A LIFTED SQUARE FORMULATION FOR CERTIFIABLE SCHUBERT CALCULUS

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Abstract. Formulating a Schubert problem as the solutions to a system of equations in either Plücker space or in the local coordinates of a Schubert cell usually involves more equations than variables. Using reduction to the diagonal, we previously gave a primal-dual formulation for Schubert problems that involved the same number of variables as equations (a square formulation). Here, we give a different square formulation by lifting incidence conditions which typically involves fewer equations and variables. Our motivation is certification of numerical computation using Smale’s $\alpha$-theory.

A $m \times n$ matrix $M$ with $m \geq n$ is rank-deficient if and only if all of its $n \times n$ minors vanish. This occurs if and only if there is a nonzero vector $v \in \mathbb{C}^n$ with $Mv = 0$. There are $\binom{m}{n}$ minors and each is a polynomial of degree $n$ in the $mn$ entries of $M$. In local coordinates for $v$, the second formulation gives $m$ bilinear equations in $mn + n - 1$ variables, and the map $(M, v) \mapsto M$ is a bijection over an open dense set of matrices of rank $n-1$. The set of rank-deficient matrices has dimension $(m+1)(n-1)$, which shows that the second formulation is a complete intersection, while the first is not if $m > n$. The principle at work here is that adding extra information may simplify the description of a degeneracy locus.

Schubert varieties in the flag manifold are universal degeneracy loci [6]. We explain how to add information to a Schubert variety to simplify its description in local coordinates. This formulates membership in a Schubert variety as a complete intersection of bilinear equations and formulates any Schubert problem as a square system of bilinear equations. This lifted formulation is both different from and typically significantly more efficient than the primal-dual square formulation of [8], as we demonstrate in Section 3.

Our motivation comes from numerical algebraic geometry [15], which uses numerical analysis to represent and manipulate algebraic varieties on a computer. It does this by solving systems of polynomial equations and following solutions along curves. For numerical stability, low degree polynomials are preferable to high degree polynomials. More essential is that Smale’s $\alpha$-theory [14] enables the certification of computed solutions to square systems of polynomial equations [10], and therefore efficient square formulations of systems of polynomial equations are desirable. Furthermore, the estimates used in implementations of $\alpha$-theory simplify for bilinear systems, as explained in [8, Rem. 2.11]. Interestingly, formulations as square systems of bilinear equations may also aid Gröbner basis
computations. Faugère, et al. [5] gave improved complexity bounds for zero-dimensional bilinear systems.

The Schubert calculus is a well-understood, rich family of enumerative problems which has served as a laboratory to study new phenomena in enumerative geometry [13]. Problems in Schubert calculus lead to highly-structured systems of polynomials that are challenging to study. Traditional formulations of most problems in Schubert calculus are not complete intersections, and those which are complete intersections have far fewer solutions than predicted by the BKK bound [4]—this is demonstrated in Table 2 of [16].

Square formulations of Schubert problems also enable the certified computation of monodromy, using either the algorithm of Beltrán and Leykin [2, 3] or the Newton homotopies of Hauenstein and Liddell [9]. This will in turn enable the certified computation of Galois groups [12, 13]. Because general degeneracy loci are pullbacks of Schubert varieties, these square formulations may lead to formulations of more general problems involving degeneracy loci as square systems of polynomials.

In Section 1 we explain the traditional formulation of Schubert problems using Stiefel coordinates and determinantal equations expressing rank conditions. In Section 2 we give our new lifted square formulation for Schubert varieties and Schubert problems, illustrating with some examples. In Section 3 we compare the efficiency of the lifted formulation with the primal-dual formulation of [8], demonstrating that the lifted formulation typically involves fewer equations and variables, and through three examples that computations using it consume fewer resources.

1. Determinantal formulation of Schubert problems

The Schubert calculus involves all questions of determining the (flags of) linear subspaces of a vector space that have specified positions with respect to other (fixed, but general) flags of linear subspaces. We briefly sketch the Schubert calculus, Stiefel coordinates for Schubert varieties, and traditional determinantal formulations of Schubert problems. We work over the complex numbers for convenience and motivation from numerical algebraic geometry. Our formulations and main result are valid over any field, if we replace claims of transversality by properness (expected dimension) when the field has positive characteristic. This is because Kleiman’s result showing transversality of the intersection of general translates becomes properness in positive characteristic [11]. For the Grassmannian, we retain transversality as Vakil [17] proved that general translates of Schubert varieties in a Grassmannian intersect transversally in any characteristic.

1.1. Schubert problems. Fix an integer $n$ and a sequence $a_*: a_1 < \cdots < a_s < n$ of positive integers. A flag of type $a_*$ is a sequence of linear subspaces

$$E_*: E_{a_1} \subset E_{a_2} \subset \cdots \subset E_{a_s} \subset \mathbb{C}^n,$$

where $\dim E_{a_j} = a_j$. A flag is complete if $a_* = \{1, 2, \ldots, n-1\}$. Given a flag $E_*$ of type $a_*$, there is a list $(e_1, \ldots, e_{a_s})$ of independent vectors such that $E_{a_j}$ is the linear span of $\{e_1, \ldots, e_{a_j}\}$ for each $1 \leq j \leq s$. In this case, write $E_* = \langle\langle e_1, \ldots, e_{a_s}\rangle\rangle_{a_*}$. The set of all
flags of type $a_\bullet$ is an algebraic manifold $\mathbb{F}\ell(a_\bullet; n)$ of dimension

$$\dim(a_\bullet) := \sum_{j=1}^s (n - a_j)(a_j - a_{j-1}) = n \cdot a_s - \sum_{i=1}^s a_j(a_j - a_{j-1}),$$

where $a_0 := 0$. When $s = 1$, the flag manifold $\mathbb{F}\ell(a_\bullet; n)$ is the Grassmannian of $a_1$-planes in $\mathbb{C}^n$, $\mathrm{Gr}(a_1; n)$, which has dimension $a_1(n-a_1)$.

The position of a flag $E_\bullet$ of type $a_\bullet$ with respect to a complete flag $F_\bullet$ is the $n \times s$ array of nonnegative integers $\dim(F_i \cap E_{a_j})$ for $i = 1, \ldots, n$ and $j = 1, \ldots, s$. These positions are encoded by permutations $w \in S_n$ with descents in $a_\bullet$. For such a permutation $w$, $w(i) > w(i+1)$ implies that $i = a_j$, for some $j$. Write $W^n_\bullet$ for this set of permutations. Given $w \in W^n_\bullet$ and a complete flag $F_\bullet$, we have the Schubert cell,

$$X_w^{\circ}F_\bullet := \{ E_\bullet \in \mathbb{F}\ell(a_\bullet) \mid \dim(F_i \cap E_{a_j}) = \#\{ k \leq a_j \mid w(k) \leq i \} \}.$$  

The Schubert variety $X_w^{\circ}F_\bullet$ is the closure of $X_w^{\circ}F_\bullet$ and is obtained by replacing the dimension equality in (1.2) with an inequality $\geq$. This has dimension $\ell(w) := \#\{ k < j \mid w(k) > w(j) \}$, the number of inversions of $w$, and thus codimension $|w| := \dim(a_\bullet) - \ell(w)$.

A Schubert problem is a list $w := (w_1, \ldots, w_r)$ of elements $w_i \in W^n_\bullet$ for $i = 1, \ldots, r$ satisfying $|w_1| + \cdots + |w_r| = \dim(a_\bullet)$. Given a Schubert problem $w$, Kleiman showed [11] there is an open dense subset of the product of flag manifolds consisting of $r$-tuples of flags $(F_1^{w_1}, \ldots, F_r^{w_r})$ such that the intersection

$$X_{w_1}^{\circ}F_1^{w_1} \cap X_{w_2}^{\circ}F_2^{w_2} \cap \cdots \cap X_{w_r}^{\circ}F_r^{w_r}$$

is transverse. Kleiman’s Theorem implies that the points of intersection lie in the corresponding Schubert cells—we lose nothing (for general flags) if we restrict to Schubert cells, and the same reasoning allows us to restrict to any dense open subset of the Schubert varieties. The number of points in the intersection is independent of the choice of general flags and this number may be determined by algorithms in the Schubert calculus.

### 1.2. Determinantal formulation of a Schubert variety

Suppose that $\mathcal{X}$ is a set of $n \times a_s$ matrices $x$ whose column vectors $e_1(x), \ldots, e_{a_s}(x)$ are independent. The association

$$\mathcal{X} \ni x \mapsto \langle \langle e_1(x), \ldots, e_{a_s}(x) \rangle \rangle_{a_\bullet} =: E_\bullet(x)$$

defines a map $\mathcal{X} \to \mathbb{F}\ell(a_\bullet; n)$. We call $\mathcal{X}$ Stiefel coordinates for the closure of the image of this map. We have $E_{a_j}(x) := \mathrm{span}\{e_1(x), \ldots, e_{a_j}(x)\}$, and we also write $E_{a_j}(x)$ for the $n \times a_j$ matrix whose columns are $e_1(x), \ldots, e_{a_j}(x)$. Whether we intend the subspace or the matrix will be clear from context.

Suppose that a set $\mathcal{X}$ of $n \times a_s$ matrices forms Stiefel coordinates for some subset $X \subset \mathbb{F}\ell(a_\bullet; n)$. Let $F_\bullet$ be a flag with a basis $f_1, \ldots, f_n$ that forms the columns of a $n \times n$ matrix. Write $F_k$ both for the $k$-dimensional subspace of the flag $F_\bullet$ and for the $n \times k$ matrix with columns $f_1, \ldots, f_k$.

For $w \in W^n_\bullet$, set $r_{i,j}(w) := \#\{ k \leq a_j \mid w(k) \leq i \}$. Then $E_\bullet \in X_wF_\bullet$ if and only if

$$\dim F_i \cap E_{a_j} \geq r_{i,j}(w) \quad i = 1, \ldots, n \quad j = 1, \ldots, s.$$
Then the condition on \( x \in \mathcal{X} \) that \( E_\bullet(x) \in X_w F_\bullet \) is
\[
\text{rank} \left( F_i \mid E_{a_j}(x) \right) \leq i + a_j - r_{i,j}(w) \quad i = 1, \ldots, n \quad j = 1, \ldots, s.
\]
This is given by the vanishing of minors of \((F_i \mid E_{a_j})\) of size \( i + a_j - r_{i,j}(w) + 1 \). These are polynomials in the entries of \( x \in \mathcal{X} \). Not all such minors are needed. Even if redundant minors are eliminated, the number that remains will in general exceed \(|w|\).

This is discussed for Grassmannians in Section 1.3 of [8], where it is shown that after removing redundancy, \(|w| = 0, 1 \) or \( a_1 = 1, n-1 \) are the only cases for which this number of minors equals \(|w|\). In Section 3.1 we present a typical example minimally requiring 17 minors, but where \(|w| = 4\).

1.3. Stiefel coordinates for Schubert varieties. A Schubert cell \( X_w^{\circ} F_\bullet \) has a description in terms of bases. For a flag \( F_\bullet \), set \( F_0 := \{0\} \).

Lemma 1.1. Let \( w \in W^a \bullet \) and \( F_\bullet \) be a complete flag. Then a flag \( E_\bullet \) of type \( a_\bullet \) lies in \( X_w^{\circ} F_\bullet \) if and only if there exist vectors \((e_1, \ldots, e_s)\) with \( e_k \in F_{w(k)} \setminus F_{w(k)-1} \) for \( k = 1, \ldots, a_s \) and \( E_\bullet = \langle \langle e_1, \ldots, e_s \rangle \rangle_{a_\bullet} \).

Proof. Let \( e_1, \ldots, e_{a_s} \) be such a collection of vectors with \( e_k \in F_{w(k)} \setminus F_{w(k)-1} \). As \( w \) is a permutation, these vectors are linearly independent. If \( E_\bullet = \langle \langle e_1, \ldots, e_s \rangle \rangle_{a_\bullet} \), then
\[
F_i \cap E_{a_j} = \langle e_k \mid k \leq a_j \text{ and } w(k) \leq i \rangle,
\]
and so \( E_\bullet \in X_w^{\circ} F_\bullet \). Conversely, if \( E_\bullet \in X_w^{\circ} F_\bullet \), observe that if \( a_{j-1} < k \leq a_j \), then the condition that \( E_\bullet \) lies in the Schubert cell and \( w \in W^a \bullet \) implies that
\[
\dim F_{w(k)} \cap E_{a_j} = 1 + \dim F_{w(k)-1} \cap E_{a_j}.
\]
For each such \( j \) and \( k \), let \( e_k \) be a nonzero vector that, together with \( F_{w(k)-1} \cap E_{a_j} \), spans \( F_{w(k)} \cap E_{a_j} \). Then \( e_k \in F_{w(k)} \setminus F_{w(k)-1} \), and \( E_\bullet = \langle \langle e_1, \ldots, e_s \rangle \rangle_{a_\bullet} \). \( \square \)

Lemma 1.1 leads to the usual Stiefel coordinates for Schubert cells [7, Ch. 10]. Given \( w \in W^a \bullet \), let \( \mathcal{X}_w \) be the collection of \( n \times a_s \) matrices \((x_{i,j})\) such that
\[
\begin{align*}
x_{w(k),k} & = 1 \text{ for } k = 1, \ldots, a_s \\
x_{i,j} & = 0 \text{ if } i > w(j) \text{ or } i = w(k) \text{ for some } k < j,
\end{align*}
\]
and \( x_{i,j} \) is otherwise unconstrained. For example, here are typical matrices in \( \mathcal{X}_w \) for \( w = 5724613 \) with \( a_\bullet = (2, 5) \) and \( w = 3652471 \) with \( a_\bullet = (2, 3, 5, 6) \).

\[
\begin{pmatrix}
x_{1,1} & x_{1,2} & x_{1,3} & x_{1,4} & x_{1,5} \\
x_{2,1} & x_{2,2} & 1 & 0 & 0 \\
x_{3,1} & x_{3,2} & 0 & x_{3,4} & x_{3,5} \\
x_{4,1} & x_{4,2} & 0 & 1 & 0 \\
1 & 0 & 0 & 0 & 0 \\
0 & x_{6,2} & 0 & 0 & 1 \\
0 & 1 & 0 & 0 & 0
\end{pmatrix}
\quad \begin{pmatrix}
x_{1,1} & x_{1,2} & x_{1,3} & x_{1,4} & x_{1,5} & x_{1,6} \\
x_{2,1} & x_{2,2} & x_{2,3} & 1 & 0 & 0 \\
1 & 0 & 0 & 0 & 0 & 0 \\
0 & x_{4,2} & x_{4,3} & 0 & 1 & 0 \\
0 & x_{5,2} & 1 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1
\end{pmatrix}
\]

It is an exercise to show that if \( x \in \mathcal{X}_w \), then \( E_\bullet(x) \in X_w^{\circ} F_\bullet \), where \( F_\bullet \) is the standard coordinate flag in \( \mathbb{C}^n \). Suppose that \( E_\bullet \in X_w^{\circ} F_\bullet \) and \( E_\bullet = \langle \langle e_1, \ldots, e_{a_s} \rangle \rangle_{a_\bullet} \) as in Lemma 1.1.
Let $y$ be a $n \times a_s$ matrix with column vectors $e_1, \ldots, e_{a_s}$. If we reduce each column of $y$ modulo those to its left, we obtain a matrix in $X_w$. We summarize this discussion.

**Lemma 1.2.** For any $w \in W^a$, the set $X_w$ gives Stiefel coordinates for the Schubert variety $X_w F_\bullet$, where $F_\bullet$ is the standard coordinate flag. The map $X_w \to X_w F_\bullet$ defined by $x \mapsto E_\bullet(x)$ is a bijection between $X_w$ and the Schubert cell $X_w F_\bullet$.

An entry $(i, j)$ is unconstrained for matrices in $X_w$ when $i < w(j)$ and there is no $k < j$ with $i = w(k)$. As $w$ is a permutation, there is some $k > j$ with $i = w(k)$. Thus the unconstrained entries in $X_w$ correspond to inversions in the permutation $w$, and so we conclude that $\dim X_w = \ell(w)$, the number of inversions in $w$.

**1.4. Determinantal formulation of a Schubert problem.** Let $w = (w_1, \ldots, w_r)$ be a Schubert problem and suppose that $F_1^\bullet, \ldots, F_r^\bullet$ are general complete flags. Choosing a basis for $\mathbb{C}^n$, if necessary, we may assume that $F_1^\bullet$ is the standard coordinate flag. Let $F_2^\bullet, \ldots, F_r^\bullet$ be $n \times n$ matrices corresponding to the flags of the same name. Then, in the local Steifel coordinates $X_{w_1} F_1^\bullet$ for $X_{w_1} F_1^\bullet$, the instance

$$X_{w_1} F_1^\bullet \cap X_{w_2} F_2^\bullet \cap \cdots \cap X_{w_r} F_r^\bullet$$

of the Schubert problem is given by the rank conditions

$$\text{rank} \left( F_i^k \mid E_{a_j}(x) \right) \leq i + a_j - r_{i,j}(w_k)$$

for $i = 1, \ldots, n$, $j = 1, \ldots, s$, and $k = 2, \ldots, r$. These rank conditions are equivalent to the vanishing of minors of appropriate sizes of these matrices. As we discussed, this typically involves more equations than variables. Call this the **determinantal formulation** of the Schubert problem.

**2. Lifted square formulations for Schubert problems**

We give a new formulation for Schubert varieties as complete intersections in that the number of variables is equal to the sum of the dimension of the Schubert variety and the number of equations. These equations are bilinear when we use Stiefel coordinates for the flag manifold. This leads to a square formulation of any Schubert problem. In Subsection 2.2 we explain an improvement to this formulation.

Fix a sequence $a_\bullet: a_1 < \cdots < a_s < n$ and let $E_\bullet$ be a flag of type $a_\bullet$ in $\mathbb{C}^n$. A complete flag $F_\bullet$ in $\mathbb{C}^n$ induces complete flags on each quotient vector space $E_{a_j}/E_{a_{j-1}}$ for $j = 1, \ldots, s$. The subspaces in the induced flag on $E_{a_j}/E_{a_{j-1}}$ are

$$\left( (E_{a_j} \cap F_k) + E_{a_{j-1}} \right)/E_{a_{j-1}} \quad \text{for } k = 1, \ldots, n.$$ 

If $w$ is the unique permutation in $W^a$ such that $E_\bullet \in X_w F_\bullet$, so that $E_\bullet$ and $F_\bullet$ have relative position $w$, then the subspaces (2.1) in the flag on $E_{a_j}/E_{a_{j-1}}$ induced by $F_\bullet$ are

$$\left( (E_{a_j} \cap F_{w(k)}) + E_{a_{j-1}} \right)/E_{a_{j-1}} \quad \text{for } a_{j-1} < k \leq a_j.$$ 

(Recall that $a_{j-1} < i < k \leq a_j$ implies that $w(i) < w(k)$ and thus $F_{w(i)} \subset F_{w(k)}$.) When $E_\bullet = \langle \langle e_1, \ldots, e_{a_j} \rangle \rangle_{a_\bullet}$ for independent vectors $e_1, \ldots, e_{a_j}$, we have another complete flag in each quotient space $E_{a_j}/E_{a_{j-1}}$ for $j = 1, \ldots, s$, whose subspaces are

$$\langle \langle e_k, e_{k+1}, \ldots, e_{a_j} \rangle \rangle_{a_\bullet} + E_{a_{j-1}}/E_{a_{j-1}} \quad \text{for } a_{j-1} < k \leq a_j.$$ 

### Subsection 2.2

In this subsection, we explain an improvement to the formulation in Subsection 2.1. Instead of using Stiefel coordinates, we use determinantal coordinates. Let $X_{w_1} F_1^\bullet$ be the Schubert cell corresponding to the permutation $w_1$.

**Theorem 2.2.** Let $w_1, w_2 \in W^a$ be permutations such that $w_1 F_1^\bullet \cap w_2 F_1^\bullet$ is non-empty. Then the determinantal formulation of $w_1 F_1^\bullet \cap w_2 F_1^\bullet$ is given by

$$\text{det} \left( F_i^k \mid E_{a_j}(x) \right) = 0$$

for $i = 1, \ldots, n$, $j = 1, \ldots, s$, and $k = 2, \ldots, r$. These determinants are equivalent to the vanishing of minors of appropriate sizes of these matrices. As we discussed, this typically involves more equations than variables. Call this the **determinantal formulation** of the Schubert problem.
We say that \((e_1, \ldots, e_{a_s})\) and \(F_*\) are in \(a_*\)-general position if for each \(j = 1, \ldots, s\), the two flags (2.1) and (2.2) on \(E_{a_j}/E_{a_j-1}\) are in linear general position. That is, an intersection \(G \cap H\) of subspaces, one from each flag, has the expected dimension \(\dim(G) + \dim(H) - \dim(E_{a_j}/E_{a_j-1})\).

The set of those \((e_1, \ldots, e_{a_s})\) with \(E_* = \langle\langle e_1, \ldots, e_{a_s}\rangle\rangle_{a_*}\) that are in \(a_*\)-general position with \(F_*\) forms an open and dense subset of those \((e_1, \ldots, e_{a_s})\) with \(E_* = \langle\langle e_1, \ldots, e_{a_s}\rangle\rangle_{a_*}\). Indeed, there is a dense open subset of the general linear group giving linear combinations of the sublist \(e_{a_{j-1}+1}, \ldots, e_{a_j}\) which induce a flag on \(E_{a_j}/E_{a_j-1}\) in linear general position with the flag induced by \(F_*\).

2.1. Lifted square formulation. The lifted square formulation relies upon the following lemma. For a number \(k \leq a_s\), define \([k]_{a_*} := \min\{a_j \mid k \leq a_j\}\), which is the smallest number in \(a_*\) that is at least as large as \(k\).

**Lemma 2.1.** Suppose that \(E_* = \langle\langle e_1, \ldots, e_{a_s}\rangle\rangle_{a_*}\) is a flag of type \(a_*\), \(F_*\) is a complete flag in \(a_*\)-general position with \((e_1, \ldots, e_{a_s})\), and \(w \in W^{a_*}\). Then \(E_* \in X^o_w F_*\) if and only if for each \(k = 1, \ldots, a_s\) there are numbers \(\alpha_{k,i}\) for \(i \leq [k]_{a_*}\) with \(w(k) < w(i)\) such that

\[
(2.3) \quad g_k := e_k + \sum_{i \leq [k]_{a_*}, w(k) < w(i)} \alpha_{k,i} e_i,
\]

where \(g_k \in F_{w(k)} \setminus F_{w(k)-1}\). Furthermore these numbers \(\alpha_{k,i}\) are the unique numbers with this property.

We illustrate this lemma with two examples.

**Example 2.2.** Suppose that \(E_3 := \langle e_1, e_2, e_3 \rangle\) lies in the Schubert cell \(X_{358,12467}^0 F_*\) in the Grassmannian \(\text{Gr}(3; 8)\) and \((e_1, e_2, e_3)\) is in general position with \(F_*\). Then there are constants \(\alpha_{1,2}, \alpha_{1,3},\) and \(\alpha_{2,3}\) such that if

\[
(2.4) \quad g_1 := e_1 + \alpha_{1,2} e_2 + \alpha_{1,3} e_3, \\
g_2 := e_2 + \alpha_{2,3} e_3, \text{ and} \\
g_3 := e_3,
\]

then \(g_1 \in F_3, g_2 \in F_5,\) and \(g_3 \in F_8 = \mathbb{C}^8\).

View these now as variables and equations for membership in \(X_{358,12467}^0 F_*\). The linear forms defining the subspaces in \(F_*\) give \(5 + 3 + 0 = 8\) equations on the vectors \(e_1, e_2, e_3\) and variables \(\alpha_{1,2}, \alpha_{1,3}, \alpha_{2,3}\). As these linear forms are general, they define a subset of codimension eight which when projected to the Grassmannian gives a subset of codimension five, which is the codimension of \(X_{358,12467}^0 F_*\). \(\diamond\)

**Example 2.3.** Suppose that \(E_* := \langle\langle e_1, e_2, e_3, e_4\rangle\rangle_{2 < 4}\) lies in the Schubert cell \(X_{59,47,12368}^0 F_*\) of the flag manifold \(\mathbb{F}l(2, 4; 9)\) and \((e_1, e_2, e_3, e_4)\) is in general position with \(F_*\). Then there
are constants $\alpha_{1,2}$, $\alpha_{3,1}$, $\alpha_{3,2}$, $\alpha_{3,4}$, and $\alpha_{4,2}$ such that if
\[
g_1 := e_1 + \alpha_{1,2}e_2, \\
g_2 := e_2, \\
g_3 := \alpha_{3,1}e_1 + \alpha_{3,2}e_2 + e_3 + \alpha_{3,4}e_4, \quad \text{and} \\
g_3 := \alpha_{4,2}e_2 + e_4,
\]
then $g_1 \in F_5$, $g_2 \in F_9 = \mathbb{C}^3$, $g_3 \in F_4$, and $g_4 \in F_7$. As a formulation for membership in $X_{59.47.12368} F_\bullet$, the linear forms defining the $F_i$ give $4 + 0 + 5 + 2 = 11$ equations on the vectors $e_1, e_2, e_3, e_4$ and five variables $\alpha_{k,i}$. As these forms are general, they define a subset of codimension eleven that when projected to $\mathbb{P} \ell(2,4;9)$ gives a subset of codimension six, which is the codimension of $X_{59.47.12368} F_\bullet$. Since the membership equations $(g_i \in F_{w(i)}, \text{etc.})$ are linear in the variables $\alpha_{k,i}$, the fibers over points of $X_{59.47.12368} F_\bullet$ are affine spaces. The equality of dimensions and surjectivity implies that the fiber over a general point is a singleton, which is the unicity assertion in Lemma 2.1.

\begin{proof}[Proof of Lemma 2.1] Suppose first that $g_k \in F_{w(k)} \setminus F_{w(k)-1}$ where $g_1, \ldots, g_a$ are defined using (2.3) for some constants $\alpha_{k,i}$. Then $E_\bullet = \langle\langle g_1, \ldots, g_a\rangle\rangle_{a\bullet}$, as the expressions (2.3) are unitriangular. Lemma 1.1 then implies that $E_\bullet \in X^0_w F_\bullet$.

For the other direction, we use induction on $j$ to construct unique constants $\alpha_{k,i}$ such that the vector $g_k$ defined by (2.3) satisfies $g_k \in F_{w(k)} \setminus F_{w(k)-1}$ for $k \leq a_j$. We will suppose that for each $k \leq a_{j-1}$ there are unique constants $\alpha_{k,i}$ for $i \leq \lceil k \rceil_{a\bullet}$ with $w(k) < w(i)$ such that if $g_k$ is the linear combination (2.3), then $g_k \in F_{w(k)} \setminus F_{w(k)-1}$, and use this to obtain the constants $\alpha_{k,i}$ for $a_{j-1} < k \leq a_j$. This is no assumption in the base case $(j = 1)$ of this construction.

By our assumption on $(e_1, \ldots, e_a)$ and $F_\bullet$, the two flags in $E_{a_j}/E_{a_j-1}$,
\[
E_{a_j-1} \subsetneq E_{a_j} \subsetneq \cdots \subsetneq E_{a_j-1} + \langle e_{a_j} \rangle \subsetneq \cdots \subsetneq E_{a_j-1} + \langle e_{a_j-1+2}, \ldots, e_{a_j} \rangle \subsetneq E_{a_j}, \quad \text{and}
\]
\[
E_{a_j-1} \subsetneq E_{a_j-1} + (F_{w(a_j-1)} \cap E_{a_j}) \subsetneq \cdots \subsetneq E_{a_j-1} + (F_{w(a_j-1)} \cap E_{a_j}) \subsetneq E_{a_j},
\]
are opposite. In particular, for any $a_{j-1} < k, i \leq a_j$, we have that
\[
(2.5) \quad \left( E_{a_j-1} + (F_{w(k)} \cap E_{a_j}) \right) \cap \left( E_{a_j-1} + \langle e_{i}, \ldots, e_{a_j} \rangle \right)
\]
has dimension $\max(0, k+1-i)$ modulo $E_{a_j-1}$. This implies that there are constants $\alpha_{k,\ell}$ for $k < \ell \leq a_j$ and an element $e \in E_{a_j-1}$ such that the sum
\[
(2.6) \quad e_k + \sum_{\ell=k+1}^{a_j} \alpha_{k,\ell} e_\ell + e
\]
lies in $F_{w(k)}$. In fact, the sum (2.6) lies in $F_{w(k)} \setminus F_{w(k)-1}$. Indeed, as $E_\bullet \in X^0_w F_\bullet$, we have that $F_{w(k)-1} \cap E_{a_j} \subsetneq F_{w(k)} \cap E_{a_j}$, and so the dimension of (2.5) drops if we replace $F_{w(k)}$ by $F_{w(k)-1}$. This also implies that the numbers $\alpha_{k,\ell}$ are unique.

The element $e \in E_{a_j-1}$ is some linear combination of $e_1, \ldots, e_{a_j-1}$ and thus also of $g_1, \ldots, g_{a_j-1}$. Since $g_i \in F_{w(i)}$, those $g_i$ with $w(i) < w(k)$ are not needed for the sum (2.6)
to lie in $F_{w(k)}$, and thus there are constants $\beta_i$ for $i \leq a_j-1$ with $w(k) < w(i)$ such that

\begin{equation}
(2.7) \quad g_k := e_k + \sum_{\ell=k+1}^{a_j} \alpha_{k,\ell} e_{\ell} + \sum_{i \leq a_j \atop w(k) < w(i)} \beta_i g_i
\end{equation}

lies in $F_{w(k)} \setminus F_{w(k)-1}$. As each $g_i$ in the second sum lies in $F_{w(i)} \setminus F_{w(i)-1}$, the constants $\beta_i$ are unique. To obtain the expression (2.3) for $g_k$ first use the formula (2.3) for each $g_i$ appearing in (2.7) to rewrite the second sum as a linear combination of $e_{\ell}$ for $\ell \leq a_j-1$ with $w(k) < w(i) < w(\ell)$, and then use that $w \in W^{a_*}$ to see that $\{k+1, \ldots, a_j\}$ is the set of $i$ in the interval $(a_{j-1}, a_j]$ with $w(k) < w(i)$. The unicity of the constants $\alpha_{k,\ell}$ follows from that of the constants $\alpha_{k,\ell}$ and $\beta_i$, and our induction hypothesis. \hfill $\square$

**Remark 2.4.** Lemma 2.1 leads to a square formulation for membership in $X_w F_\bullet$ for flags in $F\ell(a_*; n)$ as follows.

1. Pick Stiefel coordinates $X_{a_*}$ for $F\ell(a_*; n)$. For $x \in X_{a_*}$, we have the partial flag, $E_\bullet(x) = \langle (e_1(x), \ldots, e_{a_s}(x)) \rangle_{a_*} \in F\ell(a_*; n)$.

2. Choose lifting coordinates

\begin{equation}
(2.8) \quad \alpha = \{ \alpha_{k,i} \mid k = 1, \ldots, a_s, i \leq [k]_{a_*} \text{ with } w(i) > w(k) \}
\end{equation}

and form the vectors

$$g_k(x, \alpha) := e_k(x) + \sum_{i \leq [k]_{a_*} \atop w(k) < w(i)} \alpha_{k,i} e_i(x),$$

for $k = 1, \ldots, a_s$.

3. Given independent linear forms $f_1, \ldots, f_n$ such that $F_j$ is defined by the vanishing of $f_{j+1}, \ldots, f_n$, our equations for $E_\bullet(x) \in X_w F_\bullet$ are

$$f_j(g_i(x, \alpha)) = 0 \quad \text{for } i = 1, \ldots, a_s \text{ and } j > w(i).$$

These equations are bilinear in the sets of variables $x \in X_{a_*}$ and $\alpha$. \hfill $\diamond$

**Definition 2.5.** Call the formulation for membership in $X_w F_\bullet$ for flags in $F\ell(a_*; n)$ of Remark 2.4 the **lifted formulation** for a Schubert variety. Write $\alpha(w)$ for the set of lifting coordinates (2.8) and $|\alpha(w)|$ for the number of these coordinates, which is

\begin{equation}
(2.9) \quad |\alpha(w)| = \sum_{k=1}^{a_s} \# \{ i \leq [k]_{a_*} \mid w(i) > w(k) \}.
\end{equation}

**Theorem 2.6.** The lifted formulation for membership in $X_w F_\bullet \subset F\ell(a_*)$ is a complete intersection.

**Proof.** We must show that $\dim X_w F_\bullet$ equals the number of variables minus the number of equations. The number of equations is the sum of codimensions of the $F_{w(k)}$ for $k \leq a_s$,

\begin{equation}
(2.10) \quad \sum_{k=1}^{a_s} n - w(k) = n \cdot a_s - \sum_{k=1}^{a_s} w(k).
\end{equation}
The number of variables is the dimension of \( \mathcal{F}(a\bullet; n) \), as calculated in (1.1)

\[
\dim(a\bullet) = n \cdot a_s - \sum_{j=1}^{s} (a_j - a_{j-1})a_j ,
\]

where \( a_0 = 0 \), plus the number \(|\alpha(w)|\) of the variables \( \alpha_{k,i} \). We rewrite (2.9) as

\[
\sum_{k=1}^{a_s} ([k]a\bullet - \#\{i \leq k \mid w(i) \leq w(k)\})
\]

\[
= \left( \sum_{k=1}^{a_s} [k]a\bullet \right) - \#\{i \leq k \leq a_s \mid w(i) \leq w(k)\}.
\]

The first equality uses that if \( a_j < i < k \leq a_{j+1} \), then \( w(i) < w(k) \), as \( w \in W^{a\bullet} \). We rewrite this as

\[
(\sum_{j=1}^{s} (a_j - a_{j-1})a_j ) - \#\{i \leq k \leq a_s \mid w(i) \leq w(k)\}.
\]

Using that \( w \in W^{a\bullet} \), the linear combination (2.12) + (2.11) − (2.10) becomes

\[
\left( \sum_{k=1}^{a_s} w(k) \right) - \#\{i \leq k \leq a_s \mid w(i) \leq w(k)\}
\]

\[
= \#\{i < k \mid w(i) > w(k)\} = \ell(w) = \dim X_\cdot w F \bullet ,
\]

which completes the proof. \( \square \)

Remark 2.7. The lifted formulation of Remark 2.4 for a Schubert variety leads to a square formulation for Schubert problems, following Subsection 1.4. Suppose that \( w := (w_1, \ldots , w_r) \) is a Schubert problem on \( \mathcal{F}(a\bullet; n) \). Let \( F_1, \ldots , F_r \) be general flags and consider the intersection of Schubert varieties

\[
X_{w_1} F_1 \cap X_{w_2} F_2 \cap \cdots \cap X_{w_r} F_r
\]

Assume that \( F_1 \) is the standard coordinate flag and use Steifel coordinates \( X_{w_1} \) for the Schubert cell \( X_{w_1} F_1 \) to formulate the intersection (2.13). Replacing the determinantal rank conditions for membership in each Schubert variety \( X_{w_2} F_2^2, \ldots , X_{w_r} F_r \) by the lifted square formulation gives the lifted formulation for the Schubert problem \( w \). It uses

\[
\ell(w_1) + |\alpha(w_2)| + \cdots + |\alpha(w_r)|
\]

variables and bilinear equations. \( \diamond \)

Since the intersection (2.13) is transverse, it is zero-dimensional (or empty). This gives the following corollary to Theorem 2.6.

Corollary 2.8. The lifted formulation for membership in the intersection (2.13) is a complete intersection in the local coordinates \( X_{w_1} \).
Remark 2.9. For Grassmannians, there are Stiefel coordinates parametrizing the intersection $X_{w_1}F^1 \cap X_{w_2}F^2$ [8, § 3.1]. These involve $\dim(\text{Gr}(a_1; n)) - |w_1| - |w_2| = \ell(w_1) - |w_2|$ variables and lead to a lifted formulation of (2.13) using
\[
\ell(w_1) - |w_2| + |\alpha(w_3)| + \cdots + |\alpha(w_r)|
\]
variables and bilinear equations. This presents (2.13) as a complete intersection using $|w_2| + |\alpha(w_2)|$ fewer equations and variables than the formulation of Corollary 2.8. ⊓⊔

2.2. Reduced lifted formulation. We introduce an improvement to the lifted square formulation, motivating it through three examples.

Example 2.10. Consider the lifted formulation for the Schubert variety $X_wF_\bullet$ in $\text{Gr}(3; 8)$ where $w = 45812367$. Suppose that $E_3 = \langle e_1, e_2, e_3 \rangle$ where $(e_1, e_2, e_3)$ come from Steifel coordinates $\mathcal{X}$ for $\text{Gr}(3; 8)$ and involve 15 variables. The lifted formulation uses three new variables $\alpha_{1,2}$, $\alpha_{1,3}$, and $\alpha_{2,3}$ as in Example 2.2 and we form the vectors $g_1, g_2, g_3$ as in (2.4). Then $E_3 \in X_wF_\bullet$ if and only if $g_1 \in F_4$, $g_2 \in F_5$, and $g_3 \in F_8$, giving seven equations in $15 + 3$ variables to define the codimension four Schubert variety $X_wF_\bullet$.

It suffices to only require that $g_1$ and $g_2$ lie in $F_5$, for then some linear combination of the two will lie in $F_4$. This dispenses with one equation. Having done this, we may also dispense with the variable $\alpha_{1,2}$, and thereby obtain a reduction of one variable and one equation. Specifically, suppose that
\[
\begin{align*}
g_1 &= e_1 + \alpha_{1,3}e_3, \\
g_2 &= e_2 + \alpha_{2,3}e_3, \quad \text{and} \\
g_3 &= e_3.
\end{align*}
\]
Then $E_3 \in X_wF_\bullet$ if $g_1, g_2 \in F_5$. This gives six equations in $15 + 2$ variables to define $X_wF_\bullet$ in the Steifel coordinates $\mathcal{X}$ for $\text{Gr}(3; 8)$. ⊓⊔

Example 2.11. A similar reduction is possible in Example 2.3. The requirement that $g_3 \in F_4$ may be relaxed to $g_3 \in F_5$, for then some linear combination of $g_3$ and $g_1$ lies in $F_4$. This removes one bilinear equation, and we may dispense with $\alpha_{3,1}$. ⊓⊔

Example 2.12. Now consider the lifted formulation for $X_wF_\bullet$ with $w = 35847126$, which has codimension six in the 21-dimensional flag manifold $\mathbb{F}\ell(3, 5; 8)$. Suppose that $e_1, \ldots, e_5$ are the column vectors from the Steifel coordinates $\mathcal{X}_{3<5}$ for $\mathbb{F}\ell(3, 5; 8)$ and set $E_\bullet := \langle\langle e_1, \ldots, e_5 \rangle\rangle_{3<5}$. The lifted formulation uses seven variables $\alpha_{k,i}$ to form the vectors
\[
\begin{align*}
g_1 &= e_1 + \alpha_{1,2}e_2 + \alpha_{1,3}e_3, \\
g_2 &= e_2 + \alpha_{2,3}e_3, \\
g_3 &= e_3, \\
g_4 &= \alpha_{4,2}e_2 + \alpha_{4,3}e_3 + e_4 + \alpha_{4,5}e_5, \quad \text{and} \\
g_5 &= \alpha_{5,3}e_3 + e_5,
\end{align*}
\]
which are required to lie in the subspaces
\[
g_1 \in F_3, \ g_2 \in F_5, \ g_3 \in F_8, \ g_4 \in F_4, \ \text{and} \ g_5 \in F_7.
\]
such that the consecutive values $w(k)+1,\ldots ,w(k)+m$ for the permutation $w$ occurred at positions $i\leq [k]_{a_s}$. If $i_1,\ldots ,i_m \leq [k]_{a_s}$ are the positions such that $w(i_j) = w(k) + j$, then the condition of Lemma 2.1 that $g_k \in F_{w(k)}$ may be replaced by $g_k \in F_{w(k)+m} = F_{w(i_m)}$, for there is some linear combination of the vectors $g_k, g_{i_1},\ldots , g_{i_m}$ that lies in $F_{w(k)}$. Likewise, the variables $\alpha_{k,i_1},\ldots ,\alpha_{k,i_m}$ are not needed.

We formalize this. Consider vectors $e_1(x),\ldots ,e_{a_s}(x)$ coming from Steifel coordinates $\mathcal{X}$ for some subset $X$ of $\mathbb{F}(a_s,n)$. For each $k = 1,\ldots ,a_s$, let $\beta_k$ be the set of indeterminates

$$
\beta_k := \{\beta_{k,i} \mid i \leq [k]_{a_s} \text{ and } \exists j > [k]_{a_s} \text{ with } w(k) < w(j) < w(i)\},
$$

and set

$$
g_k = g_k(x,\beta) := e_k(x) + \sum_i \beta_{k,i} e_i(x). \tag{2.15}
$$

Write $\beta = \beta(w) = \cup_k \beta_k$ for the set of all these indeterminates and $|\beta(w)|$ for the number of indeterminates in $\beta$.

For a complete flag $F_\bullet$, the reduced lifted formulation for membership in $X_w F_\bullet$ in the Steifel coordinates $\mathcal{X}$ uses the additional variables $\beta(w)$ to form the expressions (2.15), and has the equations given by the membership requirements

$$
g_k(x,\beta) \in F_{w(k)+m(k)}, \text{ for } k = 1,\ldots ,a_s,
$$

where $m(k)$ is the largest number $m$ such that the consecutive values $w(k)+1,\ldots ,w(k)+m$ for the permutation $w$ occur at positions $i \leq [k]_{a_s}$.

The results in Subsection 2.1 hold mutatis mutandis for this reduced lifted formulation of Schubert varieties and Schubert problems and are omitted.

3. Comparison with the primal-dual square formulation

We compare the efficiency of this lifted formulation to the primal-dual formulation of [8]. Both involve added variables and bilinear equations in local Steifel coordinates. We first compare these formulations to the determinantal formulation of a particular Schubert variety. Next, we determine which of the two uses fewer added variables for each Schubert variety on a flag manifold in $\mathbb{C}^9$, and then compare their computational efficiency for solving three Schubert problems, including two from [8]. We almost always observe a gain in efficiency for the lifted formulation over the primal-dual formulation.

We may take advantage of whichever formulation is most efficient for a given Schubert variety, for they are compatible. That is, one may construct a hybrid system of equations for the intersection (2.13) using a lifted formulation to determine membership in some of the Schubert varieties and a primal-dual formulation to determine membership in the
others. Whenever \(|w| = 1\), the determinantal formulation for membership in the hypersurface Schubert variety \(X_w F\) is a single determinant in Steifel coordinates, so there is no need to use an alternative formulation to obtain a square system. In what follows, we will always use the determinantal formulation when \(|w| = 1\).

3.1. **Comparison of three formulations.** We compare the three formulations, determinantal, primal-dual, and lifted, for membership in the Schubert variety \(X_{3478 1256} F\) in \(\text{Gr}(4, 8)\). Let \(X\) be Steifel coordinates for \(\text{Gr}(4, 8)\), which is a set of 8 \(\times\) 4 matrices of rank 4 and \(F\) be a flag in \(\mathbb{C}^8\). The Schubert variety \(X_{3478 1256} F\) consists of those 4-planes \(H\) that meet the fixed 4-plane \(F_4\) in a subspace of dimension 2.

If \(F_4\) is represented as the column space of a 8 \(\times\) 4 matrix, then a 4-plane \(H\) from \(X\) lies in \(X_{3478 1256} F\) if and only if

\[
\text{rank}(H F_4) \leq 6.
\]

*A priori*, each of the 7 \(\times\) 7 minors of this matrix must vanish for a total of 64 quartic equations in the entries of \(H \in X\). In [8, §1.3] the Plücker embedding of the Grassmannian is used to give a smaller set of equations which are linear combinations of the maximal 4 \(\times\) 4 minors of \(X\). The dimension of the linear span of such equations is the cardinality of the set \(\{p \in \binom{[8]}{4} \mid p \not\subseteq 3478\}\) of increasing sequences \(p\) of length 4 from \([8] = \{1, \ldots, 8\}\) where one of the inequalities \(p_1 \leq 3, p_2 \leq 4, p_3 \leq 7,\) or \(p_4 \leq 8\) does not hold. There are seventeen such sequences

\[
5678, 4678, 3678, 4578, 2678, 3578, 4568, 1678, 2578, \\
3568, 4567, 1578, 2568, 3567, 1568, 2567,\text{ and } 1567,
\]

so that in Steifel coordinates, \(X_{3478 1256} F\) is defined by 17 equations.

The primal-dual formulation uses a variant of the classical reduction to the diagonal. Consider the map \(\perp\) on \(G(4, 8)\) which sends a linear subspace \(H\) to its annihilator, \(H^\perp\). This is an isomorphism in which \(\perp(X_w F) = X_w F^\perp\), where \(F^\perp\) is the flag of linear forms annihilating the linear subspaces in \(F\) and \(w^\perp = w_0 w w_0\), where \(w_0(i) = n+1-i\).

To understand this in Steifel coordinates, pick a basis corresponding to the rows of a matrix whose dual basis corresponds to the columns. The dual Schubert variety \(X_w F\) has Steifel coordinates \(X_{w^\perp}\), where we send \(K \in X_{w^\perp}\) to the row span of \(K^T \Phi^{-1}\), where \(\Phi\) is the matrix whose first \(i\) columns span \(F_i\). In this formulation, the intersection of \(X_{3478 1256} F\) with the set parametrized by \(X\) is the intersection of the graph of \(\perp\) with the product \(X_{3478 1256} F^\perp \times X\). Since \(3478 1256^\perp = 3478 1256\), the primal-dual formulation uses the coordinates \(X_{3478 1256} \times X\) with the equations

\[
K^T \Phi^{-1} H = 0_{4 \times 4},
\]

which state that the four-plane \(K^T \Phi^{-1}\) annihilates \(H\). This involves 12 = \(\text{dim} X_{3478 1256}\) new coordinates and 16 bilinear equations, which are the entries of the matrix \(K^T \Phi^{-1} H\).

Finally, the lifted formulation uses the local coordinates

\[
\mathcal{Y} = \begin{pmatrix}
1 & 0 & y_{1,1} & y_{1,2} \\
0 & 1 & y_{2,1} & y_{2,2}
\end{pmatrix}^T
\]

from \(\text{Gr}(2, 4)\): For \(Y \in \mathcal{Y}\) and \(H \in X\), the 8 \(\times\) 2 matrix \(HY\) is a two-plane in \(H\).
If $\phi_1, \ldots, \phi_4$ are the equations that define $F_4$, then the lifted formulation for the intersection of $X_{3478, 1256} F_4$ with the set parametrized by $\mathcal{X}$ uses the coordinates $\mathcal{X} \times \mathcal{Y}$ and the equations

$$\phi_i( HY) = 0 \quad \text{for } i = 1, \ldots, 4.$$ 

This involves $4 = \dim \mathcal{Y}$ new coordinates and $8$ bilinear equations (linear in the entries of $Y$ and $H$) as $\phi_i(HY) = 0$ gives two equations, one for each column in $HY$.

### 3.2. Added variables for Schubert varieties on flag manifolds in $\mathbb{C}^9$. The square primal-dual formulation of a Schubert variety on a flag manifold [8] uses that every flag $E_\bullet$ in $\mathbb{C}^n$ has an annihilating dual flag $E_\bullet^\perp$ in the dual space to $\mathbb{C}^n$. If $E_\bullet$ has type $a_\bullet$, then $E_\bullet^\perp$ has type $a_\bullet^\perp := \{ n-a_j \mid a_j \in a_\bullet \}$. This duality gives an isomorphism $\perp : \mathbb{F}(a_\bullet; n) \to \mathbb{F}(a_\bullet^\perp; n)$ with $\perp(X_w F_\bullet) = X_{w^\perp} F_\bullet^\perp$ (we refer to Section 4 of [8] where $w^\perp$ is defined). A variant of the classical reduction to the diagonal allows us to formulate membership of a flag $E_\bullet$ in $X_w F_\bullet$ by parametrizing $X_{w^\perp} F_\bullet^\perp$, using $\ell(w)$ new variables.

As explained in [8, Rem. 4.10], sometimes membership of a flag $E_\bullet$ of type $a_\bullet$ in a Schubert variety $X_w F_\bullet$ is equivalent to the membership of a projection $\pi(E_\bullet)$ in the projected Schubert variety $\pi(X_w F_\bullet) = X_{w^\perp} F_\bullet$, where $\pi : \mathbb{F}(a_\bullet; n) \to \mathbb{F}(b_\bullet; n)$ is the natural projection and $b_\bullet \subset a_\bullet$. When this occurs, the primal-dual formulation uses fewer, $\ell(v)$, new variables. This is the reduced primal-dual formulation.

For every Schubert variety $X_w F_\bullet$ on a flag manifold $\mathbb{F}(a_\bullet; 9)$ with $1 < |w| < \frac{1}{2} \dim(a_\bullet)$ we compared the numbers of new variables needed in the two formulations. The restriction $1 < |w|$ is because the determinantal formulation when $|w| = 1$ is already a complete intersection. The restriction $|w| < \frac{1}{2} \dim(a_\bullet)$ is because, as in Remark 2.7, if $|w| \geq \frac{1}{2} \dim(a_\bullet)$, then we would work in local Steifel coordinates $X_w$ for the Schubert variety $X_w F_\bullet$ in any Schubert problem involving $w$ (and any Schubert problem has at most one permutation satisfying this inequality).

There are $3,395,742$ such Schubert varieties in the $256$ flag manifolds $\mathbb{F}(a_\bullet; 9)$. We compared the reduced lifted formulation of Subsection 2.2 with the reduced primal-dual formulation for all these Schubert varieties. In $141,256$ ($4.160\%$) the primal-dual formulation used fewer new variables, in $3,161,233$ ($93.094\%$) the lifted formulation used fewer new variables, and in $93,253$ ($2.746\%$) the two were tied.

This overstates the efficiency of the primal-dual formulation. For example, in only $7$ of $1725$ relevant Schubert varieties in $\mathbb{F}(2, 3, 5; 9)$ did the reduced primal-dual formulation involve fewer additional variables. In contrast, on the isomorphic dual flag variety $\mathbb{F}(4, 6, 7; 9)$ in $124$ out of $1725$ relevant Schubert varieties the reduced primal-dual formulation involved fewer variables.

To gain an idea of how this might be exploited, we determined which of each pair of dual flag manifolds $\mathbb{F}(a_\bullet; 9)$ and $\mathbb{F}(a_\bullet^\perp; 9)$ was more favorable for the reduced lifted formulation of its Schubert varieties. We redid our computation comparing the two formulations, but restricted it to those flag manifolds $\mathbb{F}(a_\bullet; 9)$ where $\mathbb{F}(a_\bullet; 9)$ was more favorable for the reduced lifted formulation than $\mathbb{F}(a_\bullet^\perp; 9)$. This is a fair restriction, for the number of additional variables in the reduced primal-dual formulation is the same for a Schubert variety and for its dual, but may be different for the reduced lifted formulations.
Redoing the computation, there were 1,877,752 Schubert varieties, as we only considered one of each dual pair of flag manifolds. In 53,698 (2.860%) the primal-dual formulation used fewer new variables, in 1,784,646 (95.04%) the lifted formulation used fewer new variables, and in 39,408 (2.099%) the two were tied.

The reduced lifted formulation is always better for the Grassmannian $\text{Gr}(k, n)$ than for its dual $\text{Gr}(n-k, n)$ when $2k \leq n$.

**Lemma 3.1.** If $2k \leq n$, then the reduced lifted formulation always uses fewer variables than the primal-dual formulation for Schubert varieties $X_w F_{\bullet}$ in the Grassmannian $\text{Gr}(k, n)$ with $|w| < \frac{1}{2}k(n-k)$.

**Proof.** The original lifted formulation for Schubert varieties in the Grassmannian $\text{Gr}(k, n)$ used $\binom{k}{2}$ additional variables, while the primal dual formulation for $X_w F_{\bullet}$ uses $\ell(w) = k(n-k) - |w|$ variables. The lemma follows as $\ell(w) \geq \frac{1}{2}k(n-k) > \frac{1}{2}k(k-1)$. □

**Remark 3.2.** The Grassmannian $\text{Gr}(k, n)$ has a more efficient primal-dual formulation that uses the Steifel coordinates of Remark 2.9 for the intersection of two Schubert varieties. This involves $k(n-k) - |w_1| - |w_2|$ new variables, while the lifted formulation uses $k(k-1)$ new variables to formulate membership in two Schubert varieties. The lifted formulation is more efficient when

$$k(n-k) - |w_1| - |w_2| > k(1).$$

Since we may assume that $|w_1| + |w_2| < \frac{1}{2}k(n-k)$, the lifted formulation is always more efficient when $k < (n+2)/3$ for then

$$k(n-k) - |w_1| - |w_2| \geq \frac{1}{2}k(n-k) > \frac{1}{2}k(2k-2) = k(1).$$

### 3.3. Computational time and resources.

We computed instances of three Schubert problems using the (reduced) lifted formulation. Two were computed using a primal-dual formulation in [8], and the third is a problem with many more solutions. In all, the lifted formulation used fewer variables and less computational resources.

**Example 3.3.** Consider the Schubert problem in $\text{Gr}(3; 9)$ given by the permutations

$$w_1, \ldots, w_4 = 489 123567 \quad \text{and} \quad w_5, \ldots, w_{10} = 689 123457.$$

This has 437 solutions and asks for the 3-planes in $\mathbb{C}^9$ which nontrivially meet four given 4-planes and six given 6-planes. The classical formulation of the intersection (2.13) in Stiefel coordinates for $X_{w_1} F_{\bullet} \cap X_{w_2} F_{\bullet}$ is a system of 12 variables, 20 independent linear combinations of cubic minors and six cubic determinants.

The square primal-dual formulation with similar coordinates involves 24 variables, 18 bilinear equations, and six cubic determinants. The determinants correspond to the conditions $w_5, \ldots, w_{10}$ as $|689 123457| = 1$. In [8] we used Bertini [1] to solve an instance of this Schubert problem given by random real flags. This computation consumed 20.37 gigahertz-hours to calculate 437 approximate solutions. We then used rational arithmetic in alphaCertified [10] to certify the solutions, which used 2.00 gigahertz-hours.

We formulate this Schubert problem using the lifted formulation. We use Stiefel coordinates for $X_{w_1} F_{\bullet} \cap X_{w_2} F_{\bullet}$ which use $\text{dim}(\text{Gr}(3; 9)) - |w_1| - |w_2| = 18 - 3 - 3 = 12$
variables. The reduced lifted formulations of $X_{w_i}F_i^i$ for $i = 3, 4$ require a total of $|\beta(w_3)| + |\beta(w_4)| = 2 + 2 = 4$ new variables and $2 \cdot 5 = 10$ bilinear equations. As in the primal-dual formulation, we formulate membership in the six remaining hypersurface Schubert varieties using six cubic determinants. The result is a system of $12 + 4 = 16$ variables and $10 + 6 = 16$ equations. To compare with the primal-dual formulation, we solved a random instance using regeneration with the same variables, hardware, software, and software version. The lifted formulation of 16 variables and equations was a significant improvement, using only 4.75 gigaHertz-hours to calculate 437 approximate solutions. The output suggests 107 of the solutions are real, while the rest are non-real. We used seven processors in parallel, but many more could be efficiently used as the regeneration tracked up to 2265 paths in one step.

Certification time was also significantly improved by using this formulation. A 33.54 gigaHertz-minute computation in alphaCertified [10] using rational arithmetic verified that the 437 points in the output are indeed approximate solutions and that the corresponding exact solutions are distinct. This computation also proved the reality for 107 of the exact solutions.

We compare the primal-dual and lifted formulations in a more general flag manifold.

Example 3.4. Consider the Schubert problem with 128 solutions in $F\ell(2, 4, 5; 8)$ given by

\[
\begin{align*}
    w_1 & = 48573126, \\
    w_2, w_3 & = 78453126, \\
    w_4, w_5 & = 68574123, \\
    w_6, w_7, w_8 & = 78465123, \text{ and} \\
    w_9 & = 47385126.
\end{align*}
\]

Applying all improvements given in [8] produced a primal-dual formulation with 41 variables, 36 bilinear equations, two quadratic determinantal equations corresponding to the hypersurface conditions $w_4, w_5$, and three quartic determinantal equations from $w_6, w_7, w_8$. This square system corresponding to a random choice of nine real flags took 2.95 gigaHertz-days of processing power to solve and 1.78 gigaHertz-hours to certify.

We analyze this Schubert problem using a reduced lifted formulation in the Stiefel coordinates $X_{w_9}$ consisting of $\ell(w_9) = 16$ variables. The reduced lifted formulations of $X_{w_i}F_i^i$ for $i = 1, 2, 3$ add $|\beta(w_1)| + |\beta(w_2)| + |\beta(w_3)| = 5 + 6 + 6 = 17$ new variables and $10 + 9 + 9 = 28$ bilinear equations. As in the primal-dual formulation, we formulate $X_{w_i}F_i^i$ for $i = 4, \ldots, 8$ using two quadratic and three quartic determinants. The reduced lifting uses $16 + 17 = 33$ variables and $28 + 2 + 3 = 33$ equations. As in Example 3.3, we compare this with the primal-dual formulation using the tools which were utilized in [8]. To facilitate certification, we computed approximate solutions with two extra digits of precision compared to our computation in [8].

With these tighter parameters, we still observed an improvement in efficiency when solving a system with the new formulation of 33 variables and equations. This used 1.13 gigaHertz-days of computing; less than half the power consumed by the similar instance using the primal-dual formulation. The output was 128 approximate solutions, of which
42 appeared to be real. Again, we used alphaCertified with rational arithmetic to certify
the approximate solutions, verify they correspond to distinct solutions, and prove that 42
exact solutions are real. Certification required 1.68 gigaHertz-hours of processor power,
marginally less than certification for the similar instance we solved via a primal-dual
formulation.

The initial computation used six processors in parallel, but many more could be effi-
ciently used as the regeneration tracked up to 708 paths in one step. Certification could
have efficiently used 128 processors.

We formulated and solved a higher-degree problem in a Grassmannian.

**Example 3.5.** Consider the Schubert problem with 28,490 solutions in \( \text{Gr}(3; 10) \) given by

\[
w_1, w_2, w_3 = 5910\, 1234678 \quad \text{and} \quad w_4, \ldots, w_{15} = 7910\, 1234568.
\]

This asks for the 3-planes in \( \mathbb{C}^{10} \) that nontrivially meet three given 5-planes and twelve
given 7-planes. In the determinantal formulation, we parametrize \( X_{w_1} F_1^1 \cap X_{w_2} F_2^2 \) using
\( \dim(\text{Gr}(3; 10)) - |w_1| - |w_2| = 21 - 3 - 3 = 15 \) variables, and membership in \( X_{w_3} F_3^3 \) is given
by the vanishing of ten independent linear combinations of cubic minors. Including the
cubic determinants for \( X_{w_i} F_i^i \) for \( i = 4, \ldots, 15 \) uses 15 variables and 22 cubic equations.

The primal-dual formulation uses 33 variables, 21 bilinear equations, and twelve cubic
determinants. The lifted formulation begins with Steifel coordinates involving 15 variables
that parametrize \( X_{w_1} F_1^1 \cap X_{w_2} F_2^2 \). The reduced lifted formulation for \( X_{w_3} F_3^3 \) uses five
bilinear equations and adds \( |\beta(w_3)| = 2 \) variables for a total of 17 variables. The twelve
hypersurface conditions \( w_4, \ldots, w_{15} \) are each given by a single cubic determinant for a
total of \( 5 + 12 = 17 \) equations. The only difference is for \( X_{w_3} F_3^3 \) which use 18 variables
and 21 bilinear equations with the primal-dual formulation but only two variables and
five bilinear equations for the lifted formulation.

We chose 15 random real flags and solved the corresponding instance of the Schubert
problem using 1.71 gigaHertz-months of processing power to apply regeneration in Bertini
v. 1.4 and 4.00 gigaHertz-hours of power to apply four Newton iterations to the output
using alphaCertified. This produced 28,490 approximate solutions, and 1436 appeared
to be real. The main calculation in Bertini used 8 processors in parallel, but many more
could be used efficiently as the regeneration tracked up to 148,161 paths in one step.

Due to the size of the output, we soft certified our results using floating-point arithmetic
in alphaCertified with 192-bit precision. This heuristically verified that the 28,490 points
are approximate solutions, that they correspond to distinct solutions, and that 1436 of
them correspond to real solutions. This computation consumed 47.15 gigaHertz-minutes
of processing power. A rigorous computation using rational arithmetic, but only for the
1436 apparently real solutions, used 1.80 gigaHertz-days and proved that 1436 points in
the output are approximate solutions corresponding to distinct real solutions.

We give additional details for the computations and comparisons in Examples 3.3, 3.4,
and 3.5 at the following site.

http://www.unk.edu/academics/math/_files/square.html
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