Automatic control of motors through Simocode pro, and its effect on the performance of the process of filling and dispensing of chemical inputs

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ABSTRACT

This article aims to describe the design of an automatic control system for the automated management of motor drives through Simocode pro; and determine the effect from the quantitative point of view on the performance of the filling and dispatch process of chemical inputs from the perspective of dispatch time and the amount of input spilled in the tank filling stage. For this, the programming of the programmable logic controller was carried out using the simatic step 7 software, then the distributed control system (DCS Siemens S410) was programmed, using the PCS7 V8.1 software, where the control logic and simocode pro integration is carried out through the profibus protocol, which is monitored from an human-machine interface (HMI) interface. Once the control system was implemented, it was possible to reduce the operating time from 60 minutes on average to 35 minutes, which reflects an improvement of 41.66%; this in turn generates an increase in the number of tank filling by 62.84%. Likewise, it is possible to reduce the amount of chemical inputs spilled in the filling stage; this improvement represents 88.60%.

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1. INTRODUCTION

Most organizations have many factors to be able to carry out the processes and satisfy the market demand [1]. Among the most important factors are: human resources, capital, technology and raw materials [2]. Thus, it is essential to focus on one of these factors and determine its performance so as to achieve the productivity goals of the organization [3]. Although various studies have been carried out on the measurement of performance in operations [4], the emphasis on measuring this indicator due to the technological factor has not been very developed [5]. Nowadays companies must place special emphasis on investing in technology in order to increase their performance, which is closely related to the productivity of a company [6].

In a globalized world, organizations or companies require the continuous implementation of technologies in order to meet the demands of their customers in terms of demand and product quality [7], this because we are in a totally competitive world [8]. In this regard, many companies lack technological infrastructure, which is why they are not increasing their productivity or performance [9]. In relation to the

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above, it would be important to specify what the term productivity means; In this regard [10], it is defined as the degree of performance with which the available resources are used in order to achieve the predetermined objectives.

Today automation is a significant part of the industry [11], its use implies continuous improvement in production processes in an organization [12]. It is under this context that the importance of control systems in industrial processes is highlighted [13]; the current trend regarding the use of control systems is closely linked to guaranteeing the optimal functioning of the equipment and components that are part of the production process [14]. Another aspect to consider when referring to the performance of a production process is the time in which the machines are in operation without showing failures [15], the fact is that the control of the parameters of an industrial process implies a crucial and rigorous activity [16], which must be developed with the highest degree of precision possible [17], since the performance of the process depends on the control, monitoring and supervision of the evolution of the controlled variable with respect to the reference value or set point [18].

Advances with respect to automated control systems are aimed at improving the management of the elements that allow the control of the crucial variables of the production process [19]. Automated management systems for the operation of work organs allow to improve the life cycle of the machines of the productive processes, guaranteeing to improve the productivity of the organizations [20]. Simocode pro is a flexible and modular motor management system [21], which optimizes the management between the process control and the motor bypass [22], increasing the availability of the working organs in the industrial process [23]. This device allows to achieve an automation with integral protection for motors that are part of the production process [24]. Now if we take into account that the companies that have processes related to the dispatch of chemical inputs, contain too many elements that influence in reducing the performance of the system [25].

It is necessary that these organizations be at the forefront of the technology of supervision, control and data acquisition [26]. Given the lack of technological tools to help control the process, they would lead to losses, due to the lack of precision in filling the tares of the trucks that distribute the chemical inputs [27], as well as the delay in dispatch time, relevant aspects that influence the performance of the production process [28]. In this sense, this article aims to describe the design of an automated management system for the drive of motors through Simocode Pro, and to determine the effect from a quantitative point of view on the performance of the process of filling and dispatch of supplies chemicals from the perspective of dispatch time and the amount of input spilled in the tank tank filling stage. It is important to specify that this scientific article is an extension of the results and findings obtained in [29].

2. VALIDATION OF THE DATA COLLECTED
2.1. Data collection
The data collection was carried out through the observation technique, and the documentary analysis. This is due to the fact that the solution proposal implied the development of a data supervision, acquisition and control system (SCADA), with which it was possible to obtain historical reports regarding the indicators under analysis. However, it is necessary to highlight that before the implementation of the SCADA system, that is, when the stage of filling and dispatching the chemical input (sulfuric acid), responded to a manual process itself, the analysis of documents from previous years was used, working in the quality control area. In addition, in Figure 1, the scheme of the research design used in this research is specified, having as a reference, the purpose of this research, which is to obtain the effect from the proposed solution on the performance of the system, from the perspective of the indicators dispatch time and quantity of input spilled in the filling stage.

Figure 1. Data collection design scheme
Where O1i represents the observation of indicator 1 (dispatch time) and O12i represents the observation of indicator 2 (amount of input spilled or in the filling stage), before the application of the proposed solution. While O1j represents the observation of indicator 1 (dispatch time) and O12j represents the observation of indicator 2 (amount of input spilled in the filling stage), after the application of the proposed solution. It is specified that both the “i” and “j” indices range from 1 to 12, due to the fact that the data collection is longitudinal, that is, the data is collected on a monthly basis for one year.

2.2. Reliability analysis

In order to establish the degree of reliability of the data collected, Table 1 and Table 2 show the results obtained from Cronbach’s Alpha, using the statistical software SPSS version 25; the analysis is shown by indicator, highlighting both indicators under study and intervening indicators. The Cronbach’s Alpha value is also specified on average in the average of the data collected in the two analyzed scenarios, that is, before and after the implementation of automatic motor control through Simocode pro. Based on the results obtained, it is stated that the level of reliability of the data collected is high.

![Table 1. Cronbach’s alpha of the manual process data](image)

| Indicators in analysis                  | Cronbach’s alpha |
|-----------------------------------------|------------------|
| Dispatch time (min)                     | 0.902            |
| Stop time for overflow (min)            | 0.901            |
| Number of tanks filled                  | 0.900            |
| Quantity of chemical inputs dispatched (kg) | 0.902       |
| Amount of chemical inputs lost for overflow (kg) | 0.900   |
| Average Cronbach’s alpha                | 0.901            |

![Table 2. Cronbach’s alpha of the automatic process data](image)

| Indicators in analysis                  | Cronbach’s alpha |
|-----------------------------------------|------------------|
| Dispatch time (min)                     | 0.943            |
| Stop time for overflow (min)            | 0.944            |
| Number of tanks filled                  | 0.922            |
| Quantity of chemical inputs dispatched (kg) | 0.911       |
| Amount of chemical inputs lost for overflow (kg) | 0.932   |
| Average Cronbach’s alpha                | 0.930            |

2.3. Normal distribution analysis

Obtained the reliability results and in order to show the level of distribution of those collected with respect to the indicators in analysis, then I proceed to show in Table 3, the results of the normality test by means of the Shapiro Wilk test, obtained by the use of the statistical software SPSS version 25. It should be noted that since the data were collected in a period of one year, the sample presented 12 results, therefore it is specified that the Shapiro Wilk test will be used, which is used for samples less than 50. It should be noted that this test affirms that there is a distribution of the data, only if the bilateral significance (sig.) is greater than the α (significance level), which is equal to 0.05. According to what was obtained, it is affirmed that the bilateral significance of the data in all the indicators is greater than 0.05, therefore it is sustained that there is normality in the collected data.

![Table 3. Normality test of the data using Shapiro-Wilk](image)

| Indicadores en análisis                  | gl | Significance |
|-----------------------------------------|----|--------------|
| Dispatch time (min)                     | 12 | 0.640        |
| Stop time for overflow (min)            | 12 | 0.516        |
| Number of tanks filled                  | 12 | 0.620        |
| Quantity of chemical inputs dispatched (kg) | 12 | 0.850     |
| Amount of chemical inputs lost for overflow (kg) | 12 | 0.613   |

3. PROCEDURE

3.1. Description of the automated process

In Figure 2, the flow diagram of the process of filling and dispatching the tank containing the chemical input is observed, for which it was established that the dispatch operation of the tank can be in manual or automatic mode, so that it can operate the system in one of these two modes, the equipment must be enabled (motors). If not, the operator must go to the command and control room (CCM) and enable the main switch. Subsequently we access the WinCC monitoring system.
The supervisory system for the dispatch of chemical input tanks (sulfuric acid) has two stations, which are located in the balance control room, which are permanently used, under strict control and monitoring of the two stages under study. The software used is PCS7 Version 8.1 and data collection is done through a Siemens S7-400 PLC, connected to the supervisor system through an Ethernet control network. The graphical interface allows additionally to control and monitoring, also to turn on, turn off equipment and acknowledge alarms. As well as through connection to a database of all process variables in which analog and discrete signals are identified.

Figure 3 shows the P&ID diagram of all the electronic instrumentation in the field, close to the process of filling and dispatching the sulfuric acid from the tank. It can be seen that during the closing of the actuator the beacon and intermittent siren will be activated to account for the end of the attention. If during the attention the overfill sensor is activated, the beacon and siren will be activated permanently for 45 seconds. The controlled valves will remain open at 100% while the cistern tank is filled, until 300 kg after filling is complete, the proportional closure will begin as indicated. When 300 kg is missing, the valve will be at 50%, when 150 kg is missing, the valve will be at 25%, when 75% is missing, the valve will be at 15% and finally when 25 kg is missing, the valve will be at 10%. Likewise, a time delay has been configured in the controller that will protect the dispatch line from overpressure. In other words, once the pump is started, the control system must receive confirmation of the valve opening, if the valve remains open for no more than 3 seconds, the control system will close it. Enabling the pump automatically enables the control valve corresponding to the scale where the delivery will take place.

It is under this context that the motor control system is described through the Siemens Simocode pro; In Figure 4, the architecture of the control circuit for the management of engines that participate in the process of filling and dispatching tanks through the Simocode pro is shown. It is important to specify that in the figure shown, In1 is the confirmation of the selection in automatic, while the input In2, is the equipment start-up confirmation. It must be taken into account that the start-up with the Simocode pro of the pumps will be linked by the profibus industrial communication network, to be monitored later from WinCC.

Figure 2. Flow diagram of the tank filling and dispatch process
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Having fixed the architecture of the control system and establishing the components to be used, next, we proceed to show the programming of the programmable logic controller using the SIMATIC STEP 7 Software, and then carry out the programming of the distributed control system (DCS SIEMENS S410), using the PCS7 V8.1 Software, where the control logic is configured, as shown in Figure 5 the hardware configuration of the industrial network and in Figure 6 the integration of the Simocode pro through the profibus protocol.
4. RESULTS AND DISCUSSION

4.1. Results

Figure 7 shows the results obtained in relation to the effect that automation has had on the dispatch time of chemical inputs, as can be seen there is an improvement in this indicator, which represents an average of 1.6% in percentage terms. More specifically, the automatic dispatch process lasts for 35 minutes per operation, while with the manual process this time ranged from 55 to 65 minutes, before this the improvement is 41.66%. Now regarding the total dispatch time it can be indicated that in a daily workday it has decreased from 464 minutes to 455 minutes, in percentage terms it represents 1.94%. Although it may seem like a small improvement value, it becomes relevant, when it is related to the dispatch time with the amount of chemical inputs dispatched, this can be seen in Figure 8.
As can be seen, once the automatic process has been applied, a positive effect has been generated in the quantity of chemical inputs dispatched, because the annual quantity has improved by 62.56%, due to the fact that, before a total of 53, 700,480.00 kg annually and now with a shorter time, with an improvement of 1.6%, a total of 87, 299,280.00 kg is shipped per year. Something important to note is that although, in both automatic and manual processes, the amount of chemical inputs per tank continues to be 18,646.00 kg, the increase in this indicator has been generated by the decrease in dispatch time, this allows that in the day a greater number of tanks is filled, therefore, the amount of chemical inputs dispatched increases from 149,168.00 kg to 242,398.00 kg per day.

As indicated, the variation in the quantity of chemical inputs (kg) dispatched is directly related to the improvement of dispatch time, this has a positive influence, since a greater number of tanks is filled during the day. This annual improvement is due to the fact that with the manual process a total of 2,874 tanks were filled, while with the automatic the number has increased to 4,680, which represents an improvement of 62.84%. Specifically, with the automatic process per day, a total of 13 tanks are filled in 455 minutes, which previously was a total of 8 tanks in a time of 464 minutes.

Likewise, the increase in the number of tanks and the optimization of the dispatch time, is generated and is related to the decrease in the downtime for each operation per day of the dispatch process, which occurred when the chemical input was overflowing of the cistern tank due to the lack of precision and the delay in closing the valves, which were operated manually. Because of what was described for each operation in the manual process, it took about 12 to 20 minutes for the other tank to be able to go up to the scale, which, on the day, this stop time reached an average of 144 minutes. A totally different scenario is generated when the automation is applied, where the stop time per operation is reduced to 7 minutes, this time is the one that takes from the closing of the filling valve to the rise of the next scale, which in the day represents a total of 91 minutes of stoppage of the automatic process; As a percentage, it can be noted that there is an improvement of 36.8% on the day.

Thus, an annual improvement in the stoppage time in the dispatch process was also determined, this when the automation was implemented, according to the data collected, when it was operated manually, there was a total of 4,852 minutes where production stopped due to some failure or overflow of the tank of the cisterns, now this indicator decreased to 2,730 minutes, this represents an annual improvement of 42.63%; as there is less time for process stoppages, it generates higher performance.

In addition, a positive annual variation was determined in the amount of chemical inputs wasted due to the overflow of the tank tanks, this when the automation was implemented. According to the data collected, when it was operated manually, there was a total of 48,160.00 kg of chemical inputs that were lost manually, due to the overflow of the tank of the cisterns or some failure of the system, now when the automation was applied, this...
indicator decreased at 5,493.00 kg of waste per year, this represents an annual improvement of 88.60%. Being more specific, on the day with the automatic process per operation there is on average a possibility of spillage of 1 to 1.5 kg, while with the manual process this amount could reach up to 20 kg per operation; This variation means a decrease in average from 129 kg to 15.7 kg of waste of chemical inputs per day, which is equal to an improvement of 87.83%.

4.2. Discussions

Regarding the dispatch time of chemical inputs, an improvement of this indicator of 1.6% is achieved; This has generated a positive annual effect of 62.56% in the quantity of chemical supplies dispatched, which represents an improvement of 62.84% in the increase in the number of filled tanks. These results agree with what was obtained in [20], where it is pointed out that when the automation process is carried out, it is evident how the production line improves in terms of control and manipulation of the immersion times of the product; Regarding the number of production, 1000 kg were produced on the manual line and by adapting the automation, 3000 kg are produced in a shift with a single operator without any physical or mental wear. Similarly in [21] it is pointed out that, by implementing the automation system in the hydrochloric acid dispatch process, it is possible to dispatch a greater quantity of hydrochloric acid safely and with fewer operators, in this way the system increases its performance by 75%.

Regarding the amount of chemical inputs spilled in the filling stage, an annual improvement of 88.60% is achieved. Likewise, with this, it is possible to reduce the stop time of the process due to the spillage of chemical inputs by 42.63%. In view of this, in [21] it is pointed out that by making the automated system by programming the Siemens CPU 1214C PLC and the KTP1000 HMI, it was possible to define exactly the amount of acid to be dispensed through manual or automatic control, thereby reducing amount of wasted hydrochloric acid; This not only protects the operator but also reflects a significant economic saving.

5. CONCLUSION

Through the automatic control system, it was possible to improve the dispatch time of chemical supplies, reducing the operating time from 60 minutes on average to 35 minutes, which reflects an improvement of 41.66%. The improvement of the process generates an increase in the number of tank filling by 62.84%. In this sense, it is recommended to train the personnel who will be in charge of the operation of the automated management system, in order to be able to provide them with the necessary scope of the operation of the system from the HMI and attend to the alarms that may arise; as well as that they are able to connect online with the PLC so that in the future modifications of the system can be made according to the requirements of the company. Thus, it is also concluded that through this proposed solution, it is possible to reduce the amount of chemical inputs spilled in the filling stage; this improvement represents 88.60%. This variation means a decrease on average from 129 kg to 15.7 kg of waste of chemical inputs per day. For better system performance, it is recommended to perform physical tests twice a year with the chemical inputs per day. For better system performance, it is recommended to perform physical tests twice a year with the chemical inputs per day.

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