A duopoly preemption game with two alternative stochastic investment choices

Kristina Rognlien Dahl · Espen Stokkereit

Received: date / Accepted: date

Abstract This paper studies a duopoly investment model with uncertainty. There are two alternative irreversible investments. The first firm to invest gets a monopoly benefit for a specified period of time. The second firm to invest gets information based on what happens with the first investor, as well as cost reduction benefits. We describe the payoff functions for both the leader and follower firm. Then, we present a stochastic control game where the firms can choose when to invest, and hence influence whether they become the leader or the follower. In order to solve this problem, we combine techniques from optimal stopping and game theory. For a specific choice of parameters, we show that no pure symmetric subgame perfect Nash equilibrium exists. However, an asymmetric equilibrium is characterized. In this equilibrium, two disjoint intervals of market demand level give rise to preemptive investment behavior of the firms, while the firms otherwise are more reluctant to be the first mover.

Keywords Duopoly · Stochastic game · Preemption · Optimal stopping · Irreversible investment

Mathematics Subject Classification (2010) C720 · C730 · L130 · L260

1 Introduction

This paper studies how a two-firm preemptive investment game is affected when the firms involved have two investment opportunities instead of one. We compare this to the classic duopoly investment model, see e.g. Fudenberg and Tirole [7].

K. R. Dahl
Department of Mathematics, University of Oslo, Pb. 1053 Blindern, 0316 Oslo, Norway
Tel.: 004722855890
E-mail: kristrd@math.uio.no

E. Stokkereit
Department of Mathematics, University of Oslo, Pb. 1053 Blindern, 0316 Oslo, Norway
1.1 Literature overview

The analysis is motivated by Décamps et al. [4]. They show that adding another investment choice to a monopoly game gives rise to a dichotomous investment region. That is, the investment region is no longer a connected set, and it is this dichotomy that causes the preemption game to change structure.

We model a duopoly which operates in a market where there is a stochastic, exogenous demand, driven by a geometric Brownian motion (GBM). The firms can at any time carry out a costly investment, where they must choose between two different technologies. The investment is irreversible, and can only be done one time by each firm. The investment reward is a higher profit rate and hence a greater income. However, how much the technologies increase the firm’s profit is uncertain; each investment can either end up in a high profit state or a low profit state. As soon as the leader has invested, the profit state of his investment choice is revealed to both firms. Also, for the follower the investment cost of copying the same technology choice is reduced. Hence, being the second investor has benefits. On the other hand, the first mover will attain a monopoly benefit due to technological advantage until the second mover has invested. We solve this problem by using results by Décamps et al [4] combined with game theoretic techniques based on the analysis of Chevalier-Roignant and Trigiorgis [3].

1.1 Literature overview

Duopoly games often have complicated structures where the firms both compete and cooperate. An important example is the case of cooperative research effort, which is studied in Aspremont and Jacquemin [1]. The paper models this cooperation to be active, in the sense that the firms at a R&D stage maximize their joint profit function, and then compete at a "market stage". Several other papers study this idea, but many exclude an active cooperative setting, and instead model the benefits of other firms’ investment by technology spillovers. Technology spillover is the concept that when one firm attains a new technology, it becomes easier for other firms to acquire the same technology, for instance because they can learn from the innovator firm’s research advances. An example of such a paper is Femminis and Martini [6]. In this paper, investment is a "one-shot" action which increases the firms’ profit rate. A certain time after the first firm has invested, the investment cost is reduced for the second firm. Thus, the first firm can be seen as an innovator, while the follower can be seen as an imitator.

Some papers that focus on second mover advantages, due to for instance information benefits, are Hoppe [8] and Y. J. Yap, S. Luckraz and S. K. Tey [19]. A paper with an in-depth study of imitation versus innovation is Bessen and Maskin [2]. They consider a setting where the more firms that invest, the bigger the probability of innovating becomes. However, if one firm succeeds, the other firms can copy this. This gives incentives to not invest and instead simply imitate. The paper focuses on social optimality, and compares situations with and without patents. Also, they cover both a static and a sequential in-
vestment context. Another relevant paper that examines the choice of doing innovation versus imitation is Jin and Troege [13].

Huisman and Kort [9] analyzes a choice between two investments. However, the setting of this paper is different from ours, as one does not know when the second investment opportunity arrives. Other papers studying investment choice are Décamps et al. [4] and Nishihara and Ohyama [14]. The solution method we apply in this paper is based on the results in Décamps et al. [4]. However, in contrast to Decamps et al. [4], we study a game between two firms and we have an additional uncertainty in the profit rate obtained from the investment. Nishihara and Ohyama [14] studies a game, but without uncertain profit rate.

The papers by Huisman et al. [10] and [11] both analyze stochastic games related to real options models. The paper [11] is quite general, but the firms only have one investment choice. We extend this by adding another technology. They study a preemption example, and we extend this example in a way which results in a more complicated structure of behavior of the firms (contrast Figure 1 in Huisman et al. [11] to our Figure 2). The paper Huisman et al. [10] differs from ours in that they don’t have a stochastic demand, but rather a Poisson process for when new information is revealed to the firms.

As mentioned, we will prove that there is no symmetric equilibrium for our game, and instead characterize an asymmetric equilibrium. In the classic paper by Fudenberg and Tirole [7], they find a symmetric equilibrium with preemptive behaviour. This is due to a monopoly advantage of the leader, and that, in their model, it pays off to update the technology since this leads to an increased profit rate. However, the literature on duopoly game theory is extensive, and there are papers which find asymmetric equilibria in connection to duopoly as well. An example of such a paper is Reinganum [16]. In this case, they find an asymmetric equilibrium where one agent becomes the innovator and the other becomes the follower. This is due to the fact that they their model has a monopoly benefit as well as a decrease in investment cost over time. In Reinganum [17], they review some classic cases with symmetric and asymmetric equilibria in connection to duopoly and timing of innovation.

In contrast to both these classic cases, our paper includes a choice between technologies. This is inspired by Décamps et al. [4]. The technology choice leads to a result which is a mixture of what is seen in Fudenberg and Tirole [7] and in Reinganum [16]. Like [16], we have a monopoly benefit and a (potentially) reduced investment cost by waiting. This points to a leader/follower type result (as found by Reinganum [16]). However, the presence of technology choice implies that we get a period of preemptive behaviour, such as in Fudenberg and Tirole [7]. Hence, the resulting behaviour of our two firms becomes a combination of that in Reinganum [16] and in Fudenberg and Tirole [7]. This kind of behaviour has, to the best of our knowledge, not been seen before, and is a unique contribution of our paper.
1.2 Structure of the paper

The paper is organized as follows. In Section 2, we give a mathematical formulation of the model. Then, Section 3 describes the different payoff functions the firms may attain (depending on the investment outcome). This includes the case of a simultaneous Cournot investment, being the market follower and being the market leader. Section 4 presents a stochastic game in this framework. The game is defined in Section 4.1, based on the approach of Huisman [11]. Then a specific scenario where double preemption intervals occur is analyzed in Section 4.2. We show that no subgame perfect symmetric Nash equilibrium exists in this case, however, we characterize an asymmetric equilibrium. Finally, we conclude in Section 5.

2 The model

Consider a framework with two firms, both facing two different irreversible investment opportunities. We call these investment 1 and investment 2. Both firms may invest at any time in either of the investment opportunities, but not in both. When the first firm has invested, thus becoming the leader, nature chooses one of two outcomes: a high profit outcome or a low profit outcome. This outcome is determined according to some probability measure. Hence, we consider a finite scenario space \( \Omega_F = \{ \omega_l^l, \omega_l^h, \omega_h^l, \omega_h^h \} \) (the subscript \( F \) stands for finite) and assume that \( P_F \) is a given probability measure on this space. Here, \( \omega_h^l \) is the scenario where investing in alternative 1 leads to a high profit, denoted \( \pi^h_1 > 0 \), while investment 2 leads to low profit, \( \pi^l_2 > 0 \). Similar interpretations hold for \( \omega_l^l, \omega_l^h \) and \( \omega_h^h \). These probabilities are the same for both firms.

Remark 1 The motivation for this problem is to study a model for an investment game involving uncertainty, since this is more realistic than a deterministic model. Only considering two possible outcomes is a simplification which is made to make the computations more manageable. However, similar kinds of arguments can be made for some number \( n < \infty \) of potential outcomes, though this will become bewildering as \( n \) grows.

The second firm to invest, thus becoming the follower, can choose what to do after the leader has invested. The follower observes the outcome of the leader’s investment. Hence, the follower has the advantage of having more information than the leader.

The profit rates of the two firms vary according to the state of the game. In accordance to what is often done in the literature, we normalize such that both agents get no profit before any investment has occurred. When the first firm has invested, it immediately gets either profit rate \( \pi^h_1 \) (high profit, investment 1), \( \pi^l_1 \) (low profit, investment 1), \( \pi^h_2 \) or \( \pi^l_2 \), depending on whether the firm chooses investment 1 or 2, and on which scenario \( \omega \in \Omega_F \) is realized. Until the second firm invests, the leader also enjoys a monopoly benefit \( \xi \). The
follower continues to have profit rate 0 until it invests. If it chooses to copy the technology of the first investor, by for example choosing investment 1, the follower gets the same level of profit as the first investor (either \( \pi_1^h \) or \( \pi_1^l \) depending on the outcome of the \( \Omega_F \)-draw). However, if the second investor chooses not to follow the first investor (i.e. by choosing investment 2), it will get a random profit rate, either \( \pi_2^h \) or \( \pi_2^l \), according to the probability measure \( P_F \) given that only \( \pi_2^h \) or \( \pi_2^l \) can happen.

To simplify, we assume that the problem is symmetric, i.e. that \( \pi_1^h = \pi_2^h =: \pi_h \), \( \pi_1^l = \pi_2^l =: \pi_l \) and that the probabilities of high or low outcomes, respectively, are the same for both investments. This means that we can remove the technology choice for the first firm, and just look at nature’s choice of high or low profit.

**Remark 2** The main purpose of our paper is to investigate the firms’ wish to become leader vs. follower, as well as how their mutual behaviour affect the other’s choices. We study how the game dynamics affect the incentive to innovate. However, we are not really concerned with the choice of one technology over the other. Our concern is the timing of investment, rather than the properties of the two technologies. Therefore, we believe that having different profits for the two technologies makes the model more complicated than what is necessary in order to highlight our problem. Assuming different profits for the two technologies would result in more parameters and messier calculations, without telling us more about the incentive to innovate. However, this should pose no real mathematical challenges (other than messiness).

Note that having two different technologies is still crucial for the model because this provides an information-aspect: The follower observes the choice of the leader, and based on this, he can choose whether to follow in the same direction or innovate. This gives the follower an advantage, though we do not really care about the actual choice of technology the follower makes.

To model the exogenous and uncertain demand for the duopoly’s product, we introduce another probability space \( (\Omega, F, P) \), and consider a Brownian motion \( (B_t)_{t \in [0, \infty)} \) in this space. Let \( (F_t)_{t \in [0, \infty)} \) be the filtration generated by the Brownian motion. The process modeling the uncertainty in demand is a geometric Brownian motion which we denote by \( (Z_t)_{t \in [0, \infty)} \), such that

\[
dZ_t = \alpha Z_t dt + \sigma Z_t dB_t.
\]

Here, \( \alpha, \sigma \in \mathbb{R}_+ \). Also, let \( r \in \mathbb{R}_+ \) be the interest rate. We assume \( \alpha < r \).

**Remark 3** The assumption of \( \alpha < r \) ensures that the profit function of the leader is well defined (i.e., finite; see calculations before equation (3) later in the paper). The need for such an assumption comes from our choice of a geometric Brownian motion exogenous demand.

For the first firm to invest, we let the cost of any investment be \( I > 0 \). If the second investor chooses to follow the leader, the investment cost is reduced to \( (1 - \theta)I \), \( \theta \in (0, 1) \), while the price for the other investment choice is still
The intuition is that it is more expensive to be innovative than to imitate technology that already exists. After both firms have invested, no more choices are made and the profit rates of the investors stay constant.

3 The payoff functions

We want to describe a game where the firms can choose when to invest, so they can influence whether they become the leader or the follower. In order to do this, we must compute the expected payoff functions attained for the different roles. More specifically, we will compute the following functions for all times \( t \geq 0 \), where we assume that the stochastic demand process \( Z_t \) has value \( z_t \) at time \( t \):

(i) \( C(z_t) \): The payoff of both firms when they invest simultaneously at time \( t \), and the firms do not take the roles of leader and follower. Note that the \( C \) stands for “Cournot” (see also Chevalier-Roignant and Trigeorgis [3]). In this case, we assume that neither of the firms get any information advantage or reduced investment cost.

(ii) \( F(z_t) \): The payoff of the second investor given that the leader stops at time \( t \) and that the follower is acting optimally.

(iii) \( L(z_t) \): The payoff of the first investor who stops at time \( t \) and hence becomes the leader, given that the other firm will act optimally as the follower.

We divide the computation of these functions into several subsections.

In the following, \( E[\cdot] \) denotes the expectation with respect to the product measure \( P \times P_F \), also let \( E^P[\cdot] \) and \( E^{P_F}[\cdot] \) denote the expectation w.r.t. the measures \( P \) and \( P_F \) respectively.
3.1 The Cournot case: $C(z_t)$

Let $\pi$ be the random variable taking the values $\pi_l$ and $\pi_h$ with probabilities determined by $P_F$. Let $E_z[\cdot]$ denote the expectation given that $Z_t = z_t$.

In the case where both firms invest exactly at time $t$ and the Cournot outcome is attained, their payoff functions are identical, and given by

$$C(z_t) = E_z[\int_0^{\infty} Z(u+t)e^{-ru}du - I]$$

$$= E_z[\int_0^{\infty} Z(s)e^{-r(s-t)}ds - I]$$

$$= E^P[\pi]\int_0^{\infty} E^P[Z(s)]e^{-ru}du - I$$

$$= E^P[\pi]\int_0^{\infty} Z(s)e^{-ru}du - I.$$ (1)

Here, the first and the third equalities follow from Tonelli’s theorem, the second equality from a change of variables and the final equality from that $Z$ is a geometric Brownian motion.

3.2 The follower’s payoff: $F(z_t)$

We begin by finding the payoff function of the follower, hence we assume that one of the firms has already invested at time $t$. Based on this we can later determine the payoff of the leader who’s optimal behavior depends on the behavior of the follower.

For the follower, two scenarios can occur: The leader got high profit $\pi_h$ or low profit $\pi_l$. The follower knows which profit level the leader got, and can choose to copy or innovate based on this.

3.2.1 The case where the leader got low profit: $F_L(z_t)$

If the leader got the low profit $\pi_l$, the payoff function of the follower at the leader’s investment time $t$ is:

$$F_L(z_t) := e^{rt}\sup_{\tau \geq 0} \max \left\{ E^P\left[ \int_{\tau+t}^{\infty} \pi_l Z_s e^{-rs}ds - (1 - \theta)I e^{-r(\tau+t)} \right], \right.$$\left.$$

$$E^P\left[ \int_{\tau+t}^{\infty} E^P[\pi] Z_s e^{-rs}ds - I e^{-r(\tau+t)} \right] \right\}$$ (2)

where $\tau$ is the stopping time from the investment time of the leader until the investment time of the follower. That is, $\tau + t$ is the investment time of the follower. In the following, we will omit specifying that this is a stopping time, in order to avoid confusion with the fact that the stopping time in question actually gives the investment time of the follower.

The first expression in the maximum corresponds to copying the leader, while the second expression corresponds to innovating. The first expression
can be rewritten:
$$
E^P \left[ \int_{t+\varepsilon}^{\infty} \pi_1 Z_s e^{-r_s} ds - (1 - \theta) I e^{-r(t+t)} \right] \\
= e^{-rt} E^P_\tau \left[ \int_{t+\varepsilon}^{\infty} \pi_1 Z_s e^{-r_s} ds - (1 - \theta) I e^{-r\tau} \right] \\
= e^{-rt} E^P_\tau \left[ E^P \left[ \int_{t+\varepsilon}^{\infty} \pi_1 Z_s e^{-r_s} ds - (1 - \theta) I e^{-r\tau} | \mathcal{F}_\tau \right] \right] \\
= e^{-rt} E^P_\tau \left[ e^{-r\tau} \left( \int_{0}^{\infty} \pi_1 Z(\tau) e^{(\alpha-r)\tau} ds - (1 - \theta) I \right) \right] \\
= e^{-rt} E^P_\tau \left[ e^{-r\tau} Z(\tau) \pi_1 - (1 - \theta) I e^{-r\tau} \right]
$$

where the second equality follows from double expectation, the third equality from the strong Markov property for the Itô diffusion $Z_t$ (see also Øksendal [15] exercise 7.11 for justification of the integral term) and the final equality follows from that $Z_t$ is a geometric Brownian motion.

A similar computation shows that the second part of the maximum in problem (2) can be written
$$
E^P_\tau \left[ \int_{t+\varepsilon}^{\infty} E^{P_{\tau}} \left[ \pi_1 Z_s e^{-r_s} ds - I e^{-r(t+t)} \right] \right] \\
= e^{-rt} E^P_\tau \left[ e^{-r\tau} \left( \int_{0}^{\infty} Z(\tau) \pi_1 - (1 - \theta) I \right) \right].
$$

Hence, problem (2) is equivalent to
$$
F_L(z_t) = \sup_{a_1, a_2} \left\{ e^{-r\tau} \max_{i=1,2} \{ a_i Z(\tau) - K_i \} \right\}
$$

where $a_1 := \frac{\pi_1}{r - \alpha}$, $a_2 := \frac{E[\pi]}{r - \alpha}$, $K_1 := (1 - \theta) I$ and $K_2 := I$. Note that $K_1 < K_2$ and $a_1 < a_2$.

Problem (3) is of the same form as the problems in Decamps et al [4] and Nishihara and Ohyama [14]. As in these papers, we have to consider several cases. The first case is $0 < \frac{a_2}{a_1} < 1$, however since $a_1 < a_2$, this never occurs.

Let $\gamma := \frac{1}{2} - \frac{a_1}{2z_L} + \frac{1}{2} \sqrt{\left( \frac{a_1}{2z_L} - \frac{1}{2} \right)^2 + \frac{2}{a_2}} > 1$. The next case to consider is $1 < \left( \frac{a_2}{a_1} \right)^{\frac{\gamma}{\gamma - 1}} < \frac{K_2}{K_1}$. Then,

$$
F_L(z_t) = \begin{cases} 
A_0 z_t^2 & \text{if } 0 < z_t < z_{1,L}^* \\
a_1 z_t - K_1 & \text{if } z_{1,L}^* \leq z_t \leq z_{2,L}^* \\
B_0 z_t - C_0 z_t^\beta & \text{if } z_{2,L}^* < z_t < z_{3,L}^* \\
a_2 z_t - K_2 & \text{if } z_t \geq z_{3,L}^* 
\end{cases}
$$

where $\beta := \frac{1}{2} - \frac{a_1}{2z_L} - \frac{1}{2} \sqrt{\left( \frac{a_1}{2z_L} - \frac{1}{2} \right)^2 + \frac{2}{a_2}} < 0$ and $A_0, B_0, C_0$ as well as the investment thresholds $z_{1,L}^*, z_{2,L}^*, z_{3,L}^*$ are determined using value matching and smooth pasting conditions as in Dixit and Pindyck [5] (i.e. requiring continuity and continuous differentiability of the value function $F_L$). In particular, we find that

$$
z_{1,L}^* = \frac{\gamma}{\gamma - 1} \frac{(1 - \theta) I (r - \alpha)}{\pi_1}, \\
A_0 = \frac{(1 - \theta) I}{(\gamma - 1) (z_{1,L}^*)^{\gamma}}.
$$
Similarly, we can also find \( z_{2,L}^*, B_0 \) and \( C_0 \), however we omit writing these out since the expressions are long, and not necessary to know for our purposes. However, we will use the fact that \( z_{1,L}^* \leq z_{2,L}^* \leq z_{3,L}^* \).

The values of this split function correspond to the following actions of the follower (starting at the top): 1) Wait until the demand reaches \( z_{1,L}^* \), then copy the leader. 2) Copy right away. 3) Wait, but make no decision to copy or innovate. This decision depends on whether demand hits \( z_{2,L}^* \) (copy) or \( z_{3,L}^* \) (innovate) first. 4) Innovate right away.

The optimal investment time is

\[
\tau^* := \inf \{ t \geq 0 | Z(t) \in [z_{1,L}^*, z_{2,L}^*] \cup [z_{3,L}^*, \infty) \}. 
\]

The reason for the waiting behavior in the interval \( (z_{2,L}^*, z_{3,L}^*) \) is due to the structure of the follower’s payoff function

\[
F_L(z_t) = \sup_{\tau \geq 0} E^P \left[ e^{-r\tau} \max \{ a_{i}(Z(\tau) - K_{i}) \} \right],
\]

as shown in equation (3). Since \( a_1 < a_2 \) and \( K_1 < K_2 \) there is a point \( \hat{z} \) where \( a_1 \hat{z} - K_1 = a_2 \hat{z} - K_2 \), and at this point we have

\[
D^+ F_L(\hat{z}) = D^- F_L(\hat{z}),
\]

where \( D^+, D^- \) denotes the right and left derivatives respectively. Thus, at \( \hat{z} \) the profit gain of a marginal increase in market demand is larger than the profit loss of a marginal decrease in market demand. As a result, there is an open nonempty interval containing \( \hat{z} \) where the follower is interested in waiting to see how the market demand \( Z \) evolves. For more on this issue, see the paper by Decamps et al [4].

The final case to consider is \( (z_{2,L}^*, \frac{z_{3,L}^*}{z_{1,L}^*}) \). In this case,

\[
F_L(z_t) = \begin{cases} 
B_0 z_t^* & \text{if } 0 < z_t < z_{1,L}^* \\
I(t)(z_t - K_2(t)) & \text{if } z_t \geq z_{3,L}^*. 
\end{cases} 
(6)
\]

The optimal investment time is \( \tau^* = \inf \{ t \geq 0 | Z(t) \geq z_{3,L}^* \} \). In this situation, the follower waits until the demand reaches the level \( z_{3,L}^* \) and then innovates.

### 3.2.2 The case where the leader got high profit: \( F_H(z_t) \)

In the case that the leader got the high profit \( \pi_h \), the payoff function of the follower at time \( t \) has a similar form as the above situation:

\[
F_H(z_t) := e^{rt} \sup_{\tau \geq 0} \max \left\{ E^P \left[ \int_{\tau+t}^{\infty} \pi_h Z_s e^{-rs} ds - (1-\theta)I e^{-r(\tau+t)} \right], \right. \\
E^P \left[ \int_{\tau+t}^{\infty} E^P \left[ \pi \right] Z_s e^{-rs} ds - I e^{-r(\tau+t)} \right] \right\}, \tag{7}
\]
3.3 The leader’s payoff: $L(z_t)$

However, since both $\pi_h > E[\pi]$ and $(1 - \theta)I < I$ are true, it follows that the first term in the maximum expression always is higher than the second. Thus, the payoff function reduces to

$$F_H(z_t) = \begin{cases} \frac{I}{\gamma - 1} - \frac{z_t}{\gamma - 1} & \text{if } 0 < z_t < z_H^* \\ \frac{\pi_h}{\gamma - 1} - I(1 - \theta) & \text{if } z_t \geq z_H^* \end{cases}$$

(8)

Here,

$$z_H^* = \frac{\gamma}{\gamma - 1} \frac{r - \alpha}{\pi_h} (1 - \theta)I$$

is the critical value such that the follower waits for all $z_t < z_H^*$ and copies immediately for $z_t \geq z_H^*$ (see e.g. Femminis and Martini [6] for solution procedure), where $\gamma$ is as before.

Note that $z_H^* < z_{1,L}^*$, i.e. the demand-threshold for the follower-firm investing when they are guaranteed a high profit is lower than the first investment threshold in the low profit case.

3.3 The leader’s payoff: $L(z_t)$

Now that we have determined the optimal behavior and payoff function for the follower, we can derive the leader’s optimal value function $L(z_t)$. This payoff function is the expectation (with respect to the probability measure corresponding to nature’s choice of high or low profit) of the payoff functions in the case where the leader gets high or low profit respectively. We let $L_L(z_t)$ and $L_H(z_t)$ be the value functions in the low and high profit cases respectively. Then,

$$L(z_t) = P_F(\text{low profit})L_L(z_t) + P_F(\text{high profit})L_H(z_t).$$

(9)

Let $p$ denote the probability of a high profit, so $p := P_F(\text{high profit})$, so the probability of a low profit is $1 - p$. We assume that $p \in (0, 1)$. If $p = 0$ (or $p = 1$), then the profit will always become low (or high), which makes our problem uninteresting.

We derive the two value functions $L_L(z_t)$ and $L_H(z_t)$ in the following subsections.

3.3.1 The low profit case: $L_L(z_t)$

The leader’s payoff function depends on the behavior of the follower. Hence, we have to take the structure of the function $F_L(z_t)$ into consideration, see Section 3.2.1. As in Section 3.2.1, we consider two cases.

First, we consider the case where $1 < \left(\frac{a_1}{K_1}\right) \frac{a_2}{K_2} < \frac{K_2}{K_1}$ (where the functions $a_1, a_2, K_1, K_2$ are defined as in Section 3.2.1). The payoff function $L_L(z_t)$ is the payoff of the leading firm when it invests at time $t$, given that the follower then behaves optimally.
By computations similar to those of Section 3.2.1, we can compute \( L_L(z_t) \)
(as we have assumed, due to symmetry, that the leader has no investment choice, and the investment time is \( t \) per definition of \( L_L(z_t) \)). For example, in the case where \( 0 < z_t < z_{1,L}^* \), we have

\[
L_L(z_t) = \mathcal{E}^P \left[ \int_0^{t + \tau^*} (\pi_t + \xi) Z(s) e^{-r(s-t)} ds + \int_{t + \tau^*}^{\infty} \pi_t Z(s) e^{-r(s-t)} ds - \mathcal{I} \right]
= \mathcal{E}^P \left[ \int_0^{t} (\pi_t + \xi) Z(s) e^{-r(s-t)} ds + \int_{t}^{\infty} \pi_t Z(s) e^{-r(s-t)} ds - \mathcal{I} \right]
= \frac{z_t (\pi_t + \xi)}{e^{r \alpha}} - \frac{z_t^2}{e^{2r \alpha}} \mathcal{E}^P \left[ e^{r \alpha \tau^*} |Z(t) = z_t - \mathcal{I} \right]
= \frac{z_t (\pi_t + \xi)}{e^{r \alpha}} - \frac{z_t^2}{e^{2r \alpha}} \mathcal{E}^P \left[ e^{r \alpha (t - |\alpha_t(t)| \sqrt{\nu + \gamma})} - \mathcal{I} \right]
= \frac{z_t}{e^{r \alpha}} z_t + \frac{\xi}{e^{2r \alpha}} z_t (1 - (\frac{z_t}{z_{1,L}^*})^{\gamma - 1}) - \mathcal{I}
\]

where \( \alpha_1(t) := \frac{1}{\sigma} \ln(\frac{Z_t}{z_t}) \), \( \nu := \frac{a}{\sigma} - \frac{a}{\sigma} \). Note that in the first equality, the first integral corresponds to the monopoly benefit, which only lasts until the follower invests (at time \( t + \tau^* \)). Note also that the second equality follows by adding and subtracting the monopoly benefit, the third equality follows from a similar argument (using the strong Markov property for Itô diffusions) as in Section 3.2.1 and the fourth equality follows from that \( \{Z_t\}_{t \geq 0} \) is a geometric Brownian motion, so we know the expectation of the first hitting time at the investment level (for the follower) \( z_{1,L}^* \) (see also Jeanblanc [12], section 8.1.3).

The final equality follows from some basic algebra.

Thus, we have

\[
L_L(z_t) = \begin{cases} 
\frac{z_t}{e^{r \alpha}} z_t + \frac{\xi}{e^{2r \alpha}} z_t (1 - (\frac{z_t}{z_{1,L}^*})^{\gamma - 1}) - \mathcal{I} & \text{if } 0 < z_t < z_{1,L}^* \\
\frac{z_t}{e^{r \alpha}} z_t - \mathcal{I} & \text{if } z_{1,L}^* \leq z_t \leq z_{2,L}^* \\
\frac{z_t}{e^{r \alpha}} z_t + M(z_t) - \mathcal{I} & \text{if } z_{2,L}^* \leq z_t \leq z_{3,L}^* \\
\frac{z_t}{e^{r \alpha}} z_t - \mathcal{I} & \text{if } z_t \geq z_{3,L}^*
\end{cases}
\]  

(10)

where,

\[
M(z_t) := (1 - P(Z \text{ hits } z_{2,L}^* \text{ first}|Z(t) = z_t)) \mathcal{E}^P \left[ \int_{t}^{t + \tau^*} \xi Z(s) e^{-r(s-t)} ds | Z \text{ hits } z_{2,L}^* \text{ first} \right] + P(Z \text{ hits } z_{3,L}^* \text{ first}|Z(t) = z_t) \mathcal{E}^P \left[ \int_{t}^{t + \tau^*} \xi Z(s) e^{-r(s-t)} ds | Z \text{ hits } z_{3,L}^* \text{ first} \right]
\]

(11)

Here, using that \( Z \) is a geometric Brownian motion (see Sigman [18])

\[
P(Z \text{ hits } z_{2,L}^* \text{ first}|Z(t) = z_t) = \frac{1 - e^{\frac{a b}{\bar{\alpha}}}}{e^{\frac{a b}{\bar{\alpha}}}}
\]

where \( a := \ln(\frac{z_{2,L}^*}{z_t}) \), \( b := \ln(\frac{z_{2,L}^*}{z_t}) \) and \( \bar{\alpha} := \frac{2|\alpha|}{\sigma^2} \). By some basic algebra, we see that

\[
P(Z \text{ hits } z_{3,L}^* \text{ first}|Z(t) = z_t) = \frac{1 - (\frac{z_{2,L}^*}{z_t})^{\bar{\alpha}}}{(\frac{z_{2,L}^*}{z_t})^{\bar{\alpha}} - (\frac{z_{2,L}^*}{z_t})^{\bar{\alpha}}}.
\]
The split in the value function of the leader, see equation (10), appears because the leader does not know whether the demand process $Z_t$ will hit the innovation level of the follower, $z_{3,L}^*$, or the copying level of the follower, $z_{2,L}^*$, first. The splits have similar interpretations as those in Section 3.2.1.

The final case is where $(\frac{a_2}{a_1})^{\frac{1}{\gamma-1}} \geq \frac{K_2}{K_1}$. From Section 3.2.1, we know that in this case the follower-firm waits until the demand reaches the level $z_{3,L}^*$ and then innovates. By similar calculations as in the previous case, we find that

$$L_L(z_t) = \begin{cases} \frac{\pi}{r-\alpha} z_t + \frac{\xi}{r-\alpha} z_t \left(1 - \frac{z_t}{z_{3,L}^*}^{\gamma-1}\right) - I & \text{if } 0 < z_t < z_{3,L}^* \\ \frac{\pi}{r-\alpha} z_t - I & \text{if } z_t \geq z_{3,L}^* \end{cases}$$

(12)

3.3.2 The high profit case: $L_H(z_t)$

Again, the leader’s payoff function depends on the behavior of the follower. We have

$$L_H(z_t) = E^P[\int_t^{\tau^*+\tau}(\pi_h + \xi)Z_s e^{-r(s-t)} ds + \int_{\tau^*+\tau}^{\infty} \pi_h Z_s e^{-r(s-t)} ds - I]$$

$$= E^P[\int_t^{\infty} \pi_h Z_s e^{-r(s-t)} ds + E^P[\int_{\tau^*+\tau}^{\infty} \xi Z_s e^{-r(s-t)} ds] - I.$$

The term $E^P[\int_{\tau^*+\tau}^{\infty} \xi Z_s e^{-r(s-t)} ds]$ equals zero if the follower stops immediately after the leader, and equals

$$\frac{\xi}{r-\alpha} z_t \left(1 - \left(\frac{z_t}{z_{H}^*}\right)^{\gamma-1}\right)$$

for $z_t \in (0, z_{H}^*)$ (see Section 3.3.1).

Thus, we have that

$$L_H(z_t) = \begin{cases} \frac{\pi}{r-\alpha} z_t + \frac{\xi}{r-\alpha} z_t \left(1 - \left(\frac{z_t}{z_{H}^*}\right)^{\gamma-1}\right) - I & \text{if } 0 < z_t < z_{H}^* \\ \frac{\pi}{r-\alpha} z_t - I & \text{if } z_t \geq z_{H}^* \end{cases}$$

(13)

3.4 Combining the expressions

To summarize, we have that the leader’s ex ante expected payoff is

$$L(z_t) = pL_H(z_t) + (1-p)L_L(z_t),$$

where we recall that $z_{H}^* < z_{1,L}^* < z_{2,L}^*$, $L_L(z_t)$ and $L_H(z_t)$ are as in equations (12)-(13).

Similarly, the follower’s ex ante expected payoff is

$$F(z_t) = pF_H(z_t) + (1-p)F_L(z_t),$$

(15)
where $F_L(z_t)$ and $F_H(z_t)$ are as in Section 3.2.1 and equation (8).

By analyzing $L(z_t)$, $F(z_t)$ and $C(z_t)$ (as functions of the demand $z_t$), we find that $C$ is a linear function satisfying $C(0) = -I$. The leader payoff function $L$ also satisfies $L(0) = -I$. However, $L(z_t)$ is strictly concave on $(0, z_{1.L}^*)$, then equal to $C(z_t)$ for $z_t \in [z_{1.L}^*, z_{2.L}^*]$ and $z_t \geq z_{3.L}^*$. What happens to $L$ in the interval $[z_{2.L}^*, z_{3.L}^*]$ depends on the values of the parameters $I, \theta, \alpha, \tau$. The follower’s payoff $F$ satisfies $F(0) = -I(1 - \theta)$. It is strictly convex in the interval $(0, z_{1,L}^*)$ and $\alpha$ is greater than, but parallel to $C(z_t)$ (and therefore $L(z_t)$ as well) for $z_t \in [z_{1,L}^*, z_{2,L}^*]$. What happens to $F$ in the interval $[z_{2,L}^*, z_{3,L}^*]$ depends on the parameters of the problem. For $z_t \geq z_{3,L}^*$, $F(z_t)$ is linear with a steeper slope than $C(z_t)$ and it is also larger than $C(z_t)$. An example of how the three payoff functions may look is shown in Figure 2 below.

4 The stochastic game

In this section, we present a problem where the firms can choose when to invest, hence influencing whether they become the leader or the follower. Our aim is to illustrate that the timing of investment can become peculiar in a duopoly where there are benefits both of being leader (monopoly benefit) and follower (information benefit and reduced investment cost). The game we present is based on games discussed in Huisman et al. [11] and Chevalier-Roignant and Trigiorgis [3].

4.1 Defining the game

We consider a duopoly, with the two firms denoted firm 1 and firm 2. For a subgame starting at time $t_0 \in [0, \infty)$, a simple strategy for firm $i$ ($i = 1, 2$) is defined to be a function $\alpha_i^{t_0} : [t_0, \infty) \times \Omega \rightarrow [0,1]$ such that

- $\forall \omega \in \Omega, \alpha_i^{t_0}(\cdot, \omega)$ is RCLL and right differentiable, and $\forall t \geq t_0, \alpha_i^{t_0}(t, \cdot)$ is $\mathcal{F}_t$-measurable.
- If $\alpha_i^{t_0}(t, \omega) = 0$ for $t = \inf\{u \geq t_0|\alpha_i^{t_0}(u; \omega) > 0\}$, then the right derivative of $\alpha_i^{t_0}(t; \omega)$ is positive.

Furthermore, let

$$\tau_i(t_0; \omega) := \begin{cases} \infty & \text{if } \alpha_i^{t_0}(t; \omega) = 0 \forall t \geq t_0 \\ \inf\{t \geq t_0|\alpha_i^{t_0}(t; \omega) > 0\} & \text{otherwise,} \end{cases}$$

and $\tau = \min\{\tau_1, \tau_2\}$.

The intuition of $\alpha_i^{t_0}$ can be interpreted in two steps. First, firm $i$ choosing $\alpha_i^{t_0}(t, \omega) = 0$ means that for the given scenario $\omega \in \Omega$, firm $i$ is not at all interested in becoming the leader firm at time $t$. If this holds for both firms in a neighborhood of $t$, then no investment will occur at this time. Second, firm $i$ choosing $\alpha_i^{t_0}(t, \omega) > 0$ means that firm $i$ definitely wants investment to occur at
time \( t \) for the given scenario, and is willing to be the leader in order for this to happen. However, the higher the level of \( \alpha_i^0(t, \omega) \), the higher is the probability that firm \( i \) actually becomes the leader given that also \( \alpha_i^0(t, \omega) > 0 \).

A closed loop strategy for firm \( i \) is a collection of simple strategies

\[
\{(\alpha_i^t(\cdot; \omega))_{0 \leq t < \infty}\}
\]

with the property that

- for all \( u, v \) such that \( t \leq u \leq v < \infty \), we have \( \alpha_i^t(v; \omega) = \alpha_i^v(v; \omega) \) whenever \( v = \inf \{ s > t | Z_s = Z_v \} \).

The point of the above property is to ensure that the strategies of two different subgames coincide at all times \( v \) that is a shared first hitting time of a new state \( Z_v \) for both games. This ensures that strategies are consistent for the different subgames.

The expected discounted value of firm \( i \) of the subgame starting at time \( t_0 \) given the simple strategies \( s^{t_0}(\omega) = \{(\alpha_i^{t_0}(\cdot; \omega))_{i=1,2}\} \) is

\[
V_i(t_0, s^{t_0}(\omega)) = E_{t_0}[e^{-\tau(t_0, \omega)}W_i(\tau(t_0, \omega), s^{t_0}(\omega))].
\]  \hspace{1cm} (16)

Here, \( E_{t_0}[\cdot] := E[\cdot | \mathcal{F}_{t_0}] \) and

\[
W_i(\tau, s^{t_0}(\omega)) = \begin{cases} L(Z_\tau(\omega)) & \text{if } \tau_i(t_0; \omega) > \tau_i(t_0; \omega), \\ F(Z_\tau(\omega)) & \text{if } \tau_i(t_0; \omega) > \tau_j(t_0; \omega). \end{cases}
\]

Finally, if \( \tau_i(t_0; \omega) = \tau_j(t_0; \omega) \), then

\[
W_i(\tau, s^{t_0}(\omega)) = C(Z_\tau(\omega)) \text{ if } \alpha_i^{t_0}(\tau; \omega) = \alpha_j^{t_0}(\tau; \omega) = 1,
\]

while

\[
W_i(t_0, s^{t_0}(\omega)) = [\alpha_i^{t_0}(\tau; \omega)(1 - \alpha_j^{t_0}(\tau; \omega))L(Z_\tau(\omega)) + \alpha_j^{t_0}(\tau; \omega)(1 - \alpha_i^{t_0}(\tau; \omega))F(Z_\tau(\omega)) + \alpha_i^{t_0}(\tau; \omega)\alpha_j^{t_0}(\tau; \omega)C(Z_\tau(\omega))] / [\alpha_i^{t_0}(\tau; \omega) + \alpha_j^{t_0}(\tau; \omega) - \alpha_i^{t_0}(\tau; \omega)\alpha_j^{t_0}(\tau; \omega)]
\]  \hspace{1cm} (17)

if \( 2 > \alpha_i^{t_0}(\tau; \omega) + \alpha_j^{t_0}(\tau; \omega) > 0 \) and

\[
W_i(t_0, s^{t_0}(\omega)) = \frac{(\alpha_i^{t_0})'(\tau; \omega)L(Z_\tau(\omega)) + (\alpha_i^{t_0})'(\tau; \omega)F(Z_\tau(\omega))}{(\alpha_i^{t_0})'(\tau; \omega) + (\alpha_j^{t_0})'(\tau; \omega)}
\]  \hspace{1cm} (18)

if \( \alpha_i^{t_0}(\tau; \omega) = \alpha_j^{t_0}(\tau; \omega) = 0 \). The functions \( L, F \) and \( C \) are as in Section 3.

For a given \( \omega \in \Omega \) a tuple of simple strategies

\[
(s_i^*)_{i=1,2} = (\alpha_i^{t_0}(t; \omega))_{i=1,2}
\]

is a Nash equilibrium for the subgame starting at time \( t_0 \) if for \( i = 1, 2 \)

\[
V_i(t_0, s_i^*, s_{-i}^*) \geq V_i(t_0, s_i, s_{-i}^*)
\]

for all simple strategies \( s_i \).

A pair of closed loop strategies \( \{(\alpha_i^t(\cdot; \omega))_{0 \leq t < \infty}\}_{i=1,2} \) is a subgame perfect equilibrium if for all \( t \in [0, \infty) \) \( (\alpha_i^t(\cdot; \omega))_{i=1,2} \) is a Nash equilibrium.
4.2 The case with a high monopoly benefit

We consider the case where $1 < \frac{(\frac{a_2}{a_1})^{1-\gamma}}{\gamma} < \frac{K_2}{K_1}$, so the function $F_L(z_t)$ is as in equation (4). Furthermore, we let the monopoly benefit $\xi$ be sufficiently large so that the following conditions hold:

- there exists $z < z^*_1, L$ such that $L(z) > F(z)$,
- there exists $z \in (z^*_2, L, z^*_3, L)$ such that $L(z) > F(z)$.

This situation will always happen for $\xi$ sufficiently large, since we see from equation (10) that $L(z)$ becomes arbitrarily large for $z < z^*_1, L$ and $z \in (z^*_2, L, z^*_3, L)$ as $\xi$ increases.

Thus, we are in the situation depicted in Figure 2, where the follower and the leader value functions, $F(z)$ and $L(z)$, intersect twice. Let $A_1$ and $A_2$ denote the two intervals where the leader’s payoff $L(z)$ exceeds the follower’s $F(z)$. Also, recall that $z^*_1, L$, $z^*_2, L$, $z^*_3, L$, and $z^*_H$ are the investment thresholds of the follower in the low and high profit cases respectively, see Sections 3.2.1 and 3.2.2.

Let $z^*_{A_1, \min}$ be the infimum of $A_1$, and let similar definitions hold for $z^*_{A_1, \max}$, $z^*_{A_2, \min}$, and $z^*_{A_2, \max}$. Note that $z^*_{A_1, \min}$ is the smallest level of demand such that $L$ is greater than or equal to $F$. We let $T^*_{z^*_{A_1, \min}}$ denote the stopping time for when the process is greater than or equal $z^*_{A_1, \min}$ given we are at time $t$, with similar definitions for $z^*_{A_2, \min}$, $z^*_{A_2, \min}$ and $z^*_{A_2, \max}$.

Under the assumptions above, we can prove the following result.
4.2 The case with a high monopoly benefit

THE STOCHASTIC GAME

Theorem 1 There is no pure symmetric subgame perfect Nash equilibrium in this setting.

However, we have the following asymmetric equilibrium. For all \( t \geq 0 \), let

\[
\alpha^i_t(u) = \begin{cases} 
\chi_{B_1}(Z_u) & \text{if } u < T_{z_{A_1}}^{t_A}, \\
\frac{L(Z_u) - F(Z_u)}{L(Z_u) - C(Z_u)} & \text{if } T_{z_{A_1}}^{t_A} \leq u < T_{z_{A_1}}^{t_{A_1}}, \\
\chi_{B_2}(Z_u) & \text{if } T_{z_{A_1}}^{t_{A_1}} \leq u < T_{z_{A_2}}^{t_{A_2}}, \\
\frac{L(Z_u) - F(Z_u)}{L(Z_u) - C(Z_u)} & \text{if } T_{z_{A_2}}^{t_{A_2}} \leq u < T_{z_{A_2}}^{t_{A_2}}, \\
\chi_{B_3}(Z_u) & \text{if } T_{z_{A_2}}^{t_{A_2}} \leq u 
\end{cases}
\]

and

\[
\alpha^j_t(u) = \begin{cases} 
0 & \text{if } u < T_{z_{A_1}}^{t_A}, \\
\frac{L(Z_u) - F(Z_u)}{L(Z_u) - C(Z_u)} & \text{if } T_{z_{A_1}}^{t_A} \leq u < T_{z_{A_1}}^{t_{A_1}}, \\
0 & \text{if } T_{z_{A_1}}^{t_{A_1}} \leq u < T_{z_{A_2}}^{t_{A_2}}, \\
\frac{L(Z_u) - F(Z_u)}{L(Z_u) - C(Z_u)} & \text{if } T_{z_{A_2}}^{t_{A_2}} \leq u < T_{z_{A_2}}^{t_{A_2}}, \\
0 & \text{if } T_{z_{A_2}}^{t_{A_2}} \leq u, 
\end{cases}
\]

where \( i \neq j \). In the expression above, \( \chi \) is the indicator function, and

\[
B_1 = \{ y \in (0, z_{A_1}) \mid L(y) \geq E[e^{-rT^y(z)} L(z)] \text{ for all } z \in (0, z_{A_1}) \}, \\
B_2 = \{ y \in [z_{A_1}, z_{A_2}) \mid L(y) \geq E[e^{-rT^y(z)} L(z)] \text{ for all } z \in [z_{A_1}, z_{A_2}) \}, \\
B_3 = \{ y \in [z_{A_2}, \infty) \mid L(y) \geq E[e^{-rT^y(z)} L(z)] \text{ for all } z \in [z_{A_2}, \infty) \},
\]

where \( T^y(z) \) is the expected hitting time for the demand process \( Z_u \) to reach \( z \), given that its current value is \( y \).

Proof The proof consists of two parts:

1. There is no subgame perfect symmetric Nash equilibrium:

We start by showing that no symmetric equilibrium exist. For this, let \( z_t \) be such that

\[
C(z_t) > \sup\{L(z) \mid z \in (0, z_{A_2})\},
\]

(19)

and assume that there is a symmetric Nash equilibrium, i.e. simple strategies \( \alpha_1, \alpha_2 \) such that \( \alpha^i_t(u) = \alpha^j_t(u) = \alpha^\ell_t(u) \) for all \( u \).

- If \( \tau(t) = \infty \), i.e. \( \alpha^\ell_t(u) = 0 \) for all \( u \geq t \), then both firms will regret their strategy. This follows since such a strategy \( s^\ell(\omega) \) gives

\[
V_i(t, s^\ell(\omega)) = 0
\]

for \( i = 1, 2 \). If for instance firm 1 instead choose \( \alpha^1_t(t) = 1 \), then \( \tau(t) = t \) and the payoff becomes \( e^{-rt} L(z_t) > 0 \) instead, which is better. Thus, we must have \( \tau(t) < \infty \).
4 THE STOCHASTIC GAME 4.2 The case with a high monopoly benefit

The asymmetric strategy is an asymmetric subgame perfect Nash equilibrium. Based on the form of the functions $u(t, s, \omega)$, we can show that the described strategies is an asymmetric subgame perfect Nash equilibrium.

Thus, we have shown that there does not exist any symmetric subgame perfect Nash equilibrium.

2. The asymmetric strategy is an asymmetric subgame perfect Nash equilibrium:

Next, we show that the described strategies is an asymmetric subgame perfect Nash equilibrium. Based on the form of the functions $\alpha_1^t, \alpha_2^t$, it is natural to classify the different time intervals into two categories:

- Category 1, where the firms' strategies are symmetric. That is, the time intervals $[T_{t_{\min}}^{z_{\min}}, T_{t_{\max}}^{z_{\max}}]$ and $[T_{t_{\min}}^{\alpha_1}, T_{t_{\max}}^{\alpha_2}]$.

- Category 2, where the firms' strategies are not symmetric. That is, the time intervals $(0, T_{t_{\min}}^{\alpha_1}), [T_{t_{\max}}^\alpha, T_{t_{\max}}^{z_{\max}}]$ and $[T_{t_{\max}}^{z_{\max}}, \infty)$.

We now consider the two categories of time intervals separately.

- Category 1. For $u \in [T_{t_{\min}}^{z_{\min}}, T_{t_{\max}}^{z_{\max}}] \cup [T_{t_{\min}}^{\alpha_1}, T_{t_{\max}}^{\alpha_2}]$, the strategies are chosen symmetrically in such a way that

$$V_i(t, s^t(\omega)) = V_j(t, s^t(\omega)) = E_i[e^{-rt}F(Z_t)].$$

Abbreviating and writing $s^t(\omega) = s = (s_i, s_j)$, we note that $s$ is chosen such that

$$V_i(t, s_i, s_j) = V_i(t, s) = V_j(t, s) = V_j(t, s_i, s_j'),$$

where $s_i', s_j'$ are any other strategy chosen by firm $i$ and firm $j$ respectively. This can be verified by evaluating the expression in (17). That is, the strategy $s$ has the property that if only one firm changes strategy.
4.2 The case with a high monopoly benefit

The payoff of this firm will be unaltered. Thus, for any of the firms there is nothing to be attained by a change of strategy for time intervals belonging to Category 1.

Category 2. For \( u \in (0, T_{A_1}^{z_{min}}) \cup [T_{A_2}^{z_{min}} T_{A_2}^{z_{max}}) \cup [T_{A_2}^{z_{max}}, \infty) \), the strategy of firm \( i \) is chosen in such a way that the firm will invest as long as investing and becoming leader is weakly better than waiting with the investment. Otherwise, firm \( i \) will wait with the investment. Since firm \( j \) is always waiting in time intervals belonging to Category 2, by the definition of the strategy, firm \( i \) cannot be better off by any alternative strategy. Also, since the firms are ex ante identical, firm \( j \) will not gain by choosing a strategy such that \( \tau_j(u) < \tau_i(u) \) for any relevant \( u \). And since we have \( L < F \) in this interval, having \( \alpha_j(u) = 0 \) at times \( u \) where \( \alpha_i(u) > 0 \) is an optimal strategy for firm \( j \). We deduce that no firm gains by a change of strategy on time intervals belonging to Category 2.

We conclude that the described strategy is a pure subgame perfect Nash equilibrium.

For values \( z_t \in A_1 \cup A_2 \) the outcome is just as in the standard preemption game described in the literature, see e.g. Huisman et al. [11]. However, for all other starting values of \( z_t \) the situation is very different. Due to the information spillover and lower price of investment, both firms have incentives to be the follower. Consequently, we get a situation where the firms need to weight the cost of investing before the other firm, versus the cost of waiting too long. One solution of this dilemma is for one firm to refuse to take any action at all, in which case the other firm behaves as in a monopoly setting, meaning the role as leader will be taken. How this will be done in practice, when both firms are equal, is an open question. In our described Nash equilibrium, firm \( j \) has the characteristic of being more patient, while firm \( i \) is more eager to invest quickly.

In our described equilibrium, the timing of the investment may become peculiar. If, for instance, \( B_2 \neq [z_{A_1}^{z_{max}}, z_{A_2}^{z_{min}}] \) (how \( B_2 \) looks depends on the parameters of the problem), then we have a scenario where

- no investment occurs for low values of \( z_t \)
- investment occurs when \( z_t \in [z_{min}, z_{max}] \)
- for some value \( z_t \in (z_{max}, z_{A_2}^{z_{max}}) \) no investment occurs
- investment occurs for \( z_t \in (z_{min}, z_{A_1}^{z_{min}}) \).

Thus a "vacuum" arises, where firms are happy to invest for lower and higher market demand levels, but not for intermediate market sizes. The explanation for such a vacuum is that in the set \( A_1 \cup A_2 \) the firms are preempted to invest immediately, since being leader is the most beneficial. Outside of this set the preemption effect vanishes, as firms are reluctant to invest since being the follower is more beneficial. In this region and in our described equilibrium, firm \( i \) will behave as a monopolist having the payoff function \( \min\{L(z_t), F(z_t)\} \) for all values \( z_t \), given that firm \( j \) is determined to become the follower.
5 Conclusion

In this paper, we studied a duopoly investment model with uncertainty and two alternative investments. Being the first firm to invest gives a monopoly benefit for a period of time, while the follower firm attains information and cost reduction benefits. We have characterized the payoff functions for both the leader and follower firm.

Furthermore, we have considered a game where the firms can choose when to invest, and hence influence whether they become the leader or the follower. The scenario we study leads to a more complex investment structure than what has been studied in previous literature. We show that no pure symmetric subgame perfect Nash equilibrium exists. However, an asymmetric equilibrium is characterized in Theorem 1. In this equilibrium, two disjoint intervals of market demand levels give rise to preemptive investment behavior of the firms, while the firms otherwise tend to be more reluctant to be the first investor.

References

1. d’Aspremont, C. and Jacquemin, A. Cooperative and non-cooperative R&D in duopoly with spillovers, The American Economic Review, vol. 78 (1988).
2. Bessen, J. and Maskin, M. Sequential innovation, patents and imitation, Rand Journal of Economics, vol.40, pp. 611-635 (2009).
3. Chevalier-Roignant, B. and Trigeorgis, L. Competitive Strategy: Options and Games, MIT press (2011).
4. Décamps, J. P., Mariotti, T. and Villeneuve, S., Irreversible investment in alternative projects, Economic theory, vol. 28, pp. 425-448 (2006).
5. Dixit, A. and Pindyck, R. Investment under uncertainty, Princeton University Press, Princeton (1994).
6. Femminis, G. and Martini, G. Irreversible investment and R&D spillovers in a dynamic duopoly, Journal of Economic Dynamics and Control, vol. 35, pp. 1061-1090 (2011).
7. Fudenberg, D. and Tirole, J. Preemption and rent equalization in the adoption of new technology, Review of Economic Studies, vol. 53, pp. 383-401 (1985).
8. Hoppe, H. C. Second-mover advantages in the strategic adoption of new technology under uncertainty, International Journal of Industrial Organization, vol. 18, pp. 315-338 (2000).
9. Huisman, K. J. M. and Kort, P. M. Strategic technology adoption taking into account future technological improvements: a real options approach, European Journal of Operational Research, vol. 159, pp. 705-728 (2004).
10. Huisman, K. J. M., Kort, P. M. and Thijsen, J. J. J. The effects of information on strategic investment and welfare, Economic theory, vol. 28, pp. 399-424 (2006).
11. Huisman, K. J. M., Kort, P. M. and Thijsen, J. J. J. Symmetric equilibrium strategies in game theoretic real option models, Journal of Mathematical Economics, vol. 48, pp. 219-225 (2012).
12. Jeanblanc, M. Credit risk, Lecture notes, Lisbon, www.maths.univ-evry.fr/pages_perso/jeanblanc/conferences/lisbon.pdf.
13. Jin, J. and Troege, M. R&D competition and endogenous spillovers, The Manchester School, vol. 74, pp. 40-51 (2006).
14. Nishihara, M. and Ohyama, A. R&D competition in alternative technologies: A real options approach, Journal of the Operations Research of Japan, vol. 51, pp. 55-80 (2007).
15. Øksendal, B. Stochastic Differential Equations, Springer, Berlin Heidelberg (2007).
16. Reinganum, J. F. On the diffusion of new technology: A game theoretic approach, The Review of Economic Studies, vol. 48, no. 3, pp. 395-405 (1981).
17. Reinganum, J. F. *The timing of innovation: Research, development, and diffusion*, Chapter 14, Handbook of Industrial Organization, Elsevier, Volume 1 (1989).
18. Sigman, K. *IEOR4700: Notes on Brownian motion*, Columbia, [www.columbia.edu/~ks20/FE-Notes/4700-07-Notes-BM.pdf](http://www.columbia.edu/~ks20/FE-Notes/4700-07-Notes-BM.pdf) (2006).
19. Yap, Y. J., Luckraz, S. and Troy, S. K. Long-term research and development incentives in a dynamic Cournot duopoly, Economic Modeling, vol. 39, pp. 8-18 (2014).