Superregular Matrices and the Construction of Convolutional Codes having a Maximum Distance Profile

Ryan Hutchinson
Mathematics Institute
University of Zürich
Zürich, Switzerland
e-mail: rhutchin@math.unizh.ch

Roxana Smarandache*
Department of Mathematics and Statistics
San Diego State University
San Diego, CA 92182-7720, USA
e-mail: rsmarand@sciences.sdsu.edu

Jochen Trumpf†
Department of Information Engineering, RSISE
The Australian National University
Canberra ACT 0200, Australia
e-mail: Jochen.Trumpf@anu.edu.au

February 1, 2008

Abstract

Superregular matrices are a class of lower triangular Toeplitz matrices that arise in the context of constructing convolutional codes having a maximum distance profile. These matrices are characterized by the property that no submatrix has a zero determinant unless it is trivially zero due to the lower triangular structure. In this paper, we discuss how superregular matrices may be used to construct codes having a maximum distance profile. We also introduce group actions that preserve the superregularity property and present an upper bound on the minimum size a finite field must have in order that a superregular matrix of a given size can exist over that field.

Keywords: convolutional codes, column distances, maximum distance profile, superregular matrices, partial realization problem

*On leave at the University of Notre Dame, Department of Mathematics, Notre Dame, IN 46556.
†Currently seconded to National ICT Australia Limited, which is funded by the Australian Government’s Department of Communications, Information Technology and the Arts and the Australian Research Council through Backing Australia’s Ability and the ICT Centre of Excellence Program.
1 Introduction

Convolutional codes are a class of error-correcting codes that have enjoyed wide use in practical applications due to the existence of efficient non-algebraic decoding algorithms. From a mathematical standpoint, however, the situation is still rather unsatisfying, as there are relatively few algebraic constructions of convolutional codes with provably good distance properties or which can be algebraically decoded. Recent years have seen interesting developments in the algebraic theory of convolutional codes: the papers [7, 8, 10, 11, 15] extend the notion of cyclicity familiar from block code theory to convolutional codes; the papers [5, 12] investigate weight enumerators and the existence of a MacWilliams Identity for convolutional codes; the paper [19] uses methods from systems theory to construct convolutional codes having a designed distance; and the papers [6, 9, 13, 18, 21] provide results concerning convolutional codes having certain maximal distance properties. Motivated by existence results appearing in certain members of this last set of papers, we decided to investigate so-called superregular matrices. These matrices arise when one considers the problem of constructing convolutional codes having a maximum distance profile.

The remainder of this paper is structured as follows. In Section 2, we give a brief introduction to convolutional codes, explain the maximal distance properties mentioned above, and define the superregularity property. In Section 3, we discuss how superregular matrices may be used to construct codes having a maximum distance profile. In Section 4, we introduce group actions that preserve the superregularity property; these actions made it possible to reduce the computation time necessary for performing searches for superregular matrices. Finally, in Section 5, we present an upper bound on the minimum field size required for a superregular matrix of a given size to exist.

2 Preliminaries

In this section, we review the theory of convolutional codes relevant to the presented work. Let \( k \) and \( n \) be positive integers with \( k < n \). Let \( \mathbb{F} \) be a finite field of characteristic \( p \), where \( p \) is a prime number.

Definition 2.1 A convolutional code \( \mathcal{C} \) of rate \( k/n \) is a rank-\( k \) submodule of the free module \((\mathbb{F}[s])^n\).

Since \( \mathbb{F}[s] \) is a principal ideal domain, \( \mathcal{C} \) is a free module and has a well-defined rank. It follows that a convolutional code may be viewed as the column space of an \( n \times k \) polynomial matrix \( G(s) \), the columns of which form an \( \mathbb{F}[s] \)-basis for \( \mathcal{C} \). As a set, we have

\[
\mathcal{C} = \{v(s) = G(s)u(s) \in (\mathbb{F}[s])^n \mid u(s) \in (\mathbb{F}[s])^k\}.
\]

\( G(s) \) is called a generator matrix for \( \mathcal{C} \), the \( u(s) \) are called information vectors, and the \( v(s) \) are called code vectors or codewords. Two generator matrices \( G_1(s) \) and \( G_2(s) \) having full
column rank generate the same code if and only if there exists a \( k \times k \) unimodular matrix \( U(s) \) such that \( G_1(s) = G_2(s)U(s) \).

The columns of \( G(s) \) may be thought of as polynomials with coefficients in \( \mathbb{F}^n \); we refer to the degrees of these polynomials as the column degrees of \( G(s) \) and denote the degree of the \( i \)th column by \( \mu_i \). Let \( m := \max_{1 \leq i \leq k} \{ \mu_i \} \). Thinking of \( (\mathbb{F}[s])^{(n \times k)} \) as \( \mathbb{F}^{(n \times k)}[s] \), we may then expand \( G(s) \) into a matrix polynomial,

\[
G(s) = G_0 + G_1 s + \cdots + G_m s^m,
\]

where \( G_i \) is an \( n \times k \) matrix over \( \mathbb{F} \), the entries of which are the coefficients of \( s^i \) in \( G(s) \). Similarly, thinking of \( (\mathbb{F}[s])^k \) as \( \mathbb{F}^k[s] \), we may expand \( u(s) \in (\mathbb{F}[s])^k \) of degree \( l \) into a vector polynomial:

\[
u(s) = u_0 + u_1 s + \cdots + u_l s^l.
\]

We may then represent the encoding process with the multiplication

\[
\begin{bmatrix}
  v_0 \\
v_1 \\
\vdots \\
v_{l+m}
\end{bmatrix} = \begin{bmatrix}
  G_0 & 0 & \cdots & \cdots & 0 \\
  G_1 & G_0 & \ddots & \cdots & \vdots \\
  \vdots & \ddots & \ddots & \ddots & \vdots \\
  G_{m-1} & \ddots & \ddots & \ddots & 0 \\
  G_m & G_{m-1} & \ddots & \ddots & G_0
\end{bmatrix} \begin{bmatrix}
u_0 \\
v_1 \\
\vdots \\
u_l
\end{bmatrix},
\]

where 0 represents the \( n \times k \) matrix with all entries zero. The large matrix in the middle is called a sliding generator matrix. From this representation, we see the origin of the name convolutional code: the vector coefficients of the information vector are convoluted with the matrix coefficients of \( G(s) \) to form the codewords.

A generator matrix \( G(s) \) is called basic if the only common divisors of the determinants of its \( k \times k \) submatrices belong to \( \mathbb{F} \backslash \{0\} \). There are several characterizations of this property; more details may be found in [11, 15, 17]. We note here two of these characterizations. The first is that a convolutional code generated by a basic generator matrix is a direct summand of \( \mathbb{F}^n[s] \). The second is that there exists a basic \( n \times (n - k) \) matrix over \( \mathbb{F}[s] \), \( H(s) \), such that \( \mathcal{C} \) is the right \( \mathbb{F}[s] \)-kernel of \( H^T(s) \). Thus, an observable code may also be described as the set

\[
\mathcal{C} = \{ v(s) \in (\mathbb{F}[s])^n \mid H^T(s)v(s) = [0 0 \cdots 0]^T \in (\mathbb{F}[s])^k \}\]

\( H(s) \) is called a parity check matrix of \( \mathcal{C} \). As with the generator matrix, one may expand \( H(s) \) as the sum

\[
H(s) = H_0 + H_1 s + \cdots + H_m s^m,
\]
where \( m' \) is the largest integer such that \( H_{m'} \neq 0 \). A convolutional code \( \mathcal{C} \) is called observable if one (and hence every) generator matrix of \( \mathcal{C} \) is basic.

The high-order coefficient matrix \( G_\infty \) of \( G(s) \) is a matrix, the \( i \)th column of which is the vector coefficient of \( s^{\mu_i} \) in column \( i \). A basic generator matrix for which \( G_\infty \) has full rank is called minimal. An important invariant of a convolutional code is its complexity, defined as follows:

**Definition 2.2** The complexity \( \delta \) of a convolutional code \( \mathcal{C} \) is the maximum of the degrees of the (polynomial) determinants of the \( k \times k \) submatrices of any generator matrix of \( \mathcal{C} \).

This definition makes sense, as the equivalence relation described above preserves the degrees of these determinants. A code of rate \( k/n \) and complexity \( \delta \) will also be referred to as an \((n, k, \delta)\)-code. If the code is observable, the complexity is normally referred to as the degree of the code; see [18] for the geometric motivation for this terminology.

In general, \( G_\infty \) need not have full rank; in this case, \( \sum_{i=1}^{k} \mu_i > \delta \). It is shown in [4] that it is always possible to find a unimodular matrix \( U(s) \) such that \( G(s)U(s) \) has a full-rank high-order coefficient matrix and a set \( \{\nu_i\}_{i=1}^{k} \) of column degrees satisfying \( \nu_1 \leq \nu_2 \leq \cdots \leq \nu_k \) and \( \sum_{i=1}^{k} \nu_i = \delta \). In this case, the column degrees are invariants of the code generated by \( G(s) \) and are called the column indices or the Kronecker indices of the code. If \( G(s) \) is minimal, the column degrees \( \nu_1 \leq \nu_2 \leq \cdots \leq \nu_k \) mentioned above are called the minimal column indices or the Forney indices of the code. For the remainder of the paper, we assume all codes to be observable and generator matrices to be minimal.

The following truncated sliding generator matrices \( G^c_j \in \mathbb{F}^{(j+1)n \times (j+1)k} \) and parity check matrices \( H^c_j \in \mathbb{F}^{(j+1)n \times (j+1)(n-k)} \) will be of importance in this work. These are defined for each \( j \in \mathbb{N}_0 \) as

\[
G^c_j := \begin{bmatrix} G_0 & 0 & \cdots & 0 \\ G_1 & G_0 & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ G_j & G_{j-1} & \cdots & G_0 \end{bmatrix} \quad \text{and} \quad H^c_j := \begin{bmatrix} H_0 & H_1 & \cdots & H_j \\ 0 & H_0 & \cdots & H_{j-1} \\ \vdots & \ddots & \ddots & \vdots \\ 0 & \cdots & 0 & H_0 \end{bmatrix}, \tag{2.1}
\]

where \( G_j = 0 \) (\( H_j = 0 \)) if \( j > m \) (\( j > m' \)). The relation \( H^T(s)G(s) = 0 \) immediately implies that \( (H^c_j)^T G^c_j = 0 \) for all \( j \in \mathbb{N}_0 \).

We turn now to some distance notions for convolutional codes.

**Definition 2.3** Let \( x \in \mathbb{F}^n \). The Hamming weight of \( x \), \( \text{wt}(x) \), is the number of nonzero components of \( x \). Let \( v(s) \in \mathbb{F}^n[s] \) be given by \( v(s) := v_0 + v_1s + \cdots + v_ls^l \) for some nonnegative integer \( l \). The weight of \( v(s) \), \( \text{wt}(v(s)) \), is the sum of the weights of its \( \mathbb{F}^n \)-coefficients:

\[
\text{wt}(v(s)) := \sum_{i=0}^{l} \text{wt}(v_i).
\]

We then have
Definition 2.4 Let $C$ be an $(n, k, \delta)$-code. Then, the free distance of $C$, $d_{\text{free}}(C)$, is
\[ d_{\text{free}}(C) := \min_{v(s) \in C} \{ \text{wt}(v(s)) \mid v(s) \neq 0 \}. \]

The following theorem gives an upper bound for how large the free distance of an $(n, k, \delta)$-code can be:

Theorem 2.5 Let $C$ be an $(n, k, \delta)$-code. Then, $d_{\text{free}}(C)$ satisfies
\[ d_{\text{free}}(C) \leq (n - k) \left( \left\lceil \frac{\delta}{k} \right\rceil + 1 \right) + \delta + 1. \]

This bound is proven in [18]. It is known as the generalized Singleton bound. The reason for this is that a convolutional code of complexity 0 is a block code, as it has a generator matrix with all entries in $\mathbb{F}$. If we set $\delta = 0$ in the above expression, it reduces to the Singleton bound from the theory of block codes. In analogy with the block code case, convolutional codes having a free distance meeting the generalized Singleton bound are called maximum distance separable (MDS).

The free distance is a global distance measure and determines the maximum number of errors that may be introduced to a codeword without jeopardizing correct decoding. A more local distance measure, relevant to the performance of sequential decoding algorithms (see, for example, [16]), is given by column distances. These are defined as follows:

Definition 2.6 Let $C$ be a convolutional code. For $j \in \mathbb{N}_0$ and a polynomial vector $v(s) \in \mathbb{F}^n[s]$ of degree $l$, set $v_{[0,j]}(s) := v_0 + v_1 s + \cdots + v_j s^j$ (where $v_j = 0$ if $j > l$). Then, the $j$th column distance of $C$, $d_{c_j}^C(C)$, is defined as
\[ d_{c_j}^C(C) := \min_{v(s) \in C} \{ \text{wt}(v_{[0,j]}(s)) \mid v_0 \neq 0 \}. \]

Because of the assumption that $C$ is observable, the fact that $v_0 \neq 0$ means that the minimum is taken over codewords resulting from information vectors with $u_0 \neq 0$. It is easy to see that the column distances satisfy
\[ d_{c_0}^C(C) \leq d_{c_1}^C(C) \leq d_{c_2}^C(C) \ldots \leq \lim_{j \to \infty} d_{c_j}^C(C) = d_{\text{free}}(C). \tag{2.2} \]

The $(m + 1)$-tuple of numbers $(d_{c_0}^C(C), d_{c_1}^C(C), \ldots, d_{c_m}^C(C))$ is called the column distance profile of the code [13] p. 112].

The following theorem gives an upper bound for the $j$th column distance:

Theorem 2.7 Let $C$ be an $(n, k, \delta)$-code. For every $j \in \mathbb{N}_0$, we have
\[ d_{c_j}^C(C) \leq (n - k)(j + 1) + 1. \]

If $d_{c_j}^C(C) = (n - k)(j + 1) + 1$ for some $j$, then $d_{c_i}^C(C) = (n - k)(i + 1) + 1$ when $i \leq j$. 

5
A proof may be found in [9]. By considering the bound in Theorem 2.7 one easily sees that the largest integer for which the upper bound in Theorem 2.7 can be attained is \( L := \left\lfloor \frac{\delta}{k} \right\rfloor + \left\lfloor \frac{\delta}{n-k} \right\rfloor \). An \((n, k, \delta)-\)code \( C \) is said to be maximum distance profile (MDP) if \( d^c_j(C) = (j + 1)(n - k) + 1 \) for all \( j \in \{0, 1, \ldots, L\} \). In other words, the column distances of an MDP code are maximal for as long as possible.

We close this section by introducing superregular matrices; in Section 2, we will see their relevance to the construction of MDP codes.

**Definition 2.8** Let \( A \) be the \((\gamma + 1) \times (\gamma + 1)\) lower triangular Toeplitz matrix 

\[
\begin{bmatrix}
  a_0 & 0 & \cdots & 0 \\
  a_1 & a_0 & \ddots & \vdots \\
  \vdots & \ddots & \ddots & 0 \\
  a_\gamma & \cdots & a_1 & a_0
\end{bmatrix}
\]

Let \( s \in \{1, 2, \ldots, \gamma + 1\} \). Suppose that \( I := \{i_1, \ldots, i_s\} \) is a set of row indices of \( A \), \( J := \{j_1, \ldots, j_s\} \) is a set of column indices of \( A \), and that the elements of each set are ordered from least to greatest. We denote by \( A^{i_1, \ldots, i_s}_{j_1, \ldots, j_s} \) the submatrix of \( A \) formed by intersecting the columns indexed by the members of \( J \) and the rows indexed by the members of \( I \). A submatrix of \( A \) is said to be proper if, for each \( \nu \in \{1, 2, \ldots, s\} \), the inequality \( j_\nu \leq i_\nu \) holds. The matrix \( A \) is said to be superregular if every proper submatrix of \( A \) has a nonzero determinant.

**Remark 2.9** Observe that the proper submatrices of \( A \) are the only ones that can possibly have a nonzero determinant: If \( j_\nu > i_\nu \) for some \( \nu \), then, in the submatrix \( A^{i_1, \ldots, i_s}_{j_1, \ldots, j_s} \), the upper right block consisting of the first \( \nu \) rows and the last \( s - \nu + 1 \) columns contains only zero entries. Hence, the matrix formed from the first \( \nu \) rows of \( A^{i_1, \ldots, i_s}_{j_1, \ldots, j_s} \) can have rank at most \( \nu - 1 \). For example, if \( \gamma \geq 4 \), we can consider the submatrix

\[
A_{1,3,4}^{1,2,5} = \begin{bmatrix}
  a_0 & 0 & 0 \\
  a_1 & 0 & 0 \\
  a_4 & a_2 & a_1
\end{bmatrix}.
\]

This submatrix clearly has a zero determinant regardless of what \( a_0, a_1, a_2, \) and \( a_4 \) are.
3 A Construction of MDP Codes from Superregular Matrices

In this section, we take a closer look at the transposes \((H_j^c)^T \in \mathbb{F}^{(j+1)(n-k) \times (j+1)n}\) of the matrices that were introduced in (2.1):

\[
(H_j^c)^T = \begin{bmatrix}
H_0^T & 0 & \cdots & 0 \\
H_1^T & H_0^T & \ddots & \vdots \\
\vdots & \vdots & \ddots & 0 \\
H_j^T & H_{j-1}^T & \cdots & H_0^T
\end{bmatrix}.
\]

We then have the following definition:

**Definition 3.1** \((H_j^c)^T\) is said to have the *maximum span property* if none of the first \(n\) columns of \((H_j^c)^T\) is contained in the span of any other \((j+1)(n-k) - 1\) columns of \((H_j^c)^T\).

We note here that, of course, each of the first \(n\) columns of \((H_j^c)^T\) is in the span of some set of \((j+1)(n-k)\) columns of \((H_j^c)^T\). We also make the observation that, if \(C\) is an \((n, k, \delta)\)-code and \((H_j^c)^T\) the transpose of its \(j\)th truncated sliding parity check matrix, then \(d_j^c(C) = (n-k)(j+1) + 1\) if and only if \((H_j^c)^T\) has the maximum span property. In particular, \(C\) is an MDP code if and only if \((H_j^c)^T\) has the maximum span property.

Since \(H(s)\) is basic, we may assume without loss of generality (for the purpose of what follows) that the \((n-k) \times (n-k)\) submatrix of \(H_0\) consisting of the first \(n-k\) columns has full rank. In this case, left multiplication by an invertible matrix followed by a column permutation gives the matrix

\[
\left(\overline{H_j^c}\right)^T := \begin{bmatrix}
1 & 0 & \cdots & 0 & \hat{H}_0 & 0 & \cdots & 0 \\
0 & 1 & \ddots & \vdots & \hat{H}_1 & \hat{H}_0 & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 & \vdots & \ddots & \ddots & 0 \\
0 & \cdots & 0 & 1 & \hat{H}_j & \hat{H}_{j-1} & \cdots & \hat{H}_0
\end{bmatrix} := \left[ I_{(j+1)(n-k)} \left| \hat{H} \right. \right].
\]

Recalling Definition 3.1, we will also say that any matrix having the same form as \(\left(\overline{H_j^c}\right)^T\) has the maximum span property if none of the first \(k\) columns of \(\hat{H}\) is contained in the span of any other \((n-k)(j+1) - 1\) columns of \(\left(\overline{H_j^c}\right)^T\). Note that if \((H_j^c)^T\) has the maximum span property, then so does \(\left(\overline{H_j^c}\right)^T\). The next theorem is a simplified version of [9, Theorem 3.5]; it relates the superregularity property to the maximum span property:

**Theorem 3.2** Let \(T\) be a \((j+1) \times (j+1)\) lower triangular Toeplitz matrix:

\[
T := \begin{bmatrix}
t_0 & 0 & \cdots & 0 \\
t_1 & t_0 & \ddots & \vdots \\
\vdots & \ddots & \ddots & 0 \\
t_j & t_{j-1} & \cdots & t_0
\end{bmatrix}
\]  

(3.3)
Then, $T$ is superregular if and only if the matrix $[I_{j+1} | T]$ has the maximum span property.

Given $k$, $n$, and $j$, we will now see how to use an appropriately sized superregular matrix to construct a matrix which has the form of $(H^T_j)$ and the maximum span property (for more details, see [9, Appendix C]):

**Theorem 3.3** Let $T$ be an $l \times l$ superregular matrix, where $l \geq (j+1)(n-1)$. Let $T'$ the submatrix obtained from $T$ by intersecting the rows indexed by $\{k, k+1, \ldots, n-1, n-1+k, n-1+k+1, \ldots, 2(n-1), \ldots, j(n-1) + k, j(n-1) + k+1, \ldots, j(n-1) + n-1\}$ and columns indexed by $\{1, 2, \ldots, k, n-1+1, n-1+2, \ldots, n-1+k, \ldots, j(n-1) + 1, j(n-1) + 2, \ldots, j(n-1) + k\}$. Then, $T' \in F^{(j+1)(n-k) \times (j+1)k}$ is a lower block triangular Toeplitz matrix such that $[I_{(j+1)(n-k)} | T']$ has the maximum span property.

If we let $j = L$, we may use the resulting matrix to construct a parity check matrix of an MDP convolutional code.

**Example 3.4** In this example, we consider the following matrix over $F_{64}$:

$$
\begin{bmatrix}
1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 \\
\omega & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
\omega^9 & \omega & 1 & 0 & 0 & 0 & 0 & 0 \\
\omega^{33} & \omega^9 & \omega & 1 & 0 & 0 & 0 & 0 \\
\omega^{33} & \omega^{33} & \omega^9 & \omega & 1 & 0 & 0 & 0 \\
\omega^9 & \omega^{33} & \omega^{33} & \omega^9 & \omega & 1 & 0 & 0 \\
1 & \omega & \omega^9 & \omega^{33} & \omega^{33} & \omega^9 & \omega & 1 
\end{bmatrix}
$$

Here, $\omega$ is a root of $x^6 + x + 1 \in F_2[x]$ and is thus a primitive field element. According to [9], this matrix is superregular. We let $k = 2$, $n = 3$, and $\delta = 2$. Then, $L = 3$, and, since $(L+1)(n-1) = 8$, we may use Theorem 3.3 to form the matrix

$$
\begin{bmatrix}
1 & 0 & 0 & 0 | \omega & 1 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 1 & 0 & 0 | \omega^{33} & \omega^9 & \omega & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 1 & 0 | \omega^9 & \omega^{33} & \omega^9 & \omega & 1 & 0 & 0 & 0 \\
0 & 0 & 0 & 1 | 1 & \omega & \omega^9 & \omega^{33} & \omega^{33} & \omega^9 & \omega & 1 
\end{bmatrix}
$$

which has the maximum span property. We may then use this matrix to construct a polynomial generator matrix for an MDP $(3,2,3)$ code. We could, for example, think of the $1 \times 2$ matrices making up the first block column of the right-hand side of this matrix as a finite sequence of Markov parameters and compute a minimal partial realization of this sequence (see, for example, [1]). We would then compute the corresponding transfer function. After some small algebraic manipulations and fixing an ordering for the codeword components, we would arrive at a polynomial generator matrix and its corresponding convolutional code.
(see [19] for more information about the relationship between the linear systems and polynomial representations of convolutional codes). In this example, one possibility for a resulting generator matrix is

\[
\begin{bmatrix}
 s^2 + \omega^{57} s + \omega^{62} & 0 \\
 0 & s^2 + \omega^{57} s + \omega^{62} \\
 \omega^2 + \omega^{44} s + \omega^{54} & s^2 + \omega^{17} s + \omega^{21}
\end{bmatrix}.
\]

4 Group Actions Preserving the Superregularity Property

In this section, we consider group actions that allow one to create new superregular matrices from a given one. The main utility of these actions is that they reduce the number of matrices one must check when performing a computer search for matrices having the superregularity property.

For a prime power \( p^e \) and a nonnegative integer \( \gamma \), denote by \( SR(p^e, \gamma) \) the set of superregular matrices of dimension \( \gamma + 1 \) over \( \mathbb{F}_{p^e} \). The first group action is a corollary of the following result, which is proven in [9]:

**Theorem 4.1** Suppose that \( A \in SR(p^e, \gamma) \). Then, \( A^{-1} \in SR(p^e, \gamma) \).

**Corollary 4.2** There is an action \( *_1 \) of the additive group \((\mathbb{Z}, +)\) on the set \( SR(p^e, \gamma) \), given by

\[
*_1 : \mathbb{Z} \times SR(p^e, \gamma) \longrightarrow SR(p^e, \gamma)
\]

\[
(x, A) \longmapsto A^{(-1)^x}.
\]

**Proof:** By Theorem 4.1, \( A^{-1} \) is superregular, and it is clear that \( *_1 \) is a group action. \( \square \)

We next have the following simple result:

**Lemma 4.3** If \( A \in SR(p^e, \gamma) \) and \( \gamma \geq 2 \), then \( A \neq A^{-1} \).

**Proof:** Suppose

\[
A := \begin{bmatrix}
 a_0 & 0 & \cdots & 0 \\
 a_1 & a_0 & \ddots & \vdots \\
 \vdots & \ddots & \ddots & 0 \\
a_\gamma & \cdots & a_1 & a_0
\end{bmatrix}
\]

is a superregular matrix, where \( \gamma \geq 2 \). Suppose in addition that \( A = A^{-1} \). Then, since \( A^2 = I_{\gamma+1} \), we must have that \( a_0a_1 + a_1a_0 = 2a_0a_1 = 0 \). By hypothesis, \( a_0, a_1 \neq 0 \). Thus, the field must have characteristic 2. We must also have that \( a_2a_0 + a_1^2 + a_0a_2 = 2a_0a_2 + a_1^2 = 0 \). Since the field has characteristic 2, this equation reduces to \( a_2^2 = 0 \). This is a contradiction, as \( a_1 \neq 0 \). Thus, \( A \neq A^{-1} \). \( \square \)

**Corollary 4.4** If \( \gamma \geq 2 \), then \( |SR(p^e, \gamma)| \) is even.
We next describe an action of the multiplicative group $F_{p^e}^* := F_{p^e} \setminus \{0\}$ of nonzero field elements of $F_{p^e}$ on $SR(p^e, \gamma)$:

**Theorem 4.5** Let $\alpha \in F_{p^e}^*$. Define

$$\alpha \cdot A := \begin{bmatrix} a_0 & 0 & \cdots & 0 \\ \alpha a_1 & \ddots & \ddots & \vdots \\ \alpha^2 a_2 & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ \alpha^{\gamma} a_{-\gamma} & \cdots & \alpha^2 a_2 & \alpha a_1 & a_0 \end{bmatrix}$$

Then, the map

$$\ast_2 : F_{p^e}^* \times SR(p^e, \gamma) \longrightarrow SR(p^e, \gamma) \quad (\alpha, A) \mapsto \alpha \cdot A$$

is an action of $F_{p^e}^*$ on $SR(p^e, \gamma)$.

**Proof:** It is readily verified that $\ast_2$ is a group action. Let

$$D := \begin{bmatrix} 1 & 0 & \cdots & 0 \\ 0 & \alpha & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ 0 & \cdots & 0 & \alpha^\gamma \end{bmatrix}.$$  

One can then describe $\ast_2$ through conjugation by $D$: $\alpha \cdot A = DAD^{-1}$. This changes the determinants of submatrices of $A$ only by factors of powers of $\alpha$, and it follows that $\alpha \cdot A$ is also superregular.  

The final group action we consider makes use of the Galois group $Aut_{F_{p^e}}F_{p^e}$. We recall here the fact that $Aut_{F_{p^e}}F_{p^e} = \langle \sigma \rangle$, where $\sigma \in Aut_{F_{p^e}}F_{p^e}$ is the $F_p$-automorphism defined by $\sigma(x) = x^p \forall x \in F_{p^e}$. Consequently, $Aut_{F_{p^e}}F_{p^e} \cong \mathbb{Z}/e\mathbb{Z}$.

**Theorem 4.6** Let $A \in SR(p^e, \gamma)$. Let $i \in \mathbb{Z}/e\mathbb{Z}$. Define

$$i \circ A := \begin{bmatrix} a_0^i & 0 & \cdots & 0 \\ a_1^i & \ddots & \ddots & \vdots \\ a_2^i & \ddots & \ddots & \vdots \\ \vdots & \ddots & \ddots & 0 \\ a_{-\gamma}^i & \cdots & a_2^i & a_1^i & a_0^i \end{bmatrix}.$$  

Then, the map

$$\ast_3 : \mathbb{Z}/e\mathbb{Z} \times SR(p^e, \gamma) \longrightarrow SR(p^e, \gamma) \quad (i, A) \mapsto i \circ A$$

is an action of the additive group $\mathbb{Z}/e\mathbb{Z}$ on $SR(p^e, \gamma)$.  

10
Proof: It is readily verified that $*_3$ is a group action. As the entries of $A$ belong to a field of characteristic $p$, the determinant of a submatrix of $i \circ A$ is the determinant of the corresponding submatrix of $A$ raised to the $p^i$th power. Thus, $i \circ A$ is also superregular. □

5 An Upper Bound for the Required Field Size

An important question to consider in trying to better understand superregular matrices is that of how large a finite field must be in order that a superregular matrix of a given size can exist over that field. For example, no $3 \times 3$ superregular matrix exists over the field $\mathbb{F}_2$: all entries in the lower triangular part of a superregular matrix must be nonzero, which means that in this case all such entries would have to be 1; clearly, this does not result in a superregular matrix, since the lower left $2 \times 2$ submatrix has a zero determinant. In this section, we give an upper bound on the required field size. We begin with a technical lemma:

Lemma 5.1 Let $i$ be a nonnegative integer and $\gamma$ a positive integer. Let $S_{i+1}$ denote the set of integer sequences $\{s_l\}_{l=0}^{i+1}$, where $s_0 = 0$, $s_{i+1} = \gamma$, and $s_l < s_{l+1} \forall l \in \{0, 1, \ldots, i\}$. Let $S_{i,\gamma} := \{\{s_l\}_{l=0}^{i+1} \in S_{i+1} \text{ with } s_j + s_{i-j+1} \leq \gamma, j = 0, 1, \ldots, \left\lceil \frac{i}{2} \right\rceil\}$. Let $T_{i+1}$ denote the set of integer sequences $\{t_l\}_{l=0}^{i+1}$, where $t_0 = 0$, $t_{i+1} = \gamma$, and $t_l < t_{l+1} \forall l \in \{0, 1, \ldots, i\}$. Let $T_{i,\gamma} := \{\{t_l\}_{l=0}^{i+1} \in T_{i+1} \text{ with } \sum_{l=0}^{m} (-1)^l(t_{l+1} - t_l) \geq 0, m = 0, 1, \ldots, i\}$. Then, $S_{i,\gamma}$ and $T_{i,\gamma}$ are finite sets, and $|S_{i,\gamma}| = |T_{i,\gamma}|$.

Proof: It is clear that $S_{i,\gamma}$ and $T_{i,\gamma}$ are finite sets. We now proceed to prove the second part of the claim. We will do this by first constructing an injective map from $S_{i,\gamma}$ to $T_{i,\gamma}$ and then an injective map from $T_{i,\gamma}$ to $S_{i,\gamma}$. Throughout the proof, $t_{-1}$ and $s_{-1}$ are defined to be 0. Suppose first that $i$ is even. Let $\{s_l\}_{l=0}^{i+1} \in S_{i,\gamma}$. For $j \in \{0, 1, \ldots, \frac{i}{2}\}$, we make the recursive definitions

$$t_{2j+1} := t_{2j} + s_{i-j+1} - s_{i-j},$$

$$t_{2j} := t_{2j-1} + s_{j} - s_{j-1}.$$  

Note that $t_0 = s_0 = 0$. Then, for $m \in \{0, 1, \ldots, i\}$, we have

$$\sum_{l=0}^{m} (-1)^l(t_{l+1} - t_l) = t_1 - (t_2 - t_1) + (t_3 - t_2) - \cdots + (-1)^m(t_{m+1} - t_m)$$

$$= 2t_1 - 2t_2 + 2t_3 - \cdots + (-1)^m t_{m+1}$$

$$= 2t_1 - 2t_2 + 2t_3 - \cdots - t_{2j}$$

or

$$= 2t_1 - 2t_2 + 2t_3 - \cdots + t_{2j+1},$$
where \( j \in \{0, 1, \ldots, \frac{m}{2}\} \) is \((m - 1)/2\) or \(m/2\) as \(m\) is odd or even, respectively. Suppose first that \(m\) is odd. The sum then becomes
\[
2t_{1} - 2t_{2} + 2t_{3} - \cdots - t_{2j} = 2t_{1} - 2(t_{1} + s_{1}) + 2t_{3} - \cdots - (t_{2j-1} + s_{j} - s_{j-1})
\]
\[
= t_{2j-1} - (s_{j} - s_{j-1}) - 2s_{j-1}
\]
\[
= t_{2j-1} - s_{j} - s_{j-1}.
\]

Using the definition of \(t_{2j+1}\) with \(j\) replaced by \(j - 1\), we may write
\[
t_{2j-1} - s_{j} - s_{j-1} = t_{2j-2} + s_{i-j+2} - s_{i-j+1} - s_{j} - s_{j-1}.
\]

Using again the definitions above, we see that, for any integer \(h \in \{0, \ldots, j - 1\}\),
\[
t_{2j-2} + s_{i-j+2} - s_{i-j+1} - s_{j} - s_{j-1} = t_{2(j-h)-2} + s_{i-(j-(h+1))+1} - s_{i-j+1} - s_{j} - s_{j-(h+1)};
\]
this equation holds trivially if \(h = 0\), and, if \(h \in \{0, \ldots, j - 2\}\), we have
\[
t_{2(j-h)-2} + s_{i-(j-(h+1))+1} - s_{i-j+1} - s_{j} - s_{j-(h+1)} =
\]
\[
t_{2(j-h)-(h)} + s_{i-(j-(h+1))} - s_{i-j+1} - s_{j} - s_{j-(h+1)} =
\]
\[
t_{2(i-(j-(h+1)))+1} - s_{i-j+1} - s_{j} - s_{j-(h+1)} =
\]
\[
t_{2(j-(h+1))-2} + s_{i-(j-(h+1))+1} - s_{i-j+1} - s_{j} - s_{j-(h+1)}.
\]

In particular, letting \(h = j - 2\) and recalling that \(s_{i+1} = \gamma\) and \(s_{0} = 0\), we see that
\[
t_{2j-2} + s_{i-j+2} - s_{i-j+1} - s_{j} - s_{j-1} = \gamma - s_{i-j+1} - s_{j}.
\]

Because \(\{s_{i}\}_{i=0}^{j+1} \in S_{i, \gamma}, \gamma - s_{i-j+1} - s_{j} \geq 0\).

Suppose now that \(m\) is even. We are then interested in the sum
\[
2t_{1} - 2t_{2} + 2t_{3} - \cdots + t_{2j+1}.
\]

From the analysis in the case of \(m\) odd, we see that we may write
\[
2t_{1} - 2t_{2} + 2t_{3} - \cdots + t_{2j+1} = t_{2j-1} - s_{j} - s_{j-1} - t_{2j} + t_{2j+1}
\]
\[
= t_{2j-1} - s_{j} - s_{j-1} - t_{2j} + t_{2j} + s_{i-j+1} - s_{i-j}
\]
\[
= t_{2j-1} - s_{j} - s_{j-1} + s_{i-j+1} - s_{i-j}.
\]

Using the same method as before, we see that, for any integer \(h \in \{0, \ldots, j - 1\}\),
\[
t_{2j-1} - s_{j} - s_{j-1} + s_{i-j+1} - s_{i-j} = t_{2(j-h)-1} + s_{i-(j-(h+1)+1} - s_{i-j} - s_{j} - s_{j-(h+1)}.
\]

In particular, letting \(h = j - 1\), the right side of this equality reduces to
\[
t_{1} + s_{i} - s_{i-j} - s_{j}.
\]
Using the definition of $t_1$, this becomes

$$s_{i+1} - s_i + s_i - s_{i-j} - s_j = s_{i+1} - s_{i-j} - s_j$$

$$= \gamma - s_{i-j} - s_j.$$  

Since $s_{i-j} < s_{i-j+1}$ and $\gamma - s_{i-j+1} - s_j \geq 0$, it follows that $\gamma - s_{i-j} - s_j \geq 0$.

It remains to be shown that $t_{i+1} = \gamma$. We have

$$t_{2j+1} = t_{2j} + s_{i-j+1} - s_{i-j}$$

$$= t_{2j-1} + s_{j} - s_{j-1} + s_{i-j+1} - s_{i-j}$$

$$= t_{2j-2} + s_{i-j+2} + s_{j} - s_{j-1} - s_{i-j}.$$  

In the same way as above, one sees that, for any integer $h \in \{1, \ldots, j\}$,

$$t_{2j-2} + s_{i-j+2} + s_{j} - s_{j-1} - s_{i-j} = t_{2(j-h)} + s_{i-(j-h)+1} - s_{j-h} + s_{j} - s_{i-j}.$$  

In particular, letting $j = \frac{i}{2}$ and $h = j$, the right side of the preceding equality simplifies to $s_{i+1}$. By hypothesis, $s_{i+1} = \gamma$. Thus, $t_{i+1} = \gamma$. This completes the case of $i$ even.

Suppose now that $i$ is odd. For $j \in \{0, 1, \ldots, \frac{i-1}{2}\}$, define $t_{2j+1}$ as above. For $j \in \{0, 1, \ldots, \frac{i-1}{2}\}$, define $t_{2j}$ as above. The proof then proceeds as in the case of $i$ even.

We thus obtain a well-defined map $f$ from $S_{i,\gamma}$ to $T_{i,\gamma}$: if $\{s_l\}_{l=0}^{i+1} \in S_{i,\gamma}$, let $f(\{s_l\}_{l=0}^{i+1}) = \{t_l\}_{l=0}^{i+1}$, where each $t_l$ is defined via the equations at the beginning of the proof. It follows immediately from the definition of the $t_l$ that $f$ is injective. Thus, to show $|S_{i,\gamma}| = |T_{i,\gamma}|$, it will suffice to construct a similar injective map from $T_{i,\gamma}$ to $S_{i,\gamma}$.

Suppose first that $i$ is even. Let $\{t_l\}_{l=0}^{i+1} \in T_{i,\gamma}$. For $j \in \{0, 1, \ldots, \frac{i}{2}\}$, we make the recursive definitions

$$s_j := s_{j-1} + t_{2j} - t_{2j-1}$$

$$s_{i-j} := s_{i-j+1} - t_{2j+1} + t_{2j}.$$  

Note that $s_0 = t_0 = 0$. Then, using these definitions, we have that

$$s_j + s_{i-j+1} = s_{j-1} + t_{2j} - t_{2j-1} + s_{i-j+2} + t_{2j-2} - t_{2j-1}$$

$$= s_{j-2} + t_{2j-2} - t_{2j-3} + t_{2j} - t_{2j-1} + s_{i-j+3} + t_{2j-4} - t_{2j-3} + t_{2j-2} - t_{2j-1}$$

$$= \gamma - 2t_1 + 2t_2 - \cdots + t_{2j}. $$
Because \( \{t_i\}_{i=0}^{i+1} \in T_{i,\gamma} \), \( 2t_1 - 2t_2 + \ldots - t_2 \geq 0 \). Thus, \( s_j + s_{i-j+1} \leq \gamma \). It remains to be shown that \( s_{i+1} = \gamma \). From the definition of \( s_0 \), it is clear that \( s_0 = 0 \). We have that

\[
\begin{align*}
s_{i+1} &= s_i + t_1 \\
&= s_{i-1} + t_3 - t_2 + t_1 \\
&= s_{i-2} + t_5 - t_4 + t_3 - t_2 + t_1 \\
&\vdots \\
&= s_{i} + t_{i+1} - t_i + t_{i-1} - t_{i-2} + \cdots + t_3 - t_2 + t_1.
\end{align*}
\]

We also have that

\[
\begin{align*}
s_s &= s_{i-2} + t_i - t_{i-1} \\
&= s_{i-4} + t_{i-2} - t_{i-3} + t_i - t_{i-1} \\
&\vdots \\
&= -t_1 + t_2 - t_3 + \cdots + t_{i-2} - t_{i-3} + t_i - t_{i-1}.
\end{align*}
\]

Thus, \( s_{i+1} = t_{i+1} \). Since \( t_{i+1} = \gamma \) by hypothesis, it follows that \( s_{i+1} = \gamma \).

Suppose now that \( i \) is odd. For \( j \in \{0, 1, \ldots, \frac{i+1}{2}\} \), define \( s_j \) as above. For \( j \in \{0, 1, \ldots, \frac{i-1}{2}\} \), define \( s_{i-j+1} \) as above. The proof then proceeds as in the case of \( i \) even.

We thus obtain a well-defined map \( g \) from \( T_{i,\gamma} \) to \( S_{i,\gamma} \): if \( \{t_i\}_{i=0}^{i+1} \in T_{i,\gamma} \), let \( g(\{t_i\}_{i=0}^{i+1}) = \{s_i\}_{i=0}^{i+1} \), where each \( s_i \) is defined via the equations above. It follows immediately from the definition of the \( s_i \) that \( g \) is injective. Thus, \( |S_{i,\gamma}| = |T_{i,\gamma}|. \)

We need one more technical lemma before computing the upper bound:

**Lemma 5.2** Let \( \gamma \) be a positive integer. Then, \( \prod_{1 \leq i \leq j \leq \gamma} \frac{2+i+j}{i+j} = \frac{1}{\gamma+2} \left( \frac{2(\gamma+1)}{\gamma+1} \right) \).

**Proof:** The proof is by induction. The claim is clearly true if \( \gamma = 1 \). Suppose that \( \prod_{1 \leq i \leq j \leq \gamma} \frac{2+i+j}{i+j} = \frac{1}{\gamma+2} \left( \frac{2(\gamma+1)}{\gamma+1} \right) \) for some \( \gamma \geq 1 \). Then,

\[
\begin{align*}
\prod_{1 \leq i \leq j \leq \gamma+1} \frac{2+i+j}{i+j} &= \prod_{1 \leq i \leq j \leq \gamma} \frac{2+i+j}{i+j} \prod_{1 \leq i \leq \gamma+1} \frac{i+\gamma+3}{i+\gamma+1} \\
&= \frac{1}{\gamma+2} \left( \frac{2(\gamma+1)}{\gamma+1} \right) \left( \frac{2(\gamma+2)}{\gamma+3} \right) \cdots \left( \frac{2(\gamma+3)}{\gamma+4} \right) \\
&\cdot \left( \frac{(\gamma+1)(\gamma+2)}{(\gamma+3)(\gamma+4)} \right) \cdots \left( \frac{(\gamma+2)(\gamma+3)}{(\gamma+3)(\gamma+4)} \right) \\
&\cdot \left( \frac{1}{\gamma+3} \right) \left( \frac{2(\gamma+4)}{\gamma+2} \right) = \frac{1}{\gamma+2} \left( \frac{2((\gamma+1)+1)}{(\gamma+1)+1} \right).
\end{align*}
\]

This proves the claim. \( \square \)

We are now ready to prove the main result of this section:
Theorem 5.3 Let $\gamma \in \mathbb{N}$. Let $C_\gamma$ denote the $\gamma$th Catalan number: $C_\gamma := \frac{1}{\gamma + 1} \binom{2\gamma}{\gamma}$. Let $\mathbb{F}$ be a finite field such that $|\mathbb{F}| > \frac{1}{2} (C_{\gamma-1} + \left\lfloor \frac{\gamma - 1}{2} \right\rfloor)$. Then, there exists a $\gamma \times \gamma$ superregular matrix over $\mathbb{F}$.

Proof: We first upper bound the number of submatrices of a $\gamma \times \gamma$ lower triangular Toeplitz matrix that possess a certain property and show that this upper bound is given by the expression in the statement of the theorem. We then observe that the number thus obtained is actually an upper bound on the minimal size a finite field $\mathbb{F}$ must have in order that a $\gamma \times \gamma$ superregular matrix over $\mathbb{F}$ can exist.

For convenience, we drop the matrix entries with index 0. Thus, a $\gamma \times \gamma$ lower triangular Toeplitz matrix $X$ with indeterminate entries is now defined by a first column of the form

$$[x_1 \ x_2 \ \cdots \ x_\gamma]^T.$$ 

The determinants of the proper square submatrices of such a matrix are given by nonzero polynomials in these indeterminates. Notice that $x_\gamma$ can appear to at most the first power in any of these polynomials; in other words, each of these polynomials has the property that either it is linear in $x_\gamma$, or $x_\gamma$ does not appear in any of its terms. We are interested in those proper square submatrices whose determinants are linear in $x_\gamma$, and we denote the set of such submatrices by $L_\gamma$.

First, we observe that $L_\gamma$ consists of the single entry $x_\gamma = X_1^\gamma$ and the submatrices $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$, where $s \in \{2, \ldots, \gamma - 1\}$, and where $j_\nu \leq i_\nu$ for all $\nu \in \{1,2,\ldots,s-1\}$. That $X_1^\gamma$ is the only $1 \times 1$ submatrix in $L_\gamma$ is obvious; to see the second part, evaluate $\det X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ by doing a cofactor expansion along the first column of $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$. The indeterminate $x_\gamma$ appears if and only if $\det X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma} \neq 0$. This is the case if and only if $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ is a proper submatrix, and $X_{1,j_1,j_2,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ is a proper submatrix if and only if only if $j_\nu \leq i_\nu$ for all $\nu \in \{1,2,\ldots,s-1\}$.

Next, we observe that $L_\gamma$ is closed with respect to transpose about the antidiagonal of $X$. In order to see this, note that the transpose $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ of any submatrix $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ about the antidiagonal is given by $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma} = X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$. Clearly, $\gamma - j_\nu + 1 \leq \gamma - i_\nu + 1 \iff j_\nu \leq i_\nu$. Of course, $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma} \in L_\gamma$ is symmetric with respect to the antidiagonal of $X$ if and only if $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma} = X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$. Let $L_\gamma \subset L_\gamma$ denote those elements of $L_\gamma$ that are symmetric with respect to the antidiagonal.

Finally, because $X$ is symmetric with respect to the antidiagonal, taking the transpose $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ of a square submatrix $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ about the antidiagonal of $X$ amounts to taking the transpose of $X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$ about its own antidiagonal. Since the determinant of a matrix is the same as the determinant of its transpose about its antidiagonal, we have that $\det X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma} = \det X_{1,j_1,...,j_s}^{i_1,i_2,...,i_{s-1},\gamma}$.

By definition, the determinants of the elements of $L_\gamma$ are polynomials linear in $x_\gamma$. We wish to determine how large a finite field must be in order to guarantee that nonzero field elements may be substituted for $x_1, x_2, \ldots, x_\gamma$ in such a way that none of these determinants
is zero. We do this by computing an upper bound \( N_\gamma \) on the number of distinct polynomials giving the determinants of the elements of \( L_\gamma \). As long as the order of the field is bigger than \( N_\gamma \), it is clearly possible to make all of these determinants nonzero. From the above observations, we see that, once we have computed \( |L_\gamma| \) and \( |L'_\gamma| \), we may take as an upper bound \( N_\gamma := \frac{1}{2}(|L_\gamma| + |L'_\gamma|) \).

As seen above, the \( s \times s \) submatrices in \( L_\gamma \), \( s \in \{2, \ldots, \gamma - 1\} \), are described by sets \( \{i_1, i_2, \ldots, i_{s-1}, j_1, j_2, \ldots, j_{s-1}\} \) of indices, where \( j_\nu \leq i_\nu \) for all \( \nu \in \{1, 2, \ldots, s-1\} \), \( 1 < i_1 < \ldots < i_{s-1} \leq \gamma \), and \( 1 < j_1 \ldots < j_{s-1} \leq \gamma \) (and the \( 1 \times 1 \) submatrix \( x_\gamma \) is associated with an empty set of indices). Each nonempty index set defines a generalized Young tableau with columns having height \( 2 \) and integer entries in \( \{2, \ldots, \gamma - 1\} \); conversely, the entries of such a tableau constitute a set of indices corresponding to a submatrix in \( L_\gamma \). The empty set of indices corresponds to a tableau with all columns having height \( 0 \). In \( [2] \), it is shown that the number of such tableaux is given by \( \prod_{1 \leq i \leq j \leq \gamma} \frac{2+i+j}{i+j} \). By Lemma 6.2, this product is \( C_{\gamma-1} \). Consequently, \( |L_\gamma| = C_{\gamma-1} \).

We compute \( |L'_\gamma| \) as follows. If the submatrix \( X_{i_1,j_1,\ldots,i_{s-1},j_{s-1}} \in L'_\gamma \), then, \( X_{i_1,j_1,\ldots,i_{s-1},j_{s-1}} = X_{i_1,j_1,\ldots,i_{s-1},j_{s-1}} \), it must be that \( \gamma - i_\nu = j_{s-\nu} - 1 \) for all \( \nu \in \{1, 2, \ldots, s-1\} \). Thus, this submatrix is completely determined by the \( s - 1 \) integers \( w_1 = j_1 - 1, w_2 = j_2 - 1, \ldots, w_{s-1} = j_{s-1} - 1 \). Since \( X_{i_1,j_1,\ldots,i_{s-1},j_{s-1}} \in L_\gamma \), we have \( j_l = w_l + 1 \leq \gamma - w_{s-l} = \nu, l \in \{1, 2, \ldots, \left\lfloor \frac{s-1}{2} \right\rfloor \} \). These inequalities can be rewritten as \( w_l + w_{s-l-1} \leq \gamma - 1, l \in \{1, 2, \ldots, \left\lfloor \frac{s-1}{2} \right\rfloor \} \). In other words, \( \{0, w_1, \ldots, w_{s-1}, \gamma - 1\} \) is a sequence that belongs to \( S_{s-1,\gamma-1} \). Thus, to each \( s \times s \) submatrix in \( L'_\gamma \), where \( s \in \{2, \ldots, \gamma - 1\} \), we have associated a unique sequence in \( S_{s-1,\gamma-1} \). Similarly, to each sequence in \( S_{s-1,\gamma-1} \), we can associate a unique \( s \times s \) submatrix in \( L'_\gamma \). If \( s = 1 \), there is only the submatrix \( X_1 \) to consider, and we have already associated this submatrix with the empty sequence, which in turn corresponds with the sequence \( \{0, \gamma - 1\} \), the sole member of \( S_{0,\gamma-1} \). Thus, \( |L'_1| = \sum_{y=0}^{\gamma-2} |S_{y,\gamma-1}| \). From Lemma 5.1, we know that \( \sum_{y=0}^{\gamma-2} |S_{y,\gamma-1}| = \sum_{y=0}^{\gamma-2} |T_{y,\gamma-1}| \). It is sufficient, then, to compute \( \sum_{y=0}^{\gamma-2} |T_{y,\gamma-1}| \).

Suppose \( \{t_i\}_{l=0}^s \in T_{s-1,\gamma-1} \). To this sequence, we can associate a nonnegative planar walk of length \( \gamma - 1 \) with \( s + 1 \) vertices. The walk begins at the origin, and steps are given by the vectors \((1, 1)\) and \((1, -1)\). The vertices are the origin, the endpoint of the walk, and the points where the direction of the walk changes from up to down or from down to up. We make the association in the following way: let \( t_i \) be the \( x \)-coordinate of the \( i \)-th vertex. It is clear that this walk is nonnegative, as the condition defining membership in \( T_{s-1,\gamma-1} \) guarantees nonnegativity of the associated walk. Conversely, the \( x \)-coordinates of the \( s + 1 \) vertices in a nonnegative planar walk of length \( \gamma - 1 \) form a sequence in \( T_{s-1,\gamma-1} \). Therefore, this association gives a bijective correspondence between sequences in \( \bigcup_{y=0}^{\gamma-2} T_{y,\gamma-1} \) and nonnegative planar walks of length \( \gamma - 1 \). It is a fact (see, for example, [3]) that the number of nonnegative planar walks of length \( \gamma - 1 \) is given by \( (\frac{\gamma-1}{2}) \). This means that \( \sum_{y=0}^{\gamma-2} |T_{y,\gamma-1}| = (\frac{\gamma-1}{2}) \). Consequently, \( |L'_\gamma| = (\frac{\gamma-1}{2}) \).
It remains to show that, in fact, a field of order bigger than \( N\gamma \) elements is large enough so that a superregular \( \gamma \times \gamma \) matrix can exist over it. This may be easily seen in the following way: the determinant of each submatrix in \( S_l, l \in \{1, \ldots, \gamma\} \), is linear in \( x_l \). \( N_l \) increases with \( l \). Thus, if we work over a field of order bigger than \( N\gamma \) elements, it is possible to successively substitute nonzero field elements for \( x_1, x_2, \ldots, x_\gamma \) in such a way that the determinant of each submatrix in \( S_l, l \in \{1, \ldots, \gamma\} \), is nonzero. This completes the proof. \( \square \)

Using computer searches, we were able to determine the exact minimum field size for small values of \( \gamma \). These may be seen in Table 1. We observe that the upper bound \( N\gamma + 1 \) appears to grow much more quickly than necessary:

| \( \gamma \) | Minimum Field Size Required | Upper Bound (\( N\gamma +1 \)) |
|------------|-----------------------------|----------------------------------|
| 3          | 3                           | 3                               |
| 4          | 5                           | 5                               |
| 5          | 7                           | 11                              |
| 6          | 11                          | 27                              |
| 7          | 17                          | 77                              |
| 8          | 31                          | 233                             |
| 9          | 59                          | 751                             |
| 10         | \( \leq 127 \)              | 2495                            |

Table 1: Comparison of Actual Required Field Size and \( N\gamma + 1 \)

It is still an open problem as to how this bound may be refined. Computer searches lead us to make the following conjecture; if true, it would offer a significant improvement to the bound given here:

**Conjecture 5.4** For \( \gamma \geq 5 \), there exists a \( \gamma \times \gamma \) superregular matrix over the field \( \mathbb{F}_{2^{\gamma-2}} \).

### 6 For Future Research: Finding a Construction

At this point, little is understood about how to construct superregular matrices. The problem of finding constructions appears to be a very hard one. One must find a way of guaranteeing that all proper submatrices with any number of zeroes above the diagonal have a nonzero determinant and do so with additional constraints coming from the Toeplitz structure. In [20], a method is given for constructing, for any prime number \( p \), a triangular Toeplitz array of dimension \( p \) having the property that all full square submatrices have a nonzero determinant. Unfortunately, there is no way of extending this construction to the much more general situation we consider here.

In [21], the following result is proven:
**Theorem 6.1** Let \( X \) be the \( \gamma \times \gamma \) matrix given by

\[
X := \begin{bmatrix}
1 & 0 & \cdots & \cdots & \cdots & 0 \\
1 & 1 & \ddots & \cdots & \vdots & \\
0 & 1 & 1 & \ddots & \vdots & \\
\vdots & \ddots & \ddots & \ddots & \ddots & \\
\vdots & \ddots & 1 & 1 & 0 & \\
0 & \cdots & \cdots & 0 & 1 & 1
\end{bmatrix},
\]

Then,

\[
X^{\gamma-1} = \begin{bmatrix}
1 & 0 & \cdots & \cdots & \cdots & 0 \\
(\gamma^{-1})_1 & 1 & \ddots & \cdots & \vdots & \\
(\gamma^{-1})_2 & (\gamma^{-1})_1 & 1 & \ddots & \vdots & \\
\vdots & \ddots & \ddots & \ddots & \ddots & \\
\vdots & \ddots & \ddots & \ddots & \ddots & \\
1 & (\gamma^{-1})_{\gamma-2} & \cdots & (\gamma^{-1})_{\gamma-3} & (\gamma^{-1})_1 & 0 \\
(\gamma^{-1})_{\gamma-3} & (\gamma^{-1})_{\gamma-4} & \cdots & (\gamma^{-1})_{\gamma-5} & (\gamma^{-1})_1 & 1
\end{bmatrix},
\]

where \( (\gamma)_{(\omega)} = \frac{\gamma!}{\omega!(\gamma-\omega)!} \), is totally positive over the real numbers. Thus, for a sufficiently large prime number \( p \), taking the entries of this matrix modulo \( p \) gives a superregular matrix.

This result gives a construction insofar as one knows that, modulo a large enough prime number, the matrix \( X^{\gamma-1} \) is superregular. It is not clear, however, how one may give a good bound as to how large \( p \) must be for a given \( \gamma \).

**References**

[1] A. Antoulas, On Recursiveness and Related Topics in Linear Systems. *IEEE Trans. Automat. Contr.*, AC-31(12): 1121–1135 (1986).

[2] M. Desainte-Catherine and G. Viennot, Enumeration of Certain Young Tableaux with Bounded Height. In *Lecture Notes in Mathematics*, volume Vol. 1234, pages 58–67, Springer, Berlin (1986).

[3] W. Feller, *An Introduction to Probability Theory and its Applications, 3rd Edition*. Wiley, New York (1950).

[4] G. Forney, Jr., Minimal Bases of Rational Vector Spaces, with Applications to Multi-variable Linear Systems. *SIAM J. Control*, 13(3): 493–520 (1975).

[5] H. Gluesing-Luerssen, On the Weight Distribution of Convolutional Codes. *Linear Algebra and its Applications*, 408: 298–326 (2005).
[6] H. Gluesing-Luerssen and B. Langfeld, A Class of One-Dimensional MDS Convolutional Codes. *Journal of Algebra and its Applications*, To appear.

[7] H. Gluesing-Luerssen and B. Langfeld, On the Algebraic Parameters of Convolutional Codes with Cyclic Structure. *Journal of Algebra and its Applications*, To appear.

[8] H. Gluesing-Luerssen and B. Langfeld, On the Algebraic Parameters of Convolutional Codes with Cyclic Structures. *Journal of Algebra and its Applications*, 5(1): 53–76 (2006).

[9] H. Gluesing-Luerssen, J. Rosenthal and R. Smarandache, Strongly MDS Convolutional Codes. *IEEE Trans. Inform. Theory*, 52(2): 584–598 (2006).

[10] H. Gluesing-Luerssen and W. Schmale, On Doubly-Cyclic Convolutional Codes. *Appl. Algebra Engrg. Comm. Comput.*, To appear.

[11] H. Gluesing-Luerssen and W. Schmale, On Cyclic Convolutional Codes. *Acta Appl. Math.*, 82: 183–237 (2004).

[12] H. Gluesing-Luerssen and G. Schneider, On the MacWilliams Identity for Convolutional Codes (2006), Available at http://www.math.rug.nl/~gluesing/Publ.html.

[13] R. Hutchinson, J. Rosenthal and R. Smarandache, Maximum Distance Profile Convolutional Codes. *Systems and Control Letters*, 54(1): 53–63 (2004).

[14] R. Johannesson and K. Zigangirov, *Fundamentals of Convolutional Coding*. IEEE Press, New York (1999).

[15] B. Langfeld, *Minimal Cyclic Convolutional Codes*. Master’s thesis, University of Oldenburg (2003), Available at http://www-m9.ma.tum.de/dm/homepages/langfeld/thesis.pdf.

[16] S. Lin and D. Costello, Jr., *Error Control Coding: Fundamentals and Applications*. Prentice-Hall, Englewood Cliffs, N.J. (2004).

[17] R. McEliece, The Algebraic Theory of Convolutional Codes. In V. Pless and W. Huffman, editors, *Handbook of Coding Theory*, volume 1, pages 1065–1138, Elsevier Science Publishers, Amsterdam, The Netherlands (1998).

[18] J. Rosenthal and R. Smarandache, Maximum Distance Separable Convolutional Codes. *Appl. Algebra Engrg. Comm. Comput.*, 10(1): 15–32 (1999).

[19] J. Rosenthal and E. York, BCH Convolutional Codes. *IEEE Trans. Inform. Theory*, 45(6): 1833–1844 (1999).

[20] R. Roth and G. Seroussi, On Generator Matrices of MDS Codes. *IEEE Trans. Inform. Theory*, 31(6): 826–831 (1985).
[21] R. Smarandache, H. Gluesing-Luerssen and J. Rosenthal, Constructions of MDS-Convolutional Codes. *IEEE Trans. Inform. Theory*, 47(5): 2045–2049 (2001).