Design of Respiration Rate Meter Using Flexible Sensor

Sarah Aghnia Miyagi#, Muhammad Ridha Mak'ru$f^1$, Endang Dian Setyoningsih1, Tarak Das2
1Department of Electromedical Engineering Politeknik Kemenkes, Surabaya
Jl. Pucang Jajar Timur No. 10, Surabaya, 60245, Indonesia
2Department of Biomedical Engineering Netaji Subhash, Engineering College Kolkata, India
#aghniamiyagi@gmail.com, m.reedha@gmail.com, dianchilik@gmail.com, tarakjubme@gmail.com

Abstract—Respiration rate is an important physiological parameter that helps to provide important information about the patient's health status, especially from the human respiratory system. So it is necessary to measure the human respiratory rate by calculating the number of respiratory frequencies within 1 minute. The respiratory rate meter is a tool used to calculate the respiratory rate by counting the number of breaths for 1 minute. The author makes a tool to detect human respiratory rate by using a sensor that detects the ascend and descend of the chest cavity based on a microcontroller so that the operator can measure the breathing rate more practically and accurately. Component tool contains analog signal conditioning circuit and microcontroller circuit accompanied by display in the form of LCD TFT. The results of measurement data on 10 respondents obtained an average error value, namely the position of the right chest cavity 6.6%, middle chest cavity 7.92%, and left chest cavity 6.85%. This value is still below the error tolerance limit of 10%. It can be concluded that to obtain the best measurement results, the sensor is placed in the position of the right chest cavity.

Keywords—Flex Sensor; Respiration Rate; Breath Per Minutes

I. INTRODUCTION

The respiratory rate meter is a tool used to calculate the respiratory rate by counting the number of breaths for 1 minute [1]. This measurement can be done to determine the health of the patient's condition associated with breathing. The amount of breathing that exceeds the normal respiratory rate (tachypnea), is lower than the average number of normal respiration (bradypnea), or even stops for a while (apnea), is a sensitive indicator for physiological sufferers who need immediate health care [2].

There are four important physiological parameters that can be used by nurses or medical personnel in determining the health status of patients in hospitals. The four parameters are body temperature, heart rate, respiratory rate, and blood pressure. Of the four parameters, the respiratory rate is the most important parameter because the respiratory rate can provide valuable information related to the condition of the heart, nerves, and lungs [2]. Respiratory rate is a vital sign used to monitor the progress of the disease and abnormal respiratory rate. There is substantial evidence that changes in respiratory rate can be used to predict potentially serious clinical events such as a heart attack or entering the intensive care unit. These studies have shown breathing rates to be better than other vital measurements such as pulse and blood pressure in distinguishing between stable patients and patients at risk [3]. Abnormal respiratory rate and changes in respiratory rate are one indicator of instability in a person's physical condition, and in many cases, breathing rate is one of the earliest indicators of this instability. It is therefore very important to monitor respiratory rate as an indicator of patient status [4]. Tarak Das develop a respiratory rate using thermistor [5].

The simplest method for determining the respiratory rate is to manually calculate the up and down motion of the chest wall directly, or by breathing sounds through a stethoscope. This method is very dependent on mind concentration and sensory sensitivity of the measurement / observation actors [2]. However, using a stethoscope for a long time is not practical and inaccurate mainly due to human error [6]. Because of human nature that is easy to forget, tired, and bored, it is now widely developed the method of measuring or observing breathing rates electronically [2]. A study comparing respiration measurement using a calculator and manual measurement showed the benefits of using digital counting techniques [7].

In 2014 I Made Naradhyana made a Monitoring Device of Respiratory System Using Arduino UNO and E-Health PCB™ using an air flow sensor and the results were displayed on the Nokia 5110 LCD. Subsequently in 2015 Wendi Era Sonata and Wildan made a tool Designing a Measuring Instrument Human Respiratory Rate Based on AT mega 8535 Microcontroller uses the LM35 sensor and is displayed on the LCD character 2x16. In 2017 Desy Yuniar Ekawati made a device with title of Designing Respiratory Rate Measurement Using Mic Condenser Accompanied by Plotting on LCD Graphics and in 2018 Erdiana Larasati has perfected the module by displaying the output on a TFT LCD and using a humidity sensor. From the results of identification of some of these studies, even though using a different sensor but have the same thing in laying the sensor, namely in the mouthpiece or mouth mask. While data collection
for the respiratory rate is not only covered but can also be on the ribs or stomach [8].

Based on the problem above, on this occasion the author wants to perfect the design of the respiratory rate measurement device by retrieving data on the up and down motion of the chest cavity because the previous device used a sensor that placed it in the mouthpiece or mouth mask. The author uses a flex sensor with TFT LCD output that is equipped with normal (eupnea) and abnormal information with 2 criteria: bradypnea and tachypnea.

II. MATERIALS AND METHODS

A. Experimental Setup

This study used ten subjects with the criteria the ages ranged between 20 and 35 years old. The subjects were randomly sampled and the data collection is repeated for 3 times at 3 placement points.

1) Materials and Tool

This study used a flex sensor to detect the ascend and descend of the chest cavity. The sensor were attached by the strap around the chest. PSA was built based on LM358 OP-AMP. The Arduino Nano microcontroller was used to convert analogue output from flex sensor to digital output. TFT LCD was used to display the final output.

2) Experiment

In this study, after the design was completed then the Respiration Rate Meter was tested using a counter. By showing the criteria (eupnea, bradypnea, tachypnea), the Respiration Rate Meter was tested with ranged between 1 and 100. Then the Respiration Rate Meter was tested on the human body.

B. The Diagram Block

In this research, the flex sensor detects the ascend and descend of the chest cavity in 1 minute. Then, the input from sensor will enter to PSA. In Arduino microcontroller was used to convert analog data from PSA into digital. The Respiratory Rate data will be displayed on the TFT LCD in the form of a number of respiratory rates along with information on bradypnea, eupnea, and tachypnea.

C. The Flowchart

The Arduino program was built based on the flowchart as shown in Fig. 2. After the initialization of the Arduino, the program starts to count the Respiration Rate for 1 minute. If it’s already 1 minute, then the value of Respiration Rate will be shown to TFT LCD with the criteria (bradypnea, eupnea, tachypnea).

D. The Analog Circuit

The important part of this development is the analogue circuit which describes in Fig. 3 (voltage divider), Fig. 4 (difference amplifier). The circuit is used to process the Respiration Rate. Hence it will ready for digital processing using Arduino.

1) Voltage Divider

Flex sensor is a sensor that when it’s curved, the resistance which is output from the sensor will be changed. So that when the flex sensor is curved it will make output from the voltage
divider change depending on the resistance produced when it’s being curved. This circuit is composed of two resistor. The value of R1 is 47K ohms and the other one is flex sensor. For the calculation of output from voltage divider, as follows:

\[ V_{out} = \frac{R_g}{R_{flex} + R_{ground}} \cdot V_{in} \]  

Where, Rg is resistor to ground then Rflex is resistance which output from flex sensor. Vout is voltage output from this circuit and Vin is voltage input for this circuit.

2) Difference Amplifier

The Difference Amplifier is to get the difference value of Vin non-inverting with Vin inverting and also its functions to gained the difference in value from the input voltage. Multiturn is to set if the sensor if in a curved condition the output of the circuit is 0V. When the flex sensor is curved, the output of this circuit is no longer 0V, the output value of this circuit varies depending on the curvature that occurs in the flex sensor itself. The output of the difference amplifier circuit is connected to the pin A1 of Arduino Nano.

\[ A_{cl} = \frac{R_f}{R_{in}} \]  

Where, Acl is gain for this circuit output. Rf is resistor feedback which R6 in Fig. 4. and Rin is resistor input which R8 in Fig. 4.

III. RESULTS

In this study, comparison of data results with predetermined comparison tools, measurement and analysis of the error value. The result shows that the Respiration Rate Meter is feasible to see the value of respiration rate from the human body.

1) The Respiration Rate Design

The photograph of the analogue part, digital part, and design of the Respiration Rate was shown in Fig. 5 and Fig. 6, respectively. The analogue part consisted of LM358 (OP-AMP). There was also some variable resistor (multiturn 50k) for offset adjustment. The digital part consisted of the Arduino Nano microcontroller which is the main board of Respiration Rate device.

2) Respiration Rate Calculation Using Auto Reference Result

Listing program 1. Program to calculate the respiration rate

```python
flex = analogRead (A1);
if (ref <= flex) {ref = flex;}
```
else
{
ref = ref;
hold = (ref * 9 / 10);
if ((flex <= hold) && (mark == 0))
{
    count ++;
    if (count == 100)
    {count=0; mark=1;}
}
}
if ((flex <= hold) && (mark == 1)) {
    ref = 100;
    mark = 0;
    hold= 330;
}

The data processing program listing on Arduino starts from reading the ADC through pin A1 and converting ADC data to voltage. In the above program listings use an auto reference system that uses the highest percentage of signal voltage to calculate respiration rate.

3) **The value of respiration within 1 minute**
Listing Program 2. Program to counting the Respiratory Rate after 1 minute

```cpp
waktu = millis() - waktusekarang;
if (waktu < 60000)
{
    if (flex > hold)
    {
        count=0;
        beat=1;
    }
}
The program is to display the patient's respiration value within 1 minute. The value is displayed within 1 minute because it is a stable time when the tool is attached to the patient.
```

4) **The Listing Program for TFT LCD**
In the TFT programming, the program was grouped into some part namely: a program to send communication to displayed into TFT LCD (Listing Program 3), a program to show the value of respiration rate (breath per minute) as shown in the Listing Program 4, and a program to show the classification of respiration rate to TFT (bradypnea, eupnea, tachypnea) as shown in the Listing Program 5.

Listing Program 3. Program to send communication into TFT

```cpp
void setup() {
    Serial.begin(9600);
}
```

```cpp
delay(500);
    Serial.print("baud=115200");
    Serial.write(0xff);
    Serial.write(0xff);
    Serial.end();
    Serial.begin(115200);
}
The Listing Program 3. was used to send communication serial into TFT LCD. The setting of baud rate is 115200 which is fixed value for this.

Listing Program 4. Program to show the value of respiration rate

```cpp
if ( currentpage == 2 )
{
    Serial.print("n0.val=");
    Serial.print(respirasi);
    Serial.write(0xff);
    Serial.write(0xff);
    Serial.print("n1.val=");
    Serial.print(detak);
    Serial.write(0xff);
    Serial.write(0xff);
    Serial.write(0xff);
}
The Listing Program 4. was used to show the value of respiration rate. After the program in Arduino count the respiration rate within 1 minute, then it will show up to TFT.

Listing Program 5. Program to show the classification of respiration rate

```cpp
if ( respirasi < 12 ){
    Serial.print("t1.txt=");
    Serial.print("BRADYPNEA");
    Serial.print("\n");
    Serial.write(0xff);
    Serial.write(0xff);
    Serial.write(0xff);
}
else if ( respirasi > 20 ){
    Serial.print("t1.txt=");
    Serial.print("TACHYPNEA");
    Serial.print("\n");
    Serial.write(0xff);
    Serial.write(0xff);
    Serial.write(0xff);
}
```
The listing program 5. was used to show the classification of respiration rate. After the value of respiration rate shown into TFT, the classification will appear after all. There are 3 classification of respiration rate, first is bradypnea, second is eupnea or normal and the last is tachypnea.

5) The Error of Respiration Rate (Breath Per Minutes) value

The validation of the Respiration Rate value shown in the TFT LCD was compared with counter. The following are data from 3 different measurement points (right chest, middle chest, left chest) for the same patient, different placements are intended as an analysis of several respiratory points in humans. The error are showed in the table I, II, and III.

| No | Subject | Error (%) |
|----|---------|-----------|
| 1  | P1      | 13.64%    |
| 2  | P2      | 4.08%     |
| 3  | P3      | 10.87%    |
| 4  | P4      | 6.9%      |
| 5  | P5      | 3.08%     |
| 6  | P6      | 13.21%    |
| 7  | P7      | 1.47%     |
| 8  | P8      | 0%        |
| 9  | P9      | 2.22%     |
| 10 | P10     | 10.53%    |

Comparison of data retrieval is done by comparing the module with a comparison device (counter) carried out on 10 different subjects for respiration rate which sensor placement on the right chest, the highest error calculated is 13.64%.

| No | Subject | Error (%) |
|----|---------|-----------|
| 1  | P1      | 11.11%    |

Comparison of data retrieval is done by comparing the module with a comparison device (counter) carried out on 10 different subjects for respiration rate which sensor placement on the middle chest, the highest error calculated is 20.93%.

| No | Subject | Error (%) |
|----|---------|-----------|
| 1  | P1      | 15.91%    |

Comparison of data retrieval is done by comparing the module with a comparison device (counter) carried out on 10 different subjects for respiration rate which sensor placement on the left chest, the highest error calculated is 15.91%.

IV. DISCUSSION

After comparing the results between the module and the measuring instrument, the average error value of the module for placement of the sensor position in the right chest cavity is 6.6%, in the left chest 6.85% and in the middle chest cavity 7.92%. The average error value for all positions has a value that is still below the maximum Respiration Rate reading threshold of 10% as stated in the regulation of Minister of Health Regulation no. 363 of 1998 concerning the maximum errors allowed in this parameter.

Based on the output of the circuit in the module, namely table 1, table 2, and table 3, the highest signal results when the sensor is placed in the right chest cavity. This is in accordance with the results of the smallest error value, namely the placement of
sensors when in the right chest cavity because the higher the output signal produced, the easier it is to detect respiration, which is in the movement of up and down the chest cavity.

And for the most appropriate placement for this module is in the right chest cavity because the error value in the placement of the sensor part is fairly small compared to the placement of sensors in the left or middle chest cavity.

V. CONCLUSION

This study has shown measurements of respiratory cavity at 3 points. This study was built based on the Arduino microcontroller, analog circuit and TFT LCD as a display. This study has proven that the accuracy of measurement points determines different measuring results. In the future, this research can be made and used in small clinics in villages at low cost.

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