Post-selection inference on high-dimensional varying-coefficient quantile regression model

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Abstract

Quantile regression has been successfully used to study heterogeneous and heavy-tailed data. Varying-coefficient models are frequently used to capture changes in the effect of input variables on the response as a function of an index or time. In this work, we study high-dimensional varying-coefficient quantile regression models and develop new tools for statistical inference. We focus on development of valid confidence intervals and honest tests for nonparametric coefficients at a fixed time point and quantile, while allowing for a high-dimensional setting where the number of input variables exceeds the sample size. Performing statistical inference in this regime is challenging due to the usage of model selection techniques in estimation. Nevertheless, we can develop valid inferential tools that are applicable to a wide range of data generating processes and do not suffer from biases introduced by model selection. We performed numerical simulations to demonstrate the finite sample performance of our method, and we also illustrated the application with a real data example.

1 Introduction

Most statistical work on regression problems has centered on the problem of modeling the mean of a response variable $Y \in \mathbb{R}$ as a function of a feature vector $X \in \mathbb{R}^p$. Under some assumptions, for instance assuming homoscedastic Gaussian noise, modeling the mean is sufficient to capture the entire distribution of $Y$ conditioned on the observed features $X = x$. In many applications, however, where these types of assumptions may not be appropriate, it is often far more meaningful to model the median (or some other specified quantile) of $Y$ given the observed feature vector $X$. In particular, in applications where we are

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interested in extreme events—for instance, modeling changes in stock prices, or modeling birth weight of infants—modeling, e.g., the 90% quantile may be far more informative than modeling the mean. In other settings, the mean is overly sensitive to outliers, while the median or some other quantile does not have this disadvantage. Fixing \( \tau \) to be the desired quantile (e.g., \( \tau = 0.5 \) for the median), we write \( q(x; \tau) \) to be the \( \tau \)th quantile for the variable \( Y \) conditional on observing \( X = x \), that is, \( q(x; \tau) \) is the function that satisfies

\[
q(x; \tau) = \inf_{q \in \mathbb{R}} \{ P \{ Y \leq q \mid X = x \} \geq \tau \}.
\]

In this paper, we are interested in a high-dimensional setting, where the vector \( X \) includes an extremely large number of measured features—perhaps larger than the sample size itself. A linear model, \( q(x; \tau) = x^\top \beta(\tau) \), may be considered to be a reasonable approximation in many settings, but if the measurements are gathered across different points in time, the effect of the features on the response \( Y \) may not be stationary. To achieve broader applicability of our model, we are furthermore interested in models with time-varying coefficients for the \( \tau \)th quantile for the variable \( Y \) conditional on observing \( X = x \) at index \( U = u \),

\[
q(x; \tau, u) = \inf_{q \in \mathbb{R}} \{ P \{ Y \leq q \mid X = x, U = u \} \geq \tau \},
\]

where \( x \in \mathbb{R}^p \) is the feature vector as before, \( \tau \in (0, 1) \) is the desired quantile, and \( u \in \mathcal{U} \) represents the time of the measurement or any other index variable that captures non-stationary effects of the features—for example, \( u \) may be used to encode spatial location. We assume that \( q(x; \tau, u) \) approximately follows a linear model \( x^\top \beta(\tau, u) \).

Fixing a quantile \( \tau \) and a time point (or index value) \( u \), we are interested in performing inference on a low-dimensional subset of coefficients of interest, \( \beta_A(\tau, u) \) for some fixed subset \( A \subset \{1, \ldots, p\} \). Specifically, we want to construct confidence intervals for these parameters or test null hypotheses such as \( H_0 : \beta_j(\tau, u) = 0, \forall j \in A \). In practice, we may have in mind some particular features of interest, and the other features are confounding variables that we need to control for; or, we may be interested in testing each of the \( p \) features individually, cycling through them in turn and treating the others as confounders.

**Prior work** Our work is related to the literature on high-dimensional inference, varying-coefficient models, and quantile regression. Statistical inference for parameters in high-dimensional models has received
a lot of attention recently. For example, in the \( \ell_1 \)-regularized linear regression model (LASSO) \cite{Tibshirani1996} one can quantify the uncertainty about the unknown parameters by debiasing the estimator \cite{Zhang2013, vanDeGeer2013, Javanmard2013, Javanmard2013b} or using a double LASSO selection procedure \cite{Belloni2013}. Extensions to generalized linear models were investigated in \cite{Belloni2016b, vanDeGeer2014, Farrell2015}. \cite{Meinshausen2015} studied construction of one-sided confidence intervals for groups of variables under weak assumptions on the design matrix. \cite{Lockhart2014} studied significance of the input variables that enter the model along the lasso path. \cite{Lee2013} and \cite{Taylor2014} performed post-selection inference conditional on the selected model. \cite{Kozbur2013} extended approach developed in \cite{Belloni2013a} to a nonparametric regression setting, where a pointwise confidence interval is obtained based on the penalized series estimator, while \cite{Lu2020} studied a kernel-sieve hybrid estimator for inference in sparse additive models. \cite{Yu2020a} considered testing in high-dimensional parametric models with cone constraints. Hypothesis testing and confidence intervals for low-dimensional parameters in graphical models were studied in \cite{Ren2015, Wang2014, Jankova2015, Jankova2017}, elliptical copula models \cite{Barber2018, Lu2018}, Markov networks \cite{Wang2016, Yu2016, Yu2020b}, differential networks \cite{Xia2015, Belilovsky2016, Liu2017, Kim2017}, and networks of point processes \cite{Wang2020}. Varying-coefficient models were introduced as a general framework that tied together generalized additive models and dynamic generalized linear models \cite{Hastie1993}. Estimation and inference for varying coefficient models in the mean have been widely studied. See, for example, \cite{Fan2000, Hoover1998, Zhang2002, Huang2004, Na2019, Na2021}. Quantile regression was studied in the presence of outliers and non-normal errors in \cite{Koenker1984}, while quantile regression with time-varying coefficient models was studied in, for example, \cite{Kim2007} and \cite{Kai2011}. Statistical inference for high-dimensional linear quantile regression was studied in \cite{Belloni2013b, Belloni2015, Belloni2016a, Bradic2017} and a closely related problem of inference in composite quantile regression was investigated in \cite{Zhao2014}. \cite{Tang2013} studied estimation of quantile varying-coefficient models in a high-dimensional setting. However, how to perform statistical inference for high-dimensional varying coefficient models remains an open question.

**Our contribution** Below, we summarize the main contributions of this work.
• We propose several approaches for constructing valid post-selection confidence intervals for the varying-coefficient quantile regression model. These approaches are asymptotically equivalent and rely on finding an approximate root of the decorrelated score. To make the construction computationally feasible with the non-differentiable loss that is used in quantile regression, we rely on a one-step approximation and reparameterization.

• We provide the asymptotic normality results for the proposed estimators. Establishing this results requires a novel analysis that generalizes the existing techniques. Specifically, we carefully overcome the challenges that arise from the non-differentiable loss used in quantile regression, the bias from the penalized regression to handle the high dimensionality, and the bias from linear approximation to handle the nonparametric component in appearing in varying coefficient models.

• We use extensive simulation studies and real data analysis to demonstrate the finite sample performance of our proposed estimators.

2 Preliminaries

In this section, we carefully develop background necessary to understand the algorithms that are presented in the subsequent section. In Section 2.1 we provide a brief overview of estimation in the varying-coefficient quantile regression model. Next, we illustrate the challenges in the high-dimensional inference in Section 2.2. In Section 2.3 we describe the decorrelated score method that can be used for high-dimensional inference when the loss function is twice differentiable. Finally, we modify the decorrelated score method to suit the non-differentiable setting of varying-coefficient quantile regression and sketch the main steps of the analysis in Section 2.4. Note that the results in Section 2.1-2.3 are not new and are presented for ease of readability.

2.1 Varying-coefficient quantile regression

For a random variable $Y \in \mathbb{R}$, its $\tau$-quantile can be equivalently described as the value $q$ that minimizes the expectation $\mathbb{E} [\tau \cdot (Y - q)_+ + (1 - \tau) \cdot (Y - q)_-]$ (for any $t \in \mathbb{R}$, we write $t_+ = \max\{t, 0\}$ and $t_- = \max\{-t, 0\}$). For a linear quantile regression problem, at a particular value of the index variable $u \in \mathcal{U} \subseteq$
\[ R \], we are therefore interested in estimating
\[
\beta(\tau, u) = \arg \min_{b \in \mathbb{R}^p} \mathbb{E} \left[ \tau \cdot (Y - X^\top b)_+ + (1 - \tau) \cdot (Y - X^\top b)_- \mid U = u \right],
\]  

(1)

where the expectation is taken over a draw of the random pair \((X, Y)\) when the index variable is equal to \(U = u\) (in other words, we can think of drawing the triplet \((X, Y, U)\) and conditioning on the event \(U = u\)).

Of course, we cannot compute this expected value or even obtain an unbiased estimate, unless by some chance our training data contains many data points \((x_i, y_i, u_i)\) with \(u_i = u\). Instead, by assuming that \(\beta(\tau, u)\) is reasonably smooth with respect to the index variable \(u \in U\), we can use a kernel method, and approximate the expected value in (1) with
\[
\sum_{i=1}^{n} w_i \cdot \left[ \tau \cdot (y_i - x_i^\top b)_+ + (1 - \tau) \cdot (y_i - x_i^\top b)_- \right],
\]

where the weights are given as
\[
w_i = \left( nh \right)^{-1} K \left( h^{-1} (u_i - u) \right), \text{ the function } K(\cdot) \text{ is the kernel function, and } h \text{ is the bandwidth.}
\]

This approximation can be interpreted as assuming that \(\beta(\tau, u)\) is locally approximately constant for values \(u_i \approx u\), and thus defines a loss function on the sampled data that would hopefully be minimized at some \(b(\tau, u) \approx \beta(\tau, u)\), but would suffer bias from the error in this approximation. We can reduce the approximation bias by instead treating \(\beta(\tau, u)\) as locally approximately linear for values \(u_i \approx u\), that is,
\[
x_i^\top \beta(\tau, u_i) \approx x_i^\top \beta(\tau, u) + (u_i - u) \cdot x_i^\top \nabla_u \beta(\tau, u).
\]

Defining \(\Gamma_i = (x_i^\top, (u_i - u) \cdot x_i^\top) \in \mathbb{R}^{2p}\) for each observation \(i = 1, \ldots, n\), this yields a new loss function,
\[
\mathcal{L}(b) = \sum_{i=1}^{n} w_i \cdot \left[ \tau \cdot (y_i - \Gamma_i^\top b)_+ + (1 - \tau) \cdot (y_i - \Gamma_i^\top b)_- \right] = \sum_{i=1}^{n} w_i \cdot \rho_\tau \left( y_i - \Gamma_i^\top b \right),
\]  

(2)

where the function \(\rho_\tau(v) = v(\tau - 1 \{ v < 0 \})\). We are now interested in minimizing (2) over a larger parameter vector, \(b = (b_0^\top, b_1^\top)^\top \in \mathbb{R}^{2p}\), where \(b_0, b_1 \in \mathbb{R}^p\). We would expect the minimum to be attained at some \(b^* = (b_0^*, b_1^*)^\top \approx (\beta(\tau, u)^\top, \nabla_u \beta(\tau, u)^\top)^\top\) if the local linear approximation is sufficiently accurate. Note that we omit the indices \((\tau, u)\) to simplify the notation, as they are fixed.

In a high dimensional setting where the dimension of the covariates \(X, p\), is growing faster than the sample size \(n\), we use a group \(\ell_1\)-penalty to estimate \(b^*\) under the assumption that the coefficient functions are
approximately sparse. In particular, we minimize the following optimization program

$$\hat{b} = \arg \min_{b \in \mathbb{R}^{2p}} \sum_{i=1}^{n} w_i \cdot \rho_r \left( y_i - \Gamma_i^\top b \right) + \lambda_b \|b\|_{1,2},$$

where $\|b\|_{1,2} = \sum_{j=1}^{p} \sqrt{b_j^2 + b_{j+p}^2}$ is the $\ell_{1,2}$ group norm that simultaneously shrinks the coefficients $b_j$ and $b_{j+p}$, $j = 1, \ldots, p$, to zero. Consistency results for $\hat{b}$ have not been established in the existing literature as it is challenging to deal with both the non-differentiable loss function and a nonparametric model. Analysis for this model is more challenging compared to the partially linear varying-coefficient model (Wang et al., 2009), where the nonparametric part is low-dimensional. Furthermore, the model in (3) is strictly more general than the partially linear varying-coefficient model.

### 2.2 High dimensional inference

We describe the challenges that arise in high-dimensional inference. Suppose first that we are interested in performing inference on a low-dimensional parameter $b^* \in \mathbb{R}^p$, where the dimension $p$ is fixed as the sample size $n$ tends to infinity. After observing data, we can estimate $b^*$ by minimizing some loss function $L(b) = L(b; \text{data})$. For instance, in a regression problem with features $x_i$ and response $y_i$, $i = 1, \ldots, n$, typically we would have $L(b) = n^{-1} \sum_{i=1}^{n} \ell(b; x_i, y_i)$, where $\ell(\cdot)$ is the negative log-likelihood under some assumed model.

In this classical setting, we can derive the well-known asymptotically normal distribution of the estimator $\hat{b}$ around the true parameter value $b^*$, by considering the score $\nabla L(b)$. Namely, assuming that the loss is twice differentiable, by taking a Taylor expansion, we can see that the estimator $\hat{b}$ satisfies

$$0 = \nabla L(\hat{b}) = \nabla L(b^*) + \nabla^2 L(b^*) \cdot (\hat{b} - b^*) + \Delta_{\text{Taylor}},$$

where $\Delta_{\text{Taylor}}$ is the error in the Taylor expansion, equal to

$$\Delta_{\text{Taylor}} = \left( \int_0^1 \nabla^2 L \left( (1 - t)b^* + t\hat{b} \right) dt - \nabla^2 L(b^*) \right) \cdot (\hat{b} - b^*).$$
Then by solving for $\hat{b}$, we have

$$\hat{b} = b^* + \left(- \nabla^2 \mathcal{L}(b^*)\right)^{-1} \cdot \left(\nabla \mathcal{L}(b^*) + \Delta_{\text{Taylor}}\right).$$

Asymptotic normality of the error $\hat{b} - b^*$ then follows from two required properties: first, that the $\sqrt{n}$-score at the true parameter, $\sqrt{n} \nabla \mathcal{L}(b^*)$, should be asymptotically normal via a central limit theorem argument, while the Taylor expansion error $\Delta_{\text{Taylor}}$ is vanishing at some appropriately fast rate; and second, that the term $\nabla^2 \mathcal{L}(b^*)$ should converge in probability to some fixed and invertible matrix (specifically, to its expectation).

In high dimensions, however, the above analysis fails. If $b \in \mathbb{R}^p$ where the dimension $p$ grows faster than the sample size $n$, then $\nabla^2 \mathcal{L}(b^*)$ will likely not converge in probability, and in general will not even be invertible. We can instead frame the argument in terms of a low-dimensional parameter of interest combined with a high-dimensional nuisance parameter. We write $b = (a^\top, c^\top)^\top$, where $a \in \mathbb{R}^k$ is the low-dimensional parameter of interests, while $c \in \mathbb{R}^{p-k}$ is the high-dimensional nuisance parameter. For example, if we are working in a regression model, where the loss takes the form $\mathcal{L}(b) = \sum_i \tilde{\ell}(y_i; x_i^\top b)$ for some loss function $\tilde{\ell}$ (e.g., squared loss for a linear regression), then we might decompose the high-dimensional parameter vector as $b = (a^\top, c^\top)^\top$ to separate the coefficients on $k$ features of interest (without loss of generality, the first $k$ coordinates of the feature vectors $X_i$) and the remaining $p-k$ features, which we think of as potential confounders that need to be controlled for in the regression.

Suppose that our estimate of the low-dimensional parameter vector of interest, $a$, is obtained by solving

$$\hat{a} = \arg \min_a \mathcal{L}(a, \bar{c}),$$

where $\bar{c}$ is some preliminary estimator of $c$. For example, in a high-dimensional regression problem, we may run an $\ell_1$-penalized regression first to obtain an initial sparse estimate of the parameters. Once an initial estimate is obtained, we can refit the low-dimensional vector $a$ without a penalty to remove the shrinkage bias. In this setting, we have

$$0 = \nabla_a \mathcal{L}(\hat{a}, \bar{c}) = \nabla_a \mathcal{L}(a^*, c^*) + \nabla_{aa}^2 \mathcal{L}(a^*, c^*) \cdot (\hat{a} - a^*) + \nabla_{ac}^2 \mathcal{L}(a^*, c^*) \cdot (\bar{c} - c^*) + \Delta_{\text{Taylor}2}. \quad (5)$$
\[ \Delta_{\text{Taylor2}} = \left( \int_0^1 \nabla_{aa}^2 \mathcal{L} \left( (1-t)a^* + t\hat{a}, (1-t)c^* + t\hat{c} \right) dt - \nabla_{aa}^2 \mathcal{L}(a^*, c^*) \right) \cdot (\hat{a} - a^*) + \left( \int_0^1 \nabla_{ac}^2 \mathcal{L} \left( (1-t)a^* + t\hat{a}, (1-t)c^* + t\hat{c} \right) dt - \nabla_{ac}^2 \mathcal{L}(a^*, c^*) \right) \cdot (\hat{c} - c^*). \] 

Therefore,

\[ \hat{a} = a^* + \left( -\nabla_{aa}^2 \mathcal{L}(a^*, c^*) \right)^{-1} \left( \nabla_a \mathcal{L}(a^*, c^*) + \nabla_{ac}^2 \mathcal{L}(a^*, c^*)(\hat{c} - c^*) + \Delta_{\text{Taylor2}} \right). \]

Let \( S = (S_a^T, S_c^T)^T = (\nabla_a \mathcal{L}^T, \nabla_c \mathcal{L}^T)^T \) denote the score vector and the negative Hessian matrix is

\[
H = \begin{pmatrix}
H_{aa} & H_{ac} \\
H_{ca} & H_{cc}
\end{pmatrix} = - \begin{pmatrix}
\nabla_{aa}^2 \mathcal{L} & \nabla_{ac}^2 \mathcal{L} \\
\nabla_{ca}^2 \mathcal{L} & \nabla_{cc}^2 \mathcal{L}
\end{pmatrix}.
\]

With this notation, we have

\[ \hat{a} = a^* + \left( H_{aa}(a^*, c^*) \right)^{-1} \left( S_a(a^*, c^*) - H_{ac}(a^*, c^*) \cdot (\hat{c} - c^*) + \Delta_{\text{Taylor2}} \right). \]

To assure the asymptotic normality of the error \( \hat{a} - a^* \), we need to handle the following four terms:

- Asymptotic normality of \( \sqrt{n}S_a(a^*, c^*) \), which will hold by a central limit theorem argument as before;

- Convergence in probability of \( H_{aa}(a^*, c^*) \) to a fixed invertible matrix, which holds since \( a \in \mathbb{R}^k \) is low-dimensional;

- Some control on the distribution of the term \( H_{ac}(a^*, c^*) \cdot (\hat{c} - c^*) \);

- Sufficiently small bound on \( \Delta_{\text{Taylor2}} \), which will hold as long as we assume that \( (\hat{a}, \hat{c}) \) is sufficiently close to \( (a^*, c^*) \).

The third term, \( H_{ac}(a^*, c^*) \cdot (\hat{c} - c^*) \), is the main challenge — since \( c \) is high-dimensional, in general it will not be possible to explicitly characterize the distribution of the error \( \hat{c} - c^* \) in its estimate. Therefore,
we note that a naive refitting does not result in an asymptotically normal estimator and a different strategy is needed for high-dimensional inference.

One strategy to solve this problem is to modify the score method. Specifically, we want the term $H_{ac}(a^*, c^*) \cdot (\tilde{c} - c^*)$ to vanish at a sufficiently fast rate, so that it is smaller than the asymptotically normal term $S_{a}(a^*, c^*)$. The decorrelated score method, described next, provides such a result.

### 2.3 The decorrelated score method

When $\hat{a}$ is defined as the minimizer of the objective function at some fixed estimator $\tilde{c}$ for the nuisance parameter, $\hat{a} = \arg \min_a L(a, \tilde{c})$, we can equivalently obtain $\hat{a}$ as the solution to the score equation $0 = \nabla_a L(a, \tilde{c})$. To decorrelate the score equations, we will instead define $\hat{a}$ as the solution to $0 = \nabla_a L(a, \tilde{c}) - V^\top \nabla_c L(a, \tilde{c})$, where $V \in \mathbb{R}^{(p-k) \times k}$ is a carefully chosen matrix, whose choice will be discusses in detail shortly. The Taylor expansion around the true parameter then gives us

$$0 = S_{a}(\hat{a}, \tilde{c}) - V^\top S_{c}(\hat{a}, \tilde{c}) = S_{a}(\hat{a}, \tilde{c}) - V^\top S_{c}(\hat{a}, \tilde{c})$$

$$- \left( H_{aa}(a^*, c^*) - V^\top H_{ca}(a^*, c^*) \right) \cdot (\hat{a} - a^*)$$

$$- \left( H_{ac}(a^*, c^*) - V^\top H_{cc}(a^*, c^*) \right) \cdot (\tilde{c} - c^*) + \text{Rem.} \quad (7)$$

Solving for $\hat{a}$, we then obtain

$$\hat{a} = a^* + \left( H_{aa}(a^*, c^*) - V^\top H_{ca}(a^*, c^*) \right)^{-1} \cdot$$

$$\left( S_{a}(a^*, c^*) - V^\top S_{c}(a^*, c^*) \right) - \left( H_{ac}(a^*, c^*) - V^\top H_{cc}(a^*, c^*) \right) \cdot (\tilde{c} - c^*) + \text{Rem} \right). \quad (8)$$

In order to show that $\hat{a}$ is asymptotically normal, we would like to show that Term 1 converges in probability to a fixed (and invertible) matrix; Term 2 converges to a normal distribution via a central limit theorem argument; and Term 3 is vanishing (relative to Term 2). The role of the matrix $V$ is precisely to make Term 3 of smaller order compared to Term 2. Specifically, the matrix $V$ is chosen so that $\nabla_{ac}^2 L(a^*, c^*) \approx$
\( V^\top \nabla_{c^*}^2 \mathcal{L}(a^*, c^*) \), enabling us to show that Term 3 is vanishing without obtaining a limiting distribution for the high-dimensional estimator \( \tilde{c} \). In general, the matrix \( V \) cannot be known in advance and is therefore data-dependent rather than fixed. However, in applications we will have that \( V \) converges to some fixed matrix sufficiently fast and all the statements above still hold.

Finding the roots of the score equation may be numerically difficult. We present two methods that can be used in order to obtain \( \hat{a} \) that approximately satisfies the score equation next.

The first method is the one-step correction method. Define

\[
W = \left( \begin{array}{c} I_k \\ -V \end{array} \right) \cdot \left( H_{aa}(a^*, c^*) - V^\top H_{ca}(a^*, c^*) \right)^{-\top}.
\]

Expanding \( W^\top S(\tilde{a}, \tilde{c}) \) at \((a^*, c^*)\) and reorganizing the terms, we obtain

\[
\tilde{a} + W^\top S(\tilde{a}, \tilde{c}) = a^* + W^\top S(a^*, c^*) - W^\top H_c(a^*, c^*) \cdot (\tilde{c} - c^*) + \text{Rem},
\]

where \( H_c = \left( \begin{array}{cc} H_{ac} \\ H_{cc} \end{array} \right) \) and \( \tilde{b} = (\tilde{a}^\top, \tilde{c}^\top)^\top \) is a preliminary, consistent estimator of \( b^* \). Note that the form of the equation above is the same as in (8). This motivates us to define the one-step corrected estimator

\[
a^{OS} = \tilde{a} + W^\top S(\tilde{a}, \tilde{c}).
\]

Similar to the earlier discussion after (8), the normality of \( a^{OS} \) will follow if we choose the matrix \( W \) so that \( W^\top H_c \approx 0_{k,p-k} \) and \( W \) itself converges to some fixed matrix sufficiently fast.

The second method for constructing \( \hat{a} \) relies on the reparametrization of the loss function. In the method sketched above, \( \hat{a} \) is defined as the minimizer of the objective function at a fixed preliminary estimate \( \tilde{c} \) of the nuisance parameter, i.e., \( \hat{a} = \arg\min_a \mathcal{L}(a, \tilde{c}) \). We saw above that the bottleneck in this analysis is the nonzero off-diagonal block of the Hessian matrix, \( H_{ac}(a^*, c^*) \). To avoid the problematic term in the Taylor expansion, we can reparametrize the loss in such a way that the new off-diagonal block will become close to zero. Specifically, consider defining \( \hat{a} \) as the solution to a different optimization problem,

\[
\hat{a} = \arg\min_a \mathcal{L}(a, \tilde{c} - V(a - \tilde{a})), \quad (9)
\]
where $\tilde{a}, \tilde{c}$ are preliminary estimates of $a^*, c^*$.

To better understand the approach in (9), consider again a regression setting where the distribution of each response variable $y_i$ is modeled as a function of $x_i^T b = (x_{i,A}^T, x_{i,A^c}^T)(a^T, c^T)^T$, where the subset $A \subset \{1, \ldots, p\}$ indexes the $k$ features of interest corresponding to the subvector $a$ of the regression coefficients.

In this setting, the negative Hessian matrix $H_{ac}(a^*, c^*)$ will be nonzero whenever features in $A$ are correlated with features in $A^c$; thus, to set this block of the Hessian matrix to be (close to) zero, we can think of modifying the features of interest in the set $A$ by regressing out the confounding features in $A^c$. Specifically, let $v_j \in \mathbb{R}^{p-k}$ be the coefficient vector when regressing the feature $j \in A$ on all features in $A^c$. Then

$$x_i^T b = (x_{i,A}^T, x_{i,A^c}^T)(a^T, c^T)^T = (x_{i,A} - V^T x_{i,A^c})^T a + x_{i,A^c}^T (c + Va),$$

where $V \in \mathbb{R}^{(p-k)\times k}$ is the matrix with columns $v_j$. Note that, in this rearranged expression, the features of interest have been modified to be approximately orthogonal to, or approximately independent from, the nuisance features. Suppose we take $\tilde{c} + V\tilde{a}$ as the preliminary estimate of the coefficients $c + Va$ on the confounding features in this new model. If we then re-estimate the parameter vector of interest $a$, obtaining a new estimate $\hat{a}$, then the final fitted regression is given by

$$(x_{i,A} - V^T x_{i,A^c})^T \hat{a} + x_{i,A^c}^T (\tilde{c} + V\tilde{a}) = (x_{i,A}, x_{i,A^c})^T (\hat{a}, \tilde{c} - V(\hat{a} - \tilde{a})),$$

thus motivating the form of the optimization problem given above in (9).

Defining $\hat{a}$ as the solution to the decorrelated optimization problem (9), the Taylor expansion then gives us

$$0 = \nabla_a \mathcal{L}(a, \tilde{c} - V(a - \tilde{a})) \bigg|_{a = \hat{a}}$$

$$= S_a(\hat{a}, \tilde{c} - V(\hat{a} - \tilde{a})) - V^T S_c(\hat{a}, \tilde{c} - V(\hat{a} - \tilde{a}))$$

$$= S_a(a^*, c^*) - V^T S_c(a^*, c^*) - \left( H_{aa}(a^*, c^*) - V^T H_{ac}(a^*, c^*) \right) \cdot (\hat{a} - a^*)$$

$$- \left( H_{ac}(a^*, c^*) - V^T H_{cc}(a^*, c^*) \right) \cdot (\tilde{c} - V(\hat{a} - \tilde{a}) - c^*) + \text{Rem},$$
where \( \text{Rem} \) is redefined appropriately as the error term in this new expansion. Solving for \( \hat{a} \), we then obtain

\[
\hat{a} = a^* + \left( H_{aa}(a^*, c^*) - V^\top H_{ca}(a^*, c^*) \right)^{-1} \cdot \left( \left( S_a(a^*, c^*) - V^\top S_c(a^*, c^*) \right) - \left( H_{ac}(a^*, c^*) - V^\top H_{cc}(a^*, c^*) \right) \cdot (\bar{c} - V(\hat{a} - \bar{a}) - c^*) + \text{Rem} \right).
\]

Therefore, \( \hat{a} \) is going to be asymptotically normal if Term 1 converges in probability to a fixed (and invertible) matrix; \( \sqrt{n} \)-Term 2 converges to a mean-zero normal distribution via a central limit theorem argument; and Term 3 and the remaining error \( \text{Rem} \) are vanishing (relative to Term 2). As before, the role of the matrix \( V \) is in controlling Term 3. Specifically, the matrix \( V \) is chosen so that \( H_{ac}(a^*, c^*) \approx V^\top H_{cc}(a^*, c^*) \), enabling us to show that Term 3 is vanishing without obtaining a limiting distribution for the high-dimensional initial estimates \( \tilde{a}, \tilde{c} \). In general, the matrix \( V \) cannot be known in advance and is therefore data-dependent rather than fixed, but in our analysis we will see that as long as \( V \) itself is sufficiently close to some fixed matrix, all the statements above will still hold.

### 2.4 Non-differentiable loss in quantile regression

When the loss function \( L \) is non-differentiable, which is the case in quantile regression, approaches based on the decorrelated score method cannot be directly applied. However, a simple modification allows us to proceed in a similar way as before. Assuming that the loss is nondifferentiable and convex, we let \( S(a, c) \) denote the subdifferential of the loss. While \( S(\cdot) \) might be highly nondifferentiable, its expected value is smooth in many problems. Therefore, we can compute the Hessian as the gradient of the expected value of \( S(\cdot) \). In particular, we define the expected score function \( \mathbb{E}S(a, c) \) as the expectation of the score \( S(\cdot) \) at any fixed parameter choice \( (a, c) \). Here it is important to note that, for a random parameter vector \( (\tilde{a}, \tilde{c}) \), the expected score function \( \mathbb{E}S(\tilde{a}, \tilde{c}) \) is not equal to \( \mathbb{E}[S(\tilde{a}, \tilde{c})] \), since this second quantity would evaluate its expectation with respect to the random values of \( \tilde{a} \) and \( \tilde{c} \) as well. With the expected score function defined, we let

\[
H(a, c) = -\nabla \mathbb{E}S(a, c)
\]

be the negative gradient of the expected score.

We specialize the discussion so far to the quantile regression problem at hand. We will base the inference
procedures on the local linear formulation of the estimation problem for the varying-coefficient quantile regression model \(\text{(3)}\). Suppose \(A = \{1, \ldots, k\}\) is the index set for the parameters of interest. Let \(Y \in \mathbb{R}^n\) be the response and \(U \in \mathbb{R}^n\) be the index for the varying coefficient. The matrix of input variables is denoted as \(X = (X_A, X_{A^c}) \in \mathbb{R}^{n \times p}\), where \(X_A \in \mathbb{R}^{n \times k}\) represents the features of interest and \(X_{A^c} \in \mathbb{R}^{n \times (p-k)}\) the other features. Let

\[
\Gamma(u) = (X_A, X_{A^c}, \text{diag}(U - u)X_A, \text{diag}(U - u)X_{A^c}) \in \mathbb{R}^{n \times 2p},
\]

and \(\Gamma_i^T(u) = (x_{i,A}^T, x_{i,A^c}^T, (u_i - u) \cdot x_{i,A}^T, (u_i - u) \cdot x_{i,A^c}^T)\) represents the \(i\)th row vector of \(\Gamma(u)\). The score function for quantile regression is given as

\[
S(a_0, a_1, c_0, c_1) = \sum_{i \in [n]} w_i \cdot \Gamma_i(u) \cdot \Psi_\tau \left( y_i - x_{i,A}^T a_0 - x_{i,A^c}^T c_0 - (u_i - u) \cdot x_{i,A}^T a_1 - (u_i - u) \cdot x_{i,A^c}^T c_1 \right),
\]

where \(\Psi_\tau(u) = \tau - \mathbb{I}(u < 0)\). Let \(b_0 = (a_0^T, c_0^T)^T \in \mathbb{R}^p\), \(b_1 = (a_1^T, c_1^T)^T \in \mathbb{R}^p\), and \(b = (b_0^T, b_1^T)^T \in \mathbb{R}^{2p}\). Then the above score function can be written as

\[
S(b) = \sum_{i \in [n]} w_i \cdot \Gamma_i(u) \cdot \Psi_\tau \left( y_i - \Gamma_i^T(u) \cdot b \right). \tag{11}
\]

Let \(b^*(\tau, u)\) be defined as a solution to \(0 = \mathbb{E}[S(b)]\) when \(h \to 0\). Let \(\tilde{q}_i(\tau, u) = \Gamma_i^T(u) b^*(\tau, u)\) be a local linear approximation to \(q_i(\tau) = q(x_i; \tau, u_i)\). Since \((\tau, u)\) is fixed, we write \(\Gamma_i(u) = \Gamma_i\), \(\tilde{q}_i(\tau, u) = \tilde{q}_i\) and \(q_i(\tau) = q_i\) for notational simplicity. Finally, we use \(\Delta_i = \Delta_i(\tau, u) = \tilde{q}_i - q_i\) to denote the approximation error from using the local linear model for the conditional quantile.

An approximate negative Hessian corresponding to the expected score function is given as

\[
H^* = H(b^*; \tau, u) = \sum_{i \in [n]} w_i \cdot f_i(q_i + \Delta_i) \cdot \Gamma_i \Gamma_i^T. \tag{12}
\]

Let \(V^* \in \mathbb{R}^{2k \times 2p}\) be the rows related to \(X_A, X_A(U - u)\) of an approximate inverse of \(H\) such that

\[
\|V^* H^* - E_a\|_{\infty, F} \leq \lambda^*.
\]
where

\[ \|V^*\|_{\infty,F} = \sup_{i \in [k], j \in [p]} \|V^*_{(i,i+k),(j,j+p)}\|_F, \]

\[ E_a = (e_1, \cdots, e_{2k})^\top \in \mathbb{R}^{2k \times 2p}, \]

and \( \lambda^\star \) is a parameter that will be precisely given in Section 4.

With these preliminaries, we define the one-step correction estimator \( \hat{a}^{OS} \) as

\[ \hat{a}^{OS} = \hat{a} - S_d(\hat{b}, \hat{V}), \]

where

\[ S_d(b, V) := \sum_{i \in [n]} S_{di}(b, V) = \sum_{i \in [n]} -w_i V \Gamma_i \Psi_\tau(y_i - \Gamma_i^\top b), \]

(13)

and \( \hat{V}, \hat{b} \) are plug-in estimators of \( V^*, b^* \) to be defined later, and \( \hat{a} = \hat{b}_{1:2k} \).

### 3 Algorithm

We provide computational details for the three proposed estimators. The first estimator is based on finding the root of the decorrelated-score; the second estimator is based on the one-step correction; and the third estimator is based on the reparametrization of the loss function. As discussed in the previous section, all these estimators are asymptotically equivalent. Estimation proceeds in three steps with the first two steps being the same for all three estimators. In the first step we obtain a pilot estimator of \( b^\star \), while in the second step we obtain \( \hat{V} \). We provide details next.

**Step 1.** Obtain the initial estimator \( \hat{b}_{ini} \) by minimizing the optimization program (3). The kernel weights are given as \( w_i = (nh)^{-1} K (h^{-1} U_i - u) \), while the penalty parameter \( \lambda_b \) is defined in a data dependent fashion as

\[ \lambda_b = c_b \sqrt{\tau(1 - \tau) \log(nhp)} \cdot \left( \max_{j \in [p]} S_n \left[ w_i^2 x_{ij}^2 \right] \right)^{1/2}, \]

(14)

where \( S_n \left[ z_i \right] \) denotes the summation, \( S_n \left[ z_i \right] = \sum_{i \in [n]} z_i \), and \( c_b \) is a data independent constant. We subsequently threshold elements of \( \hat{b}_{ini} \) to obtain \( \hat{b} \) with

\[ \hat{b}_j = \begin{cases} \hat{b}_{ini} \cdot 1 \left\{ \left( \hat{b}_{ini}^2 \right)^2 + \left( \hat{b}_{ini}^{j+p} \right)^2 > \lambda_b^2 \right\}, & j = 1, \ldots, p, \\ \hat{b}_{ini} \cdot 1 \left\{ \left( \hat{b}_{ini}^2 \right)^2 + \left( \hat{b}_{ini}^{j-p} \right)^2 > \lambda_b^2 \right\}, & j = p + 1, \ldots, 2p, \end{cases} \]

to ensure the sparsity of the estimator for Theorem 1.
Step 2. Obtain \( \hat{V} \) by

\[
\hat{V} = \arg \min_{V \in \mathbb{R}^{2k \times 2p}} \left\{ \text{trace} \left( \frac{1}{2} V \hat{H} V^\top - E_a V^\top \right) + \lambda_V \| V \|_1, F \right\},
\]

(15)

where \( \lambda_V = n^{-1} c_v \sqrt{n h \Phi^{-1} \left( 1 - \frac{0.05}{2 nh} \right)} \) with \( c_v \) being a data independent constant; and \( \hat{H} = \sum_{i \in [n]} w_i \hat{f}_i \Gamma_i \Gamma_i^\top \) with \( w_i \) being the kernel weight as defined in Step 1 and \( \hat{f}_i \) is computed with a data adaptive procedure as

\[
\hat{f}_i = \frac{1}{2h_f} \left\{ |y_i - \Gamma_i^\top \hat{b}| \leq h_f \right\}
\]

with

\[
h_f = (\Phi^{-1}(\tau + h_p) - \Phi^{-1}(\tau - h_p)) \min \left\{ \sqrt{\text{Var}(\hat{e})}, \frac{Q_{0.75}(\hat{e}) - Q_{0.25}(\hat{e})}{1.34} \right\},
\]

where

\[
\hat{e}_i = y_i - \Gamma_i^\top \hat{b}, \quad Q_\alpha(\hat{e}) = \inf_q \left\{ q : \frac{\sum_i w_i \mathbf{1}\{ \hat{e}_i \leq q \}}{\sum_i w_i} \geq \alpha \right\},
\]

\[
\text{Var}(\hat{e}) = \frac{\sum_i w_i \left( \hat{e}_i - \frac{\sum_j w_j \hat{e}_j}{\sum_j w_j} \right)^2}{\sum_i w_i},
\]

and

\[
h_p = n^{-1/3} \left\{ \Phi^{-1}(0.975) \right\}^{2/3} \left\{ \frac{1.5[\phi(\Phi^{-1}(\tau))]^2}{2[\Phi^{-1}(\tau)]^2 + 1} \right\}^{1/3}
\]

is the Powell bandwidth defined in Koenker (2005, Section 3.4.4).

Step 3. Here we obtain our final estimator \( \tilde{a} \) using one of the three procedures.

1. Finding the root of the decorrelated score. We would like to construct \( \tilde{a} \) by solving for \( \sum_i \tilde{S}_i(a) = 0 \) where \( \tilde{S}_i(a) = S_{di}((a^\top, \hat{c})^\top, \hat{V}) \) with \( S_{di} \) defined in (13). Because \( \sum_i \tilde{S}_i(a) \) is not continuous, we can approximately solve the equation by

\[
\tilde{a}^{DS} = \arg \min \left\{ \sum_i \tilde{S}_i(a)^\top \left[ \sum_i \tilde{S}_i(a) \tilde{S}_i(a)^\top \right]^{-1} \sum_i \tilde{S}_i(a) \right\}.
\]

Minimizing the above problem is not computationally simple. The following two strategies might be preferred, as discussed in Section 2.3.
2. The one step correction estimator. We compute the estimator as

\[ \hat{a}^{OS} = \hat{a} + \sum_{i \in [n]} w_i \hat{V}_i \Gamma_i^\top \Psi_\tau (y_i - \Gamma_i^\top \hat{b}). \]  

(17)

3. The reparametrization estimator. We first obtain \( \tilde{\Gamma}_i, \tilde{y}_i \) as \( \tilde{\Gamma}_i = \Gamma_{i,A} - \hat{V}_i^2 \Gamma_{i,A} c \) and \( \tilde{y}_i = y_i - \Gamma_i^\top \hat{b} \), where \( \hat{V}_2 = \hat{V}_{11}^{-1} \hat{V}_{12}, \hat{V}_{11} = \hat{V}_{1:2k} \in \mathbb{R}^{2k \times 2k} \) and \( \hat{V}_{12} = \hat{V}_{(2k+1):2p} \in \mathbb{R}^{2k \times 2(p-k)} \). Then the estimators is computed as

\[ \hat{a}^{RP} = \arg \min_a \sum_i w_i \cdot \rho_{\tau} \left( \tilde{y}_i - \tilde{\Gamma}_i^\top a \right). \]  

(18)

With the estimator \( \hat{a} \), being \( \hat{a}^{DS}, \hat{a}^{OS} \), or \( \hat{a}^{PR} \), we can perform statistical inference about the parameter of interests, \( a \). For any one of the three estimamors, we have that

\[ \hat{\Sigma}_a^{-1/2}(\hat{a} - a) \sim N(0, I_k), \]

where the covariance matrix is computed as

\[ \hat{\Sigma}_a = nh \sum_i w_i^2 \hat{V}_i \Gamma_i^\top \Psi_\tau^2 (y_i - \Gamma_i^\top \hat{b}) \Gamma_i \hat{V}_i^\top. \]

We end this section with some remarks on the computation. The kernel weights we chose in our simulation studies are given as

\[ w_i = (nh)^{-1} \mathbb{1} \{ |U_i - u|/h < 0.5 \} \]

with \( h = c_h n^{-1/3} \) and \( c_h = 4 \). However, we note that any kernel function that satisfies Assumption [1] presented later in Section 4.1 can be used. Many frequently used kernels, such as the Gaussian kernel and box kernel, satisfy this assumption. We also set \( c_b = 0.4 \) and \( c_v = 0.02 \) in our numerical studies. The performance of the algorithm is not very sensitive to the choice of these parameters. Both in Step 1 and Step 2 of the algorithm, one can perform optional refitting of the selected coefficients to improve finite sample performance. For example, in Step 1, let \( S \in \mathbb{R}^s \) be the support of the covariates in \( \Gamma \) corresponding to \( \hat{b} \),
and $\Gamma_{i,S}$ and $b_S$ are the corresponding entries in $\Gamma_i$ and $b$, then

$$\hat{b}_{\text{post}} = \left\{ \arg \min_{\hat{b} \in \mathbb{R}^p} \sum_{i=1}^n w_i \cdot \rho_T \left( y_i - \Gamma_{i,S}^\top \hat{b}_S \right) : b_j = 0 \forall j \in S^c \right\}$$

can be used to replace $\hat{b}$.

## 4 Main results

In this section, we present our main results. We start by detailing the assumptions in Section 4.1. Results on estimation consistency are presented in Section 4.2. Finally, we give results on the asymptotic normality of the estimator in Section 4.3.

### 4.1 Assumptions

We state the assumptions needed to establish our results.

**Assumption 1.** (Kernel assumptions) The kernel function $K(\cdot)$ satisfies

- $K(t) \leq \nu_0 < \infty$ for all $t$, \[ \int K(u)du = \nu_1 < \infty, \]
- $\int K^2(u)du = \nu_2 < \infty$, \[ \int K(u)u^2 du = \mu_2 < \infty, \]
- $\int K(u)u^4 du = \mu_4 < \infty$.

The kernel is chosen by a statistician, so the above assumption does not put restrictions on the data generating process. A number of standard kernels such as the Gaussian kernel, box kernel, and Epanechnikov kernel, all satisfy the above assumption.

**Assumption 2.** (Assumptions on $U$) We assume $U$ has bounded support. Without loss of generality, we assume $U \in [0, 1]$. Let $f_U(u)$ be the density of $U$. There exists $\bar{f}$ such that $f_U(u) \leq \bar{f}$. 


From Assumptions 1 and 2, the kernel weights $w_i$’s satisfy the following with high probability

$$\|w_i\|_{\infty} \leq \frac{\nu_0}{nh} \leq \frac{B_K}{nh}, \quad \sum_i w_i \leq B_K,$$

$$\sum_i w_i \left(\frac{u_i - u}{h}\right)^2 \leq B_K, \quad \text{and} \quad \sum_i w_i \left(\frac{u_i - u}{h}\right)^4 \leq B_K$$

for some constant $B_K > 0$.

**Assumption 3.** (Assumptions on the distribution of $Y$) Let $f_i(y)$ be the conditional density of $Y_i$ given $X_i = x_i, U_i = u_i$. We assume that there exist constants $\underline{f}, \bar{f}, \bar{f}'$ such that

$$0 < \underline{f} \leq f_i(y) \leq \bar{f}, \quad \text{and} \quad |f_i'(y)| \leq \bar{f}' \quad \text{for all } y.$$

This type of assumption on the conditional distribution of $Y$ is commonly used in the literature on quantile regression, for example, see Belloni et al. (2016a).

**Assumption 4.** (Approximate linear sparsity and smoothness of $q(x; \tau, u)$) Assume there exists a smooth and sparse $\beta^*(\tau, u)$ such that:

- $u \mapsto \beta^*(\tau, u)$ is differentiable for all $\tau \in [\varepsilon, 1 - \varepsilon]$ and

$$\|\beta^*(\tau, u') - \beta^*(\tau, u) - (u' - u) \cdot \nabla_u \beta^*(\tau, u)\|_2 \leq B_\beta(u' - u)^2;$$

- the supports of $\beta^*(u, \tau)$ and $\partial_u \beta^*(\tau, u)$ are sparse; that is, for the sets

$$S := \{ j \in [p] \mid \beta^*_j(\tau, u) \neq 0 \}$$

and

$$S' := \{ j \in [p] \mid \beta^*_j(\tau, u) \neq 0 \text{ or } \partial_u \beta^*_j(\tau, u) \neq 0 \},$$

we have $s := |S| \ll n$ and $|S'| \leq s_1 := c_1 s$ for some constant $c_1$.

We assume that the quantile function $q_i = q(x_i; \tau, u_i)$ can be well approximated by a linear function
\(x_i^\top \beta^*(\tau, u_i)\); specifically,

\[
P\left\{ Y \leq x_i^\top \beta^*(\tau, u_i) \ \bigg| \ X = x_i, U = u_i \right\} = \tau + R_i,
\]

where

\[
\sqrt{\sum_i w_i R_i^2} = \epsilon_R = O\left(\sqrt{\frac{\log(np)}{nh}}\right).
\]

This assumption requires that the conditional quantiles of \(Y\) approximately follow a linear varying-coefficient model and the approximation error is vanishing as \(n \to \infty\). In addition, the varying-time coefficient \(\beta^*(\tau, u)\) is Hölder smooth, sparse and has sparse first derivatives.

For the case when \(u\) and \(\tau\) are fixed, we will write \(\beta^* = \beta^*(\tau, u)\). Let \(b^* = b^*(\tau, u) = (\beta^*(\tau, u)^\top, \nabla_u^\top \beta^*(\tau, u))^\top\)

and write \(q_i = q(x_i; \tau, u_i), \tilde{q}_i = \Gamma_i^\top b^*\) as a local linear approximation to \(q_i\). Let

\[
H = \sum_{i \in [n]} w_i \cdot f_i(q_i) \cdot \Gamma_i \Gamma_i^\top \quad \text{and} \quad H^* = \sum_{i \in [n]} w_i \cdot f_i(\tilde{q}_i) \cdot \Gamma_i \Gamma_i^\top.
\]

**Assumption 5.** (Assumptions on the Hessian) Let \(V^*\) be the rows related to \([X_A, X_A(U - u)]\) of an approximate inverse of \(H^*\). We assume that

\[
\|H^* V^* - E_a\|_{\infty,F} \leq \lambda^* = O\left(B_V\sqrt{\frac{\log p}{nhf}}\right), \quad \|V^*\|_{0,F} \leq s_2 = c_2 s,
\]

where \(\|V\|_{0,F} := |\{(i, j) : i \in [k], j \in [p], V_{(i,i+k),(j,j+p)} \neq 0\}|, \|V\|_{\infty,F} := \max_{i \in [k], j \in [p]} \|V_{(i,i+k),(j,j+p)}\|_F\) and \(\max_{i \in [n]} \|V^* \Gamma_i\|_2 = B_V \asymp \log p\). Furthermore, we have

\[
(nh)^{-1} s B_V^2 \log p = o(1) \quad \text{and} \quad \log(B_V^2 h_f h) = o(\log p).
\]

Assumption 5 holds when \(X_A\) follows a multivariate approximately sparse linear model with respect to \(X_{A'},\) where we require the coefficients to be approximately linear, sparse and smooth (see Appendix C). For example, when the distribution of \(X\) does not depend on \(U\) and the exact sparse linear model holds, Assumption 5 obviously holds.

**Assumption 6.** (Assumptions on \(X\)) We make the following assumptions on the covariate \(X\):
• **Boundedness:** there exists a constant $B_X$ such that with high probability,

$$
\max_i \|x_i\|_\infty \leq B_X \text{ and } \max_{j \in [p]} \sum_i w_i^2 x_{ij}^2 \leq \frac{B_X^2 B^2_K}{nh}.
$$

• **Restricted eigenvalues:** Consider the following cones

$$
C(s_1) = \{ \theta : \|\theta\|_0 \leq s_1 \text{ and } \|\theta\|_2 = 1 \}, \text{ and }
$$

$$
C(S_2) = \{ \Theta \in \mathbb{R}^{2k \times 2p} : \|\Theta_{S_2^c}\|_1,\| \Theta_{S_2^c}\|_F \leq 6\|\Theta_{S_2}\|_1,\|\Theta\|_1 = 1 \},
$$

where $S_2 = \{(i, j) : \|V^*_i, (i, i+k), (j, j+p)\|_F > 0 \}$ is the support of $V^*$. By Assumption 5, $|S_2| \leq s_2$. We assume there exist $0 < \kappa_-^2 \leq \kappa_+^2 < \infty$ such that

$$
\kappa_-^2 \leq \sum_{i \in [n]} w_i (\Gamma_i^T \theta)^2 \leq \kappa_+^2 \quad \text{for all } \theta \in C(s_1) \text{ and } (19)
$$

$$
\kappa_-^2 \leq \sum_{i \in [n]} w_i \text{trace}(\Theta^T \Gamma_i \Gamma_i^T \Theta) \leq \kappa_+^2 \quad \text{for all } \Theta \in C(S_2). \quad (20)
$$

• **For some constant $\kappa_q > 0$,**

$$
\inf_{\|\delta\|_1 \leq \frac{\sqrt{2s} \sqrt{\log p}}{\sqrt{n} \sqrt{\kappa_h f}}} \left( \frac{f \cdot \sum_{i \in [n]} w_i \cdot (\Gamma_i^T \delta)^2}{f' \cdot \sum_{i \in [n]} w_i \cdot (\Gamma_i^T \delta)^3} \right)^{3/2} \geq \kappa_q. \quad (21)
$$

The assumptions on the design $X$ are mild and commonly used in the literature on high-dimensional estimation and inference. For example, boundedness and restricted eigenvalue condition was used in Negahban et al. (2012). The condition (21) is a mild growth condition, which is satisfied for many design matrices $X$, see Belloni et al. (2016a) and Belloni and Chernozhukov (2011).

Finally, we need the following growth condition.

**Assumption 7.** (Growth conditions) We assume

$$
h \asymp O(n^{-1/3}), \quad h_f \asymp O(n^{-1/3}), \quad \text{and} \quad (nhf)^{-1/2} s \log p \log(np) = o(1).
$$
With these assumptions, we are ready to present our main results next.

4.2 Consistency and sparsity results of the initial estimators

We establish the asymptotic properties of the initial estimators in Step 1 and Step 2 from Section 3.

**Theorem 1.** Under Assumptions 1, 2, 3, 4, 6 and 7, the estimator \( \hat{b} \) from Step 1 in Section 3 satisfies

\[
S_n \left[ w_i \cdot \left( \Gamma_i^\top \left( \hat{b} - b^* \right) \right)^2 \right] \leq O_p \left( \frac{s \log(np)}{nh} \right),
\]

(22)

\[
\| \hat{b} - b^* \|_{1,2} \leq O_p \left( \frac{s \sqrt{\log(np)}}{nh} \right), \quad \text{and}
\]

(23)

\[
\| \hat{b} \|_{0,2} \leq O_p(s),
\]

(24)

where \( S_n [z_i] := \sum_{i \in [n]} z_i \), \( \|b\|_{1,2} := \sum_{i=1}^p \sqrt{b_i^2 + b_{i+p}^2} \) and \( \|b\|_{0,2} \) is defined as the \( \ell_0 \) norm of the vector \( \left( \sqrt{b_1^2 + b_{1+p}^2}, \ldots, \sqrt{b_p^2 + b_{2p}} \right) \).

Theorem 1 gives us convergence results regarding the \( \ell_{1,2} \)-penalized quantile regression estimator from (3). In particular, (22) gives the rate of convergence of the prediction \( \ell_2 \)-norm, (23) gives the \( \ell_{1,2} \)-norm of the error, and (24) gives the sparsity of \( \hat{b} \) in Step 1 of Section 3. Both Theorem 2 and Theorem 3 rely on these conditions. The extra growth condition in Assumption 6 is mild. Specifically, with the penalty parameter \( \lambda_b \approx O \left( \sqrt{\frac{\log p}{nh}} \right) \) the assumption is satisfied. The sparsity here is achieved by truncating the small components in \( \hat{b}^\text{ini} \) to zero, while maintaining the same rate of convergence.

**Theorem 2.** Suppose the assumptions for Theorem 1 hold and the estimator \( \hat{b} \) obtained in Step 1 satisfies (22), (23), and (24). Furthermore, suppose that \( \lambda_V \geq 2\lambda^* \) and Assumption 5 holds for \( \lambda^* \). Then \( \hat{V} \) from Step 2 satisfies

\[
\| \hat{V} - V^* \|_F \leq O_p \left( B_V \sqrt{\frac{s \log(np)}{nhh_f}} \right), \quad \text{and}
\]

(25)

\[
\| \hat{V} - V^* \|_{1,F} \leq O_p \left( sB_V \sqrt{\frac{\log(np)}{nhh_f}} \right),
\]

(26)

where \( \|V\|_{1,F} := \sum_{i \in [k], j \in [p]} \| V_{(i,i+k), (j,j+p)} \|_F \).

Theorem 2 gives the convergence rate of the \( \ell_{1,2} \)-norm and prediction \( \ell_2 \)-norm of \( \hat{V} \) in Step 2 of Section 3.
Because the $\widehat{H}$ in the objective function relies on the estimator $\widehat{b}$, both the convergence and sparsity results from Theorem 1 are needed.

### 4.3 Normality result of the final estimators

We state the asymptotic normality result for the one step estimator.

**Theorem 3.** *(Normality for the one-step estimator)* Assume that Assumptions 1–7 hold and (22), (23), (24), (25), (26) hold. Then the one step estimator defined in (17) satisfies

$$
\sqrt{nh}\hat{\Sigma}_a^{-1/2}(\hat{a}^{OS} - a^*) \rightarrow_d N(0, I_{2k}),
$$

where the covariance matrix $\hat{\Sigma}_a$ is estimated as either

$$
\hat{\Sigma}_a = nh\hat{V} \left\{ \sum_i w_i^2 \Gamma_i \Psi_\tau(y_i - \Gamma_i^\top \hat{b})\Psi_\tau(y_i - \Gamma_i^\top \hat{b})^\top \Gamma_i^\top \right\} \hat{V}^\top \tag{27}
$$

or

$$
\hat{\Sigma}_a = \tau(1 - \tau)\nu_2 \hat{V} \left\{ \sum_j w_j \Gamma_j \Gamma_j^\top \right\} \hat{V}^\top. \tag{28}
$$

Theorem 3 tells us that the one step estimator is $\sqrt{nh}$-consistent. The covariance (28) is the expected version of (27), where (27) comes from the central limit theorem. The estimators from the decorrelated score ($\hat{a}^{DS}$) and reparameterization ($\hat{a}^{RP}$) are both asymptotically equivalent to $\hat{a}^{OS}$; the detailed proof is in the appendix.

### 5 Numerical studies

Through an empirical study, we investigate the finite sample performance of our confidence interval construction approach and show that it works under high-dimensional settings and is robust to different error distributions.

For each individual, the data is generated independently and identically distributed from the following distribution of $\{U, X_1, X_{-1}, \epsilon, Y\}$. First, we generate the index variables as $U \sim \text{Unif}[0, 2]$ and the confounding...
variables as

\[ X_{-1} | U \sim \mathcal{N}(\mu(U), \Sigma(U)), \]

where \( \mu_j(U) = a_0 \cdot j \cdot (U^{a_1} - 1) \) and \( \Sigma(U) \) is an autoregressive (AR) covariance with elements \( \Sigma(U)_{i,j} = \rho(U)^{|i-j|} \) and the parameter \( \rho(U) = \rho^{1+b_0(U^{b_1} - 1)} \). Note that when \( a_1 = b_1 = 0 \) we have a model where the nuisance covariates \( X_{-1} | U \) are homogeneous and do not depend on the index variable \( U \). We then generate \( X_1 \) and \( Y \). Let \( \nu \in \mathbb{R}^{p-1} \) with \( \nu_j - 1 = 1/j^2, j = 2, \cdots, p \), and \( \beta = (1/2, c_y \nu^\top)^\top \). Then

\[
X_1 = X_{-1}(c_x \nu) + \epsilon_x, \text{ where } \epsilon_x \sim \mathcal{N}(0, 1) \text{ and is independent of } (X_{-1}, U),
\]

\[ Y = X\beta(U) + \epsilon, \text{ where } \beta(U) = \beta(c_0 U^{c_1} + 1 - c_0), \]

and \( \epsilon | X, U \sim \sigma_e(U) \cdot F_e \cdot \sqrt{(2 - \gamma + \gamma \cdot x_1^2)/2} \).

Note that \( \epsilon \) is allowed to depend on \( X \). In particular, \( \gamma = 0 \) leads to a homogeneous setting and \( \gamma = 1 \) leads to a heterogeneous setting. Here \( \sigma_e(U) = \sigma_e(1 + d_0(U^{d_1} - 1)) \) and \( F_e \) is either the standard Gaussian or \( t \) distribution with 3 degrees of freedom (\( t(3) \)).

Specially, this data generation process leads to the following quantiles:

\[
q(x; \tau, u) = x\beta(u) + \sigma_e(u) \cdot \sqrt{(2 - \gamma + \gamma \cdot x_1^2)/2} \cdot q_e(\tau),
\]

where \( q_e(\tau) \) is the \( \tau \)-th quantile of the distribution \( F_e \). In this simulation, we are interested in the inference for \( \beta_1(\tau, u) \in \mathbb{R}^1 \) at the point \( (\tau, u) = (0.5, 1) \). At this point, \( q(x; 0.5, 1) = x\beta(1) \) satisfy Assumption 5.

The coefficients \( c_x \) and \( c_y \) are used to control the \( R^2 \) in different regression equations. We use \( R_y^2 \) to denote the \( R^2 \) in the equation \( Y - X_1\beta_1(U) = X_{-1}\beta_{-1}(U) + \epsilon \), while \( R_x^2 \) denotes the \( R^2 \) in the equation \( X_1 = X_{-1}(c_x \nu) + \epsilon_x \). We vary the parameters and choose \( c_y, c_x \) to form different combinations of \( (R_y^2, R_x^2) \). Details can be found in Appendix B.

We evaluate the performance of our algorithms described in Section 3 (DS (16), OS (17) and RP (18)) and compare them with the Oracle and the Naive methods. For the oracle method, we assume that the true (low dimensional) set of predictors is known in advance and our inference is based on the kernel weighted quantile regression on the true set of variables. For the Naive method, we fit the kernel weighted penalized regression as in Step 1. Then we fit the post-regularized regression and do the inference treating the set
Table 1: Simulation results for the correlation setting $(R^2_x, R^2_y) = (0.7, 0.3)$.

\[
S = \{ j : \hat{\beta}_j \neq 0 \}\text{ as fixed. We compare their performance from } M = 100 \text{ simulations in terms of the bias, empirical standard deviation (SD), the expected estimated standard error (ESE), and coverage rate for the 95% nominal confidence intervals (CR).}
\]

The simulation results for two settings with normally distributed and $t(3)$-distributed $\epsilon$’s are listed in Table 1. Additional simulation results are presented in Table 2 in Appendix B. From the simulation, the oracle method consistently produce confidence intervals with coverage rate close to the nominal value 95% in all simulation settings. The Naive estimator has some significant bias when $R^2_y$ is small and $R^2_x$ is large. Furthermore, without any correction, the confidence intervals tend to have significantly lower coverage than the nominal value. The OS, DS, and PR estimators have relatively low bias compared to the naive method in all settings; also, their coverage rates are closer to the nominal value than the naive method.

We plot the trend of coverage rate for all methods with the change of $R^2_y$ and $R^2_x$ in Figure 1 to better understand the performance of the different methods as the data generating distribution changes. We find that the confidence intervals from the Naive method significantly undercover when the response $Y$ has low correlation with the covariates $X$ and $X_1$ has high correlation with the confounding variables $X_{-1}$. On the
Figure 1: Left: CR of different methods with $R^2_y$ fixed at 0.3 and changing $R^2_x$. Right: CR of different methods with $R^2_x$ fixed at 0.7 and changing $R^2_y$. In the simulation, the error term $\epsilon$ is normally distributed and $\gamma = 0$.

Figure 2: Inference for fat. Left: fixing scaled dietary beta-carotene level at 0, 95% confidence intervals for different $\tau$. Right: fixing $\tau = 0.5$, 95% confidence intervals for different beta-carotene levels.

other hand, the proposed methods provide satisfactory coverage across all settings. Regarding the widths of the confidence intervals, the Naive method underestimates the standard error in some data settings, resulting in low coverage rates. The OS, DS, and PR methods provide CI’s with the correct coverage rate and the widths of the CI’s are slightly larger than those of the Oracle method. Among the three proposed methods, the OS method has the best finite sample performance in terms of stability and computational cost.

6 Real data example

As an illustration of our method, we apply our methods to analyze the plasma beta-carotene level data set collected by a cross-sectional study (Nierenberg et al., 1989). This dataset consists of 315 observations on 14 variables. Our interest is to study the relationship between the plasma beta-carotene level and the following
variables: age, sex, smoking status, quetelet (BMI), vitamin use, number of calories consumed per day, grams of fiber consumed per day, number of alcoholic drinks consumed per week, cholesterol consumed per day, dietary beta-carotene consumed per day and dietary retinol consumed per day.

We fit our varying coefficient model by using dietary beta-carotene consumption as the index $U$. We replace all categorical variables with dummy variables and standardize all variables. Then we include all two-way interactions in our model, so we have 116 confounding variables in total. We take the plasma beta-carotene level as the outcome $Y$, the fat intake (in grams) or the fiber intake (in grams) as the treatment effect $X_A$ respectively, and the remaining variables as the confounding variables. We use our model to make inference on $\beta(\tau, u)$ at different beta-carotene consumption level $u$ and different quantiles $\tau$.

Our results are shown in Figures 2 and 3. The Naive method is shown in red and we compare it with the one-step correction (OS) method. From Figure 2, the result of the naive method suggests that the fat intake is significantly negatively correlated with the plasma beta-carotene level; however, the OS method suggests that this negative effect is not significant. For fiber, the Naive method underestimated the positive effect of fiber intake on the plasma beta-carotene level, whereas the OS method showed that this positive relationship is significant. Furthermore, from Figure 3 (right plot), we can see an increasing trend of the effect of fiber intake with the increasing level of dietary beta-carotene.

7 Discussion

We studied high-dimensional quantile regression model with varying coefficients that allows us to capture non-stationary effects of the input variables across time. Despite the importance in practical applications,
no valid statistical inferential tools were previously available for this problem. We addressed this issue by developing new tools for statistical inference, allowing us to construct valid confidence bands and honest tests for nonparametric coefficient functions of time and quantile. Performing statistical inference in this regime is challenging due to the usage of model selection techniques in estimation. Our inferential results do not rely on correct model selection and are valid for a range of data generating procedures, where one cannot expect for perfect model recovery. The statistical framework allows us to construct a confidence interval at a fixed point in time and a fixed quantile based on a normal approximation, as well as a uniform confidence band for the nonparametric coefficient function based on a Gaussian process approximation. We perform numerical simulations to demonstrate the finite sample performance of our method. In addition, we also illustrate the performance of the methods through an application to a real data example.

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A  Technical details

A.1  Notations

We summarize the additional notation used throughout the appendix. We let $\Psi_\tau(u) = \tau - 1 \{u < 0\}$, $\rho_\tau(u) = u \Psi_\tau(u)$, and use

$$W_i(\delta) = \rho_\tau(y_i - (q_i + \delta)) - \rho_\tau(y_i - q_i);$$

$$W^\#_i(\delta) = -\delta \Psi_\tau(y_i - q_i);$$

and

$$W^\natural_i(\delta) = \int_0^\delta [1 \{y_i \leq q_i + z\} - 1 \{y_i \leq q_i\}] dz$$

$$= (y_i - (q_i + \delta)) [1 \{q_i + \delta \leq y_i < q_i\} - 1 \{q_i \leq y_i < q_i + \delta\}].$$

We denote the sum as $S_n[\cdot] = \sum_{i \in [n]} \cdot$ and $E S_n[\cdot] = E [S_n[\cdot]]$. Denote the negative Hessian

$$H = S_n[w_i f_i(q_i) \cdot \Gamma_i \Gamma_i^T],$$

$$H^* = S_n[w_i f_i(\tilde{q}_i) \cdot \Gamma_i \Gamma_i^T],$$

$$H(\delta) = ES_n[w_i \hat{f}_i(\delta) \cdot \Gamma_i \Gamma_i^T] = S_n[w_i \cdot E [\hat{f}_i(\delta)] \cdot \Gamma_i \Gamma_i^T],$$

and

$$\hat{H}(\delta) = S_n[w_i \hat{f}_i(\delta) \cdot \Gamma_i \Gamma_i^T],$$

where

$$\hat{f}_i(\delta) = \frac{1 \{|y_i - \Gamma_i^T (b^* + \delta)| \leq h_f\}}{2h_f}.$$

Let $\Delta_i = \tilde{q}_i - q_i$. Recall that $V^* \in \mathbb{R}^{2k \times 2p}$ are the rows related to $X_A, X_A(U - u)$ of an approximate inverse of $H^*$ such that $\|H^* V^* - E_a\|_{\infty,F} \leq \lambda^*$ and $\|V^*\|_{F,0} \leq s_2 = c_2s$. Its estimator $\hat{V}$ is as defined in (15). The one step correction estimator $\hat{a}^{OS} = \hat{a} - S(\hat{a}, \hat{c}, \hat{V})$, where $S(a,c,V) = -\sum_i w_i V_i \Psi_\tau(y_i - \Gamma_i^T (a^T, c^T)^T).$
A.2 Proof of Theorem 3

Recall the definitions of $\hat{\alpha}^{OS}$ in (17) and $S_d(b, V)$ in (13). We have

$$\hat{\alpha}^{OS} - \alpha^* = \hat{\alpha} - \alpha^* - \left\{ S_d((\hat{\alpha}^\top, \hat{c}^\top)^\top, V^*) - S_d((\alpha^\star^\top, c^\star^\top)^\top, V^*) \right\}$$

$$- \left\{ S_d((\hat{\alpha}^\top, \hat{c}^\top)^\top, \hat{V}) - S_d((\alpha^\star^\top, c^\star^\top)^\top, V^*) \right\} - S_d((\alpha^\star^\top, c^\star^\top)^\top, V^*).$$

By Lemma 1 and Lemma 2 (presented later in Section A.4), we have

$$\|\hat{\alpha} - \alpha^* - \left\{ S_d((\hat{\alpha}^\top, \hat{c}^\top)^\top, V^*) - S_d((\alpha^\star^\top, c^\star^\top)^\top, V^*) \right\}\|_2 = o_p\left(\sqrt{\frac{1}{nh}}\right)$$

and

$$\|S_d((\hat{\alpha}^\top, \hat{c}^\top)^\top, \hat{V}) - S_d((\alpha^\star^\top, c^\star^\top)^\top, V^*)\|_2 = o_p\left(\sqrt{\frac{1}{nh}}\right).$$

Therefore,

$$\hat{\alpha}^{OS} - \alpha^* = -S_d((\alpha^\star^\top, c^\star^\top), V^*) + o_p\left(\sqrt{\frac{1}{nh}}\right)$$

$$= \sum_i w_i V^\star \Gamma_i \Psi_\tau(y_i - q_i)$$

$$- \sum_i w_i V^\star \Gamma_i \{ \Psi_\tau(y_i - q_i) - \Psi_\tau(y_i - \tilde{q}_i) \} + o_p\left(\sqrt{\frac{1}{nh}}\right)$$

$$= \sum_i w_i V^\star \Gamma_i \Psi_\tau(y_i - q_i) + o_p\left(\sqrt{\frac{1}{nh}}\right).$$

The last equality holds by Lemma 3, which we present later in Section A.4.

Because Assumptions 3 and 6 hold, by Lindeberg CLT, we have

$$\sqrt{nh} \sum_i w_i V^\star \Gamma_i \Psi_\tau(y_i - q_i) \rightarrow N(0, \Sigma)$$

and, therefore,

$$\sqrt{nh} \Sigma^{-1/2} (\hat{\alpha}^{OS} - \alpha^*) \overset{d}{\rightarrow} N(0, I_{2k}),$$

where $\Sigma = \tau(1-\tau)\nu_2 \lim_{n\rightarrow\infty} E \left[ \{ V^\star \Gamma^\top V^\star^\top \} \mid U = u \right]$. By Lemma 4 (presented later in Section A.4),
for both forms of $\hat{\Sigma}_a$, we have

$$\hat{\Sigma}_a \xrightarrow{p} \Sigma.$$  

Therefore by Slutsky’s Theorem,

$$\sqrt{n} \hat{\Sigma}_a^{-1/2} (\hat{a}^{OS} - a^*) \xrightarrow{d} N(0, I_{2k}).$$

A.3 Asymptotic equivalence of decorrelated score, one-step and reparameterization estimators

Denote

$$H_{ac}(f, V) = \sum_i w_i f_i V \Gamma_i \left[ \begin{array}{cc} 0_{2(p-k) \times 2k} & I_{2(p-k)} \end{array} \right], \quad \text{and}$$

$$H_{aa}(f, V) = \sum_i w_i f_i V \Gamma_i \left[ \begin{array}{cc} I_{2k} & 0_{2k \times 2(p-k)} \end{array} \right].$$

The decorrelated score estimator $\hat{a}^{DS}$ in (16) that minimizes

$$S_d((\hat{a}^{DS}, \hat{c}^\top, \hat{V})^\top \Psi^{-1} S_d((a^\top, c^\top)^\top, \hat{V}),$$

where

$$\Psi = \sum_i w_i^2 \hat{V} \Gamma_i \Psi \tau(y_i - \Gamma_i^\top \hat{b}) \Psi \tau(y_i - \Gamma_i^\top \hat{b})^\top \Gamma_i^\top \hat{V} \top,$$

is asymptotically equivalent to the one-step estimator.

To show this, given the optimization range

$$A_{r} = \{a : \|a - a^*\|_2 < \frac{C}{\log n}\},$$

we have

$$\|S_d((\hat{a}^{DS}, \hat{c}^\top, \hat{V})^\top, \hat{V})\|_2 = o_p \left( \sqrt{\frac{1}{nh}} \right)$$
and

\[
S_d((\tilde{a}^{DS\top}, \tilde{c}^{\top})^{\top}, \tilde{V})
= S_d((a^{\top}, c^{*\top})^{\top}, V^*) + \left( S_d((a^{\top}, c^{*\top})^{\top}, \tilde{V}) - S_d((a^{*\top}, c^{*\top})^{\top}, \tilde{V}) \right)
= o_p\left(\frac{1}{nh}\right)
+ \left( S_d((\tilde{a}^{DS\top}, \tilde{c}^{\top})^{\top}, \tilde{V}) - S_d((a^{*\top}, c^{*\top})^{\top}, \tilde{V}) \right)
= o_p\left(\frac{1}{nh}\right)
+ \left( S_d((\tilde{a}^{DS\top}, \tilde{c}^{\top})^{\top}, \tilde{V}) - S_d((a^{*\top}, c^{*\top})^{\top}, \tilde{V}) \right)
= S_d((a^{*\top}, c^{*\top})^{\top}, V^*) + H_{aa}(f, V^*)(\tilde{a}^{DS} - a^*)
+ o(\|\tilde{a}^{DS} - a^*\|_2) + o_p\left(\sqrt{\frac{1}{nh}}\right).
\]

(29)

Therefore, we have

\[
\tilde{a}^{DS} - a^* = -H_{aa}(f, V^*)^{-1}S_d((a^{*\top}, c^{*\top})^{\top}, V^*) + o_p\left(\sqrt{\frac{1}{nh}}\right),
\]

which is asymptotic equivalent to the one-step estimator.

For the reparameterization estimator in (18), we need to assume that \( \tilde{V} \) can be decomposed as \( \tilde{V} = \tilde{V}_{11} \begin{bmatrix} I_{2k} & -\tilde{v} \end{bmatrix} \) where \( \tilde{V}_{11} \) is invertible with high probability, and \( \tilde{v} = -\tilde{V}_{11}^{-1}\tilde{V}_{12} \). Similarly we have \( V^* = V_{11}^* \begin{bmatrix} I_{2k} & -v^* \end{bmatrix} \) where \( v^* = -(V_{11}^*)^{-1}V_{12}^* \). Let

\[
\begin{align*}
s(a, c, v) & = \sum_i w_i I_{2k} \begin{bmatrix} I_{2k} & -v \end{bmatrix} \begin{bmatrix} \Gamma_i \Psi_r(y_i - \Gamma_i^{\top}(a, c)) \end{bmatrix}, \\
h_{ac}(f, v) & = \sum_i w_i f_i I_{2k} \begin{bmatrix} I_{2k} & -v \end{bmatrix} \begin{bmatrix} \Gamma_i \Gamma_i^{\top} \begin{bmatrix} 0_{2(p-k)\times 2k} & I_{2(2p-k)} \end{bmatrix}^{\top} \end{bmatrix}, \text{ and} \\
h_{aa}(f, v) & = \sum_i w_i f_i I_{2k} \begin{bmatrix} I_{2k} & -v \end{bmatrix} \begin{bmatrix} \Gamma_i \Gamma_i^{\top} \begin{bmatrix} I_{2k} & 0_{2k\times 2(p-k)} \end{bmatrix}^{\top} \end{bmatrix}.
\end{align*}
\]

We have \( \hat{a}^{RP} \) minimizing \( \mathcal{L}(a, \hat{c} + \hat{v}^{\top}(\tilde{a} - a)) \) as defined in (8). The optimization of the low-dimension
quantile regression will approximately solve the following score

\[ s(a, \hat{c} + \hat{v}^\top (\hat{a} - a), \hat{v}) \]

\[ = s(a, \hat{c}, \hat{v}) + h_{ac}(\hat{f}, \hat{v})\hat{v}^\top (\hat{a} - a) + o(\|\hat{v}^\top (\hat{a} - a)\|_2) + o_p \left( \sqrt{\frac{1}{nh}} \right) \]

in the sense that

\[ s(\hat{a}^{RP}, \hat{c} + \hat{v}^\top (\hat{a} - a), \hat{V}) = o_p \left( \sqrt{\frac{1}{nh}} \right). \]

Since

\[ h_{ac}(\hat{f}, \hat{v})\hat{v}^\top (\hat{a} - a) = o_p \left( \sqrt{\frac{1}{nh}} \right), \]

the equivalence of \( \hat{v} \) and the lasso estimator from a regression of \( \Gamma_{1:2k} \) on \( \Gamma_{(2k+1):2p} \) implies that a similar expansion as decorrelated score (13) holds. Therefore, we have

\[ s(\hat{a}^{RP}, \hat{c}, \hat{v}) \]

\[ = s(a^*, c^*, v^*) + h_{aa}(f, v^*)(\hat{a}^{RP} - a^*) + o(\|\hat{a}^{RP} - a^*\|_2) + o_p \left( \sqrt{\frac{1}{nh}} \right) \]

and \( \hat{a}^{RP} - a^* \) is asymptotically equivalent to \( [h_{aa}(f, v^*)]^{-1}s(a^*, c^*, v^*) \), which converges to a normal distribution.

A.4 Lemmas for the normality results

**Lemma 1.** Suppose that Assumptions 1-6 and the conditions (22)-(26) hold. Then

\[ \|\hat{a} - a^* - \left\{ S_d((\hat{a}^\top, \hat{c}^\top)^\top, V^*) - S_d((a^*\top, c^*\top)^\top, V^*) \right\} \|_2 = o_p \left( \sqrt{\frac{1}{nh}} \right). \]
Proof. From the definition of $S_d(b, V)$ in (13), we can rewrite the objective as

\[
\hat{a} - a^* - \left\{ S_d((\hat{a}^T, \hat{c}^T)^T, V^*) - S_d((a^*^T, c^*^T)^T, V^*) \right\} \\
= \hat{a} - a^* + \sum_i w_i V^* \Gamma_i \Psi_i (y_i - \Gamma_i^T (a^*^T, c^*^T)^T) \\
- \sum_i w_i V^* \Gamma_i \Psi_i (y_i - \Gamma_i^T (a^*^T, c^*^T)^T) \\
= \hat{a} - a^* + \sum_i w_i V^* \Gamma_i \left[ \mathbb{1} \left\{ y_i \leq \Gamma_i b^* \right\} - \mathbb{1} \left\{ y_i \leq \Gamma_i \hat{b} \right\} \right] \\
= \hat{a} - a^* + \sum_i w_i V^* \Gamma_i \left[ F_i (y_i \leq \Gamma_i b^*) - F_i (y_i \leq \Gamma_i \hat{b}) \right] \\
\underbrace{+ \sum_i w_i V^* \Gamma_i \left[ \mathbb{1} \left\{ y_i \leq \Gamma_i b^* \right\} - F_i (y_i \leq \Gamma_i \hat{b}) \right] - \left( \mathbb{1} \left\{ y_i \leq \Gamma_i \hat{b} \right\} - F_i (y_i \leq \Gamma_i \hat{b}) \right]}_{II}. \\
\]

For the term $I$, we use Taylor expansion and have

\[
I = \hat{a} - a^* + \sum_i w_i V^* \Gamma_i \left( F_i (y_i \leq \Gamma_i b^*) - F_i (y_i \leq \Gamma_i \hat{b}) \right) \\
= \hat{a} - a^* + \sum_i w_i V^* \Gamma_i \left( f_i (\Gamma_i b^*) \Gamma_i (b^* - \hat{b}) + \frac{f_i'}{2} (\Gamma_i \hat{b}_i) (b^* - \hat{b})^\top \Gamma_i^T \Gamma_i (b^* - \hat{b}) \right) \\
= \hat{a} - a^* + V^* H^* (b^* - \hat{b}) + R_1 \\
= \hat{a} - a^* + E_a (b^* - \hat{b}) + (V^* H^* - E_a) (b^* - \hat{b}) + R_1 \\
= (V^* H^* - E_a) (b^* - \hat{b}) + R_1, \\
\]

where $\tilde{b}_i = t_i b^* + (1 - t_i) \hat{b}$ and

\[
R_1 = \sum_i w_i V^* \Gamma_i \frac{f_i'}{2} (\Gamma_i \tilde{b}_i) (b^* - \hat{b})^\top \Gamma_i^T \Gamma_i (b^* - \hat{b}).
\]

By (22),

\[
\|R_1\|_2 \leq 2k B_V \sum_i w_i |\Gamma_i (b^* - \hat{b})|^2 = O_p \left( \frac{s B_V \log(n)}{n^h} \right).
\]
We also have

$$\| (V^* H^* - E_a)(b^* - \hat{b}) \|_2 \leq \| (V^* H^* - E_a) \|_{\infty, F} \| b^* - \hat{b} \|_{1, 2} = O_p \left( \lambda^* \cdot s \sqrt{\frac{\log(np)}{nh}} \right),$$

where the norm $\| \cdot \|_{\infty, F}$ is defined as

$$\| V \|_{\infty, F} = \sup_{i \in [k], j \in [p]} \| V(i,i+k), (j,j+p) \|_F$$

and the second inequality is because of Assumption 5 and (22). Furthermore, since $\lambda^* = O \left( B_V \sqrt{\frac{\log p}{nh f}} \right)$ by Assumption 5, we have

$$\| I \|_2 = O_p \left( \lambda^* \cdot s \sqrt{\frac{\log(np)}{nh}} \right) = O_p \left( \frac{B_V s \log(np)}{nh \sqrt{h_f}} \right) = o_p \left( \sqrt{\frac{1}{nh}} \right).$$

For the term $II$, by Lemma 5 (presented later in Section A.4) we have

$$\| II \|_2 = O_p \left( B_K B_V \sqrt{f B_X m r_b \log p \frac{1}{nh}} \right).$$

Plugging the rate for $r_b$ from condition (23), $\| II \|_2 = o_p \left( \sqrt{\frac{1}{nh}} \right)$, which completes the proof.

Lemma 2. Suppose Assumptions 1-7 and conditions (22) - (26) hold. Then

$$\| S_d((\hat{a}^T, \hat{c}^T)^T, \hat{V}) - S_d((\hat{a}^T, \hat{c}^T)^T, V^*) \|_2 = O_p \left( \frac{s B_V \log(np)}{nh \sqrt{h_f}} \right) = o_p \left( \sqrt{\frac{1}{nh}} \right).$$
Proof. Using the Hölder’s inequality, we have

\[
\|S_d((\hat{a}^T, \hat{c}^T)^T, \hat{V}) - S_d((\hat{a}^T, \hat{c}^T)^T, V^*)\|_2 \\
\leq \|\hat{V} - V^*\|_{1,F} \|\sum_i w_i \Gamma_i \Psi_{\tau}(y_i - \Gamma_i^T (\hat{a}^T, \hat{c}^T)^T)\|_{\infty,2} \\
= \|\hat{V} - V^*\|_{1,F} \|\sum_i w_i \Gamma_i \Psi_{\tau}(y_i - \Gamma_i^T \hat{b})\|_{\infty,2} \\
\leq \|\hat{V} - V^*\|_{1,F} \left[ \|\sum_i w_i \Gamma_i \Psi_{\tau}(y_i - q_i)\|_{\infty,2} \\
+ \|\sum_i w_i \Gamma_i [\Psi_{\tau}(y_i - \Gamma_i^T \hat{b}) - \Psi_{\tau}(y_i - q_i)]\|_{\infty,2} \right].
\]

Note that

\[
\|\hat{V} - V^*\|_{1,F} = O_p \left( s B V \sqrt{\frac{\log(np)}{n h h_f}} \right)
\]
by (26) and

\[
\|\sum_i w_i \Gamma_i \Psi_{\tau}(y_i - q_i)\|_{\infty,2} = O_p \left( \sqrt{\frac{\log(p)}{n h}} \right)
\]
by (44) and (45) in Lemma 8 (presented later in section A.5). Furthermore,

\[
\|\sum_i w_i \Gamma_i [\Psi_{\tau}(y_i - \Gamma_i^T \hat{b}) - \Psi_{\tau}(y_i - q_i)]\|_{\infty,2} \\
\leq \|\sum_i w_i \Gamma_i [\Psi_{\tau}(y_i - \Gamma_i^T \hat{b}) - \Psi_{\tau}(y_i - \Gamma_i^T b^*)]\|_{\infty,2} \\
+ \|\sum_i w_i \Gamma_i [\Psi_{\tau}(y_i - \Gamma_i^T b^*) - \Psi_{\tau}(y_i - q_i)]\|_{\infty,2}.
\]
The first term in the last inequality can be bounded as

\[
\| \sum_i w_i \Gamma_i [\Psi_\tau(y_i - \Gamma_i^T \hat{b}) - \Psi_\tau(y_i - \Gamma_i^T b^*)] \|_{\infty, 2}
\]

\[
= \| \sum_i w_i \Gamma_i \left( \mathbb{1} \{ y_i \leq \Gamma_i b^* \} - \mathbb{1} \{ y_i \leq \Gamma_i \hat{b} \} \right) \|_{\infty, 2}
\]

\[
\leq \| \sum_i w_i \Gamma_i \left( F_i(y_i - \Gamma_i b^*) - F_i(y_i - \Gamma_i \hat{b}) \right) \|_{\infty, 2}
\]

\[
+ \| \sum_i w_i \Gamma_i \left( \mathbb{1} \{ y_i \leq \Gamma_i b^* \} - F_i(y_i - \Gamma_i b^*) \right) - \left( \mathbb{1} \{ y_i \leq \Gamma_i \hat{b} \} - F_i(y_i - \Gamma_i \hat{b}) \right) \|_{\infty, 2}
\]

\[
= O_p\left( \frac{s \log(np)}{nh \sqrt{h_f}} \right) + O_p\left( B_K B_V \sqrt{ \hat{f} B_X m r \log(np) \over nh } \right),
\]

where the first part of the last equation is the same as the proof in Lemma 1 and the second part comes from Lemma 5 (presented later in Section A.4), where \( r_b \leq O_p\left( s \sqrt{\log(np) \over nh} \right) \) because of (23) and \( B_V \asymp O(\log(p)) \).

For the second term, applying Lemma 3 (presented next) with a union bound, we have

\[
\| \sum_i w_i \Gamma_i [\Psi_\tau(y_i - \Gamma_i^T b^*) - \Psi_\tau(y_i - q_i)] \|_{\infty, 2} = o_p\left( \sqrt{\log(np) \over nh} \right).
\]

Combining the two bounds, we have

\[
\| S_d(\hat{a}^T, \hat{c}^T, \hat{V}) - S_d(\check{a}^T, \check{c}^T, V^*) \|_F
\]

\[
= O_p\left( s B_V \sqrt{ \log(np) \over nh h_f } \right).
\]

\[
\left\{ O_p\left( \frac{s \log(np)}{nh \sqrt{h_f}} \right) + O_p\left( \sqrt{ s(\log(np))^{7/2} \over (nh)^{3/2} } \right) + o_p\left( \frac{ \log(np) \over nh } \right) \right\}
\]

\[
= o_p\left( \frac{1}{nh} \right).
\]

The last equality is because of Assumption 7. This completes the proof.

Lemma 3. Under Assumptions 1, 2, 4, and 6 for any \( V \in C(S_2) \subset \mathbb{R}^{2k \times 2p} \) such that \( \max_{i \in [n]} \| V \Gamma_i \|_2 = \)
$O(\log p) \leq B_V$ and $h \leq O(n^{-1/3})$ as assumed in Assumption 7 we have

$$\left\| \sum_i w_i V \Gamma_i [\Psi_\tau(y_i - q_i) - \Psi_\tau(y_i - \tilde{q}_i)] \right\|_2 = O_p \left( \sqrt{B_V B_K \frac{\bar{f}}{nh} \cdot (h^2 + \epsilon_R)} + \frac{\bar{f} \kappa_+ \|V\|_F}{nh} \cdot (h^2 + \epsilon_R) \right).$$

**Proof.** We have

$$\|S_n [w_i V \Gamma_i [\Psi_\tau(y_i - q_i) - \Psi_\tau(y_i - \tilde{q}_i)]]\|_2 = \|S_n [w_i V \Gamma_i [\mathbb{1} \{y_i \leq \tilde{q}_i\} - \mathbb{1} \{y_i \leq q_i\}]]\|_2 \leq \left\| (S_n - ES_n) [w_i V \Gamma_i [\mathbb{1} \{y_i \leq \tilde{q}_i\} - \mathbb{1} \{y_i \leq q_i\}]] \right\|_2 + \|S_n [w_i V \Gamma_i [F_i(\tilde{q}_i) - F_i(q_i)]]\|_2.$$

By Lemma 6 (presented later in this section),

$$I = O_p \left( B_V B_K \sqrt{\frac{\bar{f}}{nh} \cdot (h^2 + \epsilon_R)} \right).$$

For the term $II$, using the mean value theorem and the Cauchy–Schwarz inequality, we have

$$II \leq \bar{f} \sqrt{\sum_i w_i \text{trace}(\Gamma_i V^\top V^\top)} \cdot \sqrt{\sum_i w_i (\tilde{q}_i - q_i)^2} = O_p \left( \bar{f} \kappa_+ \|V\|_F \cdot (h^2 + \epsilon_R) \right),$$

where the last equality is because of Lemma 12 and Assumption 6. The proof follows from the rate of $h$ given in Assumption 7.
Lemma 4. Let
\[
\tilde{\Sigma}_{a1} := nh \sum_i w_i^2 \hat{V}_i \Psi_\tau(y_i - \Gamma_i^T \hat{b}) \Psi_\tau(y_i - \Gamma_i^T \hat{b})^T \Gamma_i^T \hat{V}^T, \tag{30}
\]
\[
\tilde{\Sigma}_{a2} := \tau(1 - \tau)\nu_2 \tilde{V} \left\{ \sum_j w_j \Gamma_j \right\} \hat{V}^T, \tag{31}
\]
and
\[
\Sigma = \tau(1 - \tau)\nu_2 \lim_{n \to \infty} \mathbb{E} \left[ V^* \Gamma \Gamma^T V^* \bigg| U = u \right].
\]

Then \( \tilde{\Sigma}_{ai} \rightarrow^p \Sigma \) for \( i = 1, 2 \).

Proof. From the consistency of \( \hat{V} \) and \( \hat{b} \), we have \( \| \hat{V} - V^* \|_F = o_p(1) \) and
\[
\max_i | \Psi_\tau(y_i - \Gamma_i^T \hat{b}) - \Psi_\tau(y_i - q_i) | = o_p(1).
\]

Therefore,
\[
\tilde{\Sigma}_{a1} = nh \sum_i w_i^2 \hat{V}_i \Psi_\tau(y_i - \Gamma_i^T \hat{b}) \Psi_\tau(y_i - \Gamma_i^T \hat{b})^T \Gamma_i^T \hat{V}^T
\]
\[
= \left( nh \right)^{-1} \sum_i K^2 \left( \frac{U_i - u}{h} \right) V^* \Gamma_i \Psi_\tau(y_i - \Gamma_i^T \hat{b}) \Psi_\tau(y_i - \Gamma_i^T \hat{b})^T \Gamma_i^T V^* + o_p(1)
\]
\[
= \mathbb{E} \left[ \left( nh \right)^{-1} \sum_i K^2 \left( \frac{U_i - u}{h} \right) V^* \Gamma_i \Psi_\tau(y_i - q_i) \Psi_\tau(y_i - q_i)^T \Gamma_i^T V^* \right] + o_p(1)
\]
\[
= \Sigma + o_p(1),
\]
which shows (30).

From the condition (55), we have \( \| \hat{V} - V^* \|_F = o_p(1) \). By the strong law of large numbers,
\[
\left\| \sum_j w_j \Gamma_j \Gamma_j^T V^* \Psi_\tau(y_i - q_i) \Psi_\tau(y_i - q_i)^T \Gamma_i^T V^* \right\|_F
\]
\[
= o_p(1).
\]
Then by the continuous mapping theorem, we have \( \| \hat{\Sigma}_a - \Sigma \|_F = o_p(1) \). This shows (31). The proof is complete now.

\[ \]

**Lemma 5.** Suppose Assumptions \( \ref{assumption-1} \) \( \ref{assumption-2} \) \( \ref{assumption-3} \) and \( \ref{assumption-6} \) hold. For any \( V \in \mathbb{C}(S_2) \subset \mathbb{R}^{2k \times 2p} \) that satisfies
\[
\max_{i \in [n]} \| V \Gamma_i \|_2 = B_V = O(\log p) \text{ and } r_b \asymp \sqrt{\log(np)/nh},
\]
we have
\[
\sup_{\| \delta \|_{0,2} \leq m} \left\| (S_n - ES_n) \left[ w_i V \Gamma_i (1 \{ y_i \leq \Gamma_i^T b^* \} - 1 \{ y_i \leq \Gamma_i^T (b^* + \delta) \}) \right] \right\|_2 = O_p \left( B_K B_V \sqrt{f B X r_b \log(np)/nh} \right).
\]

**Proof.** Let \( \mathcal{W} = \{ \tilde{W}_1, \ldots, \tilde{W}_K \} \) be the \( \frac{1}{2} \)-net for \( \{ W \in \mathbb{R}^{2k} \mid \| W \|_2 \leq 1 \} \). That is, for all \( W \in \mathbb{R}^{2k} \) with \( \| W \|_2 \leq 1 \), there exists \( \tilde{W} \in \mathcal{W} \subseteq \{ W \in \mathbb{R}^{2k} \mid \| W \|_2 \leq 1 \} \) such that \( \| \tilde{W} - W \|_2 \leq \frac{1}{2} \). We have that \( K \leq 5^{2k} \). Then
\[
\sup_{\| \delta \|_{0,2} \leq m} \left\| (S_n - ES_n) \left[ w_i V \Gamma_i (1 \{ y_i \leq \Gamma_i^T b^* \} - 1 \{ y_i \leq \Gamma_i^T (b^* + \delta) \}) \right] \right\|_2 \leq 2 \cdot \max_{\tilde{W} \in \mathcal{W}} \sup_{\| \delta \|_{0,2} \leq m} \sup_{\| \delta \|_{1,2} \leq r_b} \left( S_n - ES_n \left[ w_i \cdot \left( 1 \{ y_i \leq \Gamma_i^T b^* \} - 1 \{ y_i \leq \Gamma_i^T (b^* + \delta) \} \right) \right] \cdot |\tilde{W}^T V \Gamma_i| \right).
\]

For the expectation, we have
\[
E \left[ 1 \{ y_i \leq \Gamma_i^T b^* \} - 1 \{ y_i \leq \Gamma_i^T (b^* + \delta) \} \right] \leq E \left[ -|\Gamma_i^T \delta| \leq y_i - \Gamma_i^T b^* \leq |\Gamma_i^T \delta| \right] = F_i \left( \Gamma_i^T b^* + |\Gamma_i^T \delta| \right) - F_i \left( \Gamma_i^T b^* - |\Gamma_i^T \delta| \right) \leq 2f \cdot |\Gamma_i^T \delta| \leq 2f B X r_b.
\]
For a fixed \( \tilde{W} \in \mathcal{W} \) and \(|S| \leq m\), define

\[ a_i = w_i \cdot |\tilde{W}^\top V \Gamma_i|, \]
and

\[ G_S = \left\{ (y_i, x_i, u_i) \mapsto a_i \cdot 1 \left\{ -|\Gamma_i^\top \delta| \leq y_i - \Gamma_i^\top \delta^* \leq |\Gamma_i^\top \delta| \right\} : \text{support} (\delta) = S, \|\delta\|_2 \leq r_b \right\} , \]

\[ \mathcal{G} = \bigcup_{|S| \leq m} G_S \]

Let \( G(\cdot) = (nh)^{-1}B_K (\tilde{W}^\top V \Gamma_i) \) be an envelope of \( \mathcal{G} \). Then \( \|G\|_{\infty} \leq \frac{B_K B_V}{nh} \). For a fixed \( g \in \mathcal{G} \), let

\[ g_i = g(y_i, x_i, u_i) = a_i \cdot 1 \left\{ -|\Gamma_i^\top \delta| \leq y_i - \Gamma_i^\top \delta^* \leq |\Gamma_i^\top \delta| \right\} . \]

Therefore, the variance is bounded as

\[ \sigma^2_G \leq \sup_{g \in \mathcal{G}} \sum_{i \in [n]} \mathbb{E} [g_i^2] \leq \bar{f} B_X \bar{r}_b \sum_{i \in [n]} a_i^2 \lesssim \frac{\bar{f} B_X B^2_K \bar{B}_V}{nh} \cdot r_b , \]

since

\[ \sum_{i \in [n]} a_i^2 \leq B^2_V \sum_{i \in [n]} w_i^2 \leq \frac{B^2_K B^2_V}{nh} . \]

The VC dimension for the space

\[ \mathcal{F}_S = \left\{ (y_i, x_i, u_i) \mapsto 1 \left\{ -|\Gamma_i^\top \delta| \leq y_i - \Gamma_i^\top \delta^* \leq |\Gamma_i^\top \delta| \right\} : \text{support} (\delta) = S, \|\delta\|_2 \leq r_b \right\} \]

is \( O(m) \). Therefore, applying Lemma 22 (presented later in Section A.8),

\[ \sup_Q N \left( \epsilon \cdot \frac{B_K B_V}{nh}, G_S, \|\cdot\|_{L_2(Q)} \right) \leq \left( \frac{C}{\epsilon} \right)^{cm} , \]

and

\[ \sup_Q N \left( \epsilon \cdot \frac{B_K B_V}{nh}, G, \|\cdot\|_{L_2(Q)} \right) \leq \left( \frac{C}{\epsilon} \right)^{cm} \cdot p^m . \]

Applying Lemma 21 (presented later in Section A.7) with \( \sigma_G = B_K B_V \sqrt{\frac{\bar{f} B_X \bar{r}_b}{nh}} \), \( \|G\|_{\infty} \leq \frac{B_K B_V}{nh} \), \( V = \)
\( cm, U = \frac{BKBV}{nh}, \) and \( A = Cm^{1/cm}p^{1/c} \) then gives us

\[
E \left[ \sup_{g \in G} \sum_{i \in [n]} g_i - E[g_i] \right] \\
\leq \left( cm - \frac{BKBV}{nh} \log \left( \frac{Cp^{1/c}}{\sqrt{fB_Xr_b}} \right) \right) + BKBV \sqrt{\frac{fB_Xr_b}{nh}} \sqrt{cm \log \left( \frac{Cp^{1/c}}{\sqrt{fB_Xr_b}} \right)} \\
= O \left( BKBV \sqrt{fB_X \frac{mr_b \log(p \vee n)}{nh}} \right),
\]

under the conditions of the lemma and the growth condition in Assumption 7. Lemma 25 then gives us

\[
\sup_{g \in G} \sum_{i \in [n]} g_i - E[g_i] = O_p \left( BKBV \sqrt{fB_X \frac{mr_b \log(p \vee n)}{nh}} \right).
\]

A union bound over \( \tilde{W} \in \mathcal{W} \) concludes the proof.

**Lemma 6.** Suppose Assumptions 1, 2, 3, 4, 6 and 7 hold. For all \( V \in C(S_2) \subset \mathbb{R}^{2k \times 2p} \) with \( B_V = \max_{i \in [n]} ||V\Gamma_i||_2 \), we have

\[
||\left( S_n - E S_n \right) [w_i V \Gamma_i (1 \{ y_i \leq \tilde{q}_i \} - 1 \{ y_i \leq q_i \})] ||_2 \\
= O_P \left( BKBV \sqrt{\frac{f}{nh} \cdot (h^2 + \epsilon_R)} \right).
\]

**Proof.** Let \( \mathcal{W} = \{ \tilde{W}_1, \ldots, \tilde{W}_K \} \) be the \( \frac{1}{2} \)-net for \( \{ W \in \mathbb{R}^{2k} | ||W||_2 \leq 1 \} \). We have that \( K \leq 5^{2k} \) and

\[
||\left( S_n - E S_n \right) [w_i V \Gamma_i (1 \{ y_i \leq \tilde{q}_i \} - 1 \{ y_i \leq q_i \})] ||_2 \\
\leq 2 \cdot \max_{\tilde{W} \in \mathcal{W}} (S_n - E S_n) \left[ w_i \cdot (1 \{ y_i \leq \tilde{q}_i \} - 1 \{ y_i \leq q_i \}) \cdot [\tilde{W}^T V \Gamma_i] \right].
\]

Let

\[
a_i = w_i \cdot |\tilde{W}^T V \Gamma_i|, \text{ and } \\
g_i = g(y_i, x_i, u_i) = a_i \cdot (1 \{ y_i \leq \tilde{q}_i \} - 1 \{ y_i \leq q_i \}).
\]
Since

\[ \mathbb{E} \left[ \mathbb{1} \{ y_i \leq \tilde{q}_i \} - \mathbb{1} \{ y_i \leq q_i \} \right] \leq 2 \tilde{f} \cdot |q_i - \tilde{q}_i|, \]

we have

\[
\sum_{i \in [n]} \mathbb{E} [g_i^2] \lesssim \sum_i 2 \tilde{f} \cdot |q_i - \tilde{q}_i| a_i^2 = \sum_i 2 \tilde{f} \cdot |q_i - \tilde{q}_i| w_i^2 \left( \bar{W}^T V \Gamma \right)^2 \leq \frac{\bar{f} B^2_k B^2_V}{nh} \sqrt{\mathbb{E}_n \left[ w_i (q_i - \tilde{q}_i)^2 \right]}. \]

Then by Lemma 12 and Assumption 6 we have

\[
\sum_{i \in [n]} \mathbb{E} [g_i^2] = O_p \left( \frac{\bar{f} B^2_k B^2_V}{nh} \cdot (h^2 + \epsilon_R) \right).
\]

The result follows from the Bernstein’s inequality and the union bound over \( \mathcal{W} \).

**A.5 Consistency of the initial estimator \( \hat{b}^{\text{ini}} \)**

We show the convergence guarantee of the initial estimator \( \hat{b}^{\text{ini}} \) defined in Section 3 Step 1. Notice that in the following two sections, we slightly abuse the notation by denoting \( \hat{b}^{\text{ini}} \) from Section 3 as \( \hat{b} \), and \( \hat{b} \) from Section 3 is defined as \( \hat{b}^{\lambda} \), since it is obtained by thresholding at the level \( \lambda \).

Let

\[
W_i(\delta) = \rho_r (y_i - (q_i + \delta)) - \rho_r (y_i - q_i),
\]

which can be decomposed as

\[
W_i(\delta) = -\delta \Psi_r (y_i - q_i) + \int_0^\delta \left[ \mathbb{1} \{ y_i \leq q_i + z \} - \mathbb{1} \{ y_i \leq q_i \} \right] dz =: W_i^\#(\delta) + W_i^\circ(\delta),
\]

using the Knight’s identity. Note that we can also write

\[
W_i^\circ(\delta) = (y_i - (q_i + \delta)) \left[ \mathbb{1} \{ q_i + \delta \leq y_i < q_i \} - \mathbb{1} \{ q_i \leq y_i < q_i + \delta \} \right].
\]
With this notation, we study properties of the following penalized quantile regression estimator

$$\hat{b} = \arg \min_b \sum_{i \in [n]} w_i \cdot \rho_\tau(y_i - \Gamma_i^\top b) + \lambda \|b\|_{1,2},$$  \hspace{1cm} (35)$$

where the groups are formed by pairs \((b_{0j}, b_{1j})\) for \(j \in [p]\) and \(w_i = (nh)^{-1} K\left(\frac{U_i - u}{h}\right)\). The estimated quantile function is denoted as \(\hat{q}_i = \Gamma_i^\top \hat{b}\).

**Theorem 4.** Under Assumptions 1, 3, 4 and 6, we have

$$S_n \left[ w_i \cdot \left( \Gamma_i^\top \left( \hat{b} - b^* \right) \right)^2 \right] = O_p \left( \frac{s \log(np)}{nh} \right)$$

and

$$\|\hat{b} - b^*\|_{1,2} = O_p \left( s \sqrt{\frac{\log(np)}{jh}} \right).$$

**Proof.** Denote \(S' = \text{support}\{b^*\}\). Let \(r_b\) be a rate satisfying \(r_b = O_p \left( \sqrt{\frac{s \log(np)}{nh}} \right)\). Recall that

$$\kappa_q = \inf_{\|\delta\|_{1,2} \leq \sqrt{s \log(p)}} \frac{\left( f \cdot S_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right] \right)^{3/2}}{f' \cdot S_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^3 \right]},$$

As \(n\) grows, we have

$$\kappa_q \geq r_b \sqrt{\frac{f}{s}}. \hspace{1cm} (36)$$

In order to establish that \(S_n \left[ w_i \cdot \left( \Gamma_i^\top \left( \hat{b} - b^* \right) \right)^2 \right] \leq r_b^2\), we use the proof by contradiction.

Suppose that \(S_n \left[ w_i \cdot \left( \Gamma_i^\top \left( \hat{b} - b^* \right) \right)^2 \right] > r_b^2\). Since the objective function is convex, there exists a vector

$$\tilde{b} = b^* + \frac{r_b}{\sqrt{S_n \left[ w_i \cdot \left( \Gamma_i^\top \left( \hat{b} - b^* \right) \right)^2 \right]}}.$$
such that \( \mathbb{S}_n \left[ w_i \cdot (\Gamma_i^\top (\hat{b} - b^*))^2 \right] = r_b^2 \) and

\[
\mathbb{S}_n \left[ w_i \cdot (\rho_r(y_i - \hat{q}_i) - \rho_r(y_i - \hat{q}_i)) \right] \leq \lambda \left( \|\hat{b}\|_{1,2} - \|b^*\|_{1,2} \right),
\]

is satisfied. We separate our analysis into two parts, according to whether \( 3\|\hat{b} - b^*\|_{S'} \|_{1,2} \geq \frac{2}{\lambda} \mathbb{S}_n \left[ w_i \cdot W_i^2(\hat{q}_i - q_i) \right] \) in (39) or not.

First, suppose that \( 3\|\hat{b} - b^*\|_{S'} \|_{1,2} \geq \frac{2}{\lambda} \mathbb{S}_n \left[ w_i \cdot W_i^2(\hat{q}_i - q_i) \right] \). By Lemma 7 (presented next), \( \|\hat{b} - b^*\|_{N'} \|_{1,2} \leq 6\|\hat{b} - b^*\|_{S'} \|_{1,2} \) and

\[
\|\hat{b} - b^*\|_{1,2} \leq 7\|\hat{b} - b^*\|_{S'} \|_{1,2} \leq 7\sqrt{|S'|\|\hat{b} - b^*\|_{S'}} \leq \frac{7\sqrt{|S'| \cdot r_b}}{\kappa_\perp} = O_p \left( s \sqrt{\frac{\log(np)}{nh}} \right). \tag{37}
\]

Starting from (40), we have that

\[
\lambda \|\hat{b} - b^*\|_{1,2} \geq \mathbb{E}\mathbb{S}_n \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top \hat{b} - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right]
\]

\[
+ \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top \hat{b} - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right].
\]

Lemma 10 (presented later in this section) gives us

\[
\mathbb{E}\mathbb{S}_n \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top \hat{b} - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right] \geq \frac{fr_b^2 \wedge \kappa_q \sqrt{fr_b}}{3} \geq \frac{fr_b^2}{3},
\]

where the second inequality follows under (36). On the event \( \mathcal{E}_{QR}(\lambda) \), we have

\[
\left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot \left( W_i^\# \left( \Gamma_i^\top \hat{b} - q_i \right) - W_i^\# \left( \Gamma_i^\top b^* - q_i \right) \right) \right] \geq -\frac{\lambda}{2} \|\hat{b} - b^*\|_{1,2}.
\]

Lemma 9 (presented later in this section) gives us

\[
\sup_{\|\delta\|_{1,2} \leq \frac{t \sqrt{\log(np)}}{n} \sqrt{r_b}} \left| \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot \left( W_i^\# \left( \Gamma_i^\top \hat{b} - q_i \right) - W_i^\# \left( \Gamma_i^\top b^* - q_i \right) \right) \right] \right| = o_p(r_b).
\]
Putting everything together, we obtain that
\[ 0 \geq \frac{f r_b}{3} - \frac{7\lambda \sqrt{|S'|}}{2\kappa_-} - o_p(r_b) > 0, \]
which is a contradiction.

The second part of the upper bound is established in the case when
\[ 3\|(\hat{b} - b^*)_{S'}\|_{1,2} < (2/\lambda)S_n \left[ w_i \cdot W_i^2(\tilde{q}_i - q_i) \right]. \]

Then we have that
\[ \|(\hat{b} - b^*)_{N'}\|_{1,2} \leq \frac{4}{\lambda} S_n \left[ w_i \cdot W_i^2(\tilde{q}_i - q_i) \right], \]
and
\[ \|\hat{b} - b^*\|_{1,2} \leq \frac{6}{\lambda} S_n \left[ w_i \cdot W_i^2(\tilde{q}_i - q_i) \right] = O_p \left( s \sqrt{\log(np) / nh} \right) , \]
where the last equation is because of Lemmas 8 and 11. The same argument as above gives us a contradiction, which completes the proof.

\[ \square \]

**Lemma 7.** On the event
\[ \mathcal{E}_{QR}(\lambda) = \left\{ \max_{j \in [p]} \sup_{v \in \mathbb{R}^2, \|v\|_2 = 1} \sum_i w_i \cdot (x_{ij}v_0 + x_{ij}(u_i - u)v_1) \cdot \Psi_\tau (y_i - q_i) \leq \frac{\lambda}{2} \right\} \]  

we have
\[ \|(\hat{b} - b^*)_{N'}\|_{1,2} \leq 3\|(\hat{b} - b^*)_{S'}\|_{1,2} + \frac{2}{\lambda} S_n \left[ w_i \cdot W_i^2(\tilde{q}_i - q_i) \right], \]
where \( N' = S'^c. \)

**Proof.** Our starting point is the observation that
\[ S_n \left[ w_i \cdot (\rho_\tau(y_i - \tilde{q}_i) - \rho_\tau(y_i - \hat{q}_i)) \right] \leq \lambda \left( \|b^*\|_{1,2} - \|\hat{b}\|_{1,2} \right), \]  

(40)
since \( \hat{b} \) minimizes (35). Due to convexity of \( \rho (\cdot) \), we have

\[
\mathbb{S}_n \left[ w_i \cdot (\rho (y_i - \hat{q}_i) - \rho (y_i - q_i)) \right] \geq \mathbb{S}_n \left[ w_i \cdot (q_i - \hat{q}_i) \cdot \Psi (y_i - q_i) \right].
\]

(41)

Using (33), we have

\[
\mathbb{S}_n \left[ w_i \cdot (\rho (y_i - \hat{q}_i) - \rho (y_i - q_i)) \right] = \mathbb{S}_n \left[ w_i \cdot (q_i - \hat{q}_i) \cdot \Psi (y_i - q_i) \right] + \mathbb{S}_n \left[ w_i \cdot W^2_i (\hat{q}_i - q_i) \right].
\]

(42)

Combining (41) and (42) with (40), we have

\[
\mathbb{S}_n \left[ w_i \cdot (\hat{q}_i - q_i) \cdot \Psi (y_i - q_i) \right] - \mathbb{S}_n \left[ w_i \cdot W^2_i (\hat{q}_i - q_i) \right] \leq \lambda \left( \|b^*\|_{1,2} - \|\hat{b}\|_{1,2} \right).
\]

(43)

On the event \( \mathcal{E}_{QR}(\lambda) \),

\[
\mathbb{S}_n \left[ w_i \cdot (\hat{q}_i - q_i) \cdot \Psi (y_i - q_i) \right] \geq -\frac{\lambda}{2} \|b^* - \hat{b}\|_{1,2}.
\]

Combining with the display above, we obtain that

\[
-\frac{\lambda}{2} \|b^* - \hat{b}\|_{1,2} \leq \mathbb{S}_n \left[ w_i \cdot W^2_i (\hat{q}_i - q_i) \right] + \lambda \left( \|b^*\|_{1,2} - \|\hat{b}\|_{1,2} \right).
\]

Since

\[
\|b^*\|_{1,2} - \|\hat{b}\|_{1,2} \leq \left\| (b^* - \hat{b}) \right\|_{S'}_{1,2} - \left\| (b^* - \hat{b}) \right\|_{N'}_{1,2},
\]

we have

\[
\frac{\lambda}{2} \| (\hat{b} - b^*) \|_{N'}_{1,2} \leq \mathbb{S}_n \left[ w_i \cdot W^2_i (\hat{q}_i - q_i) \right] + \frac{3}{2} \lambda \left( \| (\hat{b} - b^*) \|_{S'}_{1,2} \right),
\]

which completes the proof.

\( \Box \)

**Lemma 8.** Under Assumption 6, for

\[
\lambda = 4 \cdot \left( \max_{j \in [p]} \mathbb{S}_n \left[ w_i^2 x_{ij}^2 \right] \right)^{1/2} \sqrt{\log(4p/\gamma)} = O \left( \sqrt{\log p \over nh} \right),
\]

(44)
we have
\[ \mathbb{P} \{ \mathcal{E}_{QR}(\lambda) \} \geq 1 - \gamma. \]

Proof. We prove that
\[
\max_{j \in [p]} | \mathbb{S}_n [ w_i \cdot x_{ij} \cdot \Psi_\tau (y_i - q_i)] | \leq \frac{\lambda}{2\sqrt{2}}
\]
and
\[
\max_{j \in [p]} | \mathbb{S}_n [ w_i \cdot x_{ij} (u_i - u) \cdot \Psi_\tau (y_i - q_i)] | \leq \frac{\lambda}{2\sqrt{2}}.
\]

Let
\[ Z_i = \frac{w_i \cdot x_{ij} \cdot \Psi_\tau (y_i - q_i)}{\sqrt{\mathbb{S}_n [ w_i^2 x_{ij}^2 ]}} \]
and note that \(|Z_i| \leq 1\) and \(\mathbb{E} [Z_i] = 0\). The Hoeffding’s inequality (Theorem 2.8 [Boucheron et al., 2013]) gives us that
\[ | \mathbb{S}_n [Z_i]| \leq \sqrt{2 \log(2/\gamma)} \]
with probability \(1 - \gamma\). An application of the union bound gives us that
\[ \max_{j \in [p]} \mathbb{S}_n [ w_i \cdot x_{ij} \cdot \Psi_\tau (y_i - q_i)] \leq \left( \max_{j \in [p]} \mathbb{S}_n [ w_i^2 x_{ij}^2 ] \right)^{1/2} \sqrt{2 \log(4p/\gamma)} \]
with probability \(1 - \gamma/2\). This proves (45). Equation (46) is shown in the same way by noting that
\[ \mathbb{S}_n [ w_i^2 x_{ij}^2 (u_i - u)^2 ] \leq \mathbb{S}_n [ w_i^2 x_{ij}^2 ] . \]

Lemma 9. Let \( \tilde{b} = b^* + \delta \),
\[
g_i(\delta) = w_i \cdot \left( W_{\tilde{b}}^2 \left( \Gamma_i^\top \tilde{b} - q_i \right) - W_{b^*}^2 \left( \Gamma_i^\top b^* - q_i \right) \right)
= w_i \cdot (y_i - \Gamma_i^\top \tilde{b}) \left[ \mathbb{1} \left\{ \Gamma_i^\top \tilde{b} \leq y_i < q_i \right\} - \mathbb{1} \left\{ q_i < y_i < \Gamma_i^\top b^* \right\} \right]
- w_i \cdot (y_i - \Gamma_i^\top b^*) \left[ \mathbb{1} \left\{ \Gamma_i^\top b^* \leq y_i < q_i \right\} - \mathbb{1} \left\{ q_i < y_i < \Gamma_i^\top b^* \right\} \right].
\]
Then

\[ \sup_{\|\delta\|_{1,2} \leq R_1} \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot g_i(\delta) \right] \]

\[ \leq R_1 \sqrt{\frac{B_X^2 B_K^2}{nhn^2}} \log(p) + R_1 \left( B_w B_X \sqrt{\frac{B_X^2 B_K^2}{n^2}} \log(p) + B_w \frac{R_2}{R_1} \right) \log(1/\gamma) \]

\[ + R_1 B_w B_X \log(1/\gamma) \]

with probability \(1 - \gamma\).

**Proof.** We will apply Lemma 25. Note that

\[ |g_i(\delta)| \leq w_i (y_i - \Gamma_i^T b) \cdot \left[ 1 \left\{ \Gamma_i^T b \leq y_i < q_i \right\} - 1 \left\{ q_i < y_i < \Gamma_i^T b \right\} \right] - 1 \left\{ \Gamma_i^T b^* \leq y_i < q_i \right\} + 1 \left\{ q_i < y_i < \Gamma_i^T b^* \right\} \]

\[ + w_i (\Gamma_i^T b^* - \Gamma_i^T b) \left[ 1 \left\{ \Gamma_i^T b^* \leq y_i < q_i \right\} - 1 \left\{ q_i < y_i < \Gamma_i^T b^* \right\} \right] \]

\[ \leq 2|w_i\Gamma_i^T \delta| \leq 2B_w B_X R_1. \]

Therefore, \( |g_i(\delta) - \mathbb{E}[g_i(\delta)]| \leq 4B_w B_X R_1 \). For the variance, we have

\[ \mathbb{E} \left[ \sum_i (g_i(\delta) - \mathbb{E}[g_i(\delta)])^2 \right] \leq \mathbb{E} \left[ \sum_i g_i^2(\delta) \right] \leq 4 \sum_{i \in [n]} w_i^2 \left( \Gamma_i^T \delta \right)^2 \leq 4B_w R_2. \]
Finally, we bound the supremum of the process. We have

\[
\mathbb{E} \left[ \sup_{\|\delta\|_{1,2} \leq R_1} \left\{ |\mathbb{E}S_n - \mathbb{E}S_n| [g_i(\delta)] \right\} \right] \\
\leq 2 \mathbb{E} \left[ \sup_{\|\delta\|_{1,2} \leq R_1} \left\{ \mathbb{E}S_n \left[ \epsilon_i \cdot g_i(\delta) \right] \right\} \right] \\
\leq 4 \mathbb{E} \left[ \sup_{\|\delta\|_{1,2} \leq R_1} \left\{ \mathbb{E}S_n \begin{bmatrix} x_{ij} \\ x_{ij}(U_i - u) \end{bmatrix} \right\} \right] \\
\leq 8 \|\delta\|_{1,2} \sqrt{\frac{B_2^2 B_2^2}{nh} \log(2p)},
\]

where (i) follows from symmetrization (Lemma 11.4 [Boucheron et al., 2013]), (ii) from contraction inequality (Theorem 11.6 [Boucheron et al., 2013]), and (iii) from a maximum inequality for sub-Gaussian random variables (Theorem 2.5 [Boucheron et al., 2013]). The result now follows by plugging the pieces into Lemma 25.

\[\square\]

**Lemma 10.** Suppose Assumptions 3 and 6 hold. For a fixed \(\delta\), we have

\[
\mathbb{E}S_n \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top (b^* + \delta) - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right] \\
\geq \frac{1}{3} \cdot \left( \mathbb{E}S_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right] \right)^{1/2} \cdot \kappa_q \cdot \left( f \cdot \mathbb{E}S_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right] \right) \cdot \beta.
\]

**Proof.** Using (33), we have

\[
\mathbb{E} \left[ W_i^\# \left( \Gamma_i^\top (b^* + \delta) - q_i \right) - W_i^\# \left( \Gamma_i^\top b^* - q_i \right) \right] = - \left( \Gamma_i^\top \delta \right) \cdot \mathbb{E} \left[ \psi_i(y_i - q_i) \right] = 0
\]
and
\[
E \left[ W_i^2 \left( \Gamma_i^\top (b^* + \delta) - q_i \right) - W_i^2 \left( \Gamma_i^\top b^* - q_i \right) \right] \\
= E \left[ \int_0^{\Gamma_i^\top \delta} \left[ \mathbf{1} \{ y_i \leq \Gamma_i^\top b^* + z \} - \mathbf{1} \{ y_i \leq \Gamma_i^\top b^* \} \right] dz \right] \\
= \int_0^{\Gamma_i^\top \delta} \left[ F_i (\Gamma_i^\top b^* + z) - F_i (\Gamma_i^\top b^*) \right] dz \\
= \int_0^{\Gamma_i^\top \delta} \left[ z f_i (\Gamma_i^\top b^*) + \frac{z^2}{2} f_i' (\Gamma_i^\top b^* + \tilde{z}) \right] dz \\
\geq \frac{f}{2} (\Gamma_i^\top \delta)^2 - \frac{\bar{f}'}{6} (\Gamma_i^\top \delta)^3.
\]

Combining the last two displays, we obtain
\[
\begin{align*}
E \mathbb{S}_n & \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top (b^* + \delta) - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right] \\
& \geq \frac{f}{2} \mathbb{S}_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right] - \frac{\bar{f}'}{6} \mathbb{S}_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^3 \right].
\end{align*}
\] (47)

We lower bound the above display in two cases. First, consider the case where
\[
\left( f \cdot \mathbb{S}_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right] \right)^{1/2} \leq \kappa_q.
\]

From the definition of \( \kappa_q \), we then obtain that
\[
\bar{f}' \cdot \mathbb{S}_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^3 \right] \leq f \cdot \mathbb{S}_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right],
\]
which combined with (47) gives us
\[
\begin{align*}
E \mathbb{S}_n & \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top (b^* + \delta) - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right] \\
& \geq \frac{f}{3} \mathbb{S}_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right].
\end{align*}
\] (48)

Next, we consider the case where
\[
\left( f \cdot \mathbb{S}_n \left[ w_i \cdot \left( \Gamma_i^\top \delta \right)^2 \right] \right)^{1/2} > \kappa_q.
\]
Let $\bar{b} = b^* + (1 - \alpha)\delta$ for some $\alpha \in (0, 1)$ to be determined later. Using the convexity of $\rho_\tau(\cdot)$, we have that

\[
\mathbb{E}S_n \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top (b^* + \delta) - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right]
\geq \frac{1}{1 - \alpha} \left( \mathbb{E}S_n \left[ w_i \cdot \left( W_i (\Gamma_i^\top \bar{b} - q_i) - W_i (\tilde{q}_i - q_i) \right) \right] \right)
\geq \frac{1}{1 - \alpha} \left( \frac{f \cdot S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^2 \right]}{f^2 S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^3 \right]} \right),
\]

where the second inequality follows from (47). We want to choose $\alpha$ such that

\[
f \cdot S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^2 \right] = \bar{f}^2 S_n \left[ w_i \cdot (\Gamma_i^\top (\bar{b} - b^*))^3 \right],
\]

which leads to

\[
1 - \alpha = \frac{f \cdot S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^2 \right]}{\bar{f}^2 S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^3 \right]}.
\]

Combining with (49), we have

\[
\mathbb{E}S_n \left[ w_i \cdot \left( W_i \left( \Gamma_i^\top (b^* + \delta) - q_i \right) - W_i \left( \Gamma_i^\top b^* - q_i \right) \right) \right]
\geq \frac{1}{3} \cdot \frac{\left( f \cdot S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^2 \right] \right)^2}{f^2 S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^3 \right]}
\geq \frac{\kappa_4}{3} \cdot \left( f \cdot S_n \left[ w_i \cdot (\Gamma_i^\top \delta)^2 \right] \right)^{1/2}.
\]

The proof follows by combining the lower bounds in (48) and (50).

\[\square\]

**Lemma 11.** Under our model assumptions,

\[
S_n \left[ w_i \cdot W_i^2 (\tilde{q}_i - q_i) \right]
\leq 2 \sqrt{2 \log(2/\gamma)} \cdot \left( f \cdot S_n \left[ w_i \cdot (\tilde{q}_i - q_i)^2 \right] + \sqrt{S_n \left[ w_i^2 (\tilde{q}_i - q_i)^2 \right]} \right)
\]

holds with probability $1 - \gamma$.

**Proof.** We will prove the lemma using Theorem 2.16 of de la Peña et al. (2009). Note that $W_i^2 (\tilde{q}_i - q_i)$ is
positive and

\[ \mathbb{E} \left[ W_i^2(\tilde{q}_i - q_i) \right] = \int_{\tilde{q}_i - q_i}^{\tilde{q}_i} [F_i(q_i + z) - F_i(q_i)] \, dz \]

\[ = \int_{0}^{\tilde{q}_i - q_i} f_i(\tilde{z}_i) \, d\tilde{z} \leq \frac{\bar{f}}{2} (\tilde{q}_i - q_i)^2, \]

where \( \tilde{z}_i \) is a point between 0 and \( z \). Therefore, the Markov’s inequality gives us

\[ \mathbb{P} \left\{ S_n \left[ w_i \cdot W_i^2(\tilde{q}_i - q_i) \right] \geq 2 \bar{f} \cdot S_n \left[ w_i \cdot (\tilde{q}_i - q_i)^2 \right] \right\} \leq \frac{1}{4}. \]

Furthermore, since \( |W_i^2(\tilde{q}_i - q_i)| \leq |\tilde{q}_i - q_i| \), we have that

\[ \mathbb{P} \left\{ S_n \left[ (w_i \cdot W_i^2(\tilde{q}_i - q_i))^2 \right] \geq S_n \left[ w_i^2 (\tilde{q}_i - q_i)^2 \right] \right\} = 0 \leq \frac{1}{4}. \]

Invoking Theorem 2.16 of de la Peña et al. (2009), define

\[ a = 2 \bar{f} S_n \left[ w_i \cdot (\tilde{q}_i - q_i)^2 \right], \quad b = \sqrt{S_n \left[ w_i^2 (\tilde{q}_i - q_i)^2 \right]}, \]

\[ S_n = S_n \left[ w_i \cdot W_i^2(\tilde{q}_i - q_i) \right], \quad V_n^2 = S_n \left[ (w_i \cdot W_i^2(\tilde{q}_i - q_i))^2 \right], \]

and observe that \( V_n \leq b^2 \), we obtain that

\[ \mathbb{P} \{ S_n \geq x(a + b + V_n) \} \leq 2e^{-\frac{x^2}{2}}, \]

which completes the proof. \( \square \)

**Lemma 12.** Under Assumptions 1, 2, 4 and 6 we have that

\[ \sum_i w_i (\tilde{q}_i - q_i)^2 \leq 2h^4 s B_X B_B B_K + 2 \frac{\epsilon R}{f} = O \left( h^4 + \epsilon^2 R \right) \]

and

\[ \sum_i w_i^2 (\tilde{q}_i - q_i)^2 \leq B_w \cdot \left( 2h^4 s B_X B_B B_K + 2 \frac{\epsilon R}{f} \right) = O \left( \frac{h^3}{n} + \frac{\epsilon R}{nh} \right). \]
Proof. First, the assumption on the density \( f_i \) proves that
\[
| x_i^\top \beta^*(\tau, u_i) - q_i | \leq R_i \frac{f}{f}. \]
Then
\[
\sum_i w_i (\tilde{q}_i - q_i)^2 \leq 2 \sum_i w_i (\tilde{q}_i - x_i^\top \beta^*(\tau, u_i))^2 + 2 \sum_i w_i (x_i^\top \beta^*(\tau, u_i) - q_i)^2 \\
\leq 2 \sum_i w_i [ x_i^\top (\beta^*(\tau, u_i) - \beta^*(\tau, u) - (u_i - u) \cdot \nabla_u \beta^*(\tau, u)) ]^2 + 2 \sum_i w_i R_i^2 \frac{f}{f} \\
\leq 2 \sum_i w_i \|x_i\|^2_{\infty} \| \beta^*(\tau, u_i) - \beta^*(\tau, u) - (u_i - u) \cdot \nabla_u \beta^*(\tau, u) \|^2 + 2 \frac{\epsilon R}{f} \\
\leq 2 s B_x^2 B_\beta \sum_i w_i (u_i - u)^4 + 2 \frac{\epsilon^2 R}{f} \\
= h^4 \cdot 2 s B_x^2 B_\beta \sum_i w_i \left( \frac{u_i - u}{h} \right)^4 + 2 \frac{\epsilon^2 R}{f} \\
\leq 2 h^4 s B_x^2 B_\beta K + 2 \frac{\epsilon^2 R}{f},
\]
which proves the first statement.

The second statement immediately follows since
\[
\sum_i w_i^2 (\tilde{q}_i - q_i)^2 \leq \|w\|_{\infty} \cdot \sum_i w_i (\tilde{q}_i - q_i)^2 \leq 2 h^4 s B_w B_x^2 B_\beta K + 2 B_w \frac{\epsilon^2 R}{f}. \]

A.6 Proof of Theorem 1

Throughout the section, use \( \hat{b}^\lambda \) to denote \( \hat{b} \) defined in Section 3. In particular, \( \hat{b} \) is defined in (35), \( \hat{b}^\lambda \) is \( \hat{b} \) thresholded at level \( \lambda \), i.e., \( \hat{b}_j^\lambda = \hat{b}_j \cdot 1 \left\{ \hat{b}_j^2 + \hat{b}_{j+p}^2 > \lambda^2 \right\}, 1 \leq j \leq p \), and \( \hat{b}_j^\lambda = \hat{b}_j \cdot 1 \left\{ \hat{b}_j^2 + \hat{b}_{j-p}^2 > \lambda^2 \right\}, p + 1 \leq j \leq 2p. \)
Let \( S' = \text{support}(b^*) \). By Assumption 4, \(|S'| \leq cs\) for some absolute constant \( c \). Therefore,

\[
\| \hat{b}^\lambda - b^* \|_{1,2} \leq \| (\hat{b}^\lambda - b^*)_{S'} \|_{1,2} + \| (\hat{b}^\lambda)_{S^c} \|_{1,2}
\leq \| (\hat{b}^\lambda - \hat{b})_{S'} \|_{1,2} + \| (\hat{b} - b^*)_{S'} \|_{1,2} + \| (\hat{b}^\lambda)_{S^c} \|_{1,2}
\leq cs\lambda + \| (\hat{b} - b^*)_{S'} \|_{1,2} + \| (\hat{b}^\lambda)_{S^c} \|_{1,2}
\leq cs\lambda + \| \hat{b} - b^* \|_{1,2},
\]

where the third inequality comes from the definition of \( \hat{b}^\lambda \). Furthermore, notice that

\[
\| \hat{b} - b^\star \|_{1,2} \geq (\| \hat{b}^\lambda \|_{0,2} - |S'|) \lambda.
\]

Therefore, \( \hat{b}^\lambda \|_{0,2} \leq 2cs + \| \hat{b} - b^\star \|_{1,2}/\lambda \). Because \( \lambda = O(\sqrt{\log(n)p}/nh) \) and \( \| \hat{b} - b^\star \|_{1,2} = O_p \left( s\sqrt{\log(n)p}/nh \right) \)

from Theorem 4, \( \| \hat{b}^\lambda \|_{0,2} \leq O_p(s) \). Now we have shown (23) and (24).

To show (22), we first use the triangle inequality,

\[
\sqrt{\sum_i \left[ w_i \cdot \left( \Gamma_i^\top (\hat{b}^\lambda - b^\star) \right) \right]^2}
\leq \sqrt{\sum_i \left[ w_i \cdot \left( \Gamma_i^\top (\hat{b}^\lambda - \hat{b}) \right) \right]^2} + \sqrt{\sum_i \left[ w_i \cdot \left( \Gamma_i^\top (\hat{b} - b^\star) \right) \right]^2}.
\]

Without loss of generality, we can order the components so that \((\hat{b}^\lambda_j - \hat{b}_j)^2 + (\hat{b}^\lambda_{j+p} - \hat{b}_{j+p})^2\) is decreasing.

Let \( T_1 \) be the set of \( cs \) indices corresponding to the largest values of \((\hat{b}^\lambda_j - \hat{b}_j)^2 + (\hat{b}^\lambda_{j+p} - \hat{b}_{j+p})^2\), similarly, let \( T_k \) be the set of \( cs \) indices corresponding to the largest values of \((\hat{b}^\lambda_j - \hat{b}_j)^2 + (\hat{b}^\lambda_{j+p} - \hat{b}_{j+p})^2\) outside
By monotonicity, \( \| (\hat{b}^\lambda - \hat{b})_T \|_2 \leq \| (\hat{b}^\lambda - \hat{b})_{T_{k-1}} \|_{1,2}/\sqrt{cs} \). Then we have,

\[
\sqrt{S_n \left[ w_i \cdot \left( \Gamma_i^\top (\hat{b}^\lambda - \hat{b}) \right)^2 \right]} = \sqrt{\sum_{k=1}^{[p/\alpha]} S_n \left[ w_i \left( \Gamma_i^\top (\hat{b}^\lambda - \hat{b})_{T_k} \right)^2 \right]}
\leq \sqrt{S_n \left[ w_i \cdot \left( \Gamma_i^\top (\hat{b}^\lambda - \hat{b})_{T_k} \right)^2 \right]} + \sqrt{\sum_{k=2}^{[p/\alpha]} S_n \left[ w_i \left( \Gamma_i^\top (\hat{b}^\lambda - \hat{b})_{T_k} \right)^2 \right]}
\leq \kappa_+ \| (\hat{b}^\lambda - \hat{b})_{T_1} \|_2 + \kappa_+ \sum_{k=2}^{[p/\alpha]} \| (\hat{b}^\lambda - \hat{b})_{T_k} \|_2
\leq \kappa_+ \| (\hat{b}^\lambda - \hat{b})_{T_1} \|_2 + \kappa_+ \sum_{k=1}^{[p/\alpha]} \| (\hat{b}^\lambda - \hat{b})_{T_k} \|_{1,2}/\sqrt{cs}
\leq \kappa_+ \lambda + \kappa_+ \| (\hat{b}^\lambda - \hat{b}) \|_{1,2}/\sqrt{cs}
= O_p \left( \sqrt{\frac{s \log(np)}{nh}} \right).
\]

In addition, from Theorem 4, \( S_n \left[ w_i \cdot \left( \Gamma_i^\top \left( \hat{b} - \hat{b}^* \right) \right)^2 \right] \leq O_p \left( \frac{s \log(np)}{nh} \right) \). Therefore, the first inequality holds.

\section{Proof of Theorem 2}

Our starting point is the basic inequality

\[
\lambda_V \left( \| V \|_{1,F} - \| V \|_{1,F} \right) \geq \text{trace} \left( \frac{1}{2} \delta_i^\top \hat{H}(\delta_b) \delta_i + \delta_i^\top \left( \hat{H}(\delta_b) - H^* \right) V^* + \delta_i^\top (H^* V^* - E_a) \right),
\]

(52)
where \( \delta_b = \hat{b} - b^\star \) and \( \delta_v = \hat{V} - V^\star \). The above display can be rearranged as

\[
\text{trace} \left( \frac{1}{2} \delta_v^\top \hat{H}(\delta_b) \delta_v \right) \\
\leq \lambda_V \left( \|V^\star\|_{1,F} - \|\hat{V}\|_{1,F} \right) - \text{trace} \left( \delta_v^\top \left( \hat{H}(\delta_b) - H^\star \right) V^\star \right) \\
- \text{trace} \left( \delta_v^\top (H^\star V^\star - E_a) \right).
\]

Denote

\[
D := B_A \left( \sqrt{\frac{\hat{f} \cdot \log(p/\gamma)}{n h h_f}} \\
+ \hat{f}' \left( 2B_K h_f + 2B_K \left( h^4 s B_X B_\beta + \frac{\epsilon_B^2}{f^2} \right)^{\frac{1}{2}} + s \sqrt{\frac{B_K \log(np)}{n h}} \right) \right),
\]

where \( B_A \) is defined in Lemma 13. By Lemma 13 with probability at least \( 1 - 2\gamma \),

\[
\left| \text{trace} \left( \delta_v^\top \left( \hat{H}(\delta_b) - H^\star \right) V^\star \right) \right| \leq \|\delta_v\|_{F \cdot D}.
\]

By assumption [5]

\[
\left| \text{trace} \left( \delta_v^\top (H^\star V^\star - E_a) \right) \right| \leq \|\delta_v\|_{1,F} \|H^\star V^\star - E_a\|_{\infty,F} \leq \lambda^\star \|\delta_v\|_{1,F}.
\]

Since \( \|V^\star\|_{1,F} - \|\hat{V}\|_{1,F} \leq \|(\delta_v)_S\|_{1,F} - \|(\delta_v)_N\|_{1,F} \), we have

\[
\lambda_V \|(\delta_v)_N\|_{1,F} \\
\leq \lambda_V \|(\delta_v)_S\|_{1,F} + \left| \text{trace} \left( \delta_v^\top \left( \hat{H}(\delta_b) - H^\star \right) V^\star \right) \right| + \left| \text{trace} \left( \delta_v^\top (H^\star V^\star - E_a) \right) \right| \\
\leq \lambda_V \|(\delta_v)_S\|_{1,F} + \|\delta_v\|_{F \cdot D} + \lambda^\star \|\delta_v\|_{1,F} \\
\leq \lambda_V \|(\delta_v)_S\|_{1,F} + \|\delta_v\|_{F \cdot D} + \frac{\lambda_V}{2} \|\delta_v\|_{1,F}.
\]

Therefore,

\[
\frac{\lambda_V}{2} \|(\delta_v)_N\|_{1,F} \leq \frac{3\lambda_V}{2} \|(\delta_v)_S\|_{1,F} + \|\delta_v\|_{F \cdot D}.
\]
We consider two cases according to whether \( \frac{3\lambda_V}{2} \| (\delta_v)_S \|_{1,F} \geq \| \delta_v \|_F \cdot D \) or not.

If

\[
\frac{3\lambda_V}{2} \| (\delta_v)_S \|_{1,F} \geq \| \delta_v \|_F \cdot D,
\]

then

\[
\| (\delta_v)_N \|_{1,F} \leq 6 \| (\delta_v)_S \|_{1,F}.
\]

Therefore, we have

\[
\| \hat{\mathbf{V}} - V^* \|_{1,F} \leq 7 \| (\hat{\mathbf{V}} - V^*)_S \|_{1,F} \leq 7 \sqrt{s_2} \| (\hat{\mathbf{V}} - V^*)_S \|_F \leq 7 \sqrt{s_2} \| \delta_v \|_F. \tag{54}
\]

On the other hand, from the basic inequality (52),

\[
\lambda_V \| \hat{\mathbf{V}} - V^* \|_{1,F} \]

\[
\geq \text{trace} \left( \frac{1}{2} \delta_v^\top \hat{\mathbf{H}} (\delta_v) + \delta_v^\top \left( \hat{\mathbf{H}} (\delta_v) - H^*\right) V^* + \delta_v^\top (H^* V^* - E_0) \right)
\]

\[
\geq \frac{f \kappa^2}{2} \| \delta_v \|_F^2 - o_p(1) \left( \| \delta_v \|_F + \frac{\| \delta_v \|_{1,F}}{\sqrt{s_2}} \right)^2 - \frac{3\lambda_V}{2} \| (\delta_v)_S \|_{1,F} - \lambda^* \| \delta_v \|_{1,F},
\]

where the second inequality above is because \( \delta_v \in C(S_2) \). Therefore, Assumption 6 holds and we can apply Lemma 18. Because \( \lambda_V \geq 2\lambda^* \), after rearrangement and combining with (54), we get

\[
\| \delta_v \|_F \leq \frac{24\lambda_V \sqrt{s_2}}{f \kappa^2 - o_p(1)} = O_p \left( \frac{s \log p}{nhh_f} \right)
\]

and

\[
\| \delta_v \|_{1,F} \leq 7 \sqrt{s_2} \| \delta_v \|_F = O_p \left( s \sqrt{\frac{\log p}{nhh_f}} \right).
\]

On the other hand, if

\[
\frac{3\lambda_V}{2} \| (\delta_v)_S \|_{1,F} \leq \| \delta_v \|_F \cdot D, \tag{55}
\]

then, from (53), we have

\[
\frac{\lambda_V}{2} \| (\delta_v)_N \|_{1,F} \leq 2 \| \delta_v \|_F \cdot D. \tag{56}
\]
Therefore

\[
\frac{\lambda_V}{2} \|(\delta_v)_N\|_{1,F} \leq 2D\|\delta_v\|_F \leq 2D\|\delta_v\|_{1,F} = 2D (\|(\delta_v)_N\|_{1,F} + \|(\delta_v)_S\|_{1,F}),
\]

which implies

\[
\|(\delta_v)_N\|_{1,F} \leq \frac{4D}{\lambda_V} (\|(\delta_v)_S\|_{1,F} + \|\delta_v\|_F D).
\]

From Assumption 5, we can see that \(B_A \lesssim B_X B_V\). Then under Assumption 7, \(h \asymp n^{-1/3}\) and \(h_f \asymp n^{-1/3}\), and by Assumption 4, \(\epsilon_R \asymp \sqrt{\frac{\log np}{nh}}\), we have

\[
D \asymp \lambda^* \asymp B_V \sqrt{\frac{\log p}{nhf}}
\]

Therefore, there exists \(\lambda_V > 2\lambda^*\) so that \(\frac{4D}{\lambda_V} \leq \frac{\epsilon}{7}\). With such a choice of \(\lambda_V\), \(\delta_v \in C(S)\). Therefore, from (55) and (56),

\[
\lambda_V \|(\delta_v)_1,F \leq \frac{14D}{3} \|\delta_v\|_F D.
\]

On the other hand, by applying Lemma 18 to the basic inequality (52), we have

\[
\lambda_V \|\delta_v\|_1,F \geq f\kappa^2 \|\delta_v\|_F^2 - o_p(1) \left(\|\delta_v\|_F + \frac{\|\delta_v\|_{1,F}}{\sqrt{s_2}}\right)^2 - 2\|\delta_v\|_F D.
\]

Combining the two we have

\[
\frac{20}{3} D\|\delta_v\|_F \geq f\kappa^2 \|\delta_v\|_F^2 - o_p(1) \left(\|\delta_v\|_F + \frac{14D}{3\lambda_V \sqrt{s_2}}\|\delta_v\|_F\right)^2.
\]

Because \(D \asymp \lambda_V \asymp O(B_V \sqrt{\frac{\log p}{nhf}})\), we have

\[
\|\delta_v\|_F \leq \frac{20}{3} \frac{D}{f\kappa^2 - o_p(1)} = O_p \left(B_V \sqrt{\frac{s \log p}{nhf}}\right)
\]

and

\[
\|\delta_v\|_{1,F} \leq \frac{14D}{3\lambda_V \sqrt{s_2}} \|\delta_v\|_F = O_p \left(s B_V \sqrt{\frac{\log p}{nhf}}\right).
\]
To complete the proof, we need to establish a few technical lemmas next.

**Lemma 13.** Suppose that the growth conditions in Assumption 7 is satisfied, and \( r_b \asymp s \sqrt{\frac{\log(np)}{nh}} \). Define
\[
B_A = \max_l \| A_{il} \|_F \quad \text{and} \quad A_{il} = \Gamma_{il} \Gamma_i^\top V^* \quad \text{where} \quad l \in [p] \quad \text{and} \quad \Gamma_{il} = (\Gamma_i, l, l+p)^\top.
\]
For any \( \gamma > 0 \) such that 
\[
\bar{f} \geq (nhf)^{-1} \log(p/\gamma) \quad \text{and} \quad r_b = O(hf \log(p/\gamma)/B_X),
\]
we have
\[
\begin{align*}
\max_{l \in [p]} \sup_{\| \delta_b \|_0, 2 \leq m} \| S_n \left[w_i(\hat{f}_i(\delta_b) - f_i(\tilde{\q}_i))\Gamma_{il} \Gamma_i^\top V^* \right] \|_F \\
\leq B_A \left( \sqrt{\frac{\bar{f} \cdot \log(p/\gamma)}{nhf}} \\
+ \bar{f}^{\ell} \left( 2B_K h_f + 2B_K \left( h^4 sB_X B_\beta + \frac{\epsilon_R^2}{\ell^2} \right)^{1/2} + s \sqrt{\frac{\log(np)}{nh}} \sqrt{B_K} \right) \right)
\end{align*}
\]
with probability \( 1 - 2\gamma \).
Proof. We have

\[
\max_{l \in [p]} \sup_{\|\delta_b\|_{0,2} \leq m \atop \|\delta_b\|_{1,2} \leq r_b} \left\| \mathbb{S}_n \left[ w_i (\hat{f}_i (\delta_b) - f_i (\tilde{q}_i)) \Gamma_i \Gamma_i^\top V^* \right] \right\|_F \\
\leq \max_{l \in [p]} \sup_{\|\delta_b\|_{0,2} \leq m \atop \|\delta_b\|_{1,2} \leq r_b} \left[ \left\| (\mathbb{S}_n - \mathbb{E} \mathbb{S}_n) \left[ w_i (\hat{f}_i (\delta_b) - \tilde{f}_i (0)) \cdot A_{il} \right] \right\|_F \\
+ \left\| (\mathbb{S}_n - \mathbb{E} \mathbb{S}_n) \left[ w_i \cdot (\hat{f}_i (0) - f_i (\tilde{q}_i)) \cdot A_{il} \right] \right\|_F \\
+ \left\| \mathbb{E} \mathbb{S}_n \left[ w_i (\hat{f}_i (\delta_b) - \tilde{f}_i (0)) \Gamma_i \Gamma_i^\top V^* \right] \right\|_F \right]
\leq \max_{l \in [p]} \sup_{\|\delta_b\|_{0,2} \leq m \atop \|\delta_b\|_{1,2} \leq r_b} \left[ \left\| (\mathbb{S}_n - \mathbb{E} \mathbb{S}_n) \left[ w_i (\hat{f}_i (\delta_b) - \tilde{f}_i (0)) \cdot A_{il} \right] \right\|_F \\
+ \left\| (\mathbb{S}_n - \mathbb{E} \mathbb{S}_n) \left[ w_i \cdot (\hat{f}_i (0) - f_i (\tilde{q}_i)) \cdot A_{il} \right] \right\|_F \\
+ \left\| \mathbb{E} \mathbb{S}_n \left[ w_i (\hat{f}_i (0) - f_i (\tilde{q}_i)) \Gamma_i \Gamma_i^\top V^* \right] \right\|_F \right]
\leq B_A \left( \sqrt{\hat{f} \log(p/\gamma)} \frac{1}{nh h_f} \\
+ \tilde{f} \left( B_{K h_f} + 2 B_K \left( h^4 s B_X B_{\beta} + \frac{\epsilon_0^2 h^4}{f^2} \right)^{1/2} + s \sqrt{\frac{\log(np)}{nh} \sqrt{B_K} + B_K h_f} \right) \right),
\]

where the last inequality follows by first combining Lemmas 14, 15, 16 and 17 and plugging in our condition for \(r_b, h\) and \(h_f\). \(\square\)

Lemma 14. Under the conditions of Lemma 13 we have

\[
\max_{l \in [p]} \sup_{\|\delta_b\|_{0,2} \leq m \atop \|\delta_b\|_{1,2} \leq r_b} \left\| (\mathbb{S}_n - \mathbb{E} \mathbb{S}_n) \left[ w_i \cdot (\hat{f}_i (\delta_b) - \tilde{f}_i (0)) \cdot A_{il} \right] \right\|_F 
\lesssim \frac{B_K B_A}{h_f} \sqrt{\hat{f} B_X r_b (m \log p + \log(1/\gamma)) \frac{1}{nh}}
\]

with probability \(1 - \gamma\), where \(A_{il}\) and \(B_A\) are defined in Lemma 13.

Proof. Let \(\mathcal{W} = \{ \tilde{W}_1, \ldots, \tilde{W}_K \} \) be the \(\frac{1}{2}\)-net for \(\{ W \in \mathbb{R}^{2k \times 2k} \mid \| W \|_F \leq 1 \} \). We have that \(K \leq 5^{4k^2}\).
and

\[
\max_{\ell \in [p]} \sup_{\|\delta_\ell\|_{1,2} \leq r_b} \left\| (S_n - ES_n) \left[ w_i \cdot (\hat{f}_i(\delta_b) - \hat{f}_i(0)) \cdot A_\ell \right] \right\|_F \\
\leq 2 \cdot \max_{W \in \mathcal{W}} \max_{\ell \in [p]} \sup_{\|\delta_\ell\|_{0,2} \leq m} \left( S_n - ES_n \right) \left[ w_i \cdot (\hat{f}_i(\delta_b) - \hat{f}_i(0)) \cdot \text{trace} \left( \hat{W}^\top A_\ell \right) \right].
\]

Our goal is to apply Lemma 25 to bound the right hand side.

Note that

\[
2 h_f \left( \hat{f}_i(\delta_b) - \hat{f}_i(0) \right) = 1 \left\{ h_f < y_i - \Gamma_i^\top b^* \leq h_f + \Gamma_i^\top \delta_b \right\} \\
- 1 \left\{ h_f + \Gamma_i^\top \delta_b < y_i - \Gamma_i^\top b^* \leq h_f \right\} \\
- 1 \left\{ -h_f \leq y_i - \Gamma_i^\top b^* < -h_f + \Gamma_i^\top \delta_b \right\} \\
+ 1 \left\{ -h_f + \Gamma_i^\top \delta_b \leq y_i - \Gamma_i^\top b^* < -h_f \right\}.
\]

We proceed to bound

\[
\max_{W \in \mathcal{W}} \sup_{\ell \in [p]} \sup_{|S| \leq m} \left( S_n - ES_n \right) \left[ w_i \cdot 2 h_f \cdot 1 \left\{ h_f < y_i - \Gamma_i^\top b^* \leq h_f + \Gamma_i^\top \delta_b \right\} \cdot \text{trace} \left( \hat{W}^\top A_\ell \right) \right],
\]

while the other terms are bounded similarly. For a fixed \( W \in \mathcal{W}, \ell \in [p] \) and \(|S| \leq m\), define

\[
a_i = \frac{w_i}{2 h_f} \cdot \text{trace} \left( \hat{W}^\top A_\ell \right), \text{ and}
\]

\[
\mathcal{G}_S = \left\{ (y_i, x_i, u_i) \mapsto a_i \cdot 1 \left\{ h_f < y_i - \Gamma_i^\top b^* \leq h_f + \Gamma_i^\top \delta_b \right\} : \text{support} (\delta_b) = S, \|\delta_b\|_{1,2} \leq r_b \right\},
\]

\[
\mathcal{G} = \bigcup_{|S| \leq m} \mathcal{G}_S
\]

Let \( G(\cdot) \) be an envelope of \( \mathcal{G} \) and note that \( \|G\|_\infty \leq \frac{B h f}{\min h_f} \). For a fixed \( g \in \mathcal{G} \), let

\[
g_i = g(y_i, x_i, u_i) = a_i \cdot 1 \left\{ h_f < y_i - \Gamma_i^\top b^* \leq h_f + \Gamma_i^\top \delta_b \right\}.
\]
We have that
\[
\mathbb{E}\left[ \mathbb{1}\left\{ h_f < y_i - \Gamma_i^\top b^* \leq h_f + \Gamma_i^\top \delta_b \right\} \right] = F_i \left( \Gamma_i^\top b^* + h_f + \Gamma_i^\top \delta_b \right) - F_i \left( \Gamma_i^\top b^* + h_f \right) \\
\leq \tilde{f} \cdot \mathbb{1}_{\left| \Gamma_i^\top \delta_b \right|} \\
\leq \tilde{f} B_X r_b,
\]
and, therefore, the variance is bounded as
\[
\sigma^2_G \leq \sup_{g \in G} \sum_{i \in [n]} \mathbb{E}\left[ g_i^2 \right] \leq \tilde{f} B_X r_b \sum_{i \in [n]} a_i^2 \leq \tilde{f} B_X B_K^2 B_A^2 \cdot \frac{r_b}{n h h_f}.
\]

The VC dimension for the space
\[
\mathcal{F}_S = \left\{ (y_i, x_i, u_i) \mapsto \mathbb{1}\left\{ h_f < y_i - \Gamma_i^\top b^* \leq h_f + \Gamma_i^\top \delta_b \right\} : \text{support (} \delta_b \text{)} = S, \| \delta_b \|_{1,2} \leq r_b \right\}
\]
is $|S| \leq m$. Therefore, applying Lemma 22 and Lemma 24,
\[
\sup_Q \log N \left( \epsilon \cdot \frac{B_K B_A}{n h f}, \mathcal{G}_S, \| \cdot \|_{L_2(Q)} \right) \lesssim m \log(1/\epsilon).
\]
Since there are $\binom{p}{m}$ different supports $S$ in $\mathcal{G}$, we have
\[
\sup_Q \log N \left( \epsilon \cdot \frac{B_K B_A}{n h f}, \mathcal{G}, \| \cdot \|_{L_2(Q)} \right) \lesssim m (\log(1/\epsilon) + \log(p)).
\]
Applying Lemma 21 with $\sigma_G = \frac{B_K B_A}{h_f} \sqrt{\frac{f r_b B_X}{n h}}$, $\|G\|_{\infty} \leq \frac{B_K B_A}{n h f}$, $V = cm$, and $A = Cp^{1/c}$, we have
\[
\mathbb{E} \left[ \sup_{g \in \mathcal{G}} \sum_{i \in [n]} g_i - \mathbb{E}[g_i] \right] \lesssim \left( \frac{m B_K B_A \log(p)}{\sqrt{f r_b B_X h}} + \frac{B_K B_A}{h_f} \sqrt{\frac{f r_b B_X}{n h}} \sqrt{m \log \frac{p}{\sqrt{f r_b B_X h}}} \right) \\
\lesssim \frac{B_K B_A}{h_f} \sqrt{\tilde{f} B X} \cdot \frac{m r_b \log p}{n h}.
\]
where the last inequality follows from the conditions on $r_b$ in Lemma 13 and Assumption 7. Finally, Lemma 25 gives us

$$
\sup_{g \in \mathcal{G}} \sum_{i \in [n]} g_i - \mathbb{E}[g_i] \lesssim \frac{B_K B_A}{h_f} \sqrt{f B_X r_b \left( m \log p + \log \left( \frac{1}{\gamma} \right) \right)} \frac{1}{n h},
$$

with probability $1 - \gamma$, and, by the union bound over $\tilde{W} \in \mathcal{W}$, $l \in [p]$,

$$
\max_{l \in [p]} \sup_{\|\delta_b\|_{1.2} \leq r_b} \max_{\|\delta_b\|_{0.2} \leq m} \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot 1 \left\{ h_f < y_i - \Gamma_i^\top b^* \leq h_f + \Gamma_i^\top \delta_b \right\} \cdot \text{trace} \left( \tilde{W}^\top A_{il} \right) \right]
\lesssim \frac{B_K B_A}{h_f} \sqrt{f B_X r_b \left( 2 m \log p + \log \left( \frac{5k^2}{\gamma} \right) \right)} \frac{1}{n h}.
$$

Handling other terms in the same way, we obtain

$$
\max_{l \in [p]} \sup_{\|\delta_b\|_{1.2} \leq r_b} \left\| \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot \left( \hat{f}_i(\delta_b) - \hat{f}_i(0) \right) \cdot A_{il} \right] \right\|_F
\lesssim \frac{B_K B_A}{h_f} \sqrt{f B_X r_b \left( m \log p + \log \left( \frac{1}{\gamma} \right) \right)} \frac{1}{n h},
$$

with probability $1 - \gamma$, which completes the proof.

\[\square\]

**Lemma 15.** Under the conditions of Lemma 13 we have

$$
\max_{l \in [p]} \left\| \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot \hat{f}_i(0) \cdot A_{il} \right] \right\|_F \leq \sqrt{f B_R^2 B_A^2 \log(p/\gamma)} \frac{1}{n h f}
$$

with probability $1 - \gamma$.

**Proof.** Let $\mathcal{W}$ be as in the proof of Lemma 14. Then

$$
\max_{l \in [p]} \left\| \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot \hat{f}_i(0) \cdot A_{il} \right] \right\|_F
\leq 2 \max_{\tilde{W} \in \mathcal{W}} \max_{l \in [p]} \left( \mathbb{S}_n - \mathbb{E}\mathbb{S}_n \right) \left[ w_i \cdot \hat{f}_i(0) \cdot \text{trace} \left( \tilde{W}^\top A_{il} \right) \right].
$$
Let $Z_i = w_i \cdot \hat{f}(0) \cdot \text{trace}(\hat{W}^T A_i)$. Then

$$
\sum_{i \in [n]} \mathbb{E} \left[ Z_i^2 \right] \leq \sum_{i \in [n]} \frac{w_i^2 \cdot \text{trace}(\hat{W}^T A_i)^2}{h_f^2} \cdot \mathbb{E} \left[ 1 \left\{ \left| y_i - \Gamma_i^T b^* \right| \leq h_f \right\} \right] = O \left( \frac{\tilde{f}B^2_K B_A^2}{n h h_f} \right)
$$

and

$$
\max_{i \in [n]} |Z_i| \leq O \left( \frac{\tilde{f}B_K B_A}{n h h_f} \right).
$$

The result follows from Lemma 25 and the union bound.

**Lemma 16.** Suppose conditions of Lemma 13 hold. Then

$$
\max_{l \in [p]} \left\| E_l^T \left( \mathbb{E} \left[ \hat{H}(\delta_b) \right] - \mathbb{E} \left[ \hat{H}(0) \right] \right) V^* \right\|_F \leq \tilde{f}' B_A \left( s \sqrt{\frac{B_K \log(np)}{n h}} + B_K h_f \right).
$$

**Proof.** For a fixed $\delta_b$, the mean value theorem gives us

$$
2 h_f \left| \mathbb{E} \left[ \hat{f}(\delta_b) \right] - \mathbb{E} \left[ \hat{f}(0) \right] \right| = \left| F_i \left( \Gamma_i^T (b^* + \delta_b) + h_f \right) - F_i \left( \Gamma_i^T (b^* + \delta_b) - h_f \right) - F_i \left( \Gamma_i^T b^* + h_f \right) + F_i \left( \Gamma_i^T b^* - h_f \right) \right| \leq 2 h_f \tilde{f}' \left| \Gamma_i^T \delta_b \right| + h_f
$$

Therefore, we have that

$$
\max_{l \in [p]} \left\| E_l^T \left( \mathbb{E} \left[ \hat{H}(\delta_b) \right] - \mathbb{E} \left[ \hat{H}(0) \right] \right) V^* \right\|_F \leq \tilde{f}' B_A \sum_{i \in [n]} w_i \cdot \left( \left| \Gamma_i^T \delta_b \right| + h_f \right) \leq \tilde{f}' B_A \left( s \sqrt{\frac{\log(np)}{n h}} \sqrt{B_K} + B_K h_f \right),
$$

where the last inequality follows from Lemma 12 and Assumption 6.

\(\square\)
Lemma 17. Suppose conditions of Lemma 13 hold. Then

$$\max_{l \in [p]} \left| E_l^T \left( E \left[ \hat{H}(0) \right] - H^* \right) V^* \right|_F \leq \bar{f} B_A \left( B_K h_f + 2 \left( h^4 s B_X B_\beta + \frac{e_2^2}{I^2} \right)^{1/2} \right).$$

Proof. The mean value theorem gives us

$$2 h_f E \left[ \hat{f}_i(0) \right] = F_i \left( \Gamma_i^T b^* + h_f \right) - F_i \left( \Gamma_i^T b^* - h_f \right)$$

$$= 2 h_f \cdot f_i(q_i) + 2 h_f \cdot (f_i(\bar{q}_i) - f_i(q_i)),$$

where $\bar{q}_i$ is a point between $\Gamma_i^T b^* - h_f$ and $\Gamma_i^T b^* + h_f$. Therefore, we have

$$\left| E \left[ \hat{f}_i(0) \right] - f_i(q_i) \right| \leq \bar{f} \left| \bar{q}_i - q_i \right| \leq \bar{f} \left( \left| \bar{q}_i - q_i \right| + h_f \right),$$

and

$$\left| f_i(\bar{q}_i) - f_i(q_i) \right| \leq \bar{f} \left| \bar{q}_i - q_i \right|.$$

Finally, we have

$$\max_{l \in [p]} \left| E_l^T \left( E \left[ \hat{H}(0) \right] - H^* \right) V^* \right|_F$$

$$\leq \bar{f} B_A \sum_{i \in [n]} w_i \cdot (2 \left| \bar{q}_i - q_i \right| + h_f)$$

$$\leq \bar{f} B_A \left( h_f \sum_{i \in [n]} w_i + 2 \left( \sum_{i \in [n]} w_i \right)^{1/2} \cdot \left( \sum_{i \in [n]} w_i \left( \bar{q}_i - q_i \right)^2 \right)^{1/2} \right)$$

$$\leq \bar{f} B_A B_K \left( h_f + 2 \left( h^4 s B_X^2 B_\beta + \frac{e_2^2}{I^2} \right)^{1/2} \right),$$

where the last inequality follows from Lemma 12 and Assumption 6.

Lemma 18. Assume $B_V$ satisfies Assumption 5 that $(nh)^{-1} s B_V^2 \log p = o(1)$ and $\log(B_V^2 h_f h) = O(\log p)$. Let $S_1$ be the support of $b^*$ and $S_2$ be the support of $V^*$ as defined in Assumption 6 with $|S_1| = s_1$ and
\[ |S_2| = s_2. \text{ Define} \]
\[
\Delta_b(r_b, s_1) = \{ \delta \in \mathbb{R}^{2p}, \|\delta\|_2 \leq r_b, \|\delta\|_0 \leq s_1 \} \quad \text{and} \\
\mathcal{C}(S) = \{ \Theta \in \mathbb{R}^{2k \times 2p} : \|\Theta_{Sc}\|_{1,F} \leq 6\|\Theta_S\|_{1,F} \}. 
\]
Then
\[
\text{trace} \left( \delta_v^\top \hat{H}(\delta_b) \delta_v \right) \geq f \kappa^2 \delta_v \|\delta_v\|_F^2 - \frac{f}{\sqrt{s_2}} \left( \|\delta_v\|_F + \frac{\|\delta_v\|_{1,F}}{\sqrt{s_2}} \right)^2
\]
for all \( \delta_b \in \Delta_b(r_b, s_1) \) and \( \delta_v \in \mathcal{C}(S_2) \).

**Proof.** For a fixed \( \delta_b \), we have that \( f_i(\delta_b) \geq f_\delta \) and \( \delta_v \in \mathcal{C}(S_2) \). Therefore,
\[
\text{trace} \left( \delta_v^\top H(\delta_b) \delta_v \right) \geq f \sum_{i \in [n]} w_i \text{trace}(\delta_v^\top \Gamma_i \Gamma_i^\top \delta_v) \geq f \kappa^2 \|\delta_v\|_F^2.
\]
The proof now follows from Lemma 19 and Lemma 20 (presented next),
\[
\text{trace} \left( \delta_v^\top \hat{H}(\delta_b) \delta_v \right) \\
\geq \text{trace} \left( \delta_v^\top H(\delta_b) \delta_v \right) - \text{trace} \left( \delta_v^\top \left( \hat{H}(\delta_b) - H(\delta_b) \right) \delta_v \right) \\
\geq \text{trace} \left( \delta_v^\top H(\delta_b) \delta_v \right) \\
- \sup_{\delta \in \Delta_v(s_2)} \sup_{\delta_b \in \Delta_b(r_b, s_1)} \left| \text{trace} \left( \delta_v^\top \left( \hat{H}(\delta_b) - H(\delta_b) \right) \delta_v \right) \right| \left( \|\delta_v\|_F + \frac{\|\delta_v\|_{1,F}}{\sqrt{s_2}} \right)^2 \\
\geq f \kappa^2 \|\delta_v\|_F^2 - o_p(1) \left( \|\delta_v\|_F + \frac{\|\delta_v\|_{1,F}}{\sqrt{s_2}} \right)^2,
\]
where \( \Delta_v(s_2) \) is as defined in Lemma 20.

**Lemma 19.** (Based on proposition 5 in [Sun and Zhang 2013].) For any fixed matrix \( M \in \mathbb{R}^{p \times p} \) and matrices \( u \in \mathbb{R}^{k \times p} \) and \( s \in \mathbb{N} \),
\[
\text{trace} \left( u^\top Mu \right) \leq \left( \|u\|_F + \frac{\|u\|_{1,F}}{\sqrt{s}} \right)^2 \|M\|_{S_s},
\]
where \( S_s = \{ u \in \mathbb{R}^{k \times p} | \| u \|_F = 1, \| u \|_{0,F} \leq s \} \) and

\[
\| M \|_{S_s} = \max_{u, v \in S_s} \text{trace} \left( u^\top M v \right).
\]

**Lemma 20.** Under the conditions of Lemma 18, we have

\[
\sup_{\delta_v \in \Delta_v(s_2)} \sup_{\delta_b \in \Delta_b(r_b, s_1)} \left| \text{trace} \left( \delta_v^\top \left( \hat{H}(\delta_b) - H(\delta_b) \right) \delta_v \right) \right| = O_p \left( \sqrt{\frac{(s_1 + s_2) f \kappa \beta B_k B_{1}^2 \log(p)}{n h h_f}} \right),
\]

where

\[
\Delta_v(s_2) = \{ \delta \in \mathbb{R}^{2k \times 2p}, \| \delta \|_F = 1, \| \delta \|_{0,F} \leq s_2 \},
\]

\[
\Delta_b(r_b, s_1) = \{ \delta \in \mathbb{R}^{2p}, \| \delta \|_2 \leq r_b, \| \delta \|_0 \leq s_1 \}.
\]

**Proof.** We have

\[
\sup_{\delta_v \in \Delta_v(s_2)} \sup_{\delta_b \in \Delta_b(r_b, s_1)} \left| \text{trace} \left( \delta_v^\top \left( \hat{H}(\delta_b) - H(\delta_b) \right) \delta_v \right) \right|
\]

\[
= \sup_{\delta_v \in \Delta_v(s_2)} \sup_{\delta_b \in \Delta_b(r_b, s_1)} \left( \mathbb{S}_n - \mathbb{E} \mathbb{S}_n \right) \left\{ w_i (2h_f)^{-1} \mathbb{1} \left\{ \left| y_i - \Gamma_i^\top (b^* + \delta_b) \right| \leq h_f \right\} \right\} \cdot \| \delta_v \|_2^2
\]

\[
\leq 2 \sup_{\delta_v \in \mathcal{N}_e} \sup_{\delta_b \in \Delta_b(r_b, s_1)} \left( \mathbb{S}_n - \mathbb{E} \mathbb{S}_n \right) \left\{ w_i (2h_f)^{-1} \mathbb{1} \left\{ \left| y_i - \Gamma_i^\top (b^* + \delta_b) \right| \leq h_f \right\} \right\} \cdot \| \delta_v \|_2^2,
\]

where \( \mathcal{N}_e \) is an \( \epsilon \)-net for \( \Delta_v(s_2) \). We have \( |\mathcal{N}_e| \leq 5^{2k s_2} \). Fix \( \delta_v \in \mathcal{N}_e \). Define

\[
a_i = (2h_f)^{-1} \mathbb{1} \cdot \text{trace} \left\{ \delta_b \Gamma_i \Gamma_i^\top \delta_v \right\},
\]

\[
G_S = \left\{ (y_i, x_i, u_i) \mapsto a_i \cdot \mathbb{1} \left\{ \left| y_i - \Gamma_i^\top (b^* + \delta_b) \right| \leq h_f \right\} : \text{support}(\delta_b) = S, \| \delta_b \|_2 \leq r_b \right\},
\]

\[
G = \cup_{S: |S| \leq s_1} G_S.
\]

Let \( G(\cdot) = \frac{B_k B_{1}^2}{2n h h_f} \) be an envelope of \( G \). For a fixed \( g \in G \), let

\[
g_i = g(y_i, x_i, u_i) = a_i \cdot \mathbb{1} \left\{ \left| y_i - \Gamma_i^\top (b^* + \delta_b) \right| \leq h_f \right\}.
\]
Therefore, the variance is bounded as
\[
\sigma^2_G \leq \sup_{g \in G} \sum_{i \in [n]} \mathbb{E} \left[ g_i^2 \right] \approx \bar{f} \bar{h} \sum_{i \in [n]} (4h_i^2)^{-1} w_i^4 \cdot \| \delta_i \Gamma_i \|^4 \lesssim \frac{\bar{f} \kappa K B_v^2}{n h h_f}.
\]

The VC dimension for the space \(G_S\) is \(O(|S|)\). Therefore, using Lemma 22,
\[
\sup_Q \log N(\epsilon, G, \| \cdot \|_{L^2(Q)}) \lesssim s_1 \left( \log(p) + \log(1/\epsilon) \right).
\]

Applying Lemma 21 we obtain
\[
\mathbb{E} \left[ \sup_{g \in G} \sum_{i \in [n]} g_i - \mathbb{E} [g_i] \right] \lesssim \sqrt{s f \kappa K B_v^2 \log(p)} \frac{1}{n h h_f},
\]
under our assumptions. Using Lemma 25
\[
\sup_{g \in G} \sum_{i \in [n]} g_i - \mathbb{E} [g_i] = O_p \left( \sqrt{s f \kappa K B_v^2 \log(p)} \frac{1}{n h h_f} \right).
\]
A union bound over \(N_\epsilon\) completes the proof. \(\square\)

A.8 Empirical Process Results

Definition 1. The covering number \(N(\epsilon, F, \| \cdot \|_{L^2(P)})\) is the minimal number of balls \(\{g \mid \|g - f\| \leq \epsilon\}\) of radius \(\epsilon\) needed to cover the set \(F\).

Let \(\|F\|_{\infty} = \sup \{ \|f\|_{\infty}, f \in F \}\). Furthermore, define
\[
\Sigma^2_F = \mathbb{E} \left[ \sup_{f \in F} \sum_{i \in [n]} W_i^2(f) \right] \quad \text{and} \quad \sigma^2_F = \sup_{f \in F} \sum_{i \in [n]} \mathbb{E} [W_i^2(f)]
\]
(57)
where \(W_i(f), f \in F, i \in [n]\) are real valued random variables.

Lemma 21. Let \(F\) be a measurable uniformly bounded class of functions satisfying
\[
N(\epsilon \|F\|_{L^2(P)}, F, L^2(P)) \leq \left( \frac{A}{\epsilon} \right)^V
\]
for all probability measures $P$, where $F := \sup_{f \in F} |f|$ is the envelope function and $A$, $V$ are constants dependent on $F$. Let $\sigma_F^2 = \sup_{f \in F} \sum_{i \in \mathbb{N}} \mathbb{E} \left[ (f_i - \mathbb{E}[f_i])^2 \right]$ and $U \geq \sup_{f \in F} \|f\|_{\infty}$ be such that $0 < \sigma_F \leq \sqrt{n}U$. Then there exists a universal constant $C$ such that

$$\mathbb{E} \left[ \sup_{f \in F} \sum_{i \in [n]} f_i - \mathbb{E}[f_i] \right] \leq C \left[ VU \log \frac{\sqrt{n}AU}{\sigma_F} + \sigma_F \sqrt{V \log \frac{\sqrt{n}AU}{\sigma_F}} \right].$$

Proof. This is essentially Proposition 2.1 of [Giné and Guillou (2001)] combined with symmetrization [Koltchinskii and Yuan (2010)].

Lemma 22 (Theorem 2.6.7 of [van der Vaart and Wellner (1996)]). Suppose $F$ is a function class with a bounded VC-dimension, $V$, and an envelope $F$. Then there exist absolute constants $c, C > 0$ such that

$$\sup_Q N(\epsilon \|F\|_{Q,2}, F, \|\cdot\|_{L_2(Q)}) \leq \left( \frac{C}{\epsilon} \right)^{cV}$$

for all $\epsilon \in (0, 1)$ and the probability measure $Q$ ranges over distributions such that $\|F\|_{Q,2} > 0$.

Lemma 23 (Lemma 22 of [Nolan and Pollard (1987)]). Let $K : \mathbb{R} \mapsto \mathbb{R}$ be a bounded variation function. The function class

$$\mathcal{K} = \left\{ K \left( \frac{s - \cdot}{h} \right) \mid h > 0, s \in \mathbb{R} \right\},$$

indexed by the kernel bandwidth and the location $s$, satisfies the uniform entropy condition

$$\sup_Q N(\epsilon, \mathcal{K}, \|\cdot\|_{L_2(Q)}) \leq C \epsilon^{-v}, \text{ for all } \epsilon \in (0, 1),$$

for some $C > 0$ and $v > 0$.

Lemma 24 (Lemma 26 of [Lu et al. (2018)]). Let $\mathcal{F}$ and $\mathcal{G}$ be two function classes satisfying

$$\sup_Q N(a_1 \epsilon, \mathcal{F}, \|\cdot\|_{L_2(Q)}) \leq C_1 \epsilon^{-v_1} \quad \text{and} \quad \sup_Q N(a_2 \epsilon, \mathcal{G}, \|\cdot\|_{L_2(Q)}) \leq C_2 \epsilon^{-v_2}$$

for some $C_1, C_2, a_1, a_2, v_1, v_2 > 0$ and any $0 < \epsilon < 1$. Define

$$\mathcal{F}_x = \{ fg \mid f \in \mathcal{F}, g \in \mathcal{G} \} \quad \text{and} \quad \mathcal{F}_+ = \{ f + g \mid f \in \mathcal{F}, g \in \mathcal{G} \}.$$
Then for any $\epsilon \in (0, 1)$,

$$\sup_Q N(\epsilon, \mathcal{F}_x, \|\cdot\|_{L_2(Q)}) \leq C_1 C_2 \left( \frac{2a_1 U}{\epsilon} \right)^{v_1} \left( \frac{2a_2 U}{\epsilon} \right)^{v_2}$$

and

$$\sup_Q N(\epsilon, \mathcal{F}_+, \|\cdot\|_{L_2(Q)}) \leq C_1 C_2 \left( \frac{2a_1 U}{\epsilon} \right)^{v_1} \left( \frac{2a_2 U}{\epsilon} \right)^{v_2},$$

where $U = \|\mathcal{F}\|_\infty \vee \|\mathcal{G}\|_\infty$.

**Lemma 25.** Let

$$Z = \sup_{f \in \mathcal{F}} \sum_{i \in [n]} W_i(f)$$

where $E[W_i(f)] = 0$ and $|W_i(f)| \leq M$ for all $i \in [n]$ and $f \in \mathcal{F}$. Then

$$Z \leq E[Z] + 4 \left( \sqrt{4M E[Z] + \sigma_f^2} \log(1/\delta) \right) \log(1/\delta)$$

with probability $1 - \delta$.

**Proof.** The lemma is a simple consequence of Theorems 11.8 and 12.2 in [Boucheron et al. (2013)]. Assume that $M = 1$. Then Theorem 12.2 in [Boucheron et al. (2013)] gives us

$$P \{ Z \geq E[Z] + t \} \leq \exp \left( - \frac{t^2}{2 \left( \Sigma_{\mathcal{F}}^2 + \sigma_f^2 \right) + t} \right).$$

Hence, with probability $1 - \delta$, we have

$$Z \leq E[Z] + \sqrt{8 \left( \Sigma_{\mathcal{F}}^2 + \sigma_f^2 \right) \log(1/\delta) \log(1/\delta)}.$$

Furthermore, Theorem 11.8 in [Boucheron et al. (2013)] gives us that

$$\Sigma_{\mathcal{F}}^2 + \sigma_f^2 \leq 8E[Z] + 2\sigma_f^2.$$
Combining with the display above, we get

$$Z \leq \mathbb{E}[Z] + 4\left(\sqrt{4\mathbb{E}[Z] + \sigma_Z^2} \log(1/\delta) \sqrt{\log(1/\delta)}\right)$$

with probability $1 - \delta$. We can rescale the equation above by $M$ to conclude the proof of the lemma.

\[ \square \]

B Numerical studies

Detailed data settings In our numerical study, we set the parameters

$$(a_0, a_1, b_0, b_1, c_0, c_1, d_0, d_1, \rho, \sigma_e) = (1, 0.1, 1, 0.1, 1, 0.5, 1, 0.2, 0.2, 1)$$

to represent a general setting. We study the cases where $\gamma = 0$ and $\gamma = 1$, and choose $c_y$ and $c_x$ to form different combinations of $(R^2_y, R^2_x)$.

Additional simulation results In Table 2, we present the performance of methods with different combinations of $(R^2_x, R^2_y)$.

C Remarks on Assumption 5

Assumption 5 holds when $X_A$ follows a multivariate approximately sparse linear model, where we require the coefficients to be approximately linear, sparse, and smooth. Specifically, we assume that there exists a smooth and sparse $\zeta_1^*(u), \cdots, \zeta_k^*(u)$, that is,

- $u \mapsto \zeta_j^*(u)$ is differentiable for $j = 1, \cdots, k$ and

$$\|\zeta_j^*(u') - \zeta_j^*(u)\|_2 \leq B_{\zeta}\|u' - u\|;$$

$$\|\zeta_j^*(u') - \zeta_j^*(u) - (u' - u) \cdot \nabla_u \zeta_j^*(u)\|_2 \leq B_{\zeta}(u' - u)^2;$$
the supports of $\beta^*(u, \tau)$ and $\partial_u \beta^*(\tau, u)$ are sparse, i.e.

$$S_j := \{ j \in [p] \mid \zeta_j^*(u) \neq 0 \} \text{ and } S'_j := \{ j \in [p] \mid \zeta_j^*(u) \neq 0 \text{ or } \partial_u \zeta_j^*(u) \neq 0 \},$$

$$s_j := |S| \ll n \text{ and } |S'| \leq s_{1j} := c_{1j} s_j \text{ for some constants } c_{1j};$$

such that with $\zeta^*(u) = (\zeta_1^*(u), \ldots, \zeta_k^*(u))^\top$ the residual $r_i = x_{i,A} - \zeta^*(u)x_{i,A^c}$ is approximately orthogonal to $x_{i,A^c}$ weighted by $w_i f_i(\hat{q}_i)$. Specifically,

$$\max \left\{ \| \sum_i w_i f_i(\hat{q}_i) r_i x_{i,A^c}^\top \|_\infty, \right\}
\left\{ \| \sum_i w_i f_i(\hat{q}_i) r_i \frac{u_i - u}{h} x_{i,A^c}^\top \|_\infty, \| \sum_i w_i f_i(\hat{q}_i) r_i \frac{(u_i - u)^2}{h^2} x_{i,A^c}^\top \|_\infty \right\}
= \epsilon_r^2 = O \left( \frac{\log(np)}{n h h_f} \right).
$$

Based on our model assumption, for a fixed $u$, let

$$r^* = r^*(u) = \begin{pmatrix} \zeta^*(u) & h \nabla_u \zeta^*(u) \\ 0 & \zeta^*(u) \end{pmatrix}.$$

We have the following sparse linear regression model

$$w_i f_i(\hat{q}_i) \begin{pmatrix} x_{i,A} \\ \frac{u_i - u}{h} x_{i,A} \end{pmatrix} = w_i f_i(\hat{q}_i) r^* \begin{pmatrix} x_{i,A^c} \\ \frac{u_i - u}{h} x_{i,A^c} \end{pmatrix} + w_i f_i(\hat{q}_i) \tilde{r}_i$$

where

$$\tilde{r}_i = \begin{pmatrix} r_i + (\zeta^*(u_i) - \zeta^*(u)) - (u_i - u) \cdot \nabla_u \zeta^*(u)x_{i,A^c} \\ \frac{u - u_i}{h} (r_i + (\zeta^*(u_i) - \zeta^*(u)) x_{i,A^c}) \end{pmatrix}.$$

If $\Sigma_{11} = \sum_i w_i f_i(\hat{q}_i) \tilde{r}_i \tilde{r}_i^\top$ is invertible, then we can have a specific $V^*$ in the form of $\Sigma_{11}^{-1}(I_{2k}, -r^*)$ satisfy Assumption 5. The sparsity of $\zeta^*(u)$ guarantees the sparsity of $V^*$, so we just need to show

$$\| H^* V^* - E_a \|_{\infty, F} \leq \lambda^*,$$

where the norm $\| \cdot \|_{\infty, F}$ for $V \in \mathbb{R}^{2k \times 2p}$ is defined as $\| V \|_{\infty, F} = \sup_{i \in [k], j \in [p]} \| V(i, i+k),(j,j+p) \|_F$. If we show that

$$\| \Sigma_{11}^{-1} \sum_i w_i f_i(\hat{q}_i) \tilde{r}_i \tilde{r}_i^\top \|_{\infty, F} \leq \lambda^*,$$
then

\[
\| \Sigma_{11}^{-1} \sum_i w_i f_i(\tilde{q}_i) \tilde{r}_i \Gamma_{i,A}^\top - I_{2k} \|_{\infty,F} = \| \Sigma_{11}^{-1} \left( \sum_i w_i f_i(\tilde{q}_i) \tilde{r}_i \Gamma_{i,A}^\top - \sum_i w_i f_i(\tilde{q}_i) \tilde{r}_i \tilde{r}_i^\top \right) \|_{\infty,F} = \| \Sigma_{11}^{-1} \left( \sum_i w_i f_i(\tilde{q}_i) \tilde{r}_i \Gamma_{i,A}^\top \right) \|_{\infty,F} \leq \lambda^*.
\]

Since \( \Sigma_{11} \) is invertible, it is sufficient to bound \( \| \sum_i w_i f_i(\tilde{q}_i) \tilde{r}_i \Gamma_{i,A}^\top \|_{\infty,F} \). Given that

\[
\| \sum_i w_i f_i(\tilde{q}_i) \tilde{r}_i \Gamma_{i,A}^\top \|_{\infty,F} \leq \sup_{l \in [k], j \in [p - k]} \left\{ \left( \sum_i w_i f_i(\tilde{q}_i)(r_{il} + x_{i,A^c}(\zeta^*_l(u_i) - \zeta^*_l(u)) - (u_i - u) \cdot \nabla u \zeta^*_l(u)) \right) (x_{i,A^c}^j, u_i - u \overline{x}_{i,A^c}^j) \right\}^2
\]

\[
+ \sum_i w_i f_i(\tilde{q}_i)(r_{il} + x_{i,A^c}(\zeta^*_l(u_i) - \zeta^*_l(u)) - (u_i - u) \cdot \nabla u \zeta^*_l(u)) \cdot \overline{x}_{i,A^c}^j \right\}^2
\]

\[
+ \sum_i w_i f_i(\tilde{q}_i) \left( \frac{u_i - u}{h} (r_{il} + x_{i,A^c}(\zeta^*_l(u_i) - \zeta^*_l(u))) \cdot \overline{x}_{i,A^c}^j \right)^2
\]

\[
+ \sum_i w_i f_i(\tilde{q}_i) \left( \frac{u_i - u}{h} (r_{il} + x_{i,A^c}(\zeta^*_l(u_i) - \zeta^*_l(u))) \cdot \overline{x}_{i,A^c}^j \right)^{-1/2}
\]

\[
= O(\epsilon_r + h) \leq \lambda^*.
\]

we have that Assumption 5 holds.
| $\epsilon$ distribution | $(R^2_x, R^2_y)$ | Method       | Bias   | SD      | ESE      | CR   |
|-------------------------|-----------------|-------------|--------|---------|---------|------|
| Normal                  | $(0.3, 0.3)$    | One Step    | -0.007 | 0.081   | 0.080   | 0.94 |
|                         |                 | Decorrelated score | 0.003 | 0.077   | 0.092   | 0.98 |
|                         |                 | Reparameterization | 0.011 | 0.081   | 0.080   | 0.94 |
|                         |                 | Naive       | 0.017  | 0.089   | 0.090   | 0.96 |
|                         |                 | Oracle      | -0.012 | 0.075   | 0.091   | 0.97 |
|                         | $(0.3, 0.7)$    | One Step    | -0.029 | 0.179   | 0.188   | 0.96 |
|                         |                 | Decorrelated score | 0.05  | 0.090   | 0.110   | 0.97 |
|                         |                 | Reparameterization | 0.05  | 0.088   | 0.095   | 0.93 |
|                         |                 | Naive       | 0.260  | 0.215   | 0.095   | 0.47 |
|                         |                 | Oracle      | -0.012 | 0.076   | 0.091   | 0.97 |
|                         | $(0.7, 0.7)$    | One Step    | 0.008  | 0.132   | 0.139   | 0.96 |
|                         |                 | Decorrelated score | 0.010 | 0.130   | 0.145   | 0.96 |
|                         |                 | Reparameterization | 0.008 | 0.130   | 0.139   | 0.94 |
|                         |                 | Naive       | 0.008  | 0.130   | 0.148   | 0.98 |
|                         |                 | Oracle      | -0.010 | 0.098   | 0.119   | 0.97 |
| $t(3)$                  | $(0.3, 0.3)$    | One Step    | -0.007 | 0.118   | 0.126   | 0.96 |
|                         |                 | Decorrelated score | 0.016 | 0.112   | 0.145   | 0.97 |
|                         |                 | Reparameterization | 0.024 | 0.102   | 0.126   | 0.95 |
|                         |                 | Naive       | 0.066  | 0.163   | 0.125   | 0.90 |
|                         |                 | Oracle      | -0.010 | 0.100   | 0.119   | 0.97 |
|                         | $(0.3, 0.7)$    | One Step    | -0.027 | 0.382   | 0.441   | 0.95 |
|                         |                 | Decorrelated score | 0.032 | 0.328   | 0.454   | 0.95 |
|                         |                 | Reparameterization | 0.031 | 0.302   | 0.441   | 0.97 |
|                         |                 | Naive       | 0.045  | 0.314   | 0.318   | 0.93 |
|                         |                 | Oracle      | 0.001  | 0.211   | 0.268   | 0.98 |

Table 2: Simulation results with data settings varying $(R^2_x, R^2_y)$ with heterogeneous $\epsilon$ (i.e. $\gamma = 1$).