Linear Intransitive Temporal Logic of Knowledge

$LTK_r$, Decision Algorithms, Inference Rules

Alexandra Lukyanchuk², Vladimir Rybakov¹

(1) School of Computing, Mathematics and DT, Manchester Metropolitan University,
    John Dalton Building, Chester Street, Manchester, M1 5GD, U.K.
(2) Institute of Mathematics and Information Technologies, Siberian Federal
    University, Krasnoyarsk, Russia

Abstract. Our paper investigates the linear logic of knowledge and time $LTK_r$, with reflexive intransitive time relation. The logic is defined semantically, – as the set of formulas true at special frames with intransitive and reflexive time binary relation. The $LTK_r$-frames are linear chains of clusters connected by a reflexive intransitive relation $R_T$. Elements inside a cluster are connected by several equivalence relations imitating the knowledge of different agents. We study the decidability problem for formulas and inference rules. Decidability for formulas follows from decidability w.r.t. admissible inference rules. To study admissibility, we introduce some special constructive Kripke models suitable to describe admissibility of inference rules. With a special technique of definable valuations we find an algorithm determining admissible inference rules in $LTK_r$. That is, we show that the logic $LTK_r$ is decidable and decidable with respect to admissibility of inference rules.

Keywords: Multi-modal logic, Temporal logic, Epistemic logic, Decision Algorithms, $n$-characterizing models, Admissible rules

1 Introduction

Interest to study of inference rules in non-standard epistemic logics appeared quite a while ago primarily from proof theory and its applications to computer sciences (CS). Research of artificial intelligence (AI) requires language adapted to description of various dynamic systems. The language of multi-modal logic, combining temporal and knowledge modalities, perfectly cope with this task (14, 17). Multi-modal logics generated by adjoining operators representing time and knowledge to the classical propositional calculus $CPC$ are very effective for modeling reasoning (in particular, where agents, who possess a certain knowledge, are operating in the processes of computation in a flow of time (14),
But initially, the facts and statements are described by formulas, and just formulas themselves are not always able to express the changing conditions and prerequisites in a very effective manner. We often want to know what will follow from given statements (assumptions), and for this we need to know what are correct logical consequence for given assumptions. So we can extend the language of logic by considering conditional statements of the form $A_1, \ldots, A_n / B$, which have the meaning if all $A_1, \ldots, A_n$ hold (are true), then $B$ also holds (is true).

We will study logical consequence in terms of admissible and valid inference rules. The notion of admissible inference rules was introduced by Lorenzen in 1955 ([20]). Admissible rules of a logic are those ones under which the set of theorems of this logic is closed. It was observed, that we can expand an axiomatic system by adding admissible, though not derivable, inference rules e.g. for Heyting intuitionistic logic $IPC$ ([19]). Hence the question of finding algorithm to determine admissible rules in non-classical logics was set up. Originally H. Friedman addressed this question to the intuitionistic logic $IPC$ ([18]) itself. This problem has been solved by V. Rybakov ([16][15]). Then the admissibility question was studied for many other non-standard logics ([13][9][8]).

S. Ghilardi has found algorithm recognizing admissibility using the concept of unification([12]). Later Vladimir Rybakov investigated the unification problem and its connection with the of decidability w.r.t inference rules in class of many popular logics ([1][2][3][6][7]).

In this paper, we extend the investigation of this area to a linear temporal multi-modal logic $LT K_r$ with linear intransitive and reflexive time and agent’s knowledge studied in [4][5]. We consider the time as a linear and discrete sequence of states. Each state consists of a set of information points connected by modal relations $R_i$. In other words, $R_i$ says which information points are effectively available for the agent $i$: it species the piece of information that the agent may access at given moment. Agents operating synchronously and each agent knows what time it is and distinguishes present state from the next one. The prime question we are dealing with in this article is the decidability of $LT K_r$. We reduce the decidability problem for $LT K_r$ to validness verification for inference rules $r$ in reduced normal form in special Kripke models, whose size is computable and bounded by the size of $r$. Hence, we prove that $LT K_r$ is decidable w.r.t. admissible inference rules and w.r.t. true formulas (theorems).

2 Necessary Preliminary Information

First we recall some necessary basic definitions, notation and known results used in this article.

The language $\mathcal{L}^{LT K}$ consists of a countable set of propositional letters $P := \{p_1, \ldots, p_n, \ldots\}$, the standard boolean operations and the set of modal operations $\{\Box_T, \Box_{\sim}, \Box_i (i \in I)\}$. Well formed formulae (wffs) are defined in the standard way, in particular, if $A$ is a wff, than $\Box_T A, \Box_{\sim} A, \Box_i A (i \in I)$ are wffs. We denote by $Fma(\mathcal{L}^{LT K})$ the set of all the wffs of $\mathcal{L}^{LT K}$ (in the sequel, in saying - formula we always refer to a formula from $Fma(\mathcal{L}^{LT K})$). The intended
meaning of the modal operations is: (a) □_TA means that the
formula A true in the current state and will be true in the next state. (b) □_¬A
means that A is known everywhere in the present time-cluster (i.e. A is part
of the environmental knowledge); (c) □_iA(i ∈ I) stands for the agent i (operating
in the system) knows A in the current state. Semantics for the language L^LTK
is based on a linear and discrete flow of time, associating a time point with
any natural number n.

An LT_K_r-frame is a multi-modal frame \( F = (W_F, R_T, R_\sim, R_1, \ldots, R_k) \),
where:
(a) \( W_F \) is the disjoint union of certain nonempty sets \( C_n \):
\[ W_F := \bigcup_{n \in J} C_n \]
where \( J = [0, L] \) and \( L \in \mathbb{N} \) or \( J = \mathbb{N} \).
(b) \( R_T \) is the linear, reflexive and intransitive relation on \( W_F \) such that:
\[ \forall w \forall z \in W_F (w R_T z \iff \exists n \in J ((w \in C_n) \& (z \in C_{n+1}))) \]
(c) \( R_\sim \) is a universal relation on any \( C_n \in W_F:
\forall w \forall z \in W_F (w R_\sim z \iff \exists n \in J ((w \in C_n) \& (z \in C_n))) \);
(d) \( \forall i \in I, R_i \) is some equivalence relation on \( C_n \).

Let LTK_r be the class of all LTK_r-frames.

Such frames simulate the situation in which agents, having a certain knowl-
edge background at a given moment, are operating in the linear flow of time.
Each time-cluster (i.e. an \( R_T \)-cluster) \( C_n \) consists of a set of information points
that are available at the moment \( n \). The relation \( R_T \) is the connection of such
information points by the flow of time. That is, given two information points \( w \) and \( z \), the expression \( w R_T z \) means either that \( w \) and \( z \) are both available at a
moment \( n \), or that \( z \) will be available in the moment \( n + 1 \) with respect to \( w \).
Since the relation \( R_\sim \) connects all the information-points available at the same
moment, it is intended to represent a sort of environmental knowledge, that is,
the whole information potentially available for the agent at a given time. The
relation \( R_i \) says which information points are effectively available for the agent
\( i \) at any given moment.

Moreover, relations on LTK_r-frame possess the following properties:
PM.1: \( v R_\sim z \implies (v R_T z \& z R_T v) \)
PM.2: \( v R_i z \implies v R_\sim z \)
PM.3: \( (v R_T z \& z R_T v) \implies v R_\sim z \).

In particular, the coincidence of the \( R_T \)- and \( R_\sim \)-clusters of the linear chain
is assumed [15].

Given a model \( M = (\mathcal{F}, V) \), where \( \mathcal{F} \) is an LTK_r-frame, the valuation \( V \)
can be extended in the standard way from the set \( P \) of propositional letters to
all well formed formulae constructed from \( P \).

**Definition 1.** Computational rules for logical operations:
Logic $LTK_r$ is the set of all $LTK_r$–valid formulae:

$$LTK_r := \{ A \in Fma(L^{LTK_r}) | \forall F \in LTK_r (F \models A) \}.$$  

If $A$ belongs to $LTK_r$, then $A$ is said to be a theorem of $LTK_r$.

**Definition 2.** Time degree $td(A)$ of a formula $A$ is defined as follows: $td(p) = td(T) = td(\bot) = 0$; $td(\neg \alpha) = td(\alpha)$; $td(\alpha \lor \beta) = td(\alpha \land \beta) = max(td(\alpha), td(\beta))$; $td(\Box \alpha) = td(\alpha)$; $td(\Box_{\omega} \alpha) = td(\alpha) + 1$.

**Definition 3.** Given a logic $L$, a model $Ch_L(n) := \langle Ch(n), V \rangle$ is said to be an $n$-characterizing model for $L$ iff: (a) $Dom(V) := \{ p_1, \ldots, p_n \}$ (b) for any formula $A$ built up from $Dom(V), Ch(n) \models A$.

**Definition 4.** Given a model $\langle Ch(n), V \rangle$, a world $w \in W_{Ch(n)}$ is definable iff there is a formula $\beta(w)$ such that $\forall z \in Ch(n)(Ch(n), z) \models \beta(w) \iff w = z$.

A consecution (an inference rule) $r$ is an expression

$$r := \varphi_1(x_1, \ldots, x_m), \ldots, \varphi_n(x_1, \ldots, x_m) / \phi(x_1, \ldots, x_m),$$

where $\varphi_1(x_1, \ldots, x_m), \ldots, \varphi_n(x_1, \ldots, x_m)$ and $\phi(x_1, \ldots, x_m)$ are wff build up from the letters $x_1, \ldots, x_m$. Expression $Pr(r)$ is an abbreviation for the premises of $r$, and $Con(r)$ for the conclusion of $r$.

An inference rule $r := \varphi_1(x_1, \ldots, x_m), \ldots, \varphi_n(x_1, \ldots, x_m) / \phi(x_1, \ldots, x_m)$ is admissible for a logic $L$ ($r \in Ad(L)$) iff for each substitution $\Sigma$, if $\Sigma(\varphi_i) \in L$ for each $i$, then $\Sigma(\phi) \in L$.

A rule $r$ is in the reduced normal form if $r := r_{\epsilon_f}/x_0$, where

$$\epsilon_f := \bigvee_{1 \leq j \leq s} \theta_j; \theta_j := \bigwedge_{1 \leq i \leq m} [x_i]^{d(j, i, 1)} \land (\Diamond x_i)^{d(j, i, 2)} \land (\Box_{\omega} x_i)^{d(j, i, 3)} \land \bigwedge_{1 \leq i \leq k} (\Diamond x_i)^{d(j, i, 4)}],$$

$d(j, i, z), d(j, i, l, z) \in \{ 0, 1 \}$ and for any formula $\alpha$ above, $\alpha^0 := \alpha, \alpha^1 := \neg \alpha$.

Given a rule $r_{nf}$ in the reduced normal form, $r_{nf}$ is said to be a normal reduced form for a rule $r$ iff, for any frame $F$, $F \models r \iff F \models r_{nf}$.

Using Corollary 3.1.13 and Corollary 3.1.15 from [13], we obtain:

**Theorem 1.** There exist an algorithm running in (single) exponential time, which, for any given rule $r$ in the language of logic $LTK_r$, constructs its normal reduced form $r_{nf}$. Moreover, $r$ is semantically equivalent to $r_{nf}$ in $LTK_r$. 

\[ \forall p \in P (\langle F, w \rangle \models \neg p \iff w \not\in P(p)); \]

\[ (\langle F, w \rangle \models \neg (\Box_T A) \iff \forall z \in W_F(wR_T z) \Rightarrow (\langle F, z \rangle \models A); \]

\[ (\langle F, w \rangle \models \neg (\Box_\omega A) \iff \forall z \in W_F(wR_\omega z) \Rightarrow (\langle F, z \rangle \models A); \]

\[ \forall i \in I, (\langle F, w \rangle \models \neg (\Box_i A) \iff \forall z \in W_F(wR_i z) \Rightarrow (\langle F, z \rangle \models A). \]
3 Construction of $Ch_{LTK_r}(n)$

In this section we will construct special $n$-characterizing models for the logic $LT K_r$ in case of intransitive time relation. This construction based on the techniques presented by V.V. Rybakov in [13].

Step 1.

Let $F$ be a set of finite $LT K_r$-frames such that, for any frame $F \in F, \forall w \forall z \in W_F (wR_T z \& zR_T w)$. Let $C(F)_n$ be a set of all different, non-isomorphic models $C := \langle F, V \rangle$, where

1. $F \in F$;
2. $\text{Dom}(V) = \{p_1, \ldots, p_n\}$;

Let $S_1(Ch_{LTK_r}(n)) := \bigcup_{C(F)} C_n$, the first slice of $Ch_{LTK_r}(n)$ contains a finite number of $R_T$-clusters with valuation of variables $p_1, \ldots, p_n$ s.t. $\forall C_i, C_j \in C(F), C_i$ is not isomorphic to $C_j$.

Step 2.

To each $C$ from $S_1(Ch_{LTK_r}(n))$ we adjoin non-isomorphic to $C$ models $C_j$ from $C(F)_n$ assuming $C_j$ to be immediate $R_T$-predecessor of $C$. The resulting model is defined as $S_{\leq 2}(Ch_{LTK_r}(n))$.

Step 3.

To each $C$ from $S_2(Ch_{LTK_r}(n))$ we adjoin all models $C_j$ from $C(F)_n$ as immediate $R_T$-predecessor of $C$. The resulting model is defined as $S_{\leq 3}(Ch_{LTK_r}(n))$.

Step 4.

Suppose, we have already constructed the model $S_{\leq i}(Ch_{LTK_r}(n))$ for $i \geq 2$ such that its frame is is an $LT K_r$-frame.

To construct $S_{\leq i+1}(Ch_{LTK_r}(n))$ we add all models from $C(F)_n$ to each $R_T$-cluster from $S_i(Ch_{LTK_r}(n))$ as its immediate $R_T$-predecessors.

The resulting models of such extension is the model

$$Ch_{LTK}(n) := (W_{Ch_{LTK_r}}, R_T, R_\sim, R_1, \ldots, R_k, V) := \bigcup_{i \in N} S_{\leq i}(Ch_{LTK_r}(n))$$

We will denote the base set of $Ch_{LTK}(n)$ as $Ch(n)$.

Lemma 1. The model $Ch_{LTK_r}(n) = \langle Ch(n), V \rangle$ is $n$-characterizing for $LT K_r$.

Lemma 2. For any $n$-characterizing model $Ch_{LTK_r}(n)$, each world $w$ from $W_{Ch(n)}$ is not definable.
4 Decidability with respect to admissible inference rules

First we introduce a special kind of $LTK_r$-frames, which plays a leading role in the description of the main result.

Let $F_P$, $F_S$, and $F_i$ be $LTK_r$-frames with the following structures:

(a) The frame $F_P = \langle W_{F_P}, R_T^P, R_S^P, R_{i1}, \ldots, R_{ik} \rangle$ is an $LTK_r$-frame such that its base set $W_{F_P}$ consists only one world denoted by $\emptyset$, $W_{F_P} := \{ \emptyset \}$.

(b) Let $F_S = \langle W_{F_S}, R_T^S, R_S^S, R_{i1}, \ldots, R_{ik} \rangle$ be a finite $LTK_r$-frame, where $W_{F_S} = \{ \bigcup_{i=0}^d C_i \}$ and $C_0 R_T C_1 R_T \ldots R_T C_d$.

(c) The frame $F_i = \langle W_{F_i}, R_T^i, R_S^i, R_{i1}, \ldots, R_{ik} \rangle$ is a finite $LTK_r$-frame, and each $R_T^i$-cluster of $F_i$ consists of only one world. Namely, $W_{F_i} = \{ w_1^i, \ldots, w_{j_i}^i \}$, and $w_1^i R_T w_2^i R_T \ldots R_T w_{j_i}^i$.

Definition 5. An $SP$-frame is a tuple $F_{SP} = \langle W_{SP}, R_T, R_\omega, R_1, \ldots, R_k \rangle$ where

1) $W_{SP} = W_{F_P} \cup W_{F_S} \cup \bigcup_{i=0}^d W_{F_i}$;

2) $R_T = R_T^P \cup R_T^S \cup \bigcup_{i=0}^d R_T^i \cup \{ (z, \emptyset) \mid z \in C_d \} \cup \bigcup_{i=0}^d \{ (w_j^i, z) \mid w_j^i \}$ is $R_T$-maximal world of $F_i$, $z \in C_i \subseteq F_S$;

3) $R_\omega = R_S^P \cup R_S^S \cup \bigcup_{i=0}^d R_s^i$;

4) $R_j = R_T^P \cup R_T^S \cup \bigcup_{i=0}^d R_j^i$ (1 ≤ $j$ ≤ $k$).

Theorem 2. An inference rule $r_{nf}$ in the reduced normal form is not admissible in $LTK_r$ if and only if there is a finite $SP$-frame $F_{SP}$, whose size is computable in the size of $r_{nf}$, and a valuation $V$ for variables from $r_{nf}$ in $F_{SP}$, such that

1) $F_{SP} \not \models V \text{ Con}(r_{nf})$;

2) $F_{SP} \models V \text{ Pr}(r_{nf})$;

3) There is $\theta_a \in \text{ Pr}(r_{nf})$, where

$$(F_{SP}, w_1^i) \models V \theta_a, (F_{SP}, w_2^i) \models V \theta_a, (F_{SP}, \emptyset) \models V \theta_a,$$

for (0 ≤ $i$ ≤ $d$);

4) for $z, w \in C_d \ (z \neq w) : (F_{SP}, z) \models V \theta_h, (F_{SP}, w) \models V \theta_m$ and $\theta_h \neq \theta_m$;

5) $R_T$-cluster $C_d$ is not isomorphic to the world $\emptyset$.

Based on this result we immediately derive

Theorem 3. The logic $LTK_r$ is decidable w.r.t. admissible rules (and consequently w.r.t. theorems).
References

1. Rybakov V. Projective formulas and unification in linear temporal logic LTLU, Logic Journal of IGPL, jzu005 (2014).
2. Rybakov V., Odintsov S. Unification and admissible rules for paraconsistent minimal Johansson’s logic J and positive intuitionistic logic IPC+, Annals of Pure and Applied Logic 164 (7) (2013), 771-784.
3. Rybakov V. Writing out unifiers for formulas with coefficients in intuitionistic logic, Logic Journal of IGPL 21 (2) (2013), 187-198.
4. Lukyanukh A., Rimatskii V. An axiomatization for the linear logic of knowledge and time LTKr with intransitive time relation, Siberian Mathematical Journal, 54 (6) (2013), 1038-1046.
5. Lukyanukh A. Decidability of multi-modal logic LTK of linear time and knowledge, Journal of Siberian Federal University, 6 (2) (2013), 220-226.
6. Rybakov V. Unifiers in transitive modal logics for formulas with coefficients (meta-variables), Logic Journal of IGPL, jzs038 (2012).
7. Rybakov V. Multi-Agent Logic based on Temporal Logic TS4K, serving Web Search, KES (2012), 108-117.
8. Calardo E. Admissible inference rules in the linear logic of knowledge and time LTK, Logic Journal of the IGPL, 14(1) (2006), 1534.
9. Golovanov M., A.V. Kosheleva A., Rybakov V. Logic of Visibility, Perception, and Knowledge and Admissible Inference Rules, Logic Journal of the IGPL, 13(2) (2005), 201-209.
10. Halpern J.Y., Van Der Meyden R., Vardi M.Y. Complete Axiomatization for Reasoning About Knowledge and Time, SIAM Journal on Computing 33(3) (2004), 674-703.
11. Gabbay D., Kurucz A., Wolter F., Zakharyaschev M. Many-Dimensional Modal Logics: Theory and Applications, Studies in Logic and the Foundations of Mathematics, Vol. 148. Elsevier, North-Holland, New York - Amsterdam, (2003).
12. Ghilardi S. Unification in intuitionistic logic, Journal of Symbolic Logic, 64 (1999), 859-880.
13. Rybakov V. Admissible Logical Inference Rules, volume 136 of Studies in Logic and the Foundations of Mathematics. Elsevier, North-Holland, New York - Amsterdam, (1997).
14. Fagin R., Halpern J.Y., Moses Y., Vardi M.Y. Reasoning About Knowledge, MIT Press, Cambridge, Massachusetts, (1995).
15. Rybakov V. Bases of admissible rules of the logics $S4$ and $Int$, Algebra and Logic, 24(1) (1985), 5568.
16. Rybakov V. A criterion for admissibility of rules in the modal system $S4$ and the intuitionistic logic, Algebra and Logic, 23(5) (1984), 369384.
17. Thomason R.H. Combination of tense and modality In D. Gabbay and F.Guenther (Eds). Handbook of Philosophical Logic, Vol. II, pp. 135-165. Reidel Dordrecht, The Netherlands, (1984).
18. Friedman H. One hundred and two problems in mathematical logic, Journal of Symbolic Logic, 40(3) (1975), 113 - 130.
19. Harrop R. Concerning Formulas of the Types $A \rightarrow B \lor C$, $A \rightarrow \exists x B(x)$, Journal of Symbolic Logic, 25(1) (1960), 27-32.
20. Lorenzen P. Einfung in Operative Logik und Mathematik, Berlin - Gottingen - Heidelberg, (1955).