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Computational Analysis of the Pulmonary Arteries in Congenital Heart Disease: A Review of the Methods and Results

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With the help of computational fluid dynamics (CFD), hemodynamics of the pulmonary arteries (PAs) can be studied in detail and varying physiological circumstances and treatment options can be simulated. This offers the opportunity to improve the diagnostics and treatment of PA stenosis in biventricular congenital heart disease (CHD). The aim of this review was to evaluate the methods of computational studies for PA’s in biventricular CHD and the level of validation of the numerical outcomes. A total of 34 original research papers were selected. The literature showed a great variety in the used methods for (re) construction of the geometry as well as definition of the boundary conditions and numerical setup. There were 10 different methods identified to define inlet boundary conditions and 17 for outlet boundary conditions. A total of nine papers verified their CFD outcomes by comparing results to clinical data or by an experimental mock loop. The diversity in used methods and the low level of validation of the outcomes result in uncertainties regarding the reliability of numerical studies. This limits the current clinical utility of CFD for the study of PA flow in CHD. Standardization and validation of the methods are therefore recommended.

1. Introduction

Stenosis of the pulmonary arteries (PAs) is commonly seen in patients with congenital heart disease (CHD). It can occur as a native substrate or after surgery [1]. Diagnosing patients with PA stenosis can be challenging as cardiac echography may be inconclusive. To confirm the diagnosis, often evaluation with multiple imaging modalities as CTA and CMR is necessary. The decision whether to treat the stenosis is primarily based on pressure gradients which need to be confirmed by cardiac catheterization [2]. However, pressure gradients might resolve under anesthesia resulting in possible under treatment of PA stenosis. In addition, restenosis and intima proliferation can occur after treatment. The mechanisms causing this are still not well understood, but several flow characteristics—i.e., turbulence, wall shear stress (WSS), and the interaction of flow and (stent) geometry—are hypothesized to be of influence [3–5]. Computational fluid dynamics (CFD) provides the opportunity to study these factors and enhance our knowledge of hemodynamics in the PAs. It allows for detailed flow visualization and simulation of exercise and treatment outcomes. However, its clinical use is still limited as there is a great variety in used methods and validation of the numerical outcomes is often challenging [6–11].

The aim of this review was to analyze the available literature on numerical studies of the pulmonary arteries in biventricular CHD, focusing on the used methods and validation of the results.

2. Methods

2.1. Search Strategy. A PubMed and Embase search was performed. The searched papers needed to include “pulmonary arteries” and “computational fluid dynamics” or a synonym in their title or abstract. The language for the search was restricted to English. All papers published before 1st of January 2021 were included.

2.2. Inclusion and Exclusion Criteria. All papers on numerical analysis of the PA’s in biventricular hearts were included.
Pediatric and adult as well as animal studies were considered. Papers with the focus on pulmonary hypertension were excluded as well as papers from before 2001, reviews, and if no full text was available. All inclusion and exclusion criteria are shown in Figure 1.

3. Results

3.1. Study Selection. The search in the PubMed and Embase databases resulted in a total of, respectively, 266 and 286 papers. After undoubling and title abstract screening, 45 papers remained. The full-text screening of these papers revealed exclusion criteria for 11 articles. This resulted in a total of 34 eligible papers for this review. The flowchart for the selection process is shown in Figure 1.

3.2. Study Overview. The 34 selected papers included four animal studies and 25 papers presenting human cases. In one paper, both human and animal cases were described [12]. In six studies, PA’s were represented by straight or curved tubes [13–18]. Altogether, the articles presented a total of 256 geometries based on 126 subjects (Table 1).

Over half of the included papers focused on the surgical treatment of PA stenosis. These 19 studies described the use of CFD in surgical planning, for comparison of different shunt configurations or to study (post)surgical complications [13–16, 18–31]. In two papers, numerical studies were used to evaluate interventional strategies [32, 33]. One of these described a CFD-assisted patient-specific stent design for PA interventions, and the other studied a new device for percutaneous pulmonary valve replacement. Technical strategies for CFD analysis were the main subject in five papers [12, 34–37]. The focus was on improving or simplifying the process of numerical modeling of the PA’s. The remaining eight papers described hemodynamics in the PA’s, for example, comparing rest and exercise conditions or describing the hemodynamic impact of abnormal anatomy [17, 37–43].

Of the 34 studies, 13 were published in journals with a clinical orientation [13, 16, 18, 20–22, 25, 27–30, 37, 43]. Most of these papers—nine, respectively—were published in cardiovascular surgical journals [13, 21, 22, 25, 27–30, 43]. The other 21 studies were published in technical journals, for example, focusing on biomedical engineering or numerical methods in medicine [12, 14, 15, 17, 19, 23, 26, 31–42, 44].

In the following sections, the various used methods for numerical analysis of the PA’s will be compared. The sections are subdivided into the major steps necessary for solving a CFD case. First is the anatomic reconstruction, then the meshing and setting the boundary conditions followed by the numerical setup and finishing with postprocessing and validation of the results. Table 2 provides a summary of the different strategies used in the selected papers.

3.3. (Re)construction of the Geometry. Figure 2 shows the source for reconstruction of the geometry used in the selected papers. In 23 of the 34 papers, at least one patient-specific anatomy was reconstructed. The source for this reconstruction was a cardiac CT in 16 studies and CMR in six studies [12, 18, 20, 21, 23, 25, 26, 30–37, 39–45]. In the remaining two studies, multiple plane measurements on cardiac angiography were taken after which the anatomy was reconstructed [16, 27]. For surgical studies, often, one patient-specific anatomy was created after which the anatomy was altered to mimic various surgical approaches.

Most groups (re)constructed a geometry consisting of the main PA bifurcation and the right and left pulmonary artery [17, 18, 21, 22, 28, 29, 32–34, 38–40]. All these models had one inlet and two outlets. Shunt anatomy was mostly represented by one aortic or shunt inlet and two or three outlets representing the RPA, LPA, and/or the descending aorta [14–16, 23, 25–27, 31, 42, 44]. In three studies, the flow in the main PA was computed using a model with one inlet and one outlet [13, 19, 20]. Kong et al. analyzed a model with one inlet and 274 outlets, making it the biggest PA anatomy studied [36]. In seven other studies, the pulmonary
circulation was reconstructed up to the peripheral arteries. Here, imaging resolution was always the limiting factor for reconstruction [12, 30, 35, 37, 41, 43, 45]. The number of outlets in these studies varied between 8 and 100 outlets per model.

An artificial geometry was used in ten studies [13–15, 17, 19, 24, 28, 38]. A geometry was constructed based on general values obtained by literature or measurements in multiple patients in seven papers [17, 19, 22, 24, 28, 29, 38]. The other three studies analyzed arteries represented by ideal (curved) tubes [13–15].

After geometry reconstruction, inlet and outlet extensions were added in four of the 34 studies [19, 21, 30, 40]. The extension of the inlet varied between five and 20 times

| Author + year | Journal | Article type | Number of geometries | Based on number of patients |
|---------------|---------|--------------|-----------------------|----------------------------|
| Corno et al. 2006 [13] | European Journal of Cardio-Thoracic Surgery | Surgical | 7 | — |
| Esmaily-Moghadam et al. 2015 [14] | Journal of biomechanical engineering | Surgical | 13 | — |
| Lashkarinia et al. 2018 [19] | Annals of Biomedical Engineering | Surgical | 5 | — |
| Matthews et al. 2011 [20] | The Journal of Heart Valve Disease | Surgical | 1 | 1* |
| Migliavacca et al. 2002 [15] | Computer Methods in Biomechanics & Biomedical Engineering | Surgical | 1 | — |
| Miyaji et al. 2019 [21] | Interactive CardioVascular and Thoracic Surgery | Surgical | 18 | 6 |
| Mosbahi et al. 2014 [22] | Interactive CardioVascular and Thoracic Surgery | Surgical | 1 | 5* |
| Piskin et al. 2017 (1) [23] | Journal of Biomechanics | Surgical | 12 | 1 |
| Piskin et al. 2017 (2) [24] | Cardiovascular Engineering and Technology | Surgical | 6 | — |
| Rao et al. 2015 [25] | Interactive CardioVascular and Thoracic Surgery | Surgical | 6 | 2 |
| Zhang et al. 2019 [26] | Computational and Mathematical Methods in Medicine | Surgical | 6 | 2 |
| Zhang et al. 2020 [44] | Computer methods and programs in biomecine | Surgical | 6 | 1 |
| Ascuitto et al. 2017 [27] | Interactive CardioVascular and Thoracic Surgery | Surgical | 4 | 4 (3 univentricular) |
| Berdajs et al. 2015 (1) [29] | Journal of Surgical Research | Surgical | 1 | 10* |
| Berdajs et al. 2015 (2) [28] | Interactive CardioVascular and Thoracic Surgery | Surgical | 4 | 20* |
| Celestin et al. 2015 [16] | Pediatric Cardiology | Surgical | 8 | 2 |
| Kato et al. 2018 [30] | Interactive CardioVascular and Thoracic Surgery | Surgical | 6 | 6 |
| Tomov et al. 2019 [18] | Journal of the American Heart Association | Surgical | 1 | 1 |
| Liu et al. 2020 [31] | Computational and mathematical methods in medicine | Surgical | 35 | 1 |
| Boumpoulis et al. 2020 [17] | Medical engineering and physics | Hemodynamics | 9 | — |
| Chern et al. 2008 [38] | Journal of Biomechanics | Hemodynamics | 3 | 10 |
| Chern et al. 2012 [39] | Computational and Mathematical Methods in Medicine | Hemodynamics | 4 | 4 |
| Das et al. 2011 [40] | Tech Science Press | Hemodynamics | 2 | 2 |
| Tang et al. 2011 [41] | Annals of Biomedical Engineering | Hemodynamics | 6 | 6 |
| Waniek et al. 2005 [42] | Artificial Organs | Hemodynamics | 5 | 1 |
| Yang et al. 2017 [45] | Congenital Heart Disease | Hemodynamics | 10 | 4 |
| Zhang et al. 2016 [43] | Interactive CardioVascular and Thoracic Surgery | Hemodynamics | 5 | 1 |
| Guibert et al. 2014 [34] | Medical Image Analysis | Technical | 17 | 17 |
| Kong et al. 2017 [36] | International Journal for Numerical Methods in Biomedical Engineering | Technical | 1 | 1 |
| Kong et al. 2019 [35] | International Journal for Numerical Methods in Biomedical Engineering | Technical | 1 | 1 |
| Spilker et al. 2007 [12] | Annals of Biomedical Engineering | Technical | 4 | 2 ** |
| Yang et al. 2016 [37] | Biomechanics and Modeling in Mechanobiology | Technical | 4 | 2 |
| Caiazzo et al. 2015 [33] | Cardiovascular Engineering and Technology | Interventional | 12 | 1 |
| Gudelweit et al. 2018 [32] | Journal of Biomechanics | Interventional | 32 | 16 |

* Animal cases ** 1 animal case, 1 human case. N/A= not applicable.
### Table 2: Used boundary conditions in the included articles.

| Author + year | Inlet | Pulsatile | Patient specific? | Outlet | Patient specific? |
|---------------|-------|-----------|-------------------|--------|-------------------|
| Berdajs et al. 2015 (1) [22] | Mass flow | Yes | - | Pressure | - |
| Berdajs et al. 2015 (2) [21] | Mass flow | - | - | Pressure | - |
| Mosbahi et al. 2014 [20] | Mass flow | - | - | Pressure | - |
| Yang et al. 2016 [42] | Mass flow | Yes | In volume | Lumped parameters | Yes |
| Yang et al. 2017 [44] | Mass flow | Yes | In volume | Lumped parameters | Yes |
| Guibert et al. 2014 [25] | Mass flow | Yes | - | Lumped parameters | - |
| Gundelwein et al. 2018 [24] | Mass flow | Yes | In volume | Lumped parameters | Yes |
| Kato et al. 2018 [39] | Mass flow | Yes | In volume | Pressure | - |
| Zhang et al. 2016 [43] | Mass flow | Yes | Yes | Pressure | - |
| Zhang et al. 2020 [34] | Mass flow | - | - | Resistance | - |
| Rao et al. 2015 [30] | Mass flow | - | In volume | Pressure | - |
| Miglavacca et al. 2002 [15] | Mass flow | - | - | Pressure | - |
| Miyaji et al. 2019 [19] | Mass flow | - | - | Pressure | - |
| Spilker et al. 2007 [12] | Mass flow | Yes | For one case | Impedance | For one case |
| Tang et al. 2011 [41] | Mass flow | Yes | Yes | Resistance | Yes |
| Liu et al. 2020 [35] | Mass flow | - | - | Resistance | Yes |
| Kong et al. 2017 [38] | Mass flow | Yes | - | No traction | - |
| Corno et al. 2006 [13] | Mass flow | Yes | - | UN | UN |
| Piskin et al. 2017 (1) [29] | Velocity | - | - | Resistance | - |
| Boumpouli et al. 2020 [17] | Velocity | Yes | - | Pressure, flow split, lumped parameters | - |
| Chern et al. 2012 [27] | Velocity | Yes | Yes | Pressure | - |
| Lashkarinia et al. 2018 [36] | Velocity | - | - | Pressure | - |
| Kong et al. 2019 [40] | Velocity | Yes | - | No traction | - |
| Tomov et al. 2019 [18] | Velocity | Yes | - | Pressure | - |
| Waniewski et al. 2005 [33] | Velocity | Yes | - | Mass flow | - |
| Chern et al. 2008 [26] | Velocity | Yes | - | UN | UN |
| Ascuitto et al. 2017 [32] | Pressure | Yes | Yes | Pressure | Yes |
| Celestin et al. 2015 [16] | Pressure | - | Yes | Pressure | Yes |
| Caiazzo et al. 2015 [23] | Pressure | Yes | - | Lumped parameters | - |
| Matthews et al. 2011 [37] | Pressure | Yes | - | Pressure | - |
| Piskin et al. 2017 (2) [45] | Resistance | - | - | Resistance | - |
| Das et al. 2011 [28] | Womersley profile | Yes | Yes | Pressure/Womersley profile | Yes |
| Zhang et al. 2019 [31] | Lumpede parameters | - | - | Lumpede parameters | - |
| Esmaily-Moghadam et al. 2015 [14] | Lumped parameters | Yes | - | Lumped parameters | - |

UN=unknown.
the diameter of the inlet. The outlet region was extended 20 times the diameter of the outlet. In the other 30 studies, the inlet and outlet regions were not extended.

A variety of software was used for segmentation of the patient-specific anatomies. The most mentioned open-source software package was SimVascular (http://simvascular.org). For commercial software, this was MIMICS (Materialise, Leuven, Belgium). Other software for segmentation included ITK-SNAP (open-source, http://itk-snap.org), OsiriX (commercial, Pixmeo SARL, Geneva, Switzerland), and CardioViz3D (open-source, Asclepios Research Project, Inria Sophia Antipolis, Greece).

3.4. Meshing. The meshing process was—partly—described in 27 of the 34 papers, while in seven, this information was completely missing. A nonstructured meshing strategy with tetrahedral elements was used in 20 of the 27 studies [12, 14, 16, 17, 19, 21, 23, 24, 30–33, 35, 36, 39–44]. A structured mesh was applied by six groups [15, 20, 22, 28, 29, 38]. Boundary layers were described by 16 authors, but the majority of the studies did not mention any boundary layer use. Of the 27 articles specifying their meshing process, 20 reported the program they used [14, 15, 17–24, 28–30, 32, 33, 36, 39–41, 43]. In most cases, this was ANSYS software (ANSYS Inc., Canonsburg PA, USA).

A mesh independence test to evaluate mesh quality was performed in 16 of the 34 papers [14–16, 18, 19, 23, 24, 31, 33, 38–44]. In 12 of these, information on the criteria for mesh independence was provided [14, 18, 19, 23, 24, 31, 33, 38–41, 44]. These criteria included velocity profiles on different locations and a difference of <5% in calculations of pressure, velocity, or WSS. In 18 of the 34 papers, a mesh independence test was not performed or at least not mentioned. Three studies applied an element size determined by a mesh independence test performed on a different geometry [17, 21, 30]. The number of elements for the final mesh varied between 30,000 and 4 million.

3.5. Boundary Conditions

3.5.1. Inlet. Table 3 shows all the used inlet and outlet boundary conditions in the included papers. The inlet boundary conditions were pulsatile in 23 and constant in 11 papers. The most common inlet boundary condition was flow rate (l/min) followed by velocity and pressure in 18, 10, and four studies, respectively. In two studies, an electrical system was applied at the inlet [14, 26]. The inlet conditions were patient-specific in seven papers [12, 16, 27, 39–41, 43]. In these studies, the stroke volume as well as the waveform was patient-specific. These conditions were mostly obtained by MRI or invasive measurements during cardiac catheterization. In five studies, a patient-specific stroke volume was implemented but with a general waveform [25, 30, 32, 37, 45]. This waveform was scaled to a cardiac index suitable for the analyzed geometry. In the other 23 studies, a general inlet boundary condition was used.

In 13 papers, the applied velocity profile was specified. This was a flat or plug flow velocity profile in six and a parabolic profile in three studies [12, 16, 17, 19, 22–24, 28, 34]. Three articles implemented a Womersley flow at the inlet, and one study used a patient-specific velocity profile obtained by phase-contrast MRI [32, 39–41]. However, most studies did not mention the kind of velocity profile they used on their inlet.

3.5.2. Outlet. The most applied outlet boundary condition was a constant pressure outlet. 14 studies used a variation of this condition, i.e., atmospheric pressure, zero pressure, or the mean PA or aortic pressure obtained by cardiac catheterization [15, 16, 18–22, 25, 27–30, 39, 43]. In one study, a
pulsatile pressure on the LPA outlet was implemented while a Womersley velocity profile was set on the RPA outlet [40]. In another study, the outflow boundary condition was defined by the LPA : RPA flow split [42]. In five papers, the three-element Windkessel model was imposed to the outlet [32–34, 37, 45]. The pure resistance strategy was used in five studies [23, 24, 31, 41, 44]. Spilker et al. described a method for the impedance boundary condition in which they reconstructed a one-dimensional (1D) anatomy and calculated the impedance value for the pulmonary anatomy [12]. One study applied multiple outlet boundary conditions and compared results. These included zero pressure, constant pressure, prescribed flow split, and a lumped parameter model [17]. In two papers, the outlet boundary conditions were not specified [13, 38].

Patient-specific information was used to calculate resistance and Windkessel values in four papers [16, 27, 31, 32, 37, 40, 41, 45]. For this, i.e., the flow split derived from flow perfusion scans, pressure from catheterization, and cardiac output from catheterization or echocardiography were taken. The other authors estimated values based on more general information.

3.6 Vessel Wall Compliance. In nine of the included papers, FSI was used to simulate deformation of the vessel wall during the cardiac cycle [12, 14, 15, 19, 20, 32, 35, 37, 45]. One of these groups applied case-specific compliance [20]. Here, the mesh was subdivided in five regions. Young’s modulus for each region was obtained by stretch testing the tissue of freshly harvested porcine pulmonary roots. These values were then imposed to the in silico geometry of the porcine pulmonary roots. No studies were available using patient-specific compliance in human cases. The eight other groups assumed a global and constant value for the compliance of the artery wall. The highest Young modulus was 5 × 10^7 Pa, and the lowest 2.6 × 10^6 Pa [19, 32]. One group implemented a Young modulus varying between 2.6 and 4.2 × 10^6 Pa [37]. They tuned the value until the computed outcomes matched the desired patient-specific outcomes. The wall thickness was assumed to be between 0.5 and 1.5 mm. In one article, a variable thickness of 10% of the diameter of the vessel was applied [14]. Four articles specified the Poisson ratio used. These were, respectively, 0.42, 0.45, 0.49, and 0.5 [14, 19, 35, 37].

3.7 Numerical Setup. The program most used for solving the numerical cases was ANSYS Fluent (ANSYS Inc. Canonsburg PA, USA). This software package was utilized by 12 groups included in this review [16, 18, 19, 21, 23–25, 27, 30, 40, 42, 44]. Other mentioned software included CFD-ACE + (ESI group, Paris, France) and SimVascular (http://simvascular.org) and ABAQUS (Simuleon, ’s-Hertogenbosch, the Netherlands). Four groups calculated their solution with special build-in-house software [12, 14, 35, 36]. In nine papers, the software was not specified [13, 26, 31, 33, 34, 37, 41, 43, 45].

3.7.1 Fluid Characteristics. In 29 of the 34 included papers, blood was assumed to behave as a Newtonian fluid while in one paper, it was assumed to be a non-Newtonian fluid [40]. Three papers did not specify the assumption they made [13, 34, 37]. In most studies, the blood density was set to be 1060 kg/m^3. Only three studies assigned a different density of 1050 kg/m^3 and 1000 kg/m^3, respectively [33, 35, 40]. In nine papers, the used density was not described. Viscosity was mostly assumed to be 0.004 kg/ms [12, 14, 15, 17, 21, 22, 28–30, 33, 39, 41, 42, 45]. Other imposed values were 0.0035 kg/ms, 0.003 kg/ms, and 0.00371 kg/ms [25, 26, 35, 38, 43, 44]. Four authors applied a varying viscosity number [16, 18, 36, 40]. One of them varied the viscosity of blood between 0.003 and 0.008 kg/ms depending on hematocrit levels varying between 30 and 55% [16]. Two authors used the Carreau model to capture the varying viscosity of blood depending on the shear rate [18, 40]. The last one analyzed the stability of their algorithm with varying viscosity numbers [36].

3.7.2 Number of Cardiac Cycles Simulated. As 10 studies were performed with a constant inlet flow, the number of simulated cardiac cycles here is irrelevant. In 11 of the other 24 papers, the number of simulated cycles was specified [12, 14, 17, 18, 32, 35, 36, 38–41]. In the majority of these studies, four cardiac cycles were calculated [12, 32, 38, 39, 41]. The minimal and maximal number of simulated cycles was, respectively, one and five [14, 17].

3.7.3 Time Step Size. Information on time step size for the simulation was provided in 13 papers [12, 14, 18, 30, 32, 33, 35, 36, 38–42]. The value varied between 0.0001 and 0.015
Table 4: Characteristics of included papers.

| Author + year       | Anatomy   | Mesh sensitivity | Mesh element number | Inlet BC          | Outlet BC           | Wall compliance | Fluid rheology |
|---------------------|-----------|------------------|---------------------|-------------------|---------------------|-----------------|----------------|
| Ascuitto et al. 2017 [27] | Angiography | No               | UN                  | Pressure           | Pressure            | No              | Newtonian      |
| Berdajs et al. 2015 (1) [28] | Not patient-specific | No               | 365,000             | Mass flow          | Pressure            | No              | Newtonian      |
| Berdajs et al. 2015 (2) [29] | Not patient-specific | No               | 365,000             | Mass flow          | Pressure            | No              | Newtonian      |
| Boumpouli et al. 2020 [17] | Not patient-specific | No               | 90,000-125,000      | Velocity           | Pressure, flow split, lumped parameters | No              | Newtonian      |
| Caiazzo et al. 2015 [33] | MRI       | Yes              | 158,000-670,000     | Pressure           | Lumped parameters   | No              | Newtonian      |
| Celestin et al. 2015 [16] | Angiography | Yes              | 1,000,000           | Pressure           | Pressure            | No              | Newtonian      |
| Chern et al. 2008 [38] | Not patient-specific | Yes              | 72,900              | Velocity           | UN                  | No              | Newtonian      |
| Chern et al. 2012 [39] | MRI       | Yes              | 1,000,000           | Velocity           | Pressure            | No              | Newtonian      |
| Corno et al. 2006 [13] | Not patient-specific | No               | Mass flow           | UN                 | No                  | UN              |                |
| Das et al. 2011 [40] | MRI       | Yes              | 150,000-650,000     | Womersley profile  | Pressure/Womersley profile | No              | Non-Newtonian  |
| Esmaily-Moghadam et al. 2015 [14] | Not patient-specific | Yes              | 400,000             | Lumped parameters  | Lumped parameters   | Yes             | Newtonian      |
| Guibert et al. 2014 [34] | MRI       | No               | UN                  | Mass flow          | Lumped parameters   | No              | UN            |
| Gundelwein et al. 2018 [32] | CT        | No               | 60,000              | Mass flow          | Lumped parameters   | Yes             | Newtonian      |
| Kato et al. 2018 [30] | CT        | No               | 2,000,000           | Mass flow          | Pressure            | No              | Newtonian      |
| Kong et al. 2017 [38] | CT        | No               | UN                  | Mass flow          | No traction         | No              | Newtonian      |
| Kang et al. 2019 [35] | CT        | No               | 1,000,000           | Velocity           | No traction         | Yes             | Newtonian      |
| Lashkarinia et al. 2018 [19] | Not patient-specific | Yes              | UN                  | Velocity           | Pressure            | Yes             | Newtonian      |
| Liu et al. 2020 [31] | CT        | Yes              | 3,723,041           | Mass flow          | Resistance          | No              | Newtonian      |
| Matthews et al. 2011 [20] | CT        | No               | 1,000,000           | Pressure           | Pressure            | Yes             | N/A           |
| Migliavacca et al. 2002 [15] | Not patient-specific | Yes              | 30,000-48,000       | Mass flow          | Pressure            | Yes             | Newtonian      |
| Miyaji et al. 2019 [21] | CT        | No               | 1,000,000           | Mass flow          | Pressure            | No              | Newtonian      |
| Mosbahi et al. 2014 [22] | Not patient-specific | No               | 365,000             | Mass flow          | Pressure            | No              | Newtonian      |
| Piskin et al. 2017 (1) [23] | CT        | Yes              | 1,007,223           | Velocity           | Resistance          | No              | Newtonian      |
| Piskin et al. 2017 (2) [24] | Not patient-specific | Yes              | 1,135,156           | Resistance          | Resistance          | No              | Newtonian      |
| Rao and Menon 2015 [25] | CT        | No               | UN                  | Mass flow          | Pressure            | No              | Newtonian      |
| Spilker et al. 2007 [12] | MRI       | No               | UN                  | Mass flow          | Impedance           | Yes             | Newtonian      |
| Tang et al. 2011 [41] | MRI       | Yes              | 1,500,000           | Mass flow          | Resistance          | No              | Newtonian      |
| Tomov et al. 2019 [18] | CT        | Yes              | >200,000            | Velocity           | No traction         | No              | Newtonian      |
| Waniewski et al. 2005 [42] | CT        | Yes              | 120,000-150,000     | Velocity           | Mass flow           | No              | Newtonian      |
| Yang et al. 2016 [37] | CT        | No               | UN                  | Mass flow          | Lumped parameters   | Yes             | UN            |
| Yang et al. 2017 [44] | CT        | No               | UN                  | Mass flow          | Lumped parameters   | Yes             | Newtonian      |
| Zhang et al. 2016 [43] | CT        | Yes              | 600,000             | Mass flow          | Pressure            | No              | Newtonian      |
| Zhang et al. 2019 [26] | CT        | No               | UN                  | Lumped parameters  | Lumped parameters   | No              | Newtonian      |
| Zhang et al. 2020 [44] | CT        | Yes              | 1,969,627           | Mass flow          | Resistance          | No              | Newtonian      |
seconds per step. In three papers, only the total number of
time steps was specified. This varied between 256 and 16000
time steps for four cardiac cycles [12, 38, 41]. A time-step
independence test was performed in one study [40].

3.7.4. Convergence Criteria. The used convergence criteria
were presented in 13 papers [14, 15, 17, 19, 23, 24, 30, 35,
36, 38, 39, 42, 44]. In most of these studies, convergence cri-
tera were set at $10^{-4}$ [14, 35, 36, 38, 39]. The used conver-
gence criteria varied between $10^{-3}$ and $10^{-7}$ [15, 42].

3.8. Computational Time. The computational time for the
cases was described in six papers. The reported time per case
varied between a couple of hours up to 1-2 months [21, 23,
35, 38, 39, 41]. In one paper, the difference in computational
time for the same case with a different number of cores was
shown. With the use of "supercomputers," computational
time was reduced to a couple of hours for highly complex
cases [35].

3.9. Results and Validation. The results presented in the
included papers varied according to the research question
proposed. In most papers, two or three numerical outcomes
were presented, i.e., pressure and WSS or streamlines and
proposed. In most papers, two or three numerical outcomes
included. The results presented in the

3.9. Results and Validation. The results presented in the
included papers varied according to the research question
proposed. In most papers, two or three numerical outcomes
were presented, i.e., pressure and WSS or streamlines and
flow rates. In the majority of the papers, figures showed the
results of the peak systolic and one or two diastolic time
steps. Velocity and WSS were the results most reported
followed by, respectively, pressure, streamlines, and flow
rates. Pressure outcomes were presented either by the peak
systolic numbers and energy loss over a stenosis or as the
time-pressure curve over the cardiac cycle.

In nine papers, clinical data of the included patients was
used to validate the CFD results (Table 4) [12, 19, 27, 32,
33, 37, 39, 40, 45]. In seven of these papers, one hemody-
namic outcome was validated [12, 19, 27, 32, 33, 37, 39,
45]. These were flow results in four, pressure in two papers,
and regurgitation fraction in one paper. One paper verified
pressure as well as flow rate results [40]. In all the papers val-
ifying computational pressure outcomes, cardiac catheteri-
ization data was used as the golden standard. In three
papers, the absolute numbers of diastolic and systolic pressure
outcomes were presented and validated [12, 27, 32].
The invasively measured pressure curve was compared to
the computational pressure curve in one study [40]. Other
sources for validation were cardiac MRI or lung perfusion
scans. With data from these sources, flow rate, flow split,
and regurgitation fraction outcomes were validated. In one
paper, the source of validation of the flow rates was not spec-
ified [33]. One paper verified wall deformation results of a
non-patient-specific case using an experimental mock-loop
setup [19]. In the 26 other papers, there was no comparison
between CFD outcomes and clinical data.

4. Discussion

The use of advanced imaging modalities to describe the
hemodynamic impact of PA stenosis is increasing. CFD is
one of these techniques providing detailed visualization of
patient-specific hemodynamics. The aim of this paper was
to review the numerical methods and—clinical—validation
of CFD for evaluation of PA’s in biventricular CHD. All of
the papers included in this review emphasize the importance
of hemodynamic evaluation of the PA’s in biventricular
CHD. They show the use and feasibility of CFD for this pur-
purpose and the wide variety of applications of the technique,
i.e., for surgical or interventional treatment planning,
research on complications, and exercise simulation. How-
ever, this review also shows limitations of the current avail-
able literature.

The literature reveals a large diversity in the setup for the
numerical analysis of PA stenosis. This heterogeneity is
important as variations in the numerical case setup signifi-
cantly influence the outcomes. Results of patient-specific
analysis are highly dependable on the source and quality of
the anatomic reconstruction. In addition, small differences
in the applied inlet or outlet boundary conditions can have
a major impact. Outcomes of WSS and velocity can differ
up to 30% with different boundary conditions [46–49]. In
the included papers for this review, 10 different sources for
anatomic reconstruction were used and 10 different methods
were identified for the definition of the inlet boundary condi-
tions. The largest variety however is seen in the definition
of outlet boundary conditions. The 34 papers described 17 dif-
ferent approaches to assign outlet boundary conditions with
very limited use of complete patient-specific boundary con-
ditions. In the majority of cases, assumptions or generaliza-
tions defined inlet and or outlet boundary conditions. In
several papers, key methodological information was missing.
This included missing information on mesh size (23/34),
number of cardiac cycles simulated (15/34), and convergence
criteria (21/34).

The heterogeneity, assumptions, and generalizations in
the computational setup result in uncertainties regarding the
outcomes. The validation of methods and results is there-
fore of major importance. It provides direct feedback on the
used methods and increases confidence in the reliability of
the technique. This review shows that the level of validation
of the CFD outcomes is very low. Studies with the main
aim to validate CFD outcomes were completely missing,
and only nine of the 31 papers compared their outcomes to
clinical data. This lowers the translational value of the
studies.

Another important limitation for the clinical utility of
CFD is the computational time. This was reported to be as
long as several days to even months per case. However, more
and more progress is made in speeding up the computational
process. By use of “super computers,” improved algorithms,
and cloud-based environments, the simulation time can be
significantly reduced. Great examples of these efforts are
shown by the two papers of Kong et al. included in this
review. They show how the use of multiple cores and adjust-
ment of algorithms can decrease computational time with
several hours [35, 36]. This can be expected to further
decrease in the coming years.

5. Conclusion

The aim of this review was to evaluate the available literature
on numerical analysis of the PA’s in biventricular CHD. The
focus was on the used methods and the rate of—clinical—validation of the outcomes. To the best of our knowledge, this is the first review evaluating the different strategies for numerical studies of the PA’s. The included literature shows the wide variety of applications of CFD and emphasizes the added value of numerical studies for hemodynamic assessment of the PA’s. However, this review also shows the large heterogeneity in used methods in all parts of the numerical setup and little validation of the results. This limits the current clinical utility of CFD. To increase the translation towards clinical use, standardization of the methodologies is desirable. Future research should therefore be pointed towards validation of methods of numerical studies.

Conflicts of Interest
The authors declare that there is no conflict of interest regarding the publication of this paper.

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