Research article

Investigation of Caputo proportional fractional integro-differential equation with mixed nonlocal conditions with respect to another function

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Abstract: In this manuscript, we analyze the existence, uniqueness and Ulam’s stability for Caputo proportional fractional integro-differential equation involving mixed nonlocal conditions with respect to another function. The uniqueness result is proved via Banach’s fixed point theorem and the existence results are established by using the Leray-Schauder nonlinear alternative and Krasnoselskii’s fixed point theorem. Furthermore, by using the nonlinear analysis techniques, we investigate appropriate conditions and results to study various different types of Ulam’s stability. In addition, numerical examples are also constructed to demonstrate the application of the main results.

Keywords: existence and uniqueness; fractional differential equations; fixed point theorems; Ulam’s stability; nonlocal conditions

Mathematics Subject Classification: 26A33, 34A08, 34B10, 34D20

1. Introduction

Fractional calculus (FC), also known as non-integer calculus, has been widely studied in recent over the past decades (beginning 1695) in fields of applied sciences and engineering. FC deals
with fractional-order integral and differential operators, which establishes phenomenon model as an increasingly realistic tool for real-world problems. In addition, it has been properly specified the term “memory” particularly in mathematics, physics, chemistry, biology, mechanics, electricity, finance, economics and control theory, we recommend these books to readers who require to learn more about the core ideas of fractional operators [1–6]. However, recently, several types of fractional operators have been employed in research education that mostly focus on the Riemann-Liouville (RL) [3], Caputo [3], Hadamard [3], Katugampola [7], conformable [8] and generalized conformable [9]. In 2017, Jarad et al. [10] introduced generalized RL and Caputo proportional fractional derivatives including exponential functions in their kernels. After that, in 2021, new fractional operators combining proportional and classical differentials have been introduced in [11]. Moreover, Akgül and Baleanu [12] studied the stability analysis and experiments of the proportional Caputo derivative.

Recently, one type of fractional operator that is popular with researchers now is proportional fractional derivative and integral operators (PFDs) with respect to another function; for more details see [13, 14]. For \( \alpha > 0, \rho \in (0,1), \psi \in C^1([a,b]), \psi' > 0 \), the PFD of order \( \alpha \) of \( h \in L^1([a,b]) \) with respect to \( \psi \) is given as:

\[
\rho \mathcal{D}_{a+}^{\alpha, \psi}[h(t)] = \frac{1}{\rho^\alpha \Gamma(\alpha)} \int_a^t \rho \mathcal{H}_{\psi}^{\alpha-1}(t,s)[h(s)]\psi'(s)ds,
\]

where \( \Gamma(\alpha) = \int_0^\infty s^{\alpha-1}e^{-s}ds, s > 0 \), and

\[
\rho \mathcal{H}_{\psi}^{\alpha-1}(t,s) = e^{s(\psi(t)-\psi(s))}(\psi(t) - \psi(s))^{\alpha-1}.
\]

The Riemann-Liouville proportional fractional derivative (RL-PFD) of order \( \alpha \) of \( h \in C^n([a,b]) \) with respect to \( \psi \) is given by

\[
\rho \mathcal{D}_{a+}^{\alpha, \psi}[h(t)] = \frac{\rho \mathcal{D}_{a+}^{\alpha}[h(t)]}{\rho^{\alpha-\alpha} \Gamma(n-\alpha)} \int_a^t \rho \mathcal{H}_{\psi}^{\alpha-\alpha-1}(t,s)[h(s)]\psi'(s)ds,
\]

with \( n = [\alpha] + 1 \), where \([\alpha]\) denotes the integer part of order \( \alpha \), \( \rho \mathcal{D}_{a+}^{\alpha, \psi} = \rho \mathcal{D}_{a+}^{\alpha} \cdot \rho \mathcal{D}_{a+}^{\alpha} \cdots \rho \mathcal{D}_{a+}^{\alpha} \), and \( \rho \mathcal{D}_{a+}^{\alpha}[h(t)] = (1 - \rho)h(t) + \rho h'(t)/\psi'(t) \). The PFD in Caputo type is given as in

\[
\rho \mathcal{D}_{a+}^{\alpha, \psi}[h(t)] = \left[\rho \mathcal{D}_{a+}^{\alpha, \psi}[h(t)]\right] = \frac{\rho^{\alpha-n}}{\Gamma(n-\alpha)} \int_a^t \rho \mathcal{H}_{\psi}^{\alpha-\alpha-1}(t,s)\rho \mathcal{D}_{a+}^{\alpha, \psi}[h(s)]\psi'(s)ds.
\]

The relation of PFD and Caputo-PFD which will be used in this manuscript as

\[
\rho \mathcal{D}_{a+}^{\alpha, \psi}[\rho \mathcal{D}_{a+}^{\alpha, \psi}[h(t)]] = h(t) - \sum_{k=0}^{n-1} \frac{\rho \mathcal{D}_{a+}^{\alpha, \psi}[h(a)]}{\rho^k k!} \rho \mathcal{H}_{\psi}^{\alpha+k+1}(t,a).
\]

Moreover, for \( \alpha, \beta > 0 \) and \( \rho \in (0,1) \), we have the following properties

\[
\rho \mathcal{D}_{a+}^{\alpha, \psi}[\rho \mathcal{H}_{\psi}^{\beta-1}(t,a)] = \frac{\Gamma(\beta)}{\rho^\alpha \Gamma(\beta + \alpha)} \rho \mathcal{H}_{\psi}^{\beta+\alpha-1}(t,a),
\]

\[
\rho \mathcal{D}_{a+}^{\alpha, \psi}[\rho \mathcal{H}_{\psi}^{\beta-1}(t,a)] = \frac{\rho^\alpha \Gamma(\beta)}{\Gamma(\beta - \alpha)} \rho \mathcal{H}_{\psi}^{\beta-\alpha-1}(t,a).
\]
Notice that if we set \( \rho = 1 \) in (1.1), (1.3) and (1.4), then we have the \( \mathbb{R}^L \)-fractional operators [3] with \( \psi(t) = t \), the Hadamard fractional operators [3] with \( \psi(t) = \log t \), the Katugampola fractional operators [7] with \( \psi(t) = t^\mu / \mu \), \( \mu > 0 \), the conformable fractional operators [8] with \( \psi(t) = (t - \alpha)^\varphi / \mu \), \( \mu > 0 \) and the generalized conformable fractional operators [9] with \( \psi(t) = t^{\mu \varphi} / (\mu + \varphi) \), respectively. Recent interesting results on \( \mathbb{F} \)Es with respect to another function could be mention in [15–25].

Exclusive investigations in concepts of qualitative property in fractional-order differential equations (\( \mathbb{F} \)DEs) have recently gotten a lot of interest from researchers as existence property (EP) and Ulam’s stability (US). The EP of solutions for \( \mathbb{F} \)DEs with initial or boundary value conditions has been investigated applying classical/modern fixed point theorems (\( \mathbb{F} \)PTs). As we know, US is four types like Hyers-Ulam stability (HU), generalized Hyers-Ulam stability (GHU), Hyers-Ulam-Rassias stability (HUR) and generalized Hyers-Ulam-Rassias stability (GHUR). Because obtaining accurate solutions to fractional differential equations problems is extremely challenging, it is beneficial in various of optimization applications and numerical analysis. As a result, it is requisite to develop concepts of US for these issues, since studying the properties of US does not need us to have accurate solutions to the proposed problems. This qualitative theory encourages us to obtain an efficient and reliable technique for solving fractional differential equations because there exists a close exact solution when the purpose problem is Ulam stable. We suggest some interesting papers about qualitative results of fractional initial/boundary value problems (\( \mathbb{B} \)VPs) involving many types of non-integer order, see [26–43] and references therein.

We are going to present some of the researches that inspired this manuscript. In recent years, pantograph equation (PE) is a type of proportional delay differential equation emerging in deterministic situations which first studied by Ockendon and Taylor [44]:

\[
\begin{align*}
\begin{cases}
u'(t) = \mu u(t) + \kappa u(\lambda t), & a < t < T, \\
u(0) = u_0 = A, & 0 < \lambda < 1, \mu, \kappa \in \mathbb{R}.
\end{cases}
\end{align*}
\]

The problem (1.8) has been a broad area of applications in applied branches such as science, medicine, engineering and economics that use the sake of \( \mathbb{P} \)Es to model some phenomena of the problem at present which depend on the previous states. For more evidences of \( \mathbb{P} \)Es ,see [45–51]. There are many researches of literature on nonlinear fractional differential equations involving a specific function with initial, boundary, or nonlocal conditions, for examples in 2013, Balachandran et al. [52] discussed the initial nonlinear \( \mathbb{P} \)Es as follows:

\[
\begin{align*}
\begin{cases}
\mathbb{C}^{\mathbb{D}}[u(t)] = h(t, u(t), u(\sigma t)), & \alpha \in (0, 1], \ 0 < t < 1, \\
u(0) = u_0, & 0 < \sigma < 1,
\end{cases}
\end{align*}
\]

where \( u_0 \in \mathbb{R} \), \( \mathbb{C}^{\mathbb{D}} \) denotes the Caputo fractional derivative of order \( \alpha \) and \( h \in C([0, 1] \times \mathbb{R}^2, \mathbb{R}) \). FC and \( \mathbb{F} \)PTs were applied to discuss the existence properties of the solutions in their work. In 2018, Harikrishman and co-workers [53] examined the existence properties of \( \psi \)-Hilfer fractional derivative for nonlocal problem for \( \mathbb{P} \)Es:

\[
\begin{align*}
\begin{cases}
\mathbb{H}^{\mathbb{D}}[u(t)] = h(t, u(t), u(\sigma t)), & t \in (a, b), \ \sigma \in (0, 1), \ \alpha \in (0, 1) \\
\mathbb{C}^{\mathbb{D}}[u(a)] = \sum_{i=1}^{k} c_i u(\tau_i), & \tau_i \in (a, b), \ \alpha \leq \gamma = \alpha + \beta - \alpha \beta,
\end{cases}
\end{align*}
\]
where $H_D^{\alpha,\beta,\phi}_{a^*}$ represents the $\psi$-Hilfer fractional derivative of order $\alpha$ and type $\beta \in [0,1]$, $\frac{1}{\alpha}\phi$ is RL-fractional integral of order $1 - \gamma$ with respect to $\psi$ so that $\psi' > 0$ and $h \in C([a,b] \times \mathbb{R}^2, \mathbb{R})$. Asawasamrit and co-workers [54] used Schaefer’s and Banach’s FPTs to establish the existence properties of FDEs with mixed nonlocal conditions (MNCs) in 2019. In 2021, Boucenna et al. [55] investigated the existence and uniqueness theorem of solutions for a generalized proportional Caputo fractional Cauchy problem. They solved the proposed problem based on the decomposition formula. Amongst important fractional equations, one of the most interesting equations is the fractional integro-differential equations, which provide massive freedom to explain processes involving memory and hereditary properties, see [56, 57].

Recognizing the importance of all parts that we mentioned above, motivated us to generate this paper which deals with the qualitative results to the Caputo proportional fractional integro-differential equation (PFDI) with MNCs:

$$
\begin{align*}
\left\{ \begin{array}{l}
C_{\rho D}^{\alpha,\phi}_{a^*}[u(t)] = f(t, u(t), u(\lambda t), r^{\alpha,\phi}_{a^*}[u(\lambda t)]), \\m \gamma_i u(\eta_i) + \sum_{j=1}^{n} \kappa_j C_{\rho D}^{\beta_i,\phi}_{a^*}[u(\xi_j)] + \sum_{r=1}^{k} \sigma_r r^{\rho,\psi}_{a^*}[u(\theta_r)] = A,
\end{array} \right. 
\end{align*}
$$

(1.11)

where $C_{\rho D}^{\alpha,\phi}_{a^*}$ is the Caputo-PFDI with respect to another increasing differentiable function $\psi$ of order $\rho = \{\alpha,\beta\}$ via $0 < \beta < \alpha \leq 1$, $j = 1, 2, \ldots, n$, $0 < \rho \leq 1$, $0 < \lambda < 1$, $r^{\rho,\psi}_{a^*}$ is the PFIO with respect to another increasing differentiable function $\psi$ of order $p = \{\omega,\delta\}$ via $0 < \delta < \gamma_i, \kappa_j, \sigma_r, A \in \mathbb{R}$, $0 \leq a \leq \eta_i, \xi_j, \theta_r \leq T$, $i = 1, 2, \ldots, m$, $f \in C(\mathcal{F} \times \mathbb{R}^4, \mathbb{R})$, $\mathcal{F} = [a, T]$. We use the help of the famous FPTs like Banach’s, Leray-Schauder’s nonlinear alternative and Krasnoselskii’s to discuss the existence properties of the solutions for (1.11). Moreover, we employ the context of different kinds of US to discuss the stability analysis. The results are well demonstrated by numerical examples at last section.

The advantage of defining MNCs of the problem (1.11) is it covers many cases as follows:

- If we set $\kappa_j = \sigma_r = 0$, then (1.11) is deduced to the proportional multi-point problem.
- If we set $\gamma_i = \sigma_r = 0$, then (1.11) is deduced to the PF multi-point problem.
- If we set $\gamma_i = \kappa_j = 0$, then (1.11) is deduced to the PF multi-point problem.
- If we set $\alpha = \rho = 1$, (1.11) emerges in nonlocal problems [58].

This work is collected as follows. Section 2 provides preliminary definitions. The existence results of solutions for (1.11) is studied in Section 3. In Section 4, stability analysis of solution for (1.11) in frame of HU, GHU, HUR and GHUR are given is established. Section 5 contains the example to illustrate the theoretical results. In addition, the summarize is provided in the last part.

2. Preliminaries

Before proving, assume that $\mathcal{E} = C(\mathcal{F}, \mathbb{R})$ is the Banach space of all continuous functions from $\mathcal{F}$ into $\mathbb{R}$ provided with $\|u\| = \sup_{t \in \mathcal{F}} |u(t)|$. The symbol $r^{\rho,\psi}_{a^*}[F_u(s)(c)]$ means that

$$
\int_{a}^{c} \rho^{\rho,\psi}_{a^*}[F_u(c)] = \frac{1}{\rho^{\rho,\psi}_{a^*}[F_u(c)]} \int_{a}^{c} (c,s) F_u(s) \psi'(s) ds,
$$
where \( q = \{ \alpha, \alpha - \beta_j, \alpha + \delta_r \}, \) \( c = \{ t, \eta, \xi_j, \theta_r \}, \) and

\[
F_u(t) := f(t, u(t), u(\lambda t), \rho_{\gamma^\alpha} [u(\lambda t)], F_u(\lambda t)).
\]  

(2.1)

In order to convert the considered problem into a fixed point problem, (1.11) must be transformed to corresponding an integral equation. We discuss the following key lemma.

**Lemma 2.1.** Let \( 0 < \beta_j < \alpha \leq 1, \) \( j = 1, 2, \ldots, n, \) \( \rho > 0, \delta_r > 0, \) \( r = 1, 2, \ldots, k \) and \( \Omega \neq 0. \) Then, the Caputo-PFIDE with MNCs:

\[
\begin{cases}
C_{\rho_1}D_{\alpha}^{\alpha, \psi} [u(t)] = F_u(t), \quad t \in (a, T), \\
\sum_{i=1}^{m} \gamma_i \mu(\eta_i) + \sum_{j=1}^{n} \kappa_j C_{\rho_1}D_{\alpha}^{\beta_j, \psi} [u(\xi_j)] + \sum_{r=1}^{k} \sigma_r \rho_{\gamma^\alpha} [u(\theta_r)] = A,
\end{cases}
\]  

(2.2)

is equivalent to the integral equation

\[
u(t) = \rho_{\gamma^\alpha} [F_u(t)] + \frac{c_1 e^{\frac{\rho_1}{\rho} (\phi(t) - \psi(a))}}{\Omega} \left( A - \sum_{i=1}^{m} \gamma_i \rho_{\gamma^\alpha} [F_u(\eta_i)] - \sum_{j=1}^{n} \kappa_j \rho_{\gamma^\alpha}^{\beta_j, \psi} [F_u(\xi_j)] - \sum_{r=1}^{k} \sigma_r \rho_{\gamma^\alpha} [F_u(\theta_r)] \right),
\]  

(2.3)

where

\[
\Omega = \sum_{i=1}^{m} \gamma_i e^{\frac{1}{\rho} (\phi(t) - \psi(a))} + \sum_{r=1}^{k} \sigma_r \rho \Gamma (1 + \delta_r).
\]  

(2.4)

**Proof.** Suppose \( u \) is the solution of (2.2). By using (1.5), the integral equation can be rewritten as

\[
u(t) = \rho_{\gamma^\alpha} [F_u(t)] + c_1 e^{\frac{\rho_1}{\rho} (\phi(t) - \psi(a))},
\]  

(2.5)

where \( c_1 \in \mathbb{R}. \) Taking \( C_{\rho_1}D_{\alpha}^{\beta_j, \psi} \) and \( \rho_{\gamma^\alpha}^{\delta_r, \psi} \) into (2.5) with (1.6) and (1.7), we obtain

\[
C_{\rho_1}D_{\alpha}^{\beta_j, \psi} [u(t)] = \rho_{\gamma^\alpha}^{\beta_j, \psi} [F_u(t)], \quad \rho_{\gamma^\alpha}^{\delta_r, \psi} [u(t)] = \rho_{\gamma^\alpha}^{\delta_r, \psi} [F_u(t)] + c_1 \rho \Gamma (1 + \delta_r).
\]  

Applying the nonlocal conditions in (2.2), we have

\[
A = \sum_{i=1}^{m} \gamma_i \rho_{\gamma^\alpha} [F_u(\eta_i)] + \sum_{j=1}^{n} \kappa_j \rho_{\gamma^\alpha}^{\beta_j, \psi} [F_u(\xi_j)] + \sum_{r=1}^{k} \sigma_r \rho_{\gamma^\alpha}^{\delta_r, \psi} [F_u(\theta_r)] + c_1 \left( \sum_{i=1}^{m} \gamma_i e^{\frac{\rho_1}{\rho} (\phi(\eta_i) - \psi(a))} + \sum_{r=1}^{k} \sigma_r \rho \Gamma (1 + \delta_r) \right).
\]

Solving the above equation, we get the value

\[
c_1 = \frac{1}{\Omega} \left( A - \sum_{i=1}^{m} \gamma_i \rho_{\gamma^\alpha} [F_u(\eta_i)] - \sum_{j=1}^{n} \kappa_j \rho_{\gamma^\alpha}^{\beta_j, \psi} [F_u(\xi_j)] - \sum_{r=1}^{k} \sigma_r \rho_{\gamma^\alpha}^{\delta_r, \psi} [F_u(\theta_r)] \right),
\]

where \( \Omega \) is given as in (2.4). Taking \( c_1 \) in (2.5), we obtain (2.3).

On the other hand, it is easy to show by direct computing that \( u(t) \) is provided as in (2.3) verifies (2.2) via the given MNCs. The proof is done. \( \square \)
3. Existence results

By using Lemma 2.1, we will set the operator $\mathcal{K} : \mathcal{E} \to \mathcal{E}$

$$(\mathcal{K}u)(t) = \rho \frac{\eta^\prime}{\alpha^\prime} [F_u(t)] + \frac{e^{-\rho t}}{\Omega} \left( A - \sum_{i=1}^{m} \gamma_i \rho \frac{\eta^\prime}{\alpha^\prime} [F_u(\eta_i)] - \sum_{j=1}^{n} \kappa_j \rho \frac{\eta^\prime}{\alpha^\prime} [F_u(\xi_j)] \right)$$

$$- \sum_{r=1}^{k} \sigma_r \rho \frac{\eta^\prime}{\alpha^\prime} [F_u(\theta_r)]$$

where $\mathcal{K}_1, \mathcal{K}_2 : \mathcal{E} \to \mathcal{E}$ defined by

$$(\mathcal{K}_1u)(t) = \rho \frac{\eta^\prime}{\alpha^\prime} F_u(t)$$

$$(\mathcal{K}_2u)(t) = \frac{e^{-\rho t}}{\Omega} \left( A - \sum_{i=1}^{m} \gamma_i \rho \frac{\eta^\prime}{\alpha^\prime} [F_u(\eta_i)] - \sum_{j=1}^{n} \kappa_j \rho \frac{\eta^\prime}{\alpha^\prime} [F_u(\xi_j)] \right)$$

$$- \sum_{r=1}^{k} \sigma_r \rho \frac{\eta^\prime}{\alpha^\prime} [F_u(\theta_r)]$$

Notice that $\mathcal{K}u = \mathcal{K}_1u + \mathcal{K}_2u$. It should be noted that (1.11) has solutions if and only if $\mathcal{K}$ has fixed points. Next, we are going to examine the existence properties of solutions for (1.11), which is discussed by employing Banach’s FPT, Leray-Schauder’s nonlinear alternative and Krasnoselskii’s FPT. For the benefit of calculation in this work, we will provide the constants:

$$\Theta(\sigma, \sigma) = \frac{(\psi(\sigma) - \psi(a))^\sigma}{\rho^\sigma \Gamma(\sigma + 1)},$$

$$\Lambda = \Theta(T, \alpha) + \frac{1}{\Omega} \left( \sum_{i=1}^{m} |\gamma_i| \Theta(\eta_i, \alpha) + \sum_{j=1}^{n} |\kappa_j| \Theta(\xi_j, \alpha - \beta_j) + \sum_{r=1}^{k} |\sigma_r| \Theta(\theta_r, \alpha + \delta_r) \right).$$

3.1. Uniqueness property

Firstly, the uniqueness result for (1.11) will be studied by applying Banach’s FPT.

**Lemma 3.1.** (Banach contraction principle [59]) Assume that $\mathcal{B}$ is a non-empty closed subset of a Banach space $\mathcal{E}$. Then any contraction mapping $\mathcal{K}$ from $\mathcal{B}$ into itself has a unique fixed point.

**Theorem 3.2.** Let $f \in C(\mathcal{F} \times \mathbb{R}^4, \mathbb{R})$ so that:

(H1) there exist constants $L_1 > 0, L_2 > 0, 0 < L_3 < 1$ so that

$$|f(t, u_1, v_1, w_1, z_1) - f(t, u_2, v_2, w_2, z_2)| \leq L_1(|u_1 - u_2| + |v_1 - v_2|) + L_2|w_1 - w_2| + L_3|z_1 - z_2|,$$

for all $u_i, v_i, w_i, z_i \in \mathbb{R}$, $i = 1, 2, t \in \mathcal{F}$. 

**AIMS Mathematics**
If
\[ \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda < 1, \] (3.6)
then the Caputo-FPIDE with MNCs (1.11) has a unique solution on \( \mathcal{J} \), where (3.4) and (3.5) refers to \( \Theta(T, \omega) \) and \( \Lambda \).

**Proof.** First, we will convert (1.11) into \( u = Ku \), where \( K \) is given as in (3.1). Clearly, the fixed points of \( K \) are solutions to (1.11). By using the Banach’s FPT, we are going to prove that \( K \) has a FPT which is a unique solution of (1.11).

Define \( \sup_{t \in J} |f(t, 0, 0, 0)| := M_1 < \infty \) and setting \( B_{r_1} := \{ u \in \mathcal{E} : ||u|| \leq r_1 \} \) with
\[ r_1 \geq \frac{M_1 \Lambda}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda}, \] (3.7)
where \( \Omega, \Theta(T, \omega) \) and \( \Lambda \) are given as in (2.4), (3.4) and (3.5). Clearly, \( B_{r_1} \) is a bounded, closed and convex subset of \( \mathcal{E} \). We have divided the method of the proof into two steps:

**Step I.** We prove that \( KB_{r_1} \subset B_{r_1} \).

For each \( u \in B_{r_1} \), we obtain
\[
|\mathcal{K}u(t)| \leq \rho_{\alpha}^{\alpha, \phi}_{\alpha} |F_u(t)| + \frac{e^\gamma(t) \rho_{\alpha}^{\alpha, \phi}_{\alpha} (\phi(t) - \psi(a))}{|\Omega|} \left( |A| + \sum_{j=1}^m |\gamma_j| \rho_{\alpha}^{\alpha, \phi}_{\alpha} |u(\eta_j)| + \sum_{j=1}^n |\kappa_j| \rho_{\alpha}^{\alpha, \phi}_{\alpha} |\xi_j| + \sum_{r=1}^i |\sigma_r| \rho_{\alpha}^{\alpha, \phi}_{\alpha} |\theta_r| \right).
\]

From the assumption (\( H_1 \)), it follows that
\[
|F_u(t)| \leq |f(t, u(t), u(\lambda t), \rho_{\alpha}^{\alpha, \phi}_{\alpha} [u(\lambda t)], F_u(\lambda t)) - f(t, 0, 0, 0, 0)| + |f(t, 0, 0, 0, 0)| \leq L_1 (|u(t)| + |u(t)|) + L_2 |\rho_{\alpha}^{\alpha, \phi}_{\alpha} [u(\lambda t)]| + L_3 |F_u(\lambda t)| + M_1 \leq 2L_1 ||u|| + L_2 ||u|| \rho_{\alpha}^{\alpha, \phi}_{\alpha} [1](t) + L_3 ||F_u(\lambda t)|| + M_1 = \left( 2L_1 + L_2 (\psi(T) - \psi(a))^{\alpha - 1} \rho_{\alpha}^{\alpha, \phi}_{\alpha} (\omega + 1) \right) ||u|| + L_3 ||F_u(\lambda t)|| + M_1.
\]

Then
\[
||F_u(\lambda t)|| \leq (2L_1 + L_2 \Theta(T, \omega)) ||u|| + M_1.
\]
This implies that
\[
|\mathcal{K}u(t)| \leq \rho_{\alpha}^{\alpha, \phi}_{\alpha} \left( \frac{(2L_1 + L_2 \Theta(T, \omega)) ||u|| + M_1}{1 - L_3} \right) (t) + \frac{e^\gamma(t) \rho_{\alpha}^{\alpha, \phi}_{\alpha} (\phi(t) - \psi(a))}{|\Omega|} \left( |A| + \sum_{j=1}^m |\gamma_j| \rho_{\alpha}^{\alpha, \phi}_{\alpha} \left( \frac{(2L_1 + L_2 \Theta(T, \omega)) ||u|| + M_1}{1 - L_3} \right) \eta_j \right) + \sum_{j=1}^n |\kappa_j| \rho_{\alpha}^{\alpha, \phi}_{\alpha} \left( \frac{(2L_1 + L_2 \Theta(T, \omega)) ||u|| + M_1}{1 - L_3} \right) \xi_j.
\]
By using the fact of $0 < e^{-\frac{\rho(t)}{\rho(t) - \psi(s)}} \leq 1$, $a \leq s < t \leq T$, it follows that

$$|(Ku)(t)| \leq \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) (\Theta(T, \alpha) + 1) \left[ \sum_{i=1}^{m} |\gamma_i (\psi(\eta_i) - \psi(\alpha))^{\rho^\alpha} \right] + \frac{|A|}{|\Omega|} \left| \Theta(\eta, \alpha) \right| + \frac{M_1 |\Lambda|}{1 - L_3} + \frac{|A|}{|\Omega|} \leq r_1,$$

which implies that $\|Ku\| \leq r_1$. Thus, $KB_1 \subset B_{r_1}$.

**Step II.** We prove that $K : E \to E$ is contraction.

For each $u, v \in \mathcal{E}$, $t \in \mathcal{J}$, we obtain

$$|(Ku)(t) - (Kv)(t)| \leq r^*_{\alpha, \beta, \xi}(u - v)(T) + \frac{e^{-\frac{\rho(t)}{\rho(t) - \psi(s)}}}{|\Omega|} \left( \sum_{i=1}^{m} |\gamma_i |^{r^*_{\alpha, \beta, \xi}} |u - v| \right) + \frac{M_1 |\Lambda|}{1 - L_3} + \frac{|A|}{|\Omega|} \leq r_1.$$  

(3.8)

From (H1) again, we can compute that

$$|F_u(t) - F_v(t)| \leq \left| f(t, u(t), u(\alpha)), \lambda u(\alpha), \lambda u(\alpha) \right| + \left| f(t, v(t), v(\alpha)), \lambda v(\alpha), \lambda v(\alpha) \right| + \frac{L_1 |u(t) - v(t)|}{\rho^\alpha \Theta(\alpha) + 1} + \frac{L_2 |u(\alpha) - v(\alpha)|}{\rho^\alpha \Theta(\alpha) + 1} + \frac{L_3 |u(\alpha) - v(\alpha)|}{\rho^\alpha \Theta(\alpha) + 1} + \frac{L_4 |u(\alpha) - v(\alpha)|}{\rho^\alpha \Theta(\alpha) + 1} \leq 2L_1 |u - v| + \frac{L_2 |\psi(T) - \psi(\alpha)|^{\rho^\alpha}}{\rho^\alpha \Theta(\alpha) + 1} |u - v|.$$  

(3.9)

By inserting (3.9) into (3.8), one has

$$|(Ku)(t) - (Kv)(t)| \leq r^*_{\alpha, \beta, \xi} \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) |u - v|.$$  

Then

By inserting (3.9) into (3.8), one has

$$|(Ku)(t) - (Kv)(t)| \leq r^*_{\alpha, \beta, \xi} \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) |u - v|.$$  

(3.8)

(3.9)

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[\mathcal{K}u - \mathcal{K}v] \leq (2L_1 + L_2 \Theta(T, \omega))(1 - \Lambda)\|u - v\|. \] It follows from \([(2L_1 + L_2 \Theta(T, \omega))(1 - \Lambda)\] < 1, that \(\mathcal{K}\) is contraction. Then, (from Lemma 3.1), we conclude that \(\mathcal{K}\) has the unique fixed point, that is the unique solution to (1.11) in \(\mathcal{E}\).

\[\square\]

### 3.2. Existence property via Leray-Schauder’s type

Next, Leray-Schauder’s nonlinear alternative is employed to analyze in the second property.

**Lemma 3.3.** (Leray-Schauder’s nonlinear alternative [59]) Assume that \(\mathcal{E}\) is a Banach space, \(C\) is a closed and convex subset of \(M\), \(X\) is an open subset of \(C\) and \(\emptyset \neq X \subseteq \mathcal{E}\). Assume that \(F : \overline{X} \rightarrow C\) is continuous, compact (that is, \(F(\overline{X})\) is a relatively compact subset of \(C\)) map. Then either (i) \(F\) has a fixed point in \(\overline{X}\), or (ii) there is \(x \in \partial X\) (the boundary of \(X\) in \(C\)) and \(q \in (0, 1)\) with \(z = qF(z)\).

**Theorem 3.4.** Assume that \(f \in C(\mathcal{J} \times \mathbb{R}^4, \mathbb{R})\) so that:

- \((H_2)\) there exists \(\Psi : (\mathbb{R}^+) \times (\mathbb{R}^+)\) and \(\Psi\) is non-decreasing, \(p, q \in C(\mathcal{J}, \mathbb{R}^+)\), \(\varrho \in C(\mathcal{J}, \mathbb{R}^+ \cup \{0\})\) so that
  \[|f(t, u, v, w, z)| \leq p(t)\Psi(|u| + |v|) + f(t)|w| + q(t)|z|, \quad \forall t \in \mathcal{J}, \quad \forall u, v, w, z \in \mathbb{R},\]
  where \(p_0 = \sup_{t \in \mathcal{J}} p(t)\), \(f_0 = \sup_{t \in \mathcal{J}} |f(t)|\), \(q_0 = \sup_{t \in \mathcal{J}} q(t) < 1\).

- \((H_3)\) there exists a constant \(N > 0\) so that
  \[\frac{N}{\|\eta\|} + \left(\frac{L_1 \Theta(T, \omega) + 2p_0 \Psi(N)}{1 - q_0}\right) > 1,\]
  where \(\Theta(T, \omega)\) and \(\Lambda\) are given as in (3.4) and (3.5).

Then the Caputo-PIDE with MNCs (1.11) has at least one solution.

**Proof.** Assume that \(\mathcal{K}\) is given as in (3.1). Next, we are going to prove that \(\mathcal{K}\) maps bounded sets (balls) into bounded sets in \(\mathcal{E}\). For any \(r_2 > 0\), assume that \(B_{r_2} := \{u \in \mathcal{E} : \|u\| \leq r_2\} \subseteq \mathcal{E}\), we have, for each \(t \in \mathcal{J}\),

\[|(\mathcal{K}u)(t)| \leq \rho^{u, \varphi}(B_{r_2}) F(u)(T) + \frac{e^{\frac{\varphi - 1}{p} |\phi(T) - \phi(a)|}}{|\Omega|} \left(\|u\| + \sum_{i=1}^{m} |\gamma_i| |\psi_i(u)| + \sum_{j=1}^{n} |\kappa_j| |\psi_j(u)| \right),\]

\[\text{AIMS Mathematics} \quad \text{Volume 7, Issue 6, 9549–9576.}\]
Then, we have
\[ |C_{\mathcal{P}}^{\alpha,\psi} u(t)| \leq p(t)\Psi(|u(t)| + |u(\omega)|) + f(t)|\frac{\phi(T) - \phi(a)}{\rho^\alpha}\|u(\omega)||u| + q(t)|C_{\mathcal{P}}^{\alpha,\psi} u(t)|. \]

It follows from (H2) that
\[ |C_{\mathcal{P}}^{\alpha,\psi} u(t)| \leq p(t)\Psi(|u(t)| + |u(\omega)|) + f(t)|\frac{\phi(T) - \phi(a)}{\rho^\alpha}\|u(\omega)||u| + q(t)|C_{\mathcal{P}}^{\alpha,\psi} u(t)|. \]

Then, we have
\[ |C_{\mathcal{P}}^{\alpha,\psi} u(t)| \leq \frac{p(t)\Psi(2||u||) + f(t)\Theta(T, \omega)||u||}{1 - q(t)}. \]

For any \( a \leq s < t \leq T \), we have \( 0 < e^{\frac{-1}{\rho}(\phi(t) - \phi(s))} \leq 1 \), then
\[ |(\mathcal{K}u)(t)| \leq \left( \frac{2p_0\Psi(||u||) + f_0\Theta(T, \omega)||u||}{1 - q_0} \right) A + \frac{|A|}{|\Omega|}, \]

which leads to
\[ ||\mathcal{K}u|| \leq \left( \frac{2p_0\Psi(||u||) + f_0\Theta(T, \omega)||u||}{1 - q_0} \right) A + \frac{|A|}{|\Omega|} := N. \]

Now, we will prove that \( \mathcal{K} \) maps bounded sets into equicontinuous sets of \( \mathcal{E} \).

Given \( \tau_1 < \tau_2 \) where \( \tau_1, \tau_2 \in \mathcal{F} \), and for each \( u \in B_{\mathcal{R}} \), then, we obtain
\[ ||(\mathcal{K}u)(\tau_2) - (\mathcal{K}u)(\tau_1)|| \]
\[ \leq \left| C_{\mathcal{P}}^{\alpha,\psi} [F_u(\tau_2) - F_u(\tau_1)] \right| + \left| \frac{e^{\frac{-1}{\rho}(\phi(\tau_2) - \phi(\omega))} - e^{\frac{-1}{\rho}(\phi(\tau_1) - \phi(\omega))}}{|\Omega|} \right| \left( |A| + \sum_{i=1}^m |\gamma_i| \right) C_{\mathcal{P}}^{\alpha,\psi} [F_u(\eta)]
+ \sum_{j=1}^n |\kappa_j| C_{\mathcal{P}}^{\alpha,\psi} [F_u(\xi_j)] + \sum_{i=1}^k |\sigma_r| C_{\mathcal{P}}^{\alpha,\psi} [F_u(\theta_i)]
\]
\[ \leq \left( \frac{2p_0\Psi(||u||) + f_0\Theta(T, \omega)||u||}{1 - q_0} \right) \left( \frac{1}{\rho^\alpha\Gamma(\alpha)} \int_{\tau_1}^{\tau_2} \rho^\alpha H_{\rho^\alpha}^{-1}(\tau_2, s)\psi(s)ds \right)
+ \frac{1}{\rho^\alpha\Gamma(\alpha)} \int_{\tau_1}^{\tau_2} \rho^\alpha H_{\rho^\alpha}^{-1}(\tau_2, s) - \rho^\alpha H_{\rho^\alpha}^{-1}(\tau_1, s) \psi(s)ds \right)
+ \left| \frac{e^{\frac{-1}{\rho}(\phi(\tau_2) - \phi(\omega))} - e^{\frac{-1}{\rho}(\phi(\tau_1) - \phi(\omega))}}{|\Omega|} \right| \left( \frac{2p_0\Psi(||u||) + f_0\Theta(T, \omega)||u||}{1 - q_0} \right) \times \left( |A| + \sum_{i=1}^m |\gamma_i| (\phi(\eta_i) - \phi(\omega)) + \sum_{j=1}^n |\kappa_j| (\phi(\xi_j) - \phi(\omega)) + \sum_{r=1}^k |\sigma_r| (\psi(\theta_r) - \psi(\omega)) \right) \]

\( \frac{\rho^\alpha\Gamma(\alpha + 1)}{\rho^\alpha\Gamma(\alpha + 1)} + \frac{\rho^\alpha\Gamma(\alpha + 1)}{\rho^\alpha\Gamma(\alpha + 1)} + \frac{\rho^\alpha\Gamma(\alpha + 1)}{\rho^\alpha\Gamma(\alpha + 1)} \)
Assume that

\[ \text{Hence, by the Arzelá-Ascoli property, } u \in (Krasnoselskii's fixed point theorem [60]) \]

Let

\[ x, y \in M \]

Clearly, which independent of \( u \in B_{r_2} \) the above inequality, \(|(Ku)(\tau_2) - (Ku)(\tau_1)| \to 0 \) as \( \tau_2 \to \tau_1 \). Hence, by the Arzelá-Ascoli property, \( K : E \to E \) is completely continuous.

Next, we will prove that there is \( B \subseteq E \) where \( B \) is an open set, \( u \neq \varphi(Ku) \) for \( \varphi \in (0, 1) \) and \( u \in \partial B \).

Assume that \( u \in E \) is a solution of \( u = \varphi(Ku) \), \( \varphi \in (0, 1) \). Hence, it follows that

\[
|u(t)| = |\varphi(Ku)(t)| \\
\leq \frac{|A|}{|\Omega|} + \left( \frac{2p_0\Psi(||u||) + f_0(0, T, \omega)||u||}{1 - q_0} \right) \\
\times \left| \Theta(T, \alpha) + \frac{1}{|\Omega|} \left( \sum_{i=1}^{m} |\gamma_i|\Theta(\eta_i, \alpha) + \sum_{j=1}^{n} |\kappa_j|\Theta(\xi_j, \alpha - \beta_j) + \sum_{r=1}^{k} |\sigma_r|\Theta(\theta_r, \alpha + \delta_r) \right) \right| \\
= \frac{|A|}{|\Omega|} + \left( \frac{2p_0\Psi(||u||) + f_0(0, T, \omega)||u||}{1 - q_0} \right) \Lambda,
\]

which yields

\[
||u|| \leq \frac{|A|}{|\Omega|} + \left( \frac{2p_0\Psi(||u||) + f_0(0, T, \omega)||u||}{1 - q_0} \right) \Lambda.
\]

Consequently,

\[
\frac{||u||}{\frac{|A|}{|\Omega|} + \left( \frac{2p_0\Psi(||u||) + f_0(0, T, \omega)||u||}{1 - q_0} \right) \Lambda} \leq 1.
\]

By \( (H_3) \), there is \( N \) so that \( ||u|| \neq N \). Define

\[
B = \{ u \in E : ||u|| < N \} \quad \text{and} \quad Q = B \cap B_{r_2}.
\]

Note that \( K : \overline{Q} \to E \) is continuous and completely continuous. By the option of \( Q \), there is no \( u \in \partial Q \) so that \( u = \varphi(Ku) \), \( \varphi \in (0, 1) \). Thus, (by Lemma 3.3), we conclude that \( K \) has fixed point \( u \in \overline{Q} \) which verifies that (1.11) has at least one solution.

\[ \square \]

3.3. Existence property via Krasnosel’skiı’s fixed point theorem

By applying Krasnosel’skiı’s FPT, the existence property will be achieved.

**Lemma 3.5.** (Krasnosel’skiı’s fixed point theorem [60]) Let \( M \) be a closed, bounded, convex and nonempty subset of a Banach space. Let \( K_1, K_2 \) be the operators such that (i) \( K_1x + K_2y \in M \) whenever \( x, y \in M \); (ii) \( K_1 \) is compact and continuous; (iii) \( K_2 \) is contraction mapping. Then there exists \( z \in M \) such that \( z = K_1z + K_2z \).

**Theorem 3.6.** Suppose that \( (H_1) \) holds and \( f \in C(\mathcal{J} \times \mathbb{R}^4, \mathbb{R}) \) so that:
Define $\sup_{t \in \mathcal{I}} |g(t)| = ||g||$. If $\exists \in C(\mathcal{J} \times \mathbb{R}^4)$ so that

$$f(t, u, v, w, z) \leq g(t), \quad \forall (t, u, v, w, z) \in \mathcal{J} \times \mathbb{R}^4.$$ 

If

$$\left(\frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3}\right) (\Lambda - \Theta(T, \alpha)) < 1,$$

then the Caputo-PIDE with MNCs (1.11) has at least one solution.

**Proof.** Define $\sup_{t \in \mathcal{J}} |g(t)| = ||g||$ and picking

$$r_3 \geq \frac{|A|}{|\Omega|} + ||g||\Lambda,$$

we consider $B_{r_3} = \{u \in \mathcal{E} : ||u|| \leq r_3\}$. Define $\mathcal{K}_1$ and $\mathcal{K}_2$ on $B_{r_3}$ as (3.2) and (3.3).

For any $u, v \in B_{r_3}$, we obtain

$$||(\mathcal{K}_1 u)(t) + (\mathcal{K}_2 v)(t)||$$

$$\leq \sup_{t \in \mathcal{J}} \left\{ \rho^\alpha |F_u(t)| + \frac{e^{\frac{r_3}{r}} \left(\psi(T) - \psi(a)\right)^\alpha}{|\Omega|} \left[|A| + \sum_{i=1}^{m} |\gamma_i| |F_v(\eta_i)| + \sum_{j=1}^{n} |\eta_j| |F_v(\xi_j)| + \sum_{r=1}^{k} |\sigma_r| \left(\psi(\theta_r) - \psi(a)\right)^{\alpha+\delta_r} |F_v(\theta_r)| \right] \right\}$$

$$\leq \frac{|A|}{|\Omega|} + ||g|| \left( \frac{(\psi(T) - \psi(a))^\alpha}{\rho^\alpha \Gamma(\alpha + 1)} + \frac{1}{|\Omega|} \left( \sum_{i=1}^{m} |\gamma_i| (\psi(\eta_i) - \psi(a))^\alpha \rho^\alpha \Gamma(\alpha + 1) + \sum_{j=1}^{n} |\eta_j| (\psi(\xi_j) - \psi(a))^{\alpha - \beta_j} \rho^\alpha \Gamma(\alpha - \beta_j + 1) + \sum_{r=1}^{k} |\sigma_r| (\psi(\theta_r) - \psi(a))^{\alpha+\delta_r} \rho^\alpha \Gamma(\alpha + \delta_r + 1) \right) \right)$$

$$= \frac{|A|}{|\Omega|} + ||g||\Lambda \leq r_3.$$ 

This implies that $\mathcal{K}_1 u + \mathcal{K}_2 v \in B_{r_3}$, which verifies Lemma 3.5 (i).

Next, we are going to show that Lemma 3.5 (ii) is verified.

Assume that $u_n$ is a sequence so that $u_n \to u \in \mathcal{E}$ as $n \to \infty$. Hence, we get

$$||(\mathcal{K}_1 u_n)(t) - (\mathcal{K}_1 u)(t)|| \leq |\mathcal{K}_1 u_n - \mathcal{K}_1 u| \leq \Theta(T, \alpha)||F_{u_n} - F_u||.$$ 

Since $f$ is continuous, verifies that $F_u$ is also continuous. By the Lebesgue dominated convergent theorem, we have

$$|(\mathcal{K}_1 u_n)(t) - (\mathcal{K}_1 u)(t)| \to 0 \quad \text{as} \quad n \to \infty.$$ 

Therefore,

$$||\mathcal{K}_1 u_n - \mathcal{K}_1 u|| \to 0 \quad \text{as} \quad n \to \infty.$$ 

Thus, implies that $\mathcal{K}_1 u$ is continuous. Also, the set $\mathcal{K}_1 B_{r_3}$ is uniformly bounded as

$$||\mathcal{K}_1 u|| \leq \Theta(T, \alpha)||g||.$$
Next step, we will show the compactness of $\mathcal{K}_1$.

Define $\sup \{|f(t, u, v, w, z)\}; (t, u, v, w, z) \in \mathcal{J} \times \mathbb{R}^4\} = f^* < \infty$, thus, for each $\tau_1, \tau_2 \in \mathcal{J}$ with $\tau_1 \leq \tau_2$, it follows that

$$|\langle (\mathcal{K}_1 u)(\tau_2) - (\mathcal{K}_1 u)(\tau_1) \rangle| = \left| \rho^{\alpha,\psi}_a [F_u(\tau_2)] - \rho^{\alpha,\psi}_a [F_u(\tau_1)] \right| \leq \frac{1}{\rho^\delta \Gamma(\alpha + 1)} \left| (\psi(\tau_2) - \psi(\alpha))^{\alpha} - (\psi(\tau_1) - \psi(\alpha))^{\alpha} \right| + 2 (\psi(\tau_2) - \psi(\tau_1))^{\alpha} f^*.$$  

Clearly, the right-hand side of the above inequality is independent of $u$ and $|\langle (\mathcal{K}_1 u)(\tau_2) - (\mathcal{K}_1 u)(\tau_1) \rangle| \to 0$, as $\tau_2 \to \tau_1$. Hence, the set $\mathcal{K}_1 B_r$ is equicontinuous, also $\mathcal{K}_1$ maps bounded subsets into relatively compact subsets, which implies that $\mathcal{K}_1 B_r$ is relatively compact.

By the Arzelá-Ascoli theorem, then $\mathcal{K}_1$ is compact on $B_r$.

Finally, we are going to show that $\mathcal{K}_2$ is contraction.

For each $u, v \in B_r$, and $t \in \mathcal{J}$, we get

$$|\langle (\mathcal{K}_2 u)(t) - (\mathcal{K}_2 v)(t) \rangle| \leq \frac{1}{|\Omega|} \left( \sum_{i=1}^{m} |\gamma_i| |\rho^\delta_a [F_u - F_v](\eta_i)| + \sum_{j=1}^{n} |\kappa_j| |\rho^\delta_a (|\psi(\eta_j) - \psi(\alpha)|^{\alpha - \beta_j})| [F_u - F_v](\xi_j) + \sum_{r=1}^{k} |\sigma_r| |\rho^\delta_a [F_u - F_v](\theta_r)| \right) \leq \frac{1}{|\Omega|} \left( \sum_{i=1}^{m} |\gamma_i| |(\psi(\eta_i) - \psi(\alpha))^{\alpha - \beta_j}| \rho^\delta \Gamma(\alpha + 1) + \sum_{j=1}^{n} \frac{|\kappa_j| |(\psi(\eta_j) - \psi(\alpha))^{\alpha - \beta_j}|}{\rho^\delta \Gamma(\alpha - \beta_j + 1)} + \sum_{r=1}^{k} \frac{|\sigma_r| |(\psi(\eta_j) - \psi(\alpha))^{\alpha + \delta_r}|}{\rho^\delta \Gamma(\alpha + \delta_r + 1)} \right) \times \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \|u - v\| \leq \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) (\lambda - \Theta(T, \alpha)) \|u - v\|.$$

Since (3.10) holds, implies that $\mathcal{K}_2$ is contraction and also Lemma 3.5 (iii) verifies. Therefore, the assumptions of Lemma 3.5 are verified. Then, (by Lemma 3.5) which verifies that (1.11) has at least one solution. \hfill \Box

4. Stability results

This part is proving different kinds of US like HU stable, GHU stable, HUR stable and GHUR stable of the Caputo-PFIDE with MNCs (1.11).

**Definition 4.1.** The Caputo-PFIDE with MNCs (1.11) is called HU stable if there is a constant $\Delta_f > 0$ so that for every $\epsilon > 0$ and the solution $z \in E$ of

$$\left| C^{\rho^\delta_a \psi}_a [z(t)] - f(t, z(t), z(\lambda t), \rho^\delta_a \psi [z(\lambda t)]) \right| \leq \epsilon, \quad (4.1)$$

there exists the solution $u \in E$ of (1.11) so that

$$|z(t) - u(t)| \leq \Delta_f \epsilon, \quad t \in \mathcal{J}. \quad (4.2)$$

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Definition 4.2. The Caputo-PFIDE with MNCs (1.11) is called GHU stable if there is a function $\Phi \in C(\mathbb{R}^+, \mathbb{R}^+)$ via $\Phi(0) = 0$ so that, for every solution $z \in E$ of

$$\left| C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z](t) - f(t, z(t), z(\lambda t), \rho_{\alpha+\beta} m_{a^+}[z(\lambda t)], C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z(\lambda t)]) \right| \leq \epsilon \Phi(t),$$

there is the solution $u \in E$ of (1.11) so that

$$|z(t) - u(t)| \leq \Phi(\epsilon), \quad t \in J.$$  \hspace{0.5cm} (4.3)

Definition 4.3. The Caputo-PFIDE with MNCs (1.11) is called HUR stable with respect to $\Phi \in C(J, \mathbb{R}^+)$ if there is a constant $\Delta_{f, \Phi} > 0$ such that for every $\epsilon > 0$ and for any the solution $z \in E$ of (4.3) there is the solution $u \in E$ of (1.11) so that

$$|z(t) - u(t)| \leq \Delta_{f, \Phi} \epsilon \Phi(t), \quad t \in J.$$  \hspace{0.5cm} (4.4)

Definition 4.4. The Caputo-PFIDE with MNCs (1.11) is called GHUR stable with respect to $\Phi \in C(J, \mathbb{R}^+)$ if there is a constant $\Delta_{f, \Phi} > 0$ such that for any the solution $z \in E$ of

$$\left| C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z](t) - f(t, z(t), z(\lambda t), \rho_{\alpha+\beta} m_{a^+}[z(\lambda t)], C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z(\lambda t)]) \right| \leq \Phi(t),$$

there is the solution $u \in E$ of (1.11) so that

$$|z(t) - u(t)| \leq \Delta_{f, \Phi} \Phi(t), \quad t \in J.$$  \hspace{0.5cm} (4.5)

Remark 4.5. Clearly, (i) Definition 4.1 $\Rightarrow$ Definition 4.2; (ii) Definition 4.3 $\Rightarrow$ Definition 4.4; (iii) Definition 4.3 for $\Phi(t) = 1$ $\Rightarrow$ Definition 4.1.

Remark 4.6. $z \in E$ is the solution of (4.1) if and only if there is the function $w \in E$ (which depends on $z$) so that: (i) $|w(t)| \leq \epsilon$, $\forall t \in J$; (ii) $C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z](t) = F_z(t) + w(t)$, $t \in J$.

Remark 4.7. $z \in E$ is the solution of (4.3) if and only if there is the function $v \in E$ (which depends on $z$) so that: (i) $|v(t)| \leq \epsilon \Phi(t)$, $\forall t \in J$; (ii) $C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z](t) = F_z(t) + v(t)$, $t \in J$.

4.1. HU stability and GHU stability

From Remark 4.6, the solution of

$$C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z](t) = f(t, z(t), z(\lambda t), \rho_{\alpha+\beta} m_{a^+}[z(\lambda t)], C_{\alpha+\beta} \mathcal{D}_{a^+}^{\alpha+\beta}[z(\lambda t)]) + w(t), \quad t \in J,$$

can be rewritten as

$$z(t) = \rho_{\alpha+\beta} m_{a^+}[F_z(t)] + \frac{e^{-n}(\psi(t))}{\Omega} \left( -\sum_{i=1}^{m} \gamma_{i} \nu_{\alpha+\beta} m_{a^+}[F_z(\eta_i)] \right) - \sum_{j=1}^{n} \sigma_{j} \nu_{\alpha+\beta} m_{a^+}[F_z(\xi_j)] + \frac{e^{-n}(\psi(t))}{\Omega} \left( -\sum_{i=1}^{m} \gamma_{i} \nu_{\alpha+\beta} m_{a^+}[w(\eta_i)] \right)$$

$$+ \sum_{j=1}^{n} \sigma_{j} \nu_{\alpha+\beta} m_{a^+}[w(\xi_j)] \right).$$

Firstly, the key lemma that will be applied in the presents of HU stable and GHU stable.
Lemma 4.8. Assume that $0 < \epsilon, \rho \leq 1$. If $z \in \mathbb{E}$ verifies (4.1), hence $z$ is the solution of

$$|z(t) - (\mathcal{K}z)(t)| \leq \Lambda \epsilon,$$

(4.9)

where $\Lambda$ is given as in (3.5).

Proof. By Remark 4.6 with (4.8), it follows that

$$|z(t) - (\mathcal{K}z)(t)| = |\sum_{i=1}^{m} \gamma_i \mathcal{D}^{\sigma_{a}^{\alpha} \phi} [w(t)] + \sum_{j=1}^{n} \kappa_j \mathcal{D}^{\beta_{j} \phi} [w(t)]|$$

$$= |\sum_{i=1}^{m} \gamma_i \mathcal{D}^{\sigma_{a}^{\alpha} \phi} [w(t)] + \sum_{j=1}^{n} \kappa_j \mathcal{D}^{\beta_{j} \phi} [w(t)]|$$

$$\leq \rho \frac{\Gamma(\alpha + 1)}{\Gamma(\alpha - \beta_j + 1)} \left( \sum_{i=1}^{m} \gamma_i |(\psi(t) - \psi(a))^{\alpha} \right) + \frac{1}{|\Omega|} \left( \sum_{i=1}^{m} \gamma_i |(\psi(t) - \psi(a))^{\alpha} \right) \left( \sum_{j=1}^{n} \kappa_j |(\psi(t) - \psi(a))^{\beta_{j}} \right)$$

$$= \Lambda \epsilon,$$

where $\Lambda$ is given by (3.5), from which (4.9) is achieved. \hfill \Box

Next, we will show the HU and GHU stability results.

Theorem 4.9. Suppose that $f \in C(\mathcal{J} \times \mathbb{R}^4, \mathbb{R})$. If (H1) is verified with (3.6) true. Hence the Caputo-PFIDE with MNCs (1.11) is HU stable as well as GHU stable on $\mathcal{J}$.

Proof. Assume that $z \in \mathcal{E}$ is the solution of (4.1) and assume that $u$ is the unique solution of

$$\begin{cases}
C_{\rho} \mathcal{D}^{\sigma_{a}^{\alpha} \phi} [u(t)] = f(t, u(t), u(\lambda t), \mathcal{D}^{\beta_{j} \phi} [u(t)], C_{\rho} \mathcal{D}^{\sigma_{a}^{\alpha} \phi} [u(\lambda t)]), & t \in (a, T), \ \lambda \in (0, 1), \\
\sum_{i=1}^{m} \gamma_i u(\eta_i) + \sum_{j=1}^{n} \kappa_j \mathcal{D}^{\beta_{j} \phi} [u(\xi_j)] + \sum_{i=1}^{k} \sigma_i \mathcal{D}^{\beta_{i} \phi} [u(\theta_i)] = A.
\end{cases}$$

By using $|x - y| \leq |x| + |y|$ with Lemma 4.8, one has

$$|z(t) - u(t)| = \left| \sum_{i=1}^{m} \gamma_i (z(t) - u(t)) + \sum_{j=1}^{n} \kappa_j (z(t) - u(t)) \right|$$

$$\leq \left| \sum_{i=1}^{m} \gamma_i (z(t) - u(t)) + \sum_{j=1}^{n} \kappa_j (z(t) - u(t)) \right|$$

$$= \Lambda \epsilon,$$
\[ \begin{align*}
&= |z(t) - (Kz)(t) + (Kz)(t) - (Ku)(t)| \\
&\leq |z(t) - (Kz)(t)| + |(Kz)(t) - (Ku)(t)| \\
&\leq \Lambda \epsilon + \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda |z(t) - u(t)|,
\end{align*} \]

where \( \Lambda \) is given as in (3.5). This offers \(|z(t) - u(t)| \leq \Delta_f \epsilon\), where

\[
\Delta_f = \frac{\Lambda}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda}.
\]

Then, the Caputo-FHIDE with MNCs (1.11) is HU stable. In addition, if we input \( \Phi(\epsilon) = \Delta_f \epsilon \) via \( \Phi(0) = 0 \), hence (1.11) is GHU stable. \( \square \)

### 4.2. The HUR stability and GHUR stability

Thanks of Remark 4.7, the solution

\[
\begin{align*}
\sigma_{\alpha, \varphi}^{ho}[z(t)] &= f(t, z(t), z(\lambda t), \psi_{\alpha, \varphi}^{*}[z(\lambda t)], \sigma_{\alpha, \varphi}^{*}[z(\lambda t)]) + v(t), \quad t \in (a, T],
\end{align*}
\]

can be rewritten as

\[
\begin{align*}
z(t) &= \sigma_{\alpha, \varphi}^{\rho}[z(t)] + \frac{e^{\rho} \rho}{\Omega} \left( A - \sum_{i=1}^{m} \gamma_{i}^{\rho} \sigma_{\alpha, \varphi}^{\rho}[F_{z}(\eta_{i})] - \sum_{j=1}^{n} \kappa_{j}^{\rho} \sigma_{\alpha, \varphi}^{\rho}[F_{z}(\xi_{j})] \\
&\quad - \sum_{r=1}^{k} \sigma_{\alpha, \varphi}^{\rho}[F_{z}(\theta_{r})] \right) + \frac{e^{\rho}}{\Omega} \left( \sum_{i=1}^{m} \gamma_{i}^{\rho} \sigma_{\alpha, \varphi}^{\rho}[v(\eta_{i})] \\
&\quad + \sum_{j=1}^{n} \kappa_{j}^{\rho} \sigma_{\alpha, \varphi}^{\rho}[v(\xi_{j})] + \sum_{r=1}^{k} \sigma_{\alpha, \varphi}^{\rho}[v(\theta_{r})] \right).
\end{align*}
\]

For the next proving, we state the following assumption:

(H3) there is an increasing function \( \Phi \in C(\mathcal{F}, \mathbb{R}^+) \) and there is a constant \( n_{\Phi} > 0 \), so that, for each \( t \in J \),

\[
\sigma_{\alpha, \varphi}^{\rho}[\Phi(t)] \leq n_{\Phi} \Phi(t).
\]

**Lemma 4.10.** Assume that \( z \in \mathcal{E} \) is the solution of (4.3). Hence, \( z \) verifies

\[
|z(t) - (Kz)(t)| \leq \Lambda \epsilon n_{\Phi} \Phi(t), \quad 0 < \epsilon \leq 1.
\]

where \( \Lambda \) is given as in (3.5).

**Proof.** From (4.11), we have

\[
\begin{align*}
|z(t) - (Kz)(t)| &\leq \sigma_{\alpha, \varphi}^{\rho}[v(t)] - \frac{e^{\rho}}{\Omega} \left( \sum_{i=1}^{m} \gamma_{i}^{\rho} \sigma_{\alpha, \varphi}^{\rho}[v(\eta_{i})] + \sum_{j=1}^{n} \kappa_{j}^{\rho} \sigma_{\alpha, \varphi}^{\rho}[v(\xi_{j})] + \sum_{r=1}^{k} \sigma_{\alpha, \varphi}^{\rho}[v(\theta_{r})] \right)
\end{align*}
\]

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where $\Lambda$ is given by (3.5), which leads to (4.13). □

Finally, we are going to show HUR and GHUR stability results.

**Theorem 4.11.** Suppose $f \in C(J \times \mathbb{R}^d, \mathbb{R})$. If $(H_1)$ is satisfied with (3.6) trues. Hence, the Caputo-HFIDE with MNCs (1.11) is HUR stable as well as GHUR stable on $J$.

**Proof.** Assume that $\epsilon > 0$. Suppose that $z \in \mathcal{E}$ is the solution of (4.6) and $u$ is the unique solution of (1.11). By using the triangle inequality, Lemma 4.8 and (4.11), we estimate that

$$
|z(t) - u(t)| = \left| z(t) - \frac{\rho_{\alpha,\psi}}{\rho_{\alpha,\psi}} [F_u(t)] - \frac{e^{\frac{\rho_{\alpha,\psi}}{\rho_{\alpha,\psi}}(\phi(t) - \phi(a))}}{A - \sum_{i=1}^{m} \gamma_i \rho_{\alpha,\psi} [F_u(\eta_i)]} - \sum_{i=1}^{m} \gamma_i \rho_{\alpha,\psi} [F_u(\eta_i)] \right| \\
= |z(t) - (Kz)(t) + (Kz)(t) - (Ku)(t)| \\
\leq |z(t) - (Kz)(t)| + |(Kz)(t) - (Ku)(t)| \\
\leq \Lambda e_{\phi} \Phi(t) + \left( \frac{2L_1 + L_2 \Theta(T_\omega)}{1 - L_2} \right) \Lambda |z(t) - u(t)|,
$$

where $\Lambda$ is given as in (3.5), verifies that $|z(t) - u(t)| \leq \Delta_{f,\phi} \epsilon \Phi(t)$, where

$$
\Delta_{f,\phi} := \frac{\Delta_{f,\phi} \epsilon \Phi(t)}{1 - \left( \frac{2L_1 + L_2 \Theta(T_\omega)}{1 - L_2} \right) \Lambda}.
$$

Then, the Caputo-HFIDE with MNCs (1.11) is HUR stable. In addition, if we input $\Phi(t) = \epsilon \Phi(t)$ with $\Phi(0) = 0$, then (1.11) is GHUR stable. □

5. Numerical examples

This part shows numerical instances that demonstrate the exactness and applicability of our main results.
Example 5.1. Discussion the following nonlinear Caputo-PFIDE with MNCs of the form:

\[
\begin{cases}
c^\frac{1}{\rho} \mathcal{D}^\frac{1}{\rho} [u(t)] = f \left( t, u(t), u \left( \frac{t}{\sqrt{3}} \right), c^\frac{1}{\rho} \mathcal{D}^\frac{1}{\rho} \left[ u \left( \frac{t}{\sqrt{3}} \right) \right] \right), & t \in (0, 1), \\
\sum_{i=1}^{2} \left( i \frac{1}{2} \right) u \left( \frac{2i+1}{5} \right) + \sum_{j=1}^{3} \left( j \frac{1}{5} \right) c^\frac{2}{\rho} \mathcal{D}^\frac{2}{\rho} \left[ u \left( \frac{j}{4} \right) \right] + \sum_{i=1}^{2} \left( i \frac{1}{3} \right) c^\frac{1}{\rho} \mathcal{D}^\frac{1}{\rho} \left[ u \left( \frac{r+1}{4} \right) \right] = 1.
\end{cases}
\]  

(5.1)

Here, \( \alpha = 1/2, \rho = 2/3, \psi(t) = \sqrt{t}, \lambda = 1/\sqrt{3}, \omega = 3/4, \sigma = 0, T = 1, m = 2, n = 3, k = 2, \gamma_i = (i + 1)/2, \eta_i = (2i + 1)/5, i = 1, 2, \kappa_j = (2j - 1)/5, \beta_j = (2j + 1)/20, \xi_j = j/4, j = 1, 2, 3, \sigma_r = r/3, \delta_r = r/(r + 1), \theta_r = (r + 1)/4, r = 1, 2. \) By using Python, we obtain that \( \Omega \approx 2.4309 \neq 0 \) and \( \Lambda \approx 4.042711 \).

(1) If we set the nonlinear function

\[
f(t, u, v, w) = \frac{1}{3^{r+1}(2 + \cos 2t)} \left( \frac{|u|}{1 + |u|} + \frac{|v|}{1 + |v|} + \frac{|w|}{1 + |w|} + \frac{|z|}{1 + |z|} \right).
\]

For any \( u_i, v_i, w_i, z_i \in \mathbb{R}, i = 1, 2 \) and \( t \in [0, 1] \), one has

\[
|f(t, u_1, v_1, w_1, z_1) - f(t, u_2, v_2, w_2, z_2)| \leq \frac{1}{3^{r+1}} (|u_1 - u_2| + |v_1 - v_2| + |w_1 - w_2| + |z_1 - z_2|).
\]

The assumption \( (H_1) \) is satisfied with \( L_1 = L_2 = L_3 = \frac{1}{27} \). Hence

\[
\left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda \approx 0.540287 < 1.
\]

All conditions of Theorem 3.2 are verified. Hence, the nonlinear Caputo-PFIDE with MNCs (5.1) has a unique solution on \([0, 1]\). Moreover, we obtain

\[
\Delta_f = \frac{\Lambda}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda} \approx 8.793988 > 0.
\]

Hence, from Theorem 4.9, the nonlinear Caputo-PFIDE with MNCs (5.1) is HU stable and also GHU stable on \([0, 1]\). In addition, by taking \( \Phi(t) = e^{\frac{\nu_1}{\rho} \phi(t)} (\psi(t) - \psi(0)) \), we have

\[
\frac{2\sqrt{\theta}}{\sqrt{3} \pi} e^{-0.5 \phi(t)} (\psi(t) - \psi(0))^3 \leq \frac{2\sqrt{\theta}}{\sqrt{3} \pi} (\psi(t) - \psi(0))^3 \Phi(t).
\]

Thus, (4.12) is satisfied with \( n_\phi = \frac{2\sqrt{\theta}}{\sqrt{3} \pi} > 0 \). Then, we have

\[
\Delta_{\phi, \Phi} := \frac{\Lambda n_\phi}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda} \approx 8.102058 > 0.
\]

Hence, from Theorem 4.11, the nonlinear Caputo-PFIDE with MNCs (5.1) is HUR stable and also GHUR stable.
(II) If we take the nonlinear function
\[ f(t, u, v, w) = \frac{1}{4^{t+2}} \left( \frac{|u| + |v|}{1 + |u| + |v|} + \frac{1}{2} \right) + \frac{1}{2^{t+3}} \left( \frac{|w| + |z|}{1 + |w| + |z|} + \frac{1}{2} \right), \]
we have
\[ |f(t, u, v, w, z)| \leq \frac{1}{4^{t+2}} \left( |u| + |v| + \frac{1}{2} \right) + \frac{1}{2^{t+3}} \left( |w| + |z| + \frac{1}{2} \right). \]
From the above inequality with (H2)–(H3), we get that \( p(t) = 1/4^{t+2}, \) \( \Psi(|u| + |v|) = |u| + |v| + 1/2 \) and \( h(t) = q(t) = 1/2^{t+3}. \) So, we have \( p_0 = 1/16 \) and \( h_0 = q_0 = 1/8. \) From all the data, we can compute that the constant \( N > 0.432489. \) All assumptions of Theorem 3.4 are verified. Hence, the nonlinear Caputo-PFIDE with MNCs (5.1) has at least one solution on \([0, 1].\) Moreover,
\[ \Delta_f := \frac{\Lambda}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{\Lambda} \right)} \approx 63.662781 > 0, \]
Hence, from Theorem 4.9, the nonlinear Caputo-PFIDE with MNCs 5.1 is HU stable and also GHU stable on \([0, 1].\) In addition, by taking \( \Phi(t) = e^{n \Phi(t)} (\psi(t) - \psi(0))^2, \) we have
\[ \frac{3}{2} \left[ \Phi(t) \right] = \frac{\sqrt{3\pi}}{2 \sqrt{2}} e^{-0.5 \Phi(t)} (\psi(t) - \psi(0)) \leq \frac{\sqrt{3\pi}}{2 \sqrt{2}} (\psi(t) - \psi(0))^{1/2} \Phi(t). \]
Thus, (4.12) is satisfied with \( n_\Phi = \frac{\sqrt{3\pi}}{2 \sqrt{2}} > 0. \) Then, we have
\[ \Delta_{f, \Phi} := \frac{\Lambda n_\Phi}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{\Lambda} \right)} \approx 69.0997 > 0, \]
Hence, from Theorem 4.11, the nonlinear Caputo-PFIDE with MNCs 5.1 is HUR stable and also GHUR stable on \([0, 1].\)

(III) If we set the nonlinear function
\[ f(t, u, v, w) = \frac{1}{4^{t+2}} \left( \frac{|u| + |v|}{1 + |u| + |v|} + \frac{1}{2} \right) + \frac{1}{2^{t+3}} \left( \frac{|w| + |z|}{1 + |w| + |z|} + \frac{1}{2} \right), \]
For \( u_i, v_i, w_i, z_i \in \mathbb{R}, i = 1, 2 \) and \( t \in [0, 1], \) we have
\[ |f(t, u_1, v_1, w_1, z_1) - f(t, u_2, v_2, w_2, z_2)| \leq \frac{1}{4^{t+2}} (|u_1 - u_2| + |v_1 - v_2|) + \frac{1}{2^{t+3}} (|w_1 - w_2| + |z_1 - z_2|). \]
The assumption \( (H_4) \) is satisfied with \( L_1 = L_2 = \frac{1}{16}, L_3 = \frac{1}{8} \) and
\[ |f(t, u, v, w, z)| \leq \frac{1}{4^{t+2}} + \frac{1}{2^{t+3}}, \]
which yields that
\[ g(t) = \frac{1}{4^{t+2}} + \frac{1}{2^{t+3}}. \]
Then
\[
\left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) (\Lambda - \Theta(T, \alpha)) \approx 0.660387 < 1.
\]
All assumptions of Theorem 3.6 are verified. Hence the nonlinear Caputo-PFIDE with MNCs (5.1) has at least one solution on [0, 1].
Furthermore, we get
\[
\Delta_f = \frac{\Lambda}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda} \approx 43.1392148 > 0.
\]
Hence, from Theorem 4.9, the nonlinear Caputo-PFIDE with MNCs (5.1) is HU stable and also GHU stable on [0, 1]. In addition, by taking \( \Phi(t) = e^{\frac{r}{\pi}}(\psi(t) - \psi(0))^2 \), we have
\[
\sum_{i=0}^{2} \Phi(t) = \frac{8 \sqrt{6}}{15 \sqrt{\pi}} e^{-0.5\phi(t)} (\psi(t) - \psi(0))^2 \leq \frac{8 \sqrt{6}}{15 \sqrt{\pi}} (\psi(t) - \psi(0))^2 \Phi(t).
\]
Thus, (4.12) is satisfied with \( n_\phi = \frac{8 \sqrt{6}}{15 \sqrt{\pi}} > 0 \). Then, we have
\[
\Delta_{f, \Phi} := \frac{\Lambda n_\phi}{1 - \left( \frac{2L_1 + L_2 \Theta(T, \omega)}{1 - L_3} \right) \Lambda} \approx 31.79594 > 0.
\]
Hence, from Theorem 4.11, the nonlinear Caputo-PFIDE with MNCs (5.1) is HUR stable and also GHUR stable on [0, 1].

Example 5.2. Discussion the following linear Caputo-PFIDE with MNCs of the form:
\[
\left\{ \begin{aligned}
\sum_{i=0}^{2} \left[ u(t) \right] &= e^{\frac{r}{\pi}}(\psi(t) - \psi(0))^2, \\
\sum_{i=1}^{2} \left[ u(t) \right] &= e^{\frac{r}{\pi}}(\psi(t) - \psi(0))^2.
\end{aligned} \right.
\]
(5.2)
By Lemma 2.1, the implicit solution of the problem (5.2)
\[
u(t) = \frac{\Gamma(\frac{3}{2})}{(\frac{3}{2})^\alpha \Gamma(\frac{5}{2} + \alpha)} e^{-\frac{r}{\pi}}(\psi(t) - \psi(0))^\frac{1}{2 + \alpha}
\]

\[
+ \frac{e^{-\frac{r}{\pi}}(\psi(t) - \psi(0))}{1 - \sum_{i=1}^{2} (i + 1) \Gamma(\frac{3}{2} + \alpha)} e^{-\frac{r}{\pi}}(\psi(t) - \psi(0))^\frac{1}{2 + \alpha}
\]

\[
- \sum_{j=1}^{2} \frac{\Gamma(\frac{3}{2})}{(\frac{3}{2})^\alpha \Gamma(\frac{5}{2} + \alpha)} e^{-\frac{r}{\pi}}(\psi(t) - \psi(0))^\frac{1}{2 + \alpha}
\]

\[
- \sum_{i=1}^{2} (\frac{r}{3})^{\alpha + \frac{r}{2 \alpha}} \Gamma(\frac{3}{2} + \alpha) e^{-\frac{r}{\pi}}(\psi(t) - \psi(0))^\frac{1}{2 + \alpha + \frac{r}{2 \alpha}}.
\]
where
\[
\Omega = \sum_{i=1}^{2} (\frac{r}{3})^{\alpha + \frac{r}{2 \alpha}} \Gamma(\frac{3}{2} + \alpha) e^{-\frac{r}{\pi}}(\psi(t) - \psi(0))^\frac{1}{2 + \alpha + \frac{r}{2 \alpha}}.
\]
We consider several cases of the following function \( \psi(t) \):
(I) If $\psi(t) = t^\alpha$ then the solution of linear Caputo-PFIDE with MNCs (5.2) is given as in

\[ u(t) = \frac{\Gamma\left(\frac{3}{2}\right)}{(\frac{2}{3})^\alpha \Gamma\left(\frac{3}{2} + \alpha\right)} e^{-\frac{\sin(t)}{\alpha}} + e^{-\frac{\sin(t)}{\alpha}} \left(1 - \sum_{i=1}^{2} \left(\chi_1 + \frac{1}{2}\right) \frac{\Gamma\left(\frac{3}{2} + \alpha\right)}{\Gamma\left(\frac{3}{2} + \alpha + \frac{r}{r+1}\right)} e^{-\frac{(\chi_1)}{r+1}} \right) + \frac{2}{(\frac{2}{3})^\alpha \Gamma\left(\frac{3}{2} + \alpha + \frac{r}{r+1}\right)} e^{-\frac{(\chi_1)}{r+1} + \frac{(\chi_2)}{r+1}} \]

where

\[ \Omega = \sum_{i=1}^{2} \left(\chi_1 + \frac{1}{2}\right) e^{-\frac{(\chi_1)}{r+1}} + \sum_{r=1}^{2} \left(\chi_1 + \frac{1}{2}\right) \frac{\Gamma\left(\frac{3}{2} + \alpha\right)}{\Gamma\left(\frac{3}{2} + \alpha + \frac{r}{r+1}\right)} e^{-\frac{(\chi_1)}{r+1} + \frac{(\chi_2)}{r+1}} \]

(II) If $\psi(t) = \frac{\sin(t)}{\alpha}$ then the solution of linear Caputo-PFIDE with MNCs (5.2) is given as in

\[ u(t) = \frac{\Gamma\left(\frac{3}{2}\right)}{(\frac{2}{3})^\alpha \Gamma\left(\frac{3}{2} + \alpha\right)} e^{-\frac{\sin(t)}{\alpha}} + \frac{2}{(\frac{2}{3})^\alpha \Gamma\left(\frac{3}{2} + \alpha + \frac{r}{r+1}\right)} e^{-\frac{(\sin(t))}{r+1} + \frac{(\sin(t))}{r+1} + \frac{(\sin(t))}{r+1}} \]

where

\[ \Omega = \sum_{i=1}^{2} \left(\chi_1 + \frac{1}{2}\right) e^{-\frac{(\chi_1)}{r+1}} + \sum_{r=1}^{2} \left(\chi_1 + \frac{1}{2}\right) \frac{\Gamma\left(\frac{3}{2} + \alpha\right)}{\Gamma\left(\frac{3}{2} + \alpha + \frac{r}{r+1}\right)} e^{-\frac{(\sin(t))}{r+1} + \frac{(\sin(t))}{r+1} + \frac{(\sin(t))}{r+1}} \]

(III) If $\psi(t) = e^{\alpha t}$ then the solution of linear Caputo-PFIDE with MNCs (5.2) is given as in

\[ u(t) = \frac{\Gamma\left(\frac{3}{2}\right)}{(\frac{2}{3})^\alpha \Gamma\left(\frac{3}{2} + \alpha\right)} e^{-\frac{e^{\alpha t}}{\alpha}} (e^{\alpha t} - 1)^{\frac{1}{2} + \alpha} + e^{-\frac{e^{\alpha t}}{\alpha}} \left(1 - \sum_{i=1}^{2} \left(\chi_1 + \frac{1}{2}\right) e^{-\frac{(\chi_1)}{r+1}} \right) e^{(\alpha t)} - 1)^{\frac{1}{2} + \alpha} \]

where

\[ \Omega = \sum_{i=1}^{2} \left(\chi_1 + \frac{1}{2}\right) e^{-\frac{e^{\alpha t}}{\alpha}} + \sum_{r=1}^{2} \left(\chi_1 + \frac{1}{2}\right) \frac{\Gamma\left(\frac{3}{2} + \alpha\right)}{\Gamma\left(\frac{3}{2} + \alpha + \frac{r}{r+1}\right)} e^{-\frac{(\sin(t))}{r+1} + \frac{(\sin(t))}{r+1} + \frac{(\sin(t))}{r+1}} \]
(IV) If \( \psi(t) = \frac{\ln(1+t)}{\alpha} \) then the solution of linear Caputo-PFIDE with MNCs (5.2) is given as

\[
u(t) = \frac{\Gamma\left(\frac{3}{2}\right)}{\left(\frac{3}{2}\right)^2 \Gamma\left(\frac{3}{2} + \alpha\right)} e^{-\frac{1}{2\alpha} \ln(1+t)} \left(\frac{\ln(1+t)}{\alpha}\right)^{1/2 + \alpha}
\]

\[+ e^{-\frac{1}{2\alpha} \ln(1+t)} \left(1 - \sum_{i=1}^{2} \left(\frac{i}{2} + \frac{1}{2}\right) e^{-\frac{1}{2\alpha} \ln(1+\frac{2i+1}{5})} \left(\frac{1}{\alpha} \ln(1 + \frac{2i + 1}{5})\right)^{1/2}\right)
\]

\[- \sum_{j=1}^{3} \left(\frac{2j - 1}{5}\right) e^{-\frac{1}{2\alpha} \ln\left(1 + \frac{2j+1}{5}\right)} \left(\frac{1}{\alpha} \ln(1 + \frac{j}{4})\right)^{1/2 + \alpha - \frac{2j-1}{20}}
\]

\[- \sum_{r=1}^{2} \left(\frac{r}{3}\right) e^{-\frac{1}{2\alpha} \ln\left(1 + \frac{r+1}{4}\right)} \left(\frac{1}{\alpha} \ln\left(1 + \frac{r + 1}{4}\right)\right)^{1/2 + \alpha + \frac{r}{\alpha}}\right).
\]

where

\[
\Omega = \sum_{i=1}^{2} \left(\frac{i}{2} + \frac{1}{2}\right) e^{-\frac{1}{2\alpha} \ln(1+t)} + \sum_{r=1}^{2} \left(\frac{r}{3}\right) e^{-\frac{1}{2\alpha} \ln\left(1 + \frac{r+1}{4}\right)} \left(\frac{1}{\alpha} \ln\left(1 + \frac{r + 1}{4}\right)\right)^{1/2 + \alpha + \frac{r}{\alpha}}\right).
\]

Graph representing the solution of the problem (5.2) with various values \( \alpha \) via many the functions \( \psi(t) = t^\alpha \), \( \psi(t) = \sin t^\alpha \), \( \psi(t) = e^t^\alpha \) and \( \psi(t) = \frac{\ln(1+t)}{\alpha} \) is shown as in Figures 1–4 by using Python.

**Figure 1.** The graphical of \( \nu(t) \) under \( \psi(t) = t^\alpha \).

**Figure 2.** The graphical of \( \nu(t) \) under \( \psi(t) = \sin t^\alpha \).
6. Conclusions

The qualitative analysis is accomplished in this work. The authors proved the existence, uniqueness and stability of solutions for Caputo-PFIDE with MNCs which consist of multi-point and fractional multi-order boundary conditions. Some famous theorems are employed to obtain the main results such as the Banach’s FPT is the important theorem to prove the uniqueness of the solution, while Leray-Schauder’s nonlinear alternative and Krasnoselskii’s FPT are used to investigate the existence results. Furthermore, we established the various kinds of Ulam’s stability like $HU$, $GHU$, $HUR$ and $GHUR$ stables. Finally, by using Python, numerical instances allowed to guarantee the accuracy of the theoretical results.

This research would be a great work to enrich the qualitative theory literature on the problem of nonlinear fractional mixed nonlocal conditions involving a particular function. For the future works, we shall focus on studying the different types of existence results and stability analysis for impulsive fractional boundary value problems.

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Conflict of interest

On behalf of all authors, the corresponding author states that there is no conflict of interest.

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