Detectors and Concepts for sub-100 ps timing with gaseous detectors

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ABSTRACT: We give a short compendium of the main ongoing detectors and concepts capable of performing accurate sub-100 ps timing at high particle fluxes and on large areas, through technologies based on gaseous media. We briefly discuss the state-of-the-art, technological limitations and prospects, and a new bizarre idea.

KEYWORDS: Gaseous detectors; Instrumentation and methods for time-of-flight (TOF) spectroscopy

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1 Introduction

Contemporary gaseous detectors relying on the resistive plate chamber (RPC) technique \cite{1, 2} provide already, quite effortlessly, time accuracies around 100\,ps-$\sigma$ for both ionizing and non-ionizing radiation thanks to the multi-gap concept \cite{3, 4}. Their range of demonstrated applicability encompasses the minimum ionizing particles (mips) characteristic of high energy particle physics (e.g.: ALICE at LHC \cite{5}, STAR at RHIC \cite{6}, or HADES at SIS \cite{7}), $\gamma$-rays \cite{8}, relativistic neutrons \cite{9} and heavy ion fragments up to $Z = 54$ \cite{10, 11}. They are employed in 100\,m$^2$-size systems as long as the flux of incoming particles does not exceed 1\,kHz/cm$^2\,$mip-equivalent ($\sim 2\,$nA/cm$^2$), during live-times corresponding to several years and to 10’s of mC/cm$^2$, at least. The widespread commercial use of float glass, that is commonly used to make the resistive plates, together with its relatively good radio-frequency behaviour and good understanding of the signal propagation characteristics \cite{12, 13}, pushes the maximum realizable module sizes beyond the demand of any present or future experiment, reaching 2\,m of length (e.g., \cite{14}). With the introduction of Chinese glass in \cite{15}, detectors can be operated without degradation of timing performance up to $\sim 20$\,kHz/cm$^2$, albeit at the price of a reduced module size down to 30\,cm $\times$ 30\,cm.

While it seems clear that RPCs can increasingly approach and establish the 100\,kHz/cm$^2$ (mip-equivalent) landmark in small detectors \cite{16}, it is at present doubtful that they can reach any time soon the rate capability that Micro-Pattern Gaseous Detectors (MPGDs) intrinsically provide, well above 10\,MHz/cm$^2$ \cite{17}, with detector sizes already at the m$^2$-scale \cite{18}. On the negative side, proportional detectors based on wires or MPGDs present, historically, a strong limitation for timing related to the physical jitter stemming from the collection time of the primary ionization. To avoid this limitation, while preserving their characteristic high rate behaviour, an intriguing scheme has been recently resurrected and is later discussed.

We will briefly present here some of the most fashionable ideas for the sub-100\,ps detection of charged particles with gaseous detectors at high particle flux (section 2), and large areas (section 3).
together with the present technological limits (section 4). In section 3 we elaborate on the concept of ‘compensation’, an idea that holds the promise for virtually unlimited detector sizes. For a recent overview on next-generation timing detectors the reader is referred to [19], while an overview on the RPC field can be found in [20].

2 Timing at high particle flux

2.1 Timing-RPCs

The time resolution of Resistive Plate Chambers can be approximated through [21], as:

\[ \sigma_t(E) = \frac{1}{\sqrt{N}} \sqrt{\frac{\lambda_0}{g} \frac{M}{(\alpha(E) - \eta(E))v_d(E)}} \quad (2.1) \]

where \( N \) represents the number of gas gaps and \( g \) their size, \( \lambda_0 \) is the mean free path of the impinging particle before an ionizing encounter, \( \alpha(E) \) and \( \eta(E) \) are the multiplication and attachment coefficients, \( v_d(E) \) is the drift velocity and \( M \) is a factor of order 1 that accounts for the avalanche statistics, and for the fact that not all primary ionizations contribute equally at threshold level.\(^1\) It turns out that correlations (mostly between \( \alpha(E), \eta(E) \) and \( g \)), introduced once a certain operating gain is required, invert the explicit dependency with the gap size given by eq. (2.1): experimentally, the best time resolutions are found for narrow gaps.\(^2\)

It is strongly hinted by data and models [22–24] that the main source of degradation of timing RPCs at high particle flux is due to the average field drop in the gas gap, that is caused by the current flowing through the resistive plates:

\[ \Delta E = \frac{1}{g} \bar{q} \bar{\phi} \rho d^* \quad (2.2) \]

and event-by-event field fluctuations seemingly play a minor role [22]. In eq. (2.2), \( \bar{q} \) is the average charge per gap, \( \rho \) the resistivity of the plates and \( d^* \) their equivalent thickness per gap, with \( \bar{\phi} \) being the average particle flux over the irradiated area [23]:

\[ \bar{\phi} = \frac{\int \int (\phi(x,y))^2 dx dy}{\int \int \phi(x,y) dx dy} \quad (2.3) \]

The above approximation is often referred to as ‘the DC model’.\(^3\) By assuming a recursive dependence of \( \bar{q} \) with the field, \( \Delta E \) can be exactly obtained in a number of practical cases [16, 22, 26], but in the following argument we consider the case of small field drops, where \( \bar{q} \) can be taken as

\(^1\)The latter effect can be included through the ‘effective fraction of gap’ \( g'/g \), whose value nears 0.5 [21].

\(^2\)For a simple image note that the product of \( \alpha(E) - \eta(E) \) and \( g \) is bound to an approximately constant value, that can be intuitively viewed as some form of ‘Raether criteria’.

\(^3\)A transient behaviour prior to reaching the stationary conditions (under which the DC model applies) can be observed at high particle flux, with a characteristic time scale \( t_{eq} \sim \frac{\tau}{K g \rho d^*} \). Here \( \tau \) is of the order of one second for float glass and \( K = \frac{1}{K} \frac{d\bar{q}}{d\bar{\phi}} \) [22, 24, 25].
approximately constant. After introducing the most recent low-pressure measurements for the main RPC gas (C$_2$H$_2$F$_4$) of $\alpha(E) - \eta(E)$ and $v_d(E)$ [27], we come to:

$$S(E) = (\alpha(E) - \eta(E))v_d(E) \approx \frac{dS}{dE}(E - E_0)$$

(2.4)

a linear approximation that is valid in the typical operating regime of timing RPCs ($E \approx 100$ kV/cm). A simple derivation follows as:

$$\frac{\Delta\sigma_t}{\sigma_t}(\bar{\phi}) \approx \frac{1}{S_0} \frac{dS}{dE} \Delta E$$

$$\approx 50\% \times \frac{\bar{\phi}}{1 \text{ kHz/cm}^2} \times \frac{\rho d}{3 \cdot 10^{12} \Omega \text{cm} \times \text{mm}}$$

(2.5)

(2.6)

For the evaluation of the above expression we have taken typical values: for the charge $\bar{q} = 2$ pC, for the ionization rate $S_0$ we assume a typical field of 100 kV/cm, and finally $g = 0.3$ mm. The column resistivity appears referred to that of 1 mm of float glass (3 · 10$^{12}$ Ω cm × mm).

Through expression 2.6 it is hence made explicit that operation at 1 kHz/cm$^2$ can be only reasonably achieved for very thin float-glass, clearly being at the limit of the technology in any case. Chinese glass, with a value for $\rho \approx 3 \cdot 10^{10} \Omega \text{cm}$ (at 20$^\circ$C) can improve this figure by approximately 2 orders of magnitude. Materials with resistivities below $\rho \approx 10^{10} \Omega \text{cm}$ often show poor streamer quenching, resulting in a worsening of the time resolution. Therefore, with today’s understanding, a maximum particle flux around 100 kHz/cm$^2$ represents a good estimate of the RPC technological horizon. A version of the scaling given by eq. (2.6) for a number of materials can be found in [28].

### 2.2 MPGDs

MPGDs make extensive use of photo-lithographic techniques in their fabrication, but the range of construction techniques has also expanded towards providing resistive protection either via embedded resistors, screen-printing, surface dissipation over thin foils, or a combination of them (see for instance [29] and references therein). In some configurations (e.g., triple-GEM), discharge probability can be made negligible small for gains around 10$^5$ even in the presence of highly ionizing radiation [18]. The ultimate rate capability of MPGDs when globally considering the effect of either a resistive protection or the damage caused by residual discharges is difficult to quantify at present, but results recently obtained under 5.9 keV X-rays in [17] (≈ 250 initial electrons) indicate that they can reliably operate up to at least 10–100 MHz/cm$^2$ when irradiated by mips. Apparently, the only insurmountable problem for accomplishing timing in these harsh conditions is the physical jitter on the collection time of the ionization produced in the so-called ‘drift region’. A solution to this long-standing problem, that had already shown a time resolution of 680 ps per single electron in early detectors [30], has been recently re-introduced by making use of modern manufacturing techniques.

The idea here is to resort to the emission of Cherenkov photons when the impinging particle crosses an auxiliary MgF window, photons that are converted to electrons via a CsI layer in contact with the gaseous medium. The proposal embodies two additional regions (‘drift’ and ‘amplification’) separated via meshes in a Micromegas-fashion, a geometry aimed at providing the necessary flexibility in terms of ion and photon-feedback suppression. In a recent work [31] a time
resolution per single photo-electron of 200ps was achieved, a value largely determined, according to simulation, by the diffusion of the electrons during their transit along the drift region:

\[ \sigma_t(E) = \frac{A}{\sqrt{n_{pe}}} \frac{D^*_L(E)}{v_d(E)} \sqrt{g} \]  

(2.7)

In eq. (2.7) \( n_{pe} \) is the average number of photo-electrons, \( D^*_L \) the longitudinal diffusion coefficient in units of \([L^{1/2}]\), \( v_d \) the electron drift velocity and \( g \) the thickness of the drift region [31]. According to simulation, the presence of pre-amplification improves the time resolution by a value of typically \( A \sim 0.5–1 \). The good statistical scaling with \( \sqrt{n_{pe}} \) projects a time resolution at the scale of 20–40ps for minimum ionizing particles when using windows with thicknesses at the few mm-scale, something that is currently being studied in beam.\(^4\)

3 Timing on large areas

Once a given position resolution is targeted by design, and as long as particle multiplicity is low, layouts based on strips show a linear scaling with the detector size and those based on pads a quadratic one. Besides, specially for a timing device, there is a natural limit to the maximum area of the pad due to capacitive effects, that does not exist in the case of strips, or at least manifests itself much more mildly [33]. Hence, and by virtue of their large simplicity of construction, we focus here on the ‘multi-strip RPC’ concept [34].

3.1 Modal dispersion and its compensation

Multi-strip RPCs are highly dispersive devices in a form commonly known in transmission line theory as ‘modal dispersion’ [35], a phenomenon that can severely impair operation. Apparently, the notion of the possible existence of modal dispersion in gaseous detectors was first postulated in 2002 by W. Riegler [36], indirectly confirmed in [37] and finally measured in [12] on a 2m-long double-strip timing RPC excited externally. During the XIII RPC Conference several groups reported high levels of cross-talk and a strong dependence of the time resolution with the position of the impinging particle [38, 39], a text-book example of the manifestation of modal dispersion. Transmission and cross-talk patterns observed and simulated in one of these detectors (BGOegg) are given in figure 1 for signals induced at three different positions along one of the strips.

It is pertinent to note at this point, before further elaboration, that the study and interpretation of cross-talk and dispersive patterns in resistive gaseous detectors dates back to the times of the Iarocci tube, at least [40]. These early studies, that included as well the direct effect on the induced signals (‘signal transparency’) were followed by a number of theoretical works in [41–44], focused on the resistive and capacitive behaviour. A 3D-simulation implicitly including inductive and capacitive effects was made available in 1997 for the Pestov counter [45], but the relatively small electrical length of the system \( \Lambda_e \) ([12]) did not lead to a sizeable dispersion. Similar to the Pestov counter, modern RPCs usually operate in conditions of full signal transparency and the influence of the materials’ resistivity both in signal induction and propagation is negligible. On the other hand, the large electrical lengths (up to \( \Lambda_e = 40 \)) lead to a strong

\(^4\)During the refereeing process, preliminary results have been presented in [32], confirming these early expectations.
signal dispersion due to the presence of different travelling modes, a genuine inductive/capacitive phenomenon. Modal dispersion can dominate critical parameters for signal propagation (like signal rise-time and cross-talk) and it is, perhaps, most readily appreciated in particle detectors through the difference between the near-end and far-end crosstalk patterns (e.g., figure 1 and [12]). Its underlying principles and importance for particle detectors, that are described in detail in a series of recent works ([12, 13, 33, 36, 37]), are sketched below.

A priori, modal dispersion is a feature inherent to the propagation along any inhomogeneous dielectric that can be assimilated to a multi-conductor transmission line (in particular, a multi-strip RPC). It results from an imbalance between the capacitive and inductive coupling of the line, a condition that reads, with approximate character, as:

\[
\frac{C_m}{C_0} \neq \frac{L_m}{L_0}
\]

(and it is useful to recall that: \( \frac{L_m}{L_0} \approx \frac{C_m}{C_0} \)) \hspace{1cm} (3.1)

In eq. (3.1) \( C_m \) refers to the mutual capacitance (capacitance between neighbouring strips), \( C_0 \) is the total strip capacitance, \( L_m \) is the mutual inductance between neighbouring strips and \( L_0 \) is the strip self-inductance; an additional sub-index 0 refers to the values obtained by replacing all dielectrics by vacuum. Under approximations of general validity for RPCs (‘short-range coupling’: \( \frac{C_{m,2}}{C_m}, \frac{C_{m,2}}{C_m} \ll 1 \)), it can be reasoned, without any further approximation [12], that the signal breaks during propagation on as many modes as transmission strips \( (N_s) \), travelling with velocities \( \vec{v} \) that are functions of the imbalance given by eq. (3.1):

\[
\vec{v} = \sqrt{\frac{C_{00}}{C_0}} \vec{f}(\frac{\Delta v}{\bar{v}})
\]

\[
\frac{\Delta v}{\bar{v}} = \frac{C_m}{C_0} - \frac{C_m}{C_0} \frac{\Delta v}{\bar{v}} \tag{3.2}
\]

with \( \vec{f} \) having dimension \( N_s \) and satisfying \( \vec{f}(0) = [1, \ldots, 1] \), and \( c \) is the speed of light. The magnitude \( \Delta v/\bar{v} \) takes a precise meaning in the 2-stripe case, where it represents the relative velocity spread between the two system modes and \( \bar{v} \) is their average velocity [37]. For a generic \( N_s \)-strip RPC one can still make use of this magnitude to define a characteristic delay per unit length as:

\[
\Delta T_y = \frac{1}{\bar{v}} \frac{\Delta v}{\bar{v}} \tag{3.4}
\]

As an example, \( \Delta T_y \) is at the level of 3.5 ps/cm in the geometry studied in figure 1. The net effect of this delay between the modes is the increase of the signal rise-time with the propagation distance \( y_o \) (figures 1, 2). It also plausibly explains the worsening of the time resolution as a function of the distance to the strip ends in 2 m-long counters [38]. This systematic dependence shifts the time resolution from an intrinsic value around 60 ps to slightly above 80 ps at the counter ends, thus compromising the goals of the LEPS2 experiment, for instance. Moreover, in simulation it can be seen that a critical condition exists when \( y_o \Delta T_y \) approaches the rise-time of the induced signal, implying that the modes begin to fully decouple during transmission. This change in behaviour can be clearly seen in figure 2 for propagation distances beyond 140 cm.

What is important to note is that \( \Delta v/\bar{v} \) can be made zero not only in the theoretical limit where the transmission structure is a homogeneous dielectric: one finds indeed a number of possible

\(^{\text{a}}\)\(C_{m,2}\) refers to the capacitance between a strip and its second neighbor.
Figure 1. Left: signals measured in the 1m-long BGOegg prototype for different trigger positions (Area = 1 cm × 1 cm, and centered relative to a given 2.5 cm-wide reference strip), with a cosmic ray stand [46]. The signals are measured at the near-end (NE) and far-end (FE) of the triggered strip (orange/blue) and the first neighbour (pink/green), for three characteristic positions relative to the near-end (5 cm, 25 cm, 50 cm). Right: simulation performed using the same technique as in [12], with dielectric parameters: $\tan \delta = 0.025$, $\epsilon_r = 5.5$ for float glass, $\epsilon_r = 4.4$ for FR4 [12] and $\epsilon_r = 10$ for the HV graphite tape. Each series is normalized to the amplitude of the signals transmitted at the near-end (orange) and, of those, the signal shape corresponding to 1 cm (measured with minimal shaping and not shown here) is used as input for all simulations. Most of the discrepancies seem attributable to the lack of a proper description of the tapered end of the strip (that influences the far-end of both the transmitted and cross-talk signals in the 5cm case, due to an imperfect description of the superposition between direct and reflected waves), the absence of an unbiased estimate of the input current, the small offsets in cables, the position jitter within the trigger region and white noise.
realizations of this condition in a practical detector. We refer to the restoration of this ideal situation as ‘compensation’. Compensation in timing RPCs was demonstrated in [12], and later employed in the STAR-MTD detector [47]. In the LEPS2 case (figure 2), it is relatively simple to modify the detector geometry by interleaving a thin teflon sheet around the central electrodes, thus decreasing the modal dispersion to about 2 ps/cm, and enabling again a reasonable transmission over 2 m.

**Figure 2.** Main signal characteristics as a function of the propagation distance for the LEPS2 detector. From top-left to bottom-right: signal rise-time (from 10% to 90% of the signal maximum), fraction of transmitted signal, fraction of cross-talk signal in 1\textsuperscript{st} neighbour relative to transmitted signal, the same but for the 2\textsuperscript{nd} neighbour. The continuous line shows the result for the default geometry, and the dashed line the expected behaviour after a simple structural modification that would reduce the strength of modal dispersion by about a factor $\times 2$.

The difficulty at conceiving that, in reality, a signal can possibly travel as a decomposition of as many modes as strips (specially being the furthest strip maybe up to one meter apart), was already addressed in one of the first papers on this topic [12]. Basically, in extreme scenarios, and due to the existence of a finite propagation speed, an electrical perturbation may only know about the existence of the furthest strip once it is already exiting the structure! Because Transmission Line Theory assumes electrostatics at every position during propagation, it is implicit to its use that the structure must be electrically short on the transverse dimension, a condition that implies for timing RPC signals a distance of about $\Lambda_e = 5$ cm [12]. This led some authors to argue about the possibility of having ‘not fully organized modes’ [13]. It is important, however, to realize that by virtue of the fact that most RPCs fall under the ‘short range coupling’ approximation ($\frac{C_{m,2}}{C_m} \approx \frac{C_{m,2}^0}{C_m^0} < 1$), the most important coupling takes place to the nearby strips, and those are in any typical detector within
the aforementioned distance. Although this explanation may seem satisfactory, and qualitatively explains the good agreement observed between theory and measurements in the 8-strip detector simulated in figure 1, it still does not provide an answer to the remarkable fact that the travelling signals are decomposed precisely in 8 modes. Only a full 3D-simulation will further clarify these aspects.

3.2 A technological ‘twist’: the Serpentine (Delay-Line) -RPC

Delay-line electrodes represent a relatively popular readout configuration aimed at reducing the number of electronic channels. The geometry is not completely alien to the RPC field, where it is employed to cover large areas for efficiency studies [48]. Without additional modifications, however, RPC detectors are not suited to build well-behaved delay lines, due to the dispersive character introduced by the modal dispersion and its dramatic effects on the inter-strip cross-talk. A simple derivation of the fraction of cross-talk expected for exponential signals \( I \sim \exp[(\alpha - \eta)v_d t] \) is given in [37]:

\[
\hat{F}_{ct} = \frac{I_{ct}}{I_{tr}} \approx \frac{R}{Z_c + R} \frac{C_m}{C_0} + \frac{1}{2} (\alpha - \eta) v_d \times y_0 \Delta T_y
\]

where \( R \) is the amplifier’s input resistance and \( Z_c \) the characteristic impedance of the line. Here, again, we see a dispersive term proportional to the quantity \( y_0 \Delta T_y \) and to the signal rise-time. If this term can be made zero while the first term (capacitive cross-talk) is reduced to a %-level, a well-behaved Serpentine-RPC would seem realizable. Signal transmission under these conditions will be mainly affected by losses and by the reflections introduced by the bends. Losses during transmission show cutoff frequencies (defined as a 3dB signal drop) due to resistive (sub-index \( R \)) and dielectric (sub-index \( G \)) behaviours, and can be approximated by [12]:

\[
f_{c,R} \approx \frac{Z_c w \ln 2}{D} \frac{2}{\pi \rho_{DC}} \quad (3.6)
\]

\[
f_{c,G} \approx \frac{\bar{v} \ln 2}{2 \pi D \tan \delta^*} \quad (3.7)
\]

Here \( w \) is the strip width, \( D \) the detector length, \( \rho_{DC} \) the DC resistance of the strips and \( \mu \) their magnetic permeability. The dielectric losses are determined by the effective \( \tan \delta^* \) of the structure, around 0.01 at 1 GHz for float glass-based RPCs. By inserting standard values, it can be seen that the bandwidth of the structure (referring here to end-to-end propagation) is not smaller than 200 MHz for an overall length of 10 m, a bandwidth that has been shown to be compatible with 50 ps-timing (e.g.: NINO, PADI [49, 50]). This time jitter should be sufficient to reconstruct the crossing point of a traversing particle with a 5 mm precision.

Based on these arguments, it seems most natural to consider the possibility of a 10-fold reduction of the number of channels in a 1 m-scale detector by means of the serpentine approach, although the concept allows easily a 100-fold reduction at the 10 cm-scale, and so on. To illustrate that, we performed a simulation based on the Allegro suite with its FEM solver EMS2D [52]. The simulations were benchmarked against earlier simulations performed with MAXWELL-2D and a custom MTL-solver in [12], yielding comparable results. The bend-model used is described...
Figure 3. A 5-strip Serpentine-RPC (left), with and without compensation. Signals are injected as indicated in the drawings and read at the near and far ends. On the right a 3-strip Serpentine-RPC with additional guard-strips is shown for comparison. The presence of spurious pulses before the arrival of the interesting signal is below 5%. No optimization of the coupling coefficient $C_m/C_0$ or the shape of the bends has been performed.

These results are just representative of what can be done if a compensated Serpentine-RPC would be further optimized to reduce the capacitive coupling $C_m/C_0$ and the effects of the bends. These type of optimized structures are currently being designed with the aim at its experimental validation in the context of muon tomography and muography.
4 The technological horizon

Based on simulations, and assuming that all aforementioned technical caveats can be solved, the theoretical technological limit of an approach based on present MPGD technology may be put at a factor $\times 1/4$ below the demonstrated value of 200 ps-$\sigma$/photo-electron. A factor $\times 1/2$ can be gained if the drift region can be reduced from 200 $\mu$m to 50 $\mu$m, and another factor $\times 1/2$ if operation under pure quencher is feasible [31]. The final performance for minimum ionizing particles will depend on the amount of photons produced at the radiator crystal and the photo-effect quantum efficiency, potentially reaching $n_{\text{pe}} = 40$ for a good photocathode. Being the device limited mainly by diffusion and showing a good $1/\sqrt{n_{\text{pe}}}$ scaling, the projections for the time resolution seem robust. Importantly, however, the necessary sensitivity and both the short and long-term stability need to be demonstrated.

Concerning RPCs, where experimental information abounds, the best present value for the time resolution is 21 ps-$\sigma$ for minimum ionizing particles, achieved in [53] on an ensemble of 24 gas gaps of 160 $\mu$m size. Values around 50 ps represent already a technology standard [23, 54]. Narrower gaps have been tried, but never down to the 50 $\mu$m or even 25 $\mu$m values that are characteristic of $\mu$-bulk Micromegas, for instance [55]. $\mu$-bulk Micromegas detectors show an excellent mechanical accuracy ([56]) and nothing seems to impede at the moment the use of similar structures or materials as RPC-spacers themselves. It will suffice to have 24 gaps of 50$\mu$m size for reaching a total gas column of 1.2mm, considered to be the minimum for efficiency to mips (equiv.: 0.3 mm $\times$4 gaps). It is at the moment not possible to anticipate the achievable improvement, and to which extent the necessary operation under extreme space charge conditions could limit performance [57], but it certainly deserves exploration. Narrower gaps are expected to yield faster signals, and therefore the necessity of electrostatic compensation ($C_m/C_0 = C_{m0}/C_{00}$) will turn essential for $m^2$-counters.

Another promising area of exploration, long neglected since the first Pestov counters, is the possibility of operation at high pressure. Higher pressure can lessen the number of gaps needed for efficiency, and can be generally considered to be an advantage, according to eq. (2.1). The original (single 100 $\mu$m-gap) Pestov counters were operated at 12 bar, and while this extreme number was then necessary for an efficient detector, the situation is much more comfortable with the multi-gap technology. Operation at 2–4 bar would thus enable the use of 25 $\mu$m–50 $\mu$m gas gaps, based on conventional 4–10 gap architectures that are well established at atmospheric pressure. Indeed, it has been recently shown that operation up to 4 bar in homogeneous fields does not require a strong reduction of the working gain, both for Xenon and Argon-based mixtures in the case of micromegas with ~ 50–100 $\mu$m gaps [58, 59].

Lastly, due to global-warming concerns new gases are being introduced by industry to replace $C_2H_2F_4$, and it remains to be seen if they provide an advantage (generally, implying the drift velocity $v_d$ to be higher for the same working gain). In all, it seems very unlikely that the land-mark value of 10 ps-$\sigma$ accuracy for mips will not be reached soon by a technology based on RPCs, even if the solution might be initially restricted to some very specific environments. That’s the scale at which delays on signal induction and particle transit due to the sheer size of the structure will start to matter. This represents an amazing situation by itself, and one that will require considerable ingenuity to be overcome.
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