Zero sets of $\mathcal{H}^p$ functions in convex domains of finite type

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Abstract We give a condition under which a divisor $\tilde{X}$ in a bounded convex domain of finite type $D$ in $\mathbb{C}^n$ is the zero set of a function in a Hardy space $\mathcal{H}^p(D)$ for some $p > 0$. This generalizes Varopoulos’ result (Pac J Math 88:189–246, 1980) on zero sets of $\mathcal{H}^p$-functions in strictly convex domains of $\mathbb{C}^n$.

Keywords Hardy classes · Zero set · Carleson measure · Convex domain · Finite type

Mathematics Subject Classification 32A26 · 32A25 · 32A35 · 42B30

1 Introduction and main result

We present here our main result and the outline of its proof.

1.1 Zero sets of functions in the Nevanlinna and Hardy classes

We denote by $D = \{z \in \mathbb{C}^n, \ r(z) < 0\}$ a bounded domain in $\mathbb{C}^n$, where $n$ is a positive integer and $r$ is a smooth function such that $dr \neq 0$ on the boundary of $D$. We set $d = |r|$ and $D_{\varepsilon} = \{z \in \mathbb{C}^n, \ r(z) < \varepsilon\}$. We denote by $bD_{\varepsilon}$ the boundary of $D_{\varepsilon}$, by $T_{\zeta}bD_{\varepsilon}(z)$ the complex tangent space to $bD_{\varepsilon}(z)$ at $z$, and by $d\sigma_{\varepsilon}$ the euclidean area measure on $bD_{\varepsilon}$.

The Nevanlinna class $\mathcal{N}(D)$ is the set of holomorphic functions $f$ on $D$ such that

$$\sup_{\varepsilon > 0}\int_{bD_{-\varepsilon}} \left| \log |f(z)| \right| d\sigma_{-\varepsilon}(z) < +\infty.$$
The Hardy space $\mathcal{H}^p(D)$, $p > 0$, is the set of holomorphic functions $f$ on $D$ such that

$$\|f\|_p = \left(\sup_{\epsilon > 0} \int_{bD-\epsilon} |f(z)|^p d\sigma(z)\right)^{1/p} < +\infty.$$ 

Let $X = \{z \in D. \ f(z) = 0\}$ be the zero set of a function $f \in \mathcal{N}(D)$, let $X_k$ be the irreducible components of $X$ and let $n_k$ be the corresponding multiplicities of $f$; the data $\hat{X} = \{X_k, n_k\}_k$ is commonly called a divisor. It is well known that $X$ or equivalently $\hat{X}$ satisfies the Blaschke Condition:

$$\sum_k n_k \int_{X_k} d(z) d\mu_{X_k}(z) < +\infty, \tag{B}$$

where $d\mu_{X_k}$ is the euclidean area measure on the regular part of $X_k$. When $D$ is the unit disk of $\mathbb{C}$, this condition simply becomes the well known condition $\sum_k 1 - |a_k| < +\infty$ where $X = \{a_k\}_k$, each $a_k$ counted accordingly to its multiplicity. It is also well known that any sequence $(a_k)_k$ satisfying the Blaschke Condition is the zero set of a function $f$ belonging to $\mathcal{N}(D)$ and of a function $g$ belonging to $\mathcal{H}^p(D)$, $p > 0$. This in particular means that the functions of the Nevanlinna class and the functions of the Hardy spaces have the same zero sets.

In $\mathbb{C}^n$, $n > 1$, the situation is much more intricate. It was proved independently by Henkin [18] and Skoda [27] that when $D$ is strictly pseudoconvex and satisfies some obvious topological condition, any divisor which satisfies the Blaschke Condition (B) is the zero set of a function $f \in \mathcal{N}(D)$. Some partial results are known for the polydisc ([6,9]), or special domains ([13]) and the Henkin–Skoda Theorem was also proved for pseudoconvex domains of finite type in $\mathbb{C}^2$ ([12]), for convex domains of finite strict type in $\mathbb{C}^n$ ([10]) and for convex domain of finite type in $\mathbb{C}^n$ ([16]).

In the case of Hardy spaces in $\mathbb{C}^n$, $n > 1$, the situation is even more complicated. Contrary to the one dimensional case, the zero sets of functions in the Nevanlinna class and the zero sets of functions in the Hardy classes are different. Moreover, for distinct $p$ and $q$, the zero sets of functions of $\mathcal{H}^p$- and $\mathcal{H}^q$-classes are different (see [25]). However, Varopoulos managed to give in [28] a general condition for a divisor $\hat{X}$ to be the zero set of an holomorphic function belonging to $\mathcal{H}^p(D)$, for some $p > 0$. Varopoulos’ proof was simplified by Andersson and Carlsson [7]. Bruna and Grellet attempted in [11] to generalize Varopoulos result to the case of convex domains of finite strict type, but there are some gaps in their proof. We aim to prove in this article the generalization of Varopoulos result to the case of convex domains of finite type in $\mathbb{C}^n$, which includes in particular the case of convex domains of finite strict type.

1.2 Varopoulos’ result

We will now present Varopoulos’ result and the scheme of its proof that we translate to the framework of convex domains of finite type. We will also explain the differences with the situation of convex domains of finite type.

Varopoulos used the Lelong current associated with a divisor $\hat{X}$ in order to define what he called a Uniform Blaschke Condition. Lelong proved that any divisor $\hat{X}$ can be associated with a closed positive $(1, 1)$-current $\theta = \theta_\hat{X}$ of order 0, that is a $(1, 1)$-form $\theta = \sum_{j,k=1}^n \theta_{j,k} dz_j \wedge d\bar{z}_k$, where each $\theta_{j,k}$ is a complex measure such that $d\theta = 0$ and for all $\lambda_1, \ldots, \lambda_n \in \mathbb{C}$, $\sum_{j,k=1}^n \theta_{j,k} \lambda_j \bar{\lambda}_k$ is a positive measure. The Blaschke Condition (B) can be reformulated by asking that $d\cdot|\theta|$ be a bounded measure on $D$. Varopoulos condition also involved $d\cdot|\theta|$, and in particular required $d\cdot|\theta|$, to be not only a bounded measure, but a Carleson measure. We
here give the definition of Carleson measures in the setting of convex domains of finite type. This notion is related to the structure of homogeneous space on $D$ induced by the polydics of McNeal defined in [20–22]. They are the analog of Koranyi balls of strictly convex domains and they are defined as follows. For $z$ near $bD$, small positive $\varepsilon$ and $v \in \mathbb{C}^n$, $v \neq 0$, we set

$$
\tau(z, v, \varepsilon) := \sup\{t > 0, |r(z + \lambda v) - r(z)| < \varepsilon, \forall \lambda \in \mathbb{C}, |\lambda| < t\}.
$$

This positive number $\tau(z, v, \varepsilon)$ is the distance from $z$ to the level set $\{r = r(z) + \varepsilon\}$ in the complex direction $v$. We now recall the definition of an $\varepsilon$-extremal basis $w_1^*, \ldots, w_n^*$ at the point $z$, given in [10]: $w_i^* = \eta_z$ is the outer unit normal to $bD_r(z)$ at $z$ and if $w_i^*, \ldots, w_{i-1}^*$ are already defined, then $w_i^*$ is a unit vector orthogonal to $w_i^*, \ldots, w_{i-1}^*$ such that $\tau(z, w_i^*, \varepsilon) = \sup_{1 \leq w_1^*, \ldots, w_{i-1}^*} \tau(z, v, \varepsilon)$. When $D$ is strictly convex, $w_1^*$ is the outer unit normal to $bD_r(z)$ and we may choose any basis of $T_z bD_r(z)$ for $w_1^*, \ldots, w_n^*$. Therefore, when $D$ is strictly convex, an $\varepsilon$-extremal basis at $z$ can be chosen smoothly depending on the point $z$. Unfortunately, this is not the case for convex domains of finite type (see [17]).

We put $\tau_i(z, \varepsilon) = \tau(z, w_i^*, \varepsilon)$, for $i = 1, \ldots, n$. Writing $A \preceq B$ if there exists a constant $c > 0$ such that $A \leq cB$ and $A \simeq B$ if $A \preceq B$ and $B \preceq A$ both hold, we have for a strictly convex domain $\tau_1(z, \varepsilon) \simeq \varepsilon$ and $\tau_j(z, \varepsilon) \simeq \varepsilon^{\frac{1}{j}}$ for $j = 2, \ldots, n$. For a convex domain of finite type $m$, we only have $\varepsilon^{\frac{1}{j}} \simeq \tau_n(z, \varepsilon) \leq \cdots \leq \tau_n(z, \varepsilon) \simeq \varepsilon^\frac{1}{m}$, uniformly with respect to $z$ and $\varepsilon$.

The McNeal polydisc centered at $z$ of radius $\varepsilon$ is the set

$$
\mathcal{P}_\varepsilon(z) := \left\{ \zeta = z + \sum_{i=1}^n \xi_i^* w_i^* \in \mathbb{C}^n, |\xi_i^*| < \tau_i(z, \varepsilon), i = 1, \ldots, n \right\}.
$$

**Definition 1.1** We say that a positive finite measure $\mu$ on $D$ is a Carleson measure and we write $\mu \in W^1(D)$ if

$$
\|\mu\|_{W^1(D)} := \sup_{z \in bD} \frac{\mu(\mathcal{P}_\varepsilon(z) \cap D)}{\sigma(\mathcal{P}_\varepsilon(z) \cap bD)} < \infty.
$$

Varopoulos Uniform Blaschke Condition requires that

$$
d|\theta|, \ d^\frac{1}{2}|\partial r \wedge \theta|, \ d^\frac{1}{2}|\overline{\partial} r \wedge \theta|, \ and \ |\partial r \wedge \overline{\partial} r \wedge \theta| \ belong \ to \ W^1(D). \quad (UB)
$$

The factors $d, d^\frac{1}{2}$ are weights which actually depend on the components of $\theta$. For example in $\partial r \wedge \theta$, the exterior product of $\theta$ with $\partial r$ cancels the normal component of $\theta$ in $dz$ so that only the tangential part of $\theta$ in $dz$ is left. Varopoulos put in front of this tangential part a factor $d^\frac{1}{2}$, the exponent $\frac{1}{2}$ being, in Varopoulos’ case of strictly pseudoconvex domains, 1 over the order of contact of a tangent vectors field and the boundary of $D$. This in particular means that the normal component of $\theta$ can behave in a worse manner than the $dz$-tangential component which itself can behave in a worse manner than the whole tangential component, this worse behavior being quantified by the order of contact of vectors fields with the boundary.

The situation is more complicated in the case of convex domains of finite type because the order of contact of tangential vectors fields is not constant. In order to overcome this difficulty, we use the following norm defined in [10]. For $z \in \mathbb{C}^n$ and $v$ a non zero vector we set

$$
k(z, v) := \frac{d(z)}{\tau(z, v, d(z))}.
$$
For a fixed \( z \), the convexity of \( D \) implies that the function defined by \( v \mapsto k(z, v) \) if \( v \neq 0 \), 0 otherwise, is a kind of non-isotropic norm. In the case of strictly convex domains, when \( v \) belongs to \( T^c_z bD_r(z) \), \( k(z, v) \) is comparable to \( d^\frac{1}{2} \), whereas if \( \eta_z \) is the unit outer normal to \( bD_d(z) \) at \( z \), \( k(z, \eta_z) \) is comparable to 1. This implies that the factor \( d^\frac{1}{2} \) in (UB) is equal to \( \frac{1}{k(z, v) k(z, \eta_z)} \) where \( v \) is any tangent vector field, the factor \( d \) is in fact \( \frac{d}{k(z, v) k(z, \eta_z)} \) and the factor “1” in front of \( |\partial r \wedge \overline{\partial} r \wedge \theta| \) is actually \( \frac{d}{k(z, v) k(z, \eta_z)} \), \( v \) and \( w \) being any tangent vector fields.

In a Uniform Blaschke Condition for convex domains of finite type, \( v \) and \( w \) have to appear explicitly because we need to link the weight \( \frac{d}{k(z, v) k(z, \eta_z)} \) and the “component of \( \theta \) in the directions \( v \) and \( w \)”.

### 1.3 Main result

In order to have a Uniform Blaschke Condition type which makes sense for general currents with measure coefficients and not only for smooth currents, we set the following definition (compare with the Uniform Blaschke Condition of [11] which makes sense only for smooth currents):

**Definition 1.2** We say that a \((p, q)\)-current \( \mu \) of order 0 with measure coefficients is a \((p, q)\)-Carleson current if

\[
\|\mu\|_{W^1_{p, q}} := \sup_{u_1, \ldots, u_p, q} \left\| \frac{1}{k(\cdot, u_1) \ldots k(\cdot, u_p, q)} \right\|_{W^1} < \infty,
\]

where the supremum is taken over all smooth vector fields \( u_1, \ldots, u_p, q \) which never vanish and where \( |\mu(\cdot)|_{[u_1, \ldots, u_p, q]} \) is the absolute value of the measure \( \mu(\cdot)|_{[u_1, \ldots, u_q]} \).

We denote by \( W^1_{p, q}(D) \) the set of all \((p, q)\)-Carleson currents.

A \( r \)-Carleson current is a sum of \((p, q)\)-Carleson currents with \( p + q = r \).

This norm was already defined and used in [4]. It is a norm on forms with measure coefficients associated with the vectorial norm \( k \). It is defined in the same spirit as the norms used in [5, 7] but \( \| \cdot \|_{W^1_{p, q}} \) takes into account the non isotropy of the boundary of the domain. In the case of strictly convex domains, we notice that if \( \theta \) satisfies the Uniform Blaschke Condition (UB), then \( d \cdot \theta \) is a \((1, 1)\)-Carleson current. We will prove the following theorem which is our main result and which, together with the preceding remarks, extends Varopoulos’ result [28] to the case of convex domains of finite type:

**Theorem 1.3** (Main Theorem) Let \( D \) be a \( C^\infty \)-smooth convex domain of finite type, \( \hat{X} \) a divisor in \( D \), \( \hat{\theta}_X \) the \((1, 1)\)-current of Lelong associated with \( \hat{X} \). Then, if \( d \cdot \hat{\theta}_X \) is a Carleson current, there exist \( p > 0 \) and \( f \in \mathcal{H}^p(D) \) such that \( \hat{X} \) is the zero set of \( f \).

**Remark 1** As pointed out by the referee, one could compare the norms and conditions defined here with the ones used in [11, 23] in the case of smooth currents. More precisely, Proposition 2.12 can be generalized to any smooth \((p, q)\)-current \( \mu \). Using this generalization one could show, for a smooth \((p, q)\)-current \( \mu \), that \( \|\mu\|_{W^1_{\{p, q\}}} \approx \|\mu(\cdot)|_{k}\|_{W^1} \), uniformly with respect to \( \mu \), where \( \|\mu(\cdot)|_{k}\| \) was defined in [10] as follows: for all \( \xi \),

\[
\|\mu(\xi)|_{k}\| := \sup \left\{ \frac{|\mu(\xi)|_{u_1, \ldots, u_p, q}}{k(\xi, u_1) \ldots k(\xi, u_p, q)}, u_1, \ldots, u_p, q \in \mathbb{C}^n \setminus \{0\} \right\}.
\]

Bruna–Grellier and Nguyen proved respectively for convex domains of finite strict type in [11] and for convex domains of finite type in [23] that if \( d \cdot \hat{\theta}_X \) is a \((1, 1)\)-current such that
is finite, then there exist \( p > 0 \) and \( f \in \mathcal{H}^p(D) \) such that \( \hat{X} \) is the zero set of \( f \).

A first problem is that when we are given a divisor \( \hat{X} \), \( \theta_{\hat{X}} \) is in general not smooth. Therefore the main results of [11,23] make sense only when \( \theta_{\hat{X}} \) is smooth. In order to prove their main results, the authors used a regularization argument as we will do (see Sect. 1.4 below) and solved successively a Poincaré equation and a \( \overline{\partial} \)-equation for smooth forms. Since we will also solve both equations for smooth forms and since our condition “\( \|d \cdot \theta_{\hat{X}}\|_k \) is a Carleson current” and their condition “\( \|d \cdot \hat{\theta}_{\hat{X}}\|_k \) is a Carleson measure” are equivalent for smooth currents, one could think of using their work on smooth currents in order to prove our main Theorem. However, there are some other gaps in Bruna–Grellier’s proof of the existence of a suitable solution of the Poincaré equation. Their “proof”, which does not use the strict type hypothesis but only the finite type hypothesis, was also used by Nguyen. Therefore, we cannot use any of these works in order to solve the Poincaré equation. However the work of Nguyen on the \( \overline{\partial} \)-equation in convex domains of finite type may be used here in order to get a suitable solution of the \( \overline{\partial} \)-equation. But as Nguyen’s article was never published, we will give here a complete proof.

1.4 Scheme of the proof of the main result

The main scheme of the proof is classical: we have to find a real valued function \( u \) such that \( i\partial\overline{\partial}u = \theta_{\hat{X}} \) with a growth condition on \( u \). Since \( D \) is convex, such a function \( u \) is equal to \( \log |f| \) for an \( f \) that defines \( \hat{X} \).

In order to find \( u \), we proceed in two steps. First we solve the equation \( i dw = \theta_{\hat{X}} \) with \( w \) such that \( w = -\overline{w} \). This is done thanks to the following theorem.

**Theorem 1.4** Let \( D \) be a \( C^\infty \)-smooth bounded convex domain of finite type, \( \theta \) a \( d \)-closed \((1,1)\)-current of order \( 0 \) such that \( d \cdot \theta \) is a Carleson current. Then there exists a real \( 1 \)-Carleson current \( \omega \) such that \( d\omega = \theta \).

We then set \( w = -i\omega \), where \( \omega \) is given by Theorem 1.4, so that \( \overline{w} = -w \). We write \( w \) as \( w = w_{1,0} + w_{0,1} \) where \( w_{1,0} \) is a \((1,0)\)-Carleson current and \( w_{0,1} \) is a \((0,1)\)-Carleson current. We trivially have \( \overline{w}_{0,1} = -w_{1,0} \). Moreover, since \( i dw = \partial w_{1,0} + \overline{\partial} w_{1,0} + \partial w_{0,1} + \overline{\partial} w_{0,1} \), and since \( i dw = \theta \) is a \((1,1)\)-current, for bidegree reasons we have \( \partial w_{1,0} = 0 \), \( \overline{\partial} w_{1,0} = \partial w_{0,1} \) and \( \overline{\partial} w_{0,1} = 0 \). Since \( D \) is convex, we can find \( v \) such that \( \overline{\partial} v \equiv \partial w_{0,1} \). Setting \( u = 2\partial v \), we get

\[
\begin{align*}
  i \partial \overline{\partial} u &= i \partial \overline{\partial} v - i \overline{\partial} \partial v \\
  &= i \partial \overline{\partial} v - i \overline{\partial} \overline{\partial} v \\
  &= i \partial w_{0,1} - \overline{\partial} w_{0,1} \\
  &= i \partial w_{0,1} + \overline{\partial} w_{1,0} \\
  &= i dw = \theta.
\end{align*}
\]

Therefore, in order to prove our main theorem, we have to find a solution of the \( \overline{\partial} \)-equation \( \overline{\partial} v = w_{0,1} \) with \( \exp v \) in \( L^p(bD) \). It is given by the following theorem:

**Theorem 1.5** Let \( D \) be a \( C^\infty \)-smooth convex domain of finite type and let \( \omega \) be a \( \overline{\partial} \)-closed \((0,1)\)-Carleson current in \( D \). Then there exist \( p > 0 \) and a solution \( v \) to the equation \( \overline{\partial} v = \omega \) such that \( \exp v \) belongs to \( L^p(bD) \).

We now give the scheme of the proofs of Theorems 1.4 and 1.5. In order to prove Theorem 1.4, without restriction, we will assume that \( 0 \) belongs to \( D \), that \( 0 \) does not belong to
supp(θ) and that θ is supported in a sufficiently small neighborhood of bD. We will use the Poincaré homotopy operator and we need a deformation retract h : D × [0, 1] → D of D onto 0. Using convexity, Bruna, Charpentier and Dupain simply defined h by h(z, t) = t · z. However, as already pointed out by Varopoulos [28], this choice does not work for Hardy spaces. In this case, it is necessary to take the mean value of a suitable family of homotopy operators. We now give an analogue for strictly convex domains of the deformation retract used by Andersson and Carlsson [7] and Varopoulos [28].

Still assuming that 0 belongs to D, we denote by p the calibrator or gauge function for D, that is \( p(ζ) = \inf\{λ > 0, \, z ∈ λ D\} \), and from now on \( r = p - 1 \). We notice that since p is homogeneous, the level sets \( bD_ε \) are homotetic and \( τ(z, v, ε) \) itself becomes homogeneous. Moreover, with such a choice of a defining function, for all \( t > 0 \), any \( v \) belongs to \( T_z^C bD_r(z) \) if and only if it belongs to \( T_{z_0}^C bD_{r(z)} \). Let \( w_1^*(z) \) be the outer unit normal to \( bD_{r(z)} \) at \( z \), let \( w_2^*(z), \ldots, w_n^*(z) \) be a basis of \( T_{z_0}^C bD_{r(z)} \) smoothly depending on \( z \), which is always possible at least locally. We notice that, for all \( t > 0 \), \( w_1^*(z) \) is the outer unit normal to \( bD_{r(z)} \) at \( tz \), and that \( w_2^*(z), \ldots, w_n^*(z) \) is a basis of \( T_{z_0}^C bD_{r(z)} \). Therefore we can assume that \( w_j^*(tz) = w_j^*(z) \) for all \( t > 0 \). Then for \( Λ = (λ_1, \ldots, λ_n) ∈ \mathbb{D}^n \), \( Λ = [ξ ∈ \mathbb{C}, \ |ξ| < 1] \), define \( h_Λ : D × [0, 1] → D \) by

\[
h_Λ(z, t) = tz + t \left( (1 - t)λ_1 w_1^*(tz) + \sum_{j=2}^{n} λ_j \sqrt{1 - t} \cdot w_j^*(tz) \right),
\]

and set

\[
Hθ = \frac{1}{(Vol(Δ))^n} \int_{Δ^n} \left( \int_{[0,1]} h_Λ^*(θ) \right) dΛ
\]

where the inner integral is the \( t \)-integral of the \( dt \)-component of \( h_Λ^*θ \). We have \( h_Λ(z, 0) = 0 \) and \( h_Λ(z, 1) = z \) for all \( z ∈ D \), \( h_Λ \) is smooth in \( D × ]0, 1[ \) for all \( Λ \) and thus \( dH + Hd = Id \).

Let us look a bit at what \( h_Λ \) and \( H \) do. When \( Λ \) is fixed, \( h_Λ(z, \cdot) \) is a path from 0 to \( z \) which, for all \( Λ ≠ 0 \), is not a straight line as in [10]. Each \( h_Λ \) induces an homotopy operator and \( H \) is in fact the mean value of these homotopy operators.

Let us fix \( z \) and \( t \) and let \( Λ \) varies over \( \mathbb{D}^n \). When \( D \) is a strictly convex domain, the factor \( \sqrt{1 - t} \) in \( h_Λ \) is comparable to \( τ(tz, w_j^*(tz), 1 - t) \) for all \( j = 2, \ldots, n \), the factor \( 1 - t \) is comparable to \( τ(tz, w_1^*(tz), 1 - t) \). In particular, when \( Λ \) varies over \( \mathbb{D}^n \), the image of \( h_Λ(z, t) \) is \( P_{1-}(tz) \).

So, when \( D \) is a convex domain of finite type, our first attempt at a proof could simply be to replace in \( h_Λ \) the vectors \( w_j^*(tz) \) by a \((1 - t)\)-extremal basis at \( tz \) that we still denote by \( w_j^*(tz), \ j = 1, \ldots, n \), and the factor \( \sqrt{1 - t} \) by \( τ(tz, w_j^*(tz), 1 - t) \) for \( j = 2, \ldots, n \), and \( 1 - t \) by \( τ(tz, w_1^*(tz), 1 - t) \). However, \( h_Λ \) would not be smooth because \( ε \)-extremal bases at \( z \) may behave in a really bad way and, in general, do not depend continuously on \( ε \) or on \( z \) (see [17]). The first difficulty to overcome is to find a smooth way of describing \( P_{1-}(tz) \).

More precisely, we have to find a smooth map \( h_Λ : D × [0, 1] → D \) with the following properties: for all \( Λ \) in \( \mathbb{D}^n(ρ) = \{ Λ ∈ C^n, \ |Λ| < ρ \} \) (where \( ρ > 0 \) is a small number which has to be determined) \( h_Λ(z, 0) = 0 \), \( h_Λ(z, 1) = z \), and there exist a uniform constant \( γ > 0 \), and \( C > c > 0 \) depending on \( ρ \) such that for fixed \( z ∈ D, \ t ∈ [0, 1 - γd(z)] \):

\[
cP_{1-}(tz) ⊂ \{h_Λ(z, t), \ |Λ| < ρ \} ⊂ C P_{1-}(tz).
\]

We will explain later why we only require that these properties hold only for \( t ∈ [0, 1 - γd(z)] \) and not for \( t \) in the whole interval \([0, 1]\). Moreover, for technical reasons that will become clear later on, we also want that \( C \) goes to 0 when \( ρ \) goes to 0. 
We will achieve this aim thanks to the Bergman metric (see Sect. 2.1 for the definition of the Bergman metric). The next two propositions link McNeal polydiscs and the Bergman metric in convex domains of finite type. The first one was proved by McNeal [21].

**Proposition 1.6** Let $\zeta \in D$ be a point near $bD$, $\varepsilon > 0$ and $w_1^*, \ldots, w_n^*$ an $\varepsilon$-extremal basis at $\zeta$ and $v = \sum_{j=1}^n v_j^* w_j^*$ a unit vector. Then, uniformly with respect to $\zeta$, $v$ and $\varepsilon$, we have

$$\frac{1}{\tau(\zeta, v, \varepsilon)} \approx \sum_{j=1}^n \frac{|v_j^*|}{\tau_j(\zeta, \varepsilon)}.$$ 

Therefore $P_{\varepsilon}(\zeta)$ could also be defined as the set $\{\zeta + \lambda v, \; v \in \mathbb{C}^n, |v| = 1, \lambda \in \mathbb{C}, |\lambda| < \tau(\zeta, v, \varepsilon)\}$. 

Now, let $B(\zeta)$ be the matrix in the canonical basis which determines the Bergman metric $\| \cdot \|_{B, \zeta}$ at $\zeta$, i.e. $\|v\|_{B, \zeta} = \overline{v}^T B(\zeta) v$ for any vector $v$. We recall that $B$ depends smoothly on $\zeta \in D$ but explodes on the boundary. The following result was proved by McNeal [22].

**Proposition 1.7** Let $\zeta \in D$ be a point near $bD$, $v$ a unit vector in $\mathbb{C}^n$. Then, uniformly with respect to $\zeta$ and $v$,

$$\|v\|_{B, \zeta} \approx \frac{1}{\tau(\zeta, v, d(\zeta))}.$$ 

Therefore there exist $C > c > 0$ such that for all $\zeta$ near $bD$ and $\rho > 0$

$$c \rho P_{d(\zeta)}(\zeta) \subset \{\zeta + \lambda v, \; v \in \mathbb{C}^n, |v| = 1 \text{ and } \|\lambda v\|_{B, \zeta} < \rho\} \subset C \rho P_{d(\zeta)}(\zeta). \quad (1)$$

Since the Bergman metric is an hermitian metric, for all $\zeta \in D$ there exists a positive hermitian matrix $A(\zeta)$ such that $A(\zeta)^{-2} = B(\zeta)$. The inverse mapping theorem ensures that $A$ depends smoothly on $\zeta \in D$, and $\|A(\zeta)v\|_{B, \zeta} = |v|$ for all $\zeta$ and $v$. Therefore (1) becomes

$$c \rho P_{d(\zeta)}(\zeta) \subset \{\zeta + A(\zeta)v, \; |v| < \rho\} \subset C \rho P_{d(\zeta)}(\zeta). \quad (2)$$

Putting $\zeta = tz$, since $d(tz) = 1 - t + t d(z) \approx 1 - t$ when $t \leq 1 - \gamma d(z)$, Corollary 2.3 yields

$$c \rho P_{1-t}(tz) \subset \{tz + A(tz)v, \; |v| < \rho\} \subset C \rho P_{1-t}(tz) \quad (3)$$

for all $z$ and $t$ such that $0 \leq t \leq 1 - \gamma d(z)$. In other words, $\{tz + A(tz)v, \; |v| < \rho\}$ is almost equal to $\rho P_{1-t}(tz)$.

For $t$ close to 1, we cannot use $A$ in order to get a set which is almost equal to $P_{1-t}(tz)$. Indeed, $A(\zeta)$ yields a set which is almost equal to $P_d(\zeta)(\zeta)$ and by homogeneity of $r$, it is possible to obtain a set which is almost equal to $P_{1-t}(tz)$ using $A(\zeta)$ as in (3) with a point $\zeta = \lambda z \in D$ such that $d(\zeta) \approx 1 - t$ (that is for a point $\zeta$ close to $bD$ if $t$ is close to 1). However, when $\zeta$ goes to the boundary, the derivatives of $A(\zeta)$ explode, and actually they explode so much that the computations will not work. This problem does not appear in the strictly convex case because the extremal bases can be chosen to be smooth in a neighborhood of $D$.

It appears in the computations that, when $1 - t \leq \gamma d(z)$, there is in fact no need to take mean value of homotopy operators. But, in order that things work when $1 - t \approx d(z)$, we have to make a cleverer choice of retracts. We define $h_\Lambda$ as follows. Let $\varphi$ be a $C^\infty$ smooth function such that $\varphi(t) = 1$ if $t < \frac{1}{2}$, $\varphi(t) = 0$ if $t > 1$, and define the map $h_\Lambda : D \times [0, 1] \to D$ for $|\Lambda| \leq \rho$ by
where γ has to be chosen sufficiently small.

The associated homotopy operator is

\[ H\theta = \frac{1}{\text{Vol}(\Delta_n(\rho))} \int_{\Lambda \in \Delta_n(\rho)} \left( \int_{t \in [0,1]} h^*_\Lambda \theta \right) d\Lambda. \]

The map \( h_\Lambda \) is \( C^\infty \)-smooth in \( D \times ]0,1[ \), \( h_\Lambda(z,0) = 0 \) and \( h_\Lambda(z,1) = z \) for all \( z \) in \( D \). For fixed \( z \) and \( t \) such that \( 1 - t \geq \gamma d(z) \) we get from (3)

\[ c t \rho \mathcal{P}_{1-t}(z) \subset \{ h_\Lambda(z, t), \ |\Lambda| < \rho \} \subset C t \rho \mathcal{P}_{1-t}(z). \]  

From (2), for fixed \( z \) and \( t \) such that \( 1 - t \leq \gamma d(z) \) we have

\[ \{ h_\Lambda(z, t), \ |\Lambda| < \rho \} \subset C \rho \mathcal{P}_{d(z)}(z). \]  

Now that we have obtained a good homotopy formula, the rest of the proof of Theorem 1.4 consists of tedious computations that we carry out in Sect. 2. In order to estimate \( H\theta \), we will distinguish three cases, depending on whether \( 1 - t \leq \frac{\gamma}{2} d(z) \), \( 1 - t \geq \gamma d(z) \) or \( \frac{\gamma}{2} d(z) \leq 1 - t \leq \gamma d(z) \) (see Sects. 2.3, 2.4, 2.5 respectively).

We will be led to compute derivatives of \( h_\Lambda \) and so of \( A \). Moreover, we will need upper bounds for these derivatives. We will compute them by applying the inverse mapping theorem to the map \( \Phi \) defined on the set of positive hermitian matrices by \( \Phi(B) = B^{-2} \). In order to compute \( d\Phi^{-1} \), we will have to solve the equation \( BM + MB = M' \) where \( M' \) is given and where \( M \) is an unknown matrix. Because we need optimal estimates, we will need an explicit expression of \( M \). We will get it using ideas of Rosenblum [26] in Sect. 2.2, after we have given in Sect. 2.1 the tools related to convex domains of finite type.

The proof of Theorem 1.5 is more classical. We will follow ideas of [7,16,27] that we have to adapt to our new norm \( \| \cdot \|_{W^1} \). We will use Diederich-Mazzilli’s solution of the \( \overline{\partial} \)-equation, which itself involved a Skoda type integral operator constructed with the Diederich–Fornæss support function \( S \) for convex domains of finite type. In order to prove Theorem 1.5, we will have to estimate the \( W^1 \)-norm of our solution. Therefore we will need to find suitable vectors fields. It turns out that extremal bases realized the supremum in the kind of norm \( \| \cdot \|_k \) used in [10]. However, we need here smooth vectors fields and as we already said, extremal bases are not smooth. The Bergman metric (again) will give us vectors fields which will be a smooth alternative to extremal bases (see Sect. 3 for details).

2 The \( d \)-equation

In order to prove Theorem 1.4, we have to prove that for all non-vanishing vector fields \( u \), all \( z_0 \in bD \), all \( \varepsilon > 0 \), the following inequality holds uniformly:

\[ \int_{\mathcal{P}_x(z_0) \cap D} \frac{1}{k(z,u(z))} |H\theta(z)[u(z)]| d\lambda(z) \lesssim \sigma(\mathcal{P}_x(z_0) \cap bD) \|\theta\|_{W^1_{1,1}}. \]  

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By standard regularization arguments (see [7]), we can assume $\theta$ smooth on $D$. When we compute $H\theta(z)[u(z)]$, we get

$$H\theta(z)[u(z)]=\frac{1}{\text{Vol}(\Delta_n(\rho))}\int_{\Lambda \in \Delta_n(\rho)} \int_{t \in [0,1]} \theta(h_\Lambda(z,t)) \left[ \frac{\partial h_\Lambda}{\partial t}(z,t), d_z h_\Lambda(z,t)[u] \right] dt d\Lambda.$$  

(7)

The definitions of $\|\|_{W^{1,1}}$ and $h_\Lambda$ naturally lead us to compute $k(\zeta, dA_\xi[u] \cdot \Lambda_1)$. We will do this in Sect. 2.2 after having recalled in Sect. 2.1 the tools for convex domains of finite type that we will need in this section.

As we will see in the next subsection, the properties of convex domain of finite type are known only in a neighborhood of the boundary. This is why, without restriction since $D$ is convex, we assume that $\text{supp}(\theta) \subset D \setminus D_{-\varepsilon_0}$, $\varepsilon_0 > 0$ as small as we want. Moreover, since $|h_\Lambda(z,t) - tz| \lesssim \rho$ uniformly with respect to $\rho, t$ and $z$, if $t$ is small enough, $h_\Lambda(z,t)$ does not belong to $\text{supp}(\theta)$. Therefore there exists a uniform $t_0 > 0$ such that we only integrate in (7) for $t \in [t_0, 1]$.

### 2.1 Some tools for convex domains of finite type

We collect here many of the properties of McNeal’s polydiscs and of the radii $\tau(z, v, \varepsilon)$. The first ones come directly from their definition:

**Proposition 2.1** For all $v \in \mathbb{C}^n$, all $\zeta \in D$, all $\varepsilon > 0$ and all $\lambda \in \mathbb{C}^*$: $\tau(\zeta, v, \varepsilon) = |\lambda| \tau(\zeta, \lambda v, \varepsilon)$.

If $v$ is a unit vector belonging to $T^*_\zeta bD_{r(\zeta)}$, then $\varepsilon^{\frac{1}{2}} \lesssim \tau(\zeta, v, \varepsilon) \lesssim \varepsilon^{\frac{1}{n}}$, uniformly with respect to $\zeta, v$ and $\varepsilon$.

If $v = \eta_\zeta$ is the outer unit normal to $bD_{r(\zeta)}$ at $\zeta$, then $\tau(\zeta, \eta_\zeta, \varepsilon) \sim \varepsilon$.

The next property is proved in [10].

**Corollary 2.3** Let $z \in D$ be a point near $bD$, $v$ a unit vector in $\mathbb{C}^n$ and $\varepsilon_1 \geq \varepsilon_2 > 0$. Then we have uniformly with respect to $z, \varepsilon_1, \varepsilon_2$ and $v$

$$\left( \frac{\varepsilon_1}{\varepsilon_2} \right)^{\frac{1}{n}} \lesssim \frac{\tau(z, v, \varepsilon_1)}{\tau(z, v, \varepsilon_2)} \lesssim \frac{\varepsilon_1}{\varepsilon_2}.$$  

As a corollary of Propositions 1.6 and 2.2 we have:

**Corollary 2.3** Let $z \in D$ be a point near $bD$. If $\varepsilon_1, \varepsilon_2, k, K > 0$ are such that $k \varepsilon_1 \leq \varepsilon_2 \leq K \varepsilon_1$, there are constants $C \geq c > 0$, depending only on $k$ and $K$, such that

$$c \mathcal{P}_{\varepsilon_1}(z) \subset \mathcal{P}_{\varepsilon_2}(z) \subset C \mathcal{P}_{\varepsilon_1}(z).$$

In particular, for all $c > 0$, $\text{Vol}(\mathcal{P}_{c \varepsilon}(z)) \sim \text{Vol}(\mathcal{P}_\varepsilon(z))$ uniformly with respect to $z$ and $\varepsilon$. The following proposition, proved in [21], and Corollary 2.3 show that the polydiscs define a structure of homogeneous space on $D$.

**Proposition 2.4** There exists $C > 0$ such that, for all $\varepsilon > 0$ and all $z, \zeta$ in a neighborhood of $bD$, the following holds true: if $\mathcal{P}_\varepsilon(z) \cap \mathcal{P}_\varepsilon(\zeta) \neq \emptyset$ we have $\mathcal{P}_\varepsilon(z) \subset C \mathcal{P}_\varepsilon(\zeta)$. In particular, $\text{Vol}(\mathcal{P}_\varepsilon(z)) \sim \text{Vol}(\mathcal{P}_\varepsilon(\zeta))$ uniformly with respect to $\zeta, z$ and $\varepsilon$.  

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We set for $\zeta, z$ near $bD$
\[
\delta(z, \zeta) := \inf\{\epsilon > 0, \ \zeta \in \mathcal{P}_\epsilon(z)\}.
\]

Corollary 2.3 and Proposition 2.4 show that $\delta$ is a pseudodistance.

The following proposition is established in [21].

**Proposition 2.5** There exists $c > 0$ sufficiently small such that for all $z \in D$ near $bD$, all $\zeta \in c \mathcal{P}_d(z)$, we have $d(z) \approx d(\zeta)$, uniformly with respect to $z$ and $\zeta$.

The following proposition, shown in [21], allows us to compare $\tau(z, v, \epsilon)$ for different points $z$.

**Proposition 2.6** For all $z \in D$ near $bD$, all unit vector $v$ in $\mathbb{C}^n$, all $\epsilon > 0$ and all $\zeta \in \mathcal{P}_\epsilon(z)$, we have uniformly with respect to $z, \zeta, \epsilon$ and $v$
\[
\tau(z, v, \epsilon) \approx \tau(\zeta, v, \epsilon).
\]

As a corollary of Propositions 2.2, 2.5 and 2.6, we have

**Corollary 2.7** There exists $c > 0$ such that for all $z$ near $bD$, all $\zeta \in c \mathcal{P}_d(z)$, all $v \in \mathbb{C}^n$: $k(\zeta, v) \approx k(z, v)$, uniformly with respect to $z, \zeta$.

We will also need the following proposition (see [2,10,14]):

**Proposition 2.8** Let $w$ be any orthonormal coordinates system centered at $\zeta$ and let $v_j$ be the unit vector in the $w_j$-direction. For all multiindices $\alpha$ and $\beta$ with $|\alpha + \beta| \geq 1$ and all $z \in \mathcal{P}_\epsilon(\zeta)$:
\[
\left| \frac{\partial^{||\alpha||+|\beta|} r}{\partial w^\alpha \partial w^\beta} (z) \right| \lesssim \epsilon \prod_{j=1}^n \tau(\zeta, v_j, \epsilon)^{\alpha_j + \beta_j}
\]
uniformly with respect to $z, \zeta$ and $\epsilon$.

We now briefly recall the definition of the Bergman metric (see [24]) and its properties on a convex domain of finite type. The orthogonal projection from $L^2(D)$ onto $L^2(D) \cap \mathcal{O}(D)$, where $\mathcal{O}(D)$ is the set of holomorphic function on $D$, is called the Bergman projection. We denote it by $B$. There exists a unique integral kernel $b$ such that for all $f \in L^2(D)$:
\[
Bf(z) = \int_D b(\zeta, z) f(\zeta) d\lambda(\zeta).
\]
The kernel $b(\zeta, z)$ is called the Bergman kernel. This kernel is holomorphic with respect to $z$, antiholomorphic with respect to $\zeta$ and satisfies $b(\zeta, z) = \overline{b(z, \zeta)}$.

The Bergman metric $\| \cdot \|_{B, \zeta}$ for $\zeta \in D$ is an hermitian metric defined by the matrix $B(\zeta) = (B_{i,j}(\zeta))_{i,j=1,...,n}$ where $B_{i,j}(\zeta) = \frac{\partial^2}{\partial \zeta_i \partial \zeta_j} \ln b(\zeta, \zeta)$. This means that the Bergman norm of $v = \sum_{i=1}^n v_i e_i$, where $e_1, \ldots, e_n$ is the canonical basis of $\mathbb{C}^n$, is given by $\|v\|_{B, \zeta} = \left(\sum_{i,j=1}^n B_{i,j}(\zeta) v_i \overline{v_j}\right)^{1/2}$.

Using Theorems 3.4 and 5.2 of [21] and Proposition 1.6, we easily get
Theorem 2.9 For all $\zeta \in D$ in a neighborhood of $bD$, we have

$$b(\zeta, \zeta) \gtrsim \frac{1}{\text{Vol}(\mathcal{P}_{d(\zeta)}(\zeta))}.$$ 

Let $w$ be any orthonormal coordinates system centered at $\zeta$ and let $v_j$ be the unit vector in the $w_j$-direction. Then we have uniformly with respect to $\zeta$:

$$\left| \frac{\partial^{\alpha\beta}|\alpha|+|\beta|b}{\partial w^\alpha \partial \overline{w}^\beta}(\zeta, \zeta) \right| \lesssim \frac{1}{\text{Vol}(\mathcal{P}_{d(\zeta)}(\zeta))} \prod_{j=1}^n \tau(\zeta, v_j, d(\zeta))^{\alpha_j+\beta_j}.$$ 

Theorem 2.9 yields to the following corollary:

**Corollary 2.10** Let $\zeta \in D$ be a point near $bD$, let $w$ be any orthonormal coordinates system centered at $\zeta$, let $v_j$ be the unit vector in the $w_j$-direction and let $(B_{ij}^w)_{i,j}$ be the Bergman matrix in the $w$-coordinates. Then we have uniformly with respect to $\zeta$:

$$\left| \frac{\partial^{\alpha\beta}|\alpha|+|\beta|B_{ij}^w}{\partial w^\alpha \partial \overline{w}^\beta}(\zeta) \right| \lesssim \frac{1}{\prod_{j=1}^n \tau(\zeta, v_j, d(\zeta))^{\alpha_j+\beta_j}}.$$ 

McNeal proved in [22]:

**Proposition 2.11** Let $\zeta \in D$ be a point near $bD$ and let $\lambda_1(\zeta) \geq \lambda_2(\zeta) \geq \ldots \geq \lambda_n(\zeta)$ be the eigenvalues of $B(\zeta)$. Then uniformly with respect to $\zeta$:

$$\lambda_1(\zeta) \approx \tau_1(\zeta, d(\zeta))^{-2}, \quad \lambda_2(\zeta) \approx \tau_n(\zeta, d(\zeta))^{-2}, \quad \ldots, \quad \lambda_n(\zeta) \approx \tau_2(\zeta, d(\zeta))^{-2}.$$ 

This also implies that $\det B(\zeta) \approx (\text{Vol}(\mathcal{P}_{d(\zeta)}(\zeta)))^{-1}$, uniformly with respect to $\zeta$.

We denote by $e_j(\zeta)$ the $j$-th column of the matrix $A(\zeta)$ so that $e_1(\zeta), \ldots, e_n(\zeta)$ is an orthonormal basis of $\mathbb{C}^n$ for the Bergman metric. We then end this section with the following proposition:

**Proposition 2.12** For all vectors fields $u$ and $v$, all smooth $(1, 1)$-current $\theta$ and all $\zeta \in D$, we have

$$\frac{|\theta(\zeta)||u(\zeta), v(\zeta)|}{k(\zeta, u(\zeta))k(\zeta, v(\zeta))} \lesssim \sum_{j,k=1}^n \frac{|\theta(\zeta)||e_j(\zeta), e_k(\zeta)|}{k(\zeta, e_j(\zeta))k(\zeta, e_k(\zeta))}.$$ 

**Proof** We write $u = \sum_{j=1}^n u_j e_j$ and $v = \sum_{j=1}^n v_j e_j$. We thus have

$$\frac{|\theta(\zeta)||u(\zeta), v(\zeta)|}{k(\zeta, u(\zeta))k(\zeta, v(\zeta))} \lesssim \sum_{j,k=1}^n |u_j(\zeta)||v_k(\zeta)| \frac{|\theta(\zeta)||e_j(\zeta), e_k(\zeta)|}{k(\zeta, e_j(\zeta))k(\zeta, e_k(\zeta))}.$$ 

From Proposition 1.7 we have $k(\zeta, u(\zeta)) \approx d(\zeta)||u||_{B,\zeta}$ and since $e_1(\zeta), \ldots, e_n(\zeta)$ is an orthonormal basis for the Bergman metric $k(\zeta, u(\zeta)) \approx d(\zeta)\sqrt{\sum_{j=1}^n |u_j(\zeta)|^2} \gtrsim d(\zeta)||u_j(\zeta)||$. The same holds true for $v$ and so

$$\frac{|\theta(\zeta)||u(\zeta), v(\zeta)|}{k(\zeta, u(\zeta))k(\zeta, v(\zeta))} \lesssim \sum_{j,k=1}^n \frac{|\theta(\zeta)||e_j(\zeta), e_k(\zeta)|}{d(\zeta)^2}.$$ 

Finally, again since $e_1(\zeta), \ldots, e_n(\zeta)$ is an orthonormal basis for the Bergman metric, $k(\zeta, e_j(\zeta)) \approx d(\zeta)||e_j(\zeta)||_{B,\zeta} \approx d(\zeta)$ and the proof of the proposition is complete.
2.2 Derivatives of the matrix $A$

We will need upper bounds of $k(\zeta, dA_\zeta [u] \cdot \Lambda)$ for any vector $u$. Since $k(\zeta, dA_\zeta [u] \cdot \Lambda) \approx d(\zeta)\|dA_\zeta [u] \cdot \Lambda\| B, \zeta$, we look for an upper bound of $\|dA_\zeta [u] \cdot \Lambda\| B, \zeta$.

First we compute $dA_\zeta$. Let $\mathcal{H}_n$ be the set of hermitian matrices in $\mathbb{C}^n$, let $\mathcal{H}_n^{++}$ be the set of positive definite hermitian matrices in $\mathbb{C}^n$ and let $\Phi : \mathcal{H}_n^{++} \to \mathcal{H}_n^{++}$ be defined by $\Phi(M) = M^{-2}$. The map $\Phi$ is one to one and for all $\zeta \in D$, $A(\zeta) = \Phi^{-1}(B(\zeta))$. We use the inverse mapping theorem in order to deduce from Corollary 2.10 the needed estimates on $A(\zeta)$. For $M \in \mathcal{H}_n^{++}$ and $H \in \mathcal{H}_n$. We have:

$$d\Phi_M(H) = M^{-2}(MH + HM)M^{-2}.$$

We want to compute the inverse of $d\Phi_M$. We first notice that $d\Phi_M(H) = H'$ if and only if $MH + HM = M^2H'M^2$. We use ideas of Rosenblum [26] in order to solve explicitly this equation. The computations are quiet similar but not exactly the same. We give them for completeness.

Let $\Omega$ be a bounded open set in $\mathbb{C}$ such that $\text{sp}(M)$, the spectrum of $M$, is included in $\Omega$, and $\text{sp}(-M) \cap \overline{\Omega} = \emptyset$. This is always possible because $\text{sp}(M)$ is included in $][0, +\infty[$. We denote by $I_n$ the identity matrix in $\mathbb{C}^n$. No $\xi$ in $b\Omega$ belongs to $\text{sp}(M) \cup \text{sp}(-M)$, so $\xi I_n + M$ and $\xi I_n - M$ are invertible and Dunford’s functional calculus asserts that

$$\frac{1}{2i\pi} \int_{b\Omega} (M - \xi I_n)^{-1} M^2 H' M^2 d\xi = M^2 H'M^2, \quad (8)$$

$$\frac{1}{2i\pi} \int_{b\Omega} M^2 H'M^2 (M + \xi I_n)^{-1} d\xi = 0. \quad (9)$$

Therefore, setting $H = \frac{1}{2i\pi} \int_{b\Omega} (M - \xi I_n)^{-1} M^2 H'M^2 (M + \xi I_n)^{-1} d\xi$, Equalities (8) and (9) yield

$$MH + HM = \frac{1}{2i\pi} \int_{b\Omega} (M - \xi I_n)^{-1} M^2 H'M^2 (M + \xi I_n)^{-1} d\xi$$

$$+ \frac{1}{2i\pi} \int_{b\Omega} (M - \xi I_n)^{-1} M^2 H'M^2 (M + \xi I_n)^{-1} M d\xi$$

$$= \frac{1}{2i\pi} \int_{b\Omega} (M - \xi I_n)(M - \xi I_n)^{-1} M^2 H'M^2 (M + \xi I_n)^{-1} d\xi$$

$$+ \frac{1}{2i\pi} \int_{b\Omega} (M - \xi I_n)(M - \xi I_n)^{-1} M^2 H'M^2 (M + \xi I_n)^{-1} (M + \xi I_n) d\xi$$

$$= M^2 H'M^2.$$

Thus, by the inverse mapping theorem, we get

$$d\Phi^{-1}_{B(\zeta)}(H') = \frac{1}{2i\pi} \int_{b\Omega_{\zeta}} (\Phi^{-1}(B(\zeta)) - \xi I_n)^{-1} (\Phi^{-1}(B(\zeta)))^2 H'(\Phi^{-1}(B(\zeta)))^2$$

$$\quad \cdot (\Phi^{-1}(B(\zeta)) + \xi I_n)^{-1} d\xi$$

where $\Omega_{\zeta}$ is any bounded open set in $\mathbb{C}$ such that $\text{sp}(\Phi^{-1}(B(\zeta)))$ is included in $\Omega_{\zeta}$ and $\text{sp}(-\Phi^{-1}(B(\zeta))) \cap \overline{\Omega_{\zeta}} = \emptyset$.

Let $u$ be a unit vector in $\mathbb{C}^n$. We fix $\zeta_0 \in D$ and an orthonormal basis $w_1, \ldots, w_n$ on $\mathbb{C}^n$, orthogonal for $B(\zeta_0)$. We denote by $B^w(\zeta)$ the matrix of the Bergman metric in the

\[ Springer \]
Corollary 2.10 and Proposition 2.11 imply that 
\[
\begin{bmatrix}
\lambda_1(\zeta_0) & 0 \\
& \ddots & \ddots \\
0 & & \lambda_n(\zeta_0)
\end{bmatrix},
\lambda_1(\zeta_0) > \lambda_2(\zeta_0) \geq \ldots \geq \lambda_n(\zeta_0).
\]
We denote by \( P \) the unitary matrix such that 
\[
B(\zeta_0) = PB(\zeta_0)\overline{P}^T.
\]
We also define the two diagonal matrices 
\[
B^w(\zeta_0)^{-\frac{1}{2}} = \begin{bmatrix}
\lambda_1(\zeta_0)^{-\frac{1}{2}} & 0 \\
& \ddots & \ddots \\
0 & & \lambda_n(\zeta)^{-\frac{1}{2}}
\end{bmatrix}
\]
and 
\[
B^w(\zeta_0)^{\frac{1}{2}} = \begin{bmatrix}
\lambda_1(\zeta)^{\frac{1}{2}} & 0 \\
& \ddots & \ddots \\
0 & & \lambda_n(\zeta)^{\frac{1}{2}}
\end{bmatrix}
\]
such that 
\[
A(\zeta_0) = PB^w(\zeta_0)^{-\frac{1}{2}}\overline{P}^T.
\]
We have 
\[
dA_{\zeta_0}[u] \cdot \Lambda = \frac{1}{2\pi} PD(\zeta_0)\overline{P}^T \cdot \Lambda,
\]
where 
\[
D(\zeta_0) = \int_{b\Omega_{\zeta_0}} (B^w(\zeta_0)^{-\frac{1}{2}} - \xi I_n)^{-1} B^w(\zeta_0)^{-1} \frac{\partial B^w}{\partial u}(\zeta_0) B^w(\zeta_0)^{-1} (B^w(\zeta_0)^{-\frac{1}{2}} + \xi I_n)^{-1} d\xi.
\]
Since \( P \) is a unitary matrix, we have 
\[
\|dA_{\zeta_0}[u] \cdot \Lambda\|_{B,\zeta_0} = |B^w(\zeta_0)^{\frac{1}{2}} \cdot D(\zeta_0) \cdot \overline{P}^T \cdot \Lambda| \leq \|B^w(\zeta_0)^{\frac{1}{2}} D(\zeta_0)\|_\infty \cdot |\Lambda|.
\]
Corollary 2.10 and Proposition 2.11 imply that 
\[
\mu_{i, j} = \frac{\partial B^w_{i, j}}{\partial u}(\zeta_0, \zeta_0) \text{ satisfies}
\]
\[
|\mu_{i, j}| \leq \frac{\lambda_j(\zeta_0)^{\frac{1}{2}} \lambda_j(\zeta_0)^{\frac{1}{2}}}{\tau(\zeta_0, u, d(\zeta_0))}.
\]
For \( \xi \in b\Omega_{\zeta_0} \), we have 
\[
B^w(\zeta_0)^{\frac{1}{2}} (B^w(\zeta_0)^{-\frac{1}{2}} - \xi I_n)^{-1} B^w(\zeta_0)^{-1} \frac{\partial B^w}{\partial u}(\zeta_0) B^w(\zeta_0)^{-1} (B^w(\zeta_0)^{-\frac{1}{2}} + \xi I_n)^{-1}
= \left(\lambda_k(\zeta)^{-\frac{1}{2}}(\lambda_k(\zeta)^{-\frac{1}{2}} - \xi)^{-1} \mu_{i, j}(\zeta_0)^{-1}(\lambda_i(\zeta)^{-\frac{1}{2}} + \xi)^{-1}\right)_{k, l}.
\]
In order to estimate \( \|B^w(\zeta_0)^{\frac{1}{2}} D(\zeta_0)\|_\infty \), we integrate (11) over \( b\Omega_{\zeta_0} \), but before, we choose a good open set \( \Omega_{\zeta_0} \). From Proposition 2.11, we have 
\[
\mu_{i, j} \geq 0 \text{ sufficiently small such that } \Omega_{\zeta_0} = \bigcup_{j=1}^n \Delta(\lambda_j^{-\frac{1}{2}}(\xi_0), c\lambda_j(\lambda_j^{-\frac{1}{2}}(\xi_0)) \text{ is included in} \\
\{ \xi \in \mathbb{C}, \lambda_0 \xi \geq \mu d(\xi) \}. \text{ Thus sp}(\Phi^{-1}(B(\zeta_0))) \text{ is included in} \Omega_{\zeta_0} \text{ and sp}(\Phi^{-1}(B(\zeta_0))) \cap \Omega_{\zeta_0} = \emptyset.
\]
For all \( k \) and all \( \xi \in b\Omega_{\zeta_0} \) holds: 
\[
|\lambda_k(\zeta_0)^{-\frac{1}{2}} - \xi|^{-1} \leq d(\zeta_0)^{-1}.
\]
Since \( \xi \) belongs to \( b\Omega_{c_0} \), there exists \( j \) and \( \phi \) such that \( \xi = \lambda_j(\zeta_0)^{-\frac{1}{2}} + cd(\zeta_0)e^{i\phi} \), so for all \( l \)

\[
|\lambda_l(\zeta_0)^{-\frac{1}{2}} + \xi| \geq |\lambda_l(\zeta_0)^{-\frac{1}{2}} + \lambda_j(\zeta_0)^{-\frac{1}{2}} - cd(\zeta_0)|
\geq \lambda_l(\zeta_0)^{-\frac{1}{2}}.
\]

so

\[
|\lambda_l(\zeta_0)^{-\frac{1}{2}} + \xi|^{-1} \leq \lambda_l(\zeta_0)^{\frac{1}{2}}.
\]  \hspace{1cm} (13)

Inequalities (10), (12) and (13) yield for all \( k \) and \( l \):

\[
\begin{align*}
\frac{1}{2} (\lambda_k(\zeta_0)^{-\frac{1}{2}} - \xi)^{-1}\mu_{kl}\lambda_l(\zeta_0)^{-\frac{1}{2}} + \xi)^{-1} & \leq \lambda_k(\zeta_0)^{-\frac{1}{2}}d(\zeta_0)^{-1}(\lambda_k(\zeta_0)^{\frac{1}{2}}\lambda_l(\zeta_0)^{\frac{1}{2}}
\leq \frac{1}{d(\zeta_0)\tau(\zeta, u, d(\zeta))}.
\end{align*}
\]

We now integrate the previous inequality on \( b\Omega_{c_0} \) and get, since the the length of \( b\Omega_{c_0} \) is less than \( 2\pi nc d(\zeta_0) \):

\[
\|B^{w}(\zeta_0)^{\frac{1}{2}}D(\zeta_0)\|_{\infty} \leq \frac{1}{\tau(\zeta, u, d(\zeta))}.
\]

Thus we have proved the following lemma:

**Lemma 2.13** For all \( \zeta \in D \) close enough to \( bD \), all vector \( u \in \mathbb{C}^n \), all \( \Lambda \in \Delta_n(1) \), we have uniformly with respect to \( \zeta \), \( u \) and \( \Lambda \)

\[
\|dA_{\xi}[u] \cdot \Lambda\|_{B, \zeta} \lesssim \frac{1}{\tau(\zeta, u, d(\zeta))}.
\]

We deduce from Lemma 2.13 the following corollary which will be very useful.

**Corollary 2.14** There exists \( c > 0 \) sufficiently small such that for all \( \xi \in D \) close to \( bD \), all \( \zeta \in cP_{d(\xi)}(\xi) \), all \( \Lambda \in \Delta_n(1) \), all vector \( v \in \mathbb{C}^n \), we have uniformly

\[
k(\zeta, A(\xi) \cdot \Lambda) \lesssim d(\xi),
k(\zeta, dA_{\xi}[v] \cdot \Lambda) \lesssim k(\xi, v).
\]

**Proof** From Corollary 2.7 we have \( k(\zeta, A(\xi) \cdot \Lambda) \approx k(\zeta, A(\xi) \cdot \Lambda) \) and since \( \|A(\xi) \cdot \Lambda\|_{B, \xi} = |\Lambda| \), we get

\[
k(\zeta, A(\xi) \cdot \Lambda) \approx d(\xi)\|A(\xi) \cdot \Lambda\|_{B, \xi}
\lesssim d(\xi).
\]

In the same way, we have \( k(\zeta, dA_{\xi}[v] \cdot \Lambda) \lesssim d(\xi)\|dA_{\xi}[v] \cdot \Lambda\|_{B, \xi} \) and Lemma 2.13 yields

\[
k(\zeta, dA_{\xi}[v] \cdot \Lambda) \lesssim \frac{d(\xi)}{\tau(\xi, v, d(\xi))} = k(\xi, v).
\]

\[\Box\]
2.3 Case 1 \( - t \leq \frac{\gamma}{2} d(z) \)

In this subsection, we want to estimate

\[
(I) := \left( \int_{z \in \mathcal{P}_{d(z)} \cap D \atop \rho \in (1 - \frac{123}{2} d(z), 1]} |\theta(h_A(z, t))| \left[ \frac{\partial h_A(z, t)}{\partial t} (z, t), d_z h_A(z, t)[u(z)] \right] \right) \cdot dtd\lambda(z).
\]

We first prove the following lemma for \( 1 - t \leq \gamma d(z) \) and not only for \( 1 - t \leq \frac{\gamma}{2} d(z) \) because we will also use it in Sect. 2.5.

**Lemma 2.15** There exists \( C > 0 \) such that for all \( z \in D \) close to \( bD \), all \( t \in [t_0, 1 - \gamma d(z)] \), all \( \Lambda \in \Delta_n(1) \), the point \( p = tz + \frac{t(1-t)}{d(z)} A(z) \cdot \Lambda \) belongs to \( C \frac{1-t}{d(z)} \mathcal{P}_d(z) \).

**Proof** We write \( p = z - \frac{1-t}{d(z)} d(z) \cdot z + \frac{t(1-t)}{d(z)} A(z) \cdot \Lambda \).

In the one hand, \( z - d(z)z \) belongs to \( K \mathcal{P}_d(z) \) for some uniform \( K \) because \( |z - d(z)z - z| \lesssim d(z) \).

In the other hand, since \( \| A(z) \cdot \Lambda \|_{B, z} \lesssim 1 \), there exists a uniform \( K' \) such that \( z + t A(z) \cdot \Lambda \) belongs to \( K' \mathcal{P}_d(z) \). Therefore, putting \( C = K + K' \), \( z - d(z)z + t A(z) \cdot \Lambda \) belongs to \( C \mathcal{P}_d(z) \) and so \( p \) belongs to \( C \frac{1-t}{d(z)} \mathcal{P}_d(z) \).

This lemma gives us the following inequalities:

**Corollary 2.16** If \( \gamma > 0 \) is small enough, for all \( z \in D \) close to \( bD \), all \( t \in [1 - \frac{\gamma}{2} d(z), 1] \) and all \( \Lambda \in \Delta_n(1) \), the following estimates hold:

\[
\begin{align*}
&d(h_A(z, t)) \approx d(tz) \approx d(z) \\
&\tau(z, v, d(z)) \approx \tau(tz, v, d(tz)) \approx \tau(h_A(z, t), v, d(h_A(z, t))), \\
&k(h_A(z, t), v) \approx k(tz, v) \approx k(z, v).
\end{align*}
\]

**Proof** Lemma 2.15 implies that \( h_A(z, t) \) belongs to \( c \mathcal{P}_d(z) \), \( c \) arbitrary small provided \( \gamma \) is small enough. Proposition 2.5 then implies that \( d(h_A(z, t)) \approx d(z) \) and Corollary 2.7 implies that \( k(h_A(z, t), v) \approx k(z, v) \).

Since \( |z - tz| \lesssim \gamma d(z) \), if \( \gamma \) is small enough, \( tz \) belongs to \( c \mathcal{P}_d(z) \) and, in the same way, we have \( d(z) \approx d(tz) \) and \( k(tz, v) \approx k(z, v) \).

**Lemma 2.17** Let \( c \) be a positive number. If \( \gamma > 0 \) is small enough, for all \( z \in D \) close to \( bD \), all \( t \in [1 - \frac{\gamma}{2} d(z), 1] \) and all \( \Lambda \in \Delta_n(1) \), the point \( h_A(z, t) \) belongs to \( c \mathcal{P}_d(z) \) and uniformly

\[
k(h_A(z, t), \frac{\partial h_A(z, t)}{\partial t}(z, t)) \lesssim 1, \\
k(h_A(z, t), d_z h_A(z, t)[u]) \lesssim k(z, u).
\]

**Proof** From Lemma 2.15, since \( 1 - t \leq \frac{\gamma}{2} d(z) \), if \( \gamma \) is small enough then \( h_A(z, t) \) belongs to \( c \mathcal{P}_d(z) \), \( c \) arbitrary small, provided that \( \gamma \) is small enough.

Since \( 1 - t \leq \frac{\gamma}{2} d(z) \), \( \frac{\partial h_A(z, t)}{\partial t}(z, t) = z + \frac{1-2t}{d(z)} A(z) \cdot \Lambda \). Propositions 1.6 and 2.1 give

\[
k(h_A(z, t), z) \lesssim |z| \lesssim 1
\]
Corollary 2.16 implies that \( k \left( h_A(z, t), \frac{1-2t}{d(z)} A(z) \cdot \Lambda \right) \lesssim \frac{1-2t}{d(z)} k(z, A(z) \cdot \Lambda) \) and Corollary 2.14 then gives
\[
k \left( h_A(z, t), \frac{1-2t}{d(z)} A(z) \cdot \Lambda \right) \lesssim \frac{|1-2t|}{d(z)} d(z) \leq 1.
\]

With (14), this proves the first inequality.

For the second one, we have \( d_z h_A(z, t)[u] = tu + t \frac{(1-t)}{d(z)^2} \partial_A A(z) \cdot \Lambda + \frac{t(1-t)}{d(z)} A z[u] \cdot \Lambda \). Corollary 2.16 gives
\[
k(h_A(z, t), tu) \lesssim k(z, u).
\]

Proposition 2.8 gives \( \left| \frac{t(1-t)}{d(z)^2} \partial_A A(z) \cdot \Lambda \right| \lesssim \frac{1}{t(z,u,d(z))} \); Corollary 2.14 yields \( k(h_A(z, t), A(z) \cdot \Lambda) \lesssim d(z) \) and so
\[
k \left( h_A(z, t), \frac{t(1-t)}{d(z)^2} \partial_A A(z) \cdot \Lambda \right) \lesssim k(z, u).
\]

Finally, again Corollary 2.14 gives \( k \left( h_A(z, t), \frac{t(1-t)}{d(z)} A z[u] \cdot \Lambda \right) \lesssim k(z, u) \). With Inequalities (15) and (16), it then comes \( k(h_A(z, t), d_z h_A(z, t)[u]) \lesssim k(z, u) \).

We now estimate (I). From Lemma 2.17, it comes
\[
(I) \lesssim \int \left( \sum_{z \in P(z) \cap \Delta} \left( \frac{1}{t(z,u,d(z))} \right) k(h_A(z, t), d_z h_A(z, t)[u(z)]) \right) dtd\Lambda d\lambda(z).
\]

Then Proposition 2.12 gives \( (I) \lesssim \sum_{j,k=1}^n (I)_{j,k} \) where
\[
(I)_{j,k} := \int \left( \sum_{z \in P(z) \cap \Delta} \left( \frac{1}{t(z,u,d(z))} \right) k(h_A(z, t), d_z h_A(z, t)[u(z)]) \right) dtd\Lambda d\lambda(z).
\]

For fixed \( z \) and \( t \), we make the substitution \( \zeta = h_A(z, t), \Lambda \) running over \( \Delta_n(\rho) \). From Lemma 2.15, when \( |\Lambda| \leq \rho \), the point \( h_A(z, t) \) belongs to \( C \frac{1-t}{d(z)} P_d(z) \) for some big \( C > 0 \). Moreover, \( \det_{d} d_A h_A(z, t) \approx \left( \frac{1-t}{d(z)} \right)^{2n} (\det_{d} A(z))^2 \) and Proposition 2.11 then yields \( \det_{d} d_A h_A(z, t) \approx \left( \frac{1-t}{d(z)} \right)^{2n} \text{Vol}(P_d(z)) \). Therefore
\[
(I)_{j,k} \lesssim \int \left( \sum_{z \in P(z) \cap \Delta} \left( \frac{1}{t(z,u,d(z))} \right) \frac{1}{k(h_A(z, t), d_z h_A(z, t)[u(z)])} \right) dtd\lambda d\lambda(z).
\]

Now we want to change the order of integration. When \( z \) belongs to \( P(z_0) \), \( t \) to \([1 - \frac{C}{2}d(z), 1] \) and \( \zeta \) to \( C \frac{1-t}{d(z)} P_d(z) \), we have \( d(z) \approx d(\zeta) \) provided \( \gamma \) is small enough. Thus there exists \( K \), not depending on \( \gamma, z, \zeta \) or \( t \) such that \( 1 - K \gamma d(\zeta) \leq t \leq 1 \). Therefore if \( \gamma \) is small enough, \( t \) belongs to \([1 - \frac{C}{2}d(\zeta), 1] \).

Because \( \delta \) is a pseudodistance, we also have \( \delta(\zeta, z) \lesssim \delta(z, z_0) \lesssim \varepsilon \), thus, there exists \( K' > 0 \), big enough, such that \( \zeta \) belongs to \( K' P(z_0) \).
Since \( \xi \) belongs to \( C^{1-t}_{d,\xi}P_{d,\xi}(z) \), we can write \( \xi = z + C^{1-t}_{d,\xi}\mu v \) with \( \mu \in \mathbb{C} \), \( v \in \mathbb{C}^n \), \( |v| = 1 \), such that \( |\mu| < \tau(z,v,d(z)) \). Provided \( \gamma \) is small enough, we have \( d(z) \approx d(\xi) \) and \( \tau(z,v,d(z)) \approx \tau(\xi,v,d(\xi)) \). Therefore \( z = \xi - C^{1-t}_{d,\xi}\mu v \) with \( |\mu| \lesssim \tau(\xi,v,d(\xi)) \) and there exists \( K'' > 0 \) big enough, such that \( z \) belongs to \( K''^{1-t}_{d,\xi}P_{d,\xi}(\xi) \).

Therefore, the set \{ \((z,t,\xi) \), \( z \in P_{\xi}(z_0), t \in [1 - \frac{\tau}{2}d(z), 1], \xi \in C^{1-t}_{d,\xi}P_{d,\xi}(z) \} \) is included in \{ \((z,t,\xi) \), \( \xi \in K''^{1-t}_{d,\xi}P_{d,\xi}(z_0), t \in [1 - \frac{1}{2}d(z), 1], z \in K''^{1-t}_{d,\xi}P_{d,\xi}(\xi) \} \). Moreover, \( \text{Vol}(P_{d,\xi}(z)) \approx \text{Vol}(P_{d,\xi}(\xi)) \) which gives

\[
(I)_{j,k} \lesssim \int_{\xi \in K''^{1-t}_{d,\xi}P_{d,\xi}(\xi) \cap \partial D \left| \frac{d(\xi)}{1-t} \right|^2 \frac{\theta(\xi)|e_j(\xi),e_k(\xi)|}{k(\xi,e_j(\xi)) \cdot k(\xi,e_k(\xi))} d\lambda(\xi)d\tau(\xi).
\]

Integrating for \( z \) in \( K''^{1-t}_{d,\xi}P_{d,\xi}(\xi) \) we get

\[
(I)_{j,k} \lesssim \int_{\xi \in K''^{1-t}_{d,\xi}P_{d,\xi}(\xi) \cap \partial D} \theta(\xi)|e_j(\xi),e_k(\xi)| d\lambda(\xi)d\tau(\xi).
\]

Now we integrate for \( t \in [1 - \frac{1}{2}d(\xi), 1] \) and we obtain

\[
(I)_{j,k} \lesssim \int_{\xi \in K''^{1-t}_{d,\xi}P_{d,\xi}(\xi) \cap \partial D} \frac{d(\xi)|\theta(\xi)|e_j(\xi),e_k(\xi)|}{k(\xi,e_j(\xi)) \cdot k(\xi,e_k(\xi))} d\lambda(\xi)
\]

and since \( d - \theta(\xi) \) is a \((1,1)\)-Carleson current, we get

\[
(I)_{j,k} \lesssim \sigma(P_{\xi}(z_0) \cap bD)||d\cdot\theta||_{W_{1,1}^1}.
\]

This finally shows that \( I \lesssim ||d\cdot\theta||_{W_{1,1}^1} \sigma(P_{\xi}(z_0) \cap bD) \).

### 2.4 Case \( \gamma d(z) \leq 1 - t \)

This subsection is devoted to the estimate of

\[
(II) := \int_{z \in P_{\xi}(z_0) \cap \partial D} |\theta(h_{\Lambda}(z,t))| \left| \frac{\partial h_{\Lambda}(z,t)}{\partial t}(z,t), d_z h_{\Lambda}(z,t)[u(z)] \right| k(z,u(z)) \text{Vol}(\Delta_n(\rho)) d\lambda(\xi).
\]

We first look for estimates of \( k(h_{\Lambda}(z,t), d_z h_{\Lambda}(z,t)[u]) \) and \( k(h_{\Lambda}(z,t), \frac{\partial h_{\Lambda}}{\partial t}(z,t)) \). We begin with following lemma that we prove for \( z \) and \( t \) such that \( \frac{\gamma}{4}d(z) \leq 1 - t \).

**Lemma 2.18** There exists \( C > 0 \) such that for all \( z \in D \) close to \( bD \), all \( t \in [\tau_0, 1 - \frac{\gamma}{2}d(z)] \), all \( \Lambda \in \Delta_n(\rho) \), the point \( q = tz + tA(tz) \cdot \Lambda \) belongs to \( Ct \rho P_{d(tz)}(tz) \).

**Proof** If we write \( A(tz) \cdot \Lambda \) as \( \mu v \) with \( \mu \in \mathbb{C} \) and \( v \in \mathbb{C}^n \), \( |v| = 1 \). We have

\[
\frac{|\mu|}{\tau(tz,v,d(tz))} \approx ||A(tz) \cdot \Lambda||_{B,tz} \lesssim \rho.
\]

Thus there exists a uniform \( K > 0 \) such that \( |\mu| \leq K \rho \tau(tz,v,d(tz)) \) and so, \( q \) belongs to \( t\rho CP_{d(tz)}(tz) \) for some \( C \) which does not depend on \( z \), \( t \) or \( \rho \).
Corollary 2.19 If $\rho > 0$ is small enough, for all $z \in D$ close to $bD$, all $t \in [t_0, 1 - \gamma d(z)]$ and all $\Lambda \in \Delta_n(\rho)$:

$$d(h_{\Lambda}(z, t)) \approx d(tz) \approx 1 - t$$

$$\tau(z, v, 1 - t) \approx \tau(tz, v, d(tz)) \approx \tau(h_{\Lambda}(z, t), v, d(h_{\Lambda}(z, t))),$$

$$k(h_{\Lambda}(z, t), v) \approx k(tz, v) = \frac{1 - t}{\tau(z, v, 1 - t)}.$$

Proof Firstly, we have $d(tz) = 1 - t + td(z) \approx 1 - t$. Secondly, since from Lemma 2.18, $h_{\Lambda}(z, t)$ belongs to $C t \rho P_{d(tz)}(tz)$, choosing $\rho$ sufficiently small we get from Proposition 2.5 $d(h_{\Lambda}(z, t)) \approx d(tz)$. This prove the first chain of almost equalities.

Since $|z - tz| \lesssim 1 - t$, $z$ belongs to $P_{K(1 - t)}(tz)$ and since $1 - t \approx d(tz)$, from Propositions 2.6 and 2.2, we have $\tau(z, v, 1 - t) \approx \tau(tz, v, d(tz))$ and $\frac{1 - t}{\tau(z, v, 1 - t)} \approx k(tz, v)$. Now since $h_{\Lambda}(z, t)$ belongs to $C t \rho P_{d(tz)}(tz)$, Proposition 2.6 gives $\tau(tz, v, d(tz)) \approx \tau(h_{\Lambda}(z, t), v, d(tz))$, provided $\rho$ is small enough. Since $d(h_{\Lambda}(z, t)) \approx d(tz)$, it then comes from Proposition 2.2 $\tau(h_{\Lambda}(z, t), v, d(tz)) \approx \tau(h_{\Lambda}(z, t), v, d(h_{\Lambda}(z, t)))$ and thus $k(h_{\Lambda}(z, t), v) \approx k(tz, v)$. \hfill $\square$

Lemma 2.20 If $\rho > 0$ is small enough, for all $z \in D$ close to $bD$, all $t \in [t_0, 1 - \gamma d(z)]$ and all $\Lambda \in \Delta_n(\rho)$, the following inequalities hold:

$$k(h_{\Lambda}(z, t), d_{\Lambda}h_{\Lambda}(z, t)[u]) \lesssim k(z, u) \left(\frac{1 - t}{d(z)}\right)^{1 - \frac{1}{m}}.$$

$$k(h_{\Lambda}(z, t), \frac{\partial h_{\Lambda}}{\partial t}(z, t)) \lesssim 1.$$

Proof Since $1 - t \geq \gamma d(z)$, $h_{\Lambda}(z, t) = tz + tA(tz) \cdot \Lambda$ and thus $d_{\Lambda}h_{\Lambda}(z, t)[u] = tu + tA_{\Lambda}t[z][u] \cdot \Lambda$. Lemma 2.18 implies that $h_{\Lambda}(z, t)$ belongs to $cP_{d(tz)}(tz)$, $c$ as small as needed if $\rho$ is small enough. We then get from Corollary 2.19

$$k(h_{\Lambda}(z, t), tu) \approx \frac{1 - t}{\tau(z, u, 1 - t)}. \quad (17)$$

Using successively Corollary 2.14 and 2.19 we get $k(h_{\Lambda}(z, t), tdA_{\Lambda}t[z][u] \cdot \Lambda) \lesssim \frac{1 - t}{\tau(z, u, 1 - t)}$.

With (17), this yields

$$k(h_{\Lambda}(z, t), d_{\Lambda}h_{\Lambda}(z, t)[u]) \lesssim \frac{1 - t}{\tau(z, u, 1 - t)}.$$

Proposition 2.2 then implies

$$k(h_{\Lambda}(z, t), d_{\Lambda}h_{\Lambda}(z, t)[u]) \lesssim \left(\frac{d(z)}{1 - t}\right)^{1 - \frac{1}{m}} \frac{1 - t}{\tau(z, u, d(z))},$$

which proves the first inequality.

We now prove the second inequality. We have $\frac{\partial h_{\Lambda}}{\partial t}(z, t) = z + A(tz) \cdot \Lambda + tdA_{\Lambda}t[z] \cdot \Lambda$. Corollary 2.19 gives

$$k(h_{\Lambda}(z, t), z) \lesssim k(tz, z) \quad (18)$$

Next from Corollary 2.14 we get

$$k(h_{\Lambda}(z, t), A(tz) \cdot \Lambda) \lesssim d(tz) \quad (19)$$
and again with Corollary 2.14 we have
\[ k(h_\Lambda(z, t), tdA_{xz}[z] \cdot \Lambda) \lesssim k(tz, z). \]  
(20)

Putting together the inequalities (18), (19) and (20) we obtain
\[ k \left( h_\Lambda(z, t), \frac{\partial h_\Lambda}{\partial t}(z, t) \right) \lesssim k(tz, z) \]
and Propositions 1.6 and 2.1 end the proof of the lemma. \( \square \)

We now come to the heart of the matter of this subsection: We estimate (II). Lemma 2.20 immediately gives
\[
(II) \lesssim \int_{z \in \mathcal{P}_z(\zeta)_\Lambda \in \Delta_\rho(t \in [\eta, 1 - \gamma d(z)])} \left( 1 - \frac{1}{d(z)} \right)^{1 - \frac{1}{m}} \frac{|\theta(h_\Lambda(z, t))|}{k(h_\Lambda(z, t), d_z h_\Lambda(z, t)[u(z)] \cdot k(h_\Lambda(z, t), \frac{\partial h_\Lambda}{\partial t}(z, t))} dt d\Lambda d\lambda(z).
\]

Then Proposition 2.12 gives (II) \( \lesssim \sum_{j,k=1}^n (II)_{j,k} \) where
\[
(II)_{j,k} := \int_{z \in \mathcal{P}_z(\zeta)_\Lambda \in \Delta_\rho(t \in [\eta, 1 - \gamma d(z)])} \left( 1 - \frac{1}{d(z)} \right)^{1 - \frac{1}{m}} \frac{1}{\text{Vol}(\mathcal{P}_d(tz))} \frac{|\theta(\zeta)|}{k(\zeta, e_j(\xi)) k(\zeta, e_k(\xi))} d\lambda(\zeta) dt d\lambda(z).
\]

We make the substitution \( \zeta = h_\Lambda(z, t) \) for \( \Lambda \) running over \( \Delta_\rho(\rho) \). Since, Proposition 2.11, \( \det A(tz) \approx \text{Vol}(\mathcal{P}_d(tz)) \), and, since Lemma 2.18, \( |h_\Lambda(z, t)|, |\Lambda| < \rho \subset C \rho \mathcal{P}_d(tz) \), we have
\[
(II)_{j,k} \lesssim \int_{z \in \mathcal{P}_z(\zeta)_\Lambda \in \Delta_\rho(t \in [\eta, 1 - \gamma d(z)])} (1 - t)^{-\frac{1}{m}} d(z)^{-\frac{1}{m} - 1} d(\xi) \frac{d(\xi) |\theta(\xi)| |e_j(\xi), e_k(\xi)|}{k(\zeta, e_j(\xi)) k(\zeta, e_k(\xi))} d\lambda(\zeta) dt d\lambda(z).
\]

We will estimate the integral in \( \xi \) using the fact that \( d \theta \) is a \( (1, 1) \)-Carleson current. For fixed \( z \) and \( t \), let \( \xi_0 \in bD \) be a point such that \( tz = \xi_0 + \alpha \eta \), \( \alpha \in \mathbb{R} \). Then \( |\alpha| \approx d(tz) \) and from Proposition 2.4, there exists \( K > 0 \), not depending on \( z \) or \( t \) such that \( \mathcal{P}_d(tz) \cap D \) is included in \( \mathcal{P}_{Kd(tz)}(\xi_0) \cap D \). Moreover, we have \( \text{Vol}(%mathcal{P}_d(tz)) \approx \text{Vol}(\mathcal{P}_{Kd(tz)}(\xi_0)) \). Thus
\[
\frac{1}{\text{Vol}(\mathcal{P}_d(tz))} \int_{\zeta \in \mathcal{P}_d(tz)} \frac{d(\xi) |\theta(\xi)| |e_j(\xi), e_k(\xi)|}{k(\zeta, e_j(\xi)) k(\zeta, e_k(\xi))} d\lambda(\zeta) \lesssim \frac{1}{\text{Vol}(\mathcal{P}_d(tz))} \int_{\zeta \in \mathcal{P}_d(tz)} \frac{d(\xi) |\theta(\xi)| |e_j(\xi), e_k(\xi)|}{k(\xi, e_j(\xi)) k(\xi, e_k(\xi))} d\lambda(\zeta) \lesssim \|\theta\|_{W^{1,1}} d(tz)^{-1}.
\]
So with Corollary 2.19 we get

$$(II)_{j,k,e} \lesssim \|\theta\|_{W^{1,1}} \int_{z \in \mathcal{P}_\epsilon(z_0) \cap bD} (1 - t)^{-\frac{1}{\theta} - 1} d(z)^{-\frac{1}{\theta} - 1} dt d\lambda(z)$$

$$\lesssim \epsilon^{-\frac{1}{\theta}} \|\theta\|_{W^{1,1}} \int_{z \in \mathcal{P}_\epsilon(z_0) \cap bD} d(z)^{-\frac{1}{\theta} - 1} d\lambda(z)$$

$$\lesssim \|\theta\|_{W^{1,1}} \sigma(\mathcal{P}_\epsilon(z_0) \cap bD).$$

Now we deal with $(II)_{j,k,\delta}$. We write $z \in \mathcal{P}_\epsilon(z_0)$ as $z = sz'$ where $s$ belongs to $[1 - \epsilon, 1]$ and $z'$ to $\mathcal{P}_\epsilon(z_0) \cap bD$. We then have $d(sz') = 1 - s$ and

$$(II)_{j,k,\delta} \lesssim \int_{z' \in \mathcal{P}_\epsilon(z_0) \cap bD} \int_{t \in [1 - \epsilon, 1]} d(z') \|\theta\|_{W^{1,1}} \frac{1}{1 - s} |\theta(\epsilon(\epsilon^z(\epsilon(\epsilon z'))| d\lambda(z') dtds d\sigma(z') \frac{1}{Vol(\mathcal{P}_d(sz') \cap tsz')} (k, e_j(\epsilon z')) \cdot (k, e_k(\epsilon z')).$$

We make the substitution $r = st$ for $t \in [1 - \epsilon, 1]$ and, since $s$ is far from 0, we get

$$(II)_{j,k,\delta} \lesssim \int_{z' \in \mathcal{P}_\epsilon(z_0) \cap bD} \int_{r \in [1 - r, 1]} d(z') \|\theta\|_{W^{1,1}} \frac{1}{1 - s} |\theta(\epsilon(\epsilon^z(\epsilon(\epsilon z'))| d\lambda(z') dtds d\sigma(z') \frac{1}{Vol(\mathcal{P}_d(sz') \cap tsz')} (k, e_j(\epsilon z')) \cdot (k, e_k(\epsilon z')).$$

Changing the order of integration between $r$ and $s$ then yields

$$(II)_{j,k,\delta} \lesssim \int_{z' \in \mathcal{P}_\epsilon(z_0) \cap bD} \int_{r \in [1 - r, 1]} d(z') \|\theta\|_{W^{1,1}} \frac{1}{1 - s} |\theta(\epsilon(\epsilon^z(\epsilon(\epsilon z'))| d\lambda(z') dtds d\sigma(z') \frac{1}{Vol(\mathcal{P}_d(sz') \cap tsz')} (k, e_j(\epsilon z')) \cdot (k, e_k(\epsilon z')).$$

Now, integrating separately for $s \in [r, \frac{r + 1}{2}]$ and for $s \in [\frac{r + 1}{2}, 1]$, we easily get

$$\int_{s \in [r, 1]} \left(\frac{s - r}{1 - s}\right)^{\frac{1}{\theta} - 1} ds \lesssim 1 - r.$$
Let $c$ be a positive number. If Lemma 2.21 holds, for all 

$$
(II)_{j,k,d} \leq \int_{\zeta \in \mathcal{P}_K(z_0) \cap D} \frac{d(\zeta) |\theta(\zeta)||e_j(\zeta), e_k(\zeta)|}{\text{Vol}(\mathcal{P}_K(\zeta))} d\lambda(\zeta) d\lambda(\zeta)
$$

This finally shows that $(II) \leq \|d \cdot \theta\|_{W^{1,1}} \sigma(\mathcal{P}_\rho(z_0) \cap bD)$.

2.5 Case $\frac{\gamma}{2} d(z) \leq 1 - t \leq \gamma d(z)$

The last piece of $H \theta$ that is left to be estimated is

$$
(III) := \int_{\frac{1}{\gamma} d(z) \leq t < 1} \frac{|\theta(h_\Lambda(z, t))|}{k(z, u(z))} \left[ \frac{\partial \Lambda(\rho)}{\partial t}(z, t), d\cdot h_\Lambda(z, t)[u(z)] \right] d\Lambda dz dt d\lambda(z).
$$

As in the previous subsections, we first want upper bounds for $k(h_\Lambda(z, t), d\cdot h_\Lambda(z, t)[u])$ and $k(h_\Lambda(z, t), \frac{\partial h_\Lambda}{\partial t}(z, t))$.

**Lemma 2.21** Let $c$ be a positive number. If $\gamma > 0$ and $\rho > 0$ are small enough, for all $z \in D$ close to $bD$, all $t \in [1 - \gamma d(z), 1 - \frac{\gamma}{2} d(z)]$ and all $\Lambda \in \Delta_n(\rho)$, the point $h_\Lambda(z, t)$ belongs to $c\mathcal{P}_d(z)$ and to $c\mathcal{P}_d(z)$ and

$$
d(h_\Lambda(z, t)) \asymp d(z) \quad \sigma(z, v, d(z)) \asymp \tau(z, v, d(z)) \asymp \tau(h_\Lambda(z, t), v, d(h_\Lambda(z, t))),
$$

$$
k(h_\Lambda(z, t), v) \asymp k(tz, v) \asymp k(z, v).
$$

**Proof** Since $|z - tz| \leq 1 - t \leq \gamma d(z)$, $tz$ belongs to $c\mathcal{P}_d(z)$ for all $c > 0$, provided $\gamma$ is sufficiently small and so $d(z)$ uniformly in $z$ and $t$.

Lemma 2.15 implies that $tz + \frac{t(1-t)}{d(z)} A(z)$ belongs to $ct \frac{1-t}{d(z)} \mathcal{P}_d(z)$. Thus, for any arbitrary $c > 0$, if $\gamma$ is small enough, $tz + \frac{t(1-t)}{d(z)} A(z)$ belongs to $c\mathcal{P}_d(z)$. Since $tz$ also belongs to $c\mathcal{P}_d(z)$ for all $c > 0$ provided $\gamma$ is small enough, $tz + \frac{t(1-t)}{d(z)} A(z)$ also belongs to $c\mathcal{P}_d(tz)$ for all $c > 0$, if $\gamma$ is small enough.

Lemma 2.18 implies that $tz + t \Lambda(z)$ belongs to $ct \rho \mathcal{P}_d(tz)$. Thus, for any arbitrary $c > 0$, if $\rho$ is small enough, $tz + t A(tz)$ belongs to $c\mathcal{P}_d(tz)$. Again, since $tz$ belongs to $c\mathcal{P}_d(z)$ for all $c > 0$ if $\gamma$ is small enough, $tz + t A(tz)$ also belongs to $c\mathcal{P}_d(tz)$ for all $c > 0$, provided $\gamma$ and $\rho$ are small enough.

By convexity $h_\Lambda(z, t) = tz + \varphi \left( \frac{1-t}{\gamma d(z)} \right) \frac{t(1-t)}{d(z)} A(z) + (1 - \varphi \left( \frac{1-t}{\gamma d(z)} \right)) t A(tz)$ belongs to $c\mathcal{P}_d(z)$ and to $c\mathcal{P}_d(tz)$.

The rest of the proof is exactly as in Corollary 2.16, so we omit it. 

\[\text{Springer}\]
Lemma 2.22 If $\rho > 0$ and $\gamma > 0$ are small enough, for all $z \in D$ close to $bD$, all $t \in [1 - \gamma d(z), 1 - \frac{\rho}{\gamma} d(z)]$ and all $\Lambda \in \Delta_{n}(\rho)$, the following inequalities hold:

$$k \left( h_{\Lambda}(z, t), \frac{\partial h_{\Lambda}}{\partial t}(z, t) \right) \lesssim 1,$$

$$k \left( h_{\Lambda}(z, t), d_{z} h_{\Lambda}(z, t)[u] \right) \lesssim k(z, u).$$

Proof We recall that $h_{\Lambda}(z, t) = tz + t\varphi \left( \frac{1 - t}{\gamma d(z)} \right) \frac{1 - t}{\gamma d(z)} A(z) \cdot \Lambda + t \left( 1 - \varphi \left( \frac{1 - t}{\gamma d(z)} \right) \right) A(tz) \cdot \Lambda$ so

$$\frac{\partial h_{\Lambda}}{\partial t}(z, t) = z + \left( \frac{1 - 2t}{d(z)} \varphi \left( \frac{1 - t}{\gamma d(z)} \right) - \frac{t(1 - t)}{\gamma d(z)} \varphi' \left( \frac{1 - t}{\gamma d(z)} \right) \right) A(z) \cdot \Lambda$$

$$+ \left( 1 - \varphi \left( \frac{1 - t}{\gamma d(z)} \right) \right) \left( \frac{t}{\gamma d(z)} \varphi' \left( \frac{1 - t}{\gamma d(z)} \right) \right) A(tz) \cdot \Lambda$$

$$+ t \left( 1 - \varphi \left( \frac{1 - t}{\gamma d(z)} \right) \right) dA_{tz}[z] \cdot \Lambda.$$ 

On the one hand

$$k(h_{\Lambda}(z, t), z) \lesssim |z| \lesssim 1. \quad (21)$$

On the other hand

$$k \left( h_{\Lambda}(z, t), \varphi \left( \frac{1 - t}{\gamma d(z)} \right) - \frac{t(1 - t)}{\gamma d(z)} \varphi' \left( \frac{1 - t}{\gamma d(z)} \right) \right) A(z) \cdot \Lambda$$

$$\lesssim \frac{1}{d(z)} k(h_{\Lambda}(z, t), A(z) \cdot \Lambda),$$

and Corollary 2.14 and Lemma 2.21 then give

$$k \left( h_{\Lambda}(z, t), \varphi \left( \frac{1 - t}{\gamma d(z)} \right) - \frac{t(1 - t)}{\gamma d(z)} \varphi' \left( \frac{1 - t}{\gamma d(z)} \right) \right) A(z) \cdot \Lambda \lesssim 1. \quad (22)$$

Similarly, Corollary 2.14 and Lemma 2.21 give

$$k \left( h_{\Lambda}(z, t), \varphi \left( \frac{1 - t}{\gamma d(z)} \right) + \frac{t}{\gamma d(z)} \varphi' \left( \frac{1 - t}{\gamma d(z)} \right) \right) A(tz) \cdot \Lambda$$

$$\lesssim \frac{1}{d(z)} k(h_{\Lambda}(z, t), A(tz) \cdot \Lambda)$$

$$\lesssim 1. \quad (23)$$

Again with Corollary 2.14 and Lemma 2.21, we obtain

$$k \left( h_{\Lambda}(z, t), \varphi \left( \frac{1 - t}{\gamma d(z)} \right) \right) dA_{tz}[z] \cdot \Lambda \lesssim k(h_{\Lambda}(z, t), dA_{tz}[z] \cdot \Lambda)$$

$$\lesssim |z| \lesssim 1. \quad (24)$$

Together (21), (22), (23) and (24) give $k \left( h_{\Lambda}(z, t), \frac{\partial h_{\Lambda}}{\partial t}(z, t) \right) \lesssim 1.$

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We now prove the second inequality:

\[
d_z h_A(z, t)[u] = tu + \left( -\frac{t(1-t)}{d(z)^2} \frac{\partial d}{\partial u}(z)\varphi \left( \frac{1-t}{\gamma d(z)} \right) - \frac{t(1-t)^2}{\gamma d(z)^2} \frac{\partial \varphi}{\partial u}(z)\varphi' \left( \frac{1-t}{\gamma d(z)} \right) \right) A(z) \cdot \Lambda \\
+ t(1-t) \varphi \left( \frac{1-t}{\gamma d(z)} \right) \frac{1}{d_A}(u) \cdot \Lambda \\
+ t \frac{\partial \varphi}{\partial u}(z) \frac{1-t}{\gamma d(z)^2} \varphi' \left( \frac{1-t}{\gamma d(z)} \right) A(tz) \cdot \Lambda \\
+ t \left( 1 - \varphi \left( \frac{1-t}{\gamma d(z)} \right) \right) d_A(z)[u] \cdot \Lambda.
\]

Proposition 2.8 implies that \( \left| \frac{\partial d}{\partial u}(z) \right| \lesssim \frac{d(z)}{\tau(z, u, d(z))} \). Therefore, since \( 1-t \approx \gamma d(z) \), we have

\[
\left| \frac{t(1-t)}{d(z)^2} \frac{\partial d}{\partial u}(z)\varphi \left( \frac{1-t}{\gamma d(z)} \right) - \frac{t(1-t)^2}{\gamma d(z)^2} \frac{\partial \varphi}{\partial u}(z)\varphi' \left( \frac{1-t}{\gamma d(z)} \right) \right| \lesssim \frac{1}{\tau(z, u, d(z))}; \\
\left| t \frac{\partial \varphi}{\partial u}(z) \frac{1-t}{\gamma d(z)^2} \varphi' \left( \frac{1-t}{\gamma d(z)} \right) \right| \lesssim \frac{1}{\tau(z, u, d(z))}.
\]

We then get with Corollary 2.14 and Lemma 2.21

\[
k(h_A(z, t), d_z h_A(z, t)[u]) \lesssim k(z, u).
\]

We now estimate (III). The way is essentially the same as in the previous subsections, the main difference being when we substitute \( \zeta = h_A(z, t) \). By Lemma 2.22 we get

\[
(III) \lesssim \int_{z \in \mathcal{P}(\zeta), \Lambda} \frac{|\theta(h_A(z, t))|^2}{k(h_A(z, t), d_z h_A(z, t)[u(z)] \cdot k(h_A(z, t), d_A(z)[u(z)])} \cdot d \Delta t d \Lambda(z).
\]

As previously, Proposition 2.12 gives \( (III) \lesssim \sum_{j, k=1}^n (III)_{j,k} \) where

\[
(III)_{j,k} := \int_{z \in \mathcal{P}(\zeta), \Lambda} \frac{|\theta(h_A(z, t))|^2}{k(h_A(z, t), e_j(h_A(z, t)), e_k(h_A(z, t))) \cdot k(h_A(z, t), e_j(h_A(z, t)), e_k(h_A(z, t)))} \cdot d \Delta t d \Lambda(z).
\]

Now we make the substitution \( \zeta = h_A(z, t) \) for \( \Lambda \) running over \( \Delta_A(\rho) \). By Lemma 2.21 \( h_A(z, t) \) belongs to \( \mathcal{P}_{d(z)}(z) \) and \( d(h_A(z, t)) \approx d(z) \). We have to be a little careful with the determinant of the Jacobian matrix of \( h_A(z, t) \). We have

\[
\det(d_A h_A(z, t)) = \left| \det \left( \varphi \left( \frac{1-t}{\gamma d(z)} \right) \frac{1-t}{d(z)} A(t) + \left( 1 - \varphi \left( \frac{1-t}{\gamma d(z)} \right) \right) A(tz) \right) \right|^2.
\]
Since $\frac{1-t}{d(z)} A(t)$ and $A(tz)$ are both positive definite hermitian matrices, we have

$$\det(d_A h_A(z, t)) \geq \left| \det \left( \frac{1-t}{d(z)} A(tz) \right) \right|^{2\phi} \left| \det(A(tz)) \right|^{2(1-\phi)},$$

where $\phi$ is a shortcut for $\varphi \left( \frac{1-t}{\gamma d(z)} \right)$.

Since $\frac{1-t}{d(z)} \approx \gamma$, Proposition 2.11 gives $\det_C \left( \frac{1-t}{d(z)} A(tz) \right) \approx \left( \text{Vol}(\mathcal{P}_d(z)) \right)^{\frac{1}{2}}$, uniformly with respect to $z$ and $t$.

Again using Proposition 2.11, we get $\det_C A(tz) \approx \left( \text{Vol}(\mathcal{P}_d(tz)(z)) \right)^{\frac{1}{2}}$. Since $tz$ belongs to $\mathcal{P}_K d(z)$ for some uniform big $K$ and since $d(tz) \approx d(z)$, we actually have $\det_C A(tz) \approx \left( \text{Vol}(\mathcal{P}_d(z)) \right)^{\frac{1}{2}}$.

Therefore $\det_D(d_A h_A(z, t)) \gtrsim \text{Vol}(\mathcal{P}_d(z))$ and

$$(III)_{j,k} \lesssim \int_{z \in \mathcal{P}_d(z) \cap D} \frac{1}{\text{Vol}(\mathcal{P}_d(z))} \frac{d(z)|\theta(\xi)|[e_j(\xi), e_k(\xi)]}{k(\xi, e_j(\xi))k(\xi, e_k(\xi))} d\lambda(\xi) d\lambda(z).$$

Now, we proceed exactly as in the previous subsections. We integrate for $t \in [1 - \gamma d(z), 1 - \frac{\gamma d(z)}{2}]$ and get

$$(III)_{j,k} \lesssim \int_{z \in \mathcal{P}_d(z) \cap D} \frac{1}{\text{Vol}(\mathcal{P}_d(z))} \frac{d(z)|\theta(\xi)|[e_j(\xi), e_k(\xi)]}{k(\xi, e_j(\xi))k(\xi, e_k(\xi))} d\lambda(\xi) d\lambda(z).$$

We use again Fubini’s theorem and get since $d(\xi) \approx d(z)$

$$(III)_{j,k} \lesssim \int_{\xi \in \mathcal{P}_d(\xi) \cap D} \frac{1}{\text{Vol}(\mathcal{P}_d(\xi))} \frac{d(\xi)|\theta(\xi)|[e_j(\xi), e_k(\xi)]}{k(\xi, e_j(\xi))k(\xi, e_k(\xi))} d\lambda(\xi) d\lambda(z).$$

We now integrate successively for $z \in K \mathcal{P}_d(\xi) \cap D$ and $\xi \in \mathcal{P}_K(\xi) \cap D$ and get

$$(III)_{j,k} \lesssim \sigma(\mathcal{P}_d(z) \cap 2D) \|d \cdot \theta\|_{W^{1,1}_{1,1}}.$$

This finally ends to prove that $(III) \lesssim \sigma(\mathcal{P}_d(z) \cap 2D) \|d \cdot \theta\|_{W^{1,1}_{1,1}}$, which completes the proof of Theorem 1.4.

### 3 The $\overline{\partial}$-equation

The solution of the $\overline{\partial}$-equation will be given by the integral operator already used by Diederich and Mazzilli [16] and which we now recall.

Let $\mathcal{V} = \{z, d(z) < \eta_0\}, \eta_0 > 0$, be a small neighborhood of $bD$ and let $S \in C^\infty(\mathcal{V} \times \overline{D})$ be the support function constructed by Diederich and Fornæss [15] and globalized in [1]. Let $Q = (Q_1, \ldots, Q_n)$ be its Hefer decomposition defined in [2] so that $S(\xi, z) = (Q(\xi, z), \xi - z)$. The support function $S$ and its Hefer decomposition are holomorphic in $D$ for all fixed $\xi \in \mathcal{V}$. Let also $\chi$ be a $C^\infty$ cut-off function such that $\chi(z) = 1$ if $r(z) \leq -\eta_0$ and $\chi(z) = 0$ if $r(z) \geq -\frac{\eta_0}{2}$. We then put for $(\xi, z) \in \overline{D} \times \overline{D}$
\[ s(\xi, z) := -r(z) \sum_{i=1}^{n} (\xi_i - z_i) d\xi_i - (1 - \chi(z)) \overline{S(z, \xi)} \sum_{i=1}^{n} Q_i(z, \xi) d\xi_i, \]
\[ q(\xi, z) := \frac{1}{r(\xi)} \left( -(1 - \chi(\xi)) \sum_{i=1}^{n} Q_i(\xi, z) d\xi_i + \chi(\xi) \sum_{i=1}^{n} \frac{\partial r(\xi)}{\partial \xi_i} d\xi_i \right), \]
\[ K(\xi, z) := c_n \sum_{k=0}^{n-1} s(\xi, z) \wedge (\partial_{\xi} s(\xi, z))^n-k \wedge (\partial_{\xi} q(\xi, z))^k \]

We get from Berndtsson–Andersson’s theorem [8]

**Proposition 3.1** Let \( \omega \) be a \( \overline{\partial} \)-closed \((0, 1)\)-form smooth on \( \overline{D} \). Then

\[ u(z) := \int_{D} \omega(\xi) \wedge K(\xi, z), \ z \in D \quad (25) \]

satisfies \( \overline{\partial} u = \omega \) on \( D \).

K. Diederich and E. Mazzilli showed that \( K \) is uniformly integrable and get from the theorem of Skoda [27] that \( u \) given by (25) is continuous up to the boundary and its boundary values are still given by (25). Following the idea of [7] also used in [11], we prove that when \( \omega \) is a smooth \( \overline{\partial} \)-closed \((0, 1)\)-form such that \( \|\omega\|_{W^{1}_{1}(0,1)} \) is finite, the function \( u = \exp(pu) \), \( u \) given by (25), is in \( L^{1}(bD) \) for some positive \( p \).

Since \( \omega(\xi) \wedge K(\xi, z) \) is an \((n, n)\)-form, we have \( \omega(\xi) \wedge K(\xi, z) = \psi(\xi, z) d\nu(\xi) \) where

\[ \psi(\xi, z) = \frac{1}{\det(e_{1, n}(\xi))} \omega(\xi) \wedge K(\xi, z)(e_1, \ldots, e_n, \overline{e}_1, \ldots, \overline{e}_n) \]

for any basis \( e_1, \ldots, e_n \) of \( \mathbb{C}^n \). In [11] they chose an \( \epsilon \)-extremal basis as a basis to compute \( \psi \). Here our hypothesis on \( \omega \) are linked to vectors fields. That’s why we will use the same basis as in Sect. 2: Let \( e_j(\xi) \) be the \( j \)th column of the matrix \( A(\xi) = \Phi^{-1}(B(\xi)) \).

We then have

\[ |\psi(\xi, z)| \leq \sum_{i=1}^{n} \frac{|K(\xi, z)(e_i(\xi))| k(\xi, e_i(\xi))}{|\det(B(\xi))|^{-1}} \frac{1}{k(\xi, e_i(\xi))} |\omega(\xi)|(e_i(\xi)) \]

where \( e_i(\xi) \) is the vectors family \( e_1(\xi), \ldots, e_n(\xi), \overline{e}_1(\xi), \ldots, \overline{e}_{i-1}(\xi), \overline{e}_{i+1}(\xi), \ldots, \overline{e}_n(\xi) \).

We set \( \tilde{\psi}_i(\xi, z) := \frac{|K(\xi, z)(e_i(\xi))| k(\xi, e_i(\xi))}{|\det(B(\xi))|^{-1}} \) so that

\[ |u(z)| \leq \sum_{i=1}^{n} \int_{D} \tilde{\psi}_i(\xi, z) \frac{1}{k(\xi, e_i(\xi))} |\omega(\xi)|(e_i(\xi)) d\nu(\xi). \]

Therefore it suffices to show that for all \( i \) and all Carleson measure \( v \), there exists \( p_v > 0 \) such that for all \( p < p_v \), the function \( v(z) := \int_{D} \tilde{\psi}_i(\xi, z) d\nu(\xi), z \in bD \), is such that \( \exp(pv) \) belongs to \( L^{1}(bD) \) and has \( L^{1} \) norm controled by \( \|v\|_{W^{1}_{1}(bD)} \).

Now we proceed similarely to [7,11]. We set for \( f \in L^{1}(bD) \)

\[ L_{i}(f)(\xi) := \int_{bD} \tilde{\psi}_i(\xi, z) f(z) d\sigma(z), \ \xi \in D \]

and we aim to prove the following lemma

**Lemma 3.2** For all \( i = 1, \ldots, n \)
(i) \( \int_{bD} \tilde{\psi}_i(\zeta, z) d\sigma(z) \leq C, \) uniformly in \( \zeta \in D, \)

(ii) for all \( v \in W^1(D), \) all \( f \in L^1(bD) \) and all \( s > 0 \) we have

\[
v[\zeta, |L_i(f)(\zeta)| \geq s] \lesssim \frac{1}{s} \|v\|_{W^1(D)} \|f\|_{L^1(bD)}
\]

uniformly with respect to \( f, v \) and \( s. \)

In order to prove Lemma 3.2, we first notice as in [16], that the denominator of \( K(\zeta, z) \) is bounded away from 0 when \( |\zeta - z| \gtrsim 1, \) so the only case which has to be investigated is when \( \zeta \) is near the boundary and it suffices to integrate for \( z \) in small neighborhood of \( \zeta, \) say \( \mathcal{P}_{\varepsilon_0}(\zeta), \varepsilon_0 \) not depending on \( \zeta. \) We thus fix a point \( \zeta_0 \) near \( bD, \varepsilon_0 > 0 \) small enough, and consider points \( z \in bD \cap \mathcal{P}_{\varepsilon_0}(\zeta_0). \)

We set \( Q(\zeta, z) := \sum_{i=1}^{n} Q_i(\zeta, z)d\xi_i \) and \( \tilde{Q}(\zeta, z) := \sum_{i=1}^{n} \bar{Q}_i(z, \zeta)d\xi_i. \) Let us notice that \( \tilde{Q} \) is holomorphic with respect to \( \zeta. \) So, when \( z \) belong to \( bD, \) only the term with \( k = n-1 \) in the sum which defines \( K \) matters. Now as in [16] we write this term as \( K_1 + K_2 \) where

\[
K_1(\zeta, z) = \frac{\tilde{Q}(\zeta, z) \wedge \bar{Q}(\zeta, z) \wedge (\overline{\partial} \zeta Q(\zeta, z))^{n-2}}{S(z, \zeta)(r(\zeta) + S(\zeta, z))^n},
\]

\[
K_2(\zeta, z) = \frac{r(\zeta)\tilde{Q}(\zeta, z) \wedge (\overline{\partial} \zeta Q(\zeta, z))^{n-1}}{S(z, \zeta)(r(\zeta) + S(\zeta, z))^n}.
\]

We will only estimate \( K_1, K_2 \) can treated with the same computations. Most of these computations are similar to those of [4]. We write \( K_1 \) in a Yu-basis at \( \zeta \) and we first recall the definition of a Yu basis at \( \zeta \) for convex domains of finite type.

For \( f : \mathbb{C} \rightarrow \mathbb{C}^n \) such that \( f(0) = 0, \) we denote by \( v(f) \) the multiplicity of 0 as a zero of \( f. \) The variety 1-type \( \Delta_1(bD_{r(\zeta)}, \zeta) \) of \( bD_{r(\zeta)} \) at a point \( \zeta \) is defined as

\[
\Delta_1(bD, \zeta) = \sup_{\zeta} \frac{v(z^a r)}{v(z - \zeta)}
\]

where the supremum is taken over all non zero germ \( z : \Delta \rightarrow \mathbb{C}^n \) from \( \Delta, \) the unit disc of \( \mathbb{C}, \) into \( \mathbb{C}^n, \) such that \( z(0) = \zeta. \) The function \( z^a r \) is the pullback of \( r \) by \( z. \)

The variety \( q \)-type \( \Delta_q(\xi, bD) \) at the point \( \xi \) is then defined as

\[
\Delta_q(bD, \xi) := \inf_{H} \Delta_1(bD_{r(\xi)} \cap H, \xi)
\]

where the infimum is taken over all \( (n-q+1) \)-dimensional complex linear manifolds \( H \) passing through \( \xi. \) Finally, the multitype \( M(bD_{r(\xi)}, \zeta) \) of \( bD_{r(\xi)} \) at the point \( \zeta \) is defined to be the \( n \)-tuple \( (\Delta_n(bD_{r(\xi)}, \zeta), \Delta_{n-1}(bD_{r(\xi)}, \zeta), \ldots, \Delta_1(bD_{r(\xi)}, \zeta)). \) From Corollary 2.21 of [17], we have, uniformly with respect to \( \zeta \) and \( \varepsilon, \) \( \text{Vol}(\mathcal{P}_\varepsilon(\zeta)) \approx \varepsilon^{2(\Delta_1(bD_{r(\xi)}, \zeta) + \ldots + \Delta_n(bD_{r(\xi)}, \zeta)))}. \)

A basis \( w_1', \ldots, w_n' \) of \( \mathbb{C}^n \) such that for all \( i, \) the order of contact of \( bD_{r(\xi)} \) and the line spanned by \( w_i' \) passing through \( \xi \) is equal to \( \Delta_n+1-i(bD_{r(\xi)}, \zeta) \) is called a Yu basis at \( \zeta \) (see [17]).

A Yu basis satisfies the following proposition which is the analog of Proposition 1.6 for the extremal basis (see [17], Theorem 2.22).

**Proposition 3.3** Let \( \zeta \in D \) be a point near \( bD, \) let \( (m_1, \ldots, m_n) \) denote the multitype of \( bD_{r(\xi)} \) at \( \zeta, \) let \( w_1', \ldots, w_n' \) be a Yu basis at \( \zeta, \) let \( \varepsilon \) be a positive number and let \( v = \sum_{j=1}^{n} v_j' w_j' \) be a unit vector. Then, uniformly with respect to \( \zeta, v \) and \( \varepsilon \) we have

\[
\frac{1}{\tau(\zeta, v, \varepsilon)} \approx \frac{\varepsilon}{\sum_{j=1}^{n} \frac{|v_j'|}{\varepsilon^m_j}}.
\]
We notice that in particular, with the notations of Proposition 3.3, \( \tau(z, w'_j, \varepsilon) \simeq \varepsilon^{\frac{1}{n_j}} \).

We fix a Yu basis \( w'_1, \ldots, w'_n \) at \( \zeta_0 \) and analogously to the extremal basis notation, we put \( \tau'_i(\xi, \varepsilon) := \tau(\xi, w'_i(\xi); \varepsilon) \). We denote by \( \xi' = (\xi'_1, \ldots, \xi'_n) \) the coordinates of a point \( \xi \) in the coordinates system centered at \( \zeta_0 \) of basis \( w'_1, \ldots, w'_n \). Then we write \( \tilde{Q} \) and \( Q \) in the Yu basis at \( \zeta_0 \): \( \tilde{Q}(\zeta, z) = \sum_{j=1}^{n} \tilde{Q}'_j(\zeta, z)d\xi'_j \) and \( Q(\zeta, z) = \sum_{j=1}^{n} Q'_j(\zeta, z)d\xi'_j \). In the Yu basis \( w'_1, \ldots, w'_n, K_1 \) is a sum of the following terms

\[
K_{v,\mu}(\zeta, z) = \frac{\tilde{Q}'_v(\zeta, z)d\xi'_v \wedge \frac{\partial r}{\partial \xi'_\mu_2}(\zeta)d\tilde{\xi}'_{\mu_2} \wedge Q'_v(\zeta, z)d\xi'_v \wedge \frac{\partial Q'_v}{\partial \xi'_{\mu_1}}(\zeta, z)d\tilde{\xi}'_{\mu_1} \wedge d\xi'_v}{S(\zeta, r(\zeta) + S(\zeta, z))^n}
\]

where \( v_i \) and \( \mu_i \) run from 1 to \( n \), \( v_i \neq v_j, \mu_i \neq \mu_j \) for \( i \neq j \). We have to estimate \( \frac{k(\xi, e_{i_0}(\xi))}{|\det(B(\xi))|} \cdot K_{v,\mu}(\zeta, z)(e_{i_0}(\xi)) \) for all such \( v \) and \( \mu \). We have the following proposition which comes from [2,3] and Proposition 3.3, and which were already used in [4]:

**Proposition 3.4** For all \( \zeta \) near enough \( bD \), all sufficiently small \( \varepsilon > 0 \), all \( \xi, \zeta, \xi' \in \mathcal{P}_\varepsilon(\zeta) \) and \( i, j = 1, \ldots, n \), we have uniformly with respect to \( \zeta, \xi, \xi' \) and \( \varepsilon \)

\[
|Q'_j(\xi, z)| \lesssim \frac{\varepsilon}{\tau'_j(\xi, \varepsilon)},
\]

\[
\left| \frac{\partial Q'_i}{\partial \xi'_{ij}}(\xi, z) \right| \lesssim \frac{\varepsilon}{\tau'_j(\xi, \varepsilon) \tau'_i(\xi, \varepsilon)}.
\]

Since \( \delta \) is a pseudodistance, we deduce the following inequalities from Proposition 4.4 from [4]: for all \( z \in \mathcal{P}_\varepsilon(\zeta_0) \setminus cP_\varepsilon(\zeta_0) \cap bD, \varepsilon > 0 \) given by Corollary 2.3 such that \( cP_\varepsilon(\zeta_0) \subset \mathcal{P}_{\frac{1}{2}\varepsilon}(\zeta_0) \), we have uniformly with respect to \( \zeta_0 \) and \( z \)

\[
|S(\zeta, \zeta_0)| \gtrsim \varepsilon, \quad (26)
\]

\[
|S(\zeta_0, z) + r(\zeta_0)| \gtrsim \varepsilon. \quad (27)
\]

With the inequality \( \left| \frac{\partial r}{\partial \xi'_{ij}}(\xi_0) \right| \lesssim \frac{d(\xi_0)}{\tau'_i(\xi_0, d(\xi_0))} \) which comes from Proposition 2.8, we get

\[
\left| \tilde{Q}'_v(\zeta_0, z) \frac{\partial r}{\partial \xi'_{ij}}(\xi_0) Q'_v(\zeta_0, z) \prod_{i=3}^{n} \frac{\partial Q'_v}{\partial \xi'_{\mu_i}}(\zeta_0, z) \right| \lesssim \frac{d(\xi_0)}{\tau'_i(\zeta_0, d(\xi_0))} \frac{1}{\varepsilon \prod_{i=1}^{n} \tau'_i(\zeta_0, \varepsilon) \prod_{i=2}^{n} \tau'_{\mu_i}(\zeta_0, \varepsilon)} \quad (28)
\]

We now estimate \( \frac{k(\zeta_0, e_{i_0}(\xi_0))}{|\det(B(\xi_0))|} \cdot \prod_{i=1}^{n} d\xi'_i \wedge \prod_{i=2}^{n} d\tilde{\xi}'_{\mu_i}(\overline{e}_{i_0}(\xi_0)) \). We denote the coordinates of \( e_i(\xi_0) \) in the Yu basis \( w'_1, \ldots, w'_n \) by \( (e'_{i_1}(\xi_0), \ldots, e'_{i_n}(\xi_0)) \). Proposition 4.8 of [4] asserts that

\[
|e'_{ij}(\xi_0)| \lesssim \tau'_j(\xi_0, d(\xi_0)).
\]

Therefore

\[
\prod_{i=1}^{n} d\xi'_i \wedge \prod_{i=2}^{n} d\tilde{\xi}'_{\mu_i}(\overline{e}_{i_0}(\xi_0)) \lesssim \prod_{i=1}^{n} \tau'_i(\xi_0, d(\xi_0)) \prod_{i=2}^{n} \tau'_{\mu_i}(\xi_0, d(\xi_0)).
\]
Since $e_1(\zeta_0), \ldots, e_n(\zeta_0)$ is an orthonormal basis for the Bergman metric, $k(\zeta_0, e_i(\zeta_0)) \approx d(\zeta_0)$ and since $(\det B(\zeta_0))^{-1} \approx \text{Vol}(\mathcal{P}_{d(\zeta_0)}(\zeta_0)) \approx \prod_{i=1}^n \tau_i'(\zeta_0, d(\zeta_0))^2$, we get
\[
\left| \frac{k(\zeta_0, e_i(\zeta_0))}{(\det B(\zeta_0))^{-1}} \cap_{i=1}^n d\varepsilon'_1 \cap_{i=2}^n d\varepsilon'_2(\varepsilon_{i_0}(\zeta)) \right| \lesssim \frac{d(\zeta_0)}{\tau_{\mu_1}(\zeta_0, d(\zeta_0))},
\]
where $\mu_1 \in \{1, \ldots, n\} \setminus \{\mu_2, \ldots, \mu_n\}$.

From (28) and (29), we obtain
\[
\left| \frac{k(\zeta_0, e_i(\zeta_0))}{(\det B(\zeta_0))^{-1}} K_{v, \mu}(\zeta_0, z)(\tilde{e}_{i_0}(\zeta)) \right| \lesssim \frac{d(\zeta_0)^2 \tau_{\mu_1}(\zeta_0, \varepsilon') \tau_{\mu_2}(\zeta_0, \varepsilon)}{\varepsilon^2 \tau_{\mu_1}(\zeta_0, d(\zeta_0)) \tau_{\mu_2}(\zeta_0, d(\zeta_0))} \frac{1}{\sigma(\mathcal{P}_{d(\zeta_0)}(\zeta_0) \cap bD)}.
\]

Since at least $\mu_1$ or $\mu_2$ is different from 1, we get from Proposition 3.3
\[
\frac{d(\zeta_0)^2 \tau_{\mu_1}(\zeta_0, \varepsilon') \tau_{\mu_2}(\zeta_0, \varepsilon)}{\varepsilon^2 \tau_{\mu_1}(\zeta_0, d(\zeta_0)) \tau_{\mu_2}(\zeta_0, d(\zeta_0))} \lesssim \left( \frac{d(\zeta_0)}{\varepsilon} \right)^{\frac{1}{2}}.
\]

Finally, we get for all $z \in bD \cap \mathcal{P}_{d(\zeta_0)} \setminus c\mathcal{P}_{d(\zeta_0)}$
\[
\left| \frac{k(\zeta_0, e_i(\zeta_0))}{(\det B(\zeta_0))^{-1}} K_{1}(\zeta_0, z)(\tilde{e}_{i_0}(\zeta)) \right| \lesssim \frac{1}{\sigma(\mathcal{P}_{d(\zeta_0)}(\zeta_0) \cap bD)}.
\]

Since $z$ belongs to $bD$ and since $\zeta_0$ belongs to $D$, $\delta(z, \zeta_0) \gtrsim d(\zeta_0)$ so the inequalities (26) and (27) are still valid for $z \in \mathcal{P}_{d(\zeta_0)} \cap bD$. Therefore we have for such $z$:
\[
\left| \frac{k(\zeta_0, e_i(\zeta_0))}{(\det B(\zeta_0))^{-1}} K_{1}(\zeta_0, z)(\tilde{e}_{i_0}(\zeta)) \right| \lesssim \frac{1}{\sigma(\mathcal{P}_{d(\zeta_0)}(\zeta_0) \cap bD)}.
\]

The estimates (31) and (32) can be shown for $K_2$ instead of $K_1$. Now, as in [14] we cover $\mathcal{P}_{d(\zeta_0)}$ with some polyannuli based on McNeal’s polydiscs. For sufficiently small $\varepsilon > 0$ we set $\mathcal{P}_\varepsilon(\zeta_0) := \mathcal{P}_{2\varepsilon}(\zeta_0) \setminus c\mathcal{P}_{2\varepsilon}(\zeta_0)$. This gives us the following covering
\[
\mathcal{P}_{d(\zeta_0)} \subset \mathcal{P}_{d(\zeta_0)}(\zeta_0) \cup \bigcup_{k=0}^{k_0} \mathcal{P}_{d(\zeta_0)}^k(\zeta_0)
\]
where $k_0$ satisfies $k_0 \approx |\ln \varepsilon_0 - \ln d(\zeta_0)|$, uniformly in $\zeta_0$ and $\varepsilon_0$. We finally get
\[
\int_{bD \cap \mathcal{P}_{d(\zeta_0)}} \tilde{\psi}_{i_0}(\zeta_0, z) d\sigma(z)
\]
\[
\lesssim \int_{bD \cap \mathcal{P}_{d(\zeta_0)}} \left| \frac{k(\zeta_0, e_i(\zeta_0))}{(\det B(\zeta_0))^{-1}} K_{1}(\zeta_0, z)(\tilde{e}_{i_0}(\zeta)) \right| d\sigma(z)
\]
\[
+ \sum_{k=0}^{k_0} \int_{bD \cap \mathcal{P}_{d(\zeta_0)}^k} \left| \frac{k(\zeta_0, e_i(\zeta_0))}{(\det B(\zeta_0))^{-1}} K_{1}(\zeta_0, z)(\tilde{e}_{i_0}(\zeta)) \right| d\sigma(z)
\]
\[
\lesssim 1 + \sum_{k=0}^{k_0} \frac{1}{2^k} \lesssim 1.
\]
uniformly with respect to \( \zeta_0 \). The first point of Lemma 3.2 is then proved.

In order to prove the second point, for \( f \in L^1(bD) \) we defined the maximal function

\[
\tilde{f}(\zeta) := \sup_{\epsilon \geq d(\zeta)} \left( \frac{1}{\sigma(P_{\epsilon}(\zeta) \cap bD)} \int_{P_{\epsilon}(\zeta) \cap bD} |f(\xi)|d\sigma(\xi) \right),
\]

We deduce from (31) and (32) and their analogous version for \( p \)

\[
\int_{bD \cap P_{\epsilon}(\zeta)} \left| \frac{k(\zeta_0, e_{i_0}(\zeta_0))}{\det(B(\zeta_0)^{-1})} K(\zeta_0, z)(\zeta_0) \right| |f(z)|d\sigma(z) \lesssim \int_{bD \cap P_{\epsilon}(\zeta)} \left| \frac{k(\zeta_0, e_{i_0}(\zeta_0))}{\det(B(\zeta_0)^{-1})} K(\zeta_0, z)(\zeta_0) \right| |f(z)|d\sigma(z)
\]

Then, for \( \zeta \)

\[
\int_{bD \cap P_{\epsilon}(\zeta)} \left| \frac{k(\zeta_0, e_{i_0}(\zeta_0))}{\det(B(\zeta_0)^{-1})} K(\zeta_0, z)(\zeta_0) \right| |f(z)|d\sigma(z)
\]

We claim that there exist \( C, C' > 0 \) depending only on \( \sigma(\epsilon) \) such that \( \exp(p\nu) \in L^1(bD) \) for some \( p > 0 \) depending only on \( \|\nu\|_{W^1} \). The method is exactly the same as in [7, 11]. We incorporate it for completeness.

Let \( E_t := \{ z \in bD, \nu(z) > t \} \). We have

\[
\int_{bD} \exp(p\nu(z))d\sigma(z) = \int_0^\infty p \exp(pt)\sigma(E_t)dt + \sigma(bD).
\]

We claim that there exist \( C, C' > 0 \) not depending on \( t \) or \( \nu \) such that \( \sigma(E_t) \leq Ce^{-\frac{C't}{\|\nu\|_{W^1}}} \).

Then, for \( p < \frac{C'}{\|\nu\|_{W^1}}, \int_{bD} \exp(p\nu(z))d\sigma(z) \) is bounded, which was to be shown. Theorem 1.5 will therefore be proved as soon as the claim is proved.

We denote by \( \chi_{E_t} \) the characteristic function of \( E_t \). We have

\[
t\sigma(E_t) \leq \int_{E_t} \nu(z)d\sigma(z)
\]

\[
\leq \int_D \left( \int_{bD} \tilde{\psi}_t(\xi, z)\chi_{E_t}(z)d\sigma(z) \right)d\nu(\xi)
\]

\[
\leq \int_D L_t(\chi_{E_t})(\xi)d\nu(\xi)
\]

\[
\leq \int_0^\infty \nu(\{L_t(\chi_{E_t}) > s \}) ds.
\]
Lemma 3.2 (i) implies that \( L_i(\chi_{E_t}) \) is bounded by some constant \( M > 0 \) which does not depend on \( t \) so
\[
t \sigma(E_t) \leq \int_0^M \nu(\{L_i(\chi_{E_t}) > s\}) \, ds
\leq \int_0^{\sigma(E_t)} \nu(\{L_i(\chi_{E_t}) > s\}) \, ds + \int_{\sigma(E_t)}^M \nu(\{L_i(\chi_{E_t}) > s\}) \, ds.
\]
Now Lemma 3.2 (ii) yields
\[
t \sigma(E_t) \precsim \sigma(E_t) \sigma(bD) \|\nu\|_{W^1} + \int_{\sigma(E_t)}^M \|\nu\|_{W^1} \frac{1}{s} \sigma(E_t) \, ds
\precsim \sigma(E_t) \|\nu\|_{W^1} \left( \sigma(bD) + \ln \left( \frac{M}{\sigma(E_t)} \right) \right).
\]
Therefore there exists \( C', C > 0 \) which does not depend on \( \nu \) or \( t \) such that \( \sigma(E_t) \leq Ce^{\frac{-C' t}{\|\nu\|_{W^1}}} \) and the claim is proved.

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