Improved Linear Regression Using Auxillary Informations

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ABSTRACT
The present study was taken under consideration in order to propose improved linear regression using auxiliary information’s of coefficient of regression, coefficient of skewness, coefficient of variation in order to achieve more precision in estimates than the already existing estimators. The properties associated with the proposed estimators are assessed by mean square error and bias and compared with the existing estimators. In the support of the theoretical proposed work we have given numerical illustration.

Keywords: Auxiliary Information, Linear regression, Mean square error, Bias, Efficiency.

INTRODUCTION
A Regression type estimator using known coefficient of variation is considered and its properties are studied. There are several instances in physical, biological and agricultural sciences where the mean is Proportional to standard deviation and consequently the coefficient of variation is known although the mean and standard deviation may not be known. Some such situations may be seen in Snedecor (1946), Hald (1952), Davies and Goldsmith (1976) and Gleser and Healy (1976). The well-known Weber’s law of psychophysics (see Guilford (1975), Chapter II provides instances where coefficient of variation is known and one such example is given in Singh (1998) also.
Sometimes simple a priori information in the form of coefficient of variation is available to the experimenters in the fields of biology, agriculture, psychophysics etc. Long association of the experimenters with the experimental information concerning the coefficient of variation. This information concerning coefficient of variation. This information concerning coefficient of variation is frequently used to plan experiments, estimate sample size, average, total, etc. (See Searles (1964) also. Further coefficient of variation may be seen in Cochran (1977, 3rd edition) on page 77 and Page 79 of Chapter 4. A good description about knowledge of coefficient of variation is given in Sukhatme et al. (1984) also on page 42.

The objective of the paper is to propose modified estimators for estimating the population mean by using the improved linear regression using auxiliary information with the coefficient of regression and coefficient of skewness of the auxiliary variables.
Notations Used

The following are the notations used in the paper

- \( N \) Population size
- \( n \) Sample size
- \( f = n/N \) Sampling fraction
- \( Y \) Study variable
- \( X \) Auxiliary variable
- \( \bar{X}, \bar{Y} \) Population means
- \( \bar{x}, \bar{y} \) Sample means
- \( x, y \) Sample totals
- \( S_x, S_y \) Population standard deviations
- \( S_{xy} \) Population covariance between variables
- \( C_x, C_y \) Population coefficient of variation
- \( \rho \) Population correlation coefficient
- \( B(.) \) Bias of the estimator
- \( MSE(.) \) Mean square error of the estimator
- \( \tilde{Y}_e \) Existing modified ratio estimator of \( \bar{Y} \)
- \( \tilde{Y}_{ip} \) Proposed modified ratio estimator of \( \bar{Y} \)
- \( M_d \) Population median of \( X \)
- \( \beta_2 \) Population kurtosis
- \( \beta_1 \) Population skewness
- \( TM = \frac{Q_1 + 2Q_2 + Q_3}{4} \) Tri-Mean

\[ HL = median((X_j + X_k)/2, 1 \leq j \leq k \leq N) \] Hodges-Lehmann estimator

\[ MR = \frac{X_{(1)} + X_{(N)}}{2} \] Population mid-range

Subscript

\( i \) For existing estimators
\( j \) For proposed estimators

Procedure and Definitions

Let the Variable of interest be \( y \) and the auxiliary variable be \( x \) taking the values \( Y_i, X_i \), and \( X_k \) respectively for the \( i^{th} \) \((i = 1,2, \ldots, N)\) unit of the population of size \( N \).

Further, Let

\[ \bar{Y} = \frac{1}{N} \sum_{i=1}^{N} Y_i , \quad \bar{X} = \frac{1}{N} \sum_{i=1}^{N} X_i , \quad \mu_{rs} = \frac{1}{N} \sum_{i=1}^{N} (X_i - \bar{X})^r (Y_i - \bar{Y})^s \]

\[ C_Y = \frac{\sigma_Y}{\bar{Y}} , \quad C_X = \frac{\sigma_X}{\bar{X}} , \quad \beta_2 = \frac{\mu_4}{\mu_2^2} , \quad \gamma_1 = \frac{\mu_3}{\mu_2^{3/2}} \]
Also, let

\[\sigma_y^2 = \frac{1}{N} \sum_{i=1}^{N} (Y_i - \bar{Y})^2, \quad \sigma_y^2 = \frac{1}{N} \sum_{i=1}^{N} (X_i - \bar{X})^2\]

\[\sigma_{xy} = \frac{1}{N} \sum_{i=1}^{N} (X_i - \bar{X})(Y_i - \bar{Y})\]

\[\rho = \frac{\sigma_{xy}}{\sigma_x \sigma_y}, \quad B = \frac{\sigma_{xy}}{\sigma_x^2}\]

Where \(y_1, y_2, \ldots, y_n\) are the observation on \(y\) and \(x_1, x_2, \ldots, x_n\) are the observations on auxiliary variable \(x\) for a simple random sample of size \(n\).

For estimating the population mean using regression method of estimation, the proposed estimator is

\[\bar{y}_{trh} = [\bar{y} + b(\bar{X} - \bar{x})] + \omega \left( \frac{S_y^2}{C_y^2} - \bar{y}^2 \right)\]

Where \(\omega\) is the characterizing scalar chosen suitably.

**Comparison of Bias and Mean Square Error of \(\bar{y}_{trh}\) of the proposed estimator via-A-vis the competing estimator**

For simplicity, it is assumed that the population size \(N\) is large enough as compared to the sample size \(n\) so that finite population correction term may be ignored.

Let

\[\bar{y} = \bar{Y}(1 + e_0), \quad \bar{x} = \bar{X}(1 + e_1), S_y^2 = \sigma_y^2(1 + e_2)\]

\[S_y^2 = \sigma_y^2(1 + e_3), \quad S_{xy} = \sigma_{xy}(1 + e_4)\] so that

\[E(e_0) = E(e_1) = E(e_2) = E(e_3) = E(e_4) = 0\] and

\[E(e_0^2) = \frac{\sigma_y^2}{n}, \quad E(e_1^2) = \frac{C_y^2}{n}, \quad E(e_2^2) = \frac{C_x^2}{n}\]

\[E(e_0 e_1) = \frac{\sigma_{xy}}{n}, E(e_0 e_2) = \frac{\mu_{03}}{n\sigma_y^2}, E(e_1 e_3) = \frac{\mu_{12}}{n\sigma_x^2}\]

Also, we have

\[b = \frac{S_{xy}}{S_x^2} = \frac{\sigma_{xy}(1 + e_4)}{\sigma_x^2(1 + e_3)} = B(1 + e_4)(1 + e_3)^{-1}\]

\[= B(1 + e_4)(1 - e_3 + e_3^2 - \cdots)\]

\[= B(1 - e_3 + e_4 + e_3^2 - e_3 e_4 + \cdots)\]

\[\bar{y}_{trh} = [\bar{Y}(1 + e_0) + B(1 - e_3 + e_4 + e_3^2 - e_3 e_4 + \cdots)(\bar{X} - \bar{x}(1 + e_0))] +\]
Taking expectations on both sides, we have bias up to term of order $O(1/n)$ as follows,

$$\text{Bias } (\bar{Y}_{\text{tre}}) = E(\bar{Y}_{\text{tre}} - \bar{Y})$$

$$\bar{Y}E(e_0) - B\bar{X}E(e_1) - B\bar{X}E(e_1e_3) = \omega \bar{Y}[E(e_2^2) - E(e_0^2) - 3E(e_0e_2) - 2E(e_0)]$$

$$\rho = \frac{\sigma_y \mu_{11}}{n \sigma_x} + \frac{\sigma_y}{n} - \frac{\sigma_y}{n}$$

$$\text{MSE } (\bar{Y}_{\text{tre}}) = \left[\{\bar{Y}_e - B\bar{X}e_1\} + \omega \bar{Y}^2(e_2 - 2e_0)\right]^2$$

value of $\omega$ minimizing the mean square error of $\bar{Y}_{\text{tre}}$

And the minimum mean square error is given by:

$$\text{MSE} (\bar{Y}_{\text{tre}}) = (1 - \rho^2) \frac{\sigma_y^2}{n} - \frac{\left\{y_1C_y \times \frac{G}{Q^2} - 2C_y^2 \times \frac{G}{Q^2} - \rho \frac{\mu_{12}}{\sigma_x\sigma_y} + 2\rho \frac{C_y^2 \times \frac{G}{Q^2}}{\sigma_y}\right\}}{\bar{Y}(\beta_2 - 1) + 4C_y^2 \times \frac{G}{Q^2} - 4y_1C_y \times \frac{G}{Q^2}}$$

Estimator based on estimated optimum $\hat{C}$.

If the exact or good guess of $\beta_2, \gamma_2, \rho$ and $\mu_{12}$ are not available, we can replace these quantities by their consistent sample estimates

$$\hat{\beta}_2, \hat{\gamma}_2, \hat{\rho}, \hat{\mu}_{12}$$ respectively and $\bar{Y} = \bar{y}$ in (4.2.4) and get the estimated optimum value of $\omega$ denoted by $\hat{\omega}$ as

$$\hat{\omega} = -\frac{\left\{\hat{\gamma}_1C_y \times \frac{G}{Q^2} - 2C_y^2 \times \frac{G}{Q^2} - \hat{\rho} \frac{\hat{\mu}_{12}}{Y_{SxS_y}} + 2\hat{\rho}^2C_y^2 \times \frac{G}{Q^2}\right\}}{\bar{y}(\hat{\beta}_2 - 1) + 4C_y^2 \times \frac{G}{Q^2} - 4\bar{y}1C_y \times \frac{G}{Q^2}}$$

Where

$$\beta_2 = \frac{\hat{\mu}_{04}}{s^2_y} \text{ with } \hat{\mu}_{04} = \frac{1}{n} \sum_{i=1}^{n} (y_i - \bar{Y})^4,$$

$$\gamma_1 = \frac{\hat{\mu}_{03}}{s^3_y} \text{ with } \hat{\mu}_{03} = \frac{1}{n} \sum_{i=1}^{n} (y_i - \bar{Y})^3,$$
we get the estimator based on the estimated optimum $\hat{c}$ as:

$$\hat{\gamma}_{lre} = [\hat{\gamma} + b(\hat{X} - \bar{x})] + \hat{c} \left( \frac{C_y^2 \times G y^2}{S_y^2} \right)$$

Let,

$$\mu_{03} = \mu_{03}(1 + e_5), \quad \mu_{04} = \mu_{04}(1 + e_6), \quad \mu_{12} = \mu_{12}(1 + e_7)$$

Also, we have

$$\hat{c} = \frac{\left( \frac{\hat{\mu}_{03}(1 + e_5)}{\sigma_y^2(1 + e_2)^2} \sigma_y^2(1 + e_3)(1 + e_2)(1 + e_9) \right) - 2C_y^2 \times \frac{G y^2}{Q D} - \frac{\sigma_y^2(1 + e_3)(1 + e_2)(1 + e_9)}{\sigma_y^2(1 + e_2)(1 + e_9) \times G y^2}}{1 + 4C_y^2 \times \frac{G y^2}{Q D} - 4 \left( \frac{\mu_{03}(1 + e_5)}{\sigma_y^2(1 + e_9)} \right) \frac{G y^2}{Q D}}$$

An Illustration

We observe that the conditions discussed in the introduction for known coefficient of variation are satisfied for the data given in Walpoole, R. E., Myres, R. H., Myres, S. L., and Ye, K. (2005, page 473) dealing with measure of aerobic fitness is the oxygen consumption in volume per unit body weight per unit time. Thirty-one individuals were used in an experiment in order to be able to model oxygen consumption (y) against time to run one and half miles (x), consumption of required values has been done and we have the following.

For the population I and II we use the Data Sets data of Singh and Chaudhary (1986) page 177 and for the population III we use the data of Murthy (1967) page 228 in which fixed capital is denoted by X (auxiliary variable) and output of 80 factories are denoted by Y (study variable). For the population IV, the data is of cultivation and production of apple in district Baramulla of Kashmir (Jammu and Kashmir) in which the apple production (in tons) is denoted by Y (study variable) and number of apple trees are denoted by X (auxiliary variable, 1 unit = 100 trees) in 117 villages of the Baramulla region of Jammu and Kashmir in 2010-2011 (Source: RC Mproject, pilot survey for estimation of cultivation and production of apple in district Baramulla, RC Mapproved project).

Table 1: Characteristics of these populations

| Parameters | Population 3 | Population 4 |
|------------|-------------|-------------|
| N          | 80          | 117         |
| n          | 20          | 15          |
| $\bar{y}$  | 5182.637    | 2179        |
| $\bar{x}$  | 1126.463    | 560.0       |
| $\rho$     | 0.941       | 0.991703    |
For the purpose of empirical investigation, we have considered the following three sets of data which are taken from various sources followed by Singh and Chaudhary (1986).

**DATA 1:** [Source: Kadilar and Cingi]

The data is consisted of 80 villages in the Murthy (1967). The variables of interest are as:

- $Y$: The level of apple production (in 100 tones)
- $X$: The number of apple trees.

For this data, we have

$$N = 104, n = 20, \theta = 0.04038, \bar{Y} = 6.254, \bar{X} = 13931.683,$$

$$s_y = 11.67, s_x = 23029.072, \beta_2(y) = 16.523, \beta_2(x) = 17.516, \delta_{22} = 14.398, \lambda^k = 0.8112.$$
Y: The number of persons per block
and
X: The number of rooms per block.

For this data, we have

\[ N = 100, n = 10, \theta = 0.09, \bar{Y} = 101.1, \bar{X} = 58.8, S_Y = 14.6595, S_X = 7.53228, \beta_2(y) = 2.3523, \beta_2(x) = 2.2387, \delta_{22} = 1.5432, \lambda^2 = 0.4385. \]

We provide the Percentage Gain in Efficiency of the proposed estimator with respect to its competitors in the following Table 1.

**Table 1: Percentage Gain in Efficiency of the proposed estimator \( s_R^{2(k)} \) with respect to \( s_R^{2} \) and \( s_Y^{2} \).**

| Data  | Percentage gain in efficiency of \( s_R^{2(k)} \) with respect to \( s_Y^{2} \) | Percentage gain in efficiency of \( s_R^{2(k)} \) with respect to \( s_R^{2} \) |
|-------|---------------------------------------------------------------------------------|---------------------------------------------------------------------------------|
| Data 1| 260.8                                                                           | 19.6                                                                           |
| Data 2| 286.78                                                                          | 79.8                                                                           |
| Data 3| 34.67                                                                           | 67.8                                                                           |

The above table well indicates the supremacy of the proposed estimators \( s_R^{2(k)} \) over \( s_R^{2} \) and \( s_Y^{2} \).

**CONCLUSION**

**Concluding Remarks**

a) for the optimum value of \( \omega \), the estimator \( \bar{y}_{lre} \) attains the minimum mean square error given by

\[
\text{MSE (} \bar{y}_{lre} \text{)} = \frac{\sigma_y^2}{n} \left( 1 - \rho^2 \right) \frac{\bar{X}^2 \left[ \frac{\sigma_Y^2}{\sigma_X^2} \frac{\sigma_X}{\sigma_Y} \right]^2}{n(\beta_2 - 1) - 4\beta_2 \left[ \frac{\sigma_Y^2}{\sigma_X^2} - \frac{\sigma_X}{\sigma_Y} \right]}\]

(4.4.2)

b) for the optimum value of \( \omega \) depending upon estimated optimum \( \hat{c} \), has the mean square error.

\[
\text{MSE (} \bar{y}_{lre} \text{)} = \frac{\sigma_y^2}{n} \left( 1 - \rho^2 \right) \frac{\bar{X}^2 \left[ \frac{\sigma_Y^2}{\sigma_X^2} \frac{\sigma_X}{\sigma_Y} \right]^2}{n(\beta_2 - 1) - 4\beta_2 \left[ \frac{\sigma_Y^2}{\sigma_X^2} - \frac{\sigma_X}{\sigma_Y} \right]}\]

From (4.4.3), we see that the estimator \( \bar{y}_{lre} \) depending on estimated optimum value is always more efficient than the usual linear regression estimator \( \bar{y}_{lre} = \bar{y} - b(\bar{X} - \bar{x}) \) in the sense having lesser mean square error.

The use of proposed estimator is limited for the situations when coefficient of variation is known. However, in case of unknown coefficient of variations its estimated value may be used after studying the performance of the estimator (robustness) against different values of CV, if the guess is in error say 5%, 10%, 15%, 20%, 25%, 50%. Further work is being done in this direction.

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