A Unified Analysis of Stochastic Gradient Methods for Nonconvex Federated Optimization

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Abstract
In this paper, we study the performance of a large family of SGD variants in the smooth nonconvex regime. To this end, we propose a generic and flexible assumption capable of accurate modeling of the second moment of the stochastic gradient. Our assumption is satisfied by a large number of specific variants of SGD in the literature, including SGD with arbitrary sampling, SGD with compressed gradients, and a wide variety of variance-reduced SGD methods such as SVRG and SAGA. We provide a single convergence analysis for all methods that satisfy the proposed unified assumption, thereby offering a unified understanding of SGD variants in the nonconvex regime instead of relying on dedicated analyses of each variant. Moreover, our unified analysis is accurate enough to recover or improve upon the best-known convergence results of several classical methods, and also gives new convergence results for many new methods which arise as special cases. In the more general distributed/federated nonconvex optimization setup, we propose two new general algorithmic frameworks differing in whether direct gradient compression (DC) or compression of gradient differences (DIANA) is used. We show that all methods captured by these two frameworks also satisfy our unified assumption. Thus, our unified convergence analysis also captures a large variety of distributed methods utilizing compressed communication. Finally, we also provide a unified analysis for obtaining faster linear convergence rates in this nonconvex regime under the PL condition.

Contents
1 Introduction 3
   1.1 Single machine setting 3
   1.2 Our contributions 3

2 Notation and Assumptions 6
   2.1 Notation 6
   2.2 Assumptions 6

3 Main Unified Theorems and Simple Special Cases 7
   3.1 Main unified theorems 7
   3.2 Simple special cases (m = 1) 8
      3.2.1 GD method 8
      3.2.2 SGD method 9
      3.2.3 L-SVRG method 9
      3.2.4 SAGA method 10
4 General Nonconvex Federated Optimization Problems
4.1 Compression operators .............................................. 11
4.2 DC framework for nonconvex federated optimization ........ 11
4.3 DIANA framework for nonconvex federated optimization ...... 12

A Missing Proofs for Unified Main Theorems .......................... 18
A.1 Proof of unified Theorem 1 ............................................ 18
A.2 Proofs for unified theorems under PL condition ............... 21
  A.2.1 Proof of unified Theorem 5 under PL condition (constant stepsise) ..... 21
  A.2.2 Proof of unified Theorem 2 under PL condition (decreasing stepsise) ... 23

B Convergence Results and Proofs for Nonconvex Optimization (m = 1) 27
B.1 GD method ................................................................. 27
B.2 SGD method ............................................................... 28
B.3 L-SVRG method ........................................................... 29
B.4 SAGA method ............................................................. 31

C Convergence Results and Proofs for Nonconvex Federated Optimization 35
C.1 DC framework for nonconvex federated optimization .......... 35
  C.1.1 DC-GD method ....................................................... 39
  C.1.2 DC-SGD method ..................................................... 41
  C.1.3 DC-LSVRG method ............................................... 43
  C.1.4 DC-SAGA method .................................................. 45
C.2 DIANA framework for nonconvex federated optimization .... 48
  C.2.1 DIANA-GD method ............................................... 58
  C.2.2 DIANA-SGD method .............................................. 59
  C.2.3 DIANA-LSVRG method ......................................... 61
  C.2.4 DIANA-SAGA method ........................................... 64

D Better Convergence for Nonconvex Optimization under PL Condition 68
D.1 GD method under PL condition ....................................... 68
D.2 SGD method under PL condition ..................................... 68
D.3 L-SVRG method under PL condition ................................. 69
D.4 SAGA method under PL condition .................................... 70

E Better Convergence for Nonconvex Federated Optimization under PL Condition 72
E.1 Better convergence results of DC-type methods under PL condition .......... 72
  E.1.1 DC-GD method under PL condition ............................. 72
  E.1.2 DC-SGD method under PL condition ........................... 73
  E.1.3 DC-LSVRG method under PL condition ......................... 73
  E.1.4 DC-SAGA method under PL condition ......................... 74
E.2 Better convergence results of DIANA-type methods under PL Condition .... 75
  E.2.1 DIANA-GD method under PL condition ......................... 75
  E.2.2 DIANA-SGD method under PL condition ....................... 75
  E.2.3 DIANA-LSVRG method under PL condition ................. 76
  E.2.4 DIANA-SAGA method under PL condition .................... 76
1 Introduction

In this paper, we develop a general framework for studying and designing SGD-type methods for solving nonconvex distributed/federated optimization problems [26, 27, 20]. Given $m$ machines/workers/devices, each having access to their own data samples, we consider the problem

$$\min_{x \in \mathbb{R}^d} \left\{ f(x) := \frac{1}{m} \sum_{i=1}^{m} f_i(x) \right\}$$

(1.1)

in the heterogeneous (non-IID) data setting, i.e., we allow different workers to have access to different data distributions. We consider the case when the loss $f_i$ in worker $i$ is of an online/expectation form,

$$f_i(x) := \mathbb{E}_{\zeta \sim D}[f_i(x, \zeta)],$$

(1.2)

and also the case when $f_i$ is of a finite-sum form,

$$f_i(x) := \frac{1}{n} \sum_{j=1}^{n} f_{i,j}(x),$$

(1.3)

where $f(x), f_i(x), f_i(x, \zeta)$ and $f_{i,j}(x)$ are possibly nonconvex functions. Forms (1.2) and (1.3) capture the population (resp. empirical) risk minimization problems in distributed/federated learning.

1.1 Single machine setting

In particular, the single machine/node case (i.e., $m = 1$) of problem (1.1) reduces to the standard problem

$$\min_{x \in \mathbb{R}^d} f(x),$$

(1.4)

where $f(x)$ can be the online/expectation form

$$f(x) := \mathbb{E}_{\zeta \sim D}[f(x, \zeta)],$$

(1.5)

or the finite-sum form

$$f(x) := \frac{1}{n} \sum_{j=1}^{n} f_{j}(x),$$

(1.6)

where $f(x), f(x, \zeta)$ and $f_{j}(x)$ are possibly nonconvex functions. These forms capture the standard population/empirical risk minimization problems in machine learning.

There has been extensive research into solving the standard problem (1.4)–(1.6) and an enormous number of methods were proposed, e.g., [45, 44, 11, 19, 7, 46, 9, 40, 29, 30, 31, 2, 37, 12, 56, 8, 35, 47]. Due to the increasing popularity of distributed/federated learning, the more general distributed/federated optimization problem (1.1)–(1.3) has attracted significant attention as well [27, 42, 39, 30, 33, 52, 43, 18, 22, 24, 55, 34, 20, 38, 25]. However, all these methods are analyzed separately, often using different approaches, intuitions, and assumptions, and separately in the $m = 1$ (single node) and $m \geq 1$ case.

1.2 Our contributions

We provide a single and sharp analysis for a large family of SGD methods (Algorithm 1) for solving the nonconvex problem (1.1). Our approach offers a unified understanding of many previously proposed SGD variants, which we believe helps the community making better sense of existing methods and results. More importantly, our unified approach also motivates and facilitates the design of, and offers plug-in convergence guarantees for, many new and practically relevant SGD variants.
Algorithm 1 Framework of stochastic gradient methods

1. **Input**: initial point \( x^0 \), stepsize \( \eta_k \)
2. **for** \( k = 0, 1, 2, \ldots \) **do**
   1. Compute stochastic gradient \( g^k \)
   2. \( x^{k+1} = x^k - \eta_k g^k \)
3. **end for**

While Algorithm 1 has a seemingly tame structure, the complication arises due to the fact that there is a potentially infinite number of meaningful and yet sharply distinct ways in which the gradient estimator \( g^k \) can be defined. The selection of an appropriate estimator is a very active and important area of research, as it directly impacts many aspects of the algorithm it gives rise to, including tractability, memory footprint, per iteration cost, parallelizability, iteration complexity, communication complexity, sample complexity and generalization.

The key technical idea of our approach is the design of a flexible, tractable and accurate parametric model capturing the behavior of the stochastic gradient. We want the model to be flexible in order to be able to describe many existing and have the potential to describe many variants of SGD. As we shall see, flexibility is achieved by the inclusion of a number of parameters. We want the model to be tractable, meaning that it needs to act as an assumption which can be used to perform a theoretical complexity analysis. Finally, we want the complexity results to be accurate, i.e., we want to recover best known rates for existing methods, and obtain sharp and useful rates with predictive power for new methods. Our parametric model is described in Assumption 1, and as we argue throughout the paper and appendices, it is indeed flexible, tractable and accurate.

**Assumption 1 (Gradient estimator)** The gradient estimator \( g^k \) in Algorithm 1 is unbiased, i.e., \( E_k[g^k] = \nabla f(x^k) \), and there exist non-negative constants \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \) and a random sequence \( \{\sigma_k^2\} \) such that the following two inequalities hold

\[
E_k[\|g^k\|^2] \leq 2A_1(f(x^k) - f^*) + B_1\|\nabla f(x^k)\|^2 + D_1\sigma_k^2 + C_1, \tag{1.7}
\]

\[
E_k[\sigma_{k+1}^2] \leq (1 - \rho)\sigma_k^2 + 2A_2(f(x^k) - f^*) + B_2\|\nabla f(x^k)\|^2 + C_2. \tag{1.8}
\]

**Flexibility**: Our model for the behavior of the stochastic gradient for nonconvex optimization, as captured by Assumption 1, is satisfied by a large number of specific variants of SGD proposed in the literature, including SGD with arbitrary sampling [49, 14, 13, 23], SGD with compressed gradients [1, 54, 5, 26, 15, 17], and a wide variety of variance-reduced SGD methods such as SVRG [19], SAGA [7] and their variants (e.g., [28, 50, 51, 3, 32, 36, 10, 43, 18]). Specific methods vary in the parameters for which recurrences (1.7) and (1.8) are satisfied. For example, SGD variants not employing variance reduction will generally have \( D_1 = 0 \), and recurrence (1.8) will not be used (i.e., we can ignore it and set \( \rho = 1, A_2 = 0, B_2 = 0 \) and \( C_2 = 0 \)). This setting was considered in [23], and was an inspiration for our work. If variance reduction is applied, then \( D_1 > 0 \) and typically \( C_1 = 0 \), and recurrence (1.8) describes the variance reduction process, with parameter \( \rho \) describing the speed of variance reduction. If \( C_2 > 0 \), variance reduction is not perfect. If \( C_2 = 0 \) as well, then the methods will be fully variance reduced, which typically means faster convergence rate. The specific values of all the parameters depend on how the stochastic gradient \( g^k \) is constructed (e.g., via minibatching, importance sampling, variance reduction, perturbation, compression).

We design several new methods, with gradient estimators that fit Assumption 1, for solving the general nonconvex distributed/federated problem (1.1)—(1.3) using compressed (e.g., quantized or sparsified) gradient communication, which is of import when training deep learning models. We adopt a direct compression (DC) framework [1, 26], and a compression of gradient differences framework (DIANA) [43, 18]. We develop several new specific methods belonging to the DC framework (Algorithm 6) and DIANA framework (Algorithm 7), show that they all satisfy Assumption 1, and thus are also captured by our unified analysis.

**Tractability**: We use our unified assumption to prove four complexity theorems: Theorems 1, 2, 3, and 4. Theorem 1 is the main theorem, and Theorem 2 is used to obtain sharper results under the PL condition.
Theorems 3 and 4 are used in combination with the previous generic Theorems 1 and 2 to obtain specialized results for distributed/federated optimization utilizing either direct gradient compression (DC framework (Algorithm 6)), or compression of gradient differences (DIANA framework (Algorithm 7)), respectively. In Tables 1–4 we visualize how these theorems lead to corollaries which describe the detailed complexity results of various existing and new methods.

**Accuracy:** For all existing methods, the rates we obtain using our general analysis match the best known rates.

Table 1: Selected methods that fit our unified analysis framework for *nonconvex optimization* \((m = 1, i.e., single node)\).

| Problem            | Assumption | Method | Algorithm | Convergence result | Recover |
|--------------------|------------|--------|-----------|--------------------|---------|
| (1.4)              | Asp 2      | GD     | Alg 2     | Thm 1              | Cor 1   |
| (1.4) with (1.5) or (1.6) | Asp 2 | SGD    | Alg 3     | Cor 2              | [12, 23] |
| (1.4) with (1.6)   | Asp 3      | L-SVRG | Alg 4     | Cor 3              | [50, 3, 36, 49] |
| (1.4) with (1.6)   | Asp 4      | SAGA   | Alg 5     | Cor 4              | [51]    |

Table 2: Selected methods that fit our unified analysis framework for *nonconvex distributed/federated optimization* \((m \geq 1, i.e., any number of nodes)\).

| Problem            | Assumption | Method   | Algorithm | Convergence result | Recover |
|--------------------|------------|----------|-----------|--------------------|---------|
| (1.1)              | Asp 5      | DC-GD    | Alg 8     | Thm 1, 3           | Cor 5   |
| (1.1) with (1.2) or (1.3) | Asp 5 | DC-SGD  | Alg 9     | Cor 6              | [23, 17] |
| (1.1) with (1.3)   | Asp 5, 6   | DC-LSVRG| Alg 10    | Cor 7              | New     |
| (1.1) with (1.3)   | Asp 5, 7   | DC-SAGA | Alg 11    | Cor 8              | New     |
| (1.1)              | Asp 5      | DIANA-GD | Alg 12    | Cor 9, New         |
| (1.1) with (1.2) or (1.3) | Asp 5 | DIANA-SGD | Alg 13    | Cor 10, New        |
| (1.1) with (1.3)   | Asp 5, 6   | DIANA-LSVRG | Alg 14   | Cor 11, New^1      |
| (1.1) with (1.3)   | Asp 5, 7   | DIANA-SAGA | Alg 15   | Cor 12, New^1      |

^1We want to mention that Horváth et al. [18] studied a weak version of DIANA-LSVRG and DIANA-SAGA with minibatch size \(b = 1\) (non-minibatch version). See Section 4.3 for more details.

Table 3: Selected methods that fit our unified analysis framework for *nonconvex optimization under the PL condition* \((m = 1)\).

| Problem            | Assumption | Method | Algorithm | Convergence result | Recover |
|--------------------|------------|--------|-----------|--------------------|---------|
| (1.4)              | Asp 2, 8   | GD     | Alg 2     | Thm 2              | Cor 13  |
| (1.4) with (1.5) or (1.6) | Asp 2, 8 | SGD    | Alg 3     | Cor 14              | [23]    |
| (1.4) with (1.6)   | Asp 3, 8   | L-SVRG | Alg 4     | Cor 15              | [51, 36] |
| (1.4) with (1.6)   | Asp 4, 8   | SAGA   | Alg 5     | Cor 16              | [51]    |

Table 4: Selected methods that fit our unified analysis framework for *nonconvex distributed/federated optimization under PL condition* \((m \geq 1)\).

| Problem            | Assumption | Method   | Algorithm | Convergence result | Recover |
|--------------------|------------|----------|-----------|--------------------|---------|
| (1.1)              | Asp 5, 8   | DC-GD    | Alg 8     | Thm 2, 3           | Cor 17  |
| (1.1) with (1.2) or (1.3) | Asp 5, 8 | DC-SGD  | Alg 9     | Cor 18              | New     |
| (1.1) with (1.3)   | Asp 5, 6, 8 | DC-LSVRG | Alg 10    | Cor 19              | New     |
| (1.1) with (1.3)   | Asp 5, 7, 8 | DC-SAGA | Alg 11    | Cor 20              | New     |
| (1.1)              | Asp 5, 8   | DIANA-GD | Alg 12    | Cor 21              | New     |
| (1.1) with (1.2) or (1.3) | Asp 5, 8 | DIANA-SGD | Alg 13    | Cor 22              | New     |
| (1.1) with (1.3)   | Asp 5, 6, 8 | DIANA-LSVRG | Alg 14   | Cor 23              | New     |
| (1.1) with (1.3)   | Asp 5, 7, 8 | DIANA-SAGA | Alg 15   | Cor 24              | New     |
2 Notation and Assumptions

We now introduce the notation and assumptions that we will use throughout the rest of the paper.

2.1 Notation

Let \( \Delta_0 := f(x^0) - f^\ast \), where \( f^\ast := \min_{x \in \mathbb{R}^d} f(x) \). Let \( [n] \) denote the set \( \{1, 2, \ldots, n\} \) and \( \| \cdot \| \) denote the Euclidean norm of a vector. Let \( \langle u, v \rangle \) denote the standard Euclidean inner product of two vectors \( u \) and \( v \). We use \( O(\cdot) \) notation to hide absolute constants. For notational convenience, we consider the online form (1.2) or (1.5) as the finite-sum form (1.3) or (1.6) by letting \( f_{i,j}(x) := f_i(x, \zeta_j) \) or \( f_i(x) := f(x, \zeta_i) \) and thinking of \( n \) as infinity (infinite data samples). By \( \mathbb{E}[\cdot] \) we denote mathematical expectation.

2.2 Assumptions

In order to prove convergence results, one usually needs one or more of the following standard smoothness assumptions for function \( f \), depending on the setting (see e.g., [45, 12, 32, 50, 3, 36, 8, 47, 23]).

**Assumption 2 (L-smoothness)** A function \( f : \mathbb{R}^d \rightarrow \mathbb{R} \) is \( L \)-smooth if

\[
\| \nabla f(x) - \nabla f(y) \| \leq L \| x - y \|, \quad \forall x, y \in \mathbb{R}^d. \quad (2.1)
\]

If one desires to obtain a refined analysis of SGD-type methods applied to finite-sum problems (1.6), the \( L \)-smoothness assumption can be replaced by average \( L \)-smoothness, defined next.

**Assumption 3 (Average L-smoothness)** A function \( f(x) := \frac{1}{n} \sum_{i=1}^{n} f_i(x) \) is average \( L \)-smooth if

\[
\mathbb{E}[\| \nabla f_i(x) - \nabla f_i(y) \|^2] \leq \frac{1}{n} \sum_{i=1}^{n} L_i^2 \| x - y \|^2 \leq L^2 \| x - y \|^2, \quad \forall x, y \in \mathbb{R}^d. \quad (2.2)
\]

Note that we slightly change the form of Assumption 3 for SAGA-type methods as follows:

**Assumption 4 (Average L-smoothness)** A function \( f(x) := \frac{1}{n} \sum_{i=1}^{n} f_i(x) \) is average \( L \)-smooth if

\[
\mathbb{E}[\| \nabla f_i(x) - \nabla f_i(y_i) \|^2] \leq L_i \frac{1}{n} \sum_{i=1}^{n} \| x - y_i \|^2, \quad \forall x, \{ y_i \}_{i \in [n]} \in \mathbb{R}^d. \quad (2.3)
\]

We now present smoothness assumptions suitable for the more general nonconvex federated problems, i.e., (1.1)–(1.3).

**Assumption 5 (L-smoothness)** For each work \( i \in [m] \), the function \( f_i(x) \) is \( L_i \)-smooth if

\[
\| \nabla f_i(x) - \nabla f_i(y) \| \leq L_i \| x - y \|, \quad \forall x, y \in \mathbb{R}^d. \quad (2.4)
\]

Moreover, we define \( L^2 := \frac{1}{m} \sum_{i=1}^{m} L_i^2 \). Note that Assumption 5 reduces to Assumption 2 in single node case (i.e., \( m = 1 \)). Similarly, for nonconvex federated finite-sum problems, i.e., (1.3), we also need the average \( L \)-smoothness assumption (Assumption 3) for each worker \( i \).

**Assumption 6 (Average L-smoothness)** A function \( f_i(x) := \frac{1}{n} \sum_{j=1}^{n} f_{i,j}(x) \) is average \( L \)-smooth if

\[
\mathbb{E}[\| \nabla f_{i,j}(x) - \nabla f_{i,j}(y) \|^2] \leq \frac{1}{n} \sum_{j=1}^{n} L_{i,j}^2 \| x - y \|^2 \leq L^2 \| x - y \|^2, \quad \forall x, y \in \mathbb{R}^d. \quad (2.5)
\]

Similarly, we slightly change the form of Assumption 6 for SAGA-type methods as follows:
Assumption 7 (Average $\bar{L}$-smoothness) A function $f_i(x) := \frac{1}{n} \sum_{j=1}^{n} f_{i,j}(x)$ is average $\bar{L}$-smooth if
\[
\mathbb{E}[\|\nabla f_{i,j}(x) - \nabla f_{i,j}(y_{i,j})\|^2] \leq \bar{L}^2 \frac{1}{n} \sum_{j=1}^{n} \|x - y_{i,j}\|^2, \quad \forall x, \{y_{i,j}\}_{j \in [n]} \in \mathbb{R}^d. \tag{2.6}
\]

Moreover, we also provide a unified analysis for nonconvex (federated) optimization problems (1.1)–(1.6) under the Polyak-Lojasiewicz (PL) condition [48].

Assumption 8 (PL condition) A function $f$ satisfies the PL condition if
\[
\exists \mu > 0, \text{ such that } \|\nabla f(x)\|^2 \geq 2\mu (f(x) - f^*), \quad \forall x \in \mathbb{R}^d, \tag{2.7}
\]
where $f^* := \min_{x \in \mathbb{R}^d} f(x)$ denotes the optimal function value.

It is worth noting that the PL condition does not imply convexity of $f$. For example, $f(x) = x^2 + 3\sin^2 x$ is a nonconvex function but it satisfies PL condition with $\mu = 1/32$. Karimi et al. [21] showed that PL condition is weaker than many conditions, e.g., strong convexity (SC), weak strong convexity (WSC), and error bound (EB). Moreover, if $f$ is convex, PL condition is equivalent to the error bound (EB) and quadratic growth (QG) condition [41, 4].

3 Main Unified Theorems and Simple Special Cases

In this section we first provide our main unified complexity results (Section 3.1), and subsequently enumerate a few special cases to showcase the flexibility of our unified approach in accurately describing specific SGD methods (Section 3.2).

3.1 Main unified theorems

We first state Theorem 1, which covers a large family of SGD methods (Algorithm 1) under the general parametric assumption (Assumption 1). The theorem says that SGD converges at the rate $O(\cdot \frac{1}{\epsilon^2})$ or $O(\cdot \frac{1}{\epsilon^4})$, depending in the value of the parameters.

**Theorem 1 (Main theorem)** Suppose that Assumptions 1 and 2 hold. Use the fixed stepsize
\[
\eta_k \equiv \eta = \min \left\{ \frac{1}{LB_1 + LD_1B_2\rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1A_2\rho^{-1})K}}, \frac{\epsilon^2}{2L(C_1 + D_1C_2\rho^{-1})} \right\}
\]
and let $\Delta_0 := f(x^0) - f^* + 2^{-1}L\eta^2 D_3\rho^{-1}\sigma_0^2$. Then the number of iterations performed by Algorithm 1 to find an $\epsilon$-solution, i.e., a point $\hat{x}$ such that
\[
\mathbb{E}[\|\nabla f(\hat{x})\|] \leq \epsilon,
\]
can be bounded by
\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ B_1 + D_1B_2\rho^{-1}, \frac{12\Delta_0 (A_1 + D_1A_2\rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1C_2\rho^{-1})}{\epsilon^2} \right\}. \tag{3.1}
\]

We now state Theorem 2, which covers a large family of SGD methods (Algorithm 1) if in addition the PL condition (Assumption 8) is satisfied. Note that under the PL condition, one can obtain a faster linear convergence $O(\cdot \log \frac{1}{\epsilon})$ (Theorem 2) rather than the sublinear convergence of Theorem 1.
Theorem 2 (Main theorem under PL condition) Suppose that Assumptions 1, 2 and 8 hold. Set the stepsize as

\[ \eta_k = \begin{cases} \eta & \text{if } k \leq \frac{K}{2}, \\ \frac{2\eta}{2+(k-\frac{K}{2})\mu} & \text{if } k > \frac{K}{2} \end{cases} \]

and let \( \Delta'_0 := f(x^0) - f^* + 2\eta^2 D_1 \rho^{-1} \sigma_k^2 \) and \( \kappa := \frac{4}{\mu} \). Then the number of iterations performed by Algorithm 1 to find an \( \epsilon \)-solution, i.e., a point \( x^K \) such that

\[ \mathbb{E}[f(x^K) - f^*] \leq \epsilon, \]

can be bounded by

\[ K = \max \left\{ 2 \left( B_1 + 2D_1 B_2 \rho^{-1} + (LA_1 + 2LD_1 A_2 \rho^{-1})\mu^{-1} \right) \kappa \log \frac{2\Delta'_0}{\epsilon}, \frac{10(C_1 + 2D_1 C_2 \rho^{-1})\kappa}{\mu \epsilon} \right\}. \tag{3.2} \]

In the following sections and appendices, we show that many specific methods, existing and new, satisfy our unified Assumption 1 and can thus be captured by our unified analysis (i.e., Theorems 1 and 2). We can thus plug their corresponding parameters (i.e., specific values for \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \)) into our unified Theorems 1 and 2 to obtain detailed convergence rates for these methods. See Tables 1 and 3 for an overview.

In particular, we give two general frameworks, i.e., DC framework (Algorithm 6) and DIANA framework (Algorithm 7) for the general nonconvex federated problems (1.1)–(1.3). We provide Theorems 3 and 4 showing that optimization methods belonging to the DC and DIANA frameworks also satisfy our unified Assumption 1, and can thus also be captured by our unified analysis to obtain detailed convergence rates in the nonconvex distributed regime. See Tables 2 and 4 for an overview.

3.2 Simple special cases \((m = 1)\)

As a case study, we first focus on the single node case (i.e., \( m = 1 \)), i.e., on the standard problem (1.4) with online form (1.5) or finite-sum form (1.6), i.e.,

\[ \min_{x \in \mathbb{R}^d} f(x), \]

where

\[ f(x) := \mathbb{E}_{\zeta \sim \mathcal{D}}[f(x, \zeta)], \quad \text{or} \quad f(x) := \frac{1}{n} \sum_{i=1}^{n} f_i(x). \]

In the following, we prove that some classical methods such as GD (Section 3.2.1), SGD (Section 3.2.2), L-SVRG (Section 3.2.3) and SAGA (Section 3.2.4) satisfy our unified Assumption 1, and thus can be captured by our unified convergence analysis, i.e., Theorems 1 and 2.

3.2.1 GD method

The vanilla gradient descent (GD) method is formalized as Algorithm 2.

\begin{algorithm}
\caption{GD}
1: In Line 2 of Algorithm 1: \( g^k = \nabla f(x^k) \)
\end{algorithm}

We now show that the gradient estimator used in GD, i.e., the true/full gradient, satisfies Assumption 1.

Lemma 1 (GD estimator satisfies Assumption 1) The gradient estimator \( g^k = \nabla f(x^k) \) satisfies the unified Assumption 1 with parameters

\[ A_1 = C_1 = D_1 = 0, \quad B_1 = 1, \quad \sigma_k^2 \equiv 0, \quad \rho = 1, \quad A_2 = B_2 = C_2 = 0. \]
3.2.2 SGD method

Many (but not all) variants of stochastic gradient descent (SGD) can be written in the form of Algorithm 3.

Algorithm 3 SGD [23]

1: In Line 2 of Algorithm 1:

\[ g^k = \begin{cases} 
\nabla f_i(x^k), & \text{Standard SGD} \\
\mathcal{C}(\nabla f(x^k)), & \text{Compressed gradient, e.g., quantized gradient, sparse gradient, etc} \\
\nabla f(x^k) + \xi, & \text{Noisy gradient} \\
\sum_{i \in I} v_i \nabla f_i(x^k), & \text{minibatch SGD, SGD with importance or arbitrary sampling} \\
\ldots, & \text{Combinations (e.g., minibatch compressed SGD, noisy SGD) and beyond}
\end{cases} \]

Khaled and Richtárik [23] showed that the stochastic gradient estimators used in many variants of SGD for nonconvex smooth problems, including variants performing minibatching, importance sampling, gradient compression and their combinations, satisfy the following generalized expected smoothness (ES) assumption.

Assumption 9 (ES: Expected Smoothness [23]) The gradient estimator \( g(x) \) is unbiased \( \mathbb{E}[g(x)] = \nabla f(x) \) and there exist non-negative constants \( A, B, C \) such that

\[
\mathbb{E}[\|g(x)\|^2] \leq 2A(f(x) - f^*) + B\|\nabla f(x)\|^2 + C, \quad \forall x \in \mathbb{R}^d. \tag{3.3}
\]

Our work can be seen as a further and substantial generalization of their approach, one that allows for many more methods to be captured by a single assumption and analysis. In particular, our unified Assumption 1 can capture the behavior of the gradient estimator constructed by variance reduced methods while ES assumption cannot. The next lemma says that, indeed, our unified Assumption 1 recovers the ES assumption in a special case.

Lemma 2 (SGD estimator satisfies Assumption 1) Any gradient estimator \( g^k \) satisfying the Expected Smoothness Assumption 9, i.e.,

\[
\mathbb{E}_k[\|g^k\|^2] \leq 2A(f(x^k) - f^*) + B\|\nabla f(x^k)\|^2 + C,
\]

(used in Line 2 of Algorithm 3) satisfies the unified Assumption 1 with parameters

\[ A_1 = A, \quad B_1 = B, \quad C_1 = C, \quad D_1 = 0, \quad \sigma_k^2 \equiv 0, \quad \rho = 1, \quad A_2 = B_2 = C_2 = 0. \]

3.2.3 L-SVRG method

The loopless (minibatch) SVRG method (L-SVRG) developed by Hofmann et al. [16] and rediscovered by Kovalev et al. [28] is formalized as Algorithm 4. Kovalev et al. [28] only studied L-SVRG in the strongly convex setting with \( b = 1 \) (no minibatch). Recently, Qian et al. [49] studied L-SVRG in the nonconvex case.

Algorithm 4 Loopless SVRG (L-SVRG) [16, 28]

Input: initial point \( x^0 = w^0 \), stepsize \( \eta_k \), minibatch size \( b \), probability \( p \in (0,1] \)

1: for \( k = 0, 1, 2, \ldots \) do

2: \[ g^k = \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \nabla f(w^k) \quad (I_b \text{ denotes random minibatch with } |I_b| = b) \]

3: \[ x^{k+1} = x^k - \eta_k g^k \]

4: \[ w^{k+1} = \begin{cases} 
   x^{k}, \quad \text{with probability } p \\
   w^{k}, \quad \text{with probability } 1 - p
\end{cases} \]

5: end for

We now show that the gradient estimator used in L-SVRG satisfies Assumption 1.
Lemma 3 (L-SVRG estimator satisfies Assumption 1) Suppose that Assumption 3 holds. The L-SVRG gradient estimator
\[
g^k = \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \nabla f(w^k)
\]
(see Line 2 in Algorithm 4) satisfies the unified Assumption 1 with parameters
\[
A_1 = A_2 = C_1 = C_2 = 0, \\
B_1 = 1, \\
D_1 = \frac{L^2}{b}, \\
\sigma_k^2 = \|x^k - w^k\|^2, \\
\rho = \frac{p}{2} + \frac{p^2}{2} - \frac{\eta^2 L^2}{b}, \\
B_2 = \frac{2\eta^2}{\rho} - \eta^2.
\]
As we discussed in Section 1.2, for variance-reduced methods, the gradient estimator usually satisfies the unified Assumption 1 with \(D_1 > 0\) and \(C_1 = 0\). The recurrence (1.8) describes the variance reduction process, with parameter \(\rho\) describing the speed of variance reduction. Here \(C_2\) is also 0, thus L-SVRG is fully variance reduced, which typically means faster convergence rate. This can be see from our main Theorems 1 and 2. Indeed, i) for Theorem 1, note that because \(A_1 = A_2 = C_1 = C_2 = 0\), the two \(O(\frac{1}{\rho})\) terms appearing in the max in (3.1) disappear, and hence the rate of L-SVRG is \(O(\frac{1}{\rho})\) as opposed to the generic rate \(O(\frac{1}{\rho})\) of less refined (i.e., not variance reduced) SGD variants. ii) for Theorem 2, note that because \(C_1 = C_2 = 0\), the last term \(O(\frac{1}{\rho})\) in (3.2) disappears, and hence the rate of L-SVRG is linear \(O(\kappa \log \frac{1}{\rho})\) as opposed to the worse sublinear rate \(O(\frac{1}{\rho})\) of less refined (i.e., not variance reduced) SGD variants.

3.2.4 SAGA method

The (minibatch) SAGA method developed by Defazio et al. [7] (in convex setting) is formalized as Algorithm 5. Here we analyze it and obtain convergence rates in nonconvex setting.

Algorithm 5 SAGA [7]

Input: initial point \(x^0, \{w^0_i\}_{i=1}^n\), stepsizes \(\eta_k\), minibatch size \(b\)

1: for \(k = 0, 1, 2, \ldots\) do
2: \(g^k = \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \frac{1}{n} \sum_{j=1}^n \nabla f_j(x^k) \quad (I_b \) denotes random minibatch with \(|I_b| = b\)\)
3: \(x^{k+1} = x^k - \eta_k g^k\)
4: \(w_i^{k+1} = \left\{ \begin{array}{ll} x^k, & \text{for } i \in I_b \\ w_i^k, & \text{for } i \notin I_b \end{array} \right. \)
5: end for

We now show that the gradient estimator used in SAGA satisfies Assumption 1.

Lemma 4 (SAGA estimator satisfies Assumption 1) Suppose that Assumption 4 holds. The SAGA gradient estimator
\[
g^k = \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \frac{1}{n} \sum_{j=1}^n \nabla f_j(x^k)
\]
(see Line 2 in Algorithm 5) satisfies the unified Assumption 1 with parameters
\[
A_1 = A_2 = C_1 = C_2 = 0, \\
B_1 = 1, \\
D_1 = \frac{L^2}{b}, \\
\sigma_k^2 = \frac{1}{n} \sum_{i=1}^n \|x^k - w_i^k\|^2, \\
\rho = \frac{b}{2n} + \frac{b^2}{2n^2} - \frac{\eta^2 L^2}{b}, \\
B_2 = \frac{2\eta^2}{\rho} - \eta^2.
\]
Remark: We obtain the detailed convergence rates for these methods by plugging their corresponding specific values of \(A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho\) (see Lemmas 1–4) into our unified Theorems 1 and 2. See Tables 1 and 3 for an overview.
4 General Nonconvex Federated Optimization Problems

In this section, we consider the more general nonconvex distributed/federated problem (1.1) with online form (1.2) or finite-sum form (1.3), i.e.,

$$\min_{x \in \mathbb{R}^d} \left\{ f(x) := \frac{1}{m} \sum_{i=1}^{m} f_i(x) \right\},$$

where

$$f_i(x) := \mathbb{E}_{\zeta \sim \mathcal{D}_i}[f_i(x, \zeta)], \quad \text{or} \quad f_i(x) := \frac{1}{n} \sum_{j=1}^{n} f_{i,j}(x).$$

Here we allow different machines/workers to have different data distributions, i.e., we consider the non-IID (heterogeneous) data setting. Note that in distributed/federated problems, the bottleneck usually is the communication cost among workers, which motivates the study of methods which employ compressed communication.

In the following, we provide two general algorithmic frameworks differing in whether direct gradient compression (DC) or compression of gradient differences (DIANA) is used. Previous approaches mostly focus on strongly convex or convex problems for specific instances of SGD. Ours is the first unified analysis covering many variants of SGD in a single theorem, covering the nonconvex regime. In fact, many specific SGD methods arising as special cases of our general approach have not been analyzed before.

4.1 Compression operators

Compressed communication is modeled by the application of a (randomized) compression operator to the communicated messages, as described next.

**Definition 1 (Compression operator)** A randomized map $C : \mathbb{R}^d \rightarrow \mathbb{R}^d$ is an $\omega$-compression operator if

$$\mathbb{E}[C(x)] = x, \quad \mathbb{E}[\|C(x) - x\|^2] \leq \omega \|x\|^2, \quad \forall x \in \mathbb{R}^d. \quad (4.1)$$

In particular, no compression ($C(x) \equiv x$) implies $\omega = 0$.

Note that (4.1) holds for many practical compression methods, e.g., random sparsification [53], quantization [1], natural compression [17]. We are not going to focus on any specific compression operator; instead, we will analyze our methods for any compression operator captured by the above definition.

4.2 DC framework for nonconvex federated optimization

In the direct compression (DC) framework studied in this section, each machine $i \in [m]$ computes its local stochastic gradient $\tilde{g}_i^k$, subsequently applies to it a compression operator $C_i^k$, and communicates the compressed vector to a server, or to all other nodes (see Algorithm 6).

**Algorithm 6** DC framework of stochastic gradient methods for nonconvex federated optimization

| Step | Description |
|------|-------------|
| 1. | **Input:** initial point $x^0 \in \mathbb{R}^d$, stepsizes $\eta_k$ |
| 2. | **for** $k = 0, 1, 2, \ldots$ **do** |
| 3. | **for all machines** $i = 1, 2, \ldots, m$ **do in parallel** |
| 4. | Compute local stochastic gradient $\tilde{g}_i^k$ |
| 5. | Compress local gradient $C_i^k(\tilde{g}_i^k)$ and send it to the server |
| 6. | **end for** |
| 7. | Aggregate received compressed gradient information: $g^k = \frac{1}{m} \sum_{i=1}^{m} C_i^k(\tilde{g}_i^k)$ |
| 8. | $x^{k+1} = x^k - \eta_k g^k$ |
| 9. | **end for** |

Our main theoretical result describing the convergence properties of Algorithm 6 is stated next.
Theorem 3 (DC framework) If the local stochastic gradient $\bar{g}_k^i$ (see Line 3 of Algorithm 6) satisfies the recursions
\begin{align}
\mathbb{E}_k[\|\bar{g}_k^i\|^2] & \leq 2A_{1,i}(f_i(x_k) - f_i^*) + B_{1,i}\|\nabla f_i(x_k)\|^2 + D_{1,i}\sigma_{k,i}^2 + C_{1,i}, \\
\mathbb{E}_k[\sigma_{k+1,i}^2] & \leq (1 - \rho_i)\sigma_{k,i}^2 + 2A_{2,i}(f(x_k) - f^*) + B_{2,i}\|\nabla f(x_k)\|^2 + D_{2,i}\mathbb{E}_k[\|g_k\|^2] + C_{2,i},
\end{align}
then $g_k$ (see Line 6 of Algorithm 6) satisfies the unified Assumption 1 with
\[ A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{1}{m} \sum_{i=1}^m D_{1,i}\sigma_{k,i}^2, \quad C_1 = \frac{(1 + \omega)C}{m}, \]
\[ \rho = \min_i \rho_i - \tau, \quad A_2 = DA + \tau A, \quad B_2 = DB + DD, \quad C_2 = DC + \tau C, \]
where $A := \max_i (A_{1,i} + B_{1,i}L_i - L_i/(1 + \omega))$, $C := \frac{1}{m} \sum_{i=1}^m C_{1,i} + 2A\Delta_f^t$, $\Delta_f^t := f^* - \frac{1}{m} \sum_{i=1}^m f_i^*$, $\tau := \frac{(1 + \omega)D}{m}$, $D_A := \frac{1}{m} \sum_{i=1}^m D_{1,i}A_{2,i}$, $D_B := \frac{1}{m} \sum_{i=1}^m D_{1,i}B_{2,i}$, $D_D := \frac{1}{m} \sum_{i=1}^m D_{1,i}D_{2,i}$, and $D_C := \frac{1}{m} \sum_{i=1}^m D_{1,i}C_{2,i}$.

The above result means that, provided that the local gradient estimators $\bar{g}_k^i$ used in the DC framework (Algorithm 6) satisfy recursions (4.2)–(4.3), the global gradient estimator $g_k$ satisfies our unified Assumption 1, and hence our main convergence results, Theorem 1 and Theorem 2 can be applied.

To showcase the generality and expressive power of our DC framework, we describe several particular ways in which such local estimators can be generated, each leading to a particular instance DC-type method. In particular, we describe methods DC-GD (Algorithm 8), DC-SGD (Algorithm 9), DC-LSVRG (Algorithm 10) and DC-SAGA (Algorithm 11). In each case we show that recursions (4.2) and (4.3) are satisfied, and in doing so, we obtain new results in the nonconvex case with or without the PL condition. Details can be found in the appendix. See the first part of Table 2 and the first part of Table 4 for a summary of these particular methods. Note that all of these results are new, with the exception of DC-GD and DC-SGD in the nonconvex non-PL case.

4.3 DIANA framework for nonconvex federated optimization

We now highlight an inherent issue of the DC framework (Algorithm 6), which will serve as a motivation for the proposed DIANA framework described here. Considering any stationary point $\hat{x}$ such that $\nabla f(\hat{x}) = \sum_{i=1}^m \nabla f_i(\hat{x}) = 0$, the aggregated compressed gradient (even if the full gradient is used locally, i.e., $\bar{g}_k^i = \nabla f_i(x_k)$), is not equal to zero 0, i.e., $g(\hat{x}) = \frac{1}{m} \sum_{i=1}^m C_i(\nabla f_i(\hat{x})) \neq 0$. This effect slows down convergence of the methods in DC framework. To address this issue, we use the DIANA framework to compress the gradient differences instead (see Line 4 of Algorithm 7).

Algorithm 7 DIANA framework of stochastic gradient methods for nonconvex federated optimization

\begin{algorithm}
\textbf{Input:} initial point $x^0$, $\{h_i^0\}_{i=1}^m$, $h^0 = \frac{1}{m} \sum_{i=1}^m h_i^0$, stepsize parameters $\eta_k, \alpha_k$
1: for $k = 0, 1, 2, \ldots$ do
2: \hspace{1em} for all machines $i = 1, 2, \ldots, m$ do in parallel
3: \hspace{2em} Compute local stochastic gradient $\bar{g}_k^i$
4: \hspace{2em} Compress shifted local gradient $\bar{\Delta}_k^i = C_k^i(\bar{g}_k^i - h_k^i)$ and send $\bar{\Delta}_k^i$ to the server
5: \hspace{2em} Update local shift $h_{k+1}^i = h_k^i + \alpha_k C_k^i(\bar{g}_k^i - h_k^i)$
6: \hspace{1em} end for
7: Aggregate received compressed gradient information: $g_k = h_k + \frac{1}{m} \sum_{i=1}^m \bar{\Delta}_k^i$
8: $x_{k+1} = x_k - \eta_k g_k$
9: $h_{k+1} = h_k + \alpha_k \frac{1}{m} \sum_{i=1}^m \bar{\Delta}_k^i$
10: end for
\end{algorithm}
The DIANA framework was previously studied by Mishchenko et al. [43], Horváth et al. [18], Chraibi et al. [6] for a few specific instances of SGD and mainly in strongly convex or convex problems. Ours is the first unified analysis covering many variants of SGD in a single theorem, covering the nonconvex regime.

Concretely, Chraibi et al. [6] analyze the strongly convex or convex problem of finding a fixed point with strong assumptions. Here we analyze the more general nonconvex setting with a more general unified assumption. Mishchenko et al. [43] analyze their methods for the ternary compression operator only, and their result in the nonconvex setting makes very strong assumptions on the local gradient estimators $\tilde{g}_k^i$. In particular, they assume that $\tilde{g}_k^i$ is unbiased, and that there exists $\sigma_i^2 \geq 0$ such that $\mathbb{E}_k[||\tilde{g}_k^i||^2] \leq ||\nabla f_i(x^k)||^2 + \sigma_i^2$. Note that this implies that $B_{1,i} = 1$ and $C_{1,i} = \sigma_i^2$ in recursion (4.2). This corresponds to a (rather restrictive) special case of recursions (4.2)–(4.3) with the rest of the parameters rendered “inactive”: $A_{1,i} = D_{1,i} = A_{2,i} = B_{2,i} = C_{2,i} = D_{2,i} = 0$, and $\rho_i = 1$. Hence, when compared to [43], our results for the DIANA framework can be seen as a generalization to arbitrary compression operators described by Definition 1, to a much more general class of local gradient estimators (including more methods), and to the PL setting. Further, Horváth et al. [18] lift some of the deficiencies of [43]. In particular, they consider general compression operators, and consider the finite-sum setting in which they use two particular variance reduced estimators $\tilde{g}_k^i$, i.e., L-SVRG and SAGA with minibatch size $b = 1$ (non-minibatch version). Our work can be seen as a generalization of their work to the potentially infinite family of local gradient estimators described by recursions (4.2)–(4.3), and further to the PL setting. Note that our framework allows for the analysis of more general variants of DIANA, such as DIANA-LSVRG or DIANA-SAGA with additional additive noise and with minibatch $b \geq 1$ (note that one can enjoy a linear speedup by adopting minibatch in parallel), which can be helpful in some situations.

Our main result for DIANA framework is described in the following Theorem 4.

**Theorem 4 (DIANA framework)** Suppose that the local stochastic gradient $\tilde{g}_k^i$ (see Line 3 of Algorithm 7) satisfies (4.2)–(4.3), same as in the DC framework. Then $g_k$ (see Line 7 of Algorithm 7) satisfies the unified Assumption 1 with

\[
A_1 = \frac{(1+\omega)A}{m}, \quad B_1 = 1, \quad D_1 = \frac{1+\omega}{m}, \quad \sigma_k^2 = \frac{1}{m} \sum_{i=1}^m D_{1,i} \sigma_{k,i}^2 + \frac{\omega}{(1+\omega)m} \sum_{i=1}^m ||\nabla f_i(x^k) - h_k^i||^2, \\
C_1 = \frac{(1+\omega)C}{m}, \quad \rho = \min \left\{ \min_i \rho_i - \tau, \quad 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau \right\}, \quad A_2 = D_A + \tau A, \quad B_2 = D_B + B, \quad C_2 = D_C + \tau C,
\]

where $A := \max_i (A_{1,i} + (B_{1,i} - 1)L_i)$, $B := \frac{\omega(1+\beta)L_i^2}{1+\omega} + D_D$, $C := \frac{1}{m} \sum_{i=1}^m C_{1,i} + 2A\Delta_f^*, \Delta_f^* := f^* - \frac{1}{m} \sum_{i=1}^m f_i^*, \tau := \alpha^2 \omega + \frac{(1+\omega)B}{m}$, $D_A := \frac{1}{m} \sum_{i=1}^m D_{1,i} A_{2,i}$, $D_B := \frac{1}{m} \sum_{i=1}^m D_{1,i} B_{2,i}$, $D_D := \frac{1}{m} \sum_{i=1}^m D_{1,i} D_{2,i}$, and $\forall \beta > 0$.

Similarly, the above result means that, provided the local gradient estimators $\tilde{g}_k^i$ used in the DIANA framework (Algorithm 7) satisfy recursions (4.2)–(4.3), the global gradient estimator $g_k$ satisfies our unified Assumption 1, and hence our main convergence results, Theorem 1 and Theorem 2 can be applied.

To showcase the generality and expressive power of our DIANA framework, we describe several particular ways in which such local estimators can be generated, each leading to a particular instance of a DIANA-type method. In particular, we describe methods DIANA-GD (Algorithm 12), DIANA-SGD (Algorithm 13), DIANA-LSVRG (Algorithm 14) and DIANA-SAGA (Algorithm 15). In each case we show that recursions (4.2) and (4.3) are satisfied, and in doing so, we obtain complexity results in the nonconvex case with or without the PL condition. Details can be found in the appendix. See the second part of Table 2 and the second part of Table 4 for a summary of these particular methods. Note that all of these results are new, with the exception of a weak version of DIANA-LSVRG and DIANA-SAGA studied by Horváth et al. [18] (as discussed above) in the nonconvex non-PL case.
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A  Missing Proofs for Unified Main Theorems

In this section, we provide the detailed proofs for our unified main theorems with/without PL condition.

A.1  Proof of unified Theorem 1

We first restate our unified Theorem 1 and then provide the detailed proof.

Theorem 1 (Main theorem) Suppose that Assumptions 1 and 2 hold. Let stepsize
\[ \eta_k \equiv \eta \leq \min \left\{ \frac{1}{LB_1 + LD_2 \rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}, \sqrt{\frac{\epsilon^2}{2LC_1 + D_2 \rho^{-1}}} \right\}, \]
then the number of iterations performed by Algorithm 1 to find an \( \epsilon \)-solution, i.e., a point \( \tilde{x} \) such that
\[ \mathbb{E}[\|\nabla f(\tilde{x})\|] \leq \epsilon, \]
can be bounded by
\[ K = \frac{8\Delta_0 L}{\epsilon^2} \left\{ B_1 + D_2 \rho^{-1}, \frac{12\Delta_0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_2 \rho^{-1})}{\epsilon^2} \right\}, \]  
where \( \Delta_0 := f(x^0) - f^* + 2^{-1} L\eta^2 D_1 \rho^{-1} \sigma_0^2. \)

Proof: First, we obtain the relation between \( f(x^{k+1}) \) and \( f(x^k) \):
\[ f(x^{k+1}) \leq f(x^k) + \langle \nabla f(x^k), x^{k+1} - x^k \rangle + \frac{\rho}{2} \| x^{k+1} - x^k \|^2 \]  
(A.2)
\[ = f(x^k) - \eta \langle \nabla f(x^k), g^k \rangle + \frac{L\eta^2}{2} \| g^k \|^2, \]  
(A.3)
where (A.2) uses \( L \)-smoothness of \( f \) (see (2.1)), and (A.3) follows from the update step \( x^{k+1} = x^k - \eta g^k \) (Line 3 of Algorithm 1). Now, we take expectation for (A.3) conditional on the past, i.e., \( x^{0:k} \), denoted as \( \mathbb{E}_k \):
\[ \mathbb{E}_k[f(x^{k+1})] \leq f(x^k) - \eta \| \nabla f(x^k) \|^2 + \frac{L\eta^2}{2} \mathbb{E}_k[\| g^k \|^2] \]
\[ \mathbb{E}_k[f(x^{k+1}) - f^*] \leq f(x^k) - f^* - \eta \| \nabla f(x^k) \|^2 + \frac{L\eta^2}{2} \mathbb{E}_k[\| g^k \|^2] \]
\[ \leq (1 + L\eta^2 A_1)(f(x^k) - f^*) - \left( \eta - \frac{L\eta^2 B_1}{2} \right) \| \nabla f(x^k) \|^2 + \frac{L\eta^2 D_1}{2} \sigma_0^2 + \frac{L\eta^2}{2} C_1 \]
where these inequalities hold by using our unified Assumption 1. Then according to (1.8) in Assumption 1, we have, for \( \forall \alpha > 0 \)
\[ \mathbb{E}_k[f(x^{k+1}) - f^* + \alpha \sigma_{k+1}^2] \leq (1 + L\eta^2 A_1 + 2\alpha A_2)(f(x^k) - f^*) + \left( \frac{L\eta^2 D_1}{2} + \alpha(1 - \rho) \right) \sigma_k^2 \]
\[ - \left( \eta - \frac{L\eta^2 B_1}{2} - \alpha B_2 \right) \| \nabla f(x^k) \|^2 + \frac{L\eta^2}{2} C_1 + \alpha C_2. \]

Now, we take expectation again and define
\[ \Delta_{k+1} := f(x^{k+1}) - f^* + \alpha \sigma_{k+1}^2 \]  
(A.4)
\[ \beta := 1 + L\eta^2 A_1 + 2\alpha A_2 \]  
(A.5)
\[ \eta' := \eta - \frac{L\eta^2 B_1}{2} - \alpha B_2 \]  
(A.6)
\[ C := \frac{L\eta^2}{2} C_1 + \alpha C_2 \]  
(A.7)
to obtain
\[
\mathbb{E}[\Delta^{k+1}] \leq \beta \mathbb{E}[f(x^k) - f^*] + \left( \frac{L\eta^2 D_1}{2} + \alpha(1 - \rho) \right) \mathbb{E}[\sigma_k^2] - \eta' \mathbb{E}[\|\nabla f(x^k)\|^2] + C
\]
\[
= \beta \mathbb{E} \left[ f(x^k) - f^* + \left( \frac{L\eta^2 D_1}{2} + \alpha(1 - \rho) \right) \sigma_k^2 \right] - \eta' \mathbb{E}[\|\nabla f(x^k)\|^2] + C
\]
\[
\leq \beta \mathbb{E}[\Delta^k] - \eta' \mathbb{E}[\|\nabla f(x^k)\|^2] + C, \quad (A.8)
\]
where the last inequality holds by setting
\[
\alpha = \frac{L\eta^2 D_1}{2\rho}, \quad (A.9)
\]
the reason is as follows:
\[
\frac{L\eta^2 D_1}{2} + \alpha(1 - \rho) \leq \alpha^{(A.5)} \alpha(1 + L\eta^2 A_1 + 2\alpha A_2),
\]
\[
\frac{L\eta^2 D_1}{2} \leq \alpha(\rho + L\eta^2 A_1 + 2\alpha A_2).
\]

Now we rewrite (A.8) as
\[
\beta^{K-k} \eta' \mathbb{E}[\|\nabla f(x^k)\|^2] \leq \beta^{K-1-k} (\beta \mathbb{E}[\Delta^k] - \mathbb{E}[\Delta^{k+1}]) + \beta^{K-1-k} C
\]
\[
= \beta^{K-k} \mathbb{E}[\Delta^k] - \beta^{K-(k+1)} \mathbb{E}[\Delta^{k+1}] + \beta^{K-1-k} C, \quad \forall 0 \leq k \leq K - 1. \quad (A.10)
\]

Summing up (A.10) for 0 \leq k \leq K - 1 to get
\[
\sum_{k=0}^{K-1} \beta^{K-1-k} \eta' \mathbb{E}[\|\nabla f(x^k)\|^2] \leq \beta^K \mathbb{E}[\Delta^0] + \sum_{k=0}^{K-1} \beta^{K-1-k} C
\]
\[
\eta' \mathbb{E}[\|\nabla f(\hat{x})\|^2] \leq \frac{\beta^K}{\sum_{k=0}^{K-1} \beta^{K-1-k}} \Delta^0 + C, \quad (A.11)
\]
where \(\hat{x}\) randomly chosen from \(\{x^k\}_{k=0}^{K-1}\) with probability \(p_k = \frac{\beta^{K-1-k}}{\sum_{k=0}^{K-1} \beta^{K-1-k}}\) for \(x^k\). Now, we compute each parameter in (A.11):

\[
\eta' = (A.6) \eta - \frac{L\eta^2 B_1}{2} - \alpha B_2
\]
\[
(A.9) \eta = \frac{L\eta^2 B_1}{2} - \frac{L\eta^2 D_1 B_2}{2\rho}
\]
\[
= \eta - \frac{\eta}{2} (L\eta B_1 + L\eta D_1 B_2 \rho^{-1})
\]
\[
\geq \frac{\eta}{2}, \quad (A.12)
\]
where the last inequality holds by setting
\[
\eta \leq \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}. \quad (A.13)
\]
For the right-hand side, we have
\[
\sum_{k=0}^{K-1} \beta^K \sum_{k=0}^{K-1-k} (1 + L\eta^2 A_1 + 2\alpha A_2)^K \\
K \\
\leq \exp \left( \frac{(L\eta^2 A_1 + 2\alpha A_2)K}{K} \right) \\
\leq \frac{2}{K}, \quad (A.14)
\]
where the last inequality holds by setting
\[
\eta \leq \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}. \quad (A.15)
\]

For the last one \( C \), we have
\[
C \overset{(A.7)}{=} \frac{L\eta^2}{2} C_1 + \alpha C_2 \\
\overset{(A.9)}{=} \frac{L\eta^2}{2} C_1 + \frac{L\eta^2 D_1}{2\rho} C_2 \\
= \frac{\eta^2}{2} (LC_1 + LD_1 C_2 \rho^{-1}). \quad (A.16)
\]

Now, we plug (A.12), (A.14) and (A.16) into (A.11):
\[
\frac{\eta}{2} \mathbb{E}[\|\nabla f(\hat{x})\|^2] \leq \frac{2}{K} \Delta^0 + \frac{\eta^2}{2} (LC_1 + LD_1 C_2 \rho^{-1}) \\
\mathbb{E}[\|\nabla f(\bar{x})\|^2] \leq \frac{4}{K \eta} \Delta^0 + \eta(LC_1 + LD_1 C_2 \rho^{-1}) \\
\leq \frac{\epsilon^2}{2} + \frac{\epsilon^2}{2} = \epsilon. \quad (A.17)
\]
Thus, we find an \( \epsilon \)-solution, i.e. a point \( \hat{x} \) such that
\[
\mathbb{E}[\|\nabla f(\hat{x})\|] \leq \sqrt{\mathbb{E}[\|\nabla f(\bar{x})\|^2]} \leq \epsilon.
\]
Note that (A.17) holds by setting
\[
\eta \leq \frac{\epsilon^2}{2L(C_1 + D_1 C_2 \rho^{-1})}, \quad (A.18)
\]
and
\[
K = \frac{8\Delta^0}{\epsilon^2} \frac{1}{\eta} = \frac{8\Delta^0 L}{\epsilon^2} \max \left\{ \frac{B_1 + D_1 B_2 \rho^{-1}}{e^2}, \frac{12\Delta^0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\}, \quad (A.19)
\]
Note that according to (A.13), (A.15), (A.18), we know that \( \eta \) needs to satisfy
\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}} \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}, \frac{\epsilon^2}{2L(C_1 + D_1 C_2 \rho^{-1})} \right\}.
\]
Also, \( \Delta^0 \overset{(A.4)}{=} f(x^0) - f^* + \alpha \sigma_0^2 \overset{(A.9)}{=} f(x^0) - f^* + 2^{-1} L\eta^2 D_1 \rho^{-1} \sigma_0^2 \overset{\text{def}}{=} \Delta_0. \) \( \square \)
A.2 Proofs for unified theorems under PL condition

In this section, we provide the detailed proofs for our unified Theorem 5 (constant stepsize) and Theorem 2 (decreasing stepsize) under PL condition. Note that under the PL condition, one can obtain a faster linear convergence $O(\cdot \log \frac{1}{\epsilon})$ (see (A.20) in Theorem 5) rather than the sublinear convergence $O(\cdot)$ (see (A.1) in Theorem 1). Besides, one can get a tighter convergence rate if one uses decreasing stepsize $\eta_k$ in $x^{k+1} = x^k - \eta_k g^k$ (Line 3 of Algorithm 1) under PL condition. See Theorem 5 (constant stepsize) and Theorem 2 (decreasing stepsize) for a comparison.

A.2.1 Proof of unified Theorem 5 under PL condition (constant stepsize)

In this section, we first provide the unified Theorem 5 under PL condition with constant stepsize and then provide the detailed proof.

Theorem 5 (Main theorem under PL condition with constant stepsize) Suppose that Assumptions 1, 2 and 8 hold. Let stepsize

$$\eta_k = \eta \leq \min \left\{ \frac{1}{LB_1 + 2LD_1B_2\rho^{-1}} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}, \frac{\mu\epsilon}{LC_1 + 2LD_1C_2\rho^{-1}} \right\},$$

then the number of iterations performed by Algorithm 1 to find an $\epsilon$-solution, i.e. a point $x^K$ such that $E[f(x^K) - f^*] \leq \epsilon$, can be bounded by

$$K = \max \left\{ B_1 + 2D_1\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}, \frac{C_1 + 2D_1C_2\rho^{-1}}{\mu\epsilon} \right\} \kappa \log \frac{2\Delta_0'}{\epsilon},$$

where $\Delta_0' := f(x^0) - f^* + L\eta^2 D_1\rho^{-1}\sigma_0^2$ and $\kappa := L/\mu$.

Proof: Similar to the proof of Theorem 1, we obtain the relation between $f(x^{k+1})$ and $f(x^k)$:

$$f(x^{k+1}) \leq f(x^k) + \langle \nabla f(x^k), x^{k+1} - x^k \rangle + \frac{L}{2} \| x^{k+1} - x^k \|^2$$

(A.21)

$$= f(x^k) - \eta \langle \nabla f(x^k), g^k \rangle + \frac{L\eta^2}{2} \| g^k \|^2,$$

(A.22)

where (A.21) uses $L$-smoothness of $f$ (see (2.1)), and (A.22) follows from the update step $x^{k+1} = x^k - \eta g^k$ (Line 3 of Algorithm 1). Now, we take expectation for (A.22) conditional on the past, i.e., $x^{0:k}$, denoted as $E_k$:

$$E_k[f(x^{k+1})] \leq f(x^k) - \eta \| \nabla f(x^k) \|^2 + \frac{L\eta^2}{2} E_k[\| g^k \|^2]$$

$$E_k[f(x^{k+1}) - f^*] \leq f(x^k) - f^* - \eta \| \nabla f(x^k) \|^2 + \frac{L\eta^2}{2} E_k[\| g^k \|^2]$$

$$\leq (1 + L\eta^2 A_1)(f(x^k) - f^*) - \left( \eta - \frac{L\eta^2 B_1}{2} \right) \| \nabla f(x^k) \|^2$$

$$+ \frac{L\eta^2 D_1}{2} \sigma_k^2 + \frac{L\eta^2}{2} C_1,$$

where these inequalities hold by using our unified Assumption 1. Then according to (1.8) in Assumption 1, we have, for $\forall \alpha > 0$

$$E_k[f(x^{k+1}) - f^* + \alpha\sigma_{k+1}^2] \leq (1 + L\eta^2 A_1 + 2\alpha A_2)(f(x^k) - f^*) + \left( \frac{L\eta^2 D_1}{2} + \alpha (1 - \rho) \right) \sigma_k^2$$

$$- \left( \eta - \frac{L\eta^2 B_1}{2} - \alpha B_2 \right) \| \nabla f(x^k) \|^2 + \frac{L\eta^2}{2} C_1 + \alpha C_2.$$  (A.23)
Then, we apply PL condition (2.7) to (A.23):

\[
E_k[f(x^{k+1}) - f^* + \alpha \sigma_{k+1}^2] \leq (1 + L\eta^2 A_1 + 2\alpha A_2)(f(x^k) - f^*) + \left(\frac{L\eta^2 D_1}{2} + \alpha(1 - \rho)\right) \sigma_k^2 - 2\mu \left(\eta - \frac{L\eta^2 B_1}{2} - \alpha B_2\right) (f(x^k) - f^*) + \frac{L\eta^2}{2} C_1 + \alpha C_2.
\]  
(A.24)

Now, we take expectation again and define

\[
\Delta^{k+1} := f(x^{k+1}) - f^* + \alpha \sigma_{k+1}^2
\]  
(A.25)

\[
\beta := L\eta^2 A_1 + 2\alpha A_2
\]  
(A.26)

\[
\eta' := \eta - \frac{L\eta^2 B_1}{2} - \alpha B_2
\]  
(A.27)

\[
C := \frac{L}{2} C_1 + \frac{\alpha}{\eta^2} C_2
\]  
(A.28)

to obtain

\[
E[\Delta^{k+1}] \leq (1 - 2\mu\eta' + \beta)E[f(x^k) - f^*] + \left(\frac{L\eta^2 D_1}{2} + \alpha(1 - \rho)\right) E[\sigma_k^2] + C\eta^2
\]

\[
= (1 - 2\mu\eta' + \beta)E \left[ f(x^k) - f^* + \left(\frac{L\eta^2 D_1}{2} + \alpha(1 - \rho)\right) \sigma_k^2 \right] + C\eta^2
\]

\[
\leq (1 - \mu\eta)E[\Delta^k] + C\eta^2,
\]  
(A.29)

where the last inequality (A.29) holds by setting

\[
\alpha = \frac{L\eta^2 D_1}{\rho}, \quad \eta \leq \frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}},
\]  
(A.30)

since

\[
1 - 2\mu\eta' + \beta \overset{(A.27)}{=} 1 - 2\mu(\eta - \frac{L\eta^2 B_1}{2} - \alpha B_2) + \beta
\]

\[
\overset{(A.26)}{=} 1 - 2\mu(\eta - \frac{L\eta^2 B_1}{2} - \alpha B_2) + L\eta^2 A_1 + 2\alpha A_2
\]

\[
\overset{(A.30)}{=} 1 - 2\mu(\eta - \frac{L\eta^2 B_1}{2} - \frac{L\eta^2 D_1 B_2}{\rho} + L\eta^2 A_1 + \frac{2L\eta^2 D_1}{\rho} A_2)
\]

\[
= 1 - 2\mu \left(1 - \frac{1}{2} \left(L\eta B_1 + 2L\eta D_1 B_2\rho^{-1} + (L\eta A_1 + 2L\eta D_1 A_2\rho^{-1})\mu^{-1}\right)\right)
\]

\[
\overset{(A.30)}{=} 1 - \mu\eta.
\]  
(A.31)

Telescoping (A.29) for 0 ≤ k ≤ K − 1, we have

\[
E[\Delta^K] \leq (1 - \mu\eta)^K E[\Delta^0] + C\eta^2 \sum_{k=0}^{K-1} (1 - \mu\eta)^k
\]

\[
\leq (1 - \mu\eta)^K \Delta^0 + \frac{C\eta}{\mu}
\]

\[
\leq \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon.
\]  
(A.32)
Thus, we find an $\epsilon$-solution, i.e., a point $x^K$ such that

$$E[f(x^K) - f^*] \leq E[\Delta^K] \leq \epsilon.$$  

Note that (A.32) holds by setting

$$\eta \leq \frac{\mu \epsilon}{2C} \leq \frac{\mu \epsilon}{LC_1 + 2LD_1C_2} = \frac{\mu \epsilon}{LC_1 + 2LD_1C_2\rho^{-1}}$$  

(A.33)

and

$$K = \frac{1}{\mu \eta} \log \frac{2\Delta^0}{\epsilon}$$

$$= \max \left\{ \frac{B_1 + 2D_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}}{C_1 + 2D_1C_2\rho^{-1}}, \frac{L}{\mu} \log \frac{2\Delta^0}{\epsilon} \right\}.$$

Note that according to (A.30) and (A.33), we know that the step size $\eta$ needs to satisfy

$$\eta \leq \min \left\{ \frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}}, \frac{\mu \epsilon}{LC_1 + 2LD_1C_2\rho^{-1}} \right\}.$$

Also, $\Delta^0 := f(x^0) - f^* + \alpha \sigma_0^2$ (A.34) follows from the update step $x^k = x^k - \eta_k g^k$ (Line 3 of Algorithm 1) leads to a tighter convergence result (see (A.20) in Theorem 5 and (A.34) in Theorem 2 for a comparison).

A.2.2 Proof of unified Theorem 2 under PL condition (decreasing stepsize)

We first restate our unified Theorem 2 under PL condition with decreasing stepsize and then provide the detailed proof. The decreasing stepsize $\eta_k$ in $x^{k+1} = x^k - \eta_k g^k$ (Line 3 of Algorithm 1) leads to a tighter convergence result (see (A.20) in Theorem 5 and (A.34) in Theorem 2 for a comparison).

**Theorem 2 (Main theorem under PL condition with decreasing stepsize)** Suppose that Assumptions 1, 2 and 8 hold. Let stepsize

$$\eta_k = \begin{cases} \eta, & \text{if } k \leq K, \\ \frac{2\eta}{2 + (k - K)2}, & \text{if } k > K \end{cases},$$

where $\eta \leq \frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}}$, then the number of iterations performed by Algorithm 1 to find an $\epsilon$-solution, i.e., a point $x^K$ such that $E[f(x^K) - f^*] \leq \epsilon$, can be bounded by

$$K = \max \left\{ 2 \left( B_1 + 2D_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1} \right) \kappa \log \frac{2\Delta_0^0}{\epsilon}, \frac{L}{\mu} \log \frac{2\Delta_0^0}{\epsilon} \right\},$$

(A.34)

where $\Delta_0^0 := f(x^0) - f^* + L\eta_0^2D_1\rho^{-1}\sigma_0^2$ and $\kappa := L/\mu$.

**Proof:** Similar to the proof of Theorem 5, we obtain the relation between $f(x^{k+1})$ and $f(x^k)$:

$$f(x^{k+1}) \leq f(x^k) + \langle \nabla f(x^k), x^{k+1} - x^k \rangle + \frac{L}{2} \| x^{k+1} - x^k \|^2$$

(A.35)

$$= f(x^k) - \eta_k \langle \nabla f(x^k), g^k \rangle + \frac{L\eta_k^2}{2} \| g^k \|^2,$$

(A.36)

where (A.35) uses $L$-smoothness of $f$ (see (2.1)), and (A.36) follows from the update step $x^{k+1} = x^k - \eta_k g^k$ (Line 3 of Algorithm 1). Now, we take expectation for (A.36) conditional on the past, i.e., $x^{0:k}$, denoted as

23
\[ \mathbb{E}_k: \]
\[ \mathbb{E}_k[f(x^{k+1})] \leq f(x^k) - \eta_k \| \nabla f(x^k) \|^2 + \frac{L \eta_k^2}{2} \mathbb{E}_k[\| g^k \|^2] \]
\[ \mathbb{E}_k[f(x^{k+1}) - f^*] \leq f(x^k) - f^* - \eta_k \| \nabla f(x^k) \|^2 + \frac{L \eta_k^2}{2} \mathbb{E}_k[\| g^k \|^2] \]
\[ \leq (1 + L \eta_k^2 A_1)(f(x^k) - f^*) - \left( \eta_k - \frac{L \eta_k^2 B_1}{2} \right) \| \nabla f(x^k) \|^2 + \frac{L \eta_k^2 D_1}{2} \sigma_k^2 + \frac{L \eta_k^2}{2} C_1 \]

where these inequalities hold by using our unified Assumption 1. Then according to (1.8) in Assumption 1, we have, for \( \forall \alpha > 0 \)
\[ \mathbb{E}_k[f(x^{k+1}) - f^* + \alpha \sigma_{k+1}^2] \leq (1 + L \eta_k^2 A_1 + 2 \alpha A_2)(f(x^k) - f^*) + \left( \frac{L \eta_k^2 D_1}{2} + \alpha (1 - \rho) \right) \sigma_k^2 \]
\[ - \left( \eta_k - \frac{L \eta_k^2 B_1}{2} - \alpha B_2 \right) \| \nabla f(x^k) \|^2 + \frac{L \eta_k^2}{2} C_1 + \alpha C_2. \] (A.37)

Then, we apply PL condition (2.7) to (A.37):
\[ \mathbb{E}_k[f(x^{k+1}) - f^* + \alpha \sigma_{k+1}^2] \leq (1 + L \eta_k^2 A_1 + 2 \alpha A_2)(f(x^k) - f^*) + \left( \frac{L \eta_k^2 D_1}{2} + \alpha (1 - \rho) \right) \sigma_k^2 \]
\[ - 2 \mu \left( \eta_k - \frac{L \eta_k^2 B_1}{2} - \alpha B_2 \right) (f(x^k) - f^*) + \frac{L \eta_k^2}{2} C_1 + \alpha C_2. \] (A.38)

Now, we take expectation again and define
\[ \Delta^{k+1} := f(x^{k+1}) - f^* + \alpha \sigma_{k+1}^2 \] (A.39)
\[ \beta_k := L \eta_k^2 A_1 + 2 \alpha A_2 \] (A.40)
\[ \eta_k := \eta_k - \frac{L \eta_k^2 B_1}{2} - \alpha B_2 \] (A.41)
\[ C_k := \frac{L}{2} C_1 + \frac{\alpha}{\eta_k} C_2 \] (A.42)

to obtain
\[ \mathbb{E}[\Delta^{k+1}] \leq (1 - 2 \mu \eta_k' + \beta_k) \mathbb{E}[f(x^k) - f^*] + \left( \frac{L \eta_k^2 D_1}{2} + \alpha (1 - \rho) \right) \mathbb{E}[\sigma_k^2] + C_k \eta_k^2 \]
\[ = (1 - 2 \mu \eta_k' + \beta_k) \mathbb{E} \left[ f(x^k) - f^* + \left( \frac{L \eta_k^2 D_1}{2} + \alpha (1 - \rho) \right) \sigma_k^2 \right] + C_k \eta_k^2 \]
\[ \leq (1 - \mu \eta_k) \mathbb{E}[\Delta^k] + C_k \eta_k^2, \] (A.43)

where the last inequality (A.43) holds by setting
\[ \alpha = \frac{L \eta_k^2 D_1}{\rho}, \quad \eta_k \leq \frac{1}{LB_1 + 2 LD_1 B_2 \rho^{-1} + (LA_1 + 2 LD_1 A_2 \rho^{-1}) \mu^{-1}} \] (A.44)
since
\[
1 - 2\mu\eta_k + \beta_k \overset{(A.41)}{=} 1 - 2\mu(\eta_k - \frac{L\eta^2_k B_1}{2} - \alpha B_2) + \beta
\]
\[
\overset{(A.40)}{=} 1 - 2\mu(\eta_k - \frac{L\eta^2_k B_1}{2} - \alpha B_2) + \frac{L\eta^2_k A_1}{\rho} + 2\alpha A_2
\]
\[
\overset{(A.44)}{=} 1 - 2\mu\eta_k \left(1 - \frac{1}{2} (L\eta_k B_1 + 2L\eta_k D_1 B_2 \rho^{-1}) \mu^{-1}\right)
\]
\[
\leq 1 - \mu\eta_k. \quad (A.45)
\]

Note that \(C_k \overset{(A.42)}{=} \frac{L}{2} C_1 + \frac{\alpha}{\eta_k} C_2 = \frac{L}{2} C_1 + \frac{L D_1}{\rho} C_2\), thus we use \(C := \frac{L}{2} C_1 + \frac{L D_1}{\rho} C_2\) to denote \(C_k\) in (A.43)

\[
\mathbb{E}[\Delta^{k+1}] \leq (1 - \mu\eta_k)\mathbb{E}[\Delta^k] + \eta^2_k. \quad (A.46)
\]

To prove the convergence result with (A.46), we provide a key proposition as follows:

**Proposition 1** For any sequence \(\{M_k\}_{k=0}^{K}\) satisfying

\[
M_k \leq (1 - ab_k)M_{k-1} + cb^2_k, \quad \forall k \in [K] \quad (A.47)
\]

where \(a, c \geq 0\). If we set \(\{b_k\}\) as

\[
b_k = \begin{cases} b & \text{if } k \leq \frac{K}{2} \\ \frac{2b}{\frac{2ab}{2 + (k - \frac{K}{2})ab}} & \text{if } k > \frac{K}{2} \end{cases} \quad (A.48)
\]

then we have

\[
M_K \leq (1 - ab)\frac{K}{2} M_0 + \frac{10c}{a^2 K}. \quad (A.49)
\]

**Proof of Proposition 1.** Telescoping (A.47) for the first part \(0 \leq k \leq K/2\), we have

\[
M_K \leq (1 - ab)\frac{K}{2} M_0 + cb^2 \sum_{k=0}^{K/2-1} (1 - ab)^k
\]
\[
\leq (1 - ab)\frac{K}{2} M_0 + \frac{cb}{a}. \quad (A.50)
\]

Now we consider the second part \(\frac{K}{2} < k < K\), we have

\[
M_k \leq (1 - ab_k)M_{k-1} + cb^2_k
\]
\[
\overset{(A.48)}{=} (1 - \frac{2ab}{2 + (k - \frac{K}{2})ab})M_{k-1} + \frac{4cb^2}{(2 + (k - \frac{K}{2})ab)^2}
\]
\[
\left(2 + (k - \frac{K}{2})ab\right)^2 M_k \leq \left(2 + (k - \frac{K}{2})ab\right) \left(2 + (k - \frac{K}{2})ab - 2ab\right) M_{k-1} + 4cb^2
\]
\[
\leq \left(2 + (k - 1 - \frac{K}{2})ab\right)^2 M_{k-1} + 4cb^2. \quad (A.51)
\]
Telescoping (A.51) for the second part $\frac{K}{2} < k < K$, we have

$$
\left(2 + \left(K - \frac{K}{2}\right)ab\right)^2 M_K \leq 4M\frac{ab}{2} + 2cb^2K
$$

\[\leq 4(1 - ab)\frac{ab}{2} M_0 + \frac{4cb}{a} + 2cb^2K \tag{A.52}\]

$$
M_K \leq (1 - ab)\frac{ab}{2} M_0 + \frac{2c}{a^2K} + \frac{8c}{a^2K}
$$

\[= (1 - ab)\frac{ab}{2} M_0 + \frac{10c}{a^2K}.\]

Now, we apply Lemma 1 to equation (A.46) and set the stepsize $\eta_k$ as

$$
\eta_k = \begin{cases} 
\frac{\eta}{2} & \text{if } k \leq \frac{K}{2} \\
\frac{2\eta}{2 + (k - \frac{K}{2})\mu \eta} & \text{if } k > \frac{K}{2},
\end{cases} \tag{A.53}
$$

then we obtain

$$
\mathbb{E}[\Delta^K] \leq (1 - \mu \eta)\frac{\Delta^0}{2} + \frac{10C}{\mu^2 K}
$$

\[\leq \frac{\epsilon}{2} + \frac{\epsilon}{2} = \epsilon. \tag{A.54}\]

Thus, we find an $\epsilon$-solution, i.e. a point $x^K$ such that

$$
\mathbb{E}[f(x^K) - f^\ast] \leq \mathbb{E}[\Delta^K] \leq \epsilon.
$$

Note that (A.54) holds by choosing

$$
K = \max \left\{ \frac{2}{\mu \eta} \log \frac{2\Delta^0}{\epsilon}, \frac{20C}{\mu^2 \epsilon} \right\}.
$$

\[\text{(A.44)} \max \left\{ \frac{2L(B_1 + 2D_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1})}{\mu} \log \frac{2\Delta^0}{\epsilon}, \frac{10L(C_1 + 2D_1C_2\rho^{-1})}{\mu^2 \epsilon} \right\}. \tag{A.55}\]

Note that according to (A.44) and (A.53), we know that the step size $\eta$ needs to satisfy

$$
\eta_k = \begin{cases} 
\frac{\eta}{2} & \text{if } k \leq \frac{K}{2} \\
\frac{2\eta}{2 + (k - \frac{K}{2})\mu \eta} & \text{if } k > \frac{K}{2},
\end{cases}
$$

where

$$
\eta \leq \frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}}.
$$

Also, $\Delta^0 \overset{(A.25)}{=} f(x^0) - f^\ast + \alpha \sigma_0^2 \overset{(A.30)}{=} f(x^0) - f^\ast + L\eta^2 D_1\rho^{-1} \sigma_0^2 \overset{\text{def}}{=} \Delta_0$. \hfill \square
B Convergence Results and Proofs for Nonconvex Optimization (m = 1)

In this section, we provide the detailed convergence rates and proofs for some specific methods (see Section 3.2) in the single machine case (i.e., m = 1) of nonconvex federated problem (1.1) which reduces to the standard nonconvex problem (1.4) with online form 1.5 or finite-sum form (1.6), i.e.,

$$\min_{x \in \mathbb{R}^d} f(x), \text{ where } f(x) := \mathbb{E}_{\zeta \sim D}[f(x, \zeta)], \text{ or } f(x) := \frac{1}{n} \sum_{i=1}^{n} f_i(x).$$

In the following, we prove that some specific methods, i.e., GD, SGD, L-SVRG and SAGA satisfy our unified Assumption 1 and thus can be captured by our unified analysis. Then, we plug their corresponding parameters (i.e., specific values for $A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho$) into our unified Theorem 1 to obtain the detailed convergence rates for these methods.

B.1 GD method

We first restate our Lemma 1 for GD method (Algorithm 2) and provide its proof. Then we plug its corresponding parameters (i.e., specific values for $A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho$) into our unified Theorem 1 to obtain the detailed convergence rate.

**Lemma 1 (GD)** Let the gradient estimator $g^k = \nabla f(x^k)$ (see Line 1 of Algorithm 2), then $g^k$ satisfies the unified Assumption 1 with

$$A_1 = C_1 = D_1 = 0, B_1 = 1, \sigma_k^2 \equiv 0, \rho = 1, A_2 = B_2 = C_2 = 0.$$

**Proof of Lemma 1.** If gradient estimator $g^k = \nabla f(x^k)$, it is easy to see that

$$\mathbb{E}_k[g^k] = \nabla f(x^k)$$

and

$$\mathbb{E}_k[\|g^k\|^2] \leq \|\nabla f(x^k)\|^2$$

since there is no randomness in the algorithm. Thus, $g^k$ satisfies the unified Assumption 1 with

$$A_1 = C_1 = D_1 = 0, B_1 = 1, \sigma_k^2 \equiv 0, \rho = 1, A_2 = B_2 = C_2 = 0.$$  \[\square\]

**Corollary 1 (GD)** Suppose that Assumption 2 holds. Let stepsize $\eta \leq \frac{1}{L}$, then the number of iterations performed by GD (Algorithm 2) to find an $\epsilon$-solution of nonconvex problem (1.4), i.e. a point $\hat{x}$ such that

$$\mathbb{E}[\|\nabla f(\hat{x})\|] \leq \epsilon,$$

can be bounded by

$$K = \frac{8\Delta_0 L}{\epsilon^2}.$$  \[\square\]

**Proof of Corollary 1.** According to our unified Theorem 1, if the stepsize is chosen as

$$\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}, \frac{2L(C_1 + D_1 C_2 \rho^{-1})}{2\epsilon^2} \right\} = \frac{1}{L},$$

since $B_1 = 1, A_1 = C_1 = D_1 = 0$ according to Lemma 1, then the number of iterations performed by GD (Algorithm 2) to find an $\epsilon$-solution of problem (1.4) can be bounded by

$$K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ B_1 + D_1 B_2 \rho^{-1}, \frac{12\Delta_0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\} = \frac{8\Delta_0 L}{\epsilon^2}$$

since $B_1 = 1, A_1 = C_1 = D_1 = 0, \sigma_0^2 = 0$, and

$$\Delta_0' := f(x^0) - f^* + 2^{-1} \ln^2 D_1 \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0.$$  \[\square\]
B.2 SGD method

We first restate our Lemma 2 for SGD method (Algorithm 3) and provide its proof. Then we plug its corresponding parameters (i.e., specific values for $A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho$) into our unified Theorem 1 to obtain the detailed convergence rate.

**Lemma 2 (SGD)** Let the gradient estimator $g^k$ (see Line 2 of Algorithm 3) satisfy Assumption 9, i.e., $\mathbb{E}_k[\|g^k\|^2] \leq 2A(f(x^k) - f^*) + B\|\nabla f(x^k)\|^2 + C$, then $g^k$ satisfies the unified Assumption 1 with

$$A_1 = A, \ B_1 = B, \ C_1 = C, \ D_1 = 0, \ \sigma_k^2 \equiv 0, \ \rho = 1, \ A_2 = B_2 = C_2 = 0.$$ 

**Proof of Lemma 2.** Suppose that the gradient estimator $g^k$ satisfies Assumption 9, i.e.,

$$\mathbb{E}_k[g^k] = \nabla f(x^k)$$

and

$$\mathbb{E}_k[\|g^k\|^2] \leq 2A(f(x^k) - f^*) + B\|\nabla f(x^k)\|^2 + C,$$

Then it is easy to see that $g^k$ satisfies Assumption 1 with

$$A_1 = A, \ B_1 = B, \ C_1 = C, \ D_1 = 0, \ \sigma_k^2 \equiv 0, \ \rho = 1, \ A_2 = B_2 = C_2 = 0.$$ 

\(\square\)

**Corollary 2 (SGD)** Suppose that Assumption 2 holds and the gradient estimator $g^k$ in Algorithm 3 satisfies Assumption 9. Let stepsize $\eta \leq \min\left\{ \frac{1}{LB}, \sqrt{\frac{\ln 2 + \epsilon^2}{\epsilon^2}} \right\}$, then the number of iterations performed by SGD (Algorithm 3) for finding an $\epsilon$-solution of nonconvex problem (1.4) with (1.5) or (1.6), i.e., a point $\hat{x}$ such that $\mathbb{E}[\|\nabla f(\hat{x})\|] \leq \epsilon$, can be bounded by

$$K = \frac{8\Delta_0 L}{\epsilon^2} \max\left\{ B, \frac{12\Delta_0 A}{\epsilon^2}, \frac{2C}{\epsilon^2} \right\}. $$

Note that it recovers the recent result for SGD given by [23].

**Proof of Corollary 2.** According to our unified Theorem 1, if the stepsize is chosen as

$$\eta \leq \min\left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}, \sqrt{\frac{\epsilon^2}{2L(C_1 + D_1 C_2 \rho^{-1})}} \right\}$$

$$= \min\left\{ \frac{1}{LB}, \sqrt{\frac{\ln 2}{LAK}}, \frac{\epsilon^2}{2LC} \right\}$$

since $A_1 = A, B_1 = B, C_1 = C, D_1 = 0$ according to Lemma 2, then the number of iterations performed by SGD (Algorithm 3) to find an $\epsilon$-solution of problem (1.4) with (1.5) or (1.6) can be bounded by

$$K = \frac{8\Delta'_0 L}{\epsilon^2} \max\left\{ B_1 + D_1 B_2 \rho^{-1}, \frac{12\Delta'_0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\}$$

$$= \frac{8\Delta'_0 L}{\epsilon^2} \max\left\{ B_1 + D_1 B_2 \rho^{-1}, \frac{12\Delta'_0 A_1}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\}$$

since $A_1 = A, B_1 = B, C_1 = C, D_1 = 0, \sigma_0^2 = 0,$ and

$$\Delta'_0 := f(x^0) - f^* + 2^{-1} L\eta^2 D_1 \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0.$$ 

\(\square\)
B.3 L-SVRG method

We first restate our Lemma 3 for L-SVRG method (Algorithm 4) and provide its proof. Then we plug its corresponding parameters (i.e., specific values for \(A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho\)) into our unified Theorem 1 to obtain the detailed convergence rate.

**Lemma 3 (L-SVRG)** Suppose that Assumption 3 holds. The gradient estimator \(g^k = \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \nabla f(w^k)\) (see Line 2 in Algorithm 4) satisfies the unified Assumption 1 with

\[
A_1 = A_2 = C_1 = C_2 = 0,
B_1 = 1, \quad D_1 = \frac{L^2}{b}, \quad \sigma_k^2 = \|x^k - w^k\|^2, \quad \rho = \frac{p}{2} + \frac{\rho^2}{2} - \frac{\eta^2 L^2}{b}, \quad B_2 = \frac{2\eta^2}{p} - \eta^2.
\]

**Proof of Lemma 3.** If gradient estimator \(g^k = \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \nabla f(w^k)\) (see Line 2 in Algorithm 4), we show the following equations:

\[
E_k[g^k] = E_k \left[ \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \nabla f(w^k) \right]
= \nabla f(x^k) - \nabla f(w^k) + \nabla f(w^k) = \nabla f(x^k)
\]  

(B.3)

and

\[
E_k[\|g^k\|^2] = E_k \left[ \|g^k - \nabla f(x^k)\|^2 + \|\nabla f(x^k)\|^2 \right]
= E_k \left[ \left\| \frac{1}{b} \sum_{i \in I_b} (\nabla f_i(x^k) - \nabla f_i(w^k)) + \nabla f(w^k) - \nabla f(x^k) \right\|^2 \right] + \|\nabla f(x^k)\|^2
= \frac{1}{b^2} E_k \left[ \left\| \sum_{i \in I_b} \left( (\nabla f_i(x^k) - \nabla f_i(w^k)) - (\nabla f(x^k) - \nabla f(w^k)) \right) \right\|^2 \right] + \|\nabla f(x^k)\|^2
\leq \frac{1}{b} E_k \left[ \|\nabla f_i(x^k) - \nabla f_i(w^k)\|^2 \right] + \|\nabla f(x^k)\|^2
\leq \frac{L^2}{b} \|x^k - w^k\|^2 + \|\nabla f(x^k)\|^2,
\]  

(B.4)

where (B.4) uses the fact \(E[\|x - E[x]\|^2] \leq E[\|x\|^2]\), and the last inequality uses Assumption 3 (i.e., (2.2)).

Now, we define \(\sigma_k^2 := \|x^k - w^k\|^2\) and obtain

\[
E_k[\sigma_{k+1}^2]
:= E_k[\|x^{k+1} - w^{k+1}\|^2]
= pE_k[\|x^{k+1} - x^k\|^2] + (1 - p)E_k[\|x^{k+1} - w^k\|^2]
= \rho \eta^2 E_k[\|g^k\|^2] + (1 - p)E_k[\|x^k - \eta g^k - w^k\|^2]
= \rho \eta^2 E_k[\|g^k\|^2] + (1 - p)E_k[\|x^k - w^k\|^2 + \|\eta g^k\|^2 - 2\langle x^k - w^k, \eta g^k \rangle]
= \rho \eta^2 E_k[\|g^k\|^2] + (1 - p)\|x^k - w^k\|^2 + (1 - p)\eta^2 E_k[\|g^k\|^2] - 2(1 - p)\langle x^k - w^k, \eta \nabla f(x^k) \rangle
\leq \eta^2 E_k[\|g^k\|^2] + (1 - p)\|x^k - w^k\|^2 + (1 - p)\beta \|x^k - w^k\|^2 + \frac{1 - p}{\beta} \|\eta \nabla f(x^k)\|^2
\]  

(B.8)

\[
= \eta^2 E_k[\|g^k\|^2] + (1 - p)(1 + \beta)\|x^k - w^k\|^2 + \frac{(1 - p)\eta^2}{\beta} \|\nabla f(x^k)\|^2
\]  

(B.9)
\[ \begin{align*} 
& \leq \eta^2 \left( \frac{L^2}{b} \| x^k - w^k \|^2 + \| \nabla f(x^k) \|^2 \right) + (1 - p)(1 + \beta) \| x^k - w^k \|^2 + \frac{(1 - p)\eta^2}{\beta} \| \nabla f(x^k) \|^2 \\
& = \left( 1 - p \right)(1 + \beta + \frac{\eta^2 L^2}{b}) \| x^k - w^k \|^2 + \left( \frac{(1 - p)\eta^2}{\beta} + \eta^2 \right) \| \nabla f(x^k) \|^2 \\
& = \left( 1 - \frac{p}{2} - \frac{p^2}{2} + \eta^2 \frac{L^2}{b} \right) \| x^k - w^k \|^2 + \left( \frac{2\eta^2}{p} - \eta^2 \right) \| \nabla f(x^k) \|^2, 
\end{align*} \]

where (B.6) uses Line 4 of Algorithm 4, (B.7) uses Line 3 of Algorithm 4, (B.8) uses Young’s inequality for \( \forall \beta > 0 \), (B.9) uses (B.5), and (B.10) holds by setting \( \beta = p/2 \).

Now, according to (B.3), (B.5) and (B.10), we know \( g^k \) satisfies the unified Assumption 1 with

\[ A_1 = A_2 = C_1 = C_2 = 0, \]

\[ B_1 = 1, \quad D_1 = \frac{L^2}{b}, \quad \sigma_k^2 = \| x^k - w^k \|^2, \quad \rho = \frac{p}{2} - \frac{p^2}{2} - \frac{\eta^2 L^2}{b}, \quad B_2 = \frac{2\eta^2}{p} - \eta^2. \]

\[ \square \]

**Corollary 3 (L-SVRG)** Suppose that Assumption 3 holds. Let stepsize \( \eta \leq \frac{1}{L(1 + 2b^{-1/3}p^{-2/3})} \), then the number of iterations performed by L-SVRG (Algorithm 4) for finding an \( \epsilon \)-solution of nonconvex problem (1.4) with (1.6), i.e. a point \( \hat{x} \) such that \( \mathbb{E}[\| \nabla f(\hat{x}) \|] \leq \epsilon \), can be bounded by

\[ K = \frac{8\Delta_0 L}{\epsilon^2} \left( 1 + \frac{2}{b^{1/3}p^{2/3}} \right). \]

In particular, we have

1. let minibatch size \( b = 1 \) and probability \( p = \frac{1}{n} \), then the number of iterations \( K = \frac{24\Delta_0 L n^{2/3}}{\epsilon^2} \).

2. let minibatch size \( b = n^{2/3} \) and probability \( p = \frac{1}{n^{1/3}} \), then the number of iterations \( K = \frac{24\Delta_0 L}{\epsilon^2} \), but each iteration costs \( n^{2/3} \) due to minibatch size \( b = n^{2/3} \).

**Remark:** i) The analysis and results for L-SVRG in this nonconvex case are new. Previous work studied the standard SVRG form [19] not this simpler loopless version. ii) L-SVRG enjoys a linear speedup for parallel computation, i.e., if one can parallel compute \( b \) minibatch stochastic gradients, then one can finding an \( \epsilon \)-solution within \( O\left( \frac{n^{2/3}}{\epsilon^2} \right) \) steps by letting \( p = \frac{b}{n} \) while a single node (minibatch \( b = 1 \)) needs \( O\left( \frac{n^{2/3}}{\epsilon^2} \right) \) steps. In the best case, one can achieve \( b = n^{2/3} \) times acceleration via parallel computation.

**Proof of Corollary 3.** According to our unified Theorem 1, the stepsize should be chosen as

\[ \eta \leq \min \left\{ \frac{1}{LB_1 + LD_1B_2\rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1A_2\rho^{-1})K}}, \frac{\epsilon^2}{2LC_1 + D_1C_2\rho^{-1}} \right\} \]

\[ = \frac{1}{LB_1 + LD_1B_2\rho^{-1}} \]

since \( A_1 = A_2 = C_1 = C_2 = 0 \) according to Lemma 3. Then the number of iterations performed by L-SVRG (Algorithm 4) to find an \( \epsilon \)-solution of problem (1.4) with (1.6) can be bounded by

\[ K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ B_1 + D_1B_2\rho^{-1}, \frac{12\Delta_0 (A_1 + D_1A_2\rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1C_2\rho^{-1})}{\epsilon^2} \right\} \]

\[ = \frac{8\Delta_0 L}{\epsilon^2} (B_1 + D_1B_2\rho^{-1}) \]
since $A_1 = A_2 = C_1 = C_2 = 0$, $\sigma_0^2 = \|x^0 - w^0\|^2 = 0$, and $\Delta_0^* := f(x^0) - f^* + 2^{-1}L\eta_2^2D_1\rho^{-1}\sigma_0^2 = f(x^0) - f^* = \Delta_0$.

Now, the remaining thing is to upper bound the term $B_1 + D_1B_2\rho^{-1}$,

$$B_1 + D_1B_2\rho^{-1} = 1 + \frac{L^2}{b} \left( \frac{2\eta^2}{p} - \eta^2 \right) \left( \frac{p}{2} + \frac{\eta^2}{2} - \frac{\eta^2 L^2}{b} \right)^{-1}$$

(B.13)

$$\leq 1 + \frac{L^2}{b} \left( \frac{2\eta^2}{p} \right) \left( \frac{p}{4} \right)^{-1}$$

(B.14)

$$= 1 + \frac{8L^2\eta^2}{bp^2}$$

(B.15)

where (B.13) follows from $B_1 = 1, D_1 = \frac{L^2}{b}$, $B_2 = \frac{2\eta^2}{p} - \eta^2, \rho = \frac{p}{2} + \frac{\eta^2}{2} - \frac{\eta^2 L^2}{b}$ in Lemma 3, the last inequality (B.15) holds by setting $\eta \leq \frac{1}{L(1 + \frac{\eta^2}{b^3/p^2})} \leq \frac{1}{Lb_1 + Lb_2B_2\rho^{-1}}$, and (B.14) is due to the fact $\frac{\eta^2 L^2}{b} \leq \frac{p}{4}$.

In sum, let stepsize

$$\eta \leq \frac{1}{L(1 + \frac{\eta^2}{b^3/p^2})},$$

then the number of iterations performed by L-SVRG (Algorithm 4) to find an $\epsilon$-solution of problem (1.4) with (1.6) can be bounded by

$$K = \frac{8\Delta_0 L}{\epsilon^2} \left( 1 + \frac{2}{b^{1/3}p^{2/3}} \right).$$

(B.16)

In particular, we have

1. let minibatch size $b = 1$ and probability $p = \frac{1}{n}$, then the number of iterations $K = \frac{24\Delta_0 L n^{2/3}}{\epsilon^2}$.

2. let minibatch size $b = n^{2/3}$ and probability $p = \frac{1}{n^{2/3}}$, then the number of iterations $K = \frac{24\Delta_0 L}{\epsilon^2}$, but each iteration costs $n^{2/3}$ due to minibatch size $b = n^{2/3}$.

\[\Box\]

### B.4 SAGA method

We first restate our Lemma 4 for SAGA method (Algorithm 5) and provide its proof. Then we plug its corresponding parameters (i.e., specific values for $A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho$) into our unified Theorem 1 to obtain the detailed convergence rate.

**Lemma 4 (SAGA)** Suppose that Assumption 4 holds. The gradient estimator $g_k = \frac{1}{b} \sum_{i \in t_b} (\nabla f_i(x^k) - \nabla f_i(w^k_i)) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_j(w^k_j)$ (see Line 2 in Algorithm 5) satisfies the unified Assumption 1 with

$$A_1 = A_2 = C_1 = C_2 = 0,$$

$$B_1 = 1, \ D_1 = \frac{L^2}{b}, \ \sigma_k^2 = \frac{1}{n} \sum_{i=1}^{n} \|x^k - w^k_i\|^2, \ \rho = \frac{b}{2n} + \frac{b^2}{2n^2} - \frac{\eta^2 L^2}{b}, \ B_2 = \frac{2\eta^2 n}{b} - \eta^2.$$
Proof of Lemma 4. If gradient estimator $g^k = \frac{1}{b} \sum_{i \in I_k} (\nabla f_i(x^k) - \nabla f_i(w^k_i)) + \frac{1}{n} \sum_{j=1}^n \nabla f_j(w^k_j)$ (see Line 2 in Algorithm 5), we show the following equations:

$$
\mathbb{E}_k[g^k] = \mathbb{E}_k \left[ \frac{1}{b} \sum_{i \in I_k} (\nabla f_i(x^k) - \nabla f_i(w^k_i)) + \frac{1}{n} \sum_{j=1}^n \nabla f_j(w^k_j) \right] 
= \nabla f(x^k) - \frac{1}{n} \sum_{i=1}^n \nabla f_i(x^k) + \frac{1}{n} \sum_{j=1}^n \nabla f_j(w^k_j)
= \nabla f(x^k)
$$

(B.17)

and

$$
\mathbb{E}_k[\|g^k\|^2] 
= \mathbb{E}_k \left[ \|g^k - \nabla f(x^k)\|^2 + \|\nabla f(x^k)\|^2 \right]
= \mathbb{E}_k \left[ \left\| \frac{1}{b} \sum_{i \in I_k} (\nabla f_i(x^k) - \nabla f_i(w^k_i)) + \frac{1}{n} \sum_{j=1}^n \nabla f_j(w^k_j) - \nabla f(x^k) \right\|^2 + \|\nabla f(x^k)\|^2 \right]
= \frac{1}{b^2} \mathbb{E}_k \left[ \left\| \sum_{i \in I_k} \left( (\nabla f_i(x^k) - \nabla f_i(w^k_i)) - \left( \frac{1}{n} \sum_{j=1}^n \nabla f_j(x^k) - \frac{1}{n} \sum_{j=1}^n \nabla f_j(w^k_j) \right) \right) \right\|^2 \right]
+ \|\nabla f(x^k)\|^2
= \frac{1}{b^2} \mathbb{E}_k \left[ \left\| \sum_{i \in I_k} (\nabla f_i(x^k) - \nabla f_i(w^k_i)) - \left( \frac{1}{n} \sum_{j=1}^n \nabla f_j(x^k) - \frac{1}{n} \sum_{j=1}^n \nabla f_j(w^k_j) \right) \right\|^2 \right]
+ \|\nabla f(x^k)\|^2
\leq \frac{1}{b^2} \mathbb{E}_k \left[ \|\nabla f_i(x^k) - \nabla f_i(w^k_i)\|^2 \right] + \|\nabla f(x^k)\|^2
\leq \frac{1}{b} \frac{1}{n} \sum_{i=1}^n \|x^k - w^k_i\|^2 + \|\nabla f(x^k)\|^2
$$

(B.18)

(B.19)

where (B.18) uses the fact $\mathbb{E}[\|x - \mathbb{E}[x]\|^2] \leq \mathbb{E}[\|x\|^2]$, and the last inequality uses Assumption 4 (i.e., (2.3)).

Now, we denote $\sigma^2_k := \frac{1}{n} \sum_{i=1}^n \|x^k - w^k_i\|^2$ and obtain

$$
\mathbb{E}_k[\sigma^2_{k+1}] := \mathbb{E}_k \left[ \frac{1}{n} \sum_{i=1}^n \|x^{k+1} - w^{k+1}_i\|^2 \right]
= \mathbb{E}_k \left[ \frac{1}{n} \sum_{i=1}^n \frac{b}{n} \|x^{k+1} - x^k\|^2 + \frac{1}{n} \sum_{i=1}^n \left( 1 - \frac{b}{n} \right) \|x^{k+1} - w^k_i\|^2 \right]
= \frac{b}{n} \mathbb{E}_k \|g^k\|^2 + \left( 1 - \frac{b}{n} \right) \mathbb{E}_k \left[ \frac{1}{n} \sum_{i=1}^n \|x^k - \eta g^k - w^k_i\|^2 \right]
= \frac{bn^2}{n} \mathbb{E}_k \|g^k\|^2 + \left( 1 - \frac{b}{n} \right) \mathbb{E}_k \left[ \frac{1}{n} \sum_{i=1}^n ((|x^k - w^k_i|^2 + \|\eta g^k\|^2 - 2 \langle x^k - w^k_i, \eta g^k \rangle)) \right]
$$

(B.20)

(B.21)

32
\[ = \eta^2 \mathbb{E}_k \|g^k\|^2 + \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{i=1}^{n} \|x^k - w^k_i\|^2 + 2 \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{i=1}^{n} (x^k - w^k_i, \eta \nabla f(x^k)) \]

\[ \leq \eta^2 \mathbb{E}_k \|g^k\|^2 + \left( 1 - \frac{b}{n} \right) \eta \sum_{i=1}^{n} (\|\nabla x^k - \nabla w^k_i\|^2 + \frac{n^2}{\beta} \|\nabla f(x^k)\|^2) \]

\[ + \left( 1 - \frac{b}{n} \right) \eta \beta \sum_{i=1}^{n} \|x^k - w^k_i\|^2 + \left( 1 - \frac{b}{n} \right) \frac{\eta^2}{\beta} \|\nabla f(x^k)\|^2 \]

\[ = \eta^2 \left( \frac{L^2}{b} \frac{1}{n} \sum_{i=1}^{n} \|x^k - w^k_i\|^2 + \|\nabla f(x^k)\|^2 \right) \]

\[ + \left( 1 - \frac{b}{n} \right) (1 + \beta) \frac{\eta^2 L^2}{b} \sum_{i=1}^{n} \|x^k - w^k_i\|^2 + \left( 1 - \frac{b}{n} \right) \frac{\eta^2}{\beta} \|\nabla f(x^k)\|^2 \]

\[ = \left( 1 - \frac{b}{2n} - \frac{b^2}{2n^2} + \frac{\eta^2 L^2}{2n^2 b} \right) \sum_{i=1}^{n} \|x^k - w^k_i\|^2 + \left( 2 \frac{\eta^2 n}{b} - \eta^2 \right) \|\nabla f(x^k)\|^2, \]

where (B.20) uses Line 4 of Algorithm 5, (B.21) uses Line 3 of Algorithm 5, (B.22) uses Young’s inequality for \( \forall \beta > 0 \), (B.23) uses (B.19), and (B.24) holds by setting \( \beta = b/2n \).

Now, according to (B.17), (B.19) and (B.24), we know \( g^k \) satisfies the unified Assumption 1 with

\[ A_1 = A_2 = C_1 = C_2 = 0, \]

\[ B_1 = 1, \quad D_1 = \frac{L^2}{b}, \quad \sigma^2_1 = \frac{1}{n} \sum_{i=1}^{n} \|x^k - w^k_i\|^2, \quad \rho = \frac{b}{2n} + \frac{b^2}{2n^2} - \frac{\eta^2 L^2}{b}, \quad B_2 = \frac{2\eta^2 n}{b} - \eta^2. \]

\[ \square \]

**Corollary 4 (SAGA)** Suppose that Assumption 4 holds. Let stepsize \( \eta \leq \frac{1}{L(1 + 2n^2 \rho - \eta^2)} \), then the number of iterations performed by SAGA (Algorithm 5) for finding an \( \epsilon \)-solution of nonconvex problem (1.4) with (1.6), i.e. a point \( \hat{x} \) such that \( \mathbb{E}[\|\nabla f(\hat{x})\|] \leq \epsilon \), can be bounded by

\[ K = \frac{8 \Delta_0 L}{\epsilon^2} \left( 1 + \frac{2n^{2/3}}{b} \right). \]

In particular, we have

1. let minibatch size \( b = 1 \), then the number of iterations \( K = \frac{24 \Delta_0 L n^{2/3}}{\epsilon^2} \).

2. let minibatch size \( b = n^{2/3} \), then the number of iterations \( K = \frac{24 \Delta_0 L}{\epsilon^2} \), but each iteration costs \( n^{2/3} \) due to minibatch size \( b = n^{2/3} \).

**Remark:** Similar to L-SVRG, SAGA also enjoys a linear speedup for parallel computation, i.e., if one can parallel compute \( b \) minibatch stochastic gradients, then one can finding an \( \epsilon \)-solution within \( O\left(\frac{n^{2/3}}{\epsilon^2 b} \right) \) steps while a single node (minibatch \( b = 1 \)) needs \( O\left(\frac{n^{2/3}}{\epsilon^2} \right) \) steps. In the best case, one can achieve \( b = n^{2/3} \) times acceleration via parallel computation.
**Proof of Corollary 4.** According to our unified Theorem 1, the stepsize should be chosen as

\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1}) K}}, \frac{\epsilon^2}{2L(C_1 + D_1 C_2 \rho^{-1})} \right\}
\]

\[
= \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}
\]

(B.25)
since \( A_1 = A_2 = C_1 = C_2 = 0 \) according to Lemma 4. Then the number of iterations performed by SAGA (Algorithm 5) to find an \( \epsilon \)-solution of problem (1.4) with (1.6) can be bounded by

\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ B_1 + D_1 B_2 \rho^{-1}, \frac{12\Delta_0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\}
\]

\[
= \frac{8\Delta_0 L}{\epsilon^2} (B_1 + D_1 B_2 \rho^{-1})
\]

(B.26)
since \( A_1 = A_2 = C_1 = C_2 = 0, \sigma_0^2 = \|x^0 - w^0\|^2 = 0 \), and \( \Delta_0 := f(x^0) - f^* + 2^{-1} L \eta^2 D_1 \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0 \).

Now, the remaining thing is to upper bound the term \( B_1 + D_1 B_2 \rho^{-1} \),

\[
B_1 + D_1 B_2 \rho^{-1} = 1 + \frac{L^2}{b} \left( \frac{2\eta^2 n}{b} - \frac{\eta^2}{b^2} \right) \left( \frac{b}{2n} + \frac{b^2}{2n^2} - \frac{\eta^2 L^2}{b} \right)^{-1}
\]

(B.27)

\[
\leq 1 + \frac{L^2}{b} \left( \frac{2\eta^2 n}{b} - \frac{\eta^2}{b^2} \right) \left( \frac{b}{4n} \right)^{-1}
\]

(B.28)

\[
= 1 + \frac{8n^2 L^2 \eta^2}{b^3}
\]

\[
\leq 1 + \frac{2n^{2/3}}{b},
\]

(B.29)

where (B.27) follows from \( B_1 = 1, D_1 = \frac{L^2}{b}, B_2 = \frac{2\eta^2 n}{b} - \frac{\eta^2}{b^2}, \rho = \frac{b}{2n} + \frac{b^2}{2n^2} - \frac{\eta^2 L^2}{b} \) in Lemma 4, the last inequality (B.29) holds by setting \( \eta \leq \frac{1}{L(1 + \frac{2n^{2/3}}{b})} \leq \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}} \), and (B.28) is due to the fact

\[
\frac{\eta^2 L^2}{b} \leq \frac{b}{4n^2}.
\]

In sum, let stepsize

\[
\eta \leq \frac{1}{L(1 + \frac{2n^{2/3}}{b})},
\]

then the number of iterations performed by SAGA (Algorithm 5) to find an \( \epsilon \)-solution of problem (1.4) with (1.6) can be bounded by

\[
K = \frac{8\Delta_0 L}{\epsilon^2} \left(1 + \frac{2n^{2/3}}{b}\right).
\]

(B.30)

In particular, we have

1. let minibatch size \( b = 1 \), then the number of iterations \( K = \frac{24\Delta_0 L n^{2/3}}{\epsilon^2} \).
2. let minibatch size \( b = n^{2/3} \), then the number of iterations \( K = \frac{24\Delta_0 L}{\epsilon^2} \), but each iteration costs \( \eta^{2/3} \)
due to minibatch size \( b = n^{2/3} \).
C Convergence Results and Proofs for Nonconvex Federated Optimization

In this section, we provide the detailed convergence rates and proofs for the more general nonconvex distributed/federated problem (1.1) with online form (1.2) or finite-sum form (1.3), i.e.,

$$\min_{x \in \mathbb{R}^d} \left\{ f(x) := \frac{1}{m} \sum_{i=1}^{m} f_i(x) \right\}, \quad \text{where} \ f_i(x) := \mathbb{E}_{\zeta \sim \mathcal{D}_i}[f_i(x, \zeta)], \ \text{or} \ f_i(x) := \frac{1}{n} \sum_{j=1}^n f_{i,j}(x).$$

Here we allow that different machine/worker $i \in [m]$ can have different data distribution $\mathcal{D}_i$, i.e., non-IID data (heterogeneous data) setting.

Note that in this general distributed/federated problem, the bottleneck usually is the communication cost among all workers. Thus we focus on the compressed gradient methods. Here we recall the definition of compression operator.

**Definition 1 (Compression operator)** A randomized map $\mathcal{C} : \mathbb{R}^d \mapsto \mathbb{R}^d$ is an $\omega$-compression operator if

$$\mathbb{E}[\mathcal{C}(x)] = x, \quad \mathbb{E}[\|\mathcal{C}(x) - x\|^2] \leq \omega \|x\|^2, \quad \forall x \in \mathbb{R}^d. \quad (C.1)$$

In particular, no compression ($\mathcal{C}(x) \equiv x$) implies $\omega = 0$.

In the following, we prove that several (new) methods belonging to the proposed general DC framework (Algorithm 6) and DIANA framework (Algorithm 7) for solving this general distributed/federated problem also satisfy the unified Assumption 1 and thus can also be captured by our unified analysis. Then, we plug their corresponding parameters into our unified Theorem 1 to obtain the detailed convergence rates for these methods.

### C.1 DC framework for nonconvex federated optimization

We first prove a general Theorem for DC framework (Algorithm 6) which shows that several (new) methods belonging to the general DC framework satisfy Assumption 1 and thus can be captured by our unified analysis. Then, we plug their corresponding parameters into our unified Theorem 1 to obtain the detailed convergence rates for these methods.

Before proving the Theorem 3, we first provide a simple version as in Theorem 6 where all workers share the same variance term $\sigma_k^2$ (see (C.2)). If the parallel workers use GD, SGD or L-SVRG for computing their local stochastic gradient $\tilde{g}_k^i$ (see Line 3 of Algorithm 6), then they indeed share the same variance term $\sigma_k^2$, i.e., Theorem 6 includes these settings. However, if the parallel workers use SAGA-type methods for computing their local stochastic gradient $\tilde{g}_k^i$, then the variance term $\sigma_{k,i}^2$ (see (C.6)) is different for different worker $i$, i.e., the more general Theorem 3 includes this SAGA setting while Theorem 6 does not.

**Theorem 6 (DC framework with same variance for all workers)** Suppose that the local stochastic gradient $\tilde{g}_k^i$ (see Line 3 of Algorithm 6) satisfies

$$\mathbb{E}_k[\|\tilde{g}_k^i\|^2] \leq 2A_{1,i}(f_i(x^k) - f^*) + B_{1,i}\|\nabla f_i(x^k)\|^2 + D_1^i\sigma_k^2 + C_{1,i}, \quad (C.2)$$

$$\mathbb{E}_k[\sigma_{k+1}^2] \leq (1 - \rho')\sigma_k^2 + 2A_2'(f(x^k) - f^*) + B_2'\|\nabla f(x^k)\|^2 + D_2'E_k[\|\tilde{g}_k\|^2] + C_2', \quad (C.3)$$

then $g^k$ (see Line 6 of Algorithm 6) satisfies the unified Assumption 1, i.e.,

$$\mathbb{E}_k[\|g_k\|^2] \leq 2A_1(f(x^k) - f^*) + B_1\|\nabla f(x^k)\|^2 + D_1\sigma_k^2 + C_1, \quad (C.4)$$

$$\mathbb{E}_k[\sigma_{k+1}^2] \leq (1 - \rho)\sigma_k^2 + 2A_2(f(x^k) - f^*) + B_2\|\nabla f(x^k)\|^2 + C_2, \quad (C.5)$$

35
with parameters
\[ A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \]
\[ D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = D_1^2 \tilde{\sigma}_k^2, \quad \rho = \rho' - \tau, \]
\[ A_2 = D_1' A_2' + \tau A, \quad B_2 = D_1' B_2' + D_1' D_2', \quad C_2 = D_1' C_2' + \tau C, \]

where \( A := \max_i (A_{1,i} + B_{1,i} L_i - L_i / (1 + \omega)), \)
\( C := \frac{1}{m} \sum_i^{m} C_{1,i} + 2 A \Delta f_i, \Delta f_i := f^* - \frac{1}{m} \sum_i^{m} f^*_i, \) and \( \tau := \frac{(1 + \omega) D_1' D_2'}{m} \).

Before providing the proof for Theorem 6, we recall the more general Theorem 3 here for better comparison. Then we provide the detailed proofs for Theorems 6 and 3.

**Theorem 3 (DC framework with different variance for different worker)** Suppose that the local stochastic gradient \( g_k \) (see Line 3 of Algorithm 6) satisfies
\[ \mathbb{E}_k[\|g_k\|^2] \leq 2 A_1 (f(x_k) - f^*) + B_1 \|\nabla f(x_k)\|^2 + D_1 \sigma_k^2 + C_1, \quad (C.6) \]
\[ \mathbb{E}_k[\sigma_k^2] \leq (1 - \rho) \sigma_k^2 + 2 A_2 (f(x_k) - f^*) + B_2 \|\nabla f(x_k)\|^2 + D_2 \|\nabla f(x_k)\|^2 + C_2, \quad (C.7) \]

then \( g_k \) (see Line 6 of Algorithm 6) satisfies the unified Assumption 1 i.e.,
\[ \mathbb{E}_k[\|g_k\|^2] \leq 2 A_1 (f(x_k) - f^*) + B_1 \|\nabla f(x_k)\|^2 + D_1 \sigma_k^2 + C_1, \quad (C.8) \]
\[ \mathbb{E}_k[\sigma_k^2] \leq (1 - \rho) \sigma_k^2 + 2 A_2 (f(x_k) - f^*) + B_2 \|\nabla f(x_k)\|^2 + C_2, \quad (C.9) \]

with parameters
\[ A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \]
\[ D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{1}{m} \sum_i^{m} D_1 \sigma_k^2, \quad \rho = \min_i \rho_i - \tau, \]
\[ A_2 = D_1 A + \tau A, \quad B_2 = D_1 B + D_2, \quad C_2 = D_1 C + \tau C, \]

where \( A := \max_i (A_{1,i} + B_{1,i} L_i - L_i / (1 + \omega)), \)
\( C := \frac{1}{m} \sum_i^{m} C_{1,i} + 2 A \Delta f_i, \Delta f_i := f^* - \frac{1}{m} \sum_i^{m} f^*_i, \) and \( \tau := \frac{(1 + \omega) D_1 D_2}{m} \).

**Proof of Theorem 6.** First, we show the that gradient estimator \( g_k \) (see Line 6 of Algorithm 6) is unbiased:
\[ \mathbb{E}_k[g_k] = \mathbb{E}_k \left[ \frac{1}{m} \sum_i^{m} C_i (\tilde{g}_i^k) \right] = \frac{1}{m} \sum_i^{m} \nabla f_i(x_k) = \nabla f(x_k). \quad (C.10) \]

Then, we prove the upper bound for the second moment of gradient estimator \( g_k \):
\[ \mathbb{E}_k[\|g_k\|^2] = \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_i^{m} C_i (\tilde{g}_i^k) - \frac{1}{m} \sum_i^{m} \tilde{g}_i^k + \frac{1}{m} \sum_i^{m} \tilde{g}_i^k \right\|^2 \right] \]
\[ \overset{(C.1)}{=} \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_i^{m} (C_i (\tilde{g}_i^k) - \tilde{g}_i^k) \right\|^2 \right] + \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_i^{m} \tilde{g}_i^k \right\|^2 \right] \]

36
Now we prove the second part, i.e., (C.5). According to (C.3), we have

\[
\begin{align*}
\mathbb{E}_k[\sigma_{k+1}^2] &\leq (1 - \rho')D'_1\hat{\sigma}_k^2 + 2D'_1A'_2(f(x^k) - f^*) + D'_1B'_2\|\nabla f(x^k)\|^2 + D'_1D'_2\mathbb{E}_k[\|g^k\|^2] + D'_1C'_2 \\
&\leq (1 - \rho')\sigma_k^2 + 2D'_1A'_2(f(x^k) - f^*) + D'_1B'_2\|\nabla f(x^k)\|^2 + D'_1C'_2 \\
&\quad + D'_1D'_2 \left( \frac{2(1 + \omega)A}{m}(f(x^k) - f^*) + \frac{1 + \omega}{m}D'_1\hat{\sigma}_k^2 + \frac{(1 + \omega)C}{m} + \|\nabla f(x^k)\|^2 \right) \\
&= (1 - \rho' + \tau)\sigma_k^2 + 2(D'_1A'_2 + \tau A)(f(x^k) - f^*) \\
&\quad + (D'_1B'_2 + D'_1D'_2)\|\nabla f(x^k)\|^2 + D'_1C'_2 + \tau C,
\end{align*}
\]

where (C.15) holds by defining \( \tau := \frac{(1 + \omega)D'_1D'_2}{m} \).

Now, we have proved the second part, i.e., (C.5) holds with

\[
\rho = \rho' - \tau, \quad A_2 = D'_1A'_2 + \tau A, \quad B_2 = D'_1B'_2 + D'_1D'_2, \quad C_2 = D'_1C'_2 + \tau C.
\]

37
Proof of Theorem 3. Similar to the proof of Theorem 6, we know that gradient estimator $g^k$ (see Line 6 of Algorithm 6) is unbiased, i.e.,

$$E_k[g^k] = E_k \left[ \frac{1}{m} \sum_{i=1}^{m} C_i^k(\tilde{g}_i^k) \right] = \frac{1}{m} \sum_{i=1}^{m} \nabla f_i(x^k) = \nabla f(x^k). \quad (C.16)$$

Then, we prove the upper bound for the second moment of gradient estimator $g^k$:

$$E_k[\|g^k\|^2] = E_k \left[ \left\| \frac{1}{m} \sum_{i=1}^{m} C_i^k(\tilde{g}_i^k) - \frac{1}{m} \sum_{i=1}^{m} \tilde{g}_i^k \right\|^2 \right]$$

$$\leq \frac{\omega}{m^2} E_k \left[ \left\| \frac{1}{m} \sum_{i=1}^{m} (C_i^k(\tilde{g}_i^k) - \tilde{g}_i^k) \right\|^2 \right] + E_k \left[ \left\| \frac{1}{m} \sum_{i=1}^{m} (\tilde{g}_i^k - \nabla f_i(x^k)) + \frac{1}{m} \sum_{i=1}^{m} \nabla f_i(x^k) \right\|^2 \right]$$

$$= \frac{\omega}{m^2} E_k \left[ \sum_{i=1}^{m} \|\tilde{g}_i^k\|^2 \right] + \frac{1}{m^2} E_k \left[ \sum_{i=1}^{m} \|\tilde{g}_i^k - \nabla f_i(x^k)\|^2 \right] + \|\nabla f(x^k)\|^2$$

$$\leq \frac{1}{m^2} \sum_{i=1}^{m} \left( (1 + \omega) E_k[\|\tilde{g}_i^k\|^2] - \|\nabla f_i(x^k)\|^2 \right) + \|\nabla f(x^k)\|^2$$

$$\leq \frac{1}{m^2} \sum_{i=1}^{m} \left( (1 + \omega)(2A_{1,i}(f_i(x^k) - f_i^*) + B_{1,i}\|\nabla f_i(x^k)\|^2 + D_{1,i}\sigma_{k,i}^2 + C_{1,i}) - \|\nabla f_i(x^k)\|^2 \right)$$

$$+ \|\nabla f(x^k)\|^2$$

$$\leq \frac{2(1 + \omega)A}{m} \sum_{i=1}^{m} (f_i(x^k) - f_i^*) + \frac{1 + \omega}{m^2} \sum_{i=1}^{m} D_{1,i}\sigma_{k,i}^2 + \frac{1 + \omega}{m^2} \sum_{i=1}^{m} C_{1,i} + \|\nabla f(x^k)\|^2 \quad (C.17)$$

$$= \frac{2(1 + \omega)A}{m} (f(x^k) - f^*) + \frac{1 + \omega}{m^2} \sum_{i=1}^{m} D_{1,i}\sigma_{k,i}^2 + \frac{1 + \omega}{m} C \|\nabla f(x^k)\|^2 \quad (C.18)$$

where (C.17) holds by defining $A := \max_{i}(A_{1,i} + B_{1,i}L_i - L_i/(1 + \omega))$, and (C.18) holds by defining $C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A \Delta f^* \Delta f^*$ and $\Delta f^* := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^*$.

Thus, we have proved the first part, i.e., (C.8) holds with

$$A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \quad (C.19)$$

$$D_1 = \frac{1 + \omega}{m}, \quad \sigma_{k,i}^2 = \frac{1}{m} \sum_{i=1}^{m} D_{1,i}\sigma_{k,i}^2, \quad (C.20)$$

38
Now we prove the second part $E_k[\sigma_{k+1}^2]$ (i.e., (C.9)). According to (C.7), we have

\[
E_k[\sigma_{k+1}^2] \tag{C.20}
= \mathbb{E}_k \left[ \frac{1}{m} \sum_{i=1}^{m} D_{1,i}^2 \right]
\leq \frac{1}{m} \sum_{i=1}^{m} D_{1,i} \left( (1 - \rho_i) \sigma_{k,i}^2 + 2A_2, i(f(x^k) - f^*) + B_2,i \|\nabla f(x^k)\|^2 + D_{2,i} \mathbb{E}_k[\|g_i\|^2] + C_{2,i} \right)
\]

\[
= \frac{1}{m} \sum_{i=1}^{m} (1 - \rho_i) D_{1,i} \sigma_{k,i}^2 + 2D_A(f(x^k) - f^*) + DB \|\nabla f(x^k)\|^2 + D_\Delta \mathbb{E}_k[\|g_i\|^2] + DC \tag{C.21}
\]

\[
\leq \frac{1}{m} \sum_{i=1}^{m} (1 - \rho_i) D_{1,i} \sigma_{k,i}^2 + 2D_A(f(x^k) - f^*) + D_B \|\nabla f(x^k)\|^2 + DC \\
+ D_D \left( \frac{2(1 + \omega)}{m} A (f(x^k) - f^*) + \frac{1 + \omega}{m^2} \sum_{i=1}^{m} D_{1,i} \sigma_{k,i}^2 + \frac{1 + \omega}{m} \|\nabla f(x^k)\|^2 \right) \\
= \frac{1}{m} \sum_{i=1}^{m} (1 - \rho_i + \tau) D_{1,i} \sigma_{k,i}^2 + 2(D_A + \tau A)(f(x^k) - f^*) \\
+ (D_B + D_D) \|\nabla f(x^k)\|^2 + DC + \tau C \tag{C.22}
\]

\[
\leq (1 - \rho_i + \tau) \sigma_{k}^2 + 2(D_A + \tau A)(f(x^k) - f^*) + (D_B + D_D) \|\nabla f(x^k)\|^2 + DC + \tau C, \tag{C.23}
\]

where (C.21) holds by defining $D_A := \frac{1}{m} \sum_{i=1}^{m} D_{1,i}A_{2,i}$, $D_B := \frac{1}{m} \sum_{i=1}^{m} D_{1,i}B_{2,i}$, $D_D := \frac{1}{m} \sum_{i=1}^{m} D_{1,i}D_{2,i}$, and $D_C := \frac{1}{m} \sum_{i=1}^{m} D_{1,i}C_{2,i}$, (C.22) holds by defining $\tau := \frac{(1 + \omega)B_0}{m}$, and the last inequality holds by defining $\rho := \min_i \rho_i - \tau$.

Now, we have proved the second part, i.e., (C.9) holds with

\[
\rho = \min_i \rho_i - \tau, \quad A_2 = D_A + \tau A, \quad B_2 = D_B + D_D, \quad C_2 = D_C + \tau C.
\]

\[\square\]

In the following sections, we prove that if the parallel workers use some specific methods, i.e., GD, SGD, L-SVRG and SAGA, for computing their local stochastic gradient $\tilde{g}_i^k$ (see Line 3 of Algorithm 6), then $g_k$ (see Line 6 of Algorithm 6) satisfies the unified Assumption 1. Then, we plug their corresponding parameters (i.e., specific values for $A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho$) into our unified Theorem 1 to obtain the detailed convergence rates for these methods.

### C.1.1 DC-GD method

In this section, we show that if the parallel workers use GD for computing their local gradient $\tilde{g}_i^k$, then $g_k$ (see Line 6 of Algorithm 8) satisfies the unified Assumption 1.

**Lemma 5 (DC-GD)** Let the local gradient estimator $\tilde{g}_i^k = \nabla f_i(x^k)$ (see Line 3 of Algorithm 8), then $\tilde{g}_i^k$ satisfies (C.2) and (C.3) with $B_{1,i} = 1, A_{1,i} = C_{1,i} = D_{1,i} = 0, \sigma_{k}^2 = 0, \rho = 1, A_2' = B_2' = C_2' = D_2' = 0$. Thus, according to Theorem 6, $g_k$ (see Line 6 of Algorithm 8) satisfies the unified Assumption 1 with

\[
A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \\
D_1 = \frac{1 + \omega}{m}, \quad \sigma_{k}^2 = 0, \quad \rho = 1, \\
A_2 = 0, \quad B_2 = 0, \quad C_2 = 0,
\]

where $A := \max_i(L_i - L_i/(1 + \omega))$, $C := 2AD_{f}^{\ast}$, and $\Delta_{f}^{\ast} := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^{*}$. 39
Algorithm 8 DC-GD

**Input:** initial point $x^0$, stepsize $\eta_k$

1. for $k = 0, 1, 2, \ldots$ do
2. for all machines $i = 1, 2, \ldots, m$ do in parallel
3. Compute local gradient $\tilde{g}_i^k = \nabla f_i(x^k)$
4. Compress local gradient $C_i^k(\tilde{g}_i^k)$ and send it to the server
5. end for
6. Aggregate received compressed gradient information $g^k = \frac{1}{m}\sum_{i=1}^{m} C_i^k(\tilde{g}_i^k)$
7. $x^{k+1} = x^k - \eta_k g^k$
8. end for

**Proof of Lemma 5.** If the local gradient estimator $\tilde{g}_i^k = \nabla f_i(x^k)$ (see Line 3 of Algorithm 8), it is easy to see that

$$\mathbb{E}_k[\tilde{g}_i^k] = \nabla f_i(x^k)$$

and

$$\mathbb{E}_k[||\tilde{g}_i^k||^2] \leq ||\nabla f_i(x^k)||^2$$

since there is no randomness. Thus the local gradient estimator $\tilde{g}_i^k$ satisfies (C.2) and (C.3) with

$$A_{1,i} = C_{1,i} = D_1' = 0, B_{1,i} = 1, \sigma_1^2 \equiv 0, \rho' = 1, A_2' = B_2' = C_2' = D_2' = 0.$$ 

Then, according to Theorem 6, $g^k$ (see Line 6 of Algorithm 8) satisfies the unified Assumption 1 with

$$A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},$$

$$D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 \equiv 0, \quad \rho = 1,$$

$$A_2 = 0, \quad B_2 = 0, \quad C_2 = 0,$$

where $A := \max_i (L_i - L_i/(1 + \omega))$, $C := 2A\Delta^*_f$, and $\Delta^*_f := f^* - \frac{1}{m}\sum_{i=1}^{m} f_i^*$. \hfill \Box

**Corollary 5 (DC-GD)** Suppose that Assumption 5 holds. Let stepsize

$$\eta \leq \min \left\{ \frac{1}{L'}, \frac{\sqrt{\frac{m \ln 2}{(1 + \omega)LA'C}}, - \frac{me^2}{2(1 + \omega)LC} }{\epsilon^2} \right\},$$

then the number of iterations performed by DC-GD (Algorithm 8) to find an $\epsilon$-solution of nonconvex federated problem (1.1), i.e. a point $\hat{x}$ such that $\mathbb{E}[||\nabla f(\hat{x})||] \leq \epsilon$, can be bounded by

$$K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ 1, \frac{12(1 + \omega)\Delta_0 A}{\epsilon^2 m}, \frac{2(1 + \omega)C}{\epsilon^2 m} \right\},$$

(C.24)

where $A := \max_i (L_i - L_i/(1 + \omega))$, $C := 2A\Delta^*_f$, and $\Delta^*_f := f^* - \frac{1}{m}\sum_{i=1}^{m} f_i^*$.

**Proof of Corollary 5.** According to our unified Theorem 1, if the stepsize is chosen as

$$\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1B_2\rho^{-1}}, \frac{\ln 2}{(LA_1 + LD_1A_2\rho^{-1})K}, \frac{me^2}{2L(C_1 + D_1C_2\rho^{-1})} \right\}$$

$$= \min \left\{ \frac{1}{L'}, \frac{\sqrt{\frac{m \ln 2}{(1 + \omega)LA'C}}, - \frac{me^2}{2(1 + \omega)LC} }{\epsilon^2} \right\},$$

(C.25)
since $B_2 = A_2 = C_2 = 0$, $B_1 = 1$, $A_1 = \frac{(1+\omega)A}{m}$ and $C_1 = \frac{(1+\omega)C}{m}$ according to Lemma 5, then the number of iterations performed by DC-GD (Algorithm 8) to find an $\epsilon$-solution of problem (1.1) can be bounded by

$$K = \frac{8\Delta_0' \max \left\{ B_1 + D_1B_2\rho^{-1}, \frac{12\Delta_0'(A_1 + D_1A_2\rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1C_2\rho^{-1})}{\epsilon^2} \right\}}{\epsilon^2}$$

$$= \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ 1, \frac{12(1+\omega)\Delta_0 A}{\epsilon^2 m}, \frac{2(1+\omega)C}{\epsilon^2 m} \right\}$$

(C.26)

since $B_2 = A_2 = C_2 = 0$, $B_1 = 1$, $A_1 = \frac{(1+\omega)A}{m}$, $C_1 = \frac{(1+\omega)C}{m}$, $\sigma_0^2 = 0$, and

$$\Delta_0' := f(x^0) - f^* + 2^{-1}L\eta^2D_1\rho^{-1}\sigma_0^2 = f(x^0) - f^* = \Delta_0.$$  

\[ \square \]

C.1.2 DC-SGD method

In this section, we show that if the parallel workers use SGD for computing their local stochastic gradient $\tilde{g}_i^k$, then $g^k$ (see Line 6 of Algorithm 9) satisfies the unified Assumption 1.

**Algorithm 9 DC-SGD**

**Input:** initial point $x^0$, stepsize $\eta_k$

1. for $k = 0, 1, 2, \ldots$
2. for all machines $i = 1, 2, \ldots, m$ do in parallel
3. Compute local stochastic gradient $\tilde{g}_i^k$ with Algorithm 3 by changing $f(x)$ to the local $f_i(x)$
4. Compress local gradient $C_i^k(\tilde{g}_i^k)$ and send it to the server
5. end for
6. Aggregate received compressed gradient information $g^k = \frac{1}{m} \sum_{i=1}^{m} C_i^k(\tilde{g}_i^k)$
7. $x^{k+1} = x^k - \eta_k g^k$
8. end for

**Lemma 6 (DC-SGD)** Let the local stochastic gradient estimator $\tilde{g}_i^k$ (see Line 3 of Algorithm 9) satisfy Assumption 9, i.e.,

$$\mathbb{E}_k[\|\tilde{g}_i^k\|^2] \leq 2A_{1,i}(f_i(x^k) - f_i^*) + B_{1,i}\|\nabla f_i(x^k)\|^2 + C_{1,i},$$

then we know that $\tilde{g}_i^k$ satisfies (C.2) and (C.3) with $\rho = 1$, $\sigma_0^2 = 0$, $A_2' = B_2' = C_2' = D_2' = 0$. Thus, according to Theorem 6, $g^k$ (see Line 6 of Algorithm 9) satisfies the unified Assumption 1 with

$$A_1 = \frac{(1+\omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1+\omega)C}{m},$$

$$D_1 = \frac{1+\omega}{m}, \quad \sigma_0^2 = 0, \quad \rho = 1,$$

$$A_2 = 0, \quad B_2 = 0, \quad C_2 = 0,$$

where $A := \max(A_{1,i} + B_{1,i}L_i - L_i/(1+\omega))$, $C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A\Delta_j$, and $\Delta_j := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^*$.

**Proof of Lemma 6.** Suppose that the local stochastic gradient estimator $\tilde{g}_i^k$ (see Line 3 of Algorithm 9) satisfies Assumption 9, i.e.,

$$\mathbb{E}_k[\tilde{g}_i^k] = \nabla f_i(x^k)$$

and

$$\mathbb{E}_k[\|\tilde{g}_i^k\|^2] \leq 2A_{1,i}(f_i(x^k) - f_i^*) + B_{1,i}\|\nabla f_i(x^k)\|^2 + C_{1,i},$$
Thus the local stochastic gradient estimator $\tilde{g}_k^i$ satisfies (C.2) and (C.3) with
\[ A_{1,i} = A_{1,i}, B_{1,i} = B_{1,i}, C_{1,i} = C_{1,i}, D'_1 = 0, \sigma_k^2 \equiv 0, \rho' = 1, A'_2 = B'_2 = C'_2 = D'_2 = 0. \]
Then, according to Theorem 6, $g^k$ (see Line 6 of Algorithm 9) satisfies the unified Assumption 1 with
\[
A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},
\]
\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 \equiv 0, \quad \rho = 1,
\]
\[
A_2 = 0, \quad B_2 = 0, \quad C_2 = 0,
\]
where $A := \max_i (A_{1,i} + B_{1,i}L_i - L_i/(1 + \omega)), C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A\Delta_f^*$ and $\Delta_f^* := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^*$. □

**Corollary 6 (DC-SGD)** Suppose that Assumption 5 holds. Let stepsize
\[
\eta \leq \min \left\{ \frac{1}{L}, \sqrt{\frac{m \ln 2}{(1 + \omega)LAR}}, \frac{me^2}{2(1 + \omega)LC} \right\},
\]
then the number of iterations performed by DC-SGD (Algorithm 9) to find an $\epsilon$-solution of nonconvex federated problem (1.1) with (1.2) or (1.3), i.e. a point $\hat{x}$ such that $E[\|\nabla f(\hat{x})\|] \leq \epsilon$, can be bounded by
\[
K = \frac{8\Delta_0}{\epsilon^2} \max \left\{ 1, \frac{12(1 + \omega)\Delta_0 A}{\epsilon^2m}, \frac{2(1 + \omega)C}{\epsilon^2m} \right\}, \quad \text{(C.27)}
\]
where where $A := \max_i (A_{1,i} + B_{1,i}L_i - L_i/(1 + \omega)), C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A\Delta_f^*$ and $\Delta_f^* := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^*$.

**Proof of Corollary 6.** According to our unified Theorem 1, if the stepsize is chosen as
\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1B_2\rho^{-1}}, \sqrt{\frac{2\ln 2}{(LA_1 + LD_1A_2\rho^{-1})K}}, \frac{e^2}{2L(C_1 + D_1C_2\rho^{-1})} \right\}
\]
\[
= \min \left\{ \frac{1}{L}, \sqrt{\frac{m \ln 2}{(1 + \omega)LAR}}, \frac{me^2}{2(1 + \omega)LC} \right\}, \quad \text{(C.28)}
\]
since $B_2 = A_2 = C_2 = 0, B_1 = 1, A_1 = \frac{(1 + \omega)A}{m}$ and $C_1 = \frac{(1 + \omega)C}{m}$ according to Lemma 6, then the number of iterations performed by DC-SGD (Algorithm 9) to find an $\epsilon$-solution of problem (1.1) with (1.2) or (1.3) can be bounded by
\[
K = \frac{8\Delta_0}{\epsilon^2} \max \left\{ \frac{1}{LB_1 + LD_1B_2\rho^{-1}}, \frac{12\Delta_0(A_1 + D_1A_2\rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1C_2\rho^{-1})}{\epsilon^2} \right\}
\]
\[
= \frac{8\Delta_0}{\epsilon^2} \max \left\{ 1, \frac{12(1 + \omega)\Delta_0 A}{\epsilon^2m}, \frac{2(1 + \omega)C}{\epsilon^2m} \right\}, \quad \text{(C.29)}
\]
since $B_2 = A_2 = C_2 = 0, B_1 = 1, A_1 = \frac{(1 + \omega)A}{m}, C_1 = \frac{(1 + \omega)C}{m}, \sigma_0^2 = 0$, and
\[
\Delta_0^* := f(x^0) - f^* + 2^{-1}Ln^2D_1\rho^{-1}\sigma_0^2 = f(x^0) - f^* = \Delta_0.
\]
□
C.1.3 DC-LSVRG method

In this section, we show that if the parallel workers use L-LSVRG for computing their local gradient \( \tilde{g}_i^k \), then \( g^k \) (see Line 7 of Algorithm 10) satisfies the unified Assumption 1.

**Algorithm 10 DC-LSVRG**

| Input: | initial point \( x^0 = w^0 \), stepsize \( \eta_k \), minibatch size \( b \), probability \( p \in (0, 1] \) |
|---|---|
| for \( k = 0, 1, 2, \ldots \) do |
| for all machines \( i, 1, 2, \ldots, m \) do in parallel |
| Compute local stochastic gradient \( \nabla f_i(x^k) \) |
| Compress local gradient \( C_i^k(\tilde{g}_i^k) \) and send it to the server |
| for \( i=1,2,\ldots,m \) do in parallel |
| end for |
| end for |
| end for |

**Lemma 7 (DC-LSVRG)** Let the local stochastic gradient estimator \( \tilde{g}_i^k = \frac{1}{b} \sum_{j \in I_i}(\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k) \) (see Line 3 of Algorithm 10), then we know that \( \tilde{g}_i^k \) satisfies (C.2) and (C.3) with \( A_{1,i} = 0, B_{1,i} = 1, C_{1,i} = 0, D'_i = \frac{E^2}{b}, \sigma^2 = \|x^k - w^k\|^2, \rho = p + p\gamma - \gamma, A'_2 = 0, B'_2 = (1-p)\eta^2\gamma^{-1}, C'_2 = 0, D'_2 = \eta^2, \) and \( \forall \gamma > 0 \). Thus, according to Theorem 6, \( g^k \) (see Line 7 of Algorithm 10) satisfies the unified Assumption 1 with

\[
\begin{align*}
A_1 &= \frac{(1+\omega)A}{m}, \\
B_1 &= 1, \\
C_1 &= \frac{(1+\omega)C}{m}, \\
D_1 &= \frac{1+\omega}{m}, \\
\sigma^2 &= \frac{E^2}{b}\|x^k - w^k\|^2, \\
\rho &= p + p\gamma - \gamma, \\
A_2 &= \tau A, \\
B_2 &= \frac{E^2((1-p)\eta^2\gamma^{-1} + \eta^2)}{b}, \\
C_2 &= \tau C,
\end{align*}
\]

where \( A := \max_i(L_i - L_i/(1 + \omega)) \), \( C := 2A\Delta f^*, \Delta f^* := f^* - \frac{1}{m} \sum_{i=1}^m f_i^* \), \( \tau := \frac{(1+\omega)E^2\eta^2}{mb} \) and \( \forall \gamma > 0 \).

**Proof of Lemma 7.** If the local stochastic gradient estimator \( \tilde{g}_i^k = \frac{1}{b} \sum_{j \in I_i}(\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k) \) (see Line 3 of Algorithm 10), we show the following equations:

\[
\begin{align*}
\mathbb{E}_k[\tilde{g}_i^k] &= \mathbb{E}_k \left[ \frac{1}{b} \sum_{j \in I_i}(\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k) \right] \\
&= \nabla f_i(x^k) - \nabla f_i(w^k) + \nabla f_i(w^k) = \nabla f_i(x^k)
\end{align*}
\]

and

\[
\begin{align*}
\mathbb{E}_k[\|\tilde{g}_i^k\|^2] &= \mathbb{E}_k \left[ \|\tilde{g}_i^k - \nabla f_i(x^k)\|^2 + \|\nabla f_i(x^k)\|^2 \right] \\
&= \mathbb{E}_k \left[ \left\| \frac{1}{b} \sum_{j \in I_i}(\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k) - \nabla f_i(x^k) \right\|^2 + \|\nabla f_i(x^k)\|^2 \right]
\end{align*}
\]
Now, we define
\[ \eta = \eta^k + (1 - p)\eta^k \delta_{\omega}(x_k). \]
where \((C.34)\) uses Line 8 of Algorithm 10, \((C.35)\) uses Young’s inequality for \(\forall \gamma > 0\), and \((C.36)\) follows from the definition \(\bar{\sigma}^2_k := \|x^k - w^k\|^2\).

Now, according to \((C.32)\) and \((C.36)\), we know the local stochastic gradient estimator \(\tilde{g}_i^k\) (see Line 3 of Algorithm 10) satisfies \((C.2)\) and \((C.3)\) with

\[
A_{1,i} = 0, \quad B_{1,i} = 1, \quad D'_1 = \frac{L^2}{b}, \quad \bar{\sigma}^2_k = \|x^k - w^k\|^2, \quad C_{1,i} = 0, \quad \rho' = p + p\gamma - \gamma, \quad A'_2 = 0, \quad B'_2 = (1 - p)\eta^2\gamma^{-1}, \quad D'_2 = \eta^2, \quad C'_2 = 0, \quad \forall \gamma > 0.
\]

Thus, according to Theorem 6, \(g^k\) (see Line 7 of Algorithm 10) satisfies the unified Assumption 1 with

\[
A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},
\]

\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma^2_k = \frac{L^2}{b}\|x^k - w^k\|^2, \quad \rho = p + p\gamma - \gamma - \tau,
\]

\[
A_2 = \tau A, \quad B_2 = \frac{L^2((1 - p)\eta^2\gamma^{-1} + \eta^2)}{b}, \quad C_2 = \tau C,
\]

where \(A := \max_i(L_i - L_i/(1 + \omega)), \quad C := 2A\Delta^*_f, \quad \Delta^*_f := f^* - \frac{1}{m}\sum_{i=1}^mf_i^*, \quad \tau := \frac{(1 + \omega)L^2\eta^2}{m^2b^2} \quad \text{and} \quad \forall \gamma > 0. \]

\[ \eta \leq \min \left\{ \frac{1}{L + L(1 + \omega)Bm^{-1}b^{-1}p^{-1}}, \sqrt{\frac{m\ln 2}{(1 + \omega)(1 + \tau p^{-1})LAR}}, \frac{me^2}{2(1 + \omega)(1 + \tau p^{-1})L^2C} \right\}, \]

**Corollary 7 (DC-LSVRG)** Suppose that Assumption 5 and 6 hold. Let stepsize

\[ \eta \leq \min \left\{ \frac{1}{L + L(1 + \omega)Bm^{-1}b^{-1}p^{-1}}, \sqrt{\frac{m\ln 2}{(1 + \omega)(1 + \tau p^{-1})LAR}}, \frac{me^2}{2(1 + \omega)(1 + \tau p^{-1})L^2C} \right\}, \]

44
then the number of iterations performed by DC-LSVRG (Algorithm 10) to find an \( \epsilon \)-solution of nonconvex federated problem (1.1) with (1.3), i.e. a point \( \bar{x} \) such that \( \mathbb{E}\|\nabla f(\bar{x})\| \leq \epsilon \), can be bounded by
\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ 1 + \frac{(1 + \omega)B}{mbp}, \frac{12(1 + \omega)(1 + \tau \rho^{-1})\Delta_0 A}{me^2}, \frac{2(1 + \omega)(1 + \tau \rho^{-1})LC}{me^2} \right\}, \tag{C.37}
\]
where \( A := \max_i (L_i - L_i/(1 + \omega)) \), \( B := \tilde{L}^2((1 - p)\eta^2 \gamma^{-1} + 2\eta^2) \), \( C := 2A\Delta_f \), \( \Delta_f := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^* \), \( \rho := p + p\gamma - \gamma - \tau \), \( \tau := \frac{(1 + \omega)\tilde{L}^2\eta^2}{mb} \) and \( \forall \gamma > 0 \).

**Proof of Corollary 7.** According to our unified Theorem 1, if the stepsize is chosen as
\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1} \frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1} K) \frac{\epsilon^2}{2L(C_1 + D_1 C_2 \rho^{-1})}}, \frac{1}{L + L(1 + \omega)Bm^{-1}b^{-1} \rho^{-1} \frac{\ln 2}{(1 + \omega)(1 + \tau \rho^{-1}) LAK} \frac{m \epsilon^2}{2(1 + \omega)(1 + \tau \rho^{-1}) LC}} \right\}
\]

since \( B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = \frac{2}{\rho}, B = \tilde{L}^2((1 - p)\eta^2 \gamma^{-1} + 2\eta^2) \), \( A_1 = \frac{(1 + \omega)A}{m}, A_2 = \tau A, C_1 = \frac{(1 + \omega)C}{m} \) and \( C_2 = \tau C \) according to Lemma 7, then the number of iterations performed by DC-LSVRG (Algorithm 10) to find an \( \epsilon \)-solution of problem (1.1) with (1.3) can be bounded by
\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ 1 + \frac{(1 + \omega)B}{mbp}, \frac{12\Delta_0(A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{me^2} \right\}, \tag{C.38}
\]

since \( B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = \frac{2}{\rho}, B = \tilde{L}^2((1 - p)\eta^2 \gamma^{-1} + 2\eta^2) \), \( A_1 = \frac{(1 + \omega)A}{m}, A_2 = \tau A, C_1 = \frac{(1 + \omega)C}{m} \) and \( C_2 = \tau C \), and \( \Delta_f := f(x^0) - f^* + 2^{-1}L\eta^2 D_1 \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0 \) due to \( \sigma_0^2 = \frac{L^2}{m} \| x^0 - w^0 \|^2 = 0 \). \( \square \)

**C.1.4 DC-SAGA method**

In this section, we show that if the parallel workers use SAGA for computing their local gradient \( \tilde{g}_i^k \), then \( g^k \) (see Line 7 of Algorithm 11) satisfies the unified Assumption 1.

**Algorithm 11 DC-SAGA**

Input: initial point \( x^0, \{w_i^0\}_{i=1}^n \), stepsize \( \eta_k \), minibatch size \( b \)
1: for \( k = 0, 1, 2, \ldots \) do
2: for all machines \( i = 1, 2, \ldots, m \) do in parallel
3: Compute local stochastic gradient \( \tilde{g}_i^k = \frac{1}{b} \sum_{j \in I_b} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^n \nabla f_{i,j}(w_{i,j}^k) \)
4: Compress local gradient \( C_i^k(\tilde{g}_i^k) \) and send it to the server
5: \( w_{i,j}^{k+1} = \begin{cases} x^k & \text{for } j \in I_b \\ w_{i,j}^k & \text{for } j \notin I_b \end{cases} \)
6: end for
7: Aggregate received compressed gradient information \( g^k = \frac{1}{m} \sum_{i=1}^m C_i^k(\tilde{g}_i^k) \)
8: \( x^{k+1} = x^k - \eta_k g^k \)
9: end for

**Lemma 8 (DC-SAGA)** Let the local stochastic gradient estimator \( \tilde{g}_i^k = \frac{1}{b} \sum_{j \in I_b} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^n \nabla f_{i,j}(w_{i,j}^k) \) (see Line 3 of Algorithm 11), then we know that \( \tilde{g}_i^k \) satisfies (C.6) and (C.7) with \( A_{1,i} = \)
0, \beta_{1,i} = 1, \beta_{1,i} = 0, D_{1,i} = \frac{\eta^2}{m}, \sigma_{2,i} = \frac{1}{\beta} \sum_{j=1}^{n} ||x^k - w_{i,j}^k||^2, \rho_i = \frac{b}{n} + \frac{\gamma}{n} - \gamma, A_{2,i} = 0, B_{2,i} = (1 - \frac{1}{m}) \eta^2 \gamma^{-1}, C_{2,i} = 0, D_{2,i} = \eta^2, \text{ and } \forall \gamma > 0. \text{ Thus, according to Theorem 3, } g^k \text{ (see Line 7 of Algorithm 11) satisfies the unified Assumption 1 with}

\begin{align*}
A_1 &= \frac{(1 + \omega)A}{m}, & B_1 &= 1, & C_1 &= \frac{(1 + \omega)C}{m}, \\
D_1 &= \frac{1 + \omega}{m}, & \sigma^2_k &= \frac{1}{mn} \sum_{i=1}^{m} \sum_{j=1}^{n} \frac{\tilde{L}^2}{b} ||x^k - w_{i,j}^k||^2, & \rho &= \frac{b}{n} + \frac{\gamma}{n} - \gamma, \\
A_2 &= \tau A, & B_2 &= \frac{\tilde{L}^2((1 - \frac{1}{m}) \eta^2 \gamma^{-1} + \eta^2)}{b}, & C_2 &= \tau C,
\end{align*}

where \( A := \max_i (L_i - L_i/(1 + \omega)) \), \( C := 2A \Delta^+_f \), \( \Delta^+_f := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^* \), \( \tau := \frac{(1+\omega)\tilde{L}^2 n^2}{mb} \) and \( \forall \gamma > 0 \).

**Proof of Lemma 8.** If the local stochastic gradient estimator \( \bar{g}_k^i = \frac{1}{b} \sum_{j \in I_h} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) \) (see Line 3 of Algorithm 11), we show the following equations:

\begin{align*}
\mathbb{E}_k[\bar{g}_k^i] &= \mathbb{E}_k \left[ \frac{1}{b} \sum_{j \in I_h} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) \right] \\
&= \nabla f_i(x^k) - \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) \\
&= \nabla f_i(x^k)
\end{align*}

and

\begin{align*}
\mathbb{E}_k[||\bar{g}_k^i||^2] &= \mathbb{E}_k \left[ ||\bar{g}_k^i - \nabla f_i(x^k)||^2 + ||\nabla f_i(x^k)||^2 \right] \\
&= \mathbb{E}_k \left[ \left( \frac{1}{b} \sum_{j \in I_h} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) \right)^2 ight] + ||\nabla f_i(x^k)||^2 \\
&= \frac{1}{b^2} \mathbb{E}_k \left[ \left( \sum_{j \in I_h} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) - \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(x^k) - \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) \right)^2 \right] + ||\nabla f_i(x^k)||^2 \\
&= \frac{1}{b} \mathbb{E}_k \left[ ||\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)||^2 \right] + ||\nabla f_i(x^k)||^2 \\
&\leq \frac{1}{b} \mathbb{E}_k \left[ ||\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)||^2 \right] + ||\nabla f_i(x^k)||^2 \quad \text{(C.40)} \\
&\leq \frac{\tilde{L}^2}{b} \frac{1}{n} \sum_{j=1}^{n} ||x^k - w_{i,j}^k||^2 + ||\nabla f_i(x^k)||^2, \quad \text{(C.41)}
\end{align*}

where (C.40) uses the fact \( \mathbb{E}[||x - \mathbb{E}[x]||^2] \leq \mathbb{E}[||x||^2] \), and the last inequality uses Assumption 7 (i.e., (2.6)).
Now, we define $\sigma^2_{k,i} := \frac{1}{n} \sum_{j=1}^{n} \|x^{k} - w_{i,j}^{k}\|^2$ and obtain

$$
E_k[\sigma^2_{k+1,i}]
\begin{aligned}
&:= E_k \left[ \frac{1}{n} \sum_{j=1}^{n} \|x^{k+1} - w_{i,j}^{k+1}\|^2 \right] \\
&= E_k \left[ \frac{1}{n} \sum_{j=1}^{n} \|x^{k+1} - x^{k}\|^2 + \frac{1}{n} \sum_{j=1}^{n} \left( 1 - \frac{b}{n} \right) \|x^{k+1} - w_{i,j}^{k}\|^2 \right] \\
&= \frac{b}{n} E_k \eta^2 \|g^k\|^2 + \left( 1 - \frac{b}{n} \right) E_k \left[ \frac{1}{n} \sum_{j=1}^{n} \|x^{k} - \eta g^k - w_{i,j}^{k}\|^2 \right] \\
&= \frac{b}{n} E_k \eta^2 \|g^k\|^2 + \left( 1 - \frac{b}{n} \right) E_k \left[ \frac{1}{n} \sum_{j=1}^{n} \left( \|x^{k} - w_{i,j}^{k}\|^2 + \|\eta g^k\|^2 - 2\langle x^{k} - w_{i,j}^{k}, \eta g^k \rangle \right) \right] \\
&\leq \eta^2 E_k \|g^k\|^2 + \left( 1 - \frac{b}{n} \right) E_k \left[ \frac{1}{n} \sum_{j=1}^{n} \|x^{k} - w_{i,j}^{k}\|^2 \right] \\
&\quad + \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{j=1}^{n} \left( \gamma \|x^{k} - w_{i,j}^{k}\|^2 + \frac{\eta^2}{\gamma} \|\nabla f(x^k)\|^2 \right) \\
&= \left( 1 - \left( \frac{b}{n} + \frac{b}{n} \gamma - \gamma \right) \right) \sigma^2_{k,i} + \frac{(1 - \frac{b}{n} \eta^2 \gamma)}{\gamma} \|\nabla f(x^k)\|^2 + \eta^2 E_k \|g^k\|^2
\end{aligned}
$$

where (C.42) uses Line 5 of Algorithm 11, (C.43) uses Line 8 of Algorithm 11, (C.44) uses Young’s inequality for $\forall \gamma > 0$, and (C.45) follows from the definition $\sigma^2_{k,i} := \frac{1}{n} \sum_{j=1}^{n} \|x^{k} - w_{i,j}^{k}\|^2$.

Now, according to (C.41) and (C.45), we know the local stochastic gradient estimator $\tilde{g}_i^k$ (see Line 3 of Algorithm 11) satisfies (C.6) and (C.7) with

$$
A_{1,i} = 0, \quad B_{1,i} = 1, \quad D_{1,i} = \frac{\bar{L}^2}{b}, \quad \sigma^2_{k,i} = \frac{1}{n} \sum_{j=1}^{n} \|x^{k} - w_{i,j}^{k}\|^2, \quad C_{1,i} = 0,
$$

$$
\rho_i = \frac{b}{n} + \frac{b}{n} \gamma - \gamma, \quad A_{2,i} = 0, \quad B_{2,i} = (1 - \frac{b}{n} \eta^2 \gamma^{-1}), \quad D_{2,i} = \eta^2, \quad C_{2,i} = 0, \quad \forall \gamma > 0.
$$

Thus, according to Theorem 3, $g^k$ (see Line 7 of Algorithm 11) satisfies the unified Assumption 1 with

$$
A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},
$$

$$
D_1 = \frac{1 + \omega}{m}, \quad \sigma^2_k = \frac{1}{mn} \sum_{i=1}^{m} \sum_{j=1}^{n} \frac{\bar{L}^2}{b} \|x^{k} - w_{i,j}^{k}\|^2, \quad \rho = \frac{b}{n} + \frac{b}{n} \gamma - \gamma, \quad \frac{1}{m} \sum_{i=1}^{m} f_i^*, \quad \tau := \frac{(1 + \omega)\bar{L}^2 \eta^2}{mb}, \quad \forall \gamma > 0.
$$

where $A := \max_i (L_i - L_i/(1 + \omega))$, $C := 2A \Delta_f^*, \Delta_f^* := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^*$, $\tau := \frac{(1 + \omega)\bar{L}^2 \eta^2}{mb}$ and $\forall \gamma > 0.$ 

$\square$
Corollary 8 (DC-SAGA) Suppose that Assumption 5 and 7 hold. Let stepsize
\[
\eta \leq \min \left\{ \frac{1}{L + L(1 + \omega)Bm^{-1}b^{-1} \rho^{-1}}, \sqrt{\frac{m \ln 2}{(1 + \omega)(1 + \tau \rho^{-1})LAK}}, \sqrt{\frac{mc^2}{2(1 + \omega)(1 + \tau \rho^{-1})LC}} \right\},
\]
then the number of iterations performed by DC-SAGA (Algorithm 11) to find an \( \epsilon \)-solution of nonconvex federated problem (1.1) with (1.3), i.e. a point \( \tilde{x} \) such that \( \mathbb{E}[\|\nabla f(\tilde{x})\|] \leq \epsilon \), can be bounded by
\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ 1 + \frac{(1 + \omega)B}{mbp}, \frac{12(1 + \omega)(1 + \tau \rho^{-1})\Delta_0 A}{mc^2}, \frac{2(1 + \omega)(1 + \tau \rho^{-1})LC}{mc^2} \right\},
\] (C.46)
where \( A := \max_i(L_i - L_i/(1 + \omega)), B := \bar{L}^2((1 - \frac{b}{n})\eta^2 \gamma^{-1} + \eta^2), C := 2A\Delta_f, \Delta_f := f^* - \frac{1}{m} \sum_{i=1}^m f_i^*, \rho := \frac{b}{n} + \frac{b}{n} \gamma - \gamma, \tau := m \frac{(1 + \omega)L^2 \eta^2}{mb} \) and \( \forall \gamma > 0 \).

Proof of Corollary 8. According to our unified Theorem 1, if the stepsize is chosen as
\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}, \sqrt{\frac{m \ln 2}{2L(C_1 + D_1 C_2 \rho^{-1})}} \right\}
\]
then the number of iterations performed by DC-LSVRG (Algorithm 11) to find an \( \epsilon \)-solution of problem (1.1) with (1.3) can be bounded by
\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ B_1 + D_1 B_2 \rho^{-1} - \frac{12\Delta_0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\}
\]
(C.47)
since \( B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = \frac{B}{B}, B = \bar{L}^2((1 - \frac{b}{n})\eta^2 \gamma^{-1} + \eta^2), A_1 = \frac{(1 + \omega)A}{m}A_2 = \tau A, C_1 = \frac{(1 + \omega)C}{m}C_2 = \tau C \) according to Lemma 8, then the number of iterations performed by DC-SAGA (Algorithm 11) to find an \( \epsilon \)-solution of nonconvex federated problem (1.1) with (1.3) can be bounded by
\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ B_1 + D_1 B_2 \rho^{-1} - \frac{12\Delta_0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\}
\]
(C.47)
since \( B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = \frac{B}{B}, B = \bar{L}^2((1 - \frac{b}{n})\eta^2 \gamma^{-1} + \eta^2), A_1 = \frac{(1 + \omega)A}{m}A_2 = \tau A, C_1 = \frac{(1 + \omega)C}{m}C_2 = \tau C, \) and \( \Delta_0 := f(x^0) - f^* + 2^{-1} L \eta^2 D_1, \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0 \) by letting \( \sigma_0^2 = 0 \). \( \square \)

C.2 DIANA framework for nonconvex federated optimization

Similar to Section C.1, we first prove a general Theorem for DIANA framework (Algorithm 7) which shows that several (new) methods belonging to the general DIANA framework satisfy Assumption 1 and thus can be captured by our unified analysis. Then, we plug their corresponding parameters into our unified Theorem 1 to obtain the detailed convergence rates for these methods.

Before proving the Theorem 4, we first provide a simple version as in Theorem 7 where all workers share the same variance term \( \tilde{\sigma}_k^2 \) (see (C.48)). If the parallel workers use GD, SGD or L-SVRG for computing their local stochastic gradient \( \tilde{g}_i \) (see Line 3 of Algorithm 7), then they indeed share the same variance term \( \tilde{\sigma}_k^2 \), i.e., Theorem 7 includes these settings. However, if the parallel workers use SAGA-type methods for computing their local stochastic gradient \( \tilde{g}_i \), then the variance term \( \sigma^2_{k,i} \) (see (C.52)) is different for different worker \( i \), i.e., the more general Theorem 4 includes this SAGA setting while Theorem 7 does not.

Theorem 7 (DIANA framework with same variance for all workers) Suppose that the local stochastic gradient \( \tilde{g}_i \) (see Line 3 of Algorithm 7) satisfies
\[
\mathbb{E}_i[\|\tilde{g}_i^k\|^2] \leq 2A_1 f_i(x^k) - f_i^* + B_1 \|\nabla f_i(x^k)\|^2 + D_1 \tilde{\sigma}_k^2 + C_1, \tag{C.48}
\]
\[
\mathbb{E}_k[\tilde{g}_k^2] \leq (1 - \rho')\tilde{\sigma}_k^2 + 2A_2 f(x^k) - f^* + B_2 \|\nabla f(x^k)\|^2 + D_2 \mathbb{E}_k[\|g_k^2\|^2] + C_2, \tag{C.49}
\]
48
then $g^k$ (see Line 7 of Algorithm 7) satisfies the unified Assumption 1, i.e.,

\[
\begin{align*}
\mathbb{E}_k[\|g^k\|^2] &\leq 2A_1(f(x^k) - f^*) + B_1\|\nabla f(x^k)\|^2 + D_1\sigma_k^2 + C_1, \\
\mathbb{E}_k[\sigma_{k+1}^2] &\leq (1 - \rho)\sigma_k^2 + 2A_2(f(x^k) - f^*) + B_2\|\nabla f(x^k)\|^2 + C_2,
\end{align*}
\]

with parameters

\[
\begin{align*}
A_1 &= \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \\
D_1 &= \frac{1 + \omega}{m}, \quad \sigma_k^2 = D_1\sigma_k^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^k) - h_i^k\|^2,
\end{align*}
\]

\[
\rho = \min \{\rho' - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\},
\]

\[
A_2 = D_1' \tau A, \quad B_2 = D_1' B_2 + B, \quad C_2 = D_1' C_2 + \tau C,
\]

where $A := \max_i (A_{1,i} + (B_{1,i} - 1)L_i)$, $B := \frac{\omega(1 + \beta)L_i^2}{1 + \omega} + D_1' D_2'$, $C := \frac{1}{m} \sum_{i=1}^m C_{1,i} + 2A\Delta_j^*$, $\Delta_j^* := f^* - \frac{1}{m} \sum_{i=1}^m f_i^*$, $\tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}$, and $\forall \beta > 0$.

Before providing the proof for Theorem 7, we recall the more general Theorem 4 here for better comparison. Then we provide the detailed proofs for Theorems 7 and 4.

**Theorem 4 (DIANA framework with different variance for different worker)** Suppose that the local stochastic gradient $\bar{g}_i^k$ (see Line 3 of Algorithm 6) satisfies

\[
\begin{align*}
\mathbb{E}_k[\|\bar{g}_i^k\|^2] &\leq 2A_{1,i}(f_i(x^k) - f_i^*) + B_{1,i}\|\nabla f_i(x^k)\|^2 + D_{1,i}\sigma_{k,i}^2 + C_{1,i}, \\
\mathbb{E}_k[\sigma_{k+1,i}^2] &\leq (1 - \rho_i)\sigma_{k,i}^2 + 2A_{2,i}(f(x^k) - f^*) + B_{2,i}\|\nabla f(x^k)\|^2 + D_{2,i}\mathbb{E}_k[\|g^k\|^2] + C_{2,i},
\end{align*}
\]

then $g^k$ (see Line 7 of Algorithm 7) also satisfies the unified Assumption 1, i.e.,

\[
\begin{align*}
\mathbb{E}_k[\|g^k\|^2] &\leq 2A_1(f(x^k) - f^*) + B_1\|\nabla f(x^k)\|^2 + D_1\sigma_k^2 + C_1, \\
\mathbb{E}_k[\sigma_{k+1}^2] &\leq (1 - \rho)\sigma_k^2 + 2A_2(f(x^k) - f^*) + B_2\|\nabla f(x^k)\|^2 + C_2,
\end{align*}
\]

with parameters

\[
\begin{align*}
A_1 &= \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \\
D_1 &= \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{1}{m} \sum_{i=1}^m D_{1,i}\sigma_{k,i}^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^k) - h_i^k\|^2,
\end{align*}
\]

\[
\rho = \min \{\min_i \rho_i - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\},
\]

\[
A_2 = D_A + \tau A, \quad B_2 = D_B + B, \quad C_2 = D_C + \tau C,
\]

where $A := \max_i (A_{1,i} + (B_{1,i} - 1)L_i)$, $B := \frac{\omega(1 + \beta)L_i^2}{1 + \omega} + D_1D_2$, $C := \frac{1}{m} \sum_{i=1}^m C_{1,i} + 2A\Delta_j^*$, $\Delta_j^* := f^* - \frac{1}{m} \sum_{i=1}^m f_i^*$, $\tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}$, $D_A := \frac{1}{m} \sum_{i=1}^m D_{1,i}A_{2,i}$, $D_B := \frac{1}{m} \sum_{i=1}^m D_{1,i}B_{2,i}$, $D_D := \frac{1}{m} \sum_{i=1}^m D_{1,i}D_{2,i}$, $D_C := \frac{1}{m} \sum_{i=1}^m D_{1,i}C_{2,i}$, and $\forall \beta > 0$. 

49
Proof of Theorem 7. First, we show that the gradient estimator $g^k$ (see Line 7 of Algorithm 7) is unbiased:

$$\mathbb{E}_k[g^k] = \mathbb{E}_k \left[ h^k + \frac{1}{m} \sum_{i=1}^{m} \Delta_i^k \right]$$

Then, we prove the upper bound for the second moment of gradient estimator $g^k$:

$$\mathbb{E}_k[||g^k||^2] \leq \frac{\omega}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^{m} ||\bar{g}_i^k - h_i^k||^2 \right] + \mathbb{E}_k \left[ \left( \frac{1}{m} \sum_{i=1}^{m} \bar{g}_i^k - \nabla f_i(x^k) \right)^2 \right]$$

(C.1)\quad \mathbb{E}_k \left[ \left( \frac{1}{m} \sum_{i=1}^{m} \bar{g}_i^k - \nabla f_i(x^k) \right)^2 \right] + \mathbb{E}_k \left[ \frac{1}{m} \sum_{i=1}^{m} \nabla f_i(x^k) \right]^2

$$= \frac{\omega}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^{m} ||\bar{g}_i^k - h_i^k||^2 \right] + \frac{1}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^{m} ||\bar{g}_i^k - \nabla f_i(x^k)||^2 \right] + \frac{1}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^{m} ||\nabla f_i(x^k)||^2 \right]$$

$$= \frac{1 + \omega}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^{m} ||\bar{g}_i^k - \nabla f_i(x^k)||^2 \right] + \frac{\omega}{m^2} \sum_{i=1}^{m} ||\nabla f_i(x^k) - h_i^k||^2 + ||\nabla f(x^k)||^2$$

$$= \frac{1 + \omega}{m^2} \sum_{i=1}^{m} \left( A_{1,i} ||f_i(x^k) - f^*_i|| + B_{1,i} ||\nabla f_i(x^k)||^2 + D_{1,i} \sigma_k^2 + C_{1,i} - ||\nabla f_i(x^k)||^2 \right)$$

(C.48)\quad \sum_{i=1}^{m} \left( A_{1,i} ||f_i(x^k) - f^*_i|| + B_{1,i} ||\nabla f_i(x^k)||^2 + D_{1,i} \sigma_k^2 + C_{1,i} - ||\nabla f_i(x^k)||^2 \right)

$$+ \frac{\omega}{m^2} \sum_{i=1}^{m} ||\nabla f_i(x^k) - h_i^k||^2 + ||\nabla f(x^k)||^2$$

50
\[
\leq \frac{1 + \omega}{m^2} \sum_{i=1}^{m} (2(A_{1,i} + (B_{1,i} - 1)L_i))(f_i(x^k) - f_i^*) + D'_i \tilde{\sigma}_k^2 + C_{1,i}) \\
+ \frac{\omega}{m^2} \sum_{i=1}^{m} \left( \left\| \nabla f_i(x^k) - h_i^k \right\|^2 + \left\| \nabla f(x^k) \right\|^2 \right) \\
\leq \frac{2(1 + \omega)A}{m^2} \sum_{i=1}^{m} (f_i(x^k) - f_i^*) + \frac{1 + \omega}{m} D'_i \tilde{\sigma}_k^2 + \frac{1 + \omega}{m^2} \sum_{i=1}^{m} C_{1,i} \\
+ \frac{\omega}{m^2} \sum_{i=1}^{m} \left( \left\| \nabla f_i(x^k) - h_i^k \right\|^2 + \left\| \nabla f(x^k) \right\|^2 \right) \\
= \frac{2(1 + \omega)A}{m} (f(x^k) - f^*) + \frac{1 + \omega}{m} \left( D'_i \tilde{\sigma}_k^2 + \frac{\omega}{1 + \omega} \sum_{i=1}^{m} \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \right) + \left\| \nabla f(x^k) \right\|^2 \\
+ \frac{(1 + \omega)C}{m}, \tag{C.57}
\]

where (C.57) holds by defining \( A := \max_i(A_{1,i} + (B_{1,i} - 1)L_i) \), and (C.58) holds by defining \( C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A\Delta^*_f \) and \( \Delta^*_f := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^* \).

Thus, we have proved the first part, i.e., (C.50) holds with
\[
A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \tag{C.59}
D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = D'_i \tilde{\sigma}_k^2 + \frac{\omega}{1 + \omega} \sum_{i=1}^{m} \left\| \nabla f_i(x^k) - h_i^k \right\|^2. \tag{C.60}
\]

Now we prove the second part (i.e., (C.51)). According to (C.49), we have
\[
\mathbb{E}_k [D'_i \tilde{\sigma}_{k+1}^2] \leq (1 - \rho')D'_i \tilde{\sigma}_k^2 + 2D'_i A'_2 (f(x^k) - f^*) + D'_i B'_2 \left\| \nabla f(x^k) \right\|^2 + D'_i D'_2 \mathbb{E}_k [\| g^k \|^2] + D'_i C'_2. \tag{C.61}
\]

For the second term of \( \tilde{\sigma}_{k+1}^2 \), we bound it as follows:
\[
\mathbb{E}_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \left\| \nabla f_i(x^{k+1}) - h_i^{k+1} \right\|^2 \right] \\
= \mathbb{E}_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \left( \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) + \nabla f_i(x^k) - h_i^{k+1} \right\|^2 \right) \right] \\
= \mathbb{E}_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) + \nabla f_i(x^k) - h_i^k - \alpha C_i^k(g_i^k - h_i^k) \right\|^2 \right] \\
= \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \mathbb{E}_k \left[ \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \right\|^2 + \left\| \nabla f_i(x^k) - h_i^k - \alpha C_i^k(g_i^k - h_i^k) \right\|^2 \right] \\
+ 2 \langle \nabla f_i(x^{k+1}) - \nabla f_i(x^k), \nabla f_i(x^k) - h_i^k - \alpha C_i^k(g_i^k - h_i^k) \rangle \\
= \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \mathbb{E}_k \left[ \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \right\|^2 + \left\| \nabla f_i(x^k) - h_i^k - \alpha C_i^k(g_i^k - h_i^k) \right\|^2 \right] \\
+ 2 \langle \nabla f_i(x^{k+1}) - \nabla f_i(x^k), (1 - \alpha)(\nabla f_i(x^k) - h_i^k) \rangle \\
\]
\[
\begin{align*}
&= \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} E_k \left[ \| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \|^2 + (1 - 2\alpha) \| \nabla f_i(x^k) - h_i^k \|^2 + \alpha^2 \| C_i^k (\overline{g}_i^k - h_i^k) \|^2 \\
&\quad + 2 (\nabla f_i(x^{k+1}) - \nabla f_i(x^k), (1 - \alpha)(\nabla f_i(x^k) - h_i^k)) \right] \\
&\leq \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} E_k \left[ \| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \|^2 + (1 - 2\alpha) \| \nabla f_i(x^k) - h_i^k \|^2 + \alpha^2 \| C_i^k (\overline{g}_i^k - h_i^k) \|^2 \\
&\quad + \beta \| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \|^2 + \frac{(1 - \alpha)^2}{\beta} \| \nabla f_i(x^k) - h_i^k \|^2 \right] \quad \forall \beta > 0 \\
&= \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} E_k \left[ (1 + \beta) \| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \|^2 + (1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta}) \| \nabla f_i(x^k) - h_i^k \|^2 \\
&\quad + \alpha^2 \| C_i^k (\overline{g}_i^k - h_i^k) \|^2 \right] \\
&\leq \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} E_k \left[ (1 + \beta) \| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \|^2 + (1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta}) \| \nabla f_i(x^k) - h_i^k \|^2 \\
&\quad + \alpha^2 (1 + \omega) \| \overline{g}_i^k - h_i^k \|^2 \right] \\
&= \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \| \nabla f_i(x^k) - h_i^k \|^2 \\
&\quad + \frac{\omega(1 + \beta)}{(1 + \omega)m} \sum_{i=1}^{m} E_k [\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \|^2] + \frac{\alpha^2 \omega}{m} \sum_{i=1}^{m} \| \overline{g}_i^k - \nabla f_i(x^k) \|^2] \\
&\leq \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \| \nabla f_i(x^k) - h_i^k \|^2 \\
&\quad + \frac{\omega(1 + \beta)}{(1 + \omega)m} \sum_{i=1}^{m} E_k [\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \|^2] + \alpha^2 \omega (2A(f(x^k) - f^*) + D_i \tilde{\sigma}_k^2 + C) \\
&\leq \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \| \nabla f_i(x^k) - h_i^k \|^2 \\
&\quad + \frac{\omega(1 + \beta)}{(1 + \omega)m} \sum_{i=1}^{m} L_i^2 \| x^{k+1} - x^k \|^2 + \alpha^2 \omega (2A(f(x^k) - f^*) + D_i \tilde{\sigma}_k^2 + C) \\
&= \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \| \nabla f_i(x^k) - h_i^k \|^2 \\
&\quad + \frac{\omega(1 + \beta)}{(1 + \omega)m} \sum_{i=1}^{m} L_i^2 \eta^2 \| \overline{g}_i^k \|^2 + \alpha^2 \omega (2A(f(x^k) - f^*) + D_i \tilde{\sigma}_k^2 + C) \\
\quad \tag{C.62}
\end{align*}
\]
\[
\begin{align*}
&\leq (1 - \rho')D_1'\sigma_k^2 + 2D_1'A'_2(f(x^k) - f^*) + D_1'B_2'\|\nabla f(x^k)\|^2 + D_1'D_2'E_k[\|g^k\|^2] + D_1'C_2' \\
&\quad + \left(1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2(1 + \omega)\right)\frac{\omega}{(1 + \omega)m}\sum_{i=1}^{m}\|\nabla f_i(x^k) - h_i^k\|^2 \\
&\quad + \frac{\omega(1 + \beta)}{(1 + \omega)m}\sum_{i=1}^{m}L_i^2\sigma_k^2E_k[\|g^k\|^2] + \alpha^2\omega\left(2A(f(x^k) - f^*) + D_1'C_2' + C\right) \\
&\quad = (1 - \rho' + \alpha^2\omega)D_1'\sigma_k^2 + 2(D_1'A'_2 + \alpha^2\omega A)(f(x^k) - f^*) + D_1'B_2'\|\nabla f(x^k)\|^2 + D_1'C_2' \\
&\quad + \alpha^2\omega C + \left(1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2(1 + \omega)\right)\frac{\omega}{(1 + \omega)m}\sum_{i=1}^{m}\|\nabla f_i(x^k) - h_i^k\|^2 \\
&\quad + B\|\nabla f(x^k)\|^2 + \frac{1 + \omega}{m}BA\left(f(x^k) - f^*\right) + \frac{1 + \omega}{m}B\left(D_1'\sigma_k^2 + \frac{\omega}{(1 + \omega)m}\sum_{i=1}^{m}\|\nabla f_i(x^k) - h_i^k\|^2\right) \\
&\quad + B\|\nabla f(x^k)\|^2 + \frac{1 + \omega}{m}BC \\
&\quad = (1 - \rho' + \alpha^2\omega)D_1'\sigma_k^2 + 2(D_1'A'_2 + \alpha^2\omega A)(f(x^k) - f^*) + (D_1'B_2' + B)\|\nabla f(x^k)\|^2 + D_1'C_2' \\
&\quad + \tau C + \left(1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 + \tau\right)\frac{\omega}{(1 + \omega)m}\sum_{i=1}^{m}\|\nabla f_i(x^k) - h_i^k\|^2 \\
&\quad \leq (1 - \rho)\sigma_k^2 + 2(D_1'A'_2 + \alpha^2\omega A)(f(x^k) - f^*) + (D_1'B_2' + B)\|\nabla f(x^k)\|^2 + D_1'C_2' + \tau C, \quad (C.63)
\end{align*}
\]

where (C.63) holds by defining \(B := \frac{\omega(1 + \beta)L^2\sigma_k^2}{1 + \omega} + D_1'D_2'\), (C.64) follows from (C.58), (C.65) holds by defining \(\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}\), and the last inequality holds by defining \(\rho := \min\{\rho' - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\}\).

Now, we have proved the second part, i.e., (C.51) holds with
\[
\rho = \min\{\rho' - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\}, \quad A_2 = D_1'A'_2 + \alpha^2\omega A, \quad B_2 = D_1'B_2' + B, \quad C_2 = D_1'C_2' + \tau C.
\]

\(\square\)

**Proof of Theorem 4.** Similar to the proof of Theorem 7, we know that gradient estimator \(g^k\) (see Line 7 of Algorithm 7) is unbiased, i.e.,

\[
\begin{align*}
\mathbb{E}_k[g^k] &= \mathbb{E}_k\left[h^k + \frac{1}{m}\sum_{i=1}^{m}\tilde{\Delta}_i^k\right] \\
&= \mathbb{E}_k\left[\frac{1}{m}\sum_{i=1}^{m}h_i^k + \frac{1}{m}\sum_{i=1}^{m}C_i^k(\tilde{g}_i^k - h_i^k)\right] \\
&= \mathbb{E}_k\left[\frac{1}{m}\sum_{i=1}^{m}h_i^k + \frac{1}{m}\sum_{i=1}^{m}(\tilde{g}_i^k - h_i^k)\right] \\
&= \mathbb{E}_k\left[\frac{1}{m}\sum_{i=1}^{m}\tilde{g}_i^k\right] = \nabla f(x^k) \quad (C.67)
\end{align*}
\]
Then, we prove the upper bound for the second moment of gradient estimator $g^k$:
\[
\mathbb{E}_k[\|g^k\|^2] = \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_{i=1}^m h_i^k + \frac{1}{m} \sum_{i=1}^m C_i^k (g_i^k - h_i^k) \right\|^2 \right]
\]
\[
= \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_{i=1}^m h_i^k + \frac{1}{m} \sum_{i=1}^m C_i^k (g_i^k - h_i^k) - \frac{1}{m} \sum_{i=1}^m g_i^k + \frac{1}{m} \sum_{i=1}^m \bar{g}_i^k \right\|^2 \right]
\]
\[
= \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_{i=1}^m \left( C_i^k (g_i^k - h_i^k) - \bar{g}_i^k + h_i^k \right) \right\|^2 \right] + \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_{i=1}^m \bar{g}_i^k \right\|^2 \right]
\]
\[
\leq \frac{\omega}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^m \left\| \bar{g}_i^k - h_i^k \right\|^2 \right] + \mathbb{E}_k \left[ \left\| \frac{1}{m} \sum_{i=1}^m \left( g_i^k - \nabla f_i(x^k) \right) + \frac{1}{m} \sum_{i=1}^m \nabla f_i(x^k) \right\|^2 \right]
\]
\[
= \frac{\omega}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^m \left\| \bar{g}_i^k - h_i^k \right\|^2 \right] + \frac{1}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^m \left\| \bar{g}_i^k - \nabla f_i(x^k) \right\|^2 \right] + \mathbb{E}_k \left[ \left\| \nabla f(x^k) \right\|^2 \right]
\]
\[
= \frac{1 + \omega}{m^2} \mathbb{E}_k \left[ \sum_{i=1}^m \left\| \bar{g}_i^k - \nabla f_i(x^k) \right\|^2 \right] + \frac{\omega}{m^2} \sum_{i=1}^m \left\| \nabla f_i(x^k) - h_i^k \right\|^2 + \mathbb{E}_k \left[ \left\| \nabla f(x^k) \right\|^2 \right]
\]
\[
\leq \frac{1 + \omega}{m^2} \sum_{i=1}^m \left( 2A_{1,i} (f_i(x^k) - f_i^*) + B_{1,i} \left\| \nabla f_i(x^k) \right\|^2 + D_{1,i} \sigma_{k,i}^2 + C_{1,i} - \left\| \nabla f_i(x^k) \right\|^2 \right)
\]
\[
+ \frac{\omega}{m^2} \sum_{i=1}^m \left\| \nabla f_i(x^k) - h_i^k \right\|^2 + \mathbb{E}_k \left[ \left\| \nabla f(x^k) \right\|^2 \right]
\]
\[
\leq \frac{1 + \omega}{m^2} \sum_{i=1}^m \left( 2A_{1,i} + (B_{1,i} - 1) L_i \right) (f_i(x^k) - f_i^*) + D_{1,i} \sigma_{k,i}^2 + C_{1,i}
\]
\[
+ \frac{\omega}{m^2} \sum_{i=1}^m \left\| \nabla f_i(x^k) - h_i^k \right\|^2 + \mathbb{E}_k \left[ \left\| \nabla f(x^k) \right\|^2 \right]
\]
\[
\leq \frac{2(1 + \omega) A}{m^2} \sum_{i=1}^m (f_i(x^k) - f_i^*) + \frac{1 + \omega}{m^2} \sum_{i=1}^m D_{1,i} \sigma_{k,i}^2 + \frac{1 + \omega}{m^2} \sum_{i=1}^m C_{1,i}
\]
\[
+ \frac{\omega}{m^2} \sum_{i=1}^m \left\| \nabla f_i(x^k) - h_i^k \right\|^2 + \mathbb{E}_k \left[ \left\| \nabla f(x^k) \right\|^2 \right]
\]
\[
= \frac{2(1 + \omega) A}{m} (f(x^k) - f^*) + \frac{1 + \omega}{m} \left( \frac{1}{m} \sum_{i=1}^m D_{1,i} \sigma_{k,i}^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \right)
\]
\[
+ \left\| \nabla f(x^k) \right\|^2 + \frac{(1 + \omega) C}{m},
\]
where (C.68) holds by defining $A := \max_i (A_{1,i} + (B_{1,i} - 1) L_i)$, and (C.69) holds by defining $C := \frac{1}{m} \sum_{i=1}^m C_{1,i} +$
Now we prove the second part (i.e., (C.54)) holds with
\[
A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},
\]
\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{1}{m} \sum_{i=1}^m D_{1,i} \sigma_{k,i}^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^k) - h_i^k\|^2.
\]
(C.70)
(C.71)

Now we prove the second part (i.e., (C.55)). According to (C.53), we have
\[
E_k \left[ \frac{1}{m} \sum_{i=1}^m D_{1,i} \sigma_{k+1,i}^2 \right] \leq \frac{1}{m} \sum_{i=1}^m D_{1,i} \left( (1 - \rho_i) \sigma_{k,i}^2 + 2A_{2,i}(f(x^k) - f^*) + B_{2,i}\|\nabla f(x^k)\|^2 + D_{2,i} \mathbb{E}_k[\|g_i\|^2] + C_{2,i} \right) \leq \frac{1}{m} \sum_{i=1}^m (1 - \rho_i) D_{1,i} \sigma_{k,i}^2 + 2D_A(f(x^k) - f^*) + D_B\|\nabla f(x^k)\|^2 + D_D \mathbb{E}_k[\|g_i\|^2] + D_C,
\]
(C.72)
(C.73)

where the last equality holds by defining \( D_A := \frac{1}{m} \sum_{i=1}^m D_{1,i}A_{2,i}, D_B := \frac{1}{m} \sum_{i=1}^m D_{1,i}B_{2,i}, D_D := \frac{1}{m} \sum_{i=1}^m D_{1,i}D_{2,i}, \) and \( D_C := \frac{1}{m} \sum_{i=1}^m D_{1,i}C_{2,i}. \)

For the second term of \( \sigma_{k+1,i}^2, \) we bound it as follows:
\[
E_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^{k+1}) - h_i^{k+1}\|^2 \right] = E_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^{k+1}) - \nabla f_i(x^k) + \nabla f_i(x^k) - h_i^{k+1}\|^2 \right] = E_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^{k+1}) - \nabla f_i(x^k) + \nabla f_i(x^k) - h_i^k - \alpha C_i^k(g_i^k - h_i^k)\|^2 \right] = E_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \left[ \|\nabla f_i(x^{k+1}) - \nabla f_i(x^k)\|^2 + \|\nabla f_i(x^k) - h_i^k - \alpha C_i^k(g_i^k - h_i^k)\|^2 \right. \right.
\]
\[
+ 2(\nabla f_i(x^{k+1}) - \nabla f_i(x^k), \nabla f_i(x^k) - h_i^k - \alpha C_i^k(g_i^k - h_i^k)) \right] \leq E_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \left[ \|\nabla f_i(x^{k+1}) - \nabla f_i(x^k)\|^2 + (1 - 2\alpha)\|\nabla f_i(x^k) - h_i^k\|^2 + 2\|C_i^k(g_i^k - h_i^k)\|^2 \right. \right.
\]
\[
+ 2(\nabla f_i(x^{k+1}) - \nabla f_i(x^k), (1 - \alpha)(\nabla f_i(x^k) - h_i^k)) \right] \leq E_k \left[ \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \left[ \|\nabla f_i(x^{k+1}) - \nabla f_i(x^k)\|^2 + (1 - 2\alpha)\|\nabla f_i(x^k) - h_i^k\|^2 + 2\|C_i^k(g_i^k - h_i^k)\|^2 \right. \right.
\]
\[
+ \beta\|\nabla f_i(x^{k+1}) - \nabla f_i(x^k)\|^2 + \frac{(1 - \alpha)^2}{\beta} \|\nabla f_i(x^k) - h_i^k\|^2 \right] \vee \beta > 0
\]
\[
\omega (1 + \omega) m \sum_{i=1}^{m} E_k \left[ (1 + \beta) \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \right\|^2 + (1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta}) \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \\
+ \alpha^2 \left\| C_i^k (\bar{g}_i^k - h_i^k) \right\|^2 \right]
\]

\[
\leq \omega (1 + \omega) \sum_{i=1}^{m} E_k \left[ (1 + \beta) \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \right\|^2 + (1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta}) \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \\
+ \alpha^2 (1 + \omega) \left\| g_i^k - h_i^k \right\|^2 \right]
\]

\[
= \frac{\omega}{(1 + \omega)m} m \sum_{i=1}^{m} E_k \left[ (1 + \beta) \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \right\|^2 + (1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta}) \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \\
+ \alpha^2 (1 + \omega) \left\| g_i^k - h_i^k \right\|^2 \right]
\]

\[
= \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} m \sum_{i=1}^{m} \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \\
+ \omega (1 + \beta) (1 + \omega) m \sum_{i=1}^{m} E_k \left[ \left\| \nabla f_i(x^{k+1}) - \nabla f_i(x^k) \right\|^2 \right] + \alpha^2 \omega (1 + \omega) m \sum_{i=1}^{m} \left\| g_i^k - \nabla f_i(x^k) \right\|^2 \\
\leq \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} m \sum_{i=1}^{m} \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \\
+ \omega (1 + \beta) (1 + \omega) m \sum_{i=1}^{m} L_i^2 \left[ \left\| x^{k+1} - x^k \right\|^2 \right] \\
+ \alpha^2 \omega \left( 2A(f(x^k) - f^*) + \frac{1}{m} \sum_{i=1}^{m} D_{1,i}\sigma_i^2 + C \right) \\
= \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} m \sum_{i=1}^{m} \left\| \nabla f_i(x^k) - h_i^k \right\|^2 \\
+ \omega (1 + \beta) (1 + \omega) m \sum_{i=1}^{m} L_i^2 \eta^2 \left[ \left\| g^k \right\|^2 \right] + \alpha^2 \omega \left( 2A(f(x^k) - f^*) + \frac{1}{m} \sum_{i=1}^{m} D_{1,i}\sigma_i^2 + C \right). \tag{C.74}
\]

By combining (C.73) and (C.74), we have

\[
E_k[\sigma_{k+1}^2] \leq E_k \left[ \frac{1}{m} \sum_{i=1}^{m} D_{1,i}\sigma_i^2 + \frac{\omega}{(1 + \omega)m} m \sum_{i=1}^{m} \left\| \nabla f_i(x^{k+1}) - h_i^{k+1} \right\|^2 \right]
\]

56
\[ \leq \frac{1}{m} \sum_{i=1}^{m} (1 - \rho_i)D_1, \sigma_i^2 + 2D_A(f(x^k) - f^*) + D_B \|\nabla f(x^k)\|^2 + D_D E_k[\|g^k\|^2] + D_C \\
+ \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_i^k\|^2 \\
+ \frac{\omega(1 + \beta)}{(1 + \omega)m} \sum_{i=1}^{m} L_i^2 \eta^2 E_k[\|g^k\|^2] + \alpha^2 \omega \left( 2A(f(x^k) - f^*) + \frac{1}{m} \sum_{i=1}^{m} D_1, \sigma_i^2 + C \right) \\
= \frac{1}{m} \sum_{i=1}^{m} (1 - \rho_i + \alpha^2 \omega)D_1, \sigma_i^2 + 2(D_A + \alpha^2 \omega A)(f(x^k) - f^*) + D_B \|\nabla f(x^k)\|^2 + D_C \\
+ \alpha^2 \omega C + \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 (1 + \omega) \right) \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_i^k\|^2 \\
+ \frac{2(1 + \omega)BA}{m} (f(x^k) - f^*) \\
+ \frac{1 + \omega}{m} \left( \frac{1}{m} \sum_{i=1}^{m} D_1, \sigma_i^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_i^k\|^2 \right) \\
+ B \|\nabla f(x^k)\|^2 + \frac{(1 + \omega)BC}{m} \tag{C.75} \]

\[ \leq \frac{1}{m} \sum_{i=1}^{m} (1 - \rho_i + \tau)D_1, \sigma_i^2 + 2(D_A + \tau A)(f(x^k) - f^*) + (D_B + B) \|\nabla f(x^k)\|^2 + D_C \\
+ \tau C + \left( 1 - 2\alpha + \frac{(1 - \alpha)^2}{\beta} + \alpha^2 + \tau \right) \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_i^k\|^2 \tag{C.77} \]

where (C.75) holds by defining \( B := \frac{\omega(1 + \beta)L_i^2 \eta^2}{1 + \omega} \), (C.76) follows from (C.69), (C.77) holds by defining \( \tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m} \), and the last inequality holds by defining \( \rho := \min\{\min_i \rho_i - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\} \).

Now, we have proved the second part, i.e., (C.55) holds with

\[ \rho = \min\{\min_i \rho_i - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\}, \]

\[ A_2 = D_A + \tau A, \quad B_2 = D_B + B, \quad C_2 = D_C + \tau C. \]

\[ \square \]

In the following sections, we prove that if the parallel workers use some specific methods, i.e., GD, SGD, L-SVRG and SAGA, for computing their local stochastic gradient \( \tilde{g}_i^k \) (see Line 3 of Algorithm 7), then \( g^k \) (see Line 7 of Algorithm 7) satisfies the unified Assumption 1. Then, we plug their corresponding parameters (i.e., specific values for \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \)) into our unified Theorem 1 to obtain the detailed convergence rates for these methods.
C.2.1 DIANA-GD method

In this section, we show that if the parallel workers use GD for computing their local gradient \( \tilde{g}_i^k \), then \( g^k \) (see Line 7 of Algorithm 12) satisfies the unified Assumption 1.

**Algorithm 12 DIANA-GD**

**Input:** initial point \( x^0 \), \( \{h_i^0\}_{i=1}^m \), \( h^0 = \frac{1}{m} \sum_{i=1}^m h_i^0 \), parameters \( \eta_k, \alpha_k \)

1: for \( k = 0, 1, 2, \ldots \) do
2: for all machines \( i = 1, 2, \ldots, m \) do in parallel
3: Compute local gradient \( \tilde{g}_i^k = \nabla f_i(x^k) \)
4: Compress shifted local gradient \( \Delta_i^k = C_i^k (\tilde{g}_i^k - h_i^k) \) and send \( \Delta_i^k \) to the server
5: Update local shift \( h_i^{k+1} = h_i^k + \alpha_k C_i^k (\tilde{g}_i^k - h_i^k) \)
6: end for
7: Aggregate received compressed gradient information \( g^k = h^k + \frac{1}{m} \sum_{i=1}^m \Delta_i^k \)
8: \( x^{k+1} = x^k - \eta_k g^k \)
9: \( h^{k+1} = h^k + \alpha_k \frac{1}{m} \sum_{i=1}^m \Delta_i^k \)
10: end for

**Lemma 9 (DIANA-GD)** Let the local gradient estimator \( \tilde{g}_i^k = \nabla f_i(x^k) \) (see Line 3 of Algorithm 12), then we know that \( \tilde{g}_i^k \) satisfies (C.48) and (C.49) with \( B_{1,i} = 1, A_{1,i} = C_{1,i} = D'_1 = 0, \sigma_i^2 \equiv 0, \rho = 1, A'_2 = B'_2 = C'_2 = D'_2 = 0 \). Thus, according to Theorem 7, \( g^k \) (see Line 7 of Algorithm 12) satisfies the unified Assumption 1 with

\[
A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,
\]

\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^k) - h_i^k\|^2,
\]

\[
\rho = \min\{1 - \tau, 2 \alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\},
\]

\[
A_2 = 0, \quad B_2 = B, \quad C_2 = 0,
\]

where \( B := \frac{\omega(1 + \beta)L^2n^2}{1 + \omega}, \tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}, \) and \( \forall \beta > 0 \).

**Proof of Lemma 9.** If the local gradient estimator \( \tilde{g}_i^k = \nabla f_i(x^k) \) (see Line 3 of Algorithm 12), it is easy to see that

\[
\mathbb{E}_k[\tilde{g}_i^k] = \nabla f_i(x^k)
\]

and

\[
\mathbb{E}_k[\|\tilde{g}_i^k\|^2] \leq \|\nabla f_i(x^k)\|^2
\]

since there is no randomness. Thus the local gradient estimator \( \tilde{g}_i^k \) satisfies (C.48) and (C.49) with

\[
A_{1,i} = C_{1,i} = D'_1 = 0, B_{1,i} = 1, \sigma_i^2 \equiv 0, \rho = 1, A'_2 = B'_2 = C'_2 = D'_2 = 0.
\]

Then, according to Theorem 7, \( g^k \) (see Line 7 of Algorithm 12) satisfies the unified Assumption 1 with

\[
A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,
\]

\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^k) - h_i^k\|^2,
\]

\[
\rho = \min\{1 - \tau, 2 \alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\},
\]

\[
A_2 = 0, \quad B_2 = B, \quad C_2 = 0,
\]

where \( B := \frac{\omega(1 + \beta)L^2n^2}{1 + \omega}, \tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}, \) and \( \forall \beta > 0 \). \(\square\)
Corollary 9 (DIANA-GD) Suppose that Assumption 5 holds. Let stepsize \( \eta \leq \frac{1}{L + L(1 + \omega)Bm^{-1} \rho} \), then the number of iterations performed by DIANA-GD (Algorithm 12) to find an \( \epsilon \)-solution of nonconvex federated problem (1.1), i.e. a point \( \tilde{x} \) such that \( \mathbb{E}[\|\nabla f(\tilde{x})\|] \leq \epsilon \), can be bounded by

\[
K = \frac{8\Delta_0 L}{\epsilon^2} \left( 1 + \frac{(1 + \omega)B}{m \rho} \right),
\]

where \( B := \frac{\omega(1 + \beta)L^2 \eta^2}{1 + \omega} \), \( \rho := \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\} \), \( \tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m} \), and \( \forall \beta > 0 \).

Proof of Corollary 9. According to our unified Theorem 1, if the stepsize is chosen as

\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}, \frac{\epsilon^2}{2L(C_1 + D_1 C_2 \rho^{-1})} \right\}
\]

\[
= \frac{1}{L + L(1 + \omega)Bm^{-1} \rho^{-1}}
\]

since \( B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = B, B = \frac{\omega(1 + \beta)L^2 \eta^2}{1 + \omega} \) and \( A_1 = A_2 = C_1 = C_2 = 0 \) according to Lemma 9, then the number of iterations performed by DIANA-GD (Algorithm 12) to find an \( \epsilon \)-solution of problem (1.1) can be bounded by

\[
K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ B_1 + D_1 B_2 \rho^{-1}, \frac{12\Delta_0 (A_1 + D_1 A_2 \rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1 C_2 \rho^{-1})}{\epsilon^2} \right\}
\]

\[
= \frac{8\Delta_0 L}{\epsilon^2} \left( 1 + \frac{(1 + \omega)B}{m \rho} \right)
\]

since \( B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = B, B = \frac{\omega(1 + \beta)L^2 \eta^2}{1 + \omega}, A_1 = A_2 = C_1 = C_2 = 0 \) and \( \Delta_0 := f(x^0) - f^* + 2^{-1}L\eta^2 D_1 \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0 \) by letting \( \sigma_0^2 = \frac{1}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^0) - h^0\|^2 = 0. \)

C.2.2 DIANA-SGD method

In this section, we show that if the parallel workers use SGD for computing their local stochastic gradient \( \bar{g}_i^k \), then \( g^k \) (see Line 7 of Algorithm 13) satisfies the unified Assumption 1.

Algorithm 13 DIANA-SGD

Input: initial point \( x^0, \{h_i^0\}_{i=1}^m \), \( h^0 = \frac{1}{m} \sum_{i=1}^m h_i^0 \), parameters \( \eta_k, \alpha_k \)

1: for \( k = 0, 1, 2, \ldots \) do
2: \hspace{1cm} for all machines \( i = 1, 2, \ldots, m \) do in parallel
3: \hspace{2cm} Compute local stochastic gradient \( \bar{g}_i^k \) with Algorithm 3 by changing \( f(x) \) to the local \( f_i(x) \)
4: \hspace{2cm} Compress shifted local gradient \( \hat{\Delta}_i^k = C_i^k(\bar{g}_i^k - h_i^k) \) and send \( \hat{\Delta}_i^k \) to the server
5: \hspace{2cm} Update local shift \( h_i^{k+1} = h_i^k + \alpha_k C_i^k(\bar{g}_i^k - h_i^k) \)
6: \hspace{1cm} end for
7: \hspace{1cm} Aggregate received compressed gradient information \( g^k = h^k + \frac{1}{m} \sum_{i=1}^m \hat{\Delta}_i^k \)
8: \hspace{1cm} \( x^{k+1} = x^k - \eta_k g^k \)
9: \hspace{1cm} \( h^{k+1} = h^k + \alpha_k \frac{1}{m} \sum_{i=1}^m \hat{\Delta}_i^k \)
10: end for

Lemma 10 (DIANA-SGD) Let the local stochastic gradient estimator \( \bar{g}_i^k \) (see Line 3 of Algorithm 13) satisfy Assumption 9, i.e.,

\[
\mathbb{E}_k[\|\bar{g}_i^k\|^2] \leq 2A_{1,i}(f_i(x^k) - f_i^*) + B_{1,i}\|\nabla f_i(x^k)\|^2 + C_{1,i},
\]
then we know that $\tilde{g}_1^k$ satisfies (C.48) and (C.49) with $D_1' = 0, \sigma_k^2 \equiv 0, \rho' = 1, A_2' = B_2' = C_2' = D_2' = 0$. Thus, according to Theorem 7, $g^k$ (see Line 7 of Algorithm 13) satisfies the unified Assumption 1 with

$$A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},$$

$$D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_k^i\|^2,$$

$$\rho = \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\},$$

$$A_2 = \tau A, \quad B_2 = B, \quad C_2 = \tau C,$$

where $A := \max_i(A_{1,i} + (B_{1,i} - 1)L_i), B := \frac{\omega(1 + \beta)L^2\eta^2}{1 + \omega}, C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A\Delta_f^\star, \Delta_f^\star := f^\star - \frac{1}{m} \sum_{i=1}^{m} f_i^\star$, $\tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}$, and $\forall \beta > 0$.

**Proof of Lemma 10.** Suppose that the local stochastic gradient estimator $g_1^k$ (see Line 3 of Algorithm 13) satisfies Assumption 9, i.e.,

$$E_k[\tilde{g}_1^k] = \nabla f_i(x^k)$$

and

$$E_k[\|\tilde{g}_1^k\|^2] \leq 2A_1,i(f_i(x^k) - f_i^\star) + B_1,i\|\nabla f_i(x^k)\|^2 + C_{1,i},$$

Thus the local stochastic gradient estimator $g_1^k$ satisfies (C.48) and (C.49) with

$$A_{1,i} = A_{1,i}, B_{1,i} = B_{1,i}, C_{1,i} = C_{1,i}, D_1' = 0, \sigma_k^2 \equiv 0, \rho' = 1, A_2' = B_2' = C_2' = D_2' = 0.$$  

Then, according to Theorem 7, $g^k$ (see Line 7 of Algorithm 13) satisfies the unified Assumption 1 with

$$A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},$$

$$D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_k^i\|^2,$$

$$\rho = \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\},$$

$$A_2 = \tau A, \quad B_2 = B, \quad C_2 = \tau C,$$

where $A := \max_i(A_{1,i} + (B_{1,i} - 1)L_i), B := \frac{\omega(1 + \beta)L^2\eta^2}{1 + \omega}, C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A\Delta_f^\star, \Delta_f^\star := f^\star - \frac{1}{m} \sum_{i=1}^{m} f_i^\star$, $\tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}$, and $\forall \beta > 0$. \hfill \Box

**Corollary 10 (DIANA-SGD)** Suppose that Assumption 5 holds. Let stepsize

$$\eta \leq \min \left\{ \frac{1}{L + L(1 + \omega)Bm^{-1}\rho^{-1}}, \sqrt{\frac{m \ln 2}{(1 + \omega)(1 + \tau \rho^{-1})LAK}}, \frac{me^2}{2(1 + \omega)(1 + \tau \rho^{-1})LC} \right\},$$

then the number of iterations performed by DIANA-SGD (Algorithm 13) to find an $\epsilon$-solution of nonconvex federated problem (1.1) with (1.2) or (1.3), i.e. a point $\tilde{x}$ such that $E[\|\nabla f(\tilde{x})\|] \leq \epsilon$, can be bounded by

$$K = \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ 1 + \frac{(1 + \omega)B}{m\rho}, \frac{12(1 + \omega)(1 + \tau \rho^{-1})\Delta_0 A}{me^2}, \frac{2(1 + \omega)(1 + \tau \rho^{-1})LC}{me^2} \right\},$$

where $A := \max_i(A_{1,i} + (B_{1,i} - 1)L_i), B := \frac{\omega(1 + \beta)L^2\eta^2}{1 + \omega}, C := \frac{1}{m} \sum_{i=1}^{m} C_{1,i} + 2A\Delta_f^\star, \Delta_f^\star := f^\star - \frac{1}{m} \sum_{i=1}^{m} f_i^\star$, $\rho := \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\}, \tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}$, and $\forall \beta > 0$. 

60
Proof of Corollary 10. According to our unified Theorem 1, if the stepsize is chosen as
\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1B_2\rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1A_2\rho^{-1})K}}, \frac{\epsilon^2}{2L(C_1 + D_1C_2\rho^{-1})} \right\}
\]
\[
= \min \left\{ \frac{1}{L + L(1 + \omega)Bm^{-1}\rho^{-1}}, \sqrt{\frac{m\ln 2}{(1 + \omega)(1 + \tau\rho^{-1})LAK}}, \frac{\rho^{-1}}{2(1 + \omega)(1 + \tau\rho^{-1})LC} \right\}
\]
since \(B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = B, B = \frac{\omega(1 + \beta)LD^2\eta^2}{1 + \omega^2}, A_1 = \frac{(1 + \omega)A}{m}, A_2 = \tau A, C_1 = \frac{(1 + \omega)C}{m}, \) and \(C_2 = \tau C\)
according to Lemma 10, then the number of iterations performed by DIANA-SGD (Algorithm 13) to find an \(\epsilon\)-solution of problem (1.1) with (1.2) or (1.3) can be bounded by
\[
K = \frac{8\Delta'\eta L}{\epsilon^2} \max \left\{ B_1 + D_1B_2\rho^{-1}, \frac{12\Delta'\eta(A_1 + D_1A_2\rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1C_2\rho^{-1})}{\epsilon^2} \right\}
\]
\[
= \frac{8\Delta_0 L}{\epsilon^2} \max \left\{ 1 + \frac{(1 + \omega)B}{m\rho}, \frac{12(1 + \omega)(1 + \tau\rho^{-1})\Delta_0\omega}{m\rho^2}, \frac{2(1 + \omega)(1 + \tau\rho^{-1})L\omega}{m\rho^2} \right\}
\]
(C.83)
since \(B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = B, B = \frac{\omega(1 + \beta)LD^2\eta^2}{1 + \omega^2}, A_1 = \frac{(1 + \omega)A}{m}, A_2 = \tau A, C_1 = \frac{(1 + \omega)C}{m}, C_2 = \tau C\) and \(\Delta' = f(x^0) - f^* + 2^{-1}\eta^2 D_1\rho^{-1}\sigma_0^2 = f(x^0) - f^* = \Delta_0\) by letting \(\sigma_0^2 = \frac{\eta^2}{(1 + \omega)m} \sum\limits_{i=1}^m \|\nabla f_i(x^0) - h^0\|^2 = 0. \]

C.2.3 DIANA-LSVRG method

In this section, we show that if the parallel workers use L-SVRG for computing their local gradient \(\tilde{g}_i^k\), then \(g^k\) (see Line 8 of Algorithm 14) satisfies the unified Assumption 1.

Algorithm 14 DIANA-LSVRG

Input: initial point \(x^0 = u^0, \{h_i^0\}_{i=1}^m, h^0 = \frac{1}{m} \sum\limits_{i=1}^m h_i^0\), parameters \(b, \eta_k, \alpha_k\), probability \(p \in (0, 1]\)
1. for \(k = 0, 1, 2, \ldots \) do
2. for all machines \(i = 1, 2, \ldots, m\) do in parallel
3. Compute local stochastic gradient \(g_i^k = \frac{1}{b} \sum\limits_{j \in I_i} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k)\)
4. Compress shifted local gradient \(\hat{\Delta}_i^k = c_i^k(\tilde{g}_i^k - h_i^k)\) and send \(\hat{\Delta}_i^k\) to the server
5. Update local shift \(h_i^{k+1} = h_i^k + \alpha_k c_i^k(\tilde{g}_i^k - h_i^k)\)
6. \(u_i^{k+1} = \begin{cases} x_i^k, & \text{with probability } p \\ \ \  \\
 u_i^k, & \text{with probability } 1 - p \end{cases}\)
7. end for
8. Aggregate received compressed gradient information \(g^k = h^k + \frac{1}{m} \sum\limits_{i=1}^m \hat{\Delta}_i^k\)
9. \(x^{k+1} = x^k - \eta_k g^k\)
10. \(h^{k+1} = h^k + \alpha_k \frac{1}{m} \sum\limits_{i=1}^m \hat{\Delta}_i^k\)
11. end for

Lemma 11 (DIANA-LSVRG) Let the local stochastic gradient estimator \(\tilde{g}_i^k = \frac{1}{b} \sum\limits_{j \in I_i} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k)\) (see Line 3 of Algorithm 14), then we know that \(\tilde{g}_i^k\) satisfies (C.48) and (C.49) with \(A_{1,i} = 0, B_{1,i} = 1, C_{1,i} = 0, D_{1,i}' = \frac{L}{b}, \sigma_i^2 = \|x^k - w^k\|^2, \rho' = p + p\gamma - \gamma, A_{1,i}' = 0, B_{2,i}' = (1 - p)\eta^2\gamma^{-1}, C_{1,i}' = 0, D_{2,i}' = \eta^2\), and \(\forall \gamma > 0\). Thus, according to Theorem 7, \(g^k\) (see Line 8 of Algorithm 14) satisfies the unified
Assumption 1 with
\[
A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,
\]
\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma^2 = \frac{\bar{L}^2}{b} \|x^k - w^k\|^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_i^k\|^2,
\]
\[
\rho = \min\{p + p\gamma - \gamma - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\},
\]
\[
A_2 = 0 \quad B_2 = (1 - p)\bar{L}^2\eta^2\gamma^{-1}b^{-1} + B, \quad C_2 = 0,
\]
where \(B := \frac{\omega(1 + \beta)\bar{L}^2\eta^2}{1 + \omega} + \bar{L}^2\eta^2b^{-1}\), \(\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}\), and \(\forall \gamma, \beta > 0\).

**Proof of Lemma 11.** If the local stochastic gradient estimator \(\tilde{g}_i^k = \frac{1}{b} \sum_{j \in I_i} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k)\) (see Line 3 of Algorithm 14), we show the following equations:

\[
\mathbb{E}_k[\tilde{g}_i^k] = \mathbb{E}_k \left[ \frac{1}{b} \sum_{j \in I_i} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k) \right] = \nabla f_i(x^k) - \nabla f_i(w^k) + \nabla f_i(w^k) = \nabla f_i(x^k) \quad (C.84)
\]

and

\[
\mathbb{E}_k[\|\tilde{g}_i^k\|^2] = \mathbb{E}_k \left[ \|\tilde{g}_i^k - \nabla f_i(x^k)\|^2 \right] + \|\nabla f_i(x^k)\|^2 \\
= \mathbb{E}_k \left[ \left\| \frac{1}{b} \sum_{j \in I_i} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) + \nabla f_i(w^k) - \nabla f_i(x^k) \right\|^2 \right] + \|\nabla f_i(x^k)\|^2 \\
= \frac{1}{b^2} \mathbb{E}_k \left[ \left\| \sum_{j \in I_i} ((\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)) - (\nabla f_i(x^k) - \nabla f_i(w^k))) \right\|^2 \right] + \|\nabla f_i(x^k)\|^2 \\
\leq \frac{1}{b^2} \mathbb{E}_k \left[ \|\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w^k)\|^2 + \|\nabla f_i(x^k)\|^2 \right] \\
\leq \frac{\bar{L}^2}{b} \|x^k - w^k\|^2 + \|\nabla f_i(x^k)\|^2, \quad (C.85)
\]

where (C.85) uses the fact \(\mathbb{E}[\|x - \mathbb{E}[x]\|^2] \leq \mathbb{E}[\|x\|^2]\), and the last inequality uses Assumption 6 (i.e., (2.5)).

Now, we define \(\tilde{\sigma}_k^2 := \|x^k - w^k\|^2\) and obtain

\[
\mathbb{E}_k[\sigma_{k+1}^2] \\
= \mathbb{E}_k[\|x^{k+1} - w^{k+1}\|^2] \\
= p\mathbb{E}_k[\|x^{k+1} - x^k\|^2] + (1 - p)\mathbb{E}_k[\|x^{k+1} - w^k\|^2] \\
= pn^2\mathbb{E}_k[\|g^k\|^2] + (1 - p)\mathbb{E}_k[\|x^k - \eta g^k - w^k\|^2] \\
= pn^2\mathbb{E}_k[\|g^k\|^2] + (1 - p)\mathbb{E}_k[\|x^k - w^k\|^2 + \|\eta g^k\|^2 - 2(x^k - w^k, \eta g^k)] \\
= pn^2\mathbb{E}_k[\|g^k\|^2] + (1 - p)\|x^k - w^k\|^2 + (1 - p)\eta^2\mathbb{E}_k[\|g^k\|^2] - 2(1 - p)(x^k - w^k, \eta \nabla f(x^k)) \\
\leq \eta^2\mathbb{E}_k[\|g^k\|^2] + (1 - p)\|x^k - w^k\|^2 + (1 - p)\gamma\|x^k - w^k\|^2 + \frac{1 - p}{\gamma} \|\eta \nabla f(x^k)\|^2 \\
\leq \eta^2\mathbb{E}_k[\|g^k\|^2] + (1 - p)(1 + \gamma)\|x^k - w^k\|^2 + \frac{(1 - p)\eta^2}{\gamma} \|\nabla f(x^k)\|^2 \\
= (1 - (p + p\gamma - \gamma))\tilde{\sigma}_k^2 + \frac{(1 - p)\eta^2}{\gamma} \|\nabla f(x^k)\|^2 + \eta^2\mathbb{E}_k[\|g^k\|^2], \quad (C.90)
\]

62
where (C.87) uses Line 6 of Algorithm 14, (C.88) uses Line 9 of Algorithm 14, (C.89) uses Young’s inequality for $\forall \gamma > 0$, and (C.90) follows from the definition $\bar{\sigma}^2_k := ||x^k - w^k||^2$.

Now, according to (C.86) and (C.90), we know the local stochastic gradient estimator $\tilde{g}^k_i$ (see Line 3 of Algorithm 14) satisfies (C.48) and (C.49) with

$$A_1, i = 0, \quad B_1, i = 1, \quad D'_i = \frac{L^2}{b}, \quad \bar{\sigma}^2_k = ||x^k - w^k||^2, \quad C_1, i = 0,$$

$$\rho' = p + pr - \gamma, \quad A'_2 = 0, \quad B'_2 = (1 - p)\eta^2_1, \quad D'_2 = \eta^2, \quad C'_2 = 0, \quad \forall \gamma > 0.$$

Thus, according to Theorem 7, $g^k$ (see Line 8 of Algorithm 14) satisfies the unified Assumption 1 with

$$A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,$$

$$D_1 = \frac{1 + \omega}{m}, \quad \sigma^2_k = \frac{L^2}{b}||x^k - w^k||^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m}||\nabla f_i(x^k) - h^k_i||^2,$$

$$\rho = \min\{p + pr - \gamma - \tau, \quad 2\alpha - (1 - \alpha)\beta - \alpha^2 - \tau\}, \quad A_2 = 0, \quad B_2 = (1 - p)\bar{L}^2\eta^2\gamma^{-1}b^{-1} + B, \quad C_2 = 0,$$

where $B := \frac{\omega(1 + \alpha)\bar{L}^2\eta^2}{1 + \omega} + \bar{L}^2\eta^2b^{-1}$, $\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}$, and $\forall \gamma, \beta > 0$.

**Corollary 11 (DIANA-LSVRG)** Suppose that Assumption 5 and 6 hold. Let stepsize

$$\eta \leq \frac{1}{L + \ell(1 + \omega)B'm^{-1}b^{-1}\rho^{-1}},$$

then the number of iterations performed by DIANA-LSVRG (Algorithm 14) to find an $\epsilon$-solution of nonconvex federated problem (1.1) with (1.3), i.e. a point $\hat{x}$ such that $\mathbb{E}[||\nabla f(\hat{x})||] \leq \epsilon$, can be bounded by

$$K = \frac{8\Delta_0\bar{L}}{\epsilon^2} \left(1 + \frac{(1 + \omega)\rho'}{\ell\beta}\right),$$

where $B' := (1 - p)\bar{L}^2\eta^2\gamma^{-1} + Bb$, $\rho := \min\{p + pr - \gamma - \tau, \quad 2\alpha - (1 - \alpha)\beta - \alpha^2 - \tau\}$, $\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}$, $B := \frac{\omega(1 + \beta)\bar{L}^2\eta^2}{1 + \omega} + \bar{L}^2\eta^2b^{-1}$, and $\forall \gamma, \beta > 0$.

**Proof of Corollary 11.** According to our unified Theorem 1, if the stepsize is chosen as

$$\eta \leq \min\left\{\frac{1}{LB_1 + LD_1B_2\rho^{-1}}, \sqrt{\frac{\ln 2}{(LA_1 + LD_1A_2\rho^{-1})K}}, \frac{\ell^2}{2L(C_1 + D_1C_2\rho^{-1})}\right\}$$

$$= \frac{1}{L + \ell(1 + \omega)B'm^{-1}b^{-1}\rho^{-1}}$$

(C.92)

since $B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = \frac{B'}{b}, B' = (1 - p)\bar{L}^2\eta^2\gamma^{-1} + Bb$ and $A_1 = A_2 = C_1 = C_2 = 0$ according to Lemma 11, then the number of iterations performed by DIANA-LSVRG (Algorithm 14) to find an $\epsilon$-solution of problem (1.1) with (1.3) can be bounded by

$$K = \frac{8\Delta'_0\bar{L}}{\epsilon^2} \max\left\{B_1 + D_1B_2\rho^{-1}, \frac{12\Delta'_0(A_1 + D_1A_2\rho^{-1})}{\epsilon^2}, \frac{2(C_1 + D_1C_2\rho^{-1})}{\epsilon^2}\right\}$$

$$= \frac{8\Delta'_0\bar{L}}{\epsilon^2} \left(1 + \frac{(1 + \omega)\rho'}{mb}\right)$$

(C.93)

since $B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = \frac{B'}{b}, B' = (1 - p)\bar{L}^2\eta^2\gamma^{-1} + Bb, A_1 = A_2 = C_1 = C_2 = 0$ and $\Delta'_0 := f(x^0) - f^* + 2\gamma D_1\rho^{-1}\sigma^2_0 = f(x^0) - f^* = \Delta_0$ by letting $\sigma^2_0 = \frac{\omega(1 + \omega)}{m} \sum_{i=1}^{m}||\nabla f_i(x^0) - h^0||^2 = 0$. □
In this section, we show that if the parallel workers use SAGA for computing their local gradient $\tilde{g}_i^k$, then $g^k$ (see Line 8 of Algorithm 15) satisfies the unified Assumption 1.

Theorem 4. Let $A_1, A_2, B_1, B_2, C_1, C_2, D_1, D_2, \rho, \beta, L, m, n, p, q > 0$, and $\forall \gamma > 0$. Thus, according to Theorem 4, $g^k$ (see Line 8 of Algorithm 15) satisfies the unified Assumption 1 with

$$A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,$$

$$D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{1}{m} \sum_{i=1}^{m} \sum_{j=1}^{m} \frac{L^2}{b} \|x^k - w_{i,j}^k\|^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|f_i(x^k) - h^k\|^2,$$

$$\rho = \min \left\{ \frac{b}{n} + \frac{b}{n} \gamma - \gamma - \tau, \ 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau \right\},$$

$$A_2 = 0, \quad B_2 = (1 - \frac{b}{n})L^2b^{-1} + B, \quad C_2 = 0,$$

where $B := \frac{\omega(1 + \beta)L^2b^2}{1 + \omega} + L^2b^{2-1}$, $\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}$, and $\forall \gamma, \beta > 0$.

Proof of Lemma 12. If the local stochastic gradient estimator $\tilde{g}_i^k = \frac{1}{b} \sum_{j \in I_b}(\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k)$ (see Line 3 of Algorithm 15), we show the following equations:

$$E_k[\tilde{g}_i^k] = E_k \left[ \frac{1}{b} \sum_{j \in I_b}(\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) \right]$$

$$= \nabla f_i(x^k) - \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k)$$

$$= \nabla f_i(x^k)$$

(C.94)
and

\begin{align*}
E_k[||g_k^k||^2] &= E_k[||g_k^k - \nabla f_i(x^k)||^2] + ||\nabla f_i(x^k)||^2 \\
&= E_k \left[ \left|\left| \frac{1}{b} \sum_{j \in I_k} (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) + \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) - \nabla f_i(x^k) \right|\right|^2 \right] + ||\nabla f_i(x^k)||^2 \\
&= \frac{1}{b^2} E_k \left[ \left|\left| \sum_{j \in I_k} \left( (\nabla f_{i,j}(x^k) - \nabla f_{i,j}(w_{i,j}^k)) - \left( \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(x^k) - \frac{1}{n} \sum_{j=1}^{n} \nabla f_{i,j}(w_{i,j}^k) \right) \right) \right|\right|^2 \right] \\
&\quad + ||\nabla f_i(x^k)||^2 \\
&\leq \frac{1}{b} E_k \left[ ||\nabla f_i(x^k) - \nabla f_i(w_{i,j}^k)||^2 \right] + ||\nabla f_i(x^k)||^2 \\
&\leq \frac{L^2}{b} \frac{1}{n} \sum_{j=1}^{n} ||x^k - w_{i,j}^k||^2 + ||\nabla f_i(x^k)||^2, \tag{C.95}
\end{align*}

where (C.95) uses the fact \( E[|x - E[x]|^2] \leq E[|x|^2] \), and the last inequality uses Assumption 7 (i.e., (2.6)). Now, we define \( \sigma_{k, i}^2 := \frac{1}{n} \sum_{j=1}^{n} ||x^k - w_{i,j}^k||^2 \) and obtain

\begin{align*}
E_k[\sigma_{k+1, i}^2] &= E_k \left[ \frac{1}{n} \sum_{j=1}^{n} ||x^{k+1} - w_{i,j}^{k+1}||^2 \right] \\
&= E_k \left[ \frac{1}{n} \sum_{j=1}^{n} \frac{b}{n} ||x^{k+1} - x^k||^2 + \frac{1}{n} \sum_{j=1}^{n} \left( 1 - \frac{b}{n} \right) ||x^{k+1} - w_{i,j}^k||^2 \right] \tag{C.97}
\end{align*}

\begin{align*}
&= \frac{b}{n} E_k \eta^2 ||g_k||^2 + \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{j=1}^{n} ||x^k - \eta g_k - w_{i,j}^k||^2 \tag{C.98}
\end{align*}

\begin{align*}
&= \frac{b \eta^2}{n} E_k ||g_k||^2 + \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{j=1}^{n} \left( ||x^k - w_{i,j}^k||^2 + ||\eta g_k||^2 - 2(x^k - w_{i,j}^k, \eta g_k) \right) \\
&= \eta^2 E_k ||g_k||^2 + \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{j=1}^{n} ||x^k - w_{i,j}^k||^2 + \frac{1}{n} \sum_{j=1}^{n} (x^k - w_{i,j}^k, \eta \nabla f(x^k)) \\
&\leq \eta^2 E_k ||g_k||^2 + \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{j=1}^{n} ||x^k - w_{i,j}^k||^2 \\
&\quad + \left( 1 - \frac{b}{n} \right) \frac{1}{n} \sum_{j=1}^{n} \left( \gamma ||x^k - w_{i,j}^k||^2 + \frac{\eta^2}{\gamma} ||\nabla f(x^k)||^2 \right) \tag{C.99}
\end{align*}
\[
\left(1 - \frac{b}{n} + \frac{b}{n} \gamma - \gamma \right) \sigma^2_{k,i} + \left(1 - \frac{b}{n} \right)^2 \| \nabla f(x^k) \|^2 + \eta^2 \mathbb{E}_k[\| g^k \|^2],
\]
(C.100)

where (C.97) uses Line 6 of Algorithm 15, (C.98) uses Line 9 of Algorithm 15, (C.99) uses Young’s inequality for \( \forall \gamma > 0 \), and (C.100) follows from the definition \( \sigma^2_{k,i} := \frac{1}{n} \sum_{j=1}^{n} \| x^k - w_{i,j}^k \|^2 \).

Now, according to (C.96) and (C.100), we know the local stochastic gradient estimator \( \hat{g}_i^k \) (see Line 3 of Algorithm 15) satisfies (C.52) and (C.53) with

\[
A_{1,i} = 0, \quad B_{1,i} = 1, \quad D_{1,i} = \frac{L^2}{b}, \quad \sigma^2_{k,i} = \frac{1}{n} \sum_{j=1}^{n} \| x^k - w_{i,j}^k \|^2, \quad C_{1,i} = 0,
\]

\[
\rho_i = \frac{b}{n} + \frac{b}{n} \gamma - \gamma, \quad A_{2,i} = 0, \quad B_{2,i} = (1 - \frac{b}{n}) \eta^2 \gamma^{-1}, \quad D_{2,i} = \eta^2, \quad C_{2,i} = 0, \quad \forall \gamma > 0.
\]

Thus, according to Theorem 4, \( g^k \) (see Line 8 of Algorithm 15) satisfies the unified Assumption 1 with

\[
A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,
\]

\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma^2_k = \frac{1}{mn} \sum_{i=1}^{m} \sum_{j=1}^{m} \frac{L^2}{b} \| x^k - w_{i,j}^k \|_2^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \| \nabla f_i(x^k) - h_i^k \|^2,
\]

\[
\rho = \min \left\{ \frac{b}{n} + \frac{b}{n} \gamma - \gamma - \tau, \ 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau \right\},
\]

\[
A_2 = 0, \quad B_2 = (1 - \frac{b}{n}) \tilde{L} \eta^2 \gamma^{-1} B + B, \quad C_2 = 0,
\]

where \( B := \frac{\omega(1 + \beta)L^2 \eta^2}{1 + \omega} + \tilde{L} \eta^2 B^{-1} \), \( \tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m} \), and \( \forall \gamma, \beta > 0 \). \( \square \)

**Corollary 12 (DIANA-SAGA)** Suppose that Assumption 5 and 7 hold. Let stepsize

\[
\eta \leq \frac{1}{L + L(1 + \omega)B'm^{-1}B^{-1} \rho^{-1}},
\]

then the number of iterations performed by DIANA-SAGA (Algorithm 15) to find an \( \epsilon \)-solution of nonconvex federated problem (1.1) with (1.3), i.e. a point \( \hat{x} \) such that \( \mathbb{E}[\| \nabla f(\hat{x}) \|] \leq \epsilon \), can be bounded by

\[
K = \frac{8\Delta_0 L}{e^2} \left( 1 + \frac{(1 + \omega)B'}{mb\rho} \right),
\]

(C.101)

where \( B' := (1 - \frac{b}{n}) \tilde{L} \eta^2 \gamma^{-1} + Bb, \rho := \min \left\{ \frac{n + \frac{b}{n} \gamma - \gamma - \tau, \ 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau \right\}, \quad \tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m} \),

\[
B := \frac{\omega(1 + \beta)L^2 \eta^2}{1 + \omega} + \tilde{L} \eta^2 B^{-1}, \quad \text{and} \ \forall \gamma, \beta > 0.
\]

**Proof of Corollary 12.** According to our unified Theorem 1, if the stepsize is chosen as

\[
\eta \leq \min \left\{ \frac{1}{LB_1 + LD_1 B_2 \rho^{-1}}, \ \sqrt{\frac{\ln 2}{(LA_1 + LD_1 A_2 \rho^{-1})K}}, \ \frac{e^2}{2LC_1 + C_1 C_2 \rho^{-1}} \right\}
\]

(C.102)

since \( B_1 = 1, D_1 = \frac{1 + \omega}{m}, B_2 = \frac{B'}{b}, B' = (1 - \frac{b}{n}) \tilde{L} \eta^2 \gamma^{-1} + Bb \) and \( A_1 = A_2 = C_1 = C_2 = 0 \) according to Lemma 12, then the number of iterations performed by DIANA-SAGA (Algorithm 15) to find an \( \epsilon \)-solution of problem (1.1) with (1.3) can be bounded by

\[
K = \frac{8\Delta_0 L}{e^2} \max \left\{ B_1 + D_1 B_2 \rho^{-1}, \ \frac{12\Delta_0 (A_1 + D_1 A_2 \rho^{-1})}{e^2}, \ \frac{2(C_1 + D_1 C_2 \rho^{-1})}{e^2} \right\}
\]

(C.103)
since $B_1 = 1, D_1 = \frac{1}{m} \omega, B_2 = \frac{B'}{n}, B' = (1 - \frac{b}{n}) \bar{L}^2 \eta^2 \gamma^{-1} + Bb, A_1 = A_2 = C_1 = C_2 = 0$ and $\Delta_0 := f(x^0) - f^* + 2^{-1} L \eta^2 D_1 \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0$ by letting $\sigma_0^2 = \frac{\omega}{(1+m)\omega} \sum_{i=1}^{m} \| \nabla f_i(x^0) - h^0 \|^2 = 0.$
D Better Convergence for Nonconvex Optimization under PL Condition

In this section, we provide the detailed better convergence rates and proofs under PL condition (i.e., Assumption 8) for some specific methods in the single machine case (i.e., \( m = 1 \)) of nonconvex federated problem (1.1) which reduces to the standard nonconvex problem (1.4) with online form (1.5) or finite-sum form (1.6), i.e.,

\[
\min_{x \in \mathbb{R}^d} f(x), \quad \text{where } f(x) := \mathbb{E}_{\zeta \sim \mathcal{D}}[f(x, \zeta)], \quad \text{or } f(x) := \frac{1}{n} \sum_{i=1}^{n} f_i(x).
\]

In the following, we prove that some specific methods, i.e., GD, SGD, L-SVRG and SAGA satisfy our unified Assumption 1 and thus can be captured by our unified analysis. Then, we plug their corresponding parameters (i.e., specific values for \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \)) into our unified Theorem 2 or 5 under PL condition to obtain the detailed better convergence rates for these methods.

D.1 GD method under PL condition

Corollary 13 (GD under PL condition) Suppose that Assumption 2 and 8 hold. Let stepsize \( \eta \leq \frac{1}{L} \), then the number of iterations performed by GD (Algorithm 2) to find an \( \epsilon \)-solution of nonconvex problem (1.4), i.e. a point \( x^K \) such that \( \mathbb{E}[f(x^K) - f^*] \leq \epsilon \), can be bounded by

\[
K = \frac{L}{\mu} \log \frac{2\Delta_0}{\epsilon}.
\]

Note that it recovers the previous result for GD under PL condition given by [48, 21].

Proof of Corollary 13. According to Theorem 5, if the stepsize is chosen as

\[
\eta_k = \eta \leq \min \left\{ \frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}}, \frac{\mu \epsilon}{LC_1 + 2LD_1C_2\rho^{-1}} \right\}
\]

since \( B_1 = 1, A_1 = C_1 = D_1 = 0 \) according to Lemma 1, then the number of iterations performed by Algorithm 1 to find an \( \epsilon \)-solution of problem (1.4) can be bounded by

\[
K = \max \left\{ B_1 + 2D_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}, \frac{C_1 + 2D_1C_2\rho^{-1}}{\mu \epsilon} \right\} \frac{L}{\mu} \log \frac{2\Delta_0}{\epsilon}
\]

since \( B_1 = 1, A_1 = C_1 = D_1 = 0, \sigma_0^2 = 0, \) and \( \Delta_0 := f(x^0) - f^* + L\eta^2D_1\rho^{-1}\sigma_0^2 = f(x^0) - f^* = \Delta_0 \). \( \square \)

D.2 SGD method under PL condition

Corollary 14 (SGD under PL condition) Suppose that Assumption 2 and 8 hold, and the gradient estimator \( g^k \) in Algorithm 3 satisfies Assumption 9. Let stepsize

\[
\eta_k = \begin{cases} \eta & \text{if } k \leq \frac{K}{2}, \\ \frac{2\eta}{2 + (k - \frac{K}{2})\mu} & \text{if } k > \frac{K}{2}, \end{cases} \quad \text{where } \eta \leq \frac{1}{LB + LA\mu^{-1}},
\]

then the number of iterations performed by SGD (Algorithm 3) for finding an \( \epsilon \)-solution of nonconvex problem (1.4) with (1.5) or (1.6), i.e. a point \( x^K \) such that \( \mathbb{E}[f(x^K) - f^*] \leq \epsilon \), can be bounded by

\[
K = \max \left\{ \frac{2L(B + A\mu^{-1})}{\mu} \log \frac{2\Delta_0}{\epsilon}, \frac{10LC}{\mu^2 \epsilon} \right\}.
\]
Note that it recovers the recent result for SGD under PL condition given by [23].

**Proof of Corollary 14.** According to Theorem 2, if the stepsize is chosen as

\[
\eta_k = \begin{cases} 
\eta & \text{if } k \leq \frac{K}{4} \\
\frac{2\eta}{2+(k-\frac{K}{2})/\mu} & \text{if } k > \frac{K}{2}
\end{cases}
\]

where

\[
\frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}} = \frac{1}{LB + LA\mu^{-1}}
\]

since \( A_1 = A, B_1 = B, C_1 = C, D_1 = 0 \) according to Lemma 2, then the number of iterations performed by Algorithm 1 to find an \( \epsilon \)-solution of problem (1.4) with (1.5) can be bounded by

\[
K = \max \left\{ \frac{2L(B_1 + 2D_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1})}{\mu} \log \frac{2\Delta_0}{\epsilon}, \frac{10L(C_1 + 2D_1C_2\rho^{-1})}{\mu^2\epsilon} \right\}
\]

since \( A_1 = A, B_1 = B, C_1 = C, D_1 = 0, \sigma_0^2 = 0, \) and \( \Delta_0 := f(x^0) - f^* + L\eta^2D_1\rho^{-1}\sigma_0^2 = f(x^0) - f^* = \Delta_0. \) \( \square \)

### D.3 L-SVRG method under PL condition

**Corollary 15 (L-SVRG under PL condition)** Suppose that Assumption 3 and 8 hold. Let stepsize \( \eta \leq \frac{1}{L(1+3b^{-1/3})p^{-2/3}} \), then the number of iterations performed by L-SVRG (Algorithm 4) for finding an \( \epsilon \)-solution of nonconvex problem (1.4) with (1.6), i.e. a point \( x^K \) such that \( \mathbb{E}[f(x^K) - f^*] \leq \epsilon, \) can be bounded by

\[
K = \left( 1 + \frac{3}{b^{1/3}p^{2/3}} \right) \frac{L}{\mu} \log \frac{2\Delta_0}{\epsilon}.
\]

In particular, we have

1. let minibatch size \( b = 1 \) and probability \( p = \frac{1}{n} \), then the number of iterations \( K = \frac{4n^{2/3}L}{\mu} \log \frac{2\Delta_0}{\epsilon}. \)

2. let minibatch size \( b = n^{2/3} \) and probability \( p = \frac{1}{n^{1/3}} \), then the number of iterations \( K = \frac{4L}{\mu} \log \frac{2\Delta_0}{\epsilon}, \) but each iteration costs \( n^{2/3} \) due to minibatch size \( b = n^{2/3}. \)

Note that it recovers the previous result for SVRG under PL condition given by [51, 36], but they studied the standard SVRG form [19] not this simpler loopless version.

**Proof of Corollary 15.** According to Theorem 5, the stepsize should be chosen as

\[
\eta_k \equiv \eta \leq \min \left\{ \frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}}, \frac{\mu\epsilon}{LC_1 + 2LD_1C_2\rho^{-1}} \right\}
\]

(D.1)

since \( A_1 = A_2 = C_1 = C_2 = 0 \) according to Lemma 3. Then the number of iterations performed by L-SVRG (Algorithm 4) to find an \( \epsilon \)-solution of problem (1.4) with (1.6) can be bounded by

\[
K = \max \left\{ B_1 + 2D_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}, \frac{C_1 + 2D_1C_2\rho^{-1}}{\mu\epsilon} \right\} \frac{L}{\mu} \log \frac{2\Delta_0}{\epsilon}
\]

(D.2)
since $A_1 = A_2 = C_1 = C_2 = 0$, $\sigma_0^2 = \|x^0 - w^0\|^2 = 0$, and $\Delta_0 := f(x^0) - f^* + 2 - 1 L_1^2 D_1 \rho^{-1} \sigma_0^2 = f(x^0) - f^* = \Delta_0$.

Now, the remaining thing is to upper bound the term $B_1 + 2 D_1 B_2 \rho^{-1}$,

$$B_1 + 2 D_1 B_2 \rho^{-1} = 1 + \frac{2 L^2}{b} \left( \frac{2 \eta^2}{p} - \eta^2 \right) \left( \frac{p}{2} + \frac{p^2}{2} - \frac{\eta^2 L^2}{b} \right)^{-1}$$

(D.3)

$$\leq 1 + \frac{2 L^2}{b} \left( \frac{2 \eta^2}{p} \right) \left( \frac{p}{4} \right)^{-1}$$

(D.4)

$$= 1 + \frac{16 L^2 \eta^2}{bp^2}$$

$$\leq 1 + \frac{3}{b^{1/3} p^{2/3}},$$

(D.5)

where (D.3) follows from $B_1 = 1, D_1 = \frac{L^2}{b}, B_2 = \frac{2 \eta^2}{p} - \eta^2, \rho = \frac{p}{2} + \frac{p^2}{2} - \frac{\eta^2 L^2}{b}$ in Lemma 3, the last inequality (D.5) holds by setting $\eta \leq \frac{1}{L (1 + \frac{3}{b^{1/3} p^{2/3}})} \leq \frac{1}{L B_1 + 2 B_2 D_1 \rho^{-1}}$, and (D.4) is due to the fact $\frac{2 L^2}{b} \leq \frac{4}{3}$.

In sum, let stepsize

$\eta \leq \frac{1}{L (1 + \frac{3}{b^{1/3} p^{2/3}})},$

then the number of iterations performed by L-SVRG (Algorithm 4) to find an $\epsilon$-solution of problem (1.4) with (1.6) can be bounded by

$$K = \left(1 + \frac{3}{b^{1/3} p^{2/3}}\right) \frac{L}{\mu} \log \frac{2 \Delta_0}{\epsilon}.$$

In particular, we have

1. let minibatch size $b = 1$ and probability $p = \frac{1}{3}$, then the number of iterations $K = \frac{4 n^{2/3}}{\mu} L \log \frac{2 \Delta_0}{\epsilon}$.

2. let minibatch size $b = n^{2/3}$ and probability $p = \frac{1}{n^{1/3}}$, then the number of iterations $K = \frac{4 L}{\mu} \log \frac{2 \Delta_0}{\epsilon}$, but each iteration costs $n^{2/3}$ due to minibatch size $b = n^{2/3}$.

\[\Box\]

D.4 SAGA method under PL condition

**Corollary 16 (SAGA under PL condition)** Suppose that Assumption 4 and 8 hold. Let stepsize $\eta \leq \frac{1}{L (1 + \frac{3}{n^{2/3} b - 1})}$, then the number of iterations performed by SAGA (Algorithm 5) for finding an $\epsilon$-solution of nonconvex problem (1.4) with (1.6), i.e. a point $x^K$ such that $\mathbb{E}\left[f(x^K) - f^*\right] \leq \epsilon$, can be bounded by

$$K = \left(1 + \frac{3 n^{2/3}}{b}\right) \frac{L}{\mu} \log \frac{2 \Delta_0}{\epsilon}.$$

In particular, we have

1. let minibatch size $b = 1$, then the number of iterations $K = \frac{4 n^{2/3}}{\mu} L \log \frac{2 \Delta_0}{\epsilon}$.

2. let minibatch size $b = n^{2/3}$, then iteration $K = \frac{4 L}{\mu} \log \frac{2 \Delta_0}{\epsilon}$, but each iteration costs $n^{2/3}$ due to minibatch size $b = n^{2/3}$.

Note that it recovers the previous result for SAGA under PL condition given by [51], but Reddi et al. [51] needed to restart SAGA for $O(\log \frac{1}{\epsilon})$ times to achieve this linear convergence rate.
Proof of Corollary 16. According to Theorem 5, the stepsize should be chosen as

$$
\eta_k \equiv \eta \leq \min \left\{ \frac{1}{LB_1 + 2LD_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}}, \frac{\mu\epsilon}{LC_1 + 2LD_1C_2\rho^{-1}} \right\}
$$

(D.6)

since $A_1 = A_2 = C_1 = C_2 = 0$ according to Lemma 4. Then the number of iterations performed by SAGA (Algorithm 5) to find an $\epsilon$-solution of problem (1.4) with (1.6) can be bounded by

$$
K = \max \left\{ B_1 + 2D_1B_2\rho^{-1} + (LA_1 + 2LD_1A_2\rho^{-1})\mu^{-1}, \frac{C_1 + 2D_1C_2\rho^{-1}}{\mu\epsilon} \right\} \frac{L}{\mu} \log \frac{2\Delta'_0}{\epsilon}
$$

(D.7)

where $B_1 = 1$ and $D_1 = L^2 b, B_2 = \frac{2n^2}{b} - \eta^2, \rho = \frac{b}{2n} + \frac{b^2}{2n^2} = \frac{\eta^2 L^2}{2b}$ in Lemma 4, the last inequality (D.10) holds by setting $\eta \leq \frac{1}{L(1 + \frac{3n^{2/3}}{b})} \leq \frac{1}{LB_1 + 2LD_1B_2\rho^{-1}}$, and (D.9) is due to the fact $\frac{\eta^2 L^2}{b} \leq \frac{b}{4n}$.

In sum, let stepsize

$$
\eta \leq \frac{1}{L(1 + \frac{3n^{2/3}}{b})},
$$

then the number of iterations performed by SAGA (Algorithm 5) to find an $\epsilon$-solution of problem (1.4) with (1.6) can be bounded by

$$
K = \left( 1 + \frac{3n^{2/3}}{b} \right) \frac{L}{\mu} \log \frac{2\Delta'_0}{\epsilon}.
$$

In particular, we have

1. let minibatch size $b = 1$, then the number of iterations $K = \frac{4n^{2/3}L}{\mu} \log \frac{2\Delta_0}{\epsilon}$.

2. let minibatch size $b = n^{2/3}$, then iteration $K = \frac{4L}{\mu} \log \frac{2\Delta_0}{\epsilon}$, but each iteration costs $n^{2/3}$ due to minibatch size $b = n^{2/3}$.

□

71
E Better Convergence for Nonconvex Federated Optimization under PL Condition

Similar to Section D, we prove better convergence rates for the more general nonconvex distributed/federated optimization problem (1.1) with online form (1.2) or (1.3) under the PL condition (i.e., Assumption 8).

\[
\min_{x \in \mathbb{R}^d} \left\{ f(x) := \frac{1}{m} \sum_{i=1}^{m} f_i(x) \right\}, \quad \text{where } f_i(x) := \mathbb{E}_{\zeta \sim D_i}[f_i(x, \zeta)], \quad \text{or} \quad f_i(x) := \frac{1}{n} \sum_{j=1}^{n} f_{i,j}(x).
\]

Recall that we allow that different machine/worker \( i \in [m] \) can have different data distribution \( D_i \), i.e., non-IID data (heterogeneous data) setting.

In section C, we have already proved that several (new) methods belonging to the proposed general DC framework (Algorithm 6) and DIANA framework (Algorithm 7) for solving this general distributed/federated problem also satisfy the unified Assumption 1 and thus can also be captured by our unified analysis. In the following, we plug their corresponding parameters (i.e., specific values \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \)) into our unified Theorem 2 or 5 under PL condition to obtain the detailed better convergence rate \( s \) for these methods.

Note that the proposed general DC framework (Algorithm 6) and DIANA framework (Algorithm 7) differing in direct gradient compression or compression of gradient differences. We would like to point out that the direct gradient compression, i.e., DC framework (Algorithm 6) has a main issue. Consider any stationary point \( \hat{x} \) such that \( \nabla f(\hat{x}) = \sum_{i=1}^{m} \nabla f_i(\hat{x}) = 0 \), the issue is that the aggregated compressed gradient (even if the local stochastic gradient uses full gradient, i.e., \( \tilde{g}_k^i = \nabla f_i(x_k) \)) does not converge to 0, i.e., \( g(\hat{x}) = \frac{1}{m} \sum_{i=1}^{m} C_i(\nabla f_i(\hat{x})) \neq 0 \). However, the proposed DIANA Framework to compress the gradient differences (see Line 4 of Algorithm 7) indeed can address this issue. They are also reflected by our theoretical results, i.e., comparing the convergence results in the following Section E.1 and Section E.2.

E.1 Better convergence results of DC-type methods under PL condition

In this section, we provide the detailed convergence results under PL condition for some specific methods (i.e., DC-GD/SGD/LSVRG/SAGA) belonging to our DC framework (Algorithm 6) by using our unified Theorem 2 under PL condition.

E.1.1 DC-GD method under PL condition

Corollary 17 (DC-GD under PL condition) Suppose that Assumption 5 and 8 hold. Let stepsize

\[
\eta_k = \begin{cases} 
\eta & \text{if } k \leq \frac{K}{2} \\
\frac{2\eta}{L + (1 + \omega)(1 - \omega)Am^{-1}} & \text{if } k > \frac{K}{2},
\end{cases} \quad \text{where } \eta \leq \frac{1}{L + L(1 + \omega)Am^{-1}1^{-1}},
\]

then the number of iterations performed by DC-GD (Algorithm 8) to find an \( \epsilon \)-solution of nonconvex federated problem (1.1), i.e. a point \( x^K \) such that \( \mathbb{E}[f(x^K) - f^*] \leq \epsilon \), can be bounded by

\[
K = \max \left\{ \frac{2L(1 + (1 + \omega)Am^{-1})}{\mu} \log \frac{2\Delta_0}{\epsilon}, \frac{10(1 + \omega)LC}{m\mu^2\epsilon} \right\},
\]

(E.1)

where \( A := \max_i(L_i - L_i/(1 + \omega)), C := 2A\Delta^*_j, \) and \( \Delta^*_i := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^* \).
\textbf{Proof of Corollary 17.} According to Lemma 5, we have proved that \(g^k\) (see Line 6 of DC-GD Algorithm 8) satisfies the unified Assumption 1 with
\begin{align*}
A_1 &= \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \\
D_1 &= \frac{1 + \omega}{m}, \quad \sigma_k^2 = 0, \quad \rho = 1, \\
A_2 &= 0, \quad B_2 = 0, \quad C_2 = 0,
\end{align*}
where \(A := \max_i(L_i - L_i/(1 + \omega))\), \(C := 2A\Delta_f^*,\) and \(\Delta_f^* := f^* - \frac{1}{m}\sum_{i=1}^m f_i^*\). Then this corollary is proved by plugging these specific values for \(A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho\) into our unified Theorem 2. \(\square\)

\textbf{E.1.2 DC-SGD method under PL condition}

\textbf{Corollary 18 (DC-SGD under PL condition)} Suppose that Assumption 5 and 8 hold, and the local gradient estimator \(\tilde{g}_i^k\) in Algorithm 9 satisfies Assumption 9. Let stepsize
\begin{equation*}
\eta_k = \begin{cases} 
\eta & \text{if } k \leq \frac{K}{2}, \\
\frac{2m}{2+(k-\frac{K}{2})\mu\eta} & \text{if } k > \frac{K}{2},
\end{cases}
\end{equation*}
where \(\eta \leq \frac{1}{L + L(1 + \omega)Am^{-1}\mu^{-1}}\), then the number of iterations performed by DC-SGD (Algorithm 9) to find an \(\epsilon\)-solution of nonconvex federated problem (1.1) with (1.2) or (1.3), i.e. a point \(x^K\) such that \(\mathbb{E}[f(x^K) - f^*] \leq \epsilon\), can be bounded by
\begin{equation*}
K = \max \left\{ \left(1 + \frac{(1 + \omega)A}{m\mu} \right) \frac{2L}{\mu} \log\frac{2\Delta_0}{\epsilon}, \frac{10(1 + \omega)LC}{m\mu^2\epsilon} \right\},
\end{equation*}
where \(A := \max_i(A_{1,i} + B_{1,i}L_i - L_i/(1 + \omega))\), \(C := \frac{1}{m}\sum_{i=1}^m C_{1,i} + 2A\Delta_f^*\) and \(\Delta_f^* := f^* - \frac{1}{m}\sum_{i=1}^m f_i^*\).

\textbf{Proof of Corollary 18.} According to Lemma 6, we have proved that \(g^k\) (see Line 6 of DC-SGD Algorithm 9) satisfies the unified Assumption 1 with
\begin{align*}
A_1 &= \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m}, \\
D_1 &= \frac{1 + \omega}{m}, \quad \sigma_k^2 = 0, \quad \rho = 1, \\
A_2 &= 0, \quad B_2 = 0, \quad C_2 = 0,
\end{align*}
where \(A := \max_i(A_{1,i} + B_{1,i}L_i - L_i/(1 + \omega))\), \(C := \frac{1}{m}\sum_{i=1}^m C_{1,i} + 2A\Delta_f^*\) and \(\Delta_f^* := f^* - \frac{1}{m}\sum_{i=1}^m f_i^*\). Then this corollary is proved by plugging these specific values for \(A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho\) into our unified Theorem 2. \(\square\)

\textbf{E.1.3 DC-LSVRG method under PL condition}

\textbf{Corollary 19 (DC-LSVRG under PL condition)} Suppose that Assumption 5, 6 and 8 hold. Let stepsize
\begin{equation*}
\eta_k = \begin{cases} 
\eta & \text{if } k \leq \frac{K}{2}, \\
\frac{2m}{2+(k-\frac{K}{2})\mu\eta} & \text{if } k > \frac{K}{2},
\end{cases}
\end{equation*}
where
\begin{equation*}
\eta \leq \frac{1}{L + L(1 + \omega)(1 + 2\tau\rho^{-1})Am^{-1}\mu^{-1} + 2L(1 + \omega)Bm^{-1}b^{-1}\rho^{-1}},
\end{equation*}
73
then the number of iterations performed by DC-LSVRG (Algorithm 10) to find an \( \varepsilon \)-solution of nonconvex federated problem \((1.1)\) with \((1.3)\), i.e. a point \( x^K \) such that \( \mathbb{E}[f(x^K) - f^*] \leq \varepsilon \), can be bounded by

\[
K = \max \left\{ \left( 1 + \frac{1 + \omega}{m} \left( \frac{(1 + 2\tau \rho^{-1})A}{\mu} + \frac{2B}{\mu b} \right) \right) \frac{2L}{\mu} \frac{2\Delta_0}{\epsilon}, \frac{10(1 + \omega)(1 + 2\tau \rho^{-1})LC}{m\rho^2 \varepsilon} \right\},
\]

(E.3)

where \( A := \max_i (L_i - L_i/(1 + \omega)) \), \( B := \bar{L}^2((1 - p)\eta^2\gamma^{-1} + \eta^2) \), \( C := 2A\Delta^*_f \), \( \Delta^*_f := f^* - \frac{1}{m} \sum_{i=1}^m f_i^* \), \( \rho := p + p\gamma - \gamma - \tau \), \( \tau := \frac{(1+\omega)\bar{L}^2\eta^2}{mb} \) and \( \forall \gamma > 0 \).

**Proof of Corollary 19.** According to Lemma 7, we have proved that \( g^k \) (see Line 7 of DC-LSVRG Algorithm 10) satisfies the unified Assumption 1 with

\[
A_1 = \frac{(1+\omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1+\omega)C}{m},
\]

\[
A_2 = \tau A, \quad B_2 = \frac{\bar{L}^2((1-p)\eta^2\gamma^{-1} + \eta^2)}{b}, \quad C_2 = \tau C,
\]

where \( A := \max_i (L_i - L_i/(1 + \omega)) \), \( C := 2A\Delta^*_f \), \( \Delta^*_f := f^* - \frac{1}{m} \sum_{i=1}^m f_i^* \), \( \tau := \frac{(1+\omega)\bar{L}^2\eta^2}{mb} \) and \( \forall \gamma > 0 \). Then this corollary is proved by plugging these specific values for \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \) into our unified Theorem 2.

\( \square \)

**E.1.4 DC-SAGA method under PL condition**

**Corollary 20 (DC-SAGA under PL condition) Supposed that Assumption 5, 7 and 8 hold.** Let stepsize

\[
\eta_k = \begin{cases} \eta \frac{2n}{\tau + (\kappa - \frac{\lambda}{b}) \rho \mu} & \text{if } k \leq \frac{K}{2} \\ \eta \frac{2n}{\tau + (\kappa - \frac{\lambda}{b}) \rho \mu} & \text{if } k > \frac{K}{2} \end{cases}
\]

where

\[
\eta \leq \frac{1}{L + L(1+\omega)(1+2\tau \rho^{-1})Am^{-1}b^{-1} + 2L(1+\omega)Bm^{-1}b^{-1}\rho^{-1}},
\]

then the number of iterations performed by DC-SAGA (Algorithm 11) to find an \( \varepsilon \)-solution of nonconvex federated problem \((1.1)\) with \((1.3)\), i.e. a point \( x^K \) such that \( \mathbb{E}[f(x^K) - f^*] \leq \varepsilon \), can be bounded by

\[
K = \max \left\{ \left( 1 + \frac{1 + \omega}{m} \left( \frac{(1 + 2\tau \rho^{-1})A}{\mu} + \frac{2B}{\mu b} \right) \right) \frac{2L}{\mu} \frac{2\Delta_0}{\epsilon}, \frac{10(1 + \omega)(1 + 2\tau \rho^{-1})LC}{m\rho^2 \varepsilon} \right\},
\]

(E.4)

where \( A := \max_i (L_i - L_i/(1 + \omega)) \), \( B := \bar{L}^2((1 - b\eta^2\gamma^{-1} + \eta^2) \), \( C := 2A\Delta^*_f \), \( \Delta^*_f := f^* - \frac{1}{m} \sum_{i=1}^m f_i^* \), \( \rho := \frac{n}{b} + \frac{b}{n} \gamma - \gamma - \tau \), \( \tau := \frac{(1+\omega)\bar{L}^2\eta^2}{mb} \) and \( \forall \gamma > 0 \).

**Proof of Corollary 20.** According to Lemma 8, we have proved that \( g^k \) (see Line 7 of DC-SAGA Algorithm 11) satisfies the unified Assumption 1 with

\[
A_1 = \frac{(1+\omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1+\omega)C}{m},
\]

\[
A_2 = \tau A, \quad B_2 = \frac{\bar{L}^2((1 - b\eta^2\gamma^{-1} + \eta^2)}{b}, \quad C_2 = \tau C,
\]

where \( A := \max_i (L_i - L_i/(1 + \omega)) \), \( C := 2A\Delta^*_f \), \( \Delta^*_f := f^* - \frac{1}{m} \sum_{i=1}^m f_i^* \), \( \tau := \frac{(1+\omega)\bar{L}^2\eta^2}{mb} \) and \( \forall \gamma > 0 \). Then this corollary is proved by plugging these specific values for \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \) into our unified Theorem 2.

\( \square \)
E.2 Better convergence results of DIANA-type methods under PL Condition

In this section, we provide the detailed convergence results under PL condition for some specific methods (i.e., DIANA-GD/SGD/LSVRG/SAGA) belonging to our DIANA framework (Algorithm 7) by using our unified Theorem 2 or 5 under PL condition.

E.2.1 DIANA-GD method under PL condition

Corollary 21 (DIANA-GD under PL condition) Suppose that Assumption 5 and 8 hold. Let stepsize

$$\eta \leq \frac{1}{L + 2L(1 + \omega)Bm^{-1}\rho^{-1}},$$

then the number of iterations performed by DIANA-GD (Algorithm 12) to find an \(\epsilon\)-solution of nonconvex federated problem (1.1), i.e. a point \(x^K\) such that \(\mathbb{E}[f(x^K) - f^*] \leq \epsilon\), can be bounded by

$$K = \left(1 + \frac{2(1 + \omega)B}{m\mu}\right) \frac{L}{\rho} \log \frac{2\Delta_0}{\epsilon},$$

where \(B := \frac{\omega(1 + \beta)L^2}{L + \omega}\), \(\rho := \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\}\), \(\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}\), and \(\forall \beta > 0\).

Proof of Corollary 21. According to Lemma 9, we have proved that \(g^k\) (see Line 7 of DIANA-GD Algorithm 12) satisfies the unified Assumption 1 with

- \(A_1 = 0\), \(B_1 = 1\), \(C_1 = 0\),
- \(D_1 = \frac{1 + \omega}{m}\), \(\sigma_k^2 = \frac{\omega}{(1 + \omega)m} \sum_{i=1}^m \|\nabla f_i(x^k) - h^k_i\|^2\),
- \(\rho = \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\}\),
- \(A_2 = 0\), \(B_2 = B\), \(C_2 = 0\),

where \(B := \frac{\omega(1 + \beta)L^2}{L + \omega}\), \(\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}\), and \(\forall \beta > 0\). Then this corollary is proved by plugging these specific values for \(A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho\) into our unified Theorem 5.

E.2.2 DIANA-SGD method under PL condition

Corollary 22 (DIANA-SGD under PL condition) Suppose that Assumption 5 and 8 hold, and the local gradient estimator \(\tilde{g}_i^k\) in Algorithm 13 satisfies Assumption 9. Let stepsize

$$\eta_k = \begin{cases} \eta \frac{2\mu}{2 + (k - \frac{K}{2})\rho \eta} & \text{if } k \leq \frac{K}{2} \\ \eta \frac{2\mu}{2 + (k - \frac{K}{2})\rho \eta} & \text{if } k > \frac{K}{2}, \end{cases}$$

where

$$\eta \leq \frac{1}{L + L(1 + \omega)(1 + 2\tau\rho^{-1})Am^{-1}\mu^{-1} + 2L(1 + \omega)Bm^{-1}\rho^{-1}},$$

then the number of iterations performed by DIANA-SGD (Algorithm 13) to find an \(\epsilon\)-solution of nonconvex federated problem (1.1) with (1.2) or (1.3), i.e. a point \(x^K\) such that \(\mathbb{E}[f(x^K) - f^*] \leq \epsilon\), can be bounded by

$$K = \max \left\{ \left(1 + \frac{1 + \omega}{m} \left(\frac{1 + 2\tau\rho^{-1}}{\mu} A + \frac{2B}{\rho}\right) \right) \frac{2L}{\mu} \log \frac{2\Delta_0}{\epsilon}, \frac{10(1 + \omega)(1 + 2\tau\rho^{-1})LC}{m\mu\epsilon^2} \right\},$$

where \(A := \max_i (A_{1,i} + (B_{1,i} - 1)L_i)\), \(B := \frac{\omega(1 + \beta)L^2\sigma^2}{1 + \omega}\), \(C := \frac{1}{m} \sum_{i=1}^m C_{1,i} + 2A\Delta^*\), \(\Delta^* := f^* - \frac{1}{m} \sum_{i=1}^m f_i^*\), \(\rho := \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\}\), \(\tau := \alpha^2\omega + \frac{(1 + \omega)B}{m}\), and \(\forall \beta > 0\).
Proof of Corollary 22. According to Lemma 10, we have proved that \( g^k \) (see Line 7 of DIANA-SGD Algorithm 13) satisfies the unified Assumption 1 with

\[
A_1 = \frac{(1 + \omega)A}{m}, \quad B_1 = 1, \quad C_1 = \frac{(1 + \omega)C}{m},
\]

\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{\omega}{1 + \omega} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_k^i\|^2,
\]

\[
\rho = \min\{1 - \tau, 2\alpha - (1 - \alpha)\beta - 1 - \alpha^2 - \tau\},
\]

\[
A_2 = \tau A, \quad B_2 = B, \quad C_2 = \tau C,
\]

where \( A := \max_i(A_i, + (B_i, 1/L_i)) \), \( B := \frac{\omega(1 + \beta)\bar{L}\eta^2}{1 + \omega} \), \( C := \frac{1}{m} \sum_{i=1}^{m} C_i, + 2A\Delta_f, \Delta_f^* := f^* - \frac{1}{m} \sum_{i=1}^{m} f_i^* \), \( \tau := \alpha^2 + \frac{(1 + \omega)B}{m} \), \( \tau := \alpha^2 + \frac{(1 + \omega)B}{m} \), and \( \forall \beta > 0 \). Then this corollary is proved by plugging these specific values for \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \) into our unified Theorem 2. \( \square \)

E.2.3 DIANA-LSVRG method under PL condition

Corollary 23 (DIANA-LSVRG under PL condition) Suppose that Assumption 5, 6 and 8 hold. Let stepsize

\[
\eta \leq \frac{1}{L + 2L(1 + \omega)B'm^{-1}b^{-1}\rho^{-1}},
\]

then the number of iterations performed by DIANA-LSVRG (Algorithm 14) to find an \( \epsilon \)-solution of nonconvex federated problem (1.1) with (1.3), i.e. a point \( x^K \) such that \( \mathbb{E}[f(x^K) - f^*] \leq \epsilon \), can be bounded by

\[
K = \left(1 + \frac{2(1 + \omega)B'}{mb\rho}\right) L \log \frac{2\Delta_0}{\epsilon}, \tag{E.7}
\]

where \( B' := (1 - p)\bar{L}\eta^2\gamma^{-1} + Bb^{-1} \), \( \rho := \min\{p + p\gamma - \gamma - \tau, 2\alpha - (1 - \alpha)\beta - 1 - \alpha^2 - \tau\} \), \( \tau := \alpha^2 + \frac{(1 + \omega)B}{m} \), \( B := \frac{\omega(1 + \beta)\bar{L}\eta^2}{1 + \omega} + \bar{L}\eta^2b^{-1} \), and \( \forall \gamma, \beta > 0 \).

Proof of Corollary 23. According to Lemma 11, we have proved that \( g^k \) (see Line 8 of DIANA-LSVRG Algorithm 14) satisfies the unified Assumption 1 with

\[
A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,
\]

\[
D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{L^2}{b} \|x^k - w^k\|^2 + \frac{\omega}{1 + \omega} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_k^i\|^2,
\]

\[
\rho = \min\{p + p\gamma - \gamma - \tau, 2\alpha - (1 - \alpha)\beta - 1 - \alpha^2 - \tau\},
\]

\[
A_2 = 0 \quad B_2 = (1 - p)\bar{L}\eta^2\gamma^{-1} + B, \quad C_2 = 0,
\]

where \( B := \frac{\omega(1 + \beta)\bar{L}\eta^2}{1 + \omega} + \bar{L}\eta^2b^{-1} \), \( \tau := \alpha^2 + \frac{(1 + \omega)B}{m} \), and \( \forall \gamma, \beta > 0 \). Then this corollary is proved by plugging these specific values for \( A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho \) into our unified Theorem 5. \( \square \)

E.2.4 DIANA-SAGA method under PL condition

Corollary 24 (DIANA-SAGA under PL condition) Suppose that Assumption 5, 7 and 8 hold. Let stepsize

\[
\eta \leq \frac{1}{L + 2L(1 + \omega)B'm^{-1}b^{-1}\rho^{-1}},
\]
then the number of iterations performed by DIANA-SAGA (Algorithm 15) to find an $\epsilon$-solution of nonconvex federated problem (1.1) with (1.3), i.e. a point $x^K$ such that $\mathbb{E}[f(x^K) - f^*] \leq \epsilon$, can be bounded by

$$K = \left(1 + \frac{2(1 + \omega)B'}{mb\rho}\right) \frac{L}{\mu} \log \frac{2\Delta_0}{\epsilon},$$

(E.8)

where $B' := (1 - \frac{b}{n})\bar{L}^2 \eta^2 \gamma^{-1} + Bb^{-1}$, $\rho := \min\left\{\frac{b}{n}, \frac{m}{\gamma}, \gamma - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\right\}$, $\tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}$, $B := \frac{\omega(1 + \beta)L^2 \eta^2}{1 + \omega} + \bar{L}^2 \eta^2 b^{-1}$, and $\forall \gamma, \beta > 0$.

**Proof of Corollary 24.** According to Lemma 12, we have proved that $g^k$ (see Line 8 of DIANA-SAGA Algorithm 15) satisfies the unified Assumption 1 with

$$A_1 = 0, \quad B_1 = 1, \quad C_1 = 0,$$

$$D_1 = \frac{1 + \omega}{m}, \quad \sigma_k^2 = \frac{1}{mn} \sum_{i=1}^{m} \sum_{j=1}^{m} \frac{\bar{L}^2}{b} \|x^k - w_{i,j}^k\|^2 + \frac{\omega}{(1 + \omega)m} \sum_{i=1}^{m} \|\nabla f_i(x^k) - h_i^k\|^2,$$

$$\rho = \min\left\{\frac{b}{n}, \frac{b}{n} \gamma - \gamma - \tau, 2\alpha - (1 - \alpha)\beta^{-1} - \alpha^2 - \tau\right\},$$

$$A_2 = 0 \quad B_2 = (1 - \frac{b}{n})\bar{L}^2 \eta^2 \gamma^{-1} b^{-1} + B, \quad C_2 = 0,$$

where $B := \frac{\omega(1 + \beta)L^2 \eta^2}{1 + \omega} + \bar{L}^2 \eta^2 b^{-1}$, $\tau := \alpha^2 \omega + \frac{(1 + \omega)B}{m}$, and $\forall \gamma, \beta > 0$. Then this corollary is proved by plugging these specific values for $A_1, A_2, B_1, B_2, C_1, C_2, D_1, \rho$ into our unified Theorem 5. \qed