Optimal Bounds between $f$-Divergences and Integral Probability Metrics

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Abstract

The families of $f$-divergences (e.g. the Kullback–Leibler divergence) and Integral Probability Metrics (e.g. total variation distance or maximum mean discrepancies) are widely used to quantify the similarity between probability distributions. In this work, we systematically study the relationship between these two families from the perspective of convex duality. Starting from a tight variational representation of the $f$-divergence, we derive a generalization of the moment-generating function, which we show exactly characterizes the best lower bound of the $f$-divergence as a function of a given IPM. Using this characterization, we obtain new bounds while also recovering in a unified manner well-known results, such as Hoeffding’s lemma, Pinsker’s inequality and its extension to subgaussian functions, and the Hammersley–Chapman–Robbins bound. This characterization also allows us to prove new results on topological properties of the divergence which may be of independent interest.

1 Introduction

Quantifying the extent to which two probability distributions differ from one another is central in most, if not all, problems and methods in machine learning and statistics. In a line of research going back at least to the work of Kullback [Kul59], information theoretic measures of dissimilarity between probability distributions have provided a fruitful and unifying perspective on a wide range of statistical procedures. A prototypical example of this perspective is the interpretation of maximum likelihood estimation as minimizing the Kullback–Leibler divergence between the empirical distribution—or the ground truth distribution in the limit of infinitely large sample—and a distribution chosen from a parametric family.

A natural generalization of the Kullback–Leibler divergence is provided by the family of $\phi$-divergences\footnote{Henceforth, we use $\phi$-divergence instead of $f$-divergence and reserve the letter $f$ for a generic function.} [Csi63, Csi67b] also known in statistics as Ali–Silvey distances [AS66].\footnote{$\phi$-divergences had previously been considered [Rén61, Mor63], though not as an independent object of study.} Informally,
a $\phi$-divergence quantifies the divergence between two distributions $\mu$ and $\nu$ as an average cost of the likelihood ratio, that is, $D_\phi(\mu \parallel \nu) \equiv \int \phi(d\mu/d\nu) \, d\nu$ for a convex cost function $\phi : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}_{\geq 0}$. Notable examples of $\phi$-divergences include the Hellinger distance, the $\alpha$-divergences (a convex transformation of the Rényi divergences), and the $\chi^2$-divergence.

Crucial in applications of $\phi$-divergences are their so-called variational representations. For example, the Donsker–Varadhan representation [DV76, Theorem 5.2] expresses the Kullback–Leibler divergence $D(\mu \parallel \nu)$ between probability distributions $\mu$ and $\nu$ as

$$D(\mu \parallel \nu) = \sup_{g \in \mathcal{L}^b} \left\{ \int g \, d\mu - \log \int e^g \, d\nu \right\},$$

(1)

where $\mathcal{L}^b$ is the space of bounded measurable functions. Similar variational representations were for example used by [NWJ08, NWJ10, RRGGP12, BBR+18] to construct estimates of $\phi$-divergences by restricting the optimization problem (1) to a class of functions $\mathcal{G} \subseteq \mathcal{L}^b$ for which the problem becomes tractable (for example when $\mathcal{G}$ is a RKHS or representable by a given neural network architecture). In recent work, [NCT16, NCM+17] conceptualized an extension of generative adversarial networks (GANs) in which the problem of minimizing a $\phi$-divergence is expressed via representations such as (1) as a two-player game between neural networks, one minimizing over probability distributions $\mu$, the other maximizing over $g$ as in (1).

Another important class of distances between probability distributions is given by Integral Probability Metrics (IPMs) defined by [Müll97] and taking the form

$$d_\mathcal{G}(\mu, \nu) = \sup_{g \in \mathcal{G}} \left\| \int g \, d\mu - \int g \, d\nu \right\|,$$

(2)

where $\mathcal{G}$ is a class of functions parametrizing the distance. Notable examples include the total variation distance ($\mathcal{G}$ is the class of all functions taking value in $[-1, 1]$), the Wasserstein metric ($\mathcal{G}$ is a class of Lipschitz functions) and Maximum Mean Discrepancies ($\mathcal{G}$ is the unit ball of a RKHS). Being already expressed as a variational problem, IPMs are amenable to estimation, as was exploited by [SFG+12, GBR+12]. MMDs have also been used in lieu of $\phi$-divergences to train GANs as was first done by [DRG15].

Rewriting the optimization problem (1) as

$$\sup_{g \in \mathcal{L}^b} \left\{ \int g \, d\mu - \int g \, d\nu - \log \int e^{(g-f) \, d\nu} \, d\nu \right\}$$

(3)

reveals an important connection between $\phi$-divergences and IPMs. Indeed, (3) expresses the divergence as the solution to a regularized optimization problem in which one attempts to maximize the mean deviation $\int g \, d\mu - \int g \, d\nu$, as in (2), while also penalizing functions $g$ which are too “complex” as measured by the centered log moment-generating function of $g$. In this work, we further explore the connection between $\phi$-divergences and IPMs, guided by the following question:

**what is the best lower bound of a given $\phi$-divergence as a function of a given integral probability metric?**

Some specific instances of this question are already well understood. For example, the best lower bound of the Kullback–Leibler divergence by a quadratic function of the total variation
distance is known as Pinsker’s inequality. More generally, describing the best lower bound of a \( \phi \)-divergence as a function of the total variation distance (without being restricted to being a quadratic), is known as Vajda’s problem, to which an answer was given by [FIIT03] for the Kullback–Leibler divergence and by [Gil06] for an arbitrary \( \phi \)-divergence.

Beyond the total variation distance—in particular, when the class \( \mathcal{G} \) in (2) contains unbounded functions—few results are known. Using (3), [BLM13, §4.10] shows that Pinsker’s inequality holds as long as the log moment-generating function grows at most quadratically. Since this is the case for bounded functions (via Hoeffding’s lemma), this recovers Pinsker’s inequality and extends it to the class of so-called subgaussian functions. This was recently used by [RZ20] to control bias in adaptive data analysis.

In this work, we systematize the convex analytic perspective underlying many of these results, thereby developing the necessary tools to resolve the above guiding question. As an application, we recover in a unified manner the known bounds between \( \phi \)-divergences and IPMs, and extend them along several dimensions. Specifically, starting from the observation of [RRGGP12] that the variational representation of \( \phi \)-divergences commonly used in the literature is not “tight” for probability measures (in a sense which will be made formal in the paper), we make the following contributions:

- we derive a tight representation of \( \phi \)-divergences for probability measures, exactly generalizing the Donsker–Varadhan representation of the Kullback–Leibler divergence.

- we define a generalization of the log moment-generating function and show that it exactly characterizes the best lower bound of a \( \phi \)-divergence by a given IPM. As an application, we show that this function grows quadratically if and only if the \( \phi \)-divergence can be lower bounded by a quadratic function of the given IPM and recover in a unified manner the extension of Pinsker’s inequality to subgaussian functions and the Hammersley–Chapman–Robbins bound.

- we characterize the existence of any non-trivial lower bound on an IPM in terms of the generalized log moment-generating function, and give implications for topological properties of the divergence, for example regarding compactness of sets of measures with bounded \( \phi \)-divergence and the relationship between convergence in \( \phi \)-divergence and weak convergence.

- the answer to Vajda’s problem for bounded functions is re-derived in a principled manner, providing a new geometric interpretation on the optimal lower bound of the \( \phi \)-divergence by the total variation distance. From this, we derive a refinement of Hoeffding’s lemma and generalizations of Pinsker’s inequality to a large class of \( \phi \)-divergences.

The rest of this paper is organized as follows: Section 2 discusses related work, Section 3 gives a brief overview of concepts and tools used in this paper, Section 4 derives the tight variational representation of the \( \phi \)-divergence, Section 5 focuses on the case of an IPM given by a single function \( g \) with respect to a reference measure \( \nu \), deriving the optimal bound in this case and discussing topological applications, and Section 6 extends this to arbitrary IPMs and sets of measures, with applications to subgaussian functions and Vajda’s problem.
2 Related work

The question studied in the present paper is an instance of the broader problem of the con-
strained minimization of a $\phi$-divergence, which has been extensively studied in works spanning
information theory, statistics and convex analysis.

Kullback–Leibler divergence. The problem of minimizing the Kullback–Leibler divergence
[KL51] subject to a convex constraint can be traced back at least to [San57] in the context of large
deviation theory and to [Kul59] for the purpose of formulating an information theoretic approach
to statistics. In information theory, this problem is known as an $I$-projection [Csi75, CM03]. The
case where the convex set is defined by finitely many affine equality constraints, which is closest
to our work, was specifically studied in [BC77, BC79] via a convex duality approach. This special
case is of particular relevance to the field of statistics, since the exponential family arises as the
optimizer of this problem.

Convex integral functionals and general $\phi$. With the advent of the theory of convex integral
functionals, initiated in convex analysis by [Roc66, Roc68], the problem is generalized to arbitrary
$\phi$-divergences, sometimes referred to as $\phi$-entropies, especially when seen as functionals over
spaces of functions, and increasingly studied via a systematic application of convex duality
[TV93]. In the case of affine constraints, the main technical challenge is to identify constraint
qualifications guaranteeing that strong duality holds: [BL91, BL93, BK06] investigate the notion
of quasi-relative interior for this purpose, and [Léo01a, Léo01b] consider integrability conditions
on the functions defining the affine constraints. A comprehensive account of this case can be
found in [CM12]. We also note the work [AS06], which shows a duality between approximate
divergence minimization—where the affine constraints are only required to hold up to a certain
accuracy—and maximum a posteriori estimation in statistics.

At a high level, in our work we show in Section 6 that one can essentially reduce the problem
of minimizing the divergence on probability measures subject to a constraint on an IPM to the
problem of minimizing the divergence on finite measures subject to two affine constraints: the
first restricting to probability measures, and the second constraining the mean deviation of a
single function in the class defining the IPM. For the restriction to probability measures, we
prove that constraint qualification always holds, a fact which was not observed in the aforesaid
works, to the best of our knowledge. For the second constraint, we show in Section 5.3 that
by focusing on a single function, we can relate strong duality of the minimization problem to
compactness properties of the divergence. In particular, we obtain strong duality under similar
assumptions as those considered in [Léo01a], even when the usual interiority conditions for
constraint qualification do not hold.

Relationship between $\phi$-divergences. A specific case of the minimization question which
has seen significant work is when the feasible set is defined by other $\phi$-divergences, and most
notably is a level set the total variation distance. The best-known result in this line is Pinsker’s
inequality, first proved in a weaker form in [Pin60, Pin64] and then strengthened independently
in [Kul67, Kem69, Csi67b], which gives the best possible quadratic lower bound on the Kullback–
Leibler divergence by the total variation distance. More recently, for $\phi$-divergences other than
the Kullback–Leibler divergence, [Gil10] identified conditions on \( \phi \) under which quadratic “Pinsker-type” lower bounds can be obtained.

More generally, the problem of finding the best lower bound of the Kullback–Leibler divergence as a (possibly non-quadratic) function of the total variation distance was introduced by Vajda in [Vaj70] and generalized to arbitrary \( \phi \)-divergences in [Vaj72], and is therefore sometimes referred to as Vajda’s problem. Approximations of the best lower bound were obtained in [BH79, Vaj70] for the Kullback–Leibler divergence and in [Vaj72, Gil08, Gil10] for \( \phi \)-divergences under various assumptions on \( \phi \). The optimal lower bound was derived in [FHT03] for the Kullback–Leibler divergence and in [Gil06] for any \( \phi \)-divergence. As an example application of Section 6, in Section 6.3 we rederive the optimal lower bound as well as its quadratic relaxations in a unified manner.

In [RW09, RW11], the authors consider the generalization of Vajda’s problem of obtaining a tight lower bound on an arbitrary \( \phi \)-divergence given multiple values of generalized total variation distances; their result contains [Gil06] as a special case. Beyond the total variation distance, [HV11] introduced the general question of studying the joint range of values taken by an arbitrary pair of \( \phi \)-divergences, which has its boundary given by the best lower bounds of one divergence as a function of the other. [GSS14] generalize this further and consider the general problem of understanding the joint range of multiple \( \phi \)-divergences, i.e. minimizing a \( \phi \)-divergence subject to a finite number of constraints on other \( \phi \)-divergences. A key conceptual contribution in this line of work is to show that these optimization problems, which are defined over (infinitely dimensional) spaces of measures, can be reduced to finite dimensional optimization problems. A related line of work [SV16, Sas18] deriving relations between \( \phi \)-divergences instead approaches the problem by defining integral representations of \( \phi \)-divergences in terms of simple ones.

Our work differs from results of this type since we are primarily concerned with IPMs other than the total variation distance, and in particular with those containing unbounded functions. It was shown in [KFG06, KFG07, SGF+09, SFG+12] that the class of \( \phi \)-divergences and the class of pseudometrics (including IPMs) intersect only at the total variation distance. As such, the problem studied in the present paper cannot be phrased as the one of a joint range between two \( \phi \)-divergences, and to the best of our knowledge cannot be handled by the techniques used in studying the joint range.

**Transport inequalities.** Starting with the work of Marton [Mar86], transportation inequalities upper bounding the Wasserstein distance by a function of the relative entropy have been instrumental in the study of the concentration of measure phenomenon (see e.g. [GL10] for a survey). These inequalities are related to the question studied in this work since the 1-Wasserstein distance is an IPM when the probability space is a Polish space and coincides with the total variation distance when the probability space is discrete and endowed with the discrete metric. In an influential paper, Bobkov and Götze [BG99] proved that upper bounding the 1-Wasserstein distance by a square root of the relative entropy is equivalent to upper bounding the log moment-generating function of all 1-Lipschitz functions by a quadratic function. The extension of Pinsker’s inequality in [BLM13, §4.10], which was inspired by [BG99], is also based on quadratic upper bounds of the log moment-generating function and we in turn follow similar ideas in Sections 4.3 and 5.1 of the present work.
3 Preliminaries

3.1 Measure Theory

**Notation.** Unless otherwise noted, all the probability measures in this paper are defined on a common measurable space \((\Omega, \mathcal{F})\), which we assume is non-trivial in the sense that \(\emptyset, \Omega \not\subseteq \mathcal{F}\), as otherwise all questions considered in this paper become trivial. We denote by \(M(\Omega, \mathcal{F})\), \(M^+(\Omega, \mathcal{F})\) and \(M^1(\Omega, \mathcal{F})\) the sets of finite signed measures, finite non-negative measures, and probability measures respectively. \(L^0(\Omega, \mathcal{F})\) denotes the space of all measurable functions from \(\Omega\) to \(\mathbb{R}\), and \(L^b(\Omega, \mathcal{F}) \subseteq L^0(\Omega, \mathcal{F})\) is the set of all bounded measurable functions. For \(\nu \in M(\Omega, \mathcal{F})\), and \(1 \leq p \leq \infty\), \(L^p(\nu, \Omega, \mathcal{F})\) denotes the space of measurable functions with finite \(p\)-norm with respect to \(\nu\), and \(L^0(\nu, \Omega, \mathcal{F})\) denotes the space obtained by taking the quotient with respect to the space of functions which are 0 \(\nu\)-almost everywhere. Similarly, \(L^0(\nu, \Omega, \mathcal{F})\) is the space of all measurable functions \(\Omega\) to \(\mathbb{R}\) up to equality \(\nu\)-almost everywhere. When there is no ambiguity, we drop the indication \((\Omega, \mathcal{F})\). For a measurable function \(f \in L^0\) and measure \(\nu \in M\), \(\nu(f) \triangleq \int f \, d\nu\) denotes the integral of \(f\) with respect to \(\nu\).

For two measures \(\mu\) and \(\nu\), \(\mu \ll \nu\) (resp. \(\mu \perp \nu\)) denotes that \(\mu\) is absolutely continuous (resp. singular) with respect to \(\nu\) and we define \(M_c(\nu) \triangleq \{\mu \in M \mid \mu \ll \nu\}\) and \(M_s(\nu) \triangleq \{\mu \in M \mid \mu \perp \nu\}\), so that by the Lebesgue decomposition theorem we have the direct sum \(M = M_c(\nu) \oplus M_s(\nu)\). For \(\mu \in M_c(\nu)\), \(\frac{d\mu}{d\nu} \in L^1(\nu)\) denotes the Radon–Nikodym derivative of \(\mu\) with respect to \(\nu\).

For a signed measure \(\nu \in M\), we write the Hahn–Jordan decomposition \(\nu = \nu^+ - \nu^-\) where \(\nu^+, \nu^- \in M^+\), and denote by \(|\nu| = \nu^++\nu^\neg\) the total variation measure.

More generally, given a \(\sigma\)-ideal \(\Sigma \subseteq \mathcal{F}\) we write \(\mu \ll \Sigma\) to express that \(|\mu|(A) = 0\) for all \(A \in \Sigma\) and define \(M_c(\Sigma) \triangleq \{\mu \in M \mid \mu \ll \Sigma\}\). Similarly, \(L^0(\Sigma)\) denotes the quotient of \(L^0\) by the space of functions equal to 0 except on an element of \(\Sigma\). For a measurable function \(f \in L^0\), and \(\sigma\)-ideal \(\Sigma\), \(\mathrm{ess \, im}_\Sigma(f) \triangleq \bigcap_{\varepsilon > 0} \{x \in \mathbb{R} \mid f^{-1}((x - \varepsilon, x + \varepsilon)) \not\subseteq \Sigma\}\) is the essential range of \(f\) with respect to \(\Sigma\), and \(\mathrm{ess \, sup}_\Sigma f \triangleq \sup \mathrm{ess \, im}_\Sigma(f)\) and \(\mathrm{ess \, inf}_\Sigma f \triangleq \inf \mathrm{ess \, im}_\Sigma(f)\) denote the \(\Sigma\)-essential supremum and infimum respectively. Finally \(L^\infty(\Sigma)\) denotes the space of a functions whose \(\Sigma\)-essential range is bounded, up to equality except on an element of \(\Sigma\). When \(\Sigma\) is the \(\sigma\)-ideal of null sets of a measure \(\nu\), we abuse notations and write \(\mathrm{ess \, im}_\nu(f)\) for \(\mathrm{ess \, im}_\Sigma(f)\) and similarly for the essential supremum and infimum.

Finally, for brevity, we define for a subspace \(X \subseteq M\) of finite signed measures the subsets \(X^+ \triangleq X \cap M^+\) and \(X^\neg \triangleq X \cap M^\neg\), and for \(\nu \in M\) we also define \(X_c(\nu) \triangleq X \cap M_c(\nu)\) and \(X_s(\nu) \triangleq X \cap M_s(\nu)\).

**Integral Probability Metrics.**

**Definition 3.1.1.** For a non-empty set of measurable functions \(\mathcal{G} \subseteq L^0\), the integral probability metric associated with \(\mathcal{G}\) is defined by

\[
d_{\mathcal{G}}(\mu, \nu) \triangleq \sup_{g \in \mathcal{G}} \left\{ \left| \int g \, d\mu - \int g \, d\nu \right| \right\},
\]

for all pairs of measures \((\mu, \nu) \in M^2\) such that all functions in \(\mathcal{G}\) are absolutely \(\mu\)- and \(\nu\)-integrable. We extend this definition to all pairs of measures \((\mu, \nu) \in M^2\) by \(d_{\mathcal{G}}(\mu, \nu) = +\infty\) in cases where there exists a function in \(\mathcal{G}\) which is not \(\mu\)- or \(\nu\)- integrable.
Remark 3.1.2. When the class $\mathcal{G}$ is closed under negation, one can drop the absolute value in the definition.

Example 3.1.3. The total variation distance $TV(\mu, \nu)$ is obtained when $\mathcal{G}$ is the class of measurable functions taking values in $[-1, 1]$.

Example 3.1.4. Note that the integrals $\int g \, d\mu$ and $\int g \, d\nu$ depend only on the pushforward measures $g_*\mu$ and $g_*\nu$ on $\mathbb{R}$. Equivalently, when $\mu$ and $\nu$ are the probability distributions of random variables $X$ and $Y$ taking values in $\Omega$, we have that $\int g \, d\mu = \int 1d\mu \circ g = \mathbb{E}[g(X)]$, the expectation of the random variable $g(X)$, and similarly $\int g \, d\nu = \mathbb{E}[g(Y)]$. The integral probability metric $d_\mathcal{G}$ thus defines the distance between random variables $X$ and $Y$ as the largest difference in expectation achievable by “observing” $X$ and $Y$ through a function from the class $\mathcal{G}$.

3.2 Convex analysis

Most of the convex functions considered in this paper will be defined over spaces of measures or functions. Consequently, we will apply tools from convex analysis in its general formulation for locally convex topological vector spaces. References on this subject include [BCR84] and [Bou87, II. and IV.§1] for the topological background, and [ET99, Part I] and [Zăl02, Chapters 1&2] for convex analysis. We now briefly review the main concepts appearing in the present paper.

Definition 3.2.1 (Dual pair). A dual pair is a triplet $(X, Y, \langle \cdot, \cdot \rangle)$ where $X$ and $Y$ are real vector spaces, and $\langle \cdot, \cdot \rangle : X \times Y \to \mathbb{R}$ is a bilinear form satisfying the following properties:

(i) for every $x \in X \setminus \{0\}$, there exists $y \in Y$ such that $\langle x, y \rangle \neq 0$.

(ii) for every $y \in Y \setminus \{0\}$, there exists $x \in X$ such that $\langle x, y \rangle \neq 0$.

We say that the pairing $\langle \cdot, \cdot \rangle$ puts $X$ and $Y$ in (separating) duality. Furthermore, a topology $\tau$ on $X$ is said to be compatible with the pairing if it is locally convex and if the topological dual $X^\ast$ of $X$ with respect to $\tau$ is isomorphic to $Y$. Topologies on $Y$ compatible with the pairing are defined similarly.

Example 3.2.2. For an arbitrary dual pair $(X, Y, \langle \cdot, \cdot \rangle)$, the weak topology $\sigma(X, Y)$ induced by $Y$ on $X$ is defined to be the coarsest topology such that for each $y \in Y$, $x \mapsto \langle x, y \rangle$ is a continuous linear form on $X$. It is a locally convex Hausdorff topology induced by the family of seminorms $p_y : x \mapsto |\langle x, y \rangle|$ for $y \in Y$ and is thereby compatible with the duality between $X$ and $Y$.

Note that in finite dimension, all Hausdorff vector space topologies coincide with the standard topology.

In the remainder of this section, we fix a dual pair $(X, Y, \langle \cdot, \cdot \rangle)$ and endow $X$ and $Y$ with topologies compatible with the pairing. As is customary in convex analysis, convex functions take values in the set of extended reals $\overline{\mathbb{R}} \equiv \mathbb{R} \cup \{+\infty, -\infty\}$ to which the addition over $\mathbb{R}$ is extended using the usual conventions, including $(+\infty) + (-\infty) = +\infty$. In this manner, convex functions can always be extended to be defined on the entirety of their domain by assuming the value $+\infty$ when they are not defined. For a convex function $f : X \to \overline{\mathbb{R}}$, $\text{dom } f \equiv \{x \in X | \}$

Note that total variation distance is sometimes defined as half of this quantity, corresponding to functions taking values in $[0, 1]$. 3
f(x) < +\infty\) is the effective domain of \(f\) and \(\partial f(x) \equiv \{y \in Y \mid \forall x' \in X, f(x') \geq f(x) + (x' - x, y)\}\) denotes its subdifferential at \(x \in X\).

**Definition 3.2.3** (Lower semicontinuity, inf-compactness). The function \(f : X \to \overline{\mathbb{R}}\) is lower semicontinuous (lsc) (resp. inf-compact) if for every \(t \in \mathbb{R}\) the sublevel set \(f^{-1}(-\infty, t] \equiv \{x \in X \mid f(x) \leq t\}\) is closed (resp. compact).

**Lemma 3.2.4.** If \(f : X \times C \to \overline{\mathbb{R}}\) is a convex function for \(C\) a convex subset of some linear space, then \(g : X \to \overline{\mathbb{R}}\) defined as \(g(x) \equiv \inf_{c \in C} f(x, c)\) is convex. Furthermore, if for some topology on \(C\) the function \(f\) is inf-compact with respect to the product topology, then \(g\) is also inf-compact.

**Definition 3.2.5** (Properness). A convex function \(f : X \to \overline{\mathbb{R}}\) is proper if \(\text{dom } f \neq \emptyset\) and \(f(x) > -\infty\) for all \(x \in X\).

**Definition 3.2.6** (Convex conjugate). The convex conjugate (also called Fenchel dual or Fenchel–Legendre transform) of \(f : X \to \overline{\mathbb{R}}\) is the function \(f^* : Y \to \overline{\mathbb{R}}\) defined for \(y \in Y\) by

\[
f^*(y) \equiv \sup_{x \in X} \{(x, y) - f(x)\}.
\]

For a set \(C \subseteq X\), \(\delta_C : X \to \overline{\mathbb{R}}_{\geq 0}\) denotes the characteristic function of \(C\), that is \(\delta_C(x) = 0\) if \(x \in C\) and \(+\infty\) elsewhere. The support function of \(C\) is \(h_C : Y \to \overline{\mathbb{R}}\) defined by \(h_C(y) = \sup_{x \in C} \langle x, y \rangle\). If \(C\) is closed and convex then \((\delta_C, h_C)\) form a pair of convex conjugate functions.

**Proposition 3.2.7.** Let \(f : X \to \overline{\mathbb{R}}\) be a function. Then:

1. \(f^* : Y \to \overline{\mathbb{R}}\) is convex and lower semicontinuous.
2. for all \(x \in X\) and \(y \in Y\), \(f(x) + f^*(y) \geq \langle x, y \rangle\) with equality iff \(y \in \partial f(x)\).
3. \(f^{**}\) is proper convex lower semicontinuous, \(f \equiv +\infty\) or \(f \equiv -\infty\).
4. if \(f \leq g\) for some \(g : X \to \overline{\mathbb{R}}\), then \(g^* \geq f^*\).

**Remark 3.2.8.** In Proposition 3.2.7, Item 2 is known as the Fenchel–Young inequality and Item 3 as the Fenchel–Moreau theorem.

In the special case of \(X = \mathbb{R} = Y\) and a proper convex function \(f : \mathbb{R} \to \overline{\mathbb{R}}\), we can be more explicit about some properties of \(f^*\) and \(f^{**}\).

**Lemma 3.2.9.** If \(f : \mathbb{R} \to \overline{\mathbb{R}}\) is a proper convex function, then \(x \in \mathbb{R}\) is such that \(f(x) \neq f^{**}(x)\) only if \(\text{dom } f\) has non-empty interior and \(x\) is one of the (at most two) points on its boundary, in which case \(f^{**}(x)\) is the limit of \(f(x')\) as \(x' \to x\) within \(\text{dom } f\).

**Definition 3.2.10.** For \(f : \mathbb{R} \to \overline{\mathbb{R}}\) a proper convex function, we define for \(\ell \in \{-\infty, +\infty\}\) the quantity \(f'(\ell) \equiv \lim_{x \to \ell} f(x)/x \in \mathbb{R} \cup \{+\infty\}\).

**Remark 3.2.11.** The limit is always well-defined in \(\mathbb{R} \cup \{+\infty\}\) for proper convex functions. The name \(f'(\ell)\) is motivated by the fact that when \(f\) is differentiable, we have \(f'(\ell) = \lim_{x \to \ell} f'(x)\).

**Lemma 3.2.12.** If \(f : \mathbb{R} \to \overline{\mathbb{R}}\) is a proper convex function, then the domain of \(f^* : \mathbb{R} \to \overline{\mathbb{R}}\) satisfies \(\text{int}(\text{dom } f^*) = (f'(-\infty), f'(+\infty))\).
Lemma 3.2.13. Let \((f_i)_{i \in I}\) be a collection of convex functions from \(\mathbb{R}\) to \(\mathbb{R}\) which are non-decreasing over some convex set \(C \subseteq \mathbb{R}\). Then for all \(x \in \text{int} C\)

\[
\lim_{x' \to x^-} \inf_{i \in I} f_i(x') \leq \inf_{i \in I} f_i^*(x) \leq \inf_{i \in I} f_i(x).
\]

Proof. For each \(i \in I\) we have by Lemma 3.2.9 that \(f_i^*(x) \in \{f_i(x), \lim_{x' \to x^-} f_i(x')\}\), so since \(f_i\) is non-decreasing over \(C\) and \(f_i^* \leq f_i\) by Proposition 3.2.7, the result follows by taking the infimum over \(i \in I\) as \(\lim_{x' \to x^-} \inf_{i \in I} f_i(x') \leq \inf_{i \in I} \lim_{x' \to x^-} f_i(x').\)

Fenchel duality theorem is arguably the most fundamental result in convex analysis, and we will use it in this paper to compute the convex conjugate and minimum of a convex function subject to a linear constraint. The following proposition summarizes the conclusions obtained by instantiating the duality theorem to this specific case.

Proposition 3.2.14. Let \(f : X \to (-\infty, +\infty]\) be a convex function. For \(y \in Y\) and \(\varepsilon \in \mathbb{R}\), define \(f_{y,\varepsilon} : X \to (-\infty, +\infty]\) by

\[
f_{y,\varepsilon}(x) \equiv f(x) + \delta_{\{\varepsilon\}}((x,y)) = \begin{cases} f(x) & \text{if } (x,y) = \varepsilon \\ +\infty & \text{otherwise} \end{cases}
\]

for all \(x \in X\).

1. Assume that \(f\) is lower semicontinuous and define \(\langle \text{dom } f, y \rangle \equiv \{(x,y) \mid x \in \text{dom } f\}\). If \(\varepsilon \in \text{int}(\langle \text{dom } f, y \rangle)\), then \(f_{y,\varepsilon}^*(x^*) = \inf_{\lambda \in \mathbb{R}} f^*(x^* + \lambda y) - \lambda \cdot \varepsilon\) for all \(x^* \in Y\), where the infimum is reached whenever \(f_{y,\varepsilon}^*(x^*)\) is finite.

2. Assume that \(f\) is non-negative and satisfies \(f(0) = 0\). Define the marginal value function

\[
\mathcal{L}_{y,f}(\varepsilon) \equiv \inf_{x \in X} f_{y,\varepsilon}(x) = \inf\{f(x) \mid x \in X \wedge (x,y) = \varepsilon\}. \quad (4)
\]

Then \(\mathcal{L}_{y,f}\) is a non-negative convex function satisfying \(\mathcal{L}_{y,f}(0) = 0\) and its convex conjugate is given by \(\mathcal{L}_{y,f}^*(t) = f^*(ty)\). Furthermore, \(\mathcal{L}_{y,f}\) is lower semicontinuous at \(\varepsilon\), that is \(\mathcal{L}_{y,f}(\varepsilon) = \mathcal{L}_{y,f}^*(\varepsilon)\), if and only if strong duality holds for problem (4), i.e. if and only if

\[
\inf\{f(x) \mid x \in X \wedge (x,y) = \varepsilon\} = \sup\{t \cdot \varepsilon - f^*(t \cdot y) \mid t \in \mathbb{R}\}.
\]

Proof. 1. This follows from a direct application of Fenchel’s duality theorem (see e.g. [Zăl02, Corollary 2.6.4, Theorem 2.8.1]).

2. Define the perturbation function \(F : X \times \mathbb{R} \to \mathbb{R}\) by \(F(x, \varepsilon) \equiv f_{y,\varepsilon}(x) = f(x) + \delta_{\{0\}}((x,y) - \varepsilon)\) so that \(\mathcal{L}_{y,f}(\varepsilon) = \inf_{x \in X} F(x, \varepsilon)\). Since \(F\) is non-negative, jointly convex over the convex set \(X \times \mathbb{R}\) and \(F(0,0) = 0\), we get that \(\mathcal{L}_{y,f}\) is itself convex, non-negative, and satisfies \(\mathcal{L}_{y,f}(0) = 0\). Furthermore, \(F^*(x^*, t) = f^*(x^* + ty)\) and \(\mathcal{L}_{y,f}^*(t) = F^*(0, t) = f^*(ty)\) by e.g. [Zăl02, Theorem 2.6.1, Corollary 2.6.4]. □
Finally, we will use the following result giving a sufficient condition for a convex function to be bounded below. Most such results in convex analysis assume that the function is either lower semicontinuous or bounded above on an open set. In contrast, the following lemma assumes that the function is upper bounded on a closed, convex, bounded set of a Banach space, or more generally on a cs-compact subset of a real Hausdorff topological vector space.

**Lemma 3.2.15** (cf. [Kön86, Example 1.6(0), Remark 1.9]). Let C be a cs-compact subset of a real Hausdorff topological vector space. If \( f : C \to \mathbb{R} \) is a convex function such that \( \sup_{x \in C} f(x) < +\infty \), then \( \inf_{x \in C} f(x) > -\infty \). In particular, if \( f : C \to \mathbb{R} \) is linear, then \( \sup_{x \in C} f(x) < +\infty \) if and only if \( \inf_{x \in C} f(x) > -\infty \).

The notion of cs-compactness (called \( \sigma \)-convexity in [Kön86]) was introduced and defined by Jameson in [Jam72], and Proposition 2 of the same paper states that closed, convex, bounded sets of Banach spaces are cs-compact. For completeness, we include a proof of Lemma 3.2.15 in Appendix A.1.

### 3.3 Orlicz spaces

We will use elementary facts from the theory of Orlicz spaces which we now briefly review (see for example [Léo07] for a concise exposition or [RR91] for a more complete reference). A function \( \theta : \mathbb{R} \to [0, +\infty] \) is a Young function if it is a convex, lower semicontinuous, and even function with \( \theta(0) = 0 \) and \( 0 < \theta(s) < +\infty \) for some \( s > 0 \). Then writing \( I_{\theta, \nu} : f \mapsto \int \theta(f) \, d\nu \) for \( \nu \in \mathcal{M} \), one defines two spaces associated with \( \theta \):

- the Orlicz space \( L^\theta(\nu) \equiv \{ f \in L^0(\nu) \mid \exists \alpha > 0, I_{\theta, \nu}(\alpha f) < \infty \} \),
- the Orlicz heart \( L^\theta_0(\nu) \equiv \{ f \in L^0(\nu) \mid \forall \alpha > 0, I_{\theta, \nu}(\alpha f) < \infty \} \), also known as the Morse–Transue space [MT50],

which are both Banach spaces when equipped with the Luxemburg norm \( \| f \|_{\theta} \equiv \inf\{ t > 0 \mid I_{\theta, \nu}(f/t) \leq 1 \} \). Furthermore, \( L^\theta_0(\nu) \subseteq L^\phi(\nu) \subseteq L^1(\nu) \) and \( L^\infty(\nu) \subseteq L^\phi(\nu) \) for all \( \theta \), and \( L^\infty(\nu) \subseteq L^\phi_0(\nu) \) when \( \operatorname{dom} \theta = \mathbb{R} \). If \( \theta^* \) is the convex conjugate of \( \theta \), we have the following analogue of Hölder’s inequality: \( \int f_1 f_2 \, d\nu \leq 2\| f_1 \|_{\theta} \| f_2 \|_{\theta^*} \), for all \( f_1 \in L^\phi(\nu) \) and \( f_2 \in L^{\phi^*}(\nu) \), implying that \((L^\phi, L^{\phi^*})\) are in dual pairing. Furthermore, if \( \operatorname{dom} \theta = \mathbb{R} \), we have that the dual Banach space \((L^\phi, \| \cdot \|_{\theta})^* \) is isomorphic to \((L^{\phi^*}, \| \cdot \|_{\theta^*})^* \).

### 4 Variational representations of \( \phi \)-divergences

In the rest of this paper, we fix a convex and lower semicontinuous function \( \phi : \mathbb{R} \to \mathbb{R} \cup \{+\infty\} \) such that \( \phi(1) = 0 \). After defining \( \phi \)-divergences in Section 4.1, we start with the usual variational representation of the \( \phi \)-divergence in Section 4.2, which we then strengthen in the case of probability measures in Section 4.3. A reader interested primarily in optimal bounds between \( \phi \)-divergences and IPMs can skip Sections 4.2 and 4.3 at a first reading.

\footnote{The definition and theory of Orlicz spaces holds more generally for \( \sigma \)-finite measures. The case of finite measures already covers all the applications considered in this paper whose focus is primarily on probability measures.}
4.1 Convex integral functionals and $\phi$-divergences

The notion of a $\phi$-divergence is closely related to the one of a convex integral functional that we define first.

**Definition 4.1.1** (Integral functional). For $\nu \in \mathcal{M}^+$ and $f : \mathbb{R} \to \mathbb{R} \cup \{\infty\}$ a proper convex function, the convex integral functional associated with $f$ and $\nu$ is the function $I_{f,\nu} : L^1(\nu) \to \mathbb{R} \cup \{\infty\}$ defined for $g \in L^1(\nu)$ by

$$I_{f,\nu}(g) = \int f \circ g \, d\nu.$$

The systematic study of convex integral functionals from the perspective of convex analysis was initiated by Rockafellar in [Roc68, Roc71], who considered more generally functionals of the form $g \mapsto \int f(\omega, g(\omega)) \, d\nu$ for $g : \Omega \to \mathbb{R}^n$ and $f : \Omega \times \mathbb{R}^n \to \mathbb{R}$ such that $f(\omega, \cdot)$ is convex $\nu$-almost everywhere. A good introduction to the theory of such functionals can be found in [Roc76, RW98a]. The specific case of Definition 4.1.1 is known as an *autonomous* integral functional, but we drop this qualifier since it applies to all functionals studied in this paper.

**Definition 4.1.2** ($\phi$-divergence). For $\mu \in \mathcal{M}$ and $\nu \in \mathcal{M}^+$, write $\mu = \mu_c + \mu_\perp$ with $\mu_c \ll \nu$ and $\mu \perp \nu$, the Lebesgue decomposition of $\mu$ with respect to $\nu$, and $\mu_\perp = \mu_\perp^+ - \mu_\perp^-$ with $\mu_\perp^+, \mu_\perp^- \in \mathcal{M}^+$, the Hahn–Jordan decomposition of $\mu_\perp$. The $\phi$-divergence of $\mu$ with respect to $\nu$ is the quantity $D_\phi(\mu \parallel \nu) \in \mathbb{R} \cup \{\infty\}$ defined by

$$D_\phi(\mu \parallel \nu) \overset{\Delta}{=} \int \phi\left(\frac{d\mu_c}{d\nu}\right) \, d\nu + \mu_\perp^+(\Omega) \cdot \phi'(\infty) - \mu_\perp^-(\Omega) \cdot \phi'(-\infty),$$

with the convention $0 \cdot (\pm \infty) = 0$.

**Remark 4.1.3.** An equivalent definition of $D_\phi(\mu \parallel \nu)$ which does not require decomposing $\mu$ is obtained by choosing $\lambda \in \mathcal{M}^+$ dominating both $\mu$ and $\nu$ (e.g. $\lambda = |\mu| + \nu$) and defining

$$D_\phi(\mu \parallel \nu) = \int \frac{d\nu}{d\lambda} \cdot \phi\left(\frac{d\mu}{d\lambda} \cdot \frac{d\nu}{d\lambda}\right) \, d\lambda,$$

with the conventions coming from continuous extension that $0 \cdot \phi(a/0) = a \cdot \phi'(\infty)$ if $a \geq 0$ and $0 \cdot \phi(a/0) = a \cdot \phi'(-\infty)$ if $a \leq 0$ (see Definition 3.2.10). It is easy to check that this definition does not depend on the choice of $\lambda$ and coincides with Definition 4.1.2.

The notion of $\phi$-divergence between probability measures was introduced by Csiszár in [Csi63, Csi67b] in information theory and independently by Ali and Silvey [AS66] in statistics. The generalization to finite signed measures is from [CGG99]. Some useful properties of the $\phi$-divergence include: it is jointly convex in both its arguments, if $\mu(\Omega) = \nu(\Omega)$ then $D_\phi(\mu \parallel \nu) \geq 0$, with equality if and only if $\mu = \nu$ assuming that $\phi$ is strictly convex at 1.

**Remark 4.1.4.** If $\mu \ll \nu$, the definition simplifies to $D_\phi(\mu \parallel \nu) = \nu\left(\phi \circ \frac{d\mu}{d\nu}\right)$. Furthermore, if $\phi'\pm\infty = \pm\infty$, then $D_\phi(\mu \parallel \nu) = +\infty$ whenever $\mu \ll \nu$. When either $\phi'(+\infty)$ or $\phi'(-\infty)$ is finite, some authors implicitly or explicitly redefine $D_\phi(\mu \parallel \nu)$ to be $+\infty$ whenever $\mu \ll \nu$, thus departing from Definition 4.1.2. This effectively defines $D_\phi(\cdot \parallel \nu)$ as the integral functional $I_{\phi,\nu}$
and the rich theory of convex integral functionals can be readily applied. As we will see in this paper, this change of definition is unnecessary and the difficulties arising from the case $\mu \not\ll \nu$ in Definition 4.1.2 can be addressed by separately treating the component of $\nu$ singular with respect to $\nu$.

An important reason to prefer the general definition is the equality $D_\phi(\nu \| \mu) = D_{\phi^\dagger}(\mu \| \nu)$ where $\phi^\dagger : x \mapsto x\phi(1/x)$ is the Csiszár dual of $\phi$, which identifies the reverse $\phi$-divergence—where the arguments are swapped—with the divergence associated with $\phi^\dagger$. Consequently, any result obtained for the partial function $\mu \mapsto D_\phi(\mu \| \nu)$ can be translated into results for the partial function $\nu \mapsto D_{\phi^\dagger}(\mu \| \nu)$ by swapping the role of $\mu$ and $\nu$ and replacing $\phi$ with $\phi^\dagger$. Note that $(\phi^\dagger)'(\infty) = \lim_{x \to 0^+} \phi(x)$ and $(\phi^\dagger)'(-\infty) = \lim_{x \to 0^+} \phi(x)$, and for many divergences of interest (including the Kullback–Leibler divergence) at least one of $\phi'(\infty)$ and $\phi(0)$ is finite. See Table 1 for some examples.

### 4.2 Variational representations: general measures

In this section, we fix a finite and non-negative measure $\nu \in M^+ \setminus \{0\}$ and study the convex functional $D_{\phi,\nu} : \mu \mapsto D_\phi(\mu \| \nu)$ over a vector space $X$ of finite measures containing $\nu$. Our primary goal is to derive a variational representation of $D_{\phi,\nu}$, expressing it as the solution of an optimization problem over $Y$, a vector space of functions put in dual pairing with $X$ via $\langle \mu, h \rangle = \mu(h)$, for a measure $\mu \in X$ and a function $h \in Y$.

Care must be taken in specifying the dual pair $(X, Y)$, since the variational representation we obtain depends on it, or more precisely, on the null $\sigma$-ideal $\Xi$ of $(\Omega, \mathcal{F})$ consisting of the measurable sets that are null for all measures in $X$. Note that, as discussed in Remark 4.1.4, this ideal $\Xi$ is irrelevant when $\phi'(\pm \infty) = \pm \infty$ (e.g., when $D_\phi$ is the KL divergence), since then $D_\phi(\mu \| \nu) = +\infty$ whenever $\mu \not\ll \nu$, but when, $\phi'(\pm \infty)$ or $\phi'(\mp \infty)$ is finite, it is possible to have

| Name                    | $\phi$                          | $\phi'(\infty) < \infty$? | $\phi(0) < \infty$? | Notes                                      |
|-------------------------|---------------------------------|----------------------------|----------------------|--------------------------------------------|
| $\alpha$-divergences    | $\frac{x^{\alpha}-1}{\alpha(\alpha-1)}$ | when $\alpha < 1$         | when $\alpha > 0$    | $\phi^\dagger = \phi_{1-\alpha}$         |
| KL                     | $x \log x$                      | No                         | Yes                  | Limit of $\alpha \to 1^-$                 |
| reverse KL              | $- \log x$                      | Yes                        | No                   | Limit of $\alpha \to 0^+$                 |
| squared Hellinger      | $(\sqrt{x} - 1)^2$             | Yes                        | Yes                  | Scaling of $\alpha = \frac{1}{2}$         |
| $\chi^2$-divergence    | $(x - 1)^2$                     | No                         | Yes                  | Scaling of $\alpha = 2$                   |
| Jeffreys                | $(x - 1)\log x$                 | No                         | No                   | KL + reverse KL                           |
| $\chi^a$-divergences   | $|x - 1|^a$                     | when $\alpha = 1$         | Yes                  | For $\alpha \geq 1$ [Vaj73]               |
| Total variation        | $|x - 1|$                       | Yes                        | Yes                  | $\chi^1$-divergence                       |
| Jensen–Shannon          | $x \log x - (1 + x)\log \left(1 + \frac{1}{x} \right)$ | Yes                      | Yes                  | a.k.a. total divergence to the average    |
| Triangular discrimination | $\frac{(x-1)^2}{x+1}$           | Yes                        | Yes                  | a.k.a. Vincze–Le Cam distance             |

Table 1: Common $\phi$-divergences (see e.g. [SV16])
\[D_\phi(\mu \mid \nu) < \infty\] even when \(\mu \not\ll \nu\), and we wish to obtain a variational representation for such discontinuous measures as well. Denoting by \(N\) the \(\sigma\)-ideal of \(\nu\)-null sets, we always have \(\Xi \subseteq N\) since we assume that \(\nu \in X\). If \(\Xi = N\), then we have \(X \subseteq M_c(\nu)\), corresponding to case of only absolutely continuous measures, but if \(\Xi \subset N\) is a proper subset of \(N\) then \(N \setminus \Xi\) quantifies the “amount of \(\nu\)-singularities” of measures in \(X\). The extreme case where \(\Xi = \{\emptyset\}\) allows for arbitrary singularities, since this implies that for any measurable set \(A \in \mathcal{F}\), there exists a measure in \(X\) with positive variation on \(A\). Furthermore, for common measurable spaces \(\Omega\), there is usually an ambient measure \(\lambda\) for which it is natural to assume that \(X \subseteq M_c(\lambda)\) (e.g. \(\lambda\) could be the Lebesgue measure on \(\mathbb{R}\) or more generally the Haar measure on a locally compact unimodular group). Denoting by \(L\) the null \(\sigma\)-ideal of this ambient measure, we could then take \(L \subseteq \Xi\), thus restricting the singularities of measures in \(X\).

Formally, we require that the pair \((X, Y)\) satisfies a decomposability condition that we define next. It is closely related to Rockafellar’s notion of a decomposable space [Roc76, Section 3] which plays an important role in the theory of convex integral functionals.

**Definition 4.2.1** (Decomposability). Let \(X \subseteq M(\Omega, \mathcal{F})\) be a vector space of finite measures and define \(\Xi \triangleq \{A \in \mathcal{F} \mid \forall \mu \in X, \ |\mu|(A) = 0\}\) the \(\sigma\)-ideal of measurable sets that are null for all measures in \(X\). Let \(Y\) be a vector space of measurable functions and let \(\nu \in X\) be a finite non-negative measure. We say that the pair \((X, Y)\) is \(\nu\)-decomposable if:

1. the pairing \((\mu, h) \mapsto \int h \, d\mu\) puts \(X\) and \(Y\) in separating duality.
2. \(\left\{ \mu \in M_c(\nu) \bigg| \frac{d\mu}{d\nu} \in L^\infty(\nu) \right\} \subseteq X \) and \(L^\infty(\Xi) \subseteq Y \subseteq L^0(\Xi)\).
3. for all \(A \not\in \Xi\), there exists \(\mu \in X^+ \setminus \{0\}\) such that \(\mu(\Omega \setminus A) = 0\).

**Remark 4.2.2.** Note that items 2 and 3 together imply that the duality is necessarily separating, so the definition would remain identical by only requiring in item 1 that \(\mu(h)\) be finite for each \(\mu \in X\) and \(h \in Y\). Furthermore, if we strengthen condition 2 by requiring that \(\{ \mu \in M_c(\mu') \mid \frac{d\mu}{d\mu'} \in L^\infty(\mu') \} \subseteq X\) for all measures \(\mu' \in X\), then 3 is implied. Thus, starting from an arbitrary dual pair \((X, Y)\) in separating duality, one can extend \(X\) by taking its sum with the space of all measures of bounded derivative with respect to measures in \(X\) and extend \(Y\) by taking its sum with \(L^\infty(\Xi)\). The resulting pair of extended spaces will then be decomposable with respect to any measure in \(X\).

**Example 4.2.3.** If \(X \subseteq M_c(\nu)\), then item 2 implies item 3, and \(\nu\)-decomposability then simply expresses that \(X\) and \(Y\) form a dual pair of decomposable spaces in the sense of [Roc76, Section 3], once \(M_c(\nu)\) is identified with \(L^1(\nu)\) via the Radon–Nikodym theorem. An example of a \(\nu\)-decomposable pair in this case is given by \((M_c(\nu), L^\infty(\nu))\). More generally, if \(\Xi\) is a proper subset of the \(\sigma\)-ideal of \(\nu\)-null sets, then item 3 requires \(X\) to contain “sufficiently many” \(\nu\)-singular measures. An example of a \(\nu\)-decomposable pair for which \(\Xi = \{\emptyset\}\) is given by \(X = M\) and \(Y = L^b(\Omega)\). An intermediate example which will be useful when considering IPMs can be obtained by constructing the largest dual pair \((X, Y)\) such that \(Y\) contains a class of functions \(\mathcal{G}\) of interest. The details of the construction are given in Definition 5.1.12 and decomposability is stated and proved in Lemma 5.1.14.
With Definition 4.2.1 at hand, our approach to obtain variational representations of the divergence is simple. We first compute the convex conjugate \( D^*_{\phi, \nu} \) of \( D_{\phi, \nu} \) defined for \( h \in Y \) by

\[
D^*_{\phi, \nu}(h) = \sup_{\mu \in \mathcal{X}} \{ \mu(h) - D_{\phi, \nu}(\mu) \} \tag{5}
\]

and prove that \( D_{\phi, \nu} \) is lower semicontinuous. By the Fenchel–Moreau theorem, we thus obtain the representation \( D_{\phi, \nu}(\mu) = D^*_{\phi, \nu}(\mu) = \sup_{h \in \mathcal{Y}} \{ \mu(h) - D^*_{\phi, \nu}(h) \} \).

We start with the simplest case where \( X \subseteq \mathcal{M}_c(\nu) \), that is when all the measures in \( X \) are \( \nu \)-absolutely continuous. Since \( D_{\phi, \nu} \) coincides with the integral functional \( I_{\phi, \nu} \) in this case, this lets us exploit the well-known fact that under our decomposability condition, \( (I_{\phi, \nu}, I_{\phi^*, \nu}) \) form a pair of convex conjugate functionals. This fact was first observed in \([LZ56]\) in the context of Orlicz spaces, and then generalized in \([Roc68, Roc71]\).

**Proposition 4.2.4.** Let \( \nu \in \mathcal{M}^+ \) be non-negative and finite, and let \( (X, Y) \) be \( \nu \)-decomposable with \( X \subseteq \mathcal{M}_c(\nu) \). Then the convex conjugate \( D^*_{\phi, \nu} \) of \( D_{\phi, \nu} \) over \( X \) is given for all \( h \in Y \) by

\[
D^*_{\phi, \nu}(h) = I_{\phi^*, \nu}(h) = \int \phi^* \circ h \, d\nu.
\]

Furthermore \( D_{\phi, \nu} \) is lower semicontinuous, therefore for all \( \mu \in X \)

\[
D_{\phi}(\mu \parallel \nu) = \sup_{h \in \mathcal{Y}} \left\{ \int h \, d\mu - \int \phi^* \circ h \, d\nu \right\}. \tag{6}
\]

**Proof.** Since \( \nu \in X \) by assumption, the function \( D_{\phi, \nu} \) is proper and convex over \( X \). The proposition is then immediate consequence of \([Roc76, Theorem 3C]\) after identifying \( \mathcal{M}_c(\nu) \) with \( L^1(\nu) \) by the Radon–Nikodym theorem and noting that \( X \) and \( Y \) are decomposable \([Roc76, Section 3]\) by Definition 4.2.1. \( \square \)

**Example 4.2.5.** Consider the case of the Kullback–Leibler divergence, corresponding to the function \( \phi : x \mapsto x \log x \). A simple computation gives \( \phi^*(x) = e^{x-1} \) and (6) yields as a variational representation, for all \( \mu \in X \)

\[
D(\mu \parallel \nu) = \sup_{g \in \mathcal{Y}} \left\{ \mu(g) - \int e^{g-1} \, d\nu \right\}. \tag{7}
\]

Note that this representation differs from the Donsker–Varadhan representation (1) discussed in the introduction. This discrepancy will be explained in the next section.

The variational representation of the \( \phi \)-divergence in Proposition 4.2.4 is well-known (see e.g. \([RRGGP12]\)). However, as already discussed, the case where \( X \) contains \( \nu \)-singular measures is also of interest and has been comparatively less studied in the literature. The following proposition generalizes the expression for \( D^*_{\phi, \nu} \) obtained in Proposition 4.2.4 to the general case of an arbitrary \( \nu \)-decomposable pair \((X, Y)\), without requiring that \( X \subseteq \mathcal{M}_c(\nu) \).

**Proposition 4.2.6.** Let \( \nu \in \mathcal{M}^+ \) be non-negative and finite measure and assume that \((X, Y)\) is \( \nu \)-decomposable. Then, the functional \( D_{\phi, \nu} \) over \( X \) has convex conjugate \( D^*_{\phi, \nu} \) given for all \( g \in Y \) by

\[
D^*_{\phi, \nu}(h) = \begin{cases} 
I_{\phi^*, \nu}(h) & \text{if } \text{ess im}_\nu(h) \subseteq [\phi'(-\infty), \phi'(\infty)] \\
+\infty & \text{otherwise}
\end{cases} \tag{8}
\]

where \( \Xi \equiv \{ A \in \mathcal{F} \mid \forall \mu \in X, |\mu|(A) = 0 \} \) is the null \( \sigma \)-ideal of \( X \).
Proof. For \( h \in Y \), let \( C(h) \) be the right-hand side of Eq. (8), our claimed expression for \( D^*_\phi,\nu(h) \).

First, we show that \( \sup_{\mu \in X} \{ \mu(h) - D^*_\phi,\nu(\mu) \} \leq C(h) \). For this, we assume that \( \text{ess} \ \text{im}_\nu(h) \subseteq [\phi'(-\infty), \phi'(\infty)] \), as otherwise \( C(h) = +\infty \) and there is nothing to prove. For \( \mu \in X \), write \( \mu = \mu_c + \mu^+_\epsilon - \mu^-_\epsilon \) with \( \mu_c \in M_c(\nu) \) and \( \mu^+_\epsilon, \mu^-_\epsilon \in M^{\text{ess}}_\epsilon(\nu) \), so that

\[
\mu(h) - D^*_\phi,\nu(\mu) = \mu_c(h) - I_{\phi,\nu} \left( \frac{d\mu_c}{d\nu} \right) + \mu^+_\epsilon(h) - \mu^-_\epsilon(\Omega) \cdot \phi'(-\infty) - \mu^-_\epsilon(h) + \mu^-_\epsilon(\Omega) \cdot \phi'(\infty). \tag{9}
\]

Observe that \( \mu_c(h) - I_{\phi,\nu} \left( \frac{d\mu_c}{d\nu} \right) \leq \nu \left( \frac{d\mu_c}{d\nu} \cdot h - \phi \circ \frac{d\mu_c}{d\nu} \right) = \nu(\phi^* \circ h) = I_{\phi^*,\nu}(h) \), by the Fenchel–Young inequality applied to \( \phi \) and monotonicity of the integral with respect to the non-negative measure \( \nu \). Since \( \mu \ll \Xi \) by definition of \( \Xi \) and thus \( \mu^+_\epsilon \ll \Xi \), we have \( \phi'(\infty) \geq \text{ess} \sup_\Xi h \geq \text{ess} \sup_\Xi \mu^+_\epsilon \) so that \( \mu^+_\epsilon(h) - \mu^+_\epsilon(\Omega) \cdot \phi'(\infty) = \mu^+_\epsilon(h - \phi'(\infty)) \leq 0 \). Similarly \( \mu^-_\epsilon(\Omega) \cdot \phi'(-\infty) - \mu^-_\epsilon(h) \leq 0 \). Using these bounds in (9) yields \( \mu(h) - D^*_\phi,\nu(\mu) \leq C(h) \) as desired.

Next, we show that \( \sup_{\mu \in X} \{ \mu(h) - D^*_\phi,\nu(\mu) \} \geq C(h) \). Observe that

\[
\sup_{\mu \in X} \{ \mu(h) - D^*_\phi,\nu(\mu) \} \geq \sup_{\mu \in X(\nu)} \{ \mu(h) - D^*_\phi,\nu(\mu) \} = I_{\phi^*,\nu}(h), \tag{10}
\]

where the equality follows from Proposition 4.2.4 applied to \( X_\nu = X_c(\nu) \) and \( Y_\nu = Y / \sim_\nu \) where \( \sim_\nu \) is the equivalence relation of being equal \( \nu \)-almost everywhere. If \( \text{ess} \ \text{im}_\nu(h) \subseteq [\phi'(-\infty), \phi'(\infty)] \), then \( I_{\phi^*,\nu}(h) = C(h) \) and (10) gives the desired conclusion. If \( \text{ess} \sup_\Xi h > \phi'(\infty) \), let \( \alpha \in \mathbb{R} \) such that \( \phi'(\infty) < \alpha < \text{ess} \sup_\Xi h \). Then \( A = \{ \omega \in \Omega \mid h(\omega) > \alpha \} \) is a measurable set in \( \mathcal{F} \setminus \Xi \). Since \( \mu_A(\Omega \setminus A) = 0 \). But then

\[
\sup_{\mu \in X} \{ \mu(h) - D^*_\phi,\nu(\mu) \} \geq \sup_{c > 0} \{ \nu(h + c \mu_A) - D^*_\phi,\nu(h + c \mu_A) \} = \nu(h) + \sup_{c > 0} [c \mu_A(h) - c \mu_A(\Omega) \cdot \phi'(\infty)]
\]

\[
\geq \nu(h) + \sup_{c > 0} [c \mu_A(\Omega) \cdot (\alpha - \phi'(\infty))] = +\infty = C(h),
\]

where the first equality is because \( I_{\phi,\nu} \left( \frac{d\mu_A}{d\nu} \right) = \phi(1) = 0 \) and \( \mu_A \in X^+_\nu(\nu) \), and the second is because \( \mu_A(\Omega) > 0 \) and \( \alpha > \phi'(\infty) \). The case \( \text{ess} \inf_\Xi h(\Omega) < \phi'(\infty) \) is analogous.

Remark 4.2.7. Although the expression of \( D^*_\phi,\nu \) obtained in Proposition 4.2.6 should coincide with the one obtained in Proposition 4.2.4 when \( X \subseteq M_c(\nu) \) (in which case \( \Xi \) coincides with the \( \sigma \)-ideal of \( \nu \)-null sets), it appears different at first glance because of the explicit constraint on the \( \Xi \)-essential range of \( g \) present in (8). However, this constraint is also present, though implicit, in Proposition 4.2.4 since \( \text{dom} \phi^\bullet = [\phi'(-\infty), \phi'(\infty)] \) and thus \( I_{\phi^*,\nu}(h) = +\infty \) whenever \( \text{ess} \ \text{im}_\nu(h) \subseteq [\phi'(-\infty), \phi'(\infty)] \). When \( X \) is allowed to contain measures which are not absolutely continuous with respect to \( \nu \), this implicit constraint on the \( \nu \)-essential range is simply strengthened to restrict the \( \Xi \)-essential range instead. In the extreme case where \( \Xi = \{ \emptyset \} \) then the true range of \( h \) is constrained.

Finally, we prove that \( D^*_\phi,\nu \) is lower semicontinuous over \( X \), yielding a variational representation of \( D^*_\phi(\mu \parallel \nu) \) in the general case.
Proposition 4.2.8. Let $\nu \in M^+$ be a non-negative and finite measure and assume that $(X, Y)$ is $\nu$-decomposable. Then, $D_{\phi, \nu}$ is lower semicontinuous over $X$. Equivalently, we have for all $\mu \in X$ the biconjugate representation

$$D_{\phi}(\mu \| \nu) = \sup \{ \mu(g) - I_{\phi, \nu}(g) \mid g \in Y \land \essinf g(\Xi) \subseteq [\phi'(\infty), \phi'(\infty)] \},$$

where $\Xi = \{ A \in \mathcal{F} \mid \forall \mu \in X, |\mu|(A) = 0 \}$ is the null $\sigma$-ideal of $X$.

Proof. Since $D_{\phi, \nu}$ is proper, by the Fenchel–Moreau theorem it suffices to show that $D_{\phi, \nu}^{\ast \ast} \geq D_{\phi, \nu}$. For $\mu \in X$, write $\mu = \mu_c + \mu_c^+ - \mu_c^-$ with $\mu_c \in M_c(\nu)$, and $\mu_c^+, \mu_c^- \in M_+^+(\nu)$ by the Lebesgue and Hahn–Jordan decompositions. Furthermore, let $(C, P, N) \in \mathcal{F}^3$ be a partition of $\Omega$ such that $|\mu_c|(\Omega \setminus C) = \nu(\Omega \setminus C) = 0$, $\mu_c^+(\Omega \setminus P) = 0$ and $\mu_c^-(\Omega \setminus N) = 0$. By Proposition 4.2.6,

$$D_{\phi, \nu}^{\ast \ast}(\mu) = \sup \{ \mu(g) - I_{\phi, \nu}(g) + \mu_c^+(g) - \mu_c^-(g) \mid g \in Y \land \essinf g(\Xi) \subseteq [\phi'(\infty), \phi'(\infty)] \}. \quad (11)$$

Let $\alpha \in \mathbb{R}$ such that $\alpha < I_{\phi, \nu}(\frac{d\mu_c}{d\nu})$. Applying Proposition 4.2.4 with $X_\nu = M_c(\nu)$ and $Y_\nu = L^\infty(\nu)$, we get the existence of $g_\nu \in L^\infty(\nu)$ such that $\mu_c(g_\nu) - I_{\phi, \nu}(g_\nu) > \alpha$. Furthermore, since $\dom \phi^* \subseteq [\phi'(\infty), \phi'(\infty)]$, we have that $g_\nu \in [\phi'(\infty), \phi'(\infty)]$ $\nu$-almost everywhere. Consequently, there exists a representative $\tilde{g}_c \in L^1(\Omega)$ of $g_c$ such that $\tilde{g}_c(\Omega) \subseteq [\phi'(\infty), \phi'(\infty)]$.

For $\beta, \gamma \in \mathbb{R} \cap [\phi'(\infty), \phi'(\infty)]$ (which is nonempty since it contains $\dom \phi^*$ and $\phi$ is convex and proper), define $\tilde{g} : \Omega \to \mathbb{R}$ by

$$\tilde{g}(\omega) = \begin{cases} \tilde{g}_c(\omega) & \text{if } \omega \in C \\ \beta & \text{if } \omega \in P \\ \gamma & \text{if } \omega \in N \end{cases}.$$

By construction $\tilde{g} \in L^1(\Omega)$, hence its equivalence class $g$ in $L^\infty(\Xi)$ belongs to $Y$ by Definition 4.2.1. Furthermore, since $\mu \ll \Xi$ we have $\mu_c(g) - I_{\phi, \nu}(g) = \mu_c(\tilde{g}_c) - I_{\phi, \nu}(\tilde{g}_c) = \mu_c(g_c) - I_{\phi, \nu}(g_c) > \alpha$, $\mu_c^+(g) = \mu_c^+(\Omega) \cdot \beta$, and $\mu_c^-(g) = \mu_c^-(\Omega) \cdot \gamma$. Since $\tilde{g}(\Omega) \subseteq [\phi'(\infty), \phi'(\infty)]$ by construction, for this choice of $g \in Y$, the optimand in (11) is at least $\alpha + \mu_c^+(\Omega) \cdot \beta - \mu_c^-(\Omega) \cdot \gamma$. This concludes the proof since $\alpha, \beta, \gamma$ can be made arbitrarily close to $I_{\phi, \nu}(\frac{d\mu_c}{d\nu})$, $\phi'(\infty)$, and $\phi'(-\infty)$ respectively.

4.3 Variational representations: probability measures

When applied to probability measures, which are the main focus of this paper, the variational representations provided by Propositions 4.2.4 and 4.2.8 are loose. This fact was first explicitly mentioned in [RRGPP12], where the authors also suggested that tighter representations could be obtained by specializing the derivation to probability measures.

Specifically, given a dual pair $(X, Y)$ as in Section 4.2, we restrict $D_{\phi, \nu}$ to probability measures by defining $\tilde{D}_{\phi, \nu} : \mu \mapsto D_{\phi, \nu}(\mu) + \delta_M(\mu)$ for $\mu \in X$. For $g \in Y$ we get

$$\tilde{D}_{\phi, \nu}^*(g) = \sup_{\mu \in X} \{ \mu(g) - \tilde{D}_{\phi, \nu}(\mu) \} = \sup_{\mu \in X} \{ \mu(g) - D_{\phi, \nu}(\mu) \}. \quad (12)$$
Observe that compared to (5), the supremum is now taken over the smaller set \( X^1 = X \cap \mathcal{M}^1 \), and thus \( \tilde{D}^{\star}_{\phi,\nu} \leq D^{\star}_{\phi,\nu} \). When \( \tilde{D}_{\phi,\nu} \) is lower semicontinuous we then get for \( \mu \in X^1 \)

\[
D_{\phi}(\mu \| \nu) = \tilde{D}_{\phi,\nu}(\mu) = \tilde{D}^{\star}_{\phi,\nu}(\mu) = \sup_{g \in Y} \{ \mu(g) - \tilde{D}_{\phi,\nu}(g) \}. \tag{13}
\]

This representation should be contrasted with the one obtained in Section 4.2, \( D_{\phi}(\mu \| \nu) = \sup_{g \in Y} \{ \mu(g) - D^{\star}_{\phi,\nu}(g) \} \), which holds for any \( \mu \in X \) and in which the optimand is smaller than in (13) for all \( g \in Y \) (see also Examples 4.3.4 and 4.3.6 below for an illustration).

In the rest of this section, we carry out the above program by giving an explicit expression for \( \tilde{D}^{\star}_{\phi,\nu} \) defined in (12) and showing that \( \tilde{D}_{\phi,\nu} \) is lower semi-continuous. We will assume in the rest of this paper that \( \text{dom} \phi \) contains a neighborhood of 1, as otherwise the \( \phi \)-divergence on probability measures becomes the discrete divergence \( D_{\phi}(\mu \| \nu) = \delta_{\{\nu\}}(\mu) \) which is only finite when \( \mu = \nu \) and for which the questions studied in this work are trivial. We start with the following lemma giving a simpler expression for \( \tilde{D}_{\phi,\nu} \).

**Lemma 4.3.1.** Define \( \phi_+ : x \mapsto \phi(x) + \delta_{\mathbb{R}_{\geq 0}}(x) \) for \( x \in \mathbb{R} \). Then for all \( \mu \in \mathcal{M} \)

\[
\tilde{D}_{\phi,\nu}(\mu) = D_{\phi_+\nu}(\mu) + \delta_{\{1\}}(\mu(\Omega)).
\]

**Proof.** Using the same notations as in Definition 4.1.2, and since \( \phi_+(-\infty) = -\infty \), it is easy to see that \( D_{\phi_+\nu}(\mu) \) equals \( +\infty \) whenever \( \mu^\circ \neq 0 \) or \( \nu([\omega \in \Omega \mid \frac{d\mu}{d\nu}(\omega) < 0]) \neq 0 \) and equals \( D_{\phi,\nu}(\mu) \) otherwise. In other words, \( D_{\phi_+\nu}(\mu) = D_{\phi,\nu}(\mu) + \delta_M(\mu) \). This concludes the proof since \( \delta_M(\mu) + \delta_{\{1\}}(\mu(\Omega)) = \delta_M(\mu) \).

In the expression of \( \tilde{D}_{\phi,\nu} \) given by Lemma 4.3.1, the non-negativity constraint on \( \mu \) is “encoded” directly in the definition of \( \phi_+ \) (cf. [BL91]), only leaving the constraint \( \mu(\Omega) = 1 \) explicit. Since \( \mu(\Omega) = \int \chi_{\Omega} \, d\mu \), this is an affine constraint which is well-suited to a convex duality treatment. In particular, we can use Proposition 3.2.14 to compute \( \tilde{D}^{\star}_{\phi,\nu} \).

**Proposition 4.3.2.** Assume that \((X, Y)\) is a \( \nu \)-decomposable dual pair for some \( \nu \in \mathcal{M}^1 \). Then the convex conjugate of \( \tilde{D}_{\phi,\nu} \) with respect to \((X, Y)\) is given for all \( g \in Y \), by

\[
\tilde{D}^{\star}_{\phi,\nu}(g) = \inf_{\lambda \in \mathbb{R}} \left\{ \int \phi_+^*(g + \lambda) \, d\nu - \lambda \left| \lambda + \text{ess sup}_{\mathbb{R}} g \leq \phi_+^*(\infty) \right\} \right\}, \tag{14}
\]

where \( \phi_+ : x \mapsto \phi(x) + \delta_{\mathbb{R}_{\geq 0}}(x) \) and \( \Xi = \{ A \in \mathcal{F} \mid \forall \mu \in X, \, |\mu|(A) = 0 \} \).

In (14) the infimum is reached if it is finite, which holds in particular whenever \( g \in L^\infty(\Xi) \).

**Proof.** We use Lemma 4.3.1 and apply Proposition 3.2.14 with \( f = D_{\phi_+\nu}, \, \gamma = \chi_{\Omega} \) and \( \varepsilon = 1 \). We need to verify that \( 1 \in \text{int}(\{\mu(\Omega) \mid \mu \in \text{dom} D_{\phi_+\nu}\}) \), but this is immediate since \((1 \pm \varepsilon)\nu \in \text{dom} D_{\phi_+\nu} \) for sufficiently small \( \varepsilon \) by the assumption that \( 1 \in \text{int} \text{ dom} \phi \).

Thus, by Proposition 3.2.14, for all \( g \in Y \)

\[
\tilde{D}^{\star}_{\phi,\nu}(g) = \inf_{\lambda \in \mathbb{R}} \left\{ D^{\star}_{\phi_+\nu}(g + \lambda) - \lambda \right\}.
\]
where the infimum is reached whenever it is finite. Equation (14) follows by using Proposition 4.2.6 and observing that \( \phi'(\infty) = \phi'(\infty) \) and \( \phi'(-\infty) = -\infty \).

It remains to verify the claims about finiteness of \( \overline{D}^*_\phi,\nu(g) \). For \( g \in L^\infty(\Xi) \), write \( M := \text{ess sup}_\Xi g \). Since \( \text{int}(\text{dom } \phi^*_\nu) = (-\infty, \phi'(\infty)) \), for any \( A < \phi'(\infty) \), the choice of \( \lambda = A - M \) makes the optimum in (14) finite.

**Remark 4.3.3.** As in Remark 4.2.7 above, when \( X \subseteq M_\nu(\nu) \) the constraint on \( \lambda \) in (14) can be dropped, leading to a simpler expression for \( \overline{D}^*_\phi,\nu(g) \) in this case. Indeed, \( \text{dom } \phi^*_\nu = (-\infty, \phi'(\infty)) \) and thus the optimum in (14) equals \( +\infty \) whenever \( \text{ess sup}_\Xi g = \text{ess sup}_\nu g > \phi'(\infty) - \lambda \).

**Example 4.3.4.** The effect of the restriction to probability measures is particularly pronounced for the total variation distance, which is the \( \phi \)-divergence for \( \phi(x) = |x - 1| \). In the unrestricted case, a simple calculation shows \( \phi \) has convex conjugate \( \phi^*(x) = x + \delta_{[-1,1]}(x) \), so that the conjugate of the unrestricted divergence \( D_{\phi,\nu}(g) \) is \( +\infty \) unless \( \text{ess sup}_\Xi g \subseteq [-1, 1] \). In the case of probability measures, the restriction \( \phi \) to the non-negative reals has conjugate \( \phi^*(x) = x \) when \( |x| \leq 1 \), \( \phi^*(x) = +\infty \) when \( x > 1 \), but \( \phi^*(x) = -1 \) when \( x < -1 \). Thus, \( D_{\phi,\nu}(g) < +\infty \) whenever \( \text{ess sup}_\Xi g \subseteq (-\infty, 1] \). Furthermore, because of the additive \( \lambda \) shift in Eq. (14), we have \( \overline{D}_{\phi,\nu}(g) < +\infty \) whenever \( \text{ess sup}_\Xi g < +\infty \), in particular whenever \( g \in L^\infty(\Xi) \).

As a corollary, we obtain a different variational representation of the \( \phi \)-divergence, valid for probability measures and containing as a special case the Donsker–Varadhan representation of the Kullback–Leibler divergence.

**Corollary 4.3.5.** Assume that \( (X, Y) \) is \( \nu \)-decomposable for some \( \nu \in \mathcal{M}^1 \). Then, \( \overline{D}_{\phi,\nu} \) is lower semicontinuous over \( X \). In particular for all probability measures \( \mu \in \mathcal{X} = X \cap \mathcal{M}^1 \)

\[
D_{\phi}(\mu \parallel \nu) = \sup_{g \in Y} \left\{ \mu(g) - \inf_{\lambda} \left\{ I_{\phi^*,\nu}(g + \lambda) - \lambda | \lambda + \text{ess sup}_\Xi g \leq \phi'(\infty) \right\} \right\},
\]

where \( \phi_* : x \mapsto \phi(x) + \delta_{\mathbb{R}_{\geq 0}}(x) \) and \( \Xi = \{ A \in \mathcal{F} \mid \forall \mu \in X, |\mu|(A) = 0 \} \).

**Proof.** Since \( 1_{\Omega} \in Y \) the linear form \( \mu \mapsto \mu(1_{\Omega}) \) is continuous for any topology compatible with the dual pair \( (X, Y) \). Consequently, the function \( \mu \mapsto \delta_{\{1\}}(\mu(\Omega)) \) is lower semicontinuous as the composition of the lower semicontinuous function \( \delta_{\{1\}} \) with a continuous function. Finally, \( D_{\phi,\nu} \) is lower semicontinuous by Propositions 4.2.4 and 4.2.8. Hence \( \overline{D}_{\phi,\nu} \) is lower semicontinuous as the sum of two lower semicontinuous functions, by using the expression in Lemma 4.3.1. The variational representation immediately follows by expressing \( \overline{D}_{\phi,\nu} \) as its biconjugate.

**Example 4.3.6.** As in Example 4.2.5, we consider the case of the Kullback–Leibler divergence, given by \( \phi(x) = \phi_*(x) = x \log x \). For a \( \nu \)-decomposable dual pair \( (X, Y) \), since \( \phi^*(x) = e^{x-1} \)

Proposition 4.3.2 implies for \( \nu \in \mathcal{M}^1 \) and \( g \in Y \) that

\[
\overline{D}_{\phi,\nu}^*(g) = \inf_{\lambda \in \mathbb{R}} \int e^{g+\lambda-1} \, d\lambda - \lambda = \log \int e^{g} \, d\nu,
\]

where the last equality comes from the optimal choice of \( \lambda = -\log \int e^{g-1} \, d\nu \). Using Corollary 4.3.5 we obtain for all probability measure \( \mu \in \mathcal{X} \)

\[
D(\mu \parallel \nu) = \sup_{g \in Y} \left\{ \mu(g) - \int e^{g} \, d\nu \right\} = \sup_{g \in Y} \left\{ \mu(g) - \nu(g) - \log \int e^{(g-\nu)(g)} \, d\nu \right\},
\]

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which is the Donsker–Varadhan representation of the Kullback–Leibler divergence [DV76]. For \( \mu \in \mathcal{X} \), the variational representation obtained in (7) can be equivalently written

\[
D(\mu \parallel \nu) = \sup_{g \in Y} \left\{ 1 + \mu(g) - \int e^g \, d\nu \right\}.
\]

Using the inequality \( \log(x) \leq x - 1 \) for \( x > 0 \), we see that the optimum in the previous supremum is smaller than the optimum in the Donsker–Varadhan representation for all \( g \in Y \). We thus obtained a “tighter” representation by restricting the divergence to probability measures.

**Example 4.3.7.** Consider the family of divergences \( \phi(x) = |x - 1|^\alpha / \alpha \) for \( \alpha \geq 1 \). A simple computation gives \( \phi^*(y) = y + |y|^\beta / \beta \) where \( \beta \geq 1 \) is such that \( 1 / \alpha + 1 / \beta = 1 \). The paper [JIW17] uses the variational representation given by Proposition 4.2.4, that is

\[
D_\phi(\mu \parallel \nu) = \sup_{g \in \mathcal{X}} \mu(g) - \nu(\phi^*(g)).
\]

However, Corollary 4.3.5 shows that the tight representation uses \( \phi^*_\alpha(y) \) which has the piecewise definition \( y + |y|^{\beta} / \beta \) when \( \beta \geq 1 \) and the constant \(-1 / \alpha \) when \( \beta = -1 \), and writes \( D_\phi(\mu \parallel \nu) = \sup_{g \in \mathcal{X}} \mu(g) - \inf_{\lambda} \nu(\phi^*_\lambda(g + \lambda)) \). Note that the additive \( \lambda \) shift, in e.g.

\[\text{the case } \alpha = 2, \text{ reduces the second term from the raw second moment } \nu(g^2) \text{ to something no larger than the variance } \nu((g - \nu(g))^2), \text{ which is potentially much smaller.}\]

## 5 Optimal bounds for a single function and reference measure

As a first step to understand the relationship between a \( \phi \)-divergence and an IPM, we consider the case of a single fixed probability measure \( \nu \in \mathcal{M}^1 \) and measurable function \( g \in \mathcal{L}^0 \), and study the optimal lower bound of \( D_\phi(\mu \parallel \nu) \) as a function of the **mean deviation** \( \mu(g) - \nu(g) \). We characterize this optimal lower bound and its convex conjugate in Section 5.1 and then present implications for topological question regarding the divergence itself in subsequent sections.

In the remainder of this work, since we are interested in probability measures, which are in particular non-negative, we assume without loss of generality that \( \phi \) is infinite on the negative reals, that is \( \phi(x) = \phi_+(x) = \phi(x) + \delta_{\mathbb{R}_{\geq 0}}(x) \). As seen in Section 4.3 (in particular Lemma 4.3.1), this does not change the value of the divergence on non-negative measures, that is \( D_\phi(\mu \parallel \nu) = D_{\phi_+}(\mu \parallel \nu) \) for \( \mu \in \mathcal{M}^+ \), but yields a tighter variational representation since \( \phi_+^* \leq \phi^* \).

Furthermore, since for probability measures \( D_\phi(\mu \parallel \nu) \) is invariant to affine shifts of the form \( \tilde{\phi}(x) = \phi(x) + c \cdot (x - 1) \) for \( c \in \mathbb{R} \), it will be convenient to assume that \( 0 \in \phi(1) \) (e.g. \( \phi'(1) = 0 \)), equivalently that \( \phi \) is non-negative and has global minimum at \( \phi(1) = 0 \). This can always be achieved by an appropriate choice of \( c \) and is therefore without loss of generality. As an example, we now write for the Kullback–Leibler divergence \( \phi(x) = x \log x - x + 1 \) which is non-negative with \( \phi'(1) = 0 \), and equivalent to the standard definition \( \phi(x) = x \log x \) for probability measures.

### 5.1 Derivation of the bound

We first define the optimal lower bound function, which comes in two flavors depending on whether the mean deviation or the absolute mean deviation is considered.

**Definition 5.1.1.** For a probability measure \( \nu \in \mathcal{M}^1 \), a function \( g \in \mathcal{L}^1(\nu) \), and set of probability measures \( M \) integrating \( g \), the **optimal lower bound on** \( D_\phi(\mu \parallel \nu) \) in terms of the mean deviation...
is the function $\mathcal{L}_{g,\nu,M}$ defined for $\varepsilon \in \mathbb{R}$ by:

$$\mathcal{L}_{g,\nu,M}(\varepsilon) \triangleq \inf \left\{ \mathcal{D}_\phi(\mu \| \nu) \mid \mu \in M \land \mu(g) - \nu(g) = \varepsilon \right\}$$

$$= \inf \left\{ \mathcal{D}_\phi(\mu \| \nu) + \delta_{(0)}(\mu(g) - \nu(g) - \varepsilon) \mid \mu \in M \right\}$$

$$(15)$$

$$\mathcal{L}_{\pm g,\nu,M}(\varepsilon) \triangleq \inf \left\{ \mathcal{D}_\phi(\mu \| \nu) \mid \mu \in M \land |\mu(g) - \nu(g)| = \varepsilon \right\}$$

$$= \min\{ \mathcal{L}_{g,\nu,M}(\varepsilon), \mathcal{L}_{g,\nu,M}(-\varepsilon) \}$$

$$(16)$$

where we follow the standard convention that the infimum of the empty set is $+\infty$.

**Lemma 5.1.2.** For every $\nu \in M^1$, $g \in \mathcal{L}^1(\nu)$, and convex set $M$ of probability measures integrating $g$, the function $\mathcal{L}_{g,\nu,M}$ is convex and non-negative. Furthermore, $\mathcal{L}_{g,\nu,M}(0) = 0$ whenever $\nu \in M$, and if $\phi'(\infty) = \infty$ then $\mathcal{L}_{g,\nu,M} = \mathcal{L}_{g,\nu,M \cap M_c(\nu)}$.

**Proof.** Convexity is immediate from Lemma 3.2.4 applied to Eq. (15), non-negativity follows from non-negativity of $\mathcal{D}_\phi(\cdot \| \nu)$, the choice $\nu = \nu$ implies $\mathcal{L}_{g,\nu,M}(0) = 0$ when $\nu \in M$, and if $\phi'(\infty) = \infty$ then $\mathcal{D}_\phi(\mu \| \nu) = +\infty$ when $\mu \in M \setminus M_c(\nu)$.  

We compute the convex conjugate of $\mathcal{L}_{g,\nu}$ by applying Fenchel duality to Eq. (15).

**Proposition 5.1.3.** Let $(X, Y)$ be a $\nu$-decomposable pair for some probability measure $\nu \in M^1$ and let $\mathcal{E} = \{ A \in \mathcal{F} \mid \forall \mu \in X, \ |\mu|(A) = 0 \}$. Then for all $g \in Y$ and $t \in \mathbb{R}$,

$$\mathcal{L}_{g,\nu,X^*_t}(t) = \inf \left\{ \mathcal{F}_\phi(tg + \lambda) \, d\nu - t \cdot \nu(g) - \lambda \mid \lambda + \text{ess sup}_{\mathcal{E}}(t \cdot g) \leq \phi'(\infty) \right\}. \quad (17)$$

Furthermore, $\mathcal{L}_{g,\nu,X^*_t}(t) = \mathcal{L}_{g,\nu,X^*_t}(\varepsilon)$ if and only if strong duality holds in Eq. (15).

**Proof.** Define $\Phi : X \to \overline{\mathbb{R}}$ by $\Phi(x) = \mathcal{D}_{\phi,\nu}(x + \nu)$ so that $\Phi$ is convex, lsc, non-negative, and 0 at 0. Furthermore, $\Phi^*(h) = \mathcal{D}_{\phi,\nu}^*(h) - \nu(h)$ for $h \in Y$, and $\mathcal{L}_{g,\nu,X^*_t}(\varepsilon) = \inf\{ \Phi(x) \mid x \in X \land (x, g) = \varepsilon \}$. The result then follows by Propositions 3.2.14 and 4.3.2.  

**Remark 5.1.4.** Since $\text{dom } \phi^* \subset \{-\infty, \phi'(\infty)\}$, $\lambda$ is always implicitly restricted in Eq. (17) to satisfy $\lambda + \text{ess sup}_\mathcal{E} tg \leq \phi'(\infty)$. When $\mathcal{E}$ is a proper subset of the null $\sigma$-ideal of $\nu$, the constraint in Eq. (17) is stronger to account for measures in $X$ which are not continuous with respect to $\nu$.

If $\phi'(\infty) = \infty$, then the infimum in Eq. (17) is taken over all $\lambda \in \mathbb{R}$ and in particular, does not depend on $\mathcal{E}$. This is consistent with the fact that, in this case, $\mathcal{D}_{\phi,\nu}$ is infinite on singular measures, hence $\mathcal{L}_{g,\nu,X^*_t} = \mathcal{L}_{g,\nu,X^*_t(\varepsilon)}$ where $X^*_t(\varepsilon) = X \cap M_c(\varepsilon)$.

**Remark 5.1.5.** Unlike in Proposition 4.3.2, it is not always true that the interiority constraint qualification conditions hold, and indeed strong duality does not always hold for the optimization problem (15). For example, for $\Omega = (-1/2, 1/2)$, $\nu$ the Lebesgue measure, $g$ the canonical injection into $\mathbb{R}$, and $\phi : x \mapsto |x - 1|$ corresponding to the total variation distance, we have $\mathcal{L}_{g,\nu,M}(\pm 1/2) = \infty$ but $\mathcal{L}_{g,\nu,M}(x) \leq 2$ for $|x| < 1/2$. However, as noted in Theorem 5.1.11 below, this generally does not matter since it only affects the boundary of the domain of $\mathcal{L}_{g,\nu}$, which contains at most two points. Furthermore, we will show in Corollary 5.3.6 via a compactness argument that when $\phi'(\infty) = \infty$ and $\text{dom } \mathcal{L}_{g,\nu}^* = \mathbb{R}$—e.g. when $g \in L_\infty(\nu)$—strong duality holds in (15).
We can simplify the expressions in Proposition 5.1.3 by introducing the function \( \psi : x \mapsto \phi(x + 1) \). We state some useful properties of its conjugate \( \psi^* \) below.

**Lemma 5.1.6.** The function \( \psi^* : x \mapsto \phi^*(x) - x \) is non-negative, convex, and inf-compact. Furthermore, it satisfies \( \psi^*(0) = 0 \), \( \psi^*(x) \leq -x \) when \( x \leq 0 \), and \( \inf(\text{dom } \psi^*) = (-\infty, \phi'(\infty)) \).

Recall that at the beginning of Section 5 we assumed, without loss of generality, that \( 0 \in \partial \phi(1) \) and \( \text{dom } \phi \subseteq \mathbb{R}_{\geq 0} \), which is necessary for Lemma 5.1.6 to hold. The proof follows immediately from basic results in convex analysis on \( \mathbb{R} \); for completeness, a proof is included in Appendix A.2.

The right-hand side of Eq. (17), expressed in terms of \( \psi^* \), will be central to our theory, so we give it a name in the following definition.

**Definition 5.1.7** (Cumulant generating function). For a \( \sigma \)-ideal \( \Xi \) and probability measure \( \nu \in M_1^1(\Xi) \), the \((\phi, \nu, \Xi)\)-cumulant generating function \( K_{g, \nu, \Xi} : \mathbb{R} \to [\mathbb{R}, \mathbb{R}] \) of a function \( g \in L^1(\Xi) \) is defined for all \( t \in \mathbb{R} \) by

\[
K_{g, \nu, \Xi}(t) \equiv \inf \left\{ \int \psi^*(tg + \lambda) \, d\nu \mid \lambda + \text{ess sup}_{\Xi}(t \cdot g) \leq \phi'(\infty) \right\}.
\]

Note that since \( \nu \in M_c(\Xi) \), we always have \( \Xi \subseteq N \equiv \{ A \in \mathcal{F} \mid \nu(A) = 0 \} \), hence \( K_{g, \nu, \Xi} \geq K_{g, \nu, N} \).

In the common case where \( \Xi = N \) we abbreviate \( K_{g, \nu} \equiv K_{g, \nu, N} \).

Note also that \( \text{ess sup}_{\Xi}(t \cdot g) \) is the piecewise-linear function

\[
\text{ess sup}_{\Xi}(t \cdot g) = \begin{cases} 
\text{ess sup}_{\Xi} g & t \geq 0 \\
\text{ess inf}_{\Xi} g & t \leq 0
\end{cases}
\]

**Example 5.1.8.** For the Kullback–Leibler divergence, \( K_{g, \nu}(t) = \log \nu(e^{tg} - 1) \) by Example 4.3.6, which is the standard (centered) cumulant generating function, thereby justifying the name.

Note that the \((\phi, \nu)\)-cumulant generating function \( K_{g, \nu} \) depends only on the pushforward measure \( g_* \nu \) of \( g \) through \( \nu \). In particular, when \( \nu \) is the probability distribution of a random variable \( X \), as in Example 3.1.4, \( K_{g, \nu}(t) \) can be equivalently written as

\[
K_{g, \nu}(t) = \inf_{\lambda \in \mathbb{R}} \mathbb{E}[\psi^*(t \cdot g(X) + \lambda)],
\]

highlighting the fact that \( K_{g, \nu} \) only depends on \( g(X) \). This contrasts with \( K_{g, \nu, \Xi} \), for an arbitrary \( \Xi \gg \nu \), for which the constraint on \( \lambda \) depends on the \( \Xi \)-essential range of \( g \), which is not solely a property of the random variable \( g(X) \) since it can depend on the value of \( g \) on \( \nu \)-null sets.

Furthermore, since for \( t \in \mathbb{R} \), the function \( \lambda \mapsto I_{\psi^*, \nu}(tg + \lambda) \) is convex in \( \lambda \), the \((\phi, \nu)\)-cumulant generating function is defined by a single-dimensional convex optimization problem whose objective function is expressed as an integral with respect to a probability measure (18, 19). Hence, the rich spectrum of stochastic approximation methods, such as stochastic gradient descent, can be readily applied, leading to efficient numerical procedures to evaluate \( K_{g, \nu}(t) \), as long as the pushforward measure \( g_* \nu \) is efficiently samplable.

**Remark 5.1.9.** Since the mean deviation, and thus the optimal bound \( \mathcal{L}_{g, \nu} \) is invariant to shifting \( g \) by a constant, we are in fact implicitly working in the quotient space \( L^1(\nu)/\mathbb{R}_1 \). As such, \( g \mapsto \inf_{\lambda \in \mathbb{R}} I_{\phi^*, \nu}(g + \lambda) \) can be interpreted as the integral functional induced by \( I_{\psi^*, \nu} \) on this quotient space, by considering its infimum over all representatives of a given equivalence class. This is analogous to the definition of a norm on a quotient space.
The following proposition states some basic properties of the cumulant generating function. As with Lemma 5.1.6, they follow from basic results in convex analysis, and we defer the proof to Appendix A.2.

**Proposition 5.1.10.** For every σ-ideal \( \Xi \), probability measure \( \nu \in \mathcal{M}_c(\Xi) \), and \( g \in L^0(\Xi) \), \( K_{g,\nu,\Xi} : \mathbb{R} \rightarrow \mathbb{R} \) is non-negative, convex, lower semicontinuous, and satisfies \( K_{g,\nu,\Xi}(0) = 0 \).

Furthermore, if \( g \) is not \( \nu \)-essentially constant then \( K_{g,\nu,\Xi} \) is inf-compact. If there exists \( c \in \mathbb{R} \) such that \( g = c \) \( \nu \)-almost surely, then there exists \( t > 0 \) (resp. \( t < 0 \)) such that \( K_{g,\nu,\Xi}(t) > 0 \) if and only if \( \phi'(\infty) < \infty \) and \( \text{ess sup}_\Xi g > c \) (resp. \( \text{ess inf}_\Xi g < c \)).

With these definitions, we can state the main result of this section giving an expression for the optimal lower bound function.

**Theorem 5.1.11.** Let \( (X, Y) \) be a \( \nu \)-decomposable pair for some probability measure \( \nu \in \mathcal{M}^1 \) and let \( \Xi = \{ A \in \mathcal{F} \mid \forall \mu \in X, \ |\mu|(A) = 0 \} \). Then for all \( g \in Y \) and \( \epsilon \in \text{int}(\text{dom} \mathcal{L}_{g,\nu,\Xi}) \),

\[
\mathcal{L}_{g,\nu,\Xi}(\epsilon) = K^*_{g,\nu,\Xi}(\epsilon). \tag{20}
\]

Furthermore, if \( \mathcal{L}_{g,\nu,\Xi} \) is lower semi-continuous, equivalently if strong duality holds in (15), then (20) holds for all \( \epsilon \in \mathbb{R} \).

**Proof.** Lemma 5.1.2 implies that \( \mathcal{L}_{g,\nu,\Xi} \) is proper and convex, thus, by the Fenchel–Moreau theorem, we have \( \mathcal{L}_{g,\nu,\Xi} = \mathcal{L}^{**}_{g,\nu,\Xi} \) except possibly at the boundary of its domain, so this is simply a restatement of Proposition 5.1.3 using the terminology from Definition 5.1.7. \( \square \)

Proposition 5.1.3 and Theorem 5.1.11 show that the conjugate of the optimal lower bound only depends on the space of measures \( X \), through the σ-ideal \( \Xi \), as long as \( X \) forms a decomposable dual pair with a space \( Y \) of functions containing \( g \). Hence, starting from a σ-ideal \( \Xi \) and a function \( g \)—or more generally a class of functions \( \mathcal{G} \)—a natural dual pair to consider is the space \( X \subseteq \mathcal{M}_c(\Xi) \) of all measures integrating functions in \( \mathcal{G} \), put in dual pairing with the subspace of \( L^0(\Xi) \) of all functions integrable by measures in \( X \). Formally, we have the following definition.

**Definition 5.1.12.** Let \( \mathcal{G} \) be a subset of \( L^0(\Sigma) \) for some σ-ideal \( \Sigma \). We define

\[
X_\mathcal{G} \equiv \{ \mu \in \mathcal{M}_c(\Sigma) \mid \forall g \in \mathcal{G}, \ |\mu|(|g|) < \infty \}
\]

and

\[
Y_\mathcal{G} \equiv \{ h \in L^0(\Xi) \mid \forall \mu \in X_\mathcal{G}, \ |\mu|(|h|) < \infty \},
\]

where \( \Xi \equiv \{ A \in \mathcal{F} \mid \forall \mu \in X_\mathcal{G}, \ |\mu|(A) = 0 \} \).

For brevity, if \( \mathcal{G} = \{ g \} \) is a singleton, we write \( X_g \) for \( X_\mathcal{G} \) and \( Y_g \) for \( Y_\mathcal{G} \).

**Remark 5.1.13.** We would like to use \( \Sigma \) rather than \( \Xi \) in the definition of \( Y_\mathcal{G} \), but need to be careful since if \( \Sigma \not\subseteq \Xi \) then using \( \Sigma \) would prevent \( (X_\mathcal{G}, Y_\mathcal{G}) \) from being in separating duality. Unfortunately, there exist pathological σ-ideals for which \( \Sigma \not\subseteq \Xi \) ([Szp34, 2. Corollaire]), but since for non-pathological choices of \( \Sigma \) (e.g. when it is the null ideal of a σ-finite, semifinite, or s-finite measure) we indeed have \( \Sigma = \Xi \), we do not dwell on this distinction.

**Lemma 5.1.14.** Consider a subset \( \mathcal{G} \subseteq L^0(\Sigma) \) for some σ-ideal \( \Sigma \). Then for every \( \nu \in X_\mathcal{G}^+ \), the pair \( (X_\mathcal{G}, Y_\mathcal{G}) \) is \( \nu \)-decomposable.
Proof. That $\mu(h) < \infty$ for all $\mu \in X_\mathcal{g}$ and $h \in Y_\mathcal{g}$ is by definition. As discussed in Remark 4.2.2, it suffices to verify that item 2 in Definition 4.2.1 is true for all $v \in X_\mathcal{g}$, and indeed just for all $v \in X_\mathcal{g}^+$ since $v \in X_\mathcal{g}$ implies $|v| \in X_\mathcal{g}^+$. Item 3 and the separability of the duality between $(X_\mathcal{g}, Y_\mathcal{g})$ then follow immediately.

For item 2, consider $v \in X_\mathcal{g}^+$ and $\mu \in \mathcal{M}_c(\nu)$ such that $\frac{d\mu}{dv} \in L^\infty(\nu)$. Then for all $g \in \mathcal{G}$ we have $|\mu([g])| = v\left(\left|\frac{d\mu}{dv}\right| \cdot |g|\right) < \infty$ by Hölder’s inequality, hence $\mu \in X_\mathcal{g}$. That $L^\infty(\Xi) \subseteq Y_\mathcal{g}$ holds is immediate since every $\mu \in \mathcal{M}_c(\Sigma)$ integrates every $h \in L^\infty(\Xi)$. □

The following easy corollary is an “operational” restatement of Theorem 5.1.11, specialized to the dual pair of Definition 5.1.12, and highlighting the duality between upper bounding the cumulant generating function and lower bounding the $\phi$-divergence by a convex lower semicontinuous function of the mean deviation.

**Corollary 5.1.15.** Consider a measurable function $g \in L^0(\Sigma)$ for some $\sigma$-ideal $\Sigma$ and let $\Xi = \{A \in \mathcal{F} \mid \forall \mu \in X_\mathcal{g}, |\mu|(A) = 0\}$. Then for every probability measure $\nu \in X_\mathcal{g}^1 \equiv X_\mathcal{g} \cap M^1$ and convex lower semicontinuous function $L : \mathbb{R} \to \mathbb{R}_{\geq 0}$, the following are equivalent:

(i) $D_\phi(\mu \parallel \nu) \geq L(\mu(g) - \nu(g))$ for every $\mu \in X_\mathcal{g}^1$.

(ii) $K_{g,\nu,\Xi} \leq L^*$. 

**Example 5.1.16.** The Hammersley–Chapman–Robbins bound in statistics is an immediate corollary of Corollary 5.1.15 applied to the $\chi^2$-divergence given by $\phi(x) = (x - 1)^2 + \delta_{[-1,\infty)}(x)$: The convex conjugate of $\psi(x) = x^2 + \delta_{[-1,\infty)}(x)$ is

$$\psi^*(x) = \begin{cases} x^2/4 & x \geq -2 \\ -1 - x & x < -2 \end{cases}$$

and satisfies in particular $\psi^*(x) \leq x^2/4$, so that $K_{g,\nu,\Xi}(t) \leq \inf_{\lambda} f(tg + \lambda)^2/4 \, dv = t^2 \text{Var}_\nu(g)/4$. Since the convex conjugate of $t \mapsto t^2 \text{Var}_\nu(g)/4$ is $t \mapsto t^2/\text{Var}_\nu(g)$, we obtain for all $\mu, \nu \in M^1$ and $g \in L^1(\nu)$ that $\chi^2(\mu \parallel \nu) \geq (\mu(g) - \nu(g))^2/\text{Var}_\nu(g)$.

Theorem 5.1.11 also gives a useful characterization of the existence of a non-trivial lower bound by the absolute mean deviation.

**Corollary 5.1.17.** Consider a measurable function $g \in L^0(\Sigma)$ for some $\sigma$-ideal $\Sigma$ and let $\Xi = \{A \in \mathcal{F} \mid \forall \mu \in X_\mathcal{g}, |\mu|(A) = 0\}$. Then for every $\nu \in X_\mathcal{g}^1$, the optimal lower bound $\mathcal{L}_{[\pm g],\nu,\chi}$ is non-zero if and only if $0 \in \text{int}(\text{dom} \, K_{g,\nu,\Xi})$. In other words, the following are equivalent

(i) there exists a non-zero function $L : \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ such that $D_\phi(\mu \parallel \nu) \geq L(|\mu(g) - \nu(g)|)$ for every $\mu \in X_\mathcal{g}^1$.

(ii) the function $K_{g,\nu,\Xi}$ is finite on an open interval around 0.

Proof. Writing $M = X_\mathcal{g}^1$, we have by Eq. (16) that the function $\mathcal{L}_{[\pm g],\nu,M}$ is non-zero if and only if there exists $\varepsilon > 0$ such that $\mathcal{L}_{g,\nu,M}(\varepsilon) = 0 \neq \mathcal{L}_{g,\nu,M}(-\varepsilon)$. Since $\mathcal{L}_{g,\nu,M}$ is convex, non-negative, and 0 at 0 by Lemma 5.1.2, such an $\varepsilon$ exists if and only if 0 is contained in the interval $(\mathcal{L}_{g,\nu,M}(-\infty), \mathcal{L}_{g,\nu,M}(\infty))$, the interior of the domain of $\mathcal{L}_{g,\nu,M}^*$. □
Remark 5.1.18. Throughout this section, we have seen the $\sigma$-ideal $\Xi$ appear in our results, in particular via $K_{g,\nu,\Xi}$ in Corollary 5.1.17. We will see in Theorem 6.2.9 however that when we consider a true IPM where we require the bound $L$ to hold jointly for all measures $\nu$ and $\mu$, we can ignore the $\sigma$-ideal $\Xi$ and consider only $K_{g,\nu}$.

5.2 Subexponential functions and connections to Orlicz spaces

In Sections 5.2 to 5.4, we explore properties of the set of functions satisfying the conditions of Corollary 5.1.17, i.e. for which there is a non-trivial lower bound of the $\phi$-divergence in terms of the absolute mean deviation, and show its relation to topological properties of the divergence. A reader primarily interested in quantitative bounds for IPMs can skip to Section 6.

In light of Corollary 5.1.17, we need to consider the set of functions $g$ such that $\text{dom} K_{g,\nu,\Xi}$ contains a neighborhood of zero. The following lemma shows that this is the case for bounded functions, and that furthermore, when $\phi'(\infty) < \infty$, boundedness is necessary. In other words, when $\phi'(\infty) < \infty$, the $\phi$-divergence cannot upper bound the absolute mean deviation of an unbounded function. This is in sharp contrast with the KL divergence (satisfying $\phi'(\infty) = \infty$), for which such upper bounds exist as long as the function satisfies Gaussian-type tail bounds [BLM13, §4.10].

Lemma 5.2.1. Let $\Xi$ be a $\sigma$-ideal and $\nu \in M_1^1(\Xi)$. If $g \in L^\infty(\Xi)$ then $\text{dom} K_{g,\nu,\Xi}$ is all of $\mathbb{R}$, and in particular contains a neighborhood of zero. Furthermore, when $\phi'(\infty) < \infty$, we have conversely that if $0$ is in the interior of the domain of $K_{g,\nu,\Xi}$, then $g \in L^\infty(\Xi)$, in which case $K_{g,\nu}(t) = K_{g,\nu,\Xi}(t)$ whenever $|t| \cdot (\text{ess sup}_{\Xi} g - \text{ess inf}_{\Xi} g) \leq \phi'(\infty)$.

Remark 5.2.2. As already discussed, Lemma 5.2.1 implies that when $\phi'(\infty) < \infty$, boundedness of $g$ is necessary for the existence of a non-trivial lower bound on $D_\phi(\mu \parallel \nu)$ in terms of the $|\mu(g) - \nu(g)|$. Moreover, we can deduce from Lemma 5.2.1 that in this case, any non-trivial lower bound must depend on $\text{ess sup}_{\Xi} |g|$ and cannot depend only on properties of $g$ such as its $\nu$-variance. In particular, any non-trivial lower bound must converge to $0$ as $\text{ess sup}_{\Xi} |g|$ converges to $+\infty$, so if it were not the case, one could obtain a non-trivial lower bound for an unbounded function $g$ by approximating it with bounded functions $g \cdot 1[|g| \leq n]$.

Proof. Recall that $(-\infty, 0] \subseteq \text{dom} \psi^*$ and that $\psi^*(x) \leq -x$ for $x \leq 0$ by Lemma 5.1.6. For $g \in L^\infty(\Xi)$, write $B$ for $\text{ess sup}_{\Xi} |g|$, and for $t \in \mathbb{R}$, write $\lambda \equiv -|t| \cdot B$. Then we have that $-2|t|B \leq t \cdot g + \lambda \leq 0 \leq \phi'(\infty)$ holds $\Xi$-a.s., and thus also $\psi^* (tg + \lambda) \leq 2|t|B$ holds $\Xi$-a.s. Thus $K_{g,\nu,\Xi}(t)$ is at most $2|t| \cdot B < \infty$ by definition, and since $t$ is arbitrary, we get $\text{dom} K_{g,\nu,\Xi} = \mathbb{R}$.

We now assume $\phi'(\infty) < \infty$ and prove the converse claim. If $K_{g,\nu,\Xi}(t)$ is finite for some $t \in \mathbb{R}$, then $tg + \lambda < \phi'(\infty)$ holds $\Xi$-a.s. for some $\lambda \in \mathbb{R}$. In particular, if it holds for some $t > 0$, then $\text{ess sup}_{\Xi} g$ is finite, and if it holds for some $t < 0$, then $\text{ess inf}_{\Xi} g$ is finite.

For the remaining claim, since $\psi^*$ is non-decreasing on the non-negative reals we have that $K_{g,\nu}(t) = \inf \{ t \psi^*(tg + \lambda) \mid \lambda \in \mathbb{R} \} = \inf \{ t \psi^*(tg + \lambda) \mid \text{ess inf}_{\Xi} tg + \lambda \leq 0 \}$. But if $\text{ess sup}_{\Xi} (tg - \text{ess inf}_{\Xi} (tg)) \leq \phi'(\infty)$, then $\text{ess inf}_{\Xi} t \cdot g + \lambda \leq 0$ implies $\text{ess sup}_{\Xi} tg + \lambda \leq \phi'(\infty)$ and $K_{g,\nu}(t) \geq K_{g,\nu,\Xi}(t) \geq K_{g,\nu}(t)$.

Since Lemma 5.2.1 completely characterizes the existence of a non-trivial lower bound when $\phi'(\infty) < \infty$, we focus on the case $\phi'(\infty) = \infty$ in the remainder of this section. Recall that $K_{g,\nu} = K_{g,\nu,\Xi}$ in this case, so we only need to consider $K_{g,\nu}$ in the following definition.
**Definition 5.2.3** \((\phi, \nu)\)-subexponential functions. Let \(\nu \in \mathcal{M}^1\) be a probability measure. We say that the function \(g \in L^0(\nu)\) is \((\phi, \nu)\)-subexponential if \(0 \in \text{int}(\text{dom } K_{g,\nu})\) and we denote by \(S^\phi(\nu)\) the space of all such functions. We further say that \(g \in L^0(\nu)\) is strongly \((\phi, \nu)\)-subexponential if \(\text{dom } K_{g,\nu} = \mathbb{R}\) and denote by \(S^\phi_*(\nu)\) the space of all such functions.

**Example 5.2.4.** For the case of the KL-divergence, if the pushforward \(g_*\nu\) of \(\nu\) induced by \(g\) on \(\mathbb{R}\) is the Gaussian distribution (respectively the gamma distribution), then \(g\) is strongly subexponential (respectively subexponential). Furthermore, it follows from Example 5.1.8 that \(g \in S^\phi(\nu)\) iff the moment-generating function of \(g\) is finite on a neighborhood of 0, which is the standard definition of subexponential functions (see e.g. [Ver18, §2.7]) and thus justifies our terminology.

**Example 5.2.5.** Lemma 5.2.1 shows that \(L^\infty(\nu) \subseteq S^\phi(\nu)\) and that furthermore, if \(\phi'(\infty) < \infty\), then \(L^\infty(\nu) = S^\phi_*(\nu) = S^\phi(\nu)\).

We start with the following key lemma allowing us to relate the finiteness of \(K_{g,\nu}\) to the finiteness of the function \(t \mapsto I_{\psi^*,\nu}(tg)\).

**Lemma 5.2.6.** For \(\nu \in \mathcal{M}^1\), \(g \in L^0(\nu)\), and \(t \in \text{dom } K_{g,\nu}\), we have that if \(\phi'(\infty) = \infty\) (resp. \(\phi'(\infty) > 0\)) then \(atg \in \text{dom } I_{\psi^*,\nu}\) for all \(\alpha \in (0, 1)\) (resp. for sufficiently small \(\alpha > 0\)).

**Proof.** Let \(\lambda \in \mathbb{R}\) be such that \(\int \psi^*(tg + \lambda) \, d\nu < \infty\) (such a \(\lambda\) exists since \(t \in \text{dom } K_{g,\nu}\)). Using the convexity of \(\psi^*\), we get for any \(\alpha \in (0, 1)\)

\[
\int \psi^*(\alpha tg) \, d\nu = \int \psi^*(\alpha (tg + \lambda) + (1 - \alpha)\frac{-\alpha \lambda}{1 - \alpha}) \, d\nu \\
\leq \alpha \int \psi^*(tg + \lambda) \, d\nu + (1 - \alpha)\psi^*(\frac{-\alpha \lambda}{1 - \alpha}).
\]

The first summand is finite by definition, and if \(-\alpha \lambda/(1 - \alpha) \in \text{dom } \psi^* \supseteq (-\infty, \phi'(\infty))\) then so is the second summand. If \(\phi'(\infty) = \infty\) this holds for all \(\alpha \in (0, 1)\), and if \(\phi'(\infty) > 0\) it holds for sufficiently small \(\alpha > 0\). \(\square\)

**Remark 5.2.7.** When \(\phi'(\infty) < \infty\), it is not necessarily true that any \(\alpha \in (0, 1)\) can be used in Lemma 5.2.6. For example, Lemma 5.2.1 implies that \(\text{dom } K_{g,\nu} = \mathbb{R}\) for all \(g \in L^\infty(\nu)\), but since \(\text{dom } \psi^* \subseteq (-\infty, \phi'(\infty)]\) we have \(I_{\psi^*,\nu}(tg) = \infty\) for sufficiently large (possibly only positive or negative) \(t\), unless \(g\) is zero \(\nu\)-a.s.

The following proposition gives useful characterizations of subexponential functions in terms of the finiteness of different integral functionals of \(g\).

**Proposition 5.2.8.** Suppose that \(\phi'(\infty) = \infty\) and fix \(\nu \in \mathcal{M}^1\) and \(g \in L^0(\nu)\). Then the following are equivalent:

\(\text{(i)}\) \(g\) is \((\phi, \nu)\)-subexponential
\(\text{(ii)}\) \(K_{|g|,\nu}(t) < \infty\) for some \(t > 0\)
\(\text{(iii)}\) \(g \in L^0(\nu)\) for \(\emptyset : x \mapsto \max\{\psi^*(x), \psi^*(-x)\}\) (here \(L^0(\nu)\) is the Orlicz space defined in Section 3.3)
Proof. (i) $\implies$ (ii) If dom $K_{g,\nu}$ contains an open interval around 0, Lemma 5.2.6 and the convexity of dom $I_{g,\nu}$ imply that there exists $s > 0$ such that $\int \psi^*(tg) \, d\nu < \infty$ for all $|t| < s$ by non-negativity of $\psi^*$, $\int \psi^*(|tg|) \, d\nu \leq \int \psi^*(tg) + \psi^*(-tg) \, d\nu < \infty$ for all $t \in (-s, s)$, which in turns implies $(-s, s) \subseteq \text{dom} K_{|g|,\nu}$.

(ii) $\implies$ (iii) Define $\eta(x) \equiv \psi^*(|x|)$. Since $\psi^*(x) \leq -x$ for $x \leq 0$ by Lemma 5.1.6, we have that $\eta(x) \leq \theta(x) \leq \eta(x) + |x|$ for all $x \in \mathbb{R}$. Since we also have $L^0(\nu) \subseteq L^1(\nu)$, this implies that $g \in L^0(\nu)$ if and only if $L^\theta(\nu)$. We conclude after observing that $K_{|g|,\nu}(t) < \infty$ for some $t > 0$ implies that $g \in L^0(\nu)$ by Lemma 5.2.6.

(iii) $\implies$ (i) Observe that for all $t \in \mathbb{R}$,

$$\max\{K_{g,\nu}(t), K_{g,\nu}(-t)\} \leq \max\left\{\int \psi^*(tg) \, d\nu, \int \psi^*(-tg) \, d\nu\right\} \leq \int \theta(tg) \, d\nu,$$

where the first inequality is by definition of $K_{g,\nu}$ and the second inequality is by monotonicity of the integral and the definition of $\theta$. Since dom $K_{g,\nu}$ is convex, if there exists $t > 0$ such that $I_{\theta,\nu}(tg) < \infty$, then (21) implies that $[-t, t] \subseteq \text{dom} K_{g,\nu}$ and $g$ is $(\phi, \nu)$-subexponential. 

Remark 5.2.9. Though Proposition 5.2.8 implies that the set of $(\phi, \nu)$-subexponential functions is the same as the set $L^\theta(\nu)$ for $\theta(x) = \max\{\psi^*(x), \psi^*(-x)\}$, we emphasize that the Luxemburg norm $\|\cdot\|_\theta$ does not capture the relationship between $D_{\phi}(\mu \| \nu)$ and the absolute mean deviation $|\mu(g) - \nu(g)|$. First, the function $\theta$, being a symmetrization of $\psi^*$, induces integral functionals which are potentially much larger than those defined by $\psi^*$, in particular it is possible to have $\max\{K_{g,\nu}(t), K_{g,\nu}(-t)\} < \inf_{\lambda \in \mathbb{R}} I_{\theta,\nu}(tg + \lambda) < I_{\theta,\nu}(tg)$. Furthermore, the Luxemburg norm summarizes the growth of $t \mapsto I_{\theta,\nu}(tg)$ with a single number (specifically its inverse at 1), whereas Theorem 5.1.11 shows that the relationship with the mean deviation is controlled by $K_{\psi^*}$, which depends on the growth of $K_{\psi^*}(t)$ with $t$.

We are now ready to prove the main result of this section, which is that the space $S^\phi(\nu)$ of $(\phi, \nu)$-subexponential functions is the largest space of functions which can be put in dual pairing with (the span of) all measures $\mu \in M_c(\nu)$ such that $D_{\phi}(\mu \| \nu) < \infty$, i.e. dom $I_{\phi,\nu}$.

Theorem 5.2.10. For $\nu \in M^1$ and $g \in L^0(\nu)$, the following are equivalent:

(i) $g$ is $(\phi, \nu)$-subexponential, i.e. $g \in S^\phi(\nu)$.

(ii) $g$ is $\mu$-integrable for every $\mu \in M_c(\nu)$ with $D_{\phi}(\mu \| \nu) < \infty$.

(iii) $g$ is $\mu$-integrable for every $\mu \in M^1_c(\nu)$ with $D_{\phi}(\mu \| \nu) < \infty$.

Proof. (i) $\implies$ (ii) If $\phi'(\infty) < \infty$ this follows since $L^\infty(\nu) = S^\phi(\nu)$, so assume that $\phi'(\infty) = \infty$. If $g \in S^\phi(\nu)$ then $g \in L^\phi(\nu)$ for $\theta(x) = \max\{\psi^*(x), \psi^*(-x)\}$ by Proposition 5.2.8. Since $\theta \geq \psi^*$ we have $\theta^* \leq \psi$, and thus for $\mu \in M_c(\nu)$ with $D_{\phi}(\mu \| \nu) < \infty$,

$$I_{\theta^*,\nu}\left(\frac{d\mu}{d\nu} - 1\right) \leq I_{\psi^*,\nu}\left(\frac{d\mu}{d\nu} - 1\right) = D_{\phi}(\mu \| \nu) < \infty,$$

implying that $\frac{d\mu}{d\nu} - 1 \in L^\theta(\nu)$. Furthermore, since $1 \in L^\infty(\nu) \subseteq L^\theta(\nu)$ we get that $\frac{d\mu}{d\nu} \in L^\theta(\nu)$.

Property 2. then follows from the fact that $(L^\theta, L^\phi)$ form a dual pair.

(ii) $\implies$ (iii) Immediate.
Proposition 5.2.11. Suppose that \( \phi'(\infty) = \infty \) and fix \( \nu \in M^1 \) and \( g \in L^0(\nu) \). Then the following are equivalent:

(i) \( g \) is strongly \((\phi, \nu)\)-subexponential, i.e. \( g \in S^\phi_\nu(\nu) \).

(ii) \( K_{|g|}(\nu)(t) < \infty \) for all \( t > 0 \).

(iii) \( g \in L^\phi_\nu(\nu) \) for \( \theta : x \mapsto \max\{\psi^+(x), \psi^-(x)\} \).

Proof. (i) \( \implies \) (ii) Since \( \phi'(\infty) = \infty \), Lemma 5.2.6 implies that \( tg \in \text{dom} I_{\psi^+, \nu} \) for all \( t \in \mathbb{R} \), and since \( \psi^+ \) is non-negative we have for each \( t > 0 \) that \( K_{|g|}(\nu)(t) \leq \int \psi^+(t|g|) \, d\nu \leq \int \psi^+(tg) + \psi^-(tg) \, d\nu < \infty \).

(ii) \( \implies \) (iii) Define \( \eta : x \mapsto \psi^+(|x|) \), so that by Lemma 5.2.6 we have \( \int \eta(tg) \, d\nu = \int \psi^+(tg) \, d\nu < \infty \) for all \( t > 0 \), and hence Property 2. implies \( g \in L^\phi_\nu(\nu) \). As in the proof of Proposition 5.2.8, \( \eta(x) \leq \theta(x) \leq \eta(x) + |x| \) for all \( x \in \mathbb{R} \) and since \( L^\phi_\nu(\nu) \subseteq L^1(\nu) \), we have that \( g \in L^\phi_\nu(\nu) \) iff \( g \in L^1(\nu) \).

(iii) \( \implies \) (i) Immediate since for \( t \in \mathbb{R} \), \( K_{|g|}(\nu)(t) \leq \int \psi^+(tg) \, d\nu \leq \int \theta(tg) \, d\nu < \infty \). \( \square \)

Finally, we collect several statements from this section and express them in a form which will be convenient for subsequent sections.

Corollary 5.2.12. Define \( \theta(x) \equiv \max\{\psi^+(x), \psi^-(x)\} \). Then we have \( S^\phi_\nu(\nu) \subseteq S^\phi_\nu(\nu) \subseteq L^1(\nu) \) and \( \text{dom} I_{\phi, \nu} \subseteq L^{\theta^*}(\nu) \subseteq L^1(\nu) \). Furthermore, \( L^{\theta^*}(\nu) \) is in dual pairing with both \( S^\phi_\nu(\nu) \) and \( S^\phi_\nu(\nu) \), and when \( \phi'(\infty) = \infty \) the topology induced by \( \| \cdot \|_{\theta^*} \) on \( S^\phi_\nu(\nu) \) is complete and compatible with the pairing.

Proof. The containment \( S^\phi_\nu(\nu) \subseteq L^1(\nu) \) is because \( S^\phi_\nu(\nu) \) is equal as a set to the Orlicz space \( L^\phi(\nu) \) by Proposition 5.2.8, and the containment \( \text{dom} I_{\phi, \nu} \subseteq L^{\theta^*}(\nu) \) can be found in the proof of (i) \( \implies \) (ii) of Theorem 5.2.10. The fact that \( (L^{\theta^*}(\nu), S^\phi_\nu(\nu)) \) form a dual pair is also immediate from the identification of \( S^\phi_\nu(\nu) \) with \( L^\phi(\nu) \) as a set. Finally, the last claim follows from the identification of \( S^\phi_\nu(\nu) \) with \( L^\phi(\nu) \) as a set and the fact that when \( \phi'(\infty) = \infty \), then \( \text{dom} \theta = \mathbb{R} \) implying that the topological dual of the Banach space \( (L^\phi(\nu), \| \cdot \|_{\theta^*}) \) is isomorphic to \( (L^{\theta^*}(\nu), \| \cdot \|_{\theta^*}) \). \( \square \)
5.3 Inf-compactness of divergences and connections to strong duality

In this section, we study the question of inf-compactness of the functional $D_{\phi,\nu}$ and that of its restriction $\tilde{D}_{\phi,\nu}$ to probability measures. Specifically, we wish to understand under which topology the information “ball” $B_{\phi,\nu}(\tau) \equiv \{\mu \in \mathcal{M} \mid D_{\phi}(\mu \parallel \nu) \leq \tau\}$ is compact. Beyond being a natural topological question, it also has implications for strong duality in Theorem 5.1.11, since the following lemma shows that compactness of the ball under suitable topologies implies strong duality.

**Lemma 5.3.1.** For every $g$, $\nu$, and $M$ as in Definition 5.1.1, if $\mu \mapsto D_{\phi}(\mu \parallel \nu)$ is inf-compact (or even countably inf-compact) with respect to a topology on $M$ such that $\mu \mapsto \mu(g)$ is continuous, then $\mathcal{L}_{g,\nu,M}$ is inf-compact (and in particular lower semicontinuous), so that strong duality holds in Theorem 5.1.11.

**Proof.** Recall from Eq. (15) that

$$\mathcal{L}_{g,\nu,M}(\varepsilon) = \inf_{\mu \in \mathcal{M}} D_{\phi}(\mu \parallel \nu) + \delta_{\{0\}}(\mu(g) - \nu(g) - \varepsilon)$$

where $f(\varepsilon, \mu) = D_{\phi}(\mu \parallel \nu) + \delta_{\{0\}}(\mu(g) - \nu(g) - \varepsilon)$ is convex. Furthermore, under the stated assumption, we have that $f$ is also inf-compact so that Lemma 3.2.4 gives the claim.

Throughout this section, we assume that $\phi'(\infty) = \infty$,

which implies that $\text{dom} \psi^* = \mathbb{R}$ by Lemma 5.1.6, and furthermore that $\mu \in \mathcal{M}_c(\nu)$ whenever $D_{\phi}(\mu \parallel \nu) < \infty$ and hence $D_{\phi,\nu} = I_{\phi,\nu}$ and $B_{\phi,\nu}(\tau) \subset \mathcal{M}_c(\nu)$ for all $\tau \geq 0$. It is well known that in this case, $B_{\phi,\nu}(\tau)$ is compact in the weak topology $\sigma(L^1(\nu), L^{\infty}(\nu))$ (e.g. [Roc71, Corollary 2B] or [TV93]). This fact can be derived as a simple consequence of the Dunford–Pettis theorem since $B_{\phi,\nu}(\tau)$ is uniformly integrable by the de la Vallée-Poussin theorem (see e.g. [Val70, pages 67–68]). In light of Lemma 5.3.1, it is however useful to understand whether $B_{\phi,\nu}(\tau)$ is compact under topologies for which $\mu \mapsto \mu(g)$ is continuous, where $g$ could be unbounded. Léonard [Léo01a, Theorem 3.4] showed, in the context of convex integral functionals on Orlicz spaces, that strong duality holds when $g \in S_0^\phi(\nu)$, and in this section we reprove this result in the language of $\phi$-divergences by noting (as is implicit in [Léo01a, Lemma 3.1]) that $B_{\phi,\nu}(\tau)$ is compact for the initial topology induced by the maps of the form $\mu \mapsto \mu(g)$ for all strongly subexponential function $g \in S_0^\phi(\nu)$.

**Proposition 5.3.2.** Fix $\nu \in \mathcal{M}^1$ and define $\Theta : x \mapsto \max\{\psi^*(x), \psi^*(-x)\}$ as in Proposition 5.2.11. If $\phi'(\infty) = \infty$, then the functional $I_{\phi,\nu}$ is $\sigma(L^\Theta(\nu), S_0^\Theta(\nu))$ inf-compact.

**Proof.** By Corollary 5.2.12, we know that $(S_0^\Theta(\nu), \| \cdot \|_\Theta)$ is a Banach space in dual pairing with $L^\Theta(\nu)$. Thus, from Proposition 4.2.4, the integral functional $I_{\phi,\nu}$, defined on $S_0^\phi(\nu)$ is convex, lower semicontinuous, and has conjugate $I_{\phi}^{\ast \ast,\nu} = I_{\phi,\nu}$ on $L^\Theta(\nu)$. Furthermore, from Lemma 5.2.6 we know for every $g \in S_0^\phi(\nu)$ that $I_{\phi}^{\ast \ast,\nu}(g) < \infty$, so $I_{\phi}^{\ast \ast}$ is convex, lsc, and finite everywhere on a Banach space, and thus continuous everywhere by [Bre64, 2.10]. Finally, [Mor64, Proposition 1] implies that its conjugate $I_{\phi,\nu}$ is inf-compact on $L^\Theta(\nu)$ with respect to the weak topology $\sigma(L^\Theta(\nu), S_0^\Theta(\nu))$.

---

5When $\phi'(\infty) < \infty$, compactness of information balls is very dependent on the specific measure space $(\Omega, \mathcal{F}, \nu)$, and in this work we avoid such conditions.
Remark 5.3.3. This result generalizes [Roc71, Corollary 2B] since $L^\infty(\nu) \subseteq S^\phi_+(\nu)$ whenever $\phi'(\infty) = \infty$ (see Example 5.2.5).

**Corollary 5.3.4.** Under the same assumptions and notations as Proposition 5.3.2, the functional $\tilde{D}_{\phi,\nu} = \sigma(L^{\phi^*}(\nu), S^\phi_+(\nu))$ is compact.

*Proof.* Observe that since $\phi(x) = \infty$ for $x < 0$, we have for every $\tau \in \mathbb{R}$ that $\{\mu \in L^{\phi^*}(\nu) \mid \tilde{D}_{\phi,\nu}(\mu) \leq \tau\} = \{\mu \in M^1 \cap L^{\phi^*}(\nu) \mid I_{\phi,\nu}(\mu) \leq \tau\} = \{\mu \in L^{\phi^*}(\nu) \mid I_{\phi,\nu}(\mu) \leq \tau\} \cap f^{-1}(1)$ where $f : \mu \to \mu(1_\Omega)$ is continuous in the weak topology $\sigma(L^{\phi^*}(\nu), S^\phi_+(\nu))$ since $L^{\infty}(\nu) \subseteq S^\phi_+(\nu)$ by Lemma 5.2.1. Hence, $M^1 \cap B_{\phi,\nu}(\tau)$ is compact as a closed subset of a compact set.

**Corollary 5.3.5.** If $\phi'(\infty) = \infty$, then for every $\tau \in \mathbb{R}$ the sets $B_{\phi,\nu}(\tau)$ and $M^1 \cap B_{\phi,\nu}(\tau)$ are compact in the initial topology induced by $\{\mu \to \mu(g) \mid g \in S^\phi_+(\nu)\}$.

*Proof.* Immediate from Proposition 5.3.2 and Corollary 5.3.4.

**Corollary 5.3.6.** Let $\nu \in M^1$ be a probability measure and assume that $\phi'(\infty) = \infty$. If $g \in L^0(\nu)$ is strongly $(\phi,\nu)$-subexponential and $M \subseteq M^1_\nu(\nu)$ is a convex set of probability measures containing every $\mu \in M^1_\nu(\nu)$ with $D_{\phi}(\mu \mid \nu) < \infty$, then the function $L_{g,\nu,M}$ is lower semicontinuous.

*Proof.* Follows from Lemma 5.3.1 and Corollary 5.3.5.

**Remark 5.3.7.** Corollary 5.3.6 does not apply when $\phi'(\infty) < \infty$ or $g \in S^\phi_+(\nu) \setminus S^\phi_+(\nu)$ (e.g. when the pushforward measure $g,\nu$ is gamma-distributed in the case of the KL divergence), and it would be interesting to identify conditions other than inf-compactness of $D_{\phi,\nu}$ under which $L_{g,\nu}$ is lower semicontinuous.

### 5.4 Convergence in $\phi$-divergence and weak convergence

Our goal in this section is to relate two notions of convergence for a sequence of probability measures $(\nu_n)_{n \in \mathbb{N}}$ and $\nu \in M^1$: (i) $D_{\phi}(\nu_n \mid \nu) \to 0$, and (ii) $|\nu_n(g) - \nu(g)| \to 0$ for $g \in L^1(\Omega)$. Specifically, we would like to identify the largest class of functions $g \in L^1(\Omega)$ such that convergence in $\phi$-divergence (i) implies (ii). In other words, we would like to identify the finest initial topology induced by linear forms $\mu \to \mu(g)$ for which (sequential) convergence is implied by (sequential) convergence in $\phi$-divergence. This question is less quantitative than computing the best lower bound of the $\phi$-divergence in terms of the absolute mean deviation, since it only characterizes when $|\nu_n(g) - \nu(g)|$ converges to 0, whereas the optimal lower bound quantifies the rate of convergence to 0 when it occurs.

---

6Throughout this section, we restrict our attention to $\phi$ which are not the constant 0 on a neighborhood of 1, i.e. such that $1 \notin \text{int}\{x \in \mathbb{R} \mid \phi(x) = 0\}$, as otherwise it is easy to construct probability measures $\mu \neq \nu$ such that $D_{\phi}(\mu \mid \nu) = 0$, hence $D_{\phi}(\nu_n \mid \nu) \to 0$ does not define a meaningful convergence notion.

7The natural notion of convergence in $\phi$-divergence defines a topology on the space of probability measures for which continuity and sequential continuity coincide (see e.g. [Kis60, Dud64, Haz07]), so it is without loss of generality that we consider only sequences rather than nets in the rest of this section. Note that the information balls $\{\mu \in M^1 \mid D_{\phi}(\mu \mid \nu) < \tau\}$ for $\tau > 0$ need not be neighborhoods of $\nu$ in this topology, and the information balls do not in general define a basis of neighborhoods for a topology on the space of probability measures [Csi62, Csi63, Csi69, Dud98].
This has been studied in the specific case of the Kullback–Leibler divergence by Harremoës, who showed [Har07, Theorem 25] that $D(\nu_n \parallel \nu) \to 0$ implies $|\nu_n(g) - \nu(g)| \to 0$ for every non-negative function $g$ whose moment generating function is finite at some positive real (in fact, the converse was also shown in the same paper under a so-called power-dominance condition on $\nu$). In this section, we generalize this to an arbitrary $\phi$-divergence and show that convergence in $\phi$-divergence implies $\nu_n(g) \to \nu(g)$ if and only if $g$ is $(\phi, \nu)$-subexponential.

This question is also closely related to the one of understanding the relationship between weak convergence and modular convergence in Orlicz spaces (e.g. [Nak50] or [Mus83]). Although convergence in $\phi$-divergence as defined above only formally coincides with the notion of modular convergence when $\phi$ is symmetric about 1 (though this can sometimes be relaxed [Her67]) and satisfies the so-called $\Delta_2$ growth condition, it is possible that this line of work could be adapted to the question studied in this section.

We start with the following proposition, showing that this question is equivalent to the differentiability of $\mathcal{L}_{g,\nu}$ at 0.

**Proposition 5.4.1.** Let $\nu \in M^1$, $g \in L^1(\nu)$, and $M \subseteq M^1$ be a convex set of measures integrating $g$ and containing $\nu$. Then the following are equivalent:

1. $\lim_{n \to \infty} \nu_n(g) = \nu(g)$ for all $(\nu_n)_{n \in \mathbb{N}} \in M^\infty$ such that $\lim_{n \to \infty} D_\phi(\nu_n \parallel \nu) = 0$.
2. $\mathcal{L}_{g,\nu,M}$ is strictly convex at 0, that is $\mathcal{L}_{g,\nu,M}(\epsilon) = 0$ if and only if $\epsilon = 0$.
3. $\partial \mathcal{L}_{g,\nu,M}^*(0) = \{0\}$, that is $\mathcal{L}_{g,\nu,M}^*$ is differentiable at 0 and $\mathcal{L}_{g,\nu,M}^{**}(0) = 0$.

**Proof.**

(i) $\implies$ (ii) Assume for the sake of contradiction that $\mathcal{L}_{g,\nu,M}(\epsilon) = 0$ for some $\epsilon \neq 0$. Then by definition of $\mathcal{L}_{g,\nu,M}$, there exists a sequence $(\nu_n)_{n \in \mathbb{N}} \in M^\infty$ such that for all $n \in \mathbb{N}$, $D_\phi(\nu_n \parallel \nu) \leq 1/n$ and $\nu_n(g) - \nu(g) = \epsilon$, thus contradicting (i). Hence, $\mathcal{L}_{g,\nu,M}(\epsilon) = 0$ if and only if $\epsilon = 0$, which is equivalent to strict convexity at 0 since $\mathcal{L}_{g,\nu,M}$ is convex with global minimum $\mathcal{L}_{g,\nu,M}(0) = 0$ by Lemma 5.1.2.

(ii) $\implies$ (i) Let $(\nu_n)_{n \in \mathbb{N}} \in M^\infty$ be a sequence such that $\lim_{n \to \infty} D_\phi(\nu_n \parallel \nu) = 0$. By definition of $\mathcal{L}_{g,\nu,M}$, we have that $D_\phi(\nu_n \parallel \nu) \geq \mathcal{L}_{g,\nu,M}(\nu_n(g) - \nu(g)) \geq 0$ for all $n \in \mathbb{N}$, and in particular $\lim_{n \to \infty} \mathcal{L}_{g,\nu,M}(\nu_n(g) - \nu(g)) = 0$. Assume for the sake of contradiction that $\nu_n(g)$ does not converge to $\nu(g)$. This implies the existence of $\epsilon > 0$ such that $|\nu_n(g) - \nu(g)| \geq \epsilon$ for infinitely many $n \in \mathbb{N}$. But then $\mathcal{L}_{g,\nu,M}(\nu_n(g) - \nu(g)) \geq \min\{\mathcal{L}_{g,\nu,M}(\epsilon), \mathcal{L}_{g,\nu,M}(-\epsilon)\} > 0$ for infinitely many $n \in \mathbb{N}$, a contradiction.

(ii) $\iff$ (iii) By a standard characterization of the subdifferential (see e.g. [Zâl02, Theorem 2.4.2(iii)]), we have that $\partial \mathcal{L}_{g,\nu,M}^*(0) = \{x \in \mathbb{R} \mid \mathcal{L}_{g,\nu,M}^*(0) + \mathcal{L}_{g,\nu,M}^**(x) = 0 \cdot x\} = \{x \in \mathbb{R} \mid \mathcal{L}_{g,\nu,M}^**(x) = 0\}$. Since $\mathcal{L}_{g,\nu,M}$ is convex, non-negative, and 0 at 0, this subdifferential contains $\epsilon \neq 0$ if and only if there exists $\epsilon \neq 0$ with $\mathcal{L}_{g,\nu,M}(\epsilon) = 0$. \hfill $\square$

The above proposition characterizes continuity in terms of the differentiability at 0 of the conjugate of the optimal lower bound function, or equivalently by Proposition 5.1.3, differentiability of the function $K_{g,\nu,E}$. In the previous section we investigated in detail the finiteness (or equivalently by convexity, the continuity) of these functions around 0; in this section we show that continuity at 0 is equivalent to differentiability at 0 assuming that $\phi$ is not the constant 0 on a neighborhood of 1.

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Proposition 5.4.2. Assume that $1 \notin \operatorname{int}\{x \in \mathbb{R} \mid \phi(x) = 0\}$. Then for every $\sigma$-ideal $\Xi$, probability measure $\nu \in M_1^c(\Xi)$, and $g \in L^0(\Xi)$, we have that $0 \in \operatorname{int} \operatorname{dom} K_{g,\nu,\Xi}$ if and only if $K'_{g,\nu,\Xi}(0) = 0$.

Proof. If the direction is immediate, since differentiability at 0 implies continuity at 0. Thus, for the remainder of the proof we assume that $K_{g,\nu,\Xi}$ is finite on a neighborhood of 0.

We first consider the case $\phi'(\infty) < \infty$, where Lemma 5.2.1 implies $g \in L^\infty(\Xi)$. Define $B \equiv \operatorname{ess sup}_\Xi |g|$, and let $\sigma \in \{-1, 1\}$ be such that $\phi(1 + \sigma x) > 0$ for all $x > 0$ as exists by assumption on $\phi$. Since $\psi$ is non-negative and $\psi(0) = 0$, a standard characterization of the subdifferential (e.g. [Zal02, Theorem 2.4.2(iii)]) implies that the function $t \mapsto \psi^*(\sigma |t|)$ has derivative 0 at 0. Then for all $t \in \mathbb{R}$, by considering $\lambda = \sigma t B$ in (18), we obtain $K_{g,\nu,\Xi}(t)$ is at most $\nu(\psi^*(tg + \sigma tB)) + \delta_{[\infty, \phi'(\infty)]}(2\sigma |t|B) \leq \psi^*(2\sigma |t|B) + \delta_{[\infty, \phi'(\infty)]}(2\sigma |t|B)$. Now, if $\sigma = -1$ then $2\sigma |t|B \leq \phi'(\infty)$ for all $t$, and if $\sigma = 1$ then necessarily $\phi'(\infty) > 0$ and so $2\sigma |t|B \leq \phi'(\infty)$ for sufficiently small $|t|$. Thus, we have for sufficiently small $|t|$ that $K_{g,\nu,\Xi}(t)$ is between 0 and $\psi^*(2\sigma |t|B)$, both of which are 0 with derivative 0 at 0, completing the proof in this case.

Now, assume that $\phi'(\infty) = \infty$, then we have $K_{g,\nu,\Xi} = K_{g,\nu} = \inf_{\lambda \in \mathbb{R}} f(\cdot, \lambda)$ for $f(t, \lambda) \equiv \nu(\psi^*(tg + \lambda))$. Note that $\psi \geq 0$ implies $f \geq 0$, so since $K_{g,\nu}(0) = f(0, 0) = 0$ we have by standard results in convex analysis (e.g. [Zal02, Theorem 2.6.1(ii)]) that $\partial K_{g,\nu}(0) = \{t^* \mid (t^*, 0) \in \partial f(0, 0)\}$. Furthermore, by assumption $K_{g,\nu}$ is finite on a neighborhood of 0, so $K_{g,\nu} = K_{g,\nu,\Xi}$ for all $c \in \mathbb{R}$, Lemma 5.2.6 implies $\operatorname{int} \operatorname{dom} K_{g,\nu} \times \mathbb{R} \subseteq \operatorname{dom} f$ and in particular, $0 \in \operatorname{int} \operatorname{dom} f$. Thus, defining for each $\omega \in \Omega$ the function $f_\omega(t, \lambda) \equiv \psi^*(t \cdot g(\omega) + \lambda)$ (where here and in the rest of the proof we fix some representative $g \in L^0(\Omega)$), standard results on convex integral functionals (e.g. [Lev68, Theorem 1] or [IT69, Formula (7)]) imply that $(t^*, \lambda^*) \in \partial f(0, 0)$ if and only $(t^*, \lambda^*) = (\nu(t^*), \nu(\lambda^*))$ for measurable functions $t^*_\omega, \lambda^*_\omega : \Omega \to \mathbb{R}$ such that $(t^*_\omega, \lambda^*_\omega) \in \partial f_\omega(0, 0)$ holds $\nu$-a.s.

Now, for each $\omega \in \Omega$, we have that $(t^*_\omega, \lambda^*_\omega) \in \partial f_\omega(0, 0)$ if and only if $\psi^*(t \cdot g(\omega) + \lambda) \geq t^*_\omega \cdot t + \lambda^*_\omega \cdot \lambda$ for all $(t, \lambda) \in \mathbb{R}^2$. By considering $t = 0$, this implies that $\lambda^*_\omega \in \partial \psi^* (0) = \{x \in \mathbb{R} \mid \psi(x) = 0\}$, which is contained in either $\mathbb{R}_{>0}$ or $\mathbb{R}_{<0}$ since $\psi$ is not 0 on a neighborhood of 0. Then since the integral of a function of constant sign is zero if and only if it is zero almost surely, we have that $(t^*_\omega, 0) = (\nu(t^*_\omega), \nu(\lambda^*_\omega))$ if and only if $\lambda^*_\omega = 0$ holds $\nu$-a.s. But $(t^*_\omega, 0) \in \partial f_\omega(0, 0)$ if and only if for all $t \in \mathbb{R}$ we have $t^*_\omega \cdot t \leq \inf_{\lambda} \psi^*(t \cdot g(\omega) + \lambda) = \psi^*(0) = 0$, i.e. if and only if $t^*_\omega = 0$.

Putting this together, we get that $\partial K_{g,\nu}(0) = \{t^* \mid (t^*, 0) \in \partial f(0, 0)\} = \{\nu(t^*_\omega) \mid (t^*_\omega, 0) \in \partial f_\omega(0, 0) \nu$-a.s.$\} = \{\nu(t^*_\omega) \mid t^*_\omega = 0$ $\nu$-a.s.$\} = \{0\}$ and $K'_{g,\nu}(0) = 0$ as desired. \ntype{1}

Remark 5.4.3. If $\phi$ is 0 on a neighborhood of 0, then it is easy to show that $K_{g,\nu}$ is not differentiable at 0 unless $\nu$ is $\nu$-essentially constant. Thus, the above proposition shows that the following are equivalent: (i) $1 \notin \operatorname{int}\{x \in \mathbb{R} \mid \phi(x) = 0\}$, (ii) for every $g$, continuity of $K_{g,\nu}$ at 0 implies differentiability at 0, (iii) $D_\phi(\mu \parallel \nu) = 0$ for probability measures $\mu$ and $\nu$ if and only if $\mu = \nu$.

A similar (but simpler) proof shows that the following are equivalent: (i) $\phi$ strictly convex at 1, (ii) for every $g$, continuity of $\psi(t) \mapsto I_{\phi\gamma}(tg)$ at 0 implies differentiability at 0, and (iii) $D_\phi(\mu \parallel \nu) = 0$ for finite measures $\mu$ and $\nu$ if and only if $\mu = \nu$. The similarity of the statements in both cases suggest there may be a common proof of the equivalences using more general techniques in convex analysis.

Thus, combining the previous two propositions and Proposition 5.1.3 computing the convex conjugate of the optimal lower bound function, we obtain the following theorem.

\ntype{31
Theorem 5.4.4. Assume that $1 \notin \text{int}(\{x \in \mathbb{R} \mid \phi(x) = 0\})$. Then for a \( \sigma \)-ideal \( \Sigma \), \( g \in L^0(\Sigma) \) and \( \nu \in X^1_\Sigma \), writing \( \Xi = \{A \in \mathcal{F} \mid \forall \mu \in X_\Sigma, |\mu|(A) = 0\} \), the following are equivalent:

(i) for all \( (\nu_n)_{n \in \mathbb{N}} \in M^1(\Xi)^\mathbb{N} \), \( \lim_{n \to \infty} D_\phi(\nu_n \parallel \nu) = 0 \) implies that \( g \) is \( \nu_n \)-integrable for sufficiently large \( n \) and \( \lim_{n \to \infty} \nu_n(g) = \nu(g) \).

(ii) for all \( (\nu_n)_{n \in \mathbb{N}} \in (X^1_\Sigma)^\mathbb{N} \), \( \lim_{n \to \infty} D_\phi(\nu_n \parallel \nu) = 0 \) implies \( \lim_{n \to \infty} \nu_n(g) = \nu(g) \).

(iii) \( \partial K_{g,\nu,\Xi}(0) = \{0\} \), i.e. \( K_{g,\nu,\Xi} \) is differentiable at \( 0 \) with \( K_{g,\nu,\Xi}'(0) = 0 \).

(iv) \( 0 \in \text{int}(\text{dom} K_{g,\nu,\Xi}) \), that is, \( g \in L^\infty(\Xi) \) when \( \phi'(\infty) < \infty \) and \( g \in S^+(\nu) \) when \( \phi'(\infty) = \infty \).

Proof. The equivalence of (ii)-(iv) is immediate from Propositions 5.4.1 and 5.4.2 since Proposition 5.1.3 implies \( \mathcal{P}^*_{g,\nu,X_\Sigma} = K_{g,\nu,\Xi} \). That (i) implies (ii) is immediate by definition of \( X^1_\Sigma \). The reformulation of \( 0 \in \text{int}(\text{dom} K_{g,\nu,\Xi}) \) depending on the finiteness of \( \phi'(\infty) \) uses Lemma 5.2.1 and Definition 5.2.3. Finally that (ii) and (iv) implies (i) is immediate when \( \phi'(\infty) < \infty \) — since every \( \mu \in M^1(\Xi) \) integrates every \( g \in L^\infty(\Xi) \) — and follows from Theorem 5.2.10 otherwise. \( \square \)

6 Optimal bounds relating \( \phi \)-divergences and IPMs

In this section we generalize Theorem 5.1.11 on the optimal lower bound function for a single measure and function to the case of sets of measures and measurable functions.

6.1 On the choice of definitions

When considering a class of functions \( \mathcal{G} \), there are several ways to define a lower bound of the divergence in terms of the mean deviation of functions in \( \mathcal{G} \). The first one is to consider the IPM \( d_\mathcal{G} \) induced by \( \mathcal{G} \) and to ask for a function \( L \) such that \( D_\phi(\mu \parallel \nu) \geq L(d_\mathcal{G}(\mu, \nu)) \) for all probability measures \( \mu \) and \( \nu \), leading to the following definition of the optimal bound.

Definition 6.1.1. Let \( \mathcal{G} \subseteq \mathcal{L}^0(\Omega) \) be a non-empty set of measurable functions and let \( N, M \subseteq M^1 \) be two sets of probability measures such that \( \mathcal{G} \subseteq L^1(\nu) \) for every \( \nu \in N \cup M \). The optimal lower bound function \( \mathcal{L}_{\mathcal{G},N,M} : \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0} \) is defined by

\[
\mathcal{L}_{\mathcal{G},N,M}(\varepsilon) \equiv \inf \left\{ D_\phi(\mu \parallel \nu) \mid (\nu, \mu) \in N \times M \land \sup_{g \in \mathcal{G}} \mu(g) - \nu(g) = \varepsilon \right\}.
\]

We also for convenience extend the definition to the negative reals by

\[
\mathcal{L}_{\mathcal{G},N,M}(\varepsilon) \equiv \mathcal{L}_{-\mathcal{G},N,M}(-\varepsilon) = \inf \left\{ D_\phi(\mu \parallel \nu) \mid (\nu, \mu) \in N \times M \land \inf_{g \in \mathcal{G}} \mu(g) - \nu(g) = \varepsilon \right\}
\]

for \( \varepsilon < 0 \) where \( -\mathcal{G} \equiv \{-g \mid g \in \mathcal{G}\} \).

Remark 6.1.2. To motivate the definition of \( \mathcal{L}_{\mathcal{G},N,M} \) on the negative reals, note that the equality \( \sup_{g \in \mathcal{G}} \mu(g) - \nu(g) = \varepsilon \) for \( \varepsilon \geq 0 \) constrains by how “much above 0” an element of \( \mathcal{G} \) can distinguish \( \mu \) and \( \nu \), whereas the constraint \( \inf_{g \in \mathcal{G}} \mu(g) - \nu(g) = -\varepsilon \) analogously constrains how much below 0 an element of \( \mathcal{G} \) can distinguish them. When \( \mathcal{G} \) is closed under negation, then \( \sup_{g \in \mathcal{G}} \mu(g) - \nu(g) = d_\mathcal{G}(\mu, \nu) = -\inf_{g \in \mathcal{G}} \mu(g) - \nu(g) \) and \( \mathcal{L}_{\mathcal{G},N,M} \) is even and exactly quantifies the smallest value taken by the \( \phi \)-divergence given a constraint on the IPM defined by \( \mathcal{G} \).
An alternative definition, using the notations of Definition 6.1.1, is to consider the largest function \( L \) such that \( D_\phi(\mu \parallel \nu) \geq L(\mu(g) - \nu(g)) \) for all \((\nu, \mu) \in N \times M \) and \( g \in \mathcal{G} \). It is easy to see that this function can simply be expressed as

\[
\inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon) = \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon) = \inf_{\nu \in N} \left\{ D_\phi(\mu \parallel \nu) \right\} (\nu, \mu, g) \in N \times M \times \mathcal{G} \land \mu(g) - \nu(g) = \varepsilon .
\]

Observe that \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} = \mathcal{L}_{g,N,M} \) when \( \mathcal{G} = \{g\} \) or \( \mathcal{G} = \{-g, g\} \). More generally, the goal of this section is to explore the relationship between \( \mathcal{L}_{g,N,M} \) and \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \). In particular, we will show that assuming a basic convexity condition on the set of measures \( M \), these functions can differ only on their (at most countably many) discontinuity points.

**Lemma 6.1.3.** Let \( N, M \subseteq M^1 \) be two sets of probability measures with \( N \subseteq M \) and \( M \) convex. Then the functions \( \mathcal{L}_{g,N,M} \) and \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) are non-negative, 0 at 0, and are non-decreasing on the non-negative reals.

**Proof.** It is sufficient to prove the result for \( \mathcal{L}_{g,N,M} \), since the result for \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) follows from the fact that taking infima preserves sign and monotonicity. Non-negativity and being 0 at 0 follow from non-negativity of \( D_\phi(\mu \parallel \nu) \) with \( D_\phi(\nu \parallel \nu) = 0 \).

Fix \( 0 \leq x \leq y \) and consider \( \alpha > \mathcal{L}_{g,N,M}(y) \), so that by definition there exist \( \mu \in M \) and \( \nu \in N \) with \( D_\phi(\mu \parallel \nu) < \alpha \) and \( \sup_{g \in \mathcal{G}} (\mu(g) - \nu(g)) = y \). Define \( \mu' = x/y \cdot \mu + (1 - x/y) \cdot \nu \), which is a probability measure in \( M \) since \( \nu \in N \subseteq M \) and \( M \) is convex. Then we have for every \( g \in \mathcal{G} \) that \( \mu'(g) - \nu(g) = x/y \cdot (\mu(g) - \nu(g)) \), and thus \( \sup_{g \in \mathcal{G}} (\mu'(g) - \nu(g)) = x \). Furthermore, by convexity of \( D_\phi, \nu \) we have \( D_\phi(\mu' \parallel \nu) \leq x/y \cdot D_\phi(\mu \parallel \nu) + (1 - x/y) \cdot D_\phi(\nu \parallel \nu) < x/y \cdot \alpha \leq \alpha \) since \( x/y \leq 1 \). This implies that \( \mathcal{L}_{g,N,M}(x) < \alpha \) and since \( \alpha \) can be made arbitrarily close to \( \mathcal{L}_{g,N,M}(y) \) that \( \mathcal{L}_{g,N,M}(x) \leq \mathcal{L}_{g,N,M}(y) \).

**Remark 6.1.4.** For convex sets of measures \( M \) and \( N \) and a single function \( g \in L^1(\nu) \), a simple adaptation of Lemma 5.1.2 shows that \( \mathcal{L}_{g,N,M} \) is convex, non-decreasing, and non-negative on the non-negative reals. Lemma 6.1.3 extends the latter two properties to the case of \( \mathcal{L}_{g,N,M} \) for a set of functions \( \mathcal{G} \), and in fact its proof shows that \( \mathcal{L}_{g,N,M}(y)/y \) is non-decreasing, which is necessary for convexity. It would be interesting to characterize the set of \( \mathcal{G}, N, \) and \( M \) for which \( \mathcal{L}_{g,N,M} \) and \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) are in fact convex.

**Proposition 6.1.5.** Under the assumptions of Lemma 6.1.3, we have for every \( \varepsilon > 0 \) that

\[
\lim_{\varepsilon' \to \varepsilon} \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon') \leq \mathcal{L}_{g,N,M}(\varepsilon) \leq \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon) ,
\]

with equality if \( \mathcal{L}_{g,N,M} \) is lower semicontinuous (equivalently left-continuous) at \( \varepsilon \) or if \( \mathcal{G} \) is compact in the initial topology on \( L^0 \) induced by the maps \( \langle \mu - \nu, \cdot \rangle \) for \( \mu \in M \) and \( \nu \in N \).

**Proof.** Under the assumptions of Lemma 6.1.3 we have \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) and \( \mathcal{L}_{g,N,M} \) are non-decreasing on the positive reals. Thus, we have

\[
\inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon) = \inf_{\nu \in N} \left\{ D_\phi(\mu \parallel \nu) \right\} (\nu, \mu) \in N \times M \land \exists g \in \mathcal{G}, \mu(g) - \nu(g) = \varepsilon \]

\[
\geq \inf_{\nu \in N} \left\{ D_\phi(\mu \parallel \nu) \right\} (\nu, \mu) \in N \times M \land \sup_{g \in \mathcal{G}} (\mu(g) - \nu(g)) \geq \varepsilon \]

(22)
\[= \inf_{\varepsilon' \geq \varepsilon} \mathcal{L}_{g,N,M}(\varepsilon') = \mathcal{L}_{g,N,M}(\varepsilon) \tag{23}\]

\[= \inf_{\varepsilon' < \varepsilon} \left\{ \mathcal{D}_\phi(\mu \parallel \nu) \left| (\nu, \mu) \in N \times M \wedge \forall \varepsilon' < \varepsilon \exists g \in \mathcal{G}, \mu(g) - \nu(g) \geq \varepsilon' \right\} \]
\[\geq \sup \inf_{\varepsilon' < \varepsilon} \left\{ \mathcal{D}_\phi(\mu \parallel \nu) \left| (\nu, \mu) \in N \times M \wedge \exists g \in \mathcal{G}, (\mu(g) - \nu(g) \geq \varepsilon') \right\} \]
\[= \sup \inf_{\varepsilon' < \varepsilon} \left\{ \mathcal{D}_\phi(\mu \parallel \nu) \left| (\nu, \mu, g) \in N \times M \times \mathcal{G} \wedge \mu(g) - \nu(g) \geq \varepsilon' \right\} \]
\[= \sup \inf_{\varepsilon' < \varepsilon \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon') = \lim_{\varepsilon' \to \varepsilon^-} \inf_{\varepsilon' < \varepsilon \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon') \tag{24}\]

where Eq. (22) is since if there is \( g \in \mathcal{G} \) with \( \mu(g) - \nu(g) = \varepsilon \) then \( \sup_{g \in \mathcal{G}} \mu(g) - \nu(g) \geq \varepsilon \), Eq. (23) is because \( \mathcal{L}_{g,N,M} \) is non-decreasing, and Eq. (24) is because \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) is non-decreasing.

For the equality claims, since \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) is non-decreasing and \( \lim_{\varepsilon' \to \varepsilon^-} \inf_{\varepsilon' < \varepsilon \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon') = \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M}(\varepsilon) \) in this case. If \( \mathcal{G} \) is compact in the claimed topology, then \( \sup_{g \in \mathcal{G}} (\mu(g) - \nu(g)) \) is the supremum of the continuous function \( (\mu - \nu, \cdot) \) on the compact set \( \mathcal{G} \), so that \( \sup_{g \in \mathcal{G}} (\mu(g) - \nu(g)) = \max_{g \in \mathcal{G}} (\mu(g) - \nu(g)) \) and thus Eq. (22) is an equality.

**Corollary 6.1.6.** Under the assumptions of Lemma 6.1.3 we have that \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) and \( \mathcal{L}_{g,N,M} \) are non-increasing on the non-positive reals, non-decreasing on the non-negative reals, 0 at 0, and differ only on their (at most countably many) discontinuity points, at which \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \geq \mathcal{L}_{g,N,M} \). In particular, they have the same convex conjugate and biconjugate.

**Proof.** Applying Proposition 6.1.5 to \( \mathcal{L}_{g,N,M}(-\varepsilon) \) for \( \varepsilon < 0 \) gives the claim for the negative reals. Since the functions share the same lsc regularization (the largest lsc function lower bounding them pointwise), they also share their convex conjugate and biconjugate. \( \Box \)

**Remark 6.1.7.** Corollary 6.1.6 is key because, as we will see in Section 6.2, it lets us reduce the problem of computing the optimal lower bound on an IPM to the case of a single function \( g \) considered in Section 5.

**Remark 6.1.8.** Corollary 6.1.6 also implies that \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) and \( \mathcal{L}_{g,N,M} \) have the same (generalized) inverse. This inverse consists simply of the best bounds on the mean deviation, that is the largest non-positive function \( V \) and smallest non-negative function \( U \) such that \( V(D_\phi(\mu \parallel \nu)) \leq \mu(g) - \nu(g) \leq U(D_\phi(\mu \parallel \nu)) \) for all \( (\mu, \nu, g) \in M \times N \times \mathcal{G} \), or equivalently such that \( d_{\phi}(\mu, \nu) \leq U(D_\phi(\mu \parallel \nu)) \) for all \( (\mu, \nu) \in M \times N \) when \( \mathcal{G} \) is closed under negation. In this language, any discontinuity of \( \inf_{g \in \mathcal{G}} \mathcal{L}_{g,N,M} \) corresponds to an interval on which \( U \) is constant, i.e. in which changing the value of the divergence does not change the largest possible value of \( d_{\phi}(\mu, \nu) \).

We conclude this section with two lemmas showing how the lower bound is preserved under natural transformations of the sets of functions \( \mathcal{G} \) or measures \( M, N \).

**Lemma 6.1.9.** For every set \( \mathcal{G} \subseteq \mathcal{L}(\Omega) \) and pair of measures \( \mu, \nu \in X_\mathcal{G} \), we have that

\[\sup_{g \in \mathcal{G}} (\mu(g) - \nu(g)) = \sup_{g \in \overline{\mathcal{G}}} (\mu(g) - \nu(g))\]

where \( \overline{\mathcal{G}} \) is the \( \sigma(Y_\mathcal{G},X_\mathcal{G}) \)-closed convex hull of \( \mathcal{G} \).
Proof. We have $\mathcal{G} \subseteq \overline{\text{co}} \mathcal{G}$, and furthermore since $\langle \mu - \nu, \cdot \rangle$ is a $(Y, \sigma_{g}, X_{g})$-continuous linear function we have that the set $\{h \in Y_{g} \mid \langle \mu - \nu, h \rangle \leq \sup_{g \in \mathcal{G}}(\langle \mu(g) - \nu(g) \rangle)\}$ is convex, $(Y, \sigma_{g}, X_{g})$-closed, and contains $\mathcal{G}$, and so also contains $\overline{\text{co}} \mathcal{G}$. \hfill \square

Lemma 6.1.10. For every $g \in \mathcal{L}^{0}(\Omega)$, we have $\mathcal{L}^{1+}_{g, \nu, X_{g}^{1}} = \mathcal{L}^{1+}_{g, \nu, X_{g}^{1}}$ where $g_{*}X_{g}^{1} = \{g_{*} \nu \mid \nu \in X_{g}^{1}\}$ is the set of probability measures on $\mathbb{R}$ obtained by pushing forward through $g$ the probability measures $\nu \in X_{g}^{1}$. Furthermore, for every $\nu \in \mathcal{M}^{1}$ and $g \in L^{1}(\nu)$ we have that $\mathcal{L}^{1}_{g, \nu, X_{g}^{1}} = \mathcal{L}^{1+}_{g, \nu, X_{g}^{1}}$.

Proof. We first prove the main claim. As in Example 3.1.4, we have for every $\nu \in X_{g}^{1}$ that $\mu(g) = \nu(g) = \int \text{Id}_{\mathbb{R}} \, dg_{*} \mu = \int \text{Id}_{\mathbb{R}} \, dg_{*} \nu$, so it suffices to show for every $\mu_{0}, \nu_{0} \in X_{g}^{1}$ the existence of $\mu, \nu \in X_{g}^{1}$ with $g_{*} \mu = g_{*} \mu_{0}, g_{*} \nu = g_{*} \nu_{0}$, and $D_{\phi}(g, \mu, g, \nu) = D_{\phi}(\mu \parallel \nu) \leq D_{\phi}(\mu_{0} \parallel \nu_{0})$.

For this, write $\xi = \frac{1}{2}(\mu_{0} + \nu_{0})$ so that $\mu_{0}, \nu_{0} \ll \xi$ and $\xi \in X_{g}^{1}$, and define the measures $\mu, \nu \in \mathcal{M}^{1}(\xi)$ by $d\mu = \frac{d\mu_{0}}{d\xi} \circ g$ and $d\nu = \frac{d\nu_{0}}{d\xi} \circ g$ (note that these are just the conditional expectations of $d\mu_{0}$ and $d\nu_{0}$ with respect to $g$). It remains to show that $\mu$ and $\nu$ have the desired properties, for which we first note that for every (Borel) measurable function $h : \mathbb{R}^{3} \to \mathbb{R} \cup \{+\infty\}$ we have

$$
\int h(\frac{d\mu}{d\xi}, \frac{d\nu}{d\xi}, g) \, d\xi = \int h(\frac{d\mu_{0}}{d\xi}, \frac{d\nu_{0}}{d\xi}, \circ g, g) \, d\xi = \int h(\frac{d\mu_{0}}{d\xi}, \circ g, \circ g, \circ g, g) \, d\xi.
$$

Then taking $h(x, y, z) = x$ we get $\mu(\Omega) = \mu(1_{\Omega}) = g_{*} \mu_{0}(1_{\mathbb{R}}) = \mu_{0}(1_{\Omega}) = 1$, and similarly by taking $h(x, y, z) = y$ we get $\nu(\Omega) = 1$. Taking $h(x, y, z) = x \cdot |z|$ we get $\mu(|g|) = \mu_{0}(|g|) < \infty$ so that $\mu \in X_{g}^{1}$, and similarly by taking $h(x, y, z) = y \cdot |z|$ we get $\nu(|g|) = \nu_{0}(|g|) < \infty$ and $\nu \in X_{g}^{1}$.

Finally, as in Remark 4.1.3, taking $h(x, y, z) = y \cdot \phi(x/y)$ if $y \neq 0$ and $h(x, y, z) = x \cdot \phi(\infty)$ if $y = 0$ gives $D_{\phi}(\mu \parallel \nu) = D_{\phi}(g_{*} \mu_{0} \parallel g_{*} \nu_{0})$, and furthermore Jensen’s inequality implies that $D_{\phi}(\mu \parallel \nu) \leq D_{\phi}(\mu_{0} \parallel \nu_{0})$ since $h$ is convex.

The furthermore claim is analogous after noting that since when $\mu \ll \nu$ and $g \in L^{1}(\nu)$ we can take $\xi = \nu_{0} = \nu$.

\hfill \square

6.2 Derivation of the bound

In this section we give our main results computing optimal lower bounds on a $\phi$-divergence given an integral probability metric. Note that from Section 6.1, the optimal lower bound is simply the infimum of the optimal lower bound $\mathcal{L}^{0}_{g, \nu}$ for each $g \in \mathcal{G}$ and $\nu \in \mathcal{N}$. Since $\mathcal{L}^{0}_{g, \nu} = K_{g, \nu}$ by Proposition 5.1.3, and given the order-reversing property of convex conjugacy, it is natural to consider the best upper bound on $K_{g, \nu}$ which holds uniformly over all $g \in \mathcal{G}$ and $\nu \in \mathcal{N}$. Formally, we have the following definition.

Definition 6.2.1. Let $\Xi$ be a $\sigma$-ideal, $\mathcal{G} \subseteq L^{0}(\Xi)$ be a set of measurable functions, and $\mathcal{N} \subseteq \mathcal{M}^{1}(\Xi)$ be a set of measures. We write $K_{g, N, \Xi}(t) \equiv \sup\{K_{g, \nu, \Xi}(t) \mid (g, \nu) \in \mathcal{G} \times \mathcal{N}\}$ and $K_{g, N}(t) \equiv \sup\{K_{g, \nu}(t) \mid (g, \nu) \in \mathcal{G} \times \mathcal{N}\}$.
Note that $K_{g,N,Ξ}$ is convex and lower semicontinuous as a supremum of convex and lower semicontinuous functions. Furthermore, as alluded to before Definition 6.2.1, we expect $K_{g,N,Ξ}$ to be equal to the conjugate of the optimal lower bound functions. This is stated formally in the following theorem which also gives a sufficient condition under which the optimal lower bound functions are convex and lower semicontinuous (see also Remark 6.2.4 below).

**Theorem 6.2.2.** Let $(X, Y)$ be a dual pair with $X \subseteq M$ and $Y \subseteq L^0(Ξ)$ where $Ξ = \{A \in 𝒯 \mid ∀μ \in X, |μ|(A) = 0\}$. Consider $𝒢 \subseteq Y$ and $N \subseteq X^1 \equiv X \cap M^1$ and assume that $(X, Y)$ is decomposable with respect to all measures in $N$. Then we have

$$L^*_{g,N,X^1} = \left( \inf_{g \in 𝒢} L_{g,N,X^1} \right)^* = K_{g,N,Ξ}. \quad (25)$$

**Proof.** The first equality in (25) follows from Corollary 6.1.6. For the second equality, we have

$$\left( \inf_{g \in 𝒢} L_{g,N,X^1} \right)^* = \left( \inf_{g \in 𝒢} L_{g,ν,X^1} \right)^* = \sup_{g \in 𝒢} L^*_{g,ν,X^1} = \sup_{g \in 𝒢} K_{g,ν,Ξ} = K_{g,N,Ξ},$$

where we used successively the definition of $L_{g,ν,X^1}$, the fact that $(\inf_{α∈A} f_α)^* = \sup_{α∈A} f_α^*$ for any collection $(f_α)_{α∈A}$ of functions, Proposition 5.1.3, and Definition 6.2.1. □

**Remark 6.2.3.** When starting from a set of function $𝒢 \subseteq L^0(Ξ)$ for some σ-ideal $Ξ$, a natural pair to which Theorem 6.2.2 can be applied is the pair $(X_ги, Y_ги)$ from Definition 5.1.12.

**Remark 6.2.4.** Theorem 6.2.2 computes the conjugate of the optimal lower bound functions, but if this function is not convex or lsc and so does not coincide with its biconjugate, it is also useful to discuss what we can be said about $L_{g,N,X^1}$ or $\inf_{g \in 𝒢} L_{g,N,X^1}$ themselves.

First note that for all $g \in 𝒢$ and $ν \in 𝑁$, $L_{g,ν,X^1}$ is convex and non-decreasing over the non-negative reals by Lemma 5.1.2 and under the assumptions of Theorem 6.2.2, $L^*_{g,ν,X^1} = K^*_{g,ν,Ξ}$ by Proposition 5.1.3. Thus, we can apply Lemma 3.2.13 and obtain for all $ε$ that

$$\liminf_{ε′→ε} \inf_{g \in 𝒢} L_{g,N,X^1}(ε′) \leq \inf_{g \in 𝒢} K^*_{g,ν,Ξ}(ε) \leq \inf_{g \in 𝒢} L_{g,N,X^1}(ε).$$

Thus the function $\inf_{(g,ν)∈𝒢×𝑁} K^*_{g,ν,Ξ}$ allows us to recover the function $\inf_{g \in 𝒢} L_{g,N,X^1}$ up to its points of discontinuity which are countable by monotonicity. Similarly, by Corollary 6.1.6 we also recover $L_{g,N,X^1}$ up to its countably many points of discontinuity.

More can be said under additional assumptions. If $L_{g,ν,X^1}$ is lower semicontinuous for each $g \in 𝒢$ and $ν \in 𝑁$ (e.g. when $φ′(∞) = ∞$, $X \subseteq M_ν(ν)$, and $𝒢 \subseteq S^1_φ(ν)$ for all $ν \in 𝑁$ by Corollary 5.3.6), then

$$\inf_{g \in 𝒢} L_{g,N,X^1}(ε) = \inf_{g \in 𝒢} L_{g,ν,X^1}(ε) = \inf_{g \in 𝒢} K^*_{g,ν,Ξ}(ε),$$

Furthermore, if we also know that the function $\inf_{(g,ν)∈𝒢×𝑁} K^*_{g,ν,Ξ}$ is itself convex and lsc, then

$$\inf_{g \in 𝒢} L_{g,N,X^1}(ε) = L_{g,N,X^1}(ε) = K^*_{g,Ν,Ξ}(ε).$$
Similarly to Corollary 5.1.15, we give in the following corollary an “operational” restatement of Theorem 6.2.2 emphasizing the duality between upper bounds on $K_{g,N}$ and lower bounds on $D_\phi(\mu \parallel \nu)$ in terms of $d_\phi(\mu, \nu)$.

**Corollary 6.2.5.** Under the assumptions of Theorem 6.2.2, for every convex and lower semicontinuous function $L : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$, the following are equivalent:

(i) $D_\phi(\mu \parallel \nu) \geq L(d_\phi(\mu, \nu))$ for all $\nu \in N$ and $\mu \in X^1$.

(ii) $D_\phi(\mu \parallel \nu) \geq L(\rho g(\mu) - \rho g(\nu))$ for all $g \in \mathcal{G}$, $\nu \in N$, and $\mu \in X^1$.

(iii) $K_{g,\nu,\mathcal{Z}}(t) \leq L^*(|t|)$ for all $t \in \mathbb{R}$, $g \in \mathcal{G}$, and $\nu \in N$.

**Proof.** The equivalence of (i) and (iii) follows from applying Theorem 6.2.2 to $\mathcal{G}' = \mathcal{G} \cup -\mathcal{G}$, since $d_\phi(\mu, \nu) = \sup_{g \in \mathcal{G}'} \rho (g(\mu) - g(\nu)) \geq 0$, $\mathcal{L}_{\mathcal{G}',N,X^1}$ is even, and $K_{g,\nu,\mathcal{Z}}(t) = \max\{K_{g,\nu,\mathcal{Z}}(t), K_{g,\nu,\mathcal{Z}}(-t)\}$. The equivalence of (i) and (iii) for $\{g, -g\}$ for each $g \in \mathcal{G}$ gives the equivalence of (ii) and (iii). □

**Example 6.2.6** (Subgaussian functions). For the Kullback–Leibler divergence, [BLM13, Lemma 4.18] shows that $D(\mu \parallel \nu) \geq \frac{1}{2}d_\phi(\mu, \nu)^2$ for all $\mu \in \mathcal{M}^1$ if and only if $\log \int e^{t(g(\mu) - g(\nu))} \, d\nu \leq t^2/2$ for all $g \in \mathcal{G}$ and $t \in \mathbb{R}$. Such a quadratic upper bound on the log moment-generating function is one of the characterizations of the so-called subgaussian functions, which contain as a special case the class of bounded functions by Hoeffding’s lemma [Hoe63] (see also Example 6.3.16). Corollary 6.2.5 recovers this result by considering the (self-conjugate) function $L : t \mapsto t^2/2$, thus showing that Pinsker’s inequality generalizes to all subgaussian functions.

Theorem 6.2.2 generalizes this further to an arbitrary $\phi$-divergence, showing that a subset $\mathcal{G} \subseteq \mathcal{L}^0(\Omega)$ of measurable functions satisfies $D_\phi(\mu \parallel \nu) \geq \frac{1}{2}d_\phi(\mu, \nu)^2$ for all $\mu \in \mathcal{M}^1$ if and only if $K_{\mathcal{G},\nu}(t) \leq t^2/2$ for all $g \in \mathcal{G}$ and $t \in \mathbb{R}$. By analogy, we refer to functions whose cumulant generating function admits such a quadratic upper bound as $\phi$-subgaussian functions.

**Example 6.2.7.** Recall from Example 5.1.16 that the $\chi^2$-divergence given by $\phi(x) = (x - 1)^2 + \delta_{\mathbb{R}, \{0\}}(x)$ satisfies

$$
\psi^*(x) = \begin{cases} 
  x^2/4 & x \geq -2 \\
  -1 - x & x < -2 
\end{cases}
$$

and $K_{\mathcal{G},\nu}(t) \leq \inf_{\lambda} \int (tg + \lambda)^2/4 \, d\nu = t^2 \text{Var}_\nu(g)/4$, showing that the class of $\chi^2$-subgaussian functions (see Example 6.2.6) includes all those with bounded variance.

**Example 6.2.8.** As a step towards understanding the Wasserstein distance, Bolley and Villani [BV05] define a “weighted total variation distance” between probability measures $\mu$ and $\nu$ as $\int g \, d|\mu - \nu|$ for some non-negative measurable function $g \in \mathcal{L}^0(\Omega)$, and their main result [BV05, Theorem 2.1] bounds this weighted total variation in terms of the KL divergence.

We rederive their result by noting that the $g$-weighted total variation is $d_{\mathcal{G}B}(\mu, \nu)$ for $gB = \{g \cdot b \mid b \in \mathcal{B}\}$ where $\mathcal{B}$ is the set of measurable functions taking values in $[-1, 1]$, so that it suffices by Theorem 6.2.2 to upper bound $K_{g,b,\nu}(t)$ for each $b \in \mathcal{B}$ in terms of $\log \int e^{g} \, d\nu$ or $\log \int e^{g^2} \, d\nu$. But since $g \geq 0$, we have $g \cdot b \leq |g| = g$ and we conclude by using the fact that finiteness of $\log \int e^{g} \, d\nu$ (resp. $\log \int e^{g^2} \, d\nu$) implies a quadratic upper bound on the centered log-moment generating function $K_{h,\nu}(t)$ for $|t| \leq 1/4$ (resp. all $t \in \mathbb{R}$) for any non-negative function $h$ (see e.g. [Ver18, Propositions 2.5.2 and 2.7.1]).
Finally, we show that when we take $N = X^1$ in Theorem 6.2.2, that is, we want a lower bound $L$ such that $D_\phi (\mu \parallel \nu) \geq L(d_\phi (\mu, \nu))$ for all probability measures $\mu$ and $\nu$ in $X$, we no longer need to consider pairs of measures such that $\mu \not\ll \nu$, and in particular we can ignore the $\sigma$-ideal $\Xi$ in the derivation of the bound. Intuitively, this is because when $\mu \not\ll \nu$, we now have sufficiently many measures in $N$ to approximate $\nu$ with a measure $\nu'$ such that $\mu \ll \nu'$.

**Theorem 6.2.9.** Let $(X, Y)$ be a dual pair with $X \subseteq M$ and assume that $(X, Y)$ is decomposable with respect to all probability measures in $X$. Then for all subsets of functions $\mathcal{G} \subseteq Y$,

$$\mathcal{L}^*_{gX^1, X^1} = \left( \inf_{g \in \mathcal{G}} \mathcal{L}_{gX^1, X^1} \right)^* = K_{gX^1} .$$

In particular, for any $\sigma$-ideal $\Sigma$ and $\mathcal{G} \subseteq L^0(\Sigma)$, the following are equivalent for every convex lsc $L : \mathbb{R}_{\geq 0} \rightarrow \mathbb{R}$:

1. $D_\phi (\mu \parallel \nu) \geq L(d_\phi (\mu, \nu))$ for all $\mu, \nu \in M_c(\Sigma)$ integrating all of $\mathcal{G}$.
2. $D_\phi (\mu \parallel \nu) \geq L(\mu(g) - \nu(g))$ for all $g \in \mathcal{G}$ and $\mu, \nu \in M_c(\Sigma)$ integrating all of $\mathcal{G}$.
3. $K_{g, \nu} (t) \leq L^* (\langle 1 \rangle)$ for all $t \in \mathbb{R}$, $g \in \mathcal{G}$, and $\nu \in M_c(\Sigma)$ integrating all of $\mathcal{G}$.

**Proof.** The in particular claim follows from the main claim applied to $(X, g, Y, \Sigma)$ by an argument analogous to that of Corollary 6.2.5. For the main claim, by Theorem 6.2.2, it suffices to show that $\inf_{g \in \mathcal{G}} \mathcal{L}_{gX^1, X^1} = \inf_{g \in \mathcal{G}, \nu \in X^1} \mathcal{L}_{g\nu, X^1}$ and $\inf_{g \in \mathcal{G}, \nu \in X^1, \nu \ll \mu} \mathcal{L}_{g\nu, X^1 \cap M_c(\nu)}$ have the same conjugate, or simply the same lsc regularization. Since the former is definitionaly no larger than the latter, it suffices to show that any lsc lower bound $L$ for the latter also lower bounds the former, equivalently, that if $D_\phi (\mu \parallel \nu) \geq L(\mu(g) - \nu(g))$ for all $\mu \ll \nu \in X^1$ and $g \in \mathcal{G}$, then this also holds for all $\mu, \nu \in X^1$.

Given any $\mu, \nu \in X^1$ and $\delta \in [0, 1]$, let $\nu_\delta = (1 - \delta) \cdot \nu + \delta \cdot \mu$ so that $\nu_\delta \in X^1$. Then for each $\delta \in [0, 1]$ we have that $\mu(g) - \nu_\delta (g) = (1 - \delta) (\mu(g) - \nu(g))$ for all $g \in \mathcal{G}$, and furthermore, by convexity of $D_\phi (\mu \parallel \cdot)$, we have for $\delta \in (0, 1]$ that

$$(1 - \delta) D_\phi (\mu \parallel \nu) = (1 - \delta) D_\phi (\mu \parallel \nu) + \delta D_\phi (\mu \parallel \mu) \geq D_\phi (\mu \parallel \nu_\delta) \geq L((1 - \delta)(\mu(g) - \nu(g)))$$

where the last inequality is because $\mu \ll \nu_\delta$. But since $L$ is lower semicontinuous, we have that $L(\mu(g) - \nu(g)) \leq \liminf_{\delta \rightarrow 0} L((1 - \delta)(\mu(g) - \nu(g))) \leq \lim_{\delta \rightarrow 0} L((1 - \delta)(\mu(g) - \nu(g)))$, and so we get that $D_\phi (\mu \parallel \nu) \geq L(\mu(g) - \nu(g))$ as desired. \qed

### 6.3 Application to bounded functions and the total variation

In this section, we consider the problem of lower bounding the $\phi$-divergence by a function of the total variation distance. Though it is a well-studied problem and most of the results we derive are already known, we consider this case to demonstrate the applicability of the results obtained in Section 6.2. In Section 6.3.1, we study Vajda’s problem [Vaj72]: obtaining the best lower bound of the $\phi$-divergence by a function of the total variation distance, and in Section 6.3.2 we show how to obtain quadratic relaxations of the best lower bound as in Pinsker’s inequality and Hoeffding’s lemma.
6.3.1 Vajda’s problem

The Vajda problem [Vaj72] is to quantify the optimal relationship between the $\phi$-divergence and the total variation, that is to compute the function

$$L_{\mathcal{B}, M^1, M^1}(\varepsilon) = \inf \{ D(\mu \| \nu) \mid (\mu, \nu) \in M^1 \times M^1 \wedge TV(\mu, \nu) = \varepsilon \}$$

$$= \inf \{ D(\phi(\mu \| \nu)) \mid (\mu, \nu) \in M^1 \times M^1 \wedge d_\mathcal{B}(\mu, \nu) = \varepsilon \}$$

where $\mathcal{B}$ is the set of measurable functions $\Omega \to [-1, 1]$. In this section, we use Theorem 6.2.9 to give for an arbitrary $\phi$ an expression for the Vajda function as the convex conjugate of a natural geometric quantity associated with the function $\psi^\star$, the inverse of its sublevel set volume function, which we call the height-for-width function.

**Definition 6.3.1.** The sublevel set volume function $\text{sls}_{\psi^\star} : \mathbb{R}_{\geq 0} \to \mathbb{R}_{\geq 0}$ maps $h \in \mathbb{R}$ to the Lebesgue measure of the sublevel set $\{x \in \mathbb{R} \mid \psi^\star(x) \leq h\}$. Since $\psi^\star$ is convex and inf-compact, the sublevel sets are compact intervals and their Lebesgue measure is simply their length.

The height-for-width function $\text{hgt}_{\psi^\star} : \mathbb{R}_{\geq 0} \to \mathbb{R}$ is the (right) inverse of the sublevel set volume function given by $\text{hgt}_{\psi^\star}(w) = \inf \{ h \in \mathbb{R} \mid \text{sls}_{\psi^\star}(h) \geq w \}$.

To understand this definition, note that since $\psi^\star$ is defined on $\mathbb{R}$, the sublevel set volume function can be interpreted as giving for each height $h$ the length of longest horizontal line segment that can be placed in the epigraph of $\psi^\star$ but no higher than $h$. The inverse, the height-for-width function, asks for the minimal height at which one can place a horizontal line segment of length $w$ in the epigraph of $\psi^\star$. See Fig. 1 for an illustration of this in the case of $\psi^\star(x) = e^x - x - 1$, corresponding to the Kullback–Leibler divergence.

The following lemma shows that the height-for-width function can be equivalently formulated as the optimal value of a simple convex optimization problem.

**Lemma 6.3.2.** For all $w \in \mathbb{R}_{\geq 0}$, $\text{hgt}_{\psi^\star}(w) = \inf_{\lambda \in \mathbb{R}} \max\{ \psi^\star(\lambda + w/2), \psi^\star(\lambda - w/2) \}$. Furthermore, if for $w > 0$ there exists $\lambda_w$ such that $\psi^\star(\lambda_w - w/2) = \psi^\star(\lambda_w + w/2)$, then $\text{hgt}_{\psi^\star}(w) = \psi^\star(\lambda_w - w/2) = \psi^\star(\lambda_w + w/2)$.

**Proof.** For every $w \geq 0$, define the function $h_w : \lambda \mapsto \max\{ \psi^\star(\lambda - w/2), \psi^\star(\lambda + w/2) \}$ which is the supremum of two convex inf-compact functions with overlapping domain, and so is itself proper, convex, and inf-compact. In particular, $h_w$ achieves its global minimum $y_w \in \mathbb{R}$, where by definition and convexity of $\psi^\star$ we have $y_w$ is the smallest number such that there exists an interval $[\lambda - w/2, \lambda + w/2]$ of length $w$ such that $\psi^\star((\lambda - w/2, \lambda + w/2)) \subseteq (-\infty, y_w]$, and thus $y_w = \inf \{ x \in \mathbb{R} \mid \text{sls}_{\psi^\star}(x) \geq w \} = \text{hgt}_{\psi^\star}(w)$ as desired.

For the remaining claim, consider $w > 0$ for which there is $\lambda_w \in \mathbb{R}$ such that $\psi^\star(\lambda_w - w/2) = \psi^\star(\lambda_w + w/2)$. By convexity of $\psi^\star$ we have for every $\lambda < \lambda_w$ that $\psi^\star(\lambda - w/2) \geq \psi^\star(\lambda_w - w/2)$, and analogously for every $\lambda > \lambda_w$ that $\psi^\star(\lambda + w/2) \geq \psi^\star(\lambda_w + w/2)$. Thus for every $\lambda$ we have $\max\{ \psi^\star(\lambda - w/2), \psi^\star(\lambda + w/2) \} = \min\{ \psi^\star(\lambda_w - w/2), \psi^\star(\lambda_w + w/2) \} = \psi^\star(\lambda_w - w/2) = \psi^\star(\lambda_w + w/2)$, so the result follows from the main claim.

**Example 6.3.3.** For the case of the KL divergence for which $\psi^\star(w) = e^w - w - 1$, one can compute that $\psi^\star(\lambda(w) + w/2) = \psi^\star(\lambda(w) - w/2)$ for $\lambda(w) = -\log \frac{e^{w/2} - e^{-w/2}}{w} = -\log \frac{2\sinh(w/2)}{w}$, so that $\text{hgt}_{\psi^\star}(w) = -1 + \frac{w}{2} \coth \frac{w}{2} + \log \frac{2\sinh(w/2)}{w}$. 

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The duality result of Theorem 6.2.9 computes the biconjugate of the optimal bound $\mathcal{L}_{\mathcal{B}, M^1, M^1}$, so we first prove that this function is convex and lsc.

**Lemma 6.3.4.** Let $M$ the set of probability measures supported on $\{-1, 1\}$. Then $\mathcal{L}_{\mathcal{B}, M^1, M^1} = \mathcal{L}_{\text{Id}_{\{-1,1\}}, M, M}$ is convex and lower semicontinuous. In particular $\mathcal{L}_{\mathcal{B}, M^1, M^1}(\varepsilon) = K_{\mathcal{B}, M^1}(\varepsilon)$ for $\varepsilon \geq 0$.

*Proof.* By Theorem 6.2.9 we have that $\mathcal{L}_{\mathcal{B}, M^1, M^1} = K_{\mathcal{B}, M^1}$, so the in particular statement follows immediately from the main claim. The main claim, that $\mathcal{L}_{\mathcal{B}, M^1, M^1} = \mathcal{L}_{\text{Id}_{\{-1,1\}}, M, M}$ is convex and lower semicontinuous, is well-known and can easily be derived using the methods of e.g. [Vaj72], but we include a proof here in our language for completeness and to illustrate how it could be generalized beyond the total variation.

Note that the set $\mathcal{B} = [-1, 1]^2 \cap \mathcal{L}^0(\Omega)$ is convex, and furthermore is $\sigma(\mathcal{L}^b(\Omega), \mathcal{M})$-compact by the Banach–Alaoglu theorem, and so by the Krein–Milman theorem $\mathcal{B}$ is the $\sigma(\mathcal{L}^b(\Omega), \mathcal{M})$-closed convex hull of its extreme points $\text{ext}(\mathcal{B}) = \{-1, 1\}^2 \cap \mathcal{L}^0(\Omega)$ the set of measurable $\{-1, 1\}$-valued functions. Thus, Lemma 6.1.9 implies $d_B = d_{\text{ext}(\mathcal{B})}$, and so $\mathcal{L}_{\mathcal{B}, M^1, M^1} = \mathcal{L}_{\text{ext}(\mathcal{B}), M^1, M^1}$.

We now prove that $\inf_{g \in \text{ext}(\mathcal{B})} \mathcal{L}_{g, M^1}$ is convex and lsc, which by Corollary 6.1.6 also implies $\mathcal{L}_{\text{ext}(\mathcal{B}), M^1, M^1} = \inf_{g \in \text{ext}(\mathcal{B})} \mathcal{L}_{g, M^1}$ is convex and lsc. By Lemma 6.1.10, for each $g \in \text{ext}(\mathcal{B})$ we have $\mathcal{L}_{g, M^1} = \mathcal{L}_{\text{Id}_{\{-1,1\}}, M, M}$ for $M_g = \{g_\mu, \mu \in M^1\}$. In particular, if $g$ is constant this set is the singleton $M_g = \{\delta_{g(\Omega)}\}$, and if $g$ is non-constant then it is exactly the set $M$ of probability measures supported on $\{-1, 1\}$. Thus, $\inf_{g \in \text{ext}(\mathcal{B})} \mathcal{L}_{g, M^1} = \mathcal{L}_{\text{Id}_{\{-1,1\}}, M, M}$.

Note that the set $M$ with the total variation norm is homeomorphic to the unit interval $[0, 1]$ via the linear map $p \mapsto p \cdot \delta_{(1)} + (1 - p) \cdot \delta_{(-1)}$. Then the function $f : \mathbb{R} \times M^2 \rightarrow \mathbb{R}$ given by $f(\varepsilon, (\mu, \nu)) = D_\varepsilon(\mu \parallel \nu) + \delta_0(\mu(\text{Id}_{\{-1,1\}}) - \nu(\text{Id}_{\{-1,1\}}) - \varepsilon)$ is jointly convex and lower semicontinuous, and hence since $M$ is compact also inf-compact. Thus, by Lemma 3.2.4, the function $\mathcal{L}_{\text{Id}_{\{-1,1\}}, M, M} = \inf_{(\mu, \nu) \in M^2} f(\cdot, (\mu, \nu))$ is convex and inf-compact as desired. \hfill $\square$

Lemma 6.3.4 implies that it suffices to compute $K_{\mathcal{B}, M^1}$.

**Lemma 6.3.5.** $K_{\mathcal{B}, M^1}(t) = \text{hgt}_{\psi^*}(2t)$ for every $t \geq 0$.

*Proof.* For $M = \{p \cdot \delta_{(1)} + (1 - p) \cdot \delta_{(-1)} \mid p \in [0, 1]\}$, we have by Lemma 6.3.4 and Theorem 6.2.9 that $K_{\mathcal{B}, M^1} = \mathcal{L}_{\mathcal{B}, M^1, M^1} = \mathcal{L}_{\text{Id}_{\{-1,1\}}, M, M} = \sup_{\nu \in M} K_{\text{Id}_{\{-1,1\}}, \nu}$. For $p \in [0, 1]$ we have

![Figure 1: Illustration of height-for-width function for $\psi^*(x) = e^x - x - 1$](image)
This mixed optimization problem is convex in $\lambda$ for each $p$ and linear in $p$ for each $\lambda \in \mathbb{R}$, and the interval $[0,1]$ is compact, so by the Sion minimax theorem [Sio58] we can swap the supremum and infimum to get

$$K_{\mathcal{B},\mathcal{M}^t}(t) = \inf_{\lambda \in \mathbb{R}} \sup_{p \in [0,1]} (p \cdot \psi^*(\lambda + t) + (1-p) \cdot \psi^*(\lambda - t))$$

so the claim follows from Lemma 6.3.2. \(\square\)

**Example 6.3.6.** For the Kullback–Leibler divergence, since $K_{\mathcal{B},\mathcal{B}^*}(t) = \log \nu(e^{t(g - v(g))})$ as in Example 4.3.6, Lemma 6.3.5 and Example 6.3.3 imply that the optimal bound on the cumulant generating function of a random variable $g$ with $v(g) = 0$ and $m \leq g \leq M \nu$-a.s. $\log \nu(e^{t g}) \leq h_{\psi^*}(t) = -(1 + \frac{M-m}{2} \coth t - \frac{M-m}{2} + \log \frac{2 \sinh((M-m)\nu/2)}{\nu})$. This is a refinement of Hoeffding’s lemma, which gives the upper bound of $(M-m)^2 t^2/8$, which we will also derive as a consequence of a general quadratic relaxation on the height function in Example 6.3.16.

**Corollary 6.3.7.** $\mathcal{L}_{\mathcal{B},\mathcal{M}^t,\mathcal{M}^t}(\epsilon) = h_{\psi^*}(\epsilon/2)$ for all $\epsilon \geq 0$. In particular, if $h_{\psi^*}$ is differentiable then $\mathcal{L}_{\mathcal{B},\mathcal{M}^t,\mathcal{M}^t}(2 h_{\psi^*}(\epsilon/2)) = x h_{\psi^*}(x) - h_{\psi^*}(x)$.

**Proof.** The main claim is immediate from Lemmas 6.3.4 and 6.3.5, and the supplemental claim follows from the explicit expression for the convex conjugate for differentiable functions. \(\square\)

**Example 6.3.8.** For the Kullback–Leibler divergence, using Example 6.3.3, the supplemental claim of Corollary 6.3.7 applied to $x = 2t$ gives $\mathcal{L}_{\mathcal{B},\mathcal{M}^t,\mathcal{M}^t}(t) = \log \frac{t}{\sinh^2 t} + t \coth t - \frac{t^2}{\sinh^2 t}$ for $V(t) = 2 \coth t - \frac{t}{\sinh^2 t} - 1/t$, which is exactly the formula derived by [FHT03].

**Remark 6.3.9.** Corollary 6.3.7 shows that lower bounds on the $\psi$-divergence in terms of the total variation are equivalent to upper bounds on the height-for-width function $h_{\psi^*}$, equivalently to lower bounds on the sublevel set volume function of $\psi^*$. The complementary problem of obtaining upper bounds on the sublevel set volume function is of interest in harmonic analysis due to its connection to studying oscillatory integrals (e.g. [Ste93, Chapter 8, Proposition 2] and [CCW99, §1-2]), and it would be interesting to see if techniques from that literature could be applied in this context.

**Remark 6.3.10.** Since the total variation $TV(\mu, \nu)$ is symmetric in terms of $\mu$ and $\nu$, the optimal lower bound on $D_\phi(\mu \parallel \nu)$ in terms of $TV(\mu, \nu)$ is the same as the optimal lower bound on $D_\phi(\nu \parallel \mu) = D_\phi(\nu \parallel \nu)$ for $\phi^\dagger = x \phi(1/x)$. By Corollary 6.3.7, this implies that $h_{\psi^*} = h_{\mathcal{S}_x(\psi^*)}$ (note that this can also be derived directly from the definition).
6.3.2 Application to Pinsker-type inequalities

Corollary 6.3.7 implies that to obtain Pinsker-type inequalities, it suffices to upper bound the height function \( \text{hgt}_{\psi^*}(t) \) by a quadratic function of \( t \). In this section, we show such bounds under mild assumptions on \( \psi^* \), both rederiving optimal Pinsker-type inequalities for the Kullback–Leibler divergence and \( \alpha \)-divergences for \(-1 \leq \alpha \leq 2\) due to Gilardoni [Gil10], and deriving new but not necessarily optimal Pinsker-type inequalities for all \( \alpha \in \mathbb{R} \). We proceed by giving two arguments approximating the minimizer \( \lambda(t) \) in the optimization problem defining the height (Lemma 6.3.2), and an argument that works directly with the optimal \( \lambda(t) \).

We begin with the crudest but most widely applicable bound.

**Corollary 6.3.11.** If \( \phi \) is twice differentiable on its domain and \( \phi'' \) is monotone, then \( \text{hgt}_{\psi^*}(t) \leq t^2/(2\phi''(1)) \) for all \( t \geq 0 \). Equivalently, for such \( \phi \) we have that \( D_\phi(\mu \parallel \nu) \geq \frac{\phi''(1)}{8} \cdot \text{TV}(\mu, \nu)^2 \) for all \( \mu, \nu \in M^1 \).

**Proof.** If \( \phi''(1) = 0 \), then the claim is trivial, so we assume that \( \phi''(1) > 0 \). If \( \phi'' \) is non-decreasing, we have by Taylor’s theorem that \( \phi(x) \geq \frac{\phi''(1)}{2}(x-1)^2 \) for \( x \geq 1 \), and equivalently \( \psi(x) \geq \frac{\phi''(1)}{2}x^2 \) for \( x \geq 0 \), so that \( \psi^*(x) \leq \frac{1}{2\phi''(1)}x^2 \) for \( x \geq 0 \). Then \( \text{hgt}_{\psi^*}(t) = \inf_{\lambda \in \mathbb{R}} \max\{\psi^*(\lambda - t/2), \psi^*(\lambda + t/2)\} \leq \max\{\psi^*(0), \psi^*(t)\} \leq t^2/(2\phi''(1)) \). On the other hand, if \( \phi'' \) is non-increasing, then analogously we have \( \psi^*(x) \leq \frac{1}{2\phi''(1)}x^2 \) for \( x \leq 0 \), so that \( \text{hgt}_{\psi^*}(t) = \inf_{\lambda \in \mathbb{R}} \max\{\psi^*(\lambda - t/2), \psi^*(\lambda + t/2)\} \leq \max\{\psi^*(0), \psi^*(-t)\} \leq t^2/(2\phi''(1)) \).

**Example 6.3.12.** Most of the standard \( \alpha \)-divergences satisfy the condition of Corollary 6.3.11, in particular the \( \alpha \)-divergences given by \( \phi_\alpha = \frac{x^\alpha - \alpha(x-1) - 1}{\alpha(x-1)} \) have \( \phi''_\alpha(x) = x^{\alpha-2} \) which is monotone for all \( \alpha \). As a result, we get for all \( \alpha \) the (possibly suboptimal) Pinsker inequality \( D_{\phi_\alpha}(\mu \parallel \nu) \geq \frac{1}{8} \cdot \text{TV}(\mu, \nu)^2 \) for all \( \mu, \nu \in M^1 \). Such a bound appears to be new for \( \alpha > 2 \), but for \( \alpha \in [-1, 2] \) Gilardoni [Gil10] established the better bound \( D_{\phi_\alpha}(\mu \parallel \nu) \geq \frac{1}{2} \cdot \text{TV}(\mu, \nu)^2 \), extending the standard case of the Kullback–Leibler divergence \( \alpha = 1 \). We rederive this optimal constant for these divergences below, and also give general conditions under which such bounds hold.

Corollary 6.3.11 used the crude linear relaxation \(-t/2 \leq \lambda(t) \leq t/2 \). In the following Corollary, we derive a tighter Pinsker-type inequality by using a Taylor expansion of \( \lambda(t) \).

**Corollary 6.3.13.** Suppose that \( \phi \) strictly convex and twice differentiable on its domain, thrice differentiable at 1 and that

\[
\frac{27\phi''''(1)}{(3-z\phi''''(1)/\phi''(1))^3} \leq \phi''(1 + z)
\]

for all \( z \geq -1 \). Then \( \text{hgt}_{\psi^*}(t) \leq t^2/(8\phi''(1)) \) for all \( t \geq 0 \), equivalently, for such \( \phi \) we have \( D_\phi(\mu \parallel \nu) \geq \frac{\phi''(1)}{2} \cdot \text{TV}(\mu, \nu)^2 \) for all \( \mu, \nu \in M^1 \).

**Remark 6.3.14.** The Pinsker constant in Corollary 6.3.13 is best-possible, since if \( \phi \) is twice-differentiable at 1, then Taylor’s theorem gives the local expansion \( \phi(x) = \phi''(1)/2 \cdot (x-1)^2 + o((x-1)^2) \), and thus the distributions \( \mu_\epsilon = (1/2 + \epsilon/2, 1/2 - \epsilon/2) \) and \( \nu = (1/2, 1/2) \) on the set \( \{0, 1\} \) have \( \text{TV}(\mu_\epsilon, \nu) = \epsilon \) and \( D_\phi(\mu_\epsilon \parallel \nu) = \phi''(1)/2 \cdot \epsilon^2 + o(\epsilon^2) \).
Suppose that Lemma 6.3.17.\[\infty = \lim_{t \to 1} \frac{\lambda}{\phi''(1)/\phi''(1)^2}\]. Taking this as given, we show under the stated assumptions of the proposition that for \(L(t) = \frac{-ct^2}{24}\) and \(c = \frac{-\phi''(1)/\phi''(1)^2}{2}\), we have that \(\psi^*(L(t) + st/2) \leq t^2/(8\phi''(1))\) for \(s \in \{\pm 1\}\). Since both sides are 0 at 0, it thus suffices to show \((L'(t) + s^2/2)(\psi^*)(L(t) + st/2) \leq t/(4\phi''(1))\). Now, let \(\leq \) indicate \(\leq 0\) and \(\geq \) if \(L'(t) + s^2/2 \geq 0\) and = \(\geq 0\) and \(\leq 0\) if \(L'(t) + s^2/2 \leq 0\). Since \(\psi\) strictly convex implies \(\psi' = ((\psi^*)')^{-1}\) is strictly increasing, we thus have that this is equivalent to

\[
L(t) + st/2 \leq \psi'\left(\frac{t}{4\phi''(1)}\right)
\]

Write \(z = \frac{t/4\phi''(1)}{L'(t) + s^2/2} = \frac{t}{4\phi''(1)}\) so that \(z\) has the same sign as \(L'(t) + s^2/2\) and \(t = \frac{6az\phi''(1)}{3cz\phi''(1)}\). Plugging this in and using the fact that \(s^2 = 1\), we wish to show that

\[
\frac{3z\phi''(1) + cz\phi'(1)}{2(3 + cz\phi''(1))} - \psi'(z) \leq 0
\]

for all \(z\) such that \(t \geq 0\). The left hand side of Eq. (28) is 0 at 0, so since \(z > 0\) implies \(\leq \) is \(\leq 0\) and \(z < 0\) implies \(\geq \) is \(\geq 0\), it suffices to show that the derivative of the left-hand side of Eq. (28) with respect to \(z\) is non-positive for all \(z\). This derivative is

\[
\frac{27\phi''(1)}{(3 + cz\phi''(1))} - \phi''(z) = \frac{27\phi''(1)}{(3 - z\phi''(1)/\phi''(1)^2) - \phi''(1 + z)}
\]

which since \(\text{dom} \psi \subseteq [-1, \infty)\) is non-positive for all \(z\) if and only if it is non-positive for all \(z \geq -1\).

Example 6.3.15 ([Gil10]). For the \(\alpha\)-divergences, we have \(\phi_2''(x) = x^{2-\alpha} - 3\) and \(\phi_2''(x) = (\alpha - 2)x^{2-\alpha}\) so that Corollary 6.3.13 is equivalent to the condition \(\frac{27}{(3 + (2 - \alpha)x)} \leq (1 + z)^{2-\alpha}\) for \(z \geq -1\).

Note that this is true for \(z = 0\) for all \(\alpha\), and the derivative of \(\frac{27}{(3 + (2 - \alpha)x)}\) with respect to \(z\) is \(\frac{27(\alpha - 2)(\alpha + 1)(1 + z)^{-2}}{(3 + (2 - \alpha)x)^3}\). Thus, for \(\alpha \in [-1, 2]\) the sign of the derivative is the opposite of the sign of \(z\), and the condition holds for all \(z \geq -1\), recovering the result of Gilardoni [Gil10] as desired.

Example 6.3.16. For the case of the Kullback–Leibler divergence, Example 6.3.15 rederives Pinsker’s inequality and Hoffding’s lemma.

Finally, we show that one can also obtain optimal Pinsker-type inequalities while arguing directly about the optimal \(\lambda(t)\), for which we need the following lemma.

Lemma 6.3.17. Suppose that \(f : \mathbb{R} \to \mathbb{R}\) is a convex function continuously differentiable on \((a, b)\) the interior of its domain with a unique global minimum and such that \(\lim_{x \to a^+} f(x) = \infty = \lim_{x \to b^-} f(x)\). Then there is a continuously differentiable function \(\lambda : (a - b, b - a) \to \mathbb{R}\)
such that $\text{hgt}_f(t) = f(\lambda(t) + t/2) = f(\lambda(t) - t/2)$ and

$$\lambda'(t) = \frac{f'(\lambda(t) + t/2) + f'(\lambda(t) - t/2)}{2(f'(\lambda(t) - t/2) - f'(\lambda(t) + t/2))},$$

(30)

$$\text{hgt}'_f(t) = \frac{f'(\lambda(t) + t/2)f'(\lambda(t) - t/2)}{f'(\lambda(t) - t/2) - f'(\lambda(t) + t/2)}.$$  

(31)

**Proof.** For each $t \in (a - b, b - a)$, the function $\lambda \mapsto f(\lambda + t/2) - f(\lambda - t/2)$ is continuously differentiable on its domain $(a + |t|/2, b - |t|/2)$, with limits $-\infty$ and $\infty$. Thus, for all such $t$ there exists $\lambda$ satisfying the implicit equation $f(\lambda(t) + t/2) = f(\lambda(t) - t/2)$, which by Lemma 6.3.2 also defines $\text{hgt}_f(t)$. Furthermore, the fact that $f$ has a unique global minimum implies this function is strictly increasing in $\lambda$ for each $t$, and thus the implicit function theorem guarantees the existence of the claimed continuously differentiable $\lambda(t)$.

Given the existence of $\lambda(t)$, we have by its definition that $\frac{d}{dt}f(\lambda(t) + t/2) = \frac{d}{dt}f(\lambda(t) - t/2)$, which implies by the chain rule the claimed value for $\lambda'(t)$, which since $\text{hgt}'_f(t) = \frac{d}{dt}f(\lambda(t) + t/2)$ implies the claimed expressions for the derivative of $\text{hgt}_f$. □

Using the previous lemma, we obtain the same optimal Pinsker-type inequality as in Corollary 6.3.13 under related but incomparable assumptions.

**Corollary 6.3.18.** If $\psi$ is strictly convex, has a positive second derivative on its domain, $1/\phi''$ is concave, and $\lim_{x \to \phi''(\infty)^-} \psi''(x) = \infty$ (e.g. if $\phi''(\infty) = \infty$), then $\text{hgt}_\psi(t) \leq t^2/(8\phi''(1))$ for all $t \geq 0$. Equivalently, for such $\phi$ we have $D_{\phi}(\mu \parallel \nu) \leq \frac{\phi''(1)}{2} \cdot \text{TV}(\mu, \nu)^2$ for all $\mu, \nu \in \mathcal{M}^1$.

**Proof.** By standard results in convex analysis, the existence and positivity of $\psi''$ imply that $\psi$ is itself twice differentiable (e.g. [HIL93, Proposition 6.2.5] or [Gor91, Proposition 1.1]). Thus, by Lemma 6.3.17, it suffices to show that $\text{hgt}'_\psi(t) \leq t/(4\phi''(1))$, or equivalently

$$\frac{(\psi')(\lambda(t) + t/2)(\psi')'(\lambda(t) - t/2)}{(\psi')(\lambda(t) - t/2) - (\psi')'(\lambda(t) + t/2)} \leq \frac{t}{4\phi''(1)}.$$  

(32)

Since $\psi'(\lambda(t) + t/2) = \psi'(\lambda(t) - t/2)$ and $\psi'$ has global minimum at 0, we have $\lambda(t) - t/2 \leq 0$ and $\lambda(t) + t/2 \geq 0$, and $(\psi')'(\lambda(t) - t/2) \leq 0$ and $(\psi')'(\lambda(t) + t/2) \geq 0$. Thus, we have that the left-hand side of Eq. (32) is half the harmonic mean of $(\psi')'(\lambda(t) + t/2)$ and $-(\psi')'(\lambda(t) - t/2)$, so it suffices by the arithmetic mean–harmonic mean inequality to prove

$$-(\psi')'(\lambda(t) + t/2) - (\psi')'(\lambda(t) - t/2) \leq \frac{t}{\phi''(1)}.$$  

(33)

Since Eq. (33) holds when $t = 0$, it suffices to prove that

$$(1/2 + \lambda'(t)) \cdot (\psi')''(\lambda(t) + t/2) + (1/2 - \lambda'(t)) \cdot (\psi')''(\lambda(t) - t/2) \leq \frac{1}{\phi''(1)}.$$  

(34)

By the relationship between the second derivative of a function and the one of its conjugate (e.g. [HIL93, Proposition 6.2.5]), this is equivalent to

$$\frac{1/2 + \lambda'(t)}{\psi''((\psi')'(\lambda(t) + t/2))} + \frac{1/2 - \lambda'(t)}{\psi''((\psi')'(\lambda(t) - t/2))} \leq \frac{1}{\phi''(1)}.$$  

(35)
Now, by Eq. (30), we have that $\lambda'(t) \in [-1/2, 1/2]$, so that by Jensen’s inequality and the concavity of $1/\psi''$, the left-hand side of Eq. (35) is at most

$$1/\psi''\left((1/2 + \lambda'(t))(\psi^*(\lambda(t) + t/2) - (\lambda'(t) - 1/2)(\psi^*(\lambda(t) - t/2))\right).$$

(36)

Finally, since by definition $\psi^*(\lambda(t) + t/2) = \psi^*(\lambda(t) - t/2)$, the term inside $1/\psi''$ in Eq. (36) is 0, so since $\psi(x) = \phi(1 + x)$ we are done.

Example 6.3.19. For the $\alpha$-divergences, we have $1/\phi''(x) = x^{2-\alpha}$ which is concave for $\alpha \in [1, 2]$, so Corollary 6.3.18 applies for these divergences. Furthermore, by Remark 6.3.10, we can consider the reverse $\alpha$-divergences with $\phi^*(x) = x^{1+\alpha}$ which has $1/(\phi^*)''(x) = x^{1+\alpha}$, which is concave for $\alpha \in [-1, 0]$.

7 Discussion

Throughout this paper, the $\phi$-cumulant generating function has proved central in explicating the relationship between $\phi$-divergences and integral probability metrics. As a starting point, the identity $K_{g,\nu} = L_{g,\nu}^*$ (Theorem 5.1.11) expresses the cumulant generating function as the convex conjugate of the best lower bound of $D_{\phi}(\mu \parallel \nu)$ in terms of $\mu(g) - \nu(g)$. This establishes a “correspondence principle” by which properties of the relationship between $\phi$-divergences and integral probability metrics translate by duality into properties of the cumulant generating function, and vice versa. An advantage of this correspondence is that the function $K_{g,\nu}$, being expressed as the solution of a single-dimensional convex optimization problem (Definition 5.1.7), is arguably easier to evaluate and analyze than its counterpart $L_{g,\nu}$, expressed as the solution to an infinite-dimensional optimization problem. Following Theorem 5.1.11, several results from the present paper can be seen as instantiations of this “correspondence principle” and we summarize some of them in Table 2.

A limitation of this correspondence is that it only describes the optimal lower bound function $L_{g,\nu}$ via its convex conjugate. When $L_{g,\nu}$ is lower semicontinuous, this is without any loss of information by the Fenchel–Moreau theorem, but in general this only provides information about the biconjugate $L_{g,\nu}^{**}$. While $L_{g,\nu}$ and $L_{g,\nu}^{**}$ differ in at most two points, as discussed in Section 5.1, the difference between the optimal lower bound and its biconjugate is potentially much more important when considering a class of functions $\mathcal{G}$ or a class of measures $\mathcal{N}$ as in Section 6.1. Some conditions under which this lower bound $L_{g,N}$ is necessarily convex and lower semicontinuous were derived in Sections 5.3 and 6.3, and we gave a characterization of $L_{g,N}$ up to countably many points in Remark 6.2.4 regardless, but this does not completely answer the question (cf. Remarks 5.3.7 and 6.1.4). We believe that an interesting direction for future work would be to identify natural necessary or sufficient conditions under which $L_{g,N}$ is convex or lower semicontinuous.

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§ 5.1  \( K_{g,\nu}(t) \leq B(t) \) for all \( t \in \mathbb{R} \)

\[
\mathcal{D}_\phi(\mu \parallel \nu) \geq B^*(\mu(g) - \nu(g)) \quad \text{for all } \mu \in X_g^1
\]

§ 5.2  \( 0 \in \text{int}(\text{dom } K_{g,\nu}) \)

\[
\mathcal{D}_\phi(\mu \parallel \nu) \geq L(|\mu(g) - \nu(g)|) \quad \text{for some } L \neq 0, \text{ all } \mu \in X_g^1
\]

§ 5.4  \( K_{g,\nu} \) differentiable at 0

\[
\mathcal{D}_\phi(\nu_n \parallel \nu) \to 0 \text{ implies } \nu_n(g) \to \nu(g) \text{ for all } (\nu_n) \in (X_g^1)^\mathbb{N}
\]

§ 6.2  \( K_{g,\nu}(t) \leq E(t) \) for all \( t \in \mathbb{R}, g \in \mathcal{G}, \nu \in X_g^1 \)

\[
\mathcal{D}_\phi(\mu \parallel \nu) \geq E^*(d_G(\mu, \nu)) \quad \text{for all } \mu, \nu \in X_g^1
\]

§ 6.3  \( \text{hgt}_{\phi^*}(2t) \leq B(t) \) for all \( t \in \mathbb{R} \)

\[
\mathcal{D}_\phi(\mu \parallel \nu) \geq B^*(\text{TV}(\mu, \nu)) \quad \text{for all } \mu, \nu \in \mathcal{M}^1
\]

Table 2: Several examples, proved in this paper, of the dual correspondence between properties of the \( \phi \)-cumulant generating function and properties of the relationship between the \( \phi \)-divergence and mean deviations. Throughout, \( \mu \in \mathcal{M}^1, g \in L^1(\nu), B : \mathbb{R} \to \mathbb{R} \) is arbitrary, \( E : \mathbb{R} \to \mathbb{R} \) is even, \( \mathcal{G} \subseteq \mathcal{L}^0 \), and \( X_g^1 \) and \( X_g^1 \) are as in Definition 5.1.12.

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A Deferred proofs

In this section, for the sake of completeness, we include proofs of results that follow from standard tools in convex analysis.
A.1 Proof of Lemma 3.2.15

Lemma 3.2.15 follows immediately from [Kön86, Remark 1.9] stated in the general context of superconvex structures, which applies to cs-compact sets by [Kön86, Example 1.6(0)]. For completeness, we include a proof here in the language of topological vector spaces.

First, a convex function which is upper bounded on a cs-closed set in the sense of Jameson [Jam72] satisfies an infinite-sum version of convexity called cs-convexity (convex-series convexity) by Simons [Sim90].

**Lemma A.1.1.** Let $C$ be a cs-closed subset of a real Hausdorff topological vector space and let $f : C \to \mathbb{R}$ be a convex function such that $\sup_{x \in C} f(x) < \infty$. Then $f$ is cs-convex.

**Proof.** Let $(\lambda_n)_{n \in \mathbb{N}} \in \mathbb{R}^\mathbb{N}$ be a sequence of real numbers such that $\sum_{i=0}^{\infty} \lambda_i = 1$ and $\lambda_n \geq 0$ for all $n \in \mathbb{N}$. Let $(x_n)_{n \in \mathbb{N}} \in C^\mathbb{N}$ be a sequence of elements in $C$ such that $r_0 \overset{\text{def}}{=} \sum_{i=0}^{\infty} \lambda_i x_i$ exists, and thus is in $C$ since $C$ is cs-closed. We wish to show that

$$f(r_0) \leq \liminf_{n \to \infty} \sum_{i=0}^{n} \lambda_i f(x_i). \quad (37)$$

Define for each $n \in \mathbb{N}$ the partial sums

$$\Lambda_n \overset{\text{def}}{=} \sum_{i=0}^{n} \lambda_i \quad \text{and} \quad s_n \overset{\text{def}}{=} \Lambda_n^{-1} \sum_{i=0}^{n} \lambda_i x_i.$$

If $\Lambda_n = 1$ for some $n \in \mathbb{N}$ then Eq. (37) is immediate from convexity. Otherwise, we have that for each $n \geq 0$,

$$r_n \overset{\text{def}}{=} \frac{r_0 - \Lambda_n \cdot s_n}{1 - \Lambda_n} = \sum_{i=n+1}^{\infty} \frac{\lambda_i}{1 - \Lambda_n} \cdot x_i$$

is an element of $C$ since $C$ is cs-closed, so that by convexity of $f$

$$f(r_0) \leq \Lambda_n \cdot f(s_n) + (1 - \Lambda_n) \cdot f(r_n) \leq \sum_{i=0}^{n} \lambda_i f(x_i) + (1 - \Lambda_n) \cdot \sup_{x \in C} f(x).$$

Since $\sup_{x \in C} f(x) < \infty$ and $\lim_{n \to \infty} \Lambda_n = 1$ by assumption, the previous inequality implies Eq. (37) as desired. \hfill \Box

Second, cs-convex functions are necessarily bounded below on cs-compact sets. Together with Lemma A.1.1, this implies Lemma 3.2.15.

**Lemma A.1.2.** Let $f : C \to \mathbb{R}$ be a cs-convex function on a cs-compact subset $C$ of a real Hausdorff topological vector space. Then $\inf_{x \in C} f(x) > -\infty$.

**Proof.** We prove the contrapositive, that if $\inf_{x \in C} f(x) = -\infty$ then $f$ is not cs-convex. Indeed, if $\inf_{x \in C} f(x) = -\infty$, then for each $n \in \mathbb{N}$ there exists $x_n \in C$ with $f(x_n) \leq -4^n$. Since $C$ is cs-compact, the element $\bar{x} \overset{\text{def}}{=} \sum_{i=1}^{\infty} 2^{-i} \cdot x_i$ exists and is in $C$. But then

$$\liminf_{n \to \infty} \sum_{i=1}^{n} 2^{-i} \cdot f(x_i) \leq \liminf_{n \to \infty} \sum_{i=1}^{n} 2^{-i} \cdot -4^i = -\infty < f(\bar{x}),$$

proving that $f$ is not cs-convex. \hfill \Box
A.2 $\phi$-cumulant generating function

Lemma A.2.1 (Lemma 5.1.6 restated). The function $\psi^* : x \mapsto \phi^*(x) - x$ is non-negative, convex, and inf-compact. Furthermore, it satisfies $\psi^*(0) = 0$, $\psi^*(x) \leq -x$ when $x \leq 0$, and $\text{int}(\text{dom} \ \psi^*) = (-\infty, \phi'(\infty))$.

Proof. We have that $\psi^*(x) = \sup_{y \in \mathbb{R}} (y \cdot x - \phi(y + 1)) = \sup_{y \in \mathbb{R}} ((y - 1) \cdot x - \phi(y)) = -x + \sup_{y \in \mathbb{R}} (y \cdot x - \phi(y)) = \phi^*(x) - x$. Non-negativity of $\psi^*$ holds since $\psi^*(x) \geq 0 \cdot x - \psi(0) = 0$, and convexity and lower semicontinuity hold for any convex conjugate. For inf-compactness, we have since $0 \in \text{int} \ \text{dom} \ \phi$ by assumption that there exists $\alpha > 0$ with $[-\alpha, \alpha] \subseteq \text{dom} \ \psi$, so that $\psi^*(y) \geq \max\{\alpha \cdot y - \phi(\alpha), -\alpha \cdot y - \psi(-\alpha)\} \geq \alpha \cdot |y| - \max\{\phi(\alpha), \psi(-\alpha)\}$, so that the sublevel sets of $\psi^*$ are closed and bounded and thus compact.

The claim about dom $\psi$ is immediate from Lemma 3.2.12 since dom $\phi \subseteq \mathbb{R}_{\geq 0}$ implies $\phi'(-\infty) = -\infty$. Finally, dom $\phi \subseteq \mathbb{R}_{\geq 0}$ also implies for $x \leq 0$ that $\psi^*(x) = \sup_{y \geq -1} (y \cdot x - \psi(y)) \leq \sup_{y \geq -1} y \cdot x - \inf_{y \geq -1} \psi(y) = -x$ where the last equality is because $\psi \geq 0$ and $x \leq 0$. \qed

Proposition A.2.2 (Proposition 5.1.10 restated). For every $\sigma$-ideal $\Xi$, probability measure $\nu \in \mathcal{M}_1(\Xi)$, and $g \in L^0(\Xi)$, $K_{g,\nu,\Xi} : \mathbb{R} \to \mathbb{R}$ is non-negative, convex, lsc, and satisfies $K_{g,\nu,\Xi}(0) = 0$.

Furthermore, if $g$ is not $\nu$-essentially constant then $K_{g,\nu,\Xi}$ is inf-compact. If there exists $c \in \mathbb{R}$ such that $g = c$ $\nu$-almost surely, then there exists $t > 0$ (resp. $t < 0$) such that $K_{g,\nu,\Xi}(t) > 0$ if and only if $\phi'(\infty) < \infty$ and $\text{ess sup}_{\Xi} g > c$ (resp. $\text{ess inf}_{\Xi} g < c$).

We prove this in steps, using the following important function:

Definition A.2.3. For every $\sigma$-ideal $\Xi$, probability measure $\nu \in \mathcal{M}_1(\Xi)$, and $g \in L^0(\Xi)$, define

$$F_{g,\nu,\Xi}(t,\lambda) \equiv \begin{cases} \int \psi^*(tg + \lambda) \, d\nu & \text{if } \text{ess sup}_{\Xi}(tg + \lambda) \leq \phi'(\infty) \\ +\infty & \text{otherwise} \end{cases}$$

so that $K_{g,\nu,\Xi} = \inf_{\lambda \in \mathbb{R}} F_{g,\nu,\Xi}((\cdot,\lambda))$.

Lemma A.2.4. For every $\sigma$-ideal $\Xi$, probability measure $\nu \in \mathcal{M}_1(\Xi)$, and $g \in L^0(\Xi)$, the function $F_{g,\nu,\Xi}$ is non-negative, convex, lsc, and the set $\{\lambda \in \mathbb{R} \mid F_{g,\nu,\Xi}(0,\lambda) = 0\}$ is compact and contains 0.

Proof. Non-negativity of $F_{g,\nu,\Xi}$ is immediate from non-negativity of $\psi^*$. The function

$$(t,\lambda) \mapsto \begin{cases} 0 & \text{if } tg + \lambda \in [-\infty, \phi'(\infty)] \Xi\text{-a.e.} \\ +\infty & \text{otherwise} \end{cases}$$

is convex and lsc since $[-\infty, \phi'(\infty)]$ is a closed interval.

Similarly, the convexity of $\psi^*$ implies the convexity of $(t,\lambda) \mapsto \int \psi^*(tg + \lambda) \, d\nu$. Furthermore, by Fatou’s lemma and since $\psi^*$ is lsc we have for every sequence $(t_n, \lambda_n) \to (t,\lambda)$ that

$$\liminf_{n \to \infty} \int \psi^*(t_n g + \lambda_n) \, d\nu \geq \int \liminf_{n \to \infty} \psi^*(t_n g + \lambda_n) \, d\nu \geq \int \psi^*(tg + \lambda) \, d\nu,$$
so that this function is also lower semicontinuous.

Finally, \( \{ \lambda \in \mathbb{R} \mid F_{\xi,\nu,\Xi}(0, \lambda) = 0 \} \) is a sublevel set of a non-negative lsc function and so is closed, it contains 0 since \( \psi^*(0) = 0 \) and \( \phi'(-\infty) \geq 0 \), and is bounded since it is contained in the compact set \( \{ \lambda \in \mathbb{R} \mid \psi^*(\lambda) = 0 \} \). \hfill \square

**Lemma A.2.5.** For every \( \sigma \)-ideal \( \Xi \), probability measure \( \nu \in \mathcal{M}_c^1(\Xi) \), and \( g \in L^0(\Xi) \), we have \( \mathbb{R} \geq \{ t \in \mathbb{R} \mid \exists \lambda \in \mathbb{R} \land F_{\xi,\nu,\Xi}(t, \lambda) = 0 \} \) if and only if \( g \) is \( \nu \)-essentially constant and either \( \phi'(-\infty) = \infty \) or \( \text{ess sup}_\Xi g = \text{ess sup}_\nu g \).

**Proof.** If \( g = c \) holds \( \nu \)-a.s. for some \( c \in \mathbb{R} \) and either \( \phi'(-\infty) = \infty \) or \( \text{ess sup}_\Xi g = \text{ess sup}_\nu g = c \), then for all \( t \geq 0 \) we have \( F_{\xi,\nu,\Xi}(t, -t \cdot c) = 0 \) since \( tg + \lambda \) is \( \nu \)-a.s. and at most \( \phi'(-\infty) \geq 0 \) \( \Xi \)-a.e.

Conversely, suppose \( \mathbb{R} \geq \{ t \in \mathbb{R} \mid \exists \lambda \in \mathbb{R} \land F_{\xi,\nu,\Xi}(t, \lambda) = 0 \} \). Then for every \( t \geq 0 \) there is \( \lambda \in \mathbb{R} \) such that \( tg + \lambda \in \{ x \in \mathbb{R} \mid \psi^*(x) = 0 \} \subseteq [-\infty, \psi^*(-\infty)] \) holds \( \nu \)-a.s. and \( tg + \lambda \in [-\infty, \phi'(-\infty)] \) holds \( \Xi \)-a.e. Since \( \psi^* \) is non-negative, convex, and inf-compact, the set \( \{ x \in \mathbb{R} \mid \psi^*(x) = 0 \} \) is a compact interval \( [a, b] \), and thus there is \( \lambda \in \mathbb{R} \) such that \( tg + \lambda \in [a, b] \) holds \( \nu \)-a.s. if only if \( |t| \cdot (\text{ess sup}_\nu g - \text{ess inf}_\nu g) \leq b - a < \infty \). Thus, since this holds for all \( t \in \mathbb{R} \), we have \( \text{ess sup}_\nu g = \text{ess inf}_\nu g, \) equivalently that \( g = c \) holds \( \nu \)-a.s. for some \( c \in \mathbb{R} \). Thus, the condition on \( t \) reduces to the existence of \( \lambda \in \mathbb{R} \) such that \( tc + \lambda \in [a, b] \) and \( \text{ess sup}_\Xi tg + \lambda = tc + \lambda + t \cdot (\text{ess sup}_\Xi g - c) \leq \phi'(-\infty) \). In particular, this implies that \( a + t \cdot (\text{ess sup}_\Xi g - c) \leq \phi'(-\infty) \) for all \( t \geq 0 \), which implies either \( \phi'(-\infty) = \infty \) or \( \text{ess sup}_\Xi g \leq c = \text{ess sup}_\nu g \) as desired. \hfill \square

We can finally prove Proposition 5.1.10.

**Proof of Proposition 5.1.10.** The main claim is immediate by applying standard results in convex analysis (e.g. [RW98b, Propositions 1.17 and 3.32]) to Lemma A.2.4. Furthermore, these results imply that \( \{ t \in \mathbb{R} \mid K_{\xi,\nu,\Xi}(t) = 0 \} = \{ t \in \mathbb{R} \mid \exists \lambda \in \mathbb{R} \land F_{\xi,\nu,\Xi}(t, \lambda) = 0 \} \).

For the supplemental claim, we have since \( K_{\xi,\nu,\Xi} \) is non-negative, convex, lsc, and 0 at 0 that it is inf-compact if and only if there exist \( t_+ > 0 \) and \( t_- < 0 \) such that \( K_{\xi,\nu,\Xi}(t_+), K_{\xi,\nu,\Xi}(t_-) > 0 \). The claimed characterization thus follows from applying Lemma A.2.5 to \( g \) and \( -g \). \hfill \square