Abstract

The AdaBoost algorithm of Freund and Schapire (1997) was designed to combine many “weak” hypotheses that perform slightly better than a random guess into a “strong” hypothesis that has very low error. We study the rate at which AdaBoost iteratively converges to the minimum of the “exponential loss” with a fast rate of convergence. Our proofs do not require a weak-learning assumption, nor do they require that minimizers of the exponential loss are finite. Specifically, our first result shows that at iteration $t$, the exponential loss of AdaBoost’s computed parameter vector will be at most $\varepsilon$ more than that of any parameter vector of $l_1$-norm bounded by $B$ in a number of rounds that is bounded by a polynomial in $B$ and $1/\varepsilon$. We also provide rate lower bound examples showing a polynomial dependence on these parameters is necessary. Our second result is that within $C/\varepsilon$ iterations, AdaBoost achieves a value of the exponential loss that is at most $\varepsilon$ more than the best possible value, where $C$ depends on the dataset. We show that this dependence of the rate on $\varepsilon$ is optimal up to constant factors, i.e. at least $\Omega(1/\varepsilon)$ rounds are necessary to achieve within $\varepsilon$ of the optimal exponential loss.

Keywords: AdaBoost, optimization, coordinate descent, convergence rate.
convergence rates when there are no simplifying assumptions. For instance, we do not assume that the “weak learning assumption” necessarily holds, that all of the weak hypotheses perform are at least slightly better than random guessing. If the weak learning assumption holds, or if other assumptions hold, it is easier to prove a fast convergence rate for AdaBoost. However, in some cases where AdaBoost is commonly applied, such simplifying assumptions do not necessarily hold, and it is not as easy to find a convergence rate.

AdaBoost can be viewed as a coordinate descent (functional gradient descent) algorithm that iteratively minimizes an objective function $L : \mathbb{R}^n \rightarrow \mathbb{R}$ called the exponential loss (Breiman, 1999; Frean and Downs, 1998; Friedman et al., 2000; Friedman, 2001; Mason et al., 1999; Onoda et al., 1998; Rätsch et al., 2001; Schapire and Singer, 1999). The exponential loss is constructed from $m$ labeled training examples $(x_1, y_1), \ldots, (x_m, y_m)$, where the $x_i$’s are in some domain $\mathcal{X}$ and $y_i \in \{-1, +1\}$, and a set of hypotheses $\mathcal{H} = \{h_1, \ldots, h_N\}$, where each $h_j : \mathcal{X} \rightarrow \{-1, +1\}$. Specifically, the exponential loss is defined as follows:

$$L(\lambda) := \sum_{i=1}^{m} \exp\left(-\sum_{j=1}^{N} \lambda_j y_i h_j(x_i)\right).$$

In each iteration, a coordinate descent algorithm moves some distance along some coordinate direction. For AdaBoost, the coordinate directions are provided by the individual weak hypotheses. Correspondingly, AdaBoost chooses some weak hypotheses and a step length, and then adds that to the current combination. The direction and step length are so chosen that the resulting vector $\lambda^t$ in iteration $t$ yields a lower value of the exponential loss than in the previous iteration, $L(\lambda^t) < L(\lambda^{t-1})$. This repeats until it reaches a minimizer if one exists. It was shown by Collins et al. (2002), and later by Zhang and Yu (2005), that AdaBoost asymptotically converges to the minimum possible exponential loss. That is,

$$\lim_{t \rightarrow \infty} L(\lambda^t) = \inf_{\lambda \in \mathbb{R}^N} L(\lambda),$$

though that work did not address a convergence rate to the minimizer of the exponential loss.

Our work specifically addresses a recent conjecture of Schapire (2010) stating that there exists a positive constant $c$ and a polynomial $\text{poly}(\cdot)$ such that for all training sets and all finite sets of weak hypotheses, and for all $B > 0$,

$$L(\lambda^t) \leq \min_{\lambda : \|\lambda\|_1 \leq B} L(\lambda) + \frac{\text{poly}(\log N, m, B)}{t^c}. \quad (1)$$

In other words, the exponential loss of AdaBoost will be at most $\varepsilon$ more than that of any other parameter vector $\lambda$ of $\ell_1$-norm bounded by $B$ in a number of rounds that is bounded by a polynomial in $\log N, m, B$ and $1/\varepsilon$. (We require $\log N$ rather than $N$ since the number of weak hypotheses will typically be extremely large.) Along with an upper bound that is polynomial in these parameters, we also provide lower bound constructions showing some polynomial dependence on $B, \varepsilon^{-1}$ is necessary. Without any additional assumptions on the exponential loss $L$, and without altering AdaBoost’s minimization algorithm for $L$, the best known convergence rate of AdaBoost prior to this work that we are aware of is that of Bickel et al. (2006) who prove a bound on the rate of the form $O(1/\sqrt{\log t})$. 538
We provide also a convergence rate of AdaBoost to the minimum value of the exponential loss. Namely, within $C/\epsilon$ iterations, AdaBoost achieves a value of the exponential loss that is at most $\epsilon$ more than the best possible value, where $C$ depends on the dataset. This convergence rate is different from the one discussed above in that it has better dependence on $\epsilon$ (in fact the dependence is optimal, as we show), and does not depend on the best solution within a ball of size $B$. However, this second convergence rate cannot be used to prove (1) since in certain worst case situations, we show the constant $C$ may be larger than $2^m$ (although usually it will be much smaller).

Within the proof of the second convergence rate, we provide a lemma (called the decomposition lemma) that shows that the training set can be split into two sets of examples: the finite margin set, and the zero loss set. Examples in the finite margin set always make a positive contribution to the exponential loss, and they never lie too far from the decision boundary. Examples in the zero loss set do not have these properties. If we consider the exponential loss where the sum is only over the finite margin set (rather than over all training examples), it is minimized by a finite $\lambda$. The fact that the training set can be decomposed into these two classes is the key step in proving the second convergence rate.

This problem of determining the rate of convergence is relevant in the proof of the consistency of AdaBoost given by Bartlett and Traskin (2007), where it has a direct impact on the rate at which AdaBoost converges to the Bayes optimal classifier (under suitable assumptions). It may also be relevant to practitioners who wish to have a guarantee on the exponential loss value at iteration $t$.

There have been several works that make additional assumptions on the exponential loss in order to attain a better bound on the rate, but those assumptions are not true in general, and cases are known where each of these assumptions are violated. For instance, better bounds are proved by Rätsch et al. (2002) using results from Luo and Tseng (1992), but these appear to require that the exponential loss be minimized by a finite $\lambda$, and also depend on quantities that are not easily measured. There are many cases where $L$ does not have a finite minimizer; in fact, one such case is provided by Schapire (2010). Shalev-Shwartz and Singer (2008) have proven bounds for a variant of AdaBoost. Zhang and Yu (2005) also have given rates of convergence, but their technique requires a bound on the change in the size of $\lambda^t$ at each iteration that does not necessarily hold for AdaBoost. Many classic results are known on the convergence of iterative algorithms generally (see for instance Luenberger and Ye, 2008; Boyd and Vandenberghe, 2004); however, these typically start by assuming that the minimum is attained at some finite point in the (usually compact) space of interest. When the weak learning assumption holds, there is a parameter $\gamma > 0$ that governs the improvement of the exponential loss at each iteration. Freund and Schapire (1997) and Schapire and Singer (1999) showed that the exponential loss is at most $e^{-2t\gamma^2}$ after $t$ rounds, so AdaBoost rapidly converges to the minimum possible loss under this assumption.

In Section 2 we summarize the coordinate descent view of AdaBoost. Section 3 contains the proof of the conjecture and associated lower bounds. Section 4 provides the $C/\epsilon$ convergence rate.
Given: \((x_1, y_1), \ldots, (x_m, y_m)\) where \(x_i \in \mathcal{X}, y_i \in \{-1, +1\}\)

set \(\mathcal{H} = \{h_1, \ldots, h_N\}\) of weak hypotheses \(h_j : \mathcal{X} \rightarrow \{-1, +1\}\).

Initialize: \(D_1(i) = 1/m\) for \(i = 1, \ldots, m\).

For \(t = 1, \ldots, T\):

- Train weak learner using distribution \(D_t\); that is, find weak hypothesis \(h_t \in \mathcal{H}\) whose correlation \(r_t = \mathbb{E}_{x \sim D_t} [y_t h_t(x)]\) has maximum magnitude \(|r_t|\).
- Choose \(\alpha_t = \frac{1}{2} \ln \left( \frac{(1 + r_t)}{(1 - r_t)} \right)\).
- Update, for \(i = 1, \ldots, m\): \(D_{t+1}(i) = D_t(i) \exp(-\alpha_t y_i h_t(x_i)) / Z_t\) where \(Z_t\) is a normalization factor (chosen so that \(D_{t+1}\) will be a distribution).

Output the final hypothesis: \(F(x) = \text{sign} \left( \sum_{t=1}^{T} \alpha_t h_t(x) \right)\).

Figure 1: The boosting algorithm AdaBoost.

2. Coordinate Descent View of AdaBoost

From the examples \((x_1, y_1), \ldots, (x_m, y_m)\) and hypotheses \(\mathcal{H} = \{h_1, \ldots, h_N\}\), AdaBoost iteratively computes the function \(F : \mathcal{X} \rightarrow \mathbb{R}\), where \(\text{sign}(F(x))\) can be used as a classifier for a new instance \(x\). The function \(F\) is a linear combination of the hypotheses. At each iteration \(t\), AdaBoost chooses one of the weak hypotheses, \(h_t\) from the set \(\mathcal{H}\), and adjusts its coefficient by a specified value \(\alpha_t\). Then \(F\) is constructed after \(T\) iterations as: \(F(x) = \sum_{t=1}^{T} \alpha_t h_t(x)\).

Since each \(h_t\) is equal to \(h_{j_t}\) for some \(j_t\), \(F\) can also be written \(F(x) = \sum_{j=1}^{N} \lambda_j h_j(x)\) for a vector of values \(\lambda = \langle \lambda_1, \ldots, \lambda_N \rangle\) (such vectors will sometimes also be referred to as combinations, since they represent combinations of weak hypotheses). In different notation, we can write AdaBoost as a coordinate descent algorithm on vector \(\lambda\). We define the “feature matrix” \(M\) elementwise by \(M_{ij} = y_i h_j(x_i)\), so that this matrix contains all of the inputs to AdaBoost (the training examples and hypotheses). Then the exponential loss can be written more compactly as:

\[
L(\lambda) = \frac{1}{m} \sum_{i} e^{-(M\lambda)_i}
\]

where \((M\lambda)_i\), the \(i\)th coordinate of the vector \(M\lambda\), is the “margin” achieved by vector \(\lambda\) on training example \(i\).

Coordinate descent algorithms choose a coordinate at each iteration where the directional derivative is the steepest, and choose a step that maximally decreases the objective along that coordinate. To perform coordinate descent on the exponential loss, we determine the coordinate \(j_t\) at iteration \(t\) as follows, where \(e_j\) is a vector that is \(1\) in the \(j\)th position and \(0\) elsewhere:

\[
j_t \in \arg\max_j \left| -\frac{dL(\lambda^{t-1} + \alpha e_j)}{d\alpha} \right|_{\alpha=0} = \arg\max_j \frac{1}{m} \left| \sum_{i=1}^{m} e^{-(M\lambda^{t-1})_i} M_{ij} \right|.
\]

It can be shown (see, for instance Mason et al., 2000) that the distribution \(D_t\) chosen by AdaBoost at each round \(t\) puts weight \(D_t(i)\) proportional to \(e^{-(M\lambda^{t-1})_i}\). Expression (2) can
The Rate of Convergence of AdaBoost

now be rewritten as

\[ j_t \in \arg\max_j \left| \sum_i D_t(i) M_{ij} \right| = \arg\max_j \left| \mathbb{E}_{i \sim D_t} [M_{ij}] \right| = \arg\max_j \left| \mathbb{E}_{i \sim D_t} [y_i h_j(x_i)] \right|, \]

which is exactly the way AdaBoost chooses a weak hypothesis in each round (see Figure 1). The correlation \( \sum_i D_t(i) M_{ij} \) will be denoted by \( r_t \) and its absolute value \( |r_t| \), denoted by \( \delta_t \). The quantity \( \delta_t \) is commonly called the edge for round \( t \). The distance \( \alpha_t \) to travel along direction \( j_t \) is chosen to minimize the \( L(\lambda_t^{-1} + \alpha e_{j_t}) \), and can be shown to be equal to \( \alpha_t = \frac{1}{2} \ln \left( \frac{1+r_t}{1-r_t} \right) \) (see, for instance Mason et al., 2000), just as in Figure 1. With this choice of step length, it can be shown (see, for instance Freund and Schapire, 1997) that the exponential loss drops by an amount depending on the edge:

\[ L(\lambda^t) = L(\lambda^{t-1}) \sqrt{1 - \delta_t^2}. \]

Our rate bounds also hold when the weak-hypotheses are confidence rated, that is, giving real-valued predictions in \([-1, +1]\), so that \( h : \mathcal{X} \to [-1, +1] \). In that case, the criterion for picking a weak hypothesis in each round remains the same, that is, at round \( t \), an \( \bar{h}_{j_t} \) maximizing the absolute correlation \( j_t \in \arg\max_j \left| \sum_{i=1}^m e^{-(BM\lambda_{t-1})} M_{ij} \right| \), is chosen, where \( M_{ij} \) may now be non-integral. An exact analytical line search is no longer possible, but if the step size is chosen in the same way

\[ \alpha_t = \frac{1}{2} \ln \left( \frac{1+r_t}{1-r_t} \right), \]

then Freund and Schapire (1997) and Schapire and Singer (1999) show that a similar drop in the loss is still guaranteed

\[ L(\lambda^t) \leq L(\lambda^{t-1}) \sqrt{1 - \delta_t^2}. \]

With confidence rated hypotheses, other implementations may choose the step size in a different way. However, in this paper, by AdaBoost we will always mean the version in (Freund and Schapire, 1997; Schapire and Singer, 1999) which chooses step sizes as in (3), and enjoys the loss guarantee as in (4). That said, all our proofs work more generally, and are robust to numerical inaccuracies in the implementation. In other words, even if the previous conditions are violated by a small amount, similar bounds continue to hold, although we leave out explicit proofs of this fact to simplify the presentation.

3. Convergence to any target loss

In this section, we bound the number of rounds of AdaBoost required to get within \( \varepsilon \) of the loss attained by any parameter vector \( \lambda^* \) as a function of \( \varepsilon \) and the \( \ell_1 \)-norm \( \|\lambda^*\|_1 \). The vector \( \lambda^* \) serves as a reference based on which we define the target loss \( L(\lambda^*) \), and its \( \ell_1 \)-norm is a measure of difficulty of attaining the target loss. We prove a bound polynomial in \( 1/\varepsilon, \|\lambda^*\|_1 \) and the number of examples \( m \), showing (1) holds, thereby resolving affirmatively the open problem posed in (Schapire, 2010). Later in the section we provide lower bounds showing how a polynomial dependence on both parameters is necessary.

**Theorem 1** For any \( \lambda^* \in \mathbb{R}^N \), AdaBoost achieves loss at most \( L(\lambda^*) + \varepsilon \) in at most \( 13\|\lambda^*\|_1^5 \varepsilon^{-5} \) rounds.
The high level idea behind the proof of the theorem is as follows. To show a fast rate, we require a large edge in each round, as indicated by (4). A large edge is guaranteed if the size of the current solution of AdaBoost is small. Therefore AdaBoost makes good progress if the size of its solution does not grow too fast. On the other hand, the increase in size of its solution is given by the step length, which in turn is proportional to the edge achieved in that round. Therefore, if the solution size grows fast, the loss also drops fast. Either way the algorithm makes good progress. In the rest of the section we make these ideas concrete through a sequence of lemmas. The proof of Theorem 1 is based on these lemmas and appears later. We conclude by indicating possibilities for improvement in our analysis that might help tighten the exponents in the rate bound of Theorem 1.

We provide some more notation. Throughout, \( \lambda^* \) is fixed, and its \( \ell_1 \)-norm is denoted by \( B \) (matching the notation in (Schapire, 2010)). One key parameter is the suboptimality \( R_t \) of AdaBoost’s solution measured via the logarithm of the exponential loss

\[
R_t = \ln L(\lambda^t) - \ln L(\lambda^*).
\]

Another key parameter is the \( \ell_1 \)-distance \( S_t \) of AdaBoost’s solution from the closest combination that achieves the target loss

\[
S_t = \inf_{\lambda} \{ \|\lambda - \lambda^t\|_1 : L(\lambda) \leq L(\lambda^*) \}.
\]

We will also be interested in how they change as captured by

\[
\Delta R_t = R_{t-1} - R_t \geq 0, \quad \Delta S_t = S_t - S_{t-1}.
\]

Notice that \( \Delta R_t \) is always non-negative since AdaBoost decreases the loss, and hence the suboptimality, in each round. Let \( T_0 \) be the bound on the number of rounds in Theorem 1. We assume without loss of generality that \( R_0, \ldots, R_{T_0} \) and \( S_0, \ldots, S_{T_0} \) are all strictly positive, since otherwise the theorem holds trivially. Also, in the rest of the section, we restrict our attention entirely to the first \( T_0 \) rounds of boosting. We first show that a poly\((B, \varepsilon^{-1})\) rate of convergence follows if the edge is always polynomially large compared to the suboptimality.

**Lemma 2** If for some constants \( c_1, c_2 \), where \( c_2 > 1/2 \), the edge satisfies \( \delta_t \geq B^{-c_1} R_t^{c_2} \) in each round \( t \), then AdaBoost achieves at most \( L(\lambda^*) + \varepsilon \) loss after \( 2B^{2c_1}(\varepsilon \ln 2)^{1-2c_2} \) rounds.

**Proof** From the definition of \( R_t \) and (4) we have

\[
\Delta R_t = \ln L(\lambda^{t-1}) - \ln L(\lambda^t) \geq -\frac{1}{2} \ln(1 - \delta_t^2) \geq 0.
\]

Combining the above with the inequality \( e^x \geq 1 + x \), and the assumption on the edge

\[
\Delta R_t \geq -\frac{1}{2} \ln(1 - \delta_t^2) \geq \delta_t^2/2 \geq \frac{1}{2} B^{-2c_1} R_{t-1}^{2c_2}.
\]

Let \( T = [2B^{2c_1}(\varepsilon \ln 2)^{1-2c_2}] \) be the bound on the number of rounds in the Lemma. If any of \( R_0, \ldots, R_T \) is negative, then by monotonicity \( R_T < 0 \) and we are done. Otherwise, they are
all non-negative. Then, applying Lemma 18 from the Appendix to the sequence $R_0, \ldots, R_T$, and using $c_2 > 1/2$ we get

$$R_T^{1-2c_2} \geq R_0^{1-2c_2} + c_2 B^{-2c_1} T > (1/2) B^{-2c_1} T \geq (\varepsilon \ln 2)^{1-2c_2} \implies R_T < \varepsilon \ln 2.$$  

If either $\varepsilon$ or $L(\lambda^*)$ is greater than 1, then the lemma follows since $L(\lambda^T) \leq L(\lambda^0) = 1 < L(\lambda^*) + \varepsilon$. Otherwise,

$$L(\lambda^T) < L(\lambda^*) e^{\varepsilon \ln 2} \leq L(\lambda^*)(1 + \varepsilon) \leq L(\lambda^*) + \varepsilon,$$

where the second inequality uses $e^x \leq 1 + (1/\ln 2)x$ for $x \in [0, \ln 2]$.

We next show that large edges are achieved provided $S_t$ is small compared to $R_t$.

**Lemma 3** In each round $t$, the edge satisfies $\delta_t \geq R_{t-1}/S_{t-1}$.

**Proof** For any combination $\lambda$, define $p_\lambda$ as the distribution on examples $\{1, \ldots, m\}$ that puts weight proportional to the loss $p_\lambda(i) = e^{-(M/\lambda)_i/(mL(\lambda))}$. Choose any $\lambda$ suffering less than the target loss $L(\lambda) \leq L(\lambda^*)$. By non-negativity of relative entropy we get

$$0 \leq \operatorname{RE}(p_{\lambda^{t-1}} \parallel p_\lambda) = \sum_{i=1}^m p_{\lambda^{t-1}} \ln \left( \frac{1/m e^{-(M/\lambda)_{i}/(mL(\lambda))}}{1/m e^{-(M/\lambda)_{i}/L(\lambda)}} \right)$$

$$= -R_{t-1} + \sum_{i=1}^m p_{\lambda^{t-1}}(i) \left( M\lambda - M\lambda^{t-1} \right)_i. \quad (6)$$

Note that $p_{\lambda^{t-1}}$ is the distribution $D_t$ that AdaBoost creates in round $t$. The above summation can be rewritten as

$$\sum_{i=1}^m p_{\lambda^{t-1}}(i) \sum_{j=1}^N \left( \lambda_j - \lambda_j^{t-1} \right) M_{ij} = \sum_{j=1}^N \left( \lambda_j - \lambda_j^{t-1} \right) \sum_{i=1}^m D_t(i) M_{ij}$$

$$\leq \left( \sum_{j=1}^N |\lambda_j - \lambda_j^{t-1}| \right) \max_j \left| \sum_{i=1}^m D_t(i) M_{ij} \right| = \delta_t \|\lambda - \lambda^{t-1}\|_1. \quad (7)$$

Since the previous holds for any $\lambda$ suffering less than the target loss, the last expression is at most $\delta_t S_{t-1}$. Combining this with (7) completes the proof.  

To complete the proof of Theorem 1, we show $S_t$ is small compared to $R_t$ in rounds $t \leq T_0$ (during which we have assumed $S_t, R_t$ are all non-negative). In fact we prove:

**Lemma 4** For any $t \leq T_0$, $S_t \leq B^3 R_t^{-2}$.

This, along with Lemmas 2 and 3, proves Theorem 1. The bound on $S_t$ in Lemma 4 can be proven if we can first show $S_t$ grows slowly compared to the rate at which the suboptimality $R_t$ falls. Intuitively this holds since growth in $S_t$ is caused by a large step, which in turn will drive down the suboptimality. In fact we can prove the following.
Lemma 5 In any round $t \leq T_0$, we have $\frac{2\Delta R_t}{R_{t-1}} \geq \frac{\Delta S_t}{S_{t-1}}$.

Proof Firstly, it follows from the definition of $S_t$ that $\Delta S_t \leq \|\lambda_t - \lambda_{t-1}\|_1 = |\alpha_t|$. Next, using (5) and (3) we may write $\Delta R_t \geq \Upsilon(\delta_t) |\alpha_t|$, where the function $\Upsilon$ has been defined in (Rätsch and Warmuth, 2005) as

$$\Upsilon(x) = -\ln\left(\frac{1-x^2}{1+x}ight).$$

It is known (Rätsch and Warmuth, 2005; Rudin et al., 2007) that $\Upsilon(x) \geq x/2$ for $x \in [0, 1]$. Combining and using Lemma 3

$$\Delta R_t \geq \delta_t \Delta S_t / 2 \geq R_{t-1} (\Delta S_t / 2S_{t-1}).$$

Rearranging completes the proof. ■

Using this we may prove Lemma 4.

Proof We first show $S_0 \leq B^3 R_0^{-2}$. Note, $S_0 \leq \|\lambda^* - \lambda^0\|_1 = B$, and by definition $R_0 = -\ln\left(\frac{1}{m} \sum_i e^{-M \lambda^*}_i\right)$. The quantity $(M \lambda^*)_i$ is the inner product of row $i$ of matrix $M$ with the vector $\lambda^*$. Since the entries of $M$ lie in $[-1, +1]$, this is at most $\|\lambda^*\|_1 = B$. Therefore $R_0 \leq -\ln\left(\frac{1}{m} \sum_i e^{-B}\right) = B$, which is what we needed.

To complete the proof, we show that $R^2 S_t$ is non-increasing. It suffices to show for any $t$ the inequality $R^2 S_t \leq R^2 S_{t-1} S_{t-1}$. This holds by the following chain

$$R^2 S_t = (R_{t-1} - \Delta R_t)^2 (S_{t-1} + \Delta S_t) = R^2_{t-1} S_{t-1} \left(1 - \frac{\Delta R_t}{R_{t-1}}\right)^2 \left(1 + \frac{\Delta S_t}{S_{t-1}}\right) \leq R^2_{t-1} S_{t-1} \exp\left(-\frac{2\Delta R_t}{R_{t-1}} + \frac{\Delta S_t}{S_{t-1}}\right) \leq R^2_{t-1} S_{t-1},$$

where the first inequality follows from $e^x \geq 1 + x$, and the second one from Lemma 5. ■

3.1. Lower-bounds

Here we show that the dependence of the rate in Theorem 1 on the norm $\|\lambda^*\|_1$ of the solution achieving target accuracy is necessary for a wide class of datasets. The arguments in this section are not tailored to AdaBoost, but hold more generally for any coordinate descent algorithm and a wide variety of loss functions.

Lemma 6 Suppose the feature matrix $M$ corresponding to a dataset has two rows with $\{-1, +1\}$ entries which are complements of each other, i.e. there are two examples on which any hypothesis gets one wrong and one correct prediction. Then the number of rounds required to achieve a target loss $\phi^*$ is at least $\inf \{\|\lambda\|_1 : L(\lambda) \leq \phi^*\} / (2 \ln m)$.

Proof We first show that the two examples corresponding to the complementary rows in $M$ both satisfy a certain margin boundedness property. Since each hypothesis predicts
oppositely on these, in any round $t$ their margins will be of equal magnitude and opposite sign. Unless both margins lie in $[-\ln m, \ln m]$, one of them will be smaller than $-\ln m$. But then the exponential loss $L(\lambda^t) = (1/m) \sum_j e^{-(M\lambda^t)^i_j}$ in that round will exceed 1, a contradiction since the losses are non-increasing through rounds, and the loss at the start was 1. Thus, assigning one of these examples the index $i$, we have the absolute margin $|\langle M\lambda^0\rangle_i|$ is bounded by $\ln m$ in any round $t$. Letting $M(i)$ denote the $i$th row of $M$, the step length $\alpha_t$ in round $t$ therefore satisfies
\[
|\alpha_t| = |M_{ij_t}\alpha_t| = |\langle M(i), \alpha_t e_{j_t}\rangle| = |(M\lambda^t)_i - (M\lambda^{t-1})_i| \leq \|(M\lambda^t)_i\| + \|(M\lambda^{t-1})_i\| \leq 2\ln m,
\]
and the statement of the lemma directly follows.

The next lemma constructs a feature matrix satisfying the properties of Lemma 6 and where additionally the smallest size of a solution achieving $\phi^* + \varepsilon$ is at least $\Omega(2^m) \ln(1/\varepsilon)$, for some fixed $\phi^*$ and every $\varepsilon > 0$. This implies that when $\varepsilon$ is a small constant (say $\varepsilon = 0.01$) AdaBoost takes at least $\Omega(2^m/\ln m)$ steps to get within $\varepsilon/2$ of the loss achieved by some $\lambda^*$ with loss $\phi^* + \varepsilon/2$. Since $m$ might be arbitrarily larger than $\varepsilon^{-1}$, this shows that a polynomial dependence of the convergence rate on the norm of the competing solution is unavoidable. Further this norm might be exponential in the number of training examples and weak hypotheses in the worst case, and hence the bound $\text{poly}(\|\lambda^*\|_1, 1/\varepsilon)$ in Theorem 1 cannot be replaced by $\text{poly}(m, N, 1/\varepsilon)$.

**Lemma 7** 1 Consider the following matrix $M$ derived out of abstaining weak hypotheses. $M$ has $m + 1$ rows labeled 0, ..., $m$ and $m$ columns labeled 1, ..., $m$ (assume $m \geq 2$). The square sub-matrix ignoring row zero is an upper triangular matrix, with 1’s on the diagonal, −1’s above the diagonal, and 0 below the diagonal. Therefore row one is $(+, -, \ldots, -)$, and row zero is defined to be just the complement of row one. Then, for any $\varepsilon > 0$, a loss of $2/(m + 1) + \varepsilon$ is achievable on this dataset, but with large norms
\[
\inf \{\|\lambda\|_1 : L(\lambda) \leq 2/(m + 1) + \varepsilon\} \geq \Omega(2^m) \ln(1/3\varepsilon).
\]
Therefore, by Lemma 6, the minimum number of rounds required for reaching loss at most $2/(m + 1) + \varepsilon$ is at least $\Omega \left( \frac{2^m}{m^2} \right) \ln(1/3\varepsilon)$.

**Proof** We first show $2/(m + 1) + \varepsilon$ loss is achievable for any $\varepsilon$. Note that if $x = (2^m - 1, 2^{m-1}, 2^{m-2}, \ldots, 1)$ then $Mx$ achieves a margin of 1 on examples 2 through $m$, and zero margin on the first two examples. Therefore $\ln(1/\varepsilon)x$ achieves loss $(2 + (m - 1)\varepsilon)/(m + 1) \leq 2/(m + 1) + \varepsilon$, for any $\varepsilon > 0$.

Next we lower bound the norm of solutions achieving loss at most $2/(m + 1) + \varepsilon$. Observe that since rows 0 and 1 are complementary, any solution’s loss on just examples 0 and 1 will add up to at least $2/(m + 1)$. Therefore, to get within $2/(m + 1) + \varepsilon$, the margins on examples 2, ..., $m$ should be at least $\ln \left( \frac{m-1}{m+1} \right) \leq \ln(1/3\varepsilon)$ (for $m \geq 2$). Now, a solution $\lambda$ gets margin at least $\ln(1/3\varepsilon)$ on example $m$ implies $\lambda_m \geq \ln(1/3\varepsilon)$ (since the other columns get zero margin on it). Since column $m$ gets margin −1 on example $m - 1$, and column $m - 1$ is the only column with a positive margin on that example, the previous fact forces

1. We thank Nikhil Srivastava for informing us of the matrix used in this lemma.
\[ \lambda_{m-1} \geq \ln(1/3\varepsilon) + \lambda_m \geq 2 \ln(1/3\varepsilon). \] Continuing this way, we get \[ \lambda_i \geq (2^{m+1-i} - 1) \ln(1/3\varepsilon) \] for \( i = m, \ldots, 2. \) Hence \[ \|\lambda\| \geq \ln(1/3\varepsilon)(2 + \ldots + 2^{m-1} - (m-2)) = (2^m + 2 - m) \ln(1/3\varepsilon) \geq \Omega(2^m) \ln(1/3\varepsilon). \]

In the next section we investigate the optimal dependence on the parameter \( \varepsilon \) and show that \( \Omega(1/\varepsilon) \) number of rounds are necessary.

4. Convergence to optimal loss

In the previous section, our rate bound depended on both the approximation parameter \( \varepsilon \), as well as the size of the smallest solution achieving the target loss. For many datasets, the optimal target loss \( \inf_\lambda L(\lambda) \) cannot be realized by any finite solution. In such cases, if we want to bound the number of rounds needed to achieve within \( \varepsilon \) of the optimal loss, the only way to use Theorem 1 is to first decompose the accuracy parameter \( \varepsilon \) into two parts \( \varepsilon = \varepsilon_1 + \varepsilon_2 \), find some finite solution \( \lambda^* \) achieving within \( \varepsilon_1 \) of the optimal loss, and then use the bound \( \text{poly}(1/\varepsilon_2, \|\lambda^*\|_1) \) to achieve at most \( L(\lambda^*) + \varepsilon_2 = \inf_\lambda L(\lambda) + \varepsilon \) loss. However, this introduces implicit dependence on \( \varepsilon \) through \( \|\lambda^*\|_1 \) which may not be immediately clear. In this section, we show bounds of the form \( C/\varepsilon \), where the constant \( C \) depends only on the feature matrix \( M \), and not on \( \varepsilon \).

**Theorem 8** AdaBoost reaches within \( \varepsilon \) of the optimal loss in at most \( C/\varepsilon \) rounds, where \( C \) only depends on the feature matrix.

Additionally, we show that this dependence on \( \varepsilon \) is optimal in Lemma 17 of the Appendix, where \( \Omega(1/\varepsilon) \) rounds are shown to be necessary for converging to within \( \varepsilon \) of the optimal loss on a certain dataset. Finally, we note that the lower bounds in the previous section indicate that \( C \) can be \( \Omega(2^m) \) in the worst case for integer matrices (although it will typically be much smaller), and hence this bound, though stronger than that of Theorem 1 with respect to \( \varepsilon \), cannot be used to prove the conjecture in (Schapire, 2010), since the constant is not polynomial in the number of examples \( m \).

Our techniques build upon earlier work on the rate of convergence of AdaBoost, which have mainly considered two particular cases. In the first case, the weak learning assumption holds, that is, the edge in each round is at least some fixed constant. In this situation, Freund and Schapire (1997) and Schapire and Singer (1999) show that the optimal loss is zero, no solution with finite size can achieve this loss, but AdaBoost achieves at most \( \varepsilon \) loss within \( O(\ln(1/\varepsilon)) \) rounds. In the second case some finite combination of the weak classifiers achieves the optimal loss, and Rätsch et al. (2002), using results from (Luo and Tseng, 1992), show that AdaBoost achieves within \( \varepsilon \) of the optimal loss again within \( O(\ln(1/\varepsilon)) \) rounds.

Here we consider the most general situation, where the weak learning assumption may fail to hold, and yet no finite solution may achieve the optimal loss. The dataset used in Lemma 17 and shown in Figure 2 exemplifies this situation. Our main technical contribution shows that the examples in any dataset can be partitioned into a zero-loss set and finite-margin set, such that a certain form of the weak learning assumption holds within the zero-loss set, while the optimal loss considering only the finite-margin set can be obtained by some finite solution. The two partitions provide different ways of making progress in
every round, and one of the two kinds of progress will always be sufficient for us to prove Theorem 8.

We next state our decomposition result, illustrate it with an example, and then state several lemmas quantifying the nature of the progress we can make in each round. Using these lemmas, we prove Theorem 8.

**Lemma 9 (Decomposition Lemma)** For any dataset, there exists a partition of the set of training examples \( X \) into a (possibly empty) zero-loss set \( A \) and a (possibly empty) finite-margin set \( F = A^c \triangleq X \setminus A \) such that the following hold simultaneously:

1. For some positive constant \( \gamma > 0 \), there exists some vector \( \eta^\dagger \) with unit \( \ell_1 \)-norm \( \| \eta^\dagger \|_1 = 1 \) that attains at least \( \gamma \) margin on each example in \( A \), and exactly zero margin on each example in \( F \)

\[
\forall i \in A : (M \eta^\dagger)_i \geq \gamma, \quad \forall i \in F : (M \eta^\dagger)_i = 0.
\]

2. The optimal loss considering only examples within \( F \) is achieved by some finite combination \( \eta^* \).

3. (Corollary to Item 2) There is a constant \( \mu_{\text{max}} < \infty \), such that for any combination \( \eta \) with bounded loss on the finite-margin set, \( \sum_{i \in F} e^{-(M\eta)_i} \leq m \), the margin \( (M\eta)_i \) for any example \( i \) in \( F \) lies in the bounded interval \([-\ln m, \mu_{\text{max}}]\).

A proof is deferred to the next section. The Decomposition Lemma immediately implies that the vector \( \eta^* + \infty \cdot \eta^\dagger \), defined as the limit of \( \lim_{c \to \infty} (\eta^* + c\eta^\dagger) \), is an optimal solution, achieving zero loss on the zero-loss set, but only finite margins (and hence positive losses) on the finite-margin set (thereby justifying the names).

Before proceeding, we give an example dataset and indicate the zero-loss set, finite-margin set, \( \eta^* \) and \( \eta^\dagger \) to illustrate our definitions. Consider a dataset with three examples \( \{a, b, c\} \) and two hypotheses \( \{h_1, h_2\} \) and the following feature matrix \( M \).

|   | \( h_1 \) | \( h_2 \) |
|---|---|---|
| a | + | − |
| b | − | + |
| c | + | + |

Figure 2:

Here + means correct \((M_{ij} = +1)\) and − means wrong \((M_{ij} = -1)\). The optimal solution is \( \infty \cdot (h_1 + h_2) \) with a loss of \( 2/3 \). The finite-margin set is \( \{a, b\} \), the zero-loss set is \( \{c\} \), \( \eta^\dagger = (1/2, 1/2) \) and \( \eta^* = (0, 0) \); for this dataset these are unique. This dataset also serves as a lower-bound example in Lemma 17, where we show that \( 0.22/\varepsilon \) rounds are necessary for AdaBoost to achieve less than \((2/3) + \varepsilon\) loss on it.

Before providing proofs, we introduce some notation. By \( \| \cdot \| \) we will mean \( \ell_2 \)-norm; every other norm will have an appropriate subscript, such as \( \| \cdot \|_1 \), \( \| \cdot \|_{\infty} \), etc. The set of all training examples will be denoted by \( X \). By \( \ell^A(i) \) we mean the exp-loss \( e^{-(M\lambda)_i} \) on example \( i \). For any subset \( S \subset X \) of examples, \( \ell^A(S) = \sum_{i \in S} \ell^A(i) \) denotes the total exp-loss on
the set $S$. Notice $L(\lambda) = (1/m)\ell^\lambda(X)$, and that $D_t(i) = \ell^{\lambda_t}(i)/\ell^{\lambda_t}(X)$, where $\lambda_t$ is the combination found by AdaBoost in round $t$. By $\delta_S(\eta;\lambda)$ we mean the edge obtained on the set $S$ by the vector $\eta$, when the weights over the examples are given by $\ell^\lambda(\cdot)/\ell^\lambda(S)$:

$$
\delta_S(\eta;\lambda) = \left| \frac{1}{\ell^\lambda(S)} \sum_{i \in S} \ell^\lambda(i)(M\eta) \right|.
$$

In the rest of the section, by loss we mean the unnormalized loss $\ell^\lambda(X) = mL(\lambda)$ and study convergence to within $\varepsilon$ of the optimal unnormalized loss $\inf_\lambda \ell^\lambda(X)$, henceforth denoted by $K$. Note that this is the same as converging to within $\varepsilon/m$ of the optimal normalized loss, that is to within $\inf_\lambda L(\lambda) + \varepsilon/m$. Hence a $C'/\varepsilon$ bound for the unnormalized loss translates to a $C'm^{-1}/\varepsilon$ bound for the normalized loss and vice versa, and does not affect the result in Theorem 8. The progress due to the zero-loss set is now immediate from Item 1 of the Decomposition Lemma:

**Lemma 10** In any round $t$, the maximum edge $\delta_t$ is at least $\gamma \left\{ \frac{\ell^{\lambda_t-1}(A)}{\ell^{\lambda_t-1}(X)} \right\}$, where $\gamma$ is as in Item 1 of the Decomposition Lemma.

**Proof** Recall the distribution $D_t$ created by AdaBoost in round $t$ puts weight $D_t(i) = \ell^{\lambda_t(i)}/\ell^{\lambda_t(X)}$ on each example $i$. From Item 1 we get

$$
\delta_X(\eta^\dagger;\lambda^{t-1}) = \left| \frac{1}{\ell^{\lambda_t-1}(X)} \sum_{i \in X} \ell^{\lambda_t-1}(i)(M\eta^\dagger) \right| = \frac{1}{\ell^{\lambda_t-1}(X)} \sum_{i \in A} \gamma \ell^{\lambda_t-1}(i) = \gamma \left\{ \frac{\ell^{\lambda_t-1}(A)}{\ell^{\lambda_t-1}(X)} \right\}.
$$

Next define $p$ to be a distribution on the columns $\{1, \ldots, N\}$ of $M$ which puts probability $p(j)$ proportional to $|\eta^\dagger_j|$ on column $j$. Since $(M\eta^\dagger)_i = \sum_j \eta^\dagger_j (Me_j)_i$, we may rewrite the edge $\delta_X(\eta^\dagger;\lambda^{t-1})$ as follows

$$
\delta_X(\eta^\dagger;\lambda^{t-1}) = \left| \frac{1}{\ell^{\lambda_t-1}(X)} \sum_{i \in X} \ell^{\lambda_t-1}(i) \sum_j \eta^\dagger_j (Me_j)_i \right| = \left| \sum_j \eta^\dagger_j \frac{1}{\ell^{\lambda_t-1}(X)} \sum_{i \in X} \ell^{\lambda_t-1}(i)(Me_j)_i \right| = \sum_j \eta^\dagger_j \delta_X(e_j;\lambda^{t-1}) \leq \sum_j |\eta^\dagger_j| \delta_X(e_j;\lambda^{t-1}).
$$

Since the $\ell_1$-norm of $\eta^\dagger$ is 1, the weights $|\eta^\dagger_j|$ form some distribution $p$ over the columns $1, \ldots, N$. We may therefore conclude

$$
\gamma \left\{ \frac{\ell^{\lambda_t-1}(A)}{\ell^{\lambda_t-1}(X)} \right\} \leq \delta_X(\eta^\dagger;\lambda^{t-1}) \leq \mathbb{E}_{j \sim p} [\delta_X(e_j;\lambda^{t-1})] \leq \max_j \delta_X(e_j;\lambda^{t-1}) \leq \delta_t.
$$

If the set $F$ were empty, then Lemma 10 implies an edge of $\gamma$ is available in each round. This in fact means that the weak learning assumption holds, and using (4), we can
show a $O(\ln(1/\varepsilon)\gamma^{-2})$ bound matching the rate bounds in (Freund and Schapire, 1997) and
(Schapire and Singer, 1999). So henceforth, we assume that $F$ is non-empty. Note that this
implies that the optimal loss $K$ is at least 1 (since any solution will get non-positive margin
on some example in $F$), a fact we will use later in the proofs.

Lemma 10 says that the edge is large if the loss on the zero-loss set is large. On the
other hand, when it is small, Lemmas 11 and 12 together show how AdaBoost can make
good progress using the finite margin set. Lemma 11 uses second order methods to show
how progress is made in the case where there is a finite solution; such arguments may have
appeared in earlier work.

**Lemma 11** Suppose $\lambda$ is a combination such that $m \geq \ell^A(F) \geq K$. Then in some
coordinate direction the edge is at least $\sqrt{C_0 (\ell^A(F) - K) / \ell^A(F)}$, where $C_0$ is a constant
depending only on the feature matrix $M$.

**Proof** Let $M_F \in \mathbb{R}^{[F] \times N}$ be the matrix $M$ restricted to only the rows corresponding to the
examples in $F$. Choose $\eta$ such that $\lambda + \eta = \eta^*$ is an optimal solution over $F$. Without loss
of generality assume that $\eta$ lies in the orthogonal subspace of the null-space $\{u : M_F u = 0\}$
of $M_F$ (since we can translate $\eta^*$ along the null space if necessary for this to hold). If $\eta = 0$,
then $\ell^A(F) = K$ and we are done. Otherwise $\|M_F \eta\| \geq \lambda_{\text{min}}\|\eta\|$, where $\lambda^2_{\text{min}}$ is the smallest
positive eigenvalue of the symmetric matrix $M_F^T M_F$ (exists since $M_F \eta \neq 0$). Now define
$f : [0, 1] \to \mathbb{R}$ as the loss along the (rescaled) segment $[\eta^*, \lambda]$
\[ f(x) \triangleq \ell(\eta^* - x\eta)(F) = \sum_{i \in F} \ell(\eta^* - x\eta)(i) e^{x(M\eta)_i}. \]
This implies that $f(0) = K$ and $f(1) = \ell^A(F)$. Notice that the first and second derivatives
of $f(x)$ are given by
\[ f'(x) = \sum_{i \in F} (M_F \eta)_i \ell(\eta^* - x\eta)(i), \quad f''(x) = \sum_{i \in F} (M_F \eta)^2_i \ell(\eta^* - x\eta)(i). \]
We next lower bound possible values of the second derivative. We define a distribution $q$ on
examples $\{1, \ldots, m\}$ which puts probability proportional to $(M_F \eta)^2_i$ on example $i$. Then
we may rewrite the second derivative as
\[ f''(x) = \|M_F \eta\|^2 \mathbb{E}_{i \sim q} \left[ \ell(\eta^* - x\eta)(i) \right] \geq \|M_F \eta\|^2 \min_i \ell(\eta^* - x\eta)(i). \]
Since both $\lambda = \eta^* - \eta$, and $\eta^*$ suffer total loss at most $m$, therefore, by convexity, so does
$\eta^* - x\eta$ for any $x \in [0, 1]$. Hence we may apply Item 3 of the Decomposition Lemma to the
vector $\eta^* - x\eta$, for any $x \in [0, 1]$, to conclude that $\ell(\eta^* - x\eta)(i) = \exp\{-(M_F(\eta^* - x\eta))_i\} \geq e^{-\mu_{\text{max}}}$ on every example $i$. Therefore we have,
\[ f''(x) \geq \|M_F \eta\|^2 e^{-\mu_{\text{max}}} \geq \lambda^2_{\text{min}} e^{-\mu_{\text{max}}} \|\eta\|^2 \quad \text{(by choice of \eta)}. \]
A standard second-order result is (see e.g. Boyd and Vandenberghe, 2004, eqn. (9.9))
\[ |f'(1)|^2 \geq 2 \left( \inf_{x \in [0, 1]} f''(x) \right) \{f(1) - f(0)\}. \]
Collecting our results so far, we get
\[ \sum_{i \in F} \ell^A(i)(M \eta)_i = |f'(1)| \geq \|\eta\| \sqrt{2 \lambda_{\min}^2 e^{-\mu_{\max}} \{\ell^A(F) - K\}}. \]

Next let \( \tilde{\eta} = \eta/\|\eta\|_1 \) be \( \eta \) rescaled to have unit \( \ell_1 \) norm. Then we have
\[ \sum_{i \in F} \ell^A(i)(M \tilde{\eta})_i = \frac{1}{\|\eta\|_1} \sum_{i \in F} \ell^A(i)(M \eta)_i \geq \|\eta\|_1 \sqrt{2 \lambda_{\min}^2 e^{-\mu_{\max}} \{\ell^A(F) - K\}}. \]

Applying the Cauchy-Schwartz inequality, we may lower bound \( \|\eta\|_1 \) by \( 1/\sqrt{N} \) (since \( \eta \in \mathbb{R}^N \)). Along with the fact \( \ell^A(F) \leq m \), we may write
\[ \frac{1}{\ell^A(F)} \sum_{i \in F} \ell^A(i)(M \eta)_i \geq \sqrt{2 \lambda_{\min}^2 N^{-1} m^{-1} e^{-\mu_{\max}} \{\ell^A(F) - K\} / \ell^A(F)}, \]

If we define \( p \) to be a distribution on the columns \( \{1, \ldots, N\} \) of \( M_F \) which puts probability \( p(j) \) proportional to \( |\tilde{\eta}_j| \) on column \( j \), then we have
\[ \frac{1}{\ell^A(F)} \sum_{i \in F} \ell^A(i)(M \eta)_i \leq E_{j \sim p} \left| \frac{1}{\ell^A(F)} \sum_{i \in F} \ell^A(i)(Me_j)_i \right| \leq \max_j \left| \frac{1}{\ell^A(F)} \sum_{i \in F} \ell^A(i)(Me_j)_i \right|. \]

Notice the quantity inside max is precisely the edge \( \delta_F(e_j; \lambda) \) in direction \( j \). Combining everything, the maximum possible edge is
\[ \max_j \delta_F(e_j; \lambda) \geq \sqrt{C_0 \{\ell^A(F) - K\} / \ell^A(F)}, \]

where we define \( C_0 = 2m^{-1} N^{-1} \lambda_{\min}^2 e^{-\mu_{\max}} \).

**Lemma 12** Suppose, at some stage of boosting, the combination found by AdaBoost is \( \lambda \), and the loss is \( K + \theta \). Let \( \Delta \theta \) denote the drop in the suboptimality \( \theta \) after one more round; i.e. the loss after one more round is \( K + \theta - \Delta \theta \). Then, there are constants \( C_1, C_2 \) depending only on the feature matrix (and not on \( \theta \)), such that if \( \ell^A(A) < C_1 \theta \), then \( \Delta \theta \geq C_2 \theta \).

**Proof** Let \( \lambda \) be the current solution found by boosting. Using Lemma 11 pick a direction \( j \) in which the edge \( \delta_F(e_j; \lambda) \) restricted to the finite loss set is at least \( \sqrt{2C_0(\ell^A(F) - K)/\ell^A(F)} \).

We can bound the edge \( \delta_X(e_j; \lambda) \) on the entire set of examples as follows
\[ \delta_X(e_j; \lambda) = \frac{1}{\ell^A(X)} \left| \sum_{i \in F} \ell^A(i)(Me_j)_i + \sum_{i \in A} \ell^A(i)(Me_j)_i \right| \]
\[ \geq \frac{1}{\ell^A(X)} \left( |\ell^A(F)\delta_F(e_j; \lambda)| - \sum_{i \in A} \ell^A(i) \right) \]
\[ \geq \frac{1}{\ell^A(X)} \left( \sqrt{2C_0(\ell^A(F) - K)\ell^A(F) - \ell^A(A)} \right). \]
Now, $\ell^\lambda(A) < C_1 \theta$, and $\ell^\lambda(F) - K = \theta - \ell^\lambda(A) \geq (1 - C_1) \theta$. Further, we will choose $C_1 < 1$, so that $\ell^\lambda(F) \geq K \geq 1$. Hence, the previous inequality implies

$$\delta_X(e_j; \lambda) \geq \frac{1}{K + \theta} \left( \sqrt{2C_0(1 - C_1) \theta - C_1 \theta} \right).$$

Set $C_1 = \min \left\{ 1/2, (1/4)\sqrt{C_0/m} \right\}$. Using $\theta \leq K + \theta = \ell^\lambda(X) \leq m$, we can bound the square of the term in brackets on the previous line as

$$\left( \sqrt{2C_0(1 - C_1) \theta - C_1 \theta} \right)^2 \geq 2C_0(1 - C_1) \theta - 2C_1 \theta \sqrt{2C_0(1 - C_1) \theta}$$

$$\geq 2C_0(1 - 1/2) \theta - 2 \left\{ (1/4)\sqrt{C_0/m} \right\} \theta \sqrt{2C_0(1 - 1/2)m} \geq C_0 \theta / 2.$$

So, if $\delta$ is the maximum edge in any direction, then $\delta \geq \delta_X(e_j; \lambda) \geq \sqrt{C_0 \theta / (2m(K + \theta))}$ (again using $1/(K + \theta) \leq \sqrt{(K + \theta)m}$). Therefore the loss after one more step is at most $(K + \theta)\sqrt{1 - \delta^2} \leq (K + \theta)(1 - \delta^2/2) \leq K + \theta - C_0 \theta / 2m$. Setting $C_2 = C_0 / (2m)$ completes the proof.

**Proof of Theorem 8.** At any stage of boosting, let $\lambda$ be the current combination, and $K + \theta$ be the current loss. We show that the new loss is at most $K + \theta - \Delta \theta$ for $\Delta \theta \geq C_3 \theta^2$ for some constant $C_3$ depending only on the dataset (and not $\theta$). Lemma 18 and some algebra will then complete the proof.

To show this, either $\ell^\lambda(A) < C_1 \theta$, in which case Lemma 12 applies, and $\Delta \theta \geq C_2 \theta \geq (C_2/m)\theta^2$ (since $\theta = \ell^\lambda(X) - K \leq m$). Or $\ell^\lambda(A) \geq C_1 \theta$, in which case applying Lemma 10 yields $\delta \geq \gamma C_1 \theta / \ell^\lambda(X) \geq (\gamma C_1/m) \theta$. By (4), $\Delta \theta \geq \ell^\lambda(X)(1 - \sqrt{1 - \delta^2}) \geq \ell^\lambda(X) \delta^2 / 2 \geq (K/2)(\gamma C_1/m)^2 \theta^2$. Using $K \geq 1$ and choosing $C$ appropriately gives the required condition.

**4.1. Proof of the Decomposition Lemma**

Throughout this section we only consider (unless otherwise stated) admissible combinations $\lambda$ of weak classifiers, which have loss $\ell^\lambda(X)$ bounded by $m$ (since such are the ones found by boosting). We prove Lemma 9 in three steps. We begin with a simple lemma that rigorously defines the zero-loss and finite-margin sets.

**Lemma 13** For any sequence $\eta_1, \eta_2, \ldots$, of admissible combinations of weak classifiers, we can find a subsequence $\eta_{(1)} = \eta_{t_1}, \eta_{(2)} = \eta_{t_2}, \ldots$, whose losses converge to zero on all examples in some fixed (possibly empty) subset $S$ (the zero-loss set), and losses bounded away from zero in its complement $X \setminus S$ (the finite-margin set)

$$\forall x \in S : \lim_{t\to\infty} \ell^\eta_{(t)}(x) = 0, \quad \forall x \in X \setminus S : \inf_{t,i} \ell^\eta_{(t)}(x) > 0. \quad (8)$$

**Proof** We will build a zero-loss set and the final subsequence incrementally. Initially the set is empty. Pick the first example. If the infimal loss ever attained on the example in the sequence is bounded away from zero, then we do not add it to the set. Otherwise we add it, and consider only the subsequence whose $t^{th}$ element attains loss less than $1/t$ on the
Lemma 14 Suppose $M$ is the feature matrix, $A$ is a subset of the examples, and $\eta_1, \eta_2, \ldots, \eta_\infty$ is a sequence of combinations of weak classifiers such that $A$ is its zero loss set, and $X \setminus A$ its finite loss set, that is, (8) holds. Then there is a combination $\eta^\dagger$ of weak classifiers that achieves positive margin on every example in $A$, and zero margin on every example in its complement $X \setminus A$

$$
(M\eta^\dagger)_i \begin{cases} 
> 0 & \text{if } i \in A, \\
= 0 & \text{if } i \in X \setminus A.
\end{cases}
$$

Proof Since the $\eta_i$ achieve arbitrarily large positive margins on $A$, $\|\eta_i\|$ will be unbounded, and it will be hard to extract a useful single solution out of them. On the other hand, the rescaled combinations $\eta_i/\|\eta_i\|$ lie on a compact set, and therefore have a limit point, which might have useful properties. We formalize this next.

We use induction on the total number of training examples $|X|$. If $X$ is zero, then the lemma holds vacuously for any $\eta^\dagger$. Assume inductively for all $X$ of size less than $m > 0$, and consider $X$ of size $m$. Since translating a vector along the null space of $M$, $\ker M = \{x : Mx = 0\}$ has no effect on the margins produced by the vector, assume without loss of generality that the $\eta_i$’s are orthogonal to $\ker M$. Also, since the margins produced on the zero loss set are unbounded, so are the norms of $\eta_i$. Therefore assume (by picking a subsequence and relabeling if necessary) that $\|\eta_i\| > t$. Let $\eta'$ be a limit point of the sequence $\eta_i/\|\eta_i\|$, a unit vector that is also orthogonal to the null-space. Then firstly $\eta'$ achieves non-negative margin on every example; otherwise by continuity for some extremely large $t$, the margin of $\eta_i/\|\eta_i\|$ on that example is also negative and bounded away from zero, and therefore $\eta_i$’s loss is more than $m$, a contradiction to admissibility. Secondly, the margin of $\eta'$ on each example in $X \setminus A$ is zero; otherwise, by continuity, for arbitrarily large $t$ the margin of $\eta_i/\|\eta_i\|$ on an example in $X \setminus A$ is positive and bounded away from zero, and hence that example attains arbitrarily small loss in the sequence, a contradiction to (8). Finally, if $\eta'$ achieves zero margin everywhere in $A$, then $\eta'$, being orthogonal to the null-space, must be $0$, a contradiction since $\eta'$ is a unit vector. Therefore $\eta'$ must achieve positive margin on some non-empty subset $Z$ of $A$, and zero margins on every other example.

Next we use induction on the reduced set of examples $X' = X \setminus Z$. Since $Z$ is non-empty, $|X'| < m$. Further, using the same sequence $\eta_i$, the zero-loss and finite-loss sets, restricted to $X'$, are $A' = A \setminus Z$ and $(X \setminus A) \setminus Z = X \setminus A$ (since $Z \subseteq A$) = $X' \setminus A'$. By the inductive hypothesis, there exists some $\eta''$ which achieves positive margins on $A'$, and zero margins on $X' \setminus A' = X \setminus A$. Therefore, by setting $\eta' = \eta' + c\eta''$ for a large enough $c$, we can achieve
Applying Lemma 14 to the sequence \( \eta^*(t) \) yields some convex combination \( \eta^\dagger \) having margin at least \( \gamma > 0 \) (for some \( \gamma \)) on \( A \) and zero margin on its complement, proving Item 1 of the Decomposition Lemma. The next lemma proves Item 2.

**Lemma 15** There is a (finite) combination \( \eta^* \) which achieves the same margins on \( F \) as the optimal solution.

**Proof** The existence of \( \eta^\dagger \) with properties as in Lemma 14 implies that the optimal loss is the same whether considering all the examples, or just examples in \( F \). Therefore it suffices to show the existence of finite \( \eta^* \) that achieves loss \( K \) on \( F \), that is, \( \ell^{\eta^*}(F) = K \).

Recall \( M_F \) denotes the matrix \( M \) restricted to the rows corresponding to examples in \( F \). Let \( \ker M_F = \{ x : M_F x = 0 \} \) be the null-space of \( M_F \). Let \( \eta(t) \) be the projection of \( \eta(t) \) onto the orthogonal subspace of \( \ker M_F \). Then the losses \( \ell^{\eta(t)}(F) = \ell^{\eta(t)}(F) \) converge to the optimal loss \( K \). If \( M_F \) is identically zero, then each \( \eta(t) = 0 \), and then \( \eta^* = 0 \) has loss \( K \) on \( F \). Otherwise, let \( \lambda^2 \) be the smallest positive eigenvalue of \( M_F^T M_F \). Then \( \| M \eta(t) \| \geq \lambda \| \eta(t) \| \).

By the definition of finite margin set, \( \inf_{t \to \infty} \ell^{\eta(t)}(F) = \inf_{t \to \infty} \ell^{\eta(t)}(F) > 0 \). Therefore, the margins \( \| M \eta(t) \| \) are bounded, and hence the \( \eta(t) \) are also bounded in norm. Therefore they have a (finite) limit point \( \eta^* \) which must have loss \( K \) over \( F \).

As a corollary, we prove Item 3.

**Lemma 16** There is a constant \( \mu_{\max} < \infty \), such that for any combination \( \eta \) that achieves bounded loss on the finite-margin set, \( \ell^{\eta}(F) \leq m \), the margin \( (M \eta)_i \) for any example \( i \) in \( F \) lies in the bounded interval \( [-\ln m, \mu_{\max}] \).

**Proof** The loss \( \ell^{\eta}(F) \) at most \( m \) implies no margin may be less than \( -\ln m \). If Item 3 of the Decomposition Lemma were false, then for some example \( x \in F \) there exists a sequence of combinations of weak classifiers, whose \( t^{th} \) element achieves more than margin \( t \) on \( x \) but has loss at most \( m \) on \( F \). Applying Lemma 13 we can find a subsequence \( \lambda^{(t)} \) whose tail achieves zero-loss on some non-empty subset \( S \) of \( F \) containing \( x \), and bounded margins in \( F \setminus S \). Applying Lemma 14 to \( \lambda^{(t)} \) we get some convex combination \( \lambda^\dagger \) which has positive margins on \( S \) and zero margin on \( F \setminus S \). Let \( \eta^* \) be as in Lemma 15, a finite combination achieving the optimal loss on \( F \). Then \( \eta^* + \infty \cdot \lambda^\dagger \) achieves the same loss on every example in \( F \setminus S \) as the optimal solution \( \eta^* \), but zero loss for examples in \( S \). This solution is strictly better than \( \eta^* \) on \( F \), a contradiction to the optimality of \( \eta^* \).

**References**

Peter L. Bartlett and Mikhail Traskin. AdaBoost is consistent. *Journal of Machine Learning Research*, 8:2347–2368, 2007.

Peter J. Bickel, Ya’acov Ritov, and Alon Zakai. Some theory for generalized boosting algorithms. *Journal of Machine Learning Research*, 7:705–732, 2006.
Stephen Boyd and Lieven Vandenberghe. *Convex Optimization*. Cambridge University Press, 2004.

Leo Breiman. Prediction games and arcing classifiers. *Neural Computation*, 11(7):1493–1517, 1999.

Rich Caruana and Alexandru Niculescu-Mizil. An empirical comparison of supervised learning algorithms. In *Proceedings of the 23rd International Conference on Machine Learning*, 2006.

Michael Collins, Robert E. Schapire, and Yoram Singer. Logistic regression, AdaBoost and Bregman distances. *Machine Learning*, 48(1/2/3), 2002.

Marcus Frean and Tom Downs. A simple cost function for boosting. Technical report, Department of Computer Science and Electrical Engineering, University of Queensland, 1998.

Yoav Freund and Robert E. Schapire. A decision-theoretic generalization of on-line learning and an application to boosting. *Journal of Computer and System Sciences*, 55(1):119–139, August 1997.

Jerome Friedman, Trevor Hastie, and Robert Tibshirani. Additive logistic regression: A statistical view of boosting. *Annals of Statistics*, 28(2):337–374, April 2000.

Jerome H. Friedman. Greedy function approximation: A gradient boosting machine. *Annals of Statistics*, 29(5), October 2001.

David G. Luenberger and Yinyu Ye. *Linear and nonlinear programming*. Springer, third edition, 2008.

Z. Q. Luo and P. Tseng. On the convergence of the coordinate descent method for convex differentiable minimization. *Journal of Optimization Theory and Applications*, 72(1):7–35, January 1992.

Llew Mason, Jonathan Baxter, Peter Bartlett, and Marcus Frean. Functional gradient techniques for combining hypotheses. In *Advances in Large Margin Classifiers*. MIT Press, 1999.

Llew Mason, Jonathan Baxter, Peter Bartlett, and Marcus Frean. Boosting algorithms as gradient descent. In *Advances in Neural Information Processing Systems 12*, 2000.

T. Onoda, G. Rätsch, and K.-R. Müller. An asymptotic analysis of AdaBoost in the binary classification case. In *Proceedings of the 8th International Conference on Artificial Neural Networks*, pages 195–200, 1998.

G. Rätsch, T. Onoda, and K.-R. Müller. Soft margins for AdaBoost. *Machine Learning*, 42(3):287–320, 2001.

Gunnar Rätsch and Manfred K. Warmuth. Efficient margin maximizing with boosting. *Journal of Machine Learning Research*, 6:2131–2152, 2005.
Gunnar Rätsch, Sebastian Mika, and Manfred K. Warmuth. On the convergence of leveraging. In Advances in Neural Information Processing Systems 14, 2002.

Cynthia Rudin, Robert E. Schapire, and Ingrid Daubechies. Analysis of boosting algorithms using the smooth margin function. Annals of Statistics, 35(6):2723–2768, 2007.

Robert E. Schapire. The convergence rate of AdaBoost. In The 23rd Conference on Learning Theory, 2010. open problem.

Robert E. Schapire and Yoram Singer. Improved boosting algorithms using confidence-rated predictions. Machine Learning, 37(3):297–336, December 1999.

Shai Shalev-Shwartz and Yoram Singer. On the equivalence of weak learnability and linear separability: New relaxations and efficient boosting algorithms. In 21st Annual Conference on Learning Theory, 2008.

Xindong Wu, Vipin Kumar, J. Ross Quinlan, Joydeep Ghosh, Qiang Yang, Hiroshi Motoda, Geoffrey J. McLachlan, Angus Ng, Bing Liu, Philip S. Yu, Zhi-Hua Zhou, Michael Steinbach, David J. Hand, and Dan Steinberg. Top 10 algorithms in data mining. Knowledge and Information Systems, 14(1):1–37, 2008.

Tong Zhang and Bin Yu. Boosting with early stopping: Convergence and consistency. Annals of Statistics, 33(4):1538–1579, 2005.
Lemma 17  To get within $\varepsilon < 0.1$ of the optimum loss on the dataset in Table 2, AdaBoost takes at least $0.22/\varepsilon$ steps.

Proof  Note that optimum loss is $2/3$, and we are bounding the number of rounds necessary to get within $(2/3)+\varepsilon$ loss for $\varepsilon < 0.1$. We begin by showing that for rounds $t \geq 3$, the edge achieved is $1/t$. First observe that the edges in rounds 1 and 2 are $1/3$ and $1/2$. Our claim will follow from the following stronger claim. Let $w^t_a, w^t_b, w^t_c$ denote the normalized-losses (adding up to 1) or weights on examples $a, b, c$ at the beginning of round $t$, and $\delta_t$ the edge in round $t$. Then for $t \geq 2$,

1. Either $1/2 = w^t_a$ or $1/2 = w^t_b$.
2. $\delta_{t+1} = \delta_t/(1 + \delta_t)$.

Proof by induction. Base case may be checked. Suppose the inductive assumption holds for $t$. Assume without loss of generality that $1/3 = w^t_a > w^t_b > w^t_c$. Then in round $t$, $h_a$ gets picked, the edge $\delta_t = 2w^t_c$, and $w^{t+1}_b = 1/2, w^{t+1}_c = (w^t_c/2)/(1 + w^t_c) = w^t_c/(1 + 2w^t_c)$. Hence, in round $t + 1$ $h_b$ gets picked and we get edge $\delta_{t+1} = 2w^t_c/(1 + 2w^t_c) = \delta_t/(1 + \delta_t)$. Proof follows by induction. Note the recurrence on $\delta_t$ yields $\delta_t = 1/t$ for $t \geq 3$.

Next we find the loss after each iteration. The loss after $T$ rounds is

$$\sqrt{1 - (1/3)^2} \prod_{i=2}^{T} \sqrt{1 - 1/i^2}$$

and can be computed as follows. Notice that in the following list

$$1 - (1/2)^2 = (1 \cdot 3)/(2 \cdot 2),$$
$$1 - (1/3)^2 = (2 \cdot 4)/(3 \cdot 3),$$
$$1 - (1/4)^2 = (3 \cdot 5)/(4 \cdot 4),$$
$$\ldots = \ldots,$$

the middle denominator $(3 \cdot 3)$ gets canceled by the right term of the first numerator and the left term of the third denominator. Continuing this way, the product till term $1 - (1/T)^2$ is $(1/2) \{ (T + 1)/T \}$. Therefore the loss after round $T$ is $(2/3) \sqrt{1 + 1/T} \geq (2/3) + (2/9)T$, for $T \geq 3$. Since the error after 3 rounds is still at least $(2/3) + 0.1$ the Lemma holds for $\varepsilon < 0.1$. 

Lemma 18  Suppose $u_0, u_1, \ldots$, are non-negative numbers satisfying

$$u_t - u_{t+1} \geq c_0 u^1_t + c_1,$$

for some non-negative constants $c_0, c_1$. Then, for any $t$,

$$\frac{1}{u^t_t} - \frac{1}{u^t_0} \geq c_1 c_0 t.$$
The Rate of Convergence of AdaBoost

Proof By induction on $t$. The base case is an identity. Assume Lemma holds for $t$. Then,

$$\frac{1}{u_{t+1}^{c_1}} - \frac{1}{w_0^{c_1}} \geq \left( \frac{1}{u_{t+1}^{c_1}} - \frac{1}{w_t^{c_1}} \right) + \left( \frac{1}{u_t^{c_1}} - \frac{1}{w_0^{c_1}} \right) \geq \frac{1}{u_{t+1}^{c_1}} - \frac{1}{w_t^{c_1}} + c_0 t, \text{ (by induction)}. $$

Thus it suffices to show

$$\frac{1}{u_{t+1}^{c_1}} - \frac{1}{u_t^{c_1}} \geq c_1 c_0 \iff \left( \frac{u_t}{u_{t+1}} \right)^{c_1} \geq 1 + c_1 c_0 u_t^{c_1} \iff \frac{1}{(1 - c_0 u_t^{c_1})^{c_1}} \geq 1 + c_1 c_0 u_t^{c_1}. $$

Since $1 + c_1 c_0 u_t^{c_1} \leq (1 + c_0 u_t^{c_1})^{c_1}$, and $(1 + c_0 u_t^{c_1}) (1 - c_0 u_t^{c_1}) < 1$, the inequality holds.  \[\blacksquare\]