UNIFORM AND OPTIMAL ERROR ESTIMATES OF AN EXPONENTIAL WAVE INTEGRATOR SINE PSEUDOSPECTRAL METHOD FOR THE NONLINEAR SCHRODINGER EQUATION WITH WAVE OPERATOR∗

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Abstract. We propose an exponential wave integrator sine pseudospectral (EWI-SP) method for the nonlinear Schrödinger equation (NLS) with wave operator (NLSW), and carry out rigorous error analysis. The NLSW is NLS perturbed by the wave operator with strength described by a dimensionless parameter \( \varepsilon \in (0, 1] \). As \( \varepsilon \to 0^+ \), the NLSW converges to the NLS and for the small perturbation, i.e. \( 0 < \varepsilon \ll 1 \), the solution of the NLSW differs from that of the NLS with a function oscillating in time with \( O(\varepsilon^2) \)-wavelength at \( O(\varepsilon^4) \) amplitudes for ill-prepared and well-prepared initial data, respectively. This rapid oscillation in time brings significant difficulties in designing and analyzing numerical methods with error bounds uniformly in \( \varepsilon \). In this work, we show that the proposed EWI-SP possesses the optimal uniform error bounds at \( O(\tau^2) \) and \( O(\tau) \) in \( \tau \) (time step) for well-prepared initial data and ill-prepared initial data, respectively, and spectral accuracy in \( h \) (mesh size) for the both cases, in the \( L^2 \) and semi-H\(^1 \) norms. This result significantly improves the error bounds of the finite difference methods for the NLSW. Our approach involves a careful study of the error propagation, cut-off of the nonlinearity and the energy method. Numerical examples are provided to confirm our theoretical analysis.

Key words. nonlinear Schrödinger equation with wave operator, error estimates, exponential wave integrator, sine pseudospectral method

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1. Introduction. In this paper, we consider the nonlinear Schrödinger equation with wave operator (NLSW) in \( d \) (\( d = 1, 2, 3 \)) dimensions as \( [4, 6, 8, 11, 22, 25, 29, 31] \)

\[
\begin{align*}
\left\{ \begin{array}{ll}
  i\partial_t \psi(x, t) - \varepsilon^2 \partial_{tt} \psi(x, t) + \nabla^2 \psi(x, t) + f(|\psi(x, t)|^2) \psi(x, t) = 0, & x \in \mathbb{R}^d, \ t > 0, \\
  \psi(x, 0) = \psi_0(x), & x \in \mathbb{R}^d, \\
  \partial_t \psi(x, 0) = \psi_0^1(x), & x \in \mathbb{R}^d,
\end{array} \right.
\end{align*}
\]

where \( \psi := \psi(x, t) \) is a complex function, \( x \) is the spatial variable, \( t \) is the time, \( 0 < \varepsilon \leq 1 \) is a dimensionless parameter, \( f : [0, +\infty) \to \mathbb{R} \) is a real-valued function, and \( \nabla^2 = \Delta \) is the Laplace operator in \( d \) dimensional space. In this paper, we will consider \( \psi_0^1 \) to be \( O(1) \) w.r.t. \( \varepsilon \).

The NLSW has different physical applications, including the nonrelativistic limit of the Klein-Gordon equation [22, 25, 29], the Langmuir wave envelope approximation in plasma [8, 11], and the modulated planar pulse approximation of the sine-Gordon equation for light bullets [6, 31].

As proven by [8, 22, 25, 29], when \( \varepsilon \to 0^+ \), the NLSW (1.1) converges to the standard nonlinear Schrödinger equation (NLS),

\[
\begin{align*}
\left\{ \begin{array}{ll}
  i\partial_t \psi(x, t) + \nabla^2 \psi(x, t) + f(|\psi(x, t)|^2) \psi(x, t) = 0, & x \in \mathbb{R}^d, \ t > 0, \\
  \psi(x, 0) = \psi_0(x), & x \in \mathbb{R}^d.
\end{array} \right.
\end{align*}
\]

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Due to the wave operator, the solution of the NLSW (1.1) differs from the solution of the NLS (1.2) with a function oscillating in time $t$ with $O(\varepsilon^2)$ wavelength. Indeed, to measure the difference between the NLSW (1.1) and the NLS (1.2), we can write the initial velocity $\psi_0^\varepsilon$ for the NLSW (1.1) as

$$\psi_0^\varepsilon(x) = i (\nabla^2 \psi_0(x) + f(|\psi_0(x)|^2)\psi_0(x)) + \varepsilon^\alpha \omega(x), \quad \alpha \geq 0,$$

where $i (\nabla^2 \psi_0(x) + f(|\psi_0(x)|^2)\psi_0(x))$ corresponds to the initial velocity for the NLS (1.2). Then we have the following asymptotic expansion for the solution $\psi(x, t)$ of the NLSW (1.1) as $\varepsilon \to 0^+$ (cf. [4])

$$\psi(x, t) = \psi^\varepsilon(x, t) + \varepsilon^2 \{\text{terms without oscillation}\} + \varepsilon^{2+\min\{\alpha, 2\}} \widetilde{\Psi}(x, t/\varepsilon^2) + \text{higher order terms with oscillation},$$

where $\psi^\varepsilon := \psi^\varepsilon(x, t)$ satisfies the NLS (1.2).

Based on this asymptotic expansion, we can make assumptions (A) and (B) (cf. section 2.2) on the NLSW. Furthermore, from (1.4), we identify two cases for the imposed initial data (1.3), i.e., the well-prepared initial data when $\alpha \geq 2$ and the ill-prepared initial data when $0 \leq \alpha < 2$.

Various numerical methods have been developed in the literatures for the NLS, including the time-splitting pseudospectral method [3, 7, 9, 17, 21, 23, 24, 27], finite difference method [1–3, 10, 15], etc. Meanwhile, there are few numerical methods for the NLSW and conservative finite difference methods [11, 16, 30] are the most popular ones. In our recent work [4], both the conservative Crank-Nicolson finite difference scheme and the semi-implicit finite difference scheme have been analyzed for NLSW. We have proved the uniform $l^2$ and semi-$H^1$ error estimates of these two schemes w.r.t. $\varepsilon \in (0, 1]$, at the order of $O(h^2 + \tau)$ for well-prepared initial data and $O(h^2 + \tau^{2/3})$ for ill-prepared initial data, in all dimensions ($d = 1, 2, 3$), with mesh size $h$ and time step $\tau$. However, the uniform convergence rates are not optimal in $\tau$. Here, we propose an exponential wave integrator sine pseudospectral (EWI-SP) method with uniform spectral accuracy in space, and the method has the optimal uniform error bounds in time at the order $O(\tau^2)$ for well-prepared initial data and $O(\tau)$ for ill-prepared initial data. EWI-SP greatly improves the uniform convergence rate compared to the finite difference methods, and the uniform error bounds are optimal for the well-prepared initial data case. In fact, the exponential wave integrator has been widely used in solving highly oscillatory PDE [5] and ODE problems [14, 18], and the main advantage of EWI-SP is that only second order derivatives in time are involved, which is the key point in our analysis to get the optimal and uniform error bounds. Other techniques of the analysis include the cut-off of the nonlinearity, energy method, and recursion properties of the scheme.

This paper is organized as follows. In section 2, we introduce EWI-SP method and our main results. Section 3 is devoted to the error estimates of EWI-SP in the case of well-prepared initial data. In section 4, ill-prepared initial data case is considered. Numerical results are reported in section 5 to confirm the error estimates. Then some conclusions are drawn in section 6. Throughout the paper, $C$ will denote a generic constant independent of $\varepsilon$, mesh size $h$ and time step $\tau$, and we use the notation $A \lesssim B$ to mean that there exists a generic constant $C$ which is independent of $\varepsilon$, time step $\tau$ and mesh size $h$ such that $|A| \leq C B$.

2. Exponential-wave-integrator sine pseudospectral method and results. In practical computation, the NLSW (1.1) is usually truncated on a bounded interval $\Omega = (a, b)$ in 1D ($d = 1$), or a bounded rectangle $\Omega = (a, b) \times (c, d)$ in 2D ($d = 2$) or a bounded box $\Omega = (a, b) \times (c, d) \times (e, f)$ in 3D ($d = 3$), with zero Dirichlet boundary condition. This truncation is accurate as long as the solution of (1.1) stays localized. For the simplicity of notation, we only deal with the case in 1D, i.e. $d = 1$ and $\Omega = (a, b)$. Extensions to 2D and 3D are straightforward, and the error estimates in $L^2$-norm and semi-$H^1$ norm are the same in 2D and 3D (cf. Remark 4.1). In 1D, NLSW (1.1) is truncated on the
interval \( \Omega = (a, b) \) as

\[
\begin{cases}
i \partial_t \psi(x, t) - \varepsilon^2 \partial_{xx} \psi(x, t) + \partial_x \psi(x, t) + f(|\psi(x, t)|^2) \psi(x, t) = 0, & x \in \Omega \subset \mathbb{R}, \ t > 0, \\
\psi(x, 0) = \psi_0(x), & x \in \Omega, \\
\psi(x, t)|_{\partial \Omega} = 0, & t > 0.
\end{cases}
\]

(2.1)

As \( \varepsilon \to 0^+ \), the solution of equation (2.1) will converge to the solution of the corresponding NLS \([4, 8, 25, 29]\)

\[
\begin{cases}
i \partial_t \psi^\varepsilon(x, t) + \partial_{xx} \psi^\varepsilon(x, t) + f(|\psi^\varepsilon(x, t)|^2) \psi^\varepsilon(x, t) = 0, & x \in \Omega \subset \mathbb{R}, \ t > 0, \\
\psi^\varepsilon(x, 0) = \psi_0(x), & x \in \Omega, \\
\psi^\varepsilon(x, t)|_{\partial \Omega} = 0, & t > 0.
\end{cases}
\]

(2.2)

In the spirit of (1.3), we assume the initial data satisfy the condition

\[
\psi_1^\varepsilon(x) = \psi_1(x) + \varepsilon^\alpha \omega^\varepsilon(x), \quad x \in \Omega,
\]

(2.3)

where \( \psi_1(x) = i (\partial_{xx} \psi_0(x) + f(|\psi_0(x)|^2) \psi_0(x)) \) is the value of \( \partial_t \psi^\varepsilon(x, t) \mid_{t=0} \) with \( \psi^\varepsilon(x, t) \) being the solution of the limiting NLS (2.2). \( \omega^\varepsilon \) is uniformly bounded in \( H^1_0 \cap H^2 \) (w.r.t. \( \varepsilon \)) and satisfies \( \liminf_{\varepsilon \to 0^+} \|\omega^\varepsilon\|_{H^2} > 0 \) and \( \alpha \geq 0 \) is a parameter describing the compatibility of the initial data with respect to the limiting NLS (2.2).

### 2.1. EWI-SP method.

For simplicity of notations, we define \( \alpha^* \) as

\[
\alpha^* = \min \{\alpha, 2\}.
\]

(2.4)

We also denote the nonlinear term \( f(|z|^2)z \) as

\[
\mathcal{F}(z) = f(|z|^2)z, \quad \forall z \in \mathbb{C}.
\]

(2.5)

Choose time step \( \tau := \Delta t \) and denote time steps as \( t_n := n \tau \) for \( n = 0, 1, 2, \ldots \); choose mesh size \( \Delta x := \frac{b-a}{M} \) with \( M \) being a positive integer and denote \( h := \Delta x \) and grid points as

\[
x_j := a + j \Delta x, \quad j = 0, 1, \ldots, M.
\]

Define the index sets

\[
\mathcal{T}_M = \{ j \mid j = 1, 2, \ldots, M - 1 \}, \quad \mathcal{T}_M^0 = \{ j \mid j = 0, 1, 2, \ldots, M \}.
\]

(2.6)

and denote

\[
X_M = \text{span} \left\{ \Phi_l(x) = \sin (\mu_l (x-a)), \quad \mu_l = \frac{\pi l}{b-a}, \quad x \in \Omega, \ l \in \mathcal{T}_M \right\},
\]

\[
Y_M = \left\{ v = (v_0, v_1, \ldots, v_M)^T \in \mathbb{C}^{M+1} \mid v_0 = v_M = 0 \right\}.
\]

We define the finite difference operators as usual, for \( \psi(x_j, t_n) \) (\( j \in \mathcal{T}_M^0, \ n \geq 1 \)),

\[
\delta^+_\tau \psi(x_j, t_n) = \frac{1}{h} (\psi(x_{j+1}, t_n) - \psi(x_j, t_n)), \quad \delta^-_\tau \psi(x_j, t_n) = \frac{1}{\tau} (\psi(x_j, t_n) - \psi(x_j, t_{n-1})).
\]

(2.7)
The exponential wave integrator sine spectral method of NLSW (2.1) is to apply sine spectral method for spatial discretization and exponential wave integrator for time. For any function \( \psi(x) \in L^2(\Omega) \), \( \phi(x) \in C_0(\Omega) \), and vector \( \phi = (\phi_0, \phi_1, \ldots, \phi_M)^T \in Y_M \), let \( P_M : L^2(\Omega) \to X_M \) be the standard \( L^2 \) projection onto \( X_M \) and \( I_M : C_0(\Omega) \to X_M \) and \( I_M : Y_M \to X_M \) be the standard sine interpolation operator as

\[
(P_M \psi) (x) = \sum_{l=1}^{M-1} \hat{\psi}_l \sin(\mu_l(x - a)), \quad (I_M \phi) (x) = \sum_{l=1}^{M-1} \hat{\phi}_l \sin(\mu_l(x - a)), \quad x \in \Omega = [a, b],
\]

and the coefficients are given by

\[
\hat{\psi}_l = \frac{2}{b-a} \int_a^b \psi(x) \sin(\mu_l(x - a)) \, dx, \quad \hat{\phi}_l = \frac{2}{M} \sum_{j=1}^{M-1} \phi_j \sin(jl\pi/M), \quad l \in \mathcal{T}_M,
\]

where \( \phi_j = \phi(x_j) \) when \( \phi \) is a function instead of a vector.

The sine spectral discretization for equation (2.1) becomes:

Find

\[
\psi_M := \psi_M(x, t) = \sum_{l=1}^{M-1} \hat{\psi}_l(t) \sin(\mu_l(x - a)), \quad x \in \Omega, \ t \geq 0,
\]

such that

\[
(i\partial_t - \varepsilon^2 \partial_x^2)\psi_M(x, t) + \Delta \psi_M(x, t) + P_M (f(|\psi_M|^2)\psi_M) = 0, \quad x \in \Omega, \ t > 0.
\]

Substituting (2.10) into (2.11) and making use of the fact that \( \Phi_l(x) = \sin(\mu_l(x - a)) \) (2.6) are orthogonal to each other, we have

\[
-\varepsilon^2 \frac{d^2}{dt^2} \hat{\psi}_l(t) + \frac{d}{dt} \hat{\psi}_l(t) - |\mu_l|^2 \hat{\psi}_l(t) + \left( \mathcal{F}(\psi_M) \right)_l = 0, \quad l \in \mathcal{T}_M, \ t > 0.
\]

Then, a numerical method can be designed by properly treating the above second order ODEs (2.12) [5,14,18], e.g. solving (2.12) via variation of constant formula and approximating the convolution term in a good manner. Now, let us state our approach in detail. For each \( l \in \mathcal{T}_M \), around time \( t_n = n\tau \) \((n \geq 0)\), we reformulate the above ODE as

\[
-\varepsilon^2 \frac{d^2}{dt^2} \hat{\psi}_l(t_n + s) + i\frac{d}{dt} \hat{\psi}_l(t_n + s) - |\mu_l|^2 \hat{\psi}_l(t_n + s) + f^\nu_l(s) = 0, \quad s \in \mathbb{R},
\]

where

\[
f^\nu_l(s) = \left( \mathcal{F}(\psi_M) \right)_l (t_n + s).
\]

For \( l \in \mathcal{T}_M \) and \( s \in \mathbb{R} \), we denote

\[
\beta^+_l = \frac{1 + \sqrt{1 + 4\varepsilon^2|\mu_l|^2}}{2\varepsilon^2} = O\left( \frac{1}{\varepsilon^2} \right), \quad \beta^-_l = \frac{1 - \sqrt{1 + 4\varepsilon^2|\mu_l|^2}}{2\varepsilon^2} = \frac{-2|\mu_l|^2}{1 + \sqrt{1 + 4\varepsilon^2|\mu_l|^2}} O(1),
\]

\[
\beta_l = \beta^+_l - \beta^-_l = \frac{\sqrt{1 + 4\varepsilon^2|\mu_l|^2}}{\varepsilon^2} = O\left( \frac{1}{\varepsilon^2} \right), \quad \kappa_l(s) = e^{is\beta^+_l} - e^{is\beta^-_l} = O(1).
\]
Optimal uniform error estimates of EWI-SP for NLSW

Solving the above second order ODE (2.13), e.g., using the variation-of-constant formula, the solution can be written as follows, for any $s \in \mathbb{R}$,

\begin{equation}
\hat{\psi}_l(t_n + s) = \gamma^n_l e^{i\beta l} + \nu^n_l e^{i\beta l} s - \frac{i}{\varepsilon^2 \beta l} \int_0^s f^n_l (s_1) \kappa_l (s - s_1) \, ds_1,
\end{equation}

with

\begin{equation}
\gamma^n_l = \beta^+_l \hat{\psi}_l (t_n) + i \partial_t \hat{\psi}_l (t_n), \quad \nu^n_l = \beta^+_l \hat{\psi}_l (t_n) + i \partial_t \hat{\psi}_l (t_n).
\end{equation}

Using the formula (2.16) and (2.17), we are going to determine the suitable approximations of $\hat{\psi}_l$ at different time steps. For $n = 0$, let $s = \tau$ in (2.16), then we get

\begin{equation}
\hat{\psi}_l (t_{n+1}) = - e^{\tau / \beta_l} \hat{\psi}_l (t_{n-1}) + 2 e^{\tau / \beta_l} \cos (\tau / \beta_l / 2) \hat{\psi}_l (t_n) - \frac{i}{\varepsilon^2 \beta_l} \int_0^\tau f^n_l (s) \kappa_l (\tau - s) \, ds
\end{equation}

\begin{equation}
+ \frac{i e^{\tau / \beta_l}}{\varepsilon^2 \beta_l} \int_0^\tau f^n_{l-1} (s) \kappa_l (\tau - s) \, ds.
\end{equation}

For convenience, we recall the definition of ‘sinc’ function as

\begin{equation}
sinc (s) = \frac{\sin (s)}{s}, \quad \text{for } s \neq 0, \text{ and } sinc (0) = 1,
\end{equation}

and introduce the following notations for $l \in T_M$,

\begin{equation}
\sigma^+_l (s) = e^{is \beta^+_l / 2} \text{sinc} (s \beta^+_l / 2), \quad \sigma^-_l (s) = e^{is \beta^-_l / 2} \text{sinc} (s \beta^-_l / 2), \quad s \in \mathbb{R}.
\end{equation}

We approximate the integrals in (2.18) and (2.19) as follows:

\begin{equation}
\int_0^\tau f^n_l (s) \kappa_l (\tau - s) \, ds \approx \int_0^\tau \left( f^n_l (0) + s \partial_t f^n_l (0) \right) \kappa_l (\tau - s) \, ds
\end{equation}

\begin{equation}
\approx \tau f^n_l (0) \left( \sigma^+_l (\tau) - \sigma^-_l (\tau) \right) + i \tau \partial_t f^n_l (0) \left( \frac{1 - \sigma^+_l (\tau)}{\beta^+_l} - \frac{1 - \sigma^-_l (\tau)}{\beta^-_l} \right),
\end{equation}

\begin{equation}
\int_0^\tau f^n_l (s) \kappa_l (-s) \, ds \approx \tau f^n_l (0) \left( \frac{1 - \sigma^+_l (\tau)}{\beta^+_l} - \frac{1 - \sigma^-_l (\tau)}{\beta^-_l} \right),
\end{equation}

where $\bar{c}$ denotes the complex conjugate of $c$ and $\partial_t f^n_l (0)$ can be computed exactly since $\partial_t \hat{\psi} (t = 0)$ is known using the initial data. For $n \geq 1$, we use the similar approximation as above and approximate $\partial_t f^n_l (0)$ by finite difference $\delta^n_l \hat{f}_l^n (0)$,
For convenience of notations, we denote \( \mathcal{D}(\phi(x, t_n)) \) for \( \phi(x, t) \) as

\[
\mathcal{D}(\phi(0)) = \frac{d}{dt} \mathcal{F}(\phi(t))|_{t=0}, \quad \mathcal{D}(\phi(t_n)) = \delta_{t_n} \mathcal{F}(\phi(t_n)), \quad n \geq 1.
\]

Thus, sine spectral method for solving (2.1) can be derived as follows. For \( n \geq 0 \), let \( \psi_n^M(x) \) be the approximations of \( \psi_M(x, t_n) \). Choose \( \psi_0^M = P_M(\psi_0) \), then \( \psi_M^{n+1}(x) \) for \( n \geq 0 \) is given by

\[
\psi_M^{n+1}(x) = \sum_{l=1}^{M-1} (\hat{\psi}_M^{n+1})_l \sin(\mu(x-a)), \quad x \in \Omega, \quad n = 0, 1, \ldots,
\]

where the sine transform coefficients can be obtained via the following formula

\[
\begin{align*}
(\hat{\psi}_M^1)_l &= c^0_l (\psi_0^M)_l + d^0_l (\hat{\psi}_1^0)_l + p_1(\mathcal{F}(\psi_0^M))_l + q_1(\mathcal{D}(\psi_0^M))_l, \\
(\hat{\psi}_M^{n+1})_l &= c_l (\hat{\psi}_M^n)_l + d_l (\psi_M^n)_l + p_1(\mathcal{F}(\psi_M^n))_l + q_1(\mathcal{D}(\psi_M^n))_l - p^n_1(\mathcal{F}(\psi_M^n))_l - q^n_1(\mathcal{D}(\psi_M^n))_l,
\end{align*}
\]

where \( \mathcal{D}(\psi_M^n) \) is given by (2.23) as

\[
\mathcal{D}(\psi_M^n) = G(\psi_M^n)P_M(\psi_0^M) + H(\psi_M^n)P_M(\hat{\psi}_1^0), \quad \mathcal{D}(\psi_M^n) = \delta_{t_n} \mathcal{F}(\psi_M^n), \quad n \geq 1,
\]

with

\[
G(z) = f(|z|^2) + f'(|z|^2) \cdot |z|^2, \quad H(z) = f'(|z|^2)z^2, \quad \forall z \in \mathbb{C},
\]

\[
c^0_l = \frac{\beta_l^+ e^{\tau \sigma^+} - \beta_l^- e^{\tau \sigma^-}}{\beta_l}, \quad d^0_l = -i e^{\tau \sigma^-} \sin(\tau \beta_l), \quad p_1 = -i e^{\tau \sigma^-} (\sigma_l^+ - \sigma_l^-),
\]

\[
q_l = \frac{\sigma}{e^{\tau \beta_l}} \left( \frac{1 - \sigma_l^+(\tau)}{\beta_l} - \frac{1 - \sigma_l^- (\tau)}{\beta_l} \right), \quad p^n_1 = -i e^{\tau \sigma^-} (\sigma_l^+ - \sigma_l^-),
\]

\[
q^n_l = \frac{\tau e^{\tau \beta_l}}{e^{\tau \beta_l}} \left( \frac{1 - \sigma_l^+(\tau)}{\beta_l} - \frac{1 - \sigma_l^- (\tau)}{\beta_l} \right), \quad c_l = -e^{\tau \beta_l}, \quad d_l = 2 e^{\tau \beta_l} \cos(\tau \beta_l),
\]

We note that \( |c_l|, |d_l|, |\sigma_l^0| \lesssim 1, |\sigma_l^0|, |q_l|, |q^n_l| \lesssim \tau^2 \) and \( |p_1|, |p^n_1| \leq \tau \) \((l \in \mathcal{T}_M)\).

In practice, the above approach is not suitable due to the difficulty of computing the sine transform coefficients in (2.25) through the integrals given in (2.9). Here, we present an efficient implementation by choosing \( \psi_M(x) \) as the interpolation of \( \psi_0(x) \) on the grid points \( \{x_j, j \in \mathcal{T}_M\} \), i.e., \( \psi_M(x, 0) = \psi_M(\psi_0(x)) \), and approximating the integrals in (2.9) and (2.25) by a quadrature rule on the grid points.

Now, we state the exponential wave integrator sine pseudospectral (EWI-S) method. Let \( \psi^n_j \) \((n \geq 1)\) be the approximation of \( \psi(x_j, t_n) \) with \( \psi_0^n = \psi^n_0 = 0 \), and we denote \( \psi_j^0 = \psi_0(x_j), \omega_j = \omega^c(x_j) \) \((j \in \mathcal{T}_M)\), \( \psi^n = (\psi^n_0, \psi^n_1, \ldots, \psi^n_M)^T \in \mathcal{Y}_M \). Thus, the numerical approximation \( \psi^{n+1} \in \mathcal{Y}_M \) at time \( t_{n+1} \) \((n = 0, 1, \ldots)\) can be computed as

\[
\psi_j^{n+1} = \sum_{l=1}^{M-1} (\hat{\psi}_M^{n+1})_l \sin(jl\pi/M), \quad j \in \mathcal{T}_M, \quad n = 0, 1, \ldots,
\]

where the coefficients are obtained through the following formula,

\[
\begin{align*}
(\hat{\psi}_1)_l &= c^0_l (\psi_0)_l + d^0_l (\hat{\psi}_1^0)_l + p_1(\mathcal{F}(\psi_0))_l + q_1(\mathcal{D}(\psi_0))_l, \quad \text{and for } n \geq 1 \text{ as }
(\hat{\psi}_M^{n+1})_l &= c_l (\hat{\psi}_M^n)_l + d_l (\psi_M^n)_l + p_1(\mathcal{F}(\psi_M^n))_l + q_1(\mathcal{D}(\psi_M^n))_l - p^n_1(\mathcal{F}(\psi_M^n))_l - q^n_1(\mathcal{D}(\psi_M^n))_l,
\end{align*}
\]
and $D(\psi_0)$ is defined by (2.23) as

$$D(\psi_0) = G(\psi_0)\psi_0^c + H(\psi_0)\psi_0^t, \quad D(\psi^n) = \delta^n F(\psi^n), \quad n \geq 1,$$

with $c_1^0$, $d_1^0$, $c_i$, $d_i$, $p_i$, $q_i$, $p_i^s$, and $q_i^s$ given in (2.27). In computation, sometimes $\psi_1$ (2.3) is not explicitly known, we can replace $(\psi_1^c)_t$ and $(\psi_1^t)_t$ (in (2.29)) by the approximation below, and the main results remain the same,

$$\hat{(\psi_1^c)_t} \approx -i(\mu_1)^2(\hat{\psi_0})_t + i(\hat{F(\psi_0)})_t + \varepsilon^n(\omega^c)_t.$$

The EWl-SP (2.28)-(2.30) is explicit, and can be solved efficiently by fast sine transform. The memory cost is $O(M)$ and the computational cost per time step is $O(M \log M)$. Actually, the scheme has a very good recursion property in phase space (cf. (3.32) and Lemma 3.4). The observation is the following: from the equation (2.1), we can see that there are two characteristics corresponding to the operators $U_+ (t) = e^{\frac{i\varepsilon^\alpha}{2}\int_{0}^{t} e^{\frac{i\varepsilon^\alpha}{2}L}d\tau}$ and $U_- (t) = e^{-\frac{i\varepsilon^\alpha}{2}\int_{0}^{t} e^{-\frac{i\varepsilon^\alpha}{2}L}d\tau}$. As $\varepsilon \to 0^+$, the first characteristic component $U_+$ will vanish while oscillating in time, and the second characteristic component $U_-$ will converge to the Schrödinger operator. That is to say, the solution behaves differently along the two characteristics.

In our scheme EWl-SP, these characteristics are treated separately through the approximations of the integrals in (2.18) and (2.19), unlike those wave-type equations (without $i\partial_t$ term) [5] and second order ODEs [14, 18].

The pseudospectral method EWl-SP (2.28)-(2.29) is a full discretization and the spectral method (2.24)-(2.25) is a semi-discretization. For simplicity, we will prove the error estimates for the full discretization and omit the analysis for the semi-discretization which can be done in the same spirit.

**Remark 2.1.** If we consider the NLSW (2.1) with periodic boundary condition or homogenous Neumann boundary condition, similar Fourier pseudospectral method or cosine pseudospectral method can be easily designed as above, and the main results in this paper remain valid in both cases.

### 2.2. Main results.

In order to state our main results, we introduce the convenient Sobolev spaces. Let $\phi(x) \in H^m(\Omega) \cap H_0^1(\Omega)$ be represented in sine series as

$$\phi(x) = \sum_{l=1}^{+\infty} \hat{\phi}_l \Phi_l(x), \quad x \in \Omega = (a, b),$$

with $\hat{\phi}_l$ and $\Phi_l(x)$ given in (2.9) and (2.6), respectively. Define the subspace of $H^m \cap H_0^1$ as $H^{m}_s(\Omega) = \{ \phi \in H^m(\Omega) | \partial_x^{2k} \phi(a) = \partial_x^{2k} \phi(b) = 0, \quad 0 \leq 2k < m \}$ (the boundary values are understood in the trace sense) equipped with the norm

$$\| \phi \|_{H^m_s(\Omega)} = \left( \sum_{l=1}^{+\infty} h_1^{2m} |\hat{\phi}_l|^2 \right)^{\frac{1}{2}},$$

which is equivalent to the $H^m$ norm in this subspace. In the remaining part of this paper, we will omit $\Omega$ when the norm is only taken with respect to the spatial variables.

For $u = (u_0, u_1, \ldots, u_M)^T \subset Y_M$, we define the discrete $l^2$, semi-$H^1$ and $l^\infty$ norms as

$$\| u \|^2_{l^2} = h \sum_{j=1}^{M-1} |u_j|^2, \quad \| \delta_x^+ u \|^2_{l^2} = h \sum_{j=1}^{M-1} |\delta_x^+ u_j|^2, \quad \| u \|_{l^\infty} = \max_{j \in T_M} |u_j|. $$
According to the known results in [8,22,25,29] and the asymptotic expansion in section 1, we make the following assumptions on NLSW (2.1), i.e. assumptions on the initial data (2.3) for (2.1),

\( (A) \quad 1 \lesssim |\omega^2(\cdot)|_{H^{m_0}} \lesssim 1, \quad \psi_0 \in H^{m_0+2}_s \quad \text{for some} \quad m_0 \geq 2; \)

and assumptions on the solution \( \psi(t) = \psi(\cdot, t) \) of the NLSW (2.1) and the solution \( \psi^s(\cdot, t) \) of the NLS (2.2), i.e., let \( 0 < T < T_{\text{max}} \) with \( T_{\text{max}} \) being the maximal common existing time,

\( (B) \quad \|\psi\|_{L^\infty([0,T],L^\infty \cap H^{m_0 \cap H_k^s})} + \|\partial_t \psi\|_{L^\infty([0,T],H^1)} + \|\psi^s\|_{L^\infty([0,T],L^\infty \cap H^{m_0 \cap H_k^s})} \lesssim 1, \quad m_0 \geq 2; \)

and \( \|\partial_t \psi\|_{L^\infty([0,T],H^1)} \lesssim \frac{1}{\varepsilon^{2-\alpha}}, \quad \|\partial_t \psi^s\|_{L^\infty([0,T],H^1)} \lesssim 1, \quad \|\psi - \psi^s\|_{L^\infty([0,T],H^1)} \lesssim \varepsilon^2, \quad k = 1, 2. \)

Under assumption (A), we can verify that \( \psi_1, \psi^s_1 \in H^{m_0}_s \) for function \( f(\cdot) \) smooth enough. Under assumption (B), in view of the equations (2.1) and (2.2), and Lemma 3.3, it is easy to show that \( \psi, \psi^s \in L^\infty([0,T];H^{m_0}_s). \)

Denote the constant \( M_1 \) as

\[
M_1 = \max \left\{ \sup_{x \in (0,1)} \|\psi(x,t)\|_{L^\infty([0,T] \times \Omega)}, \|\psi^s(x,t)\|_{L^\infty([0,T] \times \Omega)} \right\}.
\]

We can prove the following error estimates for EW1-SP (2.28)-(2.30).

**Theorem 2.1.** *(Well-prepared initial data)* Let \( \psi^n \in Y_M \) and \( \psi^n_T(x) = I_M(\psi^n) \) \((n \geq 0)\) be the numerical approximations obtained from EW1-SP (2.28)-(2.30). Assume \( f(s) \in C^k([0, +\infty)) \) \((k \geq 3)\), under assumptions (A) and (B), there exist constants \( 0 < \tau_0, \frac{h_0}{\varepsilon} \leq 1 \) independent of \( \varepsilon \), if \( 0 < h \leq h_0 \) and \( 0 < \tau \leq \tau_0 \), we have for \( \alpha \geq 2 \), i.e. the well-prepared initial data case,

\[
\begin{align*}
&\|\psi(\cdot, t_n) - \psi^n_T(\cdot)\|_{L^2} \lesssim h^m + \tau^2, \quad \|\psi^n\|_{L^\infty} \lesssim M_1 + 1, \\
&\|\nabla(\psi(\cdot, t_n) - \psi^n_T(\cdot))\|_{L^2} \lesssim h^{m-1} + \tau^2, \quad 0 \leq n \leq \frac{T}{\tau},
\end{align*}
\]

where \( m = \min\{m_0, k\} \) and \( M_1 \) is defined in (2.35).

Similarly, we have for the ill-prepared initial data case.

**Theorem 2.2.** *(Ill-prepared initial data)* Under the same condition of Theorem 2.1, there exist constants \( 0 < \tau_0, \frac{h_0}{\varepsilon} \leq 1 \) independent of \( \varepsilon \), if \( 0 < h \leq h_0 \) and \( 0 < \tau \leq \tau_0 \), we have for \( \alpha \in [0,2) \), i.e. the ill-prepared initial data case,

\[
\begin{align*}
&\|\psi(\cdot, t_n) - \psi^n_T(\cdot)\|_{L^2} \lesssim h^m + \frac{\tau}{\varepsilon^{2-\alpha}}, \quad \|\nabla(\psi(\cdot, t_n) - \psi^n_T(\cdot))\|_{L^2} \lesssim h^{m-1} + \frac{\tau^2}{\varepsilon^{2-\alpha}}, \\
&\|\psi(\cdot, t_n) - \psi^n_T(\cdot)\|_{L^2} \lesssim h^m + \tau^2 + \varepsilon^2, \quad \|\nabla(\psi(\cdot, t_n) - \psi^n_T(\cdot))\|_{L^2} \lesssim h^{m-1} + \tau^2 + \varepsilon^2, \\
&\|\psi^n\|_{L^\infty} \lesssim M_1 + 1, \quad 0 \leq n \leq \frac{T}{\tau},
\end{align*}
\]

where \( m = \min\{m_0, k\} \) and \( M_1 \) is defined in (2.35). Thus, by taking the minimum of \( \varepsilon^2 \) and \( \frac{\tau^2}{\varepsilon^{2-\alpha}} \) for \( 0 < \varepsilon \leq 1 \), we could obtain uniform error bounds as

\[
\begin{align*}
&\|\psi(\cdot, t_n) - \psi^n_T(\cdot)\|_{L^2} \lesssim h^m + \tau^{4/(4-\alpha)}, \quad \|\nabla(\psi(\cdot, t_n) - \psi^n_T(\cdot))\|_{L^2} \lesssim h^{m-1} + \tau^{4/(4-\alpha)}, \quad 0 \leq n \leq \frac{T}{\tau},
\end{align*}
\]
Remarks 2.2. The main results can be extended directly to the system of $N$ $(N \geq 2)$ coupled nonlinear Schrödinger equations with wave operator (NLSW) as

$$i\partial_t \psi_k - \varepsilon^2 \partial_{tt} \psi_k(x,t) + \nabla^2 \psi_k(x,t) + f_k(|\psi_1|^2, \ldots, |\psi_N|^2) \psi_k(x,t) = 0, \quad k = 1, \ldots, N,$$

where the initial data and boundary conditions for each $\psi_k$ are similarly given as (2.1) and (2.3), and the functions $f_k : [0, \infty)^N \to \mathbb{R}$ $(k = 1, \ldots, N)$ belong to $C^k$ $(k \geq 3)$ function class.

Since the exact solution behaves very differently for the well-prepared initial data $(0 \leq \alpha < 2)$ (see (1.4) and [4]), we treat these two cases separately. For the well-prepared initial data, in order to prove Theorem 2.1, we will compare the EWI-SP approximation (2.28)-(2.31) with the well-prepared initial data, in order to prove Theorem 2.2, we will compare the EWI-SP approximation (2.28)-(2.31) with the $L^2$ projection of the exact solution. Following the steps in section 2.1, where we construct the EWI-SP (2.28)-(2.31), it is easy to find that the errors introduced only come from the trigonometric interpolation (spectral accurate in space) and Gaußchei type quadrature [14, 18] for the integrals in (2.16) (second order accurate in time). This observation gives Lemma 3.4 for the local truncation error, which is of spectral order in space and second order in time. In addition, because we use a Gaußchei type quadrature, the scheme (2.28)-(2.31) posses a very nice recursive property which leads to the nice recursion formula for the error (3.32). These are the key points in our analysis. In the proof, we also use the cutoff technique for the nonlinear term, discrete Sobolev inequality and the energy method.

For the ill-prepared initial data, in order to prove Theorem 2.2 with two different estimates, we adopt a strategy similar to the finite difference method [4] (cf. diagram (4.1)). The idea for establishing the estimates is analogous to that of Theorem 2.1. The same analysis works for 2D and 3D cases, and we discuss this in Remark 4.1

3. Convergence in the well-prepared initial data case. Before the analysis of convergence, we first review and introduce some lemmas for the projection operator $P_M$ and interpolation operator $I_M$ [20, 26].

Lemma 3.1. ($L^2$ projection) Let $\phi(x) \in H^m_0(\Omega)$ $(m \geq 2)$, then

$$\|\phi - P_M(\phi)\|_{L^2} \leq \pi^{-m} h^m, \quad \|
abla\phi - P_M(\phi)\|_{L^2} \leq \pi^{-m} h^{m-1}.$$ (3.1)

For the sine trigonometric interpolation $I_M$, we have similar results.

Lemma 3.2. (Sine interpolation) Let $\phi(x) \in H^1_0(\Omega)$ and $\phi = (\phi_0, \phi_1, \ldots, \phi_M)^T$ with $\phi_j = \phi(x_j)$ $(j \in \mathbb{N}_M)$, we have

$$\|I_M(\phi)(\cdot)\|_{L^2} \leq \|\phi(\cdot)\|_{L^2} + h\|
abla\phi(\cdot)\|_{L^2}, \quad \|\delta_+^h \phi(\cdot)\|_{L^2} \leq \|
abla I_M(\phi)(\cdot)\|_{L^2} \leq \frac{\pi}{2} \|\delta_+^h \phi\|_{L^2}.$$ (3.2)

$I_M$ and $P_M$ are identity transforms on $X_M$, and if $\phi(x) \in X_M$, then

$$\|
abla\phi(\cdot)\|_{L^2} \leq \|\phi(\cdot)\|_{L^2}.$$ (3.3)

Proof. The lemma can be proved analogous to [20, 26]. We prove the first statement here for reader’s convenience. By definition of $I_M$, using Cauchy inequality, it is easy to check that

$$\|I_M(\phi)(\cdot)\|_{L^2}^2 = h \sum_{j=1}^{M-1} |\phi(x_j)|^2 = \|\phi(\cdot)\|_{L^2}^2 - \sum_{j=0}^{M-1} \int_{x_j}^{x_{j+1}} (|\phi(x)|^2 - |\phi(x_j)|^2) \ dx$$

$$= \|\phi(\cdot)\|_{L^2}^2 - \sum_{j=0}^{M-1} \int_{x_j}^{x_{j+1}} \sum_{\delta_k \phi(x_k)} |\phi(x')|^2 \ dx' \ dx$$

$$\leq \|\phi(\cdot)\|_{L^2}^2 + 2h\|
abla\phi(\cdot)\|_{L^2} \|\phi(\cdot)\|_{L^2},$$ (3.3)
which implies the first conclusion by using Cauchy inequality. For the second conclusion, we note that
\[
\|\nabla I_M(\phi)\|^2_2 = \frac{h-a}{2} \sum_{l=1}^{M-1} |\mu_l|^2 |\tilde{\phi}_l|^2, \quad \delta_\phi^2 \phi(x_j) = \sum_{l=0}^{M-1} \frac{\mu_l}{h} \sin(\frac{\mu_l}{2} j) \cos(\mu_l(j+\frac{1}{2})h), \quad 0 \leq j \leq M - 1,
\]
thus by Parseval’s identity, we know
\[
\|\delta_\phi^2 \phi\|^2_2 = \frac{hM}{2} \sum_{l=0}^{M-1} |\mu_l|^2 |\tilde{\phi}_l|^2 |\sin(\frac{\mu_l}{2})|^2.
\]
Recalling that \(0 < \frac{1}{4} \mu_l h \leq \frac{\pi}{2} (l \in \mathcal{T}_M), \sin(\frac{\mu_l h}{2}) \in [\frac{1}{2}, 1], \) we get the second conclusion. 

For \(I_M\) applied to the nonlinear term, we require some regularity to achieve the desired accuracy. 

Lemma 3.3. For \(\phi(x) \in H^m_s(\Omega) (m \geq 2)\) and \(f(\cdot) \in C^k([0, \infty)) (k \geq 2), \) we have
\[
F(\phi) = f(|\phi|^2) \phi \in H^m_s, \quad \text{with} \quad \|F(\phi)\|_{H^q} \lesssim \|\phi\|_{H^q}, \quad m^* = \min\{m, k\}.
\]

Proof. This is essentially due to the fact that \(F(\phi)\) maps an odd function to an odd function. The results can be checked by direct computation and we omit it here. 

Using Lemmas 3.1 and 3.2, we find for any \(\Phi \in \mathcal{H}_0\),
\[
\|I_M(\Phi) - P_M(\Phi)\|_{L^2} = \|I_M[\Phi - P_M(\Phi)]\|_{L^2} \lesssim \|\Phi - P_M(\Phi)\|_{L^2} + h\|\nabla(\Phi - P_M(\Phi))\|_{L^2}.
\]
Let \(\psi_t(x, t)\) be the solution of the NLSW (2.1), we write \(\psi(t)\) in short of \(\psi(x, t)\). In order to prove the main theorem, we define the ‘local truncation error’ \(\xi^\alpha(x) = \sum_{l=1}^{M-1} (\xi_l^\alpha) \Phi_l(x) \in X_M\) for \(l \in \mathcal{T}_M\) as
\[
(\xi_l^\alpha)_l = c_l^\alpha (\check{\psi})_l + d_l^\alpha (\check{\psi})_l + p_l(\check{\Phi}(\psi))_l + q_l(\check{D}(\psi))_l = (\xi_l^\alpha)_l,
\]
\[
(\xi_l^\alpha)_l = c_l(\psi(\tau_{l-1}))_l + d_l(\psi(\tau_{l-1}))_l + p_l(\check{\Phi}(\psi(\tau_{l-1})))_l + q_l(\check{D}(\psi(\tau_{l-1})))_l = (\xi_l^\alpha)_l,
\]
\[
(\xi_l^\alpha)_l = c_l(\psi(\tau_{l-1}))_l + d_l(\psi(\tau_{l-1}))_l + p_l(\check{\Phi}(\psi(\tau_{l-1})))_l + q_l(\check{D}(\psi(\tau_{l-1})))_l = (\xi_l^\alpha)_l,
\]
\[
\xi_0^\alpha(x) = e^{i\tau \beta_l^\alpha} \xi_0^\alpha(x) - e^{i\tau \beta_l^\alpha} \xi_0^\alpha(x),
\]
\[
\xi_0^\alpha(x) = e^{i\tau \beta_l^\alpha} \xi_0^\alpha(x) - e^{i\tau \beta_l^\alpha} \xi_0^\alpha(x),
\]
where \(\xi^{\alpha, \pm}(x) = \sum_{l=1}^{M-1} (\xi_l^{\alpha, \pm}) \Phi_l(x) \in X_M\) and for \(\alpha \geq 2, \) i.e., the well-prepared initial data case, we have
\[
\|\xi^{\alpha, \pm}(\cdot)\|_{L^2} \lesssim \tau h^m + \tau^3, \quad \|\nabla \xi^{\alpha, \pm}(\cdot)\|_{L^2} \lesssim \tau h^{m-1} + \tau^3, \quad m = \min\{m_0, k\}, \quad n \geq 0;
\]
for \(\alpha \in [0, 2), \) i.e. the ill-prepared initial data case, we have
\[
\|\xi^{\alpha, \pm}(\cdot)\|_{L^2} \lesssim \tau h^m + \tau^3, \quad \|\nabla \xi^{\alpha, \pm}(\cdot)\|_{L^2} \lesssim \tau h^{m-1} + \tau^3, \quad m = \min\{m_0, k\}, \quad n \geq 0.
\]
In addition, the coefficients $p_l, q_l, p^*_l$ and $q^*_l \ (n \geq 0)$ given in (2.27) can be split as

$$p_l = e^{i\tau \beta^+_l} p^+_l - e^{i\tau \beta^-_l} p^-_l, \quad q_l = e^{i\tau \beta^+_l} q^+_l - e^{i\tau \beta^-_l} q^-_l, \quad p^*_l = e^{i\tau \beta^+_l} (p^+_l - p^-_l), \quad q^*_l = e^{i\tau \beta^-_l} (q^+_l - q^-_l),$$

$$p_l = -i \frac{\epsilon}{\epsilon^2 \beta_l} \hat{\gamma}^+_l(\tau), \quad p^-_l = i \frac{\epsilon}{\epsilon^2 \beta_l} \hat{\gamma}^-_l(\tau), \quad q_l = \frac{\tau}{\epsilon^2 \beta_l} \left( 1 - \sigma^+_l(\tau) \right), \quad q^-_l = \frac{\tau}{\epsilon^2 \beta_l} \left( 1 - \sigma^-_l(\tau) \right),$$

where $|p^+_l| \lesssim \tau, |q^+_l| \lesssim \tau^2$.

Proof. Multiplying both sides of NLSW (2.1) by $\Phi_l(x) = \sin(\mu l (x - a))$ and integrating over $\Omega$, we easily recover the equations for $(\psi_l(t))$, which are exactly the same as the (2.12) with $\psi_M$ being replaced by $\psi(x,t)$. Replacing $\psi_M$ with $\psi(x,t)$, we use the same notations $f^n_l(s)$ as in (2.14), and it is worth noting that the time derivatives of $f^n_l(s)$, enjoy the same properties of time derivatives of $\mathcal{F}(\psi(x,t))$. Thus, the same representations (2.18) and (2.19) hold for $(\psi(t_n))$ with $n = 1$ and $n \geq 2$, respectively.

Now it is clear that the error $\xi^n(x)$ comes from the approximations for the integrals (2.25) and trigonometric interpolation (2.29). First, we can write the integrals in (2.18) and (2.19) as

$$\int_0^1 f^+_l(s) k_1(\tau - s) ds = e^{i\tau \beta^+_l} \int_0^1 f^+_l(s) e^{-i\beta^+_l s} ds - e^{i\tau \beta^-_l} \int_0^1 f^-_l(s) e^{-i\beta^-_l s} ds,$$

then $\xi^n(x) \ (n \geq 0)$ can be written as (3.8) with

$$\xi^{n,+}(x) = \eta^{n,+}(x) + \zeta^{n,+}(x), \quad \xi^{n,-}(x) = \eta^{n,-}(x) + \zeta^{n,-}(x),$$

where the interpolation error $\zeta^{n,+}(x), \zeta^{n,-}(x) \in X_M \ (n \geq 0)$ are determined by their sine transform coefficients for $l \in \mathcal{T}_M$ given by

$$(\zeta^{n,\pm}_l) = p^\pm_l ([\mathcal{F}(\psi_0)]_l - (\mathcal{F}(\psi_0))_l) + q^\pm_l [(\hat{G}(\psi_0) \psi^*_l)_l + (\hat{H}(\psi_0) \psi^*_l)_l] - (\hat{H}(\psi_0) \psi^*_l)_l,$$

with coefficients $p^\pm_l$ and $q^\pm_l$ given in the lemma, and the integral approximation error $\eta^{n,+}(x), \eta^{n,-}(x) \in X_M \ (n \geq 0)$ are given by their sine transform coefficients as, for $l \in \mathcal{T}_M$,

$$(\eta^{n,\pm}_l) = -i \frac{\epsilon}{\epsilon^2 \beta_l} \int_0^1 \int_0^s \int_0^1 (\partial_t f^n_l(s_2)) e^{-is \beta^\pm_l} ds_2 ds_1 ds, \quad \text{and for } n \geq 1,$$

Now, to obtain estimates (3.9) and (3.10), we only need to estimate $\zeta^{n,\pm}$ and $\eta^{n,\pm}$.

First, let us consider $\zeta^{n,\pm}$. For $n = 0$, recalling assumptions (A) and (B), it is easy to verify that $\psi_0, \psi(\tau)$ belong to $H^{m\pm}_s$ and $\psi^*_l \in H^m_0 \ (m = \min\{m_0, k\})$, while $\mathcal{F}(\psi_0)$ belongs to $H^{m\min\{m_0, k\}} \ G(\psi_0) \psi^*_l$ and $H(\psi_0) \psi^*_l$ belong to $H^{m*}_s \ (m* = \min\{m, k - 1\} \geq 2)$. Hence, noticing (3.6) and Lemma 3.1, we know

$$\|\zeta^{n,\pm}\|_{L^2} \lesssim \tau (h^m + \tau h^{m*}) \lesssim \tau (h^m + \tau^2), \quad \|\nabla \zeta^{n,\pm}\|_{L^2} \lesssim \tau (h^{m-1} + \tau^2).$$

Similarly, we can get for $n \geq 1$ that

$$\|\zeta^{n,\pm}\|_{L^2} \lesssim \tau h^m, \quad \|\nabla \zeta^{n,\pm}\|_{L^2} \lesssim \tau h^{m-1}.$$
Then we estimate \( \eta^{n,\pm} \). Noticing \( f \in C^3 \) and assumptions (A) and (B), in view of the particular assumption \( \partial_t \psi \sim \varepsilon^{\alpha - 2} \), we can deduce that for \( t \in [0, T] \),

\[
(3.17) \quad \| \partial_t F(\psi(t)) \|_{L^2} \lesssim \varepsilon^{\alpha - 2}, \quad \| \nabla [\partial_t F(\psi(t))] \|_{L^2} \lesssim \varepsilon^{\alpha - 2}.
\]

The key point is the behavior of \( \partial_t \psi \). Substituting all the above results into (3.14), we can easily get

\[
| \partial_t F(\psi(s_2)) \|_{L^2} \lesssim 2 \tau \varepsilon^{\alpha - 2}.
\]

and by applying Cauchy inequalities and Bessel inequalities as well as (3.17), we obtain

\[
(3.18) \quad \| \partial_t F(\psi(s_2)) \|_{L^2} \lesssim \tau \varepsilon^{\alpha - 2}.
\]

In the same spirit, we can deduce that

\[
(3.19) \quad \| \partial_t F(\psi(s_2)) \|_{L^2} \lesssim \tau \varepsilon^{\alpha - 2}.
\]

Thus, we have proved that

\[
(3.20) \quad \| \partial_t F(\psi(s_2)) \|_{L^2} \lesssim \tau \varepsilon^{\alpha - 2}.
\]

Now, we are ready to prove the lemma. By combining all the results above and triangle inequality, we finally prove (3.9) and (3.10) if we separate the cases \( \alpha \geq 2 \) and \( \alpha \in [0, 2) \).

Now, let us look back at our main results. Making use of explicit property of the proposed scheme, we know that if the error estimates are correct, we can replace the nonlinearity \( F(z) = f(|z|^2)z \) by a cut-off nonlinearity \( F_n(z) \) defined as

\[
(3.19) \quad F_n(z) = \rho \left( \frac{|z|^2}{B} \right) f(|z|^2)z, \quad \text{where} \quad \rho(s) \in C^\infty_0(\mathbb{R}) \quad \text{satisfying} \quad \rho(s) = \begin{cases} 1, & |s| \leq 1, \\ 0, & |s| \geq 2, \\ \in [0, 1], & |s| \in [1, 2]. \end{cases}
\]

where \( B = (M_1 + 1)^2 \) with \( M_1 \) given in (2.35). It is true that this replacement doesn’t affect NLS and NLS by themselves. Thus, if the same error estimates in Theorem 2.1 and 2.2 hold for NLS with the truncated nonlinearity \( F_n(z) \), it is a direct consequence that the error estimates (Theorem 2.1 and 2.2) hold true for NLS with nonlinearity \( F(z) \) as the corresponding numerical schemes coincide in this case (see more discussions in [2, 4]).

Based on the above observation, we only need to prove Theorems 2.1 and 2.2 for the nonlinearity \( F(z) \) replaced by \( F_n(z) \). From now on, we will treat \( F(z) \) as \( F_n(z) \) while not changing the notation.

Proof of Theorem 2.1. Let us define the error \( e^n \in Y_M \) and \( e^n(x) \in X_M \) \( (n \geq 0) \) as

\[
(3.20) \quad e^n = (P_M \psi(t_n))(x_j) - \psi^n_j, \quad j \in T^n, \quad n \geq 0
\]

\[
(3.21) \quad e^n(x) = I_M(e^n)(x) = \sum_{i=1}^{M-1} (e^n_i) \Phi_i(x), \quad n \geq 0, \quad x \in \Omega.
\]
Then, by triangle inequality and Lemma 3.2 as well as assumptions (A) and (B), we obtain

\[
\|\psi(\cdot, t_n) - \psi^n(\cdot)\|_{L^2} \leq \|\psi(\cdot, t_n) - P_M(\psi(t_n))(\cdot)\|_{L^2} + \|e^n(\cdot)\|_{L^2} \lesssim h^{m_0} + \|e^n(\cdot)\|_{L^2},
\]

\[
\|\nabla\psi(\cdot, t_n) - \psi^n(\cdot)\|_{L^2} \lesssim h^{m_0 + 1} + \|\nabla e^n(\cdot)\|_{L^2}, \quad n \geq 0.
\]

Applying inverse inequality, and Lemma 3.2 further, we have

\[
\|\psi^n\|_{L^\infty} \leq \sup_{j \in T_M^d} \|\psi(x_j, t_n) - \psi^n_j\| + \|\psi(t_n)\|_{L^\infty} \leq \sup_{j \in T_M^d} \|e^n_j + \psi(x_j, t_n) - P_M(\psi(t_n))(x_j)\| + M_1
\]

\[
\leq M_1 + \|e^n\|_{L^\infty} + \sup_{j \in T_M^d} |I_M(\psi(t_n))(x_j) - P_M(\psi(t_n))(x_j)|
\]

\[
\leq M_1 + \|e^n\|_{L^\infty} + C_1 h^{d/2} \|I_M(\psi(t_n))(\cdot) - P_M(\psi(t_n))(\cdot)\|_{L^2}
\]

\[
\leq M_1 + C_2 h^{m_0 - d/2} + \|e^n\|_{L^\infty} \leq M_1 + \frac{1}{2} + \|e^n\|_{L^\infty}, \quad n \geq 0,
\]

where \(C_1\) and \(C_2\) depend on \(\|\psi\|_{L^\infty([0, T] \cap H^{m_0})}\) and \(0 < h < h_1\) for some \(h_1 > 0\), \(d\) is the dimension of the spatial space, i.e., \(d = 1\) in the current case. However, we put \(d\) here to indicate how the proof works for two and three dimensions \((d = 2, 3)\) (see also Remark 4.1). As a consequence of the discrete Sobolev inequality in 1D,

\[
\|e^n\|_{L^\infty} \lesssim \|e^n\|_{H^1}^{1/2} \|e^n\|_{L^2} \lesssim \|e^n(\cdot)\|_{L^2} \|\nabla e^n(\cdot)\|_{L^2},
\]

we only need to estimate the \(L^2\) and semi-\(H^1\) norms of \(e^n(x)\) \((n \geq 0)\).

For \(e^0\) and \(e^1\), considering \(e^0(x)\), we note

\[
e^0(x) = P_M(\psi(0))(x) - I_M(\psi(0))(x),
\]

in view of Lemma 3.2 and (3.6), we get \(\|e^0(\cdot)\|_{L^2} \lesssim h^{m_0} \lesssim h^m\) and \(\|\nabla e^0(\cdot)\|_{L^2} \lesssim h^{m_0 - 1} \lesssim h^{m-1}\), where \(m = \min\{m_0, k\}\). For \(e^1(x)\), we have \(\psi^0_j \in H^m_n\) and

\[
(e^1)_t = -\langle \tilde{e}^i \rangle_t + e^i_t \left( (\tilde{\psi}^0)_t - (\tilde{\psi}_0)_t \right) + d^i_t \left( (\tilde{\psi}^i)_t - (\tilde{\psi}^i)_t \right).
\]

Then Lemma 3.4 implies \(\|e^1(\cdot)\|_{L^2} \lesssim h^m + \tau^3\) and \(\|\nabla e^1(\cdot)\|_{L^2} \lesssim h^{m-1} + \tau^3\). It is obvious \(\|\psi^0\|_{L^\infty} \leq M_1 + 1\), and by discrete Sobolev inequality, we obtain

\[
\|e^1\|_{L^\infty} \lesssim \|e^1(\cdot)\|_{L^2} \|\nabla e^1(\cdot)\|_{L^2} \lesssim h^{m_0 - 2} + \tau^6,
\]

which implies there exist \(h_2, \tau_1 > 0\) such that \(\|e^1\|_{L^\infty} \leq \frac{1}{2}\), and \(\|\psi^1\|_{L^\infty} \leq M_1 + 1\) for \(0 < \tau \leq \tau_1\), \(0 < h \leq h_2\) in view of (3.22). This proves the conclusion for \(n = 0, 1\) in Theorem 2.1 by noticing (3.21).

Before going to the next step, we note the decomposition as

\[
(e^0)_{l_t} = (e^{0, +})_t + (e^{0, -})_l, \quad (e^1)_t = (e^{0, +})_t e^{1, +} - (e^{0, -})_t e^{1, -} - (\tilde{\psi}^0)_l, \quad l \in T_M,
\]

where \(e^{0, \pm}(x) = \sum_{l=1}^{M_1} (\tilde{e}^{0, \pm})_l \Phi_l(x) \in X_M\) are given by

\[
(e^{0, +})_l = -\frac{\beta_+}{\beta_0}(\tilde{\psi}_l - \tilde{\psi}_0) - \frac{i}{\beta_0}[(\tilde{\psi}^0)_l - (\tilde{\psi}_0)_l] h - (\tilde{\psi}^0)_l h, \quad (e^{0, -})_l = \frac{\beta_+}{\beta_0}(\tilde{\psi}_l - \tilde{\psi}_0) + \frac{i}{\beta_0}[(\tilde{\psi}^0)_l - (\tilde{\psi}_0)_l] + \frac{i}{\beta_0}[(\tilde{\psi}^0)_l h - (\tilde{\psi}_0)_l h].
\]
We can easily derive that

$$\|e^{0,\pm}(\cdot)\|_{L^2} \lesssim \h^m, \quad \|\nabla e^{0,\pm}(\cdot)\|_{L^2} \lesssim \h^{m-1}. \quad (3.28)$$

**Error equation for** $e^n(x)$ ($n \geq 2$). For other time steps, subtracting (3.7) from (2.29) and noticing $e^{i\tau} = e^{i\tau_1^+} \cdot e^{i\tau_1^-}$ and $2e^{i\tau} \cos(\frac{\tau_1}{2}) = e^{i\tau_1^+} + e^{i\tau_1^-}$, we obtain

$$(3.29) \quad (\tilde{e}^{n+1})_l = -e^{i\tau(\beta_1^+ + \beta_1^-)}(\tilde{e}^{n-1})_l + (e^{i\tau\beta_1^+} + e^{i\tau\beta_1^-})(\tilde{e}^n)_l - (\tilde{\xi}^n)_l + \tilde{W}^n_l, \quad n \geq 1, \quad l \in T_M,$$

where $\tilde{W}^n_l$ can be written as follows (similar as Lemma 3.4),

$$\tilde{W}^n_l = e^{i\tau\beta_1^+} \tilde{W}^{n,+}_l - e^{i\tau\beta_1^-} \tilde{W}^{n,-}_l - e^{i\tau}(\tilde{W}^{n-1,+}_l - \tilde{W}^{n-1,-}_l), \quad n \geq 1, \quad \text{with} \quad \tilde{W}^0_l = 0,$$

$$\tilde{W}^{n,\pm}_l = \tilde{p}_l \left( (\mathcal{F}(\tilde{\psi}(t_n)))_l - (\mathcal{F}(\tilde{\psi}^n))_l \right) + q^l \left( \delta_l^\pm (\mathcal{F}(\tilde{\psi}(t_n)))_l - \delta_l^\pm (\mathcal{F}(\tilde{\psi}^n))_l \right), \quad n \geq 1, \quad l \in T_M.$$  

**Property of** $\tilde{W}^{n,\pm}_l$. Next, we claim that if $\|\psi^n\|_{L^\infty} \leq M_1 + 1$, under assumptions (A) and (B), $f \in C^3([0,\infty))$ and $\mathcal{F}(z)$ enjoys the properties of $\mathcal{F}_n(z)$ (3.19), then we have (see detailed proof in Appendix)

$$\frac{b-a}{2} \sum_{l=1}^{M-1} |\tilde{W}^{n,\pm}_l|^2 \lesssim \tau^2 \sum_{k=n-1}^{n} \|e^k(\cdot)\|_{L^2}^2 + \tau^2 \h^{2m_0}, \quad (3.30)$$

$$\frac{b-a}{2} \sum_{l=1}^{M-1} \tilde{p}_l^2 |\tilde{W}^{n,\pm}_l|^2 \lesssim \tau^2 \sum_{k=n-1}^{n} \|e^k(\cdot)\|_{L^2}^2 + \|\nabla e^k(\cdot)\|_{L^2}^2 + \tau^2 \h^{2m_0-2}, \quad n \geq 1. \quad (3.31)$$

**Proof by energy method.** Using (3.29) iteratively, noticing Lemma 3.4 and above decomposition (3.30), we can find that for $n \geq 1$,

$$\tilde{e}^{n+1} = (\tilde{e}^{0,\pm})_l e^{i(n+1)\tau\beta_1^+} + (\tilde{e}^{0,\pm})_l e^{i(n+1)\tau\beta_1^-} - \sum_{k=0}^{n} \left( (\tilde{\xi}_{k,+}^n)_l e^{i(n+k)\tau\beta_1^+} - (\tilde{\xi}_{k,-}^n)_l e^{i(n+k)\tau\beta_1^-} \right), \quad l \in T_M. \quad (3.32)$$

Using Cauchy inequality, we have

$$|\tilde{e}^{n+1}_l|^2 \lesssim 6 \left( |(\tilde{e}^{0,\pm})_l|^2 + |(\tilde{e}^{0,\pm})_l|^2 + (n+1) \sum_{k=0}^{n} |(\tilde{\xi}_{k,+}^n)_l|^2 + (n+1) \sum_{k=0}^{n} |(\tilde{\xi}_{k,-}^n)_l|^2 \right) + n \sum_{k=1}^{n} |\tilde{W}_{l,k}^{+,\pm}|^2 + n \sum_{k=1}^{n} |\tilde{W}_{l,k}^{-,\pm}|^2, \quad l \in T_M, \quad (3.33)$$

Then summing above inequalities together for $l \in T_M$, making use of Lemma 3.4 and Parseval identity,
noticing claim (3.31), for all $1 \leq n \leq \frac{T}{\tau} - 1$, we have $\|e^{n+1}(\cdot)\|_{L^2} = \frac{k-\sigma}{2} \sum_{l=1}^{M-1} |(e^{n+1})(\cdot)|^2$ and

$$\|e^{n+1}(\cdot)\|_{L^2}^2 \leq 6\left(\|e^{0,+}(\cdot)\|_{L^2}^2 + \|e^{0,-}(\cdot)\|_{L^2}^2 + (n + 1) \sum_{k=0}^{n} (\|\xi_{k,+}(\cdot)\|_{L^2}^2 + \|\xi_{k,-}(\cdot)\|_{L^2}^2)
+ nC_0 \tau^2 \sum_{k=0}^{n} (\|e^{k}(\cdot)\|_{L^2}^2 + h^{2m_0})\right)$$

$$\leq C_1 h^{2m_0} + (n + 1)^2 \tau C_2 (\tau^4 + h^{2m}) + C_0 T \tau \sum_{k=0}^{n} \|e^{k}(\cdot)\|_{L^2}^2$$

$$\leq C_3 (\tau^4 + h^{2m}) + C_0 T \tau \sum_{k=0}^{n} \|e^{k}(\cdot)\|_{L^2}^2, \quad 1 \leq n \leq \frac{T}{\tau} - 1,$$

where $C_0, C_1, C_2$ and $C_3$ are constants depending on $T$, $f(\cdot)$, $M_1$ and $\|\psi\|_{L^\infty([0,T];H^{m_0})}$. Thus, the error bounds for $e^0(x)$ and $e^1(x)$ combined with discrete Gronwall inequality [4, 15, 16] would imply that there exists a $\tau_2 > 0$ independent of $\varepsilon$ such that when $0 < \tau \leq \tau_2$, we can get

$$\|e^{n+1}(\cdot)\|_{L^2}^2 \lesssim \tau^4 + h^{2m}, \quad \text{and} \quad \|e^{n+1}(\cdot)\|_{L^2} \lesssim \tau^2 + h^m, \quad 1 \leq n \leq \frac{T}{\tau} - 1. \tag{3.34}$$

Then we estimate $\|\nabla e^{n+1}(\cdot)\|_{L^2}$. Similar as the above $L^2$ case, multiplying both sides of (3.33) by $|\mu_l|^2$ and summing up for all $l \in T_M$, noticing claim (3.31), for all $1 \leq n \leq \frac{T}{\tau} - 1$, using the derived $L^2$ estimates, we know

$$\|\nabla e^{n+1}(\cdot)\|_{L^2}^2 \lesssim \left(\|\nabla e^{0,+}(\cdot)\|_{L^2} + \|\nabla e^{0,-}(\cdot)\|_{L^2} + (n + 1) \sum_{k=0}^{n} (\|\nabla \xi_{k,+}(\cdot)\|_{L^2}^2 + \|\nabla \xi_{k,-}(\cdot)\|_{L^2}^2)
+ n \tau^2 \sum_{k=0}^{n} (\|e^{k}(\cdot)\|_{L^2}^2 + h^{2m_0})\right)$$

$$\lesssim (\tau^4 + h^{2m_0^2}) + \tau \sum_{k=0}^{n} \|\nabla e^{k}(\cdot)\|_{L^2}^2, \quad 1 \leq n \leq \frac{T}{\tau} - 1.$$
4. Convergence in the ill-prepared initial data case. Next, we start to prove Theorem 2.2. Again we will treat $F(z)$ as $F_{\mu}(z)$ while not changing the notation. The idea of the proof is shown in the diagram (4.1), where $\psi_{h,\tau}$ denotes the EWI-SP numerical solution, $\psi$ is the exact solution of the corresponding NLS, and $\psi^s$ is the exact solution of the corresponding NLS. In fact, the similar idea has been employed in the study of asymptotic preserving (AP) schemes [13, 19].

\begin{equation}
\begin{aligned}
\psi_{h,\tau} & \quad \xrightarrow{O(h^m+\tau^s+z^2)} \psi \\
& \quad \xrightarrow{L^2 \text{ error}} \psi^s
\end{aligned}
\end{equation}

**Proof of (2.37) in Theorem 2.2.** First, let us consider (2.37), for which the proof is identical to the above proof for Theorem 2.2. The only thing needed to be modified is the local error bound, where $\|\xi^{n,\pm}(\cdot)\|_{L^2} \lesssim \tau(h^m + \epsilon^{n-2}\tau^2)$ and $\|\nabla \xi^{n,\pm}(\cdot)\|_{L^2} \lesssim \tau(h^m + \epsilon^{n-2}\tau^2)$ (Lemma 3.4) in this case. Following the analogous proof of Theorem 2.2, one can easily prove assertion (2.37) and we omit the details here for brevity.

Now, we come to prove (2.38), using a similar idea in [4]. The proof is also similar to that of Theorem 2.2, and we just outline the main steps. Let $\psi^s := \psi^s(x,t)$ be the solution of NLS (2.2), and we write $\psi^s(t_n)$ for $\psi^s(x,t_n)$ in short. Denote the ‘error’ $\mathcal{E} \in \mathcal{Y}_M$ and $\mathcal{E}^n(x) \in \mathcal{X}_M$ ($n \geq 0$) as

\begin{equation}
\mathcal{E}^n(x) = I_M(\mathcal{E}^n)(x) = \sum_{i=1}^{M-1} (\tilde{\mathcal{E}}^n_i) \Phi_i(x), \quad n \geq 0, \quad x \in \Omega.
\end{equation}

Using triangle inequality, we have for $n \geq 0$,

\begin{equation}
\|\psi(\cdot,t_n) - \psi^n(\cdot)\|_{L^2} \leq \|\psi(\cdot,t_n) - \psi^s(\cdot,t_n)\|_{L^2} + \|\psi^s(\cdot,t_n) - P_M(\psi^s(t_n))(\cdot)\|_{L^2} + \|\mathcal{E}^n(\cdot)\|_{L^2}
\end{equation}

\begin{equation}
\lesssim \epsilon^2 + h^{m_0} + \|\mathcal{E}^n(\cdot)\|_{L^2},
\end{equation}

\begin{equation}
\|\nabla[\psi(\cdot,t_n) - \psi^n(\cdot)]\|_{L^2} \leq \|\nabla[\psi^s(\cdot,t_n) - \psi^s(\cdot,t_n)]\|_{L^2} + \|\nabla[\psi^s(\cdot,t_n) - P_M(\psi^s(t_n))(\cdot)]\|_{L^2} + \|\nabla \mathcal{E}^n(\cdot)\|_{L^2}
\end{equation}

\begin{equation}
\lesssim \epsilon^2 + h^{m_0} + \|\nabla \mathcal{E}^n(\cdot)\|_{L^2},
\end{equation}

which indicates that we only need to estimate $\|\mathcal{E}^n(\cdot)\|_{L^2}$ and $\|\nabla \mathcal{E}^n(\cdot)\|_{L^2}$.

In order to estimate the ‘error’ $\mathcal{E}^n$, we define the ‘local truncation error’ $\chi_n(x) = \sum_{i=1}^{M-1} (\tilde{\chi}_i) \Phi_i(x) \in X_M$ for $\psi^s(x,t)$ as

\begin{equation}
\begin{aligned}
(\chi^0)_l & = \alpha_l(\psi_0)_l + d_l(\hat{\psi}_1)_l + p_l(\mathcal{F}(\psi_0))_l + q_l(D(\psi^s(0)))_l - (\psi^s(\tau))_l, \\
(\chi^n)_l & = \alpha_l(\psi^s(t_{n-1}))_l + d_l(\hat{\psi}^s(t_n))_l + p_l(\mathcal{F}(\psi^s(t_n)))_l + q_l(D(\psi^s(t_n)))_l - \left[
\begin{array}{c}
\frac{\partial_l(\mathcal{F}(\psi^s(t_{n-1})))}{(\psi^s(t_{n+1}))_l} - (\psi^s(t_{n+1}))_l, \\
\frac{\partial_l(\mathcal{F}(\psi^s(t_n)))}{(\psi^s(t_{n-1}))_l} - (\psi^s(t_{n-1}))_l
\end{array}\right]
\end{aligned}
\end{equation}

Rewriting the NLS (2.2) as

\begin{equation}
i \partial_t \psi^s - \epsilon^2 \partial_{xx} \psi^s + \partial_{xx} \psi^s + (f(\psi^s)^2) \psi^s + \epsilon^2 \partial_{tt} \psi^s = 0,
\end{equation}
and recalling \( \psi^a(x, 0) = \psi_0 \) and \( \partial_t \psi^a(x, 0) = \psi_1(x) \), we can prove analogous results in the same way as Lemma 3.4. Here we present the results and omit the details.

**Lemma 4.1.** Let \( \chi^n(x) (n \geq 0) \) be defined as (4.5), \( f(\cdot) \in C^k([0, \infty)) \) \( (k \geq 3) \), under assumptions (A) and (B), we have the following decomposition of \( \chi^n(x) (n \geq 0) \) (3.12),

\[
\begin{align*}
\chi^0(x) &= e^{i\tau \beta^+} \chi^{n, +}(x) - e^{i\tau \beta^-} \chi^{n, -}(x), \\
\chi^n(x) &= e^{i\tau \beta^+} \chi^{n-1, +}(x) - e^{i\tau \beta^-} \chi^{n-1, -}(x) - e^{i\tau \beta^x} (\chi^{n-1, +}(x) - \chi^{n-1, -}(x)), \quad n \geq 1,
\end{align*}
\]

where \( \chi^{n, \pm}(x) = \sum_{l=1}^{M-1} (\chi^{n, \pm}_l)\Phi_l(x) \in X_M \) and for \( \alpha \in [0, 2) \), i.e. the ill-prepared initial data case, we have

\[
\|\chi^{n, \pm}(\cdot)\|_{L^2} \lesssim \tau h^m + \tau^3 + \tau \varepsilon^2, \quad \|\nabla \chi^{n, \pm}(\cdot)\|_{L^2} \lesssim \tau h^{m-1} + \tau^3 + \tau \varepsilon^2, \quad m = \min\{m_0, k\}, \quad n \geq 0.
\]

The decomposition in Lemma 4.1 is analogous to that in the proof of Lemma 3.4 and the lemma also holds true for \( \alpha \geq 2 \).

**Proof of (2.38) and (2.39) in Theorem 2.2.** First, for \( \mathcal{E}^0(x) \) and \( \mathcal{E}^1(x) \) we note that we can write

\[
(\mathcal{E}^0)_l = (\mathcal{E}^{0, +})_l + (\mathcal{E}^{0, -})_l, \quad (\mathcal{E}^1)_l = (\mathcal{E}^{0, +})_l e^{i\tau \beta^+} + (\mathcal{E}^{0, -})_l e^{i\beta^-} - (\chi^0)_l, \quad l \in T_M,
\]

where \( \mathcal{E}^{0, \pm}(x) = \sum_{l=1}^{M-1} (\mathcal{E}^{0, \pm}_l)\Phi_l(x) \in X_M \) are given by

\[
(\mathcal{E}^{0, +})_l = -\frac{\beta^-}{\beta^+}[\overline{(\psi_0)_l} - (\psi_0)_l] - i\beta^x[(\psi_1)_l - (\psi_1)_l], \quad (\mathcal{E}^{0, -})_l = \frac{\beta^+}{\beta^-}[\overline{(\psi_0)_l} - (\psi_0)_l] + \frac{i\beta^x}{\beta^-}[\overline{(\psi_1)_l} - (\psi_1)_l].
\]

In view of the fact that \( \frac{1}{\beta} \leq \varepsilon^2 \) and \( \psi_1^a = \psi_1 + \varepsilon^\omega \xi^2(x) \), it is easy to verify that

\[
\|\mathcal{E}^{0, \pm}(\cdot)\|_{L^2} \lesssim h^m + \varepsilon^{2+\alpha}, \quad \|\nabla \mathcal{E}^{0, \pm}(\cdot)\|_{L^2} \lesssim h^{m-1} + \varepsilon^{2+\alpha},
\]

which implies (2.38) for \( n = 0, 1 \) in view of Lemma 4.1. For time steps \( n \geq 2 \), following the same procedure of the proof for Theorem 2.1, we can get conclusion (2.38) for all \( 0 \leq n \leq M_2 \) with the help of Lemma 4.1.

Finally, it remains to prove (2.39) which enables us to simplify the nonlinearity \( \mathcal{F} \) to \( \mathcal{F}_n \). Since assertions (2.37) and (2.38) have been proven and the constants in the estimates are independent of \( \varepsilon, \tau \) and \( h \), we take the minimum of \( \varepsilon^2 \) and \( \frac{\varepsilon^2}{\delta} \) for \( 0 < \varepsilon \leq 1 \), and the following holds for \( 0 \leq n \leq M_2 \),

\[
\|\psi(\cdot, t_n) - \psi^n_\gamma(\cdot)\|_{L^2} \lesssim h^m + \tau^{4/(2-\alpha)}, \quad \|\nabla [\psi(\cdot, t_n) - \psi^n_\gamma(\cdot)]\|_{L^2} \lesssim h^{m-1} + \tau^{4/(2-\alpha)}.
\]

Hence for \( \alpha \in [0, 2) \), Sobolev inequality implies that

\[
\|\psi(\cdot, t_n) - \psi^n_\gamma(\cdot)\|_{L^\infty} \leq \sqrt{\|\psi(\cdot, t_n) - \psi^n_\gamma(\cdot)\|_{L^2} \|\nabla [\psi(\cdot, t_n) - \psi^n_\gamma(\cdot)]\|_{L^2}} \lesssim h^{m-1} + \tau,
\]

which justifies \( \max_{x \in T_M} |\psi(x, t_n) - \psi^n_\gamma(\cdot)| \leq 1 \) for sufficient small \( \tau \) and \( h \). Hence (2.39) is proven. The proof of Theorem 2.2 is complete. \( \square \)
Remark 4.1. Let us make a final remark that the above proof and the main results (Theorem 2.1 and 2.2) are valid for 2D and 3D cases. The key point for extension to 2D and 3D is the discrete Sobolev inequality in higher dimensions as [28]

\begin{align}
\|\psi_h\|_{\infty} \leq C |\ln h| \|\psi_h\|_{H^1}, \quad \|\phi_h\|_{\infty} \leq Ch^{-1/2} \|\phi_h\|_{H^1},
\end{align}

where \(\psi_h\) and \(\phi_h\) are 2D and 3D mesh functions with zero at the boundary, respectively, and the discrete semi-\(H^1\) norm \(\| \cdot \|_{H^1}\) and \(l^\infty\) norm \(\| \cdot \|_{\infty}\) can be defined similarly as the 1D version (2.34). Thus, by requiring the time step \(\tau\) satisfies the additional condition \(\tau \lesssim h\), with the discrete Sobolev inequality and the uniform bounds for the semi-\(H^1\) norm at \(h^{m-1} + \tau\), using \(m \geq 2\), we can control the \(l^\infty\) bound of the numerical solution, which guarantees the correctness of the cutoff (3.19). The readers can refer to [4] for more discussion.

5. Numerical results. In this section, we report the numerical results of our scheme EWI-SP (2.28)-(2.29) to confirm our theoretical analysis. The nonlinearity is taken as \(f(|z|^2) = -|z|^2\).

| \(\alpha = 0\) | \(h = 2\) | \(h = 1\) | \(h = 1/2\) | \(h = 1/4\) | \(\alpha = 2\) | \(h = 2\) | \(h = 1\) | \(h = 1/2\) | \(h = 1/4\) |
|---|---|---|---|---|---|---|---|---|---|
| \(\varepsilon = 1/2\) | 1.03E00 | 9.59E-2 | 6.76E-4 | 4.15E-8 | 9.45E-1 | 8.55E-2 | 6.39E-4 | 3.90E-8 |
| \(\varepsilon = 1/2^2\) | 8.45E-1 | 6.85E-2 | 2.36E-4 | 2.47E-9 | 8.45E-1 | 6.46E-2 | 2.45E-4 | 2.43E-9 |
| \(\varepsilon = 1/2^4\) | 8.62E-1 | 6.71E-2 | 1.37E-4 | 5.44E-11 | 8.62E-1 | 6.72E-2 | 1.40E-4 | 6.99E-11 |
| \(\varepsilon = 1/2^8\) | 8.62E-1 | 6.73E-2 | 1.36E-4 | 5.06E-11 | 8.62E-1 | 6.73E-2 | 1.36E-4 | 5.06E-11 |

Table 5.1 Spatial error analysis for EWI-SP (2.28)-(2.29), with different \(\varepsilon\) for Case I \((\alpha = 2)\) and Case II \((\alpha = 0)\), for \(\|e^n(x)\|_{H^1}\).

For the numerical experiments, the initial value is chosen as \(\psi_0(x) = \pi^{-1/4} e^{-x^2/2}\) and \(\omega^\varepsilon(x) = e^{-x^2/2}\) in (2.1). The computational domain is chosen as \([a, b] = [-16, 16]\). The ‘exact’ solution is computed using the proposed scheme with very fine mesh \(h = 1/128\) and time step \(\tau = 10^{-6}\). We study the following two cases of initial data:  
Case I. \(\alpha = 2\), i.e., the well-prepared initial data case. 
Case II. \(\alpha = 0\), i.e., the ill-prepared initial data case.

The errors are defined as \(e^n \in Y_M\) and \(e^n(x) \in X_M\) with \(e^n_j = \psi(x_j, t_n) - \psi^n_j\) and \(e^n(x) = \psi(t_n) - I_M(\psi^n(x))\). We measure the \(H^1\) norm of \(e^n(x)\), i.e. \(\|e^n(\cdot)\|_{H^1} = \|e^n(\cdot)\|_{L^2} + \|\nabla e^n(\cdot)\|_{L^2}\).

The errors are displayed at \(t = 1\). For spatial error analysis, we choose time step \(\tau = 10^{-6}\), such that the error in time discretization can be neglected (cf. Tab. 5.1). For temporal error analysis, we choose \(h = 1/32\) such that the spatial error can be ignored.

Tab. 5.1 depicts the spatial errors for both Case I and Case II, which clearly demonstrates that EWI-SP is uniformly spectral accurate in \(h\) for all \(\varepsilon \in (0, 1]\). Tabs. 5.2 and 5.3 present the temporal errors for Case I and II, respectively. From Tab. 5.2, we can conclude that the temporal error of EWI-SP is of second order uniformly in \(\varepsilon \in (0, 1]\), for \(\alpha = 2\). From Tab. 5.3 with \(\alpha = 0\), when time step \(\tau\) is small (upper triangle part of the table), second order convergence of the temporal error is clear; when \(\varepsilon\) is small (lower triangle part of the table), second order convergence of the temporal error is also
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\[ \alpha = 2 \quad \tau = 0.2 \quad \tau = 0.2 \quad \tau = 0.2 \quad \tau = 0.2 \quad \tau = 0.2 \quad \tau = 0.2 \]

\[ \varepsilon = 1/2 \quad 4.63E-2 \quad 2.97E-3 \quad 1.17E-5 \quad 7.34E-7 \quad 4.59E-8 \quad 2.87E-9 \quad 1.87E-10 \]

rate — 1.98 1.99 2.00 2.00 2.00 2.00 1.97

\[ \varepsilon = 1/2^2 \quad 4.22E-2 \quad 4.52E-3 \quad 2.83E-4 \quad 1.77E-5 \quad 1.11E-6 \quad 6.91E-8 \quad 4.32E-9 \quad 2.77E-10 \]

rate — 1.61 2.00 2.00 2.00 2.00 2.00 1.98

\[ \varepsilon = 1/2^3 \quad 5.01E-2 \quad 3.99E-3 \quad 3.76E-4 \quad 2.37E-5 \quad 1.48E-6 \quad 9.27E-8 \quad 5.78E-9 \quad 3.53E-10 \]

rate — 1.83 1.70 2.00 2.00 2.00 2.00 2.02

\[ \varepsilon = 1/2^4 \quad 5.50E-2 \quad 3.73E-3 \quad 3.09E-4 \quad 2.45E-5 \quad 1.53E-6 \quad 9.61E-8 \quad 6.01E-9 \quad 3.74E-10 \]

rate — 1.94 1.80 1.83 2.00 2.00 2.00 2.00

\[ \varepsilon = 1/2^5 \quad 5.65E-2 \quad 3.85E-3 \quad 2.43E-4 \quad 1.95E-5 \quad 1.61E-6 \quad 1.02E-7 \quad 6.38E-9 \quad 4.04E-10 \]

rate — 1.94 1.99 1.82 1.80 1.99 2.00 1.99

\[ \varepsilon = 1/2^6 \quad 5.69E-2 \quad 3.88E-3 \quad 2.45E-4 \quad 1.54E-5 \quad 1.25E-6 \quad 1.00E-7 \quad 6.30E-9 \quad 3.82E-10 \]

rate — 1.94 1.99 1.82 1.80 1.99 2.00 1.99

\[ \varepsilon = 1/2^7 \quad 5.70E-2 \quad 3.89E-3 \quad 2.46E-4 \quad 1.54E-5 \quad 9.62E-7 \quad 6.01E-8 \quad 3.76E-9 \quad 2.48E-10 \]

rate — 1.94 1.99 1.82 1.80 1.99 2.00 1.99

| \varepsilon = 1/2^8 | 5.70E-2 | 3.89E-3 | 2.46E-4 | 1.54E-5 | 9.62E-7 | 6.01E-8 | 3.76E-9 | 2.46E-10 |
|---------------------|--------|--------|--------|--------|--------|--------|--------|--------|
| rate                | 1.94   | 1.99   | 2.00   | 2.00   | 2.00   | 2.00   | 2.00   | 1.97   |

Table 5.2

Temporal error analysis for EWI-SP, with different \( \varepsilon \) for Case I \((\alpha = 2)\), with \( \|e^n(\cdot, \tau)\|_{H^1} \). The convergence rate is calculated as \( \log_2(\|e^n(\cdot, 4\tau)\|_{H^1}/\|e^n(\cdot, \tau)\|_{H^1})/2 \).
Estimating each term on the RHS above, noticing the assumption which implies
\[ |\| (\| H \| = 0 \| e_\alpha = 0) \| = 0 \| e_\alpha = 0 \| \cdot \| e_\alpha = 0 \| \cdot \| e_\alpha = 0 \|^2 \]
and the fact about the coefficients $|p_i| \leq \tau$, $|q_i| \leq \tau^2$ (Lemma 3.4), we can find

\[ \sum_{i=1}^{M-1} |W_i^{n,\pm}|^2 \lesssim \tau^2 \left[ \sum_{i=1}^{M-1} \left( |F(\psi(t_n))| - |F(\psi^n)| \right)^2 + \tau^2 \sum_{i=1}^{M-1} |\delta_i (F(\psi(t_n))) - \delta_i (F(\psi^n))|^2 \right]. \]

Estimating each term on the RHS above, noticing the assumption which implies $F(\cdot)$ is global Lipschitz,
we get
\[
\frac{b-a}{2} \sum_{l=1}^{M-1} \left( |\mathcal{F}(\hat{w}(t_n))|_t - |\mathcal{F}(\hat{w}(t_n))|_t \right)^2 = \| I_M(\mathcal{F}(\hat{w}(t_n)))-I_M(\mathcal{F}(\hat{w}(t_n))) \|^2_{L^2}
\]
\[
= h \sum_{j=1}^{M-1} |\mathcal{F}(w_j, t_n) - \mathcal{F}(\hat{w}_n)|^2 \leq C_F h \sum_{j=1}^{M-1} |\hat{w}_j - \hat{w}_n|^2 = C_F \| I_M(\mathcal{F}(\hat{w}(t_n)))-I_M(\mathcal{F}(\hat{w}(t_n))) \|^2_{L^2}
\]
\[
\leq 2C_F \left( \| I_M(\mathcal{F}(\hat{w}(t_n)))-P_M(\mathcal{F}(\hat{w}(t_n))) \|^2_{L^2} + \| P_M(\mathcal{F}(\hat{w}(t_n)))-I_M(\mathcal{F}(\hat{w}(t_n))) \|^2_{L^2} \right) \lesssim \| e^n(\cdot) \|^2_{L^2} + h^{2m_0},
\]
where \(C_F\) only depends on \(f(\cdot)\) and \(M_1\). Similarly, making use of the properties of \(\mathcal{F}\), we have
\[
\frac{b-a}{2} \sum_{l=1}^{M-1} \tau^2 |\delta^-_t(\mathcal{F}(\hat{w}(t_n))|_t - \delta^-_t(\mathcal{F}(\hat{w}(t_n))|_t \right)^2 = h \tau^2 \sum_{j=1}^{M-1} |\delta^-_t(\mathcal{F}(w_j, t_n)) - \delta^-_t(\mathcal{F}(\hat{w}_n))|^2
\]
\[
\leq C_F h \left( \sum_{j=1}^{M-1} |\psi_j - \psi_n|^2 + \sum_{j=1}^{M-1} |\psi_j - \psi_{n-1}|^2 \right) \leq C_F h \sum_{k=n-1}^{n} \sum_{j=1}^{M-1} |\psi_j - \psi_{n-1}|^2
\]
\[
= C_F \sum_{k=n-1}^{n} \left( \| I_M(\psi(k)) - I_M(\psi^{k}(\cdot)) \|^2_{L^2} \lesssim \| e^n(\cdot) \|^2_{L^2} + \| e^{n-1}(\cdot) \|^2_{L^2} + h^{2m_0},
\]
where \(C_F\) only depends on \(f(\cdot)\) and \(M_1\). Combining all the above results together, we get the first claim in the conclusion (3.31). Similarly, using Lemma 3.2, we can get
\[
\sum_{l=1}^{M-1} |\mu| \left| \mathcal{W}^l_{\psi} \right|^2 \lesssim \left[ \left\| \nabla [I_M (\mathcal{F}(\hat{w}(t_n))) - \mathcal{F}(\hat{w}(t_n))] \right\|^2_{L^2} + \tau^2 \| \nabla [I_M (\delta^-_t(\mathcal{F}(\psi(t_n)) - \delta^-_t(\mathcal{F}(\psi^n)))]) \|^2_{L^2} \right].
\]
In view of Lemma 3.2, the semi-\(H^1\) norms on the RHS are equivalent to the discrete semi-\(H^1\) norm of the corresponding grid functions, and we can estimate the RHS by estimating the corresponding discrete semi-\(H^1\) norms, which has been essentially done in our recent work [4]. For example, with the assumptions made in the claim (3.31), we have
\[
\delta^+_\psi \left( \mathcal{F}(w_j, t_n) - \mathcal{F}(\psi_j) \right)
\]
\[
= \int_0^1 (G(\omega(t_n))\delta^+_\psi w_j, t_n) + H(\omega(t_n)) \delta^+_\psi w_j, t_n) d\theta - \int_0^1 (G(\omega(t_n))\delta^+_\psi \psi_j, t_n) d\theta
\]
\[
= \int_0^1 \left[ (G(\omega(t_n)) - G(\omega(t_n))) \delta^+_\psi w_j, t_n) + (H(\omega(t_n)) - H(\omega(t_n))) \delta^+_\psi \psi_j, t_n) \right] d\theta
\]
\[
+ \int_0^1 \left[ G(\omega(t_n)) \delta^+_\psi w_j, t_n) - \delta^+_\psi \psi_j, t_n) \right] d\theta, \quad j = 0, 1, \ldots, M - 1,
\]
where \(\omega(t_n) = \theta \psi(x_j+1, t_n) + (1 - \theta) \psi(x_j, t_n)\) and \(\delta^+_\psi = \delta^+_\psi \psi_j, t_n)\) for \(\theta \in [0, 1]\). Using the global Lipschitz properties of \(G(\cdot)\) and \(H(\cdot)\) in the current case, then it is a direct consequence that [4]
\[
|\delta^+_\psi \left( \mathcal{F}(w_j, t_n) - \mathcal{F}(\psi_j) \right) | \lesssim \| \delta^+_\psi (\psi_j - \psi_j) \|^2 + \| \psi(x_j, t_n) - \psi_j \|, \quad 0 \leq j \leq M - 1,
\]
which implies
\begin{equation}
\|\delta_n^x (F(\psi(x_j, t_n)) - F(\psi^n))\|_{L^2}^2 \lesssim \|\delta_n^x (\psi(x_j, t_n) - \psi^n)\|_{L^2}^2 + \|\psi(x_j, t_n) - \psi^n\|_{L^2}^2.
\end{equation}

Combining (A.2) together with Lemma 3.2, we have
\begin{align*}
\|\nabla[I_M (F(\psi(t_n)) - F(\psi^n))]\|_{L^2}^2 & \lesssim \|\nabla[I_M (\psi(t_n) - \psi^n) (\cdot)]\|_{L^2}^2 + \|I_M (\psi(t_n) - \psi^n) (\cdot)\|_{L^2}^2 \\lesssim \|\nabla e^n (\cdot)\|_{L^2}^2 + \|e^n (\cdot)\|_{L^2}^2 + h^{2m_0 - 2}.
\end{align*}

The remaining term can be estimated in the same way and we omit the details here for brevity. Finally, we can obtain
\begin{align}
\frac{b - a}{2} \sum_{l=1}^{M-1} |\mu_l|^2 |\tilde{W}_{l-1}^n| \lesssim \tau^2 \sum_{k=n-1}^{n} \left( \|\nabla e^k (\cdot)\|_{L^2}^2 + \|e^k (\cdot)\|_{L^2}^2 + \right) + \tau^2 h^{2m_0 - 2}.
\end{align}

It is obvious that the constant in the inequality only depends on \(f (\cdot), M_1\) and \(\|\psi\|_{L^\infty(0,T; H^{m_0})}\).

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