Battery Less Solar Photovoltaic Water Pumping System using Incremental Conductance Method

M. Gayathiri* and K. Lakshmi

Department of Electrical and Electronics Engineering, Sri Krishna College of Engineering and Technology Coimbatore – 641008, Tamil Nadu, India; Gayathirimallika.m@gmail.com, Lakshmi.k@skcet.ac.in

Abstract

Objectives: The work is to improvise the energy efficiency, cost and payback time of solar Photovoltaic water pumping system. Methods/Statistical Analysis: In this proposed work overview of the solar panel is presented, resulting in a Maximum Power Point Tracking (MPPT) technique to improve the efficiency and also to increase the potential of solar plant. The energy efficiency, total cost and payback time are the important aspects in this design. If the numbers of panels are reduced, high gain will be achieved and without batteries, space can be reduced. The incremental conductance based water pumping system without batteries is presented for the domestic purposes and irrigation of small crops. Findings: The proposed system result uses the most extreme intensity of (100 w) condition at a voltage (272.5 v) and simulation results are obtained using MATLAB and Simulink. Application/Improvements: It is a low cost solution and also it requires no additional power equipment.

Keywords: Incremental Conductance Method, Maximum Power Point Tracking (MPPT), Photovoltaic (PV), Solar Array and Buck Converter

1. Introduction

Photovoltaic (PV) structures have been utilized for a many decades. Now a day, with the attention on power, PV has transform into be an essential wellspring of vitality for a wide scope of uses. Upgrades in changing over light vitality into electrical power just as the cost value decreases have made these improvements. To be sure, even with higher proficiency execution lower cost value aim remains the most extreme vitality from the PV framework gadget beneath different lighting installations

Unfortunately, PV structure frameworks have two major issues: The change productivity of electric power age is low (9-17%), especially under low illumination conditions and the measure of electric power created by sunlight based clusters changes ceaselessly with atmosphere conditions. Also, the sun powered cell V-I trademark is nonlinear and differs with enlightenment and temperature.

As a rule, there is a phenomenal point on the V-I or V-P bend, known as Maximum Power Point (MPP), at which the total PV system (cluster, converter and so on.) works with better proficiency and produces its greatest yield control. The locale of the MPP isn’t known, yet can be found, either through estimation models by means of or seek calculations.

Thus Maximum Power Point Tracking (MPPT) techniques are required to keep up the PV panel working point at its MPPT: Maximum Power Point Tracking, every now and again alluded to as MPPT, is an electronic framework that works the Photovoltaic (PV) modules to create all the power they are able to do. Most extreme power point is a physical module to lead them point legitimately at the sun, it is anything but a mechanical following framework. MPPT is a totally electronic framework that differs the electrical working purpose of the modules with the goal that the modules can supply most extreme accessible power.
2. Modeling of Components

Under test in order to reproduce simple segments which are being used for this postulation, we have to use logical approximations to what the components truly do. Without this progression, it is difficult to analyze these circuits. By utilizing these models we are then ready to do discrete examination with the help of a PC for estimations. Figuring these by hand is time restrictive. In MATLAB there are many square sets recently made to facilitate the usage of their product condition. By interfacing these numerical models, we can be ready to reenact the circuit and concentrate near genuine information. When the right tuning has been done in reproduction, the information would then be able to be utilizing the information to instantiate a genuine gadget.

2.1 Solar Array

We created a model of the solar array based on:

\[
I_d = I_{sat} e^{\frac{qV_d}{kT} - 1}
\]

Where \( I_d \) is the diode current (A), \( V_d \) is the voltage over the diode (V), \( I_{sat} \) is the diode turn around immersion current (A), \( q \) is the electron charge \((1.602 \times 10^{-19} \text{C})\), \( k \) is Boltzmann’s constant \((1.381 \times 10^{-23} \text{J/K})\), \( T \) is the crossing point temperature (K) and \( E \) is Napier’s Constant (generally 2.71828). As expressed by Mohan, the phone trademark at a given irradiance and temperature essentially comprises of two fragments: The steady voltage portion and the consistent current section. The current is restricted as the cell is shortcircuited. The most extreme power condition happens at the knee of the trademark where the two sections meet. It is attractive to work at the MPP. In a perfect world, an unadulterated DC current ought to be drawn from the sun based cluster, however the decrease in conveyed control isn’t extensive even within the sight of a considerable lot of swell current. To guarantee that the exhibit keeps working at the MPP, a P and O strategy is utilized where at ordinary interims the measure of current drawn is irritated and the subsequent power yield is watched. On the off chance that an expanded current outcomes in more power, it is additionally expanded until power yield starts to decay. Then again, on the off chance that an expansion in current outcomes in less power than previously, at that point the current is expanded until the power yield quits expanding and starts to go down. For this reproduction, a sun based exhibit that could yield more prominent than 100W of intensity was chosen.

The panel is made by Kyocera, KD135GX-LP. The datasheet for this board can be found in the Appendix. This board has an open circuit voltage \( V_{oc} \) of 22 V with a short out current \( I_{sc} \) of 8.4 A. The voltage at greatest power \( V_{mp} \) is 17.7 V while the current at most extreme power \( I_{mp} \) is 7.6 A. By connecting these qualities to:

\[
P = I \times V
\]

We achieve 134.5 W of yield control from the sun powered exhibit under full sunlight based enlightenment. So as to display the shifting measure of shading and overcast spread, a profile of light was contrived that will check the MPPT’s capacity to change set focuses inside a sensible measure of time.

2.2 Buck Converter

A Buck converter (step down converter) is a DC to DC control converter which adventures down voltages from its input (supply) to its output (load). It is a class of exchanged mode control supply (SMPS) typically containing something like two semiconductor a diode and a transistor, but current buck converters a significant part of the time replace the diode with second transistor used for synchronous adjustment and no short of what one imperativeness amassing segment, a capacitor, indictor or the two blend.

2.2.1 Continuous Mode

Buck converter works in constant mode if the current through the inductor (\( I_L \)) never falls to zero, during commutation cycle.

- At the point when switch shut the voltage over the indictor is:
  \( V_L = V_i - V_0 \)

- At the point when switch is opened the diode is forward one-sided. The voltage over the indictor is
  \( V_L = -V_0 \)

Changing rate of \( I_L \) can be calculated from:

\[
V_L = L \frac{dI_L}{dt}
\]

with \( V_L \) equal to \( V_i - V_0 \) on state and to \(-V_0\) during off states, therefore increase ion current during the on states is given by:

\[
\Delta I_{Lon} = \frac{(V-v)}{L*ton}
\]

We assume that the converter works in steady states, the energy stored in each component at the end of com-
mutation cycle. T is equal to that the start of the cycle. Current $I_i$ is the same at $t = 0$ and at $t = T$.

$$\Delta I_{on} + \Delta I_{off} = 0,$$

$$(V-V)/L + t_{on} - (V/L) + t_{off} = 0.$$  

Capacitor current

$$I_c = I_{pv} - I_{dc}.$$  

From the Table 1, if $dP/dV > 0$ then operating point is moving towards Maximum power point.

if $dP/dV < 0$ then operating point is moving away from Maximum power point. (P and O) Figure 1 shows the waveform of continuous mode operation.

**Table 1.** Voltage and power calculation for proposed model

| Current (A) | Voltage (V) | Power ($P = A*V$) | $\Delta P = P_n - P_{n-1}$ | $\Delta V = V_n - V_{n-1}$ | $dP/dV$ |
|-------------|-------------|--------------------|-----------------------------|-----------------------------|--------|
| 0.305       | 0.171       | 0.55               | 0.052                       | 0.171                       | 0.30   |
| 0.344       | 2.492       | 0.85               | 0.805                       | 2.321                       | 0.34   |
| 0.337       | 5.013       | 1.68               | 0.832                       | 2.521                       | 0.33   |

Continuous operation

2.2.2 **Discontinuous Mode**

The inductor current falling under zero, outcomes in the releasing of the yield capacitor amid each cycle and thusly higher switching losses.

We consider that converter works in steady states. Therefore, the energy in the inductor is the equivalent towards the start and end of the cycle. This implies normal estimation of inductor voltages ($V_i$) is zero.

$$(V_i - V_0)DT - V_0 & T = 0.$$  

The waveform discontinues mode is shown in Figure 2.

![Continuous operation](image1)

**Figure 1.** Continuous operation.

**Table 2.** Voltage and power calculation for proposed model

2.2.3 **Non Ideal Circuit**

Towards this new energy policy Photovoltaic system merges as a promising clean source characterized by long lifespan and high reliability. However the efficiency of such system is strongly affected by specific degradation modes that may occur during the lifetime of PV module. Thus, these modules failures should be detected and controlled by applying responsible monitoring and diagnostics methods. Normalized voltage is shown in Figure 3.

![Discontinuous operation](image2)

**Figure 2.** Discontinuous operation.

**Figure 3.** Non ideal characteristics of panel.

3. **Methodology**

Maximum Power Point Tracking (MPPT) calculations is imperative in PV frameworks since it lessens the PV bunch cost by decreasing the amount of PV boards.
Battery Less Solar Photovoltaic Water Pumping System using Incremental Conductance Method

This paper presents comparative examination of two essential MPPT calculations explicitly irritate and observe and gradual conductance. These figuring are commonly utilized in light of its minimal effort and straightforwardness of affirmation. Some basic parameters, for example, voltage, current and power yield for each extraordinary mix has been pursued for the two calculations.

Mat lab Simulink device compartment has been utilized for execution examination by a 70 W Photovoltaic (PV) show. Photovoltaic is the most reassuring wellsprings of reasonable effective power essentialness. Because of the regular and monetary preferences, PV age is supported over other feasible vitality sources, since they are unblemished, boundless and require little upkeep. PV cells make electric power by explicitly changing over daylight based imperativeness to electrical essentialness. PV board and clusters, make DC control that must be changed over to AC at standard power recurrence so as to encourage the heaps. Along these lines PV frameworks require interfacing power converters between the PV group and the network. Photovoltaic-produced essentialness can be conveyed to control framework organizes through lattice related inverters. One basic issue in PV frameworks is the plausible crisscross between the working qualities of the heap and the PV cluster.

The Photovoltaic working point is at the intermixing of the I-V curves of the PV group and weight, when a PV bunch is direct connected with a stack. The Maximum Power Point (MPP) of PV board isn’t accomplished as a rule. This issue is overwhelmed by utilizing a MPPT which keeps up the PV display’s working point at the MPP. The event of MPP in the I-V plane isn’t known cloister; along these lines it is resolved using a model of the PV gatherings and estimation of irradiance and bunch temperature. Figuring this estimation are every now and again too much excessive and the required parameters for the PV display show are not known sufficiently in thusly, the MPPT always searches for MPP. Figure 4 shows the flow chart of the proposed algorithm.

Of these, the two most unavoidable MPPT methods (Perturb and Observe (P and O) and Incremental Conductance procedures) are analyzed. The paper has been managed in the going with way. The essential association lines of PV cell and the characteristics of PV cluster are discussed the P and O and InC MPPT figuring in detail. The recreation consequences of PV exhibit, MPPT calculations and their examination are talked about , Last area closes with the degree for further work.

3.1 MPPT for Proposed Model

A MPPT approach is cling to follow the working purpose of Photovoltaic. The outline of flowchart is representation of voltage and current for Photovoltaic. The dVpv and dIpv sort of incremental voltage and current of PV board.

\[
\frac{dP_{pv}}{dV_{pv}} = I_{pv} + V_{pv} \frac{dI_{pv}}{dV_{pv}}
\]

4. Simulated Performance for Proposed Model

The information is taken from Irradiation (929.50 wm\(^2\)) and given through the panel, the solar oriented board has 96 cells and it is work up to 1000 w of power. The boost
converters rectify the voltage swells. The output power and voltages are taken from boost converter, the maximum intensity of (10 0w) condition at a voltage (272.5 v) and simulation results are obtained using MATLAB and Simulink. The simulation model is shown in Figure 5.

5. Result

Simulink created by MathWorks, is a graphical programming condition for modeling, simulating and analyzing multi domain dynamical framework. Its essential interface is a graphical block and adaptable arrangement of block libraries. Figure 6 shows the simulation output. It offers tight integration whatever is left of the MATLAB environment and can either drive MATLAB or be scripted from it. Simulink is broadly used in automatic control and digital signal processing for multi domain simulation and model-based design.

6. Conclusion

In this paper a consistent model of a 70 W Photovoltaic board has been made using MATLAB Simulink. This model is utilized for the Maximum Power Point following calculation. The P and O and Incremental conductance MPPT computations are discussed and their entertainment results are appeared. It is appeared incremental conductance technique has favored execution over P and O figuring. These computations update the components and constant state execution of the Photovoltaic structure similarly as it improves the adequacy of the DC-DC converter system. Since sun oriented boards are very wasteful regardless, any technique for improving force exchange from these boards is a beneficial addition in generally speaking productivity. By interfacing a sun based exhibit to a buck converter, we can control the yield voltage of the boards. The parameter to be controlled is the level of time a switch is dynamic amid each control cycle. So as to look at the execution of various calculations intended to control the buck converter, a reenactment was made to think about the calculations.

7. References

1. Hohm DP, Ropp ME. Comparative study of Maximum Power Point Tracking algorithms using an experimental, programmable, Maximum Power Point Tracking test bed. Conference Record of the Twenty-Eighth IEEE Photovoltaic Specialists; 2000. p. 1699–702.
2. Pongratanakul N, Kasparis T. Tool for automated simulation of solar arrays using general purpose simulators. IEEE Conference Proceedings 0-7803-8502-0/04; 2004. p. 10–4.
3. Esram T, Chapman PL. Comparison of Photovoltaic array Maximum Power Point Tracking techniques. IEEE
Transactions on Energy Conversion. 2007; 22(2):439–49. https://doi.org/10.1109/TEC.2006.874230

4. Zainudin HN, Mekhilef S. Comparison study of Maximum Power Point Tracker techniques for PV systems. Proc 14th International Middle East Power Systems Conference; 2010. p. 750–5.

5. Dufo-Lopez R, Bernal-Agustín JL. Multi-objective design of PV-wind-diesel-hydrogen-battery systems. Renewable Energy. 2008; 33(12):2559–72. https://doi.org/10.1016/j.renene.2008.02.027

6. Electrical Engineering Department. 2011. http://ee.iitd.ernet.in/Short_listing_MTECH_PHD.pdf

7. Hearps P, McConnell D. Renewable energy technology cost review. Melbourne Energy Institute: Tech Rep; 2011. p. 1–58.

8. Luna-Rubio R, Trejo-Perea M, Vargas-Vazquez D, Ríos-Moreno GJ. Optimal sizing of renewable hybrids energy systems: A review of methodologies. Solar Energy. 2011; 86:1077–88. https://doi.org/10.1016/j.solener.2011.10.016

9. Solar radiation data in Thailand. 2007. https://indico.cern.ch/event/478090/attachments/1397519/2261578/7_Text-202-271.pdf

10. Hocaoglu FO, Gerek ON, Kurban M. A novel hybrid (wind-Photovoltaic) system sizing procedure. Solar Energy. 2009; 83(11):2019–28. https://doi.org/10.1016/j.solener.2009.07.010

11. 1661-2007 - IEEE Guide for Test and Evaluation of Lead-Acid Batteries used in Photovoltaic (PV) Hybrid Power Systems. 2008. https://ieeexplore.ieee.org/document/4449092.

12. IEEE Recommended Practice for Sizing Lead-Acid Batteries for Photovoltaic (PV) Systems Sponsor. 2000. https://ieeexplore.ieee.org/document/210970

13. Mishra AM, Singh B. Solar Photovoltaic array dependent dual output converter based water pumping using switched reluctance motor drive. IEEE. 2016; 53(6):5615–23.

14. Varma RK, Shalehi R. SSR mitigation with a new control of PV solar farm as statcom. IEEE Transactions on Sustainable Energy. 2017; 8(4):1473–83. https://doi.org/10.1109/TSTE.2017.2691279