Quasar and galaxy classification in Gaia Data Release 2

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ABSTRACT
We construct a supervised classifier based on Gaussian Mixture Models to probabilistically classify objects in Gaia data release 2 (GDR2) using only photometric and astrometric data in that release. The model is trained empirically to classify objects into three classes – star, quasar, galaxy – for \( G \geq 14.5 \) mag down to the Gaia magnitude limit of \( G = 21.0 \) mag. Galaxies and quasars are identified for the training set by a cross-match to objects with spectroscopic classifications from the Sloan Digital Sky Survey. Stars are defined directly from GDR2. When allowing for the expectation that quasars are 500 times rarer than stars, and galaxies 7500 times rarer than stars (the class imbalance problem), samples classified with a threshold probability of 0.5 are predicted to have purities of 0.43 for quasars and 0.28 for galaxies, and completenesses of 0.58 and 0.72 respectively. The purities can be increased up to 0.60 by adopting a higher threshold. Not accounting for this expected low frequency of extragalactic objects (the class prior) would give both erroneously optimistic performance predictions and severely impure samples. Applying our model to all 1.20 billion objects in GDR2 with the required features, we classify 2.3 million objects as quasars and 0.37 million objects as galaxies (with individual probabilities above 0.5). The small number of galaxies is due to the strong bias of the satellite detection algorithm and on-ground data selection against extended objects. We infer the true number of quasars and galaxies – as these classes are defined by our training set – to be 690 000 and 110 000 respectively (±50%). The aim of this work is to see how well extragalactic objects can be classified using only GDR2 data. Better classifications should be possible with the low resolution spectroscopy (BP/RP) planned for GDR3.

Key words: methods: data analysis – methods: statistical – surveys – astrometry – galaxies: general – quasars: general

1 INTRODUCTION
The Gaia mission is designed to target stars in our Galaxy (Gaia Collaboration 2016). Yet by recording all point-like objects brighter than some magnitude over the entire sky, it also observes many extragalactic objects. This is in fact desirable, because objects of effectively infinite distance are used to define the astrometric reference frame and to tie this to the International Celestial Reference Frame (ICRF) (Gaia Collaboration 2018b).

The Gaia data processing system includes modules to classify and characterize extragalactic objects both using the onboard low-resolution BP/RP spectrophotometry and astrometry (Bailer-Jones et al. 2008, 2013; Delchambre 2018; Tsalmantza et al. 2012) and by image reconstruction (Krone-Martins et al. 2013) (see also Proft & Wambsganss 2015). However, these results will only become available starting with the third Gaia data release planned for 2021.

The second Gaia data release (hereafter GDR2) provides, among other things, astrometry (positions, parallaxes, proper motions) and three-band photometry for up to 1.7 billion objects (Gaia Collaboration 2018a). There have been various efforts to identify extragalactic objects in the Gaia releases, mostly via a positional cross-match to other catalogues. Souchay et al. (2019), for example, cross-matched the Sloan Digital Sky Survey (SDSS) Data Release 14 quasar catalogue to GDR2, finding 399 000 counterparts within 1″. Secrest et al. (2015) identified 1.4 million Active Galactic Nuclei (AGN) in the mid-infrared AllWISE catalogue using a two-colour criterion defined by Mateos et al. (2012). The Gaia Collaboration (2018b) identified 557 000 of these in a cross-match to GDR2, which they used to put the GDR2 positions and proper motions on a global reference frame (called Gaia-CRF2) that is non-rotating relative to this sample. Their sample excludes detections within 5.7° of the Galactic plane, so the true number of AGN that Gaia can see will be higher.
Paine et al. (2018) cross-matched the same AGN sample from Secrest et al. (2015) to GDR1. This produced a sample of 568,000 AGN for $G < 20.7$ mag with an estimated 50% completeness. They claim a stellar contamination of just 0.2%, but as this is assessed from the fraction of their objects with SDSS spectra that are spectroscopically classified as stars, and SDSS spectroscopy is much less complete for stars than AGN, this must be an underestimate of the true contamination. Bai et al. (2018) used colours from Pan-STARRS1 and AllWISE to construct a machine learning method to classify 80 million objects with counterparts in GDR2 as stars, quasars, or galaxies.

Numerous studies have been published that classify stars using GDR2 data (typically combined with non-GDR2 data), but there are very few published works that classify extragalactic objects using GDR2 data. Heintz et al. (2018) looked for quasars by identifying objects with zero proper motion. When cross-matching these candidates to quasars colour-selected in WISE (the Wide-Field Infrared Survey Explorer), they conclude that within 1° of the north Galactic pole the contamination from stars for $G = 18$ to 20 mag was around 25%. Other studies have looked for (and found) tens of lensed quasars (e.g. Lemon et al. 2018; Delchambre et al. 2019).

In this paper we classify extragalactic objects in the GDR2 catalogue across the whole sky for $G \geq 14.5$ mag. In order to classify as many of the objects as possible using a homogenous set of data, we only use features from GDR2. These include the colours, astrometry, and a measure of photometric variability. Several studies have shown that good quasar classifications can be obtained from multiband optical and/or infrared photometry (e.g. Richards et al. 2015; Secrest et al. 2015; Jin et al. 2019), so including additional photometry would improve our classifications for objects that have such data. But beyond wanting to classify as much of GDR2 as possible, and doing so homogeneously, another motivation for this work is to determine how well classification can be done using a limited set of photometry and astrometry. The classifier we produce will contribute to the Discrete Source Classifier (DSC) in the Gaia data processing pipeline (Bailer-Jones et al. 2013). DSC classifies Gaia sources primarily using the dispersed BP/RP spectra, but when these spectra are noisy, blended, or ambiguous, classifications based on other features can improve performance.

We classify objects probabilistically into the three classes star, quasar, and galaxy. Our model is trained empirically, using a subset of the GDR2 data, with extragalactic class labels provided externally from a cross-match to SDSS. By not synthesising data we avoid many difficulties with selection functions, passbands, and zeropoints. As GDR2 has no explicit morphological information (although we will exploit the fact that some of the features are sensitive to non-point-like character), our definition of the galaxy class is a subset of what we normally understand this class to be. The "star" class is essentially defined as the complement of these (albeit with some contamination). Our method accommodates class imbalance: the fact that extragalactic objects are much rarer than stars in GDR2. This turns out to be very significant.

It should nonetheless be superseded by DSC’s classifications of a significant fraction of the Gaia objects, based primarily on BP/RP spectra, to be published as part of GDR3 in the second half of 2021.

2 DATA

All of the input data to the model – whether for the train, test, validation, or application phases – are drawn from GDR2. Both the train and test sets are drawn from the same sample; in particular they have their true classes determined in the same way (explained below). A validation set is one in which true classes have been determined by other authors from other data, and generally has a different feature distribution from the train/test set. An application set is one with unknown classes (here all of GDR2).

We build a model only for objects with $G \geq 14.5$ mag, as we expect few brighter unresolved extragalactic objects. The faint limit is $G = 21.0$ mag, set by the GDR2 catalogue.

2.1 Classes

We have three classes: stars, quasars, galaxies. As we are using a supervised learning algorithm, the definition of our classes is determined by the training data, which we now discuss.

2.2 Train and test data

There are two ways of constructing a training set. The first is synthetic, which uses models of the Gaia instruments to predict GDR2 data for simulated objects of known class. The second is empirical, in which we take GDR2 data for objects with classes determined from other surveys. We adopt the latter approach for a number of reasons:

(i) It is difficult to get consistent object models for the wide range of types of stars, quasars, and galaxies that Gaia observes;

(ii) It is difficult to model the Gaia data accurately. This is particularly true for the (integrated) photometry;

(iii) It is difficult to model the GDR2 selection function, which arises not only from the survey, but also from the data processing and the numerous decisions made by the consortium of what to include in the catalogue.

All of these difficulties would increase the misclassification rate, the magnitude of which would not be apparent from the test set. By constructing instead an empirical training set from GDR2, we are immune to many of these problems. We don’t need to worry about selection functions, photometric passbands, astrometric zeropoints, or the inflation of uncertainties and so forth, because these are the same in the training, testing, and application sets. What we do have to do, though, is assign classes reliably to a sufficient number of objects in GDR2 using information from other sources (which is not without its problems). We do this in the following way for each class.

2.2.1 Quasars

The SDSS-DR14 quasar catalogue contains 526,356 quasars that have been confirmed by optical spectroscopy (Pàris 2019).
Figure 1. The quasar redshift distributions (upper panel) and SDSS g-band magnitude distributions (lower panel) for the full SDSS sample (blue line, 446 134 objects), what remains after the cross-match with GDR2 (green line, 275 940 objects) and what remains for our train/test set (i.e. have all 8 features; black line, 209 287 objects). Each distribution is separately normalized.

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We then cross-match these to GDR2 by sky position. We then cross-match these to GDR2 in the same way as we did for the quasars, finding 321 965 matches. Of these, 19 261 have the complete set of eight GDR2 features we use in our classifier. This number is much smaller than one might expect given Gaia’s magnitude limit of \( G = 21.0 \) mag. The reduction (by a factor of 7.2) in the number of objects when making the cross-match is much more than with the quasars (factor of 1.6), because Gaia only records objects with point-like image profiles, so most galaxies are excluded already on-board the satellite. The exact impact of the on-board detection algorithm on what is recorded is rather complicated (de Bruijne et al. 2015). Many galaxies that were recorded were then removed during the on-ground data processing, in particular if they gave poor solutions for the colours. The Gaia colours are computed from low resolution slitless spectrophotometry (Evans et al. 2018), so they can be corrupted by neighbouring sources. This is crudely quantified by the flux excess factor (\( \text{phot\_bp\_rp\_excess\_factor} \)) in GDR2, and all sources with this factor above 5 were removed from the catalogue (Gaia Collaboration 2018a). Figure 2 shows that there is a significant change in the redshift and magnitude distribution of the SDSS sample when we require the cross-match with GDR2 (blue to green line): we lose high redshift and faint galaxies.

Of the 321 965 cross-matches we obtained, 94% have 2-parameter astrometric solutions, i.e. just positions but no parallax or proper motions, and 28% have no reported Gaia colours. The latter is almost entirely a subset of the former, i.e. almost everything that has no colour also has no parallax or proper motions. This explains most of the large reduction (by a factor of 17) in the number of objects when making the cross-match. Why so few galaxies have 5-parameter astrometric solutions, and why we nonetheless require this for our classifier, will be explained in section 2.5 below.

The Gaia colour-colour diagram of the remaining set of 19 261 objects is shown in Figure 3. In addition to the main bulk of galaxies in the upper left part of this plot, we see an additional, unexpectedly tight sequence of objects just below the grey dashed line. These are stellar contaminants, either errors in the SDSS classification, erroneous cross-matches to GDR2, or BP/RP spectra corrupted by blends with nearby AGN. Its authors estimate the contamination of this catalogue to be around 0.5%. We select those 446 134 objects that have the \texttt{zWarning} flag equal to zero, which indicates no issues with the classification or redshift determination. We then cross-match these to GDR2 by sky position with a 1" search radius using the CDS X-match tool, finding 275 940 matches. Of these, 209 287 have the complete set of eight GDR2 features we use in our classifier (defined in section 2.5) and \( G \geq 14.5 \) mag. Figure 1 shows the distribution of SDSS redshifts and magnitudes for the samples at each of the three phases of selection. We see that requiring a cross-match to GDR2 (blue to green line) and then also requiring all eight features (green to black line) shifts the population to brighter magnitudes each time, but that the redshift distribution is hardly affected in either case.

Earlier in this project we experimented with using a “quasar” training set constructed from the 557 000 AllWISE AGN cross-matched to GDR2 by Gaia Collaboration (2018b) (see section 1). When we used these to define our “quasar” training set, we obtained comparable results to those we report below in terms of completeness and purity. However, a training set constructed from mid-infrared data will be a different population from that which Gaia sees. In particular, it will include dust-obsured quasars that are not be visible in the optical, leaving just the unobscured host galaxy visible to Gaia that would nonetheless have a “quasar” training label.

2.2.2 Galaxies

Our galaxy train/test set is constructed from SDSS-DR15 (Aguado et al. 2019). We select all objects from the SpecObjAll table that have class equal to GALAXY and \texttt{zWarning} equal to zero, and that do not have subClass equal to either AGN or AGN BROADLINE. This gives 2 303 453 objects. We then cross-match these to GDR2 in the same way as we did for the quasars, finding 321 965 matches. Of these, 19 261 have the complete set of eight GDR2 features we need. This number is much smaller than one might expect given Gaia’s magnitude limit of \( G = 21.0 \) mag. The reduction (by a factor of 7.2) in the number of objects when making the cross-match is much more than with the quasars (factor of 1.6), because Gaia only records objects with point-like image profiles, so most galaxies are excluded already on-board the satellite.

Figure 2 shows that there is a significant change in the redshift and magnitude distribution of the SDSS sample when we require the cross-match with GDR2 (blue to green line): we lose high redshift and faint galaxies.

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Figure 2. The galaxy redshift distributions (upper panel) and SDSS g-band magnitude distributions (lower panel) for the full SDSS sample (blue line, 2,903,453 objects), what remains after the the cross-match with GDR2 (green line, 321,965 objects) and what remains for our train/test set (i.e. have all 8 features and have $g - rp \geq f(bp-g)$; black line, 18,499 objects). Each distribution is separately normalized.

Figure 3. Colour–colour diagram for the 19,261 galaxies selected for the train/test set. The grey dashed line – the “colour edge” – is the locus defined by $g - rp = f(bp-g)$ in equation 1. The 762 objects below this line are excluded from the train/test set. The smooth curved boundary at the top of the plot is a result of the cut in the flux excess factor imposed when GDR2 was constructed.

Although requiring the eight features led to a significant reduction in the number of galaxies, this (together with the colour cut) has little impact on the redshift and magnitude distribution (green to black line in Figure 2): there is just a slight increase in the proportion of the faintest and most-redshifted galaxies. This indicates that the lack of parallaxes and proper motions is hardly correlated with the galaxy magnitudes and redshifts.

2.2.3 Stars

Building the star training set in the same way as the quasars and galaxies ones is unwise, because the SDSS spectroscopic selection function for stars is complex, poorly determined, and is unlikely to have a desirable distribution over stellar types. We instead take advantage of the fact that, a priori, we expect most ($\geq 99.8\%$) of GDR2 objects to be stars (see section 4) and take a random subset of all GDR2 objects to represent the “star” class. Although we remove known quasars and galaxies as defined by the previous classes, this set will still be contaminated. Exactly how contaminated we don’t know, although the class prior (set in section 4) is the formal expectation. This contamination will inevitably reduce the accuracy of our classifications, albeit by a small amount here, and there is some hope that our model can generalize enough to be relatively insensitive to the contaminants. One must resist the temptation to identify the contaminants with the classifier, remove them from the training set, and then retrain the model, as this involves circular logic.
2.2.4 Size of training and testing sets

Our training set is a random subset of 100,000 stars, 100,000 quasars, and 10,000 galaxies from the samples defined above. The test is randomly constructed from the remaining objects, and comprises 100,000 stars, 100,000 quasars, and 8000 galaxies. We will deal with the issue of class imbalance – the different numbers of objects in each class – in section 3.4.

2.3 Validation data

We construct four validation sets in order to see how our model performs on data with very different properties and parameter distributions from our train/test sets. The first two of these we construct via a positional cross-match to GDR2, for which we use a 1'' radius. In all cases we retain only objects with all the eight features we need and $G \geq 14.5$ mag (these are the numbers given below).

The 2dF QSO Redshift Survey (2QZ) identified 23,338 quasars spectroscopically, spread over two narrow bands on the sky (Croom et al. 2004). A cross-match of these to GDR2 left 18,642 objects.

The 6dF galaxy survey (6dFGS) published spectra of 125,071 galaxies spread over the southern sky (Jones et al. 2009). A cross-match of those with a galaxy classification (8V$\geq$1) to GDR2 retained, after also removing any galaxies that lie beyond the colour edge (equation 1), 3017 objects.

Ting et al. (2018) compiled a set of 36,909 “pristine” (their term) red clump (RC) stars identified using APOGEE spectra, for which they estimate the contamination from non-RC stars to be 3% (their Table 2). We identify these in GDR2 using the GDR2-2MASS cross-match table provided in the Gaia archive. 10,111 of the objects have our eight features and $G \geq 14.5$ mag. Most of them are at low Galactic latitudes.

The final validation set we use is a random subset of 500,000 objects with distances below 500 pc with 95% confidence. These are drawn at random from those 19 million objects with $r_{\text{MAX}} < 500$ pc in the distance catalogue of Baier-Jones et al. (2018). This is likely to be quite a pure set of stars, although there may be some contamination from anomalous astrometric solutions (Lindegren et al. 2018). We refer to this set as the “nearby stars”.

2.4 Application data

The application data is the subset of GDR2 that has all eight features available and $G \geq 14.5$ mag. There are 1,203,405,908 such objects.

2.5 Feature selection

We use a total of eight features in our models: apparent magnitude ($G$), sine of the Galactic latitude ($\sin b$), parallax, total proper motion ($\sqrt{\mu_{\alpha}^{2} + \mu_{\delta}^{2}}$), blue colour ($b-p = G - G_{\text{BP}}$), red colour ($g-rp = G_{\text{RP}} - G$), relative variability in the $G$ band ($\text{relvarg}$), and the astrometric unit weight error (uwe). These features we now define and discuss.

$G$ is the very broad pass band used by Gaia for doing the astrometry. Figure 4 shows that its distribution varies somewhat among the three classes, as does that of the two Gaia colours. This can also be seen in the colour–magnitude and colour–galaxy classification in Gaia DR2
G [mag]
-1.0 -0.5 0.0 0.5 1.0
sinb
-4 -2 0 2 4
parallax [mas]
0 5 10 15 20
proper motion [mas/yr]
-1 0 1
bp−g [mag]
-0.5 0.0 0.5 1.0 1.5 2.0
bp−g [mag]
-0.5 0.0 0.5 1.0 1.5 2.0
g−rp [mag]
0.00 0.05 0.10 0.15 0.20 0.25
relvarg
0 1 2 3 4 5 6 7
uwe
training set
true classes
star
quasar
galaxy

Figure 4. The distribution of the eight features in the training set coloured according to their true classes. Black: stars, blue: quasars, orange: galaxies. Each distribution is separately normalized. sinb has been randomized for quasars and galaxies (constant probability per unit sky area).

\[
\sqrt{\frac{\text{astrometric\_chi2\_al}}{\text{astrometric\_n\_good\_obs\_al} - 5}).
\]

Larger values generally indicate a poorer fit to the astrometric solution, and it shows an enhanced value for some galaxies (Figure 4).

We investigated doing classification with a subset of these features. No one feature was critical. Performance degraded rather smoothly as features were removed. We also experimented with using other features in GDR2, such as the colour excess factor, but this did not improve performance. Other astrometric features such as the astrometric uncertainties or excess noise are quite correlated with uwe. Adding such features degraded performance (or did not improve it significantly), because they increase the dimensionality of the data space for little contribution of information. There is not a large amount of relevant, independent classification information in GDR2, and for a given number of training objects, lower-dimensional models are more robust than higher-dimensional ones.

3 METHODS

3.1 Classification model

Many machine learning methods have been developed and used for supervised classification. Most of these, such as support vector machines (SVMs) and neural networks (NNs), model the boundary between classes in a multivariate data space, and use this to explicitly assign each object to one class (e.g. Hastie et al. 2001). However, rather than performing such a “hard” classification, we want to do probabilistic classification, i.e. determine the probabilities that each object belongs to all of the classes. Not only does this give more flexibility in assigning classes (and thus adjusting the completeness and purity of samples, as we will see in later sections), it also provides us with a simple way of handling the crucial problem of class imbalance (in section 3.4). Although one can get machine learning methods like SVMs and NNs to map their outputs to the range 0–1, this does not necessarily produce a reliable probability when the target labels were just 0s and 1s.

Probabilistic classification can be performed with a Gaussian Mixture Model (GMM, e.g. Fraley & Raftery 2002). This models the distribution of the data in the \( p \)-dimensional feature space for each class using a sum of \( K \) Gaussians. Specifically, the probability density for a feature vector \( x \) in class \( C_k \) is

\[
P(x \mid C_k) = \sum_{q=1}^{Q} a_{k,q} \phi(x \mid m_{k,q}, V_{k,q})
\]

where \( \phi \) indicates the density of a normalized multivariate Gaussian of mean \( m \) and covariance matrix \( V \). The so-called mixing coefficients are subject to \( a_{k,q} \geq 0 \), and to \( \sum_{q=1}^{Q} a_{k,q} = 1 \) for all \( k \). A GMM with a sufficiently large number of components can in principle model any data distribution to arbitrary accuracy. The means, covariance matrices, and mixing coefficients of the Gaussians are determined by maximizing the likelihood over the training data. The GMM is then applied to a new object by computing the probability density for each class. When normalized, these values are the posterior class probabilities. This assumes equal class priors, but this will be relaxed (see section 3.4). A class is assigned by taking either the highest probability, or the highest probability that exceeds a threshold. In the
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Figure 5. Colour–magnitude diagram (top) and colour–colour diagram (bottom) for the training set coloured according to their true classes. Black: stars, blue: quasars, orange: galaxies (points plotted in that order). 10 000 objects have been selected at random from each class. The contours for each class (built from the entire train/test data set in each case) show equal spaced densities from 1/6 to 5/6 of the maximum density for that class. The classes overlap, so we have plotted them separately in Figure A1 in the appendix.

3.2 Terminology

The term true class cannot refer to some absolute truth, but rather to the assumed class, because the training, testing, and validation data inevitably have some labelling errors. The term assigned class refers to that which we assign using the probabilistic outputs of the classifier. Class fraction is the fraction of objects of each class within a sample, so it is something we can measure given the classes. Class prior is the class fraction we expect a sample to have, so is an assumption.

3.3 Performance metrics

We measure performance on the test set with the usual confusion matrix. Cell i,j (row, column) of this is the number of objects of true class i classified into class j. This is a $K \times K$ matrix if we classify by maximum posterior probability, and a $K \times (K+1)$ matrix if a threshold is used. The former contains $K^2$ independent numbers, but the performance can be usefully summarized using two metrics for each class:

- completeness (also called recall or sensitivity), the number of true positives as a fraction of all objects of that true class;
- purity (also called precision), the number of true positives as a fraction of all objects of that assigned class.

We will mostly be interested in the completeness and purity of the quasar and galaxy classes, as these objects are rare and thus harder to classify.

3.4 Handling class imbalance

A randomly selected sample of GDR2 objects will usually be dominated by stars, and thus have very unequal class fractions. This class imbalance must be accommodated both in the classifier design and in the reporting of results on a test set. Failure to do so gives both incorrect predicted performance on the test set and poor classification results on an application set. This can be seen by a simple example. Suppose we train a two-class classifier on the assumption of equal class fractions, and it gives a purity and a completeness of 0.9 in both classes on a balanced test set. If we now apply this classifier to an unbalanced data set with $s$ times as many objects of class 1 as of class 2, then although the completenesses are both still 0.9, the purities are $0.9s/(0.9s + 0.1)$ and $0.9/(0.1s + 0.9)$ respectively. For $s = 100$, these purities are 0.9989 and 0.0826 respectively. Class 1 dominates in this unbalanced set, so the class 2 output is dominated by

\[
\begin{pmatrix}
0.9s & 0.1s \\
0.1 & 0.9
\end{pmatrix}
\]

with $s = 1$ in training.
misclassifications, making the purity much lower than that expected based on the balanced test set.

The initial reaction to this problem might be to train and test the model on appropriately imbalanced sets. But this does not solve the problem, because a GMM models just the data distribution but not the amplitude in each class. In fact, most machine learning methods do not learn the relative sizes of the training set classes in a way that would accommodate class imbalance (as shown, for example, by Baier-Jones et al. 2008). Even if they did, then in order to get a sufficient number of training samples in the smallest class, we would need $s$ times as many training samples in the larger class, which may not be available. Resampling already noisy observed data to achieve this is unwise because it increases the noise further. Various ideas for dealing with this problem have been published in the machine learning literature (e.g. SMOTE from Chawla et al. 2002), but they are often complicated or cumbersome (e.g. by creating synthetic objects).

Fortunately, the problem is easily solved when using a probabilistic classifier like the GMM. When applied to a new feature vector $x$, the GMM provides the likelihoods (equation 2) for classes $k = 1 \ldots K$. These likelihoods are independent of the class balance in the training set, so we can train with whatever number of objects is necessary in order to fit each class adequately. Rather than just normalizing the likelihoods to give class probabilities (the equal prior case), we use Bayes’ theorem to combine them with the class priors $I = \{\pi_k\}$, to produce the posterior probabilities

$$P(C_k | x, I) = \frac{1}{Z} \pi_k P(x | C_k)$$

where $Z = \sum_k \pi_k P(x | C_k)$. As the posterior probabilities have changed, objects of a given true class (row of the confusion matrix) will be redistributed across assigned classes (columns of the confusion matrix). Thus changing the class prior generally changes both the completeness and purity.

In practice our class priors will never be equal to the true (unknown) class fractions, but any reasonable estimate (see section 4) will be far better than implicitly assuming equal class fractions. All results we report are from using posterior probabilities.

As this posterior classifier now assumes the data set has a particular class fraction, we will get a relevant confusion matrix only if the test set has the same class fraction. If only a limited number of test objects is available, it seems we would have to cut down the number of objects in the smallest class in order to achieve the required class fraction. This would not only waste test data, it would also increase the noise in our performance metrics due to small-number statistics. Fortunately there is a simple remedy: We can use a balanced test set and then re-weight the confusion matrix to reflect the class prior, by multiplying each row of the confusion matrix by $\pi_k$. The numbers in this modified confusion matrix are no longer integers in general, but this is unimportant when we compute the completeness and purity. This adjustment affects the purities (as that is a calculation across rows), but not the completenesses.

We can go one step further and adopt any size test set in each class that we like, e.g. to avoid small number statistics when a classifier would otherwise assign very few objects to an output class. If the class fractions in this test set are $\{\alpha_k\}$, then we multiply each row $k$ of the raw confusion matrix by the factor

$$\lambda_k = \frac{\pi_k}{\alpha_k} \left( \frac{1}{\sum_k (\pi_k/\alpha_k)} \right).$$

This scales the actual number of objects in each row to the number of objects expected for a test set with class fractions $\{\pi_k\}$.

### 3.5 A random classifier

If, for a two-class problem, the target data set has class fractions $(0.99, 0.01)$, then it is easy to achieve a high completeness and purity on the first class (e.g. just assign everything to be class 1). Thus at the minimum we should compare our performance to what a random classifier can do, defined as a classifier that assigns classes at random according to the class priors. For such a classifier the expected completeness and purity for class $k$ is $\pi_k$. We will use this as a reference in section 5.

### 4 ESTIMATION OF THE CLASS PRIOR

The relevant class prior is the expected class fraction in the sample of GDR2 data we will apply the classifier to. The only reliable way to determine these class fractions is if we had classifications for a representative subset of the data (here at least $10^6$ objects), but this does not exist.

Part of the class prior we can hope to estimate to some degree of accuracy, however. SDSS obtained spectra for as many galaxies and quasars as possible over a magnitude and wavelength range similar to Gaia’s. We can therefore use the values for the numbers of objects found in SDSS that cross-matched to GDR2 (together with the additional filtering) that we reported in sections 2.2.1 and 2.2.2. These were 209 287 quasars and 18 499 galaxies, a ratio of 11.3:1. If we just look at the subset in stripe 82, which is a more systematic survey of what Gaia can see over a range of Galactic latitudes, the numbers are 6952 quasars and 402 galaxies, a ratio of 17.3:1. Neither of these values is a very accurate representation of the true, unknown, ratio in GDR2, but it seems reasonable to adopt a class fraction of 15:1.

We cannot use SDSS in the same way to determine the ratio of stars to extragalactic objects, because stars were very selectively and sparsely targeted by SDSS. An early estimate during Gaia’s study phase suggested that of one billion objects observed by Gaia down to $G = 20$ mag, between one and ten million would be extragalactic (Perryman et al. 2001). The studies mentioned in section 1 found up to one million quasars or AGN in GDR2, which, among 1.7 billion sources, would imply a ratio to stars of 1700:1. However, these have certainly missed some quasars, especially at low Galactic latitudes. We choose to adopt a slightly higher ratio of 500:1.

We therefore adopt a class prior of $(\text{star, quasar, galaxy}) = (7500, 15, 1)$, which when normalized is $(0.997871, 0.001996, 0.000133)$. This is probably accurate only to within a factor of a few. While it will remain uncertain, it is the best we can do a priori, and is far better than assuming equal class priors. In section 5.1.3 we investigate the impact on our results of varying this.
One of the benefits of our method is that it is simple to adjust the class probabilities to reflect a different prior. One simply divides the posterior probabilities we provide by the prior we used, multiply by the new prior, and renormalize (as used, for example, Baier-Jones et al. 2008).

5 RESULTS

Training the classifier takes around 20 minutes using a single CPU core. When applied to a new object, the classifier gives the posterior probabilities for the three classes (the probability vector). To be consistent with our definition of galaxies in section 2.2.2, we must then make one modification. If an object has a colour beyond the colour edge of equation 1, i.e. has $g-r_p < f(bp-g)$, it cannot be a galaxy, so we set $P_{gal} = 0$ and renormalize the probability vector.

5.1 Results on test data

The distributions of the posterior class probabilities obtained on the test set are shown in Figure 6. This shows a peak towards high probabilities for the true class in all cases. For the quasars and galaxies there is also a lower peak at low probabilities for the true classes, indicating the loss of true objects due to overlap with the other classes in feature space. This plot is normalized separately for each class to allow an easier comparison of the probability distributions. In reality, quasars and galaxies are much rarer than stars.

5.1.1 Class assignment by maximum probability

We first assign classes by identifying the largest probability in the probability vector for each class. The resulting confusion matrix is shown in Table 1.3 We achieve a purity of 43% for quasars and 28% for galaxies. These are not particularly high: The features available in GDR2 are not providing a very strong discrimination is the presence of many more stars. But these purities are not that bad when we consider that they assume that only every 1 in 500 objects is a quasar and only every 1 in 7500 is a galaxy. The completenesses for both the quasars and galaxies are higher, at around 58% and 73% respectively. The purity on the galaxy class can vary by 3.5% when we take different random selections of the train and test sets, as quantified by the standard deviation indicated in the table. This is another consequence of the rarity of galaxies, as a small change in the modelling of the density of the star class can lead to a large change in the number of contaminants in the galaxy class.

Not using a class prior (or rather, assuming equal priors) in the classifier produces the completeness and purity shown in the penultimate column and row of Table 1. The most striking result is how impure the quasar and galaxy samples become: 95% of what we would classify as a quasar, and 99.5% of what we would classify as a galaxy, would be incorrect. This is because such a classifier doesn’t know that these classes are rare, so it assigns too many objects to them. Most of these are of the wrong class, so the purity is low. Because this equal-prior classifier is too liberal in classifying things as quasars and galaxies, it also captures more of them, and so the completenesses of these classes actually increases. But this cannot justify not using a prior, as a sample with such large contamination is nearly useless. (We discuss this further in section 5.1.3 below.)

5.1.2 Class assignment by threshold

We can instead choose to assign objects to classes only if the posterior probability exceeds a threshold. The higher the threshold, the higher the purity of the resulting sample, but the lower its completeness. This is shown in the upper panel of Figure 7. If we took a threshold of, say, 0.8 on the quasar output, then we would achieve a completeness of 0.45 and a purity of 0.52. The same threshold for galaxies would give a completeness of 0.65 and a purity of 0.40. If we consider the sum of the completeness and purity for the quasar and galaxy classes as a single metric (the red dot-dash line in the upper panel of Figure 7), then we see that a broad range of thresholds provides similar performance (although we might be able to do better, as we are free to use different thresholds on different classes).

Although a completeness of 1.0 can be achieved trivially by setting the threshold to zero, there is a limit to what purity can be achieved, even at very high thresholds. This is about 0.60 for both quasars and galaxies.

The price we pay when assigning thresholds is that a given object can either be assigned to more than one class (if the thresholds are low enough, e.g. all less than 0.5) or assigned to no class at all (if the thresholds are high enough) and so remain unclassified.

Table 2 shows the confusion matrices for thresholds of 0.5 and 0.8 (same on all classes). For 0.5 the completenesses and purities are very similar to those from taking the maximum probability (cf. Table 1), which makes sense when we see that just 0.001% of stars, 0.08% of quasars, and 0.7% of galaxies go unclassified. Raising the thresholds to 0.8 increases these to 0.3%, 27%, and 13% respectively. The lower panel of Figure 7 shows how the fraction of unclassified objects varies with the threshold.

5.1.3 Changing the class prior

The class prior is not well constrained (section 4), so what is the effect on the performance if we change it from the adopted value of $(\text{star, quasar, galaxy}) = (7500, 15, 1)$? We do not need to refit the GMM to do this, so it is easy to modify our classifications to reflect a different prior. Recall that when we change the class prior we not only modify the model output probabilities, but also the (effective) class fraction in the test set (as explained in section 3.4). This must be done to retain consistency of the meaning of the class prior.

If we increase the star:quasar ratio by a factor of two, but keep the quasar:galaxy ratio constant, so the class prior

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3 Recall that the confusion matrix has been adjusted as explained in the final paragraph of section 3.4. This adjustment only rescales each row; the ratios between the columns are unaffected. The raw confusion matrix is shown in Table B1. If we row-normalize the confusion matrix (i.e. so that each row sums to one; this gives the same result for both confusion matrices) we get, in each row, the probabilities that a single object is classified into the three classes.
Figure 6. The distribution of the three output probabilities (three panels) on the test set. The distributions for objects of the three true classes are shown in different colours (black: stars, blue: quasars, orange: galaxies). Each histogram in each panel is normalized. Note the logarithmic density scales. (The peak at low probabilities for stars in the right panel is under the one for quasars.)

Table 1. Confusion matrix (and derived metrics) on the test set when assigning classes according to maximum posterior probability. The confusion matrix itself is the $3 \times 3$ subtable in the upper-left corner: It shows the numbers of objects we would get if the test set had the same class fraction as the class prior (which is why they are not integers; see section 3.4). The completeness (compl.) and purity of each class derived from these numbers are shown in the next column and row. The following column and row marked “(stdev)” give the standard deviations in the completeness and purity over a set of 10 classifiers constructed with different randomly selected train/test sets. The penultimate column and row give, for comparison, the completeness and purity achieved if we adopt equal class priors in the classifier (with the same effective class fractions in the test as the main part of the table). The final column and row give the completeness and purity of a random classifier.

| true class | assigned class | equal prior: | random: |
|------------|----------------|--------------|---------|
| STAR       | star 99453 156 | 24.9 0.9982 0.9989 | 0.9989 |
| QUASAR     | 83.2 116 0.301 | 0.5811 ±0.0105 | 0.9674 0.0020 |
| GALAXY     | 3.46 0.164 9.67 | 0.7273 ±0.0184 | 0.9343 0.0001 |
| purity     | 0.9991 0.4251 0.2771 | <±0.0001 ±0.0164 ±0.0351 |
| (stdev)    |                |              |         |
| equal prior: purity | > 0.9999 0.0504 0.0052 |
| random: purity       | 0.9979 0.0020 0.0001 |

Table 2. As Table 1, but now assigning classes only if the posterior probability exceeds 0.5 (upper table) or 0.8 (lower table). “Unclassified” gives the (effective) number not classified into any class (as they have probabilities under the threshold), for each true class.

| threshold=0.5 | assigned class | | equal prior: |
| true class | star quasar galaxy unclassified | compl. | random: |
|------------|----------------|--------|---------|
| STAR       | 99452 156 24.9 | 0.996 0.9982 |
| QUASAR     | 83.1 116 0.267 | 0.151 0.5809 |
| GALAXY     | 3.43 0.143 9.62 | 0.0064 0.7240 |
| purity     | 0.9991 0.4250 0.2764 | |

| threshold=0.8 | assigned class | | equal prior: |
| true class | star quasar galaxy unclassified | compl. | random: |
|------------|----------------|--------|---------|
| STAR       | 99250 83.7 13.0 | 288 0.9961 |
| QUASAR     | 56.2 89.4 0.106 | 53.6 0.4488 |
| GALAXY     | 2.77 0.6548 8.67 | 1.79 0.6528 |
| purity     | 0.9994 0.5164 0.3991 | |
discriminating features (i.e. spectra) to classify them with an acceptable purity.

We now keep the star:quasar ratio constant, but increase the quasar:galaxy ratio to 30:1, so the class prior is now (7500, 15, 0.5). Quasar performance is virtually unchanged from the nominal results (in Table 1), but the galaxy completeness drops by 0.03 to 0.69 and the purity drops by 0.09 to 0.19. If, conversely, galaxies were twice as common as in the nominal class prior, i.e. (7500, 15, 2), then galaxy completeness and purity instead increase by the similar amounts, to 0.75 and 0.38 respectively.

The closer we push the class prior towards equal priors, the better the measured performance. Does this imply we should simply use equal priors? No, because the class prior is not is now (15,000, 15, 1), the purities for quasars and galaxies decrease to 0.31 and 0.20 respectively. The completenesses are also lowered, to 0.51 and 0.70 respectively. Increasing the star:quasar ratio by another factor of two, so quasars are now 2000 times rarer than stars (and galaxies 30,000 times rarer), the purities for quasars and galaxies become 0.21 and 0.14 respectively, and the completenesses 0.45 and 0.66. Clearly, if extragalactic objects were this rare, we would need more

![Figure 7](image_url)

**Figure 7.** Top: The variation of the completeness (dashed lines) and purity (solid lines) of each class (black: stars, blue: quasars, orange: galaxies) with the posterior probability threshold (same for all classes) used for assigning classes. This is computed on the test set. The red dot-dash line shows the average of the completeness and purity for the quasar and galaxy classes. Bottom: The corresponding variation in the fraction of objects in each true class that remain unclassified. The vertical axis in this panel only extends to 0.5 (where the probability is well above 0.999 for stars, 0.939 for quasars, and 0.993 for galaxies) but the lines continue up to 1.0.

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5.2 Results on validation data

We now apply our model to the validation sets described in section 2.3. These have neither the parameter distributions of our training data set nor the class fractions that our model is expecting, so the significance of these results should not be over-interpreted.

We first classify the quasars in 2QZ. 15,223 objects – a fraction of 0.82 of the total – are classified as quasars (by maximum posterior probability). This compares to an expected completeness of 0.58 (Table 1). The fact that 2QZ gives a higher completeness could just indicate that the feature distribution of 2QZ is tightly clustered on the higher probability regions for quasars that made our train/test set in Figure 4. In fact, the distributions of all the features are quite similar, except for Galactic latitude: the 2QZ sample is

![Figure 7](image_url)

**Figure 7.** Top: The variation of the completeness (dashed lines) and purity (solid lines) of each class (black: stars, blue: quasars, orange: galaxies) with the posterior probability threshold (same for all classes) used for assigning classes. This is computed on the test set. The red dot-dash line shows the average of the completeness and purity for the quasar and galaxy classes. Bottom: The corresponding variation in the fraction of objects in each true class that remain unclassified. The vertical axis in this panel only extends to 0.5 (where the probability is well above 0.999 for stars, 0.939 for quasars, and 0.993 for galaxies) but the lines continue up to 1.0.
located entirely at high latitudes, an indication to the model of lower star probability.

For objects in 6dFGS, only 42% are classified as galaxies by our classifier, compared to an expected completeness of 73%. The reason is the converse of the one just given for quasars: the 6dFGS galaxies (that match to GDR2) have quite a different distribution from our training set. In particular, they extend redder in \( bp-g \) and have far more sources that are bluer in \( g-rp \). They are also generally brighter and have an excess of objects with very low relvarg, which is absent in our training sample. This demonstrates the caution one must exercise when assessing performance on independent validation sets.

We next apply our model to the red clump stars. Our model classifies all of them as stars with very high confidence. The largest value of \( P_{qso} \) is \( 4 \times 10^{-6} \) and of \( P_{gal} \) is \( 5 \times 10^{-5} \). Ting et al. estimate their sample to have a 3% contamination, but this is presumably by other stars rather than quasars or galaxies.

Finally we apply our model to the 500,000 objects in the "nearby stars" validation set. 99.83% are classified as stars, quite a different distribution from our training set. In particular, they extend redder in \( bp-g \) and have far more sources that are bluer in \( g-rp \). They are also generally brighter and have an excess of objects with very low relvarg, which is absent in our training sample. This demonstrates the caution one must exercise when assessing performance on independent validation sets.

5.3 Results on application data (all of GDR2)

1,203,405,908 of the 1.69 billion objects in GDR2 have all eight features and \( G \geq 14.5 \) mag. Applying our classifier to these using a single CPU core took 17 hours. We find 2,287,566 objects with \( P_{qso} > 0.5 \) and 367,555 objects with \( P_{gal} > 0.5 \). If we instead classify according to the maximum probability, we get 2,297,133 quasars and 378,219 galaxies.

Defining the extragalactic probability as \( P_{ext} = P_{qso} + P_{gal} \), we find 2,690,021 objects with \( P_{ext} > 0.5 \). We call this the extragalactic sample. All other objects of course have \( P_{star} \geq 0.5 \) and so are classified as stars.

5.3.1 Distribution in feature space

The distributions of the features in the application set for objects with posterior probabilities greater than 0.5 are shown in Figure 8. These are colour-coded by the assigned class, and as the quasars and galaxies are predicted to have a contamination of more than 50% (see Table 2), care must be taken when comparing them to the features colour-coded by the true class in Figure 4.

We see that the distributions for the parallax, proper motion, and the two colours are quite similar for test and application for all three classes. Hence, most stellar contamination in the two extragalactic classes occurs from that subset of stars which have a very similar distribution in these parameters.

In contrast, the quasar and in particular the galaxy \( G \)-band magnitude distributions have peaks at fainter magnitudes in the application classes. This can be a result of both stellar contamination and the true objects in Gaia having a slightly fainter magnitude distribution than our (SDSS-based) training set. Recall Figure 1, which shows that the peak of the SDSS \( g \)-band magnitude distribution for the training set is at around 19.5. The distributions in colour and magnitude are also visualized in Figure 9, which can be compared to the corresponding diagrams for the true classes in the Figure 5 (compare also Figure A1 with A2).

Whereas the distributions for the quasars (and the stars) are quite similar, the galaxies in the application set show both a marked shift to fainter magnitudes and a change in the distribution for objects with \( g-rp \leq 1.5 \). These regions are in the tails of the training set distribution, and so were perhaps modelled less well by the GMM. The horizontal spur at \( G \geq 19 \) mag stretching between \( g-rp \geq 1 \) and 1.5 mag in the upper panel of Fig. 9 is predominantly stars in the Large and Small Magellanic clouds (LMC and SMC). We also see an excess of objects classified as galaxies along the colour edge (equation 1); these are predominantly stellar contaminants.

The latitude distribution in the applied classes shows that there is lower frequency of classified extragalactic objects at low latitudes. This is an expected consequence of dust absorption by the Galactic disk, which decreases the number of lines-of-sight through the Galaxy. The LMC/SMC and parts of the Galactic bulge are prominent peaks in the distributions for quasars and/or galaxies (explained in the next subsection).

We also see some differences in the distributions for relvarg. The galaxies show an excess of low amplitude variables in the application set. As the distribution for stars is ramping up towards low amplitudes, this is almost certainly a signal of the stellar contamination. Quasars show a more complicated change in relvarg, in particular an excess of higher amplitude variables. As there are relatively few stars with such high amplitudes, and there is very little contamination of galaxies into the quasars (see Table 2), this suggests that we are picking up a larger proportion of higher-amplitude variable quasars than we had in our training set.

Finally, the distribution of uwe is largely unchanged for the quasars, but the galaxy class now shows a second peak just below 2, and no longer the broad hump at around 4. There is no clear-cut reason for these, although the loss of the hump into the star class would not be noticeable in the distribution for stars, as they are far more numerous.

5.3.2 Distribution on the sky

Figure 10 shows the distribution on the sky of the \( P > 0.5 \) sample for each assigned class. The spatial distribution for stars follows our expectations, with a concentration of objects towards the Galactic plane and bulge.

The LMC and SMC stand out in all three panels. Wherever there is a high density of objects on the sky, like in the LMC/SMC, the density of misclassified objects will likewise be high, even if the misclassification rate is no higher. In addition to this, the LMC and SMC are so distant that the parallaxes and proper motions of their constituent stars are statistically insignificant, like many extragalactic objects, so we may also have a higher misclassification rate.

The distribution for quasars displays two features. First, there is a lower density at low latitudes that appears to follow the dust in the Milky Way. This complex pattern is not learned from the training data, because \( \sin b \) was random...
Figure 8. The distribution of the eight features for objects in the application set assigned to classes when the posterior probability is greater than 0.5. The colour indicates the assigned class, black: stars, blue: quasars, orange: galaxies. Each distribution is separately normalized.

ized for extragalactic objects in the training, and longitude is not used at all. The fact that we don’t find quasars in these regions is presumably because they are genuinely absent from the Gaia catalogue due to dust obscuration. The second feature is the presence of numerous stripes. These are a consequence of how Gaia scans the sky (on quasi great circles) and the fact that it performs on-board object detection independently each time it crosses the same point on the sky: Objects near the magnitude detection limit and/or in crowded regions may be recorded different numbers of times in each scan. This determines – together with various quality thresholds and filtering done during processing – whether or not an object has sufficient data to define all eight features required for our classification. Just as with the LMC/SMC, a variable number of objects produces a variable number of misclassifications, which is why the stripes are different for the three classes in Figure 10. (They are much less visible in the stars’ plot because the misclassification rate is so low.) There are many factors involved in determining this, so there is a not a simple mapping between the scanning law and the stripes we see. Further discussion and examples can be found in Arenou et al. (2018).

5.3.3 Distribution in WISE colours

Figure 11 shows the distribution of objects in our extragalactic sample in a WISE colour space. The bands W1, W2, and W3 are located at 3.4\,\mu m, 4.6\,\mu m, and 12\,\mu m respectively. 1.1 million objects in our sample (42%) have measurements in all three of these bands. We overplot the “wedge” defined by Mateos et al. (2012) to identify AGN. This wedge has been used by various authors, for example Paine et al. (2018) and Gaia Collaboration (2018b) who identified around half a million AGN in GDR1 and GDR2 respectively (see introduction). We see from Figure 11 that objects in our sample with the highest value of \( P_{qso} \) are found in this wedge. 66% of our extragalactic sample falls inside the wedge, with a median value of \( P_{qso} \) of 0.97 (the interquartile range is 0.823–0.998). The near horizontal slab of low \( P_{qso} \) objects at \( W1−W2 \approx 0 \) mag comprises high probability galaxies plus stellar contaminants. In the upper panel of Figure 11 we see a second clump of objects with high \( P_{qso} \) at \( W2−W3 < 2 \) mag, \( W1−W2 > 0 \) mag. Most of these have \( bp−g > 0.5 \) and \( g−rp > 1 \) and are therefore outside the main set of quasars in the training set (cf. Fig. A1). This classification of these objects as quasars is therefore an extrapolation of the GMM. This observation, together with the fact that most objects in this second clump are in dense regions on the sky (the Galactic plane or the LMC/SMC) and so may have spurious colours, suggests they are misclassifications. They are quite rare, however (just 3000 of the 1.1 million with WISE colours). The set of objects in Figure 11 with \( W2−W3 > 4 \) mag (and outside the wedge) with reasonably high \( P_{qso} \) do, in contrast, have a \( bp−g, g−rp \) colour distribution similar to the quasars in the training set, suggesting that many of them are indeed quasars (and they all lie outside of dense sky regions). A comparison with Figure 5 of Mateos et al. (2012) indicates that some of these could be objects for which the radiation emitted in these bands is dominated by the host galaxy.

5.3.4 Distribution in redshift

We obtain redshifts for our extragalactic sample from the SDSS-DR15 spectroscopic catalogue. We select all objects with non-negative redshifts that are class QSO or GALAXY.
9% and 4% respectively of our extragalactic sample. The distribution of these redshifts is shown in the upper panel of Figure 12. The quasars extend to much higher redshifts than the galaxies. 3.9% of the quasars in our extragalactic sample (that have redshifts) have \( z > 3 \), and 0.08% (165 objects) have \( z > 4 \). The shape of this distribution does not change much if we limit it to objects with \( P_{\text{qso}} > 0.8 \) or 0.9. Note, however, that if we limit the sample to only those sources that have visually-verified redshifts (those with a defined value of \( z_{\text{v1}} \) in SDSS, shown with the thick light-blue line), we lose the highest redshift objects. The lower panel shows these distributions expressed as a fraction of the number in SDSS-DR15 (for each redshift bin). The combination of the Gaia on-board detection together with our feature selection retains so few galaxies that the fraction for galaxies is virtually zero. For quasars, we find over 40% of quasars in SDSS-DR15 with redshifts between 0.2 and 2.0 (higher for the visually-verified subset), with the fraction dropping to higher and lower redshifts.

Figure 9. Colour–magnitude diagram (top) and colour–colour diagram (bottom) for objects in the application set assigned to classes when the posterior probability is greater than 0.5. The colour indicates the assigned class, black: stars, blue: quasars, orange: galaxies (plotted in that order). 10,000 objects have been selected at random from each class. The contours for each class (built from all the data in each case) show equal spaced densities from 1/6 to 5/6 of the maximum density for that class. The classes overlap, so we have plotted them separately in Figure A2 in the appendix.

5.3.5 Estimating the true class fraction from the posterior probabilities

We would like to estimate the true fraction of quasars and galaxies among the 1.20 billion objects in the application set. This is not straightforward due to the incompleteness and contamination, and there is more than one way to do it.

One approach is to use the posterior probabilities. If a set of \( N \) objects have posterior probabilities for class \( k \) of \( \{P_i\} \), then the expected number of objects that are truly of class \( k \) is \( \sum_i P_i \). For the complete set of objects in the application set this gives \( \hat{N}_{\text{qso}} = 3,502,040 \) and \( \hat{N}_{\text{gal}} = 505,367 \) (rounded to the nearest integer). These correspond to class fractions of \( 29 \times 10^{-4} \) for quasars and \( 4.2 \times 10^{-4} \) for galaxies. This is similar to the class prior for quasars \( (20 \times 10^{-4}) \), but three times larger than its value for galaxies \( (1.3 \times 10^{-4}) \). This may not be the best way to infer the true class fractions, however, because \( \sum_i P_i \) is dominated by many objects with very small probabilities. Such probabilities may be poorly defined, because they are often obtained from the tails of the Gaussian distributions that are less well constrained during the training. The probabilities also do not take into account the measurement uncertainties on individual objects, and there are inevitably outright misclassifications.

Two alternative ways of inferring the true class fractions that use the confusion matrix on the test set are explained in appendix B. These produce values consistent with each other, but that are five times lower than those obtained above. Because these only focus on the well-classified objects, we think these are more reliable. Our final inference of the true class fractions for quasars and galaxies (as defined by our training sets), for the 1.20 billion Gaia sources with all eight features and \( G > 14.5 \) mag, are \( 5.7 \times 10^{-4} \) and \( 0.91 \times 10^{-4} \) respectively, each with a 1σ uncertainty of about 50% (see Table B2). These correspond to 690,000 quasars and 110,000 galaxies. The former is consistent with the number of quasars that other authors have found in GDR2 by various means (see section 1).
Figure 10. Distribution in Galactic coordinates for objects in the application set assigned to classes when the posterior probability is greater than 0.5, shown separately for each class. Each plot shows the number of objects per healpix at level 7 (0.21 sq. deg.) on a logarithmic scale in an Aitoff (equal-area) projection. The Galactic centre is in the middle and longitude increases to the left. The panels for quasars and galaxies show all objects with $P > 0.5$, whereas the panel for stars is a random subset of one million objects with $P > 0.5$ (so multiply the scale for stars by about $10^3$ to get the true numbers per healpix).
Figure 11. WISE colours of objects in our extragalactic sample, colour coded by the mean $P_{\text{qso}}$ in small colour bins (upper panel), or by the density of objects as computed by a kernel density estimate (lower panel; the colour bar covers the full range of densities). Of the 2.7 million objects in this sample, 1.1 million have all three WISE colours and so are shown here. The grey dashed polygon indicates the wedge defined by Mateos et al. (2012) to identify AGN using these WISE colours.

6 THE CATALOGUE

We provide the results from the application of our model to GDR2 (described in section 5.3) as a catalogue with three columns 4: the GDR2 source identifier (a long integer), $P_{\text{qso}}$, and $P_{\text{gal}}$. The two probabilities are rounded off to the sixth decimal place. The star probability can be computed from $P_{\text{star}} = 1 - (P_{\text{qso}} + P_{\text{gal}})$, and all other data obtained by cross-matching to GDR2 using the source identifier. As our main goal is to identify extragalactic objects, we only report in this catalogue the extragalactic sample, i.e. those objects with

$$P_{\text{ext}} = P_{\text{qso}} + P_{\text{gal}} > 0.5.$$  

There are 2690021 such objects, a fraction 0.00224 of the 1.20 billion objects in GDR2 with all 8 features and $G \geq 14.5$ mag. The catalogue is sorted by increasing source_id.

The probabilities we provide assume the class prior of (star, quasar, galaxy) = (7500, 15, 1). To adopt a different prior, simply divide the probability vector for each source by this class prior, multiply by the new class prior, and renormalize.

This set of quasars and galaxies with $P_{\text{ext}} > 0.5$ is a superset of the set obtained by selecting by maximum probability. To see this, consider the necessary (and sufficient) conditions for assigning an object to the quasar class using maximum probability:

$$P_{\text{qso}} > P_{\text{gal}}$$  \hspace{1cm} (5a)

$$P_{\text{qso}} + \frac{1}{2} P_{\text{gal}} > \frac{1}{2}$$  \hspace{1cm} (5b)

the latter coming from $P_{\text{qso}} > P_{\text{star}}$. If this second condition is true then so is $P_{\text{qso}} + P_{\text{gal}} > 1/2$, the condition to be in the catalogue. The same argument applies for quasars when swapping $P_{\text{qso}}$ and $P_{\text{gal}}$. That the $P_{\text{ext}} > 0.5$ set can contain more objects than those obtained from maximum probability can be illustrated with the example $(P_{\text{star}}, P_{\text{qso}}, P_{\text{gal}}) = (0.44, 0.30, 0.26)$. This object would be in the $P_{\text{ext}} > 0.5$ set, but would not be classified as either quasar or galaxy using maximum probability. The two conditions in equation 5

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4 http://www.mpia.de/homes/calj/gdr2_class.html

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can be used to find those objects in the catalogue that are classified as quasars by maximum probability (and the set of galaxies is found by swapping $P_{\text{qso}}$ and $P_{\text{ext}}$ in the equations). The number of objects of each class in the catalogue with probabilities above a specified probability threshold are shown in Figure 13. The discontinuities at probabilities of 0.5 are a consequence of $P_{\text{ext}} > 0.5$.

The galaxy subset of our catalogue has considerable contamination, so should be used with caution. The quasar subset is also contaminated, but its higher probability quasar members that are absent in other catalogues could be targets for spectroscopic follow-up. They may also be useful for future realizations of astrometric reference frames. Our catalogue extends across the Galactic plane, in contrast to many other searches for quasars. When accounting for the contamination and incompleteness, the catalogue as a whole can also be used to estimate the class prior for future classification projects (see section 5.3.5).

## 7 SUMMARY AND CONCLUSIONS

We have used eight features based on photometry and astrometry from the second Gaia data release to identify quasars and galaxies. The purities of our samples are not particularly high according to our test set: 0.43 for quasars and 0.28 for galaxies (Table 1). Purities of up to 0.60 can be achieved when adopting a high threshold, but at the price of a smaller sample (section 5.1.2). This modest performance must nonetheless be seen in the context of the assumed rareness of the extragalactic objects (the class prior): 1 in 500 for quasars and 1 in 7500 for galaxies. The predicted completenesses are 0.58 for quasars and 0.73 for galaxies.

Our results are more satisfactory for quasars than they are for galaxies, not only in terms of sample purity, but also in terms of consistency with the training data and the nature of the contamination (sections 5.3.1 and 5.3.2). The Gaia detection algorithm and subsequent data filtering severely limit the number of galaxies available. This results in a rather non-standard definition of our “galaxy” class, and yields only a small training sample.

To achieve better results we would either need a narrower definition of our classes, so as to reduce the overlap in the feature space with stars (although this would make them even rarer), or we need features that better discriminate between the classes, e.g. spectra. The GMM classifier itself performs well: We would achieve purities of around 0.95 if the objects in the three classes were equally common (section 5.1.3).

Our classification approach is purely empirical, so both avoids the need to model the Gaia selection function and eliminates having to determine precise astrometric and photometric zeropoints and uncertainties. The resulting distribution of classified objects in feature space, e.g. in Galactic sky coordinates, of course still shows the signature of the Gaia selection function (in particular the magnitude limit and scanning law). As with any supervised machine learning method, our three classes – star, quasar, galaxy – are defined by the set of objects in their training sets.

We have shown that it is essential to incorporate an approximately-correct class prior into the classification process. This influences both the classification probabilities and the (effective) class fractions in the test set. If one instead assumes equal class priors (implicitly or explicitly), then the predicted purity of the rarer class(es) of objects will be hugely overestimated: Both the predicted purity would be higher – at around 0.95 for both quasars and galaxies – compared to the prediction using the correct class prior, and the actual purity considerably lower – 0.050 for quasars and 0.0052 for galaxies – compared to the model with the correct class prior (section 5.1.3).

Among the 1.20 billion objects in GDR2 that have $G \geq 14.5$ and the eight features we require, we identify 2.3 million objects as quasars and 0.37 million objects as galaxies, with individual posterior probabilities of 0.5 or more. We provide the classification posterior probabilities so that samples with a determinable trade-off between completeness and purity can be selected. The number of objects classified of course depends on the class prior to some degree (section 5.1.3). Our probabilities can easily be adjusted to reflect a different class prior from the one we adopted (section 6). Using the above measured numbers of objects together with the confusion matrix on the test data, we can infer the true number of extragalactic objects in the GDR2 sample (section 5.3.5).

We estimate 690 000 quasars and 110 000 galaxies, which correspond to class fractions of $5.7 \times 10^{-4}$ and $9.1 \times 10^{-4}$ respectively (the $1\sigma$ accuracy in these figures is about 50%). There are far fewer galaxies than quasars because the Gaia observing mode and data processing selects strongly against extended objects.

Better classifications for many objects could be obtained using additional non-Gaia data, such as additional optical and infrared photometry, although this is not available homogeneously for the 1.20 billion objects we classify here. Spectra would enable even better classifications, of course. We are expecting of order $10^8$ low resolution optical
(BP/RP) spectra to be released as part of the third Gaia data release, planned for 2021. We will use these spectra, supported by a classifier similar to the one described here, to provide object classifications in that data release. Use of these spectra should permit a better separation of the classes and furnish more reliable probabilities, and therefore allow us to construct purer samples than could be attained in the present work.

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APPENDIX A: DISTRIBUTION OF THE TRAINING FEATURES

Figures A1 and A2 are Figures 5 and 9 respectively, but with each class shown in a separate panel.

APPENDIX B: ESTIMATING THE TRUE CLASS FRACTION FROM THE MEASURED CLASS FRACTION AND THE CONFUSION MATRIX

B1 Inversion

We want to estimate the true fraction of objects \(t_i\) in each class \(k\). Let \(m_{ij}\) be the measured fraction of objects classified into class \(k\) (using maximum probability). The measured fraction differs from the true fraction because of incompleteness and because of contamination from other classes. Let \(c_{ij}\) be the fraction of true class \(i\) that is classified into measured class \(j\). When \(i = j\) this is the completeness of class \(j\), and when \(i \neq j\) this is the fraction of true class \(i\) that contaminates measured class \(j\). It follows that

\[
m_{ij} = c_{ij}t_j + \sum_{i \neq j} c_{ij}t_i .
\]  

(B1)

The \(c_{ij}\) are the elements \((i\text{th row, } j\text{th column})\) of the row-normalized (rows summing to one) confusion matrix. For a K-class problem, equation B1 gives a system of \(K\) linear equations in \(K\) unknowns, which can be written in matrix form as

\[
m = C^t \cdot t
\]  

(B2)

where \(m = \{m_{ij}\}\) and \(t = \{t_i\}\) are \(K\)-element column vectors. \(C^t\) is the transpose of the row-normalized confusion matrix and may be considered as a transition matrix. Equation B2 can be solved by matrix inversion to give an estimate of the true class fraction \(t\). Applying this to the measured class fractions found in section 5.3, along with the confusion matrix in Table 1, the estimate for the true class fractions is \(5.8 \times 10^{-4}\) for quasars and \(0.87 \times 10^{-4}\) for galaxies.
A difficulty here is that the confusion matrix is noisy, especially for galaxies, and this noise can be amplified and introduce asymmetry via the nonlinear operation of inverting $\mathbf{C}^T$. Another potential problem is that the elements of $\mathbf{t}$ are not constrained to be positive (although because $\mathbf{m}$ is normalized, equation B2 ensures $\mathbf{t}$ is too).

### B2 Trinomial likelihood

A more robust estimate of $\mathbf{t}$ can be obtained using total regression. We consider $\mathbf{C}$ as a measured, noisy version of the true, unknown confusion matrix $\mathbf{C}$. If we had this, then the measured class fraction would be $\bar{\mathbf{m}}$, i.e., $\bar{\mathbf{m}} = \mathbf{C}^T \mathbf{t}$ (and equation B2 is an approximation which we now don’t use).

We model the number of objects classified into the three classes in the application data set – call these $N_1$, $N_2$, and $N_3$ – with a trinomial likelihood that depends on $\bar{\mathbf{m}}$, i.e.

$$P(N_1, N_2, N_3 \mid \bar{\mathbf{m}}, \sum_k N_k) \propto \bar{m}_1^{N_1} \bar{m}_2^{N_2} \bar{m}_3^{N_3}.$$  \hspace{1cm} (B3)

We can write down a similar trinomial likelihood for the elements in the first row of the (unnormalized) confusion matrix – call these $\{n_{1j}\}$ – in terms of the first row of $\bar{\mathbf{C}}$, and likewise for rows 2 and 3. The joint likelihood for $\{N_k\}$ and $\{n_{ij}\}$ is then

$$L = P(N_1, N_2, N_3 \mid \bar{\mathbf{m}}, \sum_k N_k) \times \prod_{i=1}^3 P(n_{1i}, n_{2i}, n_{3i} \mid \bar{C}_i, \sum_j n_{ij})$$  \hspace{1cm} (B4)

where $\bar{C}_i$ indicates the $i$th row of $\bar{\mathbf{C}}$. Note that the numbers $\{n_{ij}\}$ are not the elements of the (modified) confusion matrix in Table 1, as those numbers have been adjusted to be appropriate for a test set with class fractions equal to the class prior. For the trinomial likelihood we must instead use the actual numbers in the confusion matrix prior to adjustment. These are given in Table B1.

---

**Table B1.** The raw confusion matrix (i.e. before multiplying each row by $\lambda_i$ from equation 4) corresponding to Table 1.

|       | star | quasar | galaxy |
|-------|------|--------|--------|
| STAR  | 99818| 157    | 25     |
| QUASAR| 41735| 58114  | 151    |
| GALAXY| 2083 | 99     | 5818   |

---

Figure A1. Colour–magnitude diagrams (top) and colour–colour diagrams (bottom) for the training set plotted in separate columns according to their true classes. From left to right: stars, quasars, galaxies. The contours for each class (built from the entire train/test data set in each case) show equal spaced densities from $1/6$ to $5/6$ of the maximum density for that class. This is the same plot as Figure 5 but with each true class in its own panel.
Figure A2. Colour–magnitude diagrams (top) and colour–colour diagrams (bottom) for objects in the application set assigned to classes (columns of this plot) when the posterior probability is greater than 0.5. From left to right: stars, quasars, galaxies. The contours for each class (built from all the data in each case) show equal spaced densities from $1/6$ to $5/6$ of the maximum density for that class. This is the same plot as Figure 9 but with each assigned class in its own panel.

The likelihood in equation B4 has eight unknowns (three elements of $\mathbf{t}$, plus nine elements of $\mathbf{C}$, minus four normalization constraints). The maximum of this has no analytic solution, so we instead adopt a uniform prior on the parameters and sample the resulting posterior using a Markov Chain Monte Carlo algorithm. We summarize the resulting marginal distributions over each element of $\mathbf{t}$ using the median and the central 68% confidence interval. These are reported in the bottom two lines of Table B2 along with other estimates for comparison.

The class fractions in GDR2 estimated in this way are similar to what we obtained from the simple inversion (line 2 of the table). They are of course lower (by a factor of about 3.5) than the class fractions obtained from just counting the number of objects classified by maximum probability (line 2), because this latter estimate obviously includes contaminants. They are also lower than the expected true fractions we computed in section 5.3.5 using the sum of the posterior probabilities (line 3); see that section for more discussion.

Table B2. Estimates of the class fractions of galaxies and quasars among the 1.20 billion sources in GDR2 that have all eight features. The first line is the class prior. The second is the fraction obtained when we assign classes according to maximum probability. This estimate is affected by both the incompleteness and contamination of the classifier which we attempt to correct for in the next two lines. The third line gives the expected true fraction computed from the sum of the posterior probabilities (see section 5.3.5). The fourth line uses a direct inversion of equation B2 to estimate the true class fraction from this measured class fraction. The fifth line is a more robust estimate of this true class fraction by modelling the likelihood of both the measured class fraction and confusion matrix via the trinomial distribution; the final line expresses the uncertainty in this estimate.

| Method            | quasars     | galaxies    |
|-------------------|-------------|-------------|
| class prior       | $20 \times 10^{-4}$ | $1.3 \times 10^{-4}$ |
| measured          | $19 \times 10^{-4}$ | $3.1 \times 10^{-4}$ |
| posterior probabilities | $29 \times 10^{-4}$ | $4.2 \times 10^{-4}$ |
| inversion         | $5.8 \times 10^{-4}$ | $0.87 \times 10^{-4}$ |
| trinomial likelihood | $5.7 \times 10^{-4}$ | $0.91 \times 10^{-4}$ |
| (68% confidence interval) | $3.6–7.8 \times 10^{-4}$ | $0.37–1.5 \times 10^{-4}$ |