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Active tectonics around the Mediterranean

Active faulting and transpression tectonics along the plate boundary in North Africa

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ABSTRACT

We present a synthesis of the active tectonics of the northern Atlas Mountains, and suggest a kinematic model of transpression and block rotation that illustrates the mechanics of this section of the Africa–Eurasia plate boundary. Neotectonic structures and significant shallow seismicity (with Mw >5.0) indicate that coeval E-W-trending, right-lateral faulting and NE-SW, thrust-related folding result from oblique convergence at the plate boundary, which forms a transpressional system. The strain distribution obtained from fault–fold structures and P axes of focal mechanism solutions, and the geodetic (NUVEL-1 and GPS) convergence show that the shortening and convergence directions are not coaxial. The transpressional strain is partitioned along the strike and the quantitative description of the displacement field yields a compression-to-transcurrence ratio varying from 33% near Gibraltar, to 50% along the Tunisian Atlas. Shortening directions oriented NNE and NNW for the Pliocene and Quaternary, respectively, and the S shape of the Quaternary anticline axes, are in agreement with the 2.24°/Myr to 3.9°/Myr modeled clockwise rotation of the small tectonic blocks and with the paleomagnetic data. The convergence between Africa and Eurasia is absorbed along the Atlas Mountains at the upper crustal level, by means of thrusting above decollement systems, which are controlled by subdued transcurrent faults. The Tell Atlas of northwest Algeria, which has experienced numerous large earthquakes with respect to the other regions, is interpreted as a restraining bend that localizes the strain distribution along the plate boundary.

1. Introduction

Along the Gibraltar–Sicily section, the Atlas Mountains are among the most active zones in the Mediterranean region, due to the Africa–Eurasia plate convergence (Figure 1). Large and moderate-sized shallow seismic events have been recorded over the last few decades along this plate boundary, with the largest being the October 10, 1980, El Asnam Ms 7.3 earthquake that was associated with a NW-dipping, emerging thrust fault [Philip and Meghraoui 1983, Yielding et al. 1989]. The next largest events are the Boumerdes (Algeria) seismic sequence, which started with a Mw 6.8 event in May 2003 [Meghraoui et al. 2004, Brommer and Bernardi 2005], and the Al Hoceima (Morocco) Mw 6.4 event in 2004 [Stich et al. 2005, Cakir et al. 2006] (Figure 2a). The thrust-and-fold belts of North Africa appear, however, as a zone of diffuse deformation, with no clear interplate limit striking across the Alboran Sea and the Rif and Tell Atlas Mountains [Grimison and Chen 1986, Serpelloni et al. 2007]. The plate boundary is often indicated as an E-W straight line parallel to the Mediterranean coast, or drawn along the foreland–hinterland limit of the Tertiary fold-and-thrust belt, or inferred from hypothetical tectonic blocks. This is probably due to the low level of seismicity associated with the relatively low convergence rate (3 to 6 mm/yr) [McKenzie 1972, Buforn et al. 2004, Nocquet and Calais 2004], and to the complex tectonic pattern of the Tertiary contractional orogen [Frizon de Lamotte et al. 2000, Faccenna et al. 2004]. Recent models using new datasets from bathymetry [Zitellini et al. 2009] and 65 continuous global positioning system (GPS) stations [Koulali et al. 2011] have provided new insights along the plate boundary. However, the link between the late Quaternary tectonics and present-day active deformation remains poorly constrained, and a conceptual kinematic model is needed to better explain the transpressive tectonics [Morel and Meghraoui 1996].

The counter-clockwise rotation of Africa with respect to Eurasia obtained from global models implies an oblique convergence along the western section of North Africa, and shows an increasing eastward rate of 3 mm/yr to 5 mm/yr (NUVEL-1 plate tectonic model) [DeMets et al. 1994]. This depends on the modeling configuration of the global plate motion [DeMets et al. 1994], the tectonic geodesy models [Nocquet and Calais 2004], the GPS measurements [McClusky et al. 2003, D’Agostino and Selvaggi 2004, Sella et al. 2002], or on the combination of various data [Serpelloni et al. 2007]. Recently acquired GPS data confirm the
oblique convergence and associated rate from Gibraltar to Tunisia–Sicily (Figure 1b) [Fernandes et al. 2007, Serpelloni et al. 2010, Vernant et al. 2010]. In this context, the relationships between the dextral Gloria transform fault (west of Gibraltar) and the Atlas geological domain is comparable to the tectonic pattern of continental-collision belts, where the major transcurrent faults interact with thrust-and-fold systems [Oldow et al. 1990, Frizon de Lamotte et al. 2000]. Using magnetic reversal reconstructions in the Atlantic, the onset of continent-continent convergence between Iberia and North Africa was determined to be at 25 Myr [Srivastava et al. 1990]. Evidence of active delamination at the lithospheric scale beneath the Alboran Sea suggests a complicated geodynamic model for this plate boundary, instead of a simple subduction during the Late Cenozoic [Seber et al. 1996].

In the present study, published tectonic data on shortening directions of Quaternary faulting and folding correlated with moment tensor summation of significant seismic events in the Rif and Tell Atlas. The crustal deformation is documented along the Atlas Mountains in terms of the displacement field, with strain partitioning largely controlled by plate motions. On the basis of some mechanical properties of shear zones, we propose a kinematic model of transpression and block rotation that accounts for the main tectonic processes along the plate boundary in North Africa.
2. Active deformation and strain rates

2.1. Active tectonics and transpression

Mainly structured during the Alpine orogeny (Eocene to Miocene), the E-W-trending coastal Atlas Mountains of North Africa underwent major active deformation during the Quaternary. This region can be subdivided into 10 distinct tectonic zones, from west to east (Figure 1b):

1. The West Rif (Figure 1b, RW) and the related southern Gibraltar region, which are characterized by NE-SW-trending Pleistocene folding, strike-slip faults, and SW vergence of fold-and-thrust nappes [Chalouan et al. 2004].

2. The East Rif overthrust structures (Figure 1b, RE), with S and SW vergence, which are characterized by the two main NE-SW-trending, left-lateral, strike-slip faults (the Jebha and N’Kor faults), and related overthrust structures. These are also visible along the Alboran ridge anticlines that are limited to the north by the E-W-trending, right-lateral Yusuf fault [Morel and Meghraoui 1996, Ballesteros et al. 2008]. The two latter structures provide striking elements of recent tectonic activity, with regard to the late Quaternary deformation visible on seismic profiles across the Alboran Sea (i.e., folded and faulted Pleistocene and Holocene deposits along the ridge, and faulted young deposits with prominent topographic offset across the Yusuf pull-apart basin) [Chalouan et al. 1997]. This region was the site of the destructive 1994 and 2004 Al Hoceima earthquakes [Stich et al. 2005, Cakir et al. 2006].

3. The Oran quadrant (Figure 1b, OR) is the region where the marine Yusuf fault extends to the east into a large continental Neogene and Quaternary basin that is affected by the NE-SW-trending and right-stepped en-echelon active folds [Thomas 1976]. As the anticline axes are deformed in an ‘S’ shape, this suggests clockwise rotation during their growth. The 1790 large historical earthquake of Oran and the Mw 5.9 1999 Ain Temouchent earthquake [Stich et al. 2005, Cakir et al. 2006].

4. The Cheliff region (Figure 1b, CH) includes the NE-SW-trending and right-stepped en-echelon active folding of the Cheliff Basin and the associated El Asnam active fault responsible for the October 10, 1980, large earthquake (Mw 7.3) [Philip and Meghraoui 1983, Meghraoui et al. 1986].

5. The Algiers region (Figure 1b, AL) represents the intermontane sedimentary basins, which include the Mitidja, and shows an average of 1000 m of topographic offset, with strongly folded late Quaternary deposits [Maouche et al. 2011]. This area was the site of the last two large earthquakes with thrust mechanisms (Ms 6.4 of June 10, 1910, at Aumale, now Sour El Ghoulane, and Mw 6.8 of May 21, 2003, at Zemmouri-Boumerdes).

6. In the Kabylies (Figure 1b, KA), the high mountains of Djurdjura have thrusts and nappes and southern vergence that involves outcrops of basement rock, and they limit the Quaternary Soummam Basin and extend to the south to the High Plateau [Boudiaf et al. 1999]. This region was the site of numerous, although low to moderate, thrust earthquakes. The Beni Ourtiane thrust earthquake of November 10, 2000 (Mw 5.7) illustrates the active deformation in this region [Bouhadad et al. 2003].

7. The Edough Massif and the coastal region of north-east Algeria (Figure 1b, ED). The right-lateral, pull-apart Neogene and Quaternary basin of Guelma, and the left-lateral, NE-SW faults with the associated earthquakes (such as the October 27, 1985, Ms 5.9 earthquake at Constantine) [Meghraoui 1988] reflect the importance of tectonic movements in this region. Moreover, active folding and related thrusts observed offshore of the Algerian–Tunisian coastline mark the frontal limit of the convergent zone [Kherroubi et al. 2009].

8. The Gafsa region (Figure 1b, GA) that covers the Aures Mountains and the south Atlas limit with the Sahara platform in Algeria and Tunisia shows active folding and faulting and NNW-SSE-trending active graben structures. Moderate, but destructive, earthquakes have affected this area [Chihi 1995].

9. The Tunis region (Figure 1b, TU) extends eastwards across Tunisia. Active NE-SW, left-lateral and east-west striking, right-lateral faults with reverse components constitute the main tectonic framework [Ben Ayed 1986, Kassem 2004]. The Sicily–Tunisia zone with the E-W-trending and NE-SW trending active thrusts are the main active zones in this region.

10. The Tunisian Sahel region (Figure 1b, SA) is a poorly known zone that has moderate earthquakes with predominant strike-slip focal mechanisms. Uplifted marine terraces can be observed along the shorelines of this region [Chihi 1995].

Fault and fold structures, stress tensor inferred from tectonic features (in-situ measurements and fault-plane stria- tions), and unconformities between Neogene and Quaternary sedimentary units in the Alboran back arc and the Cheliff intermontane basins provide evidence of NE-SW to NW-SE successive shortening movements superimposed on the main Cenozoic overthrust structures, [Meghraoui et al. 1986, Rebai et al. 1992]. Using restored cross-sections and detailed regional studies along the plate boundary zone across Spain and Morrocco, Dewey and others [1989] estimated 5 mm/yr for the N-S to NW-SE contractional rate over the last 9 Myr. Kinematic analysis of fault populations in the Rif and Tell Atlas indicates two successive shortening directions (NNE and then NNW), which suggests a clockwise block rotation of 15° to 25°, if the main regional stress direction has remained unchanged since the early Quaternary [Meghraoui et al. 1986, Rebai et al. 1992, Morel and Meghraoui 1996]. Folded and faulted Quaternary deposits
Figure 2. (a) Focal mechanism dataset used in the present study. Global CMTs in red and European Mediterranean RCMTs in blue (see main text for data references). (b) Quaternary tectonic shortening directions (red symbols) [Meghraoui 1988, Rebai et al. 1992, Morel and Meghraoui 1996] and P axes (yellow symbols) of all of the events mapped in Figure 2a for the dataset used in the present study. (c) Recent GPS data for the western Mediterranean with Nubia fixed (black, Anzidei et al. 2001; red, Fernandes et al. 2007; yellow, Vernant et al. 2010; cyan, Serpelloni et al. 2010). The yellow strip indicates the plate boundary zone in North Africa. A clockwise rotation of GPS directions can be observed from ENE-WSW in northern Iberia to NW-SE at the plate boundary in northern Algeria and N-S to ENE-SSW in northern Morocco. Note that the P axes and shortening directions of Figure 2b are not coincident with the convergence directions, as indicated by the GPS vectors in the western Mediterranean. This discrepancy is related to the obliquely convergent African and Eurasian plates.
and marine terraces along the NE-SW, left-lateral faults of the Rif Mountains show uplift and left-lateral slip rates that reach a maximum of 1 mm/yr and 2.3 mm/yr, respectively [Morel and Meghraoui 1996]. The late Pleistocene and Holocene shortening rate of 0.17 mm/yr to 1.2 mm/yr across the El Asnam fault was obtained from paleoseismic data analysis [Meghraoui and Doumaz 1996]. This implies an estimated total shortening rate that yields a maximum of 2.2 mm/yr across the Tell Atlas, as obtained from summing the compressional deformation across the Cheliff basin and the related fault-related folds [Meghraoui et al. 1996]. The late Quaternary shortening directions obtained from the kinematic analysis of fault populations (Figure 2b) document the displacement field along the northern Atlas fold-thrust belts, and indicate strain partitioning between the 

tension mechanism that expresses the interactions between the active folding and thrusting with the strike-slip faults along the plate boundary. 

Local and regional seismotectonic studies in North Africa have suggested that the active thrusts and strike-slip faulting are coeval, and that contractional tectonics are accompanied by right-lateral en-echelon fold axes, basal décollements and dip-slip geometries with imbricate structures in the upper crust [Yielding et al. 1989, Meghraoui et al. 1996]. The correlation between the offshore, right-lateral Yussuf fault (of the Alboran Sea) and the continental right-stepping en-echelon folds in the Cheliff Basin (Figure 1a) implies that the crustal deformation is decoupled and therefore the E-W, right-lateral, strike-slip faulting and the NE-SW, folding and thrust or reverse faulting. The comparison between the P axis directions of the focal mechanisms, the shortening directions from fault kinematics, and the GPS slip directions and velocities indicate an along-strike difference in the shortening and compression directions (Figure 2b and c). This discrepancy between local shortening and large-scale convergence directions might be due to a transpression mechanism that expresses the interactions between the active folding and thrusting with the strike-slip faults along the plate boundary. 

2.2. Geodesy and convergence rate 

Recent measurements from GPS stations complement and increase the accuracy of recent tectonic movements of the previous global models of plate convergence of NUVEL-1 and REVEL in the western Mediterranean [DeMets et al. 1994]. Early continuous GPS stations in northern Algeria installed in the framework of the Tyrrhenian Geodetic Network (TYRGEONET) and the Geodynamic Modeling of the Apennines (GEOMODAP) have provided results from measurements that extended from 1995 to 1998 from two stations in Algiers and Arzew [Anzidei et al. 2001] (see Figure 2c). The continuous GPS Geodynamic Data and Analysis Center (GEODAC) network with stations located mainly in Spain and Portugal, and three stations in northern Morocco, include the plate boundary between Iberia and Morocco. These data were processed from 1996 to 2005 and revealed a clear clockwise rotation of convergence rates from WNW-ESE in northern Spain, to NW-SE in southern Spain, and NNE-SSW in northern Morocco [Fernandes et al. 2007]. This rotation was further confirmed by survey-mode GPS campaigns from 1999 to 2009 in Morocco, which incorporated results from continuous GPS in Spain [Vernant et al. 2010, Koulali et al. 2011]. All of the GPS data indicated a 3 mm/yr to 5 mm/yr rate of convergence across the plate boundary between Spain and Algeria–Morocco regions, and 1 mm/yr to 2 mm/yr velocities in southern Spain and the Rif Mountains, and 2 mm/yr to 3 mm/yr across the Tell Atlas in Algeria. The rates of convergence increase to 5-6 mm/yr further east across the plate boundary between Lampedusa, Sicily and Sardinia [Serpelloni et al. 2007] (Figure 2c). The change in the convergence directions shown by GPS data from the Gibraltar Strait to Sicily illustrates an obliquely convergent plate boundary. 

2.3. Seismicity and moment tensor summation

The area that includes the fold-and-thrust belt of North Africa and Sicily has been characterized by the occurrence of several large and moderate shallow earthquakes (Figures 1a and 2a). The thrust focal mechanisms are predominantly located in the Tell Atlas (northern Algeria) and the right-lateral strike-slip mechanisms are mainly in the Atlantic and Alboran sea domains, which suggests the oblique convergence and an associated transpression system. Even if not homogeneous, the spread of shallow seismicity over the plate boundary and the recently well-constrained seismic parameters (such as focal mechanisms and seismic source characteristics) required the subdivision of the study region into 10 zones. The local and regional active tectonics combined with the characteristics of moderate and large earthquakes constrain the defined zones. The strain field distribution along the coastal Rif and Tell mountains has a general consistency with the P axis directions of the focal mechanism solutions, which strike from NW-SE to N-S going eastwards (Figures 1a and 2b). 

To study the pattern of seismic deformation along the plate boundary zone, we use the more recently updated dataset of moment tensors that is available for the last 30 yr in this region (Figure 3). Moment tensors are obtained by merging all of the on-line catalogs: (1) the Global Centroid
Moment Tensor (GCMT) catalog [Dziewonski et al. 1983, 2000, and references therein; Ekström et al. 2005a, 2005b; www.globalcmt.org] that includes the seismic moment tensors for all earthquakes worldwide with $M \geq 5.5$ available, starting from 1977; (2) the European Mediterranean Regional Centroid Moment Tensor (RCMT) catalog [Pondrelli et al. 2002, 2004, 2006, 2007; http://www.bo.ingv.it/RCMT] that includes the moment tensors for all seismic events with $M \geq 4.5$ in Europe and the Mediterranean region, starting from 1997. When a moment tensor exists in both catalogs, for a given earthquake with $M > 5.5$, we select the GCMT, while for lower $M$ we use the RCMT solution. As already used for similar datasets by Pondrelli et al. [2006], these criteria are associated with the methods used to compute the moment tensors. Indeed, GCMTs have been traditionally computed by inverting for body and mantle seismic waves, which are suitable for large-magnitude events, thus with $M > 5.5$, while the RCMTs are computed by inverting for surface waves, that when recorded at regional distances are appropriate to determine the seismic moment tensor for moderate magnitude events, with $4.5 > M > 5.5$.

The dataset that we composed and used in the computations included seismic moment tensors for earthquakes of the last 30 years with $M > 4.5$ (Figure 2). We applied the moment tensor summation technique to each box [Kostrov 1974, Jackson and McKenzie 1988, Ekström and England 1989, Westaway 1990], which allowed quantitative evaluation of the strain due to a number $N$ of earthquakes within a rock volume $V$. $V$ is commonly a layer characterized by a length, width and the thickness of the seismogenic zone, which is here fixed to 15 km (Table 1). The Kostrov [1974] methodology works starting from the following equation:

$$F_y = \frac{1}{2\mu V} \sum_{k=1}^{N} M_{k}^y$$

where $\mu$ is the shear modulus, and the sum of the moment tensor elements $M_{k}^y$ is taken for each $k$-earthquake. Already applied in the Mediterranean, this method evolved to determine the average strain rate integrated over time. In addition, we calculate the seismically inferred velocity and the percentage of seismic strain rate that can be compared to an expected strain rate determined with other data; e.g. geodetic measurements [Jackson and McKenzie 1988, Pondrelli et al. 1995, Meghraoui and Pondrelli 1998, Vannucci et al. 2004, Stich et al. 2006]. Using Equations (4) and (7) in Pondrelli et al. [1995] and with 30 years of data, we compute the relative horizontal velocities for each box, as normal ($v_{x_0}$) and parallel ($v_{y_0}$) to the plate boundary (the reference system being NE-down as positive, equal to $xyz$). To evaluate how much the seismic strain contributes to the total seismically inferred velocity at the plate boundary, we also computed the moment tensor rate $N$ for each box [Jackson and McKenzie 1988, Pondrelli et al. 1995], which was determined on the basis of the NUVEL-1 velocities [DeMets et al. 1994]. The comparison between $N$ and the cumulative seismic moment tensor rate gives the percentage of seismic deformation with respect to the overall deformation, and allows the definition of the aseismic deformation. Furthermore, our seismic strain results are strictly related to the volume of the boxes; e.g. the volume within which we average the seismic moment release. These boundary conditions are acceptable when the objective is only to obtain a picture of the seismic deformation pattern, while they become critical if we seek an absolute deformation rate.

Computations were carried out on separate boxes, to identify the partitioning of strain distribution and where strike-slip or compressive deformation prevails. The data are shown in Table 1, where all of the used and obtained parameters are reported for each box. In Figure 3, the cumulative focal mechanisms obtained by moment tensor summations show that when moving from W to E, the geometry of the seismic deformation is different from what is expected for a pure compressive tectonic boundary. It is evident that the deformation is not simply purely compressive, and that a strike-
slip component in most of the boxes prevails or provides a greater contribution, as for the Cheliff region (Figure 1b, CH). This strain distribution is typical of oblique convergence, where part of the deformation is cumulating not only across it, but also along the strike of the boundary.

The geometry of the deformation pattern is confirmed also by the seismic velocity values and percentages (Table 1). Taking into account that the computations are carried out in a reference system where x is North-positive, y is East-positive and z is down, we can see that in all of the studied regions the seismic velocity component across the boundary (Table 1, v_{xx}) is compressive (negative values), which also reaches values of nearly 10 mm/yr for the Cheliff region. The only opposite result is for the SA region (Tunisia; Figure 1b), where seismicity is relatively scarce, but extension in this region can exist. The greatest values are, however, found for the seismically inferred velocity component across the boundary (v_{xx}), all of which are positive, which means dextral motion.

In a couple of regions, the strike-slip component is greater than the compressive component, as in the East Rif and Cheliff regions. Areas with seismically inferred velocities (v_{xx} and v_{xy}) lower than 0.1 mm/yr are not used in our discussion, although we take into account that they follow the general trend.

Comparing the predicted strain rate obtained using NUVEL-1, and the seismically inferred velocities computed in this study, we evaluate the ratio of total deformation inferred from the existing shallow seismicity. In three regions, the seismically inferred velocity is greater than that predicted. In particular, this is the case in the East Rif region, for the strike-slip component only, and in the Algiers and Cheliff regions, where the seismically inferred velocity is larger for both components. It is worth noting that for all of the regions, the percentages of the strike-slip motion are greater than the percentages of the predicted compressive strain rate. This implies that a considerable part of the strike-slip deformation is not accounted for along the North Africa plate boundary in the NUVEL-1 global plate motion model. Hence, these results underline how the strike-slip motion is relevant in an area where usually only the convergence is considered, and that the missed component of transpression and internal deformation along the plate boundary needs to be taken into account in the kinematic model.

Finally, the comparison between the P axis directions of focal mechanisms, the shortening directions from fault kinematics, and the GPS velocities and directions indicates a clear along-strike difference (Figures 2b and c). This discrepancy between the shortening and convergence directions might reflect a transpression mechanism with interactions between active folding and thrusting with strike-slip faults along the plate boundary.

3. Model of block rotation and transpression

In a previous study, analysis of recent tectonic structures of the Goringe–Alboran–Tell (GALTEL) regions revealed that the Quaternary fault-related folds and associated shallow seismicity can be interpreted as a transpressive deformation with clockwise block rotation [Morel and Meghraoui 1996]. Kinematic modeling with block rotations applied to the Transverse Ranges in California, USA [Jackson and Molnar 1990], provide an interesting analog to the North Africa plate boundary. For the sake of simplicity of the tectonic blocks in North Africa, we group these as: (i) the Rif in a single large block (Figure 1b, RE plus RW); (ii) Algiers and Kabylies in a single large block (Figure 1b, AL plus KA); and (iii) the Edough, Gafsa, Tunis and Sahel re-

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| Box | Length (km) | Width (km) | Predicted velocity (cm/yr) | Strike | N. events | Total seismic moment (e25 dyn.cm) | v_{xx} (mm/yr) | v_{xy} (mm/yr) | %xx | %xy |
|-----|-------------|------------|-----------------------------|-------|-----------|-------------------------------|--------------|--------------|-----|-----|
| RE  | 220         | 120        | 0.38                        | 150   | 27        | 5.142                         | -1.624       | 4.073        | 49  | 214 |
| RW  | 250         | 120        | 0.35                        | 120   | 6         | 0.229                         | -0.098       | 0.358        | 6   | 12  |
| AL  | 200         | 120        | 0.45                        | 150   | 21        | 22.248                        | -5.299       | 4.335        | 136 | 193 |
| CH  | 200         | 120        | 0.45                        | 150   | 13        | 54.815                        | -9.668       | 14.349       | 248 | 638 |
| ED  | 220         | 220        | 0.50                        | 160   | 2         | 0.186                         | -0.037       | 0.040        | 0.80 | 2.3 |
| GA  | 300         | 300        | 0.50                        | 160   | 6         | 0.881                         | -0.062       | 0.437        | 1.3  | 26  |
| KA  | 220         | 100        | 0.45                        | 150   | 4         | 0.569                         | -0.086       | 0.180        | 2.2  | 8   |
| OR  | 200         | 120        | 0.38                        | 150   | 2         | 0.513                         | -0.054       | 0.204        | 1.6  | 11  |
| SA  | 250         | 300        | 0.50                        | 160   | 5         | 0.189                         | 0.005        | 0.031        | 0.10 | 1.8 |
| TU  | 300         | 200        | 0.50                        | 160   | 2         | 0.148                         | -0.025       | 0.021        | 0.5  | 1.2 |

Table 1. Parameters obtained from the computation of the cumulative moment tensors. See Figure 1b for each box and tectonic zone. The length and width are for the volume V used in the summation, with the strain rate predicted by the NUVEL-1 plate tectonic model [DeMets et al. 1994]. v_{xx} and v_{xy} represent the seismically inferred velocity across (v_{xx}) and along (v_{xy}) the plate boundary, with the percentages of the seismic deformation with respect to the overall deformation across (%xx) and along (%xy) the boundary also given. The reference system used is x corresponding to North-positive, y corresponding to East-positive, and z corresponding to down-positive.
regions in a single large block (Figure 1b, ED, GA, TU plus SA). The sub-division of the remaining five tectonic zones (see Figure 1b and Table 2) is based on the active tectonics background and the known seismic fault parameters. Taking into account the main shock location, the coseismic faulting, and the aftershock distribution of the El Asnam earthquake [Yielding et al. 1989], we can delimit small tectonic blocks (50 km long, 20 km wide) that belong to a large zone and can undergo rotation (Figures 1b and 4). This pattern of active deformation can be modeled and expressed by means of field parameters, as follows.

3.1. Rotation

The model assumes the rotation $R$ of small rigid blocks about the vertical axes and in a zone of continuous deformation [Lamb 1987], where:

$$ R = \frac{w}{2} \left( \cos^2 \phi - \tan \phi \sin 2\phi \right) - 1 \quad (2) $$

The parameters of relation (2) include the strain rate $w = S v \cos \theta / a$; $\theta$ as the angle between the direction of the slip rate vector $S v$ and the deforming zone; $a$ as the width of the deforming zone; and $\phi$ as the angle between the small block trend and the deforming zone (Figure 4). The block rotation implies a combined simple-shear and pure-shear deformation if we consider pinned blocks, due to the local tectonic conditions (deformation strip along the plate boundary) [Jackson and Molnar 1990]. Although the constraints of rotation rates depend totally on the chosen convergence rate, the inferred clockwise rotation rates in the Rif and Tell Atlas presented in Table 2 (2.24°/Myr to 3.9°/Myr) are consistent with the data obtained from paleomagnetic analyses in the Caltanisetta basin (North African margin in Sicily) since the Pliocene (3°/Myr to 7°/Myr) [Scheepers and Langereis 1993], and in the Cheliff basin near the El Asnam fault (3°/Myr to 8°/Myr) [Aifa et al. 1992, Derder at al. 2011].

| Zone            | Convergence rate \((\text{mm/y})\) | $\phi$ \(^{(\circ)}\) | $\theta$ \(^{(\circ)}\) | $R$ \(^{(\circ)/\text{Myr}}\) |
|-----------------|----------------------------------|-----------------|-----------------|-----------------|
| Rif–Alboran     | 3.6                              | 35              | 40              | 2.24            |
| Cheliff west    | 4.5                              | 45              | 50              | 3.62            |
| Cheliff east    | 4.5                              | 45              | 55              | 3.58            |
| Kabylies        | 5                                | 35              | 60              | 3.27            |
| Tunisia–Sicily  | 5                                | 45              | 60              | 3.9             |

Table 2. The clockwise rotation rates, $R$, calculated for the small tectonic blocks, and averaged for main tectonic zones along the North Africa plate boundary. See Figure 1b and explanation in main text for the model of block rotation and transpression. Convergence rates and strikes $\theta$ are from NUVEL-1 [DeMets et al. 1994], $\phi$ is the angle between the tectonic blocks and the trend of the deforming zone.

The shaded relief shows a schematic representation of a small tectonic block and the related El Asnam fault. The calculated compression-to-transcurrence ratios are given in Table 3.

Figure 4. Upper panels: Kinematic model of a deformed zone with small-block rotation and lateral extension [Lamb 1987, Jackson and Molnar 1990]. Lower panels: pinned model where the slip vector $V = V_n + V_l$ and with no lateral extension within the deforming zone. The difference between the bookshelf and pinned models is illustrated by the different distances of CD in each case. The shortening angle $\beta$ represents the ratio between the pure shear and lateral shear within the deforming zone, $\alpha-1$ represents the shortening across the zone, and $\theta$ is the convergence strike (see text).
Transpression

In continuum mechanics, the transpression deformation can be factorized into simultaneous lateral displacements (simple shear) and horizontal shortening (pure shear). With \( \alpha^{-1} = (1-S) \) representing the shortening across the zone, and \( S \) as the amount of shortening, the shear strain,

\[
\gamma = \tan \phi = S / (1 - S) \cot \beta, \tag{3}
\]

can be expressed as a function of the contraction deformation [Sanderson and Marchini 1984]. The Quaternary shortening directions (Figure 2b), which can be expressed by the angle \( \beta \) with respect to the zone margin, range from 140˚N to 180˚N along the North Africa plate boundary, and might result from the partitioning of transpressional strain (Figure 4) [Teyssier et al. 1995, Jones and Tanner 1995, Meghraoui and Pondrelli 1998]. Hence, the compression-to-transcurrence ratio that can be estimated at each point along the plate boundary is calculated from:

\[
\frac{dS}{d\gamma} = \frac{1}{\alpha^2 \cot \beta} \tag{4}
\]

The shortening dimension \( \alpha^{-1} = 0.58 \) is estimated from the 50 km of shortening during the last 9 Myr along the Tell and Rif Atlas [Dewey et al. 1989]. Taking into account an average value of \( \beta \) for the five tectonic zones identified for the model of block rotation along the plate boundary, we obtain a compression-to-transcurrence ratio ranging between 33% at Gibraltar to 50% across northern Tunisia (see also Table 3).

4. Pattern of deformation of the plate boundary: discussion and conclusions

The plate boundary in North Africa is here examined in the light of the numerous detailed geological and seismological analyses. The quantitative estimation of the displacement field along the five zones of the Atlas Mountains indicates that as well as convergent movements, the right-lateral faulting mechanism observed on the Atlantic side also affects the crustal deformation in North Africa [Meghraoui and Pondrelli 1998, Pondrelli 1999, Gomez et al. 2000]. Although the shallow thrust mechanisms can be related to the crustal shortening by means of basal décollements, the convergent driving mechanism appears to be controlled at depth also by strike-slip and high-angle reverse faults. The model of transpression and block rotation that we propose is based on numerous and detailed observations along the plate boundary, where the pattern of deformation of active zones, such as the El Asnam region, is taken as a reference.

Field observations and analog experiments show that NE-SW-trending, active fault-related folds can be coeval with E-W, deep-seated, right-lateral, strike-slip faults, and refer to transpressional tectonics [Thomas 1976, Oldow et al. 1990, Odonne and Costa 2003]. The relationships between the two faulting types can also be interpreted using a simple kinematic model that integrates clockwise block rotations within a deforming zone similar to that applied in the active Transverse Ranges in California (Figure 4) [Jackson and Molnar 1990]. The remarkable correlation between field observations [Meghraoui et al. 1986, Meghraoui et al. 1996, Morel and Meghraoui 1996] and paleomagnetic data [Aifa et al. 1992, Scheepers and Langereis 1993] reinforces the idea that our model of clockwise small-block rotation is not speculative, but is supported by the tectonic and geomorphological data. The plate boundary in North Africa can be considered as a narrow E-W-trending zone, with dextral shearing and contractional deformation.

The deformation zone in Figure 2c (yellow strip) shows that the plate boundary does not have a linear shape, but instead a rather irregular strip with three main bends, in the Alboran Sea, the Cheliff Basin, and the Sicily–Tunisia domain (Figure 5). This deformation zone encompasses from the eastern end of the Gloria Transform to Sicily, and it is defined by the occurrence of large earthquakes with \( M_w \geq 6.0 \). The two latter bends, the Cheliff Basin and the Sicily–Tunisia domain, correspond to zones of maximum compression-to-transcurrence ratio (Table 3, 43% and 50%, respectively), which are in agreement with the eastward rotation from 120˚N to 170˚N of the convergence directions, and implies that the compression-to-transcurrence ratio increases progressively eastwards (Figures 2c and 5). Taking into account the \( P \) axes directions of significant earthquakes along the Gibraltar–Sicily plate boundary and the shortening directions from the tectonic data (Figure 2b), there is good correlation when only the Quaternary thrust structures and the focal mechanisms are involved. A more complex tectonic picture appears for the Alboran–Rif region, which might be due to a rapidly changing deformation zone and the superposition of successive tectonic phases. However, the occurrence of the 1959 (Ms 5.5) Yussuf earthquake and the 1994 and 2004 (Mw 6.0, Mw 6.4, respectively) Al Hoceima earthquakes, and the related Quaternary tectonic transpression tectonics in north africa

| Zone             | \( \beta \) (rad) | \( \frac{dS}{dt} / (d\gamma / dt) \) (%) |
|------------------|------------------|----------------------------------------|
| Rif–Alboran      | 1.57             | 33                                     |
| Cheliff west     | 0.99             | 43                                     |
| Cheliff east     | 1.27             | 37                                     |
| Kabylies         | 1.39             | 36                                     |
| Tunisia–Sicily   | 0.78             | 50                                     |

Table 3. Average strikes of the shortening component, \( \beta \), with regard to the deforming zone, and derived compression-to-transcurrence ratios, \( \frac{dS}{dt} / (d\gamma / dt) \), along the plate boundary in North Africa. Note that the maximum compression-to-transcurrence ratios are obtained for the two main bends along the plate boundary: Cheliff west and Tunisia–Sicily.
structures, provide a clearer view of the active deformation in the region. When compared with the pattern of active faulting and the distribution of shortening directions (Figure 2b and c), the clockwise rotation of GPS velocities is predominant at the boundary between the Betics in Spain and Rif in Morocco (Figure 2c). The discrepancy between the P axes of the earthquake focal mechanisms and the GPS directions allows us to consider the Rif and Tell Atlas belt as a deformation strip along the North Africa plate boundary. This difference in the convergence directions is the result of an obliquely convergent plate boundary.

The regional strain partitioning in North Africa is inferred from the interactions between folds and strike-slip faults in a deforming zone. Although the role of strike-slip faulting is difficult to integrate into a convergent model of the plate boundary, its geometry and relationships to the active thrust or reverse fault are here illustrated by the bookshelf and pinned-block model of Figure 4. The angular difference between the shortening directions and the convergence is significant here, where the plate boundary is oblique to the convergent motion; i.e., the discrepancy between shortening and convergence is more evident along the western section of the plate boundary (see Figure 2). In this case, the shortening component is refracted from the slip vectors along the E-W-trending plate boundary and it cannot be considered as coaxial with the convergence direction. Furthermore, the left-stepping geometry of the deforming zone in northwest Algeria and along the plate boundary can be interpreted as a restraining bend with significant transpressive deformation (Figure 5). This is supported by the occurrence of the largest earthquakes of the plate boundary in the Rif and Tell Atlas (M >6.0).

The velocities computed from the seismic deformation (Table 1) are clearly higher than the predicted velocities obtained from the global plate motion models (NUVEL-1A), an observation that is more pronounced on the strike-slip component than on the compressive values. Moreover, as the percentages of transpressive motion are always greater than the compressive components, this implies that the NUVEL-1 results used to compute the predicted velocities do not include at least part of the deformation along the boundary. This unexpected amount and style of Quaternary deformation can be attributed to strain that is produced within the boundary by the block rotation modeling proposed herein. The seismic deformation evaluated in this study takes place over a time span that is probably not representative of the seismic cycle for the area, but it is significant for the recent large and moderate-sized events that occurred in the region. The 3 mm/yr to 5 mm/yr geodetic convergence rate [Nocquet and Calais 2004] is, however, comparable with the estimated 1.5 mm/yr and 2.2 mm/yr [Meghraoui et al. 1996] across the active structures of the Rif and Tell Atlas, respectively. Furthermore, considering that the active deformation is distributed as far as the southern Sahara Atlas front, the estimated 2.2 mm/yr is a lower bound of the total shortening rate along the plate boundary.

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