Bloomier Filters: A second look

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Abstract. A Bloom filter is a space efficient structure for storing static sets, where the space efficiency is gained at the expense of a small probability of false-positives. A Bloomier filter generalizes a Bloom filter to compactly store a function with a static support. In this article we give a simple construction of a Bloomier filter. The construction is linear in space and requires constant time to evaluate. The creation of our Bloomier filter takes linear time which is faster than the existing construction. We show how one can improve the space utilization further at the cost of increasing the time for creating the data structure.

1 Introduction

A Bloom filter is a compact data structure that supports set membership queries [2]. Given a set $S \subseteq D$ where $D$ is a large set and $|S| = n$, the Bloom filter requires space $O(n)$ and has the following properties. It can answer membership queries in $O(1)$ time. However, it has one-sided error: Given $x \in S$, the Bloom filter will always declare that $x$ belongs to $S$, but given $x \in D \setminus S$ the Bloom filter will, with high probability, declare that $x \notin S$. Bloom filters have found wide ranging applications [4, 5, 14, 16, 19, 20]. There have also been generalizations in several directions of the Bloom filter [8, 13, 21, 23]. More recently, Bloom filters have been generalized to “Bloomier” filters that compactly store functions [7]. In more detail: Given $S \subseteq D$ and a function $f : S \to \{0, 1\}$ a Bloomier filter is a data structure that supports queries to the function value. It also has one-sided error: given $x \in S$, it always outputs the correct value $f(x)$ and if $x \in D \setminus S$ with high probability it outputs ‘⊥’, a symbol not in the range of $f$. In [7] the authors construct a Bloomier filter that requires, $O(n \log n)$ time to create; $O(n)$ space to store and, $O(1)$ time to evaluate.

In this paper we give an alternate construction of Bloomier filters, which we believe is simpler than that of [7]. It has similar space and query time complexity. The creation is slightly faster, $O(n)$ vs. $O(n \log n)$. Changing the value of $f(x)$ while keeping $S$ the same is slower in the worst case for our method, $O(\log n)$ vs. $O(1)$. For a detailed comparison we direct the reader to §6. In §3 we discuss another construction that is very natural and has a smaller space requirement. However, this algorithm has a creation time of $O(n^3)$ which is too expensive. In §4 we discuss how bucketing can be used to reduce the construction time of this algorithm to $n \log^{O(1)} n$ and make it more practical. In §7 we discuss some experimental results comparing the existing construction to ours for storing the in-degree information for a billion URLs.

2 The construction

2.1 A 1-bit Bloomier Filter

We begin with the following simplified problem: Given a set $S$ of $n$ elements and a function $f : S \to \{0, 1\}$, encode $f$ into a space efficient data structure that allows fast access to the values of $f$. A simple way to solve this problem is to use a hash table (with open addressing) which requires $O(n)$ space and $O(1)$ time on average to evaluate $f$. If we want worst case $O(1)$ time for function evaluation, we could try different hash functions until we find one which produces few hash collisions on the set $S$. This solution however does not generalize to our ultimate goal which is to have a compact encoding of the function $f : D \to \{0, 1, \perp\}$, where $f|_S = f$ and $f(x) = \perp$ with high probability if $x \notin S$. Thus if $D$ is much larger than $S$, the solution using
hash tables is not very attractive as it uses space proportional to $D$. To counter-act this one could use the hash table in conjunction with a Bloom filter for $S$. This is not the approach we will take\footnote{The reason this is not optimal is because to achieve error probability $\epsilon$, we will need to evaluate $O(\log 1/\epsilon)$ hash functions.}.

Our approach to solving the simplified problem uses ideas from the creation of minimal perfect hashes (see [9]). We first map $S$ onto the edges of a random (undirected) graph $G(V,E)$ constructed as follows. Let $V$ be a set of vertices with $|V| \geq |S|$, where $c \geq 1$ is a constant. Let $h_1, h_2 : D \rightarrow V$ be two hash functions. For each $x \in S$, we create an edge $e = (h_1(x), h_2(x))$ and let $E$ be the set of edges formed in this way (so that $|E| = |S| = n$). If the graph $G$ is not acyclic we try again with two independent hash functions $h'_1, h'_2$. It is known that if $c > 2$, then the expected number of vertices on tree components is $|V| + O(1)$ ([3] Theorem 5.7 ii). Indeed, in [10] the authors proved that if $G(V, E)$ is a random graph with $|V| = c|E|$ and $c > 2$, then with probability $\exp(1/c)\sqrt{(c-2)/c}$ the graph is acyclic. Thus, if $c > 2$ is fixed then the expected number of iterations till we find an acyclic graph is $O(1)$. In particular, if $c \geq 2.09$ then with probability at least $1/3$ the graph $G$ is acyclic. Thus the expected number of times we will have to re-generate the graph until we find an acyclic graph is $\leq 3$. Once we have an acyclic graph $G$, we try to find a function $g : V \rightarrow \{0, 1\}$ such that $f(x) \equiv g(h_1(x)) + g(h_2(x)) \pmod{2}$ for each $x \in S$. One can view this as a sequence of $n$ equations for the variables $g(v), v \in V$. The fact that $G$ is acyclic implies that the set of equations can be solved by simple back-substitution in linear time. We then store the table of values $g(v) (\in \{0, 1\})$ for each $v \in V$.

To evaluate the function $f$, given $x$, we compute $h_1(x)$ and $h_2(x)$ and add up the values stored in the table $g$ at these two indices modulo 2. The expected creation time is $O(n)$, evaluation time is $O(1)$ (two hash function computations and two memory lookups to the table of values $g$) and the space utilization is $|cn|$ bits.

Next, we generalize this approach to encoding the function $\bar{f} : D \rightarrow \{0, 1, \perp\}$ that when restricted to $S$ agrees with $f$ and outside of $S$ it maps to $\perp$ with high probability. Here again we will use the same construction of the random acyclic graph $G(V,E)$ together with a map from $S \rightarrow E$ via two hash functions $h_1, h_2$. Let $m \geq 2$ be an integer and $h_3 : D \rightarrow \mathbb{Z}/m\mathbb{Z}$ be another independent hash function. We solve for a function $g : V \rightarrow \mathbb{Z}/m\mathbb{Z}$ such that the equations $f(x) \equiv g(h_1(x)) + g(h_2(x)) + h_3(x) \pmod{m}$ holds for each $x \in S$. Again since the graph $G$ is acyclic these equations can be solved using back-substitution. Note that back-substitution works even though we are dealing with the ring $\mathbb{Z}/m\mathbb{Z}$ which is not a field unless $m$ is prime. To evaluate the function $f$ at $x$ we compute $h_i(x)$ for $1 \leq i \leq 3$ and then compute $g(h_1(x)) + g(h_2(x)) + h_3(x) \pmod{m}$. If the computed value is either 0 or 1 we output it otherwise, we output the symbol $\perp$. Algorithms 1 and 2 give the steps of the construction in more detail. It is clear that if $x \in S$ then the value output by our algorithm is the correct value $f(x)$. If $x \notin S$ then the value of $h_3(x)$ is independent of the values of $g(h_1(x))$ and $g(h_2(x))$ and uniform in the range $\mathbb{Z}/m\mathbb{Z}$. Thus $\Pr_{x \in D \setminus S}[g(h_1(x)) + g(h_2(x)) + h_3(x) \in \{0, 1\}] = \frac{2}{m}$.

In summary, we have proved the following:

**Proposition 1.** Fix $c > 2$ and let $m \geq 2$ be an integer, the algorithms described above (Algorithms 1 and 2) implement a Bloomier filter for storing the function $f : D \rightarrow \{0, 1, \perp\}$ and the underlying function $f : S \rightarrow \{0, 1\}$ with the following properties:

1. The expected time for creation of the Bloomier filter is $O(n)$.
2. The space used is $[cn][\log_2 m]$ bits, where $n = |S|$.
3. Computing the value of the Bloomier filter at $x \in D$ requires $O(1)$ time (3 hash function computations and 2 memory lookups).
4. Given $x \in S$, it outputs the correct value of $f(x)$.
5. Given $x \notin S$, it outputs $\perp$ with probability $1 - \frac{2}{m}$.

### 2.2 General $k$-bit Bloomier Filters

It is easy to generalize the results of the previous section to obtain Bloomier filters with range larger than just the set $\{0, 1\}$. Given a function $f : S \rightarrow \{0, 1\}^k$ it is clear that as long as the range $\{0, 1\}^k$ embeds into the ring
In this section we consider the task of handling changes to the function stored in the Bloomier filter produced by the algorithms in the previous section. We will only consider changes to the function \( f : S \to \{0, 1\}^k \) in \( \mathbb{Z}/m\mathbb{Z} \). One can still use Algorithm 1 without any changes. This translates into the simple requirement that we take \( m \geq 2^k \). Algorithm 2 needs a minor modification, namely, we check if \( f = g(h_1(x)) + g(h_2(x)) + h_3(x) \mod m \) (mod \( m \)) \in \{0, 1\}^k \) and if so we output \( f \) otherwise, we output \( \perp \). We encapsulate the claims about the generalization in the following theorem (the proof of which is similar to that of Proposition 1):

**Theorem 1.** Fix \( c > 2 \) and let \( m \geq 2^k \) be an integer, the algorithms described above implement a Bloomier filter for storing the function \( f : D \to \{0, 1\}^k \cup \{\perp\} \), and the underlying function \( f : S \to \{0, 1\}^k \) with the following properties:

1. The expected time for creation of the Bloomier filter is \( O(n) \).
2. The space used is \( \lfloor cn \rfloor \cdot \log_2 m \) bits, where \( n = |S| \).
3. Computing the value of the Bloomier filter at \( x \in D \) requires \( O(1) \) time (3 hash function computations and 2 memory lookups).
4. Given \( x \in S \), it outputs the correct value of \( f(x) \).
5. Given \( x \notin S \), it outputs \( \perp \) with probability \( 1 - \frac{2^k}{m} \).

**Algorithm 1** Generate Table

**Input:** A set \( S \subseteq D \) and a function \( f : S \to \{0, 1\}, c > 2 \), and an integer \( m \geq 2 \).

**Output:** Table \( g \) and hash functions \( h_1, h_2, h_3 \) such that \( \forall s \in S : g[h_1(s)] + g[h_2(s)] + h_3(s) \equiv f(s) \mod m \).

Let \( V = \{0, 1, \ldots, [cn] - 1\} \), where \( n = |S| \)

\[
\begin{align*}
\text{repeat} & \quad \text{Generate } h_1, h_2 : D \to V \text{ where } h_i \text{ are chosen independently from } \mathcal{H} - \text{a family of hash functions; Let } E = \\
& \{ (h_1(s), h_2(s)) : s \in S \}. \\
\text{until } G(V, E) \text{ is a simple acyclic graph.} \\
\text{Let } h_3 : D \to \mathbb{Z}/m\mathbb{Z} \text{ be a third independently chosen hash function from } \mathcal{H}.
\end{align*}
\]

\[
\text{for all } T - \text{ a connected component of } G(V, E) \text{ do} \\
\quad \text{Choose a vertex } v \in T \text{ whose degree is non-zero.} \\
\quad F \leftarrow \{v\}; g[v] \leftarrow 0. \\
\quad \text{while } F \neq T \text{ do} \\
\qquad \text{Let } C \text{ be the set of nodes in } T \setminus F \text{ adjacent to nodes in } F. \\
\qquad \text{for all } w = h_i(s) \in C \text{ do} \\
\quad \quad g[w] \leftarrow f(s) - g[h_{3-i}(s)] - h_3(s) \mod m. \\
\qquad \text{end for} \\
\quad F \leftarrow F \cup C. \\
\quad \text{end while} \\
\text{end for}
\]

**Algorithm 2** Query function

**Input:** Table \( g, h_1, h_2 : D \to \{0, \ldots, [cn] - 1\}, h_3 : D \to \mathbb{Z}/m\mathbb{Z} \) hash functions and \( x \in D \).

**Output:** \( 0, 1 \) or \( \perp \) - the output of the Bloomier filter represented by the table \( g \).

\[
f \leftarrow g[h_1(x)] + g[h_2(x)] + h_3(x) \mod m. \\
\text{if } f \in \{0, 1\} \text{ then} \\
\quad \text{Output } f. \\
\text{else} \\
\quad \text{Output } \perp.
\]

2.3 **Mutable Bloomier filters**

In this section we consider the task of handling changes to the function stored in the Bloomier filter produced by the algorithms in the previous section. We will only consider changes to the function \( f : S \to \{0, 1\}^k \)
where $S$ remains the same but only the values taken by the function changes. In other words, the support of the function remains static.

Consider what happens when $f : S \rightarrow \{0, 1\}^k$ is changed to the function $f' : S \rightarrow \{0, 1\}^k$ where $f(x) = f'(x)$ except for a single $y \in S$. In this case we can change the values stored in the $g$-table so that we output the value of $f'$ at $y$. We assume that the edges of the graph $G$ are available (this is an additional $O(n \log n)$ bits). We begin with the observation that the values stored at $g(v)$ for vertices $v$ not in the connected component containing the edge $e = (h_1(y), h_2(y))$ remain unaffected. Thus changing $f$ to $f'$ affects only the $g$ values of the connected component, $C$ (say), containing the edge $e$. Recomputing the $g$ values corresponding to $C$ would take time $O(|C|)$. How big can the largest connected component in $G$ get? Our graph $G(V, E)$ built in Algorithm 1 is a sparse random graph with $|E| < \frac{1}{2}|V|$. A classical result due to Erdős and Rényi says that in this case the largest component is almost surely\(^2\) $O(\log n)$ in size where $n = |V|$ (see [12] or [3]). Thus updates to the Bloomier filter take $O(\log n)$ time provided we ensure that the largest component in $G$ is small when creating it. The result from [12] tells us that adding the extra condition while creating $G$ will not change the expected running time of Algorithm 1. We call this modified algorithm Algorithm 1’.

**Theorem 2.** The Bloomier filter constructed using algorithms 1’ and 2 can accommodate changes to function values in time $O(\log n)$, provided the graph $G$ is also retained. Moreover, the claims of Theorem 1 remain true for algorithms 1’ and 2.

### 3 Reducing the space utilization

If we are willing to spend more time in the creation phase of the Bloomier filter, we can further reduce the space utilization of the Bloomier filter. In this section we show how one can get a Bloomier filter for a function $f : S \rightarrow \{0, 1\}^k$ with error rate $\frac{\epsilon}{2n}$ using only $n(1 + \epsilon)[\log_2 m]$ bits of storage, where $n = |S|$ and $\epsilon > 0$ is a constant. In §2 we used a random graph generated by hash functions to systematically generate a set of equations that can be solved efficiently. The solution to these equations is then stored in a table which in turn encodes the function $f$. The main idea to reduce space usage further is to have a table $g[0], g[1], \ldots, g[N-1]$, where $N = (1 + \epsilon)n$, and try to solve the following set of equations over $\mathbb{Z}/m\mathbb{Z}$:

$$\sum_{1 \leq i \leq s} h_i(x)g[h_i(x)] + h_0(x) = f(x), \quad x \in S$$

(1)

for the unknowns $g[0], \ldots, g[N-1]$. Here $s \geq 1$ is a fixed integer and $h_0, h_1, \ldots, h_{2s}$ are independent hash functions. Since $s$ is fixed, look up of a function value will only take $O(1)$ hash function evaluations. These equations can be solved provided the determinant of the sparse matrix corresponding to these equations is a unit in $\mathbb{Z}/m\mathbb{Z}$. The next subsection gives an answer (under suitable conditions) to this question when $m$ is a prime.

#### 3.1 Full rank sparse matrices over a finite field

Let $GL^s_{n \times r}(F_p)$ be the set of full rank $n \times r$ matrices over $F_p$\(^3\) that have exactly $s$ non-zero entries in each column. Our aim in this section is to get a lower bound for $\sharp GL^s_{n \times r}(F_p)$ (the cardinality of this set). We note the following lemma whose proof we omit.

**Lemma 1.** Let $M^s_{n \times r}(F_p)$ be the matrices over $F_p$ where each column has exactly $s$ non-zero entries. Then $\sharp M^s_{n \times r}(F_p) = \binom{n}{s}(p-1)^s$.

\(^2\) This means that the probability that the condition holds is $1 - o(1)$.

\(^3\) Here $p$ is a prime number and $F_p$ is the finite field with $p$ elements. Any two finite fields with $p$ elements are isomorphic and the isomorphism is canonical. If the field has $p^r$, $r > 1$, elements then the isomorphism is not canonical.
Before we begin the task of getting a lower bound for the sparse full rank matrices we briefly recall the method of proof for finding \(\mathbb{GL}_n(F_p)\) – the group of invertible \(n \times n\) matrices over \(F_p\). One can build invertible matrices column by column as follows: Choose any non-zero vector for the first column, there are \(p^n - 1\) ways of choosing the first column. The second column vector should not lie in the linear span of the first. Therefore there are \(p^n - p\) choices for the second column vector. Proceeding in this way there are \(p^n - p^j\) for the \(j + 1\) column. Thus we have \(\mathbb{GL}_n(F_p) = \prod_{0 \leq j < n}(p^n - p^{n-j})\).

One can adapt this idea to get a bound on the invertible \(s\)-sparse matrices. There are \(\binom{n}{s}(p - 1)^s\) ways of choosing the first column. Inductively, suppose we have chosen the first \(i\) columns to be linearly independent, then we have a vector space \(V_i \subseteq F_p^n\) of dimension \(i\) spanned by the first \(i\) columns. One can grow this matrix to a rank \(i + 1\) matrix by augmenting it by any \(s\)-sparse vector \(v \notin V_i\). Thus we are faced with the task of finding an upper bound on the number of \(s\)-sparse vectors contained in \(V_i\). We introduce some notation: suppose \(v = (v_1, v_2, \ldots, v_n)^t \in F_p^n\) is a vector then we define \(v^{\circ}\) to be the vector \((v_n, v_1, \ldots, v_{n-1})^t\) (a cyclic shift of \(v\)). Note that if \(v\) is \(s\)-sparse then so is \(v^{\circ}\). Our approach is to show that under certain circumstances the vector space spanned by the orbit of a sparse vector under the circular shifts have high dimension and consequently, all the shifts cannot be contained in \(V_i\) (unless \(i = n\)). It is natural to expect that given a \(s\)-sparse vector \(v\), the vector space \(W^{\circ}\) spanned by all the circular shifts \(v, v^{\circ}, \ldots, v^{\circ^{n-1}}\) has dimension \(\geq n - s\). Unfortunately, this is not so: For example, consider \(v = (1, 0, 1, 0, 1, 0)\) whose cyclic shifts generate a vector space of dimension 2. This motivates the next lemma.

**Lemma 2.** Suppose \(q\) is a prime number and \(v \in F_p^n\) is an \(s\)-sparse vector with \(0 < s < q\). Then the orbit \(\{v, v^{\circ}, \ldots, v^{\circ^{n-1}}\}\) has cardinality \(q\).

**Proof.** We have a natural action of the group \(\mathbb{Z}/q\mathbb{Z}\) on the set of cyclic shifts of \(v\), via \(a \mapsto v^{\circ^a}\). Suppose we have \(v^{\circ^i} = v^{\circ^j}\) for \(0 \leq i \neq j \leq q - 1\). Then we have \(v^{\circ^{i+j}} = v = v^{\circ^q}\). Since we have a group action this implies that \(v^{\circ^{i+j}} = v\). Since \(q\) is prime this means that \(v^{\circ} = v\). But \(0 < s < q\) therefore \(v^{\circ} \neq v\) and we have a contradiction. \(\square\)

One can show that the vector space spanned by the cyclic shifts of an \(s\)-sparse vector \((0 < s < n)\) has dimension at least \(n/s\). However, this bound is not sufficient for our purpose. We need the following stronger conditional result whose proof is relegated to the appendix (see Theorems 8 and 9 in the Appendix).

**Theorem 3.** Let \(v = (w_0, \ldots, w_{q-1}) \in F_p^q\), where \(p\) is a prime that is a primitive root modulo \(q\) (i.e., \(p\) generates the cyclic group \(\mathbb{F}_q^*\)). Suppose \(w_0 + w_1 + \cdots + w_{q-1} \neq 0\) and \(w_i\) are not all equal, then \(W^{\circ}\) (the vector space spanned by the cyclic shifts of \(v\)) has dimension \(q\).

Let \(V_i\) be a vector space of dimension \(i\) contained in \(F_p^n\). We have \(\frac{1}{q}\binom{q}{s}\) \((p - 1)^s\) orbits of size \(q\) under the action of \(\mathbb{Z}/q\mathbb{Z}\) on the \(s\)-sparse vectors. If \(s < n\) then all the coordinates cannot be identical. Once the \(s\) non-zero positions for an \(s\)-sparse vector are chosen then there are \(\geq (p - 1)^s - (p - 1)^{s-1}\) vectors whose coordinates do not sum to zero\(^4\). Now each of these orbits generates a vector space of rank \(q\) by the above theorem. In each orbit there are at most \(i\) vectors that can belong to \(V_i\). Consequently, there are at least

\[
\frac{1}{q}\binom{q}{s}{(p - 1)^s - (p - 1)^{s-1}} (q - i)
\]

\(s\)-sparse vectors that do not belong to \(V_i\). We have thus proved the following theorem:

**Theorem 4.** Let \(q, p\) be prime numbers such that \(p\) is congruent to a primitive root modulo \(q\). Then

\[
\mathbb{GL}_n(F_p) \geq \prod_{0 \leq i \leq r-1} \left(\frac{1}{q}\binom{q}{s}{(p - 1)^s - (p - 1)^{s-1}} (q - i)\right) \cdot \frac{(p-1)((p-1)^s+(−1)^{s+1})}{p}.
\]

\(^4\) Indeed, it is not hard to show that the exact number of such vectors is \(\frac{(p-1)((p-1)^s+(−1)^{s+1})}{p}\).
We note that the bound obtained above is almost tight\(^5\) in the case \(s = 1\), where the 1-sparse matrices are simply diagonal matrices (with non-zero entries) multiplied by permutation matrices.

### 3.2 The Algorithm

The outline of the algorithm is as follows. To create the Bloomier filter given \(f : S \rightarrow \{0,1\}^k\), we consider each element \(x\) of \(S\) in turn. We generate a random equation as in (1) for \(x\) and check that the list of equations that we have so far has full rank. If not, we generate another equation using a different set of \(2s\) hash functions. At any time, we keep the hash functions that have been used so far in blocks of \(2s\) hash functions. When generating a new equation we always start with the first block of hash functions and try subsequent blocks only if the previous blocks failed to give a full rank system of equations. The results of the previous section show that the expected number of blocks of hash functions is bounded (provided the vector space has high dimension). Once we have a full rank set of equations for all the elements of \(S\), we then proceed to solve the sparse set of equations. The solution to the equations is then stored in a table. At look up time, we generate the equations using each block of hash functions in turn and output the first value in the range of \(f\).

The first step of the algorithm finds the smallest prime larger than \(q\) for \(q\) obtained in \(\operatorname{Algorithm 3}\). The final loop of the algorithm attempts to find a random prime \(p\) where \(p \equiv g_i \pmod{q}\) for some \(i\), and \(p\) is prime.

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\(^5\) The bound is tight if we use the exact formula for the number of \(s\)-sparse vectors that do not sum to 0 in the derivation.
the interval $[2^{m-1} \cdots 2^m - 1]$. Again, by the prime number theorem for arithmetic progressions, the number of primes in this interval is \( \sim \frac{\varphi(q-1)x}{2(q-1)(m^2-2)} \), where \( x = 2^m - 1 \). This tells us that the expected number of iterations of the loop is about \( \frac{2 \ln(2q-1)(m-1)}{\varphi(q-1)} = O(m \log \log q) \). We can use a probabilistic primality test to check for primality of the random \( m \)-bit numbers that we generate. If we use the Miller-Rabin primality test (from [22]) the expected number of bit-operations\(^6\) is \( O(m^4) \). In summary, the expected running time of Algorithm 3 is \( \tilde{O}(n + m^4) \). Note that \( m \) will be very small in practice (a prime of about 64-bits should suffice).

**Algorithm 4 Create Table**

**Input:** A set \( S \subseteq D \) and a function \( f : S \rightarrow \{0, 1\}^k \), two primes \( p, q \), \( \mathcal{H} \) a hash family, and \( s \geq 2 \).

**Output:** Table \( g, h_0 \) a hash function and \( r \) blocks of \( 2s \) hash functions \( B_i \).

1. Let \( h_0 \) be a random hash function from \( \mathcal{H} \).
2. Let \( i \leftarrow 0 \).
3. **for all** \( x \in S \) **do**
   1. \( i \leftarrow i + 1 \); \( j \leftarrow 0 \).
   2. **repeat**
      1. **if** \( B_j \) is not defined **then**
         1. Generate \( h_1, \ldots, h_{2s} \) random hash functions from \( \mathcal{H} \).
         2. \( B_j \leftarrow \{h_1, \ldots, h_{2s}\} \).
      **end if**
   3. **end repeat**
   4. Let \( h_1, \ldots, h_{2s} \) be the hash functions in \( B_j \).
   5. \( M[i, h_{k+s}(x)] \leftarrow h_k(x) \) for \( 1 \leq k \leq s \); \( j \leftarrow j + 1 \).
5. **until** \( \text{Rank}(M) = i \)
6. **end for**
7. Let \( v = (f(x) - h_0(x) : x \in S)^\dagger \).
8. Solve the system \( M \times g = v \) for \( g = \langle g[i] : 1 \leq i \leq q \rangle^\dagger \) over \( \mathbb{F}_p \).

9. **Return** \( g, h_0 \) and \( B_i \).

**Analysis of Algorithm 4:** The algorithm essentially mimics the proof of Theorem 4. It starts with a rank \( i \) matrix and grows the matrix to a rank \( i + 1 \) matrix by adding an \( s \)-sparse row using hash functions in \( B_j \).\(^7\) Let \( n = |S| \) and suppose, \( q \geq n(1 + \epsilon) \) for a fixed \( \epsilon > 0 \). Then equation (2) tells us that in \( O(1/\epsilon) \) iterations we will find that the rank of the matrix increases. In more detail, the probability that a random \( s \)-sparse vector does not lie in \( V_i \) is at least \( \frac{q - 1}{q} \) since \( i < n \) and \( q \geq n(1 + \epsilon) \). Note that this requires rather strong pseudorandom properties from the hash family \( \mathcal{H} \). As mentioned in the discussion following Lemma 4.2 in [7], a family of cryptographically strong hash functions is needed to ensure that the vectors generated by the hash function from the input behave as random and independent sparse vectors over the finite field. We will make this assumption on the hash family \( \mathcal{H} \). Checking the rank can be done by Gaussian elimination keeping the resulting matrix at each stage. The inner-loop thus runs in expected \( O(n^2) \) time and the “for” loop takes \( O(n^3) \) time on average. Solving the resulting set of sparse equations can be done in \( O(n^3) \) time since the Gaussian elimination has already been completed. The algorithm also generates \( r \) blocks of hash functions, and by the earlier analysis the expected value of \( r \) is \( O(1/\epsilon) \). In summary, the expected running time of Algorithm 4 is \( O(n^3) \). We refer the reader to the appendix for a discussion on why sparse matrix algorithms cannot be used in this stage, and also why \( s = 1 \) cannot be used here.

**Analysis of Algorithm 5:** In this algorithm we try the blocks of hash functions and output the first “plausible” value of the function (namely, a value in the range of the function \( f \)). If the wrong block, \( B_i \), of hash functions was used then the probability that the resulting function value, \( y \), belongs to the range \( \text{Output:} \)

\( M \leftarrow (0)_{n \times q} \) (a \( n \times q \) zero matrix).

\( g, h_0 \) a hash function from \( \mathcal{H} \).

\( i \leftarrow 0 \).

**for all** \( x \in S \) **do**

\( i \leftarrow i + 1 \); \( j \leftarrow 0 \).

**repeat**

\( i \leftarrow i + 1 \); \( j \leftarrow 0 \).

**if** \( B_j \) is not defined **then**

1. Generate \( h_1, \ldots, h_{2s} \) random hash functions from \( \mathcal{H} \).
2. \( B_j \leftarrow \{h_1, \ldots, h_{2s}\} \).

**end if**

Let \( h_1, \ldots, h_{2s} \) be the hash functions in \( B_j \).

\( M[i, h_{k+s}(x)] \leftarrow h_k(x) \) for \( 1 \leq k \leq s \); \( j \leftarrow j + 1 \).

**until** \( \text{Rank}(M) = i \)

**end for**

Let \( v = (f(x) - h_0(x) : x \in S)^\dagger \).

Solve the system \( M \times g = v \) for \( g = \langle g[i] : 1 \leq i \leq q \rangle^\dagger \) over \( \mathbb{F}_p \).

**Return** \( g, h_0 \) and \( B_i \).

\(^6\) The soft-Oh notation, \( \tilde{O} \), hides factors of the form \( \log \log n \) and \( \log m \)

\(^7\) Strictly speaking the row could have \(< s \) non-zero entries because a hash function could map to zero. But this happens with low probability.
\( \{0,1\}^k \) is \( \frac{2^k}{p} \). If the right block \( B_i \) was used then, of course, we get the correct value of the function and \( y = f(x) \). If \( x \in D \setminus S \), then again the probability that \( y \in \{0,1\}^k \) is at most \( \frac{2^k}{p} \). Since \( r \) and \( s \) are \( O(1) \) the algorithm requires \( O(1) \) operations over the finite field \( \mathbb{F}_p \). This requires \( O(\log^2 p) \) bit operations with the usual algorithms for finite field operations, and only \( O(\log p \log \log p) \) bit operations if FFT multiplication is used.

**Algorithm 5** Query function

**Input:** Table \( g \), hash functions \( h_0, B_i, 1 \leq i \leq r, x \in D \).

**Output:** \( y \in \{0,1\}^k \) or \( \perp \).

\[
i \leftarrow 1
\]

while \( i \leq r \) do

Let \( h_1, \ldots, h_r \) be the hash functions in \( B_i \).

Let \( y \leftarrow h_0(x) + \sum_{1 \leq j \leq s} h_s(x)g[h_{i+s}(x)] \).

if \( y \in \{0,1\}^k \) then

Return \( y \).

end if

\( i \leftarrow i + 1 \)

end while

Return \( \perp \).

**How to get one-sided error:** The analysis in the previous paragraph shows that the probability that we err on any element of \( S \) is \( \leq \frac{2^k}{p} \). Thus, if \( p \) is large we can construct a \( g \) table using Algorithm 4 and verify whether we give the correct value of \( f \) for all elements of \( S \). If not, we can use Algorithm 4 again to construct another table \( g \). The probability we succeed at any stage is \( \geq 1 - \frac{2^k}{p} \), and if \( p \) is taken large enough that this is \( \geq \frac{1}{2} \), then the expected number of iterations is \( \leq 2 \). We summarize the properties of the Bloomier filter constructed in this section below:

**Theorem 5.** Fix \( \epsilon > 0 \) and \( s \geq 2 \) an integer, let \( S \subseteq D \), \( |S| = n \) and let \( m, k \) be positive integers such that \( m \geq k \). Given \( f : S \rightarrow \{0,1\}^k \), the Bloomier filter constructed, (with parameters \( \epsilon, m \) and \( s \)) by Algorithms 3 and 4, and queried, using Algorithm 5, has the following properties:

1. The expected time to create the Bloomier filter is \( \tilde{O}(n^3 + m^3) \).
2. The space utilized is \( |n(1+\epsilon)|m \) bits.
3. Computing the value of the Bloomier filter at \( x \in D \) requires \( O(1) \) hash function evaluations and \( O(1) \) memory look ups.
4. If \( x \in S \), it outputs the correct value of \( f(x) \).
5. If \( x \notin S \), it outputs \( \perp \) with probability \( 1 - O(\frac{1}{\epsilon}2^{k-m}) \).

**4 Bucketing**

The construction in §3 is space efficient but the time to construct the Bloomier filter is exhorbitant. In this section we show how to mitigate this with bucketing. To build a Bloomier filter for \( f : S \rightarrow \{0,1\}^k \), one can choose a hash function \( g : S \rightarrow \{0,1,\ldots,b-1\} \) and then build Bloomier filters for the functions \( f_i : S_i \rightarrow \{0,1\}^k \), for \( i = 0,1,\ldots,b-1 \), where \( S_i = g^{-1}(i) \) and \( f_i(x) = f(x) \) for \( x \in S_i \). The sets \( |S_i| \) have an expected size of \( |S|/b \) and hence results in a speedup for the construction time. The bucketing also allows one to parallelize of the construction process, since each of the buckets can in processed independently. To quantify the time saved by bucketing we need a concentration result for the size of the buckets produced by the hash function.

8
Fix a bucket $b_i$, $0 \leq b_i < b$ and define random variables $X_{s_j}^{(b_i)}$, \ldots, $X_{s_n}^{(b_i)}$ for $s_j \in S$ as follows: Pick a hash function $g : S \rightarrow \{0, 1, \ldots, b - 1\}$ from a family of hash functions $\mathcal{H}$ and set $X_{s_j}^{(b_i)} = 1$ if $g(s_j) = b_i$ and set $X_{s_j}^{(b_i)} = 0$ otherwise. Under the assumption that the random variables $X_{s_j}^{(b_i)}$ are mutually independent, we obtain using Chernoff bounds that $\Pr \left[ \sum_j X_{s_j}^{(b_i)} > (1 + \delta) \frac{|S|}{b} \right] < 2^{-\frac{\delta^2}{8}}$ provided $\delta > 2e - 1$. This bound holds for any bucket and consequently, $\Pr \left[ \exists j : \sum_j X_{s_j}^{(b_i)} > (1 + \delta) \frac{|S|}{b} \right] < 2^{-\frac{\delta^2}{8}}$. Thus with probability $\geq 1 - 2b2^{-\frac{\delta^2}{8}}$ all the buckets have at most $(1 + \delta) \frac{|S|}{b}$ elements. Suppose we take the number of buckets $b$ to be $\frac{|S|}{c \log |S|}$ for $c > 1$. Then the probability that all the buckets are of size $< c(1 + \delta) \log |S|$ is at least $1 - 2^{-c\delta \log |S| + \log |S| - c \log \log |S|}$ which for large enough $S$ is $> 1/2$. In other words, the expected number of trials until we find a hash function $g$ that results in all the buckets being “small” is less than 2.

Remark 1. Note that the assumption that the random variables $X_{s_j}$ be mutually independent requires the hash family to have strong pseudorandom properties. For instance, if $\mathcal{H}$ is a 2-universal family of hash functions then the random variables $X_{s_j}$ are only pairwise independent.

In the following discussion we adopt the notation from Theorem 5. We assume that we have a hash function $g$ that results in all buckets have $O(\log n)$ elements. The time for creation of the Bloomier filter in §3 for each bucket is reduced to $O(\log^3 n + r^4)$. To query the bucketed Bloomier filter, given $x$, we first compute the bucket, $g(x)$, and then query the Bloomier filter for that bucket. Thus, querying requires one more hash function evaluation than the non-bucketing version. Suppose $n_i$ is the number of elements of $S$ that belonged to the bucket defined by $b_i$, then the Bloomier filter for this bucket requires $n_i(1 + \epsilon)r$ bits. The total number of bits used is $\sum_{0 \leq i < b} n_i(1 + \epsilon)r \leq \sum_{0 \leq i < b} (n_i(1 + \epsilon) + 1)r = n(1 + \epsilon)r + br$, since $\sum_i n_i = n$. Since the number of buckets is $O(n / \log n)$, the number of bits used is $n(1 + \epsilon)r + O(rn / \log n)$.

We summarize the properties of the bucketing variant of the construction in §3 in the following theorem.

Theorem 6. Fix $\epsilon > 0$ and $s \geq 2$ an integer, let $S \subseteq D$, $|S| = n$ and let $m, k$ be positive integers such that $m \geq k$. Given $f : S \rightarrow \{0, 1\}^k$, bucketed using $|S| / \log |S|$ buckets for a fixed $c > 1$, the Bloomier filter constructed on the buckets, (with parameters $\epsilon, m$ and $s$) by Algorithms 3 and 4, and queried (on the buckets), using Algorithm 5, has the following properties:

1. The expected time to create the Bloomier filter is $\tilde{O}(\frac{n}{\log n}(\log^3 n + m^4))$.
2. The space utilized is $n(1 + \epsilon)m + O(mn / \log n)$ bits.
3. Computing the value of the Bloomier filter at $x \in D$ requires $O(1)$ hash function evaluations and $O(1)$ memory look ups.
4. If $x \in S$, it outputs the correct value of $f(x)$.
5. If $x \notin S$, it outputs $\perp$ with probability $1 - O(\frac{1}{2}2^{k-m})$.

5 A remark on the use of sparse matrices

There are more efficient algorithms for computing the rank of a sparse matrix and for inverting such matrices (see [25, 17, 18]). However, these algorithms do not lend themselves to an incremental operation: Fix $s$, given an $s$-sparse $r \times n$ matrix $M$ whose rank has already been computed by any of these algorithms, compute the rank of an $s$-sparse $(r + 1) \times n$ matrix that contains $M$ in the first $r$ rows. To reduce the running time of Algorithm 4 to $O(n^2)$, one would need to solve the above problem in $O(n)$ time. Checking that an $s$-sparse $n \times n$ matrix over $\mathbb{F}_p$ is full rank can be done in $O(n^2)$ time. However, since the $s$-sparse invertible matrices are relatively rare (consider the case when $s$ is small, for instance, 1) we cannot simply pick a random $s$-sparse matrix and have a resonable probability of it being invertible. This is why we have to build the matrix in stages as we do in the above algorithm.
implies that a hash function is able to create an injection of a set
were
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Birthday paradox implies that there will be collisions among the elements (since the hash functions map the
to have a solution we need at least two hash functions. Indeed, if we had only one hash function then the
"chosen" hash value for each element requires a matching problem to be solved. For the matching problem
first table. A bit-mask computed using another hash function is used to provide error resiliency. To find the
functions contains two hash functions. Out of these, only one of them determines the “variable” \( g[i] \) to be
used for an element. The construction then attempts to implicitly create a matching between the
S
S elements into a set of size
S
S. Let
f
f be the function that we wish to store. The approach of [7] is
as follows: They first show that if we have \( r \) hash functions (we need \( r > 1 \) see the discussion below), then
for each element \( x \in S \) we can single out a hash value \( (h_{i(x)}(x)) \) which does not collide with the chosen
hash values for the other elements. They prepare a table that stores the mapping from \( x \) to the chosen hash
function \( (i \mapsto i(x)) \) efficiently, and then look up a second table using the hash function indicated by the
first table. A bit-mask computed using another hash function is used to provide error resiliency. To find the
“chosen” hash value for each element requires a matching problem to be solved. For the matching problem
to have a solution we need at least two hash functions. Indeed, if we had only one hash function then the
Birthday paradox implies that there will be collisions among the elements (since the hash functions map the
set \( S \) of size \( n \) to a set of size \( \approx n \)). For the colliding elements we cannot select the “chosen” hash value.
Provided \( r > 1 \), they show that the matching problem can be solved in \( O(n \log n) \) time on average. The
space used is \( rc(q + k)n \) bits, where \( r \geq 2, c > 1 + \frac{1}{\sqrt{n}} \) and \( q = \log \frac{r}{\epsilon} \) (here \( \epsilon \) is the probability of an error
given \( x \in D \setminus S \)). Look up requires \( r + 1 \) hash function evaluations and \( r + 1 \) memory accesses (\( r \) accesses to
Table 1 and one access to Table 2 in the notation of [7]). Since \( r \geq 2 \), we need at least 3 memory accesses.
More importantly, their construction allows changes to the function value in the same time as a look up.

The method from §2 can be constructed in linear time on average which is faster than [7]. The space utilization is similar \( \approx (2 + \delta)n(\log \frac{1}{\delta} + k) \) (for any \( \delta > 0 \)). Changing the value of \( f(x) \) for \( x \in S \) is slower
taking \( O(\log n) \) time. Looking up a function value requires 3 hash evaluations and 2 memory accesses (which
is slightly faster than their scheme). The method from §3 is more efficient in the storage space than both

6 Comparison with earlier work

Our constructions in §2 and §3 and those of [7] are related in the broad sense that all approaches use hash
functions to generate equations that can be solved to construct a Bloomier filter. However, the details differ
markedly. Let \( S \subseteq D \) and \( f : S \to \{0,1\}^k \) be the function that we wish to store. The approach of [7] is
as follows: They first show that if we have \( r \) hash functions (we need \( r > 1 \) see the discussion below), then
for each element \( x \in S \) we can single out a hash value \( (h_{i(x)}(x)) \) which does not collide with the chosen
hash values for the other elements. They prepare a table that stores the mapping from \( x \) to the chosen hash
function \( (i \mapsto i(x)) \) efficiently, and then look up a second table using the hash function indicated by the
first table. A bit-mask computed using another hash function is used to provide error resiliency. To find the
“chosen” hash value for each element requires a matching problem to be solved. For the matching problem
to have a solution we need at least two hash functions. Indeed, if we had only one hash function then the
Birthday paradox implies that there will be collisions among the elements (since the hash functions map the
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Provided \( r > 1 \), they show that the matching problem can be solved in \( O(n \log n) \) time on average. The
space used is \( rc(q + k)n \) bits, where \( r \geq 2, c > 1 + \frac{1}{\sqrt{n}} \) and \( q = \log \frac{r}{\epsilon} \) (here \( \epsilon \) is the probability of an error
given \( x \in D \setminus S \)). Look up requires \( r + 1 \) hash function evaluations and \( r + 1 \) memory accesses (\( r \) accesses to
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taking \( O(\log n) \) time. Looking up a function value requires 3 hash evaluations and 2 memory accesses (which
is slightly faster than their scheme). The method from §3 is more efficient in the storage space than both

Fig. 1. Comparisons of the Bloomier Filters
methods. It requires only \((1 + \delta)n(\log \frac{1}{\delta} + k)\) space for any fixed \(\delta > 0\). Look up time is still \(O(1)\), but creation time is an exhorbitant \(O(n^3)\). The bucketing approach from §4 reduces this to \(n \log^{O(1)} n\). We believe it would be an interesting problem to construct Bloomier filters that require \(cn(\log \frac{1}{\delta} + k)\) bits of storage for \(c < 2\), while allowing a look up time of \(O(1)\) and a creation time of \(O(n)\).

Note: Some recent independent results of [11] are much closer to our approach. They use results of [6] to get a bound on the number sparse invertible matrices over the field \(\mathbb{F}_2\) and, consequently, encode the function.

7 Experimental Results

In this section we discuss the results of some experiments that we ran comparing our construction of Bloomier filters (from §2) and the scheme of [7]. The function we store is \(\text{InDeg}\) that maps a URL to the number of URLs that link to it. We obtained the in-link information for little over a billion URLs from the Live Search crawl data. We measured the creation time and memory usage for both the schemes for various numbers of URLs and averaged the results over 45 trials. The results are graphed in Figure 1. Figure 1a shows the time taken by both methods for creation of the Bloomier filter (we used \(c = 2.5\) and error probability = \(2^{-32}\) for both the schemes). Figure 1b displays the number of trials by the creation phase of each algorithm to find an appropriate graph (acyclic in our algorithm and lossless expander in theirs). As one can see from the results, the number of trials until a lossless expander is found is about the same as that of finding an acyclic graph. However, it takes comparatively longer to find a matching in the graph. Our scheme ends up being between 3 to 5 times faster for creation of the filter as a result (see 1c). Also, the memory footprint of the constructed Bloomier filter in both schemes is similar allowing the in-link information for \(\approx 1.1 \times 10^9\) URLs to fit in \(\approx 20GB\).

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A Circulant matrices over finite fields

Definition 1. Let $V$ be an $n$-dimensional vector space over a field $\mathbb{F}$ and let $w = (w_0, w_1, \ldots, w_{n-1}) \in V$. A circulant matrix associated to $w$ is the $n \times n$ matrix

$$
\begin{pmatrix}
w_0 & w_1 & \cdots & w_{n-2} & w_{n-1} \\
w_{n-1} & w_0 & \cdots & w_{n-3} & w_{n-2} \\
\vdots & \vdots & \ddots & \vdots & \vdots \\
w_2 & w_3 & \cdots & w_0 & w_1 \\
w_1 & w_2 & \cdots & w_{n-1} & w_0
\end{pmatrix}
$$

The following results are from [15], however, the proofs need some modification since we are dealing with vector spaces over finite fields.

First we need a closed form for the determinant of a circulant matrix.

Theorem 7. Let $p$ be a prime and $n$ a positive integer relatively prime to $n$. Let $w = (w_0, w_1, \ldots, w_{n-1})$ be a vector in $\mathbb{F}_p^n$ and let $W$ be the circulant matrix associated to $w$. Then

$$
\det W = \prod_{0 \leq \ell \leq n-1} \left( \sum_{0 \leq j \leq n-1} \epsilon^{\ell j} w_j \right),
$$

where $\epsilon$ is a primitive $n$-root of unity contained in the algebraic closure $\overline{\mathbb{F}}_p$.

Proof. One can view $W$ as a linear transformation acting on the vector space $\mathbb{F}_p^n$. An explicit calculation shows us that the vectors $x_\ell = (1, \epsilon^\ell, \epsilon^{2\ell}, \ldots, \epsilon^{(n-1)\ell})$, $0 \leq \ell \leq n-1$, are all eigenvectors with eigenvalues

$$
\lambda_\ell = w_0 + \epsilon^\ell w_1 + \cdots + \epsilon^{(n-1)\ell} w_{n-1}.
$$

Since $\{x_0, \ldots, x_{n-1}\}$ is a linearly independent set, we conclude that

$$
\det W = \prod_{0 \leq \ell \leq n-1} \lambda_\ell.
$$

It is not immediately apparent that the product is actually in $\mathbb{F}_p$. To show that one looks at the smallest field $\mathbb{F}_{p^r}$ that contains $\epsilon$. The Galois group of this field $\text{Gal}(\mathbb{F}_{p^r}/\mathbb{F}_p)$ is cyclic of order $r$, indeed, $r$ is the smallest integer such that $p^r \equiv 1 \mod n$. The Galois group is generated by the Frobenius map, $\text{Fr}$, that sends $x \mapsto x^p$. Under this map, $\epsilon \mapsto \epsilon^p = \epsilon^s$ where $s \equiv p \mod n$. Consequently, $\text{Fr}(\lambda_\ell) = \lambda_{s\ell}$ where $s\ell \equiv \ell' \mod n$. Since $\gcd(n, p) = 1$ the Frobenius just permutes the terms of the product $\prod_{0 \leq \ell \leq n-1} \lambda_\ell$. The product $\prod_{0 \leq \ell \leq n-1} \lambda_\ell = \det W$ is fixed by the Galois group and so it belongs to $\mathbb{F}_p$. \qed
Theorem 8. Let $p$, $q$ be primes such that $q$-th cyclotomic polynomial $f(x) = \sum_{0 \leq i < q} x^i$ is irreducible modulo $p$. Suppose $W$ is a circulant matrix associated to $w = (w_0, w_1, \cdots, w_{q-1})$ with entries in the finite field $\mathbb{F}_p$, then

$$\det W = \det \begin{bmatrix} w_0 & w_1 & \cdots & w_{q-2} & w_{q-1} \\ w_{q-1} & w_0 & \cdots & w_{q-3} & w_{q-2} \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ w_2 & w_3 & \cdots & w_0 & w_1 \\ w_1 & w_2 & \cdots & w_{q-1} & w_0 \end{bmatrix} = 0$$

if and only if either $\sum_{0 \leq i < q} w_i = 0$ or all the $w_i$ are equal.

Proof. We will make use of the notation introduced in the previous theorem here. If $\sum_i w_i = 0$ then $\lambda_0 = 0$ and so $\det W = 0$. Suppose all the $w_i$ are equal then for $\ell > 0$

$$\lambda_\ell = w_0 (1 + \ell^q + \cdots + \ell^{(q-1)})$$

$$= w_0 \left( \frac{\ell^q - 1}{\ell - 1} \right)$$

$$= 0, \text{ since } \ell^q = 1.$$ 

Assume that $\det W = 0$ and that $\lambda_0 \neq 0$. Then by the formula for the determinant $\lambda_\ell = 0$ for some $\ell < q$. By the formula for $\lambda_\ell$, $\ell^q$ is a root of the polynomial

$$p(x) = \sum_{0 \leq i < q} v_i x^i.$$ 

However, since $q$ is prime, $\ell^q$ is a primitive $q$-th root of unity, and the minimal polynomial for a primitive $q$-th over the rationals is the $q$-th cyclotomic polynomial $f(x) = \sum_{0 \leq i < q} x^i$. This is an irreducible polynomial modulo $p$ (by our assumption) and hence is also the minimal polynomial for $\ell^q$ over $\mathbb{F}_p$. Thus $p(x)$ is a constant multiple of $f(x)$ and thus all $w_i$ are equal. \qed

Theorem 9. Let $q$ be a prime and $f(x) = \sum_{0 \leq i < q} x^i$ be the $q$-th cyclotomic polynomial. Then $g(x)$ is irreducible modulo a prime $p$, iff $p \equiv g \mod q$ where $g$ is a generator of the cyclic group $\mathbb{F}_q^\ast$.

Proof. Let $K = \mathbb{F}_p$. Every root, $r$, of $f(x)$ over the algebraic closure $\overline{K}$, satisfies $r^q \equiv 1$. In other words, they are elements of multiplicative order $q$ in $\overline{K}$. The smallest extension $\mathbb{F}_{p^e}$, which contains elements of multiplicative order $q$ is the smallest such that $p^e \equiv 1 \mod q$. This is the order of $p$ in the multiplicative group $\mathbb{F}_q^\ast$. Suppose $p \equiv g \mod q$ then the smallest such $s$ is $q - 1$. The field $\mathbb{F}_{p^{s-1}}$ is the splitting field of the polynomial $f(x)$ and consequently, $f(x)$ is irreducible in $\mathbb{F}_p$. Now if the order of $p$ modulo $q$ is $< q - 1$. Then, there is an extension of $\mathbb{F}_p$, (say) $\mathbb{F}_{p^{s-1}}$, that contains a root $\alpha$ of $f(x)$. Now the polynomial $f'(x) = \prod_{\sigma \in \text{Gal}(\mathbb{F}_{p^{s-1}}/\mathbb{F}_p)} (x - \sigma(\alpha))$ is a factor of $f(x)$ which has coefficients in $\mathbb{F}_p$ of degree $e < q - 1$. Consequently, $f(x)$ is not irreducible over $\mathbb{F}_p$. \qed

A bit of algebraic number theory gives some more information: The polynomial $f(x)$ is irreducible modulo $p$ iff $p$ remains inert in the $q$-th cyclotomic field $\mathbb{Q}(\mu_q)$, where $\mu_q = \exp(2\pi i/q)$. This happens iff the Artin symbol at $p$ is a generator of the Galois group $\text{Gal}(\mathbb{Q}(\mu_q))$. By the Chebotarev density theorem this happens for a constant density of primes, indeed, the density is $\frac{2(q-1)}{q^2-1}$. 

13