CLOSED RANGE FOR $\bar{\partial}$ AND $\bar{\partial}_b$ ON BOUNDED HYPERSURFACES IN STEIN MANIFOLDS

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Abstract. We define weak $Z(q)$, a generalization of $Z(q)$ on bounded domains $\Omega$ in a Stein manifold $M^n$ that suffices to prove closed range of $\bar{\partial}$. Under the hypothesis of weak $Z(q)$, we also show (i) that harmonic $(0, q)$-forms are trivial and (ii) if $\partial\Omega$ satisfies weak $Z(q)$ and weak $Z(n - 1 - q)$, then $\bar{\partial}_b$ has closed range on $(0, q)$-forms on $\partial\Omega$. We provide examples to show that our condition contains examples that are excluded from $(q - 1)$-pseudoconvexity and the authors' previous notion of weak $Z(q)$.

1. Introduction

The purpose of this article is to establish sufficient conditions for the closed range of $\bar{\partial}$ (and $\bar{\partial}_b$) on not necessarily pseudoconvex domains (and their boundaries) in Stein manifolds. We pay particular attention to keeping the boundary regularity at a minimum; our results holds for $C^3$ boundaries. In [HR11], we develop a notion of weak $Z(q)$ for which we can prove closed range of $\bar{\partial}_b$ for smooth bounded CR manifolds of hypersurface type in $\mathbb{C}^n$. In this paper, we generalize our notion of weak $Z(q)$ and relax the smoothness assumption. The microlocal analysis technique of [HR11] requires significant boundary smoothness, and to replace the microlocal analysis, we assume that our CR manifold is the boundary of a bounded domain in a Stein manifold and attain the closed range of $\bar{\partial}_b$ as a consequence of the $\bar{\partial}$-theory which we prove. Our analysis of $\bar{\partial}_b$ is in the spirit of [Sha03]. Additionally, we show that the weak $Z(q)$-hypothesis is sufficient to show that harmonic forms vanish at level $(0, q)$. Finally, we provide examples to show that our new condition is more general than either $(q - 1)$-pseudoconvexity [Zam08] or the weak $Z(q)$-hypothesis of [HR11].

Let $\Omega \subset \mathbb{C}^n$ be a bounded domain with a $C^2$ defining function $\rho$. The Levi form of $\partial\Omega$ is the form

$$L_\rho(t) = \sum_{j,k=1}^{n} \frac{\partial^2 \rho}{\partial z_j \partial \bar{z}_k} t_j t_k,$$

where $\sum_{j=1}^{n} \frac{\partial \rho}{\partial z_j} t_j = 0$.

If the Levi form is positive semi-definite for all boundary points, we say $\Omega$ is pseudoconvex. Suppose that $f$ is a $(0, q)$-form on $\Omega$ with components in $L^2$. If $\bar{\partial} f = 0$, where $\bar{\partial}$ is the Cauchy-Riemann operator, we wish to know whether there exists a $(0, q - 1)$-form $u$ with $L^2$ components such that $\bar{\partial} u = f$. When $\Omega$ is a pseudoconvex domain, this question was answered in the affirmative for all $1 \leq q \leq n$ by

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Hörmander in [Hor65]. In fact, pseudoconvexity is a necessary condition to solve $\bar{\partial}$ in $L^2$ for all $1 \leq q \leq n$.

If we only wish to solve $\bar{\partial}$ for a fixed value of $q$, pseudoconvexity is no longer necessary. If the Levi form has at least $n-q$ positive eigenvalues or at least $q+1$ negative eigenvalues, we say that $\partial \Omega$ satisfies $Z(q)$. It is known that the $\bar{\partial}$ problem can be solved in $L^2$ if $\partial \Omega$ satisfies $Z(q)$. In fact, $Z(q)$ is equivalent to the solvability of $\bar{\partial} u = f$ if the components of $u$ are required to be elements of the $L^2$ Sobolev space $W^{1/2}$ (see [Hor65], Theorem 3.2.2 in [FK72], or [AG62]).

If we allow the Levi form to degenerate as in the pseudoconvex case, solvability is less well understood. One candidate that has been studied in some detail is $q$-pseudoconvexity (see [Zam08]). In $q$-pseudoconvexity, a subbundle of the tangent bundle of at most dimension $q$ exists locally with the property that the sum of the $q+1$ smallest eigenvalues of the Levi form is greater than or equal to the trace of the Levi form with respect to the subbundle. As shown in Theorem 1.9.9 in [Zam08], this implies that for $L^2$ $(0, q+1)$-forms $f$ in the kernel of $\bar{\partial}$, there exists an $L^2$ $(0, q)$-form $u$ solving $\bar{\partial} u = f$. To be consistent with the notation convention in $Z(q)$, we will typically refer to this as $(q-1)$-pseudoconvexity.

In this paper, we will generalize $(q-1)$-pseudoconvexity as follows. Taking the trace of the Levi form with respect to a vector bundle can be thought of in local coordinates as taking the trace of the Levi form with respect to a projection matrix (i.e., a hermitian matrix with eigenvalues of 0 or 1). We will relax this condition by allowing eigenvalues that are between 0 and 1. This gives us needed flexibility, as demonstrated by an example in Proposition 6.1 in which the rank of the identity minus our matrix is forced to be locally nonconstant. By analogy with the nondegenerate case, we will call such domains weak $Z(q)$ domains (see Definition 2.41 for a formal definition). The example in Proposition 6.1 thus illustrates that weak $Z(q)$ is a strictly weaker condition than any previously known condition.

We also allow for the boundary to be disconnected, using techniques developed for the annulus between two pseudoconvex domains in [Sha85a]. These techniques allow us to solve $\bar{\partial}$ modulo the space of harmonic $(0, q)$-forms in some weighted $L^2$ space. By adapting recent arguments of Shaw [Sha10], we are able to show that the space of harmonic $(0, q)$-forms in fact vanishes, which allows us to use Hörmander’s methods to obtain results in unweighted $L^2$ spaces. Our main $L^2$-result is thus the following:

**Theorem 1.1.** Let $M$ be an $n$-dimensional Stein manifold, and let $\Omega$ be a bounded subset of $M$ with $C^3$ boundary satisfying weak $Z(q)$ for some $1 \leq q \leq n-1$. Then we have

1. The space of harmonic $(0, q)$-forms $H^q(\Omega)$ is trivial.
2. The $\bar{\partial}$-Laplacian $\Box^q$ has closed range in $L^2_{(0,q)}(\Omega)$.
3. The $\bar{\partial}$-Neumann operator $N^q$ exists and is continuous in $L^2_{(0,q)}(\Omega)$.
4. The operator $\bar{\partial}$ has closed range in $L^2_{(0,q)}(\Omega)$ and $L^2_{(0,q+1)}(\Omega)$.
5. The operator $\bar{\partial}^*$ has closed range in $L^2_{(0,q)}(\Omega)$ and $L^2_{(0,q-1)}(\Omega)$.

We work in Stein manifolds motivated by results in [HL75]. The $C^3$ boundary is needed for our method of proof because of additional integration by parts that are carried out to handle the nonpositive eigenvalues of the Levi form. Unfortunately, while the results of Theorem 1.1 do not depend on the metric, our condition appears to depend on the metric (see Proposition 6.3). See [Str11] for discussion of analogous
difficulties surrounding the apparent metric dependence of Property (P). This is another benefit of working in generic Stein manifolds, since our example in Section 6 requires a non-Euclidean metric. Our condition also implies stronger results which do depend on the metric. Let \( \varphi \) be a global plurisubharmonic exhaustion function for \( M \), and let the metric for \( M \) be given by the Kähler form \( \omega = i\partial\bar{\partial}\varphi \). For a weight function \( \phi \) which is chosen to equal \( \pm \varphi \) in a neighborhood of each connected component of \( \partial \Omega \), we can define the weighted \( L^2 \)-norm \( \|f\|_{t}^2 = \int_{\Omega} e^{-t\phi} |f|^2 \, dV \). For sufficiently large \( t > 0 \), we will be able to obtain Sobolev space estimates for the weighted \( \bar{\partial} \)-Neumann operator defined with respect to this norm.

**Theorem 1.2.** Let \( M \) be an \( n \)-dimensional Stein manifold, and let \( \Omega \) be a bounded subset of \( M \) with \( C^3 \) boundary satisfying weak \( Z(q) \) for some \( 1 \leq q \leq n - 1 \). Then there exists a constant \( t > 0 \) such that for all \( t > t \) and \(-\frac{1}{2} \leq s \leq 1 \) we have

1. The weighted \( \bar{\partial} \)-Neumann operator \( N^t_{\Omega} \) exists and is continuous in \( L^2_{(0,q)}(\Omega) \).
2. The canonical solution operators to \( \bar{\partial} \) given by
   \[ \bar{\partial}_t^* N^t_{\Omega} : W^s_{(0,q)}(\Omega) \to W^s_{(0,q+1)}(\Omega) \]
   and \( N^t_{\bar{\partial}_t} : W^s_{(0,q+1)}(\Omega) \to W^s_{(0,q)}(\Omega) \) are continuous.
3. The canonical solution operators to \( \bar{\partial}_t \) given by
   \[ \bar{\partial}N^t_{\Omega} : W^s_{(0,q)}(\Omega) \to W^s_{(0,q+1)}(\Omega) \]
   and \( N^t_{\bar{\partial}} : W^s_{(0,q+1)}(\Omega) \to W^s_{(0,q)}(\Omega) \) are continuous.
4. For every \( f \in W^s_{(0,q)}(\Omega) \cap \ker \bar{\partial} \) there exists a \( u \in W^s_{(0,q-1)}(\Omega) \) such that \( \bar{\partial} u = f \).

Interestingly, Theorem 1.2 is actually needed to prove Theorem 1.1 when the boundary is disconnected; see Section 5 for details. The estimates of Theorem 1.2 were carried out by the first author in [Har09] for pseudoconvex domains with \( C^2 \) boundary; again, the additional integration by parts needed for weak \( Z(q) \) seem to require an additional degree of smoothness. Furthermore, the elliptic regularization carried out in Section 4 seems to require a \( C^3 \) boundary.

When \( \partial \Omega \) satisfies weak \( Z(q) \) and weak \( Z(n-q-1) \), we say that \( \partial \Omega \) satisfies weak \( Y(q) \). In [HR11], the authors continued work of [Nic06] and [Rai10] to understand solvability for the boundary operator \( \bar{\partial}_b \) on CR-manifolds of hypersurface type. The definition given for weak \( Y(q) \) in that paper is completely superseded by the definition in the present paper. When our bounded weak \( Y(q) \) manifold is an actual hypersurface in a Stein manifold, we now have the following result:

**Theorem 1.3.** Let \( M \) be an \( n \)-dimensional Stein manifold, and let \( \Omega \) be a bounded subset of \( M \) with connected \( C^3 \) boundary satisfying weak \( Y(q) \) for some \( 1 \leq q < n - 1 \). For every \( f \in L^2_{(0,q)}(\partial \Omega) \cap \ker \bar{\partial}_b \) there exists a \( u \in L^2_{(0,q-1)}(\partial \Omega) \) satisfying \( \bar{\partial}_b u = f \). Hence, \( \bar{\partial}_b \) has closed range in \( L^2_{(0,q)}(\partial \Omega) \).

Additional assumptions seem necessary for \( q = n - 1 \), even in the pseudoconvex case (see [CS01] for details).

2. Basic Properties and Notation

Let \( M \) be an \( n \)-dimensional Stein manifold, \( n \geq 2 \), and fix a smooth, strictly plurisubharmonic exhaustion function \( \varphi \) for \( M \). We endow \( M \) with the Kähler metric given by the Kähler form \( \omega = i\partial\bar{\partial}\varphi \). In local coordinates \( z_1, \ldots, z_n \), we will
write
\[ \omega = i \sum_{j,k=1}^{n} g_{jk} dz_j \wedge d\bar{z}_k = i \sum_{j,k=1}^{n} \frac{\partial^2 \rho}{\partial z_j \partial \bar{z}_k} dz_j \wedge d\bar{z}_k. \]

As usual, \( g^{jk} \) will denote the inverse matrix to \( g_{jk} \). By the usual convention, we will use the metric to raise and lower indices, so that, for example,
\[ \sum_{\ell=1}^{n} g_{jk} b_{\ell k} = b_{j}^{\ell} \]
\[ \sum_{\ell=1}^{n} c_{j\ell} \bar{g}^{\ell k} = c_j^k. \]

Additionally, we use the bracket \( \langle \cdot, \cdot \rangle \) notation for the metric pairing, i.e., if \( L, L' \in T^{1,0}(M) \), then \( \langle L, L' \rangle = \omega(iL' \wedge L) \) whereas if \( \alpha = \sum_{j=1}^{n} a_j dz_j \) and \( \alpha' = \sum_{j=1}^{n} a'_j dz_j \) in local coordinates, then \( \langle \alpha, \alpha' \rangle = \sum_{j,k=1}^{n} a_j^* g^{kj} a_j \). By multilinearity, \( \langle \cdot, \cdot \rangle \) now extends to \( (p,q) \)-forms.

Let \( \Omega \subset M \) be a bounded domain with \( C^m \) boundary. By definition, this means that there exists a \( C^m \) function \( \rho \) on \( M \) such that \( \Omega = \{ z \in M : \rho(z) < 0 \} \) and \( d\rho \neq 0 \) on \( \partial \Omega \). Such a \( \rho \) is called a \( C^m \) defining function for \( \Omega \). For \( z \in \partial \Omega \), we define the induced CR-structure on \( \partial \Omega \) at \( z \) by
\[ T^{1,0}_z(\partial \Omega) = \{ L \in T^{1,0}_z(M) : \partial \rho(L) = 0 \}. \]

Let \( T^{1,0}(\partial \Omega) \) denote the space of \( C^{m-1} \) sections of \( T^{1,0}_z(\partial \Omega) \). We will also need \( T^{0,1}(\partial \Omega) = \overline{T^{1,0}(\partial \Omega)} \) and the exterior algebra generated by these: \( T^{p,q}(\partial \Omega) \). Let \( \Lambda^{p,q}(\partial \Omega) \) denote the bundle of \( C^{m-1} \) \( (p,q) \)-forms on \( T^{p,q}(\partial \Omega) \). We use \( \tau \) to denote the orthogonal projection and restriction:
\begin{equation}
\tau : \Lambda^{p,q}(M) \to \Lambda^{p,q}(\partial \Omega).
\end{equation}

For each element \( X \) of \( T^{p,q} \) (resp. \( \Lambda^{p,q} \)), we denote the metric dual element of \( \Lambda^{p,q} \) (resp. \( T^{p,q} \)) by \( X^\sharp \). This is defined to satisfy the relationships \( X^\sharp(Y) = \langle Y, X \rangle \) for all \( Y \in T^{p,q} \) (resp. \( Y(X^\sharp) = \langle Y, X \rangle \) for all \( Y \in \Lambda^{p,q} \)). For example, the dual of the Kähler form is given in local coordinates by
\[ \omega^\sharp = i \sum_{j,k=1}^{n} g^{kj} \frac{\partial}{\partial z_j} \wedge \frac{\partial}{\partial z_k}. \]

For any \( C^2 \) defining function \( \rho \), the Levi form \( \mathcal{L}_\rho \) is the real element of \( \Lambda^{1,1}(\partial \Omega) \) defined by
\[ \mathcal{L}_\rho(iL \wedge L') = i\bar{\partial} \rho(iL \wedge L') \]
for any \( L, L' \in T^{1,0}(\partial \Omega) \). As usual, if \( \hat{\rho} \) is another \( C^2 \) defining function for \( \Omega \), then \( \hat{\rho} = \rho h \) for some nonvanishing \( C^1 \) function \( h \), and \( \mathcal{L}_{\hat{\rho}} = h \mathcal{L}_\rho \). We will typically suppress the subscript \( \rho \) when the choice of defining function is not relevant.

**Definition 2.1.** For \( 1 \leq q \leq n-1 \), we say \( \partial \Omega \) satisfies \( Z(q) \) weakly if there exists a real \( \Upsilon \in T^{1,1}(\partial \Omega) \) satisfying
\begin{enumerate}
\item \( |\theta|^2 \geq (i\theta \wedge \bar{\partial} \theta)(\Upsilon) \geq 0 \) for all \( \theta \in \Lambda^{1,0}(\partial \Omega) \).
\item \( \mu_1 + \cdots + \mu_q - \mathcal{L}(\Upsilon) \geq 0 \) where \( \mu_1, \ldots, \mu_{n-1} \) are the eigenvalues of \( \mathcal{L} \) in increasing order.
\item \( \omega(\Upsilon) \neq 0 \).
\end{enumerate}

**Remark 2.2.** Note that this is an intrinsic definition, so it can also be applied to abstract CR-manifolds of hypersurface type. This replaces the definition given
in [HR11], and the main results of that paper still follow with this more general definition.

The fact that \( \partial \Omega \) is the boundary of a domain induces a natural orientation on \( \partial \Omega \). It is sometimes useful to reverse the orientation and think of \( \partial \Omega \) as the boundary of the complement instead. The following observation is trivial for \( Z(q) \), and motivates the definition of \( Y(q) \), so it is of interest to confirm the corresponding fact for weak \( Z(q) \).

**Proposition 2.3.** For \( 1 \leq q \leq n-2 \), let \( \Omega \subset M \) be a bounded domain and let \( B \subset M \) be a sufficiently large bounded pseudoconvex domain so that \( \partial B \subset B \). Then \( \partial \Omega \) satisfies \( Z(q) \) weakly if and only if \( \partial(B/\Omega) \) satisfies \( Z(n-q-1) \) weakly.

**Proof.** Suppose \( \partial \Omega \) satisfies \( Z(q) \) weakly, and let \( \tilde{\Omega} \) be the element of \( \mathcal{T}^{1,1}(\partial \Omega) \) given by Definition 2.1. On \( \partial B \), we can define \( \tilde{\Omega} = 0 \), and on \( \partial \Omega \) we define \( \tilde{\Omega} = (\tau \omega)^{\dagger} - \tilde{\Omega} \).

If \( \mu_1, \ldots, \mu_{n-1} \) are the eigenvalues of the Levi form of \( \partial \Omega \) in increasing order, then \( \mu_1 = -\mu_{n-1}, \ldots, \mu_{n-1} = -\mu_1 \) are the eigenvalues of the Levi form of \( \partial(B/\Omega) \) (on \( \partial \Omega \)) in increasing order, so since \( \mathcal{L}((\tau \omega)^{\dagger}) = \mu_1 + \cdots + \mu_{n-1} \), we have

\[
\mu_1 + \cdots + \mu_{n-q-1} - \mathcal{L}(\tilde{\Omega}) = \tilde{\mu}_1 + \cdots + \tilde{\mu}_q - \tilde{\mathcal{L}}(\tilde{\Omega}).
\]

Furthermore, \( \omega(\tilde{\Omega}) = n - 1 - \omega(\tilde{\Omega}) \neq n - q - 1 \).

Similar computations prove the converse. \( \square \)

**Remark 2.4.** We can replace \( B \) with any bounded domain such that \( \partial B \) satisfies \( Z(n-q-1) \) weakly.

Motivated by this, we define

**Definition 2.5.** For \( 1 \leq q \leq n-2 \), we say \( \partial \Omega \) satisfies \( Y(q) \) weakly if \( \partial \Omega \) satisfies \( Z(q) \) weakly and \( Z(n-q-1) \) weakly.

We note that Definition 2.1 is essentially a local property (modulo connected boundary components).

**Lemma 2.6.** For \( 1 \leq q \leq n-1 \), let \( \sigma : \partial \Omega \to \{-1,1\} \) be continuous and suppose that for every \( p \in \partial \Omega \) there exists an open neighborhood \( U_p \) of \( p \) such that \( U_p \cap \partial \Omega \) is connected and a real \( \chi_p \in \mathcal{T}^{1,1}(U_p) \) satisfying

1. \( |\theta|^2 \geq (i \theta \wedge \bar{\theta})(\chi_p) \geq 0 \) for all \( \theta \in \Lambda^{1,0}(U_p) \).
2. \( \mu_1 + \cdots + \mu_q - \mathcal{L}(\chi_p) \geq 0 \) on \( U_p \) where \( \mu_1, \ldots, \mu_{n-1} \) are the eigenvalues of the Levi form in increasing order.
3. \( \sigma(p)(\omega(\chi_p) - q) > 0 \) on \( U_p \).

Then \( \partial \Omega \) satisfies \( Z(q) \) weakly.

**Remark 2.7.** The function \( \sigma \) represents a choice of orientation for each connected boundary component of \( \Omega \).

**Proof.** Choose a finite cover \( \{U_p\}_{p \in \mathcal{P}} \) of \( \partial \Omega \) and let \( \chi_p \) be a subordinate partition of unity. If we let \( \tilde{\Omega} = \sum_{p \in \mathcal{P}} \chi_p \chi_p \), then the necessary properties are satisfied by linearity. Since \( \sigma \) is constant on each connected component of \( \partial \Omega \), \( \omega(\chi_p) - q \) will have a constant sign on each connected component of \( \partial \Omega \), so there is no possibility of cancellation in the corresponding sum. \( \square \)
Fix $p \in \partial \Omega$, and choose local coordinates that are orthonormal at $p$ and satisfy 
\[ \frac{\partial p_j}{\partial z_j}(p) = 0 \] for all $1 \leq j \leq n - 1$. At $p$ we can write 
\[ \Upsilon = i \sum_{j,k=1}^{n-1} b^{kj} \frac{\partial}{\partial z_k} \wedge \frac{\partial}{\partial z_j} \quad \text{and} \quad \mathcal{L} = i \sum_{j,k=1}^{n-1} c_{jk} dz_j \wedge d\bar{z}_k \]
where $b^{kj}$ and $c_{jk}$ are hermitian $(n-1) \times (n-1)$ matrices. Suppose that the local coordinates are chosen to diagonalize $b^{kj}$ at $p$, and write $b^{kj} = \delta_{jk} \lambda_j$. When restricted to $p$, the defining characteristics of weak $Z(q)$ will take the form
\begin{enumerate}
\item $0 \leq \lambda_j \leq 1$ for all $1 \leq j \leq n - 1$.
\item $\mu_1 + \cdots + \mu_q - (\lambda_1 c_{11} + \cdots + \lambda_{n-1} c_{n-1,n-1}) \geq 0$.
\item $\lambda_1 + \cdots + \lambda_{n-1} \neq q$.
\end{enumerate}

If there is an orthonormal local coordinate frame that diagonalizes $b^{kj}$ such that $\lambda_1 = \cdots = \lambda_m = 1$ and $\lambda_{m+1} = \cdots = \lambda_{n-1} = 0$ for some $m \neq q$, then this is the condition studied in [HR11] which was shown to generalize $Z(q)$ and $(q-1)$-pseudoconvexity [Zam08] (with the weight $\varphi(z) = |z|^2$ in [HR11]).

Alternatively, we can choose orthonormal coordinates that diagonalize the Levi form at a point, so that $c_{jk} = \delta_{jk}\lambda_j$. The second condition then translates into
\[ \mu_1 (1 - b^{11}) + \cdots + \mu_q (1 - b^q) - (\mu_{q+1} b^{q+1} + \cdots + \mu_{n-1} b^{n-1}) \geq 0. \]
Since $(1 - b^{ij}) \geq 0$, $b^{ij} \geq 0$, and $\mu_j \leq \mu_q \leq \mu_{q+1} \leq \mu_k$ for all $j \leq q < k \leq n$, it follows that $\mu_q (q - \omega(\Upsilon)) \geq 0$ and $\mu_{q+1} (q - \omega(\Upsilon)) \geq 0$. Hence, if $\mu_q < 0$, then $\omega(\Upsilon) > q$, and if $\mu_{n-1} > 0$, then $\omega(\Upsilon) < q$. Equivalently, we have

**Lemma 2.8.** For $1 \leq q \leq n - 1$ let $\Omega \subset M$ be a bounded domain and suppose that $\partial \Omega$ satisfies $Z(q)$ weakly. Let $\Upsilon$ be as in Definition 2.7. For any fixed boundary point, if $\omega(\Upsilon) < q$ then the Levi form has at least $n - q$ nonnegative eigenvalues, and if $\omega(\Upsilon) > q$, then the Levi form has at least $q + 1$ nonpositive eigenvalues.

Many results will be easier to work with when the boundary is connected. The fact that we are only working with bounded domains induces a natural decomposition into domains with connected boundaries.

**Lemma 2.9.** For any Stein manifold $M$, supposed that $\Omega \subset M$ is a connected bounded domain with $C^3$ boundary satisfying $Z(q)$ weakly for some $1 \leq q \leq n - 1$. Then $\Omega = \Omega_1 / \bigcup_{j=2}^{m} \overline{\Omega}_j$ where $\Omega_j$ has connected boundary for each $1 \leq j \leq m$, $\Omega_1$ satisfies $Z(q)$ weakly, and $\Omega_j$ satisfies $Z(n - q - 1)$ weakly for each $2 \leq j \leq m$. The $(1,1)$-vector $\Upsilon$ in definition 2.1 will satisfy $\omega(\Upsilon) < q$ on $\partial \Omega_1$ and $\omega(\Upsilon) > q$ on $\partial \Omega_j$ for $2 \leq j \leq m$.

**Proof.** Let $\psi : M \to \mathbb{C}^{2n+1}$ be an embedding (see Theorem 5.3.9 in [Har90]). Since $\Omega$ is bounded, there exists a minimal radius $R > 0$ such that $\psi[\Omega]$ is contained in a ball centered at zero with radius $R$. Denote the pullback of this ball under $\psi$ by $B$. Then $B$ is a strictly pseudoconvex domain in $M$ containing $\Omega$ and since $R$ is minimal there exists at least one point $p \in \partial \Omega \cap \partial B$. At $p$, $\partial \Omega$ must also be strictly pseudoconvex, so $\omega(\Upsilon)(p) < q$ by the contrapositive of Lemma 2.8. By continuity, $\omega(\Upsilon) < q$ on the connected boundary component containing $p$, so we define this to be $\partial \Omega_1$. Since $\Omega$ is connected, the remaining boundary components (finitely many, since $\Omega$ is relatively compact with $C^3$ boundary) can be thought of as boundaries of $Z(n - q - 1)$ domains by Proposition 2.3 and Remark 2.4. Using the argument
Remark 2.10. One consequence of this proof is that there are no bounded weak $Z(0)$ domains, since $\omega(\Upsilon) < 0$ is impossible. On the other hand, bounded weak $Z(n - 1)$ domains can exist (e.g., pseudoconvex domains), but they must have connected boundaries (otherwise some boundary components would bound weak $Z(0)$ domains). For analysis of the $q = n - 1$ case on domains with disconnected boundaries, see [Hor04] and [Sha10].

To prove our basic estimates, we will need extensions of $\Upsilon$ to $M$.

Lemma 2.11. Suppose that $\partial \Omega$ satisfies $Z(q)$ weakly, and let $\Upsilon$ be as in Definition 2.4. Let $\rho$ be any $C^m$ defining function for $\Omega$. There exist relatively compact open sets $U^+, U^-$, and $U^0$ covering $\overline{\Omega}$ such that $\partial \Omega \cap U^0 = \emptyset$ and $U^+ \cap U^- = \emptyset$, along with real $\Upsilon^+, \Upsilon^- \in T^{1,1}(M)$ satisfying

\begin{enumerate}
\item $|\theta|^2 \geq (i\theta \wedge \bar{\theta})(\Upsilon^\pm) \geq 0$ for all $\theta \in \Lambda^{1,0}(M)$.
\item $\omega(\Upsilon^+) < q$ and $\omega(\Upsilon^-) > q$ on $M$.
\item For any $\theta \in \Lambda^{1,0}(M)$ we have
\[(i\theta \wedge \bar{\theta})(\Upsilon^\pm) = (i\tau \wedge \bar{\tau})(\Upsilon)\]
on $\partial \Omega \cap U^\pm$.
\item On a neighborhood of $\partial \Omega \cap U^\pm$, we have $(\theta \wedge \bar{\theta})(\Upsilon^\pm) = 0$ for all $\theta \in \Lambda^{1,0}(M)$.
\end{enumerate}

Remark 2.12. Note that $U^+ \neq \emptyset$ by Lemma 2.9. On the other hand, if $\partial \Omega$ is connected, we can set $U^- = \emptyset$ and $U^0 = \emptyset$.

Proof. Let $K^+ = \{ z \in \partial \Omega : \omega(\Upsilon) < q \}$ and $K^- = \{ z \in \partial \Omega : \omega(\Upsilon) > q \}$. By the continuity of $\omega(\Upsilon)$ these are disconnected from each other, so there exist open neighborhoods $U^+$ and $U^-$ such that $K^\pm \subset U^\pm$ and $K^\pm \cup U^\mp = \emptyset$. Choose $U^0$ such that $\partial \Omega \cap U^0 = \emptyset$ and $\overline{\Omega} \subset U^0 \cup U^+ \cup U^-$.

Let $\psi(w,t) : U \times [0,|\rho(w)|] \to U$ solve the initial value problem $\psi(w,0) = w$ and $\frac{\partial}{\partial t} \psi(w,t) = -\left( (\text{sgn}\rho)|\partial \rho|^{-2}(\partial \rho)^2 \right)(\psi(w,t))$. By construction, this will satisfy

$$\frac{\partial}{\partial t} \rho(\psi(w,t)) = - (\text{sgn}\rho)|\partial \rho|^{-2}(\partial \rho, \partial \rho)(\psi(w,t)) = - (\text{sgn}\rho)(\psi(w,t)), $$

so $\psi(w,|\rho(w)|) \in \partial \Omega$.

We denote parallel translation along $\psi(w,t)$ by

$$P^b_{\psi(w,a)} : T^p_q\psi(w,a)(M) \to T^p_q\psi(w,b)(M).$$

Choose $\chi \in C_0^\infty(U)$ such that $\chi \equiv 1$ on a neighborhood of $\partial \Omega$. We define $\Upsilon^\pm$ on $\partial \Omega \cap U^\pm$ by

$$(i\theta \wedge \bar{\theta})(\Upsilon^\pm) = (i\tau \wedge \bar{\tau})(\Upsilon)$$

for any $\theta \in \Lambda^{1,0}(M)$. On $U \cap U^\pm$, we parallel translate $\Upsilon^\pm$ along $\psi$, as follows. We define

$$\Upsilon^+(w) = \chi(w)P^0_{|\rho(w)|,w}\Upsilon^+(\psi(w,|\rho(w)|))$$

with a ball in $\mathbb{C}^{2n+1}$, we again see that each of these subdomains has a strictly pseudoconvex point, and hence the Levi form is negative definite (when viewed as part of $\partial \Omega$). When the Levi form is negative-definite, we must have $\omega(\Upsilon) > q$ by Lemma 2.8.
and
\[
\Upsilon^-(w) = \chi(w)F^0_{\rho(w)}, w \Upsilon^-(\psi(w, |\rho(w)|)) + (1 - \chi(w))\omega^z.
\]
We can now define \(\Upsilon^+ = 0\) on \(M/(U \cap U^+)\) and \(\Upsilon^- = \omega^z\) on \(M/(U \cap U^-)\).

We are now ready to define our weight function. Let \(U^\pm, U^0\), and \(\Upsilon^\pm\) be as in Lemma 2.11. Fix \(\chi \in C_0^\infty(M/\overline{U^+})\) such that \(\chi \equiv 1\) on \(\overline{U^+}\). Set
\[
\phi = \chi \varphi - (1 - \chi)\varphi.
\]
While the complex Hessian of \(\phi\) on \(U^0\) will involve derivatives of \(\chi\), we still have
\begin{equation}
\label{2.2}
i\partial\bar{\partial}\phi = \begin{cases} 
\omega & \text{on } U^+ \\
-\omega & \text{on } U^-.
\end{cases}
\end{equation}

We next define the usual weighted \(L^2\)-inner products. For \(f, h \in L^2_{(0, q)}(\Omega)\), define
\[ (f, h)_t = \int_{\Omega} e^{-t\phi} \langle f, h \rangle \, dV. \]
and \(\|f\|_t = \sqrt{(f, f)_t}\). Since \(e^{-t\phi}\) is uniformly bounded on \(\Omega\), the space of \((0, q)\)-forms bounded in \(\|\cdot\|_t\) is equal to \(L^2_{(0, q)}(\Omega)\). The operator
\[ \bar{\partial} : L^2_{(0, q)}(\Omega, e^{-t\phi}) \to L^2_{(0, q+1)}(\Omega, e^{-t\phi}) \]
is given its \(L^2\)-maximal definition, and the adjoint
\[ \bar{\partial}^* : L^2_{(0, q+1)}(\Omega, e^{-t\phi}) \to L^2_{(0, q)}(\Omega, e^{-t\phi}) \]
is defined with respect to the weighted inner product \((\cdot, \cdot)_t\). We also have \(\square^q = \bar{\partial}\bar{\partial}^* + \bar{\partial}^*\bar{\partial}\) with the induced domain. The space of harmonic forms is given by
\[ H^q_\square(\Omega) = L^2_{(0, q)}(\Omega, e^{-t\phi}) \cap \ker \bar{\partial} \cap \ker \bar{\partial}^*, \]
with the projection onto these denoted \(H^q_{k} : L^2_{(0, q)}(\Omega, e^{-t\phi}) \to H^q_\square(\Omega, e^{-t\phi})\). When it exists, the weighted \(\bar{\partial}\)-Neumann operator
\[ N^q_{\square} : L^2_{(0, q)}(\Omega, e^{-t\phi}) \to \text{Dom}(\square^q) \]
satisfies \(\square^q N^q_{\square} = I - H^q_{\square}\).

Let \(I_q\) denote the set of increasing multi-indices over \(\{1, \cdots, q\}\) of length \(q\). For an open set \(U \subset M\) with local coordinates \(\{z_1^U, \ldots, z_n^U\}\), we let \(\nabla^U_j\) denote the covariant derivative with respect to \(\frac{\partial}{\partial z_j^U}\). We also use \(\nabla^U_{j, t} = -\nabla^U_j + t \frac{\partial \phi}{\partial z_j^U}\). This satisfies the adjoint relationship
\[
\sum_{j,k=1}^n (g_{U, j} \nabla^U_{j, t} f, h_k)_t = \sum_{j,k=1}^n (g_{U, j} f, \nabla^U_{j, t} h_k)_t
\]
assuming \(f\) and \(h_k\) are compactly supported. If \(U\) is a finite open cover of \(\Omega\) by such sets, we let \(\{\chi^U_U\}_{U \in \mathcal{U}}\) denote a partition of unity subordinate to this cover.
and define the following gradient terms on \((0, q)\)-forms \(f\) for any \(\Upsilon \in T^{1,1}(M)\):

\[
\|\nabla f\|_t^2 = \sum_{U \in U} \sum_{j,k=1}^n (\chi^U b^{kj}_{\Upsilon} \nabla^j_k f, \nabla^j_k f)_t
\]

\[
\|\nabla_\Upsilon f\|_t^2 = \sum_{U \in U} \sum_{j,k=1}^n (\chi^U b^{kj}_{\Upsilon} \nabla^j_k f, \nabla^j_k f)_t
\]

\[
\|\nabla_\Upsilon f\|_t^2 = \sum_{U \in U} \sum_{j,k=1}^n (\chi^U \nabla^j_k f, \nabla^j_k f)_t
\]

where

\[
\Upsilon = i \sum_{j,k=1}^n \partial \frac{b^{kj}}{\partial z^j_k} \wedge \partial \frac{b^{kj}}{\partial \bar{z}^j_k}
\]

on \(U\). We also introduce vector fields which will figure prominently in our error terms:

\[
E = \sum_{U \in U} \sum_{j,k,\ell} \chi^U g_U \left( \frac{\partial}{\partial z^k_j U} b^{\ell j}_{U} \right) \frac{\partial}{\partial z^j_k}
\]

\[
E_\Upsilon = \sum_{U \in U} \sum_{j,k,\ell,\tau} \chi^U g_U \left( \frac{\partial}{\partial z^k_j U} b^{\tau j}_{U} \right) b^{\ell j}_{U} \frac{\partial}{\partial \bar{z}^j_k U}.
\]

Note that if we change coordinates, \(b^{\tau j}_{U}\) will be multiplied by matrices of holomorphic functions, which will be annihilated by \(\frac{\partial}{\partial \bar{z}^j_k}\), so the vector fields remain invariant under changes of coordinates. At any point \(p \in \Omega\), choose orthonormal coordinates at \(p\) that diagonalize \(b^{kj}_{\Upsilon}\) with eigenvalues \(\lambda_j\) corresponding to the eigenvector \(\frac{\partial}{\partial \bar{z}^j_k}\) at \(p\). If \(\Upsilon\) satisfies property (1) in Lemma 2.11, then \(0 \leq \lambda_j \leq 1\). If \(\Upsilon\) is \(C^1\), then at \(p\) we can write

\[
E = \sum_{j=1}^n A^j \frac{\partial}{\partial z^j}
\]

and

\[
E_\Upsilon = \sum_{j=1}^n A^j \lambda_j \frac{\partial}{\partial z^j}
\]

where \(A^j\) are continuous functions on our local coordinate patch. Hence, at \(p\), since \(\lambda_j^2 \leq \lambda_j\) we have

\[
\|\nabla_{E_\Upsilon,t} f\|_t^2 = \sum_{j=1}^n A^j \lambda_j |\nabla_{j,t} f|^2 \leq C \sum_{j=1}^n \lambda_j |\nabla_{j,t} f|^2
\]

for some constant \(C > 0\). Integrating, this gives us

\[
\|\nabla_{E_\Upsilon,t} f\|_t^2 \leq C \|\nabla_\Upsilon f\|_t^2.
\]

On the other hand, since \((1 - \lambda_j)^2 \leq (1 - \lambda_j)\), we also have at \(p\)

\[
|\nabla_E f - \nabla_{E_\Upsilon} f|^2 = \sum_{j=1}^n A_j (1 - \lambda_j) |\nabla_j f|^2 \leq C \sum_{j=1}^n (1 - \lambda_j) |\nabla_j f|^2
\]

for some constant \(C > 0\). Integration gives us

\[
\|\nabla_E f - \nabla_{E_\Upsilon} f\|_t^2 \leq C \left( \|\nabla f\|_t^2 - \|\nabla_\Upsilon f\|_t^2 \right).
\]
We also abuse notation and define the action of \((1,1)\)-forms on \((0,q)\)-forms. Let \(f \in C^1_{(0,q)}(\Omega) \cap \text{Dom}(\bar{\partial}_t^q)\). For any point \(p \in \Omega\), choose local coordinates that are orthonormal at \(p\) and define

\[
i\bar{\partial}\partial\phi(f,f)(p) = \sum_{J \in I_{q-1}} \sum_{j,k=1}^n \frac{\partial^2 \phi}{\partial z_j \partial \bar{z}_k} f_{kJ} \bar{f}_{jJ}
\]

where \(f_{kJ} = (-1)^\sigma f_K\) for \(K \in I_q\) if \(\{k\} \cup J = K\) as sets and \(\sigma\) is the length of the permutation that changes \(kJ\) into \(K\). Due to (2.2), we have

\[
i\bar{\partial}\partial\phi(f,f) = \begin{cases} q |f|^2 & \text{on } U^+ \\ -q |f|^2 & \text{on } U^- \end{cases}
\]

For any point \(p \in \partial \Omega\), choose local coordinates that are orthonormal at \(p\) such that \(\frac{\partial \rho}{\partial z_j}(p) = 0\) for all \(1 \leq j \leq n - 1\). We define

\[
\mathcal{L}(f,f)(p) = \sum_{J \in I_{q-1}} \sum_{j,k=1}^{n-1} \frac{\partial^2 \rho}{\partial z_j \partial \bar{z}_k} f_{kJ} \bar{f}_{jJ}.
\]

We note for future reference that if \(\mu_1, \ldots, \mu_{n-1}\) are the eigenvalues of \(\mathcal{L}\) arranged in increasing order, then (adapting the proof of Lemma 4.7 in [Str10]), we have

\[
\mathcal{L}(f,f) \geq (\mu_1 + \cdots + \mu_q) |f|^2.
\]

### 3. The Basic Estimate

Let \(\rho\) be a \(C^m\) defining function for \(\Omega\) with \(|d\rho| = 1\) on \(\Omega\). For \(f \in C^1_{(0,q)}(\Omega) \cap \text{Dom}(\bar{\partial}_t^q)\) with \(1 \leq q \leq n\), we have the Morrey-Kohn-Hörmander equality (see for example [CS01], [FK72], [Hör90], or [Str10]):

\[
\|\bar{\partial} f\|^2_{t^k} + \|\bar{\partial}^* f\|^2_{t^k} = \|\nabla f\|^2_{t^k} + t \int_{\Omega} i\bar{\partial}\partial\phi(f,f) e^{-t\phi} dV + \int_{\partial \Omega} \mathcal{L}(f,f) e^{-t\phi} dS + O(\|f\|^2_{t^k}).
\]

The error term involves the curvature of the Kähler metric, and can be computed explicitly using the Bochner-Kodaira technique [Siu82]. Since this term can be controlled by choosing \(t\) large enough, we won’t need the precise value.

We wish to understand integration by parts in the gradient term. Note that in (2.3), (2.4), and (2.5), the integrated terms are invariant under changes of coordinate, so derivatives of the partition of unity \(\chi^U\) that arise from integration by parts will cancel. Hence, for clarity of notation, we can suppress the partition of unity without losing information.

Let \(U^\pm\), \(U^\circ\), and \(Y^\pm\) be as in Lemma 2.11. Note that property \(6\) in this lemma guarantees that \(\chi^U\) has no normal component on \(\partial \Omega \cap U^\pm\), so \(Y^\pm|_{\partial \Omega \cap U^\pm}\) is made up of tangential derivatives which can be integrated by parts without introducing a boundary term. Hence, working in local coordinates with \(f \in C^2_{(0,q)}(\Omega) \cap C^2_0(U^\pm)\)
we have

\begin{align*}
\|\nabla_{\mathcal{Y}^\pm} f\|^2_t &= \sum_{j,k=1}^n (b^{kj}_j \nabla_{k,t} f, \nabla_{j,t} f)_t \\
&= \sum_{j,k,t=1}^n (g^{kl}_j f, \nabla_{k,t} (b^{jl}_j \nabla_{j,t} f))_t \\
&= \sum_{j,k=1}^n (b^{kj}_j f, \nabla_{k,t} \nabla_{j,t} f)_t - (f, \nabla_E f)_t.
\end{align*}

(3.2)

To continue, we will need the commutator

\begin{align*}
\sum_{j,k=1}^n b^{kj}_j [\nabla_{k,t}^* \nabla_j^* f] &= -t \sum_{j,k=1}^n b^{kj}_j \frac{\partial^2 \phi}{\partial z_k \partial z_j} f + O(f) = -\mp t \omega(\mathcal{Y}^\pm) f + O(f)
\end{align*}

where the error terms are independent of \( t \) and \( \Box_t \) has been used. Substituting in (3.2), we have

\begin{align*}
\|\nabla_{\mathcal{Y}^\pm} f\|^2_t &= \mp t(\omega(\mathcal{Y}^\pm) f, f)_t + \sum_{j,k=1}^n (b^{kj}_j \nabla_j^* \nabla_{k,t}^* f) - (f, \nabla_E f)_t + O(\|f\|^2_t) \\
&= \mp t(\omega(\mathcal{Y}^\pm) f, f)_t + \sum_{j,k,t=1}^n (g^{kj}_j \nabla_{k,t} (b^{jl}_j \nabla_{j,t} f), \nabla_{k,t}^* f)_t - (f, \nabla_E f)_t \\
&\quad + O(\|f\|^2_t) \\
&= \mp t(\omega(\mathcal{Y}^\pm) f, f)_t + \|\nabla_{\mathcal{Y}^\pm} f\|^2_t - (f, \nabla_{E,t} f)_t - (f, \nabla_E f)_t + O(\|f\|^2_t).
\end{align*}

When we integrate the error terms by parts, it will be helpful to note that on \( \partial \Omega \) we have \( E_t \rho = 0 \) but

\[ E \rho = \sum_{j,k,t} g^{kj}_j \left( \frac{\partial}{\partial z_k} b^{jl}_j \right) \frac{\partial \rho}{\partial z_j} = - \sum_{j,k} b^{kj}_j \frac{\partial^2 \rho}{\partial z_j \partial z_k} = -\mathcal{L}(\mathcal{Y}). \]

It is also important to note that \( \mathcal{Y}^\pm \) must be \( C^2 \) if integration by parts with respect to \( \nabla_{E_{\mathcal{Y}^\pm}} \) is going to be well-defined. Considering the error terms in (3.3), we have

\begin{align*}
(f, \nabla_{E,t} f)_t &= (f, \nabla_{E_{\mathcal{Y}^\pm},t} f)_t + ((\nabla_{E} - \nabla_{E_{\mathcal{Y}^\pm}}) f, f)_t + \int_{\partial \Omega} \mathcal{L}(\mathcal{Y}) |f|^2 e^{-t\phi} dS + O(\|f\|^2_t) \\
(f, \nabla_E f)_t &= (f, \nabla_{E_{\mathcal{Y}^\pm},t} f, f)_t + (f, (\nabla_{E} - \nabla_{E_{\mathcal{Y}^\pm}}) f)_t + O(\|f\|^2_t).
\end{align*}

(3.4)

(3.5)

Substituting (3.4) and (3.5) into (3.3), we have

\begin{align*}
\|\nabla_{\mathcal{Y}^\pm} f\|^2_t &= \mp t(\omega(\mathcal{Y}^\pm) f, f)_t - 2Re \left( (\nabla_{E_{\mathcal{Y}^\pm},t} f, f)_t + (f, (\nabla_{E} - \nabla_{E_{\mathcal{Y}^\pm}}) f)_t \right) \\
&\quad + \|\nabla_{\mathcal{Y}^\pm} f\|^2_t - \int_{\partial \Omega} \mathcal{L}(\mathcal{Y}) |f|^2 e^{-t\phi} dS + O(\|f\|^2_t). \tag{3.6}
\end{align*}

(3.6)

Since we have property (1) in Lemma 2.11, we can now write

\[ \|\nabla f\|^2_t = \left( \|\nabla f\|^2_t - \|\nabla_{\mathcal{Y}^\pm} f\|^2_t \right) + \|\nabla_{\mathcal{Y}^\pm} f\|^2_t. \]
and use the Schwarz inequality, the small constant/large constant inequality, (2.7) and (2.6) to control the error terms in (3.6). We conclude

\begin{equation}
\|\nabla f\|_t^2 \geq \mp t(\omega(\mathcal{Y}^\pm) f, f)_t - \int_{\partial \Omega} \mathcal{L} (\mathcal{Y}) |f|^2 dS + O(\|f\|_t^2)
\end{equation}

Substituting (3.7) and (2.8) into (3.1), we have

\begin{equation}
\|\partial_t f\|_t^2 + \|\partial_t f\|_t^2 \geq \mp t((q - \omega(\mathcal{Y}^\pm)) f, f)_t + \int_{\partial \Omega} (\mathcal{L}(f, f) - \mathcal{L}(\mathcal{Y}) |f|^2) e^{-t\phi} dS + O(\|f\|_t^2).
\end{equation}

We are now ready to prove the basic estimate (see Proposition 3.1 in [Sha85a] for the case where \(\Omega\) is the annuli between two weakly-pseudoconvex domains).

**Proposition 3.1.** Let \(M\) be an \(n\)-dimensional Stein manifold, \(n \geq 2\), and let \(\Omega\) be a bounded subset of \(M\) with \(C^3\) boundary satisfying weak \(Z(q)\) for some \(1 \leq q \leq n - 1\).

1. For any constant \(\varepsilon > 0\) there exists \(t_\varepsilon > 0\) and a \(C_\varepsilon > 0\) such that for any \(t \geq t_\varepsilon\) and \(f \in L^2_{(0, q)}(\Omega, e^{-t\phi}) \cap \text{Dom}(\partial) \cap \text{Dom}(\partial^*)\) we have

\[ \varepsilon \left( \|\partial_t f\|_t^2 + \|\partial_t^* f\|_t^2 \right) + C_\varepsilon \|f\|_{t, W^{-1}}^2 \geq \|f\|_t^2, \]

where \(\|\cdot\|_{t, W^{-1}}\) is the dual norm to \(\|\cdot\|_{t, W}^1\).

2. There exist constants \(C > 0\) and \(\bar{t} > 0\) such that for all \(t \geq \bar{t}\) and \(f \in L^2_{(0, q)}(\Omega, e^{-t\phi}) \cap \text{Dom}(\partial) \cap \text{Dom}(\partial^*) \cap (H^q(\Omega))^\perp\) we have

\[ C \left( \|\partial_t f\|_t^2 + \|\partial_t^* f\|_t^2 \right) \geq \|f\|_t^2. \]

3. If \(\partial \Omega\) is connected, then for any constant \(\varepsilon > 0\) there exists \(t_\varepsilon > 0\) such that for all \(t \geq t_\varepsilon\) and \(f \in L^2_{(0, q)}(\Omega, e^{-t\phi}) \cap \text{Dom}(\partial) \cap \text{Dom}(\partial^*)\) we have

\[ \varepsilon \left( \|\partial_t f\|_t^2 + \|\partial_t^* f\|_t^2 \right) \geq \|f\|_t^2. \]

**Proof.** Let \(U^\pm, U^0, \) and \(\mathcal{Y}^\pm\) as in Lemma (2.11). Let \(\chi^\pm\) and \(\chi^0\) form a partition of unity subordinate to \(U^\pm\) and \(U^0\). Given \(f \in C^2_{(0, q)}(\Omega) \cap \text{Dom}(\partial^*)\), we define \(f^\pm = \chi^\pm f \) and \(f^0 = \chi^0 f\). Since \(\partial \Omega\) is \(C^3\), \(\mathcal{Y}^\pm\) are \(C^2\), and hence (3.8) holds for \(f^\pm\).

By property (2) of Definition 2.11 the boundary term in (3.8) is positive, so we have

\[ \|\partial_t f^\pm\|_t^2 + \|\partial_t^* f^\pm\|_t^2 \geq \mp t((q - \omega(\mathcal{Y}^\pm)) f^\pm, f^\pm)_t + O(\|f^\pm\|_t^2). \]

By property (2) of Lemma 2.11 we have \(\pm (q - \omega(\mathcal{Y}^\pm)) > 0\). Since \(\Omega\) is bounded we know that \(\pm (q - \omega(\mathcal{Y})) \geq C_0\) for some constant \(C_0 > 0\). Furthermore,

\[ \|\partial_t f\|_t^2 + \|\partial_t f\|_t^2 \leq 2 \|\partial_t^* f\|_t^2 + 2 \|\partial_t f\|_t^2 + O(\|f\|_t^2), \]

so

\[ 2 \|\partial_t f\|_t^2 + 2 \|\partial_t f\|_t^2 \geq t C_0 \|f\|_t^2 + O(\|f\|_t^2). \]

Since \(f_0\) is compactly supported in \(\Omega\), we have Gårding’s inequality

\[ \|f^0\|_{t, W^{-1}}^2 \leq C_t (\|\partial_t f^0\|_t^2 + \|\partial_t^* f^0\|_t^2 + \|f^0\|_t^2) \]

for some constant \(C_t > 0\). Using the duality between \(W_0^1\) and \(W^{-1}\) we have

\[ \|f^0\|_t^2 \leq \|f^0\|_{t, W^{-1}} \sqrt{C_t (\|\partial_t f^0\|_t^2 + \|\partial_t^* f^0\|_t^2 + \|f^0\|_t^2)}. \]
Theorem 3.2. Let \( \tilde{f} \) be an \( f_0 \)-closable range in Stein manifolds, and let \( \Omega \) be a bounded subset of \( M \) with \( C^3 \) boundary satisfying weak \( Z(q) \) for some \( 1 \leq q \leq n-1 \). Then there exists a constant \( \varepsilon > 0 \) such that for all \( t > \varepsilon \) we have

1. \( \mathcal{H}_t^q(\Omega) \) is finite dimensional. If \( \partial \Omega \) is connected, then \( \mathcal{H}_t^q(\Omega) = \{0\} \).
2. The weighted \( \bar{\partial} \)-Laplacian \( \square_t^q \) has closed range in \( L^2_{(0,q)}(\Omega, e^{-t\phi}) \) and \( F^2_{(0,q+1)}(\Omega, e^{-t\phi}) \).
3. The weighted \( \bar{\partial} \)-Neumann operator \( N_t^q \) exists and is continuous.
4. The operator \( \bar{\partial}_t \) has closed range in \( L^2_{(0,q)}(\Omega, e^{-t\phi}) \) and \( F^2_{(0,q+1)}(\Omega, e^{-t\phi}) \).
5. The canonical solution operators to \( \bar{\partial}_t \) given by \( \bar{\partial}_t N_t^q : L^2_{(0,q)}(\Omega, e^{-t\phi}) \to L^2_{(0,q-1)}(\Omega, e^{-t\phi}) \) and \( N_t^q \bar{\partial}_t : L^2_{(0,q+1)}(\Omega, e^{-t\phi}) \to L^2_{(0,q)}(\Omega, e^{-t\phi}) \) are continuous.
6. The canonical solution operators to \( \bar{\partial}_t \) given by \( \bar{\partial} N_t^q : L^2_{(0,q)}(\Omega, e^{-t\phi}) \to L^2_{(0,q)}(\Omega, e^{-t\phi}) \) and \( N_t^q \bar{\partial}_t : L^2_{(0,q-1)}(\Omega, e^{-t\phi}) \to L^2_{(0,q)}(\Omega, e^{-t\phi}) \) are continuous.
7. For every \( f \in L^2_{(0,q)}(\Omega) \) \( \cap \ker \bar{\partial} \cap (\mathcal{H}_t^q(\Omega)) \) there exists a \( u \in L^2_{(0,q-1)}(\Omega) \) such that \( \bar{\partial} u = f \).
4. Sobolev Estimates

In this section we will use elliptic regularization to obtain estimates in the $L^2$-Sobolev space $W^1$ when $\partial \Omega$ is connected. The first author obtained such estimates for $C^2$-pseudoconvex domains in [Har09]. In that paper, he used an exhaustion by smooth strictly pseudoconvex domains. Although smooth $Z(q)$ domains can exhaust bounded weakly $Z(q)$ domains with connected boundaries, constructing $\mathcal{Y}$ on the exhaustion domains in such a way that the estimates are uniform may not be possible. Hence, we will use elliptic regularization in the present paper. Our discussion follows the argument in Section 3.3 of [Str10], focusing on steps where the reduced boundary regularity requires more careful estimates.

We will need two equivalent norms on $W^1(\Omega)$: the standard norm $\|u\|_{W^1}^2 = \|u\|^2 + \|\nabla u\|^2$ and the weighted norm $\|u\|_{W^1}^2 = \|u\|^2 + \|\nabla u\|^2$. Although these are equivalent, the constant involved will depend on $\delta$, so for estimates where the dependency on $\delta$ is significant we will need to use the weighted norm. Only at the end of the proof will we be able to pass to estimates for the standard norm, which is more suitable for interpolation. For $u \in W^1((0,\rho) \cap \text{Dom}(\bar{\partial}_t^*)$ and $\delta > 0$ we define

$$Q_{t,\delta}(u,u) = \|\bar{\partial}_t u\|^2 + \|\bar{\partial}_t^* u\|^2 + \delta \|\nabla u\|^2.$$ 

As in [Str10], we have a unique self-adjoint operator $\square_{t,\delta}^q$ on $L^2((0,\rho))\cap \text{Dom}(\bar{\partial}_t^*)$ satisfying $(\square_{t,\delta}^q u, v)_{\delta} = Q_{t,\delta}(u,v)$ for all $u \in \text{Dom}(\square_{t,\delta}^q)$ and $v \in W^1((0,\rho) \cap \text{Dom}(\bar{\partial}_t^*))$, where $\text{Dom}(\square_{t,\delta}^q)$ is the subspace of $W^1((0,\rho) \cap \text{Dom}(\bar{\partial}_t^*))$ on which $\square_{t,\delta}^q u \in L^2((0,\rho))$. Finally we wish to estimate $\partial, D_t^h$ by considering difference quotients of components of $u$ in our special basis. This will preserve $\text{Dom}(\bar{\partial}_t^*)$, but uniform bounds on $D_t^h u$ will now involve the $C^2$ norm of $\rho$. We then wish to estimate $Q_{t,\delta}(D_t^h u, v)$. The details for this estimate are contained in (3.8) through (3.11) in [Str10], but we will simply observe that they involve uniform bounds for $[\bar{\partial}_t, D_t^h]u$, $[\bar{\partial}_t^*, D_t^h]u$, and $[\nabla, D_t^h]u$, which will all involve the $C^3$ norm of $\rho$. Working with the smooth cutoff functions necessary to work locally will not involve additional derivative of $\rho$, so Strohme's argument will allow us to bound tangential derivatives of $u$ in the $W^1$ norm. As usual, the structure of $\square_{t,\delta}^q$ as a second-order elliptic operator will allow us to estimate the second derivatives in the normal direction (which only involve second derivatives of $\rho$).

Our goal is to show that the $W^1$ norm of $N_{t,\delta}^q f$ is bounded by the $W^1$ norm of $f$ with a constant that is independent of $\delta$, so that we may use a limiting argument to show that this estimate also holds for $N_{t,\delta}^q f$. Since $\bar{\partial} \oplus \bar{\partial}_t^*$ is an elliptic system, it will
suffice to estimate tangential derivatives, but first we must clarify how a differential operator acts globally on a \((0, q)\)-form. Let \(\psi \in W^2_{0, q}(\Omega) \cap \text{Dom}(\bar{\partial}_t^\ast)\) and let \(T\) be a differential operator defined on \(\Omega\) that is tangential on the boundary. Since \(\partial \Omega\) is \(C^3\), we may assume \(T\) has \(C^2\) coefficients. For \(U \subset M\) with local coordinates \(\{z_1, \ldots, z_n\}\) we can write

\[
\psi = \sum_{I \in \mathcal{I}_q} \psi_I dz_I,
\]

where the components \(\psi_I\) are all in \(W^2(\Omega)\). The covariant derivative \(\nabla_T \psi\) is globally defined and in local coordinates we can write

\[
\nabla_T \psi = \sum_{I \in \mathcal{I}_q} T \psi_I dz_I + O(\psi),
\]

where the coefficients in the zero order term involve coefficients of \(T\) and are hence \(C^2\). However, \(\nabla_T \psi\) is probably not in the domain of \(\bar{\partial}_t^\ast\). On the other hand, for \(U\) sufficiently small, we can also choose a \(C^2\) orthonormal basis for the space of \((1, 0)\)-forms \(\omega_1, \ldots, \omega_n\) where \(\omega_n = \partial \rho\). In this basis we write

\[
\psi = \sum_{I \in \mathcal{I}_q} \tilde{\psi}_I \omega_I.
\]

Since the transition matrices between \(dz\) and \(\omega\) have \(C^2\) entries, \(\tilde{\psi}_I\) can be obtained by applying a linear operator with \(C^2\) coefficients to \(\psi_I\). We define

\[
D_T^U \psi = \sum_{I \in \mathcal{I}_q} T \tilde{\psi}_I \omega_I,
\]

and sum over a partition of unity to obtain \(D_T \psi\). Note that \(D_T\) preserves tangential and normal components of \(\psi\), so it will also preserve the domain of \(\bar{\partial}_t^\ast\). However, returning to local coordinates,

\[
D_T^U \psi = \sum_{I \in \mathcal{I}_q} T \psi_I dz_I + O(\psi),
\]

where the coefficients of the zero order terms are obtained by differentiating the \(C^2\) transitions matrices between \(dz\) and \(\omega\), so they are only \(C^1\). Hence, \(D_T - \nabla_T\) is a zero-order operator with \(C^1\) coefficients. This requires some caution. For example, if \(\nabla_T^2\) is a second-order differential operator with \(C^1\) coefficients, then \([\nabla_T^2, \nabla_T]\) is a second-order differential operator with continuous coefficients, and hence \([\nabla_T^2, \nabla_T]\) is a form in \(L^2(0, q)\). However, \([\nabla_T^2, D_T - \nabla_T]\) may not be a differential operator with continuous coefficients, so we cannot make use of \([\nabla_T^2, D_T] \psi\).

On the other hand, commutators between \(D_T\) and first-order differential operators will still have continuous (hence bounded) coefficients.

For \(\varepsilon > 0\), let \(t_\varepsilon\) and \(t\) be as in (3) of Proposition 3.1. Then for \(u \in W^1_{0, q}(\Omega) \cap \text{Dom}(\bar{\partial}_t^\ast)\), when \(\partial \Omega\) is connected we have \(\varepsilon Q_{t_\varepsilon, t}(u, u) \geq \|u\|_t^2\). Let \(f \in W^1_{0, q}(\Omega)\). We immediately obtain

\[
(4.1) \quad \|N_{t, \delta}^q f\|_t \leq \varepsilon \|f\|_t.
\]

Since \(N_{t, \delta}^q f \in W^2_{0, q}\), we can set \(u = D_T N_{t, \delta}^q f\) and obtain \(u \in W^1_{0, q}(\Omega) \cap \text{Dom}(\bar{\partial}_t^\ast)\). Hence,

\[
(4.2) \quad \|D_T N_{t, \delta}^q f\|_t^2 \leq \varepsilon Q_{t_\varepsilon, \delta}(D_T N_{t, \delta}^q f, D_T N_{t, \delta}^q f).
\]
To estimate $Q_{t,\delta}(D_T N_{t,\delta}^{0} f, D_T N_{t,\delta}^{0} f)$, we will need to work with slightly smoother forms. To that end, we introduce the following density lemma:

**Lemma 4.1.** Let $\Omega \subset M$ be a bounded domain with $C^3$ boundary, and let $u \in W^1_{(0,q)}(\Omega) \cap \text{Dom}(\bar{\partial}_t^*).$ Then there exists a sequence $u_\ell \in C^2_{(0,q)}(\Omega) \cap \text{Dom}(\bar{\partial}_t^*)$ converging to $u$ in the $W^1$ norm.

**Proof.** Let $\rho$ be a $C^3$ defining function for $\Omega$, and let

$$I_q = \left\{ f \in L^2_{(0,q)}(\Omega) : f = \bar{\partial}_\rho \wedge g, g \in L^2_{(0,q-1)}(\Omega) \right\}.$$  

Choose $\chi \in C_0^\infty(M)$ such that $\chi = 1$ in a neighborhood of $\partial\Omega$ and $\bar{\partial}\rho \neq 0$ on the support of $\chi$. If we let $\nu$ denote the orthogonal projection onto $I_q$ where defined, then $\chi\nu$ is a linear operator with $C^2(\Omega)$ coefficients. Since $u \in W^1_{(0,q)}(\Omega)$, $u$ has a boundary trace in $L^2$. By the usual density lemma (e.g., Lemma 4.3.2 in [CS01]) and the usual characterization of $\text{Dom}(\bar{\partial}_t^*)$ (e.g., Lemma 4.2.1 in [CS01]), we have that the boundary trace of $\chi\nu u$ is zero a.e. Since components of $\chi\nu u$ are in $W^1_{(0,q)}(\Omega)$, $\chi\nu u$ is the limit in $W^1$ of a sequence $u_\nu \in C^\infty_{(0,q)}(\Omega)$, so we can write $u_\nu \to \chi\nu u$ in $W^1_{(0,q)}(\Omega)$. We can also write $u$ as a limit in $W^1_{(0,q)}(\Omega)$ of forms $\tilde{u}_\ell \in C^2_{(0,q)}(\Omega)$. If we set $u_\ell = u_\nu + (1 - \chi\nu)\tilde{u}_\ell$, then $u_\ell \to u$ in $W^1_{(0,q)}(\Omega)$ since

$$
\|u_\ell - u\|_{W^1} \leq \|u_\nu - \chi\nu u\|_{W^1} + \|(1 - \chi\nu)(\tilde{u}_\ell - u)\|_{W^1}.
$$

Since $\nu$ has $C^2(\Omega)$ coefficients, $u_\ell$ is in $C^2_{(0,q)}(\Omega)$. Furthermore, since $\nu(1 - \chi\nu) = (1 - \chi)\nu$, we have $\nu u_\ell = 0$ on the boundary of $\Omega$, so $u_\ell \in \text{Dom}(\bar{\partial}_t^*)$. 

With this density lemma in place, we are ready to prove the key lemma for our estimate (analogous to (3.50) in [Str10]).

**Lemma 4.2.** Let $\Omega \subset M$ be a bounded domain with connected $C^3$ boundary satisfying weak $Z(q)$. There exist constants $C > 0$ independent of $t$ and $C_t > 0$ depending on $t$ such that for any $f \in W^1_{(0,q)}(\Omega)$ and differential operator $T$ with $C^2(\Omega)$ coefficients that is tangential on the boundary of $\Omega$, we have

$$Q_{t,\delta}(D_T N_{t,\delta}^{0} f, D_T N_{t,\delta}^{0} f) \leq C(D_T f, D_T N_{t,\delta}^{0} f) + C \left\| N_{t,\delta}^{0} f \right\|_{t, W^1}^2 + C_t \| f \|_{t}^2. $$

**Proof.** We will adopt the convention that the values of $C > 0$ and $C_t > 0$ may increase from line to line. Let $u = D_T N_{t,\delta}^{0} f$ and let $u_\ell \in C^2_{(0,q)}(\Omega) \cap \text{Dom}(\bar{\partial}_t^*)$ be the sequence converging to $D_T N_{t,\delta}^{0} f$ given by Lemma 4.1. Note that the principal part of $\bar{\partial}_t^*$ is the same as the principal part of $\bar{\partial}^*$, so only the low order terms depend on $t$. Hence, $[D_T, \bar{\partial}_t^*]$ has a first order component which is independent of $t$ and a lower order component which depends on $t$, so

$$
\left\| [D_T, \bar{\partial}_t^*] N_{t,\delta}^{0} f \right\|_t \leq C \left\| N_{t,\delta}^{0} f \right\|_{t, W^1} + C_t \left\| N_{t,\delta}^{0} f \right\|_t
$$

$$
\leq C \left\| N_{t,\delta}^{0} f \right\|_{t, W^1} + C_t \| f \|_t,
$$

respectively.
where the second inequality follows from (4.1). Estimating commutators in this fashion gives us

\[ Q_{t,\delta}(u, u_t) \leq (DT\bar{\partial}_{t,\delta}^q f, \bar{\partial}u_t)_t + (DT\bar{\partial}_{t,\delta}^q f, [D_{T}]^{\star}_t, \bar{\partial}u_t)_t + \delta(DT\nabla N_{t,\delta}^q f, \nabla u_t)_t + C \left( \left\| N_{t,\delta}^q f \right\|_{t, W^1} + C_t \left\| f \right\|_t \right) \sqrt{Q_{t,\delta}(u_t, u_t)}. \]

Since \( T \) is tangential, we can integrate by parts and commute again to obtain

\[ Q_{t,\delta}(u, u_t) \leq Q_{t,\delta}(N_{t,\delta}^q f, (DT)^{\star}_t u_t) + (\bar{\partial}N_{t,\delta}^q f, [(DT)^{\star}_t, \bar{\partial}]u_t)_t + \delta(\nabla N_{t,\delta}^q f, [(DT)^{\star}_t, \nabla]u_t)_t + C \left( \left\| N_{t,\delta}^q f \right\|_{t, W^1} + C_t \left\| f \right\|_t \right) \sqrt{Q_{t,\delta}(u_t, u_t)}. \]

By definition,

\[ Q_{t,\delta}(N_{t,\delta}^q f, (DT)^{\star}_t u_t) = (f, (DT)^{\star}_t u_t)_t = (DT f, u_t)_t. \]

Since all terms with \( u_t \) can now be estimated by the \( W^1 \) norm of \( u_t \), we can take limits and obtain

\[ Q_{t,\delta}(u, u) \leq (DT f, u)_t + (\bar{\partial}N_{t,\delta}^q f, [(DT)^{\star}_t, \bar{\partial}]u)_t + \delta(\nabla N_{t,\delta}^q f, [(DT)^{\star}_t, \nabla]u)_t + C \left( \left\| N_{t,\delta}^q f \right\|_{t, W^1} + C_t \left\| f \right\|_t \right) \sqrt{Q_{t,\delta}(u, u)}. \]

Now, we may also use the estimate

\[ \left( C \left\| N_{t,\delta}^q f \right\|_{t, W^1} + C_t \left\| f \right\|_t \right) \sqrt{Q_{t,\delta}(u, u)} \leq \frac{1}{2} \left( C \left\| N_{t,\delta}^q f \right\|_{t, W^1} + C_t \left\| f \right\|_t \right)^2 + \frac{1}{2} Q_{t,\delta}(u, u) \]

and absorb the last term in the left-hand side to obtain

\[ Q_{t,\delta}(u, u) \leq 2(DT f, u)_t + 2(\bar{\partial}N_{t,\delta}^q f, [(DT)^{\star}_t, \bar{\partial}]u)_t + 2\delta(\nabla N_{t,\delta}^q f, [(DT)^{\star}_t, \nabla]u)_t + 2C \left( \left\| N_{t,\delta}^q f \right\|_{t, W^1} + C_t \left\| f \right\|_t^2 \right)^2 \]

The remaining commutators will each be estimated using the same technique; we will illustrate the method with \([\bar{\partial}^*_t N_{t,\delta}^q f, [(DT)^{\star}_t, \bar{\partial}^*_t]u_t]_t\) since it could potentially involve additional factors of \( t \). Recall that \( \nabla_T \) has \( C^2 \) coefficients, while \( DT - \nabla_T \) is a zero-order operator with \( C^1 \) coefficients. Since adjoints of zero-order operators won’t introduce additional factors of \( t \), we can break down the commutator as follows:

\[ (4.4) \quad [(DT)^{\star}_t, \bar{\partial}^*_t] = [(DT - \nabla_T)^{\star}_t, \bar{\partial}^*] + [(DT - \nabla_T)^{\star}_t, (\bar{\partial}^*_t - \bar{\partial}^*)] + [(\nabla_T)^{\star}_t, \bar{\partial}^*_t], \]

The zero-order component of \([[(DT - \nabla_T)^{\star}_t, \bar{\partial}^*] \) is independent of \( t \) but only has continuous coefficients; we denote this \( A \). If we let \( B_t = [(DT)^{\star}_t, \bar{\partial}^*_t] - A \), then \( B_t \) is a first-order operator depending on \( t \) (in the zero-order component) with \( C^1 \)
coefficients. Thus, if we commute $D_T$ with $B_t$ but not $A$ we obtain
\[
(\bar{\partial_t} N_{t,\delta}^q f, [(D_T)_t^* \bar{\partial_t^*}] u)_t = (\bar{\partial_t} N_{t,\delta}^q f, (A + B_t)_{D_T} N_{t,\delta}^q f)_t \\
\leq (\bar{\partial_t} N_{t,\delta}^q f, D_T B_t N_{t,\delta}^q f)_t + C \left\| N_{t,\delta}^q f \right\|_{t,W^1}\|f\|_t^2.
\]
Integrating $D_T$ by parts, commuting with $\bar{\partial_t^*)$, and using (4.2), we have
\[
(\bar{\partial_t} N_{t,\delta}^q f, [(D_T)_t^* \bar{\partial_t^*}] u)_t = (\bar{\partial_t} (D_T) N_{t,\delta}^q f, B_t N_{t,\delta}^q f)_t + C \left\| N_{t,\delta}^q f \right\|_{t,W^1}\|f\|_t^2.
\]
However, this can be bounded by
\[
(\bar{\partial_t} N_{t,\delta}^q f, [(D_T)_t^* \bar{\partial_t^*}] u)_t \leq \sqrt{Q_{t,\delta}((D_T) N_{t,\delta}^q f, (D_T) N_{t,\delta}^q f)} \times \left(C \left\| N_{t,\delta}^q f \right\|_{t,W^1} + C_t \|f\|_t \right) + C \left\| N_{t,\delta}^q f \right\|_{t,W^1} + C_t \|f\|_t^2.
\]
The same upper bound will be obtained if $\bar{\partial_t^*}$ is replaced with $\bar{\partial}$ or $\nabla$, so we have
\[
(4.5) \quad Q_{t,\delta}(u, u) \leq \sqrt{Q_{t,\delta}((D_T) N_{t,\delta}^q f, (D_T) N_{t,\delta}^q f)} \left(C \left\| N_{t,\delta}^q f \right\|_{t,W^1} + C_t \|f\|_t \right) + 2(D_T f, u)_t + C \left\| N_{t,\delta}^q f \right\|_{t,W^1} + C_t \|f\|_t^2.
\]
Note that $(D_T)_t^* = -D_T + a_t$, where $a_t$ is a $C^1$ function depending on $t$. In particular,
\[
Q_{t,\delta}((D_T) N_{t,\delta}^q f + u, (D_T) N_{t,\delta}^q f + u) = Q_{t,\delta}(a_t N_{t,\delta}^q f, a_t N_{t,\delta}^q f) \\
\leq (f, a_t^2 N_{t,\delta}^q f)_t + C_t \|f\|_t \sqrt{Q_{t,\delta}((D_T) N_{t,\delta}^q f, (D_T) N_{t,\delta}^q f)}.
\]
After using the small constant/large constant inequality to absorb the $Q_{t,\delta}$ term on the right-hand side, we have
\[
Q_{t,\delta}((D_T) N_{t,\delta}^q f + u, (D_T) N_{t,\delta}^q f + u) \leq C_t \|f\|_t^2,
\]
and hence
\[
Q_{t,\delta}((D_T) N_{t,\delta}^q f, (D_T) N_{t,\delta}^q f) \leq C Q_{t,\delta}(u, u) + C_t \|f\|_t^2.
\]
Substituting this into (4.5) and again using the small constant/large constant estimate to absorb the $Q_{t,\delta}$ term on the left-hand side will imply (4.3). \qed

Combining Lemma 4.2 and (4.2), we have
\[
\left\| D_T N_{t,\delta}^q f \right\|_{t}^2 \leq \varepsilon C \left( \left\| (D_T f, D_T N_{t,\delta}^q f) \right\|_t^2 + \left\| N_{t,\delta}^q f \right\|_{t,W^1}^2 \right) + C_t \|f\|_t^2.
\]
Another application of the small constant/large constant inequality to the first term on the right-hand side gives us
\[
\left\| D_T N_{t,\delta}^q f \right\|_{t}^2 \leq \varepsilon C \left( \|f\|_{t,W^1}^2 + \left\| N_{t,\delta}^q f \right\|_{t,W^1}^2 \right) + C_t \|f\|_t^2.
\]
By Lemma 2.2 in [Str10], the normal derivatives of $N_{t,\delta}^q f$ consist of linear combinations of $\bar{\partial} N_{t,\delta}^q f$, $\bar{\partial} N_{t,\delta}^q f$, and tangential derivatives of $N_{t,\delta}^q f$. We can convert $\bar{\partial}^*$ to
\[ \partial_t^* \] by adding a zeroth order term, so summing over all tangential derivatives and the normal derivative gives us

\[
\left\| N_{t,\delta}^q f \right\|_{t,W^{1,1}}^2 \leq \varepsilon C \left( \|f\|_{t,W^{1,1}}^2 + \left\| N_{t,\delta}^q f \right\|_{t,W^{1,1}}^2 \right) + C_t \|f\|_{t,W^{1,1}}^2.
\]

When \( \varepsilon \) is sufficiently small (and hence \( t \) is sufficiently large), we can absorb the \( W^1 \) norm of \( N_{t,\delta}^q f \) on the left-hand side, obtaining

\[
(4.6) \quad \left\| N_{t,\delta}^q f \right\|_{t,W^{1,1}}^2 \leq \varepsilon C \|f\|_{t,W^{1,1}}^2 + C_t \|f\|_{t,W^{1,1}}^2.
\]

Since all constants have been chosen independently of \( \delta \), the usual limiting argument will give us \( W^1 \) estimates for \( N_{t}^q \). Standard arguments now give us

**Theorem 4.3.** Let \( M \) be an \( n \)-dimensional Stein manifold, and let \( \Omega \) be a bounded subset of \( M \) with connected \( C^3 \) boundary satisfying weak \( Z(q) \) for some \( 1 \leq q \leq n-1 \). Then there exists a constant \( t > 0 \) such that for all \( t > t \) and \( -\frac{1}{2} \leq s \leq 1 \) we have

1. The weighted \( \partial \)-Neumann operator \( N_{t}^q \) is continuous in \( W^{s}_{(0,q)}(\Omega) \).
2. The canonical solution operators to \( \partial \) given by \( \partial_t^* N_t^q : W^{s}_{(0,q)}(\Omega) \to W^{s}_{(0,q-1)}(\Omega) \) and \( N_t^q \partial_t^* : W^{s}_{(0,q+1)}(\Omega) \cap \text{Dom}(\partial_t^*) \to W^{s}_{(0,q)}(\Omega) \) are continuous.
3. The canonical solution operators to \( \partial_t^* \) given by \( \partial_t N_t^q : W^{s}_{(0,q)}(\Omega) \to W^{s}_{(0,q+1)}(\Omega) \) and \( N_t^q \partial_t : W^{s}_{(0,q-1)}(\Omega) \cap \text{Dom}(\partial) \to W^{s}_{(0,q)}(\Omega) \) are continuous.
4. For every \( f \in W^{s}_{(0,q)}(\Omega) \cap \ker \partial \) there exists a \( u \in W^{s}_{(0,q-1)}(\Omega) \) such that \( \partial u = f \).

**Remark 4.4.** Theorem 4.3 is identical to Theorem 1.2 except for the additional hypothesis that \( \partial \Omega \) is connected. Also, \( \partial_t^* N_t^q \) is a problematic solution operator to \( \partial \) since it places a boundary condition on the data. However, estimates for this operator are needed to obtain estimates for the dual operator \( \partial N_t^q \) in the dual Sobolev space.

**Proof.** We have already completed the proof of (1) when \( s = 0 \) and \( s = 1 \), so interpolation will give us the result for \( 0 < s < 1 \). We emphasize that the weighted Sobolev spaces used in (4.6) are equivalent to standard Sobolev spaces which are amenable to interpolation. When \( -\frac{1}{2} \leq s < 0 \) we use the duality between \( W^s \) and \( W^{-s} \) and the fact that \( N_t^q \) is self-adjoint:

\[
\| N_t^q f \|_{W^s} \leq C_t \sup_{h \in W^{-s}(\Omega), \|h\|_{W^{-s-1}}^s} |(N_t^q f, h)_t| \leq C_t \sup_{h \in W^{-s}(\Omega), \|h\|_{W^{-s-1}}^s} |(f, N_t^q h)_t| \leq C_t \|f\|_{W^s}.
\]

For \( \partial_t^* N_t^q \) and \( \partial N_t^q \), we use Lemma 3.2 in [Str10]. Although this Lemma assumes \( N_t^q \) is smooth, we can use elliptic regularization and Lemma 4.4 as before to obtain sufficient regularity. Interpolation will give us estimates for \( 0 \leq s \leq 1 \).

For \( N_t^q \partial \) and \( \partial_t^* N_t^q \), we first note that since \( f \in W^1_{(0,q)}(\Omega) \) implies \( N_t^q f, \partial N_t^q f, \) and \( \partial_t^* N_t^q f \) are all in \( W^1(\Omega) \), we can conclude that

\[
\partial D_T N_t^q f = [\partial, D_T] N_t^q f + D_T \partial N_t^q f \in L^2_{(0,q+1)}(\Omega).
\]
and 
\[ \partial_t D_T N_{t}^q f = [\partial_t^*, D_T]N_{t}^q f + D_T \partial_t N_{t}^q f \in L^2_{(0,q-1)}(\Omega). \]

Thus we can substitute into (3) of Proposition 3.1 and estimate commutators to obtain
\[ \|D_T N_{t}^q f\|_{t,W}^2 \leq \varepsilon \left( \|D_T \partial_t N_{t}^q f\|_{t,w}^2 + \|D_T \partial_t N_{t}^q f\|_{t,w}^2 + C \|N_{t}^q f\|_{t,W} \right) + C_t \|N_{t}^q f\|_{t}^2. \]

Estimating the normal derivatives using Lemma 2.2 in [Str10] we can estimate the\nW^1 norms of \( N_{t}^q f \), and hence the error term on the right hand side can be absorbed\nto the left for sufficiently small \( \varepsilon > 0 \). Hence we have (after possibly increasing \( t_\varepsilon \))
\[ \|N_{t}^q f\|_{t,W}^2 \leq \varepsilon \left( \|\partial_t^* N_{t}^q f\|_{t,w}^2 + \|\partial_t^* N_{t}^q f\|_{t,w}^2 \right) + C_t \|N_{t}^q f\|_{t}^2. \]

For \( f_1 \in W^2_{(0,q-1)}(\Omega) \), let \( f = \partial_t f_1 \) to obtain
\[ \|N_{t}^q \partial_t f_1\|_{t,W}^2 \leq \varepsilon \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,w}^2 + C_t \|N_{t}^q \partial_t f_1\|_{t}^2. \]

To estimate the projection, we use integration by parts:
\[ \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,w}^2 \leq (N_{t}^q \partial_t f_1, \partial_t f_1)_{t,W} + C \|N_{t}^q \partial_t f_1\|_{t,W} \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,W} \]
\[ + C_t \|N_{t}^q \partial_t f_1\|_{t,w} + \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,w} + C_t \|N_{t}^q \partial_t f_1\|_{t,W} \|\partial_t^* N_{t}^q \partial_t f_1\|_{t}. \]

Repeated use of the small constant/large constant inequality allows us to absorb\nthe \( \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,W}^2 \) terms on the left-hand side and obtain
\[ \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,w}^2 \leq C(N_{t}^q \partial_t f_1, \partial_t f_1)_{t,W} + C \|N_{t}^q \partial_t f_1\|_{t,W}^2 \]
\[ + C_t \|N_{t}^q \partial_t f_1\|_{t,w}^2 + C_t \|\partial_t^* N_{t}^q \partial_t f_1\|_{t}^2. \]

A second integration by parts gives us
\[ \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,w}^2 \leq C(\partial_t^* N_{t}^q \partial_t f_1, f_1)_{t,W} + C \|N_{t}^q \partial_t f_1\|_{t,W} \|f_1\|_{t,W} \]
\[ + C_t \|N_{t}^q \partial_t f_1\|_{t} + \|f_1\|_{t,W} + C \|N_{t}^q \partial_t f_1\|_{t,w}^2 + C_t \|\partial_t^* N_{t}^q \partial_t f_1\|_{t}^2, \]

and more small constant/large constant inequalities yield
\[ \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,w}^2 \leq C \|f_1\|_{t,w}^2 + C \|N_{t}^q \partial_t f_1\|_{t,W}^2 \]
\[ + C_t \|f_1\|_{t,w}^2 + C_t \|N_{t}^q \partial_t f_1\|_{t}^2 + C_t \|\partial_t^* N_{t}^q \partial_t f_1\|_{t}^2. \]

All of the terms with \( C_t \) in front are bounded by \( \|f_1\|_{t,w}^2 \), so
\[ \|\partial_t^* N_{t}^q \partial_t f_1\|_{t,w} \leq C \|f_1\|_{t,w}^2 + C \|N_{t}^q \partial_t f_1\|_{t,W}^2 \]
\[ + C_t \|f_1\|_{t,w}^2. \]

Now we can substitute into the original estimate for \( \|N_{t}^q \partial_t f_1\|_{t,W}^2 \) and, by making \( \varepsilon \) sufficiently small and adjusting \( t_\varepsilon \) we obtain
\[ \|N_{t}^q \partial_t f_1\|_{t,W} \leq \varepsilon \|f_1\|_{t,w}^2 + C_t \|f_1\|_{t,w}^2. \]

For \( f_2 \in W^2_{(0,q+1)}(\Omega) \), let \( f = \partial_t^* f_2 \) and use similar techniques to estimate \( N_{t}^q \partial_t^* f_2 \). Density lets us generalize to \( f_1 \) and \( f_2 \) in \( W^1 \).

As before, we interpolate to obtain estimates for \( 0 < s < 1 \) and use duality to obtain estimates for \( -\frac{1}{2} < s < 0 \) (since we now have estimates for the adjoint of each operator). \( \square \)
5. Proofs of Main Theorems

When \( s < \frac{1}{2} \), we immediately obtain a solution operator for the \( \bar{\partial} \)-Cauchy Problem (see Section 9.1 in [CS01]).

**Corollary 5.1.** Let \( M \) be an \( n \)-dimensional Stein manifold, let \( \Omega \) be a bounded subset of \( M \) with connected \( C^3 \) boundary satisfying weak \( Z(n-q-1) \) for some \( 1 \leq q < n-1 \), and let \(-\frac{1}{2} \leq s < \frac{1}{2}\). For every \( f \in W^{s, q+1}_{0, q} (M) \cap \ker \bar{\partial} \) supported in \( \Omega \), there exists a \( u \in W^s_{0, q} (M) \) supported in \( \Omega \) such that \( \bar{\partial} u = f \), and the solution operator is continuous.

**Proof.** The proof is identical to that given for Proposition 3.4 in [Sha03]. It suffices to have estimates for \( \bar{\partial} N^{(n,n-q-1)} \). On \( Z^{(n-q-1)} \) domains we have estimates for the operator \( \bar{\partial} N^{(0,n-q-1)} \), but these are equivalent since the holomorphic component of \((p,q)\)-forms has no impact on our estimates (except in the curvature terms, but these are all dominated when \( t \) is large).

Furthermore, we can now use techniques of Shaw [Sha10] to remove the requirement that the boundary of \( \Omega \) be connected.

**Corollary 5.2.** Let \( M \) be an \( n \)-dimensional Stein manifold, and let \( \Omega \) be a bounded subset of \( M \) with \( C^3 \) boundary satisfying weak \( Z(q) \) for some \( 1 \leq q < n-1 \). For every \( f \in L^2_{(0,q)} (\Omega) \cap \ker \bar{\partial} \) there exists a \( u \in L^2_{(0,q-1)} (\Omega) \) such that \( \bar{\partial} u = f \). In particular, \( H^q (\Omega) = \{0\} \).

**Remark 5.3.** This is also known for bounded weak \( Z(n-1) \) domains, by Remark 2.10 and Theorem 3.2.

**Proof.** Without loss of generality, assume that \( \Omega \) is connected. By Lemma 2.4 we have the decomposition \( \Omega = \Omega_1 \setminus \bigcup_{j=2}^m \Omega_j \) where \( \Omega_1 \) is a weak \( Z(q) \) domain with connected boundary and each \( \Omega_j \) with \( 2 \leq j \leq m \) is a weak \( Z(n-q-1) \) domain with connected boundary and \( \overline{\Omega_j} \subset \Omega_1 \).

The proof now follows like the proof of Theorem 3.2 in [Sha10], but we must make a few clarifying remarks. Shaw's proof initially finds a solution \( U \) in \( W^{-1} (\Omega_1) \), and then proposes two techniques for regularizing this to a solution in \( L^2 (\Omega_1) \). The first technique requires approximating \( \Omega_1 \) from within by smooth strongly pseudoconvex domains. While we can approximate from within by smooth \( Z(q) \) domains, the role of \( \Upsilon \) on these domains is unpredictable, so the constants in our estimates may not be uniform. Hence, we use the second technique, which decomposes \( U \) into a component supported near the boundary of \( \Omega_1 \) and a compactly supported component. This technique requires solving \( \bar{\partial} \) for compactly supported forms in \( \Omega_1 \), but as Shaw points out, this can be accomplished by solving \( \partial \) on a ball containing \( \Omega_1 \).

This gives us vanishing of \( H^1_t (\Omega) \). However, this is isomorphic to a Dolbeault cohomology group which is independent of \( t \), so the dimension of \( H^q_t (\Omega) \) must also be independent of \( t \). Hence, \( H^q (\Omega) = \{0\} \) as well.

Now that the vanishing of the space of harmonic \((0,q)\)-forms has been established, Theorem 1.1 will follow for the unweighted operators and spaces (see Theorem 4.4.1 in [CS01]) from Theorem 3.2.

In the proof of Theorem 4.3 we required a connected boundary only because it gave us vanishing for the space of harmonic \((0,q)\)-forms. Now that we’ve established
this for disconnected boundaries, the proof of Theorem 1.3 can be carried through
for all bounded domains, as in the statement of Theorem 1.2.

In [Sha85b], Shaw uses the $\bar{\partial}$ operator to solve $\bar{\partial}b$ extrinsically on smooth pseudo-
convex domains. Since we are working on $C^3$ domains, we will more closely follow
the methods of [Sha03], which are adapted to work on non-smooth domains. We
now prove Theorem 1.3.

Proof of Theorem 1.3 We outline the proof, following the construction in [Sha03].
By embedding $M$ in $\mathbb{C}^{2n+1}$, we can pullback a ball containing the image of $\partial\Omega$
to obtain a strictly pseudoconvex set $B$ such that $\Omega \subset B$. Let $\Omega^+ = B \setminus \Omega$ and
$\Omega^- = \Omega$. In [HL81] a Martinelli-Bochner-Koppelman type kernel is constructed for
Stein manifolds, and in [LT87] it is shown that the transformation induced by this
kernel satisfies a jump formula. As a result, there exists an integral kernel $K_q(z, \zeta)$
of type $(0, q)$ in $z$ and $(n, n-q-1)$ in $\zeta$ satisfying a Martinelli-Bochner-Koppelman
formula such that we can define

$$\int_{\partial\Omega} K_q(\zeta, z) \wedge f(\zeta) = \begin{cases}
  f^+(z) & z \in \Omega^+ \\
  f^-(z) & z \in \Omega^-
\end{cases}$$

(see section 2.4 in [HL81]). If, by an abuse of notation, we extend $f^+$ and $f^-$ to
$\partial\Omega$ by considering non-tangential limits, we have the jump formula

$$\tau f^+(z) - \tau f^-(z) = (-1)^q f(z)$$
on $\partial\Omega$ where $\tau$ is defined in (2.1) (see Proposition 2.3.1 in [LT87]). Since $\bar{\partial}_b f = 0$,
we have $\bar{\partial} f^+ = 0$ and $\bar{\partial} f^- = 0$. Since $f^+$ and $f^-$ have non-tangential boundary
values in $L^2$, they have components in $W^{1/2}$.

Let $E$ denote a linear extension operator from $\Omega^+$ to $B$ that is continuous in
the Sobolev spaces $W^s(\Omega^+)$ for $0 \leq s \leq 1/2$. Applying this componentwise to $f^+$,
we obtain a $(0, q)$-form $Ef^+$ that is in $W^{1/2}(B)$. Since $\bar{\partial} f^+ = 0$ on $\Omega^+$, we have
$\bar{\partial} Ef^+$ supported in $\Omega^-$. Furthermore, $\bar{\partial} Ef^+$ has components in $W^{-1/2}(M)$, so by
Corollary [3.3] there exists $V \in W^{-1/2}(M)$ supported in $\Omega^-$ satisfying $\bar{\partial} V = \bar{\partial} Ef^+$.
Thus $\tilde{f}' = Ef^+ - V \in W^{-1/2}(B)$ satisfies $\bar{\partial} \tilde{f}' = 0$ on $B$ and $\tilde{f}' = f^+$ on $\Omega^+$.

We may now use the canonical solution operator to define $u^+ = \bar{\partial}^* N^q_0 \tilde{f}'$ and
$u^- = \bar{\partial}^* N^q_0 \tilde{f}'$. By interior regularity for $N^q_0$, $u^+$ gains a derivative on compact
subsets of $B$, so $u^+$ has components in $W^{1/2}$ on a neighborhood of $\Omega$. By Theorem
4.3, $u^-$ also has components in $W^{1/2}$. Since each of these forms satisfies an elliptic
system, they have trace values in $L^2(\partial\Omega)$, so abusing notation we can write $u = (-1)^q(u^+ - u^-)$ on $\partial\Omega$. \qed

6. Examples

Our first goal in this section is to motivate Definition 2.1 by constructing an example
where this definition holds but earlier definitions fail. In [HK11] we proposed a more restrictive
definition for weak $Z(q)$. In the context of bounded domains in $\mathbb{C}^n$ with connected boundaries,
this was equivalent to $(q-1)$-pseudoconvexity in the sense of [Zam08]. The key difference is that in $(q-1)$-
pseudoconvexity the eigenvalues of $\Upsilon$ must all be zero or one. This can often be achieved locally by changing
the metric. The critical issue seems to be that if $\Upsilon$ is continuous then $(q-1)$-
pseudoconvexity forces the rank of $\Upsilon$ and the rank of $I - \Upsilon$ to be locally constant.
We will construct an example where this is impossible, but the added flexibility of
Definition [2.1] still allows us to prove closed range results. We summarize the first result of this section as follows:

**Proposition 6.1.** There exists a smooth bounded domain $\Omega \subset \mathbb{C}^3$ with $0 \in \partial\Omega$ such that:

1. There does not exist a hermitian metric in a neighborhood of the origin such that $\partial\Omega$ is 1-pseudoconvex at the origin.
2. In the Euclidean metric, $\partial\Omega$ is weakly $Z(2)$.

In what follows, we assume $M = \mathbb{C}^n$ is equipped with a strictly plurisubharmonic exhaustion function $\varphi$. After adding a pluriharmonic polynomial to $\varphi$, we may assume $\varphi(0) = 0$, $d\varphi(0) = 0$, and $\frac{\partial^2 \varphi}{\partial z_j \partial z_k}(0) = 0$ for all $1 \leq j, k \leq n$. Under these assumptions, $\varphi$ is a defining function for a strictly convex domain when $R$ is sufficiently small.

Let $\psi \in C^\infty(\mathbb{R})$ satisfy $\psi'' \geq 0$ and $\psi(x) = |x|$ for all $|x| \geq 1$. Note that this forces $|\psi'| \leq 1$. Since our main results hold for $C^3$ domains, we could also use a $C^3$ function that is piecewise polynomial to obtain $C^3$ domains, but we will continue to assume that $\psi$ is $C^{\infty}$ in order to make clear that boundary smoothness does not play a role in our counterexamples.

For $r > 0$ set $\psi_r(x) = r \psi \left( \frac{x}{r} \right)$, so that $\psi''_r \geq 0$ and $\psi_r(x) = |x|$ for all $|x| \geq r$. Note that this forces $|\psi'_r| \leq 1$. Given any two defining function $\rho_1$ and $\rho_2$, we wish to construct a smooth approximation to the defining function $\max\{\rho_1, \rho_2\}$. Hence, we define

$$\rho(z) = \frac{1}{2} \psi_r(\rho_1(z) - \rho_2(z)) + \frac{1}{2} (\rho_1(z) + \rho_2(z)).$$

We compute

$$\bar{\partial}\rho = \frac{1}{2} (1 + \psi'_r(\rho_1(z) - \rho_2(z))) \bar{\partial}\rho_1 + \frac{1}{2} (1 - \psi'_r(\rho_1(z) - \rho_2(z))) \bar{\partial}\rho_2$$

$$\partial\bar{\partial}\rho = \frac{1}{2} (1 + \psi'_r(\rho_1(z) - \rho_2(z))) \partial\bar{\partial}\rho_1 + \frac{1}{2} (1 - \psi'_r(\rho_1(z) - \rho_2(z))) \partial\bar{\partial}\rho_2$$

$$+ \frac{1}{2} \psi''_r(\rho_1(z) - \rho_2(z)) (\partial\rho_1 - \partial\rho_2) \wedge (\bar{\partial}\rho_1 - \bar{\partial}\rho_2).$$

Let $\rho_1(z) = -\text{Im} z_n + P(z_1, \ldots, z_{n-1})$, where $P$ is a smooth function vanishing at the origin. Then $\partial\rho_1 = -\frac{1}{2} d\bar{z}_n + \partial P$ and $\bar{\partial}\rho_1 = \partial\bar{\partial} P$. Let $\rho_1$ be the defining function for an unbounded domain $\Omega_1$. For any $z \in \partial\Omega$ and $L \in T_z^{1,0}(\mathbb{C}^n)$, the mapping $L \mapsto L' := L + 2i(\partial\rho_1(L)) \frac{\partial}{\partial z_n}$ projects $L$ onto $L' \in T_z^{1,0}(\partial\Omega_1)$. Note that $i\partial\bar{\partial}\rho_1(i\bar{L} \wedge L) = \mathcal{L}_{\rho_1}(i\bar{L} \wedge L')$. Hence, every eigenvector and eigenvalue of $\mathcal{L}_{\rho_1}$ corresponds to an eigenvector and eigenvalue of $i\partial\bar{\partial}\rho_1$, and the additional eigenvalue of zero corresponds to the eigenvector $\frac{\partial}{\partial z_n}$.

Let $\rho_2(z) = \varphi(z) - R^2$, and recall that this defines a bounded strictly convex domain for $R > 0$ sufficiently small. Then for $r$ and $R$ sufficiently small, $\rho(z) = \rho_1(z)$ in a neighborhood of the origin, but $\rho(z)$ defines a bounded domain. For any $L \in T_z^{1,0}(\partial\Omega_1)$, we check

$$\mathcal{L}_{\rho}(i\bar{L} \wedge L) \geq \frac{1}{2} (1 + \psi'_r(\rho_1(z) - \rho_2(z))) \mathcal{L}_{\rho_1}(i\bar{L} \wedge L') + \frac{1}{2} (1 - \psi'_r(\rho_1(z) - \rho_2(z))) |L|^2.$$

Hence, positive eigenvalues will remain positive, while zero eigenvalues will become positive when $\psi'_r < 1$. We conclude
Lemma 6.2. Let \( \Omega_1 \) be an unbounded domain in \( \mathbb{C}^n \) defined by the defining function \( \rho_1(z) = -\text{Im}z_n + P(z_1, \ldots, z_{n-1}) \) where \( P \) is a smooth function vanishing at the origin. There exists an arbitrarily small bounded domain \( \Omega \) defined by a smooth defining function \( \rho \) such that \( \rho = \rho_1 \) on a neighborhood of the origin and the Levi form of \( \partial \Omega \) has at least as many positive eigenvalues as the Levi form of \( \partial \Omega_1 \) has nonnegative eigenvalues when \( \rho \neq \rho_1 \).

Now, we are ready to introduce our unbounded domain.

Proof of Proposition 6.1. For convenience, we set \( z_1 = x + iy \) and define \( P(z_1, z_2) = 2x|z_2|^2 - xy^3 \). Let \( \Omega_1 \subset \mathbb{C}^3 \) be defined by \( \rho_1(z) = -\text{Im}z_3 + P(z_1, z_2) \). Since \( \bar{\partial}x = \frac{1}{2}d\bar{z}_1 \) and \( \bar{\partial}y = \frac{1}{2}d\bar{z}_1 \) we compute:

\[
\bar{\partial}\rho_1 = \left( |z_2|^2 - \frac{1}{2}y^4 - 2ixy^3 \right) d\bar{z}_1 + 2xzz_2d\bar{z}_2 - \frac{i}{2}d\bar{z}_3
\]

and

\[
(6.1) \quad \bar{\partial}\partial\rho_1 = -3xy^2z_1 \wedge d\bar{z}_1 + z_2dz_1 \wedge d\bar{z}_2 + \bar{z}_2dz_2 \wedge d\bar{z}_1 + 2xzd\bar{z}_2 \wedge d\bar{z}_2.
\]

We choose a basis for \( T^{1,0}(\partial\Omega_1) \) by setting \( L_j = \frac{\partial}{\partial z_j} + 2i\frac{\partial P}{\partial \bar{z}_j} \frac{\partial}{\partial \bar{z}_j} \) for \( 1 \leq j \leq 2 \). Under this basis we can represent the Levi form by the matrix \( c_{jk} = \mathcal{L}_{\rho_1}(i\bar{L}_k \wedge L_j) = i\bar{\partial}\partial\rho_1 \left( i\frac{\partial}{\partial z_k} \wedge \frac{\partial}{\partial \bar{z}_j} \right) \). Note that

\[
\text{det} \begin{pmatrix} \frac{-3xy^2}{2x} & \frac{z_2}{2x} \\ \frac{z_2}{2x} & \frac{2}{2x} \end{pmatrix} = -6x^2y^2 - |z_2|^2.
\]

Since this is nonpositive, the Levi form always has one nonpositive and one nonnegative eigenvalue. When \( z_2 \neq 0 \) or both \( x \neq 0 \) and \( y \neq 0 \), then the determinant is strictly negative so the Levi form has one negative eigenvalue and one positive eigenvalue. In this case, \( Z(2) \) is satisfied. If the determinant vanishes but \( x(2 - 3y^2) > 0 \), then the Levi form has one positive eigenvalue and one zero eigenvalue, so \( Z(2) \) still holds.

Both 1-pseudoconvexity and the definition of weak \( Z(2) \) given in [HR11] require orthonormal coordinates. For an arbitrary hermitian metric, let \( u_1 \) and \( u_2 \) be an orthonormal basis for \( T^{1,0}(\partial\Omega_1) \). Each of these can be written in the form

\[
u_j = \sum_{k=1}^{2} a_j^k L_k
\]

for smooth functions \( a_j^k \). We use \( c_{jk}^u \) to denote the Levi form with respect to these new coordinates, and note that

\[
(6.2) \quad c_{jk}^u = \sum_{\ell, m=1}^{2} a_{j}^{\ell} c_{\ell m} \bar{a}_{k}^{m}.
\]

The eigenvalues of \( c^u \) will be denoted \( \mu_1^u \leq \mu_2^u \). Computing the trace, we have

\[
\mu_1^u + \mu_2^u = \sum_{k, \ell, m=1}^{2} a_{j}^{\ell} c_{\ell m} \bar{a}_{k}^{m} = \sum_{\ell, m=1}^{2} g_{\ell m} c_{\ell m}
\]

where \( g_{\ell m} \) is a positive definite \( 2 \times 2 \) hermitian matrix. Substituting (6.1), we have

\[
(6.3) \quad \mu_1^u + \mu_2^u = -3xy^2g^{11} + 2\text{Re}(z_2g^{21}) + 2xyg^{22}.
\]
For $\partial \Omega$ to be 1-pseudoconvex, we need either $\mu_1^\varphi + \mu_2^\varphi \geq 0$ or $\mu_1^\varphi + \mu_2^\varphi - c_{11}^\varphi \geq 0$. We will show that each of these leads to contradictions.

First, assume that $\mu_1^\varphi + \mu_2^\varphi \geq 0$. Set $y = 0$, so that by (6.5), $2 \text{Re}(z_2 g^{21}) + 2xg^{22} \geq 0$. Since the left hand side of this inequality equals zero when $x = z_2 = 0$, this must be a critical point and hence all first derivatives in $x$ or $z_2$ will also vanish when $x = z_2 = 0$. Hence, when $x = z_2 = 0$ we have $g^{21} = g^{22} = 0$. However, this implies that $g^{\bar{m}\ell}$ has rank 1, contradicting the fact that $g^{\bar{m}\ell}$ is nondegenerate. Thus $\mu_1^\varphi + \mu_2^\varphi$ can not be nonnegative in a neighborhood of the origin.

Now, we assume that $\mu_1^\varphi + \mu_2^\varphi - c_{11}^\varphi \geq 0$. Combining our assumption with (6.3) yields

$$-3xy^2(g^{11} - |a_1|^2) + 2 \text{Re}(z_2(g^{21} - a_1^1a_1^2)) + 2x(g^{22} - |a_1|^2) \geq 0.$$  

As before, derivatives in $x$ and $z_2$ must vanish when $x = z_2 = 0$, so at these points we have $g^{21} - a_1^1a_1^2 = 0$ and

$$-3y^2(g^{11} - |a_1|^2) + 2(g^{22} - |a_1|^2) = 0.$$  

When $y \neq 0$, this means that the rank of $g^{kj} - \bar{a}_1^k a_1^j$ is either zero or two. However,

$$g^{\bar{m}\ell} - \bar{a}_1^m a_1^\ell = \sum_{j,k=1}^2 \bar{a}_k^m (\delta_{kj} - \delta_{j1} \delta_{k1}) a_1^\ell.$$  

Hence $g^{kj} - \bar{a}_1^k a_1^j$ must have rank one, contradicting the fact that it must have a rank of zero or two. We conclude that $\mu_1^\varphi + \mu_2^\varphi - c_{11}^\varphi$ can not be nonnegative in a neighborhood of the origin.

Since the above construction was carried out for an arbitrary metric, we conclude that there is no metric in a neighborhood of the origin in which $\partial \Omega$ is 1-pseudoconvex.

We must now show that Definition 2.1 holds for this domain under the Euclidean metric (i.e., $\varphi = |z|^2$). If $u_1$ and $u_2$ are orthonormal vectors in the span of $L_1$ and $L_2$ then the sum of the two smallest eigenvalues of the Levi form are

$$\mu_1 + \mu_2 = \mathcal{L}(i \bar{u}_1 \wedge u_1 + i \bar{u}_2 \wedge u_2).$$  

If

$$\Upsilon_t = i \bar{u}_1 \wedge u_1 + i \bar{u}_2 \wedge u_2 - t(2i \bar{L}_1 \wedge L_1 + 3y^2 i \bar{L}_2 \wedge L_2),$$

then

$$\mu_1 + \mu_2 - \mathcal{L}(\Upsilon_t) = 0,$$

so (2) of Definition 2.1 is satisfied. Since $L_1$ and $L_2$ are also in the span of $u_1$ and $u_2$, condition (1) will follow for $t \geq 0$ sufficiently small. Finally, $\omega(\Upsilon_t) = 2 - t(2 |L_1|^2 + 3y^2 |L_2|^2)$, so condition (3) holds for any $t \neq 0$. Hence $\Omega_1$ satisfies weak $Z(2)$.

We use Lemma 6.2 to turn our example into a bounded domain. We have already shown that weak $Z(2)$ is satisfied in the interior of the set where $\rho = \rho_1$, and it is automatically satisfied at all points where $\rho \neq \rho_1$ because the usual definition of $Z(2)$ holds, so it remains to check the points on the boundary of the set where $\rho = \rho_1$. At such points, let $\bar{L}_1$ and $\bar{L}_2$ be smooth extensions of $L_1$ and $L_2$. If $\bar{u}_1$ and $\bar{u}_2$ are orthonormal vectors in the span of $\bar{L}_1$ and $\bar{L}_2$, we define

$$\Upsilon_t = i \bar{u}_1 \wedge \bar{u}_1 + i \bar{u}_2 \wedge \bar{u}_2 - t(2i \bar{L}_1 \wedge L_1 + 3y^2 i \bar{L}_2 \wedge \bar{L}_2).$$
We still have
\[ \mu_1 + \mu_2 - \mathcal{L}(\Upsilon_t) = t\mathcal{L}(2i\bar{L} \wedge \bar{L} + 3y^2i\bar{L}_2 \wedge \bar{L}_2). \]

This quantity is zero when \( \rho = \rho_1 \), and by construction we are adding a positive component to \( \mathcal{L} \) when we transition to \( \rho_2 \), so \( \mu_1 + \mu_2 - \mathcal{L}(\Upsilon_t) \geq 0 \) in a neighborhood of the set where \( \rho = \rho_1 \). Using the patching argument of Lemma 2.6, a global \( \Upsilon \) can be obtained. \( \square \)

We will also construct an example demonstrating that our condition is not invariant under changes of metric. Roughly speaking, this example contains a direction which is poorly behaved (at some points in a neighborhood of the origin this direction is an eigenvector of the Levi form with a negative eigenvalue, while at other points it can be an eigenvector corresponding to the largest positive eigenvalue). In order for weak \( Z(2) \) to be satisfied, the metric must be chosen to minimize the size of this direction (and prevent it from corresponding to the largest positive eigenvalue).

**Proposition 6.3.** There exists a bounded domain \( \Omega \subset \mathbb{C}^4 \) with smooth boundary such that

1. \( \partial\Omega \) does not satisfy weak \( Z(2) \) under the Euclidean metric.
2. There exists a strictly plurisubharmonic exhaustion function \( \varphi \) for \( \mathbb{C}^4 \) such that \( \partial\Omega \) satisfies weak \( Z(2) \) with respect to the metric \( \omega = i\partial\bar{\partial}\varphi \).

**Proof.** As before, we can construct an unbounded domain and use Lemma 6.2 to make this bounded. To minimize the number of subscripts, we will write \( \rho \) in place of the \( \rho_1 \) used in the statement of Lemma 6.2. As above, let \( z_1 = x + iy \) and \( \rho(z) = -\text{Im}z_4 + P(z_1, z_2, z_3) \) where \( P(z_1, z_2, z_3) = -9|z_1|^4 + 6(x^2|z_2|^2 + y^2|z_3|^2) + |z_2|^2|z_3|^2 + \frac{1}{4}(|z_2|^4 + |z_3|^4) \). We choose a basis for \( T^{1,0}(\partial\Omega) \) by setting \( L_j = \frac{\partial}{\partial z_j} + 2i\frac{\partial P}{\partial z_j} \) for \( 1 \leq j \leq 3 \).

We compute
\[
\bar{\partial} \rho = \left(-18|z_1|^2z_1 + 6x|z_2|^2 + 6iy|z_3|^2\right)dz_1 + \left(6x^2z_2 + |z_3|^2z_2 + \frac{1}{2}|z_2|^2z_2\right)dz_2 + \left(6y^2z_3 + |z_2|^2z_3 + \frac{1}{2}|z_3|^2z_3\right)dz_3 - \frac{i}{2}d\bar{z}_4
\]
and
\[
i\partial\bar{\partial} \rho = i(-36|z_1|^2 + 3|z_2|^2 + 3|z_3|^2)dz_1 \wedge d\bar{z}_1 + i(6x^2 + |z_2|^2 + |z_3|^2)dz_2 \wedge d\bar{z}_2 + i(6y^2 + |z_2|^2 + |z_3|^2)dz_3 \wedge d\bar{z}_3 + 6ix(z_2dz_1 \wedge d\bar{z}_2 + \bar{z}_2d\bar{z}_2 \wedge d\bar{z}_1) + 6iy(-iz_3dz_1 \wedge d\bar{z}_3 + i\bar{z}_3d\bar{z}_3 \wedge d\bar{z}_1) + i(\bar{z}_2z_3dz_2 \wedge d\bar{z}_3 + z_2\bar{z}_3dz_2 \wedge d\bar{z}_3).
\]

If we consider the \( 2 \times 2 \) block spanned by \( d\bar{z}_2 \) and \( dz_3 \), we can see that this is positive definite unless \( z_2 = z_3 = 0 \) and either \( x = 0 \) or \( y = 0 \). Hence, the Levi form has at least two positive eigenvalues and satisfies \( Z(2) \) except on this set.

To define our metric, we let \( \varphi_t(z) = t|z_1|^2 + \sum_{j=2}^4|z_j|^2 \) for some fixed \( t \geq 1 \) and use the Kähler form \( \omega_t = i\partial\bar{\partial}\varphi_t \). Note that \( \omega_t \) is the Euclidean metric. We set \( L_1^1 = L_1, L_2^1 = L_2 \) and \( L_3^1 = L_3 \). If we use the notation \( P^t_j = L_1^tP_t \), then in this basis our metric can be written \( g^t_{jk} = i\partial\bar{\partial}\varphi_t(i\bar{L}_k^t \wedge \bar{L}_j^t) = \langle L_j^t, L_k^t \rangle = \delta_{jk} + 4P^t_jP^t_k \).
We write
\[ \Upsilon_t = i \sum_{j,k=1}^{n-1} b_{kj}^t \bar{L}_k^t \wedge L_j^t. \]

When \( y = z_2 = z_3 = 0 \), we have \( \delta \bar{\partial} \rho = -36ix^2dz_1 \wedge d\bar{z}_1 + 6ix^2dz_2 \wedge d\bar{z}_2 \), \( P_j^t = 0 \) if \( j = 2,3 \) and \( P_1^t = -\frac{\delta}{\sqrt{t}} x^3 \). Consequently, the eigenvalues of \( \Upsilon \) are \( \mu_1 = \frac{-36x^2}{t(1+4|P_1^t|^2)} = -\frac{36x^2}{t} + O(x^8) \), \( \mu_2 = 0 \), and \( \mu_3 = 6x^2 \). To check condition (2) of Definition 2.1 we compute
\[ \mu_1 + \mu_2 - \Upsilon(\Upsilon_t) = \frac{-36x^2}{t}(1 - b_{11}^t) - 6x^2b_{22}^t + O(x^8). \]

Since \( b_{22}^t \geq 0 \) and \( 1 \geq b_{11}^t + O(x^6) \), (by condition (1) of Definition 2.1) nonnegativity requires \( b_{22}^t = 0 \) and \( b_{11}^t = 1 + O(x^6) \). Similar computations when \( x = z_2 = z_3 = 0 \) require \( b_{33}^t = 0 \) on this set. At the origin, \( \Upsilon_t \) is now represented by a matrix whose eigenvalues are bounded between 0 and 1 (by condition (1) of Definition 2.1 again) with diagonal entries of 0 and 1, so the off-diagonal entries must vanish. Hence, \( \Upsilon_t = iL_1^t \wedge L_1^t \) at the origin. Since nonvanishing terms of order \( O(|z|) \) would cause the eigenvalues of \( \Upsilon_t \) to grow larger than 1 or smaller than 0 in some direction, we conclude that \( \Upsilon_t = iL_1^t \wedge L_1^t + O(|z|^2) \) near the origin.

We note that \( \mu_1 + \mu_2 - \Upsilon(\Upsilon_t) \geq 0 \) (condition (2) in Definition 2.1) is equivalent to \( \text{Tr } \Upsilon - \Upsilon(\Upsilon_t) \geq \mu_1 \), which is in turn equivalent to \( (\text{Tr } \Upsilon - \Upsilon(\Upsilon_t))\omega_t - i\delta \bar{\partial} \rho \geq 0 \) on \( T^{1,0}(\partial \Omega) \). Note that the inverse of our metric is
\[ g_{ij}^t = \delta_{ij} - \frac{4}{1 + \frac{3}{4} |P^t|^2} P_k^t P_j^t = \delta_{ij} - 4P_k^t P_j^t (1 + O(|P^t|^2)). \]

If \( \{u_j\} \) is an orthonormal basis of \( T^{1,0}(\partial \Omega) \) near 0, then
\[ \text{Tr } \Upsilon = \sum_{t=1}^3 \Upsilon(i\bar{u}_t \wedge u_t) = \sum_{j,k=1}^3 g_{kj}^t \Upsilon(i\bar{L}_k^t \wedge L_j^t) = \frac{1}{t} (-36|z_1|^2 + 3|z_2|^2 + 3|z_3|^2)g_{11}^t + 6|z_1|^2 + 2(|z_2|^2 + |z_3|^2) + O((|z_2|^2 + |z_3|^2)|z|^6), \]

where
\[ g_{11}^t = \frac{1}{1 + 1296t^{-1}|z_1|^6} + O((|z_2|^2 + |z_3|^2)|z|^4). \]
The \( g_{11}^t \) term is left intact in the computation because it does not lead to a term of the form \( O((|z_2|^2 + |z_3|^2)|z|^6) \). In any case,
\[ \text{Tr } \Upsilon - \Upsilon(\Upsilon_t) = 6|z_1|^2 + 2(|z_2|^2 + |z_3|^2) + O(|z|^4). \]

If we test positivity of \( (\text{Tr } \Upsilon - \Upsilon(\Upsilon_t))\omega_t - i\delta \bar{\partial} \rho)(i\bar{L}_1^t \wedge L_1^t) \), we see that this is equivalent to
\[ 6|z_1|^2 + 2(|z_2|^2 + |z_3|^2) - \frac{1}{t} (-36|z_1|^2 + 3|z_2|^2 + 3|z_3|^2) + O(|z|^4) \geq 0. \]

Considering coefficients of \( |z_2|^2 \), it is necessary that \( 2 \geq \frac{9}{4} t \), or \( t \geq \frac{2}{9} \). Since the Euclidean metric corresponds to \( t = 1 \), weak \( Z(2) \) will fail for the Euclidean metric.

For the positive result, we set \( \Upsilon_t = i(g_{11}^t)^{-1} L_1^t \wedge L_1^t \), so that conditions (1) and (3) are immediately satisfied. Note that \( (g_{11}^t)^{-1} = g_{11}^t + O((|z_2|^2 + |z_3|^2)|z|^4) \), so we have
\[ \text{Tr } \Upsilon - \Upsilon(\Upsilon_t) = 6|z_1|^2 + 2(|z_2|^2 + |z_3|^2) + O((|z_2|^2 + |z_3|^2)|z|^6). \]
For \(|z|\) sufficiently small, this gives us
\[
\text{Tr } \mathcal{L} - \mathcal{L}(T_t) \geq 6 |z_1|^2 + \frac{3}{2} (|z_2|^2 + |z_3|^2).
\]
Hence,
\[
(\text{Tr } \mathcal{L} - \mathcal{L}(T_t)) \omega_t - i\partial \bar{\partial} \rho \geq i \left( 6(t + 6) |z_1|^2 + \frac{3}{2} (t - 2) (|z_2|^2 + |z_3|^2) \right) dz_1 \wedge d\bar{z}_1
+ i \left( 6y^2 + \frac{1}{2} (|z_2|^2 + |z_3|^2) \right) dz_2 \wedge d\bar{z}_2 + i \left( 6x^2 + \frac{1}{2} (|z_2|^2 + |z_3|^2) \right) dz_3 \wedge d\bar{z}_3
- 6ix(z_2 dz_1 \wedge d\bar{z}_2 + \bar{z}_2 d\bar{z}_2 \wedge d\bar{z}_1) - 6iy(-i z_3 dz_1 \wedge d\bar{z}_3 + i \bar{z}_3 d\bar{z}_3 \wedge d\bar{z}_1)
- i(\bar{z}_2 z_3 dz_2 \wedge d\bar{z}_3 + \bar{z}_2 \bar{z}_3 d\bar{z}_3 \wedge d\bar{z}_2).
\]
To check that this is positive for \(t \geq 6\), we first evaluate the determinant of the \(2 \times 2\) minor spanned by \(dz_2\) and \(dz_3\):
\[
\left( 6y^2 + \frac{1}{2} (|z_2|^2 + |z_3|^2) \right) \left( 6x^2 + \frac{1}{2} (|z_2|^2 + |z_3|^2) \right) - |z_2|^2 |z_3|^2 =
36x^2 y^2 + 3 |z_1|^2 (|z_2|^2 + |z_3|^2) + \frac{1}{4} (|z_2|^2 - |z_3|^2)^2.
\]
Since this determinant is nonnegative and the terms of the diagonal are nonnegative, it follows from [HJ85] Theorem 4.3.8 that the form under consideration must have at least two nonnegative eigenvalues. Noting that the determinant of this minor is bounded below by \(3 |z_1|^2 (|z_2|^2 + |z_3|^2)\), we can bound the determinant of the entire \(3 \times 3\) form below by
\[
3 |z_1|^2 (|z_2|^2 + |z_3|^2) \left( 6(t + 6) |z_1|^2 + \frac{3}{2} (t - 2) (|z_2|^2 + |z_3|^2) \right)
- 36y^2 |z_3|^2 \left( 6y^2 + \frac{1}{2} (|z_2|^2 + |z_3|^2) \right) - 36x^2 |z_2|^2 \left( 6x^2 + \frac{1}{2} (|z_2|^2 + |z_3|^2) \right).
\]
Substituting \(t \geq 6\) into this we can check that the positive terms dominate the negative terms, so the form is positive and weak \(Z(2)\) is satisfied for \(|z|\) sufficiently small. Lemma [6.2] can now be used to create a bounded domain where \(|z|\) remains sufficiently small for weak \(Z(2)\) to hold on the entire domain. □

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