Simple Near-field to Far-field Transformation Method Using Antenna Array-factor

Hirokazu Kobayashi*, Yoshio Yamaguchi, Yi Cui

Department of Information Engineering, Niigata University, Niigata, 211-8121, Japan

Abstract This paper presents a simple and practical method and measurement results of transformation by using the idea of array-factor for direct far-field prediction from the near-field data of antenna and RCS in cylindrical scanning system. When radiation pattern of an antenna or scattering pattern of radar cross-section (RCS) is measured, its characteristics is usually evaluated in the far-field area. However, measurement is usually done in the radio anechoic chamber to reduce unnecessary reflected wave and deviates from the condition of far-field according to the size or the measuring frequency. On the other hand, it is well known that methods such as compact-range or the transformation processing approach can transform the pick-up data from the near-field to the far-field. The measurement results by this simple near-field transformation agree very well with the conventional far region measurement method.

Keywords Near-Field Transformation, Far-Field, Array-Factor, Cylindrical Scanning, RCS

1. Introduction

Electromagnetic wave propagation caused by a source can be also considered as the result of an equivalent secondary source between the wave source and observation point. When the electromagnetic field in an area near the source is known by some methods then the field in other areas can be theoretically predict. Thus a near-field measurement method can be applied to predict the antenna or radar cross-section (RCS) pattern which cannot be physically measured from far distance. The exact method of near-field to far-field transformation has been reported from 1970s for antenna[1-4] and RCS measurement[5],[6]. It is a traditional and well-established approach to formulate the electromagnetic field relation between the probe and the antenna under measurement using modal expansion method according to the ways of probe scanning which can be classified into three major types: flat-plane, cylindrical, and spherical scanning. The flat-plane scanning type is the simplest, and as a result, we can easily obtain the far-field from the data of near-field distribution using fast Fourier transformation (FFT). It is, however, difficult to apply the FFT for the other scanning types, i.e., cylindrical or spherical, and selection of the scanning type depends on the directivity of the antenna or the beam width of the RCS. In this paper, we present a method that available to apply in any scanning type.

When antenna array is studied, it is common to use array-factor (AF) for representing the electromagnetic far-field which is the result of the radiation of array elements as small point sources. The AF is a basic theory for beam-forming of phased array antenna, adaptive array processing and so on. This AF concept can be also directly applied to the near-field to far-field transformation. The formulation of the AF is very simple as compared to the complicated modal expansion method which needs various special functions according to the scanning plane. In addition, AF based method is only dependent on the coordinates of the probing sample points, which is one of its major features. In this paper, we mainly discuss the far-field transformation in circular cylindrical scanning for antenna and quasi-bistatic RCS patterns.

2. Array-factor of a Ring and Cylindrical Array

When the same isolated elements are arranged in the linear and homogeneous space, assuming there is no mutual coupling among elements, the AF in terms of angular variables of the spherical coordinate system $(\theta, \phi)$ is:

$$ f(\theta, \phi) = \sum a_n \exp \{jk (ux_n + vy_n + wz_n) \} $$

where $(x_n, y_n, z_n)$ are the 3-dimensional coordinates of the $n$-th element, $u = \sin \theta \cos \phi$, $v = \sin \theta \cos \phi$, $w = \cos \theta$; $k = 2\pi/\lambda$ is the wave-number and $\lambda$ is the wave-length. Eq. (1) expresses the far-field pattern which is produced by point sources. If we use the measured electromagnetic field distributed near the antenna instead of the AF element as point source then it is expected that Eq. (1) shows the far-field radiation pattern of the antenna. Furthermore, this expression is already in a fashion of the far-field pattern, and the near-field data can be directly transformed to the far-field by
putting the phase and amplitude of these near-field data to the complex number coefficient, $a_n$.

The flat-plane scanning is suitable for measurement of high directivity antenna such as the aperture antennas.[3]. On the other hand, the cylindrical (circle) scanning based on ring array is known to be best for patch and/or wire antenna and so on with broad pattern. The processing of FFT is employable in the flat-plane scanning system, but, unfortunately, not in other scanning system like cylindrical or spherical. In this study we mainly concentrate on the cylindrical scanning system but as will be seen later, the proposed transformation method using AF in Eq. (1) is independent on scanning types.

It only needs the near-field phase and amplitude data, $a_n$ at coordinates $(x_n, y_n, z_n)$.

Eq. (5) approximately becomes $f(\theta, \phi) \equiv aN J_0(k\rho)$ in both horizontal and vertical planes.

Next, the directivity of a ring array is considered. The directivity is defined by the radiation field $P(\theta, \phi)$ divided by the average receiving power density $P_r/(4\pi)$ of the array. The factor of $4\pi$ of the average power density originates in an isotropic reference antenna. The directivity in the direction of the maximum beam is especially called gain of directivity, which is expressed as

$$D_0 = \frac{|P_{\max}|^2}{P_r/4\pi} = \frac{4\pi |P_{\max}|^2}{|P(\theta, \phi)|^2 \sin \theta d\theta d\phi}. \quad (6)$$

This $D_0$ is usually expressed by numerical integration. However, in the case of a ring array we show the above denominator $|P(\theta, \phi)|^2$ can be analytically calculated as follows.

First, for any $p, n = 1, 2, \cdots, N$ a relation

$$a_p a_n \exp \{jY_p - J_n\} \cdot \exp \{jK \sin \theta \cos(\phi - \phi_n)\} = a_p a_n \exp \{jY_p - y_n\} \exp \{jK \sin \theta \cos(\phi - \phi_n)\} \quad (7a)$$

$$\rho_{pm} = 2\pi \sin \frac{\phi_n - \phi_p}{2}, \quad (7b)$$

$$\gamma_n = -k R_n \sin \theta \cos(\phi - \phi_n) \quad (7c)$$

can be derived. Substituting the above relation to the denominator of Eq. (6), we get

$$\int_0^{2\pi} \int_0^\pi \exp \{jK \rho_{pm} \sin \theta \cos(\phi - \phi_n)\} \sin \theta d\theta d\phi = 4\pi \sum_{p=1}^N \sum_{n=1}^N a_p a_n \exp \{jY_p - y_n\} \int_0^{2\pi} \int_0^\pi \exp \{jK \rho_{pm} \sin \theta \cos(\phi - \phi_n)\} \sin \theta d\theta d\phi \quad (8)$$

Finally, the result is expressed as

$$D_0 = \frac{|P_{\max}|^2}{P_r/4\pi} = \frac{|a_p a_n|^2}{W} \quad (9a)$$

$$W = \sum_{p=1}^N \sum_{n=1}^N a_p a_n \exp \{j(Y_p - y_n)\} \sin \theta d\theta d\phi. \quad (9b)$$

The above described AF and directivity are effective for element antenna with omni-directional pattern. If the pattern of element antenna have a form of $f_t(\alpha) = (\cos \alpha)^s \cdot (\sin \alpha)^{t-1}; s = 1, 2, \cdots, t \geq 1 \quad (10)$

where $\alpha$ is the angle measured from bore-sight of the element antenna, the factor $W$ of Eq. (9b) then becomes the following closed-form:

$$W = \frac{1}{2} \Gamma(s) \sum_{p=1}^N \sum_{n=1}^N \frac{(-1)^{s+j} J_{s+j+1}\left((kp_{pm})\right)}{(i\rho_{pm})^{s+j+1}} (p \neq n), \quad (11)$$

$S_p = \frac{1}{2} \Gamma(s) \sum_{j=1}^P \frac{(-1)^{s+j} J_{s+j+1}\left((kp_{pm})\right)}{(i\rho_{pm})^{s+j+1}} (p \neq n), \quad (12)$

$S_n = \frac{1}{2} \Gamma(s) \sum_{p=1}^N \frac{(-1)^{s+j} J_{s+j+1}\left((kp_{pm})\right)}{(i\rho_{pm})^{s+j+1}} (p \neq n), \quad (13)$

where $\Gamma(\cdot)$ and $J(\cdot)$ are the Gamma and Bessel functions,
respectively. For example, for vertical short dipoles, element
antenna becomes \( f_p = \cos \alpha \) by setting \( s = 1 \), \( t = 1/2 \). \( S_{pm} \)
in Eq. (11) is given by
\[
S_{pm} = \frac{\sin(k\rho_{pm})}{k\rho_{pm}} - \frac{1}{(k\rho_{pm})^2} \left( \frac{\sin(k\rho_{pm})}{k\rho_{pm}} - \cos(k\rho_{pm}) \right). \quad (12)
\]

Eq. (2)-(5) are the AF expressions for a single ring array.
When \( M \)-pieces of ring arrays of radius \( R_{mn} \) overlap
cylindrically, then by considering the \( z \)-axis, the single ring
array Eq. (1) can be modified to
\[
f(\theta, \phi) = \sum_{m=1}^{M} \sum_{n=1}^{N} a_{mn} \exp\left\{i k R_{mn} \sin \theta \cos(\phi - \varphi_{mn}) + i k z_{mn} \cos \theta \right\}, \quad (13)
\]
where \( \theta, \phi \) are angles of the radiation pattern in the spherical
coordinates. Each ring array is arranged in the same way. In
other words, each element coordinates is same in the \( x \)-, \( y \)-
plane, i.e., \( \varphi_{mn} = \varphi_n \). Moreover, the distance in the direction
of the diameter is \( R_{mn} = R_n \) because the form of a
cylinder is assumed.

3. Near-field Measurement for Antenna

In this section, we examine the procedure for predicting
the far-field measurement. The phase and amplitude of the
measured data in the near-field can be directly input to the
complex coefficients \( a_{mn} \). Since the radius of the cylinder
is constant, one can set \( R_{mn} = R \). The probe antenna is
linearly moved along the \( z \)-axis of the cylinder and the
antenna under test (AUT) sitting on a pedestal is rotated
around the \( z \)-axis as shown Fig. 2. At the same time, AUT
takes the probe pattern into account, and its compensation is
as follows.

![Diagram of cylindrical scanning system of near-field measurement](image)

**Figure 2.** Cylindrical scanning system of near-field measurement

The pattern of the probe is assumed to be \( f_p(\theta_p, \phi_p) \)
where \( \theta_p \) and \( \phi_p \) are the local spherical coordinates at
the sampling point of the measure data. The real pattern of
the cylindrical array antenna system can be required by
multiplying the AF to this element pattern as weighting. In
order to evaluate the far-field without grating-lobe, it is
necessary to know the beam pattern of the probe antenna,
\( f_p(\theta_p, \phi_p) \). Thus after the probe correction the far-field pat-
tern Eq. (13) is simply modified to
\[
f(\theta, \phi) = \sum_{m=1}^{M} \sum_{n=1}^{N} a_{mn} f_p(\theta_p, \phi_p) \exp\{i k R_{mn} \sin \theta \cos(\phi - \varphi_{mn}) + i k z_{mn} \cos \theta\} \quad (14)
\]
for 3-dimensional cylindrical scanning transformation. This
compensation of the probe antenna to AF as element pattern
weighting is the key point in array antenna theory for
near-field to far-field transformation on non-flat scanning
measurement. For simplicity, assuming the pattern of the
probe antenna is \( f_p = \cos \phi \) \((|\phi| \leq \pi/2)\), \( = 0 \left(|\phi| > \pi/2\right) \) in a single layer of ring array, we can approximately
convert the pattern to the scanning coordinates as \( \cos(\phi - \varphi_{mn}) \). Then the far-field pattern Eq. (14) reduces to
\[
f(\theta, \phi) = \sum_{n=1}^{N} a_{n} \cos(\phi - \varphi_{n}) \exp\{i k R_{n} \sin \theta \cos(\phi - \varphi_{n})\}. \quad (15)
\]

If the edge of the waveguide is selected as probe antenna
then we may use the calculated table value of the horn an-
tenna to correct the probe pattern. However, it can be ex-
pected that there is not so difference in the result of the
near-field transformation even if it is replaced by the cosine
function as mentioned above, from the viewpoint of the
computing time. The directivity gain of the AUT is evalu-
ated by using Eq. (9a) and the absolute gain including
antenna loss can be evaluated using the substitution method
for standard horn gains.

In the actual measurement, sampling interval of the probe
\( \Delta \varphi_{mn} \) and \( \Delta z_{mn} \) become important parameters. The angle
\( \varphi_{mn} \) is rotated within the range of \( 0 \sim 2\pi \) and \( z_{mn} \) is lim-
ited to the area where the power level between the probe
antenna and AUT is detectable. The movement interval of the
probe can be chosen according to the sampling theorem.
Usually the probe is measured outside the effective
near-field which is several numbers of wave-length away.
The interval of the sampling position at this time becomes a
pitch satisfying \( \Delta \varphi_{mn} \leq \pi/kR = \lambda/2R \) and \( \Delta z_{mn} \leq \pi/k = \lambda/2 \).

4. Far-field Transformation Results for
Antenna and RCS

Fig. 3 is a photograph of the measuring system with the
AUT and probe antennas as shown Fig. 2. For this cylindrical
scanning measurement \( z = \pm 350 \text{mm}, \varphi_{mn} = 0 \sim 2\pi \);
the sampling interval are \( \Delta z = 2 \text{ mm} \) and \( \Delta \varphi = \pi/180 \) at
frequency 22 GHz. A measured example of amplitude and
phase of the near-field using the cylindrical scanning system
is shown in Fig. 4. The AUT is a standard pyramidal horn
whose aperture is 103.3 \( \times \) 78.6 mm and the probe antenna
is a single side of the standard waveguide (WR42) which is separated 270 mm away from the aperture of the AUT.

According to Eq. (13), the 3- and 2-dimensional displays of the far-field transformation result using the measured near-field data in Fig. 4 is shown in Fig. 5 and Fig. 6, respectively. The result of conventional far-field measurement is also drawn in Fig. 6. It can be seen that both results agree very well.

![Figure 3. Near-field measurement of cylindrical scanning](image)

![Figure 4. Near-field measurement of a horn antenna in Fig. 3 at f = 22 GHz, (a): amplitude, (b): phase distribution](image)

![Figure 5. Far-field 3-dimensional pattern transformed from the near-field distribution in Fig. 4 by using AF](image)

![Figure 6. Far-field 2-dimensional planar-cut patterns of Fig. 5](image)

If the probe pattern is not taken into account, unnecessary grating lobe will appear in the rear direction of the AUT. Fig. 7 shows an example in which no compensation of probe antenna pattern is made to AF. It can be seen that the probe compensation is necessary for the measurement using AF. Since the flat-plane scanning is unable to simultaneously measure the antenna with the front and back lobes, the cylindrical scanning becomes the best method for antennas with or without pencil beam. On the other hand, the scanning in the direction of the z-axis is essentially the same to the plane scanning system. So, the aspect angle between the probe and AUT affects the measurement precision for this direction of cylinder scanning system.
As for the directivity evaluation, the difference between the result using the AF according to Eq. (9a) and the result based on the shape size is less than 0.3 dB. Using Eq. (6) directly, it is found that the results are almost the same.

Next, we discuss the RCS measurement, which is a key parameter for radar system design. The RCS is defined by the formula

$$\sigma = 4\pi \lim_{r \to \infty} r^2 \left| \frac{E^s(r)}{E^{inc}(0)} \right|^2,$$

(16)

where $E^s(r)$ is a component of the scattered electric field at the observation point, $E^{inc}(0)$ is a component of the incident electric field at the origin where the target is located; and $r = |r|$ is the distance from the origin to the observation point. Eq. (16) can be used only in the far-field region of the scatterer where the scattered field has the form of an outgoing spherical wave. The distance to the far-field region can be expressed in terms of the maximum linear size $L$ of the scatterer and the wavelength as $r^{FF} = 2L^2/\lambda$. This relation implies that in the microwave frequency range (frequency $f$ between 1 GHz and 100 GHz) and for targets of several meters in size or larger, the far-field zone is located too far to permit a direct measurement of RCS. For example, $r^{FF} \approx 66$ m when $L = 1$ m and $f = 10$ GHz. This formula is also valid for far-field of antenna.

Now we will show an example of RCS transformation by near-field measuring. However, the method for the antenna measurement introduced so far cannot be applied to the RCS measurement as it is because it is necessary to provide both transmitter and receiver for the RCS measurement system. Therefore, the transformation theory of the antenna can be applied to the RCS measurement by illuminating the whole area of the target by plane wave. When the size of the target is comparatively small, an incident plane wave can be made compulsorily by a compact-range system in the near zone of the target. Then the AF transformation algorithm is applied to the picked-up near-field data scattered from the target. Transmission and reception by the compact-range is only available for the monostatic mode, but not for the bistatic mode.

Fig. 8 is a photo of the cylindrical RCS measurement using compact-range. Target whose size is less than ±50 mm may be illuminated by the plane wave of which the phase deviation is within ±5 deg. In this situation, the RCS transformation result is shown in Fig. 10. The target is a perpendicularly set-up circular metallic disc with diameter 81 mm and thickness 5 mm. The distance between the receiving probe and the center of the disc is 190 mm and the measuring frequency is 10 GHz. The compact-range transmitter is a parabolic reflector of diameter 1.2 m which is 1.5 m from the center of the disc. Fig. 9 is the phase deviation plot around the quiet-zone, in which target under test will be located. The plane wave from the compact-range illuminates the disc at the incident angle of 45 deg. As shown in Fig. 10, the direction 0 deg corresponds to the specular reflection, −45 deg., and it is in good agreement with the theory value in this direction of the main lobe. The error at the direction (±90 deg.) for the theory calculation value is due to neglect of the thickness of the disc. The theoretical value for the thin disc is calculated by using the method of PTD (Physical Theory of Diffraction)[7].

Figure 7. An example without compensation of probe antenna pattern: measurement conditions are same in Fig. 6(b)

As for the directivity evaluation, the difference between the result using the AF according to Eq. (9a) and the result based on the shape size is less than 0.3 dB. Using Eq. (6) directly, it is found that the results are almost the same.

Next, we discuss the RCS measurement, which is a key parameter for radar system design. The RCS is defined by the formula

$$\sigma = 4\pi \lim_{r \to \infty} r^2 \left| \frac{E^s(r)}{E^{inc}(0)} \right|^2,$$

(16)

where $E^s(r)$ is a component of the scattered electric field at the observation point, $E^{inc}(0)$ is a component of the incident electric field at the origin where the target is located; and $r = |r|$ is the distance from the origin to the observation point. Eq. (16) can be used only in the far-field region of the scatterer where the scattered field has the form of an outgoing spherical wave. The distance to the far-field region can be expressed in terms of the maximum linear size $L$ of the scatterer and the wavelength as $r^{FF} = 2L^2/\lambda$. This relation implies that in the microwave frequency range (frequency $f$ between 1 GHz and 100 GHz) and for targets of several meters in size or larger, the far-field zone is located too far to permit a direct measurement of RCS. For example, $r^{FF} \approx 66$ m when $L = 1$ m and $f = 10$ GHz. This formula is also valid for far-field of antenna.

Now we will show an example of RCS transformation by near-field measuring. However, the method for the antenna measurement introduced so far cannot be applied to the RCS measurement as it is because it is necessary to provide both transmitter and receiver for the RCS measurement system. Therefore, the transformation theory of the antenna can be applied to the RCS measurement by illuminating the whole area of the target by plane wave. When the size of the target is comparatively small, an incident plane wave can be made compulsorily by a compact-range system in the near zone of the target. Then the AF transformation algorithm is applied to the picked-up near-field data scattered from the target. Transmission and reception by the compact-range is only available for the monostatic mode, but not for the bistatic mode.

Fig. 8 is a photo of the cylindrical RCS measurement using compact-range. Target whose size is less than ±50 mm may be illuminated by the plane wave of which the phase deviation is within ±5 deg. In this situation, the RCS transformation result is shown in Fig. 10. The target is a perpendicularly set-up circular metallic disc with diameter 81 mm and thickness 5 mm. The distance between the receiving probe and the center of the disc is 190 mm and the measuring frequency is 10 GHz. The compact-range transmitter is a parabolic reflector of diameter 1.2 m which is 1.5 m from the center of the disc. Fig. 9 is the phase deviation plot around the quiet-zone, in which target under test will be located. The plane wave from the compact-range illuminates the disc at the incident angle of 45 deg. As shown in Fig. 10, the direction 0 deg corresponds to the specular reflection, −45 deg., and it is in good agreement with the theory value in this direction of the main lobe. The error at the direction (±90 deg.) for the theory calculation value is due to neglect of the thickness of the disc. The theoretical value for the thin disc is calculated by using the method of PTD (Physical Theory of Diffraction)[7].
5. Conclusions

In this paper, the near-field transformation method using the AF has been proposed and it was shown that applying the idea of the AF is an easy and simple concept to obtain enough accuracy. In addition, by producing the plane wave using compact-range, this antenna measurement method is easily extended to the RCS measurement as well. The near-field method can be applied even in the quiet-zone of poor performance as compared with the traditional far-field measurement. Furthermore, data are measured in the closed space by cylindrical scanning and it is proven that the measurement accuracy is good in the direction of circumference. On the other hand, the accuracy of the flat-plane scanning depends on the aspect angle to the AUT for the $z$-direction of the cylindrical scanning measurement. Applying FFT for transformation calculation in this flat-plane direction can shorten the computing time by approximately 1/10 times but it is not applicable to cylindrical scanning direction. Since the traditional modal expansion based near-field transformation for cylindrical scanning generally becomes too complex due to the use of special functions, it is advantageous to use this simple and effective AF-based approach as an alternative transformation method.

ACKNOWLEDGEMENTS

This work was supported in its measurement by Keycom Corp., Tokyo, Japan. The authors would like to thank the president, Mr. Hirosuke Suzuki.

REFERENCES

[1] Appel-Hansen, J., Dyson J. D., Gillespie E. S., and Hickman T. G., "Antenna measurements," in the Handbook of Antenna Design, ed. A. W. Rudge, etc., pp. 584-694, IEE UK, 1986.
[2] Yaghjian, A. D., An Overview of Near-field Antenna Measurements, IEEE Trans. on Antennas and Propagation, Vol. AP-34, No. 1, pp. 30-45, 1986.
[3] Newell A. W., Planar Near-field Measurements, National Institute of Standards and Technology, Lecture Notes, 1989.
[4] Slater, D., "Near-field Antenna Measurements," Artech House, 1991.
[5] Hansen, T. B., Marr, R. A., Lammers, U. H. W., Tanigawa, and T. J., McGahan, R. V., Bistatic RCS Calculations From Cylindrical Near-Field Measurements—Part I: Theory, IEEE Trans. on Antennas and Propagation, Vol. AP-54, No. 12, pp. 3846 – 3856, 2006.
[6] Kobayashi, H., Osipov, A., and Suzuki, H., An Improved Image-based Near-field-to-far-field Transformation for Cylindrical Scanning Surfaces, Proc. 30th General Assembly and Scientific Symposium of International Union of Radio Science (URSI), Istanbul, Turkey, B04-3, August 2011.
[7] Kobayashi, H., and Hongo, K., Scattering of Electromagnetic Plane Waves by Conducting Plates, Electromagnetics, vol.17, no.6, pp. 573-587, 1997.