Hamiltonian Multivector Fields and Poisson Forms in Multisymplectic Field Theory

Michael Forger\textsuperscript{1}, Cornelius Paufler\textsuperscript{2} and Hartmann Römer\textsuperscript{3}

\textsuperscript{1} Departamento de Matemática Aplicada, Instituto de Matemática e Estatística, Universidade de São Paulo, Caixa Postal 66281, BR–05315-970 São Paulo, S.P., Brazil

\textsuperscript{2} Matematisk Fysik / Alba Nova Kungliga Tekniska Högskolan SE–10691 Stockholm, Sweden

\textsuperscript{3} Fakultät für Mathematik und Physik Physikalisches Institut Albert-Ludwigs-Universität Freiburg im Breisgau Hermann-Herder-Straße 3 D–79104 Freiburg i.Br., Germany

Abstract

We present a general classification of Hamiltonian multivector fields and of Poisson forms on the extended multiphase space appearing in the geometric formulation of first order classical field theories. This is a prerequisite for computing explicit expressions for the Poisson bracket between two Poisson forms.

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\textsuperscript{1}E-mail address: forger@ime.usp.br
\textsuperscript{2}E-mail address: pcp@theophys.kth.se
\textsuperscript{3}E-mail address: hartmann.roemer@physik.uni-freiburg.de
1 Introduction and General Setup

The present paper is a continuation of previous work on Poisson brackets of differential forms in the multiphase space approach to classical field theory [1, 2]. Our aim is to specialize the general constructions of Ref. [2] from abstract (exact) multisymplectic manifolds to the extended multiphase spaces of field theory, which at present seem to be the only known examples of multisymplectic manifolds, to clarify the structure of Hamiltonian multivector fields, of Hamiltonian forms and of Poisson forms on these spaces and to give explicit formulas for the Poisson bracket between the latter introduced in Refs [1, 2].

The structure of the article is as follows. In the remainder of this introduction, we briefly review the geometric constructions needed in the paper. We put particular emphasis on the consequences that arise from the existence of a certain vector field, the scaling or Euler vector field. Also, we fix the notation to be used in what follows. In Section 2, we present an explicit classification of locally Hamiltonian multivector fields on extended multiphase space in terms of adapted local coordinates and, following the logical inclusion from locally Hamiltonian to (globally) Hamiltonian to exact Hamiltonian multivector fields, show how the last two are situated within the first. Section 3 is devoted to the study of Hamiltonian forms and Poisson forms that are associated with (globally) Hamiltonian multivector fields. In Section 4, we use the outcome of our previous analysis to derive expressions for the Poisson bracket between two Poisson forms. In Section 5, we summarize our main conclusions and comment on the relation of our results to other approaches, as well as on perspectives for future research. Finally, in order to make the article self-contained, we include in an appendix a proposition that is not new but is needed in some of the proofs.

We begin with a few comments on the construction of the extended multiphase space of field theory [3–7], which starts out from a given general fiber bundle over space-time, with base space $M$ (dim $M = n$), total space $E$, bundle projection $\pi : E \to M$ and typical fiber $Q$ (dim $Q = N$). It is usually referred to as the configuration bundle since its sections constitute the possible field configurations of the system. (Of course, the manifold $M$ represents space-time, whereas the manifold $Q$ plays the role of a configuration space.) The extended multiphase space, which we shall simply denote by $P$, is then the total space of a larger fiber bundle over $M$ and in fact the total space of a vector bundle over $E$ which can be defined in several equivalent ways, e.g., by taking the twisted affine dual $J^\circ E$ of the first order jet bundle $JE$ of $E$ or by taking the bundle $\bigwedge^n_{n-1} T^* E$ of $(n-1)$-horizontal $n$-forms on $E$; see [2,5,7] for details. Therefore, there is a natural class of local coordinate systems on $P$, namely those that arise from combining fiber bundle charts of $E$ over $M$ with vector bundle charts of $P$ over $E$: these so-called adapted local coordinates $(x^\mu, q^i, p^\mu_i, p)$ are completely fixed by specifying local coordinates $x^\mu$ for $M$ (the space-time coordinates), local coordinates $q^i$ for $Q$ (the position variables) and a local trivialization of $E$ over $M$, and are such that the induced local coordinates $p^\mu_i$ (the multimomentum variables) and $p$ (the energy
variable) are linear along the fibers of $P$ over $E$. For details, we refer to Ref. [2], where one can also find the explicit transformation law for the multimomentum variables and the energy variable induced by a change of the space-time coordinates, of the position variables and of the local trivialization.

A first important feature of the extended multiphase space $P$ is that it carries a naturally defined multicanonical form $\theta$ whose exterior derivative is, up to a sign, the multisymplectic form $\omega$:

$$\omega = -d\theta.$$  \hspace{1cm} (1)

The global construction can be found in Refs [2,5,7], so we shall just state their explicit form in adapted local coordinates:

$$\theta = p_i^\mu dq^i \wedge d^n x_\mu + p d^n x.$$  \hspace{1cm} (2)

$$\omega = dq^i \wedge dp_i^\mu \wedge d^n x_\mu - dp \wedge d^n x.$$  \hspace{1cm} (3)

Here, we have already employed part of the following conventions concerning local differential forms defined by a system of adapted local coordinates, which will be used systematically throughout this paper:

$$d^n x = dx^1 \wedge \ldots \wedge dx^n,$$  \hspace{1cm} (4)

$$d^n x_\mu = i_{\partial_\mu} d^n x = (-1)^{\mu-1} dx^1 \wedge \ldots \wedge dx^{\mu-1} \wedge dx^{\mu+1} \wedge \ldots \wedge dx^n,$$  \hspace{1cm} (5)

$$d^n x_{\mu\nu} = i_{\partial_\mu} i_{\partial_\nu} d^n x \ldots d^n x_{\mu_1 \ldots \mu_r} = i_{\partial_{\mu_1}} \ldots i_{\partial_{\mu_r}} d^n x.$$  \hspace{1cm} (6)

This implies

$$i_{\partial_\mu} d^n x_{\mu_1 \ldots \mu_r} = d^n x_{\mu_1 \ldots \mu_r},$$  \hspace{1cm} (7)

whereas

$$dx^\kappa \wedge d^n x_\mu = \delta^\kappa_\mu d^n x,$$  \hspace{1cm} (8)

$$dx^\kappa \wedge d^n x_{\mu\nu} = \delta^\kappa_\nu d^n x_\mu - \delta^\kappa_\mu d^n x_\nu,$$  \hspace{1cm} (9)

$$dx^\kappa \wedge d^n x_{\mu_1 \ldots \mu_r} = \sum_{s=1}^r (-1)^{r-s} \delta^\kappa_{\mu_s} d^n x_{\mu_1 \ldots \mu_{s-1} \mu_{s+1} \ldots \mu_r}.$$  \hspace{1cm} (10)

For later use, we also recall the definition of the Lie derivative of a differential form $\alpha$ along an $r$-multivector field $X$,

$$L_X \alpha = d i_X \alpha - (-1)^r i_X d\alpha,$$  \hspace{1cm} (11)
which leads to the following relations, valid for any differential form \( \alpha \) and any two multivector fields \( X \) and \( Y \) of tensor degrees \( r \) and \( s \), respectively,

\[
d L_X \alpha = (-1)^{r-1} L_X d \alpha ,
\]

\[
i_{[X,Y]} \alpha = (-1)^{(r-1)s} L_X i_Y \alpha - i_Y L_X \alpha ,
\]

\[
L_{[X,Y]} \alpha = (-1)^{(r-1)(s-1)} L_X L_Y \alpha - L_Y L_X \alpha ,
\]

\[
L_X \wedge Y \alpha = (-1)^s i_Y L_X \alpha + L_Y i_X \alpha ,
\]

where \([X, Y]\) denotes the Schouten bracket of \( X \) and \( Y \). For decomposable multivector fields \( X = X_1 \wedge \ldots \wedge X_r \) and \( Y = Y_1 \wedge \ldots \wedge Y_s \), it can be defined in terms of the Lie bracket of vector fields according to the formula

\[
[X, Y] = \sum_{i=1}^{r} \sum_{j=1}^{s} (-1)^{i+j} [X_i, X_j] \wedge X_1 \wedge \ldots \hat{X_i} \ldots \wedge X_r \wedge Y_1 \wedge \ldots \hat{Y_j} \ldots \wedge Y_s ,
\]

where as usual the hat over a symbol denotes its omission. We shall also write

\[
L_X Y = [X, Y] ,
\]

for any two multivector fields \( X \) and \( Y \). For properties of the Schouten bracket, we refer to [8]. A proof of the above identities relating the Schouten bracket and the Lie derivative of forms along multivector fields can be found in the appendix of Ref. [2].

A second property of the extended multiphase space \( P \) which provides additional structures for tensor calculus on this manifold is that it is the total space of a fiber bundle, which implies that we may speak of vertical vectors and horizontal covectors. In fact, it is so in no less than three different ways. Namely, \( P \) is the total space of a fiber bundle over \( M \) (with respect to the so-called source projection), the total space of a vector bundle over \( E \) (with respect to the so-called target projection) and the total space of an affine line bundle over the ordinary multiphase space \( P_0 \) [2]. Therefore, the notions of verticality for multivector fields and of horizontality for differential forms on \( P \) admit different interpretations, depending on which projection is used. In any case, one starts by defining tangent vectors to the total space of a fiber bundle to be vertical if they are annihilated by the tangent map to the bundle projection, or what amounts to the same thing, if they are tangent to the fibers. Dually, a \( k \)-form on the total space of a fiber bundle is said to be \( l \)-horizontal if it vanishes whenever one inserts at least \( k - l + 1 \) vertical tangent vectors; the standard horizontal forms are obtained by taking \( l = k \). Finally, an \( r \)-multivector on the total space of a fiber bundle is said to be \( s \)-vertical if its contraction with any \((r - s + 1)\)-horizontal form vanishes. It is not difficult to show that these definitions are equivalent to requiring that, locally, an \( l \)-horizontal \( k \)-form should be a sum of exterior products of \( k \) one-forms, among which there are at least \( l \) horizontal ones, and that an \( s \)-vertical \( r \)-multivector field should be a sum of exterior products of \( r \) tangent vectors, among which there are at least \( s \) vertical ones.
Using this rule, properties of verticality for multivectors or horizontality for forms are easily derived from the corresponding properties for vectors or one-forms, respectively, which in the case of the extended multiphase space $P$ and in adapted local coordinates $(x^\mu, q^i, p_\mu^i, p^i)$ are summarized in Tables 1 and 2 below.

In what follows, the terms “vertical” and “horizontal” will usually refer to the source projection, except when explicitly stated otherwise.

| Tangent vectors | vertical with respect to the projection onto $P_0$ | vertical with respect to the target projection onto $E$ | vertical with respect to the source projection onto $M$ |
|-----------------|---------------------------------|---------------------------------|---------------------------------|
| $\frac{\partial}{\partial p}$ | yes | yes | yes |
| $\frac{\partial}{\partial p_\mu^i}$ | no | yes | yes |
| $\frac{\partial}{\partial q^i}$ | no | no | yes |
| $\frac{\partial}{\partial x^\mu}$ | no | no | no |

Table 1: Verticality of tangent vectors on extended multiphase space

| One-forms | horizontal with respect to the projection onto $P_0$ | horizontal with respect to the target projection onto $E$ | horizontal with respect to the source projection onto $M$ |
|-----------|---------------------------------|---------------------------------|---------------------------------|
| $dp$ | no | no | no |
| $dp_\mu^i$ | yes | no | no |
| $dq^i$ | yes | yes | no |
| $dx^\mu$ | yes | yes | yes |

Table 2: Horizontality of cotangent vectors on extended multiphase space
A third important feature of the extended multiphase space $P$ is that it carries a naturally defined vector field $\Sigma$, the scaling vector field or Euler vector field, which exists on any manifold that is the total space of a vector bundle. In adapted local coordinates,

$$\Sigma = p_i^\mu \frac{\partial}{\partial p_i^\mu} + p \frac{\partial}{\partial p}.$$  \hspace{1cm} (18)

It is then easy to verify the following relations (see Proposition 2.1 of Ref. [2]):

$$L_\Sigma \theta = \theta.$$ \hspace{1cm} (19)

$$L_\Sigma \omega = \omega.$$ \hspace{1cm} (20)

$$i_\Sigma \theta = 0.$$ \hspace{1cm} (21)

$$i_\Sigma \omega = -\theta.$$ \hspace{1cm} (22)

In particular, the last equation means that the scaling vector field allows to reconstruct $\theta$ from $\omega$. But the main utility of $\Sigma$ is that taking the Lie derivative $L_\Sigma$ along $\Sigma$ provides a device for controlling the dependence of functions and, more generally, of tensor fields on $P$ on the multimomentum variables and the energy variable, that is, along the fibers of $P$ over $E$: $L_\Sigma$ has only integer eigenvalues, and eigenfunctions of $L_\Sigma$ with eigenvalue $k$ are homogeneous polynomials of degree $k$ in these variables.

As we shall see soon, homogeneity under $L_\Sigma$ plays a central role in the analysis of various classes of multivector fields and differential forms on $P$.

Let us recall a few definitions. An $r$-multivector field $X$ on $P$ is called locally Hamiltonian if $i_X \omega$ is closed, or equivalently, if

$$L_X \omega = 0.$$ \hspace{1cm} (23)

It is called globally Hamiltonian if $i_X \omega$ is exact, that is, if there exists an $(n-r)$-form $f$ on $P$ such that

$$i_X \omega = df.$$ \hspace{1cm} (24)

In this case, $f$ is said to be a Hamiltonian form associated with $X$. Finally, it is called exact Hamiltonian if

$$L_X \theta = 0.$$ \hspace{1cm} (25)

Of course, exact Hamiltonian multivector fields are globally Hamiltonian (to show this, set $f = (-1)^{r-1}i_X \theta$ and apply eqs (23) and (24)), and globally Hamiltonian multivector fields are obviously locally Hamiltonian. Conversely, an $(n-r)$-form $f$ on $P$ is called a Hamiltonian form if there exists an $r$-multivector field $X$ on $P$ such that eq. (24) holds; in this case, $X$ is said to be a Hamiltonian multivector field associated with $f$. Moreover, $f$ is called a Poisson form if in addition, it vanishes on the kernel of $\omega$, that is, if for any multivector field $Z$, we have

$$i_Z \omega = 0 \implies i_Z f = 0.$$ \hspace{1cm} (26)
A trivial example of a Poisson form is the multisymplectic form $\omega$ itself. Another example is provided by the multicanonical form $\theta$, since it follows trivially from eq. (22) that $\theta$ vanishes on the kernel of $\omega$.

Concerning stability under the Lie derivative along the scaling vector field $\Sigma$, we have the following

**Proposition 1.1** The space $\mathfrak{X}_{LH}^\wedge(P)$ of locally Hamiltonian multivector fields, the space $\mathfrak{X}_H^\wedge(P)$ of globally Hamiltonian multivector fields, the space $\mathfrak{X}_{EH}^\wedge(P)$ of exact Hamiltonian multivector fields and the space $\mathfrak{X}_0^\wedge(P)$ of multivector fields taking values in the kernel of $\omega$ are all invariant under the Lie derivative along the scaling vector field $\Sigma$:

$$L_X \omega = 0 \implies L_{[\Sigma,X]} \omega = 0 ,$$

$$i_X \omega = df \implies i_{[\Sigma,X]} \omega = d(L_{\Sigma} f - f) ,$$

$$L_X \theta = 0 \implies L_{[\Sigma,X]} \theta = 0 ,$$

$$i_\xi \omega = 0 \implies i_{[\Sigma,\xi]} \omega = 0 .$$

**Proof.** All these relations can be shown by direct calculation. For example, eqs (27) and (29) follow directly from combining eq. (14) with eqs (20) and (19), respectively. Similarly, eq. (28) follows directly from combining eq. (13) with eqs (20) and (12). Finally, eq. (30) is a special case of eq. (28), obtained by putting $f = 0$. \[ \square \]

Dually, we have

**Proposition 1.2** The space $\Omega_H(P)$ of Hamiltonian forms, the space $\Omega_0(P)$ of forms that vanish on the kernel of $\omega$ and the space $\Omega_P(P)$ of Poisson forms are all invariant under the Lie derivative along the scaling vector field $\Sigma$:

$$df = i_X \omega \implies d(L_{\Sigma} f) = i_{X+[\Sigma,X]} \omega .$$

**Proof.** The first statement is a consequence of eq. (31), which follows directly from combining eqs (12) and (13) with eq. (20). For the second statement, assume that $f$ vanishes on the kernel of $\omega$. Then if $\xi$ is any multivector field $\xi$ taking values in the kernel of $\omega$, the multivector field $[\Sigma,\xi]$ takes values in the kernel of $\omega$ as well (cf. eq. (31)), so that according to eq. (13),

$$i_\xi (L_{\Sigma} f) = L_{\Sigma} i_\xi f - i_{[\Sigma,\xi]} f = 0 .$$
But this means that $L_\Sigma f$ vanishes on the kernel of $\omega$. Finally, the third statement follows by combining the first two.

A special class of multivector fields and of differential forms on $P$ which will be of particular importance in what follows is that of fiberwise polynomial multivector fields and of fiberwise polynomial differential forms on $P$: their coefficients are polynomials along the fibers of $P$ over $E$, or in other words, polynomials in the multimomentum variables and the energy variable. The main advantage of working with tensor fields on the total space of a vector bundle which are fiberwise polynomial is that they allow a unique and globally defined (or in other words, coordinate independent) decomposition into homogeneous components, according to the different eigenspaces of the Lie derivative $L_\Sigma$ along $\Sigma$; the corresponding eigenvalue will in what follows be called the scaling degree (to distinguish it from the ordinary tensor degree). In doing so, it must be borne in mind that, in an expansion with respect to an adapted local coordinate system, the scaling degree receives contributions not only from the coefficient functions but also from some of the coordinate vector fields and differentials since the vector fields $\mathcal{O}/\partial x^\mu$, $\partial/\partial q^i$, $\partial/\partial p^\mu_i$ and $\partial/\partial p$ carry scaling degree 0, 0, $-1$ and $-1$, respectively, while the differentials $dx^\mu$, $dq^i$, $dp^\mu_i$ and $dp$ carry scaling degree 0, 0, $+1$ and $+1$, respectively; moreover, the scaling degree is additive under the exterior product, since $L_\Sigma$ is a derivation. Therefore, a fiberwise polynomial $r$-multivector field on $P$ admits a globally defined decomposition into a finite sum

$$X = \sum_{s \geq -r} X_s ,$$

where $X_s$ is its homogeneous component of scaling degree $s$:

$$L_\Sigma X_s = s X_s .$$

Each $X_s$ can be obtained from $X$ by applying a projector which is itself a polynomial in $L_\Sigma$:

$$X_s = \prod_{s' \geq -r} \frac{1}{s - s'} (L_\Sigma - s') X .$$

Similarly, a fiberwise polynomial $(n - r)$-form $f$ on $P$ admits a globally defined decomposition into a finite sum

$$f = \sum_{s \geq 0} f_s ,$$

where $f_s$ is its homogeneous component of scaling degree $s$:

$$L_\Sigma f_s = s f_s .$$

Each $f_s$ can be obtained from $f$ by applying a projector which is itself a polynomial in $L_\Sigma$:

$$f_s = \prod_{s' \geq s} \frac{1}{s - s'} (L_\Sigma - s') f .$$
The relevance of these decompositions for locally Hamiltonian multivector fields and for Hamiltonian forms on the extended multiphase space $P$ stems from the following theorems, whose proof will follow from statements to be derived in the course of the next two sections, by means of explicit calculations in adapted local coordinates.

**Theorem 1.3**  
*Except for trivial contributions, locally Hamiltonian multivector fields and Hamiltonian forms on $P$ are fiberwise polynomial. More precisely, we have:*

1. Any locally Hamiltonian $r$-multivector field on $P$, with $0 < r < n$, can be decomposed into the sum of a fiberwise polynomial locally Hamiltonian $r$-multivector field and an $r$-multivector field taking values in the kernel of $\omega$. Such a decomposition is unique up to fiberwise polynomial $r$-multivector fields taking values in the kernel of $\omega$. (Note that for $r=1$, this decomposition is trivial.)

2. Any Hamiltonian form (Poisson form) of degree $n-r$ on $P$, with $0 < r < n$, can be decomposed into the sum of a fiberwise polynomial Hamiltonian form (fiberwise polynomial Poisson form) of degree $n-r$ and a closed form (closed form vanishing on the kernel of $\omega$) of degree $n-r$. Such a decomposition is unique up to fiberwise polynomial closed forms (up to fiberwise polynomial closed forms vanishing on the kernel of $\omega$) of degree $n-r$.

More specifically, we have:

**Theorem 1.4**  
*Fiberwise polynomial locally Hamiltonian $r$-multivector fields and fiberwise polynomial Hamiltonian forms of degree $n-r$ have non-trivial homogeneous components of scaling degree $s$ only for $s = -1, 0, \ldots, r-1$ and for $s = 0, 1, \ldots, r$, respectively. More precisely, we have:*

1. Every fiberwise polynomial locally Hamiltonian (Hamiltonian, exact Hamiltonian) $r$-multivector field $X$ on $P$, with $0 < r < n$, admits a unique, globally defined decomposition into homogeneous components with respect to scaling degree, which can be written in the form\(^1\)

$$X = X_{-} + X_{+} + \xi \quad \text{with} \quad X_{+} = \sum_{s=0}^{r-1} X_{s}, \tag{38}$$

where each $X_{s}$ is locally Hamiltonian (Hamiltonian, exact Hamiltonian) and

$$\xi = \sum_{-r \leq s \leq -2} \xi_{s} + \sum_{s \geq r} \xi_{s} \tag{39}$$

is a fiberwise polynomial $r$-multivector field on $P$ taking values in the kernel of $\omega$.

\(1\)We abbreviate $X_{-1}$ as $X_{-}$.
Every fiberwise polynomial Hamiltonian form (Poisson form) $f$ of degree $n - r$ on $P$, with $0 < r < n$, admits a unique, globally defined decomposition into homogeneous components with respect to scaling degree, which can be written in the form

$$f = f_0 + f_+ + f_c$$

with

$$f_+ = \sum_{s=1}^{r} f_s ,$$

where each $f_s$ is Hamiltonian (Poisson) and

$$f_c = \sum_{s \geq r+1} (f_c)_s$$

is a fiberwise polynomial closed $(n - r)$-form on $P$.

The cases $r = 0$ and $r = n$ are exceptional and must be dealt with separately; see Propositions 2.2 and 3.2 for $r = 0$ and Propositions 2.3 and 3.1 for $r = n$.

In view of these theorems, it is sufficient to study locally Hamiltonian multivector fields and Hamiltonian forms which are homogeneous under the Lie derivative along the scaling vector field $\Sigma$. This condition of homogeneity is also compatible with the correspondence between globally Hamiltonian multivector fields $X$ and Hamiltonian forms $f$ established by the fundamental relation (24), because $\omega$ itself is homogeneous: according to eq. (24), $\omega$ has scaling degree 1. Indeed, except for the ambiguity inherent in this correspondence ($f$ determines $X$ only up to a multivector field taking values in the kernel of $\omega$ and $X$ determines $f$ only up to a closed form), eq. (24) preserves the scaling degree, up to a shift by 1: $X$ is homogeneous with scaling degree $s - 1$ if and only if $f$ is homogeneous with scaling degree $s$:

$$L_\Sigma X = (s - 1)X \quad \text{modulo multivector fields} \quad \iff \quad L_\Sigma f = sf \quad \text{modulo closed forms}$$

For a proof, note that the condition on the lhs amounts to requiring that $i_{[\Sigma,X]}\omega = (s - 1)i_X\omega$, while the condition on the rhs amounts to requiring that $d L_\Sigma f = sdf$, so the equivalence stated in eq. (42) is an immediate consequence of eq. (31). A particular case occurs when $s = 1$, since the locally Hamiltonian multivector fields which are homogeneous of scaling degree 0 are precisely the exact Hamiltonian multivector fields: for $L_X\omega = 0$,

$$L_\Sigma X = 0 \quad \text{modulo multivector fields} \quad \iff \quad L_X\theta = 0 .$$

Indeed, combining eqs (22) and (13) gives

$$L_X\theta = -L_Xi_\Sigma\omega = (-1)^r (i_{[X,\Sigma]}\omega - i_\Sigma L_X\omega) = (-1)^{r-1}i_{[\Sigma,X]}\omega .$$
More generally, the fundamental relation \((24)\) preserves the property of being fiberwise polynomial, in the following sense: If \(X\) is a fiberwise polynomial Hamiltonian \(r\)-multivector field and \(f\) is a Hamiltonian \((n - r)\)-form associated with \(X\), then modifying \(f\) by addition of an appropriate closed \((n - r)\)-form if necessary, we may always assume, without loss of generality, that \(f\) is fiberwise polynomial as well. Conversely, if \(f\) is a fiberwise polynomial Hamiltonian \((n - r)\)-form and \(X\) is a Hamiltonian \(r\)-multivector field associated with \(f\), then modifying \(X\) by addition of an appropriate \(r\)-multivector field taking values in the kernel of \(\omega\) if necessary, we may always assume, without loss of generality, that \(X\) is fiberwise polynomial as well.

## 2 Hamiltonian multivector fields

Our aim in this section is to determine the explicit form, in adapted local coordinates, of locally Hamiltonian \(r\)-multivector fields on the extended multiphase space \(P\), where \(0 \leq r \leq n + 1\). (Multivector fields of tensor degree \(> n + 1\) are uninteresting since they always take their values in the kernel of \(\omega\).)

As a first step towards this goal, we shall determine the explicit form, in adapted local coordinates, of the multivector fields on \(P\) taking values in the kernel of \(\omega\); this will also serve to identify, in the next section, the content of the kernel condition \((26)\) that characterizes Poisson forms. To this end, note first that \(\omega\) being a homogeneous differential form (of degree \(n + 1\)), its kernel is graded, that is, if an inhomogeneous multivector field takes values in the kernel of \(\omega\), so do all its homogeneous components.

**Proposition 2.1** An \(r\)-multivector field on \(P\), with \(r > 1\), takes values in the kernel of \(\omega\) if and only if, in adapted local coordinates, it can be written as a linear combination of 3-vertical terms, of the 2-vertical terms

\[
\begin{align*}
\frac{\partial}{\partial q^i} & \wedge \frac{\partial}{\partial q^j} \wedge \frac{\partial}{\partial x^{\mu_3}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}}, \\
\frac{\partial}{\partial p^k} & \wedge \frac{\partial}{\partial p^l} \wedge \frac{\partial}{\partial x^{\mu_3}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}}, \\
\frac{\partial}{\partial q^i} & \wedge \frac{\partial}{\partial p^k} \wedge \frac{\partial}{\partial x^{\mu_3}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}},
\end{align*}
\]  

and of the 1-vertical terms

\[
\begin{align*}
\left( \frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial p^k} + \delta_i^k \frac{\partial}{\partial p^i} \wedge \frac{\partial}{\partial x^\mu} \right) \wedge \frac{\partial}{\partial x^{\mu_3}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}}, \\
\left( \frac{\partial}{\partial p^i} \wedge \frac{\partial}{\partial x^{\mu_2}} + \frac{\partial}{\partial p^i} \wedge \frac{\partial}{\partial x^{\mu_1}} \right) \wedge \frac{\partial}{\partial x^{\mu_3}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}}.
\end{align*}
\]
Thus every $r$-multivector field $X$ on $P$ admits, in adapted local coordinates, a unique decomposition of the form

$$X = \frac{1}{r!} X^{\mu_1 \ldots \mu_r} \frac{\partial}{\partial x^{\mu_1}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} + \frac{1}{(r-1)!} X^{i, \mu_2 \ldots \mu_r} \frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} + \frac{1}{r!} \tilde{X}^{i \mu_2 \ldots \mu_r} \frac{\partial}{\partial p_i} \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} + \xi,$$

(48)

where all coefficients are totally antisymmetric in their space-time indices and $\xi$ takes values in the kernel of $\omega$; then

$$i_X \omega = -\frac{1}{(r-1)!} \tilde{X}^{\mu_2 \ldots \mu_r} d^n x_{\mu_2 \ldots \mu_r} + \frac{(-1)^r}{r!} X^{i, \mu_1 \ldots \mu_r} dq^i \wedge d^n x_{\mu_1 \ldots \mu_r} + \frac{(-1)^{r-1}}{(r-1)!} X^{i, \mu_2 \ldots \mu_r} dp_i \wedge d^n x_{\mu_2 \ldots \mu_r} + \frac{1}{r!} X^{\mu_1 \ldots \mu_r} dq^i \wedge dp_i \wedge d^n x_{\mu_1 \ldots \mu_r} - \frac{(-1)^r}{r!} X^{i, \mu_1 \ldots \mu_r} dp \wedge d^n x_{\mu_1 \ldots \mu_r},$$

(49)

and similarly,

$$i_X \theta = \frac{1}{(r-1)!} p_i^\mu X^{i, \mu_2 \ldots \mu_r} d^n x_{\mu_2 \ldots \mu_r} + \frac{1}{r!} \mu X^{\mu_1 \ldots \mu_r} d^n x_{\mu_1 \ldots \mu_r} + \frac{(-1)^r}{r!} p_i^\mu X^{\mu_1 \ldots \mu_r} dq^i \wedge d^n x_{\mu_1 \ldots \mu_r},$$

(50)

where, in each of the last two equations, the first term is to be omitted if $r = n$, whereas only the last term in the first equation remains and $i_X \theta$ vanishes identically if $r = n+1$.

**Proof.** First of all, the fact that $\omega$ vanishes on 3-vertical multivector fields and on the 2-vertical and 1-vertical local multivector fields written down in eqs (45)–(47) follows directly from the local coordinate expression for $\omega$, eq. (3). To prove the converse, we
write down the local coordinate expression for a general r-multivector field \(X\),

\[
X = \frac{1}{r!} X^{\mu_1 \ldots \mu_r} \frac{\partial}{\partial x^{\mu_1}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} \\
+ \frac{1}{(r-1)!} X^{i, j_2 \ldots j_r} \frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial x^{j_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{j_r}} \\
+ \frac{1}{(r-1)!} X^{i, j_2 \ldots j_r} \frac{\partial}{\partial p_k^i} \wedge \frac{\partial}{\partial x^{j_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{j_r}} \\
+ \frac{1}{(r-1)!} X^{i, j_2 \ldots j_r} \frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial x^{j_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{j_r}} \\
+ \frac{1}{(r-2)!} X^{i, j_2 \ldots j_r} \frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial x^{j_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{j_r}} \\
+ \xi',
\]

where \(\xi'\) contains the 3-vertical terms as well as the 2-vertical terms listed in eq. (45) that occur in \(X\) and hence are annihilated under contraction with \(\omega\). This leads to

\[
i_X \omega = \frac{1}{r!} X^{\mu_1 \ldots \mu_r} dq^i \wedge dp^i_\mu \wedge d^n x_{\mu_1 \ldots \mu_r} - \frac{(-1)^r}{r!} X^{\mu_1 \ldots \mu_r} dp \wedge d^n x_{\mu_1 \ldots \mu_r} \\
+ \frac{(-1)^{r-1}}{(r-1)!} X^{i, j_2 \ldots j_r} dp^i_\mu \wedge d^n x_{j_2 \ldots j_r} \\
- \frac{(-1)^{r-1}}{(r-1)!} X^{i, j_2 \ldots j_r} dq^i \wedge d^n x_{j_2 \ldots j_r} \\
- \frac{1}{(r-1)!} X^{j_2 \ldots j_r} d^n x_{j_2 \ldots j_r} + \frac{1}{(r-2)!} X^{i, j_2 \ldots j_r} d^n x_{j_2 \ldots j_r} .
\]

These two equations can conveniently be rewritten in the form (48) and (49), respectively, by setting

\[
X^{\mu_1 \ldots \mu_r} = \frac{1}{r} \sum_{s=1}^r (-1)^{s-1} X^{f_{s, j_1 \ldots j_s} \mu_1 \ldots \mu_s \mu_{s+1} \ldots \mu_r},
\]

\[
\tilde{X}^{j_2 \ldots j_r} = X^{j_2 \ldots j_r} - \sum_{s=2}^r (-1)^s X^{f_{s, j_1 \ldots j_s} \mu_2 \ldots \mu_s \mu_{s+1} \ldots \mu_r},
\]

and

\[
\xi = \frac{1}{(r-1)!} (X^{i, j_2 \ldots j_r} - X^{j_2 \ldots j_r}) \frac{\partial}{\partial p^i_\mu} \wedge \frac{\partial}{\partial x^{j_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{j_r}} \\
+ \frac{1}{(r-2)!} X^{f_{i, k, j_3 \ldots j_r} \mu_2 \ldots \mu_r} (\frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial p^k_\mu} + \delta_k^i \frac{\partial}{\partial p^k_\mu} \wedge \frac{\partial}{\partial x^k}) \wedge \frac{\partial}{\partial x^{j_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{j_r}} \\
+ \xi',
\]

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which is the general local coordinate expression for an \( r \)-multivector field taking values in the kernel of \( \omega \).

With the standard local coordinate representation \([48]\) for \( r \)-multivector fields \( X \) at hand, we are now in a position to analyze the restrictions imposed on the coefficients \( X_{\mu_1...\mu_r}^i, X_i^{\mu_1...\mu_r}, X_{\mu_1...\mu_r}^i \) and \( \tilde{X}^{\mu_1...\mu_r} \) by requiring \( X \) to be locally Hamiltonian.\footnote{Of course, it makes no sense to discuss the question which locally Hamiltonian multivector fields are also globally Hamiltonian when working in local coordinates.}

As a warm-up exercise, we shall settle the extreme cases of tensor degree 0 and \( n + 1 \).

**Proposition 2.2** A function on \( P \), regarded as a 0-multivector field, is locally Hamiltonian if and only if it is constant; it is then also exact Hamiltonian. Similarly, an \((n + 1)\)-multivector field on \( P \), with standard local coordinate representation

\[
X = \tilde{X} \frac{\partial}{\partial p} \land \frac{\partial}{\partial x_1} \land \ldots \land \frac{\partial}{\partial x_n} + \xi ,
\]

where \( \xi \) takes values in the kernel of \( \omega \), is locally Hamiltonian if and only if the coefficient function \( \tilde{X} \) is constant and is exact Hamiltonian if and only if it vanishes.

**Proof.** For functions, we use the fact that the operator \( i_f \) corresponding to the constant function 1 on a manifold is defined to be the identity, so that the operator \( i_f \) corresponding to an arbitrary function \( f \) on a manifold is simply multiplication by \( f \). Therefore, we have for any differential form \( \alpha \)

\[
L_f \alpha = d(i_f \alpha) - i_f d\alpha = d(f \alpha) - f d\alpha = df \land \alpha ,
\]

implying that if \( f \) is constant, \( L_f \alpha = 0 \) no matter what \( \alpha \) one chooses. On the other hand, we compute in adapted local coordinates

\[
L_f \omega = \left( \frac{\partial f}{\partial x^{\nu}} dx^{\nu} + \frac{\partial f}{\partial q^i} dq^i + \frac{\partial f}{\partial p_j^\nu} dp_j^\nu + \frac{\partial f}{\partial p} dp \right) \land \left( dq^i \land dp_i^\mu \land d^n x_\mu - dp \land d^n x \right)
\]

\[
= \frac{\partial f}{\partial x^{\mu}} dq^i \land dp_i^\mu \land d^n x - \frac{\partial f}{\partial q^i} dq^i \land dq_j^\nu \land dp_i^\mu \land d^n x_\mu - \frac{\partial f}{\partial q^i} dq^i \land dp \land d^n x
\]

\[
+ \frac{\partial f}{\partial p_j^\nu} dq^i \land dp_i^\mu \land dp_j^\nu \land d^n x_\mu - \frac{\partial f}{\partial p_i^\mu} dp_i^\mu \land dp \land d^n x
\]

\[
+ \frac{\partial f}{\partial p} dq^i \land dp_i^\mu \land dp \land d^n x_\mu .
\]

Inspecting the various terms, we see that this expression can only vanish if all partial derivatives of \( f \) are identically zero. Similarly, for multivector fields of degree \( n + 1 \), it is clear that when \( r \) equals \( n + 1 \), the last four terms in eq. (51) vanish
by antisymmetry, so that – in contrast to what happens in the general case – the first three terms in eq. (48) also take values in the kernel of \( \omega \) and can thus be incorporated into \( \xi \). Therefore, by putting

\[
\tilde{X}^{\mu_1 \ldots \mu_n} = \epsilon^{\mu_1 \ldots \mu_n} \tilde{X},
\]

we can reduce the standard local coordinate representation of \( X \) to the form given in eq. (51) and the expression (49) to

\[
i_X \omega = \tilde{X}. \]

But

\[
L_X \omega = d(i_X \omega) - (-1)^n i_X d\omega = d(i_X \omega) \quad \text{and} \quad L_X \theta = d(i_X \theta) - (-1)^{n+1} i_X d\theta = (-1)^{n+1} i_X \omega,
\]

so the proposition follows.

The intermediate cases \((0 < r \leq n)\) are much more interesting. However, the situation for tensor degree \(n\) is substantially different from that for tensor degree \(< n\), mainly due to the fact that when \(r\) equals \(n\), the penultimate term in eq. (49) and the last term in eq. (50) still vanish by antisymmetry; this case will therefore be dealt with first. To this end, we begin by simplifying the notation, writing

\[
X^{\mu_1 \ldots \mu_n} = \epsilon^{\mu_1 \ldots \mu_n} \tilde{X},
\]

so that the standard local coordinate representation (48) of \( X \) takes the form

\[
X = \tilde{X} \frac{1}{n!} \epsilon^{\mu_1 \ldots \mu_n} \frac{\partial}{\partial x^{\mu_1}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_n}}
+ X^i \frac{1}{(n-1)!} \epsilon^{\mu_2 \ldots \mu_n} \frac{\partial}{\partial q^i} \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_n}}
+ X_i \frac{1}{n!} \epsilon^{\mu_1 \mu_2 \ldots \mu_n} \frac{\partial}{\partial p_i} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_n}}
+ X^{\mu} \frac{1}{(n-1)!} \epsilon^{\mu_2 \ldots \mu_n} \frac{\partial}{\partial p^\mu} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_n}}
+ \xi,
\]

where \( \xi \) takes values in the kernel of \( \omega \), while eqs. (49) and (50) take the form

\[
i_X \omega = (-1)^{n-1} \tilde{X} dp + X^i p_i dq^i - (-1)^{n-1} X_i dq^i - X_\mu dx^\mu,
\]

and

\[
i_X \theta = p \tilde{X} + (-1)^{n-1} p_i X^i,
\]

respectively.

**Proposition 2.3** An \( n \)-multivector field \( X \) on \( P \) is locally Hamiltonian if and only if, locally and modulo terms taking values in the kernel of \( \omega \), it can be written in terms of...
a single function $f$, as follows:

$$X = -\frac{1}{(n-1)!} \epsilon^{\mu_2 \ldots \mu_n \mu} \left( \frac{\partial f}{\partial x^\mu} \frac{\partial}{\partial p} - \frac{1}{n} \frac{\partial f}{\partial p} \frac{\partial}{\partial x^\mu} \right) \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_n}}$$

Moreover, $X$ is exact Hamiltonian if and only if $f$ is a linear function of the multimomentum variables $p^\rho_\rho$ and of the energy variable $p$.

**Proof.** Obviously, $X$ is locally Hamiltonian if and only if, locally, $i_X \omega = df$ for some function $f$, which in view of eq. (54) leads to the following system of equations for the coefficients $\tilde{X}, X^i, X_i$ and $X_\mu$ of $X$ in its standard local coordinate representation (53):

$$\tilde{X} = (-1)^{n-1} \frac{\partial f}{\partial p} , \quad X^i = \frac{\partial f}{\partial p^\mu_i} , \quad X_i = (-1)^n \frac{\partial f}{\partial q^i} , \quad X_\mu = -\frac{\partial f}{\partial x^\mu} .$$

Inserting this back into eq. (53) and rearranging the terms, we arrive at eq. (56). Note also that then,

$$i_X \theta = (-1)^{n-1} p \frac{\partial f}{\partial p} + (-1)^{n-1} p^\mu_i \frac{\partial f}{\partial p^\mu_i} ,$$

that is,

$$i_X \theta = (-1)^{n-1} L_{\Sigma} f .$$

Next, $X$ will be exact Hamiltonian if and only if, in addition,

$$f = (-1)^{n-1} i_X \theta ,$$

which in view of the previous equation means that $f$ must be an eigenfunction of the scaling operator $L_{\Sigma}$ with eigenvalue 1: this is well known to be the case if and only if $f$ is linear in the multimomentum variables $p^\rho_\rho$ and the energy variable $p$.

□

Now we turn to multivector fields of tensor degree $< n$. Here, the main result is

**Theorem 2.4.** An $r$-multivector field $X$ on $P$, with $0 < r < n$, is locally Hamiltonian if and only if the coefficients $X^{\mu_1 \ldots \mu_r}, X^i_1 \mu_2 \ldots \mu_r, X_i^\mu_1 \ldots \mu_r$ and $\tilde{X}^\mu_2 \ldots \mu_r$ in its standard local coordinate representation (48) satisfy the following conditions:

1. the coefficients $X^{\mu_1 \ldots \mu_r}$ depend only on the local coordinates $x^\rho$ for $M$ and, in the special case $N=1$, also on the local fiber coordinates $q^r$ for $E$,
2. the coefficients \(X^{i_1 \ldots i_r} \mu_1 \ldots \mu_r\) are "antisymmetric polynomials in the multimomentum variables" of degree \(r - 1\), i.e., they can be written in the form

\[
X^{i_1 \ldots i_r} \mu_1 \ldots \mu_r = \sum_{s=1}^{r} X^{s}_{i_1 \ldots i_r} \mu_1 \ldots \mu_r,
\]

with

\[
X^{s}_{i_1 \ldots i_r} \mu_1 \ldots \mu_r = \frac{1}{(s-1)!} \frac{1}{(r-s)!} \sum_{\pi \in S_{r-1}} (-1)^{\pi} \mu_{(2)} p_{i_2} \ldots p_{i_s} \mu_{(s)} \chi^{s}_{s-1} \mu_{(s)} \mu_{(s+1)} \ldots \mu_{(r)},
\]

where \(S_{r-1}\) denotes the permutation group of \(\{2, \ldots, r\}\) and the coefficients \(\chi^{s}_{s-1} \mu_{(s)} \mu_{(s+1)} \ldots \mu_{(r)}\) depend only on the local coordinates \(x^\rho\) for \(M\) as well as the local fiber coordinates \(q^r\) for \(E\) and are totally antisymmetric in \(i, i_2, \ldots, i_s\) as well as in \(\mu_{s+1}, \ldots, \mu_r\).

3. the remaining coefficients \(X^{\mu_1 \ldots \mu_r}_i\) and \(\tilde{X}^{\mu_2 \ldots \mu_r}_i\) can be expressed in terms of the previous ones and of new coefficients \(X^{\mu_1 \ldots \mu_r}_i\) depending only on the local coordinates \(x^\rho\) for \(M\) as well as the local fiber coordinates \(q^r\) for \(E\) and are totally antisymmetric in \(\mu_1, \ldots, \mu_r\), according to

\[
X^{\mu_1 \ldots \mu_r}_i = -p \frac{\partial X^{\mu_1 \ldots \mu_r}}{\partial q^i} + p^\mu_i \frac{\partial X^{\mu_1 \ldots \mu_r}}{\partial x^\mu} - \sum_{s=1}^{r} p^\mu_i \frac{\partial X^{\mu_1 \ldots \mu_{s-1}} \mu_{s+1} \ldots \mu_r}{\partial x^\nu} - \sum_{s=1}^{r-1} (-1)^{s-1} p^\mu_i \frac{\partial X^{i_1 \ldots i_s} \mu_1 \ldots \mu_r}{\partial x^\mu}
\]

\[
\sum_{s=1}^{r-1} (-1)^{s-1} p^\mu_i \frac{\partial X^{i_1 \ldots i_s} \mu_1 \ldots \mu_r}{\partial x^\mu} - \sum_{s=2}^{r} p^\mu_i \frac{\partial X^{i_1 \mu_2 \ldots \mu_s} \mu_{s+1} \ldots \mu_r}{\partial x^\mu}
\]

\[
\tilde{X}^{\mu_2 \ldots \mu_r}_i = (-1)^r p \frac{\partial X^{\mu_2 \ldots \mu_r}}{\partial x^\nu}
\]

\[
- \sum_{s=1}^{r-1} (-1)^{s-1} p^\mu_i \frac{\partial X^{i_1 \mu_2 \ldots \mu_s} \mu_{s+1} \ldots \mu_r}{\partial x^\mu} - \sum_{s=2}^{r} p^\mu_i \frac{\partial X^{i_1 \mu_2 \ldots \mu_{s-1}} \mu_{s+1} \ldots \mu_r}{\partial x^\mu} - (-1)^r \frac{\partial X^{\mu_2 \ldots \mu_r}}{\partial x^\mu}.
\]

It is exact Hamiltonian if and only if, in addition, the coefficients \(X^{i_1 \mu_2 \ldots \mu_r}\) depend only on the local coordinates \(x^\rho\) for \(M\) as well as the local fiber coordinates \(q^r\) for \(E\) and the coefficients \(X^{\mu_1 \ldots \mu_r}\) vanish.
Proof. The proof will be carried out by “brute force” computation. First, we apply the exterior derivative to eq. (49) and use eq. (10) to simplify the expressions involving derivatives with respect to the space-time variables. Collecting the terms, we get

\[
L_X \omega = - \frac{1}{(r-2)!} \frac{\partial X_{\mu \ldots \nu}}{\partial x^\nu} d^n x_{\mu \ldots \nu} \\
- \frac{1}{(r-1)!} \left( \frac{\partial X_{\mu_{2 \ldots \nu}}}{\partial q^i} - (-1)^{r-1} \frac{\partial X_{\mu_{2 \ldots \nu}}}{\partial x^\nu} \frac{\partial}{\partial x^i} \right) dq^i \wedge d^n x_{\mu_{2 \ldots \nu}} \\
- \frac{1}{(r-1)!} \left( \frac{\partial X_{\mu_{2 \ldots \nu}}}{\partial p^\mu_i} + \frac{\partial X_{i,\mu_{2 \ldots \nu}}}{\partial x^\nu} - \sum_{s=2}^r \delta_{\mu_s}^{\mu_{s-1}} \frac{\partial X_{i,\mu_{s-1 \ldots \nu}}}{\partial x^\nu} \right) dp_i^\mu \wedge d^n x_{\mu_{2 \ldots \nu}} \\
- \frac{(-1)^r}{r!} \left( \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial q^i} + \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial p^\mu_i} \right) dq^i \wedge dp \wedge d^n x_{\mu_{1 \ldots \nu}} \\
- \frac{(-1)^r}{r!} \left( \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial p^\mu_i} - \sum_{s=1}^r (-1)^{s-1} \delta_{\mu_s}^{\mu_{s-1}} \frac{\partial X_{i,\mu_{s-1 \ldots \nu}}}{\partial p^\mu_i} \right) dp_i^\mu \wedge dp \wedge d^n x_{\mu_{1 \ldots \nu}} \\
+ \frac{(-1)^r}{r!} \left( \delta_k^i \delta_k^\nu \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial x^\mu} - \sum_{s=1}^r \delta_k^i \delta_k^\nu \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial x^\mu} \right) \\
- \sum_{s=1}^r (-1)^{s-1} \delta_{\mu_s}^{\mu_{s-1}} \frac{\partial X_{i,\mu_{s-1 \ldots \nu}}}{\partial q^i} - \frac{\partial X_{i,\mu_{1 \ldots \nu}}}{\partial p^\mu_i} \right) \right) \\
\times dq^i \wedge dp_i^k \wedge d^n x_{\mu_{1 \ldots \nu}} \\
- \frac{(-1)^r}{r!} \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial q^i} dq^i \wedge dq^j \wedge d^n x_{\mu_{1 \ldots \nu}} \\
+ \frac{(-1)^{r-1}}{(r-1)!} \frac{\partial X_{i,\mu_{2 \ldots \nu}}}{\partial p^\nu} dp_k^\nu \wedge dp_i^\lambda \wedge d^n x_{\lambda_{\mu_{2 \ldots \nu}}} \\
- \frac{1}{r!} \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial q^i} dq^i \wedge dq^j \wedge dp_i^\mu \wedge d^n x_{\mu_{1 \ldots \nu}} \\
- \frac{1}{r!} \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial p^\nu} dp_k^\mu \wedge dp_i^\lambda \wedge d^n x_{\lambda_{\mu_{1 \ldots \nu}}} \\
+ \frac{1}{r!} \frac{\partial X_{\mu_{1 \ldots \nu}}}{\partial p} dq^i \wedge dp_i^\mu \wedge dp \wedge d^n x_{\mu_{1 \ldots \nu}}.
\]
Next we analyze terms no. 6, 10, 11 and 12.

- Term No. 12: Given mutually different indices $\kappa_1, \ldots, \kappa_r$, we choose indices $k$ and $\kappa \notin \{\kappa_1, \ldots, \kappa_r\}$ (here we use the hypothesis that $r < n$) and, when $r < n - 1$, a complementary set of indices $\nu_1, \ldots, \nu_{n-r-1}$ to contract this term with the multivector field $\partial_k \wedge \partial^k \wedge \partial_0 \wedge \partial_{\nu_1} \wedge \ldots \wedge \partial_{\nu_{n-r-1}}$ (no sum over $k$), concluding that $X^{\kappa_1, \ldots, \kappa_r}$ cannot depend on $p^k$. Obviously, there is one case where this argument does not work: namely when $N = 1, r = n - 1$ and $\mu \notin \{\kappa_1, \ldots, \kappa_r\}$. This situation will however be covered in the next item.

- Term No. 11: Given indices $i, \mu$ and mutually different indices $\kappa_1, \ldots, \kappa_r$, we choose indices $j$ and $\nu \notin \{\kappa_1, \ldots, \kappa_r\}$ (here we use the hypothesis that $r < n$) such that either $j \neq i$ or $\nu \neq \mu$ and, when $r < n - 1$, a complementary set of indices $\nu_1, \ldots, \nu_{n-r-1}$ to contract this term with the multivector field $\partial_j \wedge \partial^j \wedge \partial_{\nu_1} \wedge \ldots \wedge \partial_{\nu_{n-r-1}}$ (no sum over $j$), concluding that $X^{\kappa_1, \ldots, \kappa_r}$ cannot depend on $p^\mu$. In this situation, the whole term vanishes identically, and no conclusion can be drawn.

- Term No. 6 (first part): Given indices $k, \kappa$ and mutually different indices $\kappa_1, \ldots, \kappa_r$ such that $\kappa \notin \{\kappa_1, \ldots, \kappa_r\}$, we choose a complementary set of indices $\nu_1, \ldots, \nu_{n-r-1}$ to contract this term with the multivector field $\partial_k \wedge \partial_0 \wedge \partial_{\kappa} \wedge \partial_{\nu_1} \wedge \ldots \wedge \partial_{\nu_{n-r-1}}$, concluding that $X^{\kappa_1, \ldots, \kappa_r}$ cannot depend on $p^\kappa$, since in this case the second term in the bracket gives no contribution. In particular, this settles the remaining case of the previous item.

- Term No. 10: Given an index $l$ and mutually different indices $\kappa_1, \ldots, \kappa_r$, we choose indices $k$ and $\kappa \notin \{\kappa_1, \ldots, \kappa_r\}$ (here we use the hypothesis that $r < n$) such that $k \neq l$ and, when $r < n - 1$, a complementary set of indices $\nu_1, \ldots, \nu_{n-r-1}$ to contract this term with the multivector field $\partial_k \wedge \partial_l \wedge \partial_k \wedge \partial_{\nu_1} \wedge \ldots \wedge \partial_{\nu_{n-r-1}}$ (no sum over $k$), concluding that $X^{\kappa_1, \ldots, \kappa_r}$ cannot depend on $q^l$. Obviously, there is one case where this argument does not work: namely when $N = 1$. In this situation, the whole term vanishes identically, and no conclusion can be drawn.

This proves the statements in item 1. of the theorem. Moreover, it allows to simplify term no. 6, as follows:

\[
- \frac{(-1)^{r-1}}{(r-1)!} \frac{\partial X^{i, \mu_2, \ldots, \mu_r}}{\partial p} dp^\mu_i \wedge dp \wedge d^n x_{\mu_2, \ldots, \mu_r}.
\]

Next we analyze terms no. 6 and 9.

- Term No. 6 (second part): Given an index $k$ and mutually different indices $\kappa_2, \ldots, \kappa_r$, we choose an index $\kappa \notin \{\kappa_2, \ldots, \kappa_r\}$ and a complementary set of indices $\nu_1, \ldots, \nu_{n-r}$ to contract this term, in the simplified form given in the previous equation, with the multivector field $\partial_k \wedge \partial_0 \wedge \partial_{\nu_1} \wedge \ldots \wedge \partial_{\nu_{n-r}}$, concluding that $X^{k, \kappa_2, \ldots, \kappa_r}$ cannot depend on $p$. 

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• Term No. 9: Given indices \( i, j, \mu, \nu \) and mutually different indices \( \kappa_2, \ldots, \kappa_r \), we choose a set of indices \( \nu_1, \ldots, \nu_{n-r} \) such that \( \{\kappa_2, \ldots, \kappa_r\} \cap \{\nu_1, \ldots, \nu_{n-r}\} = \emptyset \) to contract this term with the multivector field \( \partial_{\mu}^i \wedge \partial_{\nu}^j \wedge \partial_{\nu_1} \wedge \ldots \wedge \partial_{\nu_{n-r}} \); obtaining

\[
\frac{\partial X^{j,\mu_2,\ldots,\mu_r}}{\partial p_i^\mu} \epsilon_{\mu_2 \ldots \mu_r \nu_1 \ldots \nu_{n-r}} = \frac{\partial X^{i,\mu_2,\ldots,\mu_r}}{\partial p_j^\nu} \epsilon_{\mu_2 \ldots \mu_r \nu_1 \ldots \nu_{n-r}} .
\]  

(64)

Now assume \( \nu \) to be chosen so that \( \nu \notin \{\kappa_2, \ldots, \kappa_r, \nu_1, \ldots, \nu_{n-r}\} \). Then if \( \mu \notin \{\kappa_2, \ldots, \kappa_r\} \), we can take \( \mu = \nu_1 \), say, to conclude that \( X^{j,\kappa_2,\ldots,\kappa_r} \) cannot depend on \( p_i^\mu \):

\[
\frac{\partial X^{j,\mu_2,\ldots,\mu_r}}{\partial p_i^\mu} = 0 \quad \text{if} \quad \mu \notin \{\mu_2, \ldots, \mu_r\} .
\]  

(65)

Moreover, if \( \mu \in \{\kappa_2, \ldots, \kappa_r\} \), this result implies that applying an operator \( \partial_{i}^{\nu} \) (with arbitrary \( i \)) to eq. (64) gives zero since on the rhs, the \( \epsilon \)-tensor kills all terms in the sum over the indices \( \mu_2, \ldots, \mu_r \) in which the index \( \mu \) appears among them:

\[
\frac{\partial^2 X^{j,\mu_2,\ldots,\mu_r}}{\partial p_i^\mu \partial p_j^\mu} = 0 \quad \text{if} \quad \mu \in \{\mu_2, \ldots, \mu_r\} \quad \text{(no sum over \( \mu \))} .
\]  

(66)

The general solution to eqs (65) and (66) can be written in the form

\[
X^{j,\mu_2,\ldots,\mu_r} = \sum_{s=1}^{r} \frac{1}{(s-1)!} \frac{1}{(r-s)!} \sum_{\pi \in S_{r-1}} (-1)^{\pi} \prod_{j_2}^{s} p_{j_2}^{\mu_{\pi(j_2)}} \prod_{j_s}^{r} p_{j_s}^{\mu_{\pi(j_s)}} Y_{s-1}^{j,j_2,\ldots,j_s,\mu_{\pi(s+1)}\ldots\mu_{\pi(r)}} ,
\]

where \( S_{r-1} \) denotes the permutation group of \( \{2, \ldots, r\} \) and the coefficients \( Y_{s-1}^{j,j_2,\ldots,j_s,\mu_{\pi(s+1)}\ldots\mu_{\pi(r)}} \) are local functions on \( E \): they do not depend on the multimomentum variables \( p_k^\mu \) or the energy variable \( p \) and are totally antisymmetric both in \( j_2, \ldots, j_s \) and in \( \mu_{s+1}, \ldots, \mu_r \). Differentiating this expression with respect to \( p_i^\mu \) with \( \mu = \mu_2 \) gives

\[
\frac{\partial X^{j,\mu_3,\ldots,\mu_r}}{\partial p_i^\mu} \epsilon_{\mu_3 \ldots \mu_r \nu_1 \ldots \nu_{n-r}} \quad \text{(no sum over \( \mu \))}
\]

\[
= \sum_{s=2}^{r} \frac{1}{(s-2)!} \frac{1}{(r-s)!} \sum_{\pi \in S_{r-2}} (-1)^{\pi} \prod_{j_3}^{s} p_{j_3}^{\mu_{\pi(j_3)}} \prod_{j_s}^{r} p_{j_s}^{\mu_{\pi(j_s)}} Y_{s-1}^{j,j_3,\ldots,j_s,\mu_{\pi(s+1)}\ldots\mu_{\pi(r)}} \times \epsilon_{\nu_1 \ldots \nu_{n-r}} \epsilon_{\mu_3 \ldots \mu_r \nu_1 \ldots \nu_{n-r}} ,
\]

where \( S_{r-2} \) denotes the permutation group of \( \{3, \ldots, r\} \), which shows that eq. (64) will hold provided that

\[
Y_{s-1}^{j,j_3,\ldots,j_s,\mu_{\pi(s+1)}\ldots\mu_{\pi(r)}} = -Y_{s-1}^{j,j_3,\ldots,j_s,\mu_{\pi(s+1)}\ldots\mu_{\pi(r)}} .
\]

This proves the statements in item 2. of the theorem. To proceed further, we write down the equations obtained from the remaining terms.
• Term No. 1:
  \[ \frac{\partial \tilde{X}^{\mu_3 \ldots \mu_r \nu}}{\partial x^\nu} = 0. \]  
  \(67\)

• Term No. 2:
  \[ \frac{\partial \tilde{X}^{\mu_2 \ldots \nu}}{\partial q^i} = (-1)^{r-1} \frac{\partial X^{\mu_2 \ldots \nu}}{\partial x^\nu}. \]  
  \(68\)

• Term No. 3:
  \[ \frac{\partial \tilde{X}^{\mu_2 \ldots \nu}}{\partial p_i^\mu} = - \frac{\partial X^{i, \mu_2 \ldots \nu}}{\partial x^\mu} + \sum_{s=2}^r \delta_{\mu_s} \frac{\partial X^{i, \mu_2 \ldots \mu_{s-1} \nu \mu_{s+1} \ldots \nu}}{\partial x^\nu}. \]  
  \(69\)

• Term No. 4:
  \[ \frac{\partial \tilde{X}^{\mu_2 \ldots \nu}}{\partial p_i} = (-1)^r \frac{\partial X^{\mu_2 \ldots \nu}}{\partial x^\nu}. \]  
  \(70\)

• Term No. 5:
  \[ \frac{\partial X^{\mu_1 \ldots \nu}}{\partial p_i} = - \frac{\partial X^{\mu_1 \ldots \nu}}{\partial q^i}. \]  
  \(71\)

• Term No. 7:
  \[ \frac{\partial X^{\mu_1 \ldots \nu}}{\partial p_k^\mu} = \delta_i^k \delta_{\mu_k} \frac{\partial X^{\mu_1 \ldots \nu}}{\partial x^\mu} - \sum_{s=1}^r \delta_i^k \delta_{\mu_s} \frac{\partial X^{\mu_1 \ldots \mu_{s-1} \nu \mu_{s+1} \ldots \nu}}{\partial x^\nu} \] 
  \[= - \sum_{s=1}^r (-1)^{s-1} \delta_{\mu_s} \frac{\partial X^{k, \mu_1 \ldots \mu_{s-1} \nu \mu_{s+1} \ldots \nu}}{\partial q^i}. \]  
  \(72\)

• Term No. 8:
  \[ \frac{\partial X^{\mu_1 \ldots \nu}}{\partial q^i} = \frac{\partial X^{\mu_1 \ldots \nu}}{\partial q^i}. \]  
  \(73\)

Beginning with eqs (60) and (71), we observe first of all that the rhs of both equations does not depend on the energy variable, so they can be immediately integrated with respect to \(p\). Moreover, the rhs of eq. (69) does not depend on the \(p_{ij}^\mu\), not only when \(\mu \notin \{\mu_2, \ldots, \mu_r\}\) but even when \(\mu \in \{\mu_2, \ldots, \mu_r\}\). (Of course, it also does not depend on \(p\).) Indeed, assuming that \(\mu = \mu_2\), say, we have

\[ \frac{\partial}{\partial p_j^\mu} \left( - \frac{\partial X^{i, \mu_2 \ldots \nu}}{\partial x^\mu} + \sum_{s=2}^r \delta_{\mu_s} \frac{\partial X^{i, \mu_2 \ldots \mu_{s-1} \nu \mu_{s+1} \ldots \nu}}{\partial x^\nu} \right) \] 
\[= - \frac{\partial^2 X^{i, \mu_2 \ldots \nu}}{\partial x^\mu \partial p_j^\mu} + \frac{\partial^2 X^{i, \nu \mu_3 \ldots \nu}}{\partial x^\nu \partial p_j^\mu}, \]
and in the sum over $\nu$, only the term with $\nu = \mu_2$ survives, as for all other terms one has $\mu \notin \{\nu, \mu_3, \ldots, \mu_r\}$, but this term cancels exactly the first summand. Thus according to the lemma formulated in the appendix, we can integrate eq. (69) explicitly to obtain

$$
\tilde{X}^{\mu_2 \ldots \mu_r} = (-1)^r \ p \ \frac{\partial X^{\mu_2 \ldots \mu_r}}{\partial x^\nu} - \Sigma^{-1} \left( \sum_{s=2}^r p_i^{\mu_s} \frac{\partial X^{\mu_2 \ldots \mu_s}}{\partial x^\nu} - \sum_{s=2}^r p_i^{\mu_s} \frac{\partial X^{\mu_2 \ldots \mu_s + 1 \mu_s + 1 \ldots \mu_r}}{\partial x^\nu} \right)
$$

$$
+ \tilde{Y}^{\mu_2 \ldots \mu_r},
$$

where the $\tilde{Y}^{\mu_2 \ldots \mu_r}$ are local functions on $E$: they do not depend on the multimomentum variables or on the energy variable. The same procedure works for eq. (72): its rhs does not depend on the $p_i^\kappa$, not only when $\kappa \notin \{\mu_1, \ldots, \mu_r\}$ but even when $\kappa \in \{\mu_1, \ldots, \mu_r\}$. (Of course, it also does not depend on $p$.) Indeed, assuming that $\kappa = \mu_1$, say, we have

$$
\frac{\partial}{\partial p_i^\kappa} \left( \delta_{i}^{k} X^{\mu_1 \ldots \mu_r} - \sum_{s=1}^{r} \delta_{i}^{k} \delta_{\kappa}^{\mu_s} \frac{\partial X^{\mu_1 \ldots \mu_s}}{\partial x^\nu} - \sum_{s=1}^{r} (-1)^{s-1} \delta_{\kappa}^{\mu_s} \frac{\partial X^{\mu_1 \ldots \mu_s - 1 \mu_s + 1 \ldots \mu_r}}{\partial q^i} \right)
$$

$$
= - \delta_{i}^{k} \frac{\partial^2 X^{\mu_2 \ldots \mu_r}}{\partial x^\nu \partial p_i^\kappa} - \frac{\partial^2 X^{\mu_1 \mu_2 \ldots \mu_r}}{\partial q^i \partial p_i^\kappa},
$$

and both of these terms vanish. Thus according to the lemma formulated in the appendix, we can integrate eq. (69) explicitly to obtain

$$
X^{\mu_1 \ldots \mu_r} = - p \ \frac{\partial X^{\mu_1 \ldots \mu_r}}{\partial q^i} + p_i^{\mu_1} \frac{\partial X^{\mu_1 \ldots \mu_r}}{\partial x^\mu} - \sum_{s=1}^{r} p_i^{\mu_s} \frac{\partial X^{\mu_1 \ldots \mu_s - 1 \mu_s + 1 \ldots \mu_r}}{\partial x^\nu}
$$

$$
- \Sigma^{-1} \left( \sum_{s=1}^{r} (-1)^{s-1} p_i^{\mu_s} \frac{\partial X^{\mu_1 \ldots \mu_s - 1 \mu_s + 1 \ldots \mu_r}}{\partial q^i} \right)
$$

$$
+ Y_i^{\mu_1 \ldots \mu_r},
$$

where the $Y_i^{\mu_1 \ldots \mu_r}$ are local functions on $E$: they do not depend on the multimomentum variables or on the energy variable. Direct calculation now shows that eqs (67), (68) and (73) reduce to

$$
\frac{\partial Y^{\mu_3 \ldots \mu_r}}{\partial x^\nu} = 0,
$$

$$
\frac{\partial Y^{\mu_2 \ldots \mu_r}}{\partial q^i} = (-1)^{r-1} \frac{\partial Y_i^{\mu_2 \ldots \mu_r}}{\partial x^\nu},
$$

\[3\]Recall that $\Sigma^{-1}$ is the operator that acts on polynomials in the multimomentum variables and the energy variable without constant term by multiplying the homogeneous component of degree $s$ by $1/s$. 22
\[ \frac{\partial Y_{ij}^{\mu_1...\mu_r}}{\partial q^i} = \frac{\partial Y_{ji}^{\mu_1...\mu_r}}{\partial q^j}, \]  

(78)

respectively. This system of equations is easily solved by setting

\[ \tilde{Y}_{ij}^{\mu_2...\mu_r} = (-1)^{r-1} \frac{\partial X_{ij}^{\mu_2...\mu_r}}{\partial x^\mu} p_i^\mu, \quad Y_{ij}^{\mu_1...\mu_r} = \frac{\partial X_{ij}^{\mu_1...\mu_r}}{\partial q^i}, \]  

(79)

where the \( X_{ij}^{\mu_1...\mu_r} \) are local functions on \( E \): they do not depend on the multimomentum variables or on the energy variable. This completes the proof of the statements in item 3. of the theorem.

All that remains to be shown are the final statements concerning exact Hamiltonian multivector fields. To this end, we apply the exterior derivative to eq. (50) and use eq. (10) to simplify the expressions involving derivatives with respect to the space-time variables. Combining this with eq. (49) and collecting the terms, we get

\[ L_X \theta = \frac{1}{(r-1)!} \left( \frac{\partial X_{ij}^{\mu_2...\mu_r}}{\partial x^\mu} p_i^\mu - (-1)^r \frac{\partial X_{ij}^{\mu_1...\mu_r}}{\partial x^\mu} p_i^\mu \right) + (-1)^r \sum_{s=2}^{r} \frac{\partial X_{ij}^{\mu_1...\mu_s-1,\mu_s+1...\mu_r}}{\partial x^\mu} p_i^{\mu_s} - (-1)^r \tilde{X}_{ij}^{\mu_2...\mu_r} \right) d^n x_{\mu_2...\mu_r} \]

(79)

\[ = \frac{1}{r!} \left( \frac{\partial X_{ij}^{\mu_1...\mu_r}}{\partial p_j^\nu} p_i^\nu + \sum_{s=1}^{r} (-1)^s-1 \frac{\partial X_{ij}^{\mu_1...\mu_s-1,\mu_s+1...\mu_r}}{\partial p_j^\nu} p_i^{\mu_s} - \tilde{X}_{ij}^{\mu_1...\mu_r} \right) dp_j^\nu \land d^n x_{\mu_1...\mu_r} \]

\[ + \frac{1}{r!} \left( \frac{\partial X_{ij}^{\mu_1...\mu_r}}{\partial p} p_i^\nu + \sum_{s=1}^{r} (-1)^s-1 \frac{\partial X_{ij}^{\mu_1...\mu_s-1,\mu_s+1...\mu_r}}{\partial p} p_i^{\mu_s} - \tilde{X}_{ij}^{\mu_1...\mu_r} \right) dp \land d^n x_{\mu_1...\mu_r} \]

\[ - \frac{1}{r} \frac{\partial X_{ij}^{\mu_1...\mu_r}}{\partial q^j} p_i^\mu dq^j \land dq^i \land d^n x_{\mu_1...\mu_r} \]

\[ - \frac{(-1)^r}{r!} \frac{\partial X_{ij}^{\mu_1...\mu_r}}{\partial p_j^\nu} p_i^\nu dq^j \land dp_j^\nu \land d^n x_{\mu_1...\mu_r} \]

\[ - \frac{(-1)^r}{r!} \frac{\partial X_{ij}^{\mu_1...\mu_r}}{\partial p} p_i^\nu dq^j \land dp \land d^n x_{\mu_1...\mu_r} \].

(Note that the last three terms would have to be omitted if \( r = n \).) Numbering the terms in this equation from 1 to 7, we see that the conditions imposed by the fact that
X should be locally Hamiltonian are already sufficient to eliminate the last four terms and imply that the first three terms will vanish as well if and only if we have

\[
(\Sigma^{-1} - 1) \left( \sum_{s=1}^{r} (-1)^{s-1} p_{j}^{\mu_{s}} \frac{\partial X_{j, \mu_{s} \ldots \mu_{s-1} \mu_{s+1} \ldots \mu_{r}}}{\partial q^{i}} \right) = 0 ,
\]

\[
(\Sigma^{-1} - 1) \left( p_{i}^{\mu} \frac{\partial X_{i, \mu_{2} \ldots \mu_{r}}}{\partial x^{\mu_{1}}} - \sum_{s=2}^{r} p_{i}^{\mu_{s}} \frac{\partial X_{i, \mu_{s} \ldots \mu_{s-1} \mu_{s+1} \ldots \mu_{r}}}{\partial x^{\nu}} \right) = 0 ,
\]

and

\[
\frac{\partial X_{\mu_{1} \ldots \mu_{r}}}{\partial q^{i}} = 0 , \quad \frac{\partial X_{\mu_{2} \ldots \mu_{r}}}{\partial x^{\nu}} = 0 .
\]

But this means that the coefficients of the multimomentum variables in the above expressions must be independent of the multimomentum variables and that the coefficients \(X_{\mu_{1} \ldots \mu_{r}}\) can without loss of generality be assumed to vanish, which completes the proof of the theorem.

\[\square\]

**Proof of Theorem 1.3 and Theorem 1.4, item 1.** Clearly, it suffices to prove the statement of Theorem 1.3, namely the possibility to decompose an arbitrary locally Hamiltonian \(r\)-multivector field \(X\) into the sum of a fiberwise polynomial locally Hamiltonian \(r\)-multivector field and an \(r\)-multivector field taking values in the kernel of \(\omega\), locally and in coordinates, since both properties—that of being fiberwise polynomial as well as that of taking values in the kernel of \(\omega\)—are algebraic conditions which hold in any coordinate system as soon as they hold in one and which are preserved when such local decompositions are glued together by means of a partition of unity. The same goes for the main statement of Theorem 1.4, namely the fact that the homogeneous components \(X_{s}\) of a fiberwise polynomial locally Hamiltonian \(r\)-multivector field \(X\) take values in the kernel of \(\omega\) as soon as \(s\) lies outside the range between \(-1\) and \(r - 1\). But in adapted local coordinates, all these statements follow directly from Theorem 2.4.

In fact, note that

\[
\left[ \Sigma , \frac{\partial}{\partial x^{\mu_{1}}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_{r}}} \right] = 0 , \quad \left[ \Sigma , \frac{\partial}{\partial q^{i}} \wedge \frac{\partial}{\partial x^{\mu_{2}}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_{r}}} \right] = 0 ,
\]

\[
\left[ \Sigma , \frac{\partial}{\partial p_{i}^{\mu_{1}}} \wedge \frac{\partial}{\partial x^{\mu_{2}}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_{r}}} \right] = - \frac{\partial}{\partial p_{i}^{\mu_{1}}} \wedge \frac{\partial}{\partial x^{\mu_{2}}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_{r}}} ,
\]

\[
\left[ \Sigma , \frac{\partial}{\partial p} \wedge \frac{\partial}{\partial x^{\mu_{2}}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_{r}}} \right] = - \frac{\partial}{\partial p} \wedge \frac{\partial}{\partial x^{\mu_{2}}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_{r}}} ,
\]

so if \(X\) has the local coordinate expression (48), its Lie derivative along the scaling vector field \(\Sigma\) will, according to the Leibniz rule for the Lie derivative, have the local coordinate expression
\[ L_{\Sigma} X = \frac{1}{(r-1)!} \left( \Sigma \cdot X^{i, \mu_2 \ldots \mu_r} \right) \frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} + \frac{1}{r!} \left( (\Sigma - 1) \cdot X^{i, \mu_1 \ldots \mu_r} \right) \frac{\partial}{\partial p^i} \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} + \frac{1}{(r-1)!} \left( (\Sigma - 1) \cdot \check{X}^{\mu_2 \ldots \mu_r} \right) \frac{\partial}{\partial p^i} \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} + L_{\Sigma} \xi \],

and if \( X \) is locally Hamiltonian, Theorem 2.3 forces the coefficient functions \( X^{i, \mu_2 \ldots \mu_r} \), \( X^{i, \mu_1 \ldots \mu_r} \) and \( \check{X}^{\mu_2 \ldots \mu_r} \) to be polynomials of degree \( r - 1 \), \( r \) and \( r \), respectively, in the multimomentum variables and the energy variable. Finally, Proposition 1.1 implies that if \( X \) is locally Hamiltonian or globally Hamiltonian or exact Hamiltonian or takes values in the kernel of \( \omega \), the same is true for all its homogeneous components \( X_s \).

\[ \square \]

The following proposition clarifies the interpretation of homogeneous locally Hamiltonian multivector fields.

**Proposition 2.5** Let \( X \) be a locally Hamiltonian \( r \)-multivector field on \( P \). Then

1. \( X \) is exact Hamiltonian iff \( [\Sigma, X] \) takes values in the kernel of \( \omega \).

2. If \( [\Sigma, X] - sX \) takes values in the kernel of \( \omega \), for some integer \( s \) between 0 and \( r - 1 \), then \( X \) is globally Hamiltonian with associated Poisson form

\[ \frac{(-1)^{r-1}}{s+1} i_X \theta . \]

3. If \( [\Sigma, X] + X \) takes values in the kernel of \( \omega \), then \( i_X \theta = 0 \).

**Proof.** The first statement follows immediately from eq. (44). Similarly, the second claim can be proved by multiplying eq. (11) by \((-1)^{r-1}/(s+1)\) and combining it with eq. (11) and eq. (11) to give

\[ d \left( \frac{(-1)^{r-1}}{s+1} i_X \theta \right) = \frac{(-1)^{r-1}}{s+1} L_X \theta + \frac{1}{s+1} i_X \omega = \frac{1}{s+1} i_{[\Sigma,X] + X} \omega , \]

which equals \( i_X \omega \) since, by hypothesis, \( i_{[\Sigma,X] - sX} \omega = 0 \). Finally, the third statement follows by observing that the kernel of \( \omega \) is contained in the kernel of \( \theta \) and hence according to the hypothesis made,

\[ 0 = i_{[\Sigma,X] + X} \theta = L_{\Sigma} i_X \theta - i_X L_{\Sigma} \theta + i_X \theta = L_{\Sigma} i_X \theta , \]

where we have used eq. (11). Therefore, according to Proposition A.1, \( i_X \theta \) is the pull-back to \( P \) of an \( n \)-form on \( E \) via the projection that defines \( P \) as a vector bundle.
over $E$, which in turn can be obtained as the pull back to $E$ of $i_X \theta$ via the zero section of $P$ over $E$. But this pull-back is zero, since $\theta$ vanishes along the zero section of $P$ over $E$.

\[ \square \]

It may be instructive to spell all this out more explicitly for locally Hamiltonian vector fields ($r=1$) and bivector fields ($r=2$).

We begin by writing down the general form of a locally Hamiltonian vector field $X$: in adapted local coordinates, it has the representation

\[ X = X^\mu \frac{\partial}{\partial x^\mu} + X^i \frac{\partial}{\partial q^i} + X_i^\mu \frac{\partial}{\partial p_i^\mu} + \tilde{X} \frac{\partial}{\partial p}, \]

(80)

where according to Theorem 2.4, the coefficient functions $X^\mu$ and $X_i^\mu$ depend only on the local coordinates $x^\rho$ for $M$ and on the local fiber coordinates $q^r$ for $E$ (the $X^\mu$ being independent of the latter as soon as $N > 1$), whereas the coefficient functions $X_i^\mu$ and $\tilde{X}$ are explicitly given by

\[ X_i^\mu = -p \frac{\partial X^\mu}{\partial q^i} + p_i^\nu \frac{\partial X^\nu}{\partial x^\mu} - p_i^\mu \frac{\partial X^\mu}{\partial x^i} + p_j^\mu \frac{\partial X^j}{\partial q^i} + \partial X^\mu - \partial q^i \]

(81)

(82)

with coefficient functions $X_i^\mu$ that once again depend only on the local coordinates $x^\rho$ for $M$ and on the local fiber coordinates $q^r$ for $E$. Regarding the decomposition (38), the situation here is particularly interesting and somewhat special since $\omega$ is nondegenerate on vector fields, so there are no nontrivial vector fields taking values in the kernel of $\omega$ and hence the decomposition (38) can be improved:

\[ \textbf{Corollary 2.6} \]

Any locally Hamiltonian vector field $X$ on $P$ can be uniquely decomposed into the sum of two terms,

\[ X = X_- + X_+, \]

(83)

where

- $X_-$ has scaling degree $-1$, i.e., $[\Sigma, X_-] = -X_-$, and is vertical with respect to the projection onto $E$.

- $X_+$ has scaling degree $0$, i.e., $[\Sigma, X_+] = 0$, is exact Hamiltonian, is projectable onto $E$ and coincides with the canonical lift of its projection onto $E$.  

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Proof. In adapted local coordinates, the two contributions to $X$ are, according to eqs (81) and (82), given by

$$X_+ = \frac{\partial X^\mu}{\partial q^i} \frac{\partial}{\partial p^i} + \frac{\partial X^\nu}{\partial x^\nu} \frac{\partial}{\partial p}$$

and

$$X_- = X^\mu \frac{\partial}{\partial x^\mu} + X^i \frac{\partial}{\partial q^i} - \left( \frac{\partial X^j}{\partial q^i} p_j^\mu - \frac{\partial X^\mu}{\partial x^\nu} p_i^\nu + \frac{\partial X^\nu}{\partial x^\nu} p_i^\mu + \frac{\partial X^\mu}{\partial q^i} p \right) \frac{\partial}{\partial p^i}$$

Thus all statements of the corollary follow from what has already been shown, except for the very last one, which is based on the following remark.

Remark. Every bundle automorphism of $E$ (as a fiber bundle over $M$) admits a canonical lift to a bundle automorphism of its first order jet bundle $JE$ (as an affine bundle over $E$) and, by appropriate (twisted affine) dualization, to the extended multiphase space $P$ (as a vector bundle over $E$). Similarly, passing to generators of one-parameter groups, one sees that every vector field $X_E$ on $E$ that is projectable to a vector field $X_M$ on $M$ admits a canonical lift to a vector field $X_{JE}$ on $JE$ and, by appropriate (twisted affine) dualization, to a vector field $X_P$ on $P$. (See, for example, [7, §4B].) When $N=1$, lifting to $P$ is even possible for arbitrary diffeomorphisms of $E$ and arbitrary vector fields on $E$; since in this case $P$ can be identified with the $n^{th}$ exterior power of the cotangent bundle of $E$. Explicitly, in terms of adapted local coordinates $(x^\mu, q^i, p^\mu_i, p)$, we may write

$$X_M = X^\mu \frac{\partial}{\partial x^\mu},$$

and

$$X_E = X^\mu \frac{\partial}{\partial x^\mu} + X^i \frac{\partial}{\partial q^i},$$

where, except for $N=1$, the $X^\mu$ do not depend on the $q^r$; then

$$X_P = X^\mu \frac{\partial}{\partial x^\mu} + X^i \frac{\partial}{\partial q^i} - \left( \frac{\partial X^j}{\partial q^i} p_j^\mu - \frac{\partial X^\mu}{\partial x^\nu} p_i^\nu + \frac{\partial X^\nu}{\partial x^\nu} p_i^\mu + \frac{\partial X^\mu}{\partial q^i} p \right) \frac{\partial}{\partial p^i}$$
Obviously, $X_P$ has scaling degree 0 and hence is not only locally but even exact Hamiltonian. Conversely, since the expressions in eqs (85) and (88) are identical, we see that all exact Hamiltonian vector fields are obtained by this lifting procedure. Similarly, one can show that all diffeomorphisms of $P$ that preserve the multicanonical form $\theta$ are obtained by lifting of automorphisms or, for $N = 1$, diffeomorphisms of $E$: this is the field theoretical analogue of a well-known theorem in geometric mechanics, according to which all diffeomorphisms of a cotangent bundle that preserve the canonical form $\theta$ are induced by diffeomorphisms of its base manifold.

Similarly, we write down the general form of a locally Hamiltonian bivector field $X$; in adapted local coordinates, it has the representation

$$X = \frac{1}{2} X^{\mu\nu} \frac{\partial}{\partial x^\mu} \wedge \frac{\partial}{\partial x^\nu} + X^{i,\mu} \frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial x^\mu}$$

$$\quad + \frac{1}{2} X^{\mu\nu}_i \frac{\partial}{\partial p^\mu_i} \wedge \frac{\partial}{\partial x^\nu} + \bar{X}^\mu \frac{\partial}{\partial p} \wedge \frac{\partial}{\partial x^\mu}$$

$$\quad + \xi,$$

where according to Theorem 2.4, the coefficient functions $X^{\mu\nu}$, $Y_i^{ij}$ and $Y_0^{i,\mu}$ depend only on the local coordinates $x^\rho$ for $M$ and on the local fiber coordinates $q^r$ for $E$ (the $X^{\mu\nu}$ being independent of the latter as soon as $N > 1$), whereas the coefficient functions $X_i^{\mu\nu}$ and $\bar{X}^\mu$ are explicitly given by

$$X_i^{\mu\nu} = -p_i \frac{\partial X^{\mu\nu}}{\partial q^i} + p_i^\kappa \frac{\partial X^{\mu\nu}}{\partial x^\kappa} - p_i^\mu \frac{\partial X^{\kappa\nu}}{\partial x^\kappa} - p_i^\nu \frac{\partial X^{\mu\kappa}}{\partial x^\kappa}$$

$$- \frac{1}{2} p_j^\mu p_k^\nu \frac{\partial Y_j^{i,jk}}{\partial q^i} - p_j^\mu \frac{\partial Y_j^{\nu,\mu}}{\partial x^\nu} + \frac{1}{2} p_j^\nu p_k^\mu \frac{\partial Y_j^{i,jk}}{\partial q^i} + p_j^\nu \frac{\partial Y_j^{\nu,\mu}}{\partial x^\nu} + \frac{\partial X^{\mu\nu}}{\partial x^\nu}$$

(91)

with coefficient functions $X_i^{\mu\nu}$ that once again depend only on the local coordinates $x^\rho$ for $M$ and on the local fiber coordinates $q^r$ for $E$. Note that now

$$\bar{X}^\mu = p \frac{\partial X^{\mu\nu}}{\partial x^\nu} - \frac{1}{2} p_i^\mu p_j^\nu \frac{\partial Y_i^{ij}}{\partial x^\nu} - p_i^\nu \frac{\partial Y_0^{i,\mu}}{\partial x^\nu} + \frac{1}{2} p_i^\mu p_j^\nu \frac{\partial Y_i^{ij}}{\partial x^\nu} + p_i^\mu \frac{\partial Y_0^{i,\nu}}{\partial x^\nu} - \frac{\partial X^{\mu\nu}}{\partial x^\nu}$$

(92)

with coefficient functions $X_i^{\mu\nu}$ that once again depend only on the local coordinates $x^\rho$ for $M$ and on the local fiber coordinates $q^r$ for $E$. Note that now

$$X_- = \frac{1}{2} \frac{\partial X^{\mu\nu}}{\partial q^i} \frac{\partial}{\partial p^i} \wedge \frac{\partial}{\partial x^\nu} - \frac{\partial X^{\mu\nu}}{\partial x^\nu} \frac{\partial}{\partial p} \wedge \frac{\partial}{\partial x^\mu}.$$  

(93)

Moreover, the operator $1 + L_\Sigma$ kills $X_-$ and removes the factors $\frac{1}{2}$ in front of the quadratic terms in eqs (91) and (92).
To conclude this section, let us note that the definition of projectability of vector fields can be immediately generalized to multivector fields: an \( r \)-multivector field \( X_E \) on the total space \( E \) of a fiber bundle over a manifold \( M \) with bundle projection \( \pi : E \to M \) is called projectable if for any two points \( e_1 \) and \( e_2 \) in \( E \),
\[
\bigwedge^r T_{e_1} \pi \cdot X_E(e_1) = \bigwedge^r T_{e_2} \pi \cdot X_E(e_2) \quad \text{if} \quad \pi(e_1) = \pi(e_2),
\]
or in other words, if there exists an \( r \)-multivector field \( X_M \) on \( M \) such that
\[
\bigwedge^r T \pi \circ X_E = X_M \circ \pi.
\]
In adapted local coordinates, this amounts to requiring that if we write
\[
X_E = \frac{1}{r!} X^{\mu_1 \ldots \mu_r} \frac{\partial}{\partial x^{\mu_1}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} + \ldots,
\]
where the dots denote 1-vertical terms, the coefficients \( X^{\mu_1 \ldots \mu_r} \) should depend only on the local coordinates \( x^\rho \) for \( M \) but not on the local fiber coordinates \( q^r \) for \( E \). Now we introduce the following terminology.

**Definition 2.7** An \( r \)-multivector field on \( P \) is called projectable if it is projectable with respect to any one of the three projections from \( P \): to \( P_0 \), to \( E \) and to \( M \).

With this terminology, Theorem 2.4 states that for \( 0 < r < n \), locally Hamiltonian \( r \)-multivector fields on \( P \) are projectable as soon as \( N > 1 \) and are projectable to \( E \) but not necessarily to \( P_0 \) or to \( M \) when \( N = 1 \). (Inspection of eq. (62) shows, however, that they are projectable to \( P_0 \) if and only if they are projectable to \( M \).)

Considering the special case of vector fields \( (r = 1) \), we believe that vector fields on the total space of a fiber bundle over space-time which are not projectable should be regarded as pathological, since they generate transformations which do not induce transformations of space-time. It is hard to see how such transformations might be interpreted as candidates for symmetries of a physical system. By analogy, we shall adopt the same point of view regarding multivector fields of higher degree, since although these do not generate diffeomorphisms of \( E \) as a manifold, they may perhaps allow for an interpretation as generators of superdiffeomorphisms of an appropriate supermanifold built over \( E \) as its even part.

### 3 Poisson forms and Hamiltonian forms

Our aim in this section is to give an explicit construction of Poisson \((n - r)\)-forms and, more generally, of Hamiltonian \((n - r)\)-forms on the extended multiphase space \( P \), where \( 0 \leq r \leq n \). (Note that eq. (24) only makes sense for \( r \) in this range.) A special
role is played by closed forms, since closed forms are always Hamiltonian and closed forms that vanish on the kernel of \( \omega \) are always Poisson: these are in a sense the trivial examples. In other words, the main task is to understand the extent to which general Hamiltonian forms deviate from closed forms and general Poisson forms deviate from closed forms that vanish on the kernel of \( \omega \).

As a warm-up exercise, we shall settle the extreme cases of tensor degree 0 and \( n \). The case \( r = n \) has already been analyzed in Ref. [2], so we just quote the result.

**Proposition 3.1**  A function \( f \) on \( P \), regarded as a 0-form, is always Hamiltonian and even Poisson. Moreover, its associated Hamiltonian \( n \)-multivector field \( X \) is, in adapted local coordinates and modulo terms taking values in the kernel of \( \omega \), given by eq. (56).

The case \( r = 0 \) is equally easy.

**Proposition 3.2**  An \( n \)-form \( f \) on \( P \) is Hamiltonian or Poisson if and only if it can be written as the sum of a constant multiple of \( \theta \) with a closed form which is arbitrary if \( f \) is Hamiltonian and vanishes on the kernel of \( \omega \) if \( f \) is Poisson.

Indeed, if \( f \) is a Hamiltonian \( n \)-form, the multivector field \( X \) that appears in eq. (24) will in fact be a function which has to be locally Hamiltonian and hence, by Proposition 2.2, constant. Thus \( df \) must be proportional to \( \omega \) and so \( f \) must be the sum of some constant multiple of \( \theta \) and a closed form.

The intermediate cases \((0 < r < n)\) are much more interesting. To handle them, the first step is to identify the content of the kernel condition (26) in adapted local coordinates (for completeness, we also include the two extreme cases):

**Proposition 3.3**  An \((n - r)\)-form \( f \) on \( P \), with \( 0 \leq r \leq n \), vanishes on the kernel of \( \omega \) if and only if, in adapted local coordinates, it can be written in the form

\[
\begin{align*}
f &= \frac{1}{r!} f^{\mu_1 \cdots \mu_r} d^n x_{\mu_1 \cdots \mu_r} + \frac{1}{(r+1)!} f^{\mu_0 \cdots \mu_r} dq^i \wedge d^n x_{\mu_0 \cdots \mu_r} \\
&\quad + \frac{1}{r!} f^{i, \mu_1 \cdots \mu_r} dp^i \wedge d^n x_{\mu_1 \cdots \mu_r} \\
&\quad + \frac{1}{(r+1)!} f^{i, \mu_0 \cdots \mu_r} \left(dp \wedge d^n x_{\mu_0 \cdots \mu_r} - dq^i \wedge dp^i \wedge d^n x_{\mu_0 \cdots \mu_r} \right),
\end{align*}
\]

where the second term in the last bracket is to be omitted if \( r = n-1 \) whereas only the first term remains if \( r = n \).
Note that for one-forms (just as for functions), the kernel condition (26) is void, since \( \omega \) is non-degenerate. Also, it is in this case usually more convenient to replace eq. (97) by the standard local coordinate representation

\[
f = f_\mu \, dx^\mu + f_i \, dq^i + f_\mu^i \, dp_i^\mu + f_0 \, dp.
\]  

\[(98)\]

**Proof.** Dualizing the statements of the proof of Proposition 2.1, we see first of all that forms of degree \( n-r \) vanishing on the kernel of \( \omega \) must be \((n-r-2)\)-horizontal (since they vanish on 3-vertical multivector fields) and that the only term which is not \((n-r-1)\)-horizontal is

\[dq^i \wedge dp^k_i \wedge d^n x_{\mu_0 \ldots \mu_r}.
\]

Thus we may write any such form as

\[
f = \frac{1}{r!} f^{\nu_1 \ldots \nu_r} \, d^n x_{\nu_1 \ldots \nu_r} + \frac{1}{(r+1)!} f_i^{\mu_0 \ldots \mu_r} \, dq^i \wedge d^n x_{\mu_0 \ldots \mu_r}
\]

\[
+ \frac{1}{(r+1)!} f_k^{\mu_0 \ldots \mu_r} \, dp^k_i \wedge d^n x_{\mu_0 \ldots \mu_r}
\]

\[
+ \frac{1}{(r+1)!} f_{i,k}^{\mu_0 \ldots \mu_r} \, dq^i \wedge dp^k_i \wedge d^n x_{\mu_0 \ldots \mu_r},
\]  

\[(99)\]

and conclude from the requirement that \( f \) should also vanish on multivector fields \( \xi \) of the type given in eqs (46) and (47) that the local coordinate representation of a general form of degree \( n-r \) vanishing on the kernel of \( \omega \) is the one given in eq. (97). Indeed, contracting eq. (99) with the bivector

\[
\frac{\partial}{\partial q^i} \wedge \frac{\partial}{\partial p^k_i} + \delta^k_i \frac{\partial}{\partial p^\kappa} \wedge \frac{\partial}{\partial x^\kappa}
\]

leads to the conclusion that the expression

\[
\left(\delta^k_i \delta^\mu_{\kappa} f^{i,\mu_0 \ldots \mu_r} + f_{i,k}^{k,\mu_0 \ldots \mu_r} \right) \, d^n x_{\mu_0 \ldots \mu_r}
\]

must vanish, so \( f \) takes the form

\[
f = \frac{1}{r!} f^{\nu_1 \ldots \nu_r} \, d^n x_{\nu_1 \ldots \nu_r} + \frac{1}{(r+1)!} f_i^{\mu_0 \ldots \mu_r} \, dq^i \wedge d^n x_{\mu_0 \ldots \mu_r}
\]

\[
+ \frac{1}{(r+1)!} f_k^{\mu_0 \ldots \mu_r} \, dp^k_i \wedge d^n x_{\mu_0 \ldots \mu_r}
\]

\[
+ \frac{1}{(r+1)!} f_{i,k}^{\mu_0 \ldots \mu_r} \left(dp \wedge d^n x_{\mu_0 \ldots \mu_r} - dq^i \wedge dp^\mu_i \wedge d^n x_{\mu_0 \ldots \mu_r}\right)
\]  

\[(100)\]

Similarly, contracting eq. (100) with the bivector

\[
\frac{\partial}{\partial p^\mu_i} \wedge \frac{\partial}{\partial x^\nu} + \frac{\partial}{\partial p^\nu_i} \wedge \frac{\partial}{\partial x^\mu}
\]
leads to the conclusion that the expression

\[ f^{\mu_0 \ldots \mu_r}_\mu d^n x^{\mu_0 \ldots \mu_r \nu} + f^{\mu_0 \ldots \mu_r}_\nu d^n x^{\mu_0 \ldots \mu_r \mu} \]

must vanish: setting \( \mu = \nu \), it is easily seen that this forces the coefficients \( f^{\mu_0 \ldots \mu_r}_\mu \) to vanish when the indices \( \mu_0, \ldots, \mu_r \) are all different from \( \mu \), and letting \( \mu \neq \nu \), we then conclude that

\[ f^{\mu_0 \ldots \mu_r}_{\mu s-1 \mu s+1 \ldots \mu_r} = f^{\mu_0 \ldots \mu_r}_{\nu s-1 \nu s+1 \ldots \nu_r} \quad \text{(no sum over } \mu \text{ or } \nu \text{)} \]

so that we can write

\[ f^k_{\mu_0 \ldots \mu_r} = \sum_{s=0}^{r} (-1)^s \delta^s_{\mu s} f^{k}_{\mu_0 \ldots \mu s-1 \mu s+1 \ldots \mu_r} \quad \text{(101)} \]

Inserting this expression into eq. (100), we arrive at eq. (97).

The proposition above can be used to prove the following interesting and useful fact.

**Proposition 3.4** An \((n - r)\)-form \( f \) on \( P \), with \( 0 \leq r \leq n \), vanishes on the kernel of \( \omega \) if and only if there exists an \((r + 1)\)-multivector field \( X \) on \( P \) such that

\[ f = i_X \omega \quad \text{(102)} \]

Then obviously,

\[ df = L_X \omega \quad \text{(103)} \]

In particular, \( f \) is closed if and only if \( X \) is locally Hamiltonian.

**Proof.** The “if” part being obvious, observe that it suffices to prove the “only if” part locally, in the domain of definition of an arbitrary system of adapted local coordinates, by constructing the coefficients of \( X \) from those of \( f \). (Indeed, since the relation between \( f \) and \( X \) postulated in eq. (102) is purely algebraic, i.e., it does not involve derivatives, we can construct a global solution patching together local solutions with a partition of unity.) But comparing eqs (48), (49) and (97) shows that when \( r < n \), this can be achieved by setting

\[ X^{\mu_0 \ldots \mu_r} = (-1)^r f^{\mu_0 \ldots \mu_r}_t \]
\[ X^{t, \mu_1 \ldots \mu_r} = (-1)^r f^{t, \mu_1 \ldots \mu_r}_i \]
\[ X^{\mu_0 \ldots \mu_r}_3 = (-1)^{r+1} f^{\mu_0 \ldots \mu_r}_i \]
\[ \tilde{X}^{\mu_1 \ldots \mu_r} = - f^{\mu_1 \ldots \mu_r} \quad \text{(104)} \]

while for \( r = n \), only the last equation is pertinent (for \( r = n - 1 \), the same conclusion can also be reached by comparing eqs (53), (54) and (98)).
Corollary 3.5 An \((n-r)\)-form \(f\) on \(P\), with \(0 \leq r \leq n\), is a Hamiltonian form if and only if \(df\) vanishes on the kernel of \(\omega\) and is a Poisson form if and only if both \(df\) and \(f\) vanish on the kernel of \(\omega\).

With these preliminaries out of the way, we can proceed to the construction of Poisson forms which are not closed. As we shall see, there are two such constructions which, taken together, will be sufficient to handle the general case.

The first construction is a generalization of the universal multimomentum map of Ref. [2], which to each exact Hamiltonian \(r\)-multivector field \(F\) on \(P\) associates a Poisson \((n-r)\)-form \(J(F)\) on \(P\) defined by eq. (105) below. What remained unnoticed in Ref. [2] is that this construction works even when \(X\) is only locally Hamiltonian. In fact, we have the following generalization of Proposition 4.3 of Ref. [2]:

**Proposition 3.6** For every locally Hamiltonian \(r\)-multivector field \(F\) on \(P\), with \(0 \leq r \leq n\), the formula

\[
J(F) = (-1)^{r-1} i_F \theta \tag{105}
\]

defines a Poisson \((n-r)\)-form \(J(F)\) on \(P\) whose associated Hamiltonian multivector field is \(F + [\Sigma, F]\), that is, we have

\[
d(J(F)) = i_{F+[\Sigma,F]} \omega \ . \tag{106}
\]

**Proof.** Obviously, \(J(F)\) vanishes on the kernel of \(\omega\) since this is contained in the kernel of \(\theta\). Moreover, since \(L_F \omega\) is supposed to vanish, we can use eqs (11), (22) and (13) to compute

\[
d(J(F)) = (-1)^{r-1} d(i_F \theta) = (-1)^{r-1} L_F \theta - i_F d\theta \\
= (-1)^r L_F i_{\Sigma} \omega + i_F \omega \\
= (-1)^r L_F i_{\Sigma} \omega + i_{\Sigma} L_F \omega + i_F \omega \\
= - i_{[F,\Sigma]} \omega + i_F \omega .
\]

The second construction uses differential forms on \(E\), pulled back to differential forms on \(P\) via the target projection \(\tau : P \to E\). Characterizing which of these are Hamiltonian forms and which are Poisson forms is a simple exercise.

**Proposition 3.7** Let \(f_0\) be an \((n-r)\)-form on \(E\), with \(0 < r < n\). Then

- \(\tau^* f_0\) is a Hamiltonian form on \(P\) if and only if \(df_0\) is \((n-r)\)-horizontal.
- \(\tau^* f_0\) is a Poisson form on \(P\) if and only if \(f_0\) is \((n-r-1)\)-horizontal and \(df_0\) is \((n-r)\)-horizontal.
Proof. In adapted local coordinates \((x^\mu, q^i)\) for \(E\) and \((x^\mu, q^i, p^\mu_i, p)\) for \(P\), we can write

\[
f_0 = \frac{1}{r!} f^{\mu_1 \ldots \mu_r}_0 d^n x_{\mu_1 \ldots \mu_r} + \frac{1}{(r+1)!} (f_0)^{\mu_0 \ldots \mu_r}_0 dq^i \wedge d^n x_{\mu_0 \ldots \mu_r} + \ldots ,
\]

where the dots denote higher order terms containing at least two \(dq\)'s. Now applying Proposition 3.3 to \(\tau^* f_0\), we see that \(\tau^* f_0\) will vanish on the kernel of \(\omega\) if and only if the terms denoted by the dots all vanish, i.e., if \(f_0\) can be written in the form

\[
f_0 = \frac{1}{r!} f^{\mu_1 \ldots \mu_r}_0 d^n x_{\mu_1 \ldots \mu_r} + \frac{1}{(r+1)!} (f_0)^{\mu_0 \ldots \mu_r}_0 dq^i \wedge d^n x_{\mu_0 \ldots \mu_r} .
\]

But this is precisely the condition for the \((n-r)\)-form \(f_0\) to be \((n-r-1)\)-horizontal. (Note that this equivalence holds even when \(r = n - 1\), provided we understand the condition of being 0-horizontal to be empty.) Similarly, since Proposition 3.4 implies that a form on \(P\) is Hamiltonian if and only if its exterior derivative vanishes on the kernel of \(\omega\), the same argument applied to \(d(\tau^* f_0) = \tau^* df_0\) shows that, irrespectively of whether \(\tau^* f_0\) itself vanishes on the kernel of \(\omega\) or not and hence whether we use eq. (107) or eq. (108) as our starting point, \(\tau^* f_0\) will be Hamiltonian if and only if

\[
d f_0 = \frac{1}{(r-1)!} \frac{\partial f^{\mu_1 \ldots \mu_r}_0}{\partial x^\nu} d^n x_{\mu_2 \ldots \mu_r} \\
+ \frac{1}{r!} \left( \frac{\partial f^{\mu_1 \ldots \mu_r}_0}{\partial q^i} - \frac{\partial (f_0)^{\mu_1 \ldots \mu_r}_0}{\partial x^\nu} \right) dq^i \wedge d^n x_{\mu_1 \ldots \mu_r} .
\]

But this is precisely the condition for the \((n-r+1)\)-form \(df_0\) to be \((n-r)\)-horizontal. Moreover, it is easy to write down an associated Hamiltonian \(r\)-multivector field \(X_0\):

\[
X_0 = \frac{(-1)^r}{r!} \left( \frac{\partial f^{\mu_1 \ldots \mu_r}_0}{\partial q^i} - \frac{\partial (f_0)^{\mu_1 \ldots \mu_r}_0}{\partial x^\nu} \right) \frac{\partial}{\partial p^\mu_i} \wedge \frac{\partial}{\partial x^\nu} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} \\
- \frac{1}{(r-1)!} \frac{\partial f^{\mu_2 \ldots \mu_r}_0}{\partial x^\nu} \frac{\partial}{\partial p} \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} .
\]

Note also that if \(f_0\) is \((n-r-1)\)-horizontal and thus has the form stated in eq. (108), \(df_0\) would contain just one additional higher order term, namely

\[
\frac{1}{(r+1)!} \frac{\partial (f_0)^{\mu_0 \ldots \mu_r}_0}{\partial q^i} dq^i \wedge dq^j \wedge d^n x_{\mu_0 \ldots \mu_r} .
\]

Its absence means that

\[
\frac{\partial (f_0)^{\mu_0 \ldots \mu_r}_0}{\partial q^i} = \frac{\partial (f_0)^{\mu_0 \ldots \mu_r}_0}{\partial q^j} ,
\]

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so there exist local functions \( f_{0}^{\mu_{0}...\mu_{r}} \) on \( E \) such that

\[
(f_{0})_{i}^{\mu_{0}...\mu_{r}} = \frac{\partial f_{0}^{\mu_{0}...\mu_{r}}}{\partial q^{i}}.
\]

This implies that \( f_{0} \) can be written as the sum

\[
f_{0} = f_{h} + f_{c}
\]

of a horizontal form \( f_{h} \) and a closed form \( f_{c} \), defined by setting

\[
f_{h} = \frac{1}{r!} \left( f_{0}^{\mu_{1}...\mu_{r}} - \frac{\partial f_{0}^{\mu_{1}...\mu_{r}\nu}}{\partial x^{\nu}} \right) d^{n}x_{\mu_{1}...\mu_{r}}, \tag{112}
\]

and

\[
f_{c} = \frac{1}{r!} \frac{\partial f_{0}^{\mu_{1}...\mu_{r}\nu}}{\partial x^{\nu}} d^{n}x_{\mu_{1}...\mu_{r}} + \frac{1}{(r+1)!} \frac{\partial f_{0}^{\mu_{0}...\mu_{r}}}{\partial q^{i}} dq^{i} \wedge d^{n}x_{\mu_{0}...\mu_{r}}. \tag{113}
\]

The same kind of local decomposition into the sum of a horizontal form and a closed form can also be derived if \( f_{0} \) is arbitrary and thus has the form stated in eq. \((107)\); this case can be handled by decreasing induction on the number of \( dq \)'s that appear in the higher order terms denoted by the dots in eq. \((107)\). We shall refrain from working this out in detail, since unfortunately the decomposition \((111)\) depends on the system of adapted local coordinates used in its construction: under coordinate transformations, the terms \( f_{h} \) and \( f_{c} \) mix. Therefore, this decomposition has no coordinate independent meaning and is in general valid only locally.

Finally, we note that in the above discussion, we have deliberately excluded the extreme cases \( r = 0 \) (n-forms) and \( r = n \) (functions). For n-forms, the equivalences stated above would be incorrect since if \( f_{0} \) has tensor degree \( n \) and hence \( X_{0} \) has tensor degree 0, \( i_{X_{0}}\omega \) would by Proposition \(2.2\) be a constant multiple of \( \omega \) whereas \( d(\tau^{*}f_{0}) \) would be reduced to a linear combination of terms of the form \( dq^{i} \wedge d^{n}x \), implying that \( \tau^{*}f_{0} \) can only be Hamiltonian if it is closed. For functions, the construction is uninteresting since according to Proposition \(3.1\) all functions on \( P \) are Poisson, and not just the ones lifted from \( E \).

Now we are ready to state our main decomposition theorem. (In what follows, we shall simply write \( f_{0} \) instead of \( \tau^{*}f_{0} \) when there is no danger of confusion, the main exception being the proof of Theorem \(3.8\) below).

**Theorem 3.8** Any Hamiltonian \((n-r)\)-form and, in particular, any Poisson \((n-r)\)-form \( f \) on \( P \), with \( 0 < r < n \), admits a unique decomposition

\[
f = f_{0} + f_{+} + f_{c} \quad \text{with} \quad f_{+} = \sum_{s=1}^{r} f_{s}, \tag{114}
\]

where
1. \( f_0 \) is (the pull-back to \( P \) of) an \((n-r)\)-form on \( E \) whose exterior derivative is \((n-r)\)-horizontal and which is otherwise arbitrary if \( f \) is Hamiltonian whereas it is restricted to be \((n-r-1)\)-horizontal iff \( f \) is Poisson.

2. \( f_+ \) is of the form
   \[
   f_+ = J(F) = (-1)^{r-1} i_F \omega \quad \text{with} \quad F = (1 + L_\Sigma)^{-1} X_+ ,
   \]
   and correspondingly, for \( s = 1, \ldots, r \), \( f_s \) is of the form
   \[
   f_s = (-1)^{r-1} \sum_s \theta \quad (116)
   \]
   where \( X \) is any fiberwise polynomial Hamiltonian \( r \)-multivector field associated with \( f \), decomposed according to eq. (38).

3. \( f_c \) is a closed \((n-r)\)-form on \( P \) which vanishes on the zero section of \( P \) (as a vector bundle over \( E \)) and which is otherwise arbitrary if \( f \) is Hamiltonian whereas it is restricted to vanish on the kernel of \( \omega \) iff \( f \) is Poisson.

We shall refer to eq. (114) and to eq. (119) below as the canonical decomposition of Hamiltonian forms or Poisson forms on \( P \).

**Proof.** Let \( f \) be a Poisson \((n-r)\)-form and \( X \) be a Hamiltonian \( r \)-multivector field associated with \( f \). As already mentioned in the introduction, we may without loss of generality assume \( X \) to be fiberwise polynomial and decompose it into homogeneous components with respect to scaling degree, according to eq. (38):

\[
X = X_- + X_+ + \xi \quad \text{with} \quad X_+ = \sum_{s=1}^r X_{s-1} .
\]

Then defining \( F \) as in the theorem, or equivalently, by

\[
F = \sum_{s=1}^r F_{s-1} \quad \text{with} \quad F_{s-1} = \frac{1}{s} X_{s-1} ,
\]

we obtain

\[
F + [\Sigma, F] = X_+ ,
\]

and hence according to eq. (106), the exterior derivative of the difference \( f - J(F) \) is given by

\[
d(f - J(F)) = df - d(J(F)) = i_X \omega - i_{X_+} \omega = i_{X_-} \omega .
\]

Applying the equivalence stated in eq. (12), we see that since \( X_- \) has scaling degree \(-1\), \( i_{X_-} \omega \) must have scaling degree \(0\) and hence, according to Proposition A.1, is the pull-back to \( P \) of some \((n-r)\)-form \( f'_0 \) on \( E \):

\[
d(f - J(F)) = i_{X_-} \omega = \tau^* f'_0 .
\]

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Next, we define $f_0$ to be the restriction of $f - J(F)$ to the zero section of $P$, or more precisely, its pull-back to $E$ with the zero section $s_0 : E \to P$,

$$f_0 = s_0^* (f - J(F)),$$

and set

$$f_c = f - \tau^* f_0 - J(F).$$

Then

$$df_c = d(f - J(F)) - d\left(\tau^* s_0^* (f - J(F))\right)$$
$$= d(f - J(F)) - \tau^* s_0^* d(f - J(F))$$
$$= \tau^* f_0' - \tau^* s_0^* \tau^* f_0'$$
$$= 0,$$

and

$$s_0^* f_c = s_0^* (f - J(F)) - s_0^* \tau^* f_0 = f_0 - s_0^* \tau^* f_0 = 0,$$

showing that indeed, $f_c$ is closed and vanishes on the zero section of $P$.

□

**Proof of Theorem 1.3 and Theorem 1.4, item 2.** These statements are immediate consequences of Theorem 3.8.

□

**Remark.** It should be noted that despite appearances, the decompositions (114) of Theorem 3.8 and (40) of Theorem 1.4 are not necessarily identical: for $s = 1, \ldots, r$, the $f_s$ of eq. (114) and the $f_s$ of eq. (40) may differ by homogeneous closed $(n - r)$-forms of scaling degree $s$. But the decomposition (114) of Theorem 3.8 seems to be the more natural one.

Theorem 3.8 implies that Poisson forms have a rather intricate local coordinate representation, involving two locally Hamiltonian multivector fields. Indeed, if we take $f$ to be a general Poisson $(n-r)$-form on $P$, with $0 < r < n$, we can apply Propositions 3.4 and 3.6 to rewrite eq. (114) in the form

$$f = f_0 + (-1)^{r-1} i_F \theta + (-1)^r i_{F_c} \omega,$$

where $f_0$ is as before while $F$ and $F_c$ are two locally Hamiltonian multivector fields on $P$ of tensor degree $r$ and $r+1$, respectively, satisfying $F_\perp = 0$ and $(F_c)_\perp = 0$.

In terms of the standard local coordinate representations (97) for $f$, (108) for $f_0$ and (48) for $F$ and for $F_c$, we obtain, according to eqs (49) and (50),

$$f_{\mu_1 \cdots \mu_r} = (-1)^{-1} \rho F_{\mu_1 \cdots \mu_r} + \sum_{s=1}^r (-1)^{r-s} p^\mu_i F^{i, \mu_1 \cdots \mu_s \mu_{s+1} \cdots \mu_r}$$
$$+ f_{0 \mu_1 \cdots \mu_r} + (-1)^{r-1} (\tilde{F}_c)^{\mu_1 \cdots \mu_r},$$

$^4$The condition $(F_c)_\perp = 0$ will guarantee that $i_{F_c} \omega$ vanishes on the zero section of $P$. 37
\[ f_{i_1 \ldots i_r} = - \sum_{s=0}^{r} (-1)^s \left( \sum_{\pi} \left( -1 \right)^{\pi} \left( \sum_{\sigma} \left( -1 \right)^{\sigma} \left( \sum_{\tau} \left( -1 \right)^{\tau} \right) \right) \right) + \left( f_0 \right)^{0_1 \ldots 0_r} - \left( F_c \right)^{0_1 \ldots 0_r} \quad (121) \]

\[ f^{i_1 \ldots i_r} = \left( F_c \right)^{i_1 \ldots i_r} \quad (122) \]

\[ f^{i_0 \ldots i_r} = \left( F_c \right)^{i_0 \ldots i_r} \quad (123) \]

where the coefficients of $F$ and of $F_c$ are subject to the constraints listed in Theorem 2.4; in particular, the coefficients $(F_c)^{0_1 \ldots 0_r}$ and $(F_c)^{i_1 \ldots i_r}$ can be completely expressed in terms of the coefficients $(F_c)^{0_1 \ldots 0_r}$ and $(F_c)^{i_1 \ldots i_r}$, according to eqs (62) and (63) (with $r$ replaced by $r+1$, $X$ replaced by $F_c$ and $X_-$ replaced by 0). In particular, we see that the coefficients $f^{i_1 \ldots i_r}$ are “antisymmetric polynomials in the multimomentum variables” of degree $r$. More explicitly, we can rewrite eq. (120) in the form

\[ f^{i_1 \ldots i_r} = (-1)^{r-1} \left( F_c \right)^{i_1 \ldots i_r} + \sum_{s=1}^{r} f^{i_1 \ldots i_r} + (-1)^{r-1} \left( F_c \right)^{i_1 \ldots i_r} \quad (124) \]

where inserting the expansion (61) (with $X$ replaced by $F$, $X_{s-1}$ replaced by $F_{s-1}$ and $Y_{s-1}$ replaced by $G_{s-1} = \frac{1}{s} g_s$, gives, after a short calculation,

\[ f^{i_1 \ldots i_r} = (-1)^{r-1} \frac{1}{s! (r-s)!} \sum_{\pi \in S_r} (-1)^{\pi} p^{\mu_{\pi(1)}}_{i_1} \ldots p^{\mu_{\pi(s)}}_{i_s} g_{s}^{j_1 \ldots j_{s-1} \mu_{\pi(s+1)} \ldots \mu_{\pi(r)}} \quad (125) \]

It is an instructive exercise to spell this out more explicitly for the case of Poisson forms $f$ of degree $n-1$ ($r = 1$), whose standard local coordinate representation (97) reads

\[ f = f^\mu d^nx_\mu + \frac{1}{2} f^{i_1} d^i x_\mu + \frac{1}{2} f^{\mu_\nu} dq_\mu \wedge d^nx_\mu + f^{i_1 \mu} dp_i^\mu \wedge d^nx_\mu + \frac{1}{2} f^{i_1 \mu} \left( dp \wedge d^nx_{\kappa \lambda} - dq_\mu \wedge dp_i^\mu \wedge d^nx_{\kappa \lambda} \right) \quad (126) \]

with coefficient functions $f^\mu$, $f^{i_1 \mu}$, $f^{i_1 \mu}$ and $f^{i_1 \mu}$ which, according to eqs (89)-(92) and (120)-(123), are given by

\[ f^\mu = p F^\mu + p_i^\mu F^i + f_0^\mu + \left( F_c \right)^\mu \quad (127) \]

\[ f^{i_1 \mu} = - (p_i^\mu F^{i_1} - p_i^\mu F^i) + \left( f_0 \right)^{i_1 \mu} - \left( F_c \right)^{i_1 \mu} \quad (128) \]

\[ f^{i_1 \mu} = \left( F_c \right)^{i_1 \mu} \quad (129) \]

\[ f^{i_1 \mu} = \left( F_c \right)^{i_1 \mu} \quad (130) \]
with
\[(F_c)^{i,\mu} = p^\mu_j (G_c)^{ij}, \quad (131)\]
where the coefficient functions \(F^\mu, F^i, f^\mu_0, (f_0)^{\mu\nu}, (F_c)^{\mu\nu}\) and \((G_c)^{ij}\) all depend only on the local coordinates \(x^\rho\) for \(M\) and on the local fiber coordinates \(q^r\) for \(E\) (the \(F^\mu\) and \((F_c)^{\mu\nu}\) being independent of the latter as soon as \(N > 1\)), whereas the coefficients \((F_c)^{\mu\nu}\) and \((\tilde{F}_c)^{\mu\nu}\) can be completely expressed in terms of the coefficients \((F_c)^{\mu\nu}\) and \((G_c)^{ij}\), according to eqs (91) and (92) (with \(X\) replaced by \(F_c\), \(Y\) replaced by \(G_c\) and \(X_\_\_\_\_\) replaced by 0). Obviously, little structural insight can be gained from such an explicit representation: the canonical decomposition (114) or (119) as such is much more instructive.

Finally, we want to clarify the relation between Poisson forms and Hamiltonian multivector fields in terms of their standard local coordinate representations.

**Theorem 3.9** Let \(f\) be a Poisson \((n-r)\)-form and \(X\) be a Hamiltonian \(r\)-multivector field on \(P\) associated with \(f\). Assume that, in adapted local coordinates, \(f\) and \(X\) are given by eqs (97) and (48), respectively. Then
\[
X^{\mu_1...\mu_r} = (-1)^{r-1} \left( \frac{\partial f^{\mu_1...\mu_r}}{\partial p} - \frac{\partial f'^{\mu_2...\mu_r}}{\partial x^\nu} \right), \quad (132)
\]
\[
X^{i,\mu_2...\mu_r} = \frac{1}{n-r+1} \frac{\partial f^{\mu_2...\mu_r\mu}}{\partial p_i^\mu}, \quad (133)
\]
\[
X^{i,\mu_1...\mu_r} = (-1)^{r} \left( \frac{\partial f^{\mu_1...\mu_r}}{\partial q^i} - \frac{\partial f'^{\mu_1...\mu_r}}{\partial x^\nu} \right), \quad (134)
\]
\[
\tilde{X}^{\mu_2...\mu_r} = - \frac{\partial f^{\mu_2...\mu_r}}{\partial x^\nu}, \quad (135)
\]
that is, locally and modulo terms taking values in the kernel of \(\omega\), \(X\) is given by
\[
X = - \frac{1}{(r-1)!} \left( \frac{\partial f^{\mu_2...\mu_r\mu}}{\partial x^\mu} \frac{\partial}{\partial p} - \frac{1}{r} \frac{\partial f^{\mu_2...\mu_r\mu}}{\partial p} \frac{\partial}{\partial x^\mu} \right)
+ \frac{1}{r} \frac{\partial f^{\mu_2...\mu_r\mu\nu}}{\partial x^\nu} \frac{\partial}{\partial x^\mu} \right) \wedge \frac{\partial}{\partial x^{\mu_2}} \wedge \ldots \wedge \frac{\partial}{\partial x^{\mu_r}} \quad (136)
\]

If, in the canonical decomposition (114) or (119) of \(f\), the closed term \(f_\_\_\_ = (-1)^{r} i_{F_c}\omega\) is absent, then \(f^{\mu_0...\mu_r} = 0\). If \(f\) is horizontal with respect to the projection onto \(M\), then \(f^{i,\mu_0...\mu_r} = 0\). In these cases, the above formulas simplify accordingly.
Proof. There are several methods for proving this, with certain overlaps. Let us begin with the “trivial” case of closed forms \( f \), for which we must have \( X = 0 \). Assuming \( f \) to be of the form

\[
\begin{align*}
f_c &= (-1)^r i_F, \\
f &= f_0 + (-1)^{r-1} i_F \theta,
\end{align*}
\]

and using eqs (120)–(123) to rewrite the expressions on the rhs of the above equations in terms of the components of \( F_c \), we must show that

\[
\begin{align*}
\frac{\partial (\tilde{F}_c)}{\partial p} &+ (-1)^r \frac{\partial (F_c)}{\partial x^\nu} = 0, \\
\frac{\partial (\tilde{F}_c)}{\partial p_i^\mu} &+ (-1)^r \frac{\partial (F_c)}{\partial x^\nu} = 0, \\
\frac{\partial (\tilde{F}_c)}{\partial q^i} &- (-1)^r \frac{\partial (F_c)}{\partial x^\nu} = 0, \\
\frac{\partial (\tilde{F}_c)}{\partial x^\nu} &+ (-1)^r \frac{\partial (F_c)}{\partial x^\nu} = 0.
\end{align*}
\]

But this follows directly from the analogues of eqs (63), (69), (68) and (67), respectively, which hold since \( F_c \) is locally Hamiltonian. To handle the remaining cases where \( f \) is of the form

\[
\begin{align*}
f &= f_0 + (-1)^{r-1} i_F \theta,
\end{align*}
\]

it is easier to proceed by direct inspection of eq. (24). Indeed, we may for a general Poisson form \( f \) apply the exterior derivative to eq. (97) and compare the result with eq. (49). In this way, eqs (135), (134) and (132) can be obtained directly by equating the coefficients of \( d^n x_{\mu_1 \ldots \mu_r} \), of \( dq^i \wedge d^n x_{\mu_1 \ldots \mu_r} \) and of \( dp \wedge d^n x_{\mu_1 \ldots \mu_r} \), respectively. The only case which requires an additional argument is eq. (133), since collecting terms proportional to \( dp_i^\mu \wedge d^n x_{\mu_1 \ldots \mu_r} \) leads to

\[
\begin{align*}
\frac{(-1)^{r-1}}{(r-1)!} X^{i_1, \mu_2 \ldots \mu_r} dp_i^\mu \wedge d^n x_{\mu_2 \ldots \mu_r} \\
&= \frac{1}{r!} \frac{\partial f_i^{\mu_1 \ldots \mu_r}}{\partial p_i^\mu} dp_i^\mu \wedge d^n x_{\mu_1 \ldots \mu_r} \\
&\quad - \frac{1}{(r-1)!} \frac{\partial f^{i_1, \mu_2 \ldots \mu_r}}{\partial x^\nu} dp_i^\mu \wedge d^n x_{\mu_2 \ldots \mu_r} - \frac{(-1)^r}{r!} \frac{\partial f^{i_1, \mu_1 \ldots \mu_r}}{\partial x^\nu} dp_i^\mu \wedge d^n x_{\mu_1 \ldots \mu_r}.
\end{align*}
\]

But when \( f \) is of the form \( f = f_0 + (-1)^{r-1} i_F \theta \), eq. (122) implies that the last two terms on the rhs of eq. (137) vanish. Moreover, since \( F \) is Hamiltonian, we know from Theorem 2.4 that the \( F^{\mu_1 \ldots \mu_r} \) depend on the \( p_i^\mu \) only if \( \mu \in \{\mu_1, \ldots, \mu_r\} \), and hence according to eq. (120), the same is true for the \( f^{\mu_1 \ldots \mu_r} \). This reduces the first term on the rhs of eq. (137) to an expression which, when compared with the lhs, leads to the conclusion that for any choice of mutually different indices \( \mu \) and \( \mu_2, \ldots, \mu_r \), we have

\[
X^{i, \mu_2 \ldots \mu_r} = \frac{\partial f^{\mu_2 \ldots \mu_r}}{\partial p_i^\mu} \quad \text{if } \mu \notin \{\mu_2, \ldots, \mu_r\} \quad \text{(no sum over } \mu\}.
\]

Summing over \( \mu \) gives eq. (133). \qed
4 Poisson brackets

In the characterization of locally Hamiltonian multivector fields and of Poisson forms derived in the previous two sections, the decomposition into homogeneous terms with respect to scaling degree plays a central role. It is therefore natural to ask how this decomposition complies with the Schouten bracket of Hamiltonian multivector fields and with the Poisson bracket of Poisson forms. To this end, let us first recall the definition of the Poisson bracket between Poisson forms given in [1] for \((n - 1)\)-forms and in [2] for forms of arbitrary degree.

**Definition 4.1** Let \(f\) and \(g\) be Poisson forms of tensor degree \(n - r\) and \(n - s\) on \(P\), respectively. Their Poisson bracket is the Poisson form of tensor degree \(n - r - s + 1\) on \(P\) defined by

\[
\{ f, g \} = (-1)^{r(s-1)} i_X i_Y \omega + d \left( (-1)^{(r-1)(s-1)} i_X f - i_X g - (-1)^{(r-1)s} i_Y i_X \theta \right),
\]

where \(X\) and \(Y\) are Hamiltonian multivector fields associated with \(f\) and \(g\), respectively.

We find the following properties of the two mentioned bracket operations with respect to scaling degree.

**Proposition 4.2** Let \(X\) and \(Y\) be homogeneous multivector fields on \(P\) of scaling degree \(k\) and \(l\), respectively. Then their Schouten bracket \([X, Y]\) is of scaling degree \(k + l\):

\[
L_{\Sigma} X = kX, \quad L_{\Sigma} Y = lY \quad \implies \quad L_{\Sigma} [X, Y] = (k + l) [X, Y].
\]

**Proof.** The proposition is a consequence of the graded Jacobi identity for multivector fields [8], which can be rewritten as the statement that the Schouten bracket with a given multivector field \(Z\) of odd/even tensor degree acts as an even/odd superderivation:

\[
[Z, [X, Y]] = [[Z, X], Y] + (-1)^{(t-1)(r-1)} [X, [Z, Y]].
\]

In particular, since \(\Sigma\) has tensor degree 1,

\[
[\Sigma, [X, Y]] = [[\Sigma, X], Y] + [X, [\Sigma, Y]],
\]

from which the proposition follows immediately.

**Corollary 4.3** Let \(X\) and \(Y\) be locally Hamiltonian multivector fields on \(P\) of scaling degree \(-1\). Then their Schouten bracket \([X, Y]\) takes values in the kernel of \(\omega\).
**Proof.** From the preceding proposition, \([X, Y]\) is a locally Hamiltonian multivector field of scaling degree \(-2\). and hence, by Theorems 1.3 and 1.4, must take values in the kernel of \(\omega\).

\[\square\]

For the Poisson bracket of Poisson forms, we have the following property.

**Proposition 4.4** Let \(f\) and \(g\) be homogeneous Poisson forms on \(P\) of scaling degree \(k\) and \(l\), respectively. Then their Poisson bracket \(\{f, g\}\) is of scaling degree \(k + l - 1\):

\[L_\Sigma f = kf, \quad L_\Sigma g = lg \quad \Rightarrow \quad L_\Sigma \{f, g\} = (k + l - 1) \{f, g\}.\] (141)

**Proof.** As explained in the last paragraph of Section 1 (see, in particular, eq. (12)), we can find homogeneous Hamiltonian multivector fields \(X\) of scaling degree \(k - 1\) and \(Y\) of scaling degree \(l - 1\) such that \(i_X \omega = df\) and \(i_Y \omega = dg\). We shall consider each of the terms in the definition of the Poisson bracket separately. We find

\[L_\Sigma (i_Y i_X \omega) = i_Y L_\Sigma i_X \omega + i_{[\Sigma, Y]} i_X \omega = i_Y i_X L_\Sigma \omega + i_Y i_{[\Sigma, X]} \omega + i_{[\Sigma, Y]} i_X \omega = i_Y i_X \omega + (k - 1) i_Y i_X \omega + (l - 1) i_Y i_X \omega = (k + l - 1) i_Y i_X \omega.\]

The same calculation works with \(\omega\) replaced by \(\theta\), so that, since \(L_\Sigma\) commutes with \(d\),

\[L_\Sigma (d (i_Y i_X \theta)) = (k + l - 1) d (i_Y i_X \theta).\]

Moreover,

\[L_\Sigma (d (i_Y f)) = d (L_\Sigma i_Y f) = d (i_Y L_\Sigma f + i_{[\Sigma, Y]} f) = d (k i_Y f + (l - 1) i_Y f) = (k + l - 1) d (i_Y f).\]

and similarly,

\[L_\Sigma (d (i_X g)) = (k + l - 1) d (i_X g).\]

Putting the pieces together, the proposition follows.

\[\square\]

Having shown in what sense both the Schouten bracket and the Poisson bracket respect scaling degree, let us use the canonical decomposition of Poisson forms to express their Poisson bracket in terms of known operations on the simpler objects from which they can be constructed. To start with, we settle the case of homogeneous Poisson forms of positive scaling degree.
Proposition 4.5  Let $X_{k-1}$ be a homogeneous locally Hamiltonian $r$-multivector field on $P$ of scaling degree $k-1$ and $Y_{l-1}$ be a homogeneous locally Hamiltonian $s$-multivector field on $P$ of scaling degree $l-1$, with $1 \leq k, l \leq r$. Set

$$f_k = \frac{(-1)^{r-1}}{k} i_{X_{k-1}} \theta, \quad g_l = \frac{(-1)^{s-1}}{l} i_{Y_{l-1}} \theta.$$  \hfill (142)

Then

$$\{f_k, g_l\} = \frac{(-1)^{r+s}}{k + l - 1} i_{[Y_{l-1}, X_{k-1}]} \theta - (-1)^{(r-1)s} \frac{(k-1)(l-1)(k+l)}{kl(k+l-1)} d(i_{X_{k-1}} i_{Y_{l-1}} \theta).$$  \hfill (143)

Proof. From the defining equation [139] for the Poisson bracket, we find

$$\{f_k, g_l\} = (-1)^{r(s-1)} i_{Y_{l-1}} i_{X_{k-1}} \omega + d \left( \frac{(-1)^{(r-1)s}}{k} i_{Y_{l-1}} i_{X_{k-1}} \theta - \frac{(-1)^{(s-1)}}{l} i_{X_{k-1}} i_{Y_{l-1}} \theta \right)$$

$$\quad - (-1)^{(r-1)s} i_{Y_{l-1}} i_{X_{k-1}} \theta \right)$$

$$= (-1)^{r(s-1)} i_{Y_{l-1}} i_{X_{k-1}} \omega + (-1)^{(r-1)s} \left( \frac{1}{k} + \frac{1}{l} - 1 \right) d \left( i_{Y_{l-1}} i_{X_{k-1}} \theta \right).$$

On the other hand, we compute

$$i_{[Y_{l-1}, X_{k-1}]} \theta = (-1)^{(s-1)r} L_{Y_{l-1}} i_{X_{k-1}} \theta - i_{X_{k-1}} L_{Y_{l-1}} \theta$$

$$= (-1)^{(s-1)r} d i_{Y_{l-1}} i_{X_{k-1}} \theta + (-1)^{(s-1)(r-1)} i_{Y_{l-1}} d i_{X_{k-1}} \theta$$

$$\quad - i_{X_{k-1}} d i_{Y_{l-1}} \theta - (-1)^{s-1} i_{X_{k-1}} i_{Y_{l-1}} \theta$$

$$= (-1)^{(s-1)r} d i_{Y_{l-1}} i_{X_{k-1}} \theta + (-1)^{s(r-1)} k i_{Y_{l-1}} i_{X_{k-1}} \omega$$

$$\quad + (-1)^{(s-1)} l i_{Y_{l-1}} i_{X_{k-1}} \omega - (-1)^{(s-1)} i_{Y_{l-1}} i_{X_{k-1}} \omega$$

$$= (-1)^{(s-1)r} d i_{Y_{l-1}} i_{X_{k-1}} \theta + (-1)^{s(r-1)} (k + l - 1) i_{Y_{l-1}} i_{X_{k-1}} \omega.$$

Thus

$$\{f_k, g_l\} = \frac{(-1)^{r+s}}{k + l - 1} i_{[Y_{l-1}, X_{k-1}]} \theta - \frac{(-1)^{(r-1)s}}{k + l - 1} d \left( i_{Y_{l-1}} i_{X_{k-1}} \theta \right)$$

$$\quad + (-1)^{(r-1)s} \left( \frac{1}{k} + \frac{1}{l} - 1 \right) d \left( i_{Y_{l-1}} i_{X_{k-1}} \theta \right).$$

Now the claim follows because

$$\frac{1}{k} + \frac{1}{l} - 1 - \frac{1}{k + l - 1} = - \frac{(k-1)(l-1)(k+l)}{kl(k+l-1)}.$$
As a special case, consider homogeneous Poisson forms of scaling degree 1, which arise by contracting $\theta$ with a Hamiltonian multivector field of scaling degree 0, that is, with an exact Hamiltonian multivector field (see the first statement in Proposition 2.5). These Poisson forms have been studied in [2] under the name “universal multimomentum map”.

**Corollary 4.6** The space of homogeneous Poisson forms on $P$ of scaling degree 1 closes under the Poisson bracket.

Obviously, it also follows from the proposition that no such statement holds for homogeneous Poisson forms of scaling degree $> 1$, since the second term in eq. (143) vanishes only for $k = 1$ or $l = 1$.

Turning to homogeneous Poisson forms on $P$ of scaling degree 0, which come from forms on $E$ by pull-back, we have

**Proposition 4.7** The space of homogeneous Poisson forms on $P$ of scaling degree 0 is abelian under the Poisson bracket:

$$\{f_0, g_0\} = 0 .$$

**Proof.** Without loss of generality, we may assume the Hamiltonian multivector fields $X_-$ and $Y_-$ associated with $f_0$ and with $g_0$, respectively, to be homogeneous of scaling degree $−1$. Therefore, using the fact that if a multivector field $X$ is homogeneous of scaling degree $k$ and a differential form $\alpha$ is homogeneous of scaling degree $l$, then the differential form $\iota_X\alpha$ is homogeneous of scaling degree $k + l$,

$$L_{\Sigma}X = kX , \quad L_{\Sigma}\alpha = l\alpha \quad \Rightarrow \quad L_{\Sigma}\iota_X\alpha = (k + l)\iota_X\alpha ,$$

which follows immediately from the formula $L_{\Sigma}\iota_X\alpha = \iota_X L_{\Sigma}\alpha + \iota_{[\Sigma,X]}\alpha$, we see that all four terms in the definition (139) of the Poisson bracket between $f_0$ and $g_0$ are differential forms of scaling degree $−1$ and hence must vanish.

For the mixed case of the Poisson bracket between a homogeneous Poisson form of strictly positive scaling degree with one of scaling degree zero, we find the following result.

**Proposition 4.8** Let $X_{k-1}$ be a homogeneous locally Hamiltonian $r$-multivector field on $P$ of scaling degree $k - 1$, with $1 \leq k \leq r$, and let $g_0$ be a homogeneous Poisson $(n - s)$-form on $P$ of scaling degree zero, with associated Hamiltonian $s$-multivector field $Y_-$. Set

$$f_k = \frac{(-1)^{r-1}}{k} i_{X_{k-1}} \theta .$$

(145)
Then
\[ \{ f_k, g_0 \} = - L_{X_{k-1}} g_0 . \] (146)

**Proof.** By Proposition 2.5, \( i_Y \theta \) vanishes. Hence only two of the four terms in the defining equation (139) for the Poisson bracket survive:
\[
\{ f_k, g_0 \} = (-1)^{r(s-1)} i_Y i_{X_{k-1}} \omega - di_{X_{k-1}} g_0 \\
= - (di_{X_{k-1}} g_0 - (-1)^r i_{X_{k-1}} dg_0) = - L_{X_{k-1}} g_0 .
\]

□

Finally, let us consider closed Poisson forms, whose associated Hamiltonian multivector fields vanish. Still, the Poisson bracket of a closed Poisson form with an arbitrary Poisson form does not vanish, but it is once again a closed Poisson form.

**Proposition 4.9** Let \( f \) be a Poisson \((n-r)\)-form on \( P \), with associated Hamiltonian \( r \)-multivector field \( X \), and let \( g \) be a closed Poisson \((n-s)\)-form on \( P \). Set
\[ g = (-1)^s i_{G_c} \omega . \] (147)
Then
\[ \{ f, g \} = (-1)^{r+s-1} i_{[G_c,X]} \omega . \] (148)

**Proof.** As the Hamiltonian multivector field associated with \( g \) vanishes, only one of the four terms in the defining equation (139) for the Poisson bracket survives:
\[
\{ f, g \} = - d(i_X g) = (-1)^{s-1} d(i_X i_{G_c} \omega) = (-1)^{rs-1} i_{[X,G_c]} \omega = (-1)^{r+s-1} i_{[G_c,X]} \omega .
\]
(For the penultimate equation, see, e.g., Proposition 3.3 of Ref. [2].)

□

In view of the canonical decomposition for Poisson forms stated in Theorem 3.8, the above propositions exhaust the possible combinations for the computation of Poisson brackets.

### 5 Conclusions and Outlook

In this paper, we have achieved three goals. First, we have determined the general structure of locally Hamiltonian multivector fields on the extended multiphase space of classical first order field theories. According to Theorem 2.4, the basic structure that arises from explicit calculations in adapted local coordinates is the decomposition of any such multivector field \( X \), of tensor degree \( r \) (\( 0 < r < n \)), into a sum of terms...
of homogeneous scaling degree plus a remainder $\xi$ which is a multivector field taking values in the kernel of $\omega$:

$$X = X_{-1} + X_0 + \ldots + X_{r-1} + \xi \quad \text{with} \quad L_\Sigma X_k = kX_k \,.$$  \hspace{1cm} (149)

Moreover, according to Proposition 2.5 all homogeneous locally Hamiltonian multivector fields of nonnegative scaling degree are in fact globally Hamiltonian, and they are exact Hamiltonian if and only if they have zero scaling degree. At the level of local coefficient functions, this decomposition arises because the coefficient functions have to be antisymmetric polynomials in the multimomentum variables; see eqs (60) and (61).

Second, we have extended the scaling degree analysis to the study of Hamiltonian forms by means of the formula

$$L_\Sigma i_X \omega = i_{X + [\Sigma, X]} \omega \,.$$  

As shown in Theorem 3.8, this leads to a canonical decomposition of any Hamiltonian $(n - r)$-form $f$ ($0 < r < n$) into a sum of terms of homogeneous scaling degree plus a remainder $f_c$ which is a closed form:

$$f = f_0 + f_1 + \ldots + f_r + f_c \quad \text{with} \quad L_\Sigma f_s = s f_s \,.$$  \hspace{1cm} (150)

Moreover, if $X$ is a Hamiltonian multivector field associated with $f$, then

$$f_s = \frac{(-1)^{r-1}}{s} i_{X_{s-1}} \theta \quad \text{for} \ s > 0 \,,$$  \hspace{1cm} (151)

where the $X_{s-1}$ are the homogeneous components of $X$ of nonnegative scaling degree as described before, whereas $f_0$ arises by pull-back from a form on the total space of the configuration bundle of the theory. Locally, this form can be decomposed into the sum of a horizontal form and a closed form (we prove this explicitly only for Poisson forms), but this decomposition has no global, coordinate invariant meaning. The canonical decomposition of Poisson forms is also useful for deriving local formulas for $X$ in terms of $f$; these are given in Theorem 3.9. They clearly show that the situation in multisymplectic geometry resembles that encountered in symplectic geometry but exhibits a significantly richer structure. In particular, the notion of conjugate variables requires a conceptual extension.

Third, we have used the canonical decomposition of Poisson forms to derive explicit formulas for the Poisson bracket between Poisson forms. The resulting Lie algebra shows an interesting and nontrivial structure. It has a trivial part, namely the space of closed Poisson forms, which constitutes an ideal that one might wish to divide out: this ideal is abelian but not central. It commutes with the most interesting and useful part, namely the subalgebra of homogeneous Poisson forms of scaling degree 1, which by means of eq. (151), specialized to the case $s = 1$, correspond to the exact Hamiltonian multivector fields, and in such a way that the Poisson bracket on this subalgebra corresponds to the
Schouten bracket for exact Hamiltonian multivector fields (up to signs). The nontrivial mixing occurs through the spaces of homogeneous Poisson forms of scaling degree 0 and of scaling degree > 1: they close under the operation of taking the Poisson bracket with a homogeneous Poisson forms of scaling degree 1 but not under the operation of taking mutual Poisson brackets, since these contain contributions lying in the ideal of closed Poisson forms.

An important aspect of our results is that they confirm, once again, the apparently unavoidable appearance of strong constraints on the dependence of Hamiltonian multivector fields and Hamiltonian forms on the multimomentum variables and the energy variable in extended multiphase space, expressed through the “antisymmetric polynomial” structure of their coefficient functions. This strongly suggests that there should be some product structure complementing the Poisson bracket operation. So far, such a structure seems to exist only for a very restricted class of Poisson forms, namely the horizontal forms studied by Kanatchikov [9]. Also, one might wonder whether the structural properties derived here still hold in the multisymplectic formulation of higher order field theories [6].

Finally, a central question that remains is how the various proposals of Poisson brackets in the multisymplectic formalism that can be found in the literature, including the one proposed in Refs [1] and [2], relates to the Peierls-DeWitt bracket that comes from the functional approach based on the concept of covariant phase space. Briefly, covariant phase space is defined as the space $S$ of solutions of the equations of motion and, formally viewed as an infinite-dimensional manifold, carries a naturally defined symplectic form $\Omega$ [12–14]. A systematic general investigation of the Peierls-DeWitt bracket in the multisymplectic framework, including a proof of the fact that it is precisely the canonical Poisson bracket for functionals on $S$ derived from the symplectic form $\Omega$ on $S$, has been carried out recently [10, 11]. In order to establish the desired relation, we must restrict this bracket to a certain class of functionals, namely functionals $F$ obtained by using fields to pull Hamiltonian forms or Poisson forms $f$ on extended multiphase space back to space-time and then integrate over submanifolds $\Sigma$ of the corresponding dimension. Explicitly, using the notation of Ref. [11], we have

\begin{equation}
F[\phi] = \int_{\Sigma} (\mathcal{F}\mathcal{L} o(\varphi, \partial \varphi))^{*} f
\end{equation}

in the Lagrangian framework and

\begin{equation}
F[\phi] = \int_{\Sigma} (\mathcal{H} o(\varphi, \pi))^{*} f
\end{equation}

in the Hamiltonian framework. Now using the classification of Hamiltonian vector fields and Hamiltonian $(n-1)$-forms obtained in this paper, it has been shown recently that the Peierls-DeWitt bracket $\{F, G\}$ between two functionals $F$ and $G$ derived from Hamiltonian $(n-1)$-forms $f$ and $g$, respectively, is the functional derived from the
Hamiltonian \((n-1)\)-form \(\{f, g\}\) [15]; details will be published elsewhere. The question of how to extend this result to Poisson forms of other degree is currently under investigation.

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A Appendix

Let \(V\) be a vector bundle over a manifold \(M\) with projection \(\pi\) and let \(i_0 : M \to V\) be its zero section. For any point \(v\) in \(V\), we shall denote the zero vector in its fiber by \(v_0\); thus \(v_0 = (i_0 \circ \pi) v\). Next, let \(\Sigma\) the scaling or Euler vector field on \(V\) and denote its flux by \(F\); thus

\[
\Sigma(v) = v, \quad F_\lambda(v) = e^\lambda v \quad \text{for} \quad \lambda \in \mathbb{R} \text{ and } v \in V.
\]

Then

\[
\lim_{\lambda \to -\infty} F_\lambda(v) = v_0.
\]

Next, consider the tangent bundle \(TV\) of the total space \(V\), together with the vertical bundle which is defined to be the kernel of the tangent map \(T\pi\) to the projection \(\pi\). Given any point \(v \in V\) and any tangent vector \(w \in T_v V\) at this point, we define a new tangent vector \(w_0 \in T_{v_0} V\) at the corresponding zero vector by

\[
w_0 = T_v (i_0 \circ \pi) \cdot w.
\]

Since \(i_0\) is an immersion, \(w_0\) will vanish if and only if \(w\) is vertical. With this tool at hand, we can investigate the properties of the tangent map \(T_v F_\lambda : T_v V \to T_{F_\lambda(v)} V\): the idea is that it should rescale vertical vectors by a factor \(e^\lambda\) but leave horizontal vectors invariant:

- Under the standard identification of the vertical tangent spaces of a vector bundle with the fibers of that vector bundle, the restriction of \(T_v F_\lambda\) to the vertical space at \(v\) is identified with \(F_\lambda\) itself, since this is a fiberwise linear map.

- \(T_v F_\lambda\) satisfies

\[
T_{F_\lambda(v)} \pi \circ T_v F_\lambda = T_v \pi.
\]
This implies that
\[
\lim_{\lambda \to -\infty} T_v F_\lambda \cdot w = w_0 ,
\]
a relation that can be checked most easily by employing an arbitrary local trivialization:
denoting the typical fiber of \( V \) by \( \tilde{V} \) and choosing a trivialization \( V|_U \cong U \times \tilde{V} \) of \( V \) over some open subset \( U \) of \( M \), we have the following correspondences:

\[
\begin{align*}
  v & \leftrightarrow (x, \tilde{v}) \quad , \quad w \leftrightarrow (u, \tilde{w}) \\
  v_0 & \leftrightarrow (x, 0) \quad , \quad w_0 \leftrightarrow (u, 0) \\
  F_\lambda(v) & \leftrightarrow (x, e^\lambda \tilde{v}) \quad , \quad T_v F_\lambda \cdot w \leftrightarrow (u, e^\lambda \tilde{w})
\end{align*}
\]

where \( x \in U, \tilde{v} \in \tilde{V}, u \in T_x M, \tilde{w} \in \tilde{V} \).

Now we are ready to prove the following

**Proposition A.1** Let \( V \) be a vector bundle over a manifold \( M \) with projection \( \pi \) and let \( \Sigma \) be the scaling or Euler vector field on \( V \). A differential form \( \alpha \) on the total space \( V \) will be the pull-back of a differential form \( \alpha_0 \) on the base space \( M \) to \( V \) via \( \pi \) if and only if it is scale invariant:

\[
\alpha = \pi^* \alpha_0 \iff L_\Sigma \alpha = 0 .
\]

**Proof.** Assume first that the form \( \alpha \) on \( V \) is the pull-back of a form \( \alpha_0 \) on \( M \); then \( \alpha = \pi^* \alpha_0 \) and hence \( d\alpha = \pi^* d\alpha_0 \). Therefore, \( \alpha \) and \( d\alpha \) are both horizontal. This means that for any vertical vector field \( X \) on \( V \), including \( \Sigma \), we have

\[
i_X \alpha = 0 ,
\]
as well as \( i_X d\alpha = 0 \), so

\[
L_X \alpha = 0 .
\]

Conversely, assume that the form \( \alpha \) on \( V \), of degree \( r \), say, satisfies \( L_\Sigma \alpha = 0 \), so \( \alpha \) is invariant under the flow \( F \) of \( \Sigma \):

\[
\frac{d}{d\lambda} F_\lambda^* \alpha = 0 .
\]

This means that given \( v \in V \) and \( w_1, \ldots, w_r \in T_v V \), the expression

\[
(F_\lambda^* \alpha)_v(w_1, \ldots, w_r) = \alpha_{F_\lambda(v)}(T_v F_\lambda \cdot w_1, \ldots, T_v F_\lambda \cdot w_r)
\]
does not depend on \( \lambda \), so its value

\[
\alpha_v(w_1, \ldots, w_r)
\]
at \( \lambda = 0 \) is equal to its value

\[
\alpha_{v_0}((w_1)_0, \ldots, (w_r)_0)
\]
obtained in the limit \( \lambda \to -\infty \). But this means that \( \alpha \) is equal to \( \pi^* \alpha_0 \) where \( \alpha_0 \) is defined as \( \alpha_0 = i_0^* \alpha \). \( \square \)
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