Modal Logics of Topological Spaces

(Extended abstract of doctoral dissertation)

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1 Introduction

In this thesis we shall present two logical systems, MP and MP*, for the purpose of reasoning about knowledge and effort. These logical systems will be interpreted in a spatial context and therefore, the abstract concepts of knowledge and effort will be defined by concrete mathematical concepts.

Our general framework consists of a set of possible worlds (situations, scenarios, consistent theories, etc.) A state of knowledge is a subset of this set and our knowledge consists of all facts common to the worlds belonging to this subset. This subset of possibilities can be thought as our view. Thus two knowers having distinct views can have different knowledge. This treatment of knowledge agrees with the traditional one ([Hin62], [HM84], [PR85], [CM86], [FHV91]) expressed in a variety of contexts (artificial intelligence, distributed processes, economics, etc.)

Our treatment is based on the following simple observation

"a restriction of our view increases our knowledge."

This is because a smaller set of possibilities implies a greater amount of common facts. Moreover, such a restriction can only be possible due to an increase of information. And such an information increase can happen with spending of time or computation resources. Here is where the notion of effort enters. A restriction of our view is dynamic (contrary to the view itself which is a state) and is accompanied by effort during which a greater amount of information becomes available to us (Pratt expresses a similar idea in the context of processes [Pra92].)

We make two important assumptions.

Our knowledge has a subject. We collect information for a specific purpose. Hence we are not considering arbitrary restrictions to our view but restrictions parameterized by possibilities contained in our view, i.e. neighborhoods

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of possibilities. After all, only one of these possibilities is our actual state. This crucial assumption enables us to express topological concepts and use a mathematical set-theoretic setting as semantics. Without such an assumption these ideas would have been expressed in the familiar theory of intuitionism (Hey56, Dum77, TvD88.) As Fitting points out in Fit69

“Let \( \langle G, R, \models \rangle \) be a [intuitionistic, propositional] model. \( G \) is intended to be a collection of possible universes, or more properly, states of knowledge. Thus a particular \( \Gamma \) in \( G \) may be considered as a collection of (physical) facts known at a particular time. The relation \( R \) represents (possible) time succession. That is, given two states of knowledge \( \Gamma \) and \( \Delta \) of \( G \), to say \( \Gamma R \Delta \) is to say: if we now know \( \Gamma \), it is possible that later we will know \( \Delta \).”

Considering neighborhoods and, inevitably, points which parameterize neighborhoods, the important duality between the facts, which constitute our knowledge, and the possible worlds, where such facts hold, emerges.

The other assumption is that of indeterminacy. Each state of knowledge is closed under logical deduction. Thus an increase of knowledge can happen only by a piece of evidence or information given from outside. Our knowledge is external (a term used by Parikh to describe a similar idea in Par87b.) This fact leads to indeterminacy (we do not know which kinds of information will be available to us, if at all) and resembles indeterminacy expressed in intuitionism through the notion of lawless sequence (see Kre58, Tro77) where, not surprisingly, topological notions arise.

To illustrate better these simple but fundamental ideas we present the following examples:

- Suppose that a machine emits a stream of binary digits representing the output of a recursive function \( f \). After time \( t_1 \) the machine emitted the stream 111. The only information we have about the function being computed at this time on the basis of this (finite) observation is that
  \[ f(1) = f(2) = f(3) = 1. \]

  As far as our knowledge concerns \( f \) is indistinguishable from the constant function \( 1 \), where \( 1(n) = 1 \) for all \( n \). After some additional time \( t_2 \), i.e. spending more time and resources, 0 might appear and thus we could be able to distinguish \( f \) from \( 1 \). In any case, each binary stream will be an initial segment of \( f \) and this initial segment is a neighborhood of \( f \). In this way, we can acquire more knowledge for the function the machine computes. The space of finite binary streams is a structure which models computation. Moreover, this space comprises a topological space. The set of binary streams under the prefix ordering is an example of Alexandrov topology (see Vic89.)

- A policeman measures the speed of passing cars by means of a device. The speed limit is 80 km/h. The error in measurement which the device
introduces is 1 km/h. So if a car has a speed of 79.5 km/h and his device measures 79.2 km/h then he knows that the speed of the passing car lies in the interval (78.2, 80.2) but he does not know if the car exceeds the speed limit because not all values in this interval are more than 80. However, measuring again and combining the two measurements or acquiring a more accurate device he has the possibility of knowing that a car with a speed of 79.5 km/h does not exceed the speed limit. Note here that if the measurement is, indeed, an open interval of real line and the speed of a passing car is exactly 80 km/h then he would never know if such a car exceeded the speed limit or not.

To express this framework we use two modalities $K$ for knowledge and $\Box$ for effort. Moss and Parikh observed in [MP92] that if the formula

$$A \rightarrow \Box K A$$

is valid, where $A$ is an atomic predicate and $\Diamond$ is the dual of the $\Box$, i.e. $\Diamond \equiv \neg \neg \Box$, then the set which $A$ represents is an open set of the topology where we interpret our systems. Under the reading of $\Diamond$ as “possible” and $K$ as “is known”, the above formula says that

“if $A$ is true then it is for $A$ possible to be known”,

i.e. $A$ is affirmative. Vickers defines similarly an affirmative assertion in [Vic89]

“an assertion is affirmative iff it is true precisely in the circumstances when it can be affirmed.”

The validity of the dual formula

$$\Box L A \rightarrow A,$$

where $L$ is the dual of $K$, i.e. $L \equiv \neg K \neg$, expresses the fact that the set which $A$ represents is closed, and hence $A$ is refutative, meaning if it does not hold then it is possible to know that. The fact that affirmative and refutative assertions are represented by opens and closed subsets, respectively, should not come to us as a surprise. Affirmative assertions are closed under infinite disjunctions and refutative assertions are closed under infinite conjunctions. Smyth in [Smy83] observed first these properties in semi-decidable properties. Semi-decidable properties are those properties whose truth set is r.e. and are a particular kind of affirmative assertions. In fact, changing our power of affirming or computing we get another class of properties with a similar knowledge-theoretic character. For example, using polynomial algorithms affirmative assertions become polynomially semi-decidable properties. If an object has this property then it is possible to know it with a polynomial algorithm even though it is not true we know it now.

Does this framework suffers from the problem of logical omniscience? Only in part. Expressing effort we are able to bound the increase of knowledge depending on information (external knowledge.) Since the modality $K$ which corresponds to knowledge is axiomatized by the normal modal logic of $S5$, knowledge
is closed under logical deduction. However, because of the strong computational character of this framework it does not seem unjustified to assume that in most cases (as in the binary streams example) a finite amount of data restricts our knowledge to a finite number of (relevant) formulae. Even without such an assumption we can incorporate the effort to deduce the knowledge of a property in the passage from one state of knowledge to the other.

We have made an effort to present our material somewhat independently. However, knowledge of basic modal logic, as in [Che80], [HC84], or [Fit93], is strongly recommended.

The language and semantics of our logical framework is presented in Chapter 2. In the same Chapter we present two systems: MP and MP*. The former was introduced in MP92 and was proven complete for arbitrary sets of subsets. It soon became evident that such sets of subsets should be combined, whenever it is possible, to yield a further increase of knowledge or we should assume a previous state of others states of knowledge where such states are a possible. Therefore the set of subsets should be closed under union and intersection. Moreover, topological notions expressed in MP make sense only in topological models. For this reason we introduce an extension of the set of axioms of MP and we call it MP*. In Chapter 3, we study the topological models of MP* by semantical means. We are able to prove the reduction of the theory of topological models to models whose associated set of subsets is closed under finite union and intersection. Finding for each satisfiable formula a model of bounded size we prove decidability for MP*. The results of this chapter will appear in Geo93. In Chapter 4, we prove that MP* is a complete system for topological models as well as topological models comprised by closed subsets. We also give necessary and sufficient conditions for turning a Kripke frame into such a topological model. In Chapter 5, we present the modal algebras of MP and MP* and some of their properties. Finally, in Chapter 6, we present some of our ideas towards future work.

2 Two Systems: MP and MP*

In section 2.1 we shall present a language and semantics which appeared first in MP92. In section 2.2 we shall present the axiom system MP, introduced and proven sound and complete with a class of models called subset spaces in MP92, and the axiom system MP*, introduced by us, which we shall prove sound and complete for, among other classes, the class of topological spaces.

2.1 Language and Semantics

We follow the notation of MP92.

Our language is bimodal and propositional. Formally, we start with a countable set A of atomic formulae containing two distinguished elements ⊤ and ⊥. Then the language L is the least set such that A ⊆ L and closed under the following rules:
φ, ψ ∈ L
φ ∧ ψ ∈ L
¬φ, □φ, Kφ ∈ L

The above language can be interpreted inside any spatial context.

Definition 1 Let X be a set and O a subset of the powerset of X, i.e. O ⊆ P(X) such that X ∈ O. We call the pair ⟨X, O⟩ a subset space. A model is a triple ⟨X, O, i⟩, where ⟨X, O⟩ is a subset space and i a map from A to P(X) with i(⊤) = X and i(⊥) = ∅ called initial interpretation.

We denote the set \{(x, U) : x ∈ X, U ∈ O, and x ∈ U\} ⊆ X × O by X × O.

For each U ∈ O let ↓ U be the set \{V : V ∈ O and V ⊆ U\} the lower closed set generated by U in the partial order (O, ⊆), i.e. ↓ U = P(U) ∩ O.

Definition 2 The satisfaction relation |= M, where M is the model ⟨X, O, i⟩, is a subset of (X × O) × L defined recursively by (we write x, U |= M φ instead of ((x, U), φ) ∈ |= M):

x, U |= M A iff x ∈ i(A), where A ∈ A
x, U |= M φ ∧ ψ if x, U |= M φ and x, U |= M ψ
x, U |= M ¬φ if x, U |=¬ M φ
x, U |= M Kφ if for all y ∈ U, y, U |= M φ
x, U |= M Lφ if for all V ∈ ↓ U such that x ∈ V, x, V |= M φ.

If x, U |= M φ for all (x, U) belonging to X × O then φ is valid in M, denoted by M |= φ.

We abbreviate ¬□¬φ and ¬K¬φ by ◦φ and Lφ respectively. We have that

x, U |= M Lφ if there exists y ∈ U such that y, U |= M φ
x, U |= M ◦φ if there exists V ∈ O such that V ⊆ U, x ∈ V, and x, V |= M φ.

Many topological properties are expressible in this logical system in a natural way. For instance, in a model where the subset space is a topological space, i(A) is open whenever A → ◦K φ is valid in this model. Similarly, i(A) is nowhere dense whenever L ◦ K ¬φ is valid (cf. MP92.)

Example. Consider the set of real numbers R with the usual topology of open intervals. We define the following three predicates:

pi where i(pi) = {π}
I₁ where i(I₁) = (−∞, π]
I₂ where i(I₂) = (π, +∞)
Q where i(Q) = {q : q is rational}.

There is no real number p and open set U such that p, U |= Kpi because that would imply p = π and U = {π} and there are no singletons which are open.
A point $x$ belongs to the closure of a set $W$ if every open $U$ that contains $x$ intersects $W$. Thus $\pi$ belongs to the closure of $(\pi, +\infty)$, i.e. every open that contains $\pi$ has a point in $(\pi, +\infty)$. This means that for all $U$ such that $\pi \in U$, $\pi, U \models \mathsf{LI}_1$, therefore $\pi, R \models \Box \mathsf{LI}_2$. Following the same reasoning $\pi, R \models \Box \mathsf{LI}_1$, since $\pi$ belongs to the closure of $(-\infty, \pi]$.

A point $x$ belongs to the boundary of a set $W$ whenever $x$ belongs to the closure of $W$ and $X - W$. By the above, $\pi$ belongs to the boundary of $(-\infty, \pi]$ and $\pi, R \models \Box (\mathsf{LI}_1 \land \mathsf{LI}_2)$.

A set $W$ is closed if it contains its closure. The interval $i(I_1) = (-\infty, \pi]$ is closed and this means that the formula $\Box \mathsf{LI}_1 \rightarrow I_1$ is valid.

A set $W$ is dense if all opens contain a point of $W$. The set of rational numbers is dense which translates to the fact that the formula $\Box \mathsf{LI}_1$ is valid. To exhibit the reasoning in this logic, suppose that the set of rational numbers was closed then both $\Box \mathsf{LI}_1$ and $\Box \mathsf{LI}_1 \rightarrow \mathsf{LI}_1$ would be valid. This implies that $\mathsf{LI}_1$ would be valid which means that all reals would be rationals. Hence the set of rational numbers is not closed.

### 2.2 MP and MP$^*$

The axiom system MP consists of axiom schemes 1 through 10 and rules of table 1 (see page 4) and appeared first in [MP92].

The following was proved in [MP92].

**Theorem 3** The axioms and rules of MP are sound and complete with respect to subset spaces.

We add the axioms 11 and 12 to form the system MP$^*$ for the purpose of axiomatizing spaces closed under union and intersection and, in particular, topological spaces.

A word about the axioms (most of the following facts can be found in any introductory book about modal logic, e.g. [Che80] or [Gol87].) The axiom 2 expresses the fact that the truth of atomic formulae is independent of the choice of subset and depends only on the choice of point. This is the first example of a class of formulae which we are going to call bi-persistent and their identification is one of the key steps to completeness. Axioms 3 through 5 and axioms 6 through 9 are used to axiomatize the normal modal logics $\mathbf{S4}$ and $\mathbf{S5}$ respectively. The former group of axioms expresses the fact that the passage from one subset to a restriction of it is done in a constructive way as actually happens to an increase of information or a spending of resources (the classical interpretation of necessity in intuitionistic logic is axiomatized in the same way). The latter group is generally used for axiomatizing logics of knowledge.

Axiom 10 expresses the fact that if a formula holds in arbitrary subsets is going to hold as well in the ones which are neighborhoods of a point. The converse is not sound.

Axiom 11 is a well-known formula which characterizes incestual frames, i.e. if two points $\beta$ and $\gamma$ in a frame can be accessed by a common point $\alpha$ then
### Axioms

1. All propositional tautologies
2. \((A \rightarrow \Box A) \land (\neg A \rightarrow \Box \neg A), \text{ for } A \in A\)
3. \(\Box(\phi \rightarrow \psi) \rightarrow (\Box \phi \rightarrow \Box \psi)\)
4. \(\Box \phi \rightarrow \phi\)
5. \(\Box \phi \rightarrow \Box \Box \phi\)
6. \(K(\phi \rightarrow \psi) \rightarrow (K \phi \rightarrow K \psi)\)
7. \(K \phi \rightarrow \phi\)
8. \(K \phi \rightarrow KK \phi\)
9. \(\phi \rightarrow KL \phi\)
10. \(K \Box \phi \rightarrow \Box K \phi\)
11. \(\Diamond \Box \phi \rightarrow \Box \Diamond \phi\)
12. \(\Diamond (K \phi \land \psi) \land L \Diamond (K \phi \land \chi) \rightarrow \Diamond (K \Diamond \phi \land \Diamond \psi \land L \Diamond \chi)\)

### Rules

\[
\begin{align*}
\phi \rightarrow \psi, \phi & \quad \text{MP} \\
\phi & \quad \text{K-Necessitation} \\
\Box \phi & \quad \Box \text{-Necessitation}
\end{align*}
\]

| Table 1: Axioms and Rules of MP* |  |  |
there is a point \( \delta \) which can be accessed by both \( \beta \) and \( \gamma \). It appeared in the equivalent form (in [MP92])

\[
\lozenge \Box \phi \land \lozenge \Box \psi \to \lozenge \Box (\phi \land \psi)
\]

and was proved sound in subset spaces closed under (finite) intersection.

Obviously our attention is focused on axiom 12. It is sound in spaces closed under (finite) union and intersection as the following proposition shows.

**Proposition 4** Axioms 1 through 12 are sound in the class of subset spaces closed under finite union and intersection.

**Proof.** Soundness for Axioms 1 through 11 is easy. For Axiom 12, suppose

\[ x, U \models \lozenge (\Box \phi \land \psi) \land L \Diamond (\Box \phi \land \chi) \]

Since \( x, U \models \lozenge (\Box \phi \land \psi) \), there exists \( U_x \subseteq U \) such that

\[ x, U_x \models \Box \phi \land \psi \]

and, since \( x, U \models L \Diamond (\Box \phi \land \Box \chi) \), there exists \( y \in U \) and \( U_y \subseteq U \) such that

\[ y, U_y \models \Box \phi \land \chi \]

We now have that \( U_x \cup U_y \subseteq U \) (we assume closure under unions.) Thus

\[ x, U_x \cup U_y \models \lozenge \Diamond \phi, \quad y, U_x \cup U_y \models \lozenge \Diamond \phi, \quad x, U_x \cup U_y \models \Diamond \psi, \quad \text{and} \quad y, U_x \cup U_y \models \Diamond \chi. \]

Therefore,

\[ x, U \models \lozenge (\lozenge \Box \phi \land \Diamond \psi \land L \Diamond \chi). \]

With the help of axiom 12 we are able to prove the key lemma which leads to the DNF Theorem (page 16) and this is the only place where we actually use it. Any formula, sound in the class of subset spaces closed under finite union and intersection, which implies the formula (note the difference from axiom 12)

\[
\lozenge (\Box \phi \land \psi) \land L \Diamond (\Box \phi \land \chi) \to \lozenge (\Box \phi \land \psi \land L \chi)
\]

where \( \Diamond \phi \to \Box \phi, \Diamond \psi \to \psi \) and \( \chi \to \Box \chi \) are theorems, can replace axiom 12.

### 3 A Semantical analysis of MP*

#### 3.1 Stability and Splittings

Suppose that \( X \) is a set and \( T \) a topology on \( X \). In the following we assume that we are working in the topological space \( (X, T) \). Our aim is to find a partition of \( T \), where a given formula \( \phi \) “retains its truth value” for each point throughout
a member of this partition. We shall show that there exists a finite partition of this kind.

**Definition 5** Given a finite family \( \mathcal{F} = \{U_1, \ldots, U_n\} \) of opens, we define the remainder of (the principal ideal in \( (\mathcal{I}, \subseteq) \) generated by) \( U_k \) by

\[
\operatorname{Rem}^\mathcal{F}U_k = \downarrow U_k - \bigcup_{U_i \not\subseteq U_k} \downarrow U_i.
\]

**Proposition 6** In a finite set of opens \( \mathcal{F} = \{U_1, \ldots, U_n\} \) closed under intersection, we have

\[
\operatorname{Rem}^\mathcal{F}U_i = \downarrow U_i - \bigcup_{U_j \subset U_i} \downarrow U_j,
\]

for \( i = 1, \ldots, n \).

We denote \( \bigcup_{U_i \in \mathcal{F}} \downarrow U_i \) with \( \downarrow \mathcal{F} \).

**Proposition 7** If \( \mathcal{F} = \{U_1, \ldots, U_n\} \) is a finite family of opens, closed under intersection, then

a. \( \operatorname{Rem}^\mathcal{F}U_i \cap \operatorname{Rem}^\mathcal{F}U_j = \emptyset \), for \( i \neq j \).

b. \( \bigcup_{i=1}^n \operatorname{Rem}^\mathcal{F}U_i = \downarrow \mathcal{F} \), i.e. \( \{\operatorname{Rem}^\mathcal{F}U_i\}_{i=1}^n \) is a partition of \( \downarrow \mathcal{F} \). We call such an \( \mathcal{F} \) a finite splitting (of \( \downarrow \mathcal{F} \)),

c. if \( V_1, V_3 \in \operatorname{Rem}^\mathcal{F}U_i \) and \( V_2 \) is an open such that \( V_1 \subseteq V_2 \subseteq V_3 \) then \( V_2 \in \operatorname{Rem}^\mathcal{F}U_i \), i.e. \( \operatorname{Rem}^\mathcal{F}U_i \) is convex.

Every partition of a set induces an equivalence relation on this set. The members of the partition comprise the equivalence classes. Since a splitting induces a partition, we denote the equivalence relation induced by a splitting \( \mathcal{F} \) by \( \sim^\mathcal{F} \).

**Definition 8** Given a set of open subsets \( \mathcal{G} \), we define the relation \( \sim^\mathcal{G} \) on \( \mathcal{I} \) with \( V_1 \sim^\mathcal{G} V_2 \) if and only if \( V_1 \subseteq U \iff V_2 \subseteq U \) for all \( U \in \mathcal{G} \).

We have the following

**Proposition 9** The relation \( \sim^\mathcal{G} \) is an equivalence.

**Proposition 10** Given a finite splitting \( \mathcal{F} \), \( \sim^\mathcal{F} = \sim^\mathcal{F} \) i.e. the remainders of \( \mathcal{F} \) are the equivalence classes of \( \sim^\mathcal{F} \).

We state some useful facts about splittings.

**Proposition 11** If \( \mathcal{G} \) is a finite set of opens, then \( \mathcal{C}(\mathcal{G}) \), its closure under intersection, yields a finite splitting for \( \downarrow \mathcal{G} \).
The last proposition enables us to give yet another characterization of remainders: every family of points in a complete lattice closed under arbitrary joins comprises a closure system, i.e. a set of fixed points of a closure operator of the lattice (cf. [GHK+80]). Here, the lattice is the poset of the opens of the topological space. If we restrict ourselves to a finite number of fixed points then we just ask for a finite set of opens closed under intersection i.e. Proposition 11.

Thus a closure operator in the lattice of the open subsets of a topological space induces an equivalence relation, two opens being equivalent if they have the same closure, and the equivalence classes of this relation are just the remainders of the open subsets which are fixed points of the closure operator. The maximum open in $\text{Rem}^F U$, i.e. $U$, can be taken as the representative of the equivalence class which is the union of all open sets belonging to $\text{Rem}^F U$.

We now introduce the notion of stability corresponding to what we mean by “a formula retains its truth value on a set of opens”.

**Definition 12** If $G$ is a set of opens then $G$ is stabile for $\phi$, if for all $x$, either $x, V \models \phi$ for all $V \in G$, or $x, V \models \neg \phi$ for all $V \in G$, such that $x \in V$.

**Proposition 13** If $G_1, G_2$ are sets of opens then

a. if $G_1 \subseteq G_2$ and $G_2$ is stable for $\phi$ then $G_1$ is stable for $\phi$,

b. if $G_1$ is stable for $\phi$ and $G$ is stable for $\chi$ then $G_1 \cap G_2$ is stable for $\phi \land \chi$.

**Definition 14** A finite splitting $F = \{U_1, \ldots, U_n\}$ is called a stable splitting for $\phi$, if $\text{Rem}^F U_i$ is stable for $\phi$ for all $U_i \in F$.

**Proposition 15** If $F = \{U_1, \ldots, U_n\}$ is a stable splitting for $\phi$, so is

$$F' = \text{Cl}(\{U_0, U_1, \ldots, U_n\}),$$

where $U_0 \in \downarrow F$.

The above proposition tells us that if there is a finite stable splitting for a topology then there is a closure operator with finitely many fixed points whose associated equivalence classes are stable sets of open subsets.

Suppose that $M = \langle X, T, i \rangle$ is a topological model for $L$. Let $F_M$ be a family of subsets of $X$ generated as follows: $i(A) \in F_M$ for all $A \in A$, if $S \in F_M$ then $X - S \in F_M$, if $S, T \in F_M$ then $S \cap T \in F_M$, and if $S \in F_M$ then $S^\circ \in F_M$ i.e. $F_M$ is the least set containing $\{i(A) | A \in A\}$ and closed under complements, intersections and interiors. Let $F_M^\circ$ be the set $\{S^\circ | S \in F_M\}$. We have $F_M^\circ = F_M \cap \downarrow T$. The following is the main theorem of this section.

**Theorem 16 (Partition Theorem)** Let $M = \langle X, T, i \rangle$ be a topological model. Then there exists a a set $\{F^\psi\}_{\psi \in L}$ of finite stable splittings such that

1. $F^\psi \subseteq F_M^\circ$ and $X \in F^\psi$, for all $\psi \in L$,
2. if \( U \in \mathcal{F}^\psi \) then \( U^\psi = \{ x \in U | x, U \models \psi \} \in \mathcal{F}_M \), and

3. if \( \phi \) is a subformula of \( \psi \) then \( \mathcal{F}^\phi \subseteq \mathcal{F}^\psi \) and \( \mathcal{F}^\psi \) is a finite stable splitting for \( \phi \),

where \( \mathcal{F}_M, \mathcal{F}_M^\circ \) as above.

**Proof.** By induction on the structure of the formula \( \psi \). In each step we take care to refine the partition of the induction hypothesis. Rather long proof. 

Theorem 16 gives us a great deal of intuition for topological models. It describes in detail the expressible part of the topological lattice for the completeness result as it appears in Chapter 3 and paves the road for the reduction of the theory of topological models to that of spatial lattices and the decidability result of this chapter.

### 3.2 Basis Model

Let \( T \) be a topology on a set \( X \) and \( B \) a basis for \( T \). We denote satisfaction in the models \( \langle X, T, i \rangle \) and \( \langle X, B, i \rangle \) by \( \models_T \) and \( \models_B \), respectively. In the following proposition we prove that each equivalence class under \( \sim \) contains an element of a basis closed under finite unions.

**Proposition 17** Let \( (X, T) \) be a topological space, and let \( B \) be a basis for \( T \) closed under finite unions. Let \( F \) be any finite subset of \( T \). Then for all \( V \in F \) and all \( x \in V \), there is some \( U \in B \) with \( x \in U \subseteq V \) and \( U \in \text{Rem}^F V \).

**Corollary 18** Let \( (X, T) \) be a topological space, \( B \) a basis for \( T \) closed under finite unions, \( x \in X \) and \( U \in B \). Then

\[
x, U \models_T \phi \iff x, U \models_B \phi.
\]

We shall prove that a model based on a topological space \( T \) is equivalent to the one induced by any basis of \( T \) which is lattice. Observe that this enables us to reduce the theory of topological spaces to that of spatial lattices and, therefore, to answer the conjecture of \[\text{MP92} \]: a completeness theorem for subset spaces which are lattices will extend to the smaller class of topological spaces.

**Theorem 19** Let \( (X, T) \) be a topological space and \( B \) a basis for \( T \) closed under finite unions. Let \( M_1 = \langle X, T, i \rangle \) and \( M_2 = \langle X, B, i \rangle \) be the corresponding models. Then, for all \( \phi \),

\[
M_1 \models \phi \iff M_2 \models \phi.
\]
3.3 Finite Satisfiability

**Proposition 20** Let \( \langle X, T \rangle \) be a subset space. Let \( F \) be a finite stable splitting for a formula \( \phi \) and all its subformulae, and assume that \( X \in F \). Then for all \( U \in F \), all \( x \in U \), and all subformulae \( \psi \) of \( \phi \), \( x, U \models_T \psi \) iff \( x, U \models_F \psi \).

Constructing the quotient of \( T \) under \( \sim_F \) is not adequate for generating a finite model because there may still be an infinite number of points. It turns out that we only need a finite number of them.

Let \( M = \langle X, T, i \rangle \) be a topological model, and define an equivalence relation \( \sim \) on \( X \) by \( x \sim y \) iff

(a) for all \( U \in T \), \( x \in U \) iff \( y \in U \), and

(b) for all atomic \( A \), \( x \in i(A) \) iff \( y \in i(A) \).

Further, denote by \( x^* \) the equivalence class of \( x \), and let \( X^* = \{ x^* : x \in X \} \). For every \( U \in T \) let \( U^* = \{ x^* : x \in X \} \), then \( T^* = \{ U^* : U \in T \} \) is a topology on \( X^* \). Define a map \( i^* \) from the atomic formulae to the powerset of \( X^* \) by \( i^*(A) = \{ x^* : x \in i(A) \} \). The entire model \( M \) lifts to the model \( M^* = \langle X^*, T^*, i^* \rangle \) in a well-defined way.

**Lemma 21** For all \( x, U, \) and \( \phi \),
\[ x, U \models_M \phi \quad \text{iff} \quad x^*, U^* \models_{M^*} \phi . \]

**Proof.** By induction on \( \phi \). \( \square \)

**Theorem 22** If \( \phi \) is satisfied in any topological space then \( \phi \) is satisfied in a finite topological space.

Observe that the finite topological space is a quotient of the initial one under two equivalences. The one equivalence is \( \sim_\phi \) on the open subsets of the topological space, where \( \mathcal{F}_\phi \) is the finite splitting corresponding to \( \phi \) and its cardinality is a function of the complexity of \( \phi \). The other equivalence is \( \sim_X \) on the points of the topological space and its number of equivalence classes is a function of the atomic formulae appearing in \( \phi \). The following simple example shows how a topology is formed with the quotient under these two equivalences.

**Example:** Let \( X \) be the interval \([0, 1)\) of real line with the set
\[ T = \{ \emptyset \} \cup \{ [0, \frac{1}{2^n}) \mid n = 0, 1, 2, \ldots \} \]
as topology. Suppose that we have only one atomic formula, call it \( A \), such that \( i(A) = \{ 0 \} \), then it is easy to see that the model \( \langle X, T, i \rangle \) is equivalent to the finite topological model \( \langle X^*, T^*, i^* \rangle \), where
\[
X^* = \{ x_1, x_2 \}, \\
T^* = \{ \emptyset, \{ x_1, x_2 \} \}, \text{ and } i(A) = \{ x_1 \}.
\]
So the overall size of the (finite) topological space is bounded by a function of the complexity of $\phi$. Thus if we want to test if a given formula is invalid we have a finite number of finite topological spaces where we have to test its validity. Thus we have the following

**Theorem 23** The theory of topological spaces is decidable.

Observe that the last two results apply for lattices of subsets by Theorem [19].

4 Completeness for MP$^*$

Open subsets of a topological space were used in [MP92] and in the previous section to provide motivation, intuition and finally semantics for MP$^*$. But in this chapter we shall show that the canonical model of MP$^*$ is actually a set of subsets closed under arbitrary intersection and finite union, i.e. the closed subsets of a topological space. However, these results are not contrary to our intuition for the following reasons: the spatial character of this logic remains untouched. The fact that the canonical model is closed under arbitrary intersections implies strong completeness with the much wider class of sets of subsets closed under infinite union and finite intersection, i.e. the open subsets of a topological space.

4.1 Subset frames

As we noted in section 2.1, we are not interpreting formulae directly over a subset space but, rather in the pointed product $X \times \mathcal{O}$. The pointed product can be turned in a set of possible worlds of a frame. We have only to indicate what the accessibility relations are.

**Definition 24** Let $(X, \mathcal{O})$ be a subset space. Its **subset frame** is the frame $\langle X \times \mathcal{O}, R_\mathcal{O}, R_K \rangle$, where

$(x, U) R_\mathcal{O} (y, V) \quad$ if $\quad U = V$

and

$(x, U) R_K (y, V) \quad$ if $\quad x = y$ and $V \subseteq U$.

If $\mathcal{O}$ is a topology, intended as the closed subsets of a topological space, we shall call its subset frame **closed topological frame**.

Our aim is to prove the most important properties of such a frame. We propose the following conditions on a possible worlds frame $\mathcal{F} = \langle S, R_1, R_2 \rangle$ with two accessibility relations
1. $R_1$ is reflexive and transitive.
2. $R_2$ is an equivalence relation.
3. $R_1 R_2 \subseteq R_2 R_1$
4. (ending points) $F$ has ending points with respect $R_1$, i.e.
   for all $s \in S$ there exists $s_0 \in S$ such that for all $s' \in S$ if $s R_1 s'$
   then $s' R_1 s_0$.
5. (extensionality condition) For all $s, s' \in S$, if there exists $s_0 \in S$ such that
   $s R_1 s_0$ and $s' R_1 s_0$ and
   for all $t \in S$ such that $t R_2 s$ there exist $t', t_0 \in S$ such that $t' R_2 s'$,
   $t R_1 t_0$ and $t' R_1 t_1$, and for all $t' \in S$ such that $t' R_2 s'$ there exist
   $t, t_0 \in S$ such that $t R_2 s, t' R_1 t_0$ and $t R_1 t_0$,
   then $s = s'$.
6. (union condition) For all $s_1, s_2 \in S$,
   if there exists $s \in S$ such that $s R_2 R_1 s_1$ and $s R_2 R_1 s_2$, then there
   exists $s' \in S$ such that for all $t \in S$ with $t R_2 s'$ then $t R_1 R_2 s_1$ or
   $t R_1 R_2 s_2$.
7. (intersection condition) For all $\{s_i\}_{i \in I} \subseteq S$,
   if there exists $s \in S$ such that $s_i R_1 s$ for all $i \in I$ then there
   exists $s' \in S$ such that for all $\{t_i\} \subseteq S$ with $t_i R_2 s_i$ and $t_i R_1 t_0$
   for all $i \in I$ and some $t_0 \in S$ then $t_i R_1 R_2 s'$.
8. The frame $F$ is strongly generated in the sense that
   there exists $s \in S$ such that for all $s' \in S$, $s R_2 R_1 s'$.

We have the following observations to make about the above conditions. Conditions 1 to 3 and 5 are first order, while the intersection condition is not. The extensionality condition implies the following

for all $s, s' \in S$ such that $s R_1 s_0$ and $s' R_2 s_0$ then $s = s'$

which implies that $R_1 \cap R_2$ is the identity in $S$. In view of the extensionality condition the relation $R_1$ is antisymmetric. So we can replace condition 3 with the condition that $R_1$ is a partial order.

Now, we have the following proposition

**Proposition 25** If $(X, T)$ is a topological space then its closed topological frame $F_T$ satisfies conditions 2 through 5.

The above proposition could lead to the consequence that topological models are possible worlds models in disguise. But the following theorem shows that this is not the case. There is a duality.

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**Theorem 26** Let $\mathcal{F} = (S, R_1, R_2)$ be a frame satisfying conditions 1 through 8. Then $\mathcal{F}$ is isomorphic to a closed topological frame $\mathcal{F}_T$.

Note that, in the above definitions, we could have used equally well the equivalence class of $s \in S$ under the equivalence induced by the symmetric closure of $R_1$ instead of the ending point of $s$ in $\mathcal{F}$. The above proofs show that the crucial conditions are conditions 1 through 5 and if we are to strengthen or relax the union and intersection conditions we get accordingly different conditions in the lattice of the set of subsets of the space. The same holds for condition 8. We only used this condition to show that there exists a top element, i.e. the whole space, and satisfy the hypothesis of the union condition. If we do not assume this condition the union of two subsets will belong to the set of subsets if they have an upper bound in it. We state this case formally without a proof because we are going to use it later.

**Proposition 27**

1. Let $(X, O)$ be a subset space closed under infinite intersections and if $U, V \in O$ have an upper bound in $O$ then $U \cup V \in O$. Then its frame $\mathcal{F}_O$ satisfies conditions 1 through 7.

2. A frame $\mathcal{F}$ satisfying conditions 1 through 7 is isomorphic to a frame $\mathcal{F}_O$ where $(X, O)$ as in (1).

4.2 On the proof theory of MP

We shall identify certain classes of formulae in $\mathcal{L}$. This approach is motivated by the results of Chapter 3. In fact, these formulae express definable parts of the lattice of subsets (see section 3.1.)

**Definition 28** Let $\mathcal{L}' \subseteq \mathcal{L}$ be the set of formulae generated by the following rules:

$\forall \subseteq \mathcal{L}' \quad \frac{\phi, \psi \in \mathcal{L}'}{\phi \land \psi \in \mathcal{L}'} \quad \frac{\phi \in \mathcal{L}'}{\neg \phi, \Diamond \phi \in \mathcal{L}'}$

Let $\mathcal{L}''$ be the set $\{K\phi, L\phi|\phi \in \mathcal{L}'\}$.

Formulae in $\mathcal{L}'$ have the following properties

**Definition 29** A formula $\phi$ of $\mathcal{L}$ is called persistent whenever $\phi \rightarrow \Box \phi$ is a theorem (see also [MP92].)

A formula $\phi$ of $\mathcal{L}$ is called anti-persistent whenever $\neg \phi$ is persistent, i.e. $\neg \phi \rightarrow \Box \neg \phi$ (or, equivalently $\Diamond \phi \rightarrow \phi$) is a theorem.

A formula $\phi$ of $\mathcal{L}$ is called bi-persistent whenever $(\phi \rightarrow \Box \phi) \land (\neg \phi \rightarrow \Box \neg \phi)$ (or, equivalently $\Diamond \phi \rightarrow \Box \phi$) is a theorem.

Thus the truth of bi-persistent formulae depends only on the choice of the point of the space while the satisfaction of persistent formulae can change at most once in any model. We could go on and define a hierarchy of sets of formulae where each member of hierarchy contains all formulae which their satisfaction could change at most $n$ times in all models.
All the following derivations are in \( \text{MP}^* \) (Axioms 1 through 12 — see table at page 3.)

Proposition 30 All formulae belonging to \( \mathcal{L}' \) are bi-persistent.

Proof. We prove it by induction, i.e. bi-persistence is retained through the application of the formation rules of \( \mathcal{L}' \).

A faster (semantical) proof would be “the initial assignment on atomic formulae extends to the wider class of \( \mathcal{L}' \)”! This implies that formulae in \( \mathcal{L}' \) define subsets of the topological space.

Formulae in \( \mathcal{L}'' \) have similar properties as the following lemma show.

Lemma 31 If \( \phi \) is bi-persistent then \( K\phi \) is persistent and \( L\phi \) is anti-persistent.

We prove some theorems of \( \text{MP}^* \) that we are going to use later.

Lemma 32 If \( \phi \) is bi-persistent then \( \vdash_{\text{MP}^*} \Diamond(\phi \land \psi) \equiv \Diamond\phi \land \Diamond\psi \).

The following is the key lemma to the DNF Theorem and generalizes Axiom 12.

Lemma 33 For all \( n \),

\[
\vdash_{\text{MP}^*} \Diamond K\phi \land \bigwedge_{i=1}^n L(\Diamond K\phi \land \psi_i) \rightarrow \Diamond \left( K\phi \land \bigwedge_{i=1}^n L\psi_i \right),
\]

where \( \phi, \psi_i \) are bi-persistent.

All formulae of \( \mathcal{L}' \) can be expressed in terms of bi-persistent, persistent and antipersistent formulae by means of the following normal form.

Definition 34

1. \( \phi \) is in prime normal form (PNF) if it has the form

\[
\psi \land K\psi' \land \bigwedge_{i=1}^n L\psi_i
\]

where \( \psi, \psi', \psi_i \in \mathcal{L}' \) and \( n \) is finite.

2. \( \phi \) is in disjunctive normal form (DNF) if it has the form \( \bigvee_{i=1}^m \phi_i \), where each \( \phi_i \) is in PNF and \( m \) is finite.

We now give the formal analogue of the Partition Theorem.

Theorem 35 (DNF) For every \( \phi \in \mathcal{L} \), there is (effectively) a \( \psi \) in DNF such that

\[
\vdash_{\text{MP}^*} \phi \equiv \psi.
\]
The DNF theorem is the most important property of $\text{MP}^*$. An immediate corollary is that, as far as $\text{MP}^*$ is concerned, we could have replaced the $\Box$ modality with $\Diamond K$, since the formulae in normal form are defined using these two modalities. Almost all subsequent proof theoretic properties are immediate or implicit corollaries of the DNF Theorem.

We close this section with the following proposition, which together with Axiom 11 shows that $2\Diamond$ is equivalent to $3\Diamond$.

**Proposition 36** For all $\phi \in \mathcal{L}$, $\vdash_{\text{MP}^*} 2\Diamond \phi \rightarrow 3\Diamond \phi$

### 4.3 Canonical Model

The *canonical model* of $\text{MP}^*$ is the structure

$$\mathcal{C} = (S, \{R_\sqcap, R_K\}, v),$$

where

- $S = \{s \subseteq \mathcal{L} | s$ is $\text{MP}^*$-maximal consistent$\}$,
- $s R_\sqcap t$ iff $\{\phi \in \mathcal{L} | \Box \phi \in s\} \subseteq t$,
- $s R_K t$ iff $\{\phi \in \mathcal{L} | K \phi \in s\} \subseteq t$,
- $v(A) = \{s \in S | A \in S\}$,

along with the usual satisfaction relation (defined inductively):

$$s \models_{\mathcal{C}} A \quad \text{iff} \quad s \in v(A)$$

$$s \not\models_{\mathcal{C}} \bot$$

$$s \models_{\mathcal{C}} \phi \quad \text{iff} \quad s \models_{\mathcal{C}} \phi$$

$$s \models_{\mathcal{C}} \phi \land \psi \quad \text{iff} \quad s \models_{\mathcal{C}} \phi \quad \text{and} \quad s \models_{\mathcal{C}} \psi$$

$$s \models_{\mathcal{C}} \Box \phi \quad \text{iff} \quad \text{for all } t \in S, \ s R_\sqcap t \text{ implies } t \models_{\mathcal{C}} \phi$$

$$s \models_{\mathcal{C}} K \phi \quad \text{iff} \quad \text{for all } t \in S, \ s R_K t \text{ implies } t \models_{\mathcal{C}} \phi$$

We write $\mathcal{C} \models \phi$, if $s \models_{\mathcal{C}} \phi$ for all $s \in S$.

A canonical model exists for all consistent bimodal systems with the normal axiom scheme for each modality (as $\text{MP}$ and $\text{MP}^*$.) We have the following well known theorems (see [Che80], or [Gol87].)

**Theorem 37 (Truth Theorem)** For all $s \in S$ and $\phi \in \mathcal{L}$,

$$s \models_{\mathcal{C}} \phi \quad \text{iff} \quad \phi \in s.$$

**Theorem 38 (Completeness Theorem)** For all $\phi \in \mathcal{L}$,

$$\mathcal{C} \models \phi \quad \text{iff} \quad \vdash_{\text{MP}^*} \phi.$$

We shall now prove some properties of the members of $\mathcal{C}$. The DNF theorem implies that every maximal consistent theory $s$ of $\text{MP}^*$ is determined by the formulae in $\mathcal{L}'$ and $\mathcal{L}''$ it contains, i.e. by $s \cap \mathcal{L}'$ and $s \cap \mathcal{L}''$. Moreover, the
set \{K\phi, L\phi | K\phi, L\phi \in s\} is determined by \(s \cap L''\) alone (this is the K-case of the DNF theorem.)

The following definition is useful

**Definition 39** Let \(P \subseteq L'\). We say \(P\) is an \(L'\) theory if \(P\) is consistent and for all \(\phi \in L'\) either \(\phi \in P\) or \(\neg \phi \in P\).

Let \(S \subseteq L''\). We say \(S\) is an \(L''\) theory if \(S\) is consistent and for all \(\phi \in L''\) either \(\phi \in S\) or \(\neg \phi \in S\).

Hence, \(s \cap L'\) is an \(L'\) theory and \(s \cap L''\) is an \(L''\) theory.

What about going in the other direction? When does an \(L'\) theory and \(L''\) theory determine an \(MP^*\) maximal consistent theory? When their union is consistent because in this case there is a unique maximal extension. To test consistency we have the following lemma.

**Lemma 40** If \(P\) and \(S\) are an \(L'\) and \(L''\) theory respectively then \(P \cup S\) is consistent if and only if \(\phi \in P\) and \(\neg \phi \in S\).

It is expected that since \(L'\) and \(L''\) theories determine \(MP^*\) maximal consistent sets they will determine their accessibility relations, as well.

**Proposition 41** For all \(s, t \in S\),

- \(s R t\) if and only if i. \(\phi \in t\) if and only if \(\phi \in s\), where \(\phi \in L'\),
  - ii. if \(L\phi \in t\) then \(L\phi \in s\), where \(\phi, \psi \in L'\).

- \(s R_{K} t\) if and only if \(K \phi \in t\) if and only if \(K \phi \in s\), where \(\phi \in L'\).

From the above proposition we have that for all \(s, t \in S\), if \(s R t\) then \(s \cap L' = t \cap L'\) and if \(s R_{K} t\) then \(s \cap L'' = t \cap L''\).

We write \(R_K R_\Box\) for the composition of the relation \(R_K\) and \(R_\Box\), i.e. if \(s, t \in S\), we write \(s R_K R_\Box t\) if there exists \(r \in S\) such that \(s R_K r\) and \(r R_\Box t\). Similarly for \(R_\Box R_K\).

For the composite relation \(R_K R_\Box\) and \(R_\Box R_K\) we have the following corollary of proposition [1]

**Corollary 42** For all \(s, t \in S\),

- \(s R_\Box R_K t\) if and only if i. if \(\phi \in s\) then \(L\phi \in t\), where \(\phi \in L'\),
  - ii. if \(L\phi \in t\) then \(L\phi \in s\), where \(\phi, \psi \in L'\).

- \(s R_K R_\Box t\) if and only if \(K \phi \in t\) if and only if \(K \phi \in s\), where \(\phi \in L'\).

We shall now prove that the canonical model \(C\) of \(MP^*\) satisfies the conditions of Section [1] on page [3]

We now have the following

**Theorem 43** The canonical model \(C\) of \(MP^*\) satisfies conditions 1 to 7 of Section [1] on page [3].

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Corollary 44 The canonical frame of $\text{MP}^\ast$ is isomorphic to a subset frame $\mathcal{F}_{\mathcal{O}_c}$ where $(X_c, \mathcal{O}_c)$ is a subset space closed under infinite intersections and if $U, V \in \mathcal{O}_c$ have an upper bound in $\mathcal{O}_c$, then $U \cup V \in \mathcal{O}_c$.

By the construction of Theorem 26, $X_c$ consists of the ending points of the members of the domain of the canonical model. We define the following initial assignment $i_c$

$$i(A) = \{ s_0 \mid A \in s_0 \}.$$ 

In this way the model $\mathcal{M} = \langle X_c, \mathcal{O}_c, i_c \rangle$ is equivalent to the canonical model as a corollary of frame isomorphism.

Corollary 45 For all $s \in S$ and $\phi \in \mathcal{L}$ we have

$$\phi \in s \text{ if and only if } s_0, U_s \models_{\mathcal{M}} \phi.$$ 

Proposition 46 The frame of a generated submodel $\mathcal{C}^\Gamma$ is isomorphic to a closed topological frame.

Now as above we have the following corollary

Corollary 47 A submodel $\mathcal{C}^\Gamma$ is equivalent to a closed topological model.

It is a well known fact that a modal system is characterized by the class of generated frames of the canonical frame.

Proposition 48 The system $\text{MP}^\ast$ is (strongly) characterized by closed topological frames.

Since the axioms and rules of $\text{MP}^\ast$ are sound for the wider class of subset spaces with finite union and intersection, we also have the following.

Proposition 49 The system $\text{MP}^\ast$ is (strongly) characterized by subset frames closed under finite unions and intersections.

Now by Proposition 48 and 49, Corollary 18 and Theorem 19 of Chapter 3, where we proved the equivalence of a topological model with the model induced by a basis closed under finite unions, we have the following corollary

Corollary 50 The system $\text{MP}^\ast$ is (strongly) characterized by open topological frames as well as subset frames closed under infinite unions and intersections.

The following disjunction property holds for $\text{MP}^\ast$

if $\vdash_{\text{MP}^\ast} K\phi_1 \lor K\phi_2 \lor \ldots \lor K\phi_n$ then $\vdash_{\text{MP}^\ast} \phi_i$, for some $i$, $1 \leq i \leq n$.

for $\phi_1, \phi_2, \ldots, \phi_n \in \mathcal{L}'$. Note that the disjunction rule does not hold for $\text{S5}$.

Proposition 51 $\text{MP}^\ast$ provides the above rule of disjunction.
We can similarly prove a stronger disjunction property, namely

if \( \vdash_{\text{MP}^*} K\phi \to K\phi_1 \lor K\phi_2 \lor \ldots \lor K\phi_n \)
then \( \vdash_{\text{MP}^*} K\phi \to \phi_i \), for some \( i, \ 1 \leq i \leq n \),

for \( \phi, \phi_1, \phi_2, \ldots, \phi_n \in \mathcal{L}' \).

Now we are able to prove the following

**Theorem 52** The canonical model of \( \text{MP}^* \) is strongly generated.

By Theorem 52 we complete the set of conditions of page 14 which turn the frame of the canonical model into a closed subset frame. To summarize, we have the following corollary (note that the canonical subset model is \( \langle X_c, \mathcal{O}_c, i_c \rangle \) of Corollary 44)

**Corollary 53** The canonical subset model of \( \text{MP}^* \) is a topological space.

## 5 The Algebras of MP and MP*

In this section we shall give a more general type of semantics for \( \text{MP} \) and \( \text{MP}^* \). Every modal logic can be interpreted in an algebraic framework. An algebraic model is nothing else but a valuation of the propositional variables in a class of appropriately chosen algebras. We shall also make connections with the previous chapters.

### 5.1 Fixed Monadic Algebras

Interior operators were introduced by McKinsey and Tarski \[MT44\].

**Definition 54** An interior operator \( I \) on a Boolean algebra \( \mathcal{B} = \langle B, 0, 1, \cap, \cup \rangle \) is an operator satisfying the conditions

\[
I(a \cap b) = Ia \cap Ib,
\]
\[
Ia \leq a,
\]
\[
IIa = Ia,
\]
\[
I1 = 1.
\]

To each interior operator \( I \) we associate its dual \( C = -I- \), called closure operator.

Universal quantifiers were introduced by P. Halmos \[Hal56\].

**Definition 55** A universal quantifier \( \forall \) on a Boolean algebra \( \mathcal{B} \) is an operator satisfying the conditions

\[
\forall(a \cup \forall b) = \forall a \cup \forall b,
\]
\[
\forall a \leq a,
\]
\[
\forall 1 = 1.
\]
To each universal quantifier $\forall$ we associate its dual $\exists = \neg\neg$, called existential quantifier.

**Definition 56** Let $I$ be an interior operator on a Boolean algebra $B$. Let $IB = \{a | a \leq Ia\}$ and $CB = \{a | Ca \leq a\}$, i.e., the fixed points of $I$ and $C$ respectively. Let $B^I = IB \cap CB$ then $B^I = \langle B^I, 0, 1, -, \cap, \cup \rangle$ is a Boolean subalgebra of $B$.

**Definition 57** A fixed monadic algebra (FMA) $B$ is a Boolean algebra with two operators $I$ and $\forall$ satisfying $\forall Ia \geq I \forall a$.

A valuation $v$ on $B$ is a function from the formulae of $\text{MP}$ to the elements of $B$ such that

- $v(A) \in B^I$, where $A$ is atomic,
- $v(\neg \phi) = -v(\phi)$,
- $v(\phi \land \psi) = v(\phi) \cap v(\psi)$,
- $v(\phi \lor \psi) = v(\phi) \cup v(\psi)$,
- $v(\Box \phi) = I v(\phi)$,
- $v(K \phi) = \forall v(\phi)$.

An algebraic model of $\text{MP}$ is a FMA $B$ with a valuation $v$ on it. We say $\phi$ is valid in this model iff $v(\phi) = 1$ and valid in an FMA iff it is valid in all models based on this algebra. Finally, $\phi$ is FMA-valid if it is valid in all FMA’s. The notion of validity can extend to a set of formulae.

Observe that the important part of the algebra is the smallest subalgebra containing $B^I$ and closed under the operators $I$ and $\forall$.

**Theorem 58 (Soundness for FMA-validity)** If a formula $\phi$ is a theorem of $\text{MP}$ then $\phi$ is FMA-valid.

**Theorem 59 (Completeness for FMA-validity)** If $\phi$ is FMA-valid then $\phi$ is a theorem of $\text{MP}$.

### 5.2 Generated Monadic Algebras

We shall now define the algebraic models of $\text{MP}^*$

**Definition 60** A generated monadic algebra (GMA) $B$ is an FMA satisfying in addition

$$CIa = ICa$$

$$C(\forall a \cap b) \cap \exists C(\forall a \cap c) \leq C(\forall Ca \cap Cb \cap \exists Cc).$$

The concepts of algebraic model, validity, GMA-validity are defined as for FMA’s. We used the direct algebraic translation of $\text{MP}^*$ axioms but we could
have defined it with a different presentation. Observe that we only need \( \text{CIA} \leq \text{ICa} \) because the other direction is derivable (see Proposition 61.)

We now have the following

**Theorem 61 (Algebraic completeness of MP\(^*\))** A formula \( \phi \) is a theorem of MP\(^*\) if and only if \( \phi \) is GMA-valid.

It is known that a modal algebra determines a (general) frame (see [BS84].) So, in our case, the canonical algebraic model of MP\(^*\), i.e. its Lindenbaum algebra, must determine a closed topological model (actually its canonical frame.) We shall state only the interesting part of this correspondence: the bijection on the domains. The accessibility relations are defined in the usual way.

**Theorem 62** There is a bijection between the set of the ultrafilters of the canonical algebra of MP\(^*\) and the pointed product \( X \times T \), where \( (X, T) \) is the canonical topology of MP\(^*\).

The general theory of modal logic provides for yet another construction. A frame determines a modal algebra. In case of the canonical frame, the modal algebra determined must be isomorphic to the canonical modal algebra. In our case, this algebra (which must be a GMA) has a nice representation. It is the algebra of partitions of the topological lattice as it appeared in Section 3.1.

## 6 Further Directions

There are several further directions

1. Due to the indeterminacy assumption (see Introduction) MP\(^*\) can be a "core" logical system for reasoning about computation with approximation or uncertainty.

2. A discrete version of our epistemic framework can arise in scientific experiments or tests. We acquire knowledge by "a step-by-step" process. Each step being an experiment or test. The outcome of such an experiment or test is unknown to us beforehand, but after being known it restricts our attention to a smaller set of possibilities. A sequence of experiments, test or actions comprises a strategy of knowledge acquisition. This model is in many respects similar to Hintikka’s “oracle” (see [Hin86].) In Hintikka’s model the “inquirer” asks a series of questions to an external information source, called “oracle”. The oracle answers yes or no and the inquirer increases her knowledge by this piece of additional evidence. This framework can be expressed by adding actions to the language. Preliminary work of ours used quantales for modelling such processes. A similar work without knowledge considerations appears in [AV90].

3. Since we can express concepts like affirmative or refutative assertions, which are closed under infinite disjunctions and conjunctions respectively,
it is very natural to add infinitary connectives or fixed points operators (the latter as a finite means to express the infinitary connectives.) This would serve the purpose of specifying such properties of programs as “emits an infinite sequence of ones” (see [Abr91] for a relevant discussion.) An interesting direction of linking topological spaces with programs can be found in [Par83].

4. Our work in the algebras of $\mathbf{MP}^*$ looks very promising. GMAs (see [Par83]) have very interesting properties. A subalgebra of a GMA corresponds to a complete space and this duality can be further investigated with the algebraic machinery of modal logic (see [Lem66a], [Lem66b], [Blo80]) or category theoretic methods.

5. Axiom [H] forces monotonicity in our systems. If we drop this axiom, an application of effort no longer implies a further increase in our knowledge. Any change of our state of knowledge is possible. A non-monotonic version of the systems presented in this thesis can be given along the lines of [Par87a].

6. It would be interesting to consider a framework of multiple agents. Adding a modality $K_i$ for each agent $i$ and assigning a different set of subsets or topology to to each agent we can study their interaction or communication by set-theoretic or topological means.

7. From our work became clear that both systems considered here are linked with intuitionistic logic. We have embed intuitionistic logic to $\mathbf{MP}$ or $\mathbf{MP}^*$ and it would be interesting to see how much of the expressiveness of these logics can be carried in an intuitionistic framework.

8. Finally, in another direction Rohit Parikh considers an enrichment of the language to express more (and purely) topological properties such as separation properties and compactness.

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