The second Noether theorem on time scales

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Abstract: We extend the second Noether theorem to variational problems on time scales. Our result provides as corollaries the classical second Noether theorem, the second Noether theorem for the $h$-calculus and the second Noether theorem for the $q$-calculus.

Keywords: time scales calculus, calculus of variations, gauge symmetries, Euler–Lagrange equations, Noether’s second theorem.

Mathematics Subject Classification 2010: 34N05, 37K05, 39A12, 49K15.

1 Introduction

In 1915, general relativity was almost a finished theory, but still there was a problem regarding the conservation of energy. David Hilbert asked for help in solving this problem the German mathematician Emmy Noether. She solved the problem proving two remarkable theorems that relate the invariance of a variational integral with properties of its Euler–Lagrange equations. These results were published in 1918 in the paper Invariante Variationsprobleme [44]. Noether was described by many important scientists, such as Pavel Alexandrov, Albert Einstein, Jean Dieudonné and David Hilbert, as the most important woman in the history of mathematics. In order to get a good exposition of the history of Emmy Noether and her important contributions to fundamental physics and mathematics, we refer the reader to the recent book [47]. This book explains very clearly that it took too much time before mathematicians and physicists began to recognize the importance of Noether’s theorems: until 1950 Noether’s theorems were poorly understood and Noether’s name disappeared almost entirely.

The first theorem in [44], usually known as Noether’s theorem, guarantees that the invariance of a variational integral with respect to a continuous symmetry transformations that depend on $\rho$ parameters implies the existence of $\rho$ conserved quantities along the Euler–Lagrange extremals. Such transformations are global transformations. Noether’s theorem explains all conservation laws of mechanics: conservation of energy comes from invariance of the system under time translations; conservation of linear momentum comes from invariance of the system under spatial translations; conservation of angular momentum reflects invariance with respect to spatial rotations.

The first Noether theorem is nowadays a well-known tool in a modern theoretical physics, engineering and the calculus of variations [4, 7, 23, 24, 31, 38, 40]. Inexplicably, it is still not well-known that the famous paper of Emmy Noether includes another important result, the second Noether theorem, which applies to variational problems that are invariant under a certain group of transformations, a so-called infinite continuous group, which depends on arbitrary functions and their derivatives (see also [29]). Such transformations are local transformations because can affect every part of the system differently. Noether’s second theorem states that

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if a variational integral has an infinite-dimensional Lie algebra of infinitesimal symmetries parameterized linearly by \( r \) arbitrary functions and their derivatives up to a given order \( m \), then there are \( r \) identities between Euler–Lagrange expressions and their derivatives up to order \( m \). These identities Noether called “dependencies”. For example, the Bianchi identities, in the general theory of relativity, are examples of such “dependencies”. Noether’s second theorem has applications in general relativity, electrodynamics, hydromechanics, quantum chromodynamics and other gauge field theories. Motivated by the important applications of the second Noether theorem, our goal in this paper is to generalize this result proving that the second Noether Theorem is valid for an infinite number of time scales. As we will see, in the particular case where the time scale \( T \) is \( \mathbb{R} \), we get from our result the classical second Noether theorem; when \( T = \mathbb{Z} \) we obtain the analogue of the second Noether theorem for the difference calculus of variations; when \( T = q^{\mathbb{N}_0} \) (for some \( q > 1 \)) we obtain a new result: the second Noether theorem for the \( q \)-calculus (quantum calculus). For more on the theory of quantum calculus and quantum calculus of variation we refer to [1], [5], [6], [17], [18], [19], [20], [34], [36], [43], [45].

The theory of time scales was introduced in 1988 by Stefan Hilger in his Ph.D thesis [26] as a means of unifying theories of differential calculus and difference calculus into a single theory. With a short time this unification aspect has been supplemented by the extension and generalization features. The time scale calculus allows to consider more complex time domains, such as \( h\mathbb{Z}, T = q^{\mathbb{N}_0} \) or hybrid domains. The study of the calculus of variations in the context of time scales had its beginning only in 2004 with the paper [11] of Martin Bohner (see also [27]). Since then, the variational calculus on time scales advanced fairly quickly, as can be verified with the large number of published papers on the subject [3], [12], [21], [22], [25], [33], [35], [37], [39], [41], [42]. Noether’s first theorem has been extended to the variational calculus on time scales using several approaches [7], [8], [40], while the second Noether theorem on time scales is still not available in the literature. So there is evidently a need for a time scale analogue of Noether’s second theorem.

The paper is organized as follows. In Section 2 we review some preliminaries about single-variable variational calculus on time scales, for example we recall the Euler–Lagrange equation for a delta variational problem. Our main results are stated in Section 3. Namely, in Subsection 3.1 we prove Noether’s second theorem for variational problems involving a single delta integral (with and without transformation of time) and in Subsection 3.2 we prove Noether’s second theorem for variational problems involving multiple delta integrals (without transformation of time). Section 4 provides a concrete example of application of our results. Finally, in Section 5 we present some concluding remarks.

## 2 Preliminaries

In this paper we assume the reader to be familiar with the calculus on time scales. For a good introduction to the theory of time scales we refer to the well-known books in this field [9], [10]. The first developments on time scale calculus was done essentially using the delta-calculus. However, for some applications, in particular to solve problems of the calculus of variations and control theory in economics, is often more convenient to work backwards in time, that is, using the nabla-calculus. In this paper we are concerned with the delta-calculus. It is clear that all the arguments used in the proofs of our results can be modified to work for the nabla-calculus. In what follows we review some preliminaries about the variational calculus on time scales needed in this paper.

Let \( T \) be a given time scale, \( n \in \mathbb{N} \), and \( L : T \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R} \) be continuous, together with its partial delta derivatives of first and second order with respect to \( t \) and partial usual derivatives of the first and second order with respect to the other variables. Suppose that \( a, b \in T \) and \( a < b \). We consider the following optimization problem on \( T \):

\[
\mathcal{L}[y] = \int_a^b L(t, y^\sigma(t), y^\Delta(t)) \Delta t \rightarrow \text{extremize},
\]

(1)
In what follows all intervals are time scales intervals, that is, we simply write $[a, b] \cap T \to \mathbb{R}^n$. By extremize we mean maximize or minimize. As usual, $y^\sigma(t)$ denotes $y(\sigma(t))$ and $[a, b]^\kappa := [a, \rho(b)]$, where $\rho$ is the backward jump operator. By extremize we mean maximize or minimize.

In what follows all intervals are time scales intervals, that is, we simply write $[a, b]$ to denote the set $[a, b] \cap T$. Let $y := (y_1, \ldots, y_n)$ and denote by $\frac{\partial L}{\partial y_k}$ the partial derivative of $L$ with respect to $y_k$.

**Definition 1** We say that $y_* \in C^1_{rd}([a, b], \mathbb{R}^n)$ is a local minimizer (resp. local maximizer) for problem (1) if there exists $\delta > 0$ such that

$$L[y_*] \leq L[y] \quad (\text{resp. } L[y_*] \geq L[y])$$

for all $y \in C^1_{rd}([a, b], \mathbb{R}^n)$ satisfying the boundary conditions $y(a) = \alpha$, $y(b) = \beta$, and

$$\|y - y_*\| := \sup_{t \in [a, b]^\kappa} |y^\sigma(t) - y_*^\sigma(t)| + \sup_{t \in [a, b]^\kappa} |y^\Delta(t) - y_*^\Delta(t)| < \delta,$$

where $| \cdot |$ denotes a norm in $\mathbb{R}^n$.

**Definition 2** We say that $\eta \in C^1_{rd}([a, b], \mathbb{R}^n)$ is an admissible variation for problem (1) provided $\eta(a) = \eta(b) = 0$.

**Definition 3** A function $f : [a, b] \times \mathbb{R} \to \mathbb{R}$ is called continuous in the second variable, uniformly in the first variable, if for each $\epsilon > 0$, there exists $\delta > 0$ such that $|x_1 - x_2| < \delta$ implies $|f(t, x_1) - f(t, x_2)| < \epsilon$ for all $t \in [a, b]$.

**Lemma 4** Suppose that $\eta := (\eta_1, \ldots, \eta_n)$ is an admissible variation for problem (1) and $y := (y_1, \ldots, y_n) \in \mathcal{D}$. Let $\phi : [a, b] \to \mathbb{R}$ and $f : [a, b] \times \mathbb{R} \to \mathbb{R}$ be defined, respectively, by $\phi(\epsilon) := L[y + \epsilon \eta]$ and $f(t, \epsilon) := L(t, y^\sigma(t) + \epsilon \eta^\sigma(t), y^\Delta(t) + \epsilon \eta^\Delta(t))$. If $\frac{\partial f}{\partial \epsilon}$ is continuous in $\epsilon$, uniformly in $t$, then

$$\phi(0) = \int_a^b \sum_{k=1}^n \left( \frac{\partial L}{\partial y_k^\sigma}(t, y^\sigma(t), y^\Delta(t))\eta_k^\sigma(t) + \frac{\partial L}{\partial y_k^\Delta}(t, y^\sigma(t), y^\Delta(t))\eta_k^\Delta(t) \right) \Delta t.$$ 

Next we present the following result that is a fundamental tool in the calculus of variations on time scales.

**Theorem 5** If $y_*$ is a weak local extremizer for problem (1) and $L$ satisfies the assumption of Lemma 4 for every $y$ and $\eta$, then the components of $y_*$ satisfies the n Euler–Lagrange equations

$$\frac{\Delta}{\Delta t} \frac{\partial L}{\partial y_k^\sigma}(t, y_*^\sigma(t), y_*^\Delta(t)) = \frac{\partial L}{\partial y_k^\sigma}(t, y_*^\sigma(t), y_*^\Delta(t)), \quad k = 1, \ldots, n$$

for $t \in [a, b]^\kappa$.

It is well-known that the forward jump operator, $\sigma$, is not delta differentiable for certain time scales. Also, the chain rule as we know it from the classical calculus (that is, when $T = \mathbb{R}$) is not valid in general. However, if we suppose that the time scale $T$ satisfies the following condition
for each $t \in \mathbb{T}$, $\sigma(t) = b_1 t + b_0$ for some $b_1 \in \mathbb{R}^+$ and $b_0 \in \mathbb{R}$

then we can deal with these two limitations as noticed in Remark 6 and Lemma 4.

**Remark 6** Note that condition (H) implies that $\sigma$ is delta differentiable and $\sigma^\Delta(t) = b_1$, $t \in \mathbb{T}^\kappa$.

Also note that condition (H) describes, in particular, the differential calculus ($\mathbb{T} = \mathbb{R}$, $b_1 = 1$, $b_0 = 0$), the difference calculus ($\mathbb{T} = \mathbb{Z}$, $b_1 = 1$, $b_0 = 1$), the h-calculus ($\mathbb{T} = h\mathbb{Z} := \{hz : z \in \mathbb{Z}\}$, $b_1 = 1$, $b_0 = h$ for some $h > 0$), and the q-calculus ($\mathbb{T} = q^{\mathbb{N}_0} := \{q^k : k \in \mathbb{N}_0\}$ for some $q > 1$, $b_1 = q$, $b_0 = 0$).

**Lemma 7** (21) Let $\mathbb{T}$ be a time scale satisfying condition (H). If $f : \mathbb{T} \to \mathbb{R}$ is two times delta differentiable, then

$$f^\sigma^\Delta(t) = b_1 f^\Delta(t), \quad t \in \mathbb{T}^\kappa.$$  

The next result is also useful for the proofs of our main results.

**Lemma 8** (cf. 22) Assume that the time scale $\mathbb{T}$ satisfies condition (H), $m \in \mathbb{N}$, and $\eta \in C^m([a,b], \mathbb{R})$ is such that $\eta^\Delta(a) = 0$ for all $i = 0, 1, \ldots, m$. Then, $\eta^\Delta^m(a) = 0$ for each $i = 1, \ldots, m$.

### 3 Main results

In this section we formulate and prove the second Noether theorem for single and multiple integral variational problems.

#### 3.1 Noether’s second theorem - single delta integral case

In this subsection we suppose that the time scale $\mathbb{T}$ satisfies condition (H) and that $L$ satisfies the assumption of Lemma 3 for every $y$ and $\eta$. As usual, $\eta^\Delta$ and $\eta^\sigma$ denote $\eta$. Let $m$ be a fixed natural number. We also assume that the time scale interval $[a,b]$ has, at least, $2m + 1$ points.

We begin with some technical results that will be useful in the proofs of Theorems 16 and 22.

**Lemma 9** (Higher-order fundamental lemma of the calculus of variations) Let $\mathbb{T}$ be a time scale satisfying condition (H) and $f_0, f_1, \cdots, f_m \in C^m([a,b], \mathbb{R})$. If

$$\int_a^{\rho^m(b)} \left( \sum_{i=0}^{m} f_i(t) \eta^{(m-1)\Delta^i}(t) \right) \Delta t = 0$$  

for all $\eta \in C^m([a,b], \mathbb{R})$ such that

$$\eta(a) = 0, \quad \eta\left(\rho^{m-1}(b)\right) = 0,$$

$$\vdots$$

$$\eta^{\Delta^{m-1}}(a) = 0, \quad \eta^{\Delta^{m-1}}\left(\rho^{m-1}(b)\right) = 0,$$

then

$$\sum_{i=0}^{m} (-1)^i \left( \frac{1}{b_1} \right)^{i(i+1)/2} f_i^{\Delta^i}(t) = 0, \quad t \in [a,b]^m.$$  

**Proof.** The proof is similar to the proof of Lemma 16 of [39].
Remark 10 We emphasize that the delta differentiability of the functions $f_0, f_1, \ldots, f_m$ was not assumed in advance.

Lemma 11 Assume that the time scale $\mathbb{T}$ satisfies condition (H) and $\eta \in C^2_{rd}([a, b], \mathbb{R})$ is such that,

$$\eta^\Delta(a) = 0, \quad i = 0, 1, \ldots, m.$$ 

Then,

$$\eta^\sigma(a) = 0, \quad i = 0, 1, \ldots, m.$$ 

Proof. If $a$ is right-dense, the result is trivial. Suppose that $a$ is right-scattered. Since $\eta^\Delta(a) = \frac{\eta^\sigma(a) - \eta(a)}{\sigma(a) - a} = 0$ and $\eta(a) = 0$, we conclude that $\eta^\sigma(a) = 0$. Since $\eta^\Delta(a) = (\eta^\Delta)^\sigma(a) = (\eta^\Delta)^\Delta(a)$, we get $\eta^\Delta^\sigma(a) = 0$. Using Lemma 7, we get $\eta^\Delta(a) = 0$. Since $\eta^\Delta(a) = \frac{\eta^\Delta^\sigma(a) - \eta^\Delta(a)}{\sigma(a) - a} = 0$ and $\eta^\Delta(a) = 0$, then $\eta^\Delta^\sigma(a) = 0$. Using Lemma 7 we get $\eta^\Delta(a) = 0$. Since $\eta^\Delta(a) = \frac{\eta^\Delta^\sigma(a) - \eta^\Delta(a)}{\sigma(a) - a} = 0$ and $\eta^\Delta(a) = 0$, then $\eta^\Delta^\sigma(a) = 0$. Lemma 7 proves that $\eta^\Delta(a) = 0$. Since $\eta^\Delta^\sigma(a) = \frac{\eta^\Delta^\sigma(a) - \eta^\Delta^\sigma(a)}{\sigma(a) - a} = 0$ and $\eta^\Delta^\sigma(a) = 0$, we get $\eta^\Delta^\sigma(a) = 0$. Repeating recursively this process, we conclude the proof.

Lemma 12 Assume that the time scale $\mathbb{T}$ satisfies condition (H) and $\eta \in C^2_{rd}([a, b], \mathbb{R})$ is such that,

$$\eta^\Delta(a) = 0, \quad i = 0, 1, \ldots, m - 1.$$ 

Then,

$$\eta^\sigma(a) = 0, \quad i = 0, 1, \ldots, m.$$ 

Proof. If $a$ is right-dense, the result is trivial. Suppose that $a$ is right-scattered. Since $\eta^\Delta^m(a) = \frac{\eta^\Delta^{m-2}\sigma(a) - \eta^\Delta^{m-2}(a)}{\sigma(a) - a} = 0$ and $\eta^\Delta^{m-2}(a) = 0$, then $\eta^\Delta^m(a) = 0$. Using Lemma 7 we get $\eta^\sigma^m(a) = 0$ or use Lemma 8. Note that $\eta^\sigma^m(a) = \frac{\eta^\sigma^{m-3}\sigma(a) - \eta^\sigma^{m-3}(a)}{\sigma(a) - a} = 0$. Lemma 8 shows that $\eta^\sigma^{m-3}(a) = 0$, hence $\eta^\sigma^{m-3}(a) = 0$. Using Lemma 7 we get $\eta^\sigma^{m-3}(a) = 0$. Next we prove that $\eta^\sigma^{m-4}(a) = 0$. Since $\eta^\sigma^{m-3}(a) = \frac{\eta^\sigma^{m-4}\sigma(a) - \eta^\sigma^{m-4}(a)}{\sigma(a) - a} = 0$ and $\eta^\sigma^{m-4}(a) = 0$, then $\eta^\sigma^{m-4}(a) = 0$. Lemma 7 shows that $\eta^\sigma^{m-4}(a) = 0$. Since $\eta^\sigma^{m-4}(a) = \frac{\eta^\sigma^{m-5}\sigma(a) - \eta^\sigma^{m-5}(a)}{\sigma(a) - a} = 0$ and $\eta^\sigma^{m-5}(a) = 0$, then $\eta^\sigma^{m-5}(a) = 0$. Lemma 7 shows that $\eta^\sigma^{m-5}(a) = 0$. Repeating recursively this process, we prove the intended result.

Let $y := (y_1, y_2, \ldots, y_n)$. Firstly we will prove the second Noether theorem without transformation of time. For that consider the following transformations that depend on arbitrary functions $p_1, p_2, \ldots, p_r$ and their delta-derivatives up to order $m$: 

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\begin{align}
\left\{ \begin{array}{l}
\overline{t} = t \\
\overline{y}_k(t) = y_k(t) + \sum_{j=1}^{r} T^{kj}(p_j)(t), \quad k = 1, 2, \ldots, n
\end{array} \right. \tag{2}
\end{align}

where, for each \( j = 1, 2, \ldots, r \), \( p_j \in C_{rd}^{2m}([a, \sigma^m(b)], \mathbb{R}) \),

\[ T^{kj}(p_j) := \sum_{i=0}^{m} g_{ij}^k p_{j}^{\sigma^m-(i+1)} \Delta^i \]

and \( g_{ij}^k \in C_{rd}^{1}([a, b], \mathbb{R}) \).

**Definition 13** \( \text{Functional } \mathcal{L} \text{ is invariant under transformations (2)} \) if, and only if, for all \( y \in C_{rd}^{1}([a, b], \mathbb{R}) \) we have

\[ \int_{a}^{b} L(t, y^\sigma(t), y^\Delta(t)) \Delta t = \int_{a}^{b} L(t, \overline{y}^\sigma(t), \overline{y}^\Delta(t)) \Delta t. \]

**Remark 14** Note that the most common definition of invariance (with equality of the integrals for any subinterval \([t_a, t_b] \subseteq [a, b] \) with \( a, b \in \mathbb{T} \)) implies Definition 13.

**Theorem 15 (Necessary condition of invariance)** \( \text{If functional } \mathcal{L} \text{ is invariant under transformations (2), then} \)

\[ \sum_{k=1}^{n} \int_{a}^{b} \left( \frac{\partial L}{\partial y_k^\sigma}(t, y^\sigma(t), y^\Delta(t)) \cdot \left( \sum_{j=1}^{r} T^{kj}(p_j) \right)^\sigma(t) + \frac{\partial L}{\partial y_k^\Delta}(t, y^\sigma(t), y^\Delta(t)) \cdot \left( \sum_{j=1}^{r} T^{kj}(p_j) \right)^\Delta(t) \right) \Delta t = 0. \] \tag{3}

**Proof.** Using the definition of invariance and noting that the family of transformations (2) depend upon arbitrary functions \( p_1, p_2, \ldots, p_r \), we conclude that, for any real number \( \varepsilon \),

\[ \int_{a}^{b} L(t, y^\sigma(t), y^\Delta(t)) \Delta t = \int_{a}^{b} L \left( t, y^\sigma(t) + \varepsilon \left( \sum_{j=1}^{r} T^{ij}(p_j) \right)^\sigma(t) , . . . , y_n^\sigma(t) + \varepsilon \left( \sum_{j=1}^{r} T^{nj}(p_j) \right)^\sigma(t) , y_1^\Delta(t) + \varepsilon \left( \sum_{j=1}^{r} T^{ij}(p_j) \right)^\Delta(t) , . . . , y_n^\Delta(t) + \varepsilon \left( \sum_{j=1}^{r} T^{nj}(p_j) \right)^\Delta(t) \right) \Delta t. \]

Differentiating with respect to \( \varepsilon \) (use Lemma 4) and taking \( \varepsilon = 0 \), we get equality 3. \qed

Define

\[ E_k(L) := \frac{\partial L}{\partial y_k^\sigma} \frac{\Delta}{\Delta t} \frac{\partial L}{\partial y_k^\Delta}, \quad k = 1, 2, \ldots, n. \]

We shall call \( E_k(L), k = 1, 2, \ldots, n \), the Euler–Lagrange expressions associated to the Lagrangian \( L \).

**Theorem 16 (Noether’s second theorem without transforming time)** \( \text{If functional } \mathcal{L} \text{ is invariant under transformations (2), then there exist the following identities} \)

\[ \sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left( \frac{1}{b_1} \right)^{(i+1)} \left( (g_{ij}^k)^\sigma E_k(L) \right)^\Delta^i = 0, \quad j = 1, 2, \ldots, r. \]
Proof. Using the necessary condition of invariance (Theorem 15) we conclude that

\[ \sum_{k=1}^{n} \int_{a}^{b} \left( \frac{\partial L}{\partial y_{k}}(t, y^{\sigma}(t), y^{\Delta}(t)) \cdot \left( \sum_{j=1}^{r} T^{kj}(p_{j}) \right)^{\sigma} \right)\Delta t = 0. \]

Fix \( j = 1, 2, \ldots, r \). By the arbitrariness of \( p_{1}, p_{2}, \ldots, p_{r} \) we can suppose that \( p_{h} \equiv 0 \) for \( h \neq j \).

Therefore

\[ \sum_{k=1}^{n} \int_{a}^{b} \left( \frac{\partial L}{\partial y_{k}}(t, y^{\sigma}(t), y^{\Delta}(t)) \cdot (T^{kj}(p_{j}))^{\sigma} \right)\Delta t = 0. \]

Integrating by parts we obtain

\[ \sum_{k=1}^{n} \left( \int_{a}^{b} \left( \frac{\partial L}{\partial y_{k}}(t, y^{\sigma}(t), y^{\Delta}(t)) - \frac{\Delta}{\Delta t} \frac{\partial L}{\partial y_{k}}(t, y^{\sigma}(t), y^{\Delta}(t)) \right) \cdot (T^{kj}(p_{j}))^{\sigma} \right)\Delta t \]

\[ + \left[ \frac{\partial L}{\partial y_{k}}(t, y^{\sigma}(t), y^{\Delta}(t)) \cdot T^{kj}(p_{j}) \right]^{b}_{a} = 0. \]

By the arbitrariness of \( p_{j} \) we can restrict to those functions such that

\[ p_{j}(a) = 0, \quad p_{j}(b) = 0, \]

\[ \vdots \]

\[ p_{j}^{m-1}(a) = 0, \quad p_{j}^{m-1}(b) = 0, \]

and

\[ p_{j}^{\sigma-1 \Delta m}(a) = 0, \quad p_{j}^{\sigma-1 \Delta m}(b) = 0. \]

Using Lemmas 8, 11 and 12 we conclude that \( T^{kj}(p_{j})(a) = 0 \) and \( T^{kj}(p_{j})(b) = 0, k = 1, 2, \ldots, n. \)

Then

\[ \sum_{k=1}^{n} \int_{a}^{b} E_{k}(L)(t, y^{\sigma}(t), y^{\Delta}(t)) \cdot (T^{kj}(p_{j}))^{\sigma} \right)\Delta t = 0. \]

that is,

\[ \sum_{k=1}^{n} \int_{a}^{b} E_{k}(L)(t, y^{\sigma}(t), y^{\Delta}(t)) \cdot (T^{kj}(p_{j}))^{\sigma} \right)\Delta t = 0. \]

Hence,

\[ \sum_{k=1}^{n} \int_{a}^{b} E_{k}(L)(t, y^{\sigma}(t), y^{\Delta}(t)) \cdot \left( \sum_{i=0}^{m} g_{ij}^{k} p_{j}^{\sigma m-i \Delta i} \right)^{\sigma} \right)\Delta t = 0. \]

Therefore, by Lemma 7 we get

\[ \int_{a}^{b} \sum_{i=0}^{m} \sum_{k=1}^{n} E_{k}(L)(t, y^{\sigma}(t), y^{\Delta}(t)) \cdot (g_{ij}^{k})^{\sigma}(t) \left( \frac{1}{b_{1}} \right)^{i} p_{j}^{\sigma m-i \Delta i} \right)\Delta i = 0. \]

Applying the higher-order fundamental lemma of the calculus of variations (Lemma 9) we obtain

\[ \sum_{i=0}^{m} \sum_{k=1}^{n} (-1)^{i} \left( \frac{1}{b_{1}} \right)^{\frac{m-i}{2}} \left( \sum_{j=0}^{r} \frac{1}{b_{1}} \right)^{i} \Delta i = 0. \]
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which is equivalent to

\[ \sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left( \frac{1}{b_1} \right)^{\frac{i(i+1)}{2}} \left( (g_{ij}^k)^{\sigma} E_k(L) \right) \Delta^i = 0 \]

proving the desired result. ■

We present some particular results that follow from Theorem 16 in the case where \( T = \mathbb{R} \), \( T = h\mathbb{Z} \) (for some \( h > 0 \)), and \( T = q^{\mathbb{N}_0} \) (for some \( q > 1 \)). If \( T = \mathbb{R} \), then \( \sigma(t) = t, f^\Delta(t) = \dot{f}(t) \) and we obtain the classical second Noether theorem without transformation of time.

**Corollary 17 (cf. [44])** Let \( L : \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R} \) be a \( C^2 \) function. If functional \( \mathcal{L} \) defined by

\[ \mathcal{L}[y] = \int_a^b L(t, y(t), \dot{y}(t)) \, dt \]

is invariant under transformations \( \sigma \) (where \( \sigma \) denotes in this context the identity function and \( \Delta \) denotes the usual derivative), then there exist the following identities

\[ \sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left[ g_{ij}^k \mathcal{L}(L) \right]^{(i)} = 0, \quad j = 1, 2, \ldots, r. \]

Choosing \( h\mathbb{Z} \) we obtain Noether’s second theorem without transformation of time for the \( h \)-calculus.

**Corollary 18** Let \( h > 0 \), \( L : h\mathbb{Z} \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R} \) and \( a, b \in h\mathbb{Z}, \ a < b \). If functional \( \mathcal{L} \) defined by

\[ \mathcal{L}[y] = \sum_{t=a}^{b-h} L(t, y(t+h), \Delta h[y](t)) \]

is invariant under transformations \( \sigma \) (where \( \sigma \) denotes in this context the function \( \sigma(t) = t+h \) and \( \Delta \) denotes the \( h \)-difference, i.e., \( y^\Delta(t) = \Delta h[y](t) = \frac{y(t+h)-y(t)}{h} \)), then there exist the following identities

\[ \sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left[ g_{ij}^k(t+h) \cdot E_k(L)(t, y(t+h), \Delta h[y](t)) \right] \Delta^i = 0, \quad t \in [a, b-mh], \quad j = 1, 2, \ldots, r. \]

For \( h = 1 \) we obtain the analogue of Noether’s second theorem for the difference calculus of variations recently proved in [28]. In the case \( T = q^{\mathbb{N}_0} \) we obtain the new result.

**Corollary 19** Let \( q > 1 \), \( L : q^{\mathbb{N}_0} \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R} \) and \( a, b \in q^{\mathbb{N}_0}, \ a < b \). If functional \( \mathcal{L} \) defined by

\[ \mathcal{L}[y] = \sum_{t=a}^{b} L(t, y(qt), \Delta q[y](t)) \]

is invariant under transformations \( \sigma \) (where \( \sigma \) denotes in this context the function \( \sigma(t) = qt \) and \( \Delta \) denotes the \( q \)-derivative, i.e. \( y^\Delta(t) = \Delta q[y](t) = \frac{y(qt)-y(t)}{(q-1)t} \)), then there exist the following identities

\[ \sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left( \frac{1}{q} \right)^{\frac{i(i+1)}{2}} \left[ g_{ij}^k(qt) \cdot E_k(L)(t, y(qt), \Delta q[y](t)) \right] \Delta^i = 0, \quad t \in \left[ a, \frac{b}{q^m} \right], \quad j = 1, 2, \ldots, r. \]
In order to prove the second Noether theorem with transformation of time, we shall consider that the Lagrangian $L$ is defined for all $t \in \mathbb{R}$ (not only for $t$ from the initial time scale $\mathbb{T}$), $L : \mathbb{R} \times \mathbb{R}^n \times \mathbb{R}^n \to \mathbb{R}$. Consider the following transformations that depend on arbitrary functions $p_1, p_2, \ldots, p_r$ and their delta-derivatives up to order $m$:

\[
\begin{align*}
\tau(t) &= t + \sum_{j=1}^{r} H^j(p_j)(t), \\
\gamma_k(\tau) &= y_k(t) + \sum_{j=1}^{r} T^k_j(p_j)(t), \quad k = 1, 2, \ldots, n
\end{align*}
\]  

(4)

where, for each $j = 1, 2, \ldots, r$, $p_j \in C^m_{rd}([a, \sigma^n(b)], \mathbb{R})$,

\[
H^j(p_j) := \sum_{i=0}^{m} f_{ij} p_j^{m-(i+1) \Delta^i} \quad \text{and} \quad T^k_j(p_j) := \sum_{i=0}^{m} g_{ij} p_j^{m-(i+1) \Delta^i}
\]

$f_{ij} \in C^1_{rd}([a, b], \mathbb{R})$ and $g_{ij} \in C^1_{rd}([a, b], \mathbb{R})$.

Moreover we assume that the map

\[
t(t) \mapsto \alpha(t) := t + \sum_{j=1}^{r} H^j(p_j)(t)
\]

is a strictly increasing $C^1_{rd}$ function and its image is again a time scale, $\overline{\mathbb{T}}$. We denote the forward shift operator relative to $\overline{\mathbb{T}}$ by $\overline{\sigma}$ and the delta derivative by $\overline{\Delta}$. We remark that the following holds\textsuperscript{[2]}:

\[
\overline{\sigma} \circ \alpha = \alpha \circ \sigma.
\]

**Definition 20** Functional $L$ is invariant under transformations\textsuperscript{[4]} if, and only if, for all $y \in C^1_{rd}([a, b], \mathbb{R})$ we have

\[
\int_{a}^{b} L(t, y^\sigma(t), y^\Delta(t)) \Delta t = \int_{\overline{a}}^{\overline{b}} L(\overline{t}, \overline{y}^\sigma(\overline{t}), \overline{y}^\Delta(\overline{t})) \overline{\Delta} t.
\]

We recall the following results that will be very useful in the proof of Theorem\textsuperscript{[22]}

**Theorem 21** (\cite{9}) Assume that $\nu : \mathbb{T} \to \mathbb{R}$ is strictly increasing and $\overline{\mathbb{T}} := \nu(\mathbb{T})$ is a time scale.

1. (Chain rule) Let $\omega : \overline{\mathbb{T}} \to \mathbb{R}$. If $\nu^\Delta(t)$ and $\omega^\overline{\Delta}(\nu(t))$ exist for all $t \in \mathbb{T}^\infty$, then

\[
(\omega \circ \nu)^\Delta = (\omega^\overline{\Delta} \circ \nu) \nu^\Delta.
\]

2. (Substitution in the integral) If $f : \overline{\mathbb{T}} \to \mathbb{R}$ is a $C^1_{rd}$ function and $\nu$ is a $C^1_{rd}$ function, then for $a, b \in \mathbb{T}$,

\[
\int_{a}^{b} f(\nu(t)) \nu^\Delta(t) \Delta t = \int_{\nu(a)}^{\nu(b)} f(s) \overline{\Delta} s.
\]

Now we are ready to state and prove Noether’s second theorem with transformation of time.

**Theorem 22** (Noether’s second theorem with transformation of time) If functional $L$ is invariant under transformations\textsuperscript{[4]}, then there exist the following identities

\[
\sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left( \frac{1}{b_k} \right)^{i+1} \left[ \left( g_{ij}^k \right)^\sigma E_k(L) \right]^{\Delta^i} + \left( f_{ij} \right)^\sigma \left( \frac{\partial L}{\partial t} \frac{\Delta^i}{\Delta t} \left( L - y_{k}\frac{\partial L}{\partial y_k} + \mu \frac{\partial L}{\partial \mu} \right) \right)^{\Delta^i} = 0
\]

(5)

for $j = 1, 2, \ldots, r$. 


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**Proof.** The idea of the proof is to reduce the statement of this result to the one of Theorem 16 using a technique of reparametrization of time: artificially we will consider \( t \) as a dependent variable of the same footing with \( y \).

Let \( r \neq 0 \) and define

\[
\tilde{L}(t, s, y, r, v) := L(s - \mu(t)r, y, \frac{v}{r})r.
\]

Note that, for \( s(t) = t \) and any \( y \in C^1_{rd}([a, b], \mathbb{R}^n) \), we have

\[
L(t, y^\sigma(t), y^\Delta(t)) = \tilde{L}(t, s^\sigma(t), y^\sigma(t), s^\Delta(t), y^\Delta(t)).
\]

Therefore, for \( s(t) = t \),

\[
\mathcal{L}[y] := \int_a^b L(t, y^\sigma(t), y^\Delta(t))\Delta t = \int_a^b \tilde{L}(t, s^\sigma(t), y^\sigma(t), s^\Delta(t), y^\Delta(t))\Delta t := \tilde{\mathcal{L}}[s, y].
\]

Note that, for \( s(t) = t \),

\[
\tilde{\mathcal{L}}[s(\cdot), y(\cdot)] = \mathcal{L}[y(\cdot)] = \int_a^b L(t, y^\sigma(t), y^\Delta(t))\Delta t
\]

\[
= \int_{\alpha(a)}^{\alpha(b)} L(\tilde{t}, (\tilde{y} \circ \tilde{\sigma})(\tilde{t}), \tilde{y}^\Delta(\tilde{t}))\Delta \tilde{t}
\]

\[
= \int_{\alpha(a)}^{\alpha(b)} L \left( \alpha(t), (\tilde{y} \circ \alpha)(t), \tilde{y}^\Delta(\alpha(t)) \right) \alpha^\Delta(t)\Delta t
\]

\[
= \int_{\alpha(a)}^{\alpha(b)} L \left( \alpha(t), (\tilde{y} \circ \alpha \circ \sigma)(t), \frac{(\tilde{y} \circ \alpha \circ \sigma)^\Delta(t)}{\alpha^\Delta(t)} \right) \alpha^\Delta(t)\Delta t
\]

\[
= \int_{\alpha(a)}^{\alpha(b)} \tilde{L} \left( t, \alpha^\sigma(t), (\tilde{y} \circ \alpha)^\sigma(t), \alpha^\Delta(t), \frac{(\tilde{y} \circ \alpha)^\Delta(t)}{\alpha^\Delta(t)} \right) \Delta t
\]

\[
= \tilde{\mathcal{L}}[\alpha(\cdot), (\tilde{y} \circ \alpha)(\cdot)].
\]

Let \( H(t, y(t)) := \alpha(t) \) and \( T = (T^1, T^2, \ldots, T^n) \) where

\[
T^k(t, y(t)) := y_k(t) + \sum_{j=1}^{r} T^{kj}(p_j)(t), \quad k = 1, 2, \ldots, n.
\]

Then, for \( s(t) = t \),

\[
(\alpha(t), (\tilde{y} \circ \alpha)(t)) = (\tilde{t}, \tilde{y}(\tilde{t})) = (H(t, y(t)), T(t, y(t))) = (H(s(t), y(t)), T(s(t), y(t))).
\]

Hence, using (6) and (7) we get

\[
\tilde{\mathcal{L}}[s(\cdot), y(\cdot)] = \tilde{\mathcal{L}}[H(s(\cdot), y(\cdot)), T(s(\cdot), y(\cdot))].
\]

This means that \( \tilde{\mathcal{L}} \) is invariant on

\[
\tilde{U} = \{(s, y)|s(t) = t \wedge y \in C^1_{rd}([a, b], \mathbb{R}^n)\}
\]

under the group of state transformations

\[
(\tilde{\sigma}, \tilde{\rho}) = (H(s, y), T(s, y))
\]
in the sense of Definition \[13\].

Using Theorem \[16\] we can conclude that there exist the following \(r\) identities \((j = 1, 2, \ldots, r)\)

\[
\sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left( \frac{1}{b_1} \right)^{i+1} \sigma^i \left( g_{ij}^k \sigma E_k(\bar{L}) \right) \Delta^i + \sum_{i=0}^{m} (-1)^i \left( \frac{1}{b_1} \right)^{i+1} \left( f_{ij} \sigma E_s(\bar{L}) \right) \Delta^i \equiv 0
\]

(8)

where we denote \(E_s(\bar{L}) := \frac{\partial L}{\partial s} - \frac{\partial L}{\partial s}\).

Note that, for \(s(t) = t\),

\[
\frac{\partial L}{\partial s^\sigma}(t, s^\sigma(t), y^\sigma(t), s^\Delta(t), y^\Delta(t)) = \frac{\partial L}{\partial t} \left( s^\sigma(t) - \mu(t)s^\Delta(t), y^\sigma(t), \frac{y^\Delta(t)}{s^\Delta(t)} \right) s^\sigma(t)
\]

and

\[
\frac{\partial L}{\partial s^\Delta}(t, s^\sigma(t), y^\sigma(t), s^\Delta(t), y^\Delta(t)) = L \left( s^\sigma(t) - \mu(t)s^\Delta(t), y^\sigma(t), \frac{y^\Delta(t)}{s^\Delta(t)} \right)
\]

\[
- \sum_{k=1}^{n} \frac{y^\Delta(t)}{s^\Delta(t)} \frac{\partial L}{\partial y_k} \left( s^\sigma(t) - \mu(t)s^\Delta(t), y^\sigma(t), \frac{y^\Delta(t)}{s^\Delta(t)} \right)
\]

\[
- \frac{\partial L}{\partial t} \left( s^\sigma(t) - \mu(t)s^\Delta(t), y^\sigma(t), \frac{y^\Delta(t)}{s^\Delta(t)} \right) \mu(t)s^\Delta(t).
\]

Hence, for \(s(t) = t\),

\[
E_s(\bar{L})(t, s^\sigma(t), y^\sigma(t), s^\Delta(t), y^\Delta(t))
\]

\[
= \frac{\partial L}{\partial t} \left( t, y^\sigma(t), y^\Delta(t) \right)
\]

\[
- \frac{\Delta}{\Delta t} \left( L(t, y^\sigma(t), y^\Delta(t)) - \sum_{k=1}^{n} \frac{y^\Delta(t)}{s^\Delta(t)} \frac{\partial L}{\partial y_k} \left( t, y^\sigma(t), y^\Delta(t) \right) - \mu(t) \frac{\partial L}{\partial t} \left( t, y^\sigma(t), y^\Delta(t) \right) \right).
\]

Also note that, for \(s(t) = t\) and \(k = 1, 2, \ldots, n\),

\[
E_k(\bar{L})(t, s^\sigma(t), y^\sigma(t), s^\Delta(t), y^\Delta(t)) = E_k(L)(t, y^\sigma(t), y^\Delta(t)).
\]

Substituting the above equalities into \(8\), we conclude the desired result:

\[
\sum_{k=1}^{n} \sum_{i=0}^{m} (-1)^i \left( \frac{1}{b_1} \right)^{i+1} \sigma^i \left( g_{ij}^k \sigma E_k(L) \right) \Delta^i + \left( f_{ij} \sigma \left( \frac{\partial L}{\partial t} - \frac{\Delta}{\Delta t} \left( L - \sum_{k=1}^{n} \frac{y^\Delta(t)}{s^\Delta(t)} \frac{\partial L}{\partial y_k} - \mu(t) \frac{\partial L}{\partial t} \right) \right) \right) \Delta^i \equiv 0
\]

for \(j = 1, 2, \ldots, r\).

\[\Box\]

**Remark 23** Define

\[
E^*_k(L) := \frac{\partial L}{\partial t} - \frac{\Delta}{\Delta t} \left( L - \sum_{k=1}^{n} \frac{y^\Delta(t)}{s^\Delta(t)} \frac{\partial L}{\partial y_k} - \mu(t) \frac{\partial L}{\partial t} \right),
\]

for \(k = 1, 2, \ldots, n\). Then \(E^*_k(L) = 0\) are the second Euler–Lagrange equations for problem \[8\]. Therefore, expression \[15\] provides “dependencies” between two types of the Euler–Lagrange expressions.

Note that if \(T = \mathbb{R}\), Noether’s identity \[5\] simplifies because

\[
\frac{\partial L}{\partial t} - \frac{\Delta}{\Delta t} \left( L - \sum_{k=1}^{n} \frac{y^\Delta(t)}{s^\Delta(t)} \frac{\partial L}{\partial y_k} - \mu(t) \frac{\partial L}{\partial t} \right) = \frac{\partial L}{\partial t} - \frac{d}{dt} \left( L - \sum_{k=1}^{n} \frac{y_k \frac{\partial L}{\partial y_k}}{s} \right) = - \sum_{k=1}^{n} \frac{y_k E_k(L)}{s}
\]

and we obtain the following corollary.
In what follows, there exists at least one admissible function $u$.

As noticed in [16], for the variational problem (9) to be well posed, we have to assume that there is a functional $L$ defined by

$$L[y] = \int_a^b L(t, y(t), y(t)) \, dt$$

is invariant under transformations (4) (where $\sigma$ denotes in this context the identity function and $\Delta$ denotes the usual derivative), then there exist the following identities

$$\sum_{k=1}^n \sum_{i=0}^m (-1)^i \left[ (g_{ij}^k E_k(L))^{(i)} - (f_{ij} \cdot \dot{y}_k E_k(L))^{(i)} \right] \equiv 0, \quad j = 1, 2, \ldots, r.$$

In the case $T = h\mathbb{Z}$ (for some $h > 0$) we obtain from Theorem 22 the second Noether theorem for the $h$-calculus; whereas if $T = q^{\mathbb{Z}_0}$ (for some $q > 1$) we get the second Noether theorem for the $q$-calculus.

### 3.2 Noether’s second theorem - multiple delta integral case

In this subsection we extend the second Noether theorem (without transformation of time) to multiple integral variational problems in the time scale setting. For simplicity of presentation we prove the result for the case of two independent variables and transformations that depend on an arbitrary function and its first-order partial delta derivatives. Clearly, our result can be generalized for $n$ independent variables and $r$ arbitrary functions and their higher-order partial delta derivatives.

For the convenience of the reader we recall notions and results that are needed in the sequel. A general introduction to differential calculus and integration theory for multi-variable functions on time scales is presented, respectively, in [13] (see also [46]) and [14]. For the double integral calculus of variations on time scales we refer the reader to [16].

Let $T_1$ and $T_2$ be two given time scales. For $i = 1, 2$, denote by $\sigma_i$ and $\Delta_i$ the forward jump operator and the delta derivative on $T_i$, respectively. Let $C^{(1)}_{rd}$ denote the set of all continuous functions defined on $T_1 \times T_2$ for which both the $\Delta_1$-partial derivative and the $\Delta_2$-partial derivative exist and are of class $C_{rd}$ (for a definition see [16]).

Let $\Omega \subseteq T_1 \times T_2$ be an $\omega$-type set and let $\Gamma$ be its positively fence (see [16]). Denote

$$\Omega^\partial := \{(x, y) \in \Omega : (\sigma_1(x), \sigma_2(y)) \in \Omega\}.$$

Let a function $L(x, y, u, p, q)$, where $(x, y) \in \Omega \cup \Gamma$ and $(u, p, q) \in \mathbb{R}^{3n}$ be given. We will suppose that $L$ is continuous, together with its partial delta derivatives of first and second order with respect to $x, y$ and partial usual derivatives of the first and second order with respect to $u, p, q$.

In what follows $u^{\Delta_1}$ and $u^{\Delta_2}$ denote, respectively, $\frac{\partial u}{\partial x^{\Delta_1}}$ and $\frac{\partial u}{\partial y^{\Delta_2}}$.

Consider the following optimization problem:

$$\mathcal{L}[u] = \int_\Omega L(x, y, u(\sigma_1(x), \sigma_2(y)), u^{\Delta_1}(x, \sigma_2(y)), u^{\Delta_2}(\sigma_1(x), y)) \Delta_1 x \Delta_2 y \rightarrow \text{extremize} \quad (9)$$

where the set of admissible functions are

$$\mathcal{D} = \{u \mid u : \Omega \cup \Gamma \rightarrow \mathbb{R}^n, u \in C^{(1)}_{rd}, u = g \text{ on } \Gamma\}$$

where $g$ is a fixed function defined and continuous on the fence $\Gamma$ of $\Omega$.

As noticed in [16], for the variational problem (9) to be well posed, we have to assume that there exists at least one admissible function $u_0 \in \mathcal{D}$ because it is possible to choose a continuous function $g$ such that no function $u$ is admissible. Note that if there exists an admissible function $u_0$, then the set $\mathcal{D}$ contains a set of functions of the form $u = u_0 + \eta$, where $\eta : \Omega \cup \Gamma \rightarrow \mathbb{R}^n$ is $C^{(1)}_{rd}$ and $\eta = 0$ on $\Gamma$. Any such $\eta$ is called an admissible variation for problem (9).
Definition 25 We say that \( u \in D \) is a local minimizer (resp. local maximizer) for problem \([4]\) if there exists \( \delta > 0 \) such that
\[
\mathcal{L}[u_\ast] \leq \mathcal{L}[u] \quad (\text{resp. } \mathcal{L}[u_\ast] \geq \mathcal{L}[u])
\]
for all \( u \in D \) with
\[
\| u - u_\ast \| := \sup_{(x,y) \in \Omega \cup \Gamma} | u(x,y) - u_\ast(x,y) | + \sup_{(x,y) \in \Omega} | u_\ast^1(x,y) - u^1(x,y) | + \sup_{(x,y) \in \Omega} | u_\ast^2(x,y) - u^2(x,y) | < \delta,
\]
where \( | \cdot | \) denotes a norm in \( \mathbb{R}^n \).

We recall the following results which will play an important role in the proofs of our results.

Theorem 26 (Green's Theorem, [15]) If the functions \( M \) and \( N \) are continuous and have continuous partial delta derivatives \( \frac{\partial M}{\Delta_1 x} \) and \( \frac{\partial N}{\Delta_2 y} \) on \( \Omega \cup \Gamma \), then
\[
\int \int_{\Omega} \left( \frac{\partial N}{\Delta_1 x} - \frac{\partial M}{\Delta_2 y} \right) \Delta_1 x \Delta_2 y = \int_{\Gamma} Mx \, dx + Nx \, dy,
\]
where the "star line integrals" on the right side in [16] denote the sum of line delta integrals taken over the line segment constituents of \( \Gamma \) directed to the right or upwards and line nabla integrals taken over the line segment constituents of \( \Gamma \) directed to the left or downwards.

Lemma 27 (Fundamental lemma of the double variational calculus, [16]) If \( M \) is continuous on \( \Omega \cup \Gamma \) with
\[
\int \int_{\Omega} M(x,y) \eta(x,y) \Delta_1 x \Delta_2 y = 0
\]
for any admissible variation \( \eta \), then
\[
M(x,y) = 0 \text{ for all } (x,y) \in \Omega^o.
\]

Theorem 28 (Euler–Lagrange equation of the double variational calculus, [16]) Suppose that an admissible function \( u_\ast \) provides a local minimum for \( \mathcal{L} \) and that \( u_\ast \) has continuous partial delta derivatives of the second order. Then \( u_\ast \) satisfies the Euler–Lagrange equation
\[
\frac{\partial L}{\partial u}(\cdot) - \frac{\partial L}{\Delta_1 x} \frac{\partial}{\partial p}(\cdot) - \frac{\partial L}{\Delta_2 y} \frac{\partial}{\partial q}(\cdot) = 0
\]
where \( (\cdot) = (x,y,u(\sigma_1(x),\sigma_2(y)),u^1(\sigma_1(x),\sigma_2(y)),u^2(\sigma_1(x),\sigma_2(y))) \) for \( (x,y) \in \Omega^o \).

Let us denote by \( \rho_1 \) and \( \rho_2 \) the backward jump operator of \( T_1 \) and \( T_2 \), respectively. In what follows we will suppose that \( T_1 \) and \( T_2 \) are such
\[
\sigma_1(\rho_1(x)) = x, \quad \forall x \in (T_1)_k
\]
and
\[
\sigma_2(\rho_2(y)) = y, \quad \forall y \in (T_2)_k,
\]
where \( T_k := T \setminus \{m\} \) if \( T \) has a right-scattered minimum \( m \); otherwise, \( T_k = T \). We recall the fact that \( \mathbb{R}, h\mathbb{Z} \) (for some \( h > 0 \)), \( q^{\mathbb{N}_0} \) (for some \( q > 1 \)) and many other interesting time scales satisfy property [11].

Let \( u(x,y) = (u_1(x,y),u_2(x,y),\ldots,u_n(x,y)) \) and consider the following transformations that depend on an arbitrary continuous function \( p \) and the partial delta derivatives of \( p \):
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\[
\begin{align*}
\mathbf{x} & = x \\
\mathbf{y} & = y \\
\mathbf{u}_k(x, y) & = u_k(x, y) + T_k(p)(x, y)
\end{align*}
\]  

(12)

where, for each \( k = 1, 2, \ldots, n \),

\[
T_k(p)(x, y) := a_0(x, y)p(x, y) + a_1(x, y)\frac{\partial}{\Delta_1 x}p(\rho_1(x), y) + a_2(x, y)\frac{\partial}{\Delta_2 y}p(x, \rho_2(y)),
\]

\( a_0, a_1, a_2 \) are \( C^1 \) functions and we assume that \( p \) has continuous partial delta derivatives of the first and second order.

**Definition 29** Functional \( L \) is invariant under transformations (12) if, and only if, for all \( u \in \mathcal{D} \) we have

\[
\int \int_{\Omega} L(x, y, u(\sigma_1(x), \sigma_2(y)), u^{\Delta_1}(x, \sigma_2(y)), u^{\Delta_2}(\sigma_1(x), y))\Delta_1 x \Delta_2 y = \int \int_{\Omega} L(x, y, \mathbf{u}(\sigma_1(x), \sigma_2(y)), \mathbf{u}^{\Delta_1}(x, \sigma_2(y)), \mathbf{u}^{\Delta_2}(\sigma_1(x), y))\Delta_1 x \Delta_2 y.
\]

In what follows we use the notations

\[
T_k(p^\sigma)(x, y) := T_k(\sigma_1(x), \sigma_2(y)), \quad T_k(p^{\sigma_1})(x, y) := T_k(\sigma_1(x), y), \quad T_k(p^{\sigma_2})(x, y) := T_k(x, \sigma_2(y)).
\]

Using similar arguments as the ones used in the proof of Theorem 15 we can prove the following result.

**Theorem 30 (Necessary condition of invariance)** If functional \( L \) is invariant under transformations (12), then

\[
\sum_{k=1}^n \int \int_{\Omega} \left( \frac{\partial L}{\partial u_k^{\sigma_1}} \cdot T_k(p^\sigma) + \frac{\partial L}{\partial u_k^{\Delta_1}} \Delta_1 x T_k(p^{\sigma_1}) + \frac{\partial L}{\partial u_k^{\Delta_2}} \frac{\partial}{\Delta_2 y} T_k(p^{\sigma_1}) \right) \Delta_1 x \Delta_2 y = 0. 
\]

(13)

Define

\[
\hat{E}_k(L) := \frac{\partial L}{\partial u_k^{\sigma_1}} - \frac{\partial}{\Delta_1 x} \frac{\partial L}{\partial u_k^{\Delta_1}} - \frac{\partial}{\Delta_2 y} \frac{\partial L}{\partial u_k^{\Delta_2}}, \quad k = 1, 2, \ldots, n.
\]

We call \( \hat{E}_k(L), \) \( k = 1, 2, \ldots, n, \) the Euler–Lagrange expressions associated to the Lagrangian \( L \) relative to problem (9).

The following lemmas will be used in the proof of Theorem 34.

**Lemma 31** If \( L \) is invariant under transformations (12), then

\[
\sum_{k=1}^n \int \int_{\Omega} \hat{E}_k(L) \cdot T_k(p^\sigma) \Delta_1 x \Delta_2 y = 0.
\]

**Proof.** Fix \( i \in \{1, 2, \ldots, n\} \). Observe that

\[
\int \int_{\Omega} \left( \frac{\partial L}{\partial u_i^{\sigma_1}} \frac{\partial}{\Delta_1 x} T_i(p^{\sigma_2}) + \frac{\partial L}{\partial u_i^{\Delta_2}} \frac{\partial}{\Delta_2 y} T_i(p^{\sigma_1}) \right) \Delta_1 x \Delta_2 y
\]
By Theorem 30 we obtain
\[
\int \int \Omega \left[ \frac{\partial}{\partial x} \left( \frac{\partial L}{\partial u_i} \cdot T^i(p^{x_2}) \right) + \frac{\partial}{\partial y} \left( \frac{\partial L}{\partial u_i} \cdot T^i(p^{y_2}) \right) \right] \Delta_1 x \Delta_2 y
\]
\[
- \int \int \Omega \left[ \frac{\partial}{\partial x} \frac{\partial L}{\partial u_i} \cdot T^i(p^{x_2}) + \frac{\partial}{\partial y} \frac{\partial L}{\partial u_i} \cdot T^i(p^{y_2}) \right] \Delta_1 x \Delta_2 y.
\]
Using Green's Theorem we get,
\[
\int \int \Omega \left[ \frac{\partial}{\partial x} \left( \frac{\partial L}{\partial u_i} \cdot T^i(p^{x_2}) \right) + \frac{\partial}{\partial y} \left( \frac{\partial L}{\partial u_i} \cdot T^i(p^{y_2}) \right) \right] \Delta_1 x \Delta_2 y
\]
\[
= \int \int \Gamma \frac{\partial L}{\partial u_i} \cdot T^i(p^{x_2}) d^x y - \frac{\partial L}{\partial u_i} \cdot T^i(p^{y_2}) d^y x.
\]
Since \( p \) is arbitrary we can choose \( p \) such that
\[
p(x, \sigma_2(y))|_{\Gamma} = 0, \quad p(\sigma_1(x), y)|_{\Gamma} = 0,
\]
\[
\frac{\partial}{\partial x} p(\rho_1(x), \sigma_2(y))|_{\Gamma} = 0, \quad \frac{\partial}{\partial y} p(x, y)|_{\Gamma} = 0,
\]
and therefore
\[
\int \int \Omega \left[ \frac{\partial}{\partial x} \left( \frac{\partial L}{\partial u_i} \cdot T^i(p^{x_2}) \right) + \frac{\partial}{\partial y} \left( \frac{\partial L}{\partial u_i} \cdot T^i(p^{y_2}) \right) \right] \Delta_1 x \Delta_2 y = 0.
\]
By Theorem 30 we obtain
\[
\sum_{k=1}^n \int \int \Omega \left( \frac{\partial L}{\partial u_k} \cdot T^k(p^{x_2}) - \frac{\partial L}{\partial u_k} \cdot T^k(p^{y_2}) \right) \Delta_1 x \Delta_2 y = 0
\]
which proves that \( \sum_{k=1}^n \int \int \Omega \tilde{E}_k(L) \cdot T^k(p^{x_2}) \Delta_1 x \Delta_2 y = 0. \]

**Lemma 32** For each \( k = 1, 2, \ldots, n, \)
\[
\int \int \Omega q \cdot T^k(p^{x_2}) \Delta_1 x \Delta_2 y = \int \int \Omega \left( q a^k_0 - \frac{\partial}{\partial x} (q a^k_1) - \frac{\partial}{\partial y} (q a^k_2) \right) \cdot p^{x_2} \Delta_1 x \Delta_2 y
\]
holds.

**Proof.** Note that
\[
\int \int \Omega q \cdot T^k(p^{x_2}) \Delta_1 x \Delta_2 y = \int \int \Omega \left[ q a^k_0 (x, y) p^{x_2}(x, y) + q a^k_1 (x, y) \frac{\partial}{\partial x} p(x, \sigma_2(y)) \right.
\]
\[
+ \left. q a^k_2 (x, y) \frac{\partial}{\partial y} p(\sigma_1(x), y) \right] \Delta_1 x \Delta_2 y
\]
and
\[
\int \int \Omega \left[ q a^k_1 (x, y) \frac{\partial}{\partial x} p(x, \sigma_2(y)) + q a^k_2 (x, y) \frac{\partial}{\partial y} p(\sigma_1(x), y) \right] \Delta_1 x \Delta_2 y
\]
\[
= \int \int \Omega \left[ \frac{\partial}{\partial x} \left( q a^k_1 (x, y) p(x, \sigma_2(y)) \right) + \frac{\partial}{\partial y} \left( q a^k_2 (x, y) p(\sigma_1(x), y) \right) \right] \Delta_1 x \Delta_2 y
\]
\[
- \int \int \Omega \left[ \frac{\partial}{\partial x} \left( q a^k_1 (x, y) \cdot p(\sigma_1(x), \sigma_2(y)) \right) + \frac{\partial}{\partial y} \left( q a^k_2 (x, y) \cdot p(\sigma_1(x), \sigma_2(y)) \right) \right] \Delta_1 x \Delta_2 y.
\]
Using Green’s Theorem we can conclude that
\[
\int \int_{\Omega} \left[ \frac{\partial}{\Delta_1 x} (qa^k_1(x,y)p(x,\sigma_2(y))) + \frac{\partial}{\Delta_2 y} (qa^k_2(x,y)p(\sigma_1(x),y)) \right] \Delta_1 x \Delta_2 y = 0.
\]
Hence
\[
\int \int_{\Omega} q \cdot T^k(p^\sigma) \Delta_1 x \Delta_2 y = \int \int_{\Omega} \left[ \frac{\partial}{\Delta_1 x} (qa^k_1) \cdot p^\sigma - \frac{\partial}{\Delta_2 y} (qa^k_2) \cdot p^\sigma \right] \Delta_1 x \Delta_2 y
\]
proving the desired result.

**Remark 33** Lemma [32] shows that we can define an adjoint operator of \(T^k\), \(\tilde{T}^k\), by
\[
\tilde{T}^k(q) = qa^k_0 - \frac{\partial}{\Delta_1 x} (qa^k_1) - \frac{\partial}{\Delta_2 y} (qa^k_2).
\]
We are now ready to state and prove the Noether second theorem without transformation of time for multiple integral problems on time scales.

**Theorem 34 (Noether’s second theorem without transforming time)** If functional \(L\) is invariant under transformations [12], then,
\[
\sum_{k=1}^{n} \tilde{T}^k(\hat{E}_k(L)) \equiv 0 \quad \text{on} \quad \Omega^o
\]
where \(\hat{E}_k(L)\) are the \(n\) Euler–Lagrange expressions and \(\tilde{T}^k\) is the adjoint operator of \(T^k\).

**Proof.** Using Lemma [31] and Lemma [32] we conclude that if \(L\) is invariant under transformations [12], then
\[
\sum_{k=1}^{n} \int \int_{\Omega} \hat{E}_k(L) \cdot T^k(p^\sigma) \Delta_1 x \Delta_2 y = \sum_{k=1}^{n} \int \int_{\Omega} \tilde{T}^k(\hat{E}_k(L)) \cdot p^\sigma \Delta_1 x \Delta_2 y = 0,
\]
where \(\tilde{T}^k\) is the adjoint operator of \(T^k\). Applying the fundamental lemma of the double variational calculus (Lemma [27]) we get
\[
\sum_{k=1}^{n} \tilde{T}^k(\hat{E}_k(L)) \equiv 0 \quad \text{on} \quad \Omega^o
\]
proving the desired result. ■

**Corollary 35 (Classical Noether’s second theorem for double integrals problems, cf. [44])** Let \(\Omega \subseteq \mathbb{R}^2\) be an \(\omega\)-type set and let \(\Gamma\) be its positive fence. Let \(L(x,y,u,p,q)\) be a function of class \(C^2\), \((x,y) \in \Omega \cup \Gamma\), \(u = (u_1,u_2,\ldots,u_n)\). If functional \(L\) defined by
\[
L[y] = \int \int_{\Omega} L(x,y,u(x,y),\frac{\partial u}{\partial x}(x,y),\frac{\partial u}{\partial y}(x,y)) \, dx \, dy
\]
is invariant under transformations [12] (where \(\rho_1\) and \(\rho_2\) denote in this context the identity function, and \(\Delta_1\) and \(\Delta_2\) denote the usual derivative), then
\[
\sum_{k=1}^{n} \tilde{T}^k(\hat{E}_k(L)) \equiv 0 \quad \text{on} \quad \Omega
\]
where
\[
\hat{E}_k(L) := \frac{\partial L}{\partial u_k} - \frac{\partial}{\partial x} \frac{\partial L}{\partial p_k} - \frac{\partial}{\partial y} \frac{\partial L}{\partial q_k}, \quad k = 1, 2, \ldots, n
\]
and \(\tilde{T}^k\) is the adjoint operator of \(T^k\).
Similarly to the single delta integral case choosing $T = h\mathbb{Z}$ (for some $h > 0$) we obtain from Theorem 34 the second Noether theorem for the double variational $h$-calculus; whereas choosing $T = q^\mathbb{N}_0$ (for some $q > 1$) we obtain the second Noether theorem for the double variational $q$-calculus.

4 Example

In order to illustrate the second Noether Theorem for the multiple integral case we will present the following example. Let $T_0, T_1, T_2$ and $T_3$ be time scales and let $\Omega \subseteq T_0 \times T_1 \times T_2 \times T_3$ be an $\omega$-type set. For $i = 0, 1, 2, 3$, denote by $\sigma_i$, $\rho_i$ and $\Delta_i$ the forward jump operator, the backward jump operator and the delta derivative on $T_i$, respectively.

Let $t := (t_0, t_1, t_2, t_3) \in \Omega$ and consider the following real functions defined on $\Omega$: $A_0, A_1, A_2, A_3$. Let $A := (A_1, A_2, A_3)$ and denote

$$
\nabla A_0(t) := \left( \frac{\partial A_0}{\Delta_1 t_1}(\sigma_0(t_0), t_1, \sigma_2(t_2), \sigma_3(t_3)), \frac{\partial A_0}{\Delta_2 t_2}(\sigma_0(t_0), \sigma_1(t_1), t_2, \sigma_3(t_3)), \frac{\partial A_0}{\Delta_3 t_3}(\sigma_0(t_0), \sigma_1(t_1), \sigma_2(t_2), t_3) \right)
$$

and

$$
\frac{\partial A}{\Delta_0 t_0}(t) := \left( \frac{\partial A_1}{\Delta_0 t_0}(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3)), \frac{\partial A_2}{\Delta_0 t_0}(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3)), \frac{\partial A_3}{\Delta_0 t_0}(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3)) \right)
$$

and

$$
curl A(t) := \left( \frac{\partial A_3}{\Delta_2 t_2}(\sigma_0(t_0), \sigma_1(t_1), t_2, \sigma_3(t_3)) - \frac{\partial A_2}{\Delta_3 t_3}(\sigma_0(t_0), \sigma_1(t_1), \sigma_2(t_2), t_3), \frac{\partial A_1}{\Delta_3 t_3}(\sigma_0(t_0), \sigma_1(t_1), \sigma_2(t_2), t_3) - \frac{\partial A_3}{\Delta_1 t_1}(\sigma_0(t_0), \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3)), \frac{\partial A_2}{\Delta_1 t_1}(\sigma_0(t_0), \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3)) - \frac{\partial A_1}{\Delta_2 t_2}(\sigma_0(t_0), \sigma_1(t_1), t_2, \sigma_3(t_3)) \right).
$$

We will consider the following Lagrangian function

$$
L = \frac{1}{2} \left\| \nabla A_0 - \frac{\partial A}{\Delta_0 t_0} \right\|^2 - \frac{1}{2} \left\| curl A \right\|^2
$$

that is the time scale version of the Lagrangian density for the electromagnetic field (see, for example, [30]).

It can be proved that the functional

$$
\mathcal{L} = \int \cdots \int_\Omega L \Delta_0 \Delta_1 \Delta_2 \Delta_3
$$

is invariant under the gauge transformations

$$
\overline{A}_k = A_k + \frac{\partial}{\Delta_k t_k} \rho_k, \quad k = 0, 1, 2, 3
$$

where $p : \Omega \to R$ is an arbitrary continuous function that has continuous partial delta derivatives of the first and second order (hence, we have equality of mixed partial delta derivatives, see [13]).
The second Noether theorem on time scales

Since, for each \( k = 0, 1, 2, 3 \),

\[ T^k(p) = \frac{\partial}{\Delta_k t_k} p^\rho_k \]

then, by Lemma 32, we conclude that

\[ \tilde{T}^k(q) = -\frac{\partial}{\Delta_k t_k} q. \]

Hence, from the second Noether theorem (Theorem 34), we get

\[ \sum_{k=0}^{3} \frac{\partial}{\Delta_k t_k} \tilde{E}_k(L) = 0 \quad \text{on} \quad \Omega^o, \]

where \( \tilde{E}_k(L) \), \( k = 0, 1, 2, 3 \), are the Euler–Lagrange expressions associated to functional \( \mathcal{L} \).

If we suppose that, for each \( k = 0, 1, 2, 3 \), \( A_k \) has continuous partial delta derivatives of the first and second order and that \( A_0 \) and the vector field \( \mathbf{A} \) satisfy the so called Lorentz conditions on time scales:

\[ \text{div} \mathbf{A} \bigg|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3))} = \frac{\partial A_0}{\Delta_0 t_0} \big|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3))} \]

\[ \text{div} \mathbf{A} \bigg|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3))} = \frac{\partial A_0}{\Delta_0 t_0} \big|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3))} \]

\[ \text{div} \mathbf{A} \bigg|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3))} = \frac{\partial A_0}{\Delta_0 t_0} \big|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3))} \]

\[ \text{div} \mathbf{A} \bigg|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), t_3)} = \frac{\partial A_0}{\Delta_0 t_0} \big|_{(t_0, \sigma_1(t_1), \sigma_2(t_2), t_3)} \]

where \( \text{div} \mathbf{A} \) denotes the divergence of a vector field \( \mathbf{A} \), that is,

\[ \text{div} \mathbf{A} := \frac{\partial A_1}{\Delta_1 t_1} + \frac{\partial A_2}{\Delta_2 t_2} + \frac{\partial A_3}{\Delta_3 t_3}, \]

then the Euler–Lagrange expressions can be written in the following way:

\[ \tilde{E}_k(L) = \frac{\partial^2 A_k}{\Delta_0 t_0^2} (t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3)) - \nabla^2 A_k(t_0, t_1, t_2, t_3), \quad k = 0, 1, 2, 3 \]

where

\[ \nabla^2 A_k(t) := \frac{\partial^2 A_k}{\Delta_1 t_1^2} (t_0, t_1, \sigma_2(t_2), \sigma_3(t_3)) + \frac{\partial^2 A_k}{\Delta_2 t_2^2} (t_0, \sigma_1(t_1), t_2, \sigma_3(t_3)) \]

\[ + \frac{\partial^2 A_k}{\Delta_3 t_3^2} (t_0, \sigma_1(t_1), \sigma_2(t_2), t_3). \]

Hence, under these assumptions, we can conclude that

\[ \sum_{k=0}^{3} \frac{\partial}{\Delta_k t_k} \left( \frac{\partial^2 A_k}{\Delta_0 t_0^2} (t_0, \sigma_1(t_1), \sigma_2(t_2), \sigma_3(t_3)) - \nabla^2 A_k(t_0, t_1, t_2, t_3) \right) = 0 \quad \text{on} \quad \Omega^o. \]
5 Concluding remarks

We proved that the important Noether’s second theorem is valid not only for the continuous and discrete calculus, but also for the quantum calculus. Moreover, in our opinion, the proofs presented in this paper are elegant and clear to follow.

The question of obtaining Noether’s second theorem for multiple integrals with transformation of time in the time scale setting remains an interesting open question. To the best authors’ knowledge, to extend the second Noether theorem to multiple integrals with transformation of time, substitution in the multiple integral is a fundamental tool and this result is not yet available in the literature.

For other generalizations of the second Noether theorem we refer the reader to [32] (in the context of the fractional calculus of variations) and [48] (in the context of the optimal control).

Acknowledgements

Work supported by FEDER funds through COMPETE–Operational Programme Factors of Competitiveness (“Programa Operacional Factores de Competitividade”) and by Portuguese funds through the Center for Research and Development in Mathematics and Applications (University of Aveiro) and the Portuguese Foundation for Science and Technology (“FCT–Fundaçao para a Ciência e a Tecnologia”), within project PEst-C/MAT/UI4106/2011 with COMPETE number FCOMP-01-0124-FEDER-022690. A. B. Malinowska was also supported by Bialystok University of Technology grant S/WI/02/2011.

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