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Published in:
Astronomy & Astrophysics

DOI:
10.1051/0004-6361/202038351

Publication date:
2020

Document version
Publisher's PDF, also known as Version of record

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Citation for published version (APA):
Muller, O., Marleau, F. R., Duc, P.-A., Habas, R., Fensch, J., Emsellem, E., Poulain, M., Lim, S., Agnello, A., Durrell, P., Paudel, S., Sanchez-Janssen, R., & van der Burg, R. F. J. (2020). Spectroscopic study of MATLAS-2019 with MUSE: An ultra-diffuse galaxy with an excess of old globular clusters. Astronomy & Astrophysics, 640, [A106]. https://doi.org/10.1051/0004-6361/202038351
Spectroscopic study of MATLAS-2019 with MUSE: An ultra-diffuse galaxy with an excess of old globular clusters

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Received 5 May 2020 / Accepted 8 June 2020

The MATLAS deep imaging survey has uncovered a plethora of dwarf galaxies in the low density environment it has mapped. A fraction of them are unusually extended and have low surface brightness. Among these so-called ultra-diffuse galaxies, a few seem to host an excess of globular clusters (GCs). With the integral field unit spectrograph MUSE we have observed one of these galaxies – MATLAS J15052031+0148447 (MATLAS-2019) – located toward the nearby group NGC 5846 and measured its systemic velocity, age, and metallicity, and that of its GC candidates. For the stellar body of MATLAS-2019 we derive a metallicity of $-1.33_{-0.10}^{+0.09}$ dex and an age of $11.2_{-1.8}^{+1.8}$ Gyr. For some of the individual GCs and the stacked GC population, we derive consistent ages and metallicities. From the 11 confirmed GCs and using a Markov Chain Monte Carlo approach we derived a dynamical mass-to-light ratio of $4.2_{-1.5}^{+1.4}$ $M_\odot/L_\odot$. This is at the lower end of the luminosity-mass scaling relation defined by the Local Group dwarf galaxies. Furthermore, we could not confirm or reject the possibility of a rotational component in the GC system. If present, this would further modify the inferred mass.

Follow-up observations of the GC population and of the stellar body of the galaxy are needed to assess whether this galaxy lacks dark matter, as was suggested for the pair of dwarf galaxies in the field of NGC 1052, or if this is a misinterpretation arising from systematic uncertainties of the method commonly used for these systems and the large uncertainties of the individual GC velocities.

Key words. galaxies: kinematics and dynamics – galaxies: stellar content – galaxies: dwarf

1. Introduction

The Mass Assembly of early Type gaLAXies with their fine Structures (MATLAS) survey is a large observing program designed to study low surface brightness features in the outskirts of nearby massive elliptical galaxies. The survey was conducted using MegaCam at the Canada-France-Hawaii Telescope (CFHT). It reaches surface brightnesses of 28.5–29.0 mag arcsec$^{-2}$ in the g-band while achieving high image quality, thereby enabling the detection of low surface brightness structures together with their globular cluster (GC) population (Duc et al. 2015). It is therefore an excellent data set in which to search for hitherto undetected dwarf galaxies. Habas et al. (2020) identified 2210 dwarf galaxy candidates with MATLAS. Among these, ~4% (Marleau et al., in prep.) fall into the category of ultra-diffuse galaxies (UDGs). These are galaxies that have effective radii larger than 1.5 kpc and a low surface brightness (Sandage & Binggeli 1984; van Dokkum et al. 2015), and appear in both cluster and field environments (van der Burg et al. 2016). Their extreme low baryonic mass density makes them ideal probes for dark matter (Silk 2019; Sales et al. 2020; Prole et al. 2019; Wasserman et al. 2019; Mancera Piña et al. 2019) and alternative models of gravity (Haghi et al. 2019; Bifilek et al. 2019; Islam & Dutta 2019; Moffat & Toth 2019).

Two of the most discussed UDGs (e.g., Hayashi & Inoue 2018; Kroupa et al. 2018; Martin et al. 2018; Ruiz-Lara et al. 2019; Müller et al. 2019a; Nusser 2020; Haslbauer et al. 2019) are the now famous NGC 1052-DF2 (van Dokkum et al. 2018) and NGC 1052-DF4 (van Dokkum et al. 2019). These galaxies appear to have a deficiency of dark matter. This conclusion is based on the velocity dispersion measured from a handful of GCs that these systems host (van Dokkum et al. 2018, 2019) and, in the case of NGC 1052-DF2, the stellar body of the galaxy (Emsellem et al. 2019; Daniell et al. 2019). If this interpretation holds, it would be puzzling that an old dwarf galaxy with an age estimate of 8.9±1.5 Gyr (Fensch et al. 2019) hosts no massive dark matter halo. In the standard framework of

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cosmology a primordial dwarf galaxy should always be surrounded by a vast dark matter halo unless it is of tidal origin (Kroupa 2012). This interpretation of a lack of dark matter has been debated, questioning the real distances of the galaxies (Trujillo et al. 2019; Monelli & Trujillo 2019; Danielli et al. 2020), the effects of tidal interactions (Ogiya 2018; Müller et al. 2019b), or rotation (Emsellem et al. 2019; Lewis et al. 2020). The two UDGs, NGC 1052-DF2 and NGC 1052-DF4, as the names suggest, reside in the same field. Therefore it is imperative to study such objects in different environments.

We have compiled a list of UDGs (Marleau et al., in prep.) from the MATLAS dwarf galaxy catalog (Habas et al. 2020) and identified a number of systems with a high number of GC candidates associated with them, which are similar to NGC 1052-DF2 and NGC 1052-DF4. The GC catalog has been compiled from the MATLAS multiband images, using color and size-proxy criteria to exclude foreground stars and background galaxies (see details in Lim et al. 2017). The candidate with the highest number of putative GCs – MATLAS J15052031+0148447, referred to here as MATLAS-2019 as this is the 2019th object from Eigenthaler & Zeilinger (2010) and presented as a histogram in the bottom right corner.

Fig. 1. Environment of the NGC 5846 group of galaxies. The large diamonds correspond to giant galaxies and the dots to dwarf galaxies, further disected by their apparent magnitudes. MATLAS-2019 is indicated with the red star, the remaining UDG candidates are marked as green stars. The colors correspond to the velocities. The MATLAS survey field is indicated as a shaded region. Velocities not taken from MATLAS-2019 are taken from Eigenthaler & Zeilinger (2010) and presented as a histogram in the bottom right corner.

For the UDG candidate MATLAS-2019 we requested 12 observation blocks (OBs) with the Multi-unit spectroscopic explorer (MUSE) mounted at the Very Large Telescope at Cerro Paranal, of which 3 were taken in Period 103 (PI: Francine Marleau) under program 0103.B-0635. The data were reduced via the MUSE pipeline (Weilbacher et al. 2020) wrapped within the pymusepipe python package pymusepipe\(^1\) (Emsellem et al. 2019), which was previously used to reduce MUSE data taken for the UDG NGC 1052-DF2. This pipeline takes all raw data available in the European Southern Observatory science archive and produces a combined and calibrated (i.e., bias and flat-field

\(^1\) https://github.com/emsellem/pymusepipe
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Table 1. Characterization of the UDG MATLAS-2019.

| RA            | Dec             | Assumed distance | RV | EV | SD             |
|---------------|-----------------|------------------|----|----|----------------|
| 15:05:20.2    | +01:48:46       | 26.3 Mpc         | 17.09 ± 0.01 mag | −15.0 mag | 25.08 mag arcsec^{-2} |
| r_{eff,26.3Mpc} | 2187.6 ± 25 pc  | −1.33^{−0.01}_{+0.01} dex | 9.4±3.4 km s^{-1} | 8.59 × 10^5 L_⊙ | 2.0±0.1 M_⊙/L_⊙ |
| Age           | 11.2±0.8 Gyr    | −3.4 M_⊙/L_⊙     | 4.2^{+0.9}_{−3.4} M_⊙/L_⊙ | 3.8^{+7.9}_{−3.1} M_⊙/L_⊙ |

corrected, astrometrically calibrated, wavelength calibrated, and flux calibrated) data cube. The sky background was kept in the derived stacked data cube, and only then removed via the usage of Zurich Atmosphere Purge (ZAP) packages (Soto et al. 2016), as was done for NGC 1052-DF2 (Emsellem et al. 2019). The total integration time on target was 7783 s or 2.16 h.

The extraction of the systemic velocity was done employing penalized pixel fitting (pPXF, Cappellari & Emsellem 2004; Cappellari 2017) and follows the same procedure as we were done for NGC 1052-DF2 (Emsellem et al. 2019). The total integration time on target was 7783 s or 2.16 h.

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The spectra from the SSP library were convolved with the line-spread function as described in Guérou et al. (2017) (see also the appendix of Emsellem et al. 2019). A variance spectrum was measured on the masked data cube, and added to pPXF. For the galaxy we measure a velocity of 2156.4±5.6 km s^{-1}. Because only 3 out of the 12 requested OBs were taken, the S/N is too low to apply a binning scheme for an estimation of the stellar velocity dispersion, as originally intended. To test whether we could boost the signal, we weighted the pixels according to the Sérsic profile of the galaxy with the optimal extraction algorithm (Horne 1986) of MUSE Python Data Analysis Framework (MPDAF, Bacon et al. 2016), giving more weight to the pixels near the center and less to the pixels in the outskirts, where fewer photons arrive. However, this led to a minimal change in the velocity estimation, due to the fact that the stellar profile is considerably flat – one of the key properties of UDGs.

The uncertainties of the velocities are derived via a wild bootstrap approach, such as we have taken in Emsellem et al. (2019). Namely, at each wavelength we randomized the sign of the residual and added it to the best fit spectrum. We repeated this 1000 times. The 1σ standard deviation of the resulting velocity distribution then gives the error.

To search for globular clusters in the MUSE data cube, we again ran Source Extractor on the 2D image to find all point sources and applied pPXF with circular apertures on top of the objects. To boost the signal, we weighted the signal with a Gaussian with kernel width equals to the measured image quality (~4.5 px or 1.1 arcsec). Point sources were rejected if the velocity was ±100 km s^{-1} away from the galactic velocity. This range was selected to avoid missing any potential GCs with large uncertainties, but still being larger than the typical velocity dispersion of ~20 to 30 km s^{-1} for such low surface brightness dwarf galaxies. Each remaining spectrum was then examined and a final GC catalog was produced. The S/N ratio per pixel is measured in a region between 6600 and 6800 Å. It is calculated as the mean fraction between the flux and the square root of the variance. The variance itself was rescaled, being multiplied by the Chi^2 value estimated from the best pPXF fit, multiplied by a more direct account of the local noise. In total we find 11 GCs (see Fig. 2). Ten out of the 11 GCs were in the GC candidate list based on the MATLAS g' images. From this MATLAS GC list, two candidates have been uncovered as stars and another two are too faint for spectroscopy in MUSE. However, if we stack together these two candidates we get a reasonable spectrum from which we can derive a velocity (2184.0 ± 12.8 km s^{-1}), which is consistent with the velocity of the UDG. This indicates that these are also likely to be GCs of MATLAS-2019, so we consider them as GC candidates. In Table 2 and Fig. 3 we present the line-of-sight velocities for the galaxy, the GCs, and the stacked MATLAS GC candidates.

3. Globular cluster system of MATLAS-2019

In this section we discuss the properties of the GC system. This includes the distribution of the GCs, their brightness, age, and metallicity estimates.

3.1. General properties of the GC system

The UDG MATLAS-2019 has a rich population of GCs. The GCs appear to be isotropically distributed, with no preferential alignment. The mean separation to the center of the galaxy is 8.0 arcsec, which corresponds to 1.0 kpc at the putative distance of 26.3 Mpc. The most distant GC is at 19.6 arcsec within the MUSE field of view, meaning a physical distance of 2.5 kpc, which roughly coincides with the effective radius of the galaxy. Half the GCs are within 6.0 arcsec (0.8 kpc). Interestingly, all the bright GCs are concentrated in the central region of the galaxy (see Fig. 2), with the brightest one, GC6, being located only 1.6 arcsec (0.2 kpc) away from the photometric galaxy center. The luminosity and putative distance of GC6 is M_V = −9.6 mag, making it compatible with being both a nuclear star cluster (NSC) and a GC (see, e.g., Fig. 8 in Fahrion et al. 2020a). Its
Additionally, we stacked the spectra of all the GC members of SSP models. The estimations are provided in Table 2. For some of the GCs we were able to estimate a metallicity.

3.2. Age and metallicity

For some of the GCs we were able to estimate a metallicity and age. We derived these properties from the weights of the SSP models. The estimations are provided in Table 2. Additionally, we stacked the spectra of all the GC members of MATLAS-2019. In doing so we reach $S/N = 19\, \text{px}^{-1}$, which yields a more robust estimation of the mean metallicity and age of the GCs. For the stacked GC population, we

| Source | RA [hh:mm:ss] | Dec [dd:mm:ss] | $m_V$ [mag] | $S/N$ [pix$^{-1}$] | $v_{\text{obs}}$ [km s$^{-1}$] | Age [Gyr] | [Fe/H] | $M_V/L_V$ |
|--------|--------------|----------------|-------------|-------------------|-----------------|----------|--------|-----------|
| UDG    | 15:05:19.185 | +01:48:41.33   | 24.2        | 12.4              | 2156.4 ± 5.6    | 11.2$^{+1.8}_{-0.8}$ | -1.33$^{+0.19}_{-0.01}$ | 2.0$^{+0.3}_{-0.1}$ |
| GC1    | 15:05:19.530 | +01:48:44.61   | 23.6        | 3.3               | 2162.3 ± 23.5   | [7.2, 13.2] | -1.26$^{+0.12}_{-0.03}$ | [1.6, 2.6] |
| GC2    | 15:05:20.042 | +01:48:39.78   | 23.5        | 4.5               | 2138.2 ± 23.3   | [6.0, 13.7] | -2.06$^{+0.35}_{-0.24}$ | [1.2, 2.1] |
| GC3    | 15:05:20.122 | +01:48:38.20   | 23.6        | 5.9               | 2130.2 ± 13.3   | 9.6$^{+3.9}_{-0.7}$ | -1.37$^{+0.24}_{-0.28}$ | 1.7$^{+0.6}_{-0.1}$ |
| GC4    | 15:05:20.141 | +01:48:44.61   | 22.9        | 5.5               | 2133.6 ± 17.2   | 9.1$^{+4.9}_{-0.2}$ | -1.29$^{+0.20}_{-0.34}$ | 1.8$^{+0.7}_{-0.1}$ |
| GC5    | 15:05:20.288 | +01:48:46.61   | 22.5        | 11.1              | 2147.0 ± 7.8    | 10.6$^{+13}_{-14}$ | -1.32$^{+0.17}_{-0.08}$ | 1.9$^{+0.3}_{-0.1}$ |
| GC6    | 15:05:20.440 | +01:48:49.26   | 23.5        | 13.2              | 2147.2 ± 5.0    | 8.0$^{+3.4}_{-0.3}$ | -1.26$^{+0.07}_{-0.09}$ | 1.6$^{+0.4}_{-0.1}$ |
| GC7    | 15:05:20.534 | +01:48:45.23   | 24.4        | 7.2               | 2157.2 ± 13.8   | 10.3$^{+19}_{-17}$ | -1.76$^{+0.27}_{-0.37}$ | 1.7$^{+0.3}_{-0.5}$ |
| GC8    | 15:05:20.559 | +01:48:41.80   | 23.4        | 4.5               | 2163.2 ± 17.7   | 11.5$^{+13.6}_{-3.1}$ | -1.56$^{+0.15}_{-0.30}$ | 1.9$^{+0.2}_{-0.4}$ |
| GC9    | 15:05:20.593 | +01:48:48.87   | 24.3        | 8.2               | 2179.1 ± 13.7   | 11.3$^{+13.6}_{-1.5}$ | -1.56$^{+0.15}_{-0.30}$ | 1.9$^{+0.2}_{-0.4}$ |
| GC10   | 15:05:20.775 | +01:49:02.96   | 23.3        | 3.7               | 2177.9 ± 16.1   | 11.3$^{+3.6}_{-1.5}$ | -1.56$^{+0.15}_{-0.30}$ | 1.9$^{+0.2}_{-0.4}$ |
| GC11   | 15:05:19.570 | +01:48:36.95   | 24.5        | 5.3               | 2134.2 ± 18.9   | [5.3, 12.2] | [-2.0, -1.4] | [1.1, 2.0] |
| Cand1  | 15:05:20.856 | +01:48:53.59   | 23.8        | 19.4              | 2150.8 ± 4.1    | 9.1$^{+3.0}_{-0.8}$ | -1.44$^{+0.10}_{-0.07}$ | 1.6$^{+0.3}_{-0.1}$ |
| Cand1-2|              |                | 4.6         | 2184.0 ± 12.8     | 9.5$^{+3.1}_{-3.5}$ | -0.96$^{+0.53}_{-0.15}$ | 1.9$^{+0.7}_{-0.6}$ |
derive a metallicity of \([\mathrm{Fe/H}] = -1.44^{+0.10}_{-0.07}\) dex and an age of 9.1^{+3.0}_{-0.8}\) Gyr. For the stellar body of MATLAS-2019 we derive \([\mathrm{Fe/H}] = -1.33^{+0.19}_{-0.01}\) dex and an age of 11.2^{+1.8}_{-0.9}\) Gyr. These values are consistent with each other, a finding similar to the one in NGC 1052-DF2 (Fensch et al. 2019). The uncertainties are derived from the 16% and 84% intervals from the previously described bootstrap. Where the bootstrap did not converge, we present the interval within which 68% of the estimates fall (again presented in Table 2). From the weighted metallicities and ages we calculated the mass-to-light ratio of the stellar population. The uncertainties are again estimated from the bootstrap. In Fig. 5 we present how these numbers relate to the luminosity-metallicity relation of nearby dwarf galaxies and the metallicity-age relation for Milky Way GCs and the GCs of the massive galaxies of the Fornax cluster, as well as the properties derived for NGC 1052-DF2 (Fensch et al. 2019). The metallicity of MATLAS-2019 is consistent with other nearby dwarf galaxies and follows the luminosity-metallicity scaling relation. The GCs of MATLAS-2019 are also consistent with the metallicity-age relation as measured with MUSE in the Fornax 3D project (Fahrion et al. 2020b,c). In this respect, there is nothing out of the ordinary in these systems.

4. Dark matter content in MATLAS-2019

From the velocities of the GCs we can derive a velocity dispersion and ultimately the dynamical mass of the system. In the following we infer the dynamical mass of MATLAS-2019 employing Bayesian considerations. We first assume a completely pressure-supported system and later generalize it for an additional rotational component.

4.1. Dynamical mass estimation of a pressure-supported system

Assuming that the globular clusters trace the underlying gravitational potential, are in dynamical equilibrium, and are pressure-supported dominated, their velocity dispersion can be used to estimate the total mass of the system. For this we need to estimate the free parameters, namely the intrinsic velocity dispersion \(\sigma_{\text{in}}\) and the systemic velocity \(v_{\text{GCs}}\), of all GCs combined.

The log likelihood function is given by

\[
\log L = \sum_{i=1}^{N} \log \left( \frac{1}{\sqrt{2\pi \sigma_{\text{obs}}}} \right) - \frac{(v_{\text{obs},i} - v_{\text{GCs}})^2}{2\sigma_{\text{obs}}^2},
\]

with

\[
\sigma_{\text{obs}}^2 = \sigma_{\text{in}}^2 + \delta_i^2 v_i^2,
\]

where \(N\) is the number of GCs, \(v_{\text{obs},i}\) is the observed radial velocity, \(v_{\text{GCs}}\) is the systemic velocity, and \(\sigma_{\text{obs}}\) is the observed velocity dispersion.
where \( N \) is the number of tracers, \( \sigma_{\text{obs}} \) is the observed velocity dispersion, which is a combination of the true velocity dispersion \( \sigma_{\text{int}} \) and the observational uncertainties \( \delta_v \). \( v_{\text{obs}} \) is the observed velocity, and \( v_{\text{GC}} \) is the systemic velocity of all GCs combined. The two variables \( v_{\text{GC}} \) and \( \sigma_{\text{int}} \) are the parameters in which we are interested. We impose a non-informative prior (Agnello & Bruun, in prep.), which suppresses velocity dispersions that are too small\(^2\). We use a Markov chain Monte Carlo (MCMC) approach to sample the two unknown parameters. For this purpose, we use the python package emcee with 100 walkers, 100 iterations of burn-ins, and finally 10,000 steps along the chains. The resulting posterior distribution is shown in Fig. 6. The errors are given by the 68\% (i.e., 1\( \sigma \) in frequentist statistics) bounds. We derive an intrinsic velocity dispersion of the GC and candidate system of \( \sigma_{\text{int}} = 9.4^{+5.3}_{-3.4} \) km s\(^{-1}\) and a systemic velocity of \( v_{\text{GCs}} = 2150.9^{+3.3}_{-2.9} \) km s\(^{-1}\), respectively.

Next, we estimate the dynamical mass-to-light ratio \( M_{\text{dyn}}/L_V \) within one de-projected half-light radius \( r_{1/2} \). The dynamical mass \( M_{\text{dyn}} \) within \( r_{1/2} \) is given by (Wolf et al. 2010)

\[
M_{\text{dyn}}(r_{1/2}) = \frac{4}{3} \frac{r_{1/2} \sigma_{\text{int}}^2 G}{r_{1/2}},
\]

where \( G \) is the gravitational constant and \( r_{1/2} \) is the measured effective radius (coming from a 2D Sérsic fit). The luminosity \( L_V \) is derived from the \( g-r \) magnitude using (Lupton 2005) and a \((g-r)\) color of 0.59 mag. With an absolute \( V \)-band magnitude of \(-15.0\) (adopting a distance of 26.3 Mpc) we get \( L_V = 8.59 \times 10^9 L_\odot \). The effective radius at a putative distance of 26.3 Mpc is \( r_{1/2} = 2187.6 \) pc. Putting all this together yields a dynamical mass within one de-projected half-light radius of \( M_{\text{dyn}} = 18.0^{+17.1}_{-14.8} \times 10^7 M_\odot \) and finally a dynamical mass-to-light ratio of \( M_{\text{dyn}}/L_V = 4.2^{+8.6}_{-3.6} M_\odot/L_\odot \). For the uncertainties in the distance, we adopted a conservative lower limit of 22 Mpc and an upper limit of 32 Mpc, corresponding to the respectively lower and higher estimated distances of the massive galaxies in the field. If we instead use the more recent mass estimator by Errani et al. (2018), which updated the estimator provided by Amorisco & Evans (2011),

\[
M_{\text{dyn}}(1.8 r_{1/2}) = \frac{6.5 r_{1/2} \sigma_{\text{int}}^2}{G},
\]

de we derive a dynamical mass-to-light ratio within 1.8 \( r_{1/2} \) (encompassing 87\% of the total luminosity) of \( 3.8^{+7.8}_{-4.1} M_\odot/L_\odot \). The two estimators yield consistent values, which shows that the choice of the mass estimator does not change the result.

We consider how this compares to other galaxies. We use the Spitzer Photometry and Accurate Rotation Curves (SPARC) database provided by Lelli et al. (2016, 2017), which gives a measure of the observed acceleration \( g_{\text{obs}} \), in terms of the acceleration expected by the baryons \( g_{\text{bar}} \). While this radial acceleration relation (RAR) is strictly speaking purely observational, the deviation from unity gives information about the dark matter content of the galaxy. If \( g_{\text{obs}} \) is equal to \( g_{\text{bar}} \), the acceleration the galaxy experiences due to gravity can be solely explained by the baryonic content of the galaxy – no need for dark matter. On the other hand, if \( g_{\text{obs}} \) is much larger than \( g_{\text{bar}} \) we need to invoke dark matter, or alternative gravity models (e.g., modified Newtonian dynamics MOND, Milgrom 1983; Famaey & McGaugh 2012) to explain the observations.

From Lelli et al. (2017) we can calculate

\[
g_{\text{obs}} = \frac{3 \sigma_{\text{int}}^2}{r_{1/2}^2}, \quad g_{\text{bar}} = \frac{\Gamma_V G L_V}{2 r_{1/2}^2},
\]

The parameter \( \Gamma_V \) is the stellar mass-to-light ratio \((M_V/L_V)\). In Fig. 7 left panel, we show the RAR, together with our estimation for MATLAS-2019, the dwarf galaxies of the Local Group, and other UDGs. The observed acceleration of the UDG is close to unity, meaning that its baryonic content is able to explain the measured velocity dispersion alone. With a \( M_{\text{dyn}}/L_V \) ratio of only 4, this is expected. Taking this at face value, the UDG appears to be lacking dark matter. However, the uncertainties are large. The upper \( 1\sigma \) error bound yields a \( M_{\text{dyn}}/L_V \) ratio of 14, which would be consistent with the RAR and the dwarf galaxies of the Local Group. At \( 2\sigma \) the \( M_{\text{dyn}}/L_V \) is 25, fully consistent with the Local Group dwarfs. This becomes even more evident when the \( M_{\text{dyn}}/L_V \) ratio as a function of the luminosity is compared to Local Group dwarf galaxies. This is shown in Fig. 7, right panel. The UDG, together with NGC 1052-DF2 and NGC 1052-DF4, follows the scaling relation as defined by Local Group dwarf galaxies and is comparable to the dwarf irregulars (dIrr) IC 1613 and NGC 6822 (Kirby et al. 2014).

4.2. Dynamical mass estimation with rotation

The previous assessment of the dynamical mass was based on the assumption that the system is fully pressure supported. An additional rotational component can change the results. In the case...
of NGC 1052-DF2, a rotational signal for both the stellar body (Emsellem et al. 2019) and the GC system (Lewis et al. 2020) was found, while the former could not be confirmed by independent measurements (Danieli et al. 2019). Let us now consider an additional rotational component for the GC system. For this, we follow the description by Lewis et al. (2020). The log likelihood function is given by

$$\log L = \frac{1}{\sqrt{2\pi} \sigma_{\text{obs}}} \left( \frac{v_{\text{obs}} - (v_{\text{rot}}(\theta) + v_{\text{GC}})}{2 \sigma_{\text{obs}}} \right)^2, \quad (7)$$

with

$$\sigma_{\text{obs}}^2 = \sigma_{\text{int}}^2 + \beta_{\text{rot}}^2, \quad (8)$$
$$v_{\text{rot}}(\theta) = A \sin(\theta - \phi), \quad (9)$$

where $v_{\text{rot}}$ describes the additional rotational component, $\phi$ the rotation axis, $\theta$ the angle between the line from the center of the galaxy to the GC and the east direction, measured counterclockwise, and $A$ is the amplitude of the rotation velocity. We sample over the unknown parameters using a MCMC approach, as before. We use flat priors as it was done in Lewis et al. (2020). The results are shown in Fig. 8. We find a best separation of $\phi = 110^{+52}_{-16}$ deg and $A = 9.8^{+6.3}_{-1.8}$ km s$^{-1}$. For the latter, the posterior distribution is mainly flat within 0 to 10 km s$^{-1}$. This posterior distribution and the best-parameter estimation with its errors can neither confirm nor rule out a rotational component of the GC system. In the following, we take the best fit at face value and assume that there is indeed a rotational component for the sake of testing its impact on the mass estimation. In Fig. 9 we present the position-velocity diagram for the best-fit rotation axis. For that, we have calculated the 2D separations of each GC to the rotation axis given by the angle $\theta$ and fixed at the center of the galaxy.

Following the description of Lewis et al. (2020) the dynamical mass is estimated with

$$M_{\text{dyn}}(r_{1/2}) = \left( \frac{v_{\text{rot}}^2}{\sin(i)} + \sigma_{\text{int}}^2 \right)^{1/2} \frac{r_{1/2}}{G}, \quad (10)$$

Here, an additional problem becomes evident – we do not know the inclination $i$ of the rotational system (if there is any). As the ellipticity of the UDG is close to zero, we can start by assuming that the inclination is 90°, in other words, we see the rotation system perfectly edge-on. In this case, the $M_{\text{dyn}}/L_V$ ratio is $2.6^{+3.6}_{-1.8}$. However, in this case, the roundness of the object would be puzzling, as low surface brightness dwarf galaxies tend to be best described as oblate-triaxial spheroids (Sánchez-Janssen et al. 2019). Is the shape of the dwarf galaxy a good indicator for the inclination of its GC system? For NGC 1052-DF2 this is not the case. There, the rotation axis of the GCs was found to be roughly perpendicular to the major axis of the galaxy (Lewis et al. 2020). If the GC system inherited a dynamic memory from an accretion event, no a priori alignment can be expected. Therefore, we cannot constrain the inclination with the ellipticity of MATLAS-2019. Smaller inclinations will increase the $M_{\text{dyn}}/L_V$ ratio to $3.0^{+4.4}_{-2.2} (60°)$, $3.9^{+6.0}_{-2.8} (45°)$, and $6.2^{+11.4}_{-3.0} (30°)$. These values are again ambiguous, with the lower values indicating a lack of dark matter, and the larger values being consistent with dark-matter-dominated dwarf galaxies. To conclude, the data at hand cannot firmly constrain the existence of a rotational component.
**4.3. MATLAS-2019 in modified Newtonian dynamics**

When the initial claim for the dark-matter-deficient UDG NGC 1052-DF2 came up (van Dokkum et al. 2018), this was used as a falsification for alternative gravity models like MOND (Milgrom 1983, see also Famaey & McGaugh 2012). In MOND-like theories, the baryons mimic the behavior of dark matter, so an absence of a phantom dark matter halo\(^3\) would be inconsistent with the theory. However, this assessment ignores a peculiar phenomenon in MOND, the so-called external field effect (EFE, see, e.g., Haghi et al. 2019 for a recent discussion), which can arise when a galaxy resides in an external gravitational potential. This EFE can lower the velocity dispersion of the system, making it appearing Newtonian, that is, dark matter free. For NGC 1052-DF2 it was shown that the EFE induced by NGC 1052 can mitigate the tension (Kroupa et al. 2018; Famaey et al. 2018).

We considered MATLAS-2019 in terms of MOND. In an isolated case, the expected MONDian velocity dispersion is calculated from the baryonic mass of the galaxy. Transforming its \(V\)-band magnitude with a \(M/L\) ratio of 2.0 gives \(\sigma_{\text{MOND}} = 17.9 \ \text{km s}^{-1}\), which is marginally above the one sigma upper limit of our measured velocity dispersion, but well within two sigma. The EFE calculation for the UDG cannot be conducted so easily, because the influence of all the nearby giant galaxies has to be taken into account. We refer to a future work but note that the EFE will push down the expected MONDian value of the velocity dispersion. One caveat though: if MATLAS-2019 is completely dominated by the EFE, it should be quickly dissolving, as the galaxy has no phantom dark matter protecting it against tidal forces (Milgrom 2015, see also a similar discussion by Bílek et al. 2019 for the UDG DF-44 in the Coma cluster).
5. Discussion and conclusions

With MUSE we have followed up the dwarf galaxy MATLAS-J15052031+0148447 (MATLAS-2019), which has a rich globular cluster system and is located in the NGC 5846 group of galaxies. The object turned out to have also been detected in the VEGAS survey by Forbes et al. (2019). We obtained spectra of the stellar body and its GC candidates. We have confirmed 11 to be real GCs associated to the galaxy and two additional as likely candidates. The mean velocity of the GC system derived from our MCMC approach is consistent with the velocity of the galaxy \((v_{\text{gal}} = \pm 2156.4 \pm 5.6 \text{ km s}^{-1})\). The velocity of the galaxy itself is consistent with the velocity distribution of the NGC 5846 group of galaxies \((v_{\text{group}} = 1828.4 \pm 295.2 \text{ km s}^{-1})\). If the dwarf galaxy is at the distance of the NGC 5846 group, its brightest GC would be rather intriguing, having a similar luminosity to \(\Omega Cen\).

For some of the GCs we were able to derive a metallicity and age. Additionally, the stacked GC spectrum allowed us to derive a metallicity and age estimate for the GC population with and without \([\text{Fe/H}]= -1.44^{+0.10}_{-0.07}\) dex and an age of \(9.1^{+3.0}_{-0.8}\) Gyr, compatible with the one derived from the stellar body of MATLAS-2019. Assuming \([\text{Fe/H}]= -1.33^{+0.19}_{-0.08}\) dex and an age of \(11.2^{+2.8}_{-1.8}\) Gyr. This shows that both the galaxy and the GCs are old and metal poor. Comparing the metallicities of the stellar body and the GCs to nearby dwarf galaxies and GCs, respectively, we find consistent results.

From the individual GC velocities, we have derived a velocity dispersion, yielding \(M_{\text{dyn}}/L_V\) within one de-projected half-light radius of \(4.2^{+3.2}_{-2.9} M_\odot / L_\odot\). Using another mass estimator within 1.8 times the effective radius, we derive a \(M_{\text{dyn}}/L_V\) ratio of \(3.9^{+2.7}_{-1.2} M_\odot / L_\odot\), which is consistent with the previous estimate. Within the uncertainties, these values are consistent with the dark-matter-dominated dwarf galaxies in the Local Group, as well as the two apparently dark-matter-deficient galaxies in the NGC 1052 group. In contrast to NGC 1052-DF2 and NGC 1052-DF4, the association of MATLAS-2019, which belongs to a rich, X-ray luminous group of galaxies, should be much less ambiguous.

For the analysis of the dynamical mass, we used the distance of 26.3 Mpc from the central body of the galaxy group, namely NGC 5846 \((\text{VNGC}5846 = 1712 \text{ km s}^{-1})\). There is a notably high difference in velocity between the two bodies. This could either mean that the UDG is on its infall into the group, or even farther behind. The latter would lower the \(M_{\text{dyn}}/L_V\) ratio. In velocity space, the closest galaxies are NGC 5869 \((\text{VNGC}5869 = 2065 \text{ km s}^{-1})\) and NGC 5813 \((\text{VNGC}5813 = 1956 \text{ km s}^{-1})\). These galaxies have distance estimates of 24.9 Mpc and 31.3 Mpc, respectively. While the former would change the derived \(M_{\text{dyn}}/L_V\) ratio to \(4.4 M_\odot / L_\odot\), the latter would lower it to \(3.5 M_\odot / L_\odot\). The conclusions remain the same.

For NGC 1052-DF2, indications of a rotational signal of the GC system were found. We asked whether this could be the case for MATLAS-2019 as well. Here, an analysis including the angles of the GCs for a rotational component of the GC system remained inconclusive. For the moment, rotation cannot be ruled out. Assuming that a rotation of the GC system is present, the unknown inclination angle of the rotational component of MATLAS-2019 makes it difficult to confine the \(M_{\text{dyn}}/L_V\) ratio. An edge-on system would lead to a dark-matter-deficient galaxy, a larger inclination would instead make it consistent with dark-matter-dominated dwarf galaxies. For the future, the confirmation of a rotational component could shed new light on the formation scenario of these systems. It is possible that the GCs were accreted and retained their dynamical memory, which could further lead to misinterpretation of the mass content of these galaxies.

The GC population is not always a good indicator of the mass of a system, as was shown for the Fornax dwarf spheroidal (Mateo et al. 1991). For Fornax, the GC system can yield a total mass of the object free of dark matter, while the stellar body suggests a \(M/L\) ratio of 10 and more (Walker et al. 2009), leaving ample space for dark matter. Laporte et al. (2019) further showed that even when solely considering the GC system of Fornax, the observation can be interpreted as “overmassive”, “just right”, or “lacking dark matter”, due to large uncertainties from observations, mass estimators, scatter in the mass-concentration relation, and tidal stripping. A sample of just a few GCs yields order-of-magnitude systematic uncertainties in the velocity dispersion and in the mass (Laporte et al. 2019), which will not be reflected in the given numbers presented here. Another caveat that has to be taken into account is that the system is not necessarily stationary-Copernican, to have reliable, “reasonable” estimates, introducing even more biases. Even by ignoring these effects, the \(1\sigma\) upper limit of the mass of the galaxy, the derived \(M_{\text{dyn}}/L_V\) ratio is consistent with other dwarf galaxies from the Local Group, therefore allowing for a fair share of dark matter. In other words, while the measured velocity dispersion of MATLAS-2019 taken at face value could be interpreted as a lack of dark matter, the uncertainties – both systematic and observational – do not rule out one or the other option. Therefore, measuring the stellar internal kinematics of the UDG is ultimately needed to understand whether there is a lack of dark matter in this galaxy.

Acknowledgements. We thank the referee for the constructive report, which helped to clarify and improve the manuscript. The corner plots were created with the open source python package corner (Foreman-Mackey 2016) The authors thank Katja Fahrion for providing the table of GCs used in Fig. 5. O.M. thanks Nicolas Martin for interesting discussions concerning the dynamical mass estimation. O.M. is grateful to the Swiss National Science Foundation for financial support. S.P. acknowledges support from the New Researcher Program (No. 2019R1C10100600) through the National Research Foundation of Korea. A.A. was supported by a grant from VILLUM FONDEN (project number 16599). This project is partially funded by the Danish council for independent research under the project “Fundamentals of Dark Matter Structures”, DFF–6108-00470.

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