The Niceness of Unique Sink Orientations

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Abstract

Random Edge is the most natural randomized pivot rule for the simplex algorithm. Considerable progress has been made recently towards fully understanding its behavior. Back in 2001, Welzl introduced the concepts of reachmaps and niceness of Unique Sink Orientations (USO), in an effort to better understand the behavior of Random Edge. In this paper, we initiate the systematic study of these concepts. We settle the questions that were asked by Welzl about the niceness of (acyclic) USO. Niceness implies natural upper bounds for Random Edge and we provide evidence that these are tight or almost tight in many interesting cases. Moreover, we show that Random Edge is polynomial on at least \( n^{\Omega(2^n)} \) many (possibly cyclic) USO. As a bonus, we describe a derandomization of Random Edge which achieves the same asymptotic upper bounds with respect to niceness.

1 Introduction

One of the most prominent open questions in the theory of optimization is whether linear programs can be solved in strongly polynomial time. In particular, it is open whether there exists a pivot rule for the simplex method whose number of steps can be bounded by a polynomial function of the number of variables and constraints. For most deterministic pivot rules discussed in the literature, exponential lower bounds are known. The first such bound was established for Dantzig’s rule by Klee and Minty in their seminal 1972 paper [19]; this triggered a number of similar results for many other rules; only in 2011, Friedmann solved a longstanding open problem by giving a superpolynomial lower bound for Zadeh’s rule [8].

On the other hand, there exists a randomized pivot rule, called Random Facet, with an expected subexponential number of steps in the worst case. This bound was found independently by Kalai [17] as well as Matoušek, Sharir and Welzl [22] in 1992. Interestingly, the proofs employ only a small number of combinatorial properties of linear programs. As a consequence, the subexponential upper bound for the Random Facet pivot rule holds in a much more general abstract setting that encompasses many other (geometric) optimization problems for which strongly polynomial algorithms are still missing [22].

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This result sparked a lot of interest in abstract optimization frameworks that generalize linear programming. The most studied such framework, over the last 15 years, is that of unique sink orientations (USO). First described by Stickney and Watson already in 1978 as abstract models for P-matrix linear complementarity problems (PLCPs) [27], USO were revived by Szabó and Welzl in 2001 [28]. Subsequently, their structural and algorithmic properties were studied extensively ([25],[26],[21],[12],[7],[13],[16],[18],[15],[13]). In a nutshell, a USO is an orientation of the n-dimensional hypercube graph, with the property that there is a unique sink in every subgraph induced by a nonempty face. The algorithmic problem associated to a USO is that of finding the unique global sink, in an oracle model that allows us to query any given vertex for the orientations of its incident edges.

In recent years, USO have in particular been looked at in connection with another randomized pivot rule, namely Random Edge (RE for short). This is arguably the most natural randomized pivot rule for the simplex method, and it has an obvious interpretation also on USO: at every vertex pick an edge uniformly at random from the set of outgoing edges and let the other endpoint of this edge be the next vertex. The path formed constitutes a random walk. Ever since the subexponential bound for Random Facet was proved in 1992, researchers have tried to understand the performance of Random Edge. This turned out to be very difficult, though. Unlike Random Facet, the Random Edge algorithm is non-recursive, and tools for a successful analysis were simply missing. A superexponential lower bound on cyclic USO was shown by Morris in 2002 [24], but there was still hope that Random Edge might be much faster on acyclic USO (AUSO).

Only in 2006, a superpolynomial and subexponential lower bound for Random Edge on AUSO was found by Matoušek and Szabó [23] and, very recently, pushed further by Hansen and Zwick [16]. While these are not lower bounds for actual linear programs, the results demonstrate the usefulness of the USO framework: it is now clear that the known combinatorial properties of linear programming are not enough to show that Random Edge is fast. Note that, in 2011, Friedmann, Hansen and Zwick proved a subexponential lower bound for Random Edge on actual linear programs, “killing” yet another candidate for a polynomial-time pivot rule [9].

Still, the question remains open whether Random Edge also has a subexponential upper bound. As there already is a subexponential algorithm, a positive answer would not be an algorithmic breakthrough; however, as Random Edge is notoriously difficult to analyze, it might be a breakthrough in terms of novel techniques for analyzing this and other randomized algorithms. The currently best upper bound on AUSO is an exponential improvement over the previous (almost trivial) upper bounds, but the bound is still exponential, $1.8^n$ [15].

In this paper, we initiate the systematic study of concepts that are tailored to Random Edge on USO (not necessarily only AUSO). These concepts — reachmaps and niceness of USO — were introduced by Welzl [29] in a 2001 workshop as an interesting research direction. At that time, it seemed more promising to work on algorithms other than Random Edge; hence, this research direction remained unexplored and the problems posed by Welzl remained open. Now that the understanding of Random Edge on USO has advanced a lot we hope that these “old” concepts will finally prove useful, probably in connection with other techniques.
The reachmap of a vertex is the set of all the coordinates it can reach with a directed path, and a USO is \( i \)-nice if for every vertex there is a directed path of length at most \( i \) to another vertex with smaller reachmap. Welzl pointed out that the concept of niceness provides a natural upper bound for the Random Edge algorithm. Furthermore, he asks the following question: “Clearly every unique sink orientation of dimension \( n \) is \( n \)-nice. Can we do better? In particular what is the general niceness of acyclic unique sink orientations?”

We settle these questions, in Section 4, by proving that for AUSO \((n-2)\)-nice is tight, meaning that \((n-2)\) is an upper bound on the niceness of all AUSO and there are AUSO that are not \((n-3)\)-nice. For cyclic USO we argue that \( n \)-nice is tight. In Section 2 we give the relevant definitions and in Section 3 we show an upper bound of \( O(n^{i+1}) \) for the number of steps RE takes on an \( i \)-nice USO. In addition, we describe a derandomization of RE which also takes at most \( O(n^{i+1}) \) on an \( i \)-nice USO, thus matching the behavior of RE.

Finally, we include two brief notes in Section 3. The first argues that RE needs at most a quadratic number of steps in at least \( n^{\Theta(2^n)} \) many, possibly cyclic, USO. The second that RE can solve the AUSO instances that have been designed as lower bounds for other algorithms (e.g. Random Facet \([20],[10]\) or Bottom Antipodal \([25]\)) in polynomial time. All the necessary details for these two notes are provided in Appendices C and D respectively.

### 2 Preliminaries

We use the notation \([n] = \{1,\ldots, n\}\). Let \( Q^n = 2^n \) be the set of vertices of the \( n \)-dimensional hypercube. A vertex of the hypercube \( v \in Q^n \) is denoted by the set of coordinates it contains. The symmetric difference of two vertices, denoted as \( v \oplus u \), is the set of coordinates in which they differ. Now, let \( J \subseteq 2^n \) and \( v \in Q^n \). A face of the hypercube, \( F_{J,v} \), is defined as the set of vertices that are reached from \( v \) over the coordinates defined by any subset of \( J \), i.e. \( F_{J,v} = \{ u \in Q^n \mid v \oplus u \subseteq J \} \). The dimension of the face is \(|J| \). We call edges the faces of dimension 1, i.e. \( F_{\{j\},v} \), and vertices the faces of dimension 0. The faces of dimension \( n - 1 \) are called facets. For \( k \leq n \) we call a face of dimension \( k \) a \( k \)-face.

Let \( v, u \in Q^n \). By \(|v \oplus u|\) we denote the Hamming distance (size of the symmetric difference) of \( v \) and \( u \). Given \( v \in Q^n \), we define the neighborhood of \( v \) as \( N(v) = \{ u \in Q^n \mid |v \oplus u| = 1 \} \). Now, let \( \psi \) be an orientation of the edges of the \( n \)-dimensional hypercube. Let \( v, u \in Q^n \). The notation \( v \xrightarrow{\psi} u \) (w.r.t \( \psi \)) means that \( F_{\{j\},v} = \{ v, u \} \) and that the corresponding edge is oriented from \( v \) to \( u \) in \( \psi \). Sometimes we write \( v \to u \), when when the coordinate is irrelevant. An edge \( v \xrightarrow{\psi} u \) is forward if \( j \in J \) and otherwise we say it is backward.

We say that \( \psi \) is a Unique Sink Orientation (USO) if every non-empty face has a unique sink. In the rest we write \( n \)-USO to mean a USO over \( Q^n \). Here \( n \) is always used to mean the dimension of the corresponding USO. Consider a USO \( \psi \); we define its outmap \( s_\psi \), in the spirit of Szabó and Welzl \([25]\). The outmap is a function \( s_\psi : Q^n \to 2^n \), defined by \( s_\psi(v) = \{ j \in [n] \mid v \xrightarrow{\psi} v \oplus \{j\} \} \) for every \( v \in Q^n \). A sink of a face \( F_{J,v} \) is a vertex \( u \in F_{J,v} \), such that \( s_\psi(u) \cap J = \emptyset \). We mention the following lemma w.r.t. the outmap function.

**Lemma 1** \([28]\). For every USO \( \psi \), \( s_\psi \) is a bijection.
The algorithmic problem for a USO $\psi$ is to find the global sink, i.e. find $t \in Q^n$ such that $s_\psi(t) = \emptyset$. The computations take place in the vertex oracle model: We have an oracle that given a vertex $v \in Q^n$, returns $s_\psi(v)$ (vertex evaluation). This is the standard computational model in the USO literature and all the upper and lower bounds refer to it.

**Reachmap and niceness.** We are now ready to define the central concepts of this paper. Given vertices $v, u \in Q^n$ we write $v \xrightarrow{} u$ if there exists a directed path from $v$ to $u$ (in $\psi$). We use $d(v, u)$ to denote the length of the shortest directed path from $v$ to $u$; if there is no such path then we have $d(v, u) = \infty$ and otherwise we have $d(v, u) \geq |v \oplus u|$. The following lemma is well-known and easy to prove by induction on $|v \oplus u|$.

**Lemma 2.** For every USO $\psi$, let $F \subseteq Q^n$ be a face and $u$ the sink of this face. Then, for every vertex $v \in F$ we have $d(v, u) = |v \oplus u|$.

Subsequently, we define the reachmap $r_\psi : Q^n \to 2^n$, for every $v \in Q^n$, as:

$$r_\psi(v) = s_\psi(v) \cup \{ j \in [n] | \exists u \in Q^n \text{ s.t. } v \xrightarrow{} u \text{ and } j \in s_\psi(u) \}.$$  

Intuitively, the reachmap of a vertex contains all the coordinates that the vertex can reach with a directed path. We say that vertex $v \in Q^n$ is $i$-covered by vertex $u \in Q^n$ if $d(v, u) \leq i$ and $r_\psi(u) \subset r_\psi(v)$ (proper inclusion). Then, we say that a USO $\psi$ is $i$-nice if every vertex $v \in Q^n$ (except the global sink) is $i$-covered by some vertex $u \in Q^n$. Of course, every $n$-USO $\psi$ is $n$-nice since every vertex $v$ is $n$-covered by the sink $t$. Moreover, $r_\psi(v) \supseteq v \oplus t$, for every vertex $v \in Q^n$.

It is not difficult to observe that every USO in 1 or 2 dimensions is 1-nice, but the situation changes in 3 dimensions. Consider the illustration in the figure below.

![Figure 1](image)

**Figure 1:** Examples of 3-dimensional USO: (a) Klee-Minty, which is 1-nice. (b) The only 2-nice 3-dimensional AUSO which is not 1-nice. (c) The only cyclic USO in 3 dimensions, which is 3-nice.

Let us note that the AUSO in Figure (b) is the largest AUSO which is not $(n-2)$-nice. As we prove in Theorem 8, every $n$-AUSO with $n \geq 4$ is $(n-2)$-nice.

**Algorithmic properties of the reachmap.** Our focus lies mostly on the concept of niceness. Nevertheless, we briefly discuss some of the algorithmic properties of the reachmap here.

It was proved by the authors, in [13], that when given an AUSO $\psi$ described succinctly by a Boolean circuit, and two vertices $s$ and $t$, deciding if $s \xrightarrow{} t$ is $PSPACE$-complete. More recently, Fearnley and Savani [6] proved that deciding whether the Bottom Antipodal algorithm (this is the algorithm that from a
vertex \(v\) jumps to vertex \(v \oplus s_\psi(v)\), started at vertex \(v\) will ever encounter a vertex \(v'\) such that \(j \in s_\psi(v')\), for a given coordinate \(j\), is \(PSPACE\)-complete. This line of work was initiated in [1] and further developed in [4] and [5] and aims at understanding the computational power of pivot algorithms [6]. Below, we provide a related theorem: it is \(PSPACE\)-complete to decide if a coordinate \(j\) is in the reachmap of a given vertex in an AUSO. It is, thus, computationally hard to discover the reachmap of a vertex.

**Theorem 3.** Let \(\psi\) be an \(n\)-AUSO (described succinctly by a Boolean circuit), \(v \in Q^n\) and \(j \in [n]\). It is \(PSPACE\)-complete to decide whether \(j \in r_\psi(v)\).

The theorem follows from the results of [13] that we mention above. A proof is included in Appendix B. Finally, we want to note that it is natural to upper bound algorithms on AUSO by the reachmap of the starting vertex. Any reasonable path-following algorithm that solves an AUSO \(\psi\) in \(c^n\) steps, for some constant \(c\), can be bounded by \(c^{r_\psi(s)}\) where \(s\) is the starting vertex. The reason is that the algorithm will be contained in the cube \(F_{r_\psi(s), s}\) of dimension \(|r_\psi(s)|\). Moreover, we claim that this is also possible for algorithms that are not path-following. As an example we give in Appendix E a variant of the Fibonacci Seesaw algorithm of [28] that runs in time \(c^{r_\psi(s)}\) for some \(c < \phi\) (the golden ratio).

### 3 Random Edge on \(i\)-nice USO

In this section we describe how RE behaves on \(i\)-nice USO. We give a natural upper bound and argue that it is tight or almost tight in many situations. In addition, we give a simple derandomization of RE, which asymptotically achieves the same upper bound. Firstly, we consider the following natural upper bound.

**Theorem 4.** Started at any vertex of an \(i\)-nice USO, Random Edge will perform an expected number of at most \(O(n^{i+1})\) steps.

**Proof.** For every vertex \(v\), there is a directed path of length at most \(i\) to a target \(t(v)\), some fixed vertex of smaller reachmap. At every step, we either reduce the distance to the current target (if we happen to choose the right edge), or we start over with a new vertex and a new target. The expected time it takes to reach some target vertex can be bounded by the expected time to reach state 0 in the following Markov chain with states 0, 1, \ldots, \(i\) (representing distance to the current target): at state \(k > 0\), advance to state \(k - 1\) with probability \(1/n\), and fall back to state \(i\) with probability \((n - 1)/n\). A simple inductive proof shows that state 0 is reached after an expected number of \(\sum_{k=1}^{i} n^k = O(n^i)\) steps. Hence, after this expected number of steps, we reduce the reachmap size, and as we have to do this at most \(n\) times, the bound follows.

Already, we can give some first evidence on the usefulness of niceness for analyzing RE: Decomposable orientations have been studied extensively in literature. The fact that RE terminates in \(O(n^2)\) steps on them has been known at least since the work of Williamson-Hoke [30]. Let a coordinate be *combed* if all edges on this coordinate are directed the same way. Then, a cube orientation is *decomposable* if in every face of the cube there is a combed coordinate. The class of decomposable orientations, known to be AUSO, contains the Klee-Minty...
cube \([10]\) (defined combinatorially in \([26]\)). It is straightforward to argue that such orientations are 1-nice and, thus, our upper bound from Theorem 4 is also quadratic. Moreover, quadratic lower bounds have been proved for the behavior of RE on Klee-Minty cubes \([3]\). We conclude that, for 1-nice USO, the upper bound in Theorem 4 is optimal.

**Counting 1-nice.** We have mentioned that the class of decomposable USO are 1-nice. This class is the previously known largest class of USO, where Random Edge is polynomial. The number of decomposable USO is \(2^\Theta(2^n)\) (a proof for this is included in the full version). We can now argue that the class of 1-nice USO is much larger than the class of decomposable ones, and also contains cyclic USO. To achieve the lower bound we use the same technique that Matoušek \([21]\) used to give a lower bound on the number of all USO. The upper bound is proved also in \([21]\). Thus, we have the number of 1-nice USO is asymptotically (in the exponent) the same as of all USO.

**Theorem 5.** The number of 1-nice \(n\)-dimensional USO is \(n^{\Theta(2^n)}\).

**Proof of Theorem 5.** Consider the following inductive construction. Let \(A_1\) be any 1-dimensional USO. Then, we construct \(A_2\) by taking any 1-dimensional USO \(A'_1\) and directing all edges on coordinate 2 towards \(A_1\). In general, to construct \(A_{k+1}\): we take \(A_k\) and put antipodally any \(k\)-dimensional USO \(A'_k\). Then, we direct all edges on coordinate \((k + 1)\) towards \(A_k\). This is safe by Lemma 3. This construction satisfies the following property: for every vertex, the minimal face that contains this vertex and the global sink has a combed coordinate. We call such a USO “target-combed”. It constitutes a generalization of decomposable USO. An illustration appears in Figure 7.

![Figure 2: A target-combed \(n\)-USO. The two larger ellipsoids represent the two antipodal facets \(A_{n-1}\) and \(A'_{n-1}\) and, similarly, for the smaller ones. The combed coordinates are highlighted. The gray subcubes can be oriented by any USO.](image)

The construction is 1-nice since for every vertex (except the sink) there is an outgoing coordinate that can never be reached again. At every iteration step from \(k\) to \(k + 1\) we can embed, in one of the two antipodal \(k\)-faces, any USO. Thus, we can use the lower bounds of \([21]\), that give us a \(\left(\frac{\epsilon}{2}\right)^{2^{k-1}}\) (assuming \(k \geq 2\)) lower bound for a \(k\)-face. Summing up, we get:

\[
uso_{1\text{nice}}(n) \geq \sum_{k=1}^{n-1} uso(k) > uso(n - 1) = \left(\frac{n - 1}{e}\right)^{2^{n-2}}
\]

where \(uso_{1\text{nice}}(n)\) and \(uso(n)\) is the number of \(n\)-dimensional 1-nice USO and general USO respectively. Thus, \(uso_{1\text{nice}}(n) = n^{\Theta(2^n)}\). The upper bound in the
statement of the theorem is from the upper bound on the number of all USO, by Matoušek [21].

The niceness of known lower bound constructions. As further motivation for the study of niceness of USO, we want to mention that RE can solve the AUSO instances that were designed as lower bounds for other algorithms in polynomial time. This is because of provable upper bounds on the niceness of those constructions. With similar arguments, upper bounds on the niceness of the AUSO that serve as subexponential lower bounds for RE can be shown; thus, RE has upper bounds on these constructions that are almost matching to the lower bounds. The upper bound for RE on the cyclic USO of Morris [24] is asymptotically matching the lower bound. We summarize the relevant information in the following table and describe the details on how to obtain it in Appendix D.

| Algorithm        | Reference | Lower bound | Niceness | RE Upper bound |
|------------------|-----------|-------------|----------|----------------|
| Random Facet     | [20, 10]  | $2^{O(\sqrt{n})}$ | 1        | $O(n^2)$       |
| Bottom Antipodal | [26]      | $\Omega(\sqrt{2n})$ | 2        | $O(n^3)$       |
| RE acyclic       | [23]      | $2^{\Omega(n^{1/3})}$ | $n^{1/3}$ | $2^{O(n^{1/3}\log n)}$ |
| RE acyclic       | [16]      | $2^{\Omega(\sqrt{n \log n})}$ | $\sqrt{n}$ | $2^{O(\sqrt{n \log n})}$ |
| RE cyclic        | [24]      | $n^{-1/2}$ | $\frac{n-1}{2}$ | $n^{\Omega(n)}$ |

A derandomization of Random Edge Consider the join operation. Given two vertices $u, v$, $\text{join}(u, v)$ is a vertex $w$ such that $u \sim w$ and $v \sim w$. We can compute $\text{join}(u, v)$ as follows: by Lemma 1, there must be a coordinate, say $j$, such that $j \in s_{\psi}(u) \oplus s_{\psi}(v)$. Assume, w.l.o.g., that $j \in s_{\psi}(u)$. Consider the neighbor $u'$ of $u$ such that $u \stackrel{j}{\rightarrow} u'$. Recursively compute $\text{join}(u', v)$. It can be seen by induction on $|u \oplus v|$ that the join operation takes $O(n)$ time. Similarly, we talk about a join of a set $S$ of vertices. A join $(S)$ is a vertex $w$ such that ever vertex in $S$ has a path to it. We can compute join$(S)$ by iteratively joining all the vertices in $S$.

Furthermore, let $N^+(v) = \{ u \in N(v) | v \rightarrow u \}$ denote the set of out-neighbors of a vertex $v$. In the subsequent lemma, we argue that the vertices in $N^+(v)$ can be joined with linearly many vertex evaluations.

Lemma 6. Let $\psi$ be an $n$-USO and $v \in Q^n$ a vertex. There is an algorithm that joins the vertices in $N^+(v)$ with $|s_{\psi}(u)|$ many vertex evaluations.

Proof. First, we evaluate all the vertices in $N^+(v)$. We maintain a set of active vertices $AV$ and a set of active coordinates $AC$. Initialize $AV = N^+(v)$ and $AC = s_{\psi}(v)$. The algorithm keeps the following invariants: every vertex that gets removed from $AV$ has a path to some vertex in $AV$; also for every vertex $u$ s.t. $v \rightarrow u$, $u \in AV$ if and only if $l \in AC$.

Then, for each $u \in AV$: for each $l \in AC$: if $l \notin s_{\psi}(u)$ and $\{l\} \neq (u \oplus v)$ then we update $AC \leftarrow AC \setminus \{l\}$ and $AV \leftarrow AV \setminus \{v \oplus \{l\}\}$. See Figure 3.

If in the above loop the vertex $u$ is the sink of the face $F_{AC,u}$ then terminate and return $v' = u$. Of course, in this case every vertex in $AV$ has a path to $u$. Otherwise the loop will terminate when there is no coordinate in $AC$ that satisfies the conditions above. In this case we have that $\forall u \in AV$, $u$ is the source.
We have $u, w \in AV$, $l \in AC$, $l \not\in s_\psi(u)$ and \{l\} $\neq (v \oplus u)$. Thus, the edge $F_{j,w}$ has to be outgoing for $w$. Hence, $w \leadsto u$ and the algorithm removes $w$ from $AV$ and $l$ from $AC$.

of the face $F_{AC\setminus(u\oplus v),w}$. That is, it is the source of the face spanned by the vertex and all the active coordinates $AC$ except the one that connects it to $v$. In this case, we return the vertex $v' = (v \oplus AC)$. We have that every vertex in $AV$ has a path to $v'$: this is because in any USO the source has a path to every vertex (this can be proved similarly to Lemma 2).

Using Lemma 6, we can now argue that there exists a derandomization of Random Edge that asymptotically matches the upper bound of Theorem 4.

Theorem 7. There is a deterministic algorithm that finds the sink of an $i$-nice $n$-USO $\psi$ with $O(n^{i+1})$ vertex evaluations.

Proof. Let $v$ be the current vertex. Consider the set $R_i \subseteq 2^n$ of vertices that are reachable along directed paths of length at most $i$ from $v$. Since $\psi$ is $i$-nice, we know that at least one of them has strictly smaller reachmap. In particular, any vertex reachable from all the vertices in $R_i$ has a smaller reachmap. Thus, we compute a join of all the vertices in $R_i$.

Consider the set $R_{i-1}$. The size of $R_{i-1} - 1$ is bounded by $|R_{i-1}| \leq \sum_{k=0}^{i-1} \binom{n}{k} \leq \sum_{k=0}^{i-1} n^k$ and, thus, $|R_{i-1}| = O(n^{i-1})$. Every vertex in $R_i$ can be reached in one step from some vertex in $R_{i-1}$. Assume that none of the vertices in $R_{i-1}$ is the sink; otherwise, the algorithm is finished. Then, for every vertex $v \in R_{i-1}$ we join $N^+(v)$ with the algorithm from Lemma 6 with $O(n)$ vertex evaluations. Therefore, with $O(n^i)$ vertex evaluations we have a set $S$ of $O(n^{i-1})$ many vertices and each $v' \in S$ is a join of $N^+(v)$ for some vertex $v \in R_{i-1}$.

The next step is to join all the vertices in set $S$, using the algorithm at the beginning of the current section, which takes $O(n)$ for each pair of vertices. Hence, the whole procedure will take an additional $O(n^i)$ vertex evaluations. The result is a vertex $u$ that joins all the vertices in $R_i$ and thus $i$-covers $v$. Because the size of the reachmap decreases by at least one in each round, we conclude that this algorithm will take at most $O(n^{i+1})$ steps.

Finally, note that to achieve this upper bound we do not need to know that the input USO is $i$-nice. Instead, we can iterate through the different values of $i = 1, 2, \ldots$ without changing the asymptotic behavior of the algorithm. \hfill \triangle

4 Bounds on niceness

In this section we answer the questions originally posed in [29] by providing matching upper and lower bounds on the niceness of USO and AUSO.

For cyclic USO, the cubes designed by Morris as a lower bound for the behavior of RE [24] are $n$-nice and, hence, match the trivial upper bound. For
the sake of conserving space, we only sketch the proof here and give explicitly an $n$-nice cyclic USO construction in Appendix A.

The idea for such a construction is quite simple, intuitively. Let $\psi$ be a cyclic $n$-USO over $Q^n$ that contains a directed cycle such that the edges that participate span all the coordinates. Then, every vertex $v$ on the cycle has $r_\psi(v) = [n]$. Now consider the sink $t$ and assume the $n$ vertices in $N(t)$ participate in the cycle. By Lemma 2, every vertex has a path to $t$. This path has to go through one of the vertices in $N(t)$. It follows that every $v \in Q^n \setminus \{t\}$ has $r_v(v) = [n]$. Therefore, the vertex antipodal from $t$ is only $n$-covered (by $t$).

The Morris cyclic USO satisfies the properties described above and, thus, is $n$-nice. An example in 3 dimensions appears in Figure 1; this USO satisfies the properties we explain above. For the rest of this section, we will turn our attention to AUSO.

4.1 An upper bound for AUSO

We prove an upper bound on the niceness of AUSO which, as we will see in the next section, is tight. We utilize the concept of Completely Unimodal Numberings (CUN), which was studied by Williamson-Hoke [30] and Hammer et al. [14]. To the best of our knowledge, this is the first time CUN is used to prove structural results for AUSO. A CUN on the hypercube $Q^n$ means that there is a bijective function $\phi: Q^n \to \{0, \ldots, 2^n - 1\}$ such that in every face $F$ there is exactly one vertex $v$ such that $\phi(v) < \phi(u)$, for every $u \in N(v) \cap F$. It is known, e.g. from [30], that for every AUSO there is a corresponding CUN, which can be constructed by topologically sorting the AUSO.

In the proof of the theorem below we will use the following notation: $w^k$ is the vertex that has $\phi(w^k) = k$, w.r.t. some fixed CUN $\phi$. An easy, but crucial observation concerns the three lowest-numbered vertices $w_0, w_1, w_2$. Of course, $w_1 \rightarrow w_0$ (where $w_0$ is the global sink); otherwise, $w_1$ would have been a second global minimum. Moreover, $w_2 \rightarrow w_j$ for exactly one $j \in \{0, 1\}$. It follows, that both $w_1$ and $w_2$ are facet sinks. We are ready to state and prove the following theorem.

Theorem 8. Any $n$-AUSO, with $n \geq 4$, is $(n-2)$-nice.

Consider the vertices $w_0$ and $w_1$ and let $e$ be the edge that connects them. Let $w \in e$ be the unique out-neighbor of $w_2$ and $w'$ the other vertex in $e$. W.l.o.g. assume $w = \emptyset$, $w' = \{1\}$ and $w^2 = \{2\}$. The situation can be depicted as:

$$
\begin{array}{c}
w = \emptyset \\
w_2 = \{2\} \\
w' = \{1\}
\end{array}
$$

These three vertices have no outgoing edges to other vertices. Their outmaps and reachmaps are summarized in the table below.

| vertex | outmap | reachmap | is sink of the facet |
|--------|--------|----------|---------------------|
| $w = \emptyset$ | $\subseteq \{1\}$ | $\subseteq \{1\}$ | $F_{[n]\setminus\{1\},w}$ |
| $w' = \{1\}$ | $\subseteq \{1\}$ | $\subseteq \{1\}$ | $F_{[n]\setminus\{1\},w'}$ |
| $w^2 = \{2\}$ | $\subseteq \{1, 2\}$ | $\subseteq \{1, 2\}$ | $F_{[n]\setminus\{2\},w^2}$ |

More precisely, the reachmap of $w^2$ is $\{2\}$ if $w = w^0$, and it is $\{1, 2\}$ if $w = w^1$. Theorem 8. Any $n$-AUSO, with $n \geq 4$, is $(n-2)$-nice.
Lemma 9. With \( w, w' \) as above, let \( v \in \mathbb{Q}^n \setminus \{w^0, [n]\} \). Then \( v \) is \((n - 2)\)-covered by some vertex in \( \{w, w', w^2\} \).

Proof. Vertex \( w^1 \) is covered by \( w^0 \) and \( w^2 \) by \( w^0 \) or \( w^1 \), so assume that \( v \) is some other vertex.

If \( v \) neither contains 1 nor 2, then \( v \) is in the facet \( F_{[n]\setminus\{1\}, w} \). Hence, 
\[
d(v, w) = |v \cup w| \leq n - 2.
\]
This is because \( F_{[n]\setminus\{1\}, w} \) is \((n - 1)\)-dimensional and 
\( 2 \notin v \). Any coordinate that is part of the corresponding path is in the reachmap of \( v \) but not of \( w \) (whose reachmap is a subset of \( \{1\} \)). Hence, \( v \) is \((n - 2)\)-covered by \( w \).

If \( v \) contains 1, then \( v \) is in the facet \( F_{[n]\setminus\{1\}, w'} \), and \( |v \cup w'| \leq n - 2 \) since \( v \neq [n] \). As before, this implies that \( v \) is \((n - 2)\)-covered by the sink \( w' \) of the facet in question.

Finally, if \( v \) contains 2 but not 1, then \( v \) is in the face \( F_{[n]\setminus\{1,2\}, w^2} \), and 
\[
d(v, w^2) \leq n - 2.
\]
Again, any coordinate on a directed path from \( v \) to \( w^2 \) within this face proves that \( v \) is \((n - 2)\)-covered by the sink \( w^k \) of the face.

It remains to \((n - 2)\)-cover the vertex \( v = [n] \). Let \( m > 2 \) be the smallest index such that \( w^m \) is not a neighbor of \( w \), and assume w.l.o.g. that \( w^k = \{k\}, 3 \leq k < m \). We have \( w^k \to w \) for all these \( k \) by the vertex ordering. Furthermore, all other edges incident to \( w^k \) are incoming. We conclude that each \( w^k, 3 \leq k < m \) has outmap equal to \( \{k\} \) and, hence, is a facet sink. The reachmap of each such \( w^k \) is \( \subseteq \{1, k\} \). The situation is depicted as:

\[
\begin{array}{cccc}
& & & \\
& & w = \emptyset & \\
& w^{m-1} = \{m - 1\} & \ldots & w^2 = \{2\} & w' = \{1\} \\
& w^m = \{k, j\} & \\
\end{array}
\]

Since \( w^m \) has at least one out-neighbor in \( \{w', w^2, \ldots, w^{m-1}\} \), we know that \( w^m = \{k, j\} \) for some \( k < j \in [n] \). Moreover, the vertex ordering again implies that the outgoing edges of \( w^m \) are exactly the ones to its (at most two) neighbors among \( w', w^2, \ldots, w^{m-1} \). Taking their reachmaps into account, we conclude that the reachmap of \( w^m \) is \( \subseteq \{k, j, 1\} \).

Lemma 10. With \( w^m \) as above and \( n \geq 4 \), \( v = [n] \) is \((n - 2)\)-covered by \( w^m \).

Proof. We first observe that \( w^m \) is the sink of the face \( F_{[n]\setminus\{k,j\}, w^m} \), since its outmap is \( \subseteq \{k, j\} \). Vertex \( v = [n] \) is contained in this \((n - 2)\)-face, hence there exists a directed path of length \( d(v, w^m) = n - 2 \) from \( v \) to \( w^m \) in this face. Since \( n \geq 4 \), the path spans at least two coordinates and thus at least one of them is different from 1. This coordinate proves that \( v \) is \((n - 2)\)-covered by \( w^m \).
4.2 A matching lower bound for AUSO

We prove a lower bound on the niceness of acyclic USO that matches the upper bound of Theorem 8. It follows (Corollary 6, [25]) from the Hypersink Reorientation Lemma (Appendix D) that in a USO we can flip any edge if the outmaps of the two vertices incident to it are the same (except the connecting coordinate). This gives rise to a particular family of USO, the Flip-Matching Orientations (FMO): those arise when we start with a uniform orientation, e.g. all edges are forward, and we flip the edges of an arbitrary matching. FMO have been studied in [25] and [23].

Theorem 11. There exists an $n$-AUSO $\psi$ which is not $i$-nice, for $i < n-2$.

Proof. Let $\psi_U$ be the forward uniform orientation, i.e. the orientation where all edges are forward. We explain how to construct $\psi$, our target orientation starting from $\psi_U$. With $Q^n_k$ we denote the set of vertices that contain $k$ coordinates, i.e. $|Q^n_k| = \binom{n}{k}$. We assume $n \geq 4$. The idea here is to construct an AUSO that has its source at $\emptyset$ and has the property that every vertex in $\bigcup_{i=0}^{n-3} Q^n_i$ has a full-dimensional reachmap.

Pick $v \in Q^n_{n-3}$ and assume w.l.o.g. that $v = [n] \setminus \{1, 2, 3\}$. Consider the 2-dimensional face $F_{\{1,2\},v}$ and direct the edges in this face backwards. This is the first step of the construction and it results in $s_\psi(v) = \{3\}$.

For the second step, consider the vertex $v' = [n] \setminus \{2\}$. We will flip $n-3$ edges in order to create a path starting at $v'$. First, we flip edge $F_{\{4\},[n]\setminus\{2\}}$. Then, for all $k \in \{4, \ldots, n-1\}$ we flip the edge $F_{\{k+1\},[n]\setminus\{k\}}$. This creates the path depicted in Figure 4.

![Figure 4: An illustration of the path starting at $v'$. The dashed edges are flipped backwards.](image)

Claim 12. $\psi$ is a USO.

The first step of the construction is to flip the four edges in $F_{\{1,2\},v}$. This is safe by considering that we first flip the two edges on coordinate 1; then, it is also safe to flip the two edges on coordinate 2. All the edges reversed at the second step of the construction (Figure 4) are between vertices in $Q^n_{n-1}$ and $Q^n_{n-2}$, and, in addition those vertices are not neighbors to each other. Furthermore, all the edges reversed at the third step of the construction are on coordinate 3 and between vertices in $Q^n_{n-3}$ and $Q^n_{n-4}$. Thus, all these edge flips are safe. Note however that edge flips do not necessarily maintain acyclicity (e.g. the cyclic USO in Figure 1c is an FMO); we have to verify acyclicity in a different way.

Claim 13. There is no cycle in $\psi$. 

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Clearly, a cycle has at least one backward and one forward edge in every
coordinate it contains. Thus, there cannot be a cycle that involves coordinate 3
because no backward edge on a different coordinate, has a path connecting it to
a backward edge on coordinate 3.

Consider the facet \( F_{\{n\}\{3\},v} \) and the USO \( \psi' \), resulting from restricting \( \psi \)
to the aforementioned facet. We can notice that \( \psi' \) is an FMO and the only
backward edges are the ones attached to the path illustrated in Figure 4. Thus,
a cycle has to use a part of this path. However, this path cannot be part of any
cycles: a vertex on the higher level (vertices in \( Q_{n-1}^n \)) of the path has only two
outgoing edges; one to the sink \( \{n\} \) and one to the next vertex on the path. A
vertex on the lower level \( Q_{n-2}^n \) has only one outgoing edge to the next vertex on
the path. Also, the last vertex of the path \( \{n\} \setminus \{n-1,n\} \) has only one outgoing
edge to \( \{n\} \setminus \{n\} \) which has only one outgoing edge to the sink \( \{n\} \).

The fact that the facet \( F_{\{n\}\{3\},v} \) has no cycle follows from the observation
that there are backwards edges only on two coordinates which is not enough for
the creation of a cycle (remember that in a USO a cycle needs to span at least
three coordinates). This concludes the proof of Claim 13, which, combined with
Claim 12, results in \( \psi \) being an AUSO.

**Claim 14.** Every vertex in \( \bigcup_{i=0}^{n-3} Q_i^n \) has a full-dimensional reachmap.

Firstly, we argue that \( v \) has \( r_\psi(v) = \{n\} \). We have \( s_\psi(v) = \{3\} \subset r_\psi(v) \).
Then, \( v \xrightarrow{3} u = \{n\} \setminus \{1,2\} \) and \( u \) has \( s_\psi(u) = \{1,2\} \subset r_\psi(v) \).
Vertex \( u \) is such that \( u \xrightarrow{1} v' = \{n\} \setminus \{2\} \): \( v' \) is the beginning of the path described in Figure 4. The
backwards edges on this path span every coordinate in \( \{4,\ldots,n\} \). This implies
that \( r_\psi(v') = \{2,4,\ldots,n\} \) and, since there is a path from \( v \) to \( v' \), \( r_\psi(v') \subseteq r_\psi(v) \).
Combined with the above, we have that \( r_\psi(v) = \{n\} \).

Secondly, we argue that \( \forall u \in Q_{n-3}^n \), \( r_\psi(u) = \{n\} \). Vertex \( u \) is the sink of the
facet \( F_{\{n\}\{3\},v} \). It follows that every vertex in \( Q_{n-3}^n \cap F_{\{n\}\{3\},v} \) has a path to
\( v \) and thus has full dimensional reachmap. The vertices in \( U_3 \) (defined earlier),
which are the rest of the vertices in \( Q_{n-3}^n \), have backward edges on coordinate
3 and thus have paths to \( F_{\{n\}\{3\},v} \). It follows that vertices in \( U_3 \) also have full
dimensional reachmaps.

Any vertex in \( \bigcup_{i=0}^{n-3} Q_i^n \) has a path to a vertex in \( Q_{n-3}^n \) since there are
outgoing forward edges incident to any vertex in \( \psi \) (except the global sink at
\( \{n\} \)). Thus, we have that \( \forall u \in \bigcup_{i=0}^{n-3} Q_i^n \), \( r_\psi(u) = \{n\} \) which proves the claim.

Finally, we combine the three Claims to conclude that the lowest vertex \( \emptyset \)
can only be covered by a vertex in \( Q_{n-2}^n \). Therefore, \( \psi \) is not \( i \)-nice for any \( i < n - 2 \), which proves the theorem. We include an example construction, for
five dimensions, in Figure 5 below.

### 5 Conclusions

In this paper we study the reachmaps and niceness of USO, concepts introduced
by Welzl [29] in 2001. The questions that Welzl originally posed are now answered
and the concepts explored further. We believe that these tools, or related ones,
will prove useful in finally closing the gap between the lower and upper bounds
known for RE. This will happen with either exponential lower bounds or with
subexponential upper bounds. It is worth mentioning that these concepts are
Figure 5: An example construction in 5 dimensions. Only the backward edges are noted. Each coordinate is labeled over a backward edge. The 5-dimensional cube is broken in 2-faces of coordinates 1,2. All the vertices in $Q_n^3$ are noted with dots. Also, $v$ is explicitly noted.

not only relevant for USO, but could also be defined on generalizations of USO, such as Grid USO [11] or Unimodal Numberings [13].

The authors of [16] define the concept of a $(k,\ell)$-layered AUSO and use it to argue that their lower bounds are optimal under the method they use. Their concept is a generalization of niceness (on AUSO) but the exact relationship remains to be discovered. They pose the following questions: Are there AUSO that are not $O\left(\sqrt{n} \log n\right)$-layered? Are there small constants $c, d$ such that all AUSO are $(cn, dn/\log n)$-layered? We believe that the techniques of our proofs from Theorems 8 and 11 may be fruitful for answering these questions.

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An $n$-nice lower bound for cyclic USO

In this section we will provide a lower bound for the niceness of cyclic USO. The result is summarized in Theorem 16. First, consider the following lemma which follows easily from the definition of reachmap.

**Lemma 15.** Consider an $n$-dimensional USO $\psi$ and let $C \subset Q_n$ be a cycle that spans every coordinate. Then, every vertex $v \in C$ has $r_\psi(v) = [n]$.

Note that as we have discussed earlier the Morris USO is $n$-nice. Here we describe a much simpler USO, which is also and FMO. The reason we think this is interesting is because it demonstrates that there are USO with large niceness, as in the example below, which RE can solve fast. It should be clear by the construction below that RE will can solve it with polynomial steps. In contrast, for Morris $n$-nice USO it will take more steps than the number of vertices.

**Theorem 16.** There exists a cyclic USO $\psi$ which is not $i$-nice for $i < n$.

**Proof.** We describe a family of cyclic FMO that contain a cycle which spans all the coordinates. To achieve this we start with the forward uniform orientation $\psi_U$ and flip $n$ edges to create a cycle $C$ with $2n$ vertices. As explained in Section 4, the trick is to involve all the vertices in $Q_n^{-1}$. We can construct the desired cycle as follows: Of course, we can create this cycle by flipping exactly $n$ edges, one in each coordinate. This concludes the construction of $\psi$, our target USO. Thus, $C$ spans all coordinates and by the lemma above, every vertex $v \in C$, has $r_\psi(v) = [n]$.

**Claim 1.** We have $r_\psi(v) = [n], \forall v \in Q_n \setminus [n]$.

We have that $\psi$ is an FMO and all backward edges are incident to vertices in $Q_n$, for $k = n - 2, n - 1$. Thus, we have that all vertices in $\bigcup_{k=0}^{n-3} Q_n^k$ are only incident to forward edges. Every vertex in $Q_n^{n-2}$ has at least one forward edge to a vertex in $Q_n^{n-1}$. We already argued that all vertices in $Q_n^{n-1}$ have full dimensional reachmaps. Therefore, every vertex in $\bigcup_{i=0}^{n-2} Q_n^i$ has a full dimensional reachmap too.

By the claim above, it follows that the only vertex that $i$-covers any other vertex $v$ is $[n]$. In particular, we have that the vertex $\emptyset$ is only $n$-covered. This concludes the proof of the theorem.

Note that the 3-dimensional cyclic USO (depicted in Figure 1c) is also an instance of the construction suggested in this section.

Reachmap and PSPACE

In [13], the authors prove that the following problem is $PSPACE$-complete. AUSO-Accessibility: The input is a Boolean circuit $C_\psi$ with $n$ inputs and $n$ outputs that represents (the outmap of) a USO, two vertices $s, t \in Q^n$ and the question is if there is a directed path from $s$ to $t$. We reduce from the problem for the proof of Theorem 3.

---

1 The size of the circuit is polynomial in the $n$. 

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Proof of Theorem 3. We provide a reduction from AUSO-Accessibility to prove \( PSPACE \)-hardness. The \( PSPACE \) upper bound follows standard arguments that can be found in [13]. The input is \( C_\psi \) and it represents an \( n \)-dimensional AUSO. We construct an \((n+1)\)-dimensional USO \( \psi' \) based on this.

First, all the edges at coordinate \( n+1 \) backwards uniform, with one exception that we discuss below. We embed the orientation \( \psi \) in the faces \( A \) and \( B \) illustrated in the figure below. We flip the edge \( F_{(n+1),t} \) which is safe as the outmaps of the two vertices involved differ only in the connecting coordinate. An illustration of the construction appears in Figure 6.

![Figure 6: An illustration of the construction. The vertices \( s \) and \( t \) are the ones from the input of the AUSO-Accessibility instance. The flipped edge appears dashed in the figure.](image)

This defines \( \psi' \). Consider the vertex \( s \cup \{n+2\} \). We have that \( \{n+1\} \in r_\psi(s) \) if and only if there is a path \( s \leadsto t \).

\[ \square \]

C Counting 1-nice and decomposable USO

In this section, we give the proof of Theorem 5 which we omitted from the main body. Afterwards, we argue about the number of decomposable USO in Theorem 2.

Proof of Theorem 5. Consider the following inductive construction. Let \( A_1 \) be any 1-dimensional USO. Then, we construct \( A_2 \) by taking any 1-dimensional USO \( A'_1 \) and directing all edges on coordinate 2 towards \( A_1 \). In general, to construct \( A_{k+1} \): we take \( A_k \) and put antipodally any \( k \)-dimensional USO \( A'_k \). Then, we direct all edges on coordinate \((k+1)\) towards \( A_k \). This is safe by Lemma 3. This construction satisfies the following property: for every vertex, the minimal face that contains this vertex and the global sink has a combed coordinate. We call such a USO “target-combed”. It constitutes a generalization of decomposable USO. An illustration appears in Figure 7.

The construction is 1-nice since for every vertex (except the sink) there is an outgoing coordinate that can never be reached again. At every iteration step from \( k \) to \( k+1 \) we can embed, in one of the two antipodal \( k \)-faces, any USO.
Figure 7: A target-combed \( n \)-USO. The two larger ellipsoids represent the two antipodal facets \( A_{n-1} \) and \( A'_{n-1} \) and, similarly, for the smaller ones. The combed coordinates are highlighted. The gray subcubes can be oriented by any USO.

Thus, we can use the lower bounds of \([21]\), that give us a \( \left( \frac{k}{2} \right)^{2^{k-1}} \) (assuming \( k \geq 2 \)) lower bound for a \( k \)-face. Summing up, we get:

\[
uso_{1nice}(n) \geq \sum_{k=1}^{n-1} uso(k) > uso(n-1) = \left( \frac{n-1}{e} \right)^{2^{n-2}}
\]

where \( uso_{1nice}(n) \) and \( uso(n) \) is the number of \( n \)-dimensional 1-nice USO and general USO respectively. Thus, \( uso_{1nice}(n) = n^{\Omega(2^n)} \). The upper bound in the statement of the theorem is from the upper bound on the number of all USO, by Matoušek \([21]\).

In addition, we provide a theorem on the number of decomposable USO. To the best of our knowledge, an explicit counting of those has not appeared in literature.

**Theorem 2.** The number of decomposable USO is \( 2^{\Theta(2^n)} \).

**Proof.** Firstly, we analyze the following recurrence relation and then we explain how it is derived from counting the number of decomposable USO. Let

\[
F(n) = P(n) \cdot F(n-1)^2, \quad n > 0,
\]

where \( P \) is some positive function defined on the positive integers, and \( F(0) \) is some fixed positive value. Taking (binary) logarithms, we equivalently obtain

\[
\log F(n) = \log P(n) + 2 \log F(n-1), \quad n > 0.
\]

If we substitute \( f(n) := \log F(n) \) and \( p(n) := \log P(n) \) we arrive at

\[
f(n) = p(n) + 2f(n-1), \quad n > 0.
\]

Simply expanding this yields

\[
f(n) = \sum_{i=0}^{n-1} 2^i p(n-i) + 2^n f(0)
\]

\[
= \sum_{i=1}^{n} 2^{n-i} p(i) + 2^n f(0)
\]

\[
= 2^n \left( f(0) + \sum_{i=1}^{n} 2^{-i} p(i) \right).
\]
We conclude that \( f(n) = \Theta(2^n) \), if the infinite series \( \sum_{i=1}^{\infty} 2^{-i} p(i) \) converges. A sufficient condition for this is \( p(n) \leq c^n \) for \( c < 2 \), or \( P(n) \leq 2^n \).

Now, let us explain how the above recurrence is derived. Let \( F(n) \) denote the number of different decomposable USO. Consider the coordinate \( n \). We can orient it in a combed way: all edges are forward or all edges are backward. In the two antipodal facets defined by this coordinate we can embed any decomposable orientation. Thus, we have \( F(n) \geq 2 \cdot F(n - 1)^2 \).

The upper bound follows from the same procedure but now we allow to choose the combed coordinate at every step. Again, for the coordinate we choose we have two choices (edges oriented forward or backward). Hence, we have \( F(n) \leq 2n \cdot F(n-1)^2 \). Note that the construction we suggest, i.e. taking any two \((n-1)\)-USO and connecting them with a combed coordinate to an \( n \)-USO is safe by the Product Lemma (statement in Appendix D).

In conclusion, we have that \( 2 \leq P(n) \leq 2n \) and, thus, the infinite series we discuss above converges and \( f(n) = \Theta(2^n) \). It follows that \( F(n) = 2^{\Theta(2^n)} \). \( \square \)

D Niceness of known USO constructions

In this section we survey the niceness of USO constructions that have appeared in the literature as lower bounds for the behavior of RE or other algorithms. For this, we first discuss the tools used in these constructions.

The constructive lemmata of \cite{25}

Schurr and Szabó, in \cite{25}, kickstarted a new direction for lower-bounding algorithms on AUSO. Not only because they proved by an adversarial argument that any deterministic algorithm needs at least \( \Omega(n^2/|\log n|) \) steps to solve an AUSO. But, also, because they provided the methods for constructing USO, which where used in most of the constructions we discuss later. Here we rewrite the two constructive lemmas for the sake of completeness and in order to argue about the preservation of niceness when they are applied.

**Lemma 3** (Product Lemma). Let \( A \) be a set of coordinates, \( B \subseteq A \) and \( \bar{B} = A \setminus B \). Let \( \tilde{s} \) be a USO on \( Q^B \) and let \( s_u, u \in Q^B \), be \( 2^{|B|} \) USOs on \( Q^B \). Then, the orientation defined by the outmap

\[
s(v) = \tilde{s}(v \cap B) \cup s_{v \cap \bar{B}}(v \cap \bar{B})
\]

on \( Q^A \) is a USO. Furthermore, if \( \tilde{s} \) and all \( s_u \) are acyclic so is \( s \).

Let \( z \) be the sink of \( \tilde{s} \). If \( \tilde{s} \) is \( i \)-nice and \( s_z \) is \( i \)-nice then so is \( s \).

**Proof.** The lemma is proved in \cite{25}. Here we will only argue about the niceness part.

Let \( \tilde{s} \) be \( i \)-nice and consider \( F_{\tilde{s},z} \), the \( |\bar{B}| \)-dimensional face that corresponds to \( z \). Consider any vertex \( v' \in Q^A \setminus F_{\tilde{s},z} \) and let \( u \in Q^B \) be such that \( v = v' \cap B \) is \( i \)-covered by \( u \) in \( \tilde{s} \). Then, we have that \( v' \) is \( i \)-covered by \( u' = u \cup (v' \cap \bar{B}) \) in \( s \). First, there is a path from \( v' \) to \( u' \) because there is such a path in \( \tilde{s} \). Thus, we have that \( r(u') \subseteq r(v') \). By our assumptions, there exists a coordinate \( l \in B \) such that \( l \in \tilde{r}(v') \setminus \tilde{r}(u') \). It is the case that \( l \in r(u') \setminus r(u') \). That means that \( r(u') \subset r(u') \) and thus \( v' \) is \( i \)-covered by \( u' \).

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Now, let \( v' \in F_{B,z} \). Since every vertex in \( F_{B,z} \) corresponds to the sink \( z \) of \( \tilde{s} \), it cannot be \( i \)-covered by a vertex outside of \( F_{B,z} \). Since, we have that \( s_z \) is \( i \)-nice it is the case that \( v' \) is \( i \)-covered by some vertex \( u' \in F_{B,z} \). Note that if \( s_z \) is \( i' \)-nice for \( i' > i \) then \( s \) would only be \( i' \)-nice.

The first dimension where there are USOs that are not 1-nice is \( 3 \). Therefore, for the above lemma and \( |\bar{B}| \leq 2 \) if \( \tilde{s} \) is 1-nice then so is \( s \). Following, we state the second lemma.

**Lemma 4** (Hypersink Reorientation). Let \( A \) be a set of coordinates, \( B \subseteq A \) and \( \bar{B} = A \setminus B \). Let \( s \) be a USO on \( Q^A \) and let \( Q^B \) be a subcube of \( Q^A \). If \( s(v) \cap \bar{B} = \emptyset \) for all \( v \in Q^B \) and \( \tilde{s} \) is a USO on \( Q^B \), then the outmap \( s'(v) = \tilde{s}(v \cap B) \) for \( v \in Q^B \) and \( s'(v) = s(v) \) otherwise is a USO on \( Q^A \).

If \( s \) and \( \tilde{s} \) are acyclic, then so is \( s' \).

Unfortunately, the above lemma does not carry niceness. This is easy to see: Assume that \( s \) is \( i \)-nice. There can be a vertex \( v \) that is \( i \)-covered in \( s \) by a vertex \( u \). However the closest neighbor of \( u \) in the hypersink \( Q^B \) might be the source of subcube \( Q^B \) in which case \( v \) is not \( i \)-covered anymore in \( s' \). It is not difficult to construct such examples. Also note that the edge flip operation we used in Section 4.2 is a corollary of this lemma. In the construction of Theorem 11 we start with the uniform orientation which is decomposable and thus 1-nice and end with a \((n - 2)\)-nice AUSO.

The lower bound constructions

Firstly, we consider Random Facet. Matoušek provided a family of LP-type problems that serve as a subexponential lower bound for Random Facet [20]. Later, Gärtner translated these to AUSO [10] on which the algorithm requires a subexponential number of pivot steps that is asymptotically matching the upper bound in the exponent. The orientations that serve as a lower bound here are decomposable and, thus, 1-nice; RE can solve them in \( O(n^2) \) steps. This is the only AUSO construction that we discuss in this section and is not based on the lemmas above.

Subsequently, consider the Bottom Antipodal algorithm. No non-trivial upper bounds are known for this algorithm. However, Schurr and Szabó [26] have described AUSO on which Bottom Antipodal takes \( \Omega(\sqrt{n}) \) steps. Their constructions are 2-nice and, thus, RE can solve them with \( O(n^3) \) steps.

Last but not least, we discuss the lower bound constructions for RE. The first superpolynomial lower bound for RE on AUSO was proved by Matoušek and Szabó in [23]. Their construction achieves the lower bound of \( 2^{\Omega(n^{1/3})} \) when Random Edge is started at a random vertex. The construction is \( n^{1/3} \)-nice, which implies an upper bound of \( 2^{O(n^{1/3} \log n)} \) which is close to the lower bound.

Very recently, Hansen and Zwick [16] improved these lower bounds by improving the techniques of [23]. They achieve a lower bound of \( 2^{O(\sqrt{n \log n})} \). Their construction is \( \sqrt{n} \)-nice; hence, we have an upper bound of \( 2^{O(\sqrt{n \log n})} \) which is almost tight.

The upper bounds for the constructions of [20], [23] and [16] are all based on Lemmas 3 and 4. The niceness bounds we mention follow directly from our arguments on the preservation of niceness for these lemmas. We turn our attention to cyclic USO.
For cyclic USO we have the lower bound provided by Morris in [24]. The number of steps required when RE starts at any vertex of a Morris USO is at least \(\frac{n-1}{2}! = n^{\Omega(n)}\) which is significantly larger than the number of all vertices. The lower bound implies that Morris USO is \(i\)-nice for \(i = \Omega(n)\); otherwise, the upper bounds of Theorem 4 would contradict the lower bound. Indeed, as we mentioned in Section 4.2, these USO are exactly \(n\)-nice and thus the upper bound we get by Theorem 4 is tight to the lower bound.

In conclusion, using the niceness concept we can argue, firstly, that RE can solve instances that serve as lower bounds for other algorithms in polynomial time. Secondly, that on the lower bounds instances for RE the upper bounds are tight or almost tight. We summarize the findings of this section in the following table (which also appears in Section 3):

| Algorithm               | Reference  | Lower bound                  | Niceness | RE Upper bound         |
|-------------------------|------------|------------------------------|----------|------------------------|
| Random Facet            | [20], [10] | \(2^{\Omega(\sqrt{n})}\)   | 1        | \(O(n^2)\)             |
| Bottom Antipodal        | [26]       | \(\Omega(\sqrt{2n})\)       | 2        | \(O(n^3)\)             |
| RE acyclic              | [23]       | \(2^{\Omega(n^{1/3})}\)    | \(n^{1/3}\) | \(2^{O(n^{1/3}\log n)}\) |
| RE acyclic              | [16]       | \(2^{\Omega(n^{1/3}\log n)}\) | \(\sqrt{n}\) | \(2^{O(n^{1/3}\log n)}\) |
| RE cyclic               | [24]       | \(\frac{n-1}{2}!\)          | \(n\)    | \(n^{O(n)}\)           |

E Fibonacci Seesaw revisited

Let \(\psi\) be a USO. The Fibonacci Seesaw (FS) [28] algorithm progresses by increasing a variable \(j\) from 0 to \(n - 1\) while it maintains the following invariant: There are two antipodal \(j\)-faces \(A\) and \(B\) of \(Q^n\) that have their sinks \(s_A\) and \(s_B\) evaluated. For \(j = 0\) this means to evaluate two antipodal vertices. To go from \(j = k\) to \(j = k + 1\) we take a coordinate \(b \in s_\psi(s_A) \oplus s_\psi(s_B)\). Such a coordinate has to exist because of Lemma 1. Let \(b \in s_\psi(s_A)\) and \(b \notin s_\psi(s_B)\). Let \(A'\) be the \((k+1)\)-face that we get by extending \(A\) with coordinate \(b\) and \(B'\) the corresponding face from \(B\). We have that \(s_B\) is the sink of \(B'\). For \(A'\) we need to evaluate the sink. But this will lie in the \(k\)-face \(A' \setminus A\). Thus, for this step we need \(t(k)\) evaluations, where \(t(k)\) is the number of steps the FS needs to evaluate the sink of a \(k\)-USO.

When we reach two antipodal facets with \(j = n - 1\) the algorithm will terminate as either \(s_A\) or \(s_B\) will be the sink. The total cost of the algorithm is known to be \(O(n^\alpha)\), where \(\alpha < \phi\) is a constant slightly smaller than the golden ratio. We consider the following algorithm:

```
Set index \(j = 0\);
Pick a starting vertex \(v^j \in Q^n\);
Set evaluated coordinates \(E^j = \emptyset\);

while \(s_\psi(v^j) \neq \emptyset\) do
    Pick \(b \in s_\psi(v^j)\);
    \(v^{j+1} \leftarrow \text{FS}(F_{E^j, v^j} \cup \{b\})\);
    \(E^{j+1} \leftarrow E^j \cup \{b\}\);
    \(j \leftarrow j + 1\);
end
```

Algorithm 1: FS Revisited

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After the jth iteration, the above algorithm considers the sink \( v^j \) of face \( F_{E^j,v^j} \). Then, it expands the set of coordinates by adding a coordinate \( b \) that is outgoing for \( v^j \) and solving, using the Fibonacci Seesaw, the face \( F_{E^j,v^j \oplus \{b\}} \). The result is the sink of the face \( F_{E^{j+1},v^{j+1}} \) which becomes vertex \( v^{j+1} \). The algorithm terminates when it has evaluated the global sink.

**Lemma 5.** Let \( \rho \) be the iteration in which the algorithm terminates. Then,

\[
\rho \geq r^0(v^0) \geq \ldots \geq r^0(v^\alpha)
\]

**Proof.** Consider \( v^j \) for any \( j \) and let \( j \in s^j(v^j) \) be the next coordinate that the algorithm will consider. In the next step, we will have \( v^{j+1} \) which will be the sink of face \( F_{E^j,v^j \oplus \{b\}} \) for some \( b \in s^j(v^j) \). We have that \( F_{E^j,v^j \oplus \{b\}} \subseteq F_{E^{j+1},v^{j+1}} \), for every \( j \leq \rho \). In particular, we have \( F_{E^j,v^j \oplus \{b\}} \subseteq F_{E^{j+1},v^{j+1}} \), for every \( 0 < j \leq \rho \). This means that there is a path \( v^0 \rightsquigarrow v^j \), for every \( 0 < j \leq \rho \). The lemma follows.

Using the above lemma, we can upper bound the iterations of the new algorithm in terms of the reachmap of the starting vertex.

**Lemma 6.** Let \( \rho \) be the iteration in which the algorithm terminates. Then, \( \rho \leq |r^0(v^0)| \).

**Proof.** After iteration \( j \), Algorithm 1 has computed \( v^j \) which is the sink of a \( j \)-face. We have argued that \( r^0(v^0) \geq r^0(v^1) \geq \ldots \geq r^0(v^\rho) \). This means that the coordinate we pick at any iteration is in the reachmap of \( v^\rho \). In addition, the set of coordinates \( E^j \) grows at every iteration. If \( E^j = r^0(v^0) \) (or equivalently \( j = |r^0(v^0)| \)), then \( v^j \) will be the sink of the face \( F_{r^0(v^0),v^0} \). This means that \( v^j \) will be the global sink of \( \psi \), i.e. \( s^j(v^j) = \emptyset \). Of course, it might happen that \( v^j \) is the global sink for \( E^j \subseteq r^0(v^\rho) \); hence, the inequality.

**Theorem 7.** Algorithm 1, when run on an \( n \)-USO \( \psi \) with starting vertex \( v^0 \in Q^\alpha \), runs in \( O(\alpha^\rho) \) many evaluations, for \( \alpha < \phi \) and \( \rho = |r^0(v^0)| \).

**Proof.** The algorithm performs at most \( \rho \) iterations. At each of them it calls the Fibonacci Seesaw to solve a face of \( \psi \). In particular, when progressing from the \( j \)th to the \( (j+1) \)th iteration it calls the Fibonacci Seesaw to solve an \( \alpha \)-face of \( \psi \). Thus, the number of vertex oracle calls of Algorithm 1 can be bound by

\[
\sum_{k=0}^{\rho} \alpha^k = \frac{\alpha^{\rho+1} - 1}{\alpha - 1} = O(\alpha^\rho)
\]

where \( 1 < \alpha < \phi \) is the constant in the time bounds of the Fibonacci Seesaw algorithm, i.e. \( \alpha \approx 1.61 \).

We have that Algorithm 1 is faster asymptotically than the Fibonacci Seesaw when the size of the reachmap of the starting vertex is small, i.e. \( |r^0(v^0)| \ll n \). We believe that similar variants as the one above (adding one coordinate at a time and recursively running the algorithm in question) would provide upper bounds where the reachmap of the starting vertex is in the exponent, for every non-path-following algorithm.