INHOMOGENEOUS SHEARLET COORBIT SPACES

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Abstract. In this paper we establish inhomogeneous coorbit spaces related to the continuous shearlet transform and the weighted Lebesgue spaces $L_{p,v}, p \geq 1$, for certain weights $v$. We present an inhomogeneous shearlet frame for $L_2(\mathbb{R}^d)$ which gives rise to a reproducing kernel $R_\delta$ that is not contained in the space $A_{1,m,v}$. To show that the inhomogeneous shearlet coorbit spaces are Banach spaces we introduce a generalization of the approach of Fornasier, Rauhut and Ullrich.

1. Introduction

When analyzing a given signal, the decomposition of the signal into a certain set of building blocks is crucial. Which kinds of building blocks to choose depends on the information that one wants to extract from the signal. Very popular kinds of building blocks are wavelets, especially when dealing with signals with isolated singularities. Because of its isotropic nature, the wavelet transform cannot efficiently deal with anisotropic features, therefore several extensions of this framework were proposed, among those the shearlet transform. While the wavelets consist only of dilated and translated copies of a mother function, the shearlets are also sheared in each scale, thereby changing the orientation of the functions. This makes them especially well suited to deal with localized directional features in a signal. Indeed, it was shown in Ref.\cite{14,18} that the shearlet transform can be used to resolve the wavefront set of a signal and in Ref.\cite{16} that the approximation of cartoon-like images with shearlets is optimally sparse.

Another main advantage of shearlets, which sets them apart from other such frameworks like the ridgelets,\cite{2} curvelets,\cite{1} or contourlets,\cite{8} for example, is, that the continuous shearlet transform, introduced and investigated in Ref.,\cite{4,6,15} stems from the action of a square-integrable representation of a topological group, the so-called full shearlet group $\mathbb{S}$. This property makes it possible to use the abstract coorbit theory, developed by Feichtinger and Gröchenig in Ref.,\cite{9,10,11} to define smoothness spaces related to the shearlet transform by measuring the decay of the voice transform. Shearlet coorbit spaces were investigated by Dahlke et al in a series of papers,\cite{3,7} Since the shearlets being used to construct these spaces need to have vanishing moments, any polynomial part in a signal is ignored by the transform because for a polynomial $g$ one has $\mathcal{S}H(f + g)(x) = \langle f + g, \psi_x \rangle = \langle f, \psi_x \rangle = \mathcal{S}Hf(x)$. This leads to the resulting shearlet coorbit spaces being homogeneous spaces. However, in practice the smoothness spaces being used, for example to analyze the regularity of the solution space of an operator equation, are usually inhomogeneous. Therefore, inhomogeneous smoothness spaces related to the shearlet transform are also of interest. In this paper we introduce non-homogeneous shearlet coorbit spaces by using a generalization of the coorbit theory developed by Fornasier, Rauhut, Ullrich et al,\cite{12,17,20} Their approach uses a more general parameter space for the transform, resulting in more design flexibility. Instead of the parameter space being a locally compact topological group, it is only assumed to be a locally compact topological Hausdorff space, thereby allowing the construction of inhomogeneous coorbit spaces. Moreover it is needed for the reproducing kernel $R_\delta$ to be integrable, which poses difficulties in some applications. For that reason we present a generalization of their approach in the sense that we only need $R_\delta$ to be integrable for parameters $q > 1$.

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1.1. Outline. After giving a short overview of the main definitions and results of this generalized coorbit theory in Section 2, we use this approach in Section 3 to define a new shearlet transform given by a continuous frame \( \mathcal{F} = \{ \psi_x \}_{x \in X} \) through the action

\[
\mathcal{S} \mathcal{H}_\mathcal{F} f(x) = \langle f, \psi_x \rangle, \quad x \in X,
\]

where the frame is indexed by a topological Hausdorff space \( X \) (without group structure). We prove that an integrability condition for (integration) parameters \( q > 1 \) on the kernel function

\[
R_{\mathcal{F}} : X \times X \to \mathbb{C}, \quad (x, y) \mapsto \langle \psi_y, \psi_x \rangle
\]

holds so that the coorbit spaces

\[
\mathcal{S} \mathcal{C}_\mathcal{F}^r = \{ f | \mathcal{S} \mathcal{H}_\mathcal{F} f \in L_{p,v}(X) \}, \quad p \geq 1, v_r, n \text{ weight function on } X,
\]

classifying distributions by the decay of their transform, are well-defined Banach spaces. As it turns out these spaces coincide for different \( \tau \). Furthermore we restrict ourselves to the case of odd dimensions. This is due to the fact that otherwise our specific construction of the frame is not well-defined.

We also note that there are other approaches, not based on coorbit space theory, to develop inhomogeneous shearlet smoothness spaces. In Ref. Labate, Mantovani and Negi used the notion of decomposition spaces to define shearlet smoothness spaces, while in Ref. Vera applied the framework of the \( \varphi \)-transform, introduced by Frazier and Jawerth, for this purpose.

1.2. Notation. We finish this section by stating a few notational conventions. Throughout this paper \( d \in \mathbb{N} \) with \( d \geq 2 \) is the space dimension. We usually treat elements \( x \in \mathbb{R}^d \) as \( x = (x_1, \ldots, x_d) \) with \( \tilde{x} = (x_2, \ldots, x_d) \in \mathbb{R}^{d-1} \). For two elements \( x, y \in \mathbb{R}^d \) we use the canonical inner product

\[
x \cdot y = \sum_{i=1}^d x_i y_i.
\]

The convention \( \mathbb{R}^* \) is used for the set \( \mathbb{R} \setminus \{0\} \), \( \mathbb{R}_+ \) will denote the set of all positive real numbers and \( \mathbb{R}_{\geq 0} \) the set of all non-negative real numbers.

For a measure space \( (X, \Sigma, \mu) \) with a weight function \( v : X \to (0, \infty) \) we denote the usual (weighted) Lebesgue spaces by \( L_{p,v}(X, \mu) \) or just by \( L_{p,v} \), if the respective measure space is clear from the context, while \( L^1_{\text{loc}}(X, \mu) \) is used for the space of locally integrable functions on \( X \). The norm for the weighted Lebesgue spaces is hereby given through \( \| f \|_{L_{p,v}} = \| f \cdot v \|_{L_p} \). For the unweighted Lebesgue spaces with \( v \equiv 1 \) we write \( L_p(X, \mu) \) and \( L_p \). We use the Hilbert space \( L_2(\mathbb{R}^d) \) of complex-valued, square-integrable functions on \( \mathbb{R}^d \) with the inner product

\[
\langle f, g \rangle_{L_2(\mathbb{R}^d)} = \int_{\mathbb{R}^d} f(x) \overline{g(x)} \, dx.
\]

For two functions \( f, g \in L_2(\mathbb{R}^d) \) the convolution product \( f \ast g \) is defined as

\[
(f \ast g)(x) = \int_{\mathbb{R}^d} f(y) g(x - y) \, dy.
\]

We write \( \mathcal{C}^k, k \in \mathbb{N}_0 \) for the space of functions \( f : \mathbb{R}^d \to \mathbb{C} \), for which all (classical) partial derivatives \( \partial^\alpha f \) for \( \alpha \in \mathbb{N}_0^d, |\alpha| \leq k \) exist and are continuous. We also use \( \mathcal{C}^k_{\infty} \) for the space of infinitely differentiable functions on \( \mathbb{R}^d \) with compact support and \( \mathcal{S} \) denotes the spaces of Schwartz-functions on \( \mathbb{R}^d \).

We will use the letter \( q \) to refer to the kernel spaces \( \mathcal{A}_q \) and \( \tau, \sigma \) to refer to the integrability parameters of the spaces of test functions \( \mathcal{H}_\tau \). We denote with \( p' = \frac{p}{p-1} \) the Hölder-dual of \( p \geq 1 \).

Concerning the Fourier transform of a function \( f \in L_1(\mathbb{R}^d) \) we write \( \hat{f} = \mathcal{F}(f) \) using the convention

\[
\mathcal{F}(f)(\omega) := \int_{\mathbb{R}^d} f(x) e^{-2\pi i \omega \cdot x} \, dx, \quad \omega \in \mathbb{R}^d,
\]

with the same symbol being used for the extension to functions \( f \in L_2(\mathbb{R}^d) \).
Given a measure space \((X, \Sigma, \mu)\) we say that a Banach space \(Y\) of locally integrable, complex-valued functions on \(X\) satisfies Condition (\(Y\)), if it is solid, i.e. if from \(f \in L^1_{\text{loc}}(X, \mu), g \in Y\) with \(|f| \leq |g|\) almost everywhere it follows that \(f \in Y\) with \(\|f\| \leq \|g\|\). Lastly, for quantities \(a\) and \(b\) we write \(a \lesssim b\) if there exists a finite constant \(C > 0\) so that \(a \leq C \cdot b\), with the constant being independent of the relevant parameters.

2. Generalized coorbit theory

In this section we give a short overview of the generalized coorbit theory. We follow Ref.\(^\text{12,20}\) in our exposition. For our setting we introduce a generalization of their approach with respect to an additional integrability parameter.

To generalize the classical coorbit theory—which assumes a locally compact group as the underlying parameter space of the respective transform—the generalization of Fornasier and Rauhut allows for the parameter space to be of a more general nature. In this case the parameter space \(X\) is only assumed to be a locally compact Hausdorff space equipped with a positive Radon measure \(\mu\). In the following \(\mathcal{H}\) denotes a separable Hilbert space (the signal space), which is usually \(L_2\), and \(\psi\) is a weight function on \(X\) while \(Y\) is a Banach space of equivalence classes of almost everywhere equal, complex-valued functions on \(X\). We start with a set of functions \(\mathfrak{F} = \{\psi_x\}_{x \in X} \subset \mathcal{H}\), which is indexed by the parameter space, and constitutes a tight continuous frame. I.e., the map \(X \to \mathcal{C}, x \mapsto (f, \psi_x)\) is measurable for each \(f \in \mathcal{H}\) and there exists a finite constant \(A > 0\) such that

\[
A \|f\|_{\mathcal{H}}^2 = \int_X |(f, \psi_x)|^2 d\mu(x) \quad \text{for all } f \in \mathcal{H}.
\]

Based on \(\mathfrak{F}\), a signal transform on the space \(\mathcal{H}\) is introduced in the following way.

**Definition 2.1.** Let \(\mathfrak{F} = \{\psi_x\}_{x \in X} \subset \mathcal{H}\) be a tight continuous frame. Then the associated voice transform is defined as the mapping

\[
V_{\mathfrak{F}} : \mathcal{H} \to L_2(X, \mu), \quad f \mapsto V_{\mathfrak{F}} f
\]

with

\[
V_{\mathfrak{F}} f : X \to \mathcal{C}, \quad x \mapsto (f, \psi_x).
\]

The above transform is well defined due to (2.1).

2.1. Kernel spaces. In order for the resulting smoothness spaces to be well defined, conditions on the voice transform \(V_{\mathfrak{F}}\) and therefore conditions on \(\mathfrak{F}\) are needed. In this approach the kernel function

\[
R_{\mathfrak{F}} : X \times X \to \mathcal{C}, (x, y) \mapsto R_{\mathfrak{F}}(x, y) := V_{\mathfrak{F}} \psi_y(x) = \langle \psi_y, \psi_x \rangle,
\]

the reproducing kernel, is used. To formulate certain conditions on this kernel function the following spaces, classifying kernel functions in terms of integrability, are used. For \(1 \leq q \leq \infty\) let

\[
A_q := \left\{ K : X \times X \to \mathcal{C} : K \text{ is measurable, } \|K|_{A_q}\| < \infty \right\}
\]

with

\[
\|K|_{A_q}\| := \max \left\{ \text{ess sup}_{x \in X} \left( \int_X |K(x, y)|^q d\mu(y) \right)^{1/q}, \text{ess sup}_{y \in X} \left( \int_X |K(x, y)|^q d\mu(x) \right)^{1/q} \right\}
\]

and the usual adaptation for \(q = \infty\). Through a weight function \(v \geq 1\) on \(X\) a kernel weight function is defined via

\[
m_v : X \times X \to (0, \infty), (x, y) \mapsto \max \left\{ \frac{v(x)}{v(y)}, \frac{v(y)}{v(x)} \right\}.
\]
Now the associated weighted kernel space $A_{q,m_v}$ is given by

$$A_{q,m_v} := \left\{ K : X \times X \to C : K \cdot m_v \in A_q \right\}$$

where

$$\| K | A_{q,m_v} \| := \| K \cdot m_v | A_q \|.$$

In the following, depending on the context, $K$ will also denote the kernel operator induced by the kernel function acting on a function $F$ through

$$K(F)(x) := \int_X K(x,y)F(y) \, d\mu(y) \text{ for } x \in X.$$ 

This way a reproducing identity is established through the action of $R_3$, namely $R_3(V_3 f) = V_3 f$ for all $f \in \mathcal{H}$. The following auxiliary Lemma for kernel operators underlines the importance of the kernel spaces $A_{q,m_v}$.

**Lemma 2.1.** Let $K$ be a kernel with $K \in A_{q,m_v}$ for all $q > 1$. Then we have the continuous embeddings

$$K(L_{p,v}(X,\mu)) \hookrightarrow L_{r,v}(X,\mu)$$

for all $1 < p < r \leq \infty$.

**Proof.** For fixed $1 < p < r < \infty$ and $g \in L_{p,v}(X,\mu)$ with $\|g|L_{p,v}\| \leq 1$ arbitrary one has

$$\|K(g)|L_{r,v}\| = \sup_{h \in L_{r',\frac{p}{p'}}} |\langle K(g), h \rangle|$$

$$\leq \sup_{h \in L_{r',\frac{p}{p'}}} \int_X \int_X |K(x,y)g(y)h(x)| \, d\mu(x) \, d\mu(y)$$

$$=: \sup_{h \in L_{r',\frac{p}{p'}}} I_{K,p,r},$$

where $r'$ denotes the Hölder-dual of $r$ satisfying $1/r + 1/r' = 1$. For some $0 < \varepsilon < 1/p - 1/r$ we set

$$\alpha := r > 0, \beta := p' > 0, \gamma := 1/p - 1/r > 0, \alpha := 1/r + \varepsilon, \beta := p/r, \gamma := 1/r' - \varepsilon, d := r'/p',$$

$$e := 1 - p/r, f := r'/p - r'/r.$$ These choices suffice the following relations:

$$1/\alpha + 1/\beta + 1/\gamma = 1, \quad \alpha + c = 1, \quad b\alpha = p, \quad d\beta = r', \quad a\alpha > 1,$$

$$b + e = 1, \quad e\gamma = p, \quad f\gamma = r', \quad c\beta > 1,$$

$$d + f = 1.$$ 

By applying the three-way Young inequality, see Lemma A.2, we obtain

$$I_{K,p,r} \leq \int_X \int_X |K(x,y)m_v(x,y)|^a |f(y)v(y)|^b \cdot |K(x,y)m_v(x,y)|^c |h(x)v(x)^{-1}|^d$$

$$\cdot |g(y)v(y)|^e |h(x)v(x)^{-1}|^f \, d\mu(x) \, d\mu(y)$$

$$\leq \frac{1}{\alpha} \int_X \int_X |K(x,y)m_v(x,y)|^{a\alpha} |g(y)v(y)|^{p\alpha} \, d\mu(x) \, d\mu(y)$$

$$+ \frac{1}{\beta} \int_X \int_X |K(x,y)m_v(x,y)|^{c\beta} |h(x)v(x)^{-1}|^{r'\beta} \, d\mu(x) \, d\mu(y)$$

$$+ \frac{1}{\gamma} \int_X \int_X |g(y)v(y)|^{p\gamma} |h(x)v(x)^{-1}|^{r'\gamma} \, d\mu(x) \, d\mu(y).$$
For the first summand we deduce the estimation
\[
\int_X \int_X |K(x, y)m_v(x, y)|^{α_a} |g(y)v(y)|^p \, dμ(x) \, dμ(y)
\]
\[
\leq \left( \text{ess sup}_{y \in X} \int_X |K(x, y)|^{α_a} |m_v(x, y)|^{α_a} \, dμ(x) \right) \int_X |g(y)|^p |v(y)|^p \, dμ(y)
\]
\[
\leq \|K|A_{α_a, m_v}|^{α_a} \|g|L_{p,v}|\|^p
\]
and the other two summands can be treated analogously. Thus we obtain
\[
I_{K, p, v} \leq \frac{1}{α} \|K|A_{α_a, m_v}|^{α_a} \|g|L_{p,v}|\|^p + \frac{1}{β} \|K|A_{cβ, m_v}|^{cβ} \|h|L_{r', \frac{1}{p'}}\|^r
\]
\[
+ \frac{1}{γ} \|g|L_{p,v}|\|^p \|h|L_{r', \frac{1}{p'}}\|^r
\]
\[
\leq \max \left\{ 1, \|K|A_{α_a, m_v}|^{α_a}, \|K|A_{cβ, m_v}|^{cβ} \right\} =: C_K
\]
for all \( g, h \). Hence, \( \|K|L_{p,v} \to L_{r,v}| \leq C_K \).

If \( 1 < p < r = \infty \) and \( g \in L_p(X, μ) \) arbitrary, it follows with Hölder’s inequality that
\[
\|K(g)|L_{∞, v}| \leq \text{ess sup}_{x \in X} \int_X |K(x, y)m_v(x, y)| \cdot |g(y)v(y)| \, dμ(y)
\]
\[
\leq \|K|A_{p', m_v}|^{p'} \|g|L_{p,v}|\|^p,
\]
which concludes the proof. \( \square \)

**Remark.** (i) The assumptions in Lemma 2.1 can be weakened in the sense, that we only need specific \( q > 1 \) for the assertion to hold, but this setting is sufficient for our work.

(ii) The proof is similar to the proof of Schur’s test, also known as the generalized Young inequality.

By letting \( K \in A_{1, m_v} \) and \( p = r \) it follows that \( 1/γ = 0 \) and \( α_a = cβ = 1 \). This means we only use the two-way Young inequality and we are in the setting of Schur’s test, see Lemma A.3.

2.2. **Coorbit spaces.** Before introducing coorbit spaces the concept of signals can first be generalized from elements of the Hilbert space \( \mathcal{H} \) to a suitable space of distributions. First of all, for \( 1 ≤ τ ≤ 2 \) consider the spaces
\[
\mathcal{H}_{τ,v} := \{ f \in \mathcal{H}, V_b f \in L_{τ,v}(X, μ) \}
\]
of test functions equipped with the natural norm
\[
\| f|\mathcal{H}_{τ,v}| : = \| V_b f|L_{τ,v}|.
\]
First we note, that these spaces are non-empty, moreover the following Lemma holds.

**Lemma 2.2.** If \( R_β \in A_{τ,m_v} \), then \( \mathcal{F} \subset \mathcal{H}_{τ,v} \).

**Proof.** For \( x \in X \) arbitrary one has
\[
\|ψ_v|\mathcal{H}_{τ,v}| = \int_X |V_b^τ ψ_v(x)|^v(y)^\tau \, dμ(y)
\]
\[
≤ v(x)^\tau \int_X |R_β(y, x)|^τ m_v(y, x)^\tau \, dμ(y)
\]
\[
≤ v(x)^\tau \|R_β|A_{τ,m_v}|\|^τ,
\]
which proves the assertion. \( \square \)

Since \( \mathcal{F} \) establishes a frame for \( \mathcal{H} \) this means \( \mathcal{H}_{τ,v} \subset \mathcal{H} \) is dense. Moreover, the spaces \( \mathcal{H}_{τ,v} \) are Banach spaces, as the following Lemma states.

**Lemma 2.3.** If \( R_β \in A_{τ'm_v} \) then the space \( \mathcal{H}_{τ,v} \) is a Banach space.
Proof. Let \( \{f_n\}_{n \in \mathbb{N}} \subset \mathcal{H}_{\tau,v} \subset \mathcal{H} \) be a Cauchy sequence, which means \( \{g_n\}_{n \in \mathbb{N}} := \{V_{\tilde{g}} f_n\}_{n \in \mathbb{N}} \) is a Cauchy sequence in \( L_{\tau,v}(X,\mu) \). By the completeness of \( L_{\tau,v} \) there exists a unique \( g \in L_{\tau,v} \) with \( g_n \to g \). Furthermore, by the reproducing formula it holds \( R_{\tilde{g}}(g_n) = g_n \) for all \( n \in \mathbb{N} \), which implies \( R_{\tilde{g}}(g) = g \). Then, by Hölder’s inequality, for every \( x \in X \) it holds

\[
|R_{\tilde{g}}(g)(x)| \leq \int_X |R_{\tilde{g}}(x,y)g(y)| \, d\mu(y) \\
\leq \|R_{\tilde{g}}(x,\cdot)\|_{L_{\tau',\frac{1}{2}}} \cdot \|g\|_{L_{\tau,v}} \\
\leq v(x)^{-1}\|R_{\tilde{g}}(1)\|_{A_{\tau',mv}} \cdot \|g\|_{L_{\tau,v}}.
\]

Thus, \( g = R_{\tilde{g}}(g) \in L_\infty \) and since \( L_\infty \cap L_{\tau,v} \subset L_2 \) it follows \( g \in L_2 \). Since the application of \( R_{\tilde{g}} \) is the orthogonal projection from \( L_2 \) onto the image of \( V_{\tilde{g}} \) there exists \( f \in \mathcal{H} \) such that \( g = V_{\tilde{g}} f \). Moreover, \( V_{\tilde{g}} f \in L_{\tau,v} \) means \( f \in \mathcal{H}_{\tau,v} \) and \( f_n \to f \) in \( \mathcal{H}_{\tau,v} \).

Hence, this set of test functions leads to the Gelfand triple setting of dense embeddings

\[
\mathcal{H}_{\tau,v} \hookrightarrow \mathcal{H} \cong \mathcal{H}^* \hookrightarrow (\mathcal{H}_{\tau,v})^*
\]

with \((\mathcal{H}_{\tau,v})^*\) being the canonical anti-dual space (the space of all conjugate linear, continuous functionals) of \( \mathcal{H}_{\tau,v} \) and this space can be interpreted as a space of distributions. An element \( h \in (\mathcal{H}_{\tau,v})^* \) is hereby identified with the functional \( f \mapsto \langle h,f \rangle \). With these embeddings it is possible to extend the notion of the voice transform in a canonical way to elements \( f \in (\mathcal{H}_{\tau,v})^* \) by \( V_{\tilde{g},\tau} f(x) = f(\psi_x) \). By Lemma 2.2 this is well defined.

With assumptions on the reproducing kernel we can prove the following nesting property.

Lemma 2.4. If \( R_{\tilde{g}} \in A_{q,m_v} \) for every \( q > 1 \) then \( \mathcal{H}_{\sigma,v} \subset \mathcal{H}_{\tau,v} \) and \((\mathcal{H}_{\tau,v})^* \subset (\mathcal{H}_{\sigma,v})^* \) for all \( \sigma < \tau \).

Proof. Assume \( f \in \mathcal{H}_{\sigma,v} \), which means \( f \in \mathcal{H} \) with \( V_{\tilde{g}} f \in L_{\sigma,v} \). Since the reproducing identity holds it follows \( V_{\tilde{g}} f = R_{\tilde{g}}(V_{\tilde{g}} f) \in R_{\tilde{g}}(L_{\sigma,v}) \) and with Lemma 2.1 we derive \( V_{\tilde{g}} f \in L_{\tau,v} \), hence \( f \in \mathcal{H}_{\tau,v} \). The second assertion is immediate.

For the coorbit spaces to be well defined we need the following two auxiliary Lemmas.

Lemma 2.5. The expression \( \|V_{\tilde{g},\tau} f\|_{L_{\tau',\frac{1}{2}}(X,\mu)} \) is an equivalent norm on \((\mathcal{H}_{\tau,v})^*\), where \( \tau' \) denotes the Hölder-dual of \( \tau \).

Proof. First we note that \( V_{\tilde{g}} \) is acting as a unitary operator on \( \mathcal{H} \), and so does \( V_{\tilde{g},\tau} \). Moreover, by definition we have \( V_{\tilde{g},\tau}(\mathcal{H}_{\tau,v}) = L_2 \cap L_{\tau,v} \), which is dense in \( L_{\tau,v} \). Then, by definition of the norm one has

\[
\|F\|_{(\mathcal{H}_{\tau,v})^*} = \sup_{h \in \mathcal{H}_{\tau,v}, \|h\|_{L_{\tau,v}} \leq 1} |\langle F, h \rangle| \\
= \sup_{h \in \mathcal{H}_{\tau,v}, \|h\|_{L_{\tau,v}} \leq 1} |\langle V_{\tilde{g},\tau} F, V_{\tilde{g},\tau} h \rangle| \\
= \sup_{H \in V_{\tilde{g},\tau}(\mathcal{H}_{\tau,v}), \|H\|_{L_{\tau,v}} \leq 1} |\langle V_{\tilde{g},\tau} F, H \rangle| \\
= \sup_{H \in L_{\tau,v}, \|H\|_{L_{\tau,v}} \leq 1} |\langle V_{\tilde{g},\tau} F, H \rangle| \\
= \|V_{\tilde{g},\tau} F\|_{L_{\tau',\frac{1}{2}}},
\]

which concludes the proof.

Lemma 2.6. (i) For \( f \in (\mathcal{H}_{\tau,v})^* \) it holds \( V_{\tilde{g},\tau} f \in L_{\tau',\frac{1}{2}} \) and the mappings \( V_{\tilde{g},\tau} : (\mathcal{H}_{\tau,v})^* \to L_{\tau',\frac{1}{2}} \) are injective.
(ii) The reproducing formula extends to \((\mathcal{H}_{\tau,v})^\sim\), i.e. \(R_\delta(V_{\delta,\tau}f) = V_{\delta,\tau}f\) for all \(f \in (\mathcal{H}_{\tau,v})^\sim\).

(iii) Conversely, if \(F \in L_{\tau, \frac{1}{\nu}}\) satisfies the reproducing property \(R_\delta(F) = F\) then there exists \(f \in (\mathcal{H}_{\tau,v})^\sim\) such that \(V_{\delta,\tau}f = F\).

**Proof.** (i) The assertion follows immediately from Lemma 2.5.

(ii) Suppose that \(f \in (\mathcal{H}_{\tau,v})^\sim\). Since \(X\) is \(\sigma\)-compact there exists a sequence of nested compact subsets \((U_n)_{n \in \mathbb{N}}\) such that \(X = \bigcup_{n \in \mathbb{N}} U_n\). Denote by \(\chi_{U_n}\) the characteristic function of \(U_n\) and let \(F_n := \chi_{U_n} V_{\delta,\tau}f \in L_2\). Obviously this series converges pointwise to \(V_{\delta,\tau}f\). For any \(x \in X\) we then have

\[
R_\delta(x,y) F_n(y) = \begin{cases} R_\delta(x,y) V_{\delta,\tau}f(y), & y \in U_n, \\ 0, & \text{else,} \end{cases}
\]

which means that \(|R_\delta(x,y) F_n(y)| \leq |R_\delta(x,y) V_{\delta,\tau}f(y)|\) for all \(y \in X\). Furthermore the expression \(R_\delta(x,y) V_{\delta,\tau}f\) is \(L_1\)-integrable and by Hölder’s inequality we obtain the estimation

\[
\|R_\delta(x,\cdot) V_{\delta,\tau}f\|_{L_1} \leq \|R_\delta(x,\cdot)\|_{L_{\tau,\nu}} \|V_{\delta,\tau}f\|_{L_{\tau,\nu}^\sim} \leq \nu(x) \|A_{\tau,\mu}\| \|f\|_{(\mathcal{H}_{\tau,v})^\sim} \]

for every \(x \in X\). Since the reproducing property holds for every \(F_n\) and because of Lebesgue’s convergence theorem we obtain

\[
V_{\delta,\tau}f(x) = \lim_{n \to \infty} F_n(x) = \lim_{n \to \infty} \int_X R_\delta(x,y) F_n(y) d\mu(y) = \int_X R_\delta(x,y) V_{\delta,\tau}f(y) d\mu(y) = R_\delta(V_{\delta,\tau}f)(x).
\]

(iii) The adjoint mapping of \(V_{\delta,\tau} : \mathcal{H}_{\tau,v} \to L_{\tau,v}\) is given by

\[
V_{\delta,v}^* : L_{\tau,v}^\sim \to (\mathcal{H}_{\tau,v})^\sim, \quad V_{\delta,v}^* F = \int_X F(x) \psi_x d\mu(x) \quad \text{for } F \in L_{\tau,\nu}^\sim.
\]

Thus for \(f := V_{\delta,v}^* F \in (\mathcal{H}_{\tau,v})^\sim\) it holds

\[
F(y) = R_\delta F(y) = \int_X (\psi_x, \psi_y) F(x) d\mu(x) = V_{\delta,\tau} V_{\delta,v}^* F(y) = V_{\delta,v}^* f(y)
\]

for every \(y \in X\). \(\square\)

Now we are ready to define the coorbit spaces.

**Definition 2.2.** The coorbit spaces of \(L_{p,v}(X,\mu)\) with respect to the frame \(\mathfrak{F} = \{\psi_x\}_{x \in X}\) and the integrability parameter \(\tau\) are defined as

\[
\text{Co}_{\mathfrak{F},\tau}(L_{p,v}) := \{ f \in (\mathcal{H}_{\tau,v})^\sim : V_{\delta,\tau}f \in L_{p,v}(X,\mu) \}
\]

endowed with the natural norms

\[
\|f\|_{\text{Co}_{\mathfrak{F},\tau}(L_{p,v})} := \|V_{\delta,\tau}f\|_{L_{p,v}}.
\]

The following proposition is essential when dealing with coorbit spaces.

**Proposition 2.7.** Suppose that \(R_\delta(L_{p,v}) \subset L_{\tau,\frac{1}{\nu}}\).

(i) A function \(F \in L_{p,v}\) is of the form \(V_{\delta,\tau} f\) for some \(f \in \text{Co}_{\mathfrak{F},\tau}(L_{p,v})\) if and only if \(R_\delta F = F\).

(ii) The spaces \((\text{Co}_{\mathfrak{F},\tau}(L_{p,v}), \|\cdot\|_{\text{Co}_{\mathfrak{F},\tau}(L_{p,v})})\) are Banach spaces.

(iii) The map \(V_{\delta,\tau} : \text{Co}_{\mathfrak{F},\tau}(L_{p,v}) \to L_{p,v}\) induces an isometric isomorphism between \(\text{Co}_{\mathfrak{F},\tau}(L_{p,v})\) and the reproducing kernel space \(\{F \in L_{p,v} : R_\delta F = F\} \subset L_{p,v}\).
Proof. (i) Assume \( f \in \text{Co}_{\bar{\mathfrak{g}},\tau}(L_{p,v}) \), then by definition \( f \in (H_{\tau,v})^\sim \) and by Lemma 2.6 ii) the reproducing identity holds. Conversely, if \( f \in L_{p,v} \) satisfies \( R_{\mathfrak{g}} f = f \) we deduce by our assumption \( f \in L_{\tau', v'} \).

Lemma 2.6 iii) implies that there exists \( f \in (H_{\tau,v})^\sim \) such that \( V_{\mathfrak{g}} f = f \), which shows the assertion.

(ii) Suppose that \( \{f_n\}_{n \in \mathbb{N}} \) is a Cauchy sequence in \( \text{Co}_{\bar{\mathfrak{g}},\tau}(L_{p,v}) \) implying that \( f_n := V_{\mathfrak{g}} f_n \) is a Cauchy sequence in \( L_{p,v} \). By the completeness of \( L_{p,v} \) this sequence converges to an element \( F \in L_{p,v} \). By i) it holds \( R_{\mathfrak{g}} f_n = f_n \) for all \( n \in \mathbb{N} \) and hence \( R_{\mathfrak{g}} F = F \). Again by i) there exists an \( f \in \text{Co}_{\bar{\mathfrak{g}},\tau}(L_{p,v}) \) with \( V_{\mathfrak{g}} f = f \) and the completeness is shown.

(iii) The assertion follows with (i) and the injectivity of \( V_{\mathfrak{g},\tau} \).

Remark 2. The assumption in Proposition 2.7 may appear strange, but is readily fulfilled for the following setting. If we assume \( R_{\mathfrak{g}} \in \mathcal{A}_{q,m_v} \) for all \( q > 1 \) then it follows from Lemma 2.1 that \( R_{\mathfrak{g}}(L_{p,v}) \subset L_{\tau',v'} \subset L_{\tau', v'} \) for all \( 1 < p < \tau' < \infty \).

2.3. Dependency on \( \tau, p, v \) and \( \mathfrak{g} \). We will now discuss the dependency of the coorbit spaces on the parameters involved. To this end we always assume \( R_{\mathfrak{g}} \in \mathcal{A}_{q,m_v} \) for all \( q > 1 \) as suggested in Remark 2.

We can obtain some nesting properties for the parameters \( \tau \) and \( p \) as well as the weight \( v \).

Lemma 2.8. (i) For all \( \sigma < \tau \) we have \( \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) \subset \text{Co}_{\mathfrak{g},\sigma}(L_{p,v}) \).

(ii) For all \( p < r \) we have \( \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) \subset \text{Co}_{\mathfrak{g},\tau}(L_{r,v}) \).

(iii) For two weights fulfilling \( v \leq w \) we have \( \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) \subset \text{Co}_{\mathfrak{g},\tau}(L_{p,w}) \).

Proof. (i) This follows immediately from Lemma 2.4.

(ii) Assume \( f \in \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) \), meaning \( f \in (H_{\tau,v})^\sim \) with \( V_{\mathfrak{g},\tau} f \in L_{p,v} \). By Lemma 2.6 (ii) the reproducing identity extends to \( (H_{\tau,v})^\sim \), thus \( V_{\mathfrak{g},\tau} f = R_{\mathfrak{g}}(V_{\mathfrak{g},\tau} f) \in R_{\mathfrak{g}}(L_{p,v}) \). With Lemma 2.1 we derive \( V_{\mathfrak{g},\tau} f \in L_{r,v} \), which shows the assumption.

(iii) Since \( L_{p,w} \subset L_{p,v} \) the assertion holds.

Remark 3. Under the additional assumption \( R_{\mathfrak{g}} \in \mathcal{A}_{1,m_v} \), the spaces \( \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) \), which are analyzed in Ref. 12 are well-defined by Schur’s test, see Lemma A.3. Hence, by Lemma 2.8 (i) we have the embeddings \( \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) \subset \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) \) for all \( 1 < \tau \leq 2 \). This is not applicable for the inhomogeneous shearlet coorbit spaces we are looking at in this paper but may be of interest for other spaces.

To identify conditions under which the Coorbit spaces are independent of the frame, we introduce a second Parseval frame for \( \mathcal{H} \) we denote by \( \mathfrak{S} = \{\psi_x\}_{x \in X} \) and introduce the Gramian kernel as

\[ G(\mathfrak{g}, \mathfrak{S})(x,y) := \langle \tilde{\psi}_y, \psi_x \rangle. \]

Then, the following holds true.

Proposition 2.9. Assume that \( \mathfrak{g} = \{\psi_x\}_{x \in X} \) and \( \mathfrak{S} = \{\tilde{\psi}_x\}_{x \in X} \) are two Parseval frames for \( \mathcal{H} \) fulfilling all necessary conditions on the reproducing kernels and the corresponding Gramian kernel fulfills \( G(\mathfrak{g}, \mathfrak{S}) \in \mathcal{A}_{1,m_v} \). Then it holds \( \text{Co}_{\mathfrak{g},\tau}(L_{p,v}) = \text{Co}_{\mathfrak{S},\tau}(L_{p,v}) \).

Proof. By expanding \( V_{\mathfrak{g}} \) with respect to \( \mathfrak{S} \) we obtain

\[ V_{\mathfrak{g}} f(x) = \langle f, \psi_x \rangle = \int_X \langle f, \tilde{\psi}_y \rangle \langle \tilde{\psi}_y, \psi_x \rangle \, d\mu(y) = G(\mathfrak{g}, \mathfrak{S})(V_{\mathfrak{g}} f)(x) \]

and the same holds for the extended voice transform. By our assumption we derive with Schur’s test that \( G(\mathfrak{g}, \mathfrak{S})(L_{p,v}) \subset L_{p,v} \) and it holds

\[ \|f|_{\text{Co}_{\mathfrak{g},\tau}(L_{p,v})}\| \leq \|G(\mathfrak{g}, \mathfrak{S})|_{\mathcal{A}_{1,m_v}}\| \|f|_{\text{Co}_{\mathfrak{S},\tau}(L_{p,v})}\|. \]

The converse is shown analogously and the assertion follows. \( \square \)
3. Shearlet coorbit spaces

In this section we introduce an inhomogeneous version of the shearlet transform and define smoothness spaces associated to this transform. In order to accomplish this we use the generalized coorbit theory outlined in Section 2. Since our approach is based on the homogeneous shearlet transform and the resulting coorbit spaces (as treated in Ref.5-6), we start by giving a short overview of the respective theory. By modifying the homogeneous shearlet transform, we then develop a new transform, given through the action of an (inhomogeneous) frame. For this new transform we then show that all the necessary conditions on the reproducing kernel hold, so that we can introduce the associated coorbit spaces with respect to the (weighted) Lebesgue spaces.

3.1. Homogeneous shearlet transform. To define the shearlet transform, one starts with an admissible function \( \psi \in L_2(\mathbb{R}^d) \), i.e. a function satisfying the condition

\[
c_\psi := \int_{\mathbb{R}^d} \left| \hat{\psi}(\omega) \right|^2 d\omega < \infty.
\]

This condition is necessary for the transform to be square-integrable. The admissible function is then translated, dilated and sheared in order to change its localization, scale and orientation. For a parameter \( a \in \mathbb{R}^* \) let

\[
A_a = \begin{pmatrix} a & 0_{d-1}^T \\ 0_{d-1} & \text{sign}(a)|a|^\frac{1}{2}I_{d-1} \end{pmatrix}
\]

denote a generalized parabolic scaling matrix and for a parameter \( s \in \mathbb{R}^{d-1} \) let

\[
S_s = \begin{pmatrix} 1 & s^T \\ 0_{d-1} & I_{d-1} \end{pmatrix}
\]

denote the so-called shear matrix. It is easy to see that \( |\det S_s| = 1 \) and \( |\det A_a| = |a|^{2-d}. \) Using these matrices one can then define the translated, dilated and sheared version of \( \psi \) through

\[
\psi_{(a,s,t)}(x) = |\det A_a|^{-\frac{1}{2}} \psi(A_a^{-1}S_s^{-1}(x-t)).
\]

In the homogeneous setting, the shearlet transform is then defined through the action of a unitary, irreducible and integrable representation of the full parameter group, the so-called shearlet group \( S = \mathbb{R}^* \times \mathbb{R}^{d-1} \times \mathbb{R}^d \) with the group law

\[
(a,s,t) \circ (a',s',t') = (aa',s + |a|^{1-d}s',t + S_sA_at').
\]

Given the mapping \( \pi : S \to \mathcal{U}(L_2(\mathbb{R}^d)) \) with \( \pi(a,s,t)\psi = \psi_{(a,s,t)} \), which can be shown to be a unitary group representation, the shearlet transform is defined as

\[
\mathcal{S}_{H} : L_2(\mathbb{R}^d) \to L_2(S), \quad f \mapsto \mathcal{S}_{H} f
\]

with

\[
\mathcal{S}_{H} f : S \to \mathbb{C}, \quad (a,s,t) \mapsto \langle f, \pi(a,s,t)\psi \rangle_{L_2(\mathbb{R}^d)}.
\]

Based on this notion of the shearlet transform Dahlke et al. introduced homogeneous shearlet coorbit spaces with respect to the Lebesgue spaces by using the coorbit space theory developed by Feichtinger and Gröchenig in Ref.9-11

3.2. Inhomogeneous shearlet frame. Similar to the wavelet approach in Ref.20 we now introduce an inhomogeneous shearlet transform by restricting the dilation parameter to a closed subset of the full parameter group, thereby only covering the higher-frequency content of a signal. To analyze the polynomial and lower-frequency part a second function is introduced to construct an inhomogeneous frame of functions in \( L_2(\mathbb{R}^d) \) as the set of building blocks for our new transform. Therefore we choose the set

\[
X := \left( \{\infty\} \times \mathbb{R}^{d-1} \times \mathbb{R}^d \right) \cup \left( [-1,1]^* \times \mathbb{R}^{d-1} \times \mathbb{R}^d \right)
\]
as the new parameter space with “∞” representing an isolated point in \( \mathbb{R} \) and \([-1, 1]^* : = \mathbb{R} \setminus \{0\} \).

The right-hand side of the union is the aforementioned subspace of the shearlet group \( \mathcal{S} \), which is closed under the group action. Obviously, this definition leads to a locally compact Hausdorff space. In the following definition we introduce a measure on the parameter space so that \( X \), together with its Borel \( \sigma \)-algebra, becomes a measure space.

**Definition 3.1.** On the space \( X \) a measure \( \mu \) is defined by

\[
\int_X F(x) \, d\mu(x) := \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} F(\infty, s, t) \, ds \, dt + \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} F(a, s, t) \frac{da}{|a|^{d-1}} \, ds \, dt
\]

with \( F \) being a complex-valued function on \( X \) which is measurable with respect to the Borel \( \sigma \)-algebra.

The first summand in the definition above is composed of the point measure on \( \mathbb{R} \) and the Lebesgue measure on \( \mathbb{R}^{d-1} \times \mathbb{R}^d \), while the second summand is the restriction of the (left) Haar measure on the shearlet group to the subset \([-1, 1]^* \times \mathbb{R}^{d-1} \times \mathbb{R}^d \). Therefore it is obvious that \( \mu \) given by \(\text{(3.2)}\) is a positive Radon measure.

Choosing the measure space \( (X, \mathcal{B}(X), \mu) \) as the underlying index space, we can introduce a continuous shearlet frame.

**Definition 3.2.** Let \( a \in \mathbb{R}^*, s \in \mathbb{R}^{d-1} \) and \( t \in \mathbb{R}^d \). Then

(i) \( L_t : L_2(\mathbb{R}^d) \to L_2(\mathbb{R}^d) \) with \( L_t \psi := \psi(\cdot - t) \) is called the (left) translation operator,

(ii) \( D_s : L_2(\mathbb{R}^d) \to L_2(\mathbb{R}^d) \) with \( D_s \psi := \psi(S_s^{-1}) \) is called the shearing operator, and

(iii) \( D_a : L_2(\mathbb{R}^d) \to L_2(\mathbb{R}^d) \) with \( D_a \psi := |\det A_a|^{-\frac{1}{2}} \psi(A_a^{-1} \cdot) \) is called the (anisotropic) dilation operator.

Using the above defined operators, we can define an inhomogeneous shearlet frame.

**Definition 3.3.** Let \( \Phi, \Psi \in L_2(\mathbb{R}^d) \) with \( \Psi \) being an admissible shearlet. Then we define \( \mathfrak{S} := \{ \psi_x \}_{x \in X} \) with

\[
\psi_{(\infty,s,t)} := L_t D_s \Phi = \Phi(S_s^{-1}(\cdot - t)) \quad \text{and} \quad \psi_{(a,s,t)} := L_t D_s D_a \Psi = |\det A_a|^{-\frac{1}{2}} \Psi(A_a^{-1} S_s^{-1}(\cdot - t)).
\]

The main theorem of this section is that \( \mathfrak{S} \), given by \(\text{(3.3)}\) and \(\text{(3.4)}\), constitutes a continuous Parseval frame under the conditions given in Theorem 3.3 below so that the transform based on \( \mathfrak{S} \) is well defined. To this end we need two technical results that can also be found in Ref.5

**Lemma 3.1.** For all \( (\alpha, s, t) \in X \) with \( \alpha = a \) or \( \alpha = \infty \) and \( f, \psi \in L_2(\mathbb{R}^d) \) the identity

\[
(f, \psi_{(\alpha, s, t)})_{L_2(\mathbb{R}^d)} = (f \ast \psi_{(\alpha, s, 0)})(t)
\]

holds true with \( \psi^* := \overline{\psi(-\cdot)} \).

**Lemma 3.2.** Let \( \phi \in L_2(\mathbb{R}^d) \), \( a \in \mathbb{R}^* \), \( s \in \mathbb{R}^{d-1} \) and \( \xi \in \mathbb{R}^d \). Then the following equations hold:

(i) \( \mathcal{F}(D_s \phi)(\xi) = \hat{\phi}(S_s^T \xi) \);

(ii) \( \mathcal{F}(D_s D_a \phi)(\xi) = |\det A_a|^{\frac{1}{2}} \hat{\phi}(A_a S_s^T \xi) \).

We now state the main theorem of this section, which identifies conditions on \( \Phi \) and \( \Psi \) for \( \mathfrak{S} \) being a continuous Parseval frame.

**Theorem 3.3.** Let \( \Psi \in L_1(\mathbb{R}^d) \cap L_2(\mathbb{R}^d) \) be an admissible shearlet and let \( \Phi \in L_1(\mathbb{R}^d) \cap L_2(\mathbb{R}^d) \) be such that

\[
\int_{\mathbb{R}^{d-1}} \frac{|\hat{\Phi}(\xi, \sigma)|^2}{|\xi|^d} \, d\sigma + \int_{|\xi_1| > 1} \int_{|\xi|^d} \frac{|\hat{\Phi}(\xi_1, \xi)|^2}{|\xi|^d} \, d\xi_1 \, d\xi = 1 \quad \text{for almost every } y \in \mathbb{R}.
\]
Then the inhomogeneous shearlet frame $F$ is a continuous Parseval frame of $L_2(\mathbb{R}^d)$, i.e.,

$$\int_X |\langle f, \psi_x \rangle|^2 \, d\mu(x) = \|f\|_{L_2(\mathbb{R}^d)}^2, \quad f \in L_2(\mathbb{R}^d).$$

**Proof.** Applying (3.2), Fubini's and Plancherel’s theorem we obtain

$$\int_X |\langle f, \psi_x \rangle|^2 \, d\mu(x) = \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} |\langle f, \psi_{(\infty,s,t)} \rangle|^2 \, ds \, dt$$

$$+ \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} |\langle f, \psi_{(a,s,t)} \rangle|^2 \, da \frac{1}{|a|^{d+1}} \, ds \, dt$$

$$= \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} |\langle f, \psi_{(\infty,s,t)} \rangle|^2 \, dt \, ds$$

$$+ \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} \int_{\mathbb{R}^d} |\langle f, \psi_{(a,s,t)} \rangle|^2 \, dt \, da \frac{1}{|a|^{d+1}} \, ds$$

$$= \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} \|\mathcal{F}((f, \psi_{(\infty,s,t)}))|L_2(\mathbb{R}^d)\|^2 \, ds$$

$$+ \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} \|\mathcal{F}((f, \psi_{(a,s,t)}))|L_2(\mathbb{R}^d)\|^2 \frac{1}{|a|^{d+1}} \, ds$$

$$= \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} |\mathcal{F}((f, \psi_{(\infty,s,t)}))(t)|^2 \, dt \, ds$$

$$+ \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} |\mathcal{F}((f, \psi_{(a,s,t)}))(t)|^2 \, dt \frac{1}{|a|^{d+1}} \, ds.$$
\[
= \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} |\hat{f}(t)|^2 |\mathcal{F}(\psi^*_{(\infty,s,0)})(t)|^2 \, dt \, ds \\
+ \int_{\mathbb{R}^{d-1}} \int_{\mathbb{R}^d} |\hat{f}(t)|^2 |\mathcal{F}(\psi^*_{(a,s,0)})(t)|^2 \, dt \, \frac{da}{|a|^{d+1}} \, ds \\
= \int_{\mathbb{R}^d} |\hat{f}(t)|^2 \left( \int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi^*_{(\infty,s,0)})(t)|^2 \, ds + \int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi_{(a,s,0)})(t)|^2 \, \frac{da}{|a|^{d+1}} \right) \, dt.
\]

Thus, if we can prove that

\[(3.6) \quad \int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi_{(\infty,s,0)})(t)|^2 \, ds + \int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi_{(a,s,0)})(t)|^2 \, \frac{da}{|a|^{d+1}} \, ds = 1
\]

for almost every \( t \in \mathbb{R}^d \), the assertion follows, since then

\[
\int_X |(f, \phi_x)|^2 \, d\mu(x) = \int_{\mathbb{R}^d} |\hat{f}(t)|^2 \, dt = ||\hat{f}||_{L^2(\mathbb{R}^d)}^2 = ||f||_{L^2(\mathbb{R}^d)}^2.
\]

Hence, it remains to show (3.6). Assuming that \( t \neq 0 \) we use Lemma 3.2 to obtain

\[
\int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi_{(\infty,s,0)})(t)|^2 \, ds + \int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi_{(a,s,0)})(t)|^2 \, \frac{da}{|a|^{d+1}} \, ds \\
= \int_{\mathbb{R}^{d-1}} |\mathcal{F}(D_{S_0} \Phi)(t)|^2 \, ds + \int_{\mathbb{R}^{d-1}} |\mathcal{F}(D_{S_0} D_{A_n} \Psi)(t)|^2 \, \frac{da}{|a|^{d+1}} \, ds \\
= \int_{\mathbb{R}^{d-1}} |\hat{\Phi}(S_t^T t)|^2 \, ds + \int_{\mathbb{R}^{d-1}} |\det A_n| |\hat{\Psi}(A_n S_t^T t)|^2 \, \frac{da}{|a|^{d+1}} \, ds \\
= \int_{\mathbb{R}^{d-1}} |\hat{\Phi}(t_1, \vec{t} + t_1 s)|^2 \, ds + \int_{\mathbb{R}^{d-1}} |\det A_1| |\hat{\Psi}(at_1, \text{sign}(a)|a|^{\frac{1}{2}}(\vec{t} + t_1 s))|^2 \, \frac{da}{|a|^{d+1}} \, ds,
\]

with \( t = (t_1, \vec{t})^T, \vec{t} \in \mathbb{R}^{d-1} \). Substituting \( \sigma := \vec{t} + t_1 s \) and \( \xi = (\xi_1, \vec{\xi}) := (at_1, \text{sign}(a)|a|^{\frac{1}{2}}(\vec{t} + t_1 s)) \), we end up with

\[
\int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi_{(\infty,s,0)})(t)|^2 \, ds + \int_{\mathbb{R}^{d-1}} |\mathcal{F}(\psi_{(a,s,0)})(t)|^2 \, \frac{da}{|a|^{d+1}} \, ds \\
= \int_{\mathbb{R}^{d-1}} |t_1|^{-(d-1)} |\hat{\Phi}(t_1, \sigma)|^2 \, d\sigma + \int_{\mathbb{R}^{d-1}} |\xi_1|^{-d} |\hat{\Psi}(\xi_1, \vec{\xi})|^2 \, d\xi_1 \, d\vec{\xi} \\
= \int_{\mathbb{R}^{d-1}} |\hat{\Phi}(t_1, \sigma)|^2 \, \left( \frac{|t_1|}{|t_1|^{d-1}} \right) \, d\sigma + \int_{\mathbb{R}^{d-1}} \int_{|\xi_1|} |\hat{\Psi}(\xi_1, \vec{\xi})|^2 \, d\xi_1 \, d\vec{\xi},
\]

and (3.6) follows from assumption (3.5). \( \square \)
Remark 4. The proof of Theorem 3.3 can also be stated in a similar manner for the case of a tight frame with arbitrary frame constant \( A < \infty \). The only difference is that \( \Phi \) and \( \Psi \) have to satisfy
\[
\int_{\mathbb{R}^d} \frac{|\hat{\Phi}(y,\sigma)|^2}{|y|^{d-1}} \, d\sigma + \int_{\mathbb{R}^{d-1}} \int_{|y|} |\hat{\Psi}(\xi_1,\xi)|^2 \frac{|\xi_1|}{|\xi_1|^d} \, d\xi_1 \, d\xi = A \quad \text{for almost every } y \in \mathbb{R}
\]
instead of (3.5).

Remark 5. For a given shearlet \( \Psi \) it is still necessary to show that one can satisfy condition (3.5) for a function \( \Phi \in L_1(\mathbb{R}^d) \cap L_2(\mathbb{R}^d) \). To this end we restrict ourselves to odd dimensions and we define \( \hat{\Phi} : \mathbb{R}^d \to \mathbb{C} \) by
\[
\hat{\Phi}(\xi) := \xi_1 \left( \int_{R \setminus [-1,1]} \frac{|\hat{\Psi}(\omega_1,\xi)|^2}{|\omega_1|^d} \, d\omega_1 \right)^{1/2}.
\]
It is straightforward to see that \( \Phi \) fulfills (3.5). Moreover, \( \Phi \in L_2(\mathbb{R}^d) \) is immediate and \( \Phi \in L_1(\mathbb{R}^d) \) can be shown if \( \hat{\Phi} \in C_0(\mathbb{R}^d) \), see Example 3.1.

Because of Theorem 3.3, we can now state the definition of the shearlet transform based on \( \mathcal{F} \).

Definition 3.4. Let \( \Phi, \Psi \in L_2(\mathbb{R}^d) \) satisfy the assumptions of Theorem 3.3 and let \( \mathcal{F} = \{ \psi_x \}_{x \in X} \) be given by Definition 3.3. Then the shearlet transform based on \( \mathcal{F} \) is defined as
\[
S\mathcal{H}_\mathcal{F} : L_2(\mathbb{R}^d) \to L_2(X,\mu), \quad f \mapsto S\mathcal{H}_\mathcal{F} f
\]
with
\[
S\mathcal{H}_\mathcal{F} f : X \to \mathbb{C}, \quad x \mapsto \{ f, \psi_x \}.
\]

3.3. Conditions on the reproducing kernel.

The main goal of this section is to lay the foundations for the definition of the coorbit spaces \( C_{0,K}(L_{p,v}(X,\mu)) \), \( 1 \leq p < \infty \), \( p < q' < \infty \), with \( v \) being a weight function on \( X \), associated to the inhomogeneous shearlet transform introduced in the previous section. To prove that these spaces are well-defined Banach spaces, we need to show that the conditions on \( \mathcal{F} \), as stated in Section 2, are satisfied. By Remark 2 it suffices to show that \( R_\mathcal{F} \in \mathcal{A}_{q,m_v} \) for all \( q > 1 \). To this end we need the following auxiliary results.

Lemma 3.4. Let \( a, a' \in [-1,1]^* \), \( s, s' \in \mathbb{R}^{d-1} \), \( t, t' \in \mathbb{R}^d \) and \( \varphi_{(a,s,t)} := |\det A_a|^{-\frac{d}{2}} \Phi(A_a^{-1}S_t^{-1}(-t)) \).

It follows that
\[
|\langle \psi_{(\infty,s,t)}, \psi_{(\infty,s',t')} \rangle| = |S\mathcal{H}\Phi(\infty, s - s', S_{s'}^{-1}(t - t'))|,
\]
\[
|\langle \psi_{(\infty,s,t)}, \psi_{(a',s',t')} \rangle| = |\langle \Psi_{(a^{-1},|a'|\frac{1}{2}(s-s'),A_{a'}^{-1}S_{s'}^{-1}(t-t'))} \rangle|,
\]
\[
|\langle \psi_{(a,s,t)}, \psi_{(a',s',t')} \rangle| = |S\mathcal{H}\Phi(a, s - s', S_{s'}^{-1}(t - t'))|,
\]
\[
|\langle \psi_{(a,s,t)}, \psi_{(a',s',t')} \rangle| = |S\mathcal{H}\Psi(a, s - s', A_{a'}^{-1}S_{s'}^{-1}(t - t'))|,
\]

Proof. We only state the proof for (3.10) in detail, (3.7)–(3.9) can be proven analogously. By the definition of \( \psi_{(a,s,t)} \) we obtain
\[
\langle \psi_{(a,s,t)}, \psi_{(a',s',t')} \rangle = \int_{\mathbb{R}^d} \psi_{(a,s,t)}(x) \overline{\psi_{(a',s',t')}(x)} \, dx
\]
\[
= \int_{\mathbb{R}^d} |\det A_a|^{-\frac{d}{2}} \Phi(A_a^{-1}S_t^{-1}(x - t)) |\det A_{a'}|^{-\frac{d}{2}} \Phi(A_{a'}^{-1}S_{s'}^{-1}(x - t')) \, dx,
\]

13
which, by means of the substitution \( y = A_{\alpha^{-1}}^{-1}S_{\alpha}^{-1}(x - t') \), leads to

\[
\langle \psi_{(a, s, t)}, \psi_{(a', s', t''')} \rangle = \int_{\mathbb{R}^d} \det A_{a''^{-1}}^{-1} [\Phi_y (A_{\alpha^{-1}}^{-1}S_{\alpha}^{-1}(S_{\alpha} A_{\alpha} y + t' - t)) \overline{\Psi}(y)] dy
\]

\[
= \int_{\mathbb{R}^d} \det A_{a''^{-1}}^{-1} [\Phi_y (A_{\alpha^{-1}}^{-1}S_{\alpha}^{-1}(A_{\alpha} y - (A_{\alpha}^{-1}S_{\alpha}^{-1}(t - t')))) \overline{\Psi}(y)] dy
\]

\[
= \int_{\mathbb{R}^d} \det A_{a''^{-1}}^{-1} [\Phi_y (A_{\alpha^{-1}}^{-1}S_{\alpha}^{-1}(a')^{-1}(s - s')) (y - (A_{\alpha}^{-1}S_{\alpha}^{-1}(t - t')))) \overline{\Psi}(y)] dy
\]

\[
= \langle \psi_{(a''^{-1}, [a']^{-1}(s - s'), A_{\alpha}^{-1}S_{\alpha}^{-1}(t - t'))}, \Psi \rangle.
\]

This yields

\[
|\langle \psi_{(a, s, t)}, \psi_{(a', s', t''')} \rangle| = |\langle \psi_{(a''^{-1}, [a']^{-1}(s - s'), A_{\alpha}^{-1}S_{\alpha}^{-1}(t - t'))}, \Psi \rangle|
\]

\[
= |\langle \Phi, \psi_{(a''^{-1}, [a']^{-1}(s - s'), A_{\alpha}^{-1}S_{\alpha}^{-1}(t - t'))} \rangle|\]

\[
= |(S \mathcal{H} \Psi)(a''^{-1}, [a']^{-1}(s - s'), A_{\alpha}^{-1}S_{\alpha}^{-1}(t - t'))|.
\]

\[
\square
\]

Using the auxiliary result above, we can prove the following lemma concerning the \( A_{q,m^{-}} \)-Norm of \( R_{\tilde{g}} \).

**Lemma 3.5.** Let \( R_{\tilde{g}} \) be the kernel function associated to the inhomogeneous shearlet frame as defined by (3.11). Then for every \( q \) the following identity holds:

\[
\text{ess sup}_{(a, \sigma, \tau) \in \mathbb{R}^{d-1} \times \mathbb{R}^d} \int_X |R_{\tilde{g}}((a, \sigma, \tau), (a, s, t))|^q m_v((\sigma, \tau), (a, s, t))^q d\mu(a, s, t)
\]

\[
= \max \left\{ \text{ess sup}_{(a, \sigma, \tau) \in \mathbb{R}^{d-1} \times \mathbb{R}^d} \int \int \left( \max \left\{ \frac{v(\infty, \sigma, \tau)}{v(\infty, \sigma_1, \tau_1)}, \frac{v(\sigma_1, \tau_1)}{v(\sigma, \tau)} \right\} \right|^q |\langle \Phi, \psi_{(\infty, \sigma', \tau')} \rangle|\right\}^q
\]

\[
+ \int_{-\infty}^1 \max \left\{ \frac{v(\infty, \sigma, \tau)}{v(\infty, \sigma_2, \tau_2)}, \frac{v(\sigma_2, \tau_2)}{v(\infty, \sigma, \tau)} \right\} \left| |\langle \Phi, \psi_{(\infty, \sigma', \tau')} \rangle| \frac{da}{|a|^{d+1}} \right| ds' dt',
\]

(3.11)

\[
= \text{ess sup}_{(a, \sigma, \tau) \in [-1,1] \times \mathbb{R}^{d-1} \times \mathbb{R}^d} \int \int \left( \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\infty, \sigma_1, \tau_1)}, \frac{v(\infty, \sigma_1, \tau_1)}{v(\sigma, \tau)} \right\} \right|^q |\langle \Phi, \psi_{(\alpha, \sigma', \tau')} \rangle|\right\}^q
\]

\[
+ \int_{-|\alpha|^{-1}}^{1} \max \left\{ \frac{v(\alpha, \sigma_1, \tau_1)}{v(\alpha, \sigma_3, \tau_3)}, \frac{v(\sigma_3, \tau_3)}{v(\alpha, \sigma, \tau)} \right\} \left| |\langle \Phi, \psi_{(\alpha, \sigma', \tau')} \rangle| \right| \frac{da'}{|a'|^{d+1}} ds' dt'
\]

with \( \sigma_1 = \sigma - s', \tau_1 = \tau - S_{\sigma_1} t', \sigma_2 = \sigma + s', \tau_2 = \tau + S_{\sigma} t', \alpha = \alpha a', \sigma_3 = \sigma + |\alpha|^{-\frac{d}{2}} s', \tau_3 = \tau + S_{\sigma} A_{\alpha} t' \).
Proof. Let \( (\alpha, \sigma, \tau) \in X \) with \( \alpha \in \{\infty\} \cup [-1, 1]^* \). Using (3.7) and (3.9) we obtain
\[
\int \int_{\mathbb{R}^d \times \mathbb{R}^d} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \psi(\infty, s, t), \psi(\alpha, \sigma, \tau) \rangle \right|^q ds \, dt \\
= \int \int_{\mathbb{R}^d \times \mathbb{R}^d} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \Phi, \psi(\alpha, \sigma, \tau) \rangle \right|^q ds \, dt.
\]
Substituting \( s' = \sigma - s \) and \( t' = S_{\sigma - s}^{-1}(\tau - t) \) then leads to
\[
\int \int_{\mathbb{R}^d \times \mathbb{R}^d} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \psi(\infty, s, t), \psi(\alpha, \sigma, \tau) \rangle \right|^q ds \, dt \\
= \int \int_{\mathbb{R}^d \times \mathbb{R}^d} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \Phi, \psi(\alpha, \sigma, \tau) \rangle \right|^q ds' \, dt'.
\]
Analogously we see that
\[
\int \int_{\mathbb{R}^d \times \mathbb{R}^d} \int_{1}^{\infty} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle \right|^q \frac{da}{|a|^{d+1}} \, ds \, dt \\
= \int \int_{\mathbb{R}^d \times \mathbb{R}^d} \int_{1}^{\infty} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \Phi, \psi(\alpha, \sigma, \tau) \rangle \right|^q \frac{da}{|a|^{d+1}} \, ds' \, dt',
\]
for \( \sigma \in \mathbb{R}^d \) and \( \tau \in \mathbb{R}^d \). Now let \( \alpha \in [-1, 1]^* \). Then (3.10) yields
\[
\int \int_{\mathbb{R}^d \times \mathbb{R}^d} \int_{1}^{\infty} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle \right|^q \frac{da}{|a|^{d+1}} \, ds \, dt \\
= \int \int_{\mathbb{R}^d \times \mathbb{R}^d} \int_{1}^{\infty} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \Phi, \psi(\alpha, \sigma, \tau) \rangle \right|^q \frac{da}{|a|^{d+1}} \, ds' \, dt',
\]
which—by substituting \( a' := a |a|^{-1} \)—leads to
\[
\int \int_{\mathbb{R}^d \times \mathbb{R}^d} \int_{1}^{\infty} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle \right|^q \frac{da}{|a|^{d+1}} \, ds \, dt \\
= \int \int_{\mathbb{R}^d \times \mathbb{R}^d} \int_{|a|^{-1}}^{1} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q \left| \langle \Phi, \psi(\alpha, \sigma, \tau) \rangle \right|^q \frac{da}{|a|^{d+1}} \, ds' \, dt'.
\]
Again, substituting with $s' := |\alpha|^\frac{1}{d} - 1 (s - \sigma)$ and $t' := A^{-1}_\alpha S^{-1}_\sigma (t - \tau)$, we get

\[
\int \int \int_{R^d R^{d-1} - 1} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, s, t)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle|^q \frac{da}{|a|^{d+1}} ds \, dt
\]

\[
= \int \int \int_{R^d R^{d-1} - |\alpha|^{-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle|^q \frac{da}{|a|^{d+1}} ds \, dt
\]

(3.14)

\[
= \int \int \int_{R^d R^{d-1} - |\alpha|^{-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle|^q \frac{da}{|a|^{d+1}} ds \, dt.
\]

Using (3.12), (3.13), and (3.14), we now have

\[
\text{ess sup}_{(\alpha, \sigma, \tau) \in X} \int |R(\alpha, \sigma, \tau), (a, s, t)\rangle |^q m_v((\alpha, \sigma, \tau), (a, s, t)) |^q \, d\mu(a, s, t)
\]

\[
= \text{ess sup}_{(\alpha, \sigma, \tau) \in X} \int \int \int_{R^d R^{d-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, s, t)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle|^q \frac{da}{|a|^{d+1}} ds \, dt
\]

\[
+ \int \int \int_{R^d R^{d-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, s, t)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle|^q \frac{da}{|a|^{d+1}} ds \, dt
\]

\[
= \max \left\{ \text{ess sup}_{(\alpha, \sigma, \tau) \in [-1, 1]^{d-1} \times R^d} \int \int \int_{R^d R^{d-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, s, t)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle|^q \frac{da}{|a|^{d+1}} ds \, dt \right\}
\]

\[
+ \int \int \int_{R^d R^{d-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, s, t)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \psi(\alpha, s, t), \psi(\alpha, \sigma, \tau) \rangle|^q \frac{da}{|a|^{d+1}} ds \, dt
\]

\[
= \max \left\{ \text{ess sup}_{(\alpha, \sigma, \tau) \in [-1, 1]^{d-1} \times R^d} \int \int \int_{R^d R^{d-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, s, t)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \Phi, \psi(\alpha, s', t') \rangle|^q \frac{da}{|a|^{d+1}} ds' \, dt' \right\}
\]

\[
+ \int \int \int_{R^d R^{d-1}} \max \left\{ \frac{v(\alpha, \sigma, \tau)}{v(\alpha, \sigma, \tau)}, \frac{v(\alpha, s, t)}{v(\alpha, \sigma, \tau)} \right\}^q |\langle \Phi, \psi(\alpha, s', t') \rangle|^q \frac{da}{|a|^{d+1}} ds' \, dt'.
\]
We use Lemma 3.5 to prove \( R_S \in A_q(m) \) for certain functions \( \Phi \) and \( \Psi \). Since it is not possible to construct functions \( \Phi, \Psi \in L_2 \) with compact support in the spatial domain satisfying the conditions in Remark 5, in the following we assume \( \Psi \) to be a bandlimited Schwartz function, in particular
\[
\text{supp } \Psi \subseteq \left( [-a_1, -a_0] \cup [a_0, a_1] \right) \times Q_b
\]
with \( 0 < a_0 < a_1 \) and \( Q_b := \times_{i=1}^{d-1} [-b_i, b_i] \) for \( b \in \mathbb{R}^{d-1} \). The function \( \Phi \) is chosen in the same way as in Remark 5. It follows that
\[
\text{supp } \hat{\Phi} \subseteq [-a_1, a_1] \times Q_b.
\]
As weight functions on \( X \) we consider
\[
(3.15) \quad v_r(\alpha, s, t) = \begin{cases} 1, & \alpha = \infty, \\ |\alpha|^{-r}, & \alpha \in [-1, 1]^s, \end{cases}
\]
with \( r \in \mathbb{R}_{>0} \), which satisfy all necessary conditions. Through simple calculations one can verify the following properties of the moderate weight \( m_{v_r} \) associated with \( v_r \) for \( a, a' \in [-1, 1]^s \):
\[
(3.16) \quad m_{v_r}(\infty, \infty) = 1,
\]
\[
(3.17) \quad m_{v_r}(\alpha, \infty) = m_{v_r}(\infty, \alpha) = |\alpha|^{-r},
\]
\[
(3.18) \quad m_{v_r}(a, a') = \max \left\{ \frac{|a|}{|a'|}, \frac{|a'|}{|a|} \right\}^{-r}.
\]
The following technical lemma concerns support properties of \( \Phi \) and \( \Psi \) in the frequency domain, similar to Lemma 3.1, Ref.\(^6\)

**Lemma 3.6.** Let \( 0 < a_0 < a_1 \) and \( b \in \mathbb{R}^{d-1} \). Then with \( \Psi \) and \( \Phi \) defined as above and for \( a \in \mathbb{R}^s \) and \( s \in \mathbb{R}^{d-1} \) we have
(i) \( \hat{\Psi}(A_s S_s^s) \neq 0 \) implies \( a \in [-\frac{2a_0}{a_1}, -\frac{a_0}{a_1}] \cup \left[ \frac{a_0}{a_1}, \frac{2a_0}{a_1} \right] \) and \( s \in Q_{d_1} \) with \( d_1 := (a_0^{-1} + a_0^{-\frac{1}{1+\frac{1}{2}}} \frac{1}{2})b \).
(ii) Assume \( |a| \leq 1 \) then \( \hat{\Phi}(A_s S_s^s) \neq 0 \) implies \( a \in [-1, -\frac{2a_0}{a_1}] \cup \left[ \frac{2a_0}{a_1}, 1 \right] \) and \( s \in Q_{d_2} \) with \( d_2 := (a_0^{-1} + a_0^{-\frac{1}{1+\frac{1}{2}}} \frac{1}{2})b \).
(iii) \( \text{supp } \hat{\Phi}(S_s^s) \subseteq \Omega_s := \{ x \in \mathbb{R}^d : |x_i| \leq a_i, \text{max}\{-b_i, -b_i - s_{i-1}x_1\} \leq x_i \leq \min\{b_i, b_i - s_{i-1}x_1\}, i = 2, \ldots d \} \).

**Proof.** The proof of (i) can be found in Lemma 3.1, Ref.\(^6\). To prove (ii) we assume there exists a \( \xi \in \text{supp } \hat{\Phi} \cap \text{supp } \hat{\Psi}(A_s S_s^s) \) which means that \( \xi \in \text{supp } \hat{\Phi} \) and \( A_s S_s^s \xi \in \text{supp } \hat{\Psi} \). This leads to
\[
(3.19) \quad |\xi_1| \leq a_1,
\]
\[
(3.20) \quad -b_i \leq \xi_{i+1} \leq b_i,
\]
\[
(3.21) \quad a_0 \leq |a||\xi_1| \leq a_1,
\]
\[
(3.22) \quad -b_i |a|^{-\frac{1}{2}} - \xi_1 s_i \leq \xi_{i+1} \leq b_i |a|^{-\frac{1}{2}} - \xi_1 s_i,
\]
for \( i = 1, \ldots, d - 1 \). By (3.19) and (3.21) it follows that \( |a| \geq \frac{a_0}{a_1} \) which means \( a \in [-1, -\frac{2a_0}{a_1}] \cup \left[ \frac{2a_0}{a_1}, 1 \right] \). Using (3.21) and \( |a| \leq 1 \), it follows that \( a_0 \leq |a||\xi_1| \leq |\xi_1| \). Also, with (3.22) and (3.20) we obtain
\[
-b_i |a|^{-\frac{1}{2}} - b_i \leq \xi_1 s_i \leq b_i |a|^{-\frac{1}{2}} + b_i,
\]
which leads to
\[ |s_i| \leq |\xi_1|^{-1} (b_i |a|^{-\frac{4}{3}} + b_i) \leq a_0^{-1} b_i \left( \frac{a_0}{a_1} \right)^{-\frac{4}{3}} + a_0^{-1} b_i \]
for \( i = 1, \ldots, d - 1 \) which proves (ii). To prove (iii) we assume there exists \( \xi \in \text{supp} \hat{\Phi} \cap \text{supp} \hat{\Phi}(S_z^T \cdot) \) which means that \( \xi \in \text{supp} \hat{\Phi} \) and \( S_z^T \xi \in \text{supp} \hat{\Phi} \). This leads to
\begin{align}
|\xi_1| &\leq a_1, \quad (3.23) \\
-b_i &\leq \xi_{i+1} \leq b_i, \quad (3.24) \\
-b_i &\leq \xi_1 s_i + \xi_{i+1} \leq b_i \quad (3.25)
\end{align}
for all \( i = 1, \ldots, d - 1 \), which means \( \xi \in \Omega_s \).}

The following two auxiliary Lemmas are of technical nature only and the proof of Lemma 3.7 is based on a draft by Steidl, Dahlke, Häuser and Teschke.

**Lemma 3.7.** For all \( y, z \in \mathbb{R}, \lambda, \lambda' > 0 \) and \( k > 1 \) the following integral estimation holds true
\[
\int_{\mathbb{R}} (1 + \lambda |x - y|)^{-k} (1 + \lambda' |x - z|)^{-k} \, dx \lesssim \max\{\lambda, \lambda'\}^{-1} (1 + \min\{\lambda, \lambda'\} |y - z|)^{-k}.
\]

**Proof.** Let \( y, z \in \mathbb{R} \) be arbitrary and assume without loss of generality that \( \lambda \leq \lambda' \). Assume further that \( |y - z| \leq \lambda^{-1} \), then
\[
(1 + \lambda |x - y|)^{-k} \leq 1 \leq 2^k (1 + \lambda |y - z|)^{-k}
\]
and thus
\[
\int_{\mathbb{R}} (1 + \lambda |x - y|)^{-k} (1 + \lambda' |x - z|)^{-k} \, dx \lesssim \int_{\mathbb{R}} (1 + \lambda |y - z|)^{-k} \, dx \\
= (1 + \lambda' |y - z|)^{-k} \frac{1}{\lambda'} \int_{\mathbb{R}} (1 + |x|)^{-k} \, dx \\
\lesssim \frac{1}{\lambda'} (1 + \lambda |y - z|)^{-k}.
\]
On the other hand if \( |y - z| > \lambda^{-1} \) let \( H_y \) and \( H_z \) be the two half-axes containing the points \( y \) and \( z \) respectively, such that \( H_y \cap H_z = \left\{ \frac{y+z}{2} \right\} \). Then, for every \( x \in H_z \) it holds \( |x - y| \geq \frac{1}{2} |y - z| \) and thus
\[
\int_{H_z} (1 + \lambda |x - y|)^{-k} (1 + \lambda' |x - z|)^{-k} \, dx \lesssim \int_{H_z} (1 + \lambda |y - z|)^{-k} \, dx \\
\lesssim (1 + \lambda |y - z|)^{-k} \frac{1}{\lambda'} \int_{\mathbb{R}} (1 + |x|)^{-k} \, dx \\
\lesssim \frac{1}{\lambda'} (1 + \lambda |y - z|)^{-k}.
\]
Similarly for every \( x \in H_y \) it holds \( |x - z| \geq \frac{1}{2} |y - z| \) and since \( |y - z| > \lambda^{-1} \) we first deduce
\[
(1 + \lambda' |x - z|)^{-k} \leq \left( \frac{\lambda'}{2} |y - z| \right)^{-k} \lesssim \left( \frac{\lambda'}{\lambda} \right)^k (\lambda |y - z|)^{-k} \\
\lesssim \left( \frac{\lambda}{\lambda'} \right)^k (1 + \lambda |y - z|)^{-k} \lesssim \frac{\lambda}{\lambda'} (1 + \lambda |y - z|)^{-k}
\]
\[ 18 \]
and hence we derive the estimate
\[ \int_{\mathbb{R}} (1 + \lambda |x - y|)^{-k} (1 + \lambda |x - z|)^{-k} \, dx \leq \frac{\lambda}{\lambda'} (1 + \lambda |y - z|)^{-k} \int_{\mathbb{R}} (1 + \lambda |x - y|)^{-k} \, dx \]

\[ \leq \frac{1}{\lambda'} (1 + \lambda |y - z|)^{-k} \int_{\mathbb{R}} (1 + |x|)^{-k} \, dx \]

(3.28)

Combining (3.27) and (3.28) thus yields
\[ \int_{\mathbb{R}} (1 + |x - y|)^{-k} (1 + \lambda |x - z|)^{-k} \, dx \]

\[ = \left( \int_{\mathbb{R}} + \int_{\mathbb{R}} \right) (1 + |x - y|)^{-k} (1 + \lambda |x - z|)^{-k} \, dx \lesssim \frac{1}{\lambda'} (1 + \lambda |y - z|)^{-k} \]

and together with (3.26) this completes the proof. \(\square\)

**Lemma 3.8.** For all \(y, z \in \mathbb{R}^*, \lambda \neq 0\) and \(k > 1\) we have
\[ \int_{\mathbb{R}} (1 + |x|)^{-k} (1 + |x - y|)^{-k} (1 + |\lambda x - z|)^{-k} \, dx \]

\[ \lesssim (1 + |y|)^{-k} \max\{1, |\lambda|\}^{-1} \left[ (1 + \min\{1, |\lambda|\} |y - \frac{z}{\lambda}|)^{-k} + (1 + \min\{1, |\lambda|\} |\frac{z}{\lambda}|)^{-k} \right]. \]

**Proof.** We use the ideas of the proof of Lemma 11.1.1, Ref.13 as well as Lemma 3.7 and define the set \(N_y := \{x \in \mathbb{R} : |x - y| \leq \frac{|y|}{2}\}\). For all \(x \in N_y\) it follows that \(|x| \geq \frac{|y|}{2}\) and thus
\[ (1 + |x|)^{-k} \leq \left( 1 + \frac{|y|}{2} \right)^{-k} \leq 2^k (1 + |y|)^{-k}. \]

On the other hand if \(x \in N_y^c\) one has \((1 + |x - y|)^{-k} \leq (1 + \frac{|y|}{2})^{-k}\). Hence, with Lemma 3.7 we can derive
\[ \int_{\mathbb{R}} (1 + |x|)^{-k} (1 + |x - y|)^{-k} (1 + |\lambda x - z|)^{-k} \, dx \]

\[ = \left( \int_{N_y} + \int_{N_y^c} \right) (1 + |x|)^{-k} (1 + |x - y|)^{-k} (1 + |\lambda x - z|)^{-k} \, dx \]

\[ \lesssim (1 + |y|)^{-k} \int_{\mathbb{R}} (1 + |x - y|)^{-k} \left( 1 + |\lambda| \left| x - \frac{z}{\lambda} \right| \right)^{-k} \, dx \]

\[ + (1 + |y|)^{-k} \int_{\mathbb{R}} (1 + |x|)^{-k} \left( 1 + |\lambda| \left| x - \frac{z}{\lambda} \right| \right)^{-k} \, dx \]

\[ \lesssim (1 + |y|)^{-k} \max\{1, |\lambda|\}^{-1} \left( 1 + \min\{1, |\lambda|\} |y - \frac{z}{\lambda}| \right)^{-k} \]

\[ + (1 + |y|)^{-k} \max\{1, |\lambda|\}^{-1} \left( 1 + \min\{1, |\lambda|\} |\frac{z}{\lambda}| \right)^{-k}, \]
which concludes the proof. □

Now we are able to prove that the integrability condition on the kernel function is satisfied, i.e. that $R_q \in A_{q,mv}$. 

**Theorem 3.9.** Let $\Psi \in L_1(\mathbb{R}^d) \cap L_2(\mathbb{R}^d)$ be an admissible shearlet with 
\[
\text{supp } \hat{\Psi} \subseteq \langle [-a_1, -a_0] \cup [a_0, a_1] \rangle \times Q_b.
\]
Let $\Phi \in L_1(\mathbb{R}^d) \cap L_2(\mathbb{R}^d)$ be chosen as in Remark 5 so that condition (3.5) is satisfied for $0 < a_0 < a_1$ and $b \in \mathbb{R}^{d-1}_+$ and additionally $\hat{\Phi} \in \mathcal{V}_0^\infty(\mathbb{R}^d)$. Then, for every $q > 1$ the kernel $R_q$ fulfills 
\[
R_q \in A_{q,mv}. 
\]

**Proof.** For $q > 1$ fixed we use Lemma 3.5 and look at the four summands in (3.11) independently. We need to show that all summands are bounded and for that we use Lemma 3.6. Let $\tilde{\alpha} := aa$ and by using Lemma 3.6 (i) with the specific weight $v_r$ we obtain 
\[
\begin{align*}
\text{ess sup}_{(\alpha,\sigma,\tau) \in X} & \int_X \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} \left|\langle \Phi, \psi_{(\alpha,\sigma,\tau),t}\rangle\right|^q \mu(a,s,t) \\
&= \text{max} \left\{ \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} \left|\langle \Phi, \psi_{(\alpha,\sigma,\tau),t}\rangle\right|^q ds dt, \right. \\
&\left. \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} \mu(a,s,t) \left|\langle \Phi, \psi_{(\alpha,\sigma,\tau),t}\rangle\right|^q ds dt \right\}. 
\end{align*}
\]
(3.29)

We need to show that all four summands of (3.29) are bounded and for this we will treat the summands independently.

First, since $\mathcal{F}(f^*) = \mathcal{F}(f)$ and $\Phi * \psi_{(a,s,0)}^* \in L_1(\mathbb{R}^d)$ we obtain 
\[
\langle \Phi, \psi_{(a,s,t)}^* \rangle = \langle \Phi, \psi_{(a,s,0)}(t) \rangle = \mathcal{F}^{-1}(\mathcal{F}(\Phi * \psi_{(a,s,0)}^*)) = \mathcal{F}^{-1}(\mathcal{F}(\mathcal{F}(\psi_{(a,s,0)}^*))) = \mathcal{F}^{-1}(\mathcal{F}(\mathcal{F}(\psi_{(a,s,0)}^*))) = t 
\]
which leads to 
\[
\int_{\mathbb{R}^d} \left|\langle \Phi, \psi_{(a,s,t)}^* \rangle\right|^q dt = \left|\mathcal{F}^{-1}(\mathcal{F}(\mathcal{F}(\psi_{(a,s,0)}^*)))\right|^q. 
\]
Applying Lemma 3.6 (ii) we see that $\mathcal{F}(\psi_{(a,s,0)}^*) \equiv 0$ for all $s \notin Q_{d_2}$ or $a \notin [-\frac{a_2}{a_1}, \frac{a_2}{a_1}]$, which implies 
\[
\left|\mathcal{F}^{-1}(\mathcal{F}(\mathcal{F}(\psi_{(a,s,0)}^*)))\right|^q = 0 
\]
for all $s \notin Q_{d_2}$ or $a \notin [-\frac{a_2}{a_1}, \frac{a_2}{a_1}]$. Thus, with Lemma 3.6 (ii) we derive 
\[
\begin{align*}
\text{ess sup}_{\alpha \in [-1,1]^d} & \int_{\mathbb{R}^d} \int_{\mathbb{R}^{d-1}} |\langle \Phi, \psi_{(a,s,t)}\rangle|^q ds dt \\
&= \text{ess sup}_{\alpha \in [-1,1]^d} \int_{\mathbb{R}^{d-1}} \left|\mathcal{F}^{-1}(\mathcal{F}(\mathcal{F}(\psi_{(a,s,0)}^*)))\right|^q ds \\
&= \text{ess sup}_{\alpha \in [-1,1]^d} \int_{\mathbb{R}^{d-1}} \left|\mathcal{F}(\mathcal{F}(\psi_{(a,s,0)}^*)))\right|^q ds \\
&= \text{ess sup}_{\alpha \in [-1, \frac{a_2}{a_1}, \frac{a_2}{a_1}]} \int_{Q_{d_2}} \left|\mathcal{F}(\mathcal{F}(\psi_{(a,s,0)}^*)))\right|^q ds < \infty. 
\end{align*}
\]
(3.30)
Using the same arguments as well as Lemma 3.6 (i) we obtain

\[
\begin{align*}
\text{ess sup}_{\alpha \in [-1,1]} \int \int \int_{D^{d-1}} & |q|^{-1} \max \left\{ \frac{|\alpha|}{|\alpha|}, \frac{|\alpha|}{|\alpha|} \right\}^{-1} \int_{D^{d-1}} \left| \left\langle \Phi, \psi_{(a,s,t)} \right\rangle \right|^{q} \frac{da}{|a|^{d+1}} \, ds \, dt \\
& \leq \int \max \left\{ |\alpha|, |\alpha|^{-1} \right\}^{-1} \int_{D^{d-1}} \left\| \mathcal{F}^{-1}(\tilde{\Phi}(\psi_{(a,s,0)})) \right\|_{L^{q}}^{q} \, ds \frac{da}{|a|^{d+1}} \\
& = \left( \int + \int \right) \max \left\{ |\alpha|, |\alpha|^{-1} \right\}^{-1} \int_{Q_{d_1}} \left\| \Phi \ast \psi_{(a,s,0)} \right\|_{L^{q}}^{q} \, ds \frac{da}{|a|^{d+1}} < \infty.
\end{align*}
\]

(3.31)

Again, with analogous arguments and Lemma 3.6 (ii) it follows that

\[
\begin{align*}
\int & \int \int_{D^{d-1}} |q|^{-1} \left| \left\langle \Phi, \psi_{(a,s,t)} \right\rangle \right|^{q} \frac{da}{|a|^{d+1}} \, ds \, dt \\
& = \int \int \left| \Phi \ast \psi_{(a,s,0)} \right|^{q} \frac{da}{|a|^{d+1}} \, ds \, dt \\
& = \left( \int + \int \right) \left| \Psi \ast \psi_{(a,s,0)} \right|^{q} \int_{Q_{d_2}} \, ds \frac{da}{|a|^{d+1}} < \infty.
\end{align*}
\]

(3.32)

For the last summand in (3.29) we choose \( q_0, q_1 \) positive, such that \( q_0 + q_1 = q \). We will specify the choice at the end of the proof. Then, it follows that

\[
\begin{align*}
\int & \int \int_{D^{d-1}} \left| \left\langle \Phi, \psi_{(\infty,s,t)} \right\rangle \right|^{q} \, ds \, dt \\
& = \int \int \int_{D^{d-1}} (\Phi \ast \psi_{(\infty,s,0)}(t))^{q_0+q_1} \, dt \, ds \\
& = \int \int \left( (\Phi \ast \psi_{(\infty,s,0)}(t))^{q_0} \right)^{q_1} \mathcal{F}^{-1}(\tilde{\Phi}(\psi_{(a,s,0)})(t))^{q_1} \, dt \, ds \\
& \leq \int \int \left( \left( \int_{D^{d}} (\Phi(x)\psi_{(\infty,s,0)}(x-t)) \, dx \right)^{q_0} \right)^{q_1} \int_{D^{d}} (\Phi(\omega)\psi_{(\infty,s,0)}(\omega)) \, d\omega \, ds \\
& =: \int_{D^{d-1}} I_0(s) \, ds.
\end{align*}
\]

(3.33)

In the following we will treat both factors \( I_0 \) and \( I_1 \) independently.

\( I_0(s) \): We assume in the following \( 0 < q_0 < 1 \). Since \( \Phi \in C_c^\infty(D^{d}) \), for every \( k \in \mathbb{N} \) it follows that \( |\Phi(x)| \leq (1 + |x|)^{-k} \) for all \( x \in \mathbb{R}^d \) with the constant depending on \( k \) and \( d \). Then,

\[
I_0(s) \lesssim \int_{D^{d}} \left( \int_{D^{d}} \prod_{i=1}^{d} \left[ (1 + |x_i + t_i|)^{-k} (1 + |(S_{-x}x)_{i}|)^{-k} \right] \, dx \right)^{q_0} \, dt =: \int_{D^{d}} I_s(t)^{q_0} \, dt
\]

21
for \( s \in \mathbb{R}^{d-1} \) fixed and where \((S_{-s}x)_i\) denotes the \(i\)-th entry of the vector \(S_{-s}x \in \mathbb{R}^d\). With this notation we intend to show

\[
(3.34) \quad \int_{\mathbb{R}^d} I_s(t)^{q_0} \, dt \lesssim (1 + \|s\|)^{1-q_0} \prod_{i=1}^d (1 + |t_i|)^{-kq_0} \, dt
\]

with the constant depending on \(k\) and \(q_0\) only. For this we first show an auxiliary result for \(d = 3\) which we will then generalize to arbitrary dimensions. To illustrate our method we differentiate between the following four cases for \( s \in \mathbb{R}^2 \) with \(s_1, s_2 \neq 0\).

**Case 1:** \(|s_1|, |s_2| \leq 1\). With Lemma 3.7 and Lemma 3.8 we obtain

\[
I_s(t) \lesssim \int_{\mathbb{R}^2} (1 + |t_1 + s_1x_2 + s_2x_3|)^{-k}(1 + |x_2 + t_2|)^{-k} \\
\quad \cdot (1 + |x_2|)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_2, x_3 \\
\lesssim \int_{\mathbb{R}} (1 + |t_2|)^{-k}(1 + |x_2 + t_2 + t_1 + s_2x_3|)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3 \\
\quad + \int_{\mathbb{R}} (1 + |t_2|)^{-k}(1 + |t_1 + s_2x_3|)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3 \\
\lesssim (1 + |t_2|)^{-k}(1 + |t_3|)^{-k}[(1 + |s_2t_3 + s_1t_2 + t_1|)^{-k} \\
\quad + (1 + |s_1t_2 - t_1|)^{-k} + (1 + |s_2t_3 + t_1|)^{-k} + (1 + |t_1|)^{-k}].
\]

**Case 2:** \(|s_1| \leq 1, |s_2| > 1\). Again, with Lemma 3.7 and Lemma 3.8 we obtain

\[
I_s(t) \lesssim \int_{\mathbb{R}} (1 + |t_2|)^{-k}(1 + |-s_1t_2 + t_1 + s_2x_3|)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3 \\
\quad + \int_{\mathbb{R}} (1 + |t_2|)^{-k}(1 + |t_1 + s_2x_3|)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3 \\
\lesssim |s_2|^{-1}(1 + |t_2|)^{-k}(1 + |t_3|)^{-k}[(1 + |-t_3 + s_1s_2^{-1}t_2 - s_2^{-1}t_1|)^{-k} \\
\quad + (1 + |s_1s_2^{-1}t_2 - s_2^{-1}t_1|)^{-k} + (1 + |t_3 + s_2^{-1}t_1|)^{-k} + (1 + |s_2^{-1}t_1|)^{-k}].
\]

**Case 3:** \(|s_1| > 1, |s_2| \leq |s_1|\). Similarly we apply Lemma 3.7 and Lemma 3.8 to derive

\[
I_s(t) \lesssim \int_{\mathbb{R}^2} (1 + |t_1 + s_1x_2 + s_2x_3|)^{-k}(1 + |x_2 + t_2|)^{-k} \\
\quad \cdot (1 + |x_2|)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_2, x_3 \\
\lesssim \int_{\mathbb{R}} (1 + |t_2|)^{-k}|s_1|^{-1}(1 + |-t_2 + s_1^{-1}t_1 + s_1^{-1}s_2x_3|)^{-k} \\
\quad \cdot (1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3 \\
\quad + \int_{\mathbb{R}} (1 + |t_2|)^{-k}|s_1|^{-1}(1 + |s_1^{-1}t_1 + s_1^{-1}s_2x_3|)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3 \\
\lesssim |s_1|^{-1}(1 + |t_2|)^{-k}(1 + |t_3|)^{-k}[(1 + |-s_1^{-1}s_2t_3 - t_2 + s_1^{-1}t_1|)^{-k} \\
\quad + (1 + |-t_2 + s_1^{-1}t_1|)^{-k} + (1 + |s_1^{-1}s_2t_3 + s_1^{-1}t_1|)^{-k} + (1 + |s_1^{-1}t_1|)^{-k}].
\]
Case 4: \(|s_1| > 1, |s_2| > |s_1|\). Finally we apply Lemma 3.7 and Lemma 3.8 again and conclude

\[
I_s(t) \lesssim \int_{\mathbb{R}} (1 + |t_2|)^{-k} |s_1|^{-1}(1 + | - t_2 + s_1^{-1}t_1 + s_1^{-1}st_3|)^{-k}
\]

\[
\cdot (1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3
\]

\[
+ \int_{\mathbb{R}} (1 + |t_2|)^{-k} |s_1|^{-1}(1 + |s_1^{-1}t_1 + s_1^{-1}st_3|^k)^{-k}(1 + |x_3 + t_3|)^{-k}(1 + |x_3|)^{-k} \, dx_3
\]

(3.38)

\[
\lesssim |s_2|^{-1}(1 + |t_2|)^{-k}(1 + |t_3|)^{-k}(1 + |t_3|)^{-k}(1 + | - t_3 - s_1s_2^{-1}t_2 + s_2^{-1}t_4|)^{-k}
\]

\[
+ (1 + | - s_1s_2^{-1}t_2 + s_2^{-1}t_4|)^{-k} + (1 + | - t_3 + s_2^{-1}t_1|)^{-k} + (1 + |s_2^{-1}t_1|)^{-k}.
\]

The four cases (3.35), (3.36), (3.37), (3.38) yield the estimate

(3.39)

\[
I_s(t) \lesssim |\det A^i_s| \sum_{i=1}^{4} \prod_{j=1}^{3} (1 + |(A^i_s t)_j|)^{-k}
\]

with the Matrices \(A^i_s, s \in \mathbb{R}^2, i = 1, \ldots, 4\), being of the form

\[
A^i_s = \begin{pmatrix}
\lambda & \mu & \nu \\
0 & 1 & 0 \\
0 & 0 & 1
\end{pmatrix}
\]

for some \(\lambda, \mu, \nu \in \mathbb{R}\) depending on \(s_1, s_2\).

In particular it follows from the four cases that

\[
|\det A^i_s| = |\lambda| = \begin{cases}
1, & |s_1|, |s_2| \leq 1, \\
|s_2|^{-1}, & |s_1| \leq 1, |s_2| > 1, \\
|s_1|^{-1}, & |s_1| > 1, |s_2| \leq |s_1|, \\
|s_2|^{-1}, & |s_1| > 1, |s_2| > |s_1|
\end{cases} = \max\{1, |s_1|, |s_2|\}^{-1}.
\]

We now intend to show, that this result holds for arbitrary dimension. To this end we fix \(d \geq 3\) as well as \(s \in \mathbb{R}^{d-1}\) with \(s_i \neq 0\) for all \(i = 1, \ldots, d - 1\) and assume that there exist matrices \(A^i_s\) for \(1 \leq i \leq 2^{d-1}\) of the form

(3.40)

\[
A^i_s = \begin{pmatrix}
* & * & \cdots & * \\
1 & & & \\
& & & \\
& & & 1
\end{pmatrix}
\]

with \(\det A^i_s = (A^i_s)_{11} = \max\{1, |s_1|, \ldots, |s_{d-1}|\}^{-1} = \min\{1, |s_1|^{-1}, \ldots, |s_{d-1}|^{-1}\} =: \min(s)\). Assume the estimate

(3.41)

\[
I_s(t) \lesssim \min(s) \sum_{i=1}^{2^{d-1}} \prod_{j=1}^{d} (1 + |(A^i_s t)_j|)^{-k}
\]

holds true for fixed \(d\). As shown in (3.39), this readily is the case for \(d = 3\). We now intend to show that the estimate (3.41) also holds for \(d + 1\). Then, (3.41) will hold for arbitrary dimension by full induction over the dimension. To this end we fix \(s \in \mathbb{R}^d\) with \(s_i \neq 0\) for all \(i = 1, \ldots, d\) and define \(\tilde{x} := (x_1, \ldots, x_d), \tilde{s} := (s_1, \ldots, s_{d-1}), \tilde{t} := (t_1, \ldots, t_d)\) and \(u := (t_1 + s_d x_{d+1}, t_2, \ldots, t_d)\). Then we
deduce from (3.41) the estimate

\[ I_s(t) = \int_{\mathbb{R}^{d+1}} \prod_{i=1}^{d+1} \left[ (1 + |x_i + t_i|)^{-k}(1 + |(S_{S_i}x_i)|)^{-k} \right] \, dx \]

\[ = \int_{\mathbb{R}^{d+1}} (1 + |x_{d+1} + t_{d+1}|)^{-k}(1 + |x_{d+1}|)^{-k} \left( \int_{\mathbb{R}^{d+1}} \prod_{i=1}^{d} (1 + |x_i + u_i|)^{-k}(1 + |(S_{S_i}x_i)|)^{-k} \, dx_i \right) \, dx_{d+1} \]

\[ = \int_{\mathbb{R}^{d+1}} I_s(u)(1 + |x_{d+1} + t_{d+1}|)^{-k}(1 + |x_{d+1}|)^{-k} \, dx_{d+1} \]

(3.42) \[ \lesssim \min(\tilde{s}) \sum_{i=1}^{2^{d-1}} \prod_{j=1}^{d} \int_{\mathbb{R}} (1 + |(A_i^ju)^j|)^{-k}(1 + |x_{d+1} + t_{d+1}|)^{-k}(1 + |x_{d+1}|)^{-k} \, dx_{d+1}, \]

whereby we remember \((S_{S_i}x_i) = x_i\) for all \(i = 2, \ldots, d + 1\) and \((A_i^ju)^j = u_j\) for all \(j = 2, \ldots, d\).

Since all integrals for \(j \neq 1\) will remain unchanged we are now interested in the integrals in (3.42) for arbitrary \(1 \leq i \leq 2^{d-1}, j = 1\) and obtain with Lemma 3.8

\[ \int_{\mathbb{R}} (1 + |(A_i^ju)^j|)^{-k}(1 + |x_{d+1} + t_{d+1}|)^{-k}(1 + |x_{d+1}|)^{-k} \, dx_{d+1} \]

\[ = \int_{\mathbb{R}} (1 + |(A_i^j\tilde{t})_1 + \min(\tilde{s})s_dx_{d+1}|)^{-k}(1 + |x_{d+1} + t_{d+1}|)^{-k}(1 + |x_{d+1}|)^{-k} \, dx_{d+1} \]

\[ \lesssim \min(\tilde{s})(1 + |t_{d+1}|)^{-k} \max\{1, \min(\tilde{s})s_d\}^{-1} \times \left[ (1 + \min\{1, \min(\tilde{s})s_d\}t_{d+1} - \frac{\min\{1, \min(\tilde{s})s_d\}}{\min(\tilde{s})s_d}\left(A_i^j\tilde{t}\right)_1 \right]^{-k} \]

\[ + \left( 1 + \frac{\min\{1, \min(\tilde{s})s_d\}}{\min(\tilde{s})s_d}\left(A_i^j\tilde{t}\right)_1 \right)^{-k} \]

\[ = \max\{\min(\tilde{s})^{-1}, |s_d|^{-1}\} \cdot \left[ (1 + |(B_i^j\tilde{t})|)^{-k}(1 + |(B_i^j\tilde{t})_1|)^{-k} + (1 + |(C_i^j\tilde{t})|)^{-k}(1 + |(C_i^j\tilde{t})_1|)^{-k} \right] \]

for some matrices \(B_i^j, C_i^j\) of the form (3.40) where

\[ (B_i^j)_{11} = (C_i^j)_{11} = (A_i^j)_{11} \left( \frac{\min\{1, \min(\tilde{s})s_d\}}{\min(\tilde{s})s_d} \right) = \min\{|s_d|^{-1}, \min(\tilde{s})\} = \min(s). \]

Since \(\max\{\min(\tilde{s})^{-1}, |s_d|^{-1}\} = \max\{1, |s_1|, \ldots, |s_d|\}^{-1} = \min(s)\) we derive together with (3.42) the estimate (3.41) for \(d + 1\). Hence, (3.41) holds true for arbitrary dimension.

With this at hand we return to arbitrary dimension \(d\) and further deduce

\[ |\det A_i^j|^{-1} = \max\{1, |s_1|, \ldots, |s_{d-1}|\} \leq 1 + \max\{|s_1|, \ldots, |s_{d-1}|\} \lesssim 1 + |\|s\||. \]
Now we can prove the following estimate for \( 0 < q_0 < 1 \) and almost every \( s \in \mathbb{R}^d \):

\[
\int_{\mathbb{R}^3} I_s(t)^{q_0} \, dt \lesssim |\text{det} \, A_s^{T} s|^{q_0} \int_{\mathbb{R}^d} \left( \sum_{i=1}^{d-1} \prod_{j=1}^{d} (1 + |(A_s^T t)_j|)^{q_0} \right) \, dt
\]

\[
\leq |\text{det} \, A_s^{T} s|^{q_0} \sum_{i=1}^{d-1} \int_{\mathbb{R}^d} \prod_{j=1}^{d} (1 + |(A_s^T t)_j|)^{-kq_0} \, dt
\]

\[
\lesssim |\text{det} \, A_s^{T} s|^{q_0-1} \int_{\mathbb{R}^d} \prod_{j=1}^{d} (1 + |t_j|)^{-kq_0} \, dt
\]

\[
\lesssim (1 + \|s\|)^{1-q_0} \int_{\mathbb{R}^d} \prod_{j=1}^{d} (1 + |t_j|)^{-kq_0} \, dt,
\]

which shows (3.34).

\( I_1(s) \): We shall now deal with the second factor in (3.32) for \( q_1 > 0 \). By Lemma 3.6 (iii) and the definition of \( \hat{\Phi} \) we obtain

\[
I_1(s)^{1/q_1} = \int_{\mathbb{R}^d} \hat{\Phi}(\omega) \hat{\Phi}(S_s^T \omega) \, d\omega
\]

\[
\leq \int_{\Omega_s} |\omega_1|^{d-1} \left( \int_{\mathbb{R}} \left| \hat{\Psi}(\xi_1, \tilde{\omega}) \right|^2 \, d\xi_1 \right)^{1/2} \left( \int_{\mathbb{R}} \left| \hat{\Psi}(\xi_1, S_s^T \omega) \right|^2 \, d\xi_1 \right)^{1/2} \, d\omega
\]

with \( \Omega_s = \{ x \in \mathbb{R}^d : |x_1| \leq a_1, \max \{-b_i, -b_i - s_{i-1} x_1\} \leq x_i \leq \min \{b_i, b_i - s_{i-1} x_1\}, i = 2, \ldots, d \} \). Since \( \hat{\Psi} \) is compactly supported and continuous, we conclude

\[
(3.43) \quad I_1(s)^{1/q_1} \lesssim \int_{\Omega_s} |\omega_1|^{d-1} \, d\omega.
\]

In the following we assume \( s > 0 \) componentwise, all other cases can be treated analogously by symmetry arguments. Then, for any \( \omega \in \Omega_s \) it follows from Lemma 3.6 (iii) that \( |\omega_1| \leq 2b_1 s_{i-1}^{-1} \) for all \( i = 2, \ldots, d \), hence, \( |\omega_1| \lesssim (\max_{i=1, \ldots, d-1} s_i)^{-1} = \|s\|_{\infty}^{-1} \). Moreover, since \( \omega \in \text{supp} \hat{\Phi} \), we derive \( -b_i \leq \omega_i \leq b_i \) for all \( i = 1, \ldots, d \). We can now estimate (3.43) in the following manner:

\[
I_1(s)^{1/q_1} \lesssim \int_{|\omega_1| \leq \min \{b_1, \|s\|_{\infty}^{-1} \}} |\omega_1|^{d-1} \, d\omega_1.
\]

Assume first that \( \|s\|_{\infty}^{-1} \geq b_1 \), then we have

\[
I_1(s)^{1/q_1} \lesssim \int_{|\omega_1| \leq b_1} |\omega_1|^{d-1} \, d\omega_1 \lesssim b_1^d \lesssim (1 + \|s\|)^{-d}.
\]

On the other hand if \( \|s\|_{\infty}^{-1} < b_1 \) it follows that

\[
I_1(s)^{1/q_1} \lesssim \int_{|\omega_1| \leq \|s\|_{\infty}^{-1}} |\omega_1|^{d-1} \, d\omega_1 \lesssim |s|^{-d} \lesssim (1 + \|s\|)^{-d}.
\]

In both cases we obtain

\[
(3.44) \quad I_1(s) \lesssim (1 + \|s\|)^{-dq_1}.
\]
Plugging (3.34) and (3.44) into (3.33) now yields
\[
\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} |\langle \Phi, \psi_{(\infty,s,t)} \rangle|^q \, ds \, dt \lesssim \int_{\mathbb{R}^d} I_0(s) I_1(s) \, ds.
\]
(3.45)
\[
\lesssim \prod_{i=1}^{d} (1 + |t_i|)^{-kq_0} \, dt \int_{\mathbb{R}^d} (1 + \|s\|)^{1-q_0-dq_1} \, ds.
\]
For any choice of \( q_0 \) we can find a \( k \in \mathbb{N} \), such that the first integral in (3.45) converges. The second integral in (3.45) is known to converge if and only if \( q_0 + dq_1 > d \). This can be obtained by setting \( q_0 = \frac{q-1}{a} \) and \( q_1 = \frac{d-1}{a} q + \frac{1}{a} \). If \( q > 1 \) this satisfies
\[
q_0 + q_1 = \frac{q-1}{d} + \frac{d-1}{d} q + \frac{1}{d} = \frac{1}{d} (q - 1 + q(d - 1) + 1) = q
\]
and
\[
q_0 + dq_1 = \frac{q-1}{d} + (d-1)q + 1 = 1 + q \left( d - 1 + \frac{1}{a} \right) - \frac{1}{d} = d - \left( d - 1 + \frac{1}{d} \right) + q \left( d - 1 + \frac{1}{d} \right) = d + (q - 1) \left( d - 1 + \frac{1}{d} \right) > d
\]
and we finally conclude
\[
\int_{\mathbb{R}^d} \int_{\mathbb{R}^d} |\langle \Phi, \psi_{(\infty,s,t)} \rangle|^q \, ds \, dt < \infty.
\]
Altogether with (3.30), (3.31) and (3.32) we have now shown that all four summands in (3.29) are bounded and this concludes the proof. \( \square \)

At this point we intend to show that there exist functions \( \hat{\Phi} \) satisfying the assumptions of Theorem 3.9. Indeed we will show that we can find \( \hat{\Psi} \) so that \( \hat{\Phi} \in \mathcal{C}_0^\infty(\mathbb{R}^d) \).

**Example 3.1.** We fix any odd dimension \( d \). Then, for \( \xi = (\xi_1, \xi_2) \) let \( \hat{\Psi}(\xi) := \hat{\psi}_1(\xi_1) \hat{\psi}_2(\xi_2) \) with
\[
\hat{\psi}_1(\xi_1) := \begin{cases} 
\xi_1 \xi_1 \xi_1, & 1 < \xi_1 < 3 \\
\xi_1 \xi_1 \xi_1, & -3 < \xi_1 < -1 \\
0, & \text{otherwise}
\end{cases}
\]
and \( \hat{\psi}_2 \in \mathcal{C}_0^\infty(\mathbb{R}^{d-1}) \) with \( \hat{\psi} \geq 0 \). According to Remark 5 we set
\[
\hat{\Phi}(\xi) := \xi_1^{d-1} \left( \int_{\mathbb{R}^d} |\Psi(\omega_1, \xi_2)|^2 \, d\omega_1 \right)^{1/2}
\]
\[
= \xi_1^{d-1} |\hat{\psi}_2(\xi_2)| \left( 2 \int_{\max(\{\xi_1\}, 1)}^{3} e^{(\omega_1 \xi_1)^2} d\omega_1 \right)^{1/2}
= : \xi_1^{d-1} |\hat{\psi}_2(\xi_2)| \hat{\psi}_1(\xi_1)
\]
with \( \hat{\Phi}(\xi) = 0 \) for \( |\xi_1| > 3 \). Now we show that this function satisfies the required assumptions. The fact that \( \hat{\psi}_1 \in \mathcal{C}_0^\infty(\mathbb{R}) \) and therefore \( \hat{\Psi} \in \mathcal{C}_0^\infty(\mathbb{R}^d) \) is immediately obvious. With the given construction, together with Remark 5, we see that the necessary condition from Theorem 3.3 is satisfied, i.e. the functions \( \Phi \) and \( \Psi \) constitute a Parseval frame. Furthermore if we assume \( \hat{\Phi} \in \mathcal{C}_0^\infty(\mathbb{R}^d) \subset \mathcal{S}(\mathbb{R}^d) \) then \( \Phi \in \mathcal{S}(\mathbb{R}^d) \subset L_1(\mathbb{R}^d) \cap L_2(\mathbb{R}^d) \) and all necessary conditions on \( \Phi \) are satisfied.
So we need to show that $\hat{\Phi} \in \mathcal{C}_0^\infty(\mathbb{R}^d)$, which means that we will show that $\varphi_1$ is infinitely continuously differentiable since $\xi_1^{-1/2}$ is a monomial. To show this we need to prove that

$$\lim_{x \to 3} \frac{d^n}{dx^n}(\varphi_1(x)) = 0$$

and

$$\lim_{x \to 1} \frac{d^n}{dx^n}(\varphi_1(x)) = 0$$

for all $n \in \mathbb{N}$. Since both statements are proven in an analogous manner, we will only show the proof of the first statement and for the remainder of this example we assume $2 < x < 3$. Since we have $\varphi_1(x) = (f \circ g)(x)$ with $f(x) = \sqrt{x}$ and

$$g(x) = 2 \int_0^x e^{\frac{x^2}{(x-2)}} \, dx,$$

we can use Faà di Bruno’s formula to get a closed expression for the $n$-th derivative. Recall that for two functions $f$ and $g$ the identity

$$(3.46) \quad \frac{d^n}{dx^n}((f \circ g)(x)) = \sum_{k=1}^{n} \frac{d^k f}{dx^k}(g(x)) B_{n,k}\left( \frac{d g}{dx}(x), \frac{d^2 g}{dx^2}(x), \ldots, \frac{d^{(n-k+1)} g}{dx^{(n-k+1)}}(x) \right)$$

holds with $B_{n,k}$ being the Bell polynomials, i.e.

$$B_{n,k}(x_1, x_2, \ldots, x_{(n-k+1)}) = \sum \frac{n!}{j_1! \cdots j_{(n-k+1)}!} \left( \frac{x_1}{1!} \right)^{j_1} \cdots \left( \frac{x_{(n-k+1)}}{(n-k+1)!} \right)^{j_{(n-k+1)}}.$$ 

The sum in the above expression is taken over all $(j_1, \ldots, j_{(n-k+1)})$ with $j_1 + \cdots + j_{(n-k+1)} = k$ and $j_1 + 2j_2 + \cdots + (n-k+1)j_{(n-k+1)} = n$. The derivatives of the square root satisfy

$$\frac{d^k f}{dx^k}(x) = c_k x^{-k+\frac{1}{2}}$$

with $c_k$ being some constant and since because of $1 < x < 3$ we have

$$(3.47) \quad \frac{d g}{dx}(x) = -2e^{\frac{x^2}{(x-2)}}$$

this means that for all $k \in \mathbb{N}$ the derivatives of $g$ satisfy

$$\frac{d^k g}{dx^k}(x) = Q_k(x) e^{\frac{x^2}{(x-2)}}$$

with $Q_k$ being some rational function without singularities in the interval $(1, 3)$. Thus, using (3.46) we now have

$$\frac{d^n \varphi_1}{dx^n}(x) = \sum_{k=1}^{n} c_k (g(x))^{-k+\frac{1}{2}} \sum_{(j_1, \ldots, j_{(n-k+1)})} c_{n,k,j} \left( \frac{Q_1(x) e^{\frac{x^2}{(x-2)}}}{x} \right)^{j_1} \cdots \left( \frac{Q_{(n-k+1)}(x) e^{\frac{x^2}{(x-2)}}}{x} \right)^{j_{(n-k+1)}}$$

$$= \sum_{k=1}^{n} R_{k,n}(x) \left( \frac{g(x)}{x} \right)^{-k+\frac{1}{2}} e^{\frac{x^2}{(x-2)}} k$$

$$= \sum_{k=1}^{n} \tilde{R}_{k,n}(x) \left( \frac{e^{\frac{x^2}{(x-2)}}}{g(x)} \right)^{1+\frac{1}{2k-1}} k^{-\frac{1}{2}}$$

$$= \sum_{k=1}^{n} \tilde{R}_{k,n}(x) \left( \frac{e^{\frac{x^2}{(x-2)}}}{g(x)} \right)^{1+\frac{1}{2k-1}} k^{-\frac{1}{2}}$$

$$= \sum_{k=1}^{n} \tilde{R}_{k,n}(x) \left( \frac{e^{\frac{x^2}{(x-2)}}}{g(x)} \right)^{1+\frac{1}{2k-1}} k^{-\frac{1}{2}}$$

$$= \sum_{k=1}^{n} \tilde{R}_{k,n}(x) \left( \frac{e^{\frac{x^2}{(x-2)}}}{g(x)} \right)^{1+\frac{1}{2k-1}} k^{-\frac{1}{2}}$$
where $R_{k,n}$ is a rational function for every $k = 1, \ldots, n$ possibly changing from line to line and \( \hat{R}_{k,n}(x) := R_{k,n}(x)^{1/2} \). Since
\[
\lim_{x \searrow 3} \hat{R}_{k,n}(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}} = 0 \quad \text{and} \quad \lim_{x \searrow 3} g(x) = 0
\]
we use l’Hospital’s rule to determine the limit of the fraction. For the derivative of the numerator we obtain
\[
\frac{d}{dx} \left( \hat{R}_{k,n}(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}} \right)
= \frac{d}{dx} \hat{R}_{k,n}(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}} + \hat{R}_{k,n}(x) \frac{d}{dx} (e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}} - \frac{1}{x-3}
= Q(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}}
\]
where $Q$ is of the form $Q(x) = Q_2(x)Q_1(x)^{2k+3} + Q_3(x)Q_1(x)^{2k+3}$ with $Q_1$, $Q_2$, $Q_3$ being rational functions. This, together with (3.47), yields
\[
\lim_{x \searrow 3} \frac{d}{dx} \left( \hat{R}_{k,n}(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}} \right) = \lim_{x \searrow 3} Q(x) e^{(2k+3)\frac{x}{(x-3)}} = 0.
\]
Thus, with l’Hospital’s rule we get
\[
\lim_{x \searrow 3} \frac{d^n \hat{\varphi}_1(x)}{dx^n} = \lim_{x \searrow 3} \sum_{k=1}^{n} \left( \frac{\hat{R}_{k,n}(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}}}{g(x)} \right) k^{-\frac{1}{2}}
= \sum_{k=1}^{n} \left( \lim_{x \searrow 3} \frac{\hat{R}_{k,n}(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}}}{g(x)} \right) k^{-\frac{1}{2}}
= \sum_{k=1}^{n} \left( \lim_{x \searrow 3} \frac{d}{dx} \left( \hat{R}_{k,n}(x)^{(e^{(\frac{x}{(x-3)})}-1)^{1+\frac{1}{x-3}}} \right) \right) k^{-\frac{1}{2}} = 0.
\]

This proves that $\check{\varphi}_1 \in \mathcal{C}_0^\infty(\mathbb{R})$ and therefore that $\tilde{\Phi} \in \mathcal{C}_0^\infty(\mathbb{R}^d)$.

### 3.4. Inhomogeneous shearlet coorbit spaces

Now we are able to give a definition of the coorbit spaces associated to our inhomogeneous shearlet frame with respect to the weighted Lebesgue spaces $L_{p,v}(X,\mu)$.

**Definition 3.5.** Let the shearlet frame $\mathfrak{F}$ be chosen so that it satisfies the conditions in Theorem 3.9. Then for $1 \leq p < \infty$ and $1 < \tau \leq 2$ with $p < \tau'$ the shearlet coorbit space with respect to the Lebesgue space $L_{p,v}(X,\mu)$ is defined as
\[
SC_{r,\tau,p}^{\mathfrak{F},\tau} := \text{Co}_{\mathfrak{F},\tau}(L_{p,v}(X,\mu)) = \{ f \in (\mathcal{H}_{r,v})^\sim : \mathcal{SH}_{\mathfrak{F},\tau} f \in L_{p,v}(X,\mu) \}.
\]

It is endowed with the natural norm
\[
\| f \|_{SC_{r,\tau,p}^{\mathfrak{F},\tau}} := \| \mathcal{SH}_{\mathfrak{F},\tau} f \|_{L_{p,v}(X,\mu)}.
\]

These spaces are well-defined Banach spaces, which is implied by Theorem 3.9.

**Theorem 3.10.** With the same assumptions as in Theorem 3.9 the spaces $SC_{r,\tau,p}^{\mathfrak{F},\tau}$ are well-defined Banach spaces.

**Proof.** As stated in Remark 2, Theorem 3.9 and Lemma 2.1 imply that the assumption in Proposition 2.7 is fulfilled. Hence, the assertion follows. □

The following results are straightforward.
Lemma 3.11. Let $1 < p < q < \infty$, $1 < \tau \leq 2$ with $p, q < \tau'$ and $0 \leq r < s$. Furthermore let $\mathcal{G}$ and $\mathcal{G}$ satisfy the conditions in Theorem 3.9 with $G(\mathcal{G}, \mathcal{G}) \in \mathcal{A}_{1,m_v}$. Then,

(i) $\mathcal{S}^p_{\mathcal{G}, \tau, p} \subset \mathcal{S}^r_{\mathcal{G}, \tau, q'}$
(ii) $\mathcal{S}^2_{\mathcal{G}, \tau, p} \subset \mathcal{S}^r_{\mathcal{G}, \tau, p'}$
(iii) $\mathcal{S}^r_{\mathcal{G}, \tau, p} = \mathcal{S}^r_{\mathcal{G}, \tau, p'}$.

Proof. (i) and (ii) follow from Lemma 2.8 (ii), (iii) is a consequence of Proposition 2.9. □

Even though we introduced new integrability conditions on the kernel to obtain new spaces, these spaces are in fact one and the same, as the following proposition shows.

Proposition 3.12. Let $1 \leq p < \infty$, $1 < \sigma, \tau \leq 2$ with $p < \sigma', \tau'$. Then, $\mathcal{S}^p_{\mathcal{G}, \tau, p} = \mathcal{S}^r_{\mathcal{G}, \sigma, \sigma'}$.

Proof. Assume $f \in \mathcal{S}^p_{\mathcal{G}, \sigma, \sigma'}$, i.e. $f \in (\mathcal{H}_{\sigma, v_r})^\sim$ with $\mathcal{S} \mathcal{H}_{\mathcal{G}, \sigma} f \in L_{p, v_r}$, by the reproducing identity and Lemma 2.1 it holds $\mathcal{S} \mathcal{H}_{\mathcal{G}, \sigma} f = R_{\mathcal{G}}(\mathcal{S} \mathcal{H}_{\mathcal{G}, \sigma} f) \in R_{\mathcal{G}}(L_{p, v_r}) \subset L_{\tau', v_r} \subset L_{\sigma', v_r}$, Thus, Lemma 2.5 yields $f \in (\mathcal{H}_{\tau, v_r})^\sim$ and $f \in \mathcal{S}^r_{\mathcal{G}, \tau, p}$. Equivalently the converse is shown. □

Remark 6. With Proposition 3.12 at hand the coorbit spaces solely depend on $p$ and not on $\tau$. Thus it is justified to omit the parameter $\tau$ and simply write

$$\mathcal{S}^p_{\mathcal{G}, \tau, p} = \{ f \in (\mathcal{H}_{\tau, v_r})^\sim : \mathcal{S} \mathcal{H}_{\mathcal{G}, \tau} f \in L_{p, v_r} (X, \mu) \}$$

for $1 \leq p < \infty$ and some $\tau$ fulfilling $p < \tau' < \infty$.

APPENDIX A.

In this appendix we will briefly discuss Young’s inequality, the three-way Young’s inequality and Schur’s test mentioned in Section 2.

Lemma A.1 (Young’s inequality). Let $a, b \geq 0$ and $p, q > 0$ with $1/p + 1/q = 1$, then

$$ab \leq \frac{a^p}{p} + \frac{b^q}{q}.$$ 

Lemma A.2 (Three-way Young’s inequality). Let $a, b, c \geq 0$ and $p, q, r > 0$ with $1/p + 1/q + 1/r = 1$, then

$$abc \leq \frac{a^p}{p} + \frac{b^q}{q} + \frac{c^r}{r},$$

Proof. By applying Young’s inequality twice and observing $\frac{q}{q} + \frac{r}{r} = 1$ with $\frac{1}{p} + \frac{1}{q} = 1$ we obtain

$$abc \leq \frac{a^p}{p} + \frac{b^q}{q} + \frac{c^r}{r} \leq \frac{a^p}{p} + \frac{b^q}{q} + \frac{1}{p} \left( \frac{(b^q)^{r/q}}{q^{r/q}} + \frac{(c^r)^{q/r}}{r^{q/r}} \right) = \frac{a^p}{p} + \frac{b^q}{q} + \frac{c^r}{r},$$

which proves the claim. □

Lemma A.3 (Schur’s test). For a kernel $K : X \times X \to C$ with $K \in \mathcal{A}_{1,m_v}$ the corresponding kernel operator fulfills

$$\|K\|_{L_{p,v}} \rightarrow L_{p,v} \leq \|K\|_{A_{1,m_v}}$$

for all $1 \leq p \leq \infty$.

Proof. For $p < \infty$ assume $f \in L_{p,v}$ with $\|f\|_{L_{p,v}} \leq 1$, then

$$\|K(f)\|_{L_{p,v}} = \sup_{g \in L_{r,v}} \langle K(f), g \rangle \leq \|K\|_{A_{1,m_v}} \leq \sup_{g \in L_{r,v}} \int_X \int_X |K(x,y)f(y)g(x)| \, d\mu(x) \, d\mu(y),$$

$$\|g\|_{L_{p,v}} \leq 1$$
where \( p' \) denotes the Hölder-dual of \( p \). By Young’s inequality we obtain

\[
\int_X \int_X |K(x, y)f(y)g(x)| \, d\mu(x) \, d\mu(y) \\
\leq \frac{1}{p} \int_X \int_X |K(x, y)| m_{v}(x, y) \cdot |f(y)|^{p} v(y)^{p} \, d\mu(x) \, d\mu(y) \\
\quad + \frac{1}{p'} \int_X \int_X |K(x, y)| m_{v}(x, y) \cdot |g(x)|^{p'} v'(x)^{p'} \, d\mu(x) \, d\mu(y) \\
\leq \frac{1}{p} \|K\|_{A_{1,m_{v}}} \cdot \|f\|_{L_{p,v}}^{p} + \frac{1}{p'} \|K\|_{A_{1,m_{v}}} \cdot \|g\|_{L_{p',v'}}^{p'}.
\]

Thus, \( \|K(f)\|_{L_{p,v}} \to L_{p,v} \| \leq \|K\|_{A_{1,m_{v}}} \|.
\]

On the other hand for \( p = \infty \) and \( f \in L_{\infty,v} \), we have

\[
\|K(f)\|_{L_{\infty,v}} \leq \text{ess sup}_{x \in X} \int_X |K(x, y)| m_{v}(x, y) \cdot |f(y)| v(y) \, d\mu(y) \\
\leq \|K\|_{A_{1,m_{v}}} \cdot \|f\|_{L_{\infty,v}}
\]

which concludes the proof.

\[\square\]

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30
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