Measuring the melt pool size in a wire arc additive manufacturing process using a high dynamic range two-colored pyrometric camera

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Abstract
Control of the melt pool size is necessary to achieve more homogenous material properties in wire arc additive manufacturing (WAAM). The melt pool size can be measured by camera imaging or temperature field measurement. The paper aims to investigate the feasibility of using a high dynamic range two-colored pyrometric camera (Pyrocam) for melt pool size measurement in a gas metal arc welding–based WAAM process. A set of band-pass filters is identified using spectroscopy analysis to reduce the optical arc emission while the melt pool remains visible. The fusion line is identified in temperature field images, the melt pool size is measured by an automated algorithm, and the results are compared with high-speed camera images. A possible correlation between melt pool size and the grain size is examined.

Keywords Additive manufacturing · DED · GMAW · High-speed camera · Microstructure · Temperature field · Ti6Al4V

1 Introduction
In recent years direct energy deposition (DED) processes have become more important in the industry. High deposition rates can be achieved, enabling a fast production of large parts. There is a market for a fast production of spare parts on demand. Especially, the aerospace industry shows high interest in the DED processes, because it allows a cheaper generation of the near net shape milling parts made of expensive alloys like Ti-6Al-4V.

There are different direct energy deposition processes. Gas metal arc welding (GMAW) provides the highest deposition rates with up to 5 kg/h in comparison with the lower deposition rates of gas tungsten arc welding (GTAW) and plasma-based welding processes [1]. In arc additive manufacturing of Ti-6Al-4V, the main issues that researchers focus on are oxidation [2–4], residual stress [5], mechanical characterization [6, 7], and microstructural analysis [8–10].

Online monitoring of wire- and arc-based direct energy deposition processes is an issue of common interest. Xu et al. [11] present a general overview online monitoring possibilities and states that most of the welding defects are “are associated with thermal history” [11]. Wu et al. showed [12] the effects of the melt pool size onto mechanical properties. However, they did not measure the melt pool size, while Xiong et al. [13] used two vision sensors to measure bead geometry. Several approaches [14–16] use pyrometers, thermo couples, or thermal cameras to monitor the temperature dissipation.

A high dynamic range two-colored pyrometric camera shows promising potential as a comprehensive online monitoring tool. It measures a temperature field, and its vision channel enables the measurement of the bead geometry. It has been successfully applied in laser cladding [17] and laser gas metal arc hybrid welding [18]. It does not need to be calibrated for different materials, and in contrast to many IR thermal cameras, it can measure through a standard window glass.

The focus of this work is to prove the applicability of this camera as an online monitoring tool in a wire-based direct energy deposition process using GMAW as well as to investigate the influence of the melt pool size on the microstructure.
2 Materials and set-up

2.1 Material

A Ti-6Al-4V welding wire with 1.2-mm diameter was used. The chemical analysis according to the supplier is shown in Table 1.

As base material, pickled Ti-6Al-4V plates with 200 mm × 200 mm × 10 mm were used. The chemical analysis of the base material is shown in Table 2.

2.2 Welding process

The welding experiments were performed with a Gefertec Arc403 3D metal printing machine. This machine contains a Fronius TransPuls Synergic 4000 CMT R (cold metal transfer) power source, and the torch is mounted on a three-axis gantry system. The arc mode was CMT at a wire feed rate of 9.8 m/min, a nominal current of 179 A, a nominal voltage of 16.6 V, and the travel speed of 1.8 m/min. A mixture of 70% Helium and 30% Argon was used as process gas with 16 l/min flow rate. The workpiece to contact tip distance was set to 15 mm.

An argon chamber was used in order to prevent oxidation during processing. This chamber was filled with Argon 4.8 (minimum purity of 99.998%). A flow rate of 50 l/min was applied for 6 min before welding to produce constant shielding gas conditions.

Samples with a width of 22 mm, a length of 100 mm, and a height of 35 mm were built. The welding head was oscillated with a meander motion (see Fig. 1). Between each layer, there was an inter-run delay time of 120 s.

2.3 Spectroscopy

The optical emissions of the arc were measured using a Stellarnet Inc. Silver-Nova spectrometer. It measures in a wavelength range of 190–1100 nm with a resolution of 1 nm with a 25-μm slit. A neutral density filter OD2 was used to tone down the arc emission. It uses a UV-enhanced CCD detector cooled by a TE Cooler. The measurement was carried out with a frequency of 33 Hz for 5 s.

2.4 High-speed camera imaging

A Phantom VEO 410L high-speed camera operating at a sample rate of 6000 Hz was used for process observation with a resolution of 832 × 200 pixels. For process illumination, a Cavitar Cavilux HF illumination laser operating at a wavelength of 810 nm ± 10 nm was used synchronized to the camera. A band-pass filter with a transmissivity range of 800 nm ± 20 nm was attached to the camera.

2.5 High dynamic range two-colored pyrometric camera imaging

The measurement of the temperature field was carried out using an IMS Chips Pyrocam high dynamic range quotient pyrometric camera with a resolution of 640 × 480 pixels. It measures in the wavelength area of 400–750 nm and is calibrated for temperatures between 600 and 1900 °C. The sample rate was set to 20 Hz. A long pass filter (625 nm), a filter short pass filter (750 nm), and a neutral density filter OD2 were selected and calibrated with the optical system.

2.6 Metallography

Cross and top view sections have been taken after welding. The sections were ground, polished, and etched. The etchant used was a Kroll etchant.

3 Methodology, results, and discussion

3.1 Spectroscopy

The melt viscosity on Ti-6Al-4V needs to be reduced to guarantee build-up geometry and to avoid lack of fusion. Thus, to increase the melt pool temperature either the welding current/voltage can be increased or the process gas needs to be changed from the regularly used pure argon. Since the electrical parameters are already at the top of the power limit of power source using pure CMT, it is necessary to change the gas mixture. An argon + helium mixture increases the melt pool temperature and has shown the best welding results.

The optical emission of the arc interferes with the pyrometric measurement. For each gas mixture, the optical arc emission is different. It is necessary to find an optimal wavelength range, where the optical arc emission is minimal. For that reason, a spectroscopy measurement using different gases (or gas mixes) was conducted (Fig. 2).

The level of intensity counts of pure Argon is slightly higher compared with 70% He + 30% Ar, but the general trend...
is similar. Especially in the wavelength range between 350 and 625 nm, a high optical emission above 15,000 is measured both for Ar100 and Ar30 + He70. Above a wavelength of 625 nm, the intensity counts are decreasing steadily. The Pyrocam only measures to a maximum wavelength of 750 nm.

To ensure a high ratio between both channels of the Pyrocam, a measurement wavelength range of at least 100 nm should be ensured. For further measurements using the Pyrocam, a long pass filter (625 nm), a short pass filter (750 nm), and a neutral density filter OD2 were used. The neutral density filter is used to protect the Pyrocam from the high arc emissions.

3.2 High-speed camera imaging

In the captured high-speed video, the movement of the molten material is visible. The point at which the melt pool stabilizes was identified as at the melt pool fusion line. After welding, a ruler was used to calibrate the distance measurement. It was placed on top of the weld material; a high-speed camera image was taken, and the conversion factor from pixels to millimeter was determined for different positions in $Y$ direction. The distance between the center of the wire to the farthestmost point on the melt pool fusion line in $X$ direction was measured manually as seen in Fig. 3 and hereafter referred to as the melt pool dimension.

Selected pictures of the high-speed monitoring are shown in Fig. 4. At respective weld times the melt pool dimension is measured.

It is commonly known that the melt pool size increases at the beginning of the welding process until it reaches a steady size. That increase is evident in the results of the melt pool dimensions shown in Table 3.

The melt pool dimensions between high-speed camera imaging and Pyrocam imaging are compared in the starting phase of the welding process, because the steady phase would only provide one constant value.

3.3 High dynamic range two-colored pyrometric camera imaging

The methodology to analyze the temperature field measurement data is shown in Fig. 5. In the temperature field image, an orange square is automatically generated marking the maximum dimensions of the area that has a temperature above 1650 °C, corresponding to the melting point of Ti6Al4V. The melt pool area is searched for within the region of interest (ROI) marked by the green square. The dimensions of the ROI are limited by areas of high optical arc emissions or their back reflections. The right side of the ROI is placed directly onto the center on the wire. To measure the melt pool dimension, the vertical distance ($X$) between the melt pool boundary is analyzed.
The measured melt pool dimensions using the Pyrocam in correlation to weld time in the first layer and the melt pool dimensions measured using the high-speed camera are shown in Fig. 6. In analogy to the high-speed camera imaging, a ruler was used to calibrate the distance measurement. Prior to welding, the ruler was placed on the substrate material; an image was taken using the visible channel of the Pyrocam. A fixed pixel to millimeter conversion factor was calculated and applied. The spatial distortion was neglected due to the steep angle of vision.

A general trend of a rising melt pool dimension that levels on a plateau at 15 mm can be observed. At low weld time, the melt pool dimension appears to be very large. There are two reasons for these measurement artifacts. If the algorithm cannot find a melt pool, the maximum length of the ROI (see green square in Fig. 5) of 36.4 mm is displayed. The other reason is related to the ignition of the arc. Strong optical arc emissions in the ignition phase interfere with the measurement, which result in deceptive melt pool dimensions. Those measurement artifacts only appear at the beginning of the layer and are not present in the steady phase.

Over the whole progression of the measurement, there is a periodic increase of the weld radius. The reason for that is the meander movement of the welding head in comparison with the direction that the melt pool dimension is measured. Whenever the welding head moves the hatch distance of 3 mm in travel direction (see Fig. 1), the melt pool dimension increases for a short time by the same amount.

When comparing with the high-speed camera, the Pyrocam measurement seems less reliable in the beginning of the process. Another reason is that very small melt pool dimensions are shaded by the gas nozzle in the Pyrocam set-up, and their accurate measurement is challenging. The Pyrocam set-up has a precision of only ± 0.14 mm, while the high-speed camera set-up has a precision of ± 0.01 mm.

The automatic analysis algorithm of melt pool dimensions using the Pyrocam is influenced by arc emission deviations. The manual evaluation of the melt pool size using a high-speed camera is not influenced by arc emission deviations since it measures in the range of 800 ± 20 nm. But the manual evaluation can differ by the subjective impression of the observer on where exactly the fusion line is placed.

The comparison of the melt pool dimensions using both the Pyrocam and the high-speed camera method is shown in Table 4. The challenging measurement of small melt pool dimensions using the Pyrocam is represented by a relative deviation of 14.80% to the high-speed camera measurement. At bigger melt pool dimensions, the relative deviation is small, and both measurement methods correlate.

In Fig. 7, the melt pool dimensions of the first layer are compared with those of the 9th layer.

Up to a welding time of 5 s, the melt pool dimensions of the 9th layer are increased like the first layer. However, in comparison with the first layer, the 9th layer shows a bigger melt pool dimension and no points, where the melt pool cannot be found (melt pool dimension = 36.4 mm). This suggests that
the melt pool is larger, and the Pyrocam set-up has no trouble finding the melt pool of that size.

The measurement artifacts relating to the ignition of the arc are found in the 9th layer as well. The progression of both layers seems similar; however, the melt pool dimension in the 9th layer does not seem to level out on a plateau. It shows a slight decreasing trend. It seems unlikely that the melt pool size in general decreases. One explanation for that decreasing trend could be connected to the measurement method. It is possible that melt pool geometry changes. More material flows in front of the welding head, and therefore, less molten material is present in the trail of the melt pool, where the melt pool dimension is measured.

### 3.4 Metallography

A metallographic top view section of the first layer is shown in Fig. 8. It shows the same area of the sample that was previously observed using the high-speed camera. Darker appearing areas in the cross section are artifacts from stitching the image.

The microstructure in the top view section looks homogenous. However, there are some marked areas that stand out. In area A, which is located at the starting point of the weld, the grain size is larger in comparison with the homogenous area in the center of the sample. The reason for the larger grain size is area A seems to be the higher arc current to ignite the arc as well as a short dwell time to ensure sufficient welding.

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**Table 3** Melt pool dimension in correlation to different weld times

| Weld time (s) | 0.7 | 1.7 | 2.7 | 3.6 |
|---------------|-----|-----|-----|-----|
| Melt pool dimension high-speed camera (mm) | 3.34 | 8.13 | 10.99 | 12.60 |

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**Fig. 5** Principle of measuring the melt pool size using a Pyrocam

**Fig. 6** Melt pool dimension in correlation to weld time in the first layer
penetration depth. A higher energy input and dwell time result in a higher amount of heat that needs to dissipate and therefore a slower cooling rate.

The morphology in area B, that recurs periodically at the edges of the sample, looks different in comparison with the homogenous area in the center of the sample. While the grain size is similar, a slightly coarser alpha phase within the grains is developed (see Fig. 9 left). The reason for that might be related to the acceleration and deceleration switching between a motion in oscillation into travel direction and back. That actual welding speed at the edge is slower than the nominal welding speed and therefore applying a higher linear energy. In contrast to area A, the energy input in area B is lower, because the arc current stays at the same level. Therefore, no

| Weld time (s) | 0.7 | 1.7 | 2.7 | 3.6 |
|---------------|-----|-----|-----|-----|
| Melt pool dimension high-speed camera (mm) | 3.34 | 8.13 | 10.99 | 12.60 |
| Melt pool dimension Pyrocam (mm) | 3.92 | 8.12 | 11.06 | 12.74 |
| Relative deviation (%) | 14.80 | 0.12 | 0.63 | 1.10 |

Fig. 7  Comparison of the melt pool dimensions of different layers measured by the Pyrocam

Fig. 8  Top view section of the first layer with schematic welding head motion
significant grain growth but a slight coarsening of the microstructure is observed.

There seems to be no correlation between the melt pool dimension, that slowly grows over multiple oscillations, and the grain size that developed in homogenous size after one oscillation. That homogenous grain size develops because the solidification follows a moving melt pool, so the preferred growth direction should follow the maximum thermal gradient and therefore change constantly.

In Fig. 9 (right), a metallographic cross section over multiple layers is shown on the right. In contrast to the grain size observed in the top view section, a strong epitaxial grain growth over multiple layers is observed in the cross section, which has been already been observed by Wang et al. [10]. The width of the grains in the cross section seems to correlate with the grain diameter in the top view section.

4 Conclusions

It is shown that the evaluation of the melt pool dimension using both a high-speed camera and a high dynamic range two-colored pyrometric camera provide comparable results. In the first layer, the melt pool dimension increases steadily until it levels out on a plateau, while in later layers, the melt pool size seems to decrease slowly. The microstructure is homogenous with slight deviations at the starting point and the edges of the sample. The grain width is smaller in the welding direction, however in the build-up direction the grains grow epitaxially over multiple layers and therefore show a large size. There seems to be no correlation between the melt pool dimension and the grain size. The phenomena of a gradually decreasing melt pool dimension in upper layers are under further investigation.

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