EURO: ESPnet Unsupervised ASR Open-source Toolkit

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ABSTRACT

This paper describes the ESPnet Unsupervised ASR Open-source Toolkit (EURO), an end-to-end open-source toolkit for unsupervised automatic speech recognition (UASR). EURO adopts the state-of-the-art UASR learning method introduced by the Wav2vec-U, originally implemented at FAIRSEQ, which leverages self-supervised speech representations and adversarial training. In addition to wav2vec2, EURO extends the functionality and produces reproducibility for UASR tasks by integrating S3PRL and k2, resulting in flexible frontends from 27 self-supervised models and various graph-based decoding strategies. EURO is implemented in ESPnet and follows its unified pipeline to provide UASR recipes with a complete setup. This improves the pipeline’s efficiency and allows EURO to be easily applied to existing datasets in ESPnet. Extensive experiments on three mainstream self-supervised models demonstrate the toolkit’s effectiveness and achieve state-of-the-art UASR performance on TIMIT and LibriSpeech datasets. EURO will be publicly available at https://github.com/espnet/espnet, aiming to promote this exciting and emerging research area based on UASR through open-source activity.

Index Terms— unsupervised ASR, self-supervised learning, ESPnet, S3PRL

1. INTRODUCTION

Over the past decade, end-to-end (E2E) supervised ASR has achieved outstanding improvements. These achievements keep pushing the limit of ASR performance in terms of word error rate (WER). However, training the state-of-the-art model still heavily relies on a reasonable amount of annotated speech [1–3]. Unfortunately, labeled data is quite limited for most of the 7000 languages worldwide [4]. The fast development of self-supervised learning (SSL) could mitigate the issue to some extent by leveraging unlabeled data. This paradigm first learns the speech representations from raw audio and then fine-tunes the model on limited transcribed speech data [5–7], resulting in reducing the need for annotated speech.

However, as there is still a need for transcribed data for downstream model training, it is difficult to directly apply the system to all languages, especially those endangered languages that are extremely difficult to obtain data [8,9]. Unsupervised ASR could be one possible direction to solve the problem where the model can be trained with more accessible unpaired speech and text data.

Wav2vec-U is the state-of-the-art UASR framework. It utilizes both SSL (i.e., wav2vec2.0) and adversarial training for the UASR task [10]. The framework is shown working not only in English, where the wav2vec2.0 [5] is trained on but also in several other mainstream languages [11–13], as well as low-resource languages [14]. This finding reveals the possibility of utilizing unsupervised learning for more languages.

The authors of wav2vec-U have released their code in FAIRSEQ [15], which greatly improves reproducibility. The implementation mainly consists of 3 steps: data preparation, generative adversarial training (GAN) [16], and iterative self-training [17] followed by Kaldi LM-decoding [18]. Along with this reproducibility direction, we develop an unsupervised ASR toolkit named ESPnet Unsupervised ASR Open-source toolkit (EURO). EURO complements the original FAIRSEQ implementation with more efficient multi-processing data preparation, flexible choices over different SSLs, and large numbers of ASR tasks through ESPnet [19]. EURO also integrates a weighted finite-state transducers (WFST) decoder using the k2 [20] toolkit for word-level recognition. k2 is the updated version of the popular ASR toolkit Kaldi [18]. It seamlessly integrates WFST and neural models implemented in PyTorch [21] by supporting automatic differentiation for finite state automaton (FSA) and finite state transducer (FST), which are commonly used in ASR as a natural representation of the model’s architecture [22]. In EURO, k2 provides a compact WFST structured and efficient algorithm for decoding. With these advantages, EURO can considerably benefit the UASR study for the speech community, together with the FAIRSEQ UASR implementation.

This paper first introduces the toolkit and its features. Then, we conduct experiments that explore mainstream self-supervised models as speech feature extractors for UASR. Finally, we provide details of the hyperparameters of our experiments.

2. RELATED WORKS

This section briefly compares the framework of EURO to wav2vec-U. As summarized in Table 1, EURO provides more flexible choices of SSL model as the acoustic feature extractor by integrating with the S3PRL toolkit [23]. With the comprehensive pipeline in the template, EURO enjoys a fast adoption to various datasets with a limited data preparation effort (less than 20 lines of code for a minimum runnable solution). Meanwhile, all the data preparation stages in EURO are designed to enable computing in parallel, which greatly minimizes the preprocessing time compared to wav2vec-U. Besides of WFST decoder introduced in Sec. 1, EURO provides a self-implemented decoder to eliminate external dependencies.
3. FUNCTIONALITIES OF EURO

Fig. 1 shows the architecture of EURO. Similar to other ESPnet tasks, EURO includes two major components: a Python library of network training/inference and a collection of recipes for running complete experiments for a number of datasets. The library is built upon PyTorch, while the recipes offer all-in-one style scripts that follow the data format style in Kaldi [18] and ESPnet [19]. In addition, a WFST decoder is included to perform word-level recognition.

3.1. Models

As discussed in Sec. 2, we follow previous works in using adversarial training to achieve UASR in EURO. To be specific, we extend the Wav2vec-U framework into our implementation.

Given a spoken utterance \(X \in D_{speech}\), we first extract the speech representation by using a speech SSL model as the feature extractor \(f(\cdot)\), resulting in a sequence of hidden representations \(H\). Then, the sequence \(H\) is passed into a preprocessor \(m(\cdot)\) to form a segmented feature sequence \(S\), which is used for the generative adversarial network (GAN). The preprocessor \(m(\cdot)\) includes three steps, including adjacent clustering pooling, principle component analysis (PCA) dimension reduction, and mean pooling. The adjacent clustering pooling utilizes the K-Means cluster IDs from the input feature \(H\) as guidance to merge the adjacent feature frames.

The network is mainly trained with a GAN-based loss and some auxiliary supporting losses. Given the segmented feature \(S\) and an unpaired phonemized text sequence \(Y_u \in D_{text}\), the framework includes a generator \(G\) and a discriminator \(C\) as the classic GAN framework. The generator \(G\), which serves as the ASR model, transcribes \(S\) into a phoneme sequence \(P\) and the discriminator \(C\) tries to distinguish \(Y_u\) from the generated phoneme sequence \(P\). The GAN-based loss \(L_{GAN}\) is as follows:

\[
L_{GAN} = \min_{G} \max_{C} \mathbb{E}_{Y_u}[\log C(Y_u)] - \mathbb{E}_{S}[\log(1 - C(G(S)))).
\]  

To stabilize the training, three auxiliary losses are also proposed, including (a) a gradient penalty loss \(L_{gp}\) to sample the mixing rate of real and fake input for different steps:

\[
L_{gp} = \mathbb{E}_{S,Y_u,\alpha \sim U(0,1)}[\|\nabla C(\alpha G(S) + (1 - \alpha) Y_u)\| - 1]^2, \tag{2}
\]

where \(\alpha\) is the mixing weight sampled from a uniform distribution [26]. (b) a smoothness penalty to penalize inconsistent phoneme prediction between adjacent segments:

\[
L_{sp} = \sum_{(p_n, p_{n+1}) \in G(S)} ||p_n - p_{n+1}||^2, \tag{3}
\]

where \(p_n \in P\) is the generator output distribution at the \(n\)’s segment. (c) a phoneme diversity loss to prevent the generator \(G\) from generating the same phoneme all the time:

\[
L_{pd} = - \sum_{n} \text{Entropy}_{p}(G(S)), \tag{4}
\]

that is defined by the entropy of the average generator output distribution over every frame. The final loss is defined as

\[
L = L_{GAN} + \lambda L_{gp} + \gamma L_{sp} + \eta L_{pd}, \tag{5}
\]

where \(\lambda, \gamma, \eta\) are the weights for each term.

3.2. Frontend

One of the major benefits of EURO compared to wav2vec-U is its tight integration with S3PRL, a toolkit for speech/audio self-supervised models, to avoid manually managing and switching between different SSL models. S3PRL supports various SSL models as a general toolkit. S3PRL has kept up-to-date with the latest SSL models in the speech and audio domain. Based on the integration with S3PRL, by simply changing one line of the configuration, EURO can utilize up to 27 speech and audio SSLs with more than 70 of their variants.\(^1\)

3.3. Decoding

EURO offers two methods for decoding, including a self-implemented prefix beam search method and a graph-based search method using k2.

The prefix beam search utilizes the same decoding process as the CTC prefix decoding [27, 28], but without the blank symbols. Similar to other ESPnet tasks, the decoding can be integrated with phoneme-level language models (LM) from both \(n\)-gram LMs and neural LMs.

As briefly introduced in Sec. 1, the graph-based search employs WFST for decoding. Different from the prefix beam search method, the graph-based search can utilize word-level LMs in the search graph, and can also be extended to word recognition. The search graph \(T\) is a composition of three functional graphs: an alignment graph \(H\), a lexicon graph \(L\), and a grammar graph \(G\):

\[
T = H \circ L \circ G, \tag{6}
\]

where \(\circ\) is WFST composition. Specifically, \(H\) merges duplicated adjacent phones; \(L\) maps sequences of phonemes to sequences of responding words; \(G\) is an \(n\)-gram word LM. Fig. 3 and Fig. 4 show an

\(^1\)https://github.com/s3prl/s3prl

\(^2\)The number is recorded in Oct. 2022.
Fig. 3. $H$ topology of phone set \{k, ae, t\}. It merges duplicated adjacent phones in the input sequence, e.g., (k, k, ae, t, t) → (k, ae, t). The arc with \(-1\) is a special arc defined in k2 pointing to the final state.

example of $H$ and $L$ implemented in k2. The lattice is generated during decoding [29], which represents the set of most likely hypothesis transcripts structured in a directed graph and can be easily integrated with neural LMs by performing lattice scoring [30, 31]. The best hypothesis is obtained by searching the best path in the lattice.

3.4. Recipes for reproducible experiments

3.4.1. Directory structure

EURO follows the unified directory organization of ESPnet as shown in Fig. 2. Similar to other tasks (e.g., ASR, speech translation (ST)), the recipe usar.sh and its related bash scripts are stored under 

```
$cat espnet2/templates/uasr/.
```

The model espnet2.model.py and task uasr.py are stored at espnet2/uasr/ and espnet2/tasks/, respectively. Decoding scripts

```
$cat uasr.inference.py and uasr_inference_k2.py
```

are placed under espnet2/bin/.

3.4.2. Recipe flow

The recipe in EURO follows the ESPnet2 style of task, which provides the template usar.sh. The stages are defined as follows:

**Stage 1-5: Data preparation.** The initial data format starts from the Kaldi style [18], but the text for transcription is supposed to be unpaired with the speech data. Then, we offer two optional data preprocessing stages: speed perturbation and voice activity detection (VAD). The VAD results can be applied in silence removal as it is shown to be important for some speech corpus for wav2vec-U. After the preprocessing, all speech data is converted into a standard format, by resampling, segmenting, silence removal, and dumping from pipe-style formats.

**Stage 6-7: Text tokenization and token list generation.** Texts are converted to phoneme tokens using the graphemes to phonemes toolkit g2p-en. Tokens are collected from the training text and formed into a corresponding token list for modeling. For UASR, the unpaired text $Y_u$ is fed into training in a random fashion. For efficiency purposes, we initialize a randomized text loader with the tokenized text, which is especially useful for large text data.

**Stage 8-11: LM preparation.** These stages train and evaluate LMs based on the unpaired text $D_{text}$. The LMs include both neural-based LMs and N-gram LM.

**Stage 12: WFST graph construction.** This stage creates the WFST decoding graph for the k2 decoder.

**Stage 13: UASR statistics collection.** In this stage, EURO collects necessary input statistics for batching and mean-variance normalization (MVN). Optionally, the feature from frontends (i.e., S3PRL module in EURO) can be extracted at the stage to support efficient training in further stages.

**Stage 14: UASR feature preprocessing.** This stage applies the preprocessing steps discussed in Sec. 3.1, including adjacent clustering pooling, PCA, and mean pooling. The resulting segments are used for UASR training.

**Stage 15: UASR training.** This stage conducts the adversarial training as discussed in Sec. 3.1.

**Stage 16: UASR decoding.** EURO has two decoding schemes as introduced in Sec. 3.3. This stage supports both decoding methods.

**Stage 17: UASR evaluation.** The evaluation in this stage utilizes the NIST sclite toolkit to compute the phone error rate (PER) or the word error rate (if applicable).

**Stage 18-20: Model packing and uploading.** This stage automatically packs the trained model checkpoint for easier sharing of the pre-trained model. EURO also supports uploading models to Huggingface for model sharing.

4. EXPERIMENTS

4.1. Datasets

**TIMIT:** The TIMIT dataset is a popular benchmark for the UASR task [12]. It contains 6300 sentences (5.4 hours) of reading speech. All sentences are manually transcribed to phonemes with time alignment. We use the standard split of the train (3096 sentences), dev (400 sentences), and test (192 sentences) sets for our experiments.

**Librispeech:** The LibriSpeech dataset is a common benchmark for the ASR task [11]. It contains 960 hours of reading speech automatically derived from the audiobooks of LibriVox. This corpus is split into 3 training sets (100 and 360 hours of clean speech, and 500 hours of other speech), 2 dev sets (each has 5 hours), and test sets (each has 5 hours).

4.2. SSL models

We explore three SSL models for UASR in EURO, wav2vec 2.0 (wav2vec2-large-lv60), HubERT (hubert-large-lv60), and WavLM (wavlm-large).\(^3\) The three models have the same architecture that consists of 24 layers of Transformer encoders [33] with a similar number of parameters. Among them, wav2vec 2.0 and HuBERT are trained on 60,000 hours of Libri-Light. In addition to Libri-Light [34], WavLM uses 10,000 hours of Gigaspeech [35] and 24,000 hours of VoxPopuli [36] for pre-training.

4.3. Comparison of SSL models

**TIMIT:** We test EURO on TIMIT to confirm that the toolkit works properly. We use the text from the same training set for unsupervised training. To make it comparable with wav2vec-U, we adopt the same setup for EURO wav2vec 2.0. More specifically, we use the model wav2vec2-large-lv60k and the features are extracted from the 15th layer of the model. For Hubert and WavLM, we explore

\(^3\)Corresponding models can be found in https://s3prl.github.io/s3prl/tutorial/upstream_collection.html
the performance of features from different layers and report the best PER results.

Table 2 shows the results on TIMIT. Wav2vec-U serves as the baseline and achieves 17.0% and 17.8% PER on dev and test sets, respectively. EURO with the same setup gets 18.5% and 19.8% PER on the dev and test set which is slightly worse than wav2vec-U. While our model is not heavily tuned under this setup, the results are comparable with wav2vec-U. For Hubert (hubert-large-ll60k), EURO performs best on features extracted from the 15th layer. The PERs on the dev set and test set are 14.9% and 16.4%. Compared with the wav2vec-U baseline and EURO wav2vec 2.0, it provides a relative improvement of 10% and 20%, respectively. WavLM (wavlm-large) provides further improvement. The model trained using features extracted from the 14th layer of WavLM achieves 17% relative improvement compared with baseline and 25% relative improvement compared with EURO wav2vec 2.0 in terms of PER. It reduces the PER to 14.3% on the dev set and 14.6% on the test set.

**Librispeech:** For Librispeech, because of the limitation of computing resources, we use 100 hours of clean speech for UASR training. Unlike TIMIT, we use the text from the whole training set (960 hours) excluding the overlap part with the training speech. The text is phonemized using G2P phonemizer [37]. In total, around 25m sentences are used for UASR training.

We measure both the PER and WER of UASR systems using different SSL models for this dataset. Wav2vec-U uses a sophisticated decoder to convert phoneme sequences to word sequences and it may not be easily applied to other datasets. To make a fair comparison, we train the wav2vec-U model using the same data and load the model into EURO. We use the same prefix beam search decoder for PER and k2 WFST decoder for WER. Table 3 shows the results of LibriSpeech’s standard dev and test sets. All EURO models outperform the baseline wav2vec 2.0. For phone recognition, the HuBERT model performs best on clean sets. It achieves PER 15.2 on the dev clean set and PER 15.1 on the test clean set. Wav2vec 2.0 performs best on more difficult sets. It achieves PER 19.3 and 19.8 on dev other and test other sets, respectively. For word recognition, Hubert gets the best WER of 29.3, 22.8, and 29.8 on dev other, test clean and test other sets. WavLM performs best on dev clean and achieves 23.0 WER which is slightly better than HuBERT.

**4.4. Experimental details**

For training, we set $\lambda = 1.5$, $\gamma = 0.5$, and $\eta = 2.0$ for TIMIT and $\lambda = 2.0$, $\gamma = 1.0$, $\eta = 4.0$ for LibriSpeech datasets. For (phone-level) prefix beam search decoding, we set beam size = 2 and tunes the weight n-gram language model in $[0, 0.9]$. For (word-level) graph-based WFST decoding, we set search beam size = 30, output beam size = 15, min active states = 14,000, and max active stats = 56,000. More details can be found in the configuration file under egs2/TEMPLATE/uasr/conf/.

**5. CONCLUSIONS**

This work introduces a new toolkit for unsupervised ASR, namely EURO. The toolkit is developed as an open platform for the research field of unsupervised ASR. The current architecture of EURO is based on the Wav2vec-U framework but greatly improves the reproducibility with flexible frontends of almost 30 SSL models and a faster preparation/inference compared to its original implementation in FAIRSEQ. By integrating with k2, EURO provides a WFST decoder for word recognition. Our experiments on TIMIT and LibriSpeech show that we could get comparable performances with wav2vec-U in FAIRSEQ but even better results with Hubert and WavLM as new frontends.

**6. ACKNOWLEDGEMENT**

Part of the work presented here was carried out during the 2022 Jelinek Memorial Summer Workshop on Speech and Language Technologies at Johns Hopkins University, which was supported with unrestricted gifts from Amazon, Microsoft, and Google. This work used the Bridges system [38], which is supported by NSF award number ACI-1445606, at the Pittsburgh Supercomputing Center (PSC).
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