Rotating black holes in 4d gauged supergravity

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Abstract: We present new results towards the construction of the most general black hole solutions in four-dimensional Fayet-Iliopoulos gauged supergravities. In these theories black holes can be asymptotically AdS and have arbitrary mass, angular momentum, electric and magnetic charges and NUT charge. Furthermore, a wide range of horizon topologies is allowed (compact and noncompact) and the complex scalar fields have a nontrivial radial and angular profile. We construct a large class of solutions in the simplest single scalar model with prepotential $F = -iX^0X^1$ and discuss their thermodynamics. Moreover, various approaches and calculational tools for facing this problem with more general prepotentials are presented.

Keywords: Black Holes in String Theory, AdS-CFT Correspondence, Superstring Vacua
# Introduction

The construction and physical understanding of 4d black hole solutions in supersymmetric theories with negative cosmological constant is relevant for a number of developments in high energy physics. One can try to analyze such solutions in their own right as string theory ground states and understand black hole thermodynamics [1–9] and microscopic degeneracy [10–13], guided by the AdS/CFT correspondence. In this sense
black holes are the best test ground for the fundamental principles of quantum gravity, and therefore the knowledge of all possible black hole solutions in a given theory can be regarded as a first step in the programme of solving this theory on a quantum level. Alternatively, these gravitational systems provide non-trivial asymptotically AdS backgrounds with holographic duals that exhibit a rich structure and a wide range of applications in field theory and condensed matter systems, see e.g. [14–19].

In the present paper we address the question of how to find generic AdS black hole solutions in theories with U(1) gauge fields and scalars that arise in the framework of gauged supergravity. Such solutions will be labeled by a set of conserved charges, corresponding to the global symmetries of the system - in four dimensions these are the mass, NUT charge, angular momentum, electric and magnetic charges of the U(1) gauge fields, and possible scalar hair. Unlike asymptotically flat black holes which only have spherical horizons, solutions in AdS can be further distinguished by their horizon topology [20]. In the compact case the horizons can be Riemann surfaces of arbitrary genus, while noncompact horizons correspond for example to black brane solutions.

There have been numerous partial results on the topic in the last decade. Due to the lack of electromagnetic duality in the electrically gauged theories that are usually considered, the various classes of solutions that were found look considerably different depending on the types of charges switched on. The known classes of electric solutions include both extremal and thermal, static and rotating solutions [21–24], where in the BPS limit the known solutions are necessarily rotating [25, 26], with constant scalars. The available magnetic black holes can instead be BPS only in the static limit [28] (with the exception of one hyperbolic rotating solution [29]) with nonconstant scalars, see also [30, 31]. Their non-BPS and thermal generalizations were also known only with vanishing angular momentum [34–37]. We show that all these seemingly disjoint classes in fact fall inside a single general solution, once we allow not only for rotation and electric and magnetic charges, but also for NUT charge. This extra freedom allows us to find a large parameter space of black hole solutions in one of the possible models (with prepotential $F = -iX^0X^1$) and gives strong hints on how to tackle the same problem with more complicated scalar manifolds.

We also discuss an alternative but complementary approach to constructing solutions which is based on dimensional reduction and the real formulation of special geometry, as developed in [38]. Within this formalism, the problem of constructing

\footnote{Note that restoring the duality only rotates electric and magnetic charges, without changing the types of black hole classes, thus the discussion remains true, upto redefinition of the meaning of electric and magnetic charges.}

\footnote{Dyonic AdS black holes were constructed recently in [27].}

\footnote{See [32, 33] for black hole solutions of this type in theories with nontrivial hypermultiplets.}
stationary solutions of 4D, $\mathcal{N} = 2$ Fayet-Iliopoulos gauged supergravity reduces to solving a particular three-dimensional Euclidean non-linear sigma model (with potential). Previously this approach has been used to construct static black hole solutions [34, 36], whereas in this paper we are interested in rotating solutions and the procedure is adapted accordingly. As an application, we present the new rotating black hole solutions of the $F = -iX^0X^1$ model within this formalism, thus providing a useful consistency check.

The plan of the paper is as follows. We briefly present the Lagrangian and equations of motion of the theory at the end of this section. Section 2 contains a general discussion of the universal structure of black holes based on the Carter-Plebański metric [39, 40], relating it to various examples existing in the literature. In the same section we comment on the difference between over- and under-rotating extremal solutions in AdS, and we explain how to choose different horizon topologies. In section 3 we study the theory with prepotential $F = -iX^0X^1$ and find a general class of nonextremal black holes with angular momentum and magnetic charges. We discuss the thermodynamics and physical properties of these solutions, showing a new type of limit leading to noncompact horizons with finite area. In section 4, these solutions are extended to allow for NUT- and electric charges, however the NUT charge will not be allowed to take arbitrary values. We also show how the solutions can be written in terms of harmonic functions and special geometry quantities and how in the limit of vanishing gauging a class of known solutions to ungauged supergravity [41] is recovered. We end the main discussion of the paper with some general comments and suggestions in section 5. Some of the useful tools and techniques we used to obtain our main results are relegated to the appendices. In app. A we consider supersymmetric rotating attractors, showing that all asymptotically flat under-rotating attractors are precisely half-BPS (in [43] they were shown to be at least quarter-BPS). In app. B we give more details about the real formulation of special geometry.

Note added: During the write-up of our work, ref. [44] appeared, where charged rotating solutions of the same model were presented.

1.1 Lagrangian and equations of motion

A detailed description of notations and conventions of abelian $\mathcal{N} = 2$ gauged supergravity can be found in [45]. In the context of black hole physics, such models are also discussed in [28, 30, 31, 46], and we refer the reader to those papers for a complete introduction.

The most general bosonic Lagrangian of $\mathcal{N} = 2$ abelian Fayet-Iliopoulos (FI)
gauged supergravity is given by

\[ e^{-1} \mathcal{L} = \frac{1}{2} R - g_{ij} \partial^i z^j \partial^j \bar{z}^i + I_{\Lambda \Sigma}(z, \bar{z}) F_{\mu \nu}^\Lambda F^{\mu \nu | \Sigma} + \frac{1}{2} R_{\Lambda \Sigma}(z, \bar{z}) e^{\mu \nu \rho \sigma} F_{\mu \nu}^\Lambda F_{\rho \sigma}^\Sigma - g^2 V(z, \bar{z}) , \]

with \( \Lambda, \Sigma = 0, 1, ..., n_V \) and \( i, j = 1, ..., n_V \), where \( n_V \) is the number of vector multiplets. The imaginary and the real part of the period matrix \( N_{\Lambda \Sigma} (I_{\Lambda \Sigma} \text{ and } R_{\Lambda \Sigma}) \), as well as the metric on the scalar moduli space \( g_{ij} \) and the scalar potential \( V \), depend on the particular vector multiplet model. The complex scalars \( z^i \) are written in terms of the holomorphic symplectic sections \( (X^\Lambda, F_{\mu \nu}^\Lambda) \). All these quantities can be specified uniquely just with a single holomorphic function, \( F(X) \), the prepotential. Therefore specifying the prepotential is equivalent to defining the full Lagrangian.

The Einstein equations following from (1.1) read

\[ -(R_{\mu \nu} - \frac{1}{2} g_{\mu \nu} R) = g_{\mu \nu} g^2 V(z, \bar{z}) + g_{\mu \nu} \partial^\sigma z^i \partial^i \bar{z}^j - 2 g_{ij} \partial^\mu (z^i \partial^\nu \bar{z}^j) + \\
- I_{\Lambda \Sigma} g_{\mu \nu} F_{\rho \sigma}^\Lambda F^{\rho \sigma | \Sigma} + 4 I_{\Lambda \Sigma} F_{\mu \nu}^\Lambda F^{\mu \nu | \Sigma} , \]

while the equations of motion for the scalar fields \( z^i \) are given by

\[ g_{ij} \partial^\mu (e \partial^\nu \bar{z}^j) + e \frac{\partial g_{ik}}{\partial z^j} \partial^\mu \bar{z}^i \partial^k z^j + e \frac{\partial I_{\Lambda \Sigma}}{\partial \bar{z}^i} F_{\rho \sigma}^\Lambda F^{\rho \sigma | \Sigma} + \frac{e}{2} \frac{\partial R_{\Lambda \Sigma}}{\partial \bar{z}^i} e^{\mu \nu \rho \sigma} F_{\mu \nu}^\Lambda F_{\rho \sigma}^\Sigma - e g^2 \frac{\partial V}{\partial \bar{z}^i} = 0 , \]

and the Maxwell equations for the vector fields \( A_{\mu}^\Lambda \) are

\[ \partial_\mu (e F^{\mu \nu | \Sigma} I_{\Sigma \Lambda} + e \frac{e^{\mu \nu \rho \sigma}}{2} F^{\rho \sigma | \Sigma} R_{\Lambda \Sigma}) = 0 . \]

The requirement of an asymptotic AdS_4 geometry fixes the values of the scalar fields at infinity. Indeed, AdS_4 corresponds to an extremum of the scalar potential, yielding the asymptotic attractor condition

\[ \frac{\partial V}{\partial \bar{z}^i} \bigg|_\infty = 0 , \quad \Leftrightarrow \quad \xi_\Lambda D_i X^\Lambda \bigg|_\infty = 0 , \]

where \( D_i X^\Lambda \) is the Kähler covariant derivative of the coordinates \( X^\Lambda \) with respect to \( z^i \). The constants \( \xi_\Lambda \) determine which linear combination \( \xi_\Lambda A^\Lambda \) is used to gauge a U(1) subgroup of the SU(2) R-symmetry. In what follows, we shall use \( g_\Lambda \equiv g \xi_\Lambda \), with \( g \) the gauge coupling constant appearing in (1.1).

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\(^4\)We use the convention \( F_{\mu \nu} = \frac{1}{2} (\partial_{\mu} A_\nu - \partial_{\nu} A_\mu) \) for the field strengths. Our signature is mostly plus, and \( \epsilon_{0123} = -\epsilon^{0123} = 1 \).
2 Universal structure of rotating black holes

This section is devoted to showing that all known rotating black holes in matter-coupled \( \mathcal{N} = 2 \) gauged supergravity in four dimensions have a universal metric structure. It turns out that in all cases the metric can be cast in the form

\[
    ds^2 = -f(dt + \omega_y dy)^2 + f^{-1} \left[ v \left( \frac{dq^2}{Q} + \frac{dp^2}{P} \right) + PQ dy^2 \right],
\]

where \( Q(q) \) and \( P(p) \) are polynomials of fourth degree respectively in the variables \( q \) (radial variable) and \( p \) (function of the angular variable \( \theta \)). The warp factors \( f, v, \omega_y \) are more general functions of \( q \) and \( p \). We start now with the examples and finish the section by commenting on some novel general features of this metric, such as the difference between over- and under-rotating solutions and the relation between the function \( P(p) \) and the choice of horizon topology.

2.1 Carter-Plebański solution

The metric and U(1) field strength of the Carter-Plebański solution \([39, 40]\) of minimal gauged supergravity are respectively given by

\[
    ds^2 = -\frac{Q(q)}{p^2 + q^2} (d\tau - p^2 d\sigma)^2 + \frac{p^2 + q^2}{Q(q)} dq^2 + \frac{p^2 + q^2}{P(p)} dp^2 + \frac{P(p)}{p^2 + q^2} (d\tau + q^2 d\sigma)^2, \quad (2.2)
\]

\[
    F = \frac{Q(p^2 - q^2) + 2 Ppq}{(p^2 + q^2)^2} dq \wedge (d\tau - p^2 d\sigma) + \frac{P(p^2 - q^2) - 2 Qpq}{(p^2 + q^2)^2} dp \wedge (d\tau + q^2 d\sigma), \quad (2.3)
\]

where the quartic structure functions read

\[
    P(p) = \alpha - P^2 + 2np - \varepsilon p^2 + (-\Lambda/3)p^4, \\
    Q(q) = \alpha + Q^2 - 2mq + \varepsilon q^2 + (-\Lambda/3)q^4. \quad (2.4)
\]

Here, \( Q, P \) and \( n \) denote the electric, magnetic and NUT-charge respectively, \( m \) is the mass parameter, while \( \alpha \) and \( \varepsilon \) are additional non-dynamical constants.

By making the coordinate transformation

\[
    \tau = At + By, \quad \sigma = Ct + Dy, \quad AD - BC = 1, \quad (2.5)
\]

(2.2) can be cast into the form (2.1), where

\[
    v = Q(A - p^2 C)^2 - P(A + q^2 C)^2, \quad f = \frac{v}{p^2 + q^2}, \quad (2.6)
\]

and

\[
    \omega_y = \frac{1}{v} \left[ Q(A - p^2 C)(B - p^2 D) - P(A + q^2 C)(B + q^2 D) \right]. \quad (2.7)
\]
We see that there is actually more than one way to write (2.2) as a fibration (2.1) over a three-dimensional base space. A simple choice would be for instance $A = D = 1$, $B = C = 0$, such that

$$v = Q - P, \quad \omega_y = \frac{Qp^2 + Pq^2}{P - Q}.$$ 

### 2.2 Rotating magnetic BPS black holes, prepotential $F = -iX^0 X^1$

Our second example is the family of BPS magnetic rotating black holes in the model with prepotential $F = -iX^0 X^1$, constructed in [29].

This model has just one complex scalar $\tau$. The symplectic sections in special coordinates are $v^T = (1, \tau, -i\tau, -i)$. The Kähler potential, metric, and vector kinetic matrix are respectively of this form:

$$e^{-K} = 2(\tau + \bar{\tau}) , \quad g_{\tau\bar{\tau}} = \partial_\tau \partial_{\bar{\tau}} K = (\tau + \bar{\tau})^{-2} ,$$

$$\mathcal{N} = \begin{pmatrix} -i\tau & 0 \\ 0 & -\frac{i}{\tau} \end{pmatrix} ,$$

thus requiring $\text{Re}\tau > 0$. For our choice of electric gauging, the scalar potential is

$$V = -\frac{4}{\tau + \bar{\tau}} (g_0^2 + 2g_0g_1\tau + 2g_0g_1\bar{\tau} + g_1^2\tau\bar{\tau}) ,$$

which has an extremum at $\tau = \bar{\tau} = |g_0/g_1|$.

The metric of the BPS solution of [29] reads

$$ds^2 = \frac{p^2 + q^2 - \Delta^2}{P} dp^2 + \frac{P}{p^2 + q^2 - \Delta^2} (dt + (q^2 - \Delta^2) dy)^2$$

$$+ \frac{p^2 + q^2 - \Delta^2}{Q} dq^2 - \frac{Q}{p^2 + q^2 - \Delta^2} (dt - p^2 dy)^2 ,$$

with the structure functions

$$P = (1 + A) \frac{E^2 l^2}{4} - Ep^2 + \frac{p^4}{l^2} , \quad Q = \frac{1}{l^2} \left( q^2 + \frac{E^2 l^2}{2} - \Delta^2 \right)^2 .$$

The upper parts of the (nonholomorphic) symplectic section $(L^A, M_A)$ and the U(1) gauge potentials are given by

$$L^0 = \frac{1}{2} \left( \frac{g_1}{g_0} \right)^{\frac{3}{2}} \left( \frac{p^2 + (q - \Delta)^2}{p^2 + q^2 - \Delta^2} \right)^{\frac{1}{2}} , \quad L^1 = \frac{1}{2} \left( \frac{g_0}{g_1} \right)^{\frac{3}{2}} \left( \frac{p^2 + q^2 - \Delta^2 + 2ip\Delta}{[(p^2 + q^2 - \Delta^2)(p^2 + (q - \Delta)^2)]^{\frac{1}{2}}} ,$$
\[ A^\Lambda = - \frac{Ep\sqrt{-A}}{4g_A(p^2 + q^2 - \Delta^2)}(dt + (q^2 - \Delta^2)dy), \quad \Lambda = 0, 1. \]

The solution is thus specified by three free parameters \( A, E, \Delta \). (The asymptotic AdS curvature radius \( l \) is related to the gauge coupling constants by \( l^{-2} = 4g_0g_1 \).) The new rotating solution that we are going to describe in section 3 is a nonextremal deformation of this solution. For \( \Delta = 0 \), the moduli are constant, and the solution reduces to a subclass of (2.2), (2.3).

The metric (2.11) can again be written in the form (2.1), where now

\[ v = Q - P, \quad f = \frac{v}{p^2 + q^2 - \Delta^2}, \quad \omega_y = \frac{P(q^2 - \Delta^2) + Qp^2}{P - Q}. \]

### 2.3 Rotating black holes of Chong, Cvetič, Lu, Pope and Chow

Finally, there are three other examples of rotating black hole solutions, described in [22–24]. They all fit in the form of the metric (2.1). We report the details of the rotating black holes with two pair-wise equal charges in SO(4)-gauged \( \mathcal{N} = 4 \) supergravity constructed in [22], since they are the most relevant for the new configurations described in section 3. The metric, dilaton, axion and gauge fields read respectively

\[
\begin{align*}
\Delta_r &= r^2 + a^2 - 2mr + g^2r_1r_2(r_1r_2 + a^2), \\
\Delta_\theta &= 1 - a^2g^2\cos^2\theta, \\
W &= r_1r_2 + a^2\cos^2\theta, \\
r_I &= r + 2ms_i^2, \\
s_I &= \sinh\delta_I, \\
c_I &= \cosh\delta_I.
\end{align*}
\]

Notice that the other scalar fields \( \varphi_2, \varphi_3, \chi_2, \chi_3 \) are set to zero in the truncation of [22]. Also, the two electromagnetic charges of the solution are carried by fields in U(1) subgroups of the two SU(2) factors in SO(4) \( \sim \) SU(2) \( \times \) SU(2). In the case \( \delta_1 = \delta_2 \), the dilaton \( \varphi_1 \) and the axion \( \chi_1 \) vanish. Then, the solution boils down to
the Kerr-Newman-AdS geometry with purely electric charge if $A^1$ is dualized, or to purely magnetic KNAdS if we dualize $A^2$. Note also that, after dualizing $A^1$, the model considered in [22] (their Lagrangian (52)) can be embedded into $\mathcal{N}=2$ gauged supergravity as well, by choosing the prepotential $F = -iX^0X^1$ [47].

After the rescaling $\phi \to ay$ and the redefinition $q = r$, $p = a \cos \theta$, the metric in (2.15) can again be cast into the form (2.1), with (quartic) structure functions\(^5\)

$$P = (1 - g^2p^2)(a^2 - p^2), \quad Q = \Delta_r,$$

and

$$v = Q - P, \quad f = \frac{v}{W}, \quad \omega_y = \frac{Q(p^2 - a^2) + P(r_1r_2 + a^2)}{v}. \quad (2.17)$$

As mentioned before, the solutions of [23, 24] can be recast in the form (2.1) too. The reader can find the complete form of the solution in the original papers, here we skip the details, since the procedure is straightforward and along the same lines as for the previous ones.

We first rescale $t \to \Xi t$, $\phi \to ay$, and redefine $q = r$, $p = a \cos \theta$. Then, for the single-charged black hole solution of [23] the structure functions are:

$$P = (1 - g^2p^2)(a^2 - p^2), \quad Q = \Delta_r,$$

$$v = (1 - g^2p^2)Q - V_r^2(a^2 - p^2)(1 - g^2p^2), \quad (2.20)$$

$$f = \frac{v}{(H)^\frac{1}{2}(p^2 + q^2)}, \quad \omega_y = \frac{2mqcP\sqrt{1 + a^2g^2s^2}}{v\Xi}, \quad (2.21)$$

while for the the two-charge rotating black holes of [24] the functions $P$, $Q$ and $v$ have the same form as (2.20) (2.21), whereas

$$f = \frac{v}{(H_1H_2)^\frac{1}{2}(p^2 + q^2)}, \quad \omega_y = \frac{2mrc_1c_2\tilde{c}_1\tilde{c}_2P}{v\Xi}. \quad (2.22)$$

The simplicity of the geometry (2.1), and the fact that it is particularly suited for a formalism based on timelike dimensional reduction like the one used in [38], should

\(^{5}\)It should be emphasized that, like in the case of the Carter-Plebański solution, also here and in the previous example there is an $\text{SL}(2, \mathbb{R})$ gauge freedom that consists in sending $t \to \alpha t + \beta y$, $y \to \gamma t + \delta y$, $\alpha\delta - \beta\gamma = \pm 1$, which preserves the form (2.1) of the metric while transforming the functions $f$, $v$ and $\omega_y$. This freedom can prove useful for the explicit construction of new solutions.
help constructing new nonextremal rotating black holes in matter-coupled gauged supergravity with an arbitrary number of vector multiplets and general prepotentials. Unfortunately even if the universal structure should remain the same, the equations of motion of gauged supergravity depend crucially on the given model and cannot be solved in complete generality, therefore we first restrict ourselves to considering the simplest interesting prepotentials with a single vector multiplet.

2.4 Over- vs. under-rotating solutions

An interesting possibility arises in the extremal limit of rotating black holes (see e.g. [48, 49]). One can sometimes find several extremal limits that correspond to either of two physically different solutions, called over-rotating and under-rotating solutions. The over-rotating solutions (a typical example here is the extremal Kerr black hole) have an ergoregion, while the under-rotating (that resemble more the extremal Reissner-Nordström spacetime) do not have ergoregions. Due to the AdS asymptotics, allowing for a wide range of coordinate choices, it might not be easy to see immediately whether one can have both types of extremal limits. The key to determining this is the following - one first needs to write the black hole metric in asymptotically AdS coordinates, from which the asymptotic time direction can be extracted. Once we know the correct Killing vector $k = \partial_t$, we can follow its behavior on the horizon. For an under-rotating solution, $k$ is null, $|k|^2 = 0$, while an overrotating solution has $|k|^2 > 0$, indicating the existence of an ergosphere.

To make the discussion more explicit, let us take the example of our metric (2.1),

$$ds^2 = -f(dt + \omega_y dy)^2 + f^{-1} \left[ v \left( \frac{dq^2}{Q} + \frac{dp^2}{P} \right) + PQ dy^2 \right],$$

and assume for the sake of argument that this metric was already written in asymptotically AdS coordinates$^6$ (this means that in the limit $q \to \infty$, one has $\omega_y = 0, f \sim q^2, v \sim q^4, Q \sim q^4$). In the extremal limit, with horizon at $q_h$, $Q(q_h) = Q'(q_h) = 0$, the norm of the timelike Killing vector is $-f$ and $f(q_h)$ will be either vanishing or negative. Typically both these possibilities will exist for some choice of parameters that determine the solution. This leads to three distinct physical possibilities for the complete geometry:

- $f(q_h) < 0$, only possible if $\omega_y(q_h) \neq 0$: this corresponds to the over-rotating solution; typically there is a lower bound for the angular momentum, $|J| > J_{\text{min}}$ (sometimes $J_{\text{min}} = 0$).

$^6$Note that this in general will not be true for the explicit solutions we find and one needs to first perform a coordinate change from the Plebański form of the metric to the asymptotically AdS form.
• $f(q_h) = 0$ and $\omega_y(q_h) = 0$: static attractor, leading to a static black hole, typically resulting from the limit $J = 0$.

• $f(q_h) = 0$, $\omega_y(q_h) \neq 0$: under-rotating solution; typically there is an upper bound for the angular momentum, $0 < |J| < J_{\text{max}}$.

The first two cases exist as extremal limits for all known rotating solutions with electromagnetic charges, while the third case is quite special and exists only in the presence of nontrivial scalar fields. Under-rotating solutions are known to exist in ungauged supergravity with cubic prepotentials, [48, 49], but not for quadratic ones of the type $F = -iX^0X^1$. We were not able to find explicit examples of under-rotating solutions in AdS among the general solutions of the $F = -iX^0X^1$ discussed in the present paper, but their existence in other models is an interesting possibility.

Note that it is important to identify the asymptotic time to be able to properly distinguish between the two rotating cases, thus only an analysis of the near-horizon geometry is in principle not enough, even if it gives good hints of the nature of the solution. In particular, observe that the near-horizon geometries of the asymptotically flat under- and over-rotating solutions are exactly the same (cf. (5.38) and (5.60) of [48]), but the former are defined in the parameter space $J^2 < P^2Q^2$, while the latter only for $J^2 > P^2Q^2$, where $P$ and $Q$ denote the magnetic and electric charge respectively.

2.5 Relation between $P(p)$ and horizon topology

The horizon topology of the black hole with metric (2.1) can be studied through the analysis of the function $P(p)$. It is a quartic polynomial in $p$ and here we choose to write it in the form

$$P(p) = (p - p_a)(p - p_b)(p - p_c)(p - p_d),$$

(2.25)

where the roots $p_{a,b,c,d}$ depend on the explicit values of the physical parameters of the metric (mass, NUT charge, electric and magnetic charges).

If we first look at the simple case without NUT charge, we have pairs of roots such that $p_c = -p_b$, $p_d = -p_b$. In order for the induced metric on the horizon $q = q_h$ (where $Q(q_h) = 0$) to have the right signature, we need $P \geq 0$. Let us first assume that the polynomial $P$ has four real roots with $0 < p_a < p_b$. Then $P$ is non-negative for $|p| \leq p_a$ or $|p| \geq p_b$. Choosing $-p_a \leq p \leq p_a$ leads to a function $P(p)$ that is bounded and vanishes at two points, which are coordinate singularities. Such a function can be defined for horizons with spherical topology, where the two singularities correspond to the north and the south pole of the (possibly squashed) sphere. Choosing the other possibility, $p_b \leq p$, leads to hyperbolic topology since the function $P$ is not bounded.
anymore. The coordinate singularity at $p = p_b$ is at the origin of the hyperbolic space in the standard hyperbolic coordinates. One can see that in this case we have two disjoint types of black holes within the same solutions, depending on whether we choose the compact or non-compact range. The third main type of topology arises in the case when $p_a$ and $p_b$ are both complex, thus $P$ is everywhere positive and non-vanishing for real $p$ - this corresponds to the flat topology of black branes, where no coordinate singularities are encountered.

To summarize the three basic types of topology and their relation with $P(p)$, the possibilities are

- spherical topology: $P(p)$ bounded and vanishing at two points, north and south pole.
- hyperbolic topology: $P(p)$ unbounded and vanishing at a single point.
- flat topology: $P(p)$ unbounded and never vanishing.

On top of those topologies and their quotients, we can have some new exotic situations in some special cases. In section 3.3 we will show the situation where the two positive roots of $P$ coincide, $p_a = p_b$. It turns out choosing $-p_a \leq p \leq p_a$ in this case leads to a sphere with two punctures on the place of the two poles, i.e. the horizon has a cylindrical topology but finite area. Thus we are lead to think that whenever the function $P(p)$ has a double root the horizon is punctured at that point, which is no longer just a coordinate singularity.

The situation with NUT charge is even more complex, since then all four roots can be a priori unrelated to each other. One can therefore have situations with $p_d < p_c < p_b = p_a$ for example, where the choice of bounded region for $P(p)$ will lead to one pole and one puncture and therefore to a bottle-shaped horizon topology. Even more exotic possibilities would be three coinciding roots, a case which is yet to be analyzed carefully. In any case, the three main types of horizon topologies continue to exist whether one allows for NUT charge or not.

## 3 Thermal rotating solutions with magnetic charges

We shall now construct a nonextremal deformation of the BPS solution to the model with prepotential $F = -iX^0X^1$, constructed in [29], and described in the previous section. Inspired by the form (58) of [22], we can make the ansatz

$$ds^2 = -\frac{Q}{W} [dt - p^2dy]^2 + \frac{P}{W} [dt + q_1q_2dy]^2 + W \left( \frac{dq^2}{Q} + \frac{dp^2}{P} \right),$$

for the 3-dimensional metric.
with
\[ Q = a_0 + a_1q + a_2q^2 + a_4q^4, \quad P = b_0 + b_1p + b_2p^2 + b_4p^4, \quad (3.2) \]
and
\[ W = q_1q_2 + p^2, \quad q_i = q - \Delta_i, \quad (3.3) \]
where \(a_i, b_i, \) and \(\Delta_i\) are constants. \(3.1\) fits into the general form of the metric \(2.1\) with
\[ v = Q - P, \quad f = \frac{v}{W}, \quad \omega_y = -\frac{1}{v} [Pq_1q_2 + Qp^2]. \quad (3.4) \]
It boils down to the BPS solution \(2.11\) when \(Q, P\) reduce to the functions \(2.12\), and \(\Delta_1 = -\Delta_2 \equiv \Delta\). The ansatz for the gauge potentials and the scalars is
\[
A^\Lambda = \frac{P^\Lambda(dt + q_1q_2dy)}{W}p, \quad \tau = e^{-\varphi} + i\chi = \frac{X^1}{X^0} = \frac{\mu W + i\nu p}{q_i^2 + p^2}, \quad (3.5)
\]
where the constants \(P^\Lambda\) are proportional to the magnetic charges, and \(\mu, \nu\) are real constants.

In order to reduce the number of free parameters, we will first restrict to the case \(\Delta_1 = -\Delta_2 \equiv \Delta\), and take \(\mu, \nu\) in the scalar to be the same as in the BPS case. We have then checked that the equations of motion are satisfied if
\[
a_0 = b_0 - a_2\Delta^2 - \frac{\Delta^4}{l^2} + 2l^2 \left( g_0^2P_0^2 + g_1^2P_1^2 \right), \quad a_1 = \frac{2l^2(g_0^2P_0^2 - g_1^2P_1^2)}{\Delta}, \quad (3.6)
\]
\[
b_1 = 0, \quad b_2 = -a_2 - 2\frac{\Delta^2}{l^2}, \quad b_4 = a_4 = 1/l^2 \equiv 4g_0g_1, \quad (3.7)
\]
\[
\mu = \frac{g_0}{g_1}, \quad \nu = 2\frac{\Delta g_0}{g_1}, \quad (3.8)
\]
where we assumed that \(g_0, g_1\) are positive. We can check that the scalar field \(\tau\) has the correct behaviour at infinity, since in this model the AdS\(_4\) asymptotic geometry is obtained for \(\tau_\infty = g_0/g_1\). If we fix the Fayet-Iliopuulos constants \(g_0\) and \(g_1\), the solution depends on the five parameters \(b_0, a_2, \Delta, P^0, P^1\), thus two more parameters with respect to the BPS solution. From the second equation of \(3.6\) we see that, in the case \(g_0P^0 = g_1P^1\), one has either \(a_1 = 0\) or \(\Delta = 0\). If \(a_1\) vanishes, one can thus have equal charges and yet a nontrivial scalar profile (i.e., \(\Delta \neq 0\)). This behaviour is qualitatively different from that of the solutions constructed for instance in [22].

Notice that the form of the scalar field and of the vector field strengths is the same as in the BPS case. The latter is recovered for
\[
a_2 = E - 2\frac{\Delta^2}{l^2}, \quad b_0 = (1 + A)\frac{E^2l^2}{4}, \quad P^\Lambda = \frac{\sqrt{-\Lambda E}}{4gL}. \quad (3.9)
\]
A further generalization to a black hole with electric and NUT-charges (that would include also the solutions of [29] and [22]) is straightforward, however, we postpone this discussion to the next section and first elaborate on the physical properties and novelties of the magnetic solutions. In this case, in fact, the absence of closed timelike curves makes them interesting thermodynamical and gravitational systems.

### 3.1 Physical discussion

Following section 2.5, we assume $P$ has four distinct roots, $\pm p_a$, $\pm p_b$, where $0 < p_a < p_b$. Then $P$ is non-negative for $|p| \leq p_a$ or $|p| \geq p_b$. Since we are interested in black holes with compact horizon\(^7\), we consider the range $|p| \leq p_a$, and set $p = p_a \cos \theta$, where $0 \leq \theta \leq \pi$. By using the scaling symmetry

\begin{align*}
  p &\to \lambda p, \quad q \to \lambda q, \quad t \to t/\lambda, \quad y \to y/\lambda^3, \quad \Delta \to \lambda \Delta, \\
  a_0 &\to \lambda^4 a_0, \quad a_1 \to \lambda^3 a_1, \quad a_2 \to \lambda^2 a_2, \quad b_0 \to \lambda^4 b_0, \quad b_2 \to \lambda^2 b_2,
\end{align*}

one can set $p_b = l$ without loss of generality. If we define the rotation parameter $j$ by $p_a^2 = j^2$, this amounts to the choice

\begin{align*}
  b_0 &= j^2, \quad b_2 = -1 - \frac{j^2}{l^2}, \quad (3.11)
\end{align*}

which implies

\begin{align*}
  a_0 &= (j^2 - \Delta^2) \left(1 - \frac{\Delta^2}{l^2}\right) + 2l^2 \left( g_0^2 p_0^2 + g_1^2 p_1^2 \right), \quad a_2 = 1 - \frac{\Delta^2}{l^2} + \frac{j^2 - \Delta^2}{l^2}. \quad (3.12)
\end{align*}

Taking also

\begin{align*}
  t \to t + \frac{j\phi}{\Xi}, \quad y \to \frac{\phi}{j\Xi}, \quad \Xi \equiv 1 - \frac{j^2}{l^2}, \quad (3.13)
\end{align*}

the metric (3.1) becomes

\begin{align*}
  ds^2 &= -\frac{Q}{(q^2 - \Delta^2 + j^2 \cos^2 \theta)} \left[ dt + \frac{j \sin^2 \theta d\phi}{\Xi} \right]^2 + (q^2 - \Delta^2 + j^2 \cos^2 \theta) \left( \frac{dq^2}{Q} + \frac{d\theta^2}{\Delta_\theta} \right) \\
  &\quad + \frac{\Delta \sin^2 \theta}{(q^2 - \Delta^2 + j^2 \cos^2 \theta)} \left[ j dt + \frac{q^2 + j^2 - \Delta^2}{\Xi} d\phi \right]^2, \quad (3.14)
\end{align*}

\(^7\)As already discussed, noncompact hyperbolic horizons can be obtained by restricting to the region $p \geq p_b$ and setting $p = p_b \cosh \theta$, where $0 \leq \theta < \infty$. In this case, the rotation parameter is defined by $p_b^2 = j^2$. The resulting black holes represent generalizations of the solutions of minimal gauged supergravity constructed in [50].
where we defined
\[ \Delta_\theta = 1 - \frac{j^2}{l^2} \cos^2 \theta. \]
From (3.6) it is clear that for \( g_0 P^0 = g_1 P^1 \) and \( \Delta = 0 \), the mass parameter \( a_1 \) can be arbitrary; this leads to the Kerr-Newman-AdS solution with magnetic charge and constant scalar. On the other hand, for zero rotation parameter, \( j = 0 \), (3.14) boils down to the static nonextremal black holes with running scalar constructed in [34].

The Bekenstein-Hawking entropy of the black holes described by (3.14) is given by
\[ S = \frac{\pi}{\Xi G} (q_h^2 + j^2 - \Delta^2), \] (3.15)
where \( G \) denotes Newton’s constant and \( q_h \) is the location of the horizon, i.e., \( Q(q_h) = 0 \).

In order to compute the temperature and angular velocity, we write the metric in the canonical (ADM) form
\[ ds^2 = -N^2 dt^2 + \sigma(d\phi - \omega dt)^2 + (q^2 - \Delta^2 + j^2 \cos^2 \theta) \left( \frac{dq^2}{Q} + \frac{d\theta^2}{\Delta_\theta} \right), \] (3.16)
with
\[ \sigma = \frac{\Sigma^2 \sin^2 \theta}{(q^2 - \Delta^2 + j^2 \cos^2 \theta) \Xi^2}, \quad \omega = \frac{j \Xi}{\Sigma^2} (Q - \Delta_\theta(q^2 + j^2 - \Delta^2)), \] (3.17)
and the lapse function
\[ N^2 = \frac{Q \Delta_\theta(q^2 - \Delta^2 + j^2 \cos^2 \theta)}{\Sigma^2}, \] (3.18)
where
\[ \Sigma^2 \equiv \Delta_\theta(q^2 + j^2 - \Delta^2)^2 - Qj^2 \sin^2 \theta. \]

The angular velocity of the horizon is thus
\[ \omega_h = \omega|_{q=q_h} = -\frac{j \Xi}{q_h^2 + j^2 - \Delta^2}, \] (3.19)
whereas at infinity one has
\[ \omega_\infty = \frac{j}{l^2}. \] (3.20)

The angular momentum computed by means of the Komar integral reads
\[ J = \frac{1}{16\pi G} \oint_{S^2_H} dS^{\mu\nu} \nabla_\mu m_\nu, \] (3.21)
with \( m = \partial_\phi \) and the oriented measure
\[ dS^{\mu\nu} = (v^\mu u^\nu - v^\nu u^\mu) \sqrt{\sigma} d\theta d\phi. \]
Here, $u = N^{-1}(\partial_t + \omega \partial_\phi)$ is the normal vector of a constant $t$ hypersurface, $v = (Q/(q^2 - \Delta^2 + j^2 \cos^2 \theta))^{1/2} \partial_q$, and

$$\sqrt{\hat{\sigma}} = \frac{\Sigma \sin \theta}{\Xi \Delta_{\theta}^{1/2}},$$

where $\hat{\sigma}$ denotes the induced metric on a two-sphere of constant $q$ and $t$. Evaluation of (3.21) yields

$$J = \frac{a_1 j}{2 \Xi^2 G}. \quad (3.22)$$

The Komar mass

$$M = -\frac{1}{8\pi G} \int_{S_\infty^2} dS^{\mu\nu} \nabla_\mu k_\nu$$

has to be computed with respect to the Killing vector $k = \Xi^{-1} \partial_t$ [8], leading to

$$M = -\frac{1}{8\pi G} \lim_{q \to \infty} \int d\theta d\phi \frac{\sin \theta}{(j^2 - l^2)^2} \left[ -2l^2 q^3 - 2(j^2 - \Delta^2) l^2 q + l^4 a_1 + O(q^{-1}) \right],$$

which is of course divergent. If we subtract the background with $a_1 = 0$ and the same $j$ and $\Delta$, we get the finite result

$$M = -\frac{a_1}{2 \Xi^2 G}. \quad (3.24)$$

Notice that the ‘ground state’ with $a_1 = 0$ is a naked singularity (contrary to the case of hyperbolic horizons addressed in footnote 7): The curvature singularity $W = 0$ is shielded by a horizon if $q_h^2 - \Delta^2 + j^2 \cos^2 \theta > 0$, which is equivalent to

$$\frac{2}{l^2} q_h^2 + a_2 > 1 + \frac{j^2}{l^2}.$$

Now, using $Q(q_h) = 0$, this can be rewritten as

$$\sqrt{a_2^2 - \frac{4a_0}{l^2}} > 1 + \frac{j^2}{l^2},$$

which can be easily shown to lead to a contradiction by using (3.12).

An alternative mass definition, that does not require any background subtraction, is based on the Ashtekar-Magnon-Das (AMD) formalism [51, 52]. (Cf. also [23] for an application to rotating AdS black holes and for more details). First of all we compute

\footnote{Note also that for $W < 0$, the real part of the scalar field becomes negative, so that ghost modes appear.}
the Weyl tensor of a conformally rescaled metric (in this case the conformal rescaling factor is $\Omega = l/q$), to leading order in $q$. This reads

$$C^t_{qtq} = - \frac{-g_0^2P_0^2 + g_1^2P_1^2}{8\Delta g_0^2g_1^2q^4} + O(1/q^6). \quad (3.25)$$

Once we have this quantity, we can compute the mass associated to the Killing vector $K = \Xi^{-1}\partial_t$, given by

$$M = \frac{1}{8\pi G(4g_0g_1)^{3/2}} \int \sqrt{\Sigma} \Omega^{-1} n^c n^d C_{cda} K^b = - \frac{(g_0^2P_0^2 - g_1^2P_1^2)}{4\Delta g_0g_1 G \Xi^2} = - \frac{a_1}{2G \Xi^2}, \quad (3.26)$$

so that the AMD procedure gives the same result as the regularized Komar integral.

The magnetic charges $\pi^\Lambda$ are given by

$$\pi^\Lambda = \frac{1}{4\pi} \oint_{S^2_\infty} F^\Lambda = - \frac{P^\Lambda}{\Xi}. \quad (3.27)$$

Now that we have computed the physical quantities of our solution, a comment on the number of free parameters is in order. We already mentioned that the metric (3.1) and the gauge potentials and scalar (3.5) depend on five parameters. However, due to the scaling symmetry (3.10), one of them is actually redundant and can be scaled away. There remain thus four free parameters, for instance $P^\Lambda, \Delta, j$, or alternatively $\pi^\Lambda, M, J$. Our black holes are therefore labelled by two independent magnetic charges, mass and angular momentum. Note also that the parameter $\Delta$ related to the running of the scalar is not independent of the mass; for this reason our solution does not carry primary hair.

The product of the horizon areas, given formula (3.15), is

$$\prod_{\alpha=1}^4 A_\alpha = \frac{(4\pi)^4}{\Xi^4} \prod_{\alpha=1}^4 (q_\alpha^2 + j^2 - \Delta^2) = \frac{(4\pi)^4}{\Xi^4} \prod_{\alpha=1}^4 (q_\alpha - q_+)(q_\alpha - q_-), \quad (3.28)$$

with $q_\pm = \pm \sqrt{\Delta^2 - j^2}$. At this point the formulas resemble the ones given in the static case, and we can use the procedure explained in [35]. We define

$$\kappa_+ = q_+^4 + \frac{a_2}{a_4} q_+^2 + \frac{a_1}{a_4} q_+ + \frac{a_0}{a_4}, \quad \kappa_- = q_-^4 + \frac{a_2}{a_4} q_-^2 + \frac{a_1}{a_4} q_- + \frac{a_0}{a_4}, \quad (3.29)$$

so that the area product will be given by $\prod_{\alpha=1}^4 A_\alpha = (4\pi)^4 \kappa_+ \kappa_- / \Xi^4$. Plugging in the values of the coefficients and using the expression (3.22) for $J$ we have

$$\prod_{\alpha=1}^4 A_\alpha = (4\pi)^4 l^2 \left( (\pi^0\pi^1)^2 + j^2 \right). \quad (3.30)$$

The charge-dependent term on the rhs of (3.30) is directly related to the prepotential; a fact that was first noticed in [35] for static black holes.
3.2 Thermodynamics and extremality

A quasi-Euclidean section of the metric can be obtained by analytically continuing $t \to -it_E$. It turns out that this is regular at $q = q_h$ provided $t_E$ is identified modulo $4\pi \Xi(q_h^2 + j^2 - \Delta^2)/Q_h'$, where $Q_h'$ denotes the derivative of $Q$ w.r.t. $q$, evaluated at the horizon. This yields the Hawking temperature

$$T = \frac{Q_h'}{4\pi(q_h^2 + j^2 - \Delta^2)}. \quad (3.31)$$

Using the expressions (3.15), (3.22) and (3.24) for the entropy, angular momentum and mass respectively, as well as the fact that $Q$ vanishes for $q = q_h$, one obtains by simple algebraic manipulations the Christodoulou-Ruffini-type mass formula

$$M^2 = \frac{S}{4\pi G} + \frac{\pi J^2}{SG} + \frac{\pi}{4SG^2}(\pi^0 \pi^1)^2 + \left(\frac{l^2}{G^2} + \frac{S}{\pi G}\right)((g_0^0 \pi^0)^2 + (g_1^1 \pi^1)^2)$$

$$+ \frac{J^2}{l^2} + \frac{S^2}{2\pi^2 l^2} + \frac{S^3 G}{4\pi^3 l^4}. \quad (3.32)$$

Note that this reduces correctly to equ. (43) of [8] in the KNAdS case $(g_0^0 \pi^0)^2 = (g_1^1 \pi^1)^2$, $\Delta = 0$, $a_1$ arbitrary.

Since $S, J, \pi^\Lambda$ form a complete set of extensive parameters, (3.32) represents also the black hole thermodynamic fundamental relation $M = M(S, J, \pi^\Lambda)$. The quantities conjugate to $S, J, \pi^\Lambda$ are the temperature

$$T = \left(\frac{\partial M}{\partial S}\right)_{J, \pi^\Lambda} = \frac{1}{8\pi GM} \left[1 - \frac{4\pi^2 J^2}{S^2} - \frac{\pi^2}{S^2 G^2}(\pi^0 \pi^1)^2 + 4((g_0^0 \pi^0)^2 + (g_1^1 \pi^1)^2)ight.$$

$$\left.+ \frac{4SG}{\pi l^2} + \frac{3S^2 G^2}{\pi^2 l^4}\right], \quad (3.33)$$

the angular velocity

$$\Omega = \left(\frac{\partial M}{\partial J}\right)_{S, \pi^\Lambda} = \frac{\pi J}{M GS} \left[1 + \frac{SG}{\pi l^2}\right], \quad (3.34)$$

and the magnetic potentials

$$\Phi^\Lambda = \left(\frac{\partial M}{\partial \pi^\Lambda}\right)_{S, J, \pi^\Sigma \neq \Lambda} = \frac{1}{MG} \left[\frac{\pi}{4SG^2 \pi^0 \pi^1 \eta_{\Lambda \Sigma} \pi^\Sigma} + \left(\frac{l^2}{G} + \frac{S}{\pi}\right) g_\Lambda^2 \pi^\Lambda\right], \quad (3.35)$$

where

$$\eta_{\Lambda \Sigma} = \begin{pmatrix} 0 & 1 \\ 1 & 0 \end{pmatrix},$$

$$−17−$$
and there is no summation over $\Lambda$ in the last term. The obtained quantities satisfy the first law of thermodynamics

$$dM = TdS + \Omega dJ + \Phi_A d\pi^A.$$  

(3.36)

Furthermore, by eliminating $M$ from (3.33)-(3.35) using (3.32), it is possible to obtain four equations of state for the black holes (3.14). It is straightforward to verify that the relation (3.33) for the temperature coincides with equ. (3.31), whereas (3.34) yields

$$\Omega = \omega_h - \omega_\infty,$$  

(3.37)

with $\omega_h$ and $\omega_\infty$ given respectively by (3.19) and (3.20). It is thus the difference between the angular velocities at the horizon and at infinity which enters the first law; a fact that was stressed in [8] for the case of the KNAdS black hole.

The Hawking temperature (3.31) vanishes in the extremal case, when $q_h$ is at least a double root of $Q$. The structure function $Q$ can then be written as

$$Q = (q - q_h)^2 \left( \frac{q^2}{l^2} + \frac{2q_h q}{l^2} + a_2 + \frac{3q_h^2}{l^2} \right),$$

and we must have

$$a_0 = a_2 q_h^2 + \frac{3q_h^4}{l^2}, \quad a_1 = -2q_h a_2 - \frac{4q_h^3}{l^2}. \quad (3.38)$$

These equations restrict of course the number of free parameters compared to the nonextremal case. To obtain the near-horizon geometry of the extremal black holes, we define new (dimensionless) coordinates $z, \hat{t}, \hat{\phi}$ by

$$q = q_h + \epsilon q_0 z, \quad t = \frac{\hat{t}q_0}{\Xi\epsilon}, \quad \phi = \hat{\phi} + \omega_h \frac{\hat{t}q_0}{\epsilon}, \quad q_0^2 \equiv \frac{\Xi l^2(q_h^2 + j^2 - \Delta^2)}{6q_h^2 + a_2 l^2},$$

(3.39)

and take $\epsilon \to 0$ keeping $z, \hat{t}, \hat{\phi}$ fixed. This leads to

$$ds^2 = \frac{q_h^2 - \Delta^2 + j^2 \cos^2 \theta}{C} \left( -z^2 d\hat{t}^2 + \frac{dz^2}{z^2} + C \frac{d\hat{\phi}^2}{\Delta_\theta} \right) + \frac{\Delta_\theta \sin^2 \theta (q_h^2 + j^2 - \Delta^2)^2}{(q_h^2 - \Delta^2 + j^2 \cos^2 \theta)} \left( \frac{d\hat{\phi}}{z} + \frac{2q_h \omega_h}{C} z d\hat{t} \right)^2,$$

(3.40)

where the constant $C$ is given by

$$C = \frac{6q_h^2}{l^2} + a_2$$

$$= \left\{ \left( 1 - \frac{\Delta^2}{l^2} \right)^2 + \frac{j^2 - \Delta^2}{l^2} + 14 \left( 1 - \frac{\Delta^2}{l^2} \right) (j^2 - \Delta^2) + 24(g_0^2 P_0^2 + g_1^2 P_1^2) \right\}^{1/2}. $$

- 18 -
If \( q_h \) is at least a triple root of \( Q, C \) vanishes, and one has an ultracold black hole. In this case, the zooming procedure (3.39) does not conform to Geroch’s criteria of limiting spaces [53], and thus the resulting geometry would not even solve the equations of motion. This problem was first pointed out by Romans [54], and discussed also in [55]. There exists an alternative limiting procedure [56, 57] which basically consists in going first to the situation where \( Q \) has a double root, and then taking the near-horizon limit simultaneously with the ultracold limit in a particular way. We postpone a discussion of the ultracold case to a future publication.

Note that in the extremal limit, when \( T = 0 \), it is easy to see that the entropy is only a function of the discrete charges \( J \) and \( \pi^I \) by inverting (3.33) in terms of \( S \).

### 3.3 Noncompact horizon with finite area

We shall now discuss the special case where the polynomial \( P(p) \) has two double roots, i.e., \( p_a = p_b \) in the notation adopted at the beginning of section 3.1. This corresponds to \( \ell^2 = \ell^2 \), which means that the conformal boundary rotates at the speed of light. For the Kerr-AdS solution, this limit (in which the metric (3.14) is of course singular) was explored in [4]9, where it was argued that it represents an interesting example in which to study AdS/CFT.

Using again the scaling symmetry (3.10), we can set \( p_a = l \) without loss of generality, so that

\[
P(p) = \frac{1}{l^2} (p^2 - \ell^2)^2
\]

in this case. The induced metric on the horizon \( q = q_h \) (where \( Q \) vanishes) is given by

\[
ds_h^2 = \frac{P}{q_h^2 - \Delta^2 + p^2} (q_h^2 - \Delta^2 + \alpha)^2 dy^2 + \frac{q_h^2 - \Delta^2 + p^2}{P} dp^2,
\]  

(3.41)

where the constant \( \alpha \) takes into account a possible shift \( t \to t + \alpha y \), similar to (3.13). If we want \( y \) to be a compact coordinate, the absence of closed timelike curves requires setting \( \alpha = \ell^2 \), since otherwise \( g_{yy} \) will be negative close to \( p^2 = \ell^2 \). Note that we consider the coordinate range \(-\ell \leq p \leq \ell\), and that (3.41) becomes singular for \( p^2 = \ell^2 \).

To understand more in detail what happens at these singularities, take for instance the limit \( p \to \ell \), in which (3.41) simplifies to

\[
ds_h^2 = (q_h^2 - \Delta^2 + \ell^2) \left[ \frac{d\rho^2}{4\rho^2} + 4\rho^2 dy^2 \right].
\]  

(3.42)

Here, the new coordinate \( \rho \) is defined by \( \rho = \ell - p \). (3.42) is clearly a metric of constant negative curvature on the hyperbolic space \( \mathbb{H}^2 \) (or on a quotient thereof, if

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9See also [58, 59].
we want $y$ to be a compact coordinate. Since (3.41) is symmetric under $p \to -p$, an identical result holds for $p \to -l$. Thus, for $p \to \pm l$, the horizon approaches a space of constant negative curvature, and there is no true singularity there. In particular, this implies that the horizon is noncompact, which comes as a surprise, since one might have expected the limit of coincident roots $p_a = p_b$ to be smooth, and for $p_a \neq p_b$ the horizon was topologically a sphere. Moreover, the horizon area reads

$$A_h = \int (q_h^2 - \Delta^2 + l^2) dy dp = 2Ll(q_h^2 - \Delta^2 + l^2),$$

where we assumed $y$ to be identified modulo $L$. We see that, in spite of being noncompact, the event horizon has finite area, and the entropy of the corresponding black hole is thus also finite. To the best of our knowledge, this represents the first instance of a black hole with noncompact horizon, but still finite entropy.

![Figure 1](image-url)

**Figure 1.** The event horizon of a black hole in the case where $P(p)$ has two double roots, embedded in $\mathbb{R}^3$ as a surface of revolution.

In order to visualize the geometry (3.41), we can embed it in $\mathbb{R}^3$ as a surface of
revolution\(^{10}\). To this end write the flat metric in cylindrical coordinates,

\[ ds_3^2 = dz^2 + dr^2 + r^2 d\phi^2 , \]

and consider \( z = z(p) \), \( r = r(p) \). Setting \( \phi = 2\pi y/L \), and identifying the resulting line element with (3.41), one gets

\[ r = \frac{L}{2\pi l} (q_h^2 - \Delta^2 + p^2)^{-1/2} (l^2 - p^2)(q_h^2 - \Delta^2 + l^2) , \tag{3.44} \]

as well as

\[ \left( \frac{dr}{dp} \right)^2 + \left( \frac{dz}{dp} \right)^2 = \frac{q_h^2 - \Delta^2 + p^2}{P} , \tag{3.45} \]

which is a differential equation for \( dz/dp \). By expanding near \( p = \pm l \), one easily sees that \( z \) diverges logarithmically for \( |p| \to l \), and that \( r \) goes to zero in this limit. We integrated (3.45) numerically for the values \( l = 1 \), \( L = 2\pi \) and \( q_h^2 - \Delta^2 = 5 \). The resulting surface of revolution is shown in figure 1, where the \( z \)-axis is vertical. Note that the two cusps extend up to infinity, with \( z \to \pm \infty \) for \( p \to \pm l \) respectively, while the ‘equator’ \( z = 0 \), where \( r \) becomes maximal, is reached for \( p = 0 \).

The metric on the conformal boundary \( q \to \infty \) of the black hole solution reads

\[ ds_{\text{bdry}}^2 = -dt^2 + 2dt dy (p^2 - l^2) + l^2 dp^2 / P , \tag{3.46} \]

and hence \( y \) becomes a lightlike coordinate there.

## 4 Inclusion of NUT- and electric charges

Inspired by the solution in section 5 of [22], we make the following ansatz to include also NUT- and electric charges:

\[ ds^2 = -\frac{Q}{W} [dt - p_1 p_2 dy]^2 + \frac{P}{W} [dt + q_1 q_2 dy]^2 + W \left( \frac{dq^2}{Q} + \frac{dp^2}{P} \right) , \tag{4.1} \]

where \( Q, P \) are again given by (3.2) (with \( a_4 = b_4 = 1/l^2 \)), and

\[ W = q_1 q_2 + p_1 p_2 , \quad q_1 = q - \Delta , \quad q_2 = q + \Delta , \quad p_1 = p - \delta , \quad p_2 = p + \delta . \]

The ansatz for the gauge potentials and the scalars is

\[ A^\Lambda = \frac{P^\Lambda (dt + q_1 q_2 dy)}{W} p_1 + \frac{Q^\Lambda (dt - p_1 p_2 dy)}{W} q_1 , \tag{4.2} \]

\(^{10}\)This is possible if \( L(q_h^2 - \Delta + l^2) \) is not too large, since otherwise \((dz/dp)^2\) in (3.45) will become negative in some region.
\[ \tau = e^{-\varphi} + i\chi = \frac{X^1}{X^0} = \frac{\mu W + i(\nu p + \lambda q)}{q_1^2 + p_1^2}, \] 

(4.3)

where the constants \( Q^A \) are proportional to the electric charges, and \( \mu, \nu, \lambda \) are constants to be determined.

We have checked that the equations of motion of the \( F = -iX^0X^1 \) model are satisfied if the parameters assume the following form:

\[ a_4 = b_4 = 1/l^2, \] 

(4.4)

\[ a_0 = b_0 - a_2 \Delta^2 - \frac{\Delta^4}{l^2} + \frac{g_0 P_{02}}{2g_1} + \frac{g_1 P_{12}}{2g_0} + \frac{g_0 Q_{02}}{2g_1} + \frac{g_1 Q_{12}}{2g_0} + \] 

\[ - \frac{a_2 \Delta^2 Q_{12}}{P_{12}} - \frac{2\Delta^4 Q_{12}}{l^2 P_{12}} - \frac{\Delta^4 Q_{14}}{l^2 P_{14}}, \] 

(4.5)

\[ b_1 = \frac{-2l^2 P_1(g_0(-2P_0P_1Q_0 + P_{02}Q_1 - Q_{02}Q^1) + g_1 P_1(P_{12} + Q_{12}))}{\Delta(P_{12} + Q_{12})}, \] 

(4.6)

\[ a_1 = \frac{-2l^2 P_1(g_0(-P_{02}P_1 + P_1 Q_{02} - 2P_0 Q_0Q_1) + g_1 P_1(P_{12} + Q_{12}))}{\Delta(P_{12} + Q_{12})}, \] 

(4.7)

\[ b_2 = -a_2 - \frac{2\Delta^2(P_{12} + Q_{12})}{l^2 P_{12}}, \] 

(4.8)

\[ \mu = \frac{g_0}{g_1}, \quad \nu = \frac{2\Delta g_0}{g_1}, \quad \lambda = \frac{2\Delta g_0 Q_1}{g_1 P_{11}}, \quad \delta = -\frac{\Delta Q_1}{P_{11}}. \] 

(4.9)

The solution has free parameters \( \Delta, b_0, a_2, P^A \) and \( Q^A \). It reduces to the one we have previously found for \( Q^1 = 0 = Q^0 \).

Let us now keep the ansatz \((4.1)-(4.2)\) for the metric and the gauge fields and look for a solution with a scalar field of the form

\[ \tau = e^{-\varphi} + i\chi = \frac{X^1}{X^0} = \frac{\mu W + i(\nu p + \lambda q)}{q_1^2 + p_1^2}. \] 

(4.10)

In this case, the equations of motions are satisfied for the following parameters

\[ a_4 = b_4 = 1/l^2, \] 

(4.11)

\[ a_0 = b_0 - a_2 \Delta^2 - \frac{\Delta^4}{l^2} + \frac{g_0 P_{02}}{2g_1} + \frac{g_1 P_{12}}{2g_0} + \frac{g_0 Q_{02}}{2g_1} + \frac{g_1 Q_{12}}{2g_0} + \] 

\[ - \frac{a_2 \Delta^2 Q_{12}}{P_{02}} - \frac{2\Delta^4 Q_{02}}{l^2 P_{02}} - \frac{\Delta^4 Q_{04}}{l^2 P_{04}}, \] 

(4.12)
\[ b_1 = -\frac{2l^2 P^0 (g_1^2 (-2P^1 P^0 Q^1 + P^{12} Q^0 - Q^{12} Q^0) + g_0^2 Q^0 (P^{02} + Q^{02})))}{\Delta (P^{02} + Q^{02})}, \]  
(4.13)

\[ a_1 = -\frac{2l^2 P^0 (g_1^2 (-P^{12} P^0 + P^0 Q^{12} - 2P^1 Q^0 Q^1) + g_0^2 P^0 (P^{02} + Q^{02})))}{\Delta (P^{02} + Q^{02})}, \]  
(4.14)

\[ b_2 = -a_2 - \frac{2\Delta^2 (P^{02} + Q^{02})}{l^2 P^0}, \]  
(4.15)

\[ \mu = \frac{g_0}{g_1}, \quad \nu = -\frac{2\Delta g_0}{g_1}, \quad \lambda = -\frac{2\Delta g_0 Q^0}{g_1 P^0}, \quad \delta = -\frac{\Delta Q^0}{P^0}. \]  
(4.16)

One can easily check that the two ansätze (4.3) and (4.10) (when expressed in terms of the parameters \( \Delta \) and \( \delta \)) are related by the strong-weak coupling transformation

\[ \tau \rightarrow \frac{g_0}{g_1} \tau. \]  
(4.17)

This is actually a residual \( \mathbb{Z}_2 \) symmetry of the full symplectic group \( \text{Sp}(4, \mathbb{R}) \) that remains after the gauging, corresponding to a reparametrization of the scalar manifold, given by the action of the matrix

\[ S = \begin{pmatrix} A & B \\ C & D \end{pmatrix} \in \text{Sp}(4, \mathbb{R}), \]  
(4.18)

with \( B = C = 0 \),

\[ A = \begin{pmatrix} 0 & \frac{g_1}{g_0} \\ \frac{g_0}{g_1} & 0 \end{pmatrix}, \]  
(4.19)

and \( D = (A^{-1})^T \). Since \( S^2 = \mathbb{I} \), it generates \( \mathbb{Z}_2 \), as stated. Notice also that the scalar potential is invariant under (4.17). Moreover, the matrix (4.18) acts on the charges by interchanging \( g_0 P^0 \leftrightarrow g_1 P^1 \) and \( g_0 Q^0 \leftrightarrow g_1 Q^1 \), which is exactly what transforms (4.5)-(4.9) to the new parameters (4.12)-(4.16).

In order to discuss more in detail the solution (4.4)-(4.9), we assume that the polynomial \( P \) has four distinct roots \( p_a < p_b < p_c < p_d \). Since we are interested in black holes with compact horizon\(^{11}\), we consider the region \( p_b \leq p \leq p_c \) (where \( P \) is positive), and set \( p = N + j \cos \theta \), where

\[ N \equiv \frac{p_b + p_c}{2}, \quad j \equiv \frac{p_c - p_b}{2}, \]  
(4.20)

and \( 0 \leq \theta \leq \pi \). Using the scaling symmetry (3.10), supplemented by

\[ \delta \rightarrow \lambda \delta, \quad b_1 \rightarrow \lambda^3 b_1, \]  

\(^{11}\)Black holes with hyperbolic horizons can be obtained by taking the region \( p \geq p_d \).
one can set \( p_d = -N + \sqrt{l^2 + 4N^2} \) without loss of generality\(^{12}\). This implies

\[
\begin{align*}
b_0 &= (j^2 - N^2) \left( 1 + \frac{3N^2}{l^2} \right), & b_1 &= 2N \left( 1 - \frac{j^2}{l^2} + \frac{4N^2}{l^2} \right), & b_2 &= -1 - \frac{j^2}{l^2} - \frac{6N^2}{l^2}, \\
a_0 &= b_0 + b_2(\Delta^2 + \delta^2) + \left( \frac{\Delta^2 + \delta^2}{l^2} \right)^2 + 2l^2 \left[ g_0^2(P^0 + Q^0) + g_1^2(P^1 + Q^1) \right], \\
a_2 &= 1 + \frac{j^2}{l^2} + \frac{6N^2}{l^2} - \frac{2}{l^2}(\Delta^2 + \delta^2). \tag{4.21}
\end{align*}
\]

Taking also

\[
t \to t + \left( \frac{j}{\Xi} + \frac{N^2 - \delta^2}{j^2} \right) \phi, \quad y \to \frac{\phi}{\Xi},
\]

the metric (4.1) becomes

\[
ds^2 = -\frac{Q}{q^2 - \Delta^2 + (N + j \cos \theta)^2 - \delta^2} \left[ dt + \frac{j \sin^2 \theta}{\Xi} d\phi - \frac{2N}{\Xi} \cos \theta d\phi \right]^2 \\
+ \left[ q^2 - \Delta^2 + (N + j \cos \theta)^2 - \delta^2 \right] \left( \frac{dq}{Q} + \frac{d\theta^2}{\Delta} \right) \\
+ \frac{\Delta \sin^2 \theta}{q^2 - \Delta^2 + (N + j \cos \theta)^2 - \delta^2} \left[ j dt + \frac{q^2 + j^2 + N^2 - \Delta^2 - \delta^2}{\Xi} d\phi \right]^2,
\]

where now

\[\Delta \theta = 1 - \frac{j^2}{l^2} \cos^2 \theta - \frac{4Nj}{l^2} \cos \theta,\]

while the fluxes and the scalar field are given respectively by

\[
\begin{align*}
F^\Lambda &= \frac{P^\Lambda(q^2 - \Delta^2 - (p - \delta)^2) - 2(q - \Delta)p Q^\Lambda}{[q^2 - \Delta^2 + (N + j \cos \theta)^2 - \delta^2]^2} \sin \theta \left[ j dt + \frac{q^2 + j^2 + N^2 - \Delta^2 - \delta^2}{\Xi} d\phi \right] \wedge d\theta \\
&\quad + \frac{Q^\Lambda(p^2 - \delta^2 - (q - \Delta)^2 - 2(p - \delta)q P^\Lambda}{[q^2 - \Delta^2 + (N + j \cos \theta)^2 - \delta^2]^2} dq \wedge \left[ dt + \frac{j \sin^2 \theta}{\Xi} d\phi - \frac{2N}{\Xi} \cos \theta d\phi \right],
\end{align*}
\]

\[\tau = \frac{g_0 q + \Delta - i(p + \delta)}{g_1 q - \Delta - i(p - \delta)},\]

with \( p = N + j \cos \theta \).

If one turns off the rotation \((j = 0)\), and fixes the charges in terms of \(N, \Delta, \delta\) according to

\[
g_1 P^1 = \frac{N^2}{l^2} - \frac{N \delta}{l^2} + \frac{1}{4}, \quad g_1 Q^1 = -\frac{\delta}{\Delta} g_1 P^1, \quad g_0 P^0 = g_1 P^1 + \frac{2N \delta}{l^2}, \quad g_0 Q^0 = g_1 Q^1 + \frac{2N \Delta}{l^2},
\]

\(^{12}\)This choice is made in order to correctly reproduce the KNTN-AdS solution of minimal gauged supergravity as a special subcase, see e.g. [26].
one recovers the spherical NUT-charged BPS solution constructed in \cite{47}\textsuperscript{13}. With the charges fixed as above, and
\[ a_1 = -\frac{4N}{\Delta} \left[ \frac{2N\Delta^2}{l^2} + \frac{2N\delta^2}{l^2} - \frac{2N^2\delta}{l^2} - \frac{\delta}{2} \right], \]
all the constraints (4.5)-(4.8) are satisfied.

From (4.22), we can also get a dyonic solution without NUT charge. Setting \( N = 0 \) one has
\[ b_0 = j^2, \quad b_1 = 0, \quad b_2 = -1 - \frac{j^2}{l^2}, \quad a_2 = 1 + \frac{j^2}{l^2} - \frac{2}{l^2}(\Delta^2 + \delta^2), \]
\[ a_0 = j^2 - \left(1 + \frac{j^2}{l^2}\right)(\Delta^2 + \delta^2) + \frac{(\Delta^2 + \delta^2)^2}{l^2} + 2l^2 \left[ g_{0}^2(P^{02} + Q^{02}) + g_{1}^2(P^{12} + Q^{12}) \right], \]
and \( a_1 \) is given by (4.7). Since \( b_1 \) vanishes, (4.6) implies \( P^1 = 0 \) or
\[ g_{0}^2 (Q^0Q^1 + P^0P^1)^2 = (Q^{12} + P^{12}) \left( g_{1}^2 Q^{12} + g_{0}^2 P^{02} \right), \]
which allows to express e.g. \( Q^0 \) in terms of the other charges. The solution is thus specified by the five parameters \( P^0, P^1, Q^1, j, \Delta \), or alternatively by three charges, angular momentum and mass.

Note that, also in the case with nonvanishing \( N \), (4.6) together with the second eqn. in (4.21) fix one of the electromagnetic charges in terms of the other parameters, and therefore the solution is labelled by three independent U(1) charges, NUT charge, angular momentum and mass. It is thus not the most general solution, which should have four independent U(1) charges.

### 4.1 Solution with harmonic functions and flat limit

We can partially rewrite the ansatz in terms of complex harmonic functions in order to make the dependence on the prepotential more suggestive. If we define the variable \( \rho = q - ip \), we can use the harmonic functions in \( \rho \),
\[ X^0 \equiv H_0 = h_0(1 - \Delta - i\delta), \quad X^1 \equiv H_1 = h_1(1 + \Delta - i\delta), \]
with \( h_0 = g_0^{-1}, h_1 = g_1^{-1} \). We can then rewrite the scalar ansatz as
\[ \tau = \frac{H_1}{H_0}, \]
\textsuperscript{13}The flat or hyperbolic BPS solutions of \cite{47} can be obtained in a similar way. Notice that only the latter represent genuine black holes, while in the spherical or flat case one has naked singularities \cite{47}.
while the function $W$ appearing in the metric and gauge field ansätze (4.1), (4.2) can be cast into the form
\[ W = l^2(q^2 + p^2)e^{-K(X^A)} , \] (4.26)
where $K$ is the Kähler potential of special geometry that depends on the prepotential\textsuperscript{14}. In the case of $F = -i X^0 X^1$, we have
\[ e^{-K}_{F=-iX^0 X^1} = \frac{1}{l^2(q^2 + p^2)} (q_1 q_2 + p_1 p_2) , \] (4.27)
as needed.

Rewriting the solution in this form makes it easy to take the limit of vanishing gauging. We take $g_0, g_1 \to 0$, keeping the ratio an arbitrary finite constant (which is the value of the scalar field at infinity). This leads to a simplification in the explicit parameters $a_i, b_i$ that parametrize the functions $P(p)$ and $Q(q)$. We can again write the metric in the form (4.22), but now with $\Delta_{\eta} = \Xi = 1$. A further redefinition of the radial coordinate $q = r + m$ for $a_1 = -2m$ leads to
\[ Q = r^2 + (j^2 + m^2 - N^2 - \Delta^2 - \delta^2) . \]
Written this way, the solution can be seen to sit inside the general class of solutions of [41] with arbitrary mass, angular momentum, electric and magnetic and NUT charges. Just like in the case with cosmological constant, we cannot recover the most general class due to the restriction that the NUT charge is fixed in terms of the electric and magnetic charges, c.f. (4.6) and (4.21).

5 Final remarks and outlook

Given the various examples and solutions we presented in the preceeding sections, we can make an ansatz that is likely to yield solutions for more general prepotentials with arbitrary number of vector multiplets. The metric ansatz would remain
\[ ds^2 = -f(dt + \omega_y dy)^2 + f^{-1} \left[ v \left( \frac{dq^2}{Q} + \frac{dp^2}{P} \right) + PQ dy^2 \right] , \] (5.1)
with
\[ Q = a_0 + a_1 q + a_2 q^2 + g^2 q^4 , \quad P = b_0 + b_1 p + b_2 p^2 + g^2 p^4 , \quad v = Q - P , \quad f = ve^{2U} , \] (5.2)
\[ e^{-2U} = i(X^L F_L - X^L F_L) , \quad \omega_y = -\frac{1}{v} \left( Q(c_0 + c_1 p + p^2) + P(d_0 + d_1 q + q^2) \right) , \] (5.3)
\textsuperscript{14}Note that here we do not mean the physical Kähler potential $K(\tau, \bar{\tau})$, but the one that is obtained directly from the sections (4.24).
scalar fields given by the symplectic sections

\[ X^\Lambda = h^\Lambda (q - ip + \Delta^\Lambda - i\delta^\Lambda) , \]  

(5.4)

and gauge fields

\[ A^\Lambda = \frac{1}{W} \left( (P^\Lambda p + k_0)(dt + (d_0 + d_1 q + q^2)dy) + Q^\Lambda (q + l_0)(dt - (c_0 + c_1 p + p^2)dy) \right) . \]  

(5.5)

The real constant parameters \( a_0, a_1, a_2, b_0, b_1, b_2, c_0, c_1, d_0, d_1, k_0, l_0, h^\Lambda, \Delta^\Lambda, \delta^\Lambda, P^\Lambda, Q^\Lambda \) will eventually have to be expressed in terms of the physical parameters of a given solution (mass, angular momentum, NUT charge, electric and magnetic charges) upon solving the equations of motion in a chosen model. The question whether the above ansatz leads to solutions in models of the STU type is left for future research.

Acknowledgments

We would like to thank S. Katmadas, A. Tomasiello and S. Vandoren for interesting discussions. A.G. and C.T. would also like to thank Università degli Studi di Milano and Milano-Bicocca for the kind hospitality during various visits, while this work was in progress.

A.G. and C.T. acknowledge support by the Netherlands Organization for Scientific Research (NWO) under the VICI grant 680-47-603. K.H. is supported in part by INFN and by the MIUR-FIRB grant RBFR10QS5J “String Theory and Fundamental Interactions”. The work of D.K. was partially supported by INFN and MIUR-PRIN contract 2009-KHZKRX. The work of O.V. is supported by the German Science Foundation (DFG) under the Collaborative Research Center (SFB) 676 “Particles, Strings and the Early Universe”.

A 1/2 BPS near-horizon geometries

An interesting class of half-supersymmetric backgrounds was obtained in [46]. It includes the near-horizon geometry of extremal rotating black holes. The metric and the fluxes read respectively

\[
 ds^2 = -z^2 e^\xi \left[ dt + 4(e^{-2\xi} - L) \frac{dx}{z} \right]^2 + 4e^{-\xi} \frac{dz^2}{z^2} + 16e^{-\xi}(e^{-2\xi} - L)dx^2 + \frac{4e^{-2\xi} d\xi^2}{Y^2(e^{-\xi} - Le^\xi)} ,
\]  

(A.1)
\[ F^A = 8i \left( \frac{XL^\Lambda}{1-iY} - \frac{X\bar{L}^\Lambda}{1+iY} \right) dt \wedge dz \quad (A.2) \]

\[ + 4 \left[ \frac{2XL^\Lambda}{1-iY} + \frac{2X\bar{L}^\Lambda}{1+iY} + (\text{Im}N)^{-1}g_{\Sigma} (zdt - 4Ldx) \wedge d\xi, \quad (A.2) \right. \]

where \( L \) is a real integration constant, \( X \equiv g_\Lambda L^\Lambda \), and \( Y \) is defined by

\[ Y^2 = 64e^{-\xi}|X|^2 - 1. \quad (A.3) \]

The moduli fields \( z^\alpha \) depend on the coordinate \( \xi \) only, and obey the differential equation

\[ \frac{dz^\alpha}{d\xi} = \frac{i}{2Y}(1-iY)g^{\alpha\beta}D_\beta \bar{X}. \quad (A.4) \]

For \( L > 0 \), the line element \( (A.1) \) can be cast into the simple form

\[ ds^2 = 4e^{-\xi} \left( -z^2 dt^2 + \frac{dz^2}{z^2} \right) + 16L(e^{-\xi} - Le^{\xi}) \left( dx - \frac{z}{2\sqrt{L}} dt \right)^2 \]

\[ + \frac{4e^{-2\xi}d\xi^2}{Y^2(e^{-\xi} - Le^{\xi})}, \quad (A.5) \]

where \( \hat{t} \equiv t/(2\sqrt{L}) \). \( (A.5) \) is of the form (3.3) of [48], and describes the near-horizon geometry of extremal rotating black holes\(^{15} \), with isometry group \( \text{SL}(2, \mathbb{R}) \times \text{U}(1) \).

From \( (A.4) \) it is clear that the scalar fields have a nontrivial dependence on the horizon coordinate \( \xi \) unless \( g_\Lambda D_\alpha X^\Lambda = 0 \). As was shown in [46], the solution with constant scalars is the near-horizon limit of the supersymmetric rotating hyperbolic black holes in minimal gauged supergravity [25]. Moreover, in [29], a class of rotating BPS black holes with running scalar was constructed for the prepotential \( F = -iX^0X^1 \), which has again \( (A.5) \) as near-horizon limit.

Let us first consider the case of gauged supergravity with flat scalar potential \( V \), that was studied recently in [43]. The condition \( V = 0 \) translates into

\[ D_\alpha X g^{\alpha\beta} D_\beta \bar{X} = 3|X|^2. \quad (A.6) \]

Now, using \( (A.4) \), it is straightforward to show that

\[ \frac{d|X|^2}{d\xi} = D_\alpha X g^{\alpha\beta} D_\beta \bar{X}. \quad (A.7) \]

Using \( (A.6) \), this can be integrated to give

\[ |X|^2 = C^2 e^{3\xi}, \quad (A.8) \]

\(^{15}\)Metrics of the type \( (A.5) \) were discussed for the first time in [60] in the context of the extremal Kerr throat geometry.
where $C$ denotes an integration constant. Then, (A.3) allows to express $\xi$ in terms of $Y$,
$$
e^{-\xi} = 8C(Y^2 + 1)^{-1/2}.
\quad (A.9)$$

In asymptotically flat space, there are underrotating black holes [49], whose near-horizon geometry is given by
$$
ds^2 = -e^{2U} r^2 (dt + \omega)^2 + e^{-2U} \left( \frac{dr^2}{r^2} + d\theta^2 + \sin^2 \theta d\phi^2 \right),
\quad (A.10)$$

where
$$
e^{-4U} = -I_4 - j^2 \cos^2 \theta, \quad \omega = j \frac{\sin^2 \theta}{r} d\phi,
\quad (A.11)$$

$j$ is the rotation parameter and $I_4$ denotes the quartic invariant of the charges. It turns out that (A.10) is actually a one-half BPS solution of gauged supergravity (with flat potential). To see this, choose $C = \frac{|I_4|}{16}$ (we need $I_4 < 0$), $L = (|I_4| - j^2)/16$, and make the coordinate transformation
$$
z = \frac{r}{2}, \quad x = \frac{2\phi}{j}, \quad e^{-\xi} = \frac{1}{4} e^{-2U},
\quad (A.12)$$

that casts (A.1) into (A.10). (Use also (A.9) to eliminate $Y$ in favour of $\xi$). In [43] it was shown that the underrotating near-horizon geometry (A.10) preserves at least one quarter of the supersymmetries, but it was not excluded that it is even 1/2 BPS (cf. footnote 14 of [43]). Here we showed that this is indeed the case.

In the case of the model with prepotential $F = -iX^0X^1$, the general solution of the differential equation (A.4) was found in [29], and is given by
$$\tau = \frac{X^1}{X^0} = \frac{g_0 Y - i + C}{g_1 Y - i - C},
\quad (A.13)$$

where $C$ denotes a complex integration constant. We shall now obtain the conditions under which the near-horizon geometry of the general solution of section 4 fits into this 1/2 BPS class. In the extremal limit, the function $Q$ has a double root at $q = q_h$. Defining new coordinates $z, \hat{t}, \hat{y}$ by
$$q = q_h + \epsilon q_0 z, \quad t = \frac{\hat{t}q_0}{\epsilon}, \quad y = \hat{y} - \frac{\hat{t}q_0}{(q_h^2 - \Delta^2)\epsilon}, \quad q_0^2 \equiv \frac{q_h^2 - \Delta^2}{C}, \quad \hat{C} \equiv a_2 + \frac{6q_h^2}{l^2},$$

and taking $\epsilon \to 0$ with $z, \hat{t}, \hat{y}$ fixed, we get the near-horizon limit of (4.1), (4.3) and the field strength following from (4.2),
$$ds^2 = \frac{W_h}{\hat{C}} \left(-z^2 d\hat{t}^2 + \frac{dz^2}{z^2}\right) + \frac{W_h dp^2}{P} + \frac{P}{W_h} \left((q_h^2 - \Delta^2)d\hat{y} - \frac{2q_h z}{\hat{C}}d\hat{t}\right)^2,
\quad (A.14)$$
$$\tau = \frac{g_0 q_h + \Delta - i(p + \delta)}{g_1 q_h - \Delta - i(p - \delta)}, \quad \text{(A.15)}$$

$$F^\Lambda = \frac{P^\Lambda((p - \delta)^2 - q_h^2 + \Delta^2) + 2pQ^\Lambda(q_h - \Delta)}{W_h^2} \left[ (q_h^2 - \Delta^2)d\hat{y} - \frac{2q_hz}{C} dt \right] \wedge dp$$
$$+ \frac{Q^\Lambda((q_h - \Delta)^2 - p^2 + \delta^2) + 2q_hP^\Lambda(p - \delta)}{W_h\hat{C}} dt \wedge dz, \quad \text{(A.16)}$$

where $W_h \equiv q_h^2 - \Delta^2 + p^2 - \delta^2$. This coincides with (A.5), (A.13) and (A.2) respectively if the following constraints hold:

$$Q = \frac{1}{l^2}(q^2 - q_h^2)^2, \quad Q^\Lambda = \delta = 0, \quad P^\Lambda = \frac{8q_h^2}{l^4g_\Lambda}\sqrt{L}. \quad \text{(A.17)}$$

The coordinates $\hat{y}$ and $p$ are related to $x$ and $\xi$ in (A.5) by

$$\hat{y} = \frac{l^2\sqrt{L}}{q_h(q_h^2 - \Delta^2)}x, \quad e^\xi = \frac{16q_h^2}{l^2W_h}, \quad \text{(A.18)}$$

while the constant $C$ in (A.13) is given by $C = -i\Delta/q_h$, and $Y = -p/q_h$. Since the location of the horizon can be set to $q_h = l$ without loss of generality by using the scaling symmetry (3.10), the 1/2 BPS near-horizon geometry is specified in terms of the two parameters $\Delta$ (or alternatively $C$) and $L$. Note that this solution was first constructed in [29]. Since (A.2), (A.5) and (A.13) do not exhaust all possible half-supersymmetric solutions, the results of this appendix do not necessarily imply that there are no further 1/2 BPS subclasses of (4.1)-(4.3).

### B Real formulation of special geometry

Here we will present three dimensional effective Lagrangian for stationary field configurations, adapted to the real formulation of special geometry. In the ungauged case, the resulting three-dimensional Lagrangian, which takes the form of a non-linear sigma model, was constructed in [38] (see eq (29)). For the case of gauged supergravity one must add an additional Fayet-Iliopoulos potential

$$e^{-1}_{3}L_3 = \frac{1}{2}R_3 - \tilde{H}_{ab}(\partial q^a\partial q^b - \partial q^a\partial q^b) + \frac{1}{2H}V(q)$$
$$- \frac{1}{H^2}(q^a\Omega_{ab}\partial q^b)^2 + \frac{2}{H^2}(q^a\Omega_{ab}\partial q^b)^2$$
$$- \frac{1}{4H^2}\left(\partial\hat{\phi} + 2q^a\Omega_{ab}\partial q^b\right)^2, \quad \text{(B.1)}$$
where $\dddot{H}_{ab} = -\frac{1}{2} \frac{\partial^2}{\partial q^a \partial q^b} \log(-2H)$. The Lagrangian is completely determined by specifying a Hesse potential $H$, which plays the analogous role to the holomorphic prepotential when using special real coordinates. In [34, 36] static solutions were considered for which the second and third lines of the above Lagrangian can be consistently set to zero. In this paper we are interested in NUT charged and rotating solutions in which case all terms become relevant.

The fields appearing in (B.1) are related to the complex scalar fields and gauge fields appearing in the main text by the following dictionary:

\[
q^a := \left( \begin{array}{c} x^\Lambda \\ y_\Lambda \end{array} \right) := \left( \begin{array}{c} e^{\phi/2} \text{Re} L^\Lambda \\ e^{\phi/2} \text{Re} M_\Lambda \end{array} \right)
\]

\[
\partial_m q^a := \left( \begin{array}{c} \frac{1}{2} \partial_m \zeta^\Lambda \\ \frac{1}{2} \partial_m \tilde{\zeta}^\Lambda \end{array} \right) := \left( \begin{array}{c} \frac{1}{2} F^\Lambda_{m0} \\ \frac{1}{2} G_\Lambda |m0| \end{array} \right)
\]

\[
\left( \partial_m \dddot{\phi} + 2\dot{q}^a \Omega_{ab} \partial_m q^b \right) := 2H^2 \varepsilon_m^{\ n} \varepsilon_{[n} \omega_{\ m]} \quad ,
\]

whilst the three- and four-dimensional metrics satisfy the expression

\[
g_4 = -e^\phi (dt + \omega_m dx^m)^2 + e^{-\phi} g_3 \quad .
\]

The Hesse potential is related to the Fayet–Iliopoulos potential $V$ through expression (A.2) of [34], and to the KK-scalar through $-2H = e^\phi$.

**B.1 Equations of motion**

For future reference it will be convenient to write down the full equations of motion of the three-dimensional effective Lagrangian (B.1).

We first perform the variation with respect to the $q^a$ fields, which results in the equations

\[
2\nabla^m \left[ \dddot{H}_{ab} \partial_m q^b \right] - \partial_a \dddot{H}_{bc} (\partial_m q^b \partial^m q^c - \partial_m q^b \partial^m \dot{q}^c) + \partial_a \left( \frac{1}{2H} V(q) \right) + 2\nabla^m \left[ \frac{1}{H^2} q^e \Omega_{ca} \left( q^d \Omega_{dc} \partial_m q^e \right) \right] - 2\partial_a \left( \frac{1}{H} q^e \right) \left[ \Omega_{cb} \partial_m q^b \frac{1}{H} \left( q^d \Omega_{de} \partial^m q^e \right) - 2\Omega_{cb} \partial_m q^b \frac{1}{H} \left( q^d \Omega_{de} \partial^m \dot{q}^e \right) \right] - \partial_a \left( \frac{1}{4H^2} \right) \left( \partial_m \dddot{\phi} + 2\dot{q}^a \Omega_{cd} \partial_m q^d \right) \left( \partial^m \dddot{\phi} + 2\dot{q}^a \Omega_{cd} \partial^m \dot{q}^d \right) = 0 \quad .
\]
Next, by varying the $\hat{q}^a$ fields we get

$$
2\nabla^m \left[ \tilde{H}_{ab} \partial_m \hat{q}^b \right] \\
+ 4\nabla^m \left[ \frac{1}{H^2} q^c \Omega_{ca} \left( q^d \Omega_{de} \partial_m \hat{q}^e \right) \right] - \nabla^m \left[ \frac{1}{H^2} \hat{q}^b \Omega_{ba} \left( \partial_m \tilde{\phi} + 2 \hat{q}^c \Omega_{cd} \partial_m \hat{q}^d \right) \right] \\
+ \frac{1}{H^2} \Omega_{ab} \partial_m \hat{q}^b \left( \partial_m \tilde{\phi} + 2 \hat{q}^c \Omega_{cd} \partial_m \hat{q}^d \right) = 0 .
$$

(B.7)

The variation of the $\tilde{\phi}$ field, which descends from the Kaluza–Klein vector, gives us simply

$$
\nabla^m \left[ \frac{1}{4H^2} \left( \partial_m \tilde{\phi} + 2 \hat{q}^c \Omega_{cd} \partial_m \hat{q}^d \right) \right] = 0 .
$$

(B.8)

Since the dualisation procedure swaps the role of the field equations and Bianchi identities, this equation gives us simply the Bianchi identity for the KK-vector. Finally, from the variation of the three-dimensional metric we obtain the following Einstein equations

$$
\frac{1}{2} R_{mn} - \tilde{H}_{ab} \left( \partial_m q^a \partial_n q^b - \partial_m \hat{q}^a \partial_n \hat{q}^b \right) + \frac{1}{2H} g_{mn} V(q) \\
- \frac{1}{H^2} \left( q^a \Omega_{ab} \partial_m \hat{q}^b \right) \left( \hat{q}^c \Omega_{cd} \partial_n \hat{q}^d \right) + \frac{2}{H^2} \left( q^a \Omega_{ab} \partial_m \hat{q}^b \right) \left( \hat{q}^c \Omega_{cd} \partial_n \hat{q}^d \right) \\
- \frac{1}{4H^2} \left( \partial_m \tilde{\phi} + 2 \hat{q}^c \Omega_{ab} \partial_m \hat{q}^b \right) \left( \partial_n \tilde{\phi} + 2 \hat{q}^c \Omega_{cd} \partial_n \hat{q}^d \right) = 0 .
$$

(B.9)

B.2 Example: solution of the $F = -iX^0X^1$ model

By way of example, we shall present the rotating nonextremal solution of the $F = -iX^0X^1$ model, as given section 4, in terms of the real formulation of special geometry:

$$
g_3 = v \left( \frac{dq^2}{Q} + \frac{dp^2}{P} \right) + PQdy^2 ,
$$

$$
q^a = \frac{v^2}{\mu^2} \left( \begin{array}{c}
\frac{q_1}{q_1^2 + p_1^2} \\
\frac{\mu W q_1 - p_1 (\nu p + \lambda q)}{q_1^2 + p_1^2} \\
\frac{\mu W p_1 + q_1 (\nu p + \lambda q)}{q_1^2 + p_1^2} \\
\frac{1}{p_1}
\end{array} \right) \\
\hat{q}^a = \frac{1}{2W} \left( \begin{array}{c}
P^0 p_1 + Q^0 q_1 \\
P^1 p_1 + Q^1 q_1 \\
\mu (P^0 q_2 - Q^0 p_2) \\
\frac{1}{\mu} (P^1 q_1 - Q^1 p_1)
\end{array} \right),
$$
\[
\frac{1}{H} \left( \partial_{\mu} \tilde{\phi} + 2 \tilde{q}^a \Omega_{ab} \partial_{\mu} \tilde{q}^b \right) = -\frac{v}{PW} \partial_{\mu} \omega_y , \\
\frac{1}{H} \left( \partial_{\mu} \tilde{\phi} + 2 \tilde{q}^a \Omega_{ab} \partial_{\mu} \tilde{q}^b \right) = \frac{v}{QW} \partial_{\mu} \omega_y .
\]

Here the functions \(Q, P, W, q_1, q_2, p_1, p_2\) and parameters \(P^A, Q^A, \mu, \nu, \lambda\) are those that appear in the solution (4.1) – (4.9), and the KK-vector is given by

\[
\omega_y = -\frac{(P q_1 q_2 + Q p_1 p_2)}{v} , \quad v = Q - P .
\]

Using the expression for the Hesse potential (B.1) of [34], one may explicitly check that the above field configuration solves the equations of motion (B.6) – (B.9).

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