Global existence for a system of quasi-linear wave equations in 3D satisfying the weak null condition

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Abstract

We show global existence of small solutions to the Cauchy problem for a system of quasi-linear wave equations in three space dimensions. The feature of the system lies in that it satisfies the weak null condition, though we permit the presence of some quadratic nonlinear terms which do not satisfy the null condition. Due to the presence of such quadratic terms, the standard argument no longer works for the proof of global existence. To get over this difficulty, we extend the ghost weight method of Alinhac so that it works for the system under consideration. The original theorem of Alinhac for the scalar unknowns is also refined.

1 Introduction

In [4], Alinhac studied the Cauchy problem for the quasi-linear wave equation in three space dimensions of the form

\[
\begin{aligned}
\frac{\partial^2 u}{\partial t^2} - \Delta u + G^{\alpha\beta\gamma}(\partial_\gamma u)(\partial_{\alpha\beta} u) &= 0, \quad t > 0, \quad x \in \mathbb{R}^3, \\
\phi(0) &= \phi_0, \quad \partial_t \phi(0) = \phi_1,
\end{aligned}
\]

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where $u : (0, \infty) \times \mathbb{R}^3 \to \mathbb{R}$, $G^{\alpha\beta\gamma} \in \mathbb{R}$, $G^{\alpha\beta\gamma} = G^{\beta\alpha\gamma}$, $\partial_0 := \partial_t$, and $\varphi_0, \varphi_1 \in C_0^\infty(\mathbb{R}^3)$. Here, and in the following, when the same index is above and below, summation is assumed from 0 to 3 for $\alpha, \beta, \gamma$. Using the remarkable energy inequality (see page 92 of [4]), he proved the following:

**Theorem 1.1 (Alinhac).** Suppose that the coefficients $G^{\alpha\beta\gamma}$ satisfy the null condition:

\[(1.2) \quad G^{\alpha\beta\gamma} X_\alpha X_\beta X_\gamma = 0 \text{ for any } X = (X_0, \ldots, X_3) \text{ with } X_0^2 = X_1^2 + X_2^2 + X_3^2.\]

Set

\[(1.3) \quad R_* := \inf \{ r > 0 : \text{supp} \{\varphi_0, \varphi_1\} \subset \{ x \in \mathbb{R}^3 : |x| < r \} \}.\]

Then, there exist constants $C > 0$, $0 < \varepsilon < 1$ depending on $\{G^{\alpha\beta\gamma}\}$ and $R_*$ with $\varepsilon \to 0$ as $R_* \to \infty$ such that if

\[(1.4) \quad W_4(u(0)) \leq \varepsilon,\]

then the Cauchy problem (1.1) admits a unique global, smooth solution $u(t,x)$ satisfying

\[(1.5) \quad W_4(u(t)) \leq C W_4(u(0)).\]

**Remark 1.2.** In page 89 of [4], only the nonlinear terms involving the spatial derivatives were considered. This was just for simplicity.

Here and in the following discussion, we use the notation:

\[(1.6) \quad E_1(u(t)) := \frac{1}{2} \int_{\mathbb{R}^3} \left[ (\partial_t u(t,x))^2 + |\nabla u(t,x)|^2 \right] dx,\]

\[(1.7) \quad W_\kappa(u(t)) := \sum_{|a| \leq \kappa-1} E_1^{1/2}(Z^a u(t)), \quad \kappa = 2, 3, \ldots\]

By $Z$, we mean any of the operators $\partial_\alpha$ ($\alpha = 0, \ldots, 3$), $\Omega_{ij} := x_i \partial_j - x_j \partial_i$ ($1 \leq i < j \leq 3$), $L_k := x_k \partial_t + t \partial_k$ ($k = 1, 2, 3$), and $S := t \partial_t + x \cdot \nabla$. Also, for a multi-index $a$, $Z^a$ stands for any product of the $|a|$ these operators. We remark that $\partial_t^k u(0,x)$ for $k = 2, 3, 4$ can be calculated with the help of the equation (1.1), and thus the quantity $W_4(u(0))$ appearing in (1.4) is determined by the given initial data $(\varphi_0, \varphi_1)$.

The novelty of this theorem due to Alinhac lies in that as for the size of data, we have only to assume that $W_4(u(0))$ is small enough. It should be compared with the fact that if we employ the standard energy inequality for variable-coefficient hyperbolic operators (see, e.g., (6.3.6) of [10]) and the Klainerman-Sobolev inequalities (see Lemma 2.4 below) together with the good commutation relations (2.1)–(2.2) below, we can obtain:
Proposition 1.3. Suppose the null condition (1.2). Then, there exist constants $C > 0$, $0 < \varepsilon < 1$ depending only on the coefficients $G^{\alpha\beta\gamma}$ such that if

\begin{equation}
W_4(u(0)) \exp(CW_5(u(0))) \leq \varepsilon,
\end{equation}

then the Cauchy problem (1.1) admits a unique global smooth solution $u(t, x)$ satisfying

\begin{equation}
W_4(u(t)) \leq W_4(u(0)) \exp(CW_5(u(0))),\quad W_5(u(t)) \leq CW_5(u(0))(1 + t)^C\varepsilon.
\end{equation}

The proof of Proposition 1.3 uses the two semi-norms, allowing the higher-order one $W_5(u(t))$ to grow slowly over time, and bounding the lower-order one $W_4(u(t))$ uniformly in time with the help of the estimation lemma (see Lemma 2.3 below). This is why we need the size condition (1.8), which is obviously more restrictive than (1.4). On the other hand, the constant $\varepsilon$ of Proposition 1.3 is independent of $R_*$ (see (1.3)). In this regard, Proposition 1.3 has an advantage over Theorem 1.1.

The purpose of this paper is twofold. Firstly, we aim at refining Theorem 1.1 by showing that it is in fact possible to choose the constant $\varepsilon$ independently of $R_*$. Secondly, we intend to generalize Theorem 1.1 to the result for a class of diagonal systems of quasilinear wave equations, such as

\begin{equation}
\begin{cases}
\partial_t^2 u_1 - \Delta u_1 + G_1^{11,\alpha\beta\gamma}(\partial_{\gamma} u_1)(\partial_{\alpha\beta} u_1) + G_1^{21,\alpha\beta\gamma}(\partial_{\gamma} u_2)(\partial_{\alpha\beta} u_1) \\
+ H_1^{11,\alpha\beta}(\partial_{\alpha} u_1)(\partial_{\beta} u_1) + H_1^{21,\alpha\beta}(\partial_{\alpha} u_1)(\partial_{\beta} u_2) + H_1^{22,\alpha\beta}(\partial_{\alpha} u_2)(\partial_{\beta} u_2) = 0,
\end{cases}
\end{equation}

Supposing the null condition for all the coefficients of the first equation, and supposing the null condition only on $\{G_2^{22,\alpha\beta\gamma}\}$ and $\{H_2^{22,\alpha\beta}\}$ as for the coefficients of the second equation, we prove:

Theorem 1.4. Suppose the symmetry condition: there hold $G_1^{11,\alpha\beta\gamma} = G_1^{11,\beta\alpha\gamma}$, $G_1^{21,\alpha\beta\gamma} = G_1^{21,\beta\alpha\gamma}$, and $G_2^{12,\alpha\beta\gamma} = G_2^{12,\beta\alpha\gamma}$, $G_2^{22,\alpha\beta\gamma} = G_2^{22,\beta\alpha\gamma}$ for all $\alpha, \beta, \gamma = 0, \ldots, 3$. Also, suppose

\begin{align}
G_1^{11,\alpha\beta\gamma} X_\alpha X_\beta X_\gamma &= G_1^{21,\alpha\beta\gamma} X_\alpha X_\beta X_\gamma = G_2^{22,\alpha\beta\gamma} X_\alpha X_\beta X_\gamma = 0, \\
H_1^{11,\alpha\beta} X_\alpha X_\beta &= H_1^{12,\alpha\beta} X_\alpha X_\beta = H_1^{21,\alpha\beta} X_\alpha X_\beta = H_2^{22,\alpha\beta} X_\alpha X_\beta = 0
\end{align}

for any $X = (X_0, \ldots, X_3) \in \mathbb{R}^4$ with $X_0^2 = X_1^2 + X_2^2 + X_3^2$. Let $0 < \eta < 1/6$, $0 < \delta < 1/6$ so that $\eta + 2\delta < 1/2$. Then, there exist constants $C > 0$, $0 < \varepsilon < 1$ depending only on the coefficients of the system (1.10), $\delta$, and $\eta$ such that if compactly supported smooth data...
satisfy $W_4(u_1(0)) + W_4(u_2(0)) < \varepsilon$, then the Cauchy problem for (1.10) admits a unique global smooth solution $(u_1(t, x), u_2(t, x))$ satisfying for all $t > 0, T > 0$

\begin{equation}
W_4(u_1(t)) + (1 + t)^{-\delta} W_4(u_2(t)) + \sum_{i=1}^{3} \sum_{|a| \leq 3} \left( \|\langle t - r \rangle^{-(1/2) - \eta} T_i Z^a u_1 \|_{L^2((0, \infty) \times \mathbb{R}^3)} + (1 + T)^{-\delta} \|\langle t - r \rangle^{-(1/2) - \eta} T_i Z^a u_2 \|_{L^2((0, T) \times \mathbb{R}^3)} \right) \leq C(W_4(u_1(0)) + W_4(u_2(0))).
\end{equation}

Here $T_i = \partial_i + (x_i/|x|) \partial_t$.

Here, and in the following as well, we use the standard notation $\langle p \rangle = \sqrt{1 + p^2}$. Note that by choosing the trivial data $u_2(0, x) = \partial_t u_2(0, x) = 0$ and assuming $H^{11, \alpha \beta} = 0$ for all $\alpha, \beta$, and thus considering the trivial solution $u_2(t, x) \equiv 0$, we can go back to the wave equation for the scalar unknowns with the nonlinear terms more general than those of (1.1)

\begin{equation}
\partial_t^2 u - \Delta u + G^{\alpha \beta \gamma}(\partial_\gamma u)(\partial_\alpha^2 u) + H^{\alpha \beta}(\partial_\alpha u)(\partial_\beta u) = 0, \ t > 0, \ x \in \mathbb{R}^3
\end{equation}

and thus obtain:

**Theorem 1.5.** Suppose the symmetry condition $G^{\alpha \beta \gamma} = G^{\beta \alpha \gamma}$. Also, suppose the null condition: there holds

\begin{equation}
G^{\alpha \beta \gamma} X_\alpha X_\beta X_\gamma = H^{\alpha \beta} X_\alpha X_\beta = 0
\end{equation}

for any $X = (X_0, \ldots, X_3) \in \mathbb{R}^4$ with $X_3^2 = X_1^2 + X_2^2 + X_3^2$. Let $0 < \eta < 1/6$ be fixed. Then, there exist constants $C > 0, 0 < \varepsilon < 1$ depending only on $\eta$, $\{G^{\alpha \beta \gamma}\}$ and $\{H^{\alpha \beta}\}$ such that if compactly supported smooth data satisfy

\begin{equation}
W_4(u(0)) \leq \varepsilon,
\end{equation}

then the Cauchy problem (1.14) admits a unique global, smooth solution $u(t, x)$ satisfying

\begin{equation}
\sup_{t > 0} W_4(u(t)) + \sum_{i=1}^{3} \sum_{|a| \leq 3} \|\langle t - r \rangle^{-(1/2) - \eta} T_i Z^a u \|_{L^2((0, \infty) \times \mathbb{R}^3)} \leq C W_4(u(0)).
\end{equation}

Moreover, the estimate

\begin{equation}
\sup_{t > 0} W_5(u(t)) \leq C W_5(u(0))
\end{equation}

also holds.
Theorem 1.5 significantly improves Theorem 1.1 because the constant $\varepsilon$ no longer depends upon $R_*$. Also, we permit the presence of the “semi-linear term” $H^{\alpha\beta}(\partial_\alpha u)(\partial_\beta u)$. Theorem 1.5 improves Theorem 1.1 of Wang [24] too, where in the absence of such semi-linear terms, global existence of solutions to (1.1) and uniform (in time) boundedness of $W_5(u(t))$ was shown under the assumption that $W_5(u(0)) \leq \varepsilon$. (Recall that in Theorem 1.5, we have only assumed $W_4(u(0))$ is small.) We remark that the constant $\varepsilon$ in Theorem 1.1 of [24] also depends upon $R_*$. In addition, we should mention the recent paper of Zha [25], which the authors became aware of while preparing the present manuscript. In [25], again in the absence of the semi-linear terms, global existence of solutions to (1.1) and uniform (in time) boundedness of $W_7(u(t))$ was shown under the assumption that $W_7(u(0)) \leq \varepsilon$. (Strictly speaking, the definition of the “generalized energy norm” in [25] is slightly different from that of ours.) We should note that the constant $\varepsilon$ in the theorem of Zha no longer depends upon $R_*$. Finally, we remark that the bound (1.18) tells us that the “grow up” (or “blow up at $t = \infty$”) suggested by the second estimate in (1.9) in fact never occurs.

The null condition was originally introduced by Christodoulou [5] and Klainerman [13] independently, as the sufficient condition on the form of quadratic nonlinear terms under which the Cauchy problem for diagonal systems of quasi-linear wave equations with quadratic and fairly general higher-order nonlinear terms admits global solutions whenever initial data are smooth and small. It is worthwhile to remark that the system (1.10) does not satisfy the null condition but does satisfy the weak null condition which was introduced by Lindblad and Rodnianski [19]. Now let us recall the condition. We anticipate the asymptotic expansion

$$u(t, x) \sim \frac{\varepsilon U(q, s, \omega)}{|x|}$$

as $|x| \to \infty$ and $|x| \sim t$, where

$$q = |x| - t, \quad s = \varepsilon \log |x|, \quad \omega = \frac{x}{|x|}.$$ 

Then we obtain a system of equations for $U = (U_i)$, the asymptotic system, by substituting (1.19) into the original system and extracting the main terms. We say that a system of nonlinear wave equations satisfies the weak null condition if the following conditions are satisfied (see [19] for details):

- The corresponding asymptotic system admits a global solution for all initial data at $s = 0$ decaying sufficiently fast in $q$. 

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• The global solution grows in $s$ at most exponentially together with its derivatives.

In the case of (1.10), we see that the asymptotic system is

\begin{align}
2\partial_s \partial_q U_1 &= 0, \\
2\partial_s \partial_q U_2 &= A_{2,12}^{12}(\omega)(\partial_q U_1)(\partial_q^2 U_2) + A_{2,11}^{12}(\omega)(\partial_q U_1)(\partial_q U_2) + A_{2,11}^{11}(\omega)(\partial_q U_1)^2,
\end{align}

where

\begin{align}
A_{2,12}^{12}(\omega) &= G_{2,\alpha\beta\gamma}(\partial_q U_1)(\partial_q U_2), \\
A_{2,11}^{12}(\omega) &= H_{2,\alpha\beta}(\partial_q U_1)(\partial_q U_2), \\
A_{2,11}^{11}(\omega) &= H_{2,\alpha\beta}(\partial_q U_1)(\partial_q U_2),
\end{align}

and $\hat{\omega} = (-1, \omega)$. Note that the quadratic terms such as $G_{1,\alpha\beta\gamma}(\partial_q U_1)(\partial_q U_2)$, ..., $H_{2,\alpha\beta}(\partial_q U_1)(\partial_q U_2)$ whose coefficients satisfy the null condition (1.11), (1.12) are negligible compared to the main terms. Note also the presence of the terms $A_{2,12}^{12}(\omega)(\partial_q U_1)(\partial_q^2 U_2)$, $A_{2,11}^{12}(\omega)(\partial_q U_1)(\partial_q U_2)$ in (1.21), which shows a feature of our study. The asymptotic system of the type

\begin{align}
2\partial_s \partial_q U_1 &= 0, \\
2\partial_s \partial_q U_2 &= (\partial_q U_1)^2
\end{align}

has already appeared in the study of the Einstein vacuum equations in harmonic coordinates (see [19]). As far as the present authors know, global existence for (1.10) with small initial data whose corresponding asymptotic system is (1.20)–(1.21) has not been proved until now. Actually, it is not difficult to find a solution of (1.20)–(1.21) obeying

\begin{align}
U_1|_{s=0} = F_1, \\
U_2|_{s=0} = F_2
\end{align}

and growing in $s$ at most exponentially. Indeed, we get from (1.20) a solution of the form $U_1 = F_1(q, \omega)$, which is independent of $s$. Substituting this into (1.21), we have

\begin{align}
2\partial_s \partial_q U_2 - A_{2,12}^{12}(\omega)\partial_q F_1(q, \omega)\partial_q^2 U_2 \\
= A_{2,11}^{12}(\omega)(\partial_q F_1(q, \omega))(\partial_q U_2) + A_{2,11}^{11}(\omega)(\partial_q F_1(q, \omega))^2.
\end{align}

This can be regarded as a linear first order partial differential equation for $\partial_q U_2$. By the standard argument (see, e.g., page 13 of [10]), we can find a global solution growing in $s$ at most exponentially, which means that the system (1.10) satisfies the weak null condition. Since the weak null condition strongly raises the possibility of global existence for the original system, it is very important to investigate whether there exist global solutions to (1.10) for small, smooth data. To the best of the present authors’ knowledge, there exist a few works verifying the prediction that the system violating the null condition but
satisfying the weak null condition actually admits global solutions for small, smooth data. See [16], [2], [3], [20], [17], [6], [12], and [21]. In this paper, we are going to prove global existence for (1.10).

The standard argument of showing global existence results such as Proposition 1.3 requires that a lower-order energy remain small as \( t \to \infty \) (see (1.9)). Since \( W_4(u_2(t)) \) may possibly grow as \( t \to \infty \) (see (1.13)), the standard argument does not apply to the proof of global existence for the system (1.10). We instead employ the ghost weight technique of showing Theorem 1.1 above (see Chapter 9 of [4]). Naturally, some modifications are necessary so as to choose \( \varepsilon \) independently of \( R_* \) and also to study the system (1.10). The constant \( \varepsilon \) of Theorem 1.1 depends upon \( R_* \) because on pages 94 and 95 Alinhac uses the inequality

\[
(1.25) \quad (1 + t)(1 + |t - r|)^{-1/2} \phi(t, x) \leq C \sum_{|a| \leq 2} \| \partial_x Z^a \phi(t, \cdot) \|_{L^2(\mathbb{R}^3)}
\]

for smooth functions \( \phi(t, x) \) with \( \text{supp} \phi(t, \cdot) \subset \{ x \in \mathbb{R}^3 : |x| < t + R \} \) for some \( R > 0 \), where the constant \( C \) on the right-hand side of (1.25) does depend upon \( R \). We avoid using (1.25) and instead employ the trace-type inequality (see Lemma 2.5 below), which plays a key role in estimating the nonlinear terms on the region \( \{ x \in \mathbb{R}^3 : |x| > (t/2) + 1 \} \) differently from how Alinhac did with the use of (1.25). For completeness, in Appendix we prove the inequality (1.25) in general space dimensions.

In order to show global existence of solutions to the system (1.10), we need the two Alinhac-type energy estimates; one is for the hyperbolic operator

\[
(1.26) \quad \partial_t^2 - \Delta + g_1^{\alpha \beta \gamma}(\partial_\gamma w(t, x)) \partial_{\alpha \beta}^2
\]

with the coefficients \( \{ g_1^{\alpha \beta \gamma} \} \) satisfying the null condition (see (3.7) below, where we will actually consider a little more general operator), and the other is for the operator

\[
(1.27) \quad \partial_t^2 - \Delta + g_2^{\alpha \beta \gamma}(\partial_\gamma v(t, x)) \partial_{\alpha \beta}^2 + g_3^{\alpha \beta \gamma}(\partial_\gamma w(t, x)) \partial_{\alpha \beta}^2
\]

with the coefficients \( \{ g_3^{\alpha \beta \gamma} \} \) satisfying the null condition and with the coefficients \( \{ g_2^{\alpha \beta \gamma} \} \) failing in satisfying the null condition (see (3.8) below). Though in page 92 of [4] the remarkable energy inequality is stated for such hyperbolic operators as (1.26) under the assumption that the variable coefficient \( w(t, x) \) satisfies

\[
(1.28) \quad \sum_{|a| \leq 3} \| \partial Z^a w(t, \cdot) \|_{L^2(\mathbb{R}^3)} \leq C_0 \varepsilon,
\]
it is worthwhile noting that the method of Alinhac is in fact considerably robust and it equally works also for \( w(t, x) \) behaving
\[
\sum_{|a| \leq 3} \| \partial Z^a w(t, \cdot) \|_{L^2(\mathbb{R}^3)} \leq C_0 \varepsilon (1 + t)^\delta
\]
for some \( 0 \leq \delta < 1/2 \). See Proposition 3.1 below. This key fact is very helpful in studying the system (1.10) whose solutions, in particular \( u_2 \), will be far from behaving like free solutions as \( t \to \infty \). We also remark that even for (1.27), we can obtain a useful energy estimate by suitably modifying the proof of the lemma on page 92 of [H]. (See Proposition 3.2 below.) In this way, we generalize the method of Alinhac so as to prove the global existence for the system (1.10) satisfying the weak null condition.

This paper is organized as follows. In the next section, key facts on the nonlinear terms satisfying the null condition are stated and useful inequalities such as the Sobolev type or the trace type are collected. In Section 3, in order to prove Theorem 1.4 the energy estimate is carried out and the desired a priori estimate is obtained. In Section 4, we show (1.18) to complete the proof of Theorem 1.5. In Appendix, we prove (1.25).

2 Preliminaries

As explained in Section 1, in addition to the usual partial differential operators \( \partial_0 := \partial/\partial t \) and \( \partial_i := \partial/\partial x_i \) (\( i = 1, 2, 3 \)), we use \( \Omega_{ij} := x_i \partial_j - x_j \partial_i \), \( L_k := x_k \partial_0 + t \partial_k \) (\( 1 \leq i < j \leq 3 \), \( k = 1, 2, 3 \)) and \( S = t \partial_0 + x \cdot \nabla \). The set of these 11 differential operators is denoted by \( Z = \{Z_0, \ldots, Z_{10}\} = \{\partial_0, \partial_1, \ldots, S\} \). For a multi-index \( a = (a_0, \ldots, a_{10}) \), we set \( Z^a := Z_0^{a_0} \cdots Z_{10}^{a_{10}} \).

We first remark several results concerning commutation relations. Let \([\cdot, \cdot]\) be the commutator: \([A, B] := AB - BA\). It is easy to verify that
\[
[Z_i, \partial_i^2 - \Delta] = 0 \quad \text{for } i = 0, \ldots, 9, \quad [S, \partial_i^2 - \Delta] = -2(\partial_i^2 - \Delta),
\]
\[
[Z_j, \partial_k] = \sum_{i=0}^{3} C_{ij}^{jk} \partial_i, \quad j = 0, \ldots, 10, \quad k = 0, \ldots, 3.
\]

Here \( C_{ij}^{jk} \) denotes a constant depending on \( i, j, \) and \( k \). These can be verified easily.

The next lemma states that the null form is preserved under the differentiation.

**Lemma 2.1.** Suppose that \( \{G^{\alpha\beta\gamma}\} \) and \( \{H^{\alpha\beta}\} \) satisfy the null condition (see (1.11), (1.12) above). For any \( Z_i \) (\( i = 0, \ldots, 10 \)), the equality
\[
Z_i G^{\alpha\beta\gamma}(\partial_\gamma v)(\partial_{\alpha\beta} w) = G^{\alpha\beta\gamma}(\partial_\gamma Z_i v)(\partial_{\alpha\beta} w) + Z_i G^{\alpha\beta\gamma}(\partial_\gamma v)(\partial_{\alpha\beta} Z_i w) + \tilde{G}_i^{\alpha\beta\gamma}(\partial_\gamma v)(\partial_{\alpha\beta} w)
\]
holds with the new coefficients \( \{ \tilde{G}^{\alpha\beta\gamma} \} \) also satisfying the null condition. Also, the equality

\[
Z_i H^{\alpha\beta}(\partial_{\alpha} v)(\partial_{\beta} w) = H^{\alpha\beta}(\partial_{\alpha} Z_i v)(\partial_{\beta} w) + H^{\alpha\beta}(\partial_{\alpha} v)(\partial_{\beta} Z_i w) + \tilde{H}^{\alpha\beta}_i(\partial_{\alpha} v)(\partial_{\beta} w)
\]

holds with the new coefficients \( \{ \tilde{H}^{\alpha\beta}_i \} \) also satisfying the null condition.

For the proof, see, e.g., page 91 of [4].

It is possible to show the following lemma essentially in the same way as in pages 90–91 of [4]. (See also Lemma 2.3 of [18]. The present authors are inspired by these arguments in [4] and [18].) Using (2.5) and (2.6), we will later exploit the fact that for local solutions \( u \), the special derivatives \( T_i u \) have better space-time \( L^2 \)-integrability and improved time decay property of their \( L^\infty(\mathbb{R}^n) \)-norms.

**Lemma 2.2.** Suppose that \( \{ G^{\alpha\beta\gamma} \} \), \( \{ H^{\alpha\beta} \} \) satisfy the null condition. Then, we have

\[
|G^{\alpha\beta\gamma}(\partial_{\gamma} v)(\partial^2_{\alpha\beta} w)| \leq C(|Tv||\partial^2 w| + |\partial v||Tv|),
\]

\[
|H^{\alpha\beta}(\partial_{\alpha} v)(\partial_{\beta} w)| \leq C(|Tv||\partial w| + |\partial v||Tw|).
\]

Here, and in the following, we use the notation

\[
Tv := \left( \sum_{k=1}^{3} |T_k v|^2 \right)^{1/2}, \quad T\partial v := \left( \sum_{k=1}^{3} \sum_{\gamma=0}^{3} |T_k \partial_{\gamma} v|^2 \right)^{1/2}
\]

**Proof.** We may focus on (2.5), because the proof of (2.6) is similar. Using the representation \( \partial_i = T_i - \omega_i \partial_t \) \((i = 1, 2, 3, \omega_i = x_i/|x|)\) and setting \( T_0 = 0, \omega_0 = -1 \), we have

\[
G^{\alpha\beta\gamma}(\partial_{\gamma} v)(\partial^2_{\alpha\beta} w)
\]

\[
= G^{\alpha\beta\gamma}(T\gamma v)(\partial^2_{\alpha\beta} w) - G^{\alpha\beta\gamma}_{\gamma\omega}(\partial_{\omega} v)(\partial^2_{\alpha\beta} w)
\]

\[
= G^{\alpha\beta\gamma}(T\gamma v)(\partial^2_{\alpha\beta} w) - G^{\alpha\beta\gamma}_{\gamma\omega}(\partial_{\omega} v)(T\alpha \partial_{\beta} w) + G^{\alpha\beta\gamma}_{\omega\omega\gamma}(\partial_{\omega} v)(\partial_{\beta} w)
\]

\[
= G^{\alpha\beta\gamma}(T\gamma v)(\partial^2_{\alpha\beta} w) - G^{\alpha\beta\gamma}_{\gamma\omega}(\partial_{\omega} v)(T\alpha \partial_{\beta} w)
\]

\[
+ G^{\alpha\beta\gamma}_{\omega\omega\gamma}(\partial_{\omega} v)(T\beta \partial_{\gamma} w) - G^{\alpha\beta\gamma}_{\omega\omega\beta}(\partial_{\omega} v)(\partial^2_{\beta} w).
\]

We find that owing to the null condition, the last term on the right-hand side above vanishes, which shows (2.5).

The next lemma says that the null condition creates cancellation which allows us to handle the quadratic nonlinear terms as higher-order ones in terms of time decay.
Lemma 2.3. If \( \{G^{\alpha\beta\gamma}\} \) satisfies the null condition, then
\[
|G^{\alpha\beta\gamma}(\partial_\gamma v)(\partial^2_{\alpha\beta} w)| \leq C(1 + t)^{-1} \sum_{|\alpha| = 1} (|Z^a v| |\partial^2 w| + |\partial v| |\partial Z^a w|)
\]
holds. Also, if \( \{H^{\alpha\beta}\} \) satisfies the null condition, then
\[
|H^{\alpha\beta}(\partial_\alpha v)(\partial_\beta w)| \leq C(1 + t)^{-1} \sum_{|\alpha| = 1} (|Z^a v| |\partial w| + |\partial v| |Z^a w|)
\]
holds.

Here, and in the following, we use the standard notation
\[
|\partial v| := \left( \sum_{\gamma = 0}^3 |\partial_\gamma v|^2 \right)^{1/2}, \quad |\partial^2 v| := \left( \sum_{\alpha, \beta = 0}^3 |\partial^2_{\alpha\beta} v|^2 \right)^{1/2}.
\]

Proof. Using the fact
\[
|Tv(t, x)| \leq C(1 + t)^{-1} \sum_{|\alpha| = 1} |Z^a v(t, x)|
\]
(see page 91 of [4], and see also (3.26) below) together with the commutation relation (2.2), we can derive (2.9)–(2.10) from (2.5)–(2.6).

The following lemma is concerned with Sobolev-type inequalities.

Lemma 2.4. For any smooth function \( v(t, x) \in C^\infty((0, \infty) \times \mathbb{R}^3) \) decaying sufficiently fast as \( |x| \to \infty \), the inequality
\[
(1 + t + |x|)(1 + |t - |x||)^{1/2}|v(t, x)| \leq C \sum_{|\alpha| \leq 2} \|Z^a v(t, \cdot)\|_{L^2(\mathbb{R}^3)}
\]
holds. Moreover, for any \( p \) with \( 2 \leq p \leq 6 \) there exists a positive constant \( C \) depending on \( p \) such that the inequality
\[
\|(1 + t + |\cdot|)^{2((1/2)-(1/p))}(1 + |t - |\cdot||)^{(1/2)-(1/p)}v(t, \cdot)\|_{L^p(\mathbb{R}^3)} \leq C \sum_{|\alpha| \leq 1} \|Z^a v(t, \cdot)\|_{L^2(\mathbb{R}^3)}
\]
holds.

Proof. See [14] for (2.13), and [8] for (2.14).

We also use the following trace-type inequality.
Lemma 2.5. Let $n \geq 2$. For any $s$ with $1/2 < s < n/2$, there exists a positive constant depending only on $n, s$ such that if $v = v(x)$ decays sufficiently fast as $|x| \to \infty$, then the inequality

$$r^{(n/2) - s} \|v(r \cdot)\|_{L^p(S^{n-1})} \leq C \|v\|_{\dot{H}^s(\mathbb{R}^n)}, \quad \frac{n - 1}{p} = \frac{n}{2} - s$$

holds, where $r := |x|$.

Proof. The proof uses the trace-type inequality due to Hoshiro [11] (for $n \geq 3$) and Fang and Wang [7] (for $n = 2$), together with the Sobolev embedding on $S^{n-1}$. See, e.g., Proposition 2.4 of [9].

3 Proof of Theorem 1.4

Since the second order quasi-linear hyperbolic system (1.10) can be written in the form of the first order quasi-linear symmetric hyperbolic system (see, e.g., (5.9) of Racke [22]), the standard local existence theorem (see, e.g., Theorem 5.8 of [22]) applies to the Cauchy problem for (1.10). In what follows, we assume that the initial data are smooth, compactly supported, and small so that

$$W_4(u_1(0)) + W_4(u_2(0)) \leq \min \left\{ \frac{\varepsilon_1}{C_0}, \frac{\varepsilon_2}{C_0}, \frac{C_0}{6C_3} \right\}$$

may hold. (See Propositions 3.1, 3.2, and 3.3 below for the constants $\varepsilon_1, \varepsilon_2, C_0,$ and $C_3$. ) We thus know that a unique, smooth solution to (1.10) exists at least for a short time interval, and it is compactly supported at any fixed time by the finite speed of propagation. We therefore also know that the set

$$\{ T > 0 : \text{There exists a smooth solution } (u_1(t, x), u_2(t, x)) \text{ to (1.10) defined for all } (t, x) \in (0, T) \times \mathbb{R}^3 \text{ satisfying}$$

$$\sup_{0 < t < T} (W_4(u_1(t)) + (1 + t)^{-\delta}W_4(u_2(t))) < \infty \}$$

is not empty. We define $T^*$ as the supremum of this set. (If we assume $T^* < \infty$, then we will get contradiction and hence obtain global existence.) Using this local smooth solution $u = (u_1, u_2)$, we next define

$$A(u(t)) := W_4(u_1(t)) + (1 + t)^{-\delta}W_4(u_2(t)).$$
Thanks to the compactness of the support of the initial data and the finiteness of the propagation speed of the solution, we can easily verify the important property that

\[(3.4) \quad A(u(t)) \in C([0, T^*]).\]

Let \( C_0 \geq 2 \) be the constant determined later (see Proposition 3.3 below). Owing to (3.4) and the absolute continuity of integral, the set

\[(3.5) \quad \{ T \in (0, T^*) : \sup_{0 < t < T} A(u(t)) + \sum_{|a| \leq 3} \left( \int_0^T \int_{\mathbb{R}^3} (t - r)^{-1 - 2\eta} \| T_i Z^a u_1(t, x) \|^2 dt dx \right)^{1/2}
\]

\[\quad + \sum_{|a| \leq 3} \sup_{0 < t < T} (1 + t)^{-\delta} \left( \int_0^t \int_{\mathbb{R}^3} (\tau - r)^{-1 - 2\eta} \| T_i Z^a u_2(\tau, x) \|^2 d\tau dx \right)^{1/2}
\]

\[\quad \leq C_0 (W_4(u_1(0)) + W_4(u_2(0))) \}

is not empty. Let us define \( T_* \) as the supremum of this set. By definition, we know \( T_* \leq T^* \). We are going to show the key a priori estimate: we actually have for all \( T \in (0, T_*) \)

\[(3.6) \quad \sup_{0 < t < T} A(u(t)) + \sum_{|a| \leq 3} \left( \int_0^T \int_{\mathbb{R}^3} (t - r)^{-1 - 2\eta} \| T_i Z^a u_1(t, x) \|^2 dt dx \right)^{1/2}
\]

\[\quad + \sum_{|a| \leq 3} \sup_{0 < t < T} (1 + t)^{-\delta} \left( \int_0^t \int_{\mathbb{R}^3} (\tau - r)^{-1 - 2\eta} \| T_i Z^a u_2(\tau, x) \|^2 d\tau dx \right)^{1/2}
\]

\[\leq \frac{2}{3} C_0 (W_4(u_1(0)) + W_4(u_2(0))).\]

To obtain the estimate (3.6), we use the ghost weight technique of Alinhac. Define the linearized hyperbolic operators \( P_1 \) and \( P_2 \) as follows:

\[(3.7) \quad P_1 := \partial_t^2 - \Delta + g_1^{11,\alpha\beta\gamma}(\partial_\gamma \varphi)\partial_\alpha\beta + g_1^{21,\alpha\beta\gamma}(\partial_\gamma \psi)\partial_\alpha\beta,
\]

\[(3.8) \quad P_2 := \partial_t^2 - \Delta + g_2^{12,\alpha\beta\gamma}(\partial_\gamma \varphi)\partial_\alpha\beta + g_2^{22,\alpha\beta\gamma}(\partial_\gamma \psi)\partial_\alpha\beta
\]

for \( \varphi, \psi \in C^\infty((0, T) \times \mathbb{R}^3) \).

**Proposition 3.1.** Suppose the symmetry condition: there hold \( g_1^{11,\alpha\beta\gamma} = g_1^{11,\beta\alpha\gamma}, \) 

\( g_1^{21,\alpha\beta\gamma} = g_1^{21,\beta\alpha\gamma} \) for all \( \alpha, \beta, \gamma = 0, \ldots, 3 \). Also, suppose the null condition: there holds

\[(3.9) \quad g_1^{11,\alpha\beta\gamma} X_\alpha X_\beta X_\gamma = g_1^{21,\alpha\beta\gamma} X_\alpha X_\beta X_\gamma = 0.
\]
for all $X = (X_0, \ldots, X_3)$ satisfying $X_0^2 = X_1^2 + X_2^2 + X_3^2$.

Let $\eta > 0$, $\delta > 0$ satisfy $\eta + \delta < 1/2$. Then, there exist two constants $\varepsilon_1$ and $C_1 (0 < \varepsilon_1 < 1, C_1 > 0)$ depending only on $\eta$, $\delta$ and the coefficients $g_1^{11,\alpha\beta\gamma}$, $g_1^{21,\alpha\beta\gamma}$ such that if the functions $\varphi$ and $\psi$ satisfy

$$\sup_{0 < t < T} (W_4(\varphi(t)) + (1 + t)^{-\delta} W_4(\psi(t))) \leq \varepsilon_1,$$

then the estimate

$$\sup_{0 < t < T} \|\partial u(t, \cdot)\|_{L^2(\mathbb{R}^3)} + \left( \int_0^T \int_{\mathbb{R}^3} \langle t - r \rangle^{-1-2\eta} \sum_{i=1}^3 |T_i u(t, x)|^2 dtdx \right)^{1/2}$$

$$\leq C_1 \left( \|\partial u(0, \cdot)\|_{L^2(\mathbb{R}^3)} + \int_0^T \|P_1 u(t, \cdot)\|_{L^2(\mathbb{R}^3)} dt \right)$$

holds.

**Proposition 3.2.** Suppose the symmetry condition: there hold $g_2^{12,\alpha\beta\gamma} = g_2^{22,\alpha\beta\gamma}$, $g_2^{22,\alpha\beta\gamma} = g_2^{22,\alpha\beta\gamma} = g_2^{22,\alpha\beta\gamma}$ for all $\alpha, \beta, \gamma = 0, \ldots, 3$. Also, suppose the null condition only on $\{g_2^{22,\alpha\beta\gamma}\}$. Let $\eta > 0$, $\delta > 0$ satisfy $\eta + \delta < 1/2$. Then, there exist two constants $\varepsilon_2$ and $C_2 (0 < \varepsilon_2 < 1, C_2 > 0)$ depending only on $\eta$, $\delta$ and the coefficients $g_2^{12,\alpha\beta\gamma}$, $g_2^{22,\alpha\beta\gamma}$ such that if the functions $\varphi$ and $\psi$ satisfy

$$\sup_{0 < t < T} (W_4(\varphi(t)) + (1 + t)^{-\delta} W_4(\psi(t))) \leq \varepsilon_2,$$

then the estimate

$$\sup_{0 < t < T} (1 + t)^{-\delta} \|\partial u(t, \cdot)\|_{L^2(\mathbb{R}^3)}$$

$$+ \sup_{0 < t < T} (1 + t)^{-\delta} \left( \int_0^t \int_{\mathbb{R}^3} \langle t - r \rangle^{-1-2\eta} \sum_{i=1}^3 |T_i u(t, x)|^2 dtdx \right)^{1/2}$$

$$\leq C_2 \|\partial u(0, \cdot)\|_{L^2(\mathbb{R}^3)} + C_2 \sup_{0 < t < T} \left( (1 + t)^{-2\delta} \int_0^t (1 + \tau)^{-\delta} \|P_2 u(\tau, \cdot)\|_{L^2(\mathbb{R}^3)} d\tau \right)$$

holds.

**Proof.** We first prove Proposition 3.1. We basically follow the argument on pages 92 to 94 of [4]. Let $a = a(t - r)$ be chosen later. In the same way as on page 93 of [4], we get by using $T_i = \partial_i + \omega_i \partial_t$ ($\omega_i := x_i / |x|$, $i = 1, 2, 3$)

$$e^a(\Box u) \partial_t u = \frac{1}{2} \partial_t \left\{ e^a (\partial_t u)^2 + |\nabla u|^2 \right\}$$

$$- \nabla \cdot \{ \cdots \} - \frac{1}{2} e^a a'(t - r) \sum_{i=1}^3 (T_i u)^2,$$
We will follow page 93 of [4] to deal with $q$, and in the following as well, because it vanishes after integration over $\mathbb{R}^3$, we write such a "harmless" term as $\nabla \cdot \{ \cdots \}$. Obviously, we also get the equality similar to (3.15), with $g_{11,\alpha\beta\gamma}$ and $\varphi$ replaced by $g_{21,\alpha\beta\gamma}$ and $\psi$, respectively. Therefore, we have

\[
\begin{align*}
(3.15) & \quad e^a g_{11,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\alpha^2 u)(\partial_t u) \\
& = -\frac{1}{2} \partial_t \left\{ e^a g_{11,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u) - 2e^a g_{11,0,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_t u) \right\} \\
& \quad + \nabla \cdot \{ \cdots \} + \frac{1}{2} e^a \left\{ g_{11,\alpha\beta\gamma}(\partial_\gamma^2 \varphi)(\partial_\alpha u) - 2g_{11,0,\alpha\beta\gamma}(\partial_\gamma^2 \varphi)(\partial_\beta u)(\partial_t u) \right\} \\
& \quad + \frac{1}{2} e^a a'(t - r) \left\{ g_{11,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u) - 2g_{11,0,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_t u) \right\} \\
& \quad + 2\omega_1 e^a q_{11,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_t u) \right\}. \\
\end{align*}
\]

Here, and in the following as well, because it vanishes after integration over $\mathbb{R}^3$, we write such a "harmless" term as $\nabla \cdot \{ \cdots \}$. Obviously, we also get the equality similar to (3.15), with $g_{11,\alpha\beta\gamma}$ and $\varphi$ replaced by $g_{21,\alpha\beta\gamma}$ and $\psi$, respectively. Therefore, we have

\[
\begin{align*}
(3.16) & \quad e^a (P_t u)(\partial_t u) \\
& = \frac{1}{2} \partial_t \left\{ e^a (\partial_\alpha u)^2 + |\nabla u|^2 \right. \\
& \quad - g_{11,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u) + 2g_{11,0,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_t u) \\
& \quad - g_{21,\alpha\beta\gamma}(\partial_\gamma \psi)(\partial_\beta u)(\partial_\alpha u) + 2g_{21,0,\alpha\beta\gamma}(\partial_\gamma \psi)(\partial_\beta u)(\partial_t u) \right\} \\
& \quad + \nabla \cdot \{ \cdots \} + e^a q, \\
\end{align*}
\]

where $q = q_1 - a'(t - r)(q_2/2)$,

\[
\begin{align*}
(3.17) & \quad q_1 = \frac{1}{2} g_{11,\alpha\beta\gamma}(\partial_\gamma^2 \varphi)(\partial_\beta u)(\partial_\alpha u) - g_{11,0,\alpha\beta\gamma}(\partial_\gamma^2 \varphi)(\partial_\beta u)(\partial_t u) \\
& \quad + \frac{1}{2} g_{21,\alpha\beta\gamma}(\partial_\gamma^2 \psi)(\partial_\beta u)(\partial_\alpha u) - g_{21,0,\alpha\beta\gamma}(\partial_\gamma^2 \psi)(\partial_\beta u)(\partial_t u), \\
\end{align*}
\]

and, for $\omega_0 = -1$

\[
\begin{align*}
(3.18) & \quad q_2 = \sum_{i=1}^{3} (T_i u)^2 \\
& \quad - g_{11,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u) + 2g_{11,0,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(-\omega_\alpha)(\partial_t u) \\
& \quad - g_{21,\alpha\beta\gamma}(\partial_\gamma \psi)(\partial_\beta u)(\partial_\alpha u) + 2g_{21,0,\alpha\beta\gamma}(\partial_\gamma \psi)(\partial_\beta u)(-\omega_\alpha)(\partial_t u). \\
\end{align*}
\]

We will follow page 93 of [4] to deal with $q_1$, while to treat $q_2$, we need to proceed differently in part from page 94 of [4]. Writing $g^{\alpha\beta\gamma} = g_{11,\alpha\beta\gamma}$ for short, using $\partial_i = T_i - \omega_i \partial_i$ ($\omega_i = x_i/|x|$, $i = 1, 2, 3$), and setting $T_0 = 0$, $\omega_0 = -1$ as before, we have for the first term
on the right-hand side of (3.17)

\begin{equation}
(3.19) \quad g^{\alpha\beta\gamma}(\partial^2_{\gamma\beta\varphi})(\partial_\beta u)(\partial_\alpha u)
= g^{\alpha\beta\gamma}(T_\gamma \partial_\beta \varphi)(\partial_\beta u)(\partial_\alpha u) - g^{\alpha\beta\gamma} \omega_\gamma(\partial^2_\beta \varphi)(\partial_\beta u)(\partial_\alpha u)
= g^{\alpha\beta\gamma}(T_\gamma \partial_\beta \varphi)(\partial_\beta u)(\partial_\alpha u) - g^{\alpha\beta\gamma} \omega_\gamma(\partial^2_\beta \varphi)(T_\beta u)(\partial_\alpha u)
+ g^{\alpha\beta\gamma} \omega_\beta \omega_\gamma(\partial^2_\varphi)(\partial_\alpha u)
= g^{\alpha\beta\gamma}(T_\gamma \partial_\beta \varphi)(\partial_\beta u)(\partial_\alpha u) - g^{\alpha\beta\gamma} \omega_\gamma(\partial^2_\beta \varphi)(T_\beta u)(\partial_\alpha u)
+ g^{\alpha\beta\gamma} \omega_\beta \omega_\gamma(\partial^2_\varphi)(\partial_\alpha u) - g^{\alpha\beta\gamma} \omega_\alpha \omega_\beta \omega_\gamma(\partial^2_\varphi)(\partial_\alpha u)^2.
\end{equation}

Since \(g_1^{1,\alpha\beta\gamma}\omega_\alpha \omega_\beta \omega_\gamma = 0\) due to the null condition, we finally obtain

\begin{equation}
(3.20) \quad |g_1^{1,\alpha\beta\gamma}(\partial^2_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u)| \leq C|T \partial_\beta \varphi||\partial_\alpha u|^2 + C|\partial^2_\gamma \varphi||T u||\partial_\alpha u|.
\end{equation}

(For the definition of \(|Tv|\) and \(|\partial v|\), see (2.7), (2.11).) Similarly, we can get for the second term on the right-hand side of (3.17)

\begin{equation}
(3.21) \quad |g_1^{1,\alpha\beta\gamma}(\partial^2_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u)| \leq C|T \partial_\beta \varphi||\partial_\alpha u| + C|\partial^2_\gamma \varphi||T u||\partial_\alpha u|.
\end{equation}

(For the definition of \(|T \partial v|\) and \(|\partial^2 v|\), see (2.7), (2.11).) Obviously, for the third and fourth terms on the right-hand side of (3.17), we can obtain the inequality similar to (3.20) and (3.21), respectively, naturally with \(\varphi\) replaced by \(\psi\).

For the second and third terms on the right-hand side of (3.18), we can proceed as above to obtain

\begin{align}
(3.22) \quad |g_1^{1,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u)| & \leq C|T \partial_\gamma \varphi||\partial_\alpha u|^2 + C|\partial_\gamma \varphi||T u||\partial_\alpha u|, \\
(3.23) \quad |g_1^{1,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(-\omega_\alpha)(\partial_\alpha u)| & \leq C|\partial_\gamma \varphi||T u||\partial_\alpha u| + C|T \varphi||\partial_\alpha u||\partial_\alpha u|.
\end{align}

Naturally, the inequalities similar to (3.22) and (3.23) hold for the fourth and fifth terms on the right-hand side of (3.18), respectively, with \(\varphi\) replaced by \(\psi\).

We get by (3.19)–(3.23)

\begin{equation}
(3.24) \quad q_1 \geq -C(|T \partial \varphi| + |T \partial \psi|)|\partial_\alpha u|^2 - C(|\partial^2_\gamma \varphi| + |\partial^2_\gamma \psi|)|T u||\partial_\alpha u|
\end{equation}

and

\begin{equation}
(3.25) \quad q_2 \geq \sum_{i=1}^{3} (T_i u)^2 - C(|T \varphi| + |T \psi|)|\partial_\alpha u|^2 - C(|\partial_\gamma \varphi| + |\partial_\gamma \psi|)|T u||\partial_\alpha u|
\end{equation}

for a positive constant \(C\). To continue the estimate of \(q_1\) and \(q_2\), we use the remarkable improvement of point-wise decay of the special derivatives \(T_{k} v\). Using

\begin{equation}
(3.26) \quad T_k = \frac{1}{t} \left(L_k - \omega_k (r - t) \partial_t \right) = \frac{1}{r} \left(L_k + (r - t) \partial_t \right)
\end{equation}
we get

\[ \partial_t = \frac{tS - \sum_{j=1}^{3} x_j L_j}{t^2 - r^2}, \quad \partial_k = \frac{tL_k + \sum_{j=1}^{3} x_j \Omega_{kj} - x_k S}{t^2 - r^2}, \]

which yield

\[ T_k \partial_\gamma \varphi \leq C(1 + t + r)^{-1} \sum_{|a|=1} |Z^a \partial_\gamma \varphi| \]

\[ \leq C(1 + t + r)^{-2}(1 + |t - r|)^{-1/2}W_4(\varphi(t)), \]

\[ T_k \partial_\gamma \psi \leq C(1 + t + r)^{-2+\delta}(1 + |t - r|)^{-1/2}((1 + t)^{-\delta}W_4(\psi(t))), \]

which yield

\[ -C(|T \partial \varphi| + |T \partial \psi|)\partial u|^2 \geq -C(1 + t)^{-2+\delta}F(t)\partial u|^2, \]

where, and in the following as well, we use the notation

\[ \Phi(t) := W_4(\varphi(t)) + (1 + t)^{-\delta}W_4(\psi(t)). \]

Furthermore, since we have by (2.13)

\[ |\partial_t^2 \varphi| + |\partial_t^2 \psi| \leq C(1 + t + r)^{-1+\delta}(1 + |t - r|)^{-1/2}F(t) \]

\[ \leq C(1 + t + r)^{-1+\delta+\eta}(1 + |t - r|)^{-(1/2)-\eta}F(t), \]

we obtain

\[ -C(|\partial_t^2 \varphi| + |\partial_t^2 \psi|)Tu|\partial u| \]

\[ \geq -C(1 + |t - r|)^{-(1/2)-\eta}Tu|F(t)^{1/2}(1 + t + r)^{-1+\delta+\eta}|\partial u|F(t)^{1/2} \]

\[ \geq -C(1 + |t - r|)^{1-2\eta}|Tu|^2F(t) - C(1 + t + r)^{-2+2\delta+2\eta}|\partial u|^2F(t). \]

Combining (3.24) with (3.30), (3.33), we get

\[ q_1 \geq -C(1 + |t - r|)^{-1-2\eta}F(t)|Tu|^2 \]

\[ -C(1 + t)^{-2+\delta}F(t)|\partial u|^2 - C(1 + t)^{-2+2\delta+2\eta}F(t)|\partial u|^2. \]

To estimate \( q_2 \) from below, we proceed differently from what Alinhac did by using (1.25) on page 94 of [4]. We first divide \((0, \infty) \times \mathbb{R}^3\) into the two pieces: \( D_{\text{int}} := \{(t, x) : |x| < (t/2) + 1\} \) and its complement \( D_{\text{ext}} \). Using (2.13) and (3.18), we easily get for \((t, x) \in D_{\text{int}}\)

\[ q_2 \geq |Tu|^2 - C(1 + t)^{-3/2+\delta}F(t)|\partial u|^2. \]
On the other hand, for \((t, x) \in D_{\text{ext}}\), we use (3.25). Since we have by the Sobolev embedding on \(S^2\) and (2.15)

\[
|T_k \varphi| \leq C(1 + t + r)^{-1} \sum_{|a|=1} |Z^a \varphi|
\]

\[
\leq C(1 + t + r)^{-1} \left( \sum_{|a|=1} \|Z^a \varphi(r \cdot)\|_{L^4(S^2)} + \sum_{1 \leq i < j \leq 3} \|\Omega_{ij} Z^a \varphi(r \cdot)\|_{L^4(S^2)} \right)
\]

\[
\leq C(1 + t + r)^{-1} r^{-1/2} W_4(\varphi(t)),
\]

we get for \((t, x) \in D_{\text{ext}}\)

\[
|T \varphi| + |T \psi| \leq C(1 + t)^{-(3/2)+\delta} \Phi(t),
\]

which yields for \((t, x) \in D_{\text{ext}}\)

\[
q_2 \geq |Tu|^2 - C(1 + t)^{-(3/2)+\delta} \Phi(t) |\partial u|^2
\]

\[
- C(1 + |t - r|)^{-1-2\eta} \Phi(t) |Tu|^2 - C(1 + t)^{-2+2\delta+2\eta} \Phi(t) |\partial u|^2.
\]

Now we are ready to finish the proof of Proposition 3.1. Let us choose the function \(a = a(\rho) \ (\rho \in \mathbb{R})\) as

\[
a(\rho) = - \int_0^\rho (1 + |s|)^{-1-2\eta} ds
\]

so that \(a'(\rho) = -(1 + |\rho|)^{-1-2\eta}\) may hold. Remark that there exists a positive constant \(c_1\) such that \(c_1 \leq e^a \leq c_1^{-1}\), because \(a\) is bounded. We then observe for \(a = a(t - r)\)

\[
\int_{\mathbb{R}^3} e^a q dx = \int_{\mathbb{R}^3} e^a (q_1 + (1 + |t - r|)^{-1-2\eta} q_2) dx
\]

\[
\geq \left( c_1 - c_2 \Phi(t) \right) \int_{\mathbb{R}^3} (1 + |t - r|)^{-1-2\eta} |Tu|^2 dx
\]

\[
- c_3 \max\{ (1 + t)^{-(3/2)+\delta}, (1 + t)^{-2+2\delta+2\eta} \} \Phi(t) \int_{\mathbb{R}^3} |\partial u|^2 dx,
\]

where \(c_2\) and \(c_3\) are positive constants. Suppose that \(\sup_{0 < t < T} \Phi(t)\) is sufficiently small so that

\[
c_1 - c_2 \sup_{0 < t < T} \Phi(t) \geq \frac{c_1}{2},
\]

\[
- c_3 \int_0^\infty \max\{ (1 + t)^{-(3/2)+\delta}, (1 + t)^{-2+2\delta+2\eta} \} dt \sup_{0 < t < T} \Phi(t) \geq -c_4
\]

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(c_4 is a sufficiently small positive constant). By integrating (3.16) over \((0, T) \times \mathbb{R}^3\) and then using the Young inequality to get

\[
\int_0^T \| P_1 u(t) \|_{L^2(\mathbb{R}^3)} dt \sup_{0 < t < T} \| \partial u(t) \|_{L^2(\mathbb{R}^3)} \leq C \left( \int_0^T \| P_1 u(t) \|_{L^2(\mathbb{R}^3)} dt \right)^2 + C^{-1} \left( \sup_{0 < t < T} \| \partial u(t) \|_{L^2(\mathbb{R}^3)} \right)^2
\]

for a sufficiently large positive constant \(C\), and finally moving the second term on the right-hand side above to the other side of the resulting inequality, we obtain (3.11).

Let us next prove Proposition 3.2. We assume the null condition on \(\{g_{22,\alpha\beta\gamma}\}\) but not on \(\{g_{12,\alpha\beta\gamma}\}\). We can proceed as in (3.19)–(3.25), except the difference that we must take account of the terms

\[
g_{22,\alpha\beta\gamma} \omega_\alpha \omega_\beta \omega_\gamma (\partial_i^2 \varphi)(\partial_i u)^2, \quad i = 1, 2
\]

which do not always vanish. We therefore get

\[
q_1 \geq -C|\partial_i^2 \varphi| (\partial_i u)^2 - C(|T \partial \varphi| + |T \partial \psi|)|\partial u|^2 - C(|\partial_i^2 \varphi| + |\partial_i^2 \psi|)|Tu||\partial u|
\]

and

\[
q_2 \geq \sum_{i=1}^3 (T_i u)^2 - C|\partial_i \varphi| (\partial_i u)^2 - C(|T \varphi| + |T \psi|)|\partial u|^2 - C(|\partial_i \varphi| + |\partial_i \psi|)|Tu||\partial u|
\]

in place of (3.24)–(3.25). These yield

\[
\int_{\mathbb{R}^3} e^\alpha q dx \geq (c_1 - c_5 \Phi(t)) \int_{\mathbb{R}^3} (1 + |t - r|)^{-1-2\eta} |Tu|^2 dx

- C(1 + t)^{-1+2\delta} \Phi(t) \left( (1 + t)^{-2\delta} \int_{\mathbb{R}^3} |\partial u(t, x)|^2 dx \right),
\]

where \(c_5\) is a positive constant. Suppose that \(\sup_{0 < t < T} \Phi(t)\) is small so that

\[
c_1 - c_5 \sup_{0 < t < T} \Phi(t) \geq \frac{c_1}{2}.
\]
Then, we get for $0 < t < T$ (cf. (3.16))

\[
\frac{1}{2} \int_{\mathbb{R}^3} e^a \left( (\partial_t u)^2 + |\nabla u|^2 \right)
- g_2^{12,\alpha\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_\alpha u) - 2 g_2^{12,\beta\gamma}(\partial_\gamma \varphi)(\partial_\beta u)(\partial_t u)
- g_2^{22,\alpha\beta\gamma}(\partial_\gamma \psi)(\partial_\beta u)(\partial_\alpha u) - 2 g_2^{22,\beta\gamma}(\partial_\gamma \psi)(\partial_\beta u)(\partial_t u) \right]_{\tau = t}^{\tau = 0}
+
\frac{1}{2} c_1 \int_0^t \int_{\mathbb{R}^3} (1 + |\tau - r|)^{-1-2\eta} |Tu(\tau, x)|^2 dxd\tau
- c_6 (1 + t)^{2\delta} \left( \sup_{0 < \tau < T} \Phi(\tau) \right) \sup_{0 < \tau < T} \left( (1 + \tau)^{-2\delta} \int_{\mathbb{R}^3} |\partial u(\tau, x)|^2 dx \right)
\leq \int_0^t \| P_2 u(\tau) \|_{L^2(\mathbb{R}^3)} \| \partial_t u(\tau) \|_{L^2(\mathbb{R}^3)} d\tau.
\]

Suppose further that $c_6 \sup_{0 < \tau < T} \Phi(t)$ is small enough. We divide both sides of (3.44) by $(1 + t)^{2\delta}$ and use the Young inequality to get

\[
(1 + t)^{-2\delta} \int_0^t \| P_2 u(\tau) \|_{L^2(\mathbb{R}^3)} \| \partial_t u(\tau) \|_{L^2(\mathbb{R}^3)} d\tau
\leq (1 + t)^{-2\delta} \int_0^t (1 + \tau)^{\delta} \| P_2 u(\tau) \|_{L^2(\mathbb{R}^3)} d\tau \sup_{0 < \tau < T} (1 + \tau)^{-\delta} \| \partial_t u(\tau) \|_{L^2(\mathbb{R}^3)}
\leq C \sup_{0 < \tau < T} \left( (1 + t)^{-2\delta} \int_0^t (1 + \tau)^{\delta} \| P_2 u(\tau) \|_{L^2(\mathbb{R}^3)} d\tau \right)^2
+ C^{-1} \left( \sup_{0 < \tau < T} (1 + \tau)^{-\delta} \| \partial_t u(\tau) \|_{L^2(\mathbb{R}^3)} \right)^2,
\]
where $C$ is a sufficiently large constant. Since $C^{-1}$ is small enough, we finally obtain (3.13).

Next, let us carry out the energy estimate for $u_1$ and $u_2$.

**Proposition 3.3.** Set $C_0 := 2 \max\{1, C_1, C_2\}$ for the constants $C_1$ and $C_2$ (see (3.11), (3.13)). Suppose that the initial data satisfies

\[
C_0 \left( W_4(u_1(0)) + W_4(u_2(0)) \right) \leq \min\{\varepsilon_1, \varepsilon_2\}
\]
(see (3.10), (3.12) for $\varepsilon_1, \varepsilon_2$) and the local solution $(u_1, u_2)$ to (1.10) satisfies for some
\( T > 0 \)

\[
\begin{align*}
(3.46) & \quad \sup_{0 < t < T} A(u(t)) + \sum_{|a| \leq 3} \left( \int_0^T \int_{\mathbb{R}^3} \langle t - r \rangle^{-1 - 2\eta} \sum_{i=1}^3 |T_i Z^a u_1(t, x)|^2 \, dt \, dx \right)^{1/2} \\
& \quad + \sum_{|a| \leq 3} \sup_{0 < t < T} (1 + t)^{-\delta} \left( \int_0^T \int_{\mathbb{R}^3} \langle \tau - r \rangle^{-1 - 2\eta} \sum_{i=1}^3 |T_i Z^a u_2(\tau, x)|^2 \, d\tau \, dx \right)^{1/2} \\
& \quad \leq C_0 (W_4(u_1(0)) + W_4(u_2(0))).
\end{align*}
\]

Then, there exists a constant \( C_3 > 0 \) such that

\[
(3.47) \quad \sup_{0 < t < T} A(u(t)) + \sum_{|a| \leq 3} \left( \int_0^T \int_{\mathbb{R}^3} \langle t - r \rangle^{-1 - 2\eta} \sum_{i=1}^3 |T_i Z^a u_1(t, x)|^2 \, dt \, dx \right)^{1/2} \\
& \quad + \sum_{|a| \leq 3} \sup_{0 < t < T} (1 + t)^{-\delta} \left( \int_0^T \int_{\mathbb{R}^3} \langle \tau - r \rangle^{-1 - 2\eta} \sum_{i=1}^3 |T_i Z^a u_2(\tau, x)|^2 \, d\tau \, dx \right)^{1/2} \\
& \quad \leq C_1 W_4(u_1(0)) + C_2 W_4(u_2(0)) + C_3 \left( W_4(u_1(0)) + W_4(u_2(0)) \right)^2.
\]

**Proof.** Let us start with the energy estimate for \( u_1 \). In view of Proposition 3.1 with \( u \) replaced by \( Z^a u_1 \ (|a| \leq 3) \), we need to deal with the integral of

\[
(3.48) \quad \| (\partial_t^2 - \Delta + \sum_{i=1}^2 G_1^{i1,\alpha\beta\gamma} (\partial_\gamma u_i) \partial_{\alpha\beta}^2) Z^a u_1(t) \|_{L^2(\mathbb{R}^3)}
\]

\(|a| \leq 3\) from 0 to \( T \). Moreover, thanks to (2.1), (2.3)–(2.4), it suffices to bound the integral from 0 to \( T \) of

\[
(3.49) \quad \sum_{|b| + |c| \leq 3 \atop |e| \leq 2} \left\| G_{bc}^{\alpha\beta\gamma} (\partial_\gamma Z^b u_1) (\partial_{\alpha\beta}^2 Z^c u_1) \right\|_{L^2(\mathbb{R}^3)},
\]

\[
(3.50) \quad \sum_{|b| + |c| \leq 3 \atop |e| \leq 2} \left\| \tilde{G}_{bc}^{\alpha\beta\gamma} (\partial_\gamma Z^b u_2) (\partial_{\alpha\beta}^2 Z^c u_1) \right\|_{L^2(\mathbb{R}^3)},
\]

\[
(3.51) \quad \sum_{|b| + |c| \leq 3} \left\| H_{bc}^{\alpha\beta} (\partial_\alpha Z^b u_1) (\partial_{\beta} Z^c u_1) \right\|_{L^2(\mathbb{R}^3)},
\]

\[
(3.52) \quad \sum_{|b| + |c| \leq 3} \left\| \tilde{H}_{bc}^{\alpha\beta} (\partial_\alpha Z^b u_1) (\partial_{\beta} Z^c u_2) \right\|_{L^2(\mathbb{R}^3)},
\]

\[
(3.53) \quad \sum_{|b| + |c| \leq 3} \left\| \tilde{H}_{bc}^{\alpha\beta} (\partial_\alpha Z^b u_2) (\partial_{\beta} Z^c u_2) \right\|_{L^2(\mathbb{R}^3)},
\]

where the coefficients \( \{ G_{bc}^{\alpha\beta\gamma} \}, \ldots, \{ \tilde{H}_{bc}^{\alpha\beta} \} \) satisfy the null condition. We may focus on (3.50), (3.53), because we can treat the others in a similar (and a little easier) way.
where we have used (2.15) with $p$ here. For $|b| \leq 1$ and $|c| = 2$ or $|b| = 3$ and $|c| = 0$, we get by (2.13)

\begin{equation}
(3.54) \quad \| (\partial_\gamma Z^b u_2)(\partial_{\alpha\beta}^2 Z^c u_1) \|_{L^2(B_t)} \leq C(1 + t)^{-\delta + (3/2)}((1 + t)^{-\delta} W_4(u_2)) W_4(u_1).
\end{equation}

Moreover, for $|b| \leq 2$ and $|c| \leq 1$, we get by the Hölder inequality and (2.14) with $p = 4$

\begin{equation}
(3.55) \quad \| (\partial_\gamma Z^b u_2)(\partial_{\alpha\beta}^2 Z^c u_1) \|_{L^2(B_t)} \leq \| \partial_\gamma Z^b u_2 \|_{L^4(B_t)} \| \partial_{\alpha\beta}^2 Z^c u_1 \|_{L^4(B_t)}
\leq C(1 + t)^{-\delta + (3/2)}((1 + t)^{-\delta} W_4(u_2)) W_4(u_1).
\end{equation}

Similarly, for $(|b|, |c|) = (3, 0), (0, 3)$ we get by (2.13)

\begin{equation}
(3.56) \quad \| (\partial_\gamma Z^b u_2)(\partial_{\alpha\beta} Z^c u_2) \|_{L^2(B_t)} \leq C(1 + t)^{-\delta + (3/2)}((1 + t)^{-\delta} W_4(u_2))^2.
\end{equation}

Also, for $|b| \leq 1$ and $|c| \leq 2$ or for $|b| \leq 2$ and $|c| \leq 1$, we get

\begin{equation}
(3.57) \quad \| (\partial_\gamma Z^b u_2)(\partial_{\alpha\beta} Z^c u_2) \|_{L^2(B_t)} \leq \| \partial_\gamma Z^b u_2 \|_{L^4(B_t)} \| \partial_{\alpha\beta} Z^c u_2 \|_{L^4(B_t)}
\leq C(1 + t)^{-\delta + (3/2)}((1 + t)^{-\delta} W_4(u_2))^2.
\end{equation}

Next, let us consider the $L^2$-norm over $B_t^c$. Lemmas 2.2 and 2.3 play an important role here. For $|b| \leq 1$ and $|c| = 2$, we get by (2.9)

\begin{equation}
(3.58) \quad \| \tilde{G}_{bc}^{\alpha\beta\gamma}(\partial_\gamma Z^b u_2)(\partial_{\alpha\beta}^2 Z^c u_1) \|_{L^2(B_t^c)}
\leq C(1 + t)^{-1} \left( \sum_{|b| \leq 1} \| ZZ^b u_2 \|_{L^\infty(B_t^c)} + \sum_{|b| \leq 1} \| \partial ZZ^b u_2 \|_{L^\infty(B_t^c)} \right) W_4(u_1)
\leq C(1 + t)^{-\delta + (3/2)}((1 + t)^{-\delta} W_4(u_2)) W_4(u_1),
\end{equation}

where we have used (2.15) with $p = 4, s = 1$ together with the Sobolev embedding $W^{1,4}(S^2) \hookrightarrow L^\infty(S^2)$. Moreover, for $|b| \leq 2$ and $|c| \leq 1$, we get by (2.14) with $p = 4$ and (2.15) with $p = 4, s = 1$

\begin{equation}
(3.59) \quad \| \tilde{G}_{bc}^{\alpha\beta\gamma}(\partial_\gamma Z^b u_2)(\partial_{\alpha\beta}^2 Z^c u_1) \|_{L^2(B_t^c)}
\leq C(1 + t)^{-1} (\| ZZ^b u_2 \|_{L^\infty L^4(B_t^c)} \| \partial^2 Z^c u_1 \|_{L^2 L^4(B_t^c)}
+ \| \partial ZZ^b u_2 \|_{L^4(B_t^c)} \| \partial ZZ^c u_1 \|_{L^4(B_t^c)})
\leq C(1 + t)^{-\delta + (3/2)}((1 + t)^{-\delta} W_4(u_2)) W_4(u_1).
\end{equation}
Here, we have used the notation

\[
\|w\|_{L^\infty L^1(B_r^c)} := \sup_{r > (t/2)+1} \|w(r)\|_{L^4(S^2)},
\]

\[
\|w\|_{L^2 L^2(B_r^c)} := \left( \int_{(t/2)+1}^{\infty} \|w(r)\|_{L^4(S^2)}^2 r^2 dr \right)^{1/2}.
\]

On the other hand, for \(|b| = 3\) and \(|c| = 0\) we employ (2.5) and (2.13) to get

\[
(3.60) \quad \left\| \tilde{G}_{bc}^{\alpha\beta\gamma} (\partial_\alpha Z^b u_2)(\partial_\beta Z^c u_2) \right\|_{L^2(B_r^c)}^{L^2(B_r^c)} \leq C(1 + t)^{-1+b} \left\| (t - r)^{-(1/2)-b} T Z^b u_2 \right\|_{L^2(R^3)} W_4(u_1) + CW_4(u_2) \| T \partial u_1 \|_{L^\infty(R^3)}.
\]

Similarly, for \(((b, c)) = (3, 0), (0, 3)\), we employ (2.6) to get

\[
(3.61) \quad \left\| \tilde{H}_{bc}^{\alpha\beta} (\partial_\alpha Z^b u_2)(\partial_\beta Z^c u_2) \right\|_{L^2(B_r^c)}^{L^2(B_r^c)} \leq C(1 + t)^{-1+b+\delta} \left( \sum_{|d|=3} \| (t - r)^{-(1/2)-b} T Z^d u_2 \right\|_{L^2(R^3)}^{L^2(R^3)} \left( (1 + t)^{-\delta} W_4(u_2) \right) + CW_4(u_2).
\]

For \(|b| \leq 2\) and \(|c| \leq 1\) or \(|b| \leq 1\) and \(|c| \leq 2\), we use (2.10) to obtain

\[
(3.62) \quad \left\| \tilde{H}_{bc}^{\alpha\beta}(\partial_\alpha Z^b u_2)(\partial_\beta Z^c u_2) \right\|_{L^2(B_r^c)}^{L^2(B_r^c)} \leq C(1 + t)^{-3/2+2\delta} \left( (1 + t)^{-\delta} W_4(u_2) \right)^2
\]

as in (3.59).

Since \(\delta\) and \(\eta\) are sufficiently small, we have only to explain how to handle the integral from 0 to \(T\) of \(\| T \partial u_1(t) \|_{L^\infty(R^3)} W_4(u_2(t)) \), \(\| T u_2(t) \|_{L^\infty(B_r^c)} W_4(u_2(t)) \), and

\[
(3.63) \quad (1 + t)^{-1+b+\delta} \sum_{|d|=3} \| (t - r)^{-(1/2)-b} T Z^d u_2 \|_{L^2(R^3)}^{L^2(R^3)}
\]

(see (3.60), (3.61)). Using (2.12) first and then (2.13), we get

\[
(3.64) \quad \| T \partial u_1(t) \|_{L^\infty(R^3)} W_4(u_2(t)) \leq C(1 + t)^{-2+b} W_4(u_1(t))(1 + t)^{-\delta} W_4(u_2(t))).
\]

Moreover, using (2.12), the Sobolev embedding \(W^{1,4}(S^2) \hookrightarrow L^\infty(S^2)\), and (2.15), we obtain

\[
(3.65) \quad \| T u_2(t) \|_{L^\infty(B_r^c)} W_4(u_2(t)) \leq C(1 + t)^{-1} \sum_{|a|=1} \| Z^a u_2(t) \|_{L^\infty(B_r^c)} W_4(u_2(t))
\]

\[
\leq C(1 + t)^{-1} \sum_{|a|=1} \| Z^a u_2(t) \|_{L^\infty L^1(B_r^c)} W_4(u_2(t))
\]

\[
\leq C(1 + t)^{-3/2+2\delta} \left( (1 + t)^{-\delta} W_4(u_2(t)) \right)^2.
\]
The estimates (3.64)–(3.66) are strong enough to get the desirable bound. When considering the integral of (3.63) from 0 to $T$, we may suppose $T > 1$ without loss of generality. Using the dyadic decomposition of the interval $(0, T)$, we get as in page 363 of [23],

\begin{equation}
(3.66) \quad \int_0^T (1 + t)^{-1+\eta+\delta} \| \langle t - r \rangle^{-(1/2) - \eta} T Z^d u_2 \|_{L^2(\mathbb{R}^3)} dt \leq \int_0^1 \cdots dt + \sum_{j=0}^{N(T)} \int_{2^j}^{2^{j+1}} \cdots dt
\end{equation}

\begin{align*}
&\leq C \sup_{0 < t < 1} \| \partial Z^d u_2 \|_{L^2(\mathbb{R}^3)} \\
&\quad + \sum_{j=0}^{N(T)} \left( \int_{2^j}^{2^{j+1}} (1 + t)^{-2+2(\eta+\delta)} dt \right)^{1/2} \| \langle t - r \rangle^{-(1/2) - \eta} T Z^d u_2 \|_{L^2((2^j, 2^{j+1}) \times \mathbb{R}^3)} \\
&\leq C \sup_{0 < t < T} (1 + t)^{-\delta} \| \partial Z^d u_2 \|_{L^2(\mathbb{R}^3)} \\
&\quad + C \left( \sum_{j=0}^{\infty} (2^j)^{-\eta + 2\delta} \right) \sup_{0 \leq j \leq N(T)} \| \langle t - r \rangle^{-(1/2) - \eta} T Z^d u_2 \|_{L^2((0, 2^{j+1}) \times \mathbb{R}^3)} \\
&\leq C \sup_{0 < t < T} (1 + t)^{-\delta} W_4(u_2(t)) \\
&\quad + C \sup_{0 < t < T} (1 + t)^{-\delta} \| \langle t - r \rangle^{-(1/2) - \eta} T Z^d u_2 \|_{L^2((0, t) \times \mathbb{R}^3)}.
\end{align*}

Here, $N(T)$ stands for the natural number such that $2^{N(T)} < T \leq 2^{N(T)+1}$, and in (3.66) we have abused the notation to mean $T$ by $2^{N(T)+1}$. We have also used the fact that the series above converges because $\delta$ and $\eta$ are small so that $-(1/2) + \eta + 2\delta < 0$.

Taking the assumption (3.46) into account, we have finally shown

\begin{equation}
(3.67) \quad \sum_{|b| + |c| \leq 3} \sum_{|d| \leq 2} \int_0^T \left\| \left( \tilde{G}_{bc}^{\alpha \beta \gamma} (\partial_{\alpha} Z^b u_2)(\partial_{\beta} Z^c u_1) \right) \right\|_{L^2(\mathbb{R}^3)} dt \\
+ \sum_{|b| + |c| \leq 3} \sum_{|d| \leq 2} \int_0^T \left\| \left( \tilde{H}_{bc}^{\alpha \beta \gamma} (\partial_{\alpha} Z^b u_2)(\partial_{\beta} Z^c u_2) \right) \right\|_{L^2(\mathbb{R}^3)} dt \\
\leq C \left( W_4(u_1(0)) + W_4(u_2(0)) \right)^2,
\end{equation}

as desired. The integral from 0 to $T$ of the $L^2(\mathbb{R}^3)$-norm in (3.49), (3.51), and (3.52) has the same bound. We have finished the energy estimate for $u_1$.

Let us turn our attention to the energy estimate for $u_2$. Taking Proposition 3.2 into account and recalling the argument above for the energy estimate for $u_1$, we may focus
on

\begin{align}
(3.68) \quad & \sum_{|b|+|c|\leq 3 \atop |a| \leq 2} \left\| G_{bc}^{\alpha \beta \gamma} (\partial_\gamma Z^b u_1) (\partial_{\alpha \beta}^2 Z^c u_2) \right\|_{L^2(\mathbb{R}^3)} , \\
(3.69) \quad & \sum_{|b|+|c|\leq 3} \left\| H_{bc}^{\alpha \beta} (\partial_\alpha Z^b u_1) (\partial_\beta Z^c u_2) \right\|_{L^2(\mathbb{R}^3)} , \\
(3.70) \quad & \sum_{|b|+|c|\leq 3} \left\| \tilde{H}_{bc}^{\alpha \beta} (\partial_\alpha Z^b u_1) (\partial_\beta Z^c u_1) \right\|_{L^2(\mathbb{R}^3)} ,
\end{align}

where the coefficients \{\(G_{bc}^{\alpha \beta \gamma}\), \(H_{bc}^{\alpha \beta}\), \(\tilde{H}_{bc}^{\alpha \beta}\)} do not necessarily satisfy the null condition. Here we safely omit the explanation of how to handle such terms as \(\tilde{G}_{bc}^{\alpha \beta \gamma}(\partial_\gamma Z^b u_2)(\partial_{\alpha \beta}^2 Z^c u_2)\), \(\tilde{H}_{bc}^{\alpha \beta}(\partial_\alpha Z^b u_2)(\partial_\beta Z^c u_2)\) with \{\(\tilde{G}_{bc}^{\alpha \beta \gamma}\), \(\tilde{H}_{bc}^{\alpha \beta}\)} satisfying the null condition, because we have already done with the estimate for them in the course of the energy estimate for \(u_1\) above.

Using (2.13)-(2.14), we get in the standard way

\begin{align}
(3.71) \quad & (1 + t)^{-\delta} \int_0^t (1 + \tau)^\delta \sum_{|b|+|c|\leq 3 \atop |a| \leq 2} \left\| G_{bc}^{\alpha \beta \gamma} (\partial_\gamma Z^b u_1) (\partial_{\alpha \beta}^2 Z^c u_2) \right\|_{L^2(\mathbb{R}^3)} d\tau \\
& \quad \leq C(1 + t)^{-\delta} \int_0^t (1 + \tau)^{-1+2\delta} d\tau \left( \sup_{0 < t < T} W_4(u_1(t)) \right) \left( \sup_{0 < t < T} (1 + t)^{-\delta} W_4(u_2(t)) \right) \\
& \quad \leq C \left( W_4(u_1(0)) + W_4(u_2(0)) \right)^2.
\end{align}

We can deal with (3.69), (3.70) in the same way as we have just done in (3.71). We have finished the energy estimate for \(u_2\). The proof of Proposition 3.3 has been finished. \(\square\)

Now we are ready to complete the proof of the key a priori estimate (3.6). Thanks to the size condition (3.1), we see by (3.47) that there holds for all \(T \in (0, T^*)\)

\begin{align}
(3.72) \quad & \sup_{0 < t < T} A(u(t)) + \sum_{|a| \leq 3} \left( \int_0^T \int_{\mathbb{R}^3} (t - r)^{-1-2\eta} \sum_{i=1}^3 |T_i Z^a u_1(t, x)|^2 dt dx \right)^{1/2} \\
& \quad + \sum_{|a| \leq 3} \sup_{0 < t < T} (1 + t)^{-\delta} \left( \int_0^T \int_{\mathbb{R}^3} (t - r)^{-1-2\eta} \sum_{i=1}^3 |T_i Z^a u_2(t, x)|^2 dt dx \right)^{1/2} \\
& \quad \leq \frac{C_0}{2} \left( W_4(u_1(0)) + W_4(u_2(0)) \right) + \frac{C_0}{6} \left( W_4(u_1(0)) + W_4(u_2(0)) \right) \\
& \quad = \frac{2}{3} C_0 \left( W_4(u_1(0)) + W_4(u_2(0)) \right),
\end{align}

which completes the proof of (3.6).

We are in a position to show that the local solution exists globally in time. We first remark that the equality \(T_* = T^*\) holds. (The definition of \(T_*\) and \(T^*\) is given below (3.2)
and (3.5), respectively.) Indeed, if we suppose $T_* < T^*$, then we see by (3.6), (3.4) and
the absolute continuity of integral that there exists $T' \in (T_*, T^*)$ such that

\begin{equation}
\sup_{0 < t < T'} A(u(t)) + \sum_{|\alpha| \leq 3} \left( \int_0^{T'} \int_{R^3} (t - r)^{-1-2\eta} \sum_{i=1}^3 |T_i Z^\alpha u_1(t, x)|^2 dt dx \right)^{1/2} \\
+ \sum_{|\alpha| \leq 3} \sup_{0 < t < T'} (1 + t)^{-\delta} \left( \int_0^t \int_{R^3} (\tau - r)^{-1-2\eta} \sum_{i=1}^3 |T_i Z^\alpha u_2(\tau, x)|^2 d\tau dx \right)^{1/2} \\
\leq C_0 \left( W_4(u(0)) + W_4(u_2(0)) \right)
\end{equation}

holds, which contradicts the definition of $T_*$. We now suppose $T_* < \infty$. Because of $T^* = T_*$, we know among others that the inequality $A(u(t)) \leq C_0 \left( W_4(u_1(0)) + W_4(u_2(0)) \right)$ holds for all $t \in (0, T^*)$. If we solve the system (1.10) by giving the smooth, compactly supported initial data $(u(T^* - \delta, x), \partial_t u(T^* - \delta, x))$ at $t = T^* - \delta$ (by $\delta$ we mean a sufficiently small constant), then by the standard local existence theorem we know that there exists $\hat{T} > T^*$ such that the local solution can be continued to a larger strip $(0, \hat{T}) \times R^3$. Since the solution $u$ is smooth and compactly supported for any fixed time $t \in (0, \hat{T})$, we know $A(u(t)) \in C([0, \hat{T}])$ and thus there exists $\tilde{T} \in (T^*, \hat{T})$ such that the local solution satisfies $W_4(u_1(t)) + (1 + t)^{-\delta} W_4(u_2(t)) \leq 2C_0$ for any $t \leq \tilde{T}$, which contradicts the definition of $T^*$. We therefore see $T^* = \infty$, and the
local solution actually exists globally in time. This global solution obviously satisfies the
estimate (1.13). The proof of Theorem 1.4 has been finished.

4 Proof of Theorem 1.5

Obviously, it suffices to show (1.18). In view of Proposition 3.1 and (3.28)–(3.53), we
need to deal with

\begin{equation}
\sum_{|b| + |c| \leq 4 \atop |\alpha| \leq 3} \left\| G_{bc}^{\alpha\beta\gamma}(\partial_\tau Z^b u)(\partial_{\alpha\beta} Z^c u) \right\|_{L^2(R^3)} , \sum_{|b| + |c| \leq 4} \left\| H_{bc}^{\alpha\beta}(\partial_\alpha Z^b u)(\partial_\beta Z^c u) \right\|_{L^2(R^3)},
\end{equation}

where the coefficients $\{G_{bc}^{\alpha\beta\gamma}\}$ and $\{H_{bc}^{\alpha\beta}\}$ satisfy the null condition. We again separate
$R^3$ into the two pieces $B_t = \{ x \in R^3 : |x| < (t/2) + 1 \}$ and $B_t^c$. We get by (2.13)–(2.14) for any $\alpha$, $\beta$, and $\gamma$

\begin{equation}
\sum_{|b| + |c| \leq 4 \atop |\alpha| \leq 3} \left\| (\partial_\tau Z^b u)(\partial_{\alpha\beta} Z^c u) \right\|_{L^2(B_t)} + \sum_{|b| + |c| \leq 4} \left\| (\partial_\alpha Z^b u)(\partial_\beta Z^c u) \right\|_{L^2(B_t^c)} \\
\leq C(1 + t)^{-3/2} W_4(u(t)) W_5(u(t)) \leq C(1 + t)^{-3/2} W_4(u(0)) W_5(u(t)).
\end{equation}
Moreover, by repeating essentially the same argument as in (3.58)– (3.62), we get

\[ (4.3) \]

\[
\sum_{|b|+|c| \leq 3} \left\| G_{bc}^{\alpha \beta} (\partial_\gamma Z^b u)(\partial_\alpha Z^c u) \right\|_{L^2(B^*_t)} + \sum_{|b|+|c| \leq 4} \left\| H_{bc}^{\alpha \beta} (\partial_\alpha Z^b u)(\partial_\beta Z^c u) \right\|_{L^2(B^*_t)}
\]

\[ \leq C(1 + t)^{-3/2}W_4(u(0))W_5(u(t)) \]

\[ + C\| T\partial u(t) \|_{L^\infty(\mathbb{R}^3)}W_5(u(t)) + C\| Tu(t) \|_{L^\infty(B^*_t)}W_5(u(t)) \]

\[ + C(1 + t)^{-\eta}W_4(u(0)) \left( \sum_{|a|=4} \left\| (t - r)^{-\eta}TZ^a u \right\|_{L^2((0,t) \times \mathbb{R}^3)} \right) \]

By (3.11), (4.2), and (4.3) (see also (3.64)–(3.66)), we get for all \( t > 0 \)

\[ (4.4) \]

\[
W_5(u(t)) + \sum_{|a| \leq 4} \left( \sum_{i=1}^3 \left\| (\tau - r)^{-\eta}TZ^a u \right\|_{L^2 ((0,t) \times \mathbb{R}^3)} \right) \]

\[ \leq CW_5(u(0)) + CW_4(u(0)) \int_0^t (1 + \tau)^{-3/2}W_5(u(\tau))d\tau \]

\[ + C_dW_4(u(0)) \sum_{|a| \leq 4} \left( \sum_{i=1}^3 \left\| (\tau - r)^{-\eta}TZ^a u \right\|_{L^2 ((0,t) \times \mathbb{R}^3)} \right) \]

for a constant \( C_d > 0 \). Suppose \( C_dW_4(u(0)) \leq 1 \), if necessary. Then, we obtain (1.18) by the Gronwall inequality. The proof of Theorem 1.5 has been completed.

A Proof of (1.25)

Let us prove (1.25) in general space dimensions \( n \geq 2 \). In the following, by \( Z^a \) we denote the \( n \)-dimensional analogue of what we have meant in the preceding sections. Also, by \([p]\) we mean the greatest integer not greater than \( p \). We prove:

**Proposition A.1.** Let \( n \geq 2 \). Suppose \( \phi(t, x) \in C^\infty((0, \infty) \times \mathbb{R}^n) \) and \( \text{supp} \phi(t, \cdot) \subset \{x \in \mathbb{R}^n : |x| < t + R\} \) for some constant \( R > 0 \). Then, there exists a constant \( C = C(n, R) > 0 \) with \( C \to \infty \) as \( R \to \infty \) such that

\[ (A.1) \]

\[ (1 + t)^{-\eta/2}(1 + |t - r|)^{-\eta/2} |\phi(t, x)| \leq C \sum_{|a| \leq [(n-1)/2] + 1} \| \partial_x Z^a \phi(t, \cdot) \|_{L^2(\mathbb{R}^n)} \]

holds.

**Proof.** We consider the two cases \( |x| > (t/2) + 1 \) and \( |x| < (t/2) + 1 \) separately. For the former, we follow the outline made on page 610 of [1]. Since

\[
\phi(t, x) = \phi(t, r\omega) - \phi(t, (t + R)\omega) = \int_{t+R}^r \frac{\partial}{\partial \rho} \phi(t, \rho\omega) d\rho,
\]

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we get by the Hölder inequality
\[ |\phi(t, x)| \leq \int_r^{t+R} |(\nabla \phi)(t, \rho \omega)| d\rho \]
\[ \leq (t - r + R)^{1/2} \left( \int_r^{t+R} |\nabla \phi(t, \rho \omega)|^2 \rho^{-1} d\rho \right)^{1/2} r^{-(n-1)/2} \]
whenever \( r < t + R \). Combined with the Sobolev embedding on \( S^{n-1} \), the last inequality yields
\[ r^{(n-1)/2} (t - r + R)^{-1/2} |\phi(t, x)| \leq C \sum_{|a| \leq [(n-1)/2]+1} \left( \int_0^{t+R} \int_{S^{n-1}} |(\nabla \Omega^a \phi)(t, \rho \omega)|^2 \rho^{-1} d\rho dS \right)^{1/2}, \]
which yields (A.1) for \(|x| > (t/2) + 1\).

For the latter case \(|x| < (t/2) + 1\), we first note that by the Sobolev embedding \( H^{[n/2]+1}(\Omega_1) \hookrightarrow L^\infty(\Omega_1) \) and the standard scaling argument, the inequality
\[ \|\phi(t, \cdot)\|_{L^\infty(\Omega_\lambda)} \leq C \lambda^{-n/2} \sum_{|a| \leq [n/2]+1} \lambda^{|a|} \| (\partial_\xi^a \phi)(t, \cdot) \|_{L^2(\Omega_\lambda)} \]
holds for all \( \lambda > 0 \). Here and in the following, we use the notation \( \Omega_\lambda := \{ x \in \mathbb{R}^n : |x| < \lambda \} \). Recalling the notation \( B_t = \{ x \in \mathbb{R}^n : |x| < (t/2) + 1 \} \) and using (3.27) together with the fact that for any \( k \in \mathbb{N}, \Omega_j \{ (t^2 - r^2)^{-k} \} \} = L_j \{ (t^2 - r^2)^{-k} \} = 0 \) and \( S\{ (t^2 - r^2)^{-k} \} = \{ (t^2 - r^2)^{-k} \} \), we get from (A.3) with \( \lambda = (t/2) + 1 \)
\[ \|\phi(t, \cdot)\|_{L^\infty(B_t)} \leq C (1 + t)^{-n/2} \sum_{|a| \leq [n/2]+1} \| Z^a \phi(t, \cdot) \|_{L^2(B_t)} \]
\[ \leq C (1 + t)^{-n/2} (t + R) \sum_{|a| \leq [n/2]+1} \left\| \frac{1}{t - |\cdot| + R} Z^a \phi(t, \cdot) \right\|_{L^2(B_t)} \]
\[ \leq C_R (1 + t)^{-(n/2)+1} \sum_{|a| \leq [n/2]+1} \left\| \frac{1}{t - |\cdot| + R} Z^a \phi(t, \cdot) \right\|_{L^2(\Omega_{t+R})} \]
\[ \leq C_R (1 + t)^{-(n/2)+1} \sum_{|a| \leq [n/2]+1} \left\| \partial_\xi Z^a \phi(t, \cdot) \right\|_{L^2(\mathbb{R}^n)}. \]
Here, we have used the well-known inequality of Lindblad [15]. We see that by (A.4) that (A.1) holds also for \(|x| < (n/2) + 1\). The proof has been finished. \( \square \)
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