Research Article

An Easy-to-Understand Method to Construct Desired Distance-Like Measures

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Metrics and their weaker forms are used to measure the difference between two data (or other things). There are many metrics that are available but not desired by a practitioner. This paper recommends in a plausible reasoning manner an easy-to-understand method to construct desired distance-like measures: to fuse easy-to-obtain (or easy to be coined by practitioners) pseudo-semi-metrics, pseudo-metrics, or metrics by making full use of well-known t-norms, t-conorms, aggregation operators, and similar operators (easy to be coined by practitioners). The simple reason to do this is that data for a real world problem are sometimes from multiagents. A distance-like notion, called weak interval-valued pseudo-metrics (briefly, WIVP-metrics), is defined by using known notions of pseudo-semi-metrics, pseudo-metrics, and metrics; this notion is topologically good and shows precision, flexibility, and compatibility than single pseudo-semi-metrics, pseudo-metrics, or metrics. Propositions and detailed examples are given to illustrate how to fabricate (including using what "material") an expected or demanded WIVP-metric (even interval-valued metric) in practical problems, and WIVP-metric and its special cases are characterized by using axioms. Moreover, some WIVP-metrics pertinent to quantitative logic theory or interval-valued fuzzy graphs are constructed, and fixed point theorems and common fixed point theorems in weak interval-valued metric spaces are also presented. Topics and strategies for further study are also put forward concretely and clearly.

1. Introduction and Preliminaries

In many cases, the measure values of true data are not unique (but two or more) for uncertainty or complexity. For example, there are several agents in China who value and order all periodicals published in China. Peking University Library and Nanjing University Library are generally thought to be the best two and incomparable to each other. For a journal J, assume that the orders given by Peking University Library and the Nanjing University Library are m-th and n-th, respectively; then, m and n may be not the same in general. There are also many other examples. In 2012, breakthrough selected by the famous journal Science are different from those selected by the famous journal Nature; Gini coefficients in China in 2012 from two different agents are 0.481 and 0.61, respectively; the Chebyshev distance (resp., the Euclidean distance, the Manhattan distance or the city block distance, and the river distance) between two points (0,1) and (1,2) in the Euclidean plane $R^2$ is 1 (resp., $\sqrt{2}$, 2, 3). Please see Proposition 1 for definitions of these metrics; the effective distances used in cluster analysis are many and varied; a given asymptomatic infected people to Corona Virus Disease (COVID-19 for short) are thought to be highly contagious (which can be represented by a fuzzy number $A$).
by experts in one country but lowly contagious (which can also be represented by a fuzzy number $B$ that is much different from $A$) by experts in another country.

In practice, most people choose just one of the measure values (or choose the arithmetic mean of these measure values) as the true data; such a kind of dispose can be accepted only in rare cases (e.g., the information loss cannot be avoided or make almost no difference). To make an improvement in the disposal of these uncertain or complex data, at least two better theories (One is theoretically inspirational, another is application-motivated; both are based mainly on the idea of fuzzy set.) have been proposed which are mostly about measuring values of difference between two abstract "points" (precisely, two elements of a set) whose information or data can be provided by at least two different agents (but cannot be provided satisfactorily by one agent, see Example 1).

Example 1

(1) The distance between two fuzzy sets $A = \{(0.1/x), (0.3/y)\}$ and $B = \{(0.6/u), (0.8/v)\}$ cannot be expressed accurately (or satisfactorily) in a real number but can be expressed satisfactorily in a 4-element set $H = \{(0.1–0.6), [0.1–0.8], [0.3–0.6], [0.3–0.8]\} = \{(0.3, 0.5, 0.7)\}$, or an interval number $d = (0.3, 0.7)$. $d$ can be determined by two elements (even if it is an infinite set). Therefore, all sets involved here can be thought to be finite.

(2) The distance between two bodies $A = \{(x, y, z)\in R^3|x^2+y^2+z^2\leq e^2\}$ (i.e., the closed ball in the 3-dimensional Euclidean space $R^3$ with center $(0, 0, 0)$ = 0 and radius $e^2$) and $B = \{(x, y, z)\in R^3|(x–e^2–e)^2+y^2+z^2\leq e^2\}$ (i.e., the ball in $R^3$ with center $(e+e, 0, 0)$ and radius $e$) cannot be expressed accurately (or satisfactorily) in a real number but can be expressed satisfactorily in several numbers (where $0\leq e\leq e$). For instance, it can be expressed in a 3-element set $[a, \tilde{a}, \bar{a}]$ (in this way information loss can be almost avoided) or be expressed by any 2-element subset of $[a, \tilde{a}, \bar{a}]$ (in this way much more information loss can be avoided), where $a = 0 = \inf\{\rho_1(\tilde{x}, \tilde{y}) | \tilde{x} \in A, \tilde{y} \in B\}$ ($\rho_1$ is the ordinary Euclidean metric on $R^3$), $\tilde{a} = e + e$ is the Euclidean distance between the centroid $(0, 0, 0)$ of $A$ and the centroid $(e + e, 0, 0)$ of $B$, and $\bar{a} = 2e$ is the Hausdorff distance between $A$ and $B$ (notice that $a \leq \tilde{a} \leq \bar{a}$).

(3) During the time of COVID-19 (especially, the first three months), a lot of things (particularly, traveling and meeting) had to stop in China. The expected College back-to-University time can be forecasted rather than accurately based on several (even the first two of them) time series (the time series of suspected cases, the time series of imported cases, the time series of close contact cases, the time series of no symptoms cases, the time series of cluster infection cases, the time series of confirmed cases, etc.) but cannot be forecasted satisfactorily by one of them.

The first way to make an improvement is using a fuzzy metric. Several authors have introduced the concepts of fuzzy metric and fuzzy metric space from different points of view [1–4]. Erceg [1] defined a fuzzy pseudo-metric on a set consisting of fuzzy sets (e.g., fuzzifications of data or information to be disposed) by generalizing the Hausdorff distance between usual sets. The motivation behind the fuzzy metric of Kramosil and Michalek [3] was a statistical metric; recently, these kinds of fuzzy metric spaces have stimulated a lot of interest (see [5] and references herein for details). Kaleva and Seikkala’s metric [2] defined the distance between two points as a fuzzy number for the reason that sometimes uncertainty is due to fuzziness rather than randomness. As is known, Kaleva and Seikkala’s fuzzy metric spaces possess rich structures with suitable choices of binary operations. Much theoretical work related to Kaleva and Seikkala’s fuzzy metric spaces has been done in recent years (see [2, 5–9] and references herein). By presenting intuitive level forms for the triangle inequalities in the definition of Kaleva and Seikkala’s fuzzy metric, Huang and Wu [6] offered a new and convenient tool for the description and analysis of fuzzy metric spaces (cf. their subsequent work [7] on the existence and uniqueness of completion of special fuzzy metric spaces). Under some intuitive and mild assumptions, Fang [5] (as an improvement on Huang and Wu [7]) also proved the existence and the uniqueness of completion of fuzzy metric spaces. Xiao et al. [10] took a closer step toward possible applications of fuzzy metrics (in integral equations, differential equations, qualitative behavior, dynamic systems, and other nonlinear problems), in which the authors studied the existence and uniqueness of fixed points (under a weaker assumption) for nonlinear contractions in fuzzy metrics spaces in the sense of Kaleva and Seikkala [2]. By virtue of a level-cut method, they established relationships between a fuzzy metric and a family of quasi-metrics (so that the utilizing of results and skills in metric spaces becomes more and more possible).

The second way is using a dissimilarity measure or a distance measure, which is defined on a set consisting of special fuzzy sets (e.g., fuzzifications of data or information to be disposed); it takes many steps toward practical applications of metrics. Balopoulos et al. [11] defined a new family of distance measures (based on matrix norms) for binary operators on $[0, 1]$, which can also be used to measure the difference between two fuzzy sets on two finite sets. Bustince et al. [12] constructed distance measures, proximity measures, and fuzzy entropies by aggregating restricted dissimilarity functions in a special way. Liu [13] gave systematically an axiom definition of entropy, distance measure, and similarity measure of fuzzy sets; he also discussed basic relations between these measures. Fan et al. [14] defined a new divergence measure, study the relations between fuzzy entropy, fuzzy Hamming distance, and divergence measures defined. They obtain quite a general conclusion and solve a problem proposed by Liu [13]. Dissimilarity measure and distance measure have already found wide applications for their intuitiveness (see [15–21]).

As far as data are concerned, fuzzy metrics mentioned above have some shortcomings. It seems not very convenient
to apply these fuzzy metrics in practical problems because axioms satisfied by these metrics are complex; implementation of computing related to these fuzzy metric spaces is obviously difficult because operations (even if addition or subtraction) or sorting of fuzzy numbers cannot be realized in computers unless the fuzzy numbers involved are extremely simple (for example, they are triangle fuzzy numbers or interval numbers). Dissimilarity measures and distance measures mentioned above also have some faults. For example, they have few nice topological properties (see [8, 11–13, 16–21]) because they do not satisfy the triangle inequality in general; axioms they satisfy are also complex. These naturally urge people to find a kind of metrics (or their weaker forms) which are down to earth, i.e., they are theoretically good, intuitive (because intuition and examples always provide inspirations for both theoretical study itself and its applications in the real world), and easy-to-use. For example, try to find a metric (or its weaker form) such that the complexity of the distance value of two points is between that of a real number and that of a fuzzy number.

An immediately thought ways to construct such a metric (or its weaker form) \( \rho \) is to take it as a weighted mean of some well-known or usually used metrics \( \rho_1, \ldots, \rho_n \), i.e., let \( \rho = k_1 \rho_1 + \cdots + k_n \rho_n \), where \( k_1, \ldots, k_n \in (0, 1) \) satisfies \( k_1 + \cdots + k_n = 1 \). However, information lost in this way may be too much compared to a way based on interval numbers (unless the set \( \{k_1, \ldots, k_n\} \) is chosen as the optimal one such that \( \rho(x, y) \) is the fittest value for each \( (x, y) \in X^2 \).

Interval numbers or interval data appear in many cases (such as numerical analysis-handling rounding errors, computer-assisted proofs, global optimization, particularly, modeling uncertainty) because the data involved there cannot be accurately expressed in real numbers but can be expressed in interval numbers. The measure values of true data can be looked as an interval data, i.e., can use an interval number to denote the measure values of true data. For example, the distance between two data can be looked as an interval data, i.e., one can use an interval number to denote the measure values of true data. Similarly, axioms and propositions about interval numbers are also characterized by using axioms and connections between these notions and other known and related notions; propositions and detailed examples are given to illustrate how to fabricate (including using what “material”) an expected or demanded WIVP-metric (even interval-valued metric) in practical problems. Sections 3 and 4 are on theoretical applications of WIVP-metrics, where we demonstrate how to construct, by using some logic implication operators, some WIVP-metrics which may be useful in quantitative logic (cf. [23]) and quantitative reasoning (cf. [24]), and how to define well matched interval-valued metrics on interval-valued fuzzy graphs. Fixed point theorems and common fixed point theorems in WIVP-metrics are presented in Section 5. We end the paper with concluding remarks in Section 6.

Now, we present some preliminary notions needed in this paper.

Let \([0, 1]^R \) be the set of all fuzzy sets on \( R \) (i.e., the set of all mappings from \( R \) to \([0, 1] \)), where \( R \) is the set of all real numbers (also called the real line) and \([0, 1] \) is the closed unit interval of \( R \). For each subset \( Y \subseteq R \) and each \( b \in [0, 1] \), we use \( b_Y \) to denote the fuzzy set on \( R \) taking value \( b \) on \( Y \) and 0 elsewhere; we will make no distinction between \( 1_Y \) and \( Y \). If a fuzzy set \( \mu \in [0, 1]^R \) satisfies \( \mu(r) = 1 \) for some \( r \in R \) and \( [\mu_a, \mu_b] \) (i.e., a closed interval of \( R \)) for any \( a \in (0, 1) \), then we call \( \mu \) a fuzzy number (we will regard \( \mu - \mu \) as functions on \([0, 1], \) cf. [14, 24, 25]). The set of all fuzzy numbers is denoted by \( \mathcal{F} \). A fuzzy number \( \mu \) is called nonnegative if \( \supp \mu \subseteq [0, +\infty) \) (where \( \supp \mu = \{x \in R | \mu(x) > 0 \} \) is called the support of \( \mu \)). The set of all nonnegative fuzzy numbers is denoted by \( \mathcal{F}_+ \). Fuzzy numbers are the most commonly used fuzzy sets on the real line (see [25–30] and references therein); one of their applications is that they can be used to define fuzzy metric space (an important notion in fuzzy analysis). A binary operation \( \ast \) on \([0, 1], \) which is commutative (or symmetric), associative, and nondecreasing coordinately, is said to be a t-norm on \([0, 1] \) if it satisfies \( a \ast 1 = a = (\forall a \in [0, 1]); \ast \) is said to be a t-conorm on \([0, 1] \) if it satisfies \( a \ast 0 = a = (\forall a \in [0, 1]). \)

**Definition 1** (see [22]). A fuzzy metric space is a quadruple \((X, d, L, R)\) (in this case, \( d : X \times X \longrightarrow \mathcal{F} \) is called a fuzzy metric) which satisfies the following two conditions (\( \forall (x, y, z) \in X^3 \)):

1. \( d \) is positive, i.e., \( (d(x, y) = 0_R \Leftrightarrow x = y) \) and symmetric, (i.e., \( d(x, y) = d(y, x) ) \)
2. \( (i) \) if \( s \leq \lambda_1(x, z), t \leq \lambda_1(y, z), \) and \( s + t \leq \lambda_1(x, y), \) then \( d(x, y)(s + t) \geq L(d(x, z)(s), d(z, y)(t)) \)
   \( (ii) \) if \( s \geq \lambda_1(x, z), t \geq \lambda_1(y, z), \) and \( s + t \geq \lambda_1(x, y), \) then \( d(x, y)(s + t) \leq R(d(x, z)(s), d(z, y)(t)) \)

Here, \( d : X \times X \longrightarrow \mathcal{F} + \) is a mapping, \( L \) and \( R \) are operations on \([0, 1] \) which are symmetric, nondecreasing coordinate and satisfy \( L(0, 0) = 0 \) and \( R(1, 1) = 1 \), and \( [d(x, y)]_{\alpha} = [\lambda_\alpha(x, y), \nu_\alpha(x, y)] (\forall x, y \in X, \forall \alpha \in (0, 1]). \)

**Definition 2** (see [31]). An interval number (i.e., a special kind of fuzzy number) is a point \( a = (a - , a + ) \) in the 2-dimensional Euclidean space \( R^2 \) which satisfies \( a - \leq a + \). The set of all interval numbers (with the point-wise order \( \leq \)) is denoted by \( I(R) \) (Notice that a total order \([32, 33] \) was also defined on \( I(R) \): \( (a - , a + ) \leq (b - , b + ) \Leftrightarrow 0.5(a - + a \))
$+ < 0.5(b - + b +) or 0.5(a - + a +) = 0.5(b - + b +)$ but $a + a - + b -$. Moreover, we will identify a closed interval $[a, b] of R$, a point $(a, b)$ in $R^2$, and a fuzzy number $1_{[a, b]}$ since there exists a natural one-to-one correspondence between the set of all closed intervals of $R$ and $l(R)$. For any $\langle a, a + \rangle, \langle b, b + \rangle \in l(R)$ and each nonnegative real number $r$, define $\langle a, a + \rangle \oplus \langle b, b + \rangle = \langle a + b, a + b + \rangle, \langle a, a + \rangle \ominus \langle b, b + \rangle = \langle a - b, a + b + \rangle, \max(a - b, a + b +), \text{ and } r(\langle a, a + \rangle = \langle r(a), r(a) + \rangle).$ When $a + b > b + a + b$, write $\langle a, a + \rangle \succ \langle b, b + \rangle$ (or $\langle b, b + \rangle \prec \langle a, a + \rangle$); when $a = a + a = a$, write $\langle a, a + \rangle = a$. For every subinterval $J \subseteq l(R)$, write $l(J) = \langle a, a + \rangle \in l(R)$ or $a - a + e \in J$.

### 2. Definition and Examples of WIVP-Metric

In this section, we will define the notion of weak interval-valued pseudo-metrics (shortly, WIVP-metrics), exemplify in detail how to construct distance-like measures (including WIVP-metrics) desired in practice by fusing easy-to-obtain or easy-to-coin semi-pseudo-metrics, pseudo-metrics, or metrics based on operators $\wedge, \vee$, and simple aggregation operators. We also characterize WIVP-metric and its special forms intuitively so that practitioners can understand them easily.

**Definition 3.** Let $X$ be a set, $\rho : X \times X \rightarrow l(R)$ a mapping (where $R + = [0, +\infty))$. If $\rho_{-} = \rho_{0} : X \times X \rightarrow [0, +\infty)$ is a semi-pseudo-metric ($\rho_{-}$ is called a pseudo-semi-metric on $X$ if it is a semi-pseudo-metric on $X$ if it is a semi-pseudo-metric on $X$ satisfying $\rho_{-}(x, y) = 0 \iff \forall x, x \in X$ and $\rho_{-}(x, y) = \rho_{-}(y, x) (V(x, y) \in X \times X)$; $\rho_{-}$ is a called a pseudo-metric on $X$ if it is a semi-pseudo-metric on $X$ satisfying triangle inequality; $\rho_{-}$ is called a semi-metric on $X$ if it is if it is a semi-pseudo-metric on $X$ satisfying the mappings $\rho_{+} : X \times X \rightarrow [0, +\infty)$ is a pseudo-metric (resp., a pseudo-metric, a metric) on $X$, then $\rho$ is called a WIVP-metric on $X$ (resp., an interval-valued pseudo-metric on $X$, a weak interval-valued metric on $X$, an interval-valued metric on $X$) and $(X, \rho)$ is called a WIVP-metric space (resp., an interval-valued pseudo-metric space, a weak interval-valued metric space, an interval-valued metric space), where $\rho_{1} : R^{2} \rightarrow R$ and $\rho_{2} : R^{2} \rightarrow R$ are the first coordinate projection and the second coordinate projection, respectively (For a WIVP-metric on $X$, write $\mathcal{B} = \{B(x, a) : x \in X, a \in (0, +\infty)\}, \mathcal{B}_{1} = \{B(x, \langle a, a + \rangle) : x \in X, \langle a, a + \rangle \in l(R), \langle a, a + \rangle \succ 0\}, \mathcal{B}_{0} = \{B(x, \langle a, a + \rangle) : x \in X, \langle a, a + \rangle \succ 0\} \subseteq X, \mathcal{T}_{1} = \{l \cup a \in \mathcal{B}_{1}, \mathcal{T}_{2} = \{l \cup a \in \mathcal{B}_{0} \subseteq \mathcal{B}_{2}, f_{0}(x, < a, a + >) \succ 0\}$ belongs to $\mathcal{B}_{1}$, $\mathcal{T}_{1}, \mathcal{T}_{2}, \rho_{1}, \rho_{2} : 2 \times X \rightarrow \mathcal{B}_{1}, \mathcal{B}_{2} : 2 \rightarrow \mathcal{B}$ is a topology on $X$, and both $\mathcal{T}_{1}, \mathcal{T}_{2}, \rho_{1}, \rho_{2}$ are pre-topologies on $X$. It can be proved that $\mathcal{T}_{1}, \mathcal{T}_{1}, \rho$, and $\mathcal{T}_{2}, \rho$ have good topological properties.).

**Proposition 1.** Let $R^{3}$ be the 3-dimension Euclidean space and $\rho_{1}, \rho_{2}, \rho_{3}$, and $\rho_{4}$ be the Chebyshev metric, the Euclidean metric, the Manhattan metric or the city block metric, and the river metric on $R^{3}$, respectively (We will consider them to be metrics on $R^{3}$ by identifying a point $(a_{1}, a_{2}) \in R^{2}$ with a point $(a_{1}, a_{2}, 0) \in R^{3},$ defined by (where $\vec{a} = (a_{1}, a_{2}, a_{3}) \in R^{3}$ and $\vec{b} = (b_{1}, b_{2}, b_{3}) \in R^{3}$),

\[
\rho_{1}(\vec{a}, \vec{b}) = \max\{|a_{1} - b_{1}|, |a_{2} - b_{2}|, |a_{3} - b_{3}|\},
\rho_{2}(\vec{a}, \vec{b}) = \sqrt{(a_{1} - b_{1})^2 + (a_{2} - b_{2})^2 + (a_{3} - b_{3})^2},
\rho_{3}(\vec{a}, \vec{b}) = |a_{1} - b_{1}| + |a_{2} - b_{2}| + |a_{3} - b_{3}|,
\rho_{4}(\vec{a}, \vec{b}) = \sqrt{a_{1}^2 + a_{2}^2 + a_{3}^2} + \sqrt{b_{1}^2 + b_{2}^2 + b_{3}^2} - |a_{1} - b_{1}|, \quad a_{1} \neq b_{1}.
\]

Again, let $\rho_{0} = (1/3)\rho_{3}$. Then, the following premises hold:

1. $\rho_{0}$ is also a metric on $R^{3}$, $\rho_{0} \leq \rho_{1} \leq \rho_{2} \leq \rho_{3}$, and $\rho_{3}(\vec{a}, \vec{b}) \leq \rho_{4}(\vec{a}, \vec{b})$ if $\vec{a} = \vec{b}$ or $a_{1} \neq b_{1}$ but $|a_{2} - b_{2}|(a_{3} - b_{3}) - a_{2}b_{2} - a_{3}b_{3} \leq \sqrt{(a_{2}^2 + a_{3}^2)(b_{2}^2 + b_{3}^2)}$ (particularly, $a_{2} = b_{2}$).

2. The mapping $\rho_{i} : J \rightarrow l(R)$, defined by $\rho_{i}(\vec{a}, \vec{b}) = \rho_{i}(\vec{a}, \vec{b}), \rho_{j}(\vec{a}, \vec{b})$(or $\vec{a} = \vec{b}$), is an interval-valued metrics on $R^{3}$ for $0 \leq i < j < 3$, interval-valued metrics on $[0, +\infty)^{3}$ for $0 \leq i \leq j \leq 4$, and interval-valued metrics on $(-\infty, 0)^{3}$ for $0 \leq i \leq j \leq 4$.

3. The mapping $\rho_{e} : R^{3} \rightarrow l(R)$, defined by $\rho_{e}(\vec{a}, \vec{b}) = e_{0}\rho_{0}(\vec{a}, \vec{b}) + e_{1}\rho_{1}(\vec{a}, \vec{b}) + e_{2}\rho_{2}(\vec{a}, \vec{b}) + e_{3}\rho_{3}(\vec{a}, \vec{b}) + e_{4}\rho_{4}(\vec{a}, \vec{b})(e)(e \geq 0, i = 0, 1, 2, 3, 4)$ is an interval-valued metric (actually, a metric) (Each of these interval-valued metrics can be used to measure the difference between any two bodies $A$ and $B$ with the centroid set $\{\vec{a}, \vec{b} \} \subseteq R^{3}$).

4. Let $(w_{1}, w_{2}) \in [0, 1]^2$ satisfying $w_{1} + w_{2} = 1$. Then, the mappings $\rho_{i}, \rho_{i}(h, g) = \langle h_{w_{1}} + w_{2}, h_{w_{1}} + w_{2}, \rho_{i}(h, g) = \langle h_{w_{1}} + w_{2}, h_{w_{1}} + w_{2}, \rho_{w_{1}}(h, g) \rangle(\vee h_{w_{1}} + w_{2}, \rho_{w_{1}}, \rho_{w_{2}}, \rho_{i}(0, +\infty)) \rightarrow l(R)$, defined by $\rho_{i}(h, g)$ is a metric on $C([a, b], g)$ (the set of all continuous functions on $[a, b], a < b \rangle$ which can be used to measure the difference between two functions $g \in C([a, b]),$ where

\[
\bar{h}_{g} = \mathbf{1}_{[0, 1]} \int_{a}^{b} |f(t) - g(t)|dt,
\]

\[
\bar{h}_{g} = \max_{n \in [0, n]} |f(t) - g(t)|.
\]

**Proposition 2.** Let $Y \neq \emptyset$ and $\vec{w} = (w_{1}, w_{2})$ a weight vector (i.e., it satisfies $(w_{1}, w_{2}) \in [0, 1]^2$ and $w_{1} + w_{2} = 1$). Then,
Complexity

(1) Consider three mappings \(\vec{d}_1, w, \vec{d}_w, 2, \vec{d}_{1,2}\) from \(\mathbb{Y}^2 = [0, 1]^2 \times [0, 1]^2\) to \(1(R+)\), defined by \(((\Phi, \Psi) \in \mathbb{Y}^2)\vec{d}_1, w(\Phi, \Psi) = \langle d_1(\Phi, \Psi), d_w(\Phi, \Psi)\rangle\), \(\vec{d}_w, 2(\Phi, \Psi) = \langle d_w(\Phi, \Psi), d_1(\Phi, \Psi)\rangle\), \(\vec{d}_{1,2}(\Phi, \Psi) = \langle d_1(\Phi, \Psi), d_2(\Phi, \Psi)\rangle\), where
\[d_1(\Phi, \Psi) = \inf[\Phi(y) - \Psi(y)] y \in Y,\]
\[d_2(\Phi, \Psi) = \sup[\Phi(y) - \Psi(y)] y \in Y,\]
and \(d_w(\Phi, \Psi) = w_1d_1(\Phi, \Psi) + w_2d_2(\Phi, \Psi)\). The last two are WIVP-metrics on \(\mathbb{Y}^1\) (but the first is not in general); all of them can be used to measure the difference between any two fuzzy sets \(\Phi, \Psi \in \mathbb{Y}^1\).

(2) For each \(d \in \{p_0, p_1, p_2, p_3, p_4, p_5\}\), consider three mappings \(\vec{d}_1, w, \vec{d}_w, 2, \vec{d}_{1,2}\) from \(\mathbb{Y}^2 = [0, 1]^2 \times [0, 1]^2\) to \(1(R+)\), defined by \(((\Phi, \Psi) \in \mathbb{Y}^2)\vec{d}_1, w(\Phi, \Psi) = \langle d_1(\Phi, \Psi), d_w(\Phi, \Psi)\rangle,\)
\(\vec{d}_w, 2(\Phi, \Psi) = \langle d_w(\Phi, \Psi), d_1(\Phi, \Psi)\rangle\), \(\vec{d}_{1,2}(\Phi, \Psi) = \langle d_1(\Phi, \Psi), d_2(\Phi, \Psi)\rangle\), where
\[d_1(\Phi, \Psi) = \inf[\Phi(y) - \Psi(y)] y \in Y,\]
\[d_2(\Phi, \Psi) = \sup[\Phi(y) - \Psi(y)] y \in Y,\]
\[d_w(\Phi, \Psi) = w_1d_1(\Phi, \Psi) + w_2d_2(\Phi, \Psi)\] and the infimum and supremum are taken in \((0, \infty)\) (Of course, the infimal and supremal in (2) and (3) can also be taken in \((0, \infty)\)). The last two are WIVP-metrics on \(\mathbb{Y}^3\) (but the first is not in general); all of them can be used to measure the difference between any two interval-valued fuzzy sets, intuitionistic fuzzy sets, or bipolar fuzzy sets [34-36] \(\Phi, \Psi \in \mathbb{Y}^3\).

Proof. We only show that \(d_w(\Phi, \Psi)\) in (1) does not satisfy the triangle inequality in general. Actually, take \(U = [x, y], A = 1_{[x, z]}, B = 1_{[y, 1]}, C = 1_{[y, 1]}\) and \(\vec{u}\) = (0.6, 0.4). Then,
\[d_w(A, C) = 0.6 \times 1 + 0.4 \times 1 = 1 \leq 0.8 = 0.6 \times 0.4 \times 1 + 0.6 \times 0.4 \times 1 = d_w(A, B) + d_w(B, C).\]

Example 2

(1) Let (The data needed here can also be taken from Example 5.) \(A = \{(0.1/x), (0.2/y), (0.1/z)\}\) and \(B = \{(1/x), (0.9/y), (1/z)\}\) be feature fuzzy sets representing two physical entities (e.g., patients), and \(C = \{(0.6/x), (0.5/y), (0.6/z)\}\) the third.

If we take a weight vector \(\vec{w} = (0.5, 0.5)\), as \(\vec{d}_{1,2}(C, A) = (0.3, 0.5) \leq 0.4 = \vec{d}_{1,2}(C, B)\), \(C\) belongs to class \(A\) (with respect to \(\vec{d}_{1,2}\)) as \(d_w(C, A) = (0.3, 0.4) \leq 0.4 \leq \vec{d}_{1,2}(C, B)\), \(C\) belongs to class \(B\) (with respect to \(\vec{d}_{1,2}\)) as \(d_w(2, C, B) = 0.4 \leq (0.4, 0.5) = \vec{d}_{1,2}(2, C, A)\), \(C\) belongs to class \(B\) (with respect to \(\vec{d}_{1,2}\)).

If we take two weight vectors \(\vec{w} = (0.5, 0.5)\) and \(\vec{v} = (0.4, 0.6)\), then \(d_w(C, A) = 0.5 \times 0.3 + 0.5 \times 0.4 = 0.4, \vec{d}_{1,2}(C, B) = 0.5 \times 0.4 + 0.5 \times 0.4 = 0.4,\) and \(d_w(C, B) = 0.4 \times 0.4 + 0.6 \times 0.4 = 0.4.\) Thus, \(d_w(C, A) = (0.4, 0.42)\) and \(d_{1,2}(C, B) = 0.4.\) As \(\vec{d}_{1,2}(w(C, A)) = (0.3, 0.4, 0.42) \leq 0.4 = \vec{d}_{1,2}, w(C, B), C\) belongs to class \(A\) (with respect to \(\vec{d}_{1,2}\)) as \(d_w(2, C, B) = 0.4 \leq (0.4, 0.42), 0.5 = \vec{d}_{1,2}(2, C, A), C\) belongs to class \(B\) (with respect to \(\vec{d}_{1,2}\)).

For class \(C\) belongs to class \(B\) (with respect to \(\vec{d}_{1,2}\)), \(\vec{d}_{1,2}(\Phi, \Psi)\) \((\Phi, \Psi \in \mathbb{Y}^3, \mathbb{Y}^2, \mathbb{Y}^1)\).
and \((\mathcal{P}_e)_{12}, w\). Take \(e_0 = e_1 = e_2 = e_3 = e_4 = 0.2\). Then, \((\mathcal{P}_e)_{12}, 2(C, A) \leq (\mathcal{P}_e)_{12}, 2(C, B)\), thus \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w\)).

(3) Let \(A = [(0.1, 0.2, 0.1)/x), ((0.3, 0.4, 0.3)/y), ((0.1, 0.2, 0.1)/z)\] and \(B = [(0.8, 0.1, 0.1)/x), ((0.7, 0.2, 0.1)/y), ((0.8, 0.1, 0.1)/z)\] be feature picture fuzzy sets representing two physical entities (e.g., patients), \(C = [(0.6, 0.1, 0.1)/x), ((0.5, 0.1, 0)/(y), ((0.6, 0.1, 0.1)/z)\] the third, and \(\bar{w} = (0.5, 0.5)\). As \((\mathcal{P}_e)_{12}, (C, A) = (1/3)(0.2, 0.4) \leq (1/3)(0.6, 0.8) = (\mathcal{P}_e)_{12}, (C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w\)\); as \((\mathcal{P}_e)_{12}, w(C, A) = (1/3)(0.2, 0.3) \leq (1/3)(0.6, 0.7) = (\mathcal{P}_e)_{12}, w(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w\)) as \((\mathcal{P}_e)_{12}, 2(C, A) = (1/3)(0.3, 0.4) \leq (1/3)(0.7, 0.8) = (\mathcal{P}_e)_{12}, 2(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w)\).

As \((\mathcal{P}_e)_{12}, (C, A) = (\mathcal{P}_e)_{12}, (C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w\)\); as \((\mathcal{P}_e)_{12}, w(C, A) = (\mathcal{P}_e)_{12}, w(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w\)) as \((\mathcal{P}_e)_{12}, 2(C, A) = (\mathcal{P}_e)_{12}, 2(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w)\).

As \((\mathcal{P}_e)_{12}, (C, A) = (\mathcal{P}_e)_{12}, (C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w)\); as \((\mathcal{P}_e)_{12}, w(C, A) = (\mathcal{P}_e)_{12}, w(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w\)) as \((\mathcal{P}_e)_{12}, 2(C, A) = (\mathcal{P}_e)_{12}, 2(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w)\).

As \((\mathcal{P}_e)_{12}, (C, A) = (\mathcal{P}_e)_{12}, (C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w)\); as \((\mathcal{P}_e)_{12}, w(C, A) = (\mathcal{P}_e)_{12}, w(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w\)) as \((\mathcal{P}_e)_{12}, 2(C, A) = (\mathcal{P}_e)_{12}, 2(C, B)\), \(C\) belongs to class \(A\) (with respect to \((\mathcal{P}_e)_{12}, w)\).

Example 3

(1) Analogously, we can predict \(A(n+1)\) from a given time series \(A(1), A(2), \ldots, A(n)\) \((n > 3)\) in the following way: Firstly, fix (maybe by experts) a natural number \(n < n\) (say, \(n = 3\)) and a set \(\{w_1, w_2, w_3\} \subset (0,1)\) satisfying \(w_1 < w_2 < w_3\) and \(w_1 + w_2 + w_3 = 1\). Secondly, compute the differences \(r_i = (i = 1, 2, \ldots, n - 3)\).
Example 4. Now, we exemplify an application of the idea of WIVP-metrics in pattern recognition (i.e., COVID-19 diagnosis). Consider the following symptom data (see Table 1), involving 5 symptoms (asthma, sore throat, cough, fever, age), and diagnosis results, involving yes (briefly, Y) and no (briefly, N), of 7 patients given by expert physicians in a Chinese hospital in Nanjing:

From this, we can get the following 7 mappings (patients):
Table 1: Symptom data and diagnosis results.

|          | $P_1$ | $P_2$ | $P_3$ | $P_4$ | $P_5$ | $P_6$ | $P_7$ |
|----------|-------|-------|-------|-------|-------|-------|-------|
| Asthma   | 39    | 41    | 52    | 45    | 39    | 55    | 60    |
| Sore throat| 48    | 51    | 48    | 53    | 62    | 55    | 57    |
| Cough    | 18    | 41    | 32    | 44    | 49    | 36    | 37    |
| Fever    | 37.8  | 38    | 38.5  | 37.8  | 38    | 38    | 38.5  |
| Age      | 67    | 41    | 44    | 68    | 70    | 50    | 54    |
| Result   | N     | Y     | N     | Y     | Y     | Y     | Y     |

$$P_1 = \begin{bmatrix}
39 & 48 & 18 & 37.8 & 67
\end{bmatrix}_{\text{asthma sore throat cough fever age}}$$

$$P_2 = \begin{bmatrix}
41 & 51 & 41 & 38 & 41
\end{bmatrix}_{\text{asthma sore throat cough fever age}}$$

$$P_3 = \begin{bmatrix}
60 & 57 & 37 & 38.5 & 54
\end{bmatrix}_{\text{asthma sore throat cough fever age}}$$

Take other 2 patients in the same hospital for test:

$$P_8 = \begin{bmatrix}
59 & 63 & 60 & 28 & 37.9 & 67
\end{bmatrix}_{\text{asthma sore throat cough fever age}}$$

$$P_9 = \begin{bmatrix}
60 & 64 & 47 & 43 & 38.6 & 70
\end{bmatrix}_{\text{asthma sore throat cough fever age}}$$

Obtain the average $d_{8,e,Y}$

Obtain the average $d_{8,e,N}$

Obtain the average $d_{8,v,Y}$

Obtain the average $d_{8,v,N}$

Compare $(d_{8,e,N}, d_{8,v,N})$ and $(d_{8,e,Y}, d_{8,v,Y})$

Make a conclusion

Notice that both $P_2$ and $P_3$ have two asthma values (we will take their center in the following computation for simplicity) because he/she ate a kind of TCM-like food before taking the two values. As the group of experts give two different weight vectors $\overrightarrow{w} = (e_1, e_2, e_3, e_4, e_5) = (2, 1.5, 30, 1)$ and $\overrightarrow{v} = (v_1, v_2, v_3, v_4, v_5) = (4, 3, 10, 60, 1)$ for importance of vector of symptom $s$ = (asthma, sore throat, cough, fever, age), we finish this decision-making problem in the following nine steps (see Figure 1).

**Step 1.** Compute the difference between $P_8$ and those with diagnosis results Y using a metric rely on $\overrightarrow{w}$ (there are many cases on choices of $\rho_e$). $\rho_e(P_2, P_8) = e_1|41 - 61| + e_2|41 - 28| + e_3|38 - 37.9| + e_4|41 - 67| = 143$, $\rho_e(P_3, P_8) = e_1|61 - 45| + e_2|60 - 53| + e_3|44 - 28| + e_4|37.8 - 37.9| + e_5|44 - 67| = 145$, $\rho_e(P_8, P_8) = e_1|61 - 55| + e_2|55 - 60| + e_3|36 - 28| + e_4|38 - 37.9| + e_5|50 - 67| = 77$, $\rho_e(P_9, P_8) = e_1|61 - 60| + e_2|57 - 60| + e_3|37 - 28| + e_4|38.5 - 37.9| + e_5|54 - 67| = 77$. Thus we obtain the average $d_8$, $e$, $Y = 132.6$.

**Step 2.** Compute the difference between $P_8$ and those with diagnosis results N using a metric rely on $\overrightarrow{v}$. $\rho_v(P_1, P_8) = e_1|39 - 61| + e_2|48 - 60| + e_3|18 - 28| + e_4|37.8 - 37.9| + e_5|67 - 67| = 109$, $\rho_v(P_3, P_8) = e_1|52 - 61| + e_2|48 - 60| + e_3|32 - 28| + e_4|38.5 - 37.9| + e_5|44 - 67| = 91$. Thus, we obtain the average $d_8$, $e$, $N = 100$.

**Step 3.** Compute the difference between $P_8$ and those with diagnosis results Y using a metric rely on $\overrightarrow{w}$. $\rho_e(P_2, P_8) = 103$, $\rho_e(P_3, P_8) = 71$, $\rho_e(P_5, P_8) = 133,

$\rho_e(P_7, P_8) = 95$, $\rho_e(P_7, P_8) = 63$. Thus, we obtain an average $d_8$, $e$, $Y = 93$.

**Step 4.** Compute the difference between $P_9$ and those with diagnosis results N using a metric rely on $\overrightarrow{w}$. $\rho_e(P_1, P_9) = 199$, $\rho_e(P_7, P_9) = 105$. Thus we obtain an average $d_8$, $e$, $N = 152$.

**Step 5.** Compute the difference between $P_8$ and those with diagnosis results Y using a metric rely on $\overrightarrow{v}$. $\rho_v(P_2, P_8) = 269$, $\rho_v(P_4, P_8) = 252$, $\rho_v(P_5, P_8) = 433$, $\rho_v(P_6, P_8) = 128$, $\rho_v(P_7, P_8) = 152$. Thus we obtain an average $d_8$, $v$, $Y = 246.8$.

**Step 6.** Compute the difference between $P_8$ and those with diagnosis results N using a metric rely on $\overrightarrow{v}$. $\rho_v(P_1, P_8) = 230$, $\rho_v(P_2, P_8) = 171$. Thus we obtain an average $d_8$, $v$, $N = 200.5$.

**Step 7.** Compute the difference between $P_9$ and those with diagnosis results Y using a metric rely on $\overrightarrow{w}$. $\rho_e(P_2, P_9) = 181$, $\rho_e(P_4, P_9) = 146$, $\rho_e(P_5, P_9) = 281$, $\rho_e(P_6, P_9) = 178$, $\rho_e(P_7, P_9) = 120$. Thus we obtain an average $d_8$, $v$, $Y = 181.2$.

**Step 8.** Compute the difference between $P_9$ and those with diagnosis results N using a metric rely on $\overrightarrow{v}$. $\rho_v(P_1, P_9) = 396$, $\rho_v(P_2, P_9) = 185$. Thus we obtain an average $d_8$, $v$, $N = 290.5$.

**Step 9.** As $d_8$, $e$, $N$, $d_8$, $v$, $N$, $X = \{100, 200.5\} \leq \{132.6, 246.8\} = \{d_8$, $e$, $Y$, $d_8$, $v$, $Y\}$, $P_8$ is $N$ (which is the same as the diagnosis result given by expert physicians in that hospital); as $d_8$, $e$, $Y$, $d_8$, $v$, $Y = \{93, 181.2\} \leq \{152, 290.5\} = \{d_8$, $e$, $N$, $d_8$, $v$, $N\}$, $P_9$ is $Y$ (which is also the same as the diagnosis result given by expert physicians in that hospital).

**Proposition 4**

(1) For a mapping $\rho : X^2 \rightarrow 1(R +)$, consider the following conditions:

$\rho_0(x, x) = 0$ (\forall x \in X)

$\rho_1(x, y) = 0$ if $x = y$ (\forall [x, y] \subseteq X)

$\rho_2(x, y) = \rho(y, x) (\forall [x, y] \subseteq X)$

$\rho_3(x, y) = \rho(x, z) \rho(y, z) (\forall [x, y, z] \subseteq X)$

$\rho_4(p_2 \circ \rho(x, y) \leq p_2[\rho(x, z), \rho(y, z)] \circ \rho(x, z) + p_2 \circ \rho(x, y) (\forall [x, y, z] \subseteq X)$
Then, ρ is a WIVP-metric (resp., an interval-valued pseudo-metric, a weak interval-valued metric, an interval-valued metric) on X if it satisfies (M0) + (M2) + (M4) (resp., (M0) + (M2) + (M3), (M1) + (M2) + (M4), (M1) + (M2) + (M3)).

Every interval-valued metric space (X, ρ) can be looked as a special fuzzy metric space, where we define L and R as L(a, b) = min[a, b] (∨ (a, b) ∈ [0, 1] × [0, 1]) and R(a, b) = max[a, b] (∨ (a, b) ∈ [0, 1] × [0, 1]), and set d = ρ.

3. WIVP-Metrics Pertinent to Logic Theory

An logic implication operator is a mapping I : [0, 1] × [0, 1] → [0, 1] which satisfies some conditions (see [41]). There are many well-known logic implication operators (see [23, 24, 41]); some of them are defined as follows:

(i) Boolean implication operator: I_B(a, b) = 0 if a = 1, b = 0 or 1 (otherwise)

(ii) Gaines-Rescher implication operator: I_{GR}(a, b) = 1 if a ≤ b or 0 if (a ≤ b)

(iii) Goguen implication operator: I_G(a, b) = 1 if (a = 0) or 1 ∧ (b / a) (if a ≠ 0)

(iv) Gödel implication operator: I_G(a, b) = 1 if (a ≤ b) or b (if a ≤ b)

(v) Kleene-Dienes implication operator: I_{KD}(a, b) = (1 − a) ∨ b

(vi) Lukasiewicz implication operator: I_L(a, b) = (1 − a + b) ∧ 1

(vii) Mandam implicator operator: I_M(a, b) = a ∧ b

(viii) Product implication operator: I_P(a, b) = 1 if (a ≤ b) or (b / a) (if a ≤ b)

(ix) Wang implication operator: I_W(a, b) = 1 if (a ≤ b) or (1 − a) ∨ b (if a ≤ b)

(x) Reichenbach implication operator: I_R(a, b) = 1 − a + ab

(xi) Yager implication operator: I_Y(a, b) = b^a ( ∀ a, b ∈ [0, 1])

(xii) Zadeh implication operator: I_Z(a, b) = (1 − a) ∨ (a ∧ b)

In this section, we will demonstrate how to construct, by using some of these logic implication operators, some WIVP-metrics that may be used in quantitative logic (cf. [23]) and quantitative reasoning (cf. [24]).

Definition 4 (cf. [42])

(1) Let S = {p_1, p_2, . . .} be a countable set (where p_i ≠ p_j if i ≠ j), a unary operator, ∨ and → binary operators, and F(S) the free algebra of type { , , → } generated by S. Elements of S are called atomic formulae (or atomic propositions), and elements of F(S) are called formulae (or propositions).

(2) [0, 1] can be looked as an algebra of type { , , → } if we define the unary operator : [0, 1] → [0, 1] and the two binary operators := [0, 1] × [0, 1] → [0, 1] as follows: a → := 0 ( ∀ a ∈ [0, 1]), a ∨ b = max{a, b} ( ∀ a, b ∈ [0, 1]), a → b = a ∧ ( ∀ a, b ∈ [0, 1]), where I := [0, 1] × [0, 1] → [0, 1] is a logic implication operator. Furthermore, for each A ∈ F(S), there exists a unique finite subset S_A ⊆ F(S) (without loss of generality we assume S_A = {p_1, p_2, . . ., p_n}) such that A can be represented uniquely by S_A and ∨ → (written as A = A(p_1, p_2, . . ., p_n)) or 0 (if A tightens). Substitute x_i for p_i in A(p_1, p_2, . . ., p_n) (k = 1, 2, . . ., n) and keep the logic connectives in A unchanged, then we obtain an expression A(x_1, x_2, . . ., x_n) and thus an n-variable function A_I : [0, 1]^n → [0, 1] which is called the I-function corresponding to A. For example, if A = p_1 → (p_2 ∨ p_3), then A(x_1, x_2, x_3) = (1 - x_1, max{x_2, x_3}).

(3) A mapping v : F(S) → [0, 1] which preserves operations , ∨ and → is called an I-valuation on F(S). The set of all I-valuations is written as Ω(I).

(4) Let A, B ∈ F(S). If v(A) = v(B) (∀ ∈ Ω(I)), then A and B are said to be I-logically equivalent.

Lemma 1. If the formulae A and B in F(S) are I-logically equivalent, then A_I = B_I (where I is a logic implication operator).

Proof. Without loss of generality, we assume S_A = {p_1, p_2, . . ., p_m}, S_B = {p_1, p_2, . . ., p_n}, and m + 1 = n. Let A* = A ∧ (r) (where r ∈ S_B - S_A), then A* = S_B. For each x = (x_1, x_2, . . ., x_m) ∈ [0, 1]^m, there exists an I-valuation v : F(S) → [0, 1] on F(S) which satisfies v(x_i) = v(x_i) (i = 1, 2, . . ., n) since F(S) is a free algebra. As A and B are R-logically equivalent, A_I(x) = A_I(x) = v → (A) = v → (B) = B_I(x), which means A_I = B_I. □

Lemma 2

(1) For any A, B ∈ F(S), define A ~ B if and only if A and B is I_{Lu}-logically equivalent. Then, ~ is an equivalence relation on F(S). The equivalence class determined by A in F(S) is written [A], and the quotient set determined by ~ is written F(S) / ~.

(2) The mapping d_{Lu} : F(S) × F(S) → [0, ∞), defined by (∀ A, B) ∈ F(S) d_{Lu}(A, B) = 1 − Δ(A_I(A), A_I(B)), A_I(x) ) ∧ A_I(B_I(x)) ) ∧ A_I(x) ) ) dI is a pseudo-metric on F(S) (A, B, Go, G, 0), where Δ is the integral domain related (A, B).

(3) For each ∈ [0, 1], the mapping d_{GR} : F(S) × F(S) → [0, ∞), defined by 1 − Δ(A_I(A), A_I(B)) = G, 0), where Δ is a pseudo-metric on F(S).

(4) d_{GR} ≥ d_{GR}(0 ≤ ≤ 1). Notice also that d_{GR}(A, B) = 0, A ~ B, 1, A + B.
Remark 1. Let \( \rho_{GR} \) be a metric on \( F(S) \) which satisfies \( \rho_{GR}(0 \leq \epsilon_1 < \epsilon_2 < 1) \), where \( \rho_{GR}(\epsilon \in [0,1]) \) is defined by \( \rho_{GR}(A, B) = d_{GR}(A, B) \) for all \( A, B \in F(S) \).

Remark 2. For any \( \rho_{GR} \in [0,1] \) is a family of metrics on \( F(S) \) which satisfy \( \rho_{GR}(0 \leq \epsilon_1 < \epsilon_2 < 1) \), where \( \rho_{GR}(\epsilon \in [0,1]) \) is defined by \( \rho_{GR}(A, B) = d_{GR}(A, B) \) for all \( A, B \in F(S) \).

Lemma 2 (2) is Theorem 6 in [40].

Theorem 1

(1) \( (F(S), d_1) \) is a WIVP-metric space (\( d_1 \in [d_{GR}, d_{L}]) \) if \( \rho_{GR} \).

(2) \( (F(S), \rho_{GR}) \) is a weak interval-valued metric space (\( \rho_{GR} \) is defined by \( \rho_{GR}(\epsilon \in [0,1]) \)).

(3) \( (F(S), \rho_{GR}) \) is a weak interval-valued metric space (\( \rho_{GR} \) is defined by \( \rho_{GR}(\epsilon \in [0,1]) \)).

Proof. It follows from Lemma 2 (including its proof) and Remarks 1.

4. Interval-Valued Metrics on Interval-Valued Fuzzy Graphs

Metric graph theory abounds in applications (e.g., it is applicable in such different areas as location theory, theoretical biology and chemistry, combinatorial optimization, and computational geometry, see [43], p.99–121 for details). In this section, we extend the notion of metrics on a graph to interval-valued metrics on an interval-valued fuzzy graph (particularly, on a fuzzy graph) and give some related examples.

An \( I \)-graph (where \( I \) is a completely distributive complete lattice with the least element 0) is a triple \( G = (V, \sigma, \mu) \) consisting of a nonempty finite set \( V \) and a pair of mappings \( \sigma : V \rightarrow I \) and \( \mu : V \times V \rightarrow I \) which satisfies \( \mu(x, y) = \mu(y, x) \). The underlying graph of \( G \) is defined as \( [G] = (V, E) \), where \( E = \{x \in V \mid \mu(x, y) > 0\} \). An \( I \)-graph \( G = (V, \sigma, \mu) \) is said to be connected if its underlying graph \( [G] = (V, E) \) is connected, i.e., for any 2-element subset \( \{x, y\} \subseteq V \), there exists a \( m(x, y) \)-element subset \( \{z_1, z_2, \ldots, z_m(x, y)\} \subseteq V \) such that \( x = z_1, z_2, \ldots, z_m(x, y) \in V \). The cardinality of \( G \) is defined as \( |G| = |V| \) (the cardinality of the interval-valued fuzzy graph).

Definition 5. Let \( G = (V, \sigma, \mu) \) be a \( [0,1] \)-graph (called also fuzzy graph [42]), and \( \epsilon \in [0,1] \). For each \( x \in V \), let \( \rho_1(x, x) = \rho_2(x, x) = 0 \). For any \( x, y \in V \), define \( \rho(x, y) = |V| \) (the cardinality of the interval-valued fuzzy graph).

Theorem 2. Let \( G = (V, \sigma, \mu) \) be an \( [0,1] \)-graph (called also interval-valued fuzzy graph). For any \( x, y \in V \), let

\[
\rho_{xy} = \begin{cases} 0, & x = y, \\ \frac{|P|}{m(P)} & x \neq y \text{ and } P_{xy} \neq \emptyset, \\ \frac{|V|^2}{m(V)} & x \neq y \text{ and } P_{xy} = \emptyset, \\ \end{cases}
\]

Then, the mappings \( \rho_1, \rho_2 : V \times V \rightarrow [0, +\infty) \) are metrics on \( V \) (called metrics on the fuzzy graph G).

Remark 2. It is easy to verify \( \rho_{xy} \leq \rho_{xy} \) for all \( \epsilon \), \( \epsilon \in \{0,1\} \) satisfying \( \epsilon_1 \leq \epsilon_2 \), thus we obtain a family \( \rho_{xy} \leq \rho_{xy} \in [0,1] \) of interval-valued metrics on \( V \) (called interval-valued metrics on the fuzzy graph G).

Theorem 2. Let \( G = (V, \sigma, \mu) \) be an \( [0,1] \)-graph (called also interval-valued fuzzy graph). For any \( x, y \in V \), let

\[
\rho_{xy} = \begin{cases} 0, & x = y, \\ \frac{|P|}{m(P)} & x \neq y \text{ and } P_{xy} \neq \emptyset, \\ \frac{|V|^2}{m(V)} & x \neq y \text{ and } P_{xy} = \emptyset, \\ \end{cases}
\]

where
and \( m(\mu) = \min\{|s, t| [s, t] \in E\} \). Then, \( \rho \) is an interval-valued metric on \( V \) (called interval-valued metric on the interval-valued fuzzy graph \( G \)).

5. Fixed Point Theorems and Common Fixed Point Theorems in WIVP-Metrics

Definition 6

(1) A sequence \( \{x_n\} \) in a WIVP-metric space \((X, \rho)\) is said to be a Cauchy sequence if, for each \((\varepsilon, -\varepsilon) \ni 0\), there exists a positive integer \( n_0 \) such that \( \rho(x_n, x_{n_0}) < (\varepsilon - \varepsilon) \forall n \geq n_0 \); \( \{x_n\} \) is said to be convergent in \((X, \rho)\) if there exists an \( x \in X \) such that \( \{x_n\} \) converges to \( x \) (i.e., for each \((\varepsilon, -\varepsilon) \ni 0\), there exists a positive integer \( n_0 \) such that \( \rho(x_n, x) < (\varepsilon - \varepsilon) \forall n \geq n_0 \)).

(2) A WIVP-metric space \((X, \rho)\) is said to be complete if every Cauchy sequence in \((X, \rho)\) is convergent.

It is not difficult to verify the following.

Lemma 3. A WIVP-metric space \((X, \rho)\) is complete if and only if \((X, \rho +)\) is complete.

The main results of this section are the following.

Theorem 3. Let \((X, \rho)\) be a complete WIVP-metric space. Then, \( f : X \longrightarrow X \) has a unique fixed point in \( X \) if it satisfies one of the following conditions:

(1) \( \rho + (f^x(x), g^y(y)) \leq k \rho + (x, y) \forall x, y \in X \), where \( k \in [0,1) \) is a constant.

(2) \( \rho + (f(x), f(y)) \leq k \rho + (x, f(x)) + \rho + (y, f(y)) \forall x, y \in X \), where \( k \in [0, (1/2)] \) is a constant.

(3) \( \rho + (f(x), g(y)) \leq k \max \rho + (x, f(x)) + \rho + (y, g(y)) \forall x, y \in X \), where \( k \in [0, (1/2)] \) is a constant.

(4) \( \rho + (f(x), f(y)) \leq k \rho + (x, f(x)) + \rho + (y, f(y)) + \rho + (x, y) \forall x, y \in X \), where \( k \) is a positive integer.

(5) \( \rho + (f(x), g(y)) \leq k \rho + (x, f(y)) + \rho + (y, f(y)) \forall x, y \in X \), where \( k \in [0, (1/2)] \) is a constant.

(6) \( \rho + (f(x), g(y)) \leq k \rho + (x, f(y)) + \rho + (y, f(y)) + \rho + (x, y) \forall x, y \in X \), where \( k \) is a positive integer.

(7) \( \rho + (f^x(x), g^y(y)) \leq k \rho + (x, f^x(x)) + k \rho + (y, g^y(y)) + k \rho + (x, y) \forall x, y \in X \), where \( k \in [0, (1/2)] \) is a constant.

(8) \( \rho + (f^x(x), g^y(y)) \leq k \rho + (x, f^x(x)) + k \rho + (y, f^y(y)) + k \rho + (x, y) \forall x, y \in X \), where \( k \) is a positive integer.

Theorem 4. Let \((X, \rho)\) be a complete weak interval-valued metric space. Then, \( f, g : X \longrightarrow X \) have common fixed point in \( X \) if they satisfy one of the following conditions (where \( s \) and \( t \) are fixed positive integers):

(1) \( \rho + (f^x(x), g^y(y)) \leq k \rho + (x, y) \forall x, y \in X \), where \( k \in [0, 1) \) is a constant.

(2) \( \rho + (f^x(x), g^y(y)) \leq k \rho + (x, f^x(x)) + \rho + (y, g^y(y)) \forall x, y \in X \), where \( k \in [0, (1/2)] \) is a constant.

(3) \( \rho + (f^x(x), g^y(y)) \leq k \rho + (x, f^x(x)) + \rho + (y, g^y(y)) \forall x, y \in X \), where \( k \in [0, (1/2)] \) is a constant.

(4) \( \rho + (f^x(x), g^y(y)) \leq k \rho + (x, f^x(x)) + \rho + (y, g^y(y)) + \rho + (x, y) \forall x, y \in X \), where \( k \) is a positive integer.

Theorem 3 may be proved based on Lemma 3 and results on contractive-type mappings satisfying (1), (4), (5), (7), (11), (12), (14), (18), (43) in [44], and Theorem 4 may be proved based on Lemma 3 and results on contractive-type mappings satisfying (176), (179), (180), (182), (186), (187), (193) in [44].

6. Concluding Remarks

Since data from many real-world problems are not only from multi agents but also becoming more and more big and complex for vagueness and uncertainty, measurement by a single metric does not meet the needs of some practical problems. Motivated by Polya’s plausible reasoning and artificial neural networks, this paper consider a distance-like
Appendix

Proof. of Proposition 1. We only prove $\rho_3(\overrightarrow{a}, \overrightarrow{b}) \leq \rho_4(\overrightarrow{a}, \overrightarrow{b})$ conditionally. If $\overrightarrow{a} = \overrightarrow{b}$, then $\rho_3(\overrightarrow{a}, \overrightarrow{b}) = 0 = \rho_4(\overrightarrow{a}, \overrightarrow{b})$. Next, we assume $(\overrightarrow{a}, \overrightarrow{b})$ satisfies $a_1 \neq b_1$ and $(a_2 - b_2)(a_1 - b_1) - a_2b_2 - a_1b_1 \leq \sqrt{(a_2 - a_1)^2 + a_3^2 + b_2^2 + b_3^2}$. There are only four cases which need to be considered.

Case 1 $(a_2 - b_2)(a_1 - b_1) = 0$. Then, $\rho_3(\overrightarrow{a}, \overrightarrow{b}) - a_1 - b_1 = \sqrt{(a_2 - a_1)^2 + a_3^2 + b_2^2 + b_3^2}$. There are only four cases which need to be considered.

Case 2 $(a_2 - b_2)(a_1 - b_1) \neq 0$. Then, $(a_2 - b_2)(a_1 - b_1) \leq \rho_3(\overrightarrow{a}, \overrightarrow{b})$. Thus, $\rho_3(\overrightarrow{a}, \overrightarrow{b}) \leq \rho_4(\overrightarrow{a}, \overrightarrow{b})$.}

Proof. of Proposition 4. We only prove (1). Firstly, we prove $\rho$ satisfies condition (2) (i) of Definition 1. By (M3) and Definition $1, \lambda_1(x, y) = \lambda_1(x, y) = \rho(x, y) \leq \rho(x, y) + \rho(z, y) = \lambda_1(x, z) + \lambda_1(z, y) = \lambda_1(x, z) + \lambda_2(x, y)$, if $\forall x, y, z \in X, \forall a \in (0, 1]$. Write $a = d(x, z)(s), b = d(y, z)(t)$, and $c = \min(a, b)$. Then $c \in (0, 1]$. It does not lose generality to assume $c = 1$ (i.e., $a = b = 1$), then $\lambda_1(x, z) = \lambda_1(x, z) = \rho(x, y) \leq \rho(x, z) \leq \rho(x, z) \leq \lambda_1(x, z) + \lambda_2(x, y)$, if $s + t \leq \lambda_1(x, z) + \lambda_2(x, y)$. Since $\lambda_1$ is nondecreasing with $r$ and $s + t \leq \lambda_1(x, y), \lambda_1(x, y) = \lambda_1(x, y) \leq \lambda_1(x, z) + \lambda_1(z, y) = \lambda_1(x, z) + \lambda_1(z, y) + \lambda_2(x, y)$. Hence, $d(x, y)(s + t) \leq 1 + 1 = \min(d(x, z)(s), d(y, z)(t)) = d(x, y)(s + t)$. Now we prove $\rho$ satisfies condition (2) (ii) of Definition 1. By (M3) and Definition 3, $\gamma_0(x, y) = \gamma_0(x, y) = \rho(x, y) \leq \rho(x, y) + \rho(z, y) = \gamma_0(x, z) + \gamma_0(z, y) = \gamma_0(x, z) + \gamma_0(z, y)$, if $\forall x, y, z \in X, \forall a \in (0, 1]$. Write $a = d(x, z)(s + t)$. Then $s \geq \lambda_1(x, z), t \geq \lambda_1(z, y), c + s + t \geq \lambda_1(x, y)$. Then, $s$
Proof. of Lemma 2. We only prove (2) (for the case of $n = L_u$) and (3). Write $\xi(A, B) = 1 - d_{L_u}(A, B)$, As $1 - A_{L_u}(x) + B_{L_u}(x) \leq 1$ or $1 - A_{L_u}(x) + B_{L_u}(x) \leq 1$, $\xi(A, B) = \Delta \{ (1 - A_{L_u}(x)) + B_{L_u}(x) \} \land \{ (1 - B_{L_u}(x)) + A_{L_u}(x) \} d_x^x$.

We first show that $d_{L_u}(A, B) = 0$ if and only if $A$ and $B$ are $I_{L_u}$-logically equivalent (particularly, $d_{L_u}(A, A) = 0$ for all $A \in F(S)$). Actually, if $d_{L_u}(A, B) = 0$ (i.e., $\xi(A, B) = 1$), then $1 - A_{L_u}(x) + B_{L_u}(x) = 1 - B_{L_u}(x) + A_{L_u}(x) = 1$ (forall $x \in \Delta$) since $I_{L_u}$ is continuous. Thus, $\nu(A \rightarrow B) = \nu(A) \land (1 - \nu(A) + \nu(B)) \land (1 - \nu(A) + \nu(B)) \land (1 \in \Delta(I_{L_u}))$. It follows that $\nu(A) \leq \nu(B)$ and $\nu(B) \leq \nu(A)$, i.e., $\nu(A) = \nu(B)$. Since $\nu$ is arbitrary, $A$ and $B$ are $I_{L_u}$-logically equivalent.

(3) By definition of $d_{GR}^\epsilon$ and Lemma 1, we know that $d_{GR}^\epsilon(A, B) = 0$ if and only if $A_{L_u}(x) = B_{L_u}(x)$ (a.e.), and that $d_{GR}^\epsilon(A, B) = 0$ if and only if $A$ and $B$ are $I_{GR}$-logically equivalent ($\epsilon \in (0, 1]$). Particularly, $d_{GR}^\epsilon(A, A) = 0$ (forall $A \in F(S)$) holds. Since $d_{GR}^\epsilon(A, B) = d_{GR}^\epsilon(B, A)$ (forall $B \in F(S)$), we only need to prove the triangle inequality. It is not loss of generality to consider only the case $\epsilon \in (0, 1]$. Step 1. $f(a, b) + f(b, c) \leq f(a, c) + 1$, where $f(s, t) = I_{GR}(s, t) \land I_{GR}(t, s)$. It is not loss of generality to assume $a < c$. Then, $f \land c = I_{GR}(a, c) \land I_{GR}(c, a) = 1 \land 0 = 0$, thus we only need to prove $f(a, b) + f(b, c) \leq 1$.

We consider the following five cases.

For the case $\epsilon \in (0, 1)$, take $A, B, C \in F(S)$. We consider the following two cases (it is not loss of generality to assume $A$ and $B$ are not $I_{GR}$-logically equivalent).

Conversely, if $A$ and $B$ are $I_{L_u}$-logically equivalent, then $A_{L_u} = B_{L_u}$ (and thus $d_{L_u}(A, B) = 0$ by Lemma 1. $d_{L_u}(A, B) = d_{L_u}(B, A)$ (forall $A, B \in F(S)$) follows from definition of $d_{L_u}$. It remains to prove the triangle inequality.

Step 1. $f(a, b) + f(b, c) \leq f(a, c) + 1$, where $f(s, t) = I_{L_u}(s, t) \land I_{L_u}(t, s)$. It is not loss of generality to assume $a \geq c$. We consider the following three cases.

(i) $a \leq b$. Then, $f(a, b) = 1 - a - b + c$, and thus $f(a, b) + f(b, c) = 2 - b + c \leq 2 - a + c = f(a, c) + 1$.

(ii) $c \leq a$. Then, $f(a, b) = 1 - a - b$, $f(b, c) = 1 - b + c$, and thus $f(a, b) + f(b, c) = 2 - a + c = f(a, c) + 1$.

(iii) $b < c$. Then, $f(a, b) = 1 - a - b$, $f(b, c) = 1$, and thus $f(a, b) + f(b, c) = 2 - a - b - a + c = f(a, c) + 1$.

Step 2. By the inequality in Step 1, we have $(A, B, C) \subseteq F(S)$.
\[ d_{GR}^{c}(A, B) = 1 - \epsilon \int_{\Delta} f\left( A_{IG}(\tilde{x}), B_{IG}(\tilde{x}) \right) d\tilde{x} \leq 1 - \epsilon \int_{\Delta} \left[ f\left( A_{IG}(\tilde{x}), C_{IG}(\tilde{x}) \right) + f\left( C_{IG}(\tilde{x}), B_{IG}(\tilde{x}) \right) - 1 \right] d\tilde{x} \leq \left( 1 - \epsilon \int_{\Delta} f\left( A_{IG}(\tilde{x}), C_{IG}(\tilde{x}) \right) d\tilde{x} \right) + \left( 1 - \epsilon \int_{\Delta} f\left( C_{IG}(\tilde{x}), B_{IG}(\tilde{x}) \right) d\tilde{x} \right) = d_{GR}^{c}(A, C) + d_{GR}^{c}(C, B). \]  

(A.3)

(ii) Either \( A \) and \( C \) are \( I_{GR} \)-logically equivalent or \( C \) and \( B \) are \( I_{GR} \)-logically equivalent. It is not loss of generality to assume that \( A \) and \( C \) are \( I_{GR} \)-logically equivalent. By Lemma 1, we have \( d_{GR}^{c}(A, B) = d_{GR}^{c}(C, B) \leq d_{GR}^{c}(A, C) + d_{GR}^{c}(C, B) \).

**Proof.** Of Theorem 2 We only show that \( \rho \) satisfies (M3) in Remark 1. Suppose \([x, y, z] \) is a 3-element subset of \( V \). If \( \mathcal{P}_{xy} = \emptyset \), then \( \mathcal{P}_{xy} \neq \emptyset \) or \( \mathcal{P}_{yz} = \emptyset \), and thus \( \rho(x, z) \leq \rho(x, y) \oplus \rho(y, z) \) (which means that \( \rho \) satisfies (M3)). If \( \mathcal{P}_{xy} \neq \emptyset \), then we consider the following two cases:

Case 1 \( \mathcal{P}_{xy} = \emptyset \) or \( \mathcal{P}_{yz} = \emptyset \). Then \( \rho(x, z) \leq (|V|^2/m(\mu)) \leq \rho(x, y) \oplus \rho(y, z) \), which means that \( \rho \) satisfies (M3).

Case 2 \( \mathcal{P}_{xy} \neq \emptyset \) and \( \mathcal{P}_{yz} \neq \emptyset \). For each path \( P_1 = u_1, u_2, \ldots, u_m \in \mathcal{P}_{yx} \) from \( x \) to \( y \) and each path \( P_2 = v_1, v_2, \ldots, v_n \in \mathcal{P}_{yz} \) from \( y \) to \( z \) there exists a path \( P_{1,2} = w_1, w_2, \ldots, w_l \in \mathcal{P}_{xz} \) from \( x \) to \( z \) such that \( \{w_1, w_2, \ldots, w_l\} \subseteq \{u_1, u_2, \ldots, u_m\} \setminus \{u_l\} \subseteq \{v_1, v_2, \ldots, v_n\} \). Therefore, \( \rho(x, z) = \vee \{\ell(P) | P \in \mathcal{P}_{xz}\} \leq \vee \{\ell(P_{1,2}) | P_{1,2} \in \mathcal{P}_{xy} \} \leq \vee \{\ell(P_1) | P_1 \in \mathcal{P}_{y} \} \oplus \vee \{\ell(P_2) | P_2 \in \mathcal{P}_{yz} \} \) satisfies (M3).

**Data Availability**

The data used to support the findings of this study are included within the article.

**Conflicts of Interest**

The authors declare that there are no conflicts of interest regarding the publication of this paper.

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