INTEGRATED SACHS–WOLFE IMPRINT OF SUPERSTRUCTURES ON LINEAR SCALES

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ABSTRACT

We build a model for the density and integrated Sachs–Wolfe (ISW) profile of supervoid and supercluster structures. Our model assumes that fluctuations evolve linearly from an initial Gaussian random field. We find these assumptions capable of describing \( N \)-body simulations and simulated ISW maps remarkably well on large scales. We construct an ISW map based on locations of superstructures identified previously in the Sloan Digital Sky Survey Luminous Red Galaxy sample. A matched filter analysis of the cosmic microwave background confirms a signal at the 3.2\( \sigma \) confidence level and estimates the radius of the underlying structures to be \( 55 \pm 28 \, h^{-1} \) Mpc. The amplitude of the signal, however, is 2\( \sigma \) higher than \( \Lambda \)CDM predictions.

Key words: cosmic background radiation – large-scale structure of universe – methods: statistical

Online-only material: color figures

1. INTRODUCTION

Since the first sky maps of the Wilkinson Microwave Anisotropy Probe (WMAP) were published, there have been claims for the existence of circular features (spots and rings) in the cosmic microwave background (CMB; Cruz et al. 2005; Granett et al. 2008a). Their origin and statistical significance are still debated. Sources, such as foreground contamination, integrated Sachs–Wolfe (ISW; Sachs & Wolfe 1967) effect, and the more exotic conformal cyclic cosmology or cosmic texture have been considered viable candidates to explain circular CMB anomalies (Rudnick et al. 2007; Inoue et al. 2010; Cruz et al. 2007; Gurzadyan & Penrose 2010). A notable feature is the cold spot (Cruz et al. 2005), which has a mean temperature of \( -70 \mu \text{K} \) in a 5\( ^\circ \) radius aperture. Additionally, 10\( \mu \text{K} \) hot and cold spots have been identified on 4\( ^\circ \) scales associated with superstructures (Granett et al. 2008a).

In this paper, we focus on the ISW effect and investigate whether it is possible that large spherical fluctuations (supervoids and superclusters) in the dark matter field produce the aforementioned features in the CMB. The large-scale ISW effect is expected in a universe with accelerated cosmic expansion arising either from a dark energy term in flat cosmological models or from spatial curvature. The effect is sensitive to both the expansion history and the rate of structure formation and the potential and calculating the linear part of the ISW effect.

2. PROFILES IN SIMULATIONS

In this section we calculate the full expected density profiles and ISW imprints of spherical overdensities and underdensities based on Pápai & Szapudi (2010) and compare them with measurements from the HVS.

2.1. Density Profiles of Superstructures in \( N \)-body Simulations

According to Pápai & Szapudi (2010), if the average density contrast in a Gaussian random field inside a sphere of radius \( R \) is given, we expect the density contrast at radius \( r \) from its center...
to be
\[
\langle \delta(r) \rangle_{\delta_m(R)} = \frac{\langle \delta(r) \delta_m(R) \rangle}{\delta_m(R)} = \int \frac{d\delta \delta_m}{\delta_m} P(\delta) \delta_m P(\delta_m) = \langle \delta^2 \rangle_{\delta_m(R)},
\]
where \(\langle \ldots \rangle\) stands for ensemble averaging, \(\delta(r)\) is the density contrast at radius \(r\), and \(\delta_m(R)\) is the average of \(\delta\) inside radius \(R\). In the Appendix of Dekel (1981) the author derived a similar formula for a single, point-like location with given density, which is the \(R \to 0\) limit. Equation (1) is essentially the two-point function multiplied by a normalization constant. A more general calculation for the density profile around local maxima in a Gaussian random field was carried out by Bardeen et al. (1986).

In order to measure \(\langle \delta(r) \rangle_{\delta_m(R)}\), one needs to select regions with \(\delta_m(R)\) and calculate the average over these. However, according to Equation (1), \(\langle \delta^2 \rangle_{\delta_m(R)}\) gives an unbiased estimator of \(\langle \langle \delta(r) \delta_m(R) \rangle \rangle\), the shape of the profile:
\[
\left\{ \frac{\delta}{\delta_m} \right\} = \int d\delta d\delta_m \frac{\delta}{\delta_m} P(\delta) \delta_m P(\delta_m) = \langle \delta^2 \rangle_{\delta_m(R)} = \int d\delta_m P(\delta_m),
\]
where we shorthand \(\delta(r)\) and \(\delta_m(R)\) as \(\delta\) and \(\delta_m\). We also use the fact that by definition \(\langle \delta(r) \delta_m(R) \rangle = \int d\delta \delta_m P(\delta) \delta_m P(\delta_m)\) and \(\langle \delta \delta_m \rangle\) is independent of \(\delta_m\). The argument above shows that it is needless to search for spheres with a certain \(\delta_m(R)\) to verify Equation (1). In the rest of this subsection we deal with the integral of \(\delta(r)\) instead of \(\delta(r)\), because the former is measurable directly
\[
M(r) = 4\pi \int_0^r drr^2 \delta(r).
\]

The linear size of the HVS is 3000 \(h^{-1}\) Mpc. We chose to place spheres at \(25^3\) evenly spaced coordinates. We counted \(25^2\) superstructures at \(r, 10^h\) Mpc, \(20^h\) Mpc, \ldots, \(160^h\) Mpc and subtracted the average to get \(M(r)\). We normalized this as \(\frac{M(r)}{\pi R^3}\) and calculated the average of the \(25^3\) instances to get an estimate of the integral of Equation (2). As \(R\) changes, technically, by weighting \(M(r)\) differently, one can get the profile of linear superstructures of different sizes. A nuisance we have to deal with is that the estimator given by Equation (2) is unstable because \(\delta_m\) can be arbitrarily small. The ratio of two Gaussian variables with zero means has a Lorentzian distribution, which has an undefined variance. This problem can be avoided if cases when \(|\delta_m|\) is below a threshold are ignored. This constraint leaves the estimator unchanged as can be seen from Equation (2). We chose the threshold based on the variance of \(\delta_m\) in the particular catalog, e.g., \(2\sqrt{\langle \delta_m^2 \rangle}\). The result is not sensitive to the exact choice but the right choice can decrease the variance of the estimator substantially. In Figure 1 we plotted the measured profiles and their theoretical counterparts for \(R = 60^h\) Mpc on the upper panel and for \(R = 100^h\) Mpc on the lower panel. We obtained the error bars by repeating the measurement on 100 mock catalogs generated with a second-order Lagrangian (2LPT) code (Croce et al. 2006). The mocks were set up to have the same cosmological parameters, size, and density as the HVS. To calculate the theoretical profiles of Equation (1), we used a matter power spectrum calculated via CAMB (Lewis et al. 2000). The measured profiles, both in 2LPT and the HVS, appear to be in good agreement with theory within the uncertainty up to \(400^h\) Mpc, the largest radius in our measurement.

![Figure 1. Integral of the spherically averaged density profile measured in the HVS and 100 2LPT simulations. Linear theory given by Equation (2) appears to be a good approximation.](image)

(A color version of this figure is available in the online journal.)

### 2.2. The ISW Imprints of Superstructures

In Pápai & Szapudi (2010) the ISW effect in the direction of the center of a superstructure was calculated. This was done simply by calculating the spherically symmetric potential of the superstructure, then computing the following integral along the path of the CMB photon (Sachs & Wolfe 1967):

\[
\Phi(r) = \frac{-3\Omega_m}{8\pi} \left( \frac{H_0}{c} \right)^2 \int_r^{\infty} \frac{M(\tilde{r})}{\tilde{r}^2} d\tilde{r},
\]

\[
\frac{\Delta T}{T} = \frac{2}{c^2} \int d\tau \frac{\partial \Phi(r(\tau), \tau)}{\partial \tau},
\]

where \(\tau\) denotes conformal time. Similarly, this calculation can be carried out for any direction easily in order to predict the full ISW profile. In linear theory the potential at a particular redshift is just \(\Phi(r, z) = \Phi(r, z = 0) \frac{\Omega(z)}{\Omega(0)}\). We leave the study of nonlinear corrections for future work. Since these integrals are linear, the linear ISW signal is predicted to be proportional to the average density of the superstructure, \(\delta_m\). In this paper, we place the centers of the superstructures at \(z = 0.52\), which is the median redshift of the galaxy catalog we use in Section 3.

### 2.3. Fluctuations in the Potential on the Largest Scales and the ISW Profile

To test the ISW profile we traced rays through the HVS along the \(z\)-axis. We calculated \(\delta\) on an \(800^3\) grid and calculated \(\Phi\) at \(z = 0\) by using the simple formula

\[
\Phi(k) = -\frac{3\Omega_m}{2} \left( \frac{H_0}{c} \right)^2 \frac{\delta(k)}{k^2}.
\]

Since we aimed to analyze imprints of superstructures at redshift 0.52, we defined the boundaries of the integral of Equation (5) in a way that put the \(25^3\) preselected locations (see Section 2.1) at this redshift. We used periodic boundary conditions and integrated up to \(3000^h\) Mpc from starting points ensuring that \(25^2\) of the locations were at redshift 0.52 each time. This yielded 25 ISW images of the HVS in the \(x-y\) plane. Each of these images contains imprints of \(25^2\) superstructures. After this, one can follow the procedure discussed for density
Figure 2. Each row shows histograms of a certain projection of density along the z-axis. A simple integral of $\delta(x, y, z)dz$ is presented in the first row, an ISW map in the second, and its filtered version in the third. (See the text for details.) The x–y plane is halfed to test the cosmic variance, hence the two columns. As a result of large fluctuations in the low k-modes in the potential, the ISW projections show a significant cosmic variance (second row) which can be reduced by filtering (third row). (A color version of this figure is available in the online journal.)

The success of these tests proves the validity of the Gaussian model of Pâpai & Szapudi (2010). We studied Euclidean ISW projections because or their simplicity but there is no reason to think that our findings are restricted to the Euclidean case. The

due to modes on the largest scales we removed the low k-modes from the potential. After experimenting we found that removing modes with $|k| < 2\pi/3000\ Mpc^{-1}$ for the HVS, gave a visually compelling result (Figure 2, bottom row). After applying this high-pass filter to a two-dimensional projection, the effect of the cosmic variance on the modes with the lowest wavenumber will be around 18%. This argument is valid for any survey or simulation. Generally, modes can be combined optimally with the proper covariance matrix. In this paper, we simply use the sum of the modes as an estimator of the ISW signal. In other words, our covariance matrix is diagonal with a truncation at 1/5 of the linear size. This subjective choice, which we consistently carry along through the paper, is based purely on the histogram of the potential (Figure 2).

Having removed the low k-modes from both the density and the potential, we computed the average in Equation (7). As before, we omitted cases when the denominator was too close to zero. (See Section 2.1.) The results for $R = 60\ h^{-1}\ Mpc$ and $R = 100\ h^{-1}\ Mpc$ are shown in Figure 3. The error bars show the uncertainty calculated from the HVS itself due to the long CPU time required to calculate the ISW images. Predictions of the linear model are calculated by removing the low k-modes from the power spectrum when doing calculation according to Equation (1).

This approach has to be modified slightly when the CMB is given and late time anisotropies are affected by every mode of the galaxy distribution. The previous exercise still proves that low k-modes are to be ignored if we want to study the imprints of superstructures statistically. This can be achieved by filtering out these modes from the CMB before performing such analysis. In addition, one has to remove the same components from the theoretical ISW profile before fitting the data. This is shown in Figure 4. We filtered the ISW map and the ISW profile, which is implicitly expressed as $f(r_{2D}, R)$, on the right-hand side of Equation (7), so that only modes with $|k| > 2\pi/3000\ Mpc^{-1}$ remained. After these manipulations the measurement remained consistent with linear theory.

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Figure 4. Same as Figure 3 with the exception that the ISW map was filtered, not the density. The error bars represent the uncertainty of the measurement. (A color version of this figure is available in the online journal.)

only major difference is that on a sphere one deals with spherical harmonics and instead of low $k$-modes we speak of low $l$-modes analogously.

3. ISW MAP OF SDSS SUPERSTRUCTURES

Having calculated the full linear ISW profile of superstructures in the dark matter density, we attempt to detect their presence on the CMB. With the locations of 50 superclusters and 50 supervoids found in the SDSS DR6 LRG sample by Granett et al. (2008a), we created ISW maps and used the matched filter technique to measure the amplitude of the ISW signal. Our ISW maps are statistical in the sense that the individual ISW profiles were predicted by using statistical properties of Gaussian, spherically symmetric density fluctuations rather than the particular (poorly observed) realization of the density field.

3.1. Superclusters and Supervoids in the SDSS LRG Sample on 100 $h^{-1}$ Mpc Scales

Large regions with significantly high overdensities or low underdensities are called here superclusters or supervoids. In a given data set these regions can be defined in many different ways. Void finder algorithms were compared in Colberg et al. (2008). Each implementation is based on a certain notion of a void. Voids can have spherical or irregular shapes, finders can be parameter free or there can be a hard coded density threshold or radius to describe what a void is like. It is important to emphasize that despite the similarities, any analysis using the output of a void finder will be sensitive to its particulars. This renders our study qualitative in nature.

Our work is based on supervoids and superclusters found in a subsample of the SDSS DR6 LRG catalog by ZOBOV and VOBOZ, parameter free void and cluster finder algorithms (Neyrinck 2008; Neyrinck et al. 2005). ZOBOV and VOBOZ calculate the Voronoi tessellation of the data in order to approximate the density field with a simple function, a function that is constant inside polyhedra. Voids are found by using the concept of drainage basins from geography. Clusters are identified analogously.

A table with the properties of 50 supervoids and 50 superclusters can be found in Granett et al. (2008b). Their sizes and densities cannot be quantified simply due to their shapes and survey boundary effects. The bias, redshift error, and the shot noise are also sources of uncertainty for both size and density. This is why we used only the directions of the centers of these superstructures in creating ISW maps in Section 3.3. The error in the angular coordinates is relatively small.

3.2. CMB and ISW Maps

We used the Internal Linear Combination (ILC) Map from the WMAP 7 year release (Gold et al. 2011) with the KQ75y7 galactic foreground and point-source mask. We employed Healpix pixelization at resolution $n_{side} = 64$ (Górski et al. 2005). In general, we strove to carry out the measurement with up-to-date maps and masks, while remaining consistent with Granett et al. (2009).

Section 2 concluded that a Gaussian model gave a good approximation to the expected ISW signal from a large spherical region in the dark matter field with given density contrast. It also became apparent that in an analysis of statistical ISW maps low $l$-modes were to be filtered out due to the large cosmic variance of the potential affecting these modes. This also lowers the cosmic variance. The lowest mode to be taken into account is determined by the sky coverage of the ISW map. Experimenting with the HVS gave us $k_{min} \approx 2\pi/5$ for a Euclidean ISW map, where $L$ is the linear size of the map. This translates into $l_{min} \approx 2\pi r/L$ via the Limber approximation, where $\lambda$ and $r$ are the angular size and the median distance of the SDSS DR6 LRG sample, respectively. A rough estimate yields $l_{min} \approx 12$.

Due to the large uncertainty in their size and density, we assume that each supervoid is a realization of the same statistical entity when we create ISW maps. We consider superclusters similar in nature but with an opposite density contrast.

An ISW map is made simply by placing the expected ISW profiles of superstructures at the locations given in Granett et al. (2008b). We set $\delta_{in}$ to 1 for clusters and $-1$ for voids in formulae of Section 2. For every radius there is a corresponding ISW map. We calculated the $a_{lm}$ coefficients of the spherical expansion of both the ISW maps and the CMB map, and zeroed the modes below $l_{min} = 12$ before transforming the $a_{lm}$’s back. These manipulations were carried out with routines from the Healpix package (Górski et al. 2005). Figure 5 shows how the ISW profile changes when modes are removed. This figure also tells about the decrease of the signal. In the case of $l_{min} = 12$, it is around 50% at the center and grows outward. Our heuristic method aims to find an acceptable compromise between the loss of signal and small sample variance.

3.3. The Matched Filter Technique

We continue with measuring the amplitude of the ISW maps created in Section 3.2 in the WMAP ILC map. To do this we used the same matched filter technique as Granett et al. (2009). A likelihood function is defined as

$$L(\lambda) = -\frac{1}{2}(T_{cmb} - \lambda T_{ISW})C^{-1}(T_{cmb} - \lambda T_{ISW}).$$

(8)

where $T_{cmb}$ is a foreground cleaned CMB map, in this case the WMAP ILC map, and $T_{ISW}$ refers to the ISW maps. The pixel covariance matrix, $C$, is computed from the best-fitting ΛCDM power spectrum. This likelihood is based on the assumption that the $T_{ISW}$ and the primary CMB are the realizations of two very different Gaussian random fields and the latter is given by the minimum of Equation (8):

$$\lambda^* = \frac{T_{ISW}C^{-1}T_{cmb}}{T_{ISW}C^{-1}T_{ISW}},$$

(9)
Figure 5. Expected ISW imprint of a spherical region with radius of 120$h^{-1}$ Mpc and an average $\delta$ of 1 at redshift 0.52. Each curve shows the same profile without modes under their respective $l_{\text{min}}$.

As explained in Section 3.2, we filtered out modes up to $l_{\text{min}} = 12$ from both $T_{\text{ISW}}$ and $T_{\text{cmb}}$, and before building the covariance matrix from $C_{ll}$'s we set $C_0 = C_1 = \cdots = C_{11} = 0$. Since the exact inverse of the covariance matrix is unstable for partial sky maps, we regularized $C$ by calculating a pseudo-inverse omitting the noisiest modes. The likelihood function above defines an error on $\lambda^*$ as

$$\Delta \lambda^2 = \frac{1}{T_{\text{ISW}} C^{-1} T_{\text{ISW}}}.$$  (11)

3.4. Results

We calculated $\lambda^*$ according to Equation (9). Since we have ISW maps for different void/cluster radii, the result is a function, $\lambda(R)$. This is presented in Figure 6 in the bottom row on the left panel. The error bars are given by Equation (11). From now on every time we refer to a $\lambda$ we mean the value at the minimum of the likelihood function, so we drop the superscript *.

If we marginalize $\lambda(R)/\Delta \lambda(R)$ over $R$, we get a 3.24σ detection.

Similarly, the marginalized value of $R$ is $55 \pm 28 h^{-1}$ Mpc.

$\lambda(R)$ can be interpreted as the average density contrast in 100 superstructures inside radius $R$, where the supervoids are taken into account with a minus sign:

$$\lambda(R) \approx \frac{1}{2}(\delta_{50c}^{50}(R) - \delta_{50v}^{50}(R)),$$  (12)

where superscripts $50c$ and $50v$ refer to the average of 50 superclusters and 50 supervoids. This interpretation originates

Figure 6. Top and mid rows contain contour plots of the best-fitting amplitude of the ISW maps, $\lambda$, and their relative uncertainty, $\sigma$ (see the text for their definition), as functions of $l_{\text{min}}$ and $R$. The bottom row shows cross sections of the contour plots from the top row at $l_{\text{min}} = 12$, as well as the prediction for the average density contrast of superstructures of a certain size. In the left column the fitting is for an ISW map consisting of the 50 most significant supervoids and 50 superclusters. The middle column shows the same for best 25–25, while the right for the remaining 50 superstructures not included in the middle column.

(A color version of this figure is available in the online journal.)
from the linear relationship between the ISW signal and the density fluctuations, and our choice of \( \delta_{\text{in}} = \pm 1 \) when building ISW maps in Section 3.2. In addition to the data curves, in Figure 6 we plotted the prediction of linear theory for the average of the 50 largest superclusters. We assumed a Gaussian probability distribution function (PDF) which is reasonable in light of the findings of Pápai & Szapudi (2010). The variance of the PDF was calculated by CAMB (Lewis et al. 2000) using the latest WMAP cosmological parameters (Jarosik et al. 2011) and it was scaled with the growth function to the median redshift of the superstructures (\( z = 0.52 \)). The number of independent clusters was estimated as \( V_{\text{survey}} / V_{\text{cluster}} \), where \( V_{\text{survey}} \) is the volume of the LRG sample used by Granett et al. (2009). \( \lambda \) is consistently several times larger than the predicted \( \delta_{\text{in}} \). As a consistency test we split the voids and clusters into two groups. Group 1 consists of the first 25 voids and 25 clusters with the highest significance in the supplementary tables of Granett et al. (2008b). The other 25 voids and 25 clusters make up group 2. We created two ISW maps, one from each of the groups. After repeating the whole procedure for these, we got the center and the right panels in the bottom row of Figure 6. As expected, superstructures associated with lower significance produce lower signal on the CMB and allow larger deviation from the average \( \lambda \). This supports the hypothesis that the signal is due to the ISW effect.

We also checked the sensitivity of the results to the choice of \( l_{\min} \), the lowest spherical harmonics included in the analysis. The result for different choices of \( l_{\min} \) is shown in the middle and top rows of Figure 6. The top row shows \( \lambda(R, l_{\min}) \), while the middle row shows \( \sigma(R, l_{\min}) = \lambda(R, l_{\min}) / \Delta \lambda(R, l_{\min}) \) on contour plots. The result seems robust for a wide range of \( l_{\min} \).

We performed another consistency check to acquire a better understanding of the uncertainty of \( \lambda \) and its relationship with \( \delta_{\text{in}} \). We created ISW maps from single superstructures. We used the matched filter technique to determine a \( \lambda \) and its error as before. The average \( \lambda \) for voids and for clusters separately are plotted in Figure 7. In this case we defined the uncertainty of \( \lambda \) as the standard deviation of its mean. We also plotted the previous results for the previous combined ISW map. All of this is for \( l_{\min} = 12 \). The three measured curves are consistent with each other, the error bars show the 2\( \sigma \) deviation. The single void and cluster fit allow wider range of \( \lambda \) than the combined fit.

4. DISCUSSION

This paper is the continuation of the work started in Pápai & Szapudi (2010). Our goal is to estimate the ISW imprint of large spherical dark matter overdensities and underdensities. In Section 2, first, we tested a simple Gaussian model for density profiles in the HVS. We created an ISW map by ray tracing through the simulation and computing the linear ISW effect. We neglected the nonlinear part of the ISW effect, as it is small in comparison at \( z = 0 \) (Cai et al. 2010). Another simplification was that our ISW map was Euclidean. For the purpose of testing this has no relevance.

As can be seen from Figure 1, the density profiles followed linear theory given by Equation (1) within 1\( \sigma \) uncertainty up to 400\( h^{-1} \) Mpc, the largest scale in our study. This is not surprising, since the density profile is the equivalent of the two-point function and on large scales high-order clustering is not important. When we averaged the density profiles, we only used locations where the average density contrast in a certain radius was in the 2\( \sigma \) (positive or negative) tail of the PDF. This demonstrates that not even the extreme cases are affected by nonlinearities significantly.

We demonstrated that cosmic variance was a much more important factor for the ISW effect than for the density. Since cosmic variance is large for low \( k \)-modes and the potential is non-vanishing as \( k \rightarrow 0 \), these modes have a relatively large effect on the ISW profile. Surely large variance modes should be removed from the CMB and the ISW maps if the ISW maps are based on the statistics of density fluctuations and not on the observed density. First, we measured the ISW profiles after filtering out the low \( k \)-modes from the HVS density and consequently the ISW map. Filtering the two-point function in the same way gave a good match to the data. (See Figure 3.)

If the ISW map is given, as in the CMB, another route has to be taken. We filtered the complete ISW map and compared it to the theoretical profile after removing the same modes. The result is shown in Figure 4.

In Section 3 we used the matched filter technique to detect the ISW signal of superstructures in the CMB. We closely followed the procedure described in Granett et al. (2009). The major difference is that our ISW map was built from theoretical assumptions about the shape of ISW profiles, while in Granett et al. (2009) the authors used an analytic curve which fitted the measured profiles the best. Because of this, the significance of our measurement can readily be interpreted. We estimated the marginalized significance of our measurement to be \( \sigma = 3.24 \). (See Section 3.4 for details.) The interpretation of the best-fitting amplitude of the ISW map is still not without difficulties. It is several times higher than the anticipated signal (Figures 6 and 7), although it appears to be 2\( \sigma \) higher than \( \Lambda \)CDM predictions, where \( \sigma \) indicates the uncertainty of the fit and not the intrinsic uncertainty of the ISW signal. We caution though that the uncertainty can still be underestimated, since it was derived from data alone. Despite the difference in amplitude, the theoretical and the measured curves run parallel with each other, which supports the idea that the signal is related to the ISW effect. Moreover, traditional cross-correlation methods have also been reported to yield higher signal than expected (Ho et al. 2008; Giannantonio et al. 2008a; Granett et al. 2009).

The ISW effect provides an explanation for another feature of observations. On average, supervoids tend to have a hot
ring around an initial cold dip and the opposite is true for superclusters (Granett et al. 2009). When we erased large-scale fluctuations in the microwave background, the expected ISW profile changed sign as seen in Figure 5. This means that in certain, not particularly unique realizations the average profiles of 50 supervoids or superstructures from a finite area of the sky can have rings in the ISW context, simply due to the cosmic variance of low \( k \)-modes.

Overall we can say that the shape of the measured signal follows the predicted ISW profile, while its amplitude exceeds expectation. This is a good reason to investigate further by studying galaxy surveys other than the SDSS. A key to a quantitative study is the well-measured galaxy density. Since the model described in this paper is a model for density fluctuations around a particular location, which is not necessarily a maximum, it is enough to know the density at this location accurately.

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