COVERINGS BY CONVEX BODIES AND INSCRIBED BALLS

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Abstract. Let $H$ be a Hilbert space. For a closed convex body $A$ denote by $r(A)$ the supremum of radii of balls, contained in $A$. We prove, that $\sum_{n=1}^{\infty} r(A_n) \geq r(A)$ for every covering of a convex closed body $A \subset H$ by a sequence of convex closed bodies $A_n$, $n \in \mathbb{N}$. It looks like this fact is new even for triangles in a 2-dimensional space.

1. Introduction

Recall, that by a plank of width $w$ in a Hilbert space one means a set of the form

$$P = \{ h \in H : |\langle h - h_0, e \rangle| \leq \frac{w}{2} \},$$

where $\|e\| = 1$. According to T. Bang’s theorem [3], if a sequence $P_n$ of planks of widths $w_n$ covers a ball of diameter $w$, then $\sum w_n \geq w$. (To be more precise this is a particular case of Bang’s theorem. The complete statement includes a convex set $P$ of minimal width $w$ instead of a ball).

K. Ball generalized the Bang’s theorem to coverings of a ball in a Banach space, for planks defined with help of linear functionals instead of inner product.

Our work is inspired by Bang’s and Ball’s theorems. The idea was to find a ”symmetric” generalization of this theorems, where the elements of the covering and the covered set are of the same nature, and they are measured “from inside”. In this paper we prove such a generalization for sets in a Hilbert space. An analogous question for general Banach spaces remains open. In the proof we use ideas from Ball’s exposition of Bang’s theorem.

2. The main result

For simplicity all over the paper we consider real Hilbert spaces (finite- or infinite-dimensional). All the results are true for complex spaces too: the only thing which one must change in the proofs is the equation of a real...
hyperplane: in complex case such an equation uses not the inner product itself, but the real part of inner product.

Let \( H \) be a Hilbert space, and let \( B \) and \( S \) be its unit ball and its unit sphere respectively. By "body" in \( H \) we mean a closed subset with non-empty interior. For a convex body \( A \) denote by \( r(A) \) the supremum of radiiuses of balls \( x + aB \), contained in \( A \).

If \( A \) is a ball of radius \( r \), then \( r(A) = r \). If \( A \) is a plank of width \( h \), then \( r(A) = h/2 \).

**Theorem 2.1.** If a convex body \( A \subset H \) is covered by a sequence of convex bodies \( A_n, n \in \mathbb{N} \), then \( \sum_{n=1}^{\infty} r(A_n) \geq r(A) \).

To prove the theorem we need first some lemmas. The goal of the lemmas is to prove, that a convex bounded body in a Hilbert space can be approximated in some sense by a polytope with finite number of faces.

**Lemma 2.2.** Let \( A \subset H \) be a bounded convex body. Then there is a ball \( U \subset A \) with \( r(U) = r(A) \).

**Proof.** Denote \( r(A) = r \). For every \( p \in [0, r) \) consider the set \( A_p \), consisting of all those \( x \in A \), for which \( x + pB \subset A \). Each \( A_p \) is a bounded convex closed set, and hence it is a weak compact. Since \( A_p \neq \emptyset \) and decrease as \( p \to r \), there is a point \( o_1 \in \bigcap_{p \in [0,r)} A_p \). Then \( U = o_1 + rB \) will be the ball we need.

**Lemma 2.3.** Let \( A \subset H \) be a bounded convex body, \( r(A) = r \), and let \( U = o_1 + rB \) be the ball from the previous lemma. Then for every \( \varepsilon > 0 \) there is a finite subset \( G = \{g_1, \ldots, g_n\} \subset rB \) such that \( (1+\varepsilon)g_i + o_1 \in H \setminus A \) and

\[
\text{dist} \left( \text{conv} \{g_i\}_{i=1}^n, 0 \right) \leq \varepsilon.
\]

**Proof.** Without loss of generality we may assume \( o_1 = 0 \) (otherwise shift the picture). We must prove, that the closed convex hull of \( (1+\varepsilon)rB \setminus A \) contains 0.

Assume it is not so. By the Hahn-Banach theorem, there is a hyperplane \( P \), strictly separating \( (1+\varepsilon)rB \setminus A \) from 0. This means, that the set \( F \) - the bigger part of the ball \( (1+\varepsilon)rB \), lying on the same side of \( P \) as 0, is included in \( A \). The subset \( F \setminus rB \) of \( A \) evidently contains a ball of radius bigger than \( r \), which contradicts the definition of \( r \).

**Lemma 2.4.** Let \( x, y \in H, \|x\| = 1 + \varepsilon \) and the hyperplane

\[
\{h \in H : \langle h, y \rangle = \|y\|^2 \}
\]

generated by \( y \) separates \( x \) from the unit ball. Then \( \|x - y\| \leq \delta(\varepsilon) \), where \( \delta(\varepsilon) \) tends to 0 as \( \varepsilon \) tends to 0.

**Proof.** Our conditions mean that

\[
\langle x, y \rangle \geq \|y\|^2
\]
and
\[ \|y\| = \sup_{h \in B} \langle h, y \rangle \leq \|y\|^2, \]
i.e. \( \|y\| \geq 1 \). We have
\[ \|x - y\|^2 = \|x\|^2 - \|y\|^2 + 2(\|y\|^2 - \langle x, y \rangle) \leq \|x\|^2 - \|y\|^2 \leq (1 + \varepsilon)^2 - 1. \]

**Lemma 2.5.** Let \( A \subseteq H \) be a bounded convex body, \( r(A) = r \), and let \( U = o_1 + rB \) be the ball from lemma 2.2. Then for every \( \varepsilon > 0 \) there is a finite subset \( V = \{v_1, \ldots, v_n\} \subseteq rB \) (\( n \) depends on \( \varepsilon \)) such that
\begin{align*}
\text{(2)} \quad & A \subseteq W := \bigcap_{v \in V} \{h \in H : \langle h - o_1, v \rangle < r^2 + \varepsilon\}, \quad \text{and} \\
\text{(3)} \quad & \text{dist (conv}V, 0) \leq \varepsilon.
\end{align*}

**Proof.** Apply lemma 2.3 for a small \( \varepsilon_1 \), to obtain corresponding \( G = \{g_1, \ldots, g_n\} \subseteq rB \). Since \((1 + \varepsilon_1)g_i + o_1 \in H \setminus A\), one can separate \((1 + \varepsilon_1)g_i + o_1 \) from \( A \) by a hyperplane
\[ P_i = \{h \in H : \langle h - o_1, w_i \rangle = \|w_i\|^2\}. \]
Since \( U = o_1 + rB \subseteq A \), \( P_i \) separates \( U \) from \((1 + \varepsilon_1)g_i + o_1 \). This means that hyperplane
\[ \{h \in H : \langle h, w_i \rangle = \|w_i\|^2\} \]
separates \( rB \) from \((1 + \varepsilon_1)g_i \), and by lemma 2.4 \( w_i \) is "very close" to \( g_i \), and \( \|w_i\| \) is "very close" to \( r \). This means in turn, that when \( \varepsilon_1 \) is small enough, the elements \( v_k = r \frac{w_k}{\|w_k\|}, k = 1, 2, \ldots, n \) fulfill the demands of this lemma. \( \Box \)

**Lemma 2.6.** For a convex body \( A \subseteq B \) and for arbitrary \( \delta > 0 \) there is a polytope \( W \) of the form
\[ \bigcap_{k=1}^n \{h \in H : \langle h - o_k, v_k \rangle < a_k\}, \]
such that \( W \supset A \) and \( r(W \cap B) \leq r(A) + \delta \)

**Proof.** The polytope \( W \) can be taken from (2) of the previous lemma 2.5 with \( \varepsilon \) small enough. Let us show this. Consider \( U = o_1 + rB \) from lemma 2.6. For simplicity assume \( o_1 = 0 \) (the general case differs not too much from this one). Assume, contrary to our statement, that \( W \cap B \) contains a ball of the form \( U_0 = o_0 + (r + \delta)B \) (and automatically \( \|o_0\| \leq 1 \)). Then \( W \supset \text{conv}\{U_0, U\} \). According to condition (3), since \((1 + \varepsilon)V \) lies outside \( W \),
\[ \text{dist (conv}((1 + \varepsilon)U \setminus W), 0) \leq (1 + \varepsilon)\varepsilon, \]
and hence
\[ \text{dist (conv}((1 + \varepsilon)U \setminus \text{conv}\{U_0, U\}), 0) \leq (1 + \varepsilon)\varepsilon. \]
But for fixed $\delta$ and $\varepsilon \to 0$ the last inequality cannot be true, since radius of $U_0$ equals $(r + \delta)$ and the distance between the centers of $U_0$ and $U$ is bounded by a number, independent on $\varepsilon$. □

**Proof of the theorem 2.1.** Denote $r(A_n) = r_n$. By the definition of $r(A)$ we must prove that $\sum_{n=1}^{N} r_n \geq r(U)$ for every ball $U \subset A$. By homogeneity this means that it is sufficient to prove the theorem for the case of $A$ being the unit ball $B$ of $H$. Also without loss of generality one may assume $A_n \subset B$: otherwise consider $A_n \cap B$ instead of $A_n$.

So the theorem can be reformulated as follows:

Let $\sum_{n=1}^{\infty} r_n < 1$ and let $A_n \subset B$ be convex bodies with $r(A_n) = r_n$. Then

$$B \setminus \bigcup_{n=1}^{\infty} A_n \neq \emptyset.$$ 

According to lemma 2.6, every $A_n$ may be included in the interior of a polytope (say, $C_n$), in such a way, that the condition $\sum_{n=1}^{\infty} r(C_n \cap B) < 1$ still takes place. So, in fact, we may assume that interiors of all of $A_n$ are relatively weakly open in $B$, and it is enough to prove, that $B$ cannot be covered by interiors of $A_n$. But in this case, since $B$ is a weak compact, it is sufficient to prove, that $B$ cannot be covered by union of finitely many interiors of $A_n$. So we reduced our theorem to the case, when the number of sets is finite (say, equals $N$).

Let us fix a sequence of positive $\delta_n$ with

$$\sum_{n=1}^{N} (1 + \delta_n) r_n < 1,$$

and select $\varepsilon_n > 0$ with

$$(1 + \delta_n)(r_n^2 - 6N\varepsilon_n) \geq r_n^2 + \varepsilon_n.$$ 

For every $A_n$ apply lemma 2.5 with $\varepsilon = \varepsilon_n$ to get corresponding vectors $a_n \in A_n$, finite sets $V_n \subset r_n B$ and open polytopes

$$W_n := \bigcap_{v \in V} \{ h \in H : \langle h - a_n, v \rangle < r_n^2 + \varepsilon_n \},$$ 

such that $A_n \subset W_n$ and

$$\text{dist} (\text{conv} V_n, 0) \leq \varepsilon_n.$$ 

We are going to prove that

$$B \setminus \bigcup_{n=1}^{N} W_n \neq \emptyset.$$ 

Let us introduce an auxiliary space \( X = H \oplus H_1 \oplus H_2 \oplus \ldots \oplus H_N \) - the Hilbertian orthogonal direct sum of isometric copies of the original space \( H \).

Let \( U_n : H \to H_n \) be corresponding isometries.

Consider \( K = V_1 \times V_2 \times \ldots \times V_N \) and for every \( \bar{g} = (g_1, g_2, \ldots, g_N) \in K \) introduce

\[
f(\bar{g}) = \sum_{n=1}^{N} ((1 + \delta_n)(g_n + U_n g_n) - U_n o_n).
\]

Fix \( \bar{x} = (x_1, x_2, \ldots, x_N) \in K \) for which \( ||f(\bar{x})|| \) is maximal. We are going to prove that

\[
x = \sum_{n=1}^{N} (1 + \delta_n)x_n
\]

is the element, we need: namely, \( x \) belongs \( B \) but does not belong to any of \( W_j \).

First of all, due to \( (1) \) \( ||\sum_{n=1}^{N} (1 + \delta_n)x_n|| \leq \sum_{n=1}^{N} (1 + \delta_n)r_n < 1 \), i.e. \( x \in B \). Now for a fixed \( j \in \{1, 2, \ldots, N\} \) consider

\[
y_j = f(\bar{x}) - (1 + \delta_j)(x_j + U_jx_j).
\]

Taking in account, that according to our construction

\[
||y_j + (1 + \delta_j)(x_j + U_jx_j)|| = ||f(\bar{x})|| \geq ||y_j + (1 + \delta_j)(v + U_jv)||
\]

for all \( v \in V_j \), we obtain for all \( v \in V_j \)

\[
(8) \quad \langle y_j, (1 + \delta_j)(x_j + U_jx_j) \rangle \geq \langle y_j, (1 + \delta_j)(v + U_jv) \rangle.
\]

Due to condition \( (6) \), there is a convex combination \( \sum_{v \in V_j} \alpha_v v \), having norm less then \( \varepsilon_j \). Multiplying \( (8) \) by \( \alpha_v \) and adding for all \( v \in V_j \) we obtain

\[
\langle y_j, (1 + \delta_j)(x_j + U_jx_j) \rangle \geq -2\varepsilon_j (1 + \delta_j)\|y_j\| \geq -6\varepsilon_j (1 + \delta_j)
\]

Let us transform the last inequality using definition of \( y_j \) and pairwise orthogonality of subspaces \( H, H_1, \ldots, H_N \).

\[
\langle x - (1 + \delta_j)x_j + (1 + \delta_j)\sum_{n \neq j} U_n x_n - \sum_{n=1}^{N} U_n o_n, (1 + \delta_j)(x_j + U_jx_j) \rangle \geq -6\varepsilon_j (1 + \delta_j),
\]

\[
(1 + \delta_j)(x, x_j) - (1 + \delta_j)^2 r_j^2 - (1 + \delta_j)(U_j o_j, U_j x_j) \geq -6\varepsilon_j (1 + \delta_j),
\]

\[
(1 + \delta_j)(x, x_j) - (1 + \delta_j)(o_j, x_j) \geq (1 + \delta_j)^2 r_j^2 - 6\varepsilon_j (1 + \delta_j).
\]

By \( (5) \) we have

\[
\langle x - o_j, x_j \rangle \geq r_j^2 + \varepsilon_j,
\]

and this by definition of \( W_j \) means that \( x \) does not belong to \( W_j \).
References

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