Holographic entanglement of purification for thermofield double states and thermal quench

Run-Qiu Yang, a Cheng-Yong Zhang b and Wen-Ming Li c

a Quantum Universe Center, Korea Institute for Advanced Study, Seoul 130-722, Korea
b Department of Physics and Center for Field Theory and Particle Physics, Fudan University, Shanghai 200433, China
c Department of Physics and State Key Laboratory of Nuclear Physics and Technology, Peking University, No.5 Yiheyuan Rd, Beijing 100871, P.R. China
E-mail: aqiu@kias.re.kr, zhangchengyong@fudan.edu.cn, liwmpku@pku.edu.cn

ABSTRACT: We explore the properties of holographic entanglement of purification (EoP) for two disjoint strips in the Schwarzschild-AdS black brane and the Vaidya-AdS black brane spacetimes. For two given strips on the same boundary of Schwarzschild-AdS spacetime, there is an upper bound of the separation beyond which the holographic EoP will always vanish no matter how wide the strips are. In the case that two strips are in the two boundaries of the spacetime respectively, we find that the holographic EoP exists only when the strips are wide enough. If the width is finite, the EoP can be nonzero in a finite time region. For thermal quench case, we find that the equilibrium time of holographic EoP is only sensitive to the width of strips, while that of the holographic mutual information is sensitive not only to the width of strips but also to their separation.

KEYWORDS: AdS-CFT Correspondence, Black Holes, Conformal Field Theory

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1 Introduction

Entanglement is one of the most significant features of quantum physics, and plays an important role in understanding quantum many-body physics, quantum field theory, quantum information as well as quantum gravity. In quantum field theory, the entanglement entropy (EE) measures the entanglement between a subregion $A$ of Hilbert space and its complement $\bar{A}$. It is defined as the von Neumann entropy of the reduced density matrix,

$$S_A := -\text{tr}_A \rho_A \log \rho_A$$

(1.1)

where $\rho_A := \text{tr}_A \rho$ is the reduced density matrix of $A$ with respect to the density matrix of the whole system. In the AdS/CFT correspondence [1], there is a simple holographic counterpart given by the Hubeny-Rangamani-Takayanagi (HRT) surface [2, 3],

$$S_A = \frac{\text{Area}(\gamma_A)}{4G_N}.$$  

(1.2)

where $G_N$ is the Newton constant, of which the relation with the central charge of CFT is $c = \frac{3}{2G_N}$, and $\gamma_A$ is the extremal surface sharing the common boundary with $A$ and is homologous to $\bar{A}$. In this paper, we will set $G_N = 1$.

For pure state, the EE computed by eq. (1.1) is the only way to characterize the quantum entanglement of a given bipartite system. However, when the system is in a mixed state it is not. There are several different quantities to describe the quantum or classical correlations between two subsystems $A$ and $B$. For example, one of the well-studied quantity both in quantum information theory and its holographic duality is the mutual information (MI) $I(A : B)$ [4–6], which is defined as

$$I(A : B) = S(\rho_A) + S(\rho_B) - S(\rho_{AB}),$$

(1.3)
where \( AB = A \cup B \). But this quantity is only the linear combination of EE, so it is not a new quantity both in the view point of holographic duality or quantum information theory.

Recently, a new quantity describing the entanglement between mix states, the entanglement of purification (EoP) \([7]\) was studied in holographic duality. Entanglement of purification (EoP) \([8]\) is defined by minimum EE for all possible purification of the mixed state, which is defined as

\[
E_P(A:B) = \min_{\rho_{AB} = Tr_{A'B'}|\psi\rangle \langle \psi|} S(\rho_{AA'}).
\]

Here \( |\psi\rangle \) is a pure state on the enlarged Hilbert space \( \mathcal{H}_A \otimes \mathcal{H}_B \otimes \mathcal{H}_{A'} \otimes \mathcal{H}_{B'} \), where \( \mathcal{H}_A \otimes \mathcal{H}_B \) is the initial Hilbert space in which the mixed state \( \rho_{AB} \) lives, and \( \mathcal{H}_{A'} \) (or \( \mathcal{H}_{B'} \)) is arbitrary that is needed in order to purify the mixed state. The EoP can be viewed as a generalization of EE, as evidently for the pure state it equals EE. The EoP of bipartite system is zero only when \( \rho_{AB} = \rho_A \otimes \rho_B \).

The EoP has strong relationship to MI. In fact, we have \([9]\)

\[
\frac{1}{2} I(A:B) \leq E_P(A:B) \leq \min\{S(\rho_A), S(\rho_B)\}.
\]

This inequality is saturated in both sides if \( AB \) is a pure state. When the MI vanishes,\(^1\) the bipartite system \( AB \) is separable and so we have \( E_P(A:B) = 0 \). Thus, the nonzero EoP can appear only when MI is nonzero.

Since there are infinite ways of purification, it is hard to work out the EoP in the CFT side \([13, 14]\) (early works focused on spin systems in numerical such as \([15, 16]\)). In recent works, inspired by the RT formula, a holographic formula for the EoP was proposed in \([7, 17]\) and generalized to multipartite and other situations in \([18-22]\). In this holographic conjecture, the EoP is dual to the entanglement wedge \([23]\) cross section \( E_W \), which reads

\[
E_P = E_W.
\]

This conjecture is powerful since it implies that the holographic state dual to the surface of entanglement wedge is an optimal purification of the density matrix of any geometric subregion of the boundary theory. Evidently, when the state is a pure one, \( E_W \) is equal to the EE, which is the same as that in the CFT side.

Now for a bipartite mixed state, we have three different quantities with their holographic descriptions at hand, i.e., the EEs of \( A \) and \( B \), the mutual information \( I(A:B) \) and the entanglement of purification \( E_P(A:B) \). The former two have been studied deeply both from information theories and holographic duality. However, the behavior of EoP is not known well at current. Though a few of works have been done to understand EoP and its holographic duality from conformal field theory \([14, 18, 20, 21]\), it is not known well how different the EoP will be if when we compare it with EE and MI in some concentrate systems. It is also important to find what new properties can be carried by EoP when we study the entanglement between two subregions in a mixed state. The main aim of this paper is to make some preliminary explorations on these aspects.

\(^1\)The MI of two disjoint regions is usually nonvanishing due to the quantum correlations between them, see \([10-12]\) for example. However, we work in the classical gravity limit in this paper.
In this work, we will explore the properties of holographic EoP in the Schwarzschild-AdS black brane and the Vaidya-AdS black brane, which are dual to the thermofield double state and thermal quench respectively. We first consider two disjoint strips with the same width on the same boundary of Schwarzschild-AdS black brane, which is dual to the two disjoint subregions of a thermal state. In the case that two strips are in two boundaries of the extended black brane respectively, we consider how the EoP evolves according to the boundary time. Finally we also consider the EoP in the quench case. Since the holographic EoP exists only when the holographic MI is positive, we will further compare the evolution behaviors of holographic MI and EoP.

The organization of this is as follows. In section 2, we first consider the two disconnected regions in the same side and try to discover the relation between EoP and the size of the subregion, the separation of the subregion. In section 3, we consider the time evolution of EoP when the two subregions in different sides. We will consider how the widths of two regions effect time-evolutilional behaviour of EoP. In section 4, we will study the effects of thermal quench on EoP of two regions by Vaidya-AdS black brane. A short summary will be found in section 5.

2 Entanglement of purification for two strips on the same side

We consider the Schwarzschild AdS black brane in \((d + 1)\)-dimensional case. The metric reads,

\[
ds^2 = \frac{1}{z^2} \left[ -f(z)dt^2 + \frac{dz^2}{f(z)} + dx_{d-1}^2 \right], \quad f(x) := 1 - \frac{z^d}{z_h^d}. \tag{2.1}
\]

Here \(dx_{d-1}^2\) is induced line elements at the spatial \((d - 1)\)-dimensional subspace with \(z = 0\) and constant \(t\). The spatial coordinates are \(\{x_1, x_2, \cdots, x_{d-1}\}\). \(z_h\) is the inverse horizon radius and the inverse temperature of dual boundary theory is \(\beta = 4\pi z_h/d\). In this paper, we set \(z_h = 1\) so the inverse temperature \(\beta = 4\pi/d\).

Let us first consider the case that the subregions \(A\) and \(B\) are both infinite strips separated by distance \(D\) on the same boundary of the spacetime at fixed time \(t = 0\) (see figure 1). The subregions are

\[
A := \{l + D/2 > x_1 > D/2, -\infty < x_i < \infty, i = 2, 3, \cdots, d - 1\}
\]

and

\[
B := \{-l - D/2 < x_1 < -D/2, -\infty < x_i < \infty, i = 2, 3, \cdots, d - 1\}.
\]

As discussed in [7], when the two subsystems are separated from each other far away enough, the system is the product state of \(A\) and \(B\), the entanglement wedges are disconnected and so there is no holographic EoP. The transition point of nonzero EoP can be find by the inequality (1.5). For a strip with width \(w\), the holographic entanglement entropy is

\[
S(w) = \frac{2V_{d-2}}{4} \int_{\delta}^{z_m} \frac{dz}{z^{d-1}} \frac{1}{\sqrt{(1 - z^d) \left(1 - \frac{z^{2d-2}}{z_m^{2d-2}}\right)}}. \tag{2.2}
\]
\[ w = 2 \int_{\delta}^{z_m} \frac{dz}{\sqrt{(1 - z^d) \left( \frac{e^{2l} - 1}{e^{2l} - 1} \right)}}. \]

From figure 1, we can see that \( S_A = S_B = S(l) \) and \( S_{AB} = S(2l + D) + S(D) \). Thus the holographic MI of \( AB \), which is the function of \( D \) and \( l \), can be expressed as

\[ I(D,l) = S_A + S_B - S_{AB} = 2S(l) - S(D) - S(2l + D). \]

The holographic EoP is nonzero only if \( I(D,l) > 0 \). The regions having EoP for different dimensional spacetimes are shown in the left panel of figure 2. For given dimension \( d \) and strip width \( l \), there is a critical separation \( D_c(d,l) \) and the holographic EoP is nonzero only if \( D < D_c(d,l) \). When \( d = 2 \), we can work out the critical separation \( D_c(2,l) \) analytically,

\[ \cosh \frac{D_c(2, l)}{2} = \sqrt{1 + 2\sqrt{2} \cosh l \cosh \frac{l}{2} + 2 \cosh l \left[ \cosh \frac{3l}{2} - \sqrt{2}(\cosh l)^{3/2} \right]} \]

The critical separation when \( l \to \infty \) is \( D_c(2, \infty) = \ln 2 = \frac{\beta}{\kappa} \ln 2 \). This means that when \( D > \ln 2 \), there is no holographic EoP no matter how large \( l \) is. When \( d > 2 \), one can work out the critical separation numerically. The results are shown in figure 2.
left panel, we see that for small given \( l \), \( D_c(d, l) \) grows with \( d \). For larger \( l \), \( D_c(d, l) \) decreases with \( d \). For \( d \) given, when \( l \) is small, the critical separation grows linearly with \( l \):

\[
D_c(d, l) \approx c_0(d)l.
\]

(2.6)

When \( d = 2 \), the coefficient \( c_0(2) = \sqrt{2} - 1 \). For larger \( d \), \( c_0(d) \approx \frac{1}{2^{(d-1)/d}} + 1 \) approximately. The critical separation \( D_c(d, l) \) when \( l \to \infty \) is related approximately to the spacetime dimension \( d \) by \( D_c(d, \infty)^{-1} \approx 0.5 + 0.4d \). For large enough \( l \), the critical separation tends to \( D_c(d, \infty) \) asymptotically and there are \( D_c(d, l) \approx D_c(d, \infty) - c_1(d)e^{-c_2(d)/l} \) where \( c_1(d), c_2(d) \) are positive constants depending on \( d \).

When \( I(D, l) > 0 \), the holographic EoP is given by

\[
\frac{4}{V_{d-2}}E(l, D) = \begin{cases} 
    \ln \left( \frac{\tanh(D/4)}{\tanh(L/4)} \right), & d = 2, \\
    -4z^2 - d\sqrt{1 - z^2} + (d - 4)z^2 \, F\left( \frac{1}{2}, \frac{d}{2} ; \frac{d+4}{2} ; z^2 \right) & \frac{z^2 + D}{2d} \mid_{z_d}, & d > 2.
\end{cases}
\]

(2.7)

We plot the holographic EoP for different \( l \) and \( D \) when \( d = 2 \) in the left and middle panels of figure 3. In the left panel, we see that when the separation \( D \) goes to zero, the holographic EoP goes to infinity. This is due to the UV divergence near the spacetime boundary. As \( D \) grows, the holographic EoP takes a nosedive. The change becomes slowly as \( D \) grows further. However, when \( D \) goes beyond the upper bound, i.e., \( D > D_c(d, l) \), the holographic EoP drops suddenly to zero. These are two phases corresponding to the connected entanglement wedge and the disconnected one, respectively. Moreover, the smaller the strip width \( l \) is, the shorter \( D \) having holographic EoP is and the sharper the nosedive is. For fixed separation, the holographic EoP vanishes when the strip width is small, as shown in the middle panel. It becomes positive discontinuously when the strips are wide enough. When the strip width is very large, the holographic EoP tends to a saturation value. The larger the separation is, the smaller saturation of holographic EoP. In the right panel of figure 3, we show the holographic EoP in different dimensional spacetimes for strips with \( l \to \infty \). The holographic EoP decays slower with separation in higher dimension. Beyond the critical separations, the holographic EoP drops discontinuously to zero.
3 Entanglement of purification for two-side subregions

The maximally extended Penrose diagram of static black brane contains two-copy of the boundaries, which corresponds to two copies of the field theory. The full spacetime is conjectured dual to the thermofield double states [24]. In general, these two copies are in an entangled state in the form

$$|\Phi\rangle := \frac{1}{Z} \sum_n e^{-\beta E_n/2} |E_n\rangle_L |E_n\rangle_R.$$  \hspace{1cm} (3.1)

The states $|E_\alpha\rangle_L$ and $|E_\alpha\rangle_R$ are eigenstates in the two copy field theories, $Z$ is the normalized factor and $\beta$ is the temperature of these two field theories.

In the last section, we only studied the subregions in one boundary state of the black branes. In this section, we will consider the case that subregions $A$ and $B$ locate at the two boundaries, respectively. The union of two time slices $t_L = t_R = 0$ at two boundaries is dual to a TFD state $|\Phi\rangle$ in (3.1). With the Hamiltonians $H_L$ and $H_R$ at the left and right dual CFTs, respectively, the time evolution of a TFD state then reads,

$$|\Phi(t)\rangle := e^{-it(H_L+H_R)}|\Phi\rangle.$$  \hspace{1cm} (3.2)

This time-dependent TFD state can be characterized by the codimension-2 surfaces of $t_B = t_L = t_R$ at the two boundaries of the AdS black brane.

3.1 Infinite size case

Let us first consider the two infinitely wide strips appearing in the two boundaries symmetrically. The subregions are (see the right panel of figure 4)

$$A := \{ t = t_B, x_1 > 0, -\infty < x_i < \infty, i = 2, 3, \cdots, d - 1 \}$$

and

$$B := \{ t = t_B, x_1 > 0, -\infty < x_i < \infty, i = 2, 3, \cdots, d - 1 \}.$$

The induced density matrix of $A \cup B$ is also time-dependent,

$$\rho_{AB} = \text{Tr}_{L,x_1>0} \text{Tr}_{R,x_1>0} (|\Phi(t_B)\rangle \langle \Phi(t_B)|).$$  \hspace{1cm} (3.3)

Thus, the EoP between $A$ and $B$ is also time-dependent. The union of $A \cup B$ and $\overline{A \cup B}$ gives the whole boundaries, so we can also study the entanglement entropy between $A \cup B$ and $\overline{A \cup B}$, which is given by

$$S_{AB} := -\text{Tr}(\rho_{AB} \ln \rho_{AB}).$$  \hspace{1cm} (3.4)

Now let us study $E(t_B) := E_P(A : B)$ and $S_{AB}$ by holographic duality.

\footnote{Here we choose the total Hamilton to be $H_L + H_R$. Alternatively, we can define the total Hamilton is $H_L - H_R$, by which the TFD state will not evolve with respective to boundary $t_B$.}
In order to compute area $\Gamma$ in this case, we need first to find the boundary of entanglement wedge, i.e., the extremal surface connect $\partial A$ and $\partial B$ (see blue line in figure 4). We rewrite the metric (2.1) into following form

$$ds^2 = -g^2(\rho)dt^2 + d\rho^2 + h^2(\rho)dx_{d-1}^2,$$

where

$$h(\rho) = \frac{2}{d} \left( \cosh \frac{d\rho}{2} \right)^{2/d}, \quad g(\rho) = h(\rho) \tanh \frac{d\rho}{2}.$$  

(3.5)

(3.6)

This metric is obtained after a coordinate transformation $d\rho = \frac{dz}{z \sqrt{1-z^d}}$ and we have set $z_0 = 1$ and so $\beta = 4\pi/d$. The Penrose diagram and the entanglement wedge cross section are shown in the figure 4.

We can continue (3.5) into the interior region of figure 4 by setting $\rho = i\kappa$ and the replacement $t \rightarrow t + i\pi/2$. For the case $t_B \equiv t_R = t_L$, the maximal volume surface is given by the blue line in figure 4. The red dotted line is for $t_B = 0$. The corresponding codimension-two surface is obtained by extremalizing following integration

$$\int h(\rho)^{d-2} \sqrt{-g^2(\rho) + (\partial \rho/\partial t)^2} dt.$$  

(3.7)

In principle, we should solve the Euler-Lagrangian equation of (3.7) to find $\rho(t)$. However, because the “Lagrangian” in (3.7) does not contain “time” explicitly, there is a “conserved charge” by which we can simplify the process to find the extremal surface. Following [25–27] we may find the first integral of the equation of motion of (3.7), which yields

$$\frac{g^2 h^{d-2}}{\sqrt{-g^2 + (\partial \rho/\partial t)^2}} = i g_0 h_0^{d-2},$$

(3.8)
where \( h_0 := h(i\kappa_0) \) and \( g_0 := g(i\kappa_0) \) with \( \kappa_0 \) \((0 < \kappa_0 < \frac{\pi}{2d})\) satisfying \( \frac{\partial h_0}{\partial t}|_{\kappa=\kappa_0} = 0 \). From (3.8), we can write the time \( t_B \) in terms of \( \kappa_0 \):

\[
t_B = \int_0^{\kappa_0} \frac{d\kappa}{(\cos \frac{\kappa}{2})^2 \tan \frac{\kappa}{2} \sqrt{1 - \frac{\cos \frac{3}{2}(d\kappa_0/2)}{\cos \frac{\pi}{2}(d\kappa_2/2)} \sin^2 \theta_0}} - \int_0^{\infty} \frac{d\rho}{(\cosh \frac{\rho}{2})^2 \tanh \frac{\rho}{2} \sqrt{1 + \frac{\cos \frac{3}{2}(d\kappa_0/2) \sinh^2 \rho}{\cosh \frac{\pi}{2}(d\kappa_2/2) \sinh \rho}}}. \tag{3.9}
\]

Here we have introduced the IR cut off \( \delta \to 0 \). Substituting (3.8) into (3.7), the extremal volume can be expressed in terms of the parameter \( \kappa_0 \),

\[
S_{AB}(t_B) = 2S_{\text{div}} + 2V_{d-2} \left[ \int_0^{\kappa_0} \frac{\frac{2}{d-2} \kappa}{\cos \frac{\pi}{2}(d\kappa_2/2) \sin^2 \theta_0} - \frac{1}{\cos \frac{3}{2}(d\kappa_2/2) \sin^2 \theta_0} d\kappa \right] + \int_0^{\infty} \left( \frac{\left( \cosh \frac{\rho}{2} \right)^{2(d-2)}}{\sqrt{1 + \frac{\cosh \frac{3}{2}(d\kappa_2/2) \sinh^2 \rho}{\cosh \frac{\pi}{2}(d\kappa_2/2) \sinh \rho}}} - \frac{\sinh \left( \cosh \frac{\rho}{2} \right)^{\frac{1}{d-2}}}{\sinh \left( \cosh \frac{\rho}{2} \right)^{\frac{1}{d-2}}} d\rho \right). \tag{3.10}
\]

Here \( S_{\text{div}} \) is the universal UV divergent term for extremal surface, which reads

\[
S_{\text{div}} := \begin{cases} \frac{1}{4} \ln(\beta/\pi\epsilon), & d = 2 \\ V_{d-2} \left( \frac{\beta \epsilon}{4(d-2)} \right)^{d-2}, & d > 2. \end{cases} \tag{3.11}
\]

In the case of \( \kappa_0 \to \frac{\pi}{2d} \arcsin \sqrt{\frac{d}{2d-2}} \), the boundary time \( t_B \to \infty \) and one can find that the entanglement entropy will grow linearly [25].

Eq. (3.9) shows that relationship between \( t_B \) and \( \kappa_0 \). Now let us consider the EoP between two regions \( A \) and \( B \). The entanglement of cross section is determined by \( \kappa_0 \) only, which can give us the relationship between \( t_B \) and the EoP between two regions \( A \) and \( B \). For convenience, we will return to the coordinates \( \{t, z, \bar{z}\} \). Because of the symmetry, the entanglement wedge cross section \( \Gamma(t_B) \) is given by (see figure 4)

\[
\Gamma(t_B) := \{x_1 = x_1(s), z = z(s), -\infty < x_i < \infty, i = 2, 3, \cdots, d - 1\} \tag{3.12}
\]

where \( (x_1(s), z(s)) \) satisfies the boundary conditions

\[
x_1(0) = 0, z(0) = z_0 \tag{3.13}
\]
with \( \cos(\kappa_0/2)^{2/d} = 1/z_0 \) and makes the area of cross section
\[
S_\Gamma := V_{d-2} \int_0^\infty z^{1-d} \sqrt{|\dot{x}_1^2 + \dot{z}^2/f|} \, ds
\]  
(3.14)
to be extremal. Here the dot means the derivative with respect to parameter \( s \).

In order to obtain a well-proposed variational problem for integration (3.14), we need
to specify additional boundary conditions when \( s \to \infty \). This can be achieved by imposing
following suppositional boundary conditions at \( s = l \to \infty \):
\[
x_1(l) = l, \quad z(l) = z_0, \quad l \to \infty,
\]  
(3.15)
where \( z_0 \) is an unknown parameter. By using the boundary conditions (3.15), the extremal
value of entanglement wedge cross section reads
\[
E(t_B) := E_P(A : B) = V_{d-1} z_0^{1-d} + V_{d-2} \int_0^\infty \left[ z^{1-d} \sqrt{|\dot{x}_1^2 + \dot{z}^2/f|} - z_0^{1-d} \dot{x}_1 \right] \, ds.  
\]  
(3.16)
Here \( V_{d-1} := V_{d-2} \int_0^\infty dx_1 \). As the “Lagrangian” in (3.14) does not contain \( x_1 \) explicitly,
the “canonical momentum” corresponding to \( x_1 \) is conserved. We can obtain following
first order differential equation
\[
p_0 = z(s)^{1-d} \dot{x}_1(s)/\sqrt{|\dot{x}_1^2 + \dot{z}^2/f|} 
\]  
(3.17)
with a constant \( p_0 \). By using the freedom of reparameterization, we can choose that \( s = x_1 \).
Then the boundary conditions (3.15) imply that \( \dot{z}(\infty) = 0 \). Thus we obtain
\[
p_0 = z_0^{1-d},
\]  
(3.18)
and (3.17) leads to
\[
x_1(z) = -p_0 \int_{z_0}^z \frac{dy}{\sqrt{f(y)(y^{2-2d} - p_0^2)}} = -z_0^{1-d} \int_{z_0}^z \frac{dy}{\sqrt{f(y)(y^{2-2d} - z_0^{2-2d})}}. 
\]  
(3.19)
The boundary conditions (3.15) require \( x_1(z_0) \to \infty \), which implies
\[
\frac{d}{dy} \left[ f(y)(z_0^{2-2d} - y^{2-2d}) \right]_{y=z_0} = 0.  
\]  
(3.20)
This shows that \( z_0 = z_h = 1 \). Then we obtain
\[
E(t_B) = \frac{V_{d-1}}{4} + \frac{V_{d-2}}{4} \int_0^\infty \left[ z^{1-d} \sqrt{\dot{x}_1^2 + \dot{z}^2/f} - \dot{x}_1 \right] \, ds
\]  
(3.21)
and eq. (3.19) gives
\[
\frac{dx_1}{dz} = -\frac{1}{\sqrt{f(z)(z^{2-2d} - 1)}}. 
\]  
(3.22)
Combining above two results, we obtain

\[ E(t_B) = \frac{V_{d-1}}{4} + \frac{V_d - 2}{4} \int_1^{z_0} \sqrt{\frac{z^{2-2d} - 1}{1 - z^d}} \, dz. \]  

(3.23)

Here \( t_B \) and \( z_0 \) are connected by eq. (3.9) with \( \cos(d\kappa_0/2)^{2/d} = 1/z_0 \).

For the case that \( d = 2 \), the relationship between \( t_B \) and \( z_0 \) can be computed analytically, which yields [25]

\[ \sinh t_B = \tan \kappa_0, \quad z_0 = \frac{1}{\cos \kappa_0} = \cosh t_B, \quad \kappa_0 \in [0, \pi/2). \]  

(3.24)

The eqs. (3.16) and (3.10) turn to

\[ E(t_B) = \frac{V_1}{4} + \frac{1}{4} \ln \left( \cosh t_B \right), \quad S_{AB}(t_B) = \frac{1}{2} \ln \left( 2 \cosh t_B \right) + 2S_{\text{div}}. \]  

(3.25)

We see that, up to constant factors, the holographic entanglement entropy between \( A \cup B \) and the holographic EoP between \( A \) and \( B \) have the similar time dependent behavior,

\[ \frac{d}{dt_B} E(t_B) = \frac{1}{2} \frac{d}{dt_B} S_{AB}(t_B). \]  

(3.26)

When \( d > 2 \), there is an essential difference between the holographic entanglement entropy and the holographic EoP. From (3.9), we can find [25]

\[ \kappa_0 \in \left[ 0, \frac{2}{d} \arcsin \sqrt{d/(2d - 2)} \right). \]  

(3.27)

The corresponding \( z_0 \) then satisfies

\[ 1 \leq z_0 < \frac{2d - 2}{\sqrt{(d - 2)(3d - 2)}}. \]  

(3.28)

In the case that \( d = 2 \), \( z_0 \) will approach to infinity when \( t_B \to \infty \) and so \( E(t_B) - V_1/4 \) can approach to infinity. However, in the case \( d > 2 \), \( z_0 \) will approach to \( \sqrt{2d - 1}/z_0 \) when \( t_B \to \infty \). Then (3.23) implies \( E(t_B) - V_{d-1} z_0^{d-1}/4 \) will approach to a finite value. There is no compact the analytical solution for both holographic entanglement entropy and holographic EoP in higher dimension. The time evolitional behaviors of \( E(t_B) \) and \( \dot{E} := dE(t_B)/dt_B \) are shown in figure 5. It has been show that the holographic entanglement entropy between \( A \cup B \) and \( \overline{A} \cup \overline{B} \) will grow linearly when \( t_B \gg \beta [25] \). From the numerical results shown in the left panel of figure 5, we can see that the holographic EoP between \( A \) and \( B \) always grows. However, the speed of growth decays exponentially,

\[ \dot{E} := dE(t_B)/dt_B \propto \exp(-\alpha_d t_B/\beta). \]  

(3.29)

Here \( \alpha_d \) is a constant which depends on the dimension \( d \).
Figure 5. Relationship between entanglement of purification and time $t_B$ when $d = 3, 4, 5$. Here we set $z_h = 1$ and $\Delta E(t_B) = E(t_B) - E(0)$.

Figure 6. The case that two finite subregions are in the different boundaries of black brane. The left panel is the case $t_L = t_R = t_B > 0$ and the right panel is the case that $t_L = t_R = 0$.

3.2 Finite size case

Now let us consider two finite subregions which are in the two boundaries of the spacetime respectively. The subregions $A$ and $B$ are given by

$$A = \{t_L = t_B, 0 < x_i < \infty, i = 2, 3, \ldots, d - 1\}$$

and

$$B = \{t_R = t_B, 0 < x_i < \infty, i = 2, 3, \ldots, d - 1\}.$$

The induced density matrix of $A \cup B$ is also time-dependent,

$$\rho_{AB} = \text{Tr}_{L,0<x_1<l} \text{Tr}_{R,0<x_1<l} (|\Phi(t_B)\rangle\langle \Phi(t_B)|).$$

Thus, the entanglement of purification between $A$ and $B$ depends on time $t_B$ and the size $l$. Similar to the infinitely wide case, we can also compute the entanglement entropy for the union $A \cup B$ by (3.4), which is dependent on the width $l$ and boundary time $t_B$.

From the holographic viewpoint, we see that there are two possibilities as shown in the figure 6. The first one is the case that the extremal surfaces connecting $\partial A$ and $\partial B$
are $\Sigma_2(l)$, which are two disconnected extremal surfaces at with fixed $t$ and will give zero entanglement wedge cross section. The second one is the case that the extremal surfaces connecting $\partial A$ and $\partial B$ are $\Sigma_1(t_B)$, which connects two subregions $A$ and $B$ and has a nonzero entanglement wedge cross section $\Gamma(t_B)$. The entanglement wedge is connected only if $\Sigma_1(t_B) < \Sigma_2(l)$. We see that the nonzero initial holographic EoP $E(l, t_B = 0)$ can appear when the area of $\Sigma_1(0)$ is smaller than the area of $\Sigma_2(l)$. As the area of $\Sigma_2(l)$ is constant and zero if $l \to 0$ but the area of $\Sigma_1(t_B)$ is nonzero and increases monotonously with $t_B$ \cite{25}, we can conclude that there is a critical length $l_c$ and a critical time $t_c(l)$ for $l > l_c$ such that

$$E(t_B) = \begin{cases} 
0, & l \leq l_c, \text{ or } t_B > t_c(l) \\
\frac{1}{4} \text{Area}(\Gamma(t_B)), & l > l_c \text{ and } t_B < t_c(l).
\end{cases} \quad (3.31)$$

Here $\Gamma(t_B)$ is the extremal surface corresponding to the entanglement wedge cross section which connects the two segments of $\Sigma_1(t_B)$. Similar to the last subsection, $\Gamma(t_B)$ can be determined by finding extremal value of following integration

$$\int_{0}^{l} z^{1-d} \sqrt{|x_1^2 + z^2/f|} ds \quad (3.32)$$

with the boundary conditions

$$x_1(0) = 0, \ z(0) = z_0, \ x_1(l) = l, \ z(l) = z_0. \quad (3.33)$$

Using the similar steps in last subsection, we can obtain the expression for the area of extremal surface

$$\text{Area}(\Gamma(t_B)) = V_{d-2} l z_0^{1-d} + 2 V_{d-2} \int_{z_0}^{z_0} \frac{\bar{z}_0^{1-d} - z^{2-2d}}{\sqrt{(1-z^d)(z^{2-2d} - z_0^{2-2d})}} dz, \quad (3.34)$$

where $\bar{z}_0$ is determined by $l$ according to following differential equation

$$z_0^{1-d} = z(x_1)^{1-d}/\sqrt{1 + z^2/f}, \quad \frac{dz}{dx_1} \bigg|_{x_1=l/2} = 0. \quad (3.35)$$

Thus, in the case that $l > l_c$ and $t_B < t_c(l)$, the evolution of EoP is given by (3.34) and (3.35). The EoP will first increase with respective to $t$ and turn to zero suddenly when $t > t_c(l)$. The values of $E(t_B)$ for different $l$ and $t_B$ are shown in the figure 7.

The values of $l_c$ and $t_c(l)$ are determined as follows. Taking the time slices of $t_L = t_R = t_B = 0$, one can find that the area of $\Sigma_1(0)$ is given by

$$S_{AB}(0) := V_{d-2} \int_{e}^{z_h} \frac{dz}{z^{d-1} \sqrt{f(z)}} = \begin{cases} 
4S_{\text{div}}, & d = 2 \\
4S_{\text{div}} - \frac{V_{d-2}}{(d-2)} \left( \frac{\pi}{d\beta} \right)^{d-2} \frac{\sqrt{\pi} \Gamma(2/d)}{\Gamma(2/d - 1/2)}, & d > 2.
\end{cases} \quad (3.36)$$
Figure 7. Relationship between holographic EoP for different $l$ and time $t_B$ when $d = 2$ (left panel) and $d = 3$ (right panel). $\Delta E(t_B) = E(t_B) - E(0)$. The cases $d > 3$ are similar to the right panel.

Here $S_{\text{div}}$ is given by (3.11) and $\beta = 4\pi z_h/d$. The area of $\Sigma_2(l)$ is given by

$$S_2(l) = 2S(l)$$

and $S(l)$ is defined in (2.2). Then the value of $l_c$ is determined by

$$S_2(l_c) = S_{AB}(0).$$

When $t_L = t_R = t_B \neq 0$, the area of $S_{AB}(t_B)$ is given by (3.10), which increases monotonously with $t_B$. The value of $t_c$ is then determined by

$$S_2(l) = S_{AB}(t_c).$$

When $d = 2$, we can obtain analytical results for $l_c$ and $t_c$. $S_{AB}(t_B)$ is the same as eq. (3.25) and $S_2(l)$ is given by

$$S_2(l) = 4S_{\text{div}} + \ln \left(\frac{\pi l}{\beta}\right).$$

Solving (3.38) and (3.39), we get

$$l_c = \frac{\beta}{\pi} \ln(\sqrt{2} + 1), \quad t_c(l) = \frac{\beta}{2\pi} \text{arccosh} \left(\sinh \frac{\pi l}{\beta}\right).$$

In the limit $l \gg \beta$, we have $t_c(l) \approx l/2$. The entanglement of purification between $A$ and $B$ is shown in the left panel of figure 7.

When $d > 2$, there is no compact analytical results for $l_c$ and $t_c$. The values of $l_c$ and $t_c(l)$ can be obtained numerically by using (2.2), (2.3), (3.9) and (3.10). The results are shown in figure 8. From the right panel, we see that $t_c(l)$ increases monotonously with $l$. From the left panel, we see that $l_c$ can be approximated well by

$$z_h/l_c \approx 0.27d \Rightarrow l_c \approx \frac{\beta}{\pi} \ln(\sqrt{2} + 1).$$
This is similar to the case of BTZ black brane. When the size $l$ of $A$ and $B$ are much larger than $\beta$ and $t_B \gg \beta$, $S_2(l)$ and $S_{AB}(t_B)$ depend on $l$ and $t_B$ linearly, respectively.

\begin{equation}
S_2(l) \approx \frac{1}{2} V_{d-2} + 4 S_{\text{div}}, \quad S_{AB}(t_B) \approx v_d V_{d-2} t_B + 4 S_{\text{div}}.
\end{equation}

Here $v_2 = 1$ and $v_d = \sqrt{d(d-2)}^{\frac{1}{2}} [2(d-1)]^{1-\frac{1}{d}} \in (1/2, 1)$ for $d > 2$. Thus, we can see that,

\begin{equation}
t_c(l) = \frac{l}{2v_d}, \quad l \gg \beta.
\end{equation}

In the case of $d \gg 1$, we have $t_c \approx l$. This agrees with the numerical results shown in the right panel of figure 8.

4 Evolution of EoP after a thermal quench

In this section, we consider the evolution of EoP in CFT after a thermal quench. This process can be described holographically by the Vaidya-AdS metric which reads

\begin{equation}
ds^2 = \frac{1}{z^2} \left[ -f(v,z) dv^2 - 2 dz dv + dx^2 + \sum_{i=1}^{d-2} dy_i^2 \right],
\end{equation}

\[f(v,z) = 1 - m(v) z^d.\]

Here the AdS space radius is rescaled to 1. The mass function we take is

\begin{equation}
m(v) = \frac{M}{2} \left( 1 + \tanh \frac{v}{v_0} \right),
\end{equation}

where $v_0$ characterizes the quench speed. We fix $v_0 = 0.01$ without loss of generality and set $M = 1$ in this section for simplicity. When $v \to -\infty$, the spacetime is pure AdS. When $v \to \infty$, the spacetime becomes a planar SAdS black brane. We consider two finite strips $A$ and $B$ with the same width $l$ on one side. The separation is $D$. See figure 9 for the configuration. Due to the translation symmetry of the metric, the entanglement wedge of cross section $\Gamma$ lies in the $(z, v)$ plane as shown in figure 9.
Figure 9. The Hubeny-Rangamani-Takayanagi surfaces for finite strips in Vaidya-AdS spacetime. $m$ is the turning point of the HRT surface corresponding to strip with width $D$ and $m'$ to $2l + D$. The area of the extremal surface $\Gamma$ connecting $m$ and $m'$ is proportional to the EoP.

The EoP exists only when the MI

$$ I(l, D, t) = 2S_l(t) - S_D(t) - S_{2l+D}(t) > 0. \tag{4.3} $$

Here $S_w(t)$ is the entanglement entropy corresponding to a strip with width $w$ at the boundary time $t$. It can be calculated holographically by the area of the corresponding HRT surface.

$$ S_w(t) = \frac{2V_{d-2}}{4} \int_{\delta}^{z_0(w, t)} \frac{dz}{z^{d-1}} \frac{1}{\sqrt{f(v, z) \left(1 - \frac{z^{d-2}}{z_0^{d-2}}\right)}}. \tag{4.4} $$

Here $z_0(w, t)$ is the turning point of the corresponding HRT surface at boundary time $t$. The HRT surface can be worked out numerically, see [28] for example. We show the evolution of HMI$^3$ when $d = 2$ in figure 10. In the left panel, we fix the separation $D = 0.4$ and let $l$ run. In the right panel, we fix the width $l = 1.5$ and let $D$ run. In both panels, the HMI grows with time at first and then decreases to a value that is smaller than the initial value. The equilibrium time is about $l + D/2$. In the left panel, when $l > 1.12$, the HMI is always greater than zero in the evolution process. Namely, there is always holographic EoP between strips $A$ and $B$. When $1.12 > l > 0.963$, the HMI is greater than zero at first and then decreases to zero, i.e., there is holographic EoP at first but it vanishes later. When $0.963 > l > 0.948$, the quantity $I(l, D, t)$ is negative at first, then it grows to be positive but decreases to be negative again with time. So the holographic EoP can exist only in some time interval. When $l < 0.948$, the HMI is always zero. In the right panel, similar phenomenon is observed. We will show the evolution of holographic EoP in figure 12.

The region allowing non-vanishing holographic EoP when $d = 2$ is shown in figure 11. When $t < 0$, the spacetime is pure $AdS_3$. The corresponding HMI (4.3) can be worked out analytically,

$$ I(l, D, t < 0) = \frac{1}{2} \log \left(\frac{l^2}{D(D + 2l)}\right). \tag{4.5} $$

$^3$For more works on the evolution of mutual information, see [29, 30].
The critical separation for given $l$ is $D_c = (\sqrt{2} - 1)l$. When $t \to \infty$, the critical separation for given $l$ coincides with (2.5) for three dimensional SAdS black brane which is shown in the left panel of figure 2. Note that no matter how large $l$ is, the critical separation when $t \to \infty$ is $D_c(2, l) \leq D_c(2, \infty) = \ln 2$.

When $l$ is fixed, the separation $D$ allowing holographic EoP increases at first and then decreases as time $t$ grows. It can be shown that the time $t_m$ needed to reach the maximum critical separation $D_{cm}$ during the evolution has relation to $l$ by $t_m \simeq 0.45l$ and $D_{cm} \simeq 0.8l$ when $l$ is large enough. The time $t_e$ needed to reach equilibrium is about $t_e \simeq l + D/2$. This can be explained as follows. The HRT surface of strip $D$ reaches equilibrium more early than that of strip $2l + D$. So $t_e$ can be approximated by the time which is needed so that $S_{2l+D}(t)$ reaches equilibrium. In asymptotic $AdS_3$ black brane, this time is about $D/2 + l$. In fact, it has been shown [31] that for a given quench in 2D CFT, the density matrix of a strip with width $L$ will be exponentially close to a thermal density matrix if the time is larger than $L/2$. So the corresponding HRT surface will reach equilibrium in time about $L/2$.

Similar behaviors are observed when $d > 2$. For pure $AdS_{d+1}$ spacetime, the corresponding HMI when $t < 0$ is

$$I(l, D, t < 0) = \frac{2^{d-3} \pi^{\frac{d-1}{2}} V_d}{d - 2} \left( \frac{1}{\Gamma(\frac{1}{2d-2})} \right)^{1-d} \left( \frac{2}{l^{d-2}} - \frac{1}{D^{d-2}} - \frac{1}{(2l + D)^{d-2}} \right).$$

(4.6)

The critical separation for given $l$ is still proportional to $l$. The coefficient can be worked out from above formula. When $t \to \infty$, the critical separation for given $l$ is shown in figure 2. In the evolution process, the time $t_m$ needed to reach the maximum critical separation $D_{cm}$ and the equilibrium time $t_e$ still depend linearly on $l$. Only the coefficients are relevant to dimension $d$. For example, when $d = 3$, we have $t_m \simeq 0.7l$, $D_{cm} \simeq 0.9l$, $t_e \simeq 0.66(2l + D)$.

Once (4.3) is satisfied, the holographic EoP is proportional to the area of the extremal surface $\Gamma$ connecting $m$ and $m'$, as shown in figure 9. Due to the symmetry, the extremal surface lies in the $(z, v)$ plane. The induced metric on this plane is

$$ds^2 = \frac{1}{z^2} \left[ -f(v, z) - 2 \frac{dz}{dv} \right] dv^2 + \frac{1}{z^2} \sum_{i=1}^{d-2} dy_i^2.$$

(4.7)
Figure 11. The region below the surface has non-vanishing holographic EoP for two strips both with width \( l \) separated by \( D \) when \( d = 2 \). The maximum separation for given \( l \) during the evolution is about \( D_{\text{cm}} \approx 0.8l \) and the corresponding time \( t_m \approx 0.45l \). The equilibrium time is about \( t_e \approx D/2 + l \). For higher dimensional case, we obtain similar qualitative behaviors.

We can get the equation describing the extremal surface as

\[
0 = 2(d - 1)f^2 + 4(d - 1)z' z'' \partial_z f + f \left[ 6(d - 1)z' - z \partial_z f \right] - z(2z'' + \partial_v f). \tag{4.8}
\]

Here \( z' = \frac{dz}{dv} \). Suppose the solution between \( m = (z_D, v_D) \) and \( m' = (z_{2l+D}, v_{2l+D}) \) can be expressed as \( \tilde{z}(v) \). The holographic EoP between the two strips \( A \) and \( B \) both with width \( l \) separated by \( D \) is

\[
\frac{4}{V_{d-2}} E(l, D, t) = \int_{v_D}^{v_{2l+D}(t)} \frac{1}{\tilde{z}^{d-1}} \sqrt{-f(v, \tilde{z}) - 2 \frac{d\tilde{z}}{dv} dv}. \tag{4.9}
\]

It must be ensured that \( v_D \) and \( v_{2l+D} \) correspond to the same boundary time \( t \).

We show the evolution of holographic EoP for given \( l \) and \( D \) when \( d = 2 \) in figure 12. The behaviors of holographic EoP in higher dimension are qualitatively similar. In the left panel, we fix the separation \( D = 0.4 \) and let \( l \) run. In the right panel, we fix \( l = 1.5 \) and let \( D \) run. When \( l \) is large enough or \( D \) is small enough, the holographic EoP for given \( l \) and \( D \) grows with time at first, and then decreases with time. The equilibrium time of holographic EoP is

\[
\text{EoP: } t_e \approx l/2, \tag{4.10}
\]

which is almost independent of separation \( D \). See the right panel of figure 12 for example. On the other hand, from figure 11 and the right panel of figure 10 we can conclude that the equilibrium time of HMI is

\[
\text{HMI: } t_e \approx l + D/2, \tag{4.11}
\]

which depends on separation \( D \). Thus, from the view of point of equilibrium time, we may conclude that MI is sensitive to the whole subsystem including strips \( A, B \) and the separation, while EoP is only sensitive to strips \( A \) and \( B \) themselves. This behavior is
Figure 12. The evolution of holographic EoP (in unit of $4/V_{d-2}$) for given $l$ and separation $D$ when $d = 2$. We fix $D = 0.4$ in the left panel and $l = 1.5$ in the right panel, respectively.

more obvious in the right panel of figure 12. We see that the equilibrium time is almost irrelevant to the separation.

In the left panel, when $l > 1.12$, there is always nonvanishing holographic EoP in the whole evolution process. When $1.12 > l > 0.963$, the holographic EoP is positive at first and then drops to zero at some critical time. When $0.963 > l > 0.948$, the holographic EoP is zero at first, then jumps to be positive for some time and drops down to zero again at some critical time. When $l < 0.948$, there is no holographic EoP all the time. Similar behaviors are observed in the right panel.

5 Summaries and discussions

In this paper, we studied the holographic entanglement of purification for Schwarzschild-AdS black branes and Vaidya-AdS black branes. For Schwarzschild-AdS black branes, we considered two disjoint strips with the same width on the same boundary and two boundaries respectively. For Vaidya-AdS black branes, we studied two disjoint strips with the same width on the same boundary.

For two disjoint trips on the same boundary of different dimensional Schwarzschild-AdS black branes, we found that there are critical separations beyond which the holographic EoP will vanish. When the strip width is small, the critical separation is linearly proportional to the strip width in which the coefficient depends on the spacetime dimension. When the strip width is very large, the critical separation is almost independent of the strip width, but inversely proportional to the spacetime dimension. For three dimensional black brane, the relationship between critical separation and strip width is given by eq. (2.5). There are no compact analytical results in higher dimensions. For fixed strip width, the holographic EoP diverges when the separation goes to zero. As the separation grows, the EoP takes a nosedive. When the separation goes beyond the critical separation, the holographic EoP drops discontinuously to zero. For fixed separation, the holographic EoP vanishes when the strip width is small. It becomes positive discontinuously when the strips are wide enough. When the strip width is very large, the holographic EoP tends to a saturation value. The larger the separation is, the smaller saturation of holographic EoP.

In the case that the two strips lay symmetrically on the two-copy boundaries of the maximally extended Schwarzschild-AdS black brane, we studied how the holographic EoP
evolves with respect to one boundary time \( t_B \). When the strip width \( l \to \infty \), the initial holographic EoP is given by eq. (3.16), which is always nonzero. In the case that \( d = 2 \), the growth behaviors of holographic EoP and holographic entanglement entropy are similar and show the linear growth at the late time limit. However, in the cases of \( d > 2 \), the holographic EoP will still grow with respect to time but the growth rate will exponentially decay to zero. If the width \( l \) of strips is finite, there is a critical width \( l_c \) and critical time \( t_c(l) \) and the holographic EoP is nonzero only when \( l > l_c \) and \( t_B < t_c(l) \). In this case, the holographic EoP will first increase with respect to \( t_B \) and suddenly drop into zero when \( t_B \geq t_c(l) \).

We also considered the evolution of EoP after a thermal quench for CFT. This process can be described holographically by the Vaidya-AdS spacetime. We find that the critical separation allowing nonvanishing holographic EoP increases with time and then decreases to a smaller value at late time. The maximum separation during the evolution is proportional to the strip width. The holographic EoP exists only when the HMI is positive. We find that when the strip width \( l \) is large enough or the separation \( D \) is small enough, the HMI is always positive. It grows with time at first but then decreases to a smaller value later. When \( d = 2 \), the equilibrium time is about \( l + D/2 \). This can be understood from [31] which has shown that the reduced density matrix of a strip with width \( l \) towards thermal equilibrium with time scale \( l/2 \) in two dimensional CFT. On the other hand, we find that the equilibrium time of holographic EoP is about \( l/2 \) and is almost independent of the separation \( D \). Thus we conclude that MI is sensitive to the whole subsystem including strips and the separation, while the EoP is only sensitive to strips themselves. When the strip width is small or the separation is large, the EoP changes discontinuously while the HMI changes continuously. Similar behaviors are found in higher dimensional spacetime.

In this paper, our discussion is limited to the leading order. The HMI of two disjoint region suffers a phase transition from nonzero to zero when the separation is larger than a critical distance [32]. However, the quantum mutual information satisfies actually an inequality [10],

\[
I(A,B) \geq \frac{C(M_A,M_B)^2}{2 ||M_A||^2 ||M_B||^2}, \tag{5.1}
\]

where \( M_A \) and \( M_B \) are the observables in the regions \( A \) and \( B \) respectively, and \( C(M_A,M_B) := \langle M_A \otimes M_B \rangle - \langle M_A \rangle \langle M_B \rangle \) is the correlation function of \( M_A \) and \( M_B \). This indicates that, due to the quantum correlations, the quantum MI of two disjoint regions is usually not vanishing, even when they are far apart. Thus, when considering the quantum correlations, as a result of (1.5), we should not expect the EoP disappears immediately after the transition point. How to describe the quantum correction in the dual bulk is still a question.

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