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Lattice Boltzmann method simulation of thermal flow dynamics in a channel

Abstract. The objective of this paper is the simulation of thermal flow dynamics in a channel. The mathematical model in a two-dimensional formulation is described by Navier-Stokes equations, continuity and temperature equations. For the numerical simulation of the problem the Lattice Boltzmann method applying the D2Q9 model is used. The validity of this method is tested by comparing the numerical solution to the analytical solution of the planar channel flow and error rates are calculated for various sizes of the computational grid. The test problem of thermal Poiseuille flow in the channel was solved to deactivate the correctness of the developed algorithm. Very good agreement between the exact and numerical solution of this problem is shown.

Key words: The lattice Boltzmann method, thermal flow dynamics, Poiseuille flow.

Introduction

Thermal flows play an important role in the flow dynamics. Recently, there has been an effort to increase the capability of the lattice Boltzmann method in order to solve for fluid flows including heat transfer [1, 2]. A detailed analysis can be found in [3].

Generally, the thermal lattice Boltzmann model (TLBE) can be divided into several categories [4]. The first is the multispeed scheme, the second is the double distribution function (DDF) scheme and the last is the hybrid thermal lattice Boltzmann equation (HTLBE) scheme [3]. The multi-speed scheme is a plain extension of the Boltzmann isothermal models with a lattice, in which only the velocity distribution function is affected. In double distribution function scheme, different distribution functions are used, one for the velocity field and the other for the temperature field or internal energy. The main advantage of the DDF scheme compared to the multi-speed scheme is to increase the numerical stability, and therefore it is widely used. The hybrid computational scheme combines the LBE and Finite difference (FD) or Finite volume (FV) methods [5]. In this paper we use DDF scheme.

The goal of this paper is the numerical implementation of thermal flow dynamics in a channel in a two-dimensional case. With the help of LBE method the profiles of velocities and temperature at different values of parameters in the system of differential equations and at different time instants are investigated.

Statement of the problem

In this paper we considered 2-D thermal flow in planar channel. The flow driven by a body force. We set cold temperature at the bottom wall and hot temperature at the top wall of the channel (Figure 1).

Figure 1 – The considered area
The governing equations can be written as [6]:

$$\frac{\partial u}{\partial t} + \frac{\partial}{\partial x_j} (u_j u_j) = -\frac{1}{\rho} \frac{\partial p}{\partial x_j} + \nu \frac{\partial^2 u}{\partial x_j \partial x_j} + F_j,$$

$$\frac{\partial \rho}{\partial t} = 0,$$

$$\frac{\partial T}{\partial t} + \frac{\partial}{\partial x_j} (u_j T) = k \frac{\partial^2 T}{\partial x_j \partial x_j}.$$

Here, $\rho$ is the linear function of the temperature $T$ and $F_x$ is the body force

$$\rho = \rho_0 - \rho_0 \beta (T - T_0),$$

$$F_x = 8 \rho_0 \nu u_{\text{max}} / H^2,$$

where $\rho_0$ is the average density, $T_0$ is the average temperature, $\beta$ is the coefficient of thermal expansion.

We assume that at the initial time, the velocity and temperature in the channel are zero. Periodic boundary conditions are used at the channel inlet and outlet for $u_1, u_2, T, p$. And the following boundary conditions are applied on channel walls

$$u_i(x_1, x_2 = 0, t) = u_i(x_1, x_2 = H, t) = u_i(x_1, x_2 = 0, t) = u_i(x_1, x_2 = H, t) = 0,$$

$$T(x_1, x_2 = 0, t) = T_{\text{cold}},$$

$$T(x_1, x_2 = H, t) = T_{\text{hot}}.$$

**Numerical method**

The lattice Boltzmann equation (LBE) method is a discrete model of a continuous medium. Currently, the LBE method may well compete with traditional methods of computational hydrodynamics, and in some areas (flows in a porous medium, multiphase and multicomponent flows) it has significant advantages [7-9]. By this method an intermediate scale model is used to simulate fluid flow. It applies simulation of the motion of fluid particles in order to capture the macroscopic parameters of the fluid. The area is discretized by uniform cartesian cells. Each cell contains a fixed number of distribution functions, which represent the number of fluid particles moving in these discrete directions. Depending on the dimension and the number of directions of velocity, there are various models that can be used. In the present study, a two-dimensional flow and a two-dimensional square lattice with nine discrete velocities (D2Q9 model) are examined. For each velocity vector, the value of the distribution function is stored. In the D2Q9 model (Figure 2), the velocities are calculated using the formulas

$$e_0 = (0, 0), \quad e_1 = (1, 0), \quad e_2 = (0, 1),$$

$$e_3 = (-1, 0), \quad e_4 = (0, -1),$$

$$e_5 = (1, 1), \quad e_6 = (-1, 1),$$

$$e_7 = (-1, -1), \quad e_8 = (1, -1),$$

where $c = \Delta x / \Delta t$ and $k$ – lattice velocity direction.

![Figure 2 – D2Q9-model](image)

Distribution functions are calculated by solving the lattice Boltzmann equation, which is a special discretization of the Boltzmann kinetic equation. After introducing the Bhatnagar – Gross – Crook approximation, we can formulate the Boltzmann equation in the form [10]

$$f_i(x + e_i \Delta t, t + \Delta t) = f_i(x, t) + \frac{\Delta t}{\tau} \left[ f_i^{\text{eq}}(x, t) - f_i(x, t) \right]$$

where $\Delta t$ denotes the lattice time step, $e_i$ is the discrete lattice velocity in the direction $i$, $\tau$ denotes the lattice relaxation time, $f_i^{\text{eq}}$ is the equilibrium distribution function. The equilibrium distribution functions are calculated by the formula

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where the values of the weight coefficients $\omega_i$ are as follows:

$$\omega_i = \begin{cases} 4/9, & i = 0, \\ 1/9, & i = 1, 2, 3, 4, \\ 1/36, & i = 5, 6, 7, 8, \\ \end{cases}$$

and $c_s = c / \sqrt{3}$ is the lattice speed of sound.

The macroscopic variables for the density and velocity of a fluid are calculated as the first two moments of the distribution functions for each cell:

$$\rho = \sum_{i=0}^{8} f_i \omega_i, \quad \bar{u} = \frac{1}{\rho} \sum_{i=1}^{8} f_i e_i.$$

For the temperature field, the distribution $g$ is

$$g_i(x + e_i \Delta t, t + \Delta t) = g_i(x, t) + \frac{\Delta t}{\tau_e} [g_i^{eq}(x, t) - g_i(x, t)].$$

The equilibrium distribution functions for the temperature field are determined by the formulas:

$$g_i^{eq} = \omega_i T \left[ 1 + \frac{e_i \cdot \bar{u}}{c_s^2} + \frac{1}{2} \left( \frac{e_i \cdot \bar{u}}{c_s^2} \right)^2 - \frac{1}{2} \frac{c_s^2}{u^2} \right]$$

The temperature field is calculated by the formula

$$T = \sum_{i=0}^{8} g_i.$$
\[
\frac{\Delta p}{x_{\text{out}} - x_{\text{in}}} = \frac{8\eta u_{\text{max}}}{(y_{\text{top}} - y_{\text{bot}})^2},
\]

where \(\Delta p\) is the pressure difference, \(\Delta p = p_{\text{out}} - p_{\text{in}}\). \(p_{\text{out}}\) and \(p_{\text{in}}\) are the pressure at the outlet and at the inlet of the channel, respectively, \(\eta\) is the dynamic viscosity, \(x_{\text{out}}\) and \(x_{\text{in}}\) are the outlet and the inlet boundaries, respectively, \(y_{\text{top}}\) and \(y_{\text{bot}}\) are the top and the bottom walls boundaries, respectively.

**Table 1 – Simulation parameters**

| Parameters | Value |
|------------|-------|
| scaling factor, scale | scale = 1:2 |
| number of points along the x axis, \(N_x\) | \(N_x = 100\cdot\text{scale}\) |
| number of points along the y axis, \(N_y\) | \(N_y = 50\cdot\text{scale}\) |
| relaxation parameter, \(\tau\) | \(\tau = \sqrt{3}/16 + 0.5\) |
| maximum velocity in a channel, \(u_{\text{max}}\) | \(u_{\text{max}} = 0.1/\text{scale}\) |
| kinematic viscosity, \(\nu\) | \(\nu = (2\tau - 1)/6\) |
| Reynolds number, \(Re\) | \(Re = 10\) |
| Prandtl number, \(Pr\) | \(Pr = 0.7\) |
| channel outlet pressure, \(p_{\text{out}}\) | \(p_{\text{out}} = 1\) |

The comparison of the exact solution with the results of the numerical solution is observed in Figures 3–5.

\(L_1\) and \(L_2\) norms of error were calculated by the following formulas:

\[
\varepsilon_{L_1}(t) = \frac{\sum|q_n(x_1, x_2, t) - q_b(x_1, x_2, t)|}{\sum|q_b(x_1, x_2, t)|},
\]

\[
\varepsilon_{L_2}(t) = \sqrt{\frac{\sum|q_n(x_1, x_2, t) - q_b(x_1, x_2, t)|^2}{\sum|q_b(x_1, x_2, t)|^2}}.
\]

where the index \(n\) means numerical solution and the index \(b\) means analytical solution.

Increasing the grid resolution helps to reduce the error norms. If we assume that the error norm is known for different grid sizes and their ratio of the sizes of each grid to the initial one is \(m\), then we can determine the order of accuracy using the following formula:

\[
n(t) = \log_m \left( \frac{\varepsilon(t)}{\varepsilon_m(t)} \right).
\]

In the test problem, the error norms were calculated at time \(t \cdot \nu / L^2 = 1\). The accuracy orders of the numerical algorithm depending on the grid size are presented in table 2.

Figure 3 shows the predicted cross-sectional profile in the force-driven channel flow for velocity and comparison between LBM simulation and analytical solution. Solid line is the analytical solution and the symbol is the numerical result.

**Table 2 – The accuracy orders of \(L_1\) and \(L_2\) of the velocity, depending on the grid size at \(t \cdot \nu / L^2 = 1\)**

| Grid size | \(u(L_1)\) | Order of accuracy, \(n\) | \(u(L_2)\) | Order of accuracy, \(n\) |
|-----------|-------------|-----------------|-------------|-----------------|
| 100 x 50  | 4.6600 x 10^-4 | 3.8978 | 6.8264 x 10^-4 | 1.9489 |
| 200 x 100 | 1.6972 x 10^-4 | 3.8175 | 4.1198 x 10^-4 | 1.9087 |
Also, Figure 4 shows the temperature cross-sectional variation at different time instants in comparison with the analytic solution. Solid lines are the numerical results and the symbol is the analytical solution. And Figure 5 demonstrates the temperature cross-sectional profiles in comparison with the analytic solution for different Prandtl numbers. Here, solid lines are the analytical solutions and the symbols are the numerical results. As can be seen from the figures, the numerical results agree well with the analytical solutions. The general results in terms of streamwise temperature and velocity for time instants $t = 0.1$ and $t = 1$ are shown in Figures 6 and 7, respectively.

**Figure 3** – Velocity profile of a 2D Poiseuille flow. Comparison of the exact solution with the result of the numerical solution at $T_{\text{top}} = 1, T_{\text{bot}} = 0, \text{Pr} = 0.7, u_{\text{max}} = 0.1$.

**Figure 4** – Temperature variation of a 2D Poiseuille flow. Comparison of the exact solution with the result of the numerical solution at $T_{\text{top}} = 1, T_{\text{bot}} = 0, \text{Pr} = 0.7, u_{\text{max}} = 0.1$. 

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**Figure 5** – Temperature profiles of a 2D Poiseuille flow. Comparison of the exact solution with the result of the numerical solution at $T_{\text{top}} = 1$, $T_{\text{bot}} = 1$, $Pr = 0.7$ and $Pr = 1.5$, $\alpha_{\text{ext}} = 0.1$

**Figure 6** – Streamwise temperature at $Pr = 0.7$, $Re = 10$ and computational time $t = 0.1$ (a) and $t = 1$ (b)

**Figure 7** – Streamwise velocity at $Pr = 0.7$, $Re = 10$ and computational time $t = 0.1$ (a) and $t = 1$ (b)


**Conclusion**

The basic aim of this paper is the development of mathematical model for thermal flow in a channel and the implementation of numerical simulation of the problem by the Lattice Boltzmann method applying the D2Q9 model. The validity of this method is tested by comparing the numerical solution to the analytical solution of the planar channel flow. The comparison of the exact solution with the numerical solution for test problem of thermal Poiseuille flow given in Figures 3–5 shows a very good agreement and relationship. It is determined that the numerical method has a second order of accuracy in time. This means that the developed algorithm may well be applied to solving the problem of the dynamic thermal flow in a three-dimensional region. This result will be obtained and shown in a future research.

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