Low Rank Matrix-valued Chernoff Bounds and Approximate Matrix Multiplication

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Abstract
In this paper we develop algorithms for approximating matrix multiplication with respect to the spectral norm. Let \( A \in \mathbb{R}^{n \times m} \) and \( B \in \mathbb{R}^{n \times p} \) be two matrices and \( \varepsilon > 0 \). We approximate the product \( A^\dagger B \) using two sketches \( \tilde{A} \in \mathbb{R}^{t \times m} \) and \( \tilde{B} \in \mathbb{R}^{t \times p} \), where \( t \ll n \), such that
\[
\| \tilde{A}^\dagger \tilde{B} - A^\dagger B \|_2 \leq \varepsilon \| A \|_2 \| B \|_2
\]
with high probability. We analyze two different sampling procedures for constructing \( \tilde{A} \) and \( \tilde{B} \); one of them is done by i.i.d. non-uniform sampling rows from \( A \) and \( B \) and the other by taking random linear combinations of their rows. We prove bounds on \( t \) that depend only on the intrinsic dimensionality of \( A \) and \( B \), that is their rank and their stable rank.

For achieving bounds that depend on rank when taking random linear combinations we employ standard tools from high-dimensional geometry such as concentration of measure arguments combined with elaborate \( \varepsilon \)-net constructions. For bounds that depend on the smaller parameter of stable rank this technology itself seems weak. However, we show that in combination with a simple truncation argument it is amenable to provide such bounds. To handle similar bounds for row sampling, we develop a novel matrix-valued Chernoff bound inequality which we call low rank matrix-valued Chernoff bound. Thanks to this inequality, we are able to give bounds that depend only on the stable rank of the input matrices.

We highlight the usefulness of our approximate matrix multiplication bounds by supplying two applications. First we give an approximation algorithm for the \( \ell_2 \)-regression problem that returns an approximate solution by randomly projecting the initial problem to dimensions linear on the rank of the constraint matrix. Second we give improved approximation algorithms for the low rank matrix approximation problem with respect to the spectral norm.

1 Introduction
In many scientific applications, data is often naturally expressed as a matrix, and computational problems on such data are reduced to standard matrix operations including matrix multiplication, \( \ell_2 \)-regression, and low rank matrix approximation.

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sampling matrices, i.e., samples that are supported on only one entry \[ \text{[AHK06, AM07, DZ10]} \] or samples that are obtained by the outer-product of the sampled rows or columns \[ \text{DKM06a, RV07} \], therefore condition (b) is often natural to assume. By incorporating the rank assumption of the matrix samples on the above matrix-valued inequalities we are able to develop a “dimension-free” matrix-valued Chernoff bound. See Theorem \[ \text{[L21]} \] for more details.

Fundamental to the applications we derive, are two probabilistic tools that provide concentration bounds of certain random matrices. These tools are inherently different, where each pertains to a different sampling procedure. In the first, we multiply the input matrix by a random sign matrix, whereas in the second we sample rows according to a distribution that depends on the input matrix. In particular, the first method is oblivious (the probability space does not depend on the input matrix) while the second is not.

The first tool is the so-called subspace Johnson-Lindenstrauss lemma. Such a result was obtained in \[ \text{Sar06} \] (see also \[ \text{Cla08, Theorem 1.3} \]) although it appears implicitly in results extending the original Johnson Lindenstrauss lemma (see \[ \text{Mag07} \]). The techniques for proving such a result with possible worse bound are not new and can be traced back even to Milman’s proof of Dvoretzky theorem \[ \text{M71} \].

**Lemma 1.1. (Subspace JL lemma \[ \text{Sar06} \])** Let \( W \subseteq \mathbb{R}^d \) be a linear subspace of dimension \( k \) and \( \varepsilon \in (0,1/3) \). Let \( R \) be a \( t \times d \) random sign matrix rescaled by \( 1/\sqrt{t} \), namely \( R_{ij} = \pm 1/\sqrt{t} \) with equal probability. Then

\[
P \left( 1 - \varepsilon \right) \|w\|_2^2 \leq \|RW\|_2^2 \leq (1 + \varepsilon) \|w\|_2^2, \text{ \forall } w \in W
\]

(1.1)

\[
\geq 1 - c_2 \exp(-c_1 \varepsilon^2 t),
\]

where \( c_1 > 0, c_2 > 1 \) are constants.

The importance of such a tool is that it allows us to get bounds on the necessary dimensions of the rank matrix in terms of the rank of the input matrices, see Theorem \[ \text{[L21]} (i.a) \].

While the assumption that the input matrices have low rank is a fairly reasonable assumption, one should be a little cautious as the property of having low rank is not robust. Indeed, if random noise is added to a matrix, even if low rank, the matrix obtained will have full rank almost surely. On the other hand, it can be shown that the added noise cannot distort the Frobenius and operator norm significantly; which makes the notion of *stable rank* robust and so the assumption of low stable rank on the input is more applicable than the low rank assumption.

Given the above discussion, we resort to a different methodology, called matrix-valued Chernoff bounds. These are non-trivial generalizations of the standard Chernoff bounds over the reals and were first introduced in \[ \text{AW02} \]. Part of the contribution of the current work is to show that such inequalities, similarly to their real-valued ancestors, provide powerful tools to analyze randomized algorithms. There is a rapidly growing line of research exploiting the power of such inequalities including matrix approximation by sparsification \[ \text{AM07, DZ10} \]; analysis of algorithms for matrix completion and decomposition of low rank matrices \[ \text{CR07, Gro09, Rec09} \]; and semi-definite relaxation and rounding of quadratic maximization problems \[ \text{Nem07, So09a, So09b} \].

The quality of these bounds can be measured by the number of samples needed in order to obtain small error probability. The original result of \[ \text{AW02, Theorem 19} \] shows that if \( M \) is distributed according to some distribution over \( n \times n \) matrices with zero mean and if \( M_1, \ldots, M_t \) are independent copies of \( M \) then for any \( \varepsilon > 0 \),

\[
P \left( \left\| \frac{1}{t} \sum_{i=1}^t M_i \right\|_2 > \varepsilon \right) \leq n \exp \left( -C \frac{\varepsilon^2 t}{\gamma^2} \right),
\]

(1.2)

where \( \|M\|_2 \leq \gamma \) holds almost surely and \( C > 0 \) is an absolute constant.

Notice that the number of samples in Ineq. (1.2) depends logarithmically in \( n \). In general, unfortunately, such a dependency is inevitable: take for example a diagonal random sign matrix of dimension \( n \). The operator norm of the sum of \( t \) independent samples is precisely the maximum deviation among \( n \) independent random walks of length \( t \). In order to achieve a fixed bound on the maximum deviation with constant probability, it is easy to see that \( t \) should grow logarithmically with \( n \) in this scenario.

In their seminal paper, Rudelson and Vershynin provide a matrix-valued Chernoff bound that avoids the dependency on the dimensions by assuming that the matrix samples are the outer product \( x \otimes x \) of a randomly distributed vector \( x \) \[ \text{RV07} \]. It turns out that this assumption is too strong in most applications, such as the ones we study in this work, and so we wish to relax it without increasing the bound significantly.

In the following theorem we replace this assumption with that of having low rank. We should note that we

\footnote{For ease of presentation we actually provide the restatement presented in \[ \text{WX08, Theorem 2.6} \], which is more suitable for this discussion.}

\footnote{Zero mean means that the (matrix-valued) expectation is the zero \( n \times n \) matrix.}
are not aware of a simple way to extend Theorem 3.1 of [RV07] to the low rank case, even constant rank. The main technical obstacle is the use of the powerful Rudelson selection lemma, see [Rud99] or Lemma 3.5 of [RV07], which applies only for Rademacher sums of outer product of vectors. We bypass this obstacle by proving a more general lemma, see Lemma 6.2. The proof of Lemma 6.2 relies on the non-commutative Khintchine moment inequality [LPS06, Bar01], which is also the backbone in the proof of Rudelson’s selection lemma. With Lemma 6.2 at our disposal, the proof techniques of [RV07] can be adapted to support our more general condition.

Theorem 1.1. Let \( 0 < \varepsilon < 1 \) and \( M \) be a random symmetric real matrix with \( \|E M\|_2 \leq 1 \) and \( \|M\|_2 \leq \gamma \) almost surely. Assume that each element on the support of \( M \) has at most rank \( r \). Set \( t = \Omega(\gamma \log(\gamma/\varepsilon^2)/\varepsilon^2) \). If \( r \leq t \) holds almost surely, then
\[
P\left( \left\| \frac{1}{t} \sum_{i=1}^{t} M_i - EM \right\|_2 > \varepsilon \right) \leq \frac{1}{\text{poly}(t)},
\]
where \( M_1, M_2, \ldots, M_t \) are i.i.d. copies of \( M \).

Proof. See Appendix, page 12.

Remark 1. (Optimality) The above theorem cannot be improved in terms of the number of samples required without changing its form, since in the special case where the rank of the samples is one it is exactly the statement of Theorem 3.1 of [RV07], see [RV07, Remark 3.4].

We highlight the usefulness of the above main tools by first proving a “dimension-free” approximation algorithm for matrix multiplication with respect to the spectral norm (Section 3.1). Utilizing this matrix multiplication bound we get an approximation algorithm for the \( \ell_2 \)-regression problem which returns an approximate solution by randomly projecting the initial problem to dimensions linear on the rank of the constraint matrix (Section 3.2). Finally, in Section 3.3 we give improved approximation algorithms for the low rank matrix approximation problem with respect to the spectral norm, and moreover answer in the affirmative a question left open by the authors of [NDT09].

2 Preliminaries and Definitions

The next discussion reviews several definitions and facts from linear algebra; for more details, see [SS90, GV96, Bh99]. We abbreviate the terms independently and identically distributed and almost surely with i.i.d. and a.s., respectively. We let \( S_n^{-1} := \{ x \in \mathbb{R}^n \mid \|x\|_2 = 1 \} \) be the \( (n-1) \)-dimensional sphere. A random Gaussian matrix is a matrix whose entries are i.i.d. standard Gaussians, and a random sign matrix is a matrix whose entries are independent Bernoulli random variables, that is they take values from \( \{\pm 1\} \) with equal probability. For a matrix \( A \in \mathbb{R}^{n \times m} \), \( A_{(i)} \), \( A^{(j)} \), denote the \( i \)'th row, \( j \)'th column, respectively. For a matrix with rank \( r \), the Singular Value Decomposition (SVD) of \( A \) is the decomposition of \( A \) as \( U \Sigma V^T \) where \( U \in \mathbb{R}^{n \times r} \), \( V \in \mathbb{R}^{m \times r} \) where the columns of \( U \) and \( V \) are orthonormal, and \( \Sigma = \text{diag}(\sigma_1(A), \ldots, \sigma_r(A)) \) is \( r \times r \) diagonal matrix. We further assume \( \sigma_1 \geq \ldots \geq \sigma_r > 0 \) and call these real numbers the singular values of \( A \). By \( A_k = U_k \Sigma_k V_k^T \) we denote the best rank \( k \) approximation to \( A \), where \( U_k \) and \( V_k \) are the matrices formed by the first \( k \) columns of \( U \) and \( V \), respectively. We denote by \( \|A\|_2 = \max\{|\langle Ax, x \rangle|_2 \mid \|x\|_2 = 1\} \) the spectral norm of \( A \), and by \( \|A\|_F = \sqrt{\sum_{i,j} A_{ij}^2} \) the Frobenius norm of \( A \). We denote by \( A^\dagger \) the Moore-Penrose pseudo-inverse of \( A \), i.e., \( A^\dagger = V \Sigma^{-1} U^T \). Notice that \( \sigma_1(A) = \|A\|_2 \). Also we define by \( \text{sr}(A) := \|A\|_F^2 / \|A\|_2^2 \) the stable rank of \( A \). Notice that the inequality \( \text{sr}(A) \leq \text{rank}(A) \) always holds. The orthogonal projector of a matrix \( A \) onto the row-space of a matrix \( C \) is denoted by \( P_C(A) = AC^\dagger C \). By \( P_{C,k}(A) \) we define the best rank-\( k \) approximation of the matrix \( P_C(A) \).

3 Applications

All the proofs of this section have been deferred to Section 4.

3.1 Matrix Multiplication

The seminal research of [FKV04] focuses on using non-uniform row sampling to speed-up the running time of several matrix computations. The subsequent developments of [DKM06a, DKM06b, DKM06c] also study the performance of Monte-Carlo algorithms on primitive matrix algorithms including the matrix multiplication problem with respect to the Frobenius norm. Sarlos [Sar06] extended (and improved) this line of research using random projections. Most of the bounds for approximating matrix multiplication in the literature are mostly with respect to the Frobenius norm [DKM06a, Sar06, CW09]. In some cases, the techniques that are utilized for bounding the Frobenius norm also imply weak bounds for the spectral norm, see [DKM06a, Theorem 4] or [Sar06, Corollary 11] which is similar with part (i.a) of Theorem 3.1.2.

In this section we develop approximation algorithms for matrix multiplication with respect to the spectral norm. The algorithms that will be presented in this section are based on the tools mentioned in Section 4.
Table 1: Summary of matrix-valued Chernoff bounds. \( M_1, \ldots, M_t \) are i.i.d. copies of \( M \).

Before stating our main dimension-free matrix multiplication theorem (Theorem 3.2), we discuss the best possible bound that can be achieved using the current known matrix-valued inequalities (to the best of our knowledge). Consider a direct application of Ineq. (32), where a similar analysis with that in proof of Theorem 3.4 (i) would allow us to achieve a bound of \( \Omega(\sqrt{m} \log(m+p)/\varepsilon^2) \) on the number of samples (details omitted). However, as the next theorem indicates (proof omitted) we can get linear dependency on the stable rank of the input matrices gaining from the “variance information” of the samples; more precisely, this can be achieved by applying the matrix-valued Bernstein inequality see e.g. [GLP+09, Rec09, Theorem 3.2] or [Ito10, Theorem 2.10].

**Theorem 3.1.** Let \( 0 < \varepsilon < 1/2 \) and let \( A, B \in \mathbb{R}^{n \times m}, B \in \mathbb{R}^{n \times p} \) both having stable rank at most \( \tilde{r} \). The following hold:

(i) Let \( R \) be a \( t \times n \) random sign matrix rescaled by \( 1/\sqrt{t} \). Denote by \( \tilde{A} = RA \) and \( \tilde{B} = RB \). If \( t = \Omega(\tilde{r} \log(m+p)/\varepsilon^2) \) then

\[
\Pr \left( \left\| \tilde{A}^\top \tilde{B} - A^\top B \right\|_2 \leq \varepsilon \left\| A \right\|_2 \left\| B \right\|_2 \right) \geq 1 - \frac{1}{\text{poly}(\tilde{r})}.
\]

(ii) Let \( p_i = \left\| A(i) \right\|_2 \left\| B(i) \right\|_2 / S \), where \( S = \sum_{i=1}^{n} \left\| A(i) \right\|_2 \left\| B(i) \right\|_2 \) be a probability distribution over \( [n] \). If we form a \( t \times m \) matrix \( \tilde{A} \) and a \( t \times p \) matrix \( \tilde{B} \) by taking \( t = \Omega(\tilde{r} \log(m+p)/\varepsilon^2) \) i.i.d. (row indices) samples from \( p_i \), then

\[
\Pr \left( \left\| \tilde{A}^\top \tilde{B} - A^\top B \right\|_2 \leq \varepsilon \left\| A \right\|_2 \left\| B \right\|_2 \right) \geq 1 - \frac{1}{\text{poly}(\tilde{r})}.
\]

Notice that the above bounds depend linearly on the stable rank of the matrices and logarithmically on their dimensions. As we will see in the next theorem we can remove the dependency on the dimensions, and replace it with the stable rank. Recall that in most cases matrices do have low stable rank, which is much smaller that their dimensionality.

**Theorem 3.2.** Let \( 0 < \varepsilon < 1/2 \) and let \( A \in \mathbb{R}^{n \times m}, B \in \mathbb{R}^{n \times p} \) both having rank and stable rank at most \( r \) and \( \tilde{r} \), respectively. The following hold:

(i) Let \( R \) be a \( t \times n \) random sign matrix rescaled by \( 1/\sqrt{t} \). Denote by \( \tilde{A} = RA \) and \( \tilde{B} = RB \).

\[
\text{(a)} \quad \text{If } t = \Omega(r/\varepsilon^2) \text{ then } \Pr(\forall x \in \mathbb{R}^m, y \in \mathbb{R}^p, |x^\top (\tilde{A}^\top \tilde{B} - A^\top B)y| \leq \varepsilon \left\| A \right\|_2 \left\| B \right\|_2) \geq 1 - e^{-\Omega(r)}.
\]

\[
\text{(b)} \quad \text{If } t = \Omega(\tilde{r}/\varepsilon^4) \text{ then } \Pr \left( \left\| \tilde{A}^\top \tilde{B} - A^\top B \right\|_2 \leq \varepsilon \left\| A \right\|_2 \left\| B \right\|_2 \right) \geq 1 - e^{-\Omega(\tilde{r}/\varepsilon^2)}.
\]

(ii) Let \( p_i = \left\| A(i) \right\|_2 \left\| B(i) \right\|_2 / S \), where \( S = \sum_{i=1}^{n} \left\| A(i) \right\|_2 \left\| B(i) \right\|_2 \) be a probability distribution over \( [n] \). If we form a \( t \times m \) matrix \( \tilde{A} \) and a \( t \times p \) matrix \( \tilde{B} \) by taking \( t = \Omega(\tilde{r} \log(r/\varepsilon^2)/\varepsilon^2) \) i.i.d. (row indices) samples from \( p_i \), then

\[
\Pr \left( \left\| \tilde{A}^\top \tilde{B} - A^\top B \right\|_2 \leq \varepsilon \left\| A \right\|_2 \left\| B \right\|_2 \right) \geq 1 - \frac{1}{\text{poly}(\tilde{r})}.
\]

**Remark 2.** In part (ii), we can actually achieve the stronger bound of \( t = \Omega(\sqrt{sr(A)} \log(sr(A)) sr(B)/\varepsilon^4) \) (see proof). However, for ease of presentation and comparison we give the above displayed bound.

Part (i,b) follows from (i,a) via a simple truncation argument. This was pointed out to us by Mark Rudelson (personal communication). To understand the significance and the differences between the different components of this theorem, we first note that the probabilistic event of part (i,a) is superior to the probabilistic event of (i,b) and (ii). Indeed, when \( B = A \) the former implies that \( |x^\top (A^\top A - A^\top A)x| < \varepsilon \cdot x^\top A^\top A x \) for every \( x \), which is stronger than \( \left\| A^\top A - A^\top A \right\|_2 \leq \varepsilon \left\| A \right\|_2^2 \). We will heavily exploit this fact in Section 4.3.1 to prove Theorem 3.4 (i,a) and (ii). Also notice that part (i,b) is
essential computationally inferior to (ii) as it gives the same bound while it is more expensive computationally to multiply the matrices by random sign matrices than just sampling their rows. However, the advantage of part (i) is that the sampling process is oblivious, i.e., does not depend on the input matrices.

3.2 \(\ell_2\)-regression In this section we present an approximation algorithm for the least-squares regression problem; given an \(n \times m\), \(n > m\), real matrix \(A\) of rank \(r\) and a real vector \(b \in \mathbb{R}^n\) we want to compute \(x_{\text{opt}} = A^\dagger b\) that minimizes \(\|Ax - b\|_2\) over all \(x \in \mathbb{R}^m\). In their seminal paper [DMM06], Drineas et al. show that if we improve the above to \(t = \Omega(m \log m / \varepsilon^2)\) rows from \(A\) and \(b\), then with high probability the optimum solution of the \(t \times d\) sampled problem will be within \((1 + \varepsilon)\) close to the original problem. The main drawback of their approach is that finding or even approximating the sampling probabilities is computationally intractable. Sarlos [Sar06] improved the above to \(t = \Omega(m \log m / \varepsilon^2)\) and gave the first \(o(nm^2)\) relative error approximation algorithm for this problem.

In the next theorem we eliminate the extra \(\log m\) factor from Sarlos bounds, and more importantly, reargue that Theorem 3.2 (i.a) that the sampling problem is oblivious, i.e., does not depend on the input matrices.

- If \(t = \Omega(r / \varepsilon^2)\), then with high probability,

\[
\|x_{\text{opt}} - \bar{x}_{\text{opt}}\|_2 \leq \frac{\varepsilon}{\sigma_{\min}(A)} \|b - Ax_{\text{opt}}\|_2.
\]

Remark 3. The above result can be easily generalized to the case where \(b\) is an \(n \times p\) matrix of rank at most \(r\) (see proof). This is known as the generalized \(\ell_2\)-regression problem in the literature, i.e., \(\arg \min_{X \in \mathbb{R}^{nm}} \|AX - B\|_2\) where \(B\) is an \(n \times p\) rank \(r\) matrix.

3.3 Spectral Low Rank Matrix Approximation

A large body of work on low rank matrix approximations [DK03, FKV04, DRVW06, Sar06, RV07, AM07, RST09, CW09, NDT09, HMT09] has been recently developed with main objective to develop more efficient algorithms for this task. Most of these results study approximation algorithms with respect to the Frobenius norm, except for [RV07, NDT09] that handle the spectral norm.

In this section we present two \((1 + \varepsilon)\)-relative-error approximation algorithms for this problem with respect to the spectral norm, i.e., given an \(n \times m\), \(n > m\), real matrix \(A\) of rank \(r\) we wish to compute \(A_k = U_k \Sigma_k V_k^\top\), which minimizes \(\|A - X_k\|_2\) over the set of \(n \times m\) matrices of rank \(k\), \(X_k\). The first additive bound for this problem was obtained in [RV07]. To the best of our knowledge the best relative bound was recently achieved in [NDT09, Theorem 1]. The latter result is not directly comparable with ours, since it uses a more restricted projection methodology and so their bound is weaker compared to our results. The first algorithm randomly projects the rows of the input matrix onto \(t\) dimension. Here, we set \(t = \Omega(\log(r / \varepsilon^2))\) in which case we get an \((1 + \varepsilon)\) error guarantee, or to be \(\Omega(k / \varepsilon^2)\) in which case we show a \((2 + \varepsilon \sqrt{(r - k) / k})\) error approximation. In both cases the algorithm succeeds with high probability. The second approximation algorithm samples non-uniformly \(\Omega(r \log(r / \varepsilon^2) / \varepsilon^2)\) rows from \(A\) in order to satisfy the \((1 + \varepsilon)\) guarantee with high probability.

The following lemma (Lemma 3.1) is essential for proving both relative error bounds of Theorem 3.3. It gives a sufficient condition that any matrix \(A\) should satisfy in order to get a \((1 + \varepsilon)\) spectral low rank matrix approximation of \(A\) for every \(k\), \(1 \leq k \leq \text{rank}(A)\).

Lemma 3.1. Let \(A\) be an \(n \times m\) matrix and \(\varepsilon > 0\). If there exists a \(t \times m\) matrix \(\hat{A}\) such that for every \(x \in \mathbb{R}^m\), \((1 - \varepsilon)x^\top \hat{A}^\top Ax \leq x^\top \hat{A}^\top \hat{A}x \leq (1 + \varepsilon)x^\top A^\top Ax\), then

\[
\left\|A - P_{\hat{A},k}(A)\right\|_2 \leq (1 + \varepsilon) \left\|A - A_k\right\|_2,
\]

for every \(k = 1, \ldots, \text{rank}(A)\).
Theorem 3.4. Let $0 < \varepsilon < 1/3$ and let $A = U \Sigma V^\top$ be a real $n \times m$ matrix of rank $r$ with $n \geq m$.

(i) (a) Let $R$ be a $t \times n$ random sign matrix rescaled by $1/\sqrt{t}$ and set $\tilde{A} = RA$. If $t = \Omega(r/\varepsilon^2)$, then with high probability

$$\left\| A - P_{\tilde{A},k}(A) \right\|_2 \leq (1 + \varepsilon) \| A - A_k \|_2,$$

for every $k = 1, \ldots, r$.

(b) Let $R$ be a $t \times n$ random Gaussian matrix rescaled by $1/\sqrt{t}$ and set $\tilde{A} = RA$. If $t = \Omega(k/\varepsilon^2)$, then with high probability

$$\left\| A - P_{A,k}(A) \right\|_2 \leq (2 + \varepsilon) \sqrt{\frac{r - k}{k}} \| A - A_k \|_2.$$

(ii) Let $p_i = \| U(i) \|_2^2 / r$ be a probability distribution over $[n]$. Let $\tilde{A}$ be a $t \times m$ matrix that is formed (row-by-row) by taking $t$ i.i.d. samples from $p_i$ and rescaled appropriately. If $t = \Omega(r \log(r/\varepsilon^2)/\varepsilon^2)$, then with high probability

$$\left\| A - P_{\tilde{A},k}(A) \right\|_2 \leq (1 + \varepsilon) \| A - A_k \|_2,$$

for every $k = 1, \ldots, r$.

We should highlight that in part (ii) the probability distribution $p_i$ is in general hard to compute. Indeed, computing $\| U(i) \|_2^2$ requires computing the SVD of $A$. In general, these values are known as statistical leverage scores by DM10. In the special case where $A$ is an edge-vertex matrix of an undirected weighted graph then $p_i$, the probability distribution over edges (rows), corresponds to the effective-resistance of the $i$-th edge.

Theorem 3.4 gives an $(1 + \varepsilon)$ approximation algorithm for the special case of low rank matrices. However, as discussed in Section 1 such an assumption is too restrictive for most applications. In the following theorem, we make a step further and relax the rank condition with a condition that depends on the stable rank of the residual matrix $A - A_k$. More formally, for an integer $k \geq 1$, we say that a matrix $A$ has a $k$-low stable rank tail if $k \geq sr(A - A_k)$.

Notice that the above definition is useful since it contains the set of matrices whose spectrum decays in a power law.

Theorem 3.5. Let $0 < \varepsilon < 1/3$ and let $A$ be a real $n \times m$ matrix with a $k$-low stable rank tail. Let $R$ be a $t \times n$ random sign matrix rescaled by $1/\sqrt{t}$ and set $\tilde{A} = RA$. If $t = \Omega(k/\varepsilon^4)$, then with high probability

$$\left\| A - P_{\tilde{A},k}(A) \right\|_2 \leq (2 + \varepsilon) \| A - A_k \|_2.$$
Then

\[ \| \mathcal{V} \|_{2}^{2} - \| \mathcal{V} \|_{2}^{2} \leq \epsilon \| \mathcal{V} \|_{2}^{2}. \]

Therefore we get that for any unit vectors \( v_1, v_2 \in \mathcal{V} \):

\[
(\mathcal{V}v_1)\mathcal{V}v_2 = \frac{\| Rv_1 + Rv_2 \|_{2}^{2} - \| Rv_1 - Rv_2 \|_{2}^{2}}{4} \leq (1 + \epsilon) \frac{\| v_1 + v_2 \|_{2}^{2} - (1 - \epsilon) \| v_1 - v_2 \|_{2}^{2}}{4} + \frac{\epsilon}{4} \frac{\| v_1 + v_2 \|_{2}^{2} + \| v_1 - v_2 \|_{2}^{2}}{2} \leq v_1^\top v_2 + \epsilon,
\]

where the first equality follows from the Parallelogram law, the first inequality follows from Equation (4.5), and the last inequality since \( v_1, v_2 \) are unit vectors. By similar considerations we get that \( (\mathcal{V}v_1)\mathcal{V}v_2 \geq v_1^\top v_2 - \epsilon \). By linearity of \( R \), we get that

\[
\forall v_1, v_2 \in \mathcal{V} : (\mathcal{V}v_1)\mathcal{V}v_2 \leq \epsilon \| v_1 \|_{2} \| v_2 \|_{2}.
\]

Notice that \( w_1, w_2 \in \mathcal{V} \), hence \( \| w_1^\top \mathcal{V}w_2 - w_1^\top w_2 \|_{2} \leq \epsilon \| w_1 \|_{2} \| w_2 \|_{2} = \epsilon \| Ax_1 \|_{2} \| Bx_2 \|_{2}. \)

### Part (b):

We start with a technical lemma that bounds the spectral norm of any matrix \( A \) when it’s multiplied by a random sign matrix rescaled by \( 1/\sqrt{t} \).

**Lemma 4.1.** Let \( A \) be an \( n \times m \) real matrix, and let \( R \) be a \( t \times n \) random sign matrix rescaled by \( 1/\sqrt{t} \). If \( t \geq sr(A) \), then

\[
\mathbb{P}(\| RA \|_{2} \geq 4 \| A \|_{2}) \leq 2e^{-t/2}.
\]

**Proof.** Without loss of generality assume that \( \| A \|_{2} = 1 \). Then \( \| A \|_{F} = \sqrt{sr(A)} \). Let \( G \) be a \( t \times n \) Gaussian matrix. Then by the Gordon-Chevet inequality,

\[
\mathbb{E} \| GA \|_{2} \leq \| I_{t} \|_{2} \| A \|_{F} + \| I_{t} \|_{F} \| A \|_{2} = \| A \|_{F} + \sqrt{t} \leq 2\sqrt{t}.
\]

The Gaussian distribution is symmetric, so \( G_{ij} \) and \( \sqrt{t}R_{ij} \) have the same distribution. By Jensen’s inequality and the fact that \( \mathbb{E}\| G_{ij} \|_{2} = \sqrt{2/\pi} \), we get that

\[
\mathbb{E}\| GA \|_{2} \leq \mathbb{E}\| GA \|_{2}/\sqrt{t}.
\]

The calculation above shows that \( \mathbb{E}\| GA \|_{2} \geq \sqrt{(1/\sqrt{t})} \). Since \( f \) is convex and \( (1/\sqrt{t}) \)-Lipschitz as a function of the entries of \( S \), Talagrand’s measure concentration inequality for convex functions yields

\[
\mathbb{P}(\| RA \|_{2} \geq \text{median}(f) + \delta) \leq 2 \exp(-\delta^2 t/2).
\]

Setting \( \delta = 1 \) in the above inequality implies the lemma.

### Row Sampling - Part (ii):

By homogeneity normalize \( A \) and \( B \) such that \( \| A \|_{2} = \| B \|_{2} = 1 \). Notice that \( A^\top B = \sum_{i=1}^{n} A_{i}^\top B_{i} \). Define \( p_{i} = \| A_{i}^\top \|_{2} \| B_{i} \|_{2} \). Also

\[
\sum_{i=1}^{n} p_{i} = \sum_{i=1}^{n} \| A_{i} \|_{2} \| B_{i} \|_{2} \leq 1. \]
define a distribution over matrices in \( \mathbb{R}^{(m+p) \times (m+p)} \) with \( n \) elements by
\[
P \left( M = \frac{1}{p_i} \begin{bmatrix} 0 & B^\top A(i) \\ A(i)^\top B(i) & 0 \end{bmatrix} \right) = p_i.
\]
First notice that
\[
EM = \sum_{i=1}^{n} \frac{1}{p_i} \begin{bmatrix} 0 & B^\top A(i) \\ A(i)^\top B(i) & 0 \end{bmatrix} = \sum_{i=1}^{n} \begin{bmatrix} 0 & B^\top A(i) \\ A(i)^\top B(i) & 0 \end{bmatrix} = \begin{bmatrix} 0 & B^\top A \\ A^\top B & 0 \end{bmatrix}.
\]
This implies that \( \|EM\|_2 = \|A^\top B\|_2 \leq 1 \). Next notice that the spectral norm of the random matrix \( M \) is upper bounded by \( \sqrt{sr(A)sr(B)} \) almost surely. Indeed,
\[
\|M\|_2 \leq \sup_{i \in [n]} \left\| \begin{bmatrix} A(i)^\top B(i) \\ A(i)^\top B(i) \end{bmatrix} \right\|_2 = S \sup_{i \in [n]} \left\| A(i)^\top \right\|_2 \left\| B(i) \right\|_2 = S \cdot 1
\]
\[
= \sum_{i=1}^{n} \left\| A(i) \right\|_2 \left\| B(i) \right\|_2 \leq \|A\|_F \|B\|_F
\]
\[
= \sqrt{sr(A)sr(B)} \leq (sr(A) + sr(B))/2,
\]
by definition of \( p_i \), properties of norms, Cauchy-Schwartz inequality, and arithmetic/geometric mean inequality. Notice that this quantity (since the spectral norms of both \( A, B \) are one) is at most \( r \) by assumption. Also notice that every element on the support of the random variable \( M \) has rank at most two. It is easy to see that, by setting \( \gamma = \bar{r} \), all the conditions in Theorem 3.4 are satisfied, and hence we get \( i_1, i_2, \ldots, i_t \) indices from \([n]\), \( t = \Omega(\bar{r} \log(\bar{r}/\epsilon^2)/\epsilon^2) \), such that with high probability
\[
\|I - \frac{1}{t} \sum_{j=1}^{t} \begin{bmatrix} 0 & \frac{1}{p_j} B^\top A(i) \\ \frac{1}{p_j} A(i)^\top B(i) & 0 \end{bmatrix} \|_2 \leq \epsilon.
\]
The first sum can be rewritten as \( \bar{A}^\top \bar{B} \) where \( \bar{A} = \frac{1}{\sqrt{t}} \begin{bmatrix} A(i_1)^\top \\ \sqrt{p_1} B(i_1) \\ \sqrt{p_2} A(i_2) \\ \sqrt{p_2} B(i_2) \\ \vdots \\ \sqrt{p_n} A(i_n) \end{bmatrix} \) and \( \bar{B} = \frac{1}{\sqrt{t}} \begin{bmatrix} B(i_1)^\top \\ \sqrt{p_1} B(i_1) \\ \sqrt{p_2} B(i_2) \\ \sqrt{p_2} B(i_2) \\ \vdots \\ \sqrt{p_n} B(i_n) \end{bmatrix} \). This concludes the theorem.

4.2 Proof of Theorem 3.3 (\( \ell_2 \)-regression)

**Proof.** (of Theorem 3.3) Similarly as the proof in [Sar06], Let \( A = USV^\top \) be the SVD of \( A \). Let \( b = Ax_{\text{opt}} + w \), where \( w \in \mathbb{R}^n \) and \( w \perp \text{colspan}(A) \). Also let \( A(\bar{x}_{\text{opt}} - x_{\text{opt}}) = Uy \), where \( y \in \mathbb{R}^{\text{rank}(A)} \). Our goal is to bound this quantity
\[
\|b - A\bar{x}_{\text{opt}}\|_2^2 = \|b - A(\bar{x}_{\text{opt}} - x_{\text{opt}}) - Ax_{\text{opt}}\|_2^2
\]
\[
= \|w - Uy\|_2^2
\]
\[
= \|w\|_2^2 + \|Uy\|_2^2, \quad \text{since } w \perp \text{colspan}(U)
\]
\[
(4.10) = \|w\|_2^2 + \|y\|_2^2, \quad \text{since } U^\top U = I.
\]
It suffices to bound the norm of \( y \), i.e., \( \|y\|_2 \leq 3 \epsilon \|w\|_2 \).
Recall that given \( A, b \) the vector \( w \) is uniquely defined.
On the other hand, vector \( y \) depends on the random projection \( R \). Next we show the connection between \( y \) and \( w \) through the “normal equations”
\[
RA\bar{x}_{\text{opt}} = Rb + w_2 \implies RA\bar{x}_{\text{opt}} = R(Ax_{\text{opt}} + w) + w_2 \implies RA(\bar{x}_{\text{opt}} - x_{\text{opt}}) = Rw + w_2 \implies U^\top R^\top RUy = U^\top R^\top Rw + U^\top R^\top w_2 \implies (4.11) U^\top R^\top RUy = U^\top R^\top Rw,
\]
where \( w_2 \perp \text{colspan}(R) \), and used this fact to derive Ineq. (4.11). A crucial observation is that the \( \text{colspan}(U) \) is perpendicular to \( w \). Set \( A = B = U \) in Theorem 3.2 and set \( \epsilon' = \sqrt{\epsilon} \), and \( t = \Omega(r/\epsilon^2) \). Notice that \( \text{rank}(A) + \text{rank}(B) \leq 2\bar{r} \), hence with constant probability we know that \( 1 - \epsilon' \leq \sigma_i(RU) \leq 1 + \epsilon' \). It follows that \( \|U^\top R^\top RUy\|_2 \geq (1 - \epsilon')^2 \|y\|_2 \). A similar argument (set \( A = U \) and \( B = w \) in Theorem 3.2) guarantees that \( \|U^\top R^\top Rw\|_2 \geq \|U^\top R^\top Rw - U^\top w\|_2 \leq \epsilon' \|U^\top w\|_2 = \epsilon' \|w\|_2 \). Recall that \( \|U\|_2 = 1 \), since \( U^\top U = I_n \) with high probability. Therefore, taking Euclidean norms on both sides of Equation (4.11) we get that
\[
\|y\|_2 \leq \frac{\epsilon'}{(1 - \epsilon')^2} \|w\|_2 \leq 4\epsilon' \|w\|_2.
\]
Summing up, it follows from Equation (4.10) that, with constant probability, \( \|b - Ax_{\text{opt}}\|_2^2 \leq (1 + 16\epsilon^2) \|b - Ax_{\text{opt}}\|_2^2 \). This proves Ineq. (3.3).

Ineq. (3.4) follows directly from the bound on the norm of \( y \) repeating the above proof for \( \epsilon' \leftarrow \epsilon \). First recall that \( x_{\text{opt}} \) is in the row span of \( A \), since \( x_{\text{opt}} = V\Sigma^{-1}U^\top b \) and the columns of \( V \) span the row space of \( A \). Similarly for \( \bar{x}_{\text{opt}} \) since the row span of \( R \cdot A \) is contained in the row-span of \( A \). Indeed, \( \epsilon \|w\|_2 \geq \|y\|_2 = \|Uy\|_2 = \|A(x_{\text{opt}} - \bar{x}_{\text{opt}})\|_2 \geq \sigma_{\text{min}}(A) \|x_{\text{opt}} - \bar{x}_{\text{opt}}\|_2 \).
4.3 Proof of Theorems 3.4, 3.5 (Spectral Low Rank Matrix Approximation)

Proof. By the assumption and using Lemma 5.1, we get that

$$\|A - P_{\bar{A},k}(A)\|_2 \leq \|A - A\bar{\Pi}_k\|_2 \leq \sup_{x \in \mathbb{R}^n, \|x\|_2 = 1} \left\|A(I - \bar{\Pi}_k)x\right\|_2^2$$

$$= \sup_{x \in \ker \bar{\Pi}_k, \|x\|_2 = 1} \|Ax\|_2^2$$

$$= \sup_{x \in \ker \bar{\Pi}_k, \|x\|_2 = 1} x^\top A^\top Ax$$

$$\leq (1 + \varepsilon) \sup_{x \in \ker \bar{\Pi}_k, \|x\|_2 = 1} x^\top \bar{A}^\top \bar{A}x,$$

using that \(x \perp \ker \bar{\Pi}_k\) implies \(\bar{\Pi}_k x = x\), left side of the hypothesis, Courant-Fischer on \(A^\top \bar{A}\) (see Eqn. 6.17), Eqn. 6.12, and properties of singular values, respectively.

**Proof of Theorem 3.4 (i):**

**Part (a):** Now we are ready to prove our first corollary of our matrix multiplication result to the problem of computing an approximate low rank matrix approximation of a matrix with respect to the spectral norm (Theorem 3.3).

**Proof.** Set \(\bar{A} = \frac{1}{\sqrt{T}}RA\) where \(R\) is a \(\Omega(r/\varepsilon^2) \times n\) random sign matrix. Apply Theorem 3.2 (i.a) on \(A\) we have with high probability that

$$\forall x \in \mathbb{R}^n, (1-\varepsilon)x^\top A^\top Ax \leq x^\top \bar{A}^\top \bar{A}x \leq (1+\varepsilon)x^\top A^\top Ax.$$  

Combining Lemma 5.1 with Ineq. (6.13) concludes the proof.

**Part (b):** The proof is based on the following lemma which reduces the problem of low rank matrix approximation to the problem of bounding the norm of a random matrix. We restate it here for reader’s convenience and completeness [NT09, Lemma 8], (see also HMT09 Theorem 9.1 or BMD09).

**Lemma 4.2.** Let \(A = A_k + U_{r-k}\Sigma_{r-k}V_{r-k}^\top\), \(H_k = U_{r-k}\Sigma_{r-k}\) and \(R\) be any \(t \times n\) matrix. If the matrix \((RU_k)^\top\) has full column rank, then the following inequality holds,

$$\|A - P_{(RA),k}(A)\|_2 \leq 2\|A - A_k\|_2 + \|(RU_k)^\top RH_k\|_2.$$ 

Notice that the above lemma, reduces the problem of spectral low rank matrix approximation to a problem of approximation the spectral norm of the random matrix \((RU_k)^\top RH_k\).

First notice that by setting \(t = \Omega(k/\varepsilon^2)\) we can guarantee that the matrix \((RU_k)^\top RH_k\) will have full column rank with high probability. Actually, we can say something much stronger; applying Theorem 3.2 (i.a) with \(A = U_k\) we can guarantee that all the singular values are within \(1 \pm \varepsilon\) with high probability. Now by conditioning on the above event (\((RU_k)^\top\) has full column rank), it follows from Lemma 4.2 that

$$\|A - P_{(RA),k}(A)\|_2 \leq 2\|A - A_k\|_2 + \|(RU_k)^\top RH_k\|_2$$

$$\leq 2\|A - A_k\|_2 + \frac{1}{1 - \varepsilon}\|RH_k\|_2$$

$$\leq 2\|A - A_k\|_2 + \frac{3}{2}\|RU_{r-k}\|_2\|\Sigma_{r-k}\|_2$$

using the sub-multiplicative property of matrix norms, and that \(\varepsilon < 1/3\). Now, it suffices to bound the norm of \(W := RU_{r-k}\). Recall that \(R = \frac{1}{\sqrt{T}}G\) where \(G\) is a \(t \times n\) random Gaussian matrix. It is well-known that the distribution of the random matrix \(GU_{r-k}\) (by rotational invariance of the Gaussian distribution) has entries which are also i.i.d. Gaussian random variables. Now, we can use the following fact about random sub-Gaussian matrices to give a bound on the spectral norm of \(W\). Indeed, we have the following

**Theorem 4.2.** [RY09, Proposition 2.3] Let \(W\) be a \(t \times (r - k)\) random matrix whose entries are independent mean zero Gaussian random variables. Assume that \(r - k \geq t\), then

$$\mathbb{P}\left(\|W\|_2 \geq \delta \sqrt{r-k}\right) \leq e^{-\cos^2\sqrt{r-k}}.$$  

for any \(\delta > \delta_0\), where \(\delta_0\) is a positive constant.

Apply union bound on the above theorem with \(\delta\) be a sufficient large constant and on the conditions of Lemma 4.2 we get that with high probability, \(\|W\|_2 \leq C_3\sqrt{r-k}\) and \(\sigma_{\min}(RU_k)^\top \leq 1/(1 - \varepsilon)\). Hence, Lemma 4.2 combined with the above discussion implies that
\begin{align*}
\|A - P_{(RA),k}(A)\|_2 & \leq 2\|A - A_k\|_2 \\
+ & \ 3/2\|RU_{r-k}\|_2 \|A - A_k\|_2 \\
= & \ 2\|A - A_k\|_2 \\
+ & \ 3\sqrt{t}/2 \|GU_{r-k}\|_2 \|A - A_k\|_2 \\
\leq & \left(2 + c_4\varepsilon\sqrt{\frac{r-k}{k}}\right) \|A - A_k\|_2,
\end{align*}

where \(c_4 > 0\) is an absolute constant. Rescaling \(\varepsilon\) by \(c_4\) concludes Theorem 3.4 (i.b).

**Proof of Theorem 3.4 (ii)** Here we prove that we can achieve the same relative error bound as with random projections by just sampling rows of \(A\) through a judiciously selected distribution.

**Proof.** (of Theorem 3.4 (ii)) The proof follows closely the proof of [SS08]. Similar with the proof of part (a).

Let \(A = UΣV^\top\) be the singular value decomposition of \(A\). Define the projector matrix \(Π = UU^\top\) of size \(n \times n\). Clearly, the rank of \(Π\) is equal to the rank of \(A\) and \(Π\) has the same image with \(A\) since every element in the image of \(A\) and \(Π\) is a linear combination of columns of \(U\). Recall that for any projection matrix, the following holds \(Π^2 = Π\) and hence \(sr(Π) = \text{rank}(A) = r\). Moreover, \(\sum_{i=1}^n \|U(i)\|_2^2 = tr(UU^\top) = tr(Π) = r\). Let \(p_i = Π(i,i)/r = \|U(i)\|_2^2 / r\) be a probability distribution on \([n]\), where \(U_i\) is the \(i\)-th row of \(U\).

Define a \(t \times n\) random matrix \(S\) as follows: Pick \(t\) samples from \(p_i\); if the \(i\)-th sample is equal to \(j(\in [n])\) then set \(S_{ij} = 1/\sqrt{p_j}\). Notice that \(S\) has exactly one non-zero entry in each row, hence it has \(t\) non-zero entries. Define \(A = SA\).

It is easy to verify that \(E_S ΠΣ^TSΣ = Π^2 = Π\). Apply Theorem 3.1 (alternatively we can use [RV07, Theorem 3.1]), since the matrix samples are rank one on the matrix \(Π\), notice that \(\|Π\|_F^2 = r\) and \(\|Π\|_2 = 1\), \(\|E_S ΠΣ^TSΣ\|_2 \leq 1\), hence the stable rank of \(Π\) is \(r\). Therefore, if \(t = O(r \log(r/\varepsilon^2)/\varepsilon^2)\) then with high probability

\begin{equation}
\|ΠΣ^TSΣ - Π\|_2 \leq \varepsilon.
\end{equation}

It suffices to show that Ineq. (4.16) is equivalent with the condition of Lemma 3.1. Indeed,

\begin{align*}
\sup_{x \in \mathbb{R}^n, x \neq 0} \frac{x^\top (ΠΣ^TSΣ - Π)x}{x^\top x} & \leq \varepsilon \iff \\
\sup_{x \notin \ker Π, x \neq 0} \frac{x^\top (ΠΣ^TSΣ - Π)x}{x^\top x} & \leq \varepsilon \iff \\
\sup_{y \in \text{Im}(A), y \neq 0} \frac{\|y^\top (ΠΣ^TSΣ - Π)y\|_2}{\|y\|_2} & \leq \varepsilon \iff \\
\sup_{x \in \mathbb{R}^m, Ax \neq 0} \frac{\|x^\top ΠΣ^TSΣA - x^\top Ax\|_2}{\|x^\top Ax\|_2} & \leq \varepsilon \iff \\
\sup_{x \in \mathbb{R}^m, Ax \neq 0} \frac{\|x^\top (ΠΣ^TSΣ - ΠA)x\|_2}{\|x^\top Ax\|_2} & \leq \varepsilon,
\end{align*}

since \(x \notin \ker Π\) implies \(x \in \text{Im}(A)\), \(\text{Im}(A) \equiv \text{Im}(Π)\), and \(ΠA = A\). By re-arranging terms we get Equation (4.13) and so the claim follows.

**Proof of Theorem 3.5** Similarly with the proof of Theorem 3.4 (i.b). By following the proof of part (i.b), conditioning on the event that \((RU_k)\) has full column rank in Lemma 4.2 we get with high probability that

\begin{align*}
\|A - P_{(RA),k}(A)\|_2 & \leq 2\|A - A_k\|_2 + \frac{\|U_k^\top R^\top RH_k\|_2}{(1 - \varepsilon)^2},
\end{align*}

using the fact that if \((RU_k)\) has full column rank then \((RU_k)^\top = ((RU_k)^\top RU_k)^{-1}U_k^\top R^\top\) and \(\|((RU_k)^\top RU_k)^{-1}\|_2 \leq 1/(1 - \varepsilon)^2\). Now observe that \(U_k^\top H_k = 0\). Since \(sr(H_k) \leq k\), using Theorem 3.2 (i.b) with \(t = Ω(k/\varepsilon^2)\), we get that \(\|U_k^\top R^\top RH_k\|_2 \leq \varepsilon\|U_k\|_2\|H_k\|_2 = \varepsilon\|A - A_k\|_2\) with high probability. Rescaling \(\varepsilon\) concludes the proof.

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**Appendix**

The next lemma states that if a symmetric positive semi-definite matrix $A$ approximates the Rayleigh quotient of a symmetric positive semi-definite matrix $\tilde{A}$, then the eigenvalues of $A$ also approximate the eigenvalues of $\tilde{A}$.

**Lemma 5.1.** Let $0 < \varepsilon < 1$. Assume $A, \tilde{A}$ are $n \times n$ symmetric positive semi-definite matrices, such that the following inequality holds

$$(1-\varepsilon)x^\top Ax \leq x^\top \tilde{A}x \leq (1+\varepsilon)x^\top Ax, \quad \forall x \in \mathbb{R}^n.$$ 

Then, for $i = 1, \ldots, n$ the eigenvalues of $A$ and $\tilde{A}$ are the same up to an error factor $\varepsilon$, i.e.,

$$(1-\varepsilon)\lambda_i(A) \leq \lambda_i(\tilde{A}) \leq (1+\varepsilon)\lambda_i(A).$$

**Proof.** The proof is an immediate consequence of the Courant-Fischer’s characterization of the eigenvalues. First notice that by hypothesis, $A$ and $\tilde{A}$ have the same null space. Hence we can assume without loss of generality, that $\lambda_i(A), \lambda_i(\tilde{A}) > 0$ for all $i = 1, \ldots, n$. Let $\lambda_i(A)$ and $\lambda_i(\tilde{A})$ be the eigenvalues (in non-decreasing order) of $A$ and $\tilde{A}$, respectively. The Courant-Fischer min-max theorem [GV06] p. 394 expresses the eigenvalues as

$$\lambda_i(A) = \min_{S^i} \max_{x \in S^i} \frac{x^\top Ax}{x^\top x},$$

where the minimum is over all $i$-dimensional subspaces $S^i$. Let the subspaces $S_0^i$ and $S_1^i$ where the minimum is achieved for the eigenvalues of $A$ and $\tilde{A}$, respectively. Then, it follows that

$$\lambda_i(\tilde{A}) = \min_{S^i} \max_{x \in S^i} \frac{x^\top \tilde{A}x}{x^\top x} \leq \max_{x \in S_0^i} \frac{x^\top \tilde{A}x}{x^\top x} \leq (1+\varepsilon)\lambda_i(A),$$

and similarly,

$$\lambda_i(A) = \min_{S^i} \max_{x \in S^i} \frac{x^\top Ax}{x^\top x} \leq \max_{x \in S_1^i} \frac{x^\top Ax}{x^\top x} \leq \frac{\lambda_i(\tilde{A})}{1-\varepsilon}. $$

Therefore, it follows that for $i = 1, \ldots, n$,

$$(1-\varepsilon)\lambda_i(A) \leq \lambda_i(\tilde{A}) \leq (1+\varepsilon)\lambda_i(A).$$

**Proof of Theorem 1.1.** For notational convenience, let $Z = \left\| \sum_{i=1}^t M_i - \mathbb{E} M \right\|_2$ and define $E_p := E_{M_1,M_2,\ldots,M_t} Z_p$. Moreover, let $X_1, X_2, \ldots, X_n$ be copies of a (matrix-valued) random variables $X$, we will denote $E_{X_1,X_2,\ldots,X_n}$ by $E_{X[n]}$. Our goal is to give sharp bounds on the moments of the non-negative random
variable $Z$ and then using the moment method to give
concentration result for $Z$.

First we give a technical lemma of independent interest that bounds the $p$-th moments of $Z$ as a function of $p$, $r$ (the rank of the samples), and the $p/2$-th moment of the random variable $\|\sum_{j=1}^t M_j^2\|_2$. More formally, we have the following

**Lemma 5.2.** Let $M_1, \ldots, M_t$ be i.i.d. copies of $M$, where $M$ is a symmetric matrix-valued random variable that has rank at most $r$ almost surely. Then for every $p \geq 2$

\[
E_p \leq r t^{-p} (2B_p)^p \mathbb{E}_{M[t]} \left( \sum_{j=1}^t M_j^2 \right)^{p/2},
\]

where $B_p$ is a constant that depends on $p$.

We need a non-commutative version of Khintchine inequality due to F. Lust-Piquard [LP86], see also [LPP91] and [Buc01]. Let $\epsilon_i$ be independent Bernoulli variables. Let $M_1, \ldots, M_t, \tilde{M}_1, \ldots, \tilde{M}_t$ be independent copies of $M$. We essential estimate the $p$-th root of $E_p$,

\[
E_p^{1/p} = \left( \mathbb{E}_{M[t]} \left\| \frac{1}{t} \sum_{i=1}^t M_i - \mathbb{E} M \right\|_2^p \right)^{1/p}.
\]

Indeed, let $\epsilon_1, \epsilon_2, \ldots, \epsilon_t$ denote independent Bernoulli variables. Let $M_1, \ldots, M_t, \tilde{M}_1, \ldots, \tilde{M}_t$ be independent copies of $M$. We essential estimate the $p$-th root of $E_p$,

\[
E_p^{1/p} \leq \left( \mathbb{E}_{M[t]} \mathbb{E}_{\tilde{M}[t]} \left\| \frac{1}{t} \sum_{i=1}^t \epsilon_i (M_i - \tilde{M}_i) \right\|_2^p \right)^{1/p}.
\]

Now we are ready to prove Lemma 5.2.

**Proof.** The proof is inspired from [RV07] Theorem 3.1. Let $p \geq 2$. First, apply a standard symmetrization argument (see [LT91]), which gives that

\[
\left( \mathbb{E}_{M[t]} \left\| \frac{1}{t} \sum_{i=1}^t M_i - \mathbb{E} M \right\|_2^p \right)^{1/p} \leq 2 \left( \mathbb{E}_{M[t]} \mathbb{E}_{\tilde{M}[t]} \left\| \frac{1}{t} \sum_{i=1}^t \epsilon_i M_i \right\|_2^p \right)^{1/p}.
\]

Notice that $\mathbb{E} \tilde{M} = \mathbb{E}_{\tilde{M}[t]} \left( \frac{1}{t} \sum_{i=1}^t \tilde{M}_i \right)$. We plug this into (5.22) and apply Jensen’s inequality,

\[
E_p^{1/p} = \left( \mathbb{E}_{M[t]} \left\| \frac{1}{t} \sum_{i=1}^t M_i - \mathbb{E} M \right\|_2^p \right)^{1/p}.
\]

Now, notice that $M_i - \tilde{M}_i$ is a symmetric matrix-valued random variable for every $i \in [t]$, i.e., it is distributed identically with $\epsilon_i (M_i - \tilde{M}_i)$. Thus

\[
E_p^{1/p} \leq \left( \mathbb{E}_{M[t]} \mathbb{E}_{\tilde{M}[t]} \left\| \frac{1}{t} \sum_{i=1}^t \epsilon_i (M_i - \tilde{M}_i) \right\|_2^p \right)^{1/p}.
\]

Denote $Y = \frac{1}{t} \sum_{i=1}^t \epsilon_i M_i$ and $\tilde{Y} = \frac{1}{t} \sum_{i=1}^t \epsilon_i \tilde{M}_i$. Then $\|Y - \tilde{Y}\|^p \leq \left( \|Y\| + \|\tilde{Y}\| \right)^p \leq 2^p (\|Y\|^p + \|\tilde{Y}\|^p)$, and $\mathbb{E} \|Y\|^p = \mathbb{E} \|\tilde{Y}\|^p$. Thus, we obtain that

\[
E_p^{1/p} \leq \left( \mathbb{E}_{M[t]} \mathbb{E}_{\tilde{M}[t]} \left\| \frac{1}{t} \sum_{i=1}^t \epsilon_i (M_i - \tilde{M}_i) \right\|_2^p \right)^{1/p}.
\]

Now by the Khintchine’s inequality the following holds
for any fixed symmetric matrices \( M_1, M_2, \ldots, M_t \).

\[
\left( \mathbb{E}_{\varepsilon_{(t)}} \left\| \frac{1}{t} \sum_{j=1}^{t} \varepsilon_j M_j \right\|_2^p \right)^{\frac{1}{p}} \leq \frac{1}{t} \left( \mathbb{E}_{\varepsilon_{(t)}} \left\| \sum_{j=1}^{t} \varepsilon_j M_j \right\|_{C_p}^p \right)^{\frac{1}{p}} \leq \frac{1}{t} B_p \left( \sum_{j=1}^{t} M_j^2 \right)^{1/2} \leq \frac{(rt)^{1/p} B_p}{t} \left( \sum_{j=1}^{t} M_j^2 \right)^{\frac{1}{2}} = \frac{(rt)^{1/p} B_p}{t} \left\| \sum_{j=1}^{t} M_j^2 \right\|_2^{\frac{1}{2}} ,
\]

(5.24)

It follows that

\[
E_p \leq rt^{1-p} (2B_p)^p \mathbb{E}_{M_{(t)}} \left\| \sum_{j=1}^{t} M_j \right\|_2^{p/2} \leq rt^{1-p} (2B_p)^p \mathbb{E}_{M_{(t)}} \left\| \sum_{j=1}^{t} M_j \right\|_2^{p/2} = \frac{rt(2B_p \sqrt{t})^p}{t^{p/2}} \mathbb{E}_{M_{(t)}} \left\| \sum_{j=1}^{t} M_j \right\|_2^{p/2} \leq \frac{rt(2B_p \sqrt{t})^p}{t^{p/2}} \left( \left( \mathbb{E} \left\| \sum_{j=1}^{t} M_j - \mathbb{E} M \right\|_2^{\frac{2}{p}} \right)^{\frac{p}{2}} + 1 \right)^{\frac{p}{2}} \leq \frac{rt(2B_p \sqrt{t})^p}{t^{p/2}} \left( \left( \mathbb{E} \left\| \sum_{j=1}^{t} M_j - \mathbb{E} M \right\|_2^{p} \right)^{\frac{1}{p}} + 1 \right)^{\frac{p}{2}} \leq \frac{rt(2B_p \sqrt{t})^p}{t^{p/2}} \left( E_{p}^{1/p} + 1 \right)^{p/2} ,
\]

(5.25)

This concludes the proof of Lemma 5.2.

Now we are ready to prove Theorem 5.2. First we can assume without loss of generality that \( M \succeq 0 \) almost surely losing only a constant factor in our bounds. Indeed, by the spectral decomposition theorem any symmetric matrix can be written as \( M = \sum_{\lambda_j \geq 0} \lambda_j u_j u_j^T \). Set \( M_+ = \sum_{\lambda_j > 0} \lambda_j u_j u_j^T \) and \( M_- = M - M_+ \). It is clear that \( \|M_+\|_2, \|M_-\|_2 \leq \|M\|_2, \|M_+\|_F, \|M_-\|_F \leq \|M\|_F \) and \( \text{rank}(M_+), \text{rank}(M_-) \leq \text{rank}(M) \). Triangle inequality tells us that

\[
\left\| \frac{1}{t} \sum_{i=1}^{t} M_j - \mathbb{E} M \right\|_2 \leq \left\| \frac{1}{t} \sum_{i=1}^{t} (M_j)_+ - \mathbb{E} M_+ \right\|_2 + \left\| \frac{1}{t} \sum_{i=1}^{t} (M_j)_- - \mathbb{E} M_- \right\|_2
\]

and one can bound each term of the right hand side separately. Hence, from now on we assume that \( M \succeq 0 \) a.s. Now use the fact that for every \( j \in [t] \), \( M_j^2 \leq \gamma \cdot M_j \) since \( M_j \)'s are positive semi-definite and \( \|M\|_2 \leq \gamma \) almost surely. Summing up all the inequalities we get that

\[
E_p^{1/p} \leq \frac{2B_p \sqrt{t} (rt)^{1/p}}{t^{p/2}} (E_{p}^{1/p} + 1) ,
\]

(5.26)

using Lemma 5.2, Ineq. (5.20), Minkowski’s inequality, Jensen’s inequality, definition of \( E_{p} \) and the assumption \( \|\mathbb{E} M\|_2 \leq 1 \). This implies the following inequality

\[
E_{p}^{1/p} \leq \frac{2B_p \sqrt{t} (rt)^{1/p}}{t^{p/2}} (E_{p}^{1/p} + 1) ,
\]

using that \( \sqrt{1+x} \leq 1+x, x \geq 0 \). Let \( a_p = \frac{4B_p (rt)^{1/p}}{\sqrt{t}} \). Then it follows from the above inequality that \( E_{p}^{1/p} \leq a_p (E_{p}^{1/p} + 1) \). It follows that almost surely. Summing up all the inequalities we get that

\[
\mathbb{P} (Z > \varepsilon) = \mathbb{P} (\min\{Z, 1\} > \varepsilon) .
\]

\[
\text{Indeed, if } E_{p}^{1/p} < 1, \text{ then } E_{p}^{1/p} < a_p. \text{ Otherwise } 1 \leq a_p.
\]
By the moment method we have that

\[
P(\min\{Z,1\} > \varepsilon) = P(\min\{Z,1\}^p > \varepsilon^p) \\
\leq \inf_{p \geq 2} \left( \frac{E \min\{Z,1\}^p}{\varepsilon^p} \right) \\
\leq \inf_{p \geq 2} \left( \frac{\min\{E_p^{1/p}, 1\}^p}{\varepsilon^p} \right) \tag{5.27} \\
\leq \inf_{p \geq 2} \left( \frac{\Theta_p}{\varepsilon^p} \right)^p \\
= \inf_{p \geq 2} \left( \frac{4B_p \sqrt{(rt)^{1/p}}}{\varepsilon \sqrt{t}} \right)^p \\
= \inf_{p \geq 2} \left( \frac{C_2 \sqrt{(rt)^{1/p}}}{\varepsilon \sqrt{t}} \right)^p ,
\]

where \( C_2 > 0 \) is an absolute constant.

Now assume that \( r \leq t \) and then set \( p = c_2 \log t \), where \( c_2 > 0 \) is a sufficient large constant, at the infimum expression in the above inequality, it follows that

\[
P \left( \left\| \frac{1}{t} \sum_{i=1}^{t} M_i - E M \right\|_2 > \varepsilon \right) \leq \left( \frac{C \sqrt{\log \log (rt) \log t}}{\varepsilon \sqrt{t}} \right)^{c_2 \log t}
\]

We want to make the base of the above exponent smaller than one. It is easy to see that this is possible if we set \( t = C_0 \gamma/\varepsilon^2 \log(C_0 \gamma/\varepsilon^2) \) where \( C_0 \) is sufficiently large absolute constant. Hence it implies that the above probability is at most \( 1/\text{poly}(t) \). This concludes the proof.