On the local limit theorems for psi-mixing Markov chains

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Abstract. In this paper we investigate the local limit theorem for additive functionals of a nonstationary Markov chain with finite or infinite second moment. The moment conditions are imposed on the individual summands and the weak dependence structure is expressed in terms of some uniformly mixing coefficients.

1. Introduction

A local limit theorem for partial sums \((S_n)_{n \geq 1}\) of a sequence of centered random variables is a result about the rate of convergence of the probabilities of the type \(P(a \leq S_n \leq b)\). Local limit theorems have been initially studied for the case of lattice random variables. The lattice case means that there exists \(v > 0\) and \(a \in \mathbb{R}\) such that the values of all the variables in the sum \(S_n\) are concentrated on the lattice \(\{a + kv : k \in \mathbb{Z}\}\), whereas the nonlattice case means that no such \(a\) and \(v\) exists.

This type of limit theorem is a deep result, a fine scale behavior of the sums \(S_n\) Controlling such probabilities is important for finding recurrence conditions for a random walk, as pointed out in Orey (1966) and further developed in Mineka and Silverman (1970), Mineka (1972). Theorems of this type are also useful in combinatorics. Bender (1973) considered asymptotic enumeration, Philipp (1988) considered continued fraction expansion, while Giuliano and Weber (2016) analyzed random models used in arithmetical number theory. In dynamical systems Guivarc'h and Hardy (1988), Aaronson and Denker (2001a) obtained local limit theorems for Gibbs Markov maps. For these reasons, this is an area of intense research in probability, dynamical systems, number theory and analysis.
This field has a rich history, and originates in the classical De Moivre-Laplace theorem, which is 283 years old and precedes the central limit theorem. The early results deal with the behavior of \( \mathbb{P}(S_n = k) \), where \( S_n \) is a sum of i.i.d. Bernoulli random variables. Among early results on local limit theorems we mention works by Gnedenko (1948) and Gnedenko and Kolmogorov (1954). For historical notes we direct the reader to McDonald (2005).

This problem was intensively studied for i.i.d. sequences of random variables in further works by Shepp (1964), Stone (1965) and Feller (1967), just to name a few.

Local limit theorems for sums of independent non-identically distributed random variables serve as a basic mathematical tool in classical statistical mechanics and quantum statistics (see Khinchin, 1949; Hincin, 1951). There are examples in the literature showing that, in the nonstationary case, the local limit theorems are more delicate than their convergence in distribution counterparts and, in general, require additional assumptions. An important counterexample is given by Gamkrelidze (1964), pointing out this phenomenon for independent summands and a variety of sufficient conditions were developed over the years. We mention especially Rozanov’s condition in the lattice case (see Rozanov (1957)), Statuljavičus’s condition (see Statuljavičus, 1965) and the Mineka-Silverman condition in the non-lattice case (see Mineka and Silverman, 1970). They were further developed in Maller (1978) and Shore (1978). A unified discussion of these conditions can be found in Mukhin (1991).

There are also numerous more recent developments in several directions for independent structures. Dolgopyat (2016) treated the vector valued sequences of independent random variables.

Concerning dependent random variables we should mention early works on Markov chains by Kolmogorov (1962). In the lattice case, for countable state Markov chains with finite second moments, the local limit theorem is discussed in Siraždinov (1955) and Séva (1995) while the case of infinite variance is analyzed in Aaronson and Denker (2001a) and Szewczak (2008, 2010). Also in the stationary case we mention the local limit theorems for Markov chains in the papers by Hervé (1962) and Bryc (1990, 1992) the concept of \( \psi \)-mixing Markov chains. As noticed in Denker (1992) and Bryc (1990, 1992) the concept of \( \psi \)-mixing is well suited to derive large deviation results. As examples of \( \psi \)-mixing Markov chains we mention Gibbs-Markov dynamical systems introduced in Aaronson and Denker (2001b), which contain finite state aperiodic Markov chains and certain recurrent Markov chains with infinite state space.

In this paper we shall continue the study of the local limit theorem for a class of nonstationary \( \psi \)-mixing Markov chains.

We assume now that \( (\xi_k)_{k \geq 1} \) is a Markov chain defined on \( (\Omega, \mathcal{K}, \mathbb{P}) \) with values in \( (S, \mathcal{B}(S)) \) with regular transition probabilities,

\[
Q_k(x, A) = \mathbb{P}(\xi_k \in A | \xi_{k-1} = x); \quad P_k(A) = \mathbb{P}(\xi_k \in A) \quad \text{where} \quad A \in \mathcal{B}(S).
\]

Also, we denote by \( Q_k \) the associated operator defined on \( L_2(\mathcal{B}(S)) \) by \( Q_k g(x) = \int g(y)Q_k(x, dy) \).

For some real-valued measurable functions \( g_j \) on \( S \) define

\[
X_j = g_j(\xi_j). \tag{1.1}
\]

The sequence \( (X_j)_{j \geq 1} \) is assumed centered (\( \mathbb{E}(X_j) = 0 \) for all \( j \geq 1 \)) and, unless otherwise specified, having finite second moments (\( \mathbb{E}(X_j^2) < \infty \) for all \( j \geq 1 \)). Set

\[
S_n = \sum_{k=1}^{n} X_k, \quad \sigma_n^2 = \mathbb{E}(S_n^2) \quad \text{and} \quad \tau_n^2 = \sum_{j=1}^{n} \mathbb{E}(X_j^2).
\]

We shall assume that there are two constant \( a > 0 \) and \( b < \infty \) with the following property:
For all \( k \geq 2 \) there is \( S'_k \in \mathcal{B}(S) \) with \( P_{k-1}(S'_k) = 1 \) such that for all \( A \in \mathcal{B}(S) \) and \( x \in S'_k \) we have
\[
aP_k(A) \leq Q_k(x, A) \leq bP_k(A). \tag{1.2}
\]

Denote
\[
\gamma = \frac{a^4}{b}.
\]

Clearly \( b \geq 1 \) and \( a \leq 1 \).

Throughout the paper we shall assume that \( \tau^2_n \to \infty \). As we shall see latter, since we assume \( a > 0 \), the condition \( \tau^2_n \to \infty \) is equivalent to \( \sigma^2_n \to \infty \) (see subsection 3.2).

In order to obtain our results we shall combine several techniques specifically designed for obtaining local limit theorems with a bound on the characteristic function using \( \gamma \). More precisely, the conditions and techniques are rooted in Mineka and Silverman (1970) and Maller (1978), who treated the local limit theorem in the non-lattice setting, for sequences of independent random variables not identically distributed. We shall prove that if we assume (1.2), then the results referring to the local CLT in Maller (1978) and also in Mineka and Silverman (1970) can be extended from independent sequences of random variables to the Markovian case. Furthermore we shall also consider the situation when the variables have infinite variance and are in the domain of attraction of the normal law.

Our paper is organized as follows. In Section 2 we present the local limit theorem for nonstationary Markov chains. In Section 3 we present bounds on the characteristic function of sums, bounds of the variance of sums and proofs of the main results.

In the following sections, the notation \( a(n) = o(n) \) means that \( a(n)/n \to 0 \) as \( n \to \infty \). Also by \( \Rightarrow \) we denote the convergence in distribution.

In the sequel we shall denote by \( f_k(t) \) the Fourier transform of \( X_k \),
\[
f_k(t) = f_{X_k}(t) = \mathbb{E}(\exp(itX_k)).
\]

2. Results

The first condition we shall impose is the usual Lindeberg condition needed to obtain the CLT.

**Lindeberg’s condition.** For any \( \varepsilon > 0 \),
\[
\frac{1}{\tau^2_n} \sum_{k=1}^{n} \mathbb{E}(X_k^2 I(|X_k| \geq \varepsilon \tau_n)) \to 0. \tag{2.1}
\]

From Gamkrelidze (1964) we know that this condition is not sufficient for a local limit theorem. We shall impose a balance-type condition involving moments of order 2.

**Condition C.** There is 0 \( \leq c < 1 \) and \( \delta > 0 \) such that
\[
\lim sup_{n \to \infty} \frac{\sum_{k=1}^{n} \mathbb{E}(X_k^2 I(|X_k| > \delta))}{\tau^2_n} < c.
\]

Next condition is a nonlattice-type condition. Recall that a random variable \( X \) has a nonlattice distribution is equivalent to \( |f_X(t)| < 1 \) for all \( t \neq 0 \).

**Condition C.** Assume (2.1) and for all \( u \neq 0 \) there is an open interval \( O_u \) containing \( u \) and a \( n_0 = n_0(u) \) such that for all \( t \in O_u \) and \( n > n_0 \),
\[
\frac{1}{n} \sum_{k=1}^{n} |f_k(t)|^2 < 1. \tag{2.2}
\]

Our general local limit theorem is as follows:
Theorem 2.1. Let \((X_j)_{j \geq 1}\) be defined by (1.1). Assume that Conditions C₁, C₂, (1.2) and (2.1) are satisfied. Then, for any function \(h\) on \(\mathbb{R}\) which is continuous and with compact support,
\[
\lim_{n \to \infty} \sup_{u \in \mathbb{R}} \left| \frac{\sqrt{2\pi}\sigma_n \mathbb{E} h(S_n - u) - \exp(-u^2/2\sigma_n^2) \int h(u) \lambda(du)}{\sqrt{2\pi}\sigma_n} \right| = 0, \tag{2.3}
\]
where \(\lambda\) is the Lebesgue measure on the real line.

It is well known that the convergence in (2.3) implies that for any \(c\) and \(d\) real numbers with \(c < d\)
\[
\lim_{n \to \infty} \sup_{u \in \mathbb{R}} \left| \frac{\sqrt{2\pi}\sigma_n \mathbb{P}(c + u \leq S_n \leq d + u) - (d - c) \exp(-u^2/2\sigma_n^2)}{\sqrt{2\pi}\sigma_n} \right| = 0.
\]
In particular, since \(\sigma_n \to \infty\) as \(n \to \infty\), then for fixed \(A > 0\),
\[
\lim_{n \to \infty} \sup_{|u| \leq A} \left| \frac{\sqrt{2\pi}\sigma_n \mathbb{P}(c + u \leq S_n \leq d + u) - (d - c)}{\sqrt{2\pi}\sigma_n} \right| = 0.
\]
If we further take \(u = 0\), then
\[
\lim_{n \to \infty} \sqrt{2\pi}\sigma_n \mathbb{P}(S_n \in [c, d]) = d - c.
\]
In other words, the sequence of measures \(\sqrt{2\pi}\sigma_n \mathbb{P}(S_n \in [c, d])\) of the interval \([c, d]\) converges to the Lebesgue measure.

As we can easily verify, condition C₁ is satisfied under stronger condition: There is \(0 \leq c < 1\) and \(\delta > 0\) such that
\[
\frac{\mathbb{E}(X_k^2 I(|X_k| > \delta))}{\mathbb{E}(X_k^2)} < c \text{ for all } k, \tag{2.4}
\]
and also under Mineka and Silverman (1970) condition, namely: For some \(\delta > 0\) and \(d > 0\),
\[
\mathbb{E}(X_k^2 I(|X_k| \leq \delta)) \geq d \mathbb{E}(X_k^2) \text{ for all } k.
\]

Clearly Condition C₁ is trivially implied if there is \(C > 0\) such that \(|X_k| \leq C\) a.s. for all \(k\), or under the near stationarity assumption:

There is a random variable \(X\) and constants \(0 \leq c_1 \leq 1\) and \(c_2 \geq 1\) such that
\[
c_1 \mathbb{P}(|X| \geq x) \leq \mathbb{P}(|X_k| \geq x) \leq c_2 \mathbb{P}(|X| \geq x) \text{ for all } x \geq 1 \text{ and all } k \in \mathbb{N}.
\]

Condition C₂ is satisfied in the stationary case if the marginal distribution satisfies \(|f_0(t)| < 1\) for all \(t \neq 0\).

Remark 2.2. As we can notice from formula (3.1), instead of the right hand side of condition (1.2) we can use a slightly weaker version of it, namely
\[
aP_k(A) \leq Q_k(x, A) \text{ and } \int Q_k(y, A)Q_{k-1}(x, dy) \leq bP_k(A). \tag{2.5}
\]

Remark 2.3. Theorem 2.1 can be reformulated for triangular arrays of Markov chains \((\xi_{n,i})\) for all \(1 \leq i \leq n\) and \(X_{n,i} = g_{n,i}(\xi_{n,i})\). The difference is that in condition (2.1) and in Conditions C₁ and C₂ the we have to replace \(X_k\) by \(X_{n,k}\) and \(f_k\) by \(f_{n,k}\). The relations in (1.2) become for \(a > 0\) and \(b < \infty\)
\[
aP_{n,k}(A) < Q_{n,k}(x, A) \leq bP_{n,k}(A).
\]

By using Theorem 2.1 we can treat linear statistics with coefficients which are uniformly bounded above and stay away from 0.

Corollary 2.4. Assume that \((\xi_k)_{k \in \mathbb{Z}}\) is a strictly stationary Markov chain. For a measurable function \(g\) and \(k \in \mathbb{Z}\), define \(X_k = g(\xi_k)\). Assume that \(\mathbb{E}(X_k) = 0\) and \(\mathbb{E}(X_k^2) < \infty\). Assume that \(X_0\) has a non-lattice distribution and condition (1.2) is satisfied. We consider an array of real
numbers \((a_{n,k})_{k \geq 1}\) such that there are two positive constants \(m, M\) with \(0 < m \leq |a_{n,k}| \leq M\) for all \(n\) and \(k\). Define
\[
X_{n,\ell} = a_{n,\ell}X_{\ell}.
\]
Then, for any function \(h\) on \(\mathbb{R}\) which is continuous and with compact support, \(S_n = \sum_{\ell=1}^{n} X_{n,\ell}\) satisfies (2.3).

**Remark 2.5.** Note that the strictly stationary case follows from Corollary 2.4 if we take for all \(1 \leq \ell \leq n\) the constants \(a_{n,\ell} = 1\).

With a very similar proof as of Corollary 2.4 we can treat the linear processes with short memory.

**Corollary 2.6.** Let \((X_k)_{k \in \mathbb{Z}}\) be as in Corollary 2.4. Let \((a_i)_{i \geq 1}\) be a sequence of real numbers such that \(\sum_{i \geq 1} |a_i| < \infty\) and \(m = \inf_j |A_j| > 0\), where \(A_j = a_1 + a_2 + \ldots + a_j\). Construct
\[
Y_k = \sum_{i \geq 1} a_i X_{k+i} \quad \text{and} \quad S_n = \sum_{k=1}^{n} Y_k.
\]
Assume that \(X_0\) has a non-lattice distribution and condition (1.2) is satisfied. Then, for any function \(h\) on \(\mathbb{R}\) which is continuous and with compact support,
\[
\lim_{n \to \infty} \sup_{u \in \mathbb{R}} \left| \sqrt{2\pi} \sigma_n A |\mathbb{E}h(S_n - u) - \exp(-u^2/2\sigma_n^2 A^2) \int h(u) \lambda(du)\right| = 0,
\]
where \(\sigma_n^2 = \mathbb{E}(\sum_{i=1}^{n} X_i)^2\) and \(A = \lim_{j \to \infty} A_j\).

We can also provide a result for the stationary situation when the variance of the individual summands can be infinite. As an application of the proof of Theorem 2.1 we obtain the following corollary:

**Corollary 2.7.** Assume that \((\xi_k)_{k \in \mathbb{Z}}\) is a strictly stationary Markov chain. Define \((X_k)_{k \in \mathbb{Z}}\) by \(X_k = g(\xi_k)\) and assume \(\mathbb{E}(X_0) = 0\) and \(H(x) = \mathbb{E}(X_0^2 I(|X_0| \leq x))\) is a slowly varying function as \(x \to \infty\). Assume (1.2) and \(X_0\) has a non-lattice distribution. Then there is \(b_n \to \infty\) such that for any function \(h\) on \(\mathbb{R}\) which is continuous and with compact support,
\[
\lim_{n \to \infty} \sup_{u \in \mathbb{R}} \left| \sqrt{2\pi} b_n |\mathbb{E}h(S_n - u) - \exp(-u^2/2b_n^2) \int h(u) \lambda(du)\right| = 0.
\]

As far as we know this corollary is new, though for Gibbs-Markov processes the result is provided in Aaronson and Denker (2001a) and for continued fraction processes can be found in Szewczak (2010).

On the other hand, we can start with a stationary Markov chain \((\xi_k)_{k \in \mathbb{Z}}\) satisfying condition (1.2) and then construct the nonstationary sequence \(X_{n,k} = g_{n,k}(\xi_k)\) satisfying our conditions and therefore provide new results. Here below are two such examples:

**Example 1.** (Continued fraction expansion) For every irrational number \(x\) in \((0, 1)\) there is a unique sequence of positive integers \(x_1, x_2, x_3, \ldots\) such that the following continued fraction expansion holds:
\[
x = \frac{1}{x_1 + \frac{1}{x_2 + \frac{1}{x_3 + \ldots}}}.
\]
If we introduce on \([0, 1]\) the Gauss probability measure with the density \(f(x) = (\ln 2)^{-1}(1 + x)^{-1}\), then the sequence \((x_1, x_2, x_3, \ldots)\) is a strictly stationary Markov chain. We know from Lemma 2.1 in Philipp (1988) that one can take for \(a\) and \(b\) which appear in condition (1.2) \(a = 0.2\) and \(b = 1.8\). Now we can consider \(X_k\) defined by (1.1) as a measurable function of \(x_k\) and apply both Corollary 2.4 and Corollary 2.7.
Example 2. (Gibbs Markov chains). Let $S$ be a countable set, $p : S \times S \to [0,1]$ be an aperiodic, irreducible stochastic matrix and $\pi_s \pi_s > 0$ for all $s \in S$, $\sum_{s \in S} \pi_s = 1$. Let $T : S^N \to S^N$ be the shift and define the Markov chain in a canonical way on $S^N$ by

$$
P(X_1 = x_1, \ldots, X_n = x_n) = \pi_{x_1} p(x_1, x_2) \cdots p(x_{n-1}, x_n).
$$

Let $\Omega \subset S^N$ such that $\Omega = \{ x \in S^N : P(X_1 = x_1, \ldots, X_n = x_n) > 0 \}$. We assume that there is $M > 1$ such that for all $s, t \in S$

$$
\frac{1}{M} \pi_t \leq p(s, t) \leq M \pi_t \quad (2.6)
$$

Then our condition (1.2) is satisfied and our results applied for suitable functions $g_{n,k}$. Such a chain is called Gibbs-Markov. For other examples of Gibbs Markov maps see Aaronson and Denker (2001b).

Example 3. In the context of Example 2, a fairly large class of countable state Markov processes satisfying condition (2.6) can be constructed by defining for $i, j \in \mathbb{N}^*$

$$
p(i, j) = \pi_j + (\delta_{i,j} - \delta_{i+1,j})\varepsilon_i,
$$

where for all $i \in \mathbb{N}^*$, $\delta_{i,i} = 1$ and for $j \neq i$ we have $\delta_{i,j} = 0$. We take $0 \leq \varepsilon_i \leq \min(1 - \pi_i, \pi_{i+1})$. In addition we assume that there is $M > 1$ such that

$$
\varepsilon_i \leq (M - 1) \min(\pi_i, \pi_{i+1}/M).
$$

For example, let $M = 2$, $\pi_j = 2^{-j}$ and set $p(i, j) = 2^{-j} + (\delta_{i,j} - \delta_{i+1,j})2^{-(3+i)}$.

3. Proofs

3.1. Bounds on the characteristic function. The bound on the characteristic function of a Markov chain is inspired by Lemma 1.5 in Nagaev (1961). It is given in the following proposition.

Proposition 3.1. Let $(X_j)_{j \geq 1}$ be defined by (1.1). Then

$$
|\mathbb{E}(\exp(iuS_n)|^4 \leq \prod_{j=1}^n \left[ 1 - \frac{\gamma}{2} (1 - |f_j(u)|^2) \right].
$$

For proving this proposition we need some preliminary considerations. For $u$ fixed let us introduce the operator $T_k = T_{u,k}$ defined on complex-valued bounded functions by:

$$
T_k(h)(x) = \int h(y) \exp(iug_k(y)) Q_k(x, dy).
$$

So

$$
T_k(h)(\xi_{k-1}) = \mathbb{E}(h(\xi_k) \exp(iuX_k))|\xi_{k-1}).
$$

Notice that the values are also complex-valued bounded functions.

For an operator $T$ on $L_\infty(S, B(S))$ denote by $||T||=\sup_{|f|_\infty < 1} |T_k(f)|_\infty$.

Lemma 3.2. For any $k \in N$, $u \in \mathbb{R}$ we have for all $k \geq 2$,

$$
||T_{k-1} \circ T_k||^2 \leq 1 - \frac{\gamma}{2} (1 - |\mathbb{E}(\exp(iuX_{k-1}))|^2).
$$

Proof. Without restricting the generality we shall assume that (1.2) is satisfied. Let $x \in S'$, where $S' \subset B(S)$ such that $P_{k-1}(S') = 1$, for which condition (1.2) holds. By the definition of $T_k$’s

$$
T_{k-1} \circ T_k(h)(x) = \int \exp(iug_{k-1}(y)) \int h(z) \exp(iug_k(z)) Q_k(y, dz) Q_{k-1}(x, dy).
$$
Changing the order of integration

\[ T_{k-1} \circ T_k(h)(x) = \int h(z) \exp(iug(z)) \int \exp(iug_{k-1}(y))Q_{k-1}(x, dy)Q_k(y, dz) \]

\[ = \int h(z) \exp(iug(z))m_x(dz), \]

where, for \( x \) fixed, \( m_x \) is the measure defined on \( B(S) \) by

\[ m_x(A) = \int \exp(iug_{k-1}(y))Q_k(y, A)Q_{k-1}(x, dy). \]

Denote by \( \text{Var}(m_x) \) the total variation of \( m_x \). With this notations and because \( h \) is bounded by 1,

\[ |T_{k-1} \circ T_k(h)(x)| \leq \text{Var}(m_x). \]

Now, in order to compute the total variation for \( m_x \) we start from the following estimate:

\[ \left( \int Q_k(y, A)Q_{k-1}(x, dy) \right)^2 - \left| \int \exp(iug_{k-1}(y))Q_k(y, A)Q_{k-1}(x, dy) \right|^2 \]

\[ = \int (1 - \cos(u(g_{k-1}(y) - g_{k-1}(y'))))Q_k(y, A)Q_{k-1}(x, dy)Q_k(y, A)Q_{k-1}(x, dy') \]

\[ = \int 2 \sin^2 \left( \frac{u}{2}(g_{k-1}(y) - g_{k-1}(y')) \right)Q_k(y, A)Q_{k-1}(x, dy)Q_k(y, A)Q_{k-1}(x, dy') \]

\[ \geq a^4P_k(A) \int 2 \sin^2 \left( \frac{u}{2}(g_{k-1}(y) - g_{k-1}(y')) \right)P_{k-1}(dy)P_{k-1}(dy'). \]

But

\[ \int Q_k(y, A)Q_{k-1}(x, dy) + \left| \int \exp(iug_{k-1}(y))Q_k(y, A)Q_{k-1}(x, dy) \right| \leq 2bP_k(A). \tag{3.1} \]

So, we obtain

\[ \left( \int Q_k(y, A)Q_{k-1}(x, dy) \right)^2 - \left| \int \exp(iug_{k-1}(y))Q_k(y, A)Q_{k-1}(x, dy) \right|^2 \]

\[ \geq \frac{a^4}{2b}P_k(A) \int 2 \sin^2 \left( \frac{u}{2}(g_{k-1}(y) - g_{k-1}(y')) \right)P_{k-1}(dy)P_{k-1}(dy') \]

\[ = \frac{a^4}{2b}P_k(A)(1 - |f_{k-1}(u)|^2). \]

Therefore

\[ |m_x(A)| \leq \int Q_k(y, A)Q_{k-1}(x, dy) - \frac{a}{2}P_k(A)(1 - |f_{k-1}(u)|^2). \]

Now we consider \( (A_i)_{i \in J} \) a finite partition of \( S \), with sets in \( B(S) \). Then

\[ \sum_{i \in J} |m_x(A_i)| \leq 1 - \frac{a}{2}(1 - |f_{k-1}(u)|^2). \]

It follows that, for all \( x \in S' \),

\[ \text{Var}(m_x) \leq 1 - \frac{a}{2}(1 - |f_{k-1}(u)|^2), \]

and Lemma 3.2 follows. \( \square \)

**Proof of Proposition 3.1.** Note that

\[ \mathbb{E}(\exp(iuS_{2k})|\xi_0 = x) = T_1 \circ T_2 \circ \cdots \circ T_{2k}(1)(x). \]

So

\[ |\mathbb{E}(\exp(iuS_{2k})|\xi_0)| \leq ||T_1 \circ T_2|| \cdots ||T_{2k-1} \circ T_{2k}|| \ a.s. \]
By Lemma 3.2 we have that, for \( k \geq 1 \),
\[
|\mathbb{E}(\exp(iuS_{2k})|\xi_0)|^2 \leq \prod_{j=1}^{k} \left[ 1 - \frac{\gamma}{2}(1 - |f_{2j-1}(u)|^2) \right] \text{ a.s.}
\]
Also, by Lemma 3.2, for \( k \geq 1 \),
\[
|\mathbb{E}(\exp(iuS_{2k})|\xi_0)|^2 \leq ||T_2 \circ T_3||^2 \cdots ||T_{2k-2} \circ T_{2k-1}||^2 ||T_{2k}(1)||^2
\leq \prod_{j=1}^{k} \left[ 1 - \frac{\gamma}{2}(1 - |f_j(u)|^2) \right] \text{ a.s.}
\]
and so, by multiplying these two relations we get
\[
|\mathbb{E}(\exp(iuS_{2k})|\xi_0)|^4 \leq \prod_{j=1}^{2k} \left[ 1 - \frac{\gamma}{2}(1 - |f_j(u)|^2) \right] \text{ a.s.}
\]
A similar result can be obtain for \( |\mathbb{E}(\exp(iuS_{2k+1})|\xi_0)|^4 \). The result in Proposition 3.1 follows. □

3.2. Mixing conditions and the variance of partial sums. We shall clarify here the relation between \( a \) and \( b \) in condition (1.2) and several mixing coefficients for stochastic processes. Let \((\Omega, \mathcal{K}, \mathbb{P})\) be a probability space and let \( \mathcal{A}, \mathcal{B} \) be two sub \( \sigma \)-algebras of \( \mathcal{K} \). Define the maximal coefficient of correlation
\[
\rho(\mathcal{A}, \mathcal{B}) = \sup_{X \in \mathbb{L}_2(\mathcal{A}), Y \in \mathbb{L}_2(\mathcal{B})} |\text{corr}(X, Y)|,
\]
where \( \mathbb{L}_2(\mathcal{A}) \) is the space of random variables that are \( \mathcal{A} \) measurable and square integrable.

Relevant to our paper are the lower and upper \( \psi \)-mixing coefficients defined by
\[
\psi'(\mathcal{A}, \mathcal{B}) = \inf \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(A)\mathbb{P}(B)}; \ A \in \mathcal{A} \text{ and } B \in \mathcal{B}, \mathbb{P}(A)\mathbb{P}(B) > 0.
\]
\[
\psi^*(\mathcal{A}, \mathcal{B}) = \sup \frac{\mathbb{P}(A \cap B)}{\mathbb{P}(A)\mathbb{P}(B)}; \ A \in \mathcal{A} \text{ and } B \in \mathcal{B}, \mathbb{P}(A)\mathbb{P}(B) > 0.
\]

We would also want to mention that the well-known \( \psi \)-mixing coefficient introduced in Blum et al. (1963) can be defined as
\[
\psi(\mathcal{A}, \mathcal{B}) = \max[\psi^*(\mathcal{A}, \mathcal{B}) - 1, 1 - \psi'(\mathcal{A}, \mathcal{B})].
\]

By a result of Bradley (2020) we have the following lemma, which will be useful to analyze the variance of partial sums.

**Lemma 3.3.** (Bradley, 2020)
\[
\rho(\mathcal{A}, \mathcal{B}) \leq 1 - \psi'(\mathcal{A}, \mathcal{B}). \tag{3.2}
\]

**Proof:** For simplicity we denote \( \rho = \rho(\mathcal{A}, \mathcal{B}) \) and \( \psi' = \psi'(\mathcal{A}, \mathcal{B}) \). Without restricting the generality we assume \( \psi' > 0 \). By the definition of \( \rho \) we have to show that, for any \( X \in \mathbb{L}_2(\mathcal{A}) \) and \( Y \in \mathbb{L}_2(\mathcal{B}) \),
\[
|\mathbb{E}(XY)| \leq (1 - \psi')||X||_2||Y||_2.
\]

By a measure theoretic argument, for variables with values in a separable Hilbert space, it is enough to prove this lemma for simple functions with mean zero. So, let \( X = \sum_{i=1}^{n} a_i I(A_i) \) and \( Y = \sum_{j=1}^{m} b_j I(B_j) \), where \( A_i \in \mathcal{A} \) and \( B_j \in \mathcal{B} \) are partitions of \( \Omega \) and \( X \) and \( Y \) have mean 0.

Denote
\[
R(A_iB_j) = (1 - \psi')^{-1}\mathbb{P}(A_iB_j) - (1 - \psi')^{-1}\psi'\mathbb{P}(A_i)\mathbb{P}(B_j)
\]
and note that, by the definition of $\psi'$, for all $i$ and $j$ we have that $R(A_iB_j) \geq 0$. Also

$$\sum_{i=1}^{n} R(A_iB_j) = \mathbb{P}(B_j)$$

and

$$\sum_{j=1}^{m} R(A_iB_j) = \mathbb{P}(A_i).$$

Moreover, we have the decomposition

$$\mathbb{P}(A_iB_j) = \psi' \mathbb{P}(A_i) \mathbb{P}(B_j) + (1 - \psi') R(A_iB_j).$$

Now, since $\mathbb{E}(X) = 0$, clearly $\sum_{i=1}^{n} a_i \mathbb{P}(A_i) = 0$ and therefore, by the above identity,

$$\mathbb{E}(XY) = \sum_{i,j} a_i b_j \mathbb{P}(A_iB_j) = \sum_{i,j} a_i b_j (\psi' \mathbb{P}(A_i) \mathbb{P}(B_j) + (1 - \psi') R(A_iB_j))$$

$$= (1 - \psi') \sum_{i,j} a_i b_j R(A_iB_j).$$

It follows that

$$|\mathbb{E}(XY)| \leq (1 - \psi') \sum_{i,j} |a_i b_j| R(A_iB_j).$$

So, by applying Holder’s inequality twice,

$$\sum_{i,j} |a_i b_j| R(A_iB_j) \leq \sum_{i} |a_i| \left( \sum_{j} R(A_iB_j) \right)^{1/2} \left\{ \sum_{j} b_j^2 R(A_iB_j) \right\}^{1/2}$$

$$\leq \left[ \sum_{i} \sum_{j} |a_i|^2 R(A_iB_j) \right]^{1/2} \left[ \sum_{i} \sum_{j} |b_j|^2 R(A_iB_j) \right]^{1/2}$$

$$= \left[ \sum_{i} |a_i|^2 \mathbb{P}(A_i) \right]^{1/2} \left[ \sum_{j} |b_j|^2 \mathbb{P}(B_j) \right]^{1/2} = \|X\|_2 \|Y\|_2.$$

For a sequence $X = (X_k)_{k \geq 1}$ of random variables $\psi_k^+(X) = \inf_{m \geq 1} \psi^+(F_1^m, F_k^\infty, \mathbb{F}_k^m)$ and $\psi_k^-(X) = \sup_{m \geq 1} \psi^-(F_1^m, F_k^\infty, \mathbb{F}_k^m)$, where $F_k^m = \sigma(X_j, k \leq j \leq m)$.

For a Markov chain $\xi = (\xi_k)_{k \geq 1}$ the definitions simplify

$$\psi'_k = \inf_{m \geq 1} \psi' (\sigma(\xi_m), \sigma(\xi_{k+m})), \quad \psi'_k = \sup_{m \geq 1} \psi' (\sigma(\xi_m), \sigma(\xi_{k+m})), \quad \rho_k = \sup_{m \geq 1} \rho(\sigma(\xi_m), \sigma(\xi_{k+m})).$$

By Theorem 7.4 (a, c and d) in Bradley (2007)

$$\rho_{k+m} \leq \rho_k \rho_m$$

$$\psi_{k+m} \leq \psi_k \psi_m$$

$$1 - \psi_{k+m}' \leq (1 - \psi_k')(1 - \psi_m').$$

So, by Theorem 7.5 in Bradley (2007) we know that:

If there is $n \geq 1$ such that $\rho_n < 1$, then $\rho_n \to 0$ at least exponentially fast.

If there is $n \geq 1$ such that $\psi_n > 0$, then $\rho_n \to 0$ at least exponentially fast.

If there is $n \geq 1$ such that $\psi_n' > 0$, then $1 - \psi_n' \to 0$ at least exponentially fast.
Notice that, in terms of conditional probabilities, we also have the following equivalent definitions:

\[
\psi_1^*(\xi) = \sup_{k} \sup_{x} \sup_{A \in B(S)} Q_k(x, A)/P(A).
\]

\[
\psi_1'(\xi) = \sup_{k} \inf_{x} \inf_{A \in B(S)} Q_k(x, A)/P(A).
\]

Note that, by (1.2) we can take \(a = \psi_1'(\xi) > 0\) and \(b = \psi_1^*(\xi) < \infty\). In particular we have \(1 - \psi_1'(\xi) \leq (1 - a)^k \to 0\) exponentially fast. On the other hand condition (2.5) becomes in terms of \(\psi\)-mixing coefficients

\[
0 < \psi_1'(\xi) \text{ and } \psi_2^*(\xi) < \infty. \tag{3.3}
\]

For a Markov chain of random variables, saying that \(\psi_1 < 1\) is equivalent to \(\psi_1' > 0\) and \(\psi_1^* < 2\), which implies our condition (1.2).

Therefore in all our results we can use the language of upper and lower \(\psi\)-mixing coefficients and use instead of (1.2) or (2.5), the mixing condition (3.3). Of course, our results also hold if \(\psi_1 < 1\).

If we consider now measurable functions of a Markov chain \(X = (g(\xi_k))_{k \geq 1}\), by the definition of the mixing coefficients, we notice that \(a < \psi_1'(X)\) and \(\psi_1^*(X) < b\). Assume the variables are centered and have finite second moments. Recall that \(\tau_n^2 = \sum_{j=1}^{n} \text{var}(X_j)\) and \(\sigma_n^2 = \mathbb{E}(S_n^2)\). From Proposition 13 in Peligrad (2012) we know that for functions of Markov chains

\[
\frac{1 - \rho_1}{1 + \rho_1} \leq \frac{\sigma_n^2}{\tau_n^2} \leq \frac{1 + \rho_1}{1 - \rho_1}.
\]

By combining this inequality with Lemma 3.3 we obtain, for \(a > 0\),

\[
\frac{a}{2 - a} \leq \frac{\sigma_n^2}{\tau_n^2} \leq \frac{2 - a}{a}. \tag{3.4}
\]

\[\square\]

3.3. Preliminary general local CLT. Here we give a general local limit theorem. Its proof is based on the inversion formula for Fourier transform, which is a traditional argument for this type of behavior. Its statement is practically obtained by arguments in Section 4 in Hafouta and Kifer (2016).

**Theorem 3.4.** Assume that not all the variables have values in some fixed lattice. Assume that \(b_n \to \infty\) and

\[
S_n/b_n \Rightarrow N(0, 1). \tag{3.5}
\]

In addition, suppose that for each \(L > 0\)

\[
\lim_{T \to \infty} \limsup_{n \to \infty} \int_{T \leq |u| \leq Lb_n} \left| \mathbb{E} \exp \left( iu \frac{S_n}{b_n} \right) \right| \, du = 0. \tag{3.6}
\]

Then, for any function \(h\) on \(\mathbb{R}\) which is continuous and with compact support,

\[
\lim_{n \to \infty} \sup_{u \in \mathbb{R}} \left| \sqrt{2\pi b_n} \mathbb{E} h(S_n - u) - \exp(-u^2/2b_n^2) \int h(u) \lambda(du) \right| = 0.
\]

By decomposing the integral in (3.6) into two parts, on \(\{T \leq |u| \leq \delta b_n\}\) and on \(\{\delta b_n \leq |u| \leq Lb_n\}\), and changing the variable in the second integral we easily argue that in order to prove this theorem it is enough to show that for each \(L\) fixed there is \(0 < \delta < L\) such that

\[
(D_1) \quad \lim_{T \to \infty} \limsup_{n \to \infty} \int_{T \leq |u| \leq \delta b_n} \left| \mathbb{E} \exp \left( iu \frac{S_n}{b_n} \right) \right| \, du = 0
\]

and

\[
(D_2) \quad \lim_{n \to \infty} b_n \int_{\delta < |u| \leq L} \left| \mathbb{E} \exp(iuS_n) \right| \, du = 0.
\]
3.4. **Proof of Theorem 2.1.** We start the proof by mentioning that, by using Condition (1.1) in Peligrad (1996) and the Lindeberg’s condition (2.1), Condition C_1 can be verified under the following condition (its proof is postponed to the end of the paper in Lemma 3.8):

**Condition A.** There is δ > 0 and n_0 ∈ N such that for 1 ≤ |u| ≤ δτ_n and n > n_0

\[
\frac{\gamma}{8} \sum_{k=1}^{n} \left( 1 - |f_k(u)\tau_n|^2 \right) > g(u) \text{ and } \exp(-g(u)) \text{ is integrable on } \mathbb{R}. \tag{3.7}
\]

Furthermore, under the Lindeberg condition, Condition C_2 implies:

**Condition B.** For u ≠ 0 there is c(u), an open interval O_u containing u and a n_0 = n_0(u) such that for all t ∈ O_u, and n > n_0

\[
\frac{\gamma}{8(\ln \tau_n)} \sum_{k=1}^{n} (1 - |f_k(t)|^2) ≥ c(u) > 1. \tag{3.8}
\]

In order to see that Condition C_2 implies Condition B, we note that the Lindeberg’s condition (2.1) entails

\[
\lim_{n \to \infty} \frac{\tau_{n+1}}{\tau_n} = 1.
\]

This gives that, for any d > 1 and all n sufficiently large

\[
\frac{\tau_n}{\tau_{n_0}} = \frac{\tau_n}{\tau_{n-1}} \cdot \frac{\tau_{n-1}}{\tau_{n-2}} \cdots \frac{\tau_{n_0+1}}{\tau_{n_0}} ≤ d^{n-n_0}.
\]

Therefore,

\[
\ln \tau_n ≤ (n - n_0) \ln d + \ln \tau_{n_0} = n \ln d + o(1)
\]

and then

\[
\frac{1}{\ln \tau_n} \sum_{k=1}^{n} (1 - |f_k(t)|^2) ≥ \frac{1}{\ln d + o(1)} \left(1 - \frac{1}{n} \sum_{k=1}^{n} |f_k(t)|^2\right).
\]

So, (3.8) is satisfied if we show that for |t - u| ≤ ε, we have:

\[
\frac{1}{\ln d + o(1)} \left(1 - \frac{1}{n} \sum_{k=1}^{n} |f_k(t)|^2\right) ≥ \frac{8}{\gamma}.
\]

This is equivalent to showing that for t such that |t - u| ≤ ε and n > n_0 we have

\[
\frac{1}{n} \sum_{k=1}^{n} |f_k(t)|^2 ≤ 1 - \frac{8}{\gamma} \ln d + o(1).
\]

If we select now d > 1 close enough to 1, we see that Condition C_2 implies Condition B.

Therefore, Theorem 2.1 will immediately follow from the following proposition:

**Proposition 3.5.** Let (X_j)_{j≥1} be defined by (1.1). Assume that Conditions A, B, (1.2) and (2.1) are satisfied. Then (2.3) holds.

**Proof:** For proving this proposition we shall verify the conditions of Theorem 3.4. The first step is to obtain the CLT. With this aim, we shall apply Theorem 2.1 in Peligrad (1996). From Bradley (1997), we know that every lower ψ−mixing Markov chain (condition implied by a > 0) satisfies a mixing condition called interlaced ρ−mixing, which is precisely the mixing condition we need to apply Theorem 2.1 in Peligrad (1996). Moreover, by (3.4) and the fact that a > 0, condition \(\sigma_n^2 \to \infty\) is equivalent to \(\tau_n^2 \to \infty\). This means that the Lindeberg condition (2.1) is equivalent to

\[
\frac{1}{\sigma_n^2} \sum_{k=1}^{n} \mathbb{E}(X_k^2 I(|X_k| ≥ \varepsilon \sigma_n)) \to 0, \text{ as } n \to \infty.
\]
Furthermore, also from (3.4), we deduce that

\[ \frac{1}{\sigma_n^2} \sum_{k=1}^{n} \mathbb{E}(X_k^2) \leq \frac{2 - a}{a} \]

and therefore, all the conditions in Theorem 2.1 Peligrad (1996) are satisfied and we obtain for this case that

\[ \frac{S_n}{\sigma_n} \Rightarrow N(0,1) \]  

An alternative way to prove the CLT is to use (3.4) and then Theorem 6.48 from Merlevède et al. (2019) in the Markov setting.

According to the discussion after the statement of Theorem 3.4, it remains to verify conditions \((D_1)\) and \((D_2)\). We begin by changing the variable in \((D_1)\) and, using (3.4) and the fact that \(a > 0\), we obtain that \((D_1)\) is equivalent to

\[
\lim_{T \to \infty} \lim_{n \to \infty} \sup_{T \leq |u| \leq \tau_n} \int_{T \leq |u| \leq \delta T} \left| \mathbb{E}\exp(iuS_n/\tau_n) \right| du = 0.
\]

By Proposition 3.1 combined with Condition A, for any \(1 \leq |u| < \delta \tau_n\),

\[
\left| \mathbb{E}\exp(iuS_n/\tau_n) \right| \leq \prod_{k=1}^{n} \left[ 1 - \frac{\gamma}{2} \left( 1 - |f_k(u/\tau_n)|^2 \right) \right]^{\frac{1}{2}} \leq \exp \left( -\frac{\gamma}{4} \sum_{k=1}^{n} \left( 1 - |f_k(u/\tau_n)|^2 \right) \right) \leq \exp(-g(u)).
\]

Integrating both sides of this inequality on the intervals \(T \leq |u| \leq \delta \tau_n\) we obtain

\[
\int_{T \leq |u| \leq \delta \tau_n} \left| \mathbb{E}\exp(iuS_n/\tau_n) \right| du \leq \int_{T \leq |u| \leq \delta \tau_n} \exp(-g(u)) du \leq \int_{|u| > T} \exp(-g(u)) du.
\]

Whence, taking first \(\limsup_n\) and then \(T \to \infty\), condition \((D_1)\) is verified.

We move now to verify \((D_2)\). Because the interval \([\delta, L]\) is compact, \((D_2)\) is verified if we can show that for any \(|u|\) fixed in \([\delta, L]\) we can find an open interval \(O_u\) such that

\[
\sigma_n \sup_{|t| \in O_u} \left| \mathbb{E}\exp(itS_n) \right| \to 0 \text{ as } n \to \infty.
\]

By using (3.4), it is enough to show that

\[
\tau_n \sup_{|t| \in O_u} \left| \mathbb{E}\exp(itS_n) \right| \to 0 \text{ as } n \to \infty. \quad (3.9)
\]

By Proposition 3.1, for any \(t\),

\[
\tau_n \left| \mathbb{E}\exp(itS_n) \right| \leq \tau_n \prod_{k=1}^{n} \left[ 1 - \frac{\gamma}{2} (1 - |f_k(t)|^2) \right]^{1/4} \leq \tau_n \exp \left( -\frac{a^4}{8b} \sum_{k=1}^{n} (1 - |f_k(t)|^2) \right) \leq \exp \left( \ln \tau_n - \frac{\gamma}{8} \sum_{k=1}^{n} (1 - |f_k(t)|^2) \right).
\]
Now (3.9) is satisfied, provided that
\[
\ln \tau_n \left( 1 - \inf_{|u| \in O_u} \frac{1}{\ln \tau_n} \sum_{k=1}^{\infty} \gamma \left( 1 - \|f_k(t)\|^2 \right) \right) \to -\infty.
\]
Since \( \tau_n \to \infty \), we obtain in this case that \( (D_2) \) follows from Condition B.

We would like to mention that Condition B is satisfied under condition (1.3) of Mineka and Silverman (1970) (which is an adaptation of a condition due to Rozanov, 1957): For \( u \neq 0 \) there is an \( \varepsilon = \varepsilon(u) > 0 \), for which
\[
\frac{1}{\ln \tau_n} \sum_{j=1}^{n} \mathbb{P}(X_j - a_j \in A(u, \varepsilon)) \to \infty,
\]
where \( a_i \) is a bounded sequence of constants satisfying \( \inf_{1 \leq j \leq \infty} \mathbb{P}(|X_j - a_j| < \delta) > 0 \) for every \( \delta > 0 \) and \( A(u, \varepsilon) = \{ x : |x| < M, |xu - \pi m| \geq \varepsilon \} \), for each integer \( m \) with \( |m| \leq M \), where \( M > 0 \) is fixed, large enough such that \( \inf_{1 \leq j \leq \infty} \mathbb{P}(|X_j| < M) > 0 \) (the existence for such an \( M \) is a part of the assumption).

The fact that condition (3.10) implies Condition B was proven by Mineka and Silverman (1970). Under condition (3.10), Mineka and Silverman (1970), on the top of page 595, showed that for each \( u \) there is a positive constant \( K_u \) independent on \( k \) such that for all \( t \) such that \( |t - u| < \varepsilon/4M \), and for all \( k \in \mathbb{N} \) we have
\[
|f_k(t)|^2 - 1 \leq -\frac{1}{4} K_u \varepsilon^2 \mathbb{P}(X_k \in A(u, \varepsilon)).
\]

Also, from Corollary 1 in Mineka and Silverman (1970), (3.10) can be replaced by the stronger condition: the variables \( X_k \)’s have uniformly bounded densities, or by Corollary 2 in the same paper, (3.10) is satisfied if there are three rationally independent numbers \( d_1, d_2, d_3 \) such that \( \inf_{1 \leq k \leq \infty} P(|X_k - d_k| < \delta) > 0 \) for \( j = 1, 2, 3 \). Therefore we can make the following remark:

**Remark 3.6.** Theorem 2.1 also hold with Condition C2 replaced by condition (3.10).

### 3.5. Proof of Corollary 2.4

First of all we notice that, for any array \( \mathbf{X}_n = (X_{n,k})_k \) defined in this corollary, the mixing coefficients satisfy \( a < \psi'(\mathbf{X}_n) \) and \( \psi^*(\mathbf{X}_n) < b \). According to Theorem 2.1, it is enough to verify Lindeberg’s condition in (2.1) as well as conditions (2.4) and C2.

Note that \( \tau_n^2 = \sum_{k=1}^{n} a_{n,k}^2 \mathbb{E}(X_0^2) \to \infty \) as \( n \to \infty \). Hence, by stationarity, Lindeberg’s condition becomes: for any \( \varepsilon > 0 \),
\[
\frac{1}{\tau_n^2} \sum_{k=1}^{n} a_{n,k}^2 \mathbb{E}(X_0^2 I(|X_0| \geq \varepsilon \tau_n)) = \frac{\mathbb{E}(X_0^2 I(|X_0| \geq \varepsilon \tau_n))}{\mathbb{E}(X_0^2)} \to 0 \text{ as } n \to \infty,
\]

On the other hand (2.4) becomes: there is \( \delta > 0 \) such that
\[
\frac{\mathbb{E}(X_0^2 I(a_{n,k} X_0 > \delta))}{\mathbb{E}(X_0^2)} \leq \frac{\mathbb{E}(X_0^2 I(|X_0| > \delta/M))}{\mathbb{E}(X_0^2)} < c \text{ for all } k,
\]
which is obviously satisfied for \( \delta \) large enough.

It remains to verify Condition C2. Fix \( u \neq 0 \), we have to find an open interval \( O_u \) containing \( |u| \) and a constant \( c(u) \) such that for any \( |t| \in U \) we have
\[
|\mathbb{E} \exp(it a_{n,k} X_0)|^2 = |f_0(a_{n,k} t)|^2 \leq c(u) < 1.
\]
As a matter of fact, if \( 0 < c < |u| < d \), then for any \( t \) satisfying \( 0 < c < |t| < d \), by the boundness of \( (a_{n,k}) \), we also have \( 0 < mc < |a_{n,k} t| < Md \). Now, since the distribution of \( \xi_0 \) is nonlattice, for any \( v \) such that \( 0 < mc \leq |v| \leq Md \) and because \( f_0 \) is continuous on the compact set \([-Md, -mc] \cup [mc, Md] \) we can find some constant \( C(c,d) \) such that
\[ |f_0(v)| \leq C(c,d) < 1. \]

3.6. **Proof of Corollary 2.6.** By Theorem 5 in Peligrad and Utev (2006), we know that

\[ \frac{1}{v_n} S_n \Rightarrow AN(0,1) \text{ as } n \to \infty, \]

We also have

\[ \frac{E(S_n^2)}{v_n^2} \to A^2 \text{ as } n \to \infty, \]

whence, by (3.4), we can find two constants \( c_1 > 0 \) and \( c_2 > 0 \) such that \( c_1 n \leq E(S_n^2) \leq c_2 n \).

Recall that \( A_i = a_1 + \cdots + a_i \) and write

\[ S_n = \sum_{i \geq 2} b_{n,i} X_i, \]

where we used the notation \( b_{n,i} = A_{i-1} \) for \( 2 \leq i \leq n \) and \( b_{n,i} = a_{i-n} + \cdots + a_{i-1} = A_{i-1} - A_{i-n-1} \) for \( i \geq n+1 \).

Let \( K_n \) be a positive integer such that \( K_n \geq n \) and \( n^{3/2} \sum_{\ell \geq K_n} |a_\ell| \to 0 \), as \( n \to \infty \). Let

\[ \tilde{S}_n = \sum_{i=2}^{n+K_n} b_{n,i} X_i. \]

For any \( t \in \mathbb{R} \),

\[ |E(\exp(itS_n)) - E(\exp(it\tilde{S}_n))| \leq 2|t|E(|S_n - \tilde{S}_n|) \]

\[ \leq 2|t|E(|X_0|) \sum_{i \geq n+K_n} |b_{n,i}| \leq 2n|t|E(|X_0|) \sum_{\ell \geq K_n} |a_\ell|. \]

Hence, for each \( L > 0 \) and any sequence \( (b_n) \),

\[ \lim_{T \to \infty} \limsup_{n \to \infty} \int_{|u| \leq L} \left| \mathbb{E} \exp \left( \frac{iu}{b_n} S_n \right) \right| \, du \]

\[ = \lim_{T \to \infty} \limsup_{n \to \infty} \int_{|u| \leq L_n} \left| \mathbb{E} \exp \left( \frac{iu}{b_n} \tilde{S}_n \right) \right| \, du. \]

Applying now Proposition 3.1 to \( \tilde{S}_n = \sum_{i=2}^{n+K_n} b_{n,i} X_i \), it follows

\[ |E(\exp(it\tilde{S}_n))| \leq \prod_{j=1}^{n+K_n} \left[ 1 - \frac{\gamma}{2}(1 - |f(b_{n,j} u)|^2) \right] \]

\[ \leq \prod_{j=1}^{n-1} \left[ 1 - \frac{\gamma}{2}(1 - |f(A_j u)|^2) \right] \leq \exp \left[ -\frac{\gamma}{2} \sum_{j=1}^{n-1} (1 - |f(A_j u)|^2) \right]. \]

From now on we can proceed exactly as in the proof of Corollary 2.4. Indeed, the proof is reduced to verify condition (2.1) and to establish Conditions C_1 and C_2 via the observation that \( m < |A_k| < A \) for all \( k \geq 1 \). \( \square \)

3.7. **Proof of Corollary 2.7.** Its proof is based on the next proposition whose proof is similar to that of Proposition 3.5 and is left to the reader.

In the next proposition \( (X_k)_{k \in \mathbb{Z}} \) is as in Theorem 2.1, with the exception that we do not assume that \( X_k \) has finite second moment. For this case we have:

**Proposition 3.7.** Assume that there is a sequence of constants \( b_n \to \infty \) such that

\[ \frac{S_n}{b_n} \Rightarrow N(0,1). \]

\[ (3.11) \]
Assume that Conditions A and B are satisfied with \( \tau_n \) replaced by \( b_n \) and that condition (1.2) holds. Then, for any function \( h \) on \( \mathbb{R} \) which is continuous and with compact support,

\[
\lim_{n \to \infty} \sup_{u \in \mathbb{R}} \left| \sqrt{2\pi b_n} \mathbb{E} h(S_n - u) - \exp(-u^2/2b_n^2) \int h(u) \lambda(du) \right| = 0. \tag{3.12}
\]

We should notice that Maller (1978), on the pages 106-107, verified Condition A (with \( \tau_n \) replaced by \( b_n \)) under the assumptions: for every \( n > n_0 \) and \( x > \delta \) we have

\[
\frac{x^2 \sum_{k=1}^{n} \mathbb{P}(|X_k| > x)}{V_n^2(x)} \leq c.
\]

In order to prove Corollary 2.7, we shall verify the conditions in Proposition 3.7. First of all, by Lemma 3.3, we notice that we can apply Theorem 1 in Bradley (1988). Alternatively, one can also use Theorem 2.1 in Peligrad (1990). It follows that we can find a sequence of positive constants \( b_n \to \infty \), such that

\[
\frac{S_n}{b_n} \Rightarrow N(0,1).
\]

It is well known that saying that \( H(x) \) is a slowly varying function as \( x \to \infty \) is equivalent to

\[
\lim_{x \to \infty} \frac{x^2 \mathbb{P}(|X| > x)}{H(x)} = 0. \tag{3.14}
\]

Also clearly, since the variables have mean 0, \( \lim_{x \to \infty} \mathbb{E}(X_0 I(|X_0| < x) = 0 \), hence Condition \( \tilde{A}_1 \) is satisfied. Obviously condition (3.13) is also satisfied and these two properties are precisely what Maller (1978), on pages 107-108, used to show that Condition A is satisfied, with \( \tau_n \) replaced by \( b_n \).

Now by Theorem 18.1.1 in Ibragimov and Linnik (1971), \( b_n = n^{1/2} h(n) \), where \( h(n) \) as slowly varying at infinity. So

\[
\lim_{n \to \infty} \frac{b_n}{b_{n-1}} = 1. \tag{3.15}
\]

By the same type of arguments used for showing that Condition C2 implies condition B, starting from (3.15) we show that Condition B is satisfied with \( \tau_n \) replaced by \( b_n \). The proof of this corollary is now complete. \( \Box \)

3.8. On the relation between Conditions C1 and A.

**Lemma 3.8.** Let \((X_j)_{j \geq 1}\) satisfying (3.11) and (3.13). Then Condition C1 implies Condition A.

**Proof:** It is enough to show that Condition C1 implies Condition (1.2) in Maller (1978) and then apply his proof on pages 107-108. This condition makes use of the symmetrization method. We shall use the notations: \( \hat{X}_k = X_k - X_k^* \) with \((X_k^*)\) an independent copy of \((X_k)\). We have to verify there are constants \( c, n_0 \in \mathbb{N} \) and \( \delta > 0 \) such that for all \( n > n_0 \) and \( x > \delta \) we have

\[
\frac{x^2 \sum_{k=1}^{n} \mathbb{P}(|\hat{X}_k| > x)}{\sum_{k=1}^{n} \mathbb{E}(\hat{X}_k^2 I(|\hat{X}_k| \leq x))} \leq c.
\]
By the Markov inequality the expression in the left hand side is dominated by
\[
\sum_{k=1}^n \frac{\mathbb{E}(X_k^2 I(|X_k| > x))}{2\tau_n^2 - \sum_{k=1}^n \mathbb{E}(X_k^2 I(|X_k| > x))}.
\]
Now, by a desymmetrization argument and monotonicity this quantity is smaller than
\[
\frac{8\sum_{k=1}^n \mathbb{E}(X_k^2 I(|X_k| > x/2))}{2\tau_n^2 - 8\sum_{k=1}^n \mathbb{E}(X_k^2 I(|X_k| > x/2))},
\]
which is uniformly bounded under Condition C1.

3.9. **Triangular arrays. A second look.** In our Remark 2.3 we have already mentioned an extension to a triangular array \((\xi_{n,i})_{1 \leq i \leq n}\) of Markov chains and \(X_{n,i} = g_{n,i}(\xi_{n,i})\). Now we discuss the situation when the mixing coefficients are different from line to line, i.e., for \(a_n > 0\) and \(b_n < \infty\)
\[
a_n P_{n,k}(A) \leq Q_{n,k}(x,A) \leq b_n P_{n,k}(A),
\]
where \(P_{n,k}(A) = \mathbb{P}(\xi_{n,k} \in A)\) and \(Q_{n,k}(x,A) = \mathbb{P}(\xi_{n,k+1} \in A|\xi_{n,k} = x)\). A natural problem is to ask if we can allow \(a_n \to 0\). This question is motivated by a remarkable result concerning the central limit theorem for triangular arrays of Markov chains, which is due to Dobrušin (1956a,b) and further developed in several papers including Gudinas (1977) and Peligrad (2012). Actually, the mixing coefficient needed for a CLT is more general, larger than \(a_n\) in (3.16). Practically, a CLT holds under the condition:
\[
\frac{1}{a_n \tau_n} \sum_{k=1}^n \mathbb{E}(X_{n,k}^2 I(|X_{n,k}| \geq \varepsilon a_n \tau_n)) \to 0 \text{ as } n \to \infty.
\]

By using the proof of Proposition 3.5, we can give the following technical sufficient conditions for the local limit theorem with mixing coefficients which are not uniformly bounded.

**Theorem 3.9.** Assume that \((\xi_{n,i})_{1 \leq i \leq n}\) is a triangular array of Markov chains and \(X_{n,i} = g_{n,i}(\xi_{n,i})\), where \(\mathbb{E}(X_{n,i}) = 0\), \(\mathbb{E}(X_{n,i}^2) < \infty\) and condition (3.17) is satisfied. Assume \(a_n \tau_n^2 \to \infty\) and there is \(\delta > 0\) and \(n_0 \in \mathbb{N}\) such that for \(1 \leq |u| \leq \delta \tau_n\) and \(n > n_0\)
\[
\frac{a_n^n}{8b_n} \sum_{k=1}^n \left(1 - \left| f_{n,k}(\frac{u}{\tau_n}) \right|^2 \right) > g(u) \text{ and } \exp(-g(u)) \text{ is integrable on } \mathbb{R}.
\]
Also assume that for \(u \neq 0\) there is \(c(u)\), an open interval \(O_u\) containing \(u\) and a \(n_0 = n_0(u)\) such that for all \(t \in O_u\), and \(n > n_0\)
\[
\frac{a_n^n}{8(\ln \tau_n) b_n} \sum_{k=1}^n \left(1 - \left| f_{n,k}(t) \right|^2 \right) \geq c(u) > 1.
\]
Then (2.3) holds.

In particular, this theorem can be applied to row-wise stationary triangular arrays. They are useful to study the local stationary Markov chains as defined, for instance, in Truquet (2019).

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This paper was developed concomitantly and independently of a new research monograph by Dolgopyat and Sarig (2020), which treats the local limit theorem for a different nonstationary situation. There are many differences between our paper and this monograph. For instance there are differences with respect to the mixing conditions. They used a condition of type (2.5) but with reverse inequalities. Nevertheless, in both papers the mixing conditions imply \(\psi^-\)mixing. We treat instantaneous functions of a Markov chain, while Dolgopyat and Sarig look at functions of two
consecutive random variables. However, the main difference is that Dolgopyat and Sarig (2020) deal with bounded random variables and we used finite (or even infinite) second moment conditions.

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