One- and two-component bottle-brush polymers: simulations compared to theoretical predictions

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Summary: Scaling predictions and results from self-consistent field calculations for bottle-brush polymers with a rigid backbone and flexible side chains under good solvent conditions are summarized and their validity and applicability is assessed by a comparison with Monte Carlo simulations of a simple lattice model. It is shown that under typical conditions, as they are also present in experiments, only a rather weak stretching of the side chains is realized, and then the scaling predictions based on the extension of the Daoud-Cotton blob picture are not applicable.

Also two-component bottle brush polymers are considered, where two types (A,B) of side chains are grafted, assuming that monomers of different kind repel each other. In this case, variable solvent quality is allowed for, such that for poor solvent conditions the backbone chains are treated as a rigid straight line or thin cylinder, while the side chains result in more flexible structures. Theories predict "Janus Cylinder"-type phase separation along the backbone in this case. The Monte Carlo simulations, using the pruned-enriched Rosenbluth method (PERM) then are restricted to rather short side chain length. Nevertheless, evidence is obtained that the phase separation between an A-rich part of the cylindrical molecule and a B-rich part can occur locally. The correlation length of this microphase separation can be controlled by the solvent quality. This lack of a phase transition is interpreted by an analogy with models for ferromagnets in one space dimension.

I. Introduction

Flexible macromolecules can be grafted to various substrates by special endgroups. Such "polymer brushes" find widespread applications and also pose challenging theoretical problems, such as an understanding of the conformational statistics and resulting geometrical structure of these tethered chain molecules. Only this latter aspect shall be considered in the present paper, for chains grafted to a straight line or a very narrow cylinder. This problem is a limiting case of "bottle brush" polymers where side chains are grafted to a long macromolecule that forms the backbone of the bottle brush. When this backbone chain is also a flexible polymer and the grafting density is not very high, a "comb polymer" results, which is outside of consideration here. Also we shall not discuss the case where the backbone chain is very short, so the conformation would resemble a "star polymer". Here we restrict attention to either stiff backbone chains or high grafting density of side chains at flexible backbones. In the lattice case stiffening of the backbone occurs due to excluded volume interactions, and a cylindrical shape of the molecule as a whole results. In fact, many experiments have been carried out where with an appropriate chemical synthesis bottle brush polymers with worm-like cylindrical shape were produced. The recent papers[46-50] contain a more detailed bibliography on this rapidly expanding field.

On the theoretical side, two aspects of the conformation of bottle brush polymers where mostly discussed: (i) conformation of a side chain when the backbone can be treated as a rigid straight line or thin cylinder, (ii) conformation of the whole bottle brush when the backbone is (semi)flexible. The latter problem is left out of consideration in the present paper. Problem (i), the stretching of the side chains in the radial direction in the case of sufficiently high grafting density, was mostly discussed in terms of a scaling description[12,13,14,15,16] extending the Daoud-Cotton "blob picture"[1] from star polymers to bottle brush polymers. If one uses the Flory exponent ν = 3/5 in the scaling relation for the average root mean square end-to-end distance of a side chain, Rc ∝ σ(1−ν)/(1+ν)N2ν/(1+ν), where σ is the grafting density and N is the number of effective monomeric units of a side chain, one obtains Rc ∝ σ1/4N3/4. These exponents happen to be identical to those which one would obtain assuming that the chains attain quasi-two-dimensional configurations, resulting if each chain is confined to a disk of width σ−1. Although this latter picture is a misconception, in experimental studies (e.g. [12,13]) this hypothesis of quasi-two-dimensional chains is discussed as a serious possibility. Therefore we find it clearly necessary to first review the correct scaling theory based on the blob picture, and discuss in detail what quantities need to be recorded in order to distinguish between these concepts. Thus, in the next section we shall give a detailed discussion of the scaling concepts for bottle brush polymers with rigid backbones.

Thereafter we shall describe the Monte Carlo test of these predictions, that we have recently performed using the pruned-enriched Rosenbluth method (PERM). After a brief description of the Monte Carlo methodology, we present our numerical results and compare them to the pertinent theoretical predictions.

In the second part of this paper, we discuss the extension from one-component to two-component bottle brush polymers. Just as in a binary polymer blend (A,B) typically the energetically unfavorable in-
teraction (described by the Flory-Huggins parameter $\chi$) should cause phase separation between A-rich and B-rich domains. However, just as in block copolymers where A-chains and B-chains are tethered together in a point, no macroscopic phase separation but only “microphase separation” is possible: for a binary (A,B) bottle brush with a rigid backbone one may expect formation of “Janus Cylinder” structures. This means, phase separation occurs such that the A-chains assemble in one half of the cylinder, the B-chains in the other half, separated from the A-chains via a flat interface containing the cylinder axis. However, it has been argued that the long range order implied by such a “Janus cylinder” type structure has a one-dimensional character, and therefore true long range order is destroyed by fluctuations at nonzero temperature. Only local phase separation over a finite correlation length along the cylinder axis may persist.

We shall again first review the theoretical background on this problem, and then describe the simulation evidence. We conclude our paper by a summary and outlook on questions that are still open, briefly discussing also possible consequences on experimental work. However, we shall not deal with the related problems of microphase separation of a bottle brush with only one kind of side chains induced by deterioration of the solvent quality or by adsorption on flat substrates.

II. Conformation of Side Chains of Bottle Brushes under Good Solvent Conditions: Theoretical Background

The most straightforward approach to understand the conformations of chains in polymer brushes and star polymers under good solvent conditions uses the concept to partition the space available for the chains into compartments, called “blobs”. The idea is that in each such region there occur only monomers of one chain, no monomers of any other chains occur in such a blob, and hence self-avoiding walk statistics holds in each blob. This means, if a (spherical) blob has a radius $r_B$ and contains $n$ monomers, these numbers must be related via

$$r_B = an^\nu, \quad \nu \approx 0.588, \quad n \gg 1. \quad (1)$$

Here $a$ is a length of the order of the size of an effective monomer, and we emphasize from the start that it is crucial to use the correct value of the self-avoiding walk exponent $\nu$, as it is provided from renormalization group calculations or accurate Monte Carlo simulations. If one would ignore the small difference between $\nu$ and the Flory estimate $3/5$, one would already miss an important distinction between two different scaling regimes for a brush on a flat substrate. An almost trivial condition of this “blobology” is that each of the $N$ effective monomeric units of a chain must belong to some blob. So we have

$$N = nn_B, \quad (2)$$

where $n_B$ is the number of blobs belonging to one particular chain.

Finally we note that the space available to the chains must be densely filled with blobs. It then remains to discuss which factors control the blob size $r_B$. The simplest case is a polymer brush on a flat substrate (under good solvent conditions, as assumed here throughout): if we neglect, for simplicity, any local fluctuations in the grafting density, the distance between grafting sites simply is given by $\sigma^{-1/2}$. Putting $r_B = \sigma^{-1/2}$ in Equation 1, we find $r_B = \sigma^{-1/2}$ in Equation 1. However, a more detailed theory of polymer brushes, such as the self-consistent field theory in the strong stretching limit, yields a somewhat different behavior: the end monomer is not localized at the outer edge of the brush, but rather can be located anywhere in the brush, according to a broad distribution; also the monomer density in polymer brushes at flat substrates is not constant up to the brush height $h$, but rather decreases according to a parabolic profile. So even for a polymer brush at a flat substrate already a description in terms of non-uniform blob sizes, that increase with increasing distance $z$ from the substrate, is required.

The free end of the chain is in the last blob and hence the end-to-end distance $R_e \approx h$ in this “Alexander picture” of polymer brushes. However, in the following we shall disregard all these caveats about the Alexander picture for flat brushes, and consider its generalization to the bottle brush geometry, where polymer chains are tethered to a line rather than a flat surface. Then we have to partition space into blobs of nonuniform size and shape in order to respect the cylindrical geometry (Figure 1).

The theory is based on the non-spherical character of the blob of the non-spherical character of the blob. The non-spherical character of the blob is not explicitly accounted for, and it rather is argued that one can characterize the blobs by one effective radius $\xi$ depending on the radial distance $r$ from the cylinder axis. One considers a segment of the array of length $L$ containing $p$ polymer chains. On a surface of a cylinder of radius $r$ and length $L$ there should then be $p$ blobs, each of cross-sectional area $\xi^2$; geometrical factors of order unity are ignored throughout. Since the surface area of the cylindrical segment is $Lr$, we must have

$$p\xi^2(r) = Lr, \quad \xi(r) = (Lr/p)^{1/2} = (r/\sigma)^{1/2}. \quad (4)$$

If the actual non-spherical shape of the blobs (Figure 1) is neglected, the blob volume clearly is of the order of $\sigma^3/2$. This means, if a (spherical) blob has a radius $\sigma$ such region there occur only monomers of one chain, no microscopic phase separation but only “microphase separation” is possible: for a binary (A,B) bottle brush with a rigid backbone one may expect formation of “Janus Cylinder” structures. This means, phase separation occurs such that the A-chains assemble in one half of the cylinder, the B-chains in the other half, separated from the A-chains via a flat interface containing the cylinder axis. However, it has been argued that the long range order implied by such a “Janus cylinder” type structure has a one-dimensional character, and therefore true long range order is destroyed by fluctuations at nonzero temperature. Only local phase separation over a finite correlation length along the cylinder axis may persist.

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\[ \xi^3(r) = (r/\sigma)^{3/2} \]. Invoking again the principle that inside a blob self-avoiding walk statistics hold, we have, in analogy with Equation (1),

\[ \xi(r) = a[n(r)]^\nu, \quad n(r) = [\xi(r)/a]^{1/\nu} = [r/(\sigma a^2)]^{1/2\nu}. \] (5)

From this result one immediately derives the power law decay for the density profile \( \rho(r) \) as follows:

\[ \rho(r) = n(r)/\xi^3(r) = a^{-3}[r/(\sigma a^2)]^{-(3\nu-1)/2\nu} \approx a^{-3}[r/(\sigma a^2)]^{-0.65} \] (6)

Using the Flory approximation \[ \nu = 3/5 \] one would find \( \rho(r) \propto r^{-2/3} \) instead.

Now the average height \( h \) of the bottle brush is estimated by requiring that we obtain all \( \sigma N \) monomers per unit length in the \( z \)-direction along the axis of the bottle brush (cf. Figure 1) when we integrate \( \rho(r) \) from \( r = 0 \) to \( r = h \),

\[ \sigma N = \int_0^h \rho(r)r\,dr = a^{-3}(\sigma a^2)^{(3\nu-1)/2\nu} \int_0^h r^{(1-\nu)/2\nu}\,dr. \] (7)

This yields, again ignoring factors of order unity,

\[ N = (\sigma a)^{(\nu-1)/(2\nu)}(h/a)^{\nu+1/(2\nu)}, \] (8a)
Note that the use of the Flory estimate \( \nu \) would simply yield \( h \propto \sigma^{1/4} N^{3/4} \), which happens to be identical to the relation that one obtains when one partitions the cylinder of height \( L \) and radius \( h \) into disks of height \( \sigma^{-1} \), requiring hence that each chain is confined strictly into one such disk. Then each chain would form a quasi-two-dimensional self-avoiding walk formed from \( n_b^{blob} = N/n' \) blobs of diameter \( \sigma^{-1} \). Since we have \( \sigma^{-1} = a \nu^\nu \) again, we would conclude that the end-to-end distance \( R \) of such a quasi-two-dimensional chain is

\[
R = \sigma^{-1}(n_b^{blob})^{3/4} = \sigma^{-1}n'^{-3/4}N^{3/4} = a(\sigma a)^{-1+3/4\nu}N^{3/4} = a(\sigma a)^{1/4N^{3/4}}. \tag{9}
\]

Putting then \( R = h \), Equation (8b) results when we use there \( \nu = 3/5 \). However, this similarity between Equations (8b), (9) is a coincidence: in fact, the assumption of a quasi-two-dimensional conformation does not imply a stretching of the chain in radial direction. In fact, when we put the x-axis of our coordinate system in the direction of the end-to-end vector \( \vec{R} \) of the chain, we would predict that the y-component of the gyration radius scales as

\[
R_{gy} = \xi(r = h) = (h/\sigma)^{1/2} = a(\sigma a)^{-\nu/(1+\nu)}N^{\nu/(1+\nu)}. \tag{10}
\]

Clearly this prediction is very different from Equation (10), even with the Flory exponent \( \nu = 3/5 \) we find from Equation (11) that \( R_{gy} \propto \sigma^{-3/8}N^{3/8} \). Hence it is clear that an analysis of all three components of the gyration radius of a polymer chain in a bottle brush is very suitable to distinguish between the different versions of scaling concepts discussed in the literature.

However, at this point we return to the geometrical construction of the filling of a cylinder with blobs, Figure 1. We explore the consequences of the obvious fact that the blobs cannot be simple spheres, when we require that each blob contains monomers from a single chain only, and the available volume is densely packed with blobs touching each other.

As mentioned above, \( \xi(r) \) was defined from the available surface area of a cylinder at radius \( r \), cf. Equation (14). It was argued that for each chain in the surface area \( Lr \) of such a cylinder a surface area \( \xi^2(r) \) is available. However, consideration of Figure 1 shows that these surfaces are not circles but rather ellipses, with axes \( f^{-1} \) and \( r/f \). The blobs hence are not spheres but rather ellipsoids, with three different axes: \( f^{-1} \) in the axial z-direction, \( r/f \) in the y-direction tangential on the cylinder surface, normal to both the z-direction and the radial direction, and the geometric mean of these two lengths \( (r\sigma^{-1})^{1/2} \), in the radial x-direction. Since the physical meaning of a blob is that of a volume region in which the excluded volume interaction is not screened, this result implies that the screening of excluded volume in a bottle brush happens in a very anisotropic way: there are three different screening lengths, \( f^{-1} \) in the axial z-direction, \( (r\sigma^{-1})^{1/2} \) in the radial x-direction, and \( r/f \) in the third, tangential, y-direction. Of course, it remains to be shown by a more microscopic theory that such an anisotropic screening actually occurs.

However, the volume of the ellipsoid with these three axes still is given by the formula

\[
V_{ellipsoid} = (\sigma^{-1}f/r/r\sigma^{-1})^{1/2} = (r\sigma^{-1})^{3/2} = [\xi(r)]^3 \tag{12}
\]

with \( \xi(r) \) given by Equation (11), and hence the volume of the blob has been correctly estimated by the spherical approximation. As a consequence, the estimations of the density profile \( \rho(r) \), Equation (8a), and resulting brush heights \( h \), Equation (8b), remain unchanged.

More care is required when we now estimate the linear dimensions of the chain in the bottle brush. We now orient the x-axis such that the \( xz \)-plane contains the center of mass of the considered chain. As Figure 1 indicates, we can estimate \( R_{gz} \) assuming a random walk picture in terms of blobs. When we go along the chain from the grafting site towards the outer boundary of the bottle brush, the blobs can make excursions with \( \Delta z = \pm f^{-1} \), independent of \( r \). Hence we conclude, assuming that the excursions of the \( n_b^{blob} \) steps add up randomly

\[
R_{gz}^2 = \sum_{i=1}^{n_b^{blob}} (f^{-1})^2 = n_b^{blob}(f^{-1})^2, \tag{13}
\]

Hence we must estimate the number of blobs \( n_b^{blob} \) per chain in a bottle brush. We must have

\[
n_b^{blob} = \sum_{i=1}^{n_b^{blob}} 1 = \int_0^h [\xi(r)]^{-1} dr \tag{14}
\]

Note from Figure 1 that we add an increment \( 2\xi(r_i) \) to \( r \) when we go from the shell \( i \) to shell \( i+1 \) in the cylindrical bottle brush. So the discretization of the integral in Equation (14) is equivalent to the sum. From Equation (14) we then find, again ignoring factors of order unity

\[
n_b^{blob} = \sigma^{1/2}h^{1/2} = (\sigma a)^{1/(1+\nu)} N^{\nu/(1+\nu)}, \tag{15}
\]

and consequently

\[
R_{gz} = f a(\sigma a)^{-\nu/(1+\nu)} N^{\nu/(2(1+\nu))} \propto \sigma^{-0.685} N^{0.185}. \tag{16}
\]
With Flory exponents we hence conclude \( n_{\text{blob}} \propto \sigma^{5/8} N^{3/8} \), and thus \( R_{gz} \propto f \sigma^{-11/16} N^{3/16} \). The estimation of \( R_{gy} \) is most delicate, of course, when we consider random excursions away from the radial directions, the excursions \( \Delta y = \pm \xi(r) \) are non-uniform. So we have instead of Equation (13),

\[
R_{gy}^2 = \sum_{i=1}^{n_{\text{blob}}} \xi^2(r_i) = \int_0^h \xi(r)dr,
\]

in analogy with Equation (14). This yields \( R_{gy}^2 = \sigma^{-1/2} h^{3/2} \) and hence

\[
R_{gy} = \sigma^{-1/4} h^{3/4} = a(\sigma a)^{-2(\nu-1)/(2\nu+2)} N^{3\nu/(2\nu+2)} \propto \sigma^{-0.055} N^{0.555}
\]

while the corresponding result with Flory exponents is \( R_{gy} \propto \sigma^{-1/16} N^{9/16} \). These different results for \( R_{gz} \propto h \{\text{Equation (15)}\}, R_{gy} \{\text{Equation (18)}\} \) and \( R_{gz} \{\text{Equation (16)}\} \) clearly reflect the anisotropic structure of a chain in a bottle brush. Note that the result for \( R_{gy} \) according to Equation (18) is much larger than the simple Daoud-Cotton-like prediction, Equation (11), but is clearly smaller than the result of the quasi-two-dimensional picture, Equation (10).

As a consistency check of our treatment, we note that also Equation (7) can be formulated as a discrete sum over blobs

\[
N = \sum_{i=1}^{n_{\text{blob}}} n_i = \int_0^h \left[ n(r)/\xi(r) \right] dr = \int_0^h \left[ r/(\sigma a) \right]^{1/2\nu-1/2} dr,
\]

which yields Equation (15), as it should be.

Finally we discuss the crossover towards mushroom behavior. Physically, this must occur when the distance between grafting points along the axis, \( f \sigma^{-1} \), becomes equal to \( aN^{\nu} \). Thus we can write

\[
h = aN^{\nu} \tilde{h}(\sigma a N^{\nu}),
\]

where we have absorbed the extra factor \( f \) in the scaling function \( \tilde{h}(\zeta) \). We note that Equation (15) results from Equation (20) when we request that

\[
\tilde{h}(\zeta \gg 1) \propto \zeta^{(1-\nu)/(1+\nu)},
\]

and hence a smooth crossover between mushroom behavior and radially stretched polymer conformations occurs for \( \sigma a N^{\nu} \) of order unity, as it should be. Analogous crossover relations can be written for the other linear dimensions, too:

\[
R_{gz} = aN^{\nu} \tilde{R}_{gz}(\zeta), \quad \tilde{R}_{gz}(\zeta \gg 1) \propto \zeta^{-(2\nu+1)/(2\nu+2)},
\]

\[
R_{gy} = aN^{\nu} \tilde{R}_{gy}(\zeta), \quad \tilde{R}_{gy}(\zeta \gg 1) \propto \zeta^{-(2\nu-1)/(2\nu+2)},
\]

The agreement between Equation (16) and Equation (22) or Equation (18) and Equation (23), respectively, provides a check on the self-consistency of our scaling arguments.

However, it is important to bear in mind that the blob picture of polymer brushes, as developed by Alexander, Daoud and Cotton, Halperin, and many others, is a severe simplification of reality, since its basic assumptions that (i) all chains in a polymer brush are stretched in the same way, and (ii) the chain ends are all at a distance \( h \) from the grafting sites, are not true. Treatments based on the self-consistent field theory, computer simulations, and computer simulations, have shown that chain ends are not confined at the outer boundary of the brush, and the monomer density distribution is a nontrivial function, that cannot be described by the blob model. However, it is widely believed that the blob model yields correctly the power laws of chain linear dimensions in terms of grafting density and chain length, so the shortcomings mentioned above affect the prefactors in these power laws only. In this spirit, we have extended the blob model for brushes in cylindrical geometry in the present section, taking the anisotropy in the shape of the blobs into account to predict the scaling behavior of both the brush height \( h \) (which corresponds to the chain end-to-end distance \( R \) and the x-component \( R_{gz} \) of the gyration radius) and of the transverse gyration radius components \( R_{gy}, R_{gz} \). To our knowledge, the latter have not been considered in the previous literature.

### III. Monte Carlo Methodology

We consider here the simplest lattice model of polymers under good solvent conditions, namely, the self-avoiding walk on the simple cubic lattice. The backbone of the bottle brush is just taken to be the z-axis of the lattice, and in order to avoid any effects due to the ends of the backbone, we choose periodic boundary conditions in the z-direction. The length of the backbone is taken to be \( L_4 \) lattice spacings, and the lattice spacing henceforth is taken as one unit of length. Note that in order to avoid finite size effects \( L_6 \) has to be chosen large enough so that no side chain can interact with its own “images” created by the periodic boundary condition, i.e. \( R_{gz} \ll L_6 \).

We create configurations of the bottle brush polymers applying the pruned-enriched-Rosenbluth method (PERM) \cite{PERM}. This algorithm is based on the biased chain growth algorithm of Rosenbluth and Rosenbluth, \cite{Rosenbluth} and extends it by re-sampling technique (“population control”) \cite{PopCon} with depth-first implementation. Similar to a recent study of star polymers \cite{Star}, all side chains of the bottle brush are grown simultaneously, adding one monomer to each side chain one after the other before the growth process of the first chain continues by the next step.
When a monomer is added to a chain of length \( n - 1 \) (containing \( n \) monomers) at the \( n \)th step, one scans the neighborhood of the chain end to identify the free neighboring sites of the chain end, to which a monomer could be added. Out of these \( n_{\text{free}} \) sites available for the addition of a monomer one site is chosen with the probability \( p_{n,i} \) for the \( i \)th direction. One has the freedom to sample these steps from a wide range of possible distributions, e.g. \( p_{n,i} = 1/n_{\text{free}} \), if one site is chosen at random, and this additional bias is taken into account by suitable weight factors. The total weight \( W_n \) of a chain of length \( n \) with an unbiased sampling is determined recursively by \( W_n = \prod_{i=1}^{n} w_b = W_{n-1} w_n \). While the weight \( w_n \) is gained at the \( n \)th step with a probability \( p_{n,i} \), one has to use \( w_n/p_{n,i} \) instead of \( w_n \). The partition sum of a chain of length \( n \) (at the \( n \)th step) is approximated as

\[
Z_n \approx \hat{Z}_n = M_n^{-1} \sum_{\alpha=1}^{M_n} W_n(\alpha),
\]

where \( M_n \) is the total number of configurations \( \{\alpha\} \), and averages of any chain property (e.g. its end-to-end distance, gyration radius components, etc.) \( \bar{A}(\alpha) \) are obtained as

\[
\bar{A}_n = \frac{1}{M_n} \sum_{\alpha=1}^{M_n} \frac{A(\alpha) W_n(\alpha)}{Z_n}
\]

As is well-known from Ref. \[84\], for this original biased sampling \[21\] the statistical errors for large \( n \) are very hard to control. This problem is alleviated by population control. \[85\] One introduces two thresholds

\[
W_n^+ = C_+ \hat{Z}_n, \quad W_n^- = C_- \hat{Z}_n,
\]

where \( \hat{Z}_n \) is the current estimate of the partition sum, and \( C_+ \) and \( C_- \) are constants of order unity. The optimal ratio between \( C_+ \) and \( C_- \) is found to be \( C_+/C_- \approx 10 \) in general. If \( W_n \) exceeds \( W_n^+ \) for the configuration \( \alpha \), one produces \( k \) identical copies of this configuration, replaces their weight \( W_n \) by \( W_n/k \), and uses these copies as members of the population for the next step, where one adds a monomer to go from chain length \( n \) to \( n + 1 \). However, if \( W_n < W_n^- \), one draws a random number \( \eta \), uniformly distributed between zero and one. If \( \eta < 1/2 \), the configuration is eliminated from the population when one grows the chains from length \( n \) to \( n + 1 \). This “pruning” or “enriching” step has given the PERM algorithm its name. On the other hand, if \( \eta \geq 1/2 \), one keeps the configuration and replaces its weight \( W_n \) by \( 2W_n \). In a depth-first implementation, at each time one deals with only a single configuration until a chain has been grown either to the end of reaching the maximum length or to be killed in between, and handles the copies by recursion. Since only a single configuration has to be remembered during the run, it requires much less memory.

In our implementation, we used \( W_n^+ = \infty \) and \( W_n^- = 0 \) for the first configuration hitting chain length \( n \). For the following configurations, we used \( W_n^+ = CZ_n(c_n/c_\alpha) \) and \( W_n^- = 0.15W_n^+ \), here \( C = 3.0 \) is a positive constant, and \( c_n \) is the total number of configurations of length \( n \) already created during the run. The bias of growing side chains was used by giving higher probabilities in the direction where there are more free next neighbor sites and in the outward directions perpendicular to the backbone, where the second part of bias decreases with the length of side chains and increases with the grafting density. Totally \( 10^5 \sim 10^6 \) independent configurations were obtained in most cases we simulated.

Typical simulations used backbone lengths \( L_b = 32, 64, \) and \( 128, \) \( f = 1 \) (one chain per grafting site of the backbone, although occasionally also \( f = 2 \) and \( f = 4 \) were used), and grafting densities \( \sigma = 1/32, 1/16, 1/8, 1/4, 1/2 \) and \( 1 \). The side chain length \( N \) was varied up to \( N = 2000 \). So a typical bottle brush with \( L_b = 128, \sigma = 1/4 \) (i.e., \( n_c = 32 \) side chains) and \( N = 2000 \) contains a total number of monomers \( N_{\text{tot}} = L_b + n_c N = 64128 \). Figure 2 shows a snapshot configuration of such a bottle brush polymer. Note that most other simulation algorithms for polymers \[65\] would fail to produce a large sample of well-equilibrated configurations of bottle brush polymers of this size: dynamic Monte Carlo algorithms using local moves involve a relaxation time (in units of Monte Carlo steps per monomer \[MCS\]) of order \( N^2 \) where \( z = 2\nu + 1 \) if one assumes that the side chains relax independently of each other and one applies the Rouse model \[82\] in the good solvent regime. \[85\] For \( N = 2000 \) such an estimate would imply that the time between subsequent statistically independent configurations is of the order of \( 10^7 \) \( MCS \), which clearly is impractical. While the pivot algorithm \[82\] would provide a significantly faster relaxation in the mushroom regime, the acceptance rate of the pivot moves quickly.

FIG. 2: Snapshot picture of a bottle brush polymer with \( L_b = 128, \sigma = 1/4, \) and \( N = 2000 \) on the simple cubic lattice. Note that different chains are displayed in different colors to distinguish them, and the periodic boundary condition is undone for the sake of a better visibility in the visualization of this configuration.
deteriorates when the monomer density increases. This algorithm could equilibrate the outer region of the bottle brush rather efficiently, but would fail to equilibrate the chain configurations near the backbone. The configurational bias algorithm \[22\] would be an interesting alternative when the monomer density is high, but it is not expected to work for very long chains, such as \( N = 2000 \). Also, while the simple enrichment technique is useful to study both star polymers \[31\] and polymer brushes on flat substrates \[31\] it also works only for chain lengths up to about \( N = 100 \). Thus, existing Monte Carlo simulations of one-component bottle brushes under good solvent conditions either used the bond fluctuation model \[34\] on the simple cubic lattice applying local moves with side chain lengths up to \( N = 41 \) \[24\] or \( N = 64 \) \[24\] or the pivot algorithm \[24\] with side chain lengths up to \( N = 80 \) \[24\] but considering flexible backbone of length \( L = 200 \). An alternative approach was followed by Yethiraj \[31\] who studied an off-lattice tangent hard sphere model by a pivot algorithm in the continuum, for \( N \leq 50 \). All these studies addressed the question of the overall conformation of the bottle brush for a flexible backbone, and did not address in detail the conformations of the side chains. Only the total mean square radius of gyration of the side chains was estimated occasionally, obtaining \( \langle R_g^2 \rangle \propto N^{1.2} \) or \( \langle R_g^2 \rangle \propto N^{1.36} \) and \( \langle R_g^2 \rangle \propto N^{1.4} \). However, due to the smallness of the side chain lengths used in these studies, as quoted above, these results have to be considered as somewhat preliminary, and also a systematic study of the dependence on both \( N \) and \( \sigma \) was not presented. We also note that the conclusions of the quoted papers are somewhat contradictory.

An interesting alternative simulation method to the Monte Carlo study of polymeric systems is Molecular Dynamics, \[35\] of course. While in corresponding studies of a bead-spring model of polymer chains for flat brushes \[24\] chain lengths \( N \) up to \( N = 200 \) were used, for chains grafted to thin cylinders \[24\] the three chain lengths \( N = 50, 100 \) and 150 were used. For \( N = 50 \), also four values of grafting density were studied. \[24\] Murat and Grest \[24\] used these data to test the scaling prediction for the density profile, Equation \[6\], but found that \( \rho(r) \) is better compatible with \( \rho(r) \propto r^{-0.5} \) rather than \( \rho(r) \propto r^{-0.65} \). However, for \( N = 50 \) the range where the power law is supposed to apply is very restricted, and hence this discrepancy was not considered to be a problem for the theory. \[24\]

Thus, we conclude that only due to the use of the PERM algorithm has it become possible to study such large bottle brush polymers as depicted in Figure \[2\]. Nevertheless, as we shall see in the next section, even for such large side chain lengths one cannot yet reach the asymptotic region where the power laws derived in the previous section are strictly valid.

IV. Monte Carlo Results for One-Component Bottle-Brush Polymers

In Figures \[3\] and \[4\] we present our data for the mean square end-to-end radii and gyration radii components of the side chains. Note that for each chain configuration a separate local coordinate system for the analysis of the chain configuration needs to be used; while the \( z \)-axis is always oriented simply along the backbone, the \( x \)-axis is oriented perpendicular to the \( z \)-axis and goes through the center of mass of the chain in this particular configuration. The \( y \)-axis then also is fixed simply from the requirement that it is perpendicular to both the \( x \)- and \( z \)-axes.

For a polymer mushroom (which is obtained if the
grafting density $\sigma$ is sufficiently small) we expect that all chain linear dimensions scale as $N^\nu$, for sufficiently long chains. Therefore we have normalized all mean square linear dimensions in Figures 3 and 4 by a factor $N^{2\nu}$, using the theoretical value $\nu = \nu_3 \approx 0.588$. However, as we see from Figures 3 and 4 in the range $10 \leq N \leq 10^3$ displayed there, even for the smallest $\sigma$ presented, where a single side chain is simulated, the shown ratios are not constant. This fact indicates that corrections to scaling should not be disregarded, and this problem clearly complicates the test of the scaling predictions derived above. For the largest value of $\sigma$ included ($\sigma = 1/4$), the irregular behavior of some of the data (Figure 3b,c, Figure 4b) indicate a deterioration of statistical accuracy. This problem gets worse for increasing number of side chains $n_c$.

A further complication is due to the residual finite size effect. Figure 5 shows a plot of $R^2_\perp = R^2_x + R^2_y$ divided by $N^{2\nu}$ vs. $\zeta = \sigma N^\nu$, including all data for $N > 5$, and three choices of $L_b$ as indicated (a), or alternatively removing data affected by the finite size of the backbone length via the periodic boundary condition (b). The slope indicated in (b) by the dotted straight line corresponds to the scaling estimate from Equation (21), $2(1 - \nu)/(1 + \nu) \approx 0.519$.

A further complication is due to the residual finite size effect. Figure 5 shows a plot of $R^2_\perp = R^2_x + R^2_y$ divided by $N^{2\nu}$ vs. $\zeta = \sigma N^\nu$. One can recognize that for small $L_b$ but large $N$ and not too large $\sigma$ systematic deviations from scaling occur (Figure 5b), which simply arise from the fact that an additional scaling variable (related to $R^2_\perp^{1/2}/L_b$) comes into play when $R^2_\perp^{1/2}$ no longer is negligibly smaller than $L_b$. While for real bottle brush polymers with stiff backbone effects due to the finite lengths of the backbone are physically meaningful and hence of interest, the situation is different in our simulation due to the use of periodic boundary conditions. The choice of periodic boundary conditions is motivated by the desire to study the characteristic structure in a bottle brush polymer far away from the backbone ends, not affected by any finite size effects. However, if $R^2_\perp^{1/2}$ becomes comparable to $L_b$, each chain interacts with its own periodic images, and this is an unphysical, undesirable, finite size effect. Therefore in Figure 5b, the data affected by such finite size effects are not included. One finds a reasonable data collapse of the scaled mean square end-to-end distance when one plots the data versus the scaling variable $\zeta = \sigma N^\nu$. These results consti-
tute the first comprehensive test of the scaling relations for bottle brush polymers. Equations (21) - (23), and the consistency between the data and the proposed scaling structure in terms of the variable $\zeta$ is indeed very gratifying. On the other hand, it is also evident from Figures 5 and 6 that only a mild stretching of the side chains away from the backbone is observed, and in this region one is still far away from the region of strong stretching, where the simple power laws Equations (8b), (18) and (16) apply. Obviously, the crossover from the simple mushroom behavior (observed for $\zeta = \sigma N^\nu \ll 1$) to the strongly stretched bottle brush (observed for $\zeta \gg 1$) takes at least one decade of the scaling variable $\zeta$. There is a rather gradual and smooth crossover rather than a kink-like behavior of the scaling function. While in the $x$-component at least near $\zeta = 10$ a weak onset of stretching can be recognized, hardly any evidence for the contraction of the $y$ and $z$-components is seen.

In order to test what one would expect if the picture of the chains as quasi-two-dimensional self-avoiding walks were correct, we have also studied single chains grafted to a straight backbone of length $\sigma$, $\sigma = 1, 1/3, 1/5, \ldots 1/63$.

FIG. 6: Log-log plot of $\langle R_{xy}^2 \rangle / N^{2\nu}$ (a), $\langle R_{yy}^2 \rangle / N^{2\nu}$ (b) and $\langle R_{zz}^2 \rangle / N^{2\nu}$ (c) versus the scaling variable $\zeta = \sigma N^\nu$, using the data in Figure 4 but for $N > 50$. The slopes indicated by dashed straight lines illustrate the scaling estimates from Equation (21), $2(1 - \nu)/(1 + \nu) \approx 0.519$ (a), from Equation (23), $-(2\nu - 1)/(\nu + 1) \approx -0.111$ (b), and from Equation (22), $-(2\nu + 1)/(\nu + 1) \approx -1.370$ (c).

FIG. 7: Log-log plot of the mean-square gyration radius components $\langle R_{gg,\text{slit}}^2 \rangle / N^{2\nu_2}$ (a), $\langle R_{yg,\text{slit}}^2 \rangle / N^{2\nu_2}$ (b) and $\langle R_{gg,\text{slit}}^2 \rangle$ (c) versus side chain length $N$ with $\nu_2 = 3/4$. As in Figure 3 only data for $N > 5$ are included. Various choices of $\sigma$ are included. Note that the walls of the slit are located at $z = \pm (\sigma^{-1} + 1)/2$ and are strictly repulsive hard walls. One chain end is fixed at the x-axis at $z = 0$, and since the x-axis represents the backbone if this polymer in a slit is taken as a model of a disk-shaped section of a bottle brush, all sites of the x-axis are excluded from occupation of the monomers of the (side) chain as well.
which are confined between two parallel repulsive infinite walls. The grafting site of the chains was chosen at the site located symmetrically between the confining walls in the slit (if the grafting site is chosen to be the origin of the coordinate system, the confining hard walls occur at \( z = \pm (\sigma^{-1} + 1)/2 \)). Figure 7 gives log-log plots of the gyration radii components of such chains confined to such disk-like slits, which we denote as \( R_{\text{gy, slit}} \). In order to distinguish then from the actual gyration radii components of the side chains in a bottle brush polymer. One can clearly see that \( \langle R_{\text{gy, slit}}^2 \rangle \) scale as \( N^{2\nu_2} = N^{3/2} \) for large \( N \), as it must be. These data are very similar to data for chains confined between repulsive walls without a grafting to a piece of a rigid backbone, as of course. In the corresponding scaling plot (Figure 8), one can see that both \( R_{\text{gy, slit}}^2 \) have the simple crossover scaling behavior

\[
\langle R_{\text{gy, slit}}^2 \rangle \propto N^{2\nu_2} \tilde{f}_y(\sigma N^{\nu})
\]

with \( \tilde{f}_x(\zeta) \propto \tilde{f}_y(\zeta) \propto \zeta^{2(\nu_2 - \nu)/\nu} \) with \( \nu_2 = 3/4 \), as expected, and seen in related previous work. Obviously, although we use in Figures 7 and 8 the same range of \( N \) and \( \sigma \) as in Figures 4 and 5, the behavior is rather different. As expected from our scaling analysis presented above, the confinement that a chain experiences in a bottle brush due to the presence of the other chains is much weaker than the confinement of a chain in the equivalent disk-like sector between confining walls. This
FIG. 10: Radial distribution function $\rho(r)$ plotted vs. $r$, for $N = 500$ (a), $N = 1000$ (b), and $N = 1500$ (c), for various choices of $\sigma$, as indicated. Note that due to the discreteness of the lattice, the number $N(r)$ of monomers in the interval $[r, r + dr]$ is not normalized by the factor $\pi r$ that applies in the continuum limit, but by the number $N_r$ of lattice sites $(x, y)$ satisfying the constraint $r^2 = x^2 + y^2$; i.e., $\sum_r N(r) = N$ and $\rho(r) = N(r)/N_r$. All data refer to $L_b = 128$ and $f = 1$.

Fact is demonstrated very directly in Figure 9, where the ratios $\langle R_{ga}^2 \rangle / \langle R_{ga,slit}^2 \rangle$ are plotted vs. $N$ for the corresponding values of $\sigma$. If the hypothesis of quasi-two dimensional confinement were valid, we would expect these ratios to be constants. Obviously, this is not the case.

As a final point of this section, we discuss the distribution of monomers (Figures 10 and 11) and chain ends (Figures 12 and 13) in the simulated model for the bottle brush polymer. Unlike corresponding radial density distributions for the off-lattice bead-spring model of Murat and Grest, where for small distances close to the backbone a kind of “layering” was observed, we see a rather smooth behavior also for small distances (Figure 10). For larger distances, the behavior is qualitatively very similar. Again we fail to provide a clear-cut evidence for the predicted power law decay, Equation (10). Note, however, that this power law is supposed to hold only in the strong stretching limit, where Equation (8b) is observable (which we do not verify either), and in addition the stringent condition $1 \ll r \ll h$ needs to be obeyed, to have this power law. Although our simulations encompass much longer chains than every previous work on bottle brushes, we clearly fail to satisfy this double inequality.

Turning to the distribution along the backbone (Figure 11), the periodicity due to the strictly periodic spacing of grafting sites is clearly visible. If desired, one could also study a random distribution of grafting sites along...
We still consider a bottle brush polymer with a strictly rigid straight backbone, where at regularly distributed grafting sites (grafting density $\sigma$) side chains of length $N$ are attached, but now we assume that there are two chemically different monomeric species, A and B, composing these side chains with $N_A = N_B = N$. These systems have found recent attention, suggesting the possibility of intramolecular phase separation.\cite{56,57,58} In a binary system pairwise interaction energies $\epsilon_{AA}$, $\epsilon_{AB}$, and $\epsilon_{BB}$ are expected, and consequently phase separation between A and B could be driven by the Flory-Huggins parameter

$$\chi = z_c \epsilon / k_B T, \quad \epsilon = \epsilon_{AB} - (\epsilon_{AA} + \epsilon_{BB}) / 2$$ \hspace{1cm} (28)$$

where $z_c$ is the coordination number of the lattice, like in the Flory-Huggins lattice model of phase separation in

V. Phase Separation in Two-Component Bottle Brushes: Theoretical Background

FIG. 12: Density distributions of chain ends $\rho_e(z)$ plotted vs. $z$, for the same choice of parameters as in Figure 11.

FIG. 13: Radial density distribution of chain ends $\rho_e(r)$ plotted vs. $r$, for the same choice of parameters as in Figures 10-12.

the backbone, of course, but we have restricted attention to the simplest case of a regular arrangement of grafting sites only. The distribution of chain ends $\rho(z)$ exhibits an analogous periodicity for small values of $\sigma$ only, while $\rho_e(z)$ is approximately constant (Figure 12) for larger values of $\sigma$.

Most interesting is the radial distribution of chain ends (Figure 13). One can see an increasing depression of $\rho_e(r)$ for small $r$ when $\sigma$ increases. Again these data are similar to the off-lattice results of Murat and Grest.\cite{22} In no case do we see the “dead zone” predicted by the self-consistent field theory in the strong stretching limit,\cite{21,24} however.
FIG. 14: Schematic description of perfect phase separation of side chains in a cylindrical binary (A, B) bottle brush polymer into a “Janus cylinder” structure, where the A-chains occupy the lower hemicylinder and the B-chains occupy the upper hemicylinder. The interface between B-rich and A-rich phases is assumed to be oriented in the yz-plane. The figure indicates the characterization of this order in terms of a local order parameter, namely the vector $\vec{\psi}(z)$ oriented normal to the interface at every grafting site. The absolute value of this vector characterizes a suitable average of the local phase separation in a disk of the cylinder located at $z$ (see text). For perfect order $\langle |\vec{\psi}(z)| \rangle = 1$ and $\vec{\psi}(z)$ is oriented along the same axis for the whole bottle brush polymer.

However, since the side chains are grafted to the backbone, only intramolecular phase separation is possible here. Actually, the energy parameter $\epsilon$ suffices for dense polymer blends or dense block polymer melts, where no solvent is present. For the problem of intramolecular phase separation in a bottle brush, the solvent cannot be disregarded and, hence, the enthalpy of mixing rather is written as:

$$E_{\text{mix}}/k_B T = \int \frac{dV}{v} \left[ \chi_{AS} \phi_A(\vec{r})\phi_S(\vec{r}) + \chi_{BS} \phi_B(\vec{r})\phi_S(\vec{r}) + \chi_{AB} \phi_A(\vec{r})\phi_B(\vec{r}) \right],$$  \hspace{1cm} (29)

where $v$ is the volume per monomer, $\phi_A(\vec{r})$, $\phi_B(\vec{r})$ and $\phi_S(\vec{r})$ are the local volume fractions of monomers of types A and B, and the solvent density, respectively, and three pairwise interaction parameters $\chi_{AS}, \chi_{BS}$, and $\chi_{AB}$ enter. The latter $\chi_{AB}$ corresponds to the $\chi$-parameter written in Equation (28), while the former two control the solvent quality for polymers A and B, respectively. Of course, using the incompressibility condition

$$\phi_A(\vec{r}) + \phi_B(\vec{r}) + \phi_S(\vec{r}) = 1$$  \hspace{1cm} (30)

the solvent density can be eliminated from the problem (but one should keep in mind that in the free energy density there is an entropy of mixing term $\phi_S(\vec{r}) \ln \phi_S(\vec{r})$ present). In the framework of the lattice model studied here, $v = 1$ and solvent molecules are only implicitly considered, identifying them with vacant sites. For simplicity, the following discussion considers only the most symmetric case, where $\chi_{AS} = \chi_{BS}$, and the numbers of A chains and B chains are equal.

Stepanyan et al. \cite{34} extend Equation (29) by a simple scaling-type argument, stating that the transition from the mixed state to the separated state occurs when the energy of the A-B contacts per side chain, $\Delta E$, is of the order of $k_B T$. They estimate this energy as

$$\Delta E/k_B T \approx Np(\hat{\phi})\chi_{AB},$$  \hspace{1cm} (34)

where $p(\hat{\phi})$ is the probability of the A-B contact, which depends on the average volume fraction $\hat{\phi}$ of the monomers inside the brush. According to the mean field
theory, \( p(\varrho) \propto \varrho \), where \( \varrho = N/h^2 \), \( h \) being the radius of the cylindrical brush. Using \( h \propto N^{3/2} \) (Equation (32)) one finds \( p(\varrho) \propto N^{-1/2} \) and using this result in Equation (34) implies \( \Delta E/k_B T \propto N^{1/2} \chi_{AB} \), and from \( \Delta E/k_B T = 1 \) we recover Equation (32).

The merit of this simple argument is that it is readily extended to other cases: e.g., for a \( \theta \)-solvent, we have \( h \propto N^{2/3} \) and hence \( p(\varrho) \propto N^{-1/3} \), yielding (35)

\[
\chi_{AB}^* \propto N^{-2/3} , \quad \theta - \text{solvent} \tag{35}
\]

For the poor solvent case, the bottle brush should collapse to a cylinder densely filled with monomers, and hence \( h \propto N^{1/2} \), \( \varrho = 1 \), and thus

\[
\chi_{AB}^* \propto N^{-1} , \quad \text{poor solvent} \tag{36}
\]

Note that Equation (36) is the same relation as for a dense bulk polymer blend or block copolymer melt, respectively. \( \frac{1}{2}, \frac{1}{2}, \frac{1}{2}, \frac{1}{2} \)

The situation is more subtle in the good solvent case, however, since there the probability of contact is no longer given by the mean field result \( p(\varrho) \propto \varrho \) but rather by \( \Delta E/k_B T \)

\[
p(\varrho) \propto \varrho^{5/4} N^{-5/8} , \tag{37}
\]

where the Flory approximation \( \nu = 3/5 \) was again used, with \( \varrho \propto N^{-1/2} \) when \( h \propto N^{3/4} \). Equations (34) and (37) now imply

\[
\chi_{AB}^* \propto N^{-3/8} , \quad \text{good solvent} \tag{38}
\]

However, these crude estimates do not suffice to prove that for \( \chi_{AB} > \chi_{AB}^* \) true long range order of this “Janus cylinder” type (Figure 14) is established. Hsu et al. \( \text{[55]} \) suggested that there is also the need to consider variations of the direction of the order parameter \( \vec{\psi}(z) \) along the \( z \)-direction (Figure 15). It was argued that for any finite side chain length \( N \) also the cylinder radius (or brush “height”) \( h \) is finite, and hence the system is one-dimensional. In one-dimensional systems with short range interactions at nonzero temperatures no long range order is possible. The situation depicted in Figure 15 is reminiscent of the one-dimensional XY-model of a chain of spins on a one-dimensional lattice where each spin at site \( i \) is described by an angle \( \varphi_i \), in the xy-plane, with \( 0 \leq i \leq 2\pi \), and where neighboring spins are coupled. This coupling is described by the Hamiltonian

\[
\mathcal{H} = -J \sum_i \cos(\varphi_{i+1} - \varphi_i) = -J \sum_i \vec{S}_i \cdot \vec{S}_{i+1} \tag{39}
\]

when \( \vec{S}_i = (\cos \varphi_i, \sin \varphi_i) \) is a unit vector in the xy-plane. While mean field theory predicts that ferromagnetic order occurs along the chain, for ferromagnetic exchange \( J > 0 \) and temperatures \( T > 0 \) the critical temperature \( T_{c}^{MF} \) which is of the order of \( J/k_B \). An exact solution of this model, Equation (39), shows that \( T_c = 0 \), since ferromagnetic long range order is unstable against long wavelength fluctuations. One can show that the spin-spin correlation function for large \( z = a(j-i) \) decays to zero exponentially fast,

\[
\langle \vec{S}_i \cdot \vec{S}_j \rangle \propto \exp[-z/\xi] , \quad z \to \infty \tag{40}
\]

where \( a \) is the lattice spacing of this spin chain. The correlation length \( \xi \) gradually grows as the temperature is lowered,

\[
\xi = 2a(J/k_B T) \tag{41}
\]

Equation (41) is at variance with mean field theory, which rather would predict \( a \) (the index MF stands for “mean field” throughout)

\[
\xi_{MF} \propto (T/T_{c}^{MF} - 1)^{-\nu_{MF}} , \quad \nu_{MF} = 1/2 . \tag{42}
\]

This critical divergence at a nonzero critical temperature \( T_{c}^{MF} \) is completely washed out by the fluctuations: rather than diverging at \( T_{c}^{MF} \) the actual correlation length \( \xi \) (Equation (41)) at \( T_{c}^{MF} \) still is only of the order of the lattice spacing.

This consideration can be generalized to spin systems on lattices which have a large but finite size in \( (d-1) \) dimensions and are infinite in one space dimensions only. E.g., when we consider an infinitely
long cylinder of cross section $\pi R^2$ we expect that Equations (31), (32) are replaced by the finite size scaling relation

$$\xi \propto (T/T_c - 1)^{-\nu},$$

(44)

where again $k_BT_c \propto J$ (but with a smaller constant of proportionality than that in the relation $k_BT_{cMF} \propto J$), and $\nu$ is the correlation length exponent of the XY model ($\nu \approx 0.67$). Equation (43) describes a smooth crossover of the ferromagnetic correlation length describing spin correlations along the axis of the cylinder from bulk, Equation (42), to a quasi-one-dimensional variation. For $T < T_c$, the correlation length resembles Equation (41), since

$$\xi \approx 2\pi \Gamma(T) R^2/|k_BT| \approx 2\pi (R^2/a)(J/k_BT), \quad T \to 0.$$

(45)

the “helicity modulus” (also called “spin wave stiffness”) $\Gamma(T)$ is of order $J$ for $T \to 0$ and shows a critical vanishing as $T \to T_c$ from below, in the thermodynamic limit $R \to \infty$. However, for finite $R$ there is a finite size rounding of this singularity of $\Gamma(T \to T_c)$, such that $\Gamma(T = T_c)$ is of order $1/R$, and hence a smooth crossover to Equation (43) occurs near $T_c$. Figure 10 gives a qualitative account of this behavior. For more details of this finite size crossover we refer to the literature.\textsuperscript{104} \textsuperscript{105} \textsuperscript{106} But we suggest a qualitatively similar behavior for the domain size $\xi$ of segregated A-rich and B-rich domains in binary bottle brush polymers. So, when we study the correlation function of the order parameter considered in Equation (31)

$$\psi(z) = \langle \tilde{\psi}(z') \cdot \tilde{\psi}(z') \rangle \propto \exp(-z^2/\xi^2),$$

(46)

we expect that the correlation length $\xi_\psi$ describing the local phase separation in the direction along the backbone of the bottle brush polymer remains of order unity as long as $\chi_{AB}^\alpha$ exceeds $\chi_{AB}^{\alpha-1}$ distinctly. For $\chi_{AB}$ near $\chi_{AB}^{\alpha-1}$ we expect that $\xi_\psi$ becomes of order $h$, the radius of the bottle brush. For $\chi_{AB} \gg \chi_{AB}^{\alpha-1}$, we expect $\psi(z) \sim h^2 \chi_{AB}$, by analogy with Equation (45). Unfortunately, the test of those predictions even in the poor solvent case where $\chi_{AB}^{\alpha-1}$ is largest, is rather difficult, since the prefactor in the relation $\chi_{AB} \times 1/N$ is unknown.

VI. Monte Carlo Results for Binary Bottle Brush Polymers

We use the same lattice model as considered before in our Monte Carlo study of the chain conformations of one-component bottle brush polymers, but now in the construction of the weights $W_\alpha(n)$ we have to take into account that the partition function now is

$$Z = \sum_\alpha q^{m_{AA} + m_{BB}} q_{AB}^{m_{AB}}$$

(47)

with (remember that we restrict attention to the choice $\epsilon_{AA} = \epsilon_{BB}$)

$$q = \exp(-\epsilon_{AA}/k_BT), \quad q_{AB} = \exp(-\epsilon_{AB}/k_BT).$$

(48)

In Equation (17) the numbers of non-bonded occupied nearest-neighbor monomer pairs AA, BB and AB are denoted as $m_{AA}, m_{BB}$ and $m_{AB}$, respectively. Note that the sum in Equation (17) extends over all possible configurations $\{\alpha\}$ of the bottle brush polymer. The choice $q = q_{AB} = 1$ corresponds to the previously studied one-component bottle brush under good solvent conditions, while the choice $q = q_{AB} > 1$ corresponds to variable solvent quality for the one-component brush (note that $q = q_{AB}$ means $\chi = 0$, Equation (28)), and also $\chi_{AB}$ which is proportional to $\chi$ then vanishes: this means there is no chemical incompatibility between A and B any longer, no physical difference between A and B exists any more). From previous work on single chains\textsuperscript{106} we know that the $\theta$-point occurs for $q_\theta = 1.3087$. Therefore we varied $q$ in the range $1 \le q \le 1.5$; $q = 1.5$ hence falls in the regime of poor solvent quality already. Of course, in order to have rather compact configurations of cylindrical bottle brushes a choice of much larger $q$ would be desirable. However, the efficiency of the PERM algorithm quickly deteriorates with increasing $q$: for $q = 1.5$ we encounter already for rather small values of the side chain length $N$ such as $N = 18$ and a backbone length of $L_b = 64$ huge statistical fluctuations. The total size of the bottle brush polymer under poor solvent conditions reached here, $N_{\text{tot}} = N\sigma L_b + L_b = 1216$, is almost two orders of magnitude smaller than the maximal size studied under good solvent conditions! However, all known simulation algorithms for polymers suffer from difficulties of equilibration in the limit of very dense configurations.\textsuperscript{84} \textsuperscript{85} \textsuperscript{86}

Since we are mostly interested in the high grafting limit ($\sigma = 1$, so the number of side chains $n_c = \sigma L_b = L_b$) in the PERM algorithm where all side chains grow simultaneously we use a bias factor such that side chains are grown with higher probability in the directions perpendicular to the backbone. This additional bias (which is not present in the standard Rosenbluth\textsuperscript{19} and PERM\textsuperscript{104} methods) must be taken into account by suitable weight factors. About $10^6$ independent configurations were typically generated.

Figures 17-19 now show typical results for the good solvent case ($q = 1$) but varying the parameter $q_{AB}$ controlling the chemical incompatibility. The visual inspection of the configurations (Figure 17) reveals little influence of $q_{AB}$; however, and this observation is corroborated by the more quantitative analysis: the average
FIG. 17: Snapshot pictures of bottle brush configurations for $L_b = 64$, $q = 1$, $N = 18$, $\sigma = 1$ and three choices of $q_{AB}$. $q_{AB} = 1.0$ (a), $q_{AB} = 0.4$ (b) and $q_{AB} = 0.1$ (c). Monomers A, monomers B, and a straight rigid backbone are shown in black, light gray, and white colors, respectively.

FIG. 18: (a) Average number of AB pairs per monomer $\langle m_{AB} \rangle / (Nn_c)$ plotted vs. $q_{AB}$ for side chain lengths $N = 6$, 12, and 18. All data refer to $\sigma = 1$, $L_b = 64$. (b) Specific heat per monomer, $c_v / (Nn_c)$ plotted vs. $q_{AB}$ for $N = 6$, 12 and 18.

FIG. 19: (a) Radial density distribution $\rho(r)$ plotted vs. $r$ for $L_b = 64$, $N = 18$, $q = 1$, $\sigma = 1$, $f = 1$ and various $q_{AB}$. (b) Normalized transverse mean square end-to-end distance $(\langle R_x^2 \rangle + \langle R_y^2 \rangle) / N^{2\nu}$ plotted vs. $N$, for $L_b = 64$, $q = 1$, $\sigma = 1$, $f = 1$, and three choices of $q_{AB}$ as shown.
FIG. 20: Vectors $\vec{R}_n^{(1)}$ from the grafting site $n$ to the $y$-component of the center of mass of the respective chain, and corresponding unit vectors (denoted by arrows). For a perfectly phase separated structure with the interface between A and B being the $yz$ plane, for $\alpha = A$ all unit vectors point along the negative $x$-axis and for $\alpha = B$ all unit vectors point along the positive $x$-axis.

FIG. 21: Correlation function $C_n$ measuring local “Janus cylinder”-type phase separation plotted versus $n$, for $N = 6$ (a), 12 (b), and 18 (c). Various choices of $q_{AB}$ are included, as indicated in the figure. Curves show fits to Equation (38). All data refer to good solvent conditions ($q = 1$), and $L_b = 64$, $\sigma = 1$, $f = 1$.

FIG. 22: Distribution $P(\theta)$ of the angle $\theta$ between the vectors towards the centers of mass of subsequent (unlike) side chains plotted vs. $\theta/\pi$, for $N = 12$ (a) and $N = 18$ (b). Various choices of $q_{AB}$ are included, as indicated.

number of A-B pairs per monomer is extremely small (Figure 15) even for $q_{AB} = 1$, and hence not much enthalpy could be won if A-chains and B-chains avoid each other: due to the excluded volume interaction, very few nearest neighbor contacts between any non-bonded monomers occur in our bottle brush model. For $N = 18$ and $q_{AB} = 1$ the total number of AB contacts per chain is only about 1.4, and increases with increasing $N$ only very slowly. So for the range of side chain lengths accessible in our work, no phase separation should be expected. In the specific heat one does see a weak peak near $0.2 \leq q_{AB} \leq 0.4$, but the height of this peak decreases very strongly with increasing $N$. Furthermore does neither the peak position shift with increasing $N$ (as one would expect from Equation 38), if this peak would be a rounded precursor of the phase transition that should occur at $\chi_{AB}$ in the limit $N \to \infty$) nor does the peak width decrease with increasing $N$. Thus, it is clear that this peak is not an indicator of a “Janus-cylinder”-type phase separation in the bottle brush: rather we interpret it as a Schottky-type anomaly, expected from the fact that in our model of alternatingly grafted A- and B-chains at a straight line backbone with coordinates $(0, 0, z)$ in the immediate environment of the backbone (e.g. at lattice sites $(x, y, z) = (\pm 1, 0, 0)$ or $(0, \pm 1, 0)$) there is a nonzero a-priori probability of $1/4$ that between the first monomer of the chain grafted at $z$ and the first monomer of the chain grafted at $z + 1$ a nearest-neighbor contact
occurs. The finite energy from this local contacts near
the backbone gives rise to the peak in the specific heat.

Also the radial density profile (Figure 19a) shows little
effects of varying $q_{AB}$, and there is also no effect in
the gyration radius component $\langle R_{g,y}^2 \rangle = \langle R_{g,x}^2 \rangle + \langle R_{g,y}^2 \rangle$ of the side chains, although a weak increase occurs in
the corresponding component of the end-to-end distance
(Figure 19b). In the latter figure, one can see for small
$N$ an even-odd oscillation, but this lattice effect clearly
has died out for $N > 10$.

In order to test for correlations measuring local phase
separation along the backbone, Equation (49) is somewhat
cumbersome to implement numerically, since for
each $z$ one has to find the direction of $\vec{\psi}(z)$ from the
condition that $|\vec{\psi}(z)|$ is maximal (cf. Equation (31)).
A simpler and similar correlation function has been defined
from the vectors pointing from the grafting site $i$ to the
center of mass of the respective side chains. Projecting
this vector into the xy-plane and defining an unit vector
$\vec{S}_i^\alpha$ ($\alpha = A$ or $B$) along this projection (Figure 20) we
define a correlation function $C_n$ as follows

$$C_n \equiv \langle \vec{S}_i^A \cdot \vec{S}_{i+n}^A \rangle + \langle \vec{S}_{i+1}^B \cdot \vec{S}_{i+1+n}^B \rangle / 2.$$  (49)

Here we have explicitly incorporated the alternating
grafting ABAB... of side chains along the backbone. The
average $\langle \ldots \rangle$ in Equation (49) includes an averaging over
all sites $\{i\}$ on which A chains are grafted, in order to
improve the statistics. If perfect long range order occurs, as
implied in Figure 20, we clearly have $C_n = 1$ independent
of $n$, while for the case of short range order, we expect
$C_n \propto \exp(-n/\xi)$. Actually, considering the fact that we
use a periodic boundary condition, we have analyzed our
numerical data in terms of the ansatz

$$C_n \propto \{\exp(-n/\xi) + \exp(-L_b - n/\xi)\}. \quad (50)$$

Figure 21 shows our data for $C_n$ for the three choices of
$N$: indeed we recognize that $C_n$ decays to zero with increasing $n$, but the increase does get slower with increasing
side chain length $N$. The scale of this correlation effect clearly increases with decreasing $q_{AB}$. While for
$N = 6$ the correlation length $\xi$ hardly depends on $q_{AB}$,
for large $N$ a slight increase of $\xi$ with decreasing $q_{AB}$ is
suggested.

In an earlier simulation study of phase separation in
binary bottle brushes, it was suggested to quantify the
degree of separation by considering the distribution of the
polar angle $\phi_i$ from the axis to monomer $\ell$. Defining
a variable $\sigma^A_\ell$, which is $\sigma^A_\ell = 1$ if monomer $\ell$ is of type
A and zero otherwise, and similarly $\sigma^B_\ell$, de Jong and ten
the specific heat (Figure 23b) are hardly distinguishable from the good solvent case. Also the radial density profile (Figure 23b) exhibits only minor differences, slightly larger densities occur inside the brush than in the good solvent cases, and the transverse component of the end-to-end distance does not exhibit much additional stretching, when $q_{AB}$ decreases (Figure 23b). The distribution $P(\theta)$ is somewhat less flat near $\theta = \pi$ (Figure 23b) than in the good solvent case (Figure 22).

Also the correlation function $C_n$ shows again an exponential decay with $n$ (Figure 25b), the correlation length $\xi$ being rather similar to the good solvent case (Figure 21). Since one might argue that our definition of a correlation function as given in Equation (49) is not the optimal choice, and there might occur larger correlation lengths for a more clever choice of a correlation function, we tried a different choice which is also easy to compute. Namely, in the xy-plane at the index $i$ of the z-coordinate we determine the center of mass of the monomers of type $\alpha = A$ or $B$ in that plane (the choice of $\alpha$ is dictated by the type of chain grafted at $z = i$). Then we introduce an unit vector $\hat{S}^i_{\alpha}$ from the z-axis in the direction towards this center of mass. In terms of these unit vectors, which then no longer distinguish from which chain the monomers $\alpha$ in the $i$'th xy-plane are coming, we can again apply the definition, Equation (49), to derive a correlation function. This correlation function is shown in Figure 25b. One sees that the qualitative behavior of both types of correlation functions is the same, but the decay of this second type of correlation function even is slightly faster than that of the correlation function used previously. Since normally, when one studies problems involving a phase transition, the correlation length of the order parameter is the largest correlation length that one can find in the system, the previous definition (focusing on the location of the center of mass of the individual side chains) seems preferable to us. It is possible of course that such differences between different ways of measuring correlations along the backbone remain so pronounced for small $N$ only, where the correlation lengths are only of the order of a few lattice spacings, and hence are less universal and depend on the details of the studied quantity.

We now turn to the poor solvent case (Figures 26-29). Already the snapshot picture of the bottle brush polymer conformations (Figure 26) reveals that now the side chains adopt much more compact configurations, due to the collapse transition that very long single chains would otherwise undergo (Figure 18). The specific heat (Figure 27h) now the specific heat (Figure 27h) gives a hint for the occurrence of a phase transition: in fact, these data still look like in the good solvent case, Figure 18. Also the distribution $P(\theta)$ and the variation of $\langle R_n^2 \rangle / \langle R_p^2 \rangle / N^{2/3}$

Brinke introduced a function

$$P(\phi) = \sum_\ell \sum_{\ell'} (\sigma_\ell^A \sigma_{\ell'}^B + \sigma_\ell^B \sigma_{\ell'}^A) \delta(|\varphi_i - \varphi_j| - \phi)$$

and studied $P(\phi)$ varying $\chi_{AB}$. However, it turns out that $P(\phi)$ always has a rather complicated shape, and its dependence on $\chi_{AB}$ is rather weak. Thus we investigated a related but somewhat different function, namely the histogram $P(\theta)$ of the angle $\theta$ between the vectors from the axis to the centers of mass of subsequent unlike side chains (Figure 22). We see in this distribution $P(\theta)$ also only a rather small dependence on $\chi_{AB}$, however: while for $q_{AB} = 1$ this distribution is essentially structureless for $\pi/2 \leq \theta \leq 3\pi/2$, for small $q_{AB} = 1$ a rather pronounced peak at $\theta \approx \pi$ develops, indicating a preference of antiparallel orientation of subsequent side chains. However, we feel that such indicators as $P(\phi)$ or $P(\theta)$ are sensitive only to the presence of short range order rather than long range order, and hence we shall focus on the correlation function $C_n$ in the following.

Next we focus on binary bottle brushes in a Theta solvent ($q = 1.3087$). Figures 23-25 show that the results are not very different from the good solvent case: the average number of AB pairs per monomer (not shown) and

![Figure 25](image-url)
with $N$ and $q_{AB}$ are qualitatively similar to the results found for good solvents and Theta solvents, and therefore are not shown here. More interesting is the monomer density profile (Figure 28). While for $N = 6$ it still has the same character as in the previous cases, for $N = 12$ and $N = 18$ we recognize an inflection point. In fact, for a collapsed polymer bottle brush we expect a profile exhibiting a flat interior region at melt densities ($\rho(r)$ near to $\rho = 1$), then an interfacial region where $\rho(r)$ rapidly decreases towards zero; in the ideal case reached for $q \to \infty$, the profile should even be a Heaviside step function, in the continuum limit, $\rho(r) = \theta(h - r)$. Obviously, for $q = 1.5$ we are still far from this behavior even for $N = 18$, but we can identify an interface location at about $r_{int} \approx 3.5$, and in the interior of the cylindrical bottle brush (for $r < r_{int}$) the monomer density corresponds at least to a concentrated polymer solution.

Figure 29 then shows again plots of $C_n$ vs. $n$, and the resulting fits to Equation (50). The behavior is qualitatively similar to the previous cases of good and Theta solvents again, but now the decay of $C_n$ with $n$ is clearly much slower, indicating a distinctly larger correlation length. This result corroborates the qualitative observation made already on the basis of the snapshot pictures, Figure 26 and quantifies it.

Our findings on the local character of phase separation in binary bottle brush polymers are now summarized in Figure 30 where plots of the inverse correlation length $1/\xi$ versus the inverse Flory-Huggins parameter $z_c / \chi = k_B T / (\epsilon_{AA} - \epsilon_{BB}) = 1 / \ln[q/q_{AB}]$ are shown (cf. Equation 28) and remember our choice $\epsilon_{AA} = \epsilon_{BB}$). This choice of variables is motivated by the analogy with the XY model in cylindrical geometry, Equation (15). on the basis of this analogy, we would expect that $\xi^{-1} \propto T$, i.e. we expect straight lines that extrapolate through zero as $T \to 0$.

Figure 30 demonstrates that this analogy is not perfect. Rather the data are compatible with an extrapolation

$$
\xi^{-1}(N, T) = \xi^{-1}(N, q, 0) + C_N(q)T \quad , \quad T \to 0 ,
$$

where $C_N(q)$ is a coefficient that decreases with increasing $N$ and depends on solvent quality and with a nonzero intercept $\xi^{-1}(N, q, 0)$ implying that even in the ground state ($T = 0$) there is lack of long range order!

A very interesting question concerns the dependence of $\xi(N, T)$ on chain length. Figure 31 presents a plot of $\xi^{-1}(N, q, 0)$, as estimated from extrapolation of the data shown in Figure 30 to $q_{AB} = 0$, as a function of $1/N$. Indeed the data are compatible with a relation $\xi^{-1}(N, q, 0) \propto 1/N$, implying long range order for $N \to \infty$ in the ground state. In principle, carrying out the same extrapolation at nonzero temperature and testing for which temperature range $\xi^{-1}(N \to \infty, T)$ starts to be nonzero, one could obtain an estimate for the critical point of intramolecular phase separation, that should occur (and then is well defined) in the limit of infinite side chain length, $N \to \infty$. Unfortunately the accuracy of our estimates for $\xi(N, T)$ does not warrant such an analysis.

The reason for this surprising persistence of disorder at low temperatures is configurational entropy, of course. As long as $q < \infty$, the bottle brush polymer is not fully compact, and when the density is small enough inside the bottle brush (as it still is in the cases shown in Figure 28), the two types of chains A, B can avoid making binary contacts (as is evident from Figures 18 and 27): $\langle m_{AB} \rangle \to 0$ as $q_{AB} \to 0$. Hence there is a per-
FIG. 27: (a) Average number of AB pairs per monomers, \(< m_{AB} > / (N n_c)\), plotted vs. \(q_{AB}\) for side chain lengths \(N = 6, 12,\) and 18. All data refer to \(\sigma = 1.5, L_b = 64\). (b) Specific heat per monomer, \(C_v / (N n_c)\), plotted vs. \(q_{AB}\) for \(N = 6, 12,\) and 18.

FIG. 28: Radial density profile \(\rho(r)\) plotted vs. \(r\) for \(L_b = 64, q_{AB} = 0.1, q = 1.5, \sigma = 1, f = 1,\) and three choices of \(N = 6, 12,\) and 18.

FIG. 29: Same as Figure 21 but for poor solvent conditions \((q = 1.5)\); for \(n = 6\) (a), \(n = 12\) (b), and \(n = 18\) (c).

Thus a (coarse-grained) cross section of the bottle brush in the xy-plane is NOT a circle, separating A-rich and B-rich regions by a straight line, but rather looks like the number 8, i.e. a dumbbell-like shape, where a (more or less circular and more or less compact A-rich region) occurs for \(x < 0\), a similar B-rich region occurs for \(x > 0\), but no monomers (apart from the backbone monomer) occur at the y-axis at \(x = 0\). The orientation of the x-axis can fluctuate as one moves along the z-axis, and unlike Figure 15 (twisting an interface in a cylinder along the z-axis clearly involves an energy cost, and this is described by the helicity modulus in the XY-model analogy, Equation (45)) the free energy cost of this structural distortion is outweighed by the configurational entropy gain, at least for \(q\) and \(N\) not too large. It is an unresolved question whether some critical value \(q_c(N)\) exists, where \(\xi^{-1}(N, q, 0)\) vanishes, and a long range ordered ground
state occurs. Another unresolved question is, whether (another?) critical value $q_c'(N)$ exists, where the character of the ground state changes such that the local cross section of the binary bottle brush changes from an 8-shaped to a circular density distribution. Actually, the problem of alternatingly grafting A-chains and B-chains along a line is equivalent to grafting symmetric AB diblock copolymers along a line, such that the junction points of the diblocks form a straight line. This problem is the lower-dimensional analog of diblocks grafted with their junction points to the flat interface between an unmixed binary (A,B) homopolymer blend. For this problem it is well-known (see Werner et al. [104] for references) that the shape of the diblocks is dumbbell like, the A-block being stretched away from the interface, in order to be embedded in the A-rich phase underneath like, and the B-rich block also being stretched away from the interface, in order to be embedded in the B-rich phase above the interface.

As a consequence of our discussion, we call into question the idea of the “Janus cylinder”-type phase separation [102, 103] and propose as an alternative possibility (Figure 32) the “double cylinder” (with cross section resembling the number 8). Which of these cross-sectional structures occur will depend on the interaction parameters $\epsilon_{AA} = \epsilon_{BB}$, and $\epsilon_{AB}$, of course. If the strength of the attractive interactions $|\epsilon_{AA}| = |\epsilon_{BB}|$ exceeds the strength of the repulsion $|\epsilon_{AB}|$ sufficiently much, it is clear that for $T \to 0$ the Janus cylinder type phase separation will occur, while in the opposite limit, when $|\epsilon_{AB}|$ exceeds $|\epsilon_{AA}| = |\epsilon_{BB}|$ sufficiently much, the double cylinder geometry will win. In the macroscopic continuum limit a comparison of the respective surface energies would imply that the double cylinder geometry, which avoids an AB interface, but requires for the same volume taken by A and B monomers a surface area of pure A and B that is larger by a factor of $\sqrt{2}$ than for the “Janus cylinder” (Figure 32), becomes energetically preferable for

$$\epsilon_{AB} > (\sqrt{2} - 1)\pi|\epsilon_{AA}| = 1.301|\epsilon_{AA}| \quad (53)$$

Since in the present work we consider the limit $q_{AB} = \exp(-\epsilon_{AB}/k_BT) \to 0$ at fixed $q = \exp(-\epsilon_{AA}/k_BT)$, it is clear that in our case Equation (53) is fulfilled. However, for the "most symmetric" choice of interaction parameters, $\epsilon_{AB} = -\epsilon_{AA} = -\epsilon_{BB}$, the conclusion would be different. For lattice models Equation (53) is questionable since very compact configurations of collapsed

---

**FIG. 30:** Plot of the inverse correlation length $1/\xi$ versus the inverse Flory Huggins parameters, $z_c/\chi$, for good solvent conditions ($q = 1$), case (a), Theta solvent conditions ($q = 1.3087$), case (b), and poor solvent conditions ($q = 1.5$), case (c). Data for three chain lengths $N = 6, 12, 18$ are included throughout. In several cases two or three choices of backbone lengths $L_b = 32, 48$ and 64 are included as well. All data refer to the choice of one grafted polymer per grafting site ($\sigma = 1$).

**FIG. 31:** Inverse correlation length plotted vs. $1/N$, in the limit $q_{AB} \to 0$, for poor solvent conditions ($q = 1.5$), and three choices of the backbone length $L_b$, to exclude that the data are strongly affected by finite size artifacts. The straight line indicates that the data are compatible with a simple linear relation, $\xi^{-1}(N,0) \propto 1/N$. 

— Additional content from the document. —
polymers must respect the lattice structure, and different geometrical factors, depending on the type of the lattice, in the inequality Equation (53) may occur.

VII. Conclusions and Outlook

In this article, we have restricted attention exclusively to static conformational properties of very long bottle brush polymers with a rigid backbone. We feel that this “simple” limiting case needs to be understood first, before the very interesting extension to the case of flexible or semiflexible backbones, or the question of the crossover between a bottle brush polyarm being deuterated, while all remaining arms of the polymer remain protonated, for example. Thus the latter two problems were not at all considered in this paper, and hence we also do not wish to comment on the recent controversy [12, 13, 14] concerning the correct interpretation of experiments on the overall linear dimensions of bottle brush polymers.

As discussed in the first part of the paper, one can find in the literature rather diverse concepts about the conformations of the side chains of a bottle brush polymer under good solvent conditions and high grafting density. One concept assumes that the cylindrical volume that the bottle brush occupies can be partitioned into disks, such that each disk contains just one polymer chain. A simple geometric consideration, reviewed in the first part of the present paper, then yields the following predictions for the linear dimensions of the chain, as a function of grafting density \( N \) and side chain length \( N^{3/4} R_{g\xi} \propto \sigma^{1/4} N^{3/4}, R_{gy} \propto \sigma^{1/4} N^{3/4}, R_{gz} \propto \sigma^{-1} \). (54)

Remember that we choose the z-axis as the direction of the rigid backbone, the x-axis is oriented normal to the z-axis towards the center of mass of the chain, and the y-axis is perpendicular to both x- and z-axes. Thus the chain conformation has a quasi-two dimensional character, and there is no stronger stretching of a chain in radial direction than in tangential direction, since \( R_{gy}/R_{g\xi} = \text{const} \) (independent of both \( N \) and \( \sigma \)).

Clearly, this quasi-two-dimensional picture is not very plausible, and more popular is an extension of the Daoud-Cotton blob picture for star polymers to the present case. While for a star polymer the blob radius simply increases proportional to the distance from the center, \( r \), and there is no geometrical difficulty to densely pack the conical compartments resulting from dividing a sphere into \( f \) equal sectors, such that each sector contains a single arm of the star, with a sequence of spheres of increasing size, it has been argued in the literature that for cylindrical geometry the blob radius scales as \( \xi(r) \propto [r/\sigma]^{1/2} \). While in the literature no mentioning of a non-spherical blob shape (or, equivalently anisotropic local screening of the excluded volume interaction) is found, we have emphasized here the geometrically obvious fact that a dense filling of space with blobs in the cylindrical geometry appropriate for a bottle brush requires that the blobs have the shape of ellipsoids with three different axes, proportional to \( r, (r/\sigma)^{1/2} \), and \( \sigma^{-1} \), respectively. While this picture does not alter the prediction for the stretching of the chain in the radial x-direction found in the literature, \( R_{gy} \propto \sigma^{-1} [1+(1+\nu)/N^{3/4}] \approx \sigma^{1/4} N^{3/4} \), different predictions result for the other two linear dimensions. While the regular Daoud-Cotton picture would yield for \( R_{gy} \) the size of the last blob, \( R_{gy} = [\xi(r = h)] = [h/\sigma]^{1/2} \propto \sigma^{-1} [1+(1+\nu)/N^{3/4}] \approx \sigma^{-3/8} N^{3/8} \), we find instead

\[
R_{gy} \propto \sigma^{-(2u-1)/(1+\nu)} N^{3u/(2u+2)} \approx \sigma^{-1/16} N^{9/16}, \quad (55)
\]

\[
R_{gz} \propto \sigma^{-(2u-1)/(1+\nu)} N^{-5u/(2u+2)} \approx \sigma^{5/8} N^{3/8}. \quad (56)
\]

Equations (55) and (56) make use of both the anisotropic blob linear dimensions and random walk-type arguments (cf. Equations (13)-(28) and are new results, to the best of our knowledge.

Also the crossover scaling towards mushroom behavior has been considered, Equations (20)-(23), and Monte Carlo evidence for this crossover scaling description was obtained, from extensive work using the PERM algorithm. Although rather large bottle brushes were simulated (backbone length \( L_b \) up to \( L_b = 128 \), avoiding free end effects by periodic boundary conditions, side chain length up to \( N = 2000 \) for grafting density \( \sigma = 1 \), see Figure 3), it was not possible to reach the asymptotic regime of strong side chain stretching where Equations (55) and (56) hold, however. One reason why for moderate grafting densities even fairly long side chains can avoid each other with small significant amount of stretching is the fact that the natural shape of a self avoiding walk configuration is an elongated ellipsoid, with three rather different eigenvalues of the gyration tensor. So side chains can to a large extent avoid each other by orienting themselves such that the longest axis of the ellipsoid is oriented in the radial x-direction and the smallest axis in the backbone z-direction. This implies that very large values of \( \sigma aN^\nu \) are needed to obtain significant stretching. This difficulty to verify any such scaling laws in our simulations, which were only able to explore the onset of stretching away from simple mushroom-type behavior, of our knowledge.
suggests that no such scaling behavior should be observable in the experiments as well: given the empirical fact that one bond of a coarse-grained lattice model corresponds to \( n = 3 - 5 \) chemical monomers, it is clear that the experimentally accessible side chain lengths do not exceed those available in our simulation. Thus, scaling theories of bottle brushes are unfortunately of very restricted usefulness for the interpretation of either experiments or simulations. The only firm conclusion about the theories mentioned above that we like to make is that there is no evidence whatsoever for the quasi-two-dimensional picture, since we do see a decrease of \( R_{gy}/R_{gx} \) with increasing \( N \).

Turning to the problem of intramolecular phase separation in binary (AB) bottle brush polymers, we have examined the proposal that a “Janus cylinder”-type phase separation occurs. This idea is questionable for several reasons (i) In a quasi-one-dimensional system, no sharp phase transition to a state with true long range order can occur; at most one can see a smooth increase in the corresponding correlation length, as the temperature is lowered (or the incompatibility between A and B is enhanced, respectively). Thus we have defined suitable correlation functions and studied the variation of the corresponding correlation length as function of the chain length \( N \) and the parameter \( q_{AB} = \exp[-\epsilon_{AB}/k_BT] \) controlling the incompatibility (\( \epsilon_{AB} \) is the repulsive energy encountered when two neighboring lattice sites are occupied by monomers of different kind). Three choices of solvent quality (taken symmetric for both A and B through the choice \( \epsilon_{AA} = \epsilon_{BB} \)) were considered, \( q = \exp(-\epsilon_{AA}/k_BT) = 1 \) (good solvent), \( q = 1.3087 \) (Theta solvent) and \( q = 1.5 \) (poor solvent). It was found that in all cases the correlation length suited to detect Janus-cylinder type ordering increases rather weakly as \( q_{AB} \to 0 \), approaching finite values even for \( q_{AB} = 0 \), for finite side chain length \( N \), while for \( N \to \infty \) an infinite correlation length is compatible with the data. No evidence for the predicted critical points and their scaling behavior with \( N \) (Equations) could be detected, however. The gradual establishment of a local phase separation lacking a sharp transition is compatible with observations from a previous simulation, however. (ii) Depending on the relation between the energy parameters \( \epsilon_{AA} \) and \( \epsilon_{AB} \) (cf. Equation), the “local” phase separation (considering a slice of suitable thickness perpendicular to the backbone of the bottle brush to obtain suitable coarse-grained densities \( \rho_A, \rho_B \) on mesoscopic scales) for temperatures \( T \to 0 \) may have two different characters (Figure): the “Janus cylinder”, which contains an interface between A-rich and B-rich phases, competes with the “double cylinder”. In the latter structure, there is no extended AB interface, A-chains and B-chains meet only in the immediate vicinity of the backbone where they are grafted. Thus, the coarse-grained density distribution under poor solvent conditions in a slice has the shape of the number 8, where in the upper part of the 8 we have the B-rich phase and in the lower part we have the A-rich phase. Of course, when we orient the x-axis (Figure) such that it is parallel to the vector connecting the center of mass of the A-rich region to the center of mass of the B-rich region in the slice, the orientation of the x-axis for both structures in Figure can randomly rotate when we move along the backbone (z-direction) due to long wavelength fluctuations, cf. Figure and hence the comments about finite correlation lengths of this phase separation apply here as well. Actually, the numerical results of the present Monte Carlo simulations give clear evidence that local phase separation of “double cylinder”-type rather than “Janus cylinder” type is observed, since the number of AB-contacts tends to zero.

FIG. 32: Possible ground structures of binary bottle brush polymers, showing the cross section perpendicular to the backbone (dot) in the continuum limit, for the symmetric case \( \epsilon_{AA} = \epsilon_{BB} \). Left part shows a double cylinder, each cylinder has a radius \( h \). Right part shows a Janus cylinder (with the same volume this requires a radius \( h' = \sqrt{2}h \). The surface energy cost of the double cylinder is \( 4\pi h L_b \epsilon_{AA} \), while the surface energy cost of the Janus cylinder is \( 2\sqrt{2}h L_b (\epsilon_{AA} + |\epsilon_{AB}|) \). (b) Possible generalizations of the double cylinder structure to the asymmetric case \( \epsilon_{AA} \neq \epsilon_{BB} \). The left part assumes \( \epsilon_{BB} = 0 \), so the B chains are in good solvent, only the A-chains collapse. The right part assumes \( |\epsilon_{BB}| > |\epsilon_{AA}| \), so that the collapsed B-rich cylinder is denser than the A-rich cylinder.
Thus, varying the solvent quality and chemical incompatibility, one can influence the character of local intramolecular phase separation, and one can control the correlation length over which the vector characterizing either interface orientation or the axis of the local dumbbell is oriented in the same way along the $z$-axis. Of course, in real systems one must expect that the solvent quality for the two types of chains will differ (Figure 32b). Then asymmetric $S$-shaped local structures will result: e.g., if the solvent is a good solvent for B but a poor one for A, the incompatibility between A and B is very high, we expect a structure where the A-chains are collapsed in a cylinder with the backbone on the cylinder surface, and from there the B-chains extend into the solution like a cylinder with the backbone on the cylinder surface, and calculate the normalized correlation function $C_z$ of $\delta M(z) = M(z) - N$ along the backbone,

$$C_z = \langle \delta M(i + z)\delta M(i) \rangle / \langle \delta M(i) \rangle^2.$$  \hspace{1cm} (57)

Here the average $\langle \ldots \rangle$ includes an averaging over all sites $\{i\}$ on which chains are grafted, in order to improve the statistics. In Figure 33 we see that this correlation actually is negative for $2 \leq z \leq 8$, indicating some tendency to pinned cluster formation.

Before one can try to understand the real two-component bottle brush polymers studied in the laboratory, two more complications need to be considered as well: (i) the flexibility of the backbone; (ii) random rather than regular grafting along the sequence. While the effects due to (i) were already addressed to some extent in an earlier simulation, \[57\], randomness of the grafting sequence has not been explored at all. However, in the study of binary brushes on flat substrates it has been found that randomness in the grafting sites destroys the long range order of the micro-phase separated structure, that is predicted to occur \[113\] for a perfectly periodic arrangement of grafting sites. In the one-dimensional case, we expect the effects of quenched disorder in the grafting sites to be even more dominant than in these two-dimensional mixed polymer brushes. Hence, it is clear that the explanation of the structure of one- and two-component bottle brush polymers still is far from being complete, and it is hoped that the present article will motivate further research on this topic, from the point of view of theory, simulation and experiment.

Acknowledgement This work was financially supported by the Deutsche Forschungsgemeinschaft (DFG), SFB 625/A3. K. B. thanks S. Rathgeber and M. Schmidt for stimulating discussions and for early information about recent papers (Refs. 14, 15, 16). H.-P. H. thanks Prof. Peter Grassberger and Dr. Walter Nadler for very useful discussions. We are grateful to the NIC Jülich for providing access to the JUMP parallel processor.
