Iterative Construction of the Optimal Sunspot-Number Series

Michal Švanda¹² · Martina Pavelková¹ · Jiří Dvořák³ · Božena Solarová¹

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Abstract
The relative number of sunspots represents the longest evidence describing the level of solar activity. As such, its use goes beyond solar physics, e.g. towards climate research. The construction of a single representative series is a delicate task that involves a combination of the observations of many observers. We propose a new iterative algorithm that allows construction of a target series of relative sunspot number of a hypothetical stable observer by optimally combining series obtained by many observers. We show that our methodology provides us with results that are comparable with recent reconstructions of both sunspot number and group number. Furthermore, the methodology accounts for the possible non-solar changes of observers’ time series such as gradually changing observing conditions or slow change in the observers’ vision. It also provides us with reconstruction uncertainties. We apply the methodology to a limited sample of observations by the ČESLOPOL network and discuss its properties and limitations.

Keywords Solar cycle · Observations · Sunspots · Statistics

1. Introduction
“Counting of sunspots”, usually accompanied by the drawing of the photosphere, belongs to the most archaic methods used in current research. However, this longest-lasting “measurement” provided mankind with important discoveries about our star. The discovery of the 11-year (Schwabe, 1844) and other cycles (see a review by Hathaway, 2010) is the most widely known. Several “by-products” also need to be mentioned here. Let us mention, e.g. the discovery of solar rotation itself (noted already by Galileo Galilei), learning that the Sun does not rotate like a solid body but reveals a differential rotation (Scheiner, 1630; Carrington, 1860), or the discovery of some of the empirical laws of solar activity, such as Spörer’s law (Carrington, 1858; Spörer, 1880).
The counts of sunspots are the only direct records at our disposal to retrace the long-term changes in the solar cycle. The overall level of solar activity is closely related to the solar forcing acting on Earth’s climate (see, e.g. reviews by Solanki, Krivova, and Haigh, 2013; Connolly et al., 2021) Therefore, the number of sunspots and its evolution in time constitute material that is used far beyond solar-physics applications.

A systematic approach was founded by Wolf (1851), who started to record daily observations of the Sun at the Zürich observatory, he later extended his records towards previous years (Wolf, 1861). It was known by that time that sunspots usually do not appear in the photosphere of the Sun isolated but form nests, the groups of sunspots. The discussion on whether it is the count of groups or the count of individual spots that is more important to assess the level of solar activity was circumvented by Wolf, who introduced his “relative number” of sunspots $R$ by combining the counts of both quantities into one index. He weighted the number of groups ten times more as compared to the total number of sunspots, as he realised that it is easier for observers to identify sunspot groups. The weighting by a factor of 10 stemmed from the fact that according to his observations, there were on average about 10 sunspots in one group.

Wolf’s goal was to have daily observations of the Sun, which was of course virtually impossible for a single observer at a single station. Hence, Wolf already established a network of auxiliary observers, where he took their observations when his own were unavailable. In order to do so, he introduced a multiplicative coefficient $k$ that linked his observations to records of other observers so that the magnitudes of the relative numbers matched. This practice continued for years, where the procedure was such that there was always a primary observer and the observations of secondary or even tertiary observers were considered only when the primary observations were missing. The chain of primary observers is the origin of the backbone method (Svalgaard and Schatten, 2016) of combining records of observers together into one composite, which today is used primarily when working with historical data.

In the modern era, the abundance of available observers is much larger, the composite may then be formed using completely different methods, usually based on some sort of averaging. For instance, the International Sunspot Number is derived from a network of stations worldwide using the following two-step algorithm (see Clette et al., 2007; Mathieu et al., 2019).

In the first step, the personal conversions coefficients $k$ are computed with respect to the records obtained at the Locarno pilot station. This is to assure continuity, because the Locarno observing station was used both in the Zürich and Brussels eras (the transition occurred in 1981). For each station, the observations on days when the daily $k$ coefficient deviates by more than $2\sigma$ from the monthly mean are considered outliers and rejected. This is repeated iteratively until the $k$ coefficients lie within the chosen statistical bounds from their monthly means.

In the second step, the transformed $R$ value is computed for each station using the $k$ coefficient determined in the first step and for each day, the network average and its standard deviation is determined. The daily average is compared to the Locarno reference. Should the difference between the Locarno pilot value and the network average exceed the standard network deviation, the Locarno reference is replaced by the network average and the $k$ coefficients are recomputed. Finally, for each day the station values are confronted with the daily network average. Should the $k$-coefficient-transformed relative number differ by more than $1\sigma$ from the network average, the exceeding station value is rejected and the daily average is computed again. This down-selection of observations is repeated again until a stable solution is found. The network daily average is then considered as a final daily relative number $R_i$. 

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Additional sunspot numbers exist, differing slightly by the methodology of their calculation. For instance, the Boulder Sunspot Number is derived from the daily Solar Region Summary produced by the US Air Force and National Oceanic and Atmospheric Administration and utilised sunspot drawings obtained from the Solar Optical Observing Network. The Boulder Sunspot Number was typically about 60% larger than the International Sunspot Number until a large revision of the International Sunspot Number took place in 2015. In the US, another representative sunspot number (Taylor, 1985) is provided by the American Association of Variable Star Observers (AAVSO).

All these datasets differ by details and sometimes in magnitude, they can be considered as independent descriptions or representations of the solar reality. In some of these relative-number series, issues were discovered. For instance, systematically increasing deviations were observed between the International Sunspot Number and the AAVSO number, which were accounted for by a flaw in the AAVSO methodology (Schaefer, 1997; Foster, 1997).

Even the International Sunspot Number was largely revised recently when several issues were discovered and corrected in the historical records (Clette et al., 2014) and even some non-solar trends in the relative numbers in recent decades (Clette and Lefèvre, 2016). This led to a new revised sunspot number (Clette and Lefèvre, 2016) issued by the World Data Center Sunspot Index and Long-term Solar Observations (WDC-SILSO1), which replaced the International Sunspot Number. For the modern era, the independent sunspot numbers now agree quite well. The corrections to the historical records performed recently on the International Sunspot Number by Clette et al. (2014) were not accepted by the entire community (see, e.g. Section 3.4 of Velasco Herrera et al., 2022). The Sunspot Workshops community2 decided that since new data and new techniques are retrieved and developed regularly, the sunspot number and other series should be included in a modern versioning system, like all scientific series.

Various methods of combining many independent observations with unknown uncertainties together to form one composite series suffer from various drawbacks. For instance, the backbone method is prone to jumps or drifts of the primary observer (see, e.g. Lockwood et al., 2016). Weighted averages may also lead to unobserved drifts. To avoid possible issues, it has been common practice not to consider all available observations, but to reject some observations by, e.g. judging the stability of such observer (see, e.g. the description of the WDC-SILSO algorithm above). These criteria often follow some rule of thumb instead of a rigorous assessment, such as, e.g. a pre-selection based on the total number of observations by a particular observer by the AAVSO network (Taylor, 1985).

We propose a methodology of combining time series of several observers together when using as many observations as possible, not excluding any of them explicitly from the beginning and not rejecting any observations during the process. The proposed methodology is developed to be suitable for the networks of several observers, where the number of available daily observations is too small to apply the WDC-SILSO method with outlier rejection. The methodology targets the construction of the series of the hypothetical observer that optimally combines the recordings of the real observers. The methodology is based on a weighted-average approach, where the optimal combination is obtained by using an iterative procedure. This approach allows us to suppress the effects of the existing long-term drifts in individual series. This paper is a first step in the development of a method that will be further tested when a richer set of observations become available.

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1 https://www.sidc.be/silso/
2 https://ssnworkshop.fandom.com/wiki/Home
2. Observations

2.1. ČESLOPOL

Solar observations have a very long tradition in the countries in the area of the current Czech Republic (Pavelková and Švanda, 2021). Already from the beginning of the seventeenth century, drawings of the Sun were recorded by Johann Zimmermann, who was the first known systematic solar observer in the Czech countries. As of the beginning of the nineteenth century, several long-term systematic observers appeared, such as Gregor Mendel or Artur Kraus. With the foundation of the Czech Astronomical Society in 1917 solar observations became a common task among amateur observers within the activities of its Solar Section. In 1964, sunspot drawings were officially declared, by politicians, as a task of national importance and in 1978 a FOTOSFEREX project was initiated (Křivský, 1978a,b).

The goal of the project was to have daily sunspot drawings available, sunspot drawings became the core for the solar-activity predictions issued by the Astronomical Institute of the Czechoslovak Academy of Sciences. One has to bear in mind that in those days access to the world data was strongly limited due to the communist regime and the only solution was the foundation of a local network. The FOTOSFEREX project relied heavily on local observations in Ondřejov, only in the case of unfavourable observing conditions were drawings from auxiliary stations (which included the amateurs) considered. These drawings were sent by telex service to Ondřejov.

With the advent of synoptic programs such as SoHO (Domingo, Fleck, and Poland, 1995) or GONG (Harvey et al., 1996) the interest in using the solar observations obtained by non-professionals decreased significantly and project FOTOSFEREX was shut down in 1998. To promote solar observations in recent years, project ČESLOPOL was initiated.

ČESLOPOL stands for ČESko-SLOvensko-POLská (Czech-Slovak-Polish) network of solar observers working for the Solar Section of the Czech Astronomical Society. At the moment, it includes 24 active observing stations. The network collaborates closely with the Solar patrol of the Astronomical Institute of the Czech Republic (ASU). Not only does it gather current observations of the Sun, it aims to include the complete archive of FOTOSFEREX and the archive of the national task and also to digitise and evaluate historical drawings. The aim of the project ČESLOPOL is to integrate all the sunspot drawings obtained in the historical Czech countries into one large database.

2.2. Data

Observers included in the ČESLOPOL network observe and draw the Sun in the usual way, which is well known among amateur and professional astronomers, usually using the projection technique. The drawings are evaluated also in a standard way, their digitisation is done by a custom software SLUNCE. This is a GUI-based software with a convenient user interface that allows us to simply input semi-evaluated drawings of the photosphere and it computes and stores the data in a digitised form. It also allows us to export the digitised observations in a CSV (comma separated values) format to allow communication with the wider world.

The archive of digitised observations grows every day. Already it is large enough to think about a calculation of an optimal representative relative sunspot number in an automatic way. For the purpose of this study we had the following subsets at our disposal:

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3The program is available for download from https://www.asu.cas.cz/~sunwatch/cs/stranka/ke-stazeni, however, its interface is in the Czech language.
A subset of observations by Ladislav Schmied covering the years 1986 – 1993 from his private observatory in Kunžak. His total personal archive covers the years 1947 – 2012, however, most of these observations have not been digitised yet.

Observations from the Solar Patrol of the Astronomical Institute of the Czech Academy of Sciences from the Ondřejov observatory, covering the years 1986 – 2020. Over the years, two main observers were active there for the long term, František Zloch and Tomáš Vaněk, complemented by several other observers active for shorter times, including the authors of this study. We only add that at the moment, observations from the years 1949 – 2022 have been digitised and are in principle available.

Observations from the Prešov observatory, Slovakia, 1984 – 2009. Again, the time span is larger, but not all the data were properly digitised.

Recordings from the Observatory Prostějov in the years 1991 – 2019.

Scarce observations from the Observatory Uherský Brod distributed over the years 1988 – 2004.

In total, the data archive used in this study contains 16 302 individual digitised sunspot drawings performed by 64 individual observers operating in 5 stations. Yearly counts of processed drawings including the count of non-zero observations (that is where $R > 0$) are given in Figure 1. The plot demonstrates that the count of observations per year varies, it also may depict a long-term trend.

2.3. Data Properties

Among others, three values from the records are most important for our study: the number of recorded sunspot groups $g$, the total number of recorded individual sunspots (umbrae) $f$ and the relative sunspot number $R$, which depends on the former two. Example plots of $R$ from the archive are given in Figure 2, where we plot first a simple average (average of $Rs$ of individual observations obtained on the same day) of our archive and also two examples of observers working for the Solar patrol ASU. The figure shows that the input data are not continuous and that the coverage by various observers may differ significantly. However, each of these observers may cover some important part of the final series, so we do not find it wise to exclude some of them from the beginning. We only point out that case c) in Figure 2 would very likely be excluded from algorithms constructing the WDC-SILSO or AAVSO sunspot numbers due to the short coverage. The inclusion of even such short series allows us to work with individual observers rather than with observing stations, which is the practice, e.g. by WDC-SILSO, considering that even using the same equipment the personal biases may be different for different human beings.
Figure 2 Demonstration of the observations used for this study. a) A simple daily mean of all used observations. b) An example history of an excellent long-term observer František Zloch. c) An example of an episodic observer (the corresponding author of this study served at the Solar patrol during his Ph.D. – only weekend services). The scales and ranges of all panels are intentionally identical.

One of the key factors influencing the “closeness” of the drawing to the solar reality are the observing conditions. In the ČESLOPOL network a five-grade scale of quality of observing conditions $Q$ is established. It is not a rigorous scale, it describes subjectively the level of details that are visible during the observation, see Table 1. Already from the definitions of individual $Q$-values it is clear that the number of recorded sunspots and possibly groups (especially when discussing the single-pore groups of the McIntosh classification Axx) strongly depends on the value of $Q$. The smaller the value, the fewer sunspots will likely be captured and drawn.

First, we studied the long-term evolution of the reported observing conditions by taking the mean of all observations available for a particular day. In Figure 3 one can see clear oscillations with a period of one year, which record the seasonally changing observational conditions. On average, the observing conditions are better in summer, where usually the drawing was recorded early in the morning under decent observing conditions. The conditions gradually worsen towards winter, when in the Czech Republic the weather is usually not favourable for observations. Cloudy skies are often a reality during the days at the end and beginning of the calendar year. The pattern of annual oscillations is quite regular until, say, year 2009; in subsequent years the behaviour seems more chaotic. We believe that this
Table 1  Subjective scale of observation quality $Q$.

| $Q$ | Definition                                                                 |
|-----|-----------------------------------------------------------------------------|
| 1   | only large spots are visible, granulation is not visible; poor observing conditions |
| 2   | smaller spots are also visible, granulation visible only occasionally         |
| 3   | smaller spots are well visible, granulation visible; average observing conditions |
| 4   | granulation and pores readily visible                                      |
| 5   | all the details are observable; exceptional observing conditions           |

![Figure 3](image_url)  The values of $Q$ smoothed by the running average over 13 days.

gradual change has to do with a decreasing number of available observations after 2010, which is evident from Figure 1. The average $Q$ suffers from the small-number statistics here.

In Figure 3 one also notices a gradual growth of average $Q$ in the years 1984–2014 followed by a decrease onwards. In the years 1984–1994 the average $Q$ oscillates around the value of 3, which stands for average observing conditions, hence the scale given in Table 1 corresponds to its definition. Between the years 1998 and 2010 the mean $Q$ is about 3.5 and in the years 2012–2015 it even reaches a mean value of almost 4. After 2018 the mean $Q$ is about 3.5 again. It is not clear why the observing conditions should slowly improve over the long period and then start to worsen again.

If these trends in $Q$ are real, they must introduce a gradual change in the recorded values of $g$, $f$ and consequently $R$. We keep the usual definition of the relative number $R$ as obtained from the observations,

$$ R = 10g + f, \quad (1) $$

where $g$ is the count of sunspot groups and $f$ is the total number of sunspots. When combining the dataset from various observers a personal coefficient $k$ is introduced, which is used traditionally to scale the personal relative number $R$ to the “representative” one $R_i$:

$$ R_i = kR = k(10g + f). \quad (2) $$

The coefficient $k$ includes personal/instrumental biases of the observer. Not only does it scale the observations of an observer to the reference data series, in general it also scales one observer to another (the value naturally depends on the selection of the two series to be compared). Hence, the observations of two observers should be bound by a single scaling coefficient. We test this idea in two ways: first we choose the observations performed by two observers on the same days and compare not only the derived relative numbers $R$, but also
the count of sunspot groups $g$ and the total count of sunspots $f$. Then, we do the same with a more limited sample for the same two observers, for observations obtained on the same day and with the same declared observing conditions. Example plots for one pair of tested observers are given in Figure 4.

We find that the idea of the coefficient scaling is fairly valid, however, the scaling coefficient seems to differ for the number of sunspot groups and for the total number of sunspots. In some cases we found that these coefficients may differ by up to a factor of three. We speculate that this may have to do with the effective resolution of the telescope used, when it may be easier to identify the groups, however, to properly resolve individual spots within the groups may be more difficult.

The scatter plots show a wider distribution along the hypothetical linear fit in the case when different observing conditions were allowed for cross-comparison than when the same observing conditions were requested. Also, the correlation coefficient is usually smaller in the former case.

This simple test shows that the observing conditions play a role in deriving the personal scaling coefficient. This justifies the need for transformation of the obtained observations to optimal ($Q = 5$) observing conditions, even though the effect is small. To achieve the goal we propose to transform $g$ and $f$ to standard conditions by simple linear transforms,

$$g_{\text{red}} = g[1 - c_g(5 - Q)].$$

$$f_{\text{red}} = f[1 - c_f(5 - Q)].$$

The values of linear-fit coefficients $c_g$ and $c_f$ were obtained for each observer independently. In order to have some meaningful estimate we considered only eight observers from our set with the largest number of observations. For each of these observers we considered linear relations similar to (3) and (4), where $g$ and $f$ values represented those of the observer and $g_{\text{red}}$ and $f_{\text{red}}$ were taken from the international sunspot number SILSO v2.0 for the same days.\(^4\) We realise that the definition of $Q$ is somewhat fuzzy, hence, we assumed an uncertainty of 0.5 for each $Q$ value in the least-squares linear fit. Furthermore, only non-zero values of $g$ and $f$ were considered in the fit.

The values of $c_g$ and $c_f$ obtained for eight observers show a spread; however, they are all negative. This fact confirms the assumption that the reduction of observations to better observing conditions must increase the $g$ and $f$ values, as if the observer would see more spots and more groups under better conditions. The representative values of $c_g = -0.0348$ and $c_f = -0.0780$ with standard deviations of 0.0046 and 0.0190, respectively, were obtained from the weighted average of the fits for the eight observers, the weights reflected the number of observations considered in the individual fits. The reduction to optimal observing conditions is one of the novel points of our methodology.

The subjective or somewhat objective judgement or description of the observing conditions may be different for other sunspot-drawing collection projects. We believe that our approach of transforming the relative numbers to fixed (e.g. optimal) observing conditions may be modified accordingly.

\(^4\)In principle, the coefficients might be derived with respect to any reasonable description of $g$ and $f$. An option other than the SILSO sunspot number would be, for instance, a simple mean as plotted in panel a) in Figure 2. Another option would be to perform the process iteratively: (i) set both $c_g$ and $c_f$ to zero, (ii) perform the optimisation run as described by our methodology, use the resulting series as the reference, (iii) determine $c_g$ and $c_f$ with respect to this new reference and (iv) run a final optimisation.
Figure 4  Example of direct comparison of two observers. Each cross corresponds to the value obtained by the two observers on the same day (red) and on the same day and with the same declared conditions (blue). The corresponding correlation coefficients are given in the plot in the corresponding colours. Counts of groups, spots and the reported relative number are plotted in individual panels. In the displayed case, the studied overlap period was more than 20 years and included 286 “blue” and 1561 “red” days to be compared. Note that in the plots in the upper row we added a small random jitter to the value to avoid point overlapping.
Now that we have the reduction coefficients for (3) and (4), we are able to transform observations of all observers to optimal observing conditions and invoke them in the construction of the optimal series of relative sunspot number. Finally, we note that the values of \(g_{\text{red}}\) and \(f_{\text{red}}\) are kept with a floating precision for further use and not rounded to integers, as one might expect from their natural interpretation.

3. Methodology

In this study we propose an iterative method of calculation of the representative relative sunspot number from a set of observations delivered by different observers. Our methodology does not prefer any of these observers and does not exclude any of them at the same time. It uses all observations and constructs the representative series in an optimal way.

The premise is that all the observers observe the same Sun. However, due to their personal/instrumental biases and local possibly varying observing conditions their recordings may differ not only from the real Sun, but also when records of different observers are mutually compared. The goal is to find the optimal estimate of the real situation on the Sun that mimics the best the recordings of individual observers and at the same time estimate the level of their personal/instrumental biases and their changes over time. In fact, we construct a time series of a hypothetical observer (who corresponds to the primary observer in the backbone method) by taking all available observations into account not preferring any of the real observers. The aim is to remove the dependence on the reference observer (which is the core of the backbone method). This is important because the personal/instrumental bias of the backbone may also change with time.

3.1. Conversion Coefficients

The personal scaling coefficients are in fact key to the success of combination of series obtained by many observers into one representative series. The coefficients \(k\) may change slowly with time. We realised that the two quantities \(g\) and \(f\) are too different in nature that one scaling coefficient may not be enough to cover all possible observing issues. Instead, we use two personal coefficients, \(k_g\) and \(k_f\) that take into account personal/instrumental biases in the conversion of the observers’ records to the representative relative number \(R_0\):

\[
R_0 = 10k_g g + k_f f. \tag{5}
\]

Here again, both \(k_g\) and \(k_f\) are allowed to change with time.

We would like to combine all sets obtained by individual observers together into the composite series (which we term the target series hereafter) to robustly describe the real evolution of sunspot count on the Sun. The idea of the personal coefficients may easily be tested on a set of observers that have at least some overlapping days. This procedure requires a somewhat robust calculation of the conversion coefficients. In the case of more observers in the sample it should in principle be possible to compute the conversion coefficient of observers 1 and 2 by using an intermediate observer 3, when the coefficients between observer 1 and 3 and observer 3 and 2 are known. This procedure is also termed “daisy-chaining” by Lockwood et al. (2016).

Our tests showed that the idea holds only approximately. We used the whole digitised archive for a selection of long-term observers to test the idea. Table 2 shows a typical example, where the conversion coefficient between observer Ladislav Schmied and observer Ivan...
Table 2  Example of testing of the recalculation of count of groups $g$ and count of spots $f$ by recalculation from data series by other observers.

| Way                        | $k_g$ |
|-----------------------------|-------|
| Schmied Ladislav → Ivan     | 0.375 |
| Schmied Ladislav → Vaněk Tomáš → Ivan | 0.296 |
| Schmied Ladislav → Zloch František → Ivan | 0.444 |
| Schmied Ladislav → Černohousová → Ivan | 0.501 |
| Average (Schmied Ladislav → 1 observer → Ivan) | 0.416 |
| Average (Schmied Ladislav → 2 observers → Ivan) | 0.449 |

| Way                        | $k_f$ |
|-----------------------------|-------|
| Schmied Ladislav → Ivan     | 0.800 |
| Schmied Ladislav → Vaněk Tomáš → Ivan | 0.600 |
| Schmied Ladislav → Zloch František → Ivan | 0.833 |
| Schmied Ladislav → Černohousová → Ivan | 1.000 |
| Average (Schmied Ladislav → 1 observer → Ivan) | 0.811 |
| Average (Schmied Ladislav → 2 observers → Ivan) | 0.849 |

($k_g = 0.375$, $k_f = 0.800$) are approximated satisfactorily when using one observer in the middle ($k_g = 0.415$, $k_f = 0.811$ on average) or even involving a two-step observer chain in the middle ($k_g = 0.449$, $k_f = 0.849$). Some other tests between other observers turned out better with a better agreement, some worse. The tests usually showed that the values of $k_g$ and $k_f$ may be significantly different, thus justifying our use of these separate coefficients.

We have to stress that in this test we computed the values of the conversion coefficients for all the overlapping observations, hence, we did not allow for the change of the conversion coefficients in time. Also, the number of mutual pairs of observations suitable for the computation of the conversion coefficients varied among observers; however, we did not introduce any weighting. Given the simplifications we consider the results of these tests to be not excellent but satisfactory. Finally, we would like to point out that the methodology in principle allows us to determine the (virtual) conversion coefficients of two observers who did not have any overlapping observations (see, e.g. Table 3). In our database this was the case, for instance, of observers alternating at the Solar patrol at the Ondřejov observatory, where only one drawing per day was considered for the archive and hence these observers never made drawings on the same day. However, the virtual conversion coefficients when using one observer in the middle and two observers in the middle provide a very reasonable match.

3.2. The Algorithm

Most of the relative sunspot-number composites rely on a pilot station to ensure continuity. The pilot station then holds a special status in the observers network. We would like to eliminate this need for the pilot station, because, e.g. in the network of amateur observers, it is difficult or even undesirable to define a pilot station. We would also like to split observing teams at stations into a set of individuals. Unfortunately, there still is a need to calibrate one observer to another by using the personal $k$ coefficients. Unlike in the procedure used in WDC-SILSO, we would like to separate the calculation of the personal conversion coefficients from the construction of the network composite, at least so that these two different steps do not use the same set of observations. At the same time, we target the usage of our
Table 3  Similar to Table 2 only for a pair of observers who did not have any common observing day because they alternated at the Solar patrol in Ondřejov.

| Way                              | $k_g$ |
|----------------------------------|-------|
| Vaněk Tomáš $\rightarrow$ Zloch František | N/A   |
| Vaněk Tomáš $\rightarrow$ Schmied Ladislav $\rightarrow$ Zloch František | 1.389 |
| Vaněk Tomáš $\rightarrow$ Černohousová $\rightarrow$ Zloch František | 1.143 |
| Vaněk Tomáš $\rightarrow$ Ivan $\rightarrow$ Zloch František | 1.000 |
| Average (Vaněk Tomáš $\rightarrow$ 1 observer $\rightarrow$ Zloch František) | 1.177 |
| Average (Vaněk Tomáš $\rightarrow$ 2 observers $\rightarrow$ Zloch František) | 1.189 |

| Way                              | $k_f$ |
|----------------------------------|-------|
| Vaněk Tomáš $\rightarrow$ Zloch František | N/A   |
| Vaněk Tomáš $\rightarrow$ Schmied Ladislav $\rightarrow$ Zloch František | 1.511 |
| Vaněk Tomáš $\rightarrow$ Černohousová $\rightarrow$ Zloch František | 1.080 |
| Vaněk Tomáš $\rightarrow$ Ivan $\rightarrow$ Zloch František | 1.005 |
| Average (Vaněk Tomáš $\rightarrow$ 1 observer $\rightarrow$ Zloch František) | 1.199 |
| Average (Vaněk Tomáš $\rightarrow$ 2 observers $\rightarrow$ Zloch František) | 1.231 |

Figure 5  Schematic cartoon illustrating two consecutive steps of the method. Within the window $W$ the coefficients of all available observers (within that window) and the reference series are evaluated. In the following window $\Delta W$ these coefficients are used to predict what the target series would be taking the observations of other observers into account.

code to networks with a few observers, maybe a few dozen of them, definitely not as many as are included in the WDC-SILSO network.

To compute a target sunspot-number series by taking into account observations from a set of observers we propose an iterative methodology. It is schematically displayed in Figure 5. The methodology is in principle divided into two alternating major steps: the period of evaluation (of the personal coefficients) and a subsequent period of prediction (of expected number of groups and sunspots). In both of the periods we work with the target series $g_0$ and $f_0$, from which the target relative number $R_0$ is computed by using (1). The target series $g_0$ and $f_0$ is built piece-by-piece during the program run.

At the start, the target series does not exist as yet, so for the evaluation of the first set of personal coefficients an initial series is used. The sensitivity of the procedure to selection of the initial series will be discussed in detail later in the paper (Section 4.4). At this moment, a natural choice would be some series that is sufficiently “solar-like”. The use of the observa-
tions of a long-term observer, who is expected to be somewhat stable, should be sufficient. During the program run, the segments of the target series provisionally filled by the initial series are replaced by the properly computed values of the target.

In the period of evaluation, which is performed in a time window having a length of \( W \), we follow the logic outlined by (5). For each observer \( \alpha \) who provided observations in the evaluation period, we compute her/his personal coefficients \( k^\alpha_g \) and \( k^\alpha_f \), which optimally scale his/her values to the target series. Each and every observation \( j \) that yields a pair of values \( g^\alpha_j \) and \( f^\alpha_j \) is first reduced to the optimal observing conditions by (3) and (4). To improve the stability of the evaluation period, we consider only those observations where \( g^\alpha_j > 1 \) and \( f^\alpha_j > 5 \).

Then, for each observation we compute the instant conversion coefficients

\[
\begin{align*}
k^\alpha_{g,j} &= g^\alpha_{j,\text{red}} / g_0 \quad \text{and} \quad k^\alpha_{f,j} = f^\alpha_{j,\text{red}} / f_0.
\end{align*}
\]  

(6)

The representative coefficients for the evaluation period having length \( W \) are then computed as an arithmetic average over all determined instant coefficients, simply as:

\[
\begin{align*}
k^\alpha_g &= \frac{1}{M^\alpha} \sum_{j \in W} k^\alpha_{g,j} \quad \text{and} \quad k^\alpha_f = \frac{1}{M^\alpha} \sum_{j \in W} k^\alpha_{f,j},
\end{align*}
\]  

(7)

where \( M^\alpha \) is the total number of observations of a given observer within the evaluation window fulfilling the thresholding condition given above. For each observer we thus obtain representative (within the window of length \( W \)) scaling coefficients and we also keep number \( M^\alpha \) that will serve as a measure of the quality of determination of these coefficients.

Then, we move forward to the prediction period. This occurs in a window of length \( \Delta W \), which immediately follows the evaluation period in time. In this period we “predict” the target series from the observations of other observers by using their personal conversion coefficients, which were determined during the previous period of evaluation.

In the prediction window having length of \( \Delta W \) we progress on a day-by-day basis. For each day \( D \) we identify a subset of observers with personal conversion coefficients from the previous evaluation period that provide observations for this particular day. By using an observer \( \beta \) we obtain a prediction based on this observer, \( g^\beta_0 \) and \( f^\beta_0 \):

\[
\begin{align*}
g^\beta_0 (D) &= k^\beta_g g^\beta (D) \quad \text{and} \quad f^\beta_0 (D) = k^\beta_f f^\beta (D).
\end{align*}
\]  

(8)

The composite prediction \( g_0 (D) \) and \( f_0 (D) \) is computed as a weighted average over observers \( \beta \), where the weights correspond to the number of observations \( M^\beta \) that served to determine the conversion coefficients in the evaluation period:

\[
\begin{align*}
g_0 (D) &= \sum_{\beta} w^\beta g^\beta_0 (D) \quad \text{and} \quad f_0 (D) = \sum_{\beta} w^\beta f^\beta_0 (D),
\end{align*}
\]  

(9)

with

\[
\begin{align*}
w^\beta = \frac{M^\beta}{\sum_{\beta} M^\beta}.
\end{align*}
\]  

(10)

\footnote{Note that a set of identifiers \( \beta \) forms a subset of the set of identifiers \( \alpha \). In the prediction period, some of the observers from the set of \( \alpha \) may be missing (they did not observe). Similarly, there might be observations provided by other observers, for which the coefficients from the previous evaluation period do not exist (they did not observe during the evaluation period). Such an observer is not considered in forming the composite within the given prediction window.}
As a final step before storing the composite prediction to target we round-off \( g_0 \) and \( f_0 \) to integers and compute \( R_0(D) = 10g_0(D) + f_0(D) \). The rounded predicted composites for a set of days \( D \) within the window of length \( \Delta W \) are added to the target series after the evaluation window of length \( W \) in the direction of the time arrow. The days from the prediction window, when no observations are available, remain unfilled.

Next, we slide the evaluation window by \( \Delta W \) forward in time and repeat the process. This adds a new segment having a length of \( \Delta W \) to the end of the target series. We slide again by \( \Delta W \) until we reach the end of the series of available observations. We refer to the progress following the arrow of time as the “half-iteration”.

To complete the “iteration” we now switch the progress against the arrow of time and start from the end of the series. All the values of the target series are dropped except for the values located in the window of \( W \) days at the very end of the series. We then repeat the procedure described above against the arrow of time by subsequent sliding by \( \Delta W \) until we reach the beginning of the series. At each step a new segment of the target series is built in front (in the direction of the time arrow) of the target series. That is, a scheme displayed in Figure 5 is mirrored in the horizontal direction. The progress is stopped when the beginning of the available observations is reached. The progression against the arrow of time makes the target series denser because it allows us to also fill days where the common observations were not available in the first half-iteration.

If necessary, the process may go iteratively back and forth again. In that case, the process starts from the \( W \)-day long window of the target series from the previous iteration, all the other values of the target series beyond this starting window are dropped. The target series is then built again by segments from the start without a direct connection to the previous realisation (except for the starting \( W \)-day long window).

4. Testing the Methodology

Our proposed methodology contains several non-trivial steps that need to be justified by testing.

4.1. Validation of the Principle

In the prediction step, the choice of the weighted average with the reduction of observations to optimal observing conditions is not obvious. The choice is based on testing of various predictive models.

The tests were performed separately again for eight observers with the largest number of observations in the data we have at our disposal. The testing followed the principles usual in machine-learning methods. For each observer considered (termed the tested observer henceforth), we split his/her observations into two equally populated halves in time. The first half mimicked the evaluation period of the algorithm described in the previous section, whereas the second half mimicked the prediction period and served as validation of the predictive model.

Following the reduced version of the methodology, we computed personal conversion coefficients of other observers with respect to the tested observer in the first half of his/her recordings. Then, we used a set of predictive models to predict what the tested observer should record in the second half. The existence of the real tested observer’s observations

---

\(^{6}\)Note that this target series cropping also drops all the values from the initial series.
Figure 6  In the upper panel one can see the observations of the tested observer (F. Zloch) as compared with their predictions by using various tested models. In the bottom panel, the corresponding relative residua are shown. Only one year, 2003, from the validation period spanning over 14 years is displayed.

during the second half allowed us to compare the predictions with observations and to determine the success rates of various predictive models.

In the evaluation, we considered the following set of predictive models:

*Previous observation*  This is a simple model that does not involve other observers, however, it is used in testing of machine-learning methods. In the validation period, we considered the previously available observation of the tested observer as the prediction.

*Long-term average*  Again, this is a simplified model that does not involve other observers, but it is used in testing the machine-learning methods. The prediction is based on the average of observations of the tested observer over the previous 30 days.

*Average*  For the given day, the observations of other available observers are scaled by the appropriate coefficients $k_g^A$ and $k_f^A$ and an arithmetic mean over all of these observers is considered. The personal conversion coefficients were computed by using raw non-reduced observations, i.e. with $c_g = 0$ and $c_f = 0$ in (3) and (4).

*Weighted average*  This predictive model is similar to the previous one, only weighting given by (10) is applied. The logic behind weighting says that when more pairs during the evaluation period are available, the derived coefficients are expected to be more robust.

*Weighted average with Q correction*  This predictive model is again an improvement on the previous. In the evaluation period, both the observations of the tested observer and the other observers are reduced to observing conditions with $Q = 5$ by using (3) and (4).

To assess the success rate of various models we employ the visual comparison (such as that displayed in Figure 6 for observer František Zloch) and the following four statistical
Table 4  Example statistical evaluation of various considered predictive models, here summarised for F. Zloch over the validation period of 14 years.

| Model               | $RB(f)$ | $RMSE(f)$ | $RB(g)$ | $RMSE(g)$ | $RB(R)$ | $RMSE(R)$ |
|---------------------|---------|-----------|---------|-----------|---------|-----------|
| Previous observation| 0.087   | 0.262     | 0.321   | 3.354     | 0.095   | 0.334     |
| Long-term average   | 0.109   | 0.263     | 0.582   | 4.896     | 0.118   | 0.383     |
| Average             | −0.098  | 0.062     | −0.125  | 0.197     | −0.114  | 0.073     |
| Weighted average    | −0.102  | 0.061     | −0.111  | 0.206     | −0.110  | 0.075     |
| Weighted average,   | −0.136  | 0.068     | −0.206  | 0.200     | −0.170  | 0.082     |
| Q correction        |         |           |         |           |         |           |

quantities. For each predictive model we evaluated the relative mean bias $RB$

$$RB(t) = \frac{1}{N} \sum_{i}^{N} \frac{(t_{i,m} - t_{i,o})}{t_{i,o}},$$  

(11)

where $t$ is the tested value $t = \{g, f, R\}$, $N$ is the number of validated pairs, $t_{i,m}$ is the model prediction, $t_{i,o}$ is the observation. Similarly, we defined the relative mean squared error

$$RMSE(t) = \frac{1}{N} \sum_{i}^{N} \left[ \frac{(t_{i,m} - t_{i,o})}{t_{i,o}} \right]^2.$$  

(12)

As auxiliary criteria we also used the maxima and minima of the relative residuals,

$$\min_{\delta t} = \min_{i < 1 < N} \left[ \frac{(t_{i,m} - t_{i,o})}{t_{i,o}} \right]$$  and

$$\max_{\delta t} = \max_{i < 1 < N} \left[ \frac{(t_{i,m} - t_{i,o})}{t_{i,o}} \right].$$  

(13)

The quantities corresponding to the example in Figure 6 are given in Table 4. The situation for the other seven observers is very similar, hence, the conclusions drawn from the example of František Zloch are general.

We see that the model of previous observation and long-term average has the largest residuals and from the tested predictive models performs the worst. This could be expected for the long-term average model, because when using a 30-day average it cannot reproduce the day-to-day changes, however, it is somewhat surprising that it does not perform significantly worse than the previous observation model. The typical time scale for significant changes on the surface of the Sun is a few days. On the other hand, it cannot be guaranteed that the previous observation was always on the previous day, which would assure a gradual change. We find both these models to be unsuitable.
The other models, on the other hand, seem to perform comparably. The only statistical quantity where the model weighted average with Q correction performs slightly better is the maximum of the relative residuum. It would seem that inclusion of the reduction to the fixed observing conditions helps to suppress the outliers.

Following these tests we gave the preference to the latest predictive model over the others. Lastly, we would like to point out that in these tests we did not allow for changes of the values of personal conversion coefficients with time. They do evolve, however, and neglecting this effect might increase the level of deviations reproduced in the assessed statistical quantities.

### 4.2. Long-Term Trends in Observers’ Coefficients

The previous sections formed the principles of our methodology that allowed us to finalise the computer code (Švanda, 2022). It is written in Python when using Numpy (Harris et al., 2020) and Pandas (McKinney, 2010) packages. Especially the latter one allowed us to write a flexible and universal code. What is missing is to determine the optimal lengths of evaluation window $W$, the prediction window $\Delta W$ and the number of iterations.

To set a reasonable value of $W$ we need to look at the evolution of the conversion coefficients. We computed the personal conversion coefficients of each observer in our dataset with respect to the reference series, which was constructed as a simple mean of the available observations and then averaged over 28 days (one solar rotation). The coefficients were computed in a sliding window having $W = 1000$ days, which is the shortest reasonable value given the scarcity of our dataset. Shorter windows may be possible, however, our dataset is not dense enough, so that in shorter windows the coefficients are not representative as only a small number of pairs entering (6) is available.

Then, we plotted the statistics of the conversion coefficients of all available observers in Figure 7. The bars are centred on the mean value of the conversion coefficients of all
observers within the considered window and extend $1\sigma$ to either side. Interestingly enough, the coefficients as compared to the mean observations seem to be correlated with the solar cycle, that is they on average seem to increase during the maxima and decrease during the minima. This is especially prominent in the case of $k_g$.

We may only speculate as to what the cause of this trend is. During the maxima, the observers are overwhelmed by an overall increased activity, so that some of them easily miss, for instance, the Axx-type groups (in McIntosh, 1990, classification it represents an isolated pore). Also, possibly, the splitting of the complicated sunspot nests into an appropriate number of magnetically coupled groups may be difficult for visual observers. On the other hand, during the minima the observers pay special attention when scanning the solar disc and hence find even the smallest Axx-type groups.

The long-term evolution of the personal conversion coefficients sets limits on an appropriate selection of the length of $W$, which should be longer than a solar cycle. The values of $W$ shorter than a cycle may introduce rising/declining trends in the conversion coefficients that affect the overall determination of $R_0$. Too short $W$s thus lead to an inappropriate evaluation of the coefficients, where during the consecutive windows shifted by $\Delta W$ one can see a positive feedback leading to the incorrect solution.

The above-described hypothesis based on the rules-of-thumb may be tested by exploring a large $(W, \Delta W)$ space. We performed the execution of our code for a set of $W$s and $\Delta W$s and studied the effects of the choice on the two important quantities.

First, we introduced a misfit. The misfit describes how well the target series represents the actual records of the individual observers. The misfit is then defined as

\[
\text{misfit} = \left[ \frac{1}{ND} \sum_D \sum_{\beta} \left( R_0(D) - \left[ 10k^\beta_g(D)g^\beta(D) + k^\beta_f(D)f^\beta(D) \right] \right)^2 \sum_{\beta} M^\beta \right]^{1/2}.
\]  

(15)

The misfit in fact evaluates the mean-squared deviation of the target series and $k$-coefficient-transformed values of individual observers, evaluated for all considered observers $\beta$ and in all days $D$. The values of the misfit are displayed in Figure 8 in the left panel. The misfit is very small for small $W$s, then there is a plateau between, say, $W = 3000$ days and $W = 6000$ days and for larger values of $W$ the misfit gradually increases. We interpret the figure in such a way that for $W < 3000$ days the methodology fits the observations very well, because it naturally allows for fast changes of the personal scaling coefficients. For $W > 6000$ days the misfit increases because the personal coefficients vary on shorter time scales. In other words, for $W < 3000$ days the method overfits the data, whereas for $W > 6000$ days it underfits the data. The reasonable values of $W$ then naturally lie within the plateau between 3000 and 6000 days. The dependence on $\Delta W$ is much weaker, it would seem that within the $W$-plateau $\Delta W < 3000$ days does not affect the misfit significantly.

Another quantity we consider is the overall trend in the personal conversion coefficients. For each day we compute the mean personal conversion coefficients for observers who provided their records on that day and its standard deviation. Then, we use a linear fit through the mean personal coefficients with standard deviations as measurement errors in time. This allows us to obtain a slope of a general linear trend in the personal scaling coefficients. The fit is performed independently for $k_g$ and $k_f$, however, $k_f$ shows a stronger dependence on $W$ and $\Delta W$ and hence it is considered further. In general, one expects the slope of the overall trend in the scaling coefficients to be around zero. Non-zero trends indicate a systematic problem either with the target series (the solution) or with a large portion of the observations. Naturally, non-linear, e.g. oscillating, trends cannot be excluded and such trends, in
principle, could escape detection by the linear fitting. Due to the two-step nature of our algorithm the systematic deviations of the personal scaling coefficients multiply during the construction of the target series and usually produce a long-term systematic trend that would be revealed by the linear fit.

The map of the $k_f$ trend is plotted in Figure 8 in the right panel. According to this the optimal values of $W$ lie around 6000 days, where it is better to use a rather small value of $\Delta W$.

This may easily be demonstrated by comparing the results of runs differing only by choice of $W$, as plotted in Figure 9. There, a solution with a short $W = 1000$ days differs significantly in the overall amplitude from the solution with $W = 5000$ days, whereas the overall structure of the resulting target series is very close (with a Pearson’s correlation coefficient close to unity). We tested that the overall increasing or decreasing trend in the amplitude of the resulting $R_0$ is indeed due to the trends in the personal conversion coefficients, as for such a solution plots similar to that presented in Figure 7 clearly show an almost steady decrease or increase.

The choice of an appropriate $W$ and $\Delta W$ is thus not straightforward. One should pay attention to appropriately assess the properties of the resulting series and evaluate critically the auxiliary criteria. Such a criterion is again a plot like that in Figure 7, where a gradually increasing or decreasing trend usually indicates an inappropriate (too short) choice of $W$.

Also, coefficients of individual observers are to be studied. For instance, when a personal coefficient of an observer changes by more than 50% over a few years, this indicates a serious issue with the observations of this observer. Should this kind of rapid change be seen for several observers, that on the other hand is an indication of an inappropriate selection of $W$. In our case, we found a choice of $W = 5000$ days to be a good trade-off between the suppression of the cycle-related changes and time resolution (compare Figures 7 and 10, where cycle-related changes are suppressed).

Figure 8 forces us to use a rather small value of $\Delta W$ for the selected $W = 5000$ days. There are, however, again other considerations. With a larger $\Delta W$ a temporal resolution in the determination of the coefficients is lost and one may then miss, e.g. an unexpected trend in someone’s coefficients. On the other hand, the choice of $\Delta W$ too short poses a risk of not finding enough suitable observers in the prediction period, which poses a risk of interruption in building the target series by adding an empty segment of the length of $\Delta W$ to the end. This usually occurs for short $\Delta W$ during the deep and long minimum, because only observations where $g > 0$ and $f > 5$ are considered. A similar situation occurs when there is a long gap

Figure 8 Maps of the auxiliary criteria helping to determine optimal values of $W$ and $\Delta W$. On the left a map of misfits (15) is plotted, on the right we plot the slope of the linear trend of the average personal scaling coefficient $k_f$. 
Figure 9  Two different solutions of $R$ by our methodology obtained with $W = 1000$ days and $W = 5000$ days (the fiducial solution), both with $\Delta W = 100$ days. Obviously, both solutions are highly correlated, however, the solution with a smaller $W$ shows a clear envelope trend (the overall amplitude of $R$ is considerably smaller during Cycles 23 and 24. This envelope trend is seen in the lower panel, where the ratio of two solutions from the upper panel is plotted. This behaviour is due to the trend in the conversion coefficients that were evaluated on scales shorter than the cycle-long oscillation.

Figure 10  Same as Figure 7, except these plots were obtained with $W = 5000$ days.

in observations. In the case when these empty segments accumulate, the building does not recover after passing the minimum or the gap and the code run leads to a valid but shortened target series. In our case, we found an optimal choice of $\Delta W = 100$ days.
4.3. Number of Iterations

As we indicated in the description of the calculation algorithm, in principle, the process is iterative. It is not clear from the beginning as to how many iterations are necessary in order to obtain a stable solution or even if the iterative procedure converges. With the code, it is easy to test this, however, many iterations may be lengthy. Using our set of about 16,000 individual observations one full iteration takes a few minutes running single-thread on an M1-based Macbook Air.

Statistical quantities defined by Equations (11) and (12) provide us with suitable quantities that could be used to study the convergence of the iterations. Therefore, using analogous formulae, we evaluate the mean difference and the mean squared difference of the computed $R_0$ between consecutive iterations. Both quantities are plotted in Figure 11 for the solutions with $W = 5000$ days and $\Delta W = 100$ days.

To properly interpret Figure 11 we recall that the term “half-iteration” indicates the progression through the data series respecting the time arrow, “full iteration” includes also the backward propagation against the arrow of time. Each point in the plot then gives the overall $RB$ comparing the results from the previous half/full iteration. By looking at panel a), one would perhaps naively choose, e.g. the point at three iterations, where the $RB$ seems considerably smaller than for two iterations. However, this means that the 3rd iteration is very similar to the 2nd iteration and hence the 3rd iteration does not bring forward any significant improvement. In the panel b) it is even more evident that two iterations are sufficient.

Putting all the above-given arguments together, our fiducial solution respecting optimally the properties of the archive of observations we are processing has thus the following choice of free parameters: The width of the evaluation window $W = 5000$ days, the width of the prediction window $\Delta W = 100$ days and two full iterations.

4.4. Sensitivity to the Choice of the Initial Series

Our methodology is iterative, therefore there must exist an initial guess of the target series, which is used for the evaluation of the weights in the first evaluation windows. A successful methodology should be rather robust with respect to the utilisation of the initial series.

In the paragraphs above, we pointed out that a reasonable choice of the initial series is anything “solar-like”, that is, it should somewhat resemble the expected solution in terms of the general trends. One obvious choice is to use the observations of one respected observer, experienced enough and with a large set of observations available. From the methodology...
Table 5 Mutual correlation coefficients and multiplicative coefficients of final sunspot number when using different initial observations.

|             | Zloch  | Schmied | Ivan  | Average |
|-------------|--------|---------|-------|---------|
| Zloch       | 1.0000 | 0.9987  | 0.9998| 0.9998  |
| Schmied     | 0.9987 | 1.0000  | 0.9983| 0.9987  |
| Ivan        | 0.9998 | 0.9983  | 1.0000| 0.9999  |
| Average     | 0.9998 | 0.9987  | 0.9999| 1.0000  |

Slopes

|             | Zloch  | Schmied | Ivan  | Average |
|-------------|--------|---------|-------|---------|
| Zloch       | 1.0000 | 0.7637  | 1.0390| 0.9726  |
| Schmied     | 1.3078 | 1.0000  | 1.3586| 1.2721  |
| Ivan        | 0.9623 | 0.7349  | 1.0000| 0.9361  |
| Average     | 1.0280 | 0.7851  | 1.0682| 1.0000  |

it follows that this observer should provide us with observations that span over a period at least $W$ long, otherwise it will not be possible to compute the personal conversion coefficients of the other observers. Professional observers or devoted amateurs usually fulfill this condition. In our case we focused to the observers working for the Solar patrol at the Ondřejov observatory, namely František Zloch. From the Czech amateurs we certainly must mention Ladislav Schmied, who in his private observatory drew the Sun for 66 years having altogether more than 12 500 drawings. Unfortunately, not all drawings by Ladislav Schmied have been digitised yet.

Another choice would be some sort of aggregated series. A choice that offers itself automatically is a simple arithmetic average of all observations in the series. Such a choice ensures that the general solar trends (such as the 11-year cycle) will be respected and also it ensures that for each considered day there will be at least one observer for which one may determine the conversion coefficients.

Our tests show that the results only weakly depend on the choice of the initial series in terms of the evolution in time. This is demonstrated in Table 5. Here, we evaluated two statistical quantities comparing the results of the fiducial runs with different initial series. First, we compute Pearson’s correlation coefficient, then we compute the quantity we refer to as slope. The slope corresponds to the optimal multiplicative factor between two series in the least-squares sense. It basically gives the slope of the linear fit without a constant term. Table 5 clearly shows that the resulting series does not depend on the initial series in terms of the evolution in time, that is, the correlation coefficients are close to unity. However, due to the different conversion coefficient of the initial series the overall amplitude may differ. That is, the resulting $R_0$ series computed from different initial series are identical except for the multiplicative scaling.

The scaling is indeed multiplicative only, as shown, e.g. in Figure 12, where the solution starting from observer F. Zloch is directly compared with the solution starting from L. Schmied (note that this pair of observers has a large scaling factor – cf. Table 5). The ratios of both solutions vary around the slope value (which is 0.7637 in this case), the histogram indicates the relative residuals being single modal and its shape is what one expects from the multiplicative model. The mutual scatter plot does not indicate any problem either.

The multiplicative scaling found for various initial series is a natural property of our methodology. As we pointed out, the methodology aims to construct a target series of ob-
Figure 12  Direct comparison of the sunspot number resulting from our code with the initial series coming from F. Zloch and L. Schmied. In the upper panel, the ratio of the solutions is plotted with respect to time. In the bottom-left panel the corresponding relative numbers are plotted against each other, in the bottom-right panel one can see the histogram of the ratios plotted in the upper panel.

servations by a hypothetical stable observer who combined the best of all. The choice of the initial series thus influences the overall magnitude of the target series, it influences the “personal coefficients” of the hypothetical observer. Real observers are known to have different scaling coefficients and ours is not an exception. In addition, various definitions of relative sunspot numbers used in the world have or had overall different magnitudes, as already discussed in the Introduction.

The resulting target series $R_0$ consequently differs from the initial one considerably. This difference is plotted for instance in Figure 13, upper panel, where we took František Zloch as an initial. One can see that even in the first evaluation windows between 1986–1999 the fiducial solution differs from the initial series. Due to the use of the observations of other observers, the target series is longer – it starts in the years before the initial series was available and naturally extends beyond the end of the initial series.

Finally, we would like to add that the sensitivity to the initial series is so low that even with a flat initial series (that is a series where both $g$ and $f$ were constant) convergence occurred to a solution that had the same character as the others (see Figure 13, bottom panel). One can note the considerably different amplitude as compared to the solution initiating from F. Zloch.

5. Concluding Remarks

In this paper we describe a new iterative methodology that allows us to compute a target series of sunspot numbers. It does not rely on a single reference observer, it in fact uses as much information as possible. The methodology is very robust and except for the overall amplitude, it provides us with essentially the same solution regardless of the initial series.
Our methodology consists of a modification of the current WDC-SILSO methodology. The main differences are the following:

- We do not use a pilot station. Our resulting composite does not favour any of the observers and constructs a series of the “hypothetical” stable observer. As a consequence, the overall amplitude is not constrained. When comparing with other concurrent series, it should be normalised, using a methodology similar to normalisation of one observer to another.
- We split the determination of the personal scaling coefficients and the computation of the composite. Those two steps use the independent set of observations.
- We use all the available observations and do not reject any of them on the statistical basis. This makes our methodology suitable for smaller networks with a rather scarce coverage. In a sense, it constitutes a compromise between the backbone method and the modern statistically driven methods.
- We use two personal scaling coefficients of the observers, one for the number of groups and one for the number of sunspots. These coefficients are allowed to slowly change with time independently.
- Our methodology is iterative and builds the target composite step-by-step. It always uses all the input data and naturally allows an inclusion of the newly discovered archival observations, should any appear later.

The question is, how does our computed relative number compare to the “official” international products? This can easily be demonstrated by plots and statistical properties. In Figure 14 we show a comparison of our fiducial solution with F. Zloch as initial and the sunspot number SILSO v2.0 (Clette et al., 2014). It can be seen that the overall agreement is very good, Pearson’s correlation coefficient reaches $\rho = 0.99$. It is clear from the plot that our solution has a smaller overall magnitude, the scaling coefficient is approximately 0.863. The ratio between the fiducial $R$ and SILSO v2.0 sunspot number is quite stable with time except for a few outliers in the minimum phase, the histogram of ratios shows the unimodality (Figure 15).
SILSO sunspot number is not the only one available in the community. A solar index of a slightly different nature is the group number GN, introduced by Hoyt and Schatten (1998). We compare this index recalculated by Vaquero et al. (2016) with the number of groups, which is computed as a by-product of our method. Figure 16 shows an excellent agreement between the two series, again, the ratio is stable over the period available for comparison (Figure 17).

The code returns not only the resulting reference $g_0$, $f_0$ and $R_0$, it naturally keeps and returns the personal conversion coefficients of each observer. It therefore allows us to study the performance of individual observers ex-post and allows us to control possible overall trends that would invalidate the solution.

In Figure 18 we plot personal conversion coefficients of two observers used in our study. They both depict a gradual change. We need to note here that the apparently smooth curve is over-sampled due to the selection of our fiducial solution ($W = 5000$ days, $\Delta W = 100$ days). The effective time resolution is $W/2 = 2500$ days, which is about 6.8 years. Either way, a decrease of $k_f$ after year about 2000 is evident in the left panel. This would
mean that F. Zloch suddenly systematically saw considerably larger number of sunspots, whereas his $k_f$ remained more-or-less the same, that is, he at the same time registered a constant number of sunspot groups.

In fact, it is possible to explain this gradual change in $k_f$. It has become a practice at the Solar patrol at the end of 1990s to use an ex-post camera aid to cross-check the drawing obtained by projection using a small 63-mm telescope with the direct observations by a 20-cm telescope at a large magnification. This hypothesis is confirmed by the fact that the personal conversion coefficients of the other Solar patrol observers active at the same time showed similar trends. This change in observing methodology was not written in the logs; either way it became a common practice that was used until this generation of observers retired. The new observers at the Solar patrol do not follow this practice and rely only on projection by the 63-mm telescope.
The other displayed trends of the observer Božena Černohousová from the Prostějov observatory indicated constantly growing personal conversion coefficients, $k_f$ with a larger growth rate than $k_g$, which very likely indicates a gradually worsening vision.

Lastly, we would like to point out that since the reference values of $g_0$ and $f_0$ are obtained by means of sample averaging, it is possible to compute formal statistical uncertainties of those two variables. By following the principle of propagation of uncertainties (Wikipedia contributors, 2022) we hence obtain statistical uncertainty of $R_0$ as well. For our fiducial solution we plot the uncertainties of $R_0$ in Figure 19.

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**Author contributions** MŠ designed the research, wrote the code, processed the data, wrote an initial manuscript draft. MP and BS digitised the observations. JD contributed the methodology from the mathematical point of view. All authors read and contributed to all manuscript versions.

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**Data Availability** The data are available upon reasonable request to the corresponding author. The compiled database used in this study is available as an example via GitHub repository. https://github.com/michalsvanda/sunspot_numbers.

**Code Availability** The code (Švanda, 2022) is available via the GitHub repository. https://github.com/michalsvanda/sunspot_numbers
Declarations

Competing interests The authors declare no competing interests.

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