Updating the MACHO fraction of the Milky Way dark halo with improved mass models

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ABSTRACT

Recent interest in primordial black holes as a possible dark matter candidate has motivated the reanalysis of previous methods for constraining massive astrophysical compact objects in the Milky Way halo and beyond. In order to derive these constraints, a model for the dark matter distribution around the Milky Way must be used. Previous microlensing searches have assumed a semi-isothermal density sphere for this task. We show this model is no longer consistent with data from the Milky Way rotation curve, and test two replacement models, namely NFW and power-law. The power-law model is the most flexible as it can break spherical symmetry, and best fits the data. Thus, we recommend the power-law model as a replacement, although it still lacks the flexibility to fully encapsulate all possible shapes of the Milky Way halo. We then use the power-law model to rederive some previous microlensing constraints in the literature, while propagating the primary halo-shape uncertainties through to our final constraints.

Our analysis reveals that the microlensing constraints towards the Large Magellanic Cloud weaken somewhat for MACHO masses around $10^4 M_\odot$ when this uncertainty is taken into account, but the constraints tighten at lower masses. Exploring some of the simplifying assumptions of previous constraints we also study the effect of wide mass distributions of compact halo objects, as well as the effect of spatial clustering on microlensing constraints. We find that both effects induce a shift in the constraints towards smaller masses, and can effectively remove the microlensing constraints from $M \sim 1 \sim 10 M_\odot$ for certain MACHO populations.

Key words: gravitational lensing: micro, (cosmology:) dark matter

1 INTRODUCTION

Interest in Primordial Black Holes (PBHs) as a dark matter (DM) candidate has been growing since the gravitational wave discoveries from LIGO of black hole (BH) binary systems in the mass range $\sim 10 M_\odot$ (Abbott et al. 2016a,b). PBHs would act as MACHOs, and would therefore be detectable from their gravitational influence as they pass between an observer and a distant source object, and from their dynamical effects on their surroundings. Multiple microlensing surveys have been, and are still, being conducted to discover such objects (Alcock et al. 2000; Tisserand et al. 2007; Wyrzykowski et al. 2011a; Udalski et al. 2015). Collectively these surveys constrain MACHOs in the mass range $10^{-7} \lesssim M/M_\odot \lesssim 30$ primarily by frequent observations of the Large and Small Magellanic Clouds (LMC and SMC).

Constraints on the higher mass end of the spectrum also exist. The dynamical effects from MACHOs will disrupt wide binary stars in the galactic halo, putting an upper limit on the fraction of MACHOs as DM in the halo (Chanamé & Gould 2004; Yoo et al. 2004; Quinn et al. 2009; Monroy-Rodríguez & Allen 2014). Similarly, dynamical heating of dwarf galaxies will be evident if MACHOs constitute a large fraction of DM, but this dynamical heating is not observed (Crnojević et al. 2016; Brandt 2016; Koushiappas & Loeb 2017). However, the existence of an intermediate mass black hole at the centre of the dwarf galaxy would weaken any MACHO constraints (Li et al. 2017). If PBHs make up a substantial fraction of DM, then accretion onto these PBHs from the interstellar medium should be observable with radio and X-ray telescopes, but again this is not observed (Gaggero et al. 2017; Inoue & Kusenko 2017). Accretion of matter onto PBHs in the early universe will also affect light from the CMB and the reionisation history of the universe, constrain-
ing the existence of PBH with $M \gtrsim 10 M_\odot$ (Chen et al. 2016; Aloni et al. 2017; Ali-Haimoud & Kamionkowski 2017). See (Poulin et al. 2017) for a detailed analysis of gas accretion onto PBH before recombination and their effect on the CMB constraints. Collectively these results strongly disfavour the hypothesis that PBHs make up a dominant component of DM, although there is still room for PBHs to make up a small fraction. However, there are some details and assumptions in obtaining these constraints that are overlooked and could significantly change the conclusion. In particular, we wish to focus on the constraints obtained by microlensing.

The first detail is that the constraints are generally obtained by assuming a delta-function mass distribution. Inflationary models that produce PBHs do so with an extended mass function (Carr et al. 2013; Green 2015; Clesse & Garcia-Bellido 2015; Garcia-Bellido & Ruiz-Morales 2017), which will inevitably change the constraints compared to when a delta-function mass distribution is assumed. Carr et al. (2016) argue that when an extended mass distribution is taken into account, PBHs in the intermediate-mass window ($1 - 10^3 M_\odot$) can still make the entirety of DM. However, their analysis is criticised by Green (2016), who argues that the microlensing constraints from EROS-2 (Tisserand et al. 2007) and the dynamical heating constraints by Brandt (2016) still strongly disfavour PBHs with an extended mass function.

The second detail generally overlooked is that PBHs may not be uniformly distributed through space, but may be contained in spatially small clusters (Clesse & Garcia-Bellido 2015, 2017b; Ezquiaga et al. 2018; Garcia-Bellido & Clesse 2017). If the cluster size is sufficiently small (i.e., much smaller than the Einstein radius of the entire cluster), then the cluster itself may act as a single lens, despite being made of many smaller components (Clesse & Garcia-Bellido 2017a). In this case, it is the entire cluster mass, and not the individual PBH mass, that is constrained by microlensing searches.

A final detail that is overlooked is that the MACHO microlensing constraints are obtained by assuming a “standard” halo (e.g. see Alcock et al. 1996, 2000; Tisserand et al. 2007; Wyrzykowski et al. 2011a). This standard halo was primarily used in the early days of MACHO surveys since there were no reliable Milky Way Rotation Curve (MWRC) data out to the distance of the LMC, and therefore no accurate way to probe the underlying mass distribution of the MW. As pointed out by the MACHO collaboration in their first year results paper (Alcock et al. 1996), accurate measurements of the Galactic mass out to large radii can be combined with microlensing observations to improve the constraints on the MACHO fraction in the MW dark halo. However this has not yet been addressed, and it is still common for MACHO fractions to be derived using the standard halo model.

Since this standard halo model has been assumed, and no longer appears to be an accurate fit to MWRC data (Sofue 2009), there is an intrinsic uncertainty in the microlensing constraints that is not properly accounted for. This issue has been recognised by Hawkins (2015), who argue that low mass halo models can be found that are consistent with the Alcock et al. (2000) optical depth, but Hawkins (2015) does not actually fit any MWRC data before coming to this conclusion. More recently, Green (2017) quantified this uncertainty, but also did so without fitting any MWRC data. Instead they made upper and lower bounds on the likely form of the rotation curve and rederived the microlensing constraints with an extended mass function from there.

Large scale surveys now exist which enable the recovery of the MWRC out to large radii, often much further out than the LMC or SMC (Xue et al. 2008; Sofue 2009, 2012, 2013; Bhattacharjee et al. 2014; Sofue 2015; Huang et al. 2016). It now seems appropriate to test the standard model against the recent data, and derive updated microlensing constraints if the model is no longer consistent with observational data.

In this paper, we test the consistency of the standard dark halo model used to derive microlensing constraints with recent data of the MWRC. We also test two other dark halo models, in search for a suitable replacement for the standard model, which we find is no longer consistent with MWRC data. We then update the EROS-2 LMC bright stars sample and MACHO Collaboration 5.7 year results to best reflect current knowledge of the MWRC, and the shape of the MW dark halo. Constraints from other microlensing surveys also exist, most notably those produced by the Optical Gravitational Lensing Experiment (OGLE Wyrzykowski et al. 2011b,a). The MACHO constraints obtained by OGLE are consistent with those obtained by EROS-2, although the results from the MACHO Collaboration are in slight tension with the results from these two surveys. We discuss this further in section 5.

On top of testing other halo models, we also explore how different populations of PBHs can affect the microlensing constraints. We investigate a spatially uniform distribution with a broad lognormal mass distribution, as well as a spatially clustered distribution of PBH, with $N_\lambda = 10 – 50$ PBH per cluster as a typical number. We find that in both cases the constraints are weakened. In the case of clustering, we find that the constraints shift to lower mass by a fixed amount that only depends on the number of PBH in the cluster and the dispersion of the lognormal.

The structure of the paper is as follows: in section 2 we introduce the mass models used for fitting the MWRC, we then follow on in section 3 with the MWRC dataset we use for fitting, and a discussion on sources of systematic error that are present in our analysis, along with the results from our fits. In section 4 we introduce key concepts in microlensing theory. We then present our results for the constraints on MACHOs in section 5 before providing a summary in section 6.

2 Milky Way Mass Models

Obtaining accurate information on the MWRC curve outside the Solar radius (~ 8.5 kpc) has been a challenging task for astronomers. Inside the Solar radii, techniques employing simple trigonometric relationships allow one to recover an accurate picture of the MWRC (e.g. tangent-point method). Indeed an accurate rotation curve inside the Solar radius has existed for some time (Fich et al. 1989).

Compiling the rotation curve outside of the Solar radius requires an accurate understanding of the 3 dimensional motion of the Sun and the distance to all sources. The distance to a source star is typically determined using the distance modulus in the case of standard candle stars, though the
error from this can be quite large (~ 5-20%). Current generation surveys overcome this by using large samples of stars. For example, the compilation by Huang et al. (2016) uses roughly 22,000 stars to compile the MWRC out to a distance of 100 kpc. Datasets now exist that allow a reasonably accurate recovery of the MWRC out to large galactocentric distances (Sofue 2012, 2015; Bhattacharjee et al. 2014; Huang et al. 2016), allowing us to test the standard model used to derived microlensing constraints.

2.1 Milky Way Rotation Curve

In this paper we parametrise the MWRC as a three component model with the bulge, the disk, and the dark halo. Each of the components is characterised by some mass distribution such that the circular rotation velocity of each component is given by

\[ V_a(R) = \sqrt{\frac{GM_a(R)}{R}}, \]

where the velocity \( V_a(R) \), and \( M_a(R) \) is the mass contained within \( R \) of component \( a \). Thus, for our three components, the total mass within \( R \) is given by

\[ M_t(R) = M_b(R) + M_d(R) + M_h(R). \]

This will then give the circular rotation curve \( V(R) \) at galactocentric radius \( R \) by

\[ V_t(R)^2 = \frac{GM_t(R)}{R} = V_b(R)^2 + V_d(R)^2 + V_h(R)^2, \]

where \( V_b(R) \), \( V_d(R) \), and \( V_h(R) \) are the circular rotational velocity components from the bulge, disk, and dark halo respectively (Sofue 2013). The radius \( R \) lies in the galactic mid-plane \( (z = 0 \text{ pc}) \), where \( z \) is the perpendicular distance from the plane of the disk). The contribution of each of these models varies with \( R \), such that the bulge component is almost negligible at large \( R \) compared to the combined effect from the disk and dark halo.

2.2 The bulge component

In our analysis we parametrise the bulge using an exponential sphere model (Sofue 2017). The volume mass density \( \rho \) for this model is given by

\[ \rho(R) = \rho_c \exp \left( -\frac{R}{a_b} \right). \]

where \( \rho_c \) is the central bulge density and \( a_b \) is the bulge scaling radius. The mass within a sphere of some galactocentric radius \( R \) is

\[ M(R) = M_b F(x), \]

where \( M_b = 8\pi a_b^3 \rho_c \) is the total bulge mass, \( x = R/a_b \), and

\[ F(x) = 1 - e^{-x}(1 + x + x^2/2). \]

The function \( F(x) \) can be obtained by performing a volume integral over exponential density sphere

\[ M_b F(x) = 4\pi \rho_c \int_0^x x'^2 e^{-x'} dx'. \]

The circular rotation velocity at \( R \) is finally given by

\[ V(R) = \sqrt{\frac{GM_b}{R}} f(R/a_b). \]

The two free parameters are \( M_b \) and \( a_b \), which are set to fixed values in our analysis (see section 3.4). Although it is well known that the bulge of the Milky Way contains a bar structure (Freudenreich 1998), this has little effect on the regions of the MWRC that we are interested in. Hence the assumption of a spherically symmetric bulge is justified.

2.3 The disk component

In this analysis we do not split up the disk into its two known components, the thin and the thick disk. Instead it is modelled as a single disk with some scaling radius and total mass. It common to model the Milky Way disc using the ‘thin disk’ approximation, where the height scale of the disk is neglected (e.g., see Xue et al. 2008; Sofue 2012, 2013; Huang et al. 2016). The surface density of the disk is modelled as an exponential and is given by

\[ \Sigma_d(R) = \Sigma_0 \exp \left( -\frac{R}{a_d} \right), \]

where \( \Sigma_0 \) is the central surface density value and is given by

\[ \Sigma_0 = \frac{M_d}{2\pi a_d^2}. \]

where \( M_d \) is the total mass of the disk and \( a_d \) is the disk scaling radius. An analytic solution for the rotational velocity exists

\[ V_d(R) = \sqrt{\frac{GM_d}{a_d^3}} D(X), \]

where \( X = \frac{R}{a_d^2} \) and \( D(X) \) is given by

\[ D(X) = \frac{X}{\sqrt{2}} \left[ I_0(X/2) K_0(X/2) - I_1(X/2) K_1(X/2) \right]^{1/2}. \]

where \( I_l \) and \( K_l \) are the modified Bessel functions (Freeman 1970). We use the two parameters \( M_d \) and \( a_d \) for fitting this model. Not accounting for the true 3-dimensional shape of the disk has only a very small effect on the resulting MWRC fits (Binney & Tremaine 2008).

2.4 The dark halo components

We aim to test and compare several different dark halo models by fitting the MWRC data, and then comparing the resulting expected number of microlensing events from each. In particular, we wish to test the semi-isothermal dark halo model (Begeman et al. 1991), the NFW model (Navarro et al. 1996), and the power-law model of Evans (1993, 1994).

2.4.1 Semi-isothermal model

The semi-isothermal model is the ‘standard’ model used by many when determining constraints on the fraction of DM as MACHOs. It produces a flat rotation curve at large galactocentric radii when the contribution from the disk component...
becomes negligible. The density profile is written as (Alcock et al. 1996)

$$\rho(R) = \frac{\rho_0}{R_{\text{c}}} \left(1 + \frac{R_{\text{c}}}{R}\right)^{-2},$$

where \(\rho_0\) is the local DM density at the Sun’s galactocentric radius \(R_0\), and \(R_{\text{c}}\) is the core radius. The standard model values used are \(\rho_0 = 0.0079 \, \text{M}_\odot \, \text{pc}^{-3}\), \(R_0 = 8.5 \, \text{kpc}\), and \(R_{\text{c}} = 5 \, \text{kpc}\). The circular rotation velocity is calculated using

$$V_{\text{iso}}(R) = \left[4\pi G \rho_0 R_c^2 \left(1 - \frac{R_c}{R} \tan^{-1}(R/R_c)\right)\right]^{1/2},$$

where \(\rho_0\) is the central DM density and is given by

$$\rho_0 = \frac{\rho_0}{1 + \left(\frac{R_c}{R}\right)^2}.$$  \hfill (15)

We keep \(\rho_0\) and \(R_c\) as free parameters for fitting.

### 2.4.2 NFW model

The NFW model allows more flexibility in the slope of the rotation curve than the semi-isothermal model does, since it is not restricted to producing flat rotation curves at large radii. The density profile is given by (Navarro et al. 1996)

$$\rho(R) = \frac{\rho_0}{R_{\text{c}}} \left(1 + \frac{R_{\text{c}}}{R}\right)^{-2},$$

where

$$\rho_0 = \rho_0 \frac{R_0}{R_{\text{c}}} \left(1 + \frac{R_0}{R_{\text{c}}}\right)^{-2}.$$  \hfill (17)

The circular rotational velocity is given by (Navarro et al. 1996)

$$V_{\text{NFW}}(R) = \left[4\pi \rho_0 R_c^2 \left(\log(1 + X) - \frac{X}{1 + X}\right)\right],$$

where \(X = R/R_{\text{c}}\) (Sofue 2012). The fitting parameters in this model are \(\rho_0\) and \(R_{\text{c}}\).

### 2.4.3 Power-law model

The power-law model is much more complicated in form than the semi-isothermal and NFW models, in part due to its ability to break spherical symmetry. Both the semi-isothermal and NFW models are spherically symmetric, but the power-law model can produce oblate and prolate halos. This does not actually make much of a difference in terms of the circular rotational velocity, as the symmetry axis of the halo is assumed to lie along the plane of the disk \((z = 0)\), thus any deviations away from spherical symmetry cancel out in the +z and –z directions. The density for this model is given by (Evans 1993, 1994)

$$\rho(R, z) = \frac{v_0^2 R_0^2}{4\pi G q^2} R_c^2 (1 + 2q^2) + R_c^2 (1 - \beta q^2) + z_0^2 (2 - (1 + \beta)q^{-2}).$$

where \(v_0\) is a normalisation velocity, \(R_c\) is a scaling radius, \(q\) is the ratio of the equipotentials, and determines whether the halo is a prolate \((q > 1)\) or oblate \((q < 1)\) spheroid, \(\beta\) determines the asymptotic slope of the rotation curve \((\beta < 0\) gives a rising curve while \(\beta > 0\) gives a falling curve). This is expressed in cylindrical coordinates, rather than spherical as the other two dark halo models are. The circular rotation velocity in the equatorial plane is computed using (Evans 1993)

$$V_{\text{PL}}(R) = \left[\frac{v_0^2 R_0^2 R_c^2}{(R_c^2 + R^2)^{\beta + 2}/2}\right]^{1/2},$$

where \(v_0\), \(\beta\), and \(R_c\) are used as fitting parameters. The parameter \(q\) cannot be physically constrained using rotation curves, for the reason explained above. Although \(q\) does not affect the rotation curve fit, it will affect the optical depth along the line of sight, and therefore the expected number of events.

Although the power-law model is much more flexible than both the isothermal and NFW profiles, it can still be rather limited in the shapes of haloes it can produce. The phase-space density, \(F(E, L_z)\), which is a function of orbital energy \(E\) and angular momentum \(L_z\), must be positive definite for the model to be self-consistent. The condition for \(F(E, L_z)\) to be positive definite is only dependent on the parameters \(\beta\) and \(q\) (Evans 1993, 1994). In particular, when the rotation curve is declining (i.e. \(\beta > 0\)), the power-law model begins to demand a less oblate/prolate shape in order for the phase-space density to be positive definite, as seen in Figure 1. In the case where \(\beta = 1\), the only positive definite case is when \(q = 1\), that is, the model is spherically symmetric.

When fitting the power-law model, we place a hard-wall prior such that \(F(E, L_z) \geq 0\) to ensure that we are fitting a self-consistent dark halo model to the MWRC. As a consequence of this, we can obtain model dependent constraints on the shape of the MW dark halo when fitting the MWRC. We stress that the constraints we obtain on \(q\) are strictly model dependent, and do not necessarily reflect the true shape of the MW halo, but only reflect the possible shapes allowed by the power-law model.

**Table 1.** A summary of the models being used for fitting the MWRC in our analysis.

| Component          | Fitted Parameters | Description                          |
|--------------------|------------------|--------------------------------------|
| Bulge              | \(M_\text{B}, \alpha\) | Exponential sphere                    |
| Disk               | \(M_\text{d}, \alpha_d\) | Razor thin, exponential disk          |
| Halo - semi-isothermal | \(\rho_0, R_0\) | Spherically symmetric, non-converging mass |
| - NFW              | \(\rho_0, R_0\) | Spherically symmetric                  |
| - power-law        | \(v_0, \beta, R_0\) | Can break spherical symmetry           |
As discussed in section 2.4.3, the parameter $q$ cannot be efficiently constrained using rotation curve data alone. Accurate 3 dimensional motions of stars should provide a tight constraint on the shape of the dark halo. This will soon be a reality with forthcoming data from the Gaia mission (Gaia Collaboration et al. 2016). For now it seems that there is very little agreement on the shape of the dark halo. Some argue that the shape is oblate (Olling & Merrifield 2000; Koposov et al. 2010; Bowden et al. 2015), prolate (Helmi 2004; Bamerjée & Jog 2011; Bowden et al. 2016), spherical (Fellhauer et al. 2006; Smith et al. 2009), and triaxial (Law & Majewski 2010; Deg & Widrow 2013).

Due to the requirements for the power-law model phase-space density to remain positive definite, we cannot test the full range of halo shapes. We explore the possible halo shapes that the power-law model allows. However, we note that our analysis will not be able to fully encapsulate the uncertainty in the halo shape, and will therefore underestimate the uncertainty in the microlensing event rate calculations. The semi-isothermal and NFW models remain spherically symmetric, but the intrinsic uncertainty in the shape of the dark halo should be kept in mind.

### 3.2 Local Stellar Surface Density Constraints

We consider the effect of adding a local stellar surface density constraint, $\Sigma_\odot$, that helps to break the degeneracy between the dark halo and disk models. The local stellar surface density is simply the amount of baryonic material (stars and gas) within a column with an area of one pc$^2$ at the galactocentric radius of the Sun. Many different estimates of the local stellar surface density exist and they are typically obtained by either stellar dynamics or by star counts (but also includes contributions from the interstellar medium). There is a general agreement between these two methods that $40 \lesssim \Sigma_\odot/M_\odot\text{pc}^{-2} \lesssim 60$. Constraints using stellar dynamics include $\Sigma_\odot = 48 \pm 8 M_\odot\text{pc}^{-2}$ (Kuijken & Gilmore 1989), $\Sigma_\odot = 51 \pm 4 M_\odot\text{pc}^{-2}$ (Bovy & Rix 2013), and $\Sigma_\odot = 44.4 \pm 4.1 M_\odot\text{pc}^{-2}$ (Bienaymé et al. 2014). From the star counts side we have $\Sigma_\odot = 49.1 M_\odot\text{pc}^{-2}$ (Flynn et al. 2006), $\Sigma_\odot = 54.2 \pm 4.9 M_\odot\text{pc}^{-2}$ (Read 2014), and $\Sigma_\odot = 47.1 \pm 3.4 M_\odot\text{pc}^{-2}$ (McKee et al. 2015). The dispersion in these results is much greater than the errors quoted on each individual result.

Figure 1. The dependence of the phase-space density $F(E, L_z)$ on the parameters $\beta$ and $q$. The shaded regions represent the parameter space where $F(E, L_z)$ is positive definite, and hence is the allowed region. When the power-law model produces a falling rotation curve, the allowed region of halo shape decreases. The MWRC is best described by a model that produces a falling rotation curve at large radii. As a consequence of this, we will not be able to fully encapsulate the uncertainty in the shape of the dark halo using the power-law model.

### 3.3 Dark Matter Substructure

The dark matter halos that we consider in this paper produce smooth distributions of DM, and do not include any substructure. Further, we do not consider any possible LMC/SMC halos, which would add more DM mass between the observer and the sources we observe. In this subsection we wish to highlight these systematic uncertainties and some of their potential impact on MACHO constraints.

#### 3.3.1 Dark Matter Caustics

It has been proposed that cold, collision-less DM can form caustics as it falls from all directions into a smooth gravitational potential (Sikivie et al. 1995; Sikivie 2003, 2011; Natarajan 2007; Natarajan & Sikivie 2007; Duffy & Sikivie 2008). The dark matter falls in towards the galactic centre, making its closest approach, and then converts its kinetic energy back into gravitational potential energy, and then repeats the process. Caustic rings form closer in towards the center of the galaxy at the turn-around points when the DM begins to turn its kinetic energy back into potential energy.

It is expected that this substructure will be destroyed during large galaxy mergers. However they may begin to form again if more DM begins to in-fall after a merger event, taking on the order of $10^3$ years to form (Dumas et al. 2015). Some observational evidence for these DM caustics exists in
other spiral galaxies (Kinney & Sikivie 2000), and in our own galaxy (Sikivie 2003; Dumas et al. 2015).

If these DM substructure features, or any other form of DM structure, do indeed exist, not accounting for them will be a source of systematic uncertainty. Some caustic rings have been accounted for whilst fitting the MWRC (de Boer & Weber 2011; Huang et al. 2016), but this is done so by assuming a thin DM distribution for the rings, without any height scaling. Without an accurate representation of the three-dimensional profile this substructure follows, there is no way for us to accurately account for its effect on the optical depth of MACHOs along an arbitrary line-of-sight. The mass of this substructure should be small compared to the total mass of the dark halo, as was found in Huang et al. (2016). For this reason, we do not consider the DM caustics, or any other possible DM substructure, when deriving our MACHO constraints.

3.3.2 LMC dark halo

Measurements of the rotation curve of the LMC suggest that it contains a substantial fraction of DM (van der Marel et al. 2002). If this is indeed the case, not accounting for an LMC halo will mean that our constraints are under-estimated, as there will be more DM along a given line-of-sight to the LMC than expected based on the MW halo predictions. However in our analysis we wish to highlight the uncertainty on MA-

cho constraints due to the intrinsic uncertainties with the MW dark halo. Any additional uncertainty due to an LMC halo should be small compared to the that of the MW given the large difference in dark halo mass.

3.4 Milky Way Rotation Curve datasets and fitting techniques

For fitting, we decide to use the recent compilation by Huang et al. (2016), who uses data from the LSS-GAC (Liu et al. 2014; Yuan et al. 2015), SDSS/SEGUE (Yanny et al. 2009), and SDSS-III/APOGEE (Eisenstein et al. 2011; Majewski et al. 2015) surveys to compile the MWRC. Other rotation curve compilations out to large galactocentric radius also exist in the literature, with Xue et al. (2008), Bhattacharjee et al. (2014), and Sofue (2013) being notable examples. The analysis by Huang et al. (2016) contains newer releases of SDSS data and also a factor of ~10x more stars than that of Xue et al. (2008), resulting in tighter errors in the resulting rotation curve.

A large difference between the analysis by Bhattacharjee et al. (2014) and that of Huang et al. (2016) is their treatment of the largely unknown velocity anisotropy parameter $\beta$, which relates the radial and transverse velocity dispersions. Bhattacharjee et al. (2014) opt for using $\beta$ from simulations of the Milky Way, or choose arbitrary values (e.g. see Fig 5 of Bhattacharjee et al. 2014), whereas Huang et al. (2016) use observationally determined values of $\beta$ and also propagate their associated uncertainties. See sec 4.2.2 of Huang et al. (2016) for a comparison of their work with that of Bhattacharjee et al. (2014).

Since we are mostly interested in the MWRC at large galacto-centric radii, the bulge fit is not terribly important. Furthermore, the data by Huang et al. (2016) does not probe the inner regions of the MWRC, and hence cannot be used to fit the bulge anyway. For these reasons we decide to fix the bulge model and propagate the uncertainty on the fixed values, in a similar fashion to McMillan (2011) and Huang et al. (2016). We set a prior of $a_d = 0.075 \pm 10\%$ kpc and $M_d = 8.9 \times 10^9 \pm 10\% M_\odot$. These values are consistent with previous estimates on the mass of the galactic bulge (McMillan 2011; Sofue 2013, 2017).

The galactocentric distance of the Sun is set to $R_0 = 8.34$ kpc, in line with recent observations by Reid et al. (2014). It should be noted that there is a considerable amount dispersion in the estimates for this distance. Some estimates place this distance as low as ~6.7 kpc (Branham 2014), while most of the literature points to values with $R_0 \sim 8$ kpc (Boylev & Bajkova 2014; Branham 2015, 2017; Bajkova & Boylev 2016; Vallée 2017; Camarillo et al. 2018). Should the true value of $R_0$ be different to the value used in this paper, we would expect a shift in our constraints on MACHOs. However, the uncertainty in $R_0 = 8.34 \pm 0.16$ kpc used to derive the rotation curve in Huang et al. (2016) is propagated in their analysis, and is encapsulated in their uncertainties on the rotation curve. Therefore, when we propagate the uncertainties on our fits to the Huang et al. (2016) data, some of the uncertainty in $R_0$ will be accounted for when we derive the constraints on MACHOs.

For the fitting procedure we employ a Markov Chain Monte Carlo (MCMC) sampling technique to explore the likelihood distribution of the data, and use the Python package emcee to employ it (Foreman-Mackey et al. 2013). The likelihood function is given by

$$L = \frac{1}{\sqrt{2\pi\sigma_l}} \exp \left(-\frac{(V_{\text{obs}} - V_{\text{model}}(R_i, \theta))^2}{2\sigma_l^2}\right),$$

where $N$ is the number of data points used in the fit, $\sigma_l$ is the uncertainty of the rotational velocity $V_{\text{obs}}$, and $\theta$ are the fitting parameters. When a Gaussian prior is added to the likelihood function changes to

$$L = \frac{1}{\sqrt{2\pi\sigma_P}} \exp \left(-\frac{(P_{\text{obs}} - P_{\text{mod}}(\theta))^2}{2\sigma_P^2}\right) \times \prod_{i=1}^N \frac{1}{\sqrt{2\pi\sigma_l}} \exp \left(-\frac{(V_{\text{obs}} - V_{\text{model}}(R_i, \theta))^2}{2\sigma_l^2}\right),$$

where $P_{\text{obs}}$ is the prior, $P_{\text{mod}}$ is either the model for the prior or simply a free parameter, and $\sigma_P$ is the uncertainty on the constraint.

3.5 Fitting Results

The results for our fitting procedure are listed in Tables 2 and 3 and the contour plots are presented in Figures A1, A2, and A3, for the semi-isothermal, NFW, and power-law models, respectively. The semi-isothermal model fits have some awkwardly shaped contours, and an unreasonably large fit for the disk scaling parameter $a_d$. The high value $a_d \sim 4$ kpc is quite inconsistent with photometrically derived values (Jurić et al. 2008; Licquia & Newman 2016; Bland-Hawthorn & Gerhard 2016; Chen et al. 2017). It appears that the disk
Table 2. The constraints for the isothermal and NFW halo models. Although the $\chi^2$ per degree of freedom (d.o.f.) for the isothermal model is not particularly larger than 1, the disk model in the fit is compensating for the lack of flexibility from the dark halo model. Had we placed a second prior on the disk shape to produce a realistic scale length, the resulting fit would be worse than reported here.

| Model           | $M_d$ ($\times 10^{10}$ $M_\odot$) | $a_b$ (pc) | $M_d$ ($\times 10^{10}$ $M_\odot$) | $a_d$ (kpc) | $\rho_0$ ($\times 10^{-8}$ $M_\odot$pc$^{-3}$) | $R_e$ (kpc) | $\chi^2$/d.o.f. |
|-----------------|-----------------------------------|------------|-----------------------------------|-------------|-----------------------------------------------|------------|-----------------|
| ISO High $\Sigma_0$ prior | 0.907*0.095 | 75.0*7.2 | 4.59*0.37 | 4.43*0.83 | 98.4*1.9 | 0.02*0.40 | 1.13 |
| ISO Low $\Sigma_0$ prior | 0.905*0.091 | 74.6*7.2 | 3.83*0.35 | 3.95*0.83 | 102.9*1.8 | 0.02*0.40 | 1.18 |
| NFW High $\Sigma_0$ prior | 0.893*0.093 | 74.7*7.2 | 4.82*0.40 | 2.96*0.28 | 105.8*7.2 | 13.4*3.0 | 1.02 |
| NFW Low $\Sigma_0$ prior | 0.894*0.091 | 75.0*7.2 | 4.09*0.40 | 2.81*0.28 | 114.7*6.9 | 11.7*2.1 | 0.976 |

Table 3. The constraints for the power law dark halo models.

| Model           | $M_d$ ($\times 10^{10}$ $M_\odot$) | $a_b$ (pc) | $M_d$ ($\times 10^{10}$ $M_\odot$) | $a_d$ (kpc) | $\rho_0$ ($\times 10^{-8}$ $M_\odot$pc$^{-3}$) | $R_e$ (kpc) | $\chi^2$/d.o.f. |
|-----------------|-----------------------------------|------------|-----------------------------------|-------------|-----------------------------------------------|------------|-----------------|
| High $\Sigma_0$ prior | 0.899*0.093 | 74.8*7.4 | 6.02*0.35 | 2.49*0.10 | 294*24 | 0.73*0.19 | 16.3*2.2 | 0.995*0.048 | 0.784 |
| Low $\Sigma_0$ prior | 0.890*0.091 | 75.1*7.4 | 5.48*0.32 | 2.325*0.092 | 297*24 | 0.71*0.16 | 15.3*2.1 | 0.995*0.048 | 0.788 |

Figure 2. The best fit plots and 2-$\sigma$ uncertainties (shaded) for the power-law model with both the low $\Sigma_0$ (LP) and high $\Sigma_0$ (HP) priors described in section 3.2. Our fixed model of the bulge is included in the combined and best fit constraints. The “Combined” shaded region is constructed using equation 3. The difference between the combined rotation curve for the low and high prior cases is not discernible at the resolution of this plot, so we only show a single combined shaded region rather than one for each prior. The effect of the two priors is noticeable between the disk and dark halo contributions, where the high prior case makes a slightly more massive disk and therefore a slightly lighter dark halo in the inner regions of the rotation curve.

Table 4. Model comparison tests for fits with the low and high $\Sigma_0$ prior, top to bottom. In either case, the isothermal dark halo model is strongly disfavoured compared to the power law dark halo model.

| Prior       | Model | $\Delta$AIC | $\Delta$BIC |
|-------------|-------|-------------|-------------|
| Low $\Sigma_0$ | NFW   | 10.4        | 8.7         |
| Low $\Sigma_0$ | PL    | 0.0         | 0.0         |
| High $\Sigma_0$ | NFW   | 8.4         | 6.8         |
| High $\Sigma_0$ | PL    | 4.3         | 2.7         |

component of the model is attempting to compensate for the lack of flexibility in the semi-isothermal halo model. This is not particularly surprising since the semi-isothermal model asymptotes to flat rotation curve at large radii, which is not evident in the observed MWRC data.

We now briefly discuss previous constraints on the Milky Way thin disk. Using 48 million stars from SDSS, Jurić et al. (2008) produced stellar density maps of the Milky Way. They then fit the stellar density maps to obtain photometrically derived constraints on the length scale of the Milky Way thin and thick disks (Jurić et al. 2008). They find a thin disk length scale of $\sim 2.5 - 3$ kpc, which is not tightly constrained due to SDSS observing high galactic latitudes. Using the newer SDSS data, in addition to data from XSTPS-GAC, Chen et al. (2017) constrain the thin disk length scale to $\sim 2.35$ kpc. By performing a Bayesian meta-analysis of 29 different photometrically derived values of the thin disk scale length, Licquia & Newman (2016) constrain the value to $2.64 \pm 0.13$ kpc. We have focused on the thin disk length scale in this brief discussion since it is the more dynamically relevant disk component, containing roughly 5× more mass than the thick disk (Bland-Hawthorn & Gerhard 2016; Huang et al. 2016).

The NFW model performs better than the semi-isothermal model since it is not confined to producing flat rotation curves. However, we needed to add in a hard wall prior of $a_d < 4$ kpc to prevent the disk model from fitting the dark halo dominated regions of the MWRC, and vice-versa.
The power law model is by far the most flexible of the dark halo models tested. It is able to produce a sensible fit even without any priors, but we still add these in to better reflect the current uncertainty in the local stellar surface density. The somewhat triangular shape of the contours of the $q$ parameter are a result of the requirement that the phase-space density be positive-definite in each step of the MCMC. Since MWRC is falling at larger phase-space density be positive-definite in each step of the MCMC. Since MWRC is falling at larger $R$, the $\beta$ parameter gets constrained such that $\beta > 0$. The triangular shape comes from the top shaded region in Figure 1.

Figure 2 shows the $2\sigma$ uncertainty regions for the fits with the low and high $\Sigma_*$ priors. The uncertainty in the disk and dark halo models is much larger than the combined rotation curve, owing to the large degeneracy that exists between these two models. Only a slight difference in the resulting fit arises from the choice of prior used.

To compare the three dark halo models we have tested, we use Information Criteria (IC) tests. The Akaike Information Criteria (AIC; Akaike 1974) and the Bayesian Information Criteria (BIC; Schwarz 1978) are the two we choose to use, and are given by

$$AIC = -2\ln L + 2k,$$

$$BIC = -2\ln L + k \ln N,$$

where $k$ is the number parameters in the model, and $N$ is the number of data points. These criteria encapsulate Occam’s razor, thus models with more parameters are penalised. The model with the lowest AIC or BIC is considered better at explaining a given dataset. A difference in AIC or BIC of 2 is considered positive evidence in favour of the model with the lower IC, while a difference of 6 is considered strong evidence (Kass & Raftery 1995).

The results for each IC test are presented in Table 4. We can see that the semi-isothermal model is strongly disfavoured compared to both the NFW and power law models, particularly for the low $\Sigma_*$ prior. This would be due to the fact that the isothermal model is producing a flat rotation curve, and a large disk is better at producing a falling rotation curve at large radii. While the NFW model does a better job than the isothermal model, it still does more poorly than the power law model. The information criteria tests show that the extra parameters in the power law model are justified, as they lead to significant improvement in the quality of the fit.

The main result we wish to illustrate here is that the semi-isothermal model does not produce an adequate fit to the MWRC. Despite this, it has been the most commonly used model for determining microlensing rates in the Milky Way halo. The power law model provides the most robust fit to the data, and is therefore a suitable replacement.

## 4 MICROLENSSING FORMALISM

### 4.1 Microlensing Amplification

PBHs can be detected by their gravitational influence as they pass very close to the line of sight of a distant star (Paczyński 1986). Just as in large scale gravitational lensing, a microlensed source will be distorted into multiple images as the lens passes by. If the lens and source are perfectly aligned, an Einstein ring of radius

$$r_E(M, x) = \sqrt{\frac{4GMLx(1 - x)}{c^2}}$$

is formed, where $M$ is the mass of the lens, $L$ is the distance between the observer and source star, and $x$ is the ratio of the observer-lens and observer-source distances. In reality it is very unlikely that the lens will fall perfectly on the line-of-sight to the source, so multiple images of the source, rather than a ring, will be produced. These multiple images are not resolvable in the case of microlensing. However, what will be detectable is the apparent brightening caused by the multiple line-of-sights now able to reach the observer. An apparent amplification of

$$A = \frac{u^2 + 2}{u^2 + 4}$$

will be observed, where $u = b/r_E$ is the impact parameter in units of the Einstein radius, and $b$ is the perpendicular separation between the lens to the observer-source line of sight.

### 4.2 Optical Depth

The optical depth $\tau$ is defined as the number of compact lenses within a tube of radius $ur_E$ and length $L$, where $ur_E = 1$ is the threshold parameter and corresponds to a minimum brightening of the source star by $\Delta \tau \sim 1.34$. The optical depth is a useful parameter in that it is independent of the MACHO mass $M$, and only depends on the density along the line of sight

$$\tau = \int \frac{\rho(s)}{M} \pi u^2 r_E^2(s) ds,$$

where $\rho(s)$ is the density along the line of sight.

### 4.3 Microlensing Rate

The microlensing rate $\frac{d\Gamma}{dt}$, where $t$ is the time it takes for the lens to cross the Einstein ring, is a model dependent function that allows one to calculate the expected distribution of event durations. This can then be used to determine the expected number of microlensing events one should observe assuming some fraction $f$ of the halo is comprised of PBHs.

#### 4.3.1 Semi-isothermal

For the semi-isothermal dark halo model, Alcock et al. (1996) obtain

$$\frac{d\Gamma}{dt} = \frac{512L\tau}{f^2} \frac{G^2 M p_0 (R_h^2 + R_E^2)}{\pi^2 c^2} \int_0^{1/s} \frac{x^2(1-x)^2}{A + Bx + x^2} e^{-Q(M,x)} dx,$$

1 Note that MACHO uses $t$ to refer to the time it takes for the lens to cross the Einstein ring, where was EROS-2 has $t_E$ as the time it takes the lens to cross the Einstein radius. Thus $t = 2t_E$. 

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where $v_c$ is the galactic rotation velocity of the Sun, $x_h \approx 1$ is the extent of the halo, and

$$Q(M,x) = \frac{4r_s^2(M,x)u^2}{\frac{1}{2}v_{c}^2}, \quad A = \frac{R_s^2 + R_0^2}{L^2},$$

$$B = -\frac{R_s}{L} \cos b \cos l,$$

where $b$ and $l$ are the Galactic latitude and longitude respectively.

### 4.3.2 NFW

For the NFW dark halo profile we derive

$$\frac{d\Gamma}{dt} = \frac{512L^2\mu G^2 M_{\text{p}0} R_c}{\pi^2 c^2} \times \int_0^{x_h} \frac{X^2(1-X)^2e^{-Q(M,x)}}{\left[1 + \frac{1}{R_c} \left(A' + Bx + x^2\right)^{1/2}\right]^2} dx,$$

where

$$A' = \frac{R_s^2}{L^2}.\tag{32}$$

The derivation of equation (31) can be performed starting with equation (A2) from Alcock et al. (1996) with the NFW model expressed in terms of the density along the line of sight from the Solar position, rather than from the galactic centre as it is in equation (16).

### 4.3.3 Power-law

Finally, for the power-law model, the microlensing rate is given by

$$\frac{d\Gamma}{dt} = \frac{8\mu G^2}{\pi c^2} \left(\frac{L^4}{R_c^2}\right)^2 \left(\beta + 2\right)\left(\frac{a_1}{q}\right) x_1 + \frac{2\mu G^2}{\pi c^2} \left(\frac{L^4}{R_c^2}\right)^2 \left(\beta + 2\right)\left(\frac{a_1}{q}\right) x_2,$$

where

$$a_1 = \left(\frac{1 + \beta}{1 - \beta}\right)^{1/2} \left(\frac{a_2}{a_1} R_{\text{H}}\right).\tag{33}$$

### 4.4 Wide mass distributions

When the mass distribution of PBH is no longer monochromatic, the equation for the microlensing rate can be generalised to take in any arbitrary mass distribution. In the case of the semi-isothermal dark halo model (28), this becomes

$$\frac{d\Gamma}{dt} = \frac{512L^2\mu G^2 \rho_c(R_s^2 + R_0^2)}{\pi^2 c^2} \times \int_0^\infty \frac{dM}{\psi(M,\mu,\sigma)} M \int_0^{x_h} \frac{x^2(1-x)^2}{A + Bx + x^2} e^{-Q(M,x)},$$

where

$$\psi(M,\mu,\sigma) = \mu \frac{e^{-\frac{1}{2}\sigma^2}}{\mu \sqrt{2\pi}\sigma^2} \exp\left(-\frac{\ln^2 M/\mu}{2\sigma^2}\right).$$

and analogously in (31) and (33). The distribution of PBH masses produced by inflationary models is well approximated by a normalized lognormal distribution (Green 2016)

$$\psi(M,\mu,\sigma) = \mu \frac{e^{-\frac{1}{2}\sigma^2}}{\mu \sqrt{2\pi}\sigma^2} \exp\left(-\frac{\ln^2 M/\mu}{2\sigma^2}\right),$$

where $\mu$ is the peak of the distribution, and $\sigma$ is its dispersion (i.e. width). The first two reduced moments of the lognormal distribution (35) are, see García-Bellido & Clesse (2017),

$$\langle M \rangle = \mu e^{\frac{1}{2}\sigma^2}, \quad \Delta M^2 = \langle M^2 \rangle - \langle M \rangle^2 = \langle M \rangle^2 \left(e^{\sigma^2} - 1\right).$$

### 4.5 Clustered PBH

The effect of clustering, with $N_{\text{cl}}$ PBH per cluster, is simply to change the reduced moments of the distribution,

$$\langle M \rangle_{\text{equiv}} = N_{\text{cl}} \langle M \rangle, \quad \Delta M^2_{\text{equiv}} = N_{\text{cl}}^2 \Delta M^2,$$

which means that the mean and dispersion parameters of the equivalent lognormal distribution change from $(\mu, \sigma)$ to $(\tilde{\mu}, \tilde{\sigma})$ with, see García-Bellido & Clesse (2017),

$$\tilde{\mu} = N_{\text{cl}} \mu e^{\frac{1}{2}(\sigma^2 - \tilde{\sigma}^2)}, \quad \tilde{\sigma}^2 = \ln \left(1 + e^{\sigma^2} - 1\right).$$

In this case, we constrain the peak in the distribution of PBH cluster masses, $\tilde{\mu}$. The microlensing constraints will then shift towards smaller values due to the integral in equation (34). Models of PBH with a wide mass distribution $\psi(M)$ that were ruled out by the microlensing surveys are still allowed when PBH clustering is considered. Very modest values of $N_{\text{cl}} \sim 10 - 100$ are enough.

### 4.6 Expected Number of Events

The expected number of events is given by

$$N_{\text{exp}} = E \int_0^\infty \frac{d\Gamma}{dt} \tilde{\xi}(i) \, di,$$

where $E$ is the total exposure time in units of star years (that is, if we look at $10^6$ stars for one year, $E = 10^6$ star years), and $\tilde{\xi}(i)$ is the efficiency function. The efficiency function encapsulates the ability of a given survey to identify microlensing events over a range of $i$. If a survey only runs for a short period of time, it will not be able to efficiently detect long duration microlensing events.

The long duration events are primarily caused by more massive lenses. The reason for this is two-fold. Firstly, a higher mass lens has a larger Einstein radius, and therefore a larger lensing footprint. Secondly, in a virialised system, more massive objects tend to move more slowly than less massive objects, and will therefore take longer to cover the same distance. These effects combine to limit the sensitivity of massive lenses by microlensing surveys.
4.7 Obtaining Microlensing Constraints

From the expected number of events we can easily obtain the fractional constraint, \( C(M) \), on PBH DM using

\[
C(M) = \frac{N_{\text{avg}}}{N_{\text{exp}}(M)},
\]

(40)

where \( N_{\text{avg}} \) is the upper limit on the average event rate of microlensing events, obtained from the Poisson distribution. The Poisson distribution of microlensing events is given by

\[
P(N_{\text{obs}}) = e^{-N_{\text{obs}}} \frac{N_{\text{obs}}^N}{N_{\text{obs}}!},
\]

(41)

where \( N_{\text{obs}} \) is the number of observed microlensing events for a given survey. We want to find the probability such that \( P(N_{\text{obs}}) = 0.95 \) for some upper \( N_{\text{avg}} \). That is, we want to find the value of \( N_{\text{avg}} \) where we can be 95\% confident that the true average event rate is not larger than \( N_{\text{avg}} \). For the EROS-2 survey, no events were observed, so we can be 95\% confident that true average event rate is not larger than 3 events. For a given value of \( N_{\text{avg}} \), the condition

\[
C(M) \leq 1
\]

(42)

constrains PBHs at mass \( M \) from contributing 100\% of the DM halo.

4.8 Wide mass distributions and clustered PBH Constraints

The final microlensing constraints when considering a wide mass distribution can be obtained by simply integrating out the monochromatic distribution constraint, see (34), as

\[
\int_{0}^{\infty} dM \psi(M, \mu, \sigma) N_{\text{exp}}(M) \leq N_{\text{avg}},
\]

(43)

which in the case of a lognormal distribution (35) can then be written as constraints on \( f_{\text{PBH}} \) as a function of the \( \mu \) parameter, for different values of \( \sigma \)

\[
f_{\text{PBH}}(\mu) \leq \left[ \int_{0}^{\infty} dM \frac{\psi(M, \mu, \sigma)}{C(M)} \right]^{-1},
\]

(44)

where \( \psi = f_{\text{PBH}} \), see (35).

We show in Figure 3 the effect of a wide mass distribution on the generic microlensing constraints from the EROS-2 survey. We also show the effect of clustering on the same constraints. In the case of the wide mass distribution, the constraints shift towards lower masses since for a wider mass distribution, there are progressively more massive lenses which can be more difficult to detect as they require a longer microlensing survey duration to detect. When the width of the distribution is small, as is mostly the case for \( \sigma = 0.5 \), the lognormal distribution is well approximated by a delta function.

For the clustered PBH, the constraints essentially change from \( C(M) \) into \( C(N_{\text{avg}} M^5 \sigma^3) \), since for large \( N_{\text{avg}} \) the new clustered distribution is well approximated by a delta function (i.e. \( \sigma << 1 \)), provided that \( \sigma \) is not too large.

The way to interpret Figure 3 is the following. For a given lognormal dispersion \( \sigma \), compute the integral (44) for an array of peak masses \( \mu \). This gives the upper bound on a set of lognormal populations with the chosen set of \( \mu \), and a fixed \( \sigma \). We show three different values of \( \sigma \) plotted in Figure 3, for an array of peak masses \( \mu \) on the x-axis.

These three curves give the 95\% confidence interval that a PBH population with a given \( \mu \) and \( \sigma \) is excluded from making up more than \( f_{\text{PBH}} \). We demonstrate such a distribution in Figure 3, where the lognormal distribution with parameters \([\mu, \sigma] = [10M_{\odot}, 0.5]\) is plotted. A vertical line drawn from the peak of the distribution intercepts the \( \sigma = 0.5 \) constraint (in green, right solid line) at \( f_{\text{PBH}} = 0.475 \), meaning that this distribution is excluded from contributing more than 47.5\% of DM at 95\% c.l. A PBH distribution with \([\mu, \sigma] = [10M_{\odot}, 2]\), or even \([\mu, \sigma] = [10M_{\odot}, \sqrt{2}]\), could still make up the entirety of DM.

5 RESULTS AND DISCUSSION

We consider two constraints on the MACHO fraction in the halo, the MACHO Collaboration 5.7 year (Alcock et al. MNRAS 000, 1–16 (2018))
The MACHO Collaboration find that MACHOs towards the LMC. The two different in their total exposure times. quite similar in their efficiencies, and only about a factor of their criteria A (Alcock et al. 2000). This is despite being events using their selection Criteria B, and 13 events using EROS-2, the MACHO Collaboration found a total of 17 sources. light-curves, as might be expected from spatially clustered ing from exotic lenses, which would result in oddly shaped of the source stars. Unquantifiable uncertainties include lens-\ishness of their efficiency function could be on the order of ∼ 20% (Alcock et al. 2001), and comes mostly from blending of the source stars. Unquantifiable uncertainties include lens-\ering from exotic lenses, which would result in oddly shaped light-curves, as might be expected from spatially clustered sources.

In stark contrast to the lack of events observed by EROS-2, the MACHO Collaboration found a total of 17 events using their selection Criteria B, and 13 events using their criteria A (Alcock et al. 2000). This is despite being quite similar in their efficiencies, and only about a factor of two different in their total exposure times.

This contrast leads to drastically different constraints on the optical depth of MACHOs towards the LMC. The MACHO Collaboration find that \( \tau = 1.2^{+0.4}_{-0.3} \times 10^{-7} \), with an additional 20% to 30% systematic uncertainty, while the EROS-2 survey finds an upper limit of \( \tau < 0.36 \times 10^{-7} \) at the 95% confidence interval. Although we will not be updating their analysis, it is worth mentioning that the microlensing constraints towards the LMC obtained by the OGLE Collaboration are in agreement with the constraints obtained by the EROS Collaboration (Wyrzykowski et al. 2011a). 3 The disagreement between the optical depth constraints be-

3 The main reason we do not update the OGLE constraints is that it is not possible to reproduce their microlensing constraints based on the information they provide in the paper detailing their analysis (Wyrzykowski et al. 2011a), as they do not provide all of the efficiency functions for their fields, or an average efficiency function as MACHO and EROS do.

Figure 4. The efficiency functions for the MACHO Collaboration 5.7 year (criteria A) and EROS-2 surveys, showing the efficiency with which each survey could detect lenses as a function of the Einstein ring crossing time (Alcock et al. 2000; Tisserand et al. 2007).

Figure 5. The expected number of microlensing events the EROS-2 survey should have seen if all DM was in the form of MACHOs with some mass \( M \). The shaded regions represent the 2-\( \sigma \) uncertainty propagated from the MWRC fit in Figure 2, and also includes the uncertainty in the shape of the MW dark halo. Here we have plotted the distribution in the expected number of events with both the low and high \( \Sigma \) prior that was used in fitting the MWRC. As one might expect, the low \( \Sigma \) prior on the disk fit results in a larger dark halo, which results in a higher expected number of events.

Figure 6. The same as Figure 5, but using the MACHO Collaboration 5.7 year efficiency.

between the MACHO and EROS Collaborations has received the attention from numerous authors (e.g. see Nelson et al. 2009; Besla et al. 2013), but motivates further study.

Follow up observations of the microlensed stars from the MACHO Collaboration revealed that some of them had repeated variability in their light curves, which strongly disfavour a microlensing interpretation of the original variability. With newer information, Bennett (2005) updates the MACHO 5.7 year results to find that \( \tau = (1.0 \pm 0.3) \times 10^{-7} \), which is still not in good agreement with the constraints from EROS-2.

With a new model for the MW dark halo selected (see
section 3.5), we can now move onto deriving constraints on the MACHO fraction of the dark halo using both the MACHO Collaboration 5.7 year and the EROS-2 results and efficiency functions. We will also propagate the uncertainties from the MWRC fits whilst rederiving the constraints for each survey.

To propagate the uncertainty, we sample steps from our MCMC chains and compute a microlensing model and event rate for a range of lens mass $M$ values, using the parameters $[v_{i}, R_{c}, q_{i}]$, where $i$ denotes the $i$-th step in the MCMC chain. The result of this is that for each lens mass $M$ we will have a range of models with parameters $[v_{i}, R_{c}, q_{i}]$ that reflects the range of models allowed by the MWRC fits from earlier. From this range of models, we can then compute the 2-$\sigma$ uncertainty values on the expected number of microlensing events, $N_{exp}$, for each lens mass $M$. That is, for each $M$, we obtain a range of $N_{exp}$ that is consistent with the MWRC data. The resulting uncertainty regions are plotted in Figure 5. The uncertainty values are obtained using the cumulative distribution function of the range of expected number of events for each lens mass $M$.

The optical depth $\tau$ along the line of sight towards the LMC is plotted in Figure 7. The optical depth along the line of sight is higher for the newly derived models compared to the standard model. This is a direct result of a higher mass along the line of sight. The higher mass is partly due to the allowed oblateness of the dark halo. Despite having a falling rotation curve, it appears that the Milky Way dark halo contains more mass along the line of sight towards the LMC than predicted by the standard model.

Figure 7. The optical depth $\tau$ along the line of sight towards the LMC for the low and high $\Sigma_{0}$ prior, as well for the standard model.

5.1 Monochromatic Mass Distribution

The updated MACHO fraction constraints for both the EROS-2 and MACHO Collaboration surveys are presented in Figure 8. Each of the shaded regions in Figure 8 represents the 2-$\sigma$ uncertainty from the MWRC fit in Figure 2. Therefore, they represent the uncertainty in the 95% confidence interval constraints by taking into account in the mass models that are used to build these constraints.

We show the individual microlensing constraints for the low and high $\Sigma_{0}$ constraints for both the EROS-2 and MACHO Collaboration surveys. In all cases, the constraints produced here are actually tighter at the lower-mass range by around half an order of magnitude. On the higher mass end, the constraints are mostly consistent with the standard model. When we consider the uncertainty in the mass models used to construct these, the constraints are marginally weaker for $M \gtrsim 0.1 M_{\odot}$, but are stronger below this value.

The range that MACHOs are excluded from making the entirety of DM for both the standard model constraints and the updated power-law model constraints, are tabulated in Table 5.

Despite being the most flexible of the three models tested in our analysis, the power-law model does have some limitations. The largest limitation is that it does not allow us to fully investigate different halo shapes, although it allows much more flexibility than the other models. The MWRC is best described by a falling rotation curve at large radii, and the power-law model is not able to produce a physical model for a wide range of halo shapes in this case. This means that we cannot encapsulate the full uncertainty that currently exists in the literature relating to the shape of the halo using the power-law model.

If future investigation reveals that the Milky Way dark
halo does indeed have a strongly oblate, or even mildly prolate shape, new models for computing microlensing event rates will need to be derived. This is particularly important if future information on the MWRC is consistent with rotation curve produced by Huang et al. (2016), and the MWRC does indeed decrease at large galactocentric radii.

5.2 Extended Mass Distribution and Clustered PBH Constraints

Here we consider the effect of an extended mass function and clustered PBHs. The updated MACHO constraints from the EROS-2 (left) and MACHO (right) surveys are presented in Figure 9. Each of the shaded regions represent the 2-σ uncertainty region of the MWRC fit using the power-law model, for a given extended mass distribution with some dispersion \(\sigma\). Starting with \(\sigma = 0.5\), we can see that when the dispersion is small, the constraints in Figure 9 do not strongly deviate away from when we considered the monochromatic PBH masses (comparing the tan shaded region in Figure 9 to the shaded region in Figure 8). For small dispersions, the lognormal distribution is well approximated by a delta-function. The scenario changes when the dispersion increases. The general trend is that the constraints shift towards the lower masses since when the dispersion is increasing, some PBH end up at higher masses where they essentially become "undetectable". That is, some PBH end up at such high masses that they are not efficiently detectable unless the observational baseline of the microlensing survey increases. Since a small proportion of the detectable population is removed from this, the constraints slightly begin to weaken (i.e. the tan shaded region, which represents a narrow PBH distribution, is more constraining than the red shaded region, which represents a broad PBH distribution).

A much more drastic result is seen with the clustered PBHs in Figs. 3 and 10. Here, even a small dispersion and small cluster size with \(N_{cl} = 10\) PBHs can shift the constraints substantially. With larger cluster sizes (\(N_{cl} = 50\)), and a broader mass distribution (\(\sigma = \sqrt{2}\)), the constraints shift to even lower masses. As discussed above, in section 4.8, the clustering of PBH produces a concentration of mass on smaller-sized objects spread over a larger volume, substantially diluting the microlensing constraints from \(C(M)\) to \(C(N_{cl}(M))\). This is the reason for the significant shift of the constraints to lower masses in this case, as seen in Fig. 10.

The constraints presented here are made with the assumption that the cluster size is much smaller than the Einstein radius, meaning that the microlensing signal they produce is similar to the regular point source/lens single as in equation (26), often referred to as a Paczynski light-curve. If this assumption breaks down, the microlensing light-curves can start to behave in a complicated fashion that is not encapsulated by the simple point source/lens case. For example, a cluster that is spatially large can cause caustics, bright and sudden spikes in the microlensing light-curve. If a cluster has many objects, there may be many caustics occurring over short time intervals, and probably would not be picked up by a search algorithm that is optimised to recover the simple Paczynski light-curve. The efficiency functions from both the MACHO and EROS-2 collaborations are determined using the point source/lens assumption, and so any constraints derived with these efficiency functions are subject to this assumption.

6 SUMMARY

In this paper we derived constraints on the Milky Way rotation curve (MWRC) using the recent compilation by Huang et al. (2016). We then used these constraints to update the MACHO fraction of the dark halo, for monochromatic and extended mass distributions. We have found that the standard model that has previously been used to derive MACHO constraints is no longer an accurate description of the MWRC. We propagate the uncertainties associated with the MWRC fits when constraining the MACHO fraction within the dark halo. This produces updated constraints on the MACHO fraction in the halo, which is more reflective of the current uncertainties associated with the size and shape of the Milky Way galaxy (both luminous and dark).

We update the microlensing constraints from the EROS-2 LMC bright stars sample (Tisserand et al. 2007) and the MACHO Collaboration 5.7 year results (Alcock et al. 2000; Bennett 2005), and summarise our updated constraints in table 5. The constraints at the higher mass end are somewhat weakened when the uncertainty in the Milky Way mass models are taken into account. At lower masses the constraints are actually tighter.

When considering an extended mass distribution, the constraints from microlensing weaken substantially with a broad distribution. Taking into account the possibility of clustered PBHs loosens the constraints further, even for small clusters with only \(N_{cl} = 10\) PBHs. It is expected that any astrophysical population will have some dispersion in their intrinsic properties. Therefore, when considering microlensing constraints, both the possible spatial distribution and mass distribution in the lens population should be taken into account.

Our analysis highlights the importance of mass modelling when deriving microlensing constraints. In the case of constraining primordial black holes as dark matter, we have demonstrated that the uncertainties relating to the size and shape of the Milky Way dark halo should be taken into account to produce more accurate constraints. This will be especially important when one wants to constrain parameters on the lens population. Not properly accounting for known uncertainties will bias the result. Even if the objective of microlensing searches is not to uncover the nature of microlensing searches is not to uncover the nature of the lens.
Figure 9. The exclusion plots for the EROS-2 (left) and MACHO (right) surveys when considering an extended mass function. The shaded regions plotted represent a combination of the low and high $\sigma_\odot$ priors in Figure 8. The $x$-axis represents the peak mass $\mu$ for the extended mass distribution constraints. The standard model constraints for the monochromatic (delta function) masses are plotted as a blue solid line, and only slightly deviate from the extended mass distribution with a small dispersion $\sigma = 0.5$. It can be noted that the constraints from both surveys weaken substantially for broader mass distributions for the updated constraints. On the right hand side of each plot we have plotted the mass distributions for $\mu = 10 M_\odot$ and $\sigma = [0.5, \sqrt{2}, 2]$, but have scaled them by $e^{1/\sigma^2}$ so that they are visible on the $y$-scale of this figure.

Figure 10. The exclusion plots for the EROS-2 (left) and MACHO (right) surveys when considering clustered PBHs. The $x$-axis represents the peak mass $\mu$ for the extended mass distribution that makes the cluster of PBH (see equation 38). The standard model constraints for the monochromatic (delta function) masses is plotted in blue. A larger cluster size $N_{cl}$ is more effective at shifting the microlensing constraints towards lower masses due to the higher combined mass of the cluster. A clustered PBH distribution is plotted to the right with parameters $N_{cl} = 10$, $\mu = 1 M_\odot$, $\sigma = 0.5$. 
of dark matter, understanding the physical and dynamical structure of the Milky Way is important for obtaining an accurate understanding of a lensing population.

One source of uncertainty that we have not been able to properly account for is the shape of the Milky Way halo. We have made an attempt, within the framework of the power-law model, to account for this. However, since the MWRC data prefers models that produce a falling rotation velocity with distance, the flexibility in the shape of the power-law model is restricted (see Figure 1).

If future exploration of the Milky Way dark halo reveals a strong deviation away from spherical symmetry (particularly in the prolate case), other models that offer more flexibility than that of the power-law model should be adopted for determining microlensing event rates.

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APPENDIX A: RESULTS OF ROTATION CURVE FITS
Figure A1. The contour plot for the constraints on the semi-isothermal dark halo model. The blue and red regions are the fits for the high and low $\Sigma_0$ priors respectively.
Figure A2. As with Figure A1, but for the NFW dark halo profile.
Figure A3. The contour plot for the constraints on the power-law dark halo model. The rather triangular contours for the $q$ parameter are a result of the hard-wall prior forcing each step in the MCMC chain to only sample models that are self-consistent (see section 2.4.3). A large shift in the disk properties ($a_d, M_d$), results in only a small shift in the parameters for the dark halo fit ($v_a, R_d, \beta$).