$d = 2$ transverse-field Ising model under the screw-boundary condition: an optimization of the screw pitch

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Abstract. A length-$N$ spin chain with the $\sqrt{N}(=v)$th neighbor interaction is identical to a two-dimensional ($d = 2$) model under the screw-boundary (SB) condition. The SB condition provides a flexible scheme to construct a $d \geq 2$ cluster from an arbitrary number of spins; the numerical diagonalization combined with the SB condition admits a potential applicability to a class of systems intractable with the quantum Monte Carlo method due to the negative-sign problem. However, the simulation results suffer from characteristic finite-size corrections inherent in SB. In order to suppress these corrections, we adjust the screw pitch $v(N)$ so as to minimize the excitation gap for each $N$. This idea is adapted to the transverse-field Ising model on the triangular lattice with $N \leq 32$ spins. As a demonstration, the correlation-length critical exponent $\nu$ is analyzed in some detail.

Keywords: finite-size scaling, other numerical approaches
An optimization of the screw pitch

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1. Introduction

A length-\( N \) spin chain with the \( \sqrt{N}(=v) \)th neighbor interaction is identical to a two-dimensional \( (d = 2) \) model under the screw-boundary condition; a schematic drawing is presented in figure 1. The screw-boundary condition provides a flexible scheme to construct a \( d \geq 2 \) cluster from an arbitrary number of spins \( N \). With the aid of Novotny’s method [1, 2], one is able to implement the screw-boundary condition systematically; details are given later. Because the quantum Monte Carlo method is inapplicable to a class of systems such as the frustrated quantum magnets (negative-sign problem), the numerical diagonalization combined with Novotny’s method might provide valuable information on such an intriguing subject.

As a matter of fact, the screw-boundary condition was adapted to the \( S = 1 \) triangular magnet for \( N \leq 20 \) [3]; tuning the spatial anisotropy and the biquadratic interaction, we are able to realize the deconfined criticality [4] between the resonating-valence-bond (RVB) and magnetic phases. The present scheme (modification) is readily applicable to this problem. Moreover, a recent reexamination of the transverse-field Ising model in \( d = 2 \) and 3 via the real-space renormalization group revealed that a procedure, the so-called ‘exact invariance under renormalization,’ yields a substantially improved critical exponent even for an analytically tractable system size; a relevance to the present treatment is addressed in section 4.

In this paper, we make an attempt to reduce the finite-size corrections inherent in the screw-boundary condition. As a matter of fact, the simulation results exhibit bumpy finite-size deviations depending on whether the pitch \( v(=\sqrt{N}) \) is close to an integral number or not; actually, in [1], such a singular case is treated separately. The screw pitch \( v \) admits a continuous variation, and there is no reason to stick to a fixed pitch \( v = \sqrt{N} \). We adjust \( v(\approx\sqrt{N}) \) so as to minimize the excitation gap \( \Delta E \) for each system size \( N \). As a demonstration, we adapt this idea to the (ferromagnetic) transverse-field Ising model on the triangular lattice for \( N \leq 32 \). In order to demonstrate the performance of this approach, we analyze the criticality (correlation-length critical exponent \( \nu \)) in some detail; the simulation results are compared with those of the fixed screw pitch \( v = \sqrt{N} \).

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Figure 1. A schematic drawing of the spin cluster for the transverse-field Ising model (3) is presented. We implement the screw-boundary condition with the screw pitch \( v \), based on Novotny’s method. As indicated above, the spins constitute a one-dimensional \( (d = 1) \) alignment \( \{\sigma_i\} \ (i = 1, 2, \ldots, N) \), and the dimensionality is lifted to \( d = 2 \) by the \( v(\approx\sqrt{N}) \) th-neighbor interactions. Full details of the simulation scheme are presented in the text.

The rest of this paper is organized as follows. In section 2, we explicate the simulation algorithm, placing an emphasis on the scheme for fixing the screw pitch to an optimal value. In section 3, we show the numerical results. As a demonstration, we make an analysis of the critical exponent \( \nu \). In section 4, we present the summary and discussion.

2. Simulation algorithm for the two-dimensional transverse-field Ising model under the screw-boundary condition: Novotny’s method

We employ Novotny’s method in order to implement the screw-boundary condition [1, 2]. For the sake of selfconsistency, in this section, we present an explicit simulation algorithm.

Before commencing an explanation of the technical details, we sketch a basic idea of Novotny’s method; see figure 1. We implement the screw-boundary condition for a finite cluster with \( N \) spins. We place an \( S = 1/2 \) spin (Pauli matrix \( \vec{\sigma} \)) at each lattice point \( i \) \((\leq N)\). Basically, the spins constitute a one-dimensional \( (d = 1) \) structure. The dimensionality is lifted to \( d = 2 \) by the long-range interactions over the \( \sqrt{N}(=v) \) th-neighbor distances; owing to the long-range interaction, the \( N \) spins form a \( \sqrt{N} \times \sqrt{N} \) rectangular network effectively. (The significant point is that the screw pitch \( v \approx \sqrt{N} \) is not necessarily an integer number, and can even afford to vary continuously.)

According to Novotny [1, 2], the long-range interactions are introduced systematically by the use of the translation operator \( P \); see equation (4). The operator \( P \) satisfies the formula

\[
P|\sigma_1, \sigma_2, \ldots, \sigma_N\rangle = |\sigma_N, \sigma_1, \ldots, \sigma_{N-1}\rangle. \tag{1}
\]
Here, the Hilbert-space bases \( \{ |\sigma_1, \sigma_2, \ldots, \sigma_N \rangle \} \) (\( \sigma_i = \pm 1 \)) diagonalize the operator \( \sigma_i^z \):

\[
|\sigma_i \rangle \langle \sigma_i | = \sigma_j |\sigma_j \rangle \langle \sigma_j |. 
\]

(2)

2.1. Details of Novotny’s method

We formulate the above idea explicitly. We adapt Novotny’s method to the transverse-field Ising model on the triangular lattice. The Hamiltonian with a screw pitch \( v(\approx \sqrt{N}) \) is given by

\[
H = -J \left[ H(1) + H\left( v + \frac{1}{2} \right) + H\left( v - \frac{1}{2} \right) \right] - \Gamma \sum_{i=1}^{N} \sigma_i^x, 
\]

(3)

with the transverse magnetic field \( \Gamma \). Hereafter, we consider the exchange interaction \( J \) as a unit of energy (\( J = 1 \)). The \( v \)th neighbor interaction \( H(v) \) is a diagonal matrix, whose diagonal element is given by

\[
H_{\{\sigma_i\},\{\sigma_j\}}(v) = \langle \{\sigma_i\} | H(v) | \{\sigma_j\} \rangle = \langle \{\sigma_i\} | TP^v | \{\sigma_j\} \rangle. 
\]

(4)

The insertion of \( P^v \) is a key ingredient to introduce the \( v \)th neighbor interaction. Here, the matrix \( T \) denotes the exchange interaction between \( \{\sigma_i\} \) and \( \{\tau_i\} \):

\[
\langle \{\sigma_i\} | T | \{\tau_i\} \rangle = \sum_{k=1}^{N} \sigma_k \tau_k. 
\]

(5)

Afterward, we search for an optimal value of the screw pitch \( v (\approx \sqrt{N}) \).

The above formulas complete the formal basis of our simulation scheme. We diagonalize the Hamiltonian matrix (3) for \( N \leq 32 \) spins numerically. In the practical numerical calculation, however, a number of formulas may be of use; see the appendices of [6,7].

2.2. Search for an optimal screw pitch \( v \)

An optimal value of the screw pitch \( v \) is determined as follows. In figure 2, we plot the (first) excitation gap \( \Delta E \) for the parameter \( a = v^2/N \), and the system sizes \( N = (+) 28 \) and \( (\times) 32 \). Here, we fix the transverse magnetic field to \( \Gamma = 4.8 \), which is close to the critical point (separating the paramagnetic and ferromagnetic phases); see figure 3. (An underlying idea behind this analysis is presented later.) From figure 2, we see that the excitation gap takes a minimum value in the vicinity of the point \( a = 1 \); note that so far, the screw-boundary-condition (Novotny method) simulation has been performed at \( a = 1 \) (\( v = \sqrt{N} \)). We adjust \( v(N) \) so as to minimize the excitation gap for each \( N \). As a result, we arrive at optimal screw pitches (\( v = \sqrt{Na} \)) of

\[
a = 1.12, 0.98, 0.81, 0.68, 1.30, \text{ and } 1.06, 
\]

(6)

for \( N = 12, 16, \ldots, 32 \), respectively. (The series of results may indicate a regularity such that the \( \sqrt{N} \)-dependence of \( a \) is sawtooth like.) The optimal screw pitch differs from the conventional one [1,2]

\[
v = \sqrt{N}. 
\]

(7)
An optimization of the screw pitch

Figure 2. The excitation gap $\Delta E$ is presented for a parameter $a = v^2/N$ ($v$ is the screw pitch), and the system size $N = (+) 28$ and ($\times$) 32; the transverse magnetic field is fixed to $\Gamma = 4.8$, which is close to a critical point (figure 3). We determine an optimal screw pitch $v(N)$ so as to minimize $\Delta E$ for each $N$.

Figure 3. The scaled energy gap $L\Delta E$ is plotted for the transverse magnetic field $\Gamma$, and system sizes $N = (+) 12$, ($\times$) 16, ($\ast$) 20, ($\square$) 24, ($\blacksquare$) 28, and ($\circ$) 32 ($L = \sqrt{N}$). Here, the screw pitch $v$ is set to an optimal value (equation (6)). We observe an onset of continuous phase transition around $\Gamma \approx 4.8$.

A comparison between equations (6) and (7) will be made in order to elucidate the performance of the present approach.

The underlying idea behind the above screw-pitch optimization (6) is as follows. In general, the excitation gap is proportional to the reciprocal correlation length $\xi \propto 1/\Delta E$. According to the scaling hypothesis, namely, at the critical point, the correlation length develops up to the linear dimension of the cluster $L \sim \xi$; in other words, the correlation

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Figure 4. The approximate critical point $\Gamma(L_1, L_2)$ (equation (8)) is plotted for $\left[\frac{2}{(L_1 + L_2)}\right]^3$ with $12 \leq N_1 < N_2 \leq 32$ ($L_{1,2} = \sqrt{N_{1,2}}$). The symbols (+) and (□) denote the data for the optimal (equation (6)) and fixed (equation (7)) screw pitches, respectively. The data indicate that the optimal screw pitch suppresses the (bumpy) finite-size deviations.

3. Numerical results

Setting the screw pitch to an optimal value (6), we turn to the analysis of the exponent $\nu$ in some detail. In figure 3, we plot the scaled excitation gap for various $\Gamma$ and $N = 12, 16, \ldots, 32$; the system size $L$ is given by $L = \sqrt{N}$, because $N$ spins constitute a rectangular cluster. According to the scaling hypothesis, the intersection point indicates a location of the critical point; for details of the scaling theory, we refer readers to a comprehensive review article [8]. We see that a phase transition occurs at $\Gamma \approx 4.8$.

In figure 4, we plot the approximate critical point $\Gamma_c(L_1, L_2)$ for $\left[\frac{2}{(L_1 + L_2)}\right]^3$ with $12 \leq N_1 < N_2 \leq 32$ ($L_{1,2} = \sqrt{N_{1,2}}$). (The abscissa scale $1/L^3$ is based on the scaling theory, which states that, in principle, the corrections of $\Gamma_c$ should behave like $1/L^{1/\nu + \omega}$ with $1/\nu + \omega = 1.5868(3) + 0.821(5)$ [9]. There may also exist subdominant corrections, and the abscissa scale is set to $1/L^3$.) Here, the symbol (+) denotes the simulation result with the optimal screw pitch adjusted to equation (6), whereas the data of (□) were calculated with the screw pitch fixed to equation (7) tentatively. The approximate critical point satisfies the fixed-point relation with respect to $L\Delta E$

$$L_1\Delta E(L_1)|_{\Gamma = \Gamma_c(L_1, L_2)} = L_2\Delta E(L_2)|_{\Gamma = \Gamma_c(L_1, L_2)},$$

for a pair of system sizes $(L_1, L_2)$. The data with the conventional scheme (symbol (□)) exhibit a pronounced bumpy finite-size behavior, at least as compared to those
Figure 5. The approximate correlation-length critical exponent $\nu(L_1, L_2)$ is plotted for $[2/(L_1 + L_2)]^2$ with $12 \leq N_1 < N_2 \leq 32$ ($L_{1,2} = \sqrt{N_{1,2}}$). The data for the symbols (+) and (□) were calculated from the scaled energy gap (equation (9)) for the optimal (equation (6)) and fixed (equation (7)) screw pitches, respectively. Similarly, from the Binder parameter (equation (11)), the data for the symbols (×) and (○) were calculated for the optimal (equation (6)) and fixed (equation (7)) screw pitches, respectively. The data for the optimized screw pitch, (+) and (×), exhibit suppressed finite-size deviations. An extrapolation to the thermodynamic limit is argued in the text.

of (+). The minimum of the (□) data corresponds to $N \approx 5^2 (1/5^3 = 0.008)$; for such a quadratic system size, the data suffer from an irregularity [1] intrinsic to the screw-boundary condition. Such irregularities appear to be remedied by optimizing $v$ (symbol (+)) satisfactorily. The extrapolated critical point $\Gamma_c|_{L=\infty}$ is no longer utilized in the subsequent analyses; rather, the finite-size critical point $\Gamma_c(L_1, L_2)$ is used. Hence, we do not go into further details as to the reliability of $\Gamma_c$. 

In figure 5, we present the approximate correlation-length critical exponent

$$\nu(L_1, L_2) = \frac{\ln(L_1/L_2)}{\ln\left(\partial \Gamma_1 \Delta E(L_1)/\partial \Gamma_2 \Delta E(L_2)\right)|_{\Gamma=\Gamma_c(L_1, L_2)}}$$

(9)

for $[2/(L_1 + L_2)]^2$ with $12 \leq N_1 < N_2 \leq 32$ ($L_{1,2} = \sqrt{N_{1,2}}$). (The abscissa scale $1/L^2$ is based on the scaling theory, which states that, in principle, the corrections of critical indices should behave like $1/L^\omega$ with $\omega = 0.821(5)$ [9]. Afterward, we make a slight variation of the abscissa scale so as to appreciate possible subdominant contributions properly.) The symbols (+) and (□) denote the results with the optimal (equation (6)) and fixed (equation (7)) screw pitches, respectively. Again, the former result (+) appears to exhibit reduced finite-size corrections as compared to the latter one (□).

We are able to calculate the critical exponent, based on the Binder parameter

$$U = 1 - \frac{\langle M^4 \rangle}{3\langle M^2 \rangle^2},$$

(10)

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with the magnetization $M = \sum_{i=1}^{N} \sigma_i^z$ and the ground-state expectation $\langle \cdots \rangle$. In figure 5, we present the approximate critical exponent
\[
\nu(L_1, L_2) = \frac{\ln(L_1/L_2)}{\ln[\partial \Gamma U(L_1)/\partial \Gamma U(L_2)]_{\Gamma = \Gamma_c(L_1, L_2)}},
\] (11)
with $12 \leq N_1 < N_2 \leq 32$ and the approximate critical point $\Gamma_c(L_1, L_2)$ satisfying the fixed-point relation
\[
U(L_1)_{\Gamma = \Gamma_c(L_1, L_2)} = U(L_2)_{\Gamma = \Gamma_c(L_1, L_2)}. \tag{12}
\]
The symbols (×) and (◦) denote the results calculated with the optimal (equation (6)) and fixed (equation (7)) screw pitches, respectively. Again, the former result (×) appears to exhibit reduced finite-size deviations.

Apart from an improvement due to the optimal screw pitch, in figure 5 it is noteworthy that the data of the symbols (+) and (×) are complementary. That is, these results, obtained independently via the scaled energy gap (equation (9)) and the Binder parameter (equation (11)), provide the upper and lower bounds for $\nu$, respectively. Encouraged by this observation, we carry out an extrapolation to the thermodynamic limit for $\nu$. An application of the least-squares fit to the data (+) yields an estimate $\nu = 0.635(4)$ in the thermodynamic limit $L \to \infty$. Similarly, the result (×) yields $\nu = 0.619(5)$. An appreciable systematic deviation seems to exist. Replacing the abscissa scale of figure 5 with $[2/(L_1 + L_2)]^{1.8}$, we arrive at the estimates $\nu = 0.628(4)$ and $\nu = 0.624(6)$ for the data (+) and (×), respectively; the deviation is now within the error margins. These results may lead to an estimate $\nu = 0.626(10)$ with the error margin covering both systematic and unsystematic (statistical) errors. As a comparison, we refer to a recent Monte Carlo simulation result $\nu = 0.630 \pm 0.020(12)$ [9] for the three-dimensional (classical) Ising model. This result is consistent with ours within the error margins, suggesting that the possible systematic errors are appreciated properly. (As mentioned below, an application of the perfect-action technique might admit a suppression of the error margin.)

Last, we address a remark. In order to demonstrate the reliability of the present approach, a comparison with an existing result would be of use; however, the Ising model on the triangular lattice has not been studied very thoroughly. In this respect, we refer readers to [10] (see figure 4), where the ordinary Ising model was simulated under the screw-boundary condition with $v = \sqrt{N}$ ($a = 1$); the critical point appears to be close to the existing result. An aim of this paper is to reduce the irregular finite-size corrections of figure 4 in [10].

4. Summary and discussion

An attempt to suppress the finite-size corrections inherent in the screw-boundary condition (figure 1) was made for the transverse-field Ising model on the triangular lattice. The screw pitch can afford to vary continuously, and there is no reason to stick to a fixed pitch $v = \sqrt{N}$. Setting the transverse magnetic field to a critical-point value $\Gamma = 4.8$, we scrutinize the $v$-dependence of $\Delta E$ (figure 2). Minimizing $\Delta E$, we determine an optimal value of $v(N)$ for each $N$, equation (6), where an effective shape of the cluster should restore its spatial isotropy. Actually, the numerical results with the optimal screw pitch for $N \leq 32$ exhibit suppressed finite-size corrections, rendering the convergence to the
thermodynamic limit smoother (figures 4 and 5); as a byproduct, the data obtained from the energy gap (equation (9)) and the Binder parameter (equation (11)) provide the upper and lower bounds for $\nu$, respectively. Encouraged by this observation, we make an extrapolation to $L \to \infty$ to obtain an estimate $\nu = 0.626(10)$ via replacing the abscissa scale with $1/L^{1.8}$.

We make a number of remarks. First, as mentioned in section 1, the transverse-field Ising model in $d = 2$ and 3 was reexamined with the analytical real-space renormalization group [5]; even for such an analytical tractable system size, detailed scrutiny of the scaling procedure affords us valuable information as to the criticality. To be specific, one may eliminate the residual finite-size corrections ($\sim 1/L^{1.8}$) by extending the interaction parameters and tuning them through the perfect-action technique [11]–[16]; this technique has been developed in the context of the lattice field theory, for which the continuum (thermodynamic) limit has to be undertaken properly and efficiently. Second, the present scheme (modification) is readily applicable to the quantum two-dimensional magnet [3], which exhibits a deconfined criticality (phase transition between the RVB and magnetic phases). Because of the negative-sign problem, the quantum Monte Carlo method is not quite efficient to realize the RVB phase, and the numerical diagonalization combined with the modified screw-boundary condition would provide a promising candidate to survey such an intriguing issue.

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