Structural bioinformatics

**BIPSPI: a method for the prediction of partner-specific protein–protein interfaces**

Ruben Sanchez-Garcia*, C. O. S. Sorzano, J. M. Carazo and Joan Segura*

GN7 of the Spanish National Institute for Bioinformatics (INB), Biocomputing Unit, National Center of Biotechnology (CSIC), Instruct Image Processing Center, Madrid 28049, Spain

*To whom correspondence should be addressed.

Associate Editor: Alfonso Valencia

Received on January 15, 2018; revised on June 13, 2018; editorial decision on July 14, 2018; accepted on July 17, 2018

**Abstract**

**Motivation:** Protein–Protein Interactions (PPI) are essentials for most cellular processes and thus, unveiling how proteins interact is a crucial question that can be better understood by identifying which residues are responsible for the interaction. Computational approaches are orders of magnitude cheaper and faster than experimental ones, leading to proliferation of multiple methods aimed to predict which residues belong to the interface of an interaction.

**Results:** We present BIPSPI, a new machine learning-based method for the prediction of partner-specific PPI sites. Contrary to most binding site prediction methods, the proposed approach takes into account a pair of interacting proteins rather than a single one in order to predict partner-specific binding sites. BIPSPI has been trained employing sequence-based and structural features from both protein partners of each complex compiled in the Protein–Protein Docking Benchmark version 5.0 and in an additional set independently compiled. Also, a version trained only on sequences has been developed. The performance of our approach has been assessed by a leave-one-out cross-validation over different benchmarks, outperforming state-of-the-art methods.

**Availability and implementation:** BIPSPI web server is freely available at http://bipspi.cnb.csic.es. BIPSPI code is available at https://github.com/bioinsilico/BIPSPI. Docker image is available at https://hub.docker.com/r/bioinsilico/bipspi/.

**Contact:** rsanchez@cnb.csic.es or jsegura@cnb.csic.es

**Supplementary information:** Supplementary data are available at Bioinformatics online.

1 **Introduction**

Protein–Protein Interactions (PPIs) are at the basis of virtually every cellular process. Therefore, elucidating the biochemical underpinnings of interactions is a fundamental step for improving our understanding of cellular mechanisms and diseases. Much research has been done on PPIs, especially at cellular level, which has led to the availability of many interactomes (Cafarelli et al., 2017). However, in order to grasp protein function in cellular processes, not only it is important to know which proteins interact but how proteins bind to their different partners and thus, identifying protein–protein interfaces becomes a central issue.

Many experimental methodologies exist for the characterization of protein–protein interfaces, including mass spectrometry (Sobott and Robinson, 2002), mutagenesis (Chen et al., 2014), X-ray crystallography (Shi, 2014) or nuclear magnetic resonance (O’Connell et al., 2009). Nevertheless, in many cases, these approaches require expensive and time-consuming experiments and are not suitable for the analysis of large datasets. As a result, many computational approaches have been designed to predict and characterize PPIs at different levels. For example, several protein–protein docking approaches (Rodrigues et al., 2015; Zhang et al., 2016) have been developed to obtain atomic models for the interaction of two proteins when solved structures of both partners are available. For those other cases in which there is no structural information, or it only exists at low resolution, other methods to identify which pairs of domains are likely to bind in PPIs have been proposed (Segura et al., 2015b; Segura et al., 2016; Wang et al., 2007).
Nonetheless, most approaches work at residue level predicting which protein residues constitute binding sites or interfaces of a protein complex. Generally, these algorithms employ knowledge derived from structurally solved protein in order to build templates or statistical models (Xue et al., 2015).

Different knowledge-based methods can be found in the scientific literature. Some of them use homology information, inferring protein interfaces from templates of homologous complexes (Mosca et al., 2013; Segura et al., 2016; Xue et al., 2011). Other approaches employ correlated mutations in order to identify pairs of residues that are likely to interact (Jones et al., 2012; Morcos et al., 2014; Pazos et al., 1997). On the other hand, most proposed data-driven methods make use of machine learning algorithms that are trained on heterogeneous sets of structurally solved complexes (Ahmad and Mizuguchi, 2011; de Vries et al., 2006; Fout et al., 2017; Hwang et al., 2016; Meyer et al., 2018; Minhas et al., 2014; Murakami and Mizuguchi, 2010; Neuvirth et al., 2004; Porollo and Meller, 2006; Savojardo et al., 2017; Segura et al., 2011, 2012). The different strategies have different relative merits, depending on the context. For example, template-based approaches might offer accurate predictions when homologue complexes are available (Xue et al., 2015). Similarly, correlated mutations have been shown to provide very useful information when high quality multiple sequence alignments can be compiled (Ovchinnikov et al., 2014). On the other hand, machine-learning solutions are not limited by the need of high quality templates or alignments, so that they can be used in more general contexts. Finally, docking algorithms, which are able to achieve atomic resolution in their prediction but are also computationally demanding, can benefit from data-driven predictions in order to get faster and more accurate solutions (Rodrigues et al., 2015; Segura et al., 2015a).

Several formulations can be found to the problem of predicting protein complex interfaces or binding sites (Ahmad and Mizuguchi, 2011). On the one hand, partner-independent binding site predictions aim to identify all residues of a given protein that interact with any protein. On the other hand, partner-specific binding site predictions (from now on ‘interface predictions’) pursue to identify which residues are involved in a particular PPI. Partner-specificity is a desirable attribute for interface predictors as most proteins interact with several partners (Grigoriev, 2003) and the interfaces for each partner can be totally different. This is especially true for transient partners with several partners (Grigoriev, 2003) and the interfaces for each partner can be totally different. This is especially true for transient (Jones et al., 2012; Morcos et al., 2014; Pazos et al., 1997). On the other hand, most proposed data-driven methods make use of machine learning algorithms that are trained on heterogeneous sets of structurally solved complexes (Ahmad and Mizuguchi, 2011; de Vries et al., 2006; Fout et al., 2017; Hwang et al., 2016; Meyer et al., 2018; Minhas et al., 2014; Murakami and Mizuguchi, 2010; Neuvirth et al., 2004; Porollo and Meller, 2006; Savojardo et al., 2017; Segura et al., 2011, 2012). The different strategies have different relative merits, depending on the context. For example, template-based approaches might offer accurate predictions when homologue complexes are available (Xue et al., 2015). Similarly, correlated mutations have been shown to provide very useful information when high quality multiple sequence alignments can be compiled (Ovchinnikov et al., 2014). On the other hand, machine-learning solutions are not limited by the need of high quality templates or alignments, so that they can be used in more general contexts. Finally, docking algorithms, which are able to achieve atomic resolution in their prediction but are also computationally demanding, can benefit from data-driven predictions in order to get faster and more accurate solutions (Rodrigues et al., 2015; Segura et al., 2015a).

Several formulations can be found to the problem of predicting protein complex interfaces or binding sites (Ahmad and Mizuguchi, 2011). On the one hand, partner-independent binding site predictions aim to identify all residues of a given protein that interact with any protein. On the other hand, partner-specific binding site predictions (from now on ‘interface predictions’) pursue to identify which residues are involved in a particular PPI. Partner-specificity is a desirable attribute for interface predictors as most proteins interact with several partners (Grigoriev, 2003) and the interfaces for each partner can be totally different. This is especially true for transient interactions, which are fundamental for processes such as signal transduction (Xue et al., 2015). It is not surprising that partner-specific methods tend to outperform non-specific approaches (Ahmad and Mizuguchi, 2011; Minhas et al., 2014). However, most current binding site prediction approaches based on machine learning algorithms are designed to achieve non-partner specific predictions. Indeed, to our knowledge, only a few machine-learning based methods computing partner-specific binding sites are currently available. Ahmad et al. proposed PPI-PI, an ensemble of 24 neural networks which used amino acid type and PSSMs (Position Specific Scoring Matrices) through a sliding window as features to predict binding sites on protein sequences (Ahmad and Mizuguchi, 2011). PAIRpred (Minhas et al., 2014), one of the state-of-the-art methods, is a Support Vector Machine that employs a specific pairwise kernel over a set of structural and/or sequence-based features. This latter set of sequence-based features is comprised by PSSMs, PSFs (Position Specific Frequency Matrices) and solvent accessibility predictions, while the structural descriptors include residue depth, solvent accessibility, protrusion index and half sphere amino acid compositions. In general, better performance is achieved when structures of the protein partners are available. Recently, Fout et al. developed a graph convolutional neural network (GCNN) method using the set of features described in PAIRpred (Fout et al., 2017). Finally, the ECLAIR method (Meyer et al., 2018), which was designed to function in high-throughput scenarios, is based on an ensemble of Random Forests, each of them trained on a different set of features including biophysical, structure-base, docking-based and co-evolutionary features.

In this work, we present BIPSPI (xgBoost Interface Prediction of Specific-Partner Interactions), a new machine-learning based method for the partner-specific prediction of residue-residue contact and binding sites. BIPSPI can predict interface residues from either protein sequences or protein structures. To that end, BIPSPI employs multiple structural and/or sequence-based amino acid features that are combined through an Extreme Gradient Boosting (XGBoost) (Chen and Guestrin, 2016) model and a new scoring function that converts residue contact predictions into binding site scores. BIPSPI performance has been evaluated by means of a leave-one-out cross-validation over different datasets (Hwang et al., 2008; Vreven et al., 2015) and against an independent testing set derived from CAPRI targets (Janin et al., 2003). Finally, BIPSPI was compared with similar methods, outperforming previous reported results. A web server where BIPSPI can be employed and results and datasets downloaded is freely available at http://bipsi.cnb.csic.es.

2 Materials and methods

BIPSPI classifier has been trained to predict interfaces from protein structures and/or sequences. This section describes the implementation of the method using structural data. A full description of the sequence-based classifier is available in Supplementary Section S1.

2.1 Datasets

Different sets of protein complexes were used to train and evaluate the performance of BIPSPI predicting protein interfaces. The first one was the Protein–Protein Docking Benchmark version 5 (Vreven et al., 2015) dataset, that contains 230 non-redundant protein complexes for which bound and unbound structures are available. Each of these complexes has resolution better than 3.25 Å and the length of each sequence is >30 amino acids. To avoid redundancy, this dataset was compiled ensuring that none of the protein complexes belonged to the same pair of SCOP families (Andreeva et al., 2008). This set will be referred to as DBv5. The second dataset was the Protein–Protein Docking Benchmark version 3, in this work termed DBv3, (Hwang et al., 2008), which is a subset of DBv5.

In addition to DBv5 and DBv3, we have compiled a new dataset of 117 protein dimers (Dm5) following a similar approach as the one used to compile the different Protein–Protein Docking Benchmark versions. This dataset was built selecting PDB dimers of at least 35 amino acids long, with resolutions better than 3 Å and for which >90% of their residues were structurally determined. Similar to DBv5 and DBv3, non-redundancy between protein complexes was established at SCOP family level in such a way that only dimers with one SCOP domain per partner were considered and none of the dimers shared the same combination of SCOP families (see Supplementary Section S6.12 for a detailed list). Finally, several CAPRI targets (see Supplementary Section S6.12 for a detailed list) were also employed as independent testing data and as a way to provide a direct comparison with other methods (Savojardo et al., 2017).
2.2 Residue–residue contact definition

Different definitions of residue–residue contact can be found in the scientific literature (Xue et al., 2015). Two of the most commonly used are: (i) residue solvent accessibility reduction after complex formation and (ii) distance threshold between residue heavy atoms. In order to compare with other existing methods, we have adopted the same contact definition that was used in PhIP (Ahmad and Mizuguchi, 2011) and PAIRpred (Minhas et al., 2014). Accordingly, a pair of residues is defined as interacting if the distance among any of their heavy atoms is < 6.0 Å.

In our analysis, we found that in DB69 there are 20 799 interacting residue pairs as opposed to 15 333 317 non-interacting residue pairs; thus, an extreme class imbalance. To properly handle this situation during the different training steps of BIPSPI, we only considered random samples of all non-interacting pairs, including non-accessible residues to account for possible conformational changes. Several sampling proportions were tested, achieving the best performance when the number of selected negative cases was three times larger than the number of interacting pairs (data not shown). This random sample, which also makes training faster, is drawn at protein complex level, in such a way that all complexes contribute to the dataset with the same relation of positive and negative cases. Finally, it is important to notice that no sampling is done for evaluation and, hence, it is performed on whole proteins data.

2.3 Data encoding

Residue pairs are codified as a vector of numerical features. In this work, a protein A is defined as a collection of residues \( a_i \) and a pair of residues \( (a_i, \beta_j) \) will identify two amino acids belonging to proteins A and B, respectively. Due to the symmetry of the problem, each pair \( (a_i, \beta_j) \) can also be defined as \( (\beta_j, a_i) \). To tackle this, we have included both representations as different examples in the training set and, when computing scores, we have assigned the average of predictions for \( (a_i, \beta_j) \) and predictions for \( (\beta_j, a_i) \) to both of them. Next sections describe how the vector of features associated to a pair of residues \( (a_i, \beta_j) \) is built.

2.3.1 Single amino acid features

Each single residue is encoded by a set of sequence-based and structural features. Sequence-based features include amino acid type, codified as a vector of 22 binary elements (one-hot encoded), sequence profiles computed with PSI-BLAST (Altschul et al., 1997) or retrieved from 3DCONS-DB (Sanchez-Garcia et al., 2017) when available, and sequence conservation scores computed with AL2CO (Pei and Grishin, 2001). Structural features are also available to describe residues, including geometrical descriptors and hydrophobicity computed with PSAIA (Mihel et al., 2008), one-hot encoded secondary structure determined by DSSP (Kabsch and Sander, 1983) and half-sphere exposure and contact number (Hamelryck, 2005) computed at radius of 12 Å with Biopython (Cock et al., 2009). An exhaustive list of the residue features is available in Supplementary Section S2.

2.3.2 Residue environment features

Residue environments are also described and included into the vector of features in such a way that for each feature its environment feature is calculated. Several residue environment definitions have been employed in different works, two of the most common ones are: (i) sequential environment through sliding window (Sikic et al., 2009) and (ii) structural environment by Euclidean distance threshold (Porollo and Meller, 2006). In these works, three types of environments are used in combination: sequential environment, structural environment and structural pairwise environment.

Sequential environment is obtained by a sliding window approach of length 11 amino acids in which all sequence-based features described above are concatenated for all residues of the window. On the other hand, structural environment features are computed from all sequence-based and structural features of each residue employing a structural neighbourhood definition based on Voronoi Diagrams (Segura et al., 2011). Basically, according to this definition, two residues are considered as neighbours if they share a common edge in the Voronoi Diagram defined by all C-alpha atoms of the protein. The computation of structural environment features is different depending whether the feature is represented by a real number or if it is represented as one-hot encoded. Hence, let \( f_i \) be a real value feature for residue \( a_i \), then, its associated structural environment feature \( e_{fi} \) is defined as a set of four values:

\[
e_{fi} = \left\{ \sum_{r \in N_i} f_r \frac{1}{|N_i|}, \sum_{r \in N_i} f_{\max}, \min f_r \right\}
\]

(1)

Where \( N_i \) is the set of neighbours of residue \( a_i \) according to Voronoi neighbourhood definition.

Similarly, let \( h = (h_1, h_2, \ldots, h_k) \) be any one-hot encoded feature for residue \( a_i \), then, \( k \) is the number of classes of the feature \( h \). Then, its associated structural environment feature of dimension \( k \) is computed as follows:

\[
e_{h_i} = \sum_{r \in N_i} h_r
\]

(2)

Residue pair scores predicted in the first step classifier are also included as new features in the second step (see Section 2.4); those scores can be regarded as pairwise features. Then, given a pair of residues \( (a_i, \beta_j) \) and a pairwise score \( F_{\beta_j} \), the structural pairwise environment score \( e_{F_{\beta_j}} \) is defined as:

\[
e_{F_{\beta_j}} = \{e_{F_{\beta_j}}^1, e_{F_{\beta_j}}^2, e_{F_{\beta_j}}^3\}
\]

(3)

where

\[
e_{F_{\beta_j}}^1 = \left\{ \sum_{r \in N_i} \sum_{r \in N_j} F_{\beta_j} \frac{1}{|N_i|} \sum_{r \in N_i} \sum_{r \in N_j} F_{\beta_j} \max F_{\beta_j} \min F_{\beta_j} \right\}
\]

(4)

\[
e_{F_{\beta_j}}^2 = \left\{ \sum_{r \in N_i} \sum_{r \in N_j} F_{\beta_j} \frac{1}{|N_i|} \sum_{r \in N_i} \sum_{r \in N_j} F_{\beta_j} \max F_{\beta_j} \min F_{\beta_j} \right\}
\]

(5)

\( N_i \) is the set of neighbours of residue \( a_i \) and \( N_j \) is the set of neighbours of residue \( \beta_j \) according to Voronoi neighbourhood definition.

2.4 BIPSPI algorithm

BIPSPI algorithm was designed as a three steps workflow (see Fig. 1). First, a XGBoost classifier (Chen and Guestrin, 2016) is fed with the set of sequence-based and structural features and their respective environments. After that, a second XGBoost classifier is fed with the same input features adding the predictions that were obtained in the first step and their associated environment scores. Finally, a scoring function converts interacting pair predictions into binding site residue scores (see Section 2.5). The training procedure and selected algorithm hyperparameters are described in Supplementary Section S3.
2.5 From residue–residue contact scores to binding site prediction

In order to obtain individual interface residues, we have designed a scoring function to compute single amino acid binding site scores from residue–residue pairs results. This scoring function takes into account all residue pairs scores relying on the rank of the predictions when all pairs are sorted from highest to lowest score. Thus, the binding site score of a given residue is derived from the list of all pair predictions ordered from highest to lowest score using the following expression:

$$I_i(z) = \frac{\sum_{j \leq \log_4(n)} X_c(i, j')}{2}$$  \hspace{1cm} (6)

Where $z$ is the particular residue whose score is computed, $n$ is the number of residue pairs and $X_c(i, j')$ is the number of times that residue $z$ appears among the $2^j$ highest score pairs (see Supplementary Section S4). Additionally, with the aim of making predictions smoother, scores are averaged along the sequence employing a window size of three amino acids and using the vector of weights $\{1/4, 1/2, 1/4\}$.

Finally, in order to provide a manageable score that allows for easy threshold selection, BIPSPI web server computes an expected precision value that is estimated using an isotonic regression model on the original scores (Zadrozny and Elkan, 2002) (see Supplementary Section S4.2 for more details).

2.6 Performance evaluation

The performance of BIPSPI predicting residue–residue contact pairs and binding sites was evaluated computing a leave-one-out cross-validation over the complexes included in the different datasets (see Section 2.1). Specifically, each of the classifiers of the method was trained with the sampled pairs of all protein complexes except for the ones that belong to the left-out complex. This evaluation procedure is the same that was used in PAIRpred and PpIP and, when trained over DBv3, allows for a straight and fair comparison with those methods. In addition, several CAPRI targets interfaces were predicted as an independent benchmark. Residue–residue contact predictions (RRCP) were evaluated with the AUC values of ROC curves averaged over protein complexes (\(AUC_{ROC}\)) and mixing all residue–residue scores from the different complexes (\(AUC_{CROC}\)). Additionally, as these measurements can provide an over-optimistic view of performance due to the imbalance between interacting and non-interacting pairs, the AUC of the precision-recall curve (\(AUC_{PR}\)) is also provided. Single residue binding site predictions were also evaluated in terms of the Matthew Correlation Coefficient (MCC), precision (\(PR\)), recall (\(RC\)), specificity (\(SPC\)) and negative predictive value (\(NPV\)), which were computed at the threshold that maximized the MCC.

3 Results

3.1 BIPSPI feature importance analysis

The importance of the different features employed in BIPSPI has been analyzed by counting the total number of tree splits caused by each variable during model training (Friedman and Meulman, 2003). In order to obtain easily interpretable results, we have focused on families of features when those are classified by type (e.g. accessibility, conservation, secondary structure, etc.). Accordingly, the family of features with the highest contribution (sum of importance of all variables in the class), approximately 65%, was conservation. However, individually, the most informative variables belonged to the accessibility family for the first step and previous step prediction scores for the second one, being accessibility the next most important family feature. Additionally, we have studied the importance of the residue environment and observed that structural environment features explained >55% of the total importance despite being <31% of the total features number. An extended discussion of feature importance can be found in Supplementary Section S5.

3.2 BIPSPI performance analysis

The performance of BIPSPI predicting residue–residue contacts and binding sites was evaluated computing a leave-one-out cross-validation on DBv5 and DlmS datasets. As expected, the method achieved the best performance when structural features and two classification steps were computed (see Table 1). Although the improvement in performance predicting residue–residue contacts between the first and second step is small, the improvement in performance predicting single residue binding sites after the second step is not negligible. For example, while BIPSPI \(AUC_{ROC}\) measured in DBv5 are 0.9011 and 0.9052 for the first and second step, respectively, the binding site \(AUC_{ROC}\) increases from 0.8046 in the first step to 0.8235 in the second one (see Table 1). This behaviour can be explained due to the high imbalance of interacting and non-interacting residue pairs, and, as a consequence, small improvements in residue–residue contact predictions can involve important improvements in binding site prediction.

In general, binding site evaluation measurements improved after the second step. For example, when BIPSPI was evaluated in DBv5 the MCC in the second step increased by >0.01 respect the first step. Also, \(AUC_{ROC}, AUC_{CROC}\) and \(AUC_{PR}\) measurements increased after the second step was employed (see Table 1). It is worth noting that the apparent precision drop in the second step that could be inferred from Table 1 values is a consequence of the fact that precision and recall were obtained for those thresholds that maximized the MCC in each step independently and thus, they cannot be compared. In fact, as it can be appreciated in the precision-recall curves included in Supplementary Section S6.2, most precision and recall values improved after the second step was applied. This improvement between the two steps can be explained by the addition of the first step scores and their associated structural pairwise environment scores (see Section 2.3.2). Protein binding sites tend to form continuous surface patches and thus, providing predicted scores of neighbour residues can be useful in order to find residues surrounded by high scored regions.
Furthermore, we analyzed the feature importance for the second step classifier obtaining that the first step scores and its associated environment values were the most important features (see Section 2.3.2 and Section 3.1). In addition to XGBoost algorithm, which has not been widely explored in bioinformatics, we have also analyzed Random Forest (Breiman, 2001) as classifier. Results obtained by XGBoost were superior to Random Forest in all the evaluated metrics (see Supplementary Section S7). Specifically, XGBoost achieved a performance over 1% and binding site MCC over 0.02.

### 3.3 BIPSPI behaves partner-specific

In order to measure the partner-specificity of BIPSPI, we have compiled a dataset where some proteins interact with multiple partners through different binding sites. Then, we have compared the scores of binding site residues for a particular interaction (e.g. protein PA interacting with PC or with PD). For this analysis, equivalent proteins (sequence identity >90%) that interact with different partners were identified from our datasets DBv5 and DImS. As a result, 46 different proteins, involving 123 interactions, in DBv5 (see Supplementary S9.1 for a list of pdb chains). To avoid any effect or artefact due overtraining, we analyzed the scores obtained in the leave-one-out cross-validation computed on DBv5 and DImS (see Section 3.2). Then, for each protein, scores from its specific interface residues were collected for the partner-specific binding site distribution and scores from residues that belong to the interfaces of other interactions were included in the non-specific binding site distribution (see Supplementary Material Section S9.2 for a detailed explanation and a particular example). Finally, both distributions were compared using the Mann–Whitney U test, achieving P-values of 2.6e-13 and 2.5e-14 for DBv5 and DImS, respectively and thus, rejecting the null hypothesis of the test that both distributions are equivalent.

### 3.4 Binding site scoring function improves other approaches

In PPiPP and PAIRpred, the binding site score of a particular residue is computed as the mean or the maximum of the residue pair scores involving this particular residue. Then, for a single residue, the resulting binding site score depends on the score of a unique pair and thus, the predicted score of other possible contacts are ignored. In this work, we have designed a novel scoring function to compute single residue binding site scores considering all predicted score pairs for a particular residue (see Section 2.5). This approach increased the performance when compared with the maximum score value proposed in PAIRpred. Finally, we have also found that averaging the predicted binding site scores through a sliding window (see Section 2.5) increased the final performance.

Table 2 summarizes the performance of different scoring approaches predicting binding sites from residue pair scores. In our benchmark, the best performance was achieved by the newly defined scoring function averaging the resulting scores through a sliding window. At this point, we would like to highlight that our proposed

### Table 1. Performance evaluation for BIPSPI leave-one-out over the DBv5, DBv3 and DImS complexes and comparison with other methods

| Algorithm | Dataset | Input | Residue–residue contact prediction | Binding site prediction |
|-----------|---------|-------|-----------------------------------|-------------------------|
|           |         |       | AUCROC | AUCROC | AUCPR | AUCROC | AUCROC | AUCPR | MCC | PR | RC | SPC | NPV |
| BIPSPI    | DlmS    | Seq   | 0.7469 | 0.7300 | 0.0170 | 0.6883 | 0.6741 | 0.3375 | 0.3779 | 0.3592 | 0.4264 | 0.8219 | 0.8595 |
|           |         | Struc | 0.8800 | 0.8909 | 0.0432 | 0.7940 | 0.7816 | 0.4739 | 0.3679 | 0.4750 | 0.5098 | 0.8680 | 0.8832 |
|           |         | Struc*| 0.8789 | 0.8875 | 0.0439 | 0.7985 | 0.7847 | 0.4772 | 0.3779 | 0.4416 | 0.5983 | 0.8228 | 0.8974 |
| DBv5      | Seq     | 0.8024 | 0.8137 | 0.0110 | 0.7286 | 0.7527 | 0.3041 | 0.2791 | 0.3003 | 0.4828 | 0.8349 | 0.9322 |
|           | Struc   | 0.9011 | 0.9184 | 0.0238 | 0.8046 | 0.8154 | 0.3967 | 0.3721 | 0.4012 | 0.5079 | 0.9037 | 0.9353 |
|           | Struc*  | 0.9052 | 0.9188 | 0.0234 | 0.8235 | 0.8225 | 0.4104 | 0.3855 | 0.3910 | 0.5585 | 0.8895 | 0.9407 |
| DBv3      | Seq     | 0.8153 | 0.8154 | 0.0113 | 0.7371 | 0.7492 | 0.3041 | 0.2830 | 0.3233 | 0.4396 | 0.8828 | 0.9251 |
|           | Struc   | 0.9024 | 0.9186 | 0.0269 | 0.8103 | 0.8136 | 0.4081 | 0.3712 | 0.4223 | 0.4815 | 0.9112 | 0.9287 |
|           | Struc*  | 0.9044 | 0.9131 | 0.0234 | 0.8157 | 0.8163 | 0.4058 | 0.3730 | 0.3831 | 0.5458 | 0.8871 | 0.9383 |
| PAIRpred  | Dv3     | Seq   | 0.809  | NA     | NA     | 0.708  | 0.708  | NA     | NA     | NA     | NA     | NA     |
|           |         | Struc-d| 0.8783 | 0.8930 | 0.0125 | 0.7587 | 0.6913 | 0.2012 | 0.1807 | 0.1680 | 0.7809 | 0.5030 | 0.9470 |
|           |         | Struc-p| 0.8783 | 0.8930 | 0.0125 | 0.7689 | 0.7741 | 0.3412 | 0.3112 | 0.3716 | 0.4197 | 0.8987 | 0.9256 |
| PPiPP     | Dv3     | Seq   | 0.729  | NA     | NA     | 0.661  | 0.661  | NA     | NA     | NA     | NA     | NA     |

**Note:** Seq, Sequence-based features only; Struc*, Structural and sequence-based features one step; Struc, Structural and sequence-based features two steps (default). Struc-d, PAIRpred structural and sequence-based features and maximum as scoring function (default); Struc-p, PAIRpred structural and sequence-based features and proposed scoring function. NA, Not available

### Table 2. Performance evaluation for BIPSPI interface scores estimated by a leave-one-out cross-validation over the complexes compiled in DBv5 using different scoring strategies

| Algorithm | Input | Binding site prediction |
|-----------|-------|-------------------------|
|           |       | AUCPR | MCC | PR | RC | SPC | NPV |
| $I_i(x)$  | Seq   | 0.2968 | 0.2740 | 0.3005 | 0.4679 | 0.8617 | 0.9272 |
|           | Struc | 0.4043 | 0.3826 | 0.3947 | 0.5444 | 0.8940 | 0.9392 |
| $I_i(x)$+ wAVG | Seq | 0.3049 | 0.2791 | 0.3003 | 0.4828 | 0.8349 | 0.9322 |
|           | Struc | 0.4104 | 0.3855 | 0.3910 | 0.5585 | 0.8895 | 0.9407 |
| Maximum   | Seq   | 0.3199 | 0.2977 | 0.2679 | 0.6394 | 0.7780 | 0.9444 |
|           | Struc | 0.3199 | 0.2977 | 0.2679 | 0.6394 | 0.7780 | 0.9444 |

**Note:** $I_i(x)$, Proposed scoring function; $I_i(x)$+ wAVG, Proposed scoring function followed by averaging along sequence (default); Seq, Sequence-based features only; Struct, Structural and sequence-based features two steps (default).
scoring function is not specific for our method but also can be applied to other pair prediction methodologies. Indeed, when applied to PAIRpred scores, it also improves its performance (see Table 1 and Section 3.5).

3.5 Comparison with other methods

We have compared our approach with four other methods (PPiPP, PAIRpred, GCNN and ECLAIR) that also use a machine-learning based approach and have been designed to predict partner-specific binding sites. In order to make comparisons with PAIRpred and PPiPP easier, we have used the same evaluation protocol consisting in a leave-one-out cross-validation over DBv3 complexes. Table 1 shows the performance of PPiPP, PAIRpred and BIPSPI using the metrics described in Section 2.6. The best performance was achieved by BIPSPI when structural data was included in the input data. Moreover, when only sequence-based features were used, BIPSPI also outperformed the other approaches. It is worth to highlight that original PAIRpred binding site predictions considerably improved when our scoring function was applied (see Section 2.5), raising the MCC coefficient by >0.1 points.

Comparison with GCNN was carried out as described in the original publication (Fout et al., 2017). Thus, BIPSPI was retrained on the set of complexes of DBv5 that are contained in Docking Benchmark v4 (DBv4) (Hwang et al., 2010) and tested on the complexes contained in DBv5 but not in DBv4. The median ROC-AUC obtained by BIPSPI on the testing set was 0.942 and thus, >4 points better than the reported in GCNN publication. Similarly, we compared our method with ECLAIR and several other non-partner-specific methods using the BM90C dataset (Meyer et al., 2018). In this case, BIPSPI also achieved the best MCC when compared with the other methods, 0.389. A detailed comparison table is included in Supplementary Section S8.1.

In addition, we have also evaluated BIPSPI performance over a set of CAPRI targets (see Supplementary Section S6.12 for a complete list of proteins and detailed results). In this evaluation, BIPSPI achieved an AUC\_ROC for pair prediction of 0.885 and, for binding site AUC\_ROC and MCC, values of 0.763 and 0.297, respectively. Moreover, we could compare these results with ISPRED4 predictions (Savojardo et al., 2017) as these targets were also used during its testing. It is worth noting that, ISPRED4 is a non-partner-specific predictor and thus, predicting global binding sites is a more general problem. Even so, BIPSPI obtains better MCC than ISPRED4, which reported an MCC of 0.28.

3.6 Use case

In this section, we illustrate how BIPSPI can be employed in order to obtain meaningful information of protein–protein interfaces, especially in those cases where several partners are involved and thus, partner-specificity becomes more important. One of these examples can be found in pdb 4ov6, in which two subunits of the preprotein convertase subtilisin/kexin type 9 (PCKS9) are in complex with a PCSK9-binding adnectin protein. PCSK9 plays an important role in the regulation of low-density lipoprotein (LDL) serum levels thanks to its LDL receptor degrading activity and it has been demonstrated that self-association of PCKS9, that occurs at the catalytic region, increase that activity (Fan et al., 2008). For these reasons, it has become a potential pharmacological target for the treatment and prevention of cardiovascular diseases (Mitchell et al., 2014). PCSK9-binding adnectins, which were derived from human...
fibronectin as an alternative to therapeutic antibodies, are known to bind also close to the active site (Mitchell et al., 2014).

BIPSPI interface residue predictions for the PCKS9-PCKS9 interaction and for the PCKS9-Adenxin interaction are shown in Figure 2. As it can be observed, BIPSPI partner-specificity allows the identification of some of the residues of each native binding site, despite being spatially close. Moreover, it can be noticed that BIPSPI predictions are spatially close to the active site that was identified through 3DBIONOTES application (see Supplementary Section S10 for additional information and Section S11 for an additional use case) (Segura et al., 2017; Tabas-Madrid et al., 2016).

4 Conclusion
In this work, we have presented BIPSPI, a partner-specific predictor of residue–residue contacts and protein binding sites that uses as input either protein sequences or structures. BIPSPI employs the Extreme Gradient Boosting algorithm over a set of structural and/or sequence-based features in order to predict scores of residue pairs that are likely to interact. Then, these predicted scores are converted into binding site predictions by a novel scoring function. BIPSPI was compared with state of the art methods using a leave-one-out cross-validation on different datasets. Additionally, several CAPRI targets were also tested as an independent evaluation benchmark. In all these evaluations, BIPSPI achieved the best performance compared to previously reported methods. Moreover, its partner specificity was successfully evaluated through a Mann–Whitney U statistical test. Finally, BIPSPI is freely available through a user-friendly web application at http://bipspi.cnb.csic.es where prediction and visualization of binding site residues can be compute from either protein structures or sequences.

Funding
Instituto de Salud Carlos III, project number PT13/0001/0009 and PT17/0009/0010 funding the Spanish National Institute of Bioinformatics. The Spanish Ministry of Economy and Competitiveness through Grants AIC-A-2011-0638, BIO2013-44647-R, BIO2016-76400-RI(AEI/FEDER, UE), the ‘Comunidad Autónoma de Madrid’ through Grant: B2017/MDM-3817. Horizon 2020 through Grant CORBEL (INFRADEV-1-2014-1---Proposal: 654248), ELIXIR-EXCELERATE (INFRADEV-1-2015-1—Proposal: 676559) and West-Life (EINFRA-2015-1, Proposal: 675858). J. Segura is recipient of a ‘Juan de la Cierva’ fellowship and R. Sanchez-Garcia is recipient of a FPU fellowship. The authors acknowledge the support and the use of resources of Istituto, a Landmark ESFRI project.

Conflict of Interest: none declared.

References
Ahmad,S. and Mizuguchi,K. (2011) Partner-aware prediction of interacting residues in protein–protein complexes from sequence data. PLoS One, 6, e29104.
Abschuld,S.F. et al. (1997) Gapped BLAST and PSI-BLAST: a new generation of protein database search programs. Nucleic Acids Res., 25, 3389–3402.
Andreeva,A. et al. (2008) Data growth and its impact on the SCOP database: new developments. Nucleic Acids Res., 36, D419–D425.
Breiman,L. (2001) Random forests. Mach. Learn., 45, 5–32.
Cafarelli,T.M. et al. (2017) Mapping, modeling, and characterization of protein–protein interactions on a proteomic scale. Curr. Opin. Struct. Biol., 44, 201–210.
Chen,J. et al. (2014) Protein–protein interface analysis and hot spots identification for chemical ligand design. Curr. Pharm. Des., 20, 1192–1200.

Chen,T. and Guestrin,C. (2016) XGBoost: a scalable tree boosting system. In: Proceedings of the 22nd ACM SIGKDD International Conference on Knowledge Discovery and Data Mining—KDD’16, Vol. 16, pp. 785–794.

Cock,P.J.A. et al. (2009) Biopython: freely available Python tools for computational molecular biology and bioinformatics. Bioinformatics, 25, 1422–1423.

Fan,D. et al. (2008) Self-association of human PCKS9 correlates with its LDLR-degrading activity. Biochemistry, 47, 1631–1639.

Fout,A. et al. (2017) Protein interface prediction using graph convolutional networks. Adv. Neural Inf. Process. Syst., 30, 6512–6521

Friedman,J.H. and Meulman,J.J. (2003) Multiple additive regression trees with application in epidemiology. Stat. Med., 22, 1363–1381.

Grigoriev,A. (2003) On the number of protein–protein interactions in the yeast proteome. Nucleic Acids Res., 31, 4157–4161.

Hamelryck,T. (2005) An amino acid has two sides: a new 2D measure provides a different view of solvent exposure. Proteins Struct. Funct. Bioinformatics, 59, 38–48.

Hwang,H. et al. (2016) A hybrid method for protein–protein interface prediction. Protein Sci., 25, 159–165.

Hwang,H. et al. (2008) Protein–protein docking benchmark version 3.0. Proteins Struct. Funct. Bioinformatics, 73, 705–709.

Hwang,H. et al. (2010) Protein–protein docking benchmark version 4.0. Proteins, 78, 3111–3114.

Jann, J. et al. (2003) CAPRI: a critical assessment of predicted interactions. Proteins Struct. Funct. Genet., 52, 2–9.

Jones,D.T. et al. (2012) PSICOV: precise structural contact prediction using sparse inverse covariance estimation on large multiple sequence alignments. Bioinformatics, 28, 184–190.

Kabsch,W. and Sander,C. (1983) Dictionary of protein secondary structure: pattern recognition of hydrogen-bonded and geometrical features. Biopolymers, 22, 2577–2637.

Meyer,M.J. et al. (2018) Interactome INSIDER: a structural interactome browser for genomic studies. Nat. Methods, 15, 107–114.

Mihelj,J. et al. (2008) PSAIA—protein structure and interaction analyzer. BMC Struct. Biol., 8, 21.

Minhas,Fu. et al. (2014) PAIRpred: partner-specific prediction of interacting residues from sequence and structure. Proteins, 82, 1142–1155.

Mitchell,T. et al. (2014) Pharmacologic profile of the adnectin BMS-962476, a small protein biologic alternative to PCSK9 antibodies for low-density lipoprotein lowering. J. Pharmacol. Exp. Ther., 340, 412–424.

Morcos,F. et al. (2014) Direct coupling analysis for protein contact prediction. Methods Mol. Biol., 1137, 55–70.

Mosca,R. et al. (2013) Interactome3D: adding structural details to protein networks. Nat. Methods, 10, 47–53.

Murakami,Y. and Mizuguchi,K. (2010) Applying the Naïve Bayes classifier with kernel density estimation to the prediction of protein–protein interaction sites. Bioinformatics, 26, 1841–1848.

Neuirth,H. et al. (2004) ProMate: a structure based prediction program to identify the location of protein–protein binding sites. J. Mol. Biol., 338, 181–199.

O’Connell,M.R. et al. (2009) The structural analysis of protein–protein interactions by NMR spectroscopy. Proteomics, 9, 5224–5232.

Osvchinnikov,S. et al. (2014) Robust and accurate prediction of residue–residue interactions across protein interfaces using evolutionary information. Elife, 3, e02030.

Pazos,F. et al. (1997) Correlated mutations contain information about protein–protein interaction. J. Mol. Biol., 271, 511–523.

Pei,J. and Grishin,N.V. (2001) AL2CO: calculation of positional conservation in a protein sequence alignment. Bioinformatics, 17, 700–712.

Porollo,A. and Meller,J. (2006) Prediction-based fingerprints of protein–protein interactions. Proteins Struct. Funct. Bioinformatics, 66, 630–645.

Rodrigues,J.P.G.L.M. et al. (2015) Information-driven structural modelling of protein–protein interactions. Methods Mol. Biol., 1215, 399–424.

Sanchez-Garcia,R. et al. (2017) 3DCONS-D8: a database of position-specific scoring matrices in protein structures. Molecules, 22, 2230.

Savojardo,C. et al. (2017) ISPRED4: interaction sites PREDiction in protein structures with a refining grammar model. Bioinformatics, 33, 1656–1663.
Segura, J. et al. (2017). 3DBIONOTES v2.0: a web server for the automatic annotation of macromolecular structures. *Bioinformatics*, 33, 3655–3657.

Segura, J. et al. (2016). 3DIANA: 3D domain interaction analysis: a toolbox for quaternary structure modeling. *Biophys. J.*, 110, 766–775.

Segura, J. et al. (2012). A holistic in silico approach to predict functional sites in protein structures. *Bioinformatics*, 28, 1845–1850.

Segura, J. et al. (2011). Improving the prediction of protein binding sites by combining heterogeneous data and Voronoi diagrams. *BMC Bioinformatics*, 12, 352.

Segura, J. et al. (2015a). VORFFP-driven dock: V-D2OCK, a fast and accurate protein docking strategy. *PLoS One*, 10, e0118107.

Segura, J. et al. (2015b). Using neighborhood cohesiveness to infer interactions between protein domains. *Bioinformatics*, 31, 2545–2552.

Shi, Y. (2014). A glimpse of structural biology through X-ray crystallography. *Cell*, 159, 995–1014.

Sikić, M. et al. (2009). Prediction of protein–protein interaction sites in sequences and 3D structures by random forests. *PLoS Comput. Biol.*, 5, e1000278.

Sobott, F. and Robinson, C.V. (2002). Protein complexes gain momentum. *Curr. Opin. Struct. Biol.*, 12, 729–734.

Tabas-Madrid, D. et al. (2016). 3DBIONOTES: a unified, enriched and interactive view of macromolecular information. *J. Struct. Biol.*, 194, 231–234.

Vreven, T. et al. (2015). Updates to the integrated protein–protein interaction benchmarks: docking benchmark version 5 and affinity benchmark version 2. *J. Mol. Biol.*, 427, 3031–3041.

de Vries, S. et al. (2006). WHISCY: what information does surface conservation yield? Application to data-driven docking. *Proteins Struct. Funct. Bioinformatics*, 63, 479–489.

Wang, H. et al. (2007). InSite: a computational method for identifying protein–protein interaction binding sites on a proteome-wide scale. *Genome Biol.*, 8, R192.

Xue, L. C. et al. (2015). Computational prediction of protein interfaces: a review of data driven methods. *FEBS Lett.*, 589, 3516–3526.

Xue, L. C. et al. (2011). HomPPI: a class of sequence homology based protein–protein interface prediction methods. *BMC Bioinformatics*, 12, 244.

Zadrozny, B. and Elkan, C. (2002). Transforming classifier scores into accurate multiclass probability estimates. In: *Proceedings of the Eighth ACM SIGKDD International Conference on Knowledge Discovery and Data Mining—KDD ’02*, p. 694.

Zhang, Q. et al. (2016). Recent advances in protein–protein docking. *Curr. Drug Targets*, 17, 1586–1594.