Diffusion of innovations in Axelrod’s model

Paulo F C Tilles and José F Fontanari

Instituto de Física de São Carlos, Universidade de São Paulo, Caixa Postal 369, 13560-970 São Carlos SP, Brazil
E-mail: fontanari@ifsc.usp.br

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Abstract. Axelrod’s model for the dissemination of culture contains two key factors required to model the process of diffusion of innovations, namely, social influence (i.e. individuals become more similar when they interact) and homophily (i.e. individuals interact preferentially with similar others). The strength of these factors is controlled by two parameters: $F$, the number of features that characterize the cultures, and $q$, the common number of states each feature can assume. For fixed $F$, a large value of $q$ reduces the frequency of interactions between individuals because it makes their cultures more diverse. Here we assume that the innovation is a new state of a cultural feature of a single individual—the innovator—and study how the innovation spreads through the networks of the individuals. For infinite regular lattices in one (1D) and two dimensions (2D), we find that initially successful innovation spreads linearly with time $t$, but in the long-time limit it spreads diffusively ($\sim t^{1/2}$) in 1D and sub-diffusively ($\sim t/\ln t$) in 2D. For finite lattices, the growth curves for the number of adopters are typically concave functions of $t$. For random graphs with a finite number of nodes $N$, we argue that the classical S-shaped growth curves result from a trade-off between the average connectivity $K$ of the graph and the per-feature diversity $q$. A large $q$ is needed to reduce the pace of the initial spreading of the innovation and thus delimit the early-adopters stage, whereas a large $K$ is necessary to ensure the onset of the take-off stage at which the number of adopters grows superlinearly with $t$. In an infinite random graph we find that the number of adopters of a successful innovation scales with $t^\gamma$ with $\gamma = 1$ for $K > 2$ and $1/2 < \gamma < 1$ for $K = 2$. We suggest that the exponent $\gamma$ may be a useful index to characterize the process of diffusion of successful innovations in diverse scenarios.

Keywords: interacting agent models, stochastic processes
1. Introduction

An innovation is an idea, practice, or object that is perceived as new by a community. In many situations, the diffusion of an innovation involves one individual—the innovator—who informs potential adopters about a new idea, who, in turn, pass on the information to their near-peers. This exchange of information occurs through a convergence process in which the participants share information with one another to reach a mutual understanding. The transfer of ideas occurs most frequently between two individuals who are alike [1].

The above sketchy account of the process of diffusion of innovations, which is based on Everett Rogers’ 1962 seminal book Diffusion of Innovations [1], contains all the ingredients of a very popular agent-based model proposed much later by the political scientist Robert Axelrod [2] to explain the persistence of cultural diversity in the society despite the effect of social influence that tends to increase the similarity of interacting agents. Since Axelrod uses the term culture to indicate any set of individual attributes that are susceptible to social influence, his model suits well the study of the diffusion of innovations within Rogers’ framework.

In Axelrod’s model agents are represented by strings of cultural features of length \( F \), where each feature can adopt \( q \) distinct states (i.e. \( q \) is the common number of states each feature can assume). A characteristic that sets Axelrod’s model apart from most models of social influence (see [3–5] for reviews) is that it accounts for homophily, which is the tendency of individuals to interact more frequently with individuals who are more similar to them. In particular, according to the rules of Axelrod’s model, the interaction between two neighboring agents occurs with probability proportional to the
number of cultural states they have in common: agents who do not have any cultural state in common cannot interact and the interaction between agents who share all their cultural states does not result in any change. This is a most important characteristic from the perspective of the diffusion of innovations since the very nature of diffusion requires some degree of heterophily between the innovator and the other agents: ideally, they would be homophilous in all other variables (e.g. education and social status) even though they are heterophilous regarding the innovation [1]. In Axelrod’s model an interaction between two neighboring agents consists of selecting at random one of the distinct features, and making the selected feature of one of the agents—the target agent—equal to its neighbor’s corresponding state. This rule models social influence since the agents become more similar after they interact. Hence there is a positive feedback loop between homophily and social influence: similarity leads to interaction, and interaction leads to still more similarity [2].

In this paper we model innovation as a novel state (say, state \(q + 1\)) that appears in the initial configuration at a single cultural feature (say, feature 1) of a single agent (the innovator) located at the origin of a regular lattice of linear size \(L\) with periodic boundary conditions or at the origin of a random graph of \(N\) nodes. (In both cases the choice of the origin is arbitrary.) In the regular lattice, \(N = L^d\) where \(d\) is the lattice dimension. The \(F\) cultural features of all other agents, as well as the \(F - 1\) features of the innovator, are set randomly according to a uniform distribution in the integers \(1, 2, \ldots, q\), as usual [2]. The important ingredient here is that the innovation in the innovator (i.e. the state of feature 1 of the agent at the origin) is fixed and cannot be changed by the rules of Axelrod’s model. However, all other agents that adopt the innovation (adopters) may, in principle, discard it through the interactions with their neighbors. This scheme is similar to the framework used to study cultural drift in Axelrod’s model, modeled as a perturbation (noise) acting continuously at a single site of the lattice [6], or to the presence of a zealot in the voter model [7]. The main difference is that both the noise source site and the zealot can change their states due to the interactions with their neighbors and their eventual return to the original states is guaranteed by external mechanisms.

In the thermodynamic limit \(N \rightarrow \infty\), the ultimate fate of the innovation depends on the set of parameters \(F\) and \(q\), since the choice of these parameters determine whether the population reaches a consensus regime in which all agents (or at least a macroscopic number of agents) share the same culture or the population is fragmented in an infinity of cultural domains of microscopic size. The nonequilibrium phase transition separating these two stationary regimes has been the object of intensive research by the statistical physics community [8–13]. Clearly, in our scenario of diffusion of innovations the consensus regime corresponds to the situation in which the innovation is adopted by the entire population (i.e. the introduction of the innovation in the community was successful): since the innovator has the innovation fixed there cannot be consensus unless all agents adopt the innovation. The multi-cultural regime corresponds to the situation in which the innovation is confined to a finite region around the innovator.

We find that in the consensus regime, where the introduction of the innovation is successful, the initial spreading of the innovation is ballistic in the one-dimensional regular lattice and diffusive in the two-dimensional case. More pointedly, we show that, regardless of the topology and connectivity of the network, initially the number
of adopters always increases linearly with time \( t \), and we derive an analytical expression for its (constant) rate of increase \( v = v(F, q) \) for short times. In the time asymptotic limit, we find that Axelrod’s model in the presence of the innovator behaves essentially as the voter model in the presence of a zealot, and so the number of adopters grows with \( t^{1/2} \) for the one-dimensional lattice and with \( t/\ln t \) for the two-dimensional lattice [7].

However, in regular lattices the typical growth curves for the number of adopters do not exhibit the classical S-shape observed in innovation diffusion experiments [1, 14]. Sigmoid-shaped growth curves are recovered for random graphs of large average connectivity \( K \). For random graphs with an infinite number of nodes we find that the number of adopters increases with \( t^{\gamma} \) where \( \gamma = 1 \) for \( K > 2 \) irrespective of the values of the parameters \( F \) and \( q \), provided convergence to the consensus regime is guaranteed. For \( K = 2 \) we find \( 1/2 < \gamma < 1 \). Since the exponent \( \gamma \) is sensitive to the social network topology it may be a useful quantitative measure to characterize the process of diffusion of innovations in diverse scenarios.

The remainder of the paper is organized as follows. In section 2 we present a brief account of Axelrod’s model and describe how the model is modified so as to reckon with the presence of the innovator at the origin of the network. In section 3 we study the spreading of the innovation in the one-dimensional lattice and present the analytical calculation of the rate \( v \) for short times. In addition, we estimate the diffusion constant in the time asymptotic limit by assuming that the Axelrod model in the presence of the innovator approaches the consensus regime in a similar way to the voter model [7, 15, 16]. The spreading in the two-dimensional lattice is considered in section 4 and the spreading in random graphs in section 5. Finally, section 6 offers our concluding remarks.

2. Model

In Axelrod’s model each agent is characterized by a set of \( F \) cultural features and each feature can take on \( q \) different states, which we label by the integers \( 1, 2, \ldots, q \). Hence there are \( q^F \) distinct cultures in total. In the initial configuration \( (t = 0) \) each agent is assigned one of these cultures with equal probability. The \( N \) agents are fixed in the nodes (sites) of a network. Here we will consider one-dimensional (\( d = 1 \)) and two-dimensional (\( d = 2 \)) regular lattices of linear length \( L \) with periodic boundary conditions, i.e. a ring and a torus, respectively, where only nearest–neighbors interactions are allowed. To probe the effects of the short-ranged interactions and of the low average connectivity of those regular lattices we will consider random graphs with average connectivity \( K = 2 \) and \( K = 40 \), as well.

According to the dynamics of the original model [2], at each time \( t \) we pick an agent at random—the target agent—as well as one of its neighbors. As usual in such asynchronous update schemes we choose the time unit as \( \Delta t = 1/N \). These two agents interact with probability equal to their cultural similarity, defined as the fraction of common cultural features. As pointed out before, this procedure models homophily. An interaction consists of selecting at random one of the distinct features, and making the
selected feature of the target agent equal to its neighbor’s corresponding state. We note that neighboring agents with antagonistic cultures (i.e. cultures that do not share any cultural state) do not interact, whereas in the case of two agents that are identical, the interaction produces no changes. This procedure is repeated until the system is frozen into an absorbing configuration. At an absorbing configuration any pair of neighbors are either identical or completely different in terms of their cultural states.

Our scenario to study the diffusion of innovations in Axelrod’s model requires a simple modification of the original setup described above. In particular, we assume that there is a special agent—the innovator—located at the origin of the network who exhibits a novel cultural state in one of its cultural features. Without loss of generality, at the beginning of the simulation we assign the new state $q + 1$ to cultural feature 1 of the innovator; the other $F - 1$ features are set randomly to the usual $q$ states as done for the $F$ features of the other agents. Hence at $t = 0$ the innovator and the rest of the population are heterophilous with regard to the innovation. In addition, for the innovator only the state $q + 1$ (i.e. the innovation) is fixed and cannot be changed through interaction with the other agents. More specifically, in the case where the innovator is selected as the target agent and its cultural feature 1 is selected to change, we do not implement the change. Otherwise, all interactions follow the usual rules of the Axelrod model. We stress that this exception holds for the innovator only. The novel state can be replaced by the other states when the other agents are updated. Of course, only feature 1 of the agents can assume the novel state $q + 1$ as the dynamics unfolds; the remaining $F - 1$ features take on the usual states $q_1, \ldots, q$.

The main measure we will consider in this paper is the mean number of agents who have adopted the innovation (adopters) at a given time $t$, denoted by $N\xi(t) - 1$, where $\xi(t)$ is the mean fraction of agents that exhibit the innovation (i.e. state $q + 1$ at cultural feature 1). Note that the innovator does not count as an adopter. In the one-dimensional lattice the adopters form a compact domain of length $N\xi$ around the innovator.

### 3. Spreading in the one-dimensional lattice

Our aim in this section is to understand how the parameters $F$ and $q$ influence the diffusion of the innovation in a ring of $N = L$ agents which are allowed to interact with their two nearest neighbors only. It is well-known that in the absence of the innovator at the origin of the lattice the model exhibits a phase transition in the space of parameters $(F, q)$ that separates the regimes characterized by consensus and multicultural absorbing configurations [9, 10]. Typically, the consensus regime occurs in the region of small $q$ and large $F$, whereas the multicultural regime occurs for large $q$ and small $F$. In particular, for $F = 3$ the innovator-free model exhibits a consensus regime for $q = 2$ and a multicultural regime for $q > 2$ in the thermodynamic limit [9]. We do not expect that the presence of the innovator would in any way alter this transition. However, the spreading of the innovation should depend strongly on whether the parameters of the innovator-free model are set so as to favor consensus or cultural diversity.
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Figure 1 shows the mean number of agents that have adopted the innovation at time $t$ for the parameter set $F = 3$ and $q = 2$, which corresponds to the consensus phase of the innovator-free model in the thermodynamic limit. Of course, since for finite $L$ the number of adopters is bounded by the lattice size $N = L$, we must observe a saturation of the number of adopters in the asymptotic limit $t \to \infty$. However, if we increase $L$ and keep $t$ finite (i.e. take the limit $L \to \infty$ before the limit $t \to \infty$ [17]) then all data fall on the power law function $t^\gamma$ with $\gamma = 1/2$ for large $t$, which shows that in the asymptotic time limit the spreading of the innovation is diffusive in an infinite lattice. For small $t$, we observe a ballistic spreading of the innovation in the ring (i.e. $N \xi - 1 \propto t^{\gamma}$ with $\gamma = 1$) with a rate $v$ that is independent of the lattice size. The challenge here is to derive an analytical estimate for the diffusion constant that characterizes the spreading for large $t$ and for the rate $v$ in the limit of small $t$. We will offer those estimates after we conclude the analysis of the simulations.

Figure 2 exhibits the evolution of the mean number of adopters for the parameter set $F = 3$ and $q = 3$, corresponding to the multicultural regime of the innovator-free model in the thermodynamic limit. Although for small $t$ we observe a ballistic spreading of the innovation, the diffusive regime never sets in and the innovation is confined to only a finite number of adopters even for an infinite lattice. In this case, the attempts of the innovator to introduce the innovation in the community failed altogether.

In order to punctuate the effect of varying the number of states $q$ for a fixed number of features $F = 8$ and so observe the two regimes of the innovator-free model in the same graph, figure 3 shows the evolution of the mean number of adopters for a chain of length $L = N = 25,600$. Since chains larger than this size produce indistinguishable curves, the figure exhibits effectively the results for the thermodynamic limit in that range of $t$. The transition takes place between $q = 6$ (consensus regime) and $q = 7$ (multicultural regime). This figure reveals two interesting results, namely, that the diffusion constant does not depend on $q$ in the consensus regime and that the rate of increase of the number of adopters decreases with increasing $q$ for short times. Next we will offer analytical evidence for these findings.
3.1. Analytical results for short-time dynamics

The simulation results indicate that for small $t$ we can write $N\xi(t) \approx 1 + vt$ where $v = v(F, q)$ is the short-time constant rate of increase of the number of adopters. We can determine $v$ by considering the first iteration only, i.e. the evolution from $t = 0$ to $t = 1/N$. (We recall that $N\xi(0) = 1$ and $\Delta t = 1/N$). The mean number of agents exhibiting the innovation (i.e. the innovator plus the adopters) at $t = 1/N$ can be written as

$$
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$$
N\xi(t) \approx 1 + vt
$$
\[ N \xi(1/N) = 2 \times \psi(F, q, N) + 1 \times [1 - \psi(F, q, N)] = 1 + \psi(F, q, N) \]  
\[ \psi(F, q, N) = \frac{1}{N} \sum_{m=1}^{F-1} \left( \frac{F-1}{m} \right) \frac{1}{q^m} \left( 1 - \frac{1}{q} \right)^{F-1-m} \frac{m}{F} \frac{1}{F - m}. \]  
\[ \xi = \frac{1}{N} (q - 1) F. \]  
\[ v = \frac{1 - q^{1-F}}{(q - 1) F}. \]

In figure 4 we compare the predictions of equation (4) with the results of the Monte Carlo simulations for the short-time regime using the same parameter set of figure 3. The analytical results agree perfectly with the simulation results, as expected. The reason that \( v \) decreases with increasing \( q \) is because the probability of interaction decreases with \( q \); the larger the \( q \) the lower the chance that the target agent and the innovator will have many features in common. In addition, the larger the \( F \), the lower the chance that feature 1 of the innovator will be selected to be transferred to the target agent. Most importantly, as pointed out above, equation (4) is valid for lattices of arbitrary dimensions \( d \) and for any graph topology since its derivation does not depend on the connectivity of the agents.

A word is in order about the short-time dynamics of the standard voter model. This model plays a key role in the analysis of the diffusive regime as described next. In fact, since in the voter model the agents always interact and the interaction always changes the target agent we have \( \psi = 1/N \), i.e. the probability that the innovation is adopted...
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by a neighbor of the innovator is given simply by the probability that any neighbor of the innovator is selected as the target agent and that the innovator is the neighbor chosen to interact with the target agent. Hence \( v = 1 \) for the voter model.

Finally, we note that we have not proved that for short times the number of adopters increases linearly with \( t \): what we have shown here was that if we assume this linear growth, as observed in the Monte Carlo simulations, then the linear coefficient \( v \) is given by equation (4). However, as we will see next, for the one-dimensional voter model we can show analytically that the number of adopters in fact grows linearly with \( t \) and that \( v = 1 \).

3.2. Analytical results for the long-time dynamics

An unexpected and somewhat unpleasant finding of our simulations is that the presence of the innovator at the origin considerably increases the time the dynamics takes to freeze into a consensus absorbing configuration as compared with the freezing time in the innovator-free situation. More pointedly, we have observed that the agents first reach a consensus for all features except for feature 1 (the innovation) and then they struggle to reach a consensus about feature 1, which keeps fluctuating at the border of the domains until the innovation eventually reaches fixation. This final stage of the dynamics accounts for most of the relaxation time. In this stage the dynamics reduces essentially to the dynamics of the voter model in which the agents are characterized by two states: 1 if they adopt the innovation and 0 otherwise. This is the reason the number of adopters in the diffusive regime shown in figure 3 does not exhibit dependence on \( q \); the system behaves as if \( q = 2 \) in that regime. There is, however, a dependence on \( F \) which appears because in the case of a single unfixed feature the probability of interaction for Axelrod’s model is \((F - 1)/F\) whereas for the voter model it is 1. But this fact can be accounted for by a simple rescaling of the time \( t \).

To obtain a quantitative estimate of the diffusion constant associated with the diffusive behavior exhibited in figures 1 and 3 we will calculate the diffusion constant

Figure 4. Short-time dynamics of the rescaled mean number of adopters \((N\xi - 1)/t\) for a chain of size \( L = 25\,600 \), \( F = 8 \) and (top to bottom) \( q = 2, 3, \ldots, 11 \). The horizontal (blue) lines show the predictions of equation (4). The total number of runs is \( 10^8 \) for each \( t \) and \( q \).
$D_v$ for the voter model. Let us assume that all agents in the chain exhibit opinion 0 except for the innovator at the origin that exhibits opinion 1. The mapping of the voter model on a spin-1/2 ferromagnetic Ising chain with zero-temperature Glauber dynamics allows the derivation of the probability $p_{n}(t)$ that an agent at a distant $n$ site from the origin exhibits opinion 1 at time $t$

$$p_{n}(t) = 1 + e^{-t} \sum_{m=1}^{\infty} [I_{n+m}(t) - I_{n-m}(t)],$$

where $I_{n}(t)$ refers to the modified Bessel functions of the first kind [18]. Using the property $I_{-n}(t) = I_{n}(t)$ we verify that $p_{0}(t) = 1$, as expected. Most importantly, $p_{n}(t)$ also yields the probability that the agents at the adjacent sites $k = 1, 2, \ldots, n-1$ exhibit the innovation too. In other words, if the agent at site $n$ has opinion 1 then all agents at the sites between the origin and site $n$ must have opinion 1 too. Hence $p_{n}(t)$ is the probability that there are at least $n$ adopters to the right of the origin. The probability that there are exactly $n$ (contiguous) adopters to the right of the origin at time $t$ is

$$q_{n}(t) = p_{n}(t) - p_{n+1}(t) = e^{-t} [I_{n}(t) + I_{n+1}(t)],$$

which is properly normalized since $\sum_{n=0}^{\infty} q_{n}(t) = p_{0}(t) = 1$, as expected. Alternatively, we can verify this normalization by explicitly carrying out the summation over the indices of the Bessel functions with the aid of the identity [19]

$$2 \sum_{n=1}^{\infty} I_{n}(t) = e^{t} - I_{0}(t).$$

Since the spreading to the left of the origin is independent of the spreading to the right (the fixed origin acts as a wall that prevents information from passing through it) we can say that the probability that there are exactly $n$ (contiguous) adopters to the right of the origin and exactly $m$ to the left at time $t$ is $q_{n,m}(t) = q_{n}(t)q_{m}(t)$. The mean number of adopters is then

$$N_{\xi}(t) - 1 = \sum_{n=0}^{\infty} \sum_{m=0}^{n} (n + m)q_{n,m}(t) = 2 \sum_{n=0}^{\infty} nq_{n}(t) = 2e^{-t} \left[ 2 \sum_{n=1}^{\infty} nI_{n}(t) - \sum_{n=1}^{\infty} I_{n}(t) \right].$$

The use of equation (7) together with the identity [19]

$$2nI_{n}(t) = t[I_{n-1}(t) - I_{n+1}(t)]$$

yields

$$N_{\xi}(t) - 1 = e^{-t} [(2t + 1)I_{0}(t) + 2tI_{1}(t)] - 1,$$

which is the exact expression of the number of adopters for the one-dimensional voter model. Using the asymptotic form of the Bessel functions for small arguments we obtain $N_{\xi}(t) - 1 \approx t$ in the short-time limit, which proves that the initial spreading is
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ballistic with rate $v = 1$. For large $t$ we can use the asymptotic form of the Bessel functions $I_0(t) \sim e^t / \sqrt{2\pi t}$ to obtain

$$N\xi(t) - 1 \sim \left( \frac{4D_v}{\pi} \right)^{1/2} t^{1/2}$$

(11)

where $D_v = 2$ is the diffusion constant of the voter model. Since the number of adopters is akin to the total magnetization of the voter model, the diffusive behavior described by equation (11) concurs with the findings of the voter model in the presence of a zealot [7].

As already pointed out, in the case of a single unfixed feature the probability of interaction for Axelrod’s model is $(F - 1)/F$ whereas for the voter model it is 1. This means that an interaction in Axelrod’s model occurs at each $(F - 1)/F$ time step on average. So the replacement $t \rightarrow t(F - 1)/F$ in equation (11) yields the correct expression for the mean number of adopters in the diffusive regime of Axelrod’s model,

$$N\xi(t) - 1 \sim \left( \frac{4D}{\pi} \right)^{1/2} t^{1/2}$$

(12)

where the diffusion constant is $D = 2(F - 1)/F$. Figure 5 shows the comparison between the predictions of equation (12) and the results of the Monte Carlo simulations for a chain of fixed size $L = 6400$. We use this rather small chain size because of the large number of runs (typically $10^5$) needed to smooth out fluctuations. However, except for $F = 3$, this figure shows good agreement between theory and simulations. We note that the deviation from the diffusive regime observed for very large values of $t$ is due to the saturation of the finite lattice. In the case $F = 3$, which corresponds to the lowest value of the diffusion constant, much larger chain sizes are needed to observe the diffusive regime, which we estimate would become perceptible for $t > 10^{12}$ only. Hence figure 5 supports our conjecture that in the thermodynamic limit the asymptotic spreading of the innovation in the one-dimensional Axelrod’s model is identical to the spreading in the voter model, except for a trivial rescaling of the time or, equivalently, of the diffusion constant.

4. Spreading in the two-dimensional lattice

We consider now the spreading of the innovation in a square lattice of linear size $L$. Figure 6 shows the results of the simulations for $F = 3$ and a fixed linear lattice size $L = 200$. As in the one-dimensional case, the presence of the innovator at the origin considerably increases the freezing time as compared with the innovator-free model, which then poses serious restrictions on the sizes of the lattices that we can simulate to obtain reliable statistical measures. For instance, for $F = 3$ the innovator-free model in the thermodynamic limit exhibits a consensus regime for $q \leq 15$ and a multicultural regime for $q \geq 16$ [12], whereas the results for $L = 200$ shown in the figure indicate that $q = 15$ corresponds to the multicultural regime. This misleading indication is due to the finite size effects. Nevertheless, despite this discrepancy around the transition region,
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Figure 5. Long-time dynamics of the rescaled mean number of adopters $F(N\xi - 1)/t^{1/2}$ for a chain of size $L = 6400$, $q = 2$ and (bottom to top) $F = 3$, 4, 5, 6, 7, 8. The horizontal (blue) lines show the predictions of equation (12) with the diffusion constant $D = 2(F - 1)/F$. The total number of runs is $10^8$ for each $t$ and $F$.

Figure 6. Mean number of adopters as a function of time for a square lattice of linear size $L = 200$, $F = 3$ and (bottom to top) $q = 17$, 16, 15, 14, 11, 8, 5, 2. For this lattice size, the curves for $q < 14$ are indistinguishable in the long-time regime. The dashed (blue) lines illustrate the linear spreading ($\propto t$) of the innovation in the short-time regime and the slow spreading ($\propto t/\ln t$) in the long-time regime, similar to the findings for the voter model in the presence of a zealot [7]. The total number of runs is $10^4$ for each $t$ and $q$.

Figure 6 reveals all the relevant information about the spreading of the innovation in the square lattice, as described next.

As pointed out, for small $t$ the mean number of adopters is given by $N\xi(t) - 1 = vt$ with the rate $v$ given by equation (4), so that the innovation spreads faster when the initial diversity of the population, which is measured by $q$, is low. This dependence on $q < 14$ disappears for large $t$ indicating that, similar to our findings for the one-dimensional lattice, the system behaves as a two-state voter model in the long-time limit. (In the thermodynamic limit this should happen for $q < 16$ [12]). Since in the context of the
voter model the total number of adopters is analogous to the total magnetization of a lattice influenced by a zealot at the origin we conjecture that $N \xi - 1 \sim t/\ln t$ for large $t$ [7]. This asymptotic behavior is consistent with the data presented in figure 6, which shows that the slopes of the curves in the long-time regime (i.e. large $t$ but not too large to avoid the saturation due to the finite value of $L$) are slightly lower than 1. In the multicultural regime $q > 15$ the innovation is restrained to a finite region around the innovator, as expected. A similar analysis for $F > 3$ yields the same qualitative results.

5. Spreading in random graphs

A conspicuous aspect of the diffusion of innovations in a regular lattice discussed in the previous sections is the absence of the classical S-shaped growth curves in the plots of the number of adopters against time [1, 14]. In fact, except perhaps for the region of values of $q$ close to the phase transition in the square lattice (see figure 6) the growth curves do not exhibit the expected sigmoid shape. Of course, in the consensus regime this shape could be observed for finite $N$ only, since for an infinite lattice the number of adopters does not saturate in the limit $t \to \infty$. However, the manner in which $N \xi - 1$ scales with $t$ in this limit offers a most valuable characterization of the spreading process, as shown in the previous sections for regular lattices. To investigate whether the absence of S-shaped growth curves for the number of adopters in Axelrod’s model is due to the short-ranged nature of the interactions (nearest neighbors) or to the low connectivity of the regular lattices, in this section we study the spreading of innovations in random graphs with $N$ nodes and average connectivity $K$.

Strictly speaking, the graphs we consider here are not the classical random graphs but the limit of the sure rewiring of the Watts and Strogatz algorithm for constructing small-world networks [20]. Explicitly, we begin with a one-dimensional lattice of $N$ nodes, each node connected to $K$ neighbors ($K/2$ on each side), and periodic boundary conditions. Then for every node $i = 1, \ldots, N$ we rewire the $K/2$ links between $i$ and $j = i + 1, i + 2, \ldots, i + K/2$ (the sums are done modulo $N$) with probability $\beta = 1$. The rewiring of a link is done by replacing the original neighbor of node $i$ by a random node chosen uniformly among all possible nodes that avoid self-loops and link duplication. The advantage of this formulation, which was also used in studies of Axelrod’s model on complex networks [21], is that the origin (i.e. node $i = 1$, where the innovator is located) is guaranteed to be connected to at least $K/2$ nodes, regardless of the values of $N$ and $K$, whereas for the classical random graphs that particular node has a probability $e^{-K}$ of being isolated from the other $N - 1$ nodes. Otherwise, the resulting graphs are very similar to classical random graphs. For instance, the degree distribution is a Poisson distribution of mean $K$. We recall that, regardless of the topology and connectivity of the network, for small $t$ the mean number of adopters increases linearly with $t$ with a rate given by equation (4).

In figure 7 we consider low-connectivity random graphs ($K = 2$) for the purpose of comparison with the one-dimensional lattice. As in that case, the growth curves do not exhibit inflection points. For such low-connectivity graphs it is difficult to establish the existence of a consensus regime because the graphs may not be connected, so that the
spreading of the innovation is restricted to the innovator’s connected subgraph and, in this case, the asymptotic values of the number of adopters would be determined by the distribution of the sizes of the connected subgraphs. Nevertheless, since on the average the size of that subgraph increases with increasing \( N \), it is still possible to observe the unlimited growth of the number of adopters with increasing time in the thermodynamic limit. This is illustrated in figure 8 which shows that the number of adopters scales with \( t^\gamma \) with \( \gamma \approx 0.68 \) for \( F = 3 \) and \( q = 2 \), indicating that the innovation spreads faster, due to the long range links, than in the chain with nearest-neighbors interactions. For \( K = 2 \) we find the same value of that exponent (i.e. \( \gamma \approx 0.68 \)) for all \( F > 2 \) and \( q \). For \( F = 2 \) the consensus regime occurs for \( q = 2 \) only, and in that case we find \( \gamma \approx 0.60 \).

Figure 9 shows the adopters’ growth curves for high-connectivity random graphs \( (K = 40) \) and \( F = 3 \). This time the typical S-shaped curves show up provided the initial cultural diversity \( q \) is not too small. We did not find evidence of a multicultural regime in the thermodynamic limit in this case. For instance, the large \( t \) portion of the curve for \( q = 128 \) moves up as \( N \) increases eventually reaching the consensus regime (see [21] for a brief discussion of the phase transition in such random graphs). Figure 10 shows that in the consensus regime the number of innovators scales linearly with \( t \). More generally and in contrast to the case \( K = 2 \), we find \( \gamma = 1 \) for \( K > 2 \) regardless of the parameters \( F \) and \( q \), provided that the introduction of the innovation is successful. It is also instructive to evaluate the mean time \( t^* \) to reach a consensus absorbing configuration for the data shown in figure 10. In fact, figure 11 shows that the mean freezing time grows linearly with the number of nodes \( N \), which is somewhat surprising since for a regular lattice the freezing time scales with the square of the number of sites [17]. The high connectivity of the graphs is probably accountable for this change in the scaling of \( t^* \) with \( N \). In addition, since only the consensus regime is observed in our simulations we have \( N \xi \to N \) in the very long-time (saturation) limit.

As in the analysis of the regular lattices, we find that the long-time dynamics in the consensus regime is not affected by the parameter \( q \). This is expected: in the initial configuration, \( q \) yields the number of different states that a given cultural feature can take on and as the dynamics proceeds towards a consensus absorbing configuration the
social influence acts so as to decrease that number, leading eventually to a situation, in
the limit of very large $t$, where each feature exhibits only two distinct states. Hence in
the consensus regime the asymptotic behavior of the dynamics should not depend on
$q$ or, more pointedly, for an infinite lattice the model should behave as if $q = 2$ in the
limit $t \to \infty$.

6. Conclusion

The focus of this study was on the spreading of an innovation in a decentralized diffusion
system in which the exchange of information among the potential adopters of an

Figure 8. Mean number of adopters as a function of time for random graphs
with (bottom to top) $N = 200, 400, 800, 1600, 3200, 6400, 12800$ nodes and average
connectivity $K = 2$ for $F = 3$ and $q = 2$. The dashed (blue) line indicates that
the number of adopters scales with $t^{0.68}$ in the limit $N \to \infty$. The total number of
independent runs is $10^4$ and in each run we used a different random graph.

Figure 9. Mean number of adopters as a function of time for random graphs with
$N = 800$ nodes and average connectivity $K = 40$ for $F = 3$ and (top to bottom)
$q = 2, 4, 8, 16, 32, 64, 128$. The total number of independent runs is $10^4$ and in
each run we used a different random graph.
innovation is the main mechanism through which innovations spread [1]. Alternatively, we could also consider a centralized diffusion system in which the innovation is pre-sented to the individuals by an external source such as a global media [22]. In the framework of Axelrod’s model, the media is viewed as a global external field and its effects have been studied in great detail in the statistical physics literature [23–27]. In contrast to our findings for the decentralized diffusion system, the relaxation to the absorbing configurations in the presence of the external field is much faster than the relaxation in its absence, and this very rapid relaxation results in concave growth curves for the number of agents who adopted the states of the external field.

In fact, although Axelrod’s model accommodates the two key ingredients—homophily and social influence—necessary to describe the spreading of an innovation
in a community, it does not always reproduce the classical S-shaped growth curves for the number of adopters of an innovation [1]. For finite populations in general and for infinite populations in the multicultural regime, the saturation part of the sigmoid growth curves is easily reproduced in the limit of large $t$, of course. Since for short times the number of adopters grows linearly with $t$, regardless of the network topology, the existence of an inflection point requires an intermediate stage of superlinear growth. Such stage appears as a marginal quirk in the one-dimensional lattice (see curve for $q = 11$ in figure 3) which is imperceptible when plotted in a linear scale. In the square lattice, the superlinear growth stage appears only in a narrow crossover region between the consensus and the multicultural regimes (see figure 6).

The requirement of an intermediate stage of superlinear growth for the existence of an inflection point in the adopters’ growth curves for finite systems can be justified as follows. First, we note that for all the network topologies considered in this paper our simulations have revealed that the growth curves are linear in the short-time regime and that the linear coefficient $v$ is given by equation (4). Second, we note that for finite systems the number of adopters saturates in the long-time regime, where the growth curves are concave functions of $t$. These two extremes can be joined continuously by a concave growth curve such as those shown in figure 7, for which the first derivatives decrease continuously from the value $v$ at $t = 0$ to the value 0 in the limit $t \to \infty$. Third, we note that to exhibit an inflection point a growth curve must have an intermediate region where its first derivative is larger than $v$. In fact, joining the short-time portion of the curve (a derivative equal to $v$) with this intermediate portion (a derivative greater than $v$) produces a region where the growth curve is convex. Since close to the saturation regime the curve is concave there must exist an inflection point at which the concavity of the curve changes. Finally, we note that since it is not possible to have a continuously differentiable growth curve by joining two linear segments (i.e. the segment with a linear coefficient $v$ and a hypothetical segment with a linear coefficient greater than $v$), then the growth curve must exhibit a stage of superlinear growth.

Our analysis of the diffusion of innovations in random graphs suggests that the desired S-shaped growth curves emerge from the trade-off between the average connectivity $K$, which must be large enough to guarantee a superlinear speedup of the number of adopters, and the initial per-feature diversity $q$, which has the effect of reducing the probability of interactions and hence of slowing down the spreading of the innovation. The interplay between these parameters is illustrated in figures 7 and 9. For low-connectivity random graphs (see figure 7), after the initial linear spreading the number of adopters grows sublinearly with $t$ and so the growth curves are concave functions of the time regardless of the value of $q$. This is probably an effect of the existence of many weakly connected subgraphs with bottlenecks that hinder the transmission of the innovation between them. The recipe to produce an inflection point for high-connectivity random graphs is to begin the spreading with a low rate $v$ (the earlier adopters stage), which can be achieved by choosing a large value of $q$, according to equation (4), and wait till the number of adopters reaches a critical value (approximately 100 adopters at $t \sim 10^3$ for the parameters of figure 9). The high connectivity of the graph will then ensure a superlinear spreading (the take-off stage) and a quick saturation (the later adopters stage) due to the finitude of the graph.
From a theoretical perspective, however, a more quantitative and unambiguous characterization of the process of diffusion of innovations is obtained by studying the approach to the consensus regime in an infinite lattice, i.e. by determining how the number of adopters scales with $t$ in the limit $t \to \infty$. In particular, our Monte Carlo simulations indicate that in this limit Axelrod’s model in the presence of the innovator behaves as the voter model in the presence of a zealot, and so the number of adopters grows with $t^{1/2}$ for the one-dimensional lattice and with $t/\ln t$ for the two-dimensional lattice [7]. In that sense, the spreading is diffusive in one dimension and sub-diffusive in two dimensions. For random graphs with average connectivity $K > 2$ we find that the number of adopters grows with $t^\gamma$ where $\gamma = 1$. Our finding that $1/2 < \gamma < 1$ for $K = 2$ indicates that the value of this exponent is sensitive to the network topology and so it may be a useful measure to compare the efficiency of the process of diffusion of successful innovations in different scenarios.

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