Pose with Style: Detail-Preserving Pose-Guided Image Synthesis with Conditional StyleGAN

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Fig. 1. Detail-preserving pose-guided person image generation. We present a single-image human reposing algorithm guided by arbitrary body shapes and poses. Our method first transfers local appearance features in the source image to the target pose with a human body symmetry prior. We then leverage a pose-conditioned StyleGAN2 generator with spatial modulation to produce photo-realistic reposing results. Our work enables applications of posed-guided synthesis (left) and virtual try-on (right). Thanks to spatial modulation, our result preserves the texture details of the source image better than prior work.

We present an algorithm for re-rendering a person from a single image under arbitrary poses. Existing methods often have difficulties in hallucinating occluded contents photo-realistically while preserving the identity and fine details in the source image. We first learn to inpaint the correspondence field between the body surface texture and the source image with a human body symmetry prior. The inpainted correspondence field allows us to transfer/warp local features extracted from the source to the target view even under large pose changes. Directly mapping the warped local features to an RGB image using a simple CNN decoder often leads to visible artifacts.

Thus, we extend the StyleGAN generator so that it takes pose as input (for controlling poses) and introduces a spatially varying modulation for the latent space using the warped local features (for controlling appearances). We show that our method compares favorably against the state-of-the-art algorithms in both quantitative evaluation and visual comparison.

CCS Concepts: • Computing methodologies:

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1 INTRODUCTION

Controllable, photo-realistic human image synthesis has a wide range of applications, including virtual avatar creation, reposing, virtual try-on, motion transfer, and view synthesis. Photo-realistic rendering of human images is particularly challenging through traditional computer graphics pipelines because it involves 1) designing or capturing 3D geometry and appearance of human and garments, 2) controlling poses via skeleton-driven deformation of 3D shape, and 3) synthesizing complicated wrinkle patterns for loose clothing. Recent learning-based approaches alleviate these challenges and have shown promising results. These methods typically take inputs 1) a single source image capturing the human appearance and 2) a target pose representation (part confidence maps, skeleton, mesh, or dense UV coordinates) and synthesize a novel human image with the appearance from source and the pose from the target.

Image-to-image translation based methods [Esser et al. 2018; Ma et al. 2017, 2018; Pumarola et al. 2018; Siarohin et al. 2018], building upon conditional generative adversarial networks [Isola et al. 2017], learn to predict the reposed image from the source image and the target pose. However, as human reposing involves significant spatial transformations of appearances, such approaches often require per-subject training using multiple images from the same persons [Chan et al. 2019; Wang et al. 2018a] or are incapable of preserving the person’s identity and the fine appearance details of the clothing in the source image.

Surface-based approaches [Grigorev et al. 2019; Lazova et al. 2019; Neverova et al. 2018; Sarkar et al. 2020] map human pixels in the source image to the canonical 3D surface of the human body (e.g., SMPL model [Loper et al. 2015]) with part segmentation and UV parameterization. This allows transferring pixel values (or local features) of visible human surfaces in the input image to the corresponding spatial location specified by the target pose. These methods thus retain finer-grained local details and identity compared to image-to-image translation models. However, modeling human appearance as a single UV texture map cannot capture view/pose-dependent appearance variations and loose clothing.

StyleGAN-based methods [Lewis et al. 2021; Men et al. 2020; Sarkar et al. 2021] very recently have shown impressive results for controllable human image synthesis [Men et al. 2020; Sarkar et al. 2021] or virtual try-on [Lewis et al. 2021]. The key ingredient is to extend the unconditioned StyleGAN network [Karras et al. 2020] to a pose-conditioned one. While their generated images are photo-realistic, it remains challenging to preserve fine appearance details (e.g., unique patterns/textures of garments) in the source image due to the global (spatially-invariant) modulation/demodulation of latent space.

We present a new algorithm for generating detail-preserving and photo-realistic re-rendering of human with novel poses from a single source image. Similar to the concurrent work [Lewis et al. 2021; Sarkar et al. 2021], we use a pose-conditioned StyleGAN network for generating pose-guided images. To preserve fine-grained details in the source image, we learn to inpaint the correspondence field between 3D body surface and the source image using a body symmetry prior. Using this inpainted correspondence field, we transfer local features from the source to the target pose and use the warped local features to modulate the StyleGAN generator network at multiple StyleBlocks in a spatially varying manner. As we combine complementary techniques of photo-realistic image synthesis (from StyleGAN-based methods) and the 3D-aware detail transfers (from surface-based methods), our method achieves high-quality human-reposing and garment transfer results (Figure 1) and alleviates visible artifacts compared with the state-of-the-art (Figure 2). While StylePoseGAN [Sarkar et al. 2021] (concurrent work to ours) also combines pose-conditioned StyleGAN with the use of proxy geometry, its global modulation/demodulation scheme limits its ability to preserve fine appearance details. We evaluate the proposed algorithm visually and quantitatively using the DeepFashion dataset [Liu et al. 2016] and show favorable results compared to the current best-performing methods. Our contributions include:

- We integrate the techniques from surface-based and styleGAN-based methods to produce detail-preserving and photo-realistic controllable human image synthesis.
- We propose an explicit symmetry prior of the human body for learning to inpaint the correspondence field between human body surface and the source image which facilitates detail transfer, particularly for drastic pose changes.
- We present a spatially varying variant of latent space modulation in the StyleGAN network, allowing us to transfer local details while preserving photo-realism.
2 RELATED WORK

Pose-guided Person Image Synthesis aims to transfer a person’s appearance from a source image to a specified target pose. Example applications include motion transfer [Aberman et al. [n.d.]; Chan et al. 2019; Yoon et al. 2021], human reposing [Ma et al. 2017, 2018; Men et al. 2020], and virtual try-on [Lewis et al. 2021; Men et al. 2020; Sarkar et al. 2021]. These approaches typically encode the poses in the source and target views as either part confidence maps [Aberman et al. [n.d.]; Ma et al. 2017, 2018] or skeleton [Chan et al. 2019; Esser et al. 2018; Men et al. 2020; Pumarola et al. 2018; Ren et al. 2020; Siarohin et al. 2018; Zhu et al. 2019] and use a conditional generative adversarial network to produce the reposed images. To handle large pose changes between the source and target views, existing methods leverage per-subject training [Aberman et al. [n.d.]; Chan et al. 2019; Wang et al. 2018a], spatial transformation/deformation [Balakrishnan et al. 2018; Ren et al. 2020; Siarohin et al. 2018], and local attention [Ren et al. 2020]. To better retain the person identity and detailed appearance in the source image, surface-based methods first establish the correspondence between pixels from the source/target image to a canonical coordinate system of the 3D human body (with UV parameterization). These methods can then transfer pixel values [Allidiek et al. 2019; Grigorev et al. 2019; Lazova et al. 2019; Neverova et al. 2018] or local features [Sarkar et al. 2020] to the target pose. As the commonly used UV parameterization only captures the surface of a tight human body [Loper et al. 2015] (i.e., cannot encode loose clothing), several methods alleviate this through explicitly predicting garment labels at the target view [Yoon et al. 2021] or implicitly re-rendering the warped features [Sarkar et al. 2020].

Very recently, pose-conditioned StyleGAN networks have been proposed [Lewis et al. 2021; Men et al. 2020; Sarkar et al. 2021]. Such methods control the target appearance using the appearance features extracted from the source image [Lewis et al. 2021; Men et al. 2020] or pose-independent UV texture [Sarkar et al. 2021] to modulate the latent space.

Our method builds upon pose-conditioned StyleGAN but differs from prior work in two critical aspects. First, instead of global latent feature modulation used in prior work, we propose to use a spatially varying modulation for improved local detail transfer. Second, we train a coordinate inpainting network for completing partial correspondence field (between the body surface and source image) using a human body symmetry prior. This allows us to directly transfer local features extracted from the source to the target pose.

Neural Rendering methods first render a coarse RGB image or neural textures via some forms of geometry proxy (e.g., point cloud, 2D/3D skeleton, or human surface meshes) and then map the coarse RGB or latent textures to an RGB image using a translation network [Kim et al. 2018; Liu et al. 2020; Meshrey et al. 2019; Raj et al. 2021; Tewari et al. [n.d.]; Thies et al. 2019]. A recent line of research focuses on learning volumetric neural scene representations for view synthesis [Lombardi et al. 2019; Mildenhall et al. 2020]. Such approaches have been extended to handle dynamic scenes (e.g., humans) [Gao et al. 2021; Li et al. 2021; Park et al. 2021; Tretschk et al. 2021; Xian et al. 2021]. Recent efforts further focus on enabling controls over viewpoints [Gafni et al. 2021; Gao et al. 2020], pose [Noguchi et al. 2021; Peng et al. 2021], expressions [Gafni et al. 2021], illumination [Zhang et al. 2021] of human face/body. However, most of these approaches often require computationally expensive per-scene/per-person training over multiple image observations.

Our method also uses body surface mesh as our geometry proxy for re-rendering. Instead of using a simple CNN translation network, we integrate the rendered latent texture with StyleGAN through spatially varying modulation. In contrast to volumetric neural rendering techniques, our method does not require per-subject training.

Deep Generative Adversarial Networks have shown great potentials for synthesizing high-quality photo-realistic images [Brook et al. 2019; Goodfellow et al. 2014; Karras et al. 2018, 2020; Zhang et al. 2019]. Using the pre-trained model, several works discover directions in the latent space that correspond to spatial or semantic changes [Härkönen et al. 2020; Jahanian et al. 2020; Peebles et al. 2020; Shen and Zhou 2021; Shoshan et al. 2021]. In the context of portrait images, some recent methods provide 3D control for the generated samples [Abdal et al. 2021; Tewari et al. 2020b] or real photographs [Tewari et al. 2020a]. Our work focuses on designing a pose-conditioned GAN with precise control on the localized appearance (for virtual try-on) and pose (for reposing).

Image-to-Image Translation provides a general framework for mapping an image from one visual domain to another [Isola et al. 2017; Park et al. 2019; Wang et al. 2018b]. Recent advances include learning from unpaired dataset [Huang et al. 2018; Lee et al. 2018; Zhu et al. 2017], extension to videos [Wang et al. 2019, 2018a], and talking heads [Wang et al. 2021; Zakharov et al. 2019].

Similar to many existing human reposing methods [Chan et al. 2019; Ma et al. 2017, 2018; Men et al. 2020; Pumarola et al. 2018; Ren et al. 2020; Zhu et al. 2019], our work can be cast an image-to-image translation problem that maps an input target pose to an RGB image with the appearance from a source image. Our core technical novelties lie in 1) spatial modulation in StyleGAN for detail transfer and 2) a body symmetry prior for correspondence field inpainting.

Localized Manipulation is often preferable over global changes in many image editing scenarios. Existing work addresses this via structured noise [Alharbi and Wonka 2020], local semantic latent vector discovery [Chai et al. 2021], latent space regression [Collins et al. 2020], and explicit masking [Shocher et al. 2020].

Our method for spatially varying feature modulation in StyleGAN shares high-level similarity with approaches that add spatial dimensions to the latent vectors in unconditional StyleGAN [Alharbi and Wonka 2020; Kim et al. 2021] and conditional GANs [AlBahr and Huang 2019; Park et al. 2019]. Our work differs in that our spatial modulation parameters are predicted from the warped appearance features extracted from the source image instead of being generated from random noise using a mapping network.

Symmetry Prior (in particular reflective symmetry) has been applied for learning deformable 3D objects [Wu et al. 2020], 3D reconstruction of objects [Sinha et al. 2012], and human pose regression [Yeh et al. 2019]. Our work applies left-right reflective symmetry to facilitate the training of coordinate-based texture inpainting network. The symmetry prior allows us to better reuse local appearance features from the source and thus leads to improved results when source and target poses are drastically different.
3 METHOD

Given an image of a person $I_{src}$ and a desired target pose $P_{trg}$ represented by image-space UV coordinate map per body part (shortly UV) extracted from DensePose [Güler et al. 2018], our goal is to generate an image preserving the appearance of the person in $I_{src}$ in the desired pose $P_{trg}$. Note that this UV representation of dense pose entangles both the pose and shape representation.

We show an overview of our proposed approach in Figure 3. We use a pose-guided StyleGAN2 generator [Karras et al. 2020] that takes $16 \times 16 \times 512$ pose features $F_{pose}$ as input. The pose features $F_{pose}$ are encoded from the DensePose representation [Güler et al. 2018] using a pose feature generator $G_{pose}$ that is composed of several residual blocks. Using the source and target pose, we use coordinate completion model to produce target coordinates that establishes the correspondence between target and source image. To encode the appearance information, we use a feature pyramid network [Lin et al. 2017] $G_{app}$ to encode the source image into multiscale features and warp them according to the target pose. We then use the warped appearance features to generate scaling and shifting parameters to spatially modulate the latent space of the StyleGAN generator.

3.1 Coordinate Completion Model

The IUV map of the source pose $P_{src}$ allows us to represent the pose-independent appearance of the person in the UV-space. However, only the appearance of visible body surface can be extracted. This leads to incomplete UV-space appearance representation and thus may not handle the dis-occluded appearance for the target pose $P_{trg}$. Previous work [Sarkar et al. 2021] encodes the partial UV-space appearance to a global latent vector for modulating the generator. This works well for clothing with uniform colors or homogenous textures, but inevitably loses the spatially-distributed appearance details. We propose to inpaint the UV-space appearance by a neural network guided by the human body mirror-symmetry prior. Instead of directly inpainting pixel values in UV-space, we choose to complete the mapping from image-space to UV-space established by $P_{src}$, and represented by UV-space source image coordinates, in order to avoid generating unwanted appearance artifacts while best preserving the source appearance. We refer to this network as coordinate completion model. We show an overview of our coordinate completion model in Figure 5.

Given a mesh grid and the dense pose of the input source image $P_{src}$, we use a pre-computed image-space to/from UV-space mapping to map coordinates from the mesh grid to appropriate locations in the UV-space (using bilinear sampling for handling fractional
coordinates. We denote these base mapped coordinates as $C_{\text{base}}$ and the mask indicating where these coordinates are as $M_{\text{base}}$.

Since human appearances are often left-right symmetrical, in addition to these base coordinates, we also map the left-right mirrored coordinates to the UV-space $C_{\text{mirrored}}$ and denote their respective mask as $M_{\text{mirrored}}$. Visualization of mapped base and mirrored coordinates are shown in Figure 6.

We combine the incomplete UV-space base and mirrored coordinates and their respective masks, such that:

$$M_{\text{mirrored}} = M_{\text{mirrored}} - (M_{\text{base}} \cdot M_{\text{mirrored}})$$  \hspace{1cm} (1)

$$M_{\text{in}} = M_{\text{base}} + M_{\text{mirrored}}$$  \hspace{1cm} (2)

$$C_{\text{in}} = C_{\text{base}} \cdot M_{\text{base}} + C_{\text{mirrored}} \cdot M_{\text{mirrored}}$$  \hspace{1cm} (3)

We concatenate the combined coordinates $C_{\text{in}}$ and their mask $M_{\text{in}}$ and pass them as input to the coordinate completion model. To implement our coordinate completion model, we follow a similar architecture to the coordinate inpainting architecture proposed by [Grigorev et al. 2019] with gated convolutions [Yu et al. 2019].

We train our model to minimize the $l_1$ loss between the generated coordinates $C_{\text{out}}$ and the input coordinates, such that:

$$L_{\text{coord}} = ||C_{\text{out}} - M_{\text{base}} \cdot M_{\text{base}}||_1$$  \hspace{1cm} (4)

where $\lambda_{\text{mirrored}}$ is set to 0.5.

We also utilize the source-target pairs to train the coordinate completion model. Specifically, we use the source dense pose $P_{\text{src}}$ to map the generated complete coordinates from the UV-space to the source image-space $S_{\text{coord}}$. Similarly, we also use the target dense pose $P_{\text{trg}}$ to map the generated complete coordinates from the UV-space to the target image-space $T_{\text{coord}}$ using the pre-computed mapping table. We then use these target and source coordinates to warp pixels from the input source image $I_{\text{src}}$ and minimize the $l_1$ loss between the foreground of the warped images and the foreground of the ground truth images, such that:

$$L_{\text{rgb}} = ||\text{warp}(I_{\text{src}} , S_{\text{coord}}) \cdot M_{\text{src}} - I_{\text{src}} \cdot M_{\text{src}}||_1$$

$$+ ||\text{warp}(I_{\text{src}}, T_{\text{coord}}) \cdot M_{\text{trg}} - I_{\text{trg}} \cdot M_{\text{trg}}||_1.$$  \hspace{1cm} (5)

where $M_{\text{src}}$ and $M_{\text{trg}}$ are the source pose mask and target pose mask, respectively.

The total loss to train the coordinate completion model is:

$$L = L_{\text{coord}} + L_{\text{rgb}}$$  \hspace{1cm} (6)

3.2 Source Feature Generator

To preserve the appearance in source image $I_{\text{src}}$, we encode it using several residual blocks into multi-scale features $F_{\text{app}}$. We utilize the pretrained coordinate completion model to obtain the target image-space coordinates $T_{\text{coord}}$ such that it could warp the source features $F_{\text{app}}$ from the source pose to the target pose $F_{\text{app}}^{\text{trg}}$. We then concatenate these warped features with the target dense pose mask $M_{\text{trg}}$ and pass them into a feature pyramid network [Lin et al. 2017] to get our multi-scale warped appearance features $F_{\text{app}}$. We show our source feature generator in Figure 4.

3.3 Affine Parameters Network and Spatial Modulation

Prior to every convolution layer in each style block of StyleGAN2, we pass the warped source features $F_{\text{app}}$ into an affine parameters network to generate scaling $\alpha_i$ and shifting $\beta_i$ parameters. Each convolution layer has its own independent affine parameters network which is composed of two $1 \times 1$ convolutions separated by a ReLU activation function for each parameter. To preserve spatial details, we modify every convolution layer in each style block of StyleGAN2 [Karras et al. 2020]. Instead of performing spatially invariant weight modulation and demodulation, we use the generated scaling and shifting tensor parameters, $\alpha_i$ and $\beta_i$, to perform spatially varying modulation of the features $\hat{F}_i$ as follows:

$$\hat{F}_i = \alpha_i \odot F_i + \beta_i,$$  \hspace{1cm} (7)

where $\hat{F}_i$ is now the modulated features that will be passed as input to the $3 \times 3$ convolution of styleGAN2 generator. The output features of the convolution $\hat{F}_{i \text{out}}$ is then normalized to zero mean and unit standard deviation. Such that:

$$\hat{F}_i = \frac{\hat{F}_{i \text{out}} - \text{mean}(\hat{F}_{i \text{out}})}{\text{std}(\hat{F}_{i \text{out}})}$$  \hspace{1cm} (8)

Similar to StyleGAN2, we then add the noise broadcast operation $B$ and the bias to $\hat{F}_i$ to get $F_{i+1}$ which will be fed into the next convolution layer. In Figure 7, we illustrate our detailed spatial modulation approach as well as the non-spatial weight modulation and demodulation of StyleGAN2.

3.4 Training Losses

In addition to StyleGAN2 adversarial loss $L_{\text{adv}}$, we train our model to minimize the following reconstruction losses:

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The goal of the coordinate completion model is to learn how to re-use the local features of the visible parts of the human in the source image for the invisible parts (unseen in the source pose) in the target pose. (a) Given a mesh grid and the dense pose of the input source image $P_{src}$, we map the base coordinates $C_{base}$ and their symmetric counterpart $C_{mirrored}$ from the 2D mesh grid to the UV-space using a pre-computed mapping table. We then concatenate the combined coordinates $C_{in}$ and their corresponding visibility mask $M_{in}$ as input to the coordinate completion model. (b) We train the model to minimize the L1 loss between the predicted coordinates $C_{out}$ and the input coordinates $C_{in}$ as shown in Eqn. 4. We also minimize the L1 loss between the warped source image and the warped target image as shown in Eqn. 5.

Fig. 6. Symmetry-guided inpainting. (Left) Given a mesh grid and the source image dense pose $P_{src}$, we first map the coordinates from the 2D mesh grid to appropriate locations in the UV-space using a pre-computed mapping table. We can then use these mapped base coordinates $C_{base}$ to warp RGB pixels from the input source image $I_{src}$. We show the base coordinates and their warped RGB pixels in (a). (b) In addition to these base coordinates, we can also map the left-right mirrored coordinates $C_{mirrored}$ from the 2D mesh grid to the UV space. To train our coordinate completion model, we combine the incomplete base and mirrored coordinates in the UV-space. We then concatenate these combined coordinates with their respective mask and pass them as input to our coordinate completion model. We show our completed coordinates and the UV texture map in (c). (Right) We compare the reposing results without and with the proposed symmetry prior.

**$\ell_1$ loss** We minimize the $\ell_1$ loss between the foreground human regions of the synthesized image $I_{trg}$ and of the ground truth target $I_{trg}$.

$$L_{\ell_1} = ||I_{trg} \cdot M_{trg} - I_{trg} \cdot M_{trg}||_1.$$  \hfill (9)

where $M_{trg}$ is the human foreground mask estimated using a human parsing method [Gong et al. 2018].

**Perceptual loss** We minimize the weighted sum of the $\ell_1$ loss between the pretrained VGG features of the synthesized $I_{trg}$ foreground and the ground truth $I_{trg}$ foreground such that:

$$L_{agg} = \sum_{i=1}^{5} w_i \cdot ||VGG_i(I_{trg} \cdot M_{trg}) - VGG_i(I_{trg} \cdot M_{trg})||_1.$$  \hfill (10)

We use $w = [1, 1, 1, 1, 1]$ and VGG ReLU output layers $l = [1, 6, 11, 20, 29]$ following [Park et al. 2019; Wang et al. 2018b].
We implement our model with PyTorch. We use ADAM optimizer with a learning rate of $\text{ratio} \cdot 0.002$ and beta parameters $(0, 0.99^{\text{ratio}})$. We set the generator ratio to $\frac{4}{5}$ and discriminator ratio to $\frac{16}{17}$.

**Training.** We first train our model by focusing on generating the foreground. We apply the reconstruction loss and the adversarial loss only on the foreground. We set the batch size to 1 and train for 50 epochs. This training process takes around 7 days on 8 NVIDIA 2080 Ti GPUs. We then finetune the model by applying the adversarial loss globally on the entire image. We set the batch size to 8 and train for 10 epochs. This training process takes less than 2 days on 2 A100 GPUs. At test time, generating a reposing results with $384 \times 512$ resolution takes 0.4 seconds using 1 NVIDIA 2080 Ti GPU.

**Dataset.** We use the DeepFashion dataset [Liu et al. 2016] for training and evaluation. We follow the train/test splits (101,967 training and 8,570 testing pairs) of recent methods [Men et al. 2020; Ren et al. 2020; Zhu et al. 2019].

### 4.2 Evaluations

**Quantitative evaluation.** is reported in Table 1. We report the human foreground peak signal-to-noise ratio (PSNR), structural similarity index measure (SSIM), learned perceptual image patch similarity (LPIPS) [Zhang et al. 2018], and Frechet Inception Distance (FID) [Heusel et al. 2017]. PSNR/SSIM often do not correlate well with perceived quality, particularly for synthesis tasks. For example, PSNR may favor blurry results over sharp ones. We report these metrics only for completeness.

Our method compares favorably against existing works such as PATN [Zhu et al. 2019] ADGAN [Men et al. 2020], and GFLA [Ren et al. 2020].

Our method also compares favorably against the concurrent work StylePoseGAN [Sarkar et al. 2021]. We report the quantitative evaluation in Table 2. We train and test our method using their DeepFashion dataset train/test split.

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**Table 1. Quantitative comparison with the state-of-the-art methods on the DeepFashion dataset [Liu et al. 2016].**

| Method                  | PSNR↑ | SSIM↑ | FID↓ | LPIPS↓ |
|-------------------------|-------|-------|------|--------|
| Resolution $= 174 \times 256$ |
| PATN [Zhu et al. 2019]   | 17.7041  | 0.7543 | 21.8568  | 0.195  |
| ADGAN [Men et al. 2020]  | 17.7223  | 0.7544 | 16.2686  | 0.175  |
| GFLA [Ren et al. 2020]   | 18.0424  | 0.7625 | 15.1722  | 0.167  |
| Ours                     | **18.5062**  | **0.7784** | **8.7449**  | **0.134** |

| Resolution $= 348 \times 512$ |
| GFLA [Ren et al. 2020] | 17.9718  | 0.7540 | 18.8519  | 0.170  |
| Ours                     | **18.3567**  | **0.7640** | **9.0002**  | **0.143** |

**Table 2. Quantitative comparison on 348 × 512 resolution with StylePoseGAN [Sarkar et al. 2021] on their DeepFashion dataset train/test split.**

| Method                  | PSNR↑ | SSIM↑ | FID↓ | LPIPS↓ |
|-------------------------|-------|-------|------|--------|
| StylePoseGAN [Sarkar et al. 2021] | 17.7568  | 0.7508 | 7.4804  | 0.167  |
| Ours                     | **18.5029**  | **0.7711** | **6.0557**  | **0.144** |

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**Face identity loss.** We use MTCNN [Zhang et al. 2016] to detect, crop, and align faces from the generated image $I_{\text{trg}}$ and ground truth target $I_{\text{frg}}$. When a face is detected, we maximize the cosine similarity between the pretrained SphereFace [Liu et al. 2017] features of the generated face and the ground truth target face. Such that:

$$L_{\text{face}} = 1 - \frac{SF(I_{\text{trg}})^T SF(I_{\text{trg}})}{\max(||SF(I_{\text{trg}})||_2 \cdot ||SF(I_{\text{trg}})||_2, \epsilon)}$$

where $SF$ is the pretrained SphereFace feature extractor, and $SF(I_{\text{trg}})$ and $SF(I_{\text{frg}})$ are features of the aligned faces of the generated and ground truth image respectively. $\epsilon = e^{-8}$ is a very small value to avoid zero-dividing.

Therefore, our final loss is: $L = L_{\text{adv}} + L_{\ell} + L\_\text{aggi} + L_{\text{face}}$.
Badour AlBahar, Jingwan Lu, Jimei Yang, Zhixin Shu, Eli Shechtman, and Jia-Bin Huang

Fig. 8. Visual comparison for human reposing. We show visual comparison of our method with PATN [Zhu et al. 2019], ADGAN [Men et al. 2020], and GFLA [Ren et al. 2020] on DeepFashion dataset [Liu et al. 2016]. Our approach successfully captures the local details from the source image.

Table 3. The ability to preserve the identity of the reposed person.

|                  | Arcface | Spherenet |
|------------------|---------|-----------|
| GFLA [Ren et al. 2020] | 0.117   | 0.197     |
| Ours             | 0.373   | 0.438     |
| Ground truth     | 0.555   | 0.444     |

Visual comparison in Figure 8 and Figure 9 show that our proposed approach captures finer-grained appearance details from the input source images.

Face identity We evaluate our model’s ability to preserve the reposed person’s identity. For test images with visible faces (7,164 from 8,570), we report in Table 3 the averaged cosine similarity between the face features (Arcface [Deng et al. 2019] and Spherenet [Coors et al. 2018]) extracted from the aligned faces in the source/target images. Our method compares favorably against GFLA [Ren et al. 2020].

4.3 Ablation study
For the ablation study, we report the results of the foreground-focused trained model.

Fig. 9. Visual comparison for human reposing. We compare our method with StylePoseGAN [Sarkar et al. 2021] on their train/test split of DeepFashion dataset [Liu et al. 2016]. Our approach preserves the appearance and captures the fine-grained details of the source image.

Table 4. The effect of symmetry-guided coordinate inpainting on the DeepFashion dataset [Liu et al. 2016].

|                  | PSNR↑ | SSIM↑ | FID↓ | LPIPS↓ |
|------------------|-------|-------|------|--------|
| Without symmetry | 18.8810 | 0.7886 | 8.5240 | 0.129   |
| With symmetry (Ours) | **18.9657** | **0.7919** | **8.1434** | **0.124** |

Symmetry prior. We evaluate the effectiveness of adding the symmetry prior to the input of the coordinate completion model. We train our networks with and without this symmetry prior and report the quantitative results in Table 4. Results show that adding the symmetry prior indeed improves the quality of the synthesis. We note that the symmetry prior generally works well for repetitive/textured patterns, but may introduce artifacts for unique patterns (e.g., text).

Modulation schemes. We quantitatively and qualitatively demonstrate the effectiveness of our proposed spatial modulation. We show quantitative evaluation in Table 5. We show qualitative results in Figure 10. Results show that spatially varying modulation improves the quality of the synthesized human foreground and captures the spatial details of the source images regardless of the input source image type.
Pose with Style: Detail-Preserving Pose-Guided Image Synthesis with Conditional StyleGAN

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Fig. 10. **Ablation.** We compare our results with other variants, including the modulation types and source of appearance features. We show that the proposed spatial modulation captures finer-grained details from the source image. Transferring appearance features from the source image leads to fewer artifacts compared to features from the UV space.

Table 5. Ablation on source for appearance (Incomplete UV, Complete UV, and Image) and modulation types (Spatial and Non-spatial).

| ID | Input Source | Spatial | PSNR↑ | SSIM↑ | FID↓ | LPIPS↓ |
|----|--------------|---------|-------|-------|------|--------|
| A  | Incomplete UV- | 18.7385 | 0.7710 | 9.4150 | 0.151 |        |
| B  | Incomplete UV ✓ | 18.6005 | 0.7696 | 9.2321 | 0.146 |        |
| C  | Complete UV -  | 18.9407 | 0.7770 | 9.7435 | 0.147 |        |
| D  | Complete UV ✓ | 18.7063 | 0.7720 | 9.0236 | 0.143 |        |
| E  | Source image -  | 18.6027 | 0.7678 | 9.4367 | 0.154 |        |
| F  | Source image ✓ | 18.7420 | 0.7739 | 8.8060 | 0.139 |        |

**Sources of appearance.** We experiment with multiple variants for encoding source appearance. Specifically, the *incomplete UV*, *complete UV* (completed using the coordinate completion model), and *source image* (our approach shown in Figure 3). We report the quantitative results in Table 5 and visual results in Figure 10. The results show that extracting appearance features directly from the source image preserves more details than other variants.

4.4 Garment transfer Results

Using the UV-space pre-computed mapping table, we can segment the UV-space into human body parts (Figure 11). We can then use this UV-space segmentation map to generate the target pose segmentation map using the target dense pose $P_{trg}$. The target segmentation map allows us to combine partial features from multiple source images to perform garment transfer. Figure 12 shows examples of bottom and top garment transfer.

4.5 Limitations

**Failure cases.** Human reposing from a single image remains challenging. Figure 13 shows two failure cases where our approach fails to synthesize realistic hands and clothing textures. Hands are difficult to capture due to the coarse granularity of DensePose. Explicitly parsing hands could help establish more accurate correspondence.

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Fig. 11. **Human body segmentation.** We create a UV-space segmentation map $S_{uv}$ of the human body using the UV-space pre-computed mapping table. We use the target dense pose $P_{trg}$ to map this UV-space segmentation map to 2D target pose $S_{trg}$, which can then be used to combine features from multiple source images to perform garment transfer.
Diversity DeepFashion dataset consists of mostly young fit models and very few dark-skinned individuals. Our trained model thus inherit the biases and perform worse on unrepresented individuals as shown in Figure 14. We believe that training and evaluating on diverse populations and appearance variations are important future directions.

5 CONCLUSIONS

We have presented a simple yet effective approach for pose-guided image synthesis. Our core technical novelties lie in 1) spatial modulation of a pose-conditioned StyleGAN generator and 2) a symmetry-guided inpainting network for completing correspondence field. We demonstrate that our approach is capable of synthesizing photorealistic images in the desired target pose and preserving details from the source image. We validate various design choices through an ablation study and show improved results when compared with the state-of-the-art human reposing algorithms. Our controllable human image synthesis approach enables high-quality human pose transfer and garment transfer, providing a promising direction for rendering human images.

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Fig. 12. Garment transfer. We show examples of garment transfer for bottom (left) and top (right) garment sources.

Fig. 13. Failure cases. Our method produces artifacts on the hands (left) and the skirt (right).

Fig. 14. Diverse in the wild cases. Our model inherits the biases of DeepFashion dataset and thus performs worse on unrepresented individuals. Our method cannot accurately synthesize curly hair (left) and fails in reposing dark-skinned individuals (right).
