Effect of using different approximation models to the exact Mohr–Coulomb material model in the FE simulation of Anchor Foundations in sand

A. S. M. Riyad1*, Md. Rokonuzzaman1 and Toshinori Sakai2

Abstract
Singlarities in the Mohr–Coulomb (MC) yield criterion create numerical difficulties when implemented in the finite element model (FEM). In this research, a two-dimensional (2D) and a three-dimensional (3D) elasto-plastic FEM coupled with isotropic strain hardening–softening or simple strain-softening law incorporating non-associated flow rule including shear band, is used to investigate the effect of singularities, embedment, shape, soil frictional as well as dilation angle on vertically uploaded shallow anchor foundations buried in Toyoura sand. Mohr–Coulomb–Drucker Prager (MC–DP) model provides a more appropriate solution than Drucker Prager–Drucker Prager (DP–DP) model. Besides, the peak resistance factor and the settlement at the ultimate capacity have been found as the functions of embedment, shape, and sand density. Also, the numerical model gives satisfactory agreement with the previous studies. In particular, a simple strain-softening model cannot capture the settlement behavior of anchor foundations in sand efficiently.

Keywords: Dilation angle, Embedment, Frictional angle, Rounded corner, Shape, Singularities

Introduction
Anchors and anchoring system usage techniques are widely used in the world in different fields of civil engineering to resist vertical or horizontal uplift forces or overturning moments acting on the structures, such as transmission towers, sheet piles, retaining walls, deepwater offshore developments, airport hangars, wind loads on tall structures, buoyancy forces on buried underwater pipelines, earthquake, ice forces at different embedment, sizes and shapes [18]. Since the pullout capacity of anchors is greatly influenced by anchor geometry and local soil conditions, many studies have focused on these important factors [16, 17, 19, 20, 22, 35, 51].

However, the settlement behavior of anchor foundations is overlooked by most of the researchers due to the shortcomings of the models to predict the real soil behavior. Furthermore, traditional design approaches are based solely on the peak friction angle ($\phi_p$)
and principle of associated flow (AF) rule, which overestimate the foundation capacity in soils [10, 13, 17, 24, 30, 34, 36, 46, 49, 55]. According to the study of Bolton [5], the $\phi_p$ is controlled by the critical state friction angle ($\phi_c$) and dilation angle ($\psi$). Besides, several studies have shown that the value of $\phi_c$ and the relationship between ($\phi_p - \phi_c$) and $\psi$ depend on the sand type [8, 29, 48]. Therefore, $\phi_p$ alone cannot uniquely predict the uplift capacity of anchors in sand. Moreover, Kumar and Kouzer [26] have studied the effect of embedment ratio (H/D) and $\phi_p$ on the pullout capacity of plate anchors in the sand and found that the pullout capacity increases with the rise of H/D and $\phi_p$. Besides, Rowe and Davis [41] used FEM to analyze a strip anchor in sand and found that the dilatancy could significantly influence the ultimate pullout resistance.

Despite the availability of complex soil models for advanced applications, Mohr–Coulomb (MC) yield criterion is widely used in the elasto-plastic geotechnical analysis due to its simplicity in application. In particular, some limitations creating barrier in its extensive application. Most of the cases, the intermediate principal stresses are neglected, and the MC criterion is expressed as a function of major (normal stress) and minor (shear stress) principal stress. However, in practical cases, the influence of intermediate principal stresses are predominant to determine the yield strength of the material [1, 9, 25, 37]. Another problem is that there are six sharp corners and tip which create singularity problems in the numerical implementation, particularly at axial symmetry conditions, whereas, the yield curve is in the form of an irregular hexagon on deviatoric ($\pi$) plane with fastigium and wracking [25, 50]. For that reason, to eliminate the computational difficulties, the apex and edges of the MC yield surface should be smoothed or rounded or special algorithmic treatment is needed [23]. Consequently, different types of techniques are proposed by numerous researchers to solve this problem for the smooth approximation of MC yield surface, for example, Drucker–Prager model, Mogi criterion, Twin Shear Unified criterion, SMP criterion, Zienkiewicz–Pande criterion, Williams–Warnke model, Gudehus–Argyris model, Rubin smooth function [4, 14, 27, 31–33, 37, 42, 58–62].

A numerical study by Walters and Thomas [56], considering the sandbox experiment, have shown that non-associated strain-softening and mobilized dilatancy are important parameters to determine the propagation of localized failure surfaces above trapdoors in the sand. In this regard, Sakai and Tanaka [43, 44] simulated the shear band proliferation precisely, in their two-dimensional (2D) anchor using a non-associated strain hardening–softening model with a shear band effect and nonlinear mobilized dilatancy in the elasto-plastic framework.

However, Meyerhof and Adams [36] proposed an empirical correction factor (“Shape factor”) to the peak uplift load for the rectangular anchor, calculated based on plane strain assumptions, as a function of embedding ratio only. Also, Dickin [11] and Frydman and Shaham [15] proposed the same as a function of embedment and aspect ratio. Besides, Murray and Geddes [38] and Vermeer and Sutjiadi [54] recommended simplified design equations and Ovesen and Strømann [40] proposed empirical design charts for isolated anchors.

In this study, a rigorous numerical model incorporating strain hardening–softening or strain-softening law with the shear-band effect is used to examine the implications of the implementation of different approximate models and rounding parameter to the
exact MC model considering anchor foundations buried in the sand of different densities ranging from dense to loose. Drucker–Prager (DP) model is used as a potential surface for fitting the MC law because of the availability of different cone parameters in the DP model to approximate the MC hexagon on the π-plane. The MC material model can be fitted into the inner and outer apices [39]. Also, design graphs are developed by some parametric studies on shapes, embedment, frictional, and dilatation angles. The results of numerical predictions are also compared with the classical bearing capacity equations.

**Experimental procedures**

The experimental setup used for this study is shown in Fig. 1. A cylindrical container having a diameter of 590 mm is used as a soil bin to neglect the boundary effects. At the time of experiments, two types of flat anchor foundations (circular and rectangular) are considered. The diameter (D) of the circular anchor for this study is 10 cm at an embedment ratio (H/D, where H = depth of sand mass) of 2 having the plate thickness of 5 mm. However, the width (B) of the rectangular anchor is 5 cm at an aspect ratio (L/B, where L = length) of 1 to 6 and embedment ratio (H/D) of 2. Each anchor is installed at the bottom of the soil bin. The data of vertical pullout load at pulling out speeds of 0.003 cm/min and upward displacement are recorded by a load cell, connected with an anchor rod and a displacement transducer is installed on the top of the anchor rod respectively with the help of a computerized data acquisition system. All movement of the anchor is operated by a direct current (DC) motor until the residual conditions are achieved. Air-dried uniform Toyoura sand (specific gravity (G_s) = 2.64, effective diameter of particle

![Testing apparatus](image)
(D50) = 0.016 cm, maximum void ratio (εmax) = 0.98, minimum void ratio (εmin) = 0.61, and no fine content less than 0.00075 cm) is used in this test. The air pluviation method is used to build up the ground above anchor foundations with the help of two sieves through the raining device. The experiment is conducted on the sand of different uniform densities which are achieved by differing falling height and deposition density. To evaluate the uniformity of the sand mass, the density of the ground is measured by using six 100 cc cylindrical samplers (D = 5 cm), which are placed on the bottom of the soil bin. In this study, three different types of sand (dense having a density of 1630 kg/m³; medium having a density of 1480 kg/m³; loose having a density of 1350 kg/m³, error allowance = ±10 kg/m³) having a relative density of 95% to 5% are used. The experimental failure mechanisms are presented in Fig. 2a, considering the circular anchor [3, 12] and Fig. 3a, considering the rectangular anchor.

Numerical modeling

Four node quadrilateral isoparametric finite elements are used for analyzing the circular anchor problems as illustrated in Fig. 2b for 2D FE analysis. The mesh extends at least at a distance of four times the diameter of the circular anchor from the edges to neglect the boundary effects. In the center part of the model, the discretization is finer with quadrilateral elements than at the edges, where finite deformation is expected. To obstruct out-of-plane displacements of the central vertical symmetrical boundaries, the mesh base is fixed in all three coordinate directions, except in the anchor plate area, and zero-displacement boundary conditions are introduced. Besides, along the anchor boundary until failure, differential quasi-elastic displacement is applied at small sequential increments and the corresponding nodal forces are averaged.

Fig. 2 Experimental failure mechanism and FE mesh for circular anchor: a Experimental failure mechanism, and b FE mesh (H/D = 2, D = 10 cm, and the number of elements = 2400)
concerning the displacement control nodes to ascertain the pullout capacity (P). In case of 3D FE simulations, first-order cubic hexahedral finite elements are used for analyzing the problems of a rectangular anchor. By taking the benefits of symmetry, one-quarter of the domain is discretized into finite elements as illustrated in Fig. 3b. The discretization is finer in the central zone (zone above the anchor and extending to H from the anchor edges, using 5 mm sided cubic hexahedral elements) than the edges due to the same reason as described for 2D FE analysis. The mesh extends at least at a distance of two times the depth of sand mass from the edges of the rectangular anchor and one time above the anchor to neglect the boundary effects [7]. More elements are used for longer anchors in the longitudinal direction to maintain the uniformity of element size across the models, for example, square anchor with \( L/B = 1 \) consists of 12,288 elements, and the rectangular anchor with \( L/B = 6 \) consists of 21,888 elements (which is approximately 1.5 times more than that of the square anchor). The normalized displacement factor, \( \delta/D \) or \( \delta/B \), and the pullout resistance
factor, \( N_p = \delta_d HA \), \( \delta_d \) is the effective unit weight of dry sand and \( A \) is the anchor surface area) are ascertained by following the recommendations of Lindsay [28]. The numerical models use the nonlinear elasticity [21], non-associated flow rules (DP potential and MC yield surface), sophisticated strain hardening–softening [44, 52] or simple strain softening constitutive law [56] in an elasto-plastic framework including the shear band [44]. Both types of material models are available for 2D analysis while only the simple strain-softening model option is available in the personally developed FORTRAN program for 3D analysis. An explicit dynamic relaxation (DR) method [45, 52] devised with the generalized return mapping algorithm [47] is used due to its robust ability to handle bifurcation problems of extremely nonlinear material; due to its explicit nature needs very small data storage and easy to be coded; use of approximate critical damping for linear isoparametric elements with reduced integration can inherently inhibit the hourglass modes at failure. This study focuses on the effect of different approximate models to the exact MC material model in the finite element method, such as DP approximation (Table 1); Argyris et al. [2]; and rounding parameter (lode angle) on the anchor (Fig. 4). The lode angle, \( \theta \) can be introduced as

### Table 1 Drucker–Prager approximation to Mohr–Coulomb model

| Parameters | Compression cone \( \theta = +\frac{\pi}{6} \) | Extension cone \( \theta = -\frac{\pi}{6} \) | Internal cone \( \theta = \tan^{-1}\left(\frac{\sin \phi}{\sqrt{3}}\right) \) | Plane strain cone | Compromise cone |
|------------|---------------------------------|---------------------------------|---------------------------------|-----------------|-----------------|
| \( \alpha \) | \( 2 \sin \phi \) \( \sqrt{3 - \sin \phi} \) | \( 2 \sin \phi \) \( \sqrt{3 - \sin \phi} \) | \( \frac{\sin \phi}{\sqrt{3 - \sin \phi}} \) | \( \tan \phi \) | \( \frac{2 \sin \phi}{\sqrt{3 - \sin \phi}} \) |
| \( \gamma \) | \( \frac{6c \cos \phi}{\sqrt{3 - \sin \phi}} \) | \( \frac{6c \cos \phi}{\sqrt{3 - \sin \phi}} \) | \( \frac{3c \cos \phi}{\sqrt{3 - \sin \phi}} \) | \( \frac{5c}{\sqrt{9 + 12 \tan^2 \phi}} \) | \( \frac{6c \cos \phi}{\sqrt{3 - \sin \phi}} \) |

If Drucker–Prager function is chosen as the potential function for its differentiability with other or Mohr–Coulomb yield criteria (generalized elasto-plastic model), in that case, \( \phi \) must be replaced by dilatation angle, \( \psi \).
\[ \theta = \frac{1}{3} \sin^{-1} \left( \frac{3\sqrt{3}J_{3D}}{2J_{2D}^2} \right) \] (1)

where \( J_{3D} \) = third deviatoric stress invariants and \( J_{2D} \) = second deviatoric stress invariants.

The MC and DP yield functions can be written in a general form using a function, \( g(\theta) \), which determines the shape of the yield surface on the deviatoric plane as

\[ f(\sigma, \kappa) = \alpha I_1 + \sqrt{J_2} \frac{g(\theta)}{g(0)} - \gamma = 0 \] (2)

where \( \alpha = \frac{2 \sin \phi}{\sqrt{3(1 - \sin \phi)}} \), \( \gamma = \frac{6c \cos \phi}{\sqrt{3(1 - \sin \phi)}} \), and the function, \( g(\theta) \), is such that \( g\left( \frac{\pi}{6} \right) = 1 \), like shape function, and this function determines the shape of the \( \pi \)-section. For instance, for MC, it becomes

\[ g(\theta) = \frac{(\cos \frac{\pi}{6} - \sin \frac{\pi}{6}) \sin \phi}{\sqrt{3}} = \frac{3 - \sin \phi}{2\sqrt{3}(\cos \theta - \sin \theta \sin \phi)} \] (3)

If now the values of \( \alpha, \gamma, \) and \( g(\theta) \) are put in Eq. (2), it will regenerate the invariant form of the MC yield function. For smoothing the corners at \( \theta = \pm \frac{\pi}{6} \) in the MC’s \( \pi \)-section as defined by Eq. (3), this function can be written as [2], graphic is shown in Fig. 5.

\[ g(\theta) = \frac{2K}{(1 + K) - (1 - K) \sin 3\theta} \] (4)

where \( g\left( -\frac{\pi}{6} \right) = K \) and to match with MC failure criteria, the value of \( K \) can be calculated using Eq. (3) as

\[ K = \frac{\sqrt{J_2}(\text{at } \theta = -\frac{\pi}{6})}{\sqrt{J_2}(\text{at } \theta = +\frac{\pi}{6})} = \frac{3 - \sin \phi}{3 + \sin \phi} \] (5)

If \( K = 1 \), Eq. (4) will generate \( g(\theta) = 1 \), which leads the circular \( \pi \)-section and no dependence of third stress invariant (i.e. DP model).

To find the inscribed circle, the value of \( \theta \) at which this circle is tangential to the MC hexagon can be found by differentiating Eq. (3) for \( \theta \) and setting the result to zero to have

\[ \theta = \tan^{-1} \left( \frac{\sin \phi}{\sqrt{3}} \right) \] (6)

Substituting this value in Eq. (3), we can have the value of \( g(\theta) \) of the inscribed circle as shown in Fig. 5. According to Fig. 5, extension cone and compression cone are defined to match the MC model either in triaxial extension or triaxial compression. Compromise cone is the average of compression cone and extension cone. However, an internal cone is inscribed into the MC [57]. Besides, another popular DP approximation to the MC criterion is obtained by forcing both criteria to predict identical collapse loads under plane strain conditions.
Different approximations to the Mohr–Coulomb material model

The material parameters used for the analysis are summarized in Table 2. The effect of intermediate principal stresses is neglected in the MC criterion, which contradicts the fact that uniaxial compressive strength is always smaller than biaxial compressive

| Parameters                              | Dense | Medium | Loose |
|-----------------------------------------|-------|--------|-------|
| Density (kg/m³)                         | 1630  | 1480   | 1350  |
| Void ratio, e                           | 0.62  | 0.78   | 0.95  |
| Relative density, Dᵢ                    | 0.95  | 0.53   | 0.05  |
| Coefficient of shear modulus, G₀        | 500   | 500    | 500   |
| Residual frictional angle, φᵣ (degrees) | 33    | 33     | 33    |
| Poisson's ratio                         | 0.3   | 0.3    | 0.3   |
| εᵣ                                      | 0.1   | 0.1    | 0.1   |
| εᵣ                                      | 0.1   | 0.4    | 0.8   |
| εₙ                                      | 0.3   | 0.3    | 0.3   |
| m                                       | 0.1   | 0.2    | 0.4   |
| β                                        | 0.1   | 0.1    | 0.1   |
strength for soils. As the strains predicted by the MC model are conservative, this model does not capture the strain-softening behavior which is found in natural soils. Conversely, the DP model considers the effect of intermediate principal stresses. Figure 6
shows the different approximations to the exact MC material model in the finite element method using a sophisticated strain hardening–softening model at H/D = 2 and D = 10 cm. It is observed that MC–DP model, where MC represents yield surface and DP is the potential failure surface, gives better results compared with the Mohr–Coulomb–Mohr–Coulomb (MC–MC), Argyris–Argyris, Drucker Prager–Drucker Prager (DP–DP) (different matching) material model (in all cases, the preceding portion indicates yield surface and the latter part points out potential failure surface) which proves its appropriateness to use it in this study.

Effect of rounding of Mohr–Coulomb material model
As the singularities or the corners and the apex of the MC yield surface caused problems in the numerical implementation, an approximate yield surface with smoothed or rounded corners has to be used (Fig. 4). The singularities in the yield surfaces, where the gradient concerning the stresses is undefined, occur at θ = ±30°. According to Borst [6], the solution is difficult to obtain in MC condition. To verify this, MC condition with pseudo-equilibrium element is used. The material parameters for this study are already shown in Table 2. Figure 7 that presents the effect of the rounding parameter (θT) considering the anchor problem at the sand of different densities. In the MC–DP model, the solution is obtained even at the time of the Lode angle limit being 29.0°, and even the result is better than that obtained using the DP–DP model. However, the success of using the popular DP yield surface highly depends on the proper selection of a matching parameter to agree with the MC yield surface condition.

Parametric study
The effect of embedment, shape, frictional, and dilatation angle on the pullout capacity of circular or rectangular anchor foundations buried in the sand of different densities have been studied through model tests and extensive FEM analysis.

Effect of embedment ratio
Figure 8 presents the numerical relationship between the pullout resistance and displacement factor for different H/D in different layers of sand using the material parameters shown in Table 2. All curves show three distinct phases: the initial phase (the uplift resistance increased with the displacement of the anchor), followed by the decreasing tendency of uplift resistance with the displacement of anchor, and finally, the uplift resistance remains unaltered with the further uplifting of the anchor (residual state). It is observed that the uplift capacity and displacement factor depend on H/D and H. However, the numerical passive plastic zone is more developed at peak load at the higher embedment (Fig. 9). Besides, peak load mobilization at lower displacement (stiffer response) is noticed at the smaller embedment. Furthermore, peak resistance and displacement factor increase with the increment in embedment ratio, whereas peak resistance factor increases and displacement factor decreases with the increase in density of sand, which is attributed to the increase in confining pressure (Fig. 10).
Shape effect (3D modeling)

The width (B) of the foundation buried in dense Toyoura sand is used in this study is 5 cm at an aspect ratio (L/B) of 1 to 6 and embedment ratio (H/B) of 2. The material
parameters used for the analysis are summarized in Table 3. However, a satisfactory agreement is found between the experimental and numerical pullout resistance–displacement factor relationships. The rate of softening after the peak is decreasing with
the increase in aspect ratio (Fig. 11). The relationship between mobilized peak resistance factor ($N_{pu}$) and $L/B$ considering rectangular anchor buried in the sand of different densities is presented in Fig. 12. The shear resistance along vertical planes plays an important role in increasing resistance factors of anchor foundations with a lower aspect ratio. The peak resistance factor is a combined function of $L/B$, $B$, and $H/B$ as well as relative density, which violates the non-robust empirical shape factor used in traditional design. However, it decreases rapidly with the increase of $L/B$. Moreover, displacement is not well predicted due to the use of a simple strain-softening model.

Effect of peak frictional and dilation angle (using simple strain softening model)
Dilatancy of sand depends on density and stress level. When the density of sand is dense with low-stress level, it demonstrates shear dilation and when loose with the high-stress level it often exhibits shear contraction. The dilation angle perspective to zero degrees relates to a soil distorts plastically with zero volume change, which is a reasonable supposition for loose sands [41]. Here, the dilation angle is assumed from 0° to 45° in

![Plastic deformation zones above the anchor in dense sand (figures are not to scale): a H/D = 1, and b H/D = 6](image)
Table 3  Parameters for simple strain softening material model

| Parameters                          | Dense  | Medium | Loose |
|-------------------------------------|--------|--------|-------|
| Density (kg/m$^3$)                  | 1630   | 1480   | 1350  |
| Void ratio, $e$                     | 0.62   | 0.78   | 0.95  |
| Relative density, $D_r$             | 0.95   | 0.53   | 0.05  |
| Coefficient of shear modulus, $G_0$ | 500    | 500    | 500   |
| Peak frictional angle, $\phi_p$     | 45     | 38     | 33    |
| Dilation angle, $\psi$             | 20     | 10     | 0     |
| Residual frictional angle, $\varphi_r$ (°) | 33     | 33     | 33    |
| Poisson's ratio                     | 0.3    | 0.3    | 0.3   |
| $B$                                 | 0.5    | 0.5    | N/A   |
| $C$                                 | 0.5    | 0.5    | N/A   |
| $D$                                 | 0.5    | 0.5    | N/A   |

N/A not applicable

Fig. 10  Relationship between a Peak resistance factor, and b displacement factor as a function of H/D
analyzing the influence of dilatancy. The uplift capacity of vertically uploaded circular anchor foundations with H/D varying from 1 to 6 has been simulated where $\phi$ ranges from 30° to 45° and $\psi$ from 0° to 45°. Figures 13 and 14 show the values of $N_{pu}$ to peak frictional and dilation angle at H/D = 1 to 6, respectively. The uplift capacity increases significantly with the peak frictional and dilation angle and the effect of dilatancy becomes greater with the increase of frictional angle and embedment ratio. Greater uplift capacity is obtained for a greater dilation angle when the embedment ratio and frictional angle are kept constant. When H/D = 2, $\phi = 30^\circ$ and $45^\circ$, the uplift capacity in the case of $\psi = 30^\circ$ is about 1.5 and 4 times the values in the case of $\psi = 0^\circ$, respectively. When H/D = 6, $\phi = 30^\circ$ and $45^\circ$, the uplift capacity in the case of $\psi = 30^\circ$ is about 1.7 and 8.8 times of the values in the case of $\psi = 0^\circ$, respectively.
Comparison with past studies

Figure 15 shows the different studies to determine the peak resistance factor as a function of $H/B$ in dense sand. Besides, Fig. 16 shows different studies on the shape effect of rectangular anchor in dense sand at $H/B = 2$. The dimensionless shape factor $S$ can be defined as
The effect of shape diminishes with the increase of aspect ratio, gradually decreased to reach the strip anchor condition at $L/B = \infty$. The experimental result [53] of the analogous trapdoor with the same width is used for the strip anchor. According to Fig. 17, with the increase of peak frictional angle, the peak resistance factor is increased significantly.

$$S = \frac{N_{pu}(\text{Rectangular Anchor})}{N_{pu}(\text{Continuous Anchor})}$$

Fig. 14 Effect of dilation angle on breakout factors for various $H/D$ ($D = 10 \text{ cm}$): $a$ $H/D = 1$, $b$ $H/D = 2$, $c$ $H/D = 3$, $d$ $H/D = 4$, $e$ $H/D = 5$, and $f$ $H/D = 6$
Fig. 15  Peak resistance factor as a function of H/B (B = 10 cm) by different studies

Fig. 16  Shape effect by different studies (H/B = 2, B = 5 cm)

Fig. 17  Effect of frictional angle by different studies at H/B = 2 (B = 10 cm)
It can be reported that the numerical model presents a very close agreement with past studies.

Conclusions

The numerical models used in this research work demonstrate their appropriateness to closely predict the experimental uplift resistance–displacement relationships of vertical anchor problems in the sand. MC–DP model gives better results compared to the MC–MC, Argyris–Argyris, DP–DP (different matching) which proves its appropriateness to use it in this study. Conversely, it is required to verify the MC–DP model for other boundary value problems and soil type. The bearing capacity of the anchor foundation decreases with the increase of aspect ratio and increases with the increase of embedment. Furthermore, the settlement at the ultimate bearing capacity of the anchor foundations always increases with the increase of embedment and it cannot be well predicted by using a simple strain-softening model. Also, it is reported that the numerical model provides a very close agreement with past studies.

Authors’ contributions

The corresponding author ASMR performed all numerical simulations, drew all the curves of the graphs, and drafted the manuscript. MR provided numerical values of the parameters of the materials model, which have been deduced from experimental tests. TS reviewed and edited the writing of this manuscript. All authors read and approved the final manuscript.

Competing interests

The authors declare that they have no competing interests.

Author details

1 Department of Civil Engineering, Khulna University of Engineering & Technology, Khulna, Bangladesh. 2 Department of Environmental Science and Technology, Graduate School & Faculty of Bioresources, Mie University, Tsu, Mie, Japan.

Received: 8 July 2018   Accepted: 29 June 2020

Published online: 04 August 2020

References

1. Al-Ajmi AM, Zimmerman RW (2005) Relation between the Mogi and the Coulomb failure criteria. Int J Rock Mech Min Sci 42(3):431–439
2. Argyris J, Faust G, Szimmat J, Warnke E, Willam K (1974) Recent developments in the finite element analysis of prestressed concrete reactor vessels. Nucl Eng Des 28(1):42–75
3. Balla A (1961) The resistance to breaking-out of mushroom foundations for pylons. In: Proc 5th international conference on soil mechanics and foundation engineering, Balkema, Rotterdam, Netherlands, pp 569–576
4. Bardet J (1990) Lode dependences for isotropic pressure-sensitive elastoplastic materials. J Appl Mech 57(3):498–506
5. Bolton M (1986) The strength and dilatancy of sands. Geotechnique 36(1):65–78
6. Borst RD (1986) Non-linear analysis of frictional materials. Ph.D. thesis, Delft Univ Tech, Netherlands
7. Bray JD, Seed RB, Seed HB (1989) The effects of tectonic movements on stresses and deformations in earth embankments. National Science Foundation, Earthquake Engineering Research Center, University of California, Berkeley
8. Cho GC, Dodds J, Santamarina JC (2006) Particle shape effects on packing density, stiffness and strength: natural and crushed sands. J Geotech Geoenviron Eng 132(5):591–602
9. Colmenares LB, Zoback MD (2005) A statistical evaluation of intact rock failure criteria constrained by polyaxial test data for five different rocks. Int J Rock Mech Min Sci 39(6):695–729
10. Davis EH (1968) Theories of plasticity and the failure of soil masses. In: Lee IK (ed) Soil mechanics-selected topics. American Elsevier, New York, pp 341–380
11. Dickin EA (1998) Uplift behavior of horizontal anchor plates in sand. J Geotech Eng 114(11):1300–1317
12. Dickin EA, Leung CF (1985) Evaluation of design methods for vertical anchor plates. J Geotech Eng 111(4):500–520
13. Drescher A, Detournay E (1993) Limit load in translational failure mechanisms for associative and non-associative materials. Geotechnique 43(3):443–456
14. Drucker DC (1952) A more fundamental approach to plastic stress–strain relations. In: Proc. 1st US national congress for applied mechanics, ASME, pp 487–491
15. Frydman S, Shahami I (1989) Pullout capacity of slab anchors in sand. Can Geotech J 26(3):385–400
16. Ghaly A, Hanna A (1992) Stresses and strains around helical screw anchors in sand. Soils Found 32(4):27–42
17. Ghaly A, Hanna A (1994) Ultimate pullout resistance of single vertical anchors. Can Geotech J 31(5):661–672
18. Hanna A, Foriero A, Ayadat T (2015) Pullout capacity of inclined shallow single anchor plate in sand. Indian Geotech J 45(1):110–120
19. Hanna A, Ranjan G (1992) Pullout-displacement of shallow vertical anchor plates. Indian Geotech J 22(1):55–62
20. Hanna A, Rahman F, Ayadat T (2011) Passive earth pressure on embedded vertical plate anchors in sand. Acta Geo 61(1):21–29
21. Hardin BO, Black W (1968) Vibration modulus of normally consolidated clay. Proc Am Soc Civ Eng 94(SM2):353–359
22. Harvey R, Burley E (1973) Behavior of shallow inclined anchorages in cohesionless sand. Ground Eng 6(5):48–55
23. Hofstetter G, Taylor R (1991) Treatment of the corner region for Drucker–Prager type plasticity. Zeitschrift für angewandte Mathematik und Mechanik 71(6):589–591
24. Ilamaruthi K, Dickin E, Muthukrishnaiyah K (2002) Experimental investigation of the uplift behaviour of circular plate anchors embedded in sand. Can Geotech J 39(3):648–664
25. Jiang H, Xie Y (2011) A note on the Mohr–Coulomb and Drucker–Prager strength criteria. Mech Res Commun 38(4):309–314
26. Kumar J, Kouzer K (2008) Vertical uplift capacity of horizontal anchors using upper bound limit analysis and finite elements. Can Geotech J 45(5):698–704
27. Lin FB, Banzan ZP (1986) Convexity of smooth yield surface of frictional material. J Eng Mech 112(11):1259–1262
28. Lindsay JA (1980) The use of physical models in design. In: Design parameters in geotechnical engineering, Vol 4, BGS, London, pp 524–526
29. Liu Q, Lehane B (2012) The influence of particle shape on the (centrifuge) cone penetration test (CPT) end resistance in uniformly graded granular soils. Géotechnique 62(1):973–984
30. Loukidas D, Chakraborty T, Salgado R (2008) Bearing capacity of strip footings on purely frictional soil under eccentric and inclined loads. Can Geotech J 45(6):768–787
31. Matsuoka H (1974) Stress-strain relationships of sands based on the mobilized plane. Soils Found 14(2):47–61
32. Matsuoka H (1976) On the significance of the “spatial mobilized plane. Soils Found 16(1):119–120
33. Matsuoka H, Hoshikawa T, Ueno K (1998) A general failure criterion and stress-strain relation for granular materials to metals. Soils Found 30(2):119–127
34. Merifield R, Lyamin A, Sloan S (2006) Three-dimensional lower-bound solutions for the stability of plate anchors in sand. Géotechnique 56(2):123–132
35. Meyerhof GG (1973) Uplift resistance of inclined anchors and piles. In: Proc 8th international conference on soil mechanics and foundation engineering, deep foundations, including pile foundations, Moscow, pp 167–172
36. Meyerhof GG, Adams JI (1968) The ultimate uplift capacity of foundations. Can Geotech J 5(4):225–244
37. Mogi K (1971) Fracture and flow of rocks under high triaxial compression. J Geophys Res 76(5):1255–1269
38. Murray EJ, Geddes JD (1987) Uplift of anchor plates in sand. J Geotech Eng 113(3):202–215
39. Mijangos I, O’Kelly KU (2009) Drucker–Prager finite element constitutive model of microindentation in polycrystalline alumina. In: Proc SEM conference on experimental & applied mechanics, Albuquerque, New Mexico, USA, pp 2704–2712
40. Ovesen N, Stрамann H (1972) Design method for vertical anchor slabs in sand. In: Proc specialty conference on performance of earth and earth-supported structures, ASCE, Vol 2, No 1, pp 1481–1500
41. Rowe RK, Davis EH (1982) Behaviour of anchor plates in sand. Géotechnique 32(1):25–41
42. Rubin M (1991) Simple, convenient isotropic failure surface. J Eng Mech 117(2):348–369
43. Sakai T, Tanaka T (2009) Uplift behavior of circular and square anchor foundations in dense sand. Doboku Gakkai Ronbunshi C 65(1):131–137
44. Sakai T, Tanaka T (2007) Experimental and numerical study of uplift behavior of shallow circular anchor in two-layered sand. J Geotech Geoenviron Eng 133(3):202–215
45. Slijepcevic M, Finlay TW, Fadl MO (1982) Uplift capacity of embedded anchors in sand. In: Behaviour of off-shore structures, Vol 1, 2, pp 451–463
46. Slijepcevic M, Finlay TW, Fadl MO (1982) Uplift capacity of embedded anchors in sand. In: Behaviour of off-shore structures, Vol 1, 2, pp 451–463
47. Simo JC, Hughes TJR (1998) Computational inelasticity. Springer, New York
48. Simon B, Housby GT (2006) The direct shear strength and dilatancy of sand-gravel mixtures. Geotech Geol Eng 24(3):523–549
49. Sloan SW (2013) Geotechnical stability analysis. Géotechnique 63(7):531–571
50. Sloan SW, Booker J (1986) Removal of singularities in Tresca and Mohr–Coulomb yield functions. Commun Appl Numer Methods 2(2):173–179
51. Sutherland HB, Finlay TW, Fadl MO (1982) Uplift capacity of embedded anchors in sand. In: Behaviour of off-shore structures, Vol 1, 2, pp 451–463
52. Tanaka T, Kawamoto O (1988) Three-dimensional finite element collapse analysis for foundations and slopes using dynamic relaxation. In: Proc 6th international conference on numerical methods in geomechanics, Innsbruck, pp 1213–1218
53. Tanaka T, Sakai T (1993) Progressive failure and scale effect of trap-door problems with granular materials. Soils Found 33(1):11–22
54. Vermeer PA, Sutjiadi W (1986) The uplift resistance of shallow embedded anchors. Int J Numer Anal Methods Geomech 1:57–87
55. Verweij AS (1971) Breakout resistance of objects embedded in ocean bottom. J Soil Mech Found Div 97(9):1183–1205
56. Walters. N, Thomas. JN (1982) Shear zone development in granular materials. In: Proc 4th international conference on numerical methods in geomechanics, Edmonton, pp 263–274
57. Wang G, Sitar N (2004) Numerical analysis of piles in elasto-plastic soils under axial loading. In: Proc 17th ASCE engineering mechanics conference, University of Delaware, Newark, pp 1–8
58. William KJ, Warnke EP (1975) Constitutive model for the triaxial behavior of concrete. In: Proc international association for bridge and structural engineering, Vol 19, pp 1–30
59. Yu MH (2004) Unified strength theory and its applications. Springer Science & Business Media, Berlin
60. Yu MH (2006) Generalized plasticity. Springer Science & Business Media, Berlin
61. Yu MH, Zan YW, Zhao J, Yoshimine M (2002) A unified strength criterion for rock material. Int J Rock Mech Min Sci 39(8):975–989
62. Zienkiewicz O, Pande G (1977) Some useful forms of isotropic yield surface for soil and rock mechanics. Finite Elem Geomech, pp 179–190

Publisher’s Note
Springer Nature remains neutral with regard to jurisdictional claims in published maps and institutional affiliations.