Mathematical models for optimising bi-enzyme biosensors

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Abstract – From our previous work we have seen examples of problems where including diffusion of a reactant into the model only affects the transient behaviour of the system but has no effect on the final steady states of its concentration. The equilibrium values are the only piece of information required for the solution of our experimental problem and in such situations it is important to identify the conditions under which a complex partial differential equations model can be replaced with a simpler one. The aim of this study is to find the optimal ratio of the two enzymes involved with a bi-enzyme electrode based on a flow injection analysis. Three mathematical models was constructed each neglect different aspects of the biosensor functionality. A detailed comparison of the models was carried out, base on various physical conditions recommendations of the best modelling strategy were given.

Keywords: Biosensors, Cascade reactions, Equilibrium, Steady-state

Introduction

In order to build a platform for biosensors based on a bi-enzyme electrode a research group at Dublin City University in Ireland have conducted a series of experiments which motivated this research work (refer to [1, 2] for details). The biosensor system investigated in this paper consists of two enzymes: glucose oxidase (GOX) and horseradish peroxidase (HRP), they are both immobilised onto an electrode modified with a conducting polymer. The two enzymes have very different kinetic characteristics, the performance of the system will depend on the optimal ratio of the two enzymes. A cascade reaction takes place at the electrode, GOX catalyses the oxidation reaction of glucose to gluconic acid, with production of H2O2. HRP is oxidised by hydrogen peroxide and then subsequently reduced by electrons provided by the electrode, which can be summarised as:

\[
\begin{align*}
\beta - D & - \text{glucose} + O_2 + H_2O \xrightarrow{\text{GOX}} \text{gluconic acid} + H_2O_2, \\
H_2O_2 + \text{HRP} & \rightarrow \text{Compound I} + H_2O, \\
\text{Compound I} + 2e^- + H^+ & \rightarrow \text{HRP} + H_2O.
\end{align*}
\]

Modelling strategies

A number of simplifying assumptions are made in order to carry out mathematical modelling for these reactions (refer to [3] for details). The standard Michaelis–Menten equation (1) was used to model this biochemical reaction:

\[
E_1 + S_1 \xrightleftharpoons[k_3]{k_2} C_1 \xrightarrow{k_3} E_1 + S_2, \quad E_2 + S_2 \xrightleftharpoons[k_3]{k_2} C_2 \xrightarrow{k_3} E_2 + P,
\]

where \( E_1 \) represents glucose oxidase, \( E_2 \) represents horseradish peroxidase, \( S_1 \) and \( S_2 \) represent the two substrates: glucose and hydrogen peroxide, \( C_1 \) and \( C_2 \) represent the two complexes and \( P \) represents the final product. All the \( k \) values denote the reactions rate, which are all constant.

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Three models of varying complexity for analysing this optimisation problem were discussed. Analytical solutions were presented with a view to expressing the steady-state current as a function of the ratio $\zeta$ of the two immobilised enzymes and thus finding its maximum value.

The first model, the "comprehensive model" assumes that the two substrates, $S_1$ and $S_2$, are free to diffuse in the solution and consists of two diffusion equations with the relevant nonlinear reaction-type boundary conditions. This model was proposed and solved numerically in [1]. We then jump to the other extreme and ignore all transport phenomena basically reducing the whole problem to the one-point kinetics of the cascade reaction in the second model, the "simplified model". This leads to a system of ordinary differential equations which is analysed using a combination of dynamical systems methods, perturbation techniques and numerical simulations. This model was also studied previously in Refs. [2, 3]. Finally, the third model, the "intermediate model" is proposed here for the first time and is a compromise between the two situations discussed above, where we allow one substrate (hydrogen peroxide) to diffuse but assume the other substrate (glucose) is only present at the electrode, in comparison with the first model, we obtain a much simpler system.

It is perhaps instructive to give some motivations regarding the choice of these three models and discuss expectations. We expect the diffusion of the first substrate $S_1$ to the electrode will have no effect on the equilibrium state except by increasing the time it takes to achieve it. So we expect there will be little difference between the first and third model. On the other hand, neglecting the diffusion of the second substrate $S_2$ (hydrogen peroxide) in the second model is potentially more serious as this assumes that all $S_2$ generated in the first reaction is immediately available for the second reaction and this could affect the size of the final steady states.

The comprehensive model

This section reviews the model introduced in [1] (where both substrates diffuse). An additional steady-state analysis of the partial differential equations is also presented.

Review of the comprehensive model

In this model, the cascade scheme (1) is modelled by a system of partial differential equations and boundary conditions representing convective and diffusive transport of the two substrates, glucose and hydrogen peroxide, as well as the reaction kinetics of the bi-enzyme electrode. For simplicity, the convective transport is not explicitly modelled and the flow injection is only reflected in the boundary conditions imposed at the top of the diffusion domain, $0 \leq x \leq L$. We have also assumed that diffusion is one-dimensional and $x$ measures distance from the electrode.

In what follows, we denote the concentrations of all the chemical species mentioned in the cascade scheme (1) by their corresponding lower case letters (e.g., $s_1 = [S_1]$, etc.). The two substrates satisfy the following diffusion equations:

$$\frac{\partial \xi_1(x, t)}{\partial t} = D_1 \frac{\partial^2 \xi_1(x, t)}{\partial x^2}, \quad 0 \leq x \leq L, \quad t \geq 0,$$

$$\frac{\partial \xi_2(x, t)}{\partial t} = D_2 \frac{\partial^2 \xi_2(x, t)}{\partial x^2}, \quad 0 \leq x \leq L, \quad t \geq 0,$$

where $D_1$ and $D_2$ denotes the coefficients of diffusion. The top boundary conditions were formed based on the fact that the first substrate $S_1$ is continuously injected into the solution at a constant speed, and the second substrate $S_2$ is flushed away constantly, where,

$$s_1(L, t) = s_0, \quad t \geq 0,$$

$$s_2(L, t) = 0, \quad t \geq 0.$$

The bottom boundary conditions are:

$$D_1 \frac{\partial \xi_1(0, t)}{\partial x} = k_1 e_1(t) s_1(0, t) - k_{-1} c_1(t),$$

$$D_2 \frac{\partial \xi_2(0, t)}{\partial x} = k_3 e_2(t) s_2(0, t) - k_{-3} c_2(t) - k_{-3} c_2(t),$$

together with,

$$\frac{d e_1}{d t} = -k_1 e_1(t) s_1(0, t) + (k_{-1} + k_2) c_1(t),$$

$$\frac{d e_2}{d t} = -k_3 e_2(t) s_2(0, t) + (k_{-3} + k_4) c_2(t).$$
\[ \frac{dc_1}{dr} = k_1 e_1(t)s_1(0, t) - (k_{-1} + k_2)c_1(t), \]
\[ \frac{dc_2}{dr} = k_3 e_2(t)s_2(0, t) - (k_{-3} + k_4)c_2(t), \]
\[ \frac{dp}{dr} = k_4 c_2(t). \]

The initial conditions are:
\[ e_1(0) = e_1^0, \quad e_2(0) = e_2^0, \quad c_1(0) = 0, \quad c_2(0) = 0, \quad p(0) = 0, \quad s_2(x, 0) = 0, \]
\[ s_1(x, 0) = \begin{cases} 
  s_0, & \text{if } x = L, \\
  0, & \text{otherwise,}
\end{cases} \]
where \( e_1^0, e_2^0 \) and \( s_0 \) are constants. We let,
\[ \zeta = \frac{e_1^0}{e_2^0}, \]
which implies,
\[ e_1^0 = \frac{e\zeta}{1 + \zeta}, \quad e_2^0 = \frac{e}{1 + \zeta}, \]
in which \( e \) represents the total amount of \( e_1 \) and \( e_2 \) consumed in the biochemical reaction, it is a constant parameter which can be measured experimentally.

The system is non-dimensionalised by the variables as shown below:
\[ \bar{s}_1(\bar{x}, \bar{t}) = \frac{s_1(x, t)}{s_0}, \quad \bar{s}_2(\bar{x}, \bar{t}) = \frac{s_2(x, t)}{s_0}, \quad \bar{e}_1(\bar{t}) = \frac{e_1(t)}{e}, \quad \bar{e}_2(\bar{t}) = \frac{e_2(t)}{e}, \]
\[ \bar{c}_1(\bar{t}) = \frac{c_1(t)}{e}, \quad \bar{c}_2(\bar{t}) = \frac{c_2(t)}{e}, \quad \bar{p}(\bar{t}) = \frac{p(t)}{e}, \quad \bar{x} = \frac{x}{L}, \quad \bar{t} = \frac{t}{t_0}, \]
where \( t_0 = 1/(k_1 s_0) \). We then obtain the non-dimensional system,
\[
\begin{align*}
\frac{\partial \bar{s}_1(x, t)}{\partial \bar{t}} &= \frac{D_1}{k_1 s_0^2} \frac{\partial^2 \bar{s}_1(x, t)}{\partial \bar{x}^2}, \\
\frac{\partial \bar{s}_2(x, t)}{\partial \bar{t}} &= \frac{D_2}{k_1 s_0^2} \frac{\partial^2 \bar{s}_2(x, t)}{\partial \bar{x}^2}, \\
\bar{s}_1(1, \bar{t}) &= 1, \\
\bar{s}_2(1, \bar{t}) &= 0, \\
\frac{\partial \bar{s}_1(0, \bar{t})}{\partial \bar{x}} &= \frac{k_1 e l}{D_2} e_1(t) s_1(0, \bar{t}) - \frac{k_{-1} e l}{D_1 s_0} c_1(\bar{t}), \\
\frac{\partial \bar{s}_2(0, \bar{t})}{\partial \bar{x}} &= \frac{k_3 e l}{D_2} e_2(t) s_2(0, \bar{t}) - \frac{k_{-3} e l}{D_2 s_0} c_1(\bar{t}) - \frac{k_{-3} e l}{D_2 s_0} c_2(\bar{t}), \\
\frac{\partial e_1}{\partial \bar{t}} &= -e_1(t) s_1(0, \bar{t}) + K_m^1 \frac{e_1(t)}{s_0} c_1(\bar{t}), \\
\frac{\partial e_2}{\partial \bar{t}} &= \frac{k_3}{k_1} e_2(t) s_2(0, \bar{t}) + \frac{k_{-3} + k_4}{k_1 s_0} c_2(\bar{t}), \\
\frac{\partial c_1}{\partial \bar{t}} &= e_1(t) s_1(0, \bar{t}) - \frac{K_m^1}{s_0} c_1(\bar{t}), \\
\frac{\partial c_2}{\partial \bar{t}} &= \frac{k_3}{k_1} e_2(t) s_2(0, \bar{t}) - \frac{k_{-3} + k_4}{k_1 s_0} c_2(\bar{t}), \\
\frac{dp}{dr} &= \frac{k_1}{k_1 s_0} c_2(\bar{t}),
\end{align*}
\]

where the bars were dropped for convenience. An extensive numerical analysis of this system was presented in [1] where the behaviour of the enzyme ratio \( \zeta \) was studied for different values of the system parameters. The time evolution of \( k_1 \bar{e}_2(\bar{t}) \), which was taken as a measure of the amperometric signal, was calculated and the steady state value, \( k_1 \bar{e}_2^* \),
was recorded as the current value and used for future parameter iterations. Note that the dimensional value of the current is,

\[ I(t) \approx \frac{dp}{dt} = k_i c_2(t) = ek_i \tilde{c}_2(t), \quad (3) \]

\[ \text{hence, } k_i \tilde{c}_2(t) \text{ can be regarded as a good measure of the amperometric signal, which should not depend on the choice of non-dimensionalisation used in the model.} \]

**Steady-state analysis**

This part of the paper analyse system (2) as \( t \to \infty \). At equilibrium, equation (2a) gives,

\[ \frac{\partial s_1(x, t)}{\partial t} = 0, \]

which means,

\[ \frac{\partial^2 s_1(x, t)}{\partial x^2} = 0; \quad (4) \]

\[ \text{then integrating equation (4) twice with respect to } x, \text{ we get,} \]

\[ s_1^e(x) = Ax + B. \]

Similarly, from equation (2b), we obtain,

\[ s_2^e(x) = Cx + D, \quad (6) \]

where \( s_1^e(x), s_2^e(x) \) denote the equilibrium values of \( s_1(x, t) \), \( s_2(x, t) \) respectively, and \( A, B, C, D \) are constants of integration.

Equation (2c) together with equation (5) gives,

\[ s_1^e(x) = (1 - B)x + B; \]

similarly equation (2d) together with equation (6) gives,

\[ s_2^e(x) = -Dx + D. \]

Thus, at \( x = 0 \), the system (2) can be reduced to,

\[ \begin{cases} 1 - B = \frac{k_i e}{D_1} \left( \frac{\zeta}{1 + \zeta} - c_1^1 \right) B - \frac{k_i e}{D_1 s_0} c_1^1, \\ -D = \frac{k_3 e}{D_2} \left( \frac{1}{1 + \zeta} - c_2^1 \right) D - \frac{k_3 e}{D_2 s_0} c_1^1 - \frac{k_i e}{D_2 s_0} c_2^2, \\ 0 = \left( \frac{\zeta}{1 + \zeta} - c_1^1 \right) B - \frac{K_1}{s_0} c_1^1, \\ 0 = \frac{k_4}{k_1} \left( \frac{1}{1 + \zeta} - c_2^1 \right) D - \frac{k_4 + k_i}{k_1 s_0} c_2^2. \end{cases} \]

\[ \text{Here, we have a system of four equations with four unknowns } B, D, c_1^1 \text{ and } c_2^2, \text{ we then reduce the system to two equations} \]

\[ \begin{cases} (c_1^1)^2 - \left( \frac{D_1 s_0}{k_2 e} + \frac{D_1 K_1^1}{k_2 e} + \frac{\zeta}{1 + \zeta} \right) c_1^1 + \frac{D_1 s_0}{k_2 e} \frac{\zeta}{1 + \zeta} = 0, \\ (c_2^2)^2 - \left( \frac{k_2 c_1^1}{k_4} + \frac{D_2 K_2^2}{k_2 e} + \frac{1}{1 + \zeta} \right) c_2^2 + \frac{k_2 c_1^1}{k_4} \frac{1}{1 + \zeta} = 0. \end{cases} \]

System (8) can be easily solved to give explicit formulas for \( c_1^1 \) and \( c_2^2 \) where,
\[
c_1^* = \frac{\left( \frac{D_1 s_0}{k_{2e}l} + \frac{D_1 k_m^1}{k_{2e}l} + \frac{\zeta}{1 + \zeta} \right)}{2} \pm \sqrt{\left( \frac{D_1 s_0}{k_{2e}l} + \frac{D_1 k_m^1}{k_{2e}l} + \frac{\zeta}{1 + \zeta} \right)^2 - \frac{4D_1 s_0}{k_{2e}l} \frac{\zeta}{1 + \zeta}},
\]

(9)

\[
c_2^* = \frac{\left( \frac{k_4 c_1^*}{k_4} + \frac{D_2 k_m^2}{k_{4e}l} + \frac{1}{1 + \zeta} \right)}{2} \pm \sqrt{\left( \frac{k_4 c_1^*}{k_4} + \frac{D_2 k_m^2}{k_{4e}l} + \frac{1}{1 + \zeta} \right)^2 - \frac{4k_4 c_1^*}{k_4} \frac{1}{1 + \zeta}}.
\]

(10)

Note that the smaller solution is selected in both these quadratic equations, as we need,

\[
c_1^* \leq e_1^0 = \frac{\zeta}{1 + \zeta}; \quad c_2^* \leq e_2^0 = \frac{1}{1 + \zeta}.
\]

We then plot the current, \(k_4 c_2^*\), as a function of \(\zeta\) by using MAPLE in Figure 1. We note that, as we chose \(k_2 = k_4\), the optimal ratio \(\zeta^*\) approaches one for large glucose concentrations. Figure 2 shows the current as a function of \(\zeta\) when the ratio \(k_4/k_2\) is varied.

Figure 1. Dependence of current on \(\zeta\). \(s_0 = 1\) (red), 5 (blue), 10 (black) and 20 (green) mM, \(k_1 = 10^2\), \(k_{-1} = 10^{-1}\), \(k_2 = 10\), \(k_3 = 10^2\), \(k_{-3} = 10^{-1}\), \(k_4 = 10\), \(e_0 = 10^{-5}\), \(l = 2 \times 10^{-4}\), \(D_1 = 6.7 \times 10^{-10}\) and \(D_2 = 8.8 \times 10^{-10}\).

Figure 2. Dependence of current on \(\zeta\). \(k_4/k_2 = 0.2\) (red), 0.5 (blue), 1 (black) and 2 (green), \(k_1 = 10^2\), \(k_{-1} = 10^{-1}\), \(k_2 = 10\), \(k_3 = 10^2\), \(k_{-3} = 10^{-1}\), \(k_4 = 10\), \(e_0 = 10^{-5}\), \(l = 2 \times 10^{-4}\), \(D_1 = 6.7 \times 10^{-10}\) and \(D_2 = 8.8 \times 10^{-10}\).
Simplified model

This section analyses the simple, one-point model of the cascade reaction which was introduced in [2]. A very detailed analysis of the model is presented in [3], the behaviour of the system for different $\zeta$ is discussed in here.

Review of the simple model

The following non-dimensional system of ordinary differential equations were constructed for the one-point model based on the fact that the substrates do not diffuse in the biochemical reaction:

\[
\begin{align*}
\frac{ds_1}{dt} &= e_1 \left( k_{s1} s_0 - \left( \frac{c_1}{1 + \zeta} - c_1 \right) s_1 \right) \\
\frac{ds_2}{dt} &= e_1 \left( k_{s2} s_0 - k_{s3} s_1 - k_{s3}^3 \left( \frac{1}{1 + \zeta} - c_2 \right) s_2 + \frac{k_{s3} c_2}{k_{s0}} \right) \\
\frac{dc_1}{dt} &= \left( \frac{1}{1 + \zeta} - c_1 \right) s_1 - \frac{K_1}{s_0} c_1 \\
\frac{dc_2}{dt} &= k_3 \left( \frac{1}{1 + \zeta} - c_2 \right) s_2 - \frac{K_2}{s_0} c_2.
\end{align*}
\] (11a-b-c-d)

We can further simplify system (11) as follows since the first substrate glucose is supplied constantly at the electrode,

\[
\begin{align*}
\frac{dc_1}{dt} &= \frac{1}{1 + \zeta} \left( 1 + \frac{K_1}{s_0} \right) c_1 \\
\frac{dc_2}{dt} &= \frac{k_3}{k_1} \left( \frac{1}{1 + \zeta} - c_2 \right) s_2 - \frac{K_3}{s_0} c_2 \\
\frac{ds_2}{dt} &= e_1 \left( k_{s2} s_0 - k_{s3} s_1 - k_{s3} \left( \frac{1}{1 + \zeta} - c_2 \right) s_2 + \frac{k_{s3} c_2}{k_{s0}} \right),
\end{align*}
\] (12a-b-c)

with initial conditions $c_1 (0) = 0$, $c_2 (0) = 0$ and $s_2 (0) = 0$, where,

\[
\begin{align*}
e_1 &= \frac{e}{s_0}, \\
K_1 &= \frac{k_{s1} + k_{s2}}{k_1}, \\
K_2 &= \frac{k_{s3} + k_{s4}}{k_1}.
\end{align*}
\]

The global behaviour of system (12) is analysed by using the slow-fast dynamics, slow invariant manifold and the dynamical systems analysis (refer to [3] for details), we concluded system (12) has the following long term behaviours,

\[
\begin{align*}
\lim_{t \to \infty} c_1 (t) &= c_1^* \quad \text{for all } \zeta, \\
\lim_{t \to \infty} c_2 (t) &= \begin{cases} 
\frac{\zeta}{(1 + \zeta)(1 + \frac{K_1}{s_0})}, & \text{if } \zeta \leq \zeta^* \\
\frac{1}{1 + \zeta}, & \text{if } \zeta \geq \zeta^*, 
\end{cases} \\
\lim_{t \to \infty} s_2 (t) &= \begin{cases} 
s_2^*, & \text{if } \zeta < \zeta^* \\
\infty, & \text{if } \zeta \geq \zeta^*, 
\end{cases}
\end{align*}
\] (13-14a-14b-15a-15b)

where,

\[
\begin{align*}
c_1^* &= \frac{\zeta}{(1 + \zeta)(1 + \frac{K_1}{s_0})}, \\
c_2^* &= \frac{s_2^*}{(1 + \zeta)(\frac{s_2^*}{s_0} + \frac{K_2}{s_0})},
\end{align*}
\] (16-17)
\[ s^*_2 = \frac{\zeta k_2 K_m^2}{s_0 \left( k_1 \left( 1 + \frac{K_m^1}{s_0} \right) - \zeta k_2 \right)}, \]  

(18)

\[ \zeta^* = \frac{k_1}{k_2} \left( 1 + \frac{K_m^1}{s_0} \right). \]  

(19)

From these results, we can see that when \( \zeta < \zeta^* \), the initial amount of glucose oxidase is less than the initial amount of horseradish peroxidase. This leads to the amount of \( s_2 \) produced from the first reaction is all consumed somehow in the second reaction and eventually an equilibrium state can be reached; and when \( \zeta \geq \zeta^* \), the initial amount of glucose oxidase is greater than the initial amount of horseradish peroxidase. The production rate is greater than the consumption rate of \( s_2 \), so the concentration of \( s_2 \) will increase indefinitely.

We plot the steady state current, \( k_4 c_2(\infty) \), as a function of \( \zeta \) for different values of \( s_0 \) (Fig. 3) and \( k_4/k_2 \) (Fig. 4). In Figure 3 the curves overlay for \( \zeta \) values ranging from 1 to 6, and in Figure 4 the curves overlay for \( \zeta \) values ranging from 0 to 1, also note that from equations (14a) and (14b), that the optimal enzymes ratio is given by,

\[ \zeta^* = \frac{k_1}{k_2} \left( 1 + \frac{K_m^1}{s_0} \right), \]

as \( c_2(\infty) \) achieves its maximum value of \( 1/(1 + \zeta^*) \) when \( \zeta = \zeta^* \). Therefore, we are able to obtain an explicit formula which gives the optimal value of \( \zeta \) in terms of the system parameters. Note the agreement between the results as shown in Figures 3 and 4 and the model in the previous section.

Figure 3. Dependence of current on \( \zeta \). \( s_0 = 0.03 \) (red), 0.09 (blue), 0.2 (black) and 5 (green) mM, \( k_1 = 10^2 \), \( k_{-1} = 10^{-1} \), \( k_2 = 10 \) and \( k_4 = 10 \).

Figure 4. Dependence of current on \( \zeta \). \( k_4/k_2 = 0.2 \) (red), 0.5 (blue), 1 (black) and 2 (green), \( k_1 = 10^2 \), \( k_{-1} = 10^{-1} \), \( k_2 = 10 \) and \( k_4 = 10 \).
Intermediate model

In this model, we assume the glucose ($s_1$) does not diffuse but is present only at the electrode boundary point, and in addition it is constant, i.e., $s_1(t) = s_0$. (In other words, $s_1$ is supplied continuously at the reaction site.) The second substrate is free to diffuse throughout the domain at all times during the experiment, which is reflected by the following diffusion equation,

$$\frac{\partial s_2(x, t)}{\partial t} = D_1 \frac{\partial^2 s_2(x, t)}{\partial x^2}.$$  

At the top layer and the electrode, we have the boundary conditions,

$$s_2(L, t) = 0,$$

$$D_1 \frac{\partial s_2(0, t)}{\partial x} = k_3e_2(t)s_2(0, t) - k_2c_1(t) - k_{-3}c_2(t),$$

together with,

$$\frac{de_1}{dt} = -k_1e_1(t)s_1(t) + (k_{-1} + k_2)c_1(t),$$

$$\frac{de_2}{dt} = -k_3e_2(t)s_2(0, t) + (k_{-3} + k_1)c_2(t),$$

$$\frac{dc_1}{dt} = k_1e_1(t)s_1(t) - (k_{-1} + k_2)c_1(t),$$

$$\frac{dc_2}{dt} = k_3e_2(t)s_2(0, t) - (k_{-3} + k_1)c_2(t),$$

$$\frac{dp}{dt} = k_4e_2(t).$$

The initial conditions are:

$$e_1(0) = e^0_1, \quad e_2(0) = e^0_2, \quad s_1(0) = s_0, \quad s_2(x, 0) = 0,$$

$$c_1(0) = 0, \quad c_2(0) = 0, \quad p(x, 0) = 0,$$

and the conservation laws are:

$$\begin{cases}
    e_1(t) + c_1(t) = e^0_1 \\
    e_2(t) + c_2(t) = e^0_2
\end{cases}$$

The system is non-dimensionalised by using the variables below,

$$\tilde{s}_2(x, \tilde{t}) = \frac{s_2(x, t)}{s_0}, \quad \tilde{e}_1(t) = \frac{e_1(t)}{e}, \quad \tilde{e}_2(t) = \frac{e_2(t)}{e},$$

$$\tilde{c}_1(t) = \frac{c_1(t)}{e}, \quad \tilde{c}_2(t) = \frac{c_2(t)}{e}, \quad \tilde{x} = \frac{x}{l}, \quad \tilde{t} = \frac{t}{t_0},$$

where $t_0 = 1/(k_1s_0)$; we then obtain the non-dimensional system,

$$\begin{align}
    \frac{\partial \tilde{c}_2(x, t)}{\partial \tilde{t}} &= \frac{D_1}{k_1s_0 l^2} \frac{\partial^2 \tilde{c}_2(x, t)}{\partial \tilde{x}^2} \\
    \tilde{s}_2(x, 0) &= 0 \\
    \tilde{s}_2(1, \tilde{t}) &= 0 \\
    \frac{\partial \tilde{c}_2(0, \tilde{t})}{\partial \tilde{x}} &= \eta \left( \tilde{s}_2(0, \tilde{t}) \left( \frac{1}{1 + \zeta} - \tilde{c}_2(\tilde{t}) \right) - \kappa c_1(\tilde{t}) - \mu c_2(\tilde{t}) \right) \\
    \frac{dc_1(\tilde{t})}{d\tilde{t}} &= \frac{\zeta}{1 + \zeta} - (1 + \sigma_1) c_1(\tilde{t}) \\
    \frac{dc_2(\tilde{t})}{d\tilde{t}} &= \rho_2 \left( \tilde{s}_2(0, \tilde{t}) \left( \frac{1}{1 + \zeta} - c_2(\tilde{t}) \right) - \sigma_2 c_2(\tilde{t}) \right),
\end{align}$$

where $\eta, \zeta, \kappa, \mu, \sigma_1, \sigma_2, \rho_2$ are constants.
with non-dimensional initial conditions,

\[ e_1(0) = \frac{i}{1+\zeta}, \quad e_2(0) = \frac{1}{1+\zeta}, \quad s_2(x,0) = 0, \quad c_1(0) = 0, \quad c_2(0) = 0, \]

and conservation laws,

\[
\begin{cases}
e_1(t) + c_1(t) = \frac{\zeta}{1+\zeta} \\
e_2(t) + c_2(t) = \frac{1}{1+\zeta},
\end{cases}
\]

where,

\[
\zeta = \frac{e_1^0}{e_2^0}, \quad \eta = \frac{k_3 e_l}{D_1}, \quad \kappa = \frac{k_2}{k_3 s_0}, \\
\mu = \frac{k_{r_3}}{k_3 s_0}, \quad \rho_2 = \frac{k_3}{k_1}, \quad \sigma_1 = \frac{K_m^1}{s_0}, \quad \sigma_2 = \frac{K_m^2}{s_0}.
\]

We now carry out a steady-state analysis of system (20). At equilibrium,

\[
\frac{\partial s_2(x,t)}{\partial t} = 0,
\]

which gives,

\[
\frac{\partial^2 s_2(x,t)}{\partial x^2} = 0. \quad (21)
\]

Then by integrating (21) twice, we obtain,

\[ s_2^*(x) = Ax + B, \]

which gives,

\[ s_2^*(0) = B, \quad (22) \]

where \( s_2^*(x) \) denotes the equilibrium value of \( s_2(x, t) \), \( A \) and \( B \) are constants of integration. Also, from equation (20c), we obtain \( A = -B \) and this condition together with equation (22) yields,

\[ s_2^*(x) = B(1-x), \]

which gives,

\[ \frac{\partial s_2^*(0)}{\partial x} = -B. \quad (23) \]

From equation (20e), we obtain

\[ c_1^* = \frac{\zeta}{(1+\zeta)(1+\sigma_1)}, \]

and, from equation (20f), we obtain,

\[ c_2^* = \frac{1}{1+\zeta} \frac{s_2^*(0)}{s_2^*(0) + \sigma_2}. \]

Also, from equations (20d) and (23), we get,

\[ -B = \eta \left( s_2^*(0) \left( \frac{1}{1+\zeta} - c_1^* \right) - \kappa c_1^* - \mu c_2^* \right), \]

which gives,

\[ (1+\zeta)B^2 + \left( \sigma_2(1+\zeta) + \eta(\sigma_2 - \mu) - \frac{\kappa \zeta \eta}{1+\sigma_1} \right) B - \frac{\kappa \zeta \eta \sigma_2}{1+\sigma_1} = 0. \]
from which, $B$ can be easily obtained as a function of $\zeta$, i.e., $B(\zeta)$ (Note that since the above quadratic equation has two real roots of different signs, we choose the positive root). Thus, the equilibrium value for the current is,

$$I \approx k_4 c_2^* = \frac{k_4}{1 + \zeta} \frac{B(\zeta)}{B(\zeta) + \sigma_2}.$$  

Figure 5 shows the plot of current ($k_4 c_2^*$) on $\zeta$ for various values of $s_0$; if we vary $k_4/k_2$ instead, we obtain the graphs in Figure 6.

**Summary and comparisons**

The work presented here shows the study of a bi-enzyme electrode based on a flow injection analysis, with the aim of finding the optimal ratio of the two enzymes involved. Three different mathematical models were considered: the “comprehensive model” (where we include the diffusion effects of the two substrates: glucose and hydrogen peroxide), the “simplified model” (which concentrated on the kinetics of the two reactions and no transport was taken into account) and the “intermediate model” (which only considered the diffusion of the substrate hydrogen peroxide). As the simplified model consisted of a system of ordinary differential equations, we were able to present a detailed analytical study of its solutions (including an exact formula for the optimal ratio of the two enzymes), unlike in the other two models where the results were mostly numerical.

The dependence of the biosensor response (i.e., the measured amperometric current) as a function of $\zeta$, the ratio of the two enzymes, is again plotted in Figure 7, for different values of the glucose concentration and, in Figure 8, for different values of $k_4/k_2$. Figures 7a and 8a are plotted based on the experimental data from [1].
To facilitate the comparison of the three models, we then plot the optimal $f$ value (the value which maximises the current) as a function of the glucose concentration. The four resulting curves are as shown in Figure 9. We note that the simple model and the intermediate model give identical results for the optimal enzyme ratio for all values of initial glucose concentration. The values predicted by the comprehensive model are quite different at low glucose concentrations but, again, identical at high glucose concentrations. Note that, at high glucose concentration, the optimal enzyme ratio approaches the same value regardless of the model used (This value is $f^* = 1$ in our graph, as a consequence of choosing $k_2 = k_4$). The fact that a given optimal enzyme ratio is achieved at a higher value of glucose concentration in the comprehensive model is quite obvious, since in that model the glucose is diffusing from a distant place (unlike in the other two models where $s_0$ represents the glucose concentration at the reaction site). Also, at high glucose concentrations, we expect both enzymes to be saturated with the corresponding substrates (i.e., working at maximum capacity) and so increasing the amount of glucose will not make any difference to the biosensor performance. The three models will give the same result in this regime as the transport effects only affect the availability of substrates at the reaction site.

Next, we studied the dependence of the optimal enzyme ratio on a different parameter associated with our chemical system, namely $k_4/k_2$ which represents the ratio of the catalytic turnover numbers for the two consecutive reactions. The optimal ratio $\zeta$ was plotted against $k_4/k_2$ for the three models and the resulting graphs are shown in Figure 10. Note that, the

![Figure 7](image1.png)

**Figure 7.** Dependence of current on $\zeta$ for different initial concentrations of $s_0$. Steady-state analysis of (a) and (b) comprehensive model, (c) simplified model, and (d) intermediate model.

![Figure 8](image2.png)

**Figure 8.** Dependence of current on $\zeta$ for different values of $k_4/k_2$. Steady-state analysis of (a) and (b) comprehensive model, (c) simplified model, and (d) intermediate model.
simple model predicts a linear relationship between $\frac{k_4}{k_2}$ as illustrated by equation (19). The three models seem to give identical results at low values of $\frac{k_4}{k_2}$, but diverge when the second reaction becomes much faster than the first.

In conclusion, parameter regimes which are characterised by high glucose concentrations and low values of $\frac{k_4}{k_2}$ seem relatively indifferent to the modelling strategy used and so we would recommend the simple model, which is the easiest to analyse. For all the other parameter regions, further understanding of the behaviour of the system is required and our results so far seem to imply that we need to investigate the relationship between diffusion rates and the speeds of the two reactions. An asymptotic analysis based on these parameters will form the subject of a future study.

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