Computational Polarization: An Information-theoretic Method for Resilient Computing

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Every day, we create 2.5 billion gigabytes of data

Data stored grows 4x faster than world economy (Mayer-Schonberger)
in machine learning and data science

- more data results in better and accurate models
  → **large scale distributed computing problems**
in machine learning and data science

- more data results in better and accurate models
  → large scale distributed computing problems

Can we scale computation inexpensively?

Our approach: serverless systems with error correction to auto-scale computation

M. Pilanci, Computational Polarization: An Information-theoretic Method for Resilient Computing, accepted to IEEE Transactions on Information Theory, 2021

B. Bartan and M. Pilanci Straggler Resilient Serverless Computing Based on Polar Codes, Allerton 2019
Distributed computation

DATA

...
Error Resilient Matrix Multiplication

Speeding Up Distributed Machine Learning Using Codes. Lee et al., 2017
Error Resilient Matrix Multiplication

Speeding Up Distributed Machine Learning Using Codes. Lee et al., 2017
Serverless computing: AWS Lambda

- low cost, no upfront investment
- 900 seconds single-core, 3GB RAM
- Python, Java, C#
Serverless computing: AWS Lambda

- Lambda functions are *stateless*
  - Local file system access and child processes may not extend beyond the lifetime of the request
  - Persistent state should be stored in a storage service (e.g., S3)
- Pywren (E. Jonas et al., 2017)
- Google Cloud and Microsoft Azure offer similar services
Serverless computing: AWS Lambda

- return times
Polar Codes

- Polar Codes were invented by Arikan in 2009
- Combines communication channels recursively to obtain better/worse channels
- It is the first code with an explicit construction to provably achieve the channel capacity for all symmetric discrete memoryless channels
- 3rd Generation Partnership Project (3GPP) adopted polar codes as the official coding scheme for the control channels of the 5G New Radio interface.
Polar Codes: Recursive Channel Transformation

2×2 construction

4×4 construction
Computational Polar Codes

A → worker → f(A)
Computational Polar Codes

\[ A_1 \rightarrow \text{Worker 1} \rightarrow f(A_1) \]

\[ A_2 \rightarrow \text{Worker 2} \rightarrow f(A_2) \]
Hadamard transform

\[ A_1 + A_2 \]

\[ A_1 - A_2 \]
Butterfly coded computation

\[ A_1 \rightarrow A_1 + A_2 \rightarrow \text{worker 1} \rightarrow f(A_1 + A_2) \]

\[ A_2 \rightarrow A_1 - A_2 \rightarrow \text{worker 2} \rightarrow f(A_1 - A_2) \]
Decoding the original computation $f(A_1)$ and $f(A_2)$ for linear functions
Runtime distribution

\[ A_1 \rightarrow A_1 + A_2 \rightarrow T_1 \rightarrow f(A_1 + A_2) \rightarrow \text{decode } f(A_1) \rightarrow f(A_1) \]

\[ A_2 \rightarrow A_1 - A_2 \rightarrow T_2 \rightarrow f(A_1 - A_2) \rightarrow \text{decode } f(A_2), f(A_1) \rightarrow f(A_2) \]

\[ T_1 \rightarrow \max(T_1, T_2) \]

\[ T_2 \rightarrow \min(T_1, T_2) \]
4 by 4 construction

\[
\begin{align*}
A_1 + A_2 &\rightarrow f(A_1 + A_2) + f(A_3 + A_4) \\
A_3 + A_4 &\rightarrow f(A_1 + A_2) - f(A_3 + A_4) \\
A_1 - A_2 &\rightarrow f(A_1 - A_2) + f(A_3 - A_4) \\
A_3 - A_4 &\rightarrow f(A_1 - A_2) - f(A_3 - A_4)
\end{align*}
\]
Computational Polarization Process

\[ T_1 \rightarrow \max(T_1, T_2) \rightarrow \max(\max(T_1, T_2), \max(T_3, T_4)) \]

\[ T_2 \rightarrow \min(T_1, T_2) \rightarrow \min(\max(T_1, T_2), \max(T_3, T_4)) \]

\[ T_3 \rightarrow \max(T_3, T_4) \rightarrow \max(\min(T_1, T_2), \min(T_3, T_4)) \]

\[ T_4 \rightarrow \min(T_3, T_4) \rightarrow \min(\min(T_1, T_2), \min(T_3, T_4)) \]
Computational Polarization Process

- Functional Martingale process
- $F(t)$ is the cumulative density function of the i.i.d. run-times
  \[
  F_{n+1}(t) = \begin{cases} 
  1 - (1 - F_n(t))^2 & \text{with probability } \frac{1}{2} \\
  F_n(t)^2 & \text{with probability } \frac{1}{2}
  \end{cases}
  \]

- $\mathbb{E}[F_{n+1}(t)|F_n] = F_n(t)$

- **Theorem:** $\|F_{n+1}(t) - F_n(t)\|_{L^2} \to 0$ as $n \to \infty$ with rate $O(2^{-2\sqrt{n}})$
  
  $F_n(t)$ converges to unit step functions

  run-time distributions converge to the Dirac measure

M. Pilanci, **Computational Polarization: An Information-theoretic Method for Resilient Computing**, arXiv preprint 2021
Run-time distributions
Fixing certain inputs to zero

\[ A_1 + A_2 \rightarrow M_1 \rightarrow f(A_1 + A_2) + f(A_3 + A_4) \]

\[ A_3 + A_4 \rightarrow M_2 \rightarrow f(A_1 + A_2) - f(A_3 + A_4) \]

\[ 0 \rightarrow M_3 \rightarrow f(A_1 - A_2) + f(A_3 - A_4) \]

\[ A_1 - A_2 \rightarrow M_4 \rightarrow f(A_1 - A_2) - f(A_3 - A_4) \]
Fixing certain inputs to zero
Computational Polarization

(B. Bartan and M. Pilanci, Straggler Resilient Serverless Computing Based on Polar Codes, 2019)
Comparison with other coding methods

- Reed-Solomon codes, LT codes, LDPC codes, Fermat Number Transform (FNT) based codes
- Computational Polar codes have $O(n \log n)$ encoding and decoding complexity
- only addition and subtraction operations in encoding and decoding
- can scale to 10,000 workers
Compute jobs
Elastic computing

- AWS Lambda serverless compute jobs 1.5 GB memory each
  
  (a) uncoded: 500 workers
  
  (b) coded: 1500 workers (1000 redundant parity)
Computational Polarization for optimization on AWS Lambda

- encode data matrix $A$ for gradient calculation, e.g., $Ax$ and $A^T y$ for Least Squares and Generalized Linear Models

random data ($20000 \times 4800$) Imagenet ($2013526 \times 196608 \sim 1.2$ TB)
Computing Nonlinear Functions

- linear functions of data $f(A)$
- polynomial functions of data $f(A)$
- gradient and Hessian calculations involving data $A$
Computational Polarization for gradient estimation

- gradient estimator

\[ \frac{\partial f(x)}{\partial x_i} \approx \frac{f(x + he_i) - f(x - he_i)}{2h} \]

- coded gradient estimator

\[ \frac{f(x + hz_i) - f(x - hz_i)}{2h} \]

- \( z_i \): redundant function evaluation directions =

- decode the gradient \( \frac{\partial f(x)}{\partial x} \) from \( \langle \frac{\partial f(x)}{\partial x}, z_i \rangle \)

B. Bartan, M. Pilanci, Distributed Black-Box Optimization via Error Correcting Codes, 2019
Adversarial Examples

- given a trained neural network
- constrained optimization problem

\[
\min_x ||x - x_0|| \text{ subject to } \text{probability}_j(x) > \text{probability}_i(x)
\]

(Szegedy et al., 2014, Goodfellow et al., 2015)
Comparison with finite differences and random search

- plane classified as truck in CIFAR10

| Class | Pr(class) |
|-------|-----------|
| 0     | 0.9984509 |
| 1     | 2.97521e-05 |
| 2     | 8.516136e-05 |
| 3     | 0.0006085799 |
| 4     | 1.0096494e-05 |
| 5     | 0.0007527866 |
| 6     | 2.6582893e-05 |
| 7     | 1.3017156e-05 |
| 8     | 1.4263238e-05 |
| 9     | 8.826052e-06 |

Pr(class = 0) = 0.9984509
Pr(class = 1) = 2.97521e-05
Pr(class = 2) = 8.516136e-05
Pr(class = 3) = 0.0006085799
Pr(class = 4) = 1.0096494e-05
Pr(class = 5) = 0.0007527866
Pr(class = 6) = 2.6582893e-05
Pr(class = 7) = 1.3017156e-05
Pr(class = 8) = 1.4263238e-05
Pr(class = 9) = 8.826052e-06

1000 iters with $c = 0.1$, ex_no = 10, $t = 1$

- Choromanski et al. Structured evolution with compact architectures for scalable policy optimization, 2018
Conclusions and future work

✓ Scalable and error resilient distributed computing system
✓ cheap encoding and decoding
✓ distributed Least Squares and GLMS
→ privacy and encryption
→ more general convex optimization problems with constraints, e.g.,
convex optimization for neural networks

M. Pilanci, T. Ergen

Neural Networks are Convex Regularizers: Exact Polynomial-time Convex Optimization Formulations for Two-Layer Networks, arXiv:2002.10553
M. Pilanci, Computational Polarization: An Information-theoretic Method for Resilient Computing arXiv Preprint, 2021. https://arxiv.org/pdf/2109.03877.pdf

B. Bartan, M. Pilanci, Straggler Resilient Serverless Computing Based on Polar Codes. 57th Annual Allerton Conference on Communication, Control, and Computing 2019, https://arxiv.org/pdf/1901.06811.pdf

B. Bartan, M. Pilanci, Distributed Black-Box Optimization via Error Correcting Codes. 57th Annual Allerton Conference on Communication, Control, and Computing 2019, https://arxiv.org/pdf/1907.05984.pdf

M. Pilanci, T. Ergen, Neural Networks are Convex Regularizers: Exact Polynomial-time Convex Optimization Formulations for Two-Layer Networks, ICML 2020