Analysis of stability for stochastic delay integro-differential equations

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Abstract
In this paper, we concern stability of numerical methods applied to stochastic delay integro-differential equations. For linear stochastic delay integro-differential equations, it is shown that the mean-square stability is derived by the split-step backward Euler method without any restriction on step-size, while the Euler–Maruyama method could reproduce the mean-square stability under a step-size constraint. We also confirm the mean-square stability of the split-step backward Euler method for nonlinear stochastic delay integro-differential equations. The numerical experiments further verify the theoretical results.

Keywords: Stochastic delay integro-differential equations; Euler–Maruyama method; Split-step backward Euler method; Mean-square stability

1 Introduction
Stochastic delay integro-differential equations, as the mathematical model, widely apply in biology, physics, economics and finance [1, 2]. Because of the stochastic delay integro-differential equations themselves, it is not easy to obtain an explicit solution for these kinds of equations, so it is necessary to research the numerical methods for numerical solution of stochastic delay integro-differentialequations [3, 4]. Stability is the basic and important property of numerical methods for stochastic systems.

There are few results on the numerical methods to stochastic delay integro-differential equations. Ding et al. [5] dealt with the stability of the semi-implicit Euler method for linear stochastic delay integro-differential equations. Rathinasamy and Balachandran [6] proved mean-square stability of the Milstein method for linear stochastic delay integro-differential equations with Markovian switching under suitable conditions on the integral term. The condition under which the split-step backward Euler method was mean-square stable has been obtained by Tan and Wang [7, 8]. Rathinasamy and Balachandran [9] also analyzed $T$-stability of the split-step-θ-methods for linear stochastic delay integro-differential equations. Wu [10] investigated the mean-square stability for stochastic delay integro-differential equations by the strong balanced methods and the weak balanced methods with sufficiently small step-size. Numerical researches for stochastic delay integro-differential equations are not perfect enough. Therefore, it is extremely essential to develop the stability of the numerical methods to stochastic equations.

The paper is organized as follows. In Sect. 2 we will introduce related symbols and definitions. Some suitable conditions will be given to guarantee stability of the Euler–Maruyama
method for stochastic delay integro-differential equations in Sect. 3. In Sect. 4, the split-step backward Euler method will be used to prove general mean-square stability of numerical solutions. In Sect. 5, we will discuss stability of nonlinear stochastic delay integro-differential equations. Furthermore, numerical experiments are provided in Sect. 6.

2 Preliminaries

Throughout this paper, unless otherwise specified, let \((\Omega, \mathcal{F}, P)\) be a complete probability space with a filtration \((\mathcal{F}_t)_{t \geq 0}\), which satisfies the usual conditions (i.e., it is increasing and right continuous while \(\mathcal{F}_0\) contains all \(P\)-null sets). Let \(|\cdot|\) be the Euclidean norm, \(W(t)\) is Wiener process defined on the probability space, which be \(\mathcal{F}_t\)-adapted and independent of \(\mathcal{F}_0\). Let \(\tau > 0\) and \(C([-\tau, 0]; \mathbb{R})\) denote the family of all continuous \(\mathbb{R}\)-valued functions on \([-\tau, 0], \mathcal{C}([-\tau, 0]; \mathbb{R}^d)\) denote the family of all continuous functions \(\xi\) from \([-\tau, 0]\) to \(\mathbb{R}^d\). \(\|\xi\|\) is defined by \(\|\xi\| = \sup_{-\tau \leq t \leq 0} |\xi(t)|\). We assume \(\xi(t), t \in [-\tau, 0]\) is the initial function, which is \(\mathcal{F}_0\)-measurable and right continuous, \(E\|\xi\|^2 < \infty\). Let \(C^b_{\mathcal{F}_0}([-\tau, 0]; \mathbb{R})\) be the family of all \(\mathcal{F}_0\)-measurable bounded \(C([-\tau, 0]; \mathbb{R})\)-valued random variables \(\xi = (\xi(\theta) : -\tau \leq \theta \leq 0)\).

As a matter of convenience, we first consider the following form of linear stochastic delay integro-differential equations:

\[
\begin{align*}
\begin{cases}
\ dx(t) = [\alpha x(t) + \beta x(t - \tau) + \gamma \int_{t-\tau}^t x(s)ds] \ dt \\
\ h(t) = \xi(t), & t \in [-\tau, 0],
\end{cases}
\end{align*}
\]

(1)

where \(\xi(t)\) is initial function, and \(\xi(t) \in C([-\tau, 0]; \mathbb{R}), \alpha, \beta, \gamma, \lambda, \mu, \eta \in \mathbb{R}\), \(W(t)\) is a standard one-dimensional Wiener process and \(\tau\) is the delay term.

Under the above assumptions, Eq. (1) has a unique solution \(x(t)\). In order to analyze mean-square stability of two numerical methods, we introduce the following lemma [11].

Lemma 2.1 If

\[
\alpha + |\beta| + |\gamma| |\tau + \frac{1}{2} (|\lambda| + |\mu| + |\eta| |\tau) < 0
\]

(2)

the solution of Eq. (1) is said to be mean-square stable, that is,

\[
\lim_{t \to \infty} E|x(t)|^2 = 0.
\]

(3)

3 Mean-square stability of the Euler–Maruyama method

Now, the Euler–Maruyama method applied to Eq. (1) one gets

\[
X_{n+1} = X_n + (\alpha X_n + \beta X_{n-m} + \gamma \bar{X}_n)h + (\lambda X_n + \mu X_{n-m} + \eta \bar{X}_n) \Delta W_n,
\]

(4)

where \(\bar{X} = X_0, X_n\) is an approximation to the analytical solution \(x(t_n)\), which is \(\mathcal{F}_{t_n}\)-measurable, \(h > 0\) is the given step-size, which satisfies \(h = \frac{1}{m}\) for a positive integer \(m\), \(t_n = nh, n = -m, \ldots, 0\), and we get \(X_n = \xi(t_n)\) when \(t_n \leq 0\), \(\Delta W_n = W(t_{n+1}) - W(t_n)\) are independent \(N(0, h)\) distributed stochastic variables. \(\bar{X}^n\) approaches the integral term, this
paper will choose a composite trapezoidal rule as the tool of the disperse integral to solve this case. We have

\[ \bar{X}_n = \frac{h}{2} X_{n-m} + h \sum_{k=1}^{m-1} X_{n-k} + \frac{h}{2} X_n. \]

**Definition 3.1** If there exists a \( h_0 > 0 \), for every step-size \( h \in (0, h_0] \) with \( h = \frac{\tau}{m} \), such that the numerical approximation \( \{X_n\} \) produced by the Euler–Maruyama method satisfies

\[ \lim_{n \to \infty} E|X_n|^2 = 0 \]  

then the numerical method applied to Eq. (1) is said to be mean-square stable.

**Theorem 3.1** Under the condition (2), let \( h_0 = \max\{h_1, h_2\} \), for step-size \( h \in (0, h_0] \), we have

\[ \lim_{n \to \infty} E|X_n|^2 = 0 \]

then the Euler–Maruyama method applied to Eq. (1) is mean-square stable, where

\[ h_1 = -\frac{2\alpha + 2|\beta| + 2|\gamma|\tau + (|\lambda| + |\mu| + |\eta|\tau)^2}{(|\alpha| + |\beta| + |\gamma|\tau)^2}, \]

\[ h_2 = \min \left\{ \frac{1}{\alpha}, -\frac{2\alpha + 2|\beta| + 2|\gamma|\tau + (|\lambda| + |\mu| + |\eta|\tau)^2}{(\alpha + |\beta| + |\gamma|\tau)^2} \right\}. \]

**Proof** From Eq. (4), we obtain

\[ X_{n+1} = (1 + \alpha h + \eta \Delta W_n)X_n + (\beta h + \mu \Delta W_n)X_{n-m} + (\gamma h + \eta \Delta W_n)nX_n. \]

(6)

Squaring both sides of Eq. (6), we have

\[ X_{n+1}^2 = (1 + \alpha h + \eta \Delta W_n)^2 X_n^2 + (\beta h + \mu \Delta W_n)^2 X_{n-m}^2 + (\gamma h + \eta \Delta W_n)nX_nX_n \]

\[ + \eta \Delta W_n \Delta W_n + 2(1 + \alpha h + \eta \Delta W_n)X_nX_{n-m} + 2(1 + \alpha h + \eta \Delta W_n)(\beta h + \mu \Delta W_n)X_nX_{n-m} \]

\[ + 2(\beta h + \mu \Delta W_n)(\gamma h + \eta \Delta W_n)nX_nX_{n-m}. \]
It follows from $2ab \leq |ab|(x^2 + y^2)$, where $a, b \in \mathbb{R}$, $\tau = mh$, that

$$2X_{n-m}\tilde{X}_n = 2X_{n-m}\left(\frac{h}{2}X_{n-m} + h \sum_{k=1}^{m-1} X_{n-k} + \frac{h}{2}X_n\right)$$

$$= hX_{n-m}^2 + 2hX_{n-m} \sum_{k=1}^{m-1} X_{n-k} + hX_nX_{n-m}$$

$$\leq hX_{n-m}^2 + h(m - 1)X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}(X_n^2 + X_{n-m}^2)$$

$$\leq \tau X_{n-m}^2 + \frac{h}{2}X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2.$$  \hspace{1cm} (7)

According to the inequality $(a_1 + a_2 + \cdots + a_n)^2 \leq n(a_1^2 + a_2^2 + \cdots + a_n^2)$,

$$\tilde{X}_n^2 = h^2 \left(\frac{1}{2}X_{n-m} + \sum_{k=1}^{m-1} X_{n-k} + \frac{1}{2}X_n\right)^2$$

$$\leq h^2 \left(\frac{1}{4}X_{n-m}^2 + (m - 1) \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{1}{4}X_n^2 + \frac{1}{2} \left[(m - 1)X_{n-m}^2 + \sum_{k=1}^{m-1} X_{n-k}^2\right]\right)$$

$$\leq \tau \left(\frac{h}{2}X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2\right).$$ \hspace{1cm} (8)

In a similar way

$$2X_{n-m}\tilde{X}_n = \tau X_{n-m}^2 + \frac{h}{2}X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2.$$ \hspace{1cm} (9)

We note that $E(\Delta W_n) = 0$, $E[(\Delta W_n)^2] = h$, and $X_m, X_{m-1}, \ldots, X_{n-m}$ are $\mathcal{F}_n$-measurable. Substituting (7), (8), (9) into the above equation and taking expectations,

$$EX_{n+1}^2 \leq (1 + \alpha^2\tau^2 + \lambda^2\tau + 2\alpha h)EX_n^2 + (\beta^2\tau^2 + \mu^2\tau)EX_{n-m}^2 + \gamma(\tau^2 + \gamma^2\tau)\tau E\left(\frac{h}{2}X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2\right)$$

$$+ \left|\left[\alpha(1 + \alpha h)\beta h\right] + |\lambda\mu|\tau\right|EX_n^2 + EX_{n-m}^2$$

$$+ \left|\left[(1 + \alpha h)\gamma h\right] + |\lambda\eta|\tau\right|E\left(\tau X_n^2 + \frac{h}{2}X_n^2\right)$$

$$+ h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2\right) + (|\beta\gamma|\tau^2 + |\mu\eta|\tau)$$

$$\times E\left(\tau X_{n-m}^2 + \frac{h}{2}X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2\right).$$
Let $Y_n = E|X_n^2|$, we have

$$Y_{n+1} \leq PY_n + QY_{n-m} + R \max_{n-m \leq i \leq n} (Y_i),$$

where

$$P = 1 + \alpha^2 h^2 + \lambda^2 h + 2\alpha h + |(1 + \alpha h)\beta h| + |\lambda \mu| h + |\lambda \eta| \tau h$$
$$+ |(1 + \alpha h)\gamma \tau h|,$$

$$Q = \beta^2 h^2 + \mu^2 h + |(1 + \alpha h)\beta h| + |\lambda \mu| h + |\beta \gamma| \tau h^2 + |\mu \eta| \tau h,$$

$$R = (\gamma^2 h^2 + \eta^2 h)\tau^2 + |(1 + \alpha h)\gamma \tau h| + |\lambda \eta| \tau h + |\beta \gamma| \tau h^2 + |\mu \eta| \tau h.$$ 

So

$$Y_{n+1} \leq (P + Q + R) \max \left\{ Y_n, Y_{n-m}, \max_{n-m \leq i \leq n} (Y_i) \right\}.$$ 

It is clear that $Y_n \to 0 \ (n \to \infty)$ if $P + Q + R < 1$, namely

$$1 + \alpha^2 h^2 + \lambda^2 h + 2\alpha h + 2|(1 + \alpha h)\beta h| + 2|\lambda \mu| h + 2|\lambda \eta| \tau h + \beta^2 h^2 + \mu^2 h$$
$$+ 2|(1 + \alpha h)\gamma \tau h| + 2|\beta \gamma| \tau h^2 + 2|\mu \eta| \tau h + \gamma^2 h^2 + \eta^2 h < 1.$$ 

Hence let

$$h_1 = -\frac{2\alpha + 2|\beta| + 2|\gamma| \tau + (|\lambda| + |\mu| + |\eta| \tau)^2}{(|\alpha| + |\beta| + |\gamma| \tau)^2},$$
$$h_2 = \min \left\{ -\frac{1}{\alpha}, -\frac{2\alpha + 2|\beta| + 2|\gamma| \tau + (|\lambda| + |\mu| + |\eta| \tau)^2}{(\alpha + |\beta| + |\gamma| \tau)^2} \right\}.$$ 

By the condition (2), we know that $h_1 > 0$, $h_2 > 0$. If $h_0 \in (0, h_1)$, we have

$$(\alpha^2 + 2|\alpha \beta| + 2|\alpha \gamma| \tau + \beta^2 + 2|\beta \gamma| \tau + \gamma^2 \tau^2) h^2$$
$$+ (2\alpha + 2|\beta| + 2|\gamma| \tau + (|\lambda| + |\mu| + |\eta| \tau)^2) h < 0.$$ 

On the other side, we address the case $1 + \alpha h > 0$. If $h_0 \in (0, h_2)$, we get

$$(\alpha^2 + 2|\alpha \beta| + 2|\alpha \gamma| \tau + \beta^2 + 2|\beta \gamma| \tau + \gamma^2 \tau^2) h^2$$
$$+ (2\alpha + 2|\beta| + 2|\gamma| \tau + (|\lambda| + |\mu| + |\eta| \tau)^2) h < 0.$$ 

Let $h_0 = \max\{h_1, h_2\}$; when $h \in (0, h_0)$, $P + Q + R < 1$ always holds, then

$$\lim_{n \to \infty} Y_n = \lim_{n \to \infty} E|X_n|^2 = 0$$

then the Euler–Maruyama method applied to Eq. (1) is mean-square stable. The theorem is completed. □
4 General mean-square stability of the split-step backward Euler method

Using the split-step backward Euler method applied to Eq. (1), we construct the numerical scheme as follows:

\[
\begin{align*}
X_n^* &= X_n + (\alpha X_n^* + \beta X_{n-m} + \gamma \tilde{X}_n)h, \\
X_{n+1} &= X_n^* + (\lambda X_n^* + \mu X_{n-m} + \eta \tilde{X}_n)\Delta W_n,
\end{align*}
\]

(10)

the relevant definitions are in Sect. 3, if \(1 - \alpha h \neq 0\), we can get the sequences \(\{X_n^*\} n \geq 0\) and \(\{X_n, n \geq 1\}\) via (10), when given \(X_n = \xi(nh)\) for \(n \in \{-m, -m + 1, \ldots, 0\}\).

**Definition 4.1** For every step-size \(h = \frac{1}{m}\), if any application of the split-step backward Euler method to Eq. (1) generates a numerical approximation \(\{X_n\}\) that satisfies

\[
\lim_{n \to \infty} E[X_n] = 0
\]

(11)

then the numerical method applied to Eq. (1) is said to be general mean-square stable.

**Theorem 4.1** Under the condition (2), assume \(1 - \alpha h \neq 0\), the split-step backward Euler method applied to Eq. (1) is generally mean-square stable.

**Proof** Assume \(1 - \alpha h \neq 0\) and implying \(\alpha < 0\); we can see from (10) that

\[
X_{n+1} = \frac{1 + \lambda \Delta W_n}{1 - \alpha h}(X_n + \beta hX_{n-m} + \gamma h\tilde{X}_n) + (\mu X_{n-m} + \eta \tilde{X}_n)\Delta W_n.
\]

(12)

Squaring both sides of Eq. (12),

\[
X_{n+1}^2 = \left(\frac{1 + \lambda \Delta W_n}{1 - \alpha h}\right)^2 \left(X_n^2 + \beta^2 h^2 X_{n-m}^2 + \gamma^2 h^2 \tilde{X}_n^2 + 2\beta \gamma hX_nX_{n-m} + 2\gamma hX_n\tilde{X}_n\right)
\]

\[
+ 2\beta \gamma hX_{n-m}X_n\tilde{X}_n + (\mu^2 X_{n-m}^2 + \eta^2 \tilde{X}_n^2 + 2\mu \eta X_{n-m}X_n\tilde{X}_n)\Delta W_n^2
\]

\[
+ 2\frac{1 + \lambda \Delta W_n}{1 - \alpha h}(X_n + \beta hX_{n-m} + \gamma h\tilde{X}_n)(\mu X_{n-m} + \eta \tilde{X}_n)\Delta W_n.
\]

According to \(2abxy \leq |ab|(x^2 + y^2)\) and \(E(\Delta W_n) = 0\), \(E(\Delta W_n^2) = h\), substituting (7), (8), (9) into the above equation and taking expectations

\[
EX_{n+1}^2 \leq \frac{1 + \lambda^2 h}{(1 - \alpha h)^2} \left[EX_n^2 + \beta^2 h^2 EX_{n-m}^2 + \gamma^2 h^2 \tau E\left(\frac{h}{2} X_{n-m}^2\right)\right]
\]

\[
+ h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2} X_n^2\right] + |\beta| h(2EX_n^2 + EX_{n-m}^2)
\]

\[
+ |\gamma| hE\left(\tau X_n + \frac{h}{2} X_{n-m} + h \sum_{k=1}^{m-1} X_{n-k} + \frac{h}{2} X_n^2\right)
\]

\[
+ |\beta \gamma| h^2 E\left(\tau X_{n-m} + \frac{h}{2} X_{n-m} + h \sum_{k=1}^{m-1} X_{n-k} + \frac{h}{2} X_n^2\right)
\]

\[
+ \mu^2 hEX_{n-m}^2 + \eta^2 \tau h E\left(\frac{h}{2} X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k} + \frac{h}{2} X_n^2\right)
\]

+ \mu^2 hEX_{n-m}^2 + \eta^2 \tau h E\left(\frac{h}{2} X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k} + \frac{h}{2} X_n^2\right)
\[EX_{n+1} \leq PEX_n + QEX_{n-m} + R \max_{n-m \leq i \leq n} E(X_i^2),\]

where

\[P = \frac{1 + \lambda^2 h}{(1 - \alpha h)^2} (1 + |\beta| h + |\gamma| h \tau) + \frac{|\lambda \eta| h \tau}{1 - \alpha h} + \frac{|\lambda \mu| h}{1 - \alpha h},\]

\[Q = \frac{1 + \lambda^2 h}{(1 - \alpha h)^2} (\beta^2 h^2 + |\beta| h + |\beta \gamma| \tau h^2) + \mu^2 h + |\mu \eta| \tau h + \frac{|\lambda \mu| h}{1 - \alpha h} + \frac{|\lambda \eta| h \tau^2}{1 - \alpha h} + \frac{|\beta \lambda \mu| h^2}{1 - \alpha h},\]

\[R = \frac{1 + \lambda^2 h}{(1 - \alpha h)^2} (|\gamma|^2 h^2 \tau^2 + |\gamma| \tau h + |\beta \gamma| \tau h^2) + \eta^2 \tau^2 h + |\mu \eta| \tau h + \frac{|\lambda \eta| \tau h}{1 - \alpha h} + \frac{|\beta \lambda \eta| \tau h^2}{1 - \alpha h} + \frac{2|\gamma \lambda \mu| h^2}{1 - \alpha h} \tau^2.\]

Let \(Y_n = E|X_n^2|\), the above inequality turns into

\[Y_{n+1} \leq (P + Q + R) \max \left\{ Y_m, Y_{n-m}, \max_{n-m \leq i \leq n} Y_i \right\}.\]

We conclude that \(Y_n \to 0\) \((n \to \infty)\), if \(P + Q + R < 1\), that is,

\[\frac{1 + \lambda^2 h}{(1 - \alpha h)^2} (1 + |\beta| h + 2|\gamma| h \tau)^2 + \frac{2|\lambda \mu| h}{1 - \alpha h} + \frac{2|\lambda \eta| \tau h}{1 - \alpha h} + \frac{2|\beta \lambda \mu| h^2}{1 - \alpha h} \tau^2 < 1.\]
Hence, we have
\[
\left[ (\beta |\lambda| + |\gamma \lambda| \tau) - \alpha (|\mu| + |\eta| \tau) \right]^2 h^2 + \left[ (|\beta| + |\gamma| \tau)^2 - \alpha^2 + (2|\lambda| + 2|\mu| + 2|\eta| \tau) \left( (|\beta \lambda| + |\gamma \lambda| \tau - \alpha (|\mu| + |\eta| \tau) \right) \right] \hat{h}
\]
\[+ 2\alpha + 2|\beta| + 2|\gamma| \tau + (|\lambda| + |\mu| + |\eta| \tau)^2 < 0. \]

Let
\[ F(h) = Ah^2 + Bh + 2\alpha + 2|\beta| + 2|\gamma| \tau + (|\lambda| + |\mu| + |\eta| \tau)^2, \]
where
\[ A = \left[ (|\beta \lambda| + |\gamma \lambda| \tau) - \alpha (|\mu| + |\eta| \tau) \right]^2, \]
\[ B = (|\beta| + |\gamma| \tau)^2 - \alpha^2 + (2|\lambda| + 2|\mu| + 2|\eta| \tau) \left( (|\beta \lambda| + |\gamma \lambda| \tau - \alpha (|\mu| + |\eta| \tau) \right), \]
\[ \Delta = \left[ (|\beta| + |\gamma| \tau)^2 - \alpha^2 + (2|\lambda| + 2|\mu| + 2|\eta| \tau) \left( (|\beta \lambda| + |\gamma \lambda| \tau - \alpha (|\mu| + |\eta| \tau) \right)^2 \right]^2 
- 4\left( (|\beta \lambda| + |\gamma \lambda| \tau - \alpha (|\mu| + |\eta| \tau) \right)^2 \left[ 2\alpha + 2|\beta| + 2|\gamma| \tau + (|\lambda| + |\mu| + |\eta| \tau)^2 \right]. \]

It is easy to see \( A > 0 \), Because of the nature of a quadratic function, we can see that \( F(h) < 0 \) holds for any \( 0 < h < 1 \), when \( \frac{-B \sqrt{\Delta}}{2A} \geq 1 \), and the split-step backward method Euler is general mean-square stable. This proves the theorem. \( \square \)

5 Mean-square stability of the split-step backward Euler method for nonlinear stochastic systems

In this section, we will discuss the mean-square stability of the split-step backward Euler method for nonlinear stochastic delay integro-differential equations. Considering the following nonlinear stochastic equation:

\[
\begin{align*}
\dot{x}(t) &= f(x(t), x(t - \tau), \int_{-\tau}^{t} x(s) \, ds) \, dt \\
&\quad + g(x(t), x(t - \tau), \int_{-\tau}^{t} x(s) \, ds) \, dW(t), \quad t \geq 0, \\
x(t) &= \xi(t), \quad t \in [-\tau, 0],
\end{align*}
\]

\[ f : \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}^d, \quad g : \mathbb{R}^d \times \mathbb{R}^d \times \mathbb{R}^d \to \mathbb{R}^{d \times m}, \]
\[ \xi(t) \in C([-\tau, 0]; \mathbb{R}^d), \quad W(t) \text{ is an } m\text{-dimensional Wiener process and } \tau \text{ is a delay term. If } f \text{ and } g \text{ are sufficiently smooth and satisfy the Lipschitz condition and the linear growth condition, Eq. (13) has a unique strong solution } x(t), \quad t \in [-\tau, \infty) \text{ and } x(t) \text{ is a measurable, sample-continuous and } F_t \text{ adapted process [12, 13].} \]

The split-step backward Euler method applied to Eq. (13) yields

\[
\begin{align*}
X_n^* &= X_n^* + f(X_n^*, X_{n-m}^*, \tilde{X}_n) h_t, \\
X_{n+1}^* &= X_n^* + g(X_n^*, X_{n-m}^*, \tilde{X}_n) \triangle W_n;
\end{align*}
\]

\( X_n, X_n^*, \tilde{X}_n, h_t, \triangle W_n \) are defined in Sects. 3 and 4.

Lemma 5.1 ([14]) If there exist constant \( a_1, a_2, a_3, b_1, b_2, b_3 \), for all \( x, u, v \in \mathbb{R}^d \), we have

\[
\langle x, f(x, 0, 0) \rangle \leq -a_1 |x|^2, \tag{15}
\]
Through the conditions (15), (16), we have

\[ |f(x, u, v) - f(x, 0, 0)| \leq a_2|u| + a_3|v|, \]
\[ |g(x, u, v)|^2 \leq b_1|x|^2 + b_2|u|^2 + b_3|v|^2. \]

**Theorem 5.1** Suppose that Lemma 5.1 holds and let

\[-a_1 + a_2 + a_3 \tau + \frac{1}{2}(b_1 + b_2 + b_3 \tau^2) < 0.\]

If there exists a \( h_0 > 0 \), for every step-size \( h \in (0, h_0] \), we have

\[ \lim_{n \to \infty} E|X_n|^2 = 0. \]

Then the numerical solution of Eq. (13) is mean-square stable, where

\[ h_0 = -\frac{-2a_1 + 2a_2 + 2a_3 \tau + (b_1 + b_2 + b_3 \tau^2)}{b_1(a_2 + a_3 \tau) + (b_2 + b_3 \tau^2)(2a_1 - a_2 - a_3 \tau)}. \]

**Proof** From the second equation of (14), we obtain

\[ |X_{n+1}|^2 = |X_n|^2 + |g(X_n^*, X_{n-m}, \tilde{X}_n)|^2 \Delta W_n^2 + 2\langle X_n^*, g(X_n^*, X_{n-m}, \tilde{X}_n) \rangle \Delta W_n. \]

Note that \( E(\Delta W_n) = 0, E((\Delta W_n)^2) = h \), and \( X_n, X_{n-m}, \tilde{X} \) are \( \mathcal{F}_n \)-measurable, hence

\[ E[X_n^* g(X_n^*, X_{n-m}, \tilde{X}_n) \Delta W_n] = 0, \]
\[ E[|g(X_n^*, X_{n-m}, \tilde{X}_n)|^2 \Delta W_n^2] = |g(X_n^*, X_{n-m}, \tilde{X}_n)|^2 h. \]

Combining condition (17) and taking expectations on both sides of the above equation,

\[ E|X_{n+1}|^2 \leq E|X_n|^2 + (b_1 E|X_n|^2 + b_2 E|X_{n-m}|^2 + b_3 E|\tilde{X}_n|^2) h \]
\[ \leq (1 + b_1 h) E|X_n|^2 + b_2 h E|X_{n-m}|^2 + b_3 h E|\tilde{X}_n|^2. \]

Next, we should derive the \( E|X_n^*|^2 \) by the first equation of (14),

\[ X_n^* - f(X_n^*, X_{n-m}, \tilde{X}_n) h = X_n. \tag{19} \]

Squaring both sides of Eq. (19), one gets

\[ |X_n^*|^2 \leq |X_n|^2 + 2h \langle X_n^*, f(X_n^*, X_{n-m}, \tilde{X}_n) \rangle. \tag{20} \]

Through the conditions (15), (16), we have

\[ 2\langle X_n^*, f(X_n^*, X_{n-m}, \tilde{X}_n) \rangle \]
\[ = 2\langle X_n^*, f(X_n^*, 0, 0) \rangle + 2\langle X_n^*, (f(X_n^*, X_{n-m}, \tilde{X}_n) - f(X_n^*, 0, 0)) \rangle \]
\[ \leq -2a_1 |X_n|^2 + a_2 (|X_n|^2 + |X_{n-m}|^2) + 2a_3 |\tilde{X}_n|^2. \]
It is easily to see that for $X_n^*\bar{X}_n$ from Sect. 3

$$2X_n^*\bar{X}_n = \tau X_n^* + \frac{h}{2}X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2.$$ 

Substituting these into Eq. (20) and taking expectations

$$E|X_n|^2 \leq E|X_n|^2 - 2a_1h E|X_n^*|^2 + a_2hE(|X_n^*|^2 + |X_{n-m}|^2)$$

$$+ a_3h\left(\tau X_n^* + \frac{h}{2}X_{n-m}^2 + h \sum_{k=1}^{m-1} X_{n-k}^2 + \frac{h}{2}X_n^2\right)$$

$$\leq (-2a_1h + a_3h + a_3h\tau)E|X_n|^2 + E|X_n|^2 + a_2hE|X_{n-m}|^2$$

$$+ a_3h\tau \max_{n-m \leq i \leq n} E|X_i|^2.$$ 

In particular

$$E|X_n|^2 \leq \frac{1}{1 + 2a_1h - a_2h - a_3h\tau} E|X_n|^2 + \frac{a_2h}{1 + 2a_1h - a_2h - a_3h\tau} E|X_{n-m}|^2$$

$$+ \frac{a_3h\tau}{1 + 2a_1h - a_2h - a_3h\tau} \max_{n-m \leq i \leq n} E|X_i|^2.$$ 

Hence

$$E|X_{n+1}|^2 \leq (1 + b_1h) E|X_n|^2 + b_2hE|X_{n-m}|^2 + b_3hE|\bar{X}_n|^2$$

$$\leq \frac{1 + b_1h}{1 + 2a_1h - a_2h - a_3h\tau} E|X_n|^2 + \left(\frac{a_2h(1 + b_1h)}{1 + 2a_1h - a_2h - a_3h\tau} + b_2h\right) E|X_{n-m}|^2$$

$$\times \max_{n-m \leq i \leq n} E|X_i|^2 + \left(\frac{a_3h\tau (1 + b_1h)}{1 + 2a_1h - a_2h - a_3h\tau} + b_3h\tau^2\right) \max_{n-m \leq i \leq n} E|X_i|^2.$$ 

We can write

$$E|X_{n+1}|^2 \leq PE|X_n|^2 + QE|X_{n-m}|^2 + \max_{n-m \leq i \leq n} R E|X_i|^2,$$

where

$$P = \frac{1 + b_1h}{1 + 2a_1h - a_2h - a_3h\tau}, \quad Q = \frac{a_2h(1 + b_1h)}{1 + 2a_1h - a_2h - a_3h\tau} + b_2h,$$

$$R = \frac{a_3h\tau (1 + b_1h)}{1 + 2a_1h - a_2h - a_3h\tau} + b_3h\tau^2.$$ 

So

$$E|X_{n+1}|^2 \leq (P + Q + R) \left\{E|X_n|^2, E|X_{n-m}|^2, \max_{n-m \leq i \leq n} E|X_i|^2\right\}.$$
If \( P + Q + R < 1 \), it is easily to see that \( E|X_n|^2 \rightarrow 0 \) when \( n \rightarrow \infty \). By the condition (18), we have

\[
[b_1(a_2 + a_3\tau) + (b_2 + b_3\tau^2)(2a_1 - a_2 - a_3\tau)]h^2 + (-2a_1 + 2a_2 + 2a_3\tau + (b_1 + b_2 + b_3\tau^2))h < 0.
\]

Namely

\[
a_2h + a_3h\tau + b_1h + a_2b_1h^2 + a_3b_1h^2 + b_3h\tau^2 + b_3\tau^2(2a_1 - a_2 - a_3\tau)h^2
\]

\[
+ b_2h + b_2(2a_1 - a_2 - a_3\tau)h^2 - 2a_1h + a_2h + a_3h\tau < 0.
\]

Therefore, for every step-size \( h \in (0, h_0] \), \( \lim_{n \rightarrow \infty} E|X_n|^2 = 0 \) holds, the split-step backward Euler method for nonlinear stochastic equations is mean-square stable. The proof is complete. \( \square \)

6 Numerical experiments

In this section, we will discuss the example to verify the theoretical results, considering the following testified equation:

\[
\begin{cases}
    dx(t) = [\alpha x(t) + \beta x(t - 1) + \gamma \int_{t-1}^{t} x(s) \, ds] \, dt \\
    + [\lambda x(t) + \mu x(t - 1) + \eta \int_{t-1}^{t} x(s) \, ds] \, dW(t), & t \geq 0,
    \\
    x(t) = \xi(t), & t \in [-1, 0].
\end{cases}
\]

Taking the parameters \( \alpha = -10, \beta = 2, \gamma = 1, \lambda = 0.5, \mu = 0.2, \eta = 0.5 \), the condition (2) is satisfied.

Case 1. We can easily see that \( h_1 = \frac{12.56}{100}, h_2 = \min\{\frac{1}{10}, \frac{12.56}{90}\} \). By Theorem 3.1, \( h_0 = \max\{h_1, h_2\} = \frac{1}{10} \). When the step-size \( h \in (0, \frac{1}{10}] \), the Euler–Maruyama method applied to Eq. (21) is mean-square stable. However, the Euler–Maruyama method is unstable when the step-size \( h = \frac{1}{5} > \frac{1}{10} \), which is shown in Fig. 1(a) and (b).

Case 2. We can know \( A = \left((|\beta\lambda| + |\gamma\lambda|\tau) - \alpha(|\mu| + |\eta|\tau)^2\right) > 0, -\frac{B + \sqrt{\Delta}}{2A} \approx 1.13 > 1 \), and the conditions satisfy Theorem 4.1. Hence for any \( 0 < h < 1 \), the split-step backward method

![Figure 1](image-url)
Euler has general mean-square stability. From Fig. 2, it is easy to confirm general mean-square stability of a numerical solution under the same step-size as Case 1. The results indicate that the split-step backward Euler method achieves superiority over the Euler–Maruyama method in terms of mean-square stability.

**Case 3.** We will address the following nonlinear stochastic delay integro-differential equation:

\[
\begin{cases}
    dx(t) = [-80x(t) + 10x(t - 1) + 10 \int_{t-1}^{t} x(s) \, ds] \, dt \\
    + [0.4x(t) + 0.4x(t - 1) + 4 \int_{t-1}^{t} x(s) \, ds] \, dW(t), & t \geq 0, \\
    x(t) = 1, & t \in [-1, 0].
\end{cases}
\]  

(22)

It is easy to ascertain that Eq. (22) satisfies the conditions of Lemma 5.1. So

\[a_1 = 80, \quad a_2 = 10, \quad a_3 = 10, \quad b_1 = 2, \quad b_2 = 2, \quad b_3 = 20, \quad \tau = 1.\]

Therefore

\[-a_1 + a_2 + a_3 \tau + \frac{1}{2} (b_1 + b_2 + b_3 \tau^2) = -96 < 0. \]  

(23)
We should calculate the step-size $h_0 \approx 0.03$ from Theorem 5.1, the data used in all figures are plotted by 200 trajectories. It is proved that the split-step backward Euler method has mean-square stability when $h = 0.01$, while $h$ dissatisfied $(0, h_0]$, that is, $h = 0.1 > h_0$, the split-step backward Euler method is unstable. This is shown in Fig. 3.

7 Conclusion

In this paper, we investigate the mean-square stability and general mean-square stability of two numerical methods for a class of linear stochastic delay equations. By comparison, we know that the split-step backward Euler method achieves superiority over the Euler–Maruyama method in terms of mean-square stability. The mean-square stability of numerical method for nonlinear stochastic delay integro-differential equations is eventually confirmed by us.

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