tilde{s} = \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)^+ \tilde{\Sigma}^T \tilde{j}, \quad (118)
\]

Finally, we express \( \tilde{\Lambda} \tilde{i} \) and \( \tilde{\Sigma} \tilde{s} \) in terms of \( \tilde{j} \) by applying \( \tilde{\Lambda} \) and \( \tilde{\Sigma} \) to (117) and (118)

\[
\tilde{\Lambda} \tilde{i} = \tilde{\Lambda} \left( \tilde{\Lambda}^T \tilde{\Lambda} \right)^+ \tilde{\Lambda}^T \tilde{j} = \tilde{\Lambda}^T \tilde{j}, \quad (119)
\]

\[
\tilde{\Sigma} \tilde{s} = \tilde{\Sigma} \left( \tilde{\Sigma}^T \tilde{\Sigma} \right)^+ \tilde{\Sigma}^T \tilde{j} = \tilde{\Sigma}^T \tilde{j}, \quad (120)
\]

and we obtain that \( \tilde{\Lambda}^T \tilde{\Lambda} + \tilde{\Sigma}^T \tilde{\Sigma} = \mathbf{I} \) by leveraging (119), (120), and (114). Following the same procedure, except that now \( \tilde{\Lambda} \) and \( \tilde{\Sigma} \) are employed in the initial decomposition, we can show that the property \( \tilde{\Sigma}^T \tilde{\Sigma} + \tilde{\Lambda}^T \tilde{\Lambda} = \mathbf{I} \) also holds true.

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