Solitons and vortices in nonlinear potential wells

Nir Dror¹ and Boris A Malomed

Department of Physical Electronics, School of Electrical Engineering, Faculty of Engineering, Tel Aviv University, Tel Aviv 69978, Israel

E-mail: drornir1@walla.com

Received 6 July 2015
Accepted for publication 8 October 2015
Published 30 November 2015

Abstract

We consider self-trapping of topological modes governed by the one- and two-dimensional (1D and 2D) nonlinear-Schrödinger/Gross–Pitaevskii equation with effective single- and double-well (DW) nonlinear potentials induced by spatial modulation of the local strength of the self-defocusing nonlinearity. This setting, which may be implemented in optics and Bose–Einstein condensates, aims to extend previous studies, which dealt with single-well nonlinear potentials. In the 1D setting, we find several types of symmetric, asymmetric and antisymmetric states, paying attention to scenarios of the spontaneous symmetry breaking. The single-well model is extended by including rocking motion of the well, which gives rise to Rabi oscillations between fundamental and dipole modes. Analysis of the 2D single-well setting gives rise to stable modes in the form of ordinary dipoles, vortex–antivortex dipoles (VADs), and vortex triangles (VTs), which may be considered as produced by spontaneous breaking of the axial symmetry. The consideration of the DW configuration in 2D reveals diverse types of modes built of components trapped in the two wells, which may be fundamental states and vortices with topological charges \( m = 1 \) and 2, as well as VADs (with \( m = 0 \)) and VTs (with \( m = 2 \)).

Keywords: nonlinear potential wells, solitons, vortices

(Some figures may appear in colour only in the online journal)

1. Introduction and the model

It is commonly known that in spaces of different dimension, \( D \), bright solitons of scalar complex field \( \phi \) may be supported by balance between the focusing nonlinearity and diffraction [1]. The solitons created by focusing term \( |\phi|^2 \phi \) in the underlying nonlinear Schrödinger/Gross–Pitaevskii equation (NLSE/GPE) are unstable in the case when the same setting gives rise to the collapse, i.e., at \( mD \geq 2 \), according to the Talanov’s criterion [2]. In particular, the Townes’ solitons [3], which form degenerate families with the norm that does not depend on the propagation constant, are destabilized by the critical collapse (corresponding to \( mD = 2 \)) in the 2D space with the cubic nonlinearity, \( m = 1 \) [4], and in the 1D space with the quintic self-focusing, \( m = 2 \) [5].

In the absence of linear trapping potentials, an effective nonlinear potential (alias pseudopotential [6]) for optical waves in photonic media, and for matter waves in a Bose–Einstein condensate (BEC) [7] can be induced by the spatial modulation of the local strength of the cubic nonlinearity, accounted for by coefficient \( \sigma (r) \) [8]:

\[
i\psi_r = -\frac{1}{2} \nabla^2 \psi + \sigma (r) |\psi|^2 \psi,
\]

the respective Hamiltonian being

\[
H = \frac{1}{2} \int \left[ |\nabla \psi|^2 + \sigma (x) |\phi (x)|^2 \right] dx.
\]

In optics, \( \psi \) is the scaled amplitude of the guided electromagnetic field, \( z \) is the propagation distance and the set of transverse coordinates is \( r = (x, y) \) or \( x \), in the 2D and 1D settings, respectively. In terms of the GPE, \( z \) is the scaled time, and the scattering length, which is proportional to \( \sigma (r) \) in equation (1), can be modified by means of the Feshbach resonance in external magnetic or optical fields [9–11]. The spatial modulation of the scattering length in atomic...
condensates was experimentally demonstrated on the sub-micron scale [12]. The necessary spatial profile may be also induced as an averaged spatial pattern ‘painted’ by a fast moving laser beam [13], or by an optical-flux lattice [14]. Another approach makes use of an appropriate magnetic lattice, into which the condensate is loaded [15], or of magnetic-field concentrators [16]. In optics, the modulation of the nonlinearity strength can be achieved by means of inhomogeneous doping of the waveguide with nonlinearity-enhancing impurities [17]. Alternatively, one can use a uniform dopant density, onto which an external field imposes an inhomogeneous distribution of detuning from the respective two-photon resonance.

The nonlinear potential induced by the modulation of the self-focusing nonlinearity, which corresponds to \( \sigma(\mathbf{r}) < 0 \) in equation (1), can readily support stable solitons in the 1D geometry, as has been demonstrated in various settings [18, 19]. On the other hand, in the 2D geometry, stable fundamental solitons can be maintained only by modulation profiles with sharp edges, all vortex solitons being unstable [8, 20, 21].

Recently, an alternative scheme was theoretically elaborated, based on the defocusing nonlinearity strength growing at \( r \to \infty \) at any rate exceeding \( r^D \) [22–32]. This scheme secures stable self-trapping of a great variety of fundamental and higher-order solitons, including solitary vortices [22, 23, 32], and complex 3D modes, such as soliton gyroscopes [25], vortex–antivortex hybrids [26], and ‘hopfions’ (vortex tori with intrinsic twist) [27]. Moreover, the scheme was extended for discrete solitons [28], quantum solitons in the Bose-Hubbard model [29], and 1D and 2SD settings with the spatially modulated long-range dipole–dipole repulsive interactions [30].

Stationary solutions to equation (1) are looked for as

\[
\psi(\mathbf{r}, z) = \phi(\mathbf{r}) e^{i\mu z},
\]

where \( \mu \) determines the propagation constant, in terms of photonic models, or the chemical potential, \(-\mu\), in BEC, and

\[
\mu \phi = \frac{1}{2} \nabla^2 \phi + \sigma(\mathbf{r}) |\phi|^2 \phi.
\]

Self-trapped solutions supported by the system are characterized by the norm (energy flow), defined as

\[
N = \int |\phi(\mathbf{r})|^2 d\mathbf{r}.
\]
We aim to consider two types of nonlinearity-modulation profiles, in the 1D and 2D geometries alike. The first corresponds to the isotropic single-well setting, with the steep anti-Gaussian shape, which was introduced in [23]:

$$\sigma(r) = \exp(\alpha r^2).$$

(6)

Another version of the single-well profile, including a pre-exponential factor, was also considered in [23]:

$$\sigma(r) = \left(\sigma_0 + \frac{\sigma_2}{2} r^2\right) \exp(\alpha r^2).$$

(7)

The main subject of the present work is an anisotropic double-well (DW) profile, whose 2D form can be defined as a natural extension of its single-well counterpart, possibly with the addition of a pre-exponential factor:

$$\sigma(r) = \left\{ \sigma_0 + \frac{\sigma_2}{2} \left[ \left( |x| - x_0 \right)^2 + y^2 \right] \right\} \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}$$

(8)

(see equation (7)), with constants $\sigma_{0,2} \geq 0$, and $x_0 \geq 0$, where $x = \pm x_0$ are positions of centers of the two wells. Different types of the DW structure correspond to $\beta = 1$ and $\beta = 0$ in equation (8) (in the latter case, the bottom of each well is shifted from $x = \pm x_0$ towards $x = 0$). A particular DW profile corresponds to $\sigma_0 = 1$, $\sigma_1 = 0$, $\beta = 1$ in equation (8) (see equation (6) for the single well):

$$\sigma(r) = \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}.$$ 

(9)

The 1D counterpart of the DW setting based on equation (9) is considered below too.

It is commonly known that the ground state generated by the linear Schrödinger equation with a DW potential is always symmetric, with respect to the two potential wells [33]. The interplay of the linear DW potentials with uniform self-focusing nonlinearities in models based on the NLSE/GPE gives rise to the fundamental effect of the spontaneous symmetry breaking (SSB) [34, 35]. In its simplest manifestation, the SSB implies that the probability to find the particle in one

with constant $\alpha > 0$ which determines the width of the well, $\sim \alpha^{-1/2}$. Another version of the single-well profile, including a pre-exponential factor, was also considered in [23]:

$$\sigma(r) = \left(\sigma_0 + \frac{\sigma_2}{2} r^2\right) \exp(\alpha r^2).$$

(7)

The main subject of the present work is an anisotropic double-well (DW) profile, whose 2D form can be defined as a natural extension of its single-well counterpart, possibly with the addition of a pre-exponential factor:

$$\sigma(r) = \left\{ \sigma_0 + \frac{\sigma_2}{2} \left[ \left( |x| - x_0 \right)^2 + y^2 \right] \right\} \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}$$

(8)

(see equation (7)), with constants $\sigma_{0,2} \geq 0$, and $x_0 \geq 0$, where $x = \pm x_0$ are positions of centers of the two wells. Different types of the DW structure correspond to $\beta = 1$ and $\beta = 0$ in equation (8) (in the latter case, the bottom of each well is shifted from $x = \pm x_0$ towards $x = 0$). A particular DW profile corresponds to $\sigma_0 = 1$, $\sigma_1 = 0$, $\beta = 1$ in equation (8) (see equation (6) for the single well):

$$\sigma(r) = \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}.$$ 

(9)

The 1D counterpart of the DW setting based on equation (9) is considered below too.

It is commonly known that the ground state generated by the linear Schrödinger equation with a DW potential is always symmetric, with respect to the two potential wells [33]. The interplay of the linear DW potentials with uniform self-focusing nonlinearities in models based on the NLSE/GPE gives rise to the fundamental effect of the spontaneous symmetry breaking (SSB) [34, 35]. In its simplest manifestation, the SSB implies that the probability to find the particle in one

with constant $\alpha > 0$ which determines the width of the well, $\sim \alpha^{-1/2}$. Another version of the single-well profile, including a pre-exponential factor, was also considered in [23]:

$$\sigma(r) = \left(\sigma_0 + \frac{\sigma_2}{2} r^2\right) \exp(\alpha r^2).$$

(7)

The main subject of the present work is an anisotropic double-well (DW) profile, whose 2D form can be defined as a natural extension of its single-well counterpart, possibly with the addition of a pre-exponential factor:

$$\sigma(r) = \left\{ \sigma_0 + \frac{\sigma_2}{2} \left[ \left( |x| - x_0 \right)^2 + y^2 \right] \right\} \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}$$

(8)

(see equation (7)), with constants $\sigma_{0,2} \geq 0$, and $x_0 \geq 0$, where $x = \pm x_0$ are positions of centers of the two wells. Different types of the DW structure correspond to $\beta = 1$ and $\beta = 0$ in equation (8) (in the latter case, the bottom of each well is shifted from $x = \pm x_0$ towards $x = 0$). A particular DW profile corresponds to $\sigma_0 = 1$, $\sigma_1 = 0$, $\beta = 1$ in equation (8) (see equation (6) for the single well):

$$\sigma(r) = \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}.$$ 

(9)

The 1D counterpart of the DW setting based on equation (9) is considered below too.

It is commonly known that the ground state generated by the linear Schrödinger equation with a DW potential is always symmetric, with respect to the two potential wells [33]. The interplay of the linear DW potentials with uniform self-focusing nonlinearities in models based on the NLSE/GPE gives rise to the fundamental effect of the spontaneous symmetry breaking (SSB) [34, 35]. In its simplest manifestation, the SSB implies that the probability to find the particle in one

with constant $\alpha > 0$ which determines the width of the well, $\sim \alpha^{-1/2}$. Another version of the single-well profile, including a pre-exponential factor, was also considered in [23]:

$$\sigma(r) = \left(\sigma_0 + \frac{\sigma_2}{2} r^2\right) \exp(\alpha r^2).$$

(7)

The main subject of the present work is an anisotropic double-well (DW) profile, whose 2D form can be defined as a natural extension of its single-well counterpart, possibly with the addition of a pre-exponential factor:

$$\sigma(r) = \left\{ \sigma_0 + \frac{\sigma_2}{2} \left[ \left( |x| - x_0 \right)^2 + y^2 \right] \right\} \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}$$

(8)

(see equation (7)), with constants $\sigma_{0,2} \geq 0$, and $x_0 \geq 0$, where $x = \pm x_0$ are positions of centers of the two wells. Different types of the DW structure correspond to $\beta = 1$ and $\beta = 0$ in equation (8) (in the latter case, the bottom of each well is shifted from $x = \pm x_0$ towards $x = 0$). A particular DW profile corresponds to $\sigma_0 = 1$, $\sigma_1 = 0$, $\beta = 1$ in equation (8) (see equation (6) for the single well):

$$\sigma(r) = \exp \left\{ \alpha \left[ \left( |x| - \beta x_0 \right)^2 + y^2 \right] \right\}.$$ 

(9)

The 1D counterpart of the DW setting based on equation (9) is considered below too.

It is commonly known that the ground state generated by the linear Schrödinger equation with a DW potential is always symmetric, with respect to the two potential wells [33]. The interplay of the linear DW potentials with uniform self-focusing nonlinearities in models based on the NLSE/GPE gives rise to the fundamental effect of the spontaneous symmetry breaking (SSB) [34, 35]. In its simplest manifestation, the SSB implies that the probability to find the particle in one
well of the DW potential is larger than in the other. This also means that another principle of quantum mechanics, according to which the ground state cannot be degenerate, is no longer valid in the nonlinear systems, as the SSB creates a degenerate pair of two mutually symmetric ground states, with the maximum of the wave function trapped in either potential well. While the same system admits a symmetric state coexisting with the asymmetric ones, it no longer represents the ground state above the SSB point, being unstable against symmetry-breaking perturbations. In systems with the defocusing nonlinearity, the ground state remains symmetric and stable, while the SSB manifests itself in the form of the spontaneous breaking of the spatial antisymmetry of the first excited state.

The SSB was introduced in early works [36], and then developed in detail in the system modeling the propagation of continuous-wave optical beams in dual-core nonlinear optical fibers [37]. Depending on the form of the nonlinearity, it gives rise to symmetry-breaking bifurcations of the supercritical (alias forward) or subcritical (backward) type [38]. The next step in the studies of the SSB phenomenology in dual-core systems was the detailed consideration of this effect for solitons, described by a system of linearly coupled partial differential NLSEs [39–43].

Figure 5. The evolution of unstable 1D antisymmetric states into stable symmetric ones, at $x_0 = 1$ and $\alpha = 0.5$: (a) $\mu = 6.5$; (b) $\mu = 15$.

Figure 6. (a) A typical example of the first excited 1D symmetric state, for $x_0 = 1$, $\mu = 5$ and $\alpha = 0.5$. It is stable at $\mu < 4.523$, i.e., $N < 10.6059$. (b) The respective solution branch $N(\mu)$, for $x_0 = 1$ and $\alpha = 0.5$.
transition to asymmetric solitons in this system was predicted by means of the variational approximation [40, 42] and investigated in a numerical form [41, 42]. The analysis of the SSB in BEC and other models based on the GPE with the DW potential was initiated in [44], and later extended for bosonic Josephson junctions [45–47] and matter-wave solitons [48].

Experimentally, the self-trapping of asymmetric states in the BEC of ⁸⁷Rb atoms loaded into the DW potential, as well as Josephson oscillations in the same setting, were reported in [49]. The SSB of laser beams coupled into an effective transverse DW potential created in a photorefractive medium was demonstrated in [50]. A spontaneously established asymmetric regime of the operation of a symmetrically coupled pair of lasers was reported too [51].

Here, our main objective is to study the SSB of self-trapped modes supported by effective nonlinear (pseudo) potentials. Previously, some results for such settings were

---

**Figure 7.** (a) The stability diagram for the first excited 1D symmetric state (an example of which is shown in figure 6), in the \((\alpha, N)\) plane, for \(x_0 = 1\). As above, the white and gray regions represent stable and unstable solutions, respectively. (b) The evolution of an unstable first excited symmetric state, for \(x_0 = 1\), \(\alpha = 0.5\) and \(\mu = 7\).

**Figure 8.** (a) A typical example of the second excited 1D symmetric state, for \(x_0 = 1\), \(\mu = 5\) and \(\alpha = 0.5\). (b) The \(N(\mu)\) curve for these solutions. The stability segment is \(2.26 < \mu < 11.13\), i.e., \(0.48 < N < 21.93\).
reported in [19, 31], but the systematic analysis based on the
model with the spatially modulated strength of the self-
defocusing nonlinearity was not developed. Because we
consider the models with the defocusing sign of the non-
linearity, the respective symmetric ground state is always
stable and is not subject to the SSB, as mentioned above.
Therefore, we focus on the SSB featured by antisymmetric
(dipole) modes, in the form of the spontaneous breaking of
their spatial antisymmetry. Another manifestation of the SSB
that we address in this work is spontaneous formation of
anisotropic patterns in the 2D isotropic single-well config-
uration, a known example of that in usual models with
the uniform nonlinearity being the creation of azimuthals [52].

Localized solutions to the 1D version of the stationary
equation (4) were obtained in the numerical form by means of
the Newton-Raphson method [53]. Symmetric 1D and 2D
modes were also produced in an approximate analytical form
by means of the Thomas–Fermi approximation (TFA). The

Figure 9. The stability diagram for the second excited 1D symmetric
state, in the (α, N) plane, for x₀ = 1. The solutions are stable in
white regions.

Figure 10. (a) The solid and dotted profiles show, severally, examples of stable and unstable composite 1D asymmetric solutions of the
[k = 0, k = 2] type, for x₀ = 1, μ = 10 and α = 0.5. (b) N(μ) curves of the composite asymmetric states of these types, also for x₀ = 1
and α = 0.5. Two stable(solid) segments were found on the lower branch: at 8.17 < μ < 9.34, i.e., 24.05 < N < 27.98, and at
9.49 < μ < 12.54, i.e., 28.51 < N < 39.38.

Figure 11. The stability diagram of the composite 1D modes of the
[k = 0, k = 0] type in the (α, N) plane, for x₀ = 1. Solutions do not
exist in the dark region at the bottom of the plot. As above, the
solutions are unstable in gray areas.
stability was then studied by adding small perturbations to the stationary solutions, \( e^{i\omega t} \phi_0(x) \), in the form of

\[
\psi(x, z) = e^{i\omega t} \left[ \phi_0(x) + g(x)e^{-i\lambda z} + f(x)e^{i\lambda z} \right].
\]  

(10)

see equation (3), where \( g(x) \) and \( f(x) \) are eigenmodes of the infinitesimal perturbation, \( \lambda \) is the corresponding eigenfrequency, which is complex (in particular, imaginary) in the case of instability, and the asterisk stands for the complex conjugation. Substituting the perturbed solution, (10), in equation (4) and the subsequent linearization results in the following eigenvalue problem:

\[
\begin{pmatrix}
\hat{L} & \sigma(x)(\phi_0(x))^2 \\
-\sigma(x)(\phi_0(x))^2 & -\hat{L}
\end{pmatrix}
\begin{pmatrix}
g(x) \\
f(x)
\end{pmatrix}
= \lambda
\begin{pmatrix}
g(x) \\
f(x)
\end{pmatrix}.
\]  

(11)

with \( \hat{L} = \mu - (1/2)d^2/dx^2 + 2\sigma(x)(\phi_0(x))^2 \). This problem can be solved using the basic finite-difference scheme, thus finding the set of eigenfrequencies \( \lambda \) and determining the

Figure 12. The Hamiltonian-versus-norm curves for families of 1D states, at \( x_0 = 1 \) and \( \alpha = 0.5 \). Continuous and dotted lines refer to stable and unstable solutions, respectively. Panel (a) exhibits the curves for the basic symmetric, antisymmetric and asymmetric states. The composite asymmetric state of the \( [k = 0, k = 2] \) type, as well as the first and second excited symmetric modes, are presented in panel (b) (the curve for the basic symmetric solutions, which represent the ground state, is included in both panels, for the sake of comparison).

Figure 13. Stability diagrams for 1D asymmetric modes, obtained with the generalized nonlinearity-modulation profile (8), for \( \sigma_2 = 2, x_0 = 1, \beta = 1 \), and (a) \( \sigma_0 = 1 \) or (b) \( \sigma_0 = 0 \). White and gray regions represent, as before, stable and unstable solutions, respectively. The asymmetric solutions do not exist in the dark region at the bottom of the plots, below the bifurcation of the antisymmetric mode.
stability of the underlying solution. In addition, direct numerical simulations of initially perturbed solutions are performed by means of the pseudospectral split-step Fourier method, to verify the predicted stability, as well as to explore the evolution of unstable states. The direct simulations were run with absorbers installed at edges of the computation domain. In the 2D setting, stationary solutions were obtained by dint of the modified squared-operator method introduced in [54] (see also book [53]), and the stability was then investigated primarily through direct simulations.

The rest of the paper is organized as follows. The 1D DW setting and the SSB effect in it are considered in section 2. The dynamics of trapped modes in a single rocking (periodically moving) 1D well is addressed in section 3. Various stable and unstable states trapped in the single- and double-well structures in 2D are considered in sections 4 and 5, respectively. The paper is concluded by section 6.
2. The one-dimensional setting

2.1. Basic 1D states: symmetric, anti-symmetric, and asymmetric solitons

The 1D version of model (4), with the simplest DW modulation profile taken as the 1D variant of equation (9),

\[ \sigma(x) = \exp \left[ \alpha \left( |x| - x_0 \right)^2 \right], \tag{12} \]

gives rise to basic families of symmetric, antisymmetric and asymmetric (antisymmetry-breaking) states. Typical examples of shapes of these three types are presented in figure 1, for \( \alpha = 0.5 \), \( x_0 = 1 \) and \( \mu = 5 \).

The symmetric solutions, which represent the ground state of the model (see below), can be analytically approximated by means of the TFA, which was efficiently applied to the description of ground states in 1D, 2D, and 3D versions of the model with the single-well structure [22–27], [30]. The TFA neglects the kinetic-energy term (the second-order derivative) in the 1D version of equation (4), with \( \sigma(x) \) substituted by expression (12):

\[ \phi_{\text{TFA}}(x) = \sqrt{\mu} \exp \left[ -(\alpha/2) \left( |x| - x_0 \right)^2 \right]. \tag{13} \]
The respective approximation for the norm of the symmetric modes is

\[ N_{\text{TFA}}(\mu) = \sqrt{\pi/\alpha} \mu \left[ 1 + \text{erf} \left( \sqrt{\pi} x_0 \right) \right], \tag{14} \]

where \( \text{erf} \) is the standard error function. The comparison of the TFA profile with its numerically generated counterpart is displayed in Figure 1.

The stability investigation was conducted for all the three basic families, by numerically solving the eigenvalue problem based on equation (11), at different values of \( \mu \) (i.e., different norms \( N \)), and different values of parameters \( x_0 \) and \( \alpha \). It has been found that the symmetric family, which does not undergo any bifurcation, is completely stable.

The antisymmetric solutions are stable for low values of \( \mu \) (sufficiently small \( N \)). Increasing \( \mu \), one hits a bifurcation point, above which the antisymmetric state loses its stability and a new asymmetric (antisymmetry-breaking) branch emerges. This asymmetric branch may be stable, at least partially, depending on values of \( x_0 \) and \( \alpha \).

Figure 2 demonstrates the stable symmetric branch, as well as the antisymmetric/antisymmetric bifurcation scenario, for \( x_0 = 1 \) and \( \alpha = 0.5 \). As shown in this example, and is true in the general case too, for all values of \( x_0 \) and \( \alpha \) examined, the bifurcation is of the supercritical type, which means that the asymmetric solutions are stable immediately after the bifurcation point. Figure 2 shows that bistability exists between the symmetric and antisymmetric modes, and between the symmetric and asymmetric ones, below and above the bifurcation, respectively.

In the case shown in Figure 2, the asymmetric branch is stable in a limited region, starting from the bifurcation point (at \( \mu = 1.719, N = 4.748 \)) and up to \( \mu = 5.206, N = 17.21 \). The stability domain strongly depends on \( \alpha \), as shown in Figure 3, which displays stability/instability domains for the asymmetric states in the \((\alpha, N)\) plane for \( x_0 = 1 \) [this may be fixed in equation (4) by means of obvious rescaling]. In particular, for \( \alpha < 0.351 \) the asymmetric states are stable in their entire existence region.

Direct simulations, for unstable asymmetric states and unstable antisymmetric ones, demonstrate that they develop an oscillatory instability and eventually converge to stable symmetric modes. The linear stability analysis shows that the instability of asymmetric states (when they are unstable) is accounted for by complex eigenvalues, while the unstable antisymmetric states are characterized by imaginary eigenvalues. With the increase of \( \mu \) (i.e., the increase of the norm), the duration of the intermediate oscillatory evolution shrinks, which is related to the fact that the imaginary part of the stability eigenvalues (i.e., the instability growth rate) increases with the norm. Examples of the evolution of unstable asymmetric states are shown in Figure 4, for \( x_0 = 1, \alpha = 0.5, \) and \( \mu = 6.5 \) or 15. In these examples, the interval of the oscillatory behavior shrinks from \( z < 275 \) at \( \mu = 6.5 \) \((N = 52.12)\), to virtually no oscillations at \( \mu = 15 \) \((N = 55.26)\). Similar results were obtained for unstable

---

**Figure 19.** The period of the Rabi (intrinsic) oscillations of the trapped 1D mode between the dipole and fundamental shapes, \( Z_1 \), as a function of \( N \).

**Figure 20.** Examples of the Rabi oscillations of the 1D trapped mode: (a) \( A_0 = 1, Z_0 = 40 \); (b) \( A_0 = 0.5, Z_0 = 40 \); (c) \( A_0 = 0.5, Z_0 = 10 \). In all the cases, \( N = 7.92 \).
antisymmetric solutions, see figure 5. In this case, the interval of the oscillations shrinks from $20 < z < 215$ at $\mu = 6.5$ ($N = 23.34$) to $10 < z < 75$ at $\mu = 15$ ($N = 57.57$).

In fact, the dynamics observed in figures 4(a) and 5(a) may be regarded as a manifestation of Josephson oscillations in the underlying bosonic coupler [45, 47, 46, 49].

2.2. Novel 1D modes: excited symmetric and composite asymmetric modes

The numerical analysis has revealed several new types of 1D states. One of them is the first excited symmetric state, which is shown in figure 6(a) for $x_0 = 1$, $\mu = 5$ and $\alpha = 0.5$. The classification of this state is based on the consideration of its energy, see below. This solution is actually a composition of two mutually reversed dipole states, centered in each well (this is better seen when the wells are set farther apart). The stability diagram for this type of the solutions is presented in figure 6(b). Note that (completely stable) excited symmetric states with two nodes ($k = 2$) were also found in the model of the same type, but with a single-well shape of the local-nonlinearity modulation [23].

Similar to the asymmetric mode, the stability of the first excited symmetric state strongly depends on $x_0$ and $\alpha$, see figure 7(a), the instability being always accounted for by complex eigenvalues. An example of the evolution of an unstable solution of this type is shown in figure 7(b). Like the unstable asymmetric and antisymmetric states presented above, it converges to a stable symmetric solution.

Also found was a second excited symmetric state, an example of which is shown in figure 8(a) for $x_0 = 1$, $\mu = 5$ and $\alpha = 0.5$. This mode is composed of two $k = 2$ single-well solutions, where, as mentioned above, $k$ is the number of nodes (zeroes) of the 1D mode trapped in the single nonlinear pseudopotential well [23]. Results for this solution family and its stability, for $x_0 = 1$ and $\alpha = 0.5$, are presented in figure 8(b), and the dependence of the solution’s stability on $\alpha$ is shown in figure 9.

Similar to the unstable antisymmetric and asymmetric states considered above, the instability of the second excited
two single-well-based constituents: a fundamental solution on one side \((k = 0)\), and a solution with two nodes \((k = 2)\) on the other. Figure 10(b) exhibits a typical \(N(\mu)\) branch for this type of composite modes. It is seen that the branch consists of two, almost coinciding, curves that merge at a certain point (in the present case, at \(\mu = 8.17, N = 24.07\)), with only the lower curve having a stability segment.

The stability map for this type of the asymmetric composite modes in the plane of \((\alpha, N)\) is shown in figure 11. It exhibits not a single stability region, but a more complex map, with internal instability strips. The dark region at low values of \(N\) (or \(\mu\)) refers to the region where the solutions do not exist, above the merger point of the two branches. Similar to what was shown before for symmetric unstable modes (see figure (7)), the evolution of unstable asymmetric composite modes originally exhibits an oscillatory behavior, leading to transformation into the stable fundamental symmetric mode (not shown here in detail).

The relative stability of the different coexisting modes with equal norms is determined by the comparison of their Hamiltonians, given by the 1D version of equation (2). The respective \(H(N)\) curves for all the above-mentioned 1D solutions are displayed in figure 12, for \(x_0 = 1, \alpha = 0.5\). As expected, the ground state, with the lowest value of the Hamiltonian, corresponds to the basic symmetric solution, while the first and second excited symmetric states have, respectively, higher values of \(H\).

2.3. The general 1D model: asymmetric modes

In addition to the detailed investigation reported above for the simplest version of the DW profile, based on equation (9), a partial analysis has been performed for the more general profile corresponding to equation (8). Specifically, we have examined the influence of parameters \(\sigma_0\) and \(\sigma_2\) on the...
stability of the asymmetric state. Figure 13(a) displays the respective stability diagram in the $N_a$ plane, with $1_{11} = 2.2$ and $0 = 0$.

Similar results were also obtained for $1_{11} = (not shown here). As seen in figure 13(a), asymmetric solutions were found for all values of $\alpha$, provided that the soliton’s norm is high enough (an expected outcome, as the effective DW potential depends on $N$). The stability region expands with the increase of $\alpha$, opposite to what is reported above for the simplified profile (9), see figure 13(a).

When the constant term is absent, $c_0 = 0$, the stability map features alternating stability and instability strips, as seen in figure 13(b). For the same parameters, but with $c_0 = 1$ (figure 13(a)), the striped pattern, barely observed at small values of $\alpha$, is much less salient.

3. A rocking one-dimensional potential well

It is natural to extend the consideration of modes trapped in the single (pseudo)potential well to the case when the well is subject to rocking motion, which corresponds to

$$
\sigma(z) = \exp \left[ \alpha \left( x - A_0 \cos(W_0z)^2 \right) \right]
$$

in the 1D version of equation (1), where the $A_0$ and $W_0$ are the rocking amplitude and frequency. In the optical realization, this corresponds to the planar waveguide with an undular guiding channel (in the plane of $(z, x)$), written by the local modulation of the defocusing nonlinearity [55]. In the case of BEC, the rocking implies oscillatory motion of the nonlinearity-modulation profile, which can be readily implemented if the modulation is induced by the optically controlled Feshbach resonance [11], as the controlling laser beam may be made moving [13].

Here, we focus on the fundamental and first-order (dipole) modes, both well-known to be stable in the static model [22]. In all the examples shown below, we fix $\alpha = 0.5$, while the parameters of the rocking well were taken in ranges $0 < A_0 < 4$ and $2\pi/40 < W_0 < 2\pi$.

Starting with the fundamental modes, two evolution scenarios can be identified, depending on the initial value of

---

**Figure 25.** The amplitude (a) and phase (b) structure of a vortex triangle supported by the single 2D nonlinear potential well, at $\alpha = 0.5$, $\mu = 7$ ($N = 25.86$). This mode is weakly unstable, see figure 26 below.

**Figure 26.** The $N(\mu)$ curves, demonstrating, for $\alpha = 0.5$, the bifurcation of the the VT (vortex-triangle) branch (the bottom panel), from the family of ordinary stable vortices with topological charge $m = 2$ (the upper panel; the curves are displayed in the different panels, as they would otherwise completely overlap). The circles mark, in both panels, the bifurcation point, at $\mu = 5.73$, $N = 19.2$. As before, solid and dotted lines refer to stable and unstable solutions, respectively. The short dashed bold segment refers to spinning VTs.
Figure 27. The evolution of a robust vortex triangle, trapped in the single nonlinear potential well, at $\alpha = 0.5$ and $\mu = 6$ ($N = 20.58$), with an initial perturbation that slightly increases its norm. The result is a triangle steadily rotating in the clockwise direction.

Figure 28. The evolution of an unstable vortex triangle at $\alpha = 0.5$ and $\mu = 7$ ($N = 25.86$).

Figure 29. An example of the amplitude (a) and phase (b) structure of an unstable vortex hexagon trapped in a single nonlinear potential well, for $\mu = 10$, $\alpha = 0.5$. 

N Dror and B A Malomed
the norm, $N$ (or $\mu$), and parameters $A_0$ and $W_0$. Namely, for the rocking period, $Z_0 = 2\pi/W_0$, exceeding a certain threshold value, the mode adiabatically follows the slowly rocking nonlinear well, maintaining its original shape. An example is shown in figure 14.

On the other hand, for period $Z_0$ below this threshold, the shape of the initial fundamental soliton is not kept. In this case, the evolution of the solution is not smooth, and may exhibit different oscillatory patterns. Examples are shown in figure 15 for $\mu = 5$, $A_0 = 1$ and $Z_0 = 4$ and 5. Further, the dependence of the threshold value of the rocking period on the rocking amplitude, $A_0$, is shown in figure 16, for two fixed values of the norm.

The evolution of the trapped dipole mode also turns out to be different above and below the threshold value of the rocking period, which is found to be virtually indistinguishable from the one shown in figure 16 for the fundamental solution. Below the threshold, the dipoles quickly transform into single-peak or fragmented patterns, which are quite similar to those observed in the case of the fundamental mode, see typical examples in figure 17 for $\mu = 5$, $A_0 = 1$ and $Z_0 = 4$ or 5.

On the other hand, when the rocking period is taken above the threshold, the mode periodically switches between the initial dipole shape and the fundamental soliton. This scenario, which may be considered as Rabi oscillations
between the two soliton species (dipole and fundamental ones) in the rocking (pseudo)potential well [56], is demonstrated in figure 18 for $N = 7.92$ (the respective propagation constant, corresponding to the dipole mode in the absence of the rocking, is $\mu = 5$).

Unlike the destructive oscillations below the threshold (see figure 17), the frequency of the Rabi oscillations above the threshold is different from the rocking frequency, $W_0$. Figure 19 shows the period of the intrinsic Rabi oscillations of the trapped mode, $Z_0$, as a function of $N$. Detailed numerical analysis demonstrates that $Z_0$ is insensitive to the rocking parameters, $Z_0$ and $A_0$. This feature is demonstrated in figure 20, where the frequency of the Rabi oscillations remains constant, while the rocking frequency varies. Thus, the Rabi oscillations between the fundamental and dipole states are actually a dynamical feature of the system based on the stationary profile of the nonlinearity modulation, while the rocking motion is a drive which helps to excite the oscillations.

Actually, the Rabi oscillations are not completely robust. Gradually, the oscillations fade away, and the trapped mode slowly relaxes into the fundamental solution. The evolution period in the course of which the Rabi oscillations remain conspicuous reduces with the increase of the underlying rocking amplitude, $A_0$, and frequency, $W_0$.

4. The two-dimensional setting: the single-well nonlinear potential

The existence and stability of the axially symmetric states, both fundamental (zero-vorticity) ones and vortices with a nonzero topological charge, in the 2D model with the isotropic single-well modulation profile, based on equation (7) with $r_0 = 0$, including the simplified version (6), were reported in [23]. In this section we introduce and briefly consider additional higher-order modes, both non-topological and topological ones, which demonstrate the SSB effect in the form of spontaneous breaking of the axial symmetry. This setting, which is fundamental by itself, deserves a detailed study, results of which will be reported elsewhere [57].

Examples of first-, second- and third-order states, which may be interpreted, respectively, as dipoles, ‘string tripoles’ and ‘string quadrupoles’, are displayed in figure 21, for $\mu = 5$ and $\alpha = 0.5$, the respective $N(\mu)$ curves being shown, for

![Figure 32](image-url) (a) and (b) Amplitude and phase profiles of the semi-vortex composite state, built of a vortex with topological charge $m = 1$ trapped in the left well, and a fundamental soliton trapped in the right well, for $x_0 = 2.5, \mu = 5$ and $\alpha = 0.5$. The respective $N(\mu)$ and $N(x_0)$ curves are displayed in panels (c) and (d), fixing $\alpha = 0.5$ and $x_0 = 0.5$ or $\mu = 5$, respectively.
\( \alpha = 0.5, \) in panel (d) of the figure. Direct simulations have demonstrated that families of the second- and third-order solutions are entirely unstable, and it is reasonable to conclude that their counterparts of still higher orders are unstable too. The instability-induced evolution transforms the unstable modes into the ground state, as shown in figure 22 for an unstable dipole. On the other hand, as shown in figure 23, dipoles have a narrow stability interval at small values of \( \mu \) (or \( N \)) (to the left of the red dot in the figure), which will be reported in detail in another work [57].

More interesting 2D topological states trapped in the single nonlinear potential well are vortex-antivortex dipoles (VADs), shaped as fundamental solutions with an embedded pair of vortical holes carrying opposite topological charges, \( \pm 1 \), so that the total charge is zero, see an example in figure 24 for \( \mu = 5 \) and \( \alpha = 0.5 \). Systematic results for this family will be presented in [57]. In particular, it bifurcates, as a stable branch, from the family of the above-mentioned ordinary (fundamental) dipoles, as shown in figure 23. With the increase of \( \mu \) and \( N \), the VAD gets destabilized by oscillatory perturbations, and then restabilizes.

The branch of \( m = 2 \) vortices gives rise, via a bifurcation, to another anisotropic topologically charged mode trapped in the single nonlinear potential well, namely, vortex triangles (VTs), see an example in figure 25 for \( \mu = 7, \alpha = 0.5 \). As shown in figure 26, this family indeed bifurcates, at

\[
\mu = 5.73, \quad N = 19.2
\]

(16)

(if \( \alpha = 0.5 \) is fixed), from the ordinary stable vortex branch with \( m = 2 \), which was constructed, in the framework of the present model, in [23]. Figure 25(b) confirms that, following its parent vortex mode, the VT carries topological charge \( m = 2 \). The fact that the triangular vortical state emerges from the double-charged vortex is a counter-intuitive manifestation of the SSB in the present setting, which, however, does not contradict general principles. Note that the present VT modes are different from rotating triangles built of well-separated unitary vortices, which were observed, as a dynamical regime initiated by splitting of unstable vortices with topological charge \( m = 3 \) (rather than \( m = 2 \)), in the same model [23].
The stability analysis of the VTs demonstrates that, strictly speaking, the entire family is unstable. Further, direct simulations of the perturbed evolution demonstrate that, starting from bifurcation point \( \mu = 16 \), at which this branch appears, and up to \( \mu = 6.55 \) \((N = 23.43)\), the VT exhibits rotation, as a robust object, at an angular velocity whose value depends on the initial perturbation. The rotation interval is designated by the short dashed bold segment in the bottom panel of figure 26. An example for such a spinning VT is shown in figure 27 for \( \mu = 6.55 \).

At \( \mu > 6.55 \), the VTs develop real instability, evolving into the above-mentioned stable VADs, see an example in figure 28, or into the ground state, as observed above for other species of unstable modes.

The systematic numerical analysis has revealed other species of anisotropic modes trapped in the single isotropic nonlinear potential well. In particular, bound states of multiple (more than three) vortices were observed. One such species, a ‘vortex hexagon’ with zero total topological charge, is shown in figure 29, bifurcates from the unstable branch of tripoles from figure 21(b). This state, as well all other bound states of many vortices, are completely unstable.

Another type of solutions, in the form of isotropic higher-order (alias, excited) radial states of vortices, were found too, for the first time in the model of the present type. An example of an excited radial state of the vortex solution, with \( n = 1 \) and one radial node (zero), is shown in figure 30. These solutions are unstable too, relaxing into the stable basic vortices (with the node-free radial structure).

5. The two-dimensional setting: the double-well nonlinear potential

5.1. Zero-vorticity states

The most essential object of the 2D analysis is the model with the DW nonlinearity profile, represented by equation (9), focusing on SSB scenarios in this setting (see a 2D DW profile based on the spatial modulation of the self-focusing nonlinearity, which was introduced in [21]). The respective fundamental symmetric state is illustrated by figure 31(a), for \( \mu = 5, \alpha = 0.5 \) and \( x_0 = 1 \). Direct simulations have shown that this state is stable for all values of \( x_0, \mu \) and \( \alpha \), with the respective \( N(\mu) \) curve for \( \alpha = 0.5 \) and \( x_0 = 1 \) displayed in figure 31(c).
This 2D symmetric state can be easily found in the approximate form in the framework of the TFA, see its 1D version (13):

\[ \phi_{\text{TFA}}(x, y) = \sqrt{\mu} \exp \left\{ -\frac{\alpha}{2} \left( |x| - x_0 \right)^2 + y^2 \right\}, \]

(17)

the corresponding approximation for the norm being [see the 1D result (14)]:

\[ N_{\text{TFA}}(\mu) = (\pi/\alpha)\mu \left[ 1 + \text{erf} \left( \sqrt{\pi}x_0 \right) \right]. \]

(18)

The latter result readily explains the nearly linear numerically found dependence \( N(\mu) \) displayed in figures 31(a) and (c). Antisymmetric zero-vorticity states, as well as asymmetric ones bifurcating from them, have been found too, but they turn out to be completely unstable (not shown here in detail), unlike their 1D counterparts, see figures 2 and 3. In direct simulations, unstable states of these type spontaneously rearrange into stable symmetric modes.

5.2. Semi-vortices trapped in the double-well potential

Stable semi-vortex 2D states can be composed of fundamental and vortex modes supported, severally, by the two nonlinear wells. A representative example, built of the fundamental solution and the vortex with topological charge \( m = 1 \), is displayed in figures 32(a) and (b), for \( x_0 = 2.5, \mu = 5 \) and \( \alpha = 0.5 \). The \( N(x_0) \) curves, with \( \mu = 5 \) for the complexes of these two types are displayed in panels (e) and (f), respectively.

Figure 35. Examples of dual-vortex complexes with topological-charge sets (+1, -1) (a), (b) and (+1, +1) (c), (d), for \( x_0 = 2.5, \mu = 5 \) and \( \alpha = 0.5 \). The \( N(x_0) \) curves, with \( \mu = 5 \) for the complexes of these two types are displayed in panels (e) and (f), respectively.

In direct simulations, those semi-vortices with \( m = 2 \) which are unstable turn into a stable complex built of a single-well fundamental state in one well and a VAD supported by the other. Following this observation, two different
combinations of the fundamental soliton and VAD, supported by the individual wells, were investigated in detail: horizontal and vertical ones, with the line connecting centers of the two vortices (which built the VAD) oriented, respectively, parallel or perpendicular to the axis of the two-well configuration, see figures 34(a)–(d), respectively. The former species is partially stable: for instance, at $x_0 = 2.5$, $m = 7$ and $\alpha = 0.5$. When fixing $x_0 = 2$, the stability region is $2.96 < m < 26.38$ (figure 34(f)), while for $x_0 = 1.5$ the solution is entirely unstable. Complexes of the latter (perpendicular) type are always unstable, which can be understood, as only a horizontally aligned dipole may realize an energy minimum in the present setting. In both cases, unstable complexes converge to the ground-state symmetric modes.

5.3. Dual-vortex configurations supported by the DW potential

Dual-vortex complexes, composed of vortices with $|m| = 1$ trapped in the two wells, were constructed too. Figures 35(a)–(d) show examples of such complexes, built of individual vortices with topological charges $(m = +1, m = -1)$ or $(m = +1, m = +1)$, so that the respective total charges are 0 or 2. In both cases, the results are similar: the solutions are unstable at $x_0 = 2$, and stable at $x_0 = 2.5$. Fixing $\mu = 5$, the $(+1, -1)$ complex is stable for $x_0 > 2.31$, $N > 46.38$ (figure 35(e)), while its counterpart of the $(+1, +1)$ type is stable at $x_0 > 2.26$, $N > 46.21$ (figure 35(f)). In this case too, unstable solutions transform themselves into symmetric ground-state modes.

Dual-vortex complexes built of vortices with $|m| = 2$ were also addressed. In both cases of topological-charge sets $(+2, -2)$ and $(+2, +2)$, the transition (bifurcation) from the individual double vortices to the VTs occurs, thus giving rise to additional dual-VT complexes. An example of the complex for the charge set $(+2, -2)$ is displayed in figures 36(a) and (b), with the respective bifurcation diagram shown in figure 36(e). In this case, the dual-vortex complexes are stable at $5.71 < \mu < 7.96$, i.e., $37.92 < N < 61.73$. Further, an example of the related dual-VT complex, with the same charge set, $(+2, -2)$, and the same parameters is presented in figures 36(c) and (d). The dual-VT complexes of this type are stable at $3.05 < \mu < 6.07$, i.e., $12.69 < N < 41.52$. For $\mu = 5$ and varying $x_0$, the dual-vortex complexes with topological charges $(+2, -2)$ are stable at $x_0 > 2.40$ for fixed

Figure 36. Dual-vortex complexes with topological charges $(+2, -2)$, built of two single-well vortices (a), (b), or vortex triangles (c), (d), for $x_0 = 2.5$, $\mu = 7$ and $\alpha = 0.5$. (e) The respective $N(\mu)$ curves, for $x_0 = 2.5$ and $\alpha = 0.5$. (f) The $N(x_0)$ curve, for the dual-vortex complexes at fixed $\mu = 5$. 

J. Opt. 18 (2016) 014003 N Dror and B A Malomed
$\mu = 0.5$, as shown in figure 36(f) (in this case, VTs do not exist, as they are generated by the bifurcation at larger values of $\mu$).

Similar results for the complexes pertaining to the topological-charge set $(+2, +2)$ are presented in figure 37. Here, for $x_0 = 2.5$, the dual-vortex complexes, and ones built of the VTs, are stable at $6.74 < \mu < 7.71$, i.e., $48.37 < N < 58.82$, and $4.47 < \mu < 5.54$, i.e., $25.30 < N < 35.87$, respectively. For $\mu = 5$, the solutions are stable at $x_0 > 2.45$, as shown in figure 37(f).

A conspicuous difference of the configuration with the charge set $(+2, +2)$ from the above one with charges $(+2, -2)$, observed in figure 37(a) (see figure 36(a)), is relatively strong deformation of cores of both left and right vortices. This is explained by attractive and destructive interference of overlapping fields of the vortices in the gap between their cores, in the cases of opposite and identical signs of the two vorticities, respectively. Indeed, in the latter case the destructive interference removes the field from the gap, making inner boundaries of the cores nearly flat, as seen in figure 37(a). A similar argument helps to understand the difference between the mutual orientations of the VTs, which is observed in figures 36(c) and 37(c): the interferometric removal of the field from the inter-core gap in the configuration case makes it possible to keep the empty corners inside the gap.

It is relevant to mention too that the stability regions are somewhat smaller for the complexes with the charge set $(+2, +2)$ than for their counterparts with charges $(+2, -2)$. Note that the difference between the dual-vortex complexes corresponding to charge sets $(+m, -m)$ and $(+m, +m)$ is much smaller in the case of $m = 1$ than for $m = 2$, see figure 35. This is explained by the fact that the size of the vortex core is essentially smaller for $m = 1$.

All the complexes with $|m| = 2$ are completely unstable at $x_0 = 2$. Direct simulations show that unstable solutions of these types transform themselves into the ground-state symmetric state, or into symmetric complexes of VADs (their description is following below). On the contrary to the VTs in the single-well case (see figure 27), the triangles forming stable dual-VT complexes in the DW potential do not exhibit rotation when perturbations are added to the initial configuration.

Dual-vortex composites, constructed of an $|m| = 1$ vortex trapped in one well, and an $|m| = 2$ vortex in the other, were also investigated. In this configuration, two families, with topological charges $(+1, +2)$ and $(-1, +2)$, were examined. Similar to the dual vortex complexes with $|m| = 2$
mentioned above, bifurcations of structures, with the same
charges, where VTs replace the vortex with |m| = 2, are
observed. An example of the vortex–vortex complex with the
charge set (+1, +2) is demonstrated in figures 38(a) and (b),
for μ = 7 and x0 = 2.5. For this charge set, the bifurcation
diagram in the (N, μ) plane is displayed in figure 38(e) for
x0 = 2.5. In this case, the vortex–vortex complexes are stable
at 6.58 < μ < 7.84, i.e., 56.02 < N < 70.36. The corre-
sponding vortex-VT complexes with charges (+1, +2),
demonstrated in figures 38(c) and (d) for μ = 7 and x0 = 2.5,
are stable at 3.01 < μ < 5.91, i.e., 17.85 < N < 48.50.
When fixing μ = 5 and varying x0, the complexes with
topological charges (+1, +2) are stable at x0 > 2.29.

Equivalent results were also observed for the other charge set, (−1, +2), see figure 39. Examples of the vortex–
vortex and vortex-VT structures, in this topological setting,
are displayed in figures 38(a)–(d), respectively, for μ = 7 and
x0 = 2.5. For x0 = 2.5, the vortex–vortex complexes are
stable at 6.07 < μ < 9.07, i.e., 50.41 < N < 84.65, and the
vortex-VT ones are stable at 2.11 < μ < 6.24, i.e.,
9.69 < N < 52.27 (figure 39(e)). As seen in figure 39(f), for
fixed μ = 5, the stability holds at x0 > 2.36.

Lastly, four combinations of VADs, of the horizontal and
vertical types, as well as with identical or opposite orienta-
tions of the left and right dipoles, were constructed and
analyzed too, see figures 40(a)–(h). A single species among
them which was found to be partly stable corresponds to the
horizontal structure shown in figures 40(c) and (d), in which
the left and right components have opposite signs (recall that
the semi-vortex complex with a VAD component may also be
stable solely in the case when this component is horizontal,
see figure 34; an explanation for the feasible stability of the
horizontal structure in the present case is essentially the same,
as only the horizontal orientation of the dipoles may realize an
energy minimum). For this solution, the N(μ) curve, with
fixed x0 = 3 (figure 40(i)), and the N(x0) one, with fixed
μ = 5 (figure 40(j)), exhibit stability regions at μ > 5.15 and
x0 > 3.05, respectively. The unstable solutions evolve into
the symmetric ground-state mode, or, in some cases, into
stable combinations of VADs. In addition to these four
complexes built of parallel VADs, another one, composed of
a vertical VAD in one well and a horizontal VAD in the other,
was also constructed. This state (which is not shown here), is
totally unstable.
To complete the study of dual-vortex complexes, it is relevant to mention that ones of both \((+m, -m)\) and \((+m, +m)\) types, composed of vortices proper (with \(m = 1\) and 2) or VTs, as well as the VAD complexes with identical or opposite orientations, do not demonstrate spontaneous breaking of their symmetry or antisymmetry with respect to the underlying DW structure, in the entire parameter region explored in our analysis. Recall that, as mentioned above, antisymmetric complexes composed of 2D fundamental modes feature spontaneous breaking of the antisymmetry, but both the resulting asymmetric complexes and the antisymmetric parent ones are completely unstable.

6. Conclusion

The purpose of this work is to extend the analysis of the recently introduced class of models which admit self-trapping of stable solitons, vortices, and more complex topologically structured modes, with the help the defocusing cubic nonlinearity whose local strength grows fast enough from the center to periphery. In addition to the previously studied models with the single-well profile of the nonlinearity modulation, we have introduced the DW settings in the 1D and 2D geometry, which may be realized in nonlinear optics and BEC. In both cases of the single- and double-well profiles, we have investigated various scenarios of the spontaneous formation of self-trapped modes, both nontopological and topological ones, whose symmetry may be lower than that of the underlying modulation pattern, due to the occurrence of the SSB in these systems. In particular, in the 2D single-well setting we have found unstable tripole and quadrupole modes and, on the other hand, partly stable ordinary (fundamental) dipoles, VADs and VTs. The most essential results are reported for the DW settings, in 1D and 2D alike. Due to the repulsive sign of the nonlinearity, symmetric modes are always stable, realizing the system’s ground state. However, the antisymmetric (dipole) states are subject to the SSB (more accurately speaking, this is spontaneous breaking of the antisymmetry). The resulting asymmetric states are partly stable in 1D, but unstable in 2D. While most results have been obtained in a numerical form, the 1D and 2D symmetric states were analyzed by means of the TFA. Stability domains have been identified for diverse 2D semi-vortex and dual-vortex configurations, built of vortices with topological charges \(m = 1\) and 2, VTs.
and VADs, trapped in each individual nonlinear potential well of the DW structure.

In the framework of the 1D system, we have also considered the model with the rocking single well. If the rocking period is large enough, the originally trapped dipole mode features Rabi oscillations between the fundamental (single-peak) and dipole shapes. In the 2D model, it may be interesting to introduce a system of three (rather than two) nonlinear-potential wells, which form an equilateral triangle, as such a configuration realizes the most fundamental 2D setting (simplex) [58]. On the other hand, in terms of the BEC model, a challenging problem is to consider 3D configurations generalizing their 2D counterparts [25–27].

References

[1] Kivshar Y S and Agrawal G P 2003 Optical Solitons: From Fibers to Photonic Crystals (San Diego: Academic)
[2] Talanov V I 1970 Pis’ma Zh. Eksp. Teor. Fiz. 11 303
   Talanov V I 1970 JETP Lett. 11 199
[3] Chiao R Y, Garmire E and Townes C H 1964 Phys. Rev. Lett. 13 479
[4] Bergé L 1998 Phys. Rep. 303 259
[5] Kh Abdullaev F and Salerno M 2005 Phys. Rev. A 72 033617
[6] Harrison W A 1966 Pseudopotentials in the Theory of Metals (New York: Benjamin)
[7] Giorgini S, Pitaevski L P and Stringari S 2008 Rev. Mod. Phys. 80 1215
[48] Matuszewski M, Malomed B A and Trippebach M 2007 Phys. Rev. A 75 063621
[49] Albiez M, Gati R, Fölling J, Hunsmann S, Cristiani M and Oberthaler M K 2005 Phys. Rev. Lett. 95 010402
[50] Kevrekidis P G, Chen Z, Malomed B A, Frantzeskakis D J and Weinstein M I 2005 Phys. Lett. A 340 275
[51] Heil T, Fischer I, Elsässer W, Mulet J and Mirasso C R 2001 Phys. Rev. Lett. 86 795
Hamel P, Haddadi S, Raineri F, Monnier P, Beaudoin G, Sagnes I, Levenson A and Yacomotti A M 2015 Nat. Photonics 9 311
[52] Desyatnikov A S, Sukhorukov A A and Kivshar Y S 2005 Phys. Rev. Lett. 95 203904
[53] Yang J 2010 Nonlinear Waves in Integrable and Nonintegrable Systems (Philadelphia: SIAM)
[54] Lakoba T I and Yang J 2007 J. Comput. Phys. 226 1668
Yang J and Lakoba T I 2007 Stud. Appl. Math. 118 153
[55] Garanovich I L, Longhi S, Sukhorukov A A and Kivshar Y S 2012 Phys. Rep. 518 1
[56] Gubeskys A, Malomed B A and Merhasin I M 2005 Stud. Appl. Math. 115 255
Kartashov Y V, Vysloukh V A and Torner L 2007 Phys. Rev. Lett. 99 233903
Makris K G, Christodoulides D N, Peleg O, Segev M and Kip D 2008 Opt. Express 16 10309
Dreisow F, Szameit A, Heinrich M, Pertsch T, Nolte S, Tünnermann A and Longhi S 2009 Phys. Rev. Lett. 102 076802
Kanna T, Mareeswaran R B, Tsitoura F, Nistazakis H E and Frantzeskakis D J 2013 J. Phys. A: Math. Theor. 46 475201
[57] Driben R, Dror N, Malomed B A and Meier T 2015 New J. Phys. 17 083043
[58] Lahaye T, Pfau T and Santos L 2010 Phys. Rev. Lett. 104 170404