The Load and Availability of Byzantine Quorum Systems*

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Abstract

Replicated services accessed via quorums enable each access to be performed at only a subset (quorum) of the servers, and achieve consistency across accesses by requiring any two quorums to intersect. Recently, $b$-masking quorum systems, whose intersections contain at least $2b+1$ servers, have been proposed to construct replicated services tolerant of $b$ arbitrary (Byzantine) server failures. In this paper we consider a hybrid fault model allowing benign failures in addition to the Byzantine ones. We present four novel constructions for $b$-masking quorum systems in this model, each of which has optimal load (the probability of access of the busiest server) or optimal availability (probability of some quorum surviving failures). To show optimality we also prove lower bounds on the load and availability of any $b$-masking quorum system in this model.

1 Introduction

Quorum systems are well known tools for increasing the efficiency of replicated services, as well as their availability when servers may fail benignly. A quorum system is a set of subsets (quorums) of servers, every pair of which intersect. Quorum systems enable each client operation to be performed only at a quorum of the servers, while the intersection property makes it possible to preserve consistency among operations at the service.

Quorum systems work well for environments where servers may fail benignly. However, when servers may suffer arbitrary (Byzantine) failures, the intersection property does not suffice for maintaining consistency; two quorums may intersect in a subset containing faulty servers only, who may deviate arbitrarily and undetectably from their assigned protocol. Malkhi and Reiter thus introduced masking quorum systems [MR98a], in which each pair of quorums intersects in sufficiently many servers to mask out the behavior of faulty servers. More precisely, a $b$-masking

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**quorum system** is one in which any two quorums intersect in \(2b + 1\) servers, which suffices to ensure consistency in the system if at most \(b\) servers suffer Byzantine failures.

In this paper we develop four new constructions for \(b\)-masking quorum systems. For the first time in this context, we distinguish between masking Byzantine faults and surviving a possibly larger number of benign faults. Our systems remain available in the face of any \(f\) crashes, where \(f\) may be significantly larger than \(b\) (such a system is called \(f\)-resilient). In addition, our constructions demonstrate optimality (ignoring constants) in two widely accepted measures of quorum systems, namely **load** and **crash probability**. The load \((L)\), a measure of best-case performance of the quorum system, is the probability with which the busiest server is accessed under the best possible strategy for accessing quorums. The crash probability \((F_p)\) is the probability, assuming that each server crashes with independent probability \(p\), that all quorums in the system will contain at least one crashed server (and thus will be unavailable). The crash probability is an even more refined measure of availability than \(f\), as a good system will tolerate many failure configurations with more than \(f\) crashes. Three of our systems are the first systems to demonstrate optimal load for \(b\)-masking quorum systems, and two of our systems each demonstrate optimal crash probability for its resilience \(f\). In proving optimality of our constructions, we prove new lower bounds for the load and crash probability of masking quorum systems.

The techniques for achieving our constructions are of interest in themselves. Two of the constructions are achieved using a **boosting** technique, which can transform any regular (i.e., benign fault-tolerant) quorum system into a masking quorum system of an appropriately larger system. Thus, it makes all known quorum constructions available for Byzantine environments (of appropriate sizes). In the analysis of one of our best systems we employ strong results from percolation theory.

The rest of this paper is structured as follows. We review related work and preliminary definitions in Sections 2 and 3, respectively. In Section 4 we prove bounds on the load and crash probability for \(b\)-masking quorum systems and introduce quorum composition. In Sections 5–7 we describe our new constructions. We discuss our results in Section 8.

### 2 Related work

Our work borrows from extensive prior work in benignly fault-tolerant quorum systems (e.g., [Gif73, Tho74, Mae85, GB85, Her86, BG87, ET89, AE91, CAA92, NW98, PW97b]). The notion of availability we use here (crash probability) is well known in reliability theory [BP73] and has been applied extensively in the analysis of quorum systems (cf. [BG87, PW93, PW97a] and the references therein). The load of a quorum system was first defined and analyzed in [NW98], which proved a lower bound of \(\Omega(\frac{1}{\sqrt{n}})\) on the load of any quorum system (and, a fortiori, any masking quorum system) over \(n\) servers. In proving load-optimality of our constructions, we generalize this lower bound to \(\Omega(\sqrt{\frac{b}{n}})\) for \(b\)-masking quorum systems.
Grids, which form the basis for our M-Grid construction, were proposed in [Mae85, CAA92, KRS93, MR98a]. The technique of quorum composition, which we use in our RT and boostFPP constructions, has been studied in [MP92, NM92, Nei92] under various names such as “coterie join” and “recursive majority”. Our M-Path construction generalizes the system of [WB92], coupled with the analysis of the Paths construction of [NW98], and the recent system of [Baz96].

Several constructions of masking quorum systems were given in [MR98a] for a variety of failure models. For the model we consider here—i.e., any \( b \) servers may experience Byzantine failures—that work gave two constructions. We compare those constructions to ours in Section 8.

Hybrid failure models have been considered in other works (e.g., [GP92, LR93, LR94, RB94]).

3 Preliminaries

In this section we introduce notation and definitions used in the remainder of the paper. Much of the notation introduced in this section is summarized in Table 1 for quick reference.

We assume a universe \( U \) of servers, \( |U| = n \), over which our quorum systems will be constructed. Servers that obey their specifications are correct. A faulty server, however, may deviate from its specification arbitrarily. We assume that up to \( b \) servers may fail arbitrarily and that \( 4b < n \), since this is necessary for a \( b \)-masking quorum system to exist [MR98a]. Beginning in Section 3.2.2, we will also distinguish benign (crash) failures as a particular failure of interest, and in general there may be more than \( b \) such failures.

3.1 Quorum systems

**Definition 3.1** A quorum system \( Q \subseteq 2^U \) is a collection of subsets of \( U \), each pair of which intersect. Each \( Q \in Q \) is called a quorum.
We use the following notation. The cardinality of the smallest quorum in \( Q \) is denoted by \( c(Q) = \min\{|Q| : Q \in Q\} \). The size of the smallest intersection between any two quorums is denoted by \( IS(Q) = \min\{|Q \cap R| : Q, R \in Q\} \). The degree of an element \( i \in U \) in a quorum system \( Q \) is the number of quorums that contain \( i \): \( \deg(i) = |\{Q : i \in Q\}| \).

**Definition 3.2** A quorum system \( Q \) is \((s,d)\)-fair if \( |Q| = s \) for all \( Q \in Q \) and \( \deg(i) = d \) for all \( i \in U \). \( Q \) is called fair if it is \((s,d)\)-fair for some \( s \) and \( d \).

**Definition 3.3** A set \( T \) is a transversal of a quorum system \( Q \) if \( T \cap Q \neq \emptyset \) for every \( Q \in Q \). The cardinality of the smallest transversal is denoted by \( MT(Q) = \min\{|T| : T \text{ is a transversal of } Q\} \).

Regular quorum systems, with \( IS(Q) = 1 \), are insufficient to guarantee consistency in case of Byzantine failures. Malkhi and Reiter [MR98a] defined several varieties of quorum systems for Byzantine environments, which are suitable for different types of services. In this paper we focus on masking quorum systems.

**Definition 3.4** [MR98a] The resilience \( f \) of a quorum system \( Q \) is the largest \( k \) such that for every set \( K \subseteq U \), \( |K| = k \), there exists \( Q \in Q \) such that \( K \cap Q = \emptyset \).

**Remark:** The resilience of any quorum system \( Q \) is \( f = MT(Q) - 1 \).

**Definition 3.5** [MR98a] A quorum system \( Q \) is a \( b \)-masking quorum system if it is resilient to \( f \geq b \) failures, and obeys the following consistency requirement:

\[
\forall Q_1, Q_2 \in Q : |Q_1 \cap Q_2| \geq 2b + 1.
\]

**Remark:** Informally, if we view the service as a shared variable which is updated and read by the clients, then the resilience requirement of Definition 3.4 ensures that no set of \( b \leq f \) faulty servers will be able to block update operations (e.g., by causing every update transaction to abort). The consistency requirement of Definition 3.5 ensures that read operations can mask out any faulty behavior of up to \( b \) servers. Examples of protocols implementing various data abstractions using \( b \)-masking quorum systems can be found in [MR98a, MR98b, MR98c].

**Lemma 3.6** Let \( Q \) be a quorum system. Then \( Q \) is \( b \)-masking if both the following conditions hold:

1. \( MT(Q) \geq b + 1 \),
2. \( IS(Q) \geq 2b + 1 \).

**Proof:** Assume that \( MT(Q) \geq b + 1 \). To see that \( Q \) is resilient to \( b \) failures, note that if there exists some \( K \) such that \( K \cap Q \neq \emptyset \) for all \( Q \in Q \), then \( K \) is a transversal. By the minimality we have \( |K| \geq b + 1 \), and we are done. Condition 2 immediately implies (1). \( \square \)

**Corollary 3.7** Let \( Q \) be a quorum system, and let \( b = \min\{MT(Q) - 1, \frac{IS(Q) - 1}{2}\} \). Then \( Q \) is \( b \)-masking.  \( \square \)
3.2 Measures

The goal of using quorum systems is to increase the availability of replicated services and decrease their access costs. A natural question is how well any particular quorum system achieves these goals, and moreover, how well it compares with other quorum systems. Several measures will be of interest to us.

3.2.1 Load

A measure of the inherent performance of a quorum system is its load. Naor and Wool define the load of a quorum system as the frequency of accessing the busiest server using the best possible strategy [NW98]. More precisely, given a quorum system $Q$, an access strategy $w$ is a probability distribution on the elements of $Q$; i.e., $\sum_{Q \in Q} w(Q) = 1$. The value $w(Q) \geq 0$ is the frequency of choosing quorum $Q$ when the service is accessed. The load is then defined as follows:

**Definition 3.8** Let a strategy $w$ be given for a quorum system $Q = \{Q_1, \ldots, Q_m\}$ over a universe $U$. For an element $u \in U$, the load induced by $w$ on $u$ is $l_w(u) = \sum_{Q_i \ni u} w(Q_i)$. The load induced by a strategy $w$ on a quorum system $Q$ is $L_w(Q) = \max_{u \in U} \{l_w(u)\}$. The system load on a quorum system $Q$ is $L(Q) = \min_w \{L_w(Q)\}$, where the minimum is taken over all strategies.

We reiterate that the load is a best case definition. The load of the quorum system will be achieved only if an optimal access strategy is used, and only in the case that no failures occur. A strength of this definition is that the load is a property of a quorum system, and not of the protocol using it. Examples of load calculations can be found in [Woo96]. As an aside, we note that not every quorum system can have a strategy that induces the same load on each server. In [HMP97] it is shown that for some quorum systems it is impossible to perfectly balance the load.

Recall that $c(Q)$ denotes the cardinality of the smallest quorum in $Q$. The following result will be useful to us in the sequel (recall Definition 3.2).

**Proposition 3.9** [NW98] Let $Q$ be a fair quorum system. Then $L(Q) = c(Q)/n$.

3.2.2 Availability

By definition a $b$-masking quorum system can mask up to $b$ arbitrary (Byzantine) failures. However, such a system may be resilient to more benign failures. By benign failures we mean any failures that render a server unresponsive, which we refer to as crashes to distinguish them from Byzantine failures.

The resilience $f$ of a quorum system provides one measure of how many crash failures a quorum system is guaranteed to survive, and indeed this measure has been used in the past to differentiate among quorum systems [BG86]. However, it is possible that an $f$-resilient quorum system, though vulnerable to a few failure configurations of $f + 1$ failures, can survive many
configurations of more than \( f \) failures. One way to measure this property of a quorum system is to assume that each server crashes independently with probability \( p \) and then to determine the probability \( F_p \) that some quorum survives with no faulty members. This is known as crash probability and is formally defined as follows:

**Definition 3.10** Assume that each server in the system crashes independently with probability \( p \). For every quorum \( Q \in Q \) let \( \mathcal{E}_Q \) be the event that \( Q \) is hit, i.e., at least one element \( i \in Q \) has crashed. Let \( \text{crash}(Q) \) be the event that all the quorums \( Q \in Q \) were hit, i.e., \( \text{crash}(Q) = \bigwedge_{Q \in Q} \mathcal{E}_Q \). Then the system crash probability is \( F_p(Q) = \Pr(\text{crash}(Q)) \).

We would like \( F_p \) to be as small as possible. A desirable asymptotic behavior of \( F_p \) is that \( F_p \to 0 \) when \( n \to \infty \) for all \( p < 1/2 \), and such an \( F_p \) is called Condorcet (after the Condorcet Jury Theorem [Con]).

### 4 Building blocks

In this section, we prove several theorems which will be our basic tools in the sequel. First we prove lower bounds on the load and availability of \( b \)-masking quorum systems, against which we measure all our new constructions. Then we prove the properties of a quorum composition technique, which we later use extensively.

#### 4.1 The load and availability of masking quorum systems

We begin by establishing a lower bound on the load of \( b \)-masking quorum systems, thus tightening the lower bound on general quorum systems [NW98] as presented in [MR98a].

**Theorem 4.1** Let \( Q \) be a \( b \)-masking quorum system. Then \( \mathcal{L}(Q) \geq \max \{ \frac{2b+1}{c(Q)}, \frac{c(Q)}{n} \} \).

**Proof:** Let \( w \) be any strategy for the quorum system \( Q \), and fix \( Q_1 \in Q \) such that \( |Q_1| = c(Q) \). Summing the loads induced by \( w \) on all the elements of \( Q_1 \), and using the fact that any two quorums have at least \( 2b+1 \) elements in common, we obtain:

\[
\sum_{u \in Q_1} l_w(u) = \sum_{u \in Q_1} \sum_{Q_i \ni u} w(Q_i) = \sum_{Q_i} \sum_{u \in (Q_1 \cap Q_i)} w(Q_i) \geq \sum_{Q_i} (2b+1) w(Q_i) = 2b+1.
\]

Therefore, there exists some element in \( Q_1 \) that suffers a load of at least \( \frac{2b+1}{|Q_1|} \).

Similarly, summing the total load induced by \( w \) on all of the elements of the universe, and using the minimality of \( c(Q) \), we get:

\[
\sum_{u \in U} l_w(u) = \sum_{u \in U} \sum_{Q_i \ni u} w(Q_i) = \sum_{Q_i} |Q_i| w(Q_i)
\]
$$\geq \sum_{Q_i} c(Q)w(Q_i) = c(Q).$$

Therefore, there exists some element in $U$ that suffers a load of at least $\frac{c(Q)}{n}$. \quad \Box

**Corollary 4.2** Let $Q$ be a $b$-masking quorum system. Then $L(Q) \geq \sqrt{\frac{2b+1}{n}}$, and equality holds if $c(Q) = \sqrt{(2b+1)n}$. \quad \Box

**Remark:** Corollary 4.2 shows that the threshold construction of [MR98a] in fact has optimal load when $b = \Omega(n)$. E.g., when $b \approx n/4$ the obtained load is $\approx 0.75$, but for such systems we can only hope for a constant load of $\approx 1/\sqrt{2} = 0.707$. However the load of the threshold construction is always $\geq 1/2$, which is far from optimal for smaller values of $b$.

On the other hand, the grid-based construction of [MR98a] does not have optimal load. It has quorums of size $O(b\sqrt{n})$ and load of roughly $2b/\sqrt{n}$. In the sequel we show systems which significantly improve this: some of our new constructions have quorums of size $O(\sqrt{bn})$ and optimal load.

Our next propositions show lower bounds on the crash probability $F_p$ in terms of $\mathcal{MT}(Q)$ and $b$.

**Proposition 4.3** Let $Q$ be a quorum system. Then $F_p(Q) \geq p^{\mathcal{MT}(Q)} = p^{b+1}$ for any $p \in [0, 1]$.

*Proof:* Consider a minimal transversal $T$ with $|T| = \mathcal{MT}(Q)$. If all the elements of $T$ crash then every quorum contains a crashed element, so $F_p(Q) \geq p^{\mathcal{MT}(Q)}$. \quad \Box

**Proposition 4.4** Let $Q$ be a $b$-masking quorum system. Then $F_p(Q) \geq p^{c(Q) - 2b}$ for any $p \in [0, 1]$.

*Proof:* Let $Q \in Q$ be a minimal quorum with $|Q| = c(Q)$, and consider $Z \subset Q$, $|Z| = 2b$. Since $Q$ is $b$-masking then $|R \cap Q| \geq 2b + 1$ for any $R \in Q$, and so $|(Q \setminus Z) \cap R| \geq 1$ and $Q \setminus Z$ is a transversal. Therefore $\mathcal{MT}(Q) \leq c(Q) - 2b$, which we plug into Proposition 4.3. \quad \Box

The next proposition is less general than Proposition 4.4, however it is applicable for most of our constructions and it gives a much tighter bound.

**Proposition 4.5** Let $Q$ be a $b$-masking quorum system such that $\mathcal{MT}(Q) \leq (\mathcal{IS}(Q) + 1)/2$. Then $F_p(Q) \geq p^{b+1}$ for any $p \in [0, 1]$.

*Proof:* If $\mathcal{MT}(Q) \leq (\mathcal{IS}(Q) + 1)/2$ then from Corollary 3.7 we have that $b+1 = \mathcal{MT}(Q)$, which again we plug into Proposition 4.3. \quad \Box

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1To avoid repetitive notation, we omit floor and ceiling brackets from expressions for integral quantities.
4.2 Quorum system composition

Quorum system composition is a well known technique for building new systems out of existing components. We compose a quorum system $S$ over another system $R$ by replacing each element of $S$ with a distinct copy of $R$. In other words, when element $i$ is used in a quorum $s \in S$ we replace it with a complete quorum from the $i$'th copy of $R$. Using the terminology of reliability theory, the system $S \circ R$ has a modular decomposition where each module is a copy of $R$. Formally:

**Definition 4.6** Let $S$ and $R$ be two quorum systems, over universes of sizes $n_S$ and $n_R$, respectively. Let $R_1, \ldots, R_n$ be $n_S$ copies of $R$ over disjoint universes. Then the composition of $S$ over $R$ is

$$S \circ R = \left\{ \bigcup R_i : S \in S, R_i \in R_i \text{ for all } i \in S \right\}.$$

The next theorem summarizes the properties of quorum composition.

**Theorem 4.7** Let $S$ and $R$ be two quorum systems, and let $Q = S \circ R$. Then

- The universe size is $n_Q = n_S n_R$.
- The minimal quorum size is $c(Q) = c(S)c(R)$.
- The minimal intersection size is $\mathcal{IS}(Q) = \mathcal{IS}(S)\mathcal{IS}(R)$.
- The minimal transversal size is $\mathcal{MT}(Q) = \mathcal{MT}(S)\mathcal{MT}(R)$.
- Denote the crash probability functions of $S$ and $R$ by $s(p) = F_p(S)$ and $r(p) = F_p(R)$. Then $F_p(Q) = s(r(p))$.
- The load is $L(Q) = L(S)L(R)$.

Proof: The behavior of the combinatorial parameters $n_Q$, $c(Q)$, $\mathcal{IS}(Q)$ and $\mathcal{MT}(Q)$ is obvious. The behavior of $F_p(Q)$ is standard in reliability theory (cf. [BP75]). As for the load, consider the following strategy: pick a quorum $S \in S$ using the optimal strategy for $S$. Then for each element $i \in S$, pick a quorum $R_i \in R_i$ using the optimal strategy for (the $i$'th copy of) $R$. Clearly this strategy induces a load of $L(S)L(R)$, and hence $L(Q) \leq L(S)L(R)$.

We now show the inequality in the opposite direction. Enumerate the elements of $Q$ by denoting the $j$'th element in $R_i$ by $u_{ij}$, let $Q(S) = \{ \bigcup R_i : R_i \in R_i \text{ for all } i \in S \}$ be the set of all quorums that are based on some $S \in S$, and let $w^Q$ be an access strategy on $Q$. Then $w^Q$ induces a strategy $w^S$ on $S$ defined by

$$w^S(S) = \sum_{Q \in Q(S)} w^Q(Q). \quad (2)$$
The load on an element \( i \in S \) (i.e., the frequency of accessing the quorum system \( R_i \)) is then
\[
l_w^S(i) = \sum_{S \ni i, S \in S} w^S(S).
\]
Similarly, \( w^Q \) induces a strategy on each copy \( R_i \) defined by
\[
w^{R_i}(R) = \left( \sum_{Q \supseteq R} w^Q(Q) \right) / l_w^S(i).
\]
(3)

This \( w^{R_i} \) is well defined when \( l_w^S(i) > 0 \). It is easy to verify that \( w^S \) and \( w^{R_i} \) are indeed strategies, i.e., that the probabilities add up to 1.

Claim 4.8 Let \( l_w^Q(u_{ij}) \) be the load induced by \( w^Q \) on an element \( u_{ij} \in R_i \), and let \( l_w^{R_i}(u_{ij}) \) be the load induced on it by \( w^{R_i} \). Then
\[
l_w^Q(u_{ij}) = l_w^S(i) \cdot l_w^{R_i}(u_{ij}).
\]

Proof of Claim: Using (2) and (3) we have that
\[
l_w^S(i) \cdot l_w^{R_i}(u_{ij}) = l_w^S(i) \sum_{R \ni u_{ij}} w^{R_i}(R) = l_w^S(i) \sum_{R \ni u_{ij}} \left( \sum_{Q \supseteq R} w^Q(Q) \right) / l_w^S(i)
\]
\[
= \sum_{R \ni u_{ij}} \sum_{Q \supseteq R} w^Q(Q) = \sum_{Q \supseteq u_{ij}} w^Q(Q) = l_w^Q(u_{ij}).
\]

To complete the proof of Theorem 4.7, assume that \( w^Q \) is an optimal strategy for \( Q \). Consider the copy \( R_i \) for which \( l_w^S(i) \) is maximal, i.e., \( L_w^S(S) = l_w^S(i) \), and let \( u_{ij} \) be the maximally-loaded element in this \( R_i \). Clearly \( l_w^S(i) > 0 \) so \( w^{R_i} \) is well defined for this \( i \). Note that we do not require \( u_{ij} \) to be the maximally-loaded element in all of \( Q \). Using the claim and the minimality of \( L(S) \) and \( L(R) \) we obtain that
\[
L(Q) = L_w^Q(Q) \geq l_w^Q(u_{ij}) = l_w^S(i) \cdot l_w^{R_i}(u_{ij})
\]
\[
= L_w^S(S) \cdot L_w^{R_i}(R) \geq L(S) L(R).
\]

By combining this inequality with the upper bound we had before we conclude that \( L(Q) = L(S) L(R) \).

The multiplicative behavior of the combinatorial parameters in composing quorum systems provides a powerful tool for “boosting” existing constructions into larger systems with possibly improved characteristics. Below, we use quorum composition in two cases, and demonstrate that this technique yields improved constructions over their basic building blocks, for appropriately larger system sizes. In particular, in Section 6 we show a composition that allows us to transform any regular quorum construction into a (larger) \( b \)-masking quorum system.

5 Simple systems

In this section we show two types of constructions, the multi-grid (denoted M-Grid) and the recursive threshold (RT). These systems significantly improve upon the original constructions of [MR98a], however both are still suboptimal in some parameter: M-Grid has optimal load but
can mask only up to $b = O(\sqrt{n})$ failures and has poor crash probability; and RT can mask up to $b = O(n)$ failures and has near optimal crash probability, but has suboptimal load.

In Sections 6 and 7 we present systems which are superior to the M-Grid and RT. Nonetheless, we feel that the simplicity of the M-Grid and RT systems, and the fact that they are suitable for very small universe sizes, are what makes them appealing.

5.1 The multi-grid system

We begin with the M-Grid system, which achieves an optimal load among $b$-masking quorum systems, where $b \leq (\sqrt{n} - 1)/2$. The idea of the construction is as follows. Arrange the elements in a $\sqrt{n} \times \sqrt{n}$ grid. A quorum in a multi-grid consists of any choice of $\sqrt{b} + 1$ rows and $\sqrt{b} + 1$ columns, as shown in Figure 1. Formally, denote the rows and columns of the grid by $R_i$ and $C_i$, respectively, where $1 \leq i \leq \sqrt{n}$. Then, the quorum system is

$\text{M-Grid}(b) = \left\{ \bigcup_{j \in J} C_j \cup \bigcup_{i \in I} R_i : J, I \subseteq \{1, \ldots, \sqrt{n}\}, |J| = |I| = \sqrt{b + 1} \right\}.$

**Proposition 5.1** The multi-grid M-Grid($b$) is a $b$-masking quorum system for $b \leq (\sqrt{n} - 1)/2$.

**Proof:** Consider two quorums $R, S \in \text{M-Grid}(b)$. If they have either a row or a column in common, then $|R \cap S| \geq \sqrt{n} \geq 2b + 1$ and we are done. Otherwise the intersection of $S$’s columns with $R$’s rows is disjoint from the intersection of $R$’s columns with $S$’s rows, so $|R \cap S| \geq 2\sqrt{b + 1} \sqrt{b + 1} > 2b + 1$. Therefore consistency holds.

Resilience holds since $f = M\mathcal{T}(\text{M-Grid}(b)) - 1 = \sqrt{n} - \sqrt{b + 1} \geq b$. Therefore $M\mathcal{T}(\text{M-Grid}(b)) \geq b + 1$, and Lemma 3.6 finishes the proof. \qed

**Proposition 5.2** $\mathcal{L}(\text{M-Grid}(b)) \approx 2\sqrt{\frac{b+1}{n}}$. 
Figure 2: An RT(4, 3) system of depth \( h = 2 \), with one quorum shaded.

**Proof:** Since M-Grid(\( b \)) is fair we can use Proposition 3.9 to get \( \mathcal{L}(\text{M-Grid}(b)) = c(\text{M-Grid}(b))/n \).

\( \square \)

**Remark:** The load of M-Grid(\( b \)) is within a factor of \( \sqrt{2} \) from the optimal load which can be achieved for \( b \approx \sqrt{n}/2 \).

A disadvantage of the M-Grid system is its poor asymptotic crash probability. If crashes occur with some constant probability \( p \) then any configuration of crashes with at least one crash per row disables the system. Therefore, as shown by [KC91, Woo96],

\[
F_p(\text{M-Grid}) \geq (1 - (1 - p)\sqrt{n})\sqrt{n} \rightarrow 1. \quad n \to \infty
\]

### 5.2 Recursive threshold systems

A recursive threshold system RT(\( k, \ell \)) of depth \( h \) is built by taking a simple building block, which is an \( \ell \)-of-\( k \) threshold system (with \( k > \ell > k/2 \)), and recursively composing it over itself to depth \( h \). In the sequel, we often omit the depth parameter \( h \) when it has no effect on the discussion. The RT systems generalize the recursive majority constructions of [MP92], the HQS system of [Kum91] is an RT(3, 2) system, and in fact the threshold system of [MR98a] can be viewed as a trivial RT(4\( b + 1, 3b + 1 \)) system with depth \( h = 1 \). As an example throughout this section we will use the RT(4, 3) system, depicted in Figure 2.

**Proposition 5.3** An RT(\( k, \ell \)) system of depth \( h \) is a fair quorum system, with \( n = k^h \) elements, quorums of size \( c(\text{RT}(k, \ell)) = \ell^h \), intersection size of \( \mathcal{I}\mathcal{S}(\text{RT}(k, \ell)) = (2\ell - k)^h \), and minimal transversals of size \( \mathcal{M}\mathcal{T}(\text{RT}(k, \ell)) = (k - \ell + 1)^h \).

**Proof:** The basic \( \ell \)-of-\( k \) system is symmetric (and therefore fair), with \( c(\ell\text{-of-}k) = \ell \), \( \mathcal{M}\mathcal{T}(\ell\text{-of-}k) = k - \ell + 1 \), and \( \mathcal{I}\mathcal{S}(\ell\text{-of-}k) = 2\ell - k \). The combinatorial parameters are computed by activating Theorem 4.7 \( h \) times, and the composition preserves the fairness. \( \square \)

Plugging this into Corollary 3.7 we obtain

**Corollary 5.4** An RT(\( k, \ell \)) system over a universe of size \( n \) is a \( b \)-masking quorum system for

\[
b = \min\{\lfloor n^{\log_k(2\ell-k)} - 1 \rfloor/2, n^{\log_k(k-\ell+1)} - 1 \}. \quad \square
\]
In the 3-of-4 example we have $IS(3\text{-of-}4) = MT(3\text{-of-}4) = 2$ and $c(3\text{-of-}4) = 3$. Therefore for the whole system (to depth $\log_4 n$) we get $c(RT(4,3)) = n^{0.79}$, with $IS(RT(4,3)) = MT(RT(4,3)) = \sqrt{n}$ and thus $b = (\sqrt{n} - 1)/2$. Note that the basic 3-of-4 system is not even 1-masking since intersections of size 2 are too small, however already from $h = 2$ (i.e., $n = 16$) we obtain a masking system.

**Proposition 5.5** The load $L(RT(k,\ell)) = n^{-(1-\log_k \ell)}$.

**Proof:** Since $RT(k,\ell)$ is fair we can use Proposition 3.9 to get $L(RT(k,\ell)) = c(RT(k,\ell))/n$. □

**Remark:** In general the load is suboptimal for this construction. For instance, in the $RT(4,3)$ system we obtain $L(RT(4,3)) = n^{-0.21}$. However for $b = (\sqrt{n} - 1)/2$ we could hope for a load of $\sqrt{2b + 1}/n = n^{-0.25}$.

**Proposition 5.6** There exists a unique critical probability $0 < p_c < 1/2$ for which

$$
\lim_{h \to \infty} F_p(RT(k,\ell)) \text{ of depth } h = \begin{cases} 
0, & p < p_c, \\
1, & p > p_c.
\end{cases}
$$

**Proof:** Let $g(p)$ be the crash probability function of the $\ell$-of-$k$ system and let $F(h) = F_p(RT(k,\ell))$ of depth $h$ denote the crash probability for the $RT(k,\ell)$ system of depth $h$. Then $F(h)$ obeys the recurrence

$$
F(h) = \begin{cases} 
g(F(h-1)), & h \geq 1, \\
p, & h = 0.
\end{cases}
$$

(4)

Now $g(p)$ is a reliability function, and therefore it is “S-shaped” (see [BP75]). This implies that there exists a unique critical probability $0 < p_c < 1$ for which $g(p_c) = p_c$, such that $g(p) < p$ when $p < p_c$ and $g(p) > p$ when $p > p_c$ (and [PW95] shows that for quorum systems such as RT in fact $p_c < 1/2$). Therefore if $p < p_c$ then repeated applications of recurrence (4) would decrease $F(h)$ arbitrarily close to 0, and when $p > p_c$ the limit is 1. □

**Proposition 5.7** If $p < 1/(k-\ell-1)$ and $\ell < k$ then $F_p(RT(k,\ell)) < \exp(-\Omega(n^{\log_k (k-\ell+1)}))$, which is optimal for systems with resilience $f = n^{\log_k (k-\ell+1)}$.

**Proof:** Let $g(p)$ and $F(h)$ be as in the proof of Proposition 5.6. Any configuration of at least $k - \ell + 1$ crashes disables the $\ell$-of-$k$ system, so

$$
g(p) = \sum_{j=k-\ell+1}^{k} \binom{k}{j} p^j (1-p)^{k-j}.
$$

By Lemma A.2 (see Appendix) we have that

$$
g(p) \leq \binom{k}{\ell-1} p^{k-\ell+1}.
$$

Plugging this into (4) gives that

$$
F(h) \leq \binom{k}{\ell-1} p^{k-\ell+1}.
$$

12
If $p < 1 / \binom{k}{\ell-1}$ then the last expression decays to zero with $h$, so $F_p(\text{RT}(k, \ell)) < \exp(-\Omega(n^{\log_k(k-\ell+1)}))$.

The lower bound of Proposition 4.3 shows that $F_p(\text{RT}(k, \ell)) \geq p^{n^{\log_k(k-\ell+1)}}$, so our analysis is tight.

For the RT(4, 3) system a direct calculation shows that $g(p) = 6p^2 - 8p^3 + 3p^4$ and $p_c = 0.2324$. Therefore Proposition 5.7 guarantees that when the element crash probability is in the range $p < 0.2324$ then $F_p \to 0$ when $n \to \infty$. Furthermore, when $p < 1/6$ then Proposition 5.7 shows that the decay is rapid, with $F_p(\text{RT}(4, 3)) < (6p)^{\sqrt{n}}$, which is optimal.

6 Boosted finite projective planes

In this section we introduce a family of $b$-masking quorum systems, the boosted finite projective planes, which we denote by boostFPP. A boostFPP system is a composition of a finite projective plane (FPP) over a threshold system (Thresh).

The first component of a boostFPP system is a finite projective plane of order $q$ (a good reference on FPP’s is [Hal86]). It is known that FPP’s exist for $q = p^r$ when $p$ is prime. Such an FPP has $n_F = q^2 + q + 1$ elements, and quorums of size $c(\text{FPP}) = q+1$. This is a regular quorum system, i.e., it has intersections of size $\mathcal{I}(\text{FPP}) = 1$. The minimal transversals of an FPP are of size $\mathcal{M}(\text{FPP}) = q+1$ (in fact the only transversals of this size are the quorums themselves). The load of FPP was analyzed in [NW98] and shown to be $L(\text{FPP}) = \frac{q+1}{n_F} \approx 1/\sqrt{n_F}$, which is optimal for regular quorum systems.

The second component of a boostFPP is a Thresh system, with $n_T = 4b+1$ elements and a threshold of $3b+1$. This is a $b$-masking quorum system in itself, with $\mathcal{I}(\text{Thresh}) = 2b+1$, $\mathcal{M}(\text{Thresh}) = b+1$ and a load of $L(\text{Thresh}) \approx 3/4$.

**Proposition 6.1** Let boostFPP($q, b$) = FPP($q$) $\circ$ Thresh($3b+1$ of $4b+1$). Then the composed system has $n = (4b+1)(q^2 + q + 1)$ elements, with quorums of size $c(\text{boostFPP}(q, b)) = (3b+1)(q+1)$, intersections of size $\mathcal{I}(\text{boostFPP}(q, b)) = 2b+1$ and minimal transversals of size $\mathcal{M}(\text{boostFPP}(q, b)) = (b+1)(q+1)$. Therefore boostFPP($q, b$) is a $b$-masking quorum system.

**Proof:** We obtain the combinatorial parameters by plugging the values of the component systems into Theorem 4.7. By Corollary 3.7 we have that the system can mask $\min\{(b+1)(q+1)-1, b\}$ failures. □

**Proposition 6.2** $L(\text{boostFPP}(q, b)) \approx \frac{3}{4q}$, which is optimal for $b$-masking quorum systems with $n \approx 4bq^2$ elements.
**Proof:** \( \text{boostFPP}(q, b) \) is a fair quorum system since both its components are fair, so by Proposition 3.9 we have

\[
\mathcal{L}(\text{boostFPP}(q, b)) = \frac{c(\text{boostFPP}(q, b))}{n} = \frac{(3b + 1)(q + 1)}{(4b + 1)(q^2 + q + 1)} \approx \frac{3}{4q}.
\]

On the other hand, for \( b \)-masking systems with \( n \approx 4bq^2 \) elements the lower bound of Theorem 4.1 gives

\[
\mathcal{L}(\text{boostFPP}(q, b)) \geq \sqrt{\frac{2b}{n}} \approx \frac{1}{\sqrt{2q}}. \quad \square
\]

Note that the optimality of the load holds for any choice of \( q \) and \( b \). Therefore when the number of servers (or elements) increases, the \( \text{boostFPP}(q, b) \) system can scale up using different policies while maintaining load optimality. There are two extremal policies:

1. Fix \( q \) and increase \( b \); then the system can mask more failures when new servers are added, however the load on the servers does not decrease.

2. Fix \( b \) and increase \( q \); then the load decreases when new servers are added, but the number of failures that the system can mask remains unchanged.

It is important to note that systems of arbitrarily high resilience can be constructed using the first policy since \( b \) can be chosen independently of \( q \). In particular, we can choose \( b = q^a \) for any \( a > 0 \). Then the resulting system has \( n \approx 4bq^2 = 4b^{\frac{2a+2}{a}} \), and so \( b \approx \left( \frac{4}{n} \right)^{\frac{a}{a+2}} \), thus asymptotically approaching the resilience upper bound of \( \frac{2}{4} \).

Finally we analyze the crash probability of \( \text{boostFPP} \). The following proposition shows that \( \text{boostFPP} \) has good availability as long as \( p < 1/4 \).

**Proposition 6.3** If \( p < 1/4 \) then \( F_p(\text{boostFPP}(q, b)) \leq \exp(-\Omega(b - \log q)) \).

**Proof:** We start by estimating \( F_p(\text{Thresh}) \). Let \#\text{crashed} denote the number of crashed elements in a universe of size \( 4b + 1 \). Let \( \gamma = \frac{b+1}{4b+1} - p \), thus \( 0 < \gamma < 1 \) when \( p < 1/4 \). Then using the Chernoff bound we obtain

\[
F_p(\text{Thresh}) = \Pr(\#\text{crashed} \geq b + 1) = \Pr(\#\text{crashed} \geq (p + \gamma)(4b + 1)) \leq e^{-2(4b+1)\gamma^2} \approx e^{-b(1-4p)^2/2}. \quad (5)
\]

Next we estimate \( F_p(\text{FPP}) \). Let \( Q_0 \in \text{FPP} \) be some quorum. Then

\[
F_p(\text{FPP}) = 1 - \Pr(\exists Q \in \text{FPP} : Q \text{ is alive}) \leq 1 - \Pr(Q_0 \text{ is alive}) = 1 - (1-p)^{q+1} \leq (q+1)p. \quad (6)
\]

14
Using Theorem 4.7 we plug (5) into (6) to obtain
\[ F_p(\text{boostFPP}(q, b)) \leq (q + 1)e^{-b(1-4p)^2/2} = e^{-\Omega(b-\log q)}. \]

Remarks:

- In general the crash probability is not optimal; since \( MT(\text{boostFPP}(q, b)) \approx bq \) then the lower bound of Proposition 4.3 shows we could hope for a crash probability of \( \exp(-\Omega(bq)) \). Nevertheless if \( q \) is constant then \( F_p \) is asymptotically optimal, and if \( b \gg q \) then the gap between the upper and lower bounds is small.

- The final estimate we get for \( F_p(\text{boostFPP}) \) seems poor, as the bound is higher than the crash probability of the Thresh components. However this is not an artifact of over-estimates in our analysis. Rather, it is a result of the property that the crash probability of FPP is higher than \( p \), and in fact \( F_p(\text{FPP}) \rightarrow 1 \) as shown by \[ \text{RST92, Woo96} \]. In this light it is not surprising that boostFPP does not have an optimal crash probability.

- The requirement \( p < 1/4 \) is essential for this system; if \( p > 1/4 \) then in fact \( F_p(\text{boostFPP}) \rightarrow 1 \) as \( n \rightarrow \infty \).

7 The multi-path system

Here we introduce the construction we call the Multi-Path system, denoted by M-Path. The elements of this system are the vertices of a triangulated square \( \sqrt{n} \times \sqrt{n} \) grid; formally, the vertices are the points \( \{(i, j) \in \mathbb{R}^2 : 1 \leq i, j \leq \sqrt{n}; \ i, j \in \mathbb{Z}\} \). The triangulated grid has an edge between \((i_1, j_1)\) and \((i_2, j_2)\) if one of the following three conditions holds: (i) \( i_1 = i_2 \) and \( j_2 = j_1 + 1 \); (ii) \( j_1 = j_2 \) and \( i_2 = i_1 + 1 \); (iii) \( i_2 = i_1 - 1 \) and \( j_2 = j_1 + 1 \). A quorum in the M-Path system consists of \( \sqrt{2b + 1} \) disjoint paths from the left side to the right side of the grid (LR paths) and \( \sqrt{2b + 1} \) disjoint top-bottom (TB) paths (see Figure 3).

The M-Path system has several characteristics similar to the basic M-Grid system of Section 5, namely an ability to mask \( b = O(\sqrt{n}) \) failures, and optimal load. Its major advantage is that it also has an optimal crash probability \( F_p \). Moreover, it is the only construction we have for which \( F_p \rightarrow 0 \) as \( n \rightarrow \infty \) when the individual crash probability \( p \) is arbitrarily close to 1/2.

We are able to prove this behavior of \( F_p \) using results from Percolation theory [Kes82, Gri89].

Remark: The system we present here is based on a triangular lattice, with elements corresponding to vertices, as in [WB92, Baz96]. We have also constructed a second system which is based on the square lattice with elements corresponding to the edges, as in [NW98]. The properties of this second system are almost identical to those of M-Path, so we omit it.

**Proposition 7.1** M-Path(b) has minimal quorums of size \( c(M-\text{Path}) \leq 2\sqrt{n}(2b + 1) \), minimal intersections of size \( IS(M-\text{Path}) \geq 2b + 1 \), and minimal transversals of size \( MT(M-\text{Path}) = \sqrt{n} - \sqrt{2b + 1} + 1 \). Therefore M-Path is a b-masking quorum system for \( b \leq \sqrt{n} - \sqrt{2n^{1/4}} \).
Figure 3: A multi-path construction on a $9 \times 9$ grid, $b = 4$, with one quorum shaded.

Proof: Let $Q_1, Q_2 \in M\text{-Path}(b)$. Then the $\sqrt{2b+1}$ LR paths of $Q_1$ intersect the $\sqrt{2b+1}$ TB paths of $Q_2$ in $\geq 2b + 1$ elements, since the LR and TB paths are disjoint. As in the M-Grid system we have that $MT(M\text{-Path}(b)) = \sqrt{n} - \sqrt{2b+1} + 1$, so when $b \leq \sqrt{n} - \sqrt{2n^{1/4}}$ it follows that $MT(M\text{-Path}(b)) \geq b + 1$ and we are done. \hfill \Box

Proposition 7.2 $\mathcal{L}(M\text{-Path}(b)) \leq 2\sqrt{\frac{2b+1}{n}}$, which is optimal.

Proof: The strategy only uses straight line LR and TB paths. It picks $\sqrt{2b+1}$ of the $\sqrt{n}$ rows uniformly at random and likewise for the columns. Clearly the load equals the probability of accessing some element in position $i, j$, which is

$$\mathcal{L}(M\text{-Path}) \leq \mathbb{P}(\text{row } i \text{ chosen}) + \mathbb{P}(\text{column } j \text{ chosen})$$

$$\leq 2\left(\frac{\sqrt{n} - 1}{\sqrt{2b+1} - 1}\right)/\left(\frac{\sqrt{n}}{\sqrt{2b+1}}\right)$$

$$= 2\sqrt{2b + 1}/\sqrt{n}.$$

By Corollary 4.2 this is optimal. \hfill \Box

Proposition 7.3 $F_p(M\text{-Path}(b)) \leq \exp(-\Omega(\sqrt{n} - \sqrt{b}))$ for any $p < 1/2$, which is optimal for systems with resilience $f = O(\sqrt{n} - \sqrt{b})$.

Proof: We use the notation $\mathbb{P}_p(E)$ to denote the probability of event $E$ defined on the grid when the individual crash probability is $p$. A path is called “open” if all its elements are alive.

Let $LR$ be the event “there exists an open LR path in the grid”, and let $LR_k$ be the event “there exist $k$ open LR paths”. A failure configuration in M-Path($b$) is one in which either $\sqrt{2b+1}$ open LR paths or $\sqrt{2b+1}$ open TB paths do not exist. By symmetry we have that

$$F_p(M\text{-Path}(b)) \leq 2\mathbb{P}_p(LR_{\sqrt{2b+1}}) = 2(1 - \mathbb{P}_p(LR_{\sqrt{2b+1}})). \quad (7)$$

16
Fix some $p'$ such that $p < p' < 1/2$. Then by Theorem 3.3 (see Appendix) we have that

$$1 - \mathbb{P}_p(LR\sqrt{2b+1}) \leq \left(\frac{1-p}{p'-p}\right)^{\sqrt{2b+1}-1} [1 - \mathbb{P}_{p'}(LR)]. \quad (8)$$

Plugging the bound on $\mathbb{P}_{p'}(LR)$ from Theorem 3.1 into (8) and (7) yields

$$F_p(M-Path(b)) \leq 2 \left(\frac{1-p}{p'-p}\right)^{\sqrt{2b+1}-1} e^{-\psi(p')\sqrt{n}} = 2e^{-\psi(p')\sqrt{n} + (\sqrt{2b+1} - 1) \ln \left(\frac{1-p}{p'-p}\right)}$$

for some function $\psi(p') > 0$. Now $\sqrt{2b+1} = O(n^{1/4})$, so for large enough $n$ we can certainly write

$$F_p(M-Path(b)) \leq \exp(-\Omega(\sqrt{n} - \sqrt{b})).$$

This is optimal by Proposition 4.3.

8 Discussion

We have presented four novel constructions of $b$-masking quorum systems. For the first time in this context, we considered the resilience of such systems to crash failures in addition to their tolerance of (possibly fewer) Byzantine failures. Each of our constructions is optimal in either its load or its crash probability (for sufficiently small $p$). Moreover, one of our constructions, namely M-Paths, is optimal in both measures. One of our constructions is achieved using a novel boosting technique that makes all known benign fault-tolerant quorum constructions available for Byzantine environments (of appropriate sizes). In proving optimality of our constructions, we also contribute lower bounds on the load and crash probability of any $b$-masking quorum system.

The properties of our various constructions are summarized in Table 3 alongside the properties of two other $b$-masking constructions proposed in [MR98a], namely Threshold and Grid.

Determining the best quorum construction depends on the goals and constraints of any particular settings, as no system is advantageous in all measures. For example, suppose we fix $n$ to be 1024, the desired load $L$ to be approximately 1/4, and assume that the individual failure probability of components is 1/8. In these settings, an M-Grid system can tolerate $b = 15$ Byzantine failures and up to $f = 28$ benign failures, but has a failure probability $F_p \geq 0.638$. In the same settings, a boostFPP system (with $n = 1001$, $q = 3$) can tolerate $b = 19$, up to $f = 79$ benign failures, with somewhat better failure probability: it has $F_p \leq 0.372$. The M-Path construction, with 4 LR and 4 TB paths per quorum, has $b = 7$ here, and can tolerate up to $f = 29$ benign failures, but has a good crash probability: $F_p \leq 0.001$ (using the estimate following Theorem 3.1, together with Theorem 3.3 with $p' = 1/7$). In this setting, the RT(4,3) construction, with depth $h = 5$, is the best, with $b = 15$, $f = 31$ and an excellent failure probability of only $F_p \leq 0.0001$. 

17
Table 2: Constructions in this paper ($n$ = number of servers).

| System     | $b$     | $f$                   | $\mathcal{L}$                   | $F_p$                          |
|------------|---------|-----------------------|---------------------------------|--------------------------------|
| Threshold  | $n/4$   | $O(n - b)$            | $1/2 + O(b/n)$                  | $\exp(-\Omega(f))$ *          |
| Grid       | $\sqrt{n}/3$ | $O(\sqrt{n} - b)$ | $O(b/\sqrt{n})$                | $\xrightarrow[n \to \infty]{} 1$ |
| M-Grid     | $\sqrt{n}/2$ | $O(\sqrt{n} - \sqrt{b})$ | $O(\sqrt{b}/n)$                | $\xrightarrow[n \to \infty]{} 1$ |
| RT($k, \ell$)† | $O(\min\{n^{\alpha_1}, n^{\alpha_2}\})$ † | $O(b)$ | $n^{-(1-\log_k \ell)}$ | $\exp(-\Omega(f))$ *          |
| boostFPP   | $n/4$   | $O(\sqrt{bn})$       | $O(\sqrt{b}/n)$                | $\exp(-\Omega(b - \log(n/b)))$ |
| M-Path     | $(1-o(1))\sqrt{n}$ | $O(\sqrt{n} - \sqrt{b})$ | $O(\sqrt{b}/n)$                | $\exp(-\Omega(f))$ *          |

† Optimal for $b$-masking systems
* Optimal for $f$-resilient systems
‡ $\alpha_1 = \log_k (2\ell - k)$ and $\alpha_2 = \log_k (k - \ell + 1)$

More generally, if masking large numbers of Byzantine server failures is important, then of the systems listed in Table 2, only Threshold and boostFPP can provide the highest possible masking ability, i.e., up to $b < n/4$. However, Threshold can mask $n/4$ Byzantine failures for any system size, whereas boostFPP approaches such degree of Byzantine resilience only for very large $n$. If, on the other hand, load is more crucial, then Threshold suffers in load whereas boostFPP offers reduced load, as do the other three systems in this paper, albeit with lower masking ability. If masking fewer Byzantine server failures is allowable, then other quorum constructions can be used, in particular RT and M-Path. These two constructions have similar masking ability, resilience, and load, but M-Path has asymptotically superior crash probability when $p$ is close to $1/2$.

Finally, we note that it is impossible to achieve optimal resilience and load simultaneously: Since necessarily $f \leq c(Q)$, Theorem 4.1 implies that $f \leq n\mathcal{L}(Q)$, i.e., when load is low then so is resilience, and when resilience is high then so is load. In order to break this tradeoff, in [MRWW98] we propose relaxing the intersection property of masking quorum systems, so that “quorums” chosen according to a specific strategy intersect each other in enough correct servers to maintain correctness of the system with a high probability.

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Appendix

A Combinatorial Lemmas

Lemma A.1 Let $0 \leq i, d \leq k$ be integers. Then $\binom{k}{d+i} \leq \binom{k-d}{i}$.

Proof: $\binom{k}{d+i}/\binom{k}{d} = \frac{k!}{(d+i)!(k-d-i)!k!} = \frac{(k-d)!}{(k-d-i)!(d+i)!} \leq \frac{(k-d)!}{(k-d-i)!i!} = \binom{k-d}{i}$  \qed

Lemma A.2 Let $0 \leq d \leq k$ be integers and let $p \in [0,1]$. Then

$$\sum_{j=d}^{k} \binom{k}{j} p^j (1-p)^{k-j} \leq \binom{k}{d} p^d.$$

Proof: $\sum_{j=d}^{k} \binom{k}{j} p^j (1-p)^{k-j} = \binom{k}{d} p^d \sum_{j=d}^{k} \binom{k}{j} p^{j-d} (1-p)^{k-j}$, so it suffices to show that the last sum is $\leq 1$. But using Lemma A.1 we get

$$\sum_{j=d}^{k} \binom{k}{j} p^{j-d} (1-p)^{k-j} = \sum_{i=0}^{k-d} \binom{k-d+i}{i} p^i (1-p)^{k-d-i} \leq \sum_{i=0}^{k-d} \binom{k-d}{i} p^i (1-p)^{k-d-i} = [p + (1-p)]^{k-d} = 1.$$  \qed

B Theorems of Percolation Theory

In this section we list the definitions and results that are used in our analysis of the M-Path system, following [Kes82, Gri89].

The percolation model we are interested in is as follows. Let $Z$ be the graph of the (infinite) triangle lattice in the plane. Assume that a vertex is closed with probability $p$ and open with
probability $1 - p$, independently of other vertices. This model is known as site percolation on the triangle lattice. Another natural model, which plays a minor role in our work, is the bond percolation model. In it the edges are closed with probability $p$.

A key idea in percolation theory is that there exists a critical probability, $p_c$, such that graphs with $p < p_c$ exhibit qualitatively different properties than graphs with $p > p_c$. For example, $\mathbb{Z}$ with $p < p_c$ has a single connected (open) component of infinite size. When $p > p_c$ there is no such component. For site percolation on the triangle $p_c = 1/2$ \cite{Kes80}.

The following theorem shows that when the probability $p$ for a closed vertex is below the critical probability, the probability of having long open paths tends to 1 exponentially fast.

Recall that $LR$ is the event “there exists an open LR path in the $\sqrt{n} \times \sqrt{n}$ grid”. Then \cite{Men86} (see also \cite{Gri89} p. 287) implies

\textbf{Theorem B.1} If $p < 1/2$ then $\mathbb{P}_p(LR) \geq 1 - e^{-\psi(p)\sqrt{n}}$, for some $\psi(p) > 0$ independent of $n$.

\textbf{Remark:} The dependence of $\psi$ on $p$ is such that $\psi(p) \to 0$ when $p \to 1/2$. However, for $p$’s not too close to 1/2 we can obtain concrete estimates using elementary techniques. For instance, a counting argument similar to that of Bazzi \cite{Baz96} shows that

$$\mathbb{P}_p(LR) \geq 1 - \frac{\sqrt{n}(3p)^{\sqrt{n}}}{1 - 3p},$$

when $p < 1/3$.

\textbf{Definition B.2} Let $\mathcal{E}$ be an event defined in the percolation model. Then the interior of $\mathcal{E}$ with depth $r$, denoted $I_r(\mathcal{E})$, is the set of all configurations in $\mathcal{E}$ which are still in $\mathcal{E}$ even if we perturb the states of up to $r$ vertices.

We may think of $I_r(\mathcal{E})$ as the event that $\mathcal{E}$ occurs and is ‘stable’ with respect to changes in the states of $r$ or fewer vertices. The definition is useful to us in the following situation. If $LR$ is the event “there exists an open left-right path in a rectangle $D$”, then it follows that $I_r(LR)$ is the event “there are at least $r + 1$ disjoint open left-right paths in $D$”.

\textbf{Theorem B.3} \cite{ACC+83} Let $\mathcal{E}$ be an increasing event and let $r$ be a positive integer. Then

$$1 - \mathbb{P}_p(I_r(\mathcal{E})) \leq \left(\frac{1 - p}{p' - p}\right)^r [1 - \mathbb{P}_{p'}(\mathcal{E})]$$

whenever $0 \leq p < p' \leq 1$.

The theorem amounts to the assertion that if $\mathcal{E}$ is likely to occur when the crash probability is $p'$, then $I_r(\mathcal{E})$ is likely to occur when the crash probability $p$ is smaller than $p'$.