Asim Zafar, Hadi Rezazadeh, and Khalid K. Ali*

On finite series solutions of conformable time-fractional Cahn-Allen equation

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Abstract: The aim of this article is to derive new exact solutions of conformable time-fractional Cahn-Allen equation. We have achieved this aim by hyperbolic function method with the aid of symbolic computation using Mathematica. This idea seems to be very easy to employ with reliable results. The time fractional Cahn-Allen equation is reduced to respective nonlinear ordinary differential equation of fractional order. Also, we have depicted graphically the constructed solutions.

Keywords: time-fractional Cahn-Allen equation; conformable derivatives; \( \exp_a \) function method; hyperbolic function method; finite series solutions

1 Introduction

Fractional differential equation may be considered as the missing part of the classical differential equations. In recent years, many authors have studied the nonlinear fractional differential equations for example see [1–8] because these equations express many complex nonlinear physical phenomena and dynamic forms in physics. Several definitions of fractional derivative have been presented to the literature, amongst are Atangana Baleanu operator, Caputo-Fabrizio and conformable derivative.

In this research, we apply two methods on conformable time-fractional Cahn-Allen equation to scrutinize the new explicit exact solutions [9–12] that may read as

\[ D_t^\gamma u_{xx} + u^3 - u = 0, \quad 0 < \gamma \leq 1. \]

We employ the \( \exp_a \) function approach [13–15] and the hyperbolic function approach [16–18] via traveling wave transformation with the conformable derivative.

The rest of the article is arranged as follows: In Section 2 some preliminaries and notations dealing with the fractional calculus theory are briefly described. Section 3 presents description of methods. The exact solutions of the nonlinear Cahn-Allen equation are constructed in Section 4. In Section 5 some graphical representation for solutions are showed. Section 6 presents the summary of the obtained results.

2 Conformable derivative

The latter part presents the results of the current study graphically.

We recall the conformable derivative with some of its properties [19].

Definition 1 Suppose \( h : \mathbb{R}_{>0} \to \mathbb{R} \) be a function. Then, for all \( t > 0 \),

\[ D_t^\alpha p(t) = \lim_{\varepsilon \to 0} \frac{p(t + \varepsilon t^{1-\alpha}) - p(t)}{\varepsilon}, \]

is known as \( \alpha, \quad 0 < \alpha \leq 1 \) order conformable fractional derivative of \( p \). The followings are some useful properties:

\[ D_t^\alpha (a + b) = a D_t^\alpha (p) + b D_t^\alpha (g), \quad \text{for all } a, b \in \mathbb{R} \]
\[ D_t^\alpha (p g) = p D_t^\alpha (g) + g D_t^\alpha (p) \]
Let \( p : \mathbb{R}_{>0} \to \mathbb{R} \) be an \( \alpha \)-differentiable function, \( g \) be a differentiable function defined in the range of \( p \).

\[ D_t^\alpha (p \circ g(t)) = t^{1-\alpha} g'(t) p'(g(t)). \]

On the top of that, the following rules hold.

\[ D_t^\alpha (t^h) = h t^{h-\alpha}, \quad \text{for all } h \in \mathbb{R} \]
\[ D_t^\alpha (\delta) = 0, \quad \text{where } \delta \text{ is constant.} \]
\[ D_t^\alpha \left( \frac{p}{g} \right) = \frac{g D_t^\alpha (p) - \alpha p D_t^\alpha (g)}{g^2}. \]

Conjointly, if \( p \) is differentiable, then \( D_t^\alpha (p(t)) = t^{1-\alpha} \frac{dp(t)}{dt}. \)
3 Description of methods

The present subsection provides a brief explanation for two reliable techniques in engendering new exact solutions to nonlinear conformable time-fractional equation. For this purpose, suppose that we have a nonlinear conformable time FDE that can be presented in the form

\[ F(u, D_t^\beta u, D_x^\gamma u, D_{xx}^\delta u, \ldots) = 0. \]  \hspace{1cm} (2)

The FDE (2) can be changed into the following nonlinear ODE of integer order

\[ \psi(U, U', U'', \ldots) = 0, \]  \hspace{1cm} (3)

with the use of following wave transformation

\[ u(x, t) = U(\eta), \eta = k_1 x - k_2 t^\nu, \]  \hspace{1cm} (4)

where \( \nu = d/d\eta \) while \( k_1 \) and \( k_2 \) are nonzero arbitrary constants.

3.1 The exp\(_a\) function approach

Let us try to search a non-trivial solution for (3) in the following form [13–15, 20]

\[ U(\eta) = A_0 + A_1 a^\eta + \ldots + A_N a^{N\eta}, \]  \hspace{1cm} (5)

where \( A_i \) and \( B_i \), for \( 0 < i < N \), are found later and \( N \) is a free positive constant.

Replacing (5) in the nonlinear (3), yields

\[ \varphi(a^\eta) = q_0 + q_1 a^\eta + \ldots + q_\tau a^{\tau\eta} = 0. \]  \hspace{1cm} (6)

Setting \( l_i(0 < i < \tau) \) in (5) to be zero, results give a set of nonlinear equations as follows:

\[ q_i = 0, \quad i = 0, \ldots, \tau \]  \hspace{1cm} (7)

by solving the generated set (7), we acquire non-trivial solutions of the nonlinear PDE (2).

3.2 The hyperbolic function approach

Let us try to search a non-trivial solution to (3) in the following form [16–18, 21]

\[ U(\eta) = A_0 + \sum_{i=1}^{N} \sinh^{i-1}(\rho)[B_i \sinh(\rho) + A_i \cosh(\rho)], \]  \hspace{1cm} (8)

where \( \rho \) is some specific functions. By calculating the positive integer \( N \), setting (8) in (3), and comparing coefficients, we will find a set of nonlinear equations whose solution, finally provides explicit exact solutions of (2). It is worth mentioning that using the separation of variables technique on \( \frac{D_t^\beta}{D_\eta} \) = sinh(\( \eta \)), we find sinh(\( \rho \)) = \( \pm \cosh(\eta) \), sinh(\( \rho \)) = \( \mp \coth(\eta) \) and sinh(\( \rho \)) = \( \pm \tanh(\eta) \). Accordingly, the solution (7) can be rewritten as

\[ U(\eta) = A_0 + \sum_{i=1}^{N} (\pm \cosh)^{i-1}(\eta)[B_i \cosh(\eta) - A_i \coth(\eta)], \]  \hspace{1cm} and

\[ U(\eta) = A_0 + \sum_{i=1}^{N} (\pm \tanh)^{i-1}(\eta)[B_i \tanh(\eta) - A_i \csc(\eta)]. \]

Similarly, it is obvious that from \( \frac{D_t^\beta}{D_\eta} = \cosh(\rho) \), we find sinh(\( \rho \)) = \( \mp \cot(\eta) \), sinh(\( \rho \)) = \( \pm \sec(\eta) \) and sinh(\( \rho \)) = \( \pm \cosec(\eta) \). Accordingly, the solution (7) can be rewritten as

\[ U(\eta) = A_0 + \sum_{i=1}^{N} (\pm \cot)^{i-1}(\eta)[B_i \cot(\eta) \pm A_i \cosec(\eta)], \]  \hspace{1cm} and

\[ U(\eta) = A_0 + \sum_{i=1}^{N} (\pm \sec)^{i-1}(\eta)[B_i \tan(\eta) \pm A_i \sec(\eta)]. \]

4 Application to time-fractional Cahn-Allen equation

Using the transformation (4) in (1), we get

\[ k_2 U'' - k_1^2 U' - U + U^3 = 0. \]  \hspace{1cm} (9)

Through balancing the terms \( U'' \) and \( U^3 \), we select \( N = 1 \), the nontrivial solution (5) reduces to:

\[ U(\eta) = \frac{a_1 a^\eta + a_0}{B_1 a^\eta + B_0}, \quad a \neq 1 \]  \hspace{1cm} (10)

By setting the above solution in (9) and equating factors of each power of \( a^\eta \) in the resulting equation, we reach a set of nonlinear algebraic equations.

\[ a_0^3 - a_0 b_0^2 = 0, \]  \hspace{1cm} (a.1)

\[ a_1^3 - a_1 b_1^2 = 0, \]  \hspace{1cm} (a.2)

\[ a_0 b_0 b_1 k_1^2 \log^2(a) - a_1 b_0^2 k_1^2 \log^2(a) + a_0 b_0 b_1 k_2 \log(a) - a_1 b_0^2 k_2 \log(a) - 2a_0 b_0 b_1 - a_1 b_0^2 + 3a_1 a_0^2 = 0, \]  \hspace{1cm} (a.3)

\[ a_1 b_0 b_1 k_1^2 \log^2(a) - a_0 b_1^2 k_1^2 \log^2(a) - a_1 b_0 b_1 k_2 \log(a) + a_0 b_1^2 k_2 \log(a) - 2a_1 b_0 b_1 - a_0 b_1^2 + 3a_0 a_1^2 = 0, \]  \hspace{1cm} (a.4)
which its solution yields the following new explicit exact solutions to (1).

\[
\begin{align*}
  a_0 &= 0, a_1 = \mp b_1, b_0 = b_0, b_1 = b_1, \\
  k_1 &= \frac{1}{\sqrt{2} \log(a)}, k_2 = -\frac{3}{2 \log(a)}.
\end{align*}
\] (11)

\[
\begin{align*}
  a_0 &= 0, a_1 = \mp b_1, b_0 = b_0, b_1 = b_1, \\
  k_1 &= \frac{1}{\sqrt{2} \log(a)}, k_2 = -\frac{3}{2 \log(a)}.
\end{align*}
\] (12)

\[
\begin{align*}
  a_0 &= \mp b_0, a_1 = 0, b_0 = b_0, b_1 = b_1, \\
  k_1 &= -\frac{1}{\sqrt{2} \log(a)}, k_2 = \frac{3}{2 \log(a)}.
\end{align*}
\] (13)

\[
\begin{align*}
  a_0 &= \mp b_0, a_1 = 0, b_0 = b_0, b_1 = b_1, \\
  k_1 &= \frac{1}{\sqrt{2} \log(a)}, k_2 = -\frac{3}{2 \log(a)}.
\end{align*}
\] (14)

\[
\begin{align*}
  u_{1,2}(x, t) &= \mp b_1 a^\left(\frac{-1}{\sqrt{2} \log(a)} x + \frac{1}{2 \log(a)} y\right) + b_0,
\end{align*}
\] (15)

\[
\begin{align*}
  u_{3,4}(x, t) &= \mp b_1 a^\left(\frac{-1}{\sqrt{2} \log(a)} x + \frac{1}{2 \log(a)} y\right) + b_0,
\end{align*}
\] (16)

\[
\begin{align*}
  u_{5,6}(x, t) &= \mp b_0 a^\left(\frac{-1}{\sqrt{2} \log(a)} x + \frac{1}{2 \log(a)} y\right) + b_0,
\end{align*}
\] (17)

\[
\begin{align*}
  u_{7,8}(x, t) &= \mp b_0 a^\left(\frac{-1}{\sqrt{2} \log(a)} x + \frac{1}{2 \log(a)} y\right) + b_0.
\end{align*}
\] (18)

We now again consider (9) to solve by utilizing the hyperbolic function approach.

**Case:** \( \frac{\partial^2 u}{\partial t^2} = \sinh(\rho) \)

Through homogenouess balancing principle, the terms \( U'' \) and \( U^3 \) gives \( N = 1 \) and the non-trivial solution (8) becomes

\[ U(\eta) = B_1 \sinh(\rho) + A_1 \cosh(\rho) + A_0. \] (19)

By setting the above non-trivial solution (19) in (9) and equating the coefficients to zero in the resultant equation, we reach a set of nonlinear polynomial equations.

\[
\begin{align*}
  A_0^3 + 3A_1^2 A_0 - A_0 &= 0, \\
  3A_1 B_1 - 2A_1 k_1^2 + A_0^3 &= 0, \\
  -3A_1 B_1^2 + 2A_1 k_1^2 + 3A_1 A_0 - A_1 &= 0, \\
  3A_1 B_1 - 2B_1 k_1^2 + B_1^3 &= 0, \\
  3A_0 B_1^2 + 3A_0 B_1 - B_1 k_1^2 - B_1^3 &= 0, \\
  3A_0 B_1^2 + A_1 k_2 + 3A_0 A_1^2 &= 0, \\
  6A_0 A_1 B_1 + B_1 k_2 &= 0.
\end{align*}
\]

On solving the obtained set of equations yields the following sets of solutions which will give us the new exact solutions of (1).

\[
\begin{align*}
  A_0 &= -\frac{1}{2}, A_1 = -\frac{1}{2}, B_1 = -\frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = -\frac{3}{2},
\end{align*}
\] (20)

\[
\begin{align*}
  A_0 &= -\frac{1}{2}, A_1 = -\frac{1}{2}, B_1 = -\frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = -\frac{3}{2},
\end{align*}
\] (21)

\[
\begin{align*}
  A_0 &= \frac{1}{2}, A_1 = -\frac{1}{2}, B_1 = -\frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = \frac{3}{2},
\end{align*}
\] (22)

\[
\begin{align*}
  A_0 &= \frac{1}{2}, A_1 = -\frac{1}{2}, B_1 = \frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = \frac{3}{2},
\end{align*}
\] (23)

\[
\begin{align*}
  A_0 &= -\frac{1}{2}, A_1 = -\frac{1}{2}, B_1 = 0, k_1 = \mp \frac{1}{2 \sqrt{2}}, k_2 = -\frac{3}{4},
\end{align*}
\] (24)

\[
\begin{align*}
  A_0 &= \frac{1}{2}, A_1 = -\frac{1}{2}, B_1 = 0, k_1 = \mp \frac{1}{2 \sqrt{2}}, k_2 = \frac{3}{4},
\end{align*}
\] (25)

\[
\begin{align*}
  A_0 &= -\frac{1}{2}, A_1 = \frac{1}{2}, B_1 = 0, k_1 = \mp \frac{1}{2 \sqrt{2}}, k_2 = \frac{3}{4},
\end{align*}
\] (26)

\[
\begin{align*}
  A_0 &= \frac{1}{2}, A_1 = \frac{1}{2}, B_1 = 0, k_1 = \mp \frac{1}{2 \sqrt{2}}, k_2 = -\frac{3}{4},
\end{align*}
\] (27)

\[
\begin{align*}
  A_0 &= -\frac{1}{2}, A_1 = \frac{1}{2}, B_1 = -\frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = \frac{3}{2},
\end{align*}
\] (28)

\[
\begin{align*}
  A_0 &= -\frac{1}{2}, A_1 = \frac{1}{2}, B_1 = \frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = \frac{3}{2},
\end{align*}
\] (29)

\[
\begin{align*}
  A_0 &= \frac{1}{2}, A_1 = \frac{1}{2}, B_1 = -\frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = -\frac{3}{2},
\end{align*}
\] (30)

\[
\begin{align*}
  A_0 &= \frac{1}{2}, A_1 = \frac{1}{2}, B_1 = \frac{1}{2}, k_1 = \mp \frac{1}{\sqrt{2}}, k_2 = -\frac{3}{2}.
\end{align*}
\] (31)

We now write some new exact solutions using (20) to (31) as follows. From (19) and (20) we get,

\[
\begin{align*}
  u(x, t) &= -\frac{1}{2} \coth(\frac{1}{\sqrt{2}} x + \frac{3 \rho'}{2} y) - \frac{1}{2} \csc(\frac{1}{\sqrt{2}} x + \frac{3 \rho'}{2} y).
\end{align*}
\] (32)

Now from Eqs. (19) and (24) we get,

\[
\begin{align*}
  u(x, t) &= -\frac{1}{2} \coth(\frac{1}{2 \sqrt{2}} x + \frac{3 \rho'}{4} y) - \frac{1}{2}.
\end{align*}
\] (33)
Now from Eqs. (19) and (28) we get,
\[
\frac{d}{dt}u(x, t) = \frac{1}{2} \cosh(\frac{1}{\sqrt{2}}x - \frac{3}{2} \frac{\tau^\rho}{2}y) - \frac{1}{2} \frac{1}{2} \csc(\frac{1}{\sqrt{2}}x - \frac{3}{2} \frac{\tau^\rho}{2}y),
\]
(34)
The other solutions can be formulated on the same way.

**Case 2:** \( \frac{d\rho}{dt} = \cosh(\rho) \) and for \( N = 1 \), the non-trivial solution (8) becomes

\[
U(\eta) = A_0 + B_1 \cot(\rho) - A_1 \csc(\rho).
\]
(35)

By setting the above non-trivial solution in (9) and equating the coefficients to zero in the resultant equation, we reach the following set of polynomial equations.

\[
-3A_0B_1^2 + A_0^2 - A_0 = 0,
3A_1B_1^2 - A_1k_1^2 - 3A_1A_0^2 + A_1 = 0,
-3A_1B_1^2 + 2A_1k_1^2 - A_1 = 0,
3A_0B_1 + 3A_1^2B_1 - 2B_1k_1^2 - B_1 = 0,
3A_1B_1 - 2B_1k_1^2 + B_1 = 0,
-6A_0A_1B_1 - A_1k_2 = 0,
3A_0B_1^2 + 3A_0A_1^2 + B_1k_2 = 0.
\]

On solving this system of equations, we obtain the following sets of solutions that will give us the new exact solutions of (1)

\[
A_0 = -\frac{1}{2}, \quad A_1 = -\frac{i}{2}, \quad B_1 = -\frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = -\frac{3i}{2},
\]
(36)

\[
A_0 = -\frac{1}{2}, \quad A_1 = \frac{i}{2}, \quad B_1 = -\frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = -\frac{3i}{2},
\]
(37)

\[
A_0 = \frac{1}{2}, \quad A_1 = -\frac{i}{2}, \quad B_1 = -\frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = \frac{3i}{2},
\]
(38)

\[
A_0 = \frac{1}{2}, \quad A_1 = \frac{i}{2}, \quad B_1 = -\frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = \frac{3i}{2},
\]
(39)

\[
A_0 = -\frac{1}{2}, \quad A_1 = 0, \quad B_1 = -\frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = -\frac{3i}{4},
\]
(40)

\[
A_0 = \frac{1}{2}, \quad A_1 = 0, \quad B_1 = -\frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = \frac{3i}{4},
\]
(41)

\[
A_0 = -\frac{1}{2}, \quad A_1 = 0, \quad B_1 = \frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = \frac{3i}{4},
\]
(42)

\[
A_0 = \frac{1}{2}, \quad A_1 = 0, \quad B_1 = \frac{i}{\sqrt{2}}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = -\frac{3i}{4}.
\]
(43)

We now write some new complex trigonometric solutions using (36) to (47) as follows. From (36) and Case-2 of (19) we get,

\[
A_0 = -\frac{1}{2}, \quad A_1 = -\frac{i}{2}, \quad B_1 = \frac{i}{2}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = -\frac{3i}{2}.
\]
(44)

\[
A_0 = \frac{1}{2}, \quad A_1 = \frac{i}{2}, \quad B_1 = \frac{i}{2}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = \frac{3i}{2}.
\]
(45)

\[
A_0 = \frac{1}{2}, \quad A_1 = -\frac{i}{2}, \quad B_1 = \frac{i}{2}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = -\frac{3i}{2}.
\]
(46)

\[
A_0 = \frac{1}{2}, \quad A_1 = \frac{i}{2}, \quad B_1 = \frac{i}{2}, \quad k_1 = \pm \frac{i}{\sqrt{2}}, \quad k_2 = -\frac{3i}{2}.
\]
(47)

From (40) and Case-2 of (19), we obtain

\[
u(x, t) = -\frac{i}{2} \cot(\frac{1}{\sqrt{2}}x + \frac{3i}{2} \frac{\tau^\rho}{2}y) - \frac{1}{2} + \frac{i}{2} \csc(\frac{1}{\sqrt{2}}x + \frac{3i}{2} \frac{\tau^\rho}{2}y).
\]
(48)

From (44) and Case-2 of (19), we procure

\[
u(x, t) = \frac{1}{2} \cot(\frac{1}{\sqrt{2}}x + \frac{3i}{2} \frac{\tau^\rho}{2}y) - \frac{1}{2} + \frac{i}{2} \csc(\frac{1}{\sqrt{2}}x + \frac{3i}{2} \frac{\tau^\rho}{2}y).
\]
(49)

The other solutions can be formulated on the same way.
5 Some graphical illustrations

In this section, we give some graphical illustrations of the acquired solutions of our equations. The 2-dimensional and 3-dimensional plots of certain solutions are presented as follows.

Figure 2: Graphs of (12) for conformable time-fractional Cahn-Allen equation.

Figure 3: Graphs of (13) for conformable time-fractional Cahn-Allen equation.

Figure 4: Graph of (32) for conformable time-fractional Cahn-Allen equation.

Figure 5: Graphs of (33) for conformable time-fractional Cahn-Allen equation.
Figure 6: Graphs of (34) for conformable time-fractional Cahn-Allen equation.

Figure 7: Graphs of (48) for conformable time-fractional Cahn-Allen equation.

Figure 8: Graphs of (49) for conformable time-fractional Cahn-Allen equation.

Figure 9: Graphs of (50) for conformable time-fractional Cahn-Allen equation.
6 Conclusion

In this paper an efficient method was built up to solve conformable time-fractional Cahn-Allen equation. This idea is based on the idea of hyperbolic function and expa function, which is a known method for solving diffusion equations. These methods are very powerful with minimum algebraic work. The computations are done using Maple 18.

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