Channel Path-Loss Measurement and Modeling in Wireless Data Network (IEEE 802.11n) Using Artificial Neural Network

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Abstract—Careful network planning has become increasingly critical with the rising deployment, coverage, and congestion of wireless local area networks (WLANs). This paper investigates and determine the Path-loss exponent value for the ubiquitous wireless local area network at the Federal University Oye-Ekiti for the line of sight and non-line of sight (N-LOS). Aside this, the paper also models the wireless network using artificial neural network (ANN) technology by training some neurons based on data collected from a drive-test.

The proposed ANN model performed with accuracy and is offered as a simple, yet strong predictive model for network planning – having both speed and accuracy. Results show, that for the area under study, Oye Campus has a higher standard deviation of 5.76dBm as against ikole Campus with 1.44dBm, this is because of dense vegetation at Oye Campus.

In view of this, the paper provides a predictive site survey for rapid wireless Access point deployment.

Index Terms—Artificial Neural Network, N-LOS, Path Loss, Propagation Model.

I. INTRODUCTION

Path Loss is difference in dB between transmitted signal and received signal strength at a location. Network Engineers mostly used path loss model as a mathematical tool to determine received signal strength at a given point. The problem of predicting propagation loss between two points may be seen as a function of several inputs and a single output. The inputs contain information about the transmitter and receiver locations, surrounding buildings, frequency, etc. while the output gives the propagation loss for those inputs. From this point of view, research in propagation loss modeling consists of finding both the inputs and the function that best approximate the propagation loss. The various models that have been proposed can be classified as empirical or deterministic models. Empirical models like ITU, TGN, SUI and Okumura-Hata[12]-[13], [17], [20] are based on received signal measurement within a given environment. The Empirical models are computationally efficient but may not be very accurate in different environment. Deterministic models like geometric theory of wave, ray-tracing [8][9] technology is very accurate but requires extensive computational time and detailed information of the environment.

The introduction of Machine learning techniques has helped in solving complex problems in our everyday life, this can be exploited for path loss predictions in given propagation environments. Artificial Neural Network (ANN) is an adaptive statistical tool that models the biological nervous system to solve regression problems. The capability of ANNs to model complex nonlinear functional relationships provides an opportunity to combine the gains of empirical and deterministic models and also to provide better computational efficiency. ANN has high processing speed and can process large volume of data, has the flexibility to adapt to different environments and can be trained to perform well in environments similar to where the training data are collected. The basic features of the ANN are for it to be able to create its own internal model of behavior of radio waves by observing the measured data, measured data have inherent behavior of the network from where it was collected, as such the measured data are needed for the creation of ANN model. The feed-forward neural networks [4], [5] are very well suited for prediction purposes because they do not allow any feedback from the output (field strength or path loss) to the input. ANN can be used to model the mathematical function of Pathloss of a given environment.

II. RELATED LITERATURE

A. Stanford University Interim (SUI) Model [2], [21]

The 802.16 IEEE group, jointly with the Stanford University, carried out an extensive work with the aim to develop a channel model for WiMAX applications in suburban environments. The model is formulated to operate based on an operating frequency above 1900MHz and a cell radius of 0.1km to 8km, base station antenna height 10m to 80m, and receiver antenna height of 1m to 10m. This model is divided into three categories of terrains namely A, B, C. The terrain category A is associated with maximum path loss, and densely populated region. Moderate path loss is captured in terrain category B. The terrain category C is associated with minimum path loss and flat terrain with light tree densities.

The basic path loss expression of The SUI model with correction factors is presented as:

\[
PL = A + 10\log_{10}\left(\frac{d}{d_0}\right) + X_f + X_h + s \quad d > d_0 \quad (1)
\]

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where \( d \) is the distance between BS and receiving antenna (m), \( d_o \) is the reference distance 100 (m), \( X_f \) is the frequency correction factor for frequency above 2 GHz, \( X_h \) is the correction factor for receiving antenna height (m), \( s \) is the correction for shadowing (dB), and \( \gamma \) is the path loss exponent. The random variables are taken through a statistical procedure as the path loss exponent \( \gamma \) and the weak fading standard deviation \( s \) is defined. The log normally distributed factors, for shadow fading because of trees and other clutter on a propagations path and its value is between 8.2 dB and 10.6 dB.

The parameter \( A \) is defined as:

\[
A = 20 \log_{10} \left( \frac{\text{nda}}{\lambda} \right)
\]  

(2)

The frequency correction factor \( X_f \) and the correction for receiver antenna height \( X_h \) for the model are expressed in:

\[
X_f = 6.0 \log_{10} \left( \frac{f}{2000} \right)
\]  

(3)

For terrain type A and B

\[
X_h = -10.8 \log_{10} \left( \frac{h_r}{2000} \right)
\]  

(4)

for terrain type C

\[
X_h = -20 \log_{10} \left( \frac{h_r}{2000} \right)
\]  

(5)

Where \( f \) is the operating frequency (MHz), \( h_r \) is the receiver antenna height (m).

For the above correction factors this model is extensively used for the path loss prediction of all three types of terrain in rural, urban and suburban environments.

B. IEEE 802.11 TGn channel model

The TGn channel model was conceived for systems with 4x4 MIMO, and are based on the Kronecker channel correlation model assumption. According to the IEEE 802.11 TGn channel model, the PL can be modeled by the free space PL for \( d < d_o \), and by a one-slope model with exponent 3.5 for \( d > d_o \). The TGn model predicts a breakpoint of 5m for ‘Small environment’ (type of environment ‘C’) and a breakpoint of 10m for ‘Large environment’ (type of environment ‘D’).

\[
\text{PL}(d) = \text{PL}_\text{LOS}(d) \quad d \leq d_o
\]  

(6)

\[
\text{PL}(d) = \text{PL}_\text{LOS}(d_o) + 35 \log_{10} \left( \frac{d}{d_o} \right) \quad d > d_o
\]  

(7)

where \( d \) is the transmit-receive separation distance in m, the standard deviations of log-normal (Gaussian in dB) shadow fading were found to be in the 3-14 dB range.

\[
\text{PL}_\text{LOS}(d) = \text{Free path loss}
\]

C. COST 231 Walfish-Ikegami (W-I) Model \([17],[20],[15]\)

This model is a combination of J. Walfish and F. Ikegami models. This model is considered as the most appropriate model for rural and suburban environments which have regular building height. Among other models like the Hata model, COST 231 W-I model gives a more precise path loss. This is as a result of the additional parameters introduced which characterized the different environments. It distinguishes different terrain with different proposed parameters. The equation of the proposed model is expressed in:

For LOS condition

\[
PL_{\text{LOS}} = 42.6 + 26 \log_{10}(d) + 20 \log_{10}(f)
\]  

(8)

And for NLOS condition

\[
PL_{\text{NLOS}} = \begin{cases} 
L_{\text{fsl}} + L_{\text{rts}} + L_{\text{msd}}, & \text{for urban and suburban} \\
L_{\text{fsl}}, & L_{\text{rts}} + L_{\text{msd}} < 0
\end{cases}
\]  

(9)

\[
L_{\text{fsl}} = 32.45 + 20 \log_{10}(d) + 20 \log_{10}(f)
\]  

is the free space loss

\[
L_{\text{rts}} \text{ is the roof top to street diffraction}
\]

\[
L_{\text{msd}} \text{ is the multi-screen diffraction loss}
\]

![Fig. 1. Diffraction angle and urban scenario \([15]\)](http://dx.doi.org/10.24018/ejece.2020.4.1.157)

\[
L_{\text{rts}} = \begin{cases} 
-16.9 - 10 \log_{10}(w) + 10 \log_{10}(f) + 20 \log_{10}(D) + L_{\text{ort}}, & h_{\text{roof}} > h_{\text{m}} \\
0, & 0 \leq 0 < 35
\end{cases}
\]  

(10)

where

\[
L_{\text{ort}} = \begin{cases} 
-10 + 0.3540, & 0 \leq 0 < 35 \\
2.5 + 0.075(0 - 35), & 35 \leq 0 < 55 \\
4 - 0.114(0 - 55), & 55 \leq 0 < 90
\end{cases}
\]  

(11)

Note that

\[
\Delta h_{\text{m}} = h_{\text{roof}} - h_{\text{m}} \Delta h_{\text{base}} = h_{\text{base}} - h_{\text{roof}}
\]  

(12)

The multi-screen diffraction loss is

\[
L_{\text{msd}} = L_{\text{bsh}} + K_a \log_{10}(d) + K_f \log_{10}(f) - 9 \log_{10}(\lambda) - 9 \log_{10}a
\]  

(13)

\[
L_{\text{bsh}} = \begin{cases} 
18 \log_{10}(1 + \Delta h_{\text{base}}), & h_{\text{base}} > h_{\text{roof}} \\
0, & h_{\text{base}} \leq h_{\text{roof}}
\end{cases}
\]  

(14)

\[
K_a = \begin{cases} 
54 - 0.8 \Delta h_{\text{base}}, & d \geq 0.5 \text{ and } h_{\text{base}} \leq h_{\text{roof}} \\
54 - 0.8 \Delta h_{\text{base}}(d/0.5), & d < 0.5 \text{ and } h_{\text{base}} \leq h_{\text{roof}}
\end{cases}
\]  

(15)
\[ K_d = \begin{cases} 18, & h_{\text{base}} > h_{\text{roof}} \\ 18 - 15 \left( \frac{h_{\text{base}}}{n_{\text{base}}} \right), & h_{\text{base}} \leq h_{\text{roof}} \end{cases} \quad (16) \]

For suburban or medium size cities with moderate tree density

\[ K_f = -4 + 0.7 \left( \frac{f}{925} - 1 \right) \quad (17) \]

And for metropolitan – urban

\[ K_f = -4 + 1.5 \left( \frac{f}{925} - 1 \right) \quad (18) \]

where
- \( d \) is the distance between transmitter and receiver antenna (m)
- \( f \) is the frequency (GHz)
- \( B \) is the building to building distance (m)
- \( w \) is the street width (m)
- \( \theta \) is the street orientation angel with respect to direct radio path (degree)

D. ITU Model [10], [17], [19], [12]

The International Telecommunication Union Radio communication (ITU-R) is a semi empirical path loss model that can be employed in different environment comprising indoor, outdoor, vehicular and pedestrian. The applicable operational frequency is 900MHz – 6GHz and the equations for the line of sight (LOS) and non-LOS (NLLOS) path loss are;

\[ P_{\text{LOS}} = 18 \log_{10}(f_c) + N \log_{10}(d) - 28 \quad (19) \]

\[ P_{\text{NLLOS}} = 20 \log_{10}(f_c) + N \log_{10}(d) + Lf(n_w) - 28 \quad (20) \]

Where;
- \( f_c \) = carrier frequency in MHz
- \( N \) = Power Loss Coefficient
- \( d \) = Tx-Rx distance in meters
- \( Lf \) = wall penetration loss
- \( n_w \) = the number of walls

E. Calculation of distance power loss coefficient

The distance power loss coefficient, \( N \) is the quantity that expresses the loss of signal power with distance. This coefficient is an empirical one. Some values are provided in Table I.

| Frequency band | Number of floors | Residential area | Office area | Commercial area |
|----------------|------------------|------------------|-------------|-----------------|
| 900 MHz        | 1                | N/A              | 9           | N/A             |
| 1.2-1.3 GHz    | 2                | N/A              | 19          | N/A             |
| 1.8-2.0 GHz    | 3                | N/A              | 24          | N/A             |
| 4 GHz           |                  | N/A              | 16          | N/A             |
| 5.2 GHz        | 4                | 30 (apartment), 28 (house) | 15 + 4(n-1) | 6 + 3(n-1) |
| 5.8 GHz        | 5                | N/A              | 22 (1 floor), 28 (2 floors) | N/A |
| 2.0 GHz        |                  |                  |             |                 |

III. DATA COLLECTION METHOD AND ANALYSIS

Pathloss model prediction for wireless data network requires practical data from the field measurement. Received signal strength were measured at various distances from the transmitter at the ISM band frequency of 2400MHz. A drive test tools for data collection includes a laptop equipped with communication Network/Protocol Analyser (metageek insider 4 software) and GPS receiver to measure the longitude and latitude of the received signal. The average transmitted power from the transmitter is 28 dBm. Results obtained was plot in MATLAB.

Designing ANN models follows a number of systemic procedures. In general, there are five basic steps: (1) data collection, (2) data preprocessing, (3) Network Building, (4) training and (5) model performance test as shown below.

The work presented in this paper is modeled using McCulloch-Pitts model. The MATLAB [1][3][5] tools contain the Neural Network Toolbox [4] for designing, implementing, visualizing and simulating neural networks. It also provides comprehensive support for many proven network paradigms, as well as graphical user interfaces (GUIs) that enable the user to design and manage neural networks in a very simple way.

\[ Y = F(\sum_{r=1}^{r} (w_r \ast p_r + b)) \quad (21) \]

\[ p = (p_1, \ldots, p_r) \] is the input column-vector

\[ W = (w_1, \ldots, w_r) \] is the weight row-vector

\[ F \] is the transfer function

The bias \( b \) can be treated as a weight whose input is always 1.
IV. PATHLOSS MEASUREMENT AND RESULTS

The path loss measurement was taken at the Ikole and Oye campus of the Federal University Oye-Ekiti Ekiti State Nigeria. The two campuses consist of structures and foliage. The measurements were done at the ISM band frequency 2.4GHz. The transmitter used is the ZoneFlex 9.7 802.11n Outdoor Access Point [6]. The receiver equipment included a laptop, equipped with LB LINK™ BL-WN150 WLAN USB adapter card and inSSIDer Wi-Fi network scanner/protocol analyzer. The receiver was moved around the campus for the received power in dBm and the longitude/latitude position of the receiver was recorded. Haversine formula was used to calculate the distance between the transmitter and the receiver given the longitude/latitude.

This work concentrated on the received radio signal needed for the path loss analysis of the coverage area. The path loss includes signal attenuation with signal fading between the transmitter and the receiver, while the channel consists of structures and foliage. It is to be noted that while conducting the drive test other WiFi AP acted as interference to the received signal.

![Fig. 4. Google Earth view of Oye campus](image)

![Fig. 5. Google Earth view of Ikole Campus](image)

| TABLE III: AP POSITION IKOLE CAMPUS |
|-------------------------------------|
| AP NAME | LONGITUDE | LATITUDE |
|----------|------------|----------|
| MechaEng AP | 5 29' 38.20"E | 7 48' 27.65"N |
| Civil Eng AP | 5 29' 35.98"E | 7 48' 27.63"N |
| Dean Eng AP | 5 29' 37.11"E | 7 48' 26.72"N |
| Dean Agric AP | 5 29' 49.41"E | 7 48' 13.72"N |

| TABLE IV: AP POSITION OYE CAMPUS |
|-----------------------------------|
| AP NAME | LONGITUDE | LATITUDE |
|----------|------------|----------|
| ICT New AP | 5 18' 42.75"E | 7 46' 34.70"N |
| Fac of sci AP | 5 18' 55.58"E | 7 46' 37.24"N |
| Theater AP | 5 18' 59.73"E | 7 46' 35.96"N |
| Science1 AP | 5 18' 15.78"E | 7 46' 37.14"N |

The measured received power in both campuses are plotted in Fig. 6, while the path loss are plotted in Fig. 7. By observing the path loss values, it was clear that the path loss deviation has less value at Ikole campus than Oye campus, this is due to less foliage and structures at Ikole campus than Oye campus as seen in the Google Earth view map.

![Fig. 6. Measured Received Power](image)

![Fig. 7. Path Loss Using Measured Data](image)

![Fig. 8. Path Loss include one Slope Model](image)

A. Determination of Power exponent and log-normal variation

Average Transmitted power from the AP datasheet, \( P_t = 28 \text{dBm} \).
Average received power from the AP $d_0=1m$,

$$P_r = -11dBm, k = P_t - P_r = 39dBm$$ (22)

Using the one slope model to determine the power exponent $\gamma$

Let

$$M_{model}(d_i) = P_t(dBm) - P_r(dBm) = K(dBm) + 10\gamma log_{10}\left(\frac{d_i}{d_0}\right) + \psi_\sigma$$

$$\psi_\sigma = \text{zero-mean Gaussian distributed random variable (in dBm) with standard deviation } \sigma \text{ (also in dBm)}$$

Minimum mean square error (MMSE) equation for the dBm power measurements is

$$F(\gamma) = \sum_{i=1}^{n} [M_{measured}(d_i) - M_{model}(d_i)]^2$$ (24)

$$F(\gamma) = \sum_{i=1}^{n} \left[ M_{measured}(d_i) - (K(dBm) + 10\gamma log_{10}\left(\frac{d_i}{d_0}\right)) \right]^2$$

$$F(\gamma) = \sum_{i=1}^{n} \left[ M_{measured}(d_i) - K(dBm) - 10\gamma log_{10}\left(\frac{d_i}{d_0}\right) \right]^2$$ (25)

MMSE occur at

$$\frac{dF(\gamma)}{d\gamma} = 0$$

$$\gamma = \frac{\sum_{i=1}^{n}[M_{measured}(d_i) - K(dBm)]}{\sum_{i=1}^{n}[10\gamma log_{10}\left(\frac{d_i}{d_0}\right)]}$$ (26)

Ikole campus

$n=93$, $\sum_{i=1}^{n}[M_{measured}(d_i)]$=summation of PL=7681.5, $\sum_{i=1}^{n}[10\gamma log_{10}\left(\frac{d_i}{d_0}\right)] = \text{distance summation} = 1330.013$

$$\gamma = \frac{(7681.5 - 93\times39)}{1330.013} = 3.05$$

Oye campus

$n=184$, $\sum_{i=1}^{n}[M_{measured}(d_i)]$=summation of PL=15631 $\sum_{i=1}^{n}[10\gamma log_{10}\left(\frac{d_i}{d_0}\right)] = \text{distance summation} = 2756.47$

$$\gamma = \frac{(15631 - 184\times39)}{2756.47} = 3.06$$

The log-normal variation or shadow fading is giving by

$$\psi_\sigma = \frac{1}{n} \sum_{i=1}^{n} [M_{measured}(d_i) - M_{model}(d_i)]^2$$

Ikole Campus

$$\psi_\sigma = \frac{1}{n} \sum_{i=1}^{n} [M_{measured}(d_i) - M_{model}(d_i)]^2 = \frac{191.48}{93} = 2.06$$

Standard deviation $\sigma = \sqrt{\psi_\sigma} = \sqrt{2.06} = 1.44 \text{ dBm}$

Oye Campus

$$\psi_\sigma = \frac{1}{n} \sum_{i=1}^{n} [M_{measured}(d_i) - M_{model}(d_i)]^2 = \frac{6114.27}{184} = 33.23$$

Standard deviation $\sigma = \sqrt{\psi_\sigma} = \sqrt{33.23} = 5.76 \text{ dBm}$

V. ANN MODELING AND RESULTS COMPARISON WITH THE FOUR EXISTING MODELS

IEEE802.11n is a fixed wireless network, therefore the ANN model presented in this paper has the following parameters: distance between WiFi AP and the receiver, carrier frequency, height of the WiFi AP and height of the receiver. Set of path loss data recorded at distances between transmitter and receiver were used in the training of the neurons. Levenberg-Marquardt (trainlm) algorithm was used to train the network, this algorithm is generally faster than the others and very ideal for the network model. During the training phase the characteristics of the network were modified by this iterative algorithm until a minimum error is obtained, that is the error between the network (predicted) output and the desired (measured) output is minimized. Observations were made during the training process. It was observed that different results were obtained each time the network was trained. This is as a result of different initial weight and bias values, and different divisions of measured data into training, validation and test sets, thus it is possible that different artificial neural structures trained on the same problem can generate different outputs for the same input. Another observation noted was that network sensitivity depends on the number of neurons in the hidden layer. When the number is few it leads to underfitting but when the number is too many it causes overfitting, the number of hidden layers was varied during training until the desired result was obtained. To achieve the modeling of the network using McCulloch-pitts model, two hidden layer of size five (5) was obtained as the best representation of the network.

| Freq (GHz) | Locatio n | $K$ (dBm) | PL Exponent | $\sigma$ (dBm) | Tx-Rx Distance(m) |
|------------|------------|------------|-------------|---------------|------------------|
| 2.4        | Ikole      | 3.05       | 1.44        | 1-100         |                  |
| 2.4        | Oye        | 3.06       | 5.76        | 1-100         |                  |

Fig. 9. Training the ANN
The various weights and bias are given below:

\[
\text{IW}^{[1,1]}: \text{WEIGHT TO LAYER 1 FROM INPUT 1} \\
\begin{pmatrix}
-7.0587 & -8.3286 & -7.5125 & -5.7149 & 6.440
\end{pmatrix}
\]

\[
\text{IW}^{[2,1]}: \text{WEIGHT TO LAYER} \\
\begin{pmatrix}
1.4840 & -1.1689 & 1.8698 & 1.2639 & -1.3860 \\
0.6068 & -2.3206 & -0.8986 & -0.6184 & -0.9326 \\
1.4982 & 1.0294 & -0.3799 & 0.0312 & -2.1832 \\
-1.2016 & -0.5139 & 0.4895 & 2.5840 & -0.0674 \\
0.6244 & 0.4632 & 1.1968 & 0.2990 & 1.0982
\end{pmatrix}
\]

\[
\text{IW}^{[3,1]}: \text{WEIGHT TO LAYER} \\
\begin{pmatrix}
0.5657 & 0.9578 & 1.7526 & 0.2508 & 0.9772
\end{pmatrix}
\]

\[
\text{B}^{[1]}: \text{BIAS TO LAYER 1} \\
\begin{pmatrix}
6.9731 & 2.6584 & 0.6378 & -3.2609 & 7.8763
\end{pmatrix}
\]

\[
\text{B}^{[2]}: \text{BIAS TO LAYER 2} \\
\begin{pmatrix}
1.7008 & -0.7874 & 0.1788 & -1.2809 & 2.2889
\end{pmatrix}
\]

\[
\text{B}^{[3]}: \text{BIAS TO LAYER 3} \\
\begin{pmatrix}
-0.23941
\end{pmatrix}
\]

From the ANN analysis the proposed mathematical function for the wireless data network Path loss is given

\[
PL = 0.61z^2 - 0.87z^4 - 0.88z^2 - 0.76z^2 + 8.4z + A \quad (27)
\]

where

\[
A = 10^\log_{10}(\frac{\text{standard deviation}}{d}) + 24 \quad (28)
\]

\[
Z = \frac{(d-35)}{6} \quad (29)
\]

\[PL\] represent the channel modeling of the wireless data network in mathematical function, where:

\[y\] the Path Loss coefficients of the environment (3.05-3.06)
\[f_c\] ISM band frequency (2.4GHz to 2.5GHz)
\[d\] distance between the Tx and Rx

The model proposed is to be site-generic, the radio transmission loss is characterized by both an average transmission loss and its associated shadow fading statistics. The model proposed in this research accounts for the loss through multiple floors to allow for such characteristics as frequency reuse between floors. The distance power loss coefficients include an implicit allowance for transmission through walls and over and through obstacles, and for other loss mechanisms likely to be encountered within a single floor of a building.

VI. DISCUSSION

From Fig. 11, the proposed ANN model matches closer with the average drive test data as compared to other models, the zero-mean Gaussian distribution is within the range of 2.06-33.32 dBm, while standard deviation ranges from 1.44dBm to 5.76dBm and the path loss exponent ranges from 3.05-3.06. It was observed from Fig 11 that the ITU model has the highest value of Path loss at 2400 MHz. compared to other models in the same environment, this is as a result of the floor penetration loss factor given in Table V for the number of floors between Access Point and the receiver. It was also observed that at a distance less than 70m the pathloss is approximately linearly depends on the distance, above 70m fading and signal attenuation drastically affect the Pathloss. This result shows that for a good signal connection in wireless data connection distance between Tx and Rx should be less than 70m. From this observation, it could be concluded that the ANN model is statistically a better model compared to others and can be used as a better estimator of path loss for university campuses in Nigeria.

VII. CONCLUSION

The research goal was to analyze the behavior of propagation channel, determine the Path loss exponent and to model the channel using ANN for wireless data communication systems operation at ISM 2.4GHz. Based on several drive tests conducted. A mathematical model was formulated which could be used in the deployment of WiFi AP due to its adaptive nature. The propose ANN new model explains the relationship between the path-loss coefficient, the distance between Tx-Rx and the frequency, together produces a novel framework that describe the Path Loss. It provides the basis for the realization of wireless data communication under complicated environment with complex utilizing of the spectrum resource. The ANN model can be used for regular IoT deployment, VOIP, and robotics operating in the ISM band 2.4GHz frequency. As a future work, it is intended that the path loss model for IEEE802.11ac with frequency band of 5GHz will be examined.
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