Tensor-Structured Coupled Cluster Theory

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We derive and implement a new way of solving coupled cluster equations with lower computational scaling. Our method is based on decomposition of both amplitudes and two electron integrals, using a combination of tensor hypercontraction and canonical polyadic decomposition. While the original theory scales as $O(N^6)$ with respect to the number of basis functions, we demonstrate numerically that we achieve sub-millihartree difference from the original theory with $O(N^4)$ scaling. This is accomplished by solving directly for the factors that decompose the cluster operator. The proposed scheme is quite general and can be easily extended to other many-body methods.

I. INTRODUCTION

Many basic building blocks of quantum theories are tensors. Examples include the one- and two-electron integrals defining the Hamiltonian or the cluster operators of coupled cluster (CC) theory, which instead define the wave function. Unfortunately, algebraic manipulations with tensors have a significant numerical cost, which tends to grow exponentially with the dimension $d$ of the tensors and often makes these manipulations the computational bottleneck of the theories.

The cost of tensor manipulations can be significantly reduced by some form of tensor decomposition in which a $d$-dimensional tensor is expressed in terms of lower dimensional objects. For example, the resolution of identity (RI, see Ref. [1] and references therein) can be used to decompose the two-electron integrals. More recently, the tensor hypercontraction (THC) scheme of Hohenstein, Parrish, and Martinez has been introduced. There, a fourth-order tensor is represented by a contraction of five factor matrices, some of which can be the same if one wants to enforce symmetries of the original tensor. Related to THC is the canonical polyadic decomposition (CPD), which as we will explain later can be regarded as its building block.

These tensor decompositions have been used in various ways to introduce low-scaling versions of conventional electronic structure methods. Tensor hypercontraction has been applied by Hohenstein and Kokkilä to the CC2 method, where it was used to represent an electron interaction potential. Shenvi et al. did the same in their Reduced Density Matrix algorithm. Benedict et al. used polyadic composition of amplitudes and electron interaction integrals in the coupled cluster doubles and full configuration interaction methods. While working on this manuscript we also learned about the recent work of Hummel et al. who showed that by using THC of the electron interaction in the context of the distinguishable cluster doubles or linearized coupled cluster singles and doubles methods, one can achieve a reduction of the computational cost from $O(N^9)$ to $O(N^5)$, where $N$ is the number of basis functions.

Here we apply tensor decompositions based on the THC to coupled cluster with single and double excitations (CCSD). The cost of the original CCSD scales as $O(N^6)$, but by using tensor decomposition we can reduce the cost to scale as $O(N^4)$. In most previous applications, THC was used to decompose the electron repulsion integrals, and grids in real space were employed to build the decomposition. We show how to build the THC algebraically for the full fourth-order tensor in $O(N^5)$ cost, or $O(N^4)$ cost if the resolution of identity is employed, and compare different ways of doing so. We also explain how to optimize all factors of the THC in $O(N^4)$ cost when solving iterative equations with decomposed tensors, such as in the CCSD method. By optimizing all factors of the THC, our implementation achieves the same $\sim$ 0.5 millihartree accuracy as previous work which used the THC but with ranks which are roughly half as large. However, we should emphasize that our method is general and is not limited to THC; rather, it can be used with any suitable tensor decomposition.

II. NOTATION AND TERMINOLOGY

Throughout this work we will use notation and diagrams which are common in the literature of tensor decompositions but which may be unfamiliar to the quantum chemistry community. A short review of our diagrammatic notation is available in Appendix A; we summarize our notation and terminology here.

One of the most basic properties of a tensor $T$ is its order, which is just its dimensionality and corresponds to the number of indices in its basis representation. Thus, a four-index object (if a tensor) corresponds with a fourth-order tensor. We sometimes refer to a first-order tensor as a vector and a second-order tensor as a matrix. Generally we denote matrices and tensors by capital letters, and vectors by boldface lower-case letters.

The rank of a tensor is the dimension of the auxiliary indices used in a particular tensor decomposition. As there are a great variety of tensor decompositions, the rank of a high-order tensor is not defined as strictly as in the case of matrices, and may consist of one number or a...
set of numbers; for our purposes, if the tensor has more than one rank it is convenient to require all its ranks to be equal. Different definitions of tensor rank have significantly different properties; for more information consult the review of Kolda et al. It should be clear from context what dimensions are meant in each particular case in the text.

The Frobenius norm of a tensor $T$ is denoted as $\|T\|$ and is given by

$$
\|T\| = \sqrt{\sum_{pqrs...} T_{pqrs...}^* T_{pqrs...}}
$$

where the superscript $*$ denotes complex conjugation; thus, it is simply the square root of the sum of the squares of the tensor’s entries.

We will require a few kinds of tensor product in this work. The Kronecker product is written as $\otimes$, and is defined via

$$
C = A \otimes B \iff C_{rp,sq} = A_{p,q} \cdot B_{r,s}.
$$

It is also convenient to introduce a column-wise Kronecker product known as the Khatri-Rao product; this is denoted by $\odot$ and is defined as

$$
D = A \odot B \iff D_{qp,\alpha} = A_{p,\alpha} \cdot B_{q,\alpha}.
$$

In the foregoing and throughout this manuscript, indices $p, q, r, s, \ldots$ correspond to general orbital labels and Greek letters $\alpha, \beta, \gamma, \ldots$ denote indices of the CPD, THC, and singular value decompositions. We follow the traditional notation that the indices $i, j, k, l \ldots$ represent occupied orbitals specifically, while $a, b, c, d \ldots$ represent virtual orbitals. We also use composite indices such as $pq$ which are defined as

$$
pq \equiv p + \dim(\{p\}) \cdot (q - 1).
$$

Curly braces $\{\}$ denote sets and $\dim()$ means the number of elements in the set.

Finally, summation is implied for any indices which appear more than once within a product. The transpose of a matrix $M$ is $M^T$ and its inverse is $M^{-1}$; if $M$ is singular or not square $M^{-1}$ refers to the pseudoinverse of $M$. We will use $\sqrt{()}$ for the element-wise square root operation:

$$
\sqrt{M}_{pq} = \sqrt{M_{pq}}.
$$

### III. TENSOR DECOMPOSITIONS

The tensor hypercontraction decomposition can be regarded as a combination of two well-established factorizations: a rank decomposition of a matrix such as the eigenvalue or singular value decomposition (SVD) on the one hand and the canonical polyadic decomposition of third order tensors on the other. Thus, we first discuss these two ideas.

#### A. Resolution of Identity and Singular Value Decomposition

The computation of a rank-revealing decomposition for the electron interaction tensor is well studied and is known by the names of the resolution of identity (RI) or density fitting method. By introducing an auxiliary basis, the Coulomb interaction can be written as a contraction of three tensors

$$
V_{pqrs} \approx U^\alpha_{pq} D_{\alpha,\alpha'} U^\alpha_{rs},
$$

where $V$ is the Mulliken-ordered interaction, $U$ and $\tilde{U}$ are (possibly different) three index integrals, and $D$ is a generalized overlap. Diagrammatically the same expression is

$$
V \approx U \odot D \odot \tilde{U}.
$$

As one may see, RI has the same basic form of a singular value or an eigenvalue decomposition of the interaction tensor. It is known that the error in the RI approximation of the Coulomb operator decays exponentially with the auxiliary basis size $r_{RI} = \dim(\{\alpha\})$, and negligible errors can be reached with the number of auxiliary basis functions scaling as $O(N)$. We note that for a given rank $r_{RI}$, the lowest error RI decomposition can be calculated using the singular value decomposition of the matrix $V_{pq,rs}$ and taking $D$, $U$, $\tilde{U}$ to be the singular values, left, and right singular vectors, respectively. The optimality of the factorization will then be guaranteed by the Eckart-Young theorem. Although this approach is not generally used for practical calculations due to its computational cost, which scales as $O(N^4 \cdot r_{RI})$, we employed it in some of our test calculations. We also note that a popular practical option in the case of two electron integrals is the use of Cholesky decomposition, but this method is limited to symmetric tensors only.

We have said that $V$ is the Mulliken-ordered interaction tensor. The restriction to Mulliken ordering is important, because the order of indices in the original tensor $V_{pq,rs}$ crucially influences the size of the rank $r_{RI}$ for a fixed approximation error. Indeed, while the SVD of the Mulliken-ordered electron interaction $V_{pq,rs}$ yields $O(N)$ non-zero singular values, the matrix $V_{pr,qs}$ formed from a Dirac-ordered interaction tensor has $O(N^2)$ non-zero singular values. This explains why there is no practical RI-like approximation for Dirac-ordered two-electron integrals (or, equivalently, exchange contribution in the context of the Hartree-Fock method).

The RI decomposition itself can readily lead to reduced scaling of some quantum chemistry algorithms. If the contractions of the electron interaction involve mostly indices $p, q$ and $r, s$, but not cross combinations between them (e.g. contractions where one tensor has indices $pq$ and $rs$ while another has indices $pr$ and $qs$), then
a reduction of cost can be achieved, such as in the RI-MP2 approach.\cite{all1,all2,all3} When these cross combinations occur, however, one needs to search for additional structure in the operator tensors. The latter can be achieved by the canonical polyadic decomposition.

### B. Canonical Polyadic Decomposition

A polyad is a rank one tensor, expressible, for example, by

\[
X_{ijk\ldots} = a_i b_j c_k \ldots
\]

or more abstractly as a series of Kronecker products

\[
X = \ldots \otimes c \otimes b \otimes a.
\]

Note that we multiply factors in inverse order; this is simply to preserve a consistent column-major indexing of tensors.

A polyadic decomposition of a tensor is thus a decomposition as a sum of polyads:

\[
T_{pqr\ldots} = \sum_\alpha a_p^\alpha b_q^\alpha c_r^\alpha \ldots
\]

or, more abstractly,

\[
T = \sum_\alpha \ldots \otimes c_\alpha \otimes b_\alpha \otimes a_\alpha.
\]

The canonical polyadic decomposition is the polyadic decomposition of lowest rank. It may be seen as one of the generalizations of SVD to third and higher order tensors, and for dimensions greater than 2, the CPD is unique under mild conditions.\cite{all1,all2}

As can be seen from the definition of Eq. (11) some matrix factorizations (for example, QR or LU factorizations) can be thought of as a CPD of matrices. In dimensions greater than 2, however, no closed form algorithm to extract the CPD is known, and one must rely on iterative optimization techniques to approximate the CPD.\cite{all1,all2,all3} Substantial effort has been made by the mathematical community to develop approaches for doing so. Typical algorithms are the alternating least squares (ALS), gradient descent by means of, for example, the method of Broyden, Fletcher, Goldfarb, and Shanno (BFGS), and nonlinear least squares (NLS) methods.\cite{all1,all2,all3} We refer the reader to the corresponding reviews for further details. We have used the Tensorlab program by Lathauwer et al. for calculating the CPD in this work.

The polyadic decomposition can be expressed more conveniently through the Khatri-Rao product. If the vectors \(a\), \(b\), and \(c\) of Eq. (11) are stacked together as columns of matrices \(A = \{a\}\), \(B = \{b\}\), \(C = \{c\}\), then the polyadic decomposition can be written as

\[
T_{pqr} = ((B \otimes A) \cdot C^T)_{pqr},
\]

which diagrammatically is

\[
\begin{array}{c}
\text{T} \\
\downarrow \\
\text{B} \\
\leftarrow \\
\text{A} \\
\rightarrow \\
\text{C} \\
\end{array}
\]

\begin{equation}
\end{equation}

### C. Tensor Hypercontraction

The THC is a factorization of fourth-order tensors and can be seen as a combination of a singular value decomposition and a canonical polyadic decomposition. The THC approximation can be written as

\[
V_{pqrs} = W_{p,\alpha}^1 W_{q,\alpha}^2 X_{\alpha,\beta} W_{r,\beta}^3 W_{s,\beta}^4 = ((W^2 \otimes W^1) \cdot X \cdot (W^4 \otimes W^3)^T)_{pqrs}.
\]

The THC can be viewed as a further approximation over RI, which is clear from the following diagram:

\[
\begin{array}{c}
\text{V} \\
\downarrow \\
\text{Q} \\
\leftarrow \\
\text{P} \\
\rightarrow \\
\text{R} \\
\end{array}
\]

\begin{equation}
\end{equation}

The sizes of the auxiliary indices \(\alpha\) and \(\beta\) are the ranks of the decomposition. In all subsequent expressions \(r_{\text{THC}} = \dim(\{\alpha\}) = \dim(\{\beta\})\) for simplicity, although there is no fundamental restriction that \(\dim(\{\alpha\}) = \dim(\{\beta\})\). Using the analogy with density fitting, several authors\cite{all1,all2,all3} have speculated that the optimal rank of THC scales as \(r_{\text{THC}} = O(N)\) in the case of the electron interaction tensor. We confirm this numerically in Sec. IV.

### D. Algorithms for Tensor Hypercontraction

#### 1. Composite Method

The diagram in Eq. (15) suggests one possible way to calculate the THC of an order-4 tensor as a combination of the singular value and canonical polyadic decompositions. The following diagram depicts the procedure we call THC-CPD:

\[
\begin{array}{c}
\text{V} \\
\downarrow \\
\text{Q} \\
\leftarrow \\
\text{P} \\
\rightarrow \\
\text{R} \\
\end{array}
\]

\begin{equation}
\end{equation}

First, one can reshape the original tensor \(V\) with dimensions \(I_1 \times I_2 \times I_3 \times I_4\) into a matrix of shape \(I_1 I_2 \times I_3 I_4\) and apply a truncated SVD of rank \(r_{\text{SVD}}\) to it. We chose to multiply square roots of singular values into left and right singular vectors. Note that this produces matrices \(U_L\) and \(U_R\) of identical norm. Next, the left and right
matrices of shapes \(I_1 I_2 \times r_{\text{SVD}}\) and \(I_3 I_4 \times r_{\text{SVD}}\) are reshaped into third-order tensors of shapes \(I_1 \times I_2 \times r_{\text{SVD}}\) and \(I_3 \times I_4 \times r_{\text{SVD}}\), respectively. The CPD of rank \(r_{\text{CPD}}\) is calculated for each of those tensors separately with any algorithm of choice, with each algorithm limited to \(n_{\text{it}}\) iterations. Finally, those factors of the CPD which do not have external indices can be merged into a single factor \(X\).

Algorithm 1 summarizes the composite method we employ, along with the computational scaling of its steps for a tensor of size \(N \times N \times N \times N\), where we used \(\text{cpd()}\) to denote a CPD method of choice.

A similar scheme was employed by Hohenstein et al. in their initial work on THC. The scaling of this algorithm is dominated by the truncated SVD in step 4. If the optimal rank of the SVD is of order \(O(N)\), the algorithm is of \(O(N^5)\) cost if \(r_{\text{SVD}} = O(N)\) and \(O(N^6)\) in the worst case. The SVD can be avoided if substitute singular vectors are available for the tensor \(V\). In the case of the electron interaction, such substitutes are given by the 3-index integrals coming from the RI approximation. The auxiliary dimension \(r_{\text{RI}}\) is of \(O(N)\).

A faster Algorithm 2 based on the RI approximation can be formulated as follows. We start with third-order tensors \(U, \tilde{U}\) of shapes \(I_1 \times I_2 \times r_{\text{RI}}\) and \(I_3 \times I_4 \times r_{\text{RI}}\), respectively, and an overlap matrix \(D\) of shape \(r_{\text{RI}} \times r_{\text{RI}}\). A matrix root \(D^{\frac{1}{2}}\) of \(D\) is calculated using the SVD or eigenvalue decomposition. This matrix is then multiplied into order-3 tensors \(U\) and \(\tilde{U}\), which yields left and right third-order tensors \(U_L\) and \(U_R\). If the size of the RI basis is large and \(U_L\) equals \(U_R\), as in the case of 3-index integrals, an optional compression step can be applied (Algorithm 3): the auxiliary dimension of \(U_L\) and \(U_R\) is reduced by a truncated SVD of rank \(r_{\text{SVD}}\). Finally, a CPD of rank \(r_{\text{CPD}}\) is calculated for the left and right parts, and the resulting factors with no external indices are merged into a single factor \(X\). The resulting algorithm is listed below:

The overall scaling of Algorithm 2 may be dominated either by the \(O(N^2 r_{\text{RI}}^2)\) cost of the SVD and matrix multiplications or by the \(O(N^2 r_{\text{SVD}} r_{\text{CPD}} n_{\text{it}})\) cost of the iterative algorithm of the CPD. In practical calculations we found that the latter contribution, despite scaling mildly with the system size \(N\) and optimal ranks \(r_{\text{CPD}}\) and \(r_{\text{SVD}}\), is always dominant because of the large number of iterations required by the CPD algorithm. This motivated us to look for an equivalent algorithm to build the THC decomposition directly.

2. Direct Method

We follow Sorber et al.\(^{32}\) to build a simple alternating least squares algorithm for THC. We begin by introducing the approximation of a fourth-order tensor \(V\) by its THC decomposition \(\tilde{V}\), which we recall is

\[
\tilde{V}_{ijkl} = W^4_{pqrs} X_{\alpha,\beta} W_{r,\xi,\eta}^{\frac{1}{2}} W_{\eta,\xi,\eta}^{\frac{1}{2}}
\]

\[
= [(W^4 \circ W^1) \cdot X \cdot (W^4 \circ W^3)']_{ijkl}.
\]

Then we can define an error tensor

\[
\Delta_V = V - \tilde{V},
\]

whose Frobenius norm is just

\[
f = \|\Delta_V\|^2 = (V_{pqrs} - \tilde{V}_{pqrs})(V_{pqrs} - \tilde{V}_{pqrs}).
\]
Diagrammatically, this is

\[ f = \begin{array}{c}
V \\
\hline \\
W & W' & W'' & W'''
\end{array} - \begin{array}{c}
V \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
X \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
X \\
\hline \\
W & W' & W'' & W'''
\end{array}. \tag{20}

Clearly, the best possible THC approximation to \( V \) will correspond to a minimum of the cost function \( f \). We note that \( f \) is a real-valued analytic function, and hence \( \frac{\partial f}{\partial W^1} = (\frac{\partial f}{\partial W^1})^* \), where \( W \in \{W^1, W^2, W^3, W^4, X\} \).

In order to minimize the cost function, we proceed with the calculation of its gradient, which can be easily done using diagram \ref{diagram20}. The partial derivative of \( f \) with respect to \( W^1 \) is

\[ \frac{\partial f}{\partial W^1} = -\begin{array}{c}
V \\
\hline \\
W & W' & W'' & W'''
\end{array} + \begin{array}{c}
V \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
X \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
X \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
X \\
\hline \\
W & W' & W'' & W'''
\end{array}. \tag{21}

and the full gradient of \( f \) can be found in the supplementary material. Noting that \( \frac{\partial f}{\partial W^1} \) is linear in \( W^* \), we contract all factors around \( W^* \) into an environment matrix \( A \), as seen in diagram \ref{diagram22} and set the derivative to zero:

\[ \begin{array}{c}
A \\
\hline \\
W & W' & W'' & W'''
\end{array} = \begin{array}{c}
A \\
\hline \\
W & W' & W'' & W'''
\end{array}. \tag{22}

We end up with a problem

\[ A \cdot W^* = B. \tag{23}\]

The solution to Eq. \ref{eq:23} can be obtained by taking the inverse of \( A \) (or a pseudoinverse, if \( A \) is a rank-deficient matrix). The final expression for \( W^{1*} \) is given diagrammatically as

\[ W^{1*} = \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} = \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array}. \tag{24}

As made clear by the diagram, if both ranks of the THC decomposition are \( r_{\text{THC}} \), then the construction of the environment matrix \( A \) scales as \( O(r_{\text{THC}}^3) \), as does computing its generalized inverse. If each of the dimensions of \( V \) equals \( N \), then the cost of calculating \( W^{1*} \) scales as \( O(N^4 r_{\text{THC}}) \). Updates for the rest of the terms in the THC decomposition can be calculated similarly.

A simple iterative optimization algorithm can be built as follows. First, the THC factors \( W \) are initialized randomly. For each factor, an update is calculated as shown on diagram \ref{diagram24}, keeping the other factors fixed. The process is iterated until convergence of the factors. The resulting THC-ALS algorithm is listed below.

\begin{algorithm}[h]
\caption{Alternating Least Squares}
1: \textbf{function} \textsc{thc-als}(\( V, r_{\text{THC}}, \epsilon \))
2: \hspace{1em} \( I_1, I_2, I_3, I_4 \gets \text{size}(V) \)
3: \hspace{1em} \( W^1, W^2, W^3, W^4, X \) \gets \text{init\_random}(I_1, I_2, I_3, I_4, r_{\text{THC}})
4: \hspace{1em} \textbf{repeat}
5: \hspace{2em} \textbf{for all} \( W \in \{W^1, W^2, W^3, W^4, X\} \) \textbf{do}
6: \hspace{3em} \( A_W \gets \text{get\_environment}(W^1, W^2, W^3, W^4, X) \)
7: \hspace{3em} \( B_W \gets \text{get\_rhs}(V, W^1, W^2, W^3, W^4, X) \)
8: \hspace{3em} \( O(N^4 r_{\text{THC}}) \) or \( O(N^2 r_{\text{THC}}) \) with RI
9: \hspace{3em} \( W_{\text{new}} \gets A_W^{-1} B_W \), \( O(r_{\text{THC}}^3) \)
10: \hspace{1em} \textbf{end for}
11: \hspace{1em} \( \Delta \gets \max_W \| W_{\text{new}} - W \| \)
12: \hspace{1em} \( W \gets W_{\text{new}} \)
13: \hspace{1em} \textbf{until} \( \Delta > \epsilon \)
14: \hspace{1em} \textbf{return} \( W^1, W^2, W^3, W^4, X \)
15: \textbf{end function}
\end{algorithm}

The calculation of the right hand side of Eq. \ref{eq:23} dominates in the cost of THC-ALS, scaling as \( O(N^4 r_{\text{THC}}) \). A simple modification is possible to reduce this cost by one order of magnitude. If an approximation to the singular vectors of the original tensor \( V \) is available from the beginning, as in the case of electron interaction, it can be used in place of \( V \), leading to a faster algorithm. The diagram corresponding to Eq. \ref{eq:23} then becomes

\[ W^{1*} = \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array} \cdot \begin{array}{c}
\Upsilon \\
\hline \\
W & W' & W'' & W'''
\end{array}. \tag{25}\]

The cost of the expression above scales as \( O(N^2 r_{\text{RI}} r_{\text{THC}}) \), because the contraction of a fourth-order tensor \( V \) with matrices \( W \) is replaced by contractions of two third-order tensors \( U \) and \( \tilde{U} \). We only need to modify the function \text{get\_rhs()} to build a lower scaling algorithm, which we refer to as THC-ALS-RI.

Alternating least squares algorithms are simple and often robust,\textsuperscript{36} but may take a large number of iterations to converge.\textsuperscript{36} Following an analogy with CPD,\textsuperscript{23} we also implemented quasi-Newton method using limited memory BFGS (L-BFGS) with a dogleg trust region\textsuperscript{37} for THC; this method we refer to as THC-BFGS.

The THC-ALS and THC-BFGS, and their RI variants, are novel direct methods to calculate the THC decomposition based on minimization of the Frobenius norm of the error. Composite methods such as THC-CPD(ALS)
TABLE I. Computational scaling per iteration of various algorithms to converge the CPD in composite methods or the THC itself in direct methods. The top half of the table shows scaling for methods which do not use an initial RI, while the bottom half of the table shows scaling for methods which do use an initial RI.

| Algorithm            | Scaling               |
|----------------------|-----------------------|
| THC-CPD(ALS)         | $O(N^3 r_{THC})$      |
| THC-CPD(BFGS)        | $O(N^3 r_{THC})$      |
| THC-CPD(NLS)         | $O(N^3 r_{THC} + r_{THC}^2 + N^2 r_{THC}^3)$ |
| THC-ALS              | $O(N^4 r_{THC} + r_{THC}^2)$ |
| THC-BFGS             | $O(N^4 r_{THC} + r_{THC}^2)$ |
| THC-CPD-RI(ALS)      | $O(N^3 r_{THC})$      |
| THC-CPD-RI(BFGS)     | $O(N^3 r_{THC})$      |
| THC-CPD-RI(NLS)      | $O(N^3 r_{THC} + r_{THC}^2 + N^2 r_{THC}^3)$ |
| THC-ALS-RI           | $O(N^2 r_{SVD} + r_{THC}^2)$ |
| THC-BFGS-RI          | $O(N^2 r_{SVD} + r_{THC}^2)$ |

and their RI variants have been used previously in earlier work on THC.

We refer the reader to the supplementary material for optimized expressions of the THC gradient and objective function. Due to their complexity many of the equations we present (especially the ones related to coupled cluster, see Section IV) were generated by a computer algebra system developed in our group, although this can be done by manipulating diagrams as well.

3. Numerical Experiments

Here we wish to compare the performance of the composite methods (THC-CPD(ALS), THC-CPD(BFGS), THC-CPD(NLS)) and direct algorithms (THC-ALS, THC-BFGS) for THC decomposition. Table II shows the scaling per iteration for the various algorithms we consider (see algorithms in the text and also Ref. 32 for further details on the scaling of CPD, which we used in the composite methods). The scaling is given for a full fourth-order tensor with sizes equal $N$ in the first part of the table, and for RI-decomposed tensors with rank $r_{SVD}$ in the second part. Recall that the composite methods in the first part of the table require an initial SVD, the cost of which scales as $O(N^4 r_{SVD})$; this cost is in addition to that of the iterative steps required to converge the CPD.

To summarize the contents of Table II let us assume that both $r_{SVD}$ and $r_{THC}$ are $O(N)$, as is the case for the electron interaction tensor. Then all composite algorithms have a non-iterative $O(N^5)$ step followed by iterative $O(N^4)$ steps, while direct algorithms have $O(N^5)$ cost per iteration. If an RI approximation is used, all algorithms have $O(N^4)$ scaling per iteration.

To get a feeling for how these various algorithms perform in practice, we compared the convergence speed of direct and composite methods using the performance metrics proposed by Dolan and More. We generated fifty sets of random THC factors using a uniform distribution, from which we built fifty tensors which had size $4 \times 4 \times 4 \times 4$ and THC ranks 2 and 3. We further generated fifty sets of random initial guesses drawn from the same uniform distribution. This yielded a set $P$ of 2500 (tensor, initial guess) pairs for each tensor rank.

The algorithms in the first part of Table II (i.e. those algorithms that do not use RI) form a set of algorithms $S$. For each problem $p$ in $P$, we applied each algorithm $s$ in $S$. We allowed the algorithms to run for up to 2000 iterations or until converged, where our convergence criterion was $\|V - \tilde{V}\| \leq 10^{-5}$. The number of iterations required for an algorithm $s$ to converge a problem $p$ we denote as $t_{p,s}$. If an algorithm did not converge a given problem, we set $t_{p,s}$ to $\infty$.

For direct methods, we stopped the iterative algorithm if $\|V - \tilde{V}\| \leq 10^{-7}$ and declared the method to have failed if it did not meet our convergence threshold. For composite methods, we retained singular values larger than $10^{-7}$ in building the factors $U_L$ and $U_R$.

We declared the CPD converged if $\|U - \tilde{U}\| \leq 10^{-10}$ and stopped the iterations if $\|U - \tilde{U}\| \leq 10^{-14}$. In all cases the threshold for the pseudoinverse was set to $10^{-14}$. We emphasize that for both direct and composite methods the definition of success was accurate decomposition of $V$, e.g. the magnitude of absolute error had to be less than the threshold $\|V - \tilde{V}\| \leq 10^{-5}$.

Having applied each algorithm $s$ to each problem $p$, we use as a performance metric

$$\rho_s(\tau) = \frac{|\{p \in P : t_{p,s} \leq 2^\tau \cdot \min_{s \in S}(t_{p,s})\}|}{|P|}.$$  \hfill (26)

In other words, $\rho_s(\tau)$ is the fraction of problems that algorithm $s$ solved within $2^\tau$ times the best algorithm for each problem. We would like $\rho_s(\tau)$ to approach one for large enough $\tau$, indicating that the algorithm converged all problems that could be converged, and we would like $\rho_s(\tau)$ to grow toward one as rapidly as possible, indicating that the algorithm converged relatively quickly.

Results are shown in Fig. I where the left panel shows results for rank two tensors and the right panel shows results for rank three tensors.

As one can see, composite methods THC-CPD outperform our direct THC decomposition. The difference in performance is more prominent for $r_{THC} = 3$ than it is for $r_{THC} = 2$. For example, THC-ALS converges for less than 50% of possible problems when $r_{THC} = 3$, compared to about 80% for $r_{THC} = 2$. We believe the poor performance of the direct algorithm is because the THC factors are not unique (as our numerical experimentation indicated), whereas the factors in the CPD are unique under mild conditions. This non-uniqueness results in gradient vectors which are close to zero in certain directions, and optimization algorithms then require many more iterations to minimize the objective function.

Overall, the best method for THC seems to be the composite THC-CPD(NLS), which we recall uses a non-

4. Conclusion
linear least squares solver for CPD. We will thus use THC-CPD(NLS) for subsequent THC decompositions in this work.

We should note that no method was able to solve all problems in our setup, though the composite methods succeeded in the very large majority of cases. Similar behavior for random test factors was previously observed for CPD. This did not pose a problem in our practical context. Here, we will use coupled cluster doubles (for THC−ALS) and THC−CPD(BFGS) for subsequent THC decompositions in our setup, though the composite methods usually obtained by projecting the similarity-transformed Hamiltonian on the left against a set of excited determinants to form residuals which are set to zero,

$$R_1 = \langle 0 | \hat{a}^\dagger_{i,\uparrow} \hat{a}_{i,\uparrow} \hat{a}_{a,\uparrow} \hat{a}_{a,\uparrow} \hat{H} | 0 \rangle = 0,$$

$$R_2 = \langle 0 | \hat{a}^\dagger_{i,\uparrow} \hat{a}^\dagger_{j,\downarrow} \hat{a}_{b,\downarrow} \hat{a}_{a,\uparrow} \hat{H} | 0 \rangle = 0.$$  

These result in polynomial equations of the amplitude tensors which can be transformed to the form

$$1T_1 = 1D_{1i}^a 1G^a_i,$$

$$2\tilde{T}_{ij} = 2D_{ij}^{ab} 2G_{ij}^{ab},$$

which can be solved by iterations until a fixed point is found. Here, $1D$ and $2D$ are orbital energy denominator tensors built from diagonal elements of the Fock matrix $F$:

$$1D_{1i}^a = \frac{1}{F_{a}^a - F_{i}^i},$$

$$2D_{ij}^{ab} = \frac{1}{F_{a}^a + F_{b}^b - F_{i}^i - F_{j}^j}.$$  

The tensors $1G$ and $2G$ are built from contractions of the amplitude tensors with the Hamiltonian.

### IV. Tensor Structured Coupled Cluster

While the direct algorithms proposed in the previous section were not particularly good for the decomposition of random tensors, we introduced them because they find new life in our tensor-decomposed coupled cluster methods, as we discuss below. Let us begin, however, with a quick overview of the restricted CCSD (RCCSD) method. We define a cluster operator

$$\hat{T} = 1\hat{T} + 2\hat{T},$$  

where the individual operators $i\hat{T}$ are excitation operators

$$1\hat{T} = 1T_1 \hat{E}_{i}^{a},$$

$$2\hat{T} = 2\tilde{T}_{ij} \hat{E}_{i}^{a} \hat{E}_{j}^{b}.$$  

Here,

$$\hat{E}_{i}^{a} = \hat{a}_{a,\uparrow}^\dagger \hat{a}_{i,\uparrow} + \hat{a}_{a,\downarrow}^\dagger \hat{a}_{a,\downarrow}$$

are spin adapted excitations, or unitary group generators, and $i\hat{T}$ are order 2i amplitude tensors.

With these cluster operators, we construct a similarity-transformed Hamiltonian $\hat{H}$ as

$$\hat{H} = e^{-\hat{T}} \hat{H} e^{\hat{T}},$$

from which the energy can be extracted as

$$E_{\text{CCSD}} = \langle 0 | \hat{H} | 0 \rangle$$

where $|0\rangle$ is a closed shell single determinant (usually a Hartree-Fock state). The excitation amplitudes are usually obtained by projecting the similarity-transformed Hamiltonian on the left against a set of excited determinants to form residuals which are set to zero.

FIG. 1. Performance metric $\rho_s(\tau)$ for various THC decomposition algorithms. Left panel: $r_{\text{THC}} = 2$. Right panel: $r_{\text{THC}} = 3$. 

A. Least Squares Coupled Cluster Theories

The logic used to derive the ALS algorithm for THC decomposition can be readily applied in the coupled cluster context. Here, we will use coupled cluster doubles (for
which one neglects \( T^1 \) as an example, with expressions for CCSD shown in the supplementary material.

We begin by imposing the THC structure on the doubles amplitudes. We approximate the amplitude tensor \( T \) with its THC decomposition \( 2\tilde{T} \). The difference between original and approximated amplitudes is

\[
\Delta_T = 2T - 2\tilde{T} = 2T - (Y^2 \odot Y^1) \cdot Z \cdot (Y^4 \odot Y^3)^T,
\]

(35)

where \( Y^i \) and \( Z \) are factors in the THC decomposition of \( 2T \). We wish to minimize the squared norm of the error tensor \( \Delta_T \), which is the minimization of the corresponding cost function \( f_T \),

\[
f_T = |\Delta_T|^2 = (2T^* - 2\tilde{T}^*)(2T - 2\tilde{T}).
\]

(36)

Setting partial derivatives of \( f_T \) with respect to the decomposition factors to zero, we obtain a new set of equations

\[
\frac{\partial f_T}{\partial Y} = -2T^* \frac{\partial^2 \tilde{T}}{\partial Y} + 2\tilde{T}^* \frac{\partial^2 \tilde{T}}{\partial Y} = 0,
\]

(37)

where \( Y \in \{Y^1, Y^2, Y^3, Y^4, Z\} \). Again, as \( f_T \) is real and analytic, only one set of derivatives (either with respect to \( Y \) or \( Y^* \)) is sufficient to find its minimum.

Now we use Eq. (33) to replace \( 2T^* \) with \( 2D^2G \). The idea is to thus to minimize the difference between a decomposed tensor \( 2\tilde{T} \) and a solution of the CCD amplitude equations. The resulting amplitude equations are

\[
\tilde{T}^* \frac{\partial \tilde{T}}{\partial Y} = 2G^2 D \frac{\partial \tilde{T}}{\partial Y}.
\]

(38)

This is the analogue of Eq. (23) in THC-ALS, and can be solved in the least-squares sense (i.e., with the help of the pseudoinverse) as the left-hand-side is linear in \( Y^* \). Diagrammatically, we have

\[
\begin{align*}
\begin{array}{c}
\hat{D} \\
\hat{A}
\end{array} & \begin{array}{c}
\hat{G} \\
\hat{B}
\end{array} \\
\begin{array}{c}
\hat{Y} \\
\hat{Z}
\end{array} & = \\
\begin{array}{c}
\hat{D} \\
\hat{A}
\end{array} & \begin{array}{c}
\hat{G} \\
\hat{B}
\end{array} \\
\begin{array}{c}
\hat{Y} \\
\hat{Z}
\end{array}
\end{align*}
\]

(39)

These equations can be further factorized if one employs CPD of \( 2D \) to disentangle particle and hole indices. A low-rank decomposition of denominator tensors can be built using an exponential parametrization (also known as Laplace transformation)\(^{31}\) as, for example,

\[
2D^{nh}_{ij} = C_{i,\omega} e^{A_{\omega} F_i} e^{A_{\omega} F_j} e^{-A_{\omega} F_a} e^{-A_{\omega} F_b} = 2D^1_{i,\omega} 2D^2_{j,\omega} 2D^3_{a,\omega} 2D^4_{b,\omega}.
\]

(40a)

(40b)

\[
\text{We have used the parameters from Ref.} \text{, which provide absolute accuracy of better than } 10^{-12} \text{ with ranks of order } \approx 15, \text{ which do not depend on the system size } N.
\]

The final form of our ALS-type coupled cluster doubles equations is thus

\[
\text{Diagrammatically, we have}
\]

\[
\begin{align*}
\begin{array}{c}
\hat{D} \\
\hat{A}
\end{array} & \begin{array}{c}
\hat{G} \\
\hat{B}
\end{array} \\
\begin{array}{c}
\hat{Y} \\
\hat{Z}
\end{array} & = \\
\begin{array}{c}
\hat{D} \\
\hat{A}
\end{array} & \begin{array}{c}
\hat{G} \\
\hat{B}
\end{array} \\
\begin{array}{c}
\hat{Y} \\
\hat{Z}
\end{array}
\end{align*}
\]

(41)

The explicit form of these equations and analogous expressions for ALS-type CCSD are shown in the supplementary material. After defining proper intermediates, which we did using our automatic algebraic system,\(^{39}\) the cost of these equations has quartic scaling in \( r_{\text{THC}} \) and \( N \) per iteration. We provide those fully factorized equations in the supplementary material along with the source code for the contractions. Most of the numerical experiments in the following section were done with a simpler code which had \( O(N^3) \) scaling because it made less sophisticated use of intermediate quantities; however, the \( O(N^4) \) and \( O(N^3) \) implementations differ only in the order in which contractions were carried out.

Equation (41) and its analogs for all other factors in the decomposition of \( 2T \) constitute what we call THC-RCCSD and are the main result of this paper. It must be stressed that the proposed scheme is generic, and can be applied to any factorization of amplitudes and the Hamiltonian. We use THC here, and leave the exploration of other possibilities for subsequent work.

\[\text{B. Test Calculations}\]

To assess the performance of our tensor-structured CCSD, we present calculations on a variety of small- to medium-sized molecules. All calculations used the cc-pVDZ basis from EMSL database\(^{32}\) and the corresponding cc-pVDZ-RI was used in the RI approximation.

For smaller systems the THC-CPD(NLS) algorithm was used to obtain the THC approximation to the full two-electron integrals in the AO basis. We set the relative convergence threshold for CPD iterations to \( 10^{-14} \), as we did in our numerical experiments in Sec. \( \text{III} \). Singular values larger than \( 10^{-12} \) were retained in obtaining \( U_L \) and \( U_R \). The maximum number of iterations allowed during the decomposition of the integrals was 1000. The subsequent coupled cluster calculations were stopped either after the energy was converged to within 10–9 Hartree or a limit of 200 iterations was reached. Thresholds for pseudoinverse calculations were set to \( 10^{-14} \).

For larger systems, listed in Tab. \( \text{III} \) THC-CPD(NLS) was applied to RI-decomposed two-electron integrals. Other parameters were as described above, except we decreased the number of iterations allowed during decomposition of the integrals to 500 and the number of coupled cluster iterations allowed to 100.
1. Decomposition of Two-Electron Integrals

The accuracy of the THC decomposition of the two-electron integrals governs the accuracy of the energy in subsequent calculations. Thus, we first wish to check the dependence on the error in the decomposition of two-electron integrals on THC rank. Figure 2 plots this error in a double logarithmic scale for three small molecules. We note that the decomposition is computationally useful if the rank $r_{THC}$ is close to the number of basis functions $N$. As the figure shows, the error in the two-electron integrals decays exponentially with respect to THC rank. We found that this trend holds for every system tested and depends only slightly on whether the two-electron integrals are decomposed in the atomic orbital or molecular orbital basis.

To see how the decomposition affects subsequent energies, we checked the error in the second-order Møller-Plesset (MP2) correlation energy, as shown in Fig. 3. The combination of MP2 and THC was first proposed by Hohenstein et al. and scales as $O(N^4)$. These authors used a version of THC with the restriction that all factors $W$ were the same, which we did not impose in our work. The error in the MP2 correlation energy follows the trend seen in the decomposition of the two-electron integrals. Results within 0.1 $mH$ of the exact MP2 correlation energy are already achieved with $r_{THC} \sim N^{1.2} - N^{1.4}$. We expect that the THC would work better for larger and more extended systems as the two-electron integrals become sparser and a lower rank decomposition would correspondingly become more accurate.

2. Restricted Coupled Cluster with Singles and Doubles

Finally, we demonstrate the behavior of the THC-decomposed RCCSD method (THC-RCCSD), seen in Fig. 4. We chose the rank of the THC decomposition of the amplitudes and two-electron integrals to be the same. The error in the RCCSD correlation energy has a non-monotonic dependence on THC rank, but follows the same basic trends as seen in Fig. 2 and Fig. 3. As with MP2, errors on the order of 0.1 $mH$ are achieved with $r_{THC} \sim N^{1.2} - N^{1.4}$. It is interesting to see what part of the error in energy can be attributed to the approximation of the Hamiltonian, especially because building the decomposition of the Hamiltonian contributed $\sim 95\%$ of the total computational cost. For this reason we calculated the correlation energy with converged THC-RCCSD amplitudes but exact two-electron integrals. As Fig. 4 shows, using the exact two-electron integrals decreases the error in energy, as one would expect, but does not remove its non-monotonic dependence on the THC rank. We attribute this behavior to the nonlinear nature of the coupled cluster equations, which can be quite sensitive to changes in the parameters of the Hamiltonian.

Having seen how the THC-RCCSD method performs for various THC decomposition ranks, we tested the method on a set of small and medium-sized molecules introduced in previous work on THC. Technical details of the calculations, including molecular geometries and reference energies, are provided in the supplementary materials. We chose the ranks of the THC decomposition of the amplitudes and integrals to be similar to the number
FIG. 5. Absolute error in the RCCSD correlation energy with exact two electron integrals.

TABLE II. CCSD correlation energies ($E_c$) and errors in the THC-RCCSD correlation energies ($\Delta E_c$) for several small molecules.

| System          | $E_c (mH)$ | $N_{THC} = N_{RI}$ | $N_{THC} = 1.5 N_{RI}$ |
|-----------------|------------|--------------------|------------------------|
| Acetic acid     | -666.510   | -0.579             | -0.453                 |
| Aniline         | -997.193   | -1.177             | -0.471                 |
| Diboron tetrafluoride | -909.944 | -0.702             | -0.716                 |
| Benzene         | -823.101   | -0.985             | -0.450                 |
| Butadiene       | -581.340   | -0.710             | -0.274                 |
| Cyclobutane     | -621.099   | -0.895             | -0.290                 |
| Dimethylsulfoxide | -661.870  | 0.195              | -0.624                 |
| Furan           | -736.463   | -0.865             | -0.454                 |
| Isobutane       | -652.505   | -0.876             | -0.263                 |
| Methylformate   | -666.805   | -0.586             | -0.455                 |
| Methyl nitrite  | -708.990   | -0.476             | -0.492                 |
| Phenol          | -1005.727  | -0.887             | -0.514                 |
| Pyridine        | -842.453   | -1.045             | -0.475                 |
| Pyrrole         | -727.051   | -0.855             | -0.407                 |
| Thiophene       | -695.593   | -1.013             | -0.657                 |
| Toluene         | -980.030   | -1.270             | -0.461                 |

$\Delta E_c (mH)$

| System          | $\Delta E_c (mH)$ |
|-----------------|-------------------|
| Acetic acid     | -0.579            |
| Aniline         | -1.177            |
| Diboron tetrafluoride | -0.702 |
| Benzene         | -0.985            |
| Butadiene       | -0.710            |
| Cyclobutane     | -0.895            |
| Dimethylsulfoxide | 0.195       |
| Furan           | -0.865            |
| Isobutane       | -0.876            |
| Methylformate   | -0.586            |
| Methyl nitrite  | -0.476            |
| Phenol          | -0.887            |
| Pyridine        | -1.045            |
| Pyrrole         | -0.855            |
| Thiophene       | -1.013            |
| Toluene         | -1.270            |

$\Delta E_c (mH)$

$\Delta E_c (mH)$

- mean unsigned error
- maximum unsigned error
- root-mean-square error

of functions $N_{RI}$ in the basis used in the RI approximation. Results are presented in Table II. We used RI for all these calculations. We note that our results are on par with calculations of Hohenstein et al.2 but similar errors are achieved with ranks which are roughly half as large. Presumably this is because in previous work most of the factors in the THC decomposition of the amplitudes were kept fixed (except $Z$), whereas our scheme optimizes all factors, therefore providing greater flexibility and reaching the exact decomposition faster. Again, we emphasize that the proposed scheme is not limited to THC, and can be applied to many other decompositions, which is the topic of ongoing investigation.

V. CONCLUSIONS

Systematically dependable quantum chemical methods rely on solving the Schrödinger equation, but unfortunately do so at a significant and often impractical computational cost. For many-body methods such as coupled cluster theory, the cost can be explained simply: the various objects of the theory are high-order tensors which must be contracted with one another, and the contraction of two high-order tensors is computationally costly. Tensor decompositions lower the cost by writing high-order tensors as sums of products of low-order objects, and are one of the most promising ways to apply many-body theories to large systems.

In this work, we have shown how the combination of tensor hypercontraction and canonical polyadic decomposition allows us to solve the closed-shell CCSD equations with $O(N^4)$ scaling by solving directly for the factors which decompose the cluster operator (Eqn. 41). By increasing the dimensions of these factors (i.e. by increasing the rank) we can approach the exact CCSD result in a more or less systematic fashion, and can achieve results within $0.1 \text{mH}$ of the exact CCSD answer with ranks on the order of the size of the basis. Our alternating least squares method improves over previous studies of THC in coupled cluster theories4,10 where fixed real-space quadratures were used to build the decomposition of cluster amplitudes and provides more accurate results for smaller ranks. The proposed scheme, however, is general and can be applied to any decomposition, as well as readily extended to more sophisticated coupled cluster theories. Among other possibilities, we plan extensions to the Unrestricted CC and our own symmetry-projected CC theories44–46. Lastly, we should mention that coupled cluster methods with decomposed amplitudes are much more suitable for parallelization than are the traditional ones, because the communication becomes much cheaper. While our work along the mentioned lines is still in the early stages, we hope that these low-scaling coupled cluster methods will help make large-scale CCSD calculations essentially routine.

SUPPLEMENTARY MATERIAL

See supplementary materials for the THC gradient expressions, complete specification of test systems and least squares coupled cluster expressions.
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Appendix A: Wiring Diagrams

We have made extensive use of wiring diagrams to simplify the representation and manipulation of complex tensor expressions. This graphical notation is similar to the usual diagrammatic notation used in many-body theory, but not identical. For completeness, we here describe the basic semantics of our diagrams.

In our notations, tensors are represented by shapes. Typically a $d$-order tensor is represented by a polygon with $d$ corners (and a second-order tensor by a circle), though we have not followed this convention universally. Indices are denoted by lines; a line connecting multiple tensors is to be summed over, and open lines correspond to free indices. If a particular element of a tensor expression is required, we label the open lines.

To be concrete, a matrix product would be represented by

\[ A \otimes B \rightarrow C_{pq} = \sum_r A_{pr} B_{rq} \]  
(A1)

and a more general contraction of a fourth-order tensor with a third-order tensor can be drawn as

\[ \sum_{qp} V_{pt} U_{qr} = W_{rm} \]  
(A2)

Diagrams can be used to readily estimate the cost of contractions (and other operations). The cost $\Omega$ of contracting two tensors over $L$ indices of size $\{\lambda\}_1^L$ to a tensor with $M$ indices of size $\{\mu\}_1^M$ scales with respect to $N$ as

\[ \Omega = O(N^{\sum_{i=1}^L \log N \dim(\{\lambda\}_i)} \sum_{m=1}^M \log N \dim(\{\mu\}_m)). \]  
(A3)

One can simply estimate the scaling of a contraction by multiplying the dimensions of each open line in the result together with those of each closed line. For example, a contraction of two third-order tensors of size $N \times N \times N$ over two indices of size $N$ scales as $O(N^4)$:

\[ \Omega = O(N^4) \]  
(A4)

Other operations that can be represented pictorially are of an outer product type. This situation corresponds to merging the nodes together and leaving all lines in the final structure:

\[ \begin{array}{c}
\text{Diagram of product} \\
\rightarrow \\
\text{Diagram of outer product} \\
\end{array} \]

Note that if one reshapes the fourth-order tensor above into a matrix with combined indices $rp$ and $sq$, then the result will coincide with the usual Kronecker product of matrices, where we recall that the Kronecker product is

\[ C = A \otimes B \Leftrightarrow C_{rp,sq} = A_{pq} B_{rs}. \]  
(A6)

The cost of product-type operations is

\[ \Omega = O(N^{\sum_{m=1}^M \log N \dim(\{\mu\}_m)}) \]  
(A7)

where $\{\mu\}_1^M$ are $M$ free indices in the resulting tensor.

For our purposes we slightly extended the diagrammatic notation by introducing summations over an index shared by more than two terms. We denote such indices by branching lines with a dot at the branching point. This dot can be interpreted either as an index of the summation itself, or as a fully diagonal tensor whose elements are contractions of Kronecker deltas, e.g.

\[ K_{p,q,r,...} = \sum_\alpha \delta_\alpha^p \delta_\alpha^q \delta_\alpha^r \ldots. \]  
(A8)

The latter interpretation means that all contractions in the diagrams can be thought pairwise as in the normal case. Although not quite standard, this extension has been used before in the tensor network literature.\(^{47}\) Using our new notation, contracting a canonical polyadic decomposition of a third-order tensor back to a full tensor can be denoted as

\[ T_{pqrs} = \sum_\alpha A_{p,q} B_{r,s} C_{\alpha}. \]  
(A9)

If the dimensions of this tensor are $N \times N \times N$ and the rank of the decomposition (the dimension of the auxiliary index $\alpha$) is $N$, then the cost of rebuilding the original tensor from its decomposed form will scale as $O(N^4)$. We note that Eq. (A3) holds in this case just the same way as with normal pairwise contractions.

Let us also list diagrammatic representations of common matrix operations. The Frobenius norm of a tensor, which we recall is

\[ \|A\| = \sqrt{\sum_p \sum_q \sum_r \ldots A_{pqrs}^* A_{pqrs}} \]  
(A10)
is given diagrammatically as the square root of a tensor fully contracted with its own conjugate:

\[ |A| = \sqrt{A \cdot A} \]  \hspace{1cm} (A11)

We have used a darker color to denote complex conjugation here.

The column-wise Khatri-Rao product is

\[ D = A \odot B \quad \Rightarrow \quad D_{qp,\alpha} = A_{p,\alpha} \cdot B_{q,\alpha}. \]  \hspace{1cm} (A12)

Note that \( A \) and \( B \) should have the same number of columns to be compatible. The resulting matrix \( D \) can be reshaped to a third-order tensor with indices \( p, q \) and \( \alpha \). Diagrammatically, the Khatri-Rao product is

\[ \begin{bmatrix} A \end{bmatrix}_{p,\alpha} \quad \begin{bmatrix} B \end{bmatrix}_{q,\alpha} \quad \begin{bmatrix} D \end{bmatrix}_{qp,\alpha} \]  \hspace{1cm} (A13)

Here we used a thick line to denote a combined index \( qp \). Note also that the canonical polyadic decomposition can be conveniently expressed through the Khatri-Rao product, which is also reflected by the diagrams:

\[ T_{pq} = \sum_\alpha A_{p,\alpha} B_{q,\alpha} C_{r,\alpha} = (A \odot B \cdot C^T)_{pq} \]  \hspace{1cm} (A14)

Finally, we point out that wiring diagrams provide an easy way to calculate derivatives. A partial derivative of a tensor network with respect to one of its component tensors is simply the network with that tensor removed.