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Non quantum uncertainty relations of stochastic dynamics

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Abstract

First we describe briefly an information-action method for the study of stochastic dynamics of hamiltonian systems perturbed by thermal noise and chaotic instability. It is shown that, for the ensemble of possible paths between two configuration points, the action principle acquires a statistical form $\langle \delta A \rangle = 0$. The main objective of this paper is to prove that, via this information-action description, some quantum like uncertainty relations such as $\langle \Delta A \rangle \geq \frac{1}{\sqrt{2\eta}}$ for action, $\langle \Delta x \rangle \langle \Delta P \rangle \geq \frac{1}{\eta}$ for position and momentum, and $\langle \Delta H \rangle \langle \Delta t \rangle \geq \frac{1}{\sqrt{2\eta}}$ for hamiltonian and time, can arise for stochastic dynamics of classical hamiltonian systems. A corresponding commutation relation can also be found. These relations describe, through action or its conjugate variables, the fluctuation of stochastic dynamics due to random perturbation characterized by the parameter $\eta$.

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1 Introduction

The discussion of this work is limited to mechanical systems without considering the quantum effect. We use the term regular dynamics to mean the mechanical processes with time reversible trajectories (geodesics) uniquely determined for each system by the Hamiltonian equations, or equivalently,
by least action principle. Compared to this deterministic character of regular dynamics, one of the strong difference of irregular (random, stochastic, or statistical) dynamics is the uncertainty (unpredictability) of the trajectories of the system. This uncertainty can be illustrated in Figure 1 showing the diffusion of perfume molecules in the air. Clearly, from the point of view of classical mechanics, if there is no random perturbation from the molecules of air, an isolated perfume molecule leaving the hole at time $t_a$ has only one possible path or a fine bundle of paths having least action and arrives at a sole point $b$ at time $t_b$. With the random perturbation of thermal noise of air molecules, however, the perfume molecules can arrive at many very different points $b$ at a time $t_b$. This is the first dynamical uncertainty due to the random noise. In the theories of chaos, this uncertainty is usually measured by Kolmogorov-Sinai entropy or by Lyapunov exponent. Another uncertainty is that, at time $t_b$, the perfume molecules can arrive at a point $b$ through different paths. This uncertainty in path space has been considered, e.g., in the path integral approach to quantum and non-quantum dynamics and in the large deviation theory. In general, these two uncertainty are not independent from each other. It is obvious that, without the first uncertainty, the second one cannot take place.

While the mathematics of regular dynamics can be perfectly formulated on the basis of the least action principle in classical mechanics, irregular or random dynamics, found in diffusion, chaotic and other nonequilibrium phenomena, is much more complicated to be described due to its stochastic and random feature. Nowadays, statistical and thermodynamic theories of irregular dynamics are still in development, among which we can cited nonequilibrium statistical mechanics, chaotic dynamics theory, anomalous transport theory, large deviation theory, small random perturbation theory and path integral method starting from Brownian motion. Many questions and topics concerning, e.g., time irreversibility, variational approaches, chaotic nature of dynamic process, connection with quantum physics are still open to investigation. Much efforts have been made to clarify the origin of diffusion laws such as the Fokker-Planck equation, the Fick’s laws, the Fourier law, the Ohm’s law and the anomalous diffusion laws (fractional or nonlinear).

As a starting point of what we will describe in this paper, we would like to mention some characteristics shared by large deviation theory, perturbation theory, and path integral approach. In these theories, variational method is used to find the most probable (or optimal) paths (histories, trajectories)
with the help of rate functional[4], action functional[5, 8, 12, 13], or path integral[3, 18]. All these functionals can be called effective action $S$ whose optimization, through a postulated exponential transition probability with a factor $\exp(-\alpha S)$, allows one to find the most probable paths. Note that $S$ are not necessarily the mechanistic action defined in classical mechanics with the Lagrangian $L = E - U[3]$, where $E$ and $U$ are respectively kinetic and potential energy. Here $L$ is defined for hamiltonian systems satisfying (in one dimensional space)

$$\dot{x} = \frac{\partial H}{\partial P} \quad \text{and} \quad \dot{P} = -\frac{\partial H}{\partial x}$$

(1)

where $x$ is the coordinates, $P = m\dot{x}$ the momenta, and $H = E + U$ is the hamiltonian of the system. The mechanistic action is defined by $A = \int_a^b L(x, P, t) dt$. Its stationary $\delta A = 0$ according to least action principle leads to the Euler-Lagrange equations[20]

$$\frac{\partial}{\partial t} \frac{\partial L}{\partial \dot{x}} - \frac{\partial L}{\partial x} = 0.$$  

(2)

If we consider the Legendre transformation $H = P\dot{x} - L$, Eqs.(1) can be easily derived from Eq.(2). It is worth noticing that, when the effective actions mentioned above are calculated by time integral of an effective Lagrangian, Eq.(2) is always satisfied by the optimal paths[3, 5, 8, 13, 18].

A point to be noticed is that, in the above theories and their applications, one is most interested by the most probable paths whose neighborhood provides the basic contribution to the transition probability[3, 8, 12, 18]. The other less probable paths of larger actions are often neglected or only taken into account (or buried) in the path integrals[2, 3]. As a matter of fact, the application of classical action principle only to the optimal paths is, to our opinion, incomplete. The physics represented by the larger action paths is an inseparable part of the dynamics and may be essential for the fundamental understanding of irregular dynamics. Recently, an informational method was proposed[21, 22] to treat all the possible paths as an ensemble. The method considers hamiltonian systems under random perturbation of thermal noise and chaotic instability leading to the uncertainties shown in Fig. 1. These uncertainties can be measured by a path information associated with different paths between two points in configuration space. The path information is optimized in connection with the average action of the hamiltonian system calculated over all the possible paths. We obtain an exponential probability
distribution of action. In principle, this action can be any effective action mentioned above. But in our previous work, the classical mechanistic action is used. It is worth noticing that this variational method is proven to be equivalent to an “extended least action principle” for stochastic dynamics, i.e., instead of $\delta A = 0$, we have $\langle \delta A \rangle = 0$ where the average $\langle \cdot \rangle$ is taken over all the paths. Using classical action turns out to be an useful choice since we have been able to derive the diffusion laws mentioned above for all the possible paths not only for the optimal paths. In this paper we will describe some mathematical consequences of this approach. Our main objective here is to derive non quantum uncertainty relations, which are in fact a necessary consequence of the description of stochastic dynamics with path probability given by distribution of action.

2 Optimizing information-action

First let us recapitulate briefly the method. Let $p_k(b|a)$ be the transition probability along a path $k$ ($k = 1, 2, \ldots, w$) from a position $a$ and to another position $b$. The dynamic uncertainty associated with $p_k(b|a)$ is measured with the following Shannon information

$$I_{ab} = - \sum_{k=1}^{w} p_k(b|a) \ln p_k(b|a).$$

We have the following normalization $\sum_{k=1}^{w} p_k(b|a) = 1$. If $w$ is very large in an ergodic phase space and if the paths are sufficiently smooth, $\sum_k$ should be replaced by a path integral in the Feynman sense\cite{2}, e.g., $I_{ab} = - \int D(x)p_k(b|a) \ln p_k(b|a)$ in keeping $a$ and $b$ fixed. The average action between $a$ and $b$ is given by

$$\langle A_{ab} \rangle = \sum_{k=1}^{w} p_k(b|a) A_{ab}(k).$$

where $A_{ab}(k)$ is the classical action along a path $k$. Our optimal information-action method consists in the following operation:

$$\delta[I_{ab} + \alpha \sum_{k=1}^{w} p_k(b|a) - \eta \sum_{k=1}^{w} p_k(b|a) A_{ab}(k)] = 0$$

leading to

$$p_k(b|a) = \frac{1}{Z} \exp[-\eta A_{ab}(k)],$$

4
where the partition function $Z = \sum_k \exp[-\eta A_{ab}(k)] = \int \mathcal{D}(x) \exp[-\eta A_{ab}(k)]$. It is straightforward to see the following relationships:

$$I_{ab} = \ln Z + \eta \langle A_{ab} \rangle \quad (7)$$

and

$$\langle A_{ab} \rangle = -\frac{\partial}{\partial \eta} \ln Z, \quad (8)$$

It is proved that[21] the distribution Eq.(6) is stable with respect to the fluctuation of action. If one uses the action of a free particle[2, 3, 6], $p_k(b|a)$ is just the transition probability of Brownian particles. In this case, we have a precise physical meaning of the multiplier $\eta$, i.e., $\eta = \frac{1}{2mD}$ where $m$ is the mass and $D$ the diffusion constant of the Brownian particle. The significance of $\eta$ will be discussed later in a general way for particles moving in a potential field $U(x)$.

### 3 Extended action principle for irregular dynamics

As expected, Eq.(6) is a least action distribution, i.e., the most probable paths are just the paths of least action $\delta A_{ab}(k) = 0$ satisfying Euler-Lagrange equation and Hamiltonian equations. The other paths do not satisfy Eqs.(1) and (2). In general, the paths have neither $\delta A_{ab}(k) = 0$ nor $\delta \langle A_{ab} \rangle = 0$.

Eq.(5) implies following relationship

$$-\eta \delta A_{ab} + \delta I_{ab} = 0. \quad (9)$$

By using Eqs.(3), (4) and the distribution (6), it is easy to calculate that Eq.(9) is equivalent to

$$\langle \delta A_{ab}(k) \rangle = \sum_k p_k(b|a) \delta A_{ab}(k) = 0. \quad (10)$$

On the other hand, in mimicking equilibrium thermodynamics, we can define a dynamic potential

$$\Psi = \frac{1}{\eta} \ln Z$$
as an analog of the free energy of Helmholtz. From Eqs. (7) and (9), it is straightforward to see that the extended action principle Eq. (10) is equivalent to the following variational principle

$$\delta \Psi = 0.$$  \hspace{1cm} (11)

A remarkable application of this above variational approach to computation of thermodynamic properties of hamiltonian systems was (independently) carried out recently[10]. The authors derived thermodynamic equations of motions for equilibrium systems with different Hamiltonians, already known in the literature and used in simulations of molecular dynamics, by considering the particle histories in phase space on constant energy surface.

The extension of action principle has some consequences on the equations of motion as discussed in [23]. For example, for the paths whose action is not at stationary, we get

$$\frac{\partial}{\partial t} \frac{\partial L_k(t)}{\partial x} - \frac{\partial L_k(t)}{\partial x} \neq 0$$

and

$$\dot{P} \neq - \frac{\partial H}{\partial x}$$

which implies a stochastic equation like

$$\dot{P}_k = - \frac{\partial H}{\partial x} + R$$  \hspace{1cm} (12)

where $R$ is a random force representing the random perturbation of thermal noise and chaotic instability. On the other hand, using the action principle Eq. (10), we recover Eqs. (1) and (2) for the ensemble of paths:

$$\left\langle \frac{\partial}{\partial t} \frac{\partial L_k(t)}{\partial x} \right\rangle - \left\langle \frac{\partial L_k(t)}{\partial x} \right\rangle = 0$$  \hspace{1cm} (13)

and

$$\langle \dot{x} \rangle = \left\langle \frac{\partial H}{\partial P} \right\rangle \text{ and } \langle \dot{P} \rangle = - \left\langle \frac{\partial H}{\partial x} \right\rangle.$$  \hspace{1cm} (14)

This implies that the mean of the “random force” $R$ over all possible paths must vanish, i.e., $\langle R \rangle = 0$, required by the extended action principle. The second equality of Eqs. (14) is the random analog of Newton’s law and has the same content as the Feynman-Hibbs quantum Newton’s law in Eq.(7-42) of [2].

In what follows, we are concerned with the spreads of the distribution of the stochastic dynamics, in other words, the deviation of the irregular dynamics from the regular one due to random perturbation. This uncertainty is a priori measured by the path information we introduced. But here it will be analyzed at the level of mechanical quantity like position, momentum, action and energy.
4 Uncertainty relations

For the sake of simplicity, we suppose the point \( b \) at \( x \) is very close to the point \( a \) at \( x_0 \) and the transition takes place in the infinitesimal time interval \( \delta t = t - t_0 \). This segment can be considered as a factor (a small element of a long path) in path integral technique[2]. Let \( \delta x = x(t) - x_0(t_0) \), the action is given by

\[
A_{ab}(x) = \frac{m(\delta x)^2}{2\delta t} + F \frac{\delta x}{2} \delta t - U(x_0) \delta t,
\]

where \( F = -\left( \frac{\partial U}{\partial x} \right)_{(x+x_0)/2} \) is the force on the path and \( m \) the mass of the studied system. The transition probability is

\[
p_k(b|a) = \frac{1}{Z} \exp \left( -\eta \left[ \frac{m}{2\delta t} \delta x^2 + F \frac{\delta t}{2} \delta x \right] \right)
\]

with

\[
Z = \int_{-\infty}^{\infty} dx \exp \left( -\eta \left[ \frac{m}{2\delta t} \delta x^2 + F \frac{\delta t}{2} \delta x \right] \right)
\]

\[
= \exp \left[ \frac{F^2 \eta \delta t^3}{8m} \right] \sqrt{\frac{2\pi \delta t}{m\eta}}.
\]

The potential energy of the point \( x_0 \) disappears after normalization because it does not depend on \( x \). \( F \) is considered constant on small \( \delta x \). It is easy to show[22] that the probability of Eq.(16) satisfies the Fokker-Planck equation and that other diffusion laws can be trivially derived from it.

How far are the randomly perturbed paths deviated from the optimal paths of regular dynamics? How different are Eqs.(14) from Eqs.(1)? This question can be answered, under different angles, by the standard deviation of action \( \langle \Delta A \rangle^2 = \langle A^2 \rangle - \langle A \rangle^2 = \langle A^2 \rangle - \langle A_{ab} \rangle^2 = \frac{-\partial(A_{ab})}{\partial \eta} \), of position \( \langle \Delta x \rangle^2 = \langle x^2 \rangle - \langle x \rangle^2 \), of momentum \( \langle \Delta P \rangle^2 = \langle P^2 \rangle - \langle P \rangle^2 \) and of Hamiltonian \( \langle \Delta H \rangle^2 = \langle H^2 \rangle - \langle H \rangle^2 \). Using the formula below\(^1\), we obtain

\[
\langle x - x_0 \rangle = -\frac{F \delta t^2}{2m},
\]

\(^1\int_{-\infty}^{\infty} dx \exp(-\alpha x^2 + 2\gamma x) = \exp(\gamma^2/\alpha)\sqrt{\frac{\pi}{\alpha}} \) and \( \int_{-\infty}^{\infty} x^n dx \exp(-\alpha x^2 + 2\gamma x) = \frac{1}{2^{n-1}\alpha^{n/2}} \frac{\partial^{n-1}}{\partial \gamma^{n-1}} [\gamma \exp(\gamma^2/\alpha)] \).
\[
\langle P - P_0 \rangle = -\frac{F \delta t}{2}, \quad (19)
\]
\[
\langle (x - x_0)^2 \rangle = \frac{\delta t}{m \eta} + \frac{F^2 \delta t^4}{4m^2}, \quad (20)
\]

and
\[
\langle (P - P_0)^2 \rangle = \frac{m}{\delta t \eta} + \frac{F^2 \delta t^2}{4}. \quad (21)
\]

Since \( \langle \Delta x \rangle = \langle \Delta(x - x_0) \rangle \), the above relationships imply
\[
\langle \Delta x \rangle^2 = \frac{\delta t}{m \eta}, \quad (22)
\]

and
\[
\langle \Delta P \rangle^2 = \frac{m}{\delta t \eta}. \quad (23)
\]

Cancelling the time \( \delta t \) and \( m \) in the above two equations, we get a "classical uncertainty relation" for irregular dynamics
\[
\langle \Delta x \rangle^2 \langle \Delta P \rangle^2 \geq \frac{1}{\eta^2}. \quad (24)
\]

Notice that this is only an asymptotic relation for \( \delta t \to 0 \). For a measurable (longer) length of time and path, we divide them into small segments of the order of \( \delta t \) and \( \delta x \). Eq.(24) should be valid for each segment. Thus it can be trivially proven that the total deviation \( \langle \Delta \rangle^2 \) of whatever quantity on a path is a sum of all the deviations on its small segments (Gaussian law of errors, see for example [6]). So in general, we must write
\[
\langle \Delta x \rangle^2 \langle \Delta P \rangle^2 \geq \frac{1}{\eta^2}, \quad (25)
\]

which is valid for any measurable period of time and path length. If the system is in rotation with \( \delta x/R = \delta \theta \) where \( \theta \) is the rotation angle and \( 1/R \) the curvature of \( \delta x \), then we get
\[
\langle \Delta \theta \rangle^2 \langle \Delta J \rangle^2 \geq \frac{1}{\eta^2}, \quad (26)
\]
where \( J \) is the angular momentum.

The action uncertainty can be calculated from Eqs.\((8)\) and \((17)\):

\[
\langle A_{ab} \rangle = \frac{1}{2\eta} - \frac{F^2\delta t^3}{8m} \tag{27}
\]

so that

\[
\langle \Delta A \rangle^2 = -\frac{\partial \langle A_{ab} \rangle}{\partial \eta} = \frac{1}{2\eta^2}. \tag{28}
\]

This relation can be written as \( \langle \Delta L \rangle^2 \langle \delta t \rangle^2 = \frac{1}{2\eta^2} \) where \( \langle \Delta L \rangle^2 = \langle L^2 \rangle - \langle L \rangle^2 \) is the standard deviation of Lagrangian. For arbitrary time and path length, we must write

\[
\langle \Delta A \rangle^2 \geq \frac{1}{2\eta^2}. \tag{29}
\]

and

\[
\langle \Delta L \rangle^2 \langle \Delta t \rangle^2 \geq \frac{1}{2\eta^2} \tag{30}
\]

where \( \langle \Delta t \rangle^2 = \langle t^2 \rangle - \langle t \rangle^2 \) is the standard deviation of time measure. Eq.\((30)\) can be verified in the same way as for position and momentum, through the calculation of \( \langle t \rangle \) and \( \langle t^2 \rangle \) with the distribution Eq.\((16)\) in relaxing \( \delta t \) and fixing \( \delta x \).

Now let \( H(t) \) be the Hamiltonian on the considered path segment at moment \( t \), we have the Legendre transformation \( H(t) = P\dot{x} - L(t) \). Considering \( L = E - U \) and \( E = P\dot{x} / 2 \), we get

\[
\langle \Delta H \rangle^2 = \langle \Delta L \rangle^2 + 4(\langle EU \rangle - \langle E \rangle \langle U \rangle). \tag{31}
\]

\( E \) and \( U \) are two independent variable, so \( \langle EU \rangle = \langle E \rangle \langle U \rangle \), we obtain

\[
\langle \Delta H \rangle^2 = \langle \Delta L \rangle^2 \tag{32}
\]

and

\[
\langle \Delta H \rangle^2 \langle \Delta t \rangle^2 \geq \frac{1}{2\eta^2}. \tag{33}
\]
Before giving an interpretation of these non quantum uncertainty relations of irregular dynamics, i.e., Eq.(25), Eq.(26), Eq.(29), Eq.(30) and Eq.(33), we would like to indicate two points. First, it seems that Eq.(29), the action uncertainty relation, is the most essential one because it tell us the spread of the action distribution and the deviation of the extended action principle \( \langle \delta A \rangle = 0 \) from the conventional one \( \delta A = 0 \). The other relations concerns the conjugate variables of action and can be a priori derived from action uncertainty. Second, the coefficient \( \eta \) plays a central role in this description of the dynamics. Roughly speaking, \( \eta \to 0 \) represents large deviation of the perturbed dynamics from the regular one (large uncertainty), large \( \eta \) represents small random perturbation and deviation (small uncertainty), and \( \eta \to \infty \) implies vanishing perturbation and convergence of irregular dynamics to regular one (zero uncertainty).

A quantitative relationship between the uncertainty and thermal noise can be shown with a special example, Brownian motion \((F = 0)\) with diffusion constant \( D = \mu k_B T \)[6], where \( \mu \) is the mobility of the particles, \( k_B \) is the Boltzmann constant and \( T \) the temperature. Here we see a relationship between \( \eta \) and temperature characterizing the thermal noise: \( \eta = \frac{1}{2m\mu k_B T} \). In this case, we can write, for example,

\[
\langle \Delta x \rangle \langle \Delta P \rangle \geq 2m\mu k_B T,
\]

which implies that the paths may be distributed very widely in phase space around the optimal (least action) paths at high temperature.

5 A commutation relation

Now let us define a certain functional \( G_k(x) \) of paths. The average of the functional over all the paths is given by

\[
\langle G_k(x) \rangle = \sum_k G_k(x)p_k(b|a).
\]

Now differentiate this equation with respect to \( x \), the average does not depend on position, so \( \frac{\partial \langle G_k(x) \rangle}{\partial x} = 0 \). The derivative of right hand side yields two terms: \( \sum_k p_k(b|a)\frac{\partial G_k(x)}{\partial x} \) and \( -\eta \sum_k p_k(b|a)G_k(x)\frac{\partial A_{ab}(k)}{\partial x} \). This implies

\[
\langle \frac{\partial G_k(x)}{\partial x} \rangle = -\eta \langle G_k(x)\frac{\partial A_{ab}(k)}{\partial x} \rangle,
\]
which is the classical analog of the Feynman-Hibbs relation given by Eq.(7-30) of [2]. Imposing $G_k(x) = x$, we obtain[2]:

$$\langle m \frac{x_{i+1} - x_i}{\delta t} x_i \rangle - \langle x_i m \frac{x_i - x_{i-1}}{\delta t} \rangle = \frac{1}{\eta},$$  \hspace{1cm} (37)

where $i$ is the index of a segment for the time period $\delta t = t_i - t_{i-1}$ of a certain path $k$. This relation can be written as

$$\langle P_{i+1} x_i \rangle - \langle x_i P_i \rangle = \frac{1}{\eta},$$ \hspace{1cm} (38)

which can be considered as a classical commutation relation, where $x_i$ is the position at time $t_i$, $P_{i+1} = \frac{x_{i+1} - x_i}{\delta t}$ and $P_i = \frac{x_i - x_{i-1}}{\delta t}$ are the momenta at time $t_{i+1}$ and $t_i$, respectively.

We would like to indicate that the above results, i.e., the uncertainty and commutation relations, were obtained by using the mechanical Lagrangian and action. Nevertheless, as mentioned above, the same conclusions can be reached with other action functionals and Lagrangians. It can be trivially shown that similar uncertainty relations arise with, e.g., Onsager-Machlup Lagrangian $L_{OM} = (\dot{x} - \mu F)^2$[3, 5] and Freidlin-Wentzell Lagrangian $L_{OM} = [\dot{\varphi} - b(\varphi)]^2$ where $\dot{\varphi} = b(\varphi)$ is the differential equation of some continuous function $\varphi$ of paths when the perturbation vanishes[8]. If the Lagrangians do not have mechanistic interpretation, the uncertainty relations should be understood differently depending on the physical content of the variables.

### 6 Concluding remarks

We have briefly presented an information-action method for stochastic dynamics of hamiltonian systems. We see that in this approach the Euler-Lagrange equations, the Hamiltonian equations and the action principle only hold in averaged form over the ensemble of all the possible paths between two state points. The main result of this paper is to show that some uncertainty relations, very similar to those in quantum mechanics, exist for stochastic dynamics of hamiltonian systems.

We are in the realm of classical physics, no quantum effect is considered. In addition, the systems under consideration are possibly macroscopic. There is normally the consensus that exact value of position and speed can be a priori assigned to a particle at the same time. Then how to understand
the uncertainty relations in classical dynamics? A plausible understanding is that $\langle \Delta A \rangle \geq \frac{1}{\sqrt{2\eta}}$ implies the distribution of action cannot be arbitrarily narrow around the least action, or the fluctuation of action has a non zero minimum due to the random perturbation. In the same way, $\langle \Delta x \rangle \langle \Delta P \rangle \geq \frac{1}{\eta}$ means that the fluctuations or the distributions of position and momentum cannot be simultaneously arbitrarily narrow. It has no meaning about the precision of the measure, because a classical body does have exact position and speed and the means $\langle x \rangle$ and $\langle P \rangle$ can be made arbitrarily close to the real values of the body whatever the fluctuation $\langle \Delta x \rangle$ and $\langle \Delta P \rangle$ of the separately measured values.

A question naturally arises. Do these classical uncertainty relations have something to do with their quantum analogs? Remember that in this work we consider classical systems under the random perturbation of thermal noise. This essential point is illustrated by the example of Brownian motion in Eq.(34) which tell us that if the thermal noise vanishes for $T \to 0$, we get, e.g., $\langle \Delta x \rangle \langle \Delta P \rangle \geq 0$. So no quantum effect can be observed here. One needs additional hypothesis in order to enter into the quantal world from the present results. For example, if one assumes $\eta = 1/\hbar$, the distribution function Eq.(6) becomes an universal Brownian distribution of Fényes-Nelson[16, 24] satisfying Fokker-Planck equation[23] whose forward and backward versions can lead to Schrödinger equation[16, 18]. At the same time the classical uncertainty relations become the Heisenberg’s relations. To our opinion, the passage from classical stochastic dynamics to the stochastic (quantum) mechanics of Fényes-Nelson is not automatic. The assumptions of an universal noise and the emergence of a constant minimum uncertainty $\hbar$ are not trivial. A priori, without any hypotheses, the results of the present work are meaningful only for classical systems.

The idea of classical uncertainty relations can be seen in the interpretation of quantum mechanics on the basis of the hypothesis of Cantorian (fractal) space-time[27, 28, 29, 30, 31]. Some authors discussed the quantum uncertainty relations due to fractal quantum paths[28, 29, 32, 33]. Their reasoning is in fact extendable to macroscopic non quantum fractal paths as discussed in [28, 29]. This is the case of classical uncertainty relations arising from fractal geometry.

As a matter of fact, a possible classical background of the Heisenberg’s relations was proposed long ago by Fürth[25] and then discussed by many authors[24, 26]. There the authors investigated an uncertainty relation of
Brownian motion for position and drift velocity of diffusion, the latter is not the instantaneous velocity (or momentum), i.e., the conjugate variable of position used in Eq.(24). It was believed that the Bohr’s concept of complementarity also enters in classical mechanics, but with a statistical average of momentum; this implies that there is no classical analogs of quantum commutation relations. The present work shows that the classical analogs of quantum relations exist.

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Figure 1: An example of random dynamics: the diffusion of scent. At time $t_a$, the molecules of the perfume get out of the bottle at point $a$. At time $t_b$, the molecules arrive at different points $b_i$ ($i = 1, 2, ...$) (first dynamical uncertainty). For a pony putting his nose at a given point $b$, all the molecules it receives at time $t_b$ may arrive there via different paths (second dynamical uncertainty). Obviously, as shown by the dotted lines in the figure, the second uncertainty cannot take place without the first one.