Analysis of thermal models to determine the loss of life of mineral oil immersed transformers

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ABSTRACT

Hot spot as well as top oil temperatures have played the most effective parameters on the life of the electrical transformers. The prognostication of these factors is very vital for determining the residual life of the electrical transformers in the transmission and distribution systems. Thus, an accurate mathematical method is required to calculate the critical temperature such as hot spot and top oil temperature based on the different types of thermal models. In this study calculates the service life of the transformers based on an accurate top oil temperature. Accordingly, An approach solution is given for calculating the thermal model. Also, findings are validated with true temperatures. Finally, this method is implemented on 2500 KVA electrical transformer.

Keywords:
Electrical transformer
Hot spot temperature
Numerical analysis
Thermal model

1. INTRODUCTION

Electrical transformers the facilities in electrical power networks that the correct operation of it has played main role in providing reliability of these systems. By noticing the costs of transformers and permanent connection of transformers to transmission and distribution systems, any action to increase the life cause improvement in the operation of power systems. Life of the electrical transformer and loading capabilities of this facilities depend on several parameters. Oil and paper in transformers are two insulation materials, that the integrity of them warranties the life of transformers. Hot spot temperature (HST) and top oil temperature (TOT) are two criteria to evaluate the integrity of these two insulation materials and transformers as important facility in power network [1]-[3]. These criteria determine the temperature limitation of transformer for loading capability, for example the IEEE standard suggests that the TOT rise over ambient temperature 65°C and depending on it has considered 110°C for HST [4]-[6]. It means that increasing the temperature of transformer over this standard value causes the degradation of insulation life of transformer. According to research, from 90°C to 110°C, the aging rate of tensile strength approximately doubles every 5°C to 10°C temperature rise [2], [3], [7]-[9]. A. A. Taheri, A. Abdali and A. Rabiee [10] a thermal resistance with solar radiation is used to explain the heat transfer theory in transformer. The effect of
long term ambient temperature was investigated in [11], [12]. There are some dynamic factors in oil immersed transformer such as ambient temperatures, winding losses and oil viscosity of transformer [3], [13]. In this article, two thermal models, classic thermal model as famous and reliable thermal model and dynamic thermal model as improved thermal model, has been used. Moreover, TOT and HST is calculated for both thermal model by IEEE standard method that has been available in [3] and also these temperatures are calculated by proposed method. To validate and show the tolerance of numerical technique, the results of models compared with measured value.

2. LITERATURE REVIEW
2.1. Thermal model
2.1.1. Classic thermal model

Thermal model is used to estimate the critical temperature of the transformer. The classic one was given base on the heat generated and distributed in the windings and oil of transformer [3], [9]. Figure 1 shows temperature distribution in the transformer.

The classic thermal model is used by a differential equation as [3]:

\[ T_0 \frac{d\theta_{top}}{dt} = -\theta_{top} + \theta_u + \theta_{amb} \quad (1) \]

The solution as:

\[ \theta_{top} = (\theta_u + \theta_{amb} - \theta_{topi})(1 - e^{-\frac{t}{T_0}}) + \theta_{topi} \quad (2) \]

and

\[ \theta_u = \theta_{fl} \left[ \frac{I_{ph} R + I}{R + 1} \right]^n \quad (3) \]

\[ T_0 = \frac{C \theta_{fl}}{P_{fl}} \quad (4) \]

where:
- \( \theta_{topi} \): Top-oil rise over ambient temperature (C)
- \( \theta_u \): Ultimate top-oil rise for load L (C)
- \( \theta_{fl} \): Initial top-oil rise for t=0 (C)
- \( \theta_{fl} \): Top-oil rise over ambient temperature at rated load
- \( T_0 \): Time constant
- \( n \): Oil exponent

Figure 1. The temperature distribution in the transformer
$I = $Specified load  
$I_{rated} =$Rated load  
$I_{pu} =$Ratio of specified load to rated load  

The transient rise of the hottest spot of the winding higher than the upper limit of the oil temperature is determined by the following formula [3]:

$$\Delta \theta_H = (\Delta \theta_{H,U} - \Delta \theta_{H,i}) \left[ 1 - \exp^{-\frac{t}{\tau_0}} \right] + \Delta \theta_{H,i} \quad (5)$$

That the initial value for hot-spot temperature rise over top-oil temperature is given by:

$$\Delta \theta_{H,i} = \Delta \theta_{H,R} I_{pu}^{2m} \quad (6)$$

The maximum hot spots are as follows:

$$\Delta \theta_{H,U} = \Delta \theta_{H,R} I_{U,pu}^{2m} \quad (7)$$

The nominal hottest temperature spot value is given by:

$$\Delta \theta_{H,R} = \Delta \theta_{H/A,R} - \Delta \theta_{TO,R} \quad (8)$$

where:  
\- $\Delta \theta_{H,R} =$Hottest temperature spot rise over top oil temperature (C)  
\- $\Delta \theta_{H,U} =$Maximum hottest temperature spot rise over maximum oil temperature for load (C)  
\- $\Delta \theta_{H,i} =$Initial hottest temperature spot rise over top oil temperature for $t = 0$ (C)  
\- $T_0 =$time constant of the transformer winding (h)  
\- $t =$Loading time (h)  
\- $\Delta \theta_{TO,R} =$Nominal hot spot rising above maximum oil temperature (C)  
\- $I =$Current of load per unit  
\- $M =$The exponent determines the non-linearity as shown in Table 1  
\- The manufacturer has specified the amount of $n$ for each mode of cooling. The amounts of $n$ and $m$ for each cooling method are shown in Table 1 [3].  

| Table 1. Exponents for temperature determination formulas |
|---------------------------------|--------|--------|
| cooling                      | $M$   | $N$   |
| OA                           | 0.8   | 0.8   |
| FA                           | 0.8   | 0.9   |
| Non-directed FOA or FOW      | 0.8   | 0.9   |
| Directed FOA or FOW          | 1     | 1     |

HST will be calculated by (9).

$$\theta_{HST} = \Delta \theta_{TOT} + \Delta \theta_{HST} + \theta_{amb} \quad (9)$$

### 2.2.2. Dynamic thermal model

Firstly, A dynamic thermal model of electrical transformer has been offered by Swift based on the principals of heat transfer theory [14]-[17] after that an improved model has been introduced by Susa by assuming the non-linear thermal oil resistance base on swift’s approach. In Susa’s model the variations of viscosity with temperature were considered [9]. TOT of dynamic thermal model is governed by (1).

$$\frac{14\times K R}{\tau_{fl}} \times \mu_{pu} \times \theta_{fl} = \mu_{pu} \times \tau_{0} \times \frac{d\theta_{oil}}{dt} + \frac{(\theta_{fl} - \theta_{amb})^{1+m}}{\tau_{fl}} \quad (10)$$

Oil viscosity is added as a parameter. This can be determined by [18].

$$\mu_{pu} = e^{\frac{2797.3}{\theta_{top}+273}} \left( \frac{2797.3}{\theta_{fl}+273} \right) \quad (11)$$

where:  
\- $K =$load current per unit  
\- $R =$proportionality of load to no-load losses  
\- $\tau_{0} =$top oil time constant, (min)  
\- $\theta_{fl} =$rated top oil rise over ambient, (K)
\( \theta_{oil} \) = top oil temperature gradient, (K)
\( \theta_{amb} \) = ambient temperature, (K)
\( \mu_{pu} \) = oil viscosity per unit

\( n \) = empirical constant, the amount of \( n \) has been specified for each cooling mode in Table 2 [2].

| Oil circulation       | With cooling | without cooling |
|----------------------|--------------|-----------------|
| Initial oil circulation, Speed=0, (cold start) | ONAF/OFAF 0.5 | 0 ONAN 0.25 ONAN 0.25 |
| Initial oil circulation, Speed>0, (transformer on load) | 0.2 | 0.25 |

HST of dynamic thermal model is given as [19]:

\[
[K^2 \times P_{wd,pu}] \times \mu_{pu} \times \Delta \theta_{hs,\text{rated}} = \mu_{pu} \times \tau_{wd,\text{rated}} \times \frac{d\theta_{hs}}{dt} + \left( \frac{(\theta_{hs}-\theta_{oil})^{n+1}}{\theta_{hs,\text{rated}}} \right)
\]

(12)

P\(_{wd,pu}\) is the load loss’s dependence on temperature that can be determined by (13)

\[
P_{wd,pu} = P_{dc,pu} \times \left( \frac{\theta_{hs}+\theta_{k}}{\theta_{hs,\text{rated}}+\theta_{k}} \right) + P_{eddy,pu} \times \left( \frac{\theta_{hs,\text{rated}}+\theta_{k}}{\theta_{hs}+\theta_{k}} \right)
\]

(13)

The behavior of the eddy losses and DC losses are shown in Peddy and Pdc respectively. DC loss is directly proportional to temperature, while eddy current loss is inversely proportional to temperature. \( \theta_k \) is the temperature coefficient of loss correction. Aluminum is equal to 225 and copper is equal to 235.

Oil time constant (\( \tau_0 \)) is one of the most important parameters that should be determined accurately. Note that, there are specific methods for each thermal model to determine \( \tau_0 \). The oil time constant for dynamic thermal model is given by [20]: Note that, (14) is based on minute and (15) is per hours and depends on whether per hours or minutes have to be changed and for data which collected per hours it shouldn’t multiply by 60, it means that the oil time constant does not need to convert to minutes.

\[
\tau_0 = \frac{C_{ch-al} \times \Delta \theta_{oil,\text{rated}}}{P_{total}} \times 60
\]

(14)

\[
\tau_0 = \frac{C_{ch-al} \times \Delta \theta_{oil,\text{rated}}}{P_{total}}
\]

(15)

3. RESEARCH METHOD

3.1. Solving techniques

3.1.1. IEEE standard method

IEEE standards C57.91-1995 has offered an exponential method based on the (14) to calculate the TOT to determine the HST of transformers for classic thermal model [3]. In (14) is derived from (1) [21].

\[
\Delta \theta_{TO} = (\Delta \theta_{TO,U} - \Delta \theta_{TO,I}) \left[ 1 - \exp^{-\frac{t}{\tau_0}} \right] + \Delta \theta_{TO,I}
\]

(16)

The ultimate value of top oil ascent for each stage is calculated by,

\[
\Delta \theta_{TO,U} = \theta_{f1} \left[ \frac{(\frac{P_{pu,R+1}}{R+1})}{(R+1)} \right]^n
\]

(17)

For calculating the initial value for the first time, \( t=0 \), knowing the record of loading profile can be so useful. The current at \( t=0 \), determined by RMS value of the loading currents for the former loadings [3]. Equation (3.5) can be used to estimate the initial value for other steps to calculate the top-oil temperature rise.

\[
\Delta \theta_{TO,I} = \theta_{f1} \left[ \frac{(\frac{P_{pu,R+1}}{R+1})}{(R+1)} \right]^n
\]

(18)

3.1.2. Numerical method

Numerical methods are used to solve the ordinary differential equation. In this study, two types of numerical solvers are compared to determine the thermal-electrical models. The first model is related to
Euler's method and is the simplest solver. Although this model is not an appropriate solver in most utilization, it reveals some common characteristics among different types of solvers. Runge-Kutta is the second type of solver, which is used in this paper. The fourth-order Runge-Kutta technique is the most widely used solution method. This solution technique, which begins with an initial value \( (t_0,y_0) \), has four slopes,

\[
K_1 = f(t_0, y_0), \quad K_2 = f(t_0 + \frac{h}{2}, y_0 + \frac{h}{2}K_1), \\
K_3 = f(t_0 + \frac{h}{2}, y_0 + \frac{h}{2}K_2), \quad K_4 = f(t_0 + h, y_0 + hK_3)
\]  

(19)

With these slopes, the next value of the dependent variable can be determined as,

\[
y_k = y_{k-1} + h \frac{K_1 + 2K_2 + 2K_3 + K_4}{6}
\]

(20)

TOT and HST of transformer can be computed for dynamic thermal model according to the algorithm has been given in Figure 2. The input data can be classified in two groups, constant and variable input data. Constant data are \( n, m, \) weight of the oil per kg, load losses and no-load losses, oil time constant and winding time constant, DC and eddy losses, And the hot spot temperature under rated load. While variable input data that can be changed by time include current or loading of transformers and ambient temperature.

![Diagram of the algorithm](image)

* N is total number of load current that are collected.

Analysis of thermal models to determine the loss of life of mineral oil … (Mohammad Tolou Askari)
3.2. The loss of life of the transformer

The quality of paper and oil which are applied in electrical transformer is directly proportional to the efficiency of it. However, the deterioration of paper can determine the loss of life (LOL) the mineral oil immersed transformers. Heat, oxygen and moisture are the most important factors to deteriorate the paper of electrical transformers. Insulation degradation can be simulated as a quantity per unit and calculated as [4], [22];

\[ per\text{-}unit\text{-}life = Ae^{\frac{H}{H_{\text{SHT} \times 273}}} \]  \hspace{1cm} (21)

where: \( A \) = is an adjusted constant based on the temperature determined for a per unit life,
\( B \) = is the slope rate of aging.

IEEE standard C57.91-1995 considered \( B=15000 \) is appropriate and is used in per-unit-life equation for loading of transformers. For \( \theta_{\text{HST}}=110 \, ^\circ \text{C} \), and per-unit-life=1, the value of \( A \) constant becomes \( 9.8 \times 10^{-18} \). The aging factor can be calculated [3], [23]

\[ F_{AA} = e^{\frac{15000}{383 - \frac{15000}{\theta_{\text{HST}} + 273}}} \]  \hspace{1cm} (22)

The equivalent aging of the electrical transformer based on reference temperature for hottest spot is \( 110^\circ \text{C} \) could be calculated as [3], [24], [25]:

\[ F_{\text{EQA}} = \frac{\sum F_{AA} d t_n}{\sum d t_n} \]  \hspace{1cm} (23)

where:
\( F_{\text{EQA}} \) = aging factor
\( n \) = time interval index
\( N \) = total time duration
\( \Delta t_n \) = time interval

And, the percentage of LOL can be determined as [26], [27]:

\[ \% \text{loss of life} = \frac{F_{\text{EQA}} \times 100}{N \, \text{NIL}} \]  \hspace{1cm} (24)

3.3. Empirical tests for case of study

3.3.1. Three phase 2500 KVA transformer

The ratio of voltage of 2500 KVA transformer is 20/0.4 KV, and without external cooling, ONAN. Three different loading currents are considered in this paper that are shown in Table 3. For this transformer the low voltage and high voltage windings have one and two axial cooling duct respectively. The transformer equipped by 17 thermocouples located as follows: One is mounted 50 mm under the tank cover of electrical transformer, 2 sensors in the oil enclosure, 4 sensors is located on the bottom of outside surface of the tank, 2 in the bottom of the tank, 4 in duct outlet in top and bottom, 4 in duct inlet in top and bottom.

| Time intervals (minutes) | Load (PU) |
|-------------------------|-----------|
| 0-300                   | 1         |
| 300-382                 | 2         |
| 382-415                 | 0         |

3.3.2. Three phase 30 MVA transformer

The voltage ratio of this transformer is 33/11 KV. Also, cooling system is oil natural and air force (ONAF). 3 thermometers are used to indicate the winding and top oil temperatures for high and low voltage windings. Also, they are used for collecting ambient temperature. This data is necessary to verify the suggested techniques provided in this article. The output of the thermometer is a function of the 4 to 20 mA current that must be converted to temperature (C).

4. RESULTS AND DISCUSSION

HST of each transformer has been plotted for both distribution transformers. LOL of transformers for each thermal model has been compared with measured value and were indicated in Tables 4 and 7 for
classic thermal model and Tables 5 and 8 for dynamic thermal model. Finally, Tables 6, and 9 tabulate the error of numerical methods rather than exponential method. By comparing the error of each thermal model for 2500 KVA transformer, which is demonstrated in Tables 4 and 5, the less error of dynamic thermal model rather than classic thermal model is comprehensible. These errors for numerical methods are less than exponential method.

4.1. 2500 KVA transformer

2500 KVA transformer was tested for 415 minutes. Figure 3 shows the comparison between the measured HST and HST achieved by the numerical methods and exponential method. Graphs have been plotted based on the classic model. Figure 4 shows the comparison of the hot spot temperature of a 2500 KVA transformer with the hot spot temperature calculated using two numerical methods (RungeKutta and Euler methods). This graph has been plotted based on the dynamic thermal model.

In Tables 4 and 5 show the comparison between the errors achieved for classis and dynamic thermal models respectively. These errors given the differences between the numerical methods and exponential methods with measured. In addition, the loss of life of the 2500 KVA transformer is compared with measured
value in the Table 6 for two types of the thermal models. Thermal models have been calculated based on R-K technique. This comparison shows that the accuracy of the dynamic thermal model is higher than that of the classical thermal model.

| Table 4. Classic thermal model of 2500 KVA transformer (ERROR OF LOL) |
|-------------------------------------------------------------|
| Error for RK4 $| (LOL_NUM - LOL_Measured) | Error of exponential $| (LOL_IEEE - LOL_Measured) |
| 1.7052 | 2.7643 |

| Table 5. Dynamic thermal model of 2500 KVA transformer (ERROR OF LOL) |
|-------------------------------------------------------------|
| Error for RK4 method $| (lolRK4 - lol_Measured) | Error for Euler method $| (lol.Euler - lol_Measured) |
| 0.7806 | 1.4912 |

| Table 6. Error of thermal models: Different solving technique |
|-------------------------------------------------------------|
| Numerical technique $| (Dynamic thermal model) | Numerical technique $| (Classic thermal model) | Exponential technique $| (Classic thermal model) |
| 0.2358 | 2.2503 | 2.7643 |

5. CONCLUSION

Several thermal models and solution are suggested for solving various thermal models to calculate the TOT and HST of transformer due to loss of life evaluation. These methods involved linear and nonlinear regression and exponential methods that are proposed by IEEE standard. Numerical methods can be used as solution to calculate the thermal model, R-K technique is an improved numerical method proposed in this research for solving two types of thermal models the first one is classical thermal model that was suggested by IEEE standard C57.91-1995 and the second one is thermal-electrical model or dynamic thermal model that assumed number of variable parameters such as viscosity of oil, ambient temperature, eddy losses. According to the results the proposed technique for solving the thermal models shows improved accuracy over the traditional methods.

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