An optimal partition problem for the localization of eigenfunctions

Guy David | Hassan Pourmohammad

1Université Paris-Saclay, CNRS, Laboratoire de mathématiques d’Orsay, Orsay, France
2Department of Mathematics, Tarbiat Modares University, Tehran, Iran

Abstract
We study the minimizers of a functional on the set of partitions of a domain $\Omega \subset \mathbb{R}^n$ into $N$ subsets $W_j$ of locally finite perimeter in $\Omega$, whose main term is $\sum_{j=1}^N \int_{\Omega \cap \partial W_j} a(x)dH^{n-1}(x)$. Here the positive bounded function $a$ may, for instance, be related to the Landscape function of some Schrödinger operator. We prove the existence of minimizers through the equivalence with a weak formulation, and the local Ahlfors regularity and uniform rectifiability of the boundaries $\Omega \cap \partial W_j$.

MSC 2020
49J45 (primary), 49Q15 (secondary)

Contents
1. INTRODUCTION ..................................... 1303
2. MORE ON THE LOCALIZATION OF WAVES ............. 1306
3. THE WEAK FUNCTIONAL $J_w$ .......................... 1307
4. THE REDUCED BOUNDARY IS AHLFORS REGULAR ........ 1309
5. CLEAN REPRESENTATIVES OF WEAK MINIMIZERS ........ 1318
6. UNIFORM RECTIFIABILITY AND ISOPERIMETRY ......... 1321
7. ALMOST MINIMAL SETS ............................... 1326
8. FURTHER QUESTIONS .................................. 1329
ACKNOWLEDGEMENTS .................................... 1329
REFERENCES ........................................ 1330

© 2022 The Authors. The publishing rights in this article are licensed to University College London under an exclusive licence. Mathematika is published by the London Mathematical Society on behalf of University College London.
1 | INTRODUCTION

The main theme of this paper is the elementary existence and regularity theory for partitions of a domain $\Omega$ that minimize a functional whose main term is the integral of a given function $a$ on the total boundary of the partition; see (1.3).

Its initial motivation comes from the localization of eigenfunctions for Shrödinger operators $\mathcal{L} = -\Delta + \mathcal{V}$ on a domain $\Omega \subset \mathbb{R}^n$, in relation to the so-called landscape function introduced in [12]. The landscape function (sometimes also called torsion function) is the solution $w$ of $\mathcal{L}w = 1$ on $\Omega$, with the Dirichlet condition $w = 0$ on $\mathbb{R}^n \setminus \Omega$, and the main point of [12] is that $w$ often controls the eigenfunctions of $\mathcal{L}$, both in the sense that there is a pointwise inequality of the type $u(x) \leq C_\lambda w(x)$ when $\mathcal{L}u = \lambda u$, but also because in many practical cases $w$ is localized in certain regions of $\Omega$, and the eigenfunctions $u$, with not too high eigenvalues, also turn out to be localized in the same regions.

It seems interesting to find algorithms that, given $w$, find a collection of regions where $w$ is localized and hence it is hoped that the eigenfunctions live too. Of course, it is tempting to do this by minimizing a functional. Most often, in practical calculations, various forms of watershed algorithms have been used. The clear advantage of such methods is that they are often very fast, but one can argue that in some cases the description of valleys for $-w$ is perhaps not optimal.

The issue was taken in [8], where a minimizing process was proposed involving the search for optimal free boundaries, as in the Alt–Caffarelli–Friedman problem [1], and its regularity studied. This gave interesting practical results too, but the functional was not much used for the localization of eigenfunctions since then, because the computations tend to be very long. Here we intend to use a different scheme that uses almost minimal partitions, that is, relies on a functional whose main term measures a weighted version of the total area of the interfaces. This is simpler and more direct (and probably can be computed much faster) than the free boundary problem, but for some reason the authors of [8] were distracted and focused on free boundaries, and forgot about their initial attempt with surface measure. The two approaches have common features, such as the use of many phases (many subdomains in our partitions) and an auxiliary term (here called $G$).

The choice of $a$ and $G$ in relation with the localization of waves will be discussed more in Section 2, but let us now describe the strong form of the (slightly more general) functionals that we intend to study in this paper. We are given a domain $\Omega \subset \mathbb{R}^n$, and an integer $N \geq 1$ (a bound for the number of pieces that we want). We want to use a functional $F$ (defined soon) to decompose $\Omega$ into disjoint subregions $W_i, 1 \leq i \leq N$. Our set of acceptable competitors will be the class $\mathcal{F} = \mathcal{F}(\Omega)$ of $N$-tuples $W = (W_1, W_2, \ldots, W_N)$, where the $W_i, 1 \leq i \leq N$, are Borel subsets of $\Omega$ such that

$$\Omega = \bigcup_{i=1}^N W_i \quad \text{and} \quad W_i \cap W_j = \emptyset \quad \text{for} \quad i \neq j. \quad (1.1)$$

That is, we consider partitions of $\Omega$ into $N$ Borel subsets, but we allow some of them to be empty. (We will systematically use bold letters to denote $N$-tuples.) Then we want to minimize on $\mathcal{F}$ the functional $J = J_s$ defined by

$$J_s(W) = F_s(W) + G(W), \quad (1.2)$$

where the main term $F_s$ involves the total weighted surface measure of the interfaces, and $G$ can be seen as a more stable bulk integral whose main goal may be to prevent the minimization by
trivial solutions. For the definition of $F_s$, we give ourselves a positive function $a$ on $\Omega$, and set

$$F_s(W) = \sum_{i=1}^{N} \int_{\Omega \cap \partial W_i} a(x) dH^{n-1}(x),$$

(1.3)

where $H^{n-1}$ denotes the Hausdorff measure of co-dimension 1 (think about surface measure) and $\partial W_i$ is (usual) boundary of $W_i$. We could also set

$$\partial(W) = \Omega \cap \bigcup_{i=1}^{N} \partial W_i$$

(1.4)

and use

$$\tilde{F}_s(W) = \int_{\partial(W)} a(x) dH^{n-1}(x);$$

(1.5)

as we shall see near Corollary 5.2, this is roughly equivalent.

Concerning the bulk part $G(W)$, we shall explain in Section 2 why some term like this is needed to avoid too trivial solutions, but the main properties that we need for our existence and regularity results are that that the variations of $G$ are smaller than the expected variations of $F_s$. We will settle on the following Hölder regularity in terms of the $W_j$ (in the $L^1$ norm): we will assume that there exists an exponent $\alpha \in (\frac{n-1}{n}, 1]$ and a constant $C \geq 0$ such that

$$|G(W) - G(W')| \leq C \sum_{i=1}^{N} |W_i \triangle W'_i|^{\alpha},$$

(1.6)

where $W = (W_1, \ldots, W_N)$ and $W' = (W'_1, \ldots, W'_N)$, we denote by $A \triangle B$ the symmetric difference $(A \setminus B) \cup (B \setminus A)$, and $|A|$ stands for the Lebesgue measure of the set $A$.

The main point of (1.6) is even weaker than this: we want to make sure that when $W$ and $W'$ are the same except on some ball of radius $r$, then $|G(W) - G(W')| \leq C r^\beta$ for some $\beta > n - 1$, so that minimizers for $J_s$ are what we shall call quasi- or almost minimizers for $F_s$ alone, which is enough for our regularity results.

The strong functionals $J_s$ and $\tilde{J}_s$ are simple to define, but it is well known that existence results are then hard to establish directly, and that for this it is better to use weak functionals, where the partitions are defined in terms of sets of finite perimeter (Caccioppoli sets), and the functional uses BV (bounded variation) norms. So, we shall introduce a related weak functional $J_w$, prove existence results for $J_w$ (see Section 3), and later on prove that this functional is equivalent to our initial strong functionals, in the sense that modulo a little bit of cleaning for the minimizers of $J_w$, the weak and strong functionals have the same minimizers. We shall do this in Section 5, after we prove the basic (but very useful) Ahlfors regularity results for the boundary associated to minimizers of $J_w$ (see Section 4).

After this, we will be allowed to use the equivalence of the weak and strong functionals and discuss their regularity equivalently in either setting.

Returning to the existence result (Theorem 3.1), we will get it under the assumptions that $\Omega$ is bounded, $a$ is continuous and positive on $\Omega$, and the bulk term $G$ is bounded and continuous for the $L^1$-distance of sets (see (3.4)).
Then the main estimate is probably the local Ahlfors regularity of the boundaries of minimizing partitions. Think about the strong functional to simplify the discussion, but the properties are proved first for the minimizers of $J_w$. We will only prove local estimates in $\Omega$ (so as to get more flexibility if needed and not worry about the regularity of $\Omega$ or uniform estimates on $a$), and assume the Hölder continuity of the bulk term $G$ (as in (1.6); see the main assumption (3.4)), and local lower and upper bounds on $a$; see (4.7). Then we will get good local Ahlfors regularity bounds (4.8) on the total (reduced) boundary (the union of the (reduced) boundaries of the $W_i$), that depend only on the parameters at hand, but not the number $N$ of pieces. See Theorem 4.2. We shall also prove Ahlfors regularity bounds on the individual boundaries of the $W_i$, but so far with bounds that depend on $N$; see Theorem 4.4.

The equivalence of weak and strong functionals will be proved in Section 5, after we describe how to clean a minimizer $W \in F_w$ to replace the $W_i$ with equivalent open sets, whose boundaries $\partial W_i$ are contained, modulo an $H^{n-1}$-negligible set, in the corresponding reduced boundaries $\partial^* W_i$.

Section 6 contains the next expected step, where we prove that the clean boundary $\partial(W)$ of a minimizer $W$ is locally uniformly rectifiable, and even satisfies S. Semmes’ Condition B; the same is even true for the individual boundaries $\partial^* W_i$ of the (equivalent open) pieces, but with an estimate that depends on $N$. See Theorem 6.1. With a little more work, we show that the $W_i$ have a nice shape, in the sense that some local isoperimetric inequality is satisfied in $W_i$. See Theorem 6.2, and the discussion that follows on the fact that this means a local John estimate (on the existence of thick curves that allow to escape from a point of $W_i$).

In Section 7, we check that if in addition $a$ is assumed to be (locally) Hölder continuous, the clean boundary $\partial(W)$ of a minimizer is a local almost minimal set, as in [5, 20]. This allows one to use the difficult regularity results obtained for such sets, and in particular, in dimension $n = 3$, the beautiful local description of the $W_i$ and $\partial(W)$ of [20], where $\partial(W)$ is shown to be $C^{1+\varepsilon}$-equivalent to one of the three minimal cones that show up in soap films.

We conclude the paper in Section 8 with a short list of open questions.

Functionals like $F_s$ and $F_w$ have been widely studied, and we cannot give a full account here. When $N = 2$ and we consider a set $W$ and its complement in $\Omega$, sets $W$ that minimize $F_w$ with a given volume $|W|$ are called isoperimetric, and have been studied for a long time.

See, for instance, [6], or the recent related survey [16]. Here we avoid one of the delicate issues, the volume constraint (treated in [14]), by using a weak volume constraint coming from the $G$-term. Even with $N$ large, the idea of studying minimal or almost minimal partitions is old; see, for instance, [7, 15] in different areas, and recall that we shall check that the boundaries of our minimizers are almost minimal sets in the sense of [5, 20].

Also $F_s$ and $F_w$ were used in [10] (but with only two pieces $W_j$), with similar uniform rectifiability results, to find big pieces of uniformly rectifiable sets inside sets that satisfy a topological condition and a conflicting upper bound on Hausdorff measure. And in [17], functionals like $F_w$ were studied, but more subtle because the price of the interface between $W_i$ and $W_j$ comes from functions $a_{i,j}(x)$ that depend on the pair $(i, j)$. In this more complicated case, the local regularity results on the individual $\partial W_i$ are still unknown, even when $N = 4$.

The authors want to thank Gian Paolo Leonardi for interesting discussions on [17] and the related problem of infiltration, and the referee for a careful reading and useful suggestions.
2 | MORE ON THE LOCALIZATION OF WAVES

In this section, we justify the idea of using a functional like \( J_s \) above to decompose a domain \( \Omega \) into regions where the eigenfunctions of Shrödinger operators operator \( \mathcal{L} = -\Delta + V \) will tend to be supported. We use the fact that these eigenfunctions are dominated by the landscape function \( w \), that is, the solution \( w \) of \( \mathcal{L}w = 1 \) on \( \Omega \), with the Dirichlet condition \( w = 0 \) on the boundary (see [2, 3]), and thus try to decompose \( \Omega \) into nice regions \( W_i \) where \( w \) is large, or equivalently that look like valleys for the effective potential \( \frac{1}{w} \). The paper [8] contains a description of one of the ways, apparently indirect, to find such a decomposition with the help of the free boundary problem. Here we propose a more classical and simpler approach, where we try to obtain that the boundaries \( \partial W_i \) are both rather short and tend to pass through the places where \( w \) is small by forcing the decomposition to minimize a functional \( J_s \) whose main term \( F_s(W) = \sum_{i=1}^{N} \int_{\Omega \cap \partial W_i} a(x) dH^{n-1}(x) \) (as in (1.3)), where \( a \) is a continuous function that is small when \( w \) is small. For instance, we could take \( a(x) = \delta + w(x) \), where \( w \) is the landscape function (see Section 1 for the definition), and \( \delta > 0 \) is a positive constant (to avoid degeneracy) but we did not test options numerically and other choices could perform better. The reason for adding a small constant \( \delta > 0 \) is that \( w \) is positive on \( \Omega \), but vanishes on the boundary because of its definition with a Dirichlet boundary condition. We usually do not want the region near \( \partial \Omega \) to play a special role in the computations, so it seems reasonable not to look for trouble by allowing \( a \) to be too small (we will see that our regularity estimates may deteriorate where \( a \) is too small). On the other hand, the standard regularity results for elliptic operators say that \( w \) is Hölder-continuous, and requiring \( a \) to be Hölder continuous will be enough for us, so we do not need to do special efforts here.

If we just minimize \( F_s \), something stupid happens: the minimal partition is just the trivial one where for instance \( W_1 = \Omega \) and all the other \( W_i \) are empty, so that all the interior boundaries \( \partial W_i \cap \Omega \) are empty. This disturbed the authors of [8] for some time, until they realized that it is easy to add another piece of functional \( G(W) \) that prevents this, by favoring partitions \( W \) for which the \( W_i \) have roughly equal volumes. So, for instance, we could take

\[
G(W) = G(|W_1|, \ldots, |W_N|) = \sum_{j=1}^{N} h(|W_j|),
\]

where \( h \) is a nice function that tends to be convex. This is what was added (for instance) to the free boundary part of the functional in [8]. We could also use the function \( w \) itself to replace the volumes \( |W_i| \) in (2.1) with some weighted integrals like \( \int_{W_i} q(w(x)) dx \), for some carefully chosen function \( q \). We shall not try to optimize such choices here; let us just observe that it is easy to ensure that they satisfy our mild estimates on \( G \). As far as the main results of this paper are concerned, our assumptions on \( G \) are sufficiently weak to cover most reasonable choices (such as nice combinations of integrals like \( \int_{W_i} b_i \), with given functions \( b_i \) in \( L^p \)-spaces); we simply selected assumptions on \( G \) that make our minimizers almost minimizers for \( F_w \) or \( F_s \).

Generally speaking, we did not do experiments and we shall not try to optimize the various choices in the definition of \( J_s \), but let us observe that a nice possibility is to also allow a special region \( W_0 \) in the partition, that we could call the black region, and where in fact \( w \) is quite small and we expect the eigenfunctions to be small too. This region could be treated differently than the other ones, typically by replacing the contribution \( \int_{\Omega \cap \partial W_0} a(x) dH^{n-1}(x) \) with a smaller one like \( \delta H^{n-1}(\Omega \cap \partial W_0) \) (we still want the boundary to be nice, so we put a little bit of surface measure...
in the functional anyway, but maybe this is not even needed because \( \Omega \cap \partial W_0 \) will contribute indirectly because it is covered by the other \( \partial W_j \). Such a black region \( W_0 \) appeared naturally in [8], typically as the region with the smallest volume, and the functional did not allow the authors to get the same nondegeneracy properties for \( W_0 \) as for the other regions. For instance, in low dimensions all the boundaries of the \( W_i \) are smooth, except for \( W_0 \) which just occupies the rest of the domain. In the case of localized waves, fortunately the eigenfunctions seem not to like to live in \( W_0 \), which turns out to be a nice feature of the free boundary functional of [8]. We could try to replicate this artificially with the minimal partition model here.

We refer the reader to [8, section 2] for a more detailed description of our motivations in regard to the localization problem, and the role of \( G(W) \).

3 \ | \ THE WEAK FUNCTIONAL \( J_w \)

We now introduce the weak form of our functionals \( F_w \) and \( J_w \). We consider a fixed bounded domain \( \Omega \subset \mathbb{R}^n \), and call \( \mathcal{P}(\Omega) \) the set of Borel subsets \( W \subset \Omega \) that have a finite perimeter in \( \Omega \). This means that the Borel function \( 1_W \) (the characteristic function of \( W \)) lies in \( BV(\Omega) \), that is, has bounded variation in \( \Omega \). Or in other words, the vector-valued distribution \( \nabla 1_W \) is a finite measure (in \( \Omega \); we do not look at what happens on \( \partial \Omega \)). We can write this measure as \( \nabla 1_W = v d \mu_W \), where \( v \) is a Borel vector valued function and \( \mu_W \) is a finite positive Borel measure on \( \Omega \), often denoted by \( |D1_W| \) and called the total variation measure of the (distribution) derivative \( D1_W \).

For any open set \( U \subset \Omega \), we shall denote by

\[
\text{Per}(W, U) = \mu_W(U) = \int_U |D1_W| \tag{3.1}
\]

the perimeter of \( W \) in \( U \). For this and other information on \( BV \) functions and Caccioppoli sets, we refer to [4] or [13].

Since this will not cost us much, we shall also work with the set \( \mathcal{P}_{loc}(\Omega) \) of Borel sets \( W \subset \Omega \) such that the restriction of \( W \) to any open set \( U \subset \subset \Omega \) (i.e., whose closure in \( \mathbb{R}^n \) is a compact subset of \( \Omega \)) lies in \( \mathcal{P}(U) \). Those are also the sets \( W \) such that \( \nabla 1_W \) is a locally finite measure on \( \Omega \); we can keep the same notation for \( \mu_W \) and its description, even though \( \mu_W \) is no longer a finite measure.

Let \( N \geq 1 \) be given. Denote by \( \mathcal{F}_w \) the class \( N \)-tuples \( W = (W_1, ..., W_N) \), where each \( W_i \), \( 1 \leq i \leq N \), is a set of locally finite perimeter in \( \Omega \), and in addition

\[
1_W = \sum_{i=1}^N 1_{W_i}. \tag{3.2}
\]

We write the fact that the \( W_i \) form a partition of \( \Omega \) this way, to insist on the fact that now we shall identify two subsets of \( \Omega \) that differ only by a set of measure 0. That is, \( \mathcal{F}_w \) is in fact an equivalence class modulo negligible sets. Our functionals \( F_w \) and \( J_w \) will be defined on \( \mathcal{F}_w \), which means in particular that \( J_w(W) = J_w(W') \) when \( W = W' \) modulo sets of Lebesgue measure 0; this was not the case for \( J_s \) and \( F_s \).

We are now ready to define our functionals \( F_w \) and \( J_w \) on \( \mathcal{F}_w \). Let \( a : \Omega \to (0, +\infty) \) be a positive function on \( \Omega \). For \( W \in \mathcal{F}_w \), we systematically set \( W = (W_1, ..., W_N) \), and use the positive (locally
finite) measure $\mu_{W_i} = |D1_{W_i}|$ as above. Then set

$$F_w(W) = \sum_{i=1}^{N} \int_{\Omega} a(x) d\mu_{W_i}(x)$$  \hspace{1cm} (3.3)$$

for $W \in F_w$; note that $F_w(W)$ may be infinite, but it is well defined.

As for $G$, for this section we shall simply assume that it is defined on $F_w$ and continuous for the $L^1$ distance. That is, set

$$\text{dist}(W, W') = \sum_{i=1}^{N} |W_i \triangle W'_i|,$$  \hspace{1cm} (3.4)$$

where $W = (W_1, ..., W_N)$, $W' = (W'_1, ..., W'_N)$, and we let

$$W_i \triangle W'_i = (W_i \setminus W'_i) \cup (W'_i \setminus W_i);$$  \hspace{1cm} (3.5)$$

we only require that for $W \in F_w$,

$$\lim_{k \to +\infty} G(W_k) = G(W)$$  \hspace{1cm} (3.6)$$

when $\{W_k\}$ is a sequence in $F_w$ such that $\lim_{k \to +\infty} \text{dist}(W_k, W) = 0$. Finally, we set as expected

$$J_w(W) = F_w(W) + G(W) \text{ for } W \in F_w(\Omega).$$  \hspace{1cm} (3.7)$$

**Theorem 3.1.** Let $\Omega$, $a$, $G$, and $J_w$ be as above. Assume that $\Omega$ is bounded, that $a$ is continuous and $a(x) > 0$ on $\Omega$, and that $G$ is bounded on $F_w$ and continuous for the distance of (3.4). Then we can find $W_0 \in F_w(\Omega)$ such that

$$J_w(W_0) \leq J_w(W) \text{ for } W \in F_w(\Omega).$$  \hspace{1cm} (3.8)$$

This will be a standard application of the compactness properties of $BV$ functions. We need the continuity of $a$ here (or at least its lower semi-continuity) because we want $F_w$ to be lower semi-continuous.

Let $\Omega$, $a$, $G$, and $J_w$ be as in the statement, and set $m = \inf_{W \in F_w} J_w(W)$; note that $m \leq J_w(W_{00}) = G(W_{00}) < +\infty$, where $W_{00} = (\Omega, \emptyset, ..., \emptyset)$ and because $F_w(W_{00}) = 0$. Let $\{W_k\}$ be a minimizing sequence in $F_w$. We assumed that $G$ is bounded because we do not want any useless complication; since $\Omega$ is bounded, this would easily follow if we required $G$ to be uniformly continuous for the distance of (3.4), for instance. Because of this, we can find $M$ such that

$$-M \leq G(W) \leq M \text{ for } W \in F_w,$$

and now for $k$ large,

$$F_w(W_k) \leq J_w(W_k) + M \leq m + 1 + M \leq J_w(W_{00}) + 1 + M \leq 2M + 1,$$  \hspace{1cm} (3.9)$$

where $W_{00} = (\Omega, \emptyset, ..., \emptyset)$ is the trivial competitor with no boundaries. Thus, we have a control on the boundaries. Write $W_k = (W_{1,k}, ..., W_{N,k})$.

For each ball $B \subset \Omega$ such that $2B \subset \Omega$, the continuity of $a$ gives a constant $\delta_B > 0$ such that

$$a(x) \geq \delta_B \text{ for } x \in B.$$  \hspace{1cm} (3.10)$$
Then for $k$ large,
\[ \sum_{i=1}^{N} \text{Per}(W_{i,k}; B) \leq \left( \inf_{B} a \right)^{-1} \sum_{i=1}^{N} \int_{B} a(x) d\mu_{W_{i,k}}(x) \]
\[ \leq \delta_B^{-1} F_{W}(W_k) \leq \delta_B^{-1}(2M + 1). \] (3.11)

This means the functions $1_{W_{i,k}}$ are a bounded family in $BV(B)$. These functions are also all bounded by 1 pointwise, and by a standard consequence of the Poincaré inequality, they form a relatively compact set in $L^1(B)$ (for the norm). Because of this, we can extract a subsequence, that we still denote by $\{W_k\}$, such that for every ball $B$ as above, functions $1_{W_{i,k}}$ converge to a limit $g_i$ in $L^1(B)$. In addition, we can even find a subsequence that converges pointwise, the limit $g_i$ does not depend on $B$, it is the characteristic function of some $W_i \subset \Omega$, and also $\sum_i 1_{W_i} = 1_\Omega$ almost everywhere.

Next we use the lower semi-continuity of the $BV$ norm, which says that for each ball $B$ as above and each $i$,
\[ \text{Per}(W_i; B) \leq \liminf_{k \to +\infty} \text{Per}(W_{i,k}; B). \]
In particular, $W_i \in P_{loc}(\Omega)$ and hence $W \in \mathcal{F}_w$. But also, since $a$ is continuous (lower semi-continuous would have been enough here), we also get that
\[ \int_{B} a(x) d\mu_{W_i}(x) \leq \liminf_{k \to +\infty} \int_{B} a(x) d\mu_{W_{i,k}}(x). \] (3.12)

This is also true, for the same reason, when we replace $B$ by any open set which is compactly contained in $\Omega$, and, by taking an increasing sequence of open sets that exhausts $\Omega$, with $B$ replaced by $\Omega$.

We still need to prove that $W$ is a minimizer, that is, that $J_{w}(W) \leq m$. But we already know from (3.12) that $F_{W}(W) \leq \liminf_{k \to +\infty} F_{W}(W_k)$, and since $\Omega$ is bounded, the fact that $W_{i,k}$ converges in $L^1(K)$ to $W_i$ for each compact set $K$ and each index $i$ implies that $\text{dist}(W_k, W)$ tends to 0 and, by assumption, $G(W) = \lim_{k \to +\infty} G(W_k)$. We sum the two estimates and get that $J_{w}(W) \leq \liminf_{k \to +\infty} J_{w}(W_k) \leq m$, as needed. \(\square\)

## 4 | THE REDUCED BOUNDARY IS AHLFORS REGULAR

In this section, we introduce the reduced boundaries associated to an acceptable partition $W = (W_1, ..., W_N) \in \mathcal{F}_w$, and prove Ahlfors regularity results for them when $W$ minimizes $J_w$. We start with the definition and basic properties of the reduced boundaries.

Each $W_i$ is a set of locally finite perimeter in $\Omega$, so it has a reduced boundary, that we shall denote by $\partial^* W_i$ or simply $\Gamma_i^*$, and which is a rectifiable subset of $\Omega$ (we still do not look at what happens on $\partial \Omega$). We refer to [4, 13] for general information on reduced boundaries, but let us recall the most important features. First of all, the total variation measure $\mu_{W_i} = |D1_{W_i}|$ is given by
\[ \mu_{W_i} = \mathcal{H}^{n-1}_{\Gamma_i^*}, \] (4.1)
where $\mathcal{H}^{n-1}_{\Gamma_i^*}$ denotes the restriction to $\Gamma_i^*$ of the Hausdorff measure. More precisely, we know that for $\mathcal{H}^{n-1}$-almost every $x \in \Gamma_i^*$, $\Gamma_i^*$ has an approximate tangent plane $P_i(x)$ at $x$, and there is a
(measurable) way to choose a unit normal vector $n_i(x)$ (in fact, pointing inwards) so that
\[ \nabla 1_{W_i} = n_i(x) H^{n-1}_{\Gamma_i^*} = n_i(x) \mu_{W_i}, \]  
where the gradient is in fact a vector valued distribution; we happily mix gradients and differentials here.

By definition of $\Gamma_i^*$, we have a nice asymptotic description of $W_i$, as being close to a half space bounded by $P(x)$, and more precisely
\[
\lim_{r \to 0} r^{-n-1} \left| \left\{ y \in W_i \cap B(x, r); \langle y - x, n(x) \rangle \geq 0 \right\} \right| = 0,
\]
so that in particular $W_i$ and its complement both have Lebesgue density $1/2$ at $x$. This information will be useful when we merge two sets $W_i$ locally, and need to compute the effect on the $\Gamma_i^*$.

The $\Gamma_i^*$ are our analogues of the $\partial W_i$ for the strong functional, and their union
\[ \Gamma^* = \partial^*(W) = \bigcup_{i \in I} \Gamma_i^* \]  
will be the first important object of study. Before we state our first Ahlfors regularity result, let us say a bit more on the structure of $\Gamma^*$ and the $\Gamma_i^*$.

**Lemma 4.1.** Let $W \in F_w$ be given. For $H^{n-1}$-almost every $x \in \Gamma^*$, $x$ lies in exactly two of the sets $\Gamma_i^*$, $1 \leq i \leq N$. Consequently, the functional $F_w$ of (3.3) is also given by
\[ F_w(W) = 2 \int_{\Gamma^*} a(x) dH^{n-1}(x). \]  

Indeed, it is classical (see [13]) that the reduced boundary $\Gamma_i^*$ coincides, modulo a set of vanishing $H^{n-1}$-measure, with the measure-theoretic boundary of $W_i$ (in $\Omega$), which can defined, for instance, as the set $\Gamma_i^d$ of points of $\Omega$ where both $W_i$ and its complement have a positive upper Lebesgue density; the main ingredient for this is the fact that if $x \in \Gamma_i^d$, the Poincaré inequality implies that the lower density of $\mu_{W_i}$ at $x$ is positive. Now if $x \in \Gamma_i^*$, the definition says that the density of $W_i$ at $x$ is precisely $1/2$, which means that we can find $j \neq i$ such that $x \in \Gamma_j^d$, hence, $H^{n-1}$-almost surely, $x \in \Gamma_j^*$. The density at $x$ of both sets $W_i$ and $W_j$ is $1/2$ (by (4.3)), and so $x$ does not lie in any other $\Gamma_k^d$ or $\Gamma_k^*$. So, almost every $x \in \Gamma^*$ lies in exactly two sets $\Gamma_i^*$, and now (4.5) is the same as (3.3).

We now state our main Ahlfors regularity estimate.

**Theorem 4.2.** Let $\Omega, a, G, \text{ and } J_w$ be as above. Assume that $\Omega$ is bounded, and that $G$ is Hölder continuous on $F_w$ for some exponent $\alpha \in (\frac{n-1}{n}, 1]$ (and for the distance of (3.4)), which means that there exists $C_\alpha \geq 0$ such that
\[ |G(W) - G(W')| \leq C_\alpha \text{ dist}(W, W')^\alpha \textrm{ for } W, W' \in F_w, \]  
(4.6)
as in (1.6). Also let $\Omega' \subset \Omega$ be open, and assume that we can find $\delta > 0$ such that

$$\delta \leq a(x) \leq 1 \text{ for } x \in \Omega'.$$  \hspace{1cm} (4.7)

Finally, suppose that $W \in P_w(\Omega)$ minimizes $J_w$ in the class $P_w(\Omega)$. Then there is a constant $C_{ar} \geq 1$, which depends only on $n, \delta, \alpha$, and $C_\alpha$, such that for $x \in \Omega' \cap \Gamma^*$ and $0 < r \leq \min(1, \text{dist}(x, \partial \Omega'))$,

$$C_{ar}^{-1} r^{n-1} \leq H^{n-1}(\Gamma^* \cap B(x, r)) \leq C_{ar} r^{n-1}. \hspace{1cm} (4.8)$$

We are mostly interested in $\Omega' = \Omega$, but we want to allow the case when $a$ only satisfies (4.7) locally. The assumption that $a(x) \leq 1$ is essentially a renormalization (we could also let $a$ tend to $+\infty$ in some places near $\partial \Omega$, but then we could apply the theorem to a slightly different functional). Similarly, we take $r \leq 1$ to be able to compare the two pieces of the functional that have different homogeneities and get a constant that does not depend on $r$ (or $W$ as long as it is a minimizer). We do not need $a$ to be continuous here (but then the existence may fail).

We shall see later that (4.8) is important, first because it is the pillar of the comparison between the strong and weak functional, but also because its proof is the main initial ingredient for our other regularity results. Later in this section, we will prove a local Ahlfors regularity estimate for the $\Gamma_i^*$ individually, (and even later look for more precise regularity results for the $\Gamma_i^*$), but the constants will depend on $N$.

The proof below follows the same path as classical results in similar settings; see, for instance, [10, 17]. We will see that somewhat weaker minimality properties of $W$ (of almost- or quasi-minimality) are enough for the conclusion, which is why we will try now to single out the main features of the proof.

We intend to test the minimality of $W$ by constructing competitors $X \in P_w(\Omega)$, which coincide with $W$ outside of a given ball $B$ such that $\overline{B} \subset \Omega'$, and which will be obtained by pouring some sets $B \cap W_i$ into other sets $W_{\ell}$. Set $I = \{1, 2, \ldots, N\}$; this will be more convenient because we often want to cut $I$ into subsets. Then let $B = B(x, r) \subset \Omega'$ be given, and also choose a proper subset $I_0$ of $I$ and, for each $i \in I_0$, a target index $\ell(i) \in I_1 := I \setminus I_0$. We want to pour each $W_i \cap B, i \in I_0$, into the target piece $W_{\ell(i)}$, and more precisely we define a new competitor $X = (X_1, \ldots, X_N)$ by

$$X_i = W_i \setminus B \text{ for } i \in I_0$$ \hspace{1cm} (4.9)

and

$$X_{\ell} = W_{\ell} \cup \left( \bigcup_{i \in I_0, \ell = \ell(i)} X_i \cap B \right) \text{ for } \ell \in I_1. \hspace{1cm} (4.10)$$

Note that the $X_j$ also form an almost-everywhere partition of $\Omega$, like the $W_i$, and $X \in P_w$ because we only moved the sets $B \cap W_i$ from one component to another one, and it is known that finite unions or intersections of sets of finite perimeters have the same properties. We will need to check what happens to the various pieces of the reduced boundaries $\Gamma_i^*$.

We start with a description of the new total reduced boundary $\partial^*(X)$ associated to $X$ in $B$. We start with its restriction to (the interior of) $B$. We are mostly interested in the case when $x \in \Gamma_i^* \cap \Gamma_j^*$ disappears from $\Gamma^*$, that is, no longer lies in any $\partial^* X_k$, and this happens (modulo a $H^{n-1}$-negligible set of exceptions) when $i \in I_0$ and $j = \ell(i)$, or symmetrically when $j \in I_0$ and $i = \ell(j)$,
or when both $i$ and $j$ lie in $I_0$, and $\ell(i) = \ell(j)$. No new point of $\partial^s(X) = \bigcup_{k \in I} \partial^s X_k$ appears in $B$, that is, $\partial^s(X) \cap B \subset \partial^s \cap B$, so, modulo a set of vanishing $H^{n-1}$-measure,

$$
\partial^s(X \cap B) \subset \Gamma^s \cap B \setminus \left( \bigcup_{i \in I_0} \Gamma^n \cap \Gamma^s_{\ell(i)} \right) \cup \bigcup_{(i,j) \in I_0^2; j \neq i \text{ and } \ell(i) = \ell(j)} \Gamma^n \cap \Gamma^s_j.
$$

(4.11)

The other inclusion also holds (modulo a negligible set), but we do not need it so we leave its proof.

On $\Omega \setminus \overline{B}$, the two sets $\Gamma^s = \partial^s(W)$ and $\partial^s(X)$ coincide (because we did not change anything in this open set), so we are left with the set $\partial^s(X) \cap \partial B$ to analyze. For this it will be easier to assume that the following additional condition on $B$ is satisfied: for each $i \in I$,

$$
H^{n-1}\text{-almost every point of } W_i \cap \partial B(x,r) \text{ is a Lebesgue density point for } W_i \text{ (in } \Omega). \quad (4.12)
$$

For this property, we assume that we have chosen a representative $W_i$ for each $W_i$, so that $\sum_i 1_{W_i} = 1_\Omega$; then (4.12) makes sense. The set of radii $r > 0$ for which (4.12) holds may depend on our representative, but anyway, for each choice of representatives $W_i$ and each choice of $x$, the set of $r \in (0, \mathrm{dist}(x,\partial \Omega))$ for which (4.12) fails is negligible, by Fubini and because almost every point of $W_i$ is a Lebesgue density point for $W_i$.

Return to $\Gamma^s$ and $\partial^s(X)$. Let $r$ be such that (4.12) holds. By assumption, $H^{n-1}(\Gamma^s \cap \partial B) = 0$ (because the points of $\Gamma^s_i$ are points of density $1/2$ for $W_i$, not Lebesgue points), but of course our cutting procedure may introduce new boundaries for the $X_i$ on $\partial B$. In fact, for $x \in \partial B$ such that $x \in W_i$ and $x$ is a density point of $W_i$, this happens if and only if $i \in I_0$, and then $x \in \partial^s(X_i) \cap \partial^s(\ell(i))$. That is, modulo a $H^{n-1}$-negligible set,

$$
\Gamma^s \cap \partial B = \emptyset \text{ and } \partial^s(X \cap \partial B) = \bigcup_{i \in I_0} W_i \cap \partial B,
$$

(4.13)

and more precisely

$$
\partial^s(X_i) \cap \partial B = W_i \cap \partial B \quad \text{for } i \in I_0
$$

(4.14)

and

$$
\partial^s(X_{\ell'}) \cap \partial B = \bigcup_{i \in I_0; \ell(i) = \ell'} W_i \cap \partial B \quad \text{for } \ell' \in I_1.
$$

(4.15)

We shall return to this when we compare $F_w(W)$ and $F_w(X)$, but let us first deal with the $G$-terms and compare $G(W)$ with $G(X)$. Observe that since $W$ and $X$ coincide on the complement of $B$, (3.4) yields

$$
\mathrm{dist}(W,X) = \sum_{i=1}^N |W_i \Delta X_i| \leq \sum_{i=1}^N (|W_i \cap B| + |X_i \cap B|) \leq 2|B| \leq C r^n,
$$

(4.16)

and by (4.3)

$$
|G(X) - G(W)| \leq C_\alpha \mathrm{dist}(W,X)^{\alpha} \leq C_\alpha r^{\alpha n}.
$$

(4.17)
Since $W$ is assumed to be a minimizer,

$$F_w(W) = J_w(W) - G(W) \leq J_w(X) - G(W)$$

$$= F_w(X) + G(X) - G(W) \leq F_w(X) + C^\alpha C_\alpha r^{\alpha n}. \quad (4.18)$$

Let us interpret this as a local almost minimality property.

**Definition 4.3.** Let $\gamma > 0$ and the constant $C_\gamma \geq 0$ be given. We say that $W \in F_w(\Omega)$ is a local almost minimizer for $J_w$, associated to the gauge function $h(r) = C_\gamma r^{\alpha n-1}$, when for each ball $B = B(x, r) \subset \Omega$, with $r \leq 1$, and each $X \in F_w(\Omega)$ that coincides with $X$ outside of $B$,

$$F_w(W) \leq F_w(X) + C_\gamma r^{\gamma r^{\alpha n-1}}. \quad (4.19)$$

We picked $\alpha > \frac{n-1}{n}$ precisely to make sure that $\gamma = \alpha n - (n-1) > 0$, so we just establishes in (4.18) that $W$ is a local almost minimizer for $J_w$, associated to the gauge function $h(r) = C_\gamma r^{\alpha n-1}$, with $C_\gamma = C^\alpha C_\alpha$. This is the only minimizing property that we need for Theorem 4.2 (and we shall no longer need $G$).

Next we compare $F_w(W)$ and $F_w(X)$, and for this the only feature of $F_w$ that we need is the fact that $\delta \leq a(x) \leq 1$ in $\Omega'$, which contains $\overline{B}$ and hence the symmetric difference between $\partial^*(W)$ and $\partial^*(X)$. That is,

$$F_w(X) - F_w(W) = 2 \int_{\partial^*(X) \setminus \partial^*(W)} a(x) dH^{n-1}(x) - 2 \int_{\partial^*(W) \setminus \partial^*(X)} a(x) dH^{n-1}(x)$$

$$\leq 2H^{n-1}(\partial^*(X) \setminus \partial^*(W)) - 2\delta H^{n-1}(\partial^*(W) \setminus \partial^*(X)) \quad (4.20)$$

and by (4.19) (we keep the notation $\gamma = \alpha n - (n-1)$ and $C_\gamma = C^\alpha C_\alpha$),

$$2\delta H^{n-1}(\partial^*(W) \setminus \partial^*(X)) \leq 2H^{n-1}(\partial^*(X) \setminus \partial^*(W)) + F_w(W) - F_w(X)$$

$$\leq 2H^{n-1}(\partial^*(X) \setminus \partial^*(W)) + C_\gamma r^{\gamma r^{\alpha n-1}} \quad (4.21)$$

or, with $C'_\gamma = (2\delta)^{-1}C_\gamma$,

$$H^{n-1}(\partial^*(W) \setminus \partial^*(X)) \leq \delta^{-1} H^{n-1}(\partial^*(X) \setminus \partial^*(W)) + C'_\gamma r^{\gamma r^{\alpha n-1}}. \quad (4.22)$$

This is a form of quasiminimality of $W$ for the Hausdorff measure, and we shall not need more than this for the proof of Theorem 4.2 (or Theorem 4.4 later). What we will do is pick various choices of balls $B$, sets $I_0 \subset I$, and mappings $\ell' : I_0 \to I_1 = I \setminus I_0$, and compute the two sides of (4.22) to get valuable information.

For the proof of the upper bound in (4.8), we decide to pour all of $B$ into $W_1$, say. That is, we take $I_1 = \{1\}$, $I_0 = I \setminus I_1$, and take $\ell(i) = 1$ for $i \in I_0$. We get a competitor $X$ such that $\partial^*(X) \cap B(x, r) = \emptyset$ (because in $B(x, r) \subset X_1$, so there is no boundary there), and of course $\partial^*(X) \cap \partial B(x, r) \subset \partial B(x, r)$ trivially. Then $H^{n-1}(\partial^*(W) \cap B(x, r)) \leq H^{n-1}(\partial^*(W) \setminus \partial^*(X)) \leq C\delta^{-1} r^{n-1}$ by (4.22), as needed.
For the lower bound in (4.8), we start with a ball \( B_0 = B(x, r_0) \subset \Omega' \), we suppose that \( r_0 \leq r_{00} \), where the small constant \( r_{00} \) will be chosen soon, and that

\[
H^{n-1}(\Gamma^* \cap B_0) < \varepsilon r_0^{n-1}
\]  

for some small enough \( \varepsilon \) (to be chosen soon), and we want to show by induction that for \( k \geq 1 \), if we set \( r_k = 2^{-k}r_0 \) and \( B_k = B(x, r_k) \), we also have

\[
H^{n-1}(\Gamma^* \cap B_k) < s^k \varepsilon r_k^n
\]  

with we shall choose \( s = 2^{-\gamma} \in (0, 1) \). Then we will produce a contradiction.

We start with \( r_0 \), and choose \( \rho \in \left( \frac{9r_0}{10}, r_0 \right) \) such that the security condition (4.12) holds for \( \rho \). This is easy to do because (4.12) holds for almost every \( \rho \). Set \( D = B(x, \rho) \), take a second copy \( D' \) of \( D \), and glue the two copies along \( \partial D \) to get a topological sphere \( \hat{D} = D \cup D' \). We do this so that we can apply Poincaré’s inequality to \( \hat{D} \) without worrying about boundaries. Next pick a proper subset \( I_0 \) of \( I \), and set \( W = \bigcup_{i \in I_0} D \cap W_i \). Note that \( W \) is a set of finite perimeter, in \( D \) as well as in \( \hat{D} \), and the union \( \hat{W} \) of \( W \) and its copy \( W' \subset D' \) is also of finite perimeter. Note that \( \partial^* W \cap D \subset \Gamma^* \), and on \( \partial D \) we have no contribution from \( \partial^* \hat{W} \), because by (4.12) almost every point of \( \partial D \) is a point of density 1 or 0 for \( W \) (in \( \Omega \)), hence also for \( \hat{W} \) (for \( \hat{D} \), which we see locally as a tube around \( \partial D' \), maybe with a slightly different metric). Thus, \( \hat{W} \) has no perimeter on \( \partial D \), and

\[
H^{n-1}(\partial^* \hat{W}) = 2H^{n-1}(\partial^* W) \leq 2H^{n-1}(\Gamma^* \cap B_0) \leq 2\varepsilon r_0^{n-1}
\]  

because \( \partial^* W \cap D \subset \Gamma^* \cap D \subset \Gamma^* \cap B_0 \), similarly for the symmetric piece, and by (4.23). The Poincaré inequality in \( \hat{D} \) (proved exactly as in a ball or a sphere) yields

\[
\min(|W|, |D \setminus W|) = \frac{1}{2} \min(|\hat{W}|, |\hat{D} \setminus \hat{W}|) 
\leq C\text{Per}(\hat{W}; \hat{D})^{n-1} = CH^{n-1}(\partial^* \hat{W})^{n-1} \leq C\varepsilon^{n-1} r_0^n
\]  

by (4.25). Let us first choose \( I_0 \) to be composed of a single \( W_1 \) such that \( |W_1| \) is the second largest one. Then \( |W| = |W_1| \leq \frac{1}{2}|D| \), the minimum in (4.26) is \( |W| \), and we get that \( |W_i| \leq C\varepsilon^{n-1} r_0^n \leq C\varepsilon^{n-1} |D| \) if \( \varepsilon \) is small enough. So, \( |W_i| \leq |D| \) for all \( i \in I \), except maybe one. Then choose any \( I_0 \) so that \( |W| \leq \frac{1}{2}|D| \). Again the minimum in (4.26) is \( |W| \), so we get that

\[
|W| \leq C\varepsilon^{n-1} r_0^n \leq C\varepsilon^{n-1} |D|.
\]  

(4.27)

We may assume that the names were chosen so that \( |W_1 \cap D| \) is largest among the \( |W_i \cap D| \); it follows from (4.27), applied to sets \( I_0 \) where we add elements of \( I \setminus \{1\} \) one by one, that \( \sum_{i \geq 1} |W_i \cap D| \leq C\varepsilon^{n-1} |D| \leq \frac{1}{10} |D| \). That is,

\[
|D \setminus W_1| = \sum_{i > 1} |W_i \cap D| \leq C\varepsilon^{n-1} r_0^n.
\]  

(4.28)
Recall that \( r_1 = r_0/2 \). We claim that we can choose a new radius \( r \), with \( r_1 < r < \rho \), such that (4.12) holds for \( r \) and

\[
H^{n-1}(\partial B(x, r) \setminus W_1) \leq (\rho - r_1)^{-1} \int_{r_1 < r' < \rho} \int_{\partial B(x, r') \setminus W_1} dH^{n-1} dr' = C(\rho - r_1)^{-1} |(B(x, \rho) \setminus B(x, r_1)) \setminus W_1| \leq CR_0^{-1} |D \setminus W_1| \leq C\varepsilon \frac{n}{n-1} r_0^{n-1}, \tag{4.29}
\]

where the first inequality is possible by Chebyshev, the second one is a baby version of the co-area formula where we replace a bulk integral by an integral on spheres, and then we use (4.28). The additional property (4.12) does not disturb, because it holds for almost all \( r \). We use \( B = B(x, r) \) to apply the construction of a competitor \( X \in F_w \) described above, with \( I_0 = I \setminus \{1\} \). That is, all the small components are poured into \( W_1 \). Note that with this choice, \( \partial^* (X) \cap B \) is empty (because now only \( X_1 \) meets \( B \)), and so

\[
H^{n-1}(\partial^* (X) \setminus \partial^* (W)) \leq H^{n-1}(\partial^* (X) \cap \partial B) \leq H^{n-1}(\partial B \setminus W_1) \leq C(r_1\varepsilon) \frac{n}{n-1} r_1^{n-1} \tag{4.30}
\]

by (4.14) and (4.15) (recall that \( r_1 < r < \rho < r_0 = 2r_1 \)). By (4.22)

\[
H^{n-1}(\Gamma^* \cap B(x, r_1)) \leq H^{n-1}(\Gamma^* \cap B) \leq H^{n-1}(\partial^* (W) \setminus \partial^* (X)) \leq CH^{n-1}(\partial^* (X) \setminus \partial^* (W)) + C' \gamma \rho^{\gamma} r_0^{n-1} \leq C\varepsilon \frac{n}{n-1} r_0^{n-1} + C' \gamma \rho^{\gamma} r_0^{n-1}. \tag{4.31}
\]

That is, \( r_1 \) satisfies (4.23) with \( \varepsilon \) replaced by \( \varepsilon_1 = C\varepsilon \frac{n}{n-1} + C' \gamma \rho^{\gamma} \). Here our constants depend on \( \delta \), but we no longer track the dependence. We are now ready to prove (4.24) by induction. To prove (4.24), it suffices to show that \( \varepsilon_k \leq s^k \varepsilon \) for all \( k \), where \( \varepsilon_k = r_k^{-n} H^{n-1}(\Gamma^* \cap B_k) \). First choose \( \varepsilon \) so small that \( C\varepsilon \frac{1}{\gamma} \frac{1}{n-1} < \frac{1}{4} \). When \( n = 1 \), we do not need to do a choice; in fact we could choose \( r \) so that the two points of \( 2B \) lie in \( W_1 \), and then the term \( C\varepsilon \frac{n}{n-1} \) does not even exist; hence the strange power. Now choose \( r_0 \) so small that \( C' \gamma \rho^{\gamma} \frac{1}{r_0^{n-1}} < \frac{1}{4} \varepsilon \). With these choices done, assume that (4.24) holds for \( k \) (this is the case when \( k = 0 \)) and prove it for \( k+1 \). By induction assumption, and the same argument as above but starting from \( r_k \) and \( B_k \), we get that \( r_{k+1} \) satisfies (4.23), with

\[
\varepsilon_{k+1} = C(s^k \varepsilon)^{\frac{n}{n-1}} + C' \gamma \rho^{\gamma} \leq C\varepsilon \frac{1}{\gamma} r_k^{\frac{1}{n-1}} \varepsilon + C' \gamma 2^{-k \gamma} \rho^{\gamma} \leq \frac{1}{4} s^k \varepsilon + \frac{1}{4} 2^{-k \gamma} \varepsilon \leq s^{k+1} \varepsilon \tag{4.32}
\]

because we took \( s = 2^{-\gamma} \geq 2^{-1} \). Thus, (4.24) holds for all \( k \geq 0 \), and in particular

\[
\lim_{\rho \downarrow 0} \rho^{1-n} H^{n-1}(\Gamma^* \cap B(x, \rho)) = 0. \tag{4.33}
\]

We claim that this is impossible for \( x \in \Gamma^* \). Indeed for \( x \in \Gamma^* \), (4.3) says that for \( \rho \) small enough, we can find two balls \( B_1, B_2 \subset B(x, \rho) \), of radius \( \rho/4 \), such that if \( m_{i,j} \) denotes the average of \( 1_{W_j} \) on \( B_j \), \( j = 1, 2 \), \( m_{i,1} \) is as close to 1 as we want and \( m_{i,2} \) is as close to 0 as we want. But by Poincaré’s inequality \( |m_{i,1} - m_{i,2}| \leq C\rho^{1-n} \mu_{W_j}(B(x, \rho)) \), so \( H^{n-1}(\Gamma^* \cap B(x, \rho)) \geq \mu_{W_j}(B(x, \rho)) \geq C^{-1} \rho^{n-1} \), in contradiction with (4.33).
We may now summarize: we took $B(x, r)$ as in the assumptions of the theorem, assumed that (4.23) holds, and got a contradiction if $\varepsilon$ and $r_00$ are chosen small enough. So, (4.23) fails, and (4.8) holds for $r \leq r_00$. We can easily extend this to $r_{00} < r \leq 1$, say, simply by using the result for $r_00$ and multiplying the constant $C_{ar}$ by $r_1^{1-n}$ (but the true invariant statement is rather to assume that $r \leq r_00$ and get the first constant $\varepsilon$). This completes the proof of Theorem 4.2.

Theorem 4.2 is not always precise enough, because we also wish to know that every $W_i$ is individually nice. The following statement gives some initial information about this.

**Theorem 4.4.** Let $\Omega$, $a$, $G$, and $J_w$ be as in Theorem 4.2. There exists a constant $C_N$, which depends only on $n$, $\delta$, $\alpha$, $C_\alpha$, but also the number of components $W_i$, such that if $\Omega' \subset \Omega$ is open, if

\[
\delta \leq a(x) \leq 1 \quad \text{for } x \in \Omega',
\]

and if $W \in F_w(\Omega)$ minimizes $J_w$ in the class $F_{w}(\Omega)$, then for $1 \leq i \leq N$, $x \in \Omega' \cap \partial^n W_i$ and $0 < r \leq \min(1, \text{dist}(x, \partial \Omega'))$,

\[
C_N^{-1} r^{n-1} \leq H^{n-1}(\partial^n W_i \cap B(x, r)).
\]

So, none of the $\Gamma_i^*$ can be too small locally. We did not need to write the upper bound, because $\Gamma^*$ is larger.

**Remark 4.5.** Unfortunately our estimate depends on $N$. The authors’ bet is that the same result also holds with a constant $C_N$ that does not depend on $N$, but were not able to prove this. Similarly, there should be an automatic regulation of the number of pieces, in the sense that if $\Omega$ has a reasonable shape (so that a Poincaré inequality holds in $\Omega$), and $\delta \leq a(x) \leq 1$ in the whole $\Omega$, and $W \in F_w(\Omega)$ minimizes $J_w$ in the class $F_{w}(\Omega)$, the number of pieces $W_i$ such that $|W_i| > 0$ should be bounded by a constant $N_0$ that depends only on $n$, $\delta$, $\alpha$, $C_\alpha$, and geometric constants related to $\Omega$. A proof of this would need to be more clever than the proof below, and bound the number of components that really interact with a given one that we want to erase.

**Remark 4.6.** In [17], Leonardi proves an analogue of Theorem 4.2 in the more general situation where $F_w$ looks like

\[
F_w(W) = \sum_{i,j \in I, i \neq j} a_{ij} \mathcal{H}^{n-1}(\Gamma^*_i \cap \Gamma^*_j),
\]

where the coefficients $a_{ij}$ are symmetric ($a_{ij} = a_{ji}$) and satisfy a condition inspired of the triangle inequality that prevents thin layers of some $W_k$ to be incorporated between $W_i$ and $W_j$ so that the energy of the interfaces diminishes. His proof is like the proof of Theorem 4.2, but with a beautiful extra argument of graph theory whose purpose is to take into account the fact that when we pour $W_i$ into $W_j$, some of the old boundary $\Gamma^*_i$ becomes a part of $\Gamma^*$, so that in the functional $F_w(W)$ the corresponding multiplying coefficients $a_{ij}$ are replaced by $a_{\ell,j}$. The same proof should also work with

\[
F_w(W) = \sum_{i,j \in I, i \neq j} \int_{\Gamma^*_i \cap \Gamma^*_j} a_{ij} d\mathcal{H}^{n-1}(x),
\]
provided that the variable coefficients \( a_{i,j}(x) \) are also Hölder continuous. We decided not to pursue this. As far as the authors know, it is not known whether the natural variant of Theorem 4.4 in this context of different coefficients holds, even with constant coefficients \( a_{i,j} \) and only \( N = 4 \).

The proof of Theorem 4.4 is easy (but the result is probably too weak). We proceed as above, suppose that \( x \in \Gamma_i^* \) and \( r_{00} \) are such that

\[
\mathcal{H}^{n-1}(\Gamma_i^* \cap B(x, r_0)) < \varepsilon r_0^{n-1},
\]

just as in (4.23) but now we will allow \( \varepsilon \) and \( r_{00} \) to depend on \( N \). We choose \( \rho \in (\frac{9 r_{00}}{10}, r_0) \) as above, so that (4.12) holds for \( \rho \), and now want to apply the same argument as above, but where we just poor some part of \( W_i \) alone into some other piece \( W' \). We consider \( D = B(x, \rho) \), add a second copy \( D' \) of \( D \) as above, to make a topological sphere \( \hat{D} \), take \( W = D \cap W_i \) and glue a second copy \( W' \) to make a set of finite perimeter \( \hat{W} \subset \hat{D} \), and apply Poincaré’s inequality in \( \hat{D} \). We get, just as for (4.25), that

\[
\min(|W|, |D \setminus W|) = \frac{1}{2} \min(|\hat{W}|, |\hat{D} \setminus \hat{W}|) \\
\leq C \text{Per}(\hat{W}; \hat{D}) \frac{n}{n-1} = C \mathcal{H}^{n-1}(\Gamma_i^* \cap \hat{D}) \frac{n}{n-1} \leq C \varepsilon \frac{n}{n-1} r_0^n.
\]

We start a discussion with the most likely case when \( |W| = |W_i \cap D| \leq \frac{1}{2} |D| \), which actually implies that \( |D|^{-1} |W_i \cap D| \) is very small. We choose a new radius \( r \), with \( r_1 < r < \rho \), such that

\[
\int_{W_i \cap \partial B(x, r)} dH^{n-1} \leq (\rho - r_1)^{-1} \int_{r_1 < r < \rho} \int_{W_i \cap \partial B(x, r)} dH^{n-1} \, dr \\
= C(\rho - r_1)^{-1} |(W_i \cap B(x, \rho)) \setminus B(x, r_1)| \leq C r_0^{-1} |W_i \cap D| \leq C \varepsilon \frac{n}{n-1} r_0^n
\]

with the same justification as for (4.29). Recall from Lemma 4.1 that modulo a \( \mathcal{H}^{n-1} \)-negligible set, \( \Gamma_i^* \) is the union of the \( \Gamma_i^* \cap \Gamma_j^* \), \( j \neq i \), so we can choose \( j \neq i \) such that

\[
\mathcal{H}^{n-1}(\Gamma_i^* \cap \Gamma_j^* \cap B(x, r)) \geq N^{-1} \mathcal{H}^{n-1}(\Gamma_i^* \cap B(x, r)),
\]

and we decide to pour \( W_i \cap B(x, r) \) into \( W_j \). In the previous construction, this amounts to taking \( I_0 = \{i\} \) and \( \ell(i) = j \). Let \( \mathbf{X} \) denote the new competitor that we get; this time we do not add anyone to \( \Gamma_i^* \) in \( B = B(x, r) \), but we remove the whole set \( \Gamma_i^* \cap \Gamma_j^* \cap B(x, r) \), so we save at least the right-hand side of (4.41) there. As before, we add the new piece \( W_i \cap \partial B \) to \( \Gamma_i^* \) and \( \Gamma_j^* \), and we do not change \( \Gamma_i^* \) on \( \Omega \setminus \overline{B} \). Altogether, (4.14) and (4.15) now yield

\[
\mathcal{H}^{n-1}(\partial^*(\mathbf{X}) \setminus \partial^*(\mathbf{W})) \geq \mathcal{H}^{n-1}(\Gamma_i^* \cap \partial^* B) \geq N^{-1} \mathcal{H}^{n-1}(\Gamma_i^* \cap B)
\]

and

\[
\mathcal{H}^{n-1}(\partial^*(\mathbf{X}) \setminus \partial^*(\mathbf{W})) \leq \mathcal{H}^{n-1}(\partial^* \mathbf{X}) \setminus \partial B \leq \mathcal{H}^{n-1}(\partial B \setminus W_i) \leq C(s^k \varepsilon) \frac{n}{n-1} r_k^{n-1}.
\]
by (4.14) and (4.15). Hence by (4.22),
\[
\mathcal{H}^{n-1}(\Gamma_i^* \cap B(x, r_1)) \leq \mathcal{H}^{n-1}(\Gamma_i^* \cap B) \leq N\mathcal{H}^{n-1}(\partial^* W) \setminus \partial^* X) \leq C N \mathcal{H}^{n-1}(\partial^* X) \setminus \partial^* W) + C'_r N r_0^r n^{-1} \leq C N \varepsilon r_0^r n^{-1} + C'_r N r_0^r n^{-1}.
\]
\[(4.44)\]

That is, \( r_1 \) satisfies (4.38) with \( \varepsilon \) replaced by \( \varepsilon_1 = C \varepsilon r_0^r n^{-1} + C'_r N r_0^r N \). This should of course be compared to (4.31); we see that we only had to multiply the right-hand side by \( N \). Before we can conclude as above, we still need to say what happens when \(|W| = |W_1 \cap D| > \frac{1}{2} |D|\), that is, when \( W_1 \) is the major part of \( D \). In this case we proceed exactly as in Theorem 4.2, that is, choose \( r \) such that (4.29) holds (with \( W_1 \) replaced by \( W_i \)), pour all the other parts \( W_j \cap B, j \neq i, \) into \( W_i \), and get (4.31), which is even better than (4.44) by a factor \( N \).

So, we managed to prove (4.44), and now we can copy the induction argument and the rest of the proof of Theorem 4.2; Theorem 4.4 follows. \( \square \)

## 5 | CLEAN REPRESENTATIVES OF WEAK MINIMIZERS

In this section, we take a minimizer \( W \in P_w(\Omega) \) for the weak functional \( J_w \), for instance, and prove that we can clean it and get an equivalent \( N \)-tuple \( W^\# \), where the \( W^\#_i \) are open. This will be used later to prove that the weak and strong functionals are equivalent, and the argument is rather standard in the business of weak functionals. We keep the same notation as above concerning the reduced boundaries \( \Gamma_i^* = \partial^* W_i \) and \( \Gamma^* = \bigcup_i \Gamma_i^* \subset \Omega \). Most of the discussion in this section does not use the form of the functional, but only local Ahlfors regular estimates for \( \Gamma^* \) like (4.8).

**Proposition 5.1.** Let \( W \in P_w(\Omega) \) be such that for every compact set \( K \subset \Omega \), there is a constant \( C_K \geq 1 \) such that for \( i \in I = \{1, 2, \ldots, N\} \),
\[
C_K^{-1} r_0^r n^{-1} \leq \mathcal{H}^{n-1}(\Gamma_i^* \cap B(x, r)) \leq C_K r_0^r n^{-1} \quad \text{for } x \in \Gamma^* \cap K \text{ and } 0 < r \leq 1.
\]
\[(5.1)\]

Then
\[
\mathcal{H}^{n-1}(\Omega \cap \overline{\Gamma_i^*} \setminus \Gamma_i^*) = 0 \quad \text{for } i \in I,
\]
\[(5.2)\]

and we can find open sets \( W^\#_i, 1 \leq i \leq N \), such that for \( i \in I \),
\[
|W_i \setminus W^\#_i| = |W^\#_i \setminus W_i| = 0
\]
\[(5.3)\]

and
\[
\Omega \cap \partial W^\#_i = \Omega \cap \overline{W^\#_i \setminus W_i} = \Gamma_i^*.
\]
\[(5.4)\]

If we only know (5.1) globally for \( \Gamma^* \), we get still (5.3) and (5.4), and instead of (5.2) we at least have
\[
\mathcal{H}^{n-1}(\Omega \cap \overline{\Gamma^*} \setminus \Gamma^*) = 0.
\]
\[(5.5)\]
Note that the conclusion holds for minimizers of the weak functional, or even when $W$ lies in one of the classes of almost- and quasi-minimizers alluded to in Definition 4.3 or near (4.22), since we then have the conclusions of Theorem 4.2 or 4.4. Set

$$\Gamma_i = \Omega \cap \Gamma_i^* \quad \text{and} \quad \Gamma = \Omega \cap \Gamma^* = \cup_{i \in I} \Gamma_i;$$

(5.6)

the main part of the proposition is (5.2) (or (5.5) if we only have (5.1) for $\Gamma^*$), which we check now.

We prove (5.5); (5.2) would be the same (add an index $i$). It is enough to check that $H^{n-1}(B \cap \Gamma \setminus \Gamma^*) = 0$ when $B$ is a closed ball such that $3B \subset \Omega$. Note that then we can apply Theorem 4.2 on $B$. Let $\epsilon > 0$, and set $\mu = H^{n-1}_{|2B\cap\Gamma^*}|$. Since by (4.8) $\mu$ is a Radon measure, we can find a compact set $K \subset \Gamma^*$ such that $\mu(2B \setminus K) \leq \epsilon$. Then let $\eta > 0$ be small, and for each $x \in \Gamma \cap B \setminus K$, choose a small ball $B(x) = B(x, r(x))$ such that $0 < r(x) < \eta/2$ and $B(x) \cap K = \emptyset$. Now use the standard 5-covering lemma of Vitali: there is an at most countable set $X \subset \Gamma \cap B \setminus K$ such that the balls $B(x, r(x)/5)$, $x \in X$, are disjoint, but the $B(x)$ cover $\Gamma \cap B \setminus K$. Since $\Gamma = \Omega \cap \Gamma^*$, each $B(x, r(x)/10)$ contains a point $y \in \Gamma^*$, and by (5.1) for $\Gamma^*$,

$$\mu(B(x, r(x)/5)) \geq \mu(B(y, r(x)/10)) = H^{n-1}(\Gamma^* \cap B(y, r(x)/10)) \geq C^{-1}r(x)^{n-1}. \quad (5.7)$$

Now

$$\sum_{x \in X} r(x)^{n-1} \leq C \sum_{x \in X} \mu(B(x, r(x)/5)) \leq C \mu(2B \setminus K) \leq C \epsilon \quad (5.8)$$

because the balls $B(x, r(x)/5)$ are disjoint and contained in $2B \setminus K$. In terms of Hausdorff measure, this shows that $H^{n-1}_\eta(\Gamma \cap B \setminus K) \leq C \epsilon$ (for the definition of $H^{n-1}_\eta$, see [18, chapter 4]). Since $\eta$ is as small as we want, we get that $H^{n-1}(\Gamma \cap B \setminus K) \leq C \epsilon$, and since $\epsilon$ is arbitrary, $H^{n-1}(\Gamma \cap B \setminus K) = 0$; (5.5) follows.

Now define the $W^#_i$, $i \in I$, by

$$W^#_i = \{ x \in \Omega \setminus \Gamma \mid |B(x, r) \setminus W_i| = 0 \text{ for some } r > 0 \}.$$  

(5.9)

These are clearly open sets, and we claim that

$$\Omega \setminus \Gamma \text{ is the disjoint union of the } W^#_i, i \in I.$$ \quad (5.10)

Indeed, let $x \in \Omega \setminus \Gamma$ be given; by definition we can find $r > 0$ such that $B = B(x, r)$ is contained in $\Omega$ and does not meet $\Gamma^*$. Since the $W_i$ cover $\Omega$, we can find $i$ such that $|W_i \cap B| > 0$. Now if $|B \setminus W_i| > 0$, we get, for instance, that

$$\int_{x \in B} \int_{y \in B} |1_{W_i(x)} - 1_{W_j(y)}| dx dy \geq |W_i \cap B||B \setminus W_i| > 0,$$

and by Poincaré’s inequality $\mu_{W_i}(B) = \int_B |D1_{W_i}| > 0$. But $\mu_{W_i}(B) = H^{n-1}(\Gamma_i^* \cap B)$ by definition of $\mu_{W_i}(B)$ and (4.1), and this contradicts the fact that $B$ does not meet $\Gamma_i^* \subset \Gamma^*$. So, $x \in W^#_i$, and (5.10) follows.

Next we check the equivalence (5.3). If $x \in W_i$, then almost always (by (5.5)) $x \in \Omega \setminus \Gamma$, hence (by (5.9)) it lies in some $W^#_j$. But $x$ is almost always a Lebesgue density point for $W_i$, so $j = i$ and $x \in W^#_i$. Conversely, if $x \in W^#_i$, some whole ball $B(x, r)$ is (almost) contained in $W_i$; but almost
always \( x \) is a point of density of all the \( W_j \) that contain it, and this forces \( j = i \). Hence, \( x \in W_i \) (because \( \Omega = \cup_j W_j \)).

We still need to check (5.4). Let \( x \in \Omega \cap \partial W^d_i = \overline{W^d_i} \setminus W^d_i \). Every small ball \( B(x, r) \) meets \( W^d_i \), so \( |W_i \cap B(x, r)| > 0 \) (because \( W^d_i \) is open). On the other hand, \( x \notin W^d_i \) hence \( |B(x, r) \setminus W_i| > 0 \) so, by the same proof using the Poincaré inequality as before, \( B(x, r) \) meets \( \Gamma_i^* \). So, \( \partial W^d_i \subset \Gamma_i \).

Conversely, if \( x \in \Gamma_i \), every ball \( B(x, r) \) meets \( \Gamma_i^* \). If \( y \) is any point of \( B(x, r) \cap \Gamma_i^* \) and \( D \) is a tiny ball centered at \( y \), then \( |W_i \cap D| > 0 \) and \( |D \setminus W_i| > 0 \) by definition of \( \Gamma_i^* \) (see (4.3)). Then also \( |W_i \cap D| > 0 \) and \( |D \setminus W_i| > 0 \) by (5.3), and \( x \in \partial W^d_i \). Proposition 5.1 follows.

The \( N \)-tuple \( \mathcal{W}^d \) does not exactly lie in our set \( \mathcal{P} \) of strong partitions, because it is not a partition. But we can easily find a true partition \( \hat{\mathcal{W}} \in \mathcal{P} \), with the property that for \( i \in I \),

\[
W^d_i \subset \hat{W}_i \subset \Omega \cap \overline{W^d_i}
\] (5.11)

and then, because \( \Omega \cap \partial W^d_i \subset \Gamma \) has no interior and by (5.4)

\[
\Omega \cap \partial \hat{W}_i = \Omega \cap \partial W^d_i = \Omega \cap \overline{\Gamma_i}.
\] (5.12)

Now we can compute the strong functional. Of course \( G(\hat{\mathcal{W}}) \) is the same for \( J_w \) and \( J_s \), so we are left with

\[
F_s(\hat{\mathcal{W}}) = \sum_{i=1}^{N} \int_{\Omega \cap \hat{W}_i} a(x) dH^{n-1}(x) = \sum_{i=1}^{N} \int_{\Omega \cap \overline{\Gamma_i}} a(x) dH^{n-1}(x)
\]

\[
= \sum_{i=1}^{N} \int_{\Omega \cap \Gamma_i^*} a(x) dH^{n-1}(x) = F_w(\hat{\mathcal{W}}),
\] (5.13)

by (3.3), (5.12), and (5.2). The authors are not sure that there may be circumstances where one can obtain (5.1) globally for \( \Gamma^* \) but not separately for each \( \Gamma_i^* \), but if this is the case we can also use a variant of \( F_s \), namely,

\[
F^s(\mathcal{W}) = 2 \int_{\partial(\mathcal{W})} a(x) dH^{n-1}(x),
\] (5.14)

where \( \partial(\mathcal{W}) = \Omega \cap (\cup_i \partial W_i) \) as above. For this one, even if we only have (5.1) for \( \Gamma^* \),

\[
F^s(\hat{\mathcal{W}}) = 2 \int_{\Gamma^*} a(x) dH^{n-1}(x) = F_w(\hat{\mathcal{W}}),
\] (5.15)

by (5.5) and (4.5).

We are now ready to say that the weak and strong functionals are equivalent.

**Corollary 5.2.** Let \( \Omega \) be a bounded domain, \( a \) a continuous positive function on \( \Omega \), and \( G \) satisfy the Hölder condition (4.6). Then the functional \( J_w \) of (3.7) has a minimizer on \( F_w \), and the associated
cleaner partition $\hat{W}$ constructed above minimizes the functionals $J_\ast$ and $J_\ast^*$ on $F$. In particular,

$$\inf_{W \in F} J_\ast(W) = \inf_{W \in F} J_\ast^*(W) = \inf_{W \in F_w} J_w(W) = J_w(\hat{W}). \quad (5.16)$$

Also, if $W_0$ is a minimizer of $J_\ast(W)$ or $J_\ast^*(W)$ in $F$, then it is also a minimizer of $J_w$ in $F_w$.

Note first that the assumptions of Theorem 3.1 are satisfied, so $J_w$ has a minimizer in $F_w$. In addition, the assumptions of Theorem 4.4 are also satisfied, except for the fact that $a(x) \leq 1$ on $\Omega$, which is not needed for the local Ahlfors estimate (see the remarks below the statement of Theorem 4.2, or simply follow the proof), so the $\Gamma_i^*$ satisfy the assumptions of Proposition 5.1, and we can construct the clean representatives $W^\#_i$ and $\hat{W}$ with the properties (5.14) and (5.15). Then $J_\ast^*(\hat{W}) = J_\ast(\hat{W}) = J_\ast^*(\hat{W})$.

Now it should be observed that for any $W \in P$ such that $J_\ast(W)$ or $J_\ast^*(W)$ is finite, the $W_i$ have locally finite perimeters, and $J_w(W) \leq J_\ast(W), J_\ast^*(W)$. This is because for any set $A$ such that $H^{n-1}(A) < +\infty$, $A$ has a finite perimeter and $\partial^* A \subset \partial A$; then we can use the definitions and (4.5). Hence, $\inf_{W \in F} J_\ast(W)$ and $\inf_{W \in F} J_\ast^*(W)$ are at least as large as $\inf_{W \in F_w} J_w(W) = J_w(\hat{W})$. The rest of the corollary follows.

\[ \square \]

## 6 UNIFORM RECTIFIABILITY AND ISOPERIMETRY

In this section, we consider a minimizer $W$ of the functional $F_w$ on $\Omega$, and assume as in Theorems 4.2 and 4.4 that $G$ is Hölder continuous, as in (4.6), and that on the open set $\Omega' \subset \Omega$, we have the bounds (4.7) on $a$.

We continue the description of the free boundary. In fact, we shall find it more convenient to use the equivalent open sets $W^\#_i$ of Proposition 5.1 (defined by (5.9)), and the closed boundaries

$$\Gamma_i = \Omega \cap \overline{\Gamma^*_i} = \Omega \cap \partial W^\#_i \quad \text{and} \quad \Gamma = \Omega \cap \overline{\Gamma^*} = \cup_{i \in I} \Gamma_i; \quad (6.1)$$

of (5.6) (see (5.3)). Recall from (5.2) that $H^{n-1}(\Omega \cap \overline{\Gamma^*_i} \setminus \Gamma^*_i) = 0$, so we are not adding any mass when we replace $\Gamma^*_i$ with $\Gamma_i$, but having a closed set is nicer. Because of Corollary 5.2, we could also have considered a minimizer of $J_\ast$ or $J_\ast^*$ in $F$, and cleaned it as we have cleaned weak minimizers in Section 5.

Recall that Theorems 4.2 says that $\Gamma$ is a locally Ahlfors regular set in $\Omega'$, and Theorems 4.4 says that the individual $\Gamma_i$ are also locally Ahlfors regular sets in $\Omega'$, but with bounds that depend on the number $N$ of pieces too. Our next step is to prove that these sets satisfy S. Semmes’ Condition B, and hence are locally uniformly rectifiable.

**Theorem 6.1.** Let $\Omega \subset \mathbb{R}^n$, $W \in F_w(\Omega)$, $\Gamma$, and $\Omega'$ be as above. There exists a constant $C_1 = C_1(n, a, C_2, \delta) > 1$ such that for $x \in \Gamma \cap \Omega'$ and $0 < r \leq \min(1, \text{dist}(x, \partial \Omega'))$, we can find two indices $i, j \in I$, with $i \neq j$, and points $x_i \in W^\#_i$ and $x_j \in W^\#_j$, such that

$$B_i = B(x_i, C_1^{-1}r) \subset W^\#_i \cap B(x, r) \quad \text{and} \quad B_j = B(x_j, C_1^{-1}r) \subset W^\#_j \cap B(x, r). \quad (6.2)$$
Moreover, there exists a constant $C_2 = C_2(n, \alpha, C_\alpha, \delta, N) \geq 1$ such that for $x \in \Gamma_i \cap \Omega'$, with $i \in I$, and $0 < r \leq \min(1, \dist(x, \partial \Omega'))$, we can find $x_i \in W_i^\#$ such that

\[ B(x_i, C_2^{-1}r) \subset W_i^\# \cap B(x, r). \]  

(6.3)

As before, it could be that (6.3) also holds with a constant $C_2$ that does not depend on $N$, but we shall not prove this. Condition B was introduced in [19], and by now we have various proofs of the fact that for locally Ahlfors regular sets, it implies the local uniform rectifiability of $\Gamma$ (or of the individual $\Gamma_i$, with a worse constant), and even that $\Gamma$ or the $\Gamma_i$ contain “big pieces of Lipschitz graphs.” See [9] for all the information that the reader could want on uniform rectifiability; here we shall only consider this as good news, and shall not comment further.

The proof will follow the same line as in [10]. We start with the result with the two balls. Note that we need $N \geq 2$ for (6.4) to hold, but this is all right because if $N = 1$, $\Omega = W_1$ and $\Gamma$ is empty.

Let $(x, r)$ be as in the statement; without loss of generality, we can assume that $|B(x, r/2) \cap W_1| \geq |B(x, r/2) \cap W_2| \geq |B(x, r/2) \cap W_i|$ for $i > 2$. Let us first show that

\[ |B(x, r/2) \setminus W_1| \geq \varepsilon r^n \]  

for some $\varepsilon > 0$ that depends on $n, \alpha, C_\alpha$, and $\delta$. If not, pick $\rho \in (r/4, r/2)$, as we chose $r$ near (4.29), such that (4.12) holds for $\rho$ and

\[ \mathcal{H}^{n-1}(\partial B(x, \rho) \setminus W_1) \leq Cr^{-1}|B(x, r/2) \setminus W_1| \leq C\varepsilon r^{n-1}. \]  

(6.5)

Then try the competitor $X$ such that $X_1 = W_1 \cup B(x, \rho)$ and $X_i = W_i \setminus B(x, \rho)$ for $i > 1$. That is, pour the $W_i \cap B(x, \rho)$ into $W_1$. The accounting is the same as near (4.30): we save $\Gamma^* \cap B(x, \rho)$, but we may add $B(x, \rho) \setminus W_1$ to $\Gamma^*$, and also add

\[ |G(W) - G(X)| \leq C_\alpha \dist(W, X)^\alpha = C_\alpha 2^\alpha |B(x, \rho) \setminus W_1|^\alpha \leq CC_\alpha \varepsilon^\alpha r^{n\alpha} \]  

(6.6)

by (4.8). The minimality of $W$ yields

\[ \mathcal{H}^{n-1}(\Gamma^* \cap B(x, \rho)) \leq C\varepsilon^{-1} \mathcal{H}^{n-1}(\partial B(x, \rho) \setminus W_1) + CC_\alpha \delta^{-1} \varepsilon^\alpha r^{n\alpha} \leq C\varepsilon^{-1} \varepsilon^\alpha r^{-1} \]  

(6.7)

because $\alpha > n^{-1}$. If $\varepsilon$ is small enough, this contradicts Theorem 4.2, so (6.4) holds.

We also need to know that $W_1$ is not too small, that is, that

\[ |B(x, r/2) \cap W_1^\#| = |B(x, r/2) \cap W_1| \geq \varepsilon r^n, \]  

(6.8)

where the first part comes from (5.3). If not, then for each $i$, $|B(x, r/2) \cap W_i| \leq \varepsilon r^n$, and by Poincaré’s inequality on the double of $B(x, r/2)$, and as (4.26), we have that for each $i \in I$,

\[ |B(x, r/2) \cap W_i| = \min(|B(x, r/2) \cap W_i|, |B(x, r/2) \setminus W_i|) \]

\[ \leq C \Per(W_i; B(x, r/2))^{\frac{n}{n-1}} \leq CH^{n-1}(\Gamma_i^* \cap B(x, r/2))^{\frac{n}{n-1}} \]  

(6.9)
and hence
\[ H^{n-1}(\Gamma^*_i \cap B(x, r/2)) \geq C^{-1} |B(x, r/2) \cap W_i|^{-\frac{n-1}{n}} \]
\[ = C^{-1} |B(x, r/2) \cap W_i| |B(x, r/2) \cap W_i|^{-\frac{1}{n}} \geq C^{-1} |B(x, r/2) \cap W_i|^{-\frac{1}{n}} r^{-1}. \quad (6.10) \]

We sum this over \( i \in I \), and get that
\[ \sum_{i \in I} H^{n-1}(\Gamma^*_i \cap B(x, r/2)) \geq C^{-1} \varepsilon^{-\frac{1}{n}} r^{-1} |B(x, r/2)| \geq C^{-1} \varepsilon^{-\frac{1}{n}} r^{n-1}. \quad (6.11) \]

By Lemma 4.1, almost every point of \( \Gamma^* \) lies in exactly two sets \( \Gamma^*_i \), so
\[ H^{n-1}(\Gamma^* \cap B(x, r/2)) \geq C^{-1} \varepsilon^{-\frac{1}{n}} r^{n-1}, \quad (6.12) \]
which contradicts the upper bound in (4.8) if \( \varepsilon \) is small enough. So, (6.8) holds too.

Let \( \tau > 0 \) be very small (even smaller than \( \varepsilon \)), to be chosen soon, and set
\[ Z = \{ y \in B(x, r/2) ; \, \text{dist}(y, \Gamma) \leq \tau r \}; \quad (6.13) \]
we want to show that
\[ |Z| \leq C \tau r^n, \quad (6.14) \]
where \( C \) depends on \( n, \alpha, C_\alpha, \) and \( \delta \), and for this we choose a maximal family \( \{z_k\}, k \in S \), of points of \( Z \) at mutual distances larger than \( 4\tau r \). Since the balls \( B(z_k, 2\tau r) \) are disjoint, and each one contains a ball of radius \( \tau r \) centered at a point of \( B(x, 3r/4) \), we see that the number \( M = \#S \) of balls is such that
\[
M \leq C \sum_{k \in K} (\tau r)^{1-n} H^{n-1}(\Gamma^* \cap B(z_k, 2\tau r)) \\
\leq C(\tau r)^{1-n} H^{n-1}(\Gamma^* \cap [\cup_k B(z_k, 2\tau r)]) \\
\leq C(\tau r)^{1-n} H^{n-1}(\Gamma^* \cap B(x, r)) \leq C(\tau r)^{1-n} r^{n-1} = C \tau^{1-n} \quad (6.15)
\]
by (4.8). On the other hand, by maximality of \( S \), the balls \( B(z_k, 5\tau r_k) \) cover \( Z \), so \( |Z| \leq CM(\tau r)^n \leq C \rho r^n \), as announced in (6.14).

If \( \tau \) is small compared to \( \varepsilon \), (6.8) implies that \( B(x, r/2) \cap W^\#_1 \) is not contained in \( Z \), so we can find \( x_1 \in B(x, r/2) \cap W_1 \) such that \( \text{dist}(x_1, \Gamma^*) > \tau r \). Then \( B_1 = B(x_1, \rho r) \subset W^\#_1 \cap B(x, r) \) (see (5.4)). Similarly,
\[ \sum_{i > 1} |B(x, r/2) \cap W^\#_i| = \sum_{i > 1} |B(x, r/2) \cap W_i| = |B(x, r/2) \setminus W_1| \geq \varepsilon r^n \quad (6.16) \]
by (6.4), so we can find \( x_2 \in B(x, r/2) \cap \cup_{i > 1} W^\#_i \) that does not lie in \( Z \), and then \( B_2 = B(x_2, \rho r) \) is contained in the set \( W^\#_i, i \geq 2 \), that contains \( x_2 \). This completes the first part of the theorem, with \( C_1 = \tau^{-1} \).
Now we prove the second part. Let $x \in \Gamma_i \cap \Omega'$ and $r > 0$ be as in the statement. We first check that

$$|B(x, r/2) \cap W_i^\#| = |B(x, r/2) \cap W_i| \geq \varepsilon r^n, \quad (6.17)$$

where now $\varepsilon > 0$ is allowed to depend on $N$ too. Indeed, if not we can choose $\rho \in (r/4, r/2)$ as before, such that (4.12) holds for $\rho$ and

$$H^{n-1}(\partial B(x, \rho) \cap W_i) \leq C r^{-1}|B(x, r/2) \cap W_i| \leq C \varepsilon r^{n-1}. \quad (6.18)$$

Then try the competitor $X$ obtained by pouring $W_i \cap B(x, \rho)$ into another component $W_j$ such that $H^{n-1}(\Gamma^n_i \cap \Gamma^n_j \cap B(x, \rho))$ is largest, so that

$$H^{n-1}(\Gamma^n_i \cap \Gamma^n_j \cap B(x, \rho)) \geq \frac{1}{N} \sum_{\ell \neq i} H^{n-1}(\Gamma^n_i \cap \Gamma^n_\ell \cap B(x, \rho)) = \frac{1}{N} H^{n-1}(\Gamma^n_i \cap B(x, \rho)), \quad (6.19)$$

where we used again the fact that almost every point of $\Gamma^n_i$ lies in exactly two sets $\Gamma^n_j$. Now the accounting is that we save $H^{n-1}(\Gamma^n_i \cap \Gamma^n_j \cap B(x, \rho))$ (see (4.11)), we pay for the additional boundary $\partial B(x, \rho) \cap W_i$, and also

$$|G(W) - G(X)| \leq C_\alpha \text{ dist}(W, X)^\alpha = C_\alpha 2^\alpha |W_i \cap B(x, \rho)|^\alpha \leq C C_\alpha \varepsilon r^{n\alpha}. \quad (6.20)$$

The minimality of $W$ yields

$$H^{n-1}(\Gamma^n_i \cap B(x, \rho))) \leq C N \delta^{-1} H^{n-1}(\partial B(x, \rho) \setminus W_i) + C \delta^{-1} C_\alpha \varepsilon r^{n\alpha} \leq C N \delta^{-1} \varepsilon^{\alpha} r^{n-1}. \quad (6.21)$$

If $\varepsilon$ is small enough, this contradicts Theorem 4.4, so (6.17) holds. And again this implies the existence of $x_1$ such that (6.3) holds, because (6.17) says $B(x, r/2) \cap W_i^\#$ cannot be contained in the set $Z$ of (6.13), if $\tau$ is chosen small enough (now depending on $N$ too). Theorem 6.1 follows. \(\square\)

We continue the description of the minimizer $W$ by saying that the open sets $W_i^\#$ have a rather round shape locally. We already know from Condition $B$ that they are not too small, since if $x \in \Gamma_i \cap \Omega'$ lies at distance $r$ from $\partial \Omega'$, we can find a ball of size $C_2^{-1} \min(1, r)$ near $x$ that is contained in $W_i$. Now we want to say that near $x$, $W_i^\#$ is also reasonably round, which we will express in terms of local isoperimetric inequalities in $W_i^\#$. We shall use the notation of (3.1) for local perimeters of sets.

**Theorem 6.2.** Let $\Omega \subset \mathbb{R}^n$, $W \in \mathcal{P}_w(\Omega)$, $\Gamma$, and $\Omega'$ be as above. There exists constants $\nu_0 = \nu_0(n, \alpha, C_2, \delta, N) > 0$ and $C_3 = C_3(n, \alpha, C_2, \delta, N) \geq 1$ such that if $i \in I$ and $Z \subset W_i^\#$ is a set of finite
perimeter such that \( Z \subset \subset \Omega' \) and \(|Z| \leq v_0\), then
\[
|Z| \leq C_3 \text{Per}(Z; W_i^\#)^{\frac{n}{n-1}}. \tag{6.22}
\]

We cannot allow \(|Z|\) to be too large, because \( Z \) could be the whole set \( W_i^\# \), which is allowed to be large by the \( G \)-term of the functional. Of course the usual isoperimetric inequality says that
\[
|Z| \leq C \text{Per}(Z)^{\frac{n}{n-1}} = CH^{n-1}(\partial^*Z)^{\frac{n}{n-1}}, \tag{6.23}
\]
so if (6.22) fails, this implies that \( \text{Per}(Z; W_i^\#) = H^{n-1}(\partial^*Z \cap W_i^\#) \) is very small compared to \( H^{n-1}(\partial^*Z) \), or equivalently that most of \( \partial^*Z \) lies on \( \partial W_i^\# \) (recall that \( \partial^*Z \subset W_i^\# \) because \( Z \subset W_i^\# \)).

So, we assume that (6.22) fails, and construct a competitor \( X \) by pouring \( Z \) into some other set \( W_j \). As usual, we choose \( j \) so that
\[
H^{n-1}(\Gamma_i^* \cap \Gamma_j^* \cap \partial^*Z \cap \partial W_i^\#) \geq \frac{1}{N} \sum_{j \neq i} H^{n-1}(\Gamma_i^* \cap \Gamma_j^* \cap \partial^*Z \cap \partial W_i^\#)
\]
\[
\geq \frac{1}{N} H^{n-1}(\partial^*Z \cap \partial W_i^\#), \tag{6.24}
\]
because (5.4) says that \( \partial^*Z \cap \partial W_i^\# \subset \Omega \cap \partial W_i^\# \subset \Omega \cap \Gamma_i^* \), (5.2) says that almost every point of \( \Omega \cap \Gamma_i^* \) lies on \( \Gamma_i^* \), and Lemma 4.1 says that almost every point of \( \Gamma_i^* \) lies on some other \( \Gamma_j^* \).

When we pour \( Z \) into \( W_j \), we erase \( \Gamma_i^* \cap \Gamma_j^* \cap \partial^*Z \cap \partial W_i^\# \) from the reduced boundary of both \( W_i \) and \( W_j \) (see the proof of (4.11)). We also add the set \( \partial^*Z \cap W_i \) to the reduced boundaries of \( W_j \) and \( W_i \), and as usual
\[
|G(W) - G(X)| \leq C_\alpha \text{dist}(W, X) = C_\alpha 2^\alpha |Z|^{\alpha} \tag{6.25}
\]
and the minimality of \( W \) yields
\[
H^{n-1}(\Gamma_i^* \cap \Gamma_j^* \cap \partial^*Z \cap \partial W_i^\#) \leq C \delta^{-1} H^{n-1}(\partial^*Z \cap W_i^\#) + C \delta^{-1} C_\alpha |Z|^{\alpha} \tag{6.26}
\]
Recall that
\[
H^{n-1}(\partial^*Z \cap W_i^\#) = \text{Per}(Z; W_i^\#) \leq (C_3^{-1}|Z|)^{\frac{n-1}{n}} \tag{6.27}
\]
because (6.22) fails, so
\[
H^{n-1}(\Gamma_i^* \cap \Gamma_j^* \cap \partial^*Z \cap \partial W_i^\#) \leq C \delta^{-1} (C_3^{-1}|Z|)^{\frac{n-1}{n}} + C \delta^{-1} C_\alpha |Z|^{\alpha} \tag{6.28}
\]
In the other direction, recall that \( \partial^*Z \cap \partial W_i^\# \) accounts for at least half of \( \partial^*Z \), so altogether by (6.23) and (6.24)
\[
|Z|^{\frac{n-1}{n}} \leq C H^{n-1}(\partial^*Z) \leq CN \delta^{-1}(C_3^{-1}|Z|)^{\frac{n-1}{n}} + CN \delta^{-1} C_\alpha |Z|^{\alpha} \tag{6.29}
\]
We are allowed to take $C_3$ so large, depending also on $N$ and $\delta$, that the first term of the right-hand side gets eaten by the left-hand side. Also $\alpha > \frac{n-1}{n}$, so the inequality fails if $|Z|$ is too small. This contradiction completes the proof of Theorem 6.2. □

The conclusion of Theorem 6.2, the fact that each $W^\#_i$ is a domain of local isoperimetry, is really a regularity result. We claim that, together with the previous Theorems 4.2 and 6.1 (local Ahlfors regularity and Condition B) for $\Gamma_i$ it implies that each $W^\#_i$ is a local John domain. This means that every point of $W^\#_i$ that is sufficiently close to $\Gamma_i$ (compared to the distance to the usual $\Omega'$) can be connected to a Condition B ball (like $B(x_1, C_2^{-1}r)$ in (6.3)) by a thick path. The corresponding global result was shown in [10], Theorem 6.1; the context is similar, but a little different because of the specific situation, but the proof of [10] can most probably be adapted to the local situation here (with estimates that may deteriorate when we look at open sets $\Omega' \subset \Omega$ that tend to $\Omega$), to justify the fact that we do not give details here.

7 | ALMOST MINIMAL SETS

In this section, we say that if we add to the traditional assumption that there exists $\delta > 0$, that depends on a domain $\Omega' \subset \Omega$, such that $\delta \leq a(x) \leq 1$ on $\Omega'$, that $a$ is also Hölder continuous on $\Omega'$, then in addition to the quasiminimality properties that we have been using so far, we get that our free boundary $\Gamma = \Omega \cap \Gamma' = \Omega \cap \cup_{i \in I} \partial^* W_i$ is an almost minimal set, and enjoys more regularity properties. The point of this paper is not to study these sets in general, so we shall content ourselves with a verification of the almost minimality property, plus two words about the additional properties that one can get.

Definition 7.1. Let $\Omega' \subset \mathbb{R}^n$ be an open set and $E \subset \Omega$ be closed in $\Omega'$. We say that $E$ is an almost minimal set in $\Omega'$, with the gauge function $h$, when for each ball $B = B(x, r) \subset \subset \Omega'$ and each Lipschitz mapping $\varphi : E \to \Omega'$ such that

$$\varphi(y) = y \text{ for } y \in E \setminus B(y, r)$$

and

$$\varphi(y) \in \overline{B}(x, r) \text{ for } y \in E \cap B(x, r),$$

we have

$$H^{n-1}(E \cap \overline{B}(x, r)) \leq H^{n-1}(\varphi(E) \cap \overline{B}(x, r)) + h(r)r^{n-1}. \quad (7.3)$$

Usually we only require the gauge function $h$ to be nondecreasing, such that $\lim_{r \to 0^+} h(r) = 0$, and often at least a Dini condition at the origin; here we will content ourselves with $h$ such that $h(r) \leq Cr^\beta$ for some $C \geq 0$ and $\beta > 0$. We tried to make the definition as simple as possible; minor variants would exist. The notion is due to Almgren [5], and is not restricted to sets of co-dimension 1 as here.

We could have demanded the existence of a one-parameter family of Lipschitz mappings $\varphi_t$, $0 \leq t \leq 1$, that connect the identity $\varphi_0$ to $\varphi_1 = \varphi$, but since we decided to take $\varphi(y) = y$ outside of $B(x, r)$, and $\varphi(y) \in \overline{B}(x, r)$ for $y \in E \cap B(x, r)$, the intermediate mapping defined by $\varphi_t(y) = t\varphi(y) + (1-t)y$ does the job.
Proposition 7.2. Let \( \Omega, F_\omega, \) and \( J_w = G + F_w \) be as above, and let \( W \) be a minimizer of \( F \) in \( F_\omega \). Assume that \( \Omega \) is bounded, that \( G \) satisfies the Hölder condition (4.6) and that on the open set \( \Omega' \subset \Omega \), we both have (4.34) and that

\[
|a(x) - a(y)| \leq C_\beta |x - y|^\beta 
\]  

(7.4)

for some \( \beta > 0 \) and some constant \( C_\beta \geq 0 \). Then \( \Gamma = \Omega \cap \overline{\delta^*(W)} \) is an almost minimal set in \( \Omega' \), with

\[
\text{the gauge } h(r) = C r^\gamma 
\]  

(7.5)

where \( \gamma = \min(\beta, \alpha n - n + 1) \) and a constant that depends only on \( n, \delta, \alpha, \beta, C_\alpha, \) and \( C_\beta \).

Indeed, let \( W \) be as in the statement, set \( E = \Gamma = \Omega \cap \overline{\delta^*(W)} \), and let \( B = B(x, r) \) and \( \varphi \) be as in Definition 7.1. We want to construct a competitor \( X \), and as usual we keep \( X = W \) on \( \Omega \setminus B \). We need to attribute the various pieces of \( B \setminus \varphi(E) \) to pieces \( W_i \).

Set \( F = \varphi(E) \), and denote by \( \{U_j\}, j \in J \), the collection of connected components of \( B \setminus F \). Also set \( A_i = W_i^\# \cap \partial B \), \( i \in I \); this is an open subset of \( \partial B \) (because \( W_i^\# \) is open), but it may be empty. If \( A_i \) is not empty, we denote by \( \{A_{i,k}\}, k \in K(i) \), the collection of its connected components. For each pair \( (i, k) \), there is a component \( H_{j(i,k)} \) such that, for every \( y \in A_{i,k} \), all the points of \( B \) that lie close enough to \( y \) belong to \( H_{j(i,k)} \). We want to take

\[
X_i = (W_i \setminus B) \cup \bigcup_{i \in I} \left( \bigcup_{k \in K(i)} H_{j(i,k)} \right) 
\]  

(7.6)

for \( i \in I \), and the main verification that we have to make is that the \( X_i \) are disjoint, that is, since the \( H_{j(i,k)} \) are contained in \( B \), that for a single component \( H_j \), we cannot have \( j = j(i, k) \) and \( j = j(i', k') \) unless \( i = i' \).

So, we give ourselves pairs \( (i, k) \) and \( (i', k') \), with \( i \neq i' \). Thus, \( A_{i,k} \) and \( A_{i',k'} \) lie in different sets \( W_i^\# \) and \( W_{i'}^\# \), and since \( \Gamma \) is the union of the boundaries of the \( W_i^\# \), we get that

\[
E = \Gamma \text{ separates } A_{i,k} \text{ from } A_{i',k'} \text{ in } \Omega. 
\]  

(7.7)

It follows easily that

\[
E \cap \overline{B} = \Gamma \text{ separates } A_{i,k} \text{ from } A_{i',k'} \text{ in } \overline{B} 
\]  

(7.8)

(otherwise there is a path in \( \overline{B} \setminus E \) that connects a point of \( A_{i,k} \) to a point of \( A_{i',k'} \), and the same path contradicts (7.6)).

Now extend the mapping \( \varphi \) to \( E \cup (\Omega \setminus B) \) by taking \( \varphi(y) = y \) on \( \Omega \setminus B \); it is easy to see that the extension is still continuous (although one may find examples where it is not Lipschitz), and we can extend it to a continuous mapping on \( \Omega \), which is the identity on \( \Omega \setminus B \) and maps \( \overline{B} \) into \( \overline{B} \). Finally, we can define a continuous deformation \( \{\varphi_t\} \) by \( \varphi_t(y) = t \varphi(y) + (1 - t)y \) that interpolates. Note that \( \varphi_t(\overline{B}) \leq \overline{B} \) and \( \varphi_t(y) = y \) on \( \partial B \). We claim that because of this,

\[
F \cap \overline{B} = \varphi_1(E \cap \overline{B}) \text{ separates } A_{i,k} \text{ from } A_{i',k'} \text{ in } \overline{B}. 
\]  

(7.9)

See [11, 7-XVII-4.3]. But since our connected component \( H_j \) of \( B \setminus F \) would have access to both \( A_{i,k} \) and \( A_{i',k'} \), we get a contradiction.
So, the sets $X_i$ are disjoint. They do not need to cover, but we can put the part of $B$ that is not covered in, say $W_1$. By construction, the total boundary $\partial(X) = \Omega \cup \bigcup_i X_i$ is contained in $(\Gamma \setminus B) \cup F$, and now we can compare. As usual, since we only modify the sets in $B$, we get that

$$|G(W) - G(X)| \leq C_\alpha \text{dist}(W, X)^\alpha \leq 2C_\alpha |B(x, r)|^\alpha \leq CC_\alpha r^{n\alpha} \tag{7.9}$$

by (4.8). Observe that

$$\left| a(x)H^{n-1}(\partial^*(W) \cap \overline{B}) - \int_{\partial^*(W) \cap \overline{B}} a(y)dH^{n-1}(y) \right| \leq C_\beta r^\delta H^{n-1}(\partial^*(W) \cap \overline{B}) \tag{7.10}$$

and similarly for $X$. Hence,

$$a(x)\left[ H^{n-1}(\partial^*(W) \cap \overline{B}) - H^{n-1}(\partial^*(X) \cap \overline{B}) \right] \leq \Delta_1 + \Delta_2, \tag{7.11}$$

with

$$\Delta_1 = \int_{\partial^*(W) \cap \overline{B}} a(y)dH^{n-1}(y) - \int_{\partial^*(X) \cap \overline{B}} a(y)dH^{n-1}(y)$$

$$= F_{\mu}(W) - F_{\mu}(X) = J_{\mu}(W) - J_{\mu}(X) - G(W) + G(X) \leq |G(W) - G(X)| \leq CC_\alpha r^{n\alpha} \tag{7.12}$$

and

$$\Delta_2 = C_\beta r^\delta \left[ H^{n-1}(\partial^*(W) \cap \overline{B}) + H^{n-1}(\partial^*(X) \cap \overline{B}) \right]. \tag{7.13}$$

Recall that $H^{n-1}_{|\partial^*} = H^{n-1}_{|\partial}$, while for $X$ we have that $H^{n-1}_{|\partial^*(X)} \leq H^{n-1}_{|\partial(X)}$. Then

$$H^{n-1}(E \cap \overline{B}(x, r)) - H^{n-1}(\varphi(E) \cap \overline{B}(x, r))$$

$$= H^{n-1}(\partial(W) \cap \overline{B}(x, r)) - H^{n-1}(\partial(X) \cap \overline{B}(x, r))$$

$$\leq H^{n-1}(\partial^*(W) \cap \overline{B}(x, r)) - H^{n-1}(\partial^*(X) \cap \overline{B}(x, r)) \leq a(x)^{-1}(\Delta_1 + \Delta_2). \tag{7.14}$$

If $H^{n-1}(E \cap \overline{B}(x, r)) \leq H^{n-1}(\varphi(E) \cap \overline{B}(x, r))$, (7.3) holds brutally. Otherwise,

$$H^{n-1}(\partial^*(X) \cap \overline{B}) \leq H^{n-1}(\partial(X) \cap \overline{B}) = H^{n-1}(\varphi(E) \cap \overline{B}(x, r))$$

$$\leq H^{n-1}(E \cap \overline{B}(x, r)) = H^{n-1}(\partial^*(X) \cap \overline{B}) \leq Cr^{n-1} \tag{7.15}$$

by the easy part of Theorem 4.2, so $\Delta_2 \leq CC_\beta r^\delta r^{n-1}$ and now (7.14) yields

$$H^{n-1}(E \cap \overline{B}(x, r)) \leq H^{n-1}(\varphi(E) \cap \overline{B}(x, r)) + a(x)^{-1}(\Delta_1 + \Delta_2)$$

$$\leq H^{n-1}(\varphi(E) \cap \overline{B}(x, r)) + C\delta^{-1}(C_\alpha r^{n\alpha} + CC_\beta r^\delta r^{n-1}). \tag{7.16}$$
Recall that \( n \alpha > n - 1 \) by assumption, so we get (7.3), with \( \gamma = \min(\beta, n \alpha - n + 1) > 0 \). This completes the proof of Proposition 7.2.

There are not so many additional regularity properties that we can prove with the help of Proposition 7.2. We could recover the Ahlfors regularity and uniform rectifiability (with a different but more complicated proof), but at least when \( n \leq 3 \) we can say more, and get a good local description of \( W \).

When \( n = 2 \), the only singularities that \( \Gamma = \partial(W) \) can have in \( \Omega \) are propeller singularities, where three \( C^{1+\sigma} \) curves of \( \Gamma \) meet at a point \( x_0 \in \Gamma \) with \( 2\pi/3 \) angles. Then of course these curves bound three different sets \( W^\#_i \). Probably a direct proof would be much faster.

When \( n = 3 \), we also have a good description of the two-dimensional almost minimal sets, which was obtained by Taylor [20]. Near each of its points, \( \Gamma \) is \( C^{1+\sigma} \)-equivalent to a minimal cone, and there are exactly three types of minimal cones: the planes, the sets \( Y \) obtained as an union of three half planes bounded by a line and that make \( 2\pi/3 \) angles along that line, and the \( T \)-sets that are obtained as images by an isometry of the cone over the union of the edges of a regular tetrahedron centered at the origin. In these cases too, \( W \) is locally composed of 2, 3, or 4 sets \( W_i \) bounded by the faces of \( \Gamma \).

It is amusing that in the case of [8], no such behavior was allowed; instead the functional managed to either have a smooth interface, or have a small black region between the active \( W_i \).

8 | FURTHER QUESTIONS

Probably the most obvious question is whether the bounds of Theorem 4.4, and the ensuing bounds for the uniform rectifiability of the pieces \( \Gamma_i = \partial W^\#_i \), really need to depend on \( N \). This is connected to the question of self-regulation: even if we start from a large enough value of \( N \), do we get that if \( \Omega \) has a nice shape and if (4.7) holds on the whole \( \Omega \), the number of nontrivial components \( W_i \) (i.e., such that \( |W_i| > 0 \)) is bounded by a constant that depends only on \( n, \alpha, C_\alpha \), bounds for the diameter and regularity of \( \Omega \), and \( \delta \)?

We did not pay attention to what happens near the boundary. Probably, if we assume that (4.7) holds on the whole \( \Omega \) and \( \Omega \) has a reasonable shape (Lipschitz should be more than enough), the results of this paper stay true at the boundary. We decided to state the results in a way that makes a discussion of what happens near the boundary when \( a(x) \) is allowed to tend to 0 at a given rate near \( \partial \Omega \), but we did not pursue this.

We do not expect much difference with the results of the present paper with functions \( a(x) \) (integrands) that also depend nicely on the direction of the tangent plane to the \( \partial^n W_i \) at \( x \). But we wish to remind the reader that in the case of “infiltration” (see [17]), when \( a(x) \) depends also on the pair of components \( W_i \) such that \( x \in \partial^n W_i \), the interesting question of whether the Ahlfors regularity property holds in \( \mathbb{R}^3 \) and with 4 components seems to be still open.

ACKNOWLEDGEMENTS

This work initiated when the second author was visiting the Université de Paris-Sud (now the Université Paris-Saclay). He would like to thank Laboratoire de mathématiques d’Orsay for the warm hospitality. He was partially supported by the Ministry of Sciences, Research and Technology of Iran during his visit. He is also deeply indebted to all the support that Massoud Amini provided during his graduate studies. Guy David was partially supported by the European Community H2020, Grant Number: GHAIA 777822, and the Simons Foundation, Grant Number: 601941, GD.
**JOURNAL INFORMATION**

*Mathematika* is owned by University College London and published by the London Mathematical Society. All surplus income from the publication of *Mathematika* is returned to mathematicians and mathematics research via the Society’s research grants, conference grants, prizes, initiatives for early career researchers and the promotion of mathematics.

**REFERENCES**

1. H. W. Alt, L. Caffarelli, and A. Friedman, *Variational problems with two phases and their free boundaries*, Trans. Amer. Math. Soc. 282 (1984), no. 2, 431–461.
2. D. N. Arnold, G. David, M. Filoche, D. Jerison, and S. Mayboroda, *Localization of eigenfunctions via an effective potential*, Commun. Partial Differ. Equ. 44 (2019), no. 11, 1186–1216.
3. D. Arnold, G. David, D. Jerison, S. Mayboroda, and M. Filoche, *Effective confining potential of quantum states in disordered media*, Phys. Rev. Lett. 116 (2016), no. 5, 056602.
4. L. Ambrosio, N. Fusco, and D. Pallara, *Functions of bounded variation and free discontinuity problems*, Oxford Mathematical Monographs, Oxford University Press, Oxford, 2000, xviii+434 pp.
5. F. Almgren, *Existence and regularity almost everywhere of solutions to elliptic variational problems with constraints*, Memoirs of the American Mathematical Society, vol. 165, Amer. Math. Soc., Providence, RI, 1976, pp. i-199.
6. E. Bombieri and E. Giusti, *Harnack’s inequality for elliptic differential equations on minimal surfaces*, Invent. Math. 15 (1972), no. 1, 24–46.
7. A. Blake and A. Zisserman, *Visual reconstruction*, MIT Press, Cambridge, MA, 1987, iv+225 pp.
8. G. David, M. Filoche, D. Jerison, and S. Mayboroda, *A free boundary problem for the localization of eigenfunctions*, Astérisque, vol. 392, société Mathématique de France, 2017, ii+203 pp.
9. G. David and S. Semmes, *Analysis of and on uniformly rectifiable sets*, vol. 38, Amer. Math. Soc., Providence, RI, 1993, xii+356 pp.
10. G. David and S. Semmes, *Quasiminimal surfaces of codimension 1 and John domains*, Pacific J. Math. 183 (1998), no. 2, 213–277.
11. J. Dugundji, *Topology*, Series in Advanced Mathematics, vol. XVI, Allyn and Bacon, Inc., Boston, 1966, 447 pp.
12. M. Filoche and S. Mayboroda, *Universal mechanism for Anderson and weak localization*, Proc. Nat. Acad. Sci. 109 (2012), no. 37, 14761–14766.
13. E. Giusti, *Minimal surfaces and functions of bounded variation*, Monographs in Mathematics, vol. 80, Springer, Berlin, 1984, xii+240 pp.
14. E. Gonzalez, U. Massari, and I. Tamanini, *On the regularity of boundaries of sets minimizing perimeter with a volume constraint*, Indiana Univ. Math. J. 32 (1983), no. 1, 25–37.
15. T. C. Hales, *The honeycomb conjecture*, Discrete Comput. Geom. 25 (2001), no. 1, 1–22.
16. D. Jerison, *The two hyperplane conjecture*, Acta Mathematica Sinica, English Series 35 (2019), no. 6, 728–748.
17. G. P. Leonardi, *Infiltrations in immiscible fluids systems*, Proc. Roy. Soc. Edinburgh Sect. A 131 (2001), no. 2, 425–436.
18. P. Mattila, *Geometry of sets and measures in Euclidean spaces: fractals and rectifiability*, vol. 44, Cambridge University Press, Cambridge, 1999, xii+343 pp.
19. S. Semmes, *A criterion for the boundedness of singular integrals on hypersurfaces*, Trans. Amer. Math. Soc. 311 (1989), no. 2, 501–513.
20. J. Taylor, *The structure of singularities in soap-bubble-like and soap-film-like minimal surfaces*, Ann. of Math. 103 (1976), 489–539.