State-Dependent Relay Channel with Private Messages with Partial Causal and Non-Causal Channel State Information

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Abstract—In this paper, we introduce a discrete memoryless State-Dependent Relay Channel with Private Messages (SD-RCPM) as a generalization of the state-dependent relay channel. We investigate two main cases: SD-RCPM with non-causal Channel State Information (CSI), and SD-RCPM with causal CSI. In each case, it is assumed that partial CSI is available at the source and relay. For non-causal case, we establish an achievable rate region using Gel’fand-Pinsker type coding scheme at the nodes informed of CSI, and Compress-and-Forward (CF) scheme at the relay. Using Shannon’s strategy and CF scheme, an achievable rate region for causal case is obtained. As an example, the Gaussian version of SD-RCPM is considered, and an achievable rate region for Gaussian SD-RCPM with non-causal perfect CSI only at the source, is derived. Providing numerical examples, we illustrate the comparison between achievable rate regions derived using CF and Decode-and-Forward (DF) schemes.

I. INTRODUCTION

The Relay Channel (RC) [1], is a communication system in which a message is transmitted from the source to the destination with the help of a relay. The Partially Cooperative Relay Broadcast Channel (PC-RBC) studied in [2], [3], is a generalization of RC in which the source node also sends a private message intended for the relay node. Therefore, in this channel the relay is also a sink of data. The Relay Channel with Private Messages (RCPM) studied in [4], is a generalization of RC in which the relay is both a source and a sink of data. Hence, RCPM can be regarded as a generalization of PC-RBC wherein the relay is also a source of data and sends a private message to the destination. The RCPM model fits networks in which dedicated relays are not available, and relaying is performed by the nodes that each node is a source and a sink of data.

In this paper, we assume that RCPM is controlled by random parameters called channel state and we refer to it as State-Dependent Relay Channel with Private Messages (SD-RCPM). Recently, state-dependent channels have attracted considerable attention. In these channels, the information on the channel state can be known to the terminals causally or non-causally. For a comprehensive overview on state-dependent channels see [5], [6].

Among state-dependent multiuser models, some results have also been obtained for the State-Dependent RC (SD-RC) and State-Dependent PC-RBC (SD-PCRBC) [7]-[14] for Gaussian and discrete memoryless cases with causal or non-causal Channel State Information (CSI). Since RCPM can be regarded as a generalization of RC and PC-RBC, the SD-RCPM can be regarded as a generalization of SD-RC and SD-PCRBC.

In this paper, after introducing SD-RCPM, we investigate two main cases: SD-RCPM with non-causal CSI, and SD-RCPM with causal CSI. In each case, we investigate SD-RCPM with partial CSI at the source and the relay. As special cases it includes three different situations in which perfect CSI is available i) only at the source, ii) only at the relay, and iii) both at the source and the relay. Situations i and ii called asymmetric scenarios refer to the cases in which CSI is available only at some of the nodes. Situation iii is called the symmetric scenario. In fact in the asymmetric cases, it is assumed that only some of the nodes have the ability or the permission to know CSI. In [11], [13], unlike most of the previous works on SD-RC, we have used CF strategy [1] for relaying in SD-RC, and showed that there exist cases (similar to the classic RC) for which CF scheme achieves rates higher than those derived using DF strategy [1] for SD-RC with asymmetric CSI in [8], [9]. Now, in this paper we also focus on CF relaying scheme. In fact similar to what is shown for classic RC, the CF and DF are both able to outperform each other under different conditions. In DF (or Partial DF) scheme, the relay has to decode the whole message intended for the destination (or a part of it). Therefore, when only the source is informed of CSI, due to lack of knowledge of CSI at the relay, the rate loss is caused at the relay as shown in [15]. On the other hand, when only the relay is informed of CSI, the source cannot use CSI and cannot conceive what the relay exactly sends, and as shown in [8], this causes a loss in the coherence gain which is expected to be achieved by DF relaying. However, DF based rate can be optimal for certain cases as shown recently in [8]. [15]. On the other hand, in CF strategy independent codebooks are exploited at the source and relay, and the relay simply compresses its received signal. Also, CF outperforms DF for relaying the message intended for the destination, when the link between the source and relay is worse than the direct link.

Here, for the non-causal situation, we derive an inner bound on the capacity region (achievable rate region) of SD-RCPM based on using Gel’fand-Pinsker (GP) type coding [16] at the nodes informed of CSI, and using CF scheme at the relay. We derive an achievable rate region for SD-RCPM in the causal case using Shannon’s strategy [17] and CF scheme. We show that our result for the causal case can be considered as a special case of non-causal CSI, and this is in analogy with the relation between the capacity of the single user channel with causal CSI [17], and its
non-causal counterpart [16]. We also show that our results sub-
sume the results in [11], [13] which are for SD-RC, and the result in [4] which is for RCPM (state-independent), as special cases. As an example, we consider the Gaussian version of SD-RCPM with additive independent distributed (i.i.d) state process, and obtain achievable rate region for the case where perfect CSI is available non-causally only at the source. We also illustrate the trade-off between relayed message rate and private messages rates for this channel. Since there is no available achievable region for SD-RCPM which is established based on DF scheme, to compare DF and CF strategies for this channel, we consider a scenario in which the relay sends no private message to the destination (i.e., SD-RCPM reduces to SD-PCBC). For this scenario, we make a comparison between our CF based derived achievable region and the rate region derived in [13] based on DF.

The rest of the paper is organized as follows. Section II introduces SD-RCPM channel model and notations. Section III investigates SD-RCPM channel with non-causal CSI. The causal case is considered in section IV and finally, Section V contains Gaussian examples.

II. PRELIMINARIES AND DEFINITIONS

In this paper, upper case letters (e.g., X) are used to denote Random Variables (RVs) while their realizations are denoted by lower case letters (e.g., x). $X_i^j$ indicates the sequence of RVs $(X_i, X_{i+1}, \ldots, X_j)$, and for brevity, $X^j$ is used instead of $X_j^j$. $p_X(x)$ denotes the probability mass function (p.m.f) of X on a set $\mathcal{X}$, where occasionally subscript X is omitted. $A^n_Y(X, Y)$ denotes the set of the strongly $\epsilon$-typical length-n sequences on $p(x, y)$, which is abbreviated by $A^n_Y$ if it is clear from the context.

A discrete memoryless SD-RCPM is denoted by $((X_1 \times X_2, 2, 2), \mathbf{y})$ in which the channel state is $(y_1, y_2, y_3)$. For $p(y_2, y_3|x_1, x_2)$ is the probability transition function. $X_1 \in \mathcal{X}_1$ and $X_2 \in \mathcal{X}_2$ are the source and relay inputs, respectively. $Y_2 \in \mathcal{Y}_2$ and $Y_3 \in \mathcal{Y}_3$ are respectively the outputs at the relay and destination, and $s$ denotes the channel state. We assume that the source and relay know an i.i.d noisy version of states (i.e., partial CSI) drawn by $p(s, s_1, s_2)$ where $s \in S, s_1 \in S_1$ and $s_2 \in S_2$. The CSI at the source (or the relay) is perfect if $s_1, (or s_2, j)$ equals $s_j$ for $1 \leq j \leq n$.

A $((2^nR_{12}, 2^nR_{23}, 2^nR_{13}), n)$ code for SD-RCPM consists of three message sets $W_{12} = \{1, \ldots, 2^nR_{12}\}$ (source to relay private message), $W_{23} = \{1, \ldots, 2^nR_{23}\}$ (relay to destination private message), and $W_{13} = \{1, \ldots, 2^nR_{13}\}$ (sent from the source to the destination with the help of the relay), where independent messages $W_{12}, W_{23}$ and $W_{13}$ are uniformly distributed over respective sets. It also consists of an encoder at the source and a set of encoding functions at the relay where for non-causal CSI are defined as $\phi_{1j} : W_{12} \times X_1 \times S_i \rightarrow X_i^n$, and $\phi_{2j} : Y_{23}^{j-1} \times W_{23} \times S_i \rightarrow X_2^n$ for $j = 1, \ldots, n$, respectively. For causal CSI these encoders are respectively defined by $\phi_{1j} : W_{12} \times X_1 \times S_i \rightarrow X_1^n$ and $\phi_{2j} : Y_{23}^{j-1} \times W_{23} \times S_i \rightarrow X_2^n$, for $j = 1, \ldots, n$. Two decoding functions $d_1$ and $d_2$ at the relay and destination are defined respectively as: $d_1 : Y_{23}^n \times S_j \rightarrow W_{12}$ and $d_2 : Y_{23}^n \rightarrow W_{23} \times X_2^n$. Note that, for decoding at the relay there is no difference between causal and non-causal cases since the relay can wait until the end of the block, before decoding. The average probability of error ($P_e^n$) is defined as the one for RCPM in [4]. A rate tuple $(R_{12}, R_{23}, R_{13})$ is said to be achievable for SD-RCPM if the channel state $\sigma$, there exists a sequence of codes $((2^nR_{12}, 2^nR_{23}, 2^nR_{13}), n)$ with $P_e^n \rightarrow 0$ as $n \rightarrow \infty$.

III. SD-RCPM WITH NON-CAUSAL CSI

In this section, we consider SD-RCPM with partial non-causal CSI at the source and the relay. In the following, the achievable rate region of this channel is derived.

**Theorem 1:** In the discrete memoryless SD-RCPM with partial non-causal CSI $S_1$ and $S_2$ respectively at the source and the relay, the nonnegative rate tuples $(R_{12}, R_{23}, R_{13})$ denoted as $R_1$, satisfying:

$$ R_{13} < I(T_1; Y_2, Y_3|K_2, Q_2) - I(T_1; S_1) $$

(1)

$$ R_{12} < I(T_2; Y_2, S_2|K_2, Q_2) - I(T_2; S_2) $$

(2)

$$ R_{13} + R_{12} < I(T_1; Y_2, Y_3|K_2, Q_2) + I(T_2; Y_2, S_2|K_2, Q_2) - I(T_1; S_1) - I(T_2; S_1) - I(T_1; T_2|S_1, S_2) $$

(3)

$$ R_{23} < I(K_2; Y_3) - I(K_2; S_2), $$

(4)

subject to the constraint

$$ I(Y_2; Y_3, T_2|K_2, Q_2, Y_3) \leq I(Q_2; Y_3|K_2) - I(Q_2; S_2|K_2), $$

(5)

are achievable for any joint p.m.f of the form

$$ p(s, s_1, s_2, k_2, q_2, t_1, t_2, x_1, x_2, y_2, y_3) = p(s, s_1, s_2)p(k_2|s_2)p(q_2|k_2, s_2)p(x_2|q_2, k_2, s_2)p(t_1, t_2|s_1) $$

$$ \times p(x_1|t_1, t_2, s_1)p(y_2, y_3|x_1, x_2, s)p(y_2|q_2, k_2, s_2, s_2). $$

(6)

**Remark 1:** The relay which is the middle terminal, knows CSI $S_2$. Hence, the relay acting as a decoder of the source-relay link and based on its knowledge of CSI, tries to cancel the effect of the channel state on $y_2$. Moreover, it can compress $S_2$ (besides $Y_2$) and sends it to destination to provide it with a partial CSI, when needed. For example, if $Y_2 = \emptyset$ the relay can compress only $S_2$ and sends it to the destination, and so the destination can use this partial CSI. To achieve these two goals, in general, we assume that in (6) $y_2$ is conditioned on $s_2$. Moreover, $T_2$ which is decoded at the relay is not decoded at the destination ($T_2$ carries source to relay private message), and hence can be regarded as a channel state for destination. So, $T_2$ can be treated similar to $S_2$, and we assume that in (6) $y_2$ is also conditioned on $t_2$. Note that, by these assumptions, the case where the relay only compresses $Y_2$ is also included.

**Outline of the Proof:** The proof is based on random coding scheme which combines GP-type coding at the source and relay, and CF strategy. More precisely, since the source is informed of CSI $S_1$, the coding scheme which extends Marton’s region to the state-dependent Broadcast Channel (BC) with non-causal CSI at Transmitter (CSIT) [13] is used at the source. The relay decoder uses $S_2$ as part of channel output. Moreover, the relay encoder uses CF and since it is informed of $S_2$, it uses GP coding to send the index of the compressed signal which is superimposed on the relay-destination private message. The auxiliary RV $K_2$ stands for private message sent from the relay to destination using GP coding, and $Q_2$ represents the bin of compressed signal’s index. Now, consider a block Markov encoding scheme where a sequence of $B - 1$ messages ($W_{12}, W_{23}, W_{13}$) for $i = 1, \ldots, B - 1$ is transmitted in $B$ blocks, each of $n$ symbols. As $B \rightarrow \infty$, the rate tuple $(R_{12}, R_{23}, R_{13})$ $\times (B - 1)$ approaches $(R_{12}, R_{23}, R_{13})$.

**Random Coding:** For any joint p.m.f defined in (6), generate $2^n(R_{12}+R_{13})$ i.i.d codewords $\mathbf{w}_{13}(k)$ where $w_{13} \in [1, 2^nR_{13}]$ and $k \in [1, 2^nR_{13}]$. Generate $2^n(R_{12}+R_{13})$ i.i.d $t_{13}(w_{12}, l)$, $w_{12} \in [1, 2^nR_{12}], l \in [1, 2^nR_{13}]$. Generate $2^n(R_{23}+R_{13})$ i.i.d codewords $k_{23}(w_{23}, m)$, $w_{23} \in [1, 2^nR_{23}], m \in [1, 2^nR_{23}]$. For each $k_{23}(w_{23}, m)$, generate $2^n(R_{23}+R_{13})$ i.i.d $q_{23}(x, t, r|w_{23}, m)$.
$t \in [1, 2^{nR_z}]$, $r \in [1, 2^{nR_z}]$. In codewords $t_1^n$, $t_2^n$, $k_2^n$ and $q_2^n$, the first index represents the bin, and the second one indexes the sequence within the particular bin. For each $k_2^n(w_{23}, m)$ and $q_2^n(t, r|w_{23}, m)$, generate $2^{nR_z}$ i.i.d $y_2^n(z|t, r, w_{23}, m)$ each with probability $\prod_{n=1}^{n}p(y_2^n|q_2^n, k_2^n)$. Randomly partition the set \{1, $2^{nR_z}$\} into $2^{nR_z}$ bins defined as $B(t)$.

**Encoding (at the beginning of block i):** We assume that the CSI $S_1^n$ and $S_2^n$ in each block are non-causally known to the source and the relay, respectively. Then:

1) Let $(w_{13,i}, w_{12,i})$ be the new message pair to be sent from the source in block $i$. The source looks for the smallest $k \in [1, 2^{nR_z}]$ and $l \in [1, 2^{nR_z}]$, such that $(t_1^n(w_{13,i}, k), t_2^n(w_{12,i}, l), s_2^n(i)) \in A_1^n$. Denote this $k$ and $l$ with $k_i$ and $l_i$, respectively. If no such indices $k$ and $l$ exist, an encoding error is declared. There exist such indices $k_i$ and $l_i$ with arbitrarily high probability, if $n$ is large enough and

$$R_1' > I(T_1; S_1)$$

(7)

$$R_2' > I(T_2; S_1)$$

(8)

$$R_{13} + R_2' > I(T_1; S_1) + I(T_2; S_1) + I(T_1; T_2|S_1)$$

(9)

Note that (7) and (9) can be showed using techniques similar to that in [19]-[20] (mutual covering lemma).

Then, the source transmits i.i.d $x_1^n(w_{13,i}, w_{12,i})$ drawn according to $p(x_1^n|t_1^n, r_1^n, s_2^n)$.

2) Knowing $s_2^n(i)$, the relay searches for the smallest $m \in [1, 2^{nR_z}]$ such that $(k_2^n(w_{23}, m), s_2^n(i)) \in A_2^n$. Denote this $m$ as $m_i$. If no such index $m$ exists, an encoding error is declared. Based on covering lemma, for sufficiently large $n$ such an index $m_i$ can be found with arbitrarily high probability, if

$$R_{23}' \geq I(K_2; S_2)$$

(10)

3) At the relay, assume $(y_2^n(z_{i-1}|t_{i-1}, r_{i-1}, w_{23}, m_{i-1}), k_2^n(w_{23,i-1}, m_{i-1}), q_2^n(t_{i-1}, r_{i-1}|w_{23,i-1}, m_{i-1}), y_2^n(i-1), t_2^n(w_{12,i-1}, l_{i-1}), s_2^n(i-1)) \in A^n_1$, and $z_{i-1} \in B(t_{i})$.

Knowing $t_i$, $s_2^n(i)$, $w_{23,i}$, and $m_i$, the relay looks for the smallest $r \in [1, 2^{nR_z}]$ defined as $r_i$ such that $(q_2^n(t_i, r_i|w_{23,i}, m_i), k_2^n(w_{23,i}, m_i), s_2^n(i)) \in A^n_2$. For sufficiently large $n$ there exists such an index $r_i$ with arbitrarily high probability, if

$$R_{2}' > I(Q_2; S_2|K_2)$$

(11)

Then the relay transmits i.i.d $x_2^n(t_i|w_{23,i})$ drawn according to $p(x_2^n|q_2^n, k_2^n, s_2^n)$.

**Decoding (at the end of block i):** The destination at the end of block $i$ decodes $w_{13,i-1}$, $w_{23,i}$, and the relay decodes $w_{12,i}$.

1) Knowing $t_i$ from the previous block, the relay seeks a unique pair $(w_{12,i}, \hat{l}_i)$ such that $(t_2^n(w_{12,i}, \hat{l}_i), y_2^n(i), q_2^n(t_i, r_i|w_{23,i}, m_i), k_2^n(w_{23,i}, m_i), s_2^n(i)) \in A^n_2$. For sufficiently large $n$, $(w_{12,i}, \hat{l}_i) = (w_{12,i}, l_i)$ with arbitrarily small probability of error if

$$R_{12} + R_{12}' < I(T_2; Y_2, S_2|K_2, Q_2)$$

(12)

Note that we have performed a full decoding of the message $w_{12}$ and the index $l$, at the relay. So, the full vector $x_2^n(t_i|w_{23,i})$ has been decoded.

2) The relay finds a unique index $z$ such that:

$$(y_2^n(z|t_i, r_i, w_{23,i}, m_i), q_2^n(t_i, r_i|w_{23,i}, m_i), k_2^n(w_{23,i}, m_i), y_2^n(i))$$

source to the relay and $R_{12} = 0$).

Note that we have performed a full decoding of $k_2^n$ and $q_2^n$ at the destination in steps 3 and 4.

5) Now, knowing $t_{i-1}, r_{i-1}, w_{23}, m_{i-1}$ and $m_{i-1}$ (from the previous block), the destination calculates a set of indices $z$ denoted by the list $L(y_2^n(i-1))$ such that $(t_2^n(w_{13,i-1}, k_{i-1}), q_2^n(t_{i-1}, r_{i-1}|w_{23,i-1}, m_{i-1}), y_2^n(i-1), k_2^n(w_{23,i-1}, m_{i-1}), s_2^n(i-1)) \in A^n_2$. The destination declares that $z_{i-1}$ has been sent in block $i - 1$, if $z_{i-1} \in B(t_i) \cap L(y_2^n(i-1))$. With arbitrarily high probability $z_{i-1} = z_{i-1}$, if $n$ is sufficiently large and

$$\hat{R}_2 < R_2 + \hat{R}_2 < I(\hat{Y}_2; Y_2, S_2|K_2, Q_2)$$

(16)

6) Finally, the destination uses $y_2^n(i) - 1$ and $y_2^n(z_{i-1}|t_{i-1}, r_{i-1}, w_{23}, m_{i-1})$, and declares that $w_{13,i-1}$ is sent, if there is a unique $w_{13,i-1}$ for some $k_{i-1} \in [1, 2^{nR_z}]$ such that $(t_2^n(w_{13,i-1}, k_{i-1}), q_2^n(t_{i-1}, r_{i-1}|w_{23,i-1}, m_{i-1}), y_2^n(i-1), k_2^n(w_{23,i-1}, m_{i-1}), s_2^n(i-1)) \in A^n_2$. Thus, $w_{13,i-1} = w_{13,i-1}$ with arbitrarily high probability, if $n$ is sufficiently large and

$$R_{13} + R_{13}' < I(T_1; Y_3, \hat{Y}_2, Q_2|K_2)$$

(17)

Combining (4), (8), (9) with (12), (17), and (10) with (14) yields (1). The constraint in (5) follows from combining (11), (13), (15), and (16). Moreover, note that since $R_{13}, R_{12}, R_{23} > 0$ and due to (5), full decoding of $k_2^n$, $k_2^n$ and $q_2^n$ does not cause additional constraints. This completes the proof.}

**Remark 2:** By setting $S = S_1 = S_2 = \emptyset$ (to make state-independent channel), and re-defining $T_1 = U_1$, $T_2 = U_2$, $K_2 = V$ and $Q_2 = X_2$ in the region $R_1$, it yields the achievable region for RCPM in [4] Theorem 2). After these substitutions and simplifications, the only difference is in [5], with its counterpart in [4] Equation 21], where the reason is as follows: since the destination does not decode $U_2$ ($T_2$ is re-defined as $U_2$), in the random coding process $Y_2$ is not generated for each $U_2$. Therefore, due to covering lemma [20], $Y_2$ should cover both $Y_2$ and $U_2$, and

$$\hat{R}_2 > I(Y_2; Y_2, U_2|V, X_2)$$

is obtained. But in [4] the authors did not notice this point, and to obtain $\hat{R}_2$ they erroneously made conditioning on $U_2$ and so they obtained $\hat{R}_2 > I(Y_2; Y_2, U_2|V, X_2)$.}

**Remark 3:** By setting $(S_2, Q_2, K_2, X_2, \hat{Y}_2) = \emptyset$ in region $R_1$ (i.e., disable relaying), $R_1$ reduces to the achievable rate region for BC with non-causal CSIT that has been derived in [13].

**Remark 4:** The region $R_1$, reduces to the achievable rate for SD-RC with non-causal perfect CSI only at the source in [11] Theorem 1) by setting $K_2 = \emptyset$ (no private $W_{23}$ from the relay to destination and $R_{23} = 0$), $T_2 = \emptyset$ (no private $W_{12}$ from the relay to the source and $R_{12} = 0$), $S_2 = \emptyset$ and $S_1 = S$ (only the
source is informed of perfect CSI) and re-defining $Q_2 = X_2$ in $\mathcal{R}_1$. Moreover, setting $S_1 = \emptyset, S_2 = S, T_2 = \emptyset, K_2 = \emptyset$, and re-defining $T_1 = X_1$ in $\mathcal{R}_1$, results in the achievable rate for SD-RC with non-causal perfect CSI only at the relay in [14] Theorem 2].

Now, we specialize Theorem 2 to cases where perfect CSI is available non-causally only at the source, only at the relay, or both at the source and relay.

**Corollary 1:** Theorem 2 is specialized to an achievable rate region for SD-RCPM with non-causal perfect CSI only at the source, by setting $S_1 = S, S_2 = \emptyset$ (since only the source is informed of CSI) and re-defining $K_2 = V, Q_2 = X_2$ in $\mathcal{R}_1$. Furthermore, setting $S_1 = \emptyset, S_2 = S$ and re-defining $T_1 = U_1, T_2 = U_2$ in $\mathcal{R}_1$, yields an achievable rate region for SD-RCPM with non-causal perfect CSI only at the relay. Setting $S_1 = S_2 = S$ in $\mathcal{R}_1$ yields an achievable rate region for SD-RCPM with non-causal perfect CSI at both the source and relay.

**IV. SD-RCPM WITH CAUSAL CSI**

In many practical applications, the state sequence is not known in advance, and has to be known in a causal manner. In this section, we consider SD-RCPM with partial causal CSI at the source and the relay. In the following, the achievable rate region for this channel is derived.

**Theorem 2:** In the discrete memoryless SD-RCPM with causal CSI $S_1$ and $S_2$ respectively at the source and the relay, the non-negative rate tuples $(R_{12}, R_{23}, R_{13})$ denoted as $\mathcal{R}_2$, satisfying:

\[
R_{13} < I(T_1; Y_2, Y_3 | K_2, Q_2) \\
R_{12} < I(T_2; Y_2, S_2 | K_2, Q_2) \\
R_{13} + R_{12} < I(T_1; Y_2, S_2 | K_2, Q_2) + I(T_2; Y_2, S_2 | K_2, Q_2) - I(T_1; T_2) \\
R_{23} < I(K_2; Y_3),
\]

subject to $I(Y_3; Y_2, S_2, T_2 | K_2, Q_2, Y_5) \leq I(Q_2; Y_3 | K_2)$, are achievable for any joint p.m.f of the form

\[
p(s, s_1, s_2) p(k_2) p(q_2 | k_2) p(x_2 | q_2, k_2, s_2) p(t_1, t_2) p(x_1 | t_1, t_2, s_1) \times p(y_2, y_3 | x_1, x_2, s), p(y_2 | q_2, k_2, s_2, t_2),
\]

where $X_1 = f_1(T_1, T_2, S_1), X_2 = f_2(Q_2, K_2, S_2)$ and $f_1(\cdot)$ and $f_2(\cdot)$ are two arbitrary deterministic functions.

**Proof:** Similar to the single user channel, the proof of the causal case follows the lines of the proof for the non-causal case in Theorem 1. The only difference is that since in the causal case $(T_1, T_2)$ and $S_1$ are independent (see (23)), the encoding scheme for the non-causal case is reduced to the one that does not include GP binning, and therefore does not require non-causal knowledge of $S_1$. Similar situation happens for $(K_2, Q_2)$ and $S_2$. So, the coding scheme is obtained based on using Shannon’s strategy in the source and the relay which are informed of CSI to incorporate the state knowledge, using random binning corresponds to Marton’s simplified region for BC in [19] at the source, and using CF relaying scheme at the relay. The proof is rather straightforward and is omitted here for brevity.

**Remark 5:** The expression of $\mathcal{R}_2$ can be interpreted as a special case of $\mathcal{R}_1$, where $(T_1, T_2)$ are independent of $S_1$, and $(K_2, Q_2)$ are independent of $S_2$. This is similar to the relation between the expression for the capacity of state-dependent single user channel with causal CSI [17], and its non-causal counterpart [16]. Hence, similar to Remark 4 $\mathcal{R}_2$ can be reduced to achievable rates derived for SD-RC with causal CSI in [13]. Moreover, similar to Corollary 1 $\mathcal{R}_2$ can be specialized to achievable rate regions for SD-RCPM with non-causal perfect CSI only at the source, only at the relay, or both at the source and relay.

**V. GAUSSIAN EXAMPLE**

In this section, we consider a general full-duplex Gaussian RC with private messages and with additive independent Gaussian state and noise, and we refer to it as Gaussian SD-RCPM. The outputs at the relay and the destination at time $j = 1, \ldots, n$ for Gaussian SD-RCPM are given by:

\[
Y_{2j} = X_{1j} + Z_{2j} + S_j \quad \text{and} \quad Y_{3j} = X_{1j} + X_{2j} + Z_{3j} + S_j, \quad (24)
\]

where $X_{1j}$ and $X_{2j}$ are transmitted signals by the source and the relay with individual average power constraints $P_1$ and $P_2$, $Z_{2j}$ and $Z_{3j}$ are independent zero-mean Gaussian RVs with variances $N_2$ and $N_3$. The channel state $S_j$ is a zero-mean Gaussian RV with variance $Q$, and is independent of $Z_{2j}$ and $Z_{3j}$.

As an example, we consider the case where the source knows state sequence $S^n$ non-causally and perfectly, while the relay is not informed of CSI. To provide an achievable rate region for this Gaussian case, we use the results obtained in Corollary 1 for this scenario. For simplicity, we assume that input distributions are Gaussian, although this assumption may not be optimal. Similar to [4], we assume that the generated codebook at the source is mapped into Gaussian RVs as $X_1 = U_1 + U_2$, and $\rho$ denotes the correlation coefficient between $U_1$ and $U_2$. Power constraint $P_1$ at the source, and parameter $\rho$ lead to power constraints for $U_1$ and $U_2$ (i.e., $P_{U_2} = \gamma P_1, P_{u_1} + P_{u_2} + 2\rho \sqrt{P_{u_1}P_{u_2}} = P_1$). Now, since the source is informed of CSI, it uses Dirty Paper Coding (DPC) (21) for transmission of message $W_{12}$ (codeword $U_2$) to relay, and uses another DPC for transmission of message $W_{13}$ (codeword $U_1$) to destination. Hence, similar to Costa’s initial DPC, the auxiliary RVs $T_1$ and $T_2$ are defined as $T_1 = U_1 + \alpha_1 S$ and $T_2 = U_2 + \alpha_2 S$, respectively. Moreover, to partially cancel the state, arbitrary correlations are assumed between $U_1$ and $S$ (via $\rho_{u_1s}$), and between $U_2$ and $S$ (via $\rho_{u_2s}$) which is called Generalized DPC (GDP). Without loss of generality $\rho_{u_2s}$ can be set to zero (i.e., using DPC instead) since $U_2$ is defined for transmission of $W_{12}$ on the point to point link between the source and relay. The relay is not informed of CSI, so $E(WS_2) = 0$ and it does not use DPC. At the relay, $\theta$ is the fraction of the relay’s power which is dedicated to the relay’s private message. Therefore, $X_2 = V + X_2', $ where $V \sim N(0, \theta P_2)$ and $X_2' \sim N(0, (1-\theta)P_2)$ are independent. We assume $Y_2 = Y_2 + fT_3 + Z_2$ where $\beta \in [0, 1]$ and $f \in [-1, 1]$, and compression noise $Z_2 \sim N(0, \beta^2)$ is independent of $S, X_1, X_2, Z_3, Z_4$. We let $f$ to be negative to consider the cases where the relay peels-off the part intended for the relay (i.e., $T_2$), and then compresses the remaining part to send to the destination. $f = 0$ refers to the case where relay only compresses $Y_2$ without removing or compressing $T_2$. So, we evaluate for this scenario (informed source only) and for a given $(\rho, \gamma, \alpha_1, \alpha_2, \rho_{u_1s}, \rho_{u_2s}, \theta, \beta, f)$ by varying these parameters, and taking the union of the resulted regions, the achievable rate region for this scenario is established (its expression is omitted here due to space). By ignoring private messages in this channel (i.e., setting $\gamma = 0$ and $\theta = 0$), this achievable region reduces to the achievable rate derived in [11] Theorem 4) for Gaussian SD-RC with non-causal CSI only at the source.

In Fig. 1 our achievable rate region for Gaussian SD-RCPM with non-causal CSI at the source, is plotted for $P_1 = Q = N_3 = 100$, $P_2 = 15$, $N_2 = 15$, parameterized by the fraction of
We introduced SD-RCPM as a generalization of SD-RC and SD-PCRBC. In order to have a unified view, both causal and non-causal cases were investigated. In each case, an achievable rate region for SD-RCPM with partial CSI at the source and relay was derived using CF scheme. We also derived an achievable rate region for Gaussian version of SD-RCPM with non-causal perfect CSI only at the source. In ongoing work, we are using DF scheme for both discrete memoryless and Gaussian version of SD-RCPM with causal and non-causal CSI.

VI. Conclusion

Fig. 1. CF based achievable rate region for general Gaussian SD-RCPM with non-causal CSI only at the source, parametrized by $\theta$.

Fig. 2. General Gaussian SD-PCRBC with non-causal CSI only at the source, for “power set 1” and “power set 2”.

the relay’s power dedicated to relay’s private message ($\theta$), and we can see the trade-off between $R_{13}$ and $R_{12}$. As illustrated in Fig. 1 when $\theta$ is increased, the maximum achievable $R_{13}$ is decreased. For example, $\theta = 0$ refers to the case where the relay sends no private message to the destination ($W_{23} = \emptyset$), and Gaussian SD-RCPM reduces to Gaussian SD-PCRBC. Therefore, for this case we can compare our CF based achievable region, with the DF based achievable region derived in [14] Theorem 5] is a trivial outer bound on the capacity region of SD-PCRBC. So we illustrate this outer bound, DF and CF based rate regions in Fig. 2 for two examples of noise configuration: 1) $N_2 = N_3$ ($N_2, N_3 = 10\mathrm{dB}, P_1 = 20\mathrm{dB}$) which is denoted as “power set 1” in Fig. 2 2) $N_3 > N_2$ ($N_3 = 10\mathrm{dB}, N_2 = 8\mathrm{dB}, P_1 = 16\mathrm{dB}$) denoted as “power set 2”. For both “power set 1” and “power set 2”, $Q = 10\mathrm{dB}, P_2 = 25\mathrm{dB}$. For these power sets, DF outperforms DF in PC-RBC (state-independent). So, in the state-dependent version of this channel it can outperform DF which is shown in Fig. 2. In these examples, if $P_2$ is also increased, CF based bound becomes closer to its respective outer bound. Note that for noise configuration where $N_3 < N_2$, it is clear that CF outperforms DF, and to prevent having a messy figure this case is not depicted in Fig. 2. We remark that these power sets are chosen to have cases that can be presented in one figure. It is also interesting to note that for all these cases, maximum achievable $R_{12}$ (when $R_{13} = 0$) coincides with that of derived for PC-RBC (state-independent), and this confirms that a complete state cancellation is performed for sending $U_2$ on the source-relay link for $R_{13} = 0$.

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