Experimental and numerical simulation as a calibration measure of a venturi tube

Abstract

The development of experimental theories has been the normal practice for studying hydraulics and fluid dynamics. Based on the fundamental equations some simplifications are included and through laboratory experimentation many of the relationships that are currently applied have been obtained. With the advancement of technology, the numerical simulation of the government equations has taken an important role in complementing the existing theories. However, it also has a certain level of simplification, so it has not been able to fully replace laboratory experimentation. A combination of both types of analysis, based on fundamental principles (theory), is necessary to obtain reliable results. In the present study, a theoretical, experimental and numerical analysis is applied to the case of flow in a Venturi tube determining that there is a high concordance when the results obtained with each of the methodologies are compared. With this, a reliable methodology is defined to analyze complex fluid flow problems.

Keywords: venturi tube, numerical simulation, experimentation, fluid dynamics, fluid flow

Abbreviation: CFD, Computational Fluid Dynamics

Introduction

Due to the complexity encountered in solving the governing equations of fluid flow, laboratory experimentation has been widely applied to develop experimental theories that help to understand and describe flow processes. However, experimentation has been developed mainly in idealized and simplified environments like laboratory flumes with constant discharge or one dimensional flow. Development of technology has allowed the study of increasingly more complex flow cases. Equipment that measure flow velocity in its three directions and methodologies to track fluid and sediment particles among many others are some of the advantages that have allowed a better knowledge on the hydraulics of flow. With the application of computational fluid dynamics (CFD), the study of hydraulics and fluid dynamics has taken an important step forward. This has permitted the analysis with a very high and detailed resolution of processes such as free surface and turbulent flows, sediment transport, hydraulic structures performance, etc. The CFD solves numerically for a discrete domain the flow governing equations, the Navier-Stokes equations they are non-linear partial differential equations. Nonetheless, the direct solution of the governing equations is possible only in very simple cases due mainly to the high computational resources required. Therefore, simplifications have been applied to solve more complex phenomena. Even though simplifications have been verified under a variety of conditions, a level of validation and corroboration is needed to accept numerical simulations as valid. The Venturi tube is a device that uses the Venturi effect proposed by Giovanni Battista Venturi in 1797 that states the following. A tube that experiences a contraction in its cross section undergoes a pressure reduction due to the decrease of section with its corresponding increase in velocity. The applications of a Venturi tube range from flow measurements to as a mixing device. Therefore it is important to know how it works and to determine calibration (velocity) coefficients that consent the determination of accurate flow parameters (velocity and static pressure). In the present work a theoretical development is compared to experimental measurements and also to numerical simulation to determine the coefficient of the Venturi tube of the Hydraulics and Fluid Dynamics Laboratory of the Engineering Department of University of Cuenca with the main purpose of establishing an analysis methodology that allow an integral study of any flow process in the Laboratory.

Materials and methods

Governing equations

The equations that describe the flow of fluids are known as the Navier-Stokes equations they are non-linear partial differential equations. The equations for an incompressible are presented in their form of conservation of mass (continuity equation) and momentum equations (in three directions x, y, z).

Conservation of mass

\[ \frac{\partial u}{\partial x} + \frac{\partial v}{\partial y} + \frac{\partial w}{\partial z} = 0 \] (1)

Momentum Equations

\[ \frac{\partial}{\partial t} \left( \rho u \right) + \frac{\partial}{\partial x} \left( \rho u^2 \right) + \frac{\partial}{\partial y} \left( \rho uv \right) + \frac{\partial}{\partial z} \left( \rho uw \right) - \frac{\partial p}{\partial x} - \frac{\partial \tau_{ux}}{\partial x} - \frac{\partial \tau_{uy}}{\partial y} - \frac{\partial \tau_{uz}}{\partial z} = 0 \] (2)

\[ \frac{\partial}{\partial t} \left( \rho v \right) + \frac{\partial}{\partial x} \left( \rho uv \right) + \frac{\partial}{\partial y} \left( \rho v^2 \right) + \frac{\partial}{\partial z} \left( \rho vv \right) - \frac{\partial p}{\partial y} - \frac{\partial \tau_{vx}}{\partial x} - \frac{\partial \tau_{vy}}{\partial y} - \frac{\partial \tau_{vz}}{\partial z} = 0 \] (3)

\[ \frac{\partial}{\partial t} \left( \rho w \right) + \frac{\partial}{\partial x} \left( \rho uw \right) + \frac{\partial}{\partial y} \left( \rho vw \right) + \frac{\partial}{\partial z} \left( \rho w^2 \right) - \frac{\partial p}{\partial z} - \frac{\partial \tau_{wx}}{\partial x} - \frac{\partial \tau_{wy}}{\partial y} - \frac{\partial \tau_{wz}}{\partial z} = 0 \] (4)

Where: \( p \) is the fluid density, \( p \) is pressure; \( g \) is the acceleration due to gravity, \( \tau_{ij} = \mu \left( \frac{\partial u_i}{\partial x_j} + \frac{\partial u_j}{\partial x_i} \right) \), and \( \mu \) is the coefficient of viscosity for a Newtonian fluid.
Venturi tube operation is based on the Bernoulli’s principle or Bernoulli’s equation. Starting from the momentum equations with the assumptions that friction terms are considerable lower compared with the other terms in the equation, the flow is along a streamline, for permanent flow and for incompressible fluid (constant density), momentum equation results in the following form.1

\[
z + \frac{p}{\gamma} + \frac{v^2}{2g} = \text{constant or}
\]

\[
z_1 + \frac{p_1}{\gamma} + \frac{v_1^2}{2g} = z_2 + \frac{p_2}{\gamma} + \frac{v_2^2}{2g}
\]  

(5)

Applying eq. (5) to the normal (section 1) and contracted (section 2) sections of a Venturi tube the following relation for the theoretical velocity in section 2 is obtained.

\[
V_2 = \sqrt{\frac{2g(h + (p_1 + p_z) / \gamma)}{1 - \left(\frac{d_z}{d_1}\right)^4}}
\]  

(6)

Where: \( h \) is the differential position between normal and contracted section, \( p_z \) normal and contracted section pressure, \( \gamma \) fluid specific weight and \( d_1 \) and \( d_z \) normal and contracted diameter. Since Bernoulli’s equation does not consider friction effects the obtained velocity is theoretical. The real value of the contracted velocity has to be determined for each Venturi tube since it will depend on Venturi’s dimensions, material and form. To make real the theoretical velocity, it is multiplied by a correction factor denominated as discharge coefficient \( C_f \).

\[
V_{2r} = C_f V_2
\]  

(7)

**Experimental configuration**

The experimental simulations were performed in the Hydraulics and Fluid Dynamics Laboratory of the Civil Engineering Department of University of Cuenca. The equipment used is the Armfield Fluid Friction Measurements unit (Armfield C6MkII). The pipes system includes, among others devices, a Venturi tube that allows the simulation of the flow throughout it as well as the measurement of parameters such as the pressure in the normal and contracted sections. In Figure 1 the pipe system and the Venturi tube detail are shown. The experimental configuration comprises a pump and a recirculation system. Five experiments with different discharges were planned. In Table 1 the discharge values simulated are presented. The devices shown in Figure 1 allow the measurement of the pressure value in the interest points (normal and contracted sections).

**Table 1** Experimental discharge values

| Experiment | Discharge (l/s) |
|------------|----------------|
| 1          | 0.204          |
| 2          | 0.355          |
| 3          | 0.49           |
| 4          | 1.011          |
| 5          | 1.216          |

Numerical simulation

The CFD is used to simulate numerically the flow through the Venturi. The CFD software package used is OpenFOAM an open source code. The numerical method used by OpenFOAM in the present simulation is the finite volume method and the solver is icoFoam. The Gauss linear scheme is used for the gradient, divergence, and laplacian operators. The interpolation scheme is set to linear. Additionally, for the component of gradient normal to a cell face the option orthogonal is selected. The Gauss linear scheme used has second order of accuracy.13 Therefore, the results have a second order precision. Simulations were considered converged when the residuals for the continuity, pressure, and momentum equations drop below the value of \( 1 \times 10^{-6} \).

**Domain and boundary conditions**

The simulated domain comprises the contraction part of the Venturi. Explicitly, it starts with the normal section with a diameter of 2.40cm and the contraction to a diameter of 1.40cm is produced in 2.6cm. The boundary conditions used for all simulations were: along the central axis of the Venturi an axisymmetric boundary condition was enforced. The device walls were given a wall no-slip or zero velocity condition. The entrance was given a constant uniform velocity corresponding to the real velocity of the Venturi. The CFD is used to simulate numerically the flow through the Venturi tube structure.

**Figure 1** Venturi tube structure.

**Figure 2** Numerical Simulation domain (coarsest mesh).

**Grid Convergence Index**

The Grid Convergence Index (GCI) is used to determine whether the grid independence has been reached.14 It permits to quantify the error due to domain discretization. A range of certainty can be determined for the solution obtained with the fine grid. This range constitutes the range that would contain the exact solution with a reliable probability.14 The GCI is determined with the following expression.

\[
GCI \left[ \text{fine grid} \right] = F_r \left| \frac{r'}{r} - 1 \right|
\]  

(8)

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$\varepsilon = \frac{f_2 - f_1}{f_1}$ \hspace{1cm} (9)

Where, $F_s$ is the factor of safety of the method, $r$ is grid refinement ratio ($h_2/h_1$), $s$ is the order of accuracy of the numerical solution $f_1$ and $f_2$ corresponds to the numerical solution with different grid resolution refined with $s$ factor. Recommendations for $F_s$ state values from 1.0 to 3.13 Depending on the level of uncertainty present on the simulation this value has to be assumed. A value of 3.0 can be seen as a conservative value required in cases of high uncertainty. However, this value can be reduced when a better knowledge or of the simulated processes is had. Moreover, in the cases when three consecutive finer meshes are used a factor of 1.25 can be used.16

Results and discussion

Experimental simulation

As stated before, five experimental simulations were performed.

Table 2 Experimental simulations results

| Experiment | Discharge (l/s) | Velocity (m/s) | Pressure (meters head) |
|------------|----------------|----------------|------------------------|
|            |                | Normal         | Contracted             | Normal         | Contracted             |
| 1          | 0.204          | 0.451          | 1.326                  | 21.822         | 21.699                  |
| 2          | 0.355          | 0.785          | 2.307                  | 21.013         | 20.721                  |
| 3          | 0.49           | 1.083          | 3.184                  | 20.020         | 19.482                  |
| 4          | 1.011          | 2.235          | 6.569                  | 13.219         | 11.12                   |
| 5          | 1.216          | 2.688          | 7.901                  | 9.120          | 6.067                   |

Table 3 Theoretical results

| Theoretical | Discharge (l/s) | Velocity (m/s) | Pressure (meters head) |
|-------------|----------------|----------------|------------------------|
|             |                | Normal         | Contracted             | Normal         | Contracted             |
| 1           | 0.204          | 0.451          | 1.326                  | 21.822         | 21.743                  |
| 2           | 0.355          | 0.785          | 2.307                  | 21.013         | 20.773                  |
| 3           | 0.49           | 1.083          | 3.184                  | 20.020         | 19.563                  |
| 4           | 1.011          | 2.235          | 6.569                  | 13.219         | 11.274                  |
| 5           | 1.216          | 2.688          | 7.901                  | 9.120          | 6.306                   |

Numerical simulation

Applying OpenFoam solver icoFoam and the conditions stated before the numerical simulations were performed. All the five cases were also simulated numerically. The results are shown in Table 4. In Figure 3 pressure and velocity distribution along the domain obtained with the numerical simulation is shown. Comparing $V_2$ and $p_2$ for all three types of analysis and considering the experimental simulation as the comparison parameter the following can be punctuated. There is not exist accountable differences between theoretical and numerical results. This is due to the fact that the same assumptions are made to obtain Bernoulli’s equation (no friction effects) and for the numerical model (smooth boundary without friction effects). The greatest error or difference registered correspond to $p_2$ (or differential pressure) when experimental and theoretical values are compared. This error is 4%. For the contracted velocity the greatest error registered is 2%. In Figure 4 a graphical comparison is presented. The GCI calculation was performed with discharge 2 (0.355 l/s). As can be observed in Table 5 all three grid resolutions used have given the same differential pressure. This means that grid independence has been reached and the error due to discretization has been eliminated. The results from coarsest mesh can be used with a higher level of certainty avoiding the computational cost of simulating the intermediate or finest mesh.

With a given discharge and for the normal and contracted cross section the normal and contracted velocities were calculated. Measurements of the pressure were taken for the normal and contracted sections. In Table 2 the experimental results are presented.

Theoretical analysis

Using eq. (6) and reorganizing its terms, an equation to determine $\Delta p(p_1 + p_2)$ is obtained as follows.

$$\Delta p = \frac{V_2^2}{2g} \left[1 - \left(\frac{d_2}{d_1}\right)^4\right]$$ \hspace{1cm} (10)

With the dimensions of the Venturi $\Delta p$ was determined. Considering $p_1$ (taken from the experimental measurements) $p_2$ was calculated for the theoretical analysis (Table 3).
Table 4 Numerical simulation results

| Numerical simulation | Discharge (l/s) | Velocity (m/s) | Pressure (meters head) |
|----------------------|----------------|---------------|------------------------|
|                      |                | Normal        | Contracted             | Normal        | Contracted             |
| 1                    | 0.204          | 0.451         | 21.822                 | 21.742        |
| 2                    | 0.355          | 0.785         | 21.013                 | 20.771        |
| 3                    | 0.49           | 1.075         | 20.02                  | 19.533        |
| 4                    | 1.011          | 2.219         | 13.219                 | 11.243        |
| 5                    | 1.216          | 2.649         | 9.12                   | 6.282         |

Figure 3 Pressure and velocity distribution along the domain.

Table 5 Differential pressure numerical results with different grid resolution

| Number of cells | $\Delta p$ (water head) |
|-----------------|-------------------------|
| 20              | 0.240                   |
| 40              | 0.240                   |
| 80              | 0.240                   |

Figure 4 Experimental, Theoretical, and Numerical Simulations comparison.

Conclusion

Theoretical, experimental, and numerical analyses were performed to simulate flow characteristics of a Venturi tube. Negligible differences were reported between theoretical and numerical simulations. On the other hand, experimental simulations show greater “error” values. However, the differences registered are lower than 5%. In laboratory procedures some level of error is expected due to Laboratory configurations. In the present study an analysis methodology has been applied using three important axes of hydraulics and fluid dynamics studies. Some theoretical developments rely on hypothesis and simplifications that not always fit real conditions. Experimental procedures some times are idealized representation of real phenomena. Numerical simulations solve the governing equations. However, a level of simplification is always present. Therefore, an integrated analysis that contains the contribution of these three main axes reduces the uncertainty and strengthens the results.

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Conflict of interest

The authors declare no conflict of interest.

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