A novel beamforming based model of coverage and transmission costing in IEEE 802.11 WLAN networks

Mehdi Guessous, Lahbib Zenkouar
Mohammadia School of Engineers, Electrical Engineering Departement, Mohammed V University In Rabat, 10000, Morocco

1 Introduction

Designers face problems of two natures when building WLAN networks: issues that are inherent to radio resources’ planning and those concerning their integration with other network parts and upper-layer services in response to developing customers’ application needs such as mobility, real-time, interactive applications, business intelligence, and on-presence analytics. An accurate design should consider thoroughly both aspects and base its decision on a solid theoretical approach, on-field feedbacks, and best practices.

Design best practices dictate running two site surveys: one at the beginning of the project, before network’s deployment, and a second, after network’s deployment, to confirm resources’ planning results and to calibrate the system’s parameters in accordance to the real network’s condition. An optional survey may be required if radio environment or its utilization has changed. An optional survey may be required if radio environment or its utilization has changed, to confirm resources’ planning results and to calibrate the system’s parameters in accordance to the real network’s condition. An optional survey may be required if radio environment or its utilization has changed, to confirm resources’ planning results and to calibrate the system’s parameters in accordance to the real network’s condition.

IEEE 802.11 WLAN indoor networks face major inherent and environmental issues such as interference, noise, and obstacles. At the same time, they must provide a maximal service performance in highly changing radio environments and conformance to various applications’ requirements. For this purpose, they require a solid design approach that considers both inputs from the radio interface and the upper-layer services at every design step. The modelization of radio area coverage is a key component in this process and must build on feasible work hypotheses. It should be able also to interpret highly varying characteristics of dense indoor environments, technology advances, service design best practices, end-to-end integration with other network parts: Local Area Network (LAN), Wide Area Network (WAN) or Data Center Network (DCN). This work focuses on Radio Resource Management (RRM) as a key tool to achieve a solid design in WLAN indoor environments by planning frequency channel assignment, transmit directions and corresponding power levels. Its scope is limited to tackle co-channel interference but can be easily extended to address cross-channel ones. In this paper, we consider beamforming and costing techniques to augment conventional RRM’s Transmit Power Control (TPC) procedures that market-leading vendors has implemented and related research has worked on. We present a novel approach of radio coverage modelization and prove its additions to the cited related-work’s models. Our solution model runs three algorithms to evaluate transmission opportunities of Wireless Devices (WD) under the coverage area. It builds on realistic hypotheses and a thorough system operation’s understanding to evaluate such an opportunity to transmit, overcomes limitations from compared related-work’s models, and integrates a hierarchical costing system to match Service Level Agreement (SLA) expectations. The term “opportunity” in this context relates also to the new transmission’s possibilities that related-work misses often or overestimates.
changed and might affect the overall network capacity. The first survey qualifies mainly the exposure to on-reach foreign autonomous radio systems, and radio characteristics of the surface to cover (walls, floors, and other obstacles). The second site survey confirms the conformance of the actual deployment to design constraints in two ways:

1. by running a passive in-data-path survey that is based on passively reported statistics such as RSSI, SNR, PHY, MAC errors, packet count, etc. at radio interface level,

2. and an active one where in-data-path patterns simulate wireless client’s traffic classes to gather actively statistics on Jitter, RTT, or any other measure concerning the rendered service, application or experience.

This approach is not very accurate as it lies on a set of preconfigured unchangeable parameters that result from special case deployments and testing contexts, which may be completely different from the on-field reality. In the market-leading implementations such as Cisco TPC or Aruba ARM, we observe that at a certain point, a reference is made to an “ideal” preconfigured parameter. The third neighbor’s RSSI and a predefined hysteresis threshold parameters are used in the first case, and the “coverage index” parameter in the second case, to decide on transmit power level planning network wide.

Inaccuracies come also from studies when they model the system as a pre-shaped radio coverage area in the form of a hierarchy of disks that delimit transmission ranges from interference or not-talk ones. Some limitations arise also from no-site survey techniques that base their radio resource management solely on WLAN reported measures. Other limitations come from simplifications such as to consider that a client association and the corresponding CSMA/CA mechanisms rely entirely on the strongest access point’s RSSI, because most of the interferences do not occur at MAC level, and radio measurements may differ from a vendor to another. Then it is necessary to ensure that model analysis inputs and outputs do not result in a contradiction.

Motivated by advances in beamforming techniques, especially from an array signal processing perspective, which make it possible to radiate energy in any direction and to easily estimate signal’s direction of arrival, this work solution model aims at fixing many of previous limitations by considering the opportunity for an access point to transmit in one specific direction. This opportunity processing accepts data from upper-layer services such as to achieve a complete end-to-end integration with other network parts.

As it will be demonstrated in this work, the number of transmit directions at access point level, could be optimized in conjunction with planning transmit power levels and channel assignment to maximize the overall network capacity. A cost-based approach prices in a timely manner each direction for an eventual transmission. Access points in this scheme discover each other over-the-air and report useful information on transmit directions, power levels and channels, to a central intelligence that coordinates the overall network operation. The ultimate result is:

1. Cancellation of co-channel interferences in a majority of deployment cases.

2. Processing of new transmission opportunities that are missing in conventional work.

3. Enhancement of end-to-end network performance.

In the upcoming section, we present a foundation on unified WIFI architectures and beamforming as they relate to this work. In Sect. 4, we discuss more formally the problem and in Sect. 5, we present our solution model. Sect. 6 discusses our solution results. In the end, we conclude and further our work. This paper is an extension of work originally presented in 2017 International Conference on Information Networking (ICOIN) [3].

2 Related Work

Co-channel interference in WLAN networks is a major problem that has been widely studied. To tackle this issue RRM and related techniques such as Transmit Power Control (TPC), Dynamic Channel Assignment (DCA), constitute a very accurate solution. If we consider TPC that is the focus of this work, the related-work’s approaches differ from each other in terms of the adopted interference’s model, inputs TPC may work on, and their processing (predictive, heuristic, etc.). We further focus on related-work’s adopted interference models.

To our knowledge, all models and derived TPC processing have considered only the transmission power level as a degree of freedom to limit co-channel interference. This work claims that the transmission direction could be an additional degree of freedom to overcome other models’ limitations when it comes to modeling irregular coverage areas in indoor WLAN environments.

Authors in this work [4] concentrate, from a lower layer perspective, on the co-channel interferences as a function of the estimated distance between the Access Points (AP) and the Wireless Devices (WD). In this scheme, the WDs estimate the distance based on the RSSI information sent by the APs in RTS control packets. The transmission power level adjusts accordingly to achieve a better network performance and interference cancellation. The issue with this model is that the power level adjustment affects other on reach WDs and APs communications. In addition, this model does not include cases where the WD does not simply receive the RTS packets.

In [5], a WD measures the amount of interference as a function of the local AP’s load, its signal’s
strength and loads from the distant APs. Here interference is a linear function of the AP’s load. This is interesting but as opposed to our work, this model misses the interpretation of interference from an energy radiation perspective. In our work, we still include AP’s load consideration in the SLA applied to the processing of transmit opportunities.

Depending on the coverage area pattern: disks or Voronoi zones, the amount of interference in \[6\], is a function of different AP’s areas overlap in the first case and to their borders in the second one. This work model is very accurate to describe how an AP’s energy radiation could affect other neighboring APs. However, it is still insufficient to interpret many cases specific to indoor WLAN deployments that relate to on-reach and unreachable AP’s. Subsection C of Sect. 4 discusses these cases in detail.

The authors in \[7\] consider both MAC and PHY layer inputs: data payload length, path loss condition, and frame retry counts, to find out the suitable PHY mode and power level combination. This procedure requires a control packet exchange that is similar to conventional RTC/CTS for this adaptation. This model is easy to implement but it is insufficient to interpret many cases specific to indoor WLAN similarly to the previous work. In addition and similarly to the first cited work, any PHY mode and corresponding power level change apply to all neighboring APs and WDs indistinguishably.

In \[8\], the authors concentrate on upper layer application performance such as FTP and HTTP, to find out an optimal power scheme or more exactly, an optimal combination between transmit power and supported load for a given distance between nodes. This model considers SLA as in the second and fourth cited works and augments its processing to include “behavioral” protocol aspects. However, the corresponding model misses the lower-level interpretation of AP’s radiated energy.

The authors in \[9\], approach the problem from an inter-protocol coordination point of view: WIFI, BT, etc. which may be very helpful to base an integrated-system wide transmit decision or “etiquette” on the utilization of shared radio resources. In this scheme, all wireless devices broadcast the information on spectrum usage. This information includes transmit power level and frequency channel of use. In addition and based on costing policies, the system allocates resources: frequency, power and time, to wireless devices. This work is a generalization of the first and fourth previously cited works and may incur the same limitations.

In this work, we review the conventional co-channel wireless coverage models and show that the system could process more transmission opportunities and still conform to the SLA. In these works \[4\] \[5\], some of the transmission opportunities were missed in areas that were considered falsely as interference ranges or worst as no-talk ones. Our solution model considers inputs from upper-layer services to conform to the SLA on the end-to-end wireless client’s experience as in works \[7\] \[8\] \[9\]. In addition, it takes advantage of the technological advances in beamforming and related techniques, to introduce, at a conceptual level in indoor WLAN networks, the direction of transmission as a new radio resource added to frequency channel and power level, to enhance work’s like \[9\] results.

3 Theoretical Background

The next two subsections describe WIFI’s unified architecture in addition to the beamforming techniques as they relate to our study. The main objective of this foundation is to justify the feasibility of the hypotheses we base our study on. These hypotheses relate to the possibility to correlate reported radio interface’s information from different APs, to coordinate their operation network-wide, to concentrate the radiated energy in any direction, in a timely manner, and to estimate accurately the direction of known and unknown sources’ signals.

3.1 WIFI’s Unified Architecture

In dense indoor networks, the transmission is difficult to model and depends on radio environment’s characteristics such as obstacles, interference, background noise, density of wireless clients, mobility applications, etc.

In this context, standalone APs’ architectures do not scale with high number of APs and WDs that require high class QoS treatment. Such architectures are replaced gradually by controller-based or “unified” ones. They are marked as unified for two reasons:

1. a central decision-making and intelligence, that is a Wireless LAN Controller (WLC), manages the overall network’s operation.
2. the WLAN integrates with the overall network parts: LAN, WAN, DCN, etc. from especially a QoS perspective.

The market-leading vendors implement such a central decision-making processor mainly in three ways:

1. appliance WLC-based,
2. virtual system WLC-based,
3. distributed AP-based.

In the latter implementation, the APs take over the WLC’s role. The first two implementations require a WLC, a virtual or physical appliance, which is reachable by all network APs over the wire. Examples of such WLCs are Cisco 8540 Wireless Controller and Aruba 7280 Mobility Controller.

Cisco unified architecture \[10\] defines two protocols:

1. CAPWAP, used by APs to build protocol associations to the active WLC.
2. NDP, to send messages over the air (OTA) for APs to exchange proprietary and standard management or control information.

In addition to these protocols, Cisco APs integrate a set of on-chip RRM techniques: CLIENTLINK and CLEANAIR that monitor and measure radio environment characteristics among other features. The WLC gathers this information via the already established CAPWAP tunnels to APs. Further, platforms such as Cisco Prime Infrastructure (CPI) and Mobility Services Engine (MSE) extend the capability of CLEANAIR to perform analytics, locate clients, interferers, and build heat maps. Based on the APs’ reported information, the WLC computes the channel assignment and power levels map network wide. Its decision still conforms to the pre-configured policy sets. Each of these sets defines a number of configurable variables and unchangeable settings such as acceptable signal levels, tolerable noise levels, usable power levels, frequencies and channels, etc.

In this work context, the WIFI unified architecture guarantees a coordinated operation between all network elements at a very low level, an accessible distributed intelligence, and a centralized decision-making. It focuses on how to enhance the centralized decision-making at WLC level and especially RRM processing. RRM is the set of tools, algorithms and services that processes inputs from AP’s radio and LAN interfaces and outputs a wireless area coverage plan or map that conforms to a predefined utility function.

3.2 Beamforming

The majority of WLAN communicating systems are equipped with omnidirectional antennas or a set of limited number of unidirectional antennas to obtain an equivalent energy radiation’s pattern. Ease and cost of such hardware configurations are some of the benefits of such designs but they lack many aspects regarding interference and noise cancellation, signal sources’ localization, and power consumption.

Beamforming techniques by definition relate to both the direction of energy radiation and the estimation of signal’s arrival direction and from an array signal processing perspective, they offer the possibility to tackle previous issues and design limitations to the next level in three ways:

1. the radiation of energy toward actual receivers allows better performance and less impact on the other system’s elements.
2. the estimation of direction of known and unknown sources allows better costing of a given directed transmission.
3. the on-chip beamforming techniques allows for a hardware real-time adaptation to extremely changing radio environments like in our context.

With reference to [11], beamforming concerns both sides of a communicating system: the emitter and the receiver. It allows the radiated energy to be concentrated in one direction and to estimate its corresponding source’s location for both legitimate and rogue interferers at receiver level. Basically, beamforming could be achieved mechanically by manually or electronically gearing a directional antenna. From a signal processing perspective, beamforming is achieved by changing certain transmitter’s characteristics such as array elements’ phase shifting, source signals’ amplitude increasing or addition weighting. Additionally, the desired array gain and beam’s direction depend on the number and geometry of array elements.

To ease our study we consider that array beamformers achieve equivalent performance to mechanical ones concerning both the resultant beam radiation’s angle and signal’s gain.

Let us consider an antenna with a beamwidth of $2 \theta_n$ such as the radiated energy in the zone delimited by this angle is equal to the maximum energy radiated by the antenna minus $n \text{ dB}$. $n$ is calculated in such manner to allow an AP to transmit in all corresponding directions at the same time without interfering with each other. A rough estimation of this number is:

$$N \approx (2 \pi)/(2 \theta_n) \quad (1)$$

In the contexts of [12] [13] studies on antenna arrays, the beamwidth is expressed as a function of the distance between array elements $d$, the number of elements $M$, and the wave length $\lambda$:

$$\Delta \theta_{\text{main}} \approx (2 \lambda)/(d \cdot M) \quad (2)$$

In general, the evolving antenna array’s beamformers could be classified as data independent, statistically optimum, adaptive or partially adaptive [11]. In this work, data dependent data beamformers (statistically optimum and adaptive) are of interest. Some of these beamformers are Multiple Sidelobe Canceller (MSC), Reference Signal (RS), Max SNR, Linearly Constrained Minimum Variance (LCMV), Lean Mean Square (LMS), Recursive Least Squares (RLS).

The other part of beamforming relates to the estimation of the Direction of Arrival (DOA). DOA estimation methods may include Bartlett, Capon, MUSIC, Min-Norm, DML, SML, WSF, Root-Music, ESPRIT, IQML, and Root-WSF. SML, WSF and Root-WSF are statistically the most efficient depending on the array geometry [14]. They could be yield into two main categories: spectral-based techniques, which are computationally optimal, and parametric methods, which are more accurate than the previous ones.

Recent algorithms are more accurate in the estimation of signal’s arrival of both known and unknown sources. They depend on the array size, antenna’s radiation pattern, source signals’ correlation,
data statistics, corresponding data generation framework, among others. However, for the rest of this study we could consider that beamforming techniques allow:

1. sufficient number of directions to mimic an omnidirectional operation,
2. geographically any direction is achievable,
3. patterns from different directions at the same AP level do not interfere and are uncorrelated,
4. on-chip real-time transmits and synchronization.

4 Problem Statement

In this section, we formalize mathematically the problem of determining the opportunity to transmit at any point under the wireless coverage area. We first focus on related-work’s models. Then in the next sections, we present our solution model and compare its results to preceding studies.

In this problem statement, we focus mainly on how related-work estimates the interference at a given point under the wireless coverage area, applies radio and upper-layer constraints, and processes the corresponding transmit opportunity.

To ease this work we consider the wireless coverage area as a two-dimensional Euclidean plane. The APs and WDs are points of this plane. They transmit in the same channel and cause the majority of co-channel interference in this area. This study focuses on co-channel operation but is easily extendible to tackle cross-channel interference or noise issues in the context described before.

Let us define:

\[ \{AP_1, AP_2, ..., AP_n\} \] — set of n access points.

\( P_j \) — a point under wireless coverage area.

\((x_i, y_i)\) — coordinates of \( AP_i \) or \( P_i \) points in an Euclidean two-dimensional plane.

\( w_{i, \text{current}}, w_{i, \text{min}}, w_{i, \text{max}}, w_{i, \text{opt}} \) — \( AP_i \)'s corresponding current, minimum, maximum and optimum transmit power levels.

\( d_{i,j} \) — distance between \( AP_i \) and \( P_j \) points.

\( I(), O() \) — interference and transmit opportunity functions.

We categorize related-work’s models into two categories: Range-based and Zone-based. In the upcoming subsections, we describe each of them and discuss their limitations.

4.1 Range-based Model

In works similar to [4], an AP’s wireless coverage corresponds to one of these ranges: a transmission, interference or no-talk range. These ranges correspond to the estimation of the distance between the AP and a receiving point \( P \) (AP or WD). Further, they consider that an AP’s wireless coverage pattern is omnidirectional in the form of a circle or a disk. In this configuration, the three circles that correspond to each range type and centered at the AP define the whole AP’s wireless coverage area as in Figure [1].

![Figure 1: Range-based model’s representation of an AP’s wireless coverage](image)

Let us further define:

\[ C_{i, tx}, C_{i, if}, C_{i, nt} \] — \( AP_i \)'s attached circles that delimit corresponding transmission, interference and no-talk ranges.

\[ R_{i, tx}, R_{i, if}, R_{i, nt} \] — \( AP_i \) corresponding ranges.

If we suppose that:

\[ R_{i, tx} \leq R_{i, if} \leq R_{i, nt} \] (3)

Then the interference and transmit opportunity are given as follows:

\[ I(P_i) \approx \sum_{k=1}^{3} a_k \sum_{j \neq i} \beta_j \cdot \text{intersection}(C_{j,k}, C_{i,1}) \] (4)

\[ O(P_i) \approx \frac{1}{\sum_{k=1}^{3} a_k \sum_{j \neq i} \beta_j \cdot \text{intersection}(C_{j,k}, P_i)} \] (5)

A weighted version of these functions is given further to account for inaccuracies and other constraints. The \( a \) and \( \beta \) weights are meant to reflect the non-linearity of interference addition, the power level’s effect on interference strength, and the type of transmission’s range. Here we consider that the interference at a given point \( P_i \) is a function of other \( AP_j \)'s
signals except from the \( P_i \) to which the point is associated. The opportunity processing is slightly different as it considers all AP's interference to \( P_i \) that is not associated to any \( P_i \) yet.

### 4.2 Zone-based Model

Works such as [5] [6] that are based on this model are different from the previous ones as ranges here are not function only of the corresponding AP transmission's characteristics: channel, power level, etc., but depend also on the neighboring APs. The result of this is that the transmission range shape is no more a solid circle but a convex polygon with straight sides. Each straight side defines a borderline that separate two neighboring APs' transmission ranges. Consequently, it is important to note that a point in a transmission range of one AP could not be in another AP's transmission range. A Zone-based AP's wireless coverage is represented in Figure 2.

![Zone-based model's representation of an AP's wireless coverage](image)

**Figure 2:** Zone-based model's representation of an AP's wireless coverage

Let us further define:

\[
G_i \quad \text{— AP}_i \text{ corresponding transmission range polygon or zone.}
\]

Then the interference and transmit opportunity are given as follows:

\[
I(P_i) \approx \alpha_1 \sum_{j \neq i} \beta_j \cdot \text{intersection}(C_{j,1}, C_{i,1})^{-\lambda} + \sum_{k=2}^{3} \alpha_k \sum_{j \neq i} \beta_j \cdot \text{intersection}(C_{j,k}, C_{i,1})
\]

\[
O(P_i) \approx \frac{1}{\sum_{k=2}^{3} \alpha_k \sum_{j \neq i} \beta_j \cdot \text{intersection}(C_{j,k}, G_i)}
\]

Similarly to formulas 4 and 5, \( \alpha \) and \( \beta \) weights are meant to represent the impact of AP's transmission characteristics. \( \lambda \) is representative of the neighboring APs impact on \( AP_i \) borderlines. In this configuration, only transmission range is affected. The processing of other ranges are the same as in the previous model. It is also to note that opportunity in this model correspond to \( P_j \) in \( AP_j \) transmission's range or zone \( G_j \), rather than intersection of the neighboring APs like in the previous model.

### 4.3 First Observations

The presented models' functions of interference and opportunity do not reflect the accuracy of interference and opportunity measurements but rather the concept behind them and their possibilities to account for different WLAN design cases and aspects. At this stage, we see clearly that both models are limited in these ways:

1. both models are limited to consider that the strength of interference is only inversely proportional to the distance of an AP from interfering neighbors.
2. both models would interpret an increase in a transmission power level as an expanded reach in all directions: uniformly in case of Range-based models but depending on neighboring APs in case of Zone-based ones.
3. a point could not be in two transmission ranges of two different APs at the same time in Zone-based models.
4. transmission range does not depend on the strength of interference in Range-based models.
5. both models would interpret falsely obstacles to the signal propagation, as a weaker signal from an AP in the context of indoor WLAN networks does not mean necessarily that this AP is out of reach.
6. similarly to the previous point a stronger signal does not mean necessarily that an AP is in reach: it signal may be guided under some conditions.

The consequence of these limitations in indoor WLAN networks, is to reduce or overestimate the transmit opportunities that the network may offer. The upcoming section presents our solution to fix these modelization limitations.

### 5 Solution model

Our solution model is suitable for WLC-controlled indoor networks in the already explained conditions. For the purpose of this study, we suppose that APs are equivalent, support MIMO technologies such as beamforming and DOA, and operate over the same channel. The wireless devices (WD) are equipped with omnidirectional antennas and transmit at a lowered power level in comparison with APs.

The model runs three algorithms:
1. Transmit Direction Discovery (TDD) algorithm that builds a per direction neighbor discovery map, computes the optimal number of transmit directions and the corresponding per direction power levels.

2. Transmit Direction Mapping (TDM) algorithm estimates the impact that may have an AP on the network when it transmits in a specific direction and builds consequently, a per-direction transmit cost-based map that represents this information.

3. Transmit Direction Opportunity (TDO) algorithm processes data from both TDM and the upper-layer network services to optimize the transmission opportunities and build a per-direction transmit opportunity-based map to represent this information.

The next workflow in Figure 7 is an overview of our solution processing.

At initialization, the number of transmission directions is set to the minimum and the power level to the maximum. TDD processing stops after all APs are discovered and exactly one or no neighbor AP is discovered at any AP direction.

Based on results from TDD, TDM categorizes the coverage area points and costs a potential transmission at each of them. The coverage area points belong to one of these three categories: Not-On-Any-Transmit-Direction (NOATD), On-Discovered-Neighbor-Direction (ODND), and Not-ODND-On-Transmit-Direction (NOOTD). After the coverage area point’s categorization, the system processes the transmission costs.

TDO algorithm evaluates the opportunity to transmit at a specific coverage area point. It returns the AP that may handle the transmission and the corresponding direction. This processing accepts inputs from TDM and the upper-layer SLA. The SLA processing is tight to the AP’s wired network interface as opposed to the radio interface.

5.1 TDD algorithm

TDD algorithm processes the optimal number of transmission directions that APs may support and the corresponding per-direction transmit power levels. To ease this study, we consider these hypotheses and simplifications:

1. only a 2D plane operation is considered.
2. a uniform beamwidth in all directions.
3. APs are able to achieve an emulated omnidirectional operation.
4. two signals from the same AP in two different directions could not interfere.
5. all APs have the same optimal and maximal numbers of transmission directions and corresponding power levels.

6. neighbor discovery is bidirectional, occurs at the opposite direction, and at the same transmit power level.

7. an AP could not discover the same neighbor AP in two separate directions.

8. an AP could not discover itself.

9. at least one neighbor AP is reachable in any AP direction.

Points 2, 3, 4 and 5 are idealistic physical characteristics of AP’s beamforming implementation. The 9th point indicates that a co-channel interference condition is detected from a neighboring AP. The 6th, 7th and 8th assumptions are further developed in separate work to cover and interpret cases where:

1. the optimal numbers of transmission directions and power levels are not the same among APs.

2. neighbor discovery is unidirectional or asymmetric.

Let us define:

\((d_i, w_i)\) — the direction and power level associated with \(AP_i\),

\(d_{-j}(x, y)\) — the opposite direction of \(d_j(x, y)\) in an euclidean 2D plane.

\(L(AP_i, d_j, w_k)\) — the set of discovered AP neighbors by \(AP_i\) in \(d_j\) direction at \(w_k\) transmit power level.

\(a(i, j), b(i, j), c(i, j)\) — respectively the segment \(L()\) slope, intercept and end point.

\(X(AP_i, d_j, w_k)\) — the set of discovered AP neighbors by \(AP_i\) in \(d_j\) direction at \(w_k\) power level.

\(O(AP_i, AP_j)\) — a segment that represents an obstacle between \(AP_i\) and \(AP_j\).

We formalize the problem as:

\[ \forall i \in \mathbb{N}, \quad \exists j, k \in \mathbb{N} \quad \text{s. t.} \quad X(AP_i, d_j, w_k) \neq \emptyset \]  \hfill (8)

\[ \forall i, j, k \in \mathbb{N}, \quad AP_i \notin X(AP_i, d_j, w_k) \]  \hfill (9)

\[ \forall i, j, j', k \in \mathbb{N}, \quad j \neq j', \quad X(AP_i, d_j, w_k) \cap X(AP_i, d_{j'}, w_k') = \emptyset \]  \hfill (10)

\[ \forall i, i', j, j', k \in \mathbb{N}, \quad i \neq i', \quad X(AP_i, d_j, w_k) \cap X(AP_i', d_{j'}, w_k') = \emptyset \]  \hfill (11)

\[ AP_i \in X(AP_i, d_j, w_k) \equiv AP_i \in X(AP_i', d_j, w_k') \]  \hfill (12)

\[ d_{-j} = d_{-j}, \quad w_k = w_{k'} \]

\[ \forall i, j \in \mathbb{N}, \quad L(AP_i, d_j) = \{ a_{i, j} \cdot x + b_{i, j} \mid x \in [x_i, x_i + c_{i, j}] \} \]
The APs’ distribution on the plan could be any random function or resulting from on-site surveys. However, we consider that the minimum and maximum distances between any of these APs are linear functions respectively of the corresponding minimum and maximum supported power levels. Figure 4 represents a simple network of seven APs with eight transmission directions each. Eight beams in red color are formed roughly around AP\textsubscript{i} corresponding transmission directions.

The AP neighbor’s per-direction discovery is based on the distance between APs that are on each other theoretical transmission range, on-site surveys, and radio interface sensing. Additionally the solution model allows the discovery of these two design special-case neighbors:

1. “isolated” neighbor AP that is at reach but separated by an obstacle.
2. “guided” neighbor AP that is not at reach but received with an acceptable signal level.

The optimization of APs transmission directions’ number is a three-step process. For directions with more than one discovered neighbor, we calculate a new number such as to have the least possible number of neighbors per any AP’s direction. Otherwise, we adjust the power levels to get some of these APs out of reach from the local AP. If no success, we revert to Range-based-like interference scheme to cost this transmission zone.

A simpler form of the proposed algorithm is given next:

\begin{align*}
1: \quad & (d^{\text{opt}}, w^{\text{opt}}) \leftarrow (d^{\text{min}}, w^{\text{max}}) \\
2: \quad & X \leftarrow \bigcup_{j=1}^{\text{opt}} \mathcal{X}(AP_i, d^{\text{max}}_j, w^{\text{opt}}) \\
3: \quad & \text{for } j = 1 \text{ to } \text{opt} \text{ do} \\
4: \quad & \text{if } \text{opt} \leq \text{max} \text{ then} \\
5: \quad & \text{if card}(X(AP_i, d^{\text{opt}}_j, w^{\text{opt}})) > 1 \text{ then}
\end{align*}
The optimum numbers of directions and power levels are respectively initialized to the minimum and the maximum numbers supported by APs. For every AP’s direction, we check the number of discovered neighbors. If many neighbors are detected, we multiply the initial number of directions by two until we obtain only one neighbor per direction. If the maximum number of direction is reached then we reduce by one level the power and try to get the same result without altering X. X is the set of all neighboring APs that were detected previously in the maximum supported directions and at the maximum supported power level.

5.2 TDM algorithm

In the previous section, TDD returned the optimal number of transmission directions, the corresponding optimal number of power levels and the sets of AP’s per-direction discovered neighbors. In addition to these elements, TDD interprets the presence of two kinds of obstacles: those that are preventing isolated neighbors from seeing each other, and those that are creating new transmission opportunities among guided neighbors. One way for TDD to interpret such kind of obstacles is by comparing the on-the-air discovery’s results with on-site surveys’ information. Based on the previous elements, TDM algorithm builds a transmission-costing map for APs to reach any point under the overall wireless coverage area.

A simpler form of the proposed algorithm is given next:

6: \[ d_{\text{opt}} \leftarrow d_{2\text{opt}} \]
7: \[ \text{end if} \]
8: \[ \text{else if card}(X(AP_i, d_{j,\text{opt}}, w_{\text{opt}})) > 1 \text{ then} \]
9: \[ \text{repeat} \]
10: \[ \text{if } \bigcup_{i=1}^{C} X(AP_i, d_{j,\text{opt}}, w_{\text{opt}-1}) = X \text{ then} \]
11: \[ w_{\text{opt}} \leftarrow w_{\text{opt}-1} \]
12: \[ \text{end if} \]
13: \[ \text{until } \forall j, \text{ card}(X(AP_i, d_{j,\text{opt}}, w_{\text{opt}})) \leq 1 \]
14: \[ \text{end if} \]
15: \[ \text{end for} \]

The optimum numbers of directions and power levels are respectively initialized to the minimum and the maximum numbers supported by APs. For every AP’s direction, we check the number of discovered neighbors. If many neighbors are detected, we multiply the initial number of directions by two until we obtain only one neighbor per direction. If the maximum number of direction is reached then we reduce by one level the power and try to get the same result without altering X. X is the set of all neighboring APs that were detected previously in the maximum supported directions and at the maximum supported power level.

5.3 TDO algorithm

TDO takes into consideration the worst-case analysis done by TDM when all the APs transmit at the same time in all supported directions at the maximum power level. Then for a given transmission, it prioritizes the directions with the least cost in duality with TDM but in addition, it integrates data from the upper service layers and returned SLA tests both on the passive and active communication’s paths.

A more complex form of this opportunity processing relies on a system-wide APs transmit operation’s synchronization to cancel costly directions and on-the-air tests to optimize NOOTD costs.

Let us define:

- \( s_{1,i,r} \) — AP weights associated with defined SLA passive and active test results.
- \( O(P_i) \) — opportunity of transmission function at \( P_i \).

\[
\rho_i \quad \text{— weights associated with each category.}
\]

\[
\text{Cost}(P_i) \quad \text{— function of transmissions cost at } P_i
\]

Then for this preliminary work, the cost of a transmission could be expressed as follows:

\[
\text{Cost}(P_i) \approx \begin{cases} 
\rho_1 I(P_i), & \text{if NOATD} \\
\rho_2 I(P_i), & \text{if ODND} \\
\rho_3 I(P_i), & \text{if NOOTD}
\end{cases}
\]

Where,

\[
I(P_i) \approx \alpha_i \sum_j \sum_k \beta_{i,j,k} \cdot \text{intersection}(L_{i,j,k}, C_i^{\text{WD}}) 
+ \sum_{k=2}^{3} \alpha_k \sum_{j \neq i} \beta_{j,k} \cdot \text{intersection}(C_{j,k}, C_{i,1})
\]

Cost calculation results were plotted on Figure 5 for the same Figure 4 network example set of seven APs and eight transmission directions. On this map, transmission costs range from white color, lowest cost points, to red color that correspond to the highest costly points.

Figure 5: TDM Cost Map example of 7 APs and 8 transmit directions
Then for this preliminary work, the transmission opportunity calculation at any point \( P_i \) is given by:

\[
O(P_i) = s_{1,i} s_{2,i} I(P_i)
\]  

(15)

The transmission opportunity processing results were plotted on Figure 6 for a set of seven APs and eight transmit directions.

Figure 6: TDO Opportunity Map example of 7 APs and 8 transmit directions

\( s_{1,i} \) and \( s_{2,i} \) weights are calculated based on the simulated SLA active test results that may include: Packet Loss Rate, Round-Trip Time (RTT), Jitter, and on SLA passive measurements at PHY and MAC levels like: error rates, transmitted packets, etc. that are directly taken from the radio and LAN interfaces. In addition, these weights take into consideration the nature of the end-user application: real-time applications do not require the same service from the network as bulk ones.

5.4 Layered Transmit Opportunity Processing

With regard to this work opportunity processing, a transmission is a four-step procedure: discover, cost, evaluate, and transmit. Discovery is primarily done by APs and could be extended to any WD. The interpretation of discovery results, costing, and opportunity processing, are done at WLC level. Costing in this work has been solely based on interference estimation but could integrate any other radio interface’s measurements: Signal to Noise Ratio (SNR), Received Channel Power Indicator (RCPI), and so on. Opportunity evaluation is based on previous radio interface costing and on measures from upper layer services. These two measures have to be fully uncorrelated to not false results.

5.5 Transmit Synchronization

In this configuration, a transmission is not tight to the access point WD is associated with, but rather to the AP that offers the best transmit opportunity among a set of APs. In fact, the WD is associated with a virtual or pseudo AP that is representative of a set of physical APs with common characteristics with regard to this association. Any physical AP attached to the pseudo-AP could source an effective transmission to the associated WD. In the context of this work, we match the WD’s corresponding pseudo-AP to a single physical AP.

6 Evaluation and Conclusion

At this stage, the evaluation is based on Matlab simulations of both our model and models from related-work [4] [5] [8] Range-based, and [6] Zone-based solutions. In the next step, we consider implementing this solution on a Linux-based APs and WDs and compare its performance with simulated related-work and vendor’s implementations.

We compare our model performance to both Range-based and Zone-based models in these three transmission conditions:

1. a free space transmission condition,
2. the presence of obstacles, “isolated” neighbor’s condition,
3. “guided” neighbor’s condition.

We first evaluate the compared transmission opportunity for any set of 30 APs and ten times a randomly selected 100 WDs on a 2D grid. To ease this work we limit the maximum number of APs to 30 and the number of WDs test points to 100.

Figure 7 shows that for 30 APs and 10 random sets of 100 WDs on the grid, the average performance calculations is almost: 77% for our solution, 68% for Zone-based and only 57% for Range-based models. Figure 8 shows the average transmit opportunity for each model per WDs sets.

Figure 7: Performance comparison for 30 AP and 10 random sets of 100 WDs

Second, as in Figure 9, we evaluate the APs number impact on the compared performance for any set of 100 WDs. APs number ranges from 1 to 30. In Figure 10, we compare Zone-based to Range-based models.
We notice a general tendency of all models to perform similarly when APs are of limited number. However, for greater APs’ numbers, the Zone-based models perform better than Range-based ones as in Figure 10. In Figure 9, our model returns a better transmit opportunity estimation when APs’ number increases in comparison to other models.

Third, in Figure 11, we vary the number of the supported directions that is applicable only to our model and observe the compared average performance. For this test purpose, this number is tight to a variable $\alpha$ that takes these values: 12.5%, 25%, 50% and 75%. We only compare our model to Zone-based one.

Figure 8: Average performance comparison per WDs in a network of 30 APs and 100 WDs

Figure 9: Comparison of our solution, Zone and Range-based models for any set of 100 WDs by APs number

Figure 10: Comparison of Zone and Range-based models for any set of 100 WDs by APs number

Figure 11: AP directions number impact on performance

As a conclusion, this work transmission processing is built on a new costing and opportunity evaluation model that leverages advances in antenna array processing such as beamforming techniques and WLAN integrated design best practices. In addition to the transmission channels and corresponding transmission power levels, it considers the direction of transmission or beam as an additional degree of freedom of dynamic RRM purposes. A comparison to other models indicates that our model is stable and performs better in very dense WLAN indoor and WLC-based network deployments.

Further work may focus on:
1. more complex neighbor AP discovery scenarios,
2. angle of incidence in TDM costing,
3. APs transmit operation coordination,
4. more complex costing layered approach for end-to-end communications.

Conflict of Interest  The authors declare no conflict of interest.
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