Multi-Agent Only Knowing

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Abstract

Levesque introduced a notion of “only knowing”, with the goal of capturing certain types of nonmonotonic reasoning. Levesque’s logic dealt with only the case of a single agent. Recently, both Halpern and Lakemeyer independently attempted to extend Levesque’s logic to the multi-agent case. Although there are a number of similarities in their approaches, there are some significant differences. In this paper, we reexamine the notion of only knowing, going back to first principles. In the process, we simplify Levesque’s completeness proof, and point out some problems with the earlier definitions. This leads us to reconsider what the properties of only knowing ought to be. We provide an axiom system that captures our desiderata, and show that it has a semantics that corresponds to it. The axiom system has an added feature of interest: it includes a modal operator for satisfiability, and thus provides a complete axiomatization for satisfiability in the logic K45.
1 Introduction

Levesque introduced a notion of “only knowing”, with the goal of capturing certain types of nonmonotonic reasoning. In particular, he hoped to capture the type of reasoning that says “If all I know is that Tweety is a bird, and that birds typically fly, then I can conclude that Tweety flies”. Levesque’s logic dealt only with the case of a single agent. It is clear that in many applications of such nonmonotonic reasoning, there are several agents in the picture. For example, it may be the case that all Jack knows about Jill is that Jill knows that Tweety is a bird and that birds typically fly. Jack may then want to conclude that Jill knows that Tweety flies.

Recently, each of us independently attempted to extend Levesque’s logic to the multi-agent case. Although there are a number of similarities in the approaches, there are some significant differences. In this paper, we reexamine the notion of only knowing, going back to first principles. In the process, we point out some problems with both of the earlier definitions. This leads us to consider what the properties of only knowing ought to be. We provide an axiom system that captures all our desiderata, and show that it has a semantics that corresponds to it. The axiom system has an added feature of interest: it involves enriching the language with a modal operator for satisfiability, and thus provides an axiomatization for satisfiability in K45. Unfortunately, the semantics corresponding to this axiomatization is not as natural as we might like. It remains an open question whether there is a natural semantics for only knowing that corresponds to this axiomatization.

The rest of this paper is organized as follows. In the next section, we review the basic ideas of Levesque’s logic and provide an alternative semantics. The use of the alternative semantics leads to a simplification of Levesque’s completeness proof. In Section 3, we review Lakemeyer’s approach, which we call the canonical-model approach, and discuss some of its strengths and weaknesses. In Section 4, we go through the same process for Halpern’s approach. In Section 5, we consider our new approach. Much of the discussion in Sections 3 and 5 is carried out in terms of three critical properties of Levesque’s approach which we call out in Section 2. In particular, we examine to what extent each of the approaches satisfies these properties. In Section 6, we show how the logic can be used, and discuss its relationship to Moore’s autoepistemic logic. Levesque showed that the single-agent version of his logic of only knowing was closely connected to autoepistemic logic. We extend his result to the multi-agent case. We conclude in Section 7 with some discussion of only knowing.

2 Levesque’s Logic of Only Knowing

We begin by reconsidering Levesque’s definition. Let $\Phi$ be a set of primitive propositions. Let $\text{ONL}(\Phi)$ be a propositional modal language formed by starting with the primitive propositions in $\Phi$, and closing off under the classical operators $\neg$ and $\lor$ and two modalities, $L$ and $N$. We omit the $\Phi$ whenever it is clear from context or not relevant to the discussion. We freely use other connectives like $\land$, $\Rightarrow$, and $\Leftrightarrow$ as syntactic abbreviations of the usual kind. In addition, we take $O\alpha$ to be an

\[1\] The reader should feel free to substitute “believe” anywhere we say “know”. Indeed, the formal logic that we use, which is based on the modal logic K45, is more typically viewed as a logic of belief rather than knowledge.
abbreviation for $L\alpha \land N\neg \alpha$. Here $L\alpha$ should be read as “the agent knows or believes (at least) $\alpha$, $N\alpha$ should be read as “the agent believes at most $\neg \alpha$” (so that $N\neg \alpha$ is “the agent believes at most $\alpha$”) and $O\alpha$ should be read as “the agent knows only $\alpha$”.

We define an objective formula to be a propositional formula (i.e., a formula with no modal operators), a subjective formula to be a Boolean combination of formulas of the form $L\varphi$ or $N\varphi$, and a basic formula to be a formula which does not mention $N$.

Levesque gave semantics to knowing and only knowing using the standard possible-worlds approach. In the single-agent case, we can identify a situation with a pair $(W,w)$, where $w$ is a possible world (represented as a truth assignment to the primitive propositions) and $W$ consists of a set of possible worlds. Intuitively, $W$ is the set of worlds which the agent considers (epistemically) possible, and $w$ describes the real world. We do not require that $w \in W$ or that $W \neq \emptyset$. As usual, we say that the agent knows (at least) $\alpha$ if $\alpha$ is true in all the worlds that the agent considers possible.

Formally, the semantics of the modality $L$ and the classical connectives is given as follows.

$(W,w) \models p$ if $w \models p$ if $p$ is a primitive proposition.

$(W,w) \models \neg \alpha$ if $(W,w) \models \not\alpha$.

$(W,w) \models \alpha \lor \beta$ if $(W,w) \models \alpha$ or $(W,w) \models \beta$.

$(W,w) \models L\alpha$ if $(W,w') \models \alpha$ for all $w' \in W$.

Notice that if $L\alpha$ holds, then the agent may know more than $\alpha$. For example, $Lp$ does not preclude $L(p \land q)$ from holding. This is why we should think of $L\alpha$ as saying that the agent knows (at least) $\alpha$.

It is well-known that this logic is characterized by the axiom system K45. For convenience, we describe K45 here:

**Axioms:**

- **P.** All instances of axioms of propositional logic.
- **K.** $(L\varphi \land L(\varphi \Rightarrow \psi)) \Rightarrow L\psi$.
- **4.** $L\varphi \Rightarrow L\varphi$.
- **5.** $\neg L\varphi \Rightarrow L\neg L\varphi$.

**Inference Rules:**

- **R1.** From $\varphi$ and $\varphi \Rightarrow \psi$ infer $\psi$.
- **R2.** From $\varphi$ infer $L\varphi$.

The axioms 4 and 5 are called the **positive introspection axiom** and **negative introspection axiom**, respectively. They are appropriate for agents that are sufficiently introspective so that they know what they know and do not know.

How do we give precise semantics to $N$? That is, when should we say that $(W,w) \models N\beta$? Intuitively, $N\beta$ is true if $\beta$ is true at all the worlds that the agent does not consider possible. It seems fairly clear from the intuition that we need to evaluate the truth of $\beta$ in worlds $w' \notin W$ since these are the worlds that the agent considers impossible in $(W,w)$. But if $\beta$ is a complicated formula involving nested $L$ operators, then we cannot simply evaluate the truth of $\beta$ at a world $w'$. We need to have a set of worlds too. In fact, the set of possible worlds we use is still $W$. That is, while

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2By requiring that $W$ is nonempty, we get the modal logic KD45; by requiring that $w \in W$, we get S5.

3Note that, since we defined worlds extensionally as truth assignments, the set of impossible worlds is well-defined and fixed for a given $W$. 

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evaluating the truth of $\beta$ in the impossible worlds, the agent keeps the set of worlds he considers possible fixed. Formally, we define

$$(W, w) \models N\alpha \text{ if } (W, w') \models \alpha \text{ for all } w' \notin W.$$ 

Let us stress three important features of this definition.

- First, as we have already observed, the set of possibilities is kept fixed when we evaluate $N\alpha$.
- Second, the set of conceivable worlds—the union of the set of “possible” worlds considered when evaluating $L$ and the set of “impossible” worlds considered when evaluating $N$—is fixed, independent of the situation $(W, w)$; it is always the set of all truth assignments.
- Finally, for every set of conceivable worlds, there is a model where that set is precisely the set of worlds that the agent considers possible.

Roughly speaking, the first property is what is required for A4, while the second property is what is required for A5. The intent of the third property is to make it possible that any objective formula can be “all you know.” As we shall see in Section 5, in a precise sense, the third property is somewhat stronger than we actually need. All we really need is that for any objective formulas the set of all worlds satisfying these formulas can be considered possible. We return to these properties for guidance when we discuss possible ways of extending Levesque’s semantics to the multi-agent case.

Since $O\alpha$ is an abbreviation for $L\alpha \land N\neg\alpha$, we have that

$$(W, w) \models O\alpha \text{ if for all worlds } w', w' \in W \text{ iff } (W, w') \models \alpha.$$ 

As it stands, the semantics has the somewhat odd property that there are situations that agree on all basic beliefs yet disagree on what is not believed. As pointed out by Levesque, the problem is that there are far too many sets of worlds than there are basic belief sets. In order to find a perfect match between the sets of basic beliefs an agent may hold and sets of worlds, Levesque introduces what he calls maximal sets of worlds. In essence, a maximal set is the largest set in the sense that adding any other world to it would change the agent’s basic beliefs. Furthermore, every set of worlds can be extended to a unique maximal set of worlds. It is well known that in the logic K45, an agent’s beliefs are completely determined by his beliefs about objective formulas (see, for example, for a proof). Thus, we define a maximal set as follows:

**Definition 2.1** If $W$ is a set of worlds, let

$$W^+ = \{ w \mid \text{for all objective formulas } \varphi, \text{ if } (W, w) \models L\varphi \text{ then } (W, w) \models \varphi \}.$$ 

$W$ is called maximal iff $W = W^+$.

Levesque defines validity and satisfiability with respect to maximal sets only. In particular, a formula $\alpha$ is valid iff for every maximal set of worlds $W$ and every world $w \in W$, we have $(W, w) \models \alpha$.

We end this review of Levesque’s logic by presenting (a slight variant of) his proof theory.

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Axioms:
A1. All instances of axioms of propositional logic.
A2. $L(\alpha \Rightarrow \beta) \Rightarrow (L\alpha \Rightarrow L\beta)$.
A3. $N(\alpha \Rightarrow \beta) \Rightarrow (N\alpha \Rightarrow N\beta)$.
A4. $\sigma \Rightarrow L\sigma \land N\sigma$ for every subjective formula $\sigma$.
A5. $N\alpha \Rightarrow \neg L\alpha$ if $\neg \alpha$ is a propositionally consistent objective formula.

Inference Rules:
MP. From $\alpha$ and $\alpha \Rightarrow \beta$ infer $\beta$.
Nec. From $\alpha$ infer $L\alpha$ and $N\alpha$.

Axioms A2–A4 tell us that that $L$ and $N$ separately have all the properties of K45-operators. Actually, A4 tells us more; it says that $L$ and $N$ are mutually introspective, so that, for example, $L\varphi \Rightarrow NL\varphi$ is valid. Perhaps the most interesting axiom is A5, which gives only-knowing its desired properties. Its soundness depends on the fact that the union of the set of worlds considered when evaluating $L$ and the set of worlds considered when evaluating $N$ is the set of all conceivable worlds.

Theorem 2.2 If $\Phi$ is infinite, then Levesque’s axiomatization is sound and complete for the language $ONL(\Phi)$ with respect to Levesque’s semantics.

As we shall see, the assumption that there are infinitely many primitive propositions in $\Phi$ is crucial for Levesque’s completeness result. Extra axioms are required if $\Phi$ is finite. In addition, it is interesting to note that the assumption that $L$ and $N$ are interpreted with respect to complementary sets of worlds is not forced by the axioms. In particular, for the soundness of Axiom A5, it suffices that the sets considered for $L$ and $N$ cover all conceivable worlds; they may overlap. The following semantics makes this precise.

Define an extended situation to be a triple $(W_L, W_N, w)$, where $W_L$ and $W_N$ are sets of worlds (truth assignments) such that $W_L \cup W_N$ consists of all truth assignments. Define a new satisfaction relation $\models^x$ that is exactly like Levesque’s except for $L$- and $N$-formulas. For them, we have

- $(W_L, W_N, w) \models^x L\alpha$ if $(W_L, W_N, w') \models^x \alpha$ for all $w' \in W_L$.
- $(W_L, W_N, w) \models^x N\alpha$ if $(W_L, W_N, w') \models^x \alpha$ for all $w' \in W_N$.

Note that $L$ and $N$ are now treated in a completely symmetric way.

Theorem 2.3 For all $\Phi$, Levesque’s axiomatization is sound and complete for the language $ONL(\Phi)$ with respect to $\models^x$.

Proof We omit the soundness proof, which is straightforward. Note that for axiom A5 to be sound it suffices that $W_L$ and $W_N$ together cover all worlds. In particular, it does not matter whether or not the two sets overlap.

To prove completeness, we use the notion of a maximal consistent set. Given an arbitrary axiom system $AX$, we say that a formula $\varphi$ is consistent with respect to $AX$...
Lemma 2.5  

(a) Here, we must be a little more careful. A finite set of formulas \( \varphi_1, \ldots, \varphi_n \) is consistent with respect to \( AX \) if the conjunction \( \varphi_1 \land \ldots \land \varphi_n \) is consistent with respect to \( AX \). An infinite set of formulas is consistent with respect to \( AX \) if every finite subset of its formulas is consistent with respect to \( AX \). Finally, given a set \( F \) of formulas, a maximal consistent subset of \( F \) is a subset \( F' \) of \( F \) which is consistent with respect to \( AX \) such that any superset of \( F' \) is not consistent with respect to \( AX \).

In the following, provability, consistency, and maximal consistency all refer to Levesque’s axiom system unless stated otherwise. To prove completeness we show that every consistent formula is satisfiable with respect to \( \models^x \), using a standard canonical model construction \([7, 10]\).

Let \( \Gamma_0 \) be the set of all maximal consistent sets of formulas in \( ONL(\Phi) \). For \( \theta \in \Gamma_0 \), define \( \theta/L = \{ \alpha \mid L\alpha \in \theta \} \) and \( \theta/N = \{ \alpha \mid N\alpha \in \theta \} \). We then define

\[
\begin{align*}
\Gamma^\theta_L &= \{ \theta' \in \Gamma_0 \mid \theta/L \subseteq \theta' \}, \\
\Gamma^\theta_N &= \{ \theta' \in \Gamma_0 \mid \theta/N \subseteq \theta' \}.
\end{align*}
\]

If we view maximal consistent sets as worlds, then \( \Gamma^\theta_L \) and \( \Gamma^\theta_N \) represent the worlds accessible from \( \theta \) for \( L \) and \( N \), respectively. The following lemma reflects the fact that \( L \) and \( N \) are both fully and mutually introspective (axiom \( A4 \)).

**Lemma 2.4** If \( \theta' \in \Gamma^\theta_L \cup \Gamma^\theta_N \), then \( \Gamma^\theta_L = \Gamma^\theta_L \) and \( \Gamma^\theta_N = \Gamma^\theta_N \).

**Proof** We prove the lemma for \( \theta' \in \Gamma^\theta_L \). The case \( \theta' \in \Gamma^\theta_N \) is completely symmetric.

To show that \( \Gamma^\theta_L = \Gamma^\theta_L \), it clearly suffices to show that \( \theta/L = \theta'/L \). Let \( \alpha \in \theta/L \). Then \( L\alpha \in \theta \) and also \( L\alpha \in \theta' \) by axiom \( A4 \). Thus \( L\alpha \in \theta \) (since \( \theta' \in \Gamma^\theta_L \) implies that \( \theta/L \subseteq \theta' \)) and, hence, \( \alpha \in \theta'/L \).

For the converse, let \( \alpha \in \theta'/L \). Thus, \( L\alpha \in \theta' \). Assume that \( \alpha \not\in \theta/L \). Then \( \neg L\alpha \in \theta \) (since \( \theta' \) is a maximal consistent set) and, therefore, \( \neg L\alpha \in \theta \), from which \( \neg L\alpha \in \theta' \), follows, a contradiction.

The proof that \( \Gamma^\theta_N = \Gamma^\theta_N \) proceeds the same way, that is, we show that \( \theta/N = \theta'/N \). Let \( \alpha \in \theta/N \). Then \( N\alpha \in \theta \) and also \( L\alpha \in \theta \) by axiom \( A4 \). Hence \( N\alpha \in \theta' \), so \( \alpha \in \theta'/N \).

For the converse, let \( \alpha \in \theta'/N \). Thus, \( N\alpha \in \theta' \). Assume that \( \alpha \not\in \theta/N \). Then \( \neg N\alpha \in \theta \) and also \( L\neg N\alpha \in \theta \), from which \( \neg N\alpha \in \theta' \), follows, a contradiction.

In traditional completeness proofs using maximal consistent sets (see, for example, \([7, 10]\)), a situation is constructed whose worlds consists of all maximal consistent sets. Here, we must be a little more careful.

We say that a maximal consistent set \( \theta \) contains a truth assignment \( w \) if for all atomic formulas \( p \), we have \( w \models p \) iff \( p \in \theta \). Clearly a maximal consistent set \( \theta \) contains exactly one world; we denote this world by \( w_\theta \). For \( \theta \in \Gamma_0 \), let \( W^\theta_L = \{ w_\theta' \mid \theta' \in \Gamma^\theta_L \} \) and \( W^\theta_N = \{ w_\theta' \mid \theta' \in \Gamma^\theta_N \} \).

**Lemma 2.5**  

(a) \( (W^\theta_L, W^\theta_N, w_\theta) \) is an extended situation.

(b) For all \( \alpha \), we have \( \alpha \in \theta \) iff \( (W^\theta_L, W^\theta_N, w_\theta) \models^x \alpha \).
Proof For part (a), to show that \((W_L^\theta, W_N^\theta, w_\theta)\) is an extended situation, we must show that \(W_L^\theta \cup W_N^\theta\) consists of all truth assignments. By way of contradiction, suppose there is a truth assignment \(w\) not in \(W_L^\theta \cup W_N^\theta\). Let \(F_w = \{ p \in \Phi \mid w = p \} \cup \{-p \mid p \in \Phi, w = \neg p\}\). \(F_w \cup \theta/L\) cannot be consistent, for otherwise there would be some \(\theta' \in \Gamma^\theta\) that contains \(F_w\), which would mean that \(w \in W_L^\theta\). Similarly \(F_w \cup \theta/N\) cannot be consistent. Thus, there must be formulas \(\varphi_1, \varphi_2, \varphi_3, \varphi_4\) such that \(\varphi_1\) and \(\varphi_2\) are both conjunctions of a finite number of formulas in \(F_w\), \(\varphi_3\) is the conjunction of a finite number of formulas in \(\theta/L\), and \(\varphi_4\) is the conjunction of a finite number of formulas in \(\theta/N\), and both \(\varphi_1 \land \varphi_3\) and \(\varphi_2 \land \varphi_4\) are inconsistent. Thus, we have \(\vdash \varphi_3 \Rightarrow \neg \varphi_1\) and \(\vdash \varphi_4 \Rightarrow \neg \varphi_2\). Using standard modal reasoning (A2, A3, and Nec), we have \(\vdash L\varphi_3 \Rightarrow L\neg \varphi_1\) and \(N\varphi_4 \Rightarrow N\neg \varphi_2\). Since \(L\psi \in \theta\) for each conjunct \(\psi\) of \(\varphi_3\), standard modal reasoning shows that \(L\varphi_3 \in \theta\). Similarly, we have \(N\varphi_4 \in \theta\). Since \(\theta\) is a maximal consistent set, both \(L\neg \varphi_1\) and \(N\neg \varphi_2\) are in \(\theta\). Since \(\vdash L\neg \varphi_1 \Rightarrow L(\neg \varphi_1 \vee \neg \varphi_2)\) and \(\vdash N\neg \varphi_2 \Rightarrow N(\neg \varphi_1 \vee \neg \varphi_2)\), it follows that both \(L(\neg \varphi_1 \vee \neg \varphi_2)\) and \(N(\neg \varphi_1 \vee \neg \varphi_2)\) are in \(\theta\). But this contradicts A5, since \(\varphi_1 \land \varphi_2\) is a propositionally consistent objective formula.

For part (b), the proof proceeds by induction on the structure of \(\alpha\). The statement holds trivially for atomic propositions, conjunctions, and negations. In the case of \(L\alpha\), we proceed by the following chain of equivalences:

\[
L\alpha \in \theta \iff \text{for all } \theta' \in \Gamma^\theta, \text{ we have } \alpha \in \theta' \iff \text{for all } \theta' \in \Gamma^\theta, \text{ we have } (W_L^{\theta'}, W_N^{\theta'}, w_{\theta'}) \models^\tau \alpha \text{ (using the induction hypothesis)} \iff \text{for all } w_{\theta'} \in W_L^\theta, \text{ we have } (W_L^\theta, W_N^\theta, w_{\theta'}) \models^\tau \alpha \text{ (by Lemma 2.4)} \iff (W_L^\theta, W_N^\theta, w_\theta) \models^\tau L\alpha.
\]

The case \(\neg \alpha\) is completely symmetric.

The completeness result now follows easily. Let \(\alpha\) be a consistent formula and \(\theta\) a maximal consistent set of formulas containing \(\alpha\). By Lemma 2.3, \((W_L^\theta, W_N^\theta, w_\theta) \models^\tau \alpha\).

Levesque considered only maximal sets in his definition of validity. In fact, this restriction has no effect on the notion of validity.

Corollary 2.6 A formula \(\alpha \in \mathcal{OL}(\Phi)\) is valid iff \((W, w) \models \alpha\) for all situations \((W, w)\) (including nonmaximal \(W\)).

Proof If \(\Phi\) is finite, it is easy to check that \(W^+ = W\) for all sets \(W\), so the result is trivially true if \(\Phi\) is finite. So suppose \(\Phi\) is infinite. Notice that each situation \((W, w)\) corresponds to an extended situation \((W_L, W_N, w)\), where \(W_L = W\) and \(W_N\) is the complement of \(W\). Let us call such an \((W_L, W_N, w)\) an extended complementary situation. Theorems 2.2 and 2.3 together imply the valid formulas obtained when considering all extended situations remain the same when we restrict ourselves to complementary situations with maximal \(W_L\). The corollary then follows from the fact that the set of all extended situations properly includes the set of all extended complementary situations, which in turn includes the set of all extended complementary situations with maximal \(W_L\).

As Theorem 2.3 shows, for the \(\models^\tau\) semantics, Levesque’s axioms are sound and complete for all sets \(\Phi\) of primitive propositions. On the other hand, as we said earlier,
Levesque’s completeness proof (with respect to his semantics) depends crucially on the fact that $\Phi$ is infinite. If $\Phi$ is finite, Levesque’s axioms are still sound with respect to his semantics, but they are no longer complete. For example, if $\Phi = \{p\}$, then $\neg Lp \Rightarrow N\neg p$ would be valid under $|=; this does not follow from the axioms given above. In fact, for each finite set $\Phi$ of primitive propositions, we can find a new axiom scheme that, taken together with the previous axioms, gives a complete axiomatization for $ONL(\Phi)$ for Levesque’s semantics if $\Phi$ is finite. The new axiom, which subsumes axiom $A5$, allows us to reduce formulas involving $N$ formulas involving only $L$.

Note that worlds, which are truth assignments to the primitive propositions $\Phi$, are themselves finite if $\Phi$ is finite. Hence we can identify a world $w$ with the conjunction of all literals over $\Phi$ that are true at $w$. For example, if $\Phi = \{p, q\}$ and $w$ makes $p$ true and $q$ false, then we identify $w$ with $p \land \neg q$. For any objective formula $\alpha$, let $W_{\alpha, \Phi}$ be the set of all worlds (over the primitive propositions $\Phi$) that satisfy $\alpha$. The axiom system $AX_{\Phi}$ is then obtained from Levesque’s system by replacing $A5$ by the following axiom:

$$A5_{\Phi}. \quad N\alpha = \bigwedge_{w \in W_{\neg \alpha, \Phi}} \neg Lw \text{ if } \neg \alpha \text{ is a propositionally consistent objective formula.}$$

The axiom is easily seen to be sound since it merely expresses that $N\alpha$ holds at $W$ just in case $W$ contains all worlds that satisfy $\neg \alpha$. Note that this property depends only on the fact that $L$ and $N$ are defined with respect to complementary sets of worlds and, hence, also holds in the case of infinite $\Phi$. However, it is only in the finite case that we can express this axiomatically. Completeness is also very easy to establish. Levesque showed that in his system, even without $A5$, every formula is provably equivalent to one without nested modalities. With $A5_{\Phi}$, we then obtain an equivalent formula that does not mention $N$. In other words, given a formula consistent with respect to $AX_{\Phi}$, a satisfying model can be constructed with the usual technique for $K45$ alone.

**Theorem 2.7** $AX_{\Phi}$ is sound and complete for the language $ONL(\Phi)$ with respect to Levesque’s semantics, if $\Phi$ is finite.

### 3 The Canonical-Model Approach

How do we extend our intuitions about only knowing to the multi-agent case? First we extend the language $ONL(\Phi)$ to the case of many agents. That is, we now consider a language $ONL_n(\Phi)$, which is just like $ONL$ except that there are modalities $L_i$ and $N_i$ for each agent $i$, $1 \leq i \leq n$, for some fixed $n$. In the remainder of the paper, we omit the $\Phi$, just writing $ONL$ and $ONL_n$, since the set of primitive propositions does not play a significant role. By analogy with the single-agent case, we call a formula basic if it does not mention any of the operators $N_i$ ($i = 1, \ldots, n$) and $i$-subjective if it is a Boolean combination of formulas of the form $L_i\varphi$ and $N_i\varphi$. What should be the analogue of an objective formula? It clearly is more than just a propositional formula. From agent 1’s point of view, a formula like $L_2p$ or even $L_2L_1p$ is just as “objective” as a propositional formula. We define a formula to be $i$-objective if it is a Boolean combination of primitive propositions and formulas of the form $L_j\varphi$ and $N_j\varphi$.

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5 This was also the situation for the logic considered in [4]. In that paper, a simple axiomatization was provided for the case where $\Phi$ was infinite; for each finite $\Phi$, an extra axiom was needed (that depended on $\Phi$).
$N_j \varphi$, $j \neq i$, where $\varphi$ is arbitrary. Thus, $q \land N_2 L_1 p$ is 1-objective, but $L_1 p$ and $q \land L_1 p$ are not. The $i$-objective formulas true at a world can be thought of as characterizing what is true apart from agent $i$’s subjective knowledge of the world.

The standard model here is to have a *Kripke structure* with worlds and accessibility relations that describe what worlds the agents consider possible in each world. Formally, a (Kripke) structure or model is a tuple $M = (W, \pi, \mathcal{K}_1, \ldots, \mathcal{K}_n)$, where $W$ is a set of worlds, $\pi$ associates with each world a truth assignment to the primitive propositions, and $\mathcal{K}_i$ is agent $i$’s accessibility relation. Given such a Kripke structure $M$, let $\mathcal{K}_i^M(w) = \{ w' : (w, w') \in \mathcal{K}_i \}$ $\mathcal{K}_i^M(w)$ is the set of worlds that agent $i$ considers possible at $w$ in structure $M$. As usual, we define

$$(M, w) \models L_i \alpha \text{ if } (M, w') \models \alpha \text{ for all } w' \in \mathcal{K}_i^M(w).$$

We focus on structures where the accessibility relations are Euclidean and transitive, where a relation $R$ on $W$ is Euclidean if $(u, v) \in R$ and $(u, w) \in R$ implies that $(v, w) \in R$, and $R$ is transitive if $(u, v) \in R$ and $(v, w) \in R$ implies that $(u, w) \in R$. We call such structures K45n-structures. It is well known that these assumptions are precisely what is required to get belief to obey the K45 axioms (generalized to $n$ agents). We say that a formula consistent with these axioms is K45n-consistent. An infinite set of formulas is said to be K45n-consistent if the conjunction of the formulas in every one of its finite subsets is K45n-consistent.

Now the question is how to define the modal operator $N_i$. The problem in the multi-agent case is that we can no longer identify a possible world with a truth assignment. In the single-agent case, knowing the set of truth assignments that the agent considers possible completely determines his knowledge. This is no longer true in the multi-agent case. Somehow we must take the accessibility relations into account. A general semantics for an $N$-like operator was first given by Humberstone and later by Ben-David and Gafni. In this approach, the semantics of $N_i$ is given as follows:

$$(M, w) \models N_i \alpha \text{ if } (M, w') \models \alpha \text{ for all } w' \in W - \mathcal{K}_i^M(w).$$

The problem with this definition is that it misses out on the intuition that when evaluating $N_i \alpha$, we keep the set of worlds that agent $i$ considers possible fixed. If $w' \in W - \mathcal{K}_i^M(w)$, there is certainly no reason to believe that $\mathcal{K}_i^M(w) = \mathcal{K}_i^M(w')$.

One approach to solving this problem is as follows: If $w$ and $w'$ are two worlds in $M$, we write $w \equiv_i w'$ if $\mathcal{K}_i^M(w) = \mathcal{K}_i^M(w')$, i.e., if $w$ and $w'$ agree on the possible worlds according to agent $i$. We then define

$$(M, w) \models N_i \alpha \text{ if } (M, w') \models \alpha \text{ for all } w' \text{ such that } w' \in W - \mathcal{K}_i^M(w) \text{ and } w \equiv_i w'.$$

While this definition does capture the first of Levesque’s properties, it does not capture the second. To see the problem, suppose we have only one agent and a structure $M$ with only one possible world $w$. Suppose that $(w, w) \in \mathcal{K}_1^M$ and $p$ is true at $w$. Then it is easy to see that $(M, w) \models L_1 p \land N_1 p$, contradicting axiom A5. The problem is that since the structure has only one world and it is in $\mathcal{K}_1^M(w)$,

\footnote{Note that here $W$ denotes the set of all worlds of the particular model $M$, not just the (epistemically) possible ones as in Levesque’s logic.}

\footnote{We use the superscript $M$ since we shall later need to talk about the $\mathcal{K}_i$ relations in more than one model at the same time.}
there are no worlds in $W - K^M_i(w)$. Thus, $N_1 p$ is vacuously true. Intuitively, there
just aren’t enough “impossible” worlds in this case; the set of conceivable worlds is
not independent of the model. To deal with this problem, we focus attention on one
particular model, the canonical model, which intuitively has “enough” worlds. Its
worlds consist of all the maximal consistent subsets of basic formulas. (Recall that
maximal consistent sets were defined in the proof of Theorem 2.3.) Thus, in some
sense, the canonical model has as many worlds as possible.

**Definition 3.1** The canonical model (for K45n) $M^e = (W^e, \pi^e, K^1_i, \ldots, K^e_i)$ is
defined as follows:

- $W^e = \{ w \mid w$ is a maximal consistent set of basic formulas with respect to K45\n
- for all primitive propositions $p$ and $w \in W^e$, $\pi(w)(p) = \text{true}$ iff $p \in w$

- $(w, w') \in K^e_i$ iff $w/L_i \subseteq w'$, where $w/L_i = \{ \alpha \mid L_i \alpha \in w \}$.

Validity in the canonical-model approach is defined with respect to the canonical
model only. More precisely, a formula $\alpha$ is said to be valid in the canonical-model
approach, denoted $|=^e \alpha$, iff $M^e|\alpha$, that is, if for all worlds $w$ in the canonical model
we have $(M^e, w)|\alpha$.

We clearly cannot use the canonical model in a practical way. It can be shown
that it has uncountably many worlds. Each of its worlds is characterized by an infinite
set of formulas, so cannot be described easily. Moreover, in general, both $K^e_i(w)$ and
$W^e - K^e_i(w)$ are infinite, so we cannot compute whether $L_i \varphi$ or $N_i \varphi$ holds at a given
world. Thus, our interest in the canonical model is mainly to understand whether it
gives reasonable semantics to the $N_i$ operator.

We start by arguing that, for an appropriate notion of “possibility” and “conceiv-
ability”, this semantics satisfies the first two of Levesque’s properties. What then is
a conceivable world? Intuitively, it is an objective state of affairs from agent $i$’s point
of view, which does not include $i$’s beliefs. In the single-agent case, this is simply a
truth assignment. In the multi-agent case, things are more complicated, since beliefs
of other agents are also part of $i$’s objective world. One way of characterizing a state
of affairs from $i$’s point of view is by the set of $i$-objective formulas that are true at a
particular world. For technical reasons, in this section we restrict even further to the
$i$-objective basic formulas—that is, those formulas that do not mention any of the
modal operators $N_j$, $j = 1, \ldots, n$—that are true. If we assume that the basic formulas
determine all the other formulas, which can be shown to be true in the single-agent
case, and under this semantics for the multi-agent case, then it is arguably reasonable
to restrict to basic formulas. However, as we shall see in Section 3, it is not clear that
this restriction is appropriate, although we make it for now.

**Definition 3.2** Given a situation $(M, w)$, let $ob_i(M, w)$ consist of all the $i$-objective
basic formulas that are true at $(M, w)$. Let $Obj_i(M, w) = \{ ob_i(M, w') \mid w' \in K^M_i(w) \}$, and let $subj_i(M, w) = \{ \text{basic } L_i \alpha \mid (M, w)|=L_i \alpha \} \cup \{ \text{basic } -L_i \alpha \mid (M, w)|\neq L_i \alpha \}$.

We take $ob_i(M, w)$ to be $i$’s state at $(M, w)$. Notice that $ob_i(M, w)$ is a maximal
consistent set of $i$-objective basic formulas. For ease of exposition, we say $i$-set from
now on rather than “maximal set of $i$-objective basic formulas”. Thus, the set of

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conceivable states for agent $i$ is the set of all $i$-sets. Notice that the set of conceivable states is independent of the model. It is easy to show that this is a generalization of the single-agent case, since in the single-agent case the $i$-objective basic formulas are just the propositional formulas, and an $i$-set can be identified with a truth assignment.

$\text{Obj}_i(M, w)$ is the set of $i$-sets that agent $i$ considers possible in situation $(M, w)$; $\text{subj}_i(M, w)$ characterizes $i$’s basic beliefs in $(M, w)$. Notice that if $\alpha$ is an $i$-objective basic formula, then $L_i\alpha \in \text{subj}_i(M, w)$ iff $\alpha$ is in every $i$-set in $\text{Obj}_i(M, w)$.

With these definitions, we can show that the first two of Levesque’s properties hold in the canonical model. The first property says that at all worlds $w'$ considered in evaluating a formula of the form $N_i \varphi$ at a world $w$, the set of possible states—that is, the set $\{ \text{obj}_i(M^c, w'') \mid w'' \notin K_i^c(w') \}$—is the same for all $w' \in K_i^c(w)$. This is easy to see, since the only worlds $w'$ we consider are those such that $K_i^c(w') = K_i^c(w)$. The second property says that the union of the set of states associated with the worlds used in computing $N_i \varphi$ at $w$ and the set of states associated with the worlds used in computing $N_i \varphi$ at $w$ should consist of all conceivable states. To show this, we must show that for every world $w$ in the canonical model, the set $\{ \text{obj}_i(M^c, w') \mid w' \approx_i w \}$ consists of all $i$-sets.

To prove this, we need two preliminary lemmas.

**Lemma 3.3** Let $w$ and $w'$ be worlds in $M^c$. Then $w \approx_i w'$ iff agent $i$ has the same basic beliefs at $w$ and $w'$, that is, $\text{subj}_i(M^c, w) = \text{subj}_i(M^c, w')$.

**Proof** The “only if” direction is immediate because $w$ and $w'$ are assumed to have the same $K_i$-accessible worlds. To prove the “if” direction, suppose that $\text{subj}_i(M^c, w) = \text{subj}_i(M^c, w')$ but $w \not\approx_i w'$. Without loss of generality, there is a world $w^* \in K_i^c(w) - K_i^c(w')$. By the definition of the canonical model, there must be a basic formula $L_i \alpha \in w'$ such that $\alpha \not\in w^*$. By assumption, $L_i \alpha \in w$, contradicting the assumption that $w^* \in K_i^c(w)$.

**Lemma 3.4** Suppose $\Gamma$ consists only of $i$-objective basic formulas, $\Sigma$ consists only of $i$-subjective basic formulas, and $\Gamma$ and $\Sigma$ are both $K45_n$-consistent. Then $\Gamma \cup \Sigma$ is $K45_n$-consistent.

**Proof** This follows immediately from part (c) of Proposition 4.2 below.

We can now prove that the set of conceivable states for agent $i$ is the same at all worlds of the canonical model. This follows from the following result.

**Theorem 3.5** Let $w \in W^c$. Then for every $i$-set $\Gamma$ there is exactly one world $w^*$ such that $\text{obj}_i(M^c, w^*) = \Gamma$ and $w \approx_i w^*$.

**Proof** Let $\Sigma = \text{subj}_i(M^c, w)$. Since $\Gamma$ consists of $i$-objective basic formulas only, $\Sigma$ consists of $i$-subjective formulas, and $\Gamma$ and $\Sigma$ are both $K45_n$-consistent, by Lemma 3.4, $\Gamma \cup \Sigma$ is $K45_n$-consistent. Let $w^*$ be a maximal consistent set that contains $\Gamma \cup \Sigma$. Since $w$ and $w^*$ agree on $\Sigma$, $w \approx_i w^*$ by Lemma 3.3. The uniqueness of $w^*$ follows by a simple induction argument.
What about the third property? This says that every subset of \( i \)-sets arises as the set of \( i \)-sets associated with the worlds that \( i \) considers possible in some situation; that is, for every set \( S \) of \( i \)-sets, there should be some situation \((M^c, w)\) such that \( S = \text{Obj}_i(M^c, w)\). As we now show, this property does not hold in the canonical model.

We do this by showing that the set of \( i \)-sets associated with the worlds considered possible in any situation in the canonical model all have a particular property we call \textit{limit closure}.\footnote{This turns out to be closely related to the limit closure property discussed in \cite{1}; a detailed comparison would take us too far afield here though.}

**Definition 3.6** We say that an \( i \)-set \( \Gamma \) is a \textit{limit} of a set \( S \) of \( i \)-sets if, for every finite subset \( \Delta \) of \( \Gamma \), there is a set \( \Gamma' \subseteq S \) such that \( \Delta \subseteq \Gamma' \). A set \( S \) of \( i \)-sets is \textit{limit closed} if every limit of \( S \) is in \( S \).

**Lemma 3.7** For every world \( w \) in \( M^c \), the set \( \text{Obj}_i(M^c, w) \) is limit closed.

**Proof** Let \( w \) be a world in the canonical model and let \( \Gamma \) be an \( i \)-set which is a limit of \( \text{Obj}_i(M^c, w) \). We want to show that \( \Gamma \in \text{Obj}_i(M^c, w) \). Let \( \Sigma = \{ \text{basic } \beta \mid L_i\beta \in w \} \). We claim that \( \Gamma \cup \Sigma \) is K45\(_n\)-consistent. For suppose not. Then there must be a finite subset \( \Delta \subseteq \Gamma \) such that \( \Delta \cup \Sigma \) is inconsistent. Since \( \Gamma \) is a limit of \( \text{Obj}_i(M^c, w) \), there must be some world \( w' \) in \( \text{Obj}_i(M^c, w) \) such that \( (M^c, w') \models \Delta \). By construction of the canonical model, since \( w' \in \mathcal{K}^*_i(w) \), we must have that \( (M^c, w') \models \Sigma \). Thus \( \Delta \cup \Sigma \) is consistent, contradicting our assumption.

Since \( \Gamma \cup \Sigma \) is consistent, there is a world \( w^* \) in the canonical model such that \( (M^c, w^*) \models \Gamma \cup \Sigma \). Clearly \( \Gamma = \text{Obj}_i(M^c, w^*) \). Moreover, by construction, we must have \( w^* \in \mathcal{K}^*_i(w) \). Thus, \( \Gamma \in \text{Obj}_i(M^c, w) \), as desired.

Since there are clearly sets of \( i \)-sets that are not limit closed, it follows that this semantics does not satisfy the third property. One consequence of this is a result already proved in \cite{12}, which we reprove here, using an approach that will be useful for later results.

**Proposition 3.8** \cite{12} If \( p \in \Phi \) and \( i \neq j \), then \( \models^c \lnot O_i \lnot O_j p \).

**Proof** We proceed by contradiction. Our goal is to show that if \( (M^c, w) \models O_i \lnot O_j p \), then the set \( \text{Obj}_i(M^c, w) \) must contain a set that includes \( O_j p \), for otherwise it would not be limit closed. It follows that there is some world \( v \in \mathcal{K}^*_i(w) \) such that \( (M^c, v) \models O_j p \), contradicting the assumption that \( (M^c, w) \models L_i \lnot O_j p \).

We first need a definition and a lemma. We say that a basic formula \( \psi \) is \( (K45)\)-\textit{independent} of a basic formula \( \varphi \) if neither \( \models_{\text{K45}_n} \varphi \Rightarrow \psi \) nor \( \models_{\text{K45}_n} \varphi \Rightarrow \lnot \psi \) hold.

**Lemma 3.9** If \( n \geq 2 \) (i.e., there are at least two agents) and \( \varphi_1, \ldots, \varphi_m \) are consistent basic \( i \)-objective formulas, then there exists a basic \( i \)-objective formula \( \psi \) of the form \( L_{i'} \psi' \) which is independent of each of \( \varphi_1, \ldots, \varphi_m \).

**Proof** Define the \textit{depth} of a basic formula \( \varphi \), denoted \( d(\varphi) \), inductively:
Suppose that φ₁, . . . , φₘ are i-objective formulas such that \( \max(d(φ₁, . . . , d(φₘ))) = K \). Let \( p \) be an arbitrary primitive proposition, and suppose \( j \neq i \). (Such a \( j \) exists, since we are assuming \( n \geq 2 \).) Let \( ψ \) be the formula \( (L_j L_i)^{K+1}p \), where by \( (L_j L_i)^{K+1} \) we mean \( K + 1 \) occurrences of \( L_j L_i \). Standard model theoretic arguments show that \( ψ \) is independent of \( φ₁, . . . , φₘ \). Very briefly: By results of [9], we know that \( φ_j \) is satisfiable in a treelike structure of depth at most \( d(φₘ) \), for \( i = 1, . . . , m \). It is easy to see that this can be extended to two structures, one of which satisfies \( ψ \), and the other of which satisfies \( ¬ψ \). Hence, \( ψ \) is independent of \( φᵢ \).

Continuing with the proof of Proposition 3.8, suppose by way of contradiction that \( (M^c, w) \models O_j ¬O_j p \). Let \( \overline{w} \) be a world such that \( (M^c, \overline{w}) \models O_j p \) and let \( Γ = obj_j(M^c, \overline{w}) \). We claim that \( Γ \) is a limit of \( Obj_j(M^c, w) \). To see this, consider any finite subset \( Δ \) of \( Γ \). Let \( ψ \) be an i-objective basic formula of the form \( L_j ψ' \) which is independent both of the conjunction of the formulas in \( Δ \) and of \( p \). The existence of such a formula follows from Lemma 3.4. Let \( Σ = subj_j(M^c, w) \). By Lemma 3.4, \( Σ ∪ Δ \cup \{L_j ψ'\} \) is consistent. Thus, there is some world \( w'' \in W^c \) such that \( (M^c, w'') \models Σ \cup Δ \cup \{L_j ψ'\} \). By Lemma 3.4 again, there is some world \( w''' \) satisfying \( p \land ¬L_j ψ' \) such that \( w''' \approx w'' \). Since \( (M^c, w') \models L_j ψ' \), we cannot have \( w''' \in K^c_j(w') \). It follows that \( (M^c, w') \models ¬N_j ¬p \), and hence \( (M^c, w') \models ¬O_j p \). Moreover, since \( w' \) and \( w \) agree on all \( i \)-subjective formulas, the canonical model construction guarantees that \( w' \approx_i w \). Since \( (M^c, w) \models O_j ¬O_j p \), \( (M^c, w') \models ¬O_j p \), and \( w' \approx_i w \), we must have that \( w' \in K^c_j(w) \). Thus, \( obj_j(M^c, w') \subset Obj_j(M^c, w) \). Moreover, by construction, \( Δ ⊂ obj_j(M^c, w') \). Since \( Δ \) was chosen arbitrarily, it follows that \( Γ \) is a limit of \( Obj_j(M^c, w) \). By Lemma 3.7, \( Γ \subset Obj_j(M^c, w) \). Thus, there is some world \( v \in K^c_j(w) \) such that \( obj_j(M^c, v) = Γ \). It is a simple property of the canonical-model approach that two worlds that agree on all basic beliefs of an agent also agree on what the agent only believes. Hence, since \( \overline{w} \) and \( v \) agree on \( j \)'s basic beliefs, it follows that \( (M^c, v) \models O_j p \), contradicting the assumption that \( (M^c, w) \models O_i ¬O_j p \).

It may seem unreasonable that \( ¬O_i ¬O_j p \) should be valid in the canonical-model approach. Why should it be impossible for \( i \) to know only that \( j \) does not only know \( p? \) After all, \( j \) can (truthfully) tell \( i \) that it is not the case that all he (\( j \)) knows is \( p \). We return to this issue in Sections 4 and 5. For now, we focus on a proof theory for this semantics.

### 3.1 A Proof Theory

We now consider an axiomatization for the language. The following axiomatization is exactly like Levesque’s except that axiom A5 now requires K45ₙ-consistency instead of merely propositional consistency. For ease of exposition, we use the same names for the axioms as we did in the single-agent case with a subscript \( n \) to emphasize that we are looking at the multi-agent version.
Axioms:

A1. Axioms of propositional logic.
A2. \( L_i(\alpha \Rightarrow \beta) \Rightarrow (L_i\alpha \Rightarrow L_i\beta) \).
A3. \( N_i(\alpha \Rightarrow \beta) \Rightarrow (N_i\alpha \Rightarrow N_i\beta) \).
A4. \( \sigma \Rightarrow L_i\sigma \land N_i\sigma \) if \( \sigma \) is an \( i \)-subjective formula.
A5. \( N_i\alpha \Rightarrow \neg L_i\alpha \) if \( \neg \alpha \) is a K45\(_n\)-consistent \( i \)-objective basic formula.

Inference Rules:

MP. From \( \alpha \) and \( \alpha \Rightarrow \beta \) infer \( \beta \).
Nec. From \( \alpha \) infer \( L_i\alpha \) and \( N_i\alpha \).

Notice that A5 assumes that \( \alpha \) ranges only over basic \( i \)-objective formulas. We need this restriction in order to appeal to satisfiability in the existing logic K45\(_n\).

To get a more general version of A5, that applies to arbitrary formulas, we will need to appeal to consistency within the logic that the axioms are meant to characterize. We return to this issue in Section 5. It is not hard to show that these axioms are sound.

Theorem 3.10. For all \( \alpha \) in \( ONL_n \), if \( \vdash \alpha \) then \( \models^c \alpha \).

Proof. The proof proceeds by the usual induction on the length of a derivation. Here we show only the soundness of A5\(_n\). Suppose \( \alpha \) is a basic \( i \)-objective formula such that \( \neg \alpha \) is K45\(_n\)-consistent. Thus, there is an \( i \)-set containing \( \neg \alpha \). By Theorem 3.3, it follows that for each world \( w \in W^c \), there is a world \( w' \approx_i w \) such that \( (M^c, w') \models \neg \alpha \). If \( w' \in K^c_i(w) \), it follows that \( (M^c, w) \models \neg L_i\alpha \). If \( w' \notin K^c_i(w) \), then \( (M^c, w) \models \neg N_i\alpha \).

Thus, \( (M^c, w) \models \neg L_i\alpha \lor \neg N_i\alpha \); equivalently, \( (M^c, w) \models N_i\alpha \Rightarrow \neg L_i\alpha \). It follows that \( \models N_i\alpha \Rightarrow \neg L_i\alpha \).

We show in Section 5 that this axiomatization is incomplete. In fact, the formula \( \neg O_i \neg O_j p \) is not provable. Intuitively, part of the problem here is that A5\(_n\) is restricted to basic formulas. For completeness, we would need an analogue of A5\(_n\) for arbitrary formulas. However, we obtain completeness for a restricted language, which we call \( ONL^c_n \). Roughly, the restriction amounts to limiting what an agent can only know. In particular, only knowing can only be applied to basic formulas.

Definition 3.11. \( ONL^c_n \) consists of all formulas \( \alpha \) in \( ONL_n \) such that, in \( \alpha \), no \( N_j \) may occur within the scope of an \( N_i \) or \( L_i \) for \( i \neq j \).

For example, \( N_i L_i \neg N_i p \) and \( N_i (L_j p \lor N_i \neg p) \) are in \( ONL^c_n \), and \( N_i N_j p \) and \( N_i L_j N_i p \) are not, for distinct \( i \) and \( j \). Note that formulas such as \( O_i \neg O_j p \) cannot be expressed in \( ONL^c_n \).

To prove completeness for the sublanguage \( ONL^c_n \), we need four preliminary lemmas. The first describes a normal form for formulas. Having such a normal form greatly simplifies the completeness proof.

Note that this peculiar axiom schema is recursive since satisfiability in propositional K45\(_n\) is decidable [8].
**Lemma 3.12** Every formula $\alpha$ in $\mathcal{OL}_n$ is provably equivalent to a disjunction of formulas of the following form:

$$
\sigma \land L_1\varphi_{10} \land \neg L_1\varphi_{11} \land \ldots \land \neg L_1\varphi_{m1} \land \ldots \land L_n\varphi_{n0} \land \neg L_n\varphi_{n1} \land \ldots \land \neg L_n\varphi_{nm} \land N_1\psi_{10} \land \neg N_1\psi_{11} \land \ldots \land \neg N_1\psi_{k1} \land \ldots \land N_n\psi_{n0} \land \neg N_n\psi_{n1} \land \ldots \land \neg N_n\psi_{nk},
$$

where $\sigma$ is a propositional formula and $\varphi_{ij}$ and $\psi_{ij}$ are all $i$-objective formulas. Moreover, if $\alpha$ in $\mathcal{OL}_n$, we can assume that $\varphi_{ij}$ and $\psi_{ij}$ are $i$-objective basic formulas.

**Proof** We proceed by induction on the structure of $\varphi$. The only nontrivial cases are if $\varphi$ is of the form $L_i\varphi'$ or $N_i\varphi'$. If $\varphi$ is of the form $L_i\varphi'$, then, since $\varphi \in \mathcal{OL}_n$, $N_j$ does not appear in $\varphi'$ for $j \neq i$. We use the inductive hypothesis to get $\varphi'$ into the normal form described in the lemma. Notice that $N_j$ does not appear in the normal form for $j \neq i$. We now use the the following equivalences to get $L_i\varphi'$ into the normal form:

- $L_i(\psi \land \psi') \iff (L_i\psi \land L_i\psi')$
- $L_i(\psi \lor L_i\psi') \iff (L_i\psi \lor L_i\psi')$
- $L_i(\psi \lor \neg L_i\psi') \iff (L_i\psi \lor \neg L_i\psi')$
- $L_iL_i\psi \iff L_i\psi$
- $(-L_i\text{false} \land L_i\neg L_i\psi) \iff -L_i\psi$
- $L_iN_i\psi \iff N_i\psi$
- $L_i\neg N_i\psi \iff \neg N_i\psi$.

The first five of these equivalences are standard $K45_n$ properties; the last two are instances of axiom $A4_n$. Similar arguments work in the case that $\varphi$ is of the form $N_i\varphi'$. We leave the straightforward details to the reader.

The next two lemmas give us some basic facts about the satisfiability and validity of formulas in $\mathcal{OL}_n$.

**Lemma 3.13** If $S_j$ is a set of consistent $j$-sets, $j = 1, \ldots, n$, and $\sigma$ is a consistent propositional formula, then there is a $K45_n$ situation $(M, w)$ such that $(M, w) \models \sigma$ and $\text{Obj}_j(M, w) = S_j$.

**Proof** This follows immediately from part (b) of Proposition 12 below.

**Lemma 3.14** If $\varphi$ and $\psi$ are $i$-objective basic formulas such that $L_i\varphi \land N_i\psi$ is consistent, then $\varphi \lor \psi$ is valid.

**Proof** Suppose that $\neg \varphi \land \neg \psi$ is consistent. Then, by Axiom $A5_n$, $N_i(\varphi \lor \psi) \Rightarrow \neg L_i(\varphi \lor \psi)$ is provable. It follows that $N_i\psi \Rightarrow \neg L_i\varphi$ is provable, contradicting the consistency of $L_i\varphi \land N_i\psi$. 

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The last lemma gives us a sharper condition on when \( w' \notin K_i^c(w) \). This condition will prove useful in the completeness proof.

**Lemma 3.15** If \( w, w' \) are worlds in the canonical model such that \( w \approx_i w' \) and \( w' \notin K_i^c(w) \), then there is an \( i \)-objective basic formula \( \varphi \) such that \( L_i \varphi \in w \) and \( \varphi \notin w' \).

**Proof** By the construction of the canonical model, we know that if \( w' \notin K_i^c(w) \), then there is some basic formula \( \varphi \) such that \( L_i \varphi \in w \) and \( \varphi \notin w' \). From Lemma 3.12, it follows that we can assume without loss of generality that \( \varphi \) is in the normal form described by that lemma. Let \( A \) consist of all subformulas of \( \varphi \) that are of the form \( L_i \psi \) and do not appear in the scope of any other modal operator. Let \( \varphi_A \) be \( \bigwedge_{\psi \in A \cap w} \psi \land \bigwedge_{\psi \in A \cap \neg \psi} \neg \psi \). It is easy to see that \( \varphi_A \in w \) (since each of its conjuncts is). Since \( w \approx_i w' \), it follows that \( \varphi_A \in w' \). Let \( \varphi' \) be the result of replacing each subformula \( L_i \psi \) of \( \varphi \) that is in \( A \) by either \( \text{true} \) or \( \text{false} \), depending on whether \( L_i \psi \in w \). By construction, \( \varphi' \) is \( i \)-objective. It is easy to see that \( \varphi_A \Rightarrow (\varphi \leftrightarrow \varphi') \) is provable. It follows that \( \varphi \notin w' \). It also follows that \( L_i \varphi_A \Rightarrow (L_i \varphi \leftrightarrow L_i \varphi') \) is provable. Since \( \varphi_A \) is an \( i \)-subjective formula, \( \varphi_A \Rightarrow L_i \varphi_A \) is provable. Hence, \( L_i \varphi_A \in w \). Since \( L_i \varphi \in w \), it follows that \( L_i \varphi' \in w \). This gives us the desired result.

We are finally ready to prove the completeness result.

**Theorem 3.16** For all \( \alpha \in \mathcal{ONL}_n^- \), if \( \models^c \alpha \) then \( \models \alpha \).

**Proof** As usual, it suffices to show that if the formula \( \alpha \in \mathcal{ONL}_n^- \) is consistent, then it is satisfiable in the canonical model. Without loss of generality, we can assume that \( \alpha \) is in the normal form described in Lemma 3.12:

\[
\sigma \land L_1 \varphi_{10} \land \neg L_1 \varphi_{11} \land \ldots \land \neg L_1 \varphi_{1m_1} \land \ldots \land L_n \varphi_{n0} \land \neg L_n \varphi_{n1} \land \ldots \land \neg L_n \varphi_{nm_n} \land N_1 \psi_{10} \land \neg N_1 \psi_{11} \land \ldots \land \neg N_1 \psi_{1k_1} \land \ldots \land N_n \psi_{n0} \land \neg N_n \psi_{n1} \land \ldots \land \neg N_n \psi_{nk_n}.
\]

Moreover, since \( \alpha \in \mathcal{ONL}_n^- \), we can assume that \( \varphi_{ij} \) and \( \psi_{ij} \) are \( i \)-objective basic formulas. Let \( A_i \) consist of all the consistent formulas of the form \( \varphi_{10} \land \psi_{10} \land \neg \varphi_{ij} \) or \( \varphi_{10} \land \psi_{10} \land \neg \psi_{ij}, \ j \geq 1 \). Let \( \xi_i \) be a formula that is independent of all the formulas in \( A_i \); such a formula exists by Lemma 3.13. Let \( S_i \) consist of all \( i \)-sets containing \( \varphi_{30} \land (\neg \psi_{30} \lor (\psi_{30} \land \xi)) \). By Lemma 3.13, there is a K45n structure \( (M, w) \) such that \( Ob_j(M, w) = S_i, \ i = 1, \ldots, n, \) and \( (M, w) \models \sigma \). Thus, there must be a world \( w^* \) in the canonical model such that \( w^* = \{ \text{basic \ } \varphi' \mid (M, w) \models \varphi' \} \). We claim that \( (M^*, w^*) \models \alpha \).

To see this, let \( \alpha' \) be the formula \( \sigma \land L_1 \varphi_{10} \land \neg L_1 \varphi_{11} \land \ldots \land \neg L_1 \varphi_{1m_1} \land \ldots \land L_n \varphi_{n0} \land \neg L_n \varphi_{n1} \land \ldots \land \neg L_n \varphi_{nm_n} \). We first show that \( (M, w) \models \alpha' \). By construction, we have that \( (M, w) \models \sigma \). Furthermore, by definition, each world \( w' \in K_i^c(w) \) satisfies \( \varphi_{10} \), so we have that \( (M, w) \models L_i \varphi_{10} \). Since \( L_i \varphi_{10} \land \neg L_i \varphi_{ij} \) is consistent for each \( j \geq 1 \), it must be the case that \( \varphi_{10} \land \neg \varphi_{ij} \) is consistent. Thus, one of \( \varphi_{10} \land \neg \psi_{10} \land \neg \varphi_{ij} \) or \( \varphi_{10} \land \psi_{10} \land \neg \varphi_{ij} \) is consistent. If the latter is consistent, then by the choice of \( \xi \), \( \varphi_{10} \land \psi_{10} \land \xi \land \neg \varphi_{ij} \) must be consistent as well. Since \( S_i \) consists of all \( i \)-sets containing \( \varphi_{10} \land (\neg \psi_{10} \lor (\psi_{10} \land \xi)) \), it follows that there must be an \( i \)-set in \( S_i \) containing \( \neg \varphi_{ij} \).
It follows that \((M, w) \models \neg L_i \varphi_{ij}, \) for \(j \geq 1.\) Thus, we have shown that \((M, w) \models \alpha'.\)

Since \((M, w)\) and \((M^c, w^*)\) agree on basic formulas, it follows that \((M^c, w^*) \models \alpha'.\)

Next, we show that \((M^c, w^*) \models N_i \psi_{i0} \land \ldots \land N_n \psi_{n0}.\) To this end, suppose that \(w^* \models \psi_i \) and \(w' \notin K^c_i(w^*).\) By Lemma 3.13, there must be some \(i\)-objective basic formula \(\varphi'\) such that \(L_i \varphi' \in w^*\) and \(\neg \varphi' \in w'.\) Since \(L_i \varphi' \in w^*\), it follows that \((M, w) \models L_i \varphi',\) and hence \(\varphi'\) is in every \(i\)-set in \(S_i.\) It follows that \(obj_i(w') \notin S_i.\) Now, one of the following four formulas must be in \(obj_i(w'):\) (1) \(\psi_{i0} \land \psi_{i0}\), (2) \(\psi_{i0} \land \neg \psi_{i0},\) (3) \(\neg \psi_{i0} \land \psi_{i0},\) (4) \(\neg \psi_{i0} \land \neg \psi_{i0}.\) Since \(L_i \varphi_0 \land N_i \psi_{i0}\) is consistent, it cannot be (4), by Lemma 3.14. It cannot be (2), for otherwise \(w'\) would be in \(S_i.\) Thus, it must be (1) or (3), so \(\psi_{i0} \in \text{obj}_i(w').\) Since this is true for all \(w'\) such that \(w' \models \psi_{ij}\) and \(w' \notin K^c_i(w^*),\) it follows that \((M^c, w^*) \models N_i \psi_{i0},\) for \(i = 1, \ldots, n.\)

Finally, we must show that \((M^c, w^*) \models \neg N_i \psi_{ij},\) for \(i = 1, \ldots, n\) and \(j = 1, \ldots, k_i.\) Clearly \(\psi_{i0} \land \neg \psi_{ij}\) is consistent, for otherwise \(N_i \psi_{i0} \land \neg N_i \psi_{ij}\) would be inconsistent. Thus, at least one of (1) \(\psi_{i0} \land \neg \psi_{ij} \land \neg \psi_{i0}\) or (2) \(\psi_{i0} \land \neg \psi_{ij} \land \psi_{i0}\) is consistent. In case (2), by choice of \(\xi_i,\) the formula \(\psi_{i0} \land \neg \psi_{ij} \land \psi_{i0} \land \neg \xi_i\) is consistent. Let \(\beta\) be \(\psi_{i0} \land \neg \psi_{ij} \land \neg \psi_{i0}\) if it is consistent, and \(\psi_{i0} \land \neg \psi_{ij} \land \psi_{i0} \land \neg \xi_i\) otherwise. By construction, \(\beta\) is consistent. By Lemma 3.14, there is a situation \((M', v)\) such that \(\text{sub}_{ij}(M', v) = \text{sub}_{ij}(M^c, w^*)\) and \((M', v) \models \beta.\) There is a world \(w'\) in the canonical model which agrees with \((M', v)\) on the basic formulas. By construction, we have \(w' \models \psi_{ij}.\) Moreover, since \((M^c, w) \models L_i (\varphi_{i0} \land \neg \psi_{i0} \lor (\psi_{i0} \land \xi)))\) it follows that \((M^c, w^*) \models L_i \neg \beta.\) Since \((M^c, w') \models \beta,\) we have that \(w' \notin K^c_i(w^*).\) Moreover, since \((M^c, w') \models \neg \psi_{ij},\) it follows that \((M^c, w^*) \models \neg N_i \psi_{ij},\) as desired. This completes the proof.

### 3.2 Discussion

As we have shown, the canonical-model semantics for \(N_i\) has some attractive features, in particular when restricted to the language \(ONL_n^-\). It is for this sublanguage that we have a nice proof-theoretic characterization. There is some evidence, however, that the semantics may not have the behavior we desire when we move beyond \(ONL_n^-\). For one thing, the formula \(\neg O_i \neg O_j p\) is valid in the canonical model: it is impossible that all \(i\) knows is that it is not the case that all \(j\) knows is \(p.\) While it is certainly consistent for \(\neg O_i \neg O_j p\) to hold, it seems reasonable to have a semantics that allows \(O_i \neg O_j p\) to be hold as well. As we have seen, the validity of \(\neg O_i \neg O_j p\) follows from the fact that the canonical-model semantics does not have the third property of Levesque’s semantics in the single-agent case: not all subsets of conceivable states are possible. In the next section, we discuss a different approach to giving semantics to only knowing—essentially that taken in \([3]\)—that has all three of Levesque’s properties, at least as long as we continue to represent an agent’s objective state of affairs using basic formulas only. The approach agrees with the canonical-model approach on formulas in \(ONL_n^-\), but makes \(O_i \neg O_j p\) satisfiable. Unfortunately, as we shall see, it too suffers from problems.

### 4 The i-Set Approach

In the \(i\)-set approach, we maintain the intuition that the set of conceivable states for each agent \(i\) can be identified with the set of \(i\)-sets. We no longer restrict attention
to the canonical model though; we consider all Kripke structures.

We define a new semantics $\models'$ as follows: all the clauses of $\models$ are identical to the corresponding clauses for $\models$, except that for $N_i$. In this case, we have

$$(M, w) \models' N_i \varphi \iff (M', w') \models' \varphi \text{ for all situations } (M', w') \text{ such that } \text{Obj}_i(M, w) = \text{Obj}_i(M', w') \text{ and } \text{obj}_i(M', w') \notin \text{Obj}_i(M, w).$$

Notice that $\models$ and $\models'$ agree for basic formulas; in general, as we shall see, they differ. We remark that this definition is equivalent to the one given in \[5\], except that there, rather than $i$-sets, $i$-\textit{objective} trees were considered. We did not want to go through the overhead of introducing $i$-objective trees here, since it follows from results in \[5, 6\] that $i$-sets are equivalent to $i$-objective trees: every $i$-set uniquely determines an $i$-objective tree and vice versa.

How well does this approach fare in terms of computing the truth of a formula at a given world. Since we now allow arbitrary structures, not just the canonical model, it seems that for computational reasons, it seems we ought to focus on finite structures. However, when it comes to formulas of the form $\text{Obj}_i(M, w) = \text{Obj}_i(M', w')$ and $\text{obj}_i(M', w') \notin \text{Obj}_i(M, w)$.

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How well does this approach fare in terms of computing the truth of a formula at a given world. Since we now allow arbitrary structures, not just the canonical model, it seems that for computational reasons, it seems we ought to focus on finite structures. However, when it comes to formulas of the form $N_i \alpha$, where $\alpha$ is $i$-objective, satisfiable formula, it can be shown that $(M, w) \models' \neg N_i \alpha$. There are simply too few sets in $\text{Obj}_i(M, w)$ if $M$ is finite to have $\neg \alpha$ hold in all “impossible” situations. This means that to really model interesting situations with only knowing, we must use infinite models, and we are back to the problems discussed in the case of the canonical model. Thus, again we focus on whether this approach gives reasonable semantics to the $N_i$ operator.

Notice that to decide if $N_i \varphi$ holds in $(M, w)$, we consider all situations that agree with $(M, w)$ on the set of possible states, hence this semantics satisfies the first of the three properties we isolated in the single-agent case. It is also clear that the $i$-sets considered in evaluating the truth of $N_i \varphi$ are precisely those not considered in evaluating the truth of $L_i \varphi$: hence we satisfy the second property. Finally, as we now show, for every set $S$ of $i$-sets, there is a situation $(M, w)$ such that $\text{Obj}_i(M, w) = S$. In fact, we prove an even stronger result.

**Definition 4.1** Let $\text{obj}_i^+(M, w)$ consist of all $i$-objective formulas (not necessarily just $i$-objective basic formulas) true at $(M, w)$ (with respect to $\models'$) and let $\text{Obj}_i^+(M, w) = \{ \text{obj}_i^+(M, w') \mid w' \in K_i^M(w) \}$.

**Proposition 4.2** Let $\Gamma$ be a satisfiable set of $i$-objective formulas, let $S_i$ be a set of maximal satisfiable sets of $i$-objective formulas, $i = 1, \ldots, n$, let $\Sigma$ be a satisfiable set of $i$-subjective formulas, and let $\sigma$ be a satisfiable propositional formula. Then

(a) there exists a situation $(M_1, w_1)$ such that $\Gamma \subseteq \text{obj}_i^+(M_1, w_1)$ and $S_i = \text{Obj}_i^+(M_1, w_1)$.

(b) there exists a situation $(M_2, w_2)$ such that $(M_2, w_2) \models \sigma$ and $\text{obj}_i^+(M_2, w_2) = S_j$, $j = 1, \ldots, n$.

(c) there exists a situation $(M_3, w_3)$ such that $(M_3, w_3) \models \Gamma \land \Sigma$.

**Proof** For part (a), we first show that, given an arbitrary situation $(M, w)$, we can construct a situation $(M^*, w^*)$ such that $\text{obj}_i^+(M^*, w^*) = \text{obj}_i^+(M, w)$ and there are
no worlds \( i \)-accessible from \( w^* \). The idea is to have \( M^* \) be the result of adding \( w^* \) to the worlds in \( M \), where \( w^* \) is just like \( w \) except that it has no \( i \)-accessible worlds and \( w^* \) is not accessible from any world. More formally, if \( M = (W, \pi, \mathcal{K}_1, \ldots, \mathcal{K}_n) \), we take \( M^* = (W^*, \pi^*, \mathcal{K}^*_1, \ldots, \mathcal{K}^*_n) \), where \( W^* = W \cup \{w^*\} \), \( \pi^*(w') = \pi(w) \) for \( w' \in W \), \( \pi^*(w^*) = \pi(w) \), \( \mathcal{K}^*_j = \mathcal{K}_j \cup \{w, w' \mid w' \in \mathcal{K}_j(w)\} \) for \( j \neq i \), and \( \mathcal{K}^*_i = \mathcal{K}_i \). It is easy to see that \( \mathcal{K}^*_j \) is Euclidean and transitive. By construction, there are no worlds \( i \)-accessible from \( w^* \) and \( (w', w^*) \notin \mathcal{K}^*_j \) for all \( w' \) and all \( j \). Moreover, if \( \psi \) is an \( i \)-objective formula, we have \( (M^*, w^*) \models \psi \) if \( (M, w) \models \psi \), since for \( j \neq i \), we have \( \mathcal{K}_j(w^*) = \mathcal{K}_j(w) \). In particular, this means that \( \text{obj}^+_i(M^*, w^*) = \text{obj}^+_i(M, w) \).

For each \( \Delta \in S' = S_i \cup \{\Gamma\} \), there is a situation \( (M^{\Delta}, w^{\Delta}) \models \psi \Delta \), where \( M^{\Delta} = (W^{\Delta}, \pi^{\Delta}, \mathcal{K}^{\Delta}_1, \ldots, \mathcal{K}^{\Delta}_n) \). By the argument above, we can assume without loss of generality that there are no worlds \( i \)-accessible from \( w^\Delta \) and \( w^\Delta \) is not accessible from any world. We define \( M_1 = (W, \pi, \mathcal{K}_1, \ldots, \mathcal{K}_n) \) by taking \( W \) to be the union of all the worlds in \( W^\Delta \), \( \Delta \in S' \). (We can assume without loss of generality that these are disjoint sets of worlds.) We define \( \pi \) so that \( \pi|_{W^\Delta} = \pi^\Delta \). We define \( \mathcal{K}_j = \bigcup_{\Delta \in S'} \mathcal{K}^\Delta_j \) for \( j \neq i \), and \( \mathcal{K}_i \) to be the least transitive, Euclidean set containing \( \bigcup_{\Delta \in S'} \mathcal{K}^\Delta_i \cup \{w^\Delta, w^\Delta\} \mid \Delta \in S' \). It is easy to check that \( \text{obj}^+_i(M_1, w^\Delta) = \text{obj}^+_i(M^\Delta, w^\Delta) \) (although this depends on the fact that \( w^\Delta \) is not \( j \)-accessible from any world for \( j \neq i \)). Thus, \( \text{obj}^+_i(M_1, w^\Delta) = S_i \) and \( \text{obj}^+_i(M_1, w^\Delta) \supseteq \Gamma \). Thus, we can take \( w_1 = w^\Delta \), completing the proof of part (a).

To summarize the construction of part (a), we start with an arbitrary situation \( (M, w) \) satisfying \( \Gamma \), convert it to a situation satisfying \( L_i \text{false} \land \Gamma \), essentially by modifying the \( i \)-accessibility relation at \( w \) so that there are no worlds \( i \)-accessible from \( w \) and \( w \) is not accessible from any world, and then again modifying the \( i \)-accessibility relation at \( w \) so that we get a structure \( (M_1, w_1) \) such that \( \text{Obj}^+_i(M_1, w_1) = S_i \). Note that in doing this construction, we did not change the propositional formulas true at \( w \), nor did we change the worlds that were \( j \)-accessible from \( w \) for \( j \neq i \). Thus, starting with a situation that satisfies a propositional formula \( \sigma \), we can repeat this construction for each \( i \) in turn, for \( i = 1, \ldots, n \). The resulting situation is \((M_2, w_2)\), and it clearly has the desired properties. This proves part (b).

For part (c), suppose \( (M', w') \models \Sigma \); let \( \text{Obj}^+_i(M', w') = S_i \). By part (a), there is a situation \( (M_3, w_3) \) such that \( \text{Obj}^+_i(M_3, w_3) = S_i \) and \( (M_3, w_3) \models \Gamma \). Since the set of subjective formulas true at a situation \( (M, w) \) is completely determined by \( \text{Obj}^+_i(M, w) \), and \( \text{Obj}^+_i(M', w') = \text{Obj}^+_i(M_3, w_3) \), it follows that \( (M_3, w_3) \models \Sigma \) as well.

How does this semantics compare to the canonical model semantics? First of all, it is easy to see that the axioms are sound. We write \( \models' \varphi \) if \( (M, w) \models' \varphi \) for every situation \( (M, w) \). Then we have the following result.

**Theorem 4.3** For all \( \alpha \in \mathcal{ONL}_n \), if \( \models \alpha \) then \( \models' \alpha \).

**Proof** As usual, the proof is by induction on the length of a derivation. All that needs to be done is to show that all the axioms are sound. Again, this is straightforward. The proof in the case of \( \mathbf{A5}_n \) proceeds just as that in the proof of Theorem 3.10, using the fact that this semantics satisfies Levesque’s second property.

Moreover, we again get completeness for the sublanguage \( \mathcal{ONL}^-_n \).
Theorem 4.4 For all $\alpha \in \mathcal{OL}_n^\sim$, $\models \alpha$ if and only if $\models' \alpha$.

Proof As usual, it suffices to show that if $\alpha$ is consistent with the axioms, then $\alpha$ is satisfiable under the $\models'$ semantics. From Theorem 3.16, we know that $\alpha$ is satisfiable in the canonical model under the $\models$ semantics. Thus, it suffices to show that for all formulas $\alpha \in \mathcal{OL}_n^\sim$, we have $(M^\omega, w) \models \alpha$ if and only if $(M^\omega, w) \models' \alpha$. By Lemma 3.12, it suffices to consider formulas $\alpha$ in normal form. We proceed by induction on the structure of formulas. The only nontrivial case obtains if $\alpha$ is of the form $N_i^\alpha'$. Since $\alpha$ is in normal form, we can assume that $\alpha'$ is basic. Suppose $(M^\omega, w) \models' N_i^\alpha'$. To show that $(M^\omega, w) \models N_i^\alpha'$, we must show that if $w' \approx_i w$ and $w' \notin K_i^\alpha(w)$, then $(M^\omega, w') \models \alpha$. By definition, if $w' \approx_i w$, then $\text{Obj}_i(M^\omega, w') = \text{Obj}_i(M^\omega, w)$. Moreover, we must have $\text{obj}_j(M^\omega, w') \notin \text{obj}_j(M^\omega, w)$, for otherwise we would have $w' \in K_i^\alpha(w)$. Hence, we must have $(M^\omega, w') \models' \alpha'$. By the induction hypothesis, we have $(M^\omega, w') \models \alpha'$. Thus, $(M^\omega, w) \models N_i^\alpha'$, as desired.

For the converse, suppose that $(M^\omega, w) \models N_i^\alpha'$. We want to show that $(M^\omega, w) \models' N_i^\alpha'$. Suppose that $(M', w')$ is such that $\text{Obj}_i(M', w') = \text{Obj}_i(M^\omega, w)$ and $\text{obj}_j(M', w') \notin \text{obj}_j(M^\omega, w)$. We must show that $(M', w') \models' \alpha$. It is easy to see that for every situation $(M, w)$ and basic formula $\varphi$, we have that $(M, w) \models L_i^\varphi$ if and only if $(M, w) \models' L_i^\varphi$. Thus, it follows that $\text{subj}_i(M', w') = \text{subj}_i(M^\omega, w)$. There must be a world $w''$ in $M^\omega$ such that $(M^\omega, w'')$ agrees with $(M', w')$ on all basic formulas according to the $\models$ semantics. Since $\text{subj}_i(M^\omega, w'') = \text{subj}_i(M^\omega, w)$, it follows from Lemma 3.3 that $w'' \approx w'$. Since $\text{obj}_j(M', w') \notin \text{obj}_j(M^\omega, w)$ and $\text{obj}_j(M', w') = \text{obj}_j(M^\omega, w')$, it follows that $w'' \notin K_i^\alpha(w)$. Since $(M^\omega, w) \models N_i^\alpha'$, we must have that $(M^\omega, w'') \models \alpha'$. And since $(M^\omega, w'')$ and $(M', w')$ agree on basic formulas, it follows that $(M', w') \models \alpha'$. Finally, since $\models$ and $\models'$ agree for basic formulas, we have $(M', w') \models' \alpha'$. This completes the proof that $(M, w) \models N_i^\alpha'$.

Although our axiomatization is complete for $\mathcal{OL}_n^\sim$, as we now show, it is not complete for the full language, for neither $\models$ nor $\models'$. Since the axiomatization is sound for both $\models$ and $\models'$, to prove incompleteness, it suffices to provide a formula which is satisfiable with respect to $\models'$ and not $\models$, and another formula which is satisfiable with respect to $\models$ and not $\models'$. As is shown in Proposition 4.3, $O_i \neg O_j p$ is satisfiable with respect to $\models'$ and (by Proposition 3.8) not with respect to $\models$. On the other hand, it is easy to see that $L_i \neg \text{false} \wedge N_i \neg O_i \neg O_j p$ is satisfiable with respect to $\models$ (in fact, it is equivalent to $L_j \text{false}$); as shown in Proposition 4.6, it is not satisfiable with respect to $\models'$.

Proposition 4.5 $O_i \neg O_j p$ is satisfiable under the $\models'$ semantics.

Proof Let $S = \{ \text{obj}_j(M, w) \mid (M, w) \models' \neg O_j p \}$. By Proposition 4.2, there is a situation $(M^\omega, w^*)$ such that $\text{Obj}_j(M^\omega, w^*) = S$. We claim that $(M^\omega, w^*) \models' O_i \neg O_j p$. Clearly $(M^\omega, w^*) \models L_i \neg O_j p$, since $\neg O_j p$ is true at all worlds $i$-accessible from $w^*$. To see that $(M^\omega, w^*) \models N_i \neg O_j p$, suppose that $\text{Obj}_i(M, w) = \text{Obj}_i(M^\omega, w^*)$ and $\text{obj}_j(M, w) \notin \text{obj}_j(M^\omega, w^*)$. We want to show that $(M, w) \models O_i \neg O_j p$. Suppose that $(M, w) \models' \neg O_j p$. By definition, $\text{obj}_j(M, w) \in S$, so there is some world $w' \in K_i^M(w^*)$ such that $\text{obj}_j(M^\omega, w') = \text{obj}_j(M, w)$. In particular, this means that $\text{obj}_j(M^\omega, w') = \text{obj}_j(M, w)$. But this contradicts the assumption that $\text{obj}_j(M, w) \notin \text{obj}_j(M^\omega, w^*)$. Thus, $(M, w) \models O_j p$ as desired, and $(M^\omega, w^*) \models O_i \neg O_j p$. 

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Proposition 4.6 There is a formula $\beta$ such that $\models' \beta$ but $\neg \beta$ is satisfiable under the $\models$ semantics.

Proof We first show that if $\varphi$ is an $i$-objective formula that is satisfiable under the $\models'$ semantics, then $\models' L_i \false \models \neg N_i \neg \varphi$. For suppose that $\varphi$ is satisfiable in a situation $(M, w)$. By Proposition 4.4, there is a situation $(M^*, w^*)$ such that $\Obj_i^+(M^*, w^*) = \Obj_i^+(M, w)$ and $\Obj_i^+(M^*, w^*) = \emptyset$. This means that $(M^*, w^*) \models' \varphi \land L_i \false$. Now let $(M', w')$ be any situation satisfying $L_i \false$. Then $\Obj_j(M', w') = \Obj_j(M^*, w^*) = \emptyset$, and $\Obj_j(M^*, w^*) \notin \Obj_j(M', w')$. It follows that $(M', w') \models' \neg N_i \neg \varphi$. Thus, we have shown that $\models' L_i \false \models \neg N_i \neg \varphi$. Since, as we showed in Proposition 4.5, the formula $O_j \neg O_i p$ is satisfiable, this means that $\models' L_i \false \models \neg N_i \neg O_j \neg O_i p$. On the other hand, since $O_j \neg O_i p$ is not satisfiable with respect to $\models$, as we showed in Proposition 4.8, neither is $\neg N_i \neg O_j \neg O_i p$, and hence $L_i \false \models \neg N_i \neg O_j \neg O_i p$ is not valid under the $\models$ semantics. Indeed, $L_i \false \wedge N_i \neg O_j \neg O_i p$ is equivalent to $L_i \false$ under the $\models$ semantics.

We can now show that our axiom system is incomplete for the full language with respect to both the $\models$ and $\models'$ semantics.

Theorem 4.7 There exist formulas $\alpha$ and $\beta$ in $\ONL_n$ such that $\not\models \alpha$ and $\models \alpha$, and $\not\models' \beta$ and $\models' \beta$.

Proof By Propositions 4.8 and 4.5, we have that $\models \neg O_j \neg O_i p$, but $\not\models' \neg O_j \neg O_i p$. Since $\models$ sound with respect to $\models'$, we cannot have $\models \neg O_j \neg O_i p$ (for otherwise we would have $\models' \neg O_j \neg O_i p$). Thus, we can take $\alpha$ to be $\neg O_j \neg O_i p$. A similar argument shows we can take $\beta$ to be $L_i \false \models \neg N_i \neg O_j \neg O_i p$.

The fact that neither $\models$ nor $\models'$ is complete with respect to the axiomatization described earlier is not necessarily bad. We may be able to find a natural complete axiomatization. However, as we suggested above, the fact that $\neg O_j \neg O_i p$ is valid under the $\models$ semantics suggests that this semantics does not quite satisfy our intuitions with regards to only-knowing for formulas in $\ONL_n - \ONL_n^\neg$. As we now show, $\models'$ also has its problems. We might hope that if $\varphi$ is a satisfiable $i$-objective formula, then $N_i \varphi \models L_i \varphi$ would be valid under the $\models'$ semantics. Unfortunately, it is not.

Proposition 4.8 The formula $N_i \neg O_j p \land L_i \neg O_j p$ is satisfiable under the $\models'$ semantics.

Proof First we show that for any situation $(M, w)$ that satisfies $O_j p$, there exists another situation $(M', w')$ such that $(M, w)$ and $(M', w')$ agree on all basic formulas, but $(M', w') \models' \neg O_j p$. We can construct $(M', w')$ as follows: Choose a particular set $\Gamma \in \Obj_j(M, w)$. It easily follows from Proposition 4.4 that there is a situation $(M', w')$ such that $\Obj_j(M', w') = \Obj_j(M, w) - \{\Gamma\}$ and $\Obj_j(M', w') = \Obj_j(M, w)$. We now show that for any basic formula $\varphi$, we have $(M, w) \models \varphi$ iff $(M', w') \models' \varphi$. If $\varphi$ is a $j$-objective formula, this is immediate from the construction. Thus, it suffices to deal with the case that $\varphi$ is of the form $L_j \varphi'$. By Lemma 3.12 we can assume
without loss of generality that $\varphi'$ is $j$-objective. Suppose that $\varphi'$ is a consistent $j$-objective formula. In this case, it is almost immediate from the definitions that if $(M, w) \models L_j \varphi'$ then $(M', w') \models L_j \varphi'$. For the converse, suppose that $(M, w) \models \neg L_j \varphi'$. Then there is some world $w'' \in \mathcal{K}^M_j(w)$ such that $(M, w'') \models \neg \varphi'$. Since $(M, w) \models L_j \varphi'$, we have that $(M, w'') \models L_j \varphi'$. Let $\varphi''$ be a $j$-objective basic formula that is independent of $p \wedge \neg \varphi'$. Let $\varphi''$ be $\varphi' \wedge p \wedge \neg \psi$ if $\psi \in \Gamma$, and $\varphi' \wedge p \wedge \psi$ otherwise. Since $\psi$ is independent of $p \wedge \neg \varphi'$, it follows that $\varphi''$ is consistent. Let $\Delta$ be any $j$-set containing $\varphi''$. It must be the case that $\Delta \in \operatorname{Obj}_j(M, w)$, for if not, let $(M^*, w^*)$ be a situation such that $\operatorname{Obj}_j(M^*, w^*) = \operatorname{Obj}_j(M, w)$ and $\operatorname{Obj}_j(M^*, w^*) = \Delta$ (such a situation exists by Proposition 1.2). Then $(M^*, w^*) \models p$, contradicting the assumption that $(M, w) \models N_j \neg p$. By construction, $\Delta \notin \Gamma$. Thus, there is some world $v \in \mathcal{K}^M_j(w')$ such that $\operatorname{obj}_j(M', v) = \Delta$. It follows that $(M', v) \models \neg \varphi'$, so $(M', w') \models \neg L_j \varphi'$. Thus, $(M', w')$ agrees with $(M, w)$ on all basic formulas. However, since $\Gamma \notin \operatorname{Obj}_j(M, w)$, it follows that $(M', w') \models \neg N_j \neg p$, and hence that $(M', w') \models \neg O_j p$.

Let $S = \{ \operatorname{obj}_j^+(M, w) \mid (M, w) \models \neg O_j p \}$. By Proposition 1.2, there is a situation $(M^*, w^*)$ such that $\operatorname{Obj}_j^+(M^*, w^*) = S$. Clearly $(M^*, w^*) \models L_i \neg O_j p$. We now show that $(M^*, w^*) \models N_i \neg O_j p$ as well. For suppose that $(M, w)$ is a situation such that $\operatorname{obj}_j(M, w) = \operatorname{obj}_j(M^*, w^*)$ and $\operatorname{obj}_j(M, w) \notin \operatorname{obj}_j(M^*, w^*)$. Moreover, suppose, by way of contradiction, that $(M, w) \models O_j p$. By the arguments above, it follows that there is a situation $(M', w')$ such that $(M', w') \models \neg O_j p$ and $(M, w)$ and $(M', w')$ agree on all basic formulas. By construction, $\operatorname{obj}_j^+(M', w') \in S = \operatorname{Obj}_j^+(M^*, w^*)$, so $\operatorname{obj}_j(M', w') \in \operatorname{obj}_j(M^*, w^*)$. Since $\operatorname{obj}_j(M, w) = \operatorname{obj}_j(M', w')$, we must also have $\operatorname{obj}_j(M, w) \in \operatorname{obj}_j(M^*, w^*)$, contradicting the choice of $(M, w)$. Thus, $(M, w) \models \neg O_j p$, as desired, and so $(M^*, w^*) \models L_i \neg O_j p \land N_i \neg O_j p$.

### 4.1 Discussion

Proposition 1.8 shows that although the $i$-set semantics has the three properties we claimed were appropriate, $N_i$ and $L_i$ still do not always interact in what seems to be the appropriate way. Intuitively, the problem here is that there is more to $i$’s view of a world than just the $i$-objective basic formulas that are true there. We should really identify $i$’s view of a situation $(M, w)$ with the set of all $i$-objective formulas that are true there. In the canonical-model approach, the $i$-objective basic formulas that are true at a world can be shown to determine all the $i$-objective formulas that are true at that world. This is not true at all situations under the $i$-set approach.

Indeed, it is no longer true that the $i$-set approach has the second of the three properties once we take $i$’s view of $(M, w)$ to be $\operatorname{obj}_j^+(M, w)$. For consider the situation $(M^*, w^*)$ constructed in the proof of Proposition 1.8. As the proof of that lemma shows, $\{ \operatorname{obj}_j^+(M^*, w^*) \mid w \in \mathcal{K}^M_j(w^*) \} \cup \{ \operatorname{obj}_j^+(M', w') \mid \operatorname{obj}_j(M', w') \notin \operatorname{Obj}_j(M^*, w^*) \}$ does not include all maximal sets of $i$-objective formulas. In particular, it does not include those maximal sets that satisfy $O_j p$.

To summarize: while the $i$-set approach arguably has enough worlds, it suffers from the fact that the full complement of worlds is not always taken into account for $L_i$ and $N_i$, as the above example shows. While the canonical model approach does not run into this problem, it suffers from a perhaps more basic deficiency: there just are not enough worlds to begin with. For example, there is no world where $O_i O_j p$ is
true.

We consider a different approach in the next section that attempts to deal with both problems.

5 What Properties Should Only Knowing Have?

Up to now, we have provided two semantics for only knowing. While both have properties we view as desirable, they also have properties that seem somewhat undesirable. This leads to an obvious question: What properties should only knowing have? Roughly speaking, we would like to have the multi-agent version of Levesque’s axioms, and no more. Of course, the problem here is axiom $A5_n$. It is not so clear what the multi-agent version of that should be. The problem is one of circularity: We would like to be able to say that $N_i \varphi \Rightarrow \neg L_i \varphi$ should hold for any consistent $i$-objective formula. The problem is that in order to say what the consistent formulas are, we need to define the axiom system. In particular, we have to make precise what this axiom should be.

To deal with this problem, we extend the language so that we can explicitly talk about satisfiability and validity in the language. We add a modal operator $Val$ to the language. The formula $Val(\varphi)$ should be read “$\varphi$ is valid”. Of course, its dual $Sat(\varphi)$, defined as $\neg Val(\neg \varphi)$, should be read “$\varphi$ is satisfiable”. With this operator in the language, we can replace $A5_n$ with

$A5'_n$. $Sat(\neg \alpha) \Rightarrow (N_i \alpha \Rightarrow \neg L_i \alpha)$ if $\alpha$ is $i$-objective.

In addition, we have the following rules for reasoning about validity and satisfiability:

V1. $(Val(\varphi) \land Val(\varphi \Rightarrow \psi)) \Rightarrow Val(\psi)$.

V2. $Sat(\varphi)$, if $\varphi$ is a satisfiable propositional formula.\[10\]

V3. $(Sat(\alpha \land \beta_1) \land \ldots \land Sat(\alpha \land \beta_k) \land Sat(\gamma \land \delta_1) \land \ldots \land Sat(\gamma \land \delta_m) \land Val(\alpha \lor \gamma)) \Rightarrow
Sat(L_i \alpha \land \neg L_i \gamma \land \beta_1 \land \ldots \land \neg L_i \gamma \land \beta_k \land \neg N_i \gamma \land \beta_1 \land \ldots \land \neg N_i \gamma \land \beta_k \land \neg \delta_1 \land \ldots \land \neg \delta_m)$, if $\alpha, \beta_1, \ldots, \beta_k, \gamma, \delta_1, \ldots, \delta_m$ are $i$-objective formulas.

V4. $(Sat(\alpha) \land Sat(\beta)) \Rightarrow Sat(\alpha \land \beta)$ if $\alpha$ is $i$-objective and $\beta$ is $i$-subjective.

NecV. From $\varphi$ infer $Val(\varphi)$.

Axiom V1 and the rule NecV make Val what is called a normal modal operator. In fact, it can be shown to satisfy all the axioms of S5. The interesting clauses are clearly V2–V4, which capture the intuitive properties of validity and satisfiability.

If we restrict to basic formulas, then V3 simplifies to $(Sat(\alpha \land \beta_1) \land \ldots \land Sat(\alpha \land \beta_k)) \Rightarrow
Sat(L_i \alpha \land \neg L_i \beta_1 \land \ldots \land \neg L_i \beta_k)$ (we can take $\gamma, \delta_1, \ldots, \delta_m$ to be $true$ to get this).

The soundness of this axiom (interpreting Sat as satisfiability) follows using much the same arguments as those in the proof of Proposition 3.2. The soundness of V4 if we restrict to basic formulas follows from Lemma 3.4. More interestingly, it follows from

\[10\]We can replace this by the simpler $Sat(p'_1 \land \ldots \land p'_k)$, where $p'_i$ is a literal—either a primitive proposition or its negation—and $p'_1 \land \ldots \land p'_k$ is consistent.
the completeness proof given below that these axioms completely characterize satisfiability in K45n; together with the K45n axioms, they provide a sound and complete language for the language augmented with the Val operator.

Let AX’ consist of the axioms for ONL given earlier together with V1–V4 and NecV, except that A5n is replaced by A5’n. AX’ is the axiom system that provides what we claim is the desired generalization of Levesque’s axioms to the multi-agent case. In particular, A5’n is the appropriate generalization of A5. The question is, of course, whether there is a semantics for which this is a complete axiomatization. We now provide one, in the spirit of the canonical-model construction of Section 3, except that, in the spirit of the extended situations of Section 2, we do not attempt to make the set of worlds used for evaluating L and N disjoint.

Let ONLn+ be the extension of ONLn to include the modal operator Val. For the remainder of this section, when we say “consistent”, we mean consistent with the axiom system AX’. We define the extended canonical model, denoted Mn+ = (Wn, πn, Kn, ..., Kn, N1n, ..., Nnn), as follows:

- Wn consists of the maximal consistent sets of formulas in ONLn+.
- For all primitive propositions p and w ∈ Wn, we have πn(w)(p) = true iff p ∈ w.
- (w, w’) ∈ Kn iff w/Ln, w’.
- (w, w’) ∈ Ninn iff w/Nn, w’.

In this canonical model, the semantics for Li and Ni is defined in terms of the Kn and Ninn relations, respectively:

(Mn, w) |= Liα if (Mn, w’) |= α for all w’ such that (w, w’) ∈ Kn.
(Mn, w) |= Nniα if (Mn, w’) |= α for all w’ such that (w, w’) ∈ Ninn.

We define the Val operator so that it corresponds to validity in the extended canonical model:

(Mn, w) |= Val(α) if (Mn, w’) |= α for all worlds w’ in Mn.

We now want to show that every formula in a maximal consistent set is satisfied at a world in the extended canonical model. To do this, we need one preliminary result, showing that Val and Sat really correspond to provability and consistency in this framework.

**Proposition 5.1** For every formula φ ∈ ONLn, if φ is provable then so is Val(φ), while if φ is not provable, then ¬Val(φ) is provable.

**Proof** By NecV, it is clear that if φ is provable, so is Val(φ). Thus, it remains to show that if φ is not provable, then ¬Val(φ) is. Using V1, it is easy to see that ¬Val(φ) is provably equivalent to Sat(¬φ), so it suffices to show that if φ is not provable—i.e., if ¬φ is consistent—then Sat(¬φ) is provable. We prove by induction on φ that if φ is consistent, then Sat(φ) is provable.

If φ is propositional, the result is immediate from V2. For the general case, we first use Lemma 3.12 to restrict attention to formulas in the canonical form specified by the lemma. Using standard modal reasoning (V1 and NecV) it is easy to show
that ⊢ Sat(φ ∨ ψ) ⇔ (Sat(φ) ∨ Sat(ψ)). Thus, it suffices to restrict attention to a conjunction in the form specified by the lemma. It is easy to see that if the conjunction is consistent, then each conjunct must be consistent. Using V4, it is easy to see that we can restrict attention to i-subjective formulas. By applying Lemma 3.12, we can assume without loss of generality that we are dealing with a consistent formula ϕ of the form L_iα ∧ ¬L_i¬β_1 ∧ ... ∧ ¬L_i¬β_k ∧ N_iγ ∧ ¬N_i¬δ_1 ∧ ... ∧ ¬N_i¬δ_m, where α, β_1, ..., β_k, γ, δ_1, ..., δ_m are all i-objective. We can also assume that each of α ∧ β_i, i = 1, ..., k and γ ∧ δ_j, j = 1, ..., m are consistent, for otherwise we could easily show that ϕ is not consistent.

Finally, we can show that α ∨ γ must be provable, for if not, by applying A5′, we can again show that ϕ is not consistent. We now apply the induction hypothesis to prove the result.

**Corollary 5.2** Each formula in ONL^+_n is provably equivalent to a formula in ONL_n.

**Proof** We proceed by induction on the structure of formulas. The only nontrivial case is for formulas of the form Val(ϕ). By the induction hypothesis, ϕ is provably equivalent to a formula ϕ' ∈ ONL_n. By straightforward modal reasoning using V1 and Necv, we can show that Val(ϕ) is provably equivalent to Val(ϕ'). By Proposition 5.1, Val(ϕ') is provably equivalent to either true or false, depending on whether ϕ' is provable.

Using standard modal logic techniques, we can now prove the following result.

**Theorem 5.3** M_e is a K45_n structure (that is, K_e and N_e are Euclidean and transitive). Moreover, for each world w ∈ W_e, we have (M_e, w) |= α iff α ∈ w.

**Proof** We leave it to the reader to check that the definition of K_e guarantees that M_e is a K45_n structure. Given Corollary 5.2, which allows us to restrict attention to α ∈ ONL_n, the proof that (M_e, w) |= α iff α ∈ w is completely straightforward and follows the same lines as the usual proofs dealing with canonical models (see, for example, [2, 9]).

We say that α is e-valid, denoted |=_e α, if M_e |= α, that is, if (M_e, w) |= α for all worlds w ∈ W_e. The following result is immediate from Theorem 5.3.

**Corollary 5.4** |=_e α iff AX' ⊢ α.

Thus, AX' is a sound and complete axiomatization of ONL^+_n with respect to the |=_e semantics.

While AX' is sufficient for our purposes, it comes at the expense of having to explicitly axiomatize validity as part of the logic itself. While we view the ability to axiomatize validity and satisfiability within the logic as a feature in our approach, it is reasonable to ask whether it is really necessary. One of the anonymous referees suggested to us the following interesting variant, which may avoid this complication, although at the expense of an infinite number of axiom schemas.

First we define an infinite sequence of languages ONL^+_n for k = 0, 1, 2, ...:
Theorem 5.6

\[ \mathcal{ONL}_n^{k+1} = \{ \alpha \mid \alpha \text{ is a Boolean combination of formulas of } \mathcal{ONL}_n^k \text{ together with} \]

formulas of the form \( L_i \alpha \) or \( N_i \alpha \) for \( \alpha \in \mathcal{ONL}_n^k \) \]

Roughly, each language adds another level of nestings of only knowing with varying agent indices. For example, \( \mathcal{ONL}_n^{k+1} \) contains the formula \( O_{\alpha_0} O_{\alpha_1} \ldots O_{\alpha_{i+1}} p \), where \( i_j \neq i_{j+1} \), something that cannot be expressed in \( \mathcal{ONL}_n^k \).

Let AX* consist of the the axioms \( A1_n - A4_n \) as before together with the following set of axioms

\[ A5_n^{k+1}. N_i \alpha \Rightarrow \neg L_i \alpha, \text{ where } \alpha \text{ is an } i\text{-objective } \mathcal{ONL}_n^k \text{ formula which is} \]

consistent with respect to \( A1_n - A4_n, A5_n^1, A5_n^2, \ldots A5_n^k \).

It is not hard to show that the axioms are sound with respect to the semantics. Whether they are also complete remains an open problem.

Apart from the question of axiomatization, how does the \( \models \) semantics compare to our earlier two? Clearly, they differ. It is easy to see that the formula \( O_i \neg O_j p \), which was not satisfiable under \( \models \), is satisfiable under \( \models \). In addition, the formula \( N_i \neg O_j p \land L_i \neg O_j p \), which is satisfiable under \( \models \), is not satisfiable under \( \models \). In both cases, it seems that the behavior of \( \models \) is more appropriate. On the other hand, all three semantics agree in the case where our intuitions are strongest, \( \mathcal{ONL}_n^- \). Since the axiom system AX characterizes how our earlier two semantics deal with \( \mathcal{ONL}_n^- \), this is shown by the following result.

**Theorem 5.5** If \( \varphi \in \mathcal{ONL}_n^- \), then \( AX \vdash \varphi \) iff \( AX' \vdash \varphi \).

**Proof** It is easy to see that each axiom of AX is sound in AX'. It follows that \( AX \vdash \varphi \) implies \( AX' \vdash \varphi \). For the converse, it suffices to show that if \( \varphi \in \mathcal{ONL}_n^- \) is consistent with AX, then it is also consistent with AX', i.e., that Sat(\( \varphi \)) holds. We show this by induction on the structure of \( \varphi \), much in the same way we proved Proposition 5.12. We can assume without loss of generality that \( \varphi \) is a conjunction in the normal form described Lemma 3.12. It is easy to see that if we can deal with the case that \( \varphi \) is an \( i \)-subjective formula, then we can deal with arbitrary \( \varphi \) by repeated applications of \( V4 \) followed by an application of \( V2 \). Thus, suppose that \( \varphi \) is an \( i \)-subjective formula which is consistent with AX. We can assume that \( \varphi \) is of the form \( L_i \alpha \land \neg L_i \beta_1 \land \ldots \land \neg L_i \beta_k \land N_i \gamma \land \neg N_i \delta_1 \land \ldots \land \neg N_i \delta_m \). We must have that \( \alpha \land \beta_j \) is consistent for \( j = 1, \ldots, k \), and that \( \gamma \land \delta_l \) is AX-consistent for \( l = 1, \ldots, m \), for otherwise \( \varphi \) would not be AX-consistent. Similarly, by Lemma 3.14, we must have that \( \alpha \lor \gamma \) is K45n-provable, otherwise \( \varphi \) would not be AX-consistent. We can now apply \( V3 \) and the inductive hypothesis to show that \( \alpha \) is AX'-consistent.

Thus, we maintain all the benefits of the earlier semantics with this approach. Moreover, while it is just as intractable to compute whether \( (M^e, w) \models \alpha \) for a particular world \( w \) in the extended canonical model as it was in all our other approaches, we can show that the validity problem for this logic is no harder than that for K45n alone. It is PSPACE-complete.

**Theorem 5.6** The problem of deciding if \( AX' \vdash \varphi \) is PSPACE-complete.
Proof PSPACE hardness follows from the PSPACE hardness of K45\textsubscript{n} \cite{9}. We sketch the proof of the upper bound. First of all, observe that it suffices to deal with the case that \(\phi\) is in ONL\textsubscript{n}, since we can then apply the arguments of Corollary 5.2 to remove all occurrences of Val from inside out. We consider the dual problem of consistency. Thus, we want to check if Sat(\(\alpha\)) holds. The first step is to convert \(\alpha\) to the normal form of Lemma 3.12. Observe that \(\alpha\) is consistent iff at least one of the disjuncts is consistent. Although the conversion to normal form may result in exponentially many disjuncts, each one is no longer than \(\alpha\). Thus, we deal with them one by one, without ever writing down the full disjunction. It suffices to show that we can decide if each disjunct is consistent in polynomial space, since we can then erase all the work and start over for the next disjunct (with a little space necessary for bookkeeping). We now proceed much as in the proof of Proposition 5.1. By applying V4 repeatedly and then V2 (as in the previous theorem), it suffices to deal with \(i\)-subjective formulas. We then apply V3 to get simpler formulas, and repeat the procedure. We remark that this gives another PSPACE decision procedure for K45\textsubscript{n}, quite different from that presented in \cite{9}.

To what extent do the three properties we have been focusing on hold under the \(|=e\) semantics? Suppose we take the conceivable states from \(i\)'s point of view to be the maximal consistent sets of \(i\)-objective formulas with respect to AX\textsubscript{i}, or equivalently, the set of \(i\)-objective formulas true at some world in \(M^e\). Let \(\text{obf}_i^e(M^e, w)\) consist of all the \(i\)-objective formulas true at world \(w\) in the extended canonical model (under the \(|=e\) semantics) and let \(\text{Obf}_i^e(M^e, w) = \{\text{obf}_i^e(M^e, w') | w' \in K_i^e(w)\}\). It is easy to see that the first two properties we isolated hold under this interpretation of conceivable state. However, it is quite possible that the “possible states” at a world \((M^e, w)\), that is, \(\text{Obf}_i^e(M^e, w)\), and the “impossible states”, that is, \(\{\text{obf}_i^e(M^e, w') | w' \approx_i w, w \notin K_i^e(w)\}\) are not disjoint.

Interestingly, this semantics does not satisfy the third property we isolated. Not all subsets of conceivable states arise as the set of possible states at some situation \((M^e, w)\). A proof analogous to that of Lemma 3.7 shows that \(\text{Obf}_i^e(M, w)\) is always limit closed. In the canonical model approach, limit closure prevents an agent from considering certain desirable sets of states. Now this is no longer the case, despite limit closure. Roughly speaking, we avoid problems by having in a precise sense “enough” possibilities. More precisely, given any consistent \(i\)-objective formula \(\alpha\), it is possible for agent \(i\) to only know \(\alpha\) by virtue of considering all maximal sets of \(i\)-objective formulas which contain \(\alpha\). Thus, as we suggested earlier, the third property we isolated in the beginning turns out to be somewhat too strong—it is sufficient but not necessary once we allow for enough possibilities.

6 Multi-Agent Nonmonotonic Reasoning

In this section, we demonstrate that the logic developed in Section 5 captures multi-agent autoepistemic reasoning in a reasonable way. We do this in two ways. First we show by example that the logic can be used to derive some reasonable nonmonotonic inferences in a multi-agent context. We then show that the logic can be used to

\footnote{The result in \cite{4} is proved only for KD45\textsubscript{n}, but the same proof applies to K45\textsubscript{n}.}
extend the definitions of stable sets and stable expansions originally developed for single agent autoepistemic logic to the multi-agent setting.

6.1 Formal Derivations of Nonmonotonic Inferences

In this section, we provide two examples of how the logic can be used for nonmonotonic reasoning.

Example 6.1 Let \( p \) be agent \( i \)'s secret and suppose \( i \) makes the following assumption: unless I know that \( j \) knows my secret assume that \( j \) does not know it. We can prove that if this assumption is all \( i \) believes then he indeed believes that \( j \) does not know his secret. Formally, we can show

\[
\vdash O_i(\neg L_i L_j p \Rightarrow \neg L_j p) \Rightarrow L_i \neg L_j p.
\]

A formal derivation of this theorem can be obtained as follows. Let \( \alpha = \neg L_i L_j p \Rightarrow \neg L_j p \).

The justifications in the following derivation indicate which axioms or previous derivations have been used to derive the current line. PL or K45 indicate that reasoning in either standard propositional logic or K45, which are subsumed by \( AX' \), is used without further analysis.

1. \( O_i \alpha \Rightarrow L_i \alpha \) PL
2. \( O_i \alpha \Rightarrow N_i \neg \alpha \) PL
3. \( (L_i \alpha \land \neg L_i L_j p) \Rightarrow L_i \neg L_j p \) K45
4. \( N_i \neg \alpha \Rightarrow (N_i \neg L_i L_j p \land N_i L_j p) \) K45
5. \( Sat(p) \) V2
6. \( Sat(p) \Rightarrow Sat(\neg L_j p) \) V3
7. \( Sat(\neg L_j p) \) V1, PL
8. \( Sat(\neg L_j p) \Rightarrow (N_i L_j p \Rightarrow \neg L_i L_j p) \) A5'n
9. \( N_i L_j p \Rightarrow \neg L_i L_j p \) PL
10. \( O_i \alpha \Rightarrow \neg L_i L_j p \) 2; 4; 9; PL
11. \( O_i \alpha \Rightarrow L_i \neg L_j p \) 1; 3; 10; PL

To see that \( i \)'s beliefs may evolve nonmonotonically given that \( i \) knows only \( \alpha \), assume that \( i \) finds out that \( j \) has found out about the secret. Then \( i \)'s belief that \( j \) does not believe the secret will be retracted. In fact, \( i \) will believe that \( j \) does believe the secret. Formally, we can show

\[
\vdash O_i(L_j p \land \alpha) \Rightarrow L_i L_j p.
\]

Notice that the logic itself is a regular monotonic logic; the nonmonotonicity of agent \( i \)'s beliefs is hidden within the \( O_i \)-operator.

All the formulas that appear in the proof above are in \( ONL_n \). Thus, we could have used the somewhat simpler proof theory of Section 3.1. To obtain an example where we need the full power of \( AX' \), simply replace \( L_j p \) by \( O_j p \), that is \( i \) now uses the default that unless he knows that \( j \) only knows \( p \), then he assumes that \( j \) does not only know \( p \). In other words, \( i \) (prudently) makes rather cautious assumptions about \( i \)'s epistemic state and assumes that \( i \) usually knows more than just \( p \). The proof is very similar to the one above. The only difference is that we now have to establish that \( Sat(\neg O_j p) \) is provable, which is straightforward.

\[\text{Note that if we replace } L_j p \text{ by } p \text{ we obtain regular single-agent autoepistemic reasoning.}\]
Example 6.2 Now let \( p \) stand for “Tweety flies”. We want to show that if \( j \) knows that all \( i \) knows about Tweety is that by default it flies, then \( j \) knows that \( i \) believes that Tweety flies. As before, we capture the fact that all \( i \) believes is that, by default, Tweety flies, by saying that all \( i \) believes is that, unless \( i \) believes that Tweety does not fly, then Tweety flies. Thus, we want to show

\[ \vdash L_jO_i(\neg L_i\neg p \Rightarrow p) \Rightarrow L_jL_ip. \]

We proceed as follows:
1. \( O_i(\neg L_i\neg p \Rightarrow p) \Rightarrow L_ip \) as above, with \( L_jp \) replaced by \( \neg p \)
2. \( L_j(O_i(\neg L_i\neg p \Rightarrow p) \Rightarrow L_ip) \) \( 1; \text{Nec}_n \)
3. \( L_jO_i(\neg L_i\neg p \Rightarrow p) \Rightarrow L_jL_ip \) \( 2; \text{K45}_n \)

In a sense, \( i \) is able to reason about \( j \)’s ability to reason nonmonotonically essentially by simulating \( j \)’s reasoning pattern.

A situation where \( i \) knows that all \( j \) knows is \( \alpha \) seems hardly attainable in practice, since an agent usually has at best incomplete information about another agent’s beliefs. It would seem much more reasonable if we could say that \( i \) knows that \( \alpha \) is all \( j \) knows about some relevant subject, say Tweety. This issue is dealt with in \( [13] \), where the canonical-model approach is extended to allow statements of the kind that all agent \( i \) knows about \( x \) is \( y \). It is shown that the forms of nonmonotonic reasoning just described, when restricted to \( ON\mathcal{L}_n^- \), go through just as well with the weaker notion of only knowing about.

6.2 i-Stable Sets and i-Stable Expansions

Single-agent autoepistemic logic was developed by Moore \( [15] \) using the concepts of stable sets and stable expansions. Levesque proved that there is a close relationship between stable sets and only-knowing in the single-agent case. Here we prove an analogous relationship for the multi-agent case. We first need to define a multi-agent analogue of stable sets.

In the single-agent case, it is well known that a stable set is a complete set of formulas that agent \( i \) could know in some situation; that is, a set \( S \) is stable if and only if there is a situation \( (W,w) \) such that \( S = \{ \alpha \mid (W,w) |= L\alpha \} \). This is the intuition that we want to extend to the multi-agent setting, where the underlying language is now \( ON\mathcal{L}_n \). First we define logical consequence in the extended canonical model in the usual way: If \( \Gamma \) is a set of formulas, we write \( M^e \models \Gamma \) if \( M^e \models \gamma \) for each formula \( \gamma \in \Gamma \). We say that \( \gamma \) is an \( e \)-consequence of \( \Gamma \), and write \( \Gamma |=^e \gamma \), exactly if \( M^e \models \Gamma \) implies \( M^e \models \gamma \).

Definition 6.3 Let \( \Gamma \) be a set of formulas in \( ON\mathcal{L}_n \). \( \Gamma \) is called i-stable iff

(a) if \( \Gamma |=^e \gamma \) then \( \gamma \in \Gamma \),

(b) if \( \alpha \in \Gamma \) then \( L_i\alpha \in \Gamma \),

(c) if \( \alpha \notin \Gamma \) then \( \neg L_i\alpha \in \Gamma \). \( [13] \)

Regular readers of papers on nonmonotonic logic will no doubt be gratified to see Tweety’s reappearance.
Note that the only difference between $i$-stable sets and the original definition of stable sets is in condition (a), which requires $i$-stable sets to be closed under $e$-consequence instead of tautological consequence (i.e., logical consequence in propositional logic) as in the single-agent case. Using $e$-consequence rather than tautological consequence makes no difference in the single-agent case; in the multi-agent case it does. Intuitively, we want to allow the agents to use $e$-consequence here to capture the intuition that it is common knowledge that all agents are perfect reasoners under the extended canonical model semantics. For example, if agent $i$ believes $\neg L_j p$ for a different agent $j$, then we want him to also believe $N_j \neg L_j p$. To do this, we need to close off under $e$-consequence.

The next theorem shows that $i$-stable sets do indeed satisfy the intuitive requirement. We define an $i$-epistemic state to be a set $\Gamma$ of $\mathcal{ONL}_n$-formulas such that for some situation $(M^e, w)$ in the extended canonical model, $\Gamma = \{ \alpha \in \mathcal{ONL}_n \mid (M^e, w) \models L_i \alpha \}$; in this case, we say that $\Gamma$ is the $i$-epistemic situation corresponding to $(M^e, w)$. For a set of $\mathcal{ONL}_n$-formulas $\Gamma$, let $L = \{ \gamma \mid \gamma \in \mathcal{ONL}_n \text{ and } \gamma \not\in \Gamma \}$, $L_i \Gamma = \{ L_i \gamma \mid \gamma \in \Gamma \}$, and $\neg L_i \Gamma = \{ \neg L_i \gamma \mid \gamma \in \Gamma \}$.

**Theorem 6.4** Let $\Gamma$ be a set of $\mathcal{ONL}_n$-formulas. $\Gamma$ is $i$-stable iff $\Gamma$ is an $i$-epistemic state.

**Proof** It is straightforward to show that every $i$-epistemic state is $i$-stable. To show the converse, let $\Gamma$ be $i$-stable. We need to show that it is also an $i$-epistemic state. Certainly $L_i \Gamma$ is consistent. If $\Gamma$ contains all $\mathcal{ONL}_n$-formulas, that is, if agent $i$ is inconsistent, then let $(M^e, w)$ be a situation where $K_i^e(w) = \emptyset$; such a situation clearly exists. Then $\Gamma$ is the $i$-epistemic situation corresponding to $(M^e, w)$. If $\Gamma$ is a proper subset of the $\mathcal{ONL}_n$-formulas, then $\Gamma$ must be consistent. (If $\Gamma$ were inconsistent, by the first property of stable sets, $\Gamma$ would contain all formulas.) In particular, this means that $p \land \neg p \not\in \Gamma$ for a primitive proposition $p$. The second property of stable sets guarantees that $L_i \Gamma \subseteq \Gamma$, while the third guarantees that $\neg L_i (p \land \neg p) \in \Gamma$. Since $\Gamma$ is consistent, so is $L_i \Gamma \cup \{ \neg L_i (p \land \neg p) \}$. $W^c$ consists of all the maximal consistent sets (with respect to $AX'$); thus, there must be some $w^* \in W^c$ that contains $L_i \Gamma \cup \{ \neg L_i (p \land \neg p) \}$. We claim that $\Gamma$ is the $i$-epistemic state corresponding to $(M^e, w^*)$. Thus, we must show that $\varphi \in \Gamma$ iff $(M^e, w^*) \models L_i \varphi$. To see this, first suppose that $\varphi \in \Gamma$. Thus, $L_i \varphi \in L_i \Gamma$. By construction, $w^*$ contains $L_i \Gamma$. By Theorem 5.3, we have that $(M^e, w^*) \models L_i \varphi$. On the other hand, if $\varphi \not\in \Gamma$, then, since $\Gamma$ is $i$-stable, we have that $\neg L_i \varphi \in \Gamma$. By the previous argument, it follows that $(M^e, w^*) \models L_i \neg L_i \varphi$. From $A4_n$, it follows that $(M^e, w^*) \models \neg L_i \varphi$, and hence $(M^e, w^*) \not\models L_i \varphi$. This proves the claim.

Moore defined the notion of a stable expansion of a set $A$ of formulas in the single-agent case. Intuitively, a stable expansion of $A$ is a stable set containing $A$ all of whose formulas can be justified, given $A$ and the formulas believed in that stable set. Further discussion and justification of the notion of stable expansion can be found in Moore’s paper. Rather than discussing this here, we go directly to our multi-agent generalization of Moore’s notion.

**Definition 6.5** Let $A$ be a set of $\mathcal{ONL}_n$-formulas. $\Gamma$ is called an $i$-stable expansion of $A$ iff $\Gamma = \{ \gamma \mid \gamma \in \mathcal{ONL}_n \mid A \cup L_i \Gamma \cup \neg L_i \Gamma \models^e \gamma \}$.
It is easy to see that an i-stable expansion is an i-stable set. The definition of i-stable expansions looks exactly like Moore’s definition of stable expansions except that we again use e-consequence instead of tautological consequence. As in the case of stable sets, this is necessary to capture the fact that it is common knowledge that all agents can do reasoning under the extended canonical model semantics.

We now generalize a result of Levesque’s [14] (who proved it for the single-agent case), showing that the i-stable expansions of a formula α correspond precisely to the different situations where i only knows α. We first need a lemma.

Lemma 6.6 Let \( (M^e, w) \) be a situation with
\[
Σ = \{ L_i γ | (M^e, w) \models L_i γ \} ∪ \{ ¬L_i γ | (M^e, w) \models ¬L_i γ \}.
\]
For any α, there is an i-objective formula α* such that
(a) \( Σ \models^e α ⇔ α^* \),
(b) \((M^e, w) \models (L_i α ⇔ L_i α^*) ∧ (N_i α ⇔ N_i α^*)\).

**Proof** Given a formula ϕ, we say that a subformula \( L_i ψ \) of ϕ occurs at top level if it is not in the scope of any modal operators. Let α* be the result of replacing each top-level subformula of α of the form \( L_i γ \) (resp., \( N_i γ \)) by \( ℓ \) true if \( Σ \models^e L_i γ \) (resp., \( Σ \models^e N_i γ \)) and by \( ℓ \) false otherwise. Clearly α* is i-objective. Moreover, a trivial argument by induction on the structure of α shows that \( Σ \models α ⇔ α^* \): If α is a primitive proposition then \( α^* = α \); if α is of the form \( α_1 ∧ α_2 \) or \( ¬α' \), then the result follows easily by the induction hypothesis; if α is of the form \( L_j β \) for \( j \neq i \), then \( α = α^* \), since α has no top-level subformulas of the form \( L_i ϕ \); finally, if α is of the form \( L_i β \), then \( α^* \) is either \( ℓ \) true or \( ℓ \) false, depending on whether \( L_i β \) is in Σ. Since either \( L_i β \) or \( ¬L_i β \) must be in Σ, the result is immediate in this case too. Part (b) follows immediately from part (a), since if \( w' \approx_i w \), we must have \((M^e, w') \models Σ\), so \((M^e, w') \models α ⇔ α^*\).

Theorem 6.7 Let \( w \) be a world in the extended canonical model and let Γ be the i-epistemic state corresponding to \( (M^e, w) \). Then, for every \( ONL \) formula α, we have that \((M^e, w) \models O_i α \) iff (a) Γ is an i-stable expansion of \{α\} and (b) \( K_i^e \) and \( N_i^e \) are disjoint.

**Proof** Let \( Σ = L_i Γ ∪ ¬L_i Γ \). To prove the “only if” direction, suppose \((M^e, w) \models O_i α \). The disjointness of \( K_i^e \) and \( N_i^e \) follows immediately from the fact that \((M^e, w) \models L_i α ∧ N_i ¬α \). To prove that Γ is an i-stable expansion of \{α\}, it suffices to show that for all \( ONL \)-formulas β, we have \((M^e, w) \models L_i β \) iff \( \{α\} ∪ Σ \models^e β \).

First suppose that \( \{α\} ∪ Σ \models^e β \). Since \((M^e, w) \models \{O_i α\} \cup Σ \), and every formula in Σ is of the form \( L_i γ \) or \( ¬L_i γ \), it easily follows that \((M^e, w) \models L_i α \) and \((M^e, w) \models ¬L_i γ \). Hence, \((M^e, w') \models α \) and \((M^e, w') \models Σ \) for every \( w' ∈ K_i^e \). It follows that \((M^e, w') \models β \) and, therefore, \((M^e, w) \models L_i β \).

For the converse, suppose that \((M^e, w) \models L_i β \). We want to show that \( \{α\} ∪ Σ \models^e β \). By Lemma 6.6, we can assume without loss of generality that β is i-objective. (For
if not, we can replace β by an i-objective β* such that \( \Sigma \models^e \beta \iff \beta^* \) and \( (M^e, w) \models L_i \beta \iff L_i \beta^* \), prove the result for \( \beta^* \), and conclude that it holds for \( \beta \) as well.) To show that \( \{ \alpha \} \cup \Sigma \models^e \beta \) we must show that for all worlds \( w' \) such that \( (M^e, w') \models \{ \alpha \} \cup \Sigma \), we have \( (M^e, w') \models \beta \). By Lemma 6.6, there is an i-objective formula \( \alpha^* \) such that \( (M^e, w) \models O\alpha \iff O\alpha^* \) and \( \Sigma \models^e \alpha \iff \alpha^* \). Thus, \( (M^e, w) \models N_i \alpha^* \land L_i \beta \). By the arguments of Lemma 3.14 (which apply without change to the extended canonical model semantics), it must be the case that \( \models^e \alpha^* \Rightarrow \beta \). Since \( \Sigma \models^e \alpha \iff \alpha^* \), it follows that \( \{ \alpha \} \cup \Sigma \models^e \beta \). Since \( (M^e, w') \models \{ \alpha \} \cup \Sigma \) by assumption, we have that \( (M^e, w') \models^e \), as desired.

To prove the “if” direction of the theorem, suppose that \( K_i^e(w) \) and \( N_i^e(w) \) are disjoint and that for all \( ONL_n \)-formulas \( \beta \), we have \( (M^e, w) \models L_i \beta \iff \{ \alpha \} \cup \Sigma \models^e \beta \). We need to show that \( (M^e, w) \models O_i \alpha \), that is, \( (M^e, w) \models L_i \alpha \land N_i \lnot \alpha \).

Since \( \{ \alpha \} \cup \Sigma \models^e \alpha \), the fact that \( (M^e, w) \models L_i \alpha \) follows immediately. To prove that \( (M^e, w) \models N_i \lnot \alpha \), let \( w' \in N_i^e(w) \) and assume, to the contrary, that \( (M^e, w') \models \alpha \). Since \( w' \in N_i^e(w) \), it follows that \( \Sigma \subseteq w' \). Hence \( w/L_i \subseteq w' \), from which \( w' \in K_i^e(w) \) follows, contradicting the assumption that \( K_i^e(w) \) and \( N_i^e(w) \) are disjoint.

7 Conclusion

We have provided three semantics for multi-agent only-knowing. All agree on the subset \( ONL_n^e \), but they differ on formulas involving nested \( N_i \)'s. Although a case can be made that the \( \models^e \) semantics comes closest to capturing our intuitions for “knowing at most”, our intuitions beyond \( ONL_n^e \) are not well grounded. It would certainly help to have more compelling semantics corresponding to \( AX' \).

On the other hand, it can be argued that semantics does not play quite as crucial a role when dealing with knowing at most as in other cases. The reason is that the structures we must deal with, in general, have uncountably many worlds. For example, whichever of the three semantics we use, there must be uncountably many worlds \( i \)-accessible from a situation \( (M, w) \) satisfying \( O_i p \), at least one for every \( i \)-set that includes \( p \). To the extent that we are interested in proof theory, the proof theory associated with \( \models^e \), characterized by the axiom system \( AX' \), seems quite natural. The fact that the validity problem is no harder in this setting than that for \( K45_n \) adds further support to its usefulness. Of course, as we suggested above, rather than only knowing, it seems more appropriate to reason about only knowing about a certain topic. Lakemeyer [K] provides a semantics for only knowing about, using the canonical-model approach. It would be interesting to see if this can also be done using the other approaches we have explored here.

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