NUMERICAL SIMULATIONS OF OPTICALLY THICK ACCRETION ONTO A BLACK HOLE. I. SPHERICAL CASE

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ABSTRACT

Modeling the radiation generated by accreting matter is an important step toward realistic simulations of black hole accretion disks, especially at high accretion rates. To this end, we have recently added radiation transport to the existing general relativistic magnetohydrodynamic code, Cosmos++. However, before attempting to model radiative accretion disks, we have tested the new code using a series of shock tube and Bondi (spherical inflow) problems. The four radiative shock tube tests, first presented by Farris et al., have known analytic solutions, allowing us to calculate errors and convergence rates for our code. The Bondi problem only has an analytic solution when radiative processes are ignored, but it is pertinent because it is closer to the physics we ultimately want to study. In our simulations, we include Thomson scattering and thermal bremsstrahlung in the opacity, focusing exclusively on the super-Eddington regime. Unlike accretion onto bodies with solid surfaces, super-Eddington accretion onto black holes does not produce super-Eddington luminosity. In our examples, despite accreting at up to 300 times the Eddington rate, our measured luminosity is always several orders of magnitude below Eddington.

Key words: accretion, accretion disks – black hole physics – magnetohydrodynamics (MHD) – methods: numerical – radiative transfer

Online-only material: color figures

1. INTRODUCTION

After more than a decade of successes in the area of general relativistic magnetohydrodynamic (GRMHD) numerical simulations of black hole accretion flows (see Abramowicz & Fragile 2011, for a review), there is now considerable understanding of accretion in this context. However, one context in which our understanding is still quite limited is the inner parts of luminous accretion flows. Here radiation pressure is expected to dominate over gas pressure in supporting the flow against the gravitational field of the black hole. Because of photon diffusion, such radiation-pressure-dominated regions can be even more fragile to the development of inhomogeneous density structures than gas-pressure-dominated ones, and because of the proximity to the black hole, relativistic effects are of utmost importance. For these reasons, numerical study of this and similar problems demands the development of general relativistic (GR) radiation MHD codes.

Although radiation hydrodynamics codes have been around for more than four decades (e.g., Christy 1966; Colgate & White 1966; Cox et al. 1966), very few multidimensional, fully (general) relativistic treatments exist even today. A few noteworthy examples closely related to our work were presented by De Villiers (2008), Farris et al. (2008), and Zanotti et al. (2011). Parallel progress has also been made in developing radiation hydrodynamics codes to solve the problem of core-collapse supernovae (Müller et al. 2010; Shibata et al. 2011; Lentz et al. 2012). There the radiation is in the form of neutrinos, but the processes (and code challenges) are very similar. The paucity of codes can be understood when one realizes that most radiation schemes become quite difficult to implement in multidimensions, given the large number of phase-space degrees of freedom that need to be tracked for the radiation field.

The sheer computational demand of multidimensional radiation MHD has, until recently, been beyond the reach of even the largest scientific computers. The potential for discovery from such simulations, though, is significant. The addition of radiative phenomena into GR fluid dynamics simulations greatly expands the possible parameter space that can be explored, with interesting phenomena such as radiation-pressure-dominated slim disks (Abramowicz et al. 1988), secular instability (Lightman & Eardley 1974), photon bubbles (Begelman 2001), and radiation-driven outflows, all topics that could potentially be investigated. Therefore, in this paper, we take the first, simplest step, considering spherical accretion onto a non-rotating black hole. This case has been considered many times previously (Shapiro 1973; Schmid-Burbk 1978; Meier 1979; Soffel 1982; Vitello 1984; Zampieri et al. 1996), but never, to our knowledge, with an explicit, multidimensional, Eulerian, GR radiation MHD code such as the one implemented here. For this reason, we feel it is worthwhile for us to present these results.

Although our implementation of GR radiation MHD is not unique—in fact, it is very similar to at least two previous implementations described in the literature (Farris et al. 2008; Zanotti et al. 2011)—we, nevertheless, begin our paper in Section 2 with a detailed discussion of our method. In Section 3, we report on a series of one-dimensional shock tube tests meant to validate our code. In Section 4, we arrive at the main results of this paper—one-dimensional spherical accretion onto a black hole including radiation. We conclude in Section 5. Most of the equations in this work are written in units where \( GM = c = 1 \), although in a few places we leave in factors of \( c \) for clarity.

2. NUMERICAL METHOD

2.1. GRMHD

We begin with a review of GRMHD before discussing the addition of radiation. This will make it easier for us to point out...
the continuity equation
\[ \rho u^\alpha,\beta = 0, \]  
and the homogenous Maxwell’s equation
\[ * F^{\alpha\beta},\beta = 0. \]  
In the MHD limit, the stress–energy tensor can be expressed as
\[ T^{\alpha\beta} = (\rho + 2 P_{\text{mag}})u^\alpha u^\beta + (P_{\text{gas}} + P_{\text{mag}})g^{\alpha\beta} - b^\alpha b^\beta, \]  
where \( \rho \) is the rest-mass density, \( h = 1 + \epsilon + P_{\text{gas}}/\rho \) is the specific enthalpy, \( \epsilon \) is the specific internal energy density, \( P_{\text{gas}} \) is the gas pressure, \( P_{\text{mag}} \) is the magnetic pressure, \( u^\alpha = g^{\alpha\gamma}u_\gamma \) is the fluid four-velocity, \( g_{\gamma\alpha} \) is the four-metric, \( g \) is the four-metric determinant, \( F^{\alpha\beta} \) is the Faraday tensor, and \(* F^{\alpha\beta} \equiv \epsilon^{\alpha\gamma\beta}\gamma_{\gamma\beta}/2 \) is its dual. For this work we use a \( \Gamma \)-law equation of state,
\[ P = (\Gamma - 1)\rho \epsilon, \]  
where \( \Gamma \) (without subscripts or superscripts) is the adiabatic index.

Expanding the MHD equations and reorganizing in terms of new variables, we arrive at the following set of coupled equations:
\[ \partial_t D + \partial_j (DV^j) = 0, \]  
\[ \partial_t \mathcal{E} + \partial_j \left( -\sqrt{-g} T^0_j \right) = -\sqrt{-g} T^0_\beta \Gamma^\beta_{0\alpha}, \]  
\[ \partial_t S_j + \partial_j \left( \sqrt{-g} T^j_\beta \right) = \sqrt{-g} T^j_\beta \Gamma^\beta_{j\alpha}, \]  
\[ \partial_t B^j + \partial_j (B^i V^i - B^0 V^j) = 0, \]  
where \( D = W\rho \) is the generalized fluid density, \( W = \sqrt{-g} u^0 = \sqrt{-g}/\alpha, \) \( \gamma = 1/\sqrt{1 - \gamma}, \) \( \alpha = 1/\sqrt{-g}_{\text{rel}}, \) \( v^2 \equiv v_\gamma v^\gamma, \) \( v^\gamma \) is the flow velocity relative to the normal observer, \( V^j = u^j/u^0 \) is the transport velocity, \( \mathcal{E} = -\sqrt{-g} T^0_0 \) is the total energy density, and \( S_j = \sqrt{-g} T^j_0 \) is the covariant momentum density. With indices, \( \Gamma \) indicates the geometric connection coefficients of the metric. Along with the evolution Equations (6)–(9), the time component of the Maxwell equation enforces the divergence-free constraint
\[ \partial_j B^j = 0. \]

There are multiple representations of the magnetic field in our equations, which we should explain: \( b^\alpha \) is the magnetic field measured by an observer comoving with the fluid, which can be defined in terms of the dual of the Faraday tensor \( b^\alpha \equiv u_\beta F^{\alpha\beta} \), and \( B^j = \sqrt{-g} B^j \) is the boosted magnetic field three-vector. The magnetic field \( B^i = * F^{i\alpha} \) is related to the comoving field by
\[ B^i = u^0 b^i - u^i b^0. \]
We also need the magnetic pressure, which is defined as \( P_{\text{mag}} = B^2/2 = b^\alpha b^\alpha/2 \). Note that unlike previous versions of \( \text{Cosmos}++ \), here we have absorbed the factor of \( \sqrt{4\pi} \) into the definition of the magnetic fields.

### 2.2. HRSC

The current work uses a high-resolution shock-capturing (HRSC) scheme to solve the GRMHD Equations (6)–(9). This method is new to \( \text{Cosmos}++ \), although it shares many elements with our earlier non-oscillatory central difference method (Anninos & Fragile 2003). We begin by noting that the MHD equations are all in the form of a conservation equation
\[ \partial_t U(P) + \partial_j F_j(P) = S(P), \]  
where
\[ U(P) = \begin{pmatrix} D \\ \mathcal{E} \\ S_j \end{pmatrix}, \quad F_j(P) = \begin{pmatrix} DV^j \\ -\sqrt{-g} T^0_j \\ \sqrt{-g} T^j_0 \end{pmatrix}, \]  
and \( S(P) = \begin{pmatrix} 0 \\ -\sqrt{-g} T^0_j \Gamma^\beta_{j\alpha} \\ \sqrt{-g} T^j_0 \Gamma^\beta_{j\alpha} \end{pmatrix} \)
are the arrays representing the conserved quantities, fluxes, and source terms, respectively. By integrating both sides of Equation (11) with respect to volume and applying Gauss’s theorem, we can rewrite the conservation equation in the form
\[ \int_V \partial_t U dV = \int_S F^j dA_j + \int_V S dV, \]  
where we have dropped the explicit dependence on the primitive variables. We can then discretize this equation using a finite-volume representation as
\[ U^{n+1} = U^n - \frac{\Delta t}{V} \sum_{\text{faces}} (F^j A_j) + \Delta t S. \]

This approach requires at least a 2nd order time integration scheme for stability. The \( \text{Cosmos}++ \) code has a number of time integration options, including 2nd order Euler, 2nd order Runge–Kutta, 2nd order Crank–Nicholson, and 3rd order Euler. The present work uses the 2nd order Runge–Kutta scheme (which is also sometimes referred to as the “midpoint” or “leapfrog” method). First, a half-time step, \( \Delta t/2 \), is taken to project the conserved variables \( U^n \) forward to \( n + 1/2 \). From these, a new set of primitives \( P^{n+1/2} \) can be computed. These intermediate primitives are then used in calculating the \( F^j \) and \( S \) needed in Equation (14).

The \( F^j \) are determined using an approximate Riemann solver. We have options for either the Harten-Lax-van Leer (HLL) or Lax–Friedrichs method. The HLL scheme reconstructs the fluxes as
\[ F = c_{\text{min}} F_R + c_{\text{max}} F_L - c_{\text{max}} c_{\text{min}} (U_R - U_L), \]  
where
\[ c_{\text{min}} = \min_{\text{faces}} F_R, \quad c_{\text{max}} = \max_{\text{faces}} F_R, \quad c_{\text{max}} c_{\text{min}} = \max_{\text{faces}} (U_R - U_L). \]  
A slope-limited linear or parabolic extrapolation gives \( P_R \) and \( P_L \), the primitive variables at the right- and left-hand sides of each zone interface. From \( P_R \) and \( P_L \), we calculate the right- and left-hand conserved quantities \( (U_R + U_L) \), the fluxes \( F_R = (F_R - F_L) + (F_L - F_R) \), and the maximum right- and left-going wave speeds, \( c_{\pm,R} \) and \( c_{\pm,L} \). The bounding wave speeds are then
where, for example, $(\delta^t)i,j−1/2,j−1/2$ is the $x_1$-component of the electric field (or emf) $\delta^t = −\epsilon_{ijk}V^{j}B^{k}$ centered on the appropriate cell edge. The best method we have found so far for constructing the edge-centered electric fields is to simply average the surrounding face-centered fluxes recovered from the Riemann solver. For example,

$$
\frac{3}{4}((\delta^t)i,j−1/2,j,k + (\delta^t)i,j−1/2,j−1,k + (\delta^t)i,j−1/2,j+k + (\delta^t)i,j−1/2,j−1/2).
$$

(20)

This procedure preserves the following mathematical representation of the divergence to round-off error in each zone:

$$
\partial_{j}B^{i} = \frac{1}{V}[
(B^{i}A^{1})_{i,j+1/2,j,k} - (B^{i}A^{1})_{i,j−1/2,j,k} + (B^{i}A^{2})_{i,j+1/2,k} - (B^{i}A^{2})_{i,j−1/2,k} + (B^{i}A^{3})_{i,j+1/2,k} - (B^{i}A^{3})_{i,j−1/2,k}].
$$

(21)

In this scheme, we maintain staggered forms of both the primitive and conserved magnetic fields, which are related by the metric determinant at their respective faces, e.g., $B^{1} = (\sqrt{−h})_{−1/2,j,k}B^{1}$. The staggered primitive field is used to overwrite the appropriate component of the extrapolated primitive field used in the flux reconstruction at each face. They are also used when we require cell-centered values of the primitive magnetic fields, such as for calculating the magnetic pressure. In this case we use the volume-averaged fields

$$
\frac{1}{2}[(B^{1})_{i,j−1/2,j,k} + (B^{1})_{i,j+1/2,j,k}]
$$

(22)

$$
\frac{1}{2}[(B^{2})_{i,j−1/2,j,k} + (B^{2})_{i,j+1/2,j,k}]
$$

(23)

$$
\frac{1}{2}[(B^{3})_{i,j−1/2,j,k} + (B^{3})_{i,j+1/2,j,k}].
$$

(24)

2.4. Radiation

We now describe the addition of the radiation field. Similar to the fluid and magnetic field, the energy and momentum of the radiation field are represented by a stress–energy tensor

$$
R^{\alpha\beta} = \int I_{\nu,n}\alpha n^{\beta}d\nu d\Omega,
$$

(25)

where $\nu$ is the photon frequency, $I_{\nu} = I(\alpha^{\mu}; n^{\nu}, \nu)$ is the specific intensity of radiation at position $x^{\mu}$ moving in the direction $n^{\nu}$, $h_{\nu}$ is the Planck's constant, and $d\Omega$ is the differential solid angle around the direction of propagation. The quantities $\nu$, $I_{\nu}$, and $d\Omega$ are measured in the local Lorentz frame of an observer with four-velocity $u^{\mu}_{\text{local}}$. 
GR radiation MHD, then, starts from the same conservation of stress–energy tensor as GRMHD, but now split into MHD and radiation components:

\[(T^\alpha{}^\beta + R^\alpha{}^\beta)_{,\beta} = 0.\]  

(26)

It is more convenient for our purposes to rewrite Equation (26) in two parts:

\[(T^\alpha{}^\beta)_{,\beta} = G^\alpha{}\]

(27)

and

\[(R^\alpha{}^\beta)_{,\beta} = -G^\alpha{},\]

(28)

where \(G^\alpha{}\) is the radiation four-force density coupling the fluid and radiation field.

### 2.4.1. Radiation Moments

Similar to fluid dynamics, we can proceed by considering various moments of the radiation equations. Starting with the zeroth radiation moment,

\[E = \int I_\nu n^\nu dvd\Omega\]

(29)

is the comoving radiation energy density,

\[F^i = \int I_\nu n^\nu n^i dvd\Omega\]

(30)

is the comoving radiation flux (three first radiation moments), and

\[\mathcal{P}^{ij} = \int I_\nu n^\nu n^i n^j dvd\Omega\]

(31)

is the (symmetric) comoving radiation pressure tensor (six second radiation moments). In the comoving frame, the radiation stress tensor is then

\[R^\alpha{}^\beta = \begin{pmatrix} E & F^1 & F^2 & F^3 \\ F^1 & p_{11} & p_{12} & p_{13} \\ F^2 & p_{21} & p_{22} & p_{23} \\ F^3 & p_{31} & p_{32} & p_{33} \end{pmatrix}\]

(32)

In our current implementation, we assume that the radiation pressure, \(P_{\text{rad}}\), is isotropic, such that \(p^{ij} = \delta^{ij} P_{\text{rad}} = \delta^{ij} E/3\). This is equivalent to keeping the first two radiative moment equations and adopting an Eddington factor of 1/3 to close the set. Although the radiation pressure is assumed to be isotropic, we emphasize that by allowing a small, nonzero radiation flux \((F^\alpha \ll E)\), we do allow for some degree of anisotropy in the radiation field. In covariant form, \(R^\alpha{}^\beta\) can now be written as

\[R^\alpha{}^\beta = E u^\alpha{} u^\beta + F^\alpha{} u^\beta + F^\beta{} u^\alpha + P_{\text{rad}} h^{\alpha{}^\beta},\]

(33)

where we have introduced the tensor \(h^{\alpha{}^\beta} = g^{\alpha{}^\beta} + u^\alpha{} u^\beta\), which projects any other tensor into the space orthogonal to \(u^\alpha\), such that \(h^{\alpha{}^\beta} u_\alpha = 0\) and the radiation flux four-vector

\[F^\alpha = h^\alpha{}_\beta \int I_\nu n^\beta dvd\Omega.\]

(34)

With this definition, the flux satisfies \(F^\alpha u_\alpha = 0\).

### 2.4.2. Radiation Four-force Density

We return now to consider the form of the radiation four-force density from Equations (27) and (28). In the comoving frame

\[G^\delta = \int (\chi_\nu I_\nu - \eta_\nu) n^\delta dvd\Omega,\]

(35)

where \(\chi_\nu = \chi_\nu^\ast + \chi_\nu^s\) is the total opacity (“\(\ast\)” and “\(s\)” stand for absorption and scattering, respectively) and \(\eta_\nu = \eta_\nu^\ast + \eta_\nu^s\) is the total emissivity. In terms of the usual cooling function \(\Lambda = \int \eta_\nu dvd\Omega\) and assuming a mean (frequency-independent) opacity of the form \(\chi = \rho \kappa\), we can write in the comoving frame

\[G^\delta = \int (\chi_\nu I_\nu - \eta_\nu) n^\delta dvd\Omega = \rho \kappa E - \Lambda\]

(36)

and

\[F^\delta = \int (\chi_\nu I_\nu - \eta_\nu) n^\delta dvd\Omega = \rho \kappa F^\delta = \rho (\kappa^\ast + \kappa^s) F^\delta.\]

(37)

Equation (37) assumes that photons are emitted isotropically in the comoving frame, so that the net momentum they remove from the gas is zero.

Noting that \(u^\delta = (1, 0, 0, 0)\), then, from the normalization of the radiation flux four-vector \(F^\alpha u_\alpha = 0\), we have \(F^\delta = (0, F^\delta)\). Thus, in the comoving frame

\[G^\delta = (\rho \kappa E - \Lambda) u^\delta + \rho \kappa F^\delta.\]

(38)

Since this expression is covariant, it must hold in any frame; we, therefore, drop the “in all subsequent references to \(G^\alpha\)."

For equilibrium blackbody radiation, \(\Lambda = \rho \kappa^\ast a_R T_\text{gas}^4\), where \(T_\text{gas} = m P_{\text{gas}}/k_B \rho\) is the ideal gas temperature of the fluid, \(a_R = 8\pi^2 k_B^4 / (15h_\text{p}^4 c^3)\) is the radiation constant, \(k_B\) is Boltzmann’s constant, and \(m = m_{\text{H}} + m_{\text{He}}\) is the mean mass of ions in the gas. If the radiation and gas are in local thermodynamic equilibrium (LTE), then \(E = a_R T_\text{gas}^4\) and the first two terms of Equation (38) drop out, though we emphasize that our scheme does not require this.

### 2.4.3. GR Radiation MHD

Again expanding and reorganizing the conservation of stress–energy in terms of new variables, we get four new conservation equations for the radiation

\[\partial T R + \partial \Gamma (\sqrt{-g} R_\mu^\nu) = \sqrt{-g} R^\mu_\nu \Gamma_{\mu\nu} - \sqrt{-g} \Omega G,\]

(39)

\[\partial T R_j + \partial \Gamma (\sqrt{-g} R_j) = \sqrt{-g} R^\nu_\mu T^\mu_j - \sqrt{-g} \Omega J_j,\]

(40)

where \(\Omega = \sqrt{-g} R^{\mu\nu} R_{\mu\nu}\) is the conserved radiation energy density and \(\Omega = \sqrt{-g} R^\mu_\mu\) is the conserved radiation momentum density. The addition of the radiation fields also modifies the MHD energy–momentum conservation equations. The new equations are

\[\partial T E + \partial \Gamma (-\sqrt{-g} T^\mu_\mu) = - \sqrt{-g} T^\mu_\mu \Gamma_{\mu\nu} - \sqrt{-g} \Omega G,\]

(41)

\[\partial T S_j + \partial \Gamma (\sqrt{-g} T_j) = \sqrt{-g} T^\mu_\mu \Gamma_{\mu\nu} + \sqrt{-g} \Omega J_j.\]

(42)
The full set of conserved variables, fluxes, and source terms is now

\[
\mathbf{U}(P) = \begin{pmatrix} D \\ S_j \\ B_j \\ R \\ \mathcal{R}_j \end{pmatrix}, \quad \mathbf{F}(P) = \begin{pmatrix} DV^i \\ -\sqrt{-g} T^i_j \\ \sqrt{-g} T^i_j \\ B^j V^i - B^i V^j \\ \sqrt{-g} R^j_0 \end{pmatrix},
\]

\[
\mathbf{S}(P) = \begin{pmatrix} 0 \\ -\sqrt{-g} T^0_\alpha - \sqrt{-g} G_0 \\ \sqrt{-g} R^0_\alpha - \sqrt{-g} G_0 \\ \sqrt{-g} R^0_\alpha - \sqrt{-g} G_0 \\ \sqrt{-g} R^0_\alpha - \sqrt{-g} G_0 \end{pmatrix}.
\]

(43)

The expanded set of primitive variables is now

\[
\mathbf{P} = \begin{pmatrix} \rho \\ \rho_\epsilon \\ V^j \\ B^j \\ E \\ F^j \end{pmatrix}.
\]

(44)

Fortunately, the inversion of the radiation variables can be written as a simple set of algebraic expressions (utilizing \(P_{\text{rad}} = E/3\)) and can be solved independently of the MHD primitive fields:

\[
E = 3 \left( \frac{\mathcal{R}^0 + 2 \rho u_0 u_\alpha \mathcal{R}^\alpha}{\sqrt{-g} g^{00} - 2 W u^0} \right)
\]

(45)

\[
F^0 = \frac{-1}{\sqrt{-g}} (W E + u_\alpha \mathcal{R}^\alpha)
\]

(46)

\[
F^j = \frac{\mathcal{R}^j}{W} - \frac{F_0 u^j}{u^0} - \frac{4}{3} E u^j - \frac{g^{0j} E}{3 u^0}.
\]

(47)

Inside the code we check that the radiation flux satisfies the physical limit \(\sqrt{\mathbf{F}_p \mathbf{F}^p} \leq E\).

The advantage of this approach is that, by writing the radiation equations in conservative form, we can take full advantage of the HRSC machinery described in Section 2.2 to solve the full set of GR radiation MHD equations. Thus, there is relatively little code development beyond adding new variables, flux terms, and source terms.

### 2.5. Wave Speed Calculation

The HLL and Lax–Friedrichs approximate Riemann solvers only require the maximum and minimum wave speeds, as opposed to the full eigenvectors of the characteristic matrix as would be necessary for a Roe-type scheme. These wave speeds are also required to fix the time step via the Courant condition. The relevant speed is the phase speed \(\omega/k\) of the wave, and we treat each coordinate direction independently. For signals propagating in the \(x_1\) coordinate direction, the corresponding eigenvector is \(k_\alpha = (-\omega, k_1, 0, 0, 0)\), and the wave speed is \(\omega/k_1\).

To find the necessary wave speeds in the grid frame, we start with the following approximate dispersion relation in the comoving frame (Gammie et al. 2003; Farris et al. 2008):

\[
\omega_{\text{cm}}^2 = v_T^2 k_{\text{cm}}^2,
\]

where

\[
v_T^2 = \max \left\{ \frac{1}{3}, \frac{v_A^2 + c_s^2 (1 - \frac{\omega_A^2}{\omega_\alpha^2})}{v_A^2}, \frac{1}{3} \right\}.
\]

(49)

\[v_T^2 = \frac{b^2}{\rho h + b^2}\] is the Alfvén speed, and \(c_s^2 = \Gamma P_{\text{rad}}/\rho h\) is the sound speed. We then substitute the relations \(\omega_{\text{cm}} = -k_\alpha \omega_A\), \(k_{\text{cm}}^2 = k_A^2 K^2\), and \(K = (g_{\alpha} + u_{\alpha} u_{\beta}) k^2\) into Equation (48) to get the following quadratic equation for the desired wave speed \(u/\omega_A\):

\[
\left[ 1 - v_T^2 \left( 1 + g_{\alpha}^0 u_{\alpha}^0 \right) \right] \left( \frac{\omega}{\omega_A} \right)^2 + 2 \left[ v_T^2 \left( V^1 + g_{\alpha}^1 u_{\alpha}^0 \right) - V^1 \right] \left( \frac{\omega}{\omega_A} \right) + \left[ V^1 V^1 - v_T^2 \left( V^1 V^1 + g_{\alpha}^1 u_{\alpha}^0 \right) \right] = 0.
\]

(50)

Wave speeds in the \(x_2\) and \(x_3\) directions are found analogously.

### 3. RADIATION SHOCK TUBE TESTS

Unfortunately, there are very few good test problems for relativistic radiation MHD codes at this time. Among the few are the four radiative shock tube tests introduced in Farris et al. (2008), which we now use to validate our code. Each test includes a nonlinear radiation-hydrodynamic wave: case 1 is a nonrelativistic strong shock; case 2 is a mildly relativistic strong shock; case 3 is a highly relativistic wave; and case 4 is a radiation-pressure-dominated, mildly relativistic wave.

Similar to Zanotti et al. (2011), and unlike Farris et al. (2008), we initiate these problems as traditional shock tubes with two states (“left” and “right”), initially separated by an imaginary partition, instead of starting from the analytic solution. At \(t = 0\) the partition is removed and the gas and radiation are allowed to evolve until a steady state is reached. The initial parameters for the four tests are presented in Table 1. The initial values for the fluxes, not given in Table 1, are set to \(F^x = 10^{-5} E\). The scattering opacity \(\kappa s\) is set to zero in all these tests. Also like Zanotti et al. (2011) and unlike Farris et al. (2008), we do not boost the fluid velocities, instead presenting our results in the frame of the shock. This is important, as quasi-stationary shocks present a particular difficulty for the PPM scheme we are using. In fact, without using the flattening procedure of Colella & Woodward (1984), we find that the two tests that exhibit discontinuities (cases 1 and 2) suffer from post-shock oscillations with amplitudes of a few percent. With the flattening procedure, the oscillations are effectively removed, without creating unnecessary dissipation in the smooth test problems.

Figures 1–4 show the four cases. Although it is possible to calculate semi-analytic solutions for each of these (Farris et al. 2008), we have chosen instead to simply plot results using 800-zone resolution against results using a much higher (3200-zone) resolution. In all cases, the results agree quite well at the different resolutions, and with previously published results.

We have used the smooth wave in case 4 to test the convergence rate of our numerical scheme. Table 2 reports the L-1 norm error (i.e., \(|E(a)|_1 = \sum \Delta x |a_i - A_i|\), where \(a_i\) and \(A_i\) are the numerical and semi-analytic solutions, respectively) for 1600-, 3200-, and 6400-zone resolutions. The convergence rate of the errors for all variables at all resolutions is almost exactly 2, as expected for a smooth flow using our overall scheme.
4. BONDI INFLOW WITH RADIATION

As we mentioned in Section 1, the case of optically thick, spherical accretion onto a non-rotating black hole has been considered many times in the past, although usually with strictly one-dimensional codes. Another difference is that most of the codes in the past have used implicit integration schemes, whereas we are, for now, attempting to proceed using the explicit scheme already in Cosmos+++. Finally, instead of assuming LTE between the gas and the radiation, we consider two physical
cooling processes in the gas: Thomson scattering and thermal bremsstrahlung. The first contributes an opacity

$$\kappa^T = 0.4 \text{ cm}^2 \text{ g}^{-1},$$

while the second has the form (Rybicki & Lightman 1986)

$$\kappa^a = 1.7 \times 10^{-25} T_K^{-7/2} \rho_{cgs} m_p^{-2} \text{ cm}^2 \text{ g}^{-1},$$

where $T_K$ is the ideal gas temperature of the fluid in kelvin, $\rho_{cgs}$ is the density in g cm$^{-3}$, and $m_p$ is the mass of a proton in g. We assume that the gas is fully ionized hydrogen, so the mean molecular weight $\mu = 0.5$.

We have chosen to set up cases similar to ones presented in Vitello (1984) and Nobili et al. (1991), though significant differences in our assumptions mean we do not expect to exactly reproduce their results. In the case of Vitello (1984), they assume LTE throughout the flow, such that they do not need to solve the radiation transport independent of the fluid transport. As we emphasized in Section 2.4.2, we do not enforce LTE in our method. There are even more differences between our approach and that of Nobili et al. (1991). First, they consider a more physical, though also more complicated, equation of state. They also account for Compton scattering of the radiation, which we do not consider in this work. Finally, they use a constant value of $T_o = 10^4$ K for the temperature of the gas at the outer boundary of their simulations, whereas we explore values in the range $10^5$–$10^7$ K.

We use a logarithmic radial coordinate of the form $x_1 \equiv 1 + \ln(r/r_S)$ to cover the expansive spatial range required, where $r_S = 2$ is the Schwarzschild radius. All simulations use a resolution of 512 zones. Note that because this problem is spherically symmetric, we have performed our tests using a one-dimensional, spherical-polar (radial) grid. Nevertheless, we have confirmed that our code produces identical results when the problem is run in two and three dimensions (when using the same radial grid spacing).

To initialize the problems, we first fix the density, $\rho_o$, and temperature, $T_o$, of the gas at $r_o$. Once $T_o$ and $\rho_o$ are fixed, and assuming some relation between $T_{\text{gas}}$ and $T_{\text{rad}}$, we can determine the polytropic index of the gas at $r_o$ from

$$\Gamma = 1 + \frac{1}{3} \left( \frac{P_{\text{gas}} + P_{\text{rad}}}{P_{\text{gas}}/2 + P_{\text{rad}}} \right).$$

From this expression, we can easily see that $\Gamma = 5/3$ for gas-pressure-dominated flows, whereas $\Gamma = 4/3$ for radiation-pressure-dominated ones. We assume that the initial value of $\Gamma$ found at $r_o$ applies throughout the flow for the duration of the simulations. By assuming a polytropic equation of state, $P \propto \rho^\Gamma$, we can determine the initial temperature profile of the gas from

$$T_{\text{gas}} = T_o (\rho/\rho_o)^{\Gamma-1}.$$
We still need to specify the initial profiles of \( u' \) and \( \rho \). For simplicity, we assume that these equal their free-fall values \( u' = -\sqrt{2M/r} \) and \( \rho = -\dot{M}/4\pi r^2 u' \) at all radii, with the mass accretion rate, \( \dot{M} \), now one of our free parameters. We explore mass accretion rates in the range \( 10 \leq \dot{m} = \dot{M}/\dot{M}_{\text{Edd}} \leq 300 \), where \( \dot{M}_{\text{Edd}} \) is the Eddington mass accretion rate. The lower limit is set by the requirement that at least some portion of the flow be optically thick. The upper limit is set by the requirement that the “photosphere” be contained within the grid. The photosphere is where the optical depth \( \tau \) becomes 1, with \( \tau \) defined as

\[
\tau \equiv \int_{0}^{\chi} (\chi^a + \chi^s) \text{d} s.
\]  

(55)

In practice, we approximate the optical depth as \( \tau \approx (\chi^a + \chi^s)r \).

We consider three types of simulations, all with \( M = 3M_\odot \), \( r_o = 10^4r_\odot \), and \( r_i = 0.95r_\odot \). In the first, the gas is purely adiabatic, as we ignore radiation; in the second, we include radiative processes as described above; in the last, we also include a radial magnetic field of the form \( B' = -\partial_\theta A_\phi \), where

\[
A_\phi = \text{sign}(\cos \theta) \cos \theta \sqrt{2P_0/\beta_o r_o^2}
\]  

(56)

and \( \beta_o = 100 \). Since the field is purely radial and weak, it has no noticeable effect on the dynamics. Nevertheless, we wanted to include at least one test using all of the physics discussed in this paper. Future work will rely much more heavily on the full capability.

For the tests with radiation, we initially specify the ratio of radiation to gas temperature, \( T_{\text{rad}}/T_{\text{gas}} \ll 1 \). This is mainly done so that the radiation energy density \( E = aT_{\text{rad}}^4 \) may start with some reasonable value. The radiation flux is similarly set to an arbitrary initial value \( F' \ll E \). We confirm that our final results are not sensitive to our choices for these parameters.

The reason we initialize the radiation temperature to a much lower value than the gas is because if the radiation and gas are nearly in thermal equilibrium, i.e., \( E \approx aT_{\text{gas}}^4 \), then the first two terms of Equation (38) are approximately equal, meaning their difference can be arbitrarily small. This makes the corresponding source terms of Equations (39)–(42) incredibly stiff, and stable evolution with an explicit scheme would require an unacceptably small time step. In future work we plan to explore using an implicit scheme to solve this source term, which will alleviate this stability problem. However, this limitation does not significantly affect the simulations presented here. This is because the radiative processes we are considering are not very efficient, so the steady-state radiation temperature (and pressure) is naturally significantly less than the gas temperatures (and pressures) we consider.

Table 3 summarizes the key simulation parameters for this section. Each simulation is run long enough for \( E \) and \( F' \) to achieve steady-state profiles out to the photosphere. Our main
diagnostic in this section is the emitted luminosity, which can be recovered directly from the evolved radiation fluxes $F_i$. Specifically,

$$L = \int_V F_i n_i dA,$$  \hspace{1cm} (57)

where $A$ is the surface area encompassing the volume $V$. The surface is taken to correspond to the photosphere ($\tau = 1$). We measure the luminosity in units of the Eddington luminosity $L = L/\dot{M}_{\text{Edd}}$, where $L_{\text{Edd}} = 4\pi GM c\sigma_T/\rho c^2$ represents the limit at which outward radiation pressure balances gravity. Above this limit, the radiation pressure is sufficient to halt, or even reverse, accretion. We define the radiative efficiency of our flows as $\eta = L/\dot{m}$.

Figure 5 shows profiles of six different simulations exploring different values of $T_o$ and $\dot{m}$. We did not include the adiabatic (E10a) or radiation + magnetic field (E10T6b) cases in this plot since they are practically indistinguishable from our reference radiation simulation, E10T6. The fact that the adiabatic and radiation simulations are so similar is not surprising since the radiation pressure is so much smaller than the gas pressure, $P_{\text{rad}} < 0.025 P_{\text{gas}}$ throughout the flow; so even with radiation, the flow behaves nearly adiabatically. This reflects the very inefficient nature of the radiative processes we are considering. The radiation + magnetic field simulations appear nearly identical, which again is expected since the magnetic field is purely radial and weak, so it cannot play a dynamical role.

In all of the cases the inflow is supersonic over the entire radial domain. The accretion radius $r_a = GM/c_{\infty}^2$ also lies beyond the outer radial boundary for each of these cases. We
are, however, able to identify the trapping radius \( r_t \), where the advection of photons inward becomes faster than their diffusion outward, i.e., \(|E V' - F'\rangle\), in all of our simulations; this point is marked with a symbol on each of the plots of \( F' \).

Simulations E10T5, E10T6, and E10T7 illustrate one of the main drawbacks of our current method—the restriction to optically thick flows. For simulations with \( \dot{m} \lesssim 10 \), the flow is only optically thick in the inner few \( r_S \). Once the optical depth drops below \( \tau \approx 0.1 \), we begin to see oscillations or noise in the profiles of \( E \) and \( F' \). These oscillations do not appear to damp away with time and indicate a fundamental limit to our method.

Even though the mass accretion rates in all these simulations are highly super-Eddington (\( \dot{m} \gg 10 \)), the luminosities are not (\( l \lesssim 7.9 \times 10^{-4} \)) (see Table 3). Clearly the low radiative efficiency of this flow \( \eta \equiv l / \dot{m} < 2.6 \times 10^{-6} \) indicates that not all of the binding energy that is liberated by accretion is able to escape in the form of radiation. Instead, much of the energy, in the form of kinetic energy, heat, and radiation, is advected into the black hole. Figure 6 presents all of our Bondi results in the \( l - \dot{m} \) plane. These results are broadly consistent with earlier studies of optically thick spherical accretion (e.g., Vitello 1984; Nobili et al. 1991; Zampieri et al. 1996), given that different assumptions were used in each work.
5. CONCLUSION

In the study of black hole accretion, it only makes sense to treat the whole problem (gravitation, gas dynamics, magnetic fields, and photons) in a relativistic framework. Therefore, the development of a fully relativistic radiation MHD numerical code is an essential step. Along with allowing us to answer some of the very long-standing questions concerning black hole accretion, having this capability will also allow us to explore such novel effects as disk self-illumination due to light bending near the black hole. There are also astrophysical applications of such novel effects as disk self-illumination due to light bending near the black hole. There are also astrophysical applications of such novel effects as disk self-illumination due to light bending near the black hole. There are also astrophysical applications of such novel effects as disk self-illumination due to light bending near the black hole.

We now have a scheme that is able to self-consistently treat the radiation on equal footing with the MHD in the vicinity of the black hole. There are also astrophysical applications of such novel effects as disk self-illumination due to light bending near the black hole. There are also astrophysical applications of such novel effects as disk self-illumination due to light bending near the black hole. There are also astrophysical applications of such novel effects as disk self-illumination due to light bending near the black hole. There are also astrophysical applications of such novel effects as disk self-illumination due to light bending near the black hole.

This paper demonstrates that we have taken the first step toward that goal. We now have a scheme that is able to self-consistently treat the radiation on equal footing with the MHD in a fully GR framework. We have shown that the method performs well restricted to the appropriate parameter space, i.e., we require \(|F_\alpha| \equiv \sqrt{F_\alpha F^{\alpha}} \ll E, \tau \gtrsim 1\), and that the gas and radiation be far from LTE.

One improvement to our method might be to extend it to treat both optically thick and thin flows by implementing a more general closure relation. Currently, we assume that the radiation pressure has the form \(P_{\gamma}^{ij} = \gamma P_{\gamma}^{ij} = E/3\delta^{ij}\), i.e., we adopt an Eddington factor of 1/3 to close the set of radiation moment equations. Although the simplicity of this prescription is desirable, this approximation is only appropriate in the optically thick limit. More general Eddington tensors, which recover the correct asymptotic behavior for both optically thick and optically thin gas, are available (e.g., Levermore 1984) and could be implemented.

A related issue that must be addressed is that HRSC schemes fail to treat the optically thick limit properly when the photon mean free path is shorter than the numerical grid spacing (Lowrie & Morel 2001). The simplest fix for this is to phase out the relevant terms in the diffusion limit when the mean free path is short (Jin & Levermore 1996).

Finally (and not surprisingly), we have found that the fully explicit method described in this paper suffers from severe time step restrictions. Even the relatively modest 512-zone, one-dimensional spherical simulations in Section 4 required approximately 10 million cycles to complete, which took approximately 48 hr on two, dual-core 2.0 GHz AMD Opteron processors. Clearly a well-resolved three-dimensional disk simulation is out of the question. One way we could get around this would be to develop a hybrid explicit–implicit scheme, where an implicit step is used to solve either the radiation source terms (while using the current HRSC method to handle the transport; cf. Turner & Stone 2001) or the full radiation equations (while still solving the MHD equations explicitly). Unfortunately, implementing implicit solvers in large, multidimensional simulations can be computationally challenging, as it involves the inversion of a large, sparsely populated matrix. It will take some work to determine the best way to proceed.

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