Residue Integrals and Waring’s Formulas for a Class of Systems of Transcendental Equations in $\mathbb{C}^n$

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Abstract

The present article is focused on the study of a special class of systems of nonlinear transcendental equations for which classical algebraic and symbolic methods are inapplicable. For the purpose of the study of such systems, we develop a method for computing residue integrals with integration over certain cycles. We describe conditions under which the mentioned residue integrals coincide with power sums of the inverses to the roots of a system of equations (i.e., multidimensional Waring’s formulas). As an application of the suggested method, we consider a problem of finding sums of multi-variable number series.

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1 Introduction

The problem of elimination of unknowns from systems of nonlinear algebraic equations is a classical algebraic problem. Its solution based on the notion of resultant was developed in works of Silvester and Bézout. This method was described in detail in the classical Van der Waerden’s monograph \cite{25}. In the middle of the 20th century, B. Buchberger suggested a new elimination method based on the notion of a Gröbner basis. Nowadays it is one of the main elimination methods in polynomial computer algebra (see, e.g., \cite{1,4}).

In the 1970s in \cite{2} L. A. Aizenberg proposed a new elimination method based on the multidimensional residue theory, namely on the formulas of multidimensional logarithmic residue and Grothendieck residue. The basic idea of the method was to find certain residue integrals connected to the power sums of roots of a given system of equations without finding the roots

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themselves. (The formulas for computing power sums may vary depending on the given system of equations.) Then, using the classical recurrent Newton formulas, one can construct a polynomial whose roots coincide with the first coordinates of the roots of the given system with the same multiplicity (i.e., resultant). This method does not increase the multiplicity of roots in comparison with the classical method (see, e.g., [25]). Its further developments were implemented in [3], [24], and [5].

In applied problems of chemical kinetics systems of transcendental equations, namely, systems consisting of exponential polynomials [6,8] (Zeldovich–Semenov model, etc.) arise as well. However, the elimination method developed in [3,5,24] cannot be applied to this kind of systems. One of the obstacles is the fact that the set of roots of a system of transcendental equations in \( n \) variables is, in general, infinite. Moreover, multi-Newton sums (with powers in \( \mathbb{N}^n \)) of the roots of such systems lead usually to divergent series. At the same time, the multidimensional logarithmic residue and Grothendieck residue formulas are not applicable to the residue integrals that arise in such kind of systems which means that one is unable to calculate power sums of the roots. Therefore, the known methods have to be modified significantly in order to be applied to such systems. In particular, one has to be able to compute power sums of the inverses to the roots (without finding the roots themselves). Then, using the obtained formulas together with analogs of recurrent Newton formulas and Waring’s formulas for entire functions of a complex variable (see [5, Ch. 1]), one can construct resultant, which is also an entire function. But nevertheless, the formulas for finding power sums are still the main component of the method.

Classical Waring’s formulas express power sums of the roots of a polynomial in terms of its coefficients (see, e.g., [25]). Multidimensional analogs of Waring’s formulas for certain types of algebraic systems were developed in [10].

In the works [7,11,13–18] simple enough classes of systems of equations containing entire or meromorphic functions were considered. An algorithm that computes the residue integrals and applies to them the recurrent Newton formulas was given in [12]. In [9] the developed methods were applied to study of a system (consisting of exponential polynomials) that arises in Zeldovich–Semenov model.

We now present a more precise review of the known results. In [18] the authors considered the system of functions:

\[
f_1(z), \ldots, f_n(z),
\]

where \( z = (z_1, \ldots, z_n) \). Each \( f_j(z) \) is analytic in the neighborhood of \( 0 \in \mathbb{C}^n \) and is defined by

\[
f_j(z) = z^\beta_j + Q_j(z), \quad j = 1, \ldots, n,
\]

where \( \beta_j = (\beta^1_j, \ldots, \beta^n_j) \) is a multi-index with integer nonnegative coordinates, \( z^\beta_j = z_1^{\beta^1_j} \cdots z_n^{\beta^j_n} \), and \( \|\beta\| = \beta^1_1 + \ldots + \beta^j_n = k_j, \quad j = 1, \ldots, n \). Functions \( Q_j \) are expanded in a neighborhood of origin into an absolutely and uniformly converging Taylor series of the form

\[
Q_j(z) = \sum_{\|\alpha\| > k_j} a^j_\alpha z^\alpha,
\]

where \( \alpha = (\alpha_1, \ldots, \alpha_n), \alpha_j \geq 0, \alpha_j \in \mathbb{Z}, \) and \( z^\alpha = z_1^{\alpha_1} \cdots z_n^{\alpha_n} \).

The formulas for computing residue integrals

\[
J_\beta = \frac{1}{(2\pi i)^n} \int_{\gamma(r)} \frac{1}{z^{\beta+U}} \cdot \frac{df}{f}
\]

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in terms of the coefficients of \( Q_j(z) \) were obtained. Here \( \gamma(r) = \{ z = (z_1, \ldots, z_n) : |z_j| = r_j, \ j = 1, \ldots, n \} \) and \( U = (1, \ldots, 1) \) is the unit vector.

Multidimensional Newton formulas for such systems were obtained in [11] and [12].

A class of systems containing the functions

\[
f_j(z) = (z^{\beta_j} + Q_j(z))e^{P_j}, \quad j = 1, \ldots, n. \tag{1}
\]

was considered in [15] and [13]. A method for finding residue integrals for such systems was given in [13].

In the present work we compute residue integrals for a specific kind of systems of \( n \) transcendental equations, and deduce from this computation (provided such series converge) the values of the sums of series (with powers in \((-N)^n\)) consisting of the roots of such systems which do not belong to coordinate subspaces. In other words, we generalize the statements from [7, 11, 13, 15, 18] to a wider class of systems of transcendental equations, where instead of the monomials \( z^{\beta_j} \) in (1) we consider products of linear functions. Our objectives are to obtain formulas for computing residue integrals, to study the connection between residue integrals and power sums of the inverses to the roots (Waring’s formulas), and to introduce a scheme for elimination of unknowns from the considered class of systems.

## 2 Calculation of residue integrals

In this section, we introduce the class of systems of transcendental equations that will be considered in this work. A. Tsikh considered its algebraic analog in [23] (see also [5, Theorems 8.5, 8.6]) and studied the number of its common roots in \( \mathbb{C}^n \). Theorem 2 shows that for any such system the residue integral \( J_\gamma(t) \) (where \( t > 0 \) is sufficiently small) can be computed by means of converging series of Taylor coefficients of the functions contained in the initial system.

For \( z = (z_1, \ldots, z_n) \in \mathbb{C}^n \) consider a system of functions

\[
\begin{cases}
f_1(z) = q_1(z) + Q_1(z), \\
\vdots \\
f_n(z) = q_n(z) + Q_n(z),
\end{cases} \tag{2}
\]

where \( Q_i(z) \) are entire functions and

\[
q_i(z_1, \ldots, z_n) = (1 - a_{i1}z_1)^{m_{i1}} \cdots (1 - a_{in}z_n)^{m_{in}} \tag{3}
\]

for \( i = 1, \ldots, n \). Here \( m_{ij} \) are positive integers and \( a_{ij} \) are complex numbers, such that \( a_{ij} \neq a_{kj}, \ i \neq k \).

Let \( J = (j_1, \ldots, j_n) \) be a multi-index where \( (j_1, \ldots, j_n) \) is a permutation of \( (1 \ldots n) \). Then by \( a_J \) we denote the vector \((a_{i_1 j_1}, \ldots, a_{i_n j_n})\). For each \( i \) we define a function

\[
h_i(z) = \begin{cases} q_i(z), & \text{if } a_{ij} \neq 0 \text{ for each } j; \\
q_i(z) \cdot \frac{1}{z_{j_1}} \cdots \frac{1}{z_{j_k}}, & \text{if } a_{ij_1} = \ldots = a_{ij_k} = 0.
\end{cases}
\]

The system

\[
h_i(z) = 0, \quad i = 1, \ldots, n \tag{4}
\]
has \( n! \) isolated roots in \( \overline{\mathbb{C}}^n \), where \( \overline{\mathbb{C}}^n = \mathbb{C} \times \cdots \times \mathbb{C} \). Since \( \overline{\mathbb{C}} \) is a compactification of the complex plane \( \mathbb{C} \), then \( \overline{\mathbb{C}}^n \) is one of the known compactifications of \( \mathbb{C}^n \). The roots of (4) are

\[
\bar{a}_j = \begin{cases} 
(1/a_{1j}, \ldots, 1/a_{nj}), & \text{if } a_{kj} \neq 0 \text{ for each } k = 1, \ldots, n, \\
(1/a_{1j}, \ldots, \infty_{[i]}, \ldots, \infty_{[i]}, \ldots, 1/a_{nj}), & \text{if } a_{i1j_1} = \ldots = a_{ikj_k} = 0,
\end{cases}
\]

where \( k, j = 1, \ldots, n \), and \( J = (j_1, \ldots, j_n) \). Note that we write \( \infty \) (as a point in \( \overline{\mathbb{C}} \)) in \( \bar{a}_j \) whenever \( a_{kj} = 0 \).

By \( \Gamma_h \) we denote the cycle

\[
\Gamma_h = \{ z \in \mathbb{C}^n : |h_i(z)| = r_i, \ r_i > 0, \ i = 1, \ldots, n \}.
\]

Now we define the cycle \( \Gamma_{h, \bar{a}_j} \) by

\[
\begin{cases} 
|l_1| = r_1, \\
\vdots \\
|l_n| = r_n,
\end{cases}
\quad \text{where} \quad \begin{cases} 
l_k = 1 - a_{kj}z_k, & \text{if } a_{kj} \neq 0, \\
l_k = 1/z_k, & \text{if } a_{kj} = 0.
\end{cases}
\]

**Lemma 1.** For sufficiently small \( r_i \), a global cycle \( \Gamma_h \) defined by (5) has connected components (local cycles) in the neighborhoods of the roots \( a_j \). Moreover, \( \Gamma_h \) is homologous to the sum of the local cycles \( \Gamma_{h, \bar{a}_j} \).

**Proof.** Consider the global cycle \( \Gamma_h \) defined by

\[
\begin{cases} 
|h_1| = r_1, \\
\vdots \\
|h_n| = r_n.
\end{cases}
\]

If \( a_{kj} \neq 0 \) for any \( k = 1, \ldots, n \) in a neighborhood of \( a_j \), then \( \Gamma_h \) is homotopic to the cycle \( \Gamma_{q, \bar{a}_j} \) defined by (6) with the homotopy defined by

\[
\begin{cases} 
|1 - ta_{1n}z_{1n}|^{m_{11}} \cdots |1 - a_{1j}z_{1j}|^{m_{1j}} \cdots |1 - ta_{1n}z_{1n}|^{m_{1n}} = r_1, \\
\vdots \\
|1 - ta_{n1}z_{n1}|^{m_{n1}} \cdots |1 - a_{nj}z_{nj}|^{m_{nj}} \cdots |1 - ta_{nn}z_{nn}|^{m_{nn}} = r_n,
\end{cases}
\]

where \( t \in [0, 1] \). For \( t = 1 \) we obtain \( \Gamma_h \), and for \( t = 0 \) we obtain \( \Gamma_{h, \bar{a}_j} \).

Now we consider \( \Gamma_h \) in the neighborhood of \( a_j \) where \( a_{i1j_1} = \ldots = a_{ikj_k} = 0 \). Then in such neighborhood \( \Gamma_h \) is homotopic to the cycle \( \Gamma_{h, \bar{a}_j} \) defined by (6), and the homotopy is defined similarly to (7) where for each \( a_{ikj_k} = 0 \) the corresponding term \( 1 - a_{ikj_k}z_{jk} \) is replaced with \( 1/z_{jk} \). \( \Box \)

For

\[
F_i(z, t) = q_i(z) + t \cdot Q_i(z), \quad i = 1, \ldots, n
\]

consider the system of equations \( F_i(z, t) = 0 \) which depends on a real parameter \( t \geq 0 \).

Let \( r_1 > 0, \ldots, r_n > 0 \) be fixed real numbers. Compactness of the cycles \( \Gamma_h \) defined by (5) yields the fact that for sufficiently small \( t > 0 \), the inequalities

\[
|q_i(z)| > |t \cdot Q_i(z)|, \quad i = 1, \ldots, n
\]
hold on $\Gamma_h$. 

By $J_{\gamma}(t)$ we denote the integral 

$$J_{\gamma}(t) = \frac{1}{(2\pi \sqrt{-1})^n} \int_{\Gamma_h} \frac{1}{z^{\gamma + I}} \cdot dF = \frac{1}{(2\pi \sqrt{-1})^n} \int_{\Gamma_h} \frac{1}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{dF_1}{F_1} \wedge \cdots \wedge \frac{dF_n}{F_n}, \quad (9)$$

where $\gamma = (\gamma_1, \ldots, \gamma_n)$ is a multi-index and $I = (1, \ldots, 1)$. This integral we call the residue integral in accordance with the paper [21].

In order to formulate the theorem below, we introduce the following notations which we will also use in further statements.

Denote by $\Delta = \Delta(t)$ the Jacobian of the system $F_1(z,t), \ldots, F_n(z,t)$ with respect to $z_1, \ldots, z_n$. Let $(-1)^s(J)$ be the sign of the permutation $J$, and $\alpha = (\alpha_1, \ldots, \alpha_n)$ be a multi-index of length $n$. By $q^{\alpha+I}(J)$ we denote $q_1^{\alpha_1+1}[j_1] \cdots q_n^{\alpha_n+1}[j_n]$, where $q_s[j_s]$ is a product of all $(1-a_j z_1)^{m_{1j_1}} \cdots (1-a_j z_n)^{m_{nj_j}}$ except $(1-a_{sj_s} z_s)^{m_{sj_s}}$. By $\beta(\alpha, J)$ we denote the vector 

$$\beta(\alpha, J) = (m_{1j_1}(\alpha_{j_1} + 1) - 1, \ldots, m_{nj_n}(\alpha_{j_n} + 1) - 1),$$

and 

$$\beta(\alpha, J)! = \prod_p \left( m_{pjp}(\alpha_{jp} + 1) - 1 \right)!$$

Finally, $a^{\gamma+I}_J$ denotes $a^{m_{1j_1}(\alpha_{j_1}+1)}_1 \cdots a^{m_{nj_n}(\alpha_{j_n}+1)}_n$, and 

$$\frac{\partial ||\beta(\alpha,J)||}{\partial z^{\beta(\alpha,J)}} = \frac{\partial^{m_{1j_1}(\alpha_{j_1}+1) + \cdots + m_{nj_n}(\alpha_{j_n}+1) - 1}}{\partial z_1^{m_{1j_1}(\alpha_{j_1}+1) - 1} \cdots \partial z_n^{m_{nj_n}(\alpha_{j_n}+1) - 1}}.$$

**Theorem 2.** Under the assumptions made for the functions $F_i$ defined by (8), the following formulas for $J_{\gamma}(t)$ as convergent (for sufficiently small $t$) series are valid:

$$J_{\gamma}(t) = \sum' \sum_{\alpha} (-t)^{||\alpha|| + ||\beta(\alpha,J)|| + n} \frac{(-1)^s(J)}{\beta(\alpha, J)! \cdot a^{\gamma+I}_J} \cdot \left[ \frac{\Delta(t)}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{Q^n}{q^{\alpha+I}(J)} \right]_{z = a_J},$$

where $\sum'$ means that the summation is performed over such all multi-indices $J$ such that $a_J$ have no zero components.

**Proof.** We have 

$$J_{\gamma}(t) = \frac{1}{(2\pi \sqrt{-1})^n} \int_{\Gamma_h} \frac{1}{z^{\gamma + I}} \cdot dF = \frac{1}{(2\pi \sqrt{-1})^n} \int_{\Gamma_h} \frac{1}{z_1^{\gamma_1+1} \cdots z_n^{\gamma_n+1}} \cdot \frac{dF_1}{F_1} \wedge \cdots \wedge \frac{dF_n}{F_n} \wedge \frac{\Delta dz}{F},$$
where $dz = dz_1 \wedge \ldots \wedge dz_n$, and $F = F_1 \cdot \ldots \cdot F_n$.

Applying a formula for the sum of a geometric sequence, we get

$$
\frac{1}{(2\pi \sqrt{-1})^n} \int_{\Gamma_h} \frac{1}{z_{\gamma_1+1} \ldots z_{\gamma_n+1}} \cdot \Delta dz
= \frac{1}{(2\pi \sqrt{-1})^n} \sum_{\|\alpha\| > 0} (-t)^{\|\alpha\|} \int_{\Gamma_h} \frac{\Delta(t)}{z_{\gamma_1+1} \ldots z_{\gamma_n+1}} \cdot \frac{Q_{\alpha_1} \ldots Q_{\alpha_n}}{q_{\alpha_1+1} \ldots q_{\alpha_n+1}} dz
= \frac{1}{(2\pi \sqrt{-1})^n} \sum_{J} (-t)^{s(J)} \sum_{\|\alpha\| > 0} (-t)^{\|\alpha\|} \times
\int_{\Gamma_h,J} \frac{\Delta(t)}{z_{\gamma_1+1} \ldots z_{\gamma_n+1}} \cdot \frac{Q^{\alpha}}{q_{\alpha_1+1} \ldots q_{\alpha_n+1}} dz
$$

and finally we obtain that $J_{\gamma}(t)$ is equal to

$$
\sum_{J} (-t)^{s(J)} \sum_{\|\alpha\| \leq \beta + n} \frac{(-1)^{s(J)}}{\beta(\alpha, J)! \cdot a_{\beta,J}} \cdot \partial^{\|\beta(\alpha, J)\|} \frac{\Delta(t)}{z_{\gamma_1+1} \ldots z_{\gamma_n+1}} \cdot \frac{Q^{\alpha}}{q_{\alpha_1+1} \ldots q_{\alpha_n+1}} \bigg|_{z=\bar{a}_J}.
$$

The resulting series converges for sufficiently small $t$.

3 Residue integrals and Waring’s formulas for algebraic systems

In this section we establish a correspondence between the residue integrals and the power sums of the inverses to the roots (Waring’s formulas). First we shrink the class of systems for which the sums in Theorem 2 are finite. Then, applying transformation $t = \frac{1}{w_j}$, $j = 1, \ldots, n$, and Lemma 4 by A. Tsikh we rewrite the residue integrals $J_{\gamma}(t)$ in new variables $w$ (Lemma 3). Further, Lemma 5 shows that $J_{\gamma}(t)$ can be expressed by a finite number of Taylor coefficients of the considered functions. Theorem 7 shows (by means of Lemma 6) that the residue integral $J_{\gamma}(t)$ equals (up to a sign) to the power sums of the inverses to the roots. The main result of the paper, Theorem 8, shows that the statement of Theorem 7 is true not only for sufficiently small $t > 0$ but also for $t = 1$ (Note that Theorems 8 and 9 allow one find power sums of the inverses to the roots of the systems without finding the roots.) As a conclusion of the section we present elimination method for the considered systems.

Suppose $Q_i(z)$ are the polynomials:

$$
Q_i(z) = z_1 \cdot \ldots \cdot z_n \sum_{\|\alpha\| \geq 0} C^{i,\alpha} z^{\alpha} \quad i = 1, \ldots, n,
$$

(10)
where $\alpha$ is a multi-index, $z^\alpha = z_1^\alpha \cdots z_n^\alpha$, and $\deg_z Q_i \leq m_{ij}$, $i, j = 1, \ldots, n$ for all non-zero $a_{ij}$. If $a_{ij} = 0$ then no restriction on $\deg_z Q_i$ is needed.

Assuming that all $w_j \neq 0$, we substitute $z_j = \frac{1}{w_j}, j = 1, \ldots, n$ in the functions

$$F_i(z, t) = (q_i(z) + t \cdot Q_i(z)), \quad i = 1, \ldots, n.$$ 

Consequently, for $i = 1, \ldots, n$, we get

$$F_i\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}, t\right) = q_i\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right) + t \cdot Q_i\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right)$$

$$= \left(1 - a_{i1} \frac{1}{w_1}\right)^{m_{i1}} \cdots \left(1 - a_{in} \frac{1}{w_n}\right)^{m_{in}} + t \cdot Q_i\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right)$$

$$= \left(\frac{1}{w_1}\right)^{m_{i1}} \cdots \left(\frac{1}{w_n}\right)^{m_{in}} \cdot \left(w_1 - a_{i1}\right)^{m_{i1}} \cdots \left(w_n - a_{in}\right)^{m_{in}} + t \cdot Q_i\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right).$$

And finally we arrive at

$$F_i\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}, t\right) = \left(\frac{1}{w_1}\right)^{m_{i1}} \cdots \left(\frac{1}{w_n}\right)^{m_{in}} \cdot \left(q_i(w) + t \cdot \tilde{Q}_i(w)\right), \quad (11)$$

where $\tilde{q}_i$ are the functions

$$\tilde{q}_i = (w_1 - a_{i1})^{m_{i1}} \cdots (w_n - a_{in})^{m_{in}},$$

and $\tilde{Q}_i$ are the polynomials

$$\tilde{Q}_i = w_1^{m_{i1}} \cdots w_n^{m_{in}} \cdot Q_i\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right).$$

From (10) we obtain

$$\deg_w \tilde{Q}_i < m_{ij}, \quad i, j = 1, \ldots, n.$$ 

Note that in the above calculations it is not important whether $a_{ij}$ vanish or not. Indeed, suppose that in $F_i(z, t) = q_i(z) + t \cdot Q_i(z), i = 1, \ldots, n$, some $a_{ij} = 0$. If, for instance, $a_{11} = 0$, then after the substitution $z_j = \frac{1}{w_j}, j = 1, \ldots, n$, the function $F_1$ takes the form

$$F_1\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}, t\right) = q_1\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right) + t \cdot Q_1\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right),$$

where

$$q_1\left(\frac{1}{w_1}, \ldots, \frac{1}{w_n}\right) = \left(1 - a_{12} \frac{1}{w_2}\right)^{m_{12}} \cdots \left(1 - a_{1n} \frac{1}{w_n}\right)^{m_{1n}}$$

$$= \left(\frac{1}{w_1}\right)^{\deg_w Q_1} \cdot \left(\frac{1}{w_2}\right)^{m_{12}} \cdots \left(\frac{1}{w_n}\right)^{m_{1n}} \times w_1^{\deg_w Q_1} \cdot (w_2 - a_{12})^{m_{12}} \cdots (w_n - a_{1n})^{m_{1n}}.$$
Consequently
\[ F_1 \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n}, t \right) = \left( \frac{1}{w_1} \right)^{\deg w_1 Q_1} \cdots \left( \frac{1}{w_n} \right)^{m_{1n}} \left( \tilde{q}_1(w) + t \cdot \tilde{Q}_1(w) \right), \]
where
\[ \tilde{q}_1 = (w_1)^{\deg w_1 Q_1} (w_2 - a_{12})^{m_{12}} \cdots (w_n - a_{1n})^{m_{1n}}, \]
and
\[ \tilde{Q}_1 = w_1^{\deg w_1 Q_1} w_2^{m_{12}} \cdots w_n^{m_{1n}} Q_1 \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n} \right). \]
I.e., we can take \( m_{11} = \deg w_1 Q_1 \). From (10) we derive that
\[ \deg w_j \tilde{Q}_1 < m_{1j}, \quad j = 1, \ldots, n. \]

Denote
\[ \tilde{F}_i = \tilde{F}_i(w, t) = \tilde{q}_i(w) + t \cdot \tilde{Q}_i(w), \quad i = 1, \ldots, n. \quad (12) \]

When \( 0 \leq t \leq 1 \), the system (12) has finite number of zeros in \( \mathbb{C}^n \) which depend on \( t \). Moreover, (12) does not have infinite roots in \( \mathbb{C}^n \) (see [23] and [5, Theorems 8.5, 8.6]). As it was shown in [23] (see also [5, Theorem 8.5]) the number of zeros (counting multiplicities) is equal to the permanent of the matrix \( (m_{ij})_{1 \leq i, j \leq n} \).

Consider the cycle
\[ \tilde{\Gamma}_h = \left\{ w \in \mathbb{C}^n : \left| h_i \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n} \right) \right| = \varepsilon_i, \quad i = 1, \ldots, n \right\} \]
for small enough \( t \).

Compactness of the cycle \( \tilde{\Gamma}_h \) implies that
\[ \left| q_i \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n} \right) \right| > t \cdot \left| Q_i \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n} \right) \right|, \quad i = 1, \ldots, n. \]

Therefore, \( \tilde{\Gamma}_h \) is homologous to the sum of the cycles \( \tilde{\Gamma}_{h, \tilde{a}_j} \)
\[ \left\{ \begin{array}{l}
\left| 1 - a_{1i_1} \frac{1}{w_1} \right| = \varepsilon_1,
\vdots
\left| 1 - a_{ni_n} \frac{1}{w_n} \right| = \varepsilon_n,
\end{array} \right. \]
obtained from the cycles \( \Gamma_{h, \tilde{a}_j} \) by the substitution \( z_j = \frac{1}{w_j} \).

The equation
\[ \left| 1 - a_{ji} \frac{1}{w_j} \right| = \varepsilon \]
defines a circle. Indeed, let us first rewrite it in the form
\[ |w_j - a_{ji}| = \varepsilon |w_j| \quad \text{or} \quad |w_j - a_{ji}|^2 = \varepsilon^2 |w_j|^2. \]
Thus
\[ (1 - \varepsilon^2) \left| w_j - \frac{a_{ji}}{1 - \varepsilon^2} \right|^2 = \frac{\varepsilon^2 |a_{ji}|^2}{(1 - \varepsilon^2)}, \]
or

\[ \left| w_j - \frac{a_{jjj}}{1 - \varepsilon^2} \right|^2 = \frac{\varepsilon^2 \cdot |a_{jjj}|^2}{(1 - \varepsilon^2)^2}, \quad j = 1, \ldots, n. \]

For sufficiently small \( \varepsilon \) the point \( a_{jjj} \) lies inside this circle, and, therefore, \( \tilde{\Gamma}_{h, a_j} \) is homologous to the cycle \( \tilde{\Gamma}_{h, a_j} \):

\[
\begin{align*}
|w_1 - a_{1j}| &= \varepsilon_1, \\
& \quad \ldots \\
|w_n - a_{nj}| &= \varepsilon_n.
\end{align*}
\]

Here \( a_{kk} \) can vanish for some \( k \).

**Lemma 3.** The following formula holds for the residue integral (9):

\[
J_{\gamma}(t) = \frac{(-1)^n}{(2\pi\sqrt{-1})^n} \int_{\tilde{\Gamma}_h} w_1^{\gamma_1 + 1} \cdots w_n^{\gamma_n + 1} \cdot \frac{dF_1}{F_1} \wedge \ldots \wedge \frac{dF_n}{F_n}.
\]

**Proof.** The equality (11) yields

\[
F_j \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n}, t \right) = \left( \frac{1}{w_1} \right)^{m_1} \cdots \left( \frac{1}{w_n} \right)^{m_n} \cdot \tilde{F}_j(w, t), \quad j = 1, \ldots, n.
\]

Then

\[
\frac{dF_j \left( \frac{1}{w_1}, \frac{1}{w_2}, \ldots, \frac{1}{w_n}, t \right)}{F_j \left( \frac{1}{w_1}, \frac{1}{w_2}, \ldots, \frac{1}{w_n}, t \right)} = \frac{d\tilde{F}_j(w, t)}{\tilde{F}_j(w, t)} - \sum_{k=1}^n m_{jk} \cdot \frac{dw_k}{w_k}.
\]

Using (11) and taking into account the change of orientation of the space after replacing \( z_j = 1/w_j, \quad j = 1, \ldots, n \), one can rewrite the integral \( J_{\gamma}(t) \) as

\[
J_{\gamma}(t) = \frac{(-1)^n}{(2\pi\sqrt{-1})^n} \int_{\tilde{\Gamma}_h} \frac{dF \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n}, t \right)}{F \left( \frac{1}{w_1}, \ldots, \frac{1}{w_n}, t \right)}
= \frac{(-1)^n}{(2\pi\sqrt{-1})^n} \int_{\tilde{\Gamma}_h} w_1^{\gamma_1 + 1} \cdots w_n^{\gamma_n + 1} \cdot \frac{dF_1}{F_1} \wedge \ldots \wedge \frac{dF_n}{F_n}
= \frac{(-1)^n}{(2\pi\sqrt{-1})^n} \int_{\tilde{\Gamma}_h} w_1^{\gamma_1 + 1} \cdots w_n^{\gamma_n + 1} \left( \frac{d\tilde{F}_1(w)}{\tilde{F}_1(w)} - \sum_{k=1}^n m_{1k} \cdot \frac{dw_k}{w_k} \right) \wedge \ldots \wedge \left( \frac{d\tilde{F}_n(w)}{\tilde{F}_n(w)} - \sum_{k=1}^n m_{nk} \cdot \frac{dw_k}{w_k} \right).
\]

All the integrals

\[
\int_{\tilde{\Gamma}_h} w_1^{\gamma_1 + 1} \frac{d\tilde{F}_1(w)}{\tilde{F}_1(w)} \wedge \ldots \wedge \frac{d\tilde{F}_n(w)}{\tilde{F}_n(w)} \frac{dw_{j_1}}{w_{j_1}} \wedge \ldots \wedge \frac{dw_{j_{n-l}}}{w_{j_{n-l}}}
\]

vanish when \( 0 \leq l < n \) and \( \varepsilon_j \) are large enough.

Indeed, when \( \varepsilon_j, \quad j = 1, \ldots, n \) are sufficiently large, the inequalities

\[
|\tilde{Q}_j| > |t \cdot \tilde{Q}_j(w)|
\]

\[9\]
hold on $\Gamma_h$. Therefore
\[
\frac{1}{F_j(w)} = \sum_{p=0}^{\infty} (-1)^p t^p \tilde{Q_j^p}(w).
\] (14)

Consequently, the integrals (13) are absolutely convergent series of integrals
\[
\int_{\Gamma_h} w^\gamma_i \frac{w^\alpha dw_1 \wedge \ldots \wedge dw_n}{\tilde{q}_1^{(p_1+1)} \ldots \tilde{q}_n^{(p_n+1)} \cdot w_{j_1} \ldots w_{j_{n-1}}}. 
\]

Stokes’ theorem and the fact that all the integrands are holomorphic imply vanishing of all these integrals.

Finally, we arrive at
\[
J_{\gamma}(t) = \frac{(-1)^n}{(2\pi i)^n} \int_{\Gamma_h} w_1^{\gamma_1+1} \ldots w_n^{\gamma_n+1} \cdot \frac{d\tilde{F}_1}{F_1} \wedge \ldots \wedge \frac{d\tilde{F}_n}{F_n} 
\]

Now we state result from [23] that we will need for further discussion.

Consider a system of algebraic equations in $\mathbb{C}^n$:
\[
f_i(z) = 0, \quad i = 1, \ldots, n. \tag{15}
\]

Suppose (15) has finite number of roots in $\mathbb{C}^n$ and does not have infinite roots in $\mathbb{C}^n$.

Denote $m_{ij} = \deg_z f_i$. When $r_1, \ldots, r_n$ are sufficiently small, the cycle
\[
\Gamma = \{ z \in \mathbb{C}^n : |f_1(z)| = r_1, \ldots, |f_n(z)| = r_n \}
\]
is homologous to the sum of cycles lying in the neighborhood of the roots of (15).

**Lemma 4** (A. Tsikh, [23]). Under the above assumptions
\[
\int_{\Gamma} \frac{P(z) dz}{f_1(z) \ldots f_n(z)} = 0
\]
for any polynomial $P(z)$ such that $p_j = \deg_z f_i P \leq m_{1j} + \ldots + m_{nj}$ for all $j = 1, \ldots, n$.

The Lemma was proved using the residue theorem (theorem on a total sum of residues) on a compact complex manifold.

**Lemma 5.** Let $\tilde{\Delta} = \tilde{\Delta}(w,t)$ be the Jacobian of (12) with respect to $w_1, \ldots, w_n$. Then
\[
\frac{1}{F_j(w)} = \sum_{p=0}^{\infty} (-1)^p t^p \tilde{Q_j^p}(w).
\]

where $K = (k_1, \ldots, k_n)$ is multi-index, $\tilde{Q^K} = \tilde{Q}_1^{k_1} \ldots \tilde{Q}_n^{k_n}$,
\[
\beta(K, J) = (m_{1j_1}(k_1 + 1) - 1, \ldots, m_{nj_n}(k_n + 1) - 1),
\]

$\beta(K, J)! = \prod_p (m_{pj_p}(k_{jp} + 1) - 1)!$, and
\[
\mathcal{R} = \{ K = (k_1, \ldots, k_n) : \text{there exists } \gamma_i \text{ such that } \| K \| < \gamma_i + 2, \; i = 1, \ldots, n \}. 
\]
The rest of the notations in the statement are as in Theorem 2.

**Proof.** Representation (14) and Lemma 3 yield

\[ J_\gamma(t) = \frac{(-1)^n}{(2\pi\sqrt{-1})^n} \int_{\Gamma_h} w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \cdot \frac{d\tilde{F}_1}{F_1} \wedge \cdots \wedge \frac{d\tilde{F}_n}{F_n} \]

\[ = \frac{(-1)^n}{(2\pi\sqrt{-1})^n} \int_{\Gamma_h} w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \sum_{|K|\geq 0} (-t)^{|K|} \Delta \cdot \frac{\tilde{Q}_K^{k_1} \cdots \tilde{Q}_K^{k_n}}{q_1^{k_1+1} \cdots q_n^{k_n+1}} dw \]

so that

\[ J_\gamma(t) = \sum_{|K|\geq 0} (-t)^{|K|} \sum_{j} (-1)^{s(j)} \cdot \frac{\partial^{p_j}|\beta(K,j)|}{\partial w^\beta(K,j)} \left[ \Delta \cdot w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \cdot \frac{\tilde{Q}_K^1 \cdots \tilde{Q}_K^n}{q_1^{k_1+1} \cdots q_n^{k_n+1}} \right]_{w=a_j}. \quad (16) \]

We now show that the summation in the above formulas is over a finite set of multi-indices. To show this, we estimate the degrees in \( w \) of the numerator and compare with the corresponding degrees of the denominator of (16).

The degree of the numerator in \( w_i \) is less than or equal to

\[ p_i = m_1i + \cdots + m_{ni} - 1 + \gamma_i + 1 + (m_1i - 1)k_1 + \cdots + (m_{ni} - 1)k_n. \]

The corresponding degree of the denominator is

\[ s_i = m_1i(k_1 + 1) + \cdots + m_{ni}(k_n + 1). \]

Lemma 4 implies vanishing of all the integrals for which the inequality \( p_i \leq s_i - 2 \) holds for all \( i = 1, \ldots, n \), so that

\[ m_1i + \cdots + m_{ni} - 1 + \gamma_i + 1 + (m_1i - 1)k_1 + \cdots + (m_{ni} - 1)k_n \]

\[ \leq m_1i(k_1 + 1) + \cdots + m_{ni}(k_n + 1) - 2. \]

After combining like terms we arrive at

\[ \gamma_i + 1 - k_1 - \cdots - k_n - 1 \leq -2 \]

or

\[ \gamma_i + 2 \leq |K|. \]

Thus, the only non-zero integrals in (16) are the ones for which \( K \) runs over such set that \( \gamma_i + 2 > |K|\) for at least one \( \gamma_i \).

\[ \square \]

**Lemma 6.** Let \( w_1, \ldots, w_s \) where \( w_j = (w_{j1}, \ldots, w_{jn}) \), \( j = 1, \ldots, n \) be all the zeros (depending on \( t \)) of (12) counting multiplicities. Then

\[ J_\gamma = (-1)^n \sum_{j=1}^s w_{j1}^{\gamma_j+1} \cdot w_{j2}^{\gamma_j+1} \cdots w_{jn}^{\gamma_j+1}. \]
The number \( s \) of zeros is equal to the permanent of the matrix \((m_{ij})_{1 \leq i, j \leq n}\) (see [23] or [5, Theorem 8.5]).

**Proof.** The statement follows from the multidimensional logarithmic residue formula and the theorem on shifted skeleton (see [3, Chapter 3]). \(\square\)

Denote by \( z^{(j)}(t) = (z_{j1}(t), \ldots, z_{jn}(t)) \), \( j = 1, \ldots, s \), the zeros of (2) with the functions \( tQ_i \), where \( Q_i \) are defined by (10) and do not lie in the coordinate subspaces. The latter fact implies that the number of the zeros is finite. Since \( w_j \) do not lie in coordinate subspaces, then \( z_{jm} = 1/w_{jm}, m = 1, \ldots, n \) and therefore we have finite number \( p \) of zeros. Consequently \( p \leq s \).

**Theorem 7.** The following equality holds:

\[
\sum_{j=1}^{p} \frac{1}{z_{j1}(t)^{\gamma_1+1} \cdots z_{jn}(t)^{\gamma_n+1}} = \sum_{K \in \mathbb{R}} (-1)^{|K|} \sum_{j} \frac{(-1)^{s(j)}}{\beta(K, J)!} \frac{\partial^{\|\beta(K, J)\|}}{\partial w^\beta(K, J)} \left[ \hat{\Delta}(t) \cdot w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \right]_{w=a_j}.
\]

**Proof.** The statement follows from Lemmas 5 and 6. \(\square\)

Thus, the power sum of zeros of (12) is a polynomial on \( t \), and, therefore, the equality in Theorem 7 also holds for \( t = 1 \).

Denote

\[
\sigma_{\gamma+1} = \sum_{j=1}^{p} \frac{1}{z_{j1}^{\gamma_1+1} \cdots z_{jn}^{\gamma_n+1}},
\]

where \( z^{(j)} = (z_{j1}, \ldots, z_{jn}) = (z_{j1}(1), \ldots, z_{jn}(1)), j = 1, \ldots, p \).

**Theorem 8** (Waring’s formulas). For the system (2) with functions \( f_j \) defined by (2) and \( Q_i \) defined by (10) the following formulas are valid:

\[
\sigma_{\gamma+1} = \sum_{j=1}^{p} \frac{1}{z_{j1}^{\gamma_1+1} \cdots z_{jn}^{\gamma_n+1}} = \frac{1}{(2\pi \sqrt{-1})^n} \sum_{\|K\| \geq 0} (-1)^{|K|} \sum_{j} (-1)^{s(j)} \int_{\tilde{V}_{h,a_j}} \hat{\Delta} \cdot w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \cdot \frac{\tilde{Q}_1^{k_1} \cdots \tilde{Q}_n^{k_n}}{q_1^{k_1+1} \cdots q_n^{k_n+1}} \, dw
\]

\[
= \sum_{K \in \mathbb{R}} (-1)^{|K|} \sum_{j} \frac{(-1)^{s(j)}}{\beta(K, J)!} \frac{\partial^{\|\beta(K, J)\|}}{\partial w^\beta(K, J)} \left[ \hat{\Delta} \cdot w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \right]_{w=a_j}.
\]

**Proof.** The statement of the Theorem is a corollary of Theorem 7. \(\square\)

Note that in [10] the authors considered algebraic systems and obtained expansions of their solutions into geometric series. Moreover, the authors obtained analogs of Waring’s formulas for the systems

\[
y_j^{m_j} + \sum_{\lambda \in \Lambda^{(j)} \cup \{0\}} x^{(j)}_\lambda y^\lambda = 0, \quad \lambda_1 + \ldots + \lambda_n < m_j, \quad j = 1, \ldots, n,
\]

where leading homogeneous parts are monomials (here \( \Lambda^{(j)} \) is a finite set of multi-indices).
4 Residue integrals and Waring’s formulas for transcendental systems

We now consider a more general situation. Let $f_j$ be entire functions in $\mathbb{C}^n$ of finite order not greater than $\rho$ and

$$f_j(z) = \prod_{s=1}^{\infty} f_{j,s}(z), \quad j = 1, \ldots, n. \quad (17)$$

Here $f_{j,s}(z)$ are entire functions in $\mathbb{C}^n$ of finite order not greater than $\rho$ admitting expansion into uniformly convergent in $\mathbb{C}^n$ infinite products with factors of the form

$$f_{j,s}(z) = (q_{j,s} + Q_{j,s}(z)),$$

where $q_{j,s}(z)$ and $Q_{j,s}(z)$ are the polynomials defined by (3) and (10) respectively. An entire function of several complex variables is not always decomposable into an infinite product of the functions associated with its zeros (see, e.g., [19]). The sufficient conditions for the existence of such an expansion (in the form of convergence of the distances between the origin and zero sets of the functions $q_{j,s} + Q_{j,s}(z)$) one can find in [20].

Denote by $z^{(j)} = (z_{j1}, \ldots, z_{jn})$, $j = 1, \ldots, \infty$, the zeros of (17) not lying on coordinate subspaces, counting multiplicities.

We now give a multidimensional Waring’s formula for transcendental systems.

**Theorem 9.** Consider the system $f_j(z) = 0$, $j = 1, \ldots, n$, with functions defined by (17). Then, the following formulas are valid:

$$\sigma_{\gamma+1} = \sum_{j=1}^{\infty} \frac{1}{\gamma_1^{n+1} \cdots \gamma_n^{n+1}} = \sum_{K \in \mathbb{R}} (-1)^{||K||+n} \sum_{S} \sum_{J} (-1)^{s(J)} \prod_{i=1}^{||K,J||} \left[ \Delta \cdot w_1^{\gamma_1+1} \cdots w_n^{\gamma_n+1} \cdot \tilde{Q}^K(s) \right]_{w=a_J},$$

where $\tilde{Q}^K(s) = \tilde{Q}_{1,s}^{k_1} \cdots \tilde{Q}_{n,s}^{k_n}$.

**Proof.** We have

$$\frac{d f_j(z)}{f_j(z)} = \frac{\prod_{s=1}^{\infty} f_{j,s}(z)}{\sum_{s=1}^{\infty} f_{j,s}(z)} = \sum_{s=1}^{\infty} \frac{d f_{j,s}(z)}{f_{j,s}(z)}.$$

It is easy to check that the above series converges uniformly on $\Gamma_{h,a,j}$. Indeed, if a sequence of continuous on a compact set $M$ functions $f_n$ uniformly convergent to a function $f$ on $M$ and $f \neq 0$ on $M$ is given, then, starting from some number $m_0$ for $m \geq m_0$, the functions $f_m \neq 0$ on $M$ and the sequence $1/f_m$ will converge uniformly on $M$ to the function $1/f$. Similarly, one can show that uniform convergence is preserved under element-wise multiplication.

Uniform convergence of $\prod_{s=1}^{\infty} f_{j,s}(z)$ on $\Gamma_{h,a,j}$ yields uniform convergence of the series

$$\sum_{s=1}^{\infty} \frac{d f_{j,s}(z)}{f_{j,s}(z)} = \frac{\prod_{s=1}^{\infty} f_{j,s}(z)}{\prod_{s=1}^{\infty} f_{j,s}(z)} = \lim_{m \to \infty} \frac{\prod_{s=1}^{m} f_{j,s}}{\prod_{s=1}^{m} f_{j,s}}.$$
on $\Gamma_q$. Thus, $J_\gamma(1)$ is defined and is equal to the convergent series of the integrals

$$
\frac{1}{(2\pi \sqrt{-1})^n} \int_{\Gamma_q} \frac{1}{z^{\gamma+1}} \cdot \frac{df_{1,s_1}(z)}{f_{1s_1}(z)} \wedge \ldots \wedge \frac{df_{ns_n}(z)}{f_{ns_n}(z)},
$$

where the summation is taken over the cubes with integer sides centered at the origin. And, for each such integral the required formula was proved in Theorem 8.

If $\prod_{s=1}^{\infty} f_{j,s}(z)$ converge absolutely, then their values does not depend on a permutation of their factors. In other words, changing the numbering of the roots does not affect the values of the infinite products of $f_{j,s}(z)$. Consequently, $J_\gamma$ also does not depend on the permutation of its terms. This yields absolute convergence of $J_\gamma$ and $\sigma_{\gamma+1}$.

**Remark 3.1** We are now ready to describe the scheme of elimination of unknowns. Consider a system of equations of the form as in Theorems 8 and 9. Let $s_i$ be the power sums of its roots

$$
s_i = \sigma_{i_1,\ldots,i_k} = \sum_{j=1}^{\infty} \frac{1}{z_{j_1}^{i_1} \cdot \ldots \cdot z_{j_n}^{i_n}}, \quad i \geq 1. \tag{18}
$$

Now, we need to find an entire function $f(w)$ of a single variable $w \in \mathbb{C}$, such that the power sums of its roots coincide with $s_i$ (by Weierstrass theorem). Let the Taylor expansion of this function be

$$
f(w) = 1 + b_1 w + \ldots + b_k w^k + \ldots
$$

Since the series in the right hand side of (18) converge absolutely, then $f$ can be decomposed into an infinite product with respect to its zeros

$$
c_i = \frac{1}{z_{j_1}^{i_1} \cdot \ldots \cdot z_{j_n}^{i_n}}, \quad i \geq 1
$$

(Hadamard’s formula), which yields that $f(w)$ is an entire function of at most first order of growth. The analogs of recurrent Newton formulas connecting the coefficients $b_k$ and the sums $s_i$ for such functions were given in [5, Chapter 1]. More precisely, Theorem 2.3 in [5] states that

$$
\sum_{j=0}^{k-1} b_j s_{k-j} + k b_k = 0, \quad b_0 = 1, \quad k \geq 1.
$$

These formulas allow one to find the coefficients of the function $f(w)$, whose roots are $c_i$. So, the function $f(w)$ is an analog of the resultant for a system of algebraic equations.

### 5 Examples

Since the power sums in Theorem 9 are multidimensional series, then, clearly, this theorem provides one with a method for computing multidimensional series of such kind. For this purpose, one has to find a system such that the power sums of its roots coincide with elements of the given series. Once such a system has been found, the sum of the series can then be found by using Theorem 9.
In this section, we consider examples which admit use of the described method. One can find power sums of roots by applying Theorem 8. Then, in the second example, we consider two functions each of which admits expansion into an infinite product of the functions considered in the first example. Using Theorem 9 we then construct the series consisting of the power sums of the roots of the system and find the sum of this series.

**Example 10.** Consider the system in two complex variables

\[
\begin{aligned}
&f_1(z_1, z_2) = (1 - a_2z_2)^2 + a_3z_1^2 = 0, \\
&f_2(z_1, z_2) = (1 - b_1z_1)^2(1 - b_2z_2) + b_3z_1^2z_2 = 0
\end{aligned}
\]  

(19)

with real coefficients \(a_i\) and \(b_i\). For this system, \(Q_1\) and \(Q_2\) are of the form (10). It is not hard to verify that the system (19) has 5 roots \((z_1, z_2), j = 1, 2, 3, 4, 5\). If \(a_2 \neq b_2\), then all the roots do not lie in the coordinate hyperplanes.

After the substitution \(z_1 = 1/w_1, z_2 = 1/w_2\), (19) takes the form

\[
\begin{aligned}
&\tilde{f}_1 = w_1(w_2 - a_2)^2 + a_3 = 0, \\
&\tilde{f}_2 = (w_1 - b_1)^2(w_2 - b_2) + b_3 = 0.
\end{aligned}
\]  

(20)

The Jacobian \(\tilde{\Delta}\) of (20) is equal to

\[
\tilde{\Delta} = \begin{vmatrix}
(w_2 - a_2)^2 & 2w_1(w_2 - a_2) \\
2(w_1 - b_1)(w_2 - b_2) & (w_1 - b_1)^2
\end{vmatrix} = (w_1 - b_1)^2(w_2 - a_2)^2 - 4w_1(w_1 - b_1)(w_2 - a_2)(w_2 - b_2)
\]

Now, using Theorem 8, we compute the power sums

\[
\sigma_j = \sum_{j=1}^{5} \frac{1}{z_j^{\gamma_j+1}} \cdot \frac{1}{z_j^{\gamma_j+1}}
= \sum_{j}(\text{(-1)}^j)^s(j) \sum_{K \in \mathbb{R}} \frac{(-1)^{||K||}}{(2\pi i)^2} \int_{\Gamma_{h,a,j}} \frac{w_1^{\gamma_1+1} \cdot w_2^{\gamma_2+1} \cdot a_3^{k_1} \cdot b_3^{k_2} \cdot \tilde{\Delta} \cdot dw_1 \wedge dw_2}{(w_2 - a_2)^{2(k_1+1)} \cdot (w_1 - b_1)^{2(k_2+1)}(w_2 - b_2)^{k_2+1}}.
\]

Here \(\mathbb{R} = \{K = (k_1, k_2) : \text{there exists } i \text{ such that } \gamma_i + 2 > k_1 + k_2 \text{ for } i = 1, 2\}\), and \(\Gamma_{h,a,j}\) are the cycles either \(|w_1| = r_{11}, |w_2 - b_2| = r_{22}\) oriented positively or \(|w_2 - a_2| = r_{12}, |w_1 - b_1| = r_{21}\) oriented negatively.

In particular, by computing \(J_{(0,0)}\) and performing necessary algebra, we obtain that

\[
\sigma_{(1,1)} = 4a_2b_1 - \frac{a_3b_2}{(b_2 - a_2)^2}
\]  

(21)

without finding the roots.

**Example 11.** Recall the known expansions of \(\sin z\) into an infinite product and a power series:

\[
\frac{\sin \sqrt{z}}{\sqrt{z}} = \prod_{k=1}^{\infty} \left(1 - \frac{z}{k^2\pi^2}\right) = \sum_{k=0}^{\infty} \frac{(-1)^k z^k}{(2k + 1)!}.
\]
Using the formula \((23)\) the sum of the first series in the right hand side of \((19)\) is
\[
\sum_{j=1}^{\infty} \frac{1}{z_j} - \frac{1}{z_j^2} = \sum_{k,m=1}^{\infty} \frac{4a_2b_1}{\pi^2 k^2 m^2} - \sum_{k,m=1}^{\infty} \frac{a_3 b_2}{\pi^2 (a_2 m^2 - b_2 k^2)^2}.
\]

Using the formula \([22, \text{No. 2, Section 5.1.25}]\)
\[
\sum_{k=1}^{\infty} \frac{1}{(k^2 + a^2)^2} = -\frac{1}{2a^4} + \frac{\pi}{4a^4} \coth(\pi a) + \frac{\pi^2}{4a^4} \frac{1}{\sinh^2(\pi a)}
\]
we find the sum of the first series in the right hand side of \((23)\)
\[
\sum_{k,m=1}^{\infty} \frac{4a_2b_1}{\pi^4 k^2 m^2} = \frac{a_2b_1}{9}
\]
and, respectively, the sum of the second series in the right hand side of \((23)\)
\[
\sum_{k,m=1}^{\infty} \frac{a_3 b_2}{\pi^2 (a_2 m^2 - b_2 k^2)^2} = -\sum_{k=1}^{\infty} \frac{a_3}{2\pi^2 b_2 k^4}
- \sum_{k=1}^{\infty} \frac{a_3}{4\pi \sqrt{-a_2 b_2 k^3}} \coth(\pi \sqrt{-b_2/a_2 k}) - \sum_{k=1}^{\infty} \frac{a_3}{4a_2 k^2} \frac{1}{\sinh^2(\pi \sqrt{-b_2/a_2 k})}.
\]
Here the sum of the first series in the right hand side is
\[
\sum_{k=1}^{\infty} \frac{a_3}{2\pi^2 b_2 k^4} = \frac{a_3 \pi^2}{180 b_2}.
\]

We now find the sum of the second series. Let \(2\Phi_1(e^{2t}, e^{2t}; e^{4t}, x)\) be a basic hypergeometric series (see, e.g., \([22, \text{p. 793}]\)). We use the known formula \([22, \text{No. 13, Section 5.2.18}]\)
\[
\sum_{k=1}^{\infty} \frac{x^{k-1}}{e^{2tk} - 1} = \frac{x}{x} \sum_{k=1}^{\infty} \frac{x^k}{e^{2tk} - 1} = \frac{1}{e^{4t} - 1} 2\Phi_1(e^{2t}, e^{2t}; e^{4t}, x) = \frac{1}{e^{4t} - 1} 2\Phi_1(e^{2t}, e^{2t}; e^{4t}, x).
\]
Therefore,
\[
\sum_{k=1}^{\infty} \frac{\coth(tk)}{k^3} = \sum_{k=1}^{\infty} \frac{1}{k^3} + 2 \sum_{k=1}^{\infty} \frac{1}{k^3(e^{2tk} - 1)}
\]
\[
= \zeta(3) + 2 \frac{1}{e^{4u} - 1} \int_{0}^{1} \frac{1}{y} dy \int_{0}^{v} \frac{1}{v} dv \int_{0}^{v} 2\Phi_1(e^{2t}, e^{2t}; e^{4t}, u) du
\]
\[
= \zeta(3) + \frac{1}{e^{4t} - 1} \int_{0}^{1} \ln^2 y \cdot 2\Phi_1(e^{2t}, e^{2t}; e^{4t}, y) dy. \quad (24)
\]

In order to find the sum of the third series we rewrite \(1/sinh^2(tk)\) as
\[
\frac{1}{\sinh^2(tk)} = \left( \frac{2}{e^{tk} - e^{-tk}} \right)^2 = \frac{4e^{2tk}}{(e^{2tk} - 1)^2}.
\]

Now, since
\[
\frac{\partial}{\partial t} \left[ \frac{1}{e^{tk} - 1} \right] = -\frac{2ke^{2tk}}{(e^{2tk} - 1)^2},
\]
we have
\[
\frac{1}{(e^{2tk} - 1)^2} = -\frac{1}{e^{2tk} - 1} - \frac{1}{2k} \cdot \frac{\partial}{\partial t} \left[ \frac{1}{e^{2tk} - 1} \right].
\]

Consequently,
\[
\sum_{k=1}^{\infty} \frac{1}{\sinh^2(tk) \cdot k^2} = -\frac{\partial}{\partial t} \left[ \sum_{k=1}^{\infty} \frac{2}{k^3(e^{2tk} - 1)} \right].
\]

Thus, using the formula (24), we find that the series \(\sigma_{1,1}\) is expressed in terms of the values of some integrals and known series without calculating the roots of the system.

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