CLASSIFICATION
OF ALMOST QUARTER-PINCHED MANIFOLDS

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Abstract. We show that if a simply connected manifold is almost quarter-
pinched, then it is diffeomorphic to a CROSS or a sphere.

1. Introduction

The goal of this paper is to use the new results of Brendle and Schoen in [5], [6] to
sharpen some older results about almost quarter-pinched manifolds studied by
Berger and Abresch-Meyer in [3], [2]. The main goal is to show that there can’t be
exotic spheres which are almost quarter-pinched. More precisely, we prove

Theorem 1.1. There exist ε(n) > 0 so that any simply connected n-dimensional
Riemannian manifold (M, g) with sectional curvatures in [1/4 − ε, 1] is diffeomorphic
to a sphere or a compact rank one symmetric space (CROSS).

In [3], Berger established this result in even dimensions, but with the weaker con-
clusion that M was either homeomorphic to a sphere or diffeomorphic to a CROSS
(see also [9] for other results in this direction). To prove his result, Berger consid-
ered a sequence of almost quarter-pinched manifolds; then using Cheeger-Gromov
compactness theory, he passed to a limit that was weakly quarter-pinched in the
sense of comparison theory. It does not seem that a similar strategy would work
for Theorem 1.1; the difficulty is that there is no obvious way to use comparison
curvatures to get information about isotropic curvatures on manifolds that only
have weakly defined curvature tensors. Instead we apply the Ricci flow to each of
the manifolds in the sequence and show that in the limit we get a Ricci flow, where
we have nice metrics for positive time. These are not necessarily quarter-pinched
(as this property is not preserved by Ricci flow), but they do have nonnegative
isotropic curvatures when we add a factor of R^2 to the metric. Thus we can use
the classification in [6] to understand what the candidates for limit manifolds are.
Finally it is worth mentioning that there is at least one example of an exotic sphere
with positive sectional curvature (see [14]).

All results in Riemannian geometry which are not specifically referenced can be
found in [13] and similarly for results on the Ricci Flow in [7] and [8].
2. Proof of Theorem 1.1

Assume by contradiction that Theorem 1.1 failed in some fixed dimension \( n \). Then one could find a sequence of simply connected \( n \)-dimensional Riemannian manifolds \( (M_i, g_i) \) such that \( 1/4 - 1/i \leq \sec \leq 1 \), and such that none of the \( M_i \) were diffeomorphic to a sphere or a CROSS.

In even dimensions it is a classical result of Klingenberg that such manifolds have injectivity radius \( \geq \pi \). In odd dimensions this is far more subtle and was settled by Abresch and Meyer in [1]. The fact that there is a uniform lower bound for the sectional curvature shows that the diameter is also bounded, by Myers’ theorem. Finally, the sectional curvature bounds imply that the curvature tensors of \( g_i \) are uniformly bounded. By the standard local existence theory for Ricci flow ([10], [11], and [7]), we can thus run the Ricci flow for a fixed amount of time \([0, t_0] \) for each of these metrics \((M_i, g_i)\), with the curvature tensor uniformly bounded in \( i \) on this time interval.

Putting all this together, we obtain a family of Ricci flows \((M_i, g_i(t), t \in [0, t_0])\) with uniformly bounded geometry. Hamilton’s extension of the Cheeger-Gromov compactness theorem then guarantees us that some subsequence converges to a Ricci flow \((M, \bar{g}(t), t \in [0, t_0])\) ([12] and [8]); the convergence is only in the \( C^{1,\alpha} \), \( \alpha < 1 \) sense at time \( t = 0 \), but is in the \( C^\infty \) sense for \( 0 < t \leq t_0 \).

We cannot expect \( \bar{g}(t) \) to be quarter-pinched for \( t > 0 \), and when \( t = 0 \) the metric isn’t sufficiently smooth that this makes sense. However, for small \( t \) the metrics \( g_i(t) \) have sectional curvature \( \geq 1/4 - 1/i - C(n) \) \( t \) for an absolute constant \( C > 0 \) (see [15], Proposition 2.5)). As the metrics \( g_i(t) \) converge in the \( C^\infty \) topology for \( t > 0 \) we see that \( g(t) \) has positive sectional curvature for \( t > 0 \). This shows that the metric is irreducible. Below we will show that the product metric on \( M \times \mathbb{R}^2 \) has nonnegative isotropic curvature for \( t > 0 \). The Brendle-Schoen classification (see [6], Theorem 2]) of such metrics then shows that \( M \) and hence \( M_i \) (for sufficiently large \( i \)) are diffeomorphic to a sphere or compact rank one symmetric space, giving the required contradiction.

In Brendle-Schoen [6] the authors show that a quarter-pinched metric also has isotropic curvature even after the metric has been multiplied with the factor \( \mathbb{R}^2 \). The proof is entirely algebraic and also shows that if the metric is almost quarter-pinched, then there is a small lower bound for the isotropic curvatures, again even after we have added the \( \mathbb{R}^2 \) factor. Thus the metrics \((M_i, g_i(0))\) have a lower bound \( -\varepsilon_i \) for the isotropic curvatures on \( M_i \times \mathbb{R}^2 \), where \( \varepsilon_i \to 0 \) as \( i \to \infty \). (The \( \varepsilon_i \) can in fact be taken to be a multiple of \( \frac{1}{i} \), but this is not important for the proof.)

Finally we need to estimate the lower bound for the isotropic curvatures of \( g_i(t) \) on \( M_i \times \mathbb{R}^2 \). It is a general fact that they will be bounded from below by \( -\varepsilon_i \exp(Ct) \), where \( C \) is a constant that depends only on the curvature bounds for \( g_i(0) \). This was established by Hamilton in the proof of [11], Theorem 4.3] as a general property of solutions to heat flows. Specifically consider a heat flow

\[ \partial_t T = \Delta T + \phi(T) \]

on tensors \( T \) and a continuous, compact, and convex condition \( X \) on the tensors \( T \) that is also invariant under the natural \( O(n) \) action induced on tensors and future invariants under the ODE \( \partial_t T = \phi(T) \). Hamilton shows that \( X \) is then also invariant under the heat flow by showing that if a solution to the heat flow starts out at some distant \( \varepsilon > 0 \) from \( X \), then at time \( t \) it will be at most distance
$\varepsilon \exp(Ct)$ away from $X$. Here $C$ depends on the set $X$ and $\phi$. The condition $X$ is rarely compact in applications, but this can easily be finessed by modifying the PDE and ODE, as we shall now discuss. In our situation we are considering the evolution of the curvature tensor

$$\partial_t R = \Delta R + R^2 + R^\#$$

under the Ricci flow. Initially the curvature tensor is bounded by some fixed constant $K_1$ that depends only on pinching constants and dimension. This shows that the flow exists on some fixed time interval $[0,t_0]$ and that the curvature tensors are bounded by some other controlled constant $K_2$ on this interval. If we have a continuous, convex, $O(n)$, and future ODE invariant condition $X$, then we can intersect it with the compact, convex, and $O(n)$ invariant set: $|R| \leq K$, where $K > K_2$. Next we modify the vector field $\phi(R) = R^2 + R^\#$ outside the region $|R| \leq K_2$ to make the new condition invariant under the ODE $\partial_t R = R^2 + R^\#$. As long as we only consider initial conditions where the curvature is bounded by $K_1$ the solutions will not be affected by these changes.

Finally we can now use that for $t > 0$ the metrics $g_i(t)$ converge to $g(t)$ in the $C^\infty$ topology to see that the limit metrics $g(t)$ have nonnegative isotropic curvatures on $M \times \mathbb{R}^2$, as desired. The proof of Theorem 1.1 is now complete.

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