Ordered Attention for Coherent Visual Storytelling

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Figure 1: To promote story coherence with consistent grounding across ordered images, we propose Ordered Image Attention (OIA). By collecting directional interactions, we can identify significant objects throughout the story. In total, five attention maps are calculated, one for each image. The border of attended images indicates how important an image is according to the Image-Sentence Attention (ISA).

ABSTRACT

We address the problem of visual storytelling, i.e., generating a story for a given sequence of images. While each story sentence should describe a corresponding image, a coherent story also needs to be consistent and relate to both future and past images. Current approaches encode images independently, disregarding relations between images. Our approach learns to encode images with different interactions based on the story position (i.e., past image or future image). To this end, we develop a novel message-passing-like algorithm for ordered image attention (OIA) that collects interactions across all the images in the sequence. Finally, to generate the story’s sentences, a second attention mechanism picks the important image attention vectors with an Image-Sentence Attention (ISA). The obtained results improve the METEOR score on the VIST dataset by 1%. Furthermore, a thorough human study confirms improvements and demonstrates that order-based interactions significantly improve coherency (64.20% vs. 28.70%). Source code available at https://github.com/tomateb/OIAVist.git

CCS CONCEPTS
• Computing methodologies → Natural language generation; Scene understanding.

KEYWORDS
Visual grounding, Visual storytelling, Ordered Attention

1 INTRODUCTION

Visual Storytelling (VST) [18, 29] – the task of generating a story based on a sequence of images – goes beyond a basic understanding
of visual scenes and can be applied in many real-world scenarios, e.g., to support the visually impaired. Moreover, VST reflects on the creative ability of intelligent systems. Although similar in concept to other cognitive tasks such as image captioning and visual question answering, VST differs as it requires reason over a sequence of images while simultaneously ensuring coherence across multiple generated sentences. To achieve this, VST methods need to address two major challenges: the first is visual and relates to grounding the story’s text to the images. The second is linguistic and relates to the quality of the story. Both challenges can be described in terms of coherency: the story should be coherent by itself, and consistent with the images.

Prior research on VST started to address the aforementioned challenges. Early works expand captioning [5, 40, 44], focusing sentence generation mainly on the current image. This limits the ability to create a narrative that includes consistent visual information. Prior work also makes limited use of temporal dependence and history, e.g., sentences that have already been generated are not used. Consequently, the output prone to linguistic errors such as repetitiveness [26]. To mitigate these issues, later works strive to generate more meaningful stories via adversarial and reinforcement learning [17, 42], which remain delicate to train.

Importantly, images are not independent. For example, if the first image in a sequence shows a protest, the model may want to focus on signs in later images. Conversely, if the last image shows a ring on a finger, then the model should pay attention to wedding-related objects and activities in the preceding images. This is important for VST because sentences are created per image but are part of a story. Hence, objects that the model is focusing on in one image should be conditioned on the selection in other images.

To do this we develop a novel model which (1) implicitly reasons over objects, activities, and their temporal dependencies in each image; and which (2) improves the coherency of the narrative. To reason over objects and activities in each image, i.e., to understand their dependencies and their temporal ordering, we introduce ordered image attention (OIA). As illustrated in Fig. 1, for each image, OIA accumulates representation information from objects detected within the corresponding image into an attended image representation. Importantly, accumulation factors depend on whether the image precedes or succeeds the image for which we are currently generating the sentence, which permits to establish an order. The attended image representations are subsequently summarized into a context embedding via an Image-Sentence Attention (ISA) unit, before being used for sentence decoding.

In addition, to alleviate common linguistic mistakes like repetitiveness and to promote coherence in the story, we incorporate information from the story generated up to the current sentence into the sentence generation decoder. Specifically, the decoding strategy decays the probability of a word if it has already been used in the story. The decoder also maintains a separate prior over the output probability distribution, independent from the language generation unit. This prior is based on counts of the words that were already predicted in the story. Both the prior, and the Recurrent Neural Net (RNN) decoder output are combined to predict the next word in the sentence.

Empirical results on the challenging VIST dataset demonstrate that the proposed method generates stories with an improved narrative quality. The method outperforms prior state-of-the-art by 1% on the METEOR score. Examples of stories generated by the approach are shown in Fig. 1. We also present a user study demonstrating the advantage of the model in terms of coherency (64.20% vs. 28.70%).

2 RELATED WORK

Vision-Language has been an active area of research for many years, addressing tasks such as image/video captioning, paragraph generation, and visual question answering. We briefly review those related areas in the following.

2.1 Visual Storytelling

Huang et al. [18] introduce the visual storytelling task. Visual storytelling is similar to captioning. Thus, early methods adapted captioning mechanisms, introducing context between story sentences [11]. Following, Kim et al. [21] used a seq2seq [35] approach built on a decoding sampling strategy to reduce repetition. Here, we use a dynamic data-driven approach where each word is penalized differently based on its average count. Next, Wang et al. [42] discuss the difficulty of learning stories with imaginary details that do not appear in the imagery. To that end, an adversarial reward system is used to improve the output stories. Several works use a reinforcement learning approach based on the interrelationships between images [17]. Recently, state-of-the-art results were obtained by generating scene graphs for each image in the sequence [41]. Following, Li et al. [22] and Zhang et al. [49] rely on preprocessing to ground visual elements. Yang et al. [45] and Hsu et al. [16] enrich the data with an external word common-sense knowledge graph. Wang et al. [41] model relations within the image with scene graphs, which requires expensive annotations and Qi et al. [30] modify the Transformer architecture to model inter region relations. Hong et al. [15] also uses scene graphs with global embeddings to achieve coherence. Instead, our model forms ordered attention, which permits the focus on consistent objects without additional supervision. More recent approaches [8, 34, 47] employ large pretrained models for visual storytelling. In our method, we do not rely on large-scale external knowledge.

2.2 Image Captioning

Barnard et al. [3] first explored annotating images with text. Since then, image/video captioning has seen a surge of research activity. Initial work utilized pre-trained image embeddings from a CNN network. The success of attention mechanisms for language translation quickly transferred to image captioning as well [44]. Later work leveraged advances in object detection and proposed a bottom-up/top-down attention approach to attend to specific objects in the image instead of fixed spatial regions [1]. Further improvements include modeling spatial and semantic interactions with graph neural networks and transformers [7, 12, 27]. A key factor for improving model performance is pre-training on large amounts of data and fine-tuning on curated supervised datasets [6, 23, 50]. Recently, multimodal pre-training models like CLIP are enabling large-scale
Appendix

The goal of visual storytelling is to generate a story, composed of visual story from multiple cues. This means that only objects related to the narrative should be highlighted, which is the focus of our work.

2.3 Multimodal Attention

Multimodal problems are characterized by input data that comes from different domains, e.g., visual and linguistic. This raises two challenges: 1) how to model interactions between different domains, and 2) how to manage the large input data. Considering those challenges, attention has been a prominent tool as it models interactions to select the important elements. In early work, Xu et al. [44] used interaction-based attention with the image at each caption generation step. This idea was later extended to visual question answering [43]. To imitate multi-step reasoning, Yang et al. [46] stacked attention modules sequentially. Later, many works concentrated on better vector-fusion modeling [4, 9, 20, 48]. Importantly, Lu et al. [25] suggested attending to the visual and textual modalities separately. Afterward, Kim et al. [19] proposed a bilinear module that efficiently generates attention for every pair. Following Lu et al. [25], Schwartz et al. [32, 33] suggested a general framework that extends attention to any number of utilities via local and interaction-based factors. We improve upon those ideas by suggesting an ordered attention. This ensures that interaction modeling is affected by the image position in a sequence.

3 METHOD

The goal of visual storytelling is to generate a story, composed of \(N\) ordered sentences \(\{y_s\}_{1 \leq s \leq N}\), given an ordered sequence of images \(I = \{I_l\}_{1 \leq l \leq N}\). Each sentence \(y_s = (y_{s,0}, \ldots, y_{s,t}, \ldots)\) is composed of words \(y_{s,i} \in \mathcal{Y}\) from vocabulary \(\mathcal{Y}\).

The order in which the images are given is essential as it defines the plot line of the story. The story should be focused, i.e., each sentence should be related to the remainder of the story. Importantly, the sentences should form a coherent body of text describing the set of images, and not only a set of related information. For instance, the story “The church was beautiful. The bride and groom walk down the aisle. The cake was amazing.” is less coherent than: “We went to the church for the wedding today. The bride and groom were excited for the day. Both cut the cake together.”

Overview: To address this challenge, we develop the model illustrated in Fig. 2. It infers conditional probabilities \(p'(y_{s,t}|y_{s,1:t-1},c_s)\) for the \(t\)-th word \(y_{s,t} \in \mathcal{Y}\) in sentence \(y_s\) given the previous word \(y_{s,t-1}\) and the context embedding \(c_s\) for sentence \(s\). The context embedding \(c_s\) summarizes region representations \(r_{i,k}\) of all \(K\) object regions across all \(N\) images \(I_l (i \in [1,N], k \in [1,K])\) via Ordered Image Attention (OIA) (Sec. 3.2) and Image-Sentence Attention (ISA) (Sec. 3.3). Specifically, when generating sentence \(s\), OIA computes an attended image representation \(a^s_t\) for every image \(I_l\) by attending to the \(K\) region representations \(r_{l,k}\) (Sec. 3.2). These attended image representations \(a^s_t\) are subsequently summarized into the context embedding \(c_s\) via an image-sentence attention (Sec. 3.2).

Below we first discuss computation of the attended image representation \(a^s_t\) (Sec. 3.2), before detailing computation of the context embedding \(c_s\) (Sec. 3.2) and computation of the conditional probabilities \(p'(y_{s,t}|y_{s,1:t-1},c_s)\) (Sec. 3.3).

Ordered Image Attention (OIA) is designed to 1) form a structure across ordered images and to 2) select the relevant objects per image. For this we model preceding and subsequent interactions separately using different attention factors. We calibrate each factor’s importance with trainable scalars, which forms a graph of dependencies between the images. For each sequence of \(N\) images, the model infers a total of \(N^2\) attention maps, one per image for each sentence. We detail this module next.

### 3.1 Ordered Image Attention (OIA)

**Attention Belief.** For each image \(I_l = \{r_{l,j}\}_{1 \leq j \leq K}\) we consider a set of \(K\) regions, represented by their feature vectors \(r_{l,k} \in \mathbb{R}^d\), where \(d\) is the objects’ embedding dimension. Suppose we are currently generating sentence \(y_s (1 \leq s \leq N)\). To do this we first...
which is a message from a subsequent image we factorize the belief $b_i$ where $b_i$ is the attention belief highlighting the importance of the $k$-th object in the $i$-th image when generating the $s$-th sentence. Importantly, for every image $i$, we require $b_{i,k}^s$ to be a valid probability distribution, i.e., we also enforce $\sum_{k=s}^{bwd} b_{i,k}^s = 1 \forall s, i$.

The object attention belief $b_{i,k}^s$ is dependent on all the input data, i.e., other objects and images. To avoid complex computation, we factorize the belief $b_{i,k}^s$ into two pairwise dependencies that preserve the order, and a local term. For the pairwise terms we use $b_{i,j}^{bwd}$, which is a message from a preceding image $I_j$, or $b_{i,j}^{fwd}$, which is a message from a subsequent image $I_j$. We also use $\mu_{i-i}$ for self-messages. Additionally, we include a local factor $\Psi_{i}(r_{i,k})$ that considers the object representation. Unlike the messages mentioned before, the local factor does not rely on interactions with other objects. We aggregate all the messages along with the local factor as illustrated in Fig. 3. For normalization we employ a softmax. Formally we compute the attention belief $b_{i,k}^s$ by distinguishing three cases. If $i = s$ we have

$$b_{i,k}^s \propto \exp(a_i^s \Psi_i(r_{i,k}) + \sum_{j<i} a_{i,j}^s \Psi_{i,j}(r_{i,k}) + \sum_{j>i} a_{i,j}^s \Psi_{i,j}(r_{i,k})),$$

If $i < s$ we use

$$b_{i,k}^s \propto \exp(a_i^s \Psi_i(r_{i,k}) + \sum_{j<i} a_{i,j}^s \Psi_{i,j}(r_{i,k}) + \sum_{j>i} a_{i,j}^s \Psi_{i,j}(r_{i,k})).$$

If $i > s$ we obtain

$$b_{i,k}^s \propto \exp(a_i^s \Psi_i(r_{i,k}) + \sum_{j<i} a_{i,j}^s \Psi_{i,j}(r_{i,k}) + \sum_{j>i} a_{i,j}^s \Psi_{i,j}(r_{i,k})).$$

In all three cases $a_i^s, a_{i,i}^s, a_{i,j}^s \in \mathbb{R}$ are scalars used to calibrate the importance of different messages for a given sentence. These scalars form a dependency structure between images for each of the generated sentence indices. Intuitively, when we generate the first sentence, the attention belief might depend more on subsequent images, to correctly identify the story event, e.g., a wedding, a parade, etc. Thus, the scalars will promote interaction with later images. An analysis of these scalars is provided in the appendix. Next, we define the different types of messages.

3.1.2 Pairwise Messages and Factors. A message aggregates interaction scores from an image to an object. The three messages $b_{j-i}^{bwd}, b_{j-i}^{fwd}$ and $\mu_{i-i}(r_{i,k})$ are computed as follows:

$$\psi_{bwd}(r_{i,k}, r_{j,k}) = \sum_{k'=1}^{K} \Psi_{bwd}(r_{i,k}, r_{j,k}),$$

(5)

$$b_{j-i}^{fwd}(r_{i,k}) = \sum_{k'=1}^{K} \Psi_{fwd}(r_{i,k}, r_{j,k}),$$

(6)

$$\mu_{i-i}(r_{i,k}) = \sum_{k'=1}^{K} \Psi_{i,i}(r_{i,k}, r_{j,k}).$$

(7)

Importantly, these messages collect three different types of order-dependent interaction factors: (1) A backward image interaction, namely $\Psi_{bwd}(r_{i,k}, r_{j,k})$. This interaction models relations to the preceding $j$-th image in the sequence. (2) A forward image interaction, namely $\Psi_{fwd}(r_{i,k}, r_{j,k})$. This interaction models relations to the subsequent $j$-th image in the sequence. (3) The self interaction factor, namely $\Psi_{i,i}(r_{i,k}, r_{j,k})$, which takes into account interactions between objects within the image. We formally define the different factors next.

Interaction factors: A commonly used practice to capture interactions across attention mechanisms is to first embed the elements into a joint Euclidean space followed by a dot-product [10, 32, 33, 38]. While we follow the same practice, we define three types of interaction factors to preserve the order. Consider two objects, $r_{i,k} \in I_i$ from the sentence-processing corresponding and $r_{j,k'} \in I_j$ from the interacting image. We describe three types of interactions for interactions with subsequent images (i.e., $j > i$) we use

$$\Psi_{fwd}(r_{i,k}, r_{j,k'}) = \frac{L_{fwd} r_{i,k}}{\|L_{fwd} r_{i,k}\|_2} \cdot \frac{R_{fwd} r_{j,k'}}{\|R_{fwd} r_{j,k'}\|_2},$$

(8)

For interactions with preceding images (i.e., $j < i$) we use

$$\Psi_{bwd}(r_{i,k}, r_{j,k'}) = \frac{L_{bwd} r_{i,k}}{\|L_{bwd} r_{i,k}\|_2} \cdot \frac{R_{bwd} r_{j,k'}}{\|R_{bwd} r_{j,k'}\|_2},$$

(9)
where \( v \) weights following Eq. (10) and Eq. (11) respectively.

In a next step we summarize the attended image representations. Given an object \( r_i \), we define the local factor as,

\[
\Psi_i(r_{i,k}) = a^\top \text{ReLU}(V r_{i,k}),
\]

where \( a \in \mathbb{R}^d \), \( V \in \mathbb{R}^{d \times d} \) are trainable weights.

### 3.2 Image-Sentence Attention (ISA)

In a next step we summarize the attended image representations \( a_i^t \) produced by OIA to compute the context embedding \( c_s \) for the sentence \( s \) that we wish to generate. For this we use the Image-Sentence Attention (ISA) unit. It picks the relevant image context for generating the specific sentence. Formally we obtain the context embedding via

\[
c_s = \sum_{i=1}^N \tilde{b}_{s,i} a_i^t,
\]

where attention factors

\[
\tilde{b}_{s,i} \propto \exp \left( \tilde{a}_s \Psi_j(a_i^t) + \tilde{a}_{s,s} \tilde{b}_{s-s} (a_i^t) \right),
\]

and where \( \tilde{a}_s, \tilde{a}_{s,s} \in \mathbb{R} \) are scalars. To avoid spurious correlations between sentences, we consider only self attentions and a local factor. This is illustrated in Fig. 4. The self-message of the attended image representation \( a_i^t \) is

\[
\tilde{b}_{s-s} (a_i^t) = \sum_{j=1}^N \Psi(a_i^t, a_j^t).
\]

Finally, the self and local factors are defined with a different set of weights following Eq. (10) and Eq. (11) respectively.

### 3.3 Story Decoding

The goal at each timestep of decoding is to compute the conditional probability \( p(y_{s,t} | y_{s,t-1}, c_s) \) where \( y_{s,t} \in \mathcal{Y} \) is the \( t \)-th word in sentence \( y_s \), \( \mathcal{Y} \) is the vocabulary and \( c_s \) is the context embedding detailed in Sec. 3.2. For this we use a GRU recurrent unit, tasked with generating probabilities over the vocabulary conditioned on the context embedding \( c_s \) and the previously generated token \( y_{s,t-1} \):

\[
p(y_{s,t} = w | y_{s,t-1}, c_s) \propto \exp(\beta_{s,t} \cdot g_w(y_{s,t-1}, h_{s,t-1}, c_s) + (1 - \beta_{s,t}) \cdot f_w(\phi_{s,t})),
\]

where \( g_w \) is the output of a GRU unit for the word \( w \). We set the GRU hidden dimension to \( d \). \( h_{s,t-1} \in \mathbb{R}^d \) is the hidden state at timestep \( t - 1 \) for sentence \( s \). \( f : \mathbb{R}^{|\mathcal{Y}|} \rightarrow \mathbb{R}^{|\mathcal{Y}|} \) is a learned prior over the vocabulary based on a bag-of-words prior histogram \( \phi_{s,t} \), which we describe in the next paragraph. The purpose of \( f \) is to reduce text repetitions. \( f_w \) denotes the value of \( f \) for a word \( w \). We also incorporate a calibration gate \( \beta_{s,t} : \mathbb{R} \rightarrow [0, 1] \) for functions \( f \) and \( g \) using

\[
\beta_{s,t} = \sigma \left( \upsilon_{\beta} \tanh(G_g h_{s,t} + G_f W_t(\phi_{s,t})) \right).
\]

Here, \( G_g \in \mathbb{R}^{d \times d} \) and \( G_f \in \mathbb{R}^{d \times d} \) are trained projections of the GRU hidden state and the bottleneck layer respectively, \( \upsilon_{\beta} \in \mathbb{R}^d \) are learned weights and \( \sigma \) is the sigmoid function. \( W_t \) is obtained from the prior as discussed next.

**Bag-of-words (BOW) prior:** Remembering history during storytelling permits to stay on topic and advance the story in the desired direction. Although quite intuitive, mimicking this ability is not trivial. E.g., most approaches for VST generate all the sentences in parallel. Converting the parallel sentence generation into a sequential one implies a major computational overhead during training.

To address this, we propose a simple yet effective learnable framework that does not require sequential training while still exploiting information found in prior sentences. The history is represented via a bag-of-words histogram \( \phi_{s,t} \), which includes all words that have been used until timestep \( t \) for the \( s \)-th sentence. During training, we initialize \( \phi_{s,t=0} \) with the ground truth history counts found in the previous \( s - 1 \) sentences. We update the statistics at each timestep with the predicted word \( y_{s,t} \) for \( s' < s \), and produce the next state of the counter \( \phi_{s,t+1} \). At inference we generate sentences sequentially and update \( \phi_{s,t} \) with the predicted words. \( \phi_{s,t} \) is fed through a shallow bottleneck network to obtain the prior \( f \), composed of two layers \( W_1 \in \mathbb{R}^{d \times |\mathcal{Y}|} \) and \( W_2 \in \mathbb{R}^{d \times d} \) without activation, where \( d \) is the bottleneck dimension:

\[
f(\phi_{s,t}) = W_2(W_1(\phi_{s,t})).
\]

Also note the use of \( W_t(\phi_{s,t}) \) in the gate (Eq. (16)).

**Intra-repetition regularization:** To regularize intra-repetitions, we decay the probability of previously used words during sentence generation. A critical aspect of this approach is to exclude words that appear frequently in the language (e.g., was, were, am). For this we pre-process the training set to calculate the average story frequency \( p(w) \) of a word \( w \) via \( p(w) = \# \text{ appearances of word } w / \# \text{ stories } w \text{ was used} \). The final count for word \( w \) at timestep \( t \) is calculated as \( \phi_{s,t}(w) = \max[0, \phi_{s,t}(w) - p(w) + 1] \). Intuitively, a word will not be penalized before it is used more than the prior belief average \( p(w) \). The final probability for word \( w \) being used is given by

\[
p'(y_{s,t} = w | y_{s,t-1}, c_s) = \frac{p(y_{s,t} = w | y_{s,t-1}, c_s)}{\pi \cdot \phi_{s,t}(w) + 1},
\]

where \( \pi \geq 0 \) is a constant hyper-parameter. A penalty of 2 proved to work best on the validation set.
Table 1: Quantitative results on the VIST dataset for METEOR, BLEU-1 . . . 4, ROUGE-L and CIDEr. The primary metric is METEOR. The ‘Img Feat’ column describes the pretrained image features. All models utilize a ResNet [13] backbone except CS&T which employs an Inception v3 model [36]. FC and Spatial refer to features extracted from the penultimate layer and the preceding one accordingly. F-RCNN are based on [1].

| Method              | M     | B-1   | B-2   | B-3   | B-4   | R     | C     | Img Feat |
|---------------------|-------|-------|-------|-------|-------|-------|-------|----------|
| CS&T [11]           | 34.4  | 60.1  | 36.5  | 21.1  | 12.7  | 29.2  | 7.1   | FC       |
| AREL [42]           | 35.0  | 63.8  | 39.1  | 23.2  | 14.1  | 29.5  | 9.4   | FC       |
| KS [45]             | 35.2  | 66.4  | 39.2  | 23.1  | 12.8  | 29.9  | 12.1  | FC       |
| HSRL [17]           | 35.2  | -     | -     | -     | 12.3  | 29.5  | 8.4   | Spatial  |
| StoryAnchor [49]    | 35.5  | 65.1  | 40.0  | 23.4  | 14.0  | 30.0  | 9.9   | FC       |
| SGVST [41]          | 35.8  | 65.1  | 40.1  | 23.8  | 14.7  | 29.9  | 9.8   | F-RCNN   |
| SGEEmb [15]         | 35.6  | 62.2  | 38.7  | 23.5  | 14.8  | 30.2  | 8.6   | F-RCNN   |
| Ours                | 36.8±0.1 | 68.4±0.7 | 42.7±0.3 | 25.2±0.2 | 15.3±0.2 | 30.2±0.1 | 10.1±0.2 | F-RCNN   |

4 RESULTS

Dataset: To train and test the model we use the VIST dataset. All images were collected from Flickr albums. All images from a story were taken from the same album. Each image sequence has five reference stories. Approximately 2.5 of the stories are based on human annotations, while the rest are rewrites. The overall numbers are 40,098 training stories, 4,988 validation stories, and 5,050 test stories.

Image Representation: An initial pre-processing step represents each of the input images \( i_j \) via \( K \) regional features \( r_{i,j} \in \mathbb{R}^d, 1 \leq k \leq K \). For this we use bottom-up attention features [1]. Specifically, for each image \( i_j \) we first extract the top \( K \) region features \( e_{i,j,k} \in \mathbb{R}^m \). Hereby, \( r_{i,j} \) is an \( m \)-dimensional feature vector extracted from a pre-trained image classification network [13] along with their respective bounding boxes \( b_{i,j,k} \in \mathbb{R}^d \), and classes \( c_{i,j,k} \in \mathbb{N} \). The final \( d \)-dimensional representation \( r_{i,j} \in \mathbb{R}^d \), of each region is defined by a combination of the extracted semantic features. Formally,

\[
r_{i,j} = W_r [W_e e_{i,j,k} + W_b b_{i,j,k} + E_c (c_{i,j,k})],
\]

where \( W_r \in \mathbb{R}^{d \times Kd}, W_e \in \mathbb{R}^{d \times Km}, W_b \in \mathbb{R}^{d \times Kb}, \) and \( E_c \) are trainable parameters shared between all images. We set \( K = 36 \) in our proposed model. Biases and normalization are omitted for readability.

Evaluation metrics: As suggested by the creators of VIST, METEOR [2] correlates best with human judgement. We also report BLEU [28], ROUGE [24], and CIDEr [39] and compare to prior work where available. The metrics are based on word correspondence with human references, which is unsuitable for measuring visual storytelling quantities such as coherence. For example, the ROUGE and CIDEr scores are almost identical for all the recent years’ baselines. While our experiments indicate statistically significant improvements across all metrics, we emphasize that human evaluation are currently the most reliable way to evaluate visual storytelling approaches.

4.1 Quantitative analysis

Comparison to state-of-the-art: In Tab. 1 we compare the method to recent baselines. Early methods did not take into account visual-spatial information (i.e., they employed FC features), which harms the performance (e.g., 35.5% vs. 36.8% on METEOR). Wang et al. [41] utilize image representations similar to our approach but do not consider relations between different images, resulting in a 1% drop on METEOR, showing that ordered structure encoding with OIA is beneficial. SGVST and StoryAnchor map images to distinct topics based on external knowledge. On the other hand, our approach is trained end-to-end. Furthermore, our image representations depend on all the images in a sequence. In contrast, SGVST uses scene graphs. Such models are pre-trained with an external model for generating scene graphs. Finally, Yang et al. [45] enhance the input with an external commonsense dataset. CIDEr scores are significantly higher, yet this improvement is not reflected in all metrics. Our work improves the state-of-the-art METEOR score from 35.8% to 36.8%. This increase is larger than the 0.8 increase of all advances since the 2018 VIST challenge (i.e., 35.0% vs. 35.8%).

Human Evaluation: Due to the subjective nature of the VST task, a human evaluation is required. We randomly selected 150 image sequences from the test set and asked three MTurk annotators to rank them or assess them with other methods. We use the AREL as a baseline. Further, our method of generating coherent stories is tested using a slightly weaker variation of the method without directionality. Since the most recent baselines are not publicly available, we cannot compare them to recent approaches. We’ll share the selected sequences to aid future comparisons.

In Fig. 5b, we assess stories coherency. To begin, we examine the importance of modeling direction-aware interactions. In our comparison, we changed only one aspect of our model. We used the
same factor for preceding and subsequent interactions. We show that on VIST metrics the effect is relatively small (i.e., no-direction; see Tab. 4). However, the human-evaluation comparison shows a significant coherency improvement (64.2% vs. 28.7%), which is not revealed with classical evaluation. Also, a comparison against the AREL baseline demonstrates a more significant improvement (70.24% vs. 25.32%).

In Fig. 5a we provide the results when asking annotators to pick the most human-like story. We use the majority vote to decide the best model per story. The generated stories outperform the AREL baseline (73.87% vs. 22.53%). Surprisingly, in many cases, the annotators found the generated stories to be more human-like than the ground truth stories (41% vs. 48.57%).

To further evaluate the quality of the stories, we follow the criteria set by the Visual Storytelling Challenge¹ and conduct a survey where judges are asked to rate six categories between 1-5: 1. Focused: the story contains information that is “naturally” relevant to the rest of the story; 2. Coherence: the sentences in the story are related and consistent; 3. Share: the inclination to share the story; 4. Human-like: the story was likely written by a human; 5. Grounded: the story directly reflects concrete entities in the image; and 6. Detailed: the story provides an appropriate level of detail. To obtain the final score, we average the annotators’ scores per sample, followed by averaging across the entire sample set. From Tab. 2 we observe: the model improved on all the criteria compared to the AREL model. Importantly, the generated stories are comparable to the ground-truth stories, indicating success in reducing the shortcomings found in prior methods. Nonetheless, the level of detail is still lacking, supporting the observation of Holtzman et al. [14] that current decoding strategies tend to generate well-formed yet somewhat generic text.

Ablation study: In Tab. 4 we conduct an ablation study for two novel components in our model: 1) Attention: In ‘w/o attention,’ we removed both OIA and ISA, which dropped the METEOR score to 35.8%. For the method referred to as ‘no-direction,’ we use the same factor for preceding and subsequent interaction (i.e., $L_\text{bwd} = L_\text{fwd}$).

and $R_\text{bwd} = R_\text{fwd}$). Here, METEOR results drop by 0.7%. Hence, ordered interactions are beneficial. 2) We assess the decoding components (Sec. 3.3). We first remove the intra-repetition regularization (Eq. (18)), which causes METEOR score to drop by 0.6%. Removing the popular words count ($\phi_{s,t}'$), results in a 0.4% drop on METEOR. The METEOR score drops by 0.4% when we remove the BOW prior. Last, we replace the GRU decoding layer with a Transformer, which did not change results a lot.

In Tab. 5 Further, we assess the necessity of different factors used in OIA. All factors contribute to the model’s performance and the directional factors (i.e., $\Psi_{\text{fwd}}$ and $\Psi_{\text{bwd}}$) have the biggest impact.

In Tab. 3, we show the ability to reduce repetitions. Text repetitiveness is measured by the repetition rate of non-singleton n-grams within each story. In our experiment, we use up to 4-grams. The use of intra-repetition regularization reduces text repetition (0.14 to 0.04). Combined with the trainable bag-of-words prior module,
we further improve this measure (0.008 vs. 0.14). We also report sentence repetitiveness, i.e., the average number of repeated sentences in a story.

![Image with captions]

Figure 7: An illustration of an image sequence along with three different stories generated by: (1) AREL baseline [42], (2) No History: a model without intra-repetition regularization and BOW prior (see Sec. 3.3); and (3) With History: the final model. Repeated sentences are highlighted with a yellow colored marker. Repeated words in a sentence are emphasized in red color.

In Fig. 6, we illustrate for each sentence, the value of the importance calibration scalars (i.e., $\alpha^i_t$ and $\alpha^s_t$ in Eq. 2, 3, and 4). Intuitively, these values indicate the importance of different image-to-image messages. We focus our analysis on the sentence-corresponding image (i.e., $i = s$). We observe that the self-message scalars (i.e., $\mu_{i=0}$) of the sentences in the middle of the sequence, i.e., sentences (2,3, and 4), are low. This indicates that the images in the middle of the sequence rely more on the other images. The beginning and the ending of the story depend more on the local factors. Notably, the most substantial influence is given to the following image (i.e., $\alpha^i_{t+1}$). This means that while generating the current sentence, the OIA decision is based mostly on the next image. This is intuitive as it helps to advance the narrative in a desired direction.

5 QUALITATIVE RESULTS

In Fig. 8 we illustrate the attention maps along with the generated story. The first sentence, “We went to the mountains,” sets the theme for the story, which requires the processing of subsequent images. Notably, the ISA module picked the subsequent images. In contrast, for the second sentence, the attention focuses mainly on the second image resulting in a description of the lake observed exclusively in this image. The third sentence relates to the scenery. Hence the attention focuses on preceding and subsequent images.

In Fig. 7, we show the ability of the method in reducing repetitions. We observe the AREL baseline to repeat the same sentences, for example, “...had a great time at...”. We also observe this repetitiveness when we remove the bag-of-words prior and the intra-sentence regularization (i.e., No History column). Nevertheless, the method remains on topic, i.e., family in the pool.

6 DISCUSSION

The VIST dataset focuses primarily on one topic and relatively simple stories. Our method may limit longer stories with non-linear narratives. Annotating longer stories is significantly more challenging since even the tiniest fraction of five-image stories is already difficult to cover. Future work on visual storytelling may consider employing image-text models trained on hundreds of millions of image-text pairs, such as CLIP [31], to overcome the lack of annotated data.

7 CONCLUSION

We present a novel approach for VST, which encourages coherency of generated story. We incorporate structure between images with a new attention method that selects the important objects in an ordered image sequence. Human evaluation and quantitative analysis demonstrate that the approach outperforms existing methods. Further, we perform ablation analysis to show effectiveness.
