LiteHAR: LIGHTWEIGHT HUMAN ACTIVITY RECOGNITION FROM WIFI SIGNALS WITH RANDOM CONVOLUTION KERNELS

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ABSTRACT

Anatomical movements of the human body can change the channel state information (CSI) of wireless signals in an indoor environment. These changes in the CSI signals can be used for human activity recognition (HAR), which is a predominant and unique approach due to preserving privacy and flexibility of capturing motions in non-line-of-sight environments. Existing models for HAR generally have a high computational complexity, contain very large number of trainable parameters, and require extensive computational resources. This issue is particularly important for implementation of these solutions on devices with limited resources, such as edge devices. In this paper, we propose a lightweight human activity recognition (LiteHAR) approach which, unlike the state-of-the-art deep learning models, does not require extensive training of a large number of parameters. This approach uses randomly initialized convolution kernels for feature extraction from CSI signals without training the kernels. The extracted features are then classified using Ridge regression classifier, which has a linear computational complexity and is very fast. LiteHAR is evaluated on a public benchmark dataset and the results show its high classification performance with a much lower computational complexity in comparison with the complex deep learning models.

Index Terms—Channel state information, random convolution kernels, human activity recognition, time series.

1. INTRODUCTION

The WiFi technology, based on the IEEE 802.11n/ac standards [1], uses Orthogonal Frequency Division Multiplexing (OFDM) which decomposes the spectrum into multiple subcarriers with a symbol transmitted over each subcarrier. Channel state information (CSI) reflects how each subcarrier is affected through the wireless communication channel.
time series as proposed in Rocket [13]. This is a fast and accurate time series classification approach which has showed significant performance improvement in classification tasks for various applications such as driver’s distraction detection using electroencephalogram (EEG) signals [14] and functional near infrared spectroscopy signals classification [15].

This paper proposes a novel approach for HAR based on Rocket [13]. Unlike the deep learning approaches [1, 3, 4, 5], our method does not require training of a large number of parameters and is computationally very light, hence called lightweight human activity recognition (LiteHAR). LiteHAR also does not require a GPU setup and can be implemented on local devices without cloud access.

2. LiteHAR MODEL

Different steps of the proposed LiteHAR model are presented in Fig. 1. The steps are described in detail next.

2.1. Input Signals

Let \( \{ (X_1, y_1), ..., (X_N, y_N) \} \) represent a set of \( N \) training samples where \( X_n = (x_{n,1}, ..., x_{n,M}) \) is the CSI amplitude signal of \( M \) subcarriers over time and \( y_n \) is the corresponding activity label. As an example, for a MIMO receiver with three antennas and 30 subcarriers per antenna, \( (x_{1,1}, ..., x_{30}) \), \( (x_{31}, ..., x_{60}) \), and \( (x_{61}, ..., x_{90}) \) represent the CSI amplitude signals of subcarriers on antenna one to three, respectively, as demonstrated in Fig. 2. Unlike most activity recognition methods (e.g. [1, 4]), we do not perform any major pre-processing on the input signals.

2.2. Feature Extraction

Let \( (\phi_1, ..., \phi_D) \) represent a set of convolution operations where the kernels \( 1, ..., D \) are randomly initialized based on Rocket [13] as follows:

- Length: Randomly selected from \( \{7, 9, 11\} \) with equal probability;
- Weights: Randomly sampled from a Normal distribution \( \mathcal{N}(0, 1) \);
- Bias: Randomly sampled from a uniform distribution \( \mathcal{U}(-1, 1) \);
- Dilation: Randomly sampled from an exponential scale \( 2^a \), where \( a \sim \mathcal{U}(0, \log_2(l_{\text{input}} - 1) - 1) \), \( l_{\text{kernel}} \) is the kernel length, and \( l_{\text{input}} \) is the length of the input signal;
- Padding: Applied randomly with equal probability;
- Stride: Set to one for all kernels.

The convolution outputs are then represented by two values per kernel, the proportion of positive values (ppv) and the maximum value (max) [13]. Hence, the extracted features for each CSI subcarrier signal \( x_m \) is \( (k_{m,1}, ..., k_{m,D}) \), where \( k_{m,d} = (\text{ppv}_{m,d}, \text{max}_{m,d}) \). As Fig. 1 shows, for \( M \) given subcarriers, \( M \) feature vectors are generated. An advantage of this feature representation approach is mapping a variable-length time series to a fixed-length feature vector, which eliminates the padding of different-length signals.

2.3. Classifier

In the proposed model, we train a classifier \( \psi(\cdot) \) per subcarrier. Therefore, for the \( M \) extracted feature vectors
Table 1: Classification performance results and training and inference time of RF [1], HMM [1], LSTM [1], SAE [3], ABLSTM [4], and the proposed LiteHAR method with 10-fold cross-validation.

| Method     | Down | Fall | Walk | Run | Sit | Stand | Pick | Avg. | Total Training Time (Sec.) | Total Inference Time (Sec.) | Inference Time per Sample (Sec.) |
|------------|------|------|------|-----|-----|-------|------|-----|---------------------------|------------------------------|--------------------------------|
| RF         | 0.53 | 0.60 | 0.81 | 0.88| 0.49| 0.57  | -    | 0.65| 6.09                      | 0.016                        | 3.8e-5                        |
| HMM        | 0.52 | 0.72 | 0.92 | 0.96| 0.76| 0.52  | -    | 0.73| 0.22                      | 0.029                        | 5.2e-4                        |
| SAE        | 0.84 | 0.84 | 0.95 | 0.83| 0.84| 0.88  | -    | 0.86| 1788.28                   | 0.23                         | 5.4e-4                        |
| LSTM       | 0.05 | 0.94 | 0.93 | 0.97| 0.81| 0.83  | -    | 0.90| 5168.86                   | 4.39                         | 0.010 ↓ 90%                   |
| ABLSTM     | 0.96 | 0.09 | 0.98 | 0.98| 0.95| 0.98  | -    | 0.97| 13007.20                  | 6.86                         | 0.016                         |
| LiteHAR    | 0.92 | 0.93 | 0.99 | 0.99| 0.86| 0.94  | -    | 0.93| 157.8                     | 5.46                         | 0.013                         |
| LiteHAR (7 classes) | 0.90 | 0.90 | 0.99 | 0.95| 0.82| 0.94  | 0.93 | 0.91| 171.5                     | 5.46                         | 0.013                         |

\((k_1, \ldots, k_M)\), a classifier bank \((\psi_1(k_1), \ldots, \psi_M(k_M))\) is trained. The predicted activity class from the bank of classifiers is \(\hat{y} = (\hat{y}_1, \ldots, \hat{y}_M)\).

The predicted class for an input \(X_n\) with target activity class \(y_n\) over all the subcarriers is extracted by voting in \(\hat{y}\) as

\[
\hat{y} = \arg\max_c \left\{ \sum_{m=1}^M 1[\hat{y}_m, C], \ldots, \sum_{m=1}^M 1[\hat{y}_m, C] \right\},
\]

(1)

where \(c \in (1, \ldots, C)\) and \(C\) is the number of activity classes and \(1[\hat{y}_m, c]\) is the indicator function such that \(1[\hat{y}_m, c] = 1\) if \(\hat{y}_m = c\) and \(1[\hat{y}_m, c] = 0\) if \(\hat{y}_m \neq c\). From (1), it is obvious that \(\sum_c \sum_{m=1}^M 1[\hat{y}_m, c] = M\). If \(\hat{y} = y_n\) the model has made a correct prediction.

Commonly, the ridge regression classifier is used in Rocket, which is a very simple and significantly fast classifier, and uses generalized cross-validation to determine appropriate regularization [13]. This classifier is used as \(\psi_m(.)\) in this paper, but one is not limited to this classifier.

3. EXPERIMENTS

3.1. Data

The experiments were conducted on the CSI dataset\(^2\) provided in [1]. The CSI data was collected at a receiver with three antennas and 30 subcarriers at a sampling rate of 1kHz. The length of each collected sample is 20 Seconds. This dataset has 7 activity classes which are Run, Pick up, Lie down, Fall, Sit down, Stand up, and Walk, collected in an indoor environment. Most proposed methods in the literature (e.g. [1, 4, 5]) have been evaluated on 6 activity classes (i.e. the Pick up activity class has been excluded) of the dataset. For the sake of comparison, LiteHAR is evaluated on these 6 classes as well as on the entire dataset (i.e. 7 activity classes).

3.2. Setup

The proposed LiteHAR model is implemented in Python using Numba\(^3\) high performance compiler and parallel and lightweight pipelining\(^4\). Our codes are available online\(^5\). The input CSI signals are down-sampled to 500Hz and normalized by subtracting the mean and dividing by the \(l_2\)-norm. The number of random kernels is \(D = 10,000\) [13]. Regularization strength is set to 10 evenly spaced numbers on a log-scale in the range \((-3, 3)\). The average results of 10 independent runs are reported and the training dataset is shuffled in each run. A computational setup similar to [4] was used.

3.3. Classification Performance Analysis

Table 1 shows the classification accuracy results of the RF [1], HMM [1], LSTM [1], SAE [3], ABLSTM [4], and the proposed LiteHAR model. The confusion matrices of the top three models are presented in Table 2.

For the experiments on 6 activity classes, ABLSTM has the highest classification performance at 97% with the best overall accuracy for three activity classes. The accuracy of LiteHAR model is slightly lower than ABLSTM, where it has achieved the best overall performance for two activity classes. However, LiteHAR has a training time of 157.8 sec while the training time for ABLSTM is about 82× more than LiteHAR. In inference, LiteHAR is 0.003 sec faster than ABLSTM. Note that current version of LiteHAR is implemented for parallel processing on CPUs. However, a GPU implementation can further accelerate the training and inference of the model.

LiteHAR has achieved a performance of 91% in classification of 7 activity classes with an accuracy of 93% for the Pick up activity class. Adding this class has dropped the accuracy of LiteHAR by 2% from the 6-class model. The confusion matrix of LiteHAR for all the activity classes is presented in Table 3.

3.4. Computational Complexity of LiteHAR

The LiteHAR model has two parts. The first part is applying random convolution transforms for feature extraction, which has a computational complexity of \(O(T \cdot N \cdot l_{input})\), where \(l_{input}\) is the length of the time series [13]. This complexity is a linear function of the number of kernels. The sec-

\(^2\)https://github.com/ermongroup/Wifi_Activity_Recognition
\(^3\)http://numba.pydata.org/
\(^4\)https://joblib.readthedocs.io/en/latest/
\(^5\)https://github.com/salehinejad/LiteHAR
Table 2: Confusion matrix of the LSTM [1], ABLSTM [4], and proposed LiteHAR methods over the Lie down, Fall, Walk, Run, Sit down, and Stand up activity classes. Rows may not sum to one due to the rounding artifact.

(a) LSTM

| Actual       | Lie down | Fall | Walk | Run | Sit down | Stand up |
|--------------|----------|------|------|-----|---------|----------|
| Lie down     | 0.95     | 0.01 | 0.01 | 0.01| 0.01    | 0.01     |
| Fall         | 0.01     | 0.94 | 0.05 | 0.01| 0.0     | 0.0      |
| Walk         | 0.0      | 0.01 | 0.93 | 0.04| 0.01    | 0.01     |
| Run          | 0.0      | 0.02 | 0.97 | 0.01| 0.0     | 0.0      |
| Sit down     | 0.03     | 0.01 | 0.05 | 0.02| 0.81    | 0.07     |
| Stand up     | 0.01     | 0.0  | 0.03 | 0.05| 0.07    | 0.83     |

(b) ABLSTM

| Actual       | Lie down | Fall | Walk | Run | Sit down | Stand up |
|--------------|----------|------|------|-----|---------|----------|
| Lie down     | 0.96     | 0.0  | 0.01 | 0.01| 0.02    | 0.02     |
| Fall         | 0.0      | 0.99 | 0.0  | 0.01| 0.0     | 0.0      |
| Walk         | 0.0      | 0.0  | 0.98 | 0.02| 0.0     | 0.0      |
| Run          | 0.0      | 0.0  | 0.02 | 0.98| 0.0     | 0.0      |
| Sit down     | 0.01     | 0.01 | 0.01 | 0.0 | 0.95    | 0.02     |
| Stand up     | 0.01     | 0.0  | 0.0  | 0.0 | 0.01    | 0.98     |

(c) LiteHAR

| Actual       | Lie down | Fall | Walk | Run | Sit down | Stand up |
|--------------|----------|------|------|-----|---------|----------|
| Lie down     | 0.92     | 0.02 | 0.01 | 0.0 | 0.02    | 0.01     |
| Fall         | 0.01     | 0.93 | 0.0  | 0.01| 0.0     | 0.0      |
| Walk         | 0.0      | 0.0  | 0.99 | 0.01| 0.0     | 0.0      |
| Run          | 0.0      | 0.0  | 0.01 | 0.99| 0.0     | 0.0      |
| Sit down     | 0.03     | 0.05 | 0.0  | 0.0 | 0.86    | 0.06     |
| Stand up     | 0.01     | 0.03 | 0.0  | 0.0 | 0.01    | 0.94     |

Table 3: Confusion matrix of the proposed LiteHAR model over the Lie down, Fall, Walk, Run, Sit down, Stand up, and Pick up activity classes. Rows may not sum to one due to the rounding artifact.

| Actual       | Lie down | Fall | Walk | Run | Sit down | Stand up | Pick up |
|--------------|----------|------|------|-----|---------|----------|--------|
| Lie down     | 0.90     | 0.01 | 0.0  | 0.0 | 0.0     | 0.01     | 0.01   |
| Fall         | 0.01     | 0.90 | 0.0  | 0.0 | 0.0     | 0.07     | 0.02   |
| Walk         | 0.0      | 0.0  | 0.99 | 0.01| 0.0     | 0.0      | 0.0    |
| Run          | 0.0      | 0.0  | 0.02 | 0.95| 0.0     | 0.0      | 0.0    |
| Sit down     | 0.00     | 0.05 | 0.0  | 0.0 | 0.82    | 0.05     | 0.01   |
| Stand up     | 0.01     | 0.01 | 0.0  | 0.01| 0.01    | 0.01     | 0.94   |
| Pick up      | 0.01     | 0.02 | 0.0  | 0.01| 0.01    | 0.01     | 0.93   |

Fig. 3: Classification accuracy performance of the proposed model per subcarrier and per antenna (Ant.) over all activity classes. Overall accuracy is 92%.

3.5. Spatial Diversity Analysis

The MIMO system with OFDM modulation offers spatial-frequency diversity in CSI data collection. Fig. 3 shows the classification performance of \( (\psi_1(k_1), \ldots, \psi_M(k_M)) \) per subcarrier (30 subcarrier/antenna) of each antenna (3 antennas), for a single run over all activity classes with an overall accuracy of 92%. Fig. 3 shows that not all the antennas and subcarriers contribute to the performance of the model and some are redundant or have negative impact. From a spatial perspective, antenna 3 has a lower overall accuracy than the other antennas (subcarriers 3 to 30). However, all subcarriers in antennas 1 and 2 have a competitive performance. Hence, one may detect and prune the redundant/destructive antennas/subcarriers from the voting mechanism in (1). This approach can enhance the classification performance of a model. During our experiments, we have observed that training LiteHAR with captured signal from the first two antennas can increase its classification performance about 1%.

4. CONCLUSIONS

WiFi-based solutions for human activity recognition (HAR) offer privacy and non-line-of-sight activity detection capabilities. Most recent proposed methods, which have achieved high classification performance on benchmark datasets, use complicated deep learning solutions with very large number of trainable parameters. In order to have an affordable and practical HAR solution, particularly for implementation on resource-limited devices in a local setup, both classification accuracy and computational complexity of the model should be considered. In this paper, we have proposed a lightweight human activity recognition (LiteHAR) solution, which has a very competitive classification performance in comparison with the state-of-the-art methods and has very low computational complexity. Unlike most deep learning solutions, LiteHAR does not require training of a large number of parameters and can be implemented on resource limited devices without GPU access.
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