The geometry of the magnetic field in the Central Molecular Zone measured by PILOT

A. Mangilli, J. Aumont, J.-Ph. Bernard, A. Buzzelli, G. de Gasperis, J.B. Durrive, K. Ferrier, G. Foënard, A. Huguet, A. Lacour, R. Misawa, L. Montie, B. Moi, I. Ristorcelli, H. Rousseau, P. Ade, D. Alin, P. de Bernardi, E. de Gouveia Dal Pino, J.P. Dubois, C. Enge, P. Hargrave, R. Laureijs, Y. Longva, B. Maffei, A.M. Magalhães, C. Martí, S. Mas, J. Montel, F. Pajot, L. Rodríguez, M. Salatino, M. Saccoccia, S. Stever, J. Tauber, C. Tibbs, and C. Tucker

(Affiliations can be found after the references)

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ABSTRACT

We present the first far infrared (FIR) dust emission polarization map covering the full extent Milky Way’s Central molecular zone (CMZ). The data, obtained with the PILOT balloon-borne experiment, covers the Galactic Center region $-2^\circ < \ell < 2^\circ$, $-4^\circ < b < 3^\circ$ at a wavelength of 240 μm and an angular resolution 2.2′. From our measured dust polarization angles, we infer a magnetic field orientation projected onto the plane of the sky that is remarkably ordered over the full extent of the CMZ, with an average tilt angle of $\sim 22^\circ$ clockwise with respect to the Galactic plane. Our results confirm previous claims that the field traced by dust polarized emission is oriented nearly orthogonal to the field traced by GHz polarized and has a spectral index consistent with synchrotron radiation, leading to their denomination as non-thermal radio filaments (NRFs) or NTFs).

The long and thin shape of NRFs strongly suggests that they follow magnetic field lines. This suggested alignment is confirmed by the measured radio polarization angles (corrected for Faraday rotation), which indicate that, in the plane of the sky, the magnetic field inside NRFs is indeed oriented along their long axes (e.g., Tsuboi et al. 1985, 1986; Reich 1994; Lang et al. 1999). From this, it has been concluded that the magnetic field in the CMZ is approximately vertical (i.e., perpendicular to the Galactic plane), at least close to the plane. At larger distances from the plane, the orientation of NRFs tends to lean outwards (i.e., away from the vertical), consistent with the magnetic field having an overall poloidal geometry (Morris 1990).

Following the initial discovery of the NRF phenomenon, many new NRFs have been identified in the CMZ. By plotting the sky distribution of all the (confirmed and likely candidate) NRFs detected at 20 cm, Yusef-Zadeh et al. (2004) observed that only the longer NRFs are nearly straight and aligned with the vertical; the shorter NRFs exhibit a broad range of orientations, with only a loose trend toward the vertical. This could indicate that the magnetic field in the CMZ is not as ordered as initially claimed, and that it has a significant fluctuating component.

Faraday rotation measurements (RMs) toward NRFs provide valuable information on the magnetic field in the diffuse ion-
ized medium near the GC, Novak et al. (2003) collected all the available RMs toward NRFs within $1^\circ (< 150$ pc) of Sgr A* and, by doing so, they showed that there is a clear pattern in the sign of RMs, such that RM $> 0$ in the North-East and South-West quadrants and RM $< 0$ in the North-West and South-East quadrants. These authors argued that the observed RM pattern could be explained by the model of Uchida et al. (1985), in which an initially vertical magnetic field is sheared out in the azimuthal direction by the differential rotation of the dense clouds present near the Galactic plane.

A different RM pattern was obtained by Roy et al. (2005), who measured the RMs of 60 background extragalactic sources through a $12^\circ$ × $4^\circ$ window centered on Sgr A* and found mostly positive values, with no evidence for a sign reversal either across the rotation axis or across the midplane. Roy et al. (2008) pointed out that this RM distribution is consistent with either the large-scale Galactic magnetic field having a bisymmetric spiral configuration or the magnetic field in the central region of the Galaxy being oriented along the Galactic bar.

More relevant to the present paper, far-infrared (FIR) and sub-millimeter (submm) polarization studies of dust thermal emission make it possible to probe the orientation, in the plane of the sky, of the magnetic field inside dense molecular clouds.

FIR polarimetry of the innermost ($\sim 3$ pc diameter) GC region was first performed by Werner et al. (1988), who detected linear polarization of 100 $\mu$m emission from three locations in the inner circumnuclear ring (CNR). At each location, they measured polarization angles $\sim 90^\circ - 100^\circ$, implying a mean magnetic field oriented at $\pm 10^\circ - 10^\circ$ East of North, i.e., within $\pm 10^\circ - 20^\circ$ of the plane of the CNR. Since the CNR is thought to be in differential rotation, they concluded that its mean magnetic field must be predominantly azimuthal (with respect to its rotation axis). Finally, from the measured polarization fractions, they inferred that the magnetic field has a turbulent component comparable to the mean azimuthal field.

As a follow-up to the work of Werner et al. (1988), Hildebrand et al. (1990) measured the linear polarization of the 100 $\mu$m emission at six positions in the CNR, along the main FIR emission ridge, and they confirmed that the mean magnetic field is approximately parallel to the plane of the CNR. Hildebrand et al. (1993) then expanded the set of 100 $\mu$m polarization measurements to cover not only the main FIR emission ridge, but the whole area of the CNR. A few of their observed positions happen to fall inside the area of the Northern streamer. By analyzing the corresponding polarization measurements, Hildebrand & Davidson (1994) found that the magnetic field runs parallel to the axis of the streamer along its entire length, i.e., out to a projected distance $\sim 4$ pc from Sgr A*.

The first submm polarimetric observations of the GC region were carried out by Novak et al. (2000). They targeted three separate $5$ pc × $5$ pc areas, centered on the CNR and on the peaks of the M$-0.02-0.07$ and M$-0.13-0.08$ molecular clouds, respectively, and in each area they detected linear polarization of the 350 $\mu$m emission. For the CNR, they inferred a mean magnetic field orientation that is approximately north-south, in good overall agreement with the FIR results. In M$-0.02-0.07$, the field appears to have two distinct behaviors: upstream of the Sgr A East shock, it runs nearly perpendicular to the Galactic plane, while downstream it closely follows the curved ridge of shock-compressed material. In M$-0.13-0.08$, the field is on average parallel to the long axis of the cloud, with a spiky structure toward the CNR, which suggests that the field has been stretched out by the tidal forces that gave the cloud its elongated shape.

Novak et al. (2003) observed a much larger, 170 pc × 30 pc, area around Sgr A*. Their 450 $\mu$m polarization map clearly shows that the magnetic field threading molecular clouds is, on the whole, approximately parallel to the Galactic plane. To reconcile the horizontal field measured in molecular clouds with the poloidal field traced by the NRFs, Novak et al. (2003) proposed that the large-scale magnetic field in the GC region is predominantly poloidal in the diffuse ISM and predominantly toroidal in dense regions along the Galactic plane, where it was sheared out in the azimuthal direction by the differential rotation of the dense gas.

Chuss et al. (2003) performed additional 350 $\mu$m polarimetric observations toward 8 selected areas within the central 50 pc. These measurements, combined with those of Novak et al. (2000), offer a broader and more complete view of the magnetic field morphology in the GC region, which conveys the general impression that the field is globally organized on scales much larger than the typical sizes of molecular clouds, while also being subject to strong local distortions by environmental forces such as shock compression and tidal shearing. Chuss et al. (2003) also found that the measured magnetic field orientation depends on the molecular gas density, being generally parallel to the Galactic plane in high-density regions and generally perpendicular to it in low-density regions.

Near-infrared (NIR) polarization observations of starlight extinction by dust also offer a promising tool to trace the magnetic field orientation in dense regions near the GC. Nishiyama et al. (2009) obtained a NIR polarization map of a 50 pc × 50 pc area centered on Sgr A*. Compared to earlier NIR polarimetric observations toward the GC (e.g., Eckart et al. 1995; Ott et al. 1999), they were able, for the first time, to separate out the contribution from foreground dust and to isolate the polarization arising within $\sim (1 - 2)$ kpc of Sgr A*. They inferred that the distribution of polarization angles exhibits a strong peak in a direction nearly parallel to the Galactic plane, in good agreement with the results of FIR/submm polarimetry. However, in contrast to Chuss et al. (2003), Nishiyama et al. (2009) found no indication that the magnetic field orientation depends on gas density – the field appears to be everywhere horizontal, including in the diffuse ISM.

All sky maps of the thermal dust and synchrotron polarized emission have been obtained with the Planck satellite at wavelengths above 850 $\mu$m (353 GHz) and angular resolution above $5^\prime$. These maps obviously include the Galactic center region, but no specific study of this region was discussed in the literature. The analysis of the all-sky map of thermal dust polarization at 850 $\mu$m (Planck Collaboration et al. 2015c) has clearly shown the existence of large variations of the polarization fraction from unexpectedly large values (up to $p \approx 20\%$) occurring essentially in the diffuse ISM, down to very low values occurring mostly on line-of-sights (LOS) with larger column densities. Over most of the sky included in the analysis, which avoided the Galactic plane (usually $|b| < 5^\circ$), the variations of $p$ appeared tightly anti-correlated with the polarization angle dispersion function ($S$) which measures the rotation of the observed field around a given sky location. This indicates that the intrinsically large dust polarization fraction is efficiently modulated by the $B$-field twisted geometry resulting in efficient depolarization of the signal both in the beam and along the LOS. Planck Collaboration et al. (2015a) showed that this behaviour is expected from MHD simulations of the ISM. These properties were confirmed in the latest analysis of the all-sky Planck data at 353 GHz based on the latest Planck data release in Planck Collaboration et al. (2018a), which also studied departures from the $p - S$ anti-correlation in details. They showed that the departures are unlikely to reflect...
large variations of the dust alignment efficiency up to a column density of \(N_H = 2 \times 10^{22} \text{ cm}^{-2}\). However, this analysis excluded regions near the Galactic plane \((|b| < 2^\circ)\), and therefore the Galactic center discussed here. The main reason for avoiding the Galactic plane and in particular the inner Galactic regions was to avoid very long line-of-sight through the plane were many B-field reversal are likely to happen, which could have affected the trend with column density. An additional difficulty comes from specific systematic effects which could be affecting data near the plane, such as band-pass mismatch and/or contamination by molecular lines (such as the CO lines) in the Planck photometric bands.

In this context, the PILOT data bring useful information regarding both the structure of the magnetic field and the physics of dust. First, the angular resolution of the instrument \((2.2')\) is higher than that of the Planck data, which helps following the field structure into small and/or distant objects, while the large instantaneous field-of-view of the instrument allows mapping large regions, allowing to bridge high resolution ground-based observation which often suffer from a limited sky coverage. Second, the data obtained with the PILOT instrument operating at 240 \(\mu\)m will allow, in conjunction with polarization data obtained at longer wavelength, to constrain the polarization SED of thermal dust with a large lever arm, which is an important constraint for dust models. Finally, the systematic effects affecting the PILOT data are likely to be of a different nature than that relevant for other instruments, which will help the analysis and interpretation of the polarized signals when co-analysis is possible.

In this paper, we present the map of polarized dust emission in the CMZ obtained at 240 \(\mu\)m by the PILOT balloon-borne experiment. The PILOT observations cover a 4 \(\times\) 6 degree field centred at \((l, b) = (0, 0)\) (we refer to this observed field as “LO” in the rest of the article), a much wider field than all previous observations of polarized FIR emission in the GC region. The PILOT maps reveal the projected magnetic field structure across the whole CMZ with an angular resolution of 2.2', i.e. with 2.3 times better linear resolution or 5 times more spatial information than the 353 GHz polarization data obtained by Planck.

The paper is organized as follows. In Sect. 2 we describe the observing strategy. The PILOT data processing is described in Sect. 3 including an overview of how we construct Stokes \(I, Q\) and \(U\) maps by using two map-making software packages (ROMA and SCANAMORPHOS) in Sect. 3.3. In Sect. 3.2 we present the polarization results focusing on the polarization angles, we discuss the polarization maps in Sect. 3.4, in Sect. 4.2 we validate them by comparing the results of the two independent map-making procedures and in Sect. 4.3 we compare our measurements with the ones obtained with the Planck satellite. We discuss the results in Sect. 5.1 focusing on the relevance of the CMZ in Sect. 5.2 on the magnetic field orientation in Sect. 5.2 and on the magnetic field strength in Sect. 5.3. We investigate the relationship between the magnetic field structure in the CMZ measured by PILOT and recently proposed models for gas orbits in the Galactic Centre in Sect. 5.4 using a model for the Milky Way’s magnetic field that we describe in Appendices [A]. We discuss the comparison of our results with previous ground measurements in Sect. 5.5. We summarize our conclusions in Sect. 6.

To aid discussion, a schematic diagram identifying key features of the CMZ that we refer to in this paper, overlaid on a map of the PILOT 240 \(\mu\)m intensity, is presented in Figure 1. Throughout the paper, we quote polarization angles in the GAL-COSMO convention (i.e. clockwise from Galactic North when looking at the source). We employ the acronym POS to describe quantities and structures that are projected onto the plane of the sky (e.g. the orientation of the magnetic field that is accessible via dust polarization measurements, which elsewhere in the literature is sometimes denoted as \((\langle B_\perp \rangle)\), and the common acronym LOS to mean line-of-sight.

2. PILOT Observations

PILOT observations of the GC region were obtained during the second flight of the PILOT balloon experiment, which took place from Alice Springs, Australia, as part of the 2017 French Space Agency (CNES) balloon campaign. A complete description of the PILOT instrument is presented in [Bernard et al. (2016)], while the performance of the PILOT instrument during the Alice Springs flight is described in [Mangilli et al. (2018)].

The data presented in this paper were obtained during four consecutive observing tiles while the target field was at elevations between 16.5 and 56°. The total duration of the observations was \(\approx 32\) min, including time for slewing and calibrations at the end of individual scans. The temperatures of the TRANS and REFLEX focal planes during the observations were stable, 304.96 ± 0.04 mK and 309.07 ± 0.03 mK respectively. The median balloon altitude was 39.8 km, with peak-to-peak variation between 39.7 and 39.9 km. The four observing tiles used four distinct positions of the half wave-plate (HWP) in order to uniformly sample polarization analysis directions as projected on the sky. Each of the observing tiles was configured to scan the target region at a different angle, with a median scan speed of 11.8 arcmin/s and a median scan leg duration of 13 s.

These scan directions were chosen to be preferentially perpendicular to the Galactic plane, while at the same time providing sufficiently varied directions for efficient destriping during map-making (see Sect. 3.5). The consequence of this observing strategy is that the elevation varies during scans, which causes variations of the signal due to emission from the residual atmosphere (see Sect. 3.4). In Sect. 3.3 we describe how we use the elevation-dependent variations across the whole flight to obtain a focal plane map of the individual detector responses.

3. Data processing

3.1. Time constant correction

The procedure that we used to estimate the time constants of the bolometers is described in [Mangilli et al. (2018)]. In summary, we use a combination of in-flight measurements of the internal calibration source (ICS) and of strong glitches detected throughout the flight to derive the time constants of both the ICS and of individual bolometers, which we assume to be constant throughout the flight. The timeline of each bolometer was then deconvolved from the corresponding time constant in Fourier space.

The bolometer time constants are at most \(\sim 1\) sample (= 25 ms) and we estimate our knowledge of their value to be accurate within \(\sim 2\) msec.

3.2. Pointing reconstruction

The pointing of each detector can be computed given the Estadius stellar sensor information, the offset between the Estadius and PILOT optical axes and a description of the PILOT focal plane geometry.

The Estadius stellar sensor [Montel et al. (2018)] data provides the pointing quaternion at a frequency of 4 Hz with an accuracy
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Fig. 1: Upper panel: Map of the Galactic central molecular zone obtained with the PILOT experiment at 240 µm. The color scale shows the total intensity in log scale. The overlaid texture based on the line integral convolution (Cabral & Leedom 2000) shows the orientation of the magnetic field projected on the plane, inferred from the measured dust polarization. Lower panel: Intensity as above, overlaid with total intensity contours at 0.1, 0.2, 0.5, and $1 \times 10^5$ MJy/sr. The circles show the location of the 100-pc twisted ring as defined in Molinari et al. (2011). The filled symbols are discussed in Sect. 5.4. The names of key molecular regions are overlaid.

of ≃ 5 arcsec in both directions and ≃ 15 arcsec in field rotation. During the observations of the CMZ region presented here, the performances of the Estadius sensor were optimal. The offset between the Estadius and the PILOT optical axes was found to vary during flight, due to thermal and mechanical deformation of the instrument. This offset was monitored during the whole flight using bright sources. For that purpose, we used total intensity maps of individual observing tiles of the PILOT data obtained using the SCANAMORPHOS map-making algorithm (see Sect. 3.5). These maps were obtained using coordinates computed with preliminary Estadius offsets derived during the flight from planet observations. These maps were correlated with Herschel maps of the same sky region at 250 µm for different assumed values of the Estadius offset. The best Estadius offset for each observing tile was derived as the one providing the best Pearson correlation coefficient between the PILOT and Herschel data. Note that three different bright sources were used in the L0 observations to derive Estadius offsets.

A preliminary version of the PILOT focal plane geometry was obtained during ground calibration of the instrument (Bernard et al. 2016). Here, we used all parameters of this determination including the pixel size and array rotation values. However, we refined the detector array position offsets with respect to the PILOT focal plane center using in-flight measurements. For that purpose, we used a similar procedure as for deriving Estadius offsets but applied to maps obtained with data from individual arrays. The offset difference between the individual offsets and the Estadius offsets was adopted as the refined arrays offsets of the focal plane geometry.

The bolometer coordinates used here were derived combining the three quaternions describing the Estadius pointing, the Estadius offset with respect to the PILOT focal plane center and each bolometer location in the focal plane. The Estadius quaternions were interpolated in time to the time corresponding to each data sample, taking into account the time shift between individual detectors within one array caused by the time-multiplexing readout electronics. For a given observing tile, the Estadius offsets were assumed constant. The focal plane geometry was assumed invariant over all observations.

We estimate that the accuracy of the pointing from the differences between pointing reconstruction solutions obtained with different Estadius offsets computed on the various sources used in L0 is ≃ 15 arcsec.
PILOT Collaboration: Galactic center polarization with PILOT

Fig. 2: Calibrated PILOT data for one observing tile during the L0 observations. The upper panel shows the data before atmospheric signal removal. The lower panel shows the data with the atmospheric signal removed as described in Sect. 3.4. In each panel, we show the array-averaged signal in $V$ as a function of time on the TRANS array #6 and REFLEX array #7, from top to bottom. Vertical lines show the extent of individual scans. The modulated signal during calibration sequences on the ICS at some ends of scans is clearly seen.

3.3. Gain calibration

The gain calibration was performed as described in Mangilli et al. (2018). The raw data for each individual bolometer located by its position in the focal plane $(x, y)$, for each observing tile (observed at a time $t_{\text{tile}}$), were divided by a response $R(x, y, t_{\text{tile}})$, computed as:

$$R(x, y, t_{\text{tile}}) = \frac{R_{\text{amo}}(x, y)}{\rho_{\text{ICS}}(x, y)} \rho_{\text{ICS}}(x, y, t_{\text{tile}}),$$

where $R_{\text{amo}}(x, y)$ is a normalized map of the relative response between all detectors, derived from the atmospheric signal averaged over the whole flight. $\rho_{\text{ICS}}$ is the ICS signal averaged over the whole flight and $\rho_{\text{ICS}}(x, y, t_{\text{tile}})$ is the ICS signal averaged over the observing tile. $R(x, y, t_{\text{tile}})$ is allowed to vary during the flight but is assumed to be constant within a given observing tile. This gain calibration strategy assumes that the ICS signal is intrinsically unpolarized.

From the all-flight time statistics on $R$, we estimate that detectors gain inter-calibration is accurate at the percent level Mangilli et al. (2018). The absolute calibration of the data was obtained from the correlation between total intensity maps of L0 with Herschel maps.

3.4. Atmospheric signal subtraction

In order to isolate the astronomical signal from the residual atmospheric emission, we correlate the observed signal of each pixel with the pointing elevation consistent with the pointing solution described in Sect. 3.2. The slope of the correlation is averaged over each observing tile, and the correlated component of the signal is subtracted from the data. The top panel of Fig. 2 shows the time evolution of the average signal measured on the five PILOT arrays for one observing tile before subtraction of the residual atmospheric emission for an observing tile scanned with decreasing elevations. We can see that the timeline signal increases as the elevation decreases. In the bottom panel of Fig. 3.4, the atmospheric signal has been cleaned and the timeline shows a flat baseline.

3.5. Map-making

3.5.1. PILOT measurements

The PILOT signal can be expressed as described in Mangilli et al. (2018) for a given bolometer at a position $(x, y)$ in the focal plane:

$$m = R_{xy}T_{xy} \times [I \pm Q \cos(2\theta) \pm U \sin(2\theta)] + O_{xy},$$

where $R_{xy}$ and $T_{xy}$ are the system response and optical transmission respectively, and $O_{xy}$ is an arbitrary electronics offset. For
the configuration of the HWP and analyzer in the PILOT instrument, the \( \pm \) sign is + and – for the REFLEX and TRANS arrays respectively (see Bernard et al. [2016]). \( \theta = 2 \times \omega + \phi \) is the analysis angle. \( \omega \) is the angle between the HWP fast axis direction as projected on the sky and the horizontal direction measured counter-clockwise as seen from the instrument. In practice, the same patch of sky is observed at different times with at least two values of the analysis angle. \( \phi \) is the time varying parallactic angle measured counter-clockwise from equatorial North to Zenith for the time and direction of the current observation. The precise positioning of the HWP fast axis was measured from ground calibration measurements obtained in front of a polarized signal of known polarization direction. From the variations between various calibration sequences, we estimate that \( \omega \) is known to an accuracy of \( \pm 1^\circ \).

The light polarization fraction \( p \) and polarization orientation angle \( \psi \) are then defined as:

\[
p = \sqrt{Q^2 + U^2} \quad \text{(3)}
\]

and

\[
\psi = 0.5 \times \arctan(U/Q). \quad \text{(4)}
\]

The magnetic field orientation is defined by \( \psi \) rotated by 90°. Note that the \( Q \) and \( U \) in Eq. [4] and therefore \( \psi \) are in the IAU convention, i.e., positive counterclockwise on the sky, and measured with respect to Equatorial North (corresponding to \( \psi = 0 \) deg). Comparison to data taken in different convention, such as the Planck data, which are delivered in the COSMO convention with respect to Galactic North, require changing the angle convention (which can be done simply as \( Q = Q' \) and \( U = U' \) and the appropriate coordinate rotation of \( Q \) and \( U \)). In this paper, since we study the orientation of the magnetic field in the Galactic plane, we discuss values of the polarization angles in Galactic coordinates and in the COSMO convention (as defined in the HEALPix software packages [Gorski et al. 2005]). In this paper, we also refer to the angle dispersion function \( S \) which quantifies the regularity of the \( B \) orientation measured defined as ([Planck Collaboration et al. 2015c], see) as

\[
S_\psi(x, \delta) = \frac{1}{N} \sum_{i=1}^{N} (\psi(x) - \psi(x + \delta_i))^2, \quad \text{(5)}
\]

where \( x \) represents the central pixel, and \( \psi(x + \delta_i) \) the polarization angle at a sky position displaced from the centre by the displacement vector \( \delta_i \). The average in Eq. [5] is taken over an annulus of radius \( \delta = \delta_i \) (the “lag”) and width \( \Delta \delta \) around the central pixel and containing \( N \) pixels. \( S \) can be computed at varying angular resolution of the data and with a lag usually ranging from half the data FWHM to arbitrarily large scale, and \( S \) increases with \( \delta \) as the field structure decorrelates with increasing scale.

Inversion of the observed signals to derive sky maps of \( I, Q \) and \( U \) was done through polarization map-making algorithms. We used two different map-making algorithms, SCANAMORPHOS and ROMA, which are described in Sect. 3.5.2 and 3.5.3 respectively. We checked that the two algorithms give consistent results, and used the SCANAMORPHOS maps for the data analysis, which appeared of better quality at the current stage of the processing.

### 3.5.2. SCANAMORPHOS

The SCANAMORPHOS software was initially developed to process on-the-fly data from the PACS and SPIRE bolometer array on-board Herschel (Roussel 2013). The software has subsequently been refined to cope with the dominant atmospheric emission in ground-based observations for different instrument architectures, such as ArTéMiS on APEX (Roussel 2018) and NIKA2 on the IRAM 30-m telescope. It has also been adapted to process the polarization data of PILOT as outlined below. Its core principle is to exploit all the available redundancy in the observations, assuming only that the sky brightness is invariant in time and that the component of the low-frequency noise that is uncorrelated (termed individual drifts or flicker noise in the documents describing the code) has a symmetric probability distribution around zero, without necessarily being Gaussian. The full processing comprises the following tasks, most of them iterative: 1) slicing of scans into distinct scan legs, allowing for a large variability of the scanning speed inherent to balloon observations; 2) baseline subtraction using robust linear fits to the time series of the whole observing blocks, blocks of 4 scan legs, and individual scan legs, over a source mask that is automatically built and updated; 3) destriping using baseline subtraction in which the fits are constrained by the data redundancy, in order to provide a coherent solution for all scan legs and all detectors; 4) masking of glitches detected exploiting the redundancy to avoid masking true sources; 5) subtraction of the average drift on small timescales (i.e., the common mode of both the residual low-frequency noise and the residual atmospheric signal); 6) subtraction of the individual drifts on successively smaller timescales; 7) projection of the corrected data. The definition of the time and space grids used by these tasks and the algorithm are described in the companion paper of the code developed for Herschel.

In order to deal with polarization data, ideally three time series corresponding to the \( I, Q \) and \( U \) Stokes parameters should be considered in the modules subtracting the drifts, instead of a single brightness time series. Even in the absence of noise, the recorded signal at a given location varies as a function of time and detector, due changes in the HWP position, focal plane position and parallactic angle as given in Eq. [2]. However, the noise-free \( I, Q \) and \( U \) series should be invariant. The Stokes parameters are recomputed at each iterative step following the formalism of Eq. [2]. The measured signal at a given time and for a given detector can then in principle be compared to the signal predicted from \( I, Q \) and \( U \) series computed from all the available data. But the signal depends on \( Q \) and \( U \) through sinusoidal terms, whose argument depends on time and detector. To avoid modulating the errors on \( Q \) and \( U \) when computing signal averages or differences, we proceed in a slightly different way, by subtracting the simulated \( Q \) and \( U \) terms from the measured signal to generate a “noised intensity” time series, that can be directly compared to the simulated intensity. In case where there is not enough redundancy in the analysis angles for a given pixel, i.e. when these are distributed over fewer than 4 separate groups, \( Q \) and \( U \) are not computed and the total intensity is equated to twice the average signal. This occurs only on the edges of the maps. In practice, the initial data are too noisy to allow meaningful estimates of the Stokes parameters, leading us to perform the first few drift subtraction steps as if the data were not polarized (i.e. assuming \( Q = U = 0 \)). It is only when the major part of the average drift has been subtracted that we take polarization into account.

For the observations discussed here, the data was taken in a way such that three observing tiles out of four were taken with roughly the same scan direction, the fourth tile being taken roughly in the orthogonal direction. We have explored the possibility of modifying the reference \( I, Q, U \) maps in the SCANAMORPHOS destriping module. These are normally com-
computed from the whole data at the previous iteration of the de-striping, but it is possible to lower the weight of some tiles, or to provide independent maps from simulations, for example. We have not used this option for the present work. Given the median scan speed and the sampling rate of the data, the fiducial value of the noise stability length is 1.5 times the beam FWHM, and we have set it to twice the FWHM to increase sample statistics. The structure of the magnetic field inferred is shown in Fig. 5. The uncertainty on the polarization angle are also shown in Fig. 5. These maps are discussed in Sect. 4.

3.5.3. ROMA

The ROMA code, described in de Gasperis et al. (2016), was developed for cosmology experiments aiming at measuring the polarization of the Cosmic Microwave Background (CMB). For this reason it is optimized for noise dominated timelines. The code assumes stationarity of the noise statistical properties, which is reasonably the case for the data of PILOT flight#2 (see Mangilli et al. 2018). Under the assumption of a Gaussian and stationary noise, the ROMA code adopts a Fourier-based, preconditioned conjugate gradient iterative method to solve for the maximum-likelihood signal map yield by the Generalized Least Square (GLS) approach (see de Gasperis et al. 2016 for details).

In particular, given the pointing matrix $A$ and the timeline vector $D$, the optimal GLS solution for the signal estimate $\tilde{S} = (I, Q, U)$ is:

$$\tilde{S} = (A^\top N^{-1} A)^{-1} A^\top N^{-1} D,$$  \hspace{1cm} (6)

where $N \equiv \langle n, n' \rangle$ is the noise covariance matrix in the time domain $(n, n')$ indicates the instrumental noise at time $t$). Notice that the matrix $N$ is block diagonal only in case of no noise cross-correlation.

The PILOT timelines of the four galactic center region observations are provided to the code after gap-filling of calibration sequences at the ends of scans using a white noise realization with the white noise level of each detector. The glitches are also masked and the atmospheric contribution is removed as described in Sect. 3.4.

In order to ensure that the signal is noise dominated, we subtracted from the observed timeline a simulated timeline based on the Planck 353 GHz total intensity map extrapolated to the PILOT frequency. The subtracted component is assumed unpolarized and is therefore equal on the TRANS and REFLEX detectors apart for possible pointing mismatch. The difference timeline is processed through ROMA with 100 iterations that are enough to ensure a good convergence. The map used for the signal subtraction is added back to the resulting total intensity map. The noise covariance matrix provided to the ROMA code was determined from the PILOT observations of the BICEP field obtained during the same flight {Mangilli et al. 2018}, treated in the same way as the L0 data. The map resolution is set to $N_{side} = 2048$ (1.7 arcmin). The code also provides maps of the variances on the Stokes parameters as well as a map of the inverse conditioning matrix allowing to assess if a sufficient number of data taken at different HWP angles are available for a given pixel. The pixel inverse condition number (ICN) is defined as the ratio of the absolute values of the smallest and largest eigenvalue of the preconditioning matrix, and provides a good tracer of the errors in the map due to a non ideal angle coverage on the given pixel (a value of ICN $\leq 0.5$ means uniform angle coverage). In our case, pixels with ICN $\leq 10^{-2}$ are removed from the analysis.

The $I, Q, U$ maps obtained are shown in Fig. 5. Due to the difficulty of accurately modelling the noise covariance matrix, in particular the off-diagonal terms that are not included in the analysis, the quality of the ROMA polarization maps is degraded and residuals stripes are still present, in particular in the $Q$ map.

Fig. 3: PILOT maps of the $I, Q, U$ parameters obtained towards the galactic center region, processed using the SCANAMORPHOS software. The maps are shown at the full resolution of the instrument of 2.2 arcmin. The maps are in units of $10^3$ MJy/sr.
Fig. 4: PILOT maps of, from top to bottom, the total intensity $I$, the polarized intensity $P$, the Stokes $Q$ and $U$ parameters, zoomed on the CMZ region and processed using the SCANAMORPHOS software. The maps are shown at the full resolution of the instrument of 2.2 arcmin. The intensity map is shown in log scale. The maps of $P$, $Q$ and $U$ are in units of $10^3$ MJy/sr.

For this reason we will not use the ROMA maps as the baseline for the analysis. Still, the ROMA maps allow for validation tests of the baseline results, as discussed in Sect. 4.2.

4. Polarization results

4.1. Polarization maps

The final maps of Stokes $I$, $Q$ and $U$ parameters across the full Galactic Center field observed by PILOT are shown in Figure 3. In this paper, we focus on the polarization results for the $\sim 3.1 \times 0.9$ ° CMZ region, for which we show zoomed maps of $I$, $Q$ and $U$ in Figure 4. The corresponding map of the polarization angle $\psi$, calculated according to Equation 4, is shown as an overlay in Figure 5.

A common issue for the interpretation of polarization observations is how the observed polarization angles (and inferred magnetic field structure) projected onto the plane of the sky (POS) correspond to emission regions situated along the line-of-sight. This is especially of concern for observations in the Galactic Plane. In Appendix A, we present a simple model that we have developed to quantify the line-of-sight (LOS) depth through the
Fig. 5: Upper panel: Map of the B-field orientation as derived from the PILOT data using the SCANAMORPHOS software. The total intensity is shown as the color map, in log scale. The B-field orientation is shown as constant length segments orthogonal to the polarization orientation, where $\sigma_\psi < 8^\circ$. Lower panel: Map of the polarization angle uncertainty per beam, in degrees.

Fig. 6: PILOT large scale maps of the I, Q and U Stokes parameters obtained with the ROMA software. The maps are in units of $10^3$ MJy/sr.

Galactic Plane that is probed by our observations. From this model, we conclude that the CMZ makes the dominant contribution to our observed polarization signal towards the Galactic Center. This is qualitatively confirmed by Figure 4, where it is evident that the structure in the PILOT Q and U maps (as well as I) is dominated by well-known emission features of the CMZ, e.g., Sgr B2, the Brick and the 20 km/s cloud (e.g. Kauffmann et al. 2017 and references therein).

What is most striking about the PILOT polarization data for the CMZ is that the polarization angle is relatively uniform across the entire region shown in Fig. 5, with a dominant orientation of $\sim +22^\circ$. This corresponds to a dominant POS magnetic field...
The mean and mode of the polarization angle distributions differ with high uncertainty ($\sigma_{\psi} \simeq 240\degree$) from the overall mean orientation in regions of high brightness e.g., near the Sgr B2, 20 km/s and 50 km/s clouds. We quantify this in Fig. 7 where we show the distribution of polarization angles within regions of increasing 240 $\mu$m intensity in the $I$ map. Polarization angle measurements with high uncertainty ($\sigma_{\psi} > 8\degree$) are excluded from the analysis. The peak of the polarization angle distribution measured for high brightness regions (shown as blue histograms in the top panel) is clearly shifted towards lower values compared to the polarization angles measured in regions of lower intensity. We discuss possible explanation for this trend in Sect. 5.2, where we make a preliminary estimate for the average magnetic field strength in the CMZ based on the POS field structure that we infer from the PILOT dust polarization measurements.

Fig. 7: Dust polarization angles measured in the CMZ as a function of 240 $\mu$m intensity. The top panel shows the polarization angle distributions plotted separately for intervals of increasing 240 $\mu$m intensity in the PILOT $I$ map. The characteristic 240 $\mu$m brightness is indicated using colour, and ranges from $10^{-3}$ MJy/sr (red) to $10^3$ MJy/sr (blue). The bottom panel plots the mean and mode of the polarization angle distributions directly as a function of the 240 $\mu$m intensity.

4.2. Comparison between map-making methods

We take advantage of having two independent map-making methods to compare the polarization angles results obtained with the two pipelines.

Fig. 8 shows the $\psi$ map pixel histograms obtained with the SCANAMORPHOS software and the ROMA software in the signal dominated region defined by $-1.4^\circ < l < 1.8^\circ$ and $-0.1^\circ < b < 0.4^\circ$, $\phi_0^{\text{ROMA}} = 18.37^\circ$, however the ROMA histogram shows a larger dispersion which is due to the poorer quality of the ROMA polarization maps that show residual stripes, in particular in the $Q$ map. As mentioned in Sec. 3.5.3, this is due to the fact that the ROMA map-making strongly depends on the accurate modeling of the detector noise and the noise covariance matrix for the moment does not include the off-diagonal terms linked to the correlated noise between the detectors.

The very good agreement of the polarization angles obtained with two pipelines that rely on very different assumptions and are implemented independently shows the robustness of the results and it is an important test of the quality of the data.

4.3. Comparison with Planck

The Planck satellite experiment observed the whole sky with two instruments, the Low Frequency Instrument (LFI) from 30 to 70 GHz and the High Frequency Instrument (HFI) from 100 to 857 GHz. Among the nine observing bands, seven channels between 30 and 353 GHz measured polarization in addition to intensity with spatial resolutions ranging from 30 to 5 arcmin (Planck Collaboration et al. 2018d). In this paper, we make use of the publicly available Planck 2018 release LFI and HFI maps, described in Planck Collaboration et al. (2018c) and Planck Collaboration et al. (2018d). Planck polarization maps adopt the HEALPix projection scheme (Gorski et al. 2005), in Galactic coordinates, and use the COSMO convention for the definition of the polarization angles. Polarization angles for Planck data are computed from the $Q$ and $U$ maps according to equation (4).

Given that dust emission is optically thin at Planck frequencies as well as 240 $\mu$m, even towards the inner regions of the Galactic plane and that the same population of dust grains is expected to dominate the emission in both wavelength regimes, it is expected that the orientation of the polarization detected with Planck and PILOT should be similar. Different emerging polarization angles could result from emission by specific dust populations with different alignment properties or spatial distribution and varying $B$-field orientation along the line-of-sight. More probably however, differences would result from remaining systematic effects in the PILOT or Planck data. Comparing apparent polarization directions is therefore an important test of the data quality.
Figure 9 compares the B-field orientation measured with PILOT at 240 μm and Planck at 353 GHz. We can see, despite the different resolutions (5 arcmin for Planck 353 GHz and 2 arcmin for PILOT), that there is an overall agreement between the measured polarization directions. It can be noticed on this figure that the Planck polarization angle directions are less homogeneous than the directions measured by PILOT. The difference map of the polarization angle between Planck and PILOT (bottom panel) shows some excursions as large as 45 degrees for some pixels, but are spread around zero, especially along the Galactic plane. We can see on this difference map obvious imprint of the low $N_{\text{side}}$ HEALPix pixels that can be seen in the Planck 353 GHz polarization angle map (and can not come from PILOT maps as they are not projected using HEALPix).

Figure 10 shows the histograms of the polarization orientation observed with PILOT (degraded to a resolution of 5 arcmin, to match Planck highest frequencies’) and Planck (70, 100, 143, 217 and 353 GHz). Histograms are computed from the polarization maps inside a box having $-1.3^\circ < l < 1.8^\circ$ and $-0.4^\circ < b < 0.1^\circ$, corresponding roughly to where the intensity measured by PILOT at 240 μm is larger than 500 μJy/sr. The histogram of the PILOT polarization angle peaks at a value (the Gaussian best fit of the histogram has $\phi_0 = 24.1^\circ$, $\sigma = 5.9^\circ$) very similar to where Planck 217 and 353 GHz histograms peak ($\phi_0 = 21.3^\circ$, $\sigma = 11.3^\circ$ and $\phi_0 = 24.9^\circ$, $\sigma = 12.3^\circ$, respectively), showing that PILOT sees the same dust as Planck at 217 and 353 GHz. The PILOT histogram is narrower than the Planck ones (when PILOT data resolution is degraded to 5 arcmin), highlighting the more homogeneous polarization directions already observed in Fig. 9.

The Planck 100 GHz channel is expected to have an important CO-line contribution towards the Galactic center region and therefore a strong spurious polarization due to spectral mismatch between bolometers. This spurious polarization was corrected for in the Planck 2018 maps, but the correction is known to be inaccurate in this region were the matter velocity can shift the CO-line significantly with respect to other regions of the sky, where the 100 GHz bolometer response to the CO-line was calibrated for spurious polarization correction (Planck Collaboration et al. 2018b). We interpret the mean value of the angle at 100 GHz of $-50^\circ$ to be partially due to this residual spurious polarization. At the other Planck frequencies (70 and 143 GHz), the histograms peak around zero degrees ($\phi_0 = -3.6^\circ$, $\sigma = 15.2^\circ$) and $\phi_0 = 1.5^\circ$, $\sigma = 12.8^\circ$, respectively).

In Fig. 11 we look at the Galactic longitude profile of the Planck and Planck polarization angles, computed in boxes of size $\Delta l = 0.15^\circ$ and $\Delta b = 0.3^\circ$ on either side of the Galactic plane, ranging from $l = -7.5^\circ$ to $l = 7.5^\circ$. We can see that the PILOT data polarization angle profile follows fairly that of Planck 217 and 353 GHz and that the discrepancies between Planck and Planck 217 and 353 GHz is of the same order than that of the discrepancies between those two Planck channels. The global dust polarization profile, traced by Planck and Planck 217 and 353 GHz, shows a polarization angle close to zero (magnetic field projection on the sky along the Galactic plane) from $l = -7.5^\circ$ to $l = 7.5^\circ$, except for a region corresponding to the extent of the CMZ (from $-1^\circ$ to $1.5^\circ$) where the measured angles range from 20 to 30°. At 143 GHz, the polarization angle follows that of the dust outside the CMZ ($l < -1^\circ$ and $l > 1.5^\circ$) but shows completely different behaviour inside, being much closer to zero (as noticed in Fig. 10). This is the hint for another component than dust – presumably synchrotron – dominating the emission in the CMZ at frequencies under 143 GHz.

5. Discussion

5.1. Do PILOT polarization measurements probe the field structure in the CMZ?

Analysis of the Planck satellite dust polarization data has shown that depolarization due to the complex nature of the field structure is omnipresent (see e.g. Planck Collaboration et al. 2015c). This is especially true towards the Galactic plane where the magnetic field is likely to rotate significantly along the line of sight and within the instrument beam as result of variations of the ordered field and turbulence. Even if dust emission is optically thin at the observed frequencies, it is thus not necessarily the case that polarization measurements are sensitive to the emission along the whole line-of-sight, as the signal may suffer significant depolarization.

Here we verify that when observing towards the Galactic center with PILOT, the polarized signal is indeed dominated by the CMZ region. For this, we use a simplified model of the ordered and turbulent distribution of the magnetic field in the Galactic disk. For the dust density distribution, we assume that the Milky Way has a four-armed spiral structure, superimposed on an axisymmetric exponential profile. The model, which is described in Appendix A, is constrained using the observed polarization fraction profile along the Galactic plane obtained from the Planck RC4 data. We use this model to estimate the relative contribution of structures in the Galactic disk along the line of sight towards the region observed with PILOT. We explore three representative regimes: no turbulent field, equipartition between the ordered and turbulent fields, and a turbulent field that is three times stronger than the ordered field. In all cases, turbulence in the disk along the line-of-sight towards the Galactic Center is insufficient to depolarize the dust emission to the low values ($p \approx 0.1-2\%$) that are observed. We conclude that the observed polarization properties are due to emission that is intrinsic to the CMZ. This is qualitatively confirmed by the good correspondence between emission structures in the PILOT total intensity map and the $Q$, $U$ and polarized intensity ($P$) maps of the CMZ (see Fig. 4).

5.2. Uniform orientation of the POS B-field

The orientation of the plane of the sky (POS) magnetic field inferred from the polarization direction measured by PILOT is surprisingly uniform across the $3.1^\circ \times 0.9^\circ$ field presented in this paper (see Sect. 4). In this subsection, we quantify the regularity of the field on linear and not just angular) scales in the CMZ via a comparison with the dispersion in the dust polarization angles in the local ISM measured by Planck. We then consider how the observed regularity of the field can be reconciled with the low fraction of dust polarization that is observed towards this region by Planck, and what we can infer about the large-scale geometry of the field in the Galactic Center region.

The polarization angle dispersion function $S$ quantifies how polarization angles correlate with increasing angular scale (see Eq. 3). In Planck Collaboration et al. (2015c), the large scale distribution of $S$ was studied at an angular resolution of 1° and associated lag of 30 arcmin, since these parameter values mitigate noise bias for an intermediate latitude study. Using the same Planck data product, working resolution and lag as in Planck Collaboration et al. (2015c), we find a median value of $S^{50}(\theta = 30^\circ) = 3.2^\circ$ in the region covered in Fig. 4. This value is close to the median value of $S$ measured over the entire mid-latitude sky by Planck Collaboration et al. (2015c). We emphasize, however, that this apparent agreement does not mean
PILOT Collaboration: Galactic center polarization with PILOT

Fig. 9: Upper panel: Comparison between the $B$-field orientation as derived from the PILOT 240 $\mu$m (red) and Planck 353 GHz (green) dust polarization measurements. The $B$-field orientation is shown as constant length line segments. The background image is the PILOT Stokes I map shown in log scale. Lower panel: map of the angle difference (in degrees) between Planck 353 GHz and PILOT 240 $\mu$m.

Fig. 10: Histogram of the PILOT polarization angles (black) on the galactic center region compared to Planck observations at 70, 100, 143, 217 and 353 GHz (blue, green, yellow, orange and red, respectively). We overplot the Gaussian fits of these histograms as thicker lines to guide the eye.

that the field in the Galactic Center and local ISM have similar structural properties. The dust emission measured by Planck at intermediate latitudes is produced in the relatively nearby ISM (within $\sim 1$ kpc). An angular scale measured at intermediate latitude therefore corresponds to a spatial scale that is $\sim 8$ times smaller than the spatial scale corresponding to the same angular scale measured at the Galactic center. Expressed otherwise, our measurement of $S_{353}(\delta = 30^\circ) = 3.2^\circ$ in the Galactic Center indicates that the POS field structure remains homogeneous over a $\sim 8$ times larger length scale than in the local ISM.

We constructed a map of $S$ from the PILOT data itself. After degrading the resolution of the PILOT data to $5^\prime$ to mitigate noise bias, we obtain a median value of $S_{240}(\delta = 2.5^\prime) = 2.5^\circ$. This value is consistent with the median $S_{353}(\delta = 30^\circ)$ from Planck, considering that it is measured at a smaller lag. We conclude that the POS magnetic field orientation in the GC region is intrinsically more regular than in the nearby ISM.

The analysis of the Planck data demonstrated that there is an anti-correlation between $S$ and dust polarization fraction $p$ (see Fig. 23 of Planck Collaboration et al. 2015c), a relation that can be used to infer the characteristic value of $p$ that would be expected for a given value of $S$. For $S_{353}(\delta = 30^\circ) = 3.2^\circ$, the $S$-$p$ anti-correlation would predict $p = 6.2$%. The largest possible $p$ values compatible with this $S$ value – corresponding to an orientation of the ordered $B$-field that is maximally in the plane of the sky – would be very close to $p = 20$%, the maximum value observed on the sky in the Planck data at 353 GHz (Planck Collaboration et al. 2015c, 2018a). However, the polarization fraction at 353 GHz that is actually measured by Planck in the Galactic Center region is $p = 1.6$% only. This leads to
the Galactic Plane by (Bland-Hawthorn & Gerhard 2016).

The homogeneity of the POS is now believed to be inclined by \( \gamma \approx 15^\circ \) clockwise to the trace of the Galactic plane by (Bland-Hawthorn & Gerhard 2016).

A mean magnetic field that is weakly inclined to the LOS in the GC region could possibly be explained by the geometry of the large-scale Galactic magnetic field. For instance, if the large-scale field is bi-symmetric and follows the Galactic bar, which is now believed to be inclined by \( \sim 30^\circ \) with respect to the LOS (Bland-Hawthorn & Gerhard 2016).

The POS magnetic field in the GC region is found to be tilted clockwise to the trace of the Galactic plane by \( +22^\circ \). This tilt angle is mostly due to variations in \( p = \sin^2 \gamma \) where \( \gamma \) is the angle of the field to the LOS. Since \( p \approx \sin^2 \gamma \), the tilt angle approaches zero, i.e., the POS magnetic field becomes approximately parallel to the Galactic plane.

The measured tilt angle \( \approx +22^\circ \) is not easily understood. There is no obvious gaseous structure that fills the GC region and has a \( +22^\circ \) clockwise tilt to the Galactic plane. The CMZ spans roughly the above longitude range, but it is much less extended in latitude, and only a relatively small portion of it (the western part of the twisted ring; see Sect. 5.4) was observed to have a clockwise tilt compatible with \( +22^\circ \).

5.3. Characteristic magnetic field strength in the CMZ

The regularity of the POS magnetic field orientation in the L0 region suggests that the magnetic field there is very strong, i.e., strong enough for magnetic pressure, \( P_{\text{mag}} \), to withstand the ram pressure from ambient interstellar clouds, \( P_{\text{ram}} \). Using a conservative estimate for \( P_{\text{ram}} \) in the Galactic Center region, Yusef-Zadeh & Morris (1987) previously showed that the condition \( P_{\text{mag}} \gg P_{\text{ram}} \) is roughly equivalent to \( B \gg 1 \) mG.

Here, we employ similar reasoning in an effort to estimate the magnetic field strength using the observed structure of the POS magnetic field in the CMZ region. As described in Section 4.1 we observe that the POS magnetic field orientation tends to become more parallel to the Galactic Plane in regions of high...
brightness. This is especially evident for the high-brightness structure in our total intensity map corresponding to Sgr B2, the 20 km/s and 50 km/s clouds and the Brick, which exhibit significant departures from the mean POS magnetic field orientation \( \cong +22^\circ \). We can thus reasonably imagine that these clouds have a ram pressure perpendicular to the magnetic field that is comparable to the local magnetic pressure: \( P_{\text{ram,}\perp} \sim P_{\text{mag}} \), where \( P_{\text{ram,}\perp} = \rho_v \delta v_{\perp}^2 \), \( \rho_v \) is the mean mass density of the cloud, and \( \delta v_{\perp} \) is the relative cloud velocity (with respect to its surroundings) perpendicular to the magnetic field.

For the characteristic gas densities in these regions \( \rho_v \), we adopt values obtained from \( \text{HC}_3\text{N} \) excitation studies by Mills et al. (2018) and Morris et al. (1976). For the LOS velocity of a cloud \( \delta v_{\text{LOS}} \) relative to its surroundings, we use the kinematic structure of the CMZ region presented by Henshaw et al. (2016). The values that we adopt for each cloud are listed in Table 1 To obtain the corresponding real space (i.e. 3D) relative velocities, we assume that the clouds as well as their surroundings follow the orbital trajectory proposed by Kruijssen et al. (2015). Finally, we project the 3D relative velocities onto the plane perpendicular to the mean magnetic field, which we take to be inclined by \( 15^\circ \) to the LOS and to have a POS orientation angle of \( +22^\circ \) (see Sect. 5.2). With these parameter values, we obtain magnetic field strength estimates ranging between 1.4 and 4.7 mG as shown in Table 1.

Table 1: Magnetic field strength estimates for CMZ clouds, assuming equipartition between magnetic pressure and ram pressure (see text in Section 5.3).

| Cloud       | \( \log(\rho_v) \) [cm\(^{-3}\)] | \( \delta v_{\text{LOS}} \) [km/s] | \( B \) [mG] |
|-------------|----------------------------------|----------------------------------|------------|
| Sgr B2      | 5.0                              | 20                               | 4.7        |
| Brick       | 4.2                              | 5.0                              | 1.4        |
| 50 km/s     | 4.5                              | 10                               | 2.7        |
| 20 km/s     | 4.3                              | 10                               | 2.8        |

Figure 12: Angle difference between the \( B \)-field orientation and the tangent to the 100-pc ring as defined in Molinari et al. (2011) as a function of the phase angle along the ring (black dots). The red and blue profiles show the corresponding 240 \( \mu \text{m} \) intensity and polarization fraction profiles in arbitrary units. The vertical lines show the range \( \pm 20^\circ \). The vertical boxes show the tangent point of the ring.

5.4. Coincidence with the 100-pc ring

The molecular cloud at the center of the CMZ is likely to orbit around the Galactic center following well defined trajectories, as described in Molinari et al. (2011) and Kruijssen et al. (2015). A legitimate question is to ask if the magnetic field as traced by dust associated to those clouds follows these structures even partly, or if the field lines are affected by the gas motion along those trajectories. If the field lines are significantly dragged by the gas motion, we would expect the \( B \)-filed orientation to be somewhat parallel to the trajectories. We would also expect the polarization fraction to lower at the tangent point of the trajectories, where the \( B \)-field orientation would be essentially along the LOS. We used the analytical description of the trajectory proposed in Molinari et al. (2011) and the tabulated orbital values in Kruijssen et al. (2015) to construct the sky projected trajectory on the plane of the sky. This track is overlaid for the Molinari et al. (2011) 100-pc ring on Fig. 1. We then compute the tangent direction to the track at each location along the trajectory. We finally compute the angle difference between this direction and the \( B \)-field orientation as measured by our polarization data, at each location along the track.

Figure 12 shows the angle difference between the \( B \)-field orientation as measured with PILOT and the tangent to the 100-pc ring. There is a very decent match between the \( B \)-field direction and the tangent to the trajectories of the Molinary 100-pc ring over half of the trajectory spanning negative longitudes. Over this section of the track, the \( B \)-field follows the tangent to the track to better than \( 8^\circ \). Those locations are indicated in Fig. 1. Along the location at positive longitudes however, the match is poor, with angle differences approaching \( \approx 45^\circ \). Using the physically motivated trajectories from Kruijssen et al. (2015) does not lead to a better overall match. In both cases, we looked but did not find any clear evidence for a trend for a decrease polarization fraction at the tangent points of the trajectories. These analyses confirm the visual impression when comparing the field orientation of Fig 5 and the trajectories in Fig 1 that the magnetic field orientation is very homogeneous over the whole region, as described in Sect. 5.2, and shows very little direction change at the location of the trajectories. Therefore, the match in direction over half the 100-pc ring as described in Molinari et al. (2011) could also be purely fortuitous.

5.5. Comparison with previous ground measurements

In principle, the \( B \)-field orientation inferred from our data could be compared to that derived from similar FIR/submm data obtained from ground observations, as long as these observations are dominated by polarized emission from large dust grains. In practice, however, the comparison is complicated by several limitations. First, ground data are often obtained at high angular resolution, but cover very small sky regions. As a consequence, the data tabulated in the literature is often too scarce to fill-up one the PILOT beam, preventing the comparison. Second, the data processing of ground data is likely to filter large scale emission. A fair comparison would require filtering the PILOT data using...
the transfer function of the data processing applied to the ground data, but this is usually not feasible, since the information about the processing is often incomplete and the processing software is not readily available.

Out of the FIR/submm polarization data available described in Sect. 1 we selected the JCMT data of Matthews et al. (2009) obtained at 450 μm as the one with spatial coverage and completeness best matching our resolution. This data covers most of the extent of the 50 km/s molecular cloud highlighted in Fig. 1. Figure 13 shows the comparison between the JCMT data and the PILOT data. In order to perform the comparison, we transformed the JCMT data provided under the form of polarization maps the average values measured in each pixel of our map. Those values were sky total intensity weighted average of the JCMT Stokes parameters and a realistic density distribution to demonstrate quantitatively that the observed polarization properties cannot be explained by the magnetic field of the Galactic disk along the line-of-sight to the Galactic Center region.

The PILOT polarization angle measurements show that the structure of the magnetic field in the plane of the sky (POS) is remarkably uniform over the full extent of our mapped region. The observed distribution of polarization angles indicates that the POS B-field in the CMZ has a dominant orientation of ~22° measured clockwise with respect to the Galactic plane (Figure 5). There are no obvious structures in the PILOT total intensity maps that correspond to this characteristic orientation.

Within our observed field, the POS magnetic field structure tends to become more parallel to the Galactic Plane in re-

6. Summary and conclusions

In this paper, we have presented new measurements of the polarized dust emission at 240 μm in the Galactic central region. The data were obtained during ~30 minutes of observations during the second flight of the PILOT balloon-borne experiment, which was launched from Alice Springs, Australia in April 2017. The observed region covers a wide field (~2° < ℓ < 2°, −4° < b < 3°) at an angular resolution of 2.2′. This paper is the first PILOT paper to present scientific analysis of polarization measurements towards astronomical targets. To validate these measurements and assess the overall quality of our data processing pipeline, we present polarization maps from the PILOT data using two independent map-making methods (SCANAMORPHOS and ROMA). The two pipelines generate similar I, Q and U maps, and yield a similar distribution of polarization angles across our observed field. The SCANAMORPHOS maps of I, Q and U used for the analysis in this paper are publicly available through the Centre d’Analyse des Données Etendues (CADE, http://http://cade.irap.omp.eu).

The key results of our analysis are:

- We obtain a clear detection of polarized thermal dust emission from the Milky Way’s Central Molecular Zone (CMZ). This is obvious from the observed structure of emission features in the PILOT I, Q and U maps (Figure 4). We develop a Galactic model with ordered and turbulent magnetic field components and a realistic density distribution to demonstrate quantitatively that the observed polarization properties cannot be explained by the magnetic field of the Galactic disk along the line-of-sight to the Galactic Center region.

- The PILOT polarization angle measurements show that the structure of the magnetic field in the plane of the sky (POS) is remarkably uniform over the full extent of our mapped region. The observed distribution of polarization angles indicates that the POS B-field in the CMZ has a dominant orientation of ~22° measured clockwise with respect to the Galactic plane (Figure 5). There are no obvious structures in the PILOT total intensity maps that correspond to this characteristic orientation.

- Within our observed field, the POS magnetic field structure tends to become more parallel to the Galactic Plane in re-
regions with high 240 μm brightness, such as the well-known Sgr B2, 20 km/s and 50 km/sclouds (Figure [7]).

- The polarization angles measured by PILOT are in good agreement with the polarization angles measured by Planck at 217 and 353 GHz across the same region. The PILOT data shows poorer agreement with the distribution of polarization angles measured by Planck at lower frequencies, which is likely due to the impact of contamination by the CO line and synchrotron emission in in the Planck 70, 100 and 143 GHz channels.

- The regularity of the POS magnetic field orientation and the low polarization fraction in the Galactic Center region suggest that the magnetic field is strong with a 3D geometry that is mostly oriented 15° with respect to the line-of-sight towards the Galactic center. Assuming equipartition between the magnetic pressure and ram pressure, we obtain magnetic field strengths estimates as high as a few mG for several CMZ molecular clouds (see Table[1]).

- We find no evidence for a connection between the orientation of the POS magnetic field structure inferred from the PILOT observations and the twisted ring structure identified in the CMZ by Molinari et al. [2011].

- We find broadly good agreement between the POS magnetic field orientations observed by PILOT at 240 μm and by SCUBAPOL on the JCMT at 450 μm for a subfield centred on the 50 km/s molecular cloud. This suggests that the homogeneity of the POS magnetic field persists to smaller scales within the 50 km/s molecular cloud region.

### Appendix A: Simplified Galactic Model

We model the Galactic plane as follows, inspired from models such as that of Jaffe et al. [2013]. The dust density distribution is composed of an axisymmetric exponential profile, plus four spiral arms with Gaussian profiles in their cross sections. The magnetic field is the sum of an ordered component and a turbulent part. The magnetic coherence length for this turbulent part is obtained by taking $k_{\text{max}} = \frac{1}{3 \lambda_{\text{min}}}$. As for the index, we consider a Kolmogorov-like turbulence for which $\alpha = -1/3$. We generate the turbulent magnetic field along a given line-of-sight as three independent Gaussian realizations (one for each component), while the values of that field along the adjacent lines-of-sight are constrained by the fact that the total three dimensional field has to be divergenceless. In practice, we do not need to explicit the precise values along these adjacent lines-of-sight since the following calculation is performed one line-of-sight at a time, but we note here that we indeed have enough freedom left in the construction of our field for it to be physical (i.e. divergenceless).

We compute the polarization fraction $p$ as follows. In principle it may be obtained using the expressions (5) to (7) of Planck Collaboration et al. [2015b]. However, for the purpose of this simple estimate, we note that to a first approximation we may neglect the optical depth effects and take $\kappa_{\nu} = 1$ in the $I$, $Q$ and $U$ integrals for the frequency of interest (Boulanger et al. [1996]), and that the source function $S_\nu$ and $p_0$ are constant along the line of sight. Therefore we have

$$ p(s) = p_0 \sqrt{\left( \int_0^s \kappa_{\nu} \cos(2\phi) \cos^2 \gamma ds' \right) + \left( \int_0^s \kappa_{\nu} \sin(2\phi) \cos^2 \gamma ds' \right)} \left( 1 - p_0 \cos(\gamma - \frac{s}{2}) \right) ds' $$

(A.1)

where we use the same notations as in the aforementioned Planck paper, $s$ is the distance along the line of sight, with origin at the Sun, and we take $p_0 = 0.2$. Note that with this definition $p$ can be greater than $p_0$.

We proceed in two steps. First, we consider the longitudes beyond the central region ($\ell \in [180°, 20°] \cup [20°, 180°]$) in order to evaluate how turbulent the magnetic field is, inside and between the spiral arms. In the top of figure [A.1] we show how in our model the polarization fraction depends on the longitude for three limiting cases: the blue curve corresponds to a switched off turbulence, orange corresponds to equipartition between the ordered and turbulent parts, and in red the root mean square of the turbulent part is three times larger than the ordered part. Comparing these results to the observed signal (bottom of that same figure) indicates that the turbulent component is important, with a typical root mean square of 2 to 3 μG. Secondly, we focus on the longitudes $\ell \in [20°, 20°]$, and estimate the contribution to $p$ of everything along these lines of sight, except the bulge and the CMZ. To do so, we take a vanishing dust density inside the molecular ring, and compute $p$ using the estimated properties of turbulence in the disk from the first step. The results are plotted in figure [A.1]. Naturally, the stronger the turbulence, the lower $p$ is. But $p$ does not reach values as low as the measured ones. Indeed, the observed $p$ is of typically 1% throughout that central region, while even in the case of a strong turbulence (red curve) $p$ is around 4%. Therefore the central part has a non negligible contribution to the observed signal.

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Fig. A.1: Top: Polarization degree as a function of longitude in our model. The curves correspond to single realizations of the turbulent field, but are representative of the typical behaviour. Bottom: Measured values with Planck, using the modified asymptotic estimator (Plaszczynski et al. 2014) at a resolution of 15 arcmin.