Improving Interaction Quality Recognition Using Error Correction

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Abstract

Determining the quality of an ongoing interaction in the field of Spoken Dialogue Systems is a hard task. While existing methods employing automatic estimation already achieve reasonable results, still there is a lot of room for improvement. Hence, we aim at tackling the task by estimating the error of the applied statistical classification algorithms in a two-stage approach. Correcting the hypotheses using the estimated model error increases performance by up to 4.1% relative improvement in Unweighted Average Recall.

1 Introduction

Evaluating the quality of Spoken Dialogue Systems (SDSs) has long since been a challenging task. While objective metrics like task completion and dialogue duration are not human-centered, subjective measures compensate for this by modeling the user’s subjective experience. This information may be used to increase the dialogue system’s performance (cf. (Ultes et al., 2012b)).

In human-machine dialogues, however, there is no easy way of deriving the user’s satisfaction level. Moreover, asking real users for answering questions about the system performance requires them to spend more time talking to the machine than necessary. It can be assumed that a regular user does not want to do this as human-machine dialogues usually have no conversational character but are task oriented. Hence, automatic approaches are the preferred choice.

Famous work on determining the satisfaction level automatically is the PARADISE framework by Walker et al. (1997). Assuming a linear dependency between objective measures and User Satisfaction (US), a linear regression model is applied to determine US on the dialogue level. This is not only very costly, as dialogues must be performed with real users, but also inadequate if quality on a finer level is of interest, e.g., on the exchange level.

To overcome this issue, work by Schmitt et al. (2011) introduced a new metric for measuring the performance of an SDS on the exchange level called Interaction Quality (IQ). They used statistical classification methods to automatically derive the quality based on interaction parameters. Quality labels were applied by expert raters after the dialogue on the exchange level, i.e., for each system-user-exchange. Automatically derived parameters were then used as features for creating a statistical classification model using static feature vectors. Based on the same data, Ultes et al. (2012a) put an emphasis on the sequential character of the IQ measure by applying temporal statistical classification using Hidden Markov Models (HMMs) and Continuous Hidden Markov Models (CHMMs).

However, statistical classifiers usually do not achieve perfect performance, i.e., there will always be misclassification. While most work focuses on applying different statistical models and improving them (Section 2), learning the error to correct the result afterwards represents a different approach. Therefore, we present our approach on estimating the error of IQ recognition models to correct their hypothesis in order to eventually yield better recognition rates (Section 4). The definition of IQ and data used for the evaluation of our approach (Section 5) is presented in Section 3. Our approach is also compared to a simple hierarchical approach also discussed in Section 5.

2 Related Work on Dialogue Quality

Besides Schmitt et al., other research groups have performed numerous work on predicting subjective quality measures on an exchange level, all not incorporating any form of error correction.

Engelbrecht et al. (2009) presented an approach using Hidden Markov Models (HMMs) to model
Higashinaka et al. (2010) proposed a model for predicting turn-wise ratings for human-human dialogues analyzed on a transcribed conversation and human-machine dialogues with text from a chat system. Ratings ranging from 1 to 7 were applied by two expert raters labeling for smoothness, closeness, and willingness.

Hara et al. (2010) derived turn level ratings from overall ratings of the dialogue which were applied by the users afterwards on a five point scale. Using n-grams to model the dialogue, results for distinguishing between six classes at any point in the dialogue showed to be hardly above chance.

3 The LEGO Corpus

For estimating the Interaction Quality (IQ), the LEGO corpus published by Schmitt et al. (2012) is used. IQ is defined similarly to user satisfaction: While the latter represents the true disposition of the user, IQ is the disposition of the user assumed by an expert rater. The LEGO corpus contains 200 calls (4,885 system-user-exchanges) to a bus information system (cf. (Raux et al., 2006)). Labels for IQ on a scale from 1 (extremely unsatisfied) to 5 (satisfied) have been assigned by three expert raters with an inter-rater agreement of \( \kappa = 0.54 \). In order to ensure consistent labeling, the expert raters had to follow labeling guidelines (cf. (Schmitt et al., 2012)).

Parameters used as input variables for the IQ model have been derived from the dialogue system modules automatically for each exchange on three levels: the exchange level, the dialogue level, and the window level (see Figure 1). As parameters like the confidence of the speech recognizer can directly be acquired from the dialogue modules, they constitute the exchange level. Based on this, counts, sums, means, and frequencies of exchange level parameters from multiple exchanges are computed to constitute the dialogue level (all exchanges up to the current one) and the window level (the three previous exchanges). A complete list of parameters is listed in (Schmitt et al., 2012).

Schmitt et al. (2011) performed IQ recognition on this data using linear SVMs. They achieved an Unweighted Average Recall (UAR) of 0.58 based on 10-fold cross-validation. Ultes et al. (2012a) applied HMMs and CHMMs using 6-fold cross validation and a reduced feature set achieving an UAR of 0.44 for HMMs and 0.39 for CHMMs.

4 Error Estimation Model

Error correction may be incorporated into the statistical classification process by a two-stage approach, which is depicted in Figure 2.

At the first stage, a statistical classification model is created using interaction parameters as input and IQ as target variable. For this work, a Support Vector Machine (SVM) and a Rule Learner are applied. At the second stage, the error \( e_r \) of the hypothesis \( h_0 \) is calculated by

\[
e_r = h_0 - r,
\]

where the reference \( r \) denotes the true IQ value. In order to limit the number of error classes, the signum function is applied. It is defined as

\[
sgn(x) := \begin{cases} 
-1 & \text{if } x < 0, \\
0 & \text{if } x = 0, \\
1 & \text{if } x > 0.
\end{cases}
\]

Therefore, the error is redefined as

\[
e_r = sgn(h_0 - r). \tag{3}
\]

Next, a statistical model is created similarly to stage one but targeting the error \( e_r \). The difference is that the input parameter set is extended by the IQ hypothesis \( h_0 \) of stage one. Here, two approaches are applied: Creating one model which estimates all error classes \((-1,0,1)\) and creating two models where each estimates positive \((0,1)\) or negative error \((-1,0)\). For the latter variant, the error of the class which is not estimated by the respective model is mapped to 0. By this, the final error hypothesis \( h_e \) may be calculated by simple addition of both estimated error values:

\[
h_e = h_{e,-1} + h_{e,+1}. \tag{4}
\]

Combining the hypothesis of the error estimation \( h_e \) with the hypothesis of the IQ estimation \( h_0 \)
at stage one produces the final hypothesis $h_f$ denoting the Interaction Quality estimation corrected by the estimated error of the statistical model:

$$h_f = h_0 - h_e.$$  \hspace{1cm} (5)

As the error estimation will not work perfectly, it might recognize an error where there is none or – even worse – it might recognize an error contrary to the real error, e.g., $-1$ instead of $+1$. Therefore, the corrected hypothesis might be out of range. To keep $h_f$ within the defined bounds of IQ, a limiting functions is added to the computation of the final hypothesis resulting in

$$h_f = \max(\min(h_0 - h_e), b_u), b_l)),$$ \hspace{1cm} (6)

where $b_u$ denotes the upper bound of the IQ labels and $b_l$ the lower bound.

5 Experiments and Results

All experiments are conducted using the LEGO corpus presented in Section 3. By applying 5-fold cross validation, hypotheses for each system-user-exchange which is contained in the LEGO corpus are estimated. Please note that some textual interaction parameters are discarded due to their task-dependent nature leaving 45 parameters.

For evaluation, we rely on two measures: The unweighted average recall (UAR) and the root mean squared error (RMSE). UAR represents the accuracy corrected by the effects of unbalanced data and is also used by cited literature. RMSE is used since the error correction method is limited to correcting the results only by one. For bigger errors, the true value cannot be reached.

The performances of two different statistical classification methods are compared, both applied for stage one and stage two: Support Vector Machine (SVM) (Vapnik, 1995) using a linear kernel, which is also used by Schmitt et al. (2011), and Rule Induction (RI) based on Cohen (1995). Furthermore, a normalization component is added performing a range normalization of the input parameters in both stages. This is necessary for using the implementation of the statistical classification algorithms at hand.

For error estimation, two variants are explored: using one combined model for all three error classes ($-1, 0, +1$) and using two separate models, one for distinguishing between $-1$ and $0$ and one for distinguishing between $+1$ and $0$ with combining their results afterwards. While using RI for error estimation yields reasonable performance results for the combined model, it is not suitable for error estimation using two separate models as all input vectors are mapped to $0$. Hence, for the two model approach, only the SVM is applied.

Results for applying error correction (EC) are presented in Table 1. Having an SVM at stage one (column SVM), recognition performance is relatively improved by up to 4.6% using EC. With RI
Table 1: Results for IQ recognition: UAR and RMSE for IQ recognition without stage two, with error correction at stage two, and with a simple hierarchical approach.

| stage two             | UAR SVM | UAR RI | RMSE SVM | RMSE RI |
|-----------------------|---------|--------|----------|---------|
| none                  | 51.1%   | 60.3%  | 0.97     | 0.88    |
| error correction      |         |        |          |         |
| SVM                   | 50.7%   | 59.6%  | 0.97     | 0.83    |
| RI                    | 52.5%   | 58.1%  | 0.88     | 0.85    |
| 2xSVM                 | 53.2%   | 60.6%  | 0.88     | 0.85    |
| simple hierarchical approach | 50.2% | 57.8%  | 0.97     | 0.85    |

at stage one, performance is only increased by up to 0.5% which has shown to be not significant using the Wilcoxon test. The relative improvements in UAR are depicted in Figure 3.

Furthermore, these results are compared to a simple hierarchical approach (SH) where the hypothesis $h_0$ of the stage one classifier is used as an additional feature for the stage two classifier targeting IQ directly. Here, the performance of the stage two classifier is of most interest since this approach can be viewed as one stage classification with an additional feature. The results in Table 1 show that RI does not benefit from additional information (comparison of last row with one stage RI recognition). SVM recognition at stage two, though, shows better results. While its performance is reduced using the SVM hypothesis as additional feature, adding the RI hypothesis improved UAR up to 12.6% relatively. However, there is no reasonable scenario where one would not use the better performing RI in favor of using its results as additional input for SVM recognition.

The question remains why SVM benefits from Error Correction as well as from adding additional input parameters while RI does not. It remains unclear if this is an effect of the task characteristics combined with the characteristics of the classification method. It may as well be caused by low classification performance. A classifier with low performance might be more likely to improve its performance by additional information or EC.

6 Conclusion

In this work, we presented an approach for improving the recognition of Interaction Quality by estimating the error of the classifier in order to correct the hypothesis. For the resulting two-staged approach, two different statistical classification algorithm were applied for both stages, i.e., SVM and Rule Learner. Performance could be improved for both stage one classifiers using separate error models relatively improving IQ recognition by up to 4.1%. The proposed error correction approach has been compared to a simple hierarchical approach where the hypothesis of stage one is used as additional feature of stage two classification. This approach relatively improved SVM recognition by up to 12.6% using a Rule Learner hypothesis as additional feature. However, as one-stage Rule Learner classification already provides better results than this hierarchical approach, it does not seem reasonable to employ this configuration. Nonetheless, why only the SVM could benefit from additional information (error correction or simple hierarchical approach) remains unclear and should be investigated in future work.

Moreover, some aspects of the error correction approach have to be discussed controversially, e.g., applying the signum function for calculating the error. While the obvious advantage is to limit the number of error classes a statistical classification algorithm has to estimate, it also prohibits of being able to correct all errors. If the absolute error is bigger than one it can never be corrected.

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