Typical local measurements in generalised probabilistic theories: emergence of quantum bipartite correlations

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What singles out quantum mechanics as the fundamental theory of Nature? Here we study local measurements in generalised probabilistic theories (GPTs) and investigate how observational limitations affect the production of correlations. We find that if only a subset of typical local measurements can be made then all the bipartite correlations produced in a GPT can be simulated to a high degree of accuracy by quantum mechanics. Our result makes use of a generalisation of Dvoretzky’s theorem for GPTs. The tripartite correlations can go beyond those exhibited by quantum mechanics, however.

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Introduction.—The continued success of quantum mechanics (QM) strongly implies that it is the fundamental description of Nature. However, it could still be that QM is simply a very good effective theory which breaks down if we are able to perform experiments with sufficiently high energy and precision. In this case QM would need to be replaced by a more general “post-quantum” theory. In particular generalised probabilistic theories (GPTs) have received considerable attention recently, both as a foil to better understand the features of QM, and as a powerful abstract way to reason about correlations and locality. These investigations have lead to many interesting results, including simplified and improved cryptographic schemes and primitives.

If Nature is actually described by a theory other than QM then the natural question arises: why is QM such a good effective theory? A natural answer, which we investigate here, is that experimental imperfections prevent us from observing any post-quantum phenomena.

Suppose that Nature is described by a GPT with a high-dimensional state space and corresponding high-dimensional set of all possible measurements. Observational limitations, such as detector resolution, mean that it is impossible to access most of these theoretically possible measurements. If physically implementable measurements are those chosen from some typical subset (a precise definition is given in the sequel) then we show that the bipartite correlations arising in any experiment can be modelled, to a high degree of precision, by those of QM. Note that the tripartite and multipartite correlations could go beyond those exhibited by QM: a sufficiently refined experiment involving three or more particles could exhibit behavior going beyond that possible within QM.

It is interesting to contrast our setting with that of decoherence, which models the passage from the microscopic to the macroscopic classical world. The crucial difference is that decoherence arises from the correlations developed between a given particle and many other inaccessible particles (in the GPT framework it is rather likely that decoherence will always lead to an effective classical theory). By way of contrast, we consider only a few particles in isolation: roughly speaking, we study the case where only the “local dimensions” are effectively truncated.

Our argument builds on several important prior ideas. The first arises from the search for an axiomatic derivation of QM: it was realised that a reasonable physical theory should allow for the convex combination of different possible measurements, and hence the underlying sets of both states and measurements should be dual convex bodies. These developments have lead to the identification of generalised probabilistic theories as a general framework to study theories of physics going beyond QM.

The second cornerstone of our argument is the concentration of measure phenomenon epitomized by Dvoretzky’s theorem which states, roughly, that a random low-dimensional section of a high-dimensional convex body looks approximately spherical. This powerful result has already found myriad applications in quantum information theory, e.g., in quantum Shannon theory and quantum computational complexity theory. Here we adapt the “tangible” version of Dvoretzky’s theorem for our purposes.

The final idea we exploit is the observation that spherical state spaces can be simulated by sections of quantum mechanical state spaces. As will become evident, our approach owes much to the recent work showing that bipartite correlations may be modelled by QM when the constituents locally obey QM.

Here we exploit these three core ideas to obtain our

Main result. If the local measurements in a GPT are chosen from a typical section of the convex body of all possible measurements then, with a high degree of accu-
racy, they do not yield any post-quantum prediction for the bipartite scenario.

More specifically, we require that the physically implementable measurements are in essence given by the section of the convex body of all measurements with a low-dimensional $O(n)$-typical subspace. This means that the accessible measurements span a subspace and the choice of this subspace is not particular among all other subspaces of the same dimension. This is a core assumption in our argument. Although we restrict our attention here to the case of a $O(n)$-typical subspaces, it is likely that our result extends to a much wider variety of typicality notions.

Our argument then implies that for most measurements given by low-dimensional subspaces the outcomes can be explained using quantum mechanics. Hence we argue that those measurement devices revealing any post-quantum behavior are extremely difficult to build—since the choice of the right subspace requires extreme fine tuning.

**Probabilistic physical theories, ordered vector spaces.** It is useful to formulate GPTs in the mathematical language of ordered vector spaces [22, 23, 24]: we begin with the description of the single-party state space and local measurements. The system is always assumed to be in a state $\omega$, which encodes the probabilities of each outcome of all the possible measurements that may be performed. The set of all possible states, state space, is denoted $\Omega$. Since any probabilistic combination of states is, in principle, preparable, $\Omega$ is a convex set. We always assume that $\Omega$ is represented as a subset of $\mathbb{R}^n$.

A state $\omega \in \Omega$ assigns a probability to each outcome of any possible measurement; a measurement outcome is represented by a map $f : \Omega \rightarrow [0, 1]$. This map respects probabilistic mixtures of states, meaning that $f(\rho \omega_1 + (1 - \rho)\omega_2) = \rho f(\omega_1) + (1 - \rho) f(\omega_2)$. Extending each map linearly allows us to conclude that measurement outcomes are elements of the dual space $V'$ to $\mathbb{R}^n$. Any such $f$ is called an effect. A special effect is the unit effect $e$ defined by $e(\omega) = 1$ for all $\omega \in \Omega$. The unit effect represents a measurement with a single outcome: this is certain to occur regardless of what the state is. Convex combinations of effects are themselves assumed to be legal effects, so the set of effects is a convex subset of the dual vector space $V$. A measurement with $M$ outcomes is then a set of effects $\{f_j\}_{j=1}^M$ summing to the unit effect $e = \sum_{j=1}^M f_j$. This ensures that outcome probabilities of measurements sum to one. It is convenient to introduce the cone generated by the zero effect, the unit effect, and all other effects, i.e., the set $V^+ \equiv \{tf \mid t \geq 0, f \text{ is an effect}\}$.

The triple $(V, V^+, e)$ is known as an ordered unit vector space and encodes all of the theoretically possible local effects of a GPT. Throughout the following we regard $(V, V^+, e)$ as the fundamental defining representation of a GPT with state space as a derived concept (i.e., $\Omega$ is henceforth defined as the set of all positive linear functionals $\omega$ on $V$ such that $e(\omega) = 1$). It is convenient to assume a further property, namely, that the triple $(V, V^+, e)$ is Archimedean. This means that if $te + f \in V^+$ for all $t > 0$, then $f \in V^+$. Such Archimedean ordered unit vector spaces are referred to as AOU spaces in the sequel. The Archimedean axiom is a kind of closure assumption which allows us, for example, to construct the order norm $\|f\|_+ \equiv \inf\{t \mid te + f \in V^+, t \geq 0\}$. All ordered vector spaces can be Archimedeanised [23], and from now on we assume that the effects of a GPT are suitably represented by an AOU space.

An important example of a GPT is that of quantum mechanics itself: an $n$-level quantum system is described by an AOU space where $V \subset M_n(\mathbb{C})$ is the set of $n \times n$ hermitian matrices. The effects are then the matrices $F \in V$ with $0 \leq F \leq 1$ and the unit is $e \equiv 1$. The cone $V^+$ generated by these effects is hence given by the positive semidefinite matrices. One can verify that the triple $(V, V^+, e)$ is Archimedean. State space $\Omega$ is given by $(F \mapsto \text{tr}(\rho F)) / \{\rho \in V^+, \text{tr}(\rho) = 1\}$ and the order norm $\|A\|_+$ is given by the largest singular value of $A$.

**Sections of GPTs.** Here we study the effective theories arising from GPTs when only a subset of the possible effects may be implemented. For this purpose it is useful to introduce the notion of a linear map between AOU spaces: we say that a linear map $\varphi : V \rightarrow W$ between two AOU spaces $(V, V^+, e_V)$ and $(W, W^+, e_W)$ is positive if $\varphi(V^+) \subset W^+$ and $\varphi$ is unital when $\varphi(e_v) = e_W$. Our definition of a section of a GPT/AOU space $W$ is then motivated by the observation that if we can only implement some subset of the effects in $W^+$ then we can implement any convex combination of them. A particular example of such a restriction is the intersection of $W^+$ with some subspace $V \subset W$. Since we can always apply the “do nothing” measurement, we require the subspace $V$ to contain $e_W$. Abstractly, a section of $(W, W^+, e_W)$ is defined to be a positive unital injection $\varphi : V \rightarrow W$ such that $\varphi(V^+) = W^+ \cap \text{im} \varphi$. This last condition has the consequence that the left inverse $\varphi^{-1}$ is also a positive unital linear map.

When restricted to a section of a GPT $(W, W^+, e_W)$ the state space of the section $(V, V^+, e_V)$ is given by a quotient of the state space of $W$, i.e., $\Omega_V = \Omega_W / \sim$, where the equivalence relation is determined by $\omega \sim \sigma$ if $f(\omega) = f(\sigma)$ for all $f \in V$. This quotient is the shadow of the convex body $\Omega_W$ on the subspace $V$.

We now describe the AOU space playing the central role in our argument. This space is given by triple $(\mathbb{R}^{n+1}, C^{n+1}_+(e), (1, 0))$ where $C^{n+1}_+(e)$ denotes the $(n+1)$-dimensional Euclidean cone with length-diameter ratio $C_2$, i.e.,

$$C^{n+1}_+(e) = \{(t, \vec{x}) \in \mathbb{R}_+ \times \mathbb{R}^n \mid t \geq c\|\vec{x}\|_2\},$$

of which $e = (1, 0)$ is the order unit.
It is a nontrivial fact that this space can be embedded into a quantum system, i.e., it is a section of QM. The argument is due to Tsirelson [20] and proceeds as follows. Let \( m = n/2 \) if \( n \) is even and \( m = (n + 1)/2 \) for odd \( n \) and define \( \gamma_1, \ldots, \gamma_{2m} \in M_{2m}(\mathbb{C}) \) via \( \gamma_{2j-1} = \sigma_z^{(j)} \sigma_x^{(j-1)} \sigma_y^{(j)} \) and \( \gamma_{2j} = \sigma_x^{(j)} \sigma_z^{(j-1)} \sigma_y^{(j)} \), where we've employed the standard Pauli matrix notation and juxtaposition indicates an implicit tensor product. Consider the positive unital injection

\[
\varphi: (t, x) \mapsto tI + c \sum_j x_j \gamma_j,
\]

(2)

(The positivity follows from \( 2t \varphi(t, x) = \varphi(t, x)^2 + (t^2 - c^2||x||^2)I \geq 0 \), arising from \( \gamma_j \gamma_k + \gamma_k \gamma_j = 2\delta_{jk}I \). Since \( \varphi \) is an injection, it has a left-inverse \( \varphi': A \mapsto (\text{tr}(A), \text{tr}(A_{\gamma_1}/c))/2^m \),

(3)

which is again positive. (Let \( x_s \equiv \text{tr}(A_{\gamma_s}) \), so that \( \text{tr}(A) - c||x||^2/c_2 \) is \( \text{tr}[A\varphi(1, -(x/||x||^2)/c_2)] \geq 0 \), since both matrices in the trace are already positive.)

**Multiparty systems.**—We now discuss how to form joint systems in the GPT framework. Suppose Alice and Bob are each in possession of a GPT \((V_A, V_A^+, e_A)\) and \((V_B, V_B^+, e_B)\), respectively, which describes the purely local measurements for each party. The GPT is then defined to be the AOU space \((V_A \otimes V_B, V_{A\otimes B}^+, e_A \otimes e_B)\) where, in order to proceed, we must specify how to construct the cone \( V_{A\otimes B}^+ \equiv \{V_{A\otimes B}^+\}_{n\geq0} \). There are an infinite variety of possibilities, however, we may restrict our attention to the following two extremal definitions [20]. The first corresponds to the maximal tensor product \((V_A \otimes_{\max} V_B)^+\) which is defined to be the Archimedeanisation of the cone \((\sum_{j=1}^k f_j \otimes g_j | f_j \in V_A^+, g_j \in V_B^+, k \in \mathbb{N})\) and the second to the minimal tensor product \((V_A \otimes_{\min} V_B)^+ \equiv \{u \in V_A \otimes V_B | (\omega_A \otimes \omega_B)(u) \geq 0, \text{for all } \omega_A \in \Omega_A \text{ and } \omega_B \in \Omega_B\} \). By way of contrast, the quantum product used in the formation of joint systems in quantum mechanics is neither the minimal nor maximal one, but is rather strictly in between: \((V_A \otimes_{\max} V_B)^+ \subset (V_A \otimes_{\min} V_B)^+ \subset (V_A \otimes_{\QQ} V_B)^+\). The quantum mechanical tensor cone \( V_{A\otimes B}^+ \) is given by the set of positive semidefinite operators in \( M_{n_A}(\mathbb{C}) \otimes M_{n_B}(\mathbb{C}) \). The state space \( \Omega_{A\otimes B}^\max \) corresponding to \((V_A \otimes_{\min} V_B)^+ \) is precisely the set of separable states and the state space \( \Omega_{A\otimes B}^\max \) corresponding to \((V_A \otimes_{\max} V_B)^+ \) is given by the set of all positive semidefinite operators \( W \) with \( \text{tr}(W) = 1 \) which satisfy \( \text{tr}(WA \otimes B) \geq 0, \forall A, B \geq 0 \). This set is dual to the set of entanglement witnesses [24] and includes all legal density operators as well as some operators with negative eigenvalues. Even though the state space \( \Omega_{A\otimes B}^\max \) in the case where our local GPTs are QM is strictly larger than quantum mechanical state space, results of [21,22] show that it does not give rise to any bipartite correlations going beyond QM. The following proposition is a slight generalization of this statement, dealing with (local) sections of quantum systems.

**Proposition 1.** Consider two AOU spaces \((V_A, V_A^+, e_A)\) and \((V_B, V_B^+, e_B)\) which are sections of quantum systems with according positive unital injections \( \varphi_A \) and \( \varphi_B \) into an \( n_A \)-level (respectively, \( n_B \)-level) quantum system. Assume, without loss of generality, that \( n_A \leq n_B \). Then for any positive unital bilinear map \( \omega_{AB}: V_A \times V_B \to \mathbb{R} \) there exists a state \( \sigma_{AB} \) of the composite quantum system \( AB \) and a positive unital automorphism \( \psi \) on \( B \) such that \( \omega_{AB}(f, g) = \text{tr}(\sigma_{AB} \varphi_A(f) \otimes (\psi \circ \varphi_B)(g)) \).

Proof. By assumption the map \( \omega_{AB}(M_A, M_B) \to \omega_{AB}(\varphi_A^{-1}(M_A), \varphi_B^{-1}(M_B)) \) is positive and unital on the quantum systems \( A, B \). Hence the statement reduces to the case where \( \varphi_A \) and \( \varphi_B \) are both the identity mapping. A proof for this case was given by Barnum et al. [21].

We stress that the existence of positive unital left inverse maps \( \varphi_A^{-1} \) and \( \varphi_B^{-1} \) is essential for this result to hold. Indeed, in the case of a hypothetical nonlocal box [20], it is impossible to find positive unital maps into quantum such that there left inverse is also positive and hence non-local boxes allow post-quantum behavior. It is also important to note that Prop. 1 does not generalize to more than two parties [22].

**Typical sections, main result.**—Consider an arbitrary pair of \( n \)-dimensional GPTs \( A \) and \( B \) and suppose that we are only able to access a typical section of the set of local effects for \( A \) (respectively, \( B \)). This is modelled by the intersection of \( V_A^\max \) (respectively, \( V_B^\max \)) with a typical \( k \)-dimensional subspace, \( k \ll n \). To do this abstractly we choose a bijection \( T \) between \( V \) and \( \mathbb{R}^n \) and consider a random linear injection \( X: \mathbb{R}^k \to \mathbb{R}^n \) such that the random variable \( X(\bar{x}) \) is distributed according to the uniform measure on the Euclidean \((n-1)\)-sphere of radius \( ||\bar{x}||^2 \). (That is, \( X \) is an \( O(n) \)-random rotation of an embedded fiducial \( k \)-dimensional subspace.) We call

\[
Q(t, \bar{x}) = te + TX(\bar{x})
\]

(4)

a centered random section of \( \mathbb{R}^{k+1} \) into \( V \) and it ensures that every subspace corresponding to a typical choice of measurement settings contains the neutral effect \( e \). Since only convex combinations of \( e \) with \( TX(\mathbb{R}^k) \) are feasible, we now study the cone \( V^+ \cap Q(\mathbb{R}_+, \mathbb{R}^k) \).

The following result captures the concentration of measure phenomenon for our setting.

**Proposition 2.** Let \((V, V^+, e)\) be an \( n \)-dimensional AOU space and \( 0 < \epsilon < 1 \). Then for \( k \leq \Theta(e^2 \log n) \) there exists a \( k+1 \) dimensional centered random section \( Q \) of \( V \), such that, with high probability,

\[
Q(C_{k+1}^+(1+\epsilon)) \subset V^+ \cap Q(\mathbb{R}_+, \mathbb{R}^k) \subset Q(C_{k+1}^+(1-\epsilon)).
\]

(5)
Proof. At the heart of the proof is the following “tangible” version of Dvoretzky’s theorem [14, 17, 29]: If \( \eta : S^{n-1} \to \mathbb{R} \) is a Lipschitz function with constant \( L \) and central value 1 (with respect to the uniform spherical measure on \( S^{n-1} \)), then for every \( \varepsilon > 0 \), if \( E \subset \mathbb{R}^n \) is a random subspace of dimension \( k \leq k_0 = c_0 \varepsilon^2 n/L^2 \), we have that

\[
\text{Prob} \left[ \sup_{S^{n-1} \cap E} |\eta(\vec{x}) - 1| > \varepsilon \right] \leq c_1 e^{-c_2 k_0}, \tag{6}
\]

where \( c_0, c_1, \) and \( c_2 \) are absolute constants.

For our scenario, we use \( \eta(\vec{z}) = \inf \{ t > 0 \mid t e + T \vec{z} \in V^+ \} \) with \( T \) chosen such that \( \eta \) has a mean (which is a particular central value) of 1 on the \((n-1)\)-dimensional Euclidean sphere and that the Lipschitz constant \( L \) of \( \eta \) is bounded via \( L \leq c' \sqrt{n/\log n} \) for some absolute constant \( c' \). This is always possible, as can be seen following the proof of Theorem 4.3 in [29]: First, by a Lemma of Dvoretzky and Rogers [14, Theorem 3.4], the bijection \( T \) can be chosen such that for all canonical vectors \( \vec{e}_k \) with \( k \leq n/2 \) it holds that \( \| T \vec{e}_k \|_2 \geq \| T \|/4 \). Without loss of generality we may assume in addition that \( \eta \) has mean 1. Then, for a vector of normal distributed variables \( \vec{g} \) and due to \( \| T \vec{z} \|_2 = \max \{ \eta(\vec{z}), \eta(-\vec{z}) \} \) and [29, Eqs. (4.14, 4.18)] we find,

\[
2 \sqrt{n} \geq 2E\eta(\vec{g}) \geq E\| T \vec{g} \|_2 \geq E \max_k \| g_k \| \| T \vec{e}_k \|_2 \geq c'' \sqrt{\log(n/2)} \| T \|/4. \tag{7}
\]

On the other hand, \( \eta \) is a sublinear function and thus

\[
|\eta(\vec{z}_1) - \eta(\vec{z}_2)| \leq \max \{ \eta(\vec{z}_1 - \vec{z}_2), \eta(\vec{z}_2 - \vec{z}_1) \} = \| T (\vec{z}_1 - \vec{z}_2) \|_2 \leq \| T \| \| \vec{z}_1 - \vec{z}_2 \|_2, \tag{8}
\]

which eventually shows \( L \leq c' \sqrt{n/\log n} \).

Now, by virtue of Dvoretzky’s theorem, the following holds with high probability. For all \( \vec{x} \neq 0 \) with \( \xi \equiv \| \vec{x} \|_2 \leq 1/(1 + \varepsilon) \), we have \( \eta[X(\vec{x}/\xi)] \leq 1 + \varepsilon \leq 1/\xi \), and hence \( Q(1, \vec{x}/\xi) = |e/\xi + T X(\vec{x}/\xi)| \xi \in V^+ \). Conversely, for all \( \vec{x} \) with \( \xi = \| \vec{x} \|_2 > 1/(1 - \varepsilon) \), we have \( \eta[X(\vec{x}/\xi)] \geq 1 - \varepsilon > 1/\xi \), i.e., \( Q(1, \vec{x}) \notin V^+ \). The converse statement completes the proof. \( \square \)

Thus, with high accuracy, the effective theory corresponding to a low-dimensional \( O(n) \)-typical section of a local GPT looks like a Euclidean AOU space, cf. Fig. 1 for an illustration. The cones \( Q(C^+_{n+1}(1 \pm \varepsilon)) \) give a very accurate description of the typical section, since by linearity all observable probabilities may at most deviate by \( \mathcal{O}(\varepsilon) \). Combining this with our previous finding, namely that Euclidean cones are sections of QM, and hence, in view of Proposition 1 all bipartite correlations of their maximal tensor product may be simulated within QM, we arrive at our anticipated main result. Conversely, due to an argument by Tsirelson [20], all bipartite dichotomic correlations can be explained within an Euclidean cone of appropriate dimension. Our result reduces to this dichotomic case, since already our description of a GPT by an AOU space is essentially limited to the dichotomic case.

Finally we briefly discuss the situation of a generalized Popescu-Rohrlich (PR) box, which exhibits (in some sense) the “maximal” possible post-quantum correlations [28]. Such boxes are locally described by an AOU vector space over \( \mathbb{R}^n \) with cone \( \mathbb{R}^+ = \{ (t, \vec{x}) \mid t \geq \sum_i |x_i| \} \) and neutral element \((1, \vec{0})\). By virtue of Proposition 2 the fraction of 3-dimensional sections from a \( 55 \times 10^9 \) dimensional box with a post-quantum behavior of more than \( 3\% \) is as low as \( 10^{-6} \) [30].

**Conclusions.**—We have presented a mechanism whereby observable bipartite correlations of an arbitrary post-quantum theory could be, with high accuracy, compatible with those exhibited by quantum mechanisms. Our argument exploited the concentration of measure phenomenon and hence works for any typical low-dimensional section of a generalised probabilistic theory. We argued that such typical sections arise due to a lack of ultra-precise experimental control, in which case it would be virtually impossible to observe any post-quantum behavior, even if the fundamental theory of Nature wasn’t quantum mechanics. This is complementary to the emergence of classicality from quantum mechanics via decoherence [3], since we consider only a pair of (microscopic) objects, rather than an ensemble of objects. Our argument indicates that there is another option for a refinement of today’s physics: we might be missing hidden post-quantum structures due to an ignorance of the correct measurement directions.

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Those estimates stem from estimating the constants $c_0$, $c_1$, and $c_2$ in the original proofs. Numerically estimations yield much better bounds and the dimension can be estimated to be $\approx 2000$. 

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