HYDRODYNAMICS OF HIGH-REDSHIFT GALAXY COLLISIONS: FROM GAS-RICH DISKS TO DISPERSION-DOMINATED MERS AND COMPACT SPHEROIDS

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ABSTRACT

Disk galaxies at high redshift (z ~ 2) are characterized by high fractions of cold gas, strong turbulence, and giant star-forming clumps. Major mergers of disk galaxies at high redshift should then generally involve such turbulent clumpy disks. Merger simulations, however, model the interstellar medium as a stable, homogeneous, and thermally pressurized medium. We present the first merger simulations with high fractions of cold, turbulent, and clumpy gas. We discuss the major new features of these models compared to models where the gas is artificially stabilized and warmed. Gas turbulence, which is already strong in high-redshift disks, is further enhanced in mergers. Some phases are dispersion dominated, with most of the gas kinetic energy in the form of velocity dispersion and very chaotic velocity fields, unlike merger models using a thermally stabilized gas. These mergers can reach very high star formation rates, and have multi-component gas spectra consistent with SubMillimeter Galaxies. Major mergers with high fractions of cold turbulent gas are also characterized by highly dissipative gas collapse to the center of mass, with the stellar component following in a global contraction. The final galaxies are early type with relatively small radii and high Sersic indices, like high-redshift compact spheroids. The mass fraction in a disk component that survives or re-forms after a merger is severely reduced compared to models with stabilized gas, and the formation of a massive disk component would require significant accretion of external baryons afterwards. Mergers thus appear to destroy extended disks even when the gas fraction is high, and this lends further support to smooth infall as the main formation mechanism for massive disk galaxies.

Key words: galaxies: evolution – galaxies: formation – galaxies: high-redshift – galaxies: interactions – methods: numerical

Online-only material: color figures

1. INTRODUCTION

In the ΛCDM cosmological model, collusions and mergers are an important growth mechanism for galaxies, and most of them should have occurred at high redshift (z > 1; e.g., Stewart et al. 2009). Major mergers, where the ratio of the baryonic masses of the involved galaxies is close to one, are in particular important for the buildup of massive galaxies (Hopkins et al. 2010). Even if recent models and high-redshift observations suggest that the growth of galaxies near L* is largely through relatively smooth and cold accretion (Dekel et al. 2009b; Bournaud & Elmegreen 2009; Conroy & Wechsler 2009; Genel et al. 2010), about one-third of a galaxy’s baryons are still expected to be provided by significant mergers (e.g., Dekel et al. 2009; Brooks et al. 2009).

The effect of the merger of two disks galaxies has been largely explored in the low-redshift context, where galactic disks are mostly made up of stars with relatively modest fractions of cold gas. In such conditions, it is known that a major merger of two spiral galaxies typically produces a remnant resembling an elliptical or early-type galaxy (ETG) (Barnes & Hernquist 1996; Mihos & Hernquist 1996; Naab & Burkert 2003; Bournaud et al. 2004a, 2007b; Naab et al. 2006, 2007; Hoffman et al. 2010). There are still some differences between the predictions of merger models and observations (Burkert et al. 2008) but there is, overall, an ample consensus that hierarchical merging is the main formation channel for present-day ETGs.

At high redshift, the role of major mergers in the formation of particular galaxies and in the growth of galaxies in general remains much more debated. First, determinations of the merger rate from high-redshift surveys are usually based on irregular structures or disturbed kinematics (e.g., Conselice et al. 2003; Lotz et al. 2006, 2008; Overzier et al. 2010; Jogee et al. 2009; López-Sanjuan et al. 2009; Puech 2010). However, primordial galaxy disks can have irregular morphologies and disturbed kinematics even when they are mostly isolated, not undergoing strong interactions (Elmegreen et al. 2007, 2009; Genzel et al. 2008; Bournaud et al. 2007a, 2008b; Dekel et al. 2009a), so the actual merger rate remains unknown. Also, high-redshift disk galaxies have typical morphologies that differ from nearby spirals (Cowie et al. 1996; Elmegreen & Elmegreen 2005; Elmegreen et al. 2007; Genzel et al. 2008), and their mergers could also have different morphologies and kinematics compared to nearby mergers, potentially making the identification of mergers more ambiguous: for instance, asymmetries and clumpiness in optical imaging are often attributed to mergers (Conselice et al. 2003; Lotz et al. 2008), but high-redshift disk galaxies seem to frequently form massive clumps just by internal instabilities that do not require interactions (Elmegreen et al. 2007, 2009; Genzel et al. 2008). Even in cosmological simulations, the galaxy merger rate is continuously revised (e.g., Genel et al. 2008, 2010, and references therein). In particular, mergers of dark halos do not necessarily lead to the merging of their central galaxies, and the baryonic mass ratio of galaxy mergers...
can significantly differ from the dark matter mass ratio of their host halos (Hopkins et al. 2010).

Second, the outcome of major mergers is usually considered to be ETGs. However, high-redshift ETGs are often unexpectedly compact compared to nearby ellipticals and merger simulations (Daddi et al. 2005; Trujillo et al. 2006; van Dokkum et al. 2009, 2008; Kriek et al. 2009). The role of mergers in forming these ETGs has been questioned: while their evolution into modern, more extended elliptical galaxies can be explained through continuous hierarchical merging (Naab et al. 2009), the emergence of compact ellipticals at high redshift remains more mysterious.

Third, the most general issue is the ability of disk-dominated galaxies to survive violent mergers. While it is known that mergers of disk galaxies can produce ETGs with no or little residual disk component (references above), whether all mergers even with very high gas fractions destroy disk galaxies and transform them into ETGs, or whether disk-dominated galaxies could survive major mergers in high-redshift conditions, remain more uncertain. The frequency of violent mergers could indeed call into question the survival of disk-dominated galaxies (Weinzirl et al. 2009). Some models of mergers, however, have led to the proposal that high-redshift merger remnants could be dominated by large rotating disk components rather than bulges and spheroids (Springel & Hernquist 2005; Robertson et al. 2006). There have been claims that such disky merger remnants cannot account for the observed properties of high-redshift disk galaxies (Shapiro et al. 2008; Bournaud & Elmegreen 2009) but this remains actively debated in simulations (Robertson & Bullock 2008) and in observations (Hammer et al. 2009).

Thus, at least three major unknowns remain: the frequency and observational signatures of high-redshift mergers, their role in forming the high-redshift populations of ETGs, and the ability of massive disk-dominated galaxies to survive these events.

The dynamics and outcome of mergers have never been modeled for realistic, high-redshift galaxies. Simulations by Cox (2004), Springel & Hernquist (2005), and Robertson et al. (2006) considered high gas fractions and concluded that disks could survive or re-form after a merger. However, these simulations had high thermal pressure support in the interstellar medium (ISM; temperature $> 10^4$ K), which forces the gas to be smooth and stable in the isolated galaxies and in the colliding pairs as well.

Star-forming galaxies at high redshift ($z = 1$–5) are very different from such models. They are generally gassy, clumpy, and turbulent, with $\sim$50% of their baryons in cold molecular gas (Daddi et al. 2010a; Tacconi et al. 2010), giant star-forming clumps of $10^{7}$–$10^{9} M_\odot$ (Elmegreen et al. 2004, 2007, 2009), and velocity dispersions of several tens of km s$^{-1}$ (Förster Schreiber et al. 2009; Shapiro et al. 2008; Genzel et al. 2008; Epinat et al. 2009; Queyrel et al. 2009). Associated star formation rates (SFRs) are around $100 M_\odot$ yr$^{-1}$. While most observations of high-redshift star-forming galaxies concerned only very massive galaxies (above the critical mass $L_*$), recent studies of $z > 1$ lensed galaxies find that gravitational instabilities and turbulent clumps could also be dominant in lower-mass galaxies (Jones et al. 2010; Swinbank et al. 2010). The morphology and dynamics of the disks suggest that the observed clumps form by gravitational instabilities (Elmegreen et al. 2004; Elmegreen & Elmegreen 2005; Shapiro et al. 2008; Bournaud et al. 2008b; Daddi et al. 2010a). Simulations of this process require cosmological codes that allow for highly supersonic turbulent speeds (Agertz et al. 2009b; Ceverino et al. 2010).

Even low-redshift spiral galaxies have an unstable, cloudy ISM supported mostly by supersonic turbulence rather than thermal pressure (e.g., Burkert 2006). Recent simulations showed that a spatial resolution of 10% of the scale height with full tracking of turbulent motions is required to reproduce the three-dimensional inertial range of turbulence inside a modern galaxy (Bournaud et al. 2010).

A typical wet merger at high redshift should involve the interaction of such clumpy, turbulent disks. The outcome could differ from previously modeled mergers using thermally stabilized gas. Recent studies have shown that ISM turbulence and clumpiness have a substantial effect in mergers of present-day spirals with just a few percent of gas, with significant differences both in the star formation history during the interaction (Teyssier et al. 2010; Saitoh et al. 2009) and the properties of the relaxed post-merger ETG (Bournaud et al. 2008a; Bois et al. 2010). The effect could presumably be more dramatic in high-redshift mergers involving high fractions of cold gas.

In this paper, we present hydrodynamical AMR simulations of major mergers between galaxies with high fractions of cold, turbulent and clumpy gas, like typical $z \sim 2$ star-forming galaxies. Gas cooling below $10^4$ K is allowed, supersonic ISM turbulence is captured, and the main star-forming complexes are directly resolved. We compare with models using artificially stabilized disks, as in traditional high-redshift studies.

We find that mergers of high-redshift disks can undergo a very clumpy and chaotic phase, during which the kinematics is dispersion dominated even for the gas component. The gas kinematics appears consistent with the observed properties of some “dispersion-dominated galaxies” as well as the spectral properties of SubMillimeter Galaxies (SMGs). A large part of the total mass is thus supported by supersonic turbulence, which is a dissipative support, hence the merging system undergoes a rapid dissipational collapse into a compact ETG. The mass fraction in a surviving or re-formed disk component is much lower for supersonically turbulent high-redshift mergers than for models with artificially warmed gas. This does not mean that mergers of gas-rich galaxies can never re-form a disk: a large enough far-out reservoir of gas could recollect into a new disk, or continuous infall of fresh gas could build a new disk. Some orbital parameters not modeled here might also be more favorable to disk survival (e.g., Hopkins et al. 2009). Still, our main conclusion is that mergers between gas-rich turbulent and clumpy galaxies are qualitatively different than mergers between gas-rich smooth galaxies with artificial pressure support, and can better explain resolved observations of high-redshift systems.

2. SIMULATIONS

This paper studies idealized models of disk galaxies. The initial conditions are not cosmological, and there is no cosmologically motivated boundary condition modeling mass infall or extended gas reservoirs. Instead, the initial conditions are designed to be representative of gas-rich major mergers of redshift $z \sim 2$ galaxies, based on their main observed characteristics. We model collisions and mergers between two such galaxies and study the effect of this merger, by comparison to the modeled evolution of a single isolated galaxy.

The simulations were performed with the AMR code RAMSES (Teyssier 2002). The technique is fully described elsewhere and shown to model realistic interstellar gas in low-redshift mergers and isolated disks (Teyssier et al. 2010; Bournaud et al. 2010). The main parameters adopted for the present simulations are in Table 1.
The box size for the simulation is 200 kpc. The coarsest level of the AMR grid is \( l = 8 \), which corresponds to a \( 256^3 \) Cartesian grid with a cell size of 781 pc. A cell that contains a gas mass larger than \( m_{\text{gas}} = 8 \times 10^4 \, M_\odot \), or a number of particles larger than 15, is refined, until the maximal level \( l = 11 \) is reached.

At that point, the cell size corresponds to 97 pc. Stars and dark matter are described with \( 2 \times 10^5 \) collisionless particles each in the initial galaxies.

Our clumpy disk simulations were performed with a barotropic cooling model (Bournaud et al. 2010), naturally producing a cloudy and turbulent ISM, with a temperature floor around \( 10^3 \) K. We refer to these as the *cooling* models. For comparison, the same gas-rich mergers were modeled with a thermally pressurized and Toomre-stable ISM, using an adiabatic equation of state (EoS) with an exponent of \( \gamma = 5/3 \) for densities above 1 cm\(^{-3} \), and \( T = 10^4 \) K for lower densities. This EoS maintains a Toomre parameter \( Q \simeq 1.5-2 \) in the initial disks and stabilizes the gas against axisymmetric perturbations. These will be called the *stabilized* models. In all cases, a density-dependent pressure floor ensures that the Jeans length is resolved by at least four cells to avoid artificial fragmentation, as initially proposed by Machacek et al. (2003) (see Teyssier et al. 2010 for the implementation details).

In the cooling models, star formation is assumed to proceed above a density threshold of 300 cm\(^{-3} \) with an efficiency of 7\%, i.e., 7\% of the gas in a given cell forms stars per local free-fall time. This gives an SFR of 120 \( M_\odot \) yr\(^{-1} \) in the isolated disk model, realistic for such gas-rich \( z \approx 2 \) systems. In the stabilized models, the star formation threshold is 3 cm\(^{-3} \) and the efficiency is 4\%, giving the same SFR in the isolated disks; we compare the two sets of models with the same SFR in pre-merger disks. The resulting star formation history in the merger models with cooling/stabilized EoS is relatively similar (see Section 3.4).

All simulations use the kinetic feedback model described in Dubois & Teyssier (2008), with 20\% of the energy from each supernovae (SNe) re-injected in the form of an expanding bubble of initial radius 100 pc (assuming that the rest of the SN energy was radiated away before propagating up to scales of 100 pc). Some models have increased feedback with 100\% of the SN energy injected into the ISM (models labeled “F”) and some have an SN feedback efficiency set to 500\% (models labeled “F5”), discussed only in Section 3.4.

Our simulations start with disk galaxies, each having a stellar mass of \( 4 \times 10^{10} \, M_\odot \), an initial gas fraction of 70\%, a disk scale length of 5 kpc with a truncation radius of 12 kpc, and an initial scale height of 800 pc. An initial bulge containing 15\% of the stellar mass is assumed, with a Hernquist profile and a scale length of 500 pc. The dark matter halo has a Burkert profile with a core radius of 8 kpc, and a mass fraction (dark/total) inside the disk radius of 30\%. The circular velocity in the outer disk is 245 km s\(^{-1} \).

In the cooling models, the initial disks spontaneously become clumpy and turbulent, with \( V/\sigma \approx 5 \) (for rotation speed \( V \) and turbulent speed \( \sigma \)). When the mergers occur, at the first pericenter, gas fractions are around 50\% after some early gas consumption (see Table 2); this seems typical for disk galaxies at \( z \approx 2 \) (Daddi et al. 2010a; Tacconi et al. 2010), and hence expected for a wet merger at \( z \approx 2 \).

Our merger models start with relatively massive disk galaxies, so as to compare with existing models, e.g., in Robertson et al. (2006). There are galaxies like this in \( z \approx 2 \) samples (for instance, in the sample of Förster Schreiber et al. 2009). Also, our pre-merger disks are not extreme in terms of gas clumpiness and turbulence: many \( z \approx 2 \) disks have even lower \( V/\sigma \) ratios (e.g., Förster Schreiber et al. 2009).

Three interaction orbits were used. They are all prograde for one galaxy and retrograde for the other in order to consider a typical total angular momentum rather than extreme cases with aligned spins.\(^7\) Orbit 1 has an impact parameter of 12 kpc and is parabolic. One disk has an initial inclination of 30\( ^\circ \) from the orbital plane, and the other has an initial inclination of 50\( ^\circ \). For orbit 2, these parameters are: 35 kpc, hyperbolic (total energy of the galaxy pair is 0.3 times its initial kinetic energy), and 30\( ^\circ \) and 50\( ^\circ \), respectively. For orbit 3, they are 25 kpc, hyperbolic (total energy = 0.2\( \times \) the initial kinetic energy), 40\( ^\circ \), and 65\( ^\circ \), respectively.

Three simulations were also run for a merger of lower-mass galaxies. The masses of all initial components (stellar disk, gaseous disk, bulge, halo) where reduced by a factor of eight compared to the initial higher-mass models, and all sizes and distances were reduced by a factor of \( \sqrt{8} \), hence keeping surface densities about constant. The pre-merger galaxies then had circular velocities of about 150 km s\(^{-1} \) in their outer disks, with a \( V/\sigma \approx 3.5 \) ratio—somewhat lower than in the more massive disks models, which is in agreement with observed trends (Förster Schreiber et al. 2009). These merger models were performed using orbit 2 with our cooling and stabilized-ISM models, and are, respectively, denoted LM-C2 and LM-S2, and LM-C2F with increased feedback.

### 3. RESULTS

#### 3.1. Ongoing Mergers

The time evolution of mergers C1 (cooling) and S1 (stabilized ISM) is shown in Figures 1 and 2. The stabilized model has relatively homogeneous tidal tails orbiting around smooth gas disks. The gas in the cooling model is dominated by numerous star-forming clumps that are somewhat more massive than the clumps were in the pre-merger galaxies. Visual inspection shows that some of the pre-existing clumps survived and some have disrupted and re-formed. Numerous filaments form in many directions, instead of a main pair of continuous tidal tails. Other projections (Figure 3) show that the gas distribution during the merger forms a very irregular spheroid in three dimensions; there

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\(^7\) Aligned spins would not necessarily result in higher angular momentum or more disk component in the final result, because of tidal removal of the angular momentum (Robertson et al. 2006).
Figure 1. Snapshots of the gas mass distribution for models C1 (cooling) and S1 (stabilized ISM) at similar instants and under similar projections. \( t = 0 \) is the first pericenter passage and all maps are in log scale. (A color version of this figure is available in the online journal.)

Figure 2. Snapshots of the stellar mass surface density distribution for models C1 (cooling) and S1 (stabilized ISM) at similar instants and under similar projections. \( t = 0 \) is the first pericenter passage and all maps are in log scale. (A color version of this figure is available in the online journal.)

are no disks. The model with stronger feedback (C1F in Figure 3) is qualitatively similar: self-gravity is already sufficient to drive strong ISM turbulence in massive galaxies at high redshift (Dekel et al. 2009a; Elmegreen & Burkert 2010).

Gas velocity fields and line-of-sight dispersion maps are shown in Figures 3 and 4. The gas velocity fields of our high-redshift cooling models are very chaotic, and often lack extended rotating components, such as large disks or long tidal tails with monotonic velocity gradients. The gas velocity dispersions are high, especially near dense clumps. Interactions at low redshift substantially increase the gas velocity dispersion, from typically 10 km s\(^{-1}\) in non-interacting spirals to 30–40 km s\(^{-1}\) in major mergers (see Elmegreen et al. 1995 for observations, Bournaud et al. 2008a for simulations). We find a similar relative increase here, but starting with disks that are already quite turbulent before the merger. This results in systems where the gas component is dispersion dominated during the merger, with \( V/\sigma \) ratios\(^8\) of around 2 or even 1 for some projections and times. The gas dispersions are high in projection on the line of sight, and also in direct measurements of the local three-dimensional motions: we measured the turbulent velocity dispersion in 1 kpc\(^3\) cubes in model C1 at \( t = 140 \) Myr; the mass-weighted average value was \( \langle \sigma_{\text{turb},1D} \rangle \simeq 175 \) km s\(^{-1}\) (higher values on projected maps such as Figures 3 and 4 result from line-of-sight projection effects, not to a physical, local turbulent motion). Similar measurements are given for all models in Table 2, at the same instant which is about the peak of turbulent speed in our merger models with cooling. These measures show that the turbulent velocities become much higher during the interactions and mergers than in the pre-merger clumpy disks, and that this property is not reproduced in the simulations using a stabilized gas model. The values of line-of-sight velocity dispersions in Figures 3 and 4 will be further compared to high-redshift observations in Section 4.1.

Mergers with the stabilized-ISM model show velocity dispersions that are lower by a factor \(~3\) for all times. Instead of chaotic velocity fields, they have relatively smooth and extended rotating gas disks, surrounded by long tidal tails that co-rotate with large-scale velocity gradients (see examples in Figure 3). Low-redshift mergers have different signatures, since they typically exhibit long tidal tails with large and smooth velocity gradients along these tails (see examples in Bournaud et al. 2004b; Chilingarian et al. 2010). Low-redshift merger models with warm stable gas versus colder and unstable gas in cooling models have been compared in Teyssier et al. (2010). While

\(^8\) Throughout the paper, \( \sigma \) refers to a one-dimensional dispersion. A system with \( V/\sigma < 2 \) is dispersion dominated with > 60% of its kinetic energy support is in the form of dispersions.
Figure 3. Three orthogonal projections of model C1 showing the surface density, velocity, and dispersion maps (mass-weighted values along the line of sight, for gas denser than 10 cm$^{-3}$). A resolution of 1 kpc was assumed (FWHM of a Gaussian beam). All snapshots are 44 $\times$ 44 kpc. Note that H$\alpha$ observations would be mostly sensitive to emission from the dense clumps. (A color version of this figure is available in the online journal.)

Table 2
Properties of the Final Relaxed Systems

| Model | Gas Consumption | ISM Turbulence | Merger Remnant Properties |
|-------|-----------------|----------------|---------------------------|
|       | $f_{\text{gas},\text{peri}}$ | $f_{\text{gas},\text{i+400 Myr}}$ | $\langle \sigma_{\text{turb},1D} \rangle$ (km s$^{-1}$) | Sersic n | $R_{1/2}$ | $f_{\text{disk}}$ |
| C1    | 45%             | 17%            | 175                      | 4.4     | 2.8     | 12%          |
| C1F   | 54%             | 22%            | 186                      | 4.2     | 3.0     | 16%          |
| C1F5  | 58%             | 21%            | 204                      | 3.9     | 3.1     | 21%          |
| S1    | 48%             | 20%            | 56                       | 2.9     | 6.1     | 40%          |
| S1F   | 52%             | 22%            | 59                       | 2.5     | 6.3     | 48%          |
| S1F5  | 56%             | 23%            | 65                       | 2.6     | 6.2     | 53%          |
| C2    | 53%             | 13%            | 153                      | 4.2     | 2.9     | 14%          |
| S2    | 49%             | 18%            | 68                       | 3.2     | 5.8     | 37%          |
| C3    | 53%             | 19%            | 164                      | 4.9     | 2.6     | 11%          |
| S3    | 47%             | 17%            | 72                       | 3.3     | 5.6     | 37%          |
| I     | ...             | ...            | ...                      | ...     | ...     | ...          |
| LM-C2 | 52%             | 19%            | 89                       | 3.7     | 1.2     | 10%          |
| LM-C2F| 58%             | 21%            | 96                       | 3.9     | 1.3     | 13%          |
| LM-S2 | 57%             | 22%            | 42                       | 2.7     | 2.0     | 35%          |

Notes. Half-mass radius $R_{1/2}$ and Sersic index $n$ (best fit between 0.3 and 3 $R_{1/2}$); gas fraction remaining at the pericenter and 400 Myr later; mass-weighted average of the one-dimensional local gas turbulent speed ($\langle \sigma_{\text{turb},1D} \rangle$) measured 140 Myr after each pericenter; baryonic mass fraction of the baryons in a rotating disk $f_{\text{disk}}$, measured using a kinematic disk+spheroid decomposition as in Martig & Bournaud (2010).

In this sense, stabilized-ISM models are a more acceptable recipe for the large-scale gas properties in low-redshift mergers than in high-redshift ones. This can be explained because low-redshift systems have weaker gas turbulence and are more stable than high-redshift systems on scales of a kpc. Low-redshift disks are only slightly unstable, and the sizes and masses of the clumps that form are much smaller than they are at high redshift. Thus, the effects of ISM turbulence and clumpiness are more striking in high-redshift mergers. Resolving gas turbulence, star-forming instabilities, and/or shocks change the star formation history of these low-redshift mergers (Barnes 2004; Saitoh et al. 2009; Teyssier et al. 2010; Chien & Barnes 2010), but have no major impact on the morphology of the merger remnants and only a limited impact on their kinematics (Bois et al. 2010).

Notes. Half-mass radius $R_{1/2}$ and Sersic index $n$ (best fit between 0.3 and 3 $R_{1/2}$); gas fraction remaining at the pericenter and 400 Myr later; mass-weighted average of the one-dimensional local gas turbulent speed ($\langle \sigma_{\text{turb},1D} \rangle$) measured 140 Myr after each pericenter; baryonic mass fraction of the baryons in a rotating disk $f_{\text{disk}}$, measured using a kinematic disk+spheroid decomposition as in Martig & Bournaud (2010).

they display substantial differences in their star formation properties, both models are dominated by long tidal tails and have similar half-mass sizes after the merger. The tails have star-forming clumps in the cooling model, but the clumps do not dominate the morphology and kinematics as they do at higher redshift.
3.2. Merger Remnants

Supersonic gas turbulence dissipates rapidly, which can produce a strong contraction of a dispersion-supported gaseous system. Such dissipative collapse is observed in Figure 1 for model C1. Some clumps are expelled by tidal interactions, but most of the gas clumps and inter-clump gas coalesce in a compact central object. Because the gas fraction is initially high, a large part of the final stellar content forms within the same gas clumps and follows their coalescence. Old stellar components contract due to the dissipation of the gas and young stars, which contain a large fraction of the total mass. Thus, the merger leads to the formation of a relatively compact stellar spheroid. This spheroid has a low half-mass radius, a high Sersic index, and an extended stellar halo visible as a low surface mass density component beyond radii of ~7 kpc in Figure 5. Table 2 gives half-mass radii and Sersic indices for all models. Figure 4 shows the corresponding stellar mass profiles. Remnants of the stabilized-ISM merger models are more extended9 and have lower Sersic indices than remnants of the cooling merger models. The isolated clumpy turbulent disk model has formed a central bulge through internal evolution (as in Noguchi 1999, Immeli et al. 2004, and Elmegreen et al. 2008 models), but remains dominated by a rotating exponential disk (Bournaud et al. 2007a).

The merger remnant of a typical high-redshift merger is not just more compact, but also less disky. Gas disk re-growth is faster in the models with a stabilized ISM (see Figure 1 at \( t = 215 \)), and thus forms a more massive final stellar disk. For example, the final disk component in model S1 contains 40% of the baryons and is obvious up to large radius in Figure 1. In cooling model C1, most star formation takes place in gas clumps before they coalesce and get a chance to re-form a disk; the final disk in model C1 is compact, with a disk fraction of only 12%. Similar differences are found for all merger orbits (Table 2).

The increased dissipation and resulting compactness in cooling models with a clumpy turbulent gas can be explained: clumps interact with each other gravitationally, scatter, and develop three-dimensional motions (i.e., high dispersions). The gas clumps and holes can then pass by each other. In stabilized-ISM models, the smooth distribution of the gas does not allow it to pass through itself and it therefore rapidly settles back into a relatively planar disk. Gas clumpiness can reduce the ISM cross section for self-interaction and thereby increase the dissipation timescale, but the supersonic turbulence that accompanies this clumpiness is highly dissipative. For modest clump filling factors, the net result is a greater dissipation rate for ISM kinetic energy. This is unlike the situation in stabilized-ISM models, where the gas is supported by a steady thermal pressure. Excess thermal energy can be radiated away, but the EoS, high-temperature floor, and/or feedback recipe, keep the gas warm in these models and make the thermal support non-dissipative in practice. Furthermore, the massive clumps that form in highly turbulent gas rapidly migrate inward through dynamical friction, unlike the relatively homogeneous gas in stabilized models which settles into a circular orbit.

3.3. Interpretation: Increased Turbulence and Rapid Dissipation in Mergers

The effect of turbulence dissipation on the size evolution of a merger can also be estimated through simple calculations. A star and gas system in equilibrium satisfies the Virial Theorem, and then the total energy from self-gravity and motion equals half of the gravitational potential energy, \( E_{\text{tot}} = 0.5E_{\text{grav}} \), both of which are negative. Loss of energy by dissipation leads to a more negative \( E_{\text{tot}} \), and so a smaller, more tightly bound equilibrium. For typical mass distributions in a galaxy, the gravitational potential energy scales with the inverse of the radius, \( R \), in which case the relative contraction is \( \Delta R / R = -\Delta E / E = \Delta E / |E| \).

If the gas mass is \( M_{\text{gas}} \) and the one-dimensional gas velocity dispersion is \( \sigma \), then \( \Delta E = -1.5M_{\text{gas}}\sigma^2 \) when a significant fraction of the gas kinetic energy is lost. With similar notation for the stars, the total energy is \( E_{\text{tot}} = 1.5M_{\text{gas}}\sigma^2 + 1.5M_{\text{stars}}V^2 \), assuming that stellar motions are of the order of the circular velocity \( V \) (even if not consisting in organized rotation). Thus \( \Delta E / E = -X/(1 + X) \) where \( X = (M_{\text{gas}}/M_{\text{stars}}) \times \tau^2 \), with \( \tau = \sigma / V \). This ratio, \(-X/(1 + X)\), is also the relative contraction of the radius after all of the initial gas motion dissipates. If \( f_g \) is the disk gas fraction, then \( X = (f_g/[1 - f_g])\tau^2 \).

Turbulent dissipation should occur in about a crossing time for radial motions (McLow 1999). The crossing time for a whole galaxy is about the orbit time, typically 100–200 Myr, so most of the non-rotational gas kinetic energy can be dissipated over the duration of a major merger. After dissipation and galaxy contraction, the gas receives new kinetic energy from the potential energy, and can then dissipate even more energy. This cycle of dissipation, contraction, heating and more dissipation, continues with ever decreasing orbit time until the radial component of the turbulent energy is gone.

Low-redshift Milky Way like disks have \( \tau \sim 3\%–5\% \), and their major mergers have a value about 3–5 times higher,
Together with $\tau \sim 20\%$ (observations: Irwin 1994; Elmegreen et al. 1995—simulations: Bournaud et al. 2008b; Teyssier et al. 2010). Together with $f_g$ of a few percent, the size of a merger remnant is not much smaller than the original galaxy size. The same would be true in high-redshift merger models that have subsonic gas, i.e., gas without much energy dissipation, even if $f_g$ is large.

High-redshift galaxy models have $\tau \sim 20\%$ (e.g., Förster Schreiber et al. 2009), $f_g \sim 0.5$ (e.g., Daddi et al. 2010a; Tacconi et al. 2010), and highly dissipative gas. With an increase of gas dispersions of a factor three during interactions (conservatively based on the known increased at low redshift, but also consistent with high-redshift mergers spectroscopy in, e.g., Shapiro et al. 2008), $\tau$ would become of the order of $\sim 60\%$ for high-redshift mergers. Then $\Delta R/R \sim 0.25$. This result implies that turbulent dissipation for a gas-rich system can cause significant radial contraction of both the gaseous and stellar components for every gas dissipation time, i.e., just 100–200 Myr. As the gas continues to dissipate energy, the systemic contraction of the galaxy continues, and the total contraction of the merger can be larger if some mass is expelled from the system and carries more energy away.

Another mechanism for galaxy contraction is inward clump migration through dynamical friction. The timescale for this, given the clump masses and total masses of our models, is typically around 500 Myr (see Bournaud et al. 2007a). This is slower than gaseous turbulence dissipation, and therefore not as important for overall shrinkage when the gas fraction is large.

Contraction also occurs if we consider the size of a disk to be determined by angular momentum. Baryons in the central few kpc of interacting galaxies loose significant angular momentum, while baryons initially in the outer disks carry away a large fraction of the initial angular momentum in tidal tails (see review in Bournaud 2010). At first order, the angular momentum of baryons near the co-rotation region, which is typically about the half-mass radius (a few kpc for the disk masses considered here) is be roughly conserved.

For a mass $M$ encompassed by a radius $R$, and a circular velocity $V = \sqrt{GM/R}$, angular momentum conservation implies that

$$R \propto 1/V^2 \propto M^{-3}.$$  

If gas initially outside the half-mass radius dissipates its turbulent energy and moves toward the center, the central mass increases, possibly as much as a factor of two. Then the half-mass radius can decrease by a factor of eight, all the while conserving angular momentum. Further shrinkage can be caused by angular momentum removal through tidally expelled baryons. Only this tidal removal is present in models with a smooth, non-turbulent ISM.

3.4. Star Formation History

The star formation histories of mergers C1, C1F, and S1 are shown in Figure 6. The efficiency was calibrated in each model to result in an SFR of approximately $100 M_{\odot}$ yr$^{-1}$ in each pre-merger galaxy, typical for $z \sim 2$ disk galaxies with similar masses. The SFR during the merger reaches a factor of $\sim 10$ higher than in the pre-merger pair in all cases, with peak values of $1000$–$2000 M_{\odot}$ yr$^{-1}$. This rate is consistent with the SFRs estimated in SMGs (e.g., Tacconi et al. 2008). The star formation peak can occur earlier-on or later-on in various models, but the maximal SFR and the duration of the starburst remain comparable, leading to globally similar amounts of gas-to-star conversion for the cooling and stabilized models.

Both the cooling and the stabilized-ISM models reach rates of star formation that are realistic for observed $z \sim 2$ disks and starbursting mergers. The rates are also consistent with each other. This does not mean that gas cooling below $10^4$ K in a clumpy turbulent ISM has no effect on star formation in mergers.

High-resolution models explicitly including gas cooling could, in principle, resolve the densest gas phases that are actually star forming (Tasker & Tan 2009; Agertz et al. 2009a; Bournaud et al. 2010), but models using an artificially thermalized ISM do not reach such high gas densities and they have to describe star formation as a low-efficiency process pervasively distributed throughout a low-density gas. The calibration of the efficiency is subjective when dense clouds are not made self-consistently by the model. Here we choose an efficiency in the stabilized-ISM model that gives the same SFR as the cooling model for an isolated disk. Had we used the same prescription for star formation in each case, then the cooling models would have had much higher SFRs and their collisions would have been more gas free. While we compare the cooling and stabilized models with similar SFRs and resulting gas fractions, the EoS used to model cold gas imposes most of this gas to be relatively cold $<10^4$ K. Different feedback models might result in higher amounts of hot extended gas, which could potentially cool down later-on and accrete onto a re-formed disk (see the discussion in Sections 3.4 and 3.5).

Globally, the SFR in our merger models peaks at about $\sim 10$ times the value of the pre-merger disk pair (with both the cooling and stabilized EoS). This factor is somewhat higher than the typical value in larger samples of merger simulations (e.g., Di Matteo et al. 2007, 2008; Martig & Bournaud 2008; Stewart et al. 2008) but not in large disagreement. This factor of about 10 also appears somewhat higher than in observations of mergers and close pairs (Bergvall et al. 2003; Bell et al. 2005; Jogee et al. 2009; Robaina et al. 2009). However, these observations indicate the SFR enhancement at a random instant of an interaction, and what they consider to be major mergers are not strictly equal-mass ones. The factor 10 at the peak SFR in our models, which is reached only for a short period, is broadly consistent with the factor of 3–4 indicated by these observational studies. We did not here focus on particularly efficient cases where the SFR enhancement in a merger can reach factors larger than a hundred (as in Mihos & Hernquist 1996 or Springel & Hernquist 2005), but rather on random, representative orbits.

The peak in the merger-induced SFR begins somewhat earlier in the cooling models than in the stabilized ones, just after the first pericenter passage (Figure 6). This earlier gas consumption cannot cause the lower disk fraction of the merger remnants because (1) it occurs only once the interaction process starts, so the gas fractions during the interaction remain quite similar in both models (Table 2) and (2) the increased feedback in model C1F delays the peak of star formation until a bit later than in model S1, but the final merger remnant is almost as compact and disk free as for the initial model C1.

The earlier merger-induced star formation activity in the cooling models is consistent with the results obtained by Teyssier et al. (2010) in low-redshift merger models (see also Saitoh et al. 2009, for resolved star-forming regions in early phases of galaxy interactions). High-resolution models with a
low-temperature floor can capture ISM turbulence, local dense shocks, and fragmentation into star-forming clouds. Stars form in these clouds when they are still in the main disk, long before they have accreted to the galaxy center. Such modeling is required to reproduce correctly the extent of star formation in early- and late-stage interactions, which is missed by standard prescriptions (see also Barnes 2004; Chien & Barnes 2010). On the other hand, low-resolution or stabilized-ISM models get intense star formation only in the dense centralized gas that follows the merger-driven inflow. Dense clouds do not form in the disk. The delay in star formation for this stabilized case is comparable to the rotation period of the entire galaxies.

3.5. Feedback and Clump Evolution in Mergers

Our simulations include a kinetic model for the energy feedback from Type II SNe. Other sorts of feedback such as Type Ia SNe, stellar winds, and mass return are important for high-redshift galaxy evolution (Agertz et al. 2011; Martig & Bournaud 2010), but the timescales for this feedback are typically longer than the timescale for a major merger of massive disk galaxies. Another sort of feedback with a short timescale is radiation pressure from young massive stars. Giant clumps in high-redshift, gas-rich galaxies could be sufficiently massive to self-regulate their star formation so that they “survive” feedback for several hundred Myr (Krumholz & Dekel 2010). This however remains debated (Murray et al. 2010). The “survival” definition of Krumholz & Dekel (2010) implies that a bound stellar clump remains but not necessarily that the gas is retained by this clump. Expelled gas could be re-accreted by the clump and start forming stars again (Pflamm-Altenburg & Kroupa 2009).

These additional feedback mechanisms are not present in our models. Nevertheless, we found that varying the efficiency of the SN feedback (in runs C1F and LM-C2F) did not result in major changes to the properties of the final ETGs. Models C1 and C1F also have similar line-of-sight velocity dispersions in their gas component (Figures 3 and 4). The main source of turbulence in high-redshift disk galaxies is generally considered to be gravitational energy released through clumping instabilities and/or inward mass accretion (Elmegreen & Burkert 2010; Dekel et al. 2009a). Observations have suggested that the local velocity dispersion scales with the local gas density and/or star formation surface density (Lehnert et al. 2009, see also Green et al. 2010 for low-redshift analogues) which could suggest energy input from stellar feedback. The local velocity dispersion scales with the local surface density also in models dominated by gravity-driven turbulence such as those in Bournaud et al. (2009). Gas turbulence can be further increased by tidal forces in mergers (Elmegreen et al. 1993, 1995; Irwin 1994; Bournaud et al. 2008a; Teyssier et al. 2010). Stellar feedback is thus not expected to be the main energy source of the turbulent motions. The same appears to be true in local galaxies (Bournaud et al. 2010).

While the pre-merger disk galaxies are already clumpy, the main gas clumps during the merger tend to be denser and more massive (see for instance the time sequence on Figure 1): some are pre-existing clumps that accrete more mass, some new clumps form with high masses allowed by the high gas.
differences between models C1 and S1, both in terms of final disk fraction and final compactness. Furthermore, the differences between models C1F and S1F, or C1F5 and C1F5 respectively, are of the same amplitude as the differences between the initial models C1 and S1. This suggests that, while a stronger feedback can moderately increase the disk fraction and half-mass radius of the final ETG, this effect is decoupled from the impact of using a cooling model generating turbulent gas rather than a thermally stabilized model. It does not strongly impact our previous conclusions on the effect of resolving gas cooling and strong ISM turbulence on the stellar size evolution and disk fraction in the final merger remnants.

3.6. Mergers of Lower-mass Galaxies

Our main set of simulations used galaxy models that were relatively massive (without being unrealistic) for the typical disks and spheroids observed at $z \sim 2$.

Lower-mass disk galaxies at $z \sim 2$, with circular velocities of 100–200 km s$^{-1}$, also show giant clumps of star formation and gas turbulent speeds of several tens of km s$^{-1}$ (Förster Schreiber et al. 2009; Wright et al. 2009), like the pre-merger galaxies in our models. ISM turbulence and clumpiness should thus have qualitatively similar effects in high- and low-mass major mergers. This can be explicitly checked using models LM-C2, LM-S2, and LM-C2F.

The structural parameters of these low-mass mergers remnant are given in Table 2, and the edge-on stellar distributions shown in Figure 7. The results are similar to what has been detailed previously for mergers of higher-mass galaxies: the gas velocity dispersions in the merging phase are higher in the cooling model, and the merger remnant is significantly more compact, with only a low fraction of its baryons in a rotating disk, while a significant disk component is found in the stabilized-ISM model. In detail, the relaxed ETG after the merger is comparatively more compact, with a stellar half-mass radius reduced by a factor of 2.5 in the cooling models compared to the stabilized-ISM model, versus 2–2.2 for the more massive cases.

4. COMPARISON TO OBSERVED GALAXY POPULATIONS

4.1. Kinematical Signatures and Dispersion-dominated Systems

The mergers modeled in realistic high-redshift conditions develop very high gas velocity dispersions, and could thus resemble some dispersion-dominated systems (DDS) observed in $z \sim 2$ surveys. To further probe whether such mergers would be easily identified in observations, three of us experienced in high-redshift spectroscopic data (T.C., B.E., K.S.) performed an eye classification of the velocity and dispersion fields from Figure 3 with gas density maps, and from Figure 4 without the density maps. The test was done without knowledge of the nature of the modeled systems. This test aims at understanding whether the kinematics of the simulated mergers would be recognized as typical for major mergers by observers familiar with the typical signatures expected for mergers. Additional instrumental/observational effects such as limited resolution, sensitivity, and noise, were not accounted for: hence this test relates only to the physical properties shown in Figures 3 and 4. Real observations could in addition miss small-scale or low-flux signatures and make the identification of mergers even more uncertain.

Model I is always recognized as an isolated disturbed disk, with some suggestions that the top-left clump could be a minor merger. The stabilized-ISM merger models are most often identified as mergers (two-thirds of the votes), generally with a high confidence level that these are binary major mergers. The cooling merger models were classified as DDS of unclear nature (about one-third of the votes), DDS of merger origin (one-third), or merger (one-third). More than half of the votes suggesting a merger or DDS merger also suggested a group or multiple merger rather than a binary major merger. This confirms that (1) ongoing mergers with clumpy turbulent gas could be classified as DDS and (2) typical high-redshift mergers have substantially different kinematics from low-redshift mergers or models with artificially stabilized gas, which have smoother velocity gradients along extended tidal tails.

Many observed DDS have small sizes, so the high observed dispersions could sometimes result from blending at low resolution, but seem real in general (Law et al. 2009). There are nevertheless DDS that are relatively massive, extended,
with chaotic velocity fields. Examples include Q1623-BX453, Q17000-BX710, and others in Law et al. (2009) and in Förster Schreiber et al. (2009). These could be major mergers of initially clumpy and turbulent galaxies, but their merger nature has not been clearly recognized yet because they lack the usual known signatures of mergers.

Disk galaxies with lower masses tend to be even more turbulent compared to the rotation speed (lower $V/\sigma$, e.g., Förster Schreiber et al. 2009). Reaching dispersion-dominated phases in mergers of such galaxies should be easier at lower mass. This might explain why observed DDS generally have small stellar masses, even though they are too numerous to all be major mergers. Overall, DDS are often suggested to result from violent gassy collapse (Law et al. 2009), which our models show can occur in high-redshift mergers.

The local turbulent speed of gas in our cooling models is typically 150–200 km s$^{-1}$ (Table 1), but the projected line-of-sight dispersions can be up to 500 km s$^{-1}$ for central clumps and up to 350 km s$^{-1}$ for other clumps. These very high dispersions arise on short phases, shortly after the interaction pericenter and about at the peak of SFR. These dispersions may seem higher than what is found in high-redshift spectroscopic surveys. Note however that our models C1 to C3 involve galaxies that are more massive than most objects targeted in spectroscopic surveys, so they naturally have higher circular, and higher dispersion velocities at fixed $V/\sigma$. Furthermore, these high dispersions would be blended out by seeing-limited observations without adaptive optics. Substantial samples of adaptive optics spectroscopic data really exist only for disk galaxies (e.g., Genzel et al. 2011). Other high-resolution data are unlikely to have targeted nearly equal-mass mergers at the peak of their high velocity dispersion phase. Whether or not the peak gas dispersions in our models are too high for real $z \approx 2$ objects is thus presently unknown; if this is the case, the effects of turbulence dissipation and size reduction in major mergers might be somewhat modest.

4.2. Submillimeter Galaxies as Ongoing Mergers?

SMGs are among the most actively star-forming objects at high redshift, and hence generally proposed to be the most actively starbursting phases of major mergers (Tacconi et al. 2008). An interesting test is then to compare the gas dynamics in our models to observations of SMGs. The properties of a representative $z = 2.3$ SMG, SMMJ2135-0102, have been mapped spatially owing to gravitational magnification by Swinbank et al. (2010). While the global properties are reminiscent of a gas-rich major merger, star formation takes place in a few giant clumps with sizes of 100–1000 pc, as in our merger models (Figure 1). Interestingly, Swinbank et al. (2010) and Danielson et al. (2011) noted that the molecular gas spectra have a multi-component shape. The spectrum is more complex than the usual double-horn profile observed for rotating gas disks (including clumpy high-redshift disks; Daddi et al. 2010a), and is best fitted by a combination of four main emitting components. Multi-component spectra in SMGs that are not just double-horn profiles were also suspected by Knudsen et al. (2009).

We modeled a “molecular gas” spectrum for model C1, 55 Myr after the pericenter passage, using gas denser than $500 \text{ cm}^{-3}$ as a proxy for molecular gas. The modeled spectrum, corresponding to the second snapshot on Figure 1, is shown in Figure 8. It has a multi-component aspect similar to that in the observation. Our models did not aim to reproduce this SMG in particular, and each individual component is not reproduced, but the amplitude of the emitting peaks is consistent with the spectra observed by Danielson et al. (2011). This property results from the dense cold gas (and star formation) being mostly located in a few giant clumps. Interestingly, the stellar mass at this instant in model C1 is $2 \times 10^{10} \text{ M}_{\odot}$, with a gas fraction of 40%, close to the estimates for SMMJ2135-0102. The SIR in the model is 1400 $\text{ M}_{\odot} \text{ yr}^{-1}$, somewhat higher than observational estimates for this object (Ivison et al. 2010) but not inconsistent with SMG-like activity in general. The modeled molecular gas spectrum has a full width at half-maximum (FWHM) and a full width at zero intensity that are quite close to the observed values, suggesting quantitative agreement on global gas dynamics between our model and a typical SMG of similar mass. Furthermore, Danielson et al. (2011) noted that the denser molecular gas tracers (such as high-J CO lines) have more peaked spectra, while lower-density tracers have smoother spectra (Greve et al. 2005 also found relatively smooth low-J spectra in SMGs). This is consistent with the peaked components being associated with dense star-forming clumps, and with our models showing smoother spectra for lower-density gas (Figure 8). Higher-resolution simulations resolving cooling down to lower temperatures would be required to qualitatively explore further this temperature dependence of molecular gas dynamics in SMGs.

Standard models of high-redshift mergers using warmed stabilized gas to model the ISM are only mildly successful in explaining the properties of SMGs. They can model $805 \mu \text{m}$ fluxes that account for SMGs (Narayanan et al. 2010), but only when the pre-merger disks are calibrated to high submillimeter fluxes: the typical enhancement of the $850 \mu \text{m}$ flux during the merger/SMG phase is not larger than a factor of 2–3. These models also have smooth gas kinematics. If dust follows the scattering of gas in a three-dimensional distribution in and around the centrally collapsed system, as in our models, then the obscuration of star formation could be very high under some lines of sight, like in SMGs (Thronson et al. 1990).

Another model of SMGs suggests that they are the high-mass end of cold-flow galaxies, with no mergers involved (Davé et al. 2010). Some SMGs could be like this, particularly those with...
large radii, relatively low SFRs, and relatively long durations compared to the orbit time. The SMGs in our model have much stronger bursts and the disk gas is consumed more quickly than in the cold-flow models, so we expect a different proportion of elemental abundances in these two cases, and different star formation histories. Multi-component gas spectra could be a confirmation of a clumpy merger origin for SMGs, if they appear to be commonly observed in larger samples.

4.3. Clumpy Morphologies in High-redshift Mergers and ETGs

The stellar distribution in our models shortly after the pericenter resembles a single “clumpy galaxy,” but it is more asymmetric than the pre-merger clumpy disk models (see second and third panels in Figure 1). This could be consistent with the population of “assembly galaxies” in Elmegreen et al. (2007), with entirely clumpy morphologies not consistent with their being isolated disks. Other examples of high-redshift clumpy mergers can be found in Lotz et al. (2006).

Our modeled high-redshift clumpy mergers lack very prominent tidal tails. There are long tidal features, but they are less contrasted than the star-forming clumps. This differs from low-redshift mergers, where long tidal tails with ample and smooth velocity gradients are typical (e.g., Bournaud et al. 2004b).

Once the mergers are relaxed, stellar clumps are seen in the central kpc of the final ETGs (Figure 2). They are relatively young (1–2 × 10⁸ yr in the final snapshots) and their masses are all lower than 2 × 10⁸ M⊙—while our pre-merger disk models harbor clumps of several 10⁸ M⊙. A lower clump mass is expected from stabilization of the merger remnant by the main stellar spheroid (Martig et al. 2009; Dekel et al. 2009a). Residual star formation is associated with those clumps after the merger, consistent with high-redshift red, but not completely dead, ETGs (Tonini et al. 2010).

These clumps might be harder to observe than the most massive ones in z ~ 2 star-forming disk galaxies, but young stellar clumps have actually been observed in the central body of high-redshift ellipticals in the Hubble Ultra Deep Field (UDF; Elmegreen et al. 2005, see examples in Figure 9). Those clumps have young stellar ages, and their masses are typically a fraction 10⁻³–10⁻⁴ of their host galaxy masses—lower than in clumpy disks but consistent with our ETG models. Other clumps are also seen around several ETGs in the Mancini et al. (2010) sample.

The outermost clumps, those formed at more than 50 kpc from the center in model C1, could become dwarf galaxies formed during the merger (tidal dwarf galaxies (TDGs) Duc et al. 2000). This would lend support to recent suggestions that the rate of TDG formation could be high at high redshift (Kroupa et al. 2010).

4.4. Compact High-redshift ETGs

Our merger models with cooling predict final stellar distributions that are relatively compact. The properties of the final ETGs in our cooling models are comparable with the properties of the three most compact high-redshift ETGs in the Mancini et al. (2010) sample with similar masses, as well as some objects in Cappellari et al. (2009). Faint extended stellar halos with high Sérsic indices are present in the observations, like the one surrounding the massive kpc-sized core in the final ETG of model C1 (Figure 4).

Real mergers should involve various mass fractions, gas fractions, and degrees of stability and clumpiness in disk galaxies. Thus, they should form a variety of ETGs, ranging from very compact objects (as spectroscopically confirmed; van Dokkum et al. 2009; Cappellari et al. 2009) to more extended ones (as present in the Mancini et al. sample). If high-redshift galaxies with lower masses are relatively more turbulent (Förster Schreiber et al. 2009), then their mergers could be even more dissipative than the more massive disk galaxies. Then the most compact ETGs would be the lowest mass (Section 3.5). Such a trend is observed among the various samples of high-redshift spheroids (see Figure 4 in Mancini et al. 2010).

Wuyts et al. (2010) also proposed recently that high-redshift mergers lead to the formation of compact ETGs. Their simulations have a stabilized, pressurized ISM model (although implementation details differ from our “stabilized” models). There is some compacting of the system during the merger, but at the same level as in our stabilized models and not at the level of our cooling models of clumpy galaxy mergers. Actually, to form ETGs that are about as compact as z ~ 2 ones, Wuyts et al. (2010) had to start with pre-merger disk galaxies that were twice as compact as our initial disk galaxies, with a disk scale length half as large. Which initial conditions are more realistic in terms of disk sizes is unknown. The known size evolution between z ~ 2 and z = 0 (Franx et al. 2008) mostly concerns spheroids. Bouché et al. (2007) propose that high-redshift disks have the same velocity–size relation as disk galaxies at z = 0 and a spin parameter two to six times larger than in the Wuyts et al. initial conditions, but this was called into question by Dutton et al. (2011). Our initial disk galaxies still seem realistic for massive star-forming disks at z ~ 2: a radial scale length of 5 kpc for a circular velocity of 245 km s⁻¹, to be compared for instance to the sub-sample of disk galaxies in Förster Schreiber et al. (2009, Figure 18).

It thus appears that a major merger model can produce the transformation of a typical z ~ 2 star-forming disk galaxies (hence relatively extended) into a typical high-redshift ETG, only if ISM cooling, turbulence, and clumpiness are captured in the simulation. Observations do suggest that compact ETGs formed from relatively diffuse disks, rather than disk galaxies that are already compact (Ricciardelli et al. 2010).
It nevertheless seems that our models predict Sersic indices that are somewhat higher than those estimated for compact high-redshift ETGs. In observations, Puech et al. (2006) also noted that compact luminous galaxies at high redshift rarely show rotational support, but instead have large dispersions and chaotic velocity fields. They suggested that high-redshift mergers produce compact remnants.

4.5. Long-term Evolution Towards Low-redshift Ellipticals

High-redshift ETGs probably do not survive in the form of compact objects in the nearby Universe. They should grow mostly through minor mergers, which can increase their stellar sizes (Naab et al. 2009). In this dry process, the small and compact disk components remaining after high-redshift mergers (Figure 1 at t = 625) could undergo inefficient star formation (Martig et al. 2009) and persist as compact disks of residual gas and stars, as often found in the central kpc of nearby ellipticals (Young et al. 2008; Crocker et al. 2011).

Of course some of these high-redshift ETGs could accrete external gas in sufficient amount to re-form a bright and massive stellar disk, in a “spiral rebuilding” scenario, as proposed for instance by Puech et al. (2006). However, our models show that such disk rebuilding does not happen spontaneously from gas expelled during the merger (in tidal tails and/or through feedback processes) that would later on fall back onto a disk. Large accretion of external gas would be required to rebuild a massive star-forming disk galaxy. Models by Martig et al. (2009) have shown that this can naturally happen in some halos in ΛCDM cosmology, when the late mass assembly history is dominated by smooth infall rather than mergers.

5. CONCLUSIONS

The ISM is very turbulent and clumpy in high-redshift galaxies. Simulations of high-redshift mergers with cooling and sufficient resolution to develop turbulence and dense gas clouds show major differences compared to models with smooth, thermally supported disks:

1. Ongoing mergers of representative high-redshift galaxies can have very irregular gaseous spheroids during the merger, with clumps and filaments throughout, instead of rotating gas disks surrounded by long tidal tails with ample and smooth velocity gradients, as is common in low-redshift mergers.

2. The gas velocity dispersion in these mergers becomes very high. At some stage, most of the gas kinetic energy is in the form of a three-dimensional velocity dispersion. Such mergers could take the appearance of dispersion-dominated galaxies with high gas dispersions and chaotic velocity fields. Their spectral properties are also consistent with SMGs.

3. Turbulent and clumpy gas undergoes a violent and dissipative collapse in mergers. The final ETGs in these mergers are relatively compact, with high Sersic indices and faint outer stellar halos.

4. The masses and sizes of disk components that survive or re-form after major mergers are strongly reduced when the hydrodynamics of the cold turbulent ISM is taken into account. Large disks at high redshift should form mainly through cold accretion rather than mergers.

5. Strong feedback processes can somewhat increase the size and disk fraction of the final ETGs formed in these mergers, but the impact of directly modeling a cold turbulent ISM phase rather than using a thermally pressurized model remains independent from the efficiency of stellar feedback.

Wet mergers at high redshift should involve galaxies that have turbulent and clumpy gas-rich disks. Mergers of such galaxies can undergo dispersion-dominated phases. They can also produce starbursts with SMG-like properties. The late phases are accompanied by dissipative collapse and the formation of compact ETGs. This is consistent with the evolutionary sequence proposed, e.g., by Ricciardelli et al. (2010). Massive rotating disk components cannot easily survive such mergers, a property that is not reproduced correctly by simulations where ISM turbulence and clumpiness are unresolved and modeled with a thermally pressurized EoS. Large rotating gas-rich disks at high redshift, such as those observed by Genzel et al. (2006) and others, are probably not the outcome of a mass assembly dominated by mergers. Large far-out reservoirs of gas, pre-existing to mergers or fed by strong feedback during the mergers, could participate to some disk rebuilding (as observed in the Governato et al. 2009 model). Stellar mass-loss and gravitational torquing over cosmological timescales can help preserve large disks (as in the Martig & Bournaud 2010 model, see also Leitner & Kravtsov 2010), but continuous cosmological infall of fresh gas probably dominates the assembly of disk-dominated galaxies down to z = 0.

If gas-rich mergers at high-redshift are characterized by strong turbulence, the spread of the gas density distribution could be very large, as it scales with the turbulent mach number (Krumholz & Thompson 2007). Not only the average gas density would be high, but there would also be an excess of dense gas at number densities of thousands per cm³ and more, compared to non-interacting systems. Dense gas excess has already been found from low-redshift merger models (e.g., Juneau et al. 2009; Teyssier et al. 2010) and could explain the enhanced HCN/CO ratios in nearby ULIRGs. An excessive fraction of dense gas could also increase the SFR at fixed average gas density, possibly consistent with recent observations of star formation in disks and mergers suggesting enhanced efficiency of gas consumption in mergers (Daddi et al. 2010b; Genzel et al. 2010).

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