Embedding Feynman integral (Calabi-Yau) geometries in weighted projective space

Bourjaily, Jacob L.; McLeod, Andrew J.; Vergu, Cristian; Volk, Matthias; von Hippel, Matt; Wilhelm, Matthias

Published in:
Journal of High Energy Physics

DOI:
10.1007/JHEP01(2020)078

Publication date:
2020

Document version
Publisher's PDF, also known as Version of record

Document license:
CC BY

Citation for published version (APA):
Bourjaily, J. L., McLeod, A. J., Vergu, C., Volk, M., von Hippel, M., & Wilhelm, M. (2020). Embedding Feynman integral (Calabi-Yau) geometries in weighted projective space. Journal of High Energy Physics, 2020(1), [078]. https://doi.org/10.1007/JHEP01(2020)078
Embedding Feynman integral (Calabi-Yau) geometries in weighted projective space

Jacob L. Bourjaily, Andrew J. McLeod, Cristian Vergu, Matthias Volk, Matt von Hippel, and Matthias Wilhelm

Niels Bohr International Academy and Discovery Center, Niels Bohr Institute, University of Copenhagen, Blegdamsej 17, DK-2100, Copenhagen Ø, Denmark
Center for the Fundamental Laws of Nature, Department of Physics, Jefferson Physical Laboratory, Harvard University, 17 Oxford street, Cambridge, MA 02138, U.S.A.

E-mail: bourjaily@nbi.ku.dk, amcleod@nbi.ku.dk, c.vergu@nbi.ku.dk, mvolk@nbi.ku.dk, mvonhippel@nbi.ku.dk, matthias.wilhelm@nbi.ku.dk

ABSTRACT: It has recently been demonstrated that Feynman integrals relevant to a wide range of perturbative quantum field theories involve periods of Calabi-Yau manifolds of arbitrarily large dimension. While the number of Calabi-Yau manifolds of dimension three or higher is considerable (if not infinite), those relevant to most known examples come from a very simple class: degree-2 hypersurfaces in k-dimensional weighted projective space WP1,...,1,k. In this work, we describe some of the basic properties of these spaces and identify additional examples of Feynman integrals that give rise to hypersurfaces of this type. Details of these examples at three loops and of illustrations of open questions at four loops are included as supplementary material to this work.

KEYWORDS: Differential and Algebraic Geometry, Scattering Amplitudes

ArXiv ePrint: 1910.01534
1 Introduction and summary

Recent years have seen the development of a rich interplay between number theory, algebraic geometry, and the study of perturbative scattering amplitudes in quantum field theory. Even for what is arguably the simplest class of amplitudes — those that can be expressed in terms of multiple polylogarithms [1–6] — a great deal of conceptual and computational progress has been made [7–29] by harnessing the geometric (or motivic) structures with which these functions are endowed when viewed as iterated integrals on the moduli space of the Riemann sphere with marked points [2, 3, 30–38].

Slightly more complicated amplitudes can be described in terms of elliptic multiple polylogarithms, which can be understood as iterated integrals over the (moduli space of the) torus. This class of functions has been the focus of a great deal of recent work and is now also under reasonably good theoretical control (in part based on an understanding of modular forms) [39–61].

In general, one expects increasingly complicated classes of integrals to appear in scattering amplitudes at higher perturbative orders, corresponding to integrals over manifolds
with higher dimension and/or genus. Even for amplitudes known or expected to be poly-
logarithmic, this feature may be impossible to realize while preserving locality (see for
example ref. [62] and the examples discussed in ref. [63]). A general understanding of the
types of integrals that can show up is currently lacking. However, in a surprisingly large
number of cases, it has been observed that these manifolds are Calabi-Yau [61, 64–70].

Even at dimensions as low as three or four, large numbers of Calabi-Yau manifolds are
known to exist — having been constructed and studied, in part, because of their role in
string compactifications (see e.g. refs. [71–74]). One may wonder if a similarly vast number
of geometries are relevant to Feynman integrals in perturbative quantum field theories.
The answer seems to be no. Indeed, all the examples identified in ref. [64] and the entire
class of ‘maximally rigid, marginal’ integrals described in ref. [66] are members of a special
family: they are given as codimension-one (degree-2k) hypersurfaces in the k-dimensional
weighted projective space $\mathbb{WP}^{1,\ldots,1,k}$. This motivates us to better understand this family of
Calabi-Yau manifolds and explore the consequences of their geometry for physics.

The coefficients of the polynomials that define these hypersurfaces are functions of
kinematic data. Virtually all known examples involve (highly) singular Calabi-Yau hyper-
surfaces, and there is little doubt that these singularities will play a significant role in our
understanding of these Feynman integrals. But in this work we mostly set these bigger
questions aside and discuss the geometry of the smooth case — obtainable, in general,
by sufficiently ‘regularizing’ complex structure deformations. This regularization makes it
possible for us to compute various topological quantities, such as Hodge numbers. The
reader may wonder what is the significance of these quantities. While a complete answer
is not available at this point, we believe it is likely that the Hodge numbers will account
for part of the contribution to the dimension of integral bases in terms of which integrals
sharing a given topology decompose.

This work is organized as follows. In section 2, we review some basic algebraic and
differential-geometric aspects of these particular Calabi-Yau geometries. In particular, we
discuss their Dolbeault cohomology groups $H^{p,q}$ and how to compute the associated Hodge
numbers $h^{p,q}$, and discuss the Euler characteristics of (smooth) Calabi-Yau hypersurfaces
of $\mathbb{WP}^{1,\ldots,1,k}$. We also review the construction of canonical holomorphic forms (unique up to
an overall scaling), and discuss how the integral of this form over various cycles defines the
independent periods of the hypersurface (which in some sense characterize its geometry).

We study these aspects of Calabi-Yau hypersurfaces in $\mathbb{WP}^{1,\ldots,1,k}$ with the general
expectation that the integral geometries appearing in Feynman diagrams can be found to
encode some of the physics of these diagrams. Characterizing these geometries is a first
and necessary step for identifying such connections. We also expect these geometries to be
relevant to the development of technology for representing these Feynman integrals in terms
of iterated integrals. For instance, periods play an important role in the definition of elliptic
multiple polylogarithms [51, 52, 54, 56] and are required to bring differential equations
into $\varepsilon$-canonical form [53]. However, for general Calabi-Yau $(k-1)$-folds beyond the elliptic
case ($k = 2$), the calculation of these periods still poses a challenging problem. (But see
ref. [75] for an example where it has been done for the quintic Calabi-Yau hypersurface in
$\mathbb{P}^4$.) Additionally, a connection between the dimension of certain cohomology groups and
numbers of master integrals has recently been established using intersection theory [76–78].
After this geometric primer, we go on in section 3 to describe in detail two examples of Calabi-Yau geometries relevant to massless, four-dimensional planar theories at three loops. Unlike the analysis in refs. [64, 66], which identified these geometries using direct integration, we here identify such hypersurfaces by taking sequences of residues (as done in ref. [67]). We do this by first deriving manifestly dual-conformal-invariant six-fold representations of these integrals using loop-by-loop Feynman parametrization [67, 79–81]. As both integrals contribute to planar maximally supersymmetric Yang-Mills theory, we expect all six remaining integrations to be transcendental; therefore, each residue mimics a polylogarithmic integration.\footnote{This follows from the expectation that three-loop integrals will evaluate to functions with uniform transcendental weight six. Even though the notion of transcendental weight is not established beyond the case of polylogarithms, both integrals degenerate to weight-six polylogarithms in known limits.} In both integrals, Calabi-Yau hypersurfaces appear in the denominator when no more residues can be taken.

The first integral we study in this way is the three-loop traintrack (or triple-box) integral shown in figure 1a, which has already been identified as a K3 surface by several of the authors [67]. We show here how to realize it as a hypersurface in $\mathbb{P}^{1,1,1,3}$. The second integral is the three-loop wheel shown in figure 1b, which involves a hypersurface in $\mathbb{P}^{1,1,1,4}$. While the general three-loop wheel depends on nine kinematic variables, we also study several of its interesting kinematic limits, some of which we evaluate in terms of polylogarithms. Moreover, we show that the three-loop wheel permits a toy model similar to that of the elliptic double-box [80], which has only three parameters while still involving a Calabi-Yau threefold.

The three-loop traintrack and wheel integrals are the minimal representatives (in terms of loop order and particle multiplicity) of massless planar topologies that contain these Calabi-Yau geometries. They occur in massless $\varphi^4$ theory (in the case of the wheel, as a dual graph), the planar limit of maximally supersymmetric Yang-Mills theory, and integrable conformal fishnet models [82–84], as well as in more general four-dimensional massless theories via generalized unitarity [85–91]. For this reason, they merit focused investigation.

While the present work inaugurates this study, it offers only a coarse analysis of the involved Calabi-Yau geometries. A more refined analysis, including e.g. Picard ranks, has been possible for some integrals containing K3 surfaces [65, 68–70, 92, 93], for instance, using differential equations. It would be important to analyze the Calabi-Yau surfaces identified here and in refs. [64, 66, 67] in a similar way, although these cases will be more difficult due to the larger number of kinematic variables.
We conclude in section 4 by highlighting open problems at four loops and beyond. In addition to discussing some of the broader questions that remain to be answered regarding the appearance of higher-dimensional varieties in Feynman integrals (and the technology required to cope with them), we consider the four-loop traintrack and wheel integrals. Intriguingly, we are not able to identify either of these examples as a Calabi-Yau hypersurface in \( \mathbb{WP}^{1,...,1,k} \).

In appendices A and B, we provide more background on the desingularization of hypersurfaces in weighted projective space and the computation of Hodge numbers and Euler characteristics. In appendix C we review loop-by-loop Feynman parametrization [67, 79–81] and derive a manifestly dual-conformal six-fold representation of the three-loop wheel integral, and in appendix D we derive a dual-conformal nine-fold representation of the four-loop wheel. In the latter case, we also describe several interesting kinematic limits and toy models. In the supplementary material, we include the details of these examples, as well as the equations defining the hypersurfaces obtained.

### 2 Calabi-Yau hypersurfaces in \( \mathbb{WP}^{1,...,1,k} \)

In this section, we characterize the \( k \)-dimensional weighted projective space \( \mathbb{WP}^{1,...,1,k} \), which involves \( k \) coordinates of weight 1 and a single coordinate of weight \( k \). This space can be defined as the quotient of \( \mathbb{C}^{k+1} \setminus \{ 0 \} \) by the equivalence relation

\[
(x_1, \ldots, x_k, y) \sim (\lambda x_1, \ldots, \lambda x_k, \lambda^k y).
\]

Here, \( \lambda \in \mathbb{C}^* \) denotes a non-zero complex number and \( (x_1, \ldots, x_k, y) \) are referred to as homogeneous coordinates on \( \mathbb{WP}^{1,...,1,k} \).

We will be interested in defining an algebraic hypersurface embedded into \( \mathbb{WP}^{1,...,1,k} \) as the zero-locus of a polynomial \( Q \) in the homogeneous coordinates. Of course, such a polynomial relation has to be consistent with the equivalence relation (2.1). In unweighted projective space, this would correspond to the requirement that the polynomial be homogeneous. Analogously, in weighted projective space, the total weight of each monomial must be the same; this number is called the (overall) degree of the polynomial.

One can show (see for example ref. [94]) that the zero-locus of any single polynomial in the coordinates of a weighted projective space defines a codimension-one Calabi-Yau hypersurface if the overall degree of the polynomial equals the sum of the weights of the weighted projective space. In the case of \( \mathbb{WP}^{1,...,1,k} \), a Calabi-Yau hypersurface can thus be defined by a polynomial \( Q \) of degree \( (\sum_{i=1}^k 1) + k = 2k \), which has the most general form

\[
Q(x_1, \ldots, x_k, y) = \sum_{(\tilde{\alpha}, \beta) \in \mathbb{N}_0^{k+1}} c_{\tilde{\alpha}, \beta} \prod_{i=1}^k x_i^{\alpha_i} y^\beta,
\]

where \( \alpha_i \) denotes the \( i^{th} \) component of \( \tilde{\alpha} \) and \( |\tilde{\alpha}| := \sum_1^k \alpha_i \). The coefficients \( c_{\tilde{\alpha}, \beta} \in \mathbb{C} \) are complex numbers, and can in general depend on additional parameters (which for us will be kinematics). However, these coefficients are only defined up to \( \mathbb{WP}^{1,...,1,k} \) coordinate
transformations. In particular, we can rescale all coordinates using the equivalence relation (2.1) to set \( c_{d,2} \rightarrow 1 \), and additionally shift \( y \) by a degree-\( k \) polynomial in the \( x_i \) to eliminate the terms linear in \( y \) (thereby setting \( c_{d,1} \rightarrow 0 \)). This brings \( Q \) into the form

\[
Q(x_1, \ldots, x_k, y) = y^2 - P(x_1, \ldots, x_k).
\]

(2.3)

Finally, we can act with a GL(\( k \)) transformation on the \( x_i \). This can be used to eliminate \( k^2 \) of the \( \binom{3k-1}{k-1} \) possible monomials in \( P \). The remaining \( \binom{3k-1}{k-1} - k^2 \) coefficients yield distinct hypersurfaces, which are usually parametrized by \( \binom{3k-1}{k-1} - k^2 \) complex structure moduli. We should emphasize that hypersurfaces taking the form (2.2) may be singular for some values of the coefficients. For generic coefficients, they are however smooth (see the discussion in appendix A).

We now consider a Calabi-Yau manifold \( X \) embedded as a codimension-one hypersurface in \( \mathbb{P}^1; \ldots; \mathbb{P}^k \) and study the forms on \( X \). Since \( X \) is a complex manifold, any \( m \)-form on \( X \) can be decomposed into a sum of forms with \( p \) holomorphic and \( q \) antiholomorphic pieces such that \( p + q = m \). Moreover, the exterior derivative decomposes as \( d = \partial + \bar{\partial} \). In analogy with de Rham cohomology, one can then define the Dolbeault cohomology groups \( H^{p,q}(X) \) as the cohomology groups of \( \bar{\partial} \). The dimensions of the Dolbeault cohomology groups are known as Hodge numbers, \( h^{p,q}(X) := \dim(H^{p,q}(X)) \). Moreover, the dimensions of the de Rham cohomology groups \( h^m \) are given by \( h^m = \sum_{p+q=m} h^{p,q} \). Recall that via Poincaré duality and de Rham’s theorem, \( h^m \) are exactly the Betti numbers, which count the numbers of independent \( m \)-cycles on \( X \).

In an \( n \)-dimensional complex manifold in which \( p \) and \( q \) run from 0 to \( n \), one might naively expect \( (n+1)^2 \) different Hodge numbers. However, due to various symmetries many of these numbers are not independent. For example, in the case of a Calabi-Yau threefold \( (k = 4) \), \( h^{1,1} \) and \( h^{2,1} \) fix the values of all other Hodge numbers.

In general, the computation of the Hodge numbers of a complex manifold poses a difficult problem.\(^2\) In the case of Calabi-Yau hypersurfaces embedded in toric varieties — of which weighted projective space is an example — the mirror-symmetry construction due to Batyrev [95] provides a framework to compute (some of the) Hodge numbers from purely combinatorial data. (For more pedagogical introductions on this topic see, for instance, refs. [96, 97].) In short, one associates to a defining polynomial (such as \( Q \) in eq. (2.2)) a pair of dual polytopes \((\Delta, \Delta^*)\). The polytope \( \Delta \) is called the Newton polytope and its vertices are given by the (shifted) vectors of exponents of the polynomial. (Note that the vertices of \( \Delta \) therefore lie in an integer lattice.) One can show that in terms of \((\Delta, \Delta^*)\) the Calabi-Yau condition becomes the statement that the dual polytope \( \Delta^* \) only has integer vertices and that both polytopes contain only the origin as an interior lattice point. Some

\(^2\)For smooth varieties, this can be achieved in general by Gröbner bases computations. We thank the referee for pointing this out to us.
of the Hodge numbers can then be computed from the polytopes as

$$h_{1,n} = \delta_{1,n} \left[ \ell(\Delta) - (d + 1) - \sum_{\text{codim } \theta^* = 1} \ell_{\text{int}}(\theta^*) \right] + \delta_{d-2,n} \left[ \ell(\Delta) - (d + 1) - \sum_{\text{codim } \theta = 1} \ell_{\text{int}}(\theta) \right] + \sum_{\text{codim } \theta^* = n + 1} \ell_{\text{int}}(\theta^*) \ell_{\text{int}}(\theta).$$

(2.4)

Here $\ell$ and $\ell_{\text{int}}$ count the total and interior lattice points of a polytope, respectively, and the sums run over faces of $\Delta$ and $\Delta^*$, denoted by $\theta$ and $\theta^*$, with the given codimension. Note that Batyrev’s framework explicitly excludes the case of K3 surfaces ($k = 3$).

This construction can be generalized to so-called complete intersection Calabi-Yaus (CICYs) embedded into a toric variety and one can obtain more Hodge numbers as the expansion coefficients of a two-variable generating function known as stringy $E$-function [98, 99],

$$E(u, v) = \sum_{p,q} (-1)^{p+q} h_{p,q} u^p v^q.$$  

(2.5)

The construction of the function $E$ relies on a generalization of the reflexive polytope criterion outlined above by so-called nef-partitions. The function has been implemented in PALP [100], which is available from SageMath [101].

For the case of a Calabi-Yau hypersurface in $\mathbb{WP}^{1,...,k}$, the Newton polytope and its dual take a relatively simple form and allow us to compute $h^{1,j}$ from eq. (2.4): for any $k \geq 4$, we find

$$h^{1,j} = \begin{cases} \binom{3k-1}{k-1} - k^2 & j = k - 2, \\ 1 & j = 1, \\ 0 & \text{otherwise.} \end{cases}$$

(2.6)

The non-trivial Hodge number $h^{1,k-2}$ counts the complex structure moduli discussed above, while $h^{1,1}$ counts the single Kähler structure modulus. We have moreover verified this formula by comparing to the stringy $E$-function implemented in PALP [100], which also computes the remaining Hodge numbers.

For the elliptic curve ($k = 2$), the Hodge numbers are well-known to be

$$h^{0,0} = 1, 
\begin{array}{c|c|c}
 h^{1,0} & h^{0,1} & = \begin{bmatrix} 1 & 1 \\ 1 & 1 \end{bmatrix} \\
h^{1,1} & 
\end{array}.$$  

(2.7)

As already mentioned, the case of the K3 surface, $k = 3$, is excluded in the general framework above. Here, in addition to the $\binom{6+2}{2} - 9 = 19$ complex structure moduli, the Kähler structure modulus contributes to $h^{1,1}$, allowing us to obtain the well-known result

$$h^{0,0} = 1, 
\begin{array}{c|c|c|c|c|c}
 h^{1,0} & h^{0,1} & h^{2,0} & h^{1,1} & h^{0,2} & = \begin{bmatrix} 1 & 20 & 1 \\ 0 & 0 & \end{bmatrix} \\
h^{2,1} & h^{1,2} & 
\end{array}.$$  

(2.8)

- 6 -
For higher $k$, we find the following patterns of Hodge numbers:

- Calabi-Yau threefold, $k = 4$:

\[
\begin{array}{cccc}
  h^{0,0} & & & 1 \\
  h^{1,0} & h^{0,1} & & 0 \\
  h^{2,0} & h^{1,1} & h^{0,2} & 0 \\
  h^{3,0} & h^{2,1} & h^{1,2} & h^{0,3} = 1 & 149 & 149 & 1 \\
  h^{3,1} & h^{2,2} & h^{1,3} & h^{0,4} & 0 \\
  h^{3,2} & h^{2,3} & & 0 \\
  h^{3,3} & & & 1 \\
\end{array}
\] (2.9)

- Calabi-Yau fourfold, $k = 5$:

\[
\begin{array}{cccccc}
  h^{0,0} & & & & & 1 \\
  h^{1,0} & h^{0,1} & & & & 0 \\
  h^{2,0} & h^{1,1} & h^{0,2} & & & 0 \\
  h^{3,0} & h^{2,1} & h^{1,2} & h^{0,3} & & 0 \\
  h^{4,0} & h^{3,1} & h^{2,2} & h^{1,3} & h^{0,4} = 1 & 976 & 3952 & 976 & 1 \\
  h^{4,1} & h^{3,2} & h^{2,3} & h^{1,4} & & 0 \\
  h^{4,2} & h^{3,3} & h^{2,4} & & & 0 \\
  h^{4,3} & h^{3,4} & & & & 0 \\
  h^{4,4} & & & & & 1 \\
\end{array}
\] (2.10)

- Calabi-Yau fivefold, $k = 6$:

\[
\begin{array}{cccccccc}
  & & & & & & & & 1 \\
  & & & & & & & 0 & 0 \\
  & & & & & & 0 & 1 & 0 \\
  & & & & & 0 & 0 & 0 & 0 \\
  & & & & 0 & 0 & 1 & 0 & 0 \\
  & & & 1 & 6152 & 67662 & 67662 & 6152 & 1 \\
  & & 0 & 0 & 1 & 0 & 0 & 0 \\
  & 0 & 0 & 1 & 0 & 0 & 0 \\
  & 0 & 0 & 1 & 0 & 0 \\
  1 & & & & & & & 1 \\
\end{array}
\] (2.11)
Table 1. Euler characteristic $\chi(X)$ of $(k-1)$-dimensional Calabi-Yau hypersurfaces $X$ in $\mathbb{P}^{1,\ldots,1,k}$ for low values of $k$.

- Calabi-Yau sixfold, $k = 7$:

\[
\begin{array}{cccccccccc}
  & 0 & 24 & -296 & 5910 & -147624 & 4482044 & -160180656 & 6588215370 \\
\hline
k \backslash \chi(X) & 2 & 3 & 4 & 5 & 6 & 7 & 8 & 9 \\
\end{array}
\]

The structure of these Hodge diamonds is very simple; a nontrivial cohomology only exists for degrees $(p,p)$ and $(p,k-p-1)$, corresponding to their middle column and row. Interestingly, the form of these Hodge diamonds is compatible with hypersurfaces embedded in ordinary (unweighted) projective space (see appendix B.3 for a short discussion). It would be interesting to understand why this occurs, as we currently do not know how to embed our hypersurfaces in unweighted projective space.

To further characterize the Calabi-Yau manifold $X$ in $\mathbb{P}^{1,\ldots,1,k}$, we compute its Euler characteristic $\chi(X)$. The Euler characteristic is equal to the alternating sum of the dimensions of the de Rham cohomology groups,

\[\chi(X) = \sum_m (-1)^m \sum_{p+q=m} h^{p,q}.\]

Following ref. [94], we can obtain a closed expression for it using an index theorem, see appendix B.1 for details. We find

\[\chi(X) = \frac{1 - (1 - 2k)^k + 2k^2}{2k}.\]

The Euler characteristic of $X$ for low values of $k$ is given in table 1.

We have seen above that a codimension-one Calabi-Yau hypersurface $X$ in $\mathbb{P}^{1,\ldots,1,k}$ is defined by a polynomial $Q(x_1, \ldots, x_k, y)$ of the form given in eq. (2.2). In the examples considered in the following sections, we will find polynomials of precisely this form with different coefficients $c_{i,\beta}$, i.e. with different complex structure moduli. The complex structure moduli of $X$ are in principle determined by integrating the holomorphic form of maximal degree along a basis of cycles on the manifold. While in practice this is a difficult problem, we still give an account of how this form is constructed.
On $\mathbb{CP}^{n_1, \ldots, n_k}$, the canonical $k$-form $\Omega_k$ is given by
\[
\Omega_k = k y \left( \bigwedge_{n=1}^{k} dx_n \right) + \sum_{n=1}^{k} (-1)^{n} x_n dy \wedge \left( \bigwedge_{m \neq n} dx_m \right).
\] (2.14)

The Calabi-Yau hypersurface $X$ is defined as the zero-locus of the polynomial $Q(x_1, \ldots, x_k, y)$ in eq. (2.2). The holomorphic form $\omega_{k-1}$ of (maximal) degree $k - 1$ on $X$ is then given by
\[
\omega_{k-1} = \text{Res} \frac{\Omega_k}{Q}.
\] (2.15)

The residue above is determined\(^3\) by the property that
\[
\frac{\Omega_k}{Q} = \left( \text{Res} \frac{\Omega_k}{Q} \right) \wedge \frac{dQ}{Q} + \cdots,
\] (2.16)
where the omitted terms are regular on the surface $Q = 0$.

The hypersurfaces we encounter in the following sections turn out not to be smooth — i.e. there are non-trivial solutions to the system of polynomial equations $Q(x_1, \ldots, x_k, y) = dQ(x_1, \ldots, x_k, y) = 0$. Heuristically, the reason for this is that some of the monomials that would in principle be allowed for homogeneous polynomials in the coordinates of $\mathbb{CP}^{n_1, \ldots, n_k}$ are missing in $Q$. Moreover, the coefficients depend on a limited number of kinematic variables, which is usually much smaller than the number of complex structure moduli. In order to regularize the polynomials arising during integration, we can however consider a deformation of the complex structure, i.e. of the coefficients of the $c_{\alpha, \beta}$ in eq. (2.2). Equivalently, we may say that we are considering the polynomials that we encounter in the following examples as special cases of a generic (smooth) polynomial $Q$ as defined in eq. (2.2). We provide more details on desingularization by complex structure deformation in appendix A.

3 Three-loop integrals involving Calabi-Yaus in $\mathbb{CP}^{n_1, \ldots, n_k}$

Among the growing list of examples of Feynman integrals involving Calabi-Yau geometries are those with surprisingly few propagators — such as the so-called ‘banana’ integrals or ‘tardigrades’,

These integrals are sub-topologies\(^4\) of almost all Feynman integrands at sufficiently high multiplicity, and it seems that any integral with a sub-topology involving a Calabi-Yau itself

\(^3\)Outside of the hypersurface $X$, this residue is not uniquely defined since we could add to $\text{Res} \frac{\Omega_k}{Q}$ terms proportional to $Q$. However, when pulled back to $X$, these terms vanish.

\(^4\)We consider one Feynman integrand a sub-topology of another if the graph of the former’s propagators is a quotient of the latter’s by an (internal) edge contraction.
involves a Calabi-Yau. Thus, even for the special classes of scattering amplitudes that are expected to be polylogarithmic to all orders (see e.g. ref. [102]), it seems impossible that any local, Feynman-integrand-level representation can have this property term-by-term. Thus, it is essential that we learn to better understand these examples.

This sense of the ubiquity of Calabi-Yau geometries can be made more precise in the context of generalized unitarity, where it is possible to describe bases of Feynman integrands subject to certain constraints. A basis large enough to represent all-multiplicity amplitudes in planar, maximally ($\mathcal{N} = 4$) supersymmetric Yang-Mills (SYM) theory through three loops was described in ref. [90]. Although $\mathcal{N} = 4$ SYM theory in the planar limit is an unquestionably simple theory, this basis represents a necessary part of any larger basis needed to represent amplitudes in theories with ultraviolet behavior worse than $\mathcal{N} = 4$ SYM theory (including the Standard Model). Thus, it is a natural place to start our understanding of the Calabi-Yau geometries relevant to general amplitudes.

At three loops, the basis of integrands needed for planar $\mathcal{N} = 4$ SYM theory consists of the traintrack and wheel integrands shown in figure 1, and all irreducible integrands that contain one (or both) as sub-topologies and scale like either integrand (or better) in the ultraviolet. Thus, these two examples arise nearly ubiquitously (at large enough multiplicity) in three-loop amplitudes, motivating us in this section to study the Calabi-Yau geometry that arises in each. But first, let us describe the methods by which we may uncover these geometries.

### 3.1 Identifying Calabi-Yau geometries via residues

Several infinite classes of Feynman diagrams have been shown to involve Calabi-Yau hypersurfaces in $\mathbb{CP}^{1,...,1,k}$ using direct integration [64, 66]. For instance, the two-dimensional banana graphs and four-dimensional tardigrades shown in eq. (3.1) both fall into this category. In fact, these integral families both achieve the maximum possible degree of non-polylogarithmic for marginal integrals. More precisely, the $L$-loop representative of each family saturates a bound on the possible ‘rigidity’ of marginal integrals, where the rigidity of an integral is defined to be the dimension of the algebraic variety one must integrate over after a maximal number of polylogarithmic integrations have been carried out [66]. The banana graphs have rigidity $L-1$, while the tardigrades have rigidity $2(L-1)$.\footnote{In the case of equal masses, the three-loop banana integral was recently expressed in terms of elliptic multiple polylogarithms [61]. While it involves a K3 surface, this K3 surface is related to the elliptic curve describing the two-loop sunrise graph in a way that drastically simplifies the problem [92]. For general Calabi-Yau hypersurfaces, we would not expect this procedure to work, but it would be interesting to see to what extent it is possible. (See ref. [69] for some work in this direction.)} The two-dimensional massive banana graphs are required, for example, in the calculation of the electron self-energy in QED [103], while the massless two-loop tardigrades enter the integrand basis for massless two-loop amplitudes using prescriptive unitarity [63, 90, 91, 104, 105].

In this work, we instead use sequences of residues to identify Calabi-Yau hypersurfaces in Feynman integrals, as done in ref. [67]. In particular, we begin with representations of (here non-marginal) Feynman integrals at $L$ loops in terms of rational integrands involving only $2L$ integration variables (motivated by the conjectured bound of transcendental weight
Figure 2. The $L$-loop traintrack integral and its dual graph.

$2L$ at $L$ loops in four dimensions). We then examine the singular locus of these integrands by taking as many residues as we can.\(^6\) This leads us to an expression of the form

$$\frac{d\vec{x}}{\sqrt{P(\vec{x})}},$$

(3.2)

where $P(\vec{x})$ is a polynomial which is cubic or higher degree in the remaining variables without repeated roots. After projectivization, this polynomial defines a codimension-one hypersurface in $\mathbb{P}^{1,\ldots,1,k}$ via eq. (2.3).

It is important to note that the above procedure mimics \textit{but is not equivalent to} the procedure of direct hyperlogarithmic integration. They are superficially similar in that direct integration partial-fractions rational integrands to isolate poles in the integration variable, while taking sequential residues also isolates poles. However, the partial-fractioning step of direct integration generates a term for each pole of the integrand, and preserves information about that pole in the form of the polylogarithmic function it constructs. If \textit{any} of these poles introduce a square root in the remaining variables, then this dependence will appear in the polylogarithmic integrand and direct integration may be obstructed. In contrast, by taking residues we may avoid this type of obstruction. As a result, the hypersurfaces we discuss in this section will not necessarily correspond to the degree of rigidity of the integrals involved; the integrals may be more ‘rigid’ than the geometry we describe would suggest.

While our residue procedure does not necessarily uncover the maximally rigid geometry, it does uncover a geometry that is important and necessary to the understanding of these Feynman integrals. In particular, it is a geometry that should characterize the periods obtained by analytic continuation in the kinematics. To motivate this, recall that we can isolate any particular residue of the integrand with an integration contour tailored to that purpose. These closed integration contours represent potential ambiguities in the original Feynman integration contour, corresponding to the possibility to encircle additional branch cuts. Much as analytically continuing polylogarithmic functions around branch cuts results in factors of $2\pi i$, analytically continuing one of the integrals discussed in this work should give rise to integrals over the maximal residues we can perform — that is, integrals over the holomorphic forms of the Calabi-Yau manifolds we describe.

3.2 Revisiting the three-loop traintrack integral

In ref. [67], some of the authors provided evidence that the $L$-loop traintrack integral, depicted in figure 2, involves an integral over a Calabi-Yau $(L-1)$-fold. There, a manifestly

\(^6\)If necessary, we perform changes of variables to rationalize square roots of quadratic polynomials along the lines of ref. [106].
dual-conformally invariant $2L$-fold representation was given for this integral:

$$\Sigma^{(L)} = \int_0^\infty \left[ d^L \alpha \right] d^L \beta \frac{1}{(f_1 \cdots f_L) g_L},$$

(3.3)

where

$$f_k := (a_0 a_{k-1} a_k b_k)(a_k b_k b_{k-1} a_0)(a_k b_k b_{k-1} a_{k-1}) f_{k-1} + \alpha_0 (\alpha_k + \beta_k) + \alpha_k \beta_k + \sum_{j=1}^{k-1} \left[ \alpha_j \alpha_k (b_j a_0 ; a_j a_k) + \alpha_j \beta_k (b_j a_0 ; a_j b_k) + \alpha_k \beta_j (b_0 a_j ; a_k b_j) + \beta_j \beta_k (b_0 a_j ; b_k b_j) \right],$$

(3.4)

$$g_L := \alpha_0 + \sum_{j=1}^L \left[ \alpha_j (b_j a_0 ; b_0 b_j) + \beta_j (a_0 a_j ; b_0 b_j) \right],$$

and $(xy;zw)$ denotes the cross-ratio

$$(xy;zw) := \frac{(x|y)(z|w)}{(x|z)(y|w)}.$$

(3.5)

The notation $(ab) := (x_a - x_b)^2$ is intended to be suggestive of the embedding (or momentum-twistor) formalism.

We now specialize to three loops. Since each $f_k$ is linear in every integration variable, we can take residues in $\beta_1$, $\beta_2$, and $\beta_3$ on the locus of $f_1 = f_2 = f_3 = 0$. This leaves a single factor in the denominator, which is a rational function of $\alpha_0, \alpha_1, \alpha_2$, and $\alpha_3$. Performing one final residue in $\alpha_3$, we obtain a square root of a polynomial with no repeated roots, $P_2(\alpha_0, \alpha_1, \alpha_2)$. This polynomial is degree six in $\alpha_0$ and $\alpha_1$ and degree four in $\alpha_2$ (the latter fact motivated the authors of ref. [67] to put this polynomial into Weierstrass form with respect to $\alpha_2$, which will here prove unnecessary). Importantly, it can be checked that $P_2$ is a homogeneous polynomial in $\alpha_0$, $\alpha_1$, and $\alpha_2$ of (overall) degree six. Therefore, writing this hypersurface as

$$Q(x_1, x_2, x_3, y) = y^2 - P_2(x_1, x_2, x_3) = 0,$$

(3.6)

we identify it as a degree-six hypersurface in $\mathbb{WP}^{1,1,1,3}$. Generic surfaces of this type are well known to be K3 manifolds, which have Hodge diamond (2.8) and Euler characteristic 24. We include the original three-loop integrand (from eq. (3.3)) in MATHEMATICA format in the supplementary material integrands_and_varieties.m.

3.3 The three-loop wheel integral

The three-loop scalar wheel integral is drawn in momentum space and dual-momentum space in figure 3. Using the notation presented in the previous subsection, it is given by

$$\mathbb{W}^{(3)} := \int d^4 x_A d^4 x_B d^4 x_C \frac{(a_1 | a_2)(b_1 | b_2)(c_1 | c_2)}{(A|C)(A|a_1)(A|a_2)(A|B)(B|b_1)(B|b_2)(B|C)(C|c_1)(C|c_2)}.$$

(3.7)
where we have included a numerator that renders it dual-conformally invariant. In appendix C, we derive an equivalent six-fold integral representation of this integral, following the strategy of refs. [67, 79, 81]. We quote the result here for convenience:

$$W^{(3)} = \frac{1}{f_1 f_2 f_3} \int_0^\infty d\alpha d\beta d\gamma \frac{n_0}{f_1 f_2 f_3},$$  

(3.8)

where

$$n_0 := v_1(u_1 u_2 u_3 v_1 v_2 v_3),$$  

$$f_1 := \alpha_1 + \alpha_2 + \alpha_1 \alpha_2,$$  

$$f_2 := \alpha_1 (1 + \alpha_2 + \beta_1 + \beta_2 + \gamma_2) + \alpha_2 (1 + u_1 w_2 (w_3 \beta_1 + \beta_2) + \gamma_2) + \beta_1 v_1 (1 + u_1 u_3 v_2 \beta_2 + \gamma_2) + u_2 v_1 (u_1 v_3 \gamma_1 + \beta_2 (1 + \gamma_2)),$$  

$$f_3 := (1 + \alpha_2 + \beta_1 + \beta_2 + \gamma_2) \left[ \alpha_1 (\gamma_1 + \beta_2 (1 + \alpha_2 + u_3 v_1 v_2 \beta_1 + \gamma_2) + w_3 \beta_1 (1 + \alpha_2 + \gamma_2)) + (1 + \gamma_2) (w_3 \alpha_1 \beta_1 + (\alpha_2 + u_3 v_1 v_2 \beta_1) \beta_2) + \gamma_1 \left[ \alpha_2 (1 + u_1 (w_3 \beta_1 + \beta_2) + \gamma_2) + u_3 v_1 (u_2 w_1 \beta_2 (1 + \gamma_2) + \beta_1 (1 + u_1 v_2 \beta_2 + \gamma_2)) \right] \right],$$

(3.9)

and where we have used the following basis of dual-conformal invariant cross-ratios:

$$u_1 := (c_1 a_1 ; a_2 b_2), \quad u_2 := (a_1 b_1 ; b_2 c_2), \quad u_3 := (b_1 c_1 ; c_2 a_2),$$  

$$v_1 := (a_1 a_2 ; b_1 c_2), \quad v_2 := (b_1 b_2 ; c_1 a_2), \quad v_3 := (c_1 c_2 ; a_1 b_2),$$  

$$w_1 := (b_2 c_1 ; c_2 b_1), \quad w_2 := (c_2 a_1 ; a_2 c_1), \quad w_3 := (a_2 b_1 ; b_2 a_1).$$

(3.10)

Note that the dihedral symmetry of $\mathfrak{W}^{(3)}$ acts quite naturally on these variables. Specifically, under the dihedral group that leaves the graph in figure 3 invariant, the $u_i$’s, $v_i$’s and $w_i$’s each form a three-orbit. We include this integrand in MATHEMATICA format in the supplementary material integrands_and_varieties.m.

To analyze the geometry of $\mathfrak{W}^{(3)}$ (3.8), we first take three residues on the locus $f_i = 0$ by eliminating the variables $\alpha_1$, $\beta_2$, and $\gamma_1$. We thereby obtain a three-form

$$\frac{d\alpha_2 d\beta_1 d\gamma_2}{\sqrt{P_{\mathfrak{W}}(\alpha_2, \beta_1, \gamma_2)}},$$

(3.11)

where $P_{\mathfrak{W}}$ is a non-homogeneous polynomial. However, assigning $\alpha_2$, $\beta_1$, and $\gamma_2$ all weight one, we can homogenize $P_{\mathfrak{W}}(\alpha_2, \beta_1, \gamma_2)$ by adding a fourth (auxiliary) weight-one coordinate
x_4. The resulting homogeneous polynomial can be chosen to have overall degree eight, and we denote it \( P^8_{W^1}(\alpha_2, \beta_1, \gamma_2, x_4) \). As it is rather long, we do not present this polynomial in the text, but we provide it in the supplementary material integrands_and_varieties.m. Finally, introducing a weight-four variable \( y \) with \( y^2 = P^8_{W^1}(x_1, x_2, x_3, x_4) \), we obtain a three-form which can be expressed as

\[
\omega_3 = \frac{x_4 dx_1 dx_2 dx_3}{y} \tag{3.12}
\]
in the patch where \( x_4 \) is a non-vanishing constant.

Up to a numerical factor, the three-form \( \omega_3 \) can be obtained from eq. (2.15) by taking the residue of

\[
\frac{4 y^2 - P^8_{W^1}(x_1, x_2, x_3, x_4)}{y^2 - P^8_{W^1}(x_1, x_2, x_3, x_4)} \tag{3.13}
\]
at the locus defined by the vanishing of the denominator, where \( \Omega_4 \) is the canonical four-form on \( \mathbb{P}^{1,1,1,1,4} \) given in eq. (2.14),

\[
\Omega_4 = 4 y dx_1 dx_2 dx_3 dx_4 + dy \left( -x_1 dx_2 dx_3 dx_4 + x_2 dx_1 dx_3 dx_4 
- x_3 dx_1 dx_2 dx_4 + x_4 dx_1 dx_2 dx_3 \right). \tag{3.14}
\]

It follows that \( Q(x_1, x_2, x_3, x_4) = y^2 - P^8_{W^1}(x_1, x_2, x_3, x_4) = 0 \) defines a Calabi-Yau threefold in \( \mathbb{P}^{1,1,1,1,4} \). The polynomial \( P^8_{W^1} \) has \( \binom{8+3}{3} - 16 = 149 \) complex structure moduli, but in our case they depend only on the nine cross-ratios in eq. (3.10). Hence, by varying these cross-ratios, we only explore a small part of the complex structure moduli space of our Calabi-Yau threefold.

**Interesting kinematic limits.** We start by considering the limit in which the legs at the rungs of the wheel become massless. This corresponds to the condition that the dual coordinates on either side of these legs become light-like separated, namely \( (a_2|b_1) \to 0, \) \( (b_2|c_1) \to 0, \) and \( (c_2|a_1) \to 0. \) In the variables (3.10), this sets all three parameters \( w_i \to 0: \)

\[
\{ (a_2|b_1) \to 0, \ (b_2|c_1) \to 0, \ (c_2|a_1) \to 0 \} \quad \Leftrightarrow \quad \{ w_1 \to 0, \ w_2 \to 0, \ w_3 \to 0 \} \tag{3.15}
\]

(Notice that we denote light-like separated points in the dual graph by dashed green lines.) It can be checked that the resulting integral is still a Calabi-Yau hypersurface in \( \mathbb{P}^{1,1,1,1,4}. \)

To see this Calabi-Yau threefold factorize into simpler geometries, we now consider the limit in which one of these massless legs becomes soft. It can easily be checked that
identifying \( a_2 = b_1 \) sets \( u_3 = v_1 = v_2 = 1 \):

\[
\{ u_3 \to 1, \; v_1 \to 1, \; v_2 \to 1, \; w_i \to 0 \} \quad (3.17)
\]

In this limit, \( P(\alpha_2, \beta_1, \gamma_2) \) factorizes, and one of its factors is a perfect square. This allows us to take an additional residue. Continuing on in this fashion, we find we can take residues in all six integration variables; so from the residue analysis, there is no irreducible geometry. However, direct integration is obstructed after just a single integration; as we emphasized in section 3.1, these functions may appear to be more rigid under direct integration than their residue analysis would suggest.

It turns out this obstruction can be avoided by additionally setting \( v_3 = 1 \) (in this case our choice is purely pragmatic, and not particularly motivated by physics). On this kinematic slice, the integral evaluates to

\[
\frac{u_1 u_2}{u_1 - u_2} \left\{ G_{u,1,1,0,1,0,0} + G_{u,0,0,0,1,0,0} + G_{u,0,0,0,1,1,0} - G_{u,1,0,0,1,0,0} - G_{u,0,0,0,1,1,0} \\
- G_{u,0,0,0,1,0,0} + G_{u,0,0,0,1,1,0} - G_{u,0,0,0,0,0} - G_{u,0,0,0,0,1} \\
- G_{u,1,0,0,1,0,0} + G_{u,1,0,0,1,1,0} + G_{u,1,0,0,0,0} + G_{u,1,0,0,0,1} \\
- G_{u,1,0,0,0,0} + G_{u,1,0,0,0,1} + G_{u,1,0,0,1,0} + G_{u,1,0,0,1,1} \\
+ \zeta_2 \left[ G_{u,1,0,0,0} + G_{u,0,1,0,0} + G_{u,0,0,1,0} - G_{u,1,0,0,0} - G_{u,1,0,0,1} - G_{u,0,0,0,1} \right] \\
+ G_{u,0,1,0,1,0} - G_{u,0,1,0,0,0} + G_{u,0,1,0,0,1} - G_{u,0,1,0,1,0} + G_{u,0,1,0,1,1} \\
+ 2 \zeta_3 \left[ G_{u,1,0,0,0} + G_{u,0,1,0,0} + G_{u,0,0,1,0} - G_{u,1,0,0,0} - G_{u,1,0,0,1} - G_{u,0,0,0,1} \right] \\
+ 4 \zeta_2 \zeta_3 \left[ G_{u,1,0,1,0,0} \right] + (u_1 \leftrightarrow u_2),
\]

using the shorthand \( G^a_{\bar{w}} := G(\{\bar{w}\}, z) \). We also include this expression in the supplementary material integrands_and_varieties.m.

Further simplifications may be achieved by taking a second of the massless legs to be soft. Identifying \( a_1 = c_2 \) after taking the limit (3.17) additionally sets \( u_2 = v_3 = 1 \), making this integral the \( u_2 \to 1 \) limit of expression (3.19):

\[
\frac{u_1 u_2}{u_1 - u_2} \left\{ G_{u,1,1,0,1,0,0} + G_{u,0,0,0,1,0,0} + G_{u,0,0,0,1,1,0} - G_{u,1,0,0,1,0,0} - G_{u,0,0,0,1,1,0} \\
- G_{u,0,0,0,1,0,0} + G_{u,0,0,0,1,1,0} - G_{u,0,0,0,0,0} - G_{u,0,0,0,0,1} \\
- G_{u,1,0,0,1,0,0} + G_{u,1,0,0,1,1,0} + G_{u,1,0,0,0,0} + G_{u,1,0,0,0,1} \\
- G_{u,1,0,0,0,0} + G_{u,1,0,0,0,1} + G_{u,1,0,0,1,0} + G_{u,1,0,0,1,1} \\
+ \zeta_2 \left[ G_{u,1,0,0,0} + G_{u,0,1,0,0} + G_{u,0,0,1,0} - G_{u,1,0,0,0} - G_{u,1,0,0,1} - G_{u,0,0,0,1} \right] \\
+ G_{u,0,1,0,1,0} - G_{u,0,1,0,0,0} + G_{u,0,1,0,0,1} - G_{u,0,1,0,1,0} + G_{u,0,1,0,1,1} \\
+ 2 \zeta_3 \left[ G_{u,1,0,0,0} + G_{u,0,1,0,0} + G_{u,0,0,1,0} - G_{u,1,0,0,0} - G_{u,1,0,0,1} - G_{u,0,0,0,1} \right] \\
+ 4 \zeta_2 \zeta_3 \left[ G_{u,1,0,1,0,0} \right] + (u_1 \leftrightarrow u_2),
\]
where

\[
\frac{u_1}{1-u_1} \left[ G_{u_1^0,0,0,0,0} + G_{u_1^0,0,1,1,0} + G_{u_1^0,0,0,1,1,0} + G_{u_1^0,0,0,1,0,1,0} 
- G_{u_1^0,1,1,0,1,0} - G_{u_1^0,0,1,0,0,0} - G_{u_1^0,0,1,0,1,0} 
+ \zeta_2 \left( G_{u_1^0,1,1,0} - G_{u_1^0,1,0,1} - G_{u_1^0,0,1,0} + G_{u_1^0,0,0,1} \right) 
+ 2\zeta_3 \left( G_{u_1^0,1,1,0} + G_{u_1^0,1,0,1} + G_{u_1^0,0,1,0} + G_{u_1^0,0,0,1} \right) 
- 6\zeta_4 \left( G_{u_1^0,0,1,1} - G_{u_1^0,0,0,0} \right) 
- 2(5\zeta_5 + \zeta_2\zeta_3)G_{u_1^0} + 4(\zeta_2^3 - \zeta_3^2) + 3\zeta_6 \right].
\]

(3.21)

We also include this expression in the supplementary material integrands_and_varieties.m.

The last massless leg is removed by setting the final cross-ratio \( u_1 = 1 \):

\[
\frac{u_1}{1-u_1} \left[ G_{u_1^0,0,0,0,0} + G_{u_1^0,0,1,1,0} + G_{u_1^0,0,0,1,1,0} + G_{u_1^0,0,0,1,0,1,0} 
- G_{u_1^0,1,1,0,1,0} - G_{u_1^0,0,1,0,0,0} - G_{u_1^0,0,1,0,1,0} 
+ \zeta_2 \left( G_{u_1^0,1,1,0} - G_{u_1^0,1,0,1} - G_{u_1^0,0,1,0} + G_{u_1^0,0,0,1} \right) 
+ 2\zeta_3 \left( G_{u_1^0,1,1,0} + G_{u_1^0,1,0,1} + G_{u_1^0,0,1,0} + G_{u_1^0,0,0,1} \right) 
- 6\zeta_4 \left( G_{u_1^0,0,1,1} - G_{u_1^0,0,0,0} \right) 
- 2(5\zeta_5 + \zeta_2\zeta_3)G_{u_1^0} + 4(\zeta_2^3 - \zeta_3^2) + 3\zeta_6 \right].
\]

(3.22)

In this limit, the integral evaluates to

\[
= 20\zeta_5.
\]

(3.23)

This might naively be surprising, as one expects the three-loop wheel to have transcendental weight six. However, one can observe that the rational prefactor diverges in the \( u_1 \to 1 \) limit of expression (3.20); in order to take this limit one should therefore expand the polylogarithmic part of this function in a power series, which leads to a drop in weight [15, 107–114].

A three-parameter toy model. The three-loop wheel integral allows for a three-parameter toy model similar to that of the elliptic double-box [80]. This toy model is defined by taking all six dual-momentum points defining the three-loop wheel integral to be light-like separated in sequence. That is, we take

\[
(a_1|b_2) = (b_2|c_1) = (c_1|a_2) = (a_2|b_1) = (b_1|c_2) = (c_2|a_1) = 0.
\]

(3.24)

(3.25)
In this limit, some of the rescalings of the Feynman parameters in our derivation become singular.\footnote{Concretely, the rescalings of the Feynman parameters $\beta_2$ taken in eq. (C.19) and those for $\gamma_i$ in eq. (C.24) are singular in the limit (3.24). However, this observation clearly signals how these problems can be remedied: to access this limit smoothly from our previous expression (C.25), we merely need to rescale

\[
\beta_2 \mapsto \beta_2 \frac{(a_1 [b_2] [a_2 c_2])}{(a_1 [a_2] [b_2 c_2])}, \quad \gamma_1 \mapsto \gamma_1 \frac{(a_2 [b_2] [c_2])}{(a_2 [b_2] [c_1] [c_2])},
\]

\[
\gamma_2 \mapsto \gamma_2 \frac{(a_1 [a_2] [b_2 c_2])}{(a_1 [a_2] [b_2 c_2])}, \quad \gamma_3 \mapsto 1 \times \frac{(a_1 [a_2] [b_2 c_2])}{(a_1 [b_2] [a_2 c_2])},
\]

take into account the relevant Jacobians, and collect terms. After this has been done, the limit (3.24) can be taken smoothly.}

The cross-ratios chosen in eq. (3.10) also become problematic; individually we have $v_i, w_i \to 0, u_i \to \infty$, while the ratios

\[
t_1 := \frac{1}{u_1 v_2 v_3} = (b_1 c_1 : b_2 c_2), \quad t_2 := \frac{1}{u_2 v_3 v_1} = (a_1 c_1 : a_2 c_2), \quad t_3 := \frac{1}{u_3 v_1 v_2} = (a_1 b_1 : a_2 b_2) \quad (3.27)
\]

remain finite. Accounting for both of these issues, we find the six-fold integral representation becomes

\[
\mathcal{W}^{(3)} \to \mathcal{W}^{\text{toy}} := \int_0^\infty d^2 \alpha \ d^2 \beta \ d^2 \gamma \ \frac{1}{g_1 \ g_2 \ g_3}, \quad (3.28)
\]

where

\[
g_1 := \alpha_1 + \alpha_2 + \alpha_1 \alpha_2,
\]

\[
g_2 := \alpha_1 (1 + \alpha_2 + \beta_1 + \gamma_2) + (\alpha_2 + \beta_2)(1 + \gamma_2) + \gamma_1,
\]

\[
g_3 := \alpha_1 \beta_2 (1 + \alpha_2 + \beta_1 + \gamma_2)(\beta_1 + t_2 (1 + \alpha_2 + \gamma_2)) + \gamma_1 \left[ t_1 \beta_1 (1 + \gamma_2) + t_2 (t_3 \alpha_2 + \beta_1) \beta_2 \right]
\]

\[
+ \beta_2 (1 + \alpha_2 + \beta_1 + \gamma_2)(t_3 \alpha_2 + \beta_1)(1 + \gamma_2),
\]

in terms of the cross-ratios (3.27).

As before, we can take residues in $\alpha_1, \beta_2$, and $\gamma_1$, obtaining a non-homogeneous curve $P_{20}^{\text{toy}}(\alpha_2, \beta_1, \gamma_2) = P_{20}^{\text{toy}}(x_1, x_2, x_3)$ that we can then homogenize with an auxiliary variable $x_4$. The resulting degree-eight polynomial is

\[
P_{20}^{\text{toy}} = \left[ x_2 (x_2^2 x_3 - x_1 x_2 x_4) t_2 + x_2^2 (x_1 x_3 (t_2 - 1) - (x_2 + x_3) x_3 - (x_2 t_2 + x_3) x_4) t_3 \right.
\]

\[
- x_2 (x_1 + x_2 + x_3 + x_4) (x_1 x_3 + (x_3 + x_4) x_4)^2 - 2 t_1 x_2 (x_1 + x_4) (x_3 + x_4)^2
\]

\[
\times \left[ (x_1 + x_2 + x_3 + x_4) (x_2^2 x_3 t_2 + x_1 x_2 x_3 + x_2 x_3 (x_3 + x_4)) \right.
\]

\[
+ t_2 x_1 (x_1 t_3 + x_2) (x_1 x_3 - x_2 x_4) + t_1^2 x_2^2 (x_1 + x_4)^2 (x_3 + x_4)^4. \quad (3.30)
\]

We include both the toy model integrand and the above hypersurface in MATHEMATICA format in the supplementary material integrands_and_varieties.m.

We pause here to highlight that it is possible to see this polynomial factorize into simpler polynomials in simple kinematic limits. Despite its presentation, the toy model’s geometry must be invariant under permutations of $t_1, t_2$, and $t_3$; thus, we may consider taking limits in any variable. However, these limits can naively look different; for instance,
if we set \( t_1 \to 0 \) or \( t_2 \to 0 \), the polynomial becomes a perfect square of a polynomial with overall degree four, while in the limit \( t_3 \to 0 \) it factorizes into \( x_2^2 \) times a polynomial of overall degree six. By symmetry, the irreducible geometry in each of these limits must be the same. In the first case (taking the limit in either \( t_1 \) or \( t_2 \)), the resulting (squared) polynomial has degree three in \( x_1 \) and \( x_4 \), and degree two in \( x_2 \) and \( x_3 \). This lets us perform an additional residue in either \( x_2 \) or \( x_3 \), by which we obtain a square root of a polynomial of overall degree six. In the second case (taking the limit in \( t_3 \)) we instead take a residue at \( x_2 = 0 \), after which the remaining polynomial has overall degree six. Both of the resulting polynomials define a K3, although it is not easy to see that they describe the same geometry (i.e. that they correspond to different parametrizations of the same hypersurface).

If we take an additional cross-ratio to zero, the curve degenerates again. It becomes a square of a polynomial that is cubic in one variable and quadratic in the remaining two. This allows an additional residue in one of the quadratic variables, giving rise to a square root of a quadratic polynomial in the remaining two variables. Such square roots are rationalizable under a change of variables, so the integral should be polylogarithmic in this limit.

### 4 Open problems at four loops and beyond

Having shown that the three-loop traintrack and wheel both involve Calabi-Yau hypersurfaces that can be embedded in \( \mathbb{WP}^{1,1,1,1} \), it is natural to ask whether their four-loop counterparts also involve such hypersurfaces.

**The four-loop traintrack.** Equations (3.3) and (3.4) provide an eight-fold integral representation of the four-loop traintrack integral (which we again provide in Mathematica format in the supplementary material integrands_and_varieties.m). We can analyze the residues of this integral in the same way as was done for the three-loop integrals in the last section, to see if it contains a Calabi-Yau hypersurface in \( \mathbb{WP}^{1,1,1,1} \). Here we can take four residues, in \( \beta_1, \beta_2, \beta_3, \) and \( \beta_4 \), on the locus \( f_1 = f_2 = f_3 = f_4 = 0 \), then one final residue in \( \alpha_4 \) on \( g_4 = 0 \) to obtain a square root of a polynomial \( P^{(4)}_T(\alpha_0, \alpha_1, \alpha_2, \alpha_3) \) with no repeated roots. This polynomial is homogeneous, but has overall degree ten. It is degree ten in \( \alpha_0 \) and \( \alpha_1 \), degree six in \( \alpha_2 \), and degree four in \( \alpha_3 \). Taking other sequences of residues also result in degree ten, twelve, or sixteen polynomials.

As \( P^{(4)}_T(\alpha_0, \alpha_1, \alpha_2, \alpha_3) \) has degree ten, \( y^2 - P^{(4)}_T(\alpha_0, \alpha_1, \alpha_2, \alpha_3) = 0 \) cannot be embedded in \( \mathbb{WP}^{1,1,1,1} \). It can be embedded in weighted projective space \( \mathbb{WP}^{1,1,1,1} \), but this does not satisfy the Calabi-Yau condition. We currently know of no way to embed this variety in a weighted projective space so that it satisfies the Calabi-Yau condition.
The four-loop wheel. The four-loop scalar wheel (or 'window') integral, $\mathfrak{W}^{(4)}$, may be drawn in momentum space and dual-momentum space as

\[
\mathfrak{W}^{(4)} = \int d^4 x_A d^4 x_B d^4 x_C d^4 x_D \frac{(a_1|a_2)(b_1|b_2)(c_1|c_2)(d_1|d_2)}{(D|A)(A|a_1)(A|a_2)(A|B)(B|b_1)(B|b_2)(B|C)(C|c_1)(C|c_2)(C|D)(D|d_1)(D|d_2)},
\]

where in the last line we have written the integral explicitly in dual-momentum space.

We derive a manifestly dual-conformally invariant integral representation of the four-loop wheel integral in general kinematics in appendix D, finding

\[
\mathfrak{W}^{(4)} = \int_0^{\infty} d\alpha \, d\beta \, d\gamma \, d\delta \frac{n_0}{f_1 f_2 f_3} \left( \frac{n_1}{f_2} + \frac{n_2}{f_3} \right).
\]

The expressions for $n_0, n_1, n_2, f_1, f_2,$ and $f_3$ are lengthy, but are given in Mathematica format in the supplementary material integrands_and_varieties.m.

Unfortunately, this expression is a nine-fold integral, while considerations of transcendental weight suggest that it should be possible to write down an eight-fold representation. This has direct consequences for the validity of our residue analysis. In particular, it means that we cannot directly associate the number of remaining integration parameters after taking a maximum number of residues with the dimension of an irreducible geometry. With this proviso in mind, we can take residues in $1, 1, 1, 2,$ and $2$, leaving a quartic with no repeated roots in five (non-projective) variables. This means that the geometry is at most a fivefold hypersurface, but could be of lower dimension. Without an eight-fold integral representation, we cannot distinguish these possibilities.

This integral has several limits with applications to integrable theories, which would make it particularly interesting to compute. We discuss these limits (some of which are polylogarithmic), as well as a nine-parameter toy model similar to the three-loop toy model (3.24), in appendix D.1.

Further directions. There are many open questions regarding the types of varieties that appear in Feynman integrals. While an increasingly large number of examples have now been identified to be Calabi-Yau, it remains unclear whether all such varieties have this property (and what this tells us about Feynman integrals in general).\footnote{The Calabi-Yau condition in the embedding we are considering restricts the degree of the defining polynomial; since we can deprojectivize and reprojectivize to increase the degree, it is effectively an upper bound. Thus, Calabi-Yaus are the first class one naturally encounters.} In this paper, we have identified two further examples of Calabi-Yaus that can be realized as hypersurfaces in the weighted projective space $\mathbb{P}^{1,\ldots,1,k}$ and have characterized hypersurfaces of this type in a number of ways. However, it again remains unclear how universal this property
might be, and what it encodes about these specific Feynman graphs. To better connect
the properties of these varieties to the physics encoded in Feynman diagrams, it may prove
necessary to move to a differential equation approach [53, 70, 92, 93, 115].

There remains a great deal of technology to be developed before the integrals that
we consider might be ‘computed’. It should be possible, for instance, to develop special
functions analogous to the elliptic multiple polylogarithms [41, 48, 51, 52, 54, 56], in terms
of which these integrals could be evaluated. In particular, a coaction of the type that has
proven useful in the polylogarithmic [9, 31, 33, 34] and elliptic cases [54] should also exist for
such functions [116]. It should also be possible to develop iterated integral representations
involving the relevant Calabi-Yau geometries, akin to what has been done for instance in
refs. [41, 59]. Developing a better understanding of these spaces of functions is sure to lead
to new surprises and simplifications, as has happened in the case of polylogarithmic and
elliptic Feynman integrals over the last few years.

Acknowledgments

We are grateful to Chuck Doran and Pierre Vanhove for useful discussions, and to Philip
Candelas and Yinan Wang for involvement in earlier stages of this work. We are also
indebted to insightful comments from Gregory Korchemsky about the relevance of \( \mathcal{W}^{(4)} \)
to the conformal fishnet theory, and to Miguel Paulos for discussions about Feynman
parametrization and for encouraging us in particular to find a conformal parametric rep-
resentation of \( \mathcal{W}^{(4)} \). This work was supported in part by the Danish Independent Re-
search Fund under grant number DFF-4002-00037 (MV, MW), the Danish National Re-
search Foundation (DNRF91), the research grant 00015369 from Villum Fonden, a Starting
Grant (No. 757978) from the European Research Council (JLB, AJM, MV, MvH, MW), the
European Union’s Horizon 2020 research and innovation program under grant agreement
No. 793151 (MvH), a Carlsberg Postdoctoral Fellowship (CF18-0641) (AJM), and the re-
search grant 00025445 from Villum Fonden (MW). Finally, JLB, AJM and MvH are grateful
for the hospitality of the Aspen Center for Physics, which is supported by National Science
Foundation grant PHY-1607611.

A Desingularization by complex structure deformation

The varieties we encounter when doing Feynman integrals are typically singular; they
may have singularities at fixed points in the Feynman parameters or at points which vary
with the external kinematics. To define a smooth variety, we deform the polynomial(s)
that define the variety. In practice, this amounts to adding new monomials and changing
the values of the coefficients already present. Such deformations turn out to be complex
structure deformations.

One may worry that, even after performing such deformations, we do not obtain a
smooth variety. At this point, we may invoke the Bertini theorem (see for example ref. [94]
for a textbook presentation).
Theorem 1 (Bertini) Given a compact complex manifold $X$ and a holomorphic line bundle $L$ over $X$ such that at every point $x \in X$ the line bundle $L$ has at least one non-zero section, then the points where a generic section $f$ of $L$ vanishes define a smooth hypersurface $M = f^{-1}(0)$.

One way we can apply this theorem is to take the embedding space to be $\mathbb{P}^n$, and $L$ to be a holomorphic line bundle whose sections are homogeneous polynomials of degree $d$. Then the Bertini theorem assures us that for a generic section $f$ of $L$, i.e. for almost every choice of values for the coefficients of a homogeneous degree $d$ polynomial, the variety defined by $\{ x \in \mathbb{P}^n \mid f(x) = 0 \}$ is smooth.

In the following, we will apply reasoning analogous to the Bertini theorem to embeddings in a weighted projective space of type $\mathbb{W}_{1,\ldots,1}^n$. Strictly speaking, the conditions of the Bertini theorem are not satisfied since the embedding space itself has a singularity. If the singularity were to have dimension one or larger, then it would generically intersect any hypersurface, and the hypersurface would inherit the singularity.

However, in the case of $\mathbb{W}_{1,\ldots,1}^n$, the singularity arises at just the point with homogeneous coordinates $(0,\ldots,0,1)$. As a result, in the neighborhood of this point we need to make the identifications

$$ (x_1,\ldots,x_k,1) \simeq (\xi x_1,\ldots,\xi x_k,1), \quad (A.1) $$

where $\xi$ is a $k$-th root of unity. Since the singularity arises at only a single point, a codimension-one hypersurface will not generically contain it. (Moreover, we can explicitly check to see if this happens). In fact, even if our variety contains this singularity, we may define a resolution and compute its Euler characteristic using for example eq. (5.1.14) of ref. [94].

B Hodge numbers and Euler characteristic

B.1 Euler characteristic

One way to compute the Euler characteristic is to integrate the top Chern class over the manifold. We may obtain the Chern classes of an embedded hypersurface from the Chern classes of the embedding manifold and some data about the embedding. There are several good presentations of this material in the literature (see for example refs. [94, 117]), so we will be brief.

Given a bundle $E$, the total Chern class $c(E)$ is the sum of all Chern classes of all degrees. Given an exact sequence of bundles $0 \to A \to B \to C \to 0$, we have $c(B) = c(A) \wedge c(C)$. Using this fact, we conclude that the Chern class of a weighted projective space with weights $(w_0,\ldots,w_n)$ is

$$ c(\mathbb{W}_{w_0,\ldots,w_n}^n) = \prod_{i=0}^{n}(1 + w_i J), \quad (B.1) $$

where $J = c_1(\mathcal{O}(1))$ is the first Chern class of the bundle $\mathcal{O}(1)$ whose sections are polynomials of homogeneity one. Depending on the weights $w_i$, this bundle may not exist as
a holomorphic bundle on \( \mathbb{P}^{w_0, \ldots, w_n} \), but can nevertheless be used as a building block for other bundles.

We can define a codimension-\( m \) variety \( Y \) as the vanishing locus of \( m \) homogeneous polynomials of degrees \( d_i \), for \( i = 1, \ldots, m \). Then, the Chern class of \( Y \) is

\[
c(Y) = \frac{\prod_{i=0}^n (1 + w_i J)}{\prod_{r=1}^m (1 + d_r J)}.
\]

In this case, the Calabi-Yau condition reads

\[
\sum_{i=0}^n w_i = \sum_{r=1}^m d_r.
\]

Then the Euler characteristic is

\[
\chi(Y_{n-m}) = \int_Y c_{n-m} = \prod_{r=1}^m d_r \int_{\mathbb{P}^{w_0, \ldots, w_n}} c_{n-m} J^m,
\]

where we have extended the integral from \( Y \) to the full \( \mathbb{P}^{w_0, \ldots, w_n} \) by wedging with a form that encodes the contribution of the normal.

For our explicit examples of a codimension-one variety \( X \) in \( \mathbb{P}^{1, \ldots, 1, k} \), we have the Chern class

\[
c(X) = \frac{(1 + J)^k (1 + k J)}{1 + 2k J},
\]

while the Euler characteristic is

\[
\chi(X_{k-1}) = \int_X c_{k-1}(X_{k-1}) = \int_{\mathbb{P}^{1, \ldots, 1, k}} 2k J \wedge c_{k-1}(X_{k-1}).
\]

The final piece of information we need is \( \int_{\mathbb{P}^{1, \ldots, 1, k}} J^k = \frac{1}{k} \) because it corresponds to the intersection of \( k \) hyperplanes at the singular point \((0, \ldots, 0, 1)\), which has a cyclic singularity of order \( k \).

Using this normalization, and the expression for \( c_{k-1} \) obtained by expanding the ratio of polynomials in \( J \),

\[
c_{k-1}(X_{k-1}) = \frac{1}{4k} \left( 1 - (1 - 2k)^k + 2k^2 \right) J^{k-1},
\]

we eventually find

\[
\chi(X_{k-1}) = \frac{1 - (1 - 2k)^k + 2k^2}{2k}.
\]

We have tabulated the Euler characteristic for the first few values of \( k \) in table 1.
B.2 Index theorems

We can also compute further combinations of Hodge numbers as a cross-check using various index theorems. In particular, we have

\[
\chi(X_{k-1}) = \sum_r (-1)^r \dim H^r_{dR}(X) = \int_X c_{k-1}(X_{k-1}),
\]

\[
\chi_h(X_{k-1}) = \sum_q (-1)^q \dim H^{0,q}_\delta(X_{k-1}) = \int_X t d_{k-1}(X_{k-1}),
\]

\[
\tau_H(X_{k-1}) = \sum_{p,q} (-1)^q \dim H^{p\geq q}_\delta(X_{k-1}) = \int_X L_{k-1}(X_{k-1}),
\]

where \(\chi_h\) is the arithmetic genus and \(\tau_H\) is the Hirzebruch signature. Also, \(td\) is the Todd class and \(L\) is the Hirzebruch polynomial. We present just the final answers for these computations:

- For \(k = 3\):
  \(\chi_h = 2\), \(\tau_H = -16\).

- For \(k = 4\):
  \(\chi_h = 0\), \(\tau_H = 0\).

- For \(k = 5\):
  \(\chi_h = 2\), \(\tau_H = 2002\).

The reader can easily check that these values are consistent with the Hodge diamonds presented in section 2.

B.3 Lefschetz hyperplane theorem

The cohomology of a hypersurface is strongly constrained by the cohomology of the embedding space. The Lefschetz-Bott theorem characterizes the connections between these cohomology groups. We follow the presentations in ref. [94] (see theorem 1.4 on page 44).

In the Lefschetz-Bott theorem, we are given a complex compact manifold \(X\) of dimension \(n + 1\) and a positive line bundle \(L\) over \(X\). Then, given a holomorphic section \(\lambda\), we denote by \(\lambda^{-1}(0)\) the points of \(X\) where \(\lambda\) vanishes. We then have\(^{10}\)

\[
H_q(\lambda^{-1}(0), \mathbb{Z}) \cong H_q(X, \mathbb{Z}), \quad q \neq n,
\]

\[
H_n(\lambda^{-1}(0), \mathbb{Z}) \rightarrow H_n(X, \mathbb{Z}),
\]

where the last map is surjective. Dualizing to cohomology and using the Hodge decomposition (and the fact that \((p, q)\)-forms pull back to \((p, q)\)-forms), we obtain the result for cohomology. We can also use the Lefschetz-Bott theorem to constrain the cohomology of complete intersections in projective spaces, by repeated application of the theorem.

Stated concretely, equations (B.15) and (B.16) tell us that the upper and lower rows of the Hodge diamonds that describe our Calabi-Yau hypersurfaces are inherited directly from \(\mathbb{P}^{1,\ldots,1,k}\), while its middle row can involve numbers greater than or equal to those describing \(\mathbb{P}^{1,\ldots,1,k}\). Interestingly, this means the Hodge numbers of these hypersurfaces

\(^{10}\) In fact, the result is more general and holds for homotopy groups. The version for homology is listed as a corollary, presumably by an application of the Hurewicz theorem.
could also arise from a codimension-one embedding in unweighted projective space, which has Hodge numbers \( h^{p,q}(\mathbb{P}^k) = \delta_{p,q} \). (We do not, however, know how to realize our Calabi-Yau hypersurfaces as embeddings in unweighted projective space.)

C  Feynman parametrization of the three-loop wheel

In this appendix, we describe the concrete steps by which the three-loop wheel

\[
\mathcal{W}^{(3)} \iff \quad \text{(C.1)}
\]

defined in eq. (3.7) and discussed at length in section 3.3, can be expressed as a rational and manifestly conformal integral. This form was quoted in eq. (3.8).

Provided only a mild degree of cleverness, it is not hard to Feynman-parametrize and integrate each of the loop variables. This is especially true for (any choice of) the first two integrations, which are easily seen to be conformal box integrals. Let us briefly review the mechanics of how those integrals may be performed before applying these techniques to the integral in question.

Review: conformal box integrals in the embedding formalism. For the sake of reference and for those readers less familiar with the embedding formalism, let us recall that the box integral

\[
\int d^4 \xi \frac{1}{(\ell | x_1)(\ell | x_2)(\ell | x_3)(\ell | x_4)}
\]

(C.2)

can be Feynman-parametrized by introducing

\[
| \mathcal{Y} | := \alpha_1 | x_1 | + \alpha_2 | x_2 | + \alpha_3 | x_3 | + \alpha_4 | x_4 |
\]

(C.3)

so that the second Symanzik polynomial \( \mathcal{F} \) may be written as

\[
\mathcal{F} = \sum_{i \leq j} \alpha_i \alpha_j (x_i | x_j) = \frac{1}{2} (| \mathcal{Y} | | \mathcal{Y} | - (| \mathcal{Y} |)^2),
\]

(C.4)

upon which the Feynman integral (C.2) becomes

\[
\int d^4 \xi \frac{1}{(\ell | x_1)(\ell | x_2)(\ell | x_3)(\ell | x_4)} \propto \int_0^\infty [d^k \vec{\alpha}] \frac{1}{(| \mathcal{Y} |)^2}.
\]

(C.5)

Above, we have used the notation \([d^k \vec{\alpha}]\) to denote the volume form on \( \mathbb{P}^k \) as expressed in terms of homogeneous coordinates \((\alpha_1, \alpha_2, \ldots, \alpha_k+1)\). Specifically,

\[
[d^k \vec{\alpha}] := d\alpha_1 \cdots d\alpha_k+1 \delta(\alpha_i - 1)
\]

(C.6)
for any $\alpha_i$. The attentive reader will notice that Feynman’s own de-projectivization prescription, $da_1 \cdots da_{k+1} \delta(\sum_j \alpha_j - 1)$, is related to that in eq. (C.6) by a change of variables with unit Jacobian and which preserves the domain of integration, $\alpha_j \in [0, \infty]$.

Provided that there is at least one point $[a_i]$ such that $(a_i|a_i) = 0$, then $\langle \mathcal{Y} | \mathcal{Y} \rangle$ will be linear in its Feynman parameter $\alpha_i$. When this happens, this Feynman parameter can be trivially integrated rationally. If the reader will forgive us for being somewhat pedantic, suppose that $|\mathcal{Y}\rangle$ may be written of the form

$$|\mathcal{Y}\rangle = |\mathcal{Q}\rangle + \eta |q\rangle$$

for any $|q\rangle$ such that $(q|q) = 0$ and for any $\eta \in \{\alpha_1, \ldots\}$; then

$$\langle \mathcal{Y} | \mathcal{Y} \rangle = (\mathcal{Q} | \mathcal{Q} \rangle + \eta (\mathcal{Q} | q \rangle),$$

and

$$\int_{0}^{\infty} [d^2 \vec{\alpha}] \frac{1}{\langle \mathcal{Y} | \mathcal{Y} \rangle^2} = \int_{0}^{\infty} [d^2 \vec{\alpha}] \int_{0}^{\infty} [d\eta] \frac{1}{[\mathcal{Q} | \mathcal{Q} \rangle + \eta (\mathcal{Q} | q \rangle)]^2} = \int_{0}^{\infty} [d^2 \vec{\alpha}] \frac{1}{(\mathcal{Q} | \mathcal{Q} \rangle) (\mathcal{Q} | q \rangle).}$$

The Feynman parametrization of the three-loop wheel integral follows directly from iteration of the above steps (with only mild cleverness at the end).

**The Feynman parametrization of the wheel integral $\mathcal{W}^{(3)}$.** Let us begin with the (dual-momentum-)space-time definition of the wheel:

$$\mathcal{W}^{(3)} := \int [d^4 x_A d^4 x_B d^4 x_C (a_1 | a_2 ) (b_1 | b_2 ) (c_1 | c_2 ) (A | C ) (A | a_1 ) (A | a_2 ) (A | B ) (B | b_1 ) (B | b_2 ) (B | C ) (C | c_1 ) (C | c_2 ).$$

We have used embedding-formalism-motivated notation to denote the squared-differences of points in dual-momentum space — i.e., $(a_1 | a_2 ) := (\vec{a}_1 - \vec{a}_2)^2$. Notice that all the points in dual-momentum space appearing in eq. (C.10) — both those being integrated and those defining the external kinematics — satisfy $\langle x | x \rangle = 0$.

Let us begin with the integration over the loop momentum $x_A$. It is not hard to see that this part of the integral is trivially identical to the box integral just discussed. Thus, we may introduce

$$|\mathcal{Y}_A\rangle := \alpha_1 |a_1 \rangle + \alpha_2 |a_2 \rangle + \alpha_3 |C \rangle + \eta_A |B \rangle =: |\mathcal{Q}_A \rangle + \eta_A |B \rangle$$

and perform the integral over $x_A$ and $\eta_A$ to arrive at

$$\mathcal{W}^{(3)} := \int [d^2 \vec{\alpha}] \int (\mathcal{Q}_A | \mathcal{Q}_A \rangle (B | \mathcal{Q}_A \rangle (B | b_1 \rangle (B | b_2 \rangle (B | C \rangle (C | c_1 \rangle (C | c_2 \rangle)$.

Now, as with $x_A$, the integral over $x_B$ in eq. (C.12) is just an ordinary conformal box integral. The only minor novelty is that one of the ‘propagators’ of this integral, $(B | \mathcal{Q}_A \rangle$, involves a ‘non-simple’ point in embedding space — one for which $(\mathcal{Q}_A | \mathcal{Q}_A \rangle \neq 0$. This does not actually cause any trouble, however, because the Symanzik formalism defining
the inner product (\( \langle \cdot|\cdot \rangle \)) in eq. (C.4) did not require the points to be simple. (The simplicity of the external points only played a role in making it trivial to integrate out one Feynman parameter rationally.) Thus, we may introduce

\[
|Y_B| := \beta_1|b_1| + \beta_2|b_2| + \beta_3|Q_A| + \eta_B|C| =: |Q_B| + \eta_B|C|
\]  
(C.13)
and integrate over \( x_B \) and \( \eta_B \) to arrive at

\[
\mathfrak{M}^{(3)} = \int_{0}^{\infty} \left[ d^2\alpha \right] \left[ d^2\beta \right] \int_{(C.1)} \frac{d^4x_C}{(Q_A \uparrow Q_A)(Q_B \uparrow Q_B)(C|Q_B)(C|C|)(C|C_2)}.
\]  
(C.14)

The careful reader should now be mildly worried as the integral over \( x_C \) in eq. (C.14) is not at all a recognizable (box) integral. Even worse: it is not even manifestly conformal in \( x_C \). To appreciate the magnitude of this problem, notice that the factor \( (Q_A|Q_A) \) in the denominator of eq. (C.14) involves a sum of terms with different conformal weights:

\[
(Q_A \uparrow Q_A) = \alpha_1\alpha_2(a_1|a_2) + \alpha_1\alpha_3(C|a_1) + \alpha_2\alpha_3(C|a_2).
\]  
(C.15)

Restoring conformality of this term turns out to be relatively easy. Consider rescaling the Feynman parameters \( \alpha_i \) according to

\[
\alpha_1 \mapsto \alpha_1(C|a_2), \quad \alpha_2 \mapsto \alpha_2(C|a_1), \quad \alpha_3 \mapsto (a_1|a_2).
\]  
(C.16)

Notice that we are actually eliminating the projective redundancy of \( \{ d^2\alpha \} \) by fixing \( \alpha_3 \mapsto (a_1|a_2) \). (This is just done for notational compactness going forward.)

Under this rescaling,

\[
(Q_A \uparrow Q_A) \xrightarrow{(C.16)} (a_1|a_2)(C|a_1)(C|a_2)(\alpha_1 + \alpha_2 + \alpha_1\alpha_2).
\]  
(C.17)

The prefactor of eq. (C.17) cancels precisely against the Jacobian from eq. (C.16), resulting in

\[
\mathfrak{M}^{(3)} \xrightarrow{(C.16)} \int_{0}^{\infty} \left[ d^2\alpha \right] \left[ d^2\beta \right] \int_{(C.1)} \frac{d^4x_C}{(\alpha_1 + \alpha_2 + \alpha_1\alpha_2)(Q_B \uparrow Q_B)(C|Q_B)(C|C_1)(C|C_2)}.
\]  
(C.18)

We have certainly improved the situation with respect to the \( x_C \) integration, but not entirely. Notice, for example, that under the rescaling (C.16), \( (Q_B|Q_B) \) becomes an irreducible (and inhomogeneous!) degree-two polynomial in \( |C| \). (This is trivial to see, considering eq. (C.17), and \( (Q_B|Q_B) = (Q_A|Q_A) + \ldots \))

In fact, this problem can be remedied without too much hassle. Upon rescaling the \( \beta_i \)'s according to

\[
\beta_1 \mapsto \beta_1\frac{(C|a_1)(a_1|a_2)}{(a_1|b_1)}, \quad \beta_2 \mapsto \beta_2\frac{(C|a_1)(a_1|a_2)}{(a_1|b_2)}, \quad \beta_3 \mapsto 1,
\]  
(C.19)

We hope the reader can forgive the abuse of notation in using the same variables \( \alpha_i \) to label the integration parameters before and after the rescaling.
and taking into account the corresponding Jacobian, the reader may verify that eq. (C.18) takes the form

\[ \mathcal{M}^{(3)} \rightarrow \infty \int_0^{\infty} d^2\alpha \, d^2\beta \int d^4x_C \, \frac{(a_1|a_2)^2(b_1|b_2)(c_1|c_2)/(a_1|b_1)}{(a_1 + a_2 + \alpha_1\alpha_2)(C|R)(C|S)(C|c_1)(C|c_2)}, \]  

(C.20)

where we have defined the ‘propagators’ \((C|R), (C|S)\) according to

\[ |R| := |a_2|(\alpha_1 + \alpha_2) + |b_1|\beta_1 \frac{a_1|a_2}{a_1|b_1} + |b_2|\beta_2 \frac{a_1|a_2}{a_1|b_2}, \]

\[ |S| := |R|(a_1|b_2) + |a_1| \left[ \alpha_2\beta_1 \frac{a_1|b_2}{a_1|b_1} + \alpha_2\beta_2 a_2|b_2 + \beta_1\beta_2 \frac{a_1|a_2}{a_1|b_1} \right] + |a_2| \left[ \alpha_1(\alpha_2 + \beta_1 + \beta_2)(a_1|b_2) \right]. \]

(C.21)

Although these new propagators are not especially simple, we may now observe that eq. (C.20) is a standard conformal box integral with respect to \(x_C(1)\). As such, our discussion above can be immediately applied. We merely introduce

\[ |Y(C)| := \gamma_1|c_1| + \gamma_2|\mathcal{R}| + \gamma_3|\mathcal{S}| + \eta_C|c_2| =: |Q_C| + \eta_C|c_2|, \]

(C.22)

and integrate over \(x_C\) and \(\eta_C\) to find

\[ \mathcal{M}^{(3)} = \int_0^{\infty} d^2\alpha \, d^2\beta \int d^3\gamma \, \frac{(a_1|a_2)^2(b_1|b_2)(c_1|c_2)/(a_1|b_1)}{(\alpha_1 + \alpha_2 + \alpha_1\alpha_2)(Q_C|c_2)(Q_C|Q_C)}. \]

(C.23)

We are essentially done. However, the representation (C.23) is still not manifestly conformal in the external points. This can be quickly remedied. All we need to do is rescale the \(\gamma_i\) Feynman parameters so that \(|Q_C|\) in eq. (C.22) becomes uniform in weight. This can be achieved by rescaling them according to

\[ \gamma_1 \mapsto \gamma_1 \frac{(a_1|a_2)(a_2|b_2)}{(a_2|c_1)}, \quad \gamma_2 \mapsto \gamma_2(a_1|b_2), \quad \gamma_3 \mapsto 1. \]

(C.24)

Upon including the Jacobian, gathering terms, and some minor simplifications, we obtain the formula quoted in eq. (3.8) — namely, eq. (C.23) becomes

\[ \mathcal{M}^{(3)} \rightarrow \infty \int_0^{\infty} d^2\alpha \, d^2\beta \, d^3\gamma \, \frac{n_0}{f_1 f_2 f_3}, \]

(C.25)

where

\[ n_0 := v_1(u_1 u_2 u_3 v_1 v_2 v_3), \]

\[ f_1 := \alpha_1 + \alpha_2 + \alpha_1\alpha_2, \]

\[ f_2 := \alpha_1(1 + \alpha_2 + \beta_1 + \beta_2 + \gamma_2) + \alpha_2(1 + u_1 w_2 w_3 \beta_1 + \beta_2) + \gamma_2 \]

\[ + \beta_1 v_1(1 + u_1 u_2 u_3 w_2 \beta_2 + \gamma_2) + u_2 v_1(u_2 v_1 \gamma_1 + \beta_2(1 + \gamma_2)), \]

\[ f_3 := (1 + \alpha_2 + \beta_1 + \beta_2 + \gamma_2) \left[ \alpha_1(\gamma_1 + \beta_2(1 + \alpha_2 + u_3 v_1 v_2 \beta_1 + \gamma_2) + u_3 \beta_1(1 + \alpha_2 + \gamma_2)) \right] + \gamma_1 \left[ \alpha_2(1 + u_1 w_3 \beta_1 + \beta_2 + \gamma_2) \right] \]

\[ + u_3 v_1(u_2 w_1 \beta_2(1 + \gamma_2) + \beta_1(1 + u_1 v_2 \beta_2 + \gamma_2)). \]

(C.26)
expressed in terms of the basis of dual-conformal invariant cross-ratios

\[ \begin{align*}
u_1 &= (c_1 a_1; a_2 b_2), & u_2 &= (a_1 b_1; b_2 c_2), & u_3 &= (b_1 c_1; c_2 a_2), \\
v_1 &= (a_1 a_2; b_1 c_2), & v_2 &= (b_1 b_2; c_1 a_2), & v_3 &= (c_1 c_2; a_1 a_2), \\
w_1 &= (b_2 c_1; c_2 b_1), & w_2 &= (c_2 a_1; a_2 c_1), & w_3 &= (a_2 b_1; b_2 a_1). \end{align*} \]  
(C.27)

Recall that these are defined according to

\[ (x y; z w) := \frac{(x y)(z w)}{(x z)(y w)}. \]  
(C.28)

Although there appeared to be some magic in the Feynman-parametric rescaling in eq. (C.19) — which restored not only conformality in the \( xC \) integration, but also its manifest linearity in each factor of the denominator of eq. (C.20) — this magic in some sense ‘had to work’. Indeed, Miguel Paulos has shown [118] that all dual-conformal Feynman integrals whose dual-graphs involve internal loop momenta connected via trees are always possible to compute conformally by integrating one loop at a time (as described in ref. [79]) and rescaling Feynman parameters accordingly. His proof extends also to integrals whose dual graphs are free of four-cycles — and hence, his argument also applies to \( \mathbb{W}^{(3)} \). Nevertheless, the existence of four-cycles in the dual graph (as will be the case for \( \mathbb{W}^{(4)} \) discussed below) prevent this line of reasoning from being applied. As such, it is natural to wonder if there is any obstruction to the magic found in the rescaling (C.19) when considered in the context of a four (or higher-)loop wheel.

D  Feynman parametrization of the four-loop wheel

Similarly to three loops, the four-loop wheel (also known as the ‘window’ integral) can be defined in dual-momentum space as

\[ \mathbb{W}^{(4)} := \int d^4 x_A d^4 x_B d^4 x_C d^4 x_D \quad (a_1 a_2)(b_1 b_2)(c_1 c_2)(d_1 d_2) \quad (D | A)(A | a_1)(A | a_2)(A | B)(B | b_1)(B | b_2)(B | C)(C | c_1)(C | c_2)(C | D)(D | d_1)(D | d_2). \]  
(D.1)

As before, sequentially introducing Feynman parameters will proceed semi-trivially until the last step as each integral is a standard, conformal box integral. Thus, we may save ourselves some of the pedantry of the previous discussion and cut to the chase — to the non-trivial steps at the end.

To integrate over the first three loop momenta, \( x_A, x_B, x_C \) in eq. (D.1), we introduce Feynman parameters according to

\[ \begin{align*} |Y_A| &:= \alpha_1 |a_1| + \alpha_2 |a_2| + \alpha_3 |D| + \eta_A |B| := |Q_A| + \eta_A |B|, \\
|Y_B| &:= \beta_1 |b_1| + \beta_2 |b_2| + \beta_3 |Q_A| + \eta_B |C| := |Q_B| + \eta_B |C|, \\
|Y_C| &:= \gamma_1 |c_1| + \gamma_2 |c_2| + \gamma_3 |Q_B| + \eta_C |D| := |Q_C| + \eta_C |D|. \end{align*} \]  
(D.2)

and integrate over the Feynman parameters \( \eta_A, \eta_B, \eta_C \) to arrive at

\[ \mathbb{W}^{(4)} = \int_0^\infty [d^2 \alpha] [d^2 \beta] [d^2 \gamma] \int d^4 x_D \quad (a_1 a_2)(b_1 b_2)(c_1 c_2)(d_1 d_2) \quad (Q_A | Q_A)(Q_B | Q_B)(Q_C | Q_C)(D | Q_C)(D | d_1)(D | d_2). \]  
(D.3)
As was the case with three loops, we now find an obstruction in the last loop integration of eq. (D.3), as it is far from manifestly conformal.

(To reiterate a point made above, we should be clear that mere conformality is not sufficient for us to Feynman parametrize and do the loop integrations. For example, consider an integral of the form

$$\int d^4 x_\ell \frac{1}{(\ell|a)(\ell|b)(\ell|c)(\ell|d) + (\ell|e)(\ell|f)}.$$

We know of no method by which such integrals can be systematically integrated.\(^{12}\) In this work, we take a much more conservative approach, and demand that integrands be brought to the form such that their (loop-dependent) denominators are built directly as products of propagators.)

Somewhat surprisingly, it turns out to be fairly straightforward to bring eq. (D.3) into a recognizable form by a sequence of rescalings as done for three loops. In particular, if we rescale (and eliminate the projective redundancy of) the Feynman parameters according to\(^{13}\)

\[
\begin{align*}
&\alpha_1 \mapsto \alpha_1(D|a_2), & &\alpha_2 \mapsto \alpha_2(D|a_1), & &\alpha_3 \mapsto 1 \times (a_1|a_2), \\
&\beta_1 \mapsto \beta_1 \frac{(D|a_1)(a_1|a_2)}{(a_1|b_1)}, & &\beta_2 \mapsto \beta_2 \frac{(D|a_1)(a_1|a_2)}{(a_1|b_2)}, & &\beta_3 \mapsto 1, \\
&\gamma_1 \mapsto \gamma_1 \frac{(D|a_1)(a_1|a_2)(b_1|b_2)}{(a_1|b_1)(b_1|c_1)}, & &\gamma_2 \mapsto \gamma_2 \frac{(D|a_1)(a_1|a_2)(b_1|b_2)}{(a_1|b_1)(b_1|c_2)}, & &\gamma_3 \mapsto 1,
\end{align*}
\]

then the integral (D.3) becomes

\[
\mathcal{W}^{(4)}(D.5) \to \int_0^\infty d^2 \alpha d^2 \beta d^2 \gamma \int d^4 x_D \frac{\kappa (D|a_1)}{(1 + \alpha_2 + \alpha_1 \alpha_2)(D|R)(D|S)(D|T)(D|d_1)(D|d_2)},
\]

where the prefactor in the numerator is

\[
\kappa := \frac{(a_1|a_2)^3(b_1|b_2)^3(c_1|c_2)(d_1|d_2)}{(a_1|b_1)^2(a_1|b_2)^2(b_1|c_1)(b_1|c_2)}.
\]

which arises from the various Jacobians. Moreover, the new `propagators' are

\[
\begin{align*}
|R| &:= |a_1| \left[ \alpha_2 \beta_1 \frac{(a_2|b_1)}{(a_1|b_1)} + \alpha_2 \beta_2 \frac{(a_2|b_2)}{(a_1|b_2)} + \beta_1 \beta_2 \frac{(a_1|a_2)(b_1|b_2)}{(a_1|b_1)(a_1|b_2)} \right] \\
&\quad + |a_2| \left[ \alpha_1 (1 + \alpha_2 + \beta_1 + \beta_2) + \alpha_2 + U \right], \\
|S| &:= |a_2|(\alpha_1 + \alpha_2) + U + V, \\
|T| &:= |S| + |a_1| f_T + |a_2| \alpha_1 \left[ \alpha_2 + \beta_1 + \beta_2 + \gamma_1 \frac{(a_1|c_1)(b_1|b_2)}{(a_1|b_1)(b_1|c_1)} + \gamma_2 \frac{(a_1|c_2)(b_1|b_2)}{(a_1|b_1)(b_1|c_2)} \right],
\end{align*}
\]

\(^{12}\)Integrand such as (D.4) arise in the context of all-loop recursion relations [119], and it would be incredibly interesting to develop methods for these integrations.

\(^{13}\)A more symmetrical choice of rescalings — one which treats the \(\gamma_i\)'s more similarly to the \(\beta_i\)'s — would have worked. We have chosen the somewhat unbalanced set of rescalings in order to maximize the number of smoothly accessible toy-model-like limits.
in terms of
\[
\mathcal{U} := |b_1\rangle \beta_1 \frac{(a_1|a_2)}{(a_1|b_1)} + |b_2\rangle \beta_2 \frac{(a_1|a_2)}{(a_1|b_2)} ,
\]
\[
\mathcal{V} := |c_1\rangle \gamma_1 \frac{(a_1|a_2)(b_1|b_2)}{(a_1|b_2)(b_1|c_1)} + |c_2\rangle \gamma_2 \frac{(a_1|a_2)(b_1|b_2)}{(a_1|b_1)(b_2|c_2)} ,
\]
and where we have defined the scalar function
\[
f_T := \frac{(a_1|a_2)(b_1|b_2)}{(a_1|b_1)(a_1|b_2)} \left[ \beta_1 \beta_2 + \beta_1 \gamma_1 + \beta_2 \gamma_2 + \alpha_2 \left( \beta_1 \frac{(a_1|b_2)(a_2|b_1)}{(a_1|a_2)(b_1|b_2)} + \beta_2 \frac{(a_1|b_1)(a_2|b_2)}{(a_1|a_2)(b_1|b_2)} + \gamma_1 \frac{(a_1|b_1)(a_2|c_1)}{(a_1|a_2)(b_1|c_1)} + \gamma_2 \frac{(a_1|b_2)(a_2|c_2)}{(a_1|a_2)(b_2|c_2)} \right) \right] .
\]

The integral (D.6) is a conformal integral (with respect to \(x_D\)) which can be done almost as trivially as the box integral. In particular, its Feynman parametrization follows more-or-less trivially from differentiation (with respect to \(\ell\)) of the (Feynman parametrized) box integral. (The interested reader should consult, e.g., ref. [79].)

Feynman parametrization of the integral (D.6) may be done by introducing
\[
\mathcal{W} := \delta_1|d_1\rangle + \delta_2|R\rangle + \delta_3|S\rangle + \delta_4|T\rangle + \eta_D|d_2\rangle \rightarrow |Q_D\rangle + \eta_D|d_2\rangle ,
\]
and integrating over \(x_D\) in the ordinary way. This results in a representation of \(\mathcal{W}^{(4)}\) of the form
\[
\mathcal{W}^{(4)} = \int_0^\infty d^3\bar{q} \, d^3\bar{p} \, d^3\bar{q}
\]
\[
\int_0^\infty d\eta_D \frac{\kappa (\mathcal{W}_D|a_1)}{(\alpha_1 + \alpha_2 + \alpha_1 \alpha_2)(\mathcal{W}_D|\mathcal{W}_D)^3}
\]
\[
= \int_0^\infty d^3\bar{q} \, d^3\bar{p} \, d^3\bar{q}
\]
\[
\int_0^\infty d\eta_D \frac{\kappa ((\mathcal{W}_D|a_1) + \eta_D|d_2|a_1)}{(\alpha_1 + \alpha_2 + \alpha_1 \alpha_2)(\mathcal{W}_D|\mathcal{W}_D) + \eta_D|\mathcal{W}_D|d_2)^3}
\]
\[
= \int_0^\infty d^3\bar{q} \, d^3\bar{p} \, d^3\bar{q}
\]
\[
\frac{\kappa}{2(\alpha_1 + \alpha_2 + \alpha_1 \alpha_2)} \left[ \frac{(d_2|a_2)}{(\mathcal{W}_D|d_2)^2(\mathcal{W}_D|\mathcal{W}_D) + \mathcal{W}_D|\mathcal{W}_D|d_2)^2} \right] .
\]

As before, the only thing we must do to render the expression (D.12) manifestly conformal with respect to the external momenta is to rescale the \(\delta_i\)’s such that \(|Q_D\rangle\) becomes uniform in weight. This is in fact easy, as the reader can easily observe that all of the factors defined in eq. (D.8) scale like \(|a_2\rangle\): as such, the only term in eq. (D.11) which has the wrong scaling weights is the first one. Rescaling as required and eliminating the projective redundancy (now just for consistency with the previous analysis) according to
\[
\delta_1 \mapsto \delta_1 (a_1|a_2)(a_1|d_1) , \quad \delta_4 \mapsto 1 ,
\]
the four-loop wheel takes the form
\[
\mathcal{W}^{(4)} \rightarrow \int_0^\infty d^3\bar{q} \, d^3\bar{p} \, d^3\bar{q}
\]
\[
\frac{n_0}{f_3 f_2 f_3} \left( \frac{n_1}{f_2} + \frac{n_2}{f_3} \right) ,
\]
where \( n_i \)'s and the \( f_i \)'s are all directly expressible in terms of dual-conformally invariant cross-ratios.

We might ask if we could have done better, and found a representation as an eight-fold integral. The difficulty here is in dealing with the final pentagon integral, which we here represent as a three-fold. These integrals can be expanded into boxes, and this would indeed give rise to a two-fold representation. However, writing out this box expansion shows that it contains dilogs which have square-root arguments — and these square roots would involve the other Feynman parameters. As such, while one can indeed write down some two-fold representation, it would not help us to understand its transcendental properties. At present, we know of no way to write the four-loop wheel as a rational eight-fold integral.

D.1 Interesting kinematic limits of the wheel integral \( \mathcal{W}^{(4)} \)

The four-loop wheel integral has several interesting kinematic limits. We discuss them below, and provide expressions for the integral in each of these limits in Mathematica format in the supplementary material `integrands_and_varieties.m`.

The `fishnet` limit of the wheel integral \( \mathcal{W}^{(4)} \). The first limit we consider is the one in which all middle legs are light-like:

\[
(a_2|b_1) = (b_2|c_1) = (c_2|d_1) = (d_2|a_1) = 0. \tag{D.15}
\]

\[
\begin{array}{c}
\text{(D.15)}
\end{array}
\]

Notice that a particular case of this limit — where the `massive` momenta flowing into the corners of the wheel are pairs of massless particles — is itself a particular planar amplitude in the integrable conformal fishnet theory [82–84],

\[
A(\bar{\varphi}_{12}, \bar{\varphi}_{12}, \bar{\varphi}_{13}, \bar{\varphi}_{13}, \bar{\varphi}_{34}, \bar{\varphi}_{34}, \bar{\varphi}_{24}, \bar{\varphi}_{24}) = 24, \tag{D.17}
\]

which is also a particular component amplitude of the 12-point \( N^4 \)MHV scattering amplitude in planar \( \mathcal{N} = 4 \) supersymmetric Yang-Mills theory, \( A^{(4)}_{12} \). This component of the supersymmetric amplitude corresponds to

\[
\int (d\eta_1^1 d\eta_2^1 \cdots d\eta_6^1) (d\eta_1^2 d\eta_{11}^2 \cdots d\eta_6^2) (d\eta_1^3 d\eta_{12}^3 \cdots d\eta_6^3) (d\eta_1^4 d\eta_{13}^4 \cdots d\eta_{12}^4) A^{(4)}_{12}. \tag{D.18}
\]

We also note that in this limit (and hence all those below it), \( n_1 \) of eq. (D.14) vanishes.
A nine-dimensional toy model of the wheel integral $\mathfrak{W}^{(4)}$. This limit is analogous to the toy models discussed in section 3.3 and ref. [80]. In this case, there are several ways to ‘route’ 8 light-like points among the external points. The only one which will be dihedrally invariant is the one defined by the conditions (D.15) and

$$\begin{align*}
(a_1|c_2) &= (a_2|c_1) = (b_1|d_2) = (b_2|d_1) .
\end{align*}$$

(D.19)

In this limit, the integral will depend on the space of kinematics associated with 8 pairwise light-like separated points — a nine-dimensional parameter space. We do not expect this limit to lead to any drop in rigidity.

The Basso-Dixon fishnet integral $I_{2,2}$ as a limit of $\mathfrak{W}^{(4)}$. Another special case of interest is the Basso-Dixon fishnet integral $I_{2,2}$, which contributes to the four-point correlation function in planar $\varphi^4$ theory. This corresponds to taking the limit where the eight dual points defining the wheel integral $\mathfrak{W}^{(4)}$ are pairwise identified according to

$$d_2 = a_1, \quad a_2 = b_1, \quad b_2 = c_1, \quad c_2 = d_1 .$$

(D.21)

Graphically, this corresponds to

$$\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array}{c}
\begin{array{32}{32}}{{32}}}
In this limit, the integral can be seen to contribute to the ‘2-magnon’ 4-point function as drawn on the right-hand part of figure 1 of ref. [121]. At leading order, this four-point function is given by a single Feynman integral: that drawn in eq. (D.24). This function is known to be non-polylogarithmic. Fourier-transformed, it corresponds to the five-loop amoeba integral of ref. [66], which is maximally rigid.

**Open Access.** This article is distributed under the terms of the Creative Commons Attribution License (CC-BY 4.0), which permits any use, distribution and reproduction in any medium, provided the original author(s) and source are credited.

**References**

[1] K.-T. Chen, *Iterated path integrals*, Bull. Amer. Math. Soc. **83** (1977) 831.

[2] A. Goncharov, *Geometry of configurations, polylogarithms and motivic cohomology*, Adv. Math. **114** (1995) 197.

[3] A.B. Goncharov, *Multiple polylogarithms, cyclotomy and modular complexes*, Math. Res. Lett. **5** (1998) 497 [arXiv:1105.2076] [INSPIRE].

[4] E. Remiddi and J.A.M. Vermaseren, *Harmonic polylogarithms*, Int. J. Mod. Phys. A **15** (2000) 725 [hep-ph/9905237] [INSPIRE].

[5] J.M. Borwein, D.M. Bradley, D.J. Broadhurst and P. Lisonek, *Special values of multiple polylogarithms*, Trans. Amer. Math. Soc. **353** (2001) 907 [math.CA/9910045].

[6] S. Moch, P. Uwer and S. Weinzierl, *Nested sums, expansion of transcendental functions and multiscale multiloop integrals*, J. Math. Phys. **43** (2002) 3363 [hep-ph/0110083] [INSPIRE].

[7] A.B. Goncharov, M. Spradlin, C. Vergu and A. Volovich, *Classical polylogarithms for amplitudes and Wilson loops*, Phys. Rev. Lett. **105** (2010) 151605 [arXiv:1006.5703] [INSPIRE].

[8] S. Caron-Huot, *Superconformal symmetry and two-loop amplitudes in planar N = 4 super Yang-Mills*, JHEP **12** (2011) 066 [arXiv:1105.5606] [INSPIRE].

[9] C. Duhr, *Hopf algebras, coproducts and symbols: an application to Higgs boson amplitudes*, JHEP **08** (2012) 043 [arXiv:1203.0454] [INSPIRE].

[10] L.J. Dixon, J.M. Drummond, M. von Hippel and J. Pennington, *Hexagon functions and the three-loop remainder function*, JHEP **12** (2013) 049 [arXiv:1308.2276] [INSPIRE].

[11] L.J. Dixon, J.M. Drummond, C. Duhr and J. Pennington, *The four-loop remainder function and multi-Regge behavior at NNLLA in planar N = 4 super-Yang-Mills theory*, JHEP **06** (2014) 116 [arXiv:1402.3300] [INSPIRE].

[12] L.J. Dixon and M. von Hippel, *Bootstrapping an NMHV amplitude through three loops*, JHEP **10** (2014) 065 [arXiv:1408.1505] [INSPIRE].

[13] J.M. Drummond, G. Papathanasiou and M. Spradlin, *A symbol of uniqueness: the cluster bootstrap for the 3-loop MHV heptagon*, JHEP **03** (2015) 072 [arXiv:1412.3763] [INSPIRE].

[14] L.J. Dixon, M. von Hippel and A.J. McLeod, *The four-loop six-gluon NMHV ratio function*, JHEP **01** (2016) 053 [arXiv:1509.08127] [INSPIRE].

[15] E. Panzer and O. Schnetz, *The Galois coaction on \( \varphi^4 \) periods*, Commun. Num. Theor. Phys. **11** (2017) 657 [arXiv:1603.04289] [INSPIRE].
[16] S. Caron-Huot, L.J. Dixon, A. McLeod and M. von Hippel, *Bootstrapping a five-loop amplitude using Steinmann relations*, Phys. Rev. Lett. 117 (2016) 241601 [arXiv:1609.00069] [inSPIRE].

[17] L.J. Dixon, M. von Hippel, A.J. McLeod and J. Trnka, *Multi-loop positivity of the planar \( \mathcal{N} = 4 \) SYM six-point amplitude*, JHEP 02 (2017) 112 [arXiv:1611.08325] [inSPIRE].

[18] L.J. Dixon, J. Drummond, T. Harrington, A.J. McLeod, G. Papathanasiou and M. Spradlin, *Heptagons from the Steinmann cluster bootstrap*, JHEP 02 (2017) 137 [arXiv:1612.08976] [inSPIRE].

[19] O. Almendi, C. Duhr, E. Gardi, A. McLeod and C.D. White, *Bootstrapping the QCD soft anomalous dimension*, JHEP 09 (2017) 073 [arXiv:1706.10162] [inSPIRE].

[20] O. Schnetz, *The Galois coaction on the electron anomalous magnetic moment*, Commun. Num. Theor. Phys. 12 (2018) 335 [arXiv:1711.05118] [inSPIRE].

[21] S. Caron-Huot, L.J. Dixon, M. von Hippel, A.J. McLeod and G. Papathanasiou, *The double pentaladder integral to all orders*, JHEP 07 (2018) 170 [arXiv:1806.01361] [inSPIRE].

[22] J. Drummond, J. Foster, Ö. Gürgöğan and G. Papathanasiou, *Cluster adjacency and the four-loop NMHV heptagon*, JHEP 03 (2019) 087 [arXiv:1812.04640] [inSPIRE].

[23] V. Del Duca, C. Duhr, F. Dulat and B. Penante, *All two-loop MHV remainder functions in multi-Regge kinematics*, JHEP 01 (2019) 162 [arXiv:1811.10398] [inSPIRE].

[24] S. Abreu, L.J. Dixon, E. Herrmann, B. Page and M. Zeng, *The two-loop five-point amplitude in \( \mathcal{N} = 4 \) super-Yang-Mills theory*, Phys. Rev. Lett. 122 (2019) 121603 [arXiv:1812.08941] [inSPIRE].

[25] D. Chicherin, T. Gehrmann, J.M. Henn, P. Wasser, Y. Zhang and S. Zoia, *Analytic result for a two-loop five-particle amplitude*, Phys. Rev. Lett. 122 (2019) 121602 [arXiv:1812.11057] [inSPIRE].

[26] D. Chicherin, T. Gehrmann, J.M. Henn, P. Wasser, Y. Zhang and S. Zoia, *The two-loop five-particle amplitude in \( \mathcal{N} = 8 \) supergravity*, JHEP 03 (2019) 115 [arXiv:1901.05932] [inSPIRE].

[27] S. Abreu, L.J. Dixon, E. Herrmann, B. Page and M. Zeng, *The two-loop five-point amplitude in \( \mathcal{N} = 8 \) supergravity*, JHEP 03 (2019) 123 [arXiv:1901.08563] [inSPIRE].

[28] S. Caron-Huot, L.J. Dixon, F. Dulat, M. von Hippel, A.J. McLeod and G. Papathanasiou, *Six-gluon amplitudes in planar \( \mathcal{N} = 4 \) super-Yang-Mills theory at six and seven loops*, JHEP 08 (2019) 016 [arXiv:1903.10890] [inSPIRE].

[29] S. Caron-Huot, L.J. Dixon, F. Dulat, M. Von Hippel, A.J. McLeod and G. Papathanasiou, *The cosmic Galois group and extended Steinmann relations for planar \( \mathcal{N} = 4 \) SYM amplitudes*, JHEP 09 (2019) 061 [arXiv:1906.07116] [inSPIRE].

[30] A.B. Goncharov, *Multiple polylogarithms and mixed Tate motives*, math.AG/0103059 [inSPIRE].

[31] A.B. Goncharov, *Galois symmetries of fundamental groupoids and noncommutative geometry*, Duke Math. J. 128 (2005) 209 [math.AG/0208144] [inSPIRE].

[32] F.C.S. Brown, *Multiple zeta values and periods of moduli spaces \( \mathcal{M}_{0,n}(\mathbb{R}) \)*, Annales Sci. École Norm. Sup. 42 (2009) 371 [math.AG/0606419] [inSPIRE].
[33] F. Brown, *On the decomposition of motivic multiple zeta values*, in *Galois-Teichmüller theory and arithmetic geometry*, Mathematical Society of Japan, Tokyo, Japan (2012), pg. 31 [arXiv:1102.1310] [SPIRE].

[34] F. Brown, *Mixed Tate motives over Z*, *Annals Math.* 175 (2012) 949 [arXiv:1102.1312].

[35] M. Deneufchâtel, G.H.E. Duchamp, V.H.N. Minh and A.I. Solomon, *Independence of hyperlogarithms over function fields via algebraic combinatorics*, [arXiv:1101.4497].

[36] C. Duhr, H. Gangl and J.R. Rhodes, *From polygons and symbols to polylogarithmic functions*, *JHEP* 10 (2012) 075 [arXiv:1110.0458] [SPIRE].

[37] O. Schnetz, *Graphical functions and single-valued multiple polylogarithms*, *Commun. Num. Theor. Phys.* 08 (2014) 589 [arXiv:1302.6445] [SPIRE].

[38] S. Bloch and P. Vanhove, *The elliptic dilogarithm for the sunset graph*, *Nucl. Phys.* B 704 (2005) 349 [hep-ph/0406160] [SPIRE].

[39] L. Adams, C. Bogner and S. Weinzierl, *The kite integral to all orders in terms of elliptic polylogarithms*, *J. Math. Phys.* 57 (2016) 122302 [arXiv:1607.01571] [SPIRE].
[51] J. Brödel, C. Duhr, F. Dulat and L. Tancredi, *Elliptic polylogarithms and iterated integrals on elliptic curves. Part I: general formalism*, JHEP 05 (2018) 093 [arXiv:1712.07089] [inSPIRE].

[52] J. Brödel, C. Duhr, F. Dulat and L. Tancredi, *Elliptic polylogarithms and iterated integrals on elliptic curves. Part II: an application to the sunrise integral*, Phys. Rev. D 97 (2018) 116009 [arXiv:1712.07095] [inSPIRE].

[53] L. Adams and S. Weinzierl, *The ε-form of the differential equations for Feynman integrals in the elliptic case*, Phys. Lett. B 781 (2018) 270 [arXiv:1802.05020] [inSPIRE].

[54] J. Brödel, C. Duhr, F. Dulat, B. Penante and L. Tancredi, *Elliptic symbol calculus: from elliptic polylogarithms to iterated integrals of Eisenstein series*, JHEP 08 (2018) 014 [arXiv:1803.10256] [inSPIRE].

[55] L. Adams, E. Chaubey and S. Weinzierl, *Planar double box integral for top pair production with a closed top loop to all orders in the dimensional regularization parameter*, Phys. Rev. Lett. 121 (2018) 142001 [arXiv:1804.11144] [inSPIRE].

[56] J. Brödel, C. Duhr, F. Dulat, B. Penante and L. Tancredi, *Elliptic Feynman integrals and pure functions*, JHEP 05 (2019) 120 [arXiv:1902.09971] [inSPIRE].

[57] J. Brödel, C. Duhr, F. Dulat, R. Marzucca, B. Penante and L. Tancredi, *An analytic solution for the equal-mass banana graph*, JHEP 09 (2019) 112 [arXiv:1907.03787] [inSPIRE].

[58] J.L. Bourjaily, P. Heslop and V.-V. Tran, *Perturbation theory at eight loops: novel structures and the breakdown of manifest conformality in N = 4 supersymmetric Yang-Mills theory*, Phys. Rev. Lett. 116 (2016) 191602 [arXiv:1512.07912] [inSPIRE].

[59] J.L. Bourjaily, E. Herrmann, C. Langer, A.J. McLeod and J. Trnka, *Prescriptive unitarity for non-planar six-particle amplitudes at two loops*, JHEP 12 (2019) 073 [arXiv:1909.09131] [inSPIRE].

[60] F.C.S. Brown, *On the periods of some Feynman integrals*, arXiv:0910.0114 [inSPIRE].

[61] F. Brown and O. Schnetz, *A K3 in φ4*, Duke Math. J. 161 (2012) 1817 [arXiv:1006.4064] [inSPIRE].

[62] J.L. Bourjaily, A.J. McLeod, M. von Hippel and M. Wilhelm, *Bounded collection of Feynman integral Calabi-Yau geometries*, Phys. Rev. Lett. 122 (2019) 031601 [arXiv:1810.07689] [inSPIRE].
[67] J.L. Bourjaily, Y.-H. He, A.J. McLeod, M. Von Hippel and M. Wilhelm, \textit{Traintracks through Calabi-Yau manifolds: scattering amplitudes beyond elliptic polylogarithms}, \textit{Phys. Rev. Lett.} \textbf{121} (2018) 071603 [arXiv:1805.09326] [nSPIRE].

[68] D. Festi and D. van Straten, \textit{Bhabha scattering and a special pencil of K3 surfaces}, \textit{Commun. Num. Theor. Phys.} \textbf{13} (2019) 463 [arXiv:1809.04970] [nSPIRE].

[69] M. Besier, D. Festi, M. Harrison and B. Naskrecki, \textit{Arithmetic and geometry of a K3 surface emerging from virtual corrections to Drell-Yan scattering}, \textit{arXiv:1908.01079} [nSPIRE].

[70] C.F. Doran, A.Y. Novoseltsev and P. Vanhove, \textit{Mirroring towers: Calabi-Yau geometry of the multiloop Feynman sunset integrals}, to appear.

[71] V. Braun, \textit{On free quotients of complete intersection Calabi-Yau manifolds}, \textit{JHEP} \textbf{04} (2011) 005 [arXiv:1202.1757] [nSPIRE].

[72] L.B. Anderson, J. Gray, A. Lukas and E. Palti, \textit{Two hundred heterotic Standard Models on smooth Calabi-Yau threefolds}, \textit{Phys. Rev.} \textbf{D 84} (2011) 106005 [arXiv:1106.4804] [nSPIRE].

[73] L.B. Anderson, J. Gray, A. Lukas and E. Palti, \textit{Heterotic line bundle standard models}, \textit{JHEP} \textbf{06} (2012) 113 [arXiv:1202.1757] [nSPIRE].

[74] J. Gray, A.S. Haupt and A. Lukas, \textit{All complete intersection Calabi-Yau four-folds}, \textit{JHEP} \textbf{07} (2013) 070 [arXiv:1303.1832] [nSPIRE].

[75] P. Candelas, X.C. De La Ossa, P.S. Green and L. Parkes, \textit{A pair of Calabi-Yau manifolds as an exactly soluble superconformal theory}, \textit{Nucl. Phys.} \textbf{B 359} (1991) 21 [nSPIRE].

[76] S. Mizera, \textit{Scattering amplitudes from intersection theory}, \textit{Phys. Rev. Lett.} \textbf{120} (2018) 141602 [arXiv:1711.00469] [nSPIRE].

[77] P. Mastrolia and S. Mizera, \textit{Feynman integrals and intersection theory}, \textit{JHEP} \textbf{02} (2019) 139 [arXiv:1810.03818] [nSPIRE].

[78] H. Frellesvig, F. Gasparotto, M.K. Mandal, P. Mastrolia, L. Mattiazzi and S. Mizera, \textit{Vector space of Feynman integrals and multivariate intersection numbers}, \textit{Phys. Rev. Lett.} \textbf{123} (2019) 201602 [arXiv:1907.02000] [nSPIRE].

[79] J.L. Bourjaily, F. Dulat and E. Panzer, \textit{Manifestly dual-conformal loop integration}, \textit{Nucl. Phys. B} \textbf{942} (2019) 251 [arXiv:1901.02887] [nSPIRE].

[80] J.L. Bourjaily, A.J. McLeod, M. von Hippel and M. Wilhelm, \textit{Elliptic double-box integrals: massless scattering amplitudes beyond polylogarithms}, \textit{Phys. Rev. Lett.} \textbf{120} (2018) 121603 [arXiv:1712.02785] [nSPIRE].

[81] J.L. Bourjaily, A.J. McLeod, M. von Hippel and M. Wilhelm, \textit{Rationalizing loop integration}, \textit{JHEP} \textbf{08} (2018) 184 [arXiv:1805.10281] [nSPIRE].

[82] Ö. Gürdoğan and V. Kazakov, \textit{New integrable 4D quantum field theories from strongly deformed planar $\mathcal{N} = 4$ supersymmetric Yang-Mills theory}, \textit{Phys. Rev. Lett.} \textbf{117} (2016) 201602 [Addendum ibid. \textbf{117} (2016) 259903] [arXiv:1512.06704] [nSPIRE].

[83] C. Sieg and M. Wilhelm, \textit{On a CFT limit of planar $\gamma_i$-deformed $\mathcal{N} = 4$ SYM theory}, \textit{Phys. Lett. B} \textbf{756} (2016) 118 [arXiv:1602.05817] [nSPIRE].

[84] D. Grabner, N. Gromov, V. Kazakov and G. Korchemsky, \textit{Strongly $\gamma$-deformed $\mathcal{N} = 4$ supersymmetric Yang-Mills theory as an integrable conformal field theory}, \textit{Phys. Rev. Lett.} \textbf{120} (2018) 111601 [arXiv:1711.04786] [nSPIRE].
[85] Z. Bern, L.J. Dixon, D.C. Dunbar and D.A. Kosower, One loop n-point gauge theory amplitudes, unitarity and collinear limits, Nucl. Phys. B 425 (1994) 217 [hep-ph/9403226] [nSPIRE].

[86] Z. Bern, L.J. Dixon, D.C. Dunbar and D.A. Kosower, Fusing gauge theory tree amplitudes into loop amplitudes, Nucl. Phys. B 435 (1995) 59 [hep-ph/9409265] [nSPIRE].

[87] Z. Bern, L.J. Dixon and D.A. Kosower, One loop amplitudes for e+e− to four partons, Nucl. Phys. B 513 (1998) 3 [hep-ph/9708239] [nSPIRE].

[88] R. Britto, F. Cachazo and B. Feng, Generalized unitarity and one-loop amplitudes in $N = 4$ super-Yang-Mills, Nucl. Phys. B 725 (2005) 275 [hep-th/0412103] [nSPIRE].

[89] Z. Bern, J.J.M. Carrasco, H. Johansson and D.A. Kosower, Maximally supersymmetric planar Yang-Mills amplitudes at five loops, Phys. Rev. D 76 (2007) 125020 [arXiv:0705.1864] [nSPIRE].

[90] J.L. Bourjaily, E. Herrmann and J. Trnka, Prescriptive unitarity, JHEP 06 (2017) 059 [arXiv:1704.05460] [nSPIRE].

[91] J.L. Bourjaily, E. Herrmann and J. Trnka, Building bases of loop integrands, to appear.

[92] S. Bloch, M. Kerr and P. Vanhove, A Feynman integral via higher normal functions, Compos. Math. 151 (2015) 2329 [arXiv:1406.2664] [nSPIRE].

[93] S. Bloch, M. Kerr and P. Vanhove, Local mirror symmetry and the sunset Feynman integral, Adv. Theor. Math. Phys. 21 (2017) 1373 [arXiv:1601.08181] [nSPIRE].

[94] T. Hubsch, Calabi-Yau manifolds: a bestiary for physicists, World Scientific, Singapore (1992) [nSPIRE].

[95] V.V. Batyrev, Dual polyhedra and mirror symmetry for Calabi-Yau hypersurfaces in toric varieties, J. Alg. Geom. 3 (1994) 493 [alg-geom/9310003] [nSPIRE].

[96] V.I. Danilov, The geometry of toric varieties, Russ. Math. Surv. 33 (1978) 97.

[97] K. Hori et al., Mirror symmetry, volume 1 of Clay mathematics monographs, American Mathematical Society, Providence, RI, U.S.A. (2003) [nSPIRE].

[98] V.V. Batyrev and L.A. Borisov, Mirror duality and string theoretic Hodge numbers, Invent. Math. 126 (1996) 183 [alg-geom/9509009] [nSPIRE].

[99] M. Kreuzer, E. Riegler and D.A. Sahakyan, Toric complete intersections and weighted projective space, J. Geom. Phys. 46 (2003) 159 [math.AG/0103214] [nSPIRE].

[100] M. Kreuzer and H. Skarke, PALP: a package for analyzing lattice polytopes with applications to toric geometry, Comput. Phys. Commun. 157 (2004) 87 [math.NA/0204356] [nSPIRE].

[101] The Sage developers, SageMath, the Sage mathematics software system (version 8.8), https://www.sagemath.org, (2019).

[102] N. Arkani-Hamed, J.L. Bourjaily, F. Cachazo and J. Trnka, Singularity structure of maximally supersymmetric scattering amplitudes, Phys. Rev. Lett. 113 (2014) 261603 [arXiv:1410.0364] [nSPIRE].

[103] S. Laporta, Analytical expressions of 3 and 4-loop sunrise Feynman integrals and 4-dimensional lattice integrals, Int. J. Mod. Phys. A 23 (2008) 5007 [arXiv:0803.1007] [nSPIRE].
[104] J.L. Bourjaily, S. Caron-Huot and J. Trnka, Dual-conformal regularization of infrared loop divergences and the chiral box expansion, *JHEP* **01** (2015) 001 [arXiv:1303.4734] [INSPIRE].

[105] J.L. Bourjaily and J. Trnka, Local integrand representations of all two-loop amplitudes in planar SYM, *JHEP* **08** (2015) 119 [arXiv:1505.05886] [INSPIRE].

[106] M. Besier, D. Van Straten and S. Weinzierl, Rationalizing roots: an algorithmic approach, *Commun. Num. Theor. Phys.* **13** (2019) 253 [arXiv:1809.10983] [INSPIRE].

[107] D.J. Broadhurst and D. Kreimer, Knots and numbers in $\varphi^4$ theory to 7 loops and beyond, *Int. J. Mod. Phys.* **C 6** (1995) 519 [hep-ph/9504352] [INSPIRE].

[108] O. Schnetz, Quantum periods: a census of $\varphi^4$-transcendentals, *Commun. Num. Theor. Phys.* **4** (2010) 1 [arXiv:0801.2856] [INSPIRE].

[109] J.M. Drummond, Generalised ladders and single-valued polylogarithms, *JHEP* **02** (2013) 092 [arXiv:1207.3824] [INSPIRE].

[110] F. Brown and O. Schnetz, Proof of the zig-zag conjecture, arXiv:1208.1890 [INSPIRE].

[111] C. Bogner and F. Brown, Feynman integrals and iterated integrals on moduli spaces of curves of genus zero, *Commun. Num. Theor. Phys.* **09** (2015) 189 [arXiv:1408.1862] [INSPIRE].

[112] E. Panzer, Feynman integrals and hyperlogarithms, Ph.D. thesis, Humboldt U., Berlin, Germany (2015) [arXiv:1506.07243] [INSPIRE].

[113] M. Golz, E. Panzer and O. Schnetz, Graphical functions in parametric space, *Lett. Math. Phys.* **107** (2017) 1177 [arXiv:1509.07296] [INSPIRE].

[114] D.J. Broadhurst, Massless scalar Feynman diagrams: five loops and beyond, arXiv:1604.08027 [INSPIRE].

[115] S. M"uller-Stach, S. Weinzierl and R. Zayadeh, Picard-Fuchs equations for Feynman integrals, *Commun. Math. Phys.* **326** (2014) 237 [arXiv:1212.4389] [INSPIRE].

[116] F. Brown, Notes on motivic periods, arXiv:1512.06410.

[117] V. Bouchard, Lectures on complex geometry, Calabi-Yau manifolds and toric geometry, hep-th/0702063 [INSPIRE].

[118] M.F. Paulos, private communication.

[119] N. Arkani-Hamed, J.L. Bourjaily, F. Cachazo, S. Caron-Huot and J. Trnka, The all-loop integrand for scattering amplitudes in planar $\mathcal{N} = 4$ SYM, *JHEP* **01** (2011) 041 [arXiv:1008.2958] [INSPIRE].

[120] B. Basso and L.J. Dixon, Gluing ladder Feynman diagrams into fishnets, *Phys. Rev. Lett.* **119** (2017) 071601 [arXiv:1705.03545] [INSPIRE].

[121] N. Gromov, V. Kazakov and G. Korchemsky, Exact correlation functions in conformal Fishnet theory, *JHEP* **08** (2019) 123 [arXiv:1808.02688] [INSPIRE].