A PTAS for parallel two-stage flowshops under makespan constraint

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Abstract

As a hybrid of the Parallel Two-stage Flowshop problem and the Multiple Knapsack problem, we investigate the scheduling of parallel two-stage flowshops under makespan constraint, which was motivated by applications in cloud computing and introduced by Chen et al. \cite{3} recently. A set of two-stage jobs are selected and scheduled on parallel two-stage flowshops to achieve the maximum total profit while maintaining the given makespan constraint. We give a positive answer to an open question about its approximability proposed by Chen et al. \cite{3}. More specifically, based on guessing strategies and rounding techniques for linear programs, we present a polynomial time approximation scheme (PTAS) for the case when the number of flowshops is a fixed constant. As the case with two flowshops is already strongly NP-hard, our PTAS achieves the best possible approximation ratio.

Keywords: Parallel two-stage flowshops; Makespan constraint; Polynomial-time approximation scheme; Multiple knapsacks; Rounding.

1. Introduction

We study the scheduling of parallel two-stage flowshops under makespan constraint. Suppose there are \( m \) identical two-stage flowshops \( \mathcal{F} = \{F_j, j \in \{1, 2, \ldots, m\}\} \) and a set of \( n \) jobs \( \mathcal{J} = \{J_i, i \in \{1, 2, \ldots, n\}\} \). Once assigning a job \( J_i \) to some flowshop \( F_j \), job \( J_i \) needs to be processed non-preemptively on \( F_j \) and the first and second operation of \( J_i \) has a workload of \( a_i \) and \( b_i \) respectively. Meanwhile, finishing processing \( J_i \) brings a profit \( p_i \). The objective is to identify the most profitable subset of jobs, denoted by \( \mathcal{J}^{\text{selected}} \), such that the minimum makespan of \( \mathcal{J}^{\text{selected}} \), i.e., the completion time of the last job, is bounded by 1. In other words, we aim at packing two-stage jobs to parallel flowshops in order to achieve the maximum total profit. Therefore, we also name the studied problem as the \((m, 2)\)-Flowshop-Packing problem.

The study of parallel two-stage flowshops under makespan constraint was recently introduced by Chen et al. \cite{3} and was motivated by applications from cloud computing \cite{21}. Receiving a request from a client for a specific resource, a server on the cloud will read certain data from disks and then transfer the data back to the client. Thus, a server can be regarded as a two-stage flowshop and a request from clients can be treated as a two-stage job consisting of a disk-reading operation and a network-transition operation. The cloud service provider aims to maximize the profit under time constraint.

For a maximization optimization problem \( \Pi \) and an approximation algorithm \( \mathcal{A} \), the approximation ratio of \( \mathcal{A} \) is defined as \( \max_{I \in \mathcal{I}} \{\mathcal{A}(I)/\text{OPT}(I)\} \), where \( \mathcal{I} \) is the set of instances.

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\textsuperscript{1}The makespan constraint can be any real value. Without loss of generality, the boundary value is set to 1, as we are always able to scale the job sizes.
A maximization problem admits a polynomial-time approximation schemes (PTAS) if there is a family of algorithms \( \{\mathcal{A}_{\epsilon}, \epsilon > 0\} \) such that each algorithm \( \mathcal{A}_{\epsilon} \) has an approximation ratio of \( 1 - \epsilon \) for any \( \epsilon > 0 \) and its time complexity is \( O(n^{f(1/\epsilon)}) \) for instance size \( n \) and some function \( f \). We say a PTAS is an efficient polynomial-time approximation scheme (EPTAS) if the running time of \( \mathcal{A}_{\epsilon} \) is in the form of \( f(1/\epsilon) \cdot n^{O(1)} \); and we say a PTAS is a fully polynomial-time approximation schemes (FPTAS) if the running time of \( \mathcal{A}_{\epsilon} \) is a polynomial in \( 1/\epsilon \), that is, \((1/\epsilon)^{O(1)} \cdot n^{O(1)}\).

It is not hard to observe that the classic Knapsack problem \([7]\) is a special case of (1,2)-Flowshop-Packing by setting \( b_i = 0 \) for all jobs. Similarly, the (m,2)-Flowshop-Packing problem generalizes the Multiple Knapsack problem, which admits no FPTAS for the two-knapsack case unless \( P = NP \) \([2]\). Therefore, the (1,2)-Flowshop-Packing problem inherits the NP-hardness from the Knapsack problem and the general case (m,2)-Flowshop-Packing is strongly NP-hard even for \( m = 2 \).

A special case with only one flowshop was initially explored by Dawande et al. \([4]\), who proposed an approximation algorithm with a ratio of \( 1/3 - \epsilon \) by utilizing the FPTAS for the Knapsack problem \([9]\). Recently, Chen et al. \([3]\) introduced the multiple-flowshops version and study this problem systematically. When the number of flowshops is part of the input, they first presented an computationally efficient 1/4-approximation algorithm and then improved the ratio to \( 1/3 - \epsilon \) by exploring the connection between the Multiple Knapsack problem and the (m,2)-Flowshop-Packing problem. When the number of flowshops is a fixed constant, they integrated approximation techniques for the classical Knapsack problem and the Parallel Machine Scheduling problem and designed a (1/2 - \( \epsilon \))-approximation algorithm, which also improves the approximability result by Dawande et al. \([4]\). Chen et al. \([3]\) then proposed an open question that whether the problem has polynomial-time approximation schemes particularly when the number \( m \) of flowshops is a fixed constant. We give a positive answer for the case when \( m \) is a fixed constant.

| Problem | Hardness | Approximability |
|---------|----------|----------------|
| (1,2)-Flowshop-Packing | NP-hard | \( 3 + \epsilon \) \([4]\) |
| (m,2)-Flowshop-Packing \((m \geq 2\) is fixed) | Strongly NP-hard | \( 2 + \epsilon \) \([3]\) |
| (m,2)-Flowshop-Packing \((m \geq 2\) is part of the input) | Strongly NP-hard | \( 1 + \epsilon \) (Our work) |

Observing that scheduling jobs on one two-stage flowshop to achieve the minimum makespan can be resolved in polynomial time by the famous Johnson’s Algorithm \([12]\), we roughly solve the studied problem by two steps: (1) identifying a high-profit job subset; (2) scheduling the selected jobs on each flowshop with Johnson’s Algorithm. The first step is more involved as it should be on the alert for jobs with large workload so that the second step will not violate the makespan constraint. Our main contribution is a PTAS for the (m,2)-Flowshop-Packing problem by combining guessing strategies and rounding techniques in linear programming. It is worth remarking that guessing a quantity in polynomial time means identifying a polynomial number of values for this quantity in polynomial time.

Our first idea is to guess in polynomial time the most profitable subset of size \( \frac{1 + \epsilon}{\epsilon} \) in the optimal solution, where \( \epsilon > 0 \) is chosen such that \( \frac{1 + \epsilon}{\epsilon} \) is an integer. Consequently, the remaining jobs that need to be selected are relatively cheaper. Based on the quantitative
formula (refer to Eq. (1)) to estimate the makespan when a job sequence is under Johnson’s order, our second idea is to design a linear program to select the cheap jobs fractionally. It turns out that this linear program guarantees a strong property. That is, except for at most a constant number of cheap jobs, most cheap jobs can be identified integrally via the optimal solution to this linear program.

To illustrate our ideas more clearly, we start with resolving the (1,2)-Flowshop-Packing problem by designing a PTAS for it. Then we extend our ideas to the general case, i.e., the (m,2)-Flowshop-Packing problem, and present another PTAS when the number of flowshops is a fixed constant. Our results significantly improve the approximation ratios obtained by Chen et al. [3] and Dawande et al. [4]. Please refer to Table 1 for existing results and our contributions.

Organization. We review the most related works in Section 2. Section 3 introduces some essential notions and terminologies. We present and analyze the PTASes for the (1,2)-Flowshop-Packing and (m,2)-Flowshop-Packing problems in Section 4 and Section 5 respectively. In Section 6, we make a conclusion and discuss future research directions.

2. Related Work

The (m, 2)-Flowshop-Packing problem aims at maximizing the total profit by selecting and scheduling jobs on parallel two-stage flowshops with makespan constraint. It is closely related to the Parallel Two-stage Flowshop Scheduling problem [14] and the Multiple Knapsack problem [13].

The Parallel Two-stage Flowshop Scheduling problem. Removing the makespan constraint and replacing the objective with makespan minimization result in another scheduling problem, named Parallel Two-stage Flowshop Scheduling, which has attracted quite a few attentions [14, 13, 21, 15, 16, 22, 20, 23]. The parallel two-stage flowshop scheduling problem is NP-hard when \( m \geq 2 \) and becomes strongly NP-hard if \( m \) is part of the input [13]. Kovalyov [14], Dong et al. [6], and Wu et al. [21] designed FPTAS independently for the parallel two-stage flowshop scheduling problem when \( m \) is a fixed constant. For the case where \( m \) is part of the input, Dong et al. [5] eventually presented a PTAS after a few explorations of its approximability by Wu et al. [22, 23]. It is worth noting that for the parallel multi-stage flowshop scheduling problem, Tong et al. [18] proposed a PTAS when both the number of flowshops and the number of stages are constant. It is still open whether a PTAS exists for the parallel multi-stage flowshop scheduling problem when \( m \) is part of the input.

The Multiple Knapsack problem. The (m, 2)-Flowshop-Packing problem reduces the Multiple Knapsack problem by setting the workload of each second-stage operation to zero. An FPTAS exists for the classic Knapsack problem [9] while the Multiple Knapsack problem with two knapsacks is strongly NP-hard [13], implying the impossibility of FPTAS unless \( P = NP \). Kellerer [13] developed a PTAS for the special case of the Multiple Knapsack problem where all knapsacks have same capacity. Chekuri and Khanna [2] proposed a PTAS for the general Multiple Knapsack problem with running time \( O(n \log(1/\epsilon)/\epsilon^2) \). They first cleverly rounded instances in a more structured one that has logarithmic profit values and size values; then grouped knapsacks by their capacities in a structured way; finally sequentially packed the most profitable items, large-size items, and the remaining cheap and small-size items with different strategies. Jansen [10, 11] improved the time efficiency by presenting an EPTAS with parameterized running time \( O\left(2^{\frac{1}{2}\log^2(1/\epsilon)} + poly(n)\right) \). All the above PTASes and EPTAS were designed for the case where \( m \) is part of the input.

Both Chen et al. [3] and Dawande et al. [4] utilized the connection between the Multiple Knapsack problem and the (m, 2)-Flowshop-Packing problem to design approximation
algorithms for the (m, 2)-Flowshop-Packing problem. In particular, they observed that a (Multiple) Knapsack instance can be constructed from an (m, 2)-Flowshop-Packing instance by linearly combining the workload at two stages for each job. Our PTAS does not utilize such connections. Instead, we rely on the structure of the optimal scheduling (with respect to the makespan) guaranteed by Johnson’s Algorithm on each flowshop.

3. Preliminary

In this section, we define the studied problem formally and introduce essential notations and important concepts.

A standard two-stage flowshop contains one machine at every stage and a two-stage job has two operations. Once a job is assigned to a flowshop, its two operations are processed non-preemptively on the two sequential machines in the flowshop, respectively. In particular, the second operation cannot start processing until the first operation has been completed. The makespan is defined as the completion time of the last job. Denote the set \( \{1, 2, \ldots, n\} \) by \( [n] \) for any positive integer \( n \). The formal definition of the scheduling of parallel two-stage flowshops under makespan constraint (or the (m,2)-Flowshop-Packing problem) is shown in Definition 1.

**Definition 1** (The (m,2)-Flowshop-Packing problem). Given a set of \( m \) identical two-stage flowshops \( \mathcal{F} = \{F_j, j \in [m]\} \) and a set of \( n \) jobs \( \mathcal{J} = \{J_i = (a_i, b_i, p_i), i \in [n]\} \), where \( a_i \) and \( b_i \) denotes the processing time or workload of \( J_i \) on the first and second stage respectively and \( p_i \) represents the profit by processing \( J_i \), the goal is to identify a subset of jobs, denoted by \( \mathcal{J}^{\text{selected}} \), and schedule them on the given flowshops such that the total profit is maximized while the makespan is limited within 1.

Assume \( a_i + b_i \leq 1 \) holds for all \( i \in [n] \) without loss of generality. We abuse notations \( a, b, p \) as linear summation functions over a job set. That is, for any subset of jobs \( \mathcal{J}' \), \( a(\mathcal{J}') = \sum_{J_i \in \mathcal{J}'} a_i \), \( b(\mathcal{J}') = \sum_{J_i \in \mathcal{J}'} b_i \), and \( p(\mathcal{J}') = \sum_{J_i \in \mathcal{J}'} p_i \). Suppose \( \mathcal{J}^* \) is the job set chosen in an optimal solution. Let \( OPT = p(\mathcal{J}^*) = \sum_{J_i \in \mathcal{J}^*} p_i \) denote the optimal total profit.

The classic Two-Stage Flowshop problem minimizes the makespan of a single two-stage flowshop and can be solved optimally by the well-known Johnson’s Algorithm [12]. More precisely, we have the following Theorem.

**Theorem 1.** [12, 1] For the two-stage flowshop problem, there exists a permutation schedule which returns the minimum makespan. In this optimal schedule, job \( J_i \) precedes job \( J_{i'} \) if \( \min\{a_i, b_i\} \leq \min\{a_{i'}, b_{i'}\} \). Moreover, the minimum makespan can be computed as

\[
\max_{s \in [n]} \left\{ \sum_{i=1}^{s} a_i + \sum_{i=s}^{n} b_i \right\}.
\]

We say a job sequence is under Johnson’s order if \( \min\{a_i, b_i\} \leq \min\{a_{i'}, b_{i'}\} \) implies job \( J_i \) precedes job \( J_{i'} \). The order of any two jobs is independent of all the other jobs under Johnson’s order. Then Corollary 1 follows immediately.

**Corollary 1.** Given a job sequence under Johnson’s order, any subsequence of this job sequence is under Johnson’s order.

Without loss of generality, all job sequences under consideration in the rest of this paper are assumed in Johnson’s order by default. We say a job is a critical job if it has the subscript \( \arg \max_{s \in [n]} \{ \sum_{i=1}^{s} a_i + \sum_{i=s}^{n} b_i \} \). The tie is broken by taking the job with the smallest subscript index.
4. PTAS for the (1,2)-Flowshop-Packing problem

In this section, a PTAS is presented for the (1,2)-Flowshop-Packing problem, in which there is only one two-stage flowshop. Solving (1,2)-Flowshop-Packing can be naturally partitioned into two steps: selecting a subset of jobs and then finding a feasible schedule on the flowshop for the chosen jobs. As Johnson’s Algorithm is able to schedule jobs to achieve the minimum makespan, we focus on the first step. For any small positive constant $\epsilon \in (0,1)$, the rough idea is to guess a constant number $\frac{1+\epsilon}{\epsilon}$ of the most profitable jobs in the optimal job set $J^*$ and then select cheaper jobs carefully such that the chosen job set $J_{\text{selected}}$ has its overall profit at least $(1-\epsilon) \cdot \text{OPT}$ while the minimum makespan is at most 1.

In sequel, we assume $|J^*| > \frac{1+\epsilon}{\epsilon}$, as otherwise the optimal solution can be found by exhausting $n^{O(1/\epsilon)}$ subsets, each having a size of at most $\frac{1+\epsilon}{\epsilon}$. We guess $\frac{1+\epsilon}{\epsilon}$ most profitable jobs in $J^*$ and denote this subset of jobs by $J_{\text{profitable}}$. It is easy to observe that each cheaper job in $J^* \setminus J_{\text{profitable}}$ has a profit of at most $\epsilon \cdot \text{OPT}$. Otherwise, the total profit of jobs in $J_{\text{profitable}}$ is at least

$$p(J_{\text{profitable}}) \geq \frac{1+\epsilon}{\epsilon} \cdot \min_{J \in J_{\text{profitable}}} p(J) \geq \frac{1+\epsilon}{\epsilon} \cdot \text{OPT} = (1+\epsilon) \cdot \text{OPT} > \text{OPT},$$

which contradicts the definitions of $J_{\text{profitable}}$ and OPT. Then Lemma 1 follows immediately.

**Lemma 1.** For any job in $J^* \setminus J_{\text{profitable}}$, its profit is at most $\epsilon \cdot \text{OPT}$.

Suppose $p_{\text{min}} = \min_{J \in J_{\text{profitable}}} p(J)$. As the jobs in $J_{\text{profitable}}$ are expected to be the $\frac{1+\epsilon}{\epsilon}$ most profitable jobs in $J^*$, all jobs in $J \setminus J_{\text{profitable}}$ with profit greater than $p_{\text{min}}$ can be ignored temporarily. Let $J' = \{J \mid p(J) \leq p_{\text{min}}, J \in J \} \cup J_{\text{profitable}}$.

Then we guess the critical job, say $J$, in the optimal solution $J^*$. A linear program, denoted by LP, is formulated to assign the cheaper jobs fractionally. The variable $x_i$ is defined as the fraction of job $J_i$ that is assigned to the given flowshop.

$$\max \sum_{i=1}^{\infty} p_i \cdot x_i \quad \text{LP}$$

$$\text{s.t.} \quad \sum_{i=1}^{n} a_i x_i + \sum_{i=s}^{n} b_i x_i \leq 1 \quad \text{(makespan constraint)}$$

$$x_i = 1, \quad J_i \in J_{\text{profitable}} \cup \{J\} \quad \text{(guessed assignments)}$$

$$x_i = 0, \quad J_i \in J \setminus (J' \cup \{J\})$$

$$x_i \in [0,1], \quad J_i \in J' \setminus (J_{\text{profitable}} \cup \{J\})$$

**Lemma 2.** If the guesses for the most profitable job set $J_{\text{profitable}}$ and the critical job $J$ are correct,

1. the linear program LP has a feasible solution, and OPT is upper bounded by the optimal objective value of LP;

2. there is a polynomial time algorithm to obtain a job set from the optimal basic feasible solution to LP such that the makespan is at most 1 and the total profit is at least $(1-\epsilon) \cdot \text{OPT}$.

**Proof.** Suppose $J^*$ is sorted in Johnson’s order. According to Theorem 1, the minimum makespan for $J^*$ can be computed by Eq. (1). By Corollary 1, $\{x_i = 1 \mid J_i \in J^* \} \cup \{x_i = 0 \mid J_i \notin J^*\}$ is a feasible solution to LP. Then the correctness of the first claim follows immediately.
Due to the Rank Lemma for linear programs (Chapter 2.1 in [15]), the single non-trivial constraint of LP implies that at most one \( x_i \) is exactly fractional, i.e., \( x_i \in (0,1) \). Suppose \( x \) is an optimal basic feasible solution to LP. The job set \( \{ J_i \mid x_i = 1, i \in [n] \} \) is chosen as \( \mathcal{J}_{\text{selected}} \).

Let \( \text{OPT}_{\text{LP}} \) be the optimal objective value of LP and \( \text{SOL} \) be the total profit of \( \mathcal{J}_{\text{selected}} \).

Then, we have

\[
\text{OPT}_{\text{LP}} \leq \max_{J \in \mathcal{F} \setminus (\mathcal{J}_{\text{profitable}} \cup \{ J_s \})} \{ p_i \} + \sum_{J \in \mathcal{J}_{\text{selected}}} p_i \\
\leq p_{\text{min}} + \text{SOL} \\
\leq \epsilon \cdot \text{OPT} + \text{SOL},
\]

where the last inequality holds due to the correct guess of \( \mathcal{J}_{\text{profitable}} \).

By the first part of this Lemma,

\[
\text{SOL} \geq \text{OPT}_{\text{LP}} - \epsilon \cdot \text{OPT} \geq \text{OPT} - \epsilon \cdot \text{OPT} = (1 - \epsilon) \cdot \text{OPT}.
\]

This completes the proof for this lemma.

\[\square\]

**Algorithm 1: PTAS for (1,2)-Flowshop-Packing**

**Input:** any constant \( \epsilon \in (0,1) \) and a (1,2)-Flowshop-Packing instance \( \{ \mathcal{F}, \mathcal{J} \} \);

**Output:** a job subset \( \mathcal{J}_{\text{selected}} \subseteq \mathcal{J} \) with the makespan upper bounded by 1;

Let \( \mathcal{C} = \{ \mathcal{J}_{\text{guess}} \mid |\mathcal{J}_{\text{guess}}| \leq \frac{1+\epsilon}{\epsilon}, \mathcal{J}_{\text{guess}} \subseteq \mathcal{J} \} \);

if \( n > \frac{1+\epsilon}{\epsilon} \) then

\[\mathcal{C}_\epsilon = \{ \mathcal{J}_{\text{guess}} \mid |\mathcal{J}_{\text{guess}}| = \frac{1+\epsilon}{\epsilon}, \mathcal{J}_{\text{guess}} \subseteq \mathcal{J} \};\]

else

\[\mathcal{C}_\epsilon = \emptyset;\]

end

for every \( \mathcal{J}_{\text{guess}} \in \mathcal{C}_\epsilon \) do

\[\mathcal{J}_{\text{profitable}} \leftarrow \mathcal{J}_{\text{guess}};\]

Let \( p_{\text{min}} = \min_{J \in \mathcal{J}_{\text{profitable}}} p(J); \)

Let \( \mathcal{J}' = \{ J \mid p(J) \leq p_{\text{min}}, J \in \mathcal{J} \} \cup \mathcal{J}_{\text{profitable}};\)

for every \( J_s \in \mathcal{J}' \) do

Use \( \mathcal{J}_{\text{profitable}}, \mathcal{J}', \) and \( J_s \) to construct LP;

if LP admits a feasible solution then

Let \( x \) be an optimal basic feasible solution to LP;

\[\mathcal{J}_{\text{selected}} \leftarrow \{ J_i \mid x_i = 1 \};\]

\[\mathcal{C} \leftarrow \mathcal{C} \cup \{ \mathcal{J}_{\text{selected}} \};\]

end

end

Let \( \text{profit} = -\infty; \)

for every \( \mathcal{J}_{\text{candidate}} \in \mathcal{C} \) do

Let \( \pi \) be the schedule of \( \mathcal{J}_{\text{candidate}} \) by Johnson’s Algorithm;

if \( p(\mathcal{J}_{\text{candidate}}) > \text{profit} \) and \( \pi \)'s makespan is at most 1 then

\[\mathcal{J}_{\text{selected}} \leftarrow \mathcal{J}_{\text{candidate}} \text{ and } \text{profit} \leftarrow p(\mathcal{J}_{\text{candidate}});\]

end

end

return \( \mathcal{J}_{\text{selected}} \)
Thus, Algorithm 1 is a PTAS. Let \( C \) denote this collection. To consider the case that \( J^* \) contains at most \( \frac{1+\epsilon}{\epsilon} \) jobs, \( C \) is initialized by \( \{ J_{\text{guess}} \mid |J_{\text{guess}}| \leq \frac{1+\epsilon}{\epsilon}, J_{\text{guess}} \subseteq J \} \). For the case \( |J^*| > \frac{1+\epsilon}{\epsilon} \), we exhaust all possible candidates of \( J_{\text{profitable}} \), that is, a job subset of size exactly \( \frac{1+\epsilon}{\epsilon} \). For each candidate of \( J_{\text{profitable}} \), we guess a critical job and use LP to obtain a candidate of \( J_{\text{selected}} \). Finally, among all candidates, we select the one with a feasible schedule and the maximum profit. Note that some candidates in \( C \) may not admit a feasible schedule satisfying the limited makespan of 1. A detailed description of our algorithm is provided in Algorithm 1.

**Theorem 2.** Algorithm 1 is a PTAS for the \((1,2)\)-Flowshop-Packing problem.

**Proof.** Based on the previous analysis, we claim that the optimal solution \( J^* \) is contained in the candidate collection \( C \). Lemma 2 implies an approximation ratio of \( 1 - \epsilon \) for any \( \epsilon \in (0, 1) \).

LP has \( O(n) \) constraints and can be solved in polynomial time via any interior point methods [16]. \( C_\epsilon \) has a cardinality of \( O(n^{(1+\epsilon)/\epsilon}) \). Thus, the first for-loop in Algorithm 1 takes \( poly(n^{1/\epsilon}) \) time. As Johnson’s algorithm has a time complexity of \( O(n \log n) \) and there are \( O(n^{(1+\epsilon)/\epsilon}) \) candidates in \( C \), the second for-loop in Algorithm 1 also takes \( poly(n^{1/\epsilon}) \) time. Thus, Algorithm 1 is a PTAS.

5. PTAS for the \((m,2)\)-Flowshop-Packing problem

In this section, we extend the ideas for the \((1,2)\)-Flowshop-Packing problem to present a PTAS for the general case, i.e., \((m,2)\)-Flowshop-Packing, when \( m \) is a fixed constant.

As there are \( m \) identical flowshops, we not only guess \( \frac{1+\epsilon}{\epsilon} \) most profitable jobs in the optimal job set \( J^* \), still denoted by \( J_{\text{profitable}} \), but also guess how the jobs in \( J_{\text{profitable}} \) distribute among the \( m \) flowshops and the critical job on each flowshop. Then, the cheaper jobs are selected by rounding a basic feasible solution of a linear program, which is more complicated than the one for the \((1,2)\)-Flowshop-Packing problem.

Suppose \( J_{\text{profitable}} \) has been correctly guessed. Let \( J^*_j \) denote the subset of jobs in \( J_{\text{profitable}} \) that are scheduled on the flowshop \( F_j \), \( j \in [m] \). Define the distribution of \( J_{\text{profitable}} \) on the \( m \) flowshops as the tuple \(( J^*_1, J^*_2, \ldots, J^*_m \)).

**Lemma 3.** There are at most \( O((m/\epsilon)^{1/\epsilon}) \) different distributions of \( J_{\text{profitable}} \) on \( m \) flowshops.

**Proof.** Assume only \( k \) flowshops contains jobs from \( J_{\text{profitable}} \). Counting the number of different distributions of \( J_{\text{profitable}} \) on \( m \) flowshops is equal to counting the number of different partitions of \( \frac{1+\epsilon}{\epsilon} \) objects into \( k \) non-empty subsets, which can be estimated by the Stirling partition number [17], denoted by \( S(\frac{1+\epsilon}{\epsilon}, k) \).

Let \( h = \min \{ m, \frac{1+\epsilon}{\epsilon} \} \). We have \( k \leq h \). Considering all possible \( k \) values, the number of different distributions of \( J_{\text{profitable}} \) on \( m \) flowshops is upper bounded as

\[
\sum_{k=1}^{h} \binom{m}{k} S \left( \frac{1+\epsilon}{\epsilon}, k \right) \leq \sum_{k=1}^{h} \binom{m}{k} \left( \frac{1+\epsilon}{\epsilon} \right)^k \left( \frac{1+\epsilon}{\epsilon} \right)^{-k} \\
\leq \frac{h}{2} \cdot (me)^h \cdot \left( \frac{1+\epsilon}{\epsilon} \cdot e \right)^h \cdot h^{\frac{1+\epsilon}{\epsilon}} \\
\leq \frac{1}{2} \cdot h^{2/\epsilon} \cdot (2me^2/\epsilon)^h,
\]

where the first inequality holds due to the bound \( S(n, k) \leq \frac{1}{2} \binom{n}{k} k^{n-k} \) [17]; the second inequality follows from the fact that \( \binom{n}{k} \leq \frac{n^k}{k!} \leq \left( \frac{n}{k} \right)^k \); the last inequality is because \( \epsilon \) is small enough positive number. \( \square \)
Taking the same strategy in Section 4, we define $p_{\text{min}} = \min_{J \in \mathcal{J}^\text{profitable}} p(J)$ and $\mathcal{J}' = \{J \mid p(J) \leq p_{\text{min}}, J \in \mathcal{J}\} \cup \mathcal{J}^\text{profitable}$.

Now we guess the critical job on each flowshop. Suppose $J_{s_j}$ is the critical job on $F_j$ in the optimal solution. To assign cheaper jobs fractionally, a linear program is formulated and we denote it by Multi-LP. The variable $x_{ij}$ is defined as the fraction of job $J_i$ that is assigned to the flowshop $F_j$.

\[
\begin{align*}
\text{max} & \quad \sum_{i \in [n]} \sum_{j \in [m]} p_{ij} \cdot x_{ij} & \quad \text{Multi-LP} \\
n & \quad \sum_{i=1}^{s_j} a_{ij} x_{ij} + \sum_{t=1}^{n} b_{ij} x_{ij} \leq 1, & \quad \forall j \in [m] \quad \text{(makespan constraints)} \\
n & \quad x_{ij} \leq 1, & \quad J_i \in \mathcal{J}' \setminus \left(\mathcal{J}^\text{profitable} \cup \{J_{s_j}, j \in [m]\}\right) \\
n & \quad x_{ij} = 1, & \quad J_i \in \mathcal{J}^\text{profitable} \setminus \{J_{s_j}, j \in [m]\}, j \in [m] \quad \text{(guessed assignments)} \\
n & \quad x_{ij} = 0, & \quad J_i \in \mathcal{J} \setminus \left(\mathcal{J}' \cup \{J_{s_j}, j \in [m]\}\right), j \in [m] \\
n & \quad x_{ij} \geq 0, & \quad J_i \in \mathcal{J} \setminus \left(\mathcal{J}^\text{profitable} \cup \{J_{s_j}, j \in [m]\}\right)
\end{align*}
\]

We introduce a dummy flowshop $F_{m+1}$ and set a sufficiently large makespan limit on $F_{m+1}$, say $a(\mathcal{J}) + b(\mathcal{J})$. Due to the makespan constraint, Multi-LP may leave some jobs in $\mathcal{J}$ unassigned. The main purpose of the dummy flowshop is to (fractionally) assign these unassigned jobs to $F_{m+1}$. We formulate another linear program, denoted by New-Multi-LP, where every job in $\mathcal{J}$ is assigned. Note that the objective of New-Multi-LP does not count the profit of jobs that are assigned to the dummy flowshop $F_{m+1}$.

\[
\begin{align*}
\text{max} & \quad \sum_{i \in [n]} \sum_{j \in [m]} p_{ij} \cdot x_{ij} & \quad \text{New-Multi-LP} \\
n & \quad \sum_{i=1}^{s_j} a_{ij} x_{ij} + \sum_{t=1}^{n} b_{ij} x_{ij} \leq 1, & \quad \forall j \in [m] \\
n & \quad \sum_{i=1}^{s_{m+1}} a_{ij} x_{ij} + \sum_{t=1}^{n} b_{ij} x_{ij} \leq a(\mathcal{J}) + b(\mathcal{J}) \\
n & \quad \sum_{j=[m+1]} x_{ij} = 1, & \quad J_i \in \mathcal{J} \setminus \left(\mathcal{J}^\text{profitable} \cup \{J_{s_j}, j \in [m+1]\}\right) \\
n & \quad x_{ij} = 1, & \quad J_i \in \mathcal{J}^\text{profitable} \setminus \{J_{s_j}, j \in [m+1]\}, j \in [m+1] \\
n & \quad x_{ij} = 0, & \quad J_i \in \mathcal{J} \setminus \left(\mathcal{J}' \cup \{J_{s_j}, j \in [m]\}\right), j \in [m] \\
n & \quad x_{ij} \geq 0, & \quad J_i \in \mathcal{J} \setminus \left(\mathcal{J}^\text{profitable} \cup \{J_{s_j}, j \in [m+1]\}\right)
\end{align*}
\]

Denote $N^\text{unassigned}$ as the number of jobs that are unassigned when constructing New-Multi-LP. Then

\[N^\text{unassigned} = |\mathcal{J} \setminus \left(\mathcal{J}^\text{profitable} \cup \{J_{s_j}, j \in [m+1]\}\right)|.
\]

New-Multi-LP has $N^\text{unassigned} + m + 1$ non-trivial constraints, which are shown as the first three sets of constraints in New-Multi-LP. Clearly, the number of assigned variables $N^\text{unassigned}$, $(m + 1)$ is considerably larger than the number of non-trivial constraints when both $m$ and $\epsilon$ are fixed constants. For any basic feasible solution $x$ to New-Multi-LP, the number of positive variables in $x$ is at most the number of non-trivial constraints.

Denote $N^\text{one}$ as the number of jobs in $\mathcal{J} \setminus \left(\mathcal{J}^\text{profitable} \cup \{J_{s_j}, j \in [m+1]\}\right)$ that are as-
assigned via a variable \( x_{ij} \) with value 1. Let \( N_{\text{frac}} \) denote the remaining job subset of \( \mathcal{J} \setminus (\mathcal{J}_{\text{profitable}} \cup \{ J_j, j \in [m+1] \}) \). Each job in \( N_{\text{frac}} \) is assigned via exactly fractional variables. As the new New-Multi-LP assigns every job in \( \mathcal{J} \setminus (\mathcal{J}_{\text{profitable}} \cup \{ J_j, j \in [m+1] \}) \), we have

\[
N_{\text{one}} + N_{\text{frac}} = N_{\text{unassigned}}.
\]

If \( J_i \) is assigned via exactly fractional variables, there are at least two exactly fractional variables associated with \( J_i \). Therefore, there are at least \( 2 \cdot N_{\text{frac}} \) exactly fractional variables and the total number of positive variables are at least \( 2 \cdot N_{\text{frac}} + N_{\text{one}} \).

To wrap up, we have

\[
N_{\text{unassigned}} + N_{\text{frac}} = N_{\text{one}} + 2 \cdot N_{\text{frac}} \leq N_{\text{unassigned}} + m + 1,
\]

which implies \( N_{\text{frac}} \leq m + 1 \).

**Lemma 4.** If all guesses, including \( \mathcal{J}_{\text{profitable}} \) and \( J_j, j \in [m] \), are correct,

1. the linear program Multi-LP has a feasible solution, and \( \text{OPT} \) is upper bounded by the optimal objective value of LP;

2. there is a polynomial time algorithm to obtain a job set from the optimal basic feasible solution to Multi-LP such that the makespan is at most 1 and the total profit is at least \( (1 - \epsilon \cdot (m + 1)) \text{OPT} \).

**Proof.** The first part of this lemma is obvious by the construction of Multi-LP.

From the definition of New-Multi-LP, we observe that restricting any basic feasible solution of New-Multi-LP to flowshops \( \mathcal{F} = \{ F_1, F_2, \ldots, F_m \} \) results in a basic feasible solution to Multi-LP. In addition, the optimal objective of New-Multi-LP is the same to the optimal objective of Multi-LP.

Suppose \( x \) is an optimal basic feasible solution to Multi-LP. Then \( x \) contains at most \( m + 1 \) fractional variables. We select job as \( \mathcal{J}_{\text{selected}} = \{ J_i \mid x_{ij} = 1, i \in [n] \text{ and } j \in [m] \} \). Let \( \text{OPT}_{\text{Multi-LP}} \) be the optimal objective value of Multi-LP and \( \text{SOL} \) be the total profit of \( \mathcal{J}_{\text{selected}} \). Then, we have

\[
\text{OPT}_{\text{LP}} \leq (m + 1) \cdot \max_{J_i \in \mathcal{J} \setminus (\mathcal{J}_{\text{profitable}} \cup \{ J_j \})} \{ p_i \} + \sum_{J_i \in \mathcal{J}_{\text{selected}}} p_i \leq (m + 1) \cdot p_{\min} + \text{SOL} \leq \epsilon \cdot (m + 1) \cdot \text{OPT} + \text{SOL},
\]

which implies

\[
\text{SOL} \geq (1 - \epsilon \cdot (m + 1)) \cdot \text{OPT}.
\]

Similar to the PTAS for (1,2)-Flowshop-Packing, our PTAS for (m,2)-Flowshop-Packing maintains all candidates, denoted by \( \mathcal{C} \), of \( \mathcal{J}_{\text{selected}} \). For each candidate of \( \mathcal{J}_{\text{profitable}} \), we guess a distribution of \( \mathcal{J}_{\text{profitable}} \) over \( \mathcal{F} \). Then a critical job is guessed on each flowshop, including the dummy flowshop. After solving New-Multi-LP, a candidate of \( \mathcal{J}_{\text{selected}} \) is obtained by restricting its optimal basic feasible solution to \( \mathcal{F} \) and discarding jobs that are assigned fractionally. Finally, we select the most profitable candidate that satisfies the limited makespan of 1. A detailed description of this PTAS is provided in Algorithm 2.

**Theorem 3.** Algorithm 2 is a PTAS for the \((m,2)\)-Flowshop-Packing problem if \( m \) is a fixed constant.
Proof. We claim that the optimal solution $J^*$ is contained in the candidate collection $C$. The approximation ratio $1 - \epsilon$ is implied by Lemma 4.

New-Multi-LP can be solved in $\text{poly}(mn)$ via any interior point methods [10], as it has $O(nm)$ constraints. By Lemma 3, there are at most $O((m/\epsilon)^{1/\epsilon})$ distributions of $J^{\text{profitable}}$. Therefore, the first for-loop in Algorithm 2 takes $\text{poly}(nO(1/\epsilon + m)(m/\epsilon)^{1/\epsilon})$ time. The second for-loop in Algorithm 2 takes $\text{poly}(n^{1/\epsilon})$ time, as $C$ contains $O(n^{(1+\epsilon)/\epsilon})$ candidates and Johnson’s algorithm runs in $O(n \log n)$.

The overall time complexity of Algorithm 2 is $\text{poly}(nO(1/\epsilon + m)(m/\epsilon)^{1/\epsilon})$. This completes the proof of this Theorem. \hfill \qed

---

**Algorithm 2: PTAS for (m,2)-Flowshop-Packing**

**Input:** any constant $\epsilon \in (0,1)$ and a (m,2)-Flowshop-Packing instance $\{F, J\}$

**Output:** a job subset $J^{\text{selected}} \subseteq J$ with the makespan upper bounded by 1;

Let $C = \{J^{\text{guess}} \mid |J^{\text{guess}}| \leq \frac{1+\epsilon}{\epsilon}, J^{\text{guess}} \subseteq J\}$;

if $n > \frac{1}{1+\epsilon}$ then
  $C_\epsilon = \{J^{\text{guess}} \mid |J^{\text{guess}}| = \frac{1+\epsilon}{\epsilon}, J^{\text{guess}} \subseteq J\}$;
else
  $C_\epsilon = \emptyset$;
end

for every $J^{\text{guess}} \in C_\epsilon$ do
  $J^{\text{profitable}} \leftarrow J^{\text{guess}}$;
  Let $p_{\min} = \min_{J \in J^{\text{profitable}}} p(J)$;
  Let $J' = \{J \mid p(J) \leq p_{\min}, J \in J \} \cup J^{\text{profitable}}$;
  for every distribution $(J_1^{\text{profitable}}, J_2^{\text{profitable}}, \ldots, J_m^{\text{profitable}})$ of $J^{\text{profitable}}$ do
    for every combination $(J_{s_1}, J_{s_2}, \ldots, J_{s_{m+1}})$, $J_{s_j} \in J', j \in [m+1]$ do
      Construct New-Multi-LP;
      if New-Multi-LP admits a feasible solution then
        Let $x$ be an optimal basic feasible solution to New-Multi-LP;
        Restrict $x$ to flowshops $F$, still denoted by $x$;
        $J^{\text{selected}} = \{J_i \mid x_{ij} = 1, \ i \in [n] \text{ and } j \in [m]\}$;
        $C \leftarrow C \cup \{J^{\text{selected}}\}$;
      end
    end
  end
end

Let $\text{profit} = -\infty$;

for every $J^{\text{candidate}} \in C$ do
  Let $\pi$ be the schedule of $J^{\text{candidate}}$ by Johnson’s Algorithm;
  if $p(J^{\text{candidate}}) > \text{profit}$ and $\pi's$ makespan is at most 1 then
    $J^{\text{selected}} \leftarrow J^{\text{candidate}}$ and $\text{profit} \leftarrow p(J^{\text{candidate}})$;
  end
end

return $J^{\text{selected}}$
6. Conclusion

We explore an interesting scheduling problem recently introduced by Chen et al. [3], i.e., the scheduling of parallel two-stage flowshops with makespan constraint (or (m,2)-Flowshop-Packing), which generalizes the classic Multiple Knapsack problem. Given a limited makespan requirement, the goal is to select a subset of two-stage jobs and schedule them on multiple flowshops to achieve the maximum profit. All existing approximation algorithms [4, 3] rely on the connection between the Multiple Knapsack problem and the (m, 2)-Flowshop-Packing problem. To design a PTAS for the case in which the number of flowshops is a fixed constant, we utilize the structure of the job sequence under Johnson’s order, and combine guessing techniques and rounding techniques in linear programming. Our PTAS achieves the best possible approximability result as the special case with two flowshops is already strongly NP-hard. Meanwhile, our PTAS gives a firm answer to an open question presented by Chen et al. [3] which asks whether there exists an PTAS for the case where the number \( m \) of flowshops is a fixed constant.

There are several open questions that worth further exploration.

1. Our current PTAS has a large time complexity due to exhaustively guessing the substructure of the optimal solution. Is it possible to design an EPTAS?

2. Though the case with at least two flowshops is strongly NP-hard, whether the case with a single flowshop is strongly NP-hard is unknown. It would be interesting to either prove the strong NP-hardness or designing a FPTAS for the single-flowshop case.

3. When \( m \) is part of the input, Chen et al. [3] presented a \((1/3 – \epsilon)\)-approximation algorithm. It is unknown whether this case is APX-hard. If not, is it possible to design a PTAS or at least an approximation algorithm with ratio better than \(1/3 – \epsilon\)?

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