High rate of complications and radiographic loosening of the biaxial total wrist arthroplasty in rheumatoid arthritis

32 wrists followed for 6 (5–8) years

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Background and purpose  The third generation of total wrist arthroplasty (TWA) was designed to solve the early loosening problem, but there have been few long-term follow-ups. We present the outcome of the biaxial total wrist prosthesis (no longer available) after 5–8 years of follow-up.

Patients and methods  40 biaxial wrist prostheses were implanted uncemented in 36 patients with rheumatoid arthritis. 32 wrists were followed clinically and radiographically. 7 prostheses had been revised at median 21 (8–71) months; 1 patient died from an unrelated cause. Mean follow-up of the remaining 32 wrists was 6 (5–8) years. Kaplan-Meier survival analysis was performed with revision defined as failure.

Results  Survival after 7 years was 81% (95% CI: 64–91). There were 31 complications, 22 wrists showed radiographic loosening. Range of motion improved, except for pronation. The mean DASH score improved and the median postoperative pain score (from 0 to 10) was 0 (0–6) at rest and 0 (0–7) during activity.

Interpretation  One quarter of the prostheses had been revised and radiographic loosening had occurred in two thirds of the cases. Radiographic and clinical follow-up is therefore necessary for patients with this implant.

The wrist is affected in one half of patients with rheumatoid arthritis during the first 2 years after onset of the disease, increasing to > 90% after 10 years (Trieb 2008). The first generation of wrist implants was developed in 1967 (Swanson 1973). It consisted of one flexible piece of silicone hinge. The initial results were promising, but stress at the silicone implants caused disintegration of the silicone with severe inflammatory reactions and mechanical failure. The second-generation implants were developed in the early 1970s (Volz 1976, Meuli 1980). They usually included 2 metal components that articulated by means of a ball-and-socket or hemispheric design. The main problem with these prostheses was loosening of the metacarpal component, joint imbalance, and dislocation. The third generation, such as the biaxial wrist prosthesis, was designed to solve these problems (Costi et al. 1998). Many prostheses of this type have been used in the past, but no long-term evaluation has been published.

Previous literature on the biaxial wrist prosthesis showed satisfactory pain relief, an improvement in range of motion, and satisfactory function after follow-up of 6, 3, and 4 years but also loosening, infections, and dislocation (Cobb and Beckenbaugh 1996, Courtman et al. 1999, Takwale et al. 2002). We analyzed the outcome of this prosthesis in 36 patients (40 prostheses) after 6 (5–8) years of follow-up.

Patients and methods

Patients  We included 36 adult patients (28 women) who received a primary biaxial total wrist arthroplasty (bilateral in 4 patients) for rheumatoid arthritis between December 2000 and September 2004. Median age at the time of surgery was 54 (18–74) years. The primary indication for surgery was severe wrist pain accompanied by wrist deformity and/or limitation of motion and function. At the follow-up, 32 total wrist arthroplasties could be evaluated, 7 prostheses had been revised with implant removal, and 1 patient had died from an unrelated cause (Figure 1). The mean follow-up of the remaining implants was 6 (5–8) years.

Operation  In all patients, a biaxial total wrist arthroplasty designed by Beckenbaugh was used (DePuy Orthopaedics Inc, Leeds, UK; no longer available: the producer withdrew the implant from the market because it was no longer profitable). It has a rounded, unconstrained, articulating interface, oriented in the plane of wrist movement. The prosthesis is composed of...
a metacarpal (distal) and a radial (proximal) component and the stems have porous-coated surfaces. The distal component consists of a larger stem for insertion into the third metacarpal and a small stud for insertion into the trapezoid to stabilize it during rotation.

Prophylactic antibiotic (1 g cefazoline) was given intravenously 20–30 min before the start of surgery. A tourniquet was applied to the upper arm. The surgical technique was according to Cobb and Beckenbaugh (1996). Neither component was cemented. Postoperative care consisted of 7–10 days of splint immobilization followed by a supervised program of physiotherapy. A removable splint was used for 4 weeks and was only taken off when the exercises were performed. A night splint was used for 3 months. All operations were performed by or directly supervised by the same orthopedic surgeon (MV).

Radiographic measurements

Postoperative radiographs at follow-up (anterior-posterior and lateral) were evaluated for radiolucent lines around the implants, subsidence and migration of the metacarpal implant, and erosion of the tip of the implant through the cortex of the third metacarpal. To measure the radiolucent lines, we used radiographic zones according to Cobb and Beckenbaugh (1996). The metacarpal component consists of 6 zones and the radial component of 5. The width of the radiolucent line was measured in mm on the follow-up radiograph (anterior-posterior view) for each different zone. A radiolucent line of 2 mm or more was defined as radiographic loosening. To determine subsidence of the metacarpal component, we measured the length from the tip of the metacarpal stem to the distal end of the third metacarpal on the primary postoperative radiograph (anterior-posterior view) and on follow-up radiographs. Subsidence was calculated by subtracting the two measurements. Angular migration was assessed on the primary postoperative radiograph, and at follow-up by measuring flexion-extension tilt (FEA on the lateral view) and by radio-ulnar angulation (RUA on the anterior-posterior view) (Figure 2). There may be measurement error due to variation in projection angle when the radiograph is taken. According to Cobb and Beckenbaugh (1996), this may be around 3 mm. We therefore decided that 5 mm or more was significant for subsidence, and migration of 10 degrees or more for the flexion-extension tilt and the radio-ulnar angulation. Radiographic loosening was defined as a radiolucent line equal to or greater than 2 mm in at least 1 zone, erosion of the tip of the implant through the cortex, subsidence equal to or greater than 5 mm, or migration equal to or greater than 10 degrees.

To examine the reproducibility of the radiographic measurements, we assessed the inter- and intra-observer variability. 12 randomly chosen radiographs were independently measured for subsidence and angular migration by 2 observers. One observer, blinded regarding the previous measurements results, measured all the radiographs a second time. The second observer measured the radiographs once. The inter-observer variability was calculated between the first measurements of observer 1 and the measurements of observer 2 using the method of Bland and Altman (1986). Intra-observer variability was calculated between the 2 measurements of observer 1. The inter- and intra-observer variability for the distance of the third metacarpal were acceptable (Table 1).

Clinical evaluation

Preoperative data that had been collected included range of motion (extension, flexion, radial deviation, ulnar deviation, pronation, and supination) measured by goniometry and DASH score in the validated Dutch translation (Disability of
Table 1. 95% prediction limits of radiographic measurements. To assess the variability between 2 measurements (either intra- or inter-observer), the difference between these 2 measurements was plotted against their mean. The mean difference would be expected to be zero since the same method was used. With the help of the mean difference and the standard deviation of the differences, the limits of agreement, also known as the 95% prediction limits, were calculated (Bland and Altman 1986).

| Intra-observer | Inter-observer |
|----------------|---------------|
| Third metacarpal distance (mm) | 3.1 | 3.4 |
| Flexion-extension tilt (degrees) | 6.5 | 4.9 |
| Radio-ulnar angulation (degrees) | 3.8 | 4.6 |

Results

Complications

There were 4 intraoperative and 27 postoperative complications, in 22 prostheses (21 patients) (Table 2). Difficulties in closure of the capsule were solved with the use of a Gore-Tex Soft Tissue Patch (WL Gore and Associates Inc., Flagstaff, AZ). Breakout of the stem through the cortex of third metacarpal was noticed on the primary postoperative radiographs in 2 patients who were treated with 14 days of splint immobilization. One of these patients developed a limited range of motion.

Patient satisfaction.

29 patients (32 prostheses) were available for follow-up evaluation; they were examined by an independent investigator (DvH). To assess the function of the prostheses, an objective grip strength and range of motion test was performed together with a subjective DASH- and pain score. The wrists were assessed for pain by scoring on an ordinal scale from 0 to 10, at rest and during activity. Range of motion was measured with a goniometer according to the same protocol as that used preoperatively. To determine the remaining amount of strength of the hand in kg, we calculated the average value after 3 attempts using a Baseline Hydraulic Hand Dynamometer (Fabrication Enterprises, Inc., New York, NY). The Baseline Hydraulic Pinch Gauge (Fabrication Enterprises) was used to measure 3 different types of strength; each is given as an average of 3 attempts. Key pinch strength was measured between thumb pad and the radial side of the second digit, tripod grip strength between thumb pad and the palmar surfaces of the second and third digits, and tip pinch strength between the tip of the thumb and the tip of the second digit. Also, patient satisfaction was scored on a 5-point scale: very satisfied, satisfied, moderate, or unsatisfied. Complications were noted and classified as intraoperative or postoperative complications.

Statistics

Kaplan-Meier survival analysis was used to estimate the cumulative probability of remaining free of revision. The differences between preoperative and postoperative range of motion and DASH score were analyzed using a non-parametric Wilcoxon signed-rank test for data that were not normally distributed (pronation and supination) and the parametric Student t-test was used for normally distributed data (flexion, extension, radial deviation, ulnar deviation, and DASH). Significance was set at a p-value of less than 0.05.
Strength. There were high inter-individual variations in strength. The mean grip strength at follow-up was 13 (SD 8) kg. Tip pinch was 2.8 (SD 1.2) kg, tripod grip strength 4.5 (SD 2.3) kg, and key pinch was 5.7 (SD 2.7) kg. In many patients, other joints on the ipsilateral side of the prosthesis were also affected; 17 patients had dysfunction of the hand, due to deformities and/or pain. 5 patients also had complaints of the elbow and 8 of the shoulder.

Survival
The mean cumulative survival after 87 months was 81% (95% CI: 64–91) (Figure 4). There were 4 relatively early revisions (range 8–22 months) and 3 later revisions (range 59–71 months). After evaluating the follow-up radiographs, 2 additional wrists were scheduled for revision. These 2 patients were not included as revisions in the survival analysis.
with a mean follow-up of 4 years. They reported a probability of survival for the biaxial total wrist replacement of 83% at 8 years with revision surgery as endpoint. We found a high proportion of radiographic loosening. Most of the patients were asymptomatic at that time, which has also been found in other studies (Torchia et al. 1997, Martin et al. 2005, van der Lugt et al. 2010). When a prosthesis has gradually loosened, there will be progressive loss of bone stock (Talwalkar et al. 2005). It is therefore necessary that patients with a biaxial total wrist prosthesis be closely followed, to recognize radiographic loosening while sufficient bone stock remains for revision—even if they are asymptomatic.

We found 31 complications in 21 patients. Cobb and Beckenbaugh (1996) had a similar percentage of complications whereas Takwale et al. (2002) had fewer complications. Other authors have reported some complications; the definitions may not have been the same, however, and for this reason comparison of complication rates is not reliable (Lirette and Kinnard 1995, Courtman et al. 1999, Stegeman et al. 2005). A fourth generation of prostheses is now being used. They are designed to solve the problems of dislocation and loosening, by preserving the distal radio-ulnar joint. However, no long-term evaluations have been published yet.

Despite the high rate of complications, a surprisingly large proportion of patients (27/32), were “very satisfied” or “satisfied” with the result of the operation. Functional range of wrist motion in healthy subjects was determined by Palmer et al. (1985) at 5˚ of flexion, 30˚ of extension, 10˚ of radial deviation, and 15˚ of ulnar deviation. Ryu et al. (1991) reported that 40˚ of wrist extension, 40˚ of wrist flexion, and a total of 40˚ of radial-ulnar deviation is needed to perform most activities of daily living. Mean range of motion in the present study was 29˚ of flexion, 28˚ of extension, 10˚ of radial deviation, and 19˚ of ulnar deviation. Thus, functional range of motion can largely be achieved. The postoperative range of motion was comparable to those in previous studies (Lirette and Kinnard 1995, Cobb and Beckenbaugh 1996, Takwale et al. 2002).

22 of 31 cases had an improved postoperative DASH score (more than 12.6 points); we may therefore conclude that patients gained functional benefit from the surgery. The remaining strength after surgery was comparable with that described in the literature for rheumatoid arthritis (Bodur et al. 2006). Wrist prostheses have no negative effect on strength of the hand and fingers for patients with rheumatoid arthritis.

We had no preoperative pain scores; thus, no comparison with the postoperative score was possible. Considering that the primary indication for surgery was severe wrist pain, we remain confident that the patients had reduced pain scores. We terminated the survival analysis when the number of patients remaining in the sample reached 10% of the initial population. For our study, this was at 87 months when only 4 patients remained. However, because of the small sample size and some early failures, the confidence interval bands were broad quite early in the analysis. Another issue is inclusion of bilateral cases in the statistical analysis. 4 patients had bilateral

### Table 4. Range of motion and DASH score in 32 wrists

| Motion       | Preoperatively | Postoperatively | p-value | n  |
|--------------|----------------|-----------------|---------|----|
| Extension a  | 18 (17)        | 28 (17)         | 0.004   | 30 |
| Flexion a    | 21 (14)        | 29 (17)         | 0.04    | 30 |
| Radial deviation a | 5 (6)  | 10 (8)         | 0.03    | 22 |
| Ulnar deviation a | 4 (6)  | 19 (13)        | < 0.001 | 22 |
| Pronation b  | 80 (5–90)      | 85 (0–95)       | 0.3     | 17 |
| Supination b | 70 (0–90)      | 90 (35–110)     | 0.02    | 17 |
| DASH (0–100) a | 66 (25) | 34 (24)        | < 0.001 | 31 |

a Values are mean (SD)
b Values are median (range)

Because of some missing preoperative data, statistical analysis was only performed with the data of patients having matching pre- and postoperative data. Student’s t-test was used for normally distributed data, and the Wilcoxon signed-rank test was used as a non-parametric alternative.

### Figure 4. Cumulative survival of 40 prostheses with revision surgery defined as failure event. The small vertical spikes represent the censored data.

### Discussion

The biaxial wrist implant, a third-generation wrist prosthesis, was developed to overcome problems with joint imbalance, dislocations, and loosening of the metacarpal component common in the earlier prostheses. In our study of this implant, most patients were satisfied but we found numerous complications with a mean cumulative survival of 81% at 7 years. In addition to revision, there was radiographic evidence of loosening in 22 of the 32 wrists. The implant survival was similar to that in previous reports, but the radiographic evidence of loosening was higher (Cobb and Beckenbaugh 1996, Takwale et al. 2002).

Cobb and Beckenbaugh (1996) followed 57 prostheses for a minimum of 5 years. Radiographic loosening occurred in 14 cases. The survival, with revision as endpoint, at 5 years was 83%. The largest study was performed by Takwale et al. (2002), with a mean follow-up of 4 years. They reported a probability of survival for the biaxial total wrist replacement of 83% at 8 years with revision surgery as endpoint. We found a high proportion of radiographic loosening. Most of the patients were asymptomatic at that time, which has also been found in other studies (Torchia et al. 1997, Martin et al. 2005, van der Lugt et al. 2010). When a prosthesis has gradually loosened, there will be progressive loss of bone stock (Talwalkar et al. 2005). It is therefore necessary that patients with a biaxial total wrist prosthesis be closely followed, to recognize radiographic loosening while sufficient bone stock remains for revision—even if they are asymptomatic.

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total wrist prostheses and 1 patient had both implants revised. We performed a second survival analysis including only the first operated wrist of the bilateral cases, and the survival rate was similar with only a very slightly broader confidence interval.

In conclusion, the biaxial total wrist prosthesis in patients with rheumatoid arthritis had a mean cumulative survival for revision after 7 years of 81% (95% CI: 64–91) with good pain relief, with improved motion, and with most patients satisfied. However, the high complication rate and a worrying amount of radiographic loosening after 5 years are problematic. Regular clinical and radiographic follow-up is therefore necessary.

DvH: collection and analysis of data and writing of the manuscript. PH: data analysis and writing of the manuscript. MdV: initiation and design of the study, and review of the manuscript.

No competing interests declared.

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