Batch queues, reversibility and first-passage percolation

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Abstract

We consider a model of queues in discrete time, with batch services and arrivals. The case where arrival and service batches both have Bernoulli distributions corresponds to a discrete-time $M/M/1$ queue, and the case where both have geometric distributions has also been previously studied. We describe a common extension to a more general class where the batches are the product of a Bernoulli and a geometric, and use reversibility arguments to prove versions of Burke’s theorem for these models. Extensions to models with continuous time or continuous workload are also described. As an application, we show how these results can be combined with methods of Seppäläinen and O’Connell to provide exact solutions for a new class of first-passage percolation problems.

1 Introduction

We consider a model of queues in discrete time, with batch services and arrivals. At the beginning of time slot $n$, there are $X_n$ customers in the queue. A number $A_n$ of customers then arrive, increasing the queue length to $X_n + A_n$. After this an amount $S_n$ of service is available, so that $D_n = \min(S_n, X_n + A_n)$ customers depart from the queue. Typically, we assume that the sequences $A_n$ and $S_n$ are random.

This model has been studied in various contexts (sometimes described as a storage model rather than a queue [3]). There is a close correspondence between this model and another type of queueing model, in which the data $S_n$ represent inter-arrival times between successive customers and the data $A_n$ represent service requirements of customers.

The case where the sequences $S_n$ and $A_n$ are independent and both consist of i.i.d. Bernoulli random variables corresponds to an $M/M/1$ queue in discrete time. The case where the Bernoulli distributions are replaced by geometric distributions has also been studied previously [2, 3, 10].

We generalise these two situations to the case where the distributions are a product of a Bernoulli and a geometric.

We show that for appropriate choices of the parameters, the queue is reversible in equilibrium, and that various forms of Burke’s theorem hold: for example, the departure process has the same distribution as the arrival process, and the queue-length at a given time is independent of the departure process before that time. The stationary distribution of the queue-length is also given by a product of a Bernoulli and a geometric.

These properties make it easy to describe the stationary behaviour of several such queues in tandem. As an application, we show how this can be used to calculate rates of growth for
certain first-passage percolation problems. This uses techniques developed by Seppäläinen [12] and O’Connell [10], and extends the class of “exactly solvable” first-passage percolation models.

In Section 2 we describe the basic queueing model in more detail. In Section 3 we collect some definitions regarding probability distributions, in particular the distribution obtained by multiplying a Bernoulli and a geometric.

In Section 4 we state and prove the reversibility results and versions of Burke’s theorem, for queues with Bernoulli-geometric arrival and service processes. We discuss related results concerning systems of queues in tandem. We also note results about the stationary distribution of the queue-length in the case where only the arrival process is assumed to have this form, and the service process consists of any i.i.d. sequence.

As well as extending the Bernoulli and geometric cases, the Bernoulli-geometric model has another useful feature, that by taking a limit as the parameter of the Bernoulli tends to 0 one can easily arrive at various continuous-time models in which arriving customers or offered service occur at times corresponding to points of Poisson processes. Taking an alternative limit, one can also consider models with continuous workload, where arrival and service batches are exponential rather than geometric. These extensions are indicated in Section 4.4.

In Section 5 we describe the application to first-passage percolation models, and give exact expressions for some time-constants.

2 Queueing model with batch services and arrivals

We describe the main queueing model of the paper.

The queue is driven by an arrival process \( (A_n, n \in \mathbb{Z}) \) and a service process \( (S_n, n \in \mathbb{Z}) \).

At time-slot \( n \in \mathbb{Z} \), \( A_n \) customers arrive at the queue. Then service is available for \( S_n \) customers; if the queue-length is at least \( S_n \), then \( S_n \) customers are served, while if the queue length is less than \( S_n \) then all the customers are served.

Let \( X_n \) be the queue length after the service \( S_{n-1} \), before the arrival \( A_n \). From the description of the queue above, we have the basic recurrences

\[
X_{n+1} = \max\{X_n + A_n - S_n, 0\} \tag{2.1}
\]

(where \([x]_+\) denotes \(\max\{x, 0\}\)). Similarly if \( Y_n \) is the queue length after the arrival \( A_n \) and before the service \( S_n \), then \( Y_n = X_n + A_n \), and

\[
Y_{n+1} = \max\{Y_n - S_n, 0\} + A_{n+1}. \tag{2.2}
\]

In this paper we will almost always consider the case where the arrival and service processes are independent, and \( (A_n, n \in \mathbb{Z}) \) and \( (S_n, n \in \mathbb{Z}) \) are both i.i.d. sequences, with \( \mathbb{E}A_n < \mathbb{E}S_n \). In this case (in fact, much more generally) we can define the queue-length sequence \( (X_n, n \in \mathbb{Z}) \) by

\[
X_n = \max\{ \sum_{r=m}^{n-1} (A_r - S_r), 0 \} \tag{2.3}
\]
Figure 2.1: The evolution of the queue with batch services and arrivals

(where a sum from \( n \) to \( n - 1 \) is understood to be 0). This quantity is almost surely finite since the common mean of the \( S_n \) is larger than that of the \( A_n \). Then the sequence \((X_n)\) satisfies the recurrences (2.1), and that \((X_n)\) is a stationary Markov chain.

Let \( D_n \) be the number departing from the queue at the time of the service \( S_n \). So

\[
D_n = \min(Y_n, S_n) \\
= Y_n - X_{n+1} \\
= X_n + A_n - X_{n+1} \\
= Y_n + A_{n+1} - Y_{n+1}.
\]

Let \( U_n \) be the unused service at the time of the service \( S_n \). So

\[
U_n = S_n - D_n \\
= [S_n - Y_n]_+.
\]

See Figure 2.1 for a representation of the evolution of the queue along with its inputs and outputs.

We also introduce some further quantities whose interpretation is ostensibly less natural (but see Section 2.1). Write \( I_n = U_n + A_{n+1} \) for the unused service plus next arrival, and \( T_n = U_n + A_n \) for the unused service plus previous arrival.

Note that although we have talked in terms of “numbers of customers”, there is no reason why the variables have to take integer values. We will also consider the case where \( A_n \) and \( S_n \) are non-negative real-valued random variables; here one might talk of “amount of work”, say, rather than “number of customers”.

This model of a discrete-time queue with batch services and arrivals has been considered in various contexts, for example by Bedekar and Azizoğlu [2], Ganesh, O’Connell and Prabhakar [3], Draief, O’Connell and Mairesse [4], and O’Connell [10].

Models that have been studied include the case where arrival batches and service batches are Bernoulli distributed, and the case where both have a geometric distribution; see the next sections for further details. The main result in this paper is to extend the versions of Burke’s theorem obtained in these cases to the case of a distribution which is the product of a Bernoulli and a geometric.
2.1 Dual queueing model

Our main batch queueing model is closely related to an alternative (and in fact more widely-studied) model of a single-server queue with first-in-first-out service discipline.

This dual model uses the same variables and recurrences as above, but with different interpretations. Now $A_n$ represents the amount of time required by the $n$th customer for service, and $S_n$ is the interarrival time between customers $n$ and $n+1$.

Let $X_n$ be the waiting time of customer $n$ between his arrival at the queue and the start of his service. Then $X_n$ obeys the same recurrence as at (2.1) above. Now $Y_n$ is the total time spent by customer $n$ in the queue (including service), and $D_n$ is the time spent by customer $n$ at the back of the queue. $U_n$ is the idle time of the server between departure of customer $n$ and arrival of customer $n+1$, $I_n$ is the interdeparture time between customers $n$ and $n+1$, and $T_n$ is the time between the starts of service of customers $n$ and $n+1$.

See Draief, Mairesse and O’Connell [3] for extensive discussions of the relations between the two models.

2.2 Geometric case

We assume that the processes $(A_n, n \in \mathbb{Z})$ and $(S_n, n \in \mathbb{Z})$ are independent, and that each process is an i.i.d. sequence.

Suppose now that both $A_n$ and $S_n$ have geometric distribution, with $P(A_n = k) = \alpha(1 - \alpha)^{k-1}$ and $P(S_n = k) = \beta(1 - \beta)^{k-1}$ for $k = 1, 2, \ldots$. For stability of the process, we require $\beta < \alpha$.

In this case, the single-server queue of Section 2.1 is an $M/M/1$ queue in discrete time. A version of Burke’s theorem was proved for this model by Hsu and Burke in [6]. Among other properties one has that the arrival and departure processes have the same law, which (in the notation of Section 2.1) says that $(S_n, n \in \mathbb{Z}) \overset{d}{=} (I_n, n \in \mathbb{Z})$.

On the other hand, Bedekar and Azizoğlu [2] showed an analogous input-output theorem for the batch-queueing model; namely, that $(A_n, n \in \mathbb{Z}) \overset{d}{=} (D_n, n \in \mathbb{Z})$.

These results are unified by Draief, Mairesse and O’Connell [3], who obtain a joint Burke’s theorem for the two models, namely that

$$((A_n, S_n), n \in \mathbb{Z}) \overset{d}{=} ((D_n, I_n), n \in \mathbb{Z}).$$

(2.4)

The same result also applies if the distributions of $A_n$ and $S_n$ are exponential rather than geometric.

2.3 Bernoulli case

Suppose instead that $A_n$ and $S_n$ both have Bernoulli distribution, with $p = P(A_n = 1) = 1 - P(A_n = 0)$ and $q = P(S_n = 1) = 1 - P(S_n = 0)$. For stability of the process, we require $p < q$.

In our main batch-queue model, this means that each arrival batch is either empty or contains a single customer, and at each slot the available service is either 1 or 0.

In this case, the batch-queue model in fact corresponds to an $M/M/1$ queue in discrete time (hence to the dual queueing model in the geometric case of Section 2.2), since the
intervals between arrivals of successive customers are geometric (with mean $1/p$) and the service time of a customer once he reaches the front of the queue is also geometric (with mean $1/q$). So the statement that $(S_n) \overset{d}{=} (I_n)$ in the geometric case of Section 2.2 corresponds to the statement that $(A_n) \overset{d}{=} (D_n)$ in the Bernoulli case.

Again this can be extended to a sort of joint input-output theorem for the two models in the Bernoulli case; namely one has that

$$(A_n, S_n), n \in \mathbb{Z} \overset{d}{=} (D_n, T_n), n \in \mathbb{Z}.$$  \hspace{1cm} (2.5)

This result is contained in the proof of Theorem 4.1 of König, O’Connell and Roch [8].

Note the difference between (2.4) and (2.5). In the geometric case, the output theorem for the single-server queue involves the interdeparture process $(I_n)$, while in the Bernoulli case it involves instead the process $(T_n)$ of intervals between starts of service. One can see that $I_n$ is not Bernoulli in the Bernoulli case (indeed, one may have $I_n = 2$); also, one can see that $T_n$ and $T_{n+1}$ are not independent in the geometric case so that (2.5) certainly does not hold there.

In Theorem 4.1 we’ll show that the common part of (2.4) and (2.5), namely the result that $(A_n) \overset{d}{=} (D_n)$, extends to a class of cases where the distributions of $A_n$ and $S_n$ are products of a geometric distribution and a Bernoulli distribution.

### 3 Bernoulli-geometric distribution

We first introduce some notation. $X$ is said to have Bernoulli distribution with parameter $p$ if $P(X = 1) = p$ and $P(X = 0) = 1 - p$.

We say that $X$ has Geom$^+$ distribution with parameter $\alpha \in (0, 1)$ if

$$P(X = k) = \alpha(1 - \alpha)^{k-1}$$

for $k \geq 1$. If $X$ has Geom$^+(\alpha)$ distribution then $X - 1$ is said to have Geom$^0(\alpha)$ distribution.

Now we define a Bernoulli-geometric distribution, with parameters $p$ and $\alpha$. A random variable with this distribution has the distribution of the product of two independent random variables, one with Ber($p$) distribution and the other with Geom$^+(\alpha)$ distribution. That is, $A \sim \text{Ber}(p)\text{Geom}(\alpha)$ if

$$P(A = k) = \begin{cases} 
1 - p, & k = 0 \\
\rho \alpha(1 - \alpha)^{k-1}, & k \geq 1.
\end{cases}$$

We have $E A = p/\alpha$, and the probability generating function of $A$ is given by

$$E(z^A) = \frac{(1 - p) - (1 - p - \alpha)z}{1 - (1 - \alpha)z}.$$ 

The distribution of $A$, conditioned on being non-zero, is simply Geom$^+(\alpha)$.

In passing, note that such a random variable $A$ may also be represented as a geometric number of independent geometrics, in the case $p < \alpha$. Namely, let $V \sim \text{Geom}^0(p)$, and let $W_i$ be i.i.d. Geom$^+(\gamma)$, where $\gamma = (\alpha - p)/(1 - p)$, and independent of $V$. Then define $R = W_1 + W_2 + \cdots + W_V$. One has $R \overset{d}{=} A$.  

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Alternatively, let \( V \sim \text{Geom}^0(r) \) where \( r = (1-p)/p/(1-p\alpha) \), and let \( W_i \) be i.i.d. \( \text{Geom}^0(\gamma) \), where \( \gamma \) is as above, and independent of \( V \). As before, define \( R = W_1 + \cdots + W_V \); again one gets \( R \overset{d}{=} A \).

### 4 Bernoulli-geometric queues

We consider a queue with arrival process \( A_n, n \in \mathbb{Z} \) where \( A_n \) are i.i.d. \( \text{Ber}(p)\text{Geom}(\alpha) \), and a service process \( S_n, n \in \mathbb{Z} \) independent of the arrival process and with \( S_n \) i.i.d. \( \text{Ber}(q)\text{Geom}(\beta) \).

For stability we clearly need \( \mathbb{E} S_n > \mathbb{E} A_n \), i.e. \( p\beta < q\alpha \).

In general, the queue-length process is not reversible. For example, if \( \alpha \) is small and \( \beta \) is large, then one tends to see infrequent but large arrival batches, and frequent but small departure batches.

However, under a further condition, which in effect reduces the number of parameters from 4 to 3, we show reversibility and various other related properties. The relevant condition is that

\[
\frac{\alpha}{1-\alpha} \cdot \frac{p}{1-p} = \frac{\beta}{1-\beta} \cdot \frac{q}{1-q}.
\]

(4.1)

Note that combined with the stability condition \( p\beta < q\alpha \), condition (4.1) implies that \( \beta < \alpha \) and \( p < q \).

For a given service distribution, condition (4.1) gives one degree of freedom for the arrival distribution. In particular, suppose \( q \) and \( \beta \) are fixed, giving an overall service intensity of \( q/\beta \). Then for any \( \lambda < q/\beta \), there exists a unique pair \( p, \alpha \) satisfying (4.1) and such that the arrival intensity \( p/\alpha \) is equal to \( \lambda \). We further discuss the relevance of (4.1) to the reversibility of the queueing process in Section 4.5.

**Theorem 4.1** Suppose that \( p\beta < q\alpha \), and (4.1) holds.

(i) The queue-length processes \((X_n)\) and \((Y_n)\) are reversible; moreover, they are jointly reversible in the sense that

\[
(..., X_{-1}, Y_{-1}, X_0, Y_0, X_1, Y_1, \ldots) \overset{d}{=} (..., X_2, Y_1, X_1, Y_0, X_0, Y_{-1}, \ldots).
\]

(4.2)

(ii) The departure process \((D_n, n \in \mathbb{Z})\) has the same law as the arrival process \((A_n, n \in \mathbb{Z})\).

(iii) The stationary distributions of the queue-length processes (before and after service) are given by

\[ X_n \sim \text{Ber}(c)\text{Geom}(\gamma), \]

where

\[ c = \frac{\beta}{1-\beta} \frac{1-\alpha}{\alpha}, \quad \gamma = \frac{\alpha - \beta}{1-\beta}; \]

and

\[ Y_n \sim \text{Ber}(p + c - pc)\text{Geom}(\gamma). \]

(iv) For all \( n \), the queue length \( X_n \) at time \( n \) is independent of the process of departures \((D_i, i < n)\) before time \( n \).
From (iii), one has
\[ E X = \frac{\beta(1 - \alpha)}{\alpha(1 - \beta)}, \quad E Y = E X + \frac{p}{\alpha}. \]

**Proof of Theorem 4.1**

To show the reversibility in (i) and the stationary distribution for \( X_n \) in (iii), it is enough to show that for all \( k, m, r \),
\[
\pi(k)\mathbb{P}(Y_0 = m|X_0 = k)\mathbb{P}(X_1 = r|Y_0 = m) = \pi(r)\mathbb{P}(Y_0 = m|X_0 = r)\mathbb{P}(X_1 = k|Y_0 = m),
\]
where \( \pi \) is the probability mass function for the distribution of \( X_n \) given in (iii).

If \( k = r \), this is obvious. The cases \( k < r \) and \( k > r \) are symmetric, and one only needs to check one, say \( k < r \).

Note that
\[
\mathbb{P}(Y_0 = m|X_0 = k) = \mathbb{P}(A = m - k),
\]
while
\[
\mathbb{P}(X_1 = r|Y_0 = m) = \begin{cases} \mathbb{P}(S \geq m - r), & r = 0 \\ \mathbb{P}(S = m - r), & r > 0 \end{cases}.
\]

Further one has by assumption that
\[
\pi(x) = \begin{cases} 1 - c, & x = 0 \\ c\gamma(1 - \gamma)x^{-1}, & x \geq 1 \end{cases}, \quad \mathbb{P}(A = x) = \begin{cases} 1 - p, & x = 0 \\ p\alpha(1 - \alpha)x^{-1}, & x \geq 1 \end{cases},
\]
\[
\mathbb{P}(S = x) = \begin{cases} 1 - q, & x = 0 \\ q\beta(1 - \beta)x^{-1}, & x \geq 1 \end{cases}, \quad \mathbb{P}(S \geq x) = \begin{cases} 1, & x = 0 \\ q(1 - \beta)x^{-1}, & x \geq 1 \end{cases}.
\]

Now one can for example divide into four further cases: (1) \( k > 0, m = r \); (2) \( k > 0, m > r \); (3) \( k = 0, m = r \); (4) \( k = 0, m > r \), and check (4.3) directly in each case.

For example, in case (1), we can use the forms of the probability distributions above to give
\[
\pi(k)\mathbb{P}(Y_0 = m|X_0 = k)\mathbb{P}(X_1 = m|Y_0 = m) = \pi(k)\mathbb{P}(A = m - k)\mathbb{P}(S = 0)
\]
\[
= c\gamma(1 - \gamma)^{m-1}(1 - p)q\beta(1 - \beta)^{m-k-1} \left[ \frac{p}{1-p} \frac{\alpha}{\alpha - \frac{1 - q}{1 - \beta}} \right] \left[ \frac{1 - \alpha}{(1 - \beta)(1 - \gamma)} \right]^{m-k}
\]
\[
= c\gamma(1 - \gamma)^{m-1}(1 - p)q\beta(1 - \beta)^{m-k-1}
\]
\[
= \pi(m)\mathbb{P}(A = 0)\mathbb{P}(S = m - k)
\]
\[
= \pi(m)\mathbb{P}(Y_0 = m|X_0 = m)\mathbb{P}(X_1 = k|Y_0 = m).
\]

Two lines from the end, we used condition (4.1) and the fact that \( \frac{(1 - \beta)(1 - \gamma)}{1 - \alpha} = 1 \) (which follows from the definition of \( \gamma \)).

The other three cases follow similarly and we omit the details.

The stationary distribution for \( Y_n \) in (iii) follows from the distribution of \( X_n \) and the fact that \( Y_n = X_n + A_n \) with \( X_n \) and \( A_n \) independent (for example, multiply the generating functions).
Given the reversibility, the properties in (ii) and (iv) can be deduced using the same arguments that have been used to establish Burke’s theorem in various settings (originally by Reich for the continuous-time $M/M/1$ queue [11]).

First note that $D_n = Y_n - X_{n+1}$ and $A_n = Y_n - X_n$. Hence the reversibility property in (i) implies that $(D_n)_{n \in \mathbb{Z}}$ and $(A_n)_{n \in \mathbb{Z}}$ have the same distribution. But $A_n$ are i.i.d. random variables, so $(A_n)_{n \in \mathbb{Z}}$ and $(A_n)_{n \in \mathbb{Z}}$ in turn have the same distribution, giving (ii).

Now note that, by (2.3) for example, we can write $X_n$ as a function of $(A_i)_{i<n}$ and $(S_i)_{i<n}$. Hence $X_n$ is independent of $(A_i)_{i \geq n}$. But, using (i) again, the collection

$$(X_n; A_n, A_{n+1}, A_{n+2}, \ldots) = (X_n; Y_n - X_n, Y_{n+1} - X_{n+1}, Y_{n+2} - X_{n+2}, \ldots)$$

has the same distribution as the collection

$$(X_n; D_{n-1}, D_{n-2}, D_{n-3}, \ldots) = (X_n; Y_{n-1} - X_n, Y_{n-2} - X_{n-1}, Y_{n-3} - X_{n+2}, \ldots).$$

Thus indeed $X_n$ is independent of $(D_i)_{i<n}$ as required for (iv).

$\square$

4.1 Fixed points

Consider a queueing server defined by a given distribution of the service process. We may ask for distributions of the arrival process with the following property: when such an arrival process is fed into the queue (independently of the service process), the resulting departure process has the same law as the arrival process. Such a distribution of the arrival process is called a fixed point for the given service process.

Starting from Burke’s theorem for a continuous-time $M/M/1$ queue, questions concerning fixed points have been extensively studied in the context of single-server queues such as the model of Section 2.1 – see for example [9] and references therein. They have also been considered, although less often, in the context of the model of batch arrivals and services in discrete time considered here – see for example [4].

Part (ii) of Theorem 4.1 is such a fixed point result. Fix a service process of BerGeom type, specified by the parameters $q$ and $\beta$. Let $\mu = q/\beta = \mathbb{E} S_n$ be the service intensity. Then for each $\lambda < \mu$, there exists an arrival process which is a fixed point of the queue, and which has arrival intensity $\mathbb{E} A_n = \lambda$ (simply choose $p$ and $\alpha$ to satisfy $p/\alpha = \lambda$ along with condition (4.1) – there is a unique way to do this).

In fact, Theorem 5 of [4] implies that this gives the unique fixed-point arrival process which is ergodic with arrival intensity $\lambda$. Furthermore, this fixed point is attractive; loosely, this means that if any ergodic arrival process is fed into a tandem of queueing servers with this service distribution, the distribution of the resulting output process converges to the fixed point as the length of the tandem grows. See [4] for precise definitions.

We note in passing that if (4.1) is satisfied, then the distribution Ber($p$)Geom($\alpha$) has minimal relative entropy with respect to the distribution Ber($q$)Geom($\beta$), out of all distributions with mean $p/\alpha$. See the introduction of [4] for related discussions.

4.2 Tandems

Using Theorem 4.1 we can also describe the behaviour of systems of queues in tandem.
Consider a system of \( R \) queues in tandem. Each queue has an independent service process, \( S_{n}^{(r)} \) for the \( r \)th queue, and each of these processes is a collection of i.i.d. \( \text{Ber}(q)\text{Geom}(\beta) \) random variables.

The first queue has an arrival process \( A_{n}^{(1)} \), which is independent of the service processes and is a collection of i.i.d. \( \text{Ber}(p)\text{Geom}(\alpha) \) random variables. We assume that \( p, q, \alpha, \beta \) satisfy (4.1) and the stability condition \( p\beta < q\alpha \).

Now, recursively, let the arrival process to the \( r \)th queue be given by the departure process from the \((r-1)\)st queue, for \( r = 2, 3, \ldots, R \); that is, \( A_{n}^{(r)} = D_{n}^{(r-1)} \). Thus a customer departing from queue \( r-1 \) moves immediately (within the same time-slot) to the next queue.

Using Theorem 4.1 and well-known methods, we obtain the following result:

**Theorem 4.2**

(i) All the departure processes \( D^{(r)} \) have the same distribution, which is also the distribution of \( A_{n}^{(1)} \).

(ii) The vector \( X_{n}^{(1)}, X_{n}^{(2)}, \ldots, X_{n}^{(R)} \) of queue-lengths of the \( R \) queues at a fixed time \( n \) is a collection of i.i.d. random variables, whose common distribution is that given in Theorem 4.1(iii).

**Proof:** Part (i) is obtained by applying Theorem 4.1(ii) repeatedly. The argument to obtain the product form result in (ii) from Theorem 4.1(iv) is exactly the same as for the familiar case of \( M/M/1 \) queues in tandem – see for example Section 2.2 of [7].

The result also extends easily to cases where the parameters of the service process vary between queues: \( S_{n}^{(r)} \sim \text{Ber}(q_{r})\text{Geom}(\beta_{r}) \). However, all the pairs \( (q_{r}, \beta_{r}) \) must still belong to the same one-parameter family satisfying (4.1).

We could also consider a vector of “queue-lengths before service”, \( Y_{n}^{(r)} \). Observe that the way we have defined the system of queues in tandem, a customer may be present after arrival and before service in several different queues at the same time-slot (since a departure from queue \( r-1 \) at time \( n \) arrives at queue \( r \) at the same time \( n \)). So in this case, the corresponding result is in fact that \( Y_{n}^{(1)}, Y_{n-1}^{(2)}, \ldots, Y_{n-R+1}^{(R)} \) form an i.i.d. sequence. This may also be proved by similar methods.

### 4.3 General service-batch distributions

In order for the reversibility properties in Theorem 4.1(i),(ii),(iv) to hold, one needs the condition (4.1) relating the parameters of the distributions of arrival and service distributions. However, one may wonder whether this is necessary to have a result like Theorem 4.1(iii) on the stationary distribution of the queue-length.

In fact, such a property holds in a much more general case. We will still assume the same sort of arrival process, but now we will consider any service process which has i.i.d. entries which are non-negative integers.

**Theorem 4.3** Suppose \( (S_{n}) \) and \( (A_{n}) \) are both i.i.d. sequences taking non-negative integer values, and independent of each other, with \( \mathbb{E}S_{n} > \mathbb{E}A_{n} \).

(a) If \( A_{n} \) has a \( \text{Ber}()\text{Geom}() \) distribution, then both \( X_{n} \) and \( Y_{n} \) have \( \text{Ber}()\text{Geom}() \) distributions.
(b) If $A_n$ takes values 0 and 1 only, then $X_n$ has a Geom$^0$ distribution.

(c) If $A_n$ has a Geom$^0$ (respectively Geom$^+$) distribution, then also $Y_n$ has a Geom$^0$ (respectively Geom$^+$) distribution.

Parts (b) and (c) are both special cases of part (a). Part (c) was already observed in Proposition 12 of [2], and results like part (b) for $M/GI/1$ queues are certainly well known.

Proof: We will use a representation of the queue length as the future maximum of a random walk. Arguments of this kind are rather classical; for example, see the book of Takács [13] for many examples (often in the context of queueing theory).

Using (2.3), we can write

$$X_0 = \max_{m \geq 0} \sum_{r=1}^{m} (-S_{-r} + A_{-r}), \quad Y_0 = A_0 + \max_{m \geq 0} \sum_{r=1}^{m} (-S_{-r} + A_{-r}).$$

Consider for example part (b). $X_0$ is the maximum of the walk

$$0, -S_{-1} + A_{-1}, -S_{-1} + A_{-1} - S_{-2} + A_{-2}, \ldots.$$

The maximum is almost surely finite since the walk has negative drift. Any positive step of this walk has size exactly 1 (since the $A_n$ are 0 or 1 and the $S_n$ are non-negative). Hence any new maximum must be precisely 1 greater than the previous maximum. We may treat these maxima as renewal times; the future evolution of the walk (relative to its current position) has the same distribution as the original walk. Note that $X_0 \geq k$ iff this walk reaches level $k$ at some point. Hence we get

$$\mathbb{P}(X_0 \geq k+1|X_0 \geq k) = \mathbb{P}(X_0 \geq 1|X_0 \geq 0) = \mathbb{P}(X_0 \geq 1)$$

for all $k$. Thus $X_0$ indeed has a geometric distribution as desired (and by stationary the same is true of $X_n$ for all $n$).

For parts (a) we generalise this argument slightly. Now the arrival batches may have size greater than 1, but we will regard such a batch as a sequence of individual steps up, each of size 1. Since the arrival batches are BerGeom, we have the memoryless property for $A_n$: the distribution of $A_n - k$, conditional on $A_n \geq k$, is the same for all $k \geq 1$. We regard the walk as a sequence of steps up of size 1, separated perhaps by some number of jumps down (which may be 0). By the memoryless property, the jumps down which separate each pair of steps up form an i.i.d. sequence, and so we have a renewal property after each step up, and thus in particular after each new maximum. Thus $\mathbb{P}(X_0 \geq k+1|X_0 \geq k)$ doesn’t depend on $k$, for $k \geq 1$, and indeed $X_0$ has a BerGeom distribution. (The difference from the previous paragraph is that the distribution for $k = 0$ may be different; hence we get a BerGeom distribution in general rather than the Geom distribution we had in the specific case above). The same argument applies also to $Y_0$.

In the special case (c), the arrival batches are Geom$^+$ so that $Y_0$ must always be strictly positive; hence in fact $Y_0$ is itself Geom$^+$. If the arrival batches are Geom$^0$, we could add 1 to every arrival batch and to every service batch to arrive at the previous case; one obtains that $Y_0 + 1$ is Geom$^+$ and hence that $Y_0$ has a Geom$^0$ distribution. □
4.4 Continuous models

All the results above have equivalent versions in the case where geometric distributions are replaced by exponential distributions.

$X$ is said to have Ber($p$)Exp($\alpha$) distribution if

$$\mathbb{P}(X \geq x) = \begin{cases} 1, & x = 0 \\ pe^{-\alpha x}, & x > 0. \end{cases}$$

$X$ may be represented as the product of a Bernoulli random variable and an exponential random variable, or as the sum of a geometric number of i.i.d. exponential random variables.

Now one could write versions of Theorems 4.1 and 4.2 where the Ber()Geom() distributions are replaced by Ber()Exp() distributions. These continuous versions can be proved directly, or derived from the discrete versions by taking an appropriate limit under which the parameter of the geometric distribution tends to 0. The analogous condition in place of (4.1) is that $\alpha p/(1 - p) = \beta q/(1 - q)$. Theorem 4.3 extends similarly (and we no longer need to assume that the services $S_n$ take integer values).

An alternative extension is to systems in continuous time rather than discrete time. Write the Bernoulli parameters as $p = \epsilon \lambda$ and $q = \epsilon \mu$; now let $\epsilon \to 0$ and rescale time by $\epsilon$. This produces a model in which arrival and service batches occur at the times of independent Poisson processes, with parameters $\lambda$ and $\mu$ respectively. Again, analogous versions of all our main results can be straightforwardly formulated. Note that in this case, the distinction between queue-length after service and queue-length before service disappears.

These continuous limits, both in time and in workload, are also exploited in the next section in the context of first-passage percolation models.

4.5 Role of condition (4.1)

It may be helpful to give some brief comments about the relevance of condition (4.1) to the reversibility of the queue-length process as in Theorem 4.1.

Consider a “busy period” of the process, i.e. an excursion away from 0. Suppose that the sequence of arrival batches in the busy period is $a_1, a_2, \ldots, a_n$ and the sequence of departures is $d_1, d_2, \ldots, d_n$. We have $a_1 + \cdots + a_n = d_1 + \cdots + d_n$, and that $a_1 + \cdots + a_m > d_1 + \cdots + d_m$ for $m = 1, 2, \ldots, n - 1$. Note that this also gives in particular that $a_1 > 0$ and $d_n > 0$.

For reversibility of the queue, we need the likelihood of such an excursion to be invariant under time-reversal (in which the role of arrivals and departures is exchanged). This likelihood is given by

$$\mathbb{P}\left(X_0 = 0, A_1 = a_1, \ldots, A_n = a_n, D_1 = d_1, \ldots, D_n = d_n\right),$$

which may also be written as

$$\mathbb{P}\left(X_0 = 0, A_1 = a_1, \ldots, A_n = a_n, S_1 = d_1, \ldots, S_{n-1} = d_{n-1}, S_n \geq d_n\right).$$

Note that when we translate from the variables $D_i$ to the variables $S_i$, the last equality becomes an inequality, since it is at this point that the queue-length returns to 0 and so some part of the final service $S_n$ may be unused.
First consider the case where the arrivals are i.i.d. Geom\(^0(\alpha)\) and the services are i.i.d. Geom\(^0(\beta)\). Then the likelihood above is equal to
\[
\alpha^n (1 - \alpha)^{a_1 + \cdots + a_n} \beta^{n-1} (1 - \beta)^{d_1 + \cdots + d_n}.
\]
Since the sum of the \(a_i\) is equal to the sum of the \(d_i\), this is invariant under the exchange \((a_1, \ldots, a_n) \leftrightarrow (d_n, \ldots, d_1)\) as required.

Now consider the case where \(A_i \sim \text{Ber}(p)\text{Geom}(\alpha)\) and \(S_i \sim \text{Ber}(q)\text{Geom}(\beta)\). Now the likelihood above becomes
\[
p^n \alpha^n (1 - \alpha)^{a_1 + \cdots + a_n} \left(1 - \frac{p}{\alpha}\right)^{\#i:a_i=0} q^n \beta^{n-1} (1 - \beta)^{d_1 + \cdots + d_n} \left(1 - \frac{q}{\beta}\right)^{\#i:d_i=0}.
\]
Since in general the number of \(a_i\) which are zero may be different from the number of \(d_i\) which are zero, this likelihood is invariant under the exchange \((a_1, \ldots, a_n) \leftrightarrow (d_n, \ldots, d_1)\) only if condition \([4.1]\) holds. Hence \([4.1]\) is also necessary for reversibility of the queue-length process.

By decomposing the queue-length process into its excursions and arguing in this way, we could in fact arrive at a proof of Theorem \([4.1]\) which avoided many of the calculations needed in the proof given above (at the expense of complicating the structure of the proof a little).

The following property is also related to the discussion above. If \(A \sim \text{Geom}\(^0(\alpha)\)\), then the ratio \(\mathbb{P}(A = k + 1)/\mathbb{P}(A = k)\) is the same for all \(k \geq 0\), namely \((1 - \alpha)\). If instead \(A \sim \text{Ber}(p)\text{Geom}(\alpha)\), then the same is true except for \(k = 0\); in the case \(k = 0\), the ratio is multiplied by a further factor \(\frac{\alpha}{1 - \alpha} \frac{p}{1 - p}\). Condition \([4.1]\) says that this “adjustment factor” is the same for the distribution of arrivals as it is for the distribution of services.

5 First-passage percolation models

In this section we consider various directed first-passage percolation models, and use Theorems \([4.1]\) and \([4.2]\) to calculate exact values for time constants.

For \((i, j) \leq (k, l) \in \mathbb{Z}^2\), denote by \(\Pi((i, j), (k, l))\) the set of “directed paths” \((i, r_1), (i + 1, r_2), \ldots, (k, r_{k-i+1})\), where \(l \leq r_1 \leq r_2 \leq \cdots \leq r_k - i + 1 \leq l\). These paths are strictly increasing in the first coordinate, and weakly increasing in the second coordinate. See Figure \([5]\) for an example.

Let \(S_n^\gamma\) be a collection of i.i.d. random variables, and for each path \(\gamma \in \Pi((i, j), (k, l))\), define the weight of the path \(\gamma\) by \(S(\gamma) = \sum_{(n,r) \in \gamma} S_n^\gamma\). Now we define the first-passage time from \((i, j)\) to \((k, l)\) as the minimum weight over all paths from \((i, j)\) to \((k, l)\):
\[
F((i, j), (k, l)) = \min_{\gamma \in \Pi((i, j), (k, l))} S(\gamma).
\]  
(5.1)

This model has various possible alternative presentations, for example in \([12]\) as a first-passage percolation model with weights on the edges, where weights on vertical edges are all equal to a constant and weights on horizontal edges are i.i.d.

By Kingman’s subadditive ergodic theorem, for any \(x > 0\), there exists a constant \(f(x)\) such that
\[
\frac{1}{N} F((0,0), ([xN],N)) \to f(x)
\]  
(5.2)
almost surely.

In [12], it is shown that if the random variables $S^n_r$ have $\text{Ber}(q)$ distribution, then

$$f(x) = \begin{cases} 
0, & x \leq (1-q)/q, \\
\left(\sqrt{qx} - \sqrt{1-q}\right)^2, & x > (1-q)/q.
\end{cases} \quad (5.3)$$

In [10], related methods are used to show that if the $S^n_r$ have $\text{Geom}(\beta)$ distribution, then

$$f(x) = \begin{cases} 
0, & x \leq \beta/(1-\beta), \\
\frac{1}{\beta} \left(\sqrt{1-\beta\sqrt{1+x}} - 1\right)^2, & x > \beta/(1-\beta),
\end{cases} \quad (5.4)$$

while if the $S^n_r$ have $\text{Exp}(1)$ distribution then

$$f(x) = \left(\sqrt{1+x} - 1\right)^2. \quad (5.5)$$

The method of [10] exploits a link between the percolation model and the system of batch queues in tandem of the sort described in Section 4.2. Using this method, we can extend the results above to the case of a $\text{Ber}()\text{Geom}()$ distribution. As suggested by the notation, the weights in the percolation problem correspond to service times in the queueing model.

Fix $q$ and $\beta$ and assume that all the $S^n_r$ are i.i.d. $\text{Ber}(q)\text{Geom}(\beta)$. In this case the service rate at each queue is $\mu = q/\beta$. For any $\lambda < \mu$, we can choose $p$ and $\alpha$ satisfying (4.1) and such that $p/\alpha = \lambda$. If the arrival batches are i.i.d. $\text{Ber}(p)\text{Geom}(\alpha)$ then the arrival rate is $\lambda$.

(Rather than choosing $\lambda < \mu$ directly, we may equivalently choose $\alpha > \beta$ or choose $p < q$. To express one of the three variables $\alpha, p, \lambda$ in terms of another, we have, as well as (4.1), that

$$\lambda = \frac{p}{\alpha} = p \left[ \frac{p}{1-p} - \frac{1-q}{q} \frac{1-\beta}{\beta} \right] + 1, \quad (5.6)$$

$$\lambda = \frac{(1-\alpha)\beta q}{\alpha^2(1-\beta - q) + \alpha\beta q}. \quad (5.7)$$

Recall that $\beta$ and $q$ are to be regarded as fixed throughout).

Now the results of Theorems 4.1 and 4.2 apply. In particular, the queue lengths $X^1_0, \ldots, X^n_0$ are i.i.d., and their expectation is given by

$$E X^\alpha_0 = \frac{\beta}{\alpha - \beta} \frac{1-\alpha}{\alpha}. \quad (5.8)$$
We may regard this expectation as a function of the arrival rate $\lambda$ and write it as $h(\lambda)$ to emphasise this. We also have

$$h(\lambda) = \frac{p}{1-p} \frac{(1-q)}{q} \left[ \frac{p(1-q)}{\beta(q-p)} + 1 \right]. \quad (5.9)$$

Now, in Section 3 of [10], it is shown, by working recursively from representations such as (2.3), that

$$\sum_{r=1}^{R} X_0^r = \sup_{m \leq 0} \left\{ -1 \sum_{r=m}^{\infty} A_r - F((m,1),(-1,R)) \right\},$$

and that by passing to the limit $R \to \infty$ and taking a Legendre transform, one obtains

$$f(x) = \sup_{0 < \lambda < \mu} \{ \lambda x - h(\lambda) \}. \quad (5.10)$$

We apply this result to various cases in turn.

**Example 1.** The weights $S_n^r$ have Ber($q$)Geom($\beta$) distribution. This is essentially the most general case of the ones we treat: all the others will be derived by taking some sort of limit from this case.

Using (5.10) and plugging in (5.6)-(5.9), we get

$$f(x) = \frac{1}{\beta q} \sup_{p \in (0,q)} \left\{ p \left[ p(1-q) + (q-p)\beta \right] \right\} \left[ x - \frac{1}{\beta q} \right]. \quad (5.11)$$

or alternatively

$$f(x) = \beta \sup_{\alpha \in (\beta,1)} \frac{1 - \alpha}{\alpha} \left[ \frac{qx}{\alpha(1-\beta-q) + \beta q} - \frac{1}{\alpha - \beta} \right]. \quad (5.12)$$

In principle one could solve a quartic equation to put these expressions into closed form, but the result is unlikely to be pretty. However, it is straightforward to show that $f(x) = 0$ if $x < (1-q)/q$ and $f(x) > 0$ otherwise.

**Example 2.** Now consider the case where the common distribution of the weights is Ber($q$)Exp(1). To obtain this case we can let $\beta \to 0$ in the previous example and multiply by $\beta$. We obtain

$$f(x) = \sup_{0 < r < 1} r^2 \left[ \frac{qx}{1-q+rq} - \frac{1}{1-r} \right].$$

**Example 3.** Now we consider a model where space becomes continuous in one direction. Consider taking the Bernoulli parameter $q$ to 0, and the space parameter $x$ to infinity. We arrive at a model where the first space parameter $i$ is replaced by a continuous parameter. For each $r$, we have a “service process” $S^r(t)$. This process is a jump process; events occur at times of a Poisson process of rate 1, say, and to each event is associated a weight, which is the amount by which the process $S^r$ jumps up at the time of the event. These weights are independent and each has Geom($\beta$) distribution. In the queueing model, the weight occurring at time $t$ in the process $S^r$ corresponds to the amount of service available at queue $r$ at time $t$. 

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The first-passage time can now be defined by
\[
\tilde{F}((s, j), (t, l)) = \inf_{s = u_j < u_{j+1} < \cdots < u_l < u_{l+1} = t} \sum_{r=j}^{l} [S^r(u_{j+1}) - S^r(u_j)],
\] (5.13)
and the time constants by
\[
\tilde{f}(y) = \lim_{N \to \infty} \frac{1}{N} \tilde{F}\left((0, 0), (\lfloor Ny \rfloor, N)\right),
\] (5.14)
which, as at (5.2), are a.s. constant for each \(y\).

To obtain this case from (5.11), we let \(q \to 0\) and set \(x = y/q\). We obtain
\[
\tilde{f}(y) = \beta \sup_{\alpha \in (\beta, 1)} \frac{1 - \alpha}{\alpha} \left[ \frac{y}{\alpha(1 - \beta)} - \frac{1}{\alpha - \beta} \right].
\]

**Example 4.** We can take the two limits of Example 2 and Example 3 together. Now the service processes will consist of weights occurring at times of a Poisson process, with each weight having \(\text{Exp}(1)\) distribution. In this case we get
\[
\tilde{f}(y) = \sup_{0 < r < 1} r^2 \left[ y - \frac{1}{1 - r} \right].
\]
In this final case the translation into closed form is more reasonable; one only needs to solve a quadratic equation, to obtain
\[
\tilde{f}(y) = \begin{cases} 
0, & y \leq 1 \\
\frac{1}{8y^2} \left[ 8y^3 + 20y^2 + 7y + 1 - \sqrt{8y + 1} \left( 8y^2 + 3y + 1 \right) \right], & y > 1.
\end{cases}
\]

Taking certain other limits or special cases in these examples recovers previously known results. Taking \(q = 1 - \beta\) in (5.11) gives the case of \(\text{Geom}(\beta)\) weights and leads to (5.4), and further taking \(\beta \to 0\) and multiplying by \(\beta\) gives the case of \(\text{Exp}(1)\) weights and leads to (5.5). On the other hand, taking \(\beta \to 1\) in (5.11) gives \(\text{Bernoulli}(q)\) weights and leads to (5.3).

One could also consider the continuous model of Examples 3 and 4 in the case where each weight has value 1, so that the service processes are simply Poisson processes. To do this we take \(\beta \to 1\) in Example 3, to obtain simply
\[
\tilde{f}(y) = \left( \lfloor \sqrt{y} - 1 \rfloor \right)^2.
\]

Finally, by taking an appropriate continuum limit in any of these cases, one can arrive at the Brownian first-passage percolation model which has been quite widely studied (see for example [1], [5]).

**Acknowledgments**

Many thanks to the referee for helpful comments, and to Louigi Addario-Berry for suggesting reference [13]. Some of the work on this paper was carried out at the Institut Henri Poincaré in Paris during the programme Interacting Particle Systems, Statistical Mechanics and Probability Theory; I am very grateful to the IHP for its hospitality and to INRIA for financial support during my stay there. The work was also supported by an EPSRC Advanced Fellowship.
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