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Load Balancing Congestion Games and their Asymptotic Behavior

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Abstract—A central question in routing games has been to establish conditions for the uniqueness of the equilibrium, either in terms of network topology or in terms of costs. This question is well understood in two classes of routing games. The first is the non-atomic routing introduced by Wardrop on 1952 in the context of road traffic in which each player (car) is infinitesimally small; a single car has a negligible impact on the congestion. Each car wishes to minimize its expected delay. Under arbitrary topology, such games are known to have a convex potential and thus a unique equilibrium. The second framework is splittable atomic games: there are finitely many players, each controlling the route of a population of individuals (let them be cars in road traffic or packets in the communication networks). In this paper, we study two other frameworks of routing games in which each of several players has an integer number of connections (which are population of packets) to route and where there is a constraint that a connection cannot be split. Through a particular game with a simple three link topology, we identify various novel and surprising properties of games within these frameworks. We show in particular that equilibria are non unique even in the potential game setting of Rosenthal with strictly convex link costs. We further show that non-symmetric equilibria arise in symmetric networks.

I. INTRODUCTION

A central question in routing games has been to establish conditions for the uniqueness of the equilibria, either in terms of the network topology or in terms of the costs. A survey on these issues is given in [1].

The question of uniqueness of equilibria has been studied in two different frameworks. The first, which we call F1, is the non-atomic routing introduced by Wardrop on 1952 in the context of road traffic in which each player (car) is infinitesimally small; a single car has a negligible impact on the congestion. Each car wishes to minimize its expected delay. Under arbitrary topology, such games are known to have a convex potential and thus a unique equilibrium [2].

The second framework, denoted by F2, is splittable atomic games. There are finitely many players, each controlling the route of a population of individuals. This type of games have already been studied in the context of road traffic by Haurie and Marcotte [3] but have become central in the telecom community to model routing decisions of Internet Service Providers that can decide how to split the traffic of their subscribers among various routes so as to minimize network congestion [4].

In this paper we study properties of equilibria in two other frameworks of routing games which exhibit surprising behavior. The first, which we call F3, known as congestion games [5], consists of atomic players with non splittable traffic: each player has to decide on the path to be followed by for its traffic and cannot split the traffic among various paths. This is a non-splittable framework. We further introduce a new semi-splittable framework, denoted by F4, in which each of several players has an integer number of connections to route. It can choose different routes for different connections but there is a constraint that the traffic of a connection cannot be split.

The structure of the paper is as follows. We first introduce the model and the notations used in the while study, we then move on to the properties of frameworks F3 (Section III) and F4 (Section IV) before concluding the paper. For completeness, we also include in the Appendix the proofs of the theorems and propositions of the paper although they will be removed from the final manuscript so as to comply with the conference regulations for final manuscript but will be made available on ArXiv.
II. Model and Notations

We shall use throughout the term atomic game to denote situations in which decisions of a player have an impact on other players’ utility. It is non-atomic when players are infinitesimally small and are viewed like a fluid of players, such that a single player has a negligible impact on the utility of other players.

We consider a system of three nodes (A, B and C) with two incoming traffic sources (respectively from node A and B) and an exit node C. There are a total of \( N \) connections originating from each one of the sources. Each connection can either be sent directly to node C or rerouted via the remaining node. The system is illustrated in Figure 1.

![Physical System](image)

This model has been used to model load balancing issues in computer networks, see [6] and references therein. Jobs arrive to two computing centers represented by nodes A and B. A job can be processed locally at the node where it arrives or it may be forwarded to the other node incurring further communication delay. The costs of links [AC] and [BC] represent the processing delays of jobs processed at nodes A and B respectively. Once processed, the jobs leave the system. A connection is a collection of jobs with similar characteristics (e.g. belonging to the same application).

We introduce the following notations:

- A link between two nodes, say A and B, is denoted by [AB]. Our considered system has three links [AB], [BC] and [AC].
- A route is simply referred by a sequence of nodes. Hence, the system has four connections: two originating from node A (route AC and ABC) and two originating from node B (route BC and BAC).

Further, in the following, \( n_{AC} \), \( n_{BC} \), \( n_{ABC} \) and \( n_{BAC} \) will refer to the number of connections routed via the different routes while \( n_{AC} \), \( n_{BC} \) and \( n_{AB} \) will refer to the number of connections on each subsequent link. By conservation law, we have:

\[
\begin{align*}
n_{AC} + n_{ABC} &= n_{BC} + n_{BAC} = N \\
\text{and} \quad &\begin{cases} \frac{n_{AC}}{N} = \frac{n_{AB}}{N} = \frac{n_{BC}}{N} = \frac{n_{ABC}}{N} = 0 \end{cases}
\end{align*}
\]

For each route \( r \), we also define the fraction (among \( N \)) of flow using it, i.e. \( f_r = n_r / N \). The conservation law becomes \( f_{AC} + f_{ABC} = f_{BC} + f_{BAC} = 1 \).

Finally, the performance measure considered in this work is the cost (delay) of connections experienced on their route. We consider a simple model in which the cost is additive (i.e. the cost of a connection on a route is simply taken as the sum of delays experienced by the connection over the links that constitute this route). We further assume that the costs on each link are linear with coefficient \( a/N \) on link [AB] and coefficient \( b/N \) on link [AC] and [BC], i.e.

\[
\begin{align*}
C_{[AB]} &= \frac{a}{N} n_{AB} = a(f_{BAC} + f_{ABC}), \\
C_{[AC]} &= \frac{b}{N} n_{AC} = b(f_{BAC} + f_{AC}), \\
C_{[BC]} &= \frac{b}{N} n_{BC} = b(f_{BC} + f_{ABC}).
\end{align*}
\]

and then:

\[
\begin{align*}
C_{AB} &= C_{[AB]}, \quad C_{ABC} = C_{[AB]} + C_{[BC]}, \\
C_{BC} &= C_{[BC]}, \quad C_{BAC} = C_{[AB]} + C_{[AC]}.
\end{align*}
\]

We restrict our study to the (pure) Nash equilibria and give the equilibria in terms of the corresponding flows marked by a star. By conservation law, the equilibria is uniquely determined by the specification of \( f_{ABC}^* \) and \( f_{BAC}^* \) (or equivalently \( n_{ABC}^* \) and \( n_{BAC}^* \)).

We recall that in this paper, we consider two types of decision models. In the first (F3), the decision is taken at the connection level (Section III), i.e. each connection has its own decision maker that seeks to minimize the connection’s cost, and the connection cannot be split into different routes. In the second (F4), (Section IV) each one of the two source nodes decides on the routing of all the connections originating there. Each connection of a given source node (either A or B) can be routed independently but a connection cannot be split into different route. We hence refer to F4 this semi-splitable framework. Note that the two-approaches (F3 and F4) coincide when there is only \( N = 1 \) connection at each source, which we also detail later.

III. Atomic Non-Splittable Case and its non-atomic limit (F3 Framework)

We consider here the case where each connection belongs to an individual user acting selfishly.

We first show that for fixed parameters, the game may have several equilibria, all of which are symmetric for any number of players. The number of distinct equilibria can be made arbitrary large by an appropriate choice of the parameters \( a \) and \( b \), and for any choice of \( a \) and \( b \), there exists \( N_0 \) such that the number of equilibria remain constant for all \( N \geq N_0 \). We then show properties of the limiting game obtained as the number of of players increases to infinity.

A. Non-uniqueness of the equilibrium

**Theorem 1.** The set of pure Nash equilibria of the game are the points satisfying \( n_{BAC}^* = n_{ABC}^* = \frac{b}{2a} \).
Proof. Consider an equilibrium \((n_{ABC}^*, n_{BAC}^*)\). Then, we have the following conditions:

\[
\begin{align*}
C_{[AC]} &= C_{AC} \leq (C_{[AB]} + a/N) + (C_{[BC]} + b/N) \\
C_{[BC]} &= C_{BC} \leq (C_{[AB]} + a/N) + (C_{[AC]} + b/N) \\
C_{[AB]} + C_{[BC]} &= C_{ABC} \leq C_{[AC]} + b/N \\
C_{[AB]} + C_{[AC]} &= C_{BAC} \leq C_{[BC]} + b/N
\end{align*}
\]

Note that the last two equations lead to:

\[
\begin{align*}
C_{[AB]} &\leq -C_{[BC]} + C_{[AC]} + b/N \\
C_{[AB]} &\leq -C_{[AC]} + C_{[BC]} + b/N
\end{align*}
\]

One can check that \((n_{ABC}^*, n_{BAC}^*) = (0, 0)\) is a solution. If the equilibrium is not the trivial null solution, then either \(n_{ABC}^* \neq 0\) or \(n_{BAC}^* \neq 0\). Either way leads to \(C_{[AB]} > 0\) and thus \(-b/N < C_{[AC]} - C_{[BC]} < b/N\) which implies that \(C_{[AC]} = C_{[BC]}\). Equation 1 becomes:

\[
\begin{align*}
0 &\leq a(n_{ABC}^* + n_{BAC}^*) + b \\
(a(n_{ABC}^* + n_{BAC}^*) + b) &\leq a(n_{ABC}^* + n_{BAC}^*) \leq b
\end{align*}
\]

But then:

\[
\begin{align*}
C_{[AC]} = C_{[BC]} &\iff b(n_{ABC}^* + n_{BAC}^*) = b(n_{BAC}^* + n_{ABC}^*) \\
N - n_{ABC}^* + n_{BAC}^* &= N - n_{BAC}^* + n_{ABC}^* \iff n_{ABC}^* = n_{BAC}^*. 
\end{align*}
\]

Therefore the equilibrium is symmetrical. Jointly with \(a(n_{ABC}^* + n_{BAC}^*) \leq b\), this leads to the conclusion.

Corollary 2. For \(N \geq N_0 = \lfloor \frac{b}{2a} \rfloor \), there exists exactly \(b/2a + 1\) Nash equilibria in pure strategies.

B. The potential and asymptotic uniqueness

When the number of players \(N\) grows to infinity, the limiting game becomes a non-atomic game with a potential [7]

\[
F_\infty(f_{ABC}, f_{BAC}) = b(f_{ABC} - f_{BAC})^2 + \frac{a}{2} (f_{ABC} + f_{BAC})^2.
\]

Indeed, recall that the potential \(g\) is unique up to an additive constant and that it satisfies

\[
\begin{align*}
\frac{\partial g}{\partial f_{AC}} &\overset{\text{def}}{=} C_{AC} = b(f_{AC} + f_{BAC}) \\
\frac{\partial g}{\partial f_{ABC}} &\overset{\text{def}}{=} C_{ABC} = a(f_{ABC} + f_{BAC}) + f_{ABC} + f_{BAC} \\
\frac{\partial g}{\partial f_{AC}} &\overset{\text{def}}{=} C_{BC} = b(f_{BC} + f_{ABC}) \\
\frac{\partial g}{\partial f_{BAC}} &\overset{\text{def}}{=} C_{BAC} = a(f_{ABC} + f_{BAC}) + f_{BAC} + f_{ABC}
\end{align*}
\]

One can check that the function

\[
g(f_{AC}, f_{ABC}, f_{BC}, f_{BAC}) = \frac{a}{2} (f_{ABC} + f_{BAC})^2 + \frac{b}{2} [(f_{AC} + f_{BAC})^2 + (f_{BC} + f_{ABC})^2]
\]

readily satisfies these conditions. Then \(g\) can be rewritten as

\[
g(f_{ABC}, f_{BAC}) = \frac{a}{2} (f_{ABC} + f_{BAC})^2 + \frac{b}{2} (1 + (f_{ABC} - f_{BAC})^2).
\]

As the potential is unique up to an additive constant, we consider \(F_\infty = g - b/Id/2\).

Proposition 3. The non-atomic game has a unique Nash equilibrium, which is \(f_{ABC}^* = f_{BAC}^* = 0\).

Proof. Note that:

\[
\begin{align*}
\frac{\partial F_\infty}{\partial f_{ABC}} &= a(f_{ABC} + f_{BAC}) + 2b(f_{ABC} - f_{BAC}) \\
\frac{\partial F_\infty}{\partial f_{BAC}} &= a(f_{ABC} + f_{BAC}) + 2b(f_{BAC} - f_{ABC})
\end{align*}
\]

Hence, the potential is twice differentiable with Hessian matrix

\[
\begin{pmatrix}
a + 2b & a - 2b \\
a - 2b & a + 2b
\end{pmatrix}
\]

This Hessian is definite positive and hence the potential is (strictly) convex. Therefore it has a unique minimum, which is the only Nash equilibrium of the game. Finally, note that \(\forall f_{ABC} \in (0, 1), f_{BAC} \in (0, 1), F_\infty(f_{ABC}, f_{BAC}) \geq 0\) and that \(F_\infty(0, 0) = 0\), which concludes the proof.

To show the uniqueness of the equilibrium in the limiting game, we made use of the fact that the limiting game has a potential which is convex. Yet, not only the limiting game has a convex potential, but also the original one, as we conclude from next theorem, whose proof is a direct application of [5].

Theorem 4. For any finite number of players, the game is a potential game [8] with the potential function:

\[
F(f_{ABC}, f_{BAC}) = bN(f_{ABC} - f_{BAC})^2 + \frac{aN}{2} (f_{ABC} + f_{BAC}) (f_{ABC} + f_{BAC} + 1/N).
\]

Proof. Consider a connection following route \(ABC\). Its cost is \(a(f_{ABC} + f_{BAC}) + b(f_{ABC} + 1 - f_{BAC})\). If this connection switches its strategy to route \(AC\), then its cost becomes \(b(1 - f_{ABC} + f_{BAC} + 1/N)\). Therefore the associated change of cost is

\[
\Delta = a(f_{ABC} + f_{BAC}) + b(f_{ABC} + 1 - f_{BAC}) - b(1 - f_{ABC} + f_{BAC} + 1/N) = a(f_{ABC} + f_{BAC}) + b(2f_{ABC} - 2f_{BAC} - 1/N).
\]

Now:

\[
\begin{align*}
\frac{1}{N}(F(f_{ABC}, f_{BAC}) - F(f_{ABC} - 1/N, f_{BAC})) &= b \left[ (f_{ABC} - f_{BAC})^2 - (f_{ABC} - 1/N - f_{BAC})^2 \right] \\
&+ \frac{a}{2} \left[ (f_{ABC} + f_{BAC}) (f_{ABC} + f_{BAC} + 1/N) - (f_{ABC} + f_{BAC} - 1/N) (f_{ABC} + f_{BAC}) \right] \\
&= \frac{b}{N} (2f_{ABC} - 2f_{BAC} - 1/N) + \frac{a}{N} (f_{ABC} + f_{BAC}) \\
&= \Delta/N.
\end{align*}
\]

By symmetry, the same argument holds for a connection originating from source \(B\).

Note that unlike the framework of non-atomic games, the fact that the game has a convex potential does not imply uniqueness. The reason for that is that in congestion games, the action space over which the potential is minimized is not a convex set (due to the non-splitable nature) so that it may have several local minima, each corresponding to another equilibrium, whereas a for a convex function over the
Euclidean space, there is a unique local minimum which is also a global minimum of the function (and thus an equilibrium of the game).

C. Efficiency

**Theorem 5.** In the non-atomic setting, the only Nash equilibrium is also the social optimum (i.e. the point minimizing the sum of costs of all players) of the system.

**Proof.** The sum of costs of all players is
\[ f_{ABC}C_{ABC} + f_{AC}C_{AC} + f_{BAC}C_{BAC} + f_{BC}C_{BC} \]
\[ = a(f_{ABC} + f_{BAC})^2 + b((f_{BC} + f_{ABC})^2 + (f_{AC} + f_{BAC})^2) \]
\[ = a(f_{ABC} + f_{BAC})^2 + 2b(1 + (f_{AC} - f_{BAC})^2). \]

The minimum is hence obtained for \( (f_{ABC}, f_{BAC}) = (0, 0) \).

Since the game possesses several equilibria, we can expect the PoA (Price of Anarchy - the largest ratio between the sum of costs at an equilibrium and the sum of costs at the social optimum) and PoS (Price of Stability - the smallest corresponding ratio) to be different.

**Theorem 6.** The price of stability of the game is 1 and the price of anarchy is \( 1 + \frac{1}{2\sqrt{N}} \).

**Proof.** From Eq. 3 the price of anarchy (resp. stability) is by definition the maximum (resp. minimum) value over the Nash equilibria of:
\[ \frac{a(f_{ABC} + f_{BAC})^2 + 2b(1 + (f_{AC} - f_{BAC})^2)}{2b} \]

Then, from Theorem 1:
\[ \text{PoA} = \max_{p \leq b/2a} \frac{(2p/N)^2 + 2b}{2b} = \max_{p \leq b/2a} \frac{2pa^2/N^2 + b}{b} \]
\[ = \frac{2a(b/2aN)^2 + b}{b} = \frac{2ab^2}{4ba^2N^2} + 1 = \frac{b}{2aN^2} = 1 \]

and
\[ \text{PoS} = \min_{p \leq b/2a} \frac{(2p/N)^2 + 2b}{2b} = \min_{p \leq b/2a} \frac{2pa^2/N^2}{b} + 1 = 1. \]

We make the following observations:
(i) In the splitable atomic games studied in [6] the PoA was shown to be greater than one for sufficiently small number of players (smaller than some threshold), and was 1 for all large enough number of players (larger than the same threshold). Here for any number of players, the PoS is 1 and the PoA is greater than 1.
(ii) The PoA decreases in \( N \) and tends to 1 as \( N \) tends to infinity, the case of splitable games.
(iii) We have shown that the PoA is unbounded: for any real value \( K \) and any number of players one can choose the cost parameters \( a \) and \( b \) so that the PoA exceeds \( K \). This corresponds to what was observed in splitable games [6] and contrast with the non-atomic setting of single commodity flows (i.e. when there is only one source node instead of two), and arbitrary topology networks where the PoA equals 4/3 [9].

IV. Atomic Semi-Splitable Case and its Splitable Limit (F4 Framework)

The game can be expressed as a 2-player matrix game where each player (i.e. each source node \( A \) and \( B \)) has \( N + 1 \) possible actions, for each of the \( N + 1 \) possible values of \( f_{ABC} \) and \( f_{BAC} \) respectively.

The utility for player \( A \) is
\[ U_A(f_{ABC}, f_{BAC}) = f_{AC}C_{AC} + f_{ABC}C_{ABC} \]
\[ = b - bf_{ABC} + bf_{BAC} \]
\[ + (a - 2b)f_{ABC}f_{BAC} + (a + 2b)f_{BAC}^2 \]

Similarly, for player \( B \):
\[ U_B(f_{ABC}, f_{BAC}) = f_{BC}C_{BC} + f_{BAC}C_{BAC} \]
\[ = b - bf_{BAC} + bf_{ABC} \]
\[ + (a - 2b)f_{BAC}f_{ABC} + (a + 2b)f_{BAC}^2 \]

Note that
\[ \frac{\partial U_A}{\partial f_{ABC}} = -b + (a - 2b)f_{BAC} + 2(a + 2b)f_{BAC} \]
\[ \frac{\partial U_B}{\partial f_{BAC}} = -b + (a - 2b)f_{ABC} + 2(a + 2b)f_{ABC} \]

Hence
\[ \frac{\partial^2 U_A}{\partial f_{ABC}^2} = 2(a + 2b) = \frac{\partial^2 U_B}{\partial f_{BAC}^2}. \]

Therefore, both \( u_A : f_{ABC} \mapsto U_A(f_{ABC}, f_{BAC}) \) and \( u_B : f_{BAC} \mapsto U_B(f_{ABC}, f_{BAC}) \) are (strictly) convex functions. This means that for each action of one player, there would be a unique best response to the second player if its action space was the interval \( (0, 1) \). Hence, for the limit case (when \( N \to \infty \)), the best response is unique. In contrast, for any finite value of \( N \), there are either 1 or 2 possible best responses which are the discrete optima of functions \( u_A : f_{ABC} \mapsto U_A(f_{ABC}, f_{BAC}) \) and \( u_B : f_{BAC} \mapsto U_B(f_{ABC}, f_{BAC}) \). We will however show that in the finite case, there may be up to \( 2 \times 2 = 4 \) Nash equilibria while in the limit case the equilibrium is always unique.

A. Efficiency

Note that the total cost of the players is
\[ \Sigma(f_{ABC}, f_{BAC}) = U_A(f_{ABC}, f_{BAC}) + U_B(f_{ABC}, f_{BAC}) \]
\[ = 2b + (a - 2b)f_{ABC}f_{BAC} + (a + 2b)(f_{ABC}^2 + f_{BAC}^2) \]
\[ = 2b + (a(f_{ABC} + f_{BAC})^2 + 2b(f_{ABC} - f_{BAC})^2 \geq 2b. \]

Further, note that \( \Sigma = 2(F_\infty + b) \). Hence \( \Sigma \) is strictly convex. Also \( \Sigma(0, 0) = 2b \). Therefore \( (0, 0) \) is the (unique) social optimum of the system. Yet, for sufficiently large \( N \) (that is, as soon as we add enough flexibility in the players’ strategies), this is not a Nash equilibrium, as stated in the following theorem:

**Theorem 7.** The point \( (f_{ABC}, f_{BAC}) = (0, 0) \) is a Nash equilibrium if and only if \( N \leq \frac{b}{a} + 2. \)

**Proof.** By symmetry and as \( u_A : f_{ABC} \mapsto U_A(f_{ABC}, f_{BAC}) \) is convex, then \( (0, 0) \) is a Nash equilibrium iff \( U_A(0, 0) \leq
The conclusion follows by convexity.

Therefore

$$U_A(1/N, 0) = b - b/N + (a + 2b)/N^2$$

which leads to the conclusion.

Also, we can bound the total cost by:

$$\Sigma(f_{ABC}, f_{BAC}) = 2b + 2(a - 2b)f_{ABC}f_{BAC} + (a + 2b)(f_{ABC}^2 + f_{BAC}^2)$$

$$\leq 2b + (a - 2b)(f_{ABC}^2 + f_{BAC}^2) + (a + 2b)(f_{ABC}^2 + f_{BAC}^2)$$

$$\leq 2b + 2a(f_{ABC}^2 + f_{BAC}^2)$$

$$\leq 2b + 4a$$

This bound is attained at \(\Sigma(1, 1) = 2b + 2(a - 2b) + 2(a + 2b) = 4a + 2b\). Yet, it is not obtained at the Nash equilibrium for sufficiently large values of \(N\):

**Theorem 8.** (1, 1) is a Nash equilibrium if and only if \(N \leq \frac{2b + a}{3a + b}\).

**Proof.** We have \(U_A(1, 1) = b + 2a\) and

$$U_A(1/N, 1) = 2a - 3a/N - b - 2b/N^2 + a/N^2.$$\

Therefore \(U_A(1/N, 1) \geq U_A(1, 1) \Leftrightarrow 2b + a \geq (3a + b)N\).

The conclusion follows by convexity.

Therefore, for \(N \geq \max(\frac{a}{b} + 2, \frac{2b + a}{3a + b})\) the Nash equilibria are neither optimal nor worse-case strategies of the game.

**B. Case of \(N = 1\)**

In case of \(N = 1\) (one flow arrives at each source node and there are thus two players) the two approach coincides: the atomic non-splitable case (F3) is also a semi-splitable atomic game (F4). \(f_{ABC}\) and \(f_{BAC}\) take values in \(\{0\}, \{1\}\). From Eq. 4 and Eq. 5, the matrix game can be written

$$\begin{pmatrix}
(b, b) & (2b, a + 2b) \\
(a + 2b, 2b) & (2a + b, 2a + b)
\end{pmatrix}$$

and the potential of Eq. 2 becomes

$$
\begin{pmatrix}
0 & a + b \\
\frac{a}{b} + 2 & 3a
\end{pmatrix}
$$

Then, assuming that either \(a\) or \(b\) is non null, we get that \((0, 0)\) is always a Nash equilibrium and that \((1, 1)\) is a Nash equilibrium if and only if \(3a \leq a + b\), i.e. \(2a < b\).

We next consider any integer \(N\) and identify another surprising feature of the equilibrium. We show that depending on the sign of \(a - 2b\), non-symmetric equilibria arise in our symmetric game. In all frameworks other than the semi-splitable games there are only symmetric equilibria in this game. We shall show however that in the limit (as \(N\) grows to infinity), the limiting game has a single equilibrium.

**C. Case \(a - 2b < 0\)**

In this case, there may be multiple equilibria, as shown in the following example.

**Example 9.** Consider \(a = 1, b = 3\) and \(N = 4\), then the cost matrices are given below, with the two Nash equilibria of the game represented in bold letters:

$$U_A = \frac{1}{16} \begin{pmatrix}
48 & 60 & 72 & 84 & 96 \\
43 & 50 & 57 & 64 & 71 \\
52 & 54 & 56 & 58 & 60 \\
75 & 72 & 69 & 66 & 63 \\
112 & 104 & 96 & 88 & 80
\end{pmatrix}, \text{ and}
$$

$$U_B = \frac{1}{16} \begin{pmatrix}
48 & 43 & 52 & 75 & 112 \\
60 & 50 & 54 & 72 & 104 \\
72 & 57 & 56 & 69 & 96 \\
84 & 64 & 58 & 66 & 88 \\
96 & 71 & 60 & 63 & 80
\end{pmatrix}.$$

Note that due to the shape of \(U_A\) and \(U_B\) the cost matrices of the game are transpose of each other. Therefore in the following, we shall only give matrix \(U_A\).

We have the following theorem:

**Theorem 10.** All Nash equilibria are symmetrical, i.e.

$$f_{ABC}^* = f_{BAC}^*.$$

The proof is given in Appendix A.

**D. Case \(a = 2b\) (with \(b > 0\))**

When \(a = 2b\), we shall show that some non-symmetrical equilibria exists.

**Theorem 11.** If \(a = 2b\), there are exactly either 1 or 4 Nash equilibria. For any \(N\), let \(\bar{N} = \lceil \frac{N}{8} \rceil\).

- If \(N \mod 8 = 4\), there are 4 equilibria \((n_{ABC}^*, n_{BAC}^*)\), which are \((\bar{N}, \bar{N})\), \((\bar{N} + 1, N)\), \((N, \bar{N} + 1)\) and \((\bar{N} + 1, N + 1)\).

- Otherwise, there is a unique equilibrium, which is \((\bar{N}, \bar{N})\) if \(N \mod 8 < 4\) or \((\bar{N} + 1, N + 1)\) if \(N \mod 8 > 4\).

**Proof.** The Nash equilibria are the optimal points for both \(u_A\) and \(u_B\). They are therefore either interior or boundary points (i.e. either \(f_{ABC}\) or \(f_{BAC}\) are in \(0, 1\)). We detail the interior point cases in Appendix B. The rest of the proof derives directly from the definition of \(\frac{\partial U_A}{\partial f_{ABC}}\) and \(\frac{\partial U_B}{\partial f_{BAC}}\). Indeed:

$$\frac{\partial U_A}{\partial f_{ABC}} = (a - 2b)f_{ABC} + 2(2b + a)f_{ABC} - b = 8b f_{ABC} - b$$

$$\frac{\partial U_B}{\partial f_{BAC}} = (a - 2b)f_{BAC} + 2(a + 2b)f_{BAC} - b = 8b f_{BAC} - b.$$
E. Case $a - 2b > 0$

**Theorem 12.** If $a - 2b > 0$, there are exactly either 1, 2 or 3 Nash equilibria.

Let $\alpha = \frac{a + 2b}{3a + 2b}$, $\beta = \frac{2a}{3a + 2b}$ and $\gamma = \frac{b}{3a + 2b}$.

Define further $\bar{N} = \lfloor N \gamma \rfloor$ and $z(N) = N\gamma - \bar{N}$. The equilibria are of the form

- Either $(\bar{N}, \bar{N})$, $(\bar{N} + 1, \bar{N})$, $(\bar{N}, \bar{N} + 1)$ if $N$ is such that $z(N) = \alpha$ (mode 3-A in Figure 2)
- Or $(\bar{N} + 1, \bar{N} + 1)$, $(\bar{N}, \bar{N} + 1)$ if $N$ is such that $z(N) = \beta$ (mode 3-B)
- Or $(\bar{N}, \bar{N})$, $\bar{N}$ if $N$ is such that $\alpha < z(N) < \beta$ (mode 2)
- Or $(\bar{N}, \bar{N})$ if $N$ is such that $\beta < z(N) < \alpha + 1$ (mode 1).

| Mode 2 | Mode 3-A | Mode 3-B | Mode 3-A | Mode 3-B |
|--------|----------|----------|----------|----------|
| $\alpha$ | $\beta$ | $\alpha + 1$ | $\beta + 1$ | $\alpha + 1$ |

Fig. 2. Different modes according to different values of $N$.

We illustrate the different modes in the following example.

**Example 13.** Suppose that $a = 10$ and $b = 3$ (we represent only the part of the matrices corresponding to $1/N \leq f_{ABC}, f_{BAC} \leq 4/N$).

If $N = 24$, there are 3 Nash equilibria:

- $1152 \ 1200 \ 1248 \ 1296$
- $1118 \ 1172 \ 1226 \ 1280$
- $1112 \ 1172 \ 1232 \ 1292$
- $1134 \ 1200 \ 1266 \ 1332$

If $N = 26$, there are 2 Nash equilibria:

- $1352 \ 1404 \ 1456 \ 1508$
- $1314 \ 1372 \ 1430 \ 1488$
- $1304 \ 1368 \ 1432 \ 1496$
- $1322 \ 1392 \ 1462 \ 1532$

If $N = 27$, there are 3 Nash equilibria:

- $1458 \ 1512 \ 1566 \ 1620$
- $1418 \ 1478 \ 1538 \ 1598$
- $1406 \ 1472 \ 1538 \ 1604$
- $1422 \ 1494 \ 1566 \ 1638$

If $N = 28$, there is a single Nash equilibrium:

- $1568 \ 1624 \ 1680 \ 1736$
- $1526 \ 1588 \ 1650 \ 1712$
- $1512 \ 1580 \ 1648 \ 1716$
- $1526 \ 1600 \ 1674 \ 1748$

F. Limit Case: Perfectly Splitable Sessions

We focus here in the limit case where $N \to +\infty$.

**Theorem 14.** There exists a unique Nash equilibrium and it is such that $f_{ABC}^* = f_{BAC}^* = \frac{b}{3a + 2b}$.

*Proof.* Note that $\frac{\partial U_A}{\partial f_{ABC}}(1) > 0$ and $\frac{\partial U_B}{\partial f_{BAC}}(1) > 0$. If $f_{ABC} = 0$ then $f_{BAC}^* = \frac{b}{2a + b}$, which implies that $-b + \frac{3(a - 2b)}{2a + b} \geq 0$, which further implies that $-a - 6b > 0$ which is impossible. Hence $f_{ABC} > 0$. Similarly $f_{BAC} > 0$ which concludes the proof.

Recall that the optimum sum (social optimum) is given by $(0,0)$ and that the worse case is given by $(1,1)$. Hence, regardless of the values of $a$ and $b$, at the limit case, we observe that there is a unique Nash equilibrium, that is symmetrical, and is neither optimal (as opposed to F3), nor the worst case scenario. The price of anarchy is then:

$$P_oA = P_oS = \frac{2b + 2f_{ABC}^2}{2b} = 1 + \frac{ab}{(3a + 2b)^2}.$$  

V. Conclusions

We revisited in this paper a load balancing problem within a non-cooperative routing game framework. This model had already received much attention in the past within some classical frameworks (the Wardrop equilibrium analysis and the atomic splittable routing game framework). We studied this game under other frameworks - the non splittable atomic game (known as congestion game) as well as a the semi-splittable framework. We have identified many surprising features of equilibria in both frameworks. We showed that unlike the previously studied frameworks, there is no uniqueness of equilibrium, and non-symmetric equilibria may appear (depending on the parameters). For each of the frameworks we identified the different equilibria and provided some of their properties. We also provided an efficiency analysis in terms of price of anarchy and price of stability. In the future we plan to investigate more general cost structures and topologies.

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Proof. Let $(f_{A B C}^*, f_{B A C}^*)$ be a Nash equilibrium in the interior (i.e. $0 < f_{A B C} < 1$ and $0 < f_{B A C} < 1$). Then $f_{A B C}$ and $f_{B A C}$ are the (discrete) minimizers of $x \mapsto U_A(x, f_{A B C})$ and $x \mapsto U_B(f_{A B C}, x)$ respectively. Further:

\[
\begin{align*}
\frac{\partial U_A}{\partial f_{A B C}} &= -b + (a - 2b)f_{B A C} + 2(2b + a)f_{A B C} \\
\frac{\partial U_B}{\partial f_{B A C}} &= -b + (a - 2b)f_{A B C} + 2(a + 2b)f_{B A C}
\end{align*}
\]

The optimum values are therefore respectively:

\[
x_A = \frac{b - \theta f_{B A C}}{\lambda} \quad \text{and} \quad x_B = \frac{b - \theta f_{A B C}}{\lambda}
\]
Lemma 17. If $(A, A)$ is a Nash equilibrium then $(A+1, A+1)$ is not a Nash equilibrium.

Proof. Suppose that $(A, A)$ and $(A+1, A+1)$ are two Nash equilibria. Then $U_A(A, A) \leq U_A(A+1, A)$ and $U_A(A+1, A+1) \leq U_A(A+1, A+1)$, which implies

$$\begin{cases} -bAN + (a - 2b)A^2 + (2b + a)A^2 & \leq -b(A+1)N + (a - 2b)A(A + 1) + (2b + a)(A+1)^2 \\ -b(A+1)N + (a - 2b)A(A + 1) + (2b + a)(A+1)^2 & \leq -bAN + (a - 2b)A(A + 1) + (2b + a)A^2 \\ \Rightarrow & \begin{cases} bN \leq (a - 2b)A + (2b + a)(2A + 1) \\ (a - 2b)(A + 1) + (2b + a)(2A + 1) \leq bN \end{cases} \\ \Rightarrow (a - 2b)(A + 1) \leq bN - (2b + a)(2A + 1) \leq (a - 2b)A \\ \Rightarrow (a - 2b)(A+1) \leq bN - (2b + a)(2A + 1) \leq (a - 2b)A \\ \Rightarrow (a - 2b)(A+1) \leq (a - 2b)A \\ \text{and therefore } a - 2b \leq 0 \text{ which is impossible.} & \end{cases}$$

Therefore the different possible combinations are mode 1, mode 2, mode 3-A and mode 3-B in Figure 2.

We first start by the occurrence of mode 3-A:

Lemma 18. Suppose that $a - 2b > 0$. Suppose that $(A, A)$ and $(A+1, A)$ are two Nash equilibria. Then

$$A = \frac{bN - 2b - a}{3a + 2b}.$$

Proof. Suppose that $(A, A)$ and $(A+1, A)$ are two Nash equilibria. Then necessarily $U_A(A, A) = U_A(A+1, A)$. Hence

$$\begin{align*} -bAN + (a - 2b)A^2 + (2b + a)A^2 &= -b(A+1)N + (a - 2b)A(A + 1) + (2b + a)(A+1)^2 \\ &\Rightarrow (a - 2b)(A + 1) + (2b + a)(2A + 1) = Nb \\ &\Rightarrow (3a + 2b)A = Nb - 2a \end{align*}$$

which leads to the conclusion.

Hence, the system is in mode 3-A iff $bN - 2b - a$ is divisible by $3a + 2b$ or in other words, if $N$ is of the form $(3a + 2b)K + 2a$ for some integer $K$.

We then move on to Mode 3-B:

Lemma 19. Suppose that $a - 2b > 0$. Suppose that $(A + 1, A+1)$ and $(A+1, A)$ are two Nash equilibria. Then

$$A = \frac{bN - 2a}{3a + 2b}.$$

Proof. Suppose that $(A + 1, A+1)$ and $(A+1, A)$ are two Nash equilibria, then $U_1(A+1, A+1) = U_1(A, A+1)$. This implies

$$\begin{align*} -Nb(A + 1) + (a - 2b)(A+1)^2 + (2b + a)(A+1)^2 &= -NbA + (a - 2b)A(A + 1) + (2b + a)A^2 \\ &\Rightarrow (a - 2b)(A + 1) + (2b + a)(2A + 1) = Nb \\ &\Rightarrow (3a + 2b)A = Nb - 2a \end{align*}$$

which concludes the proof.

Finally, for Mode 2:

Lemma 20. Suppose that $a - 2b > 0$. Suppose that $(A, A+1)$ and $(A+1, A)$ are only two Nash equilibria. Then

$$(3a + 2b)A + 2b + a < bN < (3a + 2b)A + 2a.$$

Proof. Suppose that $(A, A+1)$ and $(A+1, A)$ are two Nash equilibria, then:

$$\begin{align*} U_A(A, A+1) &\leq U_A(A+1, A+1) \text{ and} \\ U_A(A+1, A) &\leq U_A(A, A) \text{ ie} \\ bN &\leq (3a + 2b)A + 2a \\ (3a + 2b)A + 2b + a &\leq bN \end{align*}$$

The conclusion comes from Lemma 18 and 19, since neither $(A, A)$ nor $(A+1, A+1)$ are Nash equilibria.

Finally the system is in mode 1 if it is not in any over modes. One can then check that the boundary cases found in Theorem 16 corresponds to the case where $A = 0$ which concludes the proof.