Full-Spin-Wave-Scaled Finite Element Stochastic Micromagnetism: Mesh-Independent FUSSS LLG Simulations of Ferromagnetic Resonance and Reversal

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Abstract

In this paper, we address the problem that standard stochastic Landau-Lifshitz-Gilbert (sLLG) simulations typically produce results that show unphysical mesh-size dependence. The root cause of this problem is that the effects of spin wave fluctuations are ignored in sLLG. We propose to represent the effect of these fluctuations by a "FULL-Spinwave-Scaled Stochastic LLG", or FUSSS LLG method. In FUSSS LLG, the intrinsic parameters of the sLLG simulations are first scaled by scaling factors that integrate out the spin wave fluctuations up to the mesh size, and the sLLG simulation is then performed with these scaled parameters. We developed FUSSS LLG by studying the Ferromagnetic Resonance (FMR) in Nd\textsubscript{2}Fe\textsubscript{14}B cubes. The nominal scaling greatly reduced the mesh size dependence relative to sLLG. We further discovered that adjusting one scaling exponent by less than 10% delivered fully mesh-size-independent results for the FMR peak. We then performed three tests and validations of our FUSSS LLG with this modified scaling. 1) We studied the same FMR but with magnetostatic fields included. 2) We simulated the total magnetization of the Nd\textsubscript{2}Fe\textsubscript{14}B cube. 3) We studied the effective, temperature- and sweeping rate-dependent coercive field of the cubes. In all three cases we found that FUSSS LLG delivered essentially mesh-size-independent results, which tracked the theoretical expectations better than unscaled sLLG. Motivated by these successful validations, we propose that FUSSS LLG provides marked, qualitative progress towards accurate, high precision modeling of micromagnetics in hard, permanent magnets.

Keywords: spin wave scaling, stochastic LLG, finite element micromagnetism, ferromagnetic resonance, renormalization group, Gilbert damping

1. Introduction

Finite element micromagnetic modeling has been proven to be a reliable tool to describe many magnetic phenomena at finite temperature. Usually the micromagnetic model utilizes a form of the Landau-Lifshitz-Gilbert (LLG) equation. If the computation requires varying the temperature, as for example in simulations of heat assisted magnetic recording or permanent magnets in electric motors and generators, thermal excitations and fluctuations need to be represented in the LLG method.

The most popular approach to deal with thermal excitations in micromagnetics is to use a Landau-Lifshitz-Bloch (LLB) based equation [1, 2] which combines the LLG equations for low temperatures and the Bloch equations for high temperatures. In contrast to the LLG equations, in LLB the magnetization magnitude is no longer conserved, moreover the transversal and longitudinal components have different damping parameters. The LLB gives good results for temperatures close to and higher than the Curie temperature, but it achieves this success by introducing several additional temperature dependent parameters. At high temperatures the magnetization reverses linearly by changing its length and orientation, a process which can be perfectly described using the LLB equation [3]. Constructing these parameters involves a considerable amount of effort, though, as it requires a multi-scale simulation approach including ab initio methods and atomistic simulations, typically necessitating additional assumptions and phenomenologies [4, 5].

In this paper, we focus on the stochastic Landau-Lifshitz-Gilbert equation (sLLG). For temperatures far smaller than the Curie temperature, as in the case of permanent magnet applications, the magnetization will fluctuate at the surface of its unit sphere. Switching will not occur by linear reversal. Hence, the sLLG is a good choice. However, unless we do a scaling of the parameters, the result will strongly depend on the mesh size. The here presented FUSSS version of the LLG fixes this problem. A key advantage of sLLG for finite temperature micromagnetism is that it requires less phenomenological considera-
tions [6, 7]. In the sLLG approach the thermal perturbations are represented by adding white noise to the LLG equation, turning it into a Langevin-type stochastic differential equation [8]. The white noise is added to the effective field of the equation in the form of a stochastic field.

However, simulating magnetization dynamics with sLLG still requires either an accurate computation of atomistic-level spin models [9, 10], or an approximate finite element (FE) calculation with mesh size of atomistic length scales. The intrinsic properties serving as input parameters for such finite element calculations are fixed on the single spin level at 0 K and are usually taken from ab initio calculations. Sadly, due to the high demand of such calculations on computing resources, simulations at the atomistic scale are limited to a sample size of few nanometers.

To calculate magnetic behavior of samples on the micromagnetic scale, usually ranging from nanometers up to a few micrometers, the mesh size has to be increased. The term mesh size is used here to describe the average edge length of the elements in the mesh. Since micromagnetism is a continuum theory, its parameters represent thermal averages over the finite elements that are much larger than the material’s unit cell. Simulations that use a coarser FE mesh but retain the atomistic parameters fail to include fluctuations on length scales between the interatomic spacing and the mesh size. A class of such fluctuations is the short wavelength spin waves that reduce the magnetization of the mesh-elements, a key parameter of the sLLG simulation. Therefore, the saturation magnetization $M_s$ computed with the sLLG equation using the atomistic magnetization on a coarse mesh is too high. Such discrepancies increase with increasing temperatures. Many works address this problem by adopting phenomenological, effective parameters to match the sLLG simulations on a finite difference or finite element mesh with experiments. Without such adaptation, the sLLG results are reliable only at low temperatures.

Another undesirable consequence of the naïve sLLG methods that do not account for the fluctuations on intra-mesh length scales is that the results of the simulations are dependent on the mesh size: larger meshes ignore more fluctuations. This is clearly an unphysical state of affairs.

An inspired, quantitative method to account for intra-mesh fluctuations is to construct and to use renormalization group equations to integrate out intra-mesh fluctuations and represent them with scale-dependent, renormalized mesh parameters in sLLG FE simulations [11–14]. Grinstein and Koch [11] demonstrated the power of this method by modeling the temperature dependence of the magnetization of iron with a Heisenberg model. They used the Heisenberg renormalization group equations to generate scale-dependent, renormalized mesh parameters, which then they used in their sLLG simulations of the magnetization of large samples. Subsequently, Kirschner et al. [15] performed Monte Carlo simulations on an atomistic level and calculated the average spontaneous magnetization for much coarser cells at different temperatures. These cell/mesh size dependent macro-spins were then used in sLLG simulations on length scales two orders of magnitude larger than the unit cell. Finally, some papers use simplified versions of the renormalization group and call the procedure “coarse graining”, such as Behbahani et al. [14] for their sLLG calculation of hysteresis loops for magnetite nanorods.

However, these renormalization group approaches still have limitations. For example, renormalization group works only in the leading logarithmic approximation, which holds only if the spin waves have a gapless, purely quadratic dispersion. The need to use this idealized dispersion forced the incorporation of the anisotropy $K_u$ and the magnetic field $h$ only as perturbative corrections. Further, the effect of the actual crystal symmetries on the spin wave dispersion were also ignored when the momentum integrals were performed in idealized, isotropic spheres. When used for asymptotic calculations, such as near the critical temperature and at very long length scales, these approximations are justified. However, in most sLLG simulations the system is far from criticality, and the length scales of the FE mesh are intermediate, only a few nanometers. For both of these reasons, the quadratic gapless spin wave dispersion approximation is quite poor. It is especially poor for hard, permanent magnets because of their large anisotropy $K_u$. It gets worse still when the magnetic fields are high. And finally, reducing the analysis to the leading logarithmic approximation is justified if the renormalization group equations are integrated out to a very long correlation length, which is the case only very close to criticality. In contrast, the justification and therefore the accuracy of this leading logarithmic approximation is limited when only a limited range of wavelengths/length scales need to be integrated out, such as in the present case, when the integration proceeds from the atomistic scale only to the mesh size. For all the above reasons, for hard magnets in high fields with typical mesh sizes, the accuracy of sLLG simulations with renormalization group-corrected parameters is limited. This is consistent with the fact that the original verification of these renormalization group ideas was performed only for the soft magnet iron, in zero field, and at temperatures approaching the critical temperature $T_c$ [11], where the approximations are the most defensible, as properly discussed in that paper.

To address the above limitations and challenges, in the present paper we report the development of an improved renormalization group, or scaling, method. 1) Instead of the exchange-only, gapless, quadratic spin wave dispersion, forced by the leading logarithmic approximation, we retain the full spin wave dispersion with the anisotropy $K_u$ and finite magnetic field $h$ in it. This way we avoid treating these latter terms only perturbatively. Specifically, we use the spin wave dispersion of the hard magnetic compound Nd$_2$Fe$_{14}$B at 300 K temperature, determined and confirmed by experiments. 2) Using these experimental dispersions also retains the proper, real spin wave dispersion that represents the crystalline symmetry of the magnetic material. With these two modifications, we integrate out the intra-mesh spin wave fluctuations from the atomistic scale to the mesh size. This integral gives rise to a scaling factor for the magnetization parameter $M_s$ appropriate for the sLLG mesh size. From this, we determine the scaling factors for all the other parameters of the sLLG simulation for the used mesh size, including the exchange stiffness constant $A_u$ and the effective magnetocrystalline anisotropy constant $K_u$. Having noticed
a small discrepancy, we seek further improvements by sub-
sequently performing FMR simulations with our micromagnetic
code [16] and determine updated renormalization factors for
the magnetocrystalline anisotropy constant $K$ at different mesh
sizes. This is done by fitting $K$ to shift all FMR curves to the
same, shared bias field.

We will demonstrate the efficiency of our method in the con-
text of analyzing ferromagnetic resonance (FMR). FMR mea-
surements are a widely used technique to investigate dynamic
magnetic behavior, especially to determine damping ef-
facts in magnetization dynamics [17]. Micromagnetic FMR
simulations have been performed for granular perpendicular media
for magnetic recording to extract the Gilbert damping con-
stant [18]. In this paper, we use our ”spin-wave renormalized
sLLG” method to simulate the magnetic field dependence of the
FMR curves and show that the simulations are in good agree-
ment with experiments, and reassuringly, are mesh size inde-
pendent.

2. Methods

To calculate magnetization dynamics at finite temperatures
we use the Langevin-type stochastic LLG equation. We chose
to compute the magnetic state evolution of a single
cube of Nd$_2$Fe$_{14}$B. We develop and analyze the spin wave-
renormalized sLLG method by simulating two test scenarios,
and use a series of mesh sizes for each scenario to test the mesh
size independence of the results.

1) The equilibrium state of the cube was simulated by ini-
tially saturating the magnet in the easy axis direction and let the
cube relax without any external influence. The thermal pertur-
bation in form of the stochastic field caused increasing devia-
tions from the easy direction. The mean value of the magneti-
ization’s z-component over time $\langle M_z \rangle$ was calculated for various
mesh sizes to quantify the mesh dependency.

2) The cube was again saturated in the easy-axis-direction.
Then it was exposed to an increasing opposing field which
eventually reversed the magnet’s magnetization at the coercive
field $H_c$. The switching simulations were performed with dif-
ferent mesh sizes to evaluate the possible mesh dependency of
$H_c$.

2.1. Stochastic LLG for finite-temperature micromagnets

The sLLG method starts with constructing the usual Landau-
Lifshitz-Gilbert (LLG) equations, and then adding to the effect-
ive field $h_{\text{eff}}$ a field representing thermal fluctuations $h_{\text{th}}$:

$$\frac{\partial \mathbf{m}}{\partial t} = -\gamma \mathbf{m} \times (h_{\text{eff}} + h_{\text{th}}) - \frac{\gamma \alpha}{M_s} \mathbf{m} \times (\mathbf{m} \times (h_{\text{eff}} + h_{\text{th}})).$$

(1)

Here $\mathbf{m}$ is the magnetic unit vector, the prefactor $\gamma' = |\gamma|/(1 + \alpha^2)$ contains the gyromagnetic ratio $\gamma$, $\alpha$ is the Gilbert damping
constant, and $M_s$ is the spontaneous magnetization at the mini-
imum scale of the micromagnetic simulation, the finite element
mesh size $l$, typically a few nanometers. The total field is the
sum of the effective field $h_{\text{eff}}$ and the stochastic field $h_{\text{th}}$. The ef-
fective field is the sum of the exchange field $h_{\text{ex}} = 2K'_s/M'_s \Delta m$,
the anisotropy field $h_{\text{ani}} = 2K'/M'_s u (\mathbf{m} \cdot \mathbf{u})$, the demagnetizing
field $h_{\text{demag}}$ and the applied field $h_{\text{ext}}$.

$$h_{\text{eff}} = h_{\text{ex}} + h_{\text{ani}} + h_{\text{demag}} + h_{\text{ext}}$$

(2)

Here, $\mathbf{u}$ is the unit vector pointing in the easy axis direction.
The stochastic field $h_{\text{th}}$ introduces thermal fluctuations without
correlation between the spatial components, in time or space.
Therefore, it is a Gaussian random process which satisfies [19]

$$\langle h_{\text{th}}(t) \rangle = 0,$$

(3)

and has the variance

$$\langle h_{\text{th}}(t) h_{\text{th}}(t + \Delta t) \rangle = 2D \delta(t) \delta(\Delta t).$$

(4)

This equation relates the strength of the thermal fluctuations

$$D = \frac{\alpha}{\gamma \mu_0 M_s^2 V_c}$$

(5)
to the dissipation of the system depending on the FE-cell vol-
ume $V_c$. Here, $k_B = 1.38 \times 10^{-23}$ J/K is the Boltzmann con-
stant, $T$ is the temperature, and $\mu_0 = 4\pi \times 10^{-7}$ H/m is the
magnetic vacuum permeability. In order to calculate magnetic
states we interpret the stochastic equation in the Stratonovich
sense and integrate (1) using a mid-point scheme [20] with a
time step $\Delta t = 1$ fs.

FE-models of a cube with 40 nm edge length were prepared
with various mesh sizes from 1 nm to 10 nm using Salome [21]
and NETGEN [22]. A representation of a meshed model is
shown in the inset of Fig. 5. The mesh is composed of uni-
formly sized tetrahedral elements, which is important to ob-
tain reliable renormalization factors. Previously tested stochas-
tic simulations proved to be very sensitive to small changes
in element size of irregular meshes. To make progress, the
sLLG simulations need the magnet’s parameters, the magneti-
zation $M_s$, the exchange stiffness constant $A_e$, the magnetocryst-
talline anisotropy constant $K_a$, and the Gilbert damping $\alpha$.
Typically, sLLG approaches adopt parameters calculated by ab ini-
tio methods on the atomic scale and use them directly as the
parameters of the finite elements. In simplistic terms, present
sLLG simulations have not taken into account how the intra-mesh spin
wave fluctuations reduce the magnetization from its saturated
value.

2.2. Spin-wave renormalization of parameters

In order to incorporate the effects of the intra-mesh, short
wavelength spin wave fluctuations up to the mesh size $l$, Grin-
stein and Koch proposed to integrate out the fluctuations caused
by spin waves with wavenumbers higher than $\pi/l$ by renormal-
ization group theory. Doing so yielded scale-dependent effective
parameters for the sLLG simulation [11]. The limitations
of this approach were discussed earlier, including 1) the use of an idealized, gapless spin wave dispersion; 2) the approxi-
mate, perturbative expansion in both the magnetic field $h$ and

\[sL\]
in the anisotropy constant \(K_u\) to only leading logarithmic order; and 3) the disregard of the crystalline symmetries of the actual material, typically resulting in a non-isotropic spin wave dispersion. As also discussed, these three approximations can be justified in soft magnets in zero field, close to the critical temperature, where long wavelength critical fluctuations dominate the physics. However, typical sLLG simulations are not performed close to criticality, in zero field, and exclusively in soft magnets. For such typical simulations, the above approximations become questionable, especially for hard magnets with large \(K_u\) values.

Motivated by these limitations, in this paper we propose a similarly-inspired, but distinct method to incorporate spin wave fluctuations. In this "full-spin-wave-scaled sLLG" method, we propose to integrate out the spin wave fluctuations by using the full, preferably experimentally verified spin wave spectrum that can have a gap, is not expanded in full, preferably experimentally verified spin wave spectrum that includes the symmetries of the crystal. It is natural to expect that our method will achieve superior accuracy of sLLG simulations for magnets with stronger crystalline anisotropy, in higher fields, having non-negligible crystalline structures, at temperatures well below criticality. Taken on face value, this program starts with the atomistic magnetization \(M_s\), determined by \textit{ab initio} calculation on the length scale of the unit cell \(a\). The reduction of the magnetization by spin waves of wavenumber \(k\), \(\Delta M(k)\), is then integrated out with wavelengths sweeping between the atomistic scale \(a\) and the mesh size \(l\) to yield the length-scale dependent magnetization

\[
M'_s = M_s - \int_{\pi/a}^{\pi/l} \Delta M(k) \, dk. \tag{6}
\]

Using the value of magnetization change caused by a spin wave leads to

\[
M'_s = M_s - 2\mu_B \int_{\pi/a}^{\pi/l} n(E(k), T) \, dk, \tag{7}
\]

where the Bose-Einstein occupation factor \(n(E(k), T)\) is

\[
n(E(k), T) = \left[ \exp (E(k)/(k_B T)) - 1 \right]^{-1}, \tag{8}
\]

and \(E(k)\) is the full spin wave spectrum that includes the anisotropy constant \(K_u\) and the magnetic field \(h\) fully, not only in leading perturbative order. \(E(k)\) also reflects the discrete symmetries of the crystal, and thus can include the wavevector \(k\) in a trigonometric function instead of simply as \(k^2\). \(\mu_B\) is the Bohr magneton. The ratio of the renormalized magnetization to the non-renormalized magnetization will be referred to as the scaling function, or scaling factor, \(s_M(l) = M'_s/M_s\).

Extending the definition of the scaling function this way increases the precision with which the spin wave fluctuations are accounted for because our method is not perturbative in the magnetic field \(h\) and in the anisotropy constant \(K_u\), and furthermore it also incorporates the discrete symmetries of the crystal. On the other hand the justification for keeping only this term becomes less compelling because strictly speaking we are not keeping only the "leading logarithmic terms" of the standard renormalization group theory. However, the farther the simulated system is from criticality, the justification to keep only the leading logarithmic terms itself becomes less compelling anyway. Therefore, for systems away from criticality the calculation of the scaling function by retaining the non-perturbative spin wave energy dispersion with the explicit crystalline symmetries becomes a net positive improvement.

The scaling of the other parameters can be constructed by using well known relationships: the exchange stiffness constant scales as \(A'_x \propto (M_s)^2\) \cite{23, 16}, and so \(A'_x/A''_x = s_M(l)^2\). Further, the magnetocrystalline anisotropy constant scales according to Callen and Callen's power law for uniaxial anisotropy \(K'_u \propto (M_s)^3\) \cite{24, 25}, and thus \(K'_u/K''_u = s_M(l)^3\).

Once all three atomistic/microscopic parameters, \(M_s\), \(A'_x\), and \(K'_u\) have been scaled to their effective values \(M'_s\), \(A'_x\), and \(K'_u\) to incorporate the intra-mesh spin wave fluctuations up to wavelength \(l\) by their scaling factors, the sLLG simulation can be performed with the mesh size \(l\). This "microscale anchored full-spin-wave-scaled sLLG" should yield mesh size-independent results.

To implement the above steps, we started by consulting the literature for the ab initio parameters of permanent magnets of interest. For hard Nd\(_2\)Fe\(_{14}\)B magnets, Herbst summarized the results of several ab initio calculations \cite{26}. Quite remarkably, the calculated values showed a substantial variation, often differing by a factor of 2 or more. For this reason, it was quite difficult to establish consensus values of the ab initio calculations for hard Nd\(_2\)Fe\(_{14}\)B magnets.

Forced by this situation, we looked for data supported by widespread agreement. We found this among the experimentally determined macroscopic intrinsic properties of Nd\(_2\)Fe\(_{14}\)B \cite{25}, taken at \(T = 300\,\text{K}\). The saturation magnetization is widely agreed to be \(M'_s = 1.61\,\text{T}\), the exchange stiffness constant \(A'_x = 7.7\,\text{pJ}/\text{m}^2\), and the magnetocrystalline anisotropy constant \(K'_u = 4.3\,\text{MJ}/\text{m}^3\).

To build on widely accepted data, we propose that the full-spin-wave-scaled sLLG method can be applied in the reverse direction as well. When the sample magnetization is measured experimentally far away from reversal processes that take place close to \(H_c\) and involve nucleation and domain wall propagation, it is reasonable to assume that the entire difference between the experimentally measured magnetization and the magnetization on the scale of the mesh size \(l\) is caused by spin wave fluctuations. Therefore, it is possible to determine the effective magnetization on the length scale of the mesh size \(l\) by \textit{adding back} the magnetization-reduction caused by spin waves to the experimentally measured magnetization, by integrating the contribution of spin waves with wavenumbers between \(\pi/l\) and \(\pi/L\), where \(L\) is the macroscopic system size. We call this approach the "macroscale-anchored full-spin-wave-scaled sLLG" method. We start from the experimentally measured macroscopic magnetization \(M'_s\) measured at length scale \(L\), and integrate the spin wave corrections with wavelengths larger than

\[
\int \Delta M(k) \, dk = \int_{\pi/L}^{\pi/l} n(E(k), T) \, dk.
\]
the mesh size \( l \) back in:

\[
M^l_i = M^L_i + \int_{\pi/L}^{\pi/l} \Delta M(k) \, dk = M^L_i + 2\mu_B \int_{0}^{\pi/l} n(E(k), T) \, dk. \tag{9}
\]

The lower limit, \( \pi/L \), was taken as zero. \( E(k) \) is the spin wave spectrum of an anisotropic Heisenberg ferromagnet \[27\] in an external field \( \mathbf{h} \):

\[
E(k) = 2\mu_B \left( \frac{2K^L_L}{M^L_i} - \mu_0 h \right) + \frac{4\mu_B A^L_L}{M^L_i} \left( 1 - \frac{1}{Z} \sum_i \cos (\mathbf{a}_i \cdot \mathbf{k}) \right). \tag{10}
\]

where \( Z \) is the coordination number of the lattice and \( \mathbf{a}_i \) are the nearest neighbor vectors. Experimental measurements of the spin wave spectrum are consistent with this form \[25\]. As outlined in the foundational parts, \( E(k) \) retained the magnetic field and the crystalline anisotropy in full, instead of perturbatively expanding in them. These factors induced a gap in the spectrum, which would have been incompatible with the standard renormalization group formulation.

Based on the above, the scaling function for the magnetization in this macroscale-anchored full-spin-wave-scaled sLLG takes the form:

\[
s_M(l) = \frac{M^l_i}{M^L_i} = 1 + 2\mu_B \int_{0}^{\pi/l} n(E(k), T) \, dk. \tag{11}
\]

Examples of the scaling factors, \( s_M(l) \), \( s_A(l) \) and \( s_E(l) \) as function of the mesh size \( l \) are shown in Fig. 3 and discussed there.

Once the full-spin-wave-scaled magnetization \( M^l_i \), exchange constant \( A^l_i \) and anisotropy \( K^l_i \) have been constructed, the sLLG method with mesh size \( l \) can be used to simulate experiments that involve not only spin waves but nucleation, domain wall propagation, ferro-magnetic resonance (FMR), and other, non-trivial phenomena. This full-spin-wave-scaled sLLG method should deliver mesh size independent results, and thus should introduce a major step forward in the accuracy and utility of sLLG methods for simulating complex and challenging magnetization dynamics.

3. Results and Discussion

3.1. Development of FUSSS LLG by simulating ferromagnetic resonance

Often ferromagnetic resonance (FMR) experiments or simulations are used to determine the effective damping constant in materials of interest \[12, 18\]. In this work, we carry out FMR simulations to critically test the above developed full-spin-wave-scaled sLLG theory by checking whether it indeed delivers results independent of the finite element mesh size. In the simulations we have adopted the often-used Gilbert damping value of \( \alpha = 0.01 \).

In the FMR-simulation, the previously prepared cube is exposed to an oscillating field with maximal amplitude of \( \mu_0 H_{\text{bias}} = 5 \text{ mT} \) applied orthogonally to the cube’s anisotropic easy axis in \( x \)-direction (see Fig. 1). The frequency is chosen to be \( f_{\text{AC}} = 216 \text{ GHz} \). Neglecting the demagnetizing field, the magnetic moments are in resonance at a bias field of \( \mu_0 H_{\text{bias}} = 1 \text{ T} \), resulting in an FMR-peak at this field:

\[
f_{\text{AC}} = \frac{\gamma \mu_0}{2\pi} (H_{\text{ani}} + H_{\text{bias}}) \tag{12}
\]

with \( H_{\text{ani}} = \frac{2K^L_L}{\mu_0 M^L_i} \tag{13} \)

and \( \gamma = 1.760 \text{859} \text{6} \times 10^{11} \text{ T}^{-1} \text{s}^{-1} \tag{14} \).

\( H_{\text{ani}} \) is the theoretical anisotropy field. The bias field is applied parallel to the cube’s easy axis. Initially, the cube’s magnetization is saturated parallel to \( H_{\text{bias}} \). At a temperature of 300 K the time evolution of the magnetization configuration is calculated by solving the stochastic LLG. The simulations are repeated with different mesh sizes and with different values of the bias field from 0.6 T to 1.9 T. Each simulation was performed for 1 ns. The transients settled after 0.4 ns – the data recorded after this transient time were accepted as the results. Sequentially the \( x \)-component of the magnetization, \( \hat{m}_x \), in the frequency spectrum of the \( x \)-component of \( \mathbf{m} \).

The results of various sLLG simulations for different mesh sizes are shown in Fig. 2. As shown in the upper panel, when the sLLG did not use parameters scaled by the spin wave fluctuations, the simulations yielded strongly mesh size dependent results. In contrast, the lower panel shows that when the full-spin-wave-scaled sLLG used parameters scaled by the spin wave fluctuations, then the simulations yielded results essentially independent of the mesh size, as discussed below.

The FMR simulations were performed for a uniformly meshed hard magnetic \( \text{Nd}_2\text{Fe}_{14}\text{B} \) cube, wherein the mesh size \( l \) was varied in the 1 nm to 10 nm range. As the upper panel shows, without scaling of the parameters, the magnetic (bias) field defining the center of the FMR peak shifted substantially from the external bias field of \( H_{\text{bias}} = 1 \text{ T} \) to the much higher bias fields of \( H_{\text{bias}} = 1.6 \text{ T} \), as \( l \) varied from 10 nm to 1 nm. This large, 60% shift demonstrates one more time the unphysical dependence of measureable quantities on the mesh size. For completeness we note that the Gilbert-damping-related FMR
line-width (the FWHM of the peaks) stayed essentially invariant at 255 mT ($\sigma^2 = 0.095$) as the mesh size $l$ was varied.

Feng and Visscher [12] introduced a mesh size dependent damping constant for a system including only exchange and thermal energy. The effective rescaled damping constant was found to increase with temperature and computational cell size. In this work we focus on permanent magnets, where in addition to the exchange the magnetocrystalline anisotropy is the dominating energy term. For the cell size of about 4 nm and 300 K the ratios of thermal energy to anisotropy energy and to the exchange energy are 0.015 and 0.134, respectively. Following the results of Feng and Visscher our computational experiments are in the low temperature regime where no or only minor scaling of the damping parameter is required.

When the parameters were scaled with the mesh size according to the above full-spin-wave-scaling with scaling factors $s_M(l) = s_M(l)^2$ and $s_K(l) = s_M(l)^3$, the FMR peaks shifted back to the vicinity of the bias field of $H_{bias} = 1$ T. The creep of $H_{bias}$ with mesh size was reduced from above 60% to below 20%, a great improvement. The fact that there was some residual dependence still left is most likely due to the fact that our scaling factors are only the leading terms of the overall spin wave fluctuation reduction of $M_s^l$.

To eliminate even this residual mesh size dependence, we modified the scaling of $K_u$, so that the FMR peak remains at the mesh size independent $H_{bias} = 1$ T. To formulate the most natural scaling function for $K_u$, we retained the power-law form and treated its exponent as the adjustable parameter. We found that the choice of the anisotropy scaling exponent $K_u \propto M_s^{2.72}$ kept the bias field of the FMR peak location fully mesh size independent, as shown in the bottom panel of Fig. 2. This is only a 9% adjustment of the scaling exponent from its Callen value of 3, a very respectable achievement from our first order approximate scaling factors.

The scaling functions we used for the full-spin-wave-scaled stochastic LLG are shown in Fig. 3. Additionally, these same scaling factors and the corresponding intrinsic property values for the used mesh sizes are listed in Table 1.

![Figure 2: FMR curves obtained with sLLG without demagnetization field for different mesh sizes. The symbols mark the computed results and the solid lines are the respective fits by Lorentz functions. While without scaling (top) the curves are shifted to higher bias fields, scaling the intrinsic properties (bottom) shifts the peaks back on top of each other.](image1)

![Figure 3: Scaling functions for intrinsic properties at a temperature of 300 K for Nd$_2$Fe$_{14}$B. While the scaling of the magnetization $s_M$ is derived from spin wave theory, the scaling for the exchange stiffness constant $s_A$ follows $A \propto M_s^2$. The scaling for the magnetocrystalline anisotropy constant $s_K$ was determined by choosing $K_u$ to shift the FMR peaks of the various mesh sizes to the appropriate bias field. $s_K$ can then be fitted by $K_u \propto (M_s^l)^{2.72}$.](image2)

Table 1: Values of scaling functions $s$ and resulting intrinsic properties at the various mesh sizes $l$. The macroscopic intrinsic properties from experiments are shown at the bottom of the table.

| $l$ (nm) | $s_M$ | $s_A$ | $s_K$ | $\mu_0 M_s^l$ (T) | $A_s^l$ (pJ/m) | $K_u^l$ (MJ/m$^3$) |
|---------|-------|-------|-------|-------------------|----------------|------------------|
| 1       | 1.049 | 1.101 | 1.138 | 1.689             | 8.478          | 4.892            |
| 2       | 1.023 | 1.046 | 1.053 | 1.647             | 8.054          | 4.527            |
| 3       | 1.012 | 1.025 | 1.026 | 1.629             | 7.893          | 4.414            |
| 4       | 1.005 | 1.010 | 1.010 | 1.618             | 7.777          | 4.341            |
| 5       | 1.002 | 1.004 | 1.003 | 1.613             | 7.731          | 4.312            |
| 10      | 1.001 | 1.002 | 1.001 | 1.612             | 7.715          | 4.306            |

From now on, we will refer to the above developed and described FULL-Spinwave-Scaled Stochastic LLG as FUSSS LLG.

3.2. Tests and Validation of FUSSS LLG

We performed several tests and validation of our FUSSS LLG. First, we repeated the FMR-simulations by including the magnetostatic field. The FMR-curves show two peaks (see Fig. 4). This curve was obtained using the fourier transform of the average magnetization of the entire cube. To analyze the spectrum we also computed the resonance of the local magnetization at different probe points. The analysis of local magnetization dynamics show that the peak at the lower $H_{bias}$ corre-
sponds to the local response at the center of the cube. In this bulk mode the major part of the cube is in resonance. The second peak at higher $H_{\text{bias}}$ values is caused by resonance at points near the top and bottom face (near the center of the face or in the middle of an edge). The edge mode arises from a different local demagnetizing field. In addition there might be magnetostatic interaction between the modes. However, in the following we show the scaling parameters can be derived neglecting magnetostatics.

The existence of these two modes was confirmed experimentally in FMR investigations of thin films [28]. The two peaks were centered at $H_{\text{bias}} \approx 0.88$ T and $H_{\text{bias}} \approx 1.31$ T, for the bulk mode and for the edge mode, respectively. As before, when the intrinsic parameters were not scaled, the sLLG curves shifted to higher bias fields as seen in the top graph of Fig. 4. For $h = 1$ nm the lower field peak shifted from $0.88$ T by $0.52$ T, again a 60% shift. To demonstrate the predictive power of our FUSSS LLG, we then repeated the simulations with the intrinsic parameters scaled by the scaling factors determined in the "no-magnetostatic-field" simulations earlier (see Table 1). The bottom graph of Fig. 4 shows that the FUSSS LLG also found the two resonance peaks, and their center bias fields were almost independent of the finite element mesh size $l$.

Second, we simulated the equilibrium value of the magnetization of a Nd$_2$Fe$_{14}$B cube with an edge length of 40 nm at 300 K temperature. For each chosen mesh size the magnetic state was relaxed for 0.5 ns after initial saturation in the easy axis direction. The magnetostatic field was not taken into account in these simulations. Due to the stochastic field in the sLLG, the magnetic moments fluctuated around the easy axis. In Fig. 5 the mean value over 2 ns of the magnetization component in easy direction $\mu_0 \langle M_z \rangle$ is plotted against the mesh size. The macroscopic magnetization was measured to be $\mu_0 M_z = 1.61$ T. Without scaling, the sLLG produces reduced values with decreasing mesh size. For $h = 1$ nm the mean magnetization is reduced by 6% to 1.51 T, as for smaller meshes the restoring force is smaller. Then we repeated the same calculation with FUSSS LLG, using scaled intrinsic parameters. As shown in the same figure, the magnetization reduction has been properly compensated, and the unphysical mesh-size dependence essentially eliminated. The deviations have been reduced from 6% to less than 1%.

Third, we simulated the reversal of the magnetization by an applied field. Here we took the magnetostatic field into account. A cubic sample was magnetically saturated in the easy axis direction, and then reversed by changing the direction of the external field from the saturation direction to the opposite with a field sweep rate of $v = 250$ mT/μs. The simulation of reversal requires a mesh size of $l \leq \sqrt{A/\kappa_u} = 1.34$ nm to properly capture the possible formation of domain walls [29]. Therefore, only calculations for $l$ of 0.5 nm to 2 nm were performed. The edge length of the cube was shortened to 10 nm to reduce the use of computation resources. For every mesh size the coercive field $H_c$ was extracted by averaging over 10 stochastic simulations, with and without scaling the input parameters. In Fig. 6 the mean values of $H_c$ are shown and compared to the reversal field calculated by conventional, non-thermal LLG.

The anisotropy field for the exchange-interaction-only model has been calculated in (13). With the material parameters of our cube, this comes to $\mu_0 H_{\text{ani}} = 6.71$ T. When the magnetostatic field is incorporated, non-thermal LLG simulations show that the coercive field is reduced by 0.35 T, to $\mu_0 H_c = 6.36$ T.

By adding thermal fluctuations, the energy barrier against switching the cube can be overcome with lower external fields. This physics can be captured as a temperature- and sweep-rate-dependent effective coercive field $H_c$. Various analytical expressions have been derived to describe this temperature- and sweep-rate-dependent $H_c$, where an applied field is swept at the

\[ H_c = \frac{A}{K_u} \left( \frac{1}{l} - \frac{1}{l_0} \right) \]

Figure 4: FMR curves for different mesh sizes $l$ of a small cube computed by (top) sLLG without parameter scaling, and (bottom) with scaled intrinsic properties. While the symbols mark the computed results, the lines are spline interpolations serving as guide to the eye. The two peaks of each curve correspond to the bulk and edge mode.

| $l$ (nm) | $H_{\text{bias}}$ (T) | sLLG no scaling | sLLG scaled |
|---------|-----------------------|-----------------|-------------|
| 1       | 0.88                  | 1.62            | 1.54        |
| 2       | 1.31                  | 1.46            | 1.42        |
| 3       | 1.88                  | 1.36            | 1.32        |
| 5       | 2.31                  | 1.26            | 1.22        |

Figure 5: Magnetization in easy axis direction averaged over 2 ns calculated for different mesh sizes $l$, with and without scaling of the input parameters $M_z^l$, $A_z^l$ and $K_u$. The inset shows an example of a mesh for the test-cube with magnetic moments in quasi-equilibrium state.
Constant rate $\nu$ [30]. El-Hilo et al. [31] proposed

$$H_c = H_0 \left(1 - \frac{1}{2\beta} \ln \left(\frac{f_0H_0}{2\nu\beta}\right)\right)$$

with $\beta = \frac{E_0}{k_B T}$. (15)

The energy barrier of the cube at zero field $E_0 = 522$ kJ/300 K was determined using the nudged elastic band method [32] and $H_0 = 6.36$ T/$\mu_0$ is the switching field without thermal fluctuations, but with magnetostatic fields. $f_0$ is the attempt frequency in zero external field, that strongly depends on the reversal mode of the sample. The approximation of $f_0$ [6] for homogeneous reversal of the cube with volume $V$,

$$f_0 = \frac{a\gamma\mu_0}{1 + a^2} \sqrt{H_0^2 V / 2\pi k_B T},$$

(17)
gives an attempt frequency of $f_0 = 198$ GHz. However, recent studies of inhomogeneous reversal [33] have suggested attempt frequencies exceeding 6 THz for hard magnetic single particles. For these two values for $f_0$ we obtained the theoretical coercive fields of $\mu_0H_c = 6.02$ T and 5.74 T, respectively. We use these two fields to define a range of expected coercive fields, signalled by the gray band in Fig. 6.

We first calculated the effective coercive field with the unscrolled sLLG. First, the coercive field had a substantial, unphysical variation with changing mesh size. Second, in the entire range of mesh sizes, the coercive field $H_c$ was well outside the gray band of theoretical expectations. Third, in fact for the smallest mesh size of $l = 0.5$ nm, $H_c$ was 4.4 T, 23% less than the lowest edge of the expected band, a substantial discrepancy.

Finally, we simulated the same reversal with FUSSS LLG, using the same scaling as in the earlier test examples. As visible in Fig. 6, first, the mesh size dependence of $H_c$ was largely eliminated. Second, $H_c$ remained inside the gray band of theoretical expectations nearly the entire mesh size range. Both these facts are encouraging signs that FUSSS LLG introduces a marked, quantitative improvement over existing sLLG methods.

4. Summary

In this paper, we addressed the problem that standard stochastic Landau-Lifshitz-Gilbert (sLLG) simulations typically produce results that show unphysical mesh-size dependence. We identified the root cause of this problem: the effects of spin wave fluctuations are ignored in sLLG. We proposed to represent the effect of these spin wave fluctuations by a "FULL-Spin-wave-Scaled Stochastic LLG", or FUSSS LLG method.

In FUSSS LLG that uses a mesh size $l$, the intrinsic parameters of the sLLG simulations $M_s, \alpha_s, K$, and $K_s$ are first scaled by scaling factors $sM(l), s_\alpha(l)$ and $s_{K}(l) = s_{K}(l)^b$ (with $b = 3$) that integrate out the spin wave fluctuations up to the mesh size $l$, and the sLLG simulation is then performed with these scaled parameters. The scaling can be naturally anchored in the microscopic, or atomistic parameters. However, given that for hard magnets there is no consensus about these values, we chose to anchor our FUSSS LLG on the macroscopic scale, in experimentally measured quantities. In this sense, our scaling factors $sM(l), s_\alpha(l)$ and $s_{K}(l)$ were integrating spin wave fluctuations "back in" to get the effective parameters right on the length scale of the mesh size $l$.

We developed FUSSS LLG by studying the Ferromagnetic Resonance (FMR) in Nd$_2$Fe$_{14}$B cubes. We found that while the scaling greatly reduced the mesh size dependence relative to sLLG, full mesh size independence was not achieved with the nominal anisotropy scaling exponent of $b = 3$. However, we discovered that adjusting $b$ from $b = 3$ to $b = 2.72$, a less than 10% adjustment, delivered fully mesh size independent results for the FMR peak.

We then performed three tests and validations of our FUSSS LLG with this modified scaling. First, we studied the same FMR but with magnetostatic fields included. This model exhibited two FMR peaks instead of one. Second, we simulated the total magnetization of the Nd$_2$Fe$_{14}$B cube. Third, we studied the effective, temperature- and sweeping rate-dependent coercive field of the cubes. In all three cases we found that FUSSS LLG delivered essentially mesh-size-independent results, which tracked the theoretical expectations better than unscaled sLLG.

Before closing, we remark that a sister version of the present FUSSS LLG can be developed for magnets where the microscopic parameters are subject of agreement by the community, in which case the microscopically anchored FUSSS LLG can be an equally powerful method.

In sum, motivated by the success of our tests and validations, we propose that FUSSS LLG provides marked, qualita-
tive progress towards accurate, high precision modeling of micromagnetics in hard, permanent magnets.

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