Modelling hydrometeorological extremes associated to the moisture transport driven by the Great Plains low-level jet

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Abstract
The Great Plains Low-Level Jet (GPLLJ) system consists of very strong winds in the lower troposphere that transport a huge amount of moisture from the Gulf of Mexico to the American Great Plains. This paper aims to study the extremes of the Transported Moisture (TM) from the GPLLJ source region to the jet domain; and, for low and high TM, to analyze the extremal dependence between the upper tail of the precipitation in the GPLLJ sink region and the lower tail of the tropospheric stability in that region, which is known as tropospheric instability. The declustered extremes of TM were analyzed using Peaks Over Threshold (POT). A non-stationary Exponential model was fitted to the cluster maxima. Estimated return levels show that the extremes of TM are expected to decrease in the future. This is meteorologically congruent with the known displacement of the western edge of the North Atlantic Subtropical High, which controls atmospheric circulation in the North Atlantic, and to a higher scale with the change of phase from negative to positive of the Atlantic Multidecadal Oscillation. Bilogistic and Logistic models were fitted to the extremes of (tropospheric instability, precipitation) for low and high TM, respectively. The extremal dependence between tropospheric instability and precipitation proves to be stronger in the case of high TM. This confirms that dynamical instability is the most important parameter for achieving high values of precipitation once there is a mechanism that allows the continuous supply of large amounts of moisture, such as the derived from a low-level jet system.

Keywords Moisture transport · Great Plains low-level jet · Extreme value analysis · Peaks over threshold methodology · Bivariate threshold excess models

1 Introduction
The World Climate Research Programme (WCRP), which is the United Nations programme defining climate research priorities, identifies Weather and Climate extremes as one of the big challenges: it has been included as an independent chapter in all Intergovernmental Panel on Climate Change (IPCC) reports [e.g. Field et al. (2012), Qin et al. (2014), Masson-Delmotte et al. (2018)]. Within the study of these extremes, the analysis of combined events, defined as “the combination of multiple climate drivers that contributes to societal or environmental risk”, has gained great importance, being multiple the publications devoted to them in high-impact journals due to their enormous socioeconomic importance [e.g. Raymond et al. (2020), Ridder et al. (2020), Zscheischler et al. (2020)]. Initially focused on the analysis of the simultaneous or consecutive occurrence of local phenomena, such as droughts and heat waves, the studies involving precipitation as one of the variables have been abundant. However, studies trying to link precipitation extremes to large-scale atmospheric circulation patterns have been much less frequent and, to the best of our knowledge, the role of the large-scale moisture transport has never been considered from this perspective.
Moisture transport from oceans to continents is the primary component of the atmospheric branch of the water
cycle and forms the link between evaporation from the ocean and precipitation over the continents (Gimeno et al. 2012). There has been an important number of studies on the role of anomalies in the transport of moisture during natural hydrometeorological hazards, extreme drought [e.g., Drumond et al. (2019)] or intense precipitation [e.g. Stohl and James (2004)]. The close relation between moisture transport and extreme precipitation events is more evident when it is studied in the areas of influence of the two major global mechanisms of atmospheric moisture transport, namely Low-Level Jet (LLJ) systems and Atmospheric Rivers (ARs), two large-scale dynamical/meteorological structures, the former being key in tropical and subtropical regions and the latter in extratropical regions (Gimeno et al. 2016).

A LLJ is a system of very strong winds in the lower troposphere, typically in the first 1000 meters height (Stensrud 1996). As water vapour is mainly confined in the lower troposphere, LLJs are major mechanisms of moisture transport at planetary scale. When LLJs are active, they transport a huge amount of moisture favoring high precipitation in the downwind regions. In contrast, in periods when LLJs are absent, downwind regions can suffer from drought events (Gimeno et al. 2016). Within these systems, the GPLLJ is the most studied one because of its socio-economic effects. It transports a huge amount of moisture from the Gulf of Mexico to the American Great Plains and it is mainly active in the summer (Burrows et al. 2019). Broadly speaking, the GPLLJ carries one-third of all water vapour entering continental United States (Helfand and Schubert 1995), and it is associated with 10 % - 45 % of the summer precipitation of the American Great Plains region (Hodges and Pu 2019). In Fig. 1 it is possible to see the climatology of the Great Plains Low-Level Jet system for the months of June, July and August.

The economic importance of the GPLLJ is enormous in the sense that it determines the average and extreme precipitation of a large agricultural region, whose production depends on precipitation, occurring large losses from floods and droughts (Basara et al. 2013). The GPLLJ affects precipitation by increasing its frequency, modifying its spatial distribution and increasing its intensity (Pitchford and London 1962; Mo et al. 1995; Walters and Winkler 2001; Schumacher and Johnson 2009; Squitieri and Gallus 2016; Squitieri and Gallus Jr 2016). The underlying mechanism to the relationship between the GPLLJ and the precipitation is a strong moisture and heat transport at low levels from the Gulf of Mexico. Moreover, wind convergence at low levels implies atmospheric instability in the output area of the GPLLJ, favoring upward movement. Therefore, it is evident that transported moisture and atmospheric instability are two factors that play an important role in precipitation.

There is great interest in studying the extremal behaviour of moisture transport because of the relationship that those extreme events have with flooding. For example, Reid et al. (2021) showed that in March 2021 in some regions of Australia there were vast floods that were associated with extreme values of moisture transport (in that study moisture transport was quantified as integrated water vapor transport, i.e. IVT). In that work, Extreme Value Theory (EVT), by means of the Generalized Extreme Value (GEV) distribution, to be defined in Sect. 3, was applied in order to see how frequent events similar to that of March 2021 are expected to occur in the future. Su and Smith (2021) also made use of the GEV distribution to model the annual maxima of IVT in the contiguous US. Whan et al. (2020) use the GEV as well with the aim of studying the relationship between extreme values of precipitation and covariates such as Atmospheric River (AR) intensity in Norway, where ARs are the key mechanism of moisture transport.

This paper has two main purposes motivated by the dynamics of the complex climatological system extensively described above. The first one is the analysis of TM from an extremal point of view. A univariate Peaks Over Threshold analysis, which is one of the most widely used methods for modelling extremes, is carried out for modelling TM. The non-stationarity of the extreme
observations of TM is also accounted for in this study. The
second one is to perform a bivariate extreme value analysis
with the aim of assessing the relation between the maxi-
mum values of precipitation and the minimum observations
of “omega” (troposferic stability in the GPLLJ sink area),
when TM is low (25% of the lowest values) and for values
of high TM (25% of the highest values). The EVT provides
the proper tools to do this type of analysis. For extensive
details, both theoretical and from a practical perspective,
see e.g. Gumbel (1958), Kotz and Nadarajah (2000), Coles
(2001), Beirlant et al. (2004), de Haan and Ferreira (2006)
and Embrechts et al. (2013).

The structure of the paper is as follows. The data is
carefully introduced in Sect. 2. Section 3 provides a com-
prehensive description of the statistical methods that were
used. Sections 4 and 5 contain the univariate extremal
study of TM and the extreme bivariate analysis of precip-
itation and “-omega” (the negative sign enables the
transformation of a sample of minima into a sample of
maxima). Finally, the results are discussed in Sect. 6.
Future work is also presented in this section.

2 Data

In a recent paper (Algarra et al. 2019), a state-of-the-art
Lagrangian approach is used in order to identify the main
moisture sources and sinks associated to the GPLLJ
(Fig. 2).

The area inside the red curve is the jet domain, that is, it
is the region with the highest occurrence of LLJs during the
period May-October, being the cross the geographical point
at which they occur most frequently (36°N, 101°W, 500m
height); the area in blue identifies the major oceanic source
region for the moisture reaching the jet domain; and the
area in green corresponds to the main sink of that moisture,
one it has been transported by the jet. So, there are two
regions of interest in our analysis: the moisture source and
sink regions, connected by the GPLLJ structure in a tem-
poral domain of several days from the evaporation in the
source to the precipitation in the sink.

Therefore, the series to analyze, based on the sources
and sink areas of moisture linked to the GPLLJ, are:

1. Transported Moisture (TM) from the GPLLJ source
region to the jet domain (mm/day), as calculated in
Algarra et al. (2019). In this study, a Lagrangian
approach was used to track air parcels reaching the jet
domain from the source region. The TM is then
computed by adding the moisture gains of the parcels
in the source region before arriving at the jet domain.

2. Precipitation in the GPLLJ sink region (mm/day):
daily series of precipitation integrated in the whole
moisture sink region of the GPLLJ taken from the
Climate Prediction Center (CPC) dataset (Xie et al.
2010), which is a state-of-the-art precipitation dataset
(see Sun et al. (2018) for a review on gridded
precipitation data).

3. Tropospheric Stability in the GPLLJ sink region
(omega, measured in Pa/s): daily series of vertical
velocity computed as the mean of omega at 850 hPa in
the sink region, taken from the reanalysis ERA-5
(Hersbach et al. 2020). Omega is defined as the vertical
component of velocity in pressure coordinates (these
three-dimensional coordinates are defined by replacing
the usual z-coordinate by atmospheric pressure p). This
is, \( \omega := \frac{dp}{dt} \), which means that if omega (\( \omega \)) is positive
there is a descending movement in the air column
(atmospheric stability) and, if negative, there is an
ascending movement (atmospheric instability). It is
important to recall that pressure (p) and height (z) are
closely related by the hydrostatic equation \( \frac{dp}{dz} = -\rho g \),
being \( \rho \) the air density and \( g \) the acceleration of
gravity. In the current analysis “-omega” is considered
at 850 hPa from the ERA5 reanalysis, which involves
three aspects:

(i) “-omega” is a metric of air ascent (the
overwhelming great majority of precipitation
occurs when air is forced to ascend).

(ii) at 850 hPa: This level (about 1500 m height)
is considered for “-omega” as it represents the
vertical movement at the lower troposphere,
where the GPLLJ occurs and most of the
moisture is confined.
Extended summer maxima of independent and identically distributed random variables is known as the GEV and is defined as:

\[
g(x, \xi, \sigma) = \left\{ \begin{array}{ll}
\exp\left(-\exp\left[-\frac{(1 + \xi \frac{y - \mu}{\sigma})^{1/\xi}}{\sigma}ight]\right), & \text{if } \xi \neq 0 \\
\exp\left(-\frac{y - \mu}{\sigma}\right), & \text{if } \xi = 0
\end{array} \right.
\]

where \(\mu, \sigma > 0\) and \(\xi \in \mathbb{R}\) are the location, scale and shape parameters of the GEV, respectively. The GEV distribution is the limiting form of the GEV as \(\xi \to 0\).

The GEV and the Annual Maxima method: The classical way of modelling observations in an extreme value context is to consider the Annual Maxima method. It consists on dividing the sample in blocks of equal size and then on selecting the maximum value of each block. As the name of the method leads to think, the traditional blocking period is the year, although other time periods may be considered instead. In this framework, the sample of maxima follows a GEV distribution as the sample size increases. This method is still widely used in various areas in spite of its drawbacks. One of the problems with this method is that, in many real situations, there is not a natural time structure in the phenomena to be analyzed. Additionally, the fact that only one observation is considered in each block generally leads to a waste of valuable information. The usual alternative is to consider the POT, which is closely connected to the GPD.

The GPD and the POT approach: The POT consists on fitting an asymptotic model to the excesses (or to the exceedances) above a sufficiently high threshold \(u\). Let \(X_1, X_2, \ldots\) be a sequence of independent random variables with distribution function \(F\) and \((X_{1,n}, X_{2,n}, \ldots, X_{n,n})\) the corresponding ascending ordered sample. If sequences of real numbers \(\{a_n > 0\}\) and \(\{b_n\}\), known as the norming constants, exist for all \(n \in \mathbb{N}\) such that

\[
\lim_{n \to \infty} P\left(\frac{X_{n,n} - b_n}{a_n} \leq x\right) = \lim_{n \to \infty} F^n(a_n x + b_n) = G(x)
\]

for all values of \(x\) for which \(G\) is a continuous function, \(F\) is said to be in the max-domain of attraction of the distribution function \(G\), \(F \in D(G)\). The distribution function \(G\) is known as the GEV and is defined as:

\[
G(y | \mu, \sigma) = \left\{ \begin{array}{ll}
\exp\left(-\exp\left[-\frac{(1 + \xi \frac{y - \mu}{\sigma})^{1/\xi}}{\sigma}\right]\right), & \text{if } \xi \neq 0 \\
\exp\left(-\frac{y - \mu}{\sigma}\right), & \text{if } \xi = 0
\end{array} \right.
\]

where \(\xi \geq 0\) is the shape parameter, \(\mu, \sigma > 0\) are the location and scale parameters, respectively.
where \( y \) is a value of the random variable \( Y \). If \( \xi \geq 0 \), \( y \in (0, \infty) \) and if \( \xi < 0 \), \( y \in (0, -\sigma_u/\xi) \). The scale and shape parameters satisfy, respectively, \( \sigma_u > 0 \) and \( -\infty < \xi < \infty \); \( \sigma_u \) is used to indicate that the scale parameter depends on the threshold \( u \). It is important to stress the fact that the Exponential distribution is the limiting form of the GPD when \( \xi \to 0 \), likewise the Gumbel is for the GEV.

When compared to the Annual Maxima method, the POT has the benefit of avoiding waste of information because all the observations that exceed a sufficiently high \( u \) may be considered. However, in applications, the seek of a “sufficiently“ high threshold is generally a very difficult task. The threshold cannot be too low because that will increase the bias of the GPD parameter estimators and will also endanger the independence assumption of the sample of excesses. On the other hand, if \( u \) is too high then the sample of excesses will have a reduced size and that will increase the variance of the parameter estimators. Therefore, achieving a balance between bias and variance is frequently a challenging task.

In the research presented in this paper, POT was definitely the best option in order to fully use the data.

### 3.1.1 Parameter estimation

There are several methods to estimate the parameters of the GPD although most commonly the selected method is maximum likelihood (ML). See e.g. de Zee Bermudez and Kotz (2010a), de Zee Bermudez and Kotz (2010b) and Mackay et al. (2011) for a review of GPD parameter estimation methods. It is possible to estimate interesting quantities using the estimates of the parameters of the GPD, such as tail probabilies and extremal quantiles.

### 3.1.2 Threshold Selection and Model Assessment

A very important question in the POT approach is how to choose the threshold \( u \). The problem is in selecting a value that allows a trade-off between the large variance of the estimators that occurs for too high values of \( u \) and the large bias that occurs for too low values of this threshold. Methods such as the Mean Excess Function, MEF [see Davison and Smith (1990)] and the stability of the parameter estimates are commonly used to determine an adequate threshold. Once the threshold is selected, attention focuses on assessing the fit of the model. For doing so, two goodness-of-fit tests for the GPD are commonly used: the Cramér-von Mises (CvM) and the Anderson-Darling (AD) tests (see Choulakian and Stephens (2001)). The Likelihood Ratio Test (LRT) is also used to assess if the GPD model can be reduced to the Exponential distribution (see Coles (2001)). In this situation, the fit to the Exponential distribution is usually assessed by the Lilliefors-corrected Kolmogorov-Smirnov (LcKS) test (see Lilliefors (1969)).

### 3.1.3 Dealing with non-stationarity: a brief mention

Non-stationarity is frequently observed when modelling environmental processes. It has to do with the fact that the probabilistic characteristics of the process under study change as time goes by. In the extremes framework, and irrespectively of the method being used, the Annual Maxima or the POT, the maximum values or the excesses above the threshold, respectively, tend to increase (or to decrease) throughout time. The usual way to deal with these changes is to incorporate them in the model parameters. This non-stationarity may just be a linear trend in the location parameter of the GEV or an exponential behavior in the scale parameter of the GPD. In the case of the GPD we might consider that the scale parameter of the GPD varies with time as \( \log(\sigma_t) = \phi_0 + \phi_1 t \). This transformation on the scale parameter of the GPD was used in the univariate data analysis that will be presented in Sect. 4. See for example Coles (2001) for further details about non-stationarity.

### 3.1.4 Analyzing dependent sequences

So far, we have assumed that the excesses above a sufficiently high threshold \( u \) are independent and identically distributed. However, this assumption is often unrealistic when working with time series, as there is usually, at least, short-term temporal dependence that may affect our analysis. The most popular way of addressing this issue is to carry out a declustering process. The “runs-declustering“, which is explained in Coles (2001), consists on fitting a GPD model to the sample of the maxima of each cluster of excesses, where clusters are defined as follows: exceedances (observations above \( u \)) separated by less than \( r \) non-exceedances are included in the same cluster. The quantity \( r \) is commonly referred to as run length.

In applications, it is most important to estimate, for a high number \( m \), the \( m \)-observation return level \( (x_m) \), which satisfies \( P(X > x_m) = p \), where \( p = \frac{1}{m} \). That is, \( x_m \) is exceeded once in every \( m \) observations. It can be estimated as follows:
\[ \hat{\lambda}_m = \begin{cases} u + \frac{\hat{\sigma}}{\xi} \left( \frac{N_u}{n} \hat{\theta} \right)^{\frac{\xi}{\xi - 1}}, & \xi \neq 0, \\ u + \hat{\sigma} \log \left( \frac{N_u}{n} \hat{\theta} \right), & \xi = 0, \end{cases} \]  

where \( \hat{\sigma} \) and \( \hat{\xi} \) are the estimates of the parameters of the GPD model fitted to the cluster maxima, \( N_u \) is the number of exceedances above the threshold \( u \), \( n \) is the total number of observations of the series and \( \hat{\theta} = \frac{N_{t}}{N_{c}} \) is the estimate of the extremal index, with \( N_{c} \) being the number of clusters of exceedances.

### 3.2 Bivariate threshold excess models

#### 3.2.1 Parametric models

Let \( F \) be the joint distribution function of \((X_1, X_2)\). It may be approximated by a parametric model \( G \) within the region \( x_1 > u_1, \ x_2 > u_2 \). Some parametric bivariate models are the Logistic model (Gumbel 1960), the Asymmetric Logistic Model (Tawn 1998), the Hüsler-Reiss Model (Hüsler and Reiss 1989), the Negative Logistic Model (Joe 1990), the Asymmetric Negative Logistic Model (Joe 1990), the Bilogistic Model (Smith 1990), the Negative Bilogistic Model (Coles and Tawn 1994) and the Coles-Tawn Model (Coles and Tawn 1991).

Let \( \hat{\varphi}_1 = 1/\hat{\xi}_1 \) with \( \hat{x}_1 \) and \( \hat{x}_2 \) being standard Fréchet-transformed values of \( x_1 \) and \( x_2 \), respectively. Then, for \( x_1 > u_1 \) and \( x_2 > u_2 \), \( F(x_1, x_2) \) may be approximated, for example, by:

1. If \( G \) is the **Logistic** model:
   \[ G(x_1, x_2) = \exp \left[ - \left( \frac{1}{\hat{\xi}_1} + \frac{1}{\hat{\xi}_2} \right) \left( \frac{1}{\hat{x}_1} + \frac{1}{\hat{x}_2} \right)^{\hat{\xi}_1} \right], \text{ where } 0 < \hat{\xi} \leq 1. \]

2. If \( G \) is the **Bilogistic** model:
   \[ G(x_1, x_2) = \exp \left[ - \hat{\varphi}_1 q^{1-\hat{\varphi}_1} - \hat{\varphi}_2 (1 - q)^{1-\hat{\varphi}_2} \right], \text{ where } q = \frac{q(\hat{\varphi}_1)}{q(\hat{\varphi}_1)} \text{ is the root of the equation } (1 - \hat{\varphi}_1)\hat{\varphi}_1(1-q) - (1-\hat{\varphi}_2)\hat{\varphi}_2 q = 0. \text{ The two parameters } (\hat{\varphi}_1 \text{ and } \hat{\varphi}_2) \text{ lie in } (0, 1). \]

(see, e.g., Beirlant et al. (2004) and Coles (2001) for further details about bivariate models).

#### 3.2.2 Pickands dependence function and extremal coefficients

It is possible to express a parametric model \( G \) as follows:

\[ G(x_1, x_2) = \exp \left\{ - \left( \frac{1}{x_1} + \frac{1}{x_2} \right) A \left( \frac{x_1}{x_1 + x_2} \right) \right\}, \]

where the function \( A(.) \) is called **Pickands dependence function**. \( A(.) \) is a convex function defined on \([0, 1]\) with \( \max(t, 1 - t) \leq A(t) \leq 1 \) for all \( 0 \leq t \leq 1 \). If \( X_1 \) and \( X_2 \) are perfectly dependent, \( A(t) = \max(t, 1 - t), \forall t \in [0, 1] \); if they are independent, \( A(t) = 1, \forall t \in [0, 1] \).

There are some extremal coefficients that can be calculated using \( A(.) \), such as the hereinafter referred to as Dependence coefficient, defined as \( 2(1 - A(1/2)) \). Independence corresponds to Dependence = 0 and perfect dependence to Dependence = 1: the strength of dependence increases as Dependence increases.

(see, e.g., Beirlant et al. (2004) for extensive information about this topic).

#### 3.2.3 Censored-likelihood method of inference

Let \((x_{11}, x_{12}), \ldots, (x_{n1}, x_{n2})\) be independent realizations of \((X_1, X_2)\). The plane is divided into four regions:

\[ D = (-\infty, u_1) \times (-\infty, u_2) \quad A = [u_1, \infty) \times (-\infty, u_2) \]
\[ B = (-\infty, u_1) \times [u_2, \infty) \quad C = [u_1, \infty) \times [u_2, \infty) \]

The **censored-likelihood function** is defined as

\[ L(\theta; (x_{11}, x_{12}), \ldots, (x_{n1}, x_{n2})) = \prod_{i=1}^{n} \psi(\theta; (x_{i1}, x_{i2})), \]

where \( \theta \) is the parameter vector of the model and

\[ \psi(\theta; (x_{i1}, x_{i2})) = \begin{cases} \frac{\partial^2 F}{\partial x_1 \partial x_2} (x_{i1}, x_{i2}), & (x_{i1}, x_{i2}) \in C, \\ \frac{\partial F}{\partial x_1} (x_{i1}, x_{i2}), & (x_{i1}, x_{i2}) \in A, \\ \frac{\partial F}{\partial x_2} (x_{i1}, x_{i2}), & (x_{i1}, x_{i2}) \in B, \\ F(u_1, u_2), & (x_{i1}, x_{i2}) \in D. \end{cases} \]

Using the likelihood function given in (5), it is possible to obtain maximum likelihood estimates and asymptotic confidence intervals for the parameters of the bivariate threshold excess models.

(see e.g., Coles (2001) for further details about this method of inference).

#### 3.2.4 Asymptotic Independence and Asymptotic Dependence

The bivariate threshold excess models presented in this paper rely on the assumption of asymptotically dependent variables. Considering \( F_1 \) and \( F_2 \) as the marginal distributions of \( X_1 \) and \( X_2 \) respectively, the following coefficient is defined:

\[ \chi := \lim_{u \to 1} P(F_2(X_2) > u \mid F_1(X_1) > u) \]

\( \chi \) takes values between 0 and 1: when \( X_1 \) and \( X_2 \) are asymptotically independent, \( \chi = 0 \); and when they are
asymptotically dependent, 0 < \gamma \leq 1. Regarding asymptotically dependent variables, the extremal dependence is stronger as \gamma increases. The coefficient \gamma defined in (6) may also be obtained as follows:

\[
\gamma = \lim_{u \to 1} \gamma(u) = \lim_{u \to 1} \left[ 2 - \frac{\log P(F_1(X_1) \leq u, F_2(X_2) \leq u)}{\log P(F_1(X_1) \leq u)} \right], \quad 0 < u < 1.
\]

(7)

(see e.g. Coles (2001) for further details about this issue).

### 3.3 General scheme of the analysis

In order to highlight the main steps of the analysis to be presented, schemes of the univariate and bivariate analyses are presented in Figs. 3 and 4, respectively. The “actions” that will be carried out are represented by rectangles and the “objects” by ellipses.

### 4 Univariate analysis of transported moisture

In this section we will address the univariate analysis of the series of TM from the GPLLJ source region to the jet domain. We will firstly present a brief exploratory analysis of the series and, afterwards, the POT analysis with declustering that was carried out.

#### 4.1 A brief exploratory analysis

The series of TM for the summer periods (months of June, July and August) is expressed in mm/day and has 3496 observations (38 summers). The data was daily recorded from 1980 to 2017. The plot of the series as well as the histogram with the kernel density estimate are presented in Fig. 5.

The plot of the series suggests that it is reasonably stationary except for the largest values, for which a declining trend seems to exist. In the left-hand plot of Fig. 6 we compare the values of TM which were observed in the first 19 years with the ones recorded during the latest 19 years; in the right-hand plot of that figure we analyze the TM’s yearly evolution. The most relevant aspect which can be observed in these figures is that the magnitude of the large values clearly decreases as time goes by.

#### 4.2 Threshold models approach

We model the data by the POT methodology due to its advantages when compared to the traditional Annual Maxima method. We used a declustering scheme for the exceedances over the chosen threshold in order to deal with the short-term temporal dependence existing between them. First, we will present the threshold selection procedure and, afterwards, the POT analysis with four different run lengths.

##### 4.2.1 Threshold selection

The two methods presented in Sect. 3.1 were applied to the series under study.

The estimated MEF presented in Fig. 7 leads to think that a value around 2 might be an appropriate threshold, as a linearity pattern is clearly visible to the right of that value. The ML estimates for the shape parameter, plotted in Fig. 7, are approximately constant above \( u = 2 \), which supports that \( u = 2 \) might be a reasonable choice. For that
choice of $u$, the number of exceedances is $N_u = 201$ (5.75% largest observations of TM).

4.2.2 POT analysis with declustering

For correct application of the POT approach, it is necessary to verify if there is some evidence of excess clustering. The exceedances above the threshold $u = 2$ are plotted in Fig. 8 (left). There is some visual evidence that there might be some temporal dependence between the exceedances. Thus, the R package evd is used to perform “runs-declustering” with run length ($r$) equal to 1, 2, 3 and 4. After a thorough analysis of the results obtained for these values of $r$, we came to the conclusion that the latter choice seems to be the best. Fig. 8 (right) shows the cluster maxima for $r = 4$. The corresponding dates can be found in Appendix B.

Table 1 contains the results with regard to the number of clusters obtained ($N_c$), the estimate of the extremal index ($\hat{\theta} = N_c/N_u$) and the ML estimates for the parameters of the GPD ($\hat{\xi}, \hat{\sigma}_{GPD}$) and the Exponential model ($\sigma_{EXP}$), with their corresponding standard errors. In the overall, the results are very much alike and clearly support that the Exponential model seems to be a better alternative than the GPD.

Now the question is if we consider the GPD model or the Exponential for modelling the cluster maxima. The profile log-likelihood 95% confidence interval for $\xi$ is $(-0.178, 0.321)$ and so it is consistent with the hypothesis...
that $\xi = 0$ (Exponential model). The Exponential and the GPD QQ-Plots are presented in Fig. 9. The figure clearly shows that the Exponential and the GPD models are both appropriate for modelling the cluster maxima.

For all values of $r$ considered, the Cramér-von Mises (CvM) and the Anderson-Darling (AD) tests did not reject the null hypothesis that the cluster maxima come from a

| $r$ | $N_c$ | $h$ (Std.Err) | $\theta$ (Std.Err) | $\xi$ (GPD Std.Err) | $\sigma_{GPD}$ (Std.Err) | $\sigma_{EXP}$ (Std.Err) |
|-----|-------|---------------|---------------------|----------------------|---------------------------|---------------------------|
| 1   | 102   | 0.507 (0.052) | 0.052 (0.114)       | 0.367 (0.055)        | 0.387 (0.038)             |                           |
| 2   | 96    | 0.478 (0.114) | 0.052 (0.118)       | 0.373 (0.058)        | 0.393 (0.040)             |                           |
| 3   | 90    | 0.448 (0.118) | 0.022 (0.118)       | 0.401 (0.064)        | 0.410 (0.043)             |                           |
| 4   | 83    | 0.413 (0.123) | 0.022 (0.123)       | 0.408 (0.067)        | 0.418 (0.046)             |                           |
Therefore, we can conclude that the GPD model fits well to the data.

The fact that the GPD model fits the declustered excess data does not necessarily mean that it is better than the Exponential model (limiting case of the GPD when $\xi \to 0$). In order to test $H_0 : \xi = 0$ vs. $H_1 : \xi \neq 0$, a Likelihood Ratio Test (LRT) was performed. It is possible to conclude that the Exponential model is more appropriate to model the cluster maxima of the excesses above $u = 2$, at all the usual significance levels.

The LcKS test did not reject the null hypothesis that the cluster maxima of the excesses above $u = 2$ come from an Exponential distribution. For all values of $r$ analyzed, the conclusion from this LcKS test is that the Exponential model fits well to the data, for the usual levels of significance. See Appendix A for the results of the statistical tests that were carried out.

Hence, we will use the Exponential model for the cluster maxima. As previously said, Fig. 6 seems to indicate a declining trend in the largest values of the series, reflecting non-stationarity as time evolves. In this framework, it is reasonable to allow the scale parameter of the Exponential distribution to vary according time. That corresponds to introduce the year of observation as a covariate. Taking into account that the scale parameter is always positive, the log link function is used. Thus, the expression for the scale parameter of the Exponential model that we fitted is the following:

$$\sigma_t = \exp(\phi_0 + \phi_1 t), \quad (8)$$

where $t = Year - 1979$. The aim of this location modification is to enable time to vary over the 38 summer periods.

The results shown in Table 2 indicate that, as suspected, the ML estimate of the parameter $\phi_1$ is negative for all the values of $r$ considered and decreasing, what means that the estimate of the scale parameter of the Exponential model is lower in more recent years when compared to the initial period. This decrease in the estimate of the scale parameter with time seems to be more important as $r$ increases.

Now the issue lies in assessing if the non-stationary Exponential model is better when compared to the stationary one. As usual in the case of nested models, a LRT can be used: the null hypothesis of that test in this case is $\phi_1 = 0$ (that is, the stationary model is more appropriate) vs. an alternative, $\phi_1 \neq 0$. Table 3 shows that the non-stationarity in the large values of TM starts to become evident for $r = 4$, at level $\alpha = 0.05$.

4.2.3 Estimating return levels

As previously said, return level estimation is one of the main focus of any extreme value analysis. From now on, we will consider the non-stationary Exponential model. For each value of $t \in \{1, 2, \ldots, 38\}$ the corresponding $\hat{\mu}_{cm}(t)$ is obtained by using $\hat{\sigma}_t = \exp(\hat{\phi}_0 + \hat{\phi}_1 t)$ in expression (3) for $\xi = 0$. We will just show the plot corresponding to $r = 4$ (see Fig. 10). The figure reveals that, in summer 1980 the estimated $m$-observation return levels are higher than the ones observed in summer 2017, for $m = 92 \times 38$, $m = 92 \times 50$ and $m = 92 \times 100$ (there are 92 observations per year in the TM series, corresponding to the daily observations of June, July and August). It is also interesting to highlight that the differences between the estimated return levels become smaller over time. We extracted from

![Fig. 9 Exponential and GPD QQ-Plots for the cluster maxima of excesses of the TM series, for $u = 2$ and $r = 4$](image)
Fig. 10 the values of the estimated return levels in the first and last summers of that series (see Table 4).

It is possible to see in Table 4 that the ratio between the estimated 38-year return level for the last summer of the TM series and the first summer of that series is approximately equal to 0.712 (representing a decrease of approximately 28\% in the estimated 38-year return level from the beginning to the end of the series). In the case of the 50-year return level, the ratio mentioned before is approximately equal to 0.705 (decrease of approximately 29\% in the estimated 50-year return level); and in the case of the 100-year return level, the ratio equals approximately 0.688 (decrease of approximately 31\% in the estimated 100-year return level). Thus, as it is obvious, the interpretation of the results of this table is in line with the interpretation of Fig. 10. Moreover, the other comment we made on that figure can also be checked in Table 4, since the difference between the estimated 100-year return level and the 38-year return level is approximately 0.554 for the first summer of the TM series and approximately 0.269 for the last summer of that series. That is, over the period under study, the difference between those estimated return levels has approximately decreased 51.4\% of the value corresponding to the first summer.

From these results, and provided the atmospheric conditions evolve in the current manner, it is possible to say that we expect to observe a persistent decrease in the extreme values of TM as time goes by (see Fig. 10).

The univariate modelling was performed by means of the R packages evd (Stephenson 2002) and extRemes (Gilleland and Katz 2016). The code used for the computations is available from the authors upon request.

### 4.3 Meteorological implications

For the meteorological interpretation of the analysis of TM, we consider as days with extreme TM those days corresponding to the cluster maxima of excesses of TM for \( r = 4 \) (see Appendix B). In order to explain the meaning of our results in meteorological terms, Fig. 11 displays the anomalies of the 500 hPa geopotential, moisture fluxes, and precipitation for all days when TM was extreme (panel a)), for extreme days in the first half of the study period 1980-2017 (panel b)), and for extreme days in the second half (panel c)). A geopotential tripole with positive anomalies on the central and eastern continent and negative ones on both sides of the Atlantic Ocean and the Pacific coasts favours atmospheric circulation from the Caribbean Sea and the Mexican Gulf to the Great Plains, and consequently also implies high values of TM and precipitation in our region of interest. This tripole is intensified for the first half of our study period and weakens in the second half, indicating that very high TM is more difficult to observe in the first two decades of the XXI century than it was in the last two decades of the XX century. This accords with a displacement of the western edge of the North Atlantic Subtropical High (NASH), the semi-permanent structure that controls atmospheric circulation in the North Atlantic, which is in turn controlled by the Atlantic Multidecadal

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**Table 2** ML estimates for the parameters of the non-stationary Exponential model fitted to the cluster maxima of excesses of the TM series, choosing \( u = 2 \) and \( r = 1, 2, 3 \) and 4

| \( r \) | \( \hat{\phi}_0 \) (Std.Err) | \( \hat{\phi}_1 \) (Std.Err) |
|-------|-----------------------------|-----------------------------|
| 1     | -0.726 (0.180)              | -0.014 (0.009)              |
| 2     | -0.705 (0.187)              | -0.014 (0.009)              |
| 3     | -0.603 (0.195)              | -0.018 (0.009)              |
| 4     | -0.538 (0.211)              | -0.020 (0.010)              |

**Table 3** Observed value of the LRT statistic and corresponding \( p \)-value, for \( r = 1, 2, 3 \) and 4

| \( H_0 : \phi_1 = 0 \) | \( r = 1 \) | \( r = 2 \) | \( r = 3 \) | \( r = 4 \) |
|------------------------|-------------|-------------|-------------|-------------|
| LRT statistic          | 2.375       | 2.306       | 3.442       | 3.926       |
| \( p \)-value           | 0.123       | 0.129       | 0.064       | 0.048       |
Oscillation (AMO), a dominant mode of climate variability in the North Atlantic Ocean with period of about 60-80 years (Trenberth et al. 2021). When the AMO is positive, the NASH is weak, low-level TM from the Caribbean to central and SE North America is reduced, and precipitation on the Great Plains is also reduced (Seager et al. 2014). This is exactly what happened in our period of interest, in which the AMO changed its phase from negative to positive in the mid-nineties (see key figures in Trenberth et al. (2021)), with a continuous increase in the AMO index.

This conceptual meteorological scheme is in complete agreement with our results in Fig. 10, which shows a decrease in the estimated 38-year, 50-year and 100-year return levels for the TM series over the study period.

### Table 4

|                  | 38-year return level | 50-year return level | 100-year return level |
|------------------|----------------------|----------------------|-----------------------|
| Summer 1980      | 4.531                | 4.688                | 5.085                 |
| Summer 2017      | 3.228                | 3.304                | 3.497                 |

Fig. 11 Anomalies of precipitation (in colors, mm/day). The vectors represent the anomalies of IVT (Integrated Vapor Transport, Kg m^{-1} s^{-1}); the orange lines show the 500 hPa geopotential field together with their anomalies (black lines). The green cross indicates the point of maximum GPLJJ intensity and green contour refers to the 75th percentile of the GPLJJ index value. Panel a: days with extreme TM in the period 1980-2017; panels b and c: days with extreme TM corresponding to the periods 1980-1998 and 1999-2017, respectively.
**5 Bivariate analysis of Precipitation and tropospheric instability**

In Sect. 1, we introduced the series of precipitation (measured in mm/day) in the GPLLJ sink region and the series of tropospheric stability in that region (omega, measured in Pa/s). As it was already referred, these series consist of 3496 observations, corresponding to the daily observations of the summer months (June, July and August) of the period 1980-2017. Now, interest focuses on studying the extremal dependence between precipitation and “-omega” (the sign of “omega” is reversed because the meteorological interest lies on studying the joint behaviour of the upper tail of precipitation and the lower tail of “omega”). In fact, our study consists in analyzing the bivariate extremes of precipitation and “-omega” for two subsamples of the series: for the days when the TM from the GPLLJ source region to the jet domain is high and when it is low. Thus, one subsample consists of the days with the 25% lowest values of TM, whereas the other one includes the 25% highest values of that variable (consequently, each subsample includes 874 observations). It is important to mention that the TM series was lagged 1 day with respect to the series of precipitation and “-omega”, that is, for example, for an observed pair of (-omega, precipitation) occurring on 2 June 1980, the corresponding value of TM is the one that occurred on 1 June 1980. The reason for doing so is meteorological: precipitation and “-omega” are observed in the GPLLJ sink region, while the TM is computed on its way from the source region to the jet domain. Hence, the moisture arrives at the sink region (approximately) 1 day after it is observed, and that is why the adjustment that we carried out was necessary. For assessing the influence of the time period, other alternatives were considered. As such, we analyzed the scenarios of moisture arrival at the sink region 2, 3 and 4 days after it is observed. In Table 5 the correlations between lagged TM values and tropospheric instability (“-omega”) and lagged TM values and precipitation are presented. The strongest correlations are observed for a lag of 1 day between TM and the other variables. Therefore, it was decided to perform the bivariate analysis of this section using this lag.

### 5.1 Preliminary analysis

The plots of the complete series of tropospheric instability and precipitation can be found in Fig. 12. They clearly show that there is no clear evidence that neither of the variables are non-stationary throughout the period under study. As such, stationarity is assumed along this bivariate analysis.

The data of interest are the observed pairs of (-omega, precipitation) for the days with low TM and for those corresponding to high TM. As we can see in Fig. 13, the boxplots show that there are higher extreme values of “-omega” when the TM is low than when it is high. In contrast, there are higher extreme values of precipitation when the TM is high than when it is low.

### 5.2 Fitting the bivariate threshold excess models

**Univariate threshold models for the margins**

The fitting of the bivariate threshold excess models requires previous fit of GPD models to the excesses over appropriate thresholds for each margin.

We came to the conclusion that \( \mu_1 = 0.03 \) is a suitable threshold for “-omega” and \( \mu_2 = 5.2 \) is an adequate threshold for the precipitation, for both low TM and high TM. We will now present the details of the justification of the thresholds that were chosen.

For selecting the threshold for “-omega”, both for low and high TM, Figs. 19 and 20 (in Appendix C) were used. The estimated mean excess functions for both low TM and high TM are consistent with the choice of \( \mu_1 = 0.03 \) as an appropriate threshold. In fact, a linearity pattern to the right of that value is evident. It is also clear that the ML estimates for the shape parameter are approximately constant above \( \mu_1 = 0.03 \) for both low TM and high TM. Consequently, \( \mu_1 = 0.03 \) seems to be an adequate threshold.

Using the same arguments as in the previous situation, \( \mu_2 = 5.2 \) seems to be a proper threshold for precipitation both for low and high TM (see Figs. 21 and 22, which are in the Appendix C).

The results of the POT analysis can be found in Table 6. As we can see in that table, the ML estimates for the shape parameter of the GPD are all negative and larger than \(-0.5\), which guarantees the asymptotic properties of ML.

| Table 5 | Correlations between lagged TM values and tropospheric instability (“-omega”) and lagged TM values and precipitation |
|---------|----------------------------------------------------------|
| lag=1   | Correlation lagged TM and -omega | Correlation lagged TM and prec. |
| lag=1   | **0.050** | **0.125** |
| lag=2   | 0.022     | 0.099     |
| lag=3   | -0.001    | 0.056     |
| lag=4   | 0.001     | 0.025     |

Bold values indicate the lag that was chosen for the bivariate analysis.
estimation (de Zee Bermudez and Kotz 2010a). Moreover, the GPD model boundary constraints are satisfied ($x_F > x_{n,n}$).

Regarding the profile log-likelihood 95% confidence intervals of $\xi$ for ‘‘-omega’’ and precipitation in the cases of low and high TM, the confidence intervals for $\xi$ for

|                      | -Omega(low TM) | Prec. (low TM) | -Omega(high TM) | Prec. (high TM) |
|----------------------|---------------|---------------|-----------------|-----------------|
| Threshold            | 0.03          | 5.2           | 0.03            | 5.2             |
| Number of excesses   | 170           | 55            | 211             | 98              |
| Percentage of excesses | 19.5 %        | 6.3 %         | 24.1 %          | 11.2 %          |
| $\xi$ (Std.Err)      | -0.180 (0.072) | -0.160 (0.128) | -0.311 (0.059) | -0.163 (0.087) |
| $\sigma$ (Std.Err)   | 0.018 (0.002) | 1.185 (0.219) | 0.017 (0.001)  | 1.676 (0.222)  |
| $\xi_C$              | 0.132         | 12.583        | 0.084           | 15.499          |
| $x_{n,n}$            | 0.098         | 9.134         | 0.077           | 11.609          |
precipitation contain the value 0, which suggests that the limiting GPD model (Exponential) is more appropriate. In contrast, the confidence intervals of \( \xi \) for \(-\omega\) only contain negative values. See Gimeno-Sotelo (2021) for further details.

In what concerns the CvM and AD tests, for \(-\omega\) and precipitation, it is concluded that the GPD model fits well to the data in both cases of low and high TM, for all usual significance levels. The results of the LRT show that for \(-\omega\), both for low and high TM, at the level of significance 0.05, the GPD model is more appropriate than the Exponential one. For precipitation, it is possible to conclude that the Exponential model is more adequate than the GPD one. See Table 12 (in Appendix D) for the results of the application of these statistical tests.

The details of the Exponential models fitted to the excess data of the precipitation are presented in Table 13 (in Appendix D), both for low and high TM. It was concluded that the Exponential model fits well to the excess data above \( u_2 = 5.2 \) in both cases of precipitation with low and high TM. In fact, the null hypothesis of the LeKS test that the excesses come from an Exponential distribution is not rejected at the usual significance levels.

**Bivariate analysis**

The marginal models for the excesses of \(-\omega,\text{precipitation}\) are GPD. In the case of the precipitation, the limiting form of the GPD (Exponential model) was considered for simplicity purposes.

In Fig. 14 the observed points of \(-\omega,\text{precipitation}\) are represented, for high and low TM, along with two lines representing the thresholds \((u_1 = 0.03, u_2 = 5.2)\). This enables the definition of three “extremal” quadrants as follows:

A  
- large values only in \(-\omega\).

B  
- large values only in precipitation.

C  
- large values in both variables.

In the plots we also indicate the number of points belonging to each of the quadrants and the corresponding percentage in terms of the total sample size. It should be mentioned that the largest difference in the percentages is observed in quadrant C (which reflects the situation of extremes in both variables).

As it was said in Sect. 3.2, the bivariate models that will be fitted assume that the variables are asymptotically dependent. In order to check that assumption, chi plots will be used. These plots represent \( u \in (0, 1) \) against empirical estimates of \( \chi(u) \). Fig. 15 presents the chi plots for \(-\omega,\text{precipitation}\) in the cases of low TM and high TM. The dashed lines refer to the approximate 95% confidence intervals. It can be seen that the empirical estimates of \( \chi(u) \) are larger than 0 in both cases for the values of \( u \) close to 1, so it is consistent with \( \chi > 0 \), and consequently with the fact that \(-\omega\) and precipitation are asymptotically dependent in both situations. Therefore, we can assume that the models presented here are appropriate for these variables.

The joint distribution function of \((X_1, X_2) = (-\omega,\text{precipitation})\) in the cases of low TM and high TM can be approximated by one bivariate parametric models within the region C. In order to estimate the parameters of the model, a one-step censored-likelihood method was used. That is, the maximization of the censored-likelihood function, given in (5), enables to obtain simultaneously the ML estimates for the marginal and dependence parameters.

In Table 7 it is possible to see the results that we obtained when fitting several usual parametric bivariate models to the pair \(-\omega,\text{precipitation}\) in the cases of low and high TM.

In Table 7, in each case, the model with the lowest AIC appears in bold: for low TM, the best model is the Bilogistic one (AIC=270.826) and for high TM, the Logistic one (AIC=311.341). It is important to point out that, within each case, the values of AIC are quite similar.

With respect to the coefficient Dependence, defined as \( 2(1 - A(1/2)) \), where \( A(.) \) is the corresponding Pickands dependence function, it can be seen in Table 7 that the value of the Dependence coefficient is larger for high TM than for low TM for all the parametric models considered, which means that the extremal dependence between \(-\omega\) and precipitation is stronger in the case of high TM than when TM is low.

The Bilogistic model proves to be the most adequate to model the joint distribution function of \(-\omega,\text{precipitation}\) within the region C in the case of low TM, whereas the Logistic model is chosen in the case of high TM.

The ML estimates for the marginal and dependence parameters of those models, as well as the corresponding standard errors, can be found in Table 8.

Pickands dependence functions corresponding to the models presented in Table 8 can be found in Fig. 16. In that figure it is possible to see that Pickands dependence function corresponding to the Logistic model for high TM is closer to \( A(t) = \max(t, 1 - t) \), \( t \in [0, 1] \) (the perfect dependence case), which means that the extremal dependence between \(-\omega\) and precipitation is stronger when there is high TM than when the TM is low, as we had concluded before.

The quantile curve of a joint distribution function \( F \) at lower tail probability \( p \) is denoted as \( Q(F, p) \), that is, \( Q(F, p) := \{(x_1, x_2) : F(x_1, x_2) = p\} \). In Fig. 17 the estimates of the quantile curves \( Q(F_j, 0.95), Q(F_j, 0.975) \) and \( Q(F_j, 0.99) \) are plotted for each \( j \in \{1, 2\} \), where \( F_1 \) denotes the joint distribution function of \(-\omega,\text{precipitation}\) in the case of low TM and \( F_2 \) for high TM. In order
to construct those estimated curves, the models presented in Table 8 were used. The dates of the 10 days that exceed the estimate of $Q(F_1, 0.95)$ and of the 13 days that are beyond the estimate of $Q(F_2, 0.95)$ are presented in Table 9. This reflects a stronger extremal dependence when TM is high when compared to low TM. The meteorological analysis of these concurrent extreme days will be presented in the next Subsection.

The $R$ package evd was used (Stephenson 2002) to perform the bivariate analysis of the data. The code developed for performing the computations is available from the authors upon request.

### 5.3 Meteorological implications

According to a simple approximation, values of high precipitation (HP) scale with precipitable water (IWV, the amount of vapour in a vertical sense, which for simplicity we sometimes refer to as moisture) and with a metric of vertical velocity (Emori and Brown 2005)$^2$. In our analysis, we use a measure of vertical velocity in the quantity “- omega” at 850Pa obtained from the ERA5 reanalysis, which represents the vertical velocity due to large-scale motions (synoptic scale, ranging from few hundred to

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$^2$ In this meteorological context, HP refers to precipitation higher than a local percentile, usually 95th.
Table 7 AIC and Dependence coefficient for the parametric models that we fitted to model the joint distribution function of (-omega, precipitation) in the cases of low and high TM within the region C in both cases

| Parametric model          | Low TM       | High TM       |
|---------------------------|--------------|---------------|
|                           | AIC          | Dependence $2(1 - A(1/2))$ | AIC          | Dependence $2(1 - A(1/2))$ |
| Logistic                  | 272.498      | 0.232         | 311.341      | 0.359         |
| Asymmetric logistic       | 273.721      | 0.200         | 331.227      | 0.323         |
| Husler–Reiss              | 271.328      | 0.227         | 311.952      | 0.352         |
| Negative logistic         | 271.351      | 0.229         | 311.366      | 0.357         |
| Asymmetric negative logistic | 273.722      | 0.205         | 315.197      | 0.348         |
| Bilogistic                | **270.826**  | **0.207**     | 319.310      | 0.418         |
| Negative bilogistic       | 271.813      | 0.216         | 313.031      | 0.352         |
| Coles–Tawn                | 271.244      | 0.203         | 312.850      | 0.353         |

Numerical results slightly vary from Gimeno-Sotelo (2021) due to the optimization method chosen to maximize the censored-likelihood for each model

Bold values indicate the fitted model with the lowest AIC in each case

Table 8 ML estimates (standard errors in brackets) for the marginal and dependence parameters of the bilogistic model for (-omega, precipitation) in the case of low TM; and the logistic model for (-omega, precipitation) in the case of high TM

| Bilogistic model (Low TM) | Logistic model (High TM) |
|---------------------------|--------------------------|
| $\hat{\sigma}_1$         | $\hat{\sigma}_1$         | $\hat{\sigma}_2$ |
| 0.018 (0.002)             | -0.154 (0.077)           | 1.025 (0.132) |
| $\hat{\xi}_1$            | $\hat{\xi}_1$           | $\hat{\xi}_2$ |
| -0.016 (0.001)            | -0.264 (0.067)           | 1.498 (0.145) |
| $\hat{\alpha}$           | $\hat{\alpha}$          | $\hat{\beta}$ |
| 0.911 (0.033)             | 0.715 (0.034)            | 0.662 (0.114) |

$\hat{\sigma}_1$ and $\hat{\xi}_1$ - estimates of the scale and shape parameter of the GPD for the excess data (“-omega”)

$\hat{\sigma}_2$ - estimate of the scale parameter of the Exponential (precipitation)

$\hat{\alpha}$ and $\hat{\beta}$ - estimates of the dependence parameters of the Bilogistic model

$\hat{\alpha}$ - estimate of the dependence parameter of the Logistic model

**Fig. 16** Pickands dependence functions corresponding to the fitted Bilogistic model for (-omega, precipitation) in the case of low TM (left); and to the Logistic model for (-omega, precipitation) in the case of high TM (right). The dashed black lines refer to the independence $A(t) = 1, t \in [0, 1]$ and perfect dependence case $A(t) = \max(t, 1-t), t \in [0, 1]$.
several thousand kilometres), derived primarily from dynamically driven instability such as that associated with extratropical fronts and cyclones. At a smaller horizontal scale, some other vertical motions also occur as a result of thermodynamic instability either at the mesoscale (from a few to several hundred kilometres, such as Mesoscale Convective Systems (MCS)), and at the microscale (up to a few kilometres only, such as those seen in isolated, clustered, or embedded MCS storm cells). The quantity \( -\omega \) is not that effective in reproducing vertical motion linked to these phenomena, and performs poorly in the case of tropical cyclones (structures between the mesoscale and synoptic scales).

In their analysis of extreme daily precipitation events, Kunkel et al. (2020) corroborated the results of previous authors who found that although HP events are strongly related to extremes of IWV, they are not related to extremes of \( -\omega \) as much. For higher values of HP, the limiting factor is IWV, not \( -\omega \). This is because for very high IWV, thermodynamic effects play an important role (mesoscale convection, MCS, supercell storms), which is not the case with low IWV, where only large-scale dynamic instability factors (fronts, extra-tropical cyclones... ) are of importance. This implies that: (a) higher values of HP may be achieved with high than with low IWV, b) with low IWV, much higher and more persistent values of dynamic instability (\( -\omega \)) are required than for high IWV, when HP can occur with lower values of \( -\omega \).

Kunkel et al. (2012) showed that for our region of interest (Great Plains) in the summer months, large-scale synoptic systems such as fronts and extratropical cyclones were responsible for the largest number of HP events, accounting for about 80% of events, with 8% related to tropical cyclones and 12% to MCS and other smaller-scale convective phenomena. This implies that dynamical instability (\( -\omega \)) is the most important parameter for achieving high values of precipitation once there is a mechanism that allows the continuous supply of large amounts of moisture (a moisture transport mechanism).

A large amount of TM from the Caribbean source to the region of interest driven by the GPLLJ (large and sustained transported moisture from the source to the sink of the GPLLJ system) results in large values of IWV in the region of interest, which do not occur for low TM. This implies that: a) precipitation has higher values when TM is high than when it is low, due to the higher values of IWV. b) high precipitation events can occur for moderate-to-high values of \( -\omega \) when TM is high, but only for high to very high values of \( -\omega \) when TM is low.

This meteorological rationale is coherent with the results presented in this paper. The analysis of the dependence of the extremes of precipitation and \( -\omega \) for days with TM above the 75th percentile compared with those below the 25th percentile confirms the stronger dependence (a greater probability that an extreme of one variable will be accompanied by an extreme of the other) for high than for low TM. For low TM, an extreme of \( -\omega \) does not guarantee a precipitation extreme because it may be accompanied by low IWV. For low values of IWV, only very extreme values of \( -\omega \) may lead to extreme precipitation.

These results may be better visualized by plotting anomalies of geopotential at 500 hPa, moisture fluxes and precipitation for the days with TM above the 75th percentile (high TM) versus the days with TM below the 25th.
Table 9 Concurrent extreme days of (-omega, precipitation) for low TM (first column) and high TM (second column). They correspond to the dates beyond the estimate of $Q(F_1, 0.95)$ and the dates beyond the estimate of $Q(F_2, 0.95)$, respectively.

| Year-Month-Day | Low TM  | High TM |
|----------------|---------|---------|
| 1983-6-28      | 1980-8-15 |
| 1994-6-8       | 1980-8-16 |
| 1994-6-23      | 1981-7-28 |
| 1995-6-9       | 1987-8-26 |
| 1998-6-8       | 1990-7-12 |
| 1998-6-9       | 1990-7-21 |
| 2004-7-23      | 1993-6-18 |
| 2008-6-5       | 1993-6-30 |
| 2014-6-15      | 1993-7-14 |
| 2015-8-18      | 2004-6-10 |
| 2005-7-26      | 2007-8-19 |
| 2007-8-19      | 2007-8-24 |

percentile (low TM). In panel b) of Fig. 18 the days with high TM are used, and there it can be seen that moisture transport is enhanced when a positive geopotential anomaly is seen over Central and Southeastern North America and a negative one occurs to the West and to the East, which then favours atmospheric circulation from the Caribbean and the Mexican Gulf towards the Great Plains. On the other hand, a positive geopotential anomaly indicates an inhibited vertical movement in this region. The effect of the enhanced moisture transport is greater than the effect of inhibited vertical movement because positive anomalies of precipitation occur over the Great Plains. The opposite pattern is seen when the TM is low (panel a)). This clearly accords with the results discussed above wherein high precipitation is much more sensitive to IWV and vertical movement (“- omega”).

These patterns are slightly different for the concurrent extreme days of “-omega” and precipitation (composites of the same meteorological variables but only for the days included in Table 9). In panel d) of Fig. 18 the concurrent extreme days of (-omega, precipitation) corresponding to high TM are used. In that panel it can be seen that the geopotential anomaly tripole is displaced slightly to the West, but this still permits strong atmospheric circulation from the Caribbean (strong moisture transport) whilst favouring vertical movement over the Great Plains (negative anomalies of geopotential). This combination of strong moisture transport and moderate vertical movement (but extreme when compared with all the days with high TM) results in stronger precipitation over the Great Plains than on all the days when there is high TM. In contrast, the concurrent extreme days of (-omega, precipitation) with low TM are used in panel c). There it is possible to visualize that the negative geopotential anomalies in Central and Southeastern North America are intensified, suggesting a stronger vertical movement displaced slightly to the West, permitting greater moisture transport from the Caribbean, although this is outside (to the East) of the GPLLJ box used in this study (TM as defined in our study thus continues to be low). This combination of greater vertical movement with some moisture transport also results in heavier precipitation over the Great Plains than for all the days when TM is low.

6 Conclusions and future work

The scenario of this paper is set on the Great Plains Low-Level Jet (GPLLJ) system, which is a system of very strong winds in the lower troposphere that transports a huge amount of moisture from the Gulf of Mexico to the American Great Plains and is mainly active during the summer months.

This work aimed to analyze the extremal behaviour of the TM from the GPLLJ source region to the jet domain; and, in the cases of low and high TM, to study the extremal dependence between the upper tail of the precipitation in the GPLLJ sink region and the lower tail of the tropospheric stability in the GPLLJ sink region (omega). For this purpose, we used the series of daily observations of TM, precipitation and “omega” of all June-July-August periods from 1980 to 2017, which amounts to 3496 observations.

In terms of the univariate analysis of TM, we used the POT methodology. The “runs-declustering” was used in order to reduce the temporal dependence between the exceedances. The declustering process was performed for several values of run length ($r$), namely 1, 2, 3 and 4. We came to the conclusion that the Exponential model was more appropriate than the GPD to model the cluster maximum of excesses over the chosen threshold. Moreover, we concluded that in the case of $r = 4$, the non-stationary model was more adequate than the stationary one. The non-stationarity over time starts to be evident for $r$ equal to 4, reflected by a declining scale parameter. The estimated 38-year, 50-year and 100-year return levels for the TM series also decreased over time and, additionally, the difference between them became smaller. It is important to recall that a “t-year” return level corresponds to a value which will be exceeded once in “t-summer” periods to come. Therefore, it is possible to say that we expect to observe lower extreme values of TM in the future.

This result is in meteorological agreement with some of the observed changes in the North Atlantic atmospheric circulation and in the climate variability mode that controls the decadal scale, the Atlantic Multidecadal Oscillation (AMO). The change of phase of AMO from negative to positive in the mid-nineties and the continuous increase in the AMO index up to the end of the studied period result in
a displacement of the western edge of the North Atlantic Subtropical High and reduced low-level moisture transport from the Caribbean to central and SE North America.

Moreover, we analyzed the bivariate extremes of \((-\omega, \text{precipitation})\) in the cases of low and high TM. The sign of \(\omega\) was changed because, meteorologically speaking, the interest lied on the study of the joint behaviour of the upper tail of precipitation and the lower tail of \(\omega\). The series of precipitation and \(-\omega\) were lagged 1 day with respect to the TM series due to the temporal nature of the GPLLJ system. The fit of bivariate threshold excess models requires previous fit of univariate threshold models to the margins. Two GPD models were fitted to the margins. In the case of precipitation, the shape parameter of the fitted GPD was very close to zero. Considering that the Exponential distribution results as the limiting case of the GPD when \(\xi\) tends to zero, the GPD was reduced to its limiting form. The censored-likelihood method was used for fitting several different parametric models. The most parsimonious models were the Bilogistic and the Logistic, for low and high TM, respectively. The extremal dependence between \(-\omega\) and precipitation proved to be stronger in the case of high TM than when TM is low. This conclusion can be visualized by means of the estimated Pickands dependence functions. Additionally, the chi plots allowed us to conclude that it is reasonable to assume that the variables are asymptotically dependent, in both the cases of low and high TM.

The results of the bivariate analysis have two important meteorological implications. Firstly, they confirm that dynamical instability, as quantified by \(-\omega\), is the most important parameter for achieving high values of precipitation once there is a moisture transport mechanism such as a low-level jet system, which continuously supply large amounts of moisture. Secondly, they confirm that moderate-to-high values of dynamical instability are necessary to generate high precipitation when TM is high, but high to very high values are required when TM is low.

Fig. 18 Anomalies of precipitation (in colors, mm/day). The vectors represent the anomalies of IVT (Integrated Vapor Transport, Kg m\(^{-1}\) s\(^{-1}\)); the orange lines show the 500 hPa geopotential field together with their anomalies (black lines). The green cross indicates the point of maximum GPLLJ intensity and green contour refers to the 75th percentile of the GPLLJ index value. The days used for the composites are: (a) those with TM below the 25th percentile (low TM); (b) those with TM above the 75th percentile (high TM); (c) the concurrent extreme days of \((-\omega, \text{precipitation})\) for low TM; and (d) the concurrent extreme days of \((-\omega, \text{precipitation})\) for high TM.
Future work should involve extending worldwide the univariate analysis of the moisture transport driven by the different LLJ systems (Algarra et al. 2019). It would also be interesting to perform an analogous analysis for the TM by the other major moisture transport systems, the atmospheric rivers; see Algarra et al. (2020). In that work, an increasing trend of moisture taken by atmospheric rivers in their main sources was identified. However, only the mean values were studied and the analysis of the extremes of the moisture transport remain to be analyzed in order to assess if they exhibit the same behavior. Regarding the bivariate analysis involving precipitation and vertical movement, it would be very valuable to know if the results reached in this paper when analyzing the GPLLLJ are extensible to other LLJ systems. Additionally, it would be interesting to discriminate according to the type of precipitation, separating large-scale precipitation from another more localized, such as that derived from MCS or isolated storms. Moreover, in that case of localized precipitation, adding other variables that reproduce vertical movements on a smaller scale would also be of interest, for example the Convective Available Potential Energy (CAPE), which better reproduces movements derived from thermodynamic instability. Finally, due to the extensive data that we possess regarding the climate processes addressed in this paper, we intend to carry out in the near future extremal analyses which will take into account the spatial characteristics of the meteorological phenomena (see Davison et al. (2012) and Huser and Wadsworth (2020)).

Appendix A Results of the statistical tests to decide if the exponential distribution is better than the GPD for the TM series

See Table 10, which contains the results of the Cramér-von Mises (CvM) test, Anderson-Darling (AD) test, Likelihood Ratio Test (LRT) and Lilliefors-corrected Kolmogorov-Smirnov (LcKS) test for the TM series, with \( u = 2 \) and declustering run length (\( r \)) equal to 1, 2, 3 and 4.

Table 10 Observed value of the Cramér-von Mises (CvM), Anderson-Darling (AD), Likelihood Ratio Test (LRT) and Lilliefors-corrected Kolmogorov-Smirnov (LcKS) statistics and corresponding \( p \)-values for the TM series, with \( u = 2 \) and declustering run length (\( r \)) equal to 1, 2, 3 and 4

| \( r \) | \( r=1 \) | \( r=2 \) | \( r=3 \) | \( r=4 \) |
|-------|-------|-------|-------|-------|
| CvM statistic | 0.035 | 0.036 | 0.033 | 0.032 |
| approx. \( p \)-value | \( >0.5 \) | \( >0.5 \) | \( >0.5 \) | \( >0.5 \) |
| AD statistic | 0.222 | 0.241 | 0.245 | 0.246 |
| approx. \( p \)-value | \( >0.5 \) | \( >0.5 \) | \( >0.5 \) | \( >0.5 \) |
| LRT statistic | 0.231 | 0.214 | 0.036 | 0.034 |
| \( p \)-value | 0.631 | 0.644 | 0.850 | 0.854 |
| LcKS statistic | 0.057 | 0.057 | 0.049 | 0.053 |
| approx. \( p \)-value | 0.755 | 0.782 | 0.940 | 0.921 |

Appendix B Dates corresponding to the cluster maxima of excesses for \( r=4 \)

See Table 11, which contains the dates corresponding to the cluster maxima of excesses for \( r = 4 \).

Table 11 Dates corresponding to the cluster maxima of excesses for \( r = 4 \)

| Year | Month-Day (m-dd) |
|------|-----------------|
| 1980 | 7-08, 8-13      |
| 1981 | 7-10, 7-29, 8-14|
| 1982 | 7-01, 8-05, 8-26|
| 1983 | 7-20, 8-26      |
| 1984 | 6-15, 8-11      |
| 1985 | 6-05, 6-25      |
| 1986 | 6-03, 7-18, 8-25|
| 1987 | 6-10, 7-10, 7-25, 8-10, 8-25|
| 1988 | 7-31, 8-07      |
| 1989 | 7-27, 8-27      |
| 1990 | 7-08, 7-19      |
| 1991 | 6-30, 7-17, 7-23|
| 1992 | 7-11, 7-21      |
| 1993 | 6-16, 7-03, 7-29, 8-19|
| 1994 | 7-17            |
| 1995 | 8-02, 8-09      |
| 1996 | 6-28, 8-09, 8-25|
| 1997 | 6-23, 7-10      |
| 1998 | 7-05, 8-01     |
| 1999 | 7-05, 7-23, 8-04|
| 2000 | 7-08, 8-12, 8-17, 8-24|
| 2002 | 6-22, 7-05      |
| 2003 | 8-16            |
| 2004 | 7-13            |
| 2005 | 7-22            |
| 2006 | 8-05            |
| 2007 | 6-28, 7-21, 8-22|
| 2008 | 7-06, 7-25      |
| 2010 | 7-29            |
| 2011 | 7-03, 7-12, 8-01|
| 2013 | 7-17, 8-28      |
| 2014 | 6-22, 7-12, 8-23|
| 2015 | 6-17, 7-30      |
| 2016 | 6-03, 6-26, 7-19, 8-08, 8-18, 8-28|
| 2017 | 8-21            |
Appendix C Threshold selection for tropospheric instability and precipitation

In Figs. 19 and 20 it is possible to see the threshold selection plots, i.e. the estimated mean excess function and the ML estimates for the shape parameter of the fitted GPD models, for tropospheric instability ("-omega"), in the cases of low and high TM. In Figs. 21 and 22 the plots corresponding to precipitation are shown.

Fig. 19 Estimated MEF of "-omega" for low TM (left) and high TM (right), with 95% confidence intervals as black dashed lines and fitted solid blue line to the right of $u_1 = 0.03$, in both the cases of low and high TM.

Fig. 20 ML estimates for the shape parameter of the GPD models fitted to the "-omega" series, for the cases of low TM (left) and high TM (right), as a function of $u$. 
Appendix D Results of the statistical tests for the distribution fitting for tropospheric instability and precipitation

In Table 12 it is possible to see the results of the Cramér-von Mises test, Anderson-Darling test and Likelihood Ratio Test for tropospheric instability (“-omega”) and precipitation, in the cases of low and high TM. In Table 13 the results of the Exponential distribution fitting and the Lilliefors-corrected Kolmogorov-Smirnov (LcKS) test for the precipitation series (in the cases of low and high TM) are shown.

Fig. 21 Estimated MEF of precipitation for low TM (left) and high TM (right), with 95% confidence intervals as black dashed lines and fitted solid blue line to the right of $\omega_2 = 5.2$, in both the cases of low and high TM.

Fig. 22 ML estimates for the shape parameter of the GPD models fitted to the precipitation series, for the cases of low TM (left) and high TM (right), as a function of $u$. 

Appendix D Results of the statistical tests for the distribution fitting for tropospheric instability and precipitation
Table 12 Observed values of the Cramér-von Mises, Anderson-Darling and Likelihood Ratio Test statistics and corresponding p-values for the “-omega” and precipitation series, for the thresholds \( u_1 = 0.03 \) for “-omega” and \( u_2 = 5.2 \) for precipitation

|                      | -Omega(low TM) | Prec. (low TM) | -Omega(high TM) | Prec. (high TM) |
|----------------------|----------------|----------------|-----------------|-----------------|
| CvM statistic        | 0.024          | 0.043          | 0.060           | 0.036           |
| approx. p-value      | >0.5           | >0.5           | >0.5            | >0.5            |
| AD statistic         | 0.173          | 0.306          | 0.427           | 0.219           |
| approx. p-value      | >0.5           | >0.5           | >0.5            | >0.5            |
| LRT statistic        | 4.344          | 1.24           | 15.503          | 2.369           |
| p-value              | 0.037          | 0.265          | \( \approx 0 \) | 0.124           |

Table 13 ML estimate for the scale parameter of the Exponential distribution (\( \hat{\sigma}_{\text{exp}} \)) and observed value of the LcKS statistic (with the approximate \( p \)-value of that test) for the precipitation series (in the cases of low and high TM), choosing threshold \( u_2 = 5.2 \) in both cases. In each case, the standard error of \( \hat{\sigma}_{\text{exp}} \) is also shown

|                      | Prec. (low TM) | Prec. (high TM) |
|----------------------|----------------|-----------------|
| \( \hat{\sigma}_{\text{exp}} \) (Std.Err) | 1.020 (0.138)  | 1.442 (0.146)   |
| LcKS statistic       | 0.099          | 0.076           |
| approx. p-value      | 0.413          | 0.376           |

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Declarations

Conflict of interest The authors declare that they have no conflict of interest.

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