Pipeline Signed Japanese Translation Focusing on a Post-positional Particle Complement and Conjugation in a Low-resource Setting

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Abstract

Because sign language is a visual language, the translation of it into spoken language is typically performed through an intermediate representation called gloss notation. In sign language, function words, such as particles and determiners, are not explicitly expressed, and there is little or no concept of morphological inflection in sign language. Therefore, gloss notation does not include such linguistic constructs. Because of these factors, we argue that sign language translation is effectively processed by taking advantage of the similarities and differences between sign language and its spoken counterpart. We thus propose a pipeline translation method that clearly focuses on the difference between spoken Japanese and signed Japanese written in gloss notation. Specifically, our method first uses statistical machine translation (SMT) to map glosses to corresponding spoken language words. We then use three transformer-based seq2seq models trained using a large out-of-domain monolingual Japanese corpus to complement postpositional particles and estimate conjugations for the verbs, adjectives, and auxiliary verbs in the first translation. We apply the seq2seq models in sequence until the translation converges. Our experimental results show that the proposed method performs robustly on the low-resource corpus and is +4.4/+4.9 points above the SMT baseline for BLEU-3/4.

1 Introduction

It is essential to build a social infrastructure for hearing-impaired and hearing communities to share sufficient information so that they can quickly obtain information necessary for daily life and disasters and lead a safe and secure life. Sign language used in deaf communities has different vocabulary and grammar from spoken language. There are two variations of sign language in Japan (Chonan, 2001): (1) Japanese Sign Language (JSL) and (2) Manually Coded Japanese (MCJ). JSL is often used by early signers, and syntax, such as word order and language structure, is different from spoken Japanese. By contrast, the syntax of MCJ is similar to that of spoken Japanese in terms of word order. It is used by late signers or acquired hearing-impaired people. However, the two variations are said to be used interchangeably and there is no clear boundary between them. In this work, we consider an intermediate between JSL and MCJ, and denote it Signed Japanese (SJ) in the following discussion.

Translation from sign language to spoken language is typically performed in two steps. First, consecutive signs are recognized from a video signal and transformed into an intermediate representation called a gloss, then the gloss is translated into a sentence in spoken language. Current state-of-the-art sign language recognition and translation methods (Camgöz et al. 2020; Yin and Read 2020) require a large amount of data and pay little attention to differences between sign language and the corresponding spoken language. Therefore, the success of these approaches relies heavily on large paired corpora, and resource-poor sign language studies, including SJ, cannot take advantage of such approaches. In sign language, function words, such as pre-positional or post-positional particles and determiners, do not tend to be explicitly signed, and inflectional morphemes associated with verbal predicates that express categories, such as tense, mood, and aspect, are not manually signed, in general. For example, in SJ, post-positional particles ‘助詞’ are generally not explicitly signed, and the signs associated with verbal predicates are not conjugated, whereas in Japanese, verbs, adjectives, and auxiliary verbs are conjugated. Therefore, the gloss does not include such language constructs.
Although gloss notation is commonly used by writing a series of spoken words that correspond to each sign in capital letters, because of the lack of sign language resources, its quality and size differ greatly according to the language (Bungeroth et al., 2008). SJ signs are heavily polysemous and their meaning is often context sensitive. Additionally, there is no publicly available corpus for SJ translation studies. Therefore, in this study, we use an in-house corpus that uses our gloss notation method. The details of the corpus and its notation are described in Section 2.

To solve challenging problems, we propose a novel pipeline method to translate from SJ written in gloss to Japanese. In particular, we focus on the linguistic differences between SJ and Japanese and estimate the post-positional particles that are missing and the appropriate forms of morphological inflection of words. Our method assumes that the ground truth gloss of the signed sentence is available. This assumption does not limit the availability of the above two-step sign language translation method. Our method first uses phrase-based statistical machine translation to match the SJ gloss to Japanese words. Then we refine the results further using transformer-based seq2seq (Sutskever et al., 2014) models, which are trained using a large out-of-domain parallel corpus. Specifically, we use three different seq2seq models (1) to complement the post-positional particles, (2) to apply morphological inflection by conjugating verbs, adjectives, and auxiliary verbs, and (3) to re-estimate the post-positional particles over the previous output. We repeatedly apply these models sequentially and adjust the translation results until they converge.

The proposed method works robustly, even for small training datasets, which are typically of the order of thousands of pairs in a dataset, and the results show that the state-of-the-art method is inferior to the SMT baseline with the low-resource setting. We found that iterative updates of translations are effective for improving the grammaticality and fluency of the translation output. Our experimental results show that the proposed model provides +4.4/+4.9 higher translation performance for BLEU3/BLEU4 scores compared with the SMT baseline.

2 Materials

We use two corpora: one is a small in-house SJ and Japanese parallel corpus, and the other is a large out-of-domain Japanese monolingual corpus. We describe the details of each corpus as follows.

2.1 SJ and Japanese parallel corpus

The locally organized in-house parallel corpus contains 1,086 sentence pairs with >7.5K glosses from a vocabulary of 655 words, and >11K Japanese words from a vocabulary of >1.2K words. The average length of a gloss sentence is 6.9 words, with a maximum length of 12 words and minimum length of 2 words, and the average length of a Japanese sentence is 10.3 words, with a maximum length of 21 words and minimum length of 5 words. The corpus consists of the ground truth gloss transcriptions of signs and their translations to Japanese sentences. The sentences are various spontaneous conversations that seemingly took place at municipal offices, such as asking for a certified copy of the resident register, pension, and unemployment insurance. In the corpus, a gloss word is written in the form $gN$, where $N$ corresponds to an arbitrary unique number. We adopt this notation instead of using Japanese words because glosses in SJ are heavily polysemous and a sign maps to different Japanese words depending on the context. Instead, we use an auxiliary dictionary to map each gloss to spoken words or phrases. This notation method also helps the proposed method to select the appropriate Japanese word or phrase within the phrase-based statistical machine translation model that we use in the study.

Because of the sparsity of the parallel corpus, approximately 2.3% of the glosses are singletons, so we add all gloss dictionary items as additional parallel data to reduce OOV issues at test time.

2.2 Out-of-domain Japanese corpus

We use a subset of the Balanced Corpus of Contemporary Written Japanese \(^1\) as an out-of-domain Japanese corpus to manually generate pseudo parallel corpora. The details of the corpus generation procedure are described in Section 3. To select the subsets, we use pattern matching to select sentences that end in a pattern such as $\sim$ か？(question), ～でした。(admit), ～ほしいで

\(^1\)https://pj.ninjal.ac.jp/corpus_center/bccwj/en/
Figure 1: Overall pipeline translation architecture from a gloss sequence $G$ to a grammatical Japanese sequence $S_{PP-C}$. The green and gray arrows indicate the translations by a statistical machine translation model and three neural machine translation models, respectively. The table in the upper right corner shows an excerpt from the gloss dictionary. (p.pos. = post-positional)

### 3 Methodology

The overall proposed pipeline translation system is shown in Fig. 1. $G$ represents a gloss sequence and $S$ represents a Japanese sequence. We define two subscripts for $S$, that is, $PP$, which denotes ‘post-positional particle,’ and $C$, which denotes ‘conjugation,’ with the prefix + or − for each subscript, which denotes the existence or non-existence, respectively, of post-positional particles and conjugation. The definition of each term is provided in Table 1.

| post-positional particles | conjugation |
|---------------------------|-------------|
| $S_{PP-C}$                | √           |
| $S_{PP-C}$                | √           |
| $S_{PP+C}$                | √           |

Table 1: Definitions of terms for the variants of $S$

### 3.1 Translation method

The proposed pipeline translation consists of six steps. Algorithm 1 shows the steps applied in sequence to gradually convert from $G$ to $S_{PP+C}$, which is the final translation of this algorithm. The details of each step are as follows:

**Step 0: Translate $G$ into $S_{PP-C}$**

We use a phrase-based statistical machine translation (pbsmt) (Koehn et al., 2007) to translate $G$ into $S_{PP-C}$. In this step, we map each gloss phrase to the appropriate Japanese phrases without considering the post-positional particles and conjugations of the output Japanese sequence.

**Step 1: Translate $S_{PP-C}$ into $S_{PP+C}$**

We use a transformer-based seq2seq model (Vaswani et al., 2017) (s2s_m1) to translate $S_{PP-C}$ into $S_{PP+C}$. In this step, the model estimates missing post-positional particles in $S_{PP-C}$ and inserts them to generate $S_{PP+C}$.

**Step 2: Translate $S_{PP-C}$ into $S_{PP+C}$**

We use another transformer-based seq2seq model (s2s_m2) to translate $S_{PP-C}$ into $S_{PP+C}$. In this step, the model estimates the appropriate morphological inflection or conjugated form for verbs, adjectives, and auxiliary verbs in $S_{PP-C}$ to generate $S_{PP+C}$.

**Step 3: Convert $S_{PP+C}$ to $S_{PP-C}$**

In this step, we remove the previously estimated post-positional particles in $S_{PP+C}$ from Step 2 to generate $S_{PP-C}$.

**Step 4: Translate $S_{PP+C}$ into $S_{PP+C}$**

We use the other transformer-based seq2seq model (s2s_m3) to translate $S_{PP+C}$ into $S_{PP+C}$ by...
re-estimating missing post-positional particles. In Step 1, we estimated the post-positional particles over a Japanese sequence in the canonical form \(S_{-PP-C}\); however, in the present step, we estimate them over for the conjugated word sequence \(S_{+PP+C}\). We assume that this will correct the previous estimation using the conjugated form of the word sequence obtained in the previous steps.

**Step 5: Convert \(S_{+PP+C}\) to \(S_{+PP-C}\)**

In this step, we transform \(S_{+PP+C}\) to \(S_{+PP-C}\) by converting words in \(S_{+PP+C}\) to their canonical form. Steps 3, 4, 5, and 2 are repeated until the translation output converges or the number of iterations reaches the maximum limit (10).

### Algorithm 1 Translation of a sign gloss sequence into a Japanese sentence

**Input:** \(G\)

**Output:** \(S_{+PP-C}\)

Step 0: \(G \rightarrow S_{-PP-C}\)

Step 1: \(S_{-PP-C} \rightarrow S_{+PP-C}\)

Step 2: \(S_{+PP-C} \rightarrow S_{+PP-C}\)

\(S_{prev} = \emptyset\)

\(S_{next} = S_{+PP+C}\)

while \(S_{prev} \neq S_{next}\) do

\(S_{prev} = S_{next}\)

Step 3: \(S_{+PP+C} \rightarrow S_{+PP-C}\)

Step 4: \(S_{+PP+C} \rightarrow S_{+PP-C}\)

Step 5: \(S_{+PP-C} \rightarrow S_{+PP-C}\)

Step 2: \(S_{+PP-C} \rightarrow S_{+PP-C}\)

\(S_{next} = S_{+PP+C}\)

end while

return \(S_{next}\)

the following noisy-channel model to estimate the best target Japanese word sentence \(s \in S_{-PP-C}\) for a source Japanese word \(g \in G\) as

\[
s_{best} = \text{argmax}_s p(g|s)p_{LM}(s),
\]

where \(p_{LM}(s)\) is a language model based on the \(n\)-grams of \(S_{-PP-C}\). \(p(g|s)\) is decomposed into a phrase-based formula using a phrase translation table and phrase reordering model (Koehn et al., 2007). For the language model, we use modified 3-gram Kneser–Ney smoothing.

### 4.2 Encoder-decoder translation models in Steps 1, 2, and 4

For the seq2seq models used in Steps 1, 2, and 4 in Section 3.1, we use a transformer-based encoder-decoder model (Ott et al., 2019). For all models, we use an encoder and decoder with an embedding of size 512, FFN-embedding of size 2048, and six layers with eight attention heads. We use the Adam optimizer with label smoothing cross-entropy loss with a smoothing factor of 0.1. We set the initial learning rate to 5e-4 with a warmup updates of 4,000 and use the inverse sqrt learning rate scheduler. We set the maximum tokens in a batch to 4K. We use tied embedding for the input and output layers. We obtain the hyperparameters from a non-exhaustive parameter search, and the results are shown in Table 9 of the Appendix.

We randomly split the corpus into training, validation, and test sets in an 8:1:1 ratio. For tokenization, we use byte pair encoding (Sennrich et al., 2016), which is trained using the training dataset. We set the number of operations to 10K for each tokenization of the seq2seq models. For the seq2seq model in Step 1, we pre-process the out-of-domain monolingual corpus as follows:

- **Source:** preprocess Japanese sequences by deleting post-positional particles and converting all conjugated words, such as verbs, adjectives, and auxiliary verbs, to their canonical forms.

- **Target:** preprocess Japanese sequences by leaving post-positional particles untouched and converting all conjugated words, such as verbs, adjectives, and auxiliary verbs, to their canonical forms.

The pre-processed corpus becomes the pseudo-parallel corpus to train the seq2seq model in Step 2.
1 to translate $S_{-PP-C}$ into $S_{+PP-C}$. The training corpora of the other seq2seq models, that is, $s2s_m1$, $s2s_m2$, and $s2s_m3$ in Step 4, are similarly preprocessed and independently trained using the pseudo-parallel corpus.

We observed that training the seq2seq model in Step 2 took more than a few hundred epochs, whereas training the seq2seq model in Steps 1 and 4 took less than 30 epochs. We used the models with the lowest validation loss for the experiments. The results on the test set demonstrated that the BLEU4 scores were 74.20, 98.75, and 75.06 for $s2s_m1$, $s2s_m2$, and $s2s_m3$, respectively. This indicates that post-positional particle estimation is more uncertain compared with the estimation of morphological inflection.

5 Experiments

To evaluate the proposed method, we conducted 100 experiments and for each test, we randomly selected 10 samples from the parallel corpus for testing and used the remaining samples to retrain the statistical machine translation model in Step 0. For each test, we finetuned the parameters of the seq2seq model ($s2s_m1$, $s2s_m2$, $s2s_m3$) by the training data and we used a beam size of 5 for decoding of the models. We averaged the 100 results to calculate the metrics of the performance.

We denote the proposed method in Section 3.1 by SMT+Iterative_s2s and compared its performance with the following baselines (naive, LSTMs, and SMT), the variants of the proposed method (SMT+1step_s2s and SMT+2step_s2s) and the transformer-based end-to-end Gloss2Text (G2T) model proposed by Yin and Read (2020). The followings are the brief explanations of each model.

- **naive**: This baseline replaces each gloss word with a Japanese word using the gloss dictionary. If more than one Japanese word is defined for a gloss, the first word is used.

- **LSTM**: This baseline uses encoder-decoder LSTM with an attention mechanism (Bahdanau et al., 2015) to directly translate $G$ into $S_{+PP+C}$. The model is trained using the parallel corpus without using the out-of-domain corpus and is configured with several different hyperparameter settings.

- **SMT**: This baseline uses only the statistical machine translation model to directly translate $G$ into $S_{+PP+C}$. This model is trained using the parallel corpus and without using the out-of-domain corpus.

- **SMT+1step_s2s**: This model is a variant of the proposed model which first executes Step 0 of Algorithm 1 to translate $G$ into $S_{-PP-C}$. Then it uses another seq2seq model trained using the out-of-domain corpus to directly translate $S_{-PP-C}$ into $S_{+PP+C}$. We compared the performance of this model, which jointly estimates post-positional particles and conjugations, with the model that estimates them separately using different models.

- **SMT+2step_s2s**: This model is another variant of the proposed model which performs Steps 0–2, but does not iteratively update the translation result as it does in Algorithm 1. We examined how the iterative updates of the result with SMT+Iterative_s2s contribute to the performance compared with the model without them.

For G2T, we changed the original hyperparameters suggested by Yin and Read (2020) and found that the following parameters were optimal using hyperparameter search on our parallel corpus. Encoder and decoder: embed-size = 256, FFN-embed-size = 1024, num-layer = 1, num-attention-head = 4.

5.1 Results

Table 2 shows the results of the experiment. To evaluate performance, we used the following metrics, BLEU-1/2/3/4 (Papineni et al., 2002), METEOR (Banerjee and Lavie, 2005), and word error rate (WER), and averaged the scores to obtain the results. The results showed that the proposed model (SMT+Iterative_s2s) outperformed the other models. The poor performance of the naive model indicates that the simple lookup method using the gloss dictionary did not produce successful results. LSTMs with different hyperparameters varying in the dimensions of the embedding and the hidden layers (256, 512, 1024) and the number of layers (1, 2) show the baseline performances to directly translate $G$ into $S_{+PP+C}$. Among them, the LSTM with the dimensions of the embedding and the hidden layers of 1024 and the number of layers of 1 showed the best performance. The best LSTM and the G2T were inferior
Table 2: Performance evaluations of naive, LSTMs, G2T (Yin and Read, 2020), SMT, SMT+1step_s2s, SMT+2step_s2s, and SMT+Iterative_s2s on BLEU1/2/3/4↑ and METEOR↑, and word error rate (WER) ↓ by averaging the scores from all experiments. The hyperparameters of LSTMs, the dimensions of the embedding and hidden layers, and the number of layers, are specified in the columns of ‘embed’, ‘hidden’, and ‘layers’, respectively. We use the same parameters for the encoder and the decoder of the LSTMs.

| Model          | Step | Source | Target       | GS  | EP  |
|----------------|------|--------|--------------|-----|-----|
| naive          |      |        |              | 0.184 | 0.049 |
| 256            |      |        |              | 0.628 | 0.538 |
| 512            |      |        |              | 0.692 | 0.608 |
| 1024           |      |        |              | 0.717 | 0.634 |
| LSTM           |      |        |              | 0.628 | 0.538 |
| 256            |      |        |              | 0.448 | 0.314 |
| 512            |      |        |              | 0.558 | 0.440 |
| 1024           |      |        |              | 0.590 | 0.466 |
| G2T (Yin and Read, 2020) |      |        |              | 0.695 | 0.640 |
| SMT            |      |        |              | 0.788 | 0.724 |
| SMT+1step_s2s  |      |        |              | 0.811 | 0.756 |
| SMT+2step_s2s  |      |        |              | 0.811 | 0.756 |
| SMT+Iterative_s2s |      |        |              | **0.817** | **0.762** |

Table 3: Error propagation analysis of SMT+Iterative_s2s. The score is the exact match for the correct ratio (%) (GS = gold standard, EP = error propagation).

| Model     | Step | Source | Target   | GS  | EP  |
|-----------|------|--------|----------|-----|-----|
| pbsmt     | 0    | G      | S−PP−C   | 38.0|     |
| s2s_m1    | 1    | S−PP−C | S−PP−C   | 79.5| 35.1|
| s2s_m2    | 2    | S−PP−C | S−PP−C   | 99.2| 35.1|
| s2s_m3    | 4    | S−PP−C | S−PP−C   | 86.9| 36.1|

5.2 Qualitative Evaluation

Table 5 shows the qualitative evaluations of the results using the proposed model and the other models with BLEU4, WER, and perplexity (PPL) scores. PPL in the last column was measured by the transformer-based language model that was pretrained by using the 494M-word Japanese Wikipedia.
We observed that the results of SMT and G2T had more post-positional particle selection errors than the other pipeline models, and the results of SMT+1step_s2s had more verb conjugation errors than SMT+2step_s2s, which suggest the efficacy of the independent estimation of post-positional particles and conjugations. We confirmed that the post-positional particle estimations using SMT+Iterative_s2s were either more natural or less error-prone than those using SMT+2step_s2s, which made the translation results more fluent.

| Loop count | Freq.   |
|------------|---------|
| 1          | 723 (72.3%) |
| 2          | 258 (25.8%) |
| 3          | 4 (0.4%)   |
| 4          | 6 (0.6%)   |
| 6          | 1 (0.1%)   |
| 7          | 2 (0.2%)   |
| 8 ≥        | 6 (0.6%)   |

Table 4: Frequency of the iteration counts of Algorithm 1 until the translation output converged using SMT+Iterative_s2s.

Table 6 shows the average perplexity scores of the results of the SMT and pipeline models. While the perplexities of the pipeline models were much lower than that of SMT, the perplexity of the proposed SMT+Iterative_s2s was not the lowest. This result suggests that word-based perplexity is not suitable for evaluating equally acceptable translation outputs.

6 Discussion

In Table 5, most of the outputs using SMT+2step_s2s and SMT+Iterative_s2s were grammatically acceptable Japanese sentences with slight differences in the post-positional particle selections. As shown in the second and third examples in Table 5, the PPL scores of SMT+2step_s2s were lower than those of SMT+Iterative_s2s, but the BLEU4 and WER scores of SMT+Iterative_s2s were better than that of SMT+2step_s2s, even though the meanings of the sentences were almost the same. By contrast, the sentences of SMT+2step_s2s and SMT+Iterative_s2s in the first and last examples had different meanings, even though the PPL, BLEU4, and WER scores indicated that the results of SMT+Iterative_s2s were better than those of SMT+2step_s2s. However, depending on the context, the results of SMT+2step_s2s may be more appropriate. The main cause of the ambiguity issue is related to the information bottleneck raised by Yin and Read (2020) regarding the gloss notation of sign language. Currently, our parallel corpus does not include any non-manual signals (NMSs), such as facial expression, eye gaze, mouth, and movement of the head and shoulders. However, NMSs act as grammatical markings for syntactic information (Valli et al. 2011; Koizumi et al. 2002). NMSs are not expressed in sequence, but simultaneously with manual signs, and their subtleties make sign recognition and annotation more difficult. Perhaps, this is one of the reasons that most existing sign language corpora do not or only contain partial NMS labels along with glosses. As suggested by Yin and Read (2020), the performance of G2T translation may not impose an upper bound for sign-to-text translation unless the gloss faithfully describes the signed sentences. We are interested in investigating whether incorporating visual features from signs would improve the proposed G2T translation method. Because of the limited space in this paper, we leave this issue for future work.

Table 7 depicts examples of the translation errors by SMT+Iterative_s2s categorized into gloss word translation error, post-positional particle exchange, and conjugation exchange. As shown in Table 3, a large portion of the translation errors originated from gloss word translations. These errors mostly occurred because of the incorrect selection of Japanese wording for gloss phrases. For instance, the phrase 被災地‘disaster area’ in the reference of the 2nd example in Table 7, which is expressed as a sequence of three glosses: 受ける‘receive’, 災害‘disaster’, and 場所‘area’, was translated into the un-grammatical phrase, 受けて 災害場所ukete saigaibasho. It is because the correct mapping from glosses to compound nouns cannot be learned by the phrase-based SMT unless they appear in the training set. The second major source of translation errors was the post-positional particle exchanges. These errors possibly change the semantic from the reference as indicated in the 5th example of Table 7, 図書館に本を寄贈する方法“how to donate books to library” v.s. 図書館の本を贈る方法 “how to give a book from the library”. As we mentioned above, some of these errors are difficult to handle because the system output may be correct in another context. Trans-
Table 5: Sample translation results by naive, G2T, SMT, SMT+1step, SMT+2step, and proposed SMT+Iterative. All the results of SMT+Iterative were when the iterative update converged in the second loop. PPL represents perplexity.

| Input | BLEU4 | WER | PPL |
|-------|-------|-----|-----|
| (1)   |       |     |     |
| Input | g467 g12 g77 |     |     |
| Reference | 我的孩子 |     |     |
| naive | 0.0 0.714 117731.4 |     |     |
| G2T   | 0.474 0.286 119.7 |     |     |
| SMT   | 0.429 0.286 119.7 |     |     |
| SMT+1step | 0.474 0.286 119.7 |     |     |
| SMT+2step | 0.643 0.143 129.6 |     |     |
| (2)   |       |     |     |
| Input | g19 g20 g87 g294 g20 g307 g202 g9 |     |     |
| Reference | 会話費用の自己負担額は安くなりますか？ |     |     |
| naive | 0.0 0.75 56747.3 |     |     |
| G2T   | 0.551 0.25 203.9 |     |     |
| SMT   | 0.531 0.25 203.9 |     |     |
| SMT+1step | 0.551 0.25 203.9 |     |     |
| SMT+2step | 0.417 0.25 107.2 |     |     |
| SMT+Iterative | 0.735 0.083 112.4 |     |     |
| (3)   |       |     |     |
| Input | g73 g475 g52 g19 g27 g151 g2 |     |     |
| Reference | 会話費用の自己負担額は安くなりますか？ |     |     |
| naive | 0.0 1.0 121.4 |     |     |
| G2T   | 1.0 1.0 121.4 |     |     |
| SMT   | 1.0 1.0 121.4 |     |     |
| SMT+1step | 0.525 0.222 768.0 |     |     |
| SMT+2step | 0.658 0.111 62.7 |     |     |
| SMT+Iterative | 0.735 0.083 112.4 |     |     |
| (4)   |       |     |     |
| Input | g258 g660 g24 g83 g34 g9 |     |     |
| Reference | 提供する情報が得られるか？ |     |     |
| naive | 0.0 0.667 4571.7 |     |     |
| G2T   | 0.597 0.111 148.3 |     |     |
| SMT   | 0.661 0.222 320.7 |     |     |
| SMT+1step | 0.597 0.111 148.3 |     |     |
| SMT+2step | 0.661 0.111 199.2 |     |     |

Table 6: Average perplexity of translations using SMT, SMT+1step, SMT+2step, and SMT+Iterative measured by the transformer-based language model trained on the 494M-word Japanese Wikipedia.

| Average perplexity |
|--------------------|
| SMT     | 934.47 |
| SMT+1step | 241.44 |
| SMT+2step | 248.01 |
| SMT+Iterative | 269.92 |

7 Related works

Camgöz et al. (2018) proposed end-to-end sign language translation in the framework of neural machine translation, allowing them to jointly learn the spatial sign representation, underlying language model, and mapping between sign and spoken language using PHOENIX-Weather 2014T (Camgöz et al., 2018) corpus. Their later work (Camgöz et al., 2020) further improved the model by introducing a transformer-based architecture that jointly learns sign language recognition and translation while being trainable in an end-to-end manner using connectionist temporal classification loss to bind the recognition and translation problems into a single unified architecture.

In a similar research line, Yin and Read (2020) proposed the G2T model using a transformer-based seq2seq model, and evaluated the performance on PHOENIX-Weather 2014T (Camgöz et al., 2018) and ASLG-PC12 (Othman and Jemni, 2012) in various ways by changing the numbers of encoder-decoder layers and embedding schemes. All the end-to-end state-of-the-art sign language translation methods rely on large datasets and cannot be used for resource-poor datasets. The
pipeline method that we proposed is related to the transfer learning method proposed by Mocilov et al. (2018). They proposed transfer learning to improve British Sign Language modeling at a gloss level by fine-tuning or layer substitution on neural network models pre-trained on the Penn Treebank dataset. Although the purpose of their work was not to translate sign language, their work is similar to ours in that it takes advantage of linguistic commonality between resource-poor sign language and its spoken language. Our approach to converting non-grammatical sentences into grammatical sentences is related to previous work on grammatical error correction (Imamura et al. 2012; Liu et al. 2018; Oyama et al. 2013). They used insert or replace operations to correct particle or morphological inflection errors in a monolithic model, and we believe that the proposed seq2seq-based iterative method using multiple models can be used for similar tasks.

8 Conclusion

We proposed a pipeline machine translation method from SJ to Japanese by assuming that the gloss of the sign is provided. We focused on grammatical differences between SJ and Japanese, particularly post-positional particles and morphological inflections, and proposed a pipeline model by cascading the phrase-based statistical machine translation and three transformer-based seq2seq models, which effectively addressed the resource-poor issue of the sign language corpus. The statistical machine translation model first maps each gloss phrase to a Japanese phrase, then three seq2seq models pre-trained using the monolingual corpus transform the initial translation by complementing post-positional particles, and apply corrections for verbs, auxiliary verbs, and adjectives. Translation is repeated until the output converges. We confirmed that the proposed method outperformed the SMT baseline by +4.4/+4.9 points for BLEU-3/4.

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Appendix

A Sample translations by SMT+Iterative_s2s

| Pipeline translation from $G$ into $S_{PP+PC}$ |
|------------------------------------------------|
| $G$ g6 g847 g71 g64 g84 g9 |
| $S_{-PP-C}$ 図書館 どこにあるですか？ |
| $S_{PP-C}$ 補聴器の購入の助成をお願いします。 |
| $S_{PP+PC}$ 補聴器の購入の助成をお願いします。 |
| “Where is the library?” |

| $G$ g25 g26 g27 g470 |
| $S_{-PP-C}$ 入院手続きについて教えるください。 |
| $S_{PP-C}$ 入院手続きについて教えるください。 |
| $S_{PP+PC}$ 入院手続きについて教えるください。 |
| “Please subsidize the purchase of hearing aids.” |

| Table 8: Examples of translation results at each pipeline step by SMT+Iterative_s2s. The words in red are the complemented post-positional particles and the words in blue are the conjugated words from the underlined lemmas above. (See the gloss definitions in Table 11.) |

B Hyper-parameters tuning results

| encoder & decoder | s2s_m1 | s2s_m2 | s2s_m3 |
|-------------------|--------|--------|--------|
| embed-dim ffn-embed-dim layers attention-heads | BLEU4 | BLEU4 | BLEU4 |
| 512 2048 6 8 | 74.20 | 98.75 | 75.06 |
| 256 1024 3 4 | 73.99 | 96.84 | 74.88 |
| 128 512 2 2 | 70.75 | 98.26 | 71.58 |
| 64 256 1 1 | 56.33 | 94.84 | 61.70 |

| Table 9: The results of hyperparameter tuning of the seq2seq models (s2s_m1, s2s_m2, and s2s_m3) used in Steps 1, 2, and 4 of Algorithm 1, respectively. The values are BLEU4 scores of the test samples extracted from the parallel corpus. |

C Statistical significance test results

| BLEU3 | BLEU4 |
|-------|-------|
| SMT | SMT+1step_s2s | SMT+2step_s2s | SMT | SMT+1step_s2s | SMT+2step_s2s |
| 1e-10** | 4e-06** | 0.164 | 1e-10** | 0.177 | 0.013* |
| 1e-10** | 0.003** | 0.013* | 1e-10** | 0.018* | 0.049* |

| Table 10: Non-parametric bootstrap test results of BLEU3 and BLEU4 for SMT, SMT+1step_s2s, SMT+2step_s2s, and SMT+Iterative_s2s. The values are the p-values. (**: p-value <0.05, ***: p-value <0.01) |

D Snippets of gloss definitions
| Arabic | English |
|-------|---------|
| g12   | 2032    |
| g151  | 2032    |
| g181  | 2032    |
| g19   | 2032    |
| g2    | 2032    |
| g20   | 2032    |
| g202  | 2032    |
| g24   | 2032    |
| g25   | 2032    |
| g258  | 2032    |
| g26   | 2032    |
| g27   | 2032    |
| g28   | 2032    |
| g294  | 2032    |
| g307  | 2032    |
| g33   | 2032    |

Table 11: Definitions of glosses used in Tables 5 and 8.