PROTON, ELECTRON, AND ION HEATING IN THE FAST SOLAR WIND FROM NONLINEAR COUPLING BETWEEN ALFVÉNIC AND FAST-MODE TURBULENCE

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ABSTRACT

In the parts of the solar corona and solar wind that experience the fewest Coulomb collisions, the component proton, electron, and heavy ion populations are not in thermal equilibrium with one another. Observed differences in temperatures, outflow speeds, and velocity distribution anisotropies are useful constraints on proposed explanations for how the plasma is heated and accelerated. This paper presents new predictions of the rates of collisionless heating for each particle species, in which the energy input is assumed to come from magnetohydrodynamic (MHD) turbulence. We first created an empirical description of the radial evolution of Alfvén, fast-mode, and slow-mode MHD waves. This model provides the total wave power in each mode as a function of distance along an expanding flux tube in the high-speed solar wind. Next, we solved a set of cascade advection–diffusion equations that give the time-steady wavenumber spectra at each distance. An approximate term for nonlinear coupling between the Alfvén and fast-mode fluctuations is included. For reasonable choices of the parameters, our model contains enough energy transfer from the fast mode to the Alfvén mode to excite the high-frequency ion cyclotron resonance. This resonance is efficient at heating protons and other ions in the direction perpendicular to the background magnetic field, and our model predicts heating rates for these species that agree well with both spectroscopic and in situ measurements. Nonetheless, the high-frequency waves comprise only a small part of the total Alfvénic fluctuation spectrum, which remains highly two dimensional as is observed in interplanetary space.

Key words: magnetohydrodynamics (MHD) – plasmas – solar wind – Sun: corona – turbulence – waves

Online-only material: color figures

1. INTRODUCTION

The energy that heats the solar corona and accelerates the solar wind originates in convective motions beneath the Sun’s surface. However, even after many years of investigation, the physical processes that transport a fraction of this energy to the corona and convert it into thermal, magnetic, and kinetic energy are still not understood. In order to construct and test theoretical models, a wide range of measurements of relevant plasma parameters must be available. In the low-density, open-field regions that reach into interplanetary space, the number of plasma parameters that need to be measured is larger because the plasma becomes collisionless and individual particle species (e.g., protons, electrons, and heavy ions) can exhibit divergent properties. Such differences in particle velocity distributions are valuable probes of kinetic processes of heating and acceleration.

The spectroscopic instruments aboard the Solar and Heliospheric Observatory (SOHO)—e.g., the Ultraviolet Coronagraph Spectrometer (UVCS) and Solar Ultraviolet Measurements of Emitted Radiation (SUMER)—have measured several key collisionless plasma properties for a variety of solar wind source regions (Kohl et al. 1995, 1997, 2006; Wilhelm et al. 1995, 1997). These observations augment decades of in situ plasma and field measurements that show similar departures from thermal equilibrium in the collisionless solar wind (e.g., Neugebauer 1982; Marsch 1999, 2006; Kasper et al. 2008). In the high-speed solar wind, both coronal and heliospheric measurements point to the existence of preferential ion heating and acceleration, as well as protons being hotter than electrons. There are also marked departures from Maxwellian velocity distributions for protons and other ions, with the temperature measured in directions perpendicular to the background magnetic field often exceeding the temperature parallel to the field (i.e., $T_\perp > T_\parallel$).

A large number of different processes have been suggested to explain the measured proton and ion properties. Many of these processes are related to the dissipation of magnetohydrodynamic (MHD) waves, and many involve multiple steps of energy conversion between waves, reconnection structures, and other nonlinear plasma features. It was noticed several decades ago that the damping of ion cyclotron resonant Alfvén waves could naturally give rise to many of the observed plasma properties (see reviews by Hollweg & Isenberg 2002; Hollweg 2008). The problem in the solar corona, though, is how these extremely high-frequency ($10^2$–$10^4$ Hz) waves could be generated from pre-existing MHD fluctuations that appear to have much lower frequencies (<0.01 Hz).

One likely source of high-frequency waves and kinetic dissipation is an MHD turbulent cascade. There is ample evidence that turbulence provides substantial heat input to the plasma in interplanetary space (see Coleman 1968; Goldstein et al. 1995; Tu & Marsch 1995; Matthaeus et al. 2003). Furthermore, self-consistent models of turbulence-driven coronal heating and solar wind acceleration have begun to succeed in reproducing a wide range of observations without the need for ad hoc free parameters (e.g., Suzuki & Inutsuka 2006; Cranmer et al. 2007; Rappazzo et al. 2008; Breech et al. 2008; Verdini et al. 2010; Bingert & Peter 2011; van Ballegooijen et al. 2011; Chandran et al. 2011). The general scenario is that convection jostles open magnetic flux tubes that are rooted in the photosphere and produces Alfvén waves that propagate into the corona. These waves undergo partial reflection, and the resulting “colliding wave packets” drive a turbulent cascade which heats the plasma when the eddies reach small enough spatial scales.

It has been known for many years that Alfvénic turbulence in a strong magnetic field produces a cascade to small scales mainly in the two-dimensional plane perpendicular to the field (Montgomery & Turner 1981; Shebalin et al. 1983), and
thus is not likely to produce high-frequency ion cyclotron waves. In other words, MHD turbulence leads to eddies with large perpendicular wavenumbers \( k_\perp \) and not large parallel wavenumbers \( k_\parallel \). Under typical plasma conditions in the corona and inner heliosphere, the linear dissipation of high-\( k_\perp \) Alfvén waves would lead to the preferential parallel heating of electrons (Leamon et al. 1999; Cranmer & van Ballegooijen 2003; Gary & Borovsky 2008). This apparently disagrees with the observational evidence for perpendicular heating of positive ions.

There have been several proposed solutions to the apparent incompatibility between the predictions of MHD turbulence and existing measurements (see also Cranmer 2009a). For example, turbulent fluctuations may be susceptible to various instabilities that cause ion cyclotron waves to grow (Markovskii et al. 2006; Vranjes & Poedts 2008) or they may induce stochastic perpendicular motions in ions if they reach nonlinear magnitudes (Voitenko & Goossens 2004; Wu & Yang 2007; Chandran 2010). Nonetheless, heliospheric measurements have provided several pieces of evidence for the existence of ion cyclotron resonance that gives rise to perpendicular ion heating in the solar wind (e.g., Marsch & Tu 2001b; Bourouaine et al. 2010; He et al. 2011; Smith et al. 2012). The most direct solution to the problem still appears to be for turbulence to transport some fraction of the fluctuation energy to high-\( k_\perp \) cyclotron resonant waves.

The goal of this paper is to investigate the idea proposed by Chandran (2005) for the turbulent generation of ion cyclotron waves. In this scenario, nonlinear couplings between Alfvén waves and other modes such as fast magnetosonic waves produce an enhancement in the high-\( k_\perp \) power-law tail of the Alfvénic fluctuation spectrum. This is made possible by the ability of fast-mode waves to cascade nearly isotropically in wavenumber space. Thus, the gradual nonlinear generation of ion cyclotron waves may provide enough heat to protons and other ions in the corona and inner solar wind (see also Luo & Melrose 2006; Chandran 2008a; Yoon & Fang 2008).

We note that it is not currently possible to produce a rigorous model that contains a fully self-consistent description of MHD wave transport (from the corona to 1 AU), turbulent cascade, mode coupling, and dissipation. In order to make some progress in trying to understand this complex system, we have created models that include a range of simplifying assumptions. One key approximation is that we divide the modeling into two separate components: (1) a large-scale model of the radial dependence of fluctuation energy densities, and (2) a small-scale description of how the “local” fluctuations at each radius evolve in wavenumber space and heat the plasma. Feedbacks from the latter to the former are not included, and we discuss their potential importance in Section 7.

We model the plasma conditions in a representative magnetic flux tube that is rooted in a polar coronal hole and that exhibits a steady-state fast solar wind outflow. In Section 2, we describe a model of background plasma conditions and large-scale wave transport in this flux tube. We take an empirical approach to the solar generation of Alfvén, fast-mode, and slow-mode MHD waves by specifying their amplitudes as free parameters at a lower coronal boundary height of 0.01 solar radii \( R_\odot \) above the photosphere. Section 3 gives a summary of how we model the small-scale transport of cascading wave energy in wavenumber space, and Section 4 describes our treatment of the nonlinear coupling between high-frequency Alfvén and fast-mode waves. In Section 5, we apply quasilinear kinetic theory to predict the net rates of particle heating from the cascading waves. Section 6 presents a selection of results for the collisionless rates of proton, electron, and heavy ion heating. Finally, Section 7 concludes this paper with a brief summary of our major results, a discussion of some of the wider implications of this work, and suggestions for future improvements.

**2. LARGE-SCALE MODEL OF CORONAL HOLE CONDITIONS**

We wish to better understand the global energy budget of MHD waves and turbulence from the lower solar corona out to the interplanetary medium. The work of this section builds on many earlier models of the radial evolution of Alfvén waves in the fast solar wind (e.g., Hollweg 1986; Tu & Marsch 1995; Cranmer & van Ballegooijen 2005; Chandran & Hollweg 2009) and extends it to describe the likely behavior of fast and slow magnetosonic waves as well. Below, we describe an empirical model of how the time-steady plasma properties vary with heliocentric distance (Section 2.1) as well as a large-scale view of the dispersion, propagation, and dissipation of linear waves in such a system (Sections 2.2–2.4).

**2.1. Background Time-steady Plasma**

We model the plasma properties along an open magnetic flux tube rooted in a polar coronal hole. At solar minimum, large unipolar coronal holes are associated with superradially expanding magnetic fields and the acceleration of the high-speed solar wind. Because we only consider a field line along the polar axis of symmetry, we do not need to include the rotational generation of azimuthal magnetic fields (e.g., the Parker spiral effect; see Weber & Davis 1967; Priest & Pneuman 1974) or other geometrical effects of streamer-like flux tube curvature (Li et al. 2011). We do not distinguish between dense polar plumes and the more tenuous interplume regions between them. The radial dependence of plasma parameters is described as a function of either the heliocentric distance \( r \) or the height above the solar photosphere \( \z = r - R_\odot \).

To specify the radial variation of the time-steady magnetic field strength \( B_0 \), mass density \( \rho_0 \), and solar wind outflow speed \( u_0 \), we used the empirical description of Cranmer & van Ballegooijen (2005). This model combined a broad range of observational constraints with a two-dimensional magnetostatic model of the expansion of thin photospheric flux tubes into a supergranular network canopy. At \( r = 1 \) AU in this model, the solar wind outflow speed \( u_0 \) is 781 km s\(^{-1}\) and the proton density \( n_p \) is 2.56 cm\(^{-3}\). This model also specifies the Alfvén speed \( V_A = B_0/(4\pi \rho_0)^{1/2} \), which decreases from a maximum value of 2890 km s\(^{-1}\) at \( r = 1.53 R_\odot \) down to 31 km s\(^{-1}\) at 1 AU. There is a local minimum in \( V_A \) at \( r \approx 1.02 R_\odot \) that is the result of the assumed shape of network “funnels” that expand superradially into the corona.

We also need to know the plasma temperature \( T \) in order to determine the relative importance of gas pressure versus magnetic pressure. Despite observational evidence for different particle species having different temperatures (and departures from Maxwellian velocity distributions), we generally assume that the majority proton–electron magnetofluid is close enough to thermal equilibrium that strong plasma microinstabilities are not excited (e.g., Gary 1991; Marsch 2006). Thus, we specify a one-fluid temperature \( T \) that is assumed to be equal to both the proton temperature \( T_p \) and the electron temperature \( T_e \), and we assume temperature isotropy \( (T_\parallel \approx T_\perp) \) for both species.
chromosphere, but the wave models discussed below start at a lower boundary condition in the low corona; i.e., they specify the wave and turbulence properties only for $z \geq 0.01 \, R_\odot$.

### 2.2. Linear Properties of MHD Waves

In this section we briefly summarize the dispersion properties of linear MHD waves (i.e., phase and group speeds for the Alfvén mode and the fast and slow magnetosonic modes) and the partitioning between fluctuations in kinetic, magnetic, and thermal energy. In Sections 2.3–2.4, we assume that all three types of MHD waves are present, and we vary their relative strengths arbitrarily in order to match the observations.

The phase speed $V_{\text{ph}} = \omega/k$ is defined in terms of the frequency $\omega$ and the magnitude of the wavenumber $k$. In general, $V_{\text{ph}}$ is a function of the Alfvén speed, the sound speed, and the angle $\theta$ between the background field direction and the wavevector $k$. We follow the standard convention of defining a Cartesian coordinate system with the background magnetic field along the $z$-axis and the $k$ vector having components only in the $x$–$z$ plane. Also, for now we express $\omega$ and $k$ in the frame comoving with the solar wind. For Alfvén waves,

$$V_{\text{ph}}^2 = V_A^2 \cos^2 \theta$$

and for the magnetosonic modes,

$$V_{\text{ph}}^2 = \frac{V_A^2 + c_s^2}{2} (1 \mp \Sigma)$$

applies with the upper sign corresponding to the fast mode and the lower sign corresponding to the slow mode, and with

$$\Sigma = \sqrt{1 - \sigma \cos^2 \theta}, \quad \sigma = \frac{4\beta}{(1 + \beta)^2}$$

(see, e.g., Whang 1997; Goedbloed & Poedts 2004). In Section 2.3, we also need to know the component of an MHD wave’s group velocity in the direction parallel to the background magnetic field. We call this quantity $V_{gz}$, and for the Alfvén mode it is identically equal to $V_A$ no matter the value of $\theta$. For the fast and slow modes,

$$V_{gz} = V_{\text{ph}} \cos \theta \left(1 \mp \frac{\sigma \sin^2 \theta}{2\Sigma (1 \pm \Sigma)} \right).$$

MHD waves excite oscillations in the plasma parameters. We denote the root-mean-square (rms) fluctuation amplitudes in velocity as $\delta u_x$, $\delta v_y$, $\delta v_z$, in magnetic field as $B_x$, $B_y$, $B_z$, and in density as $\delta \rho$. We ignore fluctuations in the electric field because their contribution to the total energy density tends to be negligible when $V_A \ll c$. The kinetic, magnetic, and thermal energy densities associated with each type of fluctuation are given as

$$K_i = \frac{\rho_0 \delta u_i^2}{2}, \quad M_i = \frac{B_i^2}{8\pi}, \quad \Theta = \frac{\rho_0^2 \delta \rho^2}{8\pi},$$

respectively, with $i = x, y, z$. For linear Alfvén waves, the total energy density $U_A$ is divided equally between transverse kinetic and magnetic fluctuations along the $y$-axis, with $U_A = K_y + M_y$, and

$$\frac{K_y}{U_A} = \frac{M_y}{U_A} = \frac{1}{2}.$$
For fast- and slow-mode waves, 
\[ U_{F,S} = K_x + K_z + M_x + M_z + \Theta \]  
(9)
and we follow Whang (1997) in expressing the partition fractions as follows:
\[ \frac{K_x}{U_{F,S}} = f_n \sin^2 \theta + f_r \cos^2 \theta, \quad \frac{K_z}{U_{F,S}} = f_n \cos^2 \theta + f_r \sin^2 \theta \]  
(10)
\[ f_n = \frac{V^2_{ph} (V^2_{ph} - V^2_A)}{c^2_s \Delta}, \quad f_r = \frac{V^2_A (V^2_{ph} - c^2_s) \cos^2 \theta}{V^2_{ph} \Delta} \]  
(11)
\[ \frac{M_x}{U_{F,S}} = \frac{(V^2_{ph} - c^2_s) \cos^2 \theta}{\Delta}, \quad \frac{M_z}{U_{F,S}} = \frac{(V^2_{ph} - c^2_s) \sin^2 \theta}{\Delta} \]  
(12)
\[ \frac{\Theta}{U_{F,S}} = \frac{V^2_{ph} - V^2_A}{\Delta}, \]  
(13)
where \( \Delta = 4V^2_{ph} - 2V^2_A - 2c^2_s \). The fast and slow velocity fluctuations \( (K_x + K_z) \) always occupy exactly half of the total energy density, and the combination of magnetic and thermal fluctuations \( (M_x + M_z + \Theta) \) takes up the other half.

The energy partition fractions given above are familiar components of plasma physics and MHD textbooks (e.g., Stix 1992; Goedbloed & Poedts 2004). However, it is difficult to see intuitively how these fractions vary throughout the heliosphere from Equations (10)–(13) alone. Thus, in Figure 2 we provide a schematic illustration of the energy partitioning for fast-mode waves. The three columns indicate the variation from low \( (\beta \ll 1) \) to medium \( (\beta = 1) \) and high \( (\beta \gg 1) \) beta plasmas.

![Figure 2](image.png)

**Figure 2.** Illustration of how fast-mode MHD waves divide their total fluctuation energy into kinetic, magnetic, and thermal energy in various regimes: wavevectors parallel to \( B_0 \) (top row), an isotropic distribution of wavevectors (middle row), wavevectors perpendicular to \( B_0 \) (bottom row); \( \beta \ll 1 \) (left column), \( \beta = 1 \) (middle column), and \( \beta \gg 1 \) (right column). Plotted areas are proportional to the partition fractions given in Equations (10)–(13). Kinetic energy fractions are denoted by \( v_x \) and \( v_z \), magnetic energy fractions are denoted by \( B_z \), and the thermal energy fraction is denoted by “th.”

The three rows show the results for purely parallel propagation (\( \theta = 0 \)), an isotropic distribution of wavenumber vectors (see below), and purely perpendicular propagation (\( \theta = \pi/2 \)). In general, all five terms on the right-hand side of Equation (9) are nonzero, but fractions less than \( \sim 1\% \) are not shown in Figure 2. This diagram can be transformed to show the properties of slow-mode waves by replacing \( \beta \) with \( 1/\beta \) and interchanging the \( x \) and \( z \) subscripts with one another.

### 2.3. Radial Transport Equations

In order to determine how the total energy density of a given wave mode evolves with heliocentric distance, we solve equations of wave action conservation that contain multiple sources of wave damping. There have been many discussions of energy conservation for both pure acoustic waves and incompressible Alfvén waves (e.g., Dewar 1970; Isenberg & Hollweg 1982; Velli 1993; Tu & Marsch 1995; Verdini & Velli 2007; Sokolov et al. 2009), but general derivations that can also be applied to fast- and slow-mode waves (for arbitrary \( \theta \)) are less frequently seen. We utilize the results of Jacques (1977) to write the damped wave action conservation equation as

\[
\frac{\partial}{\partial t} \left( \frac{U_m}{\Omega} \right) + \frac{1}{A_0} \frac{\partial}{\partial r} \left( \frac{u_0 + V_{ph,m}}{A_0} \right) = -\frac{Q_m}{\Omega}, \tag{14}
\]

where the subscript \( m \) can be replaced by \( A, F, \) or \( S \) for the relevant mode, \( A_0 \) is the cross sectional area of the flux tube (i.e., \( A_0 \propto 1/B_0 \)), and \( Q_m \) is the total dissipation rate for the mode in question. The dimensionless factor that takes account of the “stretching” effect of wavelengths in an accelerating reference frame is

\[
\Omega = \left( \frac{V_{ph,m}}{u_0 \cos \theta + V_{ph,m}} \right), \tag{15}
\]

and the angle brackets denote a weighted average over all angles,

\[
\langle f \rangle = \frac{\int d\theta \sin \theta \ f(\theta)}{\int d\theta \sin \theta}, \tag{16}
\]

where here we consider outward propagating waves with \( 0 < \theta < \pi/2 \). The factor of \( \cos \theta \) in Equation (15) comes from the difference between the wave frequency in the Sun’s reference frame \( (\omega_0) \) and the comoving-frame frequency \( (\omega = \omega_0 - k \cdot v_{ph}) \) that appears in the definition of the wave action; see Section III of Jacques (1977).\(^1\) Equation (14) implicitly assumes that \( \omega_0 \) remains constant, but it does not require the specification of any given value of \( \omega_0 \).

Our use of weighted averages over \( \theta \) is derived from the assumption that wave power is distributed isotropically in three-dimensional \( k \)-space. In Appendix A we discuss the motivations for assuming such an isotropic distribution of wavenumber vectors (specifically for the fast-mode waves). For Alfvén waves, this assumption has no impact on solving Equation (14), since the arguments of both angle-bracketed quantities given above are independent of \( \theta \) (see also Hollweg 1974). Thus, one obtains the same result for Alfvén waves whether one assumes a single value of \( \theta \) or the isotropic distribution. For fast- and slow-mode MHD waves, some quantities depend strongly on \( \theta \)

\(^1\) We note that the adopted form of Equations (14)–(15) is only one out of several possible ways of placing and grouping the angle brackets. For the fast and slow modes, there is also potential ambiguity about whether one should use Lagrangian or Eulerian averages for \( u_0 \) in the transport equation. In future work we will explore the consequences of different methods of averaging.
and others do not. For example, slow-mode waves in low-beta plasmas have values of the angle-dependent quantity \(u_0 + V_{\text{gr,m}}\) that are always nearly equal to \(u_0 + c_s\). Figure 1 shows the radial dependence of \((u_0 + V_{\text{gr,F}})\) for the isotropic distribution of fast-mode waves.

We solve Equation (14) for the energy densities of the three MHD modes \((U_A, U_F, U_S)\), and we compute the dispersion and energy partition properties of all three wave types as given in Section 2.2. At this stage, we neglect couplings between multiple modes and other nonlinear effects. This is an approximation that is likely to break down wherever the wave amplitudes become large (e.g., Chin & Wentzel 1972; Wentzel 1974; Goldstein 1978; Lacombe & Mangeney 1980; Poedts et al. 1998; Vasquez & Hollweg 1999; Del Zanna et al. 2001; Gogoberidze et al. 2007). In Section 4, we discuss the likelihood of rapid coupling between the high-wavenumber tails of the Alfvén and fast-mode power spectra. However, we continue to assume that the total energy densities are given by the solution of the individual transport equations.

To specify the dissipation rates \(Q_m\), we include both linear collisional effects (e.g., viscosity, thermal conductivity, and electrical resistivity) for all three modes and nonlinear turbulent damping for the Alfvén and fast mode. Thus, we use

\[
Q_A = \tilde{Q}_A + 2\gamma_A U_A, \quad Q_F = \tilde{Q}_F + 2\gamma_F U_F, \quad Q_S = 2\gamma_S U_S. \tag{17}
\]

We give the amplitude damping rates \(\gamma_m\), which include an approximation for the transition from strongly collisional to collisionless regimes, in Appendix B. The turbulent damping rates \(\tilde{Q}_A\) and \(\tilde{Q}_F\) are described in more detail below. In general, these rates depend on the parallel and perpendicular components of the wavenumber \((k_\parallel, k_\perp)\). For the purposes of evaluating these rates in the global wave transport equations, we assumed that \(k_\perp = 1/\lambda_\perp\) for all three modes, where \(\lambda_\perp\) is the turbulent correlation length described below. For the fast and slow modes, our assumption of an isotropic distribution of wavenumbers is consistent with also assuming \(k_\parallel = k_\perp\). For the Alfvén mode, we found that \(\gamma_A\) never depended on the assumed value of \(k_\perp\) at all, but for completeness we used the critical balance condition (introduced in Appendix A) to specify \(k_\parallel\).

We adopt phenomenological forms for the turbulent dissipation rates that are equivalent to the total energy fluxes that cascade from large to small scales. Thus, \(\tilde{Q}_A\) and \(\tilde{Q}_F\) are constrained only by the properties of fluctuations at the largest scales, and they do not specify the exact kinetic means of dissipation once the energy reaches the smallest scales (but see, however, Section 5). Dimensionally, these are similar to the rate of cascading energy flux derived by von Kármán & Howarth (1938) for isotropic hydrodynamic turbulence. For the nonlinear dissipation of Alfvénic fluctuations, we use

\[
\tilde{Q}_A = \rho_0 \tilde{\alpha}_A \mathcal{E}_{\text{turb}} \frac{Z_\perp^2 Z_+^2 + Z_\perp^2 Z_-^2}{4\lambda_\perp^2}, \tag{18}
\]

(see also Hossain et al. 1995; Zhou & Matthaeus 1990a; Matthaeus et al. 1999; Dmitruk et al. 2001, 2002; Breech et al. 2008). For the fast-mode waves, we use

\[
\tilde{Q}_F = \rho_0 \tilde{\alpha}_F \frac{(v_\|^2 + v_\|^2)^2}{V_A \lambda_\perp}, \tag{19}
\]

where the quantity \((v_\|^2 + v_\|^2)\) collects together the total kinetic energy in fast-mode velocity fluctuations (Chandran 2005; Suzuki et al. 2007). Many of the terms introduced in Equations (18) and (19) are defined throughout the remainder of this subsection.

Equation (18) depends on the magnitudes of the Elsasser (1950) variables, \(Z_\pm = v_\pm \pm B_\parallel/(4\pi\rho_0)^{1/2}\), which specify the power in outward \((Z_-)\) and inward \((Z_+)\) propagating Alfvénic fluctuations. Alfvénic turbulent heating occurs only when there is energy in both modes. In practice, we compute an effective reflection coefficient \(\mathcal{R} = |Z_+|/|Z_-|\) whose magnitude is always less than unity, and thus we express the Elsasser variables in terms of the Alfvénic energy density as

\[
Z_- = \sqrt{\frac{4U_A}{\rho_0(1 + R^2)}}, \quad Z_+ = RZ_- \tag{20}
\]

An accurate solution for \(Z_\pm\) requires the integration of non-WKB equations of Alfvén wave reflection (e.g., Heinemann & Olbert 1980; Verdini & Velli 2007). However, our assumption that the total power \(U_A\) varies in accord with straightforward wave action conservation has been shown to be reasonable, even in environments where \(\mathcal{R}\) is not small such as the chromosphere (van Ballegooijen et al. 2011) and interplanetary space (Zank et al. 1996; Cramer & van Ballegooijen 2005).

We estimate the reflection coefficient \(\mathcal{R}\) using a modification of the low-frequency approximation of Chandran & Hollweg (2009). Specifically, we examine the magnitudes of terms in the transport equation for the inward Elsasser variable,

\[
\frac{\partial Z_-}{\partial r} + (u_0 - V_A) \frac{\partial Z_+}{\partial r} = \left(\frac{Z_+}{4H_D} + \frac{Z_-}{2H_A}\right) - Z_+ Z_- \left(2\lambda_\perp^{-2}\right), \tag{21}
\]

where

\[
H_A = \frac{V_A}{\partial V_A / \partial r}, \quad H_D = \frac{\rho_0}{\partial \rho_0 / \partial r}. \tag{22}
\]

Chandran & Hollweg (2009) neglected both terms on the left-hand side of Equation (21) as well as the term containing \(H_D\), and thus were able to solve for \(Z_+\) straightforwardly. However, in cases of strong reflection, the term containing \(H_D\) may have a magnitude comparable to the other dominant terms. Thus, we keep all three terms on the right-hand side and solve for

\[
\mathcal{R} \approx \frac{2h/|H_A|}{1 + (h/|H_D|)}, \tag{23}
\]

where

\[
h = \frac{\lambda_\perp(u_0 + V_A)}{2Z_-}. \tag{24}
\]

Equation (22) of Chandran & Hollweg (2009) is recovered in the limit of \(h \ll |H_D|\), with \(\mathcal{R} \approx 2h/|H_A|\). In the case of purely linear reflection, Cramer (2010) found that the most accurate local estimates for \(\mathcal{R}\) were obtained when \(H_A\) was replaced with the positive-definite quantity

\[
\tilde{H}_A = V_{\text{Arel}} = \frac{\rho_0}{r} \left(1 - \frac{R_\odot}{r}\right). \tag{25}
\]

We used \(\tilde{H}_A\) instead of \(H_A\) in Equations (23) and (24) to compute \(\mathcal{R}\).

The definitions of the turbulent dissipation rates contain the perpendicular length scale \(\lambda_\perp\), which is an effective transverse correlation length of the turbulence for the largest “outer-scale” eddies. For simplicity we use the same correlation length for
both the Alfvénic and fast-mode fluctuations, but this may not be universally valid (e.g., Suzuki et al. 2007). In previous papers, we assumed that $\lambda_\perp$ scales with the transverse width of the magnetic flux tube; i.e., that $\lambda_\perp \propto R_0^{-1/2}$ (Hollweg 1986). Here we describe the evolution of the transverse correlation length $\lambda_\perp$ with the following transport equation,

$$\frac{\partial \lambda_\perp}{\partial t} = \frac{\lambda_\perp}{2A_0} \frac{\partial A_0}{\partial \tau} + \frac{\beta_\perp}{u_0 + V_\perp} \left( \frac{Z_\perp^2 Z_\perp + Z_\perp^2 Z_\parallel}{Z_\perp^2 + Z_\perp^2 Z_\parallel} \right), \quad (26)$$

where $\beta_\perp$ is a dimensionless constant that is often assumed to be equal to $\tilde{\alpha}_\perp/2$ (e.g., Hossain et al. 1995). The first term on the right-hand side of Equation (26) drives the correlation length to expand linearly with the perpendicular flux-tube cross section (Hollweg 1986). The second term takes account of the nonlinear coupling between the fluctuations and the background plasma properties. It is given in a form suggested initially by Matthaeus et al. (1994) and later generalized to nonzero cross-helicity turbulence by Breech et al. (2008) and others. Our transport equation attempts to bridge together the effects of the two terms. In the lower solar atmosphere (between the photosphere and the chosen lower boundary of 0.01 $R_\odot$ for the wave transport models) we assumed that the first term in Equation (26) is dominant, and thus $\lambda_\perp \propto A_0^{1/2}$.

The turbulent dissipation rates also depend on dimensionless Kolmogorov-type constants $\tilde{\alpha}_\perp$ and $\tilde{\alpha}_t$ that are often assumed to have values of order unity. For example, Hossain et al. (1995) and Breech et al. (2009) found that $\tilde{\alpha}_\perp \approx 0.5$ gives rise to dissipation rates that agree well with both numerical simulations and heliospheric observations. In our case, we used this value as a starting point, but we also varied $\tilde{\alpha}_\perp$ as a free parameter in order to produce the best match to the well-constrained Alfvénic fluctuations. On the other hand, the properties of heliospheric fast-mode turbulence are not known nearly as well as the Alfvén wave turbulence. We thus relied on the independent wave-kinetic simulations of P. Pongkitiwanichakul & B. D. G. Chandran (2012, in preparation) to fix $\tilde{\alpha}_t$ at a value of 2.3.

The Alfvénic cascade rate contains an efficiency factor $\epsilon_\text{turb}$ that attempts to account for regions where the turbulent cascade may not have time to develop before the fluctuations are carried away by the wind. Cranmer et al. (2007) estimated this efficiency factor to scale as

$$\epsilon_\text{turb} = \frac{1}{1 + (t_{\text{eddy}}/t_{\text{ref}})}, \quad (27)$$

where the two timescales above are $t_{\text{eddy}}$, a nonlinear eddy cascade time, and $t_{\text{ref}}$, a timescale for large-scale Alfvén wave reflection (see also Dmitruk & Matthaeus 2003; Oughton et al. 2006). The reflection time is often defined as $t_{\text{ref}} = 1/|V_\perp \cdot \mathbf{\nabla} \lambda_\perp|$, but we solved Equation (25) for $t_{\text{ref}}$ in order to remain consistent with the adopted model for $\mathcal{R}$. The eddy cascade time is given by

$$t_{\text{eddy}} = \frac{\lambda_\perp \sqrt{3\pi}}{(1 + M_\Lambda) v_y}, \quad (28)$$

where the Alfvén Mach number $M_\Lambda = U_\perp / V_\perp$ and the numerical factor of $3\pi$ comes from the normalization of an assumed shape of the turbulence spectrum (see Appendix C of Cranmer & van Ballegooijen 2005). The two limiting cases of $\epsilon_\text{turb} \ll 1$ and $\epsilon_\text{turb} \approx 1$ are roughly equivalent to the “weak” and “strong” cascade phenomenologies discussed in Section 3, but they are not precisely the same.

### 2.4. Representative Solutions

We solved the transport equations given in Section 2.3 by numerically integrating upward from a specified set of lower boundary conditions at $z = 0.01 R_\odot$ and assuming time-steady conditions (i.e., $\partial U_m/\partial t = 0$). We used a logarithmic grid of 500 radial zones in $z$ that expands out to a maximum distance of $860 R_\odot \approx 4$ AU. The transport equations were solved with straightforward first-order Euler steps. The values of the Elsasser variables $Z_\perp$ in each zone were determined by iteration, since Equations (20) and (23) do not give a simple closed-form solution for $Z_+ \pm Z_-$ by themselves.

There are a number of free parameters in this model whose values were not easily obtained from either theoretical calculations or observations. In addition to the lower boundary conditions on the wave energy densities $U_\perp, U_\parallel$, and $U_\perp$, there is also the lower boundary condition on the correlation length $\lambda_\perp$ and the values of the two von Kármán constants $\tilde{\alpha}_\perp$ and $\tilde{\beta}_\perp$. Initially, we varied these six parameters randomly in order to build up a large Monte Carlo ensemble of trial solutions. For each model, we synthesized the radial variation of observable plasma fluctuations such as the rms parallel and perpendicular fluctuation speeds

$$v_\parallel = v_z, \quad v_\perp = (v_x^2 + v_y^2)^{1/2}, \quad (29)$$

the Elsasser variables $Z_\pm$, and the rms fractional density fluctuation amplitude $\delta \rho/\rho_0$. The velocity amplitudes $v_\parallel$ and $v_\perp$ contain contributions from all three MHD wave types. In nearly all models produced here, $v_1$ is dominated by the fast mode and $v_\perp$ is dominated by the Alfvén mode. Observations of these quantities are discussed below.

There was no single set of parameter values that gave rise to perfect agreement between all of the synthesized and observed fluctuation quantities. This is not surprising, since the models are certainly incomplete and there are significant uncertainties in the observations and their interpretation. Also, even though we aimed to restrict ourselves to measurements made in “quiet” high-latitude fast-wind streams, sometimes only low-latitude data were available. Thus, in Table 1 we give a set of optimized parameters that were chosen because they produce adequate agreement with the full set of observed quantities. There were other combinations of the six parameters that gave better agreement on any single observation, but in most of these cases the agreement became worse for other observations. Although the ratio of the two von Kármán constants $\tilde{\alpha}_\perp/\tilde{\beta}_\perp$ was allowed to vary freely, the optimal value was nonetheless found to be close to the commonly used value of 2 (Hossain et al. 1995). The best photospheric value of $\lambda_\perp \approx 120$ km is intermediate between the values of 75 km (Cranmer et al. 2007) and 300 km (Cranmer & van Ballegooijen 2005) found from earlier models.

### Table 1

| Parameter | Value |
|-----------|-------|
| $\tilde{\alpha}_\perp$ | 0.60 |
| $\tilde{\beta}_\perp$ | 0.31 |
| $\tilde{\alpha}_t$ | 2.3 |
| $(U_\perp/\rho_0)^{1/2}$ (at $z = 0.01 R_\odot$) | 29.0 km s$^{-1}$ |
| $(U_\parallel/\rho_0)^{1/2}$ (at $z = 0.01 R_\odot$) | 24.3 km s$^{-1}$ |
| $(U_\perp/\rho_0)^{1/2}$ (at $z = 0.01 R_\odot$) | 9.17 km s$^{-1}$ |
| $\lambda_\perp$ (at photosphere) | 120 km |
velocity fluctuations are more difficult to find, and we show only the on-disk nonthermal line width velocities of Chae et al. (1998) as a way to compare with the modeled values of \(v_1\).

Figure 3(a) shows how the modeled density fluctuation amplitude \(\delta \rho / \rho_0\) is dominated by slow-mode waves in the low corona \((z \lesssim 0.1 R_\odot)\) and by fast-mode waves in the extended corona and solar wind \((z \gtrsim 1 R_\odot)\). The low-corona observations are drawn as an approximate boundary region around the polar plume data given by Ofman et al. (1999). The intermediate data point at \(z = 4 R_\odot\) is an empirical value of \(\delta \rho / \rho_0\) estimated from radio sounding data (Coles & Harmon 1989; Spangler 2002; Harmon & Coles 2005; Chandran et al. 2009), but it is still unclear what fraction of the measured density fluctuations is due to anything even close to ideal MHD waves. At larger distances, we show approximate ranges of density fluctuations as reported by Marsch & Tu (1990) (blue rectangles at \(z = 200 R_\odot\)), Tu & Marsch (1994) (open rectangle), and Issautier et al. (1998) (blue rectangle at \(z > 300 R_\odot\)).

Figure 3(b) compares the result of solving Equation (26) for \(\lambda_\perp\) with the simpler approximation of \(\lambda_\perp \propto B_0^{-1/2}\). The plot also shows fast-wind estimates of \(\lambda_\perp\) between 1.4 and 5 AU from Ulysses (Breech et al. 2008). Figure 3(b) also compares the total heating rate \(Q_\text{tot} = Q_A + Q_E + Q_S\) with observational constraints and with the modeled coronal heating rate from Cranmer et al. (2007). The shaded area between 0.2 and 5 \(R_\odot\) is an envelope surrounding a collection of empirical and theoretical heating curves from Wang (1994), Hansteen & Leer (1995), and Allen et al. (1998). These rates illustrate what is needed to produce the observed coronal heating and solar wind acceleration. The area shown at larger distances \((z > 60 R_\odot)\) is a representation of the range of total \((\text{proton and electron})\) empirical heating rates estimated by Cranmer et al. (2009). Note that the turbulent heating rates \(Q_A\) and \(Q_E\) dominate the total heating rate, with approximately 70% of the total coming from \(Q_A\) and 20% from \(Q_E\). Less than 10% of \(Q_\text{tot}\) comes from the linear damping terms.

There are additional measurement techniques that may be used to further constrain the model parameters, and in future work we will incorporate as many of these as possible. For example, Hollweg et al. (2010) argued that radio measurements of Faraday rotation fluctuations may put unique empirical constraints on the value of \(\lambda_\perp\) in the corona. Also, Sahraoui et al. (2010) used multi-spacecraft data to tease out new details of the wavenumber anisotropy of MHD fluctuations, which may lead to better limits on, e.g., \(v_\parallel / v_\perp\) in the heliosphere. Unfortunately, the vast majority of these measurements have been made for the slow solar wind and not the much less structured fast wind associated with polar coronal holes. Nearer to the Sun, Kitagawa et al. (2010) used dispersive and energy partition properties of thin-tube MHD waves to diagnose the presence and strengths of various modes in active regions. These techniques may be useful in open-field regions as well.

Although we did not include any explicit multi-mode coupling in the transport equations of Section 2.3, there is some feedback between the modes. For example, the correlation length \(\lambda_\perp\) is used in both the Alfvénic and fast-mode turbulent heating expressions, and it is also used to set the wavenumbers \(k_\parallel\) and \(k_\perp\) in the linear dissipation rates \(\gamma_m\). Thus, the choice of the lower boundary condition on \(\lambda_\perp\) can have a significant impact on the radial evolution of all three wave types. Figure 4 illustrates this by varying the photospheric value of \(\lambda_\perp\) between 30 and 300 km and using the other standard parameters from Table 1. The integrated energy densities are plotted in velocity

Figure 3 shows the comparison between synthesized and observed fluctuation quantities for the model parameters given in Table 1. The observational constraints on \(v_\perp\) at \(z \lesssim 0.1 R_\odot\) are a combination of the off-limb nonthermal emission line widths given by Banerjee et al. (1998) and Landi & Cranmer (2009). The observations shown between 0.3 and 1 \(R_\odot\) are from Esser et al. (1999). At larger heights, \(v_\perp\) becomes approximately equal to \(Z_-\), so we truncate the \(v_\perp\) curve in favor of showing the radial dependence of \(Z_-\) more clearly. The latter are compared directly with high-speed wind data from Helios and Ulysses (Bavassano et al. 2000). Observations of longitudinal

![Figure 3](https://example.com/figure3.png)

**Figure 3.** (a) Model values for \(v_\perp\) (black solid curve), \(Z_-\) (black dot-dashed curve), and \(Z_+\) (black dotted curve) compared with measurements (gray boxes). Model values for \(v_\parallel\) (red dashed curve) compared with measurements (light red circles). Velocities are plotted in units of km s\(^{-1}\); see Equation (29). Total density amplitude \(\delta \rho / \rho_0\) (blue solid curve) is shown with its components from fast-mode (blue dot-dashed curve) and slow-mode (blue dotted curve) waves, and compared with observations (light blue regions and rectangles). (b) Modeled total heating rate \(Q_\text{tot} / \rho_0\) (red dashed curve) compared with empirical constraints (light red regions) and the total heating rate from Cranmer et al. (2007) (green dot-dashed curve), all in erg s\(^{-1}\) g\(^{-1}\). Standard model value for \(\lambda_\perp\) (solid black curve) compared with earlier assumption \(\lambda_\perp \propto B_0^{-1/2}\) (black dotted curve) and with in situ estimates (gray region), shown in units of cm. See the text for data sources.

(A color version of this figure is available in the online journal.)
plasma properties. This seems to be the general assumption made by the majority of MHD simulations of turbulence in the solar wind. Whether or not this approximation is valid, it is useful to begin studying the wavenumber dependence of the cascade in this manner.

3.1. Wavenumber Advection–Diffusion Equations

We model the MHD fluctuations as time-steady Fourier distributions of wave power in three-dimensional wavenumber space. Although additional information about the physics of turbulence can be found in more complex statistical measures of the system (e.g., higher-order structure functions), we limit ourselves to describing the power spectrum because that is the basic quantity needed to compute the quasilinear particle heating rates.

Because of the simplified flux-tube geometry discussed in Section 2.1, we assume the background magnetic field is parallel to the bulk flow velocity, and thus the system has only one preferred spatial direction (see, however, Narita et al. 2010). The random turbulent motions create a statistical equivalence between the x- and y-directions transverse to the background field, so that we can describe the power spectra as two-dimensional functions of \( k_x \) and \( k_y \) only. By convention, we define the full three-dimensional power spectrum \( E_m \) in effective velocity-squared units; i.e., when integrated over the full volume of wavenumber space, the spectrum gives the fluctuation energy density per unit mass, or

\[
\frac{U_m}{\rho_0} = \int d^3k \, E_m(k). \tag{30}
\]

In Appendix A, we review some of the basic physical processes that determine the shape of the spectrum for Alfvénic \((m = A)\) and fast-mode \((m = F)\) fluctuations.

We describe the driven turbulent cascade as a combination of advection and diffusion in wavenumber space. At first, it may appear that a smooth and continuous description of the spectral “spreading” of a cascade ignores too much of the inherently stochastic and nonlocal nature of turbulence. However, Chandrasekhar (1943) showed that such a model can be made to capture the essential statistics of a large ensemble of random-walk-like (i.e., Brownian) processes. Specific models of turbulent wavenumber transport using diffusion or advection equations include those of Pao (1965), Leith (1967), Tu et al. (1984), Tu (1988), Zhou & Matthaeus (1990b), Miller et al. (1996), Stawicki et al. (2001), Chandran (2008b), and Matthaeus et al. (2009, 2009), Jiang et al. (2009), and Galier & Buchlin (2010).

For the cascade of Alfvénic fluctuations, we generally follow the approach taken by Cranmer & van Ballegooijen (2003). The general forms of these equations are given as

\[
\frac{\partial E_A}{\partial t} = \frac{1}{k^4} \frac{\partial}{\partial k} \left( D_{A\parallel} \frac{\partial}{\partial k} (k^2 E_A) - \mu A E_A \right) + \alpha_i \frac{\partial}{\partial k} \left( D_{A\parallel} \frac{\partial E_A}{\partial k} \right) + S_A - 2 \gamma A E_A + C_{AF} \tag{31}
\]

\[
\frac{\partial E_F}{\partial t} = \frac{\alpha_F}{k^2} \frac{\partial}{\partial k} \left( k^2 D_F \frac{\partial E_F}{\partial k} \right) + S_F - 2 \gamma F E_F - C_{AF} \tag{32}
\]

\footnote{See, however, “expanding box” type simulations (Grappin & Velli 1996; Liewer et al. 2001) that attempt to include some aspects of the large-scale radial evolution of the plasma parcel undergoing a turbulent cascade, and collisionless kinetic models that include expansion effects together with local diffusion in velocity space (Isenberg & Vasquez 2009, 2011).}
and the terms on the right-hand sides of Equations (31) and (32) are defined throughout the remainder of this subsection. The mode coupling term $C_{AF}$ is described further in Section 4, and the dissipation rates $\gamma_{A}$ and $\gamma_{T}$ are described in Section 5.

The perpendicular Alfvénic cascade is described by the first term on the right-hand side of Equation (31), and we assume an arbitrary linear combination of advection and diffusion. Cranmer & van Ballegooijen (2003) found that many key properties of the turbulence do not depend on whether the cascade is modeled as advection, diffusion, or both, so we retain all terms for maximum generality. For both the parallel Alfvénic spectral transport and the isotropic fast-mode transport, a more standard diffusion coefficient is assumed. The dimensionless multipliers to the $E_{A}$ diffusion coefficients are denoted $\alpha_{\parallel}$ and $\alpha_{ \perp}$ to correspond roughly to $\alpha_{A}$ in Equation (18), and the dimensionless multiplier for the wavenumber advection coefficient is denoted $\mu_{\perp}$.

For the Alfvénic cascade, the overall behavior of wavenumber transport in the perpendicular and parallel directions is specified by the diffusion-like coefficients

$$D_{A_{\perp}} = \frac{k_{\perp}^2}{\tau_{A_{\perp}}}, \quad D_{A_{\parallel}} = \left(\frac{v_{\perp}}{V_{A}}\right)^2 D_{A_{\perp}},$$

(33)

where $\tau_{A_{\perp}}$ is the cascade timescale defined below, and $v_{\perp}$ is the $k_{\perp}$-dependent velocity response of the waves. Note that $D_{A_{\parallel}}$ is independent of $k_{\parallel}$, so it can be pulled out of the derivative in Equation (31). Cranmer & van Ballegooijen (2003) showed that the above form for the diffusion coefficients tends to reproduce the Goldreich & Sridhar (1995) critical balance, and Mattheaus et al. (2009) derived similar functional forms for the coefficients. When specifying the properties of the wavenumber cascade, we apply the scalings for “balanced” turbulence (i.e., zero cross helicity, or $Z_{\ast} = Z_{\perp}$), which is more straightforward to implement but is formally inconsistent with the large-scale transport model of Section 2.

For ideal MHD Alfvénic fluctuations, $v_{\perp}^2$ is equal to $b_{\perp}^2$, the latter representing the transverse magnetic variance spectrum divided by $4\pi B_{0}$ to convert it to units of velocity squared. Following the usual convention, the power spectrum $E_{A_{\perp}}$ tracks the magnetic fluctuations, so the reduced spectra are defined formally as

$$b_{\perp}^2 = k_{\perp}^2 \int dk_{\perp} E_{A_{\perp}}, \quad v_{\perp}^2 = \phi b_{\perp}^2.$$

(34)

The dimensionless factor $\phi$ describes the departure from ideal MHD energy equipartition. For small values of $k_{\perp}$, we assume $\phi \approx 1$. However, as $k_{\perp}$ increases into the regime of kinetic Alfvén waves (KAWs), $\phi$ can become much larger than 1. Hollweg (1999) described how the main difference between $v_{\perp}$ and $b_{\perp}$ in the KAW regime comes from an enhanced response of the electron velocity distribution to the electric and magnetic fluctuations. For simplicity, we use an approximate analytic expression

$$\phi = \frac{\omega^2}{k_{\perp}^2 v_{\perp}^2 V_{A}} \approx \frac{1 + k_{\perp}^2 \rho_{p}}{1 + k_{\perp}^2 \rho_{p}^2 m_{e}/(\beta m_{p})},$$

(35)

where $\rho_{p} = w_{p}/\Omega_{p}$ is the proton thermal gyroradius, with the proton most-probable speed given by $w_{p} = (2k_{B} T_{p}/m_{p})^{1/2}$ and the proton cyclotron frequency by $\Omega_{p} = eB/m_{p}c$. Our term $\phi$ is equivalent to $\alpha^2$ as defined by Howes et al. (2008).

Inspired by Equation (A6), we define the Alfvénic spectral transport timescale as

$$\tau_{A} = \frac{1 + \chi_{0}}{k_{\perp} v_{\perp}},$$

(36)

where we chose to replace the general critical balance parameter $\chi$ by its value at the outer-scale parallel wavenumber $k_{0\parallel}$. Thus,

$$\chi_{0} = \frac{\omega_{0}}{k_{\perp} v_{\perp}} \approx \frac{k_{0\parallel} V_{A}}{k_{\perp} b_{\perp}}$$

(37)

and $\chi_{0}$ is the appropriate critical balance parameter to use when solving for the properties of the dominant low-frequency cascade. From Equation (35) we see that KAW outer-scale frequency $\omega_{0} \approx \phi^{1/2} k_{0\parallel} V_{A}$, so that a factor of $\phi^{1/2}$ cancels out of both the numerator and denominator to give the final approximate expression above. The wavenumber $k_{0\parallel}$ specifies the spatial scale along the field at which energy is injected in the source term $S_{\perp}$ (see below). Because $k_{0\parallel}$ is assumed to be constant (at a given heliocentric distance $r$), the parameters $\tau_{A}$ and $\chi_{0}$ are both functions of $k_{\perp}$ and not $k_{\parallel}$. The above form for Equation (36) was motivated by the analysis of Zhou & Matthaeus (1990b), Chandran (2008b), and Howes et al. (2011), who described how the cascade and wavenumber anisotropy change when the system transitions from weak ($\chi_{0} \gg 1$) to strong ($\chi_{0} \ll 1$) turbulence.

As mentioned above, our expressions for $\tau_{A}$, $D_{A_{\perp}}$, and $D_{A_{\parallel}}$ assume zero cross helicity (i.e., $R = 1$). There is still no agreement about how to generalize these terms when inefficient wave reflection gives rise to nonzero cross helicity. Lithwick et al. (2007) found that the cascade timescales for outward and inward wave modes are different from one another when $R \neq 1$, but their parallel spatial scales are the same. However, Beresnyak & Lazarian (2008, 2009) found that $k_{\parallel}$ for the outward mode should be larger than $k_{\parallel}$ for the inward mode, and thus the Goldreich & Sridhar (1995) critical balance must be modified (see Equation (45) below). Chandran (2008b) outlined a method for setting up the advection–diffusion equations in the case of $R \neq 1$, but we defer a full implementation of that approach to future work.

Putting aside the issue of imbalanced turbulence, the dominant perpendicular nature of the Alfvénic cascade allows us to define a reduced transport equation that follows the evolution of the spectrum as a function of $k_{\perp}$ only. If we ignore the mode coupling term $C_{AF}$ for now, we can multiply Equation (31) by $k_{\perp}^2$ and integrate over $k_{\parallel}$ to obtain

$$\frac{\partial b_{\perp}^2}{\partial t} = k_{\perp} \frac{\partial}{\partial k_{\perp}} \left[ \frac{1}{\tau_{A_{\perp}}} \left( \alpha_{\perp} k_{\perp} \frac{\partial b_{\perp}^2}{\partial k_{\perp}} - \mu_{\perp} b_{\perp}^2 \right) \right] + \tilde{S}_{\perp} - 2 \tilde{\gamma}_{A} b_{\perp}^2.$$

(38)

This is essentially the same as Equation (11) of Cranmer & van Ballegooijen (2003). The reduced source term $\tilde{S}_{\perp}$ and dissipation rate $\tilde{\gamma}_{A}$ are defined similarly to the corresponding terms in Equation (31), but they are weighted toward the low-$k_{\parallel}$ regions of wavenumber space that are “filled” by the cascade. In Appendices C.1–C.3, we derive analytic solutions for the time-steady Alfvén wave power spectrum in various limiting cases.

The cascade of fast-mode waves, described by Equation (32), appears to be conceptually simpler than the strongly anisotropic Alfvén wave cascade. The diffusion coefficient is given by $D_{T_{\parallel}} = k_{\perp}^2/\tau_{T_{\parallel}}$, where $\tau_{T_{\parallel}}$ is related to the IK-like cascade time given by Equation (A2) with $p = 1$. There is increasing
evidence (e.g., Markovskii et al. 2010) that a fast-mode cascade is more rapid in the directions perpendicular to the field than along the field. However, the cascade does appear to proceed outward “radially” in the direction of increasing $k$. Thus, it makes the most sense to use an isotropic diffusion formalism as in Equation (32), but scale the magnitude of the diffusion timescale with $\theta$. Following the weak turbulence model of Chandran (2005), we adopt

$$\tau_F = \frac{V_A}{k v_F^2 \sin \theta}, \quad (39)$$

which implies that

$$D_F = \frac{k^3 v_F^2 \sin \theta}{V_A} = \frac{4\pi k^6 E_F \sin \theta}{V_A}. \quad (40)$$

Chandran (2005) showed that the $\sin \theta$ dependence in the denominator of $\tau_F$ is consistent with an isotropic energy flux for the cascade, but it does not guarantee an isotropic wavenumber spectrum $E_F(k)$. More information about how we chose to implement the fast-mode cascade is given in Appendices C.4 and C.5.

In order to fully describe the cascade in the advection–diffusion equations, four dimensionless spectral transport constants ($\alpha_\perp, \alpha_\parallel, \mu_\perp, \alpha_F$) need to be specified. Matthaeus et al. (2009) summarized the results of many MHD turbulence models and found that $\alpha_\perp$ often takes on values between 0.2 and 0.5, and $\alpha_\parallel \approx 0.43/\alpha_\perp$ seems to be a useful parameterization (see Equation (13) of Matthaeus et al. 2009). Zhou & Matthaeus (1990b) and Matthaeus et al. (2009) made a case for a classical form of the diffusion operator that implies $\mu_\perp = 2\alpha_\perp$. Alternatively, van Ballegooijen (1986) found that a cascade of random-walk-like displacements of magnetic flux tubes is described well by $\mu_\perp = \alpha_\perp$. Howes et al. (2008) and Chandran (2008b) used a straightforward advection equation to model an Alfvénic cascade, which sets $\alpha_\perp = 0$ and assumes $\mu_\perp \neq 0$. For this type of model, Howes et al. (2008) derived $\mu_\perp \approx 0.2$.

In our models, we are constrained by the values of the cascade constants $\tilde{\alpha}_A$ and $\tilde{\alpha}_F$ used in the global transport equations of Section 2. We related these constants to the ones defined above by integrating the cascade advection–diffusion terms over wavenumber to find $\partial U_m/\partial t$. By demanding this quantity be equal to the heating rate $Q_m$, we obtained

$$\frac{2\alpha_\perp}{3} + \mu_\perp = \frac{3\sqrt{6\pi}}{4} \tilde{\alpha}_A, \quad (41)$$

which assumes that the perpendicular cascade is dominant and that $R \approx 1$, and

$$\alpha_F = \frac{32}{7\pi} \tilde{\alpha}_F. \quad (42)$$

We keep the ratio $s = \mu_\perp/\alpha_\perp$ as a free parameter and we explore the ramifications of varying it below. Note, however, that if we used $s = 2$ (as assumed by Zhou & Matthaeus 1990b), then Equation (41) gives $\alpha_\perp \approx 0.73$ and $\mu_\perp \approx 1.47$. These are roughly consistent with the constants given by Zhou & Matthaeus (1990b) and Matthaeus et al. (2009). To complete the system of cascade constants, we adopt the Matthaeus et al. (2009) choice for $\tilde{\alpha}_F = 0.43\alpha_\perp$, but we compute this quantity using the Matthaeus et al. (2009) assumption of $s = 2$.

The source terms, $S_A$ in Equation (31) and $S_F$ in Equation (32), describe the outer-scale injection of fluctuation energy. The global energy balance of the waves is already described by the radial transport model of Section 2. Thus, we specify the magnitudes of $S_A$ and $S_F$ by demanding that the time-steady total energy densities $U_A$ and $U_F$ be maintained at their known values at a given distance $r$. From a physical standpoint, however, it is unclear whether the passive propagation of waves dominates the source terms, or whether there is significant local “stirring” that converts large-scale dynamical motions (e.g., velocity shears in evolved corotating streams) into new fluctuations.

We adopt specific functional forms for $S_A(k_\parallel, k_\perp)$ and $S_F(k)$ that are described in detail in Appendix C. Generally, the source terms are nonzero only at the lowest wavenumbers, at which the fluctuations are driven. For the Alfvén waves, we continue to use the assumption from Section 2.3 that the perpendicular driving scale is set by the turbulence correlation length; i.e., $k_\perp = 1/\lambda_\perp$. For the fast-mode fluctuations, we assume their outer-scale wavenumber magnitude $k_{OF}$ is also equal to $k_{OF}$, since the largest-scale transverse stirring motions are likely to be common to both Alfvénic and fast-mode waves. There are several ways that one could imagine defining the parallel outer-scale Alfvén wavenumber $k_{OF}$.

1. Monochromatic Alfvén waves that propagate up from the corona retain a constant frequency $\omega_0$ in the Sun’s inertial frame. However, because the phase speed varies with distance, the corresponding wavelength undergoes “stretching” commensurate with the dispersion relation

$$k_{OF} = \frac{\omega_0}{\omega_0 + V_A}. \quad (43)$$

2. The fluctuations propagating up from the Sun may already be fully turbulent (see, e.g., van Ballegooijen et al. 2011). Thus, the outer-scale parallel wavenumber may be coupled continuously to the perpendicular wavenumber via critical balance (Goldreich & Sridhar 1995), with

$$k_{OF} \approx k_{OF} \left(\frac{U_A}{V_A} \sqrt{\rho_0} \right). \quad (44)$$

3. In flux tubes with nonzero cross helicity (i.e., $R < 1$), Beresnyak & Lazarian (2008, 2009) found that the inward waves should obey the Goldreich & Sridhar (1995) critical balance, but the outward waves (which are generally what we intend to model) obey a modified version of critical balance, which we approximate as

$$k_{OF} \approx k_{OF} \left(\frac{U_A}{V_A} \sqrt{\rho_0} \frac{1}{R} \right). \quad (45)$$

4. In some cases we assume that the dimensionless ratio $k_{OF}/k_{OF}$ remains fixed at a constant specified value. Many studies of MHD turbulence assume isotropic forcing at the outer scale, which is consistent with the fixed ratio $k_{OF}/k_{OF} = 1$. The lack of a physical justification for this approximation is offset by its simplicity.

Figure 5 illustrates the ratio $k_{OF}/k_{OF}$ for several of the above methods of setting the parallel outer scale. For example, it shows the result of evaluating Equation (43) for a range of wave periods $P = 2\pi/\omega_0$ between 1 and 100 minutes. Constant assumed values of $k_{OF}/k_{OF}$ would correspond to horizontal lines in Figure 5.
3.2. Solutions in the Absence of Coupling

Here we present some example results for the power spectra $E_A(k_\perp, k_\parallel)$ and $E_f(k_\parallel, k_\perp)$. These spectra are computed from Equations (31), (32), and (38) in the limiting cases of time independence and no mode coupling ($C_{AF} = 0$). The Alfvénic spectrum was first computed in its reduced form using the solutions for $b_\perp(k_\perp)$ given in Appendices C.1 and C.2, and then it was expanded into full wavenumber space by using the results of Appendix C.3. The shape of the fast-mode spectrum was determined from the analytic solutions given in Appendices C.4 and C.5.

To illustrate the wavenumber dependence of the power spectra, we chose a single coronal height $z = 10 R_\odot$ at which $\beta \approx 0.04$. We typically plot the wavenumbers in terms of dimensionless quantities $k_\parallel V_A/\Omega_p$ and $k_\perp \rho_p$. Dissipative wave–particle interactions tend to become important when these quantities reach order-unity values, and ideal MHD conditions apply when these quantities are small. Typically, the driving scale for Alfvénic turbulence occurs at $k_0 \rho_p \approx 10^{-6}$ to $10^{-4}$, with the larger values generally occurring at larger heliocentric distances.

In Figure 6 we show the time-steady $k_\perp$ dependence for the Alfvénic $b_\perp$ and $v_\perp$ fluctuations, both with and without KAW dissipation. To set the cascade properties, we utilized the values of the constants given in Section 3.1, and we also assumed $s = \mu_\perp/\alpha_\perp = 2$ and $k_{0\parallel}/k_{0\perp} = 0.1$. The KAW damping ratio $\gamma/\omega$ appropriate for the assumed value of $\beta$, which was used in Equation (C11), is also shown in green (see also Section 5). At the outer scale, the peak value of $v_\perp$ is 42 km s$^{-1}$. We caution that this value should not be assumed to be equivalent to the full rms velocity amplitude. In this case $(U_A/\rho_0)^{1/2} = 196$ km s$^{-1}$, which is almost a factor of five larger than the maximum value of $v_\perp$ at this height.

The damped spectra shown in Figure 6 have several features that resemble those of measured KAWs in the solar wind. Using the conventional form of the reduced energy spectrum $(e_\perp \propto b_\perp^2/k_\perp^2)$, we found that the magnetic fluctuation power made a transition from a Kolmogorov-like power law $k_\perp^{-5/3}$ to a steeper spectrum with $k_\perp^{-2.5}$ at $k_\perp \rho_p \approx 1$. The spectrum becomes shallower again around $k_\perp \rho_p \approx 40$ because the wavenumber dependence of $\phi$ flattens out at low values of $\beta$. This behavior is reminiscent of that predicted by Voitenko & De Keyser (2011). At larger radial distances where $\beta \gtrsim 1$, the KAW dispersion relation (Equation (35)) gives rise to a more sustained increase in $\phi$ with increasing $k_\perp$. This in turn produces spectra that remain steep, with $e_\perp \propto k_\perp^{-2.5}$ persisting over several orders of magnitude of $k_\perp$ in agreement with both measurements (Smith et al. 2006; Sahraoui et al. 2010) and other models (Howes et al. 2008). We note that the predicted undamped KAW power-law decline of $k_\perp^{-7/3}$ (see Appendix C.1) was not seen for any sustained range of $k_\perp$.

Figure 7 shows the result of varying the normalization of the parallel outer-scale wavenumber $k_{0\parallel}$ on the shape of $b_\perp(k_\perp)$. We kept the same value of $s = 2$ that was used in Figure 6, but we varied the constant ratio $k_{0\parallel}/k_{0\perp}$ over five orders of magnitude. For the lowest values of $k_{0\parallel}$ the outer-scale critical balance ratio $\chi_0$ always remains much smaller than unity. This means that the stirring or forcing takes place well within the “filled” region of wavenumber space, and thus strong turbulence occurs. In this case, $b_\perp \propto k_\perp^{-1/3}$ and thus $e_\perp \propto k_\perp^{-5/3}$. The opposite extreme...
Figure 7. Reduced Alfvénic magnetic spectra at $z = 10 R_\odot$, computed assuming different values of $k_0 / k_{0\perp} = 0.01$ (red dashed curve), 0.1 (black solid curve), 1 (green dotted curve), 10 (blue dot-dashed curve), and 1000 (violet dotted curve). (A color version of this figure is available in the online journal.)

case of large $k_0$ corresponds to $\chi_0 \gg 1$ and weak turbulence with less anisotropic driving. In that limit, the inertial range spectra are given by $b_\perp \propto k_\perp^{-1/2}$ and $e_\perp \propto k_\perp^{-2}$. Our model shows the gradual transition between these two extreme cases.

In Figure 8 we compare the Alfvén and fast-mode spectra with one another. As above, we used the background conditions at a coronal height of $z = 10 R_\odot$ and we assumed $k_0 \parallel / k_0 \perp = 0.1$. We illustrate the most extreme case of a lack of high-frequency Alfvénic power by showing the contours of $E_A(k_\parallel, k_\perp)$ for the case $s \rightarrow \infty$. In this limit, Equation (C16) describes an exponential decrease of power with increasing $\chi$. Other comparable examples of this kind of spectrum can be found in Figure 4(b) of Cranmer & van Ballegooijen (2003) and Figures 1 and 2 of Jiang et al. (2009). We computed the Alfvénic and fast-mode spectra with the kinetic sources of damping that were described in Section 5. Note that $E_F$ experiences the strongest damping at intermediate values of $\theta$. For $\theta \lesssim 10^\circ$ or $\theta \gtrsim 85^\circ$, the transit-time damping described by Equation (58) is relatively weak.

4. COUPLING BETWEEN ALFVÉN AND FAST-MODE WAVES

4.1. Basic Physics and Phenomenological Rates

There are several ways that the ideal linear MHD wave modes can become coupled to one another in the corona and solar wind.

1. Inhomogeneities in the background plasma can blur the definitions of the individual modes. For example, linear reflection due to radial variations in $V_A$ (Ferraro & Plumpton 1958; Heinemann & Olbert 1980) may produce not only incoming Alfvén waves (i.e., $0 < R < 1$), but also fast and slow magnetosonic waves (e.g., Stein 1971; McDougall & Hood 2007). In addition, large-scale bends in the background magnetic field B (Frisch 1964; Wentzel 1974), density variations between flux tubes (Valley 1974; Markovskii 2001; Mecheri & Marsch 2008), or velocity shears (Poedts et al. 1998; Gogoberidze et al. 2007) can drive instabilities that partially convert Alfvén waves into other modes.

2. Even in a homogeneous medium, the MHD waves begin to lose their ideal linear character when their amplitudes become large. Nonlinear Alfvén waves naturally drive second-order fluctuations in $V_A$ and $\delta \rho$ that mimic the properties of both slow and fast magnetosonic waves (Hollweg 1971; Spangler 1989; Vasquez & Hollweg 1999). Large-amplitude waves also excite a range of wave–wave interactions that can often be characterized either as two
modes giving birth to a third, or one mode splitting into several others (e.g., Chin & Wentzel 1972; Goldstein 1978; Del Zanna et al. 2001; Sharma & Kumar 2010). Models of weak turbulence, in which the wave–wave interactions describe the cascade process (Chandran 2005, 2008a; Luo & Melrose 2006; Yoon & Fang 2008) also create this kind of coupling.

3. Although not strictly a multi-mode coupling, when \( k_\perp \rho_p \gtrsim 1 \) the Alfvén mode begins to exhibit oscillations in density, parallel electron velocity, and the parallel electric and magnetic fields (Hasegawa & Chen 1976; Hollweg 1999). Observationally, it has proved difficult to separate such dispersive KAW density fluctuations from those arising from independent sources of fast or slow MHD waves (e.g., Harmon & Coles 2005; Chandran et al. 2009).

In this paper, we take account of one particular nonlinear effect from the second entry in the above list. Specifically, Chandran (2005) suggested that weak turbulence couplings between Alfvén and fast-mode fluctuations may provide enough power at high \( k_\perp \) to induce substantial ion cyclotron heating. Suzuki et al. (2007) argued that this effect may be relatively unimportant because the fast-mode cascade timescale \( \tau_F \) is long in comparison to the Alfvén cascade timescale \( \tau_A \). This may be the case in the low-frequency regime of wavenumber space where \( \chi \ll 1 \), but at the cyclotron resonant frequencies of interest (\( k_\perp \sim \Omega_p/\nu_A \)) the Alfvénic cascade is quenched because \( \chi \gg 1 \). The fast-mode cascade may in fact even be faster than any intrinsic Alfvénic spectral transfer in this region of wavenumber space. Therefore, we proceed using the Chandran (2005) results for Alfvén/fast-mode coupling.

We express the coupling term in Equations (31) and (32) as

\[
C_{AF} = \frac{E_F - E_A}{\tau_{AF}}
\]  

(46)
such that, in the absence of other processes, the power spectra at a given wavenumber \( k \) are driven toward a common value over a coupling timescale \( \tau_{AF}(k) \). The weak turbulence model of Chandran (2005) gave an approximate value for this timescale of

\[
\tau_{AF} \approx \frac{15}{23 \pi^2} \tau_F \sin^2 \theta
\]  

(47)
which holds in the limiting cases of \( E_F > E_A \) and nearly parallel propagation (\( \theta \ll 1 \)). In the opposite case of \( E_A \gg E_F \), it is likely that \( \tau_{AF} \) would no longer depend linearly on \( \tau_F \) and may scale instead with \( \tau_A \). However, the region of wavenumber space with which we are most concerned is the high-\( k_\perp \), low-\( \theta \) ion cyclotron regime. At those wavenumbers, we know that in the absence of coupling the condition \( E_F \gg E_A \) is likely to be satisfied, and the coupling will be a transfer of energy from the dominant fast-mode spectrum to the much less intense Alfvén mode.

The wave–wave conditions of frequency and wavenumber matching (e.g., Sagdeev & Galeev 1969) confirm that the most rapid coupling should occur when the dispersive properties of the Alfvén and fast-mode waves are the most similar to one another; i.e., at \( \theta \to 0 \). Note that Equation (39) gave \( \tau_F \propto 1/\sin \theta \), so the combined dependence for the coupling time is \( \tau_{AF} \propto \sin \theta \). In practice, however, we found that using this ideal expression for \( \tau_{AF} \) could lead to an unphysical singularity at \( \theta = 0 \). We removed this singularity by replacing \( \theta \) in Equation (47) by \( \theta + \delta \theta \). We set \( \delta \theta \) to a constant value of 0.01 to avoid having an infinitely fast coupling rate at parallel propagation.\(^5\) To retain the most generality, we chose to reparameterize the coupling timescale as

\[
\tau_{AF} = \frac{1}{\Phi} \tau_F \sin^2(\theta + \delta \theta),
\]  

(48)
where we find it useful to vary the constant coupling strength \( \Phi \) up or down from the value of \( 23\pi^2/15 \approx 15.1 \) derived by Chandran (2005). The case \( \Phi = 0 \) corresponds to ignoring the coupling altogether.

Note that the above form for the coupling timescale implies that \( \tau_{AF} \propto k_\perp/k^{3/2} \), so that the coupling is rapid at wavenumbers corresponding to ion cyclotron resonance (large \( k_\perp \), small \( k_\parallel \)). The coupling is much slower at KAW wavenumbers favored by the pure Alfvénic cascade (small \( k_\perp \), large \( k_\parallel \)). Thus, the bulk of the Alfvénic spectrum at \( \chi \ll 1 \) is likely to be more or less unaffected by the coupling. This seems to be consistent with our assumption that the integrated energy densities \( U_A \) and \( U_F \) also remain uncoupled from one another. We realize that this may be a severe underestimate of the degree of energy transfer between Alfvén and magnetosonic modes in the corona and solar wind. However, one main purpose of this paper is to investigate how much can be accomplished with only this small degree of coupling in the high-\( k_\perp \) tails of the power spectra.

### 4.2. Approximate Solutions for Coupled Spectra

The exact solutions to Equations (31) and (32) with coupling \( (C_{AF} \neq 0) \) must be found numerically. Here we present an approximate solution that is both (1) likely to reflect the proper behavior of more rigorous numerical solutions in many limiting regimes of parameter space, and (2) efficient to implement on a large grid of model spectra spanning a wide range of heliocentric distances. We begin by approaching the problem iteratively; i.e., we solve Equation (31) for \( E_A \) under the assumption that \( E_F \) is known, and we then solve Equation (32) for \( E_F \) under the assumption that \( E_A \) is known. The analytic solutions derived below suggest a natural way to terminate this iteration after only one round.

When solving the advection–diffusion equation for Alfvénic fluctuations, let us temporarily ignore the outer-scale source term \( S_A \) and the dissipation-range damping term that depends on \( \gamma_A \). Since we are most concerned with the generation and transport of wave power in the high-\( k_\perp \) regions that undergo ion cyclotron resonance, we consider the weak turbulence regime of \( \chi \gg 1 \), in which the transport of energy is mainly from low to high \( k_\perp \) and there is negligible parallel spreading (see also Oughton et al. 2006). Thus, we solve the advection–diffusion equation for discrete, non-interacting “strips” of wavenumber space each having constant \( k_\perp \). The nonlinear coupling supplies wave energy locally, and the Alfvénic cascade takes it from low to high \( k_\perp \). If we simplify further by assuming pure advection (i.e., \( \alpha = 0 \)), the time-steady version of Equation (31) becomes

\[
\frac{\mu_\perp}{k_\perp} \frac{\partial}{\partial k_\perp} \left( \frac{k_\perp^2 E_A}{\tau_A} \right) = \frac{E_F - E_A}{\tau_{AF}}.
\]  

(49)
where we use Equation (A6) to give the timescale \( \tau_A \approx \chi/(k_\perp v_\perp) \) in the weak turbulence regime, and we use Equation (48) for \( \tau_{AF} \).

\(^5\) Also note that the magnetic field in MHD turbulence undergoes a complex, multi-scale “wandering,” such that the direction corresponding to \( \theta = 0 \) is continuously varying in time and space (see, e.g., Ragot 2006; Shalchi & Kourakis 2007). Thus, the plasma may seldom “see” exactly parallel wavenumber conditions.
The advection–coupling equation above can be rewritten as a first-order ordinary differential equation,

\[
\frac{\partial E_A}{\partial k_\perp} + \left( \frac{10}{3k_\perp} + \frac{f_0}{k_\perp^{10/3}} \right) E_A = \frac{f_0 E_F}{k_\perp^{10/3}},
\]

where

\[
f_0 = \frac{\Phi}{\mu_\perp} \left( \frac{v_{\text{OF}}}{v_{0\text{L}}} \right)^2 k_{\perp}^{3/2} k_{\parallel}^{5/2}.
\]

To obtain Equation (50), we made several power-law assumptions for the timescales \( \tau_A \) and \( \tau_{\text{AF}} \), which depend on the velocity spectra \( v_\perp \) (for Alfvén waves) and \( v_\parallel \) (for fast-mode waves), respectively, with

\[
v_\perp = v_{0\text{L}} \left( \frac{k_\perp}{k_{0\text{L}}} \right)^{-1/3}, \quad v_\parallel = v_{\text{OF}} \left( \frac{k}{k_{\text{OF}}} \right)^{-1/4}.
\]

We also assumed that we are solving for \( E_A \) mainly in the small-\( \theta \) region of wavenumber space in which \( k \approx k_1 \).

With the above assumptions taken into account, Equation (50) can be solved by means of an integrating factor. We first define the dimensionless independent variable

\[
y = \frac{3f_0}{7k_{\perp}^{10/3}}, \quad \left( \frac{k_\perp}{k_{0\text{L}}} \right)^7 \left( \frac{k_{\parallel}}{k_{0\parallel}} \right)^{7/3}
\]

which is a measure of the relative strength of the nonlinear coupling. When \( y \gg 1 \) (or \( k_\perp \ll k_\parallel \)) the coupling is strong and we should expect \( E_A \approx E_F \). When \( y \ll 1 \) (or \( k_\perp \gg k_\parallel \)) the coupling is weak in comparison to the cascade and we expect \( E_A \approx E_F \). Note also that \( y \) depends much more sensitively on \( \theta \) than on the magnitude \( k \). Working through the integrating factor method and choosing an integration constant of zero (to avoid the solution diverging to infinity when \( y \gg 1 \)), we obtain

\[
E_A = \frac{7y^3}{3} \left[ 1 - e^y y^{3/7} \Gamma \left( \frac{4}{7}, y \right) \right] E_F,
\]

where \( \Gamma(a, y) \) is the incomplete gamma function. This function behaves as expected in the limits of strong and weak coupling as discussed above.

Next, we solve the coupled fast-mode advection–diffusion equation for \( E_F \) under the assumption that \( E_A \) is known. Making use of many of the same simplifications that were used to solve the \( E_A \) equation, we include only the cascade and coupling terms, with

\[
\alpha_F \frac{\partial}{\partial k_\perp} \left( k^2 D_F \frac{\partial E_F}{\partial k_\perp} \right) = C_{\text{AF}} \left[ \frac{1}{\gamma_{\text{AF}}} \left( 1 - \frac{E_A}{E_F} \right) \right] E_F.
\]

Noticing that the quantity in square brackets above is an effective damping rate \( \gamma_{\text{AF}} \), we use Equation (54) to write the ratio \( E_A/E_F \) as a known function of \( k_1 \) and \( k_\perp \). After substituting in the wavenumber dependence for \( \tau_{\text{AF}} \), we found that \( \gamma_{\text{AF}} \propto (k/k_{\text{OF}})^{1/2} \). The analytic solution of \( E_F(k) \) for this special case is given in Equation (C32), and the constant \( c_\gamma \) in that expression is specified here to be

\[
c_\gamma = \frac{8\Phi}{49\alpha_F \sin^2 \theta} \left( 1 - \frac{E_A}{E_F} \right).
\]

The solution of Equation (C32) is applied only for \( k \geq k_{\text{OF}} \), and the uncoupled/undamped fast-mode power spectrum \( E_{\text{OF}} \) is used for \( k < k_{\text{OF}} \).

Since our solution for the ratio \( E_A/E_F \) depends only on wavenumber and not on any prior solutions of \( E_A \) or \( E_F \), we found that there is no need for further iteration. We solve first for \( E_F \) as described above, using Equation (54) for the ratio \( E_A/E_F \), and then we use this ratio to solve for \( E_A \). Note that the complete solution for \( E_F \) must take account of both coupling and transit-time damping (i.e., the damping rate given by Equation (58)). In practice, we apply both types of damping separately to the uncoupled and undamped fast-mode power spectrum \( E_{\text{OF}} \) and we use the solution that gives rise to stronger local damping at any given wavenumber. At high enough values of \( k_1 \), the complete solution for \( E_A \) must take into account the effects of ion cyclotron damping. We use the approximate prescription given by Equation (C20) to implement this damping.

If the original uncoupled spectra obey \( E_{\text{OA}} \leq E_{\text{OF}} \), then the coupled spectra follow

\[
E_{\text{OA}} \leq E_A \leq E_F \leq E_{\text{OF}}
\]

at wavenumbers in the high-\( k_1 \) regime where the coupling is applied. Usually, the relative increase in \( E_A \) from its uncoupled solution is greater than the relative decrease in \( E_F \) from its uncoupled solution. In all cases, however, we found that the variations in the spectra introduced by the coupling do not significantly affect the total wavenumber-integrated power in either \( E_A \) or \( E_F \).

Figure 9 illustrates the effects of including coupling on \( E_A \). As in earlier plots of spectrum results, we used the representative height \( z = 10 R_\odot \) and we assumed \( k_{\text{of}} = k_{0\parallel}/10 \). In order to show that the coupling can be efficient even when the uncoupled Alfvén wave power \( E_{\text{OA}} \) is negligibly small, we assumed the extreme limiting case of \( s \to \infty \). In Figure 9(a) we show the \( k_1 \) dependence of the spectra along a slice taken at a constant value of \( k_{0\perp} = k_{0\parallel} \). We varied the parameter \( \Phi \) between \( 10^{-6} \) and \( 10^{3} \). Even if the coupling is several orders of magnitude weaker than estimated by Chandran (2005), it is still likely to be efficient at generating some Alfvénic wave power at \( k_1 \approx \Omega_r/V_A \). However, if the coupling constant \( \Phi \) is significantly smaller than \( \sim 10^{-3} \), the ion cyclotron damping at \( k_1 \approx \Omega_r/V_A \) is likely to overshadow the “local supply” of wave energy from the coupling and give rise to a low level of resonant wave power.

Figure 9(b) shows how the power at a given wavenumber \( (k_\perp = k_{0\perp} \text{ and } k_\parallel V_A/\Omega_r = 10^{-3}) \) varies as a function of \( \Phi \). The fast-mode power decreases monotonically as \( \Phi \) is increased, which confirms our treatment of the coupling in Equation (55) as an effective damping. The Alfvénic power generally increases (from its uncoupled value far below the lower edge of the plot) with increasing \( \Phi \), but there is some nonmonotonicity around \( \Phi \approx 10^{-2} \). This gives rise to a slightly counterintuitive result that there may be more \( E_A \) power at high \( k_1 \) (and thus more proton and ion heating) at some values of \( \Phi \) than in the \( \Phi \to \infty \) limit.

An example of the full wavenumber dependence of the coupled \( E_A(k_1, k_\perp) \) spectrum is shown in Figure 10(a) for a radial distance of \( r = 10 R_\odot \). This model has the same parameters as the one shown in Figure 8, except that we set \( \Phi = 10 \). Despite the appearance of substantial wave power at large values of \( k_1 \), most of the power is still contained within the critical balance locus of \( \chi \lesssim 1 \). This is illustrated in another way by Figure 10(b), in which we show the radial dependence of the spectrum-averaged angle \( \Theta_{\text{BA}} \) between the background field direction and the wavenumber vector \( k \). We used a definition for the spectrum-averaged wavevector anisotropy that is similar
to that of Gary et al. (2010),

\[
\tan^2(\langle \Theta_{Bk} \rangle) = \frac{\int d^3k \ E_A(k) k^2_\perp}{\int d^3k \ E_A(k) k^2_\parallel}. \tag{57}
\]

Note that the model result at \( r = 1 \) AU (89.5°) is reasonably close to the value of ~88° measured by Sahraoui et al. (2010) from the four Cluster satellites at 1 AU. It is evident that a strongly perpendicular (“quasi-two-dimensional”) sense of wavenumber anisotropy is not incompatible with the existence of high-frequency ion cyclotron resonant wave power.

5. KINETIC DISPERSION AND DISSIPATION

When computing the dissipation rates \( \gamma_A \) and \( \gamma_F \), we are careful to distinguish between two conceptually different sources of damping. First, there are the collisional and outer-scale cascade processes that were included in Equation (17). These processes act at low wavenumber and drive the overall radial evolution of the wave energy densities \( U_A \) and \( U_F \). We do not include them in the damping terms in Equations (31) and (32) because their net effects are already included in the source terms \( S_A \) and \( S_F \).

Second, there are the largely collisionless kinetic processes that become dominant at large wavenumbers. These are the actual processes that dissipate the power and give rise to heating, and we describe them in the remainder of this section.

Once the power levels of Alfvénic and fast-mode fluctuations are specified as detailed functions of \( k_\parallel, k_\perp \), and radial distance, we compute their damping rates and species-dependent heating rates from linear Vlasov theory. Although it is known that strong MHD turbulence is far from “wavelike” (i.e., coherent wave packets do not survive for more than about one period before being shredded by the cascade), there is a long history of using damped linear wave theory to study the small-scale dissipation of such a cascade (see, e.g., Eichler 1979; Quataert 1998; Leamon et al. 1999; Quataert & Gruzinov 1999; Marsch & Tu 2001a; Cranmer & van Ballegooijen 2003; Gary & Borovsky 2004; Harmon & Coles 2005). A typical justification of this approach is that no matter the strength of the fluctuations at the outer scale, once the cascade reaches the high-\( k \) dissipation range the magnitudes are much smaller and quite linear; see also Spangler (1991) and Lehe et al. (2009).

For the Alfvén waves, we utilize the Vlasov–Maxwell code described by Cranmer & van Ballegooijen (2003) and Cranmer
et al. (2009) to solve the “warm” linear dispersion relation for the real and imaginary parts of the frequency in the solar wind frame (\(\omega = \omega_r + i \omega_i\)) assuming a known real wavevector \(k\). The code uses the Newton–Raphson technique to isolate individual solutions from a grid of starting guesses in \(\omega_r, \omega_i\) space, and we select only the left-hand-polarized (Alfvénic) solutions. We assumed homogeneous plasma conditions and isotropic Maxwellian velocity distributions (with \(T_p = T_e\)), and we ran the code for a range of assumed values of \(\beta\) between 10\(^{-3}\) and 10\(^{2}\). The code also provides the partition fractions of wave energy in electric, magnetic, kinetic, and thermal perturbations for each wave mode (see also Krauss-Varban et al. 1994).

Figure 11 shows several example solutions for the real and imaginary parts of the frequency along one-dimensional cuts through wavenumber space. For simplicity, we present all damping rates \(\gamma\) as their absolute values, since strictly speaking the solutions from the Vlasov–Maxwell code all have \(\gamma < 0\). Figure 11(a) illustrates the approach to the ion cyclotron resonance regime by holding \(k_\perp\) constant at a small value and plotting \(\omega_r, \gamma\) versus \(k_\parallel\). Note the cessation of weakly damped solutions at \(\gamma \approx \omega_r \approx \Omega_p\), which takes place at lower values of \(k_{\parallel \text{max}}\) for higher values of \(\beta\). Equation (C18) is a parameterized fit to the \(\beta\)-dependence of this cutoff wavenumber.

Figure 11(b) shows the approach to the high-\(k_\perp\) KAW dissipation limit for a constant small value of \(k_\perp\). When solving the dispersion relation along a succession of increasing values of \(k_\perp\), there are sometimes small discontinuities in slope between neighboring solutions (especially in strongly damped regions where \(|\gamma/\omega_r| \gtrsim 0.5\)). Nonetheless, the dispersion properties of our solutions remain sufficiently “KAW-like” to represent a continuous set of damping rates from low to high \(k_\perp\). The behavior of \(\omega_r, \gamma\) versus \(k_\parallel\) agrees reasonably well with the approximate expression given by Equation (35). For values of \(\beta \gtrsim 1\), there are secondary maxima in \(\gamma/\omega_r\) at \(k_\parallel \rho_p \approx 1\) that come from proton Landau damping, whereas the larger rates at \(k_\parallel \rho_p > 10\) are dominated by electron Landau damping. The damping rates shown in Figure 11(b) were also used as the effective KAW ratios \(\gamma_{\parallel}/\omega_r\) described in Appendix C.2. These rates were used to compute the high-\(k_\perp\) dissipation of \(b_\parallel\) and \(v_\perp\) as shown in Figures 6 and 7.

For the fast-mode waves, we make use of a parameterized expression for the rate of transit-time damping, which in several studies was found to be the dominant kinetic process to dissipate this wave mode (e.g., Barnes 1966; Perkins 1973; Yan & Lazarian 2004). Thus, we assume

\[
\frac{\gamma_f}{\omega_r} = \frac{\theta^2}{4} \frac{\sqrt{\pi^2 \beta}}{1 + \theta^2 \Omega_p^2/\omega_r^2} \sqrt{\frac{m_e}{m_p}} \exp\left(-\frac{m_e}{m_p \beta \cos^2 \theta}\right),
\]

where \(\omega_r\) is given by the ideal fast-mode dispersion relation of Equation (4). This expression was given by Yan & Lazarian (2004) based on initial calculations of Stepanov (1958). Equation (58) is valid strictly for only \(\theta \ll 1\), but it does not diverge from the more exact solution at larger \(\theta\) by more than about a factor of two.

The remainder of this section describes how the dissipated Alfvén wave energy is partitioned between protons, electrons, and heavy ions. We ignore the particle heating that comes from fast-mode wave dissipation because its overall magnitude was found to be small in comparison to that from Alfvén waves. In a pure hydrogen plasma, we separate the damping rate \(\gamma\) into components attributed to the kinetic effects of protons and electrons. To zeroth order, the contribution to \(\gamma\) from other ions is negligibly small and can be estimated separately (see below). Thus, we define \(\gamma = \gamma_p + \gamma_e\), where

\[
\gamma_s = \gamma \frac{\psi_s}{\psi_p + \psi_e},
\]

where \(s = p, e\) denotes either the protons or electrons, and the species-dependent resonance functions are given by

\[
\psi_s = \frac{\omega_p \omega_r^2}{k_\parallel w_{\parallel s}} \sum_{\ell = -\infty}^{+\infty} \exp\left(-\tilde{\xi}_{\ell}^2 - \tilde{\xi}_{\ell}^2\right) \sum_{m = -\ell}^{\ell} a_m I_m(\tilde{\xi}_{\ell}),
\]

where \(\omega_p^2 = 4\pi e^2 n_s/m_s\) is the squared plasma frequency, \(w_{\parallel s}\) and \(w_{\perp s}\) are parallel and perpendicular thermal speeds of species.
The dimensionless coefficients \(a_n\) depend on the electric-field polarization vector that is output from the Vlasov–Maxwell dispersion code of Cranmer & van Ballegooijen (2003), and they are given in full by Equations (43)–(45) of Marsch & Tu (2001a). Equation (60) is valid for an isotropic Maxwellian distribution, for which \(w_{\parallel} = w_{\perp}\) and there is assumed to be zero differential bulk flow between the protons and electrons. The dominance of ion cyclotron or Landau damping depends on the values of the dimensionless resonance factors,

\[
\xi_{\parallel} = \frac{\omega - k_{\parallel} \Omega_0}{k_{\parallel} w_{\parallel}}, \quad \xi_{\perp} = \frac{k_{\perp} w_{\perp}}{\Omega_0 \sqrt{2}}, \tag{61}
\]

In practice, we truncate the infinite sum in Equation (60) at \(-10 \leq \ell \leq +10\). Test runs made with a larger range of summation indices produced no substantial differences from those using the default range.

Figure 12 shows separate sets of contours for \(\gamma_p/\omega_o\) and \(\gamma_e/\omega_o\) in wavenumber space for an example value of \(\beta = 0.1\). These contours can be compared with Figure 4(a) of Cranmer & van Ballegooijen (2003), which was computed for \(\beta \approx 0.01\). The proton damping rate \(\gamma_p/\omega_o\) increases rapidly as \(k_{\parallel} V_A/\Omega_p\) approaches unity, and the electron damping rate \(\gamma_e/\omega_o\) increases more slowly as \(k_{\perp} \rho_p\) increases from 0.1 to 100. The complex behavior of the contours in the region of wavenumber space with both high \(k_{\parallel}\) and high \(k_{\perp}\) is the result of the dispersion relation being affected by the presence of strongly damped ion Bernstein modes (see, e.g., Stix 1992; Howes et al. 2008).

It is evident from Figure 12 that, in the solar corona, the region of nearly parallel Alfvén wave propagation in wavenumber space (i.e., \(\theta \ll 1\)) is dominated by proton damping and the region of nearly perpendicular propagation (\(\theta \rightarrow \pi/2\)) is dominated by electron damping. The observational evidence for preferential proton and ion heating (Kohl et al. 2006) thus presents a problem when confronted with the dominant perpendicular anisotropy of Alfvénic turbulence.

Figure 13 illustrates the magnitude of this apparent discrepancy by comparing the large-scale radial dependence of two key angles. The strongly anisotropic Alfvénic cascade is illustrated by \(\theta_{\text{crit}}\), which is the angle between \(\mathbf{k}\) and \(\mathbf{B}_0\) at which occurs both the Goldreich & Sridhar (1995) critical balance (\(\chi = 1\)) and the onset of KAW dispersion (\(k_{\perp} \rho_p = 1\)). We find that \(\tan \theta_{\text{crit}} \approx V_A/b_{\parallel}\), where \(b_{\parallel}\) is evaluated at \(k_{\perp} \rho_p = 1\), and we plot \(\tan \theta_{\text{crit}}\) for three example values of the outer-scale wavenumber ratio \(k_{00}/k_{0\perp}\). Figure 13 also shows the radial dependence of \(\theta_{ep}\), which is defined as the angle at which the contours for \(\gamma_p/\omega_o = 0.1\) intersect with those of \(\gamma_e/\omega_o = 0.1\) in wavenumber space. (This point is shown in Figure 12 with a filled circle.) For \(\theta < \theta_{ep}\) the damping is dominated by protons and ions; for \(\theta > \theta_{ep}\) the damping is dominated by electrons. Note that \(\theta_{ep} \ll \theta_{\text{crit}}\) in the solar corona and much of the inner heliosphere, so that it is difficult to see how the cascade of linear Alfvén waves alone can be responsible for the observed proton and ion heating.

We computed the rates of proton and electron plasma heating from the modeled values of \(\gamma_p\) and \(\gamma_e\) by using the quasilinear framework outlined by Marsch & Tu (2001a) and Cranmer & van Ballegooijen (2003). The volumetric heating rates \(Q_s\) (e.g., expressed in units of erg s\(^{-1}\) cm\(^{-3}\)) are given by integrals over vector wavenumber \(\mathbf{k}\) of the form

\[
Q_s/\rho = \int d^3\mathbf{k}\ E_s(\mathbf{k}) 2\gamma_s, \tag{62}
\]
\[ \begin{align*}
\text{Table 2} \\
\text{Choices for Cascade and Coupling Parameters} \\
\begin{array}{|c|c|c|c|}
\hline
\text{Figure} & s & \text{Prescription for } k_{0i} & \Phi & \text{Multiplier to } U_p \\
\hline
14 & 2 & \text{Varies} & 0 & 1 \\
15 & \text{Varies} & \chi_0 = 1/R & 0 & 1 \\
16(a) & 2 & \chi_0 = 1/R & \text{Varies} & 1 \\
16(b) & 2 & \chi_0 = 1/R & 10 & \text{Varies} \\
17 & 2 & \chi_0 = 1/R & 10 & \text{Varies} \\
\hline
\end{array}
\end{align*} \]

where \( s = p, e \) denotes the particle type of interest. For now, we ignore differences between parallel and perpendicular heating and only compute the summed heating rate \( Q_s = Q_p + Q_e \). In order to perform the wavenumber integration in Equation (62), we constructed two-dimensional numerical grids of \( \gamma_p \) and \( \gamma_e \) for values of \( 10^{-3} \Omega_p/V_A \leq k \parallel \leq k_{\text{max}} \) and \( 10^{-3} \leq k \perp \rho_p \leq 10^3 \). We used 200 points in \( k \parallel \) and 100 points in \( k \perp \), and we constructed a total of 14 grids for values of \( \beta \) ranging from \( 10^{-3} \) to \( 22 \) (with \( \beta \) varying logarithmically with three samples per decade). Linear interpolation was used to evaluate the damping rates at values of \( k \parallel, k \perp, \text{ and } \beta \) between the discrete grid points. We assumed that the ratios \( \gamma_p/\omega_r \) and \( \gamma_e/\omega_r \) remain constant as one extrapolates into the weakly damped regions defined by \( k \perp \rho_p < 10^{-3} \) and \( k \parallel V_A/\Omega_p < 10^{-3} \).

To estimate the heating rates experienced by heavy ions, we assume that most low-abundance ions do not have a significant effect on the overall wave dispersion relation. This allows us to use an “optically thin” resonance condition for the ion cyclotron wave–particle interaction (Cranmer 2000), which results in a perpendicular heating rate

\[ Q_{\perp} \approx \frac{\pi \Omega_p^2}{V_A} \left( 1 - \frac{Z_i}{A_i} \right) \int d^3 k \ E_A(k) \delta(k \parallel - \Omega_i/V_A), \]

(63)

where \( Z_i \) and \( A_i \) are the ion charge and mass in proton units (see also Cranmer 2001; Tu & Marsch 2001; Landi & Cranmer 2009). The Dirac delta function extracts a one-dimensional “strip” of the power spectrum that is in resonance with the ion Larmor motions at \( \omega_r \approx k \parallel V_A = \Omega_i \). Thus, Equation (63) can be evaluated with just a single integration along the \( k \parallel \) direction.

6. RESULTS FOR COLLISIONLESS PARTICLE HEATING

Here we present results for \( Q_p/Q_e \), the ratio of proton to electron heating rates, computed from Equation (62) with various assumptions for the shape of the turbulent Alfvén wave spectrum \( E_A(k \parallel, k \perp) \). Figures 14 and 15 show how this ratio behaves for pure “uncoupled” Alfvén waves, and Figure 16 summarizes the outcome of coupling the Alfvén and fast-mode waves as discussed in Section 4. Table 2 summarizes the specific values of cascade and coupling parameters that were assumed in each of these plots.

In Figure 14 we show the radial dependence of \( Q_p/Q_e \) for various methods of computing the outer-scale parallel wavenumber \( k_{0i} \). In all panels, the turbulence spectra were computed with constant values of \( s = 2 \) and \( \Phi = 0 \), as well as the other default parameter choices discussed in Section 3.1. Figure 14(a) assumes a range of radially constant wave frequencies which determine \( k_{0i} \) from Equation (43). Figure 14(b) applies the Goldreich & Sridhar (1995) conditions of critical balance for both zero and nonzero cross helicity at the outer scale; see Equations (44) and (45).

Figure 14(c) shows the relative heating rates \( Q_p/Q_e \) for a range of constant ratios \( k_{0i}/k_{0\perp} \). At the coronal base (\( z = 0.01 R_\odot \)), note that \( Q_p/Q_e \) behaves non-monotonically as a function of this wavenumber anisotropy ratio. The minimum value of \( Q_p/Q_e \) occurs at \( k_{0i}/k_{0\perp} \approx 0.55 \). The non-monotonic behavior occurs because of two competing effects. At large values of \( k_{0i} \), the weak-turbulence critical balance curve (\( X_0 = 1 \)) begins to approach the ion cyclotron frequencies. This has the
result of increasing \( Q_p \) while leaving \( Q_e \) unchanged. However, when \( k_0 \) becomes very small, the wave power becomes concentrated into narrower “cones” that provide more energy to the KAWs. This has the result of increasing both \( Q_p \) and \( Q_e \), but the smaller rate \( Q_p \) receives a larger fractional change.

Each panel of Figure 14 also shows the empirically determined range of \( Q_p/Q_e \) ratios from the \textit{Helios} and \textit{Ulysses} measurements described by Cranmer et al. (2009). The plotted error range of \( \pm 0.3 \) in \( \log(Q_p/Q_e) \) accounts for both modeling and observational uncertainties. Also, we show the theoretical prediction for \( Q_p/Q_e \) from the gyrokinetic model of Howes (2010) as a dashed black curve. As discussed by Howes (2011), this model agrees well with the Cranmer et al. (2009) measurements at \( r \gtrsim 200 R_{\odot} \), but underestimates the proton heating at \( r \lesssim 100 R_{\odot} \). The Howes (2010) gyrokinetic model includes the same sources of high-\( k_\perp \) KAW damping that we use, but not the high-\( k_\parallel \) sources of ion cyclotron damping. In Figure 14, we find that the best agreement with the Cranmer et al. (2009) measured ratio comes from the model that assumes critical balance with the Beresnyak & Lazarian (2008, 2009) modification for nonzero cross helicity; i.e., \( x_0 \approx 1/R \).

In Figure 15 we vary the ratio \( s \) used in the Alfvénic parallel cascade function \( g(x) \); see Equation (C14). We retain the \( x_0 \approx 1/R \) approximation for \( k_0 \) that was found to be an optimal choice for agreement with observations at \( r \gtrsim 60 R_{\odot} \). For lower heights in the low-\( \beta \) corona, we find that large values of \( s \) give insufficient wave power at the ion cyclotron resonant values of \( k_\parallel \) to provide significant energy to the protons. One would need to specify \( s \lesssim 0.5 \) in order for there to be enough high-\( k_\parallel \) power to give protons a substantial fraction of the dissipated energy. Cranmer & van Ballegooijen (2003) and Landi & Cranmer (2009) came to this same essential conclusion. Although there are still no firm experimental or theoretical bounds on the expected value of \( s \) in MHD turbulence, it is generally believed that values as low as \( s \lesssim 0.5 \) are unrealistic.

Figure 16 shows the results of mode coupling between the Alfvén and fast-mode fluctuations. The curves in Figure 16(a) were computed for a range of constant values of the coupling constant \( \Phi \) from \( 10^{-6} \) to \( 10^{3} \). At large distances (\( r \gtrsim 0.3 \) AU), it is clear that the presence or absence of coupling has very little effect on the \( Q_p/Q_e \) ratio. This insensitivity occurs because much of the proton heating at intermediate and high values of \( \beta \) comes from the Landau and transit-time damping of KAWs. The low-\( k_\perp \) high-\( k_\parallel \) part of the \( E_\parallel \) spectrum is there no matter the value of \( \Phi \), and it dominates the proton and electron heating in this case. The results are similar to those of Howes (2010, 2011) who did not include mode coupling.

In the low-\( \beta \) corona, Figure 16 indicates that \( \Phi \) needs to be at least of order unity to excite sufficient power in high-\( k_\parallel \) ion
cylotron waves to heat protons on par with the electrons (i.e., $Q_p/Q_e \sim 1$). For low values of $\Phi$, the plotted ratio undergoes several increases and decreases as a function of radius that we cannot trace to any one simple cause. The local maximum that appears at $z \approx 0.5 R_\odot$ corresponds to the local minimum in plasma $\beta$ (see Figure 1). In the low-\(\beta\) regime, it is likely that the relative “competition” between mode coupling, transit-time damping (for $E_F$), and ion cyclotron damping (for $E_\lambda$) undergoes numerous reversals as a function of radius.

In Figure 16(b) we fix the coupling constant at $\Phi = 10$, which is of the same order of magnitude as predicted by Chandran (2005), and we vary the normalization of the fast-mode wave power. It was evident from Figure 4 that small changes in the large-scale wave transport properties could give rise to large changes in the fast-mode power in much of the corona and solar wind. Thus, we take the standard model for $U_F(r)$ and multiply it by constant factors ranging from $10^{-3}$ to $10^{2}$. We note, however, that we do not have excessive freedom to increase the $U_F$ normalization too far above the standard model. A significantly higher coronal population of fast-mode waves would contribute to a larger $v_\perp$ that may exceed the observational constraints shown in Figure 3(a). Nonetheless, Figure 16(b) shows that the standard model ends up being a reasonable solution that matches the observed in situ heating ratio (Cranmer et al. 2009) and also gives appreciable proton heating in the extended corona (as required qualitatively from UVCS proton temperature measurements); see Cranmer & van Ballegooijen (2003).

An example calculation of preferential heavy ion heating is shown in Figure 17. The ion used for the model was O$^{+5}$, whose properties have been measured in the corona from emission in the O vi 1032, 1037 Å spectral line doublet (Kohl et al. 2006). We used the parameters corresponding to the best agreement with observational constraints on $Q_p/Q_e$ (see Table 2). We then adjusted the fast-mode wave power $U_F(r)$ by changing the multiplicative constant that was varied in Figure 16(b). As in Figure 16(b), values of this multiplicative constant between about 1 and 10 appear to bracket the observational constraints.

The plotted ranges for the observationally determined $Q_{i\perp}$ rates were derived by combining observations from both the UVCS (Cranmer et al. 1999) and SUMER (Landi & Cranmer 2009) instruments on SOHO with semi-empirical solutions of the perpendicular internal energy conservation equations. These heating rates were not given explicitly by either Cranmer et al. (1999) or Landi & Cranmer (2009), but they were computed and saved from the models that produced agreement with the observed radial behavior of $T_{i\perp}$. The SUMER and UVCS data were obtained for off-limb measurements of O vi emission, in which the line widths are primary diagnostics of $T_{i\perp}$. Note that the radial dependence of the two observationally determined regions is similar to that in the plotted model curves. However, the SUMER data correspond to about a factor of 10 higher fast-mode wave power normalization than the UVCS data.

If the postulated mode-coupling explanation for ion cyclotron proton/ion heating is correct, then the results given in Figures 16 and 17 constrain the required levels of fast-mode wave power. In the low corona ($z \lesssim 0.1 R_\odot$), there may need to be up to a factor of 10 higher value of $U_F$ than in the standard model of Section 2, but in the extended corona and heliosphere the standard model may be close to correct. Of course, it is only the high-$k_\parallel$ tail of the fast-mode spectrum that matters to the calculation of available Alfvénic power at the ion cyclotron resonances, not its outer-scale normalization. Therefore, it is possible that $U_F$ may depart significantly from the values predicted by the standard model of Section 2, but still produce agreement with the various observations by having different values for the spectral slope and angle dependence of $E_F(k)$.

7. DISCUSSION AND CONCLUSIONS

The aim of this paper was to explore the consequences of Chandran’s (2005) conjecture that nonlinear couplings between Alfvén and fast-mode waves may produce sufficient ion cyclotron wave power to heat protons and heavy ions in the corona. To test this idea, we constructed a semi-empirical model of the background plasma and MHD wave properties in a flux tube connected to a polar coronal hole. For the sake of practicality, we utilized several approximations when solving the wave energy transport equations for the energy densities of Alfvén, fast, and slow modes.

1. The equations themselves were adapted from standard WKB “wave action conservation” theory, which does not take account of the effects of linear wave reflection in a fully self-consistent manner. We also assumed the associated WKB limiting case of equipartition between the kinetic and magnetic energy densities for the dominant Alfvén waves (i.e., $K_v = M_v$). Roughly speaking, these approximations are consistent with an assumption that the wave frequencies are higher than $\sim 10^{-3}$ Hz in the corona. However, it has also been shown that the radial behavior of Alfvénic wave power in the solar wind is never far from the predictions of WKB theory even in the heliosphere where reflection is not negligible (Zank et al. 1996; Cranmer & van Ballegooijen 2005).

2. Because of other evidence that the dominant inertial-frame frequencies in coronal MHD turbulence may be lower than...
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Although the effects of removing these approximations should be investigated further, we do not believe their use invalidates the results of the wave transport models presented above.

With the above caveats taken into account, we produced a standard model of the Alfvén, fast-mode, and slow-mode energy densities between 0.01 and 1000 $R_\odot$ above the solar photosphere. In agreement with earlier results, we found that slow-mode MHD waves of solar origin probably cannot survive into the extended corona. In addition, we found that the amplitudes of fast-mode waves at large distances are more sensitive to the assumed model parameters than are the amplitudes of Alfvén waves. For this reason, the standard model of fast-mode wave energy density was treated as a representative example and not a definitive prediction. Thus, other reasonable models of the available fast-mode power can be obtained by multiplying or dividing the standard model’s energy density by factors of order 10–100 without sacrificing too much realism.

At each radial distance, we simulated the time-steady wavenumber power spectra of Alfvénic and fast-mode turbulent fluctuations. We included the effects of nonlinear coupling and collisionless kinetic wave dissipation. We also computed the time-steady heating rates for protons, electrons, and a representative minor ion species (O$^+$) for comparison with observational constraints. The resulting heating rates for the standard model of fast-mode wave power were found to provide both substantial constraints. The resulting heating rates for the standard model’s assumed fast-mode wave energy density may not exceed values of order 10–100 without sacrificing too much realism.

To make further progress with the proposed set of ideas, it will be important to better understand the origin of the fast, slow, and Alfvén waves in the solar photosphere and chromosphere. Hollweg (1978a), Spruit (1981), and others studied the wavelike oscillations induced by convective jostling in small-scale flux tubes that extend up into the chromosphere. However, once waves reach the sharp and “corrugated” TR boundary, they can undergo reflection, refraction, and multiple types of mode conversion (Hollweg 1978b; Bogdan et al. 2002; Hasan & van Ballegooijen 2008; Fedun et al. 2011; Cally & Hansen 2011). The types and strengths of MHD waves that survive the chaotic lower atmosphere probably also depend on the nature of the region underlying the solar wind flux tubes of interest (i.e., coronal hole, active region, or quiet loops).

Future work must also involve more physical realism for the model of turbulent cascade. Replacing our hodge-podge collection of analytic solutions with a fully self-consistent numerical simulation is an obvious priority. A key part of this improvement will be to remove the assumption of scale separation that prevents different radial zones from interacting with one another in wavenumber space (see, e.g., Verdi et al. 2009). In addition, we note that the advection–diffusion terms in Equations (31) and (32) contain the limiting assumption that the spectral transfer is “local” in $k$-space. It has been shown that true MHD turbulence is not so local because of intermittent high-order wave–wave interactions and nonlinear steepening effects (e.g., Medvedev 2000; Chandran 2008b; Cho 2010; Howes et al. 2011). We also assumed energy equipartition between the $v_\perp$ and $b_\perp$ spectra in the MHD inertial range, but in situ measurements show that not to be the case in actual solar wind turbulence (Grappin et al. 1983; Wang et al. 2011).

We also intend to improve upon the kinetic treatment of collisionless particle heating described in Section 5. We assumed isotropic Maxwellian velocity distributions when solving for the linear damping rates, but Bashir et al. (2010) showed how non-Maxwellian temperature anisotropies can significantly affect the KAW dispersion relation. The ultimate rate of electron heating from KAW Landau damping can also be affected by nonlinearity and Coulomb collision effects that we did not include (e.g., Borovsky & Gary 2011). The time evolution of proton and ion velocity distributions, under the influence of cyclotron resonant heating, is also decidedly non-Maxwellian (Galinsky & Shevchenko 2000; Isenberg 2001; Cranmer 2001; Isenberg & Vasquez 2009, 2011).

Finally, we emphasize that the proposed idea of nonlinear coupling between Alfvén and fast-mode waves is only one proposed solution to the problem of preferential proton/ion heating. Some of the other suggested explanations were listed briefly in Section 1. One recent example that has received significant attention is the stochastic energization of protons and ions that occurs when KAW amplitudes become sufficiently high (Johnson & Cheng 2001; Chandran 2010; Chandran et al. 2011). To excite this proposed stochasticity, the dimensionless ratio $v_\perp/c_s$ (evaluated at $k_z R_\odot = 1$) should exceed values of order 0.1. However, in this paper’s standard model of Alfvénic fluctuations (either with or without nonlinear couplings), this ratio never exceeds a value of 0.003. The main factor responsible for this dramatic mismatch is our assumption of the Goldreich & Sridhar (1995) scaling in the limit of strong turbulence (i.e., $v_\perp \propto k_z^{-1/3}$). Alternative theories of the strong Alfvénic cascade (e.g., Boldyrev 2006; Podesta 2011) give a shallower dependence of $v_\perp \propto k_z^{-1/4}$. This would allow larger values of $v_\perp$ to survive to the onset of KAW dispersion at $k_z \rho_p \approx 1$. We
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await improved theoretical descriptions of MHD turbulence and conclusive empirical tests of such models.

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APPENDIX A

HEURISTIC OVERVIEW OF MHD TURBULENCE

The cascade of energy from large to small eddies was first described in the context of isotropic hydrodynamic turbulence (von Kármán & Howarth 1938; Kolmogorov 1941; Obukhov 1941; Batchelor 1953). The spectral transport timescale for energy to be transferred down to the next order of magnitude of eddy size is estimated generally as \( \tau_e \approx (kV)\tau \), where \( k \) is the magnitude of the local wavevector \( \mathbf{k} \) and \( V \) is the local eddy velocity at this value of \( k \). For isotropic fluctuations that depend only on \( k \) and not its direction, we can define the reduced one-dimensional spectrum \( e_m(k) = v^2 / k \). Thus, since

\[
\frac{U_m}{\rho_0} = \int dk \ e_m(k), \tag{A1}
\]

we relate the eddy velocity to the full three-dimensional spectrum via \( v^2 = 4\pi k^2 E_m \). The cascade rate is estimated as \( \varepsilon \sim v^2 / \tau_e \). Assuming that \( \varepsilon \) is constant in the inertial range leads to the steady Kolmogorov–Obukhov spectrum \( e_m \propto k^{-5/3} \), or \( E_m \propto k^{-11/3} \).

When the background magnetic field becomes strong, other physical processes become important. Iroshnikov (1963) and Kraichnan (1965) (hereafter IK) realized that the “eddy” description of hydrodynamic turbulence could be generalized by referring to colliding MHD wave packets, and that the Alfvén speed \( V_A \) introduces a new absolute scale into the problem. If one continues to treat the cascade isotropically in \( k \)-space, a more generalized spectral transport time can be defined as

\[
\tau_s = \frac{1}{kv} \left( \frac{V_A}{v} \right)^p , \tag{A2}
\]

where \( p = 0 \) gives the Kolmogorov–Obukhov limit and \( p = 1 \) is the result of the IK analysis. Using the same assumption above that \( \varepsilon \) is constant, we obtain a more general one-dimensional power spectrum \( e_m \propto k^{-(p+5)/(p+3)} \). For the IK value of \( p = 1 \), the spectrum is \( e_m \propto k^{-3/2} \) (see also Boldyrev 2005).

It has been known for several decades that a cascade of Alfvén-wave-like fluctuations does not lead to an isotropic distribution of power in wavenumber space (Strauss 1976; Montgomery & Turner 1981; Shebalin et al. 1983; Higdon 1984). The dominant energy cascade takes place mainly in the two-dimensional plane perpendicular to the background field. For the Alfvénic fluctuations, we can define the local eddy velocity as \( v_{\perp} \) being mainly a function of \( k_{\perp} \). The one-dimensional spectrum in this case is given by \( e_{\perp} = v^2_{\perp} / k_{\perp} \) and the integration over wavenumber space is best done in cylindrical coordinates with

\[
\frac{U_A}{2\pi \rho_0} = \int dk_\perp \int dk_\parallel k_\parallel E_A = \int dk_\perp e_A. \tag{A3}
\]

Taking into account the spectral anisotropy \( (k_1 \neq k_2) \) we can also write an even more general perpendicular transport time for the Alfvén waves as

\[
\tau_A = \frac{1}{k_\perp v_\perp} \left( \frac{V_A}{v_{\perp}} \right)^p \left( \frac{k_1}{k_\perp} \right)^q . \tag{A4}
\]

A perpendicular generalization of the IK model is given by \( p = 1 \) and \( q = 0 \), which gives \( e_{\perp} \propto k^{-3/2} \) (see also Nakayama 1999, 2001; Boldyrev 2006; Podesta 2011). Weak three-wave couplings have been shown to give rise to the case \( p = q = 1 \), which yields \( e_{\perp} \propto k^{-5/3} \) (e.g., Gal´erit et al. 2000; Bhattacharjee & Ng 2001; Boldyrev & Perez 2009). However, in that case nonlinear effects grow in magnitude as \( k_{\perp} \) gets larger, so it is generally believed that a weakly turbulent inertial range must eventually become strongly turbulent (see also Goldreich & Sridhar 1997).

Goldreich & Sridhar (1995) described strong Alfvénic turbulence with a spectral transfer time given by \( p = q = 0 \), and thus \( e_{\perp} \propto k^{-5/3} \) reminiscent of the original Kolmogorov–Obukhov model. In this case of strong mixing between the turbulent motions (perpendicular to the field) and the flow of Alfvén wave packets (parallel to the field) there is a so-called critical balance that couples \( k_{\perp} \) and \( k_\parallel \) to one another. We define a critical balance parameter

\[
\chi \approx \frac{k_{\perp} V_A}{k_\perp v_{\perp}} , \tag{A5}
\]

such that the Goldreich & Sridhar (1995) strong cascade is consistent with the condition \( \chi \approx 1 \). Combining this with the velocity scaling \( v_{\perp} \propto k^{-1/3} \) yields the wavenumber anisotropy scaling \( k_{\perp} \propto k_\parallel^{2/3} \). Note that assuming \( p = q = 0 \) in Equation (A4) is equivalent to \( \tau_A \) being given by \( \chi^{p/q} / (k_{\perp} v_{\perp}) \); see also Gal´erit et al. (2005). An alternate way of describing the cascade was given by Zhou & Matthaeus (1990b), who defined a triple correlation timescale equivalent to

\[
\tau_A \approx 1 + \frac{\chi}{k_\perp v_{\perp}} . \tag{A6}
\]

This expression naturally bridges the strong \( (\chi \lesssim 1) \) and weak \( (\chi \gg 1) \) turbulence scaling limits, and we use a similar relation in Section 3.1.

The cascade of compressible fast-mode waves has received less attention than that of the incompressible Alfvén waves. Because fast-mode waves propagate at a roughly constant phase speed no matter the direction angle \( \theta \), the fast-mode cascade has been suspected to resemble isotropic hydrodynamic turbulence. In fact, numerical simulations do tend to find that fast-mode waves produce a more isotropic spectrum than do Alfvén waves (Cho & Lazarian 2003; Svidzinski et al. 2009).\(^4\) The rate of the cascade is generally assumed to follow the weak IK-type scaling of Equation (A2) with \( p = 1 \) (see, e.g., Chandran 2005; Suzuki et al. 2007). Thus, because in most cases we expect \( v_{\perp} \ll V_A \), the fast-mode cascade timescale \( \tau_F \) is likely to be significantly longer than the Alfvénic timescale \( \tau_A \).

It is important to emphasize that there is still no agreement concerning the most realistic and universal way to describe MHD turbulence. There remains controversy about the applicability of the various power-law exponents (especially 5/3 versus

\(^4\) This is generally valid in the ideal MHD range, at which \( \omega \ll \Omega_p \). We ignore the large literature of “whistler turbulence,” in which dispersive effects may lead to wavenumber anisotropy at higher frequencies \( \omega \gg \Omega_p \).
3/2) for the Alfvénic inertial range (Beresnyak 2011; Forman et al. 2011; Mason et al. 2011; Podesta 2011). Simulations have not been able to accurately pin down the amount of slow “leakage” of power to the high-\(k_\perp\) region of the spectrum where \(\chi \gg 1\). Furthermore, the observed steepening of the spectrum at high values of \(k_\perp\) is still not well understood (Leamon et al. 1998; Stawicki et al. 2001; Howes et al. 2008). In many models, the precise scalings depend on the degree of cross helicity of the fluctuations (i.e., on the imbalance between \(Z_+\) and \(Z_-\)) and on whether the turbulence is driven or decaying (e.g., Lithwick et al. 2007; Chandran 2008b; Chen et al. 2011). In this paper, we attempt to identify the most controversial aspects of the models and discuss how they can be modified once such issues are resolved.

**APPENDIX B**

**LINEAR DAMPING RATES: COLLISIONAL AND COLLISIONLESS**

Alfvén (1947) and Osterbrock (1961) first proposed that MHD waves in the solar atmosphere could be damped by collisional processes. These processes include viscosity, thermal conductivity, electrical resistivity (i.e., Joule or Ohmic dissipation), and ion–neutral friction. In the fully collisional regime we make use of the basic expressions derived by Braginskii (1965). Here we describe the total linear damping rate for MHD wave mode \(m\) by a sum of three components,

\[
\gamma_m = \gamma_{vis,m} + \gamma_{ohm,m} + \gamma_{con,m},
\]

where \(\gamma_{vis,m}\) denotes damping due to kinematic viscosity, \(\gamma_{ohm,m}\) denotes electrical resistivity, and \(\gamma_{con,m}\) denotes thermal conductivity. Since our main goal is model to the wave damping in the (almost completely ionized) corona and solar wind, we ignore ion–neutral friction. For Alfvén waves,

\[
\gamma_{vis,A} = \frac{1}{\rho_0} \left( \eta_1 k^2_\parallel + \eta_2 k^2_\perp \right) \quad (B2)
\]

\[
\gamma_{ohm,A} = \left( \frac{c^2}{4\pi \sigma_\parallel} \right) k^2_\parallel + \left( \frac{c^2}{4\pi \sigma_\perp} \right) k^2_\perp \quad (B3)
\]

\[
\gamma_{con,A} = 0. \quad (B4)
\]

For fast- and slow-mode waves \((m = F, S)\), we note that the damping rates given explicitly by Braginskii (1965) are valid only in the \(\beta \ll 1\) limit. The expressions given here are appropriate for arbitrary values of \(\beta\), but we made the assumption that \(k_\parallel \approx k_\perp\). In other words, for the assumed isotropic distribution of fast and slow wavevectors, the damping rates depend only on the magnitude \(k^2 = k^2_\parallel + k^2_\perp\). With that caveat, the damping rates are given by

\[
\gamma_{vis,m} = \frac{2k^2}{\rho_0} \left[ \eta_0 \left( 4f_{ex} - 4f_{ex} + f_{ex} + f_{sx} \right) + \eta_1 f_{sx} \right]
\]

\[
+ \eta_2 \left( f_{sx} + 2f_{sx} + f_{ex} \right) \quad (B5)
\]

\[
\gamma_{ohm,m} = \frac{c^2 k^2 f_B}{4\pi \sigma_\parallel} \quad (B6)
\]

\[
\gamma_{con,m} = \frac{4(\gamma - 1)^2 k_B T}{\rho_0 c^2} f_B k^2 (\kappa_1 + \kappa_\perp), \quad (B7)
\]

where the fractions \(f\) specify the energy partition fractions of Section 2.2. Specifically, \(f_{ex} = \Theta / U_m\), \(f_B = (M_e + M_i) / U_m\), \(f_{sx} = K_e / U_m\), \(f_{ux} = K_u / U_m\), and \(f_{sz} = (f_{ux} f_{uz})^{1/2}\). We assume that protons dominate other ion species in the viscosity and thermal conductivity terms, and that electrons dominate the electrical resistivity terms (see also Tu 1984; Whang 1997; Campos 1999).

We use the Braginskii (1965) expressions for the transport coefficients in the fully collisional limit. These coefficients depend on the proton and electron Coulomb collision timescales (e.g., Spitzer 1962),

\[
\tau_p = \frac{3}{4} \sqrt{\frac{m_p}{\pi e^2 n_p} \ln \Lambda} \quad (B8)
\]

\[
\tau_e = \frac{3}{4} \sqrt{\frac{m_e}{2\pi e^2 n_p} \ln \Lambda} \quad (B9)
\]

where we approximate the Coulomb logarithm in the coronal regime of temperatures and densities by

\[
\ln \Lambda = 3.2 + \left( \frac{2}{3} \ln \left( \frac{T_e}{10^6 K} \right) - \frac{1}{2} \ln \left( \frac{n_e}{10^6 \text{ cm}^{-3}} \right) \right). \quad (B10)
\]

We also specify the magnitudes of the proton and electron gyrofrequencies,

\[
\Omega_p = \frac{e B_0}{m_p c}, \quad \Omega_e = \frac{e B_0}{m_e c} \quad (B11)
\]

and the dimensionless products

\[
x_p = \tau_p \Omega_p, \quad x_e = \tau_e \Omega_e. \quad (B12)
\]

Thus, the proton viscosity coefficients are given by

\[
\eta_0 = 0.96 n_p k_B T_p \tau_p, \quad \eta_1 = 2 x_p \eta_2 \quad (B13)
\]

\[
\eta_2 = n_p k_B T_p \tau_p \left( \frac{1.2 \chi_p^2 + 2.23}{x_p^4 + 4.03 x_p^2 + 2.33} \right). \quad (B14)
\]

The electrical conductivities are given by

\[
\sigma_1 = \frac{1.95 e^2 n_e \tau_e}{m_e} \quad (B15)
\]

\[
\sigma_{\perp} = \frac{e^2 n_e \tau_e}{m_e} \left( 1 - \frac{6.416 \chi_p^2 + 1.837}{x_p^4 + 14.79 \chi_p^2 + 3.7703} \right)^{-1}. \quad (B16)
\]

The thermal conductivities are given by

\[
\kappa_1 = \frac{3.906 n_p k_B T_p \tau_p}{m_p} \quad (B17)
\]

\[
\kappa_{\perp} = \frac{n_p k_B T_p \tau_p}{m_p} \left( \frac{2 \chi_p^2 + 2.645}{x_p^4 + 2.70 \chi_p^2 + 0.677} \right). \quad (B18)
\]

Finally, we need to take account of the transition from collisional to collisionless wave damping. In the low-density limit of the classical Braginskii (1965) expressions, some of the transport coefficients (e.g., \(\eta_0, \eta_1, \kappa_1\)) become infinitely large as the mean time between collisions becomes infinite. This “molasses limit” has been recognized to be unphysical.
the unmodified Braginskii (1965) rates. For heights greater than
z ≈ 1 R⊙, however, the rates multiplied by C become about two
orders of magnitude smaller than the unmodified classical rates.

APPENDIX C

ANALYTIC SOLUTIONS TO ADVECTION–DIFFUSION
PROBLEMS IN LIMITED PARAMETER REGIMES

C.1. Alfvén Waves: Cascade and Source Terms

Equation (38) is a reduced one-dimensional version of the full
advection–diffusion equation for Alfvénic fluctuations. The
Appendix of Cranmer & van Ballegooijen (2003) presented
one method of solving this equation in the low-wavenumber,
strong turbulence (χ0 ≪ 1) limit. Here we derive a more
general case for arbitrary χ0. Ignoring both wave damping and
mode coupling, and assuming a steady state (i.e., ∂b⊥/∂t = 0),
Equation (38) can be simplified to

$$\frac{\partial \varepsilon}{\partial x} = \tilde{S}_A,$$

where here we define x = ln k⊥ and we write the cascade rate as

$$\varepsilon = \frac{1}{\tau_A} \left( \mu_\perp b_\perp^2 - \alpha_\perp \frac{\partial b_\perp^2}{\partial x} \right)$$

and the macroscopic expansion timescale for waves is estimated as

$$\tau_{\text{esc}} \approx \frac{\rho_0}{(u + V_A) \left| \partial \rho_0 / \partial x \right|}.$$  

For strong collisions, C ≈ 1 and the Braginskii (1965) expressions
are valid. For weak collisions, C ≈ τesc/τp ≪ 1 and the
damping rates are quenched.

Figure 18 illustrates how the components of the wave damp-
ing rates vary with radial distance in the model of the fast solar
wind described in Section 2. For the fast- and slow-mode waves,
the viscous and conductive damping terms are of roughly com-
parable strength, but for the fast mode the conductive damping
wins out at large distances (β ≫ 1). The viscous term is most
important for the Alfvén mode, but its magnitude remains small
in comparison to the dominant terms for fast- and slow-mode
damping. At the heights displayed here, Ohmic dissipation never
appears to be important in comparison to the other terms. This
situation is reversed, however, lower down in the chromosphere
(see, e.g., Khodachenko et al. 2004). The curves in Figure 18
are shown for the general case of the transition to a collisionless
plasma (i.e., with all rates multiplied by C). For z ≲ 0.1 R⊙
in the low corona, C ≈ 1 and the general rates are identical to
the unmodified Braginskii (1965) rates. For heights greater than

Figure 18. Linear collisional damping rates for MHD waves. Color denotes
the physical dissipation process: viscosity (black), electrical resistivity (red),
and thermal conductivity (blue). Line style denotes the wave mode: Alfvén
(solid curves), fast mode (dashed curves), and slow mode (dotted curves). All
quantities are plotted as base-10 logarithms of the rates, in units of s−1, for the
standard model with parameters listed in Table 1.

(A color version of this figure is available in the online journal.)

(see Williams 1995; Cranmer & van Ballegooijen 2005). Thus,
we derived a simplified version of the general expressions of
Chang & Callen (1992) and Ji et al. (2009) to describe what
happens when collisions become infrequent. We computed the γ
dissipation rates as above, but then we multiplied them all by
the following dimensionless factor C, where

$$C = \frac{\tau_{\text{esc}}}{\tau_{\text{esc}} + \tau_p}.$$  

and the macroscopic expansion timescale for waves is estimated
as

$$\tau_{\text{esc}} \approx \frac{\rho_0}{(u + V_A) \left| \partial \rho_0 / \partial x \right|}.$$  

For strong collisions, C ≈ 1 and the Braginskii (1965) expressions
are valid. For weak collisions, C ≈ τesc/τp ≪ 1 and the
damping rates are quenched.

Figure 18 illustrates how the components of the wave damp-
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wind described in Section 2. For the fast- and slow-mode waves,
the viscous and conductive damping terms are of roughly com-
parable strength, but for the fast mode the conductive damping
wins out at large distances (β ≫ 1). The viscous term is most
important for the Alfvén mode, but its magnitude remains small
in comparison to the dominant terms for fast- and slow-mode
damping. At the heights displayed here, Ohmic dissipation never
appears to be important in comparison to the other terms. This
situation is reversed, however, lower down in the chromosphere
(see, e.g., Khodachenko et al. 2004). The curves in Figure 18
are shown for the general case of the transition to a collisionless
plasma (i.e., with all rates multiplied by C). For z ≲ 0.1 R⊙
in the low corona, C ≈ 1 and the general rates are identical to
the unmodified Braginskii (1965) rates. For heights greater than
In practice, we integrate this equation numerically and use the definition of $q$ to obtain $b_\perp(k_\perp)$. In the energy containing range ($x \ll x_0$), we see that $\varepsilon \to 0$, and thus $q$ is constant and $b_\perp^2 \propto k_\perp^2$. The low-$k_\perp$ region of wavenumber space stands in contrast to the inertial range because here the shape of the fluctuation spectrum does depend on the value of $s$.

In the MHD strong-turbulence inertial range (where $s \approx s_0$), we can use Equation (C2) to write the dissipation term on the right-hand side of Equation (C8) as

$$b_\perp^2 \approx \frac{\varepsilon}{\mu_\perp k_\perp v_\perp}.$$  

(C9)

if we also assume $x_0 \ll 1$ in the high-$k_\perp$ limit. To retain the most generality in cases when $s$ is not infinitely large, we can use Equation (41) to replace $\mu_\perp$ by $\mu_\perp = \mu_\perp + 2\alpha_\perp / 3$. This may not be completely accurate for the cases of weakest advection (i.e., $s \approx 0$), but it is an improvement on ignoring the influence of the $\alpha_\perp$ diffusion term altogether.

To simplify the modified transport equation, we take a further cue from Howes et al. (2008) and use the critical balance condition $\omega \approx k_\perp v_\perp$ to rewrite the equation as

$$\frac{k_\perp}{\varepsilon} \frac{\partial \varepsilon}{\partial k_\perp} = -\frac{2}{\mu_\perp} \left( \frac{\tilde{\gamma}}{\omega} \right)_A,$$

(C10)

where the ratio $\left( \tilde{\gamma}/\omega \right)_A$ is the output of the Vlasov–Maxwell dispersion analysis discussed in Section 5. For the KAW domain, this ratio is largely independent of $k_\perp$ and thus it can be treated as a function of $k_\perp$ only. When we solve this equation numerically, we start the integration at a low enough value of $k_\perp$ that the damping is negligibly small (i.e., at which $\varepsilon = \varepsilon_0$). Thus, we integrate upward in $k_\perp$ with

$$\varepsilon = \varepsilon_0 \exp \left[ -\frac{2}{\mu_\perp} \int \frac{dk_\perp}{k_\perp} \left( \frac{\tilde{\gamma}}{\omega} \right)_A \right].$$  

(C11)

Finally, the damped solution for $\varepsilon(k_\perp)$ is used in Equation (C6) to obtain the damped power spectrum.

C.3. Alfvén Waves: Coupled Parallel and Perpendicular Transport

The previous sections described the cascade as a function of $k_\perp$ and ignored the behavior of the full power spectrum $E_A(k_\perp, k_\|)$. To first order, the strong predicted anisotropy of MHD turbulence justifies this approach, but we are also concerned with the possible leakage of power to high values of $k_\perp$ and thus to high frequencies. Here we mainly follow the analysis of Cranmer & van Ballegooijen (2003), but we also include the possible effects of weak turbulence when $x_0 \gg 1$. Goldreich & Sridhar (1995) wrote the full power spectrum as a separable function of two variables, $k_\perp$ and $\chi$, with

$$E_A(k_\perp, k_\|) = \frac{V_A b_\perp(k_\perp)}{k_\perp} g(\chi)$$  

(C12)

and $\chi = k_\| V_A / (k_\perp b_\perp)$. This definition allows the dimensionless function $g(\chi)$ to be normalized to unity,

$$\int_{-\infty}^{\infty} d\chi g(\chi) = 1,$$

(C13)

but in practice we usually calculate the normalization for $g(\chi)$ from the condition that the total power over all wavenumber space integrates properly to $U_A$.

It has been known for some time that the dominant contribution to the integral in Equation (C13) should come from the region where $|\chi| \lesssim 1$. For values of $k_\|$ at which $|\chi| \lesssim 1$, the Goldreich & Sridhar (1995) solution for $b_\perp \propto k_\perp^{-1/3}$ gives a dominant perpendicular dependence for the inertial range of $E_A \propto k_\perp^{-10/3}$. We also expect $g(\chi)$ to grow negligibly small for $|\chi| \gg 1$, and thus for these large-$k_\perp$ regions of wavenumber space there should be very little Alfvénic wave power. Cho et al. (2002) found that numerical simulations of anisotropic MHD turbulence were consistent with $g(\chi)$ being fitted reasonably well with either a simple exponential function ($g \sim e^{-n\chi}$) or a Castaing function (a convolution of multiple exponentials). Cranmer & van Ballegooijen (2003) derived an analytic solution to a simplified version of Equation (31), with

$$g(\chi) = \frac{2\Gamma(n)}{3\Gamma(n-0.5)\sqrt{\pi}} \left( 1 + \frac{4\alpha_{\perp}^2 \chi^2}{9\alpha_{\perp}} \right)^{-n},$$

(C14)

and

$$n = 1 + \frac{3s}{4}.$$  

(C15)

These expressions are appropriate for the MHD inertial range where $v_\perp \propto k_\perp^{-1/3}$, but we use them for the entire range of
modeled wavenumbers. The above form for \( g(\chi) \) resembles a generalized Lorentzian, or kappa distribution (e.g., Vasyliunas 1968; Pierrard & Lazar 2010) that is Gaussian for small arguments and evolves to a power-law tail for large arguments. We can simplify the argument of the power-law term by using the values of the cascade parameters discussed in Section 3.1, with \( \alpha_\perp/\alpha_\parallel \approx 18.6/(3s + 2) \).

An example choice for the dimensionless advection–diffusion ratio (\( s = \mu_\perp/\alpha_\parallel = 2 \)) gives rise to a power-law exponent \( n = 5/2 \), and the large-\( k_\parallel \) behavior of the Alfvénic power spectrum is \( E_A \propto k_\parallel^{-5} \). Smaller values of \( s \) give shallower power-law slopes. In fact, Cranmer & van Ballegooijen (2003) and Landi & Cranmer (2009) found that if \( s \) could be maintained at small values of order 0.1–0.3, there would be sufficient high-\( k_\parallel \) power to heat protons and heavy ions in the corona via ion cyclotron resonance. In the opposite limit of pure advection (i.e., \( s \to \infty \) or \( \alpha_\perp \to 0 \), with \( \alpha_\parallel \) and \( \mu_\perp \) remaining finite) Equation (14) becomes a Gaussian,

\[
g(\chi) \propto \exp\left(-\frac{\mu_\perp}{3\alpha_\parallel} \chi^2 \right). \tag{C16}
\]

Chandran (2008b) also obtained a similar Gaussian solution for the parallel spectrum under the assumption of pure advection. Using the values of the cascade parameters discussed in Section 3.1, we can set \( \mu_\perp \approx 1.95 \) in the limit of \( s \to \infty \). Thus, the ratio \( \mu_\perp/\alpha_\parallel \approx 6.2 \) and we can write \( g \sim e^{-2x^2} \) in the pure-advection limit.

In this paper, we modify the analysis described above in one additional way. Instead of using the usual critical balance parameter \( \chi \) as the argument of \( g(\chi) \), we use

\[
\chi_{\text{eff}} = \frac{\chi}{\sqrt{1 + \chi_0^2}}. \tag{C17}
\]

where \( \chi_0 \) is defined in Equation (37). In the strong turbulence regime (\( \chi_0 \ll 1 \)) this modification makes no difference. In the weak turbulence regime (\( \chi_0 \gg 1 \)) this has the effect of extending the “filled” region of the spectrum (i.e., \( g(\chi_{\text{eff}}) \approx 1 \)) up through all wavenumbers with \( k_\parallel \lesssim k_{0\parallel} \).

Finally, we must adjust the highest frequency part of the spectrum to account self-consistently for the effects of ion cyclotron damping. Because the cyclotron resonance at high \( k_\parallel \) has a rapid onset (see Figure 11(a)), we need only model its effects over a limited range of wavenumber space. We truncate the calculation of the spectrum at a maximum parallel wavenumber

\[
k_{\text{limax}} V_A \frac{\Omega_p}{\Omega_\parallel} = 0.72 \frac{k_\parallel}{k_{0\parallel}^4} \tag{C18}
\]

at which \( |\gamma_A|/\Omega_p \approx 1 \). Above this wavenumber, we found that slowly varying solutions to the Vlasov–Maxwell dispersion relation cease to exist (see also Stix 1992). Between 0.1\( k_{\text{limax}} \) and \( k_{\text{limax}} \), we include the time-steady effect of resonant damping by assuming that the local Alfvénic wave power is produced solely by the nonlinear coupling with the fast mode. If only the coupling and damping are present, the time-steady transport equation simplifies to

\[
\frac{\partial E_A}{\partial t} \approx \frac{E_F - E_A}{\tau_{\text{AF}}} - 2 \gamma_A E_A = 0, \tag{C19}
\]

which can be solved analytically for \( E_A \). However, we note that we already have a time-steady solution for \( E_A \) in the presence of nonlinear coupling, but it does not take into account the ion cyclotron damping. Equation (54) gives that solution, which we now call \( E_{0A} \). Thus, we insert it in place of \( E_F \) in Equation (19) above, since that is the solution toward which the coupling will drive the system in the absence of damping. We then use the analytic solution

\[
E_A \approx \frac{E_{0A}}{1 + 2 \gamma_A / \tau_{\text{AF}}} \tag{C20}
\]

to account for ion cyclotron dissipation at high \( k_\parallel \). This solution gives rise to a significant reduction in the power spectrum when the damping rate \( \gamma_A \) exceeds the rate at which power is supplied from the nonlinear coupling.

### C.4. Fast-mode Waves: Cascade and Source Terms

This section is conceptually similar to Appendix C.1 in that we ignore both damping and mode coupling, assume time-steady conditions, and model the spectral transport of fast-mode waves as a balance between diffusive cascade and the outer-scale source term. In that limiting case, Equation (32) becomes

\[
\frac{\partial \varepsilon}{\partial k} = k^2 S_F. \tag{C21}
\]

where the cascade rate is defined here as

\[
\varepsilon = -\frac{4\pi \alpha_\parallel k^8 \sin \theta}{V_A} \frac{\partial E_F}{\partial k}. \tag{C22}
\]

When \( S_F = 0 \), the cascade rate is constant along radial rays of constant \( \theta \), and thus \( E_F \propto k^{-7/2} \). We follow Chandran (2005) and others by assuming a Gaussian shape for the fast-mode source term, but we also add a corresponding \( \sin \theta \) angle dependence, with

\[
S_F(k) = S_0 \exp\left[ -\left( \frac{k}{k_{0F}} \right)^2 \right] \sin \theta. \tag{C23}
\]

We eventually set \( S_0 \) at the level required to maintain the spectrum at the known total energy density \( U_F \). Our choice to constrain \( k_{0F} \) to be equal to \( k_{0\parallel} = 1/\lambda_{\parallel} \) is discussed in Section 3.1.

Because both the left and right sides of Equation (C21) depend identically on \( \sin \theta \), the resulting time-steady solution for \( E_F(k) \) becomes independent of \( \theta \). This outcome was motivated by simulation results that show that the fast-mode power spectrum is largely isotropic in wavenumber space (Cho & Lazarian 2003; Svidzinski et al. 2009). It is also possible that additional isotropization of the fast-mode spectrum can come from couplings with slow-mode waves (Chandran 2008a) or from multi-scale “wandering” of the magnetic field that gives rise to a continuously varying direction for \( \theta = 0 \) (Shalchi & Kourakis 2007). In future work, our method of artificially forcing isotropy via the source term should be replaced with a more realistic description.

In any case, we cancel out both instances of \( \sin \theta \) and integrate Equation (C21) to obtain

\[
\varepsilon(k) = k_{0F}^3 S_0 \left( \frac{\sqrt{\pi}}{4} e^{-x} - \frac{\text{erf} x}{2} \right), \tag{C24}
\]

where \( x = k/k_{0F} \). In the limit \( x \gg 1 \), the term in parentheses above approaches a constant value of \( \sqrt{\pi}/4 \). In
the limit $x \ll 1$, the term in parentheses is approximately equal to $x^3/3$. Finally, we integrate the definition of $\varepsilon$ to get the time-steady spectrum,

$$
\frac{E_F^2}{2} = \frac{V_A}{4\pi \omega_F} \int_{k_0}^{\infty} dk \frac{\varepsilon(k)}{k^8},
$$

(C25)

which we evaluate numerically using Equation (C24) for the cascade rate in the integrand. In the energy containing range ($k \ll k_0$), this yields $E_F \propto k^{-2}$, and thus $v_\mathcal{F} \propto k^{+1/2}$.

**C.5. Fast-mode Waves: Cascade and Dissipation Terms**

If we consider high values of $k$ above those affected by the outer-scale source term, we can solve for the transition from the inertial range to the dissipation range in the fast-mode power spectrum. An analytic solution becomes possible if we rewrite the fast-mode spectral transport time $\tau_F$ as a function of $k$ and \( \theta \) only. This can be done by using the time-steady inertial range scaling for $v_\mathcal{F}$, with

$$
v_\mathcal{F}^2 = v_0^2 \left( \frac{k}{k_0} \right)^{-1/2}, \quad \tau_F = \frac{V_A}{v_0^2} \sin \theta \sqrt{k/k_0}.
$$

(C26)

Note that Equation (8) of Suzuki et al. (2007) gave the same result for the fast-mode cascade timescale (but without the $\sin \theta$ term). The normalization wavenumber $k_0$ is defined arbitrarily here; it needs to be set well below the regime of strong damping, but well above the outer-scale wavenumber $k_0$ so that we can justify ignoring the source term.

The above approximation gives $D_F \propto k^{5/2} \sin \theta$. It is also straightforward to model the fast-mode damping rate as being proportional to a constant power of the wavenumber, and thus we assume $\gamma_F = \gamma_0 (k/k_0)^\alpha$. Note that the normalizing constant $\gamma_0$ may depend on the angle $\theta$ as well. The time-steady version of Equation (32) becomes

$$
\frac{\alpha_F v_\mathcal{F}^2 k^{1/2} \sin \theta}{k^2 V_A} \left( \frac{k}{k_0} \right)^{7/2} \frac{\partial}{\partial k} \left( k^{9/2} \frac{\partial E_F}{\partial k} \right) = 2\gamma_0 \left( \frac{k}{k_0} \right)^{\zeta} E_F.
$$

(C27)

Defining the auxiliary variable

$$
x = \frac{k}{7} \left( k/k_0 \right)^{7/2}
$$

(C28)

helps to greatly simplify the differential equation. Thus,

$$
\frac{\partial^2 E_F}{\partial x^2} = \frac{c_F E_F}{x^{2(\zeta+13)/7}},
$$

(C29)

where

$$
c_F = \frac{2\gamma_0 V_A}{\alpha_F v_0^2 k_0 \sin \theta} \left( \frac{2}{7} \right)^{(2\zeta+13)/7}
$$

(C30)

is a constant that is essentially the ratio of the damping rate to the cascade rate at the normalization wavenumber $k_0$.

For $\zeta \gg 1$, Equation (C29) is solved analytically with two linearly independent terms proportional to the two types of modified Bessel function ($I_\zeta$ and $K_\zeta$). Knowing that the only physically realistic solution is one that decreases monotonically with increasing $k$ (or with decreasing $x$), we then use only one of those terms, which is given by

$$
E_F(k) \propto k^{-7/4} K_\zeta \left[ 2 \left( \frac{2}{7} \right)^{1/2} \sqrt{c_F} \left( \frac{k}{k_0} \right)^{7/4} \right].
$$

(C31)

where $\zeta = 7/(2\zeta - 1)$. Note that the transit-time damping rate of Equation (58) gives $\zeta = 1$ and $\zeta = 7$. In the limiting case that the modified Bessel function of the second kind has a small argument, we have $K_\zeta(x) \sim x^{-\zeta}$ and thus $E_F \propto k^{-7/2}$, independent of the value of $\zeta$. This is the proper inertial-range solution in the case of either low wavenumber ($k \ll k_0$) or weak damping ($c_F \ll 1$). The opposite case of a large argument gives exponentially steep dissipation in the limit of large $k$ and/or large $\gamma_0$. This kind of solution was also derived by Hunana & Zank (2010).

Another useful special case for the damping exponent is $z = 1/2$. For this value of the exponent, Equation (C29) is solved with two linearly independent power-law terms. As above, we keep only the solution that does not diverge as $x \to 0$ (i.e., as $k \to \infty$), and the time-steady spectrum is given by

$$
E_F(k) \propto k^{-7+1+4\gamma_F}/4.
$$

(C32)

The weak-damping limit of $c_F \ll 1$ gives the proper inertial-range solution $E_F \propto k^{-7/2}$, but the presence of a nonzero value of $c_F$ makes the spectrum steeper. This is one (possibly rare) case in which a physically motivated source of damping gives rise to a power-law “dissipation range.”

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