A discontinuous Galerkin method for a time-harmonic eddy current problem *

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Abstract

We introduce and analyze a discontinuous Galerkin method for a time-harmonic eddy current problem formulated in terms of the magnetic field. The scheme is obtained by putting together a DG method for the approximation of the vector field variable representing the magnetic field in the conductor and a DG method for the Laplace equation whose solution is a scalar magnetic potential in the insulator. The transmission conditions linking the two problems are taken into account weakly in the global discontinuous Galerkin scheme. We prove that the numerical method is uniformly stable and obtain quasi-optimal error estimates in the DG-energy norm.

1 Introduction

In this paper, we present a discontinuous Galerkin (DG) approximation of a time-harmonic eddy current problem. The eddy current approximation of Maxwell equations is obtained by disregarding the displacement current term. It is commonly used in applications related to induction heating, transformers, magnetic levitation and non-destructive testing. These problems often involve composite materials and structures, complex transmission conditions and, eventually, boundary layers due to the skin effect. The ability of DG methods to handle efficiently unstructured meshes with hanging nodes combined with $hp$-adaptive strategies make them well-suited for the numerical simulation of physical systems related to eddy currents.

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The eddy current problem is generally written in terms of either the electric or the magnetic field, cf. [4]. These two formulations are equivalent at the continuous level but they lead to different numerical schemes. A discontinuous Galerkin method for a time-harmonic eddy current problem written in terms of the electric field has been analyzed in the pioneering work of Perugia and Schotzau [17]. For the time-domain eddy current problem, Ausserhofer et al. used in [6] a formulation in terms of a magnetic vector potential, thus similar to the one in terms of the electric field, and proposed a numerical method based on edge elements, a DG approximation in the conductor and a standard Galerkin approximation in the insulator.

When using the formulation in terms of the electric field, the presence of some constraints in the insulator region leads naturally to a mixed formulation with the introduction of additional unknowns, hence the total number of degrees of freedom is quite high. It is possible to use a primal form by eliminating these additional unknowns (see [17]); however this procedure requires the introduction of several lifting operators thus making a little bit cumbersome the algorithm.

Here, differently from what done in these previous papers, we choose the magnetic field as primary unknown. At the discretization level, the advantage of this approach rests on the reduction of the number of degrees of freedom resulting from the introduction of a scalar magnetic potential in the non-conducting region; moreover, the fact that the equation in this region is simply the Laplace equation permits to employ all the techniques that have been already devised for this basic problem. It is also worth noting that the additional unknowns possibly deriving from the topological shape of the conducting domain are easily inserted in the problem by means of suitable elements of the first de Rham cohomology group. In the end, the global formulation of the problem turns out to be a rather simple $H(\text{curl})$-elliptic problem for vector fields that are curl-free in the insulator $\Omega_I$.

Our DG formulation is obtained by applying for the Laplace equation posed in $\Omega_I$ the usual interior penalty finite element method, that can be traced back to [5], see also [9] and the references cited therein for more details. In the conductor $\Omega_C$ we employ, as in [12, 17], the interior penalty method corresponding to the Nédélec curl-conforming finite element space of the second kind.

We prove the stability of the resulting combined DG scheme by exploiting the elliptic character of the problem. We also obtain, under adequate regularity assumptions, quasi-optimal asymptotic error estimates. It is worthwhile to notice that the implementation of the DG-method presented here only requires the use of standard shape functions. On the other hand, the theoretical convergence results in Section 5 make use of some known properties of curl-conforming finite elements, more precisely, of the Nédélec finite elements of the second kind.

The outline of this paper is as follows. In Section 2 we derive the model problem used in the finite element approximation. We introduce our DG formulation in Section 3. Section 4 is devoted to the convergence analysis, and asymptotic error estimates are provided in Section 5. Finally, in Section 6 we include a numerical experiment that confirms the order of convergence.
2 The model problem

Let $\Omega_C \subset \mathbb{R}^3$ be a bounded polyhedral domain with a Lipschitz boundary $\Gamma$. We denote by $\mathbf{n}_\Gamma$ the unit normal vector on $\Gamma$ that points towards $\Omega_e := \mathbb{R}^3 \setminus \overline{\Omega}_C$. In order to illustrate the impact of the conductor’s topology in our method, we assume that $\Omega_C$ has a toroidal shape. We notice that the eddy current problem is posed in the whole space with asymptotic conditions on the behaviour of the electric and magnetic fields at infinity. Depending on the nature of the eddy current problem being solved and the geometry involved, a discretization method can be obtained for this problem by either applying a pure finite element approach on a truncated domain or by using a combination of boundary (BEM) and finite elements (FEM), see [2, 10, 14, 3]. The FEM–BEM formulation is posed in the conductor but its implementation is more difficult and it leads to more complex algebraic linear systems of equations. The FEM method needs a large computational domain, but it is simpler and it can provide an alternative in many practical situations. It is the option that we will consider in the following. To this end, we introduce a bounded domain $D$ containing in its interior $\overline{\Omega}_C$ and whose connected boundary $\Sigma = \partial D$ is located at a large enough distance from the conductor $\Omega_C$. The bounded domain $\Omega_I := D \setminus \overline{\Omega}_C$ then represents the non-conducting region of the computational domain $D$ (see Figure 1).

\begin{figure}[h]
\centering
\includegraphics[width=0.8\textwidth]{geometry.png}
\caption{The geometry of the computational domain $D$.}
\end{figure}

Under our assumptions, the first de Rham cohomology group $\mathcal{H}^1(\Omega_I)$ of $\Omega_I$, namely, the space of curl-free vector fields that are not gradients, has dimension one. If we assume that $\Omega_I$ is a polyhedral domain endowed with a tetrahedral mesh, one can use the technique given in [7] for the explicit construction of a piecewise-linear vector field $\mathbf{\rho}$ spanning $\mathcal{H}^1(\Omega_I)$ and satisfying $\mathbf{\rho} \times \mathbf{n}_\Sigma = \mathbf{0}$ on $\Sigma$, where $\mathbf{n}_\Sigma$ denotes the outward unit normal vector to $\Sigma$. For an alternative construction of $\mathbf{\rho}$ see Alonso Rodríguez et al. [1].

The eddy current problem formulated in terms of the magnetic field $\mathbf{h}$ and the scalar
magnetic potential $\psi$ reads as follows:

\[
\begin{align*}
\omega \mu h + \text{curl } e &= 0 \quad \text{in } D \\
e &= \sigma^{-1} (\text{curl } h - j) \quad \text{in } \Omega_C \\
h &= \nabla \psi + k \rho \quad \text{in } \Omega_I \\
\psi &= 0 \quad \text{on } \Sigma,
\end{align*}
\]

(1)

where $j$ is the applied current density, $\mu$ is the magnetic permeability and $\sigma$ is the electric conductivity. In what follows, we assume that $\mu$ and $\sigma$ are positive piecewise constant functions in $\Omega_C$ and that $\mu|_{\Omega_I} = \mu_0$ is the permeability constant of vacuum. It follows from the first equation (1) that

\[
0 = \text{div}(h|_{\Omega_I}) = \text{div}(\nabla \psi + k \rho) \quad \text{in } \Omega_I.
\]

(2)

We point out here that the electric field $e$ is not uniquely determined in $\Omega_I$. Nevertheless, the tangential components of the magnetic field and the tangential components of any admissible representation of the electric field should be continuous across the interface $\Gamma$, i.e.,

\[
h|_{\Omega_C} \times n_\Gamma = (\nabla \psi + k \rho) \times n_\Gamma.
\]

(3)

and

\[
e|_{\Omega_C} \times n_\Gamma = e|_{\Omega_I} \times n_\Gamma.
\]

(4)

The electric field $e$ is considered here as an auxiliary variable, it will be removed from the formulation. Hence, we should deduce from (4) a transmission condition relating $h$ and $\psi$ on $\Gamma$. Applying the surface divergence operator $\text{div}_\Gamma$ to both side of (4) and recalling that $\text{div}_\Gamma(e \times n_\Gamma) = \text{curl } e \cdot n_\Gamma$ we deduce that the field $\text{curl } e$ admits continuous normal components across $\Gamma$. As a consequence of the first equation of (1), $\mu h$ should also have continuous normal components across $\Gamma$, i.e.,

\[
\mu h \cdot n_\Gamma = \mu_0(\nabla \psi + k \rho) \cdot n_\Gamma.
\]

(5)

Finally, we deduce from (4) and the property $\text{curl } \rho = 0$ that

\[
\int_{\Gamma} e|_{\Omega_C} \times n_\Gamma \cdot \rho = \int_{\Gamma} e|_{\Omega_I} \times n_\Gamma \cdot \rho = \int_{\Omega_I} \text{curl } e \cdot \rho,
\]

thus

\[
\int_{\Gamma} \sigma^{-1} (\text{curl } h - j) \cdot (\rho \times n_\Gamma) = \omega \int_{\Omega_I} \mu_0(\nabla \psi + k \rho) \cdot \rho.
\]

(6)

From now on, for the sake of simplicity in notations, $h$ will stand for $h|_{\Omega_C}$. Taking into account (2), (3), (5) and (6), we deduce that the eddy current problem can be formulated...
in terms of the magnetic field and its scalar potential representation in the insulator in the following form: Find $\mathbf{h} : \Omega_C \to \mathbb{C}^3$, $\psi : \Omega_I \to \mathbb{C}$ and $k \in \mathbb{C}$ such that,

$$i \omega \mu \mathbf{h} + \text{curl} \left[ \sigma^{-1} \left( \text{curl} \mathbf{h} - j \right) \right] = 0$$

in $\Omega_C$ \hspace{1cm} (7)

$$\mathbf{h} \times \mathbf{n}_\Gamma = (\nabla \psi + k \rho) \times \mathbf{n}_\Gamma$$

on $\Gamma$ \hspace{1cm} (8)

$$\mu \mathbf{h} \cdot \mathbf{n}_\Gamma = \mu_0 (\nabla \psi + k \rho) \cdot \mathbf{n}_\Gamma$$

on $\Gamma$ \hspace{1cm} (9)

$$\int_\Gamma \sigma^{-1} (\text{curl} \mathbf{h} - j) \cdot (\rho \times \mathbf{n}_\Gamma) = i \omega \mu_0 \int_{\Omega_j} (\nabla \psi + k \rho) \cdot \rho$$

(10)

$$\text{div}(\nabla \psi + k \rho) = 0$$

in $\Omega_I$ \hspace{1cm} (11)

$$\psi = 0$$

on $\Sigma$. \hspace{1cm} (12)

We refer to [4, Section 5] for a proof of the well-posedness of problem (7)-(12).

3 The discrete problem

3.1 Notations

Given a real number $r \geq 0$ and a polyhedron $\mathcal{O} \subset \mathbb{R}^d$, $(d = 2, 3)$, we denote the norms and seminorms of the usual Sobolev space $\text{H}^r(\mathcal{O})$ by $\| \cdot \|_{r, \mathcal{O}}$ and $| \cdot |_{r, \mathcal{O}}$ respectively (cf. [13]). We use the convention $L^2(\mathcal{O}) := \text{H}^0(\mathcal{O})$ and $L^2(\mathcal{O}) := [L^2(\mathcal{O})]^3$. We recall that, for any $t \in [-1, 1]$, the spaces $\text{H}^t(\partial \mathcal{O})$ have an intrinsic definition (by localization) on the Lipschitz surface $\partial \mathcal{O}$ due to their invariance under Lipschitz coordinate transformations. Moreover, for all $0 < t \leq 1$, $\text{H}^{-t}(\partial \mathcal{O})$ is the dual of $\text{H}^t(\partial \mathcal{O})$ with respect to the pivot space $L^2(\partial \mathcal{O})$. Finally we consider $\text{H}(\text{curl}, \mathcal{O}) := \{ \mathbf{v} \in L^2(\mathcal{O})^3 : \text{curl} \mathbf{v} \in L^2(\mathcal{O})^3 \}$ and endow it with its usual Hilbertian norm $\| \mathbf{v} \|^2_{\text{H}(\text{curl}, \mathcal{O})} := \| \mathbf{v} \|^2_{0, \mathcal{O}} + \| \text{curl} \mathbf{v} \|^2_{0, \mathcal{O}}$.

We consider a sequence $\{ \mathcal{T}_h \}_{h}$ of conforming and shape-regular triangulations of $\overline{\Omega}_C \cup \overline{\Omega}_I$. We assume that each partition $\mathcal{T}_h$ consists of tetrahedra $K$ of diameter $h_K$ and unit outward normal to $\partial K$ denoted $\mathbf{n}_K$. We also assume that for all $K \in \mathcal{T}_h$ we have either $K \subset \overline{\Omega}_C$ or $K \subset \overline{\Omega}_I$ and denote

$$\mathcal{T}_h^{\Omega_C} := \{ K \in \mathcal{T}_h; \ K \subset \overline{\Omega}_C \}, \quad \mathcal{T}_h^{\Omega_I} := \{ K \in \mathcal{T}_h; \ K \subset \overline{\Omega}_I \}.$$ 

We also assume that the meshes $\{ \mathcal{T}_h^{\Omega_C} \}_{h}$ are aligned with the discontinuities of the coefficients $\sigma$ and $\mu$. The parameter $h := \max_{K \in \mathcal{T}_h} \{ h_K \}$ represents the mesh size.

We denote by $\mathcal{F}_h^{\Omega_C}(\overline{\Omega}_C)$ and $\mathcal{F}_h^{\Omega_I}(\overline{\Omega}_I)$ the sets of interior faces of the triangulations $\mathcal{T}_h^{\Omega_C}$ and $\mathcal{T}_h^{\Omega_I}$ respectively. We also introduce the sets of boundary faces

$$\mathcal{F}_h^{\Gamma} := \{ F = K \cap K'; \ K \in \mathcal{T}_h^{\Omega_C}, \ K' \in \mathcal{T}_h^{\Omega_I} \} \quad \text{and} \quad \mathcal{F}_h^{\Sigma} := \{ F = \partial K \cap \Sigma; \ K \in \mathcal{T}_h^{\Omega_I} \}.$$ 


and consider
\[
\mathcal{F}_h^{\Omega_C} := \mathcal{F}_h^0(\Omega_C) \cup \mathcal{F}_h^{\Gamma}, \quad \mathcal{F}_h^{\Omega_I} := \mathcal{F}_h^0(\Omega_I) \cup \mathcal{F}_h^\Sigma, \quad \text{and} \quad \mathcal{F}_h := \mathcal{F}_h^{\Omega_C} \cup \mathcal{F}_h^{\Omega_I}.
\]

We notice that \( \{ \mathcal{F}_h^{\Gamma} \}_h \) is a shape regular family of triangulations of \( \Gamma \) into triangles \( T \) of diameter \( h_T \). Finally, we consider the set \( \mathcal{E}_h \) of edges \( e = T \cap T' \) (where \( T \) and \( T' \) are two adjacent triangles from \( \mathcal{F}_h^{\Gamma} \)).

Let \( \mathcal{O}_h \) be anyone of the previously introduced partitions of \( \overline{\Omega}_C \cup \overline{\Omega}_I, \overline{\Omega}_C, \overline{\Omega}_I \) or \( \Gamma \) and let \( E \) be a generic element of the given partition. We introduce for any \( s \geq 0 \) the broken Sobolev spaces
\[
H^s(\mathcal{O}_h) := \prod_{E \in \mathcal{O}_h} H^s(E) \quad \text{and} \quad H^s(\mathcal{O}_h) := \prod_{E \in \mathcal{O}_h} H^s(E)^3.
\]

For each \( w := \{ w_E \} \in H^s(\mathcal{O}_h) \), the components \( w_E \) represents the restriction \( w|_E \). When no confusion arises, the restrictions will be written without any subscript.

The space \( H^s(\mathcal{O}_h) \) is endowed with the Hilbertian norm
\[
\|w\|_{s,\mathcal{O}_h}^2 := \sum_{E \in \mathcal{O}_h} \|w_E\|_{s,E}^2.
\]

We consider identical definitions for the norm and the seminorm on the vectorial version \( H^s(\mathcal{O}_h) \). We use the standard conventions \( L^2(\mathcal{O}_h) := H^0(\mathcal{O}_h) \) and \( L^2(\mathcal{O}_h) := H^0(\mathcal{O}_h) \) and introduce the bilinear forms
\[
(w, z)_{\mathcal{O}_h} = \sum_{E \in \mathcal{O}_h} \int_E w_E z_E, \quad \forall w, z \in L^2(\mathcal{O}_h)
\]
and
\[
(w, z)_{\mathcal{O}_h} = \sum_{E \in \mathcal{O}_h} \int_E w_E \cdot z_E, \quad \forall w, z \in L^2(\mathcal{O}_h).
\]

Assume that \((v, \varphi, m) \in H^{1+s}(\mathcal{T}^{\Omega_C}_h) \times H^{1+s}(\mathcal{T}^{\Omega_I}_h) \times \mathbb{C}, \) with \( s > 1/2 \). Moreover, let us recall that \( \rho \) has been constructed as a piecewise-linear vector field, therefore its restriction to any face \( F \) has a meaning. We define \( \text{curl}_h v \in H^s(\mathcal{T}^{\Omega_C}_h) \) by \( (\text{curl}_h v)|_K = \text{curl} v_K \), for all \( K \in \mathcal{T}^{\Omega_C}_h \); \( \nabla_h \varphi \in H^s(\mathcal{T}^{\Omega_I}_h) \) by \( (\nabla_h \varphi)|_K = \nabla \varphi_K \), for all \( K \in \mathcal{T}^{\Omega_I}_h \).

We also need to introduce the following quantities, that are defined on the sets of faces of \( \Omega_C \) and \( \Omega_I \) through a local definition on each face: the averages \( \{ v \}_F \in L^2(\mathcal{F}^{\Omega_C}_h) \) and \( \{ \nabla_h \varphi + m \rho \}_F \in L^2(\mathcal{F}^{\Omega_I}_h) \) by
\[
\{ v \}_F := \{ v \}_F \quad \text{with}
\]
\[
\{ v \}_F := \begin{cases} 
(v_K + v_{K'})/2 & \text{if } F = K \cap K' \in \mathcal{F}_h^0(\Omega_C) \\
v_K & \text{if } F \subset \partial K \text{ and } F \in \mathcal{F}_h^{\Gamma}.
\end{cases}
\]

\[
\{ v \}_F := \begin{cases} 
(v_K + v_{K'})/2 & \text{if } F = K \cap K' \in \mathcal{F}_h^0(\Omega_C) \\
v_K & \text{if } F \subset \partial K \text{ and } F \in \mathcal{F}_h^{\Gamma}.
\end{cases}
\]
and
\[
\{\nabla_h \varphi + m \rho \}_F := \{\nabla_h \varphi + m \rho \}_F \text{ with }
\]
\[
\{\nabla_h \varphi + m \rho \}_F := \begin{cases} 
(\nabla \varphi_K + \nabla \varphi_{K'})/2 + m(\rho_K + \rho_{K'})/2 & \text{if } F = K \cap K' \in \mathcal{F}_h^0(\Omega_I) \\
\nabla \varphi_K + m \rho_K & \text{if } F \subset \partial K \text{ and } F \in \mathcal{F}_h^\Sigma,
\end{cases}
\]
(14)

and the jumps \([v, \varphi, m]_F \in L^2(\mathcal{F}_h^{\Omega_C})\) and \([\varphi n]_F \in L^2(\mathcal{F}_h^{\Omega_I})\) by
\[
[v, \varphi, m]_F := [(v, \varphi, m)]_F \text{ with }
\]
\[
[v, \varphi, m]_F := \begin{cases} 
[v \times n]_F := v_K \times n_K + v_{K'} \times n_{K'} & \text{if } F = K \cap K' \in \mathcal{F}_h^0(\Omega_C) \\
v_K \times n_K + (\nabla \varphi_{K'} + m \rho_{K'}) \times n_{K'} & \text{if } F = K \cap K' \in \mathcal{F}_h^\Sigma \text{ with } K \in \mathcal{T}_h^{\Omega_C}, K' \in \mathcal{T}_h^{\Omega_I},
\end{cases}
\]
(15)

and
\[
[\varphi n]_F := \begin{cases} 
\varphi_K n_K + \varphi_{K'} n_{K'} & \text{if } F = K \cap K' \in \mathcal{F}_h^0(\Omega_I) \\
\varphi_K n_\Sigma & \text{if } F \subset \partial K \text{ and } F \in \mathcal{F}_h^\Sigma.
\end{cases}
\]
(16)

Similarly, we define the edge averages \(\{v\}_e \in L^2(\mathcal{E}_h)\) by
\[
\{v\}_e := \{v\}_e \text{ with } \{v\}_e := (v_{K_e} + v_{K'_e})/2
\]
where \(K_e, K'_e \in \mathcal{T}_h^{\Omega_C}\) are such that \(T = \partial K_e \cap \Gamma \in \mathcal{F}_h^\Gamma, T' = \partial K'_e \cap \Gamma \in \mathcal{F}_h^\Gamma\) and \(e = T \cap T'\).

We also need to define the edge jumps \([\varphi t]_e \in L^2(\mathcal{E}_h)\) by
\[
[\varphi t]_e := [\varphi t]_e \text{ with } [\varphi t]_e := \varphi_{K_e} t_e + \varphi_{K'_e} t'_e,
\]
where \(K_e, K'_e\) are in this case the elements from \(\mathcal{T}_h^{\Omega_I}\) such that \(T = \partial K_e \cap \Gamma \in \mathcal{F}_h^\Gamma, T' = \partial K'_e \cap \Gamma \in \mathcal{F}_h^\Gamma\) and \(e = T \cap T'\). Here, \(t_e, t'_e\) are the tangent unit vectors along the edge \(e\) given by \(t_e = (n_T \times \nu_T)|_e\) and \(t'_e = (n_T \times \nu_{T'})|_e\) where \(\nu_T\) and \(\nu_{T'}\) are the outward unit normal vector to \(\partial T\) and \(\partial T'\) respectively that lies on the tangent plane to \(\Gamma\).

### 3.2 The DG formulation

Hereafter, given an integer \(k \geq 0\) and a domain \(\mathcal{O} \subset \mathbb{R}^3\), \(\mathcal{P}_k(\mathcal{O})\) denotes the space of polynomials of degree at most \(k\) on \(\mathcal{O}\). For any \(m \geq 1\), we introduce the finite element spaces
\[
X_h := \prod_{K \in \mathcal{T}_h^{\Omega_C}} \mathcal{P}_m(K)^3 \quad \text{and} \quad V_h := \prod_{K \in \mathcal{T}_h^{\Omega_I}} \tilde{\mathcal{P}}_m(K),
\]

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where

\[ \tilde{P}_m(K) := \begin{cases} P_m(K) & \text{if } \partial K \cap \Gamma \notin F_h^T \\ P_m(K) + P_{m+1}^T(K) & \text{if } T = \partial K \cap \Gamma \in F_h^T \end{cases} \quad (17) \]

with \( P_{m+1}^T(K) \) representing the subspace of \( P_{m+1}(K) \) spanned by the elements of the Lagrange basis corresponding to nodal points located on \( T \). It follows that \( P_m(K) \subset \tilde{P}_m(K) \subset P_{m+1}(K) \) and if \( T = \partial K \cap \Gamma \in F_h^T \), then \( \tilde{P}_m(K)|_T = P_{m+1}(T) \).

Let \( h_x \in \prod_{F \in \mathcal{F}_h} P_0(F) \) and \( h_\varepsilon \in \prod_{e \in \mathcal{E}_h} P_0(e) \) be defined by \( h_x|_F := h_F \), \( \forall F \in \mathcal{F}_h \) and \( h_\varepsilon|_e := h_e \), \( \forall e \in \mathcal{E}_h \) respectively. By virtue of our hypotheses on \( \sigma \) and on the triangulation \( \mathcal{T}_h^{\Omega_C} \), we may consider that \( \sigma \) is an element of \( \prod_{K \in \mathcal{T}_h^{\Omega_C}} P_0(K) \) and denote \( \sigma_K := \sigma|_K \) for all \( K \in \mathcal{T}_h^{\Omega_C} \). We introduce \( s_F \in \prod_{F \in \mathcal{F}_h(\Omega_C)} P_0(F) \) defined by \( s_F := \min(\sigma_K, \sigma_{K'}) \), if \( F = \partial K \cap \partial K' \in \mathcal{F}_h^I(\Omega_C) \) and \( s_F := \sigma_K \), if \( F = \partial K \cap \Gamma \in \mathcal{F}_h^T \). We also need to define \( s_e \in \prod_{e \in \mathcal{E}_h} P_0(e) \) given by \( s_e := \min(\sigma_K, \sigma_{K'}) \) where \( K_x, K_e \in \mathcal{T}_h^{\Omega_C} \) are such that \( T = \partial K_x \cap \Gamma \in \mathcal{F}_h^T \), \( T' = \partial K_e \cap \Gamma \in \mathcal{F}_h^T \) and \( e = T \cap T' \).

We consider, for \( s > 1/2 \), the Hilbert space

\[ X^s(\mathcal{T}_h^{\Omega_C}) := \{ v \in H^s(\mathcal{T}_h^{\Omega_C}); \ \text{curl}_h v \in H^{1/2+s}(\mathcal{T}_h^{\Omega_C}) \} \]

and define on \( X^s(\mathcal{T}_h^{\Omega_C}) \times H^{1+s}(\mathcal{T}_h^{\Omega_C}) \times \mathbb{C} \) the sesquilinear forms

\[
A_h^{\Omega_C}((\mathbf{u}, \phi, c), (v, \varphi, m)) := \omega (\mu_{\mathbf{u}}, v)_{\mathcal{T}_h^{\Omega_C}} + (\sigma^{-1} \text{curl}_h \mathbf{u}, \text{curl}_h v)_{\mathcal{T}_h^{\Omega_C}} \\
+ \left\{ (\sigma^{-1} \text{curl}_h \mathbf{u})_F, \left[\left[ v, \varphi, m \right]_F \right] \right\}_{\mathcal{T}_h^{\Omega_C}} + \left\{ (\sigma^{-1} \text{curl}_h v)_F, \left[\left[ (\mathbf{u}, \phi, c) \right]_F \right] \right\}_{\mathcal{T}_h^{\Omega_C}} \\
+ a^{\Omega_C} \left( s_F^{-1} h_{\mathcal{F} h}^{-1} \left[\left[ (\mathbf{u}, \phi, c) \right]_F, \left[\left[ (v, \varphi, m) \right]_F \right] \right] \right)_{\mathcal{T}_h^{\Omega_C}},
\]

\[
A_h^{\Omega_I}((\mathbf{u}, \phi, c), (v, \varphi, m)) := \omega \mu_0(\nabla \varphi + c \rho, \nabla \mathbf{v} + m \rho)_{\mathcal{T}_h^{\Omega_I}} + \frac{a_I^{\Omega_I}}{\omega \mu_0} \left( h_{\mathcal{F} h}^{-1} \left[\left[ \phi \mathbf{n} \right]_F, \left[\left[ \varphi \mathbf{n} \right]_F \right] \right] \right)_{\mathcal{T}_h^{\Omega_I}} \\
- \omega \mu_0 \left( \left\{ \nabla \varphi + c \rho \right\}_F, \left[\left[ \phi \mathbf{n} \right]_F \right] \right)_{\mathcal{T}_h^{\Omega_I}} - \omega \mu_0 \left( \left\{ \nabla \mathbf{v} + m \rho \right\}_F, \left[\left[ \varphi \mathbf{n} \right]_F \right] \right)_{\mathcal{T}_h^{\Omega_I}} \\
- \left\{ (\sigma^{-1} \text{curl}_h \mathbf{u})_e, \left[\left[ \phi \mathbf{t} \right]_e \right] \right\}_{\mathcal{E}_h} - \left\{ (\sigma^{-1} \text{curl}_h v)_e, \left[\left[ \varphi \mathbf{t} \right]_e \right] \right\}_{\mathcal{E}_h} + \alpha (s_e^{-1} h_{\mathcal{F} h}^{-2} \left[\left[ \phi \mathbf{t} \right]_e, \left[\left[ \varphi \mathbf{t} \right]_e \right] \right] \right)_{\mathcal{E}_h},
\]

and let

\[ A_h((\mathbf{u}, p, c), (v, \varphi, m)) := A_h^{\Omega_C}((\mathbf{u}, \phi, c), (v, \varphi, m)) + A_h^{\Omega_I}((\mathbf{u}, \phi, c), (v, \varphi, m)). \]

Let us assume that \( \sigma^{-1} \mathbf{j} \in H^{1/2+s}(\mathcal{T}_h^{\Omega_C}) \) with \( s > 1/2 \). Then we can define the linear form \( L_h(\cdot) \) on \( X^s(\mathcal{T}_h^{\Omega_C}) \times H^{1+s}(\mathcal{T}_h^{\Omega_C}) \times \mathbb{C} \) by

\[ L_h((v, \varphi, m)) := (\sigma^{-1} \mathbf{j}, \text{curl}_h v)_{\mathcal{T}_h^{\Omega_C}} + \left\{ (\sigma^{-1} \mathbf{j})_F, \left[\left[ (v, \varphi, m) \right]_F \right] \right\}_{\mathcal{T}_h^{\Omega_C}} - \left\{ (\sigma^{-1} \mathbf{j})_e, \left[\left[ \varphi \mathbf{t} \right]_e \right] \right\}_{\mathcal{E}_h}. \]

We propose the following DG formulation of problem (7)-(12):

\[ A_h((h_x, \psi_h, k_h), (v, \varphi, m)) = L_h((v, \varphi, m)) \quad \forall (v, \varphi, m) \in X_h \times V_h \times \mathbb{C}. \]

(18)

The existence and uniqueness of the solution of this problem is proved in Theorem 4.1. We end this section by showing that the DG scheme (18) is consistent.
Proposition 3.1. Let \((h, \psi, k) \in H(\text{curl}, \Omega_C) \times H^1(\Omega_I) \times \mathbb{C}\) be the solution of (7)-(12). Under the assumption \(\sigma^{-1} j \in H^{1/2+s}(T_h^{\Omega_C})\) and the regularity conditions \((h, \psi, k) \in X_s(T_h^{\Omega_C}) \times H^{1+s}(T_h^{\Omega_I}) \times \mathbb{C}\), with \(s > 1/2\), we have that
\[
A_h((h, \psi, k), (v, \varphi, m)) = L_h((v, \varphi, m)) \quad \forall (v, \varphi, m) \in X_h \times V_h \times \mathbb{C}.
\]

Proof. Using again the notation \(e = \sigma^{-1}(\text{curl} h - j)\) and taking into account that \([h, \psi, k]_\mathcal{F} = 0\), \([\psi n]_\mathcal{F} = 0\), and \([\psi t]_\mathcal{E} = 0\), it is straightforward to show that
\[
A_h((h, \psi, k), (v, \varphi, m)) - L_h((v, \varphi, m)) = \omega \int_{\Omega_C} \mu h \cdot v + \int_{\Omega_C} e \cdot \text{curl} h v
\]
\[
+ \omega \mu_0 \int_{\Omega_I} (\nabla \psi + k \rho) \cdot (\nabla_h \varphi + m \rho) + (\{e\}_\mathcal{F}, [v, \varphi, m]_\mathcal{F})_{\mathcal{T}^{\Omega_C}}
\]
\[
- \omega \mu_0 (\{\nabla \psi + k \rho\}_\mathcal{F}, [\varphi n]_\mathcal{F} - [\varphi]_\mathcal{E} - [\varphi t]_\mathcal{E})_{\mathcal{E}_h}. \tag{19}
\]
Integrating by parts in each \(K \in \mathcal{T}_h^{\Omega_C}\) and using (7) yield
\[
\int_{\Omega_C} e \cdot \text{curl} h v = \sum_{K \in \mathcal{T}_h^{\Omega_C}} \int_K \text{curl} e \cdot v - \sum_{K \in \mathcal{T}_h^{\Omega_C}} \int_{\partial K} e \cdot v \times n_K
\]
\[
= -\omega \int_{\Omega_C} \mu h \cdot v - \sum_{F \in \mathcal{F}_h(\Omega_C)} \int_F \{e\}_F \cdot [v \times n]_F - \sum_{T \in \mathcal{F}_h} \int_T e \cdot v \times n. \tag{20}
\]
Similarly, integrating by parts in each \(K \in \mathcal{T}_h^{\Omega_I}\) together with (10) and (11) give
\[
\omega \mu_0 \int_{\Omega_I} (\nabla \psi + k \rho) \cdot (\nabla_h \varphi + m \rho) = -\omega \mu_0 \sum_{K \in \mathcal{T}_h^{\Omega_I}} \int_K \text{div}(\nabla \psi + k \rho) \varphi
\]
\[
+ \omega \mu_0 \sum_{K \in \mathcal{T}_h^{\Omega_I}} \int_{\partial K} (\nabla \psi + k \rho) \cdot n_K \varphi + m \int_{\Omega_I} (\nabla \psi + k \rho) \cdot \rho = \omega \mu_0 \sum_{F \in \mathcal{F}_h(\Omega_I)} \int_F \{\nabla \psi + k \rho\}_F \cdot [\varphi n]_F
\]
\[
- \omega \mu_0 \sum_{T \in \mathcal{F}_h} \int_T (\nabla \psi + k \rho) \cdot \varphi n_T + \omega \mu_0 \sum_{T \in \mathcal{F}_h} \int_T (\nabla \psi + k \rho) \cdot \varphi n_S + m \int_T e \cdot (\rho \times n_T). \tag{21}
\]
Substituting back (20) and (21) in (19) we obtain
\[
A_h((h, \psi, k), (v, \varphi, m)) - L_h((v, \varphi, m)) = -\sum_{T \in \mathcal{F}_h} \int_T e \cdot \text{curl}_T \varphi
\]
\[
- \omega \mu_0 \sum_{T \in \mathcal{F}_h} \int_T (\nabla \psi + k \rho) \cdot \varphi n_T - (\{e\}_\mathcal{E}, [\varphi t]_\mathcal{E})_{\mathcal{E}_h}. \tag{22}
\]
Finally, using the integration by parts formula

\[
\sum_{T \in \mathcal{F}_h} \int_T \mathbf{e} \cdot \nabla \phi = \sum_{T \in \mathcal{F}_h} \int_T (\nabla \phi) \mathbf{e} - \sum_{T \in \partial \Omega} \int_{\partial T} \mathbf{e} \cdot \mathbf{n} = \int_{\Omega} (\nabla \phi) \mathbf{e} - \{\mathbf{e}, \mathbf{f}\}_{\mathcal{E}_h},
\]

we deduce from (22) that

\[
A_h((\mathbf{h}, \varphi, k), (\mathbf{v}, \varphi, m)) - L_h((\mathbf{v}, \varphi, m)) = -\int_T (\nabla \phi) \mathbf{e} - \omega \mu_0 \sum_{T \in \mathcal{F}_h} \nabla (\psi + k \mathbf{p}) - \varphi \mathbf{n}_T.
\]

and the result follows from the identity \(\nabla \mathbf{e} = \mathbf{curl} \cdot \mathbf{n}\), equation (7) and the transmission condition (9). \qed

4 Convergence analysis of the DG-FEM formulation

The aim of this Section is to prove that the DG-FEM formulation (18) is stable in the DG-norm defined on \(X(T_h) \times H^1(\Omega) \times \mathbb{C}\) by

\[
\|(\mathbf{v}, \varphi, m)\|^2 := \|\omega \mu_0 \mathbf{e}\|^2_{0, \Omega} + \|
\sigma^{-1/2} \mathbf{curl}_h \mathbf{v}\|^2_{0, \Omega} + \omega \mu_0 \|
\nabla \varphi + m \mathbf{p}\|^2_{0, \Omega} + \|
\mathbf{f}\|^2_{0, \mathcal{F}_h} + \omega \mu_0 \|
\mathbf{n}\|^2_{0, \mathcal{F}_h} + \|
\sigma^{-1/2} \mathbf{curl}_h \mathbf{v}\|_{0, \mathcal{E}_h}.
\]

(23)

We also need to introduce

\[
\|(\mathbf{v}, \varphi, m)\|^2 \asymp := \|(\mathbf{v}, \varphi, m)\|^2 + \|
\mathbf{s}_h^{\mathcal{F}} \mathbf{f}\|_{0, \mathcal{F}_h}^2 + \|
\sigma^{-1/2} \mathbf{curl}_h \mathbf{v}\|_{0, \mathcal{E}_h}^2 + \|
\mathbf{f}\|_{0, \mathcal{F}_h}^2 + \|
\mathbf{n}\|_{0, \mathcal{F}_h}^2.
\]

The following discrete trace inequality is standard, (see, e.g. [9, Lemma 1.46]).

Lemma 4.1. For all integer \(k \geq 0\) there exists a constant \(C^* > 0\) independent of \(h\) such that

\[
h_Q \|v\|^2_{0, \partial Q} \leq C^* \|v\|^2_{0, Q} \quad \forall v \in P_k(Q), \quad \forall Q \in \{T_h, \mathcal{F}_h^I\}.
\]

(24)

It is used to prove the following auxiliary result.

Lemma 4.2. For all \(k \geq 0\), there exist constants \(C_{\Omega_0} > 0\) and \(C_{\Omega_I} > 0\) independent of the mesh size and the coefficients such that

\[
\|s_h^{\mathcal{F}} \mathbf{f}\|_{0, \mathcal{E}_h} + \|s_h^{\mathcal{F}} \mathbf{f}\|_{0, \mathcal{E}_h}^2 \leq C_{\Omega_0} \|\sigma^{-1/2} \mathbf{w}\|_{0, \Omega} \leq \|s_h^{\mathcal{F}} \mathbf{f}\|_{0, \mathcal{E}_h}^2 \|s_h^{\mathcal{F}} \mathbf{f}\|_{0, \mathcal{E}_h}.
\]

(25)
for all \( \mathbf{w} \in \prod_{K \in \mathcal{T}_h^{\Omega_C}} \mathcal{P}_k(K)^3 \), and

\[
\| h^{1/2}_F \{ \mathbf{w} \}_F \|_{0,h,\Omega_I} \leq C_{\Omega_I} \| \mathbf{w} \|_{0,\Omega_I}, \tag{26}
\]

for all \( \mathbf{w} \in \prod_{K \in \mathcal{T}_h^{\Omega_I}} \mathcal{P}_k(K)^3 \).

**Proof.** By definition of \( s_F \), for any \( \mathbf{w} \in \prod_{K \in \mathcal{T}_h^{\Omega_C}} \mathcal{P}_k(K)^3 \),

\[
\| s_F^{1/2} h^{1/2}_F \{ \sigma^{-1} \mathbf{w} \}_F \|^2_{0,F,h^{\Omega_C}} = \sum_{F \in \mathcal{F}_h^{\Omega_C}} h_F \| s_F^{1/2} \{ \sigma^{-1} \mathbf{w} \}_F \|^2_{0,F} \leq \sum_{K \in \mathcal{T}_h^{\Omega_C}} \sum_{F \in \mathcal{F}_K} h_F \| s_F^{1/2} \sigma_K^{-1} \mathbf{w}_K \|^2_{0,F} \leq \sum_{K \in \mathcal{T}_h^{\Omega_C}} h_K \| \sigma_K^{-1/2} \mathbf{w}_K \|^2_{0,\partial K}. \tag{27}
\]

Similarly,

\[
\| s_E^{1/2} h_N \{ \sigma^{-1} \mathbf{w} \}_N \|^2_{0,E,h} = \sum_{e \in \mathcal{E}_h} h_e^2 \| s_E^{1/2} \{ \sigma^{-1} \mathbf{w} \}_e \|^2_{0,e} \leq \sum_{T \in \mathcal{T}_h^T} \sum_{e \in \mathcal{E}(T)} h_e^2 \| s_E^{1/2} \sigma_T^{-1} \mathbf{w}_T \|^2_{0,T} \leq \sum_{T \in \mathcal{T}_h^T} h_T \| \sigma_T^{-1/2} \mathbf{w}_T \|^2_{0,\partial T}, \tag{28}
\]

where \( K_T \in \mathcal{T}_h^{\Omega_C} \) is such that \( T = \partial K_T \cap \Gamma \). It follows from (24) that

\[
\| s_E^{1/2} h_N \{ \sigma^{-1} \mathbf{w} \}_N \|^2_{0,E,h} \leq C^* \sum_{T \in \mathcal{T}_h^T} h_T \| \sigma_T^{-1/2} \mathbf{w}_T \|^2_{0,T} \leq C^* \sum_{K \in \mathcal{T}_h^{\Omega_C}} h_K \| \sigma_K^{-1/2} \mathbf{w}_K \|^2_{0,\partial K}
\]

and (25) follows by applying again the discrete trace inequality (24) in the last estimate and in (27). Finally, for any \( \mathbf{w} \in \prod_{K \in \mathcal{T}_h^{\Omega_I}} \mathcal{P}_k(K)^3 \),

\[
\| h^{1/2}_F \{ \mathbf{w} \}_F \|^2_{0,h,\Omega_I} = \sum_{F \in \mathcal{F}_h^{\Omega_I}} h_F \| \{ \mathbf{w} \}_F \|^2_{0,F} \leq \sum_{K \in \mathcal{T}_h^{\Omega_I}} h_K \| \mathbf{w}_K \|^2_{0,\partial K} \tag{29}
\]

and (26) follows again from (24).

**Proposition 4.1.** There exists a constant \( M > 0 \) independent of \( h \) such that

\[
| A_h((\mathbf{u}, \phi, c), (\mathbf{v}, \varphi, m)) | \leq M \| (\mathbf{u}, \phi, c) \| \| (\mathbf{v}, \varphi, m) \|
\]

for all \( (\mathbf{u}, \phi, c), (\mathbf{v}, \varphi, m) \in X^s(\mathcal{T}_h^{\Omega_C}) \times H^{1+s}(\mathcal{T}_h^{\Omega_I}) \times \mathbb{C} \), with \( s > 1/2 \).

**Proof.** By the Cauchy-Schwarz inequality, we have that

\[
| A_h^{\Omega_C}((\mathbf{u}, \phi, c), (\mathbf{v}, \varphi, m)) | \leq \omega \| \mathbf{u} \|^2_{0,\Omega_C} \| \nabla \mathbf{v} \|^2_{0,\Omega_C} + \| \sigma^{-1/2} \text{curl}_h \mathbf{u} \|^2_{0,\Omega_C} \| \sigma^{-1/2} \text{curl}_h \mathbf{v} \|^2_{0,\Omega_C}
\]

\[
+ \| s_F^{1/2} h^{1/2}_F \{ \sigma^{-1/2} \text{curl}_h \mathbf{u} \}_F \|^2_{0,F,h^{\Omega_C}} + \| s_F^{1/2} h^{1/2}_F \{ \sigma^{-1/2} \text{curl}_h \mathbf{v} \}_F \|^2_{0,F,h^{\Omega_C}} + \| a^{\Omega_C} s_F^{1/2} h^{1/2}_F \{ (\mathbf{u}, \phi, c) \}_F \|^2_{0,F,h^{\Omega_C}} + \| a^{\Omega_C} s_F^{1/2} h^{1/2}_F \{ (\mathbf{v}, \varphi, m) \}_F \|^2_{0,F,h^{\Omega_C}}.
\]

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Applying (25) with \( w = \text{curl}_h v \) we obtain
\[
|A^\Omega_h^\alpha((\mathbf{u}, \phi, c), (v, \varphi, m))| \leq (1 + C_{\Omega} + \mathbf{a}^\Omega \mathbf{c}) \| (\mathbf{u}, \phi, c) \|_{\Omega} \| (v, \varphi, m) \|
\]
for all \((\mathbf{u}, \phi, c)\) and \((v, \varphi, m) \in X^s(\mathcal{T}_h^\alpha) \times H^{1+s}(\mathcal{T}_h^\alpha) \times \mathbb{C}\). On the other hand,
\[
|A^\Omega_h((\mathbf{u}, \phi, c), (v, \varphi, m))| \leq \omega \mu_0 \| \nabla_h \phi + c \mathbf{p} \|_{0,\Omega^\alpha} \| \nabla_h \varphi + m \mathbf{p} \|_{0,\Omega^\alpha} \\
+ \omega \mu_0 \| h^{1/2}_F \{ \nabla_h \varphi + \alpha \mathbf{p} \} \|_{0,\Omega^\alpha} \| h^{1/2}_F \{ \phi n \} \|_{0,\Omega^\alpha} \\
+ \omega \mu_0 \| h^{1/2}_F \{ \nabla_h \phi + m \mathbf{p} \} \|_{0,\Omega^\alpha} \| h^{1/2}_F \{ \varphi \mathbf{n} \} \|_{0,\Omega^\alpha} \\
+ \omega \mu_0 \| h^{1/2}_F \{ \nabla_h \varphi + m \mathbf{p} \} \|_{0,\Omega^\alpha} \| h^{1/2}_F \{ \phi n \} \|_{0,\Omega^\alpha}
\]
and it follows from (26) (applied with \( w = \nabla_h \varphi + m \mathbf{p} \)) and (25) (applied with \( w = \text{curl}_h v \)) that
\[
|A^\Omega_h((\mathbf{u}, \phi, c), (v, \varphi, m))| \leq (1 + C_{\Omega} + C_{\Omega} + \mathbf{a}^\Omega \mathbf{c} + \alpha) \| (\mathbf{u}, \phi, c) \|_{\Omega} \| (v, \varphi, m) \|
\]
which gives the result.

**Proposition 4.2.** There exists a constant \( \alpha_0 > 0 \) independent of the mesh size and the coefficients such that if \( \min(\mathbf{a}^\Omega \mathbf{c}, \mathbf{a}^\Omega \mathbf{c}, \alpha) \geq \alpha_0 \) then,
\[
\Re \left[ (1 - \iota) A_h((v, \varphi, m), (\bar{v}, \bar{\varphi}, \bar{m})) \right] \geq \frac{1}{2} \| (v, \varphi, m) \|^2 \quad \forall (v, \varphi, m) \in X_h \times V_h \times \mathbb{C} \quad \text{(30)}
\]

**Proof.** By definition of \( A_h(\cdot, \cdot) \),
\[
\Re \left[ (1 - \iota) A_h((v, \varphi, m), (\bar{v}, \bar{\varphi}, \bar{m})) \right] = \omega \| \mu^{1/2} v \|_{0,\Omega^c}^2 + \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega^c}^2 \\
+ 2 \Re \left( \{ \sigma^{-1} \text{curl}_h v \} \{ \bar{v}, \bar{\varphi}, \bar{m} \} \right)_{F}^\alpha + \mathbf{a}^\Omega \| h^{1/2}_F \{ (v, \varphi, m) \} \|_{0,\Omega^\alpha}^2 \\
+ \omega \mu_0 \| \nabla_h \varphi + m \mathbf{p} \|_{0,\Omega^\alpha}^2 + 2 \omega \mu_0 \Re \left( \{ \nabla_h \varphi + m \mathbf{p} \} \{ \bar{\varphi} \mathbf{n} \} \right)_{F}^\alpha \\
+ \omega \mu_0 \| h^{1/2}_F \{ \varphi \mathbf{n} \} \|_{0,\Omega^\alpha}^2 - 2 \Re \left( \{ \sigma^{-1} \text{curl}_h v \} \{ \bar{\varphi} \mathbf{n} \} \right)_{E}^\alpha + \alpha \| h^{-1}_E \{ \varphi \mathbf{t} \} \|_{0,\Omega^\alpha}^2 
\]

It follows from the Cauchy-Schwarz inequality and (25) that,
\[
2 \Re \left( \{ \sigma^{-1} \text{curl}_h v \} \{ \bar{v}, \bar{\varphi}, \bar{m} \} \right)_{F}^\alpha \\
\leq 2 \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega^c} \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega^c} \| \nabla_h \varphi + m \mathbf{p} \|_{0,\Omega^\alpha} \| \varphi \mathbf{n} \|_{0,\Omega^\alpha} \\
\leq 2 \omega_1 \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega^c} \| h^{-1/2}_F \{ (v, \varphi, m) \} \|_{0,\Omega^\alpha} \\
\leq \frac{1}{4} \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega^c}^2 + 4 \omega_1 \| h^{-1/2}_F \{ (v, \varphi, m) \} \|_{0,\Omega^\alpha}^2.
\]
Similarly, by virtue of (26),

$$2\text{Re} \left( (\nabla_h \varphi + m \rho)_{\mathcal{F}} \left[ [\nabla_h \varphi + m \rho]_{\mathcal{F}} \right] \right)_{\mathcal{F},0} = 2\| h_{\mathcal{F}}^{1/2} \{ \nabla_h \varphi + m \rho \}_{\mathcal{F}} \|_{0,\mathcal{F},0} \| h_{\mathcal{F}}^{1/2} [\nabla_h \varphi + m \rho]_{\mathcal{F}} \|_{0,\mathcal{F},0}$$

$$\leq 2C_o \| \nabla_h \varphi + m \rho \|_{0,\Omega} \| h_{\mathcal{F}}^{1/2} [\nabla_h \varphi + m \rho]_{\mathcal{F}} \|_{0,\mathcal{F},0}$$

$$\leq \frac{1}{2} \| \nabla_h \varphi + m \rho \|_{0,\Omega}^2 + 4C_o^2 \| h_{\mathcal{F}}^{1/2} [\nabla_h \varphi + m \rho]_{\mathcal{F}} \|_{0,\mathcal{F},0}^2. \quad (33)$$

Finally, using (25) we have that

$$2\text{Re} \left( \{ \sigma^{-1} \text{curl}_h v \} \nabla_h \varphi \right)_{\mathcal{E},0} = 2\| s_{\mathcal{E}} \|_{0}\| \sigma^{-1} \text{curl}_h v \|_{\mathcal{E}} \| \sigma^{-1} \text{curl}_h v \|_{\mathcal{E}} \| \varphi \|_{0,\mathcal{E}}$$

$$\leq 2C_T \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega}^2 \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega} \| \varphi \|_{0,\mathcal{E}}$$

$$\leq \frac{1}{2} \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega}^2 + 4C_T^2 \| \sigma^{-1/2} \text{curl}_h v \|_{0,\Omega} \| \varphi \|_{0,\mathcal{E}}^2. \quad (34)$$

Combining (31) with (32)-(34) and choosing $\alpha_0 = 1/2 + 4C_o^2 + 4C_T^2$, we obtain (30). $\square$

We are now in a position to prove the $\| \cdot \|$-stability of the DG scheme (18).

**Theorem 4.1.** Assume that $\sigma^{-1} j \in H^{1/2+s}(\mathcal{F}_{\Omega}^{0C})$ and $\min \{ a^\Omega, a^{\Omega_t}, \alpha \} \geq \alpha_0$. Then, there exists a unique $(h_h, \psi_h, k_h) \in X_h \times V_h \times \mathbb{C}$ solution of Problem (18). Moreover if $(h, \psi, k) \in [H(\text{curl}, \Omega) \times H(\Omega_t) \times \mathbb{C}] \cap [X^s(\mathcal{T}_h^{0C}) \times H^{1+s}(\mathcal{T}_h^{0C}) \times \mathbb{C}]$ is the solution to (7)-(12) then

$$\| (h - h_h, \psi - \psi_h, k - k_h) \| \leq (1 + 2\sqrt{2}M) \inf_{(h, \psi, k) \in X_h \times V_h} \| (h - h, \psi - \psi, k - k) \|.$$  \quad (35)

**Proof.** The well posedness of Problem (18) follows immediately from Proposition 4.2.

Moreover we deduce from Proposition 4.2 and the consistency of the scheme that

$$\frac{1}{2} \| (h_h - v, \psi_h - \varphi, k_h - m) \|^2$$

$$\leq \text{Re} \left[ (1 - i) A_h \left( (h_h - v, \psi_h - \varphi, k_h - m), (h_{C,h} - v, \psi_h - \varphi, k_h - m) \right) \right]$$

$$= \text{Re} \left[ (1 - i) A_h \left( (h - v, \psi - \varphi, k - m), (h - v, \psi - \varphi, k - m) \right) \right]$$

for all $(v, \varphi, m) \in X_h \times V_h \times \mathbb{C}$. Then from Proposition 4.1 we have

$$\| (h_h - v, \psi_h - \varphi, k_h - m) \| \leq 2\sqrt{2}M \| (h - v, \psi - \varphi, k - m) \|.$$  \quad (36)

The result follows now from the triangle inequality. $\square$

### 5 Asymptotic error estimates

We denote by $\Pi_{h,m}^{\text{curl}}$ the $m$-order $H(\text{curl}, \Omega_C)$-conforming Nédélec interpolation operator of the second kind, see for example [16] or [15, Section 8.2]. It is well known that $\Pi_{h,m}^{\text{curl}}$ is bounded on $H(\text{curl}, \Omega_C) \cap H^s(\text{curl}, \mathcal{T}_h^{0C})$ for $s > 1/2$, where

$$H^{s}(\text{curl}, \mathcal{T}_h^{0C}) := \{ v \in H^{s}(\mathcal{T}_h^{0C}); \, \text{curl}_h v \in H^{s}(\mathcal{T}_h^{0C}) \}.$$
Moreover, there exists a constant $C_1 > 0$ independent of $h$ such that (cf. [4])

$$
\|u - \Pi_{h,m}^{\text{curl}} u\|_{0,\Omega_C} + \|\text{curl}(u - \Pi_{h,m}^{\text{curl}} u)\|_{0,\Omega_C} \leq C_1 h^{\min(s,m)} \left( \|u\|_{s,\Omega_C} + \|\text{curl} u\|_{s,\Omega_C} \right). 
$$

We introduce $L^2_T(\Gamma) = \{ \varphi \in L^2(\Gamma); \varphi \cdot n = 0 \}$ and consider the $m$-order Brezzi-Douglas-Marini (BDM) finite element approximation of the space

$$
H(\text{div}_T, \Gamma) := \{ \varphi \in L^2(\Gamma); \text{div}\varphi \in L^2(\Gamma) \}
$$

relatively to the mesh $\mathcal{F}_h^T$ (see, e.g. [8]). It is given by

$$
\text{BDM}(\mathcal{F}_h^T) = \{ \varphi \in H(\text{div}_T, \Gamma); \varphi|_T \in \mathcal{P}_m(T)^2, \forall T \in \mathcal{F}_h^T \}.
$$

The corresponding interpolation operator $\Pi_{h,m}^{\text{BDM}}$ is bounded on $H(\text{div}_T, \Gamma) \cap \prod_{T \in \mathcal{F}_h^T} \mathcal{H}^s(T)^2$ for all $\delta > 0$ and we recall that it is uniquely characterized on each $T \in \mathcal{F}_h^T$ by the conditions

$$
\int_e \Pi_{h,m}^{\text{BDM}} \varphi \cdot n_T q = \int_e \varphi \cdot n_T q \quad \forall q \in \mathcal{P}_m(e), \quad \forall e \in \mathcal{E}(T),
$$

$$
\int_T \Pi_{h,m}^{\text{BDM}} \varphi \cdot q = \int_T \varphi \cdot q \quad \forall q \in \mathcal{P}_{m-2}(T)^2 + \mathcal{S}_{m-1}(T),
$$

where $\mathcal{S}_{m-1}(T) := \{ q \in \tilde{\mathcal{P}}_{m-1}(T)^2; \quad q \cdot \left( \begin{array}{c} x_1 \\ x_2 \end{array} \right) = 0 \}$ with $\tilde{\mathcal{P}}_{m-1}(T)$ representing the set of homogeneous polynomials of degree $m - 1$ and $\left( \begin{array}{c} x_1 \\ x_2 \end{array} \right)$ being the local variable on the plane containing $T$.

The commuting diagram property

$$
(\Pi_{h,m}^{\text{curl}} u) \times n_T = \Pi_{h,m}^{\text{BDM}} (u \times n_T)
$$

holds true for all $u \in H(\text{curl}, \Omega_C) \cap H^s(\text{curl}, \mathcal{T}_h^{\Omega_C}), s > 1/2$, see [11, section 9] for more details.

For all $K \in \mathcal{T}_h^{\Omega_T}$ we define the local interpolation operator $\tilde{\pi}_{K,m} : H^{1+s}(K) \to \tilde{\mathcal{P}}_m(K)$, $s > 1/2$ as follows: recalling the definition of $\mathcal{P}_m(K)$ given in (17)

- if $\partial K \cap \Gamma \not\in \mathcal{F}_h^T$ then $\tilde{\mathcal{P}}_m(K) = \mathcal{P}_m(K)$ and we take $\tilde{\pi}_{K,m} = \pi_{K,m}$, where $\pi_{K,m}$ is defined as in [15, Section 5.6];

- if $\partial K \cap \Gamma = T \in \mathcal{F}_h^T$ then $\tilde{\mathcal{P}}_m(K) = \mathcal{P}_m(K) + \mathcal{P}^T_{m+1}(K)$ and $\tilde{\pi}_{K,m}$ is defined by changing the conditions defining $\pi_{K,m}$ on $T$ and on the edges composing $T$ into

$$
\int_T \tilde{\pi}_{K,m} pq = \int_T pq \quad \forall q \in \mathcal{P}_{m-2}(T)
$$

and

$$
\int_e \tilde{\pi}_{K,m} pq = \int_e pq \quad \forall q \in \mathcal{P}_{m-1}(e), \quad \forall e \in \mathcal{E}(F)
$$

respectively. The remaining degrees of freedom are the same as those defining $\pi_{K,m}$, see [15, Section 5.6].
We notice that \(\dim(\mathcal{P}_m(K) + \mathcal{P}^T_{m+1}(K)) = \dim(\mathcal{P}_m(K)) + m + 1\) and the number of degrees of freedom defining \(\tilde{\pi}_{K,m}\) is equal to the number of degrees of freedom of \(\pi_{K,m}\) plus \(\dim(\mathcal{P}_{m-2}(T)) - \dim(\mathcal{P}_{m-3}(T)) = m - 1\) additional degrees of freedom on \(T\) and one additional degree of freedom on each of the three edges of \(T\), which gives a total of \(\dim(\mathcal{P}_m(K)) + m + 1\) degrees of freedom. Using this fact, it is straightforward to show that \(\tilde{\pi}_{K,m}\) is uniquely determined on elements \(K \in \mathcal{T}_h^{\Omega_t}\) with a face \(T\) lying on \(\Gamma\). Moreover, it is clear that the corresponding global \(H^1(\Omega)\)-conforming interpolation operator \(\tilde{\pi}_{h,m}\) satisfies the following interpolation error estimate.

**Proposition 5.1.** If \(p \in H^1(\Omega_t) \cap H^{1+s}(\mathcal{T}_h^{\Omega_t})\) with \(s > 1/2\), there exists a constant \(C > 0\) independent of \(h\) such that
\[
\|\nabla(p - \tilde{\pi}_{h,m}p)\|_{0,\Omega_t} \leq C h^{\min(m,s)}\|p\|_{1+s,\mathcal{T}_h^{\Omega_t}}. \tag{42}
\]

**Proof.** See [15, Lemma 5.47] and [15, Theorem 5.48]. \(\square\)

The commuting diagram property stated in the next proposition is the reason for which we use \(\tilde{\pi}_h\) instead of the usual Lagrange interpolation operator.

**Proposition 5.2.** For any \(p \in H^1(\Omega) \cap H^{1+s}(\mathcal{T}_h^{\Omega_t})\), with \(s > 1/2\), it holds
\[
\nabla \tilde{\pi}_{h,m}p \times n_\Gamma = \Pi_{h,m}^{BDM}(\nabla p \times n_\Gamma).
\]

**Proof.** We first notice that \(\nabla \tilde{\pi}_{h,m}p \times n_\Gamma \in \mathbf{H}(\text{div}_\Gamma, \Gamma)\) and \(\nabla \tilde{\pi}_{h,m}p \times n_\Gamma \in \mathcal{P}_m(T)\) for all \(T \in \mathcal{F}_h^T\). Hence, \(\nabla \tilde{\pi}_{h,m}p \times n_\Gamma \in \text{BDM}(\mathcal{F}_h^T)\). To show that \(\nabla \tilde{\pi}_{h,m}p \times n_\Gamma = \Pi_{h,m}^{BDM}(\text{curl}_\Gamma p)\), it is sufficient to compare the degrees of freedom of these two tangential fields on each triangle \(T \in \mathcal{F}_h^T\). On the one hand, for all \(q \in \mathcal{P}_m(e), e \in \mathcal{E}(T)\),
\[
\int_e (\nabla \tilde{\pi}_{h,m}p \times n_\Gamma - \Pi_{h,m}^{BDM}(\nabla p \times n_\Gamma)) \cdot n_F q = 0,
\]
where the last identity follows from the fact that \(\tilde{\pi}_{h,m}p\) and \(p\) must coincide at the endpoints \(a_e\) and \(b_e\) of edge \(e\) (by definition of the \(\tilde{\pi}_{h,m}\)) and from (41), taking into account that \(\frac{\partial q}{\partial t_e} \in \mathcal{P}_{m-1}(e)\).

On the other hand, for any \(q \in \mathcal{P}_{m-2}(T)^2 + \mathbf{S}_{m-1}(T)\), we have that
\[
\int_T (\nabla \tilde{\pi}_{h,m}p \times n_\Gamma - \Pi_{h,m}^{BDM}(\nabla p \times n_\Gamma)) \cdot q = 0
\]
\[
= \int_T \nabla (\tilde{\pi}_{h,m}p - p) \times n_\Gamma \cdot q = -\int_T \nabla (\tilde{\pi}_{h,m}p - p) \cdot (q \times n_\Gamma)
\]
\[
= \int_T (\tilde{\pi}_{h,m}p - p) \, \text{div}_\Gamma(q \times n_\Gamma) - \sum_{e \in \mathcal{E}(T)} \int_e (\tilde{\pi}_{h,m}p - p)(q \times n_\Gamma) \cdot \mathbf{n}_e
\]
\[
= \int_T (\tilde{\pi}_{h,m}p - p) \, \text{div}_\Gamma(q \times n_\Gamma) - \sum_{e \in \mathcal{E}(T)} \int_e (\tilde{\pi}_{h,m}p - p) \mathbf{q} \cdot t_e = 0
\]
by virtue of (40) and (41), since $\text{div}_\Gamma (q \times n_\Gamma) \in P_{m-2}(F)$ and $q \cdot t_e \in P_{m-1}(e)$. 

Finally, we consider the $L^2(\mathcal{T}_h^{\Omega_C})$-orthogonal projection $P^k_{\mathcal{T}_h^{\Omega_C}}$ onto $\prod_{K \in \mathcal{T}_h^{\Omega_C}} P_k(K)^3$ and the $L^2(\mathcal{T}_h^{\Omega_I})$-orthogonal projection $P^k_{\mathcal{T}_h^{\Omega_I}}$ onto $\prod_{K \in \mathcal{T}_h^{\Omega_I}} P_k(K)^3$, $k \geq 0$. We denote indifferently by $\Pi^k$ the restriction of $P^k_{\mathcal{T}_h^{\Omega_C}}$ and $P^k_{\mathcal{T}_h^{\Omega_I}}$ to an element $K$.

**Lemma 5.1.** For all $K \in \mathcal{T}_h$ and $w \in H^s(K)$, $r \geq 1/2$, we have

$$h_F \| w - P^k_K w \|_{0,F} + h^{rac{1}{2}}_K \| w - P^k_K w \|_{0,K} + \| w - P^k_K w \|_{0,K} \leq C h^{\min\{r,k+1\}}_K \| w \|_{r,K}, \quad (43)$$

with a constant $C > 0$ independent of $h$.

**Proof.** See [9], Lemma 1.58 and Lemma 1.52.

We are now in a position to prove the main result of this section.

**Theorem 5.1.** Let $(h, \psi, k) \in H(\text{curl}, \Omega_C) \times H^1(\Omega_I) \times \mathbb{C}$ and $(h_h, \psi_h, k_h) \in X_h \times V_h \times C$ be the solutions to (7)-(12) and (18) respectively. If $\sigma^{-1} j \in H^{1/2+s}(\mathcal{T}_h^{\Omega_C})$, $(h, \psi) \in X^s(\mathcal{T}_h^{\Omega_C}) \times H^{1+s}(\mathcal{T}_h^{\Omega_I})$, with $s > 1/2$, and $\min(a^{\Omega_C}, a^{\Omega_I}, \alpha) \geq \alpha_0$, then

$$\|(h - h_h, \psi - \psi_h, k - k_h)\| \leq C h^{\min(s,m)} \| (h)_{s,T_h^0} \| + \| \text{curl} h \|_{1/2+s,T_h^0} + \| \psi \|_{1+s,T_h^{\Omega_I}},$$

where $C > 0$ is a constant independent of $h$.

**Proof.** Taking $(\nu, \varphi) = (\Pi_{h,m} \text{curl} h, \tilde{\pi}_{h,m} \psi)$ in (35) yields

$$\|(h - h_h, \psi - \psi_h, k - k_h)\| \leq (1 + 2\sqrt{2} M) \|(h - \Pi_{h,m} \text{curl} h, \psi - \tilde{\pi}_{h,m} \psi, 0)\|_{*}.$$

All the jumps terms in the right-hand side of the last inequality are zero since the identities

$$(\Pi_{h,m} \text{curl} h) \times n = \Pi_{h,m} \text{BDM} (h \times n_\Gamma) = \Pi_{h,m} \text{BDM} ((\nabla \psi + k \rho) \times n_\Gamma) = (\nabla \tilde{\pi}_{h,m} \psi + k \rho) \times n_\Gamma \quad (44)$$

holds true on $\Gamma$ and we also have that

$$\|[\psi - \tilde{\pi}_{h,m} \psi]_F = \|[\psi - \tilde{\pi}_{h,m} \psi]_\mathcal{E} = 0,$$

by construction. Note that in the last equality of (44) we have used the fact that $\rho$ belongs to $H(\text{curl}; \Omega_I)$ and is a piecewise-linear polynomial. It follows that,

$$\| (h - \Pi_{h,m} \text{curl} h, \psi - \tilde{\pi}_{h,m} \psi, 0) \|_{*}^{2}$$

$$= \| (\omega \mu)^{1/2} (h - \Pi_{h,m} \text{curl} h) \|_{0,\Omega_C}^{2} + \| \sigma^{-1/2} \text{curl} (h - \Pi_{h,m} \text{curl} h) \|_{0,\Omega_C}^{2}$$

$$+ \omega \mu_0 \| \nabla h (\psi - \tilde{\pi}_{h,m} \psi) \|_{0,\Omega_I}^{2} + \| s^{1/2} \sigma^{1/2} (\sigma^{-1} \text{curl} (h - \Pi_{h,m} \text{curl} h)) \|_{0,\mathcal{F}}^{2}$$

$$+ \| s^{1/2} \sigma^{-1/2} \text{curl} (h - \Pi_{h,m} \text{curl} h) \|_{0,\mathcal{E}}^{2} + \| h^{1/2} \{ \nabla (\psi - \tilde{\pi}_{h,m} \psi) \} \|_{0,\mathcal{F}}^{2}.$$
We deduce from the triangle inequality that,

\[
\|s^{1/2}h^{1/2}\{\sigma^{-1}\text{curl}(h - \Pi_{h,m}^{\text{curl}})}\|_{0,F_h^{\Omega_C}} = \|s^{1/2}h^{1/2}\{\sigma^{-1}(\text{curl}h - P_{\tau_h^{\Omega_C}}^{m-1}\text{curl}h)}\|_{0,F_h^{\Omega_C}} \\
+ \|s^{1/2}h^{1/2}\{\sigma^{-1}(P_{m-1}^{\Omega_C}\text{curl}h - \text{curl}\Pi_{h,m}^{\text{curl}})}\|_{0,F_h^{\Omega_C}} = A_{\Omega_C} + B_{\Omega_C}.
\]

Using (25) yields

\[
B_{\Omega_C} \leq C_{\Omega_C}\|\sigma^{-1/2}(P_{\tau_h^{\Omega_C}}^{m-1}\text{curl}h - \text{curl}\Pi_{h,m}^{\text{curl}}h)\|_{0,\Omega_C} \\
= C_{\Omega_C}\|\sigma^{-1/2}P_{\tau_h^{\Omega_C}}^{m-1}\text{curl}h - \text{curl}\Pi_{h,m}^{\text{curl}}h\|_{0,\Omega_C} \leq C_{\Omega_C}\|\sigma^{-1/2}\text{curl}(h - \Pi_{h,m}^{\text{curl}}h)\|_{0,\Omega_C}
\]

and by virtue of (27) we obtain

\[
A_{\Omega_C}^2 \leq \sum_{K \in F_h^{\Omega_C}} h_K\|\sigma^{-1/2}(\text{curl}h - P_{K}^{m-1}\text{curl}h)\|^2_{0,\partial K}.
\]

Similarly, we consider the splitting

\[
\|s^{1/2}h^{1/2}\{\sigma^{-1}\text{curl}(h - \Pi_{h,m}^{\text{curl}})}\|_{0,\mathcal{E}_h} \leq \|s^{1/2}h^{1/2}\{\sigma^{-1}(\text{curl}h - P_{\tau_h^{\Omega_C}}^{m-1}\text{curl}h)}\|_{0,\mathcal{E}_h} \\
+ \|s^{1/2}h^{1/2}\{\sigma^{-1}(P_{m-1}^{\tau_h^{\Omega_C}}\text{curl}h - \text{curl}\Pi_{h,m}^{\text{curl}}h)}\|_{0,\mathcal{E}_h} = A_{\mathcal{E}} + B_{\mathcal{E}}
\]

and use (25) to obtain

\[
B_{\mathcal{E}} \leq C_{\mathcal{E}}\|\sigma^{-1/2}(P_{\tau_h^{\Omega_C}}^{m-1}\text{curl}h - \text{curl}\Pi_{h,m}^{\text{curl}}h)\|_{0,\Omega_C} \\
= C_{\mathcal{E}}\|\sigma^{-1/2}P_{\tau_h^{\Omega_C}}^{m-1}\text{curl}h - \text{curl}\Pi_{h,m}^{\text{curl}}h\|_{0,\Omega_C} \leq C_{\mathcal{E}}\|\sigma^{-1/2}\text{curl}(h - \Pi_{h,m}^{\text{curl}}h)\|_{0,\Omega_C}.
\]

Moreover, it follows from (28) that

\[
A_{\mathcal{E}}^2 \leq \sum_{T \in T_h^{\Omega_C}} h_T^2\|\sigma^{-1/2}(\text{curl}h - P_{K}^{m-1}\text{curl}h)\|^2_{0,\partial T}.
\]

Finally,

\[
\|h^{1/2}\{\nabla(\psi - \overline{\pi}_{h,m}\psi)}\|_{0,F_h^{\Omega_I}} \leq \|h^{1/2}\{\nabla\psi - P_{\tau_h^{\Omega_I}}^{m}\nabla\psi}\|_{0,F_h^{\Omega_I}} \\
+ \|h^{1/2}\{P_{\tau_h^{\Omega_I}}^{m}\nabla\psi - \nabla\overline{\pi}_{h,m}\psi}\|_{0,F_h^{\Omega_I}} = A_{\Omega_I} + B_{\Omega_I}
\]

and we derive from (26) and (29) the following estimates

\[
B_{\Omega_I} \leq C_{\Omega_I}\|P_{\tau_h^{\Omega_I}}^{m}\nabla\psi - \nabla\overline{\pi}_{h,m}\psi\|_{0,\Omega_I} \leq C_{\Omega_I}\|\nabla(\psi - \overline{\pi}_{h,m}\psi)\|_{0,\Omega_I},
\]

\[
A_{\Omega_I}^2 \leq \sum_{K \in T_h^{\Omega_I}} h_K\|\nabla\psi - P_{K}^{m}\nabla\psi\|^2_{0,\partial K}.
\]
Combining the last inequalities we deduce that

\[
\| (h - \Pi_{h,m}^{\text{curl}} h, \psi - \tilde{\pi}_{h,m} \psi) \|_2^* \leq C \left( \| h - \Pi_{h,m}^{\text{curl}} h \|_{0,\Omega_C}^2 + \| \text{curl}(h - \Pi_{h,m}^{\text{curl}} h) \|_{0,\Omega_C}^2 
\right.
\]

\[
+ \| \nabla h(\psi - \tilde{\pi}_{h,m} \psi) \|_{0,\Omega_I}^2 + \sum_{K \in \mathcal{T}_h^{\Omega_C}} h_K \| \text{curl} h - P_K^{m-1} \text{curl} h \|_{0,\partial K}^2
\]

\[
+ \sum_{T \in \mathcal{F}_h^{\Omega_C}} h_T^2 \| \text{curl} h - P_K^{m-1} \text{curl} h \|_{0,\partial T}^2 + \sum_{K \in \mathcal{T}_h^{\Omega_I}} h_K \| \nabla \psi - P_K^n \nabla \psi \|_{0,\partial K}^2
\]

with \( C > 0 \) independent of \( h \). Applying the interpolation error estimates given by (36), (42) and (43) we obtain

\[
\| (h - \Pi_{h,m}^{\text{curl}} h, \psi - \tilde{\pi}_{h,m} \psi) \|_* \leq C \left( h_{\text{min}(s,m)} \| h \|_{s,T_h^{\Omega_C}} + \| \text{curl} h \|_{s,T_h^{\Omega_C}} + h_{\text{min}(s,m)} \| \psi \|_{1+s,T_h^{\Omega_I}} 
\right.
\]

\[
+ h_{\text{min}(1/2+s,m)} \| \text{curl} h \|_{1/2+s,T_h^{\Omega_C}} + h_{\text{min}(s,m+1)} \| \nabla \psi \|_{s,T_h^{\Omega_I}}
\]

and the result follows.

6 Numerical results

We performed numerical experiments consisting in the implementation (in a MATLAB code) of the DG method (18) to solve the eddy current problem (7)-(12). Actually, in order to have at our disposal an analytical solution of the problem we considered the associated transmission problem

\[
\begin{align*}
\dot{h} + \text{curl}(\text{curl} h) &= f & \text{in } \Omega_C \\
h \times n_\Gamma &= \nabla \psi \times n_\Gamma + g_1 & \text{on } \Gamma \\
h \cdot n_\Gamma &= \nabla \psi \cdot n_\Gamma + g_2 & \text{on } \Gamma \\
\Delta \psi &= 0 & \text{in } \Omega_I \\
\psi &= \psi_* & \text{on } \Sigma,
\end{align*}
\]

in the domains \( \Omega_C := (0.25,0.75)^3 \) and \( \Omega_I := (0,1)^3 \setminus \overline{\Omega_C} \) and with data \( f, g_1, g_2 \) and \( \psi_* \) chosen in such a way that the exact solutions are

\[
h(x) = (1 + i) \begin{pmatrix}
\sin(2\pi x_1) \\
\sin(2\pi x_2) \\
\sin(2\pi x_3)
\end{pmatrix} \quad \text{in } \Omega_C,
\]

and \( \psi(x) = \frac{1}{|x-x_*|} + \frac{1}{|x-x'|} i \) in \( \Omega_I \) (having set \( x_* = (2,0,0)^t \) and \( x' = (0,0,3)^t \)).

We use the following notations:

\[
e_h(h, \psi) := \|(h - h_h, \psi - \psi_h)\|, \quad (45)
\]
namely, the error of the method in the DG norm (23), and
\[
e_h(h)^2 := \| (\nu \mu)^{1/2} (h - h_\nu) \|_{\sigma,\Omega}^2 + \| \sigma^{-1/2} \text{curl}_h (h - h_\nu) \|_{\sigma,\Omega}^2
\]
\[
+ \| s_F^{-1/2} h_F^{-1/2} \left[ (h - h_\nu, \psi - \psi_h, 0) \right]_F \|_{\sigma,\Omega}^2,
\]
\[
e_h(\psi)^2 := \nu \mu \| \nabla_h (\psi - \psi_h) \|_{\sigma,\Omega}^2 + \nu \mu \| h_F^{-1/2} \left[ (\psi - \psi_h) n_F \right]_F \|_{\sigma,\Omega}^2,
\]
\[
+ \| s_\epsilon^{-1/2} h_\epsilon^{-1} \left[ (\psi - \psi_h) t F \right]_F \|_{\sigma,\Omega}^2.
\]
Note that \( e_h(h, \psi)^2 = e_h(h)^2 + e_h(\psi)^2 \).

We consider the experimental rate of convergence defined by
\[
\gamma_h(h, \psi) := \frac{\log(e_h(h, \psi)/e_h(h, \psi))}{\log(h/\hat{h})},
\]
where \( h \) and \( \hat{h} \) denote two different mesh sizes with corresponding errors \( e_h(h, \psi) \) and \( e_h(h, \psi) \). We use a similar definition for \( \gamma_h(h) \) and \( \gamma_h(\psi) \).

We report in Table 1 the errors and the convergence orders obtained for different meshes for \( m = 1 \) and by considering stabilization parameters \( a^{oc} = a^{oy} = \alpha = 50 \). The meshes are obtained by dividing the domain in small cubes of size \( 1/M \) and then dividing each small cube in 6 tetrahedra. Thus the total number of elements is \( \text{nelem} = 6M^3 \), the number of elements in the conductor is \( \text{nec} = \frac{1}{5} \text{nelem} \), the number of elements in the insulator is \( \text{nei} = \frac{7}{5} \text{nelem} \) and the number of faces on the interface is \( \text{nfg} = 3M^2 \). Let us recall that the finite element space \( V_h \) is defined through (17), hence the number of degrees of freedom reported in Table 1 is \( \text{ndof} = 12\text{nec} + 4\text{nei} + 6\text{nfg} \).

| \( M \) | \( \text{ndof} \) | \( e_h(h, \psi) \) | \( \gamma_h(h, \psi) \) | \( e_h(h) \) | \( \gamma_h(h) \) | \( e_h(\psi) \) | \( \gamma_h(\psi) \) |
|---|---|---|---|---|---|---|---|
| 4 | 2208 | 2.044e-00 | - | 2.007e-00 | - | 3.943e-01 | - |
| 8 | 16512 | 1.010e-00 | 1.018 | 1.099e-00 | 0.992 | 5.265e-02 | 2.905 |
| 12 | 54432 | 6.675e-01 | 1.021 | 6.671e-01 | 1.020 | 2.477e-02 | 1.859 |
| 16 | 127488 | 4.978e-01 | 1.020 | 4.975e-01 | 1.020 | 1.733e-02 | 1.242 |
| 20 | 247200 | 3.967e-01 | 1.017 | 3.965e-01 | 1.017 | 1.352e-02 | 1.080 |
| 24 | 425088 | 3.297e-01 | 1.015 | 3.295e-01 | 1.015 | 1.128e-02 | 1.034 |

Table 1: Convergence history of the DG method with \( m = 1 \).

It is easily verified that the correct linear convergence rate is achieved.

Let us underline that the DG discretization of the eddy current model written in terms of the electric field \( \mathbf{e} \) (see the formulation proposed in [17]) would have a larger number of degrees of freedom when using polynomials of degree \( m = 1 \): precisely, \( \text{ndof} = 12(\text{nec} + \text{nei}) \).

We have repeated the computations using polynomial of degree \( m+1 = 2 \) in the whole insulator and not only in the faces of the interface. Therefore the number of degrees of freedom reported in Table 2 is \( \text{ndof} = 12\text{nec} + 10\text{nei} \).
\[
\begin{array}{|c|c|c|c|c|c|c|}
\hline
M & \text{ndof} & e_h(h, \psi) & r_h(h, \psi) & e_h(h) & r_h(h) & e_h(\psi) & r_h(\psi) \\
\hline
4  & 3936  & 2.099e-00 & - & 2.031e-00 & - & 5.319e-01 & - \\
8  & 31488 & 1.011e-00 & 1.054 & 1.009e-00 & 1.009 & 5.811e-00 & 3.194 \\
12 & 106272 & 6.673e-01 & 1.025 & 6.671e-01 & 1.021 & 1.528e-02 & 3.295 \\
16 & 251904 & 4.975e-01 & 1.020 & 4.975e-01 & 1.020 & 6.158e-03 & 3.158 \\
20 & 492000 & 3.965e-01 & 1.017 & 3.965e-01 & 1.017 & 3.231e-03 & 3.891 \\
\hline
\end{array}
\]

Table 2: Convergence history of the DG method with \( m = 1 \) in the conductor and \( m = 2 \) in the insulator.

As expected, in the insulator one sees a higher order of convergence than in the previous case. A reasonable guess is in fact a second order convergence in the insulator. However, for the same \( M \) the number of degrees of freedom is around the double.

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