Response to Reviewer 1:

Dear Referee,

Thank you for your detailed comments on our manuscript “Hydro-mechanical processes and their influence on the stimulation effected volume: Observations form a decimeter-scale hydraulic stimulation project”. Following your request, we reorganized the manuscript in a way that the impact is better visible. Therefore, we removed the “Q-strategy” in the introduction and the discussion. We drastically shortened the introduction, cleaned up the discussion and removed all statements that are somehow doubled in the manuscript. In addition, we separated even more strictly between pure observations and interpretation. We argue that the manuscript strongly benefits from this re-structuring. As most of the statements have been moved to different locations or even been rewritten in a clearer way, we cannot answer in a detailed way on each of your comments. We are sorry for these inconveniences. However, here is a short response on your main comments.

1) Terminology:
   
   We tried to make it clearer and avoid geological subunits, whenever possible. As the rock mass is rather complex and we want to take advantage of the comprehensive monitoring in such an environment, we think it is useful to simplify the geological description further as it is now in the revised version.

2) The Q strategy:
   
   As already mentioned above, we changed this and think that the impact and main research question are more obvious now.

3) presentation:
   
   We shortened the manuscript by at least six pages. The manuscript is now much better to the point.

4) technical:
   
   We added a critical section about the effect of monitoring quality depending on the injection location in the conclusion. We argue that the uncertainties of the measured values are given by the grouped presentations of the different experiments and the shown or written detection limit of the sensors.

5) Scientific conclusiveness:
   
   We made clearer statements in terms about the use of stress tensors and the influence of target geology on the stimulation outcome. For more peripherical information, such as seismic velocity model etc., we like to draw your attention to the corresponding cited papers. Adding this information would again extent the paper and add another level of complexity.

Response to Reviewer 2

Dear Referee,
thank you for your comments on the manuscript: “Hydro-mechanical processes and their influence on the stimulation-effected volume: Observations from a decameter-scale hydraulic stimulation project”. Due to the requests from you and reviewer 1, we had to drastically reorganise the manuscript. Thus, the introduction was shortened, the results section cleaned and the interpretation part reduced to the essential observations.

Here are summarized responses to your comments.

Figure 1: The 3D geometry is difficult to show in a figure. For more detailed information we referred to Doetsch et al. 2018.

Figure 2: We provided the reference for the original geological images and thus prefer to leave the figure as it is.

Figure 3: Yes, the figure is rather busy, but we improved now the figure caption, to make it clearer.

Figure 9: We improved the caption for better clarity.

Figure 12: We improved the caption for better clarity.

In general, we polished the text and focussed on the most important observations. Thus, we argue the also the description of the figures in the text improved and the overall readability of the manuscript improved.
Hydro-mechanical processes and their influence on the stimulation affected volume: Observations from a decameter-scale hydraulic stimulation project

Hannes Krietsch¹⁴, Valentin S. Gischig¹², Joseph Doetsch¹, Keith F. Evans¹, Linus Villiger³, Mohammadreza Jalali⁴, Benoît Valley⁵, Simon Löw¹, Florian Amann⁴

¹Department of Earth Sciences, ETH Zurich, Zurich, 8092, Switzerland
²CSD Ingenieure, Bern, 3097, Switzerland
³Swiss Seismological Service, ETH Zurich, Zurich, 8092, Switzerland
⁴Department of Engineering Geology & Hydrogeology, RWTH Aachen, Aachen, 52062, Germany
⁵CHYN, University of Neuchâtel, Neuchâtel, 2000, Switzerland

Correspondence to: Hannes Krietsch (hannes.krietsch@erdw.ethz.ch)

Abstract

Six hydraulic shearing experiments have been conducted in the framework of the In-situ Stimulation and Circulation experiment within a decameter-scale crystalline rock volume at the Grimsel Test Site, Switzerland. During each experiment fractures associated with one out of two different shear zone types were hydraulically reactivated. The two shear zone types differ in terms of tectonic genesis and architecture. An extensive monitoring system of sensors recording seismicity, pressure and strain was spatially distributed in eleven boreholes around the injection locations. As a result of the stimulation, the near-wellbore transmissivity increased up to three orders in magnitude. With one exception, jacking pressures were unchanged by the stimulations, while jacking pressures of the stimulated structures reduced during most of the experiments. Transmissivity change, jacking pressure and seismic activity were different for the two shear zone types, suggesting that the shear zone characteristics govern the seismo-hydro-mechanical response. The elevated fracture-fluid-pressures associated with the stimulations propagated mostly along the stimulated shear zones. The absence of high-pressure signals away from the injection point for most experiments (except two out of six experiments) is interpreted as channelized flow within the shear zones. The observed deformation field within 15 m – 20 m from the injection point is characterized by variable extensional and compressive strain, produced by fracture normal opening and/or slip dislocation, as well as stress redistribution related to these processes. At greater distance from the injection location, strain measurements indicate a volumetric compressive zone, in which the strain magnitude decreases with increasing distance. This compressive strain signals are interpreted as a poro-elastic far-field response to the emplacement of fluid volume around the injection interval. The exceptional hydro-mechanical data reveal that the overall stimulation affected volume is significantly larger than implied by the seismicity cloud, and can be subdivided into a primary stimulated and secondary affected zone.

1 Introduction

The need for CO₂-neutral and nuclear-free energy production has led to global interest in the extraction of deep geothermal energy in Europe. Presently, It has been stated, that only a small portion of the worldwide geothermal resources are exploited (Tester et al., 2006). Unfortunately, at the depths where temperatures are high enough for industrial scale electricity production (>150 °C), the natural transmissivities of interconnected fractures are too small in many regions of the world, to establish sufficient fluid circulation for effective heat extraction (Manning and Ingebritsen, 1999). In many regions of the world, Thus, in these regions, the geothermal reservoirs need to be engineered by high-pressure hydraulic stimulation treatments that aim to sufficiently increase the reservoirs transmissivity (Brown et al., 2012).
These engineered heat exchangers, which are mostly located within the crystalline crust, are and are referred to as engineered/enhanced geothermal systems (EGS) or petrothermal systems. Hydraulic stimulations include two possible endmember mechanisms: hydraulic shearing (HS), which i.e denotes the hydraulic reactivation of pre-existing fractures with by irreversible shear dilation, and hydraulic fracturing (HF), i.e. the initiation and propagation of new tensile fractures during which new tensile fractures are initiated and propagated. Both mechanisms can occur concomitantly under certain conditions that depend upon the in-situ stress field, injection pressure and/or flow rate, initial fracture transmissivity, and fracture network connectivity (McClure and Horne, 2014; Rutledge et al., 2004). HS and HF stimulations involve high-pressure fluid injections into open-hole borehole intervals or through casing perforations, the latter being the norm in the oil and gas industry.

Numerous examples of hydraulic stimulation injections in crystalline rocks have shown that they generally give rise to induced seismicity (Evans et al., 2005a; Häring et al., 2008; Parker, 1999; Pearson, 1981; Sasaki, 1998), which Evans et al., 2005a; Häring et al., 2008; Parker, 1999; Pearson, 1981; Sasaki, 1998). If the fault slip induced during HS is rapid enough, seismic energy is radiated. Such induced earthquakes can be strongly enough exceed magnitudes to be that which are recognized felt at the surface (Davies et al., 2013; Zoback and Harjes, 1997). Thus, one of the main challenges for EGS is a) keeping the seismic hazard at an acceptable level while b) strongly increasing the reservoirs transmissivity and connectivity. A deeper understanding of the seismo-hydro-mechanical (SHM) responses of rock masses and its fractures to elevated fluid pressure is needed to meet these challenges. Thermelastic stress perturbations induced by the high temperature differences between rock mass and injection fluid are also important (Tomec and Sauter, 2005a; Häring et al., 2008; Parker, 1999; Pearson, 1981; Sasaki, 1998). Pearson, 1981; Sasaki, 1998). However, keeping the seismic hazard at an acceptable level while strongly increasing the reservoirs transmissivity and connectivity. A deeper understanding of the seismo-hydro-mechanical (SHM) responses of rock masses and its fractures to elevated fluid pressure is needed to meet these challenges. Thermelastic stress perturbations induced by the high temperature differences between rock mass and injection fluid are also important (Tomec and Sauter, 2005a; Häring et al., 2008; Parker, 1999; Pearson, 1981; Sasaki, 1998).

Quantitative seismological, hydraulic and/or mechanical observations pertaining to reservoir stimulation have been made largely in a number the context of laboratory experiments (Bandis et al., 1983; Olsson and Barton, 2001; Vogler et al., 2018), bandis et al., 1983; olsson and Barton, 2001; vogler et al., 2018), and in full-scale field projects on the kilometer-scale (i.e. reservoir-scale) (Evans, 2005; Evans et al., 2005b; Häring et al., 2008). Experiments on the intermediate scale of tens to hundreds of meters are relatively few in number, but are key to bridging the gap in process understanding between these extremes laboratory- and reservoir-scale. Experiments on this intermediate scale increase complexity of the test volume with respect to are less controlled compared to laboratory-sized experiments, but still allow detailed monitoring of seismicity, and the pore-pressure and deformation response at a high spatial resolution. Several intermediate-scale field projects have been performed to investigate the application of hydraulic stimulation techniques to establish hydraulic linkage between boreholes separated by tens to a hundred meters and at depths of several hundred meters. However, in multiple examples, the projects at this scale (e.g. Cornet & Morin, 1997; MacDonald et al., 1992; Niitsuma, 1989; Rummel & Kappelmayer, 1983; Wallroth et al., 1999). Le Mayet in France (Cornet and Morin, 1997), Falkenberg in Germany (Rummel and Kappelmeyer, 1983), Fjällbacka in Sweden (Wallroth et al., 1999), the Gamma project in Japan (Niitsuma et al., 1989), and Phase 1 of the Rosemonowes project in the UK (MacDonald et al., 1992). In all these projects, the reservoirs were accessed from boreholes drilled from the surface, giving little possibility of installing dense instrumentation in the near-field. Experiments performed at similar 10-100 m scale within underground rock laboratories, where holes are drilled from galleries, can overcome this limitation.

Since far, direct observations of fracture fluid pressure during the stimulation of full- and intermediate-scale reservoirs are rare owing to the practical difficulties of sensor emplacement. Thus, information about pressure propagation and induced deformations usually stems from micro-seismic recordings (e.g. Duboeuf et al., 2017; Evans, Moriya, et al., 2005; Rutledge et al., 2004). Duboeuf et al., 2017; Evans, Moriya, et al., 2005; Rutledge et al., 2004) and active seismic velocity tomography (Doetsch et al., 2018b; Rivet et al., 2016). In addition, seismicity clouds are often used to infer size, shape and growth of the rock mass volume affected by the stimulation treatments (Cipolla and Wallace, 2014; Mayerhofer et al., 2010; Shapiro et al., 1997). However, Duboeuf et al., 2017 argued that induced
seismicity is not necessarily directly associated with fluid pressure diffusion, but rather with induced stress perturbations. Thus, the seismic cloud may not necessarily illuminate the zones of highest fracture fluid pressures.

Another issue associated with reservoir stimulations concerns the estimation of the volume affected by the stimulation. Seismicity clouds are often used to infer size, shape and growth of the stimulated rock mass (Cipolla and Wallace, 2014; Mayerhofer et al., 2010; Shapiro et al., 1997). However, there is evidence from some field sites that a significant fraction of the induced slip and deformation was aseismic (Cornet et al., 1998; Dubouef et al., 2017; Evans et al., 2005a; Guglielmi et al., 2015; Villiger et al., 2020). Thus, there is some doubt as to the degree to which induced seismicity and the seismic cloud illuminate the hydro-mechanical rock mass response to and represent the volume affected by stimulation treatments, respectively.

The patterns of micro-seismicity induced during reservoir-scale stimulation experiments in crystalline rock suggest that fracture zones and faults serve as the primary pathways for fluid penetration of enhanced fluid pressure in the reservoir, and that diffusion occurs mainly in an interconnected fracture features or fracture planes network in the reservoir features or planes within the reservoir discontinuities (Evans et al., 2005a; Fehler et al., 1987). Thus, the flow field seems to be likely complex and does not conform with idealized radial or dipole geometries (Evans et al., 2005a).

During the majority of intermediate- to full-scale stimulations, the only direct observations on the rock mass the reservoir response to fluid injections have been made at the can only be inferred from pressure and flow data acquired along the injection well. It has been demonstrated that injection well injectivity can be irreversibly enhanced by several orders of magnitude during stimulation, due primarily to induced irreversible dislocation of fractures (Bao and Eaton, 2016; Davies et al., 2013; Evans et al., 2005b; Kaieda et al., 2000; Zoback and Harjes, 1997). Flow profile measurements logging in injection wells conducted during various stimulation projects in crystalline rock show that the majority of the injected fluid volume injected during stimulation entered the formation/reservoir through a small number of natural fractures, whose transmissivities were permanently increased by the injections (e.g. Brown et al., 2012; Cornet & Morin, 1997; K. F. Evans, Genter, et al., 2005; K. Evans & Sikaneta, 2013; Parker, 1999). (McClure & Horne, 2014) note that injection pressure limiting behavior, which is a common feature of hydraulic fracturing treatments, is also observed for stimulations that are believed to involve hydraulic shearing. This pressure within fractures required for full hydraulic jacking provides a measure of the normal stress component acting on the fractures, and, as such, it is a quantity of importance.

Nevertheless, although important insight in the stimulation induced reservoir response have been inferred from induced seismic data and observations in injection wells, in-situ measurements of direct observations of the pressure field evolution and HM-coupled mechanical responses away from the injection well are still missing.

We here present here the direct hydraulic and mechanical observations that were made during six isothermal hydraulic shearing experiments, conducted in February 2016 at the Grimsel Test Site (GTS), Switzerland. The experiments were part of the In-Situ Stimulation and Circulation (ISC) project (Amann et al., 2018). A comprehensive monitoring system - consisting of pressure intervals and longitudinal strain sensors - was distributed along 12 boreholes throughout the decameter-scale test volume. This monitoring system provided great insight into the detailed information on the complex flow field and rock mass response during stimulation, as well as important constraints on the shape and size of the volume affected by the stimulations. We followed the same standardized injection protocol for all six HS experiments to highlight the influence of the target geological structures (i.e., shear zone) on the variability of HM-coupled rock mass responses. We also compared our hydro-mechanical observations with the observed induced seismicity (Villiger et al., 2014; 2019) and results from active seismic surveys (Doetsch et al., 2018b; Schopper et al., 2020) that took place during ongoing stimulation in the test volume conducted during the stimulations.
seismicity occurring in the vicinity of the injection. Amann et al. (2018) identified relevant SHM processes that can be explored in such decameter-scale experiments: a) hydro-mechanical-coupled fluid flow and pressure propagation, b) transient pressure- and permanent slip-dependent permeability changes, c) fracture formation and its interplay with the pre-existing fracture network, d) rock mass deformation around the stimulated fractures due to fault slip and poro-elasticity, e) the transition from aseismic to seismic slip, and f) the spatial and temporal evolution of induced seismicity. To increase the understanding of these processes at the decameter scale, the In-situ Stimulation and Circulation (ISC) project was carried out at the Grimsel Test Site, Switzerland (Amann et al., 2018). A total of six hydraulic shearing and six hydraulic fracturing experiments were conducted within the framework of this project.

In this paper, we focus on the hydro-mechanical-coupled (HM) observations made during the six hydraulic shearing (HS) experiments conducted in February 2016. An overview of the six hydraulic fracturing (HF) experiments that were conducted within the same rock mass in May 2016 is given in Butler et al. (2019). HF experiments conducted on a smaller scale as part of the stress characterization program are presented by (Gischig et al., 2018; Jalali et al., 2018a; Krietsch et al., 2018c). The analysis of observed induced seismicity is presented by Villiger et al. (2019). An extensive description of the overall project, stimulation experiments, characterization steps, and monitoring setup are presented by Doetsch et al. (2017). Here we seek answer to the following questions:

Q1: How does the transmissivity, induced-slip dislocation and injection pressure evolve at the injection interval, and how variable are these outcomes between the experiments?
Q2: How does the transient hydraulic pressure field develop during the stimulation?
Q3: How is the transient and permanent deformation field throughout the volume characterized, and how do adjacent fractures interact in connection with the in-situ stress field?
Q4: What is the extent of the pressurized and stimulation effected volume in relation to the seismicity cloud?

Below, we provide a brief literature review related to the research questions.

**Thermoelastcity stress perturbations induced by the high temperature differences between rock mass and injection fluid are also important (Tomac and Sauter, 2018), but are not considered in our study which is essentially isothermal.**

### 1.1 Hydro-mechanical processes near the injection well

Field tests have demonstrated that borehole injectivity can be irreversibly enhanced by several orders of magnitudes during stimulation, due primarily to induced irreversible dislocation of fractures (Bao and Eaton, 2016; Davies et al., 2013; Evans et al., 2005b; Kaleda et al., 2000; Zoback and Harjes, 1997). Flow profile measurements (e.g., spinner and temperature logs) conducted during various stimulation projects in crystalline rock show that the majority of the fluid volume injected during stimulation entered the formation through a small number of natural fractures whose transmissivities were permanently increased by the injections (e.g., Fenton Hill (Brown et al., 2012), Le Mayet-de- Montagne (Cornet and Morin, 1997), Rosemanoves Phase-2 (Parker, 1999); Soultz-sous-forêt (Evans et al., 2005b), Basel (Evans and Sikaneta, 2013). This observation, together with the patterns of microseismicity induced during the injections, suggests that hydraulic activation of pre-existing fractures in shear is the dominant mechanism during the hydraulic stimulation of fractured borehole intervals, at least away from the well (Cornet and Jones, 1994). Hydraulic fractures have been observed at the injection well following stimulation injections at some sites (e.g. Rosemanoves, Fenton Hill (Breede et al., 2013)), although there is some doubt whether they can be driven to propagate far from the injection well (McClure and Horne, 2014). Such fractures would be expected to intersect natural fractures during propagation, which might be reactivated in shear, leading to increasing leak-off from the hydraulic fracture that will ultimately prevent further extension. Nevertheless, McClure and Horne (2014) note that pressure-limiting behavior, which is a common feature of hydraulic fracturing treatments, is also observed for stimulations that are believed to involve hydraulic shearing. Pressure-limiting behavior is best explained by the lift-off or hydraulic jacking of fracture surfaces when the fluid pressure reaches the level of the normal stress acting across fractures carrying the flow. Fractures that support shear stress under ambient conditions will release that stress through slip as effective normal
stress decreases, the release being total when lift-off conditions are attained. Thus pressure-limiting behavior is consistent with permeability enhancement through hydraulic shearing.

The pressure within fractures required for full hydraulic jacking or lift-off provides a measure of the normal stress component acting on the fractures, and, as such, it is a quantity of importance. Hydraulic jacking pressure can be estimated from flow pressure (Q-P) cross-plots of data from step-rate or step-pressure tests, which also provide estimates of injectivity. Such tests were performed before and after each of the hydraulic shear stimulations at the ISC site to characterize the local changes in media characteristics. Since the interpretation and uncertainties of these tests are important to this paper, we describe them in some detail in section 3.

1.2 Pressure propagation

The hydro-mechanical (HM) properties of faults depend on their geological predisposition (Caine et al., 1996; Faulkner and Rutter, 2001; Guglielmi et al., 2008). Permeability and compliance may vary by several orders of magnitude along and across a fault zone (Achtziger-Zupančič et al., 2016; Faulkner et al., 2010). The patterns of microseismicity induced during reservoir-scale stimulation experiments in crystalline rock suggest that fracture zones and faults serve as the primary pathways for the penetration of enhanced fluid pressure in the reservoir, and that diffusion occurs along tube-shaped features or planes within the reservoir (Evans et al., 2005a; Fehler et al., 1987). Thus, the flow-field is complex and does not conform with idealized radial or dipole geometries (Evans et al., 2005a).

An increase in fluid pressure within a fracture may lead to an increase in the mechanical aperture in two different ways: a) a reversible elastic opening governed by the compliance characteristics of the fracture (Zange et al., 2008; Evans and Meier, 1995; Rutqvist, 1995), or b) an irreversible opening arising from shear failure and associated dilation (Lee and Cho, 2002; Rahman et al., 2002). An increased aperture will generally result in a higher fracture transmissivity, although the process is strongly non-linear and dependent upon multiple factors such as mean aperture, contact area and the presence of damage particles (Tsang, 1984; Zimmerman and Main, 2004). Importantly, the transmissivity increase will also affect the propagation of pressure along the fracture inasmuch as the diffusion process becomes non-linear, resulting in a steepening of the pressure front (Murphy et al., 2004; Hummel and Müller, 2009). With increasing fracture dilation and non-linearity of diffusion, the propagating pressure front becomes steeper, in principle ultimately becoming a shock front when the two fracture surfaces are separate and the fracture become infinitely compliant (Murphy and Dach, 1985). Thus, at a given distance to an injection point, pressures build up more rapidly once the pressure front arrives than would be the case for linear diffusion.

Segall (1989) and Segall and Fitzgerald (1998) described stress changes within and outside of hydrocarbon and geothermal reservoirs that have suffered a decline in fluid pressure through production. The reservoir is considered to be the volume of rock that has suffered pore pressure depletion through diffusion. They show that within the reservoir, the stress changes are the sum of a poro-elastic body force induced by the direct pore pressure change (given by \( \alpha \cdot \Delta P \) where \( \alpha \) is Biot’s coefficient) and the elastic deformation it produces (itself dependent upon boundary conditions), whereas outside of the reservoir, the stress change is due only to the deformation. Following this, in this paper we use the terms “primary-stimulated zone” to mean the volume in which fluid-pressure changes reflect direct diffusion via a hydraulic connection to the injection location, and “secondary-effected zone” to mean the volume where fluid-pressure changes are due only to deformation (i.e. induced stress transfer), without a change in fluid content.

1.3 Mechanical rock mass response

If a rock mass at large depth is critically stressed (e.g., Townend and Zoback, 2000), then small increases in fracture fluid pressures can induce hydraulic shearing along optimally orientated fractures. In such situations, shear failure can be triggered at large distances from the injection point by relatively small pore pressure increases (Evans et al., 1999; Husen et al., 2007; Saar and Manga, 2003).

Stress transfer and deformation related to fracture slip is often referred to as Coulomb failure stress changes in the literature (Stein, 1999). Slip along a fracture plane leads to formation of compressional and dilatational lobes adjacent to the nodal plane (Fowler, 1990; Zoback, 2010). These slip-induced stress changes are often considered to be a trigger for reactivation of pre-existing fractures outside the pressurized structures, or as a cause of compression of fractures and the host rock (Jung, 2013). Furthermore, induced tensile stresses may induce failure (Hill, 2008), and can lead to the formation of splay (also called wing) cracks. These form usually at an angle of approximately 70° to the plane of
the shear fracture (Lehner and Kachanov, 1996). Preisig et al. (2015) have demonstrated that stress interaction between neighboring fractures, due to slip or fracture opening, may affect the pressure propagation and deformation field around the stimulation volume and the stimulation of adjacent fractures zones.

1.4 Extent of the stimulation-effected volume

Since direct observations of fracture fluid pressure during the stimulation of full- and intermediate-scale reservoirs are rare owing to the practical difficulties of sensor emplacement, information about pressure propagation usually stems from microseismic recordings (e.g., Dubouef et al., 2017; Evans et al., 2005a; Rutledge et al., 2004) and active seismic velocity tomography (Doetsch et al., 2018; Rivet et al., 2016). However, Dubouef et al. (2017) argued that induced seismicity is not necessarily directly associated with fluid pressure diffusion, but rather with induced stress perturbations. Thus, the seismic cloud may not necessarily illuminate the zones of highest fracture fluid pressures.

Another issue associated with reservoir stimulations concerns the estimation of the volume affected by the stimulation. Seismicity clouds are often used to infer size, shape, and growth of the stimulated rock mass (Cipolla and Wallace, 2014; Mayerhofer et al., 2010; Shapiro et al., 1997). However, there is evidence from some field sites that a significant fraction of the induced slip and deformation was aseismic (Cornet et al., 1998; Dubouef et al., 2017; Evans et al., 2005a; Guglielmi et al., 2015). Thus, there is some doubt as to the degree to which the seismic cloud represents the rock mass volume that was affected by the hydraulic stimulation treatment.

2 Test volumesite characteristics

The test volume The ISC project was conducted at the Grimsel Test Site (GTS), Switzerland. This underground research facility has an overburden of ~480 m and is located at the southern end of the Grimsel Test Site (GTS). This underground research facility operated by Nagra (Swiss National Cooperative for the Disposal of Radioactive Waste). The ISC test volume is at the southern end of the laboratory and can be accessed from three tunnels. A total of 15 boreholes were drilled into the test volume for stress measurements (referred to as SBH-boreholes), rock mass characterization, high pressure fluid injection (INJ-boreholes), and monitoring of pressure (PRP-boreholes), strain (FBS-boreholes) and seismicity (GEO-boreholes) (Figure 1).
Figure 1. Location of the GTS in Switzerland indicated in the geological map (a), and location of the test volume within the GTS (b). (c) shows the location of the injection intervals together with the target shear zones. d) illustrates locations of the strain sensors and tilt meters, with indicated tilt axes, and labels the target shear zones. The pressure monitoring intervals are shown in e) and the station locations of the seismic monitoring network is indicated in f). More details on the monitoring setup can be found in Doetsch et al. 2018a.

2.1 Geology and in-situ state of stress

The GTS is located in crystalline rocks and has an overburden of ~480 m at the geological boundary between the Grimsel Granodiorite and Central Aar Granite (Keusen et al., 1989). The Early Permian rocks of these lithologies (Grimsel Granodiorite and Central Aar Granite) intruded the crystalline crust 299±2 Ma ago (Keusen et al., 1989; Schaltegger and Corfu, 1992). Both lithologies have a similar quartz content of between 15–30 % (Wenning et al., 2018) and are close to the mineralogical transition between granodioritic and granitic rocks (Wenning et al., 2018). At the end of the Alpine deformation, the rock mass was exhumed after it underwent compressional and transpressional deformations at upper greenschist conditions (~450°C and 600 MPa) (Challandes et al., 2008; Goncalves et al., 2012; Wehrens et al., 2016). In preparation for the stimulation experiments, the geology of the test volume was characterized by performing tunnel mapping and core- and borehole logging (Krietsch et al., 2018b). The rock mass in the test volume contains a pervasive foliation with an average orientation of 140/80 (i.e., dip-direction/dip) which dips on average towards 140° at an angle of 80° (Krietsch et al., 2018b). In addition, the rock mass is intersected by two sets of shear zones (see Figure 1c-f) that differ in their genetic history and present-day architecture. The older set, referred to as S1, contains four subparallel–ductile shear zones (Figure 2a) which includes few poorly hydraulically connected fractures (Brixel et al., 2020b) with an average orientation of 142/77 (i.e., dip-direction/dip) (Figure 2c). The shear zones contain few discrete fractures (i.e., brittle discontinuities) inside which formed during low temperature retrograde deformations of the shear zones (Wehrens et al., 2016). Note that the minor S1 shear zone HS8 in Figure 2 was not included in the geological model presented by Krietsch et al.
(2018b) as it was only recently localized from borehole intersection data and seismicity detected during HS8 (Villiger et al., 2019). The younger set, referred to as S3, includes subparallel brittle-ductile shear zones with an average orientation of 183/65 (Figure 2a). Within the test volume, these two present S3 shear zones coincide with two a meta-basic dyke each which accommodated most of the brittle-ductile post-deformation. A total of four S1 shear zones and two S3 shear zones have been mapped inside the test volume (Krietsch et al., 2018b). Note that the orientations of both shear zone types vary slightly throughout the volume. This is evident in the range of orientations observed at the boreholes that intersect them whose poles are plotted in Figure 2c. Geophysical imaging (Doetsch et al., 2018). OPTV images suggests that The rock mass between the two S3 shear zones is intensely fractured at the eastern end of the test volume (>20 fractures/borehole meter). The location at extent of this highly fractured zone was constrained by geophysical imaging. This has been confirmed by Geophysical imaging (Doetsch et al., 2018). Thus, this zone differs from the relatively undisturbed rock mass surrounding these shear zones which has 1-3 fractures per meter (Krietsch et al., 2018b). During the deformation history of the rock mass, the S1 shear zones were sheared in a right lateral manner by the S3 shear zones. Therefore, the S1 shear zones and the fractures included therein can have a local orientation that is sub-parallel to S3.

Figure 2. Photographs and interpretations of the S1 (a) and S3 (b) shear zones as seen at the tunnel wall (Krietsch et al., 2018b). c) A lower hemisphere stereo net showing the poles of all mapped fractures and shear zones. The orientations of the principal stress components from the unperturbed and perturbed tensor are also shown.

In addition to the geological characterization, the in-situ stress field was characterized prior to stimulation within the test volume by Krietsch et al. (2018c). An extensive stress characterization survey was carried out in preparation for the ISC stimulation experiments (Krietsch et al., 2018c). The campaign combined stress relief methods (i.e., overcoring using USBM-probes and CSIRO HI-cells), hydraulic fracturing, and concomitant seismic monitoring (Gischig et al., 2018; Jalali et al., 2018a). A transverse isotropic elastic rock mass model was required for the inversion of the overcoring data due to the pervasive foliation of the rock mass. A progressive stress field perturbation to an otherwise relatively uniform ‘far-field’ stress
state was observed, that begins 11 m from the S2 shear zones, as they are approached from south (Krietsch et al., 2018c). The estimated unperturbed “far-field” principal stress magnitudes (measured 40 m away from the target shear zones) were 13.1 MPa (σ1), 9.2 MPa (σ2) and 8.7 MPa (σ3). As the shear zone is approached, σ3 declines to as low as 2.9 MPa immediately before the zone. A CSIRO Hi-cell test conducted at a distance of ~5 m from the shear zone yielded the principal stress magnitudes dropped to reduced of 13.1 MPa (σ1), 8.2 MPa (σ2) and 6.5 MPa (σ3). In addition, the principal axis orientations that differed from those of the unperturbed tensor, as shown in Figure 2c (Note that this solution is referred to as the perturbed tensor, although the hydraulic fracture and hydraulic jacking tests show that stress was even more strongly perturbed as the shear zone was approached). The origin of the perturbation is unclear, although it may be related to the mechanical property changes associated with the highly fractured zone between the S3 shear zones at the eastern end of the test volume. For more information on the conducted stress measurements see...

As the shear zone is approached, σ3 declines to as low as 2.9 MPa immediately before the zone. Although the perturbed stress tensors have been measured closer to the target stimulation volume (~about XX m) and shear zones, also the unperturbed stress tensor measured about XX m from the stimulation volume is considered in our analyses; through the conceivable substantial stress heterogeneities, it remains unclear whether the perturbed or unperturbed stress tensor explains our observations better.

The unperturbed stress tensor would imply that the shear stresses acting on the S1 shear zones tend to be higher than those acting on the S3 shear zones, whereas they are similar for the perturbed stress tensor (Figure 3). We assume that the perturbed stress tensor is a better representative as it is more representative for locations near the stimulation injection well, whereas the unperturbed stress tensor should be more reliable for the far-field areas of the test volume. Given the necessarily limited spatial coverage of the stress measurements, it is not clear whether the stress perturbation is localized to the shear zone region near the SBH4 borehole, or is representative of the entire shear zone and thus also found at the intersection of the shear zones with the stimulation injection boreholes.

![Stress States](image)

**Figure 3.** Stress states associated with the perturbed and unperturbed tensors for S1 and S3 shear zones. The implied average shear and normal stresses acting on the S1 and S3 shear zones (estimated over all mapped borehole intersections of these shear zones) are indicated in black. Also shown are the shear and normal stress acting on the principal fractures imaged in the S1 and S3 intersections with INJ-boreholes stimulation intervals. Additionally, a range of injection pressures is indicated as black lined failure criterion with different friction coefficients.
Monitoring and Methods

The ISC test volume is at the southern end of the laboratory and can be accessed from three tunnels. A total of 152 boreholes were drilled into the test volume for stress measurements (referred to as SBH-boreholes), rock mass characterization, high pressure fluid injection (referred to as INJ-boreholes), and monitoring of pressure (PRP-boreholes), strain (FBS-boreholes) and seismicity (GEO-boreholes) (Figure 1).

The six stimulation experiments targeted the four S1 shear zones and two S3 shear zones along the INJ-boreholes (Table 1 and Figure 1c). Note that during the deformation history of the rock mass, the S1 shear zones were sheared in a right lateral manner by the S3 shear zones. Therefore, some of the S1 shear zone fractures that were injected have an S3 orientation. Hence, some of the S1 shear zone fractures that were injected have an S3 orientation.

The injection intervals for the stimulation experiments were defined on the basis of optical televiewer (OPTV) images and the 3D geological model (Krietsch et al., 2018b). They had a length of 1 m or 2 m, and covered the target shear zones plus adjacent brittle fractures. Table 1 summarizes all experiments and geological, hydraulic and mechanical properties of the corresponding injection intervals. To quantify the near-wellbore transmissivity changes of the intervals resulting from the experiments, low-pressure (P\text{injection} < 0.5 MPa) hydraulic tests consisting of pulse and constant rate injections were conducted before and after the hydraulic stimulation campaign in each injection interval (Brixel et al., 2020a, 2020b; Jalali et al., 2018a, 2018b). The hydraulic properties of the intervals (i.e. transmissivity, storativity, and wellbore storage) were estimated using the numerical simulator nSight1.

Table 1. Overview stimulation experiment with corresponding information about the injection interval. Note that the experiments are sorted in chronological order.

| Experiment | HS2 | HS4 | HS5 | HS3 | HS8 | HS1 |
|------------|-----|-----|-----|-----|-----|-----|
| Date       | 08.02.2017 | 09.02.2017 | 10.02.2017 | 13.02.2017 | 14.02.2017 | 15.02.2017 |
| Injection borehole | INJ1 | INJ1 | INJ1 | INJ1 | INJ1 | INJ2 |
| Interval depth [m] | 38.00-40.00 | 27.20-28.20 | 31.20-32.20 | 34.30-35.30 | 22.00-23.00 | 39.75-40.75 |
| Target shear zone | S1.2 | S3.1 | S3.2 | S1.1 | S1.0 | S1.3 |
| Number of brittle fractures | 5 | >3 | >1 | 2 | 2 | 3 |
| Interval transmissivity pre-stimulation pulse tests [m²/s] | 2.5e-9 | 1.2e-7 | 1.2e-8 | 4.8e-10 | 2.8e-10 | 8.3e-11 |
| Injection cycle | | | | | | |
| 2 injectivity [lit/min/MPa] | 0.018 | 0.95 | 0.08 | 0.0028 | 0.0019 | 0.0006 |
| Injection cycle | | | | | | |
| 2 jacking pressure [MPa] | 4.9 | 7.1 | 6.9 | 4.8 | 5.4 | 5.6 |

1 An open-source n-dimensional statistical inverse graphical hydraulic test simulator developed by Sandia National Laboratory. (https://github.com/nsights/nSIGHTS)
### Injection Protocol

We followed the same standardized injection protocol for all six HS experiments to highlight the influence of the target geological structure (i.e., shear zone) on the variability of HM-coupled rock mass responses. The standardized protocol is illustrated in Figure 4 and consisted of four injection cycles, referred to as C1-C4, which each consisted of progressively-increased pressure or flow-rate steps. In all cases, the steps were kept constant until quasi steady-state flow conditions were reached. The first two cycles were step-pressure injection tests and were intended to estimate the pre-stimulation jacking pressure and injectivity of the target shear zone injection interval (see section 3.2). Here, the first cycle of the test primarily serves to break down the injection interval, and so that the fracture changes during subsequent cycles are largely elastic. The third cycle was a step-rate test-injection that constituted the actual stimulation phase. The majority of the fluid volume was injected during this cycle, and was intended to propagate the stimulation effects away from the injection well. The last cycle was performed to estimate the post-stimulation jacking pressure and injectivity (see section 3.2), and began under pressure control but then switched to flow rate control to obtain higher flow rates in the last two injection steps. Each injection cycle was followed by a shut-in phase in which no fluid is injected or released, and a subsequent venting phase. During venting, the pressure lines leading to the injection interval were opened to the atmosphere in the AU Tunnel for 20 mins to 40 mins after C1 and C2, and 40 mins after C3. However, the lines leading to the pressure monitoring intervals were opened only after the actual stimulation phase and the final injection cycle for intervals that showed a significant pressure change, and then only after the shut-in phase of C3 and C4. All intervals remained shut in after C1 and C2. The duration of venting after C3 for those intervals that were opened generally followed the duration of venting of the corresponding injection interval, although the duration was shorter for some intervals in some experiments (e.g. PRP3.1 in HS3). Thus, the induced fluid pressure disturbances within the fractures of the rock mass were partly, but not entirely drained at the beginning of each injection cycle.

### Injection Summary

| Injection | Total volume injected [lit] | Total Backflow from boreholes [lit] |
|-----------|-----------------------------|-----------------------------------|
|           | 797                         | 300.57                            |
|           | 1253                        | 109.73                            |
|           | 1211                        | 143.63                            |
|           | 831                         | 89.78                             |
|           | 1258                        | 175.79                            |
|           | 982                         | 360.995                           |

### Final Interval Properties

| Interval transmissivity post-stimulation pulse tests [m²/s] | Injection Cycle 1 | Injection Cycle 2 | Injection Cycle 3 | Injection Cycle 4 |
|-----------------------------------------------------------|-------------------|-------------------|-------------------|-------------------|
|                                                           | 2.2e-7            | 1.2e-7            | 5.5e-8            | 2.3e-7            |
|                                                           | 7.5e-8            | 1.5e-7            |

| Injection Cycle | 4 jacking pressure [MPa] | Injection Cycle | 1.11 | 3.9 |
|-----------------|--------------------------|-----------------|------|----|
|                 |                          |                 |      |    |

### Reactivated Fracture

| Number of reactivated fractures | Cumulative slip dislocation [mm] | Injection Cycle 1 | Injection Cycle 2 | Injection Cycle 3 | Injection Cycle 4 |
|---------------------------------|----------------------------------|-------------------|-------------------|-------------------|-------------------|
| 1                               | 0.85 - 1.1                       | 0.6 - 1.6         | Unclear           | 1.1 - 1.4         | 0.2 - 0.8         | 0.7 - 0.81        |
Following each experiment, all intervals were allowed to drain for a minimum of 12 hours before the next experiment. The total volume of fluid injected in each experiment was limited to approximately 1000 liter to ensure low seismic hazard and little disturbances to nearby experiments (Gischig et al., 2016). The backflows from the injection borehole and all pressure monitoring intervals were measured during the venting phases after each cycle.

Figure 4. Injection protocol for (a) experiment HS2, which targets S1 structure S1.2, and (b) experiment HS4, which targets S3 structure S3.1. The various phases of the four cycles performed in each experiment are indicated in b. Similar plots for all other intervals are presented in Figure A2 of the Appendix.

3.2 Monitored properties at the injection well Measurement of hydraulic properties at the injection interval

To quantify the near-wellbore transmissivity changes of the intervals resulting from the experiments, low-pressure (P_{injection} < 0.5 MPa) hydraulic tests consisting of pulse and constant rate injections were conducted before and after the hydraulic stimulation campaign in each injection interval. The hydraulic properties of the intervals (i.e., transmissivity, storativity, and wellbore storage) were estimated using the numerical simulator nSight2. For a more detailed description of the in-situ hydrology and the induced changes, see Jalali et al. (2018a, 2018b).

Figure 5. Illustration of the relationship between injection pressure and flow rate during each of the four injection cycles of test HS2. The points denote the P-Q data pairs prevailing at the end of the pressure or flow rate step. The slope of the initial linear curve at low pressure for each cycle denotes the interval injectivity. The high pressures reached during the first cycle reflect the breakdown of the cohesive component of strength and/or initiation of shearing, which are likely to irreversibly increase interval injectivity, as is cycle 3 which is the stimulation. Cycles 2 and 4 are passive intended to work the fracture in the elastic regime so that deviations from the initial linear trend

An open-source n-dimensional statistical inverse graphical hydraulic test simulator developed by Sandia National Laboratory.
Hydraulic jacking pressure and injectivity were determined from a $PQ-QP$ cross-plot of the test data, where $P$ presents the injection pressure and $Q$ is the injection flow rate, an example of which is shown in Figure 5. Each point denotes the flow and pressure values at the end of each step when quasi steady-state conditions are reached, typically after 10 minutes. The first cycle of the test primarily serves to break down the injection interval and so that the fracture changes during subsequent cycles are largely elastic. The low-pressure linear trend on the $P-Q$ plot defines the initial injectivity of the test interval and the intersection with the pressure axis defines the initial formation pressure. The injectivity of the test interval is taken as the ratio of the injectivity increase, in the simplest case according to the cubic law, gives rise to a progressively steepening $P-Q$ curve which in principle will reach a limiting pressure when the surfaces of the fractures just separate. For a single fracture, the limiting pressure will reflect the normal stress acting on the fracture. This would be the so-called ‘jacking pressure’. In practice, the $P-Q$ curve usually transitions to a steep, high-pressure quasi linear trend rather than a limiting pressure, perhaps reflecting the development of increasing hydraulic losses within or at the entrance to the fractures taking the flow.(Dahlø et al., 2003) Dahlø et al. (2003) noted that there is no consensus as to which feature in the $P-Q-Q$ plot provides the best estimation of the jacking pressure (i.e. the normal stress across the fractures that supports the lowest normal stress) because it is unclear at which point along the steepening $P-Q$ curve the compliant fracture response turns into lift-off of the fracture surfaces. Hydropower engineers sometimes pick the first deviation from the low-pressure linear trend as the jacking pressure (eg. Johannesson et al., 1988) as their focus is on the pressure at which hydro-mechanical effects begin to enhance losses from the pressure tunnels, rather than the pressure at which surfaces are just separated, which is of interest here. We take our best estimate of the jacking pressures before and after the stimulation as the intersection of the low- and high-pressure trends of the second and fourth cycles respectively. In both these cycles it is assumed that the response of the fracture network to the step-increases in pressure is purely elastic and repeatable. Shear slip on fractures though which the injected fluid flows could give rise to irreversible increases in aperture with attendant increases of low-pressure transmissivity. However, most shear stress is released in the first cycle which usually extends to significantly higher pressures than subsequent cycles owing to the low injectivity that permanently increases with breakdown.

For the same reasons given above, the pre-stimulation jacking pressure and $C3$ (Figures 6 and Figure 7A3 in the appendix) are derived from the second and fourth injection cycle, too $C2$ of the test data, and the post-stimulation values from $C4$ (Figures 6 and Figure 7A3 in the appendix). The injectivity is taken as the ratio between the flow rate and injection pressure at low injection pressures, when mechanical effects are negligible. The jacking pressure was determined during $C2$ and $C4$ using the method described in section 3.1. In addition, we picked the injection pressure limit during the actual stimulation (injection cycle 5) $C5$ for all experiments (Figure Figure 7A3). The induced slip dislocation within the injection intervals were estimated from 3.3 Measurement of slip dislocation at the injection interval.
Acoustic televiewer (ATV) logs that were run before and after each HS experiment. The ATV probe used for the measurements has a travel time precision of 0.1 µs, yielding a radius precision of 0.07 mm for borehole fluids with a P-wave velocity of 1483 m/s. Note that the travel time precision of the ATV decreases as the measured amplitude of the received P-wave decreases. Thus, the precision strongly decreases as the borehole wall becomes very rough, or the borehole radius becomes strongly elliptical (Moor and Valley, 2018). Since the S3 shear zones are located in weak meta-basic dykes, which appear rougher at the borehole walls as the S1 shear zones, the radius resolution is lower for S3 shear zones than for S1 shear zones.

The ATV probe measures the borehole radius with a 360° coverage normal to the borehole axis (Figure 6a). By comparing the pre- and post-stimulation geometry of the borehole cross-section across fractures in a borehole it is possible to determine whether dislocation has occurred, and estimate the relative displacement vector (Cornet et al., 1998; Evans et al., 2005b) (Cornet et al., 1998; Evans et al., 2005b). To enable reasonable comparability between the images, all logs were recentralized using an ellipse fit function. Afterwards, a difference log was produced for each test interval by subtracting the pre-stimulation log from the post-stimulation log. In this difference log, a positive caliper change at a location along the borehole wall indicates that the location has moved away from the borehole axis during stimulation (Figure 6b). The resolved radius changes can be due to: a) stimulation-induced fracture reactivation (i.e., sinusoidal traces along the borehole wall, see Figure 6c), or b) damage along the borehole wall (i.e., diffuse traces, see Figure 6c). To validate the orientations and locations of reactivated fractures, the ATV logs were compared with the brittle fractures mapped in the optical televiewer images.

To estimate the magnitude of slip dislocation across a reactivated fracture, the areas of radius increase and decrease are mapped along the fracture trace (Figure 6b). The sum of the absolute maximum radius changes on both sides of the fracture (i.e. Δr_X1 and Δr_X2) revealed the apparent amount of slip dislocation (Δr_apparent). Note that since the radius changes are measured normal to borehole axis. Thus, the true slip dislocation Δr_total is calculated by correcting the apparent dislocation Δr_apparent with respect to the intersection angle between the borehole axis and the fracture plane (α). The detection threshold for slip dislocation depends on the fracture orientation and ATV accuracy.

The direction of the induced-slip dislocation can be inferred from the difference logs, too. Along the sinusoidal trace of the reactivated fracture within the difference log, the radius change varies from positive to negative and back. The location at which these radius change variations occur (Δr = 0) is normal to the direction of induced permanent dislocation (Figure 6b). Note that this orientation is not well resolved for all experiments.

Figure 6. a) Illustration of the travel-time (i.e. radius) measurement of an ATV log across a sheared fracture. b) Observation of slip displacement direction and apparent magnitude estimate visualized in the unwrapped difference log. c) Difference logs for HS2 and HS4 experiments. A clear trace of a reactivated fracture is visible in the HS2 log, whereas a diffuse trace with potential borehole wall damage is shown in the HS4 log.
The ATV probe used for the measurements has a travel time precision of 0.1 µs, yielding a radius precision of 0.07 mm for borehole fluids with a P-wave velocity of 1483 m/s. Note that the travel time precision of the ATV decreases as the measured amplitude of the received P-wave decreases. Thus, the precision strongly decreases as the borehole wall becomes very rough, or the borehole radius becomes strongly elliptical (Moor and Valley, 2018). Since the S2 shear zones are located in weak meta-basal dykes, which appear rougher at the borehole walls than for S1 shear zones, the radius resolution is lower for S2 shear zones than for S1 shear zones.

3.34 Pressure monitoring

The three PRP boreholes were equipped with a customized grouted packer systems to continuously monitor fluid pressure in a total of seven intervals throughout the test volume that allowed the fluid pressure in several intervals to be continuously monitored during the experiments (Figure 1). The pressure monitoring intervals in all boreholes were assigned names formed according to the borehole name and the interval number counted from the borehole bottom upwards (e.g. PRP2-1 is the lowermost interval in PRP2). The intervals were chosen to cover the different target shear zones in the volume, thereby allowing the pressure in these shear zones to be monitored (Table 2).

The distances between the monitoring intervals and the injection locations are listed in Table A. The packer system consists of a grouted section (uppermost part), the open pressure monitoring intervals (2 to 3 per borehole), resin sections in intervals without pressure monitoring, and inflatable packers to seal off the monitoring intervals. The packers have a length of 0.2 m and were inflated with pressures between 2 and 3 MPa. The seventeen intervals were connected to pressure sensors in the AU tunnel through saturated polyamide lines of 2 mm OD. The sensors used were Keller PAA33-X transmitters that had an accuracy of 0.025 MPa. A detailed description of this packer system can be found in Doetsch et al. (2018a).

| Interval name | Depth [m] | Number of fractures | S1-type | S3-type |
|---------------|-----------|---------------------|---------|---------|
| PRP1-1        | 41.8 – 47.9 | 14                  | S1.2 & S1.3 |         |
| PRP1-2        | 28.9 – 32.0 | 6                   |         | S3.2    |
| PRP1-3        | 23.2 – 25.2 | 6                   |         | S3.1    |
| PRP2-1        | 40.0 – 45.0 | 8                   | S1.3    |         |
| PRP2-2        | 21.4 – 27.0 | 11                  | S3.1 & S3.2 |       |
| PRP3-1        | 24.8 – 32.3 | 4                   | S1.1 & S1.2 |       |
| PRP3-2        | 15.0 - 20.5 | 10                  | S3.1&S3.2 |         |

In addition to these fixed pressure monitoring intervals in the PRP-holes, a double-packer system was installed in one of the twenty INJ-boreholes that was not used for injection. The system allowed pressure to be monitored between the two packers, and between the lower packer and borehole bottom. Similarly, the pressure was also monitored between the lower packer and the borehole bottom in the INJ-Borehole that was used for injection. The packer systems in the INJ-holes were moved for each experiment to allow injection into and monitoring of the target shear zone to be stimulated (Table A).

The pressure monitoring intervals in all boreholes were assigned names formed from the borehole name and the interval number counted from the borehole bottom upwards (e.g., PRP2-1 is the lowermost interval in PRP2).
3.54 Deformation monitoring

3.54.1 Strain monitoring

The Fhree FBS boreholes were dedicated to longitudinal strain monitoring (Figure 1d). Borehole FBS1 intersects all target shear zones, FBS2 is parallel to the S3 shear zones, and FBS3 is subparallel to the S1 shear zones. A total of 20 longitudinal Fiber-Bragg-Grating (FBG) strain sensors (Type 003600 by Micron Optics Inc.) were installed in each of these boreholes. The sensors were placed covering along sections with intact rock mass, as well as with single and multiple fractures based on optical televiewer (OPTV) images and the geological model (Doetsch et al., 2018a; Krietsch et al., 2018b). Subsequently, the sensors were grouted in place. The FBG sensors have a base length of 1 m and recorded strain signals with a resolution of 1 microstrain (µe) at a sampling frequency of 1000 Hz. The boreholes were logged with an optical televiewer (OPTV) to provide the information needed to design the system. The optical fiber was then installed in a tube with sensors covering both intact rock mass sections, single and multiple fractures, as well as shear zones (Error! Reference source not found.). Subsequently, the tubes containing the optical fibers were grouted in place.

The sensors were interrogated at 1 kHz, and as first processing step, the data were averaged over 1 s intervals before recording, giving a sampling rate of 1 Hz, and an improved resolution of 0.1 µe (Krietsch et al., 2018a; Krietsch et al., 2018b). Temperature corrections were not applied or required for the FBG data since the injected fluid had the same temperature as the rock mass and temperature variations within the rock volume were negligible. To quantify deformation, we follow the geomechanics convention and take the compressional strain as positive.

3.54.2 Tilt monitoring

Two horizontal bi-axial inclinometers (Type A711-2 by Jewell Instruments) were installed at the bottom of approximately 50 cm deep boreholes drilled on the floor of the VE-tunnel (T1-T2 in Figure 1d). They monitor the deviation from horizontal in two orthogonal axes with an accuracy of ~0.5 microradians (µ-rad) at a sampling rate of 100 Hz. The tilt data were processed with a low pass Butterworth filter with 100 Hz cut-off, which enhances resolution to ~0.05 microradians. The instruments were oriented such that the x-axis was parallel to the tunnel axis and the y-axis normal to it. A positive tilt signal on the x-axis implies the tunnel floor has dipped towards SWS, and a positive signal on the y-axis implies a dip towards ESE (i.e. towards the test volume) (Figure 1d). Instrument T2 is placed near the intersection of the tunnel with the two S3 shear zones, S3.1 and S3.2, and instrument T1 lies some 13 m to the south, near the intersection of the tunnel with the S1 zones S1.2 and S1.3.

3.56 Seismic Monitoring

A total of 18 piezo-electric acoustic emission (AE) receivers (Type Ma-Blis-70m by GMuG) were installed along the tunnel walls around the test volume. Additionally, eight sensors of the same type were deployed in four dedicated boreholes (i.e., referred to as GEO boreholes, Figure 1f). The eight borehole sensors are closest to the injection locations (3 m – 25 m distance) for all six experiments. The sensors have a bandwidth of 1 to 100 kHz. Additionally, five calibrated one-component accelerometers (Type 736T by Wilcoxon) were collocated with the five AE sensors at the tunnel wall for magnitude calibration purposes.

Seismic data were recorded continuously throughout the experiments at a sampling rate of 200 kHz, using a 32-channel acquisition system, with 31 active channels. Induced seismic events were located using an anisotropic velocity model based
on manually picked P-wave onsets. For more details on the seismic monitoring and event localization, see (Doetsch et al., 2018a; Gischig et al., 2018; Villiger et al., 2019; 2020) Doetsch et al. (2017), Gischig et al. (2018) and Villiger et al. (2019).

4. Results

The multi-faceted monitoring system provides an unusually detailed description of the hydro-mechanical (HM) response during stimulation of the fractures and shear zones contained within the experimental rock volume. As already mentioned, the focus of this contribution is the hydro-mechanical response of the S1 and S3 shear zone types to the stimulation injections, and in particular, to differences between the two (Figure 2). Given the large volume of data recorded, some economies must be made where possible in reporting the results. In the following, we will for the most part restrict to illustrating the HM observations using the figures for two of the stimulation experiments - HS2 and HS4 as examples. Similar observation representative for all six hydraulic shearing (HS) experiments which are documented in the appendix. We use the experiments called HS2 and HS4 as representatives for stimulations that targeted S1- and S3- shear zones, fault zones, respectively. The seismological responses of the rock mass and shear zones are covered in detail by Villiger et al. (2019), and thus only a brief summary will be presented in this paper.

4.1 Hydro-mechanical observations at injection intervals

Near-wellbore observations

From Table 1 it is clear that the initial injectivity and near-well transmissivity for the S1-intervals were systematically lower than those for the S3-intervals by 1-3 orders of magnitude (Table 1). Despite this difference, the post-stimulation transmissivities were remarkably similar, all lying between 5.5e-8 m²/s within a factor of 2 of and 2.3e-7 m²/s. Thus, substantial transmissivity increases of up to 3 orders of magnitude were realized for the S1 shear zones, whereas the increases for the S3 shear zones were limited to less than an order of magnitude (Figure 8). The final low-pressure injectivities measured during the last injection cycle, ranged between 0.4 – 1.7 l/min/MPa, and the final transmissivities range between 1.2e-7 – 2.3e-7 m²/s (Table 1).

Cross-plots of the pressure and flow rate values prevailing at the end of the steps in the various stages of the six experiments are shown in Figure 6 and Figure 7, and the pre-stimulation and post-stimulation jacking pressures, transmissivities and injectivities are listed in Table 1. It is evident that the initial jacking pressures in the two injection intervals covering S3 shear zones are systematically lower than those for the S1 shear zones, in most cases by ~1.5 MPa. Following the stimulations, the majority of the intervals showed the same or slightly reduced jacking pressure, with one showing a significant decrease (S1 stimulation - HS1) and one a significant increase (S3 stimulation - HS5) (see Table 1). The highest drop in jacking pressure of 1.7 MPa was observed for the S1 interval HS1. The final jacking pressures for the S1-intervals varied between 3.9 and 5.5 MPa, whereas for the S3-intervals the variation was 6.8 and 7.4 MPa. As opposed to S3 intervals, For the maximum recorded interval pressure during cycle 1 in S1 intervals it is also evident that the first injection cycle peak injection pressures during CJ for the S1 stimulations exceeded the jacking pressure, was much higher than the jacking pressure and for the maximum stimulation cycle injection pressure limit observed for the same interval, suggesting a significant cohesive component to the reopening strength of the zone, whereas no such injection peak pressure was evident for the S3 intervals during the first injection cycle.
Figure 7. Cross-plots of flow versus pressure data for the four injection cycles of the S1 and S3 stimulation experiment in a) and b) respectively in a-f. The points defining the curves for each cycle denote flow/pressure data pairs defined at the end of each step of the test in question. The first cycle frequently reaches high pressures, which may reflect the inelastic processes of the breakage of cohesive bonds and/or the slippage of fractures supporting shear stress. In subsequent cycles, the response to pressurization is largely elastic and reversible.

An upper limit of injection pressure despite increasing flow rates (referred to as pressure limiting behavior) was observed during the main stimulation injection cycle C3 was observed in all experiments, with some slight systematic differences between the S1 and S3 intervals. For the S3-stimulations, a slight increase in pressure with increased flow rate was evident, as the PQ-PQ curves becoming progressively steeper with increased flow rate when a pressure limit was approached on the final step (Figure 7). In contrast, the C3-PQ curves for the S1-stimulations showed more classic pressure limiting behavior, with pressure monotonically declining with higher flow rate in some cases (i.e. HS2, HS3), and declining before recovering in others (e.g. HS1, HS8). The comparison between the injection pressures at the end of the first and last injection steps during C3 are listed in Table 3. Note, that a As for the jacking pressures, the maximum injection pressures attained in the stimulation injections were consistently higher for the S3 shear zones than for S1 shear zones (Table 3).

Table 3. Injection pressures measured at the end of the first and last (before shut-in) injection steps of the stimulation injection cycle (C3). The difference between the two values is listed in the lower row.

|                 | HS2 (S1) | HS4 (S3) | HS5 (S3) | HS3 (S1) | HS8 (S1) | HS1 (S1) |
|-----------------|----------|----------|----------|----------|----------|----------|
| Pressure Limit  |          |          |          |          |          |          |
| $P_{\text{Step1-C2}}$ [MPa] | 5.53 | 7.25 | 7.3 | 5.13 | 5.39 | 5.91 |
|-----------------------------|------|------|-----|------|------|------|
| $P_{\text{LastStep-C1}}$ [MPa] | 5.23 | 7.51 | 8.85 | 4.72 | 5.94 | 5.97 |
| Difference [MPa] | -0.3 | +0.26 | +1.55 | -0.41 | +0.55 | +0.06 |

From Table 1 it is clear that initial injectivity and near-well transmissivity for the S1 intervals were systematically lower than those for the S2 intervals by 1-3 orders of magnitude. Despite this difference, the post-stimulation transmissivities were remarkably similar, all lying within a factor of 2 of 1e07 m²/s. Thus, substantial transmissivity increases of up to 3 orders of magnitude were realized for the S1 shear zones, whereas the increases for the S3 shear zones were limited to less than an order of magnitude (Figure 8). The final injectivities range between 0.4 – 1.7 l/min/MPa, and the final transmissivities range between 1.2e-7 – 2.3e-7 m²/s (Table 1).

The measured backflow during the venting of each HS experiment ranged from 9% (HS7) to 37% (HS1 and HS2) of the injected fluid volume. Since the rock mass was left to drain for only 12 hours between the experiments, the low backflow volumes would have been larger had drainage been longer, although not by much as flow rates at the end of the 12 hours were invariably small. In addition, flow was observed from brittle fracture traces at the tunnels during and following the experiments. With the exception of the main flow outlet in the AU tunnel, this flow was not measured during the 12-hour venting.

The estimates of injection-induced slip resolved across fractures in the injection intervals are shown in Figure 8d and the unwrapped difference images shown in Figure A3 of the Appendix. The resolved slip was localized on a single fracture, as in HS2, or distributed over various fractures as in HS4 (Figure 6). The maximum value of ~1.4 mm was found for an S1-stimulation (HS3 in Figure 7d). Dislocations slightly less than a millimeter were also identified for other stimulated target S1 shear zones (HS1 and HS2, and perhaps also HS8), although the uncertainty is large. A value of ~1 mm was obtained for an S3 stimulation (HS4), but the uncertainty in this estimate was large because of the greater borehole wall roughness at the S3 shear zones. The resolution of the ATV data was lower at these zones (HS4 and HS5) (Error! Reference source not found.) (Figure A4). Dislocations slightly less than a millimeter were also identified for S1 shear zones HS1 and HS2, and perhaps also HS8, although the uncertainty is large. The direction of the slip vector could only be determined for two zones: for HS2 it was 261°/2 (i.e., dip direction/dip) and for the two reactivated fractures in HS3 it was 264°/01 and 286°/04. All three fractures were reactivated in a right lateral strike-slip dislocation in an east-west direction.
Figure 87. Hydro-mechanical responses of the target intervals to the stimulation experiments. Indicated are (a) pre-and post-stimulation transmissivity, (b) pre- and post-stimulation jacking pressure, (c) injection pressure limit observed during C3, (d) estimated cumulative slip displacement, and (e) number of detected and located seismic events.

4.2 Hydraulic response

Fluid pressure inside the rock mass

No systematic differences in the recorded pressure magnitude responses away from the injection well to injection into S1 and S3 shear zones were evident away from the injection well. During all HS experiments, the highest fluid pressure perturbations were detected in monitoring intervals that cross the target shear zones. Transient fluid pressure perturbations were observed on almost all PRP pressure monitoring intervals during all six hydroseismic stimulation experiments. In four experiments, the pressure increases rarely exceeded 1 MPa, regardless of shear zone type, even though peak injection pressures ranged between 5 – 9 MPa (Figure 87 and Figure A4A5). However, relatively high fluid-pressure magnitudes were observed during experiments S3 stimulation (HS5) and S1 stimulation (HS8), respectively (Figure A4A5).

These observations, where injection took place into zone S3.2, the maximum pressure perturbations of 5.7 MPa, 6.7 MPa and 2.7 MPa were observed in PRP1-2 (S3.2), PRP2-2 (S3.1) and INJ2-1 (S1.1, S1.2, and S1.3) respectively, the latter interval spanning 28.3 – 45.0 m of INJ2 during this experiment (Table 4). For HS8, which featured injection into zone S1.0, the maximum perturbation of 4.2 MPa occurred in INJ2-2, which spanned depths 5.9 – 18.6 m during HS8 (Table 4). The INJ2-2 interval contained only minor fractures, the nearest fracture zone being S1.0 which intersected INJ2-1.5 m from the interval at 20.1 m.
Perturbations were also seen in the other few pressure monitoring intervals during these two experiments but were minor in comparison. Although one of the monitoring intervals that detected the strong pressure signals covered the target shear zone that was being injected (i.e. PRP1-2 during HS5), the remainder of the strong responses were from intervals that covered other zones, indicating that the shear zones are interconnected. For example, interval INJ 1-1 (S1.1, S1.2 & S1.3) during HS5 showed an abrupt rise in pressure to 2.7 MPa towards the end of C4 (see Krietsh et al. (under review) for details). However, the majority of intervals outside of the target shear zone registered only minor pressure perturbations.

Table 4. Locations and packed-off length of monitoring intervals in the INJ boreholes during the stimulation experiments. The fracture zones that intersect the interval are given in the adjacent column. Monitoring intervals that include the interval undergoing injection are marked with (*).

| Ext. (Zone) | INJ 1-1 Depth (m) | Zones | INJ 1-2 Depth (m) | Zones | INJ 2-1 Depth (m) | Zones | INJ 2-2 Depth (m) | Zones |
|-------------|-------------------|-------|-------------------|-------|-------------------|-------|-------------------|-------|
| HS2         | 10.0 - 45.0       | S1.3  | 18.0 - 40.0       | S1.2  | 16.0 - 45.0       | S1.3  | 11.5 - 35.5       | S1.2  |
| HS4         | 20.2 - 45.0       | S3.1  | 27.2 - 28.2       | S3.1  | 28.3 - 45.0       | S1.1, S1.2, S1.3 | 19.6 - 27.3 | S1.0, S3.1, S2.2 |
| HS5         | 33.2 - 45.0       | S1.1, S1.2, S1.3 | 41.2 - 22.2 | S2.2 | 28.3 - 45.0 | S1.1, S1.2, S1.3 | 19.6 - 27.3 | S1.0, S3.1, S2.2 |
| HS3         | 36.3 - 45.0       | S1.2, S1.3 | 34.3 - 35.3 | S1.1 | 28.3 - 45.0 | S1.1, S1.2, S1.3 | 19.6 - 27.3 | S1.0, S3.1, S2.2 |
| HS5         | 31.0 - 45.0       | S1.1, S1.2, S1.3 | 22.0 - 23.0 | S1.0 | 19.6 - 45.0 | S1.0, S1.1, S1.2, S3.1, S3.2 | 5.9 - 18.6 | S1.0, S3.1, S2.2 |
| HS1         | 40.7 - 45.0       | S1.3  | 27.0 - 30.7       | S1.1, S1.2, S1.3, S3.2 | 41.75 - 45.0 | - | 40.75 - 40.75 | S1.3 |

No systematic differences in the recorded pressure magnitude responses to injection into S1 and S2 shear zones were evident. However, a tendency for the pressure in the PRP intervals to react more immediately to shut-in after injections into S1 intervals compared to S3 intervals can be discerned, particularly at the end of the stimulation injection cycle C3 (Figure A2 & Table A2A3). This difference is exemplified in Figure 9 where the immediate pressure response of S1 shear zones (e.g. PRP1-1) to shut-in after injection into another S1 shear zone (e.g. HS2) aPRP1-1 (S1.3) to C3 shut-in in HS2 (injection into zone S1.2) can be contrasted with the somewhat delayed reaction of pressure intervals sampling S3 structures (PRP1-3 and PRP2-2) that were target during (both S2.1) to in HS4 stimulation (injection into zone S3.1) (Figure 8). Indeed, for the S3-stimulations, almost all monitoring intervals that included the target shear zone showed a delayed response to the shut-ins.

The fluid pressure in most monitoring intervals at the end of the experiments remained perturbed from their initial values, but in all cases had returned to initial values by the start of the subsequent experiment the following morning (note that the sequence of experimental results in Figure A5A4 are presented in chronological order). The pressures prevailing in PRP1-1, PRP2-1, and PRP3-1 at the end of the experiments were below the initial values due to the effect of venting the intervals following the stimulation injection cycle C4 and last injection cycle C4 (Figures 8 & Figure A4A5). It is noteworthy that the venting responses of S1-2 intervals covering the S1.3 shear zone (PRP1-1 and PRP2-1) consistently differed from all other intervals in that significant backflow occurred during venting so that the interval pressure declined relatively slowly. In contrast, the pressure in all other intervals declined rapidly to atmospheric pressure in the tunnel when the valve was opened, although it was clear in some cases that backflow into the interval was occurring.
as the pressure began to climb once the valve was closed (e.g. S1 covering pressure interval PRP3-1 (S1.1 and S1.2) in HS4) (Figure 9). Thus, backflow into S1 intervals upon venting tended to be greater than at intervals cutting S3 fracture zones. Pressure perturbations were also detected out to the furthest remote monitoring intervals from the target intervals. The largest distance to injection was 25 m for PRP1-1 during HS8 (Figure A6c), although maximum distances during the other stimulations were typically 15-19 m for the other stimulations (Figures 8 and A6). These distances are pressure perturbations Euclidean distances from initial levels prevailing at the various monitoring locations at the end of the stimulation injection cycle C3 are plotted as a function of the straight-line distance from the monitoring intervals to the injection point in Figures 9c/d and 21. Thus, these distances, which are listed in Table A1, will generally be less than the true distances of pressure diffusion along hydraulically active fluid pathways. For most stimulations, pressure perturbations were detected out to the furthest monitoring intervals from the target intervals, the largest being 25 m for PRP1-1 during HS8 (Figure A5e), although maximum distances during the other stimulations were typically 15-19 m (Figure 9 and Figure A5). No systematic difference in pressure transmission distances for S1- and S3-stimulations was evident. For both shear zone types, the pressure perturbations registered in intervals that cut the target shear zone tended to be greater than at other intervals located at a comparable distance. There are, however, some exceptions to this. For HS4 however, a relatively weak response was observed at an interval (PRP3-2), that covered the shear zone into which the fluid was injected (PRP3-2 (S3.2) in comparison with other intervals at nearer or comparable distances that did not cover the target shear zone (i.e. PRP1-3 (S3.2), PRP2-1 (S1.3)), and PRP1-1 (S1.2) (Figure 8).
4.2.1 Extent of pressure perturbation

The pressure perturbations from initial levels prevailing at the various monitoring locations at the end of the stimulation injection cycle C3 are plotted as a function of the straight-line distance from the monitoring intervals to the injection point in Figures 9c/d and 21. These distances, which are listed in Table A1, will generally be less than the true distances of pressure diffusion along hydraulically active fluid pathways. For most stimulations, pressure perturbations were detected out to the furthest monitoring intervals from the target intervals, the largest being 25 m for PRP1-1 during HS8 (Figure A5a), although maximum distances during the other stimulations were typically 15-19 m (Figure 9 and Figure A5). No systematic difference in pressure transmission distances for S1- and S3-stimulations was evident. For both shear zone types, the pressure perturbations registered in intervals that cut the target shear zone tended to be greater than at other intervals located at a comparable distance. There are, however, some exceptions to this. For HS7, a relatively weak response was observed at PRP2-2 (S2.2) in comparison with other intervals at nearer or comparable distances that did not cover the target shear zone (i.e., PRP1-1 (S3.2), PRP2-1 (S1.3)), and PRP1-1 (S1.3).
4.3 Mechanical response: Spatial-temporal rock mass deformation

During all HS experiments, the FBG sensors measured compressional and extensional strain perturbations whose magnitudes correlated over time with the-in response to the injection protocol. Specifically, it was observed that a) The largest strain magnitudes were observed during periods of fluid injection and b) the magnitudes decreased during shut-in and venting (see Figure 10a-b for the experiments HS2 and HS4). Examples of strain signatures recorded during HS2 (S1) and HS4 (S3) are shown in Figure 10a and b, respectively. For all sensors in all experiments, the strain signatures represent perturbations from the values prevailing at the start of the experiment in question (i.e., zero strain at the start of the experiments). Compressional strains are taken as positive. Since the strain signals denote changes in the relative axial displacement of one end of the baseline with respect to the other divided by the base length, they represent relative axial displacements integrated over the entire FBG base length. As such, they could reflect intact rock deformation and/or fracture dislocation. For each strain signature, we define the permanent (i.e., irreversible) strain as the strain remaining at the end of the experiment, and the reversible strain as the difference between the peak strain and the permanent strain (Figure 9). Here, the peak strain corresponds to the largest strain excursion in the coda, and may be positive (i.e., compressional) or negative (i.e., extensional). In most cases, the peak strain was observed during the stimulation injection cycle (C3) (Figure 10a-b), when the largest amount of fluid was injected. Generally, we observed that the reversible strain amplitudes were often larger than the permanent irreversible amplitudes (Table 4), as can be seen from the ratio of the two averaged over all gauges for all experiments in Table 5. It is noteworthy that non-zero permanent strains were detected for each experiment on all operational gauges.

Table 5. Ratio between reversible peak strain magnitude ($\varepsilon_{rp}$) and permanent strain magnitude ($\varepsilon_p$), averaged over all operational gauges and all experiments

| Experiment | HS2 (S1) | HS4 (S3) | HS5 (S3) | HS3 (S1) | HS8 (S1) | HS1 (S1) |
|------------|----------|----------|----------|----------|----------|----------|
| Ratio $\varepsilon_{rp}/\varepsilon_p$ | 10.1     | 19.8     | 222.8    | 10.0     | 9.8      | 4.9      |

4.3.1 Strain along borehole axis

Profiles of strain signals picked at the end of the C2 and C3 injections and permanent strains are shown along the three FBG borehole axes in Figure 9 and A7. Spatial coherence between neighboring gauges is evident along the strain profiles although heterogeneity is also present in some cases appears to be related to shear zone intersection points (Figures 9 and A7). Note that although the boreholes have different orientations, they are not orthogonal. This, together with the heterogeneity of the strain field, precludes the estimation of volume strains from the data. Within boreholes that are parallel to target shear zones (i.e., FBS3 for S1-stimulations and FBS2 for S3-stimulations), extensional strains were measured at the locations along the borehole axes that lay closest to the injection locations (Figure 9 and A7). This extension in most cases transitioned into compression within 5 m either up or down the boreholes from this point. In contrast, boreholes that are sub-normal to the target shear zone (i.e., FBS1 and FBS2 for S1-stimulations, and FBS1 and FBS3 for S3-stimulation) tended to show compressional strains near the point closest to the injection location (note that this point is not necessarily the borehole intersection of the target shear zone). In a simple way, these tendencies are consistent with expected parallel and normal linear strains along a profile normal to a fracture undergoing an opening mode dislocation.
Figure 9a and b) Examples of strain time series from four FBGSs during HS2 and HS4 respectively. The vertical shading denotes periods of injection during the four cycles. Examples of the permanent strain, the peak strain and the reversible peak strain are indicated on the HS4 strain codas. c) and d) Profiles of permanent strain, and strain at the end of the injection phases of C2 and C3 along the three FBS boreholes for HS2 and HS4 respectively. The open circle along each borehole denotes the location that lie closest to the injection point for the experiment in question. The pink and green bands indicate places where the holes cut S1 and S3 shear zones respectively. The small black arrows indicate the sensors whose strain codas are shown in a) and b).

4.3.2 Extent of deformation field

Figure 10 and Figure A8 plot show the absolute amplitude of the strain signals as a function of distance from the strain gage to the injection point for the end of injection C3 and permanent deformation after stimulation. Tension and compression are distinguished by upward- or downward-oriented triangles respectively. For each experiment, the upper frame shows the strain prevailing at the end of injection in C3, and the lower shows the permanent strain. In most experiments, a general tendency for lower strain amplitudes at greater distance is evident (Figures 10 and A8), with. During almost all experiments, perturbation strain signals larger than 1 µε were detected at the FBG furthest away from the injection locations.
Thus, the overall extent of the **mechanically effected deformed** zone was larger than 27-33 m, with respect to radial distance to the injection point. In the near-field

As noted earlier, points along the boreholes that were close to the injection location the **FBG points sensors** showed **complex signals**, which included either extension or compression (or a transition between both with ongoing stimulation) depending on the orientation of the sensor axes and location with respect upon whether the borehole and hence the FBG axes were parallel or perpendicular to the target shear zones. With increasing distance from further away from the injection point location, the strains in most cases tended to be compressional, regardless of sensor orientation (Figure 5, Figure 110 and Figure A78). The transition from this compressional field at distance to a mix of compression and extension (i.e. complex strain field) seemed to occur at slightly larger distances from the injection point for S1- than S3-stimulations during C3 (Table 5). The distances of this transition zone from the injection location are listed in Table 6 for all HS experiments.

Table 6 | Distance of strain-transition-zone (change from a variable to compressional strain field) to the injection point, measured at shut-in of injection cycles 2, 3 and 4.

| Test name     | Shut-in C2 | Shut-in C3 | Shut-in C4 |
|---------------|------------|------------|------------|
| HS2 (S1)      | 26 m       | 25 m       | 23 m       |
| HS4 (S3)      | 16 m       | 16 m       | 16 m       |
| HS5 (S3)      | 16 m       | 12 m       | 18 m       |
| HS3 (S1)      | 18 m       | 18 m       | 18 m       |
| HS8 (S1)      | 16 m       | 17 m       | 17 m       |
| HS1 (S1)      | 18 m       | 18 m       | 18 m       |

Figure 510. Strain signals with respect to distance to the injection point for HS2 and HS4. Generally, the strain perturbations prevailing at the end of the injection phase of cycle 3 were compressive beyond a certain distance which varied between experiments. This distance is denoted by the vertical grey line in (a) and (b), and separates the compressional zone from the so-called ‘complex zone’ where a mix of extensile and compressive strains are observed. The color code of the triangle indicates the number of fractures located within the FBG sensor intervals.
4.3.3 Tilt measurements

The two inclinometers are located in the floor of the VE tunnel (Figures 1d and 12). Instrument T2 is located near the intersection of the tunnel with the two S3 shear zones, S3.1 and S3.2, and instrument T1 lies some 13 m to the south, near the intersection of the tunnel with the S1 zones S1.2 and S1.3. The data series presented in Figure 12 show that the floor of the VE tunnel underwent tilting during all experiments, the magnitudes ranging from -4 to 2 µ-radians (i.e., -23.0e-4° to 11.5e-4°) for both tilt axes (Figures 11 and A9). Nearly-immediate tilt responses were seen at the start and stop of injection in most cycles and most experiments. Figure A8 shows that the largest tilt signals for each experiment tended to be observed on the instrument closest to the target shear zone which was target for that stimulation (Figure A9). Specifically, for injections into the S1 shear zones, significantly larger signals were seen on instrument T1 than T2. The sense of the tilt indicated that the tunnel floor tilted away from the target S1 shear zone towards WNW during the stimulations. Significant permanent tilts remained only after the HS2 and HS1 stimulations. During the S1 stimulation HS4, the tunnel floor near T1 tilted temporarily towards east (i.e., towards the test volume), whereas the tunnel floor near T2, which lies to the north near the intersection of the S1 zones with the tunnel, tilted towards west (i.e., away from the test volume). However, the permanent tilts at T1 and T2 both indicated tilting towards the east with a similar magnitude. During the other S3 stimulation (HS5), T1 showed tilting to the NW whereas T2 indicated tilting the SW, with no significant permanent tilt on either instrument. Thus, the transient tilts at both locations indicate similar E-W components of tilting of the tunnel floor away from the test volume, but with opposite north-south components (Figure A89). Significant permanent tilts remained only after the two S1 stimulations (HS2 and HS1). Note that, in general, the transient tilt signals were often much more pronounced than the permanent signals.

![Figure 612](image)

**Figure 612.** Inclinometer data for a S1-stimulation (HS2) (a), and S3-stimulation (HS4) (b). The upper panel shows the tilt time series for both experiments with the injection periods marked by the shaded vertical bands. The lower panel shows for each experiment on the right side a horizontal section through the study volume at the level of the tunnels. In these sections, the showing the shear-zones, the injection locations and tiltmeter T1 and T2 positions are indicated. The x- and y-axes of the tilt data are indicated on T2. Axes orientations of T1 are the same. Changes in the downward-oriented normal vector of the tunnel
floor at T1 and T2 are shown in the lower-hemisphere plots at the left of the frames. These frames are zoomed in sections to the very center of the lower hemisphere stereo net. Thus, the axes appear as a cartesian coordinate system.

4.3.4 Fracture initiation and stress transfer-induced compressional strains

During the C3 stimulation injection cycle-phase of an S3 stimulation experiment (HS4) (injection into S2.2) the FBG sensor installed at 24 m depth in FBS2 indicated strong (up to ~370 με peak strain) very localized extension (Figure 12) between the ends of the 1 m baseline of the sensor. No macroscopic fracture was evident on the OPTV images of the sensor location interval prior to the experiment. The strain records at 24 m and neighboring sensor locations in FBS2 are shown in Figure 13 together with the injection protocol for HS4. The large extension at 24 m began abruptly near the end of the stimulation cycle when flow rate was stepped from 20 to 25 l/min, and rapidly developed at rates up to -1.2 με/s to reach a peak strain of ~370 με by the end of the injection. Following the experiment, the sensor showed a permanent strain of -120 με, implying a reversible peak strain component of ~250 με. The strain responses at this and neighboring sensor locations in FBS2 to injection during C1 and C2 are shown at an expanded scale in the inset of Figure 13. In almost all cases the sensor register extension, although with different magnitudes which range between barely resolved at the 20 m sensor during C2, to 8 με at the 26 m sensor during C2. The relatively large strain at the 26 m may be due to the opening of a fracture, which was seen on the OPTV images of the interval. However, all other intervals were free of fractures, and the small strain responses of these intervals to the C1 and C2 injections are compatible with a continuum strain field origin for the signals. In contrast, the large extensile strain at 24 m that occurs when the flow rate is stepped from 20 to 25 l/min during C3 is not consistent with a continuum strain origin. This large extensile strain at 24 m coincides with the development of moderately large compressive strains recorded by the FBGs at 20 m and 22 m, and a complex reversal of an initial extensile strain to result in a compressive permanent strain at 26 m. Following injection, all strains progressively decayed to leave a permanent strain. Similar strains responses on the four sensors were observed during the subsequent C4-final injection cycle (C4). We interpret these strain responses as resulting from the opening of a fracture across the 24 m interval that first occurred flow rate was stepped from 20 to 25 l/min during C3. This would explain the extension measured at 24 m and compression on the neighboring sensors. Evidently, once opened, the fracture retained a permanent set. Accepting that the 24 m interval contained no fracture prior to the experiment, as suggested by the pre-stimulation OPTV survey, implies that the fracture must have propagated across the interval at the start of the highest-rate phase of the stimulation. Unfortunately, it was not possible to conduct a post-stimulation OPTV survey as the hole was cemented.
5. Discussion and Interpretation

Our interpretation is organized in a way that each section seeks answer to one of the research questions (Q1-Q4), mentioned in the introduction.

5.1 Hydro-mechanical processes at the injection interval (Q1) - Reactivation of pre-existing fractures and near-wellbore transmissivity enhancement

Stress information retrieved from the injection and pressure observations at the injection interval revealed a distinct behavior of S1 and S3 stimulations: During the first injection cycle of S1 stimulations, the peak injection pressure exceeded the jacking pressure and the maximum injection pressure of the stimulation cycle (i.e. limiting pressure). This phenomenon indicates that the pre-existing fractures S1 shear zones had a cohesive component of strength, tensile strength component that had to be overcome to reopen the fracture. We are considering this process still as a reactivation of a pre-existing fracture, since the pre-existing fracture was elastically opened during the subsequent cycles. This break down was not observed during S3 stimulation, which suggests that the S3 shear zones were not so well healed. Such tensile strength at S1 shear zones is observed this break down effect at various S1 injection locations, it is likely, that the degree to which the shear zones are healed can be extrapolated from the injection well to the decameter scale test volume. The fact that the break down was not required for S3 shear zones, which is consistent with the observation that S3 shear zones had a much lower initial transmissivity compared to S1 shear zones (Figure 7).

Prior to the stimulations, the jacking pressures of the two S1 intervals were ~7 MPa, which is systematically higher (~7-8 MPa) than the values obtained for the S3 intervals (~5 MPa), which ranged between 4.8 MPa and 5.6 MPa. For all experiments, an injection pressure limit was observed during the stimulation cycle, which we interpret as lift-off of fractures (Pearson, 1981). Again, the limiting pressure was systematically higher for S3 stimulation (7-9 MPa) than for the S1 stimulation (5-6 MPa). We interpret this as higher normal stress acting across S3 shear zones than across S1 shear zones. This contradicts is in disagreement with the stress characterization of tensors established by (Krietsch et al., 2018c) (Figure 3), from

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Figure 713. a) injection protocol during the stimulation experiment of interval HS4 with interpolations as dashed line after experiment. b) Strain records at four neighboring FBG sensor locations in FBS2 during HS4. The inset shows the strains at an expanded scale during the first two cycles.
which one would expect slightly higher normal stress across S1 than across S3. Further, the expected normal stresses would be higher (>8.5 MPa for the unperturbed stress tensor and > 10.5 MPa for the perturbed stress tensor) than observed during the stimulations, which concludes suggests that the normal stress across S1 shear zones should have higher normal stresses acting across them be higher than the across S3 shear zones. This inconsistency is best explained. We explain this inconsistency as reflecting stress heterogeneity in the stimulated rock volume (note that the perturbed stress tensor has been measured at about 40XX m from the stimulated rock volume). Indeed, during the stress measurements a jacking pressure of 3 MPas was obtained at the margins of the S3 I structure, which is lower than obtained across the same structure at the INJI borehole. Thus, we conclude that stress varies significantly along the structure, and that significant stress heterogeneity is present in the stimulated rock mass. The origin of this contrast between S1 and S3 intervals is uncertain.

For all experiments, an injection pressure limit was observed during the stimulation cycle, which we interpret as lift-off of the target shear zone, following Pearson (1981). As we observed slip dislocation at the injection interval, we argue that we induced a mixed mode dislocation (i.e. mode I, II and/or III), which is in agreement with observations from Evans et al. (2005b) and McClure and Horne (2014).

The induced slip displacements imaged at the injection intervals occurred along single or multiple fractures (Figure 5 and A4).

The number of reactivated fractures was larger for the initially high transmissive S3 intervals, compared to the initially low transmissive S1 intervals. In all cases with multiple reactivated fractures, one fracture trace was dominant. Experienced distinct large shear dislocations in the ATV images. These observations are well in agreement with the observations presented in Evans et al. (2005b) for the Soultz-sous Forêt stimulation projects stimulation projects, respectively.

The slip direction of each reactivated fracture of the slip induced on each of the planes of interval fractures was compared with the direction of the maximum shear stress vector resolved on the planes for the individual fractures using the perturbed stress tensors. The angle between the maximum shear stress vectors and the azimuth of induced slip dislocations varied between 28° and 33° (Table 6). Thus, the derived slip direction corresponds to right-lateral shear sense, while the predictions of the stress tensor measured nearby point to oblique right-later shear sense with a thrust faulting component. The angular misfit might be explained by a transient local stress transfer between adjacent fractures during fluid injection at the injection well (Kakurina et al., 2019). However, stress heterogeneity, as already inferred above may also explain, why slip direction are not well predicted by the measured stress tensor.

Given the different architectures and properties of the S1 and S3 shear zones, stress heterogeneity is expected. High fracture densities and the presence of metabasic dikes produce elasticity contrasts around the S3 shear zones (Wenning et al. 2018; Doetsch et al., 2020). Enhanced foliation and associated elastic anisotropy have been measured for the S3 shear zones (Krietsch et al. 2018b; Doetsch et al. 2020). Additionally, these material properties do not only vary between shear zone type, but also laterally along individual shear zones (see seismic velocity distributions along S3 shear zones, Doetsch et al. 2020). Thus, we argue that stress variations related to material contrasts (both changes in magnitude as well as stress rotations) give rise to larger change in normal stress along the different shear zones types than their orientation in a constant stress field.

Although all fractured experienced a. The overall right lateral shear sense, which is consistent with the prediction is similar for the detected dislocations and for the predicted shear stress directions. The angular misfit might also be explained by a transient local stress transfer between adjacent fractures during fluid injection at the injection well (Kakurina et al., 2019).

Table 6. Orientation of slip dislocation on the fractures estimated from the pre- and post-stimulation ATV logs, and the maximum shear stresses resolved on the fractures from the perturbed stress tensor. All orientations are given as dip-direction/dip.

| Experiment | Slip direction | τ_{max} | Misfit [°] |
|------------|----------------|---------|------------|
| HS2        | 081/02         | 077/35  | 33         |
| HS3        | 084/01         | 078/27  | 28         |
5.2 Near-wellbore transmissivity enhancement

We found that the near-wellbore transmissivity enhancement was most efficient for target structures that had low initial near-wellbore transmissivities. After stimulation, the near-wellbore transmissivities were similar in magnitude for all here presented experiments. This may reflect an upper limit on shear-induced irreversible transmissivity enhancement. Lee and Cho (2002) found similar effects on the laboratory experiments which suggest that is linked to the achievable, shear induced transmissivity enhancement depends on the height of asperities along the fracture surface, as inferred at the lab scale by Lee and Cho (2002). Nonetheless, in our case, the magnitude of transmissivity enhancement depends on the architecture of the stimulated structures. Stimulation of the intensely fractured rock mass around S3 shear zones was associated with only limited transmissivity enhancement, while the less intensely fractured S1 shear zones contributed larger transmissivity enhancement. We argue that stimulation of long open-hole sections would have led to less advantageous stimulation outcomes. Prior to stimulation, the fractures in all intervals differed in near-wellbore transmissivities, but had similar slip tendencies (Figure XX). We argue that the low transmissive structures (i.e. S1 shear zones) in the same packer interval with initially high transmissivity structures (i.e. S3 shear zones) would not lead to a transmissivity enhancement of the low transmissive structures, because the highly-transmissive structures would have taken most of the injected fluid. This highlights the advantage of short injection intervals over long open hole injections. The reactivated stimulated shear zones differed initially in near-wellbore transmissivities, but had similar slip tendencies (Figure XX). We argue that the low transmissive structures (i.e. S1 shear zones) in the same packer interval with initially high transmissivity structures (i.e. S3 shear zones) would not have been reactivated for the stimulation flow rates used in this study. If they were in the same interval as structures with initially high transmissivity (i.e. S3 shear zones). This highlights the advantage of short injection intervals over long open hole injections.

The induced slip displacements imaged at the injection intervals occurred along single or multiple fractures. For the S1 stimulation intervals, one or two fractures tended to be activated, whereas the S3 stimulation interval HS4 showed evidence to suggest that more than 3 fractures had been reactivated (Figure 6 and Error! Reference source not found.). In all cases with multiple reactivated fractures, one fracture trace was dominant in the ATV image. These observations are well in agreement with the observations presented by Evans et al. (2005b) for the Soultz-sous Forêt stimulation projects, respectively. The direction of the slip induced on each of the planes of interval fractures was compared with the direction of maximum shear stress resolved on the planes using both the unperturbed and perturbed stress tensors. The results listed in Table 7 show that the angle varied between 28° and 45°, depending on which stress tensor was used. Generally, the perturbed stress tensor gave slightly smaller angles than the unperturbed tensor, although the angular misfit is still relatively large. We interpret this to indicate that the perturbed tensor does not adequately represent the degree of local stress field heterogeneity present in the stimulated zone. Generally, the predominant sense of slip observed on the fractures was right lateral strike slip, whereas both tensors predicted a thrusting component for the shear dislocation, which was not observed. Nevertheless, the overall shear sense is similar for the detected dislocations and for the predicted shear stress directions. The angular misfit might also be explained by transient local stress transfer between adjacent fractures during fluid injection at the injection well (Kakurina et al., 2019).

Table 7. Orientation of slip dislocation on the fractures estimated from the pre- and post stimulation ATV logs, and the maximum shear stresses resolved on the fractures from the unperturbed and perturbed stress tensor. All orientations are given as dip-direction/dip.

| Experiment | Slip direction | Perturbed Tensor |  | Misfit [°] |
|------------|----------------|------------------|---|------------|
| HS2        | 081/02         | 077/35           | 33 |            |
5.334 Complex flow field and mechanical rock mass responses

The monitored pressure signals indicated that the pressure diffused pre-dominantly along the target shear zones, similar to observations of stimulations at other EGS sites (e.g. at Soultz-sous-Forêt stimulation experiment [Evans et al., 2005a]). Because individual fractures adjacent associated with the target shear zone also often frequently intersected the same pressure monitoring intervals as the target shear zones, it was impossible to resolve which portion of the pressure signal propagated along the adjacent which individual fracture and/or within the target shear zone. We observed rapid penetration increases of high of higher-fluid pressures (i.e. on the order magnitude of the injection pressure) close to the injection pressure only during one S1- and one S3-stimulation (HS8 and HS5, respectively, Figure XXA5). During most experiments and the majority of monitoring intervals, the pressure signals are far below lower than the injection pressure and rarely exceeds 1 MPa (Figure XXA5). These findings are somewhat unexpected: According to [Murphy et al. (2004), among others, Murphy et al. (2004)] such an increased steepness in pressure fronts are indicative of demonstrate that fracture dilation during fluid injection leads to a non-linearity of the pressure diffusion field, and promotes higher fluid pressures and pressure increases further away from the borehole as linear pressure diffusion would produce. Most pressure signals in our case resemble a linear diffusive pressure field. Nonetheless, FBG strain measurements and P-Q curves (Figure 7) confirm that fracture dilation occurred during stimulation. The majority of our observed pressure perturbations detected at the monitoring locations were small in comparison to injection pressure, and did not obviously have a form suggestive of non-linear diffusion. Although this may explain high pressure observations away from the borehole, the majority of the pressure measurements are significantly lower than the injection pressure. Thus, our observations suggest that the flow field in the fault planes is heterogeneous and high--pressure signals away from the injection point may be associated-limited to with-flow channels. As shown by Krietsch et al. (2020) flow along channels may change during ongoing injections. However, there were clear evidence of fracture dilation during stimulation by the steepening P-Q curves at higher pressures (Figure 7) and by FBG strain signals (Figure 10 and Error! Reference source not found.). The S3-stimulation experiment gives rise to steeper pressure fronts, which promote more rapid penetration of higher fluid pressures into the rock mass than linear diffusion would imply. In the limit where the fracture faces become separated (i.e. lift-off), the diffusion front appears shock-like. We observed shock-like pressure fronts during two out of the six HS experiments; that observed the steep pressure front, highlighted that pressure diffusion occurs along channels that can reorient during ongoing injection (Krietsch et al., 2020). During this experiment the steep pressure front was observed subsequently in different monitoring intervals (i.e. first in PRP2-2 and later in PRP1-2, see Figure XX). We argue that the observed pressure perturbations indicate, that the non-linear diffusion field propagated inside the target shear zones along channels through the volume, surrounded by a diffusion field of lower non-linearity or even linear appearance. However, most This observation challenges common interpretations: conceptual models about of the hydro-mechanical rock mass responses to stimulation treatments, which are based on oversimplified fault geometries (i.e. single penny-shaped fracture) and pressure diffusion models (radially or spherically symmetric -diffusion models) (e.g. Cappa et al., 2019).

5.45 Hydromechanical rock mass responses

Based on the observed pressure response behavior of the pressure perturbation toup on shut-in, we divided our pressure signals into two different types. 1) The pressure monitoring intervals that cover the target shear zone often observed a delayed response to shut-in, indicating a diffusion-controlled pressure signal. 2) In contrast to this, pressure intervals that are outside of the target shear zone often responded immediately to shut-in (Figure A45 and Table A32). In some cases, this behavior was detected
further away from the injection location than the diffusion-controlled signals. Therefore, we propose that these signals are most likely associated with a poro-elastic far-field response, and represent the local fracture fluid pressure response to transient far-field stress changes and associated volumetric deformations during stimulation (Segall, 1989). Note that the poro-elastic effects occur predominantly during S3 stimulations.

Similarly, the observed deformation signals can loosely be divided into a near- and a far-field response. The deformations in the near-field to the injection in this zone reflect stress field changes, arising predominantly from effective normal stress reductions across fractures which can produce both normal opening and also relaxation of shear stress through slip (referred to in the literature as Coulomb failure stress change, Stein, 1999; Stein, 1999). The observed magnitude and sign (tension or compression) of these hydro-mechanical deformations strongly depend on the position and orientation of the strain sensor with respect to the stimulated zone. This interpretation is consistent with McClure and Horne (2014) and Rutledge et al. (2004) who note that deformations arising from mode I- and mode II & III-dislocations can occur simultaneously. It is noteworthy that the observed peak strain often by far exceed the permanent strain remaining after stimulation. This implies that the reversible component of fracture dislocation (a combination of normal and shear compliance) may be larger than the irreversible component (a combination of slip and shear dilatancy).

In the near-field, we also observed potential formation of new fractures that propagated away from the stimulated shear zone (Figure XX12). These initiated fractures are interpreted as splay cracks, tensile fractures, that formed due to tensile stress concentrations induced by shear dislocation along the irregularities (asperities) of the main shear zone (McClure and Horne, 2014), or by gradients of the slip magnitude.

In the far-field, i.e. outside this complex strain field, the vast majority of strain measurements show compression, regardless of orientation of the sensors. We interpret this to indicate that these consistent compressive signals in the far-field rock mass was produced by volumetric compression as is a consequence of the volumetric expansion of the volume in the near-field to the injection location (Segall and Fitzgerald, 1998). The tilt signals also belong to this category of far-field responses, as they do not directly measure fluid pressure induced effective normal stress changes and the corresponding elastic and inelastic consequences (e.g. fracture opening and closure, slip, etc.). Similarly, also the rapid pressure increases some distance away from injection may be related to far-field volumetric compression (Segall, 1989). This expansion is also indicative in the tilt signals, which were larger in magnitude during stimulation, compared to the permanent strain signals.

Far-field deformations occurred, similarly as for the hydraulic signals, due to the transient far-field stress changes and the coupled volumetric compression (Segall, 1989).
processes accompany, where the full complexity of injection-induced deformation styles are depicted on either side of the main fracture. Where the full complexity of injection-induced deformation styles are depicted on either side of the main fracture.

Figure 14. Schematic overview of hydro-mechanical mechanisms active within the ‘Primary stimulated zone’ about an injection interval. The shape of the Coulomb stress change lobes was modified after Karakostas et al. (2014) and Preisig et al. (2015).

While the aforementioned processes were mainly caused by slip and opening of fractures within the primary volume due to effective stress reduction, we also observed potential formation of new fractures that propagated away from the stimulated shear zone (see chapter 4.3.4). These initiated fractures are interpreted as splay cracks, that formed due to tensile stress concentrations induced by shear dislocation along the irregularities (asperities) of the main shear zone (McClure and Horne, 2014). It is also possible that the fractures initiate and locally propagate as mode-I fractures in local volumes where the minimum principal stress is low due to stress heterogeneity. However, due to significant irreversible strain magnitudes (Figure 13) we argue that the induced dislocation has a dominant mode II/III component.

Based on the sparse tilt data, we were not able to quantify the permanent induced changes within the test volume. Nevertheless, both tiltmeters indicated permanent deformations remained after each of the six experiments, although the reversible components of the tilt magnitudes were larger than the irreversible components (Figure 12 and Figure A8). This can be explained by transient expansion of the primary stimulated zone (Segall and Fitzgerald, 1998). Our data indicate that the poro-elastic far-field responses are at least of similar importance for the description of the transient far-field deformations in the secondary-affected zone as the slip-induced stress transfer (i.e., Coulomb failure stress change). Therefore, the poro-elastic response is an important deformation component to consider, but makes deformation field analysis more complex. To analyze the tilt data properly, the source mechanism needs to be modelled which is beyond the scope of this paper.

5.5. Stimulation effects volume

Based on hydraulic and mechanical observations we suggest two distinct zones around the injection point: 1) A complex near-field zone dominated by pressure diffusion, fracture opening, closure, shear slip and the formation of new fractures, and 2) a far-field zone dominated by stress transfer and the associated poro-elastic response (Figure 14). Thus, we subdivide the overall
effected rock volume into a primary stimulation zone which is close to the injection point and a secondary effected zone, that captures the far-field responses (Figure 13).

Figure 8. Schematic overview of hydro-mechanical mechanisms active within the "Primary stimulated zone" about an injection interval. The black arrows indicate fracture surface dislocations. The shape of the shear induced Coulomb stress change lobes was modified after Karakostas et al. (2014) and Preisig et al. (2015). For sake of simplicity, both the shear induced and the poro-elastic processes are drawn individually on either side of the main fracture and not superimposed. Karakostas et al. (2014) and Preisig et al. (2015).

The pressure monitoring observations indicate that the radial extent of the diffusion-controlled pressure changes extended up to 15 m from the injection point (Figures 14 & A6). Beyond this distance, between 15 m and ~22 m, the poro-elastic response was dominant. Due to the sparse monitoring, we cannot exclude that poro-elastic responses reach much further into the rock mass. Thus, the transition between the primary stimulated zone and the secondary effected zone, the two different responses, was taken as 15 m from injection point along the shear zone. This also corresponds to the transition between the so-called 'complex' strain field, which appeared to be directly affected by active fracture slip and normal opening (Poisson effect), and the compressional strain field, which decayed in magnitude with distance and appeared to be a far-field effect arising from the expansion of the primary stimulated zone. As for the pressure, we cannot determine the outer limit of the compressional strain field, because strains larger than the 0.1 µε detection limit were observed on all operating on the most remote FBG sensors during all stimulations.

We Based on our observations, the extent of the mechanically determined primary stimulation zone depend on the target shear zone properties, such as initial transmissivity and number of reactivated fractures. Strains larger than the 0.1 µε detection limit
were observed on all operating FBG sensors during all stimulations, even though some were up to 30 m from the injection points.

Figure 9.4. Comparison radial extension stimulated zones determined by hydraulics (H), deformation (M) and seismics (S). For the seismic observations, we distinguish between active seismics (velocity changes) and passive seismics (located seismic events). Note that we did not distinguish between measurement directions for the H and M estimates, as we did not have enough measurement locations to resolve it properly.

5.6 Comparison between hydro-mechanical observations and seismic responses

Doetsch et al. (2018b) and Schopper et al. (2020) used active seismic methods to analyze P-wave velocity changes that were observed during the stimulation experiments. They found that 4D seismic tomograms allowed the tracking of fluid pressure and strain evolution. Close to the injection location, a zone of a P-wave velocity decrease with decreasing P-wave velocities was detected that was surrounded by a zone of increased P-wave velocities. We propose that these distinct zones of P-wave velocity changes correspond to the primary stimulated and secondary affected zone, respectively.

Here, we consider the isoline marking a 0.1% of P-wave velocity decrease to denote the boundary between the two stimulated zones (Figure 15). The extent of the isoline boundary was measured parallel and normal to the target shear zone, and was found to be elongated along the target shear zone, which is consistent with the monitored pressure perturbations. In general, the extent of the zone with decreased P-wave velocities reached further from the injection point during S1-stimulations than during S3-stimulations, which is in agreement with strain field observations. Based on the active seismic observations, the primary stimulated zone can be characterized as being ellipsoidal, as inferred from the strain data.
Villiger et al. (2019, 2020) analyzed the induced seismicity induced during the stimulation. For details on the network sensitivity and its impact on the estimate of the seismically active zones, we refer to their article published in this journal. The localization accuracy of the seismic events is estimated at better than ±1.5 m. The radial extent of the clouds was found to be similar in both directions (i.e., parallel and normal) for S1 and S3 stimulations. However, more seismic events were detected along the target shear zone than normal to it. The seismic cloud has a smaller extent than the primary stimulation zone estimates from HM monitoring (Figure 8). Thus, it seems to underestimate the total volume that has been affected by the stimulation. Additionally, it fits publications by Duboeuf et al. (2017) and Guglielmi et al. (2015a), who showed that a large portion of the stimulation induced dislocation is aseismic. However, it disagrees with Cappa et al. (2019) who argued that seismicity is induced ahead of the hydraulically pressurized zone.

During the S1 stimulations, the peak injection pressures observed during the initial cycle, C1, were higher than the jacking pressures derived from C2 and C4 or the pressure limit observed during C3. This indicates that the pre-existing target fractures had a cohesive component of strength that had to be overcome in order to reopen the fracture. In contrast, this effect was not observed during S3 stimulations which suggests that the S3 shear zones were not so well healed. This fits with the observation that S3 shear zones had a higher initial transmissivity (Figure 8).

The pre-stimulation transmissivities of the S1 target structures are 1-2 orders of magnitude lower than those of the two S3 structures, the S3,1 zone of HS1 being the most transmissive at 1.2x10^-2 m²/s (Figure 8a). Following stimulation, the transmissivity values of all zones, both S1 and S3, lie with a factor of two of 10^-2 m²/s. Thus, the systematically greater increase in the transmissivity of the S1 zones primarily reflects their lower initial transmissivity. In contrast, the transmissivity of the S3 interval with the highest initial transmissivity (HS4), remained unchanged at 1.2x10^-2 m²/s. This may reflect an upper limit on shear induced irreversible transmissivity enhancement that is linked to the height of asperities along the fracture surface, as inferred at the lab scale by Lee and Cho (2002).

Figure 8 shows that jacking pressures of most intervals remained largely unchanged by the stimulation injections. Exceptions are the S1 interval HS1 (S1.3) whose jacking pressure declined from 5.6 MPa to 3.9 MPa, and the S3 interval HS5 whose jacking pressure increased from 6.9 MPa to the range 7.4-8.1 MPa (Table 1). Prior to the stimulations, the jacking pressures of the two S1 intervals were ~7 MPa, which is systematically higher than the values obtained for the S3 intervals, which ranged between 4.8 MPa and 5.6 MPa. The origin of this contrast between S1 and S2 intervals is uncertain. Jacking pressure is commonly taken as a measure of the stress normal to the fracture plane that is undergoing jacking, and so it is conceivable that the difference reflects the different orientations of S1 and S3 structures. However, both the perturbed and unperturbed stress tensors obtained from the stress characterization of Krietsch et al. (2018c) (Figure 3) imply that the S1 shear zones should have higher normal stresses acting across them than the S3 shear zones. This inconsistency is best explained as reflecting stress...
heterogeneity in the stimulated rock volume. The stress characterization of Krietsch et al. (2018c) found that the minimum principal stress dropped from 8 MPa to 3 MPa over an 8 m section of the SBH4 borehole as an S3 shear zone was approached. Indeed, the 3 MPa value was a jacking pressure obtained at the margins of the S3.1 structure. Since this is lower than the jacking pressures obtained across the S3.1 interval in the INJ1 borehole, we conclude that stress varies significantly along the structure, and that significant stress heterogeneity is present in the stimulated rock mass.

For all experiments, an injection pressure limit was observed during C3. Following Pearson, (1981), we interpret this pressure limit as lift-off of the target shear zone. Evans et al. (2005a) and McClure and Horne, (2014) noted that pressure limiting does not necessarily indicate pure mode I fracture propagation, as it can also occur when shearing occurs (mode II & III), as was observed at several injection points after stimulation. As seen in numerous laboratory experiments (e.g. Esaki et al., 1999; Lee and Cho, 2002), progressive reduction of the effective normal stress across a rough fracture that supports a shear load will eventually lead to slip, which will serve to partly relax the shear stress. This slip will give rise to dilation and damage of the surface, an attendant permeability increase. Continued reduction of effective normal stress can lead to further slip until all shear stress has been relaxed, although the dilation angle for subsequent slip increments generally decreases with net slip. Thus, the amount of dilation and attendant permanent permeability enhancement is limited. Increasing pressures to zero effective normal stress will lead to lift-off of the two sheared surfaces, and pressure limiting behavior.

The induced slip displacements imaged at the injection intervals occurred along single or multiple fractures. For the S1 stimulation intervals, one or two fractures tended to be activated, whereas the S3.1 stimulation interval HS4 showed evidence to suggest that more than 3 fractures had been reactivated (Figure 6 and Error! Reference source not found.). In all cases with multiple reactivated fractures, one fracture trace was dominant in the ATV image. These observations are well in agreement with the observations presented by Evans et al. (2005b) for the Soultz sous Forêt stimulation projects, respectively. The direction of the slip induced on each of the planes of interval fractures was compared with the direction of maximum shear stress resolved on the planes using both the unperturbed and perturbed stress tensors. The results listed in Table 7 show that the angle varied between 28° and 45°, depending on which stress tensor was used. Generally, the perturbed stress tensor gave slightly smaller angles than the unperturbed tensor, although the angular misfit is still relatively large. We interpret this to indicate that the perturbed tensor does not adequately represent the degree of local stress field heterogeneity present in the stimulated zone. Generally, the predominant sense of slip observed on the fractures was right lateral strike slip, whereas both tensors predicted a thrusting component for the shear dislocation, which was not observed. Nevertheless, the overall shear sense is similar for the detected dislocations and for the predicted shear stress directions. The angular misfit might also be explained by transient local stress transfer between adjacent fractures during fluid injection at the injection well (Kakurina et al., 2019).

Table 7. Orientation of slip dislocation on the fractures estimated from the pre- and post-stimulation ATV logs, and the maximum shear stresses resolved on the fractures from the unperturbed and perturbed stress tensor. All orientations are given as dip direction/dip.
5.2 Pressure propagation (Q2)

During all HS experiments, the highest fluid pressure perturbations were detected in monitoring intervals that cross the target shear zones. Note that fractures adjacent to the target shear zone also frequently intersect the same pressure monitoring intervals, which renders it impossible to resolve which portion of the pressure signal propagated along the adjacent fracture and within the target shear zone. In contrast, pressure monitoring intervals that do not cover the target shear zone register comparatively minor pressure perturbations of less than 1 MPa during the stimulation experiments. This, indicates that the pressure diffused predominantly along the target shear zones, similar to observations of stimulations at other EGS sites (e.g. at Soultz sous forêt stimulation experiment (Evans et al., 2005a)). Murphy et al., (2004) demonstrate that fracture dilation during fluid injection leads to non-linearity of the pressure diffusion field. This gives rise to steeper pressure fronts, which promote more rapid penetration of higher fluid pressures into the rock mass than linear diffusion would imply. In the limit where the fracture faces become separated (i.e. lift-off), the diffusion front appears shock-like. We observed shock-like pressure fronts during two out of the six HS experiments: one for injection into S1.0 zone during HS8 and one for S3.2 shear zone during HS5. Aside from these, all other pressure perturbations detected at the monitoring locations were small in comparison, and did not obviously have a form suggestive of non-linear diffusion. The reason for this is uncertain, although it may reflect the limited number of pressure monitoring points in the medium. Evidence of fracture dilation during stimulation was provided by the steepening curves of the Q-P diagrams at higher pressures (Figure 10 and Error! Reference source not found.) for all HS experiments, and so non-linear diffusion would be expected, at least along target structures. The fact that we observed shock-like pressure fronts only during two experiment might indicate that pressure diffusion was confined to channels within the target shear zone, and these were not sampled by our monitoring intervals. This can be inferred directly from the HS5 experiment during which a shock-like pressure front appeared first at PRP2.2 and at a later stage at PRP1.2, indicating propagation of the channelized pressure front (Krietsch et al., under review). Thus, we interpret that the non-linear diffusion field propagated along channels through the volume, surrounded by a diffusion field of lower non-linearity or linear appearance. Two different types of fracture fluid pressure signals were observed during stimulations. The pressure monitoring intervals that cover the target shear zone often observed a delayed response to shut in, indicating a diffusion controlled pressure signal. This type of signal belongs to the primary stimulated zone. On the other hand, pressure intervals that are outside of the target shear zone often responded immediately to shut in (Figure A1 and Table A2). In some cases, this behavior was detected further away from the injection location than the diffusion controlled signals. Therefore, we propose that these signals are poro-elastic in nature, and represent the local fracture fluid pressure response to transient far-field stress changes and associated volumetric deformations during stimulation. The different response behaviors are listed in Error! Reference source not found.. This poro-elastic far-field effect which occurs outside of the primary stimulated zone within the secondary effected zone has been described by Segall (1989) (see Figure 14).
5.3 Mechanical response and its link to the in-situ stress field (Q3)

Strains larger than the 0.1 με detection limit were observed on all operating FBG sensors during all stimulations, even though some were up to 30 m from the injection point. We observed a transition from a complex strain field to a zone with purely compressional strain that decayed in magnitude with distance. The distance between the transition zone and the injection location at the highest stimulation step (i.e., shut-in of C3) ranged between 12 m and 25 m. We interpret the complex strain field as corresponding to the primary-stimulated zone. The deformations in the zone reflect stress-field changes arising predominantly from effective normal stress reductions across fractures which can produce both normal opening and also relaxation of shear stress through slip (referred to in the literature as Coulomb failure stress change, Stein, 1999). The observed magnitude and sign (tension or compression) of these hydro-mechanical deformations strongly depend on the position and orientation of the strain sensor with respect to the stimulated zone. This interpretation is consistent with McClure and Horne (2014) and Rutledge et al. (2004) who note that deformations arising from mode I and mode II & III dislocations can occur simultaneously.

The influence of sensor orientation with respect to the target shear zone was highlighted in the complex strain zone, because: a) the majority of sensors oriented sub-normal to the target shear zone detected compressional strains, whereas b) sensors oriented sub-parallel to the target shear zone recorded extensional strains. This effect was predominant for the sensors that spanned only intact rock along their base length. We interpret these observations as reflecting compressive loading of the rock mass adjacent to the plane of the target shear zone by the normal opening of fractures. The extensile strain developed in the orthogonal direction we propose represent a Poisson effect. Taking the ratio of magnitudes of the aforementioned extensional and compression signals, we estimated an average rock mass Poisson’s ratio of $\nu_{\text{mean}} \approx 0.33$. Note that other hydro-mechanical responses are superimposed on this Poisson effect in the complex strain field.

Outside this complex strain field, the vast majority of strain measurements show compression, regardless of orientation of the sensors. We interpret this to indicate that the rock mass was compressed as a consequence of the volumetric expansion of the primary-stimulated zone. The relative absence of extension suggests that the geometry of the primary-stimulated zone approximates a flattened prolate spheroid: for otherwise extensile strain would occur sub-parallel to the plane of the target structure (Segall and Fitzgerald, 1998). This secondary affected zone occurred, similarly as for the hydraulic signals, due to the transient far-field stress changes and the coupled volumetric compression (Segall, 1989).

While the aforementioned processes were mainly caused by slip and opening of fractures within the primary volume due to effective stress reduction, we also observed potential formation of new fractures that propagated away from the stimulated shear zone (see chapter 4.3.4). These initiated fractures are interpreted as splay cracks, that formed due to tensile stress concentrations induced by shear dislocation along the irregularities (asperities) of the main shear zone (McClure and Horne, 2014). It is also possible that the fractures initiate and locally propagate as mode I fractures in local volumes where the minimum principal stress is low due to stress heterogeneity. However, due to significant irreversible strain magnitudes (Figure 12) we argue that the induced dislocation has a dominant mode II/III component.

Based on the sparse tilt data, we were not able to quantify the permanent induced changes within the test volume. Nevertheless, both tiltmeters indicated permanent deformations remained after each of the six experiments, although the reversible components of the tilt magnitudes were larger than the irreversible components (Figure 12 and Figure A8). This can be explained by transient expansion of the primary-stimulated zone (Segall and Fitzgerald, 1998). Our data indicate that the pore-elastic far-field responses are at least of similar importance for the description of the transient far-field deformations in the secondary affected zone as the slip-induced stress transfer (i.e., Coulomb failure stress change). Therefore, the pore-elastic response is an important deformation component to consider, but makes deformation field analysis more complex. To analyze the tilt data properly, the source mechanism needs to be modeled which is beyond the scope of this paper.
Figure 14. Schematic overview of hydro-mechanical mechanisms active within the ‘Primary stimulated zone’ about an injection interval. The shape of the Coulomb stress change lobes was modified after Karakostas et al. (2014) and Preisig et al. (2015).

5.4 Extent of volume affected by the stimulation (Q4)

To estimate the total volume affected by the stimulation during the six stimulation experiments, we combined the observations presented here from the hydraulic (i.e. pressure signals) and mechanical (i.e. strain signals) responses, and integrate the active seismic observations made by Doetsch et al. (2018), Schopper et al. (under review) and passive seismic observations by (Villiger et al., 2019). The pressure monitoring observations indicate that the radial extent of the diffusion-controlled pressure changes extended up to 15 m from the injection point. Beyond this distance, between 15 m and 22 m, the poro-elastic response was dominant. Thus, the transition between the primary stimulated zone and the secondary affected zone was taken as 15 m from injection point. This also corresponds to the transition between the so-called ‘complex’ strain field, which appeared to be directly affected by active fracture slip and normal opening (Poisson effect), and the compressional strain field, which decayed in magnitude with distance and appeared to be a far-field effect arising from the expansion of the primary stimulated zone. The extent of the mechanically determined primary stimulation zone depend on the target shear zone properties, such as initial transmissivity and number of reactivated fractures.

Doetsch et al. (2018) and Schopper et al. (under review) used active seismic methods to analyze P-wave velocity changes that were observed during the stimulation experiments. They found that 4D seismic tomograms allowed the tracking of fluid pressure and strain evolution. Close to the injection location, a zone a P-wave velocity decrease was detected that was surrounded by zone of P-wave velocity increase. We propose that the zone of P-wave velocity decrease corresponds to the primary stimulated zone, where deformations are induced by effective normal stress reductions across fractures and slip-induced stress redistributions, and the outer zone of P-wave velocity increase is associated with the secondary affected zone.
Here, we consider the isoline marking the 0.1% of P-wave velocity decrease to denote the boundary between the two stimulated zones (Figure 15). The extent of the isoline was measured parallel and normal to the target shear zone, and was found to be elongated along the target shear zone. This agrees with the observed fluid pressure increases along the shear zone compared to other directions. In general, the P-wave velocity drop reached further from the injection point during S1-stimulations than during S3-stimulations. This is similar to the observations made for the above described (see Section 4.3.2) transition zone between the different strain fields.

Figure 15. Comparison between active and passive seismic observations during S1(a) and S3(b) stimulations in map view. The extent of the active seismic velocity change was traced with the 0.1% isoline. This figure was modified after (Schopfer et al., under review; Villiger et al., 2019)

Figure 15 also shows located seismic events for the HS2 (S1.2) and HS4 (S3.1) stimulations. The localization accuracy of the seismic events is estimated as ±1.5 m (see Villiger et al. (2019) for details of the microseismic observations). As a general observation, the stimulation of S1-zones tended to produce more compact distributions. As was done for the active seismic analysis, we measured the extent of the seismic clouds parallel and normal to the target shear zones. The radial extent of the clouds was found to be similar for both shear zone types and both measured directions (i.e., parallel and normal). However, more seismic events were detected along the target shear zone than normal to it.

Figure 16 summarizes the different radial extents of the stimulation affected volume based on the different measurement methods. The HM observations underline the existence of a primary stimulated and secondary affected zone. The onset of poro-elastic effects in the pressure monitoring data fit the transition from ‘complex’ strain field to compressional strain field. Note that the poro-elastic effects occur predominantly during S3-stimulations. The seismic cloud has a smaller extent than the primary stimulation zone estimated from HM monitoring. Thus, it seems to underestimate the total volume that has been affected by the stimulation. Additionally, Duboeuf et al. (2017) and Guglielmi et al. (2015) stated that a large portion of the stimulation induced dislocation is aseismic. Therefore, we distinguish between the zone that was affected by the stimulation (i.e., including poro-elastic far field effects) and the zone of stimulation induced permanent displacements. The active seismics estimated an extent of the primary stimulated zone parallel to the target shear zone that is similar to the HM-based estimations. Based on the active seismic observations, the primary stimulated zone can be characterized as being ellipsoidal.
Figure 16. Comparison radial extension stimulated zones determined by hydraulics (H), deformation (M) and seismics (S). For the seismic observations, we distinguish between active seismics (velocity changes) and passive seismics (located seismic events). Note that we did not distinguish between measurement directions for the H and M estimates, as we did not have enough measurement locations to resolve it properly.

6. Conclusions

The six decameter-scale hydraulic shearing experiments conducted at 480 m depth at the Grimsel Test Site, Switzerland have revealed exceptional insights into the seismo-hydro-mechanical responses of the crystalline rock mass and fractures to high-rate injections. This was facilitated by a dense array of instrumentation installed in the test volume that included seismometers, pore-pressure- and strain-monitoring boreholes, and inclinometers installed along tunnels. The test volume was cut by two sets of fracture zones, denoted S1 and S3, that had different orientations and different ages.

Data acquired with the comprehensive monitoring system in this study demonstrate the complexity of fluid flow and coupled deformations during hydraulic stimulations. For the interpretation it has to be considered, that the hydraulic and mechanical data were not acquired at the same locations and thus do not directly capture couplings between the mechanical and the hydraulic response at the same location. Due to the spatial coverage of monitoring sensors it is likely that not all experiments have the same spatial data coverage. Further, the total size of the rock volume affected by the stimulation was not captured since the most remote strain sensors indicate deformations.

Two different shearzone sets (S1 and S3) were the target of the stimulation injections. The key results of the experiments can be summarized as follows:

- All six injection intervals were stimulated to a similar level in near-wellbore transmissivity, implying that initially low transmissive structures were stimulated more efficiently, than structures of enhanced initial transmissivity.
- The jacking pressures are low compared to minimum principal stress magnitudes determined in the relatively undisturbed rock mass immediately to the south and almost certainly reflects strong stress heterogeneity in the study volume.
- Systematically lower initial transmissivities by up to 3 orders of magnitude were observed for all four of the intervals that cut S1 target structures, with one S3 interval having a high transmissivity of $10^{-7}$ m$^2$/s. Following the stimulation, all five other transmissivities were increased to this level. Evidence of shearing was seen on fractures cutting four of the six intervals, but could not be linked to the transmissivity increases as the normal component of dislocation was not estimated.
- Systematically higher initial jacking pressures of ~7 MPa were found for the two S3 intervals, the values for S1 intervals ranging between 4.8 and 5.6 MPa. With one exception, jacking pressures were unchanged by the stimulations. The measured jacking pressures are low compared to minimum principal stress magnitudes determined in the relatively undisturbed rock mass immediately to the south and almost certainly reflects strong stress heterogeneity in the decameter-scale test volume.

- During the stimulation injections, hydraulic pressure propagated heterogeneously through the target shear zone up to a distance of approximately 15 m distance to injection point. Shock-like rapid relatively large pressure increases in pressure fronts perturbation to relatively large magnitudes observed during two experiments are interpreted as non-linear pressure diffusion field along fully-dilated (i.e. wall separation) channels within the target structures. All other pressure perturbations that had delayed arrival times had markedly lower amplitudes, and could have involved linear or non-linear diffusion. Another class of pressure perturbation seen at some measurement points outside the target zone were coincident with changes in injection, and are believed to be poro-elastic in nature.

- All operational FBG strain sensors throughout the study volume detected significant signals during all experiments. Generally, the signals had both reversible transient and permanent strain components, the former being larger than the latter. Strains measured at distances less than 15 m to the injection points were a complex mix of compression and extension, whereas only compression was measured beyond, the magnitude diminishing with distance. The complex near-field zone is believed to correspond to an active zone affected by local stress perturbations arising from reductions of effective normal stress reductions along fractures due to a diffusion-controlled pressure field leading to normal and shear dislocation along fractures, normal and shear dislocation of fractures in the target structures, whereas the more distant compression is taken to be the response of the surrounding medium to the volume increase of the active near-field volume and is a purely poro-elastic far-field effect in nature.

- Direct evidence of mode 1 fracture propagation was given by the sudden and pronounced extension of one FBG sensor during a stimulation, with simultaneous compression of neighboring sensors. This is interpreted to reflect the formation of a wing crack from the end of a slip patch on the target structure. Stress communication between different fractures is observed, as strong fracture opening leads to compression of adjacent fractures and the rock mass.

- The dimensions of the microseismic cloud is smaller than the dimensions of the primary stimulated zone as derived from the pressure and strain monitoring systems. We propose that this is a better measure of the stimulated volume than the seismicity cloud. The latter is also also more-in accord with the active seismic-volume of transient seismic velocity decreases as inferred from 4D seismic tomography, and is our preferred measure of the stimulated volume.

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Figure A1. a) Structure logs of injection intervals, b) structure logs of strain monitoring boreholes with sensor locations, and c) customized packer system in the PRP boreholes, including open intervals, concrete and resin sections. Note that the actual packers surrounding the open intervals are not shown here, due to their length of only 20 cm.
Figure A2. Injection protocols for all experiments. The tests are in chronological order.
Figure A3. P-Q diagrams for all conducted HS experiments.

![P-Q diagrams for all conducted HS experiments](image)

Figure A3.4. Difference plots from ATV logs. Logs are in chronological order.
Figure A4A5. Pressure perturbation time series for all monitoring intervals. The shut-in moments are marked as vertical lines. Note that all intervals were vented after a period of shut-in.
Figure A5-A6. Pressure signals at the moment of shut-in after C3 with respect to radial distance to injection point.

Figure A6-A7. Strain along borehole axis picked transient at the end of injection cycle 2 and 3, and the permanent strain signal after the experiment.
Figure A7-A8 Strain signals with respect to distance to injection point for all experiments. The variable and compressional strain fields are labelled during C3.
Figure A89. Inclinometer data for each of the six experiments. The upper panel shows the tilt time series for both experiments with the injection periods marked by the shaded vertical bands. The lower panel shows a horizontal section through the study volume at the level of the tunnels showing the shear-zones and tiltmeter T1 and T2 positions. The x- and y-axes of the tilt data are indicated on T2. Changes in the downward-oriented normal vector of the tunnel floor at T1 and T2 are shown in the lower-hemisphere plots at the left of the frames.
Table A14. Locations and packed-off length of monitoring intervals in the INJ boreholes during the stimulation experiments. The fracture zones that intersect the interval are given in the adjacent column. Monitoring intervals that include the interval undergoing injection in the other INJ borehole are marked with (*).

| Expt. (Zone) | INJ1-1 Depth (m) | Zones | INJ1-2 Depth (m) | Zones | INJ2-1 Depth (m) | Zones | INJ2-2 Depth (m) | Zones |
|--------------|------------------|-------|------------------|-------|------------------|-------|------------------|-------|
| HS2 (S1.2)   | 41.0 – 45.0      | $S_{1.3}$ | 38.0 – 40.0      | $S_{1.2}$ | 36.2 – 45.0      | $S_{1.3}$ | 31.5 – 35.2      | $S_{1.2}$ |
| HS4 (S3.1)   | 29.2 – 45.0      | $S_{3.2}, S_{1.1}$, $S_{1.2}, S_{1.3}$ | 27.2 – 28.2 | $S_{3.1}$ | 28.3 – 45.0      | $S_{1.1}, S_{1.2}$, $S_{1.3}$ | 19.6 – 27.3 | $S_{1.0}, S_{3.1}$, $S_{3.2}$ |
| HS5 (S3.2)   | 33.2 – 45.0      | $S_{1.1}, S_{1.2}$, $S_{1.3}$ | 31.2 – 32.2 | $S_{3.2}$ | 28.3 – 45.0      | $S_{1.1}, S_{1.2}$, $S_{1.3}$ | 19.6 – 27.3 | $S_{1.0}, S_{3.1}$, $S_{3.2}$ |
| HS3 (S1.1)   | 36.3 – 45.0      | $S_{1.2}, S_{1.3}$ | 34.3 – 35.3      | $S_{1.1}$ | 28.3 – 45.0      | $S_{1.1}, S_{1.2}$, $S_{1.3}$ | 19.6 – 27.3 | $S_{1.0}, S_{3.1}$, $S_{3.2}$ |
| HS8 (S1.0)   | 24.0 – 45.0      | $S_{3.1}, S_{3.2}$, $S_{1.1}, S_{1.2}$, $S_{1.3}$ | 22.0 – 23.0 | $S_{1.0}$ | 19.6 – 45.0      | $S_{1.0}, S_{1.1}$, $S_{1.2}, S_{1.3}$, $S_{3.1}, S_{3.2}$ | 5.9 – 18.6 | $S_{1.0}, S_{3.1}$, $S_{3.2}$ |
| HS1 (S1.3)   | 30.7 – 45.0      | $S_{1.3}$ | 27.0 – 39.7      | $S_{1.1}, S_{1.2}$, $S_{3.1}, S_{3.2}$ | 41.75 – 45.0 | - | 39.75 – 40.75 (* | $S_{1.3}$ |

Table A23. Radial distances between the midpoints of the pressure monitoring intervals and the injection interval for all HS tests. The “OBS” intervals represent the inactive INJ borehole.

| Interval      | HS2 | HS4 | HS5 | HS3 | HS8 | HS1 |
|---------------|-----|-----|-----|-----|-----|-----|
| PRP1_1        | 11.9| 19.6| 16.4| 14.2| 24.1| 15.2|
| PRP1_2        | 11.79| 7.8 | 7.7 | 8.9 | 10.6| 8.2 |
| PRP1_3        | 16.3| 7.1 | 9.9 | 12.5| 6.2 | 11.2|
| PRP2_1        | 9.2 | 16.7| 13.4| 11.2| 21.3| 12.2|
| PRP2_2        | 16.0| 6.6 | 9.4 | 12.1| 5.5 | 10.8|
| PRP3_1        | 20.2| 16.2| 16.9| 18.0| 16.8| 17.4|
| PRP3_2        | 25.0| 16.0| 18.9| 21.4| 13.1| 20.2|
| OBS_2         | 14.7| 10.7| 13.1| 15.4| 11.8| 16.0|
| OBS_1         | 15.3| 15.7| 14.3| 14.0| 15.0| 18.1|
| INJ-1         | 4.0 | 9.4 | 7.4 | 5.9 | 12.0| 9.5 |
Table A32. Response behavior of the pressure monitoring intervals at shut-in of injection cycle 3 for all HS tests. This table also makes the link to the shear zone targeted during each stimulation and covered by the monitoring intervals (both in bold). The responses are classified as immediate (in case of an immediate response to shut-in) and delayed (in case of a delayed response to shut-in). The underlined responses are from the intervals that covered the exact targeted shear zones. The ones in italic are taken from the intervals that do not cover the targeted shear zones.

| Stimulated shear zone type | S1 | S3 | S3 | S1 | S1 | S1 |
|----------------------------|----|----|----|----|----|----|
| Covered shear zone type    | Interval | HS2 | HS4 | HS5 | HS3 | HS8 | HS1 |
| S1 PRP1-1                  | immediate | immediate | - | immediate | delayed | immediate |
| S3 PRP1-2                  | immediate | delayed | delayed | immediate | immediate | immediate |
| S3 PRP1-3                  | - | delayed | delayed | delayed | immediate | - |
| S1 PRP2-1                  | immediate | immediate | immediate | immediate | immediate | immediate |
| S3 PRP2-2                  | immediate | delayed | delayed | delayed | immediate | immediate |
| S1 PRP3-1                  | - | - | immediate | immediate | immediate | delayed |
| S3 PRP3-2                  | - | delayed | delayed | delayed | delayed | immediate |
| Depends on test INJ2-2     | delayed | delayed | delayed | delayed | immediate |
| Depends on test INJ2-1     | - | immediate | immediate | - | immediate | - |
| Depends on test INJ1-2     | - | - | - | - | - | delayed |
| Depends on test INJ1-1     | - | immediate | delayed | delayed | immediate | - |