Abstract

Monadically stable and monadically NIP classes of structures were initially studied in the context of model theory and defined in logical terms. They have recently attracted attention in the area of structural graph theory, as they generalize notions such as nowhere denseness, bounded cliquewidth, and bounded twinwidth.

Our main result is the – to the best of our knowledge first – purely combinatorial characterization of monadically stable classes of graphs, in terms of a property dubbed \textit{flip-flatness}. A class \(\mathcal{C}\) of graphs is flip-flat if for every fixed radius \(r\), every sufficiently large set of vertices of a graph \(G \in \mathcal{C}\) contains a large subset of vertices with mutual distance larger than \(r\), where the distance is measured in some graph \(G'\) that can be obtained from \(G\) by performing a bounded number of flips that swap edges and non-edges within a subset of vertices. Flip-flatness generalizes the notion of uniform quasi-wideness, which characterizes nowhere dense classes and had a key impact on the combinatorial and algorithmic treatment of nowhere dense classes. To obtain this result, we develop tools that also apply to the more general monadically NIP classes, based on the notion of indiscernible sequences from model theory. We show that in monadically stable and monadically NIP classes indiscernible sequences impose a strong combinatorial structure on their definable neighborhoods. All our proofs are constructive and yield efficient algorithms.

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1 Introduction

An important open problem in structural and algorithmic graph theory is to characterize those hereditary graph classes for which the model checking problem for first-order logic is tractable\(^1\) [23, Section 8.2]. A result of Grohe, Kreutzer, and Siebertz [24] states that for monotone graph classes (that is, classes closed under removing vertices and edges), the limit of tractability is precisely captured by the notion of nowhere denseness, introduced by Nešetřil and Ossona de Mendez [29]. Examples of nowhere dense classes include the class of planar graphs, all classes that exclude a fixed minor, and classes with bounded expansion. Whereas these classes are sparse (for instance, they exclude some fixed biclique as a subgraph), the aforementioned problem seeks to generalize the result of Grohe, Kreutzer, and Siebertz to classes that are not necessarily sparse. Indeed, there are known hereditary graph classes that are not sparse, and for which the model checking problem is tractable, such as transductions of classes of bounded local cliquewidth [5], transductions of nowhere dense classes [16], or classes of ordered graphs (that is, graphs equipped with a total order) of bounded twinwidth [6].

So far, a complete picture is understood in two contexts: for monotone graph classes, where tractability coincides with nowhere denseness, and for hereditary classes of ordered graphs, where tractability coincides with bounded twinwidth. Despite the apparent dissimilarity of the combinatorial definitions of nowhere denseness and bounded twinwidth, those notions can be alternatively characterized in a uniform way in logical terms by the following notion, originating in model theory. Unless mentioned otherwise, all formulas are first-order formulas.

Say that a class \(\mathcal{C}\) of graphs **transduces** a class \(\mathcal{D}\) of graphs if for every \(H \in \mathcal{D}\) there is some \(G \in \mathcal{C}\) from which \(H\) can be obtained by performing the following steps: (1) coloring the vertices of \(G\) arbitrarily (2) interpreting a fixed formula \(\varphi(x, y)\) (involving the edge relation and unary relations for the colors), thus yielding a new graph \(\varphi(G)\) with the same vertices as \(G\) and edges \(uv\) such that \(\varphi(u, v)\) holds, and finally (3) taking an induced subgraph of \(\varphi(G)\). The transducability relation on graph classes is transitive, and classes that do not transduce the class of all graphs are called **monadically NIP**. For instance, the class of all bipartite graphs transduces the class of all graphs: to obtain an arbitrary graph \(G\), consider its 1-subdivision, obtained by placing one vertex on each edge of \(G\), thus yielding a bipartite graph \(H\); then the formula \(\varphi(x, y)\) expressing that \(x\) and \(y\) have a common neighbor defines a graph on \(V(H)\) containing \(G\) as an induced subgraph. Hence, the class of bipartite graphs is not monadically NIP. On the other hand, all the graph classes mentioned earlier – nowhere dense classes and transductions thereof, classes of bounded twinwidth, or transductions of classes with bounded local cliquewidth – are monadically NIP. This suggests that monadic NIP might constitute the limit of tractability of the model checking problem. More precisely, the following has been conjectured\(^2\).

**Conjecture 1** ([1]). Let \(\mathcal{C}\) be a hereditary class of graphs. Then the model checking problem for first-order logic is fixed parameter tractable on \(\mathcal{C}\) if and only if \(\mathcal{C}\) is monadically NIP.

Quite remarkably, among monotone graph classes, classes that are monadically NIP correspond precisely to nowhere dense classes [2], and among hereditary graph classes of ordered graphs, classes that are monadically NIP correspond precisely to classes of bounded

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1 more precisely, **fixed parameter-tractable**, that is, solvable in time \(f(|\varphi|) \cdot |G|^c\), where \(\varphi\) is the input formula and \(G\) is the input graph, for some function \(f : \mathbb{N} \to \mathbb{N}\) and constant \(c\).

2 To the best of our knowledge the conjecture was first explicitly discussed during the open problem session of the Algorithms, Logic and Structure Workshop in Warwick, in 2016, see [1].
twinwidth [6]. One may tweak the definition of monadic NIP classes by considering other logics than first-order logic. For instance, for the counting extension \( \text{CMSO}_2 \) of monadic second-order logic, one recovers precisely the notion of classes of bounded cliquewidth [9], or classes of bounded treewidth if only monotone classes are considered. Thus, variations on the definition of monadic NIP recover important notions from graph theory: nowhere denseness, bounded twinwidth, bounded treewidth, and bounded cliquewidth.

Note that both implications in Conjecture 1 remain open. The conjecture is so far confirmed for monotone graph classes [24] (where monadically NIP classes are exactly the nowhere dense classes) and for hereditary classes of ordered graphs [6], tournaments [22], interval graphs and permutation graphs [7], (where monadically NIP classes are exactly the classes of bounded twinwidth). As a special important case, the conjecture predicts that all monadically stable graph classes are tractable. A class \( \mathcal{C} \) is monadically stable if it does not transduce the class of all half-graphs, that is, graphs with vertices \( a_1, b_1, \ldots, a_n, b_n \) such that \( a_i \) is adjacent to \( b_j \) if and only if \( i \leq j \). Although much more restrictive than monadically NIP classes, monadically stable classes include all nowhere dense classes [2], and hence also all classes \( \mathcal{D} \) that transduce in a nowhere dense class \( \mathcal{C} \) (called structurally nowhere dense classes [19]). Those include dense graph classes, such as for instance squares of planar graphs. In fact, it is conjectured [30] that every monadically stable class of graphs is structurally nowhere dense.

These outlined connections between structural graph theory and model theory have recently triggered the interest to generalize combinatorial and algorithmic results from nowhere dense classes to structurally nowhere dense, monadically stable and monadically NIP classes, and ultimately to efficiently solve the model checking problem for first-order logic on these classes [5, 6, 19, 13, 21, 27, 30, 31, 32]. Logical results on monadically stable and monadically NIP classes in model theory include [3, 34, 8, 4].

Contribution

As discussed above, many central graph classes such as those with bounded cliquewidth, twinwidth or nowhere dense classes can be characterized both from a structural (i.e., graph theoretic) and a logical perspective. While monadically stable and monadically NIP graph classes are naturally defined via logic, structural characterizations have so far been elusive. In this work we take a step towards a structure theory for monadically stable and monadically NIP classes of graphs, which is the basis for their future algorithmic and combinatorial treatment, in particular, a tool for approaching Conjecture 1, as we discuss later.

Flatness.

Our main result, Theorem 3, provides a purely combinatorial characterization of monadically stable graph classes in terms of flip-flatness. Flip-flatness generalizes uniform quasi-wideness\(^3\), introduced by Dawar in [10] in his study of homomorphism preservation properties. Uniform quasi-wideness was proved by Nešetřil and Ossona de Mendez [29] to characterize nowhere dense graph classes and is a key tool in the combinatorial and algorithmic treatment of these classes. To foster the further discussion, let us formally define this notion.

\(^3\) Another reasonable name for flip-flatness would be flip-wideness. We avoided this name to prevent confusion with the recently introduced graph parameter flip-width [37], which is studied in the same context.
A set of vertices is \textit{distance-}r \textit{independent} in a graph if any two vertices in the set are at distance greater than \( r \). A class of graphs \( \mathcal{C} \) is \textit{uniformly quasi-wide} if for every \( r \in \mathbb{N} \) there exists a function \( N_r : \mathbb{N} \rightarrow \mathbb{N} \) and a constant \( s \in \mathbb{N} \) with the following property. For all \( m \in \mathbb{N} \), \( G \in \mathcal{C} \), and \( A \subseteq V(G) \) with \( |A| \geq N_r(m) \), there exists \( S \subseteq V(G) \) with \( |S| \leq s \) and \( B \subseteq A \setminus S \) with \( |B| \geq m \) such that \( B \) is distance-\( r \) independent in \( G - S \) (see the top of Figure 1). Intuitively, for uniformly quasi-wide classes, in sufficiently large sets one can find large subsets that are distance-\( r \) independent after the deletion of a constant number of vertices. Uniform quasi-wideness is only suitable for the treatment of sparse graphs. Already very simple dense graph classes, such as the class of all cliques, are not uniformly quasi-wide.

Inspired by the notion of uniform quasi-wideness, Jakub Gajarský and Stephan Kreutzer proposed the new notion of \textit{flip-flatness}. Roughly speaking, flip-flatness generalizes uniform quasi-wideness by replacing in its definition the deletion of a bounded size set of vertices by the inversion of the edge relation between a bounded number of (arbitrarily large) vertex sets. Let us make this definition more precise. A \textit{flip} in a graph \( G \) is specified by a pair of sets \( F = (A, B) \) with \( A, B \subseteq V(G) \). We write \( G \oplus F \) for the graph with the same vertices as \( G \), and edges \( uv \) such that \( uv \in E(G) \) xor \( (u, v) \in (A \times B) \cup (B \times A) \). For a set \( F = \{F_1, \ldots, F_n\} \) of flips, we write \( G \oplus F \) for the graph \( G \oplus F_1 \oplus \cdots \oplus F_n \).

\begin{definition}
A class of graphs \( \mathcal{C} \) is \textit{flip-flat} if for every \( r \in \mathbb{N} \) there exists a function \( N_r : \mathbb{N} \rightarrow \mathbb{N} \) and a constant \( s_r \in \mathbb{N} \) such that for all \( m \in \mathbb{N} \), \( G \in \mathcal{C} \), and \( A \subseteq V(G) \) with \( |A| \geq N_r(m) \), there exists a set \( F \) of at most \( s_r \) flips and \( B \subseteq A \) with \( |B| \geq m \) such that \( B \) is distance-\( r \) independent in \( G \oplus F \).
\end{definition}
Intuitively, for flip-flat classes in sufficiently large sets one can find large subsets that are distance-$r$ independent after a constant number of flips (see bottom of Figure 1). For example, the class of all cliques is flip-flat, requiring only a single flip to make the whole vertex set distance-$\infty$ independent. Our main result is the following purely combinatorial characterization of monadic stability.

Theorem 3. A class of graphs is monadically stable if and only if it is flip-flat.

Notably, our proof is algorithmic and yields polynomial bounds in the following sense.

Theorem 4. Every monadically stable class $\mathcal{C}$ of graphs is flip-flat, where for every $r$, the function $N_r$ is polynomial. Moreover, given an $n$-vertex graph $G \in \mathcal{C}$, and $r \in \mathbb{N}$, we can compute a subset $B \subseteq A$ and a set of flips $F$ that makes $B$ distance-$r$ independent in $G \oplus F$ in time $O(f_{\mathcal{C}}(r) \cdot n^3)$ for some function $f_{\mathcal{C}}$.

Just as uniform quasi-wideness provided a key tool for the algorithmic treatment of nowhere dense graph classes, in particular for first-order model checking [24], we believe that the characterization by flip-flatness will provide an important step towards the algorithmic treatment of monadically stable classes. We leave as an open question whether a similar characterization of monadically NIP classes exists.

Indiscernible sequences. Our study is based on indiscernible sequences, which are a fundamental tool in model theory. An indiscernible sequence is a (finite or infinite) sequence $I = (\bar{a}_1, \bar{a}_2, \ldots)$ of tuples of equal length of elements of a fixed (finite or infinite) structure, such that any two finite subsequences of $I$ that have equal length, satisfy the same formulas. More generally, for a set of formulas $\Delta$, the sequence $I$ is $\Delta$-indiscernible if for each formula $\varphi(\bar{x}_1, \ldots, \bar{x}_k)$ from $\Delta$ either all subsequences of $I$ of length $k$ satisfy $\varphi$, or no subsequence of length $k$ satisfies $\varphi$. For example, any enumeration of vertices forming a clique or an independent set in a graph is $\Delta$-indiscernible for $\Delta = \{E(x_1, x_2)\}$ containing only the edge relation. Also, any increasing sequence of rationals in the structure $(\mathbb{Q}, <)$ is $\Delta$-indiscernible for $\Delta$ being the set of all formulas. We use indiscernible sequences to obtain new insights about monadically stable and monadically NIP classes.

It was shown by Blumensath [4] that in monadically NIP classes, any fixed element interacts with the tuples of an indiscernible sequence in a very regular way. We give a new finitary proof of Blumensath’s result. Building on this, we develop our main technical tool, Theorem 11, where we show that the regular properties of the indiscernible sequences extend to their disjoint definable neighborhoods (see Section 3.2 for details). A result similar to Theorem 11, also for disjoint definable neighborhoods in monadically NIP classes, plays a key role in [6, 35].

Apart from powering our algorithmic proof of flip-flatness, Theorem 11 has already found further applications in monadically stable classes of graphs: it was recently used to obtain improved bounds for Ramsey numbers [14] and to prove an algorithmic game-characterization of these classes, called Flipper game [20]. The paper [20] provides two proofs for this game characterization. One is constructive and algorithmic and builds on our work. The other builds on model theoretic tools; it is non-constructive but self-contained and highlights additional properties of monadically stable graph classes, including a second (though non-constructive) proof of Theorem 3. The algorithmic version of the Flipper game plays a crucial role for proving that the first-order model checking problem is fixed parameter tractable for structurally nowhere dense classes of graphs [16]. This suggests that our developed techniques may be an important tool towards resolving Conjecture 1.
2 Preliminaries

We use standard notation from graph theory and model theory and refer to [11] and [25] for extensive background. We write \( |m| \) for the set of integers \( \{1, \ldots, m\} \).

Relational structures and graphs. A (relational) signature \( \Sigma \) is a set of relation symbols, each with an associated non-negative integer, called its arity. A \( \Sigma \)-structure \( A \) consists of a universe, which is a non-empty, possibly infinite set, and interpretations of the symbols from the signature: each relation symbol of arity \( k \) is interpreted as a \( k \)-ary relation over the universe. By a slight abuse of notation, we do not differentiate between structures and their universes and between relation symbols and their interpretations. By \( \mathcal{C} \) we denote classes of structures over a fixed signature. Unless indicated otherwise, \( \mathcal{C} \) may contain finite and infinite structures.

A monadic extension \( \Sigma^+ \) of a signature \( \Sigma \) is any extension of \( \Sigma \) by unary predicates. A unary predicate will also be called a color. A monadic expansion or coloring of a \( \Sigma \)-structure \( A \) is a \( \Sigma^+ \)-structure \( A^+ \), where \( \Sigma^+ \) is a monadic extension of \( \Sigma \), such that \( A \) is the \( \Sigma \)-reduct of \( A^+ \), that is, the \( \Sigma \)-structure obtained from \( A^+ \) by removing all relations with symbols in \( \Sigma^+ \setminus \Sigma \). When \( \mathcal{C} \) is a class of \( \Sigma \)-structures and \( \Sigma^+ \) is a monadic extension of \( \Sigma \), we write \( \mathcal{C}[\Sigma^+] \) for the class of all possible \( \Sigma^+ \)-expansions of structures from \( \mathcal{C} \).

A graph is a finite structure over the signature consisting of a binary relation symbol \( E \), interpreted as the symmetric and irreflexive edge relation.

First-order logic. We say that two tuples \( \bar{a}, \bar{b} \) of elements are \( \varphi \)-connected in a structure \( A \) if \( A \models \varphi(\bar{a}, \bar{b}) \). We call the set \( N_\varphi^A(\bar{a}) = \{ \bar{b} \in A^{|\bar{b}|} : A \models \varphi(\bar{a}, \bar{b}) \} \) the \( \varphi \)-neighborhood of \( \bar{a} \). We simply write \( N_\varphi(\bar{a}) \) when \( A \) is clear from the context.

Let \( \Phi(\bar{x}) \) be a finite set of formulas with free variables \( \bar{x} \). A \( \Phi \)-type is a conjunction \( \tau(\bar{x}) \) of formulas in \( \Phi \) or their negations, such that every formula in \( \Phi \) occurs in \( \tau \) either positively or negatively. More precisely, \( \tau(\bar{x}) \) is a formula of the following form, for some subset \( A \subseteq \Phi \):

\[
\tau(\bar{x}) = \bigwedge_{\varphi \in A} \varphi(\bar{x}) \land \bigwedge_{\varphi \notin \Phi \setminus A} \neg \varphi(\bar{x}).
\]

Note that for every \(|\bar{x}|\)-tuple \( \bar{a} \) of elements of \( A \), there is exactly one \( \Phi \)-type \( \tau(\bar{x}) \) such that \( A \models \tau(\bar{a}) \).

Stability and NIP. While we already defined monadic stability and NIP in terms of transductions in the introduction, let us also give the equivalent original definition. A formula \( \varphi(\bar{x}, \bar{y}) \) has the \( k \)-order property on a class \( \mathcal{C} \) of structures if there are \( A \in \mathcal{C} \) and two sequences \( (\bar{a}_i)_{1 \leq i \leq k}, (\bar{b}_j)_{1 \leq i \leq k} \) of tuples of elements of \( A \), such that for all \( i, j \in [k] \)

\[
A \models \varphi(\bar{a}_i, \bar{b}_j) \iff i \leq j.
\]

The formula \( \varphi \) is said to have the order property on \( \mathcal{C} \) if it has the \( k \)-order property for all \( k \in \mathbb{N} \). The class \( \mathcal{C} \) is called stable if no formula has the order-property on \( \mathcal{C} \). A class \( \mathcal{C} \) of \( \Sigma \)-structures is monadically stable if for every monadic extension \( \Sigma^+ \) of \( \Sigma \) the class \( \mathcal{C}[\Sigma^+] \) is stable.

Similarly, a formula \( \varphi(\bar{x}, \bar{y}) \) has the \( k \)-independence property on a class \( \mathcal{C} \) if there are \( A \in \mathcal{C} \), a size \( k \) set \( A \subseteq A^{[\bar{x}]} \) and a sequence \( (\bar{b}_j)_{J \subseteq A} \) of tuples of elements of \( A \) such that for all \( J \subseteq A \) and for all \( \bar{a} \in A \)

\[
A \models \varphi(\bar{a}, \bar{b}_J) \iff \bar{a} \in J.
\]
We then say that $A$ is shattered by $\varphi$. We define the independence property (IP), classes with the non-independence property (NIP classes), and monadically NIP classes as expected. Note that every (monadically) stable class is (monadically) NIP, Baldwin and Shelah proved that in the definitions of monadic stability and monadic NIP, one can alternatively rely on formulas $\varphi(x, y)$ with just a pair of singleton variables, instead of a pair of tuples of variables [3, Lemma 8.1.3, Theorem 8.1.8].

We call a relation $R$ definable on a structure $\mathcal{A}$ if $R = \{ \bar{a} \in \mathcal{A}^{[k]} : \mathcal{A} \models \varphi(\bar{a}) \}$ for some formula $\varphi(x)$. The following is immediate from the previous definitions.

**Lemma 5.** Let $\mathcal{C}$ be a monadically stable (monadically NIP) class of $\Sigma$-structures, let $\Sigma^+$ be a monadic extension of $\Sigma$ and let $\mathcal{D}$ be the hereditary closure of any expansion of $\mathcal{C}[\Sigma^+]$ by definable relations. Then also $\mathcal{D}$ is monadically stable (monadically NIP).

A formula $\varphi(x, \bar{y})$ has pairing index $k$ on a class $\mathcal{C}$ of structures if there is $\mathcal{A} \in \mathcal{C}$ and two sequences $(a_{ij})_{1 \leq i < j \leq k}$ and $(\bar{b}_i)_{1 \leq i \leq k}$ such that for all $1 \leq i < j \leq k$ and $\ell \in [k]$

$$\mathcal{A} \models \varphi(a_{ij}, \bar{b}_\ell) \iff \ell \in \{i, j\}.$$ 

We require that $x$ is a single free variable, while $\bar{y}$ is allowed to be a tuple of variables. Intuitively, from a graph theoretic perspective, if a formula has unbounded pairing index on a class $\mathcal{C}$, then it can encode arbitrarily large 1-subdivided cliques in $\mathcal{C}$, where the principal vertices are represented by the tuples $\bar{b}_\ell$ and the subdivision vertices are represented by single elements $a_{ij}$. As discussed in the introduction, this is sufficient to encode arbitrary graphs in $\mathcal{C}$ by using an additional color predicate. In this case, $\mathcal{C}$ cannot be monadically NIP. The above reasoning is formalized in the following characterization.

**Lemma 6.** A class $\mathcal{C}$ of $\Sigma$-structures is monadically NIP if and only if for every monadic extension $\Sigma^+$ of $\Sigma$ every $\Sigma^+$-formula $\varphi(x, \bar{y})$ has bounded pairing index on $\mathcal{C}[\Sigma^+]$.

**Indiscernible sequences.** Let $\mathcal{A}$ be a $\Sigma$-structure and $\varphi(\bar{x}_1, \ldots, \bar{x}_m)$ a formula. We say a sequence $(\bar{a}_i)_{1 \leq i \leq n}$ of tuples from $\mathcal{A}$ (where all $\bar{x}_i$ and $\bar{a}_i$ have the same length) is a $\varphi$-indiscernible sequence of length $n$, if for every two sequences of indices $i_1 < \cdots < i_m$ and $j_1 < \cdots < j_m$ from $[n]$ we have

$$\mathcal{A} \models \varphi(\bar{a}_{i_1}, \ldots, \bar{a}_{i_m}) \iff \mathcal{A} \models \varphi(\bar{a}_{j_1}, \ldots, \bar{a}_{j_m}).$$

For a set of formulas $\Delta$ we call a sequence $\Delta$-indiscernible if it is $\varphi$-indiscernible for all $\varphi \in \Delta$. For finite $\Delta$, by (iteratively applying) Ramsey’s theorem we can extract a $\Delta$-indiscernible sequence from any sequence. In general structures however, in order to extract a large $\Delta$-indiscernible sequence we must initially start with an enormously large sequence. To the best of our knowledge the following theorem goes back to Ehrenfeucht and Mostowski [17].

**Theorem 7.** Let $\Delta$ be a finite set of formulas. There exists a function $f$ such that every sequence of elements of length at least $f(m)$ (in a structure with a signature matching $\Delta$) contains a $\Delta$-indiscernible subsequence of length $m$.

In stable classes we can efficiently find polynomially large (that is, $f(m) = m^{O(1)}$) indiscernible sequences of elements (see also [28, Theorem 3.5]). In the full version of the paper we observe that the run time is essentially bounded by the time it takes to evaluate the formulas from $\Delta$ on a small polynomial part of the input structure.
3 Technical overview

Our work is organized as follows. Section 3.1 introduces useful combinatorial properties of indiscernibles in monadically NIP classes. We extend those properties in Section 3.2, where we prove our main tool, Theorem 11. We use this tool in Section 3.3 to prove flip-flatness. Due to space constraints, we mostly provide proof sketches, which should convey the key ideas. All missing proofs can be found in the full version of the paper [15].

3.1 Indiscernibles in monadically stable and monadically NIP classes

In classical model theory, instead of classes of finite structures, usually infinite structures are studied. For a single infinite structure $\mathbb{A}$, we say $\mathbb{A}$ is (monadically) stable/NIP, if the class $\{\mathbb{A}\}$ is (monadically) stable/NIP. In this context, an indiscernible sequence is usually assumed to be of infinite length and indiscernible over the set of all first-order formulas. Using $\Omega$ to denote the set of all first-order formulas, we will denote the latter property as $\Omega$-indiscernibility.

It is well-known that indiscernible sequences can be used to characterize stability and NIP for infinite structures. To characterize NIP, define the alternation rank of a formula $\varphi(x, y)$ over a sequence $I$ in a structure $\mathbb{A}$ as the maximum $k$ such that there exists a (possibly non-contiguous) subsequence $(\bar{a}_1, \ldots, \bar{a}_{k+1})$ of $I$ and a tuple $\bar{b} \in \mathbb{A}^{2}$ such that for all $i \in [k]$ we have $\mathbb{A} \models \varphi(\bar{b}, \bar{a}_i) \iff \mathbb{A} \models \neg \varphi(\bar{b}, \bar{a}_{i+1})$. A structure $\mathbb{A}$ is NIP if and only if every formula has finite alternation rank over every $\Omega$-indiscernible sequence in $\mathbb{A}$ [33, Theorem 12.17]. Stable classes can be characterized in a similar way. We say the exception rank of a formula $\varphi(x, y)$ over a sequence $I$ in a structure $\mathbb{A}$ is the maximum $k$ such that there exists a tuple $\bar{b} \in \mathbb{A}^{2}$ such that for $k$ distinct tuples $\bar{a}_i \in I$ we have $\mathbb{A} \models \varphi(\bar{b}, \bar{a}_i)$ and for $k$ other distinct tuples $\bar{a}_i \in I$ we have $\mathbb{A} \models \neg \varphi(\bar{b}, \bar{a}_i)$. A structure $\mathbb{A}$ is stable if and only if every formula has finite exception rank over every $\Omega$-indiscernible sequence in $\mathbb{A}$ [33, Corollary 12.24].

Hence, NIP and stability can be characterized by the interaction of tuples of elements with indiscernible sequences. For monadically NIP structures, Blumensath [4] shows that the interaction of single elements with indiscernible sequences is even more restricted.

Theorem 8 ([4, Corollary 4.13]). In every monadically NIP structure $\mathbb{A}$, for every formula $\varphi(x, y)$, where $x$ is a single free variable, and $\Omega$-indiscernible sequence $(\bar{a}_i)_{i \in \mathbb{N}}$ of $|y|$-tuples the following holds: for every element $b \in \mathbb{A}$ there exists an exceptional index $\text{ex}(b) \in \mathbb{N}$ and two truth values $t_{<}(b), t_{>}(b) \in \{0, 1\}$ such that

for all $i < \text{ex}(b) : \mathbb{A} \models \varphi(b, \bar{a}_i) \iff t_{<}(b) = 1$, and

for all $i > \text{ex}(b) : \mathbb{A} \models \varphi(b, \bar{a}_i) \iff t_{>}(b) = 1$.

See Figure 2 for examples. In particular, the alternation rank of the formulas $\varphi(x, y)$ with a single free variable $x$ over every $\Omega$-indiscernible sequence in a monadically NIP structure is at most 2.

Theorem 8 will be a crucial tool for proving flip-flatness. However, as we strive for algorithmic applications, we have to develop an effective, computable version that is suitable for handling classes of finite structures. Instead of requiring $\Omega$-indiscernibility, we will specifically consider $\Delta$-indiscernible sequences with respect to special sets $\Delta = \Delta_k^\varphi$ that we define soon. These sets $\Delta_k^\varphi$ will strike the right balance of being on the one hand sufficiently rich to allow us to derive structure from them, but on the other hand sufficiently simple such that we can efficiently evaluate formulas from $\Delta_k^\varphi$, making our flip-flatness result algorithmic.
exists an exceptional index $\Phi$ for every element $i$. Later on, we state the result not for single formulas but for $\Phi$-types.

For a finite set of formulas $\Phi(x, y)$ and an integer $k$ we define $\Delta_k^\Phi$ to be the set of all formulas $\gamma(\varphi_1, \ldots, \varphi_{k'})$, where $(\varphi_1, \ldots, \varphi_{k'})$ is a $\Phi$-pattern of length $k' \leq k$. Note that the set $\Delta_k^\Phi$ is finite, as (up to equivalence) there are only finitely many boolean combinations of formulas in $\Phi$. We write $\Delta_k^\varphi$ for $\Delta_k^\Phi$.

We can now state a finitary version of Theorem 8 as follows. For the convenient use later on, we state the result not for single formulas $\varphi$ but for $\Phi$-types.

**Theorem 9.** For every monadically NIP class $\mathcal{C}$ of structures and finite set of formulas $\Phi(x, y)$ there exist integers $n_0$ and $k$, such that for every $\mathcal{A} \in \mathcal{C}$ the following holds. If $I = (\bar{a}_i)_{1 \leq i \leq n}$ is a $\Delta_k^\Phi$-indiscernible sequence of length $n \geq n_0$ in $\mathcal{A}$, and $b \in \mathcal{A}$, then there exists an exceptional index $\text{ex}(b) \in [n]$ and $\Phi$-types $\tau_-(x, \bar{y})$ and $\tau_+(x, \bar{y})$ such that

$\mathcal{A} \models \tau_-(b, \bar{a}_i)$ holds for all $1 \leq i < \text{ex}(b)$, and

$\mathcal{A} \models \tau_+(b, \bar{a}_i)$ holds for all $\text{ex}(b) < i \leq n$.

Our proof uses different tools than [4]. It is combinatorial, fully constructive, and gives explicit bounds on $n_0$ and $k$ as well as the required set of formulas $\Delta_k^\Phi$. One may alternatively finitize Theorem 8 via compactness, but then we do not obtain these crucial properties.

For the more restricted monadically stable classes we can give even stronger guarantees: for every element $b \in \mathcal{A}$, the types do not alternate and we have $\tau_- = \tau_+$.

**Theorem 10.** For every monadically stable class $\mathcal{C}$ of structures and finite set of formulas $\Phi(x, y)$ there exist integers $n_0$ and $k$, such that for every $\mathcal{A} \in \mathcal{C}$ the following holds. If $I = (\bar{a}_i)_{1 \leq i \leq n}$ is a $\Delta_k^\Phi$-indiscernible sequence of length $n \geq n_0$ in $\mathcal{A}$, and $b \in \mathcal{A}$, then there exists an exceptional index $\text{ex}(b) \in [n]$ and a $\Phi$-type $\tau$, such that

$\mathcal{A} \models \tau(b, \bar{a}_i)$ for all $i \in [n]$ with $i \neq \text{ex}(b)$.
Building on Theorem 9, we give a full proof of Theorem 10. In order to give an intuition about the interaction of monadic stability and $\Delta_k^\Phi$-indiscernibility, we sketch a standalone proof here.

**Proof sketch of Theorem 10.** For simplicity, we will focus on the case were $\Phi$ is a singleton set $\{\varphi(x,\bar{y})\}$. Let $k$ be the smallest number such that the bound for the pairing index of $\varphi$ and $\neg \varphi$ on $\mathcal{C}$ is less than $k$. Such a bound exists since $\mathcal{C}$ is in particular monadically NIP. Assume towards a contradiction that there exists a sufficiently long $\Delta_k^\Phi$-indiscernible sequence $I$ in a structure $\mathcal{A} \in \mathcal{C}$ and an element $b \in \mathcal{A}$ that is $\varphi$-connected to at least two tuples in $I$ and not $\varphi$-connected to at least two other tuples in $I$. By symmetry, we can assume that $b$ is not $\varphi$-connected to the majority of $I$. We therefore find a length-$k$ subsequence $\bar{a}_1, \ldots, \bar{a}_k$ of $I$ and two distinct indices $i_0, j_0 \in [k]$, such that $b$ is $\varphi$-connected exactly to the $i_0$th and $j_0$th element of $\bar{a}_1, \ldots, \bar{a}_k$. We say that the $i_0$th and $j_0$th element are $\varphi$-paired by $b$. Our goal is to derive a contradiction by finding also for every other pair $i, j$ of indices an element that $\varphi$-pairs them, witnessing that $\varphi$ has pairing index at least $k$ in $\mathcal{C}$.

In stable classes, every sufficiently long $\Delta_k^\Phi$-indiscernible sequence $I$ is also totally $\Delta_k^\Phi$-indiscernible: This means that every permutation $I'$ of $I$ is again $\Delta_k^\Phi$-indiscernible, with the formulas from $\Delta_k^\Phi$ taking the same truth values on $I'$ as on $I$. Intuitively speaking, if permuting two elements in an indiscernible sequence would change the truth value of a formula, then this formula orders these two elements and by indiscernibility also orders a large part of the sequence, contradicting stability. A proof of the statement for $\Omega$-indiscernibles can be found in [36, Lemma 9.1.1].

For the more general monadically NIP case, we cannot rely on total indiscernibility. Instead, we bound the alternation rank by pairing tuples located around alternation points, leading to a similar but more involved reasoning.

For the more general monadically NIP case, we cannot rely on total indiscernibility. Instead, we bound the alternation rank by pairing tuples located around alternation points, leading to a similar but more involved reasoning.

![Figure 4](image-url) All types of neighborhoods a vertex (top) can have in indiscernible sequences (bottom) in different graph classes.
We conclude this section by mentioning that a behavior similar to Theorem 10 was already observed in [26] for the edge relation in nowhere dense classes. Considering only the edge relation, we depict the different possible behavior of vertices towards indiscernible sequences in different classes of graphs in Figure 4. In monadically NIP (or stable) classes, the same six (or four) patterns apply for connections with respect to any formula $\varphi(x, y)$.

### 3.2 Disjoint definable neighborhoods

In the previous section we have seen that in monadically stable and monadically NIP classes, every element is very homogeneously connected to all but at most one element of an indiscernible sequence. At a first glance, this exceptional behavior towards one element seems to be erratic and standing in the way of combinatorial and algorithmic applications. However, it turns out that it can be exploited to obtain additional structural properties.

The key observation is that elements that are “exceptionally connected” towards a single element of an indiscernible sequence, inherit some of the good properties of that sequence. We will give a simple example to demonstrate this idea. Let $G$ be a graph containing certain red vertices $R$ and blue vertices $B$, such that the edges between $R$ and $B$ describe a matching (see Figure 5, left).

**Figure 5** Examples of one-to-one and many-to-one connections in a graph. On the left: a matching. On the right: a star forest.

Given a formula $\varphi(x_1, \ldots, x_q)$, define

$$\hat{\varphi}(x_1, \ldots, x_q) := \exists b_1, \ldots, b_q \in B. \varphi(b_1, \ldots, b_q) \land \bigwedge_{i \in [q]} E(x_i, b_i).$$

Take a $\hat{\varphi}$-indiscernible sequence $R'$ among $R$. Obviously, every vertex in the blue neighborhood $B'$ of $R'$ has one exceptional connection towards $R'$, that is, towards its unique matching neighbor in $R'$. It is now easy to see that $B'$ is a $\varphi$-indiscernible sequence in $G$: for every sequence of red vertices $a_1, \ldots, a_q \in R'$ and their unique blue matching neighbors $b_1, \ldots, b_q \in B'$ we have $G \models \hat{\varphi}(a_1, \ldots, a_q)$ if and only if $G \models \varphi(b_1, \ldots, b_q)$.

This example sketches how first-order definable one-to-one connections towards elements of an indiscernible sequence preserve indiscernibility. The more general case however is the many-to-one case, where we have a set of elements, each of which is exceptionally connected to a single element of an indiscernible sequence $I$, while allowing multiple elements to be exceptionally connected to the same element of $I$ (think, for example, of $R$ and $B$ being the centers and leaves of a star-forest as depicted in Figure 5, right). Our notion of such many-to-one connections will be that of disjoint $\alpha$-neighborhoods. Recall, that for a formula $\alpha(\bar{x}, y)$, the $\alpha$-neighborhood $N_{\alpha}(\bar{a})$ of a tuple $\bar{a}$ is defined as the set of all $b$ satisfying $\alpha(\bar{a}, b)$. We say a sequence $J$ of $|\bar{x}|$-tuples has disjoint $\alpha$-neighborhoods if $N_{\alpha}(\bar{a}_1) \cap N_{\alpha}(\bar{a}_2) = \emptyset$ for all distinct $\bar{a}_1, \bar{a}_2 \in J$.

As the main technical tool of this paper, we prove for monadically NIP classes that every sequence of disjoint $\alpha$-neighborhoods contains a large subsequence that exerts strong control over its neighborhood. This lifts the strongly regular behaviour of idiscernible sequences to sequences of disjoint $\alpha$-neighborhoods. The main result of this section, Theorem 11, is the backbone of our flip-flatness proof and states the following. In every large sequence of disjoint $\alpha$-neighborhoods, we will find a still-large subsequence such that the $\varphi$-connections...
of every element \(a\) towards all \(\alpha\)-neighborhoods in the subsequence can be described by a bounded set of sample elements in the following sense. After possibly omitting one exceptional neighborhood at index \(\text{ex}(a)\) depending on \(a\), the \(\varphi\)-connections are completely homogeneous (in the stable case) or alternate at most once (in the NIP case). A related (but orthogonal) result was also proved in [38, Lemma 64] using tools from model theory.

\[
\begin{align*}
\text{ex}(a) = &\ s_1 \\
\text{ex}(a) = &\ s_3 \\
\end{align*}
\]

**Figure 6** A visualization of Theorem 11. On the bottom: a sequence \(I\) with disjoint \(\alpha\)-neighborhoods. On the top right: a small set of sample elements \(S\). The \(\varphi\)-neighborhoods of the elements in \(S\) in the \(\alpha\)-neighborhood of \(I\) are colored accordingly. Note that their \(\varphi\)-neighborhoods can overlap. The \(\varphi\)-neighborhood of \(a\) in the \(\alpha\)-neighborhood of \(I\) is equal to the \(\varphi\)-neighborhood of \(s_<(a) = s_1\) before the exceptional index \(\text{ex}(a)\). After it, it is equal to the \(\varphi\)-neighborhood of \(s_>(a) = s_3\). For the \(\alpha\)-neighborhood of \(\bar{a}\) we make no claims.

**Theorem 11.** For every monadically NIP class of structures \(\mathcal{C}\), and formulas \(\varphi(x, y)\) and \(\alpha(x, y)\), there exists a function \(N : \mathbb{N} \to \mathbb{N}\) and an integer \(k\) such that for every \(m \in \mathbb{N}\) every structure \(\mathcal{A} \in \mathcal{C}\) and every finite sequence of tuples \(J \subseteq \mathcal{A}^{[m]}\) of length \(N(m)\) whose \(\alpha\)-neighborhoods are disjoint the following holds. There exists a subsequence \(I = (\bar{a}_i)_{1 \leq i \leq m} \subseteq J\) of length \(m\) and a set \(S \subseteq \mathcal{A}\) of at most \(k\) sample elements such that for every element \(a \in \mathcal{A}\) there exists an exceptional index \(\text{ex}(a) \in [m]\) and a pair \(s_<(a), s_>(a) \in S\) such that

\[
\text{for all } 1 \leq i < \text{ex}(a) : N_\alpha(\bar{a}_i) \cap N_\varphi(a) = N_\alpha(\bar{a}_i) \cap N_\varphi(s_<(a)), \text{ and}
\]

\[
\text{for all } \text{ex}(a) < i \leq m : N_\alpha(\bar{a}_i) \cap N_\varphi(a) = N_\alpha(\bar{a}_i) \cap N_\varphi(s_>(a)).
\]

If \(a \in N_\alpha(\bar{a}_i)\) for some \(\bar{a}_i \in I\), then \(i = \text{ex}(a)\).

If \(\mathcal{C}\) is monadically stable, then \(s_< (a) = s_>(a)\) for every \(a \in \mathcal{A}\).

A visualization of the NIP case of Theorem 11 is provided in Figure 6. An important ingredient of the proof is the following Ramsey-type result due to Ding et al. [12, Corollary 2.4]. We say a bipartite graph with sides \(a_1, \ldots, a_t\) and \(b_1, \ldots, b_t\) forms

- a *matching* of order \(\ell\) if \(a_i\) and \(b_j\) are adjacent if and only if \(i = j\) for all \(i, j \in [\ell]\),
- a *co-matching* of order \(\ell\) if \(a_i\) and \(b_j\) are adjacent if and only if \(i \neq j\) for all \(i, j \in [\ell]\),
- a *ladder* of order \(\ell\) if \(a_i\) and \(b_j\) are adjacent if and only if \(i \leq j\) for all \(i, j \in [\ell]\).

We call two distinct vertices \(u\) and \(v\) **twin**s in a graph \(G\) they have the same neighborhood with regard to the edge relation, i.e. \(N_G^G(u) \setminus \{v\} = N_G^G(v) \setminus \{u\}\).
**Theorem 12** ([12, Corollary 2.4]). There exists a function $Q : \mathbb{N} \to \mathbb{N}$ such that for every $\ell \in \mathbb{N}$ and for every bipartite graph $G = (L, R, E)$ without twins, where $L$ has size at least $Q(\ell)$, contains a matching, co-matching, or ladder of order $\ell$ as an induced subgraph.

Equipped with Theorem 10 from the previous subsection and the above Theorem 12, we will now give a proof sketch of the monadically stable case of Theorem 11.

**Proof sketch of Theorem 11 (monadically stable case).** We will build the sequence $I$ by inductively extracting indiscernible subsequences $I_i$ of $J$ and growing a set of sample elements $S_i = \{s_1, \ldots, s_i\}$. During the induction, we maintain the following invariant: every two distinct sample elements from $S_i$ have pairwise different $\varphi$-neighborhoods in the $\alpha$-neighborhood of every tuple of $I_i$. We start with $I_0 = J$ and $S_0 = \emptyset$ where this trivially holds. Let us now describe the inductive construction of $I_{i+1}$ and $S_{i+1}$. We first add a constant symbol for every element in $S_i$ to the signature of $\mathcal{A}$. This extended signature will allow us to express for all $j \in [i]$ the formula $\nu_j(x, \bar{y})$ stating that $x$ has the same $\varphi$-neighborhood as $s_j$ in the $\alpha$-neighborhood of $\bar{y}$, i.e., $N_\nu(y) \cap N_\varphi(x) = N_\nu(y) \cap N_\varphi(s_j)$. We collect all these formulas into the set $\Phi = \{\nu_j : j \in [i]\}$ and build $I_{i+1}$ by extracting a $\Delta^2_\varphi$-indiscernible sequence from $I_i$, for the appropriate value of $k$ given by Theorem 10. Now by Theorem 10, for every element $b \in \mathcal{A}$, there exists a $\Phi$-type $\tau(x, \bar{y})$ such that $b$ is $\tau$-connected to all but at most one tuple from $I_{i+1}$. Since the $\Phi$-types capture information about the connections relative to vertices in $S_i$, one of the following two cases applies for every $b \in \mathcal{A}$.

1. The $\varphi$-neighborhood of $b$ is different to the $\varphi$-neighborhood of every element of $S_i$ in the $\alpha$-neighborhood all but at most one tuple of $I_{i+1}$.
2. For some $j \in [i]$, the $\varphi$-neighborhood of $b$ is equal to the $\varphi$ neighborhood of $s_j$ in the $\alpha$-neighborhood around all but at most one tuple of $I_{i+1}$ (whose index will be $\text{ex}(b)$).

If the first case applies for some $b \in \mathcal{A}$, then we can build $S_{i+1}$ by setting $s_{i+1} := b$, which satisfies our invariant (after we possibly drop one more element from $I_{i+1}$). If the second case applies for every $b \in \mathcal{A}$, every element is represented by $S_i$, and the construction stops with $I := I_{i+1}$ and $S := S_i$.

It now remains to show that the construction stops after less than $k$ steps for some $k$ depending only on $\mathcal{C}$, $\varphi$, and $\alpha$. To this end, we show that for every $\ell \in \mathbb{N}$, there exists $k \in \mathbb{N}$ with the following property. If there exists $I_k$ and $S_k$ satisfying the invariant of our construction, then we can derive a formula $\psi$ from $\varphi$ and $\alpha$ which has pairing index at least $\ell$ in an expansion of $\mathcal{A}$ with a constant number of colors (in the full proof we use 3 colors). As $\mathcal{C}$ is monadically NIP, the pairing index of $\psi$ is bounded, which also yields a bound for $k$.

Assume we are given $I_k$ and $S_k$, such that all the elements from $S_k$ have different $\varphi$-neighborhoods, in the $\alpha$-neighborhoods around the tuples of $I_k$. By choosing $k$ large enough, repeated application of Theorem 12 and the pigeonhole principle, we find a subset $S' = \{s_1, \ldots, s_{\ell}\}$ of $S_k$ and a subsequence $I' = \{\bar{a}_1, \ldots, \bar{a}_{\ell}\}$ of $I_k$ with the following property. For each $j \in [\ell]$, there exists a subset $N'_j$ of the $\alpha$-neighborhood of $\bar{a}_j$, such that the $\varphi$-connections from $S'$ to the $N'_j$ all form a matching, all form a co-matching, or all form a ladder. Assume the $\varphi$-connections form a matching. Let us now show that the formula

$$\psi(x, \bar{y}) := \exists z \in N_\varphi(x) \cap N_\alpha(\bar{y}). R(z)$$

has pairing index at least $\ell$ in the class $\mathcal{C}$ extended with an additional unary predicate $R$. The situation is depicted in Figure 7. The formulas $\varphi$ and $\alpha$ interpret a large 1-subdivided biclique in $\mathcal{A}$ as follows. The tuples from $I'$ and the elements from $S'$ form the principle vertices. The subdivision vertices are formed by $\bigcup_{\ell \in [\ell]} N'_\ell$. Due to the assumed matchings, each subdivision element has exactly one incoming $\varphi$-connection from $S'$. Due to the tuples
in \( I' \) having disjoint \( \alpha \)-neighborhoods, each subdivision element has exactly one incoming \( \alpha \)-connection from the elements of \( I' \). Since \( I' \) has size \( t \) and \( S' \) has size \( t^2 \) we can assign to every pair \( \bar{a}_i, \bar{a}_j \in I' \) a unique element \( s_{ij} \in S' \). By marking with the predicate \( R \) the two unique subdivision elements from \( N_r(s_{ij}) \cap N'_i \) and \( N_r(s_{ij}) \cap N'_j \), we get that \( s_{ij} \) is \( \psi' \)-connected only to \( \bar{a}_i \) and \( \bar{a}_j \) among \( I' \). As desired, \( S' \) and \( I' \) witness that \( \psi \) has pairing index at least \( t \).

In case the \( \varphi' \)-connections form a co-matching or a ladder, we can replace \( \varphi \) with a derived formula \( \varphi' \), such that the \( \varphi' \)-connections form a matching in a coloring of \( \bar{G} \), which completes the proof sketch for the size bound of \( S \).

Lastly, in order to ensure that \( a \in N_\alpha(\bar{a}_i) \) implies \( i = \text{ex}(a) \), we can augment the formula \( \psi_j(x, \bar{y}) \) in the construction to return false whenever \( x \) is contained in \( N_\alpha(\bar{y}) \). This way, we enforce the single exception given by Theorem 10 to be on \( a_i \).

To prove the more general NIP case, we replace Theorem 10 with Theorem 9, which introduces the possibility for a vertex \( a \) to be sampled by two vertices \( s_<(a) \) and \( s_>(a) \), alternating around \( \text{ex}(a) \). We also have to slightly adapt the search for the next sample element \( s_j \) using an additional indiscernibility argument.

### 3.3 Flatness in monadically stable classes of graphs

In this section we use Theorem 11 to characterize monadically stable graph classes in terms of flip-flatness. We start with the forward direction, restated for convenience.

#### Theorem 4.
Every monadically stable class \( \mathcal{C} \) of graphs is flip-flat, where for every \( r \), the function \( N_r \) is polynomial. Moreover, given an \( n \)-vertex graph \( G \in \mathcal{C} \), \( A \subseteq V(G) \), and \( r \in \mathbb{N} \), we can compute a subset \( B \subseteq A \) and a set of flips \( F \) that makes \( B \) distance-\( r \) independent in \( G \oplus F \) in time \( O(f_\varphi(r) \cdot n^3) \) for some function \( f_\varphi \).

**Partial proof.** Let \( \mathcal{C} \) be a monadically stable class of graphs and \( r \in \mathbb{N} \). We want to show that in every graph \( G \in \mathcal{C} \), in every set \( A \subseteq V(G) \) of size \( N_r(m) \) we find a subset \( B \subseteq A \) of size at least \( m \) and a set \( F \) of at most \( s_r \) flips such that \( B \) is distance-\( r \) independent in \( G \oplus F \). We will first inductively describe how to obtain the set of vertices \( B \) and the set of flips \( F \) and bound the runtime and values for \( N_r \) and \( s_r \) later. In the base case we have \( r = 0 \). We can pick \( B := A \) and \( F := \emptyset \) and there is nothing to show.

In the inductive case we assume the result is proved for \( r \) and extend it to \( r + 1 \). Let \( r = 2i + p \) for some \( i \in \mathbb{N} \) and parity \( p \in \{0, 1\} \). Apply the induction hypothesis to obtain \( s_r \) flips \( F_r \) and a set \( A_r \) that is distance-\( r \) independent in \( G_r := G \oplus F_r \). Note that for every fixed number \( t \) of flips, since flips are definable by coloring and a quantifier-free formula, the class \( \mathcal{C}_t \) of all graphs obtainable from graphs of \( \mathcal{C} \) by at most \( t \) flips is monadically stable by Lemma 5. Hence, \( G_r \) comes from the monadically stable class \( \mathcal{C}_{s_r} \). Our goal is to
find a set of flips $F'_{r+1}$ (of fixed finite size which will determine the number $s_{r+1}$) together with a set $A_{r+1} \subseteq A_r$, that is distance-$(r+1)$ independent in $G_{r+1} := G_r \oplus F'_{r+1}$. Then $G_r = G \oplus F_{r+1}$ with $F_{r+1} = F_r \cup F'_{r+1}$.

Since the elements in $A_r$ have pairwise disjoint distance-$i$ neighborhoods, we can apply Theorem 11 to $A_r$ with $\varphi(x, y) = E(x, y)$ and $\alpha(x, y) = \text{dist}\_\leq i(x, y)$. Since we are in the monadically stable case, this yields a subset $A_{r+1} \subseteq A_r$ and a small set of sample vertices $S$ such that for every vertex $a \in V(G)$ there exists $s(a) \in S$ and $\text{ex}(a) \in A_{r+1}$ such that $a$ has the same edge-neighborhood as $s(a)$ in the distance-$i$ neighborhoods of all elements from $A_{r+1} \setminus \{\text{ex}(a)\}$. We now do a case distinction depending on whether $r$ is even or odd.

**The odd case: $r = 2i + 1$.** For every $s \in S$ let $C_s$ be the set containing every vertex $a$ for which we have $s(a) = s$ and that is at distance at least $i + 1$ from every vertex in $A_{r+1}$. Let $D_s$ be the set containing every edge-neighbor of $s$ that is at distance exactly $i$ from one of the vertices in $A_{r+1}$. We now build the set of flips $F'_{r+1}$ by adding for every sample vertex $s \in S$ the flip $(C_s, D_s)$.

Let us now argue that $A_{r+1}$ is distance-$(r+1)$ independent in $G_{r+1} := G_r$. We only flip edges in $G_r$ between pairs of vertices $a, b$ such that $a$ has distance (in $G_r$) at least $i+1$ and $b$ has distance exactly $i$ to $A_{r+1}$. It follows that $A_{r+1}$ remains distance-$(2i+1)$ independent in $G_{r+1}$. Assume towards a contradiction that there exists a path $P = (a, a_1, \ldots, a_i, u, b_1, \ldots, b_i, b)$ of length $r + 1 = 2i + 2$ between two vertices $a, b \in A_{r+1}$ in $G_{r+1}$. The distance between $a$ and $a_i$ (resp. $b$ and $b_i$) is not affected by the flips. Only the connection between $a_i$ (resp. $b_i$) and $u$ can possibly be impacted. Additionally, note that $u \in C_{s(u)}$.

Since $a$ and $b$ are distinct we have that either $\text{ex}(u) \neq a$ or $\text{ex}(u) \neq b$. By symmetry we can assume the former case. As $a_i$ is in the distance-$i$ neighborhood of $a$, we have $G_r \models E(u, a_i) \iff G_r \models E(s(u), a_i)$. Observe that if $E(s(u), a_i)$ holds in $G_r$, then $a_i \in D_{s(u)}$ and therefore the edge $(u, a_i)$ was removed by the flips and is not in $G_{r+1}$. Similarly, if $E(s(u), a_i)$ does not hold in $G_r$, then $a_i \notin D_{s(u)}$ and the edge $(u, a_i)$ was not introduced by any flip. We can conclude that $P$ is not a path in $G_{r+1}$, and that $A_{r+1}$ is distance-$(r+1)$ independent in $G_{r+1}$.

**The even case and runtime analysis.** The even distance creates a symmetry that requires additional care to handle, but otherwise proceeds similarly to the odd case. The arguments concerning size bounds and runtimes can be found there as well. The runtime bound crucially uses the fact that we take $\Delta^2_k$-indiscernible sequences only with respect to formulas $\Phi$ that can be evaluated in polynomial time.

We have shown that for graph classes, monadic stability implies flip-flatness. We now show that the reverse holds as well. We will use the following statement, which is an immediate consequence of Gaifman’s locality theorem [18]. For an introduction of the locality theorem see for example [23, Section 4.1].

**Corollary 13** (of [18, Main Theorem]). Let $\varphi(x, y)$ be a formula. Then there are numbers $r, t \in \mathbb{N}$, where $r$ depends only on the quantifier-rank of $\varphi$ and $t$ depends only on the signature and quantifier-rank of $\varphi$, such that every (colored) graph $G$ can be vertex-colored using $t$ colors in such a way that for any two vertices $u, v \in V(G)$ with distance greater than $r$ in $G$, $G \models \varphi(u, v)$ depends only on the colors of $u$ and $v$. We call $r$ the Gaifman radius of $\varphi$.

**Lemma 14.** Every flip-flat class of graphs is monadically stable.
Proof sketch of Lemma 14. Assume towards a contradiction that there exists a class $\mathcal{C}$ that is not monadically stable but flip-flat. Then there exists a formula $\sigma(x,y)$ and a graph $G \in \mathcal{C}$, such that $\sigma$ defines an order on a large vertex set $A$ in a coloring $G^+$. Let $r$ be the Gaifman radius of $\sigma$. By flip-flatness there exists a (still large) subset $B$ of $A$ and a bounded size set of flips $F$, such that $B$ is distance-$r$ independent in $H := G^+ \oplus F$. Let $H^+$ be the graph where we have marked the flips $F$ with colors in $H$. We can rewrite $\sigma$ to a formula $\sigma'$ of the same quantifier rank such that for all $u,v \in V(G)$ we have $H^+ \models \sigma'(u,v)$ if and only if $G^+ \models \sigma(u,v)$. In particular, $\sigma'$ orders $B$ in $H^+$. By Corollary 13 and the pigeonhole principle, there must be two distinct vertices $u,v \in B$ such that $H^+ \models \sigma'(u,v)$ if and only if $H^+ \models \sigma'(v,u)$. However as $\sigma'$ orders $B$, we also have $H^+ \not\models \sigma'(v,u)$; a contradiction. ◀

From Theorem 4 and Lemma 14 we conclude the following.

▶ Theorem 3. A class of graphs is monadically stable if and only if it is flip-flat.

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