Moran-type bounds for the fixation probability in a frequency-dependent Wright–Fisher model

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Abstract We study stochastic evolutionary game dynamics in a population of finite size. Individuals in the population are divided into two dynamically evolving groups. The structure of the population is formally described by a Wright–Fisher type Markov chain with a frequency dependent fitness. In a strong selection regime that favors one of the two groups, we obtain qualitatively matching lower and upper bounds for the fixation probability of the advantageous population. In the infinite population limit we obtain an exact result showing that a single advantageous mutant can invade an infinite population with a positive probability. We also give asymptotically sharp bounds for the fixation time distribution.

Keywords Evolutionary game dynamics · Stochastic dynamics · Finite populations · Strong selection
1 Introduction

Evolutionary game theory (Hofbauer and Sigmund 1998; Maynard Smith 1982; Nowak 2006; Sandholm 2010; Weibull 1997) is a mathematically accessible way of modeling the evolution of populations consisting of groups of individuals which exhibit different forms of behavior. It is commonly assumed within this theoretical framework that individuals reproduce or adopt their behavior according to their fitness, which depends on the population composition through a parameter representing utility of a random interaction within the population. The fundamental interest of the theory is in understanding which forms of behavior have the ability to persist and which forms have a tendency to be driven out by others.

In the language of game theory, behavior types are called strategies and the utility is identified with the expected payoff in an underlying game. The basic biological interpretation is that each strategy is linked to a phenotype in the population and more successful types of behavior have higher reproductive fitness. In applications to the evolution of social or economic behavior, the propagation of strategies can be explained by an interplay between cultural inheritance, learning, and imitation (Nowak et al. 2010; Sandholm 2010; Traulsen et al. 2009, 2010).

In the case of finite populations, the evolutionary dynamics is typically modeled by a discrete-time Markov process such as Moran and Wright–Fisher processes (Fudenberg et al. 2006; Imhof and Nowak 2006; Lessard and Ladret 2007; Taylor et al. 2004; Traulsen and Hauert 2009). In this paper we focus on the evolutionary game dynamics of the Wright–Fisher process introduced by Imhof and Nowak (2006). In this discrete time model, there are two competing types of individuals in a population of fixed size whose fitness depends, up to a certain selection parameter, on the composition of the population (type frequencies). During each generation every individual is replaced by an offspring whose type is determined at random, independently of others, based on the fitness profile of the population. The resulting model is a discrete-time Markov chain whose states represent the number of individuals of one of the two types present in the current generation.

The Markov chain has two absorbing states corresponding to the situation where one of the two types becomes extinct and the other invades the population. The study of the probability of fixation in an absorption state representing a homogeneous population thus becomes a primary focus of the theory (Allen and Tarnita 2014; Lessard and Ladret 2007; McCandlish et al. 2015; McCandlish and Stoltzfus 2014; Patwa and Wahl 2008). Following common jargon in the literature, we will occasionally refer to the evolution of the Markov process until fixation as the invasion dynamics of the model. For recent progress in evolutionary game theory on graphs, we refer the reader to Cox and Durrett (2016), Durrett (2016), Evilsizor and Lanchier (2016), Foxall and Lanchier (2016) and the references therein.

Formally, the Wright–Fisher process introduced in Imhof and Nowak (2006) can be seen as a variation of the classical Wright–Fisher model for genetic drift (Durrett 2010b; Etheridge 2011; Ewens 2004; Gale 1990) with a frequency-dependent selection
mechanism. Throughout the paper we are concerned with the generic case of the selection that systematically favors one of the two population types. We thus will impose a condition ensuring that the local drift of the Markov chain (i.e., the expected value of the jump conditioned on the current state of the Markov chain) is strictly positive at any state excluding the two absorbing states. Since the fitness in Imhof and Nowak’s model is determined by the payoff matrix of a game, this condition turns out to be essentially equivalent to the assumption that one of the strategies in the underlying $2 \times 2$ game is dominant.

The main goal of this paper is to derive qualitatively matching upper and lower bounds for the fixation probability of the model. The bounds become sharp in the limit of the infinite population, but even for a fixed population size they have similar mathematical form and thus capture adequately the invasion dynamics of the model. The core of the paper is an exploration of Moran’s method (1960) and its ramifications in our framework.

The rest of the paper is organized as follows. The underlying model is formally introduced in Sect. 2. Our results are stated and discussed in Sect. 3. Conclusions are outlined in Sect. 4. The proofs are deferred to Sect. 5. Finally, an analogue of our main result for a related frequency-dependent Moran model, which has been introduced in Nowak et al. (2004), Taylor et al. (2004), is briefly discussed in the “Appendix”.

2 Mathematical model

The Wright–Fisher Markov process introduced in Imhof and Nowak (2006), which we now present, describes the evolution of two competing types of individuals in a population of fixed size $N$ evolving in discrete non-overlapping generations. Individuals of the first type follow a so-called strategy $A$ and those of the second type follow a so-called strategy $B$. The underlying $2 \times 2$ symmetric game is described by the payoff matrix

\[
\begin{array}{cc}
A & B \\
A & a & b \\
B & c & d
\end{array}
\]

where $a, b, c, d$ are given positive constants. The matrix entries $a, b, c, d$ represent the utility of an interaction of (the individual of type) $A$ with $A$, $A$ with $B$, $B$ with $A$, and $B$ with $B$, respectively, for the first named individual in the pair.

We denote by $X_t^{(N)}$ the number of individuals following strategy $A$ in the generation $t \in \mathbb{Z}_+$. Here and henceforth $\mathbb{Z}_+$ stands for the set of nonnegative integers $\mathbb{N} \cup \{0\}$, where $\mathbb{N}$ denotes the set of positive integers. With each of the two strategies is associated a fitness, which, when $X_t^{(N)} = i$, is given respectively by

\[
f_N(i) = 1 - w + w\pi_A(i, N) \quad \text{and} \quad g_N(i) = 1 - w + w\pi_B(i, N),
\]

where $w \in [0, 1]$ is the so called selection parameter, while
\[
\pi_A(i, N) = \frac{a(i - 1) + b(N - i)}{N - 1} \quad \text{and} \quad \pi_B(i, N) = \frac{ci + d(N - i - 1)}{N - 1}
\]
are expected payoffs in a single game with a randomly chosen, excluding self-interaction, member of the population. The selection parameter \( w \) is a proxy for modeling the strength of the effect of interactions (governed by the payoff matrix) on the evolution of the population compared to inheritance.

Given that \( X_t^{(N)} = i \), the number of individuals in the next generation adopting strategy \( A \) is described by \( N \) independent Bernoulli trials with success probability given by

\[
\xi^*_N(i) = \frac{i f_N(i)}{i f_N(i) + (N - i) g_N(i)}.
\]

Thus, conditionally on \( X_t^{(N)} \), the next generation \( X_{t+1}^{(N)} \) is a binomial random variable \( \text{BIN}(N, \xi^*_N(X_t^{(N)})) \) centered around \( N \xi^*_N(X_t^{(N)}) \):

\[
P \left( X_{t+1}^{(N)} = j \mid X_t^{(N)} = i \right) = \binom{N}{j} \left( \xi_N(i) \right)^j \left( 1 - \xi_N(i) \right)^{N-j}
\]
for all \( 0 \leq i, j \leq N \). The Wright–Fisher Markov chain with transition kernel in the form (2) comprises a class of classical models of population genetics (Durrett 2010b; Etheridge 2011; Ewens 2004; Gale 1990). Under the assumptions on the underlying game stated below in this section, the most mathematically related case is a model of genetic drift in a diploid population with favorable selection and without mutation, which formally corresponds to choosing a payoff matrix with \( a = b > 1 \) and \( c = d = 1 \).

Note that the Markov chain has two absorbing states, 0 and \( N \), which correspond to the extinction of individuals using one of the two strategies. Our primary objective in this paper focuses on the estimation of the following fixation (absorption at \( N \), or yet alternatively, invasion) probability:

\[
p_N(i) = P \left( X_T^{(N)} = N \mid X_0^{(N)} = i \right),
\]
where

\[
T = \min \left\{ t \in \mathbb{N} : X_t^{(N)} = 0 \text{ or } X_t^{(N)} = N \right\}.
\]
Throughout the paper we are interested in the dependence of \( p_N(i) \) on \( i \) and \( N \) while the parameters \( a, b, c, d \) and \( w > 0 \) are maintained fixed. We make the following standing assumption.

**Assumption 1** We assume that \( w > 0, a > c, \) and \( b > d \).

We remark that in the notation of Taylor et al. (2004), Assumption 1 reads \( w > 0, \xi > 0, \) and \( \zeta < 0. \) Moreover, under Assumption 1, \( A \) is the strictly dominant strategy in
the underlying game, and the implementation of strategy \( A \) by both players corresponds to the unique Nash equilibrium and the unique evolutionary stable strategy. Strictly speaking, an evolutionary stable strategy is a stationary distribution or an absorbing state of the process identified with the corresponding Dirac measure. In particular, the unique evolutionary stable strategy is the state where all players follow strategy \( A \) Hofbauer and Sigmund (1998), Weibull (1997).

A canonical example of a game satisfying Assumption 1 is the prisoner’s dilemma where \( b > d > a > c \), in which case strategy \( A \) represents defection and strategy \( B \) represents cooperation. Examples of games with \( b > a > c > b \) (Time’s sales versus Newsweek’s sales and cheetahs and antelopes, respectively) are considered in Dixit and Nalebuff (1991, Section 3.2) and Karlin and Peres (2014, Section 3.2). Another version of the cheetahs and antelopes discussed in Section 3.2 of Karlin and Peres (2014) provides an example of a game where \( b > c > a > d \). The invasion dynamics for two examples of a frequency-dependent Moran process with an underlying game such that \( a > c > b > d \) is analyzed in Taylor et al. (2004).

A connection between Assumption 1 and the structure of the local drift of the Markov chain \( X^{(N)} \), which is crucially important for our agenda, is discussed in Sect. 3.3. In the rest of this section we focus on more technical aspects and immediate implications of this assumption.

For an integer \( N \geq 2 \), let \( \Omega_N \) and \( \Omega_N^o \) denote the state space and the set of transient (non-absorbing) states of \( X^{(N)} \), respectively. That is,

\[
\Omega_N = \{0, 1, \ldots, N\} \quad \text{and} \quad \Omega_N^o = \{1, \ldots, N - 1\}. \tag{5}
\]

It has been pointed out in Taylor et al. (2004) (for a related frequency-dependent Moran process which we discuss in the Appendix) and Imhof and Nowak (2006) (for the Wright–Fisher process considered in this paper) that, to a large extent, the invasion dynamics of the model for a given population size \( N \) can be characterized by the behavior of the sign of the function \( h_N(i) = f_N(i) - g_N(i) \), and that the latter is entirely determined in the whole range \( i \in \Omega_N^o \) by the pair

\[
\{ \text{sign}(h_N(1)), \text{sign}(h_N(N - 1)) \}.
\]

Using the linear structure of \( f_N(i) \) and \( g_N(i) \), it is straightforward to verify that Assumption 1 is equivalent to the following.

**Assumption 2** We assume that the parameters \( a, b, c, d, w > 0 \) are chosen in such a way that there exist an integer \( N_0 \geq 2 \) and real constants \( \alpha \) and \( \gamma \) such that

\[
0 < \alpha \leq \frac{g_N(i)}{f_N(i)} \leq \gamma < 1 \quad \text{for all} \quad N \geq N_0 \text{ and } i \in \Omega_N^o. \tag{6}
\]

Assumption 2 can be thought of as a uniform over \( N \) version of the A-dominance condition \( h_N(0) > 0 \) and \( h_N(N) > 0 \) introduced in Nowak et al. (2004), Taylor et al. (2004) (\( \xi' > 0 \) and \( \zeta' < 0 \) in their notation).
As alluded to above, for a fixed \( N \in \mathbb{N} \), both \( f_N(i) \) and \( g_N(i) \) are linear functions of \( i \), and hence their graphs are straight segments. It follows that, if Assumption 2 is satisfied, one can set

\[
N_0 = \min \{ N \geq 2 : a(N - 1) > cN - d \text{ and } b(N - 1) > d(N - 2) + c \},
\]

and

\[
\alpha = \min \left\{ \frac{g_{N_0}(1)}{f_{N_0}(1)}, \frac{g_{N_0}(N_0 - 1)}{f_{N_0}(N_0 - 1)}, \lim_{N \to \infty} \frac{g_N(1)}{f_N(1)}, \lim_{N \to \infty} \frac{g_N(N - 1)}{f_N(N - 1)} \right\}, \\
\gamma = \max \left\{ \frac{g_{N_0}(1)}{f_{N_0}(1)}, \frac{g_{N_0}(N_0 - 1)}{f_{N_0}(N_0 - 1)}, \lim_{N \to \infty} \frac{g_N(1)}{f_N(1)}, \lim_{N \to \infty} \frac{g_N(N - 1)}{f_N(N - 1)} \right\},
\]

in order to obtain \( \alpha, \gamma \) and \( N_0 \) explicitly in terms of the basic data \( a, b, c, d \) and \( w \). Also, notice that

\[
\lim_{N \to \infty} \frac{g_N(1)}{f_N(1)} = \frac{d}{b} \quad \text{and} \quad \lim_{N \to \infty} \frac{g_N(N - 1)}{f_N(N - 1)} = \frac{c}{a}.
\]

**Remark 1** We emphasize that (6) is assumed to hold for a given specific choice of the (strictly positive) parameters \( a, b, c, d \) and \( w \). In fact, by continuity, (6) remains true within some interval of values \( w > 0 \) bounded away from zero, but ultimately fails when \( w \) approaches zero because \( \frac{g_N(i)}{f_N(i)} = 1 \) for \( w = 0 \). However, throughout the paper, the parameter \( w \) remains fixed and is not varied.

### 3 Results and discussion

The organization of this section is as follows. The section is divided into five subsections, the first two contain a preliminary discussion and the other two present our main results. Section 3.1 aims to provide a brief background and a suitable general context for our approach and results. It also contains a summary of our main results, which consist of Theorems 4 and 7. Section 3.2 discusses relevant results of Imhof and Nowak (2006) from the perspective outlined in Sect. 3.1. In Sect. 3.3 we state our results for a fixed finite population of size \( N \), and in Sect. 3.4 we discuss their asymptotic counterparts in the infinite population limit and some implications. Finally, in Sect. 3.5 we illustrate our results with a numerical example.

#### 3.1 Preliminary discussion

In Imhof and Nowak (2006) it is shown, among other results, that under Assumption 1 the selection in the Wright–Fisher process favors \( A \) in that \( p_N(i) > i/N \) for all \( i \in \Omega^N_N \). Notice that \( i/N \) is the probability that \( A \) wins in the absence of selection, i.e., when \( w = 0 \). Our goal is to obtain a further insight into the behavior of the fixation
probability $p_N(i)$ as a function of $i$ and $N$. Our main contribution can be partially summarized as follows:

**Theorem 3** (Main results in a nutshell) Let Assumption 1 hold. Then, for the Wright–Fisher process defined in (1) and (2), there exist constants $\rho, \theta \in (0, 1)$ such that

$$\frac{1 - \rho^i}{1 - \rho^N} \leq p_N(i) \leq \frac{1 - \theta^i}{1 - \theta^N}, \quad \text{for all } N \geq N_0, \ i \in \Omega_N^o. \quad (8)$$

Furthermore, there exists a constant $q \in [\theta, \rho]$ such that

$$\lim_{N \to \infty} p_N(i) = 1 - q^i, \quad \forall \ i \in \mathbb{N}. \quad (9)$$

The first part of the above theorem is the content of Theorem 4, and the second one in a more detailed form is stated in Theorem 6. Notice that the limit in (9) has the same form $1 - c^i$ for some $c \in (0, 1)$ as the asymptotic of the lower and upper bounds in (8). In intuitive accordance with the fact that $A$ is the unique Nash equilibrium and evolutionary stable strategy in the underlying game, (9) implies that a single advantageous mutant has a non-zero probability of invasion even at the infinite population limit.

The Wright–Fisher Markov chains with directional selection (i.e. favoring one of the two population types), either the classical one with constant selection bias $g_N(i)/f_N(i)$ or the more general one with the frequency dependent selection mechanism introduced in Imhof and Nowak (2006), are known to exhibit complex multi-scale dynamics. We refer to Durrett (2010b, Section 6.3.1), Ewens (2004, Section 1.4.3), Buckley and Pollett (2010, Section 3), and Chalub and Souza (2014), Waxman (2011) for a description of several possible scaling schemes and limiting procedures for these models. Due to the high likelihood of big jumps and space-wise inhomogeneity of the local drift, obtaining a quantitative insight into a mechanism of transforming a relatively simple structure of the transition kernel into the global dynamics of these Markov chains turns out to be a challenging task. The usual approach to overcome the difficulty is to implement a small parameter expansion which, although often formally not limited to any particular drift structure, ultimately leads to the (conceptually undesirable) comparison of the model to stochastic processes without drift.

When $w$ is small—a regime commonly referred to as weak selection—the fitness of individuals plays little role on the dynamics of evolution, and rather it is simply the proportions of the previous generation which play the primary role in determining the next generation.

The main content of our work is an alternative method, which is in essence equivalent to an indirect coupling of the Imhof-Nowak model with an “exponential submartingale”. In particular, this method allows us to considerably improve the previous work in Imhof and Nowak (2006) and obtain qualitatively matching lower and upper bounds for the fixation (absorption) probabilities in this model.

Using explicit formulas available for the Moran chain, it can be verified that if $g_N^o(i)/f_N^o(i) = q \in (0, 1)$ for all $N \in \mathbb{N}$ and $i \in \Omega_N^o(i)$, then
\[ p_N(i) = \frac{1 - q^i}{1 - q^N}. \] (10)

This example formally corresponds to the payoff matrix \( a = b = 1 + \frac{1}{w} \frac{1 - q}{1 - q^N} \) and \( c = d = 1 \). The expression for the absorption probability in the form \( p_N(i) = \frac{1 - q^i}{1 - q^N} \) is universal for finite-state Markov chains \( X_t \) with a space homogenous transition kernel and positive average drift for which a constant \( q \in (0, 1) \) can be found such that \( M_t = q^{X_t} \) is a martingale (see, e.g., Durrett 2010a). Fixation probabilities for the diffusion approximation of the classical Wright–Fisher model with selection are in the form \( p_N(i) = \frac{1 - q^i}{1 - q^N} \), which is similar. This form of the fixation probability is believed to be universal for a large class of evolutionary models in structured populations (Adlam and Nowak 2014). Results similar to (10) for the Wright–Fisher process were obtained by Kimura via diffusion approximations (see also Ewens 2004). However, these results are only valid for large population sizes and Markov chains that move by small steps, i.e. \( w = 1 - r \) is sufficiently small.

The proof of the bounds for a given population size relies on identifying “exponential sub- and super-martingales” dominating the process [we remark, for instance, that for a linear Brownian motion \( B_t + \mu t, \mu > 0 \), the proper choice is \( \rho = e^{-2\mu} \) by virtue of Theorem 8.5.6 in Durrett (2010a)].

### 3.2 Comparison to the neutral Wright–Fisher process

In the regime of neutral selection where \( w = 0 \), \( X_t^{(N)} \) is a martingale, and the precise computation \( p_N(i) = i/N \) readily follows. When \( w > 0 \) the situation is more difficult due to the space inhomogeneity of the transition kernel combined with the large amplitude of one-step fluctuations. The latter is compared here to the nearest-neighbor transitions of a Moran process, for instance the companion Moran model introduced in Nowak et al. (2004), Taylor et al. (2004). By using a comparison with the neutral selection case, it is shown in Imhof and Nowak (2006) that if Assumption 1 is satisfied, then

\[ p_N(i) > i/N, \quad \forall \ N \geq N_0, \ i \in \Omega_N^o. \] (11)

This result holds for any \( w > 0 \) and is an instance of the following general principle.

**Proposition 1** Let \( X = (X_t)_{t \in \mathbb{Z}_+} \) be a Markov chain on \( \Omega_N \) for some \( N \geq 2 \). For \( i \in \Omega_N \), let

\[ \mu(i) = E(X_{t+1} - X_t | X_t = i) \] (12)

**denote the local drift of \( X \) at site \( i \). Suppose that:**

1. 0 and \( N \) are absorbing states.
2. If \( i \in \Omega_N^o \) and \( j \in \Omega_N \), then \( P(X_m = j | X_0 = i) > 0 \) for some \( m \in \mathbb{N} \).
3. \( \mu(i) \geq 0 \) for any \( i \in \Omega_N^o \).
Let \( p_N(i) = P(X \text{ absorbs at } N|X_0 = i) \). Then \( p_N(i) \geq i/N \) for any \( i \in \Omega_N^o \). Furthermore, the inequality is strict if and only if \( \mu(i) > 0 \) for at least one site \( i \in \Omega_N^o \).

Note that under Assumption 1, we have the following relation for the local drift of the Wright–Fisher Markov chain \( X^{(N)} \)

\[
\mu_N(i) := E(X^{(N)}_{t+1} - X^{(N)}_t|X^{(N)}_t = i) = N\xi_N(i) - i
\]

\[
= \frac{i(N - i)(f_N(i) - g_N(i))}{f_N(i) + (N - i)g_N(i)} > 0, \quad \forall \ i \in \Omega_N^o.
\]  

(13)

The proof of the proposition is in essence the observation that \( X \) is a bounded submartingale, and hence \( E(X_T|X_0) = Np_N(X_0) \geq X_0 \) by the optional stopping theorem (Durrett 2010a, Theorem 5.7.5).

In the weak selection regime, Imhof and Nowak (2006) provides a nearly complete analysis of \( p_N(i) \) and in particular obtains a version of the so-called one-third law of evolutionary dynamics for the model. The results of Imhof and Nowak (2006) for the fixation probability under weak selection are further refined and extended in Lessard and Ladret (2007). In particular, Lessard and Ladret (2007) derives a second order correction term to \( i/N \) for the fixation probability \( p_N(i) \). In this paper, we concentrate on the case of directional (beneficial for type A) selection as postulated in Assumption 1, but we do not make the assumption of weak selection.

### 3.3 Moran’s bounds and a coupling with the classical Wright–Fisher chain

Intuitively, it is clear that in the framework of Proposition 1, the local drift \( \mu(i) \) defined in (12) is a characteristic of the Markov chain \( X_t \) which is intimately related to the value of the fixation probabilities. Notice, for instance, that if \( X_0 = i \) and \( T \) is the absorption time of the Markov chain \( X \), then by the monotone convergence theorem we obtain that

\[
\sum_{t=0}^{\infty} E(\mu_N(X_t)) = E(X_T - X_0) = Np_N(i) - i.
\]

The general heuristic assertion of a close association between the local drift and the fixation probabilities is especially evident in the particular instance of the Wright–Fisher process, since according to (13),

\[
\xi_N(i) = \frac{i}{N} + \frac{1}{N}\mu_N(i),
\]  

(14)

and, by virtue of (2), \( (\xi_N(i))_{i \in \Omega_N^o} \) is the sequence defining the dynamics of the model. Thus, in view of the inequality in (13), in order to study the shape of \( p_N(i) \) as a function of \( i \) it may be conceptually desirable to compare \( X^{(N)} \) with a suitable stochastic process.
with positive drift, for which the solution to the gambler’s ruin problem is explicitly known (see, e.g., Durrett 2010a).

It has been emphasized in the work of Imhof and Nowak (2006), Taylor et al. (2004) that the fitness difference \( h_N(i) = f_N(i) - g_N(i) \), and in particular its sign, is a major factor influencing the invasion dynamics of the model. Note that by virtue of (13), the sign of \( h_N(i) \) coincides with the sign of the local drift \( \mu_N(i) \). Moreover, (13) can be rewritten as

\[
\mu_N(i) = \frac{i(N-i)(1 - \frac{g_N(i)}{f_N(i)})}{i + (N-i)\frac{g_N(i)}{f_N(i)}}, \quad \forall \, i \in \Omega^o_N, \tag{15}
\]

showing that the value of \( \mu_N(i) \) is in fact determined by the ratio \( \frac{g_N(i)}{f_N(i)} \). From this perspective, Assumption 2 together with (7) can be thought of as a tool establishing lower and upper bounds for the drift in terms of the selection parameter \( w \) and payoff matrix of the underlying game. In fact, (15) yields

\[
\frac{i(N-i)(1 - \gamma)}{i + (N-i)\gamma} \leq \mu_N(i) \leq \frac{i(N-i)(1 - \alpha)}{i + (N-i)\alpha}, \quad \forall \, i \in \Omega^o_N, \tag{16}
\]

where the lower and upper bounds have the form of the local drift of the Wright–Fisher process with a constant selection \( \frac{g_N(i)}{f_N(i)} \). These bounds suggest in particular the possibility of a comparison of our model with the classical Wright–Fisher process of mathematical genetics, and furthermore indicate, at least at the level of heuristic argument, that the dynamics of \( X^{(N)}(t) \) should be similar to that of the Wright–Fisher process with constant selection.

The following lemma, whose proof is included in Sect. 5.1, is the key technical observation we use to derive Theorem 4, our main result regarding the fixation probability in finite populations.

**Lemma 1** Let Assumption 1 hold. Then:

(a) There exists a constant \( \rho \in (0, 1) \) such that \( E(\rho^{X_{t+1}^{(N)}}|X_t^{(N)} = i) \leq \rho^i \) for any \( N \geq N_0, \, i \in \Omega^o_N \) and integer \( t \in \mathbb{Z}_+ \).

(b) There exists a constant \( \theta \in (0, 1) \) such that \( E(\theta^{X_{t+1}^{(N)}}|X_t^{(N)} = i) \geq \theta^i \) for any \( N \geq N_0, \, i \in \Omega^o_N \) and integer \( t \in \mathbb{Z}_+ \).

(c) Furthermore, in the above conclusions one can choose, respectively,

\[
\rho = e^{-2(1-\gamma)} \quad \text{and} \quad \theta = e^{-\frac{2(1-\alpha)}{\alpha}}. \tag{17}
\]

The lemma is a suitable modification of the ideas of Moran (1960, 1961) adapted to the present model with a frequency-dependent selection. The values of \( \rho \) and \( \theta \) suggested in (17) are obtained from the corresponding estimates of Moran for the classical Wright–Fisher chain with a constant selection (Moran 1960). Slightly better bounds can be obtained based on Arnold’s elaboration of Moran’s original approach (Arnold 1968; Buckley and Seneta 1983).
Lemma 1 implies that the sequence \((\rho X_t^{(N)})_{t \in \mathbb{Z}_+}\) is a supermartingale while \((\theta X_t^{(N)})_{t \in \mathbb{Z}_+}\) is a submartingale. Since both \(\rho X_t^{(N)}\) and \(\theta X_t^{(N)}\) are non-negative random variables bounded from above by one, Doob’s optional stopping theorem (Durrett 2010a, Theorem 5.7.5) implies that with probability one,

\[
\rho X_0^{(N)} \geq E\left(\rho X_T | X_0^{(N)}\right) = p_N \left(X_0^{(N)}\right) \rho^N + \left(1 - p_N \left(X_0^{(N)}\right)\right)
\]

and

\[
\theta X_0^{(N)} \leq E\left(\theta X_T | X_0^{(N)}\right) = p_N \left(X_0^{(N)}\right) \theta^N + \left(1 - p_N \left(X_0^{(N)}\right)\right).
\]

This yields the following exponential bounds of the form (10) for the fixation probabilities.

**Theorem 4** Suppose that Assumption 1 holds. Let constants \(\rho \in (0, 1)\) and \(\theta \in (0, 1)\) be determined by (17). Then

\[
\frac{1 - \rho^i}{1 - \rho^N} \leq p_N(i) \leq \frac{1 - \theta^i}{1 - \theta^N},
\]

for all \(N \geq N_0\) and \(i \in \Omega^o_N\).

Since \(\frac{1 - \rho^N}{N} < \frac{1 - \rho^i}{i}\) for all \(i \in \Omega^o_N\), the linear bound in (11) can be recovered as a direct implication of Theorem 4. The upper bound suggested in the theorem indicates that the exponential lower bound captures correctly the qualitative behavior of \(p_N(i)\) as a function of the initial state \(i\).

Theorem 4 can be strengthened to the following coupling result. In what follows we refer to a Markov chain on \(\Omega^o_N\) with transition kernel given by (2) as an \((N, \xi^\to_N)\)–binomial process, where \(\xi^\to_N := (\xi_N(0), \xi_N(1), \ldots, \xi_N(N))\) is the vector of conditional frequency expectations with \(\xi_N(0) = \xi_N(N) = 0\) and \(\xi_N(i) \in (0, 1)\) for any \(i \in \Omega^o_N\).

**Theorem 5** Suppose that Assumption 1 is satisfied. Let

\[
\eta_N(i) = \frac{\gamma^{-1}i}{\gamma^{-1}i + (N - i)} \quad \text{and} \quad \xi_N(i) = \frac{\alpha^{-1}i}{\alpha^{-1}i + (N - i)}.
\]

Then, in a possibly enlarged probability space, for any \(N \geq N_0\) and \(i \in \Omega^o_N\) there exists a Markov chain \((X_t^{(N,1)}, X_t^{(N,2)}, X_t^{(N,3)})_{t \in \mathbb{Z}_+}\) on \(\Omega^o_N \times \Omega^o_N \times \Omega^o_N\) such that the following holds true:

1. \((X_t^{(N,1)})_{t \in \mathbb{Z}_+}\) is an \((N, \eta^\to_N)\)-binomial process.
2. \((X_t^{(N,2)})_{t \in \mathbb{Z}_+}\) is an \((N, \xi^\to_N)\)-binomial process with \(\xi^\to_N\) given by (1).
3. \((X_t^{(N,3)})_{t \in \mathbb{Z}_+}\) is an \((N, \xi^\to_N)\)-binomial process.
4. \( X_0^{(N,1)} = X_0^{(N,2)} = X_0^{(N,3)} = i \) and \( X_t^{(N,1)} \leq X_t^{(N,2)} \leq X_t^{(N,3)} \) for all \( t \in \mathbb{N} \), with probability one.

The theorem utilizes in our setting the idea of comparison of a Markov process to a similar but more explicitly understood one (see, for instance, Daley 1968; Daley and Moran 1968; Kamae et al. 1977; O’Brien 1975; Sonderman 1980 and references therein for early work in this direction). Ignoring the technicalities, the theorem is a particular case of a more general coupling comparison result due to O’Brien (1975) [see in addition, for instance, Theorem 2 in Kamae et al. (1977) and Theorem 3.1 in Sonderman (1980) for related results]. In Sect. 5.2 we give a simple self-contained proof of Theorem 5, specifically exploiting a particular structure of binomial processes.

Theorem 5 asserts that there exists a coupling such that for almost any realization of the triple process \((X_t^{(N,1)}, X_t^{(N,2)}, X_t^{(N,3)})_{t \in \mathbb{Z}_+}\), the entire trajectory of the frequency-dependent model \((X_t^{(N,2)})_{t \in \mathbb{Z}_+}\), whose distribution coincides with the distribution of the chain \((X_t^{(N)})_{t \in \mathbb{Z}_+}\) studied in this paper, is placed between trajectories of two Wright–Fisher models with constant selection. The result suggests that the qualitative behavior of \((X_t^{(N)})_{t \in \mathbb{Z}_+}\) in a macroscopic level is similar to those of classical Wright–Fisher models with a constant selection. Furthermore, the hierarchy of the Wright–Fisher models allows to derive lower and upper bounds for important characteristics of our model in terms of the analogous quantities for standard Wright–Fisher models with selection. We remark that Theorem 4 can be deduced from Theorem 5 combined with results of Moran (1960) which show that the fixation probabilities of \((X_t^{(N,1)})_{t \in \mathbb{Z}_+}\) are dominated from below by \(\frac{1-\rho}{1-\theta}\) while the fixation probabilities of \((X_t^{(N,3)})_{t \in \mathbb{Z}_+}\) are dominated from above by \(\frac{1-\rho}{1-\theta}\), where \(\rho\) and \(\theta\) are defined in (17).

Note both \(\eta_N(i)\) and \(\xi_N(i)\) in (18) are non-decreasing functions of \(i\). It has been shown in Imhof and Nowak (2006) (see the proof of Lemma 1 on p. 679) that \(\xi_N(i)\) has a similar property for a general payoff matrix \(A\), namely \(\xi_N(i) \leq \xi_N(i+1)\) for all \(i \in \Omega_N^a\). With this result in hand, we can formally prove the intuitively obvious statement that \(p_N(i)\) is an increasing function of the initial state \(i\), and it is also a smooth and strictly monotone function of each of the five parameters \(a, b, c, d,\) and \(w\).

Proposition 2  (i) For a fixed \(n \geq N_0\) and \(i \in \Omega_N^a\), consider \(p_N(i)\) as a function of the parameters \(w\) and \(a, b, c, d\) which is defined within the domain

\[
\mathcal{D} := \{(a, b, c, d, w) \in \mathbb{R}^5 : w \in (0, 1), a, b, c, d > 0\}.
\]

Then the partial derivatives of \(p_N(i)\) with respect to any of the parameters \(a, b, c, d,\) and \(w\) exist anywhere within \(\mathcal{D}\). Furthermore,

\[
\frac{\partial p_N(i)}{\partial w} > 0, \quad \frac{\partial p_N(i)}{\partial b} > 0, \quad \frac{\partial p_N(i)}{\partial c} < 0, \quad \frac{\partial p_N(i)}{\partial a} > 0 \text{ unless } N = 2, \quad \frac{\partial p_N(i)}{\partial d} < 0 \text{ unless } N = 2.
\]
(ii) For any fixed \( N \geq N_0 \), \( p_N(i) \) is a strictly increasing function of the parameter \( i \) on \( \Omega_N \).

For the sake of completeness the proof of the proposition is included Sect. 5.3.

### 3.4 Branching process limit for large populations

In this section we consider the asymptotic behavior of the model when the population size approaches infinity. In view of Theorem 4 we have the following bounds for the limiting fixation probability:

\[
1 - \rho^i < \lim_{N \to \infty} p_N(i) < 1 - \theta^i.
\]

Thus the following result is a direct implication of Theorem 4.

**Corollary 1** Under Assumption 1,

(a) \( \liminf_{N \to \infty} p_N(i) > 0, \forall i \in \mathbb{N} \).

(b) \( \lim_{N \to \infty} p_N(i_N) = 1 \) for any sequence \( i_N \in \Omega^o_N \) such that \( \lim_{N \to \infty} i_N = +\infty \).

The first part of Corollary 1 can be refined as follows.

**Theorem 6** Let Assumption 1 hold. Then \( \lim_{N \to \infty} p_N(i) \) exists and is strictly positive for any \( i \in \mathbb{N} \). Furthermore,

\[
\lim_{N \to \infty} p_N(i) = 1 - q^i,
\]

where \( q \) is the unique in \((0, 1)\) root of the equation \( q = e^{-\lambda(1-q)} \) with

\[
\lambda = \frac{1-w+wb}{1-w+wd}.
\]

Theorem 6 implies in particular that just one advantageous mutant can invade an arbitrarily large finite population with probability uniformly bounded away from zero. A similar result for the frequency-dependent Moran model of Nowak et al. (2004), Taylor et al. (2004) has been obtained in Antal and Scheuring (2006).

The proof of Theorem 6 is based on the approximation of the Wright–Fisher model by a branching process with a Poisson distribution of offspring. The idea to study the fixation probability of a Wright–Fisher model using a branching process approximation goes back to at least Fisher (1930) and Haldane (1927). Typically, this approximation scheme is exploited using heuristic or numerical arguments (Ewens 2004; Gale 1990). The proof of Theorem 6 given in Sect. 5.4 is rigorous. A small but essential part of the formal argument is the use of a priori estimates provided by Theorem 4.

Once it has been established that a single advantageous mutant has a non-zero probability of extinction, it is natural to ask how long extinction takes, if at all. This question is addressed in the following result.
Theorem 7 Suppose that Assumption 1 is satisfied. Let $\lambda$ and $q$ be as defined in the statement of Theorem 6, and introduce

$$s_1 = \frac{4 - \lambda^2 q^2}{\lambda q} \quad \text{and} \quad s_2 = \frac{\lambda e^{-\lambda}}{\lambda q + e^{-\lambda q} - 1}. \quad (20)$$

Then there exist a constant $C_0 > 0$ and a function $\psi : (1, \infty) \to (0, \infty)$ that depend only on the payoff matrix $(a, b, c, d)$ and the selection parameter $w$, such that the following holds true for any real $\eta > 1$, $k, m \in \mathbb{N}$, and integers $N \geq N_0$, $J \in \Omega^a_N$:

$$P \left( T \leq m | X^{(N)}_0 = k \right) \leq \left( \frac{qs_2 (1 - \lambda^m q^m)}{s_2 - \lambda^m q^m} \right)^k e^{\psi(\eta) \lambda^{-m} (k \eta^m \lambda^m - N)} + mC_0 \frac{J^{3/2}}{N} + e^{\psi(\eta) \lambda^{-m} (k \eta^m \lambda^m - J)}$$

and

$$P \left( T \leq m | X^{(N)}_0 = k \right) \geq \left( \frac{qs_1 (1 - \lambda^m q^m)}{s_1 - \lambda^m q^m} \right)^k - mC_0 \frac{J^{3/2}}{N} - e^{\psi(\eta) \lambda^{-m} (k \eta^m \lambda^m - J)}.$$

Remark 2 A few remarks are in order.

(i) An explicit upper bound for $C_0$ can be derived from (34) and (35) below.
(ii) One can set $\psi(\eta) = \min \left\{ \psi > 0 : e^x - 1 \leq \eta x \text{ for all } x \in [0, \psi \lambda^{-1}] \right\}$. This can be seen from the proof of Lemma 3 below.
(iii) The identity $q = e^{-\lambda (1-q)}$ implies $\lambda q < 1$ because $e^{-q^{-1}(1-q)} < q$ for any $q \in (0, 1)$ and $e^{-\lambda (1-q)}$ is a decreasing function of $\lambda$. In particular, for $i = 1, 2$, we have

$$\lim_{m \to \infty} \left( \frac{qs_1 (1 - \lambda^m q^m)}{s_1 - \lambda^m q^m} \right)^k = q^k,$$

which is, according to Theorem 6 and (31) below, equivalent to

$$1 - \lim_{N \to \infty} p_N(k) = \lim_{N \to \infty} \lim_{m \to \infty} P \left( T \leq m, X^{(N)}_T = 0 | X^{(N)}_0 = k \right) = \lim_{m \to \infty} \lim_{N \to \infty} P \left( T \leq m, X^{(N)}_T = 0 | X^{(N)}_0 = k \right).$$

On the other hand, a suitable adaptation of the heuristic argument given in Section 6.3.1 of Durrett (2010b) for a Moran model suggests that

$$\lim_{N \to \infty} P \left( T \leq c \log N, X^{(N)}_T = N | X^{(N)}_0 = k \right) = 0.$$
as long as \( c < C_1 \) for some threshold constant \( C_1 > 0 \). If this heuristic is correct then the bounds given in the theorem are tight for large values of \( m \) and \( N \) as long as we maintain \( m < c \log N \) for some \( c < C_1 \).

(iv) The contribution of the correction term \( e^{\psi(\eta)\lambda^{-m}(k\eta^m \lambda^m - J)} \) is small for large values of \( N \) if, for instance, one sets \( J = N^\alpha \) for some positive real \( \alpha < 2/3 \) and maintain \( k\eta^m \lambda^m < cJ \) for some constant \( c \in (0, 1) \).

The proof of Theorem 7 is given in Sect. 5.5. The main ingredient of the proof is the branching process approximation which confirms that the first \( m \) steps of the Wright–Fisher model look with a high probability like the first \( m \) steps of a branching process with Poisson distribution of offspring. The first steps are the most important ones since there is little randomness involved in the dynamics of the process for intermediate values of \( i \), where, with high probability, \( X_{t+1}^{(N)} = \xi_N X_t^{(N)} > (1 + \varepsilon)X_t^{(N)} \) for a small \( \varepsilon > 0 \) (Chernoff–Hoeffding bounds for a binomial distribution (Hoeffding 1963) can be used to verify this). Compare also with the three phases of the fixation process.

![Figure 1](image)

**Fig. 1** The solid blue line represents the fixation probability \( p_\infty(1) = 1 - q \) of a single advantageous mutant in the infinite population limit as a function of the selection parameter \( w \). The black dots represent numerically obtained fixation probabilities \( p_{100}(1) \) for six different values of \( w \). Numerical results are obtained by observing \( 10^4 \) realizations of the Markov chain (2) with the above specified parameters (color figure online).

| \( N \)   | 10   | 20   | 50   | 100  | 500  | 1000 | 10,000 |
|----------|------|------|------|------|------|------|--------|
| \( q_N \)  | 0.6979 | 0.6567 | 0.6090 | 0.5909 | 0.5812 | 0.5792 | 0.5776  |
| \( q_N - q \) | 0.1209 | 0.0797 | 0.0320 | 0.0139 | 0.0042 | 0.0022 | 0.0006  |

Table 1 \( q_N \) is the value obtained from the nonlinear least squares fitting of numerically obtained fixation probabilities starting with \( i = 1, 2, \ldots, 10 \) individuals.

Up to \( N = 1000 \), we realized the Markov chain (2) \( 10^4 \) times and for \( N = 10,000 \) we used \( 5 \times 10^4 \) realizations.
process described in detail in Section 6.3.1 of Durrett (2010b). To estimate the error of the approximation we use an optimal (so called maximal) coupling of binomial and Poisson distributions and classical bounds on the total variation distance between the two distributions. Finally, to evaluate the extinction time distribution of the branching process we use bounds of Agresti (1974) obtained through the comparison of a Poisson branching process to a branching process with a fractional linear generating function of offspring. We remark that in the context of biological applications, the approximation of an evolutionary process by a branching process with a fractional linear generating function of offspring was apparently first considered in Rannala (1997).

3.5 Numerical example

Consider the following payoff matrix:

|   | A | B |
|---|---|---|
| A | 4 | 2 |
| B | 3 | 1 |

Theorem 6 indicates a very limited influence of the population size $N$ on the fixation probability $p_N(i)$ for large values of $N$. For illustration purposes we consider a fixed population size $N = 100$ and let the selection parameter vary between 0 and 1. Figure 1 shows a comparison of numerical and analytical results. The blue line represents the analytically obtained limiting fixation probability $p_\infty := \lim_{N \to \infty} p_N(1) = 1 - q$ as a function of the selection parameter $w$, while the black dots are numerically obtained fixation probabilities of one advantageous mutant for $N = 100$, averaged over $10^4$ independent realizations.

We also performed numerical simulations for the fixed selection parameter $w = 0.3$ and the initial number of mutants varying through $i = 1, 2, \ldots, 10$. The results of these simulations are shown in Table 1. In the case of large populations, Theorem 6 suggests that the fixation probability at zero is given by $q = 0.5770$. We numerically obtained the fixation probabilities $p_N(i)$ for the above specified parameters and used a nonlinear least squares routine in MATLAB to find the best fitting $q_N$ assuming that $p_N(i) = 1 - q_N^i$. Table 1 shows the results of this nonlinear fitting $q_N$ and the differences $q_N - q$ for the specified values of the population sizes $N$.

4 Conclusion

In this paper, we considered the fixation probability of symmetric games in Wright–Fisher processes with directional selection describing evolutionary dynamics of two types. Our analysis shows the existence of exponential lower and upper bounds for the fixation probabilities for any population size $N \in \mathbb{N}$. Using these facts one can draw the following biological conclusions.

1. The fixation probabilities of an advantageous or a deleterious mutant in a population of size $N$ depend on both population size and the relative fitnesses of the phenotypes (Fig. 2).
2. In the case of advantageous mutants, the dependence on the population size is weak, i.e. the lower bound on the fixation probability is bounded below by a positive constant depending only on the fitness of the two phenotypes.

3. The fixation probability \( q_N(i) \) of \( i \) deleterious mutants is an exponentially decreasing function of \( N \).

In addition, we studied the asymptotic of the fixation probability as the population size goes to infinity. We showed that

4. A single advantageous mutant can invade an arbitrarily large finite population with probability uniformly bounded away from zero.

5. Whenever the initial population \( X_0^{(N)} \) of advantageous players is unbounded as \( N \) goes to infinity (even if its proportion \( X_0^{(N)}/N \) vanishes to zero asymptotically), the fixation probability \( p_N(i) \) is asymptotically zero for deleterious players and one for advantageous players.
5 Proofs

This section, divided into five subsections, contains proofs of the results stated in Sect. 3. The proof of Lemma 1 is given in Sect. 5.1. The proof of Theorem 5 is included in Sect. 5.2. Section 5.4 is devoted to the proof of Theorem 6. Finally, the proof of Theorem 7 is given in Sect. 5.5.

5.1 Proof of Lemma 1

First, observe that if $X$ is a binomial random variable $\text{BIN}(N, \xi)$, then it follows from the binomial theorem that for any constant $\rho \in \mathbb{R}$,

$$E(\rho^X) = \sum_{k=0}^{N} \rho^k \binom{N}{k} \xi^k (1-\xi)^{N-k} = (\xi \rho + 1-\xi)^N. \tag{21}$$

Thus, in order to prove part (a) of the lemma we need to show that the following inequality holds for some $\rho \in (0, 1)$ and all $N \geq N_0$ and $i \in \Omega_N^o$:

$$\left(\rho \xi_N(i) + 1 - \xi_N(i)\right)^N \leq \rho^i.$$  

Using the notation $x = i/N$, the above inequality can be rewritten as

$$1 - (1 - \rho)\xi_N(Nx) \leq \rho^x.$$

It follows from (1) and Assumption 1 that $\xi_N(Nx) \geq \frac{x}{x + (1-x)\gamma}$. Thus, it suffices to show that for some constant $\rho \in (0, 1)$ and all $x \in (0, 1)$,

$$\frac{x}{x + (1-x)\gamma} - \frac{1 - \rho^x}{1 - \rho} \geq 0. \tag{22}$$

Similarly, in order to prove part (b) of the lemma it is sufficient to show that for some constant $\theta \in (0, 1)$ and all $x \in (0, 1)$,

$$\frac{x}{x + (1-x)\alpha} - \frac{1 - \theta^x}{1 - \theta} \leq 0. \tag{23}$$

Inequalities (22) and (23) have been analyzed in a similar context by Moran (1960) [see specifically the bottom of p. 488 in Moran (1960)] who found the feasible solutions given in (17). More precisely, the last paragraph on page 488 in Moran (1960) asserts that, for $s, \phi \in (0, 1)$, we have $\frac{(1+s)x}{1+sx} > \frac{1-e^{-2\phi}}{1-e^{-2\phi}}$ on $[0,1]$ if $\phi \geq s$ and $\frac{(1+s)x}{1+sx} < \frac{1-e^{-2\phi}}{1-e^{-2\phi}}$ on $[0,1]$ if $\phi \leq s(1+s)^{-1}$. To obtain the formulas in (17) we use this observation by Moran first for the pair $\gamma = \frac{s}{1+s}$ and $\rho = e^{-2\phi}$, and then for the pair $\alpha = \frac{s}{1+s}$ and $\theta = e^{-2\phi}$. The proof of the lemma is complete.  

\(\blacksquare\)
5.2 Proof of Theorem 5

The proof relies on a standard coupling argument. Fix any \( N \geq N_0 \). It follows from Assumption 1 that

\[
\eta_N(i) \leq \xi_N(i) \leq \zeta_N(i), \quad \forall \ i \in \Omega_N^0. \tag{24}
\]

Let \((U_{t,k})_{t \in \mathbb{Z}_+, k \in \mathbb{N}}\) be a double-indexed sequence of independent random variables, each one distributed uniformly on the interval \((0, 1)\). Using the interpretation of the binomial random variable as a sum of independent Bernoulli random variables, the Markov chain \((X_t^{(N,1)}, X_t^{(N,2)}, X_t^{(N,3)})_{t \in \mathbb{Z}_+}\) can be constructed inductively in the following manner. For each \( t \in \mathbb{Z}_+ \), define Bernoulli random variables \((b_{t,k}^{(1)}, b_{t,k}^{(2)}, b_{t,k}^{(3)})_{1 \leq k \leq N}\) as follows:

\[
b_{t,k}^{(1)} = 1(U_{t,k} \leq \eta_N(X_t^{(N,1)})), \quad b_{t,k}^{(2)} = 1(U_{t,k} \leq \xi_N(X_t^{(N,2)}))
\]

\[
b_{t,k}^{(3)} = 1(U_{t,k} \leq \zeta_N(X_t^{(N,3)})),
\]

where we use the notation \(1(A)\) to denote the indicator function of the event \(A\). Then set

\[
X_{t+1}^{(N,1)} = \sum_{k=1}^{N} b_{t,k}^{(1)}, \quad X_{t+1}^{(N,2)} = \sum_{k=1}^{N} b_{t,k}^{(2)}, \quad X_{t+1}^{(N,3)} = \sum_{k=1}^{N} b_{t,k}^{(3)}. \tag{25}
\]

It follows from (24) and the fact that both \(\eta_N(i)\) and \(\xi_N(i)\) are monotone increasing functions of \(i\), that the inequality \(X_t^{(N,1)} \leq X_t^{(N,2)} \leq X_t^{(N,3)}\) implies that \(\xi_N(X_t^{(N,2)}) \geq \eta_N(X_t^{(N,1)} \geq \eta_N(X_t^{(N,1)})\) and \(\xi_N(X_t^{(N,2)}) \leq \zeta_N(X_t^{(N,3)})\), hence \(\eta_N(X_t^{(N,1)}) \leq \eta_N(X_t^{(N,3)}) \leq \zeta_N(X_t^{(N,3)})\). By virtue of (25), the latter inequalities along with \(X_t^{(N,1)} \leq X_t^{(N,2)} \leq X_t^{(N,3)}\) imply \(X_{t+1}^{(N,1)} \leq X_{t+1}^{(N,2)} \leq X_{t+1}^{(N,3)}\), and the claim follows by induction on \(t\).

5.3 Proof of Proposition 2

For \(i, j \in \Omega_N\) let \(Q_{i,j}^{(N)} = P(X_{t+1}^{(N)} = j | X_t^{(N)} = i)\). Then, by the Markov property,

\[
p_N(i) = \sum_{j=1}^{N-1} Q_{i,j}^{(N)} p_N(j) + Q_{i,N}^{(N)}, \quad \forall \ i \in \Omega_N^0.
\]

Given \(N\) and \(i, j\), consider \(Q_{i,j}^{(N)}\) as a function \(\mathbb{R}^5 \rightarrow \mathbb{R}\) of the five independent variables \(a, b, c, d,\) and \(w\). The existence of the partial derivatives of \(p_N(i)\) with respect to these variables follows from the implicit function theorem applied to the smooth functions \(Q_{i,j}^{(N)}\) and the function \(f = (f_1, \ldots, f_{N-1}) : \mathbb{R}^{5+N-1} \rightarrow \mathbb{R}^{N-1}\), where

\[
\mathbb{R}.
\]
\[ f_i(a, b, c, d, w, p_N(1), \ldots, p_N(N-1)) := p_N(i) - \sum_{j=1}^{N-1} Q^{(N)}_{i,j} p_N(j) - Q^{(N)}_{i,N}. \]

We remark that the functions \( Q^{(N)}_{i,j} \) are smooth by virtue of (1) and (2). To apply the implicit function theorem one needs to check that a certain Jacobian is invertible. This condition is equivalent to the claim that one is not an eigenvalue of the \((N-1) \times (N-1)\) matrix \( (Q^{(N)}_{i,j}) \). It can be shown [see, for instance, Section 1.5 in Lawler (2006)] that, since the finite-state Markov chain \( X_t^{(N)} \) is irreducible, the Perron-Frobenius eigenvalue of this matrix is strictly less than one, and hence the conditions of the implicit function theorem are satisfied.

The monotonicity of \( p_N(i) \) on each of the parameters \( a, b, c, d, w, \) and \( i \) follows then from the corresponding monotonicity of \( \xi_N(i) \) (Imhof and Nowak 2006, p. 679) and the following version of O’Brien’s results in (1975):

**Proposition 3** Let \( \overrightarrow{\eta}_N = (\eta_i)_{0=1}^N \) and \( \overrightarrow{\xi}_N = (\xi_i)_{i=0}^N \) be two vectors in \( \mathbb{R}^{N+1} \) such that

1. \( \eta_0 = \xi_0 = 0, \eta_N = \xi_N = 1, \) and \( 0 < \eta_i \leq \xi_i \leq 1 \) for any \( i \in \Omega_N^o. \)
2. Either \( \eta_i \leq \xi_i + 1 \) for all \( i \in \Omega_N^o \) or \( \xi_i \leq \eta_i + 1 \) for all \( i \in \Omega_N^o. \)

Then for any \( i, j \in \Omega_N^o, i \leq j, \) there exists a Markov chain \( (X_t^{(N,1)}, X_t^{(N,2)})_{t \in \mathbb{Z}_+} \) on \( \Omega_N \times \Omega_N \) with the following properties:

1. \( (X_t^{(N,1)})_{t \in \mathbb{Z}_+} \) is an \( (N, \overrightarrow{\eta}_N) \)-binomial process.
2. \( (X_t^{(N,2)})_{t \in \mathbb{Z}_+} \) is an \( (N, \overrightarrow{\xi}_N) \)-binomial process.
3. With probability one, \( X_0^{(N,1)} = i, X_0^{(N,2)} = j, \) and \( X_t^{(N,1)} \leq X_t^{(N,2)} \) for \( t \in \mathbb{Z}_+. \)

We remark that Theorem 5 and Proposition 3 are two variants of the same result, and a self-contained proof of the latter can be obtained using a coupling argument similar to the one we employed in the proof of the theorem.

\[ \square \]

### 5.4 Proof of Theorem 6

Throughout the argument we formally treat the process \( X^{(N)} \) as a Markov chain on \( \mathbb{Z}_+ = \mathbb{N} \cup \{0\} \) with absorption states at 0 and \( N, N+1, N+2, \ldots, \) and assume that all chains \( X^{(N)}, N \geq N_0, \) have a common initial state, a given integer \( i_0 \in \mathbb{N}. \)

First, observe that for any fixed \( i \in \mathbb{N}, \)

\[ \lim_{N \to \infty} \xi_N(i)N = \lambda i, \]

where \( \lambda \) is defined in (19). Therefore, for any fixed pair of integer states \( i > 0 \) and \( j \geq 0, \) and an integer time \( t \in \mathbb{Z}_+, \)

\[ \lim_{N \to \infty} P(X_{t+1}^{(N)} = j | X_t^{(N)} = i) = e^{-\lambda i} \frac{(\lambda i)^j}{j!}. \quad (26) \]

Let \( Z = (Z_t)_{t \in \mathbb{Z}_+} \) be a Markov chain on \( \mathbb{Z}_+ \) with absorption state at zero and Poisson transition kernels

\[ \square \]
\[ P(Z_{t+1} = j | Z_t = i) = e^{-\lambda_i} \frac{\lambda_i^j}{j!}, \quad i \in \mathbb{N} \text{ and } j \geq 0. \]

Assume that the Markov chain \( Z \) has the same initial state \( Z_0 = i_0 \) as any \( X^{(N)} \), \( N \geq N_0 \). Since the sum of two independent Poisson random variables is a Poisson random variable with the parameter equal to the sum of their parameters, we can assume without loss of generality that \( Z \) is a Galton-Watson branching process with a Poisson offspring distribution. More precisely, we assume that (cf. Ewens 2004, Section 1.4)

\[ Z_{t+1} = \sum_{k=1}^{Z_t} Y_{t,k} \]

for some independent random variables \( Y_{t,k}, t \in \mathbb{Z}_+, k \in \mathbb{N} \), each one distributed as \( \text{Poisson}(\lambda) \), namely

\[ P(Y_{t,k} = j) = e^{-\lambda} \frac{\lambda^j}{j!}, \quad j \geq 0, \]

for all \( t \in \mathbb{Z}_+ \) and \( k \in \mathbb{N} \), with the parameter \( \lambda \) introduced in (19). As usual, we convene that the sum in (27) is empty if \( Z_t = 0 \).

The convergence of the transition kernels in (26) implies the weak convergence of the sequence of Markov chains \( X^{(N)} \) to the branching process \( Z \) [see, for instance, Theorem 1 in Karr (1975)]. Since \( \lambda > 1 \) under the conditions of Theorem 6 (recall that \( w > 0 \) and \( b > d \)), it follows that

\[ \lim_{t \to \infty} P(Z_t = + \infty) > 0. \] (28)

Let \( T_0^{(N)} = \inf \{ t > 0 : X_t^{(N)} = 0 \} \) and \( T_0 = \inf \{ t > 0 : Z_t = 0 \} \) be the first hitting time of zero by the Markov chains \( X^{(N)} \) and \( Z \), respectively. Convene, as usual, that the infimum of an empty set is \(+ \infty\). \( T_0 \) is the extinction time of the branching process \( Z \), and in this notation (28) reads \( P(T_0 < \infty) < 1 \). In fact [see, for instance, Ewens (2004), Section 1.4], \( q = \left[ P(T_0 < \infty) \right]^{1/i_0} \) is the unique in \((0,1)\) root of the fixed-point equation \( q = e^{-\lambda(1-q)} \), whose right-hand side is the moment-generating function of \( Y_{t,k} \) evaluated at \( q \in (0,1) \).

Since the transition kernel of \((X_t^{(N)})_{t \in \mathbb{Z}_+}\) converges to that of \((Z_t)_{t \in \mathbb{Z}_+}\),

\[ \lim_{N \to \infty} P(T_0^{(N)} < K) = P(T_0 < K), \quad \forall K \in \mathbb{N}. \] (29)

Therefore, by the monotone convergence theorem,

\[ \lim_{K \to \infty} \lim_{N \to \infty} P(T_0^{(N)} < K) = P(T_0 < \infty). \] (30)

Remark 3 The indicator \( \mathbbm{1}(T_0 < \infty) \) is not a continuous function of the stochastic process in the appropriate topology. This can be understood intuitively by the fact that
the equality of two processes during an arbitrarily large but finite interval of time does not guarantee that the corresponding two indicators have the same value. Hence, no standard continuous mapping theorem Billingsley (1999) seems to apply in order to derive (29) with $K = +\infty$ directly from the results of Karr (1975).

We conclude the proof of Theorem 6 by showing that we can interchange the limits in the above identity, and hence

$$
\lim_{N \to \infty} P \left( T_0^{(N)} < \infty \right) = \lim_{N \to \infty} \lim_{K \to \infty} P \left( T_0^{(N)} < K \right) = P(T_0 < \infty). \quad (31)
$$

To this end, write

$$
\left| P \left( T_0^{(N)} < \infty \right) - P(T_0 < \infty) \right| \leq \left| P \left( T_0^{(N)} < \infty \right) - P \left( T_0^{(N)} < K \right) \right|
$$

$$
+ \left| P \left( T_0^{(N)} < K \right) - P(T_0 < K) \right| + \left| P(T_0 < K) - P(T_0 < \infty) \right|
$$

$$
:= A_1(N, K) + A_2(N, K) + A_3(N, K), \quad (32)
$$

where the last line serves to define the events $A_i(N, K), i = 1, 2, 3$.

Pick any $\epsilon > 0$. First we will estimate

$$
A_1(N, K) = \left| P \left( T_0^{(N)} < \infty \right) - P \left( T_0^{(N)} < K \right) \right| = P \left( K \leq T_0^{(N)} < \infty \right).
$$

It follows from Assumption 2 that for all $i, N \in \mathbb{N}$ we have

$$
\xi_N(i) = \frac{i}{i + (N - i)g_N(i)/f_N(i)} \leq \frac{i}{\alpha N}.
$$

Therefore, using the strong Markov property and the lower bound in Theorem 4, we obtain for any $m \in \mathbb{N}$ and $N$ sufficiently large,

$$
A_1(N, K) = P \left( K \leq T_0^{(N)} < \infty \right)
$$

$$
= P \left( K \leq T_0^{(N)} < \infty, \max_{0 \leq t \leq K-1} X_t^{(N)} < m \right)
$$

$$
+ P \left( K \leq T_0^{(N)} < \infty, \max_{0 \leq t \leq K-1} X_t^{(N)} \geq m \right)
$$

$$
\leq P \left( X_1^{(N)} \neq 0, \ldots, X_{K-1}^{(N)} \neq 0, \max_{0 \leq t \leq K-1} X_t^{(N)} < m \right)
$$

$$
+ \sum_{j=m}^{N-1} P \left( \max_{0 \leq t \leq K-1} X_t^{(N)} = j \right) \cdot (1 - p_N(j))
$$

$$
\leq \left[ 1 - P \left( X_{K+1}^{(N)} = 0 \right) \right] \cdot \left( 1 - p_N(m) \right)
$$

$$
\leq \left[ 1 - \left( 1 - \frac{m}{\alpha N} \right)^{K-1} \right] + \frac{\rho^m}{1 - \rho^N}.
$$

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Choose now $m_0 \in \mathbb{N}$ so large that
\[
\limsup_{N \to \infty} \frac{\rho_m^{m_0}}{1 - \rho^N} = \rho_m^{m_0} \leq \frac{\varepsilon}{6},
\]
and then $K_1$ so large that for any $K > K_1$,
\[
\limsup_{N \to \infty} \left[ 1 - \left(1 - \frac{m_0}{\alpha N} \right)^N \right]^K = \left[ 1 - \exp\left(-\frac{m_0}{\alpha}\right) \right]^K \leq \frac{\varepsilon}{6}.
\]
Then, for any $K > K_1$,
\[
\limsup_{N \to \infty} A_1(N, K) \leq \frac{\varepsilon}{3}.
\]
Find now $K_2 \in \mathbb{N}$ such that for any $K > K_2$ we have
\[
A_3(N, K) = \left| P(T_0 < K) - P(T_0 < \infty) \right| \leq \frac{\varepsilon}{3}.
\]
Finally, pick any $K_0 = \max\{K_1, K_2\}$, and then using (30) choose $N_1$ such that $N > N_1$ implies
\[
A_2(N, K_0) = \left| P\left( T_0^{(N)} < K_0 \right) - P(T_0 < K_0) \right| \leq \frac{\varepsilon}{3}.
\]
It follows from the above estimates for $A_i(N, K_0)$, $i = 1, 2, 3$, and the basic inequality (32) that
\[
\limsup_{N \to \infty} \left| P\left( T_0^{(N)} < \infty \right) - P(T_0 < \infty) \right| \leq \varepsilon.
\]
Since $\varepsilon > 0$ is an arbitrary positive number,
\[
\lim_{N \to \infty} \left| P\left( T_0^{(N)} < \infty \right) - P(T_0 < \infty) \right| = 0.
\]
This establishes (31), and therefore, since $P(T_0 < \infty) = q^{t_0}$, it completes the proof of Theorem 6.

5.5 Proof of Theorem 7

The proof of the theorem is broken up into a series of lemmas. Throughout the argument we continue to use notations introduced in Sect. 5.4. We will use a certain optimal coupling between the branching process $(Z_t)_{t \in \mathbb{Z}_+}$ and the Wright–Fisher model $(X_t^{(N)})_{t \in \mathbb{Z}_+}$. By coupling we mean constructing in the same probability space a joint distribution of a pair of processes such that their marginal distributions coincide.
with those of $(Z_t)_{t \in \mathbb{Z}_+}$ and $(X_t^{(N)})_{t \in \mathbb{Z}_+}$. With a slight abuse of notation we will denote by $(X_t^{(N)}, Z_t)_{t \in \mathbb{Z}_+}$ the process of pairs constructed below, thus preserving the original names for the two marginal components of the coupled process. The construction specifically aims to minimize (and also enable us to estimate) $P(X_t^{(N)} \neq Z_t)$. We fix $k \in \mathbb{N}$ and assume throughout the proof that $N > k$ and $X_0^{(N)} = Z_0 = k$.

To explain the coupling construction, we need to recall the following general result [see, for instance, “Appendix A1” in Barbour et al. (1992)]:

**Proposition 4** Let $X$ and $Y$ be two random variables and $\delta(X, Y) \geq 0$ be the total variation distance between their distributions. That is,

$$\delta(X, Y) := \sup_A |P(X \in A) - P(Y \in A)|,$$

where the supremum is taken over measurable subsets $A$ of the real line. Then there exists a probability space and a random pair $(\tilde{X}, \tilde{Y})$ defined on the same probability space such that

1. $\tilde{X}$ is distributed the same as $X$.
2. $\tilde{Y}$ is distributed the same as $Y$.
3. $P(\tilde{X} \neq \tilde{Y}) = \delta(X, Y)$.

If $X$ and $Y$ are defined on the set of non-negative integers, the total variation distance $\delta(X, Y)$ is equal to $\frac{1}{2} \sum_{n=0}^{\infty} |P(X = n) - P(Y = n)|$ (see Durrett (2010a) for more properties of the total variation distance). The coupling described in Proposition 4 is often called a maximal coupling of random variables $X$ and $Y$.

We will also use the following coupling inequalities from the literature [for the first assertion see, for instance, Theorem 4 in Chatterjee et al. (2005) and for the second one Theorem 1.C(i) in Barbour et al. (1992)]:

**Proposition 5** (i) Let $X = \text{BIN}(N, p)$ be a binomial random variable with parameters $N \in \mathbb{N}$ and $p \in [0, 1]$ and $Y = \text{Poisson}(Np)$ be a Poisson random variable with parameter $\lambda = Np$. If $\lambda > 1$, then $\delta(X, Y) \leq \frac{p}{2}$. (ii) Let $X$ and $Y$ be two Poisson random variables with parameters $\lambda > 1$ and $\mu > 0$, respectively. Then $\delta(X, Y) \leq \frac{1}{\sqrt{\lambda}} |\mu - \lambda|$.

Using the above results, we can construct a coupling of the Wright–Fisher Markov chain $(X_t^{(N)})_{t \in \mathbb{Z}_+}$ and the branching process $(Z_t)_{t \in \mathbb{Z}_+}$ as follows. The resulting joint process $(X_t^{(N)}, Z_t)_{t \in \mathbb{Z}_+}$ will be a Markov chain, and we are now in position to describe its transition kernel. Suppose that the random pairs $(X_s^{(N)}, Z_s)$ have been defined and sampled for all $s \leq t$ and that $X_s^{(N)} = Z_s$ for all $s \leq t$. Let $i_t$ be the common value of $Z_t$ and $X_t^{(N)}$. Then, using the above results and at first approximating $X_t^{(N)}$ by a Poisson random variable with parameter $N \xi_N(i_t)$, we can construct the pair $(X_{t+1}^{(N)}, Z_{t+1})$ in such a way that
\[ P \left( X_{i+1}^{(N)} \neq Z_{i+1} | X_t = Z_t = i_t \right) \]
\[ \leq \frac{1}{2} \xi_N(i_t) + \frac{1}{\sqrt{\lambda i_t}} |N\xi_N(i_t) - \lambda i_t| \]
\[ \leq \frac{i_t}{2\alpha N} + \frac{1}{\sqrt{\lambda i_t}} |N\xi_N(i_t) - f_N(i_t)g_N(i_t)| + \frac{1}{\sqrt{\lambda i_t}} |f_N(i_t)g_N(i_t) - \lambda i_t| \tag{34} \]

A bit tedious but straightforward calculation shows that in this coupling construction

\[ P \left( X_{i+1}^{(N)} \neq Z_{i+1} | X_t = Z_t = i_t \right) \leq C_0 \frac{i_t^{3/2}}{N}, \tag{35} \]

where \( C_0 \) is a constant which depends only on the payoff matrix \( (a, b, c, d) \) and the selection parameter \( w \), but is independent of \( i_t \) and \( N \).

Once \( X_t^{(N)} \neq Z_t \) occurs for the first time, we can continue to run the processes \( (X_s^{(N)})_{s \geq t} \) and \( (Z_s)_{s \geq t} \) independently of each other. The above discussion is summarized in the following lemma.

**Lemma 2** There exist a probability space and a constant \( C_0 > 0 \) which depends on the payoff matrix \( (a, b, c, d) \) only, such that the processes \( (X_t^{(N)})_{t \in \mathbb{Z}_+} \) and \( (Z_t)_{t \in \mathbb{Z}_+} \) can be defined jointly in this probability space and the following holds true:

1. The pairs \( (X_t^{(N)}, Z_t) \) form a Markov chain.
2. The inequality in (35) is satisfied for any \( i_t \in \Omega_N \).
3. For any \( i, j, k, m \in \Omega_N \) such that \( i \neq j \), we have

\[ P \left( X_{i+1}^{(N)} = k, Z_{i+1} = m | X_t = i, Z_t = j \right) = P \left( X_{i+1}^{(N)} = k | X_t = i \right) \cdot P( Z_{i+1} = m | Z_t = j ). \]

In the rest of the proof of Theorem 7 we will consider the Markov chain \( (X_t^{(N)}, Z_t)_{t \in \mathbb{Z}_+} \) as described in Lemma 2. For \( k \in \mathbb{N} \) we will denote by \( P_k \) the distribution of the Markov chain \( (X_t^{(N)}, Z_t)_{t \in \mathbb{Z}_+} \) conditioned on \( X_0^{(N)} = Z_0 = k \). We will denote by \( E_k \) the corresponding expectation operator.

Let \( \tau_N > 0 \) be the first time when the path of the Wright–Fisher model diverges from the path of the branching process, that is

\[ \tau_N = \inf \left\{ t \in \mathbb{N} : X_t^{(N)} \neq Z_t \right\}. \tag{36} \]

In the above coupling construction, as long as \( Z_t = X_t^{(N)} \) the next pair \( (X_{i+1}^{(N)}, Z_{i+1}) \) is sampled using the maximal coupling, and after the first time when it occurs that \( Z_t \neq X_t^{(N)} \) we continue to sample \( (Z_s)_{s \geq \tau_N} \) and \( (X_s^{(N)})_{s \geq \tau_N} \) independently. We remark that the third property in the conclusion of Lemma 2 (eventual independence of the marginal processes) will never be used in our proof and is needed only to formally specify in a certain way the construction of the coupled Markov chain for all
times \( t \in \mathbb{Z}_+ \). In fact, we are going to observe and study the properties of the coupled chain only up to the time \( \tau_N \).

Fix now any \( m \in \mathbb{N} \) and \( \eta > 1 \). We will consider only large enough values of \( N \), namely we will assume throughout that \( N > (\lambda \eta)^m \). Recall \( T \) from (4). Similarly, for the branching process \( Z_t \) define

\[
\sigma_N = \inf\{t \in \mathbb{N} : Z_t = 0 \text{ or } Z_t \geq N\}.
\]

Recall \( \tau_N \) from (36). To evaluate the distribution function of \( T \) we will use the following basic inequalities valid for any \( k, m \in \mathbb{N} \):

\[
P_k(T \leq m) \leq P_k(T \leq m, \tau_N > m) + P_k(\tau_N \leq m) \leq P_k(\sigma_N \leq m) + P_k(\tau_N \leq m) \quad (37)
\]

and

\[
P_k(T \leq m) \geq P_k(T \leq m, \tau_N > m) \geq P_k(\sigma_N \leq m) - P_k(\tau_N \leq m). \quad (38)
\]

In the next two lemmas we estimate \( P(\sigma_N \leq m) \). For \( t \in \mathbb{N} \) let

\[
W_t = \max_{0 \leq i \leq t} Z_i. \quad (39)
\]

First, we will establish the following inequality:

**Lemma 3** For all \( \eta > 1 \) there exists \( \theta_\eta > 0 \) such that for any \( \theta \in (0, \theta_\eta] \) and \( k, J, m \in \mathbb{N} \) we have

\[
P_k(W_m \geq J) \leq e^{\theta \lambda^{-m}(k \eta^m \lambda^m - J)}. \]

**Proof** Let \( U_t := \lambda^{-t} Z_t \). Then \( (U_t)_{t \in \mathbb{Z}_+} \) is a martingale with respect to its natural filtration. For any \( \theta > 0 \), \( f(x) = e^{\theta x} \) is a convex function and hence the sequence \( e^{\theta U_t}, t \in \mathbb{Z}_+ \), form a sub-martingale. Hence, by Doob’s maximal inequality [see, for instance, Theorem 5.4.2 in Durrett (2010a)],

\[
P_k(W_m \geq J) = P_k\left( \max_{0 \leq k \leq m} e^{\theta U_k} \geq e^{\theta J \lambda^{-m}} \right) \leq e^{-\theta J \lambda^{-m}} E_k\left( e^{\theta U_m} \right)
\]

\[
= e^{-\theta J \lambda^{-m}} E_k\left( E_k\left( e^{\theta \lambda^{-m} Z_m \mid Z_{m-1}} \right) \right)
\]

\[
= e^{-\theta J \lambda^{-m}} E_k\left( \exp\left( \lambda Z_{m-1}(e^{\theta \lambda^{-m}} - 1) \right) \right). \quad (40)
\]

Pick now \( \theta > 0 \) so small that \( e^x - 1 \leq \eta x \) for any positive \( x \leq \theta \lambda^{-1} \). It follows then from (40) that for any \( J, m \in \mathbb{N} \),

\[
P_k(W_m \geq J) \leq e^{-\theta J \lambda^{-m}} E_k\left( e^{\theta \eta \lambda^{-m-1} Z_{m-1}} \right).
\]
Applying induction, we obtain that
\[ P_k(W_m \geq J) \leq e^{-\theta J \lambda^{-m}} E_k(e^{\theta \eta^m Z_0}) = e^{-\theta J \lambda^{-m}} \cdot e^{\theta \eta^m k}, \]
as required. \(\square\)

Recall now the notation \(T_0 = \inf\{t \in \mathbb{N} : Z_t = 0\}\). It follows from the results of Agresti (1974) that for any \(k \in \mathbb{N}\),
\[ \left( \frac{q s_1(1 - \lambda^m q^m)}{s_1 - \lambda^m q^m} \right)^k \leq P(T_0 \leq m \mid Z_0 = k) \leq \left( \frac{q s_2(1 - \lambda^m q^m)}{s_2 - \lambda^m q^m} \right)^k, \]
where \(s_1\) and \(s_2\) are introduced in (20). Combining these inequalities with the result of Lemma 3 for \(J = N\) we arrive to the following result:

**Lemma 4** Let \(s_1\) and \(s_2\) be defined by (20). Then, for any real \(\eta > 1\) and integers \(k, J, m, N \in \mathbb{N}\), the following holds true:

(i) \(P_k(\sigma_N \leq m) \leq \left( \frac{q s_2(1 - \lambda^m q^m)}{s_2 - \lambda^m q^m} \right)^k \).

(ii) \(P_k(\sigma_N \leq m) \geq \left( \frac{q s_1(1 - \lambda^m q^m)}{s_1 - \lambda^m q^m} \right)^k \).

Notice that the identity \(q = e^{-\lambda(1-q)}\) implies \(\lambda q < 1\) because \(e^{-q^{-1}(1-q)} < q\) for any \(q \in (0, 1)\) and \(e^{-\lambda(1-q)}\) is a decreasing function of \(\lambda\).

Recall \(\tau_N\) from (36). In view of (37) and (38), in order to complete the proof of Theorem 7 it remains to evaluate \(P_k(\tau_N \leq m)\). To this end, recall \(W_t\) from (39), fix any \(J \in \mathbb{N}\), and write using the Markov property of \((X_t^{(N)}, Z_t)_{t \in \mathbb{Z}^+}\) and the estimate in (35),
\[ P_k(\tau_N \leq m) \leq P_k(\tau_N \leq m \text{ and } W_m < J) + P_k(W_m \geq J) \]
\[ \leq \sum_{t=1}^{m} P_k(X_t^{(N)} \neq Z_t \mid X_{t-1}^{(N)} = Z_{t-1} < J) \cdot P_k(X_{t-1}^{(N)} = Z_{t-1} < J) \]
\[ + P_k(W_m \geq J) \]
\[ \leq \sum_{t=1}^{m} P_k(X_t^{(N)} \neq Z_t \mid X_{t-1}^{(N)} = Z_{t-1} < J) + P_k(W_m \geq J) \]
\[ \leq m C_0 \frac{J^{3/2}}{N} + P_k(W_m \geq J). \] (42)
Using the result in Lemma 3 we can deduce from (42) the following:
Lemma 5 For any real \( \eta > 1 \) and integers \( N, m \in \mathbb{N}, J \in \Omega_N^o \), we have
\[
P_k(\tau_N \leq m) \leq mC_0\frac{J^{3/2}}{N} + e^{\psi(\eta)\lambda^{-m}}(k\eta^m\lambda^m - J),
\]
where \( C_0 \) is the constant introduced in (35) and \( \psi(\eta) \) is the constant \( \theta_\eta \) introduced in the statement of Lemma 3.

The claim of Theorem 7 follows now from the bounds in (37) and (38) along with the estimates given in Lemmas 4 and 5. \( \square \)

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Appendix 1: Moran process

The goal of this section is to obtain an analogue of Theorem 3 (i.e., of the results stated in full detail in Theorems 4 and 6) for the frequency-dependent Moran process introduced in Nowak et al. (2004), Taylor et al. (2004). The main result of this section is stated in Theorem 8.

For a given integer \( N \geq 2 \), the Moran process which we denote by \( Y_N(t) \), \( t \in \mathbb{Z}_+ \), is a discrete-time birth and death Markov chain on \( \Omega_N \) with transition kernel \( P_N(i,j) := P(Y_{i+1} = j | Y_i = i) \) defined as follows. The chain has two absorption states, 0 and \( N \), and for any \( i \in \Omega_N^o \),
\[
P_N(i,j) = \begin{cases} 
\frac{N-i}{N}\xi_N(i) & \text{if } j = i + 1 \\
\frac{i}{N}(1 - \xi_N(i)) & \text{if } j = i - 1 \\
1 - P_{i,i-1} - P_{i,i+1} & \text{if } j = i \\
0 & \text{otherwise.}
\end{cases}
\]

The process in this form, with a general selection parameter \( w \in (0, 1] \), was introduced in Nowak et al. (2004). We remark that even though (Taylor et al. 2004) formally considered only the basic variant with \( w = 1 \), their main theorems hold for an arbitrary \( w \in (0, 1] \).

Similarly to (3), we define
\[
\hat{p}_N(i) = P \left( Y^{(N)}_\tau = N | Y^{(N)}_0 = i \right),
\]
where \( \tau = \inf \{ t > 0 : Y^{(N)}_t = 0 \text{ or } Y^{(N)}_t = N \} \). Since the Moran model is a birth-death process, the fixation probabilities are known explicitly (Nowak et al. 2004;
Taylor et al. 2004) [see, for instance, Example 6.4.4 in Durrett (2010a) for a general birth and death chain result]:

\[
\hat{p}_N(i) = \frac{1 + \sum_{j=1}^{i-1} \prod_{k=1}^{j} \frac{g_N(k)}{f_N(k)}}{1 + \sum_{j=1}^{N-1} \prod_{k=1}^{j} \frac{g_N(k)}{f_N(k)}}. \tag{43}
\]

In what follows we however bypass a direct use of this formula. The result following is an analogue of Lemma 1 for the Moran process.

**Lemma 6** Let Assumption 2 hold. Then for any \( N \geq N_0 \) and \( i \in \Omega_N^o \),

\[
E(\gamma^{Y_{i+1}^{(N)}} | Y_i^{(N)} = i) \leq \gamma^i \text{ and } E(\alpha^{Y_{i+1}^{(N)}} | Y_i^{(N)} = i) \geq \alpha^i. \tag{44}
\]

**Proof** We will only prove the first inequality in (44). The proof of the second one can be carried out in a similar manner. We have:

\[
E \left( \gamma^{Y_{i+1}^{(N)}} | Y_i^{(N)} = i \right) = \gamma^{i+1} \frac{N-i}{N} \xi_N(i) + \gamma^{i-1} \frac{i}{N} \left( 1 - \xi_N(i) \right) \\
+ \gamma^i \left( 1 - \frac{N-i}{N} \xi_N(i) - \frac{i}{N} \left( 1 - \xi_N(i) \right) \right) \\
= \gamma^i + \gamma^{i-1} \left( 1 - \gamma \right) \frac{i}{N} - \gamma^{i-1} \left( 1 - \gamma \right) \xi_N(i) \left( \gamma + \left( 1 - \gamma \right) \frac{i}{N} \right).
\]

Since by virtue of (2) and Assumption 2,

\[
\frac{i}{N} - \xi_N(i) \left( \gamma + \left( 1 - \gamma \right) \frac{i}{N} \right) \leq 0,
\]

we conclude that \( E(\gamma^{Y_{i+1}^{(N)}} | Y_i^{(N)} = i) \leq \gamma^i. \)

\( \square \)

In the same way as Lemma 1 implies Theorem 4, the above result yields the following bounds for the fixation probabilities in the Moran process:

\[
\frac{1 - \gamma^i}{1 - \gamma^N} \leq \hat{p}_N(i) \leq \frac{1 - \alpha^i}{1 - \alpha^N}. \tag{45}
\]

More precisely, we have:

**Theorem 8** Let Assumption 1 hold. Then:

(i) For any \( N \geq N_0 \) and \( i \in \Omega_N^o \), the inequalities in (45) hold true.

(ii) Furthermore, for any \( i \in \mathbb{N} \),

\[
\lim_{N \to \infty} \hat{p}_N(i) = 1 - \lambda^{-i}, \tag{46}
\]

where \( \lambda \) is defined in (19).
A proof of the limit in (46) is outlined at the end of the appendix, after the following Remark.

**Remark 4** The identities for the optimal values of $\alpha$ and $\gamma$ given in (7) suggest that in some cases one of the bounds in (45) might be asymptotically tight for large populations. The purpose of this remark is to explore conditions for the equalities $\lambda^{-1} = \alpha$ or $\lambda^{-1} = \gamma$ to hold true. By the definition given in (19), $\lambda = \lim_{N \to \infty} \frac{f_N(i)}{g_N(i)}$ for any $i \in \mathbb{N}$. Moreover, for any $N \geq N_0$,

\[
\frac{f_N(1)}{g_N(1)} = \frac{1 - w + wb}{1 - w + wd + (c - d)(N - 1)^{-1}} \tag{47}
\]

and

\[
\frac{f_N(N - 1)}{g_N(N - 1)} = \frac{1 - w + wa + (b - a)(N - 1)^{-1}}{1 - w + wc} \tag{48}
\]

It follows from (47) that

\[
\lambda = \frac{1 - w + wb}{1 - w + wd} = \begin{cases} 
\sup_{N \geq N_0} \frac{f_N(1)}{g_N(1)} & \text{if } c \geq d \\
\inf_{N \geq N_0} \frac{f_N(1)}{g_N(1)} & \text{if } c \leq d.
\end{cases}
\]

Furthermore, (48) implies that

\[
\frac{1 - w + wa}{1 - w + wc} = \begin{cases} 
\inf_{N \geq N_0} \frac{f_N(N - 1)}{g_N(N - 1)} & \text{if } b \geq a \\
\sup_{N \geq N_0} \frac{f_N(N - 1)}{g_N(N - 1)} & \text{if } b \leq a
\end{cases}
\]

and

\[
\frac{1 - w + wa + (b - a)(N_0 - 1)^{-1}}{1 - w + wc} = \begin{cases} 
\max_{N \geq N_0} \frac{f_N(N - 1)}{g_N(N - 1)} & \text{if } b \geq a \\
\min_{N \geq N_0} \frac{f_N(N - 1)}{g_N(N - 1)} & \text{if } b \leq a.
\end{cases}
\]

In principle, the last three identities contain all the information which is needed to identify necessary and sufficient conditions for the occurrence of either $\alpha = \lambda^{-1}$ or $\gamma = \lambda^{-1}$, where it is assumed, as in (7), that the optimal bounds $\alpha = \inf_{N \geq N_0} \min_{i \in \Omega^N} \frac{g_N(i)}{f_N(i)}$ and $\gamma = \sup_{N \geq N_0} \max_{i \in \Omega^N} \frac{g_N(i)}{f_N(i)}$ are employed. For instance, in the generic prisoner’s dilemma case $b > d > a > c$ one can set

\[
\gamma^{-1} = \lambda = \inf_{N \geq N_0} \min_{i \in \Omega^N} \frac{f_N(i)}{g_N(i)} \tag{49}
\]
provided that \( \frac{1 - w + wb}{1 - w + wd} \leq \frac{1 - w + wa}{1 - w + wc} \), which is equivalent to

\[
(1 - w)(c + b - a - d) \leq w(ad - bc).
\]

This leads us to consider the following possible scenarios for a prisoner’s-dilemma-type underlying game, that is assuming that \( b > d > a > c \):

1. \( ad \geq bc \) and \( c + b - a - d \leq 0 \) (for instance, \( b = 4, d = 3, a = 2, c = 1 \)). In this case (49) holds for any \( w \in (0, 1] \).
2. \( ad > bc \) and \( c + b - a - d > 0 \) (for instance, \( b = 5, d = 3, a = 2, c = 1 \)). In this case (49) holds if and only if

\[
\frac{1 - w}{w} \leq \frac{ad - bc}{c + b - a - d} \quad \Leftrightarrow \quad w \geq \left(1 + \frac{ad - bc}{c + b - a - d}\right)^{-1}.
\]

3. \( ad = bc \) and \( c + b - a - d > 0 \) (for instance, \( b = 6, d = 3, a = 2, c = 1 \)). In this case (49) holds only if \( w = 1 \).
4. \( ad < bc \) and \( c + b - a - d \geq 0 \) (for instance, \( b = 7, d = 3, a = 2, c = 1 \)). In this case (49) holds for no \( w \in (0, 1] \).
5. It remains to consider the case when \( ad < bc \) and \( c + b - a - d < 0 \). We will now verify that this actually cannot happen. To get a contradiction, assume that this scenario is feasible and let \( \varepsilon = \min\{b - d, a - c\} \), \( d' = d + \varepsilon \), \( c' = c + \varepsilon \). Then

\[
c' + b - a - d' = c + b - a - d < 0
\]

and, since \( ad < bc \) and \( a < b \),

\[
ad' = ad + a\varepsilon < bc' = bc + b\varepsilon.
\]

But, due to the choice of \( \varepsilon \) we made, we should have either \( b = d' \) or \( a = c' \). In the former case (50) and (51) imply the combination of inequalities \( c' - a < 0 \) and \( a < c' \), while in the latter they yield \( b - d' < 0 \) and \( d' < b \), neither of which is possible.

The limit in (46) has been computed in Antal and Scheuring (2006) (technically, in the specific case \( w = 1 \)), see in particular formula (39) there. The proof in Antal and Scheuring (2006) relies on (43) and involves some semi-formal approximation arguments. We conclude this appendix with the outline of a formal proof of this result which is based on a different approach, similar to the one employed in the proof of Theorem 6.

Toward this end observe first that, provided that both processes have the same initial state, the fixation probabilities of the Markov chain \( Y^{(N)} \) coincide with those of a Markov chain \( \tilde{Y}^{(N)} = (\tilde{Y}^{(N)}_t)_{t \in \mathbb{Z}_+} \) on the state space \( \Omega_N \) with transition kernel \( \tilde{P}_{i,j}^{(N)} := P(\tilde{Y}^{(N)}_{t+1} = j | \tilde{Y}^{(N)}_t = i) \) which is defined as follows. Similarly to \( Y^{(N)} \), the chain \( \tilde{Y}^{(N)} \) has two absorbing states, 0 and \( N \). Furthermore, for any \( i \in \Omega_N^\alpha \),
The advantage of using the chain $\tilde{Y}^{(N)}$ over $Y^{(N)}$ rests on the fact that while both $P_{i,i+1}^{(N)}$ and $P_{i,i+1}^{(N)}$ converge to zero as $N \to \infty$,

$$
\lim_{N \to \infty} \tilde{P}_{i,i+1}^{(N)} = \lim_{N \to \infty} \frac{N-i}{N} \xi_N(i) + \frac{i}{N} (1 - \xi_N(i)) = \lim_{N \to \infty} \frac{\xi_N(i)}{i + \frac{1}{N}} = \frac{\lambda}{1 + \lambda}
$$

and, consequently, $\lim_{N \to \infty} \tilde{P}_{i,i-1}^{(N)} = 1 + \frac{1}{1 + \lambda}$. In other words, as $N \to \infty$, the sequence of Markov chains $\tilde{Y}^{(N)}$ converges weakly to the nearest-neighbor random walk (birth and death chain) $\tilde{Z} = (\tilde{Z}_t)_{t \in \mathbb{Z}^+}$ on $\mathbb{Z}^+$ with absorption state at zero and transition kernel defined at $i \in \mathbb{N}$ as follows:

$$
P(\tilde{Z}_{t+1} = j | \tilde{Z}_t = i) = \begin{cases} 
\frac{\lambda}{1+\lambda} & \text{if } j = i + 1 \\
\frac{1}{1+\lambda} & \text{if } j = i - 1 \\
0 & \text{otherwise}.
\end{cases}
$$

If $\lambda > 1$, then, similarly to (28), we have $P\left(\lim_{t \to \infty} \tilde{Z}_t = +\infty\right) > 0$. The rest of the proof is similar to the argument following (28) in the proof of Theorem 6, with the processes $\tilde{Y}^{(N)}$ and $\tilde{Z}$ considered instead of, respectively, $X^{(N)}$ and $Z$. The only two exceptions are:

1. $P\left(\lim_{t \to \infty} \tilde{Z}_t = 0 | \tilde{Z}_t = i\right) = \lambda^i$ for any $i \in \mathbb{N}$. This follows from the solution to the “infinite-horizon” variation of the standard gambler’s ruin problem (Durrett 2010a) (take the limit as $N \to \infty$ in (43) assuming that $\frac{g_N(k)}{f_N(k)} = \lambda^{-1}$ for all $N, k \in \mathbb{N}$).

2. The last four lines in (33) should be suitably replaced. For instance, one can use the following bound:

$$
P\left(\tilde{Y}_1^{(N)} \neq 0, \ldots, \tilde{Y}_{K-1}^{(N)} \neq 0, \max_{0 \leq t \leq K-1} \tilde{Y}_t^{(N)} < m\right)$$

$$
+ \sum_{j=m}^{N-1} P\left(\max_{0 \leq t \leq K-1} \tilde{Y}_t^{(N)} = j\right) (1 - \tilde{p}_N(j))$$

$$
\leq \left[1 - P\left(\tilde{Y}_1^{(N)} = m - 2, \tilde{Y}_2^{(N)} = m - 3, \ldots, \tilde{Y}_{m-1}^{(N)} = 0 | \tilde{Y}_0^{(N)} = m - 1\right)\right]^{K-m}$$

$$
+ (1 - \tilde{p}_N(m))
$$

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\[
\begin{align*}
&\leq \left[ 1 - \prod_{i=1}^{m-1} \frac{P_{i,i-1}^{(N)}}{P_{i,i-1}^{(N)} + P_{i,i+1}^{(N)}} \right]^{K/m-1} + \frac{\gamma^m}{1 - \gamma^N} \\
&= \left[ 1 - \prod_{i=1}^{m-1} \frac{g_N(i)}{g_N(i) + f_N(i)} \right]^{K/m-1} + \frac{\gamma^m}{1 - \gamma^N} \\
&\leq \left[ 1 - \left( \frac{\alpha}{1 + \alpha} \right)^{m-1} \right]^{K/m-1} + \frac{\gamma^m}{1 - \gamma^N}.
\end{align*}
\]

We leave the details to the reader.

Appendix 2

In this short appendix we discuss an interpretation of the drift \( \mu_N(i) \) which is not used anywhere the paper, but it is worthwhile to state it explicitly as it is of independent interest. For \( i \in \Omega_N \) and \( j = 1, \ldots, N \), let

\[
S_{N,i}(j) = \begin{cases} 
1 & \text{if } j \leq i \\
0 & \text{if } j > i
\end{cases} \quad \text{and} \quad F_{N,i}(j) = \begin{cases} 
f_N(i) & \text{if } j \leq i \\
g_N(i) & \text{if } j > i
\end{cases}
\]

Thus, if one enumerates and labels the individuals at the state \( X_t^{(N)} = i \) in such a way that the first \( i \) individuals are of type A and get labeled 1, and the remaining \( N - i \) individuals are of type B and get labeled 0, then \( S_{N,i}(j) \) and \( F_{N,i}(j) \) represent, respectively, the label and the fitness of the \( j \)-th individual. Furthermore, using the above enumeration, let \((u, v), u < v \) be a pair of individuals chosen at random. That is,

\[
P(u = j, v = k) = \frac{2}{N(N - 1)} \quad \text{for any } j, k \in \Omega_N \setminus \{0\}, j < k.
\]

Let

\[
H_{N,i} := \frac{2i(N - i)}{N(N - 1)} = E(S_{N,i}(v) - S_{N,i}(u))
\]

be the heterozygosity (Durrett 2010b, Section 1.2) of the Wright–Fisher process \( X_t^{(N)} \) at state \( i \in \Omega_N \), that is the probability that two individuals randomly chosen from the population when \( X_t^{(N)} = i \) have different types. In this notation,

\[
\mu_N(i) = \frac{N(N - 1)}{2} H_{N,i} \frac{f_N(i) - g_N(i)}{f_N(i) + (N - i)g_N(i)}
\]

\[
= \frac{N(N - 1)}{2} \cdot \frac{E(F_{N,i}(v) - F_{N,i}(u))}{\sum_{j=1}^{N} F_{N,i}(j)}
\]

\[
= \frac{1}{2} \sum_{j,k=1}^{N} \left| F_{N,i}(k) - F_{N,i}(j) \right| \sum_{j=1}^{N} F_{N,i}(j),
\]

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suggesting that the drift $\mu_N(i)$ can serve as a measure of heterozygosity that is suitable for our game-theoretic framework.

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