Asynchronous Extensions of HyperLTL

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Abstract—Hyperproperties are a modern specification paradigm that extends trace properties to express properties of sets of traces. Temporal logics for hyperproperties studied in the literature, including HyperLTL, assume a synchronous semantics and enjoy a decidable model checking problem. In this paper, we introduce two asynchronous and orthogonal extensions of HyperLTL, namely Stuttering HyperLTL (HyperLTL$_{S}$) and Context HyperLTL (HyperLTL$_{C}$). Both of these extensions are useful, for instance, to formulate asynchronous variants of information-flow security properties. We show that for these logics, model checking is in general undecidable. On the positive side, for each of them, we identify a fragment with a decidable model checking that subsumes HyperLTL and that can express meaningful asynchronous requirements. Moreover, we provide the exact computational complexity of model checking for these two fragments which, for the HyperLTL$_{S}$ fragment, coincides with that of the strictly less expressive logic HyperLTL.

I. INTRODUCTION

Model checking is a well-established formal method technique to automatically check for global correctness of finite-state systems [1], [2]. Properties for model checking are usually specified in classic regular temporal logics such as LTL, CTL, and CTL$^*$ [3], [4], which provide temporal modalities for describing the ordering of events along individual execution traces of a system (trace properties). These logics lack mechanisms to relate distinct traces, which is required to express important information-flow security policies. Examples include properties that compare observations made by an external low-security agent along traces resulting from different values of not directly observable inputs. These security requirements go, in general, beyond regular properties.

In the last decade, a novel specification paradigm has been introduced that generalizes traditional regular trace properties by properties of sets of traces, the so-called hyperproperties [5]. Hyperproperties relate distinct traces and are useful to formalize information-flow security policies like noninterference [6], [7] and observational determinism [8]. Hyperproperties also have applications in other settings, such as the symmetric access to critical resources in distributed protocols [9]. Many temporal logics for hyperproperties have been proposed in the literature [10]–[16] for which model checking is decidable, including HyperLTL [11], HyperCTL$^*$ [11], HyperQPTL [13], [15], and HyperPDL$-\Delta$ [16] which extend LTL, CTL$^*$, QPTL [17], and PDL [18], respectively, by explicit first-order quantification over traces and trace variables to refer to multiple traces at the same time.

In all these logics, the mechanism for comparing distinct traces is synchronous and consists in evaluating the temporal modalities by a lockstepwise traversal of all the traces assigned to the quantified trace variables. This represents a limitation in various scenarios [19], [20] where properties of interest are instead asynchronous, since these properties require to relate traces at distinct time points which can be arbitrarily far from each other. Recently, two powerful and expressively equivalent formalisms have been introduced [20] for specifying asynchronous linear-time hyperproperties. The first one, called $H_{\mu}$, is based on a fixpoint calculus, while the second one exploits parity multi-tape Alternating Word Automata (AAWA) [20] for expressing the quantifier-free part of a specification. AAWA allow to specify very expressive non-regular multi-trace properties. As a matter of fact, model checking against $H_{\mu}$ or its AAWA-based counterpart is undecidable even for the (quantifier) alternation-free fragment. In [20], two decidable subclasses of parity AAWA are identified which lead to $H_{\mu}$ fragments with decidable model checking. Both subclasses express only $\omega$-regular languages over the synchronous product of tuples of traces with fixed arity. In particular, the first subclass captures all the multi-trace regular properties and the corresponding $H_{\mu}$ fragment (the so called $k$-synchronous fragment for a given $k \geq 1$) is strictly more expressive than HyperLTL, while the second subclass is non-elementarily more succinct than the first subclass and leads to a $H_{\mu}$ fragment which seems expressively incomparable with HyperLTL.

Our contribution: In this paper, we introduce two novel expressive extensions of HyperLTL for the specification of asynchronous linear-time hyperproperties, obtained by adding intuitive logical features that provide natural modeling facilities. The first formalism, that we call Stuttering HyperLTL (HyperLTL$_{S}$), is useful in information-flow security settings where an observer is not time-sensitive, i.e. the observer cannot distinguish consecutive time points along an execution having the same observation. This requires asynchronously matching sequences of observations along distinct execution traces. The novel feature of HyperLTL$_{S}$ consists in temporal modalities parameterized by finite sets $\Gamma$ of LTL formulas. These modalities are evaluated along sub-traces of the given traces which are obtained by removing “redundant” positions with respect to the pointwise evaluation of the LTL formulas.
in \( \Gamma \). We show that model checking against the alternation-free fragment of HyperLTL\(_S\) is already undecidable. On the positive side, we identify a meaningful fragment, called \textit{simple HyperLTL}\(_S\), with a decidable model-checking problem, which strictly subsumes HyperLTL and allows to express asynchronous variants of relevant security properties such as noninterference \([6]\) and observational determinism \([8]\). Moreover, model checking against simple HyperLTL\(_S\) has the same computational complexity as model checking for HyperLTL and is expressively incomparable with the two \(H\) fragments previously described. In particular, unlike these two fragments and HyperLTL, quantifier-free formulas of simple HyperLTL\(_S\) can express some non-regular multi-trace properties.

The second logic that we introduce, called \textit{Context HyperLTL} (HyperLTL\(_C\)), allows to specify complex combinations of asynchronous and synchronous requirements. HyperLTL\(_C\) extends HyperLTL by unary modalities parameterized by a non-empty subset \(C\) of trace variables (context) which restrict the evaluation of the temporal modalities to the traces associated with the variables in \(C\). Like HyperLTL\(_S\), model checking against HyperLTL\(_C\) is undecidable. In this case we exhibit a fragment of HyperLTL\(_C\) which is, in a certain sense, maximal with respect to the decidability of model checking, and extends HyperLTL by allowing the comparison of different traces at time points of bounded distance. This fragment is subsumed by \(k\)-synchronous \(H\), and we establish that for a fixed quantifier alternation depth, model checking this fragment is exponentially harder than model checking HyperLTL.

With regard to expressiveness issues, both HyperLTL\(_C\) and HyperLTL\(_S\) are subsumed by \(H\). On the other hand, questions concerning the comparison of the expressive power of HyperLTL\(_S\) and HyperLTL\(_C\) are left open: we conjecture that (simple) HyperLTL\(_S\) and HyperLTL\(_C\) are expressively incomparable.

\textbf{Related work:} Another linear-time temporal logic, called asynchronous HyperLTL (AHyperLTL), for pure asynchronous hyperproperties and useful for asynchronous security analysis has been recently introduced in \([21]\). This logic, which is expressively incomparable with HyperLTL, adds an additional quantification layer over the so called trajectory variables. Intuitively, a \textit{trajectory} describes an asynchronous interleaving of the traces in the current multi-trace where single steps of distinct traces can overlap, and temporal modalities, indexed by trajectory variables, are evaluated along the associated trajectories. The logic has an undecidable model-checking problem, but \([21]\) identifies practical fragments with decidable model-checking, and reports an empirical evaluation.

Other known logics for linear-time hyperproperties are the first-order logic with equal-level predicate FOL\([<,\leq]\) \([22]\) and its monadic second-order extension S1S[\(E\)] \([13]\). We conjecture that these logics are expressively incomparable with \(H\), HyperLTL\(_C\), and HyperLTL\(_S\). For instance, we believe that S1S[\(E\)] cannot express counting properties requiring that two segments along two different traces at an unbounded distance from each other have the same length. This kind of requirements can be instead expressed in HyperLTL\(_C\) and \(H\).

Proving these conjectures are left for future work.

\section{Preliminaries}

Given \(i,j \in \mathbb{N}\), we use \([i,j]\) for the set of natural numbers \(h\) such that \(i \leq h \leq j\), \([i,j)\) for the set of natural numbers \(h\) such that \(i \leq h < j\), and by \([i,\infty)\) the set of natural numbers \(h\) such that \(h \geq i\).

We fix a \textit{finite} set \(AP\) of atomic propositions. A \textit{trace} is an infinite word over \(2^{AP}\). A \textit{pointed trace} is a pair \((\pi,i)\) consisting of a trace \(\pi\) and a position \(i \in \mathbb{N}\) along \(\pi\).

For a word \(w\) over some alphabet \(\Sigma\), \(|w|\) is the length of \(w\) (\(|w| = \infty\) if \(w\) is infinite), for each \(0 \leq i < |w|\), \(w(i)\) is the \((i+1)\)\textsuperscript{th} symbol of \(w\), and \(w^i\) is the suffix of \(w\) from position \(i\), i.e., the word \(w(i)w(i+1)\ldots\)

Given \(n,h \in \mathbb{N}\) and integer constants \(c > 1\), \(Tower_c(h,n)\) denotes a tower of exponentials of base \(c\), \(h\), and argument \(n\): \(Tower_c(0,n) = n\) and \(Tower_c(h+1,n) = c^{Tower_c(h,n)}\). For each \(h \in \mathbb{N}\), we denote by \(h\)-\textsc{ExpSpace} the class of languages decided by deterministic Turing machines bounded in space by functions of \(n\) in \(O(Tower_c(h,n^h))\) for some integer constants \(c > 1\) and \(d \geq 1\). Note that \(0\)-\textsc{ExpSpace} coincides with \(\textsc{Pspace}\).

\subsection{Linear-time Temporal Logic (LTL)}

We recall syntax and semantics of LTL \([3]\). Formulas \(\theta\) of LTL over the set \(AP\) of atomic propositions are defined as follows:

\[
\theta ::= p | \neg \theta | \theta \land \theta | X\theta | \theta U \theta
\]

where \(p \in AP\) and \(X\) and \(U\) are the “next” and “until” temporal modalities respectively. The logic is interpreted over pointed traces \((\pi,i)\). The satisfaction relation \((\pi,i) \models \theta\), meaning that formula \(\theta\) holds at position \(i\) along \(\pi\), is inductively defined as follows (we omit the semantics for the Boolean connectives which standard):

\[
(\pi,i) \models p \iff p \in \pi(i)
\]
\[
(\pi,i) \models X\theta \iff (\pi,i+1) \models \theta
\]
\[
(\pi,i) \models \theta_1 U \theta_2 \iff \text{for some } j \geq i : (\pi,j) \models \theta_2 \text{ and } (\pi,k) \models \theta_1 \text{ for all } i \leq k < j
\]

A trace \(\pi\) is a model of \(\theta\), written \(\pi \models \theta\), if \((\pi,0) \models \theta\).

\subsection{Linear-time Hyper Specifications}

In this section, we consider an abstract notion of linear-time hyper specifications which are interpreted over sets of traces. For the rest of the discussion, we fix an ordered set \(\text{VAR}\) of trace variables.

A \textit{pointed trace assignment} \(\Pi\) is a partial mapping over \(\text{VAR}\), assigning to each trace variable \(x\) in its domain \(\text{Dom}(\Pi)\) a pointed trace. The assignment \(\Pi\) is initial if for each \(x \in \text{Dom}(\Pi)\), \(\Pi(x)\) is of the form \((\pi,0)\) for some trace \(\pi\). For a trace variable \(x \in \text{VAR}\) and a pointed trace \((\pi,i)\), we denote by \(\Pi[x \mapsto (\pi,i)]\) the pointed trace assignment having domain \(\text{Dom}(\Pi) \cup \{x\}\) that behaves as \(\Pi\) on the variables in \(\text{Dom}(\Pi) \setminus \{x\}\) and assigns to \(x\) the pointed trace \((\pi,i)\).
A multi-trace specification $S(x_1, \ldots , x_n)$ is a specification (in some formalism) parameterized by a subset \( \{x_1, \ldots , x_n\} \) of VAR whose semantics is represented by a set $\mathbb{T}$ of pointed trace assignments with domain $\{x_1, \ldots , x_n\}$. Depending on the given formalism, one can restrict to consider only initial pointed trace assignments. We write $\Pi \models S(x_1, \ldots , x_n)$ for the trace assignments $\Pi$ in $\mathbb{T}$.

Given a class $C$ of multi-trace specifications, linear-time hyper expressions $\xi$ over $C$ are defined as follows:

\[
\xi := \exists x, \xi \mid \forall x, \xi \mid S(x_1, \ldots , x_n) \]

where $x, x_1, \ldots , x_n \in VAR$, $S(x_1, \ldots , x_n)$ is a multi-trace specification in the class $C$, $\exists x$ is the hyper existential trace quantifier for variable $x$, and $\forall x$ the hyper universal trace quantifier for $x$. Informally, the expression $\exists x, \xi$ requires that for some trace $\pi$ in the given set of traces, $\xi$ holds when $x$ is mapped to $(\pi, 0)$, while $\forall x, \xi$ requires that all traces $\pi, \xi$ holds when $x$ is mapped to $(\pi, 0)$. We say that an expression $\xi$ is a sentence if every variable $x_i$ in the multi-trace specification $S(x_1, \ldots , x_n)$ of $\xi$ is in the scope of a quantifier for the trace variable $x_i$, and distinct occurrences of quantifiers are associated with distinct trace variables. The quantifier alternation depth of $\xi$ is the number of switches between $\exists$ and $\forall$ quantifiers in the quantifier prefix of $\xi$.

For instance, HyperLTL sentences \([11]\) are linear-time hyper sentences over the class of multi-trace specifications obtained by LTL formulas by replacing atomic propositions $p$ with relativized versions $p[x]$, where $x \in VAR$. Intuitively, $p[x]$ asserts that $p$ holds at the pointed trace assigned to $x$.

Given a linear-time expression $\xi$ with multi-trace specification $S(x_1, \ldots , x_n)$, a set $\mathcal{L}$ of traces, and an initial pointed trace assignment $\Pi$ such that $Dom(\Pi)$ contains the variables in $\{x_1, \ldots , x_n\}$ which are not in the scope of a quantifier, and the traces referenced by $\Pi$ are in $\mathcal{L}$, the satisfaction relation $(\mathcal{L}, \Pi) \models \xi$ is inductively defined as follows:

\[
(\mathcal{L}, \Pi) \models \exists x, \xi \iff \text{for some trace } \pi \in \mathcal{L} : (\mathcal{L}, \Pi[x \mapsto (\pi, 0)]) \models \xi \\
(\mathcal{L}, \Pi) \models \forall x, \xi \iff \text{for each trace } \pi \in \mathcal{L} : (\mathcal{L}, \Pi[x \mapsto (\pi, 0)]) \models \xi \\
(\mathcal{L}, \Pi) \models S(x_1, \ldots , x_n) \iff \Pi \models S(x_1, \ldots , x_n)
\]

If $\xi$ is a sentence, we write $\mathcal{L} \models \xi$ to mean that $(\mathcal{L}, \Pi_0) \models \xi$, where $\Pi_0$ is the empty assignment.

C. Kripke Structures and Asynchronous Word Automata

Kripke structures. A Kripke structure (over AP) is a tuple $K = (S, S_0, E, V)$, where $S$ is a set of states, $S_0 \subseteq S$ is the set of initial states, $E \subseteq S \times S$ is a transition relation which is total in the first argument (i.e. for each $s \in S$ there is a $t \in S$ with $(s, t) \in E$), and $V : S \to 2^{AP}$ is an AP-valuation assigning to each state $s$ the set of propositions holding at $s$. The Kripke structure $K$ is finite if $S$ is finite.

A path $\nu = t_0, t_1, \ldots$ of $K$ is an infinite word over $S$ such that $t_0 \in S_0$ is an initial state and for all $i \geq 0$, $(t_i, t_{i+1}) \in E$. The path $\nu = t_0, t_1, \ldots$ induces the trace $V(t_0) V(t_1) \ldots$. A finite path of $K$ is a non-empty finite infix of some path of $K$. A trace of $K$ is a trace induced by some path of $K$. We denote by $L(K)$ the set of traces of $K$. We also consider fair finite Kripke structures $(K, F)$, that is, finite Kripke structures $K$ equipped with a subset $F$ of $K$-states. A path $\nu$ of $K$ is $F$-fair if $\nu$ visits infinitely many times states in $F$. We denote by $L(K, F)$ the set of traces of $K$ associated with the $F$-fair paths of $K$. We consider the following decision problems for a given class $C$ of multi-trace specifications:

- **Model checking problem:** checking for a given finite Kripke structure $K$ and a linear-time hyper sentence $\xi$ over $C$, whether $L(K) \models \xi$ (we also write $K \models \xi$).
- **Fair model checking problem:** checking for a given fair finite Kripke structure $(K, F)$ and a linear-time hyper sentence $\xi$ over $C$, whether $L(K, F) \models \xi$.

Note that model checking reduces to fair model checking for the special case where $F$ coincides with the set of $K$-states.

Labeled Trees. A tree $T$ is a prefix closed subset of $\mathbb{N}^*$. Elements of $T$ are called nodes and the empty word $\varepsilon$ is the root of $T$. For $x \in T$, a child of $x$ in $T$ is a node of the form $x \cdot n$ for some $n \in \mathbb{N}$. A path of $T$ is a maximal sequence $\pi$ of nodes such that $\pi(0) = \varepsilon$ and $\pi(i)$ is a child in $T$ of $\pi(i-1)$ for all $0 < i < |\pi|$. For an alphabet $\Sigma$, a $\Sigma$-labeled tree is a pair $(T, Lab)$ consisting of a tree and a labelling $Lab : T \to \Sigma$ assigning to each node in $T$ a symbol in $\Sigma$.

Asynchronous Word Automata. We consider a variant of the framework of alternating asynchronous word automata introduced in [20], a class of finite-state automata for the asynchronous traversal of multiple infinite words. Given a set $X$, $\mathbb{B}^+(X)$ denotes the set of positive Boolean formulas over $X$, that is, Boolean formulas built from elements in $X$ using $\lor$ and $\land$ (we also allow the formulas true and false). Let $n \geq 1$. A Büchi nAAWA over a finite alphabet $\Sigma$ is a tuple $\mathcal{A} = (\Sigma, q_0, Q, \rho, F)$, where $Q$ is a finite set of (control) states, $q_0 \in Q$ is the initial state, $\rho : Q \times \Sigma^n \to \mathbb{B}^+(Q \times \{1, n\})$ is the transition function, and $F \subseteq Q$ is a set of accepting states. Intuitively, an nAAWA has access to $n$ infinite input words over $\Sigma$ and at each step, it activates multiple copies. For each copy, there is exactly one input word whose current input symbol is consumed, so the reading head of such word moves one position to the right.

In particular, the target of a move of $\mathcal{A}$ is encoded by a pair $(q, i) \in A \times [1, n]$, where $q$ indicates the target state while the direction $i$ indicates on which input word to progress.

Formally, a run of $\mathcal{A}$ over an $n$-tuple $w = (w_1, \ldots , w_n)$ of infinite words over $\Sigma$ is a $(Q \times X^n)$-labeled tree $r = (T_r, Lab_r)$, where each node of $T_r$ labelled by $(q, \varphi)$ with $\varphi = (i_1, \ldots , i_n)$ describes a copy of the automaton that is in state $q$ and reads the $(i_h + 1)^{th}$ symbol of the input word $w_h$ for each $h \in [1, n]$. Moreover, we require that

- $r(\varepsilon) = (q_0, (0, \ldots , 0))$, that is, initially, the automaton is in state $q_0$ reading the first position of each input word;
- for each $r \in T_r$ with $Lab_r(r) = (q, (i_1, \ldots , i_n))$, there is a (possibly empty) set $\{ (q_1, d_1), \ldots , (q_k, d_k) \} \subseteq Q \times \{1, n\}$ for some $k \geq 0$ satisfying $\delta(q, (w_1(i_1), \ldots , w_n(i_n)))$ such that $r$ has $k$ children
\[ \tau_1, \ldots, \tau_k \text{ and } Lab_r(\tau_j) = (q_j, (i_1, \ldots, i_{d_j} + 1, \ldots, i_n)) \]

for all \( 1 \leq j \leq k \).

The run \( r \) is accepting if each infinite path \( \nu \) visits infinitely often nodes labeled by some accepting state in \( F \). We denote by \( \mathcal{L}(A) \) the set of \( n \)-tuples \( \overrightarrow{\nu} \) of infinite words over \( \Sigma \) such that there is an accepting run of \( A \) over \( \overrightarrow{\nu} \).

For each \( k \geq 1 \), we also consider \( k \)-synchronous Büchi \( n \)LTL-AWA \((\text{20})\), which is a Büchi \( n \)LTL-AWA such that for each run \( r \) and for each node of \( r \) with label \( (q, \overrightarrow{\nu}) \), the position vector \( \overrightarrow{\nu} = (i_1, \ldots, i_n) \) satisfies \( |i_\ell - i_\ell'| \leq k \) for all \( \ell, \ell' \in [1, k] \). Intuitively, a \( k \)-synchronous \( n \)LTL-AWA cannot be ahead more than \( k \) steps in one direction with respect to the others. Note that \( n \)LTL-AWA over \( 2^{AP} \) can be seen as multi-trace specifications. It is known \((\text{20})\) that model checking against linear-time hyper sentences over Büchi \( n \)LTL-AWA is undecidable, and the problem becomes decidable when one restricts to consider \( k \)-synchronous Büchi \( n \)LTL-AWA. In particular, the following holds.

**Proposition II.1** (\(\text{[20]}\)). Let \( d \in \mathbb{N} \). The (fair) model checking problem against linear-time hyper sentences of quantifier alternation depth \( d \) over the class of \( k \)-synchronous Büchi \( n \)LTL-AWA over \( 2^{AP} \) \((k, n, AP \text{ being input parameters of the problem instances})\) is \((d + 1)\)-EXPSPACE-complete, and for a fixed formula, it is \((d - 1)\)-EXPSPACE-complete for \( d > 0 \) and NLOGSPACE-complete otherwise.

### III. STUTTERING HYPERLTL

In this section we introduce an asynchronous extension of HyperLTL that we call stuttering HyperLTL (HyperLTL-S for short). Stuttering HyperLTL is obtained by exploiting relativized versions of the temporal modalities with respect to finite sets \( \Gamma \) of LTL formulas. Intuitively, these modalities are evaluated along sub-traces of the given traces which are obtained by removing “redundant” positions with respect to the pointwise evaluation of the LTL formulas in \( \Gamma \). The rest of this section is organized as follows. In Subsection III-A we introduce a generalization of the classical notion of stuttering. Then, in Subsection III-B we define the syntax and semantics of HyperLTL-S and provide some examples of specifications in this novel logic. Finally, we investigate the model checking problem against HyperLTL-S. In Subsection III-C we show that the problem is in general undecidable, and in Subsection III-D we identify a meaningful fragment of HyperLTL-S for which model checking is shown to be decidable.

#### A. LTL-Relativized Stuttering

Classically, a trace is stutter-free if there are no consecutive positions having the same propositional valuation unless the valuation is repeated ad-infinitum. We can associate to each trace a unique stutter-free trace by removing “redundant” positions. In this subsection, we generalize these notions with respect to the pointwise evaluation of a finite set of LTL formulas.

**Definition III.1** (LTL stutter factorization). Let \( \Gamma \) be a finite set of LTL formulas and \( \pi \) a trace. The \( \Gamma \)-stutter factorization of \( \pi \) is the unique increasing sequence of positions \( \{i_k\}_{k \in [0, m_\infty]} \) for some \( m_\infty \in \mathbb{N} \cup \{\infty\} \) such that the following holds for all \( j < m_\infty \):

- \( i_0 = 0 \) and \( i_j < i_{j+1} \);
- for each \( \theta \in \Gamma \), the truth value of \( \theta \) along the segment \( [i_j, i_{j+1}] \) does not change, i.e. for all \( h, k \in [i_j, i_{j+1}] \), \( (\pi, h) \models \theta \iff (\pi, k) \models \theta \), and the same holds for the infinite segment \([m_\infty, \infty)\) in case \( m_\infty \neq \infty \);
- the truth value of some formula in \( \Gamma \) changes along adjacent segments, i.e. for some \( \theta \in \Gamma \) (depending on \( j \)), \( (\pi, i_j) \models \theta \iff (\pi, i_{j+1}) \not\models \theta \).

Thus, the \( \Gamma \)-stutter trace \( \{i_k\}_{k \in [0, m_\infty]} \) of \( \pi \) partitions the trace in adjacent non-empty segments such that the valuation of formulas in \( \Gamma \) does not change within a segment, and changes in moving from a segment to the adjacent ones. This factorization induces in a natural way a trace obtained by selecting the first positions of the finite segments and all the positions of the unique infinite segment, if any. Formally, the \( \Gamma \)-stutter trace of \( \pi \), denoted by \( \text{stfr}_\Gamma(\pi) \), is defined as follows:

- \( \text{stfr}_\Gamma(\pi) \mid definition of \( \text{stfr}_\Gamma(\pi) \) is defined as follows:

\[
\text{stfr}_\Gamma(\pi) \defeq (\pi(0))_{i \in \mathbb{N}} \ldots \pi(i_{m_\infty-1}) \cdot \pi^{m_\infty} \text{ if } m_\infty \neq \infty.
\]

As an example, assume that \( AP = \{p, q, r\} \) and let \( \Gamma = \{p \cup q\} \). Given \( h, k \geq 1 \), let \( \pi_{h,k} \) be the trace \( \pi_{h,k} = p^h q^k \cdot r^\omega \). All these traces have the same \( \Gamma \)-stutter trace which is given by \( p^\omega \). This is because for \( p \cup q \) is true for \( p^h q^k r^\omega \) and \( q^k r^\omega \) (for all \( h \) and \( k \)) and false for \( r^\omega \). Therefore, there are two change points which are the initial position (with valuation \( p \)) and the first \( r \) position.

We say that a trace \( \pi \) is \( \Gamma \)-stutter free if it coincides with its \( \Gamma \)-stutter trace, i.e. \( \text{stfr}_\Gamma(\pi) = \pi \). Note that if \( \Gamma = \emptyset \), each trace is \( \emptyset \)-stutter free, i.e. \( \text{stfr}_\emptyset(\pi) = \pi \).

For each finite set \( \Gamma \) of LTL formulas, we define the successor function \( \text{succ}_\Gamma \) as follows. The function maps a pointed trace \( (\pi, i) \) to the trace \( (\pi, \ell) \) where \( \ell \) is the first position of the segment in the \( \Gamma \)-stutter factorization of \( \pi \) following the \( i \)-segment (if the \( i \)-segment is not the last one). If the segment is the last one then \( \ell = i + 1 \). Formally,

**Definition III.2** (Relativized Successor). Let \( \Gamma \) be a finite set of LTL formulas, \( \pi \) a trace with \( \Gamma \)-stutter factorization \( \{i_k\}_{k \in [0, m_\infty]} \) and \( i \geq 0 \). The \( \Gamma \)-successor of the pointed trace \( (\pi, i) \), denoted by \( \text{succ}_\Gamma(\pi, i) \), is the trace \( (\pi, \ell) \) where position \( \ell \) is defined as follows: if there is \( j < m_\infty \) such that \( i \in [i_j, i_{j+1} - 1] \), then \( \ell = i_{j+1} \); otherwise (note that in this case \( m_\infty \neq \infty \) and \( i \geq i_{m_\infty} \)), \( \ell = i + 1 \).

#### B. Syntax and Semantics of Stuttering HyperLTL (HyperLTL-S)

HyperLTL-S formulas over the given finite set \( AP \) of atomic propositions and finite set \( VAR \) of trace variables are linear-time hyper expressions over multi-trace specifications \( \psi \), called HyperLTL-S quantifier-free formulas, where \( \psi \) is defined by the following syntax:

\[
\psi ::= T \mid p[x] \mid \neg \psi \mid \psi \land \psi \mid X_\Gamma \psi \mid \psi U_\Gamma \psi
\]
where \( p \in \text{AP}, \ x \in \text{VAR} \), \( \Gamma \) is a finite set of LTL formulas over \( \text{AP} \), and \( X_{\Gamma} \) and \( U_{\Gamma} \) are the stutter-relativized versions of the LTL temporal modalities.

When \( \Gamma \) is empty, we omit the subscript \( \Gamma \) in the temporal modalities. Informally, \( p[x] \) asserts that \( p \) holds at the pointed trace assigned to \( x \), while the relativized temporal modalities \( X_{\Gamma} \) and \( U_{\Gamma} \) are evaluated by a lockstepwise traversal of the \( \Gamma \)-stutter traces associated with the currently quantified traces. We also exploit the standard logical connectives \( \lor \) (disjunction) and \( \rightarrow \) (implication) as abbreviations, and the relativized eventually modality \( F_{\Gamma} \psi \stackrel{\text{def}}{=} \top \land U_{\Gamma} \psi \) and its dual \( G_{\Gamma} \psi \stackrel{\text{def}}{=} \neg F_{\Gamma} \neg \psi \) (relativized always). The size \( |\xi| \) of a HyperLTL\(_S\) (quantifier-free) formula \( \xi \) is the number of distinct sub-formulas of \( \xi \) plus the number of distinct sub-formulas of those LTL formulas occurring in the subscripts of the temporal modalities.

For each finite set \( \Gamma \) of LTL formulas, we denote by HyperLTL\(_S[\Gamma]\) the syntactical fragment of HyperLTL\(_S\) where the subscripts of each temporal modality is \( \Gamma \). Note that standard HyperLTL corresponds to the fragment HyperLTL\(_S[\emptyset]\).

In the following, for each HyperLTL\(_S\) formula \( \varphi \), we denote by HyperLTL\(_S\)(\( \varphi \)) the HyperLTL\(_S\) formula obtained from \( \varphi \) by replacing each relativized temporal modality in \( \varphi \) with its \( \emptyset \)-relativized version.

**Semantics of HyperLTL\(_S\) Quantifier-free Formulas.** Given a finite set \( \Gamma \) of LTL formulas, we extend in a natural way the relativized successor function \( \text{succ}_\Gamma \) to pointed trace assignments \( \Pi \) as follows: the \( \Gamma \)-successor \( \text{succ}_\Gamma(\Pi) \) of \( \Pi \) is the pointed trace assignment with domain \( \text{Dom}(\Pi) \) associating to each \( x \in \text{Dom}(\Pi) \) the \( \Gamma \)-successor \( \text{succ}_\Gamma(\Pi(x)) \) of the pointed trace \( \Pi(x) \). For each \( j \in \mathbb{N} \), we use \( \text{succ}_\Gamma^j \) for the function obtained by \( j \) applications of the function \( \text{succ}_\Gamma \).

Given a HyperLTL\(_S\) quantifier-free formula \( \psi \) and a pointed trace assignment \( \Pi \) such that \( \text{Dom}(\Pi) \) contains the trace variables occurring in \( \psi \), the satisfaction relation \( \Pi \models \psi \) is inductively defined as follows (we omit the semantics of the Boolean connectives which is standard):

\[
\begin{align*}
\Pi \models p[x] & \iff \Pi(x) = (\pi, i) \text{ and } p \in \pi(i) \\
\Pi \models X_{\Gamma} \psi & \iff \text{succ}_\Gamma(\Pi) \models \psi \\
\Pi \models \psi_1 U_{\Gamma} \psi_2 & \iff \text{for some } i \geq 0 : \text{succ}_\Gamma^i(\Pi) \models \psi_2 \text{ and } \text{succ}_\Gamma^{i+1}(\Pi) \models \psi_1 \text{ for all } 0 \leq k < i
\end{align*}
\]

In the following, given a set \( \Gamma \) of LTL formulas, we also consider the model checking problem against the fragment HyperLTL\(_S[\Gamma]\) of HyperLTL\(_S\). For this fragment, by the semantics of HyperLTL\(_S\), we deduce the following fact, where for a set \( L \) of traces, \( \text{stfr}_\Gamma(L) \) denotes the set of \( \Gamma \)-stutter traces over the traces in \( L \), i.e. \( \text{stfr}_\Gamma(L) \stackrel{\text{def}}{=} \{ \text{stfr}_\Gamma(\pi) \mid \pi \in L \} \).

**Remark III.1.** A set \( L \) of traces is a model of a HyperLTL\(_S[\Gamma]\) sentence \( \varphi \) if and only if \( \text{stfr}_\Gamma(L) \) is a model of the HyperLTL sentence HyperLTL\(_S\)(\( \varphi \)).

Let LTL\(_S\) be the extension of LTL obtained by adding the stutter-relativized versions of the LTL temporal modalities. Note that LTL\(_S\) formulas correspond to one-variable HyperLTL\(_S\) quantifier-free formulas. We can show that LTL\(_S\) has the same expressiveness as LTL, as established by the following Proposition III.1 (missing proofs of all the claims in this paper can be found in the Appendix). On the other hand, HyperLTL\(_S\) quantifier-free formulas are in general more expressive than HyperLTL quantifier-free formulas. In particular, while model checking HyperLTL is known to be decidable \([11]\), model checking the alternation-free fragment of HyperLTL\(_S\) is already undecidable (see Subsection III-C).

**Proposition III.1.** Given a LTL\(_S\) formula, one can construct in polynomial time an equivalent LTL formula.

We now show that HyperLTL\(_S\) is strictly less expressive than the fixpoint calculus H\(_\mu\) introduced in \([20]\). Indeed, H\(_\mu\) cannot be embedded into HyperLTL\(_S\) since for singleton trace sets, H\(_\mu\) characterizes the class of \( \omega \)-regular languages, while HyperLTL\(_S\) corresponds to LTL, which consequently, captures only a strict subclass of \( \omega \)-regular languages. Moreover, by the following result and the fact that parity A\(\text{W}A\) are equivalent to H\(_\mu\) quantifier-free formulas \([20]\), we obtain that HyperLTL\(_S\) is subsumed by H\(_\mu\).

**Proposition III.2.** Given a HyperLTL\(_S\) quantifier-free formula \( \psi \) with trace variables \( x_1, \ldots, x_n \), one can build in polynomial time a Buchi \( \text{w}A\) A\(\text{W}A\) such that \( L(\text{A}_\psi) \) is the set of \( n \)-tuples \( (\pi_1, \ldots, \pi_n) \) of traces so that \( (\{ x_1 \mapsto (\pi_1, 0), \ldots, x_1 \mapsto (\pi_n, 0) \}) \models \psi \).

**Proof.** By exploiting the dual R\(_\Gamma\) (relativized release) of the until modality U\(_\Gamma\), we can assume without loss of generality that \( \psi \) is in negation normal form, so negation is applied only to relativized atomic propositions. Given a finite set \( \Gamma \) of LTL formulas, let \( \xi_\Gamma \) be the following LTL formula

\[
\xi_\Gamma = \bigwedge_{\xi \in \Gamma} G(\xi \leftrightarrow X\xi) \lor \bigvee_{\xi \in \Gamma} (\xi \leftrightarrow \neg X\xi)
\]

The LTL formula \( \xi_\Gamma \) has as models the traces \( \pi \) such that the first segment in the factorization of \( \pi \) is either infinite or has length 1. For each \( i \in [1, n] \), we can easily construct in linear time (in the number of distinct sub-formulas in \( \Gamma \)) a Büchi \( n\text{A}W\)A\(\text{w}A\) such that \( L(A_{\psi}) \) is the set of \( n \)-tuples \( (\pi_1, \ldots, \pi_n) \) of traces so that the \( i \)-th component \( \pi_i \) is a model of \( \xi_\Gamma \). Similarly, we can also define \( A_{\psi,i} \) accepting the \( n \)-tuples \( (\pi_1, \ldots, \pi_n) \) of traces so that the \( i \)-th component \( \pi_i \) is not a model of \( \xi_\Gamma \).

Let \( \Upsilon \) be the set of subscripts \( \Gamma \) occurring in the temporal modalities of \( \psi \). Then by exploiting the automata \( A_{\psi,i} \) and \( A_{\Upsilon,i} \) where \( \Gamma \in \Upsilon \) and \( i \in [1, n] \), we construct a Büchi \( n\text{A}W\)A\(\text{w}A\) satisfying Proposition III.2 as follows. Given an input multi-trace \( (\pi_1, \ldots, \pi_n) \), the behaviour of the automaton \( A_{\psi} \) is subdivided in phases. At the beginning of each phase with current position vector \( \varphi = (j_1, \ldots, j_n) \), \( A_{\psi} \) keeps track in its state of the currently processed sub-formula \( \theta \) of \( \psi \). By the transition function, \( \theta \) is processed in accordance with the ‘local’ characterization of the semantics of the Boolean connectives and the relativized temporal modalities. Whenever \( \theta \) is of the form \( \theta_1 U_{\Gamma} \theta_2 \) or \( \theta_1 R_{\Gamma} \theta_2 \), or \( \theta \) is argument of a sub-formula of the form \( X_{\Gamma} \theta \), and \( A_{\psi} \) has to check that \( \theta \)
holds at the position vector \((\text{succ}_{\theta}(\pi_1, j_1), \ldots, \text{succ}_{\theta}(\pi_1, j_1))\), \(A_{\varphi}\) moves along the directions \(1, \ldots, n\) in turns. During the movement along direction \(i \in [1, n]\), the automaton is in state \((\theta, i, \Gamma)\) and guesses that either (i) the next input position is in the current segment of the \(\Gamma\)-factorization of \(\pi_i\) and this segment is not the last one, or (ii) the previous condition does not hold, hence, the next input position corresponds to \(\text{succ}_{\theta}(\pi_1, j_1)\). In the first (resp., second case) case, it activates in parallel a copy of the auxiliary automaton \(A_{\Gamma_i}\) (resp., \(A_{\Gamma_j}\)) for checking that the guess is correct and moves one position to the right along \(\pi_i\). Moreover, in the first case, \(A_{\varphi}\) remains in state \((\theta, i, \Gamma)\), while in the second case, the automaton changes direction by moving to the state \((\theta, i+1, \Gamma)\) if \(i < n\), and starts a new phase by moving at state \(\theta\) otherwise.

**Examples of Specifications.** Stuttering HyperLTL can express relevant information-flow security properties for asynchronous frameworks such as distributed systems or cryptographic protocols. These properties specify how information may propagate from input to outputs by comparing distinct executions of a system possibly at different points of time. Assume that each user is classified either at a low security level, representing public information, or at a high level, representing secret information. Moreover, let \(LI\) be a set of propositions for describing inputs of low users, \(LO\) propositions that describe outputs of low users, and \(HI\) be a set of propositions for representing inputs of high users. As a first example, we consider the asynchronous variant of the noninterference property, as defined by Goguen and Meseguer [6], asserting that the observations of low users do not change when all high inputs are removed. In an asynchronous setting, a user cannot infer that a transition occurred if consecutive observations remain unchanged. In other terms, steps observed by a user do not correspond to the same number of steps in different executions of the system. Thus, since a low user can only observe the low output propositions, we require that for each trace \(\pi\), there is a trace \(\pi'\) with no high inputs such that the \(LO\)-stutter traces of \(\pi\) and \(\pi'\) coincide, that is, \(\pi\) and \(\pi'\) are indistinguishable to a low user. This can be expressed in HyperLTL as follows, where proposition \(p_\theta\) denotes absence of high input.

\[
\forall x. \exists y. G_{p_\theta}[y] \land G_{LO} \bigwedge_{p \in LO} (p[x] \leftrightarrow p[y])
\]

Assuming that the observations are not time-sensitive, noninterference cannot in general be expressed in HyperLTL unless one only considers systems where all the traces are \(LO\)-stutter free. Another relevant example is generalized noninterference as formulated in [7] which allows nondeterminism in the low-observable behavior and requires for all system traces \(\pi\) and \(\pi'\), the existence of an interleaved trace \(\pi''\) whose high inputs are the same as \(\pi\) and whose low outputs are the same as \(\pi'\). This property can be expressed in HyperLTL as follows:

\[
\forall x. \forall y. \exists z. G_{HI} \bigwedge_{p \in HI} (p[y] \leftrightarrow p[z]) \land G_{LO} \bigwedge_{p \in LO} (p[y] \leftrightarrow p[z])
\]

Another classical security policy is observational determinism specifying that traces which have the same initial low inputs are indistinguishable to a low user. The following HyperLTL formula captures observational determinism with equivalence of traces up to stuttering as formulated in [8].

\[
\forall x. \forall y. \bigwedge_{p \in LI} (p[x] \leftrightarrow p[y]) \rightarrow G_{LO} \bigwedge_{p \in LO} (p[x] \leftrightarrow p[y])
\]

Lastly, an interesting feature of HyperLTL is the possibility of combining asynchrony and synchrony constraints. We illustrate this ability by considering an unbounded time requirement which has application in the analysis of procedural software: “whenever a procedure \(A\) is invoked, the procedure terminates, but there is no bound on the running time of \(A\) that upper-bounds the duration of \(A\) on all traces”. In other words, for every candidate bound \(k\) there is a trace in which \(A\) is invoked and terminates with a longer duration. We assume, crucially, that procedure \(A\) can be activated at most once along an execution, and we let \(c_A\) characterize the call to \(A\) and \(r_A\) the return. This requirement can be expressed in HyperLTL as follows.

\[
\forall x. \exists y. F_{c_A}[x] \rightarrow \left( F_{c_A}[y] \land X_{c_A} \left( \neg r_A[x] \land \neg r_A[y] \right) \right)
\]

Essentially, we claim there is always a call to \(A\) that runs for a longer period of time than any candidate maximum duration. Note that the occurrence of the relativized until \(U_{c_A}\) in the previous formula can be equivalently replaced by the standard until \(U\). We have used the relativized until since the previous formula is in the fragment investigated in Subsection [II-D] below which enjoys a decidable model checking problem.

**C. Undecidability of Model Checking HyperLTL.**

In this section, we establish the following negative result.

**Theorem III.1.** The model checking problem for HyperLTL is undecidable even for the HyperLTL segment where the quantifier alternation depth is 0 and the stutter-relativized temporal modalities just use two sets of LTL-formulas where one is empty and the other one consists of atomic propositions only.

Theorem III.1 is proved by a reduction from the Post’s Correspondence Problem (PCP, for short) [23]. We fix an instance \(I\) of PCP which is a tuple

\[
I = (\langle u_1^1, \ldots, u_n^1 \rangle, \langle u_1^2, \ldots, u_n^2 \rangle)
\]

where \(n \geq 1\) and for each \(1 \leq i \leq n\), \(u_i^1\) and \(u_i^2\) are non-empty finite words over a finite alphabet \(\Sigma\). Let \(|n| = \{1, \ldots, n\}\). A solution of \(I\) is a non-empty sequence \(i_1, i_2, \ldots, i_k\) of integers in \(|n|\) such that \(u_{i_1}^1 \cdot u_{i_2}^1 \cdot \ldots \cdot u_{i_k}^1 = u_{i_1}^2 \cdot u_{i_2}^2 \cdot \ldots \cdot u_{i_k}^2\). PCP consists in checking for a given instance \(I\), whether \(I\) admits a solution. This problem is known to be undecidable [23].

**Assumption.** We assume without loss of generality that each word \(u_i^1\) of \(I\), where \(i \in |n|\) and \(\ell = 1, 2\), has length at least 2. Indeed, if this assumption does not hold, we consider the instance \(I'\) of PCP obtained from \(I\) by replacing each word.
of the form $a_1 \ldots a_n$ with the word $a_1 a_1 \ldots a_n a_n$ (i.e., we duplicate each symbol occurring in $u^i_\ell$). Evidently $I'$ has a solution if and only if $I$ has a solution.

In order to encode the PCP instance $I$ into an instance of the model checking problem for HyperLTL$_S$, we exploit the following set $\mathcal{AP}$ of atomic propositions, where $\#, p_1, \ldots, p_n, q_1, q_2$ are fresh symbols not in $\Sigma$.

\[
\mathcal{AP} \overset{\text{def}}{=} \Sigma \cup \{\#\} \cup \{p_1, \ldots, p_n\} \cup \{q_1, q_2\}
\]

Intuitively, for each $i \in [n]$ and $\ell = 1, 2$, propositions $p_i$ and $q_i$ are exploited to mark each symbol of the word $u^i_\ell$ of the instance $I$, while proposition $\#$ is used to mark only the last symbol of $u^i_\ell$. Thus, for the word $u^i_\ell$, we denote by $[u^i_\ell, p_i, q_i]$ the finite word over $2^{\mathcal{AP}}$ of length $|u^i_\ell|$ obtained from $u^i_\ell$ by marking each symbol of $u^i_\ell$ with propositions $p_i$ and $q_i$ and, additionally, by marking the last symbol of $u^i_\ell$ with proposition $\#$. Formally, $[u^i_\ell, p_i, q_i]$ is the finite word over $2^{\mathcal{AP}}$ having length $|u^i_\ell|$ such that for each $0 \leq h < |u^i_\ell|$, $[u^i_\ell, p_i, q_i](h) = \{u^i_\ell(h), p_i, q_i\}$ if $h < |u^i_\ell| - 1$, and $[u^i_\ell, p_i, q_i](h) = \{u^i_\ell(h), p_i, q_i, \#\}$ otherwise.

Given a non-empty sequence $i_1, i_2, \ldots, i_k$ of integers in $[n]$ and $\ell = 1, 2$, we encode the word $u^i_1 \cdot u^i_2 \cdot \cdots \cdot u^i_k$ by the trace, denoted by $\pi_{i_1, \ldots, i_k}^\ell$, defined as:

\[
\pi_{i_1, \ldots, i_k}^\ell \overset{\text{def}}{=} \{\#\} \cdot [u^i_1, p_{i_1}, q_{i_1}] \cdot \ldots \cdot [u^i_k, p_{i_k}, q_{i_k}] \cdot \{\#\}^\omega
\]

Let $\Gamma$ be the set of atomic propositions given by $\Gamma = \{\#, p_1, \ldots, p_n\}$. We crucially observe that since each word of $I$ has length at least 2, the projection of the $\Gamma$-stutter trace $stfr_{\Gamma}(\pi_{i_1, \ldots, i_k}^\ell)$ of $\pi_{i_1, \ldots, i_k}^\ell$ over $\pi_{i_1, \ldots, i_k}^\ell$ is given by:

\[
\{\#\} \cdot \{p_{i_1}\} \cdot \{\#\} \cdot \ldots \cdot \{p_{i_k}\} \cdot \{\#\} \cdot \{\#\}^\omega
\]

Hence, we obtain the following characterization of non-emptiness of the set of $\Gamma$’s solutions, where a well-formed trace is a trace of the form $\pi_{i_1, \ldots, i_k}^\ell$ for some non-empty sequence $i_1, i_2, \ldots, i_k$ of integers in $[n]$ and $\ell = 1, 2$.

**Proposition III.3.** $I$ has a solution if and only if there are two well-formed traces $\pi_1$ and $\pi_2$ satisfying the following conditions, where $\Gamma = \{\#, p_1, \ldots, p_n\}$:

1. for each $\ell = 1, 2$, $\pi_\ell$ does not contain occurrences of propositions $q_3, \ldots, q_9$, i.e., for each $h \in \mathbb{N}$, $q_3, \ldots, q_9 \notin \pi_\ell(h)$;
2. the projections of $\pi_1$ and $\pi_2$ over $\Sigma$ coincide, i.e., for each $h \in \mathbb{N}$ and $p \in \Sigma$, $p \in \pi_1(h)$ iff $p \in \pi_2(h)$;
3. the projections of $stfr_{\Gamma}(\pi_1)$ and $stfr_{\Gamma}(\pi_2)$ over $\Gamma$ coincide, i.e., for each $h \in \mathbb{N}$ and $p \in \Gamma$, $p \in stfr_{\Gamma}(\pi_1)(h)$ iff $p \in stfr_{\Gamma}(\pi_2)(h)$.

By exploiting Proposition III.3, we construct a finite Kripke structure $\mathcal{K}_I$ and a HyperLTL$_S$ sentence $\varphi_2$ over $\mathcal{AP}$ whose quantifier alternation depth is 0 and whose temporal modalities are parameterized either by the empty set or by $\Gamma = \{\#, p_1, \ldots, p_n\}$ such that $I$ has a solution if and only if $\mathcal{K}_I \models \varphi_2$. Note that Theorem III.1 then follows directly by the undecidability of PCP.

First, we easily deduce the following result concerning the construction of the Kripke structure $\mathcal{K}_I$.

**Proposition III.4.** One can build in time polynomial in the size of $I$ a finite Kripke structure $\mathcal{K}_I$ over $\mathcal{AP}$ satisfying the following conditions:

- the set of traces of $\mathcal{K}_I$ contains the set of well-formed traces;
- each trace of $\mathcal{K}_I$ having a suffix where $\#$ always holds is a well-formed trace.

Finally, the HyperLTL$_S$ sentence $\varphi_2$ is defined as follows, where $\Gamma = \{\#, p_1, \ldots, p_n\}$:

\[
\varphi_2 \overset{\text{def}}{=} \exists x_1, \exists x_2. FG(\#[x_1] \land \#[x_2]) \land G(\neg q_2[x_1] \land \neg q_1[x_2]) \land \bigwedge_{p \in \Sigma} G(p[x_1] \leftrightarrow p[x_2])
\]

Assume that $\varphi_2$ is interpreted over the Kripke structure $\mathcal{K}_I$ of Proposition III.3. Then, by Proposition III.4, the first conjunct in the body of $\varphi_2$ ensures that the two traces $\pi_1$ and $\pi_2$ of $\mathcal{K}_I$ selected by the existential quantification are well-formed traces. Moreover, the other three conjuncts in the body of $\varphi_2$ correspond to Conditions (1)–(3) of Proposition III.3 over the selected traces $\pi_1$ and $\pi_2$. Hence, $\mathcal{K}_I \models \varphi_2$ if and only if there are two well-formed traces that satisfy Conditions (1)–(3) of Proposition III.3 if and only if $I$ admits a solution. This concludes the proof of Theorem III.1.

D. A Decidable Fragment of HyperLTL$_S$

In the previous section, we have shown that the model checking problem is undecidable for the HyperLTL$_S$ sentences whose relativized temporal modalities exploit two distinct sets of LTL formulas. In this section, we establish that the use of a unique finite set $\Gamma$ of LTL formulas as a subcript of the temporal modalities in the given formula leads to a decidable model checking problem. In particular, we consider the fragment of HyperLTL$_S$, we call simple HyperLTL$_S$, whose quantifier-free formulas $\psi$ satisfy the following requirement: there exists a finite set $\Gamma$ of LTL formulas (depending on $\psi$) such that $\psi$ is a Boolean combination of quantifier-free formulas in HyperLTL$_S|\Gamma$ and one-variable HyperLTL$_S$ quantifier-free formulas.

Simple HyperLTL$_S$ strictly subsumes HyperLTL and can express interesting asynchronous security properties like asynchronous noninterference [6] and observational determinism [8]. In particular, the HyperLTL$_S$ sentences at the end of Subsection III.B used for expressing noninterference (but not generalized noninterference), observational determinism, and the unbounded time procedural requirement are simple HyperLTL$_S$ formulas.

We solve the (fair) model checking for simple HyperLTL$_S$ by a reduction to HyperLTL model checking, which is known to be decidable [11]. Our reduction is exponential in the size of the given sentence. As a preliminary step, we first show, by an adaptation of the standard automata-theoretic approach for LTL [24], that the problem for a simple HyperLTL$_S$ sentence $\varphi$ can be reduced in exponential time to the fair model...
checking against a sentence in the fragment HyperLTL$_S$ with some set $\Gamma$ of atomic propositions depending on $\varphi$.

**Reduction to the Fragment HyperLTL$_S$ with $\Gamma$ being Propositional.** In order to prove the reduction from simple HyperLTL$_S$ to LTL$_S$ with propositional $\Gamma$ (formally expressed in Theorem III.2 below), we need some preliminary results. Recall that a Nondeterministic Büchi Automaton (NBA) is a tuple $A = (\Sigma, Q, Q_0, \Delta, Acc)$, where $\Sigma$ is a finite alphabet, $Q$ is a finite set of states, $Q_0 \subseteq Q$ is the set of initial states, $\Delta \subseteq Q \times \Sigma \times Q$ is the transition function, and $Acc \subseteq Q$ is the set of accepting states. Given a infinite word $w$ over $\Sigma$, a run of $A$ over $w$ is an infinite sequence of states $q_0, q_1, \ldots$ such that $q_0 \in Q_0$ and for all $i \geq 0$, $(q_i, w(i), q_{i+1}) \in \Delta$. The run is accepting if for infinitely many $i$, $q_i \in Acc$. The language $L(A)$ accepted by $A$ consists of the infinite words $w$ over $\Sigma$ such that there is an accepting run over $w$.

Fix a non-empty set $\Gamma$ of LTL formulas over $\mathcal{AP}$. The closure $cl(\Gamma)$ of $\Gamma$ is the set of LTL formulas consisting of the sub-formulas of the formulas in $\Gamma$ and their negations (we identify $\neg \varphi$ with $\varphi$). Note that $\Gamma \subseteq cl(\Gamma)$.

By construction and Proposition III.5, we easily obtain the following result.

**Proposition III.6.** For each infinite word $w$ over $2^{\mathcal{AP}}$, $w \in L(K, F)$ if and only if $w \in L(\mathcal{AP}, \mathcal{F})$ and $(w)_{\mathcal{AP}} \in L(\mathcal{K}, F)$. Moreover, for each $\pi \in L(K, \mathcal{F})$, there exists $w \in L(K, F)$ such that $(w)_{\mathcal{AP}} = \pi$.

For each $\Gamma' \subseteq \Gamma$, let $\mathcal{G}'_{prop}$ be the set of propositions in $\mathcal{AP}$ that are associated with the formulas in $\Gamma'$, in other words $\mathcal{G}'_{prop} \equiv \{\varphi \mid \varphi \in \Gamma'\}$. By Propositions III.5 and III.6 we deduce the following result which allows to reduce the fair model checking against a simple HyperLTL$_S$ sentence to the fair model checking against a HyperLTL$_S$ sentence in the fragment HyperLTL$_S^\Gamma_{\mathcal{G}'_{prop}}$ for some set $\Gamma'_{prop}$ of atomic propositions.

**Lemma III.1.** The following holds:
1) For each $\varphi \in \Gamma$ and $w \in L(K, F_1)$, $\varphi(\varphi(\varphi(\varphi)(w)(\mathcal{AP})) = (w_{\mathcal{AP}})$
2) For all $\pi \in L(K, F_1)$, $(\text{stfr}_{\mathcal{G}'_{prop}}(w))_{\mathcal{AP}} = \text{stfr}_{\mathcal{G}'_{prop}}(\pi)$.

**Proof.** Property 1 directly follows from Proposition III.5 and Proposition III.6. Now, let us consider Property 2. Let $\Gamma' \subseteq \Gamma$, $w \in L(K, F_1)$, and $\pi = (w)_{\mathcal{AP}}$. By Proposition III.6 $w \in L(\mathcal{A}_\Gamma)$. Moreover, by Property (1) of Proposition III.5 for all $i \geq 0$ and $\varphi \in \Gamma'$, $\varphi(\varphi(\varphi(\varphi)(w)(\mathcal{AP})) = (w_{\mathcal{AP}})$.

We can now prove the desired result.

**Theorem III.2.** Given a simple HyperLTL$_S$ sentence $\varphi$ and a fair finite Kripke structure $(K, F)$ over $\mathcal{AP}$, one can construct in single exponential time a Kripke structure $(K', F')$ over $2^{\mathcal{AP}}$ such that $\varphi' = O(\varphi)|\varphi'$ is in the fragment HyperLTL$_S^\Gamma_{\mathcal{G}'_{prop}}$ for some $\mathcal{AP}' \subseteq \mathcal{AP}$, $\varphi' = O(\varphi)|\varphi'$.

**Proof.** By hypothesis, there is a finite set $\Gamma' \subseteq \mathcal{AP}$ formulas such that $\varphi$ is of the form $Q_n x_n Q_{n-1} x_{n-1} \ldots Q_1 x_1 \psi$ where $n \geq 1$, $Q_i \in \{\exists, \forall\}$ for all $i \in [1, n]$, and $\psi$ is a Boolean combination of quantifier-free formulas in a set $\mathcal{T}_1 \cup \mathcal{T}_\Gamma$, where $\mathcal{T}_1$ consists of one-variable HyperLTL$_S$ quantifier-free formulas and $\mathcal{T}_\Gamma$ consists of quantifier-free formulas in HyperLTL$_S^\Gamma$. By Proposition III.1 we can assume without
Claim. Let \( \Gamma \) be the set of LTL formulas corresponding to the formulas in \( \Upsilon_1 \) (i.e., for each \( \theta \in \Upsilon_1 \), we take the LTL formula obtained from \( \theta \) by removing the unique variable occurring in \( \theta \)). We define:

- \( \Gamma \) is the set of LTL formulas obtained from the unique variable occurring in \( \theta \).

- \( (K', F') \) is the \( \Gamma \)-extension of \( (K, F) \);

- \( \psi' \) is obtained from \( \psi \) by replacing (i) each formula \( \xi \in \Upsilon_1 \) with the \( x \)-relativized proposition in \( AP \), given by \( \alpha(LTL(\xi))[x] \), where \( LTL(\xi) \) is the LTL formula associated with \( \xi \) and \( x \) is the unique variable occurring in \( \xi \), and (ii) each formula \( \xi \in \Upsilon_1 \) with the formula obtained from \( \xi \) by replacing each relativized temporal modality in \( \xi \) with its \( \Gamma' \)-relativized version.

We show that \( L(K', F') \models \psi' \) if and only if \( L(K, F) \models \varphi \). Hence, Theorem III.2 directly follows. For each \( i \in [1, n] \), let \( \varphi_i \) be the \( i \)-th relativized proposition in \( AP \), given by \( \alpha(LTL(\xi))[x] \), where \( LTL(\xi) \) is the LTL formula associated with \( \xi \) and \( x \) is the unique variable occurring in \( \xi \), and (ii) each formula \( \xi \in \Upsilon_1 \) with the formula obtained from \( \xi \) by replacing each relativized temporal modality in \( \xi \) with its \( \Gamma' \)-relativized version.

Claim. Let \( 0 \leq i \leq n \) and \( w_1, \ldots, w_{n-1} \in L(K', F') \). Then, \( L(K, F) \models \varphi \) if and only if \( L(K, F) \models \varphi_i \).

Proof of the Claim. For the base case \( i = 0 \), the result directly follows from construction and Lemma III.1. For the induction step, the result directly follows from the induction hypothesis and the second part of Proposition III.1.

Fair Model checking against HyperLTL \( G[1] \) with \( \Gamma \subseteq AP \). By Theorem III.2, we can restrict to the fair model checking against the fragments HyperLTL \( \Gamma \) where \( \Gamma \) is a non-empty finite set of atomic propositions. We show that this problem can be reduced in polynomial time to a variant of model checking against HyperLTL.

Definition III.3 (LTL-conditioned model checking). For a Kripke structure \( K \) and a LTL formula \( \theta \), we denote by \( L(K, \theta) \) the set of traces of \( K \) which satisfy \( \theta \). The LTL-conditioned model checking problem against HyperLTL is checking for a finite Kripke structure \( K \), a LTL formula \( \theta \) and a HyperLTL sentence \( \varphi \), whether \( L(K, \theta) \models \varphi \).

LTL-conditioned model checking against HyperLTL can be easily reduced in linear time to HyperLTL model checking (for details see the appendix).

Proposition III.7. Given an LTL formula \( \theta \) and a HyperLTL sentence \( \varphi \), one can construct in linear time a HyperLTL sentence \( \varphi' \) having the same quantifier prefix as \( \varphi \) such that for each Kripke structure \( K \), \( L(K, \theta) \models \varphi \) iff \( L(K, \theta) \models \varphi' \).

Let \( (K, F) \) be a fair finite Kripke structure with \( \Gamma = \langle S, S_0, E, V \rangle \) and \( \varphi \) be a HyperLTL \( \Gamma \) sentence with \( \Gamma \subseteq AP \) and \( \Gamma \neq \emptyset \). Let \( acc \) be a fresh proposition not in \( AP \). Starting from \( K, F \), and \( \Gamma \), we construct in polynomial time a finite Kripke structure \( \hat{K} \) over \( AP = AP \cup \{ acc \} \) and an LTL formula \( \hat{\theta} \) over \( AP \) such that the projections over \( AP \) of the traces of \( \hat{K} \) satisfying \( \hat{\theta} \) correspond to the traces in \( sfr_{\Gamma}(L(K, F)) \). By Remark III.1 and since \( \varphi \) does not contain occurrences of the special proposition \( acc \), we obtain that \( L(K, F) \) is a model of the HyperLTL \( \Gamma \) sentence \( \varphi \) iff \( L(\hat{K}, \hat{\theta}) \) is a model of the HyperLTL sentence HyperLTL \( \varphi \).

Intuitively, the Kripke structure \( \hat{K} \) is obtained from \( K \) by adding edges which keep track of the states associated with the starting positions of adjacent segments along the \( \Gamma \)-stutter factorizations of the (traces of) the \( F \)-fair paths of \( K \). Formally, let \( R_T(K) \) and \( R_T(K, F) \) be the sets of state pairs in \( K \) defined as follows:

- \( R_T(K) \) consists of the pairs \((q, q') \in S \times S \) such that \( V(q) \cap \Gamma \neq V(q') \cap \Gamma \) and there is a finite path of \( K \) of the form \( q \cdot q' \) such that \( V(q) \cap \Gamma = V(q(i)) \cap \Gamma \) for all \( 0 < i < |\rho| \).
- \( R_T(K, F) \) is defined similarly but, additionally, we require that the finite path \( q \cdot q' \) visits some accepting state in \( F \).

The finite sets \( R_T(K) \) and \( R_T(K, F) \) can be easily computed in polynomial time by standard closure algorithms. By exploiting the sets \( R_T(K) \) and \( R_T(K, F) \), we define the finite Kripke structure \( \hat{K} = \langle \hat{S}, \hat{S}_0, \hat{E}, \hat{V} \rangle \) over \( \hat{AP} = AP \cup \{ acc \} \) as follows:

- \( \hat{S} = S \times \{ 0, 1 \} \) and \( \hat{S}_0 = S_0 \times \{ 0 \} \).
- \( \hat{E} \) consists of the edges \((s, \ell), (s, \ell')\) such that one of the following holds:
  - either \((s, s') \in E \cup R_T(K) \) and \((\ell' = 1 \iff s' \in F)\),
  - or \((s, s') \in R_T(K, F) \) and \(\ell' = 1\).
- \( \hat{V}((s, 1)) = V(s) \cup \{ acc \} \) and \( \hat{V}((s, 0)) = V(s) \).

Let \( \hat{\theta} \) be the LTL formula over \( \hat{AP} \) defined as follows:

\[
G acc \land G \left( \bigvee_{p \in \Gamma} (p \leftrightarrow \neg \rho p) \lor \bigwedge_{p \in \Gamma} (p \leftrightarrow \rho p) \right)
\]

The first conjunct in the definition of \( \hat{\theta} \) ensures that proposition \( acc \) holds infinitely often while the second conjunct captures the traces that are \( \Gamma \)-stutter free. By construction, we easily obtain the following result.

Proposition III.8. \( sfr_{\Gamma}(L(K, F)) \) coincides with the set of projections over \( AP \) of the traces in \( L(\hat{K}, \hat{\theta}) \).

Proof. Let \( \pi \in sfr_{\Gamma}(L(K, F)) \). Hence, there is a \( F \)-fair path \( \nu \) of \( K \) such that \( \pi = sfr_{\Gamma}(V(\nu)) \) where \( V(\nu) \) is the trace associated with \( \nu \). By construction, there is a trace \( \hat{\pi} \) of \( \hat{K} \) such that \( acc \in \hat{\pi}(i) \) for infinitely many \( i \) and the projection of \( \hat{\pi} \) over \( AP \) coincides with \( \pi \). By construction of the LTL formula \( \hat{\theta} \), \( \hat{\pi} \) satisfies \( \hat{\theta} \). Hence, \( \hat{\pi} \in L(\hat{K}, \hat{\theta}) \). The converse direction is similar.
HyperLTL(\(\varphi\)).

By [13] model checking a finite Kripke structure \(K\) against a HyperLTL sentence \(\varphi\) of quantifier alternation depth \(d\) can be done in nondeterministic space bounded by \(O(Tower_2(d, |\varphi| \log(|K|)))\). Thus, since simple HyperLTL\(S\) subsumes HyperLTL, by Theorem [III.2] and Proposition [III.7] we obtain the main result of this section, where the lower bounds correspond to the known ones for HyperLTL [13].

**Theorem III.3.** For each \(d \in \mathbb{N}\), (fair) model checking against simple HyperLTL\(S\) sentences of quantifier alternation depth \(d\) is \(d\)-EXPSPACE-complete, and for a fixed formula, it is \((d – 1)\)-EXPSPACE-complete for \(d > 0\) and \(N\)LOGSPACE-complete otherwise.

**IV. CONTEXT HYPERLTL**

In this section, we introduce an alternative logical framework for specifying asynchronous linear-time hyperproperties. The novel framework, we call context HyperLTL (HyperLTL\(C\) for short), extends HyperLTL by unary modalities \((C)\) parameterized by a non-empty subset \(C\) of trace variables—called the context—which restrict the evaluation of the temporal modalities to the traces associated with the variables in \(C\). Formally, HyperLTL\(C\) formulas over the given finite set \(\text{AP}\) of atomic propositions and finite set \(\text{VAR}\) of trace variables are linear-time hyper expressions over multi-trace specifications \(\psi\), called HyperLTL\(C\) quantifier-free formulas, where \(\psi\) is defined by the following syntax:

\[
\psi ::= \top | p \cdot x | \neg \psi | \psi \land \psi | (C)\psi
\]

where \(p \in \text{AP}\), \(x \in \text{VAR}\), and \((C)\) is the context modality with \(\emptyset \neq C \subseteq \text{VAR}\). A context \(C\) is non-empty subset of trace variables in \(\text{VAR}\). The size \(|\xi|\) of a HyperLTL\(C\) (quantifier-free) formula \(\xi\) is the number of distinct sub-formulas of \(\xi\). A context \(C\) is global for a formula \(\xi\) if \(C\) contains all the trace variables occurring in \(\xi\).

**Semantics of HyperLTL\(C\) quantifier-free formulas.** Let \(\Pi\) be a pointed trace assignment. Given a context \(C\) and an offset \(i \geq 0\), we denote by \(\Pi +_C i\) the pointed trace assignment with domain \(\text{Dom}(\Pi)\) defined as follows:

- for each \(x \in \text{Dom}(\Pi) \cap C\) with \(\Pi(x) = (\pi, h)\), \(\Pi +_C i)(x) = (\pi, h + i)\);
- for each \(x \in \text{Dom}(\Pi) \setminus C\), \((\Pi +_C i)(x) = \Pi(x)\).

Intuitively, the positions of the pointed traces associated with the variables in \(C\) advance of the offset \(i\), while the positions of the other pointed traces remain unchanged.

Given a HyperLTL\(C\) quantifier-free formula \(\psi\), a context \(C\), and a pointed trace assignment \(\Pi\) such that \(\text{Dom}(\Pi)\) contains the trace variables occurring in \(\psi\), the satisfaction relation \((\Pi, C) \models \psi\) is inductively defined as follows (we omit the semantics of the Boolean connectives which is standard):

\[
\begin{align*}
(\Pi, C) \models p \cdot x & \iff \Pi(x) = (\pi, i) \text{ and } p \in \pi(i) \\
(\Pi, C) \models X \psi & \iff (\Pi +_C 1, C) \models \psi \\
(\Pi, C) \models \psi_1 \land \psi_2 & \iff \text{for some } i \geq 0: (\Pi +_C i, C) \models \psi_2 \\
& \text{and } (\Pi +_C k, C) \models \psi_1 \text{ for all } k < i \\
(\Pi, C) \models (C)\psi & \iff (\Pi, C') \models \psi
\end{align*}
\]

We write \(\Pi \models \psi\) to mean that \((\Pi, \text{VAR}) \models \psi\).

**Examples of specifications.** Context HyperLTL extends HyperLTL by allowing to specify complex combinations of asynchronous and synchronous constraints. As an example consider the following property [20]. A HyperLTL quantifier-free formula \(\psi(x_1, \ldots, x_n)\) holds along the traces bound by variables \(x_1, \ldots, x_n\) after an initialization phase, which can take a different number of steps on each trace. This can be expressed by an HyperLTL\(C\) quantifier-free formula as follows, where proposition \(in\) characterizes the initialization phase:

\[
\begin{align*}
(\{x_1\})(in[x_1] \cup \neg in[x_1] \land (\{x_2\}) \ldots \\
& \ldots (\{x_n\})(in[x_n] \cup \neg in[x_n] \land (\{x_1, \ldots, x_n\})\psi) \ldots ))
\end{align*}
\]

As another example, illustrating the high expressiveness of HyperLTL\(C\), we consider the following hyper-bounded-time response requirement: “for every trace there is a bound \(k\) such that each request \(q\) is followed by a response \(p\) within exactly \(k\) steps.” This can be expressed in HyperLTL\(C\) as follows:

\[
\begin{align*}
\forall x. \exists y. F q[x] \rightarrow [\bigwedge_{r \in \text{AP}} G(r[x] \leftrightarrow r[y]) \land \\
\{y\} F (q[y] \land \{x\} G \left( q[x] \rightarrow \{x, y\} \left( \neg p[y] \cup p[x] \right) \right))
\end{align*}
\]

Note that \(x\) and \(y\) refer to the same trace and the context modalities are exploited to synchronously compare distinct segments along the same trace, that correspond to different request-response intervals. This ability is not supported by Stuttering HyperLTL. On the other hand, we conjecture that unlike HyperLTL\(S\), HyperLTL\(C\) cannot express asynchronous variants of security properties such as noninterference and observational determinism (see Subsection [III.B]).

**A. Undecidability of model checking against HyperLTL\(C\)**

In this section, we establish that model checking against HyperLTL\(C\) is in general undecidable. Let \(F_0\) and \(F_1\) be the fragments of HyperLTL\(C\) consisting of the formulas such that the number of trace variables is 2, the nesting depth of context modalities is 2, and, additionally, (i) in \(F_0\) the quantifier alternation depth is 0, and (ii) in \(F_1\) the quantifier alternation depth is 1 and each temporal modality in the scope of a non-global context is \(F\).

**Theorem IV.1.** The model checking problem against HyperLTL\(C\) is undecidable even for the fragments \(F_0\) and \(F_1\).

Theorem [IV.1] is proved by a polynomial-time reduction from the halting problem for Minsky 2-counter machines [25]. Such a machine is a tuple \(M = (Q, q_{\text{init}}, q_{\text{halt}}, \Delta)\), where \(Q\) is a finite set of (control) locations, \(q_{\text{init}} \in Q\) is the initial location, \(q_{\text{halt}} \in Q\) is the halting location, and \(\Delta \subseteq Q \times L \times Q\) is a transition relation over the instruction set \(L = \{\text{inc, dec, zero}\} \times \{1, 2\}\). We adopt the following notational conventions. For an instruction \(op = (\_, c) \in L\), let \(c(op) \equiv c \in \{1, 2\}\) be the counter associated with \(op\). For a transition \(\delta \in \Delta\) of the form \(\delta = (q, op, q')\), we define...
from(δ) \equiv q, \text{op}(δ) \equiv \text{op}, c(δ) \equiv c(\text{op}), \text{and to}(δ) \equiv q'. Without loss of generality, we assume that for each transition \( δ \in Δ, from(δ) \neq q_{halt}. \)

An \( M \)-configuration is a pair \((q, ν)\) consisting of a location \( q \in Q \) and a counter valuation \( ν : \{ 1, 2 \} \rightarrow N \). A computation of \( M \) is a non-empty finite sequence \((q_1, ν_1), \ldots, (q_k, ν_k)\) of configurations such that for each \( 1 \leq i < k, (q_i, op, q_{i+1}) \in Δ \) for some instruction \( op \in L \) (depending on \( i \)) and the following holds, where \( c \in \{ 1, 2 \} \) is the counter associated with the instruction \( op \): (i) \( ν_{i+1}(c') = ν_i(c') \) if \( c' \neq c \); (ii) \( ν_{i+1}(c) = ν_i(c) + 1 \) if \( op = (\text{inc}, c) \); (iii) \( ν_{i+1}(c) = ν_i(c) - 1 \) if \( op = (\text{dec}, c) \) (in particular, it has to be \( ν_i(c) > 0 \)); and (iv) \( ν_{i+1}(c) = ν_i(c) = 0 \) if \( op = (\text{zero}, c) \). \( M \) halts if there is a computation starting at the initial configuration \((q_{init}, ν_{init})\), where \( ν_{init}(1) = ν_{init}(2) = 0 \), and leading to some halting configuration \((q_{halt}, ν)\). The halting problem is to decide whether a given machine \( M \) halts, and it is undecidable [25]. We prove the following result, from which Theorem IV.1 for the fragment \( F_0 \) directly follows.

**Proposition IV.1.** One can build a finite Kripke Structure \( K_M \) and a HyperLTL\(_C\) sentence \( \varphi_M \) in the fragment \( F_0 \) such that \( M \) halts \( \Leftrightarrow K_M \models \varphi_M \).

**Proof.** First, we define a suitable encoding of a computation of \( M \) as a trace where the finite set \( \text{AP} \) of atomic propositions is given by \( \text{AP} \equiv Δ \cup \{ 1, 2, \text{beg}_1, \text{beg}_2 \} \).

Intuitively, in the encoding of an \( M \)-computation, we keep track of the transition used in the current step of the computation. Moreover, for each \( c \in \{ 1, 2 \} \), the propositions in \( \{ c, \text{beg}_c \} \) are used for encoding the current value of counter \( c \). In particular, for \( c \in \{ 1, 2 \} \), a \( c \)-code for the \( M \)-transition \( δ \in Δ \) is a finite word \( w_c \) over \( 2^{\text{AP}} \) of the form \( \{ δ, \text{beg}_c \} \cdot \{ δ, c \}^h \) for some \( h \geq 0 \) such that \( h = 0 \) if \( \text{op}(δ) = (\text{zero}, c) \). The \( c \)-code \( w_c \) encodes the value for counter \( c \) given by \( h \) (or equivalently \( w_c - 1 \)). Note that only the occurrences of the symbols \( \{ δ, c \} \) encode units in the value of counter \( c \), while the symbol \( \{ δ, \text{beg}_c \} \) is only used as left marker in the encoding. A configuration-code \( w \) for the \( M \)-transition \( δ \in Δ \) is a finite word over \( 2^{\text{AP}} \) of the form \( w = \{ δ \} \cdot w_1 \cdot w_2 \) such that for each counter \( c \in \{ 1, 2 \} \), \( w_c \) is a \( c \)-code for transition \( δ \). The configuration-code \( w \) encodes the \( M \)-configuration \((\text{from}(δ), ν)\), where \( ν(c) = |w_c| - 1 \) for all \( c \in \{ 1, 2 \} \). Note that if \( \text{op}(δ) = (\text{zero}, c) \), then \( ν(c) = 0 \).

A computation-code is a trace of the form \( \pi = w_{δ_1} \cdots w_{δ_k} \cdot \emptyset^{k'} \), where \( k \geq 1 \) and for all \( 1 \leq i \leq k, w_{δ_i} \) is a configuration-code for transition \( δ_i \), and whenever \( i < k \), it holds that \( \text{to}(δ_i) = \text{from}(δ_{i+1}) \). Note that by our assumptions \( \text{to}(δ_i) \neq q_{halt} \) for all \( 1 \leq i < k \). The computation-code \( \pi \) is initial if the first configuration-code \( w_{δ_1} \) encodes the initial configuration, and it is halting if for the last configuration-code \( w_{δ_k} \) in \( π \), it holds that \( \text{to}(δ_k) = q_{halt} \). For all \( 1 \leq i \leq k \), let \((q_i, ν_i)\) be the \( M \)-configuration encoded by the configuration-code \( w_{δ_i} \), and \( c_i = c(δ_i) \). The computation-code \( π \) is good if, additionally, for all \( 1 \leq j < k \), the following holds: (i) \( ν_{j+1}(c_j) = ν_j(c_j) \) if either \( c \neq c_j \) or \( \text{op}(δ_j) = (\text{zero}, c_j) \) (equality requirement); (ii) \( ν_{j+1}(c_j) = ν_j(c_j) + 1 \) if \( \text{op}(δ_j) = (\text{inc}, c_j) \) (increment requirement); (iii) \( ν_{j+1}(c_j) = ν_j(c_j) - 1 \) if \( \text{op}(δ_j) = (\text{dec}, c_j) \) (decrement requirement).

Clearly, \( M \) halts \( \iff \) there exists an initial and halting good computation-code. By construction, it is a trivial task to define a Kripke structure \( K_M \) satisfying the following.

**Claim.** One can construct in polynomial time a finite Kripke structure \( K_M \) over \( \text{AP} \) such that the set of traces of \( K_M \) which visit some empty position (i.e., a position with label the empty set of propositions) corresponds to the set of initial and halting computation-codes.

We now define a HyperLTL\(_C\) quantifier-free sub-formula \( ψ_{good} \) is defined in the following. Intuitively, when interpreted on the Kripke structure \( K_M \) of the previous claim, formula \( ϕ_M \) asserts the existence of two traces \( π_1 \) and \( π_2 \) bounded to the trace variables \( x_1 \) and \( x_2 \), respectively, such that (i) \( π_1 \) and \( π_2 \) coincide (this is ensured by the first conjunct); (ii) \( π_1 \) is an initial and halting computation-code (this is ensured by the previous claim and the second conjunct); (iii) \( π_1 \) satisfies the goodness requirement by means of the conjunct \( ψ_{good} \).

We now define the quantifier-free formula \( ψ_{good} \). Let \( Δ_{halt} = \{ δ \in Δ \mid \text{to}(δ) = q_{halt} \} \) be the set of transitions having as a target location the halting location. In the definition of \( ψ_{good} \), we crucially exploit the context modalities. Essentially, for each position \( i \geq 0 \) along \( π_1 \) and \( π_2 \) corresponding to the initial position of a \( c \)-code for a transition \( δ \in Δ_{halt} \) within a configuration code \( w_δ \), we exploit:

- temporal modalities in the scope of the context modality \( \langle \{ x_2 \} \rangle \) for moving the current position along trace \( π_2 \) (the trace bounded by \( x_2 \)) to the beginning of the \( c \)-code of the configuration code \( w_δ \) following \( w_δ \), and then we use the temporal modalities in the scope of the global context \( \{ x_1, x_2 \} \) for synchronously ensuring that for the \( c \)-codes associated to the consecutive configuration codes \( w_δ \) and \( w'_δ \), the equality, increment, and decrement requirements are fulfilled.

Formally, the HyperLTL\(_C\) quantifier-free formula \( ψ_{good} \) is defined as follows:

\[
ψ_{good} \equiv \bigwedge_{δ \in Δ \setminus Δ_{halt}} \bigwedge_{c \in \{ 1, 2 \}} \left[ \{ x_1 \} \bowtie \neg ψ_{beg}[c_δ]\left(\{ x_2 \}\right) \land \left(\{ x_1, x_2 \} \left(ψ_{halt}(δ, c) \land ψ_{inc}(δ, c) \land ψ_{dec}(δ, c)\right)\right)\right]
\]

where the sub-formulas \( ψ_{halt}(δ, c), ψ_{inc}(δ, c), \) and \( ψ_{dec}(δ, c) \) capture the equality, increment, and decrement requirements, respectively.
respectively, and are defined as follows.

\[ \psi_=(\delta, c) \triangleq [c \neq c(\delta) \lor op(\delta) = (\text{zero}, c)] \rightarrow X[(c[x_1] \land c[x_2]) \cup (\neg c[x_1] \land \neg c[x_2])] \]

\[ \psi_{inc}(\delta, c) \triangleq op(\delta) = (\text{inc}, c) \rightarrow X[(c[x_1] \land c[x_2]) \cup (\neg c[x_1] \land c[x_2] \land X \neg c[x_2])] \]

\[ \psi_{dec}(\delta, c) \triangleq op(\delta) = (\text{dec}, c) \rightarrow X[(c[x_1] \land c[x_2]) \cup (c[x_1] \land \neg c[x_2] \land X \neg c[x_1])] \]

This finishes the proof. □

B. Fragment of HyperLTL with decidable model checking

By Theorem [IV.1] model checking HyperLTLC is undecidable even for formulas where F is the unique temporal modality occurring in the scope of a non-global context operator. This justifies the investigation of the fragment, we call bounded HyperLTLC, consisting of the HyperLTLC formulas where the unique temporal modality occurring in a non-global context is the next modality X. For instance, for each \( k \geq 0 \), the formula \( \{x_1\} X^k \{\{x_1, x_2\} G \{p[x_1] \leftrightarrow p[x_2]\} \} \) is bounded while the formula \( \{x_1\} F \{\{x_1, x_2\} G \{p[x_1] \leftrightarrow p[x_2]\} \} \) is not. Note that bounded HyperLTLC subsumes HyperLTLL and is able to express a restricted form of synchronicity by allowing to compare traces at different times-tamps whose distances are bounded (a bound is given by the nesting depth of next modalities in the formula). As an example, the after-initialization synchronization requirement described after the definition of HyperLTL can be expressed by assuming that the lengths of the initialization phases differ at most a given integer \( k \). We conjecture that bounded HyperLTLC is not more expressive than HyperLTLL. However, as a consequence of Theorem [IV.2] below, for a fixed quantifier alternation depth, bounded HyperLTLC is at least singly exponentially more succinct than HyperLTLL.

We show that model checking against bounded HyperLTLC is decidable by a polynomial-time translation of bounded HyperLTLLC quantifier-free formulas \( \psi \) into equivalent \( (|\psi| + 1) \)-synchronous Büchi AAWA.

Proposition IV.2. Given a HyperLTL \( \psi \) quantifier-free formula \( \psi \) with trace variables \( x_1, \ldots, x_n \), one can build in polynomial time a Büchi nAAWA \( A_\psi \) such that \( L(A_\psi) \) is the set of \( n \)-tuples \( (\pi_1, \ldots, \pi_n) \) of traces so that \( \{x_1 \rightarrow (\pi_1, 0), \ldots, x_1 \rightarrow (\pi_n, 0)\} \models \psi \). Moreover, \( A_\psi \) is \( (|\psi| + 1) \)-synchronous if \( \psi \) is in the bounded fragment of HyperLTLC.

Proof. By exploiting the release modality \( R \) (the dual of the until modality), we can assume without loss of generality that \( \psi \) is in negation normal form, so negation is applied only to relativized atomic propositions. The construction of the Büchi nAAWA \( A_\psi \) is a generalization of the standard translation of LTL formulas into equivalent standard Büchi alternating word automata. In particular, the automaton \( A_\psi \) keeps track in its state of the sub-formula of \( \psi \) currently processed, of the current context \( C \), and of a counter modulo the cardinality \( |C| \) of \( C \). This counter is used for recording the directions associated to the variables in \( C \) for which a move of one position to the right has already been done in the current phase of \( |C| \)-steps. By construction, whenever the automaton is in a state associated with a sub-formula \( \theta \) of \( \psi \), then \( A_\psi \) can move only to states associated with \( \theta \) or with strict sub-formulas of \( \theta \). In particular, each path in a run of \( A_\psi \) can be factorized into a finite number \( \nu_1, \ldots, \nu_k \) of contiguous segments (with \( \nu_k \) possibly infinite) such that for each \( i \in [1, k] \), segment \( \nu_i \) is associated with a sub-formula \( \theta_i \) of \( \psi \) and a context \( C_i \) occurring in \( \psi \), and the following holds, where the offset of a position vector \( \varsigma = (j_1, \ldots, j_n) \) in \( \mathbb{N}^n \) is the maximum over the differences between pairs of components, i.e. \( \max\{j_k - j_{k'} | \ell, \ell' \in [1, n]\}\):

- there is some occurrence of \( \theta_i \) in \( \psi \) which is in the scope of the context modality \( \langle C_i \rangle \);
- if \( i < k \), then \( \theta_{i+1} \) is a strict sub-formula of \( \theta_i \);
- if either \( C_i \) is global or the root modality of \( \theta_i \) is not in \( \{U, R\} \), then the offset at each node along the segment \( \nu_i \) and at the first node of \( \nu_{i+1} \) if \( i < k \) is at most the offset at the beginning of \( \nu_i \) plus one.

Hence, if \( \psi \) is in the bounded fragment of HyperLTL, the offset at each node of a run is at most \( |\psi| + 1 \), i.e. \( A_\psi \) is \( (|\psi| + 1) \)-synchronous and the result follows. □

By exploiting Propositions [II.1] and [IV.2] we deduce that for a fixed quantifier alternation depth \( d \), model checking against bounded HyperLTL is \( (d + 1) \)-EXPSPACE-complete, hence singly exponentially harder than model checking against HyperLTLL. However, for a fixed formula, the complexity of the problem is the same as for HyperLTLL.

Theorem IV.2. Let \( d \in \mathbb{N} \). The (fair) model checking problem against bounded HyperLTL sentences of quantifier alternation depth \( d \) is \( (d + 1) \)-EXPSPACE-complete, and for a fixed formula, it is \( (d - 1) \)-EXPSPACE-complete for \( d > 0 \) and \( \text{NLOGSPACE-complete otherwise} \).

Proof. The upper bounds follow from Propositions [II.1] and [IV.2] while since bounded HyperLTLC subsumes HyperLTLL, the lower bound for a fixed formula of alternation depth \( d \) is inherited from the known one for HyperLTLL [13]. Finally, for \( (d + 1) \)-EXPSPACE-hardness, we adapt the reduction given in [13] for showing that for all integer constants \( c > 1 \) and \( c' \geq 1 \), model checking against HyperLTLL sentences \( \varphi \) with quantifier alternation depth \( d \) requires space at least \( \Omega(\text{Tower}_c(d, |\varphi|^{c'})) \). Here, for simplicity, we assume that \( c = 2 \) and \( c' = 1 \). The reduction in [13] for model checking HyperLTLL is based on building, for each \( n > 1 \), an HyperLTLL formula of size polynomial in \( n \), with quantifier alternation depth \( d \) over a singleton set \( AP = \{p\} \) of atomic propositions. This formula is of the form \( \psi_d(x, y) \) for two free trace variables \( x \) and \( y \) such that for all traces \( \pi_x \) and \( \pi_y \) (over \( AP \)), \( \{x \rightarrow (\pi_x, 0), y \rightarrow (\pi_y, 0)\} \models \psi_d(x, y) \) if and only if \( p \) occurs exactly once in \( \pi_x \) (resp., \( \pi_y \)) and \( p \) occurs on \( \pi_y \) exactly \( g(d + 1, n) \) positions after \( p \) occurs on \( \pi_x \), where

- \( g(0, n) = \text{Tower}_2(0, n) = n \);
- \( g(d + 1, n) = g(d, n) \ast \text{Tower}_2(d + 1, n) \).
The construction is given by induction on \( d \), and the formula \( \psi_0(x, y) \) for the base case \( d = 0 \) and a fixed \( n > 1 \) do not use universal quantifiers (note that \( \psi_0(x, y) \) requires that \( p[y] \) occurs exactly \( n + 2^n \) positions after \( p[x] \) occurs). Thus, since bounded HyperLTL\(_C\) subsumes HyperLTL and \( g(2, n) = n * 2^n * 2^n \), in order to show that model checking against bounded HyperLTL\(_C\) formulas \( \varphi \) with quantifier alternation depth \( d \) requires space at least \( \Omega(\text{Tower}_2(d + 1, |\varphi|)) \), it suffices to show the following result.

**Claim.** Let \( \mathcal{AP} = \{ p \} \) and \( n > 1 \). One construct in time polynomial in \( n \) a bounded HyperLTL\(_C\) formula \( \psi(x, y) \) with two free variables \( x \) and \( y \) and not containing universal quantifiers (hence, the quantifier alternation depth is 0) such that for all traces \( \pi_x \) and \( \pi_y \), \( \{ x \mapsto (\pi_x, 0), y \mapsto (\pi_y, 0) \} \models \psi(x, y) \) iff

- \( p \) occurs exactly once on \( \pi_x \) (resp., \( \pi_y \));
- for each \( i \geq 1 \), \( p \in \pi_x(i) \) iff \( p \in \pi_y(i + n * 2^n * 2^n) \).

\( \Box \)

**V. Conclusions**

We have introduced in this paper two extensions of HyperLTL to express asynchronous hyperproperties: HyperLTL\(_S\) and HyperLTL\(_C\). Even though the model-checking problems of these logics are in general undecidable we have presented one decidable fragment of each logic that allows to express asynchronous properties of interest.

We plan to extend our work in many directions. First, we intend to settle the question concerning the comparison of the expressive power of HyperLTL\(_S\) and HyperLTL\(_C\). Second, we aim to understand the decidability border of model checking syntactical fragments of the framework resulting by combining HyperLTL\(_S\) and HyperLTL\(_C\). In particular, the decidability status of model checking against the fragment obtained by merging simple HyperLTL\(_S\) and bounded HyperLTL\(_S\) is open. Finally, other goals regard the extensions of the considered logic to the branching-time setting and the investigation of first-order and monadic second-order logics for the specification of asynchronous hyperproperties in the linear-time and branching-time settings.

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Appendix

VI. PROOFS FROM SECTION III

A. Proof of Proposition III.1

Proposition III.1. Given a LTL$_S$ formula, one can construct in polynomial time an equivalent LTL formula.

Proof. Given an LTL$_S$ formula $\psi$, we construct in polynomial time an LTL formula $f(\psi)$ such that for each pointed trace $(\pi, i)$, it holds that $(\pi, i) \models \psi$ iff $(\pi, i) \models f(\psi)$. The proof is by induction on structure of $\psi$.

- $\psi = p$ for some $p \in AP$: we set $f(p) \defeq p$ and the result trivially follows.

- $\psi = \neg \psi'$ (resp., $\psi = \psi_1 \land \psi_2$): we set $f(\psi) \defeq \neg f(\psi')$ (resp., $f(\psi) \defeq f(\psi_1) \land f(\psi_2)$) and the result directly follows from the induction hypothesis.

- $\psi = X\psi'$: if $\Gamma = \emptyset$, we set $f(\psi) = Xf(\psi')$ and the result directly follows from the induction hypothesis. Now, assume that $\Gamma \neq \emptyset$. We exploit the auxiliary LTL formula $\theta_\Gamma$ defined as: $\theta_\Gamma \defeq \bigwedge_{\xi \in \Gamma} (\xi \leftrightarrow X\xi)$. Formula $\theta_\Gamma$ asserts that the given position and the next one along the given trace agree on the evaluation of all the LTL formulas in $\Gamma$. Hence, the LTL formula $G\theta_\Gamma$ requires that for the given position $i$ of the given trace $\pi$, the number of segments in the $\Gamma$-stutter factorization of $\pi$ is finite and $i$ belongs to the last segment. Thus, the LTL formula $f(X\psi')$ is defined as follows:

$$f(X\psi') \defeq [G\theta_\Gamma \rightarrow Xf(\psi')] \land \neg[G\theta_\Gamma \rightarrow \theta_\Gamma \land Xf(\psi')]$$

Given a pointed trace $(\pi, i)$, $f(X\psi')$ requires that either (i) position $i$ belongs to the last segment of the $\Gamma$-stutter factorization of $\pi$ and $f(\psi')$ holds at the next position $i + 1$, or (ii) the $i$-segment in the $\Gamma$-stutter factorization of $\pi$ is not the last one and $f(\psi')$ holds at the first position of the first segment following the $i$-segment. Hence, by the induction hypothesis, correctness of the construction follows.

- $\psi = \psi_1 \lor \psi_2$: if $\Gamma = \emptyset$, we set $f(\psi) = f(\psi_1) \lor f(\psi_2)$ and the result directly follows from the induction hypothesis. Now, assume that $\Gamma \neq \emptyset$. In this case, the LTL formula $f(\psi_1 \lori \psi_2)$ is defined as follows:

$$f(\psi_1 \lori \psi_2) \defeq [G\theta_\Gamma \rightarrow f(\psi_1) \lor f(\psi_2)] \land \neg[G\theta_\Gamma \rightarrow f(\psi_2) \lor (f(\psi_1) \land \neg \theta_\Gamma \rightarrow Xf(\psi_1)) \lor g(\psi_1 \lori \psi_2)]$$

Given a pointed trace $(\pi, i)$, $f(\psi_1 \lori \psi_2)$ requires that either (i) position $i$ belongs to the last segment of the $\Gamma$-stutter factorization of $\pi$ and $f(\psi_1)Xf(\psi_2)$ holds at position $i$, or (ii) the $i$-segment in the $\Gamma$-stutter factorization of $\pi$ is not the last one and

- either $f(\psi_1)$ holds at position $i$,
- or $f(\psi_1)$ holds at position $i$ and there is a segment $\nu$ following the $i$-segment such that $f(\psi_2)$ holds at the first position of $\nu$ and $f(\psi_1)$ holds at the first position of each segment preceding $\nu$ end following the $i$-segment,
- or $f(\psi_1)$ holds at position $i$, the last segment, say $\nu$, is defined, $f(\psi_2) \lor f(\psi_1)$ holds at the first position of $\nu$, and $f(\psi_1)$ holds at the first position of each segment preceding $\nu$ end following the $i$-segment.

Note that the size of $f(\psi)$ (i.e., the number of distinct sub-formulas of $f(\psi)$) is polynomial in the size of $\psi$. \qed
B. Detailed proof of Proposition III.2

Proposition III.2. Given a HyperLTL$_S$ quantifier-free formula $\psi$ with trace variables $x_1, \ldots, x_n$, one can build in polynomial time a Büchi nAWA $A_\psi$ such that $L(A_\psi)$ is the set of $n$-tuples $(\pi_1, \ldots, \pi_n)$ of traces so that $\{x_1 \mapsto (\pi_1, 0), \ldots, x_1 \mapsto (\pi_n, 0)\} = \psi$.

Proof. Without loss of generality, we assume that $\psi$ is in negative normal form (NNF), i.e. negation is applied only to relativized atomic propositions. Indeed, by exploiting the dual $R_{\Gamma}$ (relativized release) of the until modality $U_{\Gamma}$, both conjunction and disjunction, and the De Morgan’s laws, we can convert in linear time a given HyperLTL$_S$ quantifier-free formula $\theta$ into an equivalent HyperLTL$_S$ quantifier-free formula $\theta'$ in NNF.

For each finite set $\Gamma$ of LTL formulas, let $\xi_\Gamma$ be the LTL formula given by

$$\xi_\Gamma = \bigwedge_{\xi \in \Gamma} G(\xi \leftrightarrow X\xi) \lor \bigvee_{\xi \in \Gamma} (\xi \leftrightarrow \neg X\xi)$$

The LTL formula $\xi_\Gamma$ has as models the traces $\pi$ such that the first segment in the factorization of $\pi$ is either infinite or has length 1. For each $i \in [1, n]$, we can easily construct in linear time (in the number of distinct sub-formulas in $\Gamma$) a Büchi nAWA $A_{\Gamma,i} = (2^{AP}, Q_{\Gamma,i}, q_{\Gamma,i}, \rho_{\Gamma,i}, F_{\Gamma,i})$ (resp., $\overline{A}_{\Gamma,i} = (2^{AP}, \overline{Q}_{\Gamma,i}, \overline{q}_{\Gamma,i}, \overline{F}_{\Gamma,i}, \overline{F}_{\Gamma,i})$) accepting the $n$-tuples $(\pi_1, \ldots, \pi_n)$ of traces so that the $i^{th}$ component $\pi_i$ is a model (resp., is not a model) of $\xi_\Gamma$.

Let $\Upsilon$ be the set of subscripts $\Gamma$ occurring in the temporal modalities of $\psi$. The Büchi nAWA $A_{\psi} = (2^{AP}, Q = Q_s \cup Q_m, q_0, \rho, F)$ satisfying Proposition III.2 is defined as follows, where we assume that the various automata $A_{\Gamma,i}$ and $\overline{A}_{\Gamma,i}$ have no state in common. The set $Q_s$ of states is the union of the states of the auxiliary automata $A_{\Gamma,i}$ and $\overline{A}_{\Gamma,i}$ where $\Gamma \in \Upsilon$ and $i \in [1, n]$, while the states in $Q_m$ consist of the sub-formulas of $\psi$ and the triples of the form $(\theta, i, \Gamma)$ where $\theta$ is a sub-formula of $\psi$, $i \in [1, n]$ and $\Gamma \in \Upsilon$. The initial state is $\psi$ and the set of accepting states consists of the states of the form $\theta_1 R \theta_2$ and the accepting states of the automata $A_{\Gamma,i}$ and $\overline{A}_{\Gamma,i}$ where $\Gamma \in \Upsilon$ and $i \in [1, n]$.

Finally, we define the transition function $\rho$. From the states in $Q_s$ the transition function is inherited from the respective nAWA $A_{\Gamma,i}$ and $\overline{A}_{\Gamma,i}$. For the states in $Q_m$, $\rho$ is defined by induction on the structure of the sub-formulas $\theta$ of $\psi$ as follows, where for each $\overline{\sigma} \in (2^{AP})^n$ and $i \in [1, n]$, $\overline{\sigma}[i]$ denotes the $i^{th}$ component of $\overline{\sigma}$:

- for each $i \in [1, n-1]$, $\rho((\theta, i, \Gamma), \overline{\sigma}) = (\rho_{\Gamma,i}(\overline{q}_{\Gamma,i}, \overline{\sigma}) \land ((\theta, i+1, \Gamma), i)) \lor (\overline{\rho}_{\Gamma,i}(\overline{q}_{\Gamma,i}, \overline{\sigma}) \land ((\theta, i, \Gamma), i))$
- $\rho((\theta, n, \Gamma), \overline{\sigma}) = (\rho_{\Gamma,n}(\overline{q}_{\Gamma,n}, \overline{\sigma}) \land (\theta, n)) \lor (\overline{\rho}_{\Gamma,n}(\overline{q}_{\Gamma,n}, \overline{\sigma}) \land ((\theta, n, \Gamma), n))$
- $\rho([x_i], \overline{\sigma}) = \begin{cases} \text{true} & \text{if } p \in \overline{\sigma}[i] \\ \text{false} & \text{otherwise} \end{cases}$
- $\rho(-[x_i], \overline{\sigma}) = \begin{cases} \text{true} & \text{if } p \notin \overline{\sigma}[i] \\ \text{false} & \text{otherwise} \end{cases}$
- $\rho(\theta_1 \lor \theta_2, \overline{\sigma}) = \rho(\theta_1, \overline{\sigma}) \lor \rho(\theta_2, \overline{\sigma})$
- $\rho(\theta_1 \land \theta_2, \overline{\sigma}) = \rho(\theta_1, \overline{\sigma}) \lor \rho(\theta_2, \overline{\sigma})$
- $\rho(X_{\Gamma} \theta, \overline{\sigma}) = \rho((\theta, 1, \Gamma), \overline{\sigma})$
• \( \rho(\theta_1 U \Gamma \theta_2 \varnothing) = \rho(\theta_2, \varnothing) \lor (\rho(\theta_1, \varnothing) \land \rho((\theta_1 U \Gamma \theta_2, 1, \Gamma), \varnothing)) \)
• \( \rho(\theta_1 R \Gamma \theta_2 \varnothing) = \rho(\theta_2, \varnothing) \lor (\rho(\theta_1, \varnothing) \lor \rho((\theta_1 R \Gamma \theta_2, 1, \Gamma), \varnothing)) \)

For a pointed trace assignment \( \Pi = \{x_1 \mapsto (\pi_1, j_1), \ldots, x_n \mapsto (\pi_n, j_n)\} \) over \( \{x_1, \ldots, x_n\} \), we denote by \( \overline{\Pi} \) the \( n \)-tuple of traces \( (\pi_1, \ldots, \pi_n) \) and by \( \varphi(\Pi) \) the position vector \( (j_1, \ldots, j_n) \).

Given an \( n \)-tuple \( \overline{\Pi} = (\pi_1, \ldots, \pi_n) \) of traces, a position vector \( \varphi = (j_1, \ldots, j_n) \), and a state \( q \) of \( A_\psi \), a \((q, \varphi)\)-run of \( A_\psi \) over the input \( \overline{\Pi} \) is defined as a run of \( A_\psi \) over \( \overline{\Pi} \) but we require that the root of the run is labeled by the pair \((q, \varphi)\) (i.e., initially, the automaton is in state \( q \) and for each \( i \in [1, n] \) reads the \((j_i + 1)^{th}\) symbol of the trace \( \pi_i \)). By construction and a straightforward induction on the structure of the sub-formulas of \( \psi \), we obtain the following result, hence, Proposition III.2 directly follows.

Claim. Let \( \Pi \) be a pointed trace assignment over \( \{x_1, \ldots, x_n\} \) and \( \theta \) be a sub-formula of \( \psi \).

Then, there is an accepting \((\theta, \varphi(\Pi))\)-run of \( A_\psi \) over \( \overline{\Pi} \) if and only if \( \Pi \models \theta \).

\[ \square \]

C. Proof of Proposition III.4

Proposition III.4. One can build in time polynomial in the size of \( \mathcal{I} \) a finite Kripke structure \( K_\mathcal{I} \) over \( \mathsf{AP} \) satisfying the following conditions:

• the set of traces of \( K_\mathcal{I} \) contains the set of well-formed traces;
• each trace of \( K_\mathcal{I} \) having a suffix where \# always holds is a well-formed trace.

Proof. Essentially, at the unique initial state, \( K_\mathcal{I} \) non-deterministically chooses to generate symbol by symbol either a well-formed trace associated to the first tuple of \( \mathcal{I} \) (\( \ell = 1 \)) or a well-formed trace associated to the second tuple of \( \mathcal{I} \) (\( \ell = 2 \)). On generating (symbol by symbol) an infix \([u_i^\ell, p_i, q_i]\) with \( i \in [n] \) and \( \ell = 1, 2 \), \( K_\mathcal{I} \) keeps track in its state of the word \( u_i^\ell \), of \( \ell = 1, 2 \), and of the position \( 0 \leq h < |u_i^\ell| \) of the symbol in \( 2^{\mathsf{AP}} \) currently generated along the infix.

On generating the last symbol of this infix, \( K_\mathcal{I} \) non-deterministically chooses either to generate symbol by symbol another infix of the form \([u_i^\ell, p_j, q_\ell]\) for some \( j \in [n] \) or to move to a trap state \( s_f \) from which the suffix \( \{\#\}^\omega \) is generated.

Formally, \( K_\mathcal{I} = (S, \{s_0\}, E, V) \) where

• \( S \) consist of the following transitions:
  - \((s_0, (u_i^\ell, 0, 0))\) for all \( i \in [n] \) and \( \ell = 1, 2 \);  
  - \((u_i^\ell, \ell, h), (u_i^\ell, \ell, h + 1))\) for all \( i \in [n], \ell = 1, 2 \), and \( 0 \leq h < |u_i^\ell| - 1 \);  
  - \((u_i^\ell, \ell, |u_i^\ell| - 1), (u_j^\ell, \ell, 0))\) for all \( i, j \in [n] \) and \( \ell = 1, 2 \);  
  - \((u_i^\ell, \ell, |u_i^\ell| - 1), s_f)\) for all \( i \in [n] \) and \( \ell = 1, 2 \);  
  - \((s_f, s_f)\).

• The \( \mathsf{AP} \)-valuation \( V \) is defined as follows:
  - \( V(s_0) = V(s_f) = \{\#\} \);  
  - \( V((u_i^\ell, \ell, h)) = \{u_i^\ell(h, p_i, q_\ell)\} \) for all \( i \in [n], \ell = 1, 2 \), and \( 0 \leq h < |u_i^\ell| - 1 \);  
  - \( V((u_i^\ell, \ell, h)) = \{u_i^\ell(h, p_i, q_\ell, \#)\} \) for all \( i \in [n], \ell = 1, 2 \), and \( h = |u_i^\ell| - 1 \).  

\[ \square \]
D. Proof of Proposition III.5

Proposition III.5. Given a finite set \( \Gamma \) of LTL formulas over \( \text{AP} \), one can construct in singly exponential time a NBA \( A_\Gamma \) over \( 2^\text{AP} \), with \( 2^{O(|\text{AP}|)} \) states satisfying the following:
1) let \( w \in L(A_\Gamma) \): then for all \( i \geq 0 \) and \( \theta \in cl(\Gamma) \), \( at(\theta) \in w(i) \) if and only if \( ((w)_\text{AP},i) \models \theta \).
2) for each trace \( \pi \) (i.e., infinite word over \( 2^\text{AP} \)), there exists \( w \in L(A_\Gamma) \) such that \( \pi = (w)_\text{AP} \).

Proof. Here, we construct a generalized NBA \( A_\Gamma \) satisfying Properties (1) and (2) of Proposition III.5 which can be converted in linear time into an equivalent NBA. Recall that a generalized NBA is defined as a NBA but the acceptance condition is given by a family \( F = \{ \text{Acc}_1, \ldots , \text{Acc}_k \} \) of sets of accepting states. In this case, a run is accepting if for each accepting component \( \text{Acc}_i \in F \), the run visits infinitely often states in \( \text{Acc}_i \).

The generalized NBA \( A_\Gamma = (\text{AP}^+, Q, Q_0, \Delta, F) \) is defined as follows. \( Q \) is the set of atoms of \( \Gamma \) consisting of the maximal propositionally consistent subsets \( A \) of \( cl(\Gamma) \). Formally, an atom \( A \) of \( \Gamma \) is a subset of \( cl(\Gamma) \) satisfying the following:
- for each \( \theta \in cl(\Gamma) \), \( \theta \in A \) iff \( \neg \theta \notin A \);
- for each \( \theta_1 \land \theta_2 \in cl(\Gamma) \), \( \theta_1 \land \theta_2 \in A \) iff \( \theta_1, \theta_2 \in A \).

Each state is initial, i.e. \( Q_0 = Q \). For an atom \( A \), \( at(A) \) denotes the subset of propositions in \( \text{AP}^+ \) associated with the formulas in \( A \), i.e. \( at(A) \) \( \overset{\text{def}}{=} \{ at(\theta) \mid \theta \in A \} \).

The transition relation \( \Delta \) captures the semantics of the next modality, and the local fixpoint characterization of the until modality. Formally, \( \Delta \) consists of the transitions of the form \((A, at(A), A') \) such that:
- for each \( X \theta \in cl(\Gamma) \), \( X \theta \in A \) iff \( \theta \in A' \);
- for each \( \theta_1 \lor \theta_2 \in cl(\Gamma) \), \( \theta_1 \lor \theta_2 \in A \) iff either \( \theta_2 \in A \), or \( \theta_1 \in A \) and \( \theta_1 \lor \theta_2 \in A' \).

Finally, the generalized Büchi acceptance condition is used for ensuring the fulfillment of the liveness requirements \( \theta_2 \) in the until sub-formulas \( \theta_1 \lor \theta_2 \) in \( \Gamma \). Formally, for each \( \theta_1 \lor \theta_2 \in cl(\Gamma) \), \( F \) has a component consisting of the atoms \( A \) such that either \( \neg (\theta_1 \lor \theta_2) \in A \) or \( \theta_2 \notin A \).

Let \( w \in L(A_\Gamma) \). By construction, there is an accepting infinite sequence of atoms \( \rho = A_0 A_1 \ldots \) such that for all \( i \geq 0 \), \( w(i) = at(A_i) \). Let \( \pi \) be the projection of \( w \) over \( \text{AP} \) (note that \( A_i \cap \text{AP} = \pi(i) \) for all \( i \geq 0 \)). By standard arguments (see [24]), the following holds: for all \( i \geq 0 \) and \( \theta \in cl(\Gamma) \), \( \theta \in A_i \) (hence, \( at(\theta) \in w(i) \)) if and only if \( (\pi, i) \models \theta \). Hence, Property (1) of Proposition III.5 follows.

For Property (2), let \( \pi \) be a trace (i.e., an infinite word over \( 2^\text{AP} \)) and let \( \rho = A_0 A_1 \ldots \) be the infinite sequence of atoms defined as follows for all \( i \geq 0 \): \( A_i = \{ \theta \in cl(\Gamma) \mid (\pi, i) \models \theta \} \).

By construction and the semantics of LTL, \( \rho \) is an accepting run of \( A_\Gamma \) over the word \( w = at(A_0) at(A_1) \ldots \). Moreover, \( \pi \) coincides with the projection of \( w \) over \( \text{AP} \). Hence, the result follows.

E. Proof of Proposition III.7

Proposition III.7. Given an LTL formula \( \theta \) and a HyperLTL sentence \( \varphi \), one can construct in linear time a HyperLTL sentence \( \varphi_\theta \) having the same quantifier prefix as \( \varphi \) such that for each Kripke structure \( K \), \( L(K, \theta) \models \varphi \) if and only if \( L(K) \models \varphi_\theta \).
Proof. Let \( \theta \) be a LTL formula and \( \varphi \) be a HyperLTL sentence of the form
\[
Q_n x_n \ldots Q_1 x_1 . \psi
\]
where \( n \geq 1 \), \( Q_i \in \{ \exists, \forall \} \) for all \( i \in [1, n] \), and \( \psi \) is quantifier-free. Since \( \varphi \) is a sentence, we can assume that \( \text{VAR} = \{ x_1, \ldots, x_n \} \) where variables \( x_1, \ldots, x_n \) are pairwise distinct. For each \( i \in [1, n] \), we denote by \( \theta(x_i) \) the HyperLTL formula obtained from \( \theta \) by replacing each occurrence of an atomic proposition \( p \) in \( \theta \) with its HyperLTL version \( p[x_i] \) (referring to the trace associated with variable \( x_i \)).

Let \( \psi_0, \psi_1 \ldots \psi_n \) be the HyperLTL quantifier-free formulas inductively defined as follows: \( \psi_0 \overset{\text{def}}{=} \psi \) and for all \( i \in [1, n] \):
\[
\psi_i = \begin{cases} 
\theta(x_i) \land \psi_{i-1} & \text{if } Q_i = \exists \\
\theta(x_i) \rightarrow \psi_{i-1} & \text{otherwise}
\end{cases}
\]

Define \( \varphi_\theta \overset{\text{def}}{=} Q_n x_n \ldots Q_1 x_1 . \psi_n \). We show that for each Kripke structure \( \mathcal{K} \), \( L(\mathcal{K}, \theta) \models \varphi \) iff \( L(\mathcal{K}) \models \varphi_\theta \). Hence, the result follows. Since \( \varphi_\theta \) is a HyperLTL sentence, it suffices to show the following for a given Kripke structure \( \mathcal{K} \):

Claim. Let \( \Pi \) be a pointed trace assignment such that either \( L(\mathcal{K}, \theta) = \emptyset \) and \( \Pi \) is empty, or \( L(\mathcal{K}, \theta) \neq \emptyset \) and \( \Pi \) associates to each variable in \( \text{VAR} \) a pointed trace \((\pi, 0)\) such that \( \pi \in L(\mathcal{K}, \theta) \). Then, for each \( i \in [1, n] \), \( L(\mathcal{K}, \theta, \Pi) \models Q_i x_i . \ldots Q_1 x_1 . \psi \) iff \( L(\mathcal{K}, \Pi) \models Q_i x_i . \ldots Q_1 x_1 . \psi \).

Proof of the claim. The proof is by induction on \( i \in [1, n] \). We focus on the induction step (the base case where \( i = 1 \) being similar). Let \( i \in [2, n] \). We assume that \( Q_i = \forall \) and \( L(\mathcal{K}, \theta) \neq \emptyset \) (the case where \( Q_i = \exists \) or \( L(\mathcal{K}, \theta) = \emptyset \) being similar). Then,
\[
(L(\mathcal{K}, \theta), \Pi) \models Q_i x_i . \ldots Q_1 x_1 . \psi \iff
\]
for each \( \pi \in L(\mathcal{K}, \theta) \), \( (L(\mathcal{K}, \theta), \Pi[x_i \mapsto (\pi, 0)]) \models Q_i x_i . \ldots Q_1 x_1 . \psi \iff
\]
for each \( \pi \in L(\mathcal{K}, \theta) \), \( (L(\mathcal{K}, \Pi[x_i \mapsto (\pi, 0)]) \models Q_i x_i . \ldots Q_1 x_1 . \psi \iff
\]
for each \( \pi \in L(\mathcal{K}) \), \( (L(\mathcal{K}), \Pi[x_i \mapsto (\pi, 0)]) \models Q_i x_i . \ldots Q_1 x_1 . \psi \iff
\]
\( (L(\mathcal{K}), \Pi) \models Q_i x_i . \ldots Q_1 x_1 . \psi \)

The second equivalence directly follows from the induction hypothesis, while the third equivalence follows from the semantics of HyperLTL and the facts that \( x_1, \ldots, x_n \) are pairwise distinct and \( \psi_i = \theta(x_i) \rightarrow \psi_{i-1} \) when \( Q_i = \forall \). \( \square \)
A. Proof of Theorem IV.1 for the fragment $F$

We show that model checking against the fragment $F$ is undecidable. For the fixed Minsky 2-counter machine $M$ (see Subsection IV-A), the result directly follows from the following proposition.

**Proposition VII.1.** One can build a finite Kripke Structure $K_M$ and a HyperLTL$_C$ sentence $\varphi_M$ in the fragment $F_1$ such that $M$ halts iff $K_M \models \varphi_M$.

**Proof.** The proof is an adaptation of the proof of Proposition IV.1. We consider the set of atomic propositions exploited in the proof of Proposition IV.1, augmented with two additional propositions $\#$ and $\#'$ used to mark $c$-codes for $c \in \{1, 2\}$. Hence,

$$AP \overset{\text{def}}{=} \Delta \cup \{1, 2, \text{beg}_1, \text{beg}_2, \#, \#'\}$$

The notion of unmarked computation-code corresponds to the notion of computation-code in the proof of Proposition IV.1 while a marked computation-code $\pi$ corresponds to a computation-code but we, additionally, require that there are exactly two $c$-codes $\pi_c$ and $\pi'_c$ along $\pi$ for some $c \in \{1, 2\}$ marked by $\#$ and $\#'$, respectively, such that $\pi_c$ and $\pi'_c$ belongs to two adjacent configuration codes along $\pi$ with $\pi_c$ preceding $\pi'_c$.

By construction, it is a trivial task to define a Kripke structure $K_M$ satisfying the following.

**Claim.** One can construct in polynomial time a finite Kripke structure $K_M$ over $AP$ such that the set of traces of $K_M$ which visit some empty position (i.e., a position with label the empty set of propositions) corresponds to the set of initial and halting (marked and unmarked) computation-codes.

The HyperLTL$_C$ formula $\varphi_M$ in the fragment $F_1$ is defined as follows:

$$\varphi_M \overset{\text{def}}{=} \exists x_1. \forall x_2. G \neg \#[x_1] \land \bigwedge_{p \in AP} \neg p[x_1] \land$$

$$(F \#'[x_2] \land F \bigwedge_{p \in AP} \neg p[x_2] \land G \bigwedge_{p \in AP \{\#, \#'} (p[x_1] \leftrightarrow p[x_2])) \rightarrow \psi'_\text{good}$$

where the HyperLTL$_C$ quantifier-free sub-formula $\psi'_\text{good}$ is defined in the following. Intuitively, when interpreted on the Kripke structure $K_M$ of the previous claim, formula $\varphi_M$ asserts the existence of a trace $\pi_1$ (bounded to the trace variable $x_1$) such that $\pi_1$ is an unmarked initial and halting computation-code and for each trace $\pi_2$ (bounded to the trace variable $x_2$) so that $\pi_2$ is some marked version of $\pi_1$, $\pi_2$ satisfies (by means of the conjunct $\psi'_\text{good}$) the goodness requirement applied to the marked $c$-codes of $\pi_2$ for some $c \in \{1, 2\}$. Since variable $x_2$ is universally quantified, this ensures that $\pi_1$ is also good.

The quantifier-free HyperLTL$_C$ formula $\psi'_\text{good}$ is defined as follows:

$$\psi'_\text{good} \overset{\text{def}}{=} G \bigwedge_{\delta \in \Delta \setminus \Delta_{\text{abs}}} \bigwedge_{c \in \{1, 2\}} (\delta[x_1] \land \text{beg}_c[x_1] \land \#'[x_2]) \rightarrow$$

$$\langle \{x_2\} \rangle F (\text{beg}_c[x_2] \land \#'[x_2] \land (\langle x_1, x_2 \rangle) (\psi_=(\delta, c) \land \psi_{\text{inc}}(\delta, c) \land \psi_{\text{dec}}(\delta, c)))$$
where the sub-formulas $\psi_=(\delta, c)$, $\psi_{inc}(\delta, c)$, and $\psi_{dec}(\delta, c)$ are defined as in the proof of Proposition IV.1.

B. Detailed proof of Proposition IV.2

Proposition IV.2. Given a HyperLTL$_C$ quantifier-free formula $\psi$ with trace variables $x_1, \ldots, x_n$, one can build in polynomial time a Büchi nAABA $A_\psi$ such that $L(A_\psi)$ is the set of $n$-tuples $(\pi_1, \ldots, \pi_n)$ of traces so that $(\{x_1 \mapsto (\pi_1, 0), \ldots, x_1 \mapsto (\pi_n, 0)\}, \{x_1, \ldots, x_n\}) \models \psi$. Moreover, $A_\psi$ is $(|\psi|+1)$-synchronous if $\psi$ is in the bounded fragment of HyperLTL$_C$.

Proof. By exploiting the release modality $R$ (the dual of the until modality), both conjunction and disjunction, and the fact that a formula $\neg\langle C \rangle \theta$ corresponds to $\langle C \rangle \neg \theta$, we can assume without loss of generality that $\psi$ is in negative normal form, i.e. negation is applied only to relativized atomic propositions.

For each $i \in [1, n]$, we write $dir(x_i)$ to mean the direction $i$. Moreover, for each context $C \subseteq \{x_1, \ldots, x_n\}$, we denote by $fst(C)$ (resp., $lst(C)$) the smallest (resp., greatest) variable occurring in $C$ with respect to the fixed ordering $x_1 < \ldots < x_n$. Additionally, for each $x \in C \setminus \{lst(C)\}$, we denote by $succ(C, x)$ the smallest variable in $C$ which is greater than $x$. The Büchi nAABA $A_\psi = \langle 2^\text{AP}, Q, q_0, \rho, F \rangle$ is defined as follows. The set $Q$ of states is the set of triples $(\theta, C, x)$ such that $\theta$ is a sub-formula of $\psi$, $C$ is a context such that some occurrence of $\theta$ in $\psi$ is in the scope of the context modality $\langle C \rangle$, and $x \in C$. The initial state $q_0$ is given by $(\psi, \{x_1, \ldots, x_n\}, x_n)$, while the set $F$ of accepting states consists of the states of the form $(\theta_1 R \theta_2, C, last(C))$.

Finally, the transition function $\rho$ is defined by induction on the structure of the sub-formulas $\theta$ of $\psi$ as follows, where for each $\overline{\sigma} \in (2^{\text{AP}})^n$ and $i \in [1, n]$, $\overline{\sigma}[i]$ denotes the $i^{th}$ component of $\overline{\sigma}$:

- for $x \neq last(C)$, $\rho((\theta, C, x), \overline{\sigma}) = ((\theta, C, succ(C, x)), dir(succ(C, x)))$
- $\rho((p[x], C, lst(C)), \overline{\sigma}) = \begin{cases} \text{true} & \text{if } p \in \overline{\sigma}[dir(x)] \\ \text{false} & \text{otherwise} \end{cases}$
- $\rho((\neg p[x], C, lst(C)), \overline{\sigma}) = \begin{cases} \text{true} & \text{if } p \notin \overline{\sigma}[dir(x)] \\ \text{false} & \text{otherwise} \end{cases}$
- $\rho((\theta_1 \lor \theta_2, C, lst(C)), \overline{\sigma}) = \rho((\theta_1, C, lst(C)), \overline{\sigma}) \lor \rho((\theta_2, C, lst(C)), \overline{\sigma})$
- $\rho((\theta_1 \land \theta_2, C, lst(C)), \overline{\sigma}) = \rho((\theta_1, C, lst(C)), \overline{\sigma}) \land \rho((\theta_2, C, lst(C)), \overline{\sigma})$
- $\rho((\langle\theta \rangle C, C, lst(C)), \overline{\sigma}) = ((\theta, C, fst(C)), dir(fst(C)))$
- $\rho((\theta_1 U \theta_2, C, lst(C)), \overline{\sigma}) = \rho((\theta_2, C, lst(C)), \overline{\sigma}) \lor [\rho((\theta_1, C, lst(C)), \overline{\sigma}) \land ((\theta_1 U \theta_2, C, fst(C)), dir(fst(C)))]
- $\rho((\theta_1 R \theta_2, C, lst(C)), \overline{\sigma}) = \rho((\theta_2, C, lst(C)), \overline{\sigma}) \land [\rho((\theta_1, C, lst(C)), \overline{\sigma}) \lor ((\theta_1 R \theta_2, C, fst(C)), dir(fst(C)))]
- $\rho((\langle C' \rangle \theta, C, lst(C)), \overline{\sigma}) = \rho((\theta, C', lst(C')), \overline{\sigma})$

We first show that if the given quantifier-free formula $\psi$ in NNF is in the bounded fragment of HyperLTL$_C$, then $A_\psi$ is a $(|\psi|+1)$-synchronous nAABA. By construction, whenever the automaton is in a state associated with a sub-formula $\theta$ of $\psi$, then $A_\psi$ can move only to states
associated with $\theta$ or with strict sub-formulas of $\theta$. In particular, each path in a run of $A_\psi$ can be factorized into a finite number $v_1, \ldots, v_k$ of contiguous segments (with $v_k$ possibly infinite) such that for each $i \in [1, k]$, segment $v_i$ is associated with a sub-formula $\theta_i$ of $\psi$ and a context $C_i$ occurring in $\psi$, and the following holds, where the offset of a position vector $\varphi = (j_1, \ldots, j_n)$ in $\mathbb{N}^n$ is the maximum over the differences between pairs of components, i.e. $\max\{j_\ell - j_{\ell'} \mid \ell, \ell' \in [1, n]\}$:

- there is some occurrence of $\theta_i$ in $\psi$ which is in the scope of the context modality $\langle C_i \rangle$;
- if $i < k$, then $\theta_{i+1}$ is a strict sub-formula of $\theta_i$;
- if either $C_i$ is global or the root modality of $\theta_i$ is not in $\{U, R\}$, then the offset at each node along the segment $v_i$ and at the first node of $v_{i+1}$ if $i < k$ is at most the offset at the beginning of $v_i$ plus one.

Hence, if $\psi$ is in the bounded fragment of HyperLTL$_C$, the offset at each node of a run is at most $|\psi| + 1$ and the result directly follows.

It remains to prove the correctness of the construction. For this, we need additional notation. For a position vector $\varphi = (j_1, \ldots, j_n)$ and a context $C \subseteq \{x_1, \ldots, x_n\}$, we denote by $\varphi +_C 1$ the position vector $(j'_1, \ldots, j'_n)$ defined as follows for all $i \in [1, n]$: $j'_i = j_i + 1$ if $x_i \in C$ and $j'_i = j_i$ otherwise.

For a pointed trace assignment $\Pi = \{x_1 \mapsto (\pi_1, j_1), \ldots, x_n \mapsto (\pi_n, j_n)\}$ over $\{x_1, \ldots, x_n\}$, we denote by $\overline{\Pi}$ the $n$-tuple of traces $(\pi_1, \ldots, \pi_n)$ and by $\varphi(\Pi)$ the position vector $(j_1, \ldots, j_n)$. Given an $n$-tuple $\pi = (\pi_1, \ldots, \pi_n)$ of traces, a position vector $\varphi = (j_1, \ldots, j_n)$, and a state $q$ of $A_\psi$, a $(q, \varphi)$-run of $A_\psi$ over the input $\pi$ is defined as a run of $A_\psi$ over $\varphi$ but we require that the root of the run is labeled by the pair $(q, \varphi)$ (i.e., initially, the automaton is in state $q$ and for each $i \in [1, n]$ reads the $(j_i + 1)^{th}$ symbol of the trace $\pi_i$). By construction and a straightforward induction on the structure of the sub-formulas of $\psi$, we obtain the following result, hence, Proposition [IV.2] directly follows.

**Claim.** Let $\Pi$ be a pointed trace assignment over $\{x_1, \ldots, x_n\}$ and $(\xi, C, \text{lst}(C))$ be a state of $A_\psi$. Then, there is an accepting $((\xi, C, \text{lst}(C)), \varphi(\Pi))$-run of $A_\psi$ over $\overline{\Pi}$ if and only if $(\Pi, C) \models \xi.$

\[\square\]

### C. Proof of the claim in the proof of Theorem [IV.2]

In this section, we establish the following result (corresponding to the claim in the proof of Theorem [IV.2]).

**Lemma VII.1.** Let $\mathcal{AP} = \{p\}$ and $n > 1$. One construct in time polynomial in $n$ a bounded HyperLTL$_C$ formula $\psi(x, y)$ with two free variables $x$ and $y$ and not containing universal quantifiers (hence, the quantifier alternation depth is 0) such that for all traces $\pi_x$ and $\pi_y$, $\{x \mapsto (\pi_x, 0), y \mapsto (\pi_y, 0)\} \models \psi(x, y)$ iff

- $p$ occurs exactly once on $\pi_x$ (resp., $\pi_y$);
- for each $i \geq 1$, $p \in \pi_x(i)$ iff $p \in \pi_y(i + n \ast 2^n + 2^n)$.

**Proof.** We encode a yardstick of length $n \ast 2^n \ast 2^n$ by using a $2^n$-bit counter for expressing integers in the range $[0, 2^{2^n} - 1]$ and an $n$-bit counter for keeping track of the position (index) $i \in [0, 2^n - 1]$ of the $(i + 1)^{th}$ bit of each valuation $v$ of the $2^n$-bit counter. In particular, such a
valuation \( v \in [0, 2^{2^n} - 1] \) is encoded by a sequence, called 2-block, of \( 2^n \) sub-blocks of length \( n \) where for each \( i \in [0, 2^n - 1] \), the \((i + 1)^{th}\) sub-block encodes both the value and the index of the \((i + 1)^{th}\)-bit in the binary representation of \( v \). To this purpose, we exploit additional trace variables (existentially quantified):

- the trace variable \( x_{bl} \), for encoding the bit indexes \( i \in [0, 2^n - 1] \) of the \( 2^n \)-bit counter by sequences of \( n \) bits (1-blocks) and the trace variable \( x_{\#} \), for separating 1-blocks: \( p[x_{\#}] \) holds exactly at the beginning of each 1-block;
- the trace variable \( x_{bl_2} \), for encoding the bit values of the \( 2^n \)-bit counter: in particular, \( p[x_{bl_2}] \) can hold only at the beginning of a 1-block;
- the trace variable \( x_{\#_2} \), for separating 2-blocks: \( p[x_{\#_2}] \) holds exactly at the beginning of each 2-block.

The formula \( \psi(x, y) \) ensures that the segment between the unique position where \( p[x] \) holds and the unique position where \( p[y] \) holds (the latter excluded) is a sequence of \( 2^n \) 2-blocks such that the first block encodes the \( 2^n \)-counter valuation 0, and the \( 2^n \)-counter is incremented on moving from a 2-block to the next one. We assume that the first bit of the \( n \)-bit counter (resp., \( 2^n \)-bit counter) is the least significant one. Moreover, in order to ensure that the \( 2^n \)-counter is correctly updated, we exploit \( n \) additionally existentially quantified trace variables \( x_1, \ldots, x_n \) where for each \( j \in [1, n] \), \( p[x_j] \) holds exactly at the beginning of each 1-block. The meaning of such variables will be explained later. Formally, the bounded HyperLTL formula \( \psi(x, y) \) is defined as follows:

\[
\psi(x, y) \equiv \exists x_{\#_1}, \exists x_{\#_2}, \exists x_{bl_1}, \exists x_{bl_2}, \exists x_1, \ldots, \exists x_n, \\
\psi_{unique} \land \psi_{align} \land \psi_{com} \land \psi_{bl_2} \land \psi_{first} \land \psi_{last} \land \psi_{inc}
\]

where the various conjuncts are quantifier-free formulas defined in the following (in particular, all the conjuncts but \( \psi_{inc} \) are HyperLTL quantifier-free formulas). For each trace variable \( z \) and \( b \in \{0, 1\} \), we write \( p[z] = b \) to mean the formula \( p[z] \) if \( b = 1 \), and the formula \( \neg p[z] \) otherwise.

**Definition of \( \psi_{unique} \).** \( \psi_{unique} \) requires that \( p[x] \) and \( p[y] \) hold exactly once with \( p[x] \) strictly preceding \( p[y] \).

\[
\psi_{unique} \equiv F(p[x] \land XFp[y]) \land \bigwedge_{z \in \{x, y\}} G(p[z] \rightarrow XG(\neg p[z]))
\]

**Definition of \( \psi_{align} \).** \( \psi_{align} \) requires that (i) at the positions where \( p[x] \) and \( p[y] \) hold, \( p[x_{\#_1}] \) and \( p[x_{\#_2}] \) hold as well, (ii) \( p[x_{\#_1}] \) and \( p[x_{\#_2}] \) do not hold at positions preceding \( p[x] \) and following \( p[y] \), (iii) \( p[x_{bl_2}] \) can hold only where \( p[x_{\#_1}] \) holds, and (iv) for each \( i \in [1, n] \), \( p[x_i] \) holds exactly
where \( p[x_{#i}] \) holds.

\[
\psi_{\text{align}} \overset{\text{def}}{=} \bigwedge_{j \in \{1,2\}} \neg p[x_{#j}] \cup \left( p[x_{#j}] \land p[x] \land F(p[x_{#j}] \land p[y] \land XG \neg p[x_{#j}]) \right) \land \\
G(p[x_{bl_2}] \rightarrow p[x_{#1}]) \land \bigwedge_{i=1}^{i=n} G(p[x_i] \leftrightarrow p[x_{#i}])
\]

**Definition of \( \psi_{\text{con}} \).** \( \psi_{\text{con}} \) ensures that the segment between \( p[x] \) and \( p[y] \) (the \( p[y] \)-position excluded) is the concatenation of segments of length \( n \) (1-blocks) and \( p[x_{#i}] \) holds exactly at the beginning of each of such segments.

\[
\psi_{\text{con}} \overset{\text{def}}{=} G(p[x_{#1}] \rightarrow \bigwedge_{i=1}^{i=n-1} X^i \neg p[x_{#1}] \land (p[y] \lor X^n p[x_{#1}]])
\]

**Definition of \( \psi_{bl_2} \).** \( \psi_{bl_2} \) ensures that each segment \( \nu \) between two consecutive \( p[x_{#z}] \)-positions (the last position of \( \nu \) excluded) encodes a 2-block, i.e. (i) the first 1-block of \( \nu \) encodes 0, (ii) the last 1-block of \( \nu \) encodes \( 2^n - 1 \), and (iii) in moving along \( \nu \) from a 1-block to the next one, the \( n \)-bit counter is incremented.

\[
\psi_{bl_2} \overset{\text{def}}{=} G(p[x_{#z}] \rightarrow p[x_{#1}] \land G((p[x_{#z}] \land \neg p[y]) \rightarrow (\bigwedge_{i=0}^{i=n-1} X^i \neg p[x_{bl_1}] \land \theta_{last}) \land \theta_{inc})
\]

\[
\theta_{last} \overset{\text{def}}{=} X[-p[x_{#z}] \cup (-p[x_{#z}] \land p[x_{#1}] \land \bigwedge_{i=0}^{i=n-1} X^i p[x_{bl_1}] \land X^n p[x_{#2}])]
\]

\[
\theta_{inc} \overset{\text{def}}{=} G((p[x_{#1}] \land X^n (p[x_{#1}] \land \neg p[x_{#z}])) \rightarrow \\
\bigvee_{i=0}^{i=n-1} (X^i \theta(0, 1) \land \bigwedge_{j=0}^{j=i-1} X^j \theta(1, 0) \land \bigwedge_{j=i+1}^{j=n-1} X^j \theta(0, 0)) \big)
\]

\[
\theta(b, b') \overset{\text{def}}{=} p[x_{bl_1}] = b \land X^n p[x_{bl_1}] = b'
\]

**Definition of \( \psi_{\text{first}} \).** \( \psi_{\text{first}} \) requires that the first 2-block encodes 0.

\[
\psi_{\text{first}} \overset{\text{def}}{=} G(p[x] \rightarrow (-p[x_{bl_2}] \land X((-p[x_{#z}] \land (p[x_{#1}] \rightarrow -p[x_{bl_2}]) \lor p[x_{#2}])))
\]

**Definition of \( \psi_{\text{last}} \).** \( \psi_{\text{last}} \) requires that the last 2-block encodes \( 2^n - 1 \).

\[
\psi_{\text{last}} \overset{\text{def}}{=} G(X(-p[x_{#z}] \cup p[y]) \rightarrow (p[x_{#1}] \rightarrow p[x_{bl_2}]))
\]

**Definition of \( \psi_{\text{inc}} \).** Formula \( \psi_{\text{inc}} \) ensures that in moving from a non-last 2-block \( bl \) to the next one \( bl' \), the \( 2^n \)-counter is incremented. This is equivalent to require that there is a 1-block \( sbl_0 \) of \( bl \) whose bit value (i.e., the Boolean value of \( p[x_{bl_1}] \)) at the beginning of \( sbl_0 \) is 0 such that for each 1-block \( sbl \) of \( bl \), denoted by \( sbl' \) the 1-block of \( bl' \) having the same \( n \)-bit counter valuation as \( sbl \), the following holds: (i) if \( sbl \) precedes \( sbl_0 \), then the bit value of \( sbl \) (resp., \( sbl' \)) is 1 (resp., 0), (ii) if \( sbl \) corresponds to \( sbl_0 \), then the bit value of \( sbl' \) is 1, and (iii) if \( sbl \) follows \( sbl_0 \), then there is \( b \in \{0, 1\} \) such that the bit value of both \( sbl \) and \( sbl' \) is \( b \). The definition of \( \psi_{\text{inc}} \) is the crucial part of the construction, where we exploit the context modalities (in a bounded way) and the trace variables \( x_1, \ldots, x_n \). The definition of \( \psi_{\text{inc}} \) is based on the construction of
auxiliary formulas $\psi_{\pm}(b,b')$ where $b,b' \in \{0,1\}$. Formula $\psi_{=}(b,b')$ holds at a position $h$ (along all the current traces) iff whenever $h$ corresponds to the beginning of a 1-block $sbl$ of a 2-block $bl$, then (i) the bit value of $sbl$ is $b$, (ii) the 2-block $bl$ is followed by a 2-block $bl'$, and (iii) the 1-block of $bl'$ having the same $n$-bit counter valuation as $sbl$ has bit value $b'$. For expressing this requirement, from the current position $h$ (along all the current traces) associated to the first position of a 1-block $sbl$ (a $p[x_{#1}]$-position) of a non-last 2-block $bl$, we exploit the non-global context modality $\langle \{x_i\}\rangle$, for each $i \in [1,n]$, for ensuring that the local position along the trace for $x_i$ moves one position to the right if and only if the $i^{th}$-bit of $sbl$ along the trace for $x_{bl_i}$ is 0 (recall that $p[x_i]$ holds exactly at the first positions of 1-blocks and $n > 1$). Then, by exploiting the global context modality and temporal modalities, we require that the local positions of all the traces move forward synchronously step by step until the local position of the trace for variable $x_{bl_i}$ corresponds to the first position of a 1-block $sbl'$ of the 2-block $bl'$ following $bl$. At this point, in order to check that $sbl$ and $sbl'$ have the same counter valuation, it suffices to check that the current Boolean value of $p[x_i]$ corresponds to the $i^{th}$ bit of $sbl'$ for each $i \in [1,n]$.

In order to define $\psi_{=}(b,b')$, we first define the auxiliary quantifier-free formulas $\theta_1(b), \ldots, \theta_n(b)$ by induction on $n - i$ where $i \in [0,n-1]$.

\[
\theta_n(b) \overset{\text{def}}{=} \langle \{x_n\}\rangle [X(\xi(b) \land \langle \{x_{bl_i}\}\rangle) X^{n-1}p[x_{bl_1}]) \lor (\chi(b) \land \langle \{x_{bl_i}\}\rangle X^n)]
\]

\[
\xi(b) \overset{\text{def}}{=} \langle \text{VAR} \rangle X(\neg p[x_{#1}] \lor (p[x_{#2}] \land (\chi(b) \lor X(\neg p[x_{#2}] \land \chi(b)))))
\]

\[
\chi(b) \overset{\text{def}}{=} p[x_{#1}] \land p[x_{bl_2}] = b \land \bigwedge_{i=1}^{n-1} (p[x_i] \leftrightarrow X^{i-1}p[x_{bl_i}])
\]

Moreover, for each $j \in [1,n-1]$, formula $\theta_j(b)$ is defined as follows:

\[
\theta_j(b) \overset{\text{def}}{=} \langle \{x_j\}\rangle [X(\theta_{j+1}(b) \land \langle \{x_{bl_i}\}\rangle) X^{j-1}p[x_{bl_1}]) \lor (\theta_{j+1}(b) \land \langle \{x_{bl_i}\}\rangle X^j)]
\]

Then, for all $b,b' \in \{0,1\}$, the quantifier-free formula $\psi_{=} (b,b')$ is given by

\[
\psi_{=} (b,b') \overset{\text{def}}{=} p[x_{#1}] \rightarrow (\theta_1(b') \land p[x_{bl_2}] = b)
\]

Finally, formula $\psi_{inc}$ is defined as follows:

\[
\psi_{inc} := G(p[x_{#1}] \land X F(p[x_{#2}] \land \neg p[y])) \rightarrow ((\psi_{=}(0,1) \land \eta) \lor (\psi_{=}(1,0) \land X((-p[x_{#2}] \land \psi_{=}(1,0)) \lor \neg p[x_{#2}] \land (p[x_{#1}] \land \psi_{=}(0,1) \land \eta))))
\]

\[
\eta := X((-p[x_{#2}] \land p[x_{#3}] = (b,b)) \lor p[x_{#2}])
\]

Note that the number of distinct sub-formulas of $\psi(x,y)$ is polynomial in $n$. \qed