Prioritizing actions: spatial action maps for conservation

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Spatial prioritization is a critical step in conservation planning, a process designed to ensure that limited resources are applied in ways that deliver the highest possible returns for biodiversity and human wellbeing. In practice, many spatial prioritizations fall short of their potential by focusing on places rather than actions, and by using data of snapshots of assets or threats rather than estimated impacts. We introduce spatial action mapping as an approach that overcomes these shortfalls. This approach produces a spatially explicit view of where and how much a given conservation action is likely to contribute to achieving stated conservation goals. Through seven case examples, we demonstrate simple to complex versions of how this method can be applied across local to global scales to inform decisions about a wide range of conservation actions and benefits. Spatial action mapping can support major improvements in efficient use of conservation resources and will reach its full potential as the quality of environmental, social, and economic datasets converge and conservation impact evaluations improve.

Keywords: spatial planning; conservation priorities; biodiversity; ecosystem services; optimization; adaptive management; decision support tools

Brief history and constraints of spatial planning for conservation

Over the past century, ecosystems have been in decline, placing one million species at risk of extinction and jeopardizing the wellbeing of people worldwide. The economic and human resources for reversing these trends and achieving conservation outcomes are limited, requiring prioritization of efforts to maximize conservation returns on investments. Conservation planning practices emerged to support such prioritization. While methods vary, the process typically includes identifying conservation challenges and goals; choosing places and actions to achieve stated goals;
developing measures and a monitoring program; implementing actions; and monitoring, evaluating, and adapting based on what is learned (Fig. 1A). Here, we address the part of this process focused on choosing places and actions. As habitat decline has advanced and conservation actions and goals have diversified, common approaches to this aspect of conservation planning have become misaligned with the needs of conservation decision making.

The need to combine questions of where and how to act
Spatial conservation prioritizations often use the implicit assumption that the action taken will be some form of nature protection. Under this assumption, it has been logical to first identify areas to conserve based on conditions in those places (e.g., species presence, habitat quality, and threat intensity), and then choose the specific set of protection actions to take in those places. These separate, ordered steps have been a central aspect of conservation planning approaches (e.g., Margules and Pressey’s “select conservation areas” and then “implement conservation actions”; or the Nature Conservancy’s “ecoregional assessments” followed by “the 5S Framework for Site Conservation” or “conservation action planning”). However, the suite of possible conservation actions has dramatically diversified as evidence has shown the limitations of protection alone. Shortcomings of isolated parks and preserves led to actions focused on ecosystem-based management addressing whole landscapes, watersheds, and seascapes. Best management practices were introduced and shown to elevate biodiversity in multiuse ecosystems, such as agricultural lands, commercial or community-managed forests, coastal zones, and cities. Additional interventions are being adopted to drive impacts through community empowerment and capacity building, development planning and mitigation, changes in markets or access to markets, formal or informal governance changes, communication campaigns, or creation and use of novel finance mechanisms, including insurance instruments or debt conversions.

These approaches have differing impacts on species, ecosystem processes, and aspects of human wellbeing depending on how they are implemented and the surrounding biophysical and socioeconomic contexts. The pace of global habitat loss, combined with the diversity of conservation objectives and range of possible conservation actions, means that protection is now not the first and best action in every case. The conservation community
has made major advances in standardizing and synthesizing evidence on how these various actions lead to diverse impacts. Yet, these efforts are either qualitative (e.g., the Conservation Actions and Measures Library\textsuperscript{42}), making it difficult to compare actions in the context of goals, or quantitative but not spatially explicit (Conservation Evidence\textsuperscript{43} Collaboration for Environmental Evidence\textsuperscript{44}), providing fodder for spatial analyses but falling short of representing how spatial variation is likely to affect results.

Conservation decision makers now need to simultaneously prioritize both where and how to work. These previously separate steps in conservation planning need to be combined to give an understanding of how much of which impacts each possible action is likely to cause across space. Armed with this information, conservation planners can better choose where and how to act to have the greatest chance of achieving their stated conservation goals.

The need to estimate change in diverse impacts

Early spatial prioritization efforts focused on occurrences of priority biodiversity elements, and the activity of sequestering nature through practices, such as the creation of nature reserves or protected areas, purchase of land easements,\textsuperscript{45} and other similar approaches.\textsuperscript{3,46,47} The methods used to prioritize these actions evolved to consider the number and sizes of preserves,\textsuperscript{48} maintenance of ecological processes,\textsuperscript{49,50} connectivity within and across biomes,\textsuperscript{51} adaptation to climate change,\textsuperscript{52–55} costs of conservation actions and foregone opportunities,\textsuperscript{56} and the balancing of benefits to ecosystems, society, and the economy.\textsuperscript{57–59} These conceptual problems were also formulated mathematically, and various algorithms have been developed to identify efficient, optimal, and other solutions to capture biodiversity elements.\textsuperscript{15,60–62}

Through all these advances, conservation prioritizations have relied primarily on snapshots of current or historic information about the status and location of biodiversity (also known as asset maps).\textsuperscript{13,14} For example, biodiversity hotspot\textsuperscript{63–65} and coldspot maps\textsuperscript{66,67} key biodiversity areas\textsuperscript{68–71} and other expressions of where biodiversity investments should be prioritized\textsuperscript{16,72,73} have relied on snapshots of species richness, vegetation conditions,\textsuperscript{74–76} ecosystem services,\textsuperscript{59,77} current human pressures,\textsuperscript{78,79} or expected habitat conversion pressures (often called threats).\textsuperscript{80,81}

Evaluations of conservation actions have shown the shortcomings of this approach, as impacts of a given action can vary based on implementation methods, and biophysical, social, or economic conditions that influence feasibility, adoption, and system responses.\textsuperscript{23,82,83} For example, a systematic review found that freshwater protected areas may cause positive conservation impacts, no impacts, or negative impacts, depending on design methods and socioecological context.\textsuperscript{84} Similar results have been found where terrestrial protected areas have been evaluated,\textsuperscript{23,85,86} emphasizing that even the most long-standing tools of conservation cannot be presumed to have consistent or positive impacts. Planning approaches now need to account for this variation and estimate the potential for conservation actions to drive desired outcomes under varying conditions.

In addition, the scope of desired conservation outcomes has expanded. The global conservation agenda now embraces connections to human well-being and embeds conservation as an underpinning element of sustainable development.\textsuperscript{37} Under this framing, conservation investments are intended to improve biodiversity and associated aspects of human wellbeing, and so prioritization efforts need to anticipate the impact of conservation actions on multiple environmental and social outcomes.

Relevant methodological advances have been made that enable the integrated selection of where and how to act, and that support estimation of diverse conservation impacts. For example, many studies have moved beyond the use of assets or threat as proxies for conservation benefits by using scenario analysis or optimization approaches to estimate impacts of possible conservation actions on multiple outcomes.\textsuperscript{88–93} Despite these advances, prominent conservation prioritization efforts continue to use more limited approaches based on assets or threats, unrealistic assumptions regarding feasibility and adoption, and limited or unspecified possible actions.\textsuperscript{72–76}

Spatial action mapping

We introduce an approach called spatial action mapping that combines several existing advances in spatial prioritization and embeds them in common conservation planning frameworks. Spatial action
mapping is meant to be used as one element in an adaptive management approach (Fig. 1A)\(^\text{12}\) and can be incorporated into any strategic conservation planning methodology.\(^\text{11}\) Spatial action mapping is best introduced into a planning process after a specific system has been described and its boundaries identified, a conservation vision and broad goals have been set, and candidate actions for achieving those goals have been put forward.

Spatial action mapping embraces the reality that only actions have outcomes and costs that can be prioritized, while assets (e.g., species, places, and carbon stocks) or threats do not.\(^\text{14,94}\) We define a spatial action map as a spatially explicit view of where and how much a given conservation action is likely to contribute to achieving stated conservation goals.

We present a general framework for spatial action mapping (Fig. 1B) that captures several of the needed advances in spatial prioritization. This framework moves beyond a general assumption that the action taken will be some form of protection. Instead, spatial action mapping explicitly specifies an action(s), actors, and impacts. In this context, actors are those parties that are responsible for implementing a decision, while stakeholders are those parties that can impact or are impacted by a decision. The general steps described also encourage analysts to move beyond the use of biodiversity asset and threat maps as proxies for conservation impact by emphasizing estimation of impacts based on expected changes in a system compared with business-as-usual (BAU) conditions (i.e., the world without the action). In addition, the framework encourages accounting for multiple possible impacts, creating the opportunity to explore synergies and tradeoffs, and advance multiple objectives (e.g., environmental, social, and economic).

This approach does not solve all of the challenges of conservation planning and does not require the adoption of the most sophisticated available approaches to mapping, modeling, or optimization. Rather, it aims to put forward a viable “next step” to advance spatial prioritization in conservation decision making.

**Applications and stakeholders**

Spatial action mapping as described in this framework can directly address several common planning questions and provide inputs to several others (Fig. 2). When a spatial action map is complete, stakeholders will better understand how much impact(s) is likely to result from an action, how potential impact(s) vary across space, and whether tradeoffs or synergies among impacts are likely. For example, spatial action maps of Myanmar show where forest protection and best management practices are likely to provide the highest levels of several ecosystem services (Fig. 3).

Many strategic planning processes aim to prioritize places for action. When these processes rely on spatial prioritization, spatial action maps produced via this framework can serve as an input to return on investment (ROI) and prioritization analyses. Costs of actions (including implementation, opportunity, maintenance, and transaction costs)\(^\text{95}\) can vary dramatically from place to place, so consideration of cost-effectiveness or cost-benefit criteria are likely to make spatial prioritization analyses much more useful. Spatial action maps lend themselves to such an approach because they address a specific action that has an identifiable set of costs, and they represent potential returns. Compare this to a typical asset or threat mapping approach that uses information on species occurrence or system conditions which themselves do not have associated costs, and so cannot be directly used in ROI analyses.

In combination with ROI analyses, typical optimization processes can be applied to identify places that most cost-effectively meet a conservation goal, maximize individual or optimize multiple returns for a given budget, or are robust to cost, budget, or other assumptions (Fig. 2). Various types of ROI can also be explored (e.g., net returns, equitable returns across beneficiaries, returns to varied stakeholders, and variance in returns). Multiple software tools are available to aid in optimization analyses.\(^\text{62,96–99}\)

For example, spatial action maps were used in an optimization analysis of the Brazilian Cerrado (Fig. 4). Maps of several expected impacts (species persistence probability, water quality, and agriculture profitability) from several actions (agricultural expansion, habitat protection, and habitat restoration) were used to explore tradeoffs and synergies and find optimal arrangements of these actions to meet environmental regulatory requirements in agricultural lands.

Spatial action maps can also be used to compare actions. For example, spatial action maps were
combined with cost data associated with reforestation or avoided deforestation to show the potential of these two actions to mitigate atmospheric carbon across the tropics (Fig. 5A and B). The maps allow stakeholders to see which action has the most cost-effective potential in a given place. For example, the Democratic Republic of Congo has much more potential for emission reductions through avoided deforestation than through reforestation (Fig. 5C, country label COD).

As another example, in an analysis of where and how much urban street tree planting could reduce urban heat and air pollution, spatial action maps were combined with cost data to estimate how returns on investment could be optimized (Fig. 6).

Spatial action mapping will be most useful when actors can implement actions on a subset of a large land- or seascape. This is often the case in conservation planning contexts where there is a mosaic of public and private lands or waters, and various stakeholders control actions in different places. Such mosaics set the stage for conservation actions to be one aspect of a larger, dynamic system, most of which the conservation decision maker does not control or cannot influence. Spatial action mapping can usefully place conservation actions in the context of other forces acting across the land- or seascape.

Alternatively, decision processes that address multiple uses across an entire land- or seascape are not best served by spatial action mapping. For example, some national land use planning or marine zoning processes have the potential to influence a range of uses across entire land or seascapes. Multiobjective scenario planning is better suited to these cases, as it provides a better framework for representing the interactions among simultaneous changes in drivers affecting whole land- or seascapes.88,90

Engagement with key stakeholders is critical throughout the entire conservation planning process,12,100,101 and the steps associated with spatial action mapping are no exception (Fig. 7). Planners, community leaders, traditional knowledge holders, activists, and many others can provide important input to spatial action mapping processes. A variety of strategies and extensive guidance are available for seeking stakeholder input, from key informant or focus group discussions to intentional choice experiments.102

A main purpose of stakeholder engagement in spatial action mapping is to understand the
Figure 3. Spatial action maps showing potential impacts of forest conservation on ecosystem services in Myanmar. Ecosystem services explored were drinking water quality (A), dry season drinking water supply (B), and flood risk reduction (C) under low and high climate change assumptions. Maps were produced using production function models to estimate multiple impacts as a result of forest protection and improved forestry management actions. Additional details under the Forest Conservation case in Table 2. Reproduced with permission.

decisions at hand, specify alternate possible actions, and ensure that spatial action mapping is code-designed as a useful tool for informing decision makers (Fig. 7). Decision-making processes where spatial action mapping may add value include community visioning processes, planning for natural resource management, biodiversity strategic actions, endangered species management, infrastructure development and mitigation, subnational comprehensive plans (e.g., municipal or state), climate resilience and risk reduction, food or water security, corporate supply chains, local economic
Spatial action mapping

Figure 4. Spatial action maps showing potential for profitable agricultural expansion under various levels of compliance with environmental regulations in Brazilian Cerrado. (A) Current land cover and land use for the Ribeirão São Jerônimo study watershed in southeastern Brazil. Prioritization maps depicting the relativized marginal values for (B) biodiversity, (C) sugarcane profit, and (D) water quality in the watershed. Efficiency frontiers show marginal losses and tradeoffs between agricultural profit and biodiversity (only BD), water quality (only WQ), or both BD and WQ (joint BD-WQ) for species (E) or water quality (F) returns. The circled maps illustrate optimal protection/restoration of 25% of native habitat that coincides with the Brazilian Forest Code’s habitat threshold for the region. Maps were produced using economic and biophysical production function models. Additional details under the Agriculture Siting case in Table 2. Modified and reproduced with permission.

In addition to the decision makers who may act based on findings, other stakeholders across diverse skills and perspectives are critical to engage. Any representation of proposed interventions is likely to be strengthened through input from stakeholders who may have authority over relevant aspects of the larger system, strong opinions about the location or impact of actions being considered, or whose lives or livelihoods may be affected by the actions. Other important stakeholders may not be affected by the decision at hand, but may hold knowledge about the impacts of interest, the feasibility of actions being considered, or the probability of adoption. These stakeholders may include those making other decisions about the system that can hinder or amplify the actions being considered.
Figure 5. Spatial action maps of potential atmospheric carbon reductions through forest restoration or avoided deforestation in the tropics. At a carbon price of US$20 tCO₂⁻¹ from 2020 to 2050, maps show potential removals from reforestation (A) and reduced emissions from avoided deforestation (B). Combining the maps allows a ranking of 77 countries based on their potential to reduce carbon emissions through both actions (C). Axes are log-scale, blue data are for Latin America/Caribbean; orange data are for Africa; and green data are for Asia. The three-letter country codes are from the UN trade statistics (https://unstats.un.org/unsd/tradekb/knowledgebase/country-code). Additional details under the Tropical Carbon case in Table 2. Figure modified and reproduced with permission.

The methodology

Our framework assumes that spatial action mapping starts after the foundations of a conservation planning process have been established (Fig. 1A). These foundations typically include clarification of the decisions to be informed by the mapping, the scope (geographic, temporal, and strategic) for the mapping exercise, the environmental and human wellbeing goals, and candidate actions that...
Figure 6. Return on investment (ROI) of urban street planting for particulate air pollution reduction in Washington, DC. Inputs to spatial action maps included land cover (A), forest cover (B), current particulate matter concentration (PM) (C), and population distribution (D). Spatial action maps were combined with cost data to estimate ROI for individual street segments (E), as well as for 1-km grid cells (F). Additional details under the Urban Trees case in Table 2. Adapted and reproduced with permission.
could be taken to achieve the goals.\textsuperscript{11,12,104} For example, a spatial action map may be developed to evaluate which countries with savanna landscapes (the geographic scope) could make a substantial contribution to national greenhouse gas emissions reductions (the goal) through proactive early dry season burning (the action).\textsuperscript{105} Spatial action mapping builds on this foundational work.

We describe a framework for spatial action mapping that follows four steps that specify: (1) which action(s) is being taken, by whom, and to what ends; (2) how the system will behave if the action(s) is not taken; (3) where the action(s) is likely to take place, including feasibility and probability of implementation as designed; and (4) how much impact the action(s) will have considering the expected effectiveness of the action under specified socioecological conditions (Fig. 1B). Methods applied at each step can range in complexity, with varying data needs, analytical approaches, and capacity requirements (Table 1). We give a selection of examples that represent application of this approach to various types of actions, diverse geographies, and a range of spatial scales, using different levels of complexity for each step in the process (Table 2). The examples are not meant to demonstrate ideal spatial action maps, but rather to show a range of applications of the general framework under the varying constraints of conservation planning in practice.

**Specify actors, actions, and impacts**

We recommend starting a spatial action mapping process by clearly describing the actions to be assessed, the actors assumed to be taking those actions, and the impacts of the actions that will be estimated. In short, this step clarifies what, by whom, and to what ends. Stakeholder input is critical in this step, and alignment with the focal decision makers and implementers on these aspects is essential (Fig. 7).

While goals and possible actions may already be identified through earlier steps in the conservation planning process (Fig. 1A), decisions may need to be specified further to support spatial action mapping. For example, a team that has identified protection as a possible conservation action may not have been specific about which types of protection are to be included (e.g., private versus public protected areas: strict nature reserve, wilderness area, and national monument). As these types of protection are relevant under different conditions and may result in different biodiversity and human wellbeing outcomes, further specification is needed before possible areas for each type of protection can be mapped. Participants in the Energy Siting case (Table 2) went beyond generic ideas of protection by describing four potential actions that applied increasingly stringent levels of environmental protection, each of which led to a different map of potential areas.\textsuperscript{106} Alignment on specific actions early in the mapping process will ensure that stakeholders have the same expectations and will streamline later steps.\textsuperscript{107}

At this stage, it is also important to specify which actors are to be reflected in the analysis. This is not the same as identifying relevant stakeholders (see section above), but rather, which subset of stakeholders’ actions will be represented in the scenarios.
Table 1. Options for spatial action mapping methods

| Step                          | Less Complex | More Complex |
|-------------------------------|--------------|--------------|
| Specify impacts               | Impacts nominated and selected through ad hoc process | Impacts identified through logic models; evidence evaluation |
| Create BAU Scenario           | Basic assumptions (e.g., resource use expands where cost-effective and legal) | Functional modeling (e.g., reflect human behavior, changing environmental conditions, etc.) |
| Create action scenario        | Single value adjustment for probability of adoption | Continuous value adjustment for probability of adoption |
| Action represented as "present" | Probability of adoption modeled based on multiple factors, including human preferences and local conditions |
| Estimate benefits and losses  | Overlay scenarios on current conditions, apply factor adjustments | Calculate changes based on literature coefficients |
|                              | Calculate changes using process models, sometimes including dependencies, feedbacks, and interactions |

Note: The general steps of spatial action mapping can be completed using a wide range of methods that vary in complexity and associated time, capacity and resource requirements to complete. This table details a range of options for several steps of the process. These options are not exhaustive. Spatial action mapping may include creation of multiple BAU and/or action scenarios. BAU, business as usual.

created. This is often an aspect of conservation prioritization that is implied rather than explicitly stated. Specifying the actor(s) represented in the mapping will help inform later assumptions and inputs regarding feasibility of the action(s) and probability of success. For example, different actors may have potential to drive actions in different geographic areas, under differing conditions, with differing resources and capacities. A spatial action map of natural reserve establishment will look different when the actor is a global land trust organization than when the actor is a specific national government or a particular coalition of Indigenous communities. The actor(s) and decision maker(s) may or may not be the same. For example, in the Marine Protection case (Table 2), the decision maker using the mapping analysis was a global nonprofit organization, but the actors included were national governments. By contrast, the Cape Town municipality was both the actor and decision maker in the Invasives Control case.

Finally, it is important to gain agreement and clarity on which impacts (positive and negative) will be estimated. Relevant impacts may have been identified in earlier conservation planning steps focused on setting goals. If not already chosen, likely impacts can be identified using logic models, which describe causal pathways from actions to environmental and human impacts. They can also reveal possible negative unintended consequences, which may be chosen as part of the mapping exercise to identify areas where tradeoffs can be minimized. We suggest considering impacts that (1) relate to the stated conservation goals; (2) are likely to result from the proposed actions undertaken by the specified actors; (3) are of greatest interest to key stakeholders; (4) are likely to vary spatially; and (5) can be quantitatively estimated in a spatially explicit manner.

Actions can cause many benefits and losses, so there may be a need to narrow the list based on stakeholder interests. This is often done implicitly, as is true for all seven cases we include. However, as different stakeholders are likely to have different interests, we recommend making this process explicit. Simple options may include facilitating stakeholder dialogues, while more complex options include elicitation of weights within a structured, participatory decision-making process.

Data, model, and capacity limitations may make it impossible to estimate changes in some impacts that are of interest to stakeholders. For example, the activities mapped in the Urban Trees case can reduce particulate matter and heat-related mortality (Fig. 6). The same actions also likely lead to reduced disease in urban residents. However, these additional health impacts were not modeled due to the much smaller number of available published exposure-response functions for many morbidity effects of particulate matter and heat, and the large...
| Title                          | Urban trees | Tropical carbon | Marine protection | Forest conservation | Energy siting | Invasive control | Agriculture siting |
|-------------------------------|-------------|-----------------|-------------------|--------------------|--------------|-----------------|--------------------|
| Application                   | Urban trees planting to reduce heat, air pollution | Reforestation and forest conservation to reduce greenhouse gas emissions | Debt swaps to fund marine protected areas | Natural habitat conservation to provide ecosystem services | Meet renewable energy commitments with minimal biodiversity impacts | Invasive species control to benefit water supplies | Expand agriculture, complying with environmental law |
| Spatial scale Geography       | Global      | Global tropics  | Global            | National Myanmar   | Subnational Western USA | Local South Africa | Local Brazilian cerrado |
| Specify actors, actions, impacts | Action(s) Tree planting | Forest conservation funded by carbon payments | Protection funded by government debt restructuring or debt forgiveness | Conservation of natural habitat (avoiding agricultural conversion) | Wind, solar, and geothermal energy infrastructure development with environmental conservation | Invasive plant removal | Sugarcane and cattle pasture expansion |
|                  | Natural regeneration | Reforestation funded by carbon payments | Government staff, landowners, community members, and forestry companies | National government | Utilities making power purchase decisions | Municipal authority | Private corporation |
| Actor(s)                     | Municipal governments | Private insurers, creditors, or development finance institutes | National governments Global nonprofit organization | National government | Utilities making power purchase decisions | Municipal authority | Private corporation |
| Decision maker(s)            | Mayors | Government ministers, CEOs, landowners, and community leaders | National governments Global nonprofit organization | National government | Utilities making power purchase decisions | Municipal authority | Private corporation |
| Impacts estimated (difference in...) | Urban planners Particulate matter concentration near residents | Forested area | Human threats in marine systems | Drinking water sediment pollution | Renewable energy production | Water quantity | Species persistence probability (407 birds and 132 mammals) |
|                              | Summer air temperature near residents | Atmospheric carbon concentrations | Human threats in coral reefs areas | Sediment pollution upstream of dams | Cost of energy provision | Jobs created | Net profit from sugarcane and cattle ranching |
|                              | Basis for BAU scenario | Expected agriculture expansion and carbon accumulation | Current conditions | Expected agriculture expansion and climate scenarios | Meet renewable energy targets, ignore environmental impacts | Expected invasive species expansion | Agriculture expansion with no Forest Code compliance |
|                              | Method used to create scenario | Dynamic-recursive projection of annual forest loss/gain in 2020–2050, assuming no changes in agroecological, economic, and policy conditions | No BAU created | No BAU created | Models applied to expand renewable energy infrastructure based on energy site suitability, but not environmental exclusions | Used existing scenarios | Converted current land uses to sugar cane or cattle ranch to maximize net profit |

Continued
Table 2. (Continued)

| Case        | Urban trees | Tropical carbon | Marine protection | Forest conservation | Energy siting | Invasives control | Agriculture siting |
|-------------|-------------|-----------------|-------------------|---------------------|--------------|------------------|--------------------|
| Action scenario | Feasibility: physical factors | Aridity index suitable Nonimpermeable land cover | Elevation Distance from cities Current forest cover | Presence of high conservation value marine area | Presence of natural habitat | Environmental exclusion categories based on conservation values, land ownership, and protection status. Energy site potential factors, including energy potential, physical characteristics, hazards, and economic viability | Presence of invasive plants | Multiple biophysical, sociopolitical, and economic factors incorporated in models used to generate scenarios of optimal agriculture expansion |
| Feasibility: sociopolitical factors | Population distribution | Protection status | | | | | Inside water source area |
| Feasibility: economic factors | Cost of tree planting Vulnerable sites (schools and hospitals) | Carbon payment of USD20 or USD50/CO$_2$e greater than agriculture revenue and transaction costs | Debt to GDP ratio 60% or higher | | | |
| Method used for probability of adoption | Assumed 100% when feasibility conditions met | Assumed 100% when feasibility conditions met | Assumed 100% when feasibility conditions met | Assumed 100% when feasibility conditions met | Assumed 100% when feasibility conditions met | Varying levels of Forest Code compliance, farm or landscape scale compliance |
| Method used to create scenario | Action represented as marginal increase in tree cover in each 1-km grid cell | Iterative land use and land cover change based on carbon payments. Reforestation created natural or plantations; conservation retained existing forest cover | Action represented as "present" | Current (2013–2014) land use/land cover map to represent no further natural vegetation loss, combined with downscaled climate scenarios | Models applied to expand renewable energy infrastructure based on energy site suitability, and three different levels of environmental exclusions | Used existing scenarios |
| Estimate benefits and losses | Methods used Moderately complex: models of air pollution, temperature, and health significance based on literature coefficients | Moderately complex: production function models used to estimate above and below-ground carbon and atmospheric CO$_2$ removals | Less complex: area of EEZ (total or area containing coral habitat) adjusted by abatable and unabatable threat scores | Moderately complex: InVEST models for all ecosystem service estimates, largely rely on production functions models based on literature coefficients | Moderately complex: linear programming model RESOLVE used to create supply curves. Less complex overlay approach for environmental impacts | More complex: Water Resources Yield Model, WR2005 and ResSim models for water quantity | Moderately complex: economic, ecological, and biophysical production function models |

Source: 128 152 108 115 106 109 90, 132

Note: Cases provide specific examples of how spatial action mapping has been done at local to global scales and for a wide range of conservation actions. Each case combined methods based on stakeholder interests, resource, and data availability and other factors. Cases show combinations of different levels of complexity in the methods used across various steps of the process. Full details of methods for each case can be found in their source publications.
data collection effort such modeling would have required. Iteration between impact selection and analytical design will help arrive at a set of impacts that are logically linked to selected actions, of interest to at least one stakeholder, and feasible to estimate.

**Calculation overview**

A robust spatial action mapping process moves beyond asset and threat assessments by using basic scenario analysis. The approach builds a spatially explicit (mapped) view of potential impact for each spatial unit \((x = 1, 2, \ldots X)\) on a land or seascape, where a unit can be any user-defined option, including a grid cell, a hexagon, a polygon, and so on. Conditions under a BAU future are compared with conditions in a future with the chosen action(s) implemented (Fig. 1B). Potential impact \((I)\) of a chosen action \((a)\) is calculated as:

\[
I_a = \sum_{x=1}^{X} f(Q_{Ax}, F_{ax}, P_{ax}, D_{ax}) - Q_{BAUx}, \tag{1}
\]

where the status of the chosen impact under the action scenario \((A)\) is a function of the quantity of expected impact \(I\) generated by perfect adoption of the action \((a)\) under the set of conditions in parcel \(x\) under the action scenario \((Q_{Ax})\), adjusted for the feasibility of action \(a\) occurring in parcel \(x\) \((F_{ax})\), the probability that action \(a\) will be adopted in parcel \(x\) if it is feasible \((P_{ax})\), and the likelihood that action \(a\) is implemented as designed in parcel \(x\) \((D_{ax})\). \(Q_{BAUx}\) is the amount of the chosen impact \(I\) generated in parcel \(x\) under the BAU scenario. A spatial action mapping analysis may consider multiple impacts from a given action, and may also consider multiple actions, each with their own associated impacts.

Each calculation is discussed further in the following sections. As the equations we provide represent general functions, their form and expression will be different in each application, with planners deciding if and how to express each variable within the constraints of their analysis. We provide qualitative descriptions of seven different applications of this framework (Table 2). Original source papers for the examples give further detail and quantitative expressions of the calculations.

**Create BAU scenario**

BAU scenarios are commonly used in policy evaluation to assess how outcomes in a scenario *without* the policy or program differ from those in a scenario *with* the policy or program. The purpose of a BAU scenario is to depict what would happen absent the policy or program (i.e., the world without the policy); thus, the BAU scenario should include expected changes in key variables that affect the outcomes of interest, including relevant policies, population, economic activity, and technology. In the context of spatial action mapping, the BAU scenario is meant to depict the system at a particular time point in the future as it will be if the conservation action being explored is not taken.

A BAU scenario is distinct from a current baseline or historic reference condition, which are sometimes used in other types of conservation analyses. Using these types of scenarios as a BAU scenario in spatial action mapping could lead to over or underestimation of impact, result in underestimated additionality of actions (by directing actions to places that may be under high threat today, but lower threat in the future), or result in missed opportunities (by underrepresenting a threat in an area where a risk is expected to increase in the near future). In general, the most informative comparison in a spatial action mapping analysis will come from the use of a BAU scenario that represents changes in the future without the candidate action. For example, the Forest Conservation case created BAU scenarios that depicted expected agricultural expansion without additional forest conservation and included a range of expected climate conditions (Table 2; the Forest Conservation case). In some cases, such as actions to mitigate climate change, extensive debates have established alternative means of setting BAU scenario conditions.

The BAU scenario is informed by the proposed action(s) and what it is expected to change. For example, in the Invasives Control case (Table 2), the proposed action is the removal of invasive alien plant species above and beyond rates achieved by BAU control efforts, so the BAU scenario was designed to depict vegetation cover (of native and nonnative species) without additional invasive species removal actions. Use of a current map of invasive species distribution as the BAU scenario in this case would misrepresent the conservation impact because the focal invasive species are expanding rapidly, and this expansion would not be captured.
There are multiple approaches to developing spatially explicit BAU scenarios (Table 1). One option is to apply basic assumptions to determine how conditions will change. For example, when exploring actions that will reduce or change the location of resource extraction, one could assume that planned new development will happen in places where it is legal and cost-effective. This approach has been used to create BAU scenarios for growth in energy infrastructure, agriculture, fisheries, and mining.\textsuperscript{117–19}

Alternatively, statistical models can be developed based on past patterns and applied to project those patterns forward into the future.\textsuperscript{120,121} This is appropriate when no major changes in the size or effect of drivers of change are expected over the projected timeframe. This approach was used in the Tropical Carbon case, where trends in drivers between 2000 and 2010 were used to project the same drivers into 2020–2050 (Table 2). A similar approach was used at a smaller scale in Indonesia to extend recent patterns of illegal forest encroachment as a BAU scenario for enforcement actions.\textsuperscript{122}

Another option for creating a BAU scenario is to model future processes that are expected to change drivers of interest (e.g., climate change, policy, and cultural shifts). Options for this type of approach include system models, cellular automata models, multiagent system models, among others. There are many cases of using this approach to estimate land use and land cover changes into the future. Examples include use of a cellular automata-Markov chain model for Dedza district, Mali,\textsuperscript{123} and development of a generalized agent-based model for larger scale applications.\textsuperscript{124}

In some instances, there is no historic experience with the major drivers of interest. In these cases, it may be most appropriate to use multiple BAU scenarios that represent a range of possible conditions without the proposed action, and to characterize uncertainty around the future state. Climate change is a driver often treated in this way, as patterns in key environmental drivers are already varying from observed, historic patterns. The authors of the Forest Conservation case included multiple climate futures in combination with both their BAU and action scenarios (Fig. 3 and Table 2, the Forest Conservation case).

In many cases, existing analyses may be used as BAU scenarios, or as inputs to creating them. Government, research, and/or industry groups regularly create scenarios or spatial plans of expected future changes in many possible aspects of a BAU scenario (e.g., energy, agriculture, transportation, infrastructure development, and climate change). These may take the form of national energy plans, agricultural zoning plans, infrastructure development proposals, global climate change scenarios, and so on. Maps of biodiversity threats or human conversion pressure\textsuperscript{125,126} may also serve as useful inputs to the creation of BAU scenarios. One caution in considering threat maps is that many capture current, rather than future, threat levels, and the drawbacks of using present or historic conditions have been discussed above.

**Create action scenario**

The action scenario depicts a future where the proposed action is implemented. Creation of the action scenario captures key changes that the action will cause, against the backdrop of other expected changes that the action does not affect. For example, in a case exploring the impacts of switching from high to low water use crops, the action scenario might represent the intended change in land use in the context of climate change and expected changes in other water uses.

The action scenario incorporates the action’s feasibility ($F_{ax}$) and likelihood that it will be implemented to design ($D_{ax}$) (see Eq. 1). Feasibility is often influenced by a suite of physical, social, institutional, and economic conditions related to both the action and the actors undertaking it. The action scenario aims to represent the influence of these factors on adoption of the action. Some feasibility factors have clear thresholds and so are amenable to binary representation. For example, a debt swap is an action that can be taken to enable a national government to take some conservation action, such as establishing new protected areas. In the Marine Protection case (Table 2), the condition of the debt available for restructuring was treated as a binary feasibility factor, where swaps were considered feasible in any country with a debt to GDP ratio of 60% or higher.\textsuperscript{108} The specific factors determining feasibility will vary by action, actor, and case, and stakeholder engagement is critical for informing this step (Fig. 7).

The action scenario should also reflect the probability of adoption ($P_{ax}$), defined as the likelihood...
that the action will be adopted in a place where it is feasible. In many conservation planning exercises, it is assumed that an action will be adopted in all the places where it could have impact. In our diverse examples of spatial action mapping, all but one assumes 100% probability of adoption in places that meet the feasibility criteria (Table 2; the Action Scenario: method used for probability of adoption). These cases assumed 100% adoption to represent the full potential of the actions explored, but complete adoption is uncommon. For example, economic subsidies have incentivized the use of cover crops in U.S. row crop systems for many years, but actual adoption remains around 3.9%.

There are several options for adjusting the action scenario to reflect the probability of adoption (Table 1). A simple approach is to use a single estimate to reduce the feasible area in the action scenario. For example, the data on cover crop adoption could be used to reduce expected adoption in any new programs to ~4% of prospective adopters. A more complex approach to projecting adoption may be possible if conditions for adoption are understood and relevant data are available. Data on such conditions may be used to select subsets of areas considered feasible for the action (e.g., ruling places “in” or “out”). For example, community-based fishery closures may have a 45% adoption rate where they are feasible and most likely to be adopted in communities with an identified community leader. This information could be used to select 45% of feasible areas, preferring selection of communities with identified community leadership. A continuous variable could be used in a similar way, selecting areas with diminishing value until the target level of adoption is met. When multiple factors or social learning are known to influence the rate of adoption, a yet more sophisticated approach could use an estimation function, including relevant factors, to estimate variation of adoption across space.

Once feasible locations for the action and actor have been determined and adjusted for probability of adoption, choices must be made about what variables in the action scenario to change to reflect adoption. The approach used here is often dictated by the analyses planned to estimate the impacts of interest in the next step. A simple approach is to identify the action as present in those areas where it is determined to be feasible and likely to be adopted. This approach is appropriate if impacts are going to be estimated through factor application or a similarly simple method, such as those applied in the Marine Protection case (Table 2). If impacts are going to be estimated functionally based on conditions in a given parcel, then the action scenario should reflect any relevant changes the action is expected to cause in the factors included in the functional equation. For example, if an impact will be estimated as a function of a single spatial data layer, such as land use/land cover, or vegetation density, the action scenario needs to reflect the action as an altered land use/land cover type, or adjusted vegetation density. This approach was used in the Urban Trees case (Table 2), where the action scenario increased the percent cover of urban street trees in 1 km grid cells, and the decrease in air pollution and heat stress impacts on the residents of this grid cell were estimated using biophysical models. There may need to be iteration between steps within the spatial action mapping process (Fig. 1B) to ensure that factors used in estimating impact are adjusted appropriately in the action scenario.

An additional variable, $D_a$, can be introduced to account for the reality that conservation actions are not always implemented as designed. This variable is defined as the likelihood that the action $a$ is fully implemented as designed. Many spatial conservation planning analyses assume that a given action will always be implemented as designed and return an ideal conservation outcome (e.g., removed extinction risk for all species; complete restoration of a degraded system; and perfectly sustainable resource extraction). However, implementation of an action can be incomplete, reducing its impact. Often, partial implementation results from weak enforcement of actions, such as poor enforcement of activity limitations (e.g., stopping illegal logging or fishing within national protected areas). Such partial adoption was explored in the Agriculture Siting case, where scenarios were created to represent different levels of compliance with existing environmental regulations in Brazil. This case also considered the differences in profit and environmental impacts when actions were implemented to ideal design (by optimizing profit and environmental gains as dual objectives) versus suboptimal design (by reducing private costs then accounting for environmental damages) (Table 2; the Agriculture Siting case).
This factor can also be estimated through a variety of methods (Table 1). In a simple approach, a single adjustment can be applied to all areas where adoption is expected. For example, enforcement of protected areas is known to be low in countries with government corruption. Consider an analysis of the potential for protected areas to impact threatened and endangered bird populations and tourism revenue in Kenya, Tanzania, the Democratic Republic of the Congo, Namibia, and Botswana. Each of these countries experiences corruption according to the Corruption Perceptions Index (CPI), so a single value could be applied across these countries to diminish the likely impact of protection given that corruption is likely to weaken implementation. However, since the CPI is a continuous index, a more complex approach could be taken by using each country’s index value as a factor to reduce likelihood of implementation to design. Many factors can alter the likelihood of implementation to design, including capacity or data limitations, biased data, incomplete information, budget limitations that lead to incomplete or altered implementation, infrastructure constraints that limit access or supplies, weak social networks, or stakeholder biases, among others. Stakeholder engagement can help reveal relevant factors for the system of interest, prioritize the ones to include in the analysis, and inform how constraints are reflected.

**Estimate benefits and losses for nature and people**

In the final step of spatial action mapping, focal impacts are evaluated under the BAU and action scenarios, and the difference between scenarios is calculated to estimate benefits and losses from the action (Fig. 1B). This step addresses estimation of impact under BAU ($Q_{BAU}$), and the remaining elements of estimating impact under the action scenario ($Q_A$). The quantity of an impact of interest (e.g., species extinction risk, greenhouse gas emissions, or income from nature-based livelihoods) varies on the basis of some set of factors in the system and an action creates impact by altering one or more of those factors. As such, a consistent approach can be used to estimate the quantity of impact under the BAU and action scenarios, and the difference in conditions within the scenarios will allow estimation of gains and losses caused by the action (see Eq. 1). As with other steps, a range of approaches can be used to estimate these values. We do not review all plausible approaches here, but rather identify several options along a spectrum of complexity (Table 1).

In a simple approach, one may be able to use existing estimates of the impact under BAU ($Q_{BAU}$), and derive impact under the action scenario by applying a single factor adjustment to BAU levels of the impact as follows:

$$Q_{Ax} = \alpha_a Q_{BAUx},$$

where $\alpha_a$ is an adjustment factor indicating the expected effect of action $a$ on impact $Q$ in parcel $x$. For example, many conservation planning analyses take this approach by implicitly applying $\alpha_a = 1$ in all places where an action is assumed to be taken (e.g., assuming the impact of a protection action is to keep all existing species and habitats in their current status). It is unlikely that impacts will be the same everywhere, but this simplifying assumption may be necessary in the absence of information about how impacts vary, or when the analysis faces other constraints. This type of approach was used in the Marine Protection case, where debt swaps were assumed to drive marine protected area establishment that would yield perfect removal of all threats that can be abated by that action (e.g., overfishing) (Table 2; the Marine Protection case).

The next tier of complexity would involve estimating $Q_{BAU}$ and $Q_A$ as a function of several coefficients derived from the literature and applied to relevant data describing conditions known to influence impact:

$$Q_x = f(\beta_1 Y_{1x}, \beta_2 Y_{2x}, \beta_3 Y_{3x} \ldots \ldots \beta_n Y_{nx}),$$

where $\beta_1, \ldots, \beta_n$ are coefficients from the literature corresponding to $Y_{1x}, \ldots, Y_{nx}$ which are factors known to affect the impact of interest. In some cases, the equations used to estimate $Q_{BAU}$ and $Q_A$ may be identical, with variation in impact being driven by variation in the values of the factors ($Y_{1x}, \ldots, Y_{nx}$) between the scenarios. If new factors are introduced through the action scenario, then different functions may be needed to represent these new factors. Conceptual models (also called logic models, result chains, theories of change, and influence diagrams) can be useful starting points for informing this kind of factor-based estimation model. Such logic
models are commonly created in other steps of the conservation planning process and reference examples exist for some conservation actions.42

This factor-based approach was used in the Agriculture Siting case to investigate the potential for targeted land-use planning to achieve both commodity production and environmental goals in the Brazilian Cerrado90 (Fig. 4 and Table 2, the Agriculture Siting case). Specifically, spatial optimization techniques were used to map marginal values across a watershed to determine where the next unit of habitat clearing versus habitat restoration or protection would be most costly or beneficial in terms of agricultural profit (estimated for sugarcane production and cattle ranching), biodiversity (estimated as bird and mammal species persistence probability), and water quality (estimated as levels of nitrogen, phosphorous, and sediment retention). Efficiency frontiers that plotted agricultural profit against biodiversity and/or water quality were used to assess the marginal loss of those services per unit gained in profit and to detect potential land-use thresholds at different adoption scales (farm versus watershed scales) and compliance levels under Brazil’s Forest Code. This approach allowed decision makers to see which configuration of agricultural growing areas, habitat protection, and habitat restoration areas best met their multiple objectives.

The factor-based estimation approach is also used for ecosystem service and biodiversity impacts in the open-source software tool InVEST136 and its sister tools RIOS,137 OPAL,138 MESH,139 and ROOT.140 InVEST has been used in many environmental decision-making contexts, including the Forest Conservation case (Table 2). In this case, sediment retention, dry season baseflows, and flood risk reduction benefits provided by forested areas were estimated using a production function approach.115 Resultant maps (Fig. 3) show variation in areas with potential to secure the benefits of interest, with the most important areas largely falling outside the country’s current protected area network but remaining highly consistent across the range of climate scenarios considered.

Further complexity could be incorporated into the estimation of $Q_{BAU}$ and $Q_A$ using process models that depict the underlying functions of the system that interact to produce the impact of interest. Process models reflect the underlying biophysical, social, and economic drivers of change in the system, and potentially include interdependencies among these processes and/or feedbacks within the system. Such processes relevant to estimating conservation impacts would include climate dynamics, environmental (e.g., migration), and social (e.g., trade) teleconnections across spatial scales, dynamic processes, such as biogeochemical processes, human learning, and behavior change, and other relevant processes. Examples include Bayesian network141,142 and integrated assessment models (GCAM143, GLOBIOM, MIRAGE-BioF144, and FASOM145). These models have the advantage of reflecting more of the underlying dynamics and nonlinearities in complex systems and they are likely to provide the potential to estimate some subset of multiple impacts through an integrated set of assumptions and data. However, they generally have extensive data requirements and are inevitably more constrained by available data, capacity, and resources to apply them in new settings.

**Frontiers in spatial action mapping**

Many conservation planning analyses fall short of their potential utility because they do not account for how the key actions, questions, and impacts of interest to relevant decision makers and stakeholders vary spatially. We have outlined an approach that explicitly considers which conservation actions are being taken by whom and uses basic scenario analysis to estimate conservation impact compared with a future without the action. This approach embeds several advances in spatial mapping (e.g., mapping feasible areas for nonprotection actions, accounting for variation in adoption and implementation, replacing static maps with estimates of impact, and including multiple ecological and socioeconomic impacts) into standard conservation planning frameworks. When combined with ROI assessments that represent variation in costs, spatial action mapping can dramatically increase the benefits of prioritizing conservation actions.

However, this approach faces several limitations in practice. Through this methodology, we make three things explicit that are usually implicit in spatial conservation prioritization: variation in the feasibility of conservation actions, variation in actual adoption of conservation actions, and variation in an action’s effectiveness. While introducing variables to describe these factors provides a way to directly address the variation we know exists, doing
so reveals uncertainty when actual relationships are not understood or data to describe them are poor. Major data gaps do exist for some of these variables. Improvements in conservation impact evaluations and a broad range of data sources are needed to fully enable the application of the spatial action mapping approach. Impact evaluation transformed the medical sciences when it emerged in the 1700s, in the form of randomized control trials. While impact evaluation methods have proliferated across other fields, they have only more recently become influential in the design of development and conservation efforts. Growth in impact evaluations would provide valuable fodder for spatial action mapping.

In addition, the factors that determine the feasibility of an action, and objective reporting on how often actions are implemented as designed are incredibly limited. In turn, there is a clear need to better understand how estimates of feasibility are linked to performance of conservation interventions. There are also often mismatches in spatial and/or temporal resolution of data inputs for estimating multiple, diverse impacts. For example, the Urban Trees case had access to high-resolution land cover data for estimating forest cover and projecting its change, but particulate air pollution data for the same region were very coarse (Fig. 6).

Conservation actions also take place in the context of complex land and seascapes where many individuals (human and other species) are interacting across space and through time; and while these complex interactions are often difficult to realistically account for, they are essential to strive to better understand as they can lead to nonlinearities in impact, probability of success, and conservation costs. As previously mentioned, approaches for addressing interactions in spatial action mapping should be more regularly employed, whether through simple (e.g., enlarging planning units to reduce influence of small-scale interactions), moderate (e.g., running multiple plan scenarios to reveal influence of interactions on plan outcomes), or more complex (e.g., building complex dependencies into models that estimate impacts) approaches. Additional advances are needed to allow consideration of changes in conditions, likely outcomes, and the relevance or social value of such outcomes over time. More fully incorporating temporal variation would allow decision makers to explore where, how, and when to act, likely introducing additional efficiencies and improving conservation outcomes.

Given these known limitations and the uncertainties they introduce, it is critical to engage decision makers and relevant stakeholders early in spatial action mapping processes to understand how the uncertainties introduced may influence the decision at hand, and how these uncertainties may be explored and expressed in ways that can inform the decision (Fig. 7). It is useful to understand the decision maker’s level of risk tolerance, as uncertainty that may be deemed scientifically interesting may be small (or large) relative to the decision maker’s tolerance. There may be aspects of uncertainty introduced by the assumptions or data used that are not relevant to the decision, or that are unlikely to alter the decision. Understanding these aspects will help narrow in on the most critical types of uncertainty to explore and may offer insights into how that uncertainty can be most usefully expressed. When uncertainties are large and relevant to the decision process, mapping may need to be directed to alternative actions supported by clearer evidence or more sufficient data, or mapping may be paused while expert elicitation techniques or additional data collection or experimentation are done to allow reduction of uncertainties and distinction of options.

While limitations abound, methods and data are sufficiently advanced to support a spatial action mapping approach. The diversity of case examples included here and extending throughout the literature make clear what is possible. The alternatives—assuming that protection will be the conservation action taken and basing spatial conservation planning on threat and asset snapshots—are misaligned with modern conservation decision making. These practices should be phased out.

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