Spinor Construction of the $c = 1/2$ Minimal Model

Alex J. Feingold, John F. X. Ries, Michael D. Weiner

1. Introduction

The representation theories of affine Kac-Moody Lie algebras and the Virasoro algebra have been found to have interesting connections with many other parts of mathematics and have played a vital role in the development of conformal field theory in theoretical physics. (See [BPZ], [GO], [BMP], [MS], [TK], the Introduction and references in [FLM].) An important contribution to Kac-Moody representation theory was the rigorous mathematical construction of representations using vertex operators, discovered independently by mathematicians and physicists, but known earlier by physicists. Once the connection was discovered, an exciting dialog began which has enriched both sides. The precise axiomatic definition of vertex operator algebras (VOA’s) by mathematicians [FLM] gave a rigorous foundation to the algebraic aspects of conformal field theory called chiral algebras by physicists. This theory includes, unifies and vastly extends the representation theories of affine Kac-Moody algebras and the Virasoro algebra.

In the theory of VOA’s one has the notion of a module and of intertwining operators going between modules [FHL], [F]. The main axiom for a VOA is an identity called the Jacobi-Cauchy identity because it combines the usual Jacobi identity for Lie algebras with the Cauchy residue formula for rational functions whose possible poles are limited to three points, 0, 1 and $\infty$. A slight modification is needed for the appropriate definition of a module, and intertwining operators are defined by a similar axiom relating them to vertex operators. We believe that an important next step is the understanding of a new kind of “matrix” Jacobi-Cauchy identity relating any two intertwining operators. This would lead to a larger unifying structure, incorporating a VOA, its modules and its intertwining operators.

There are several new features which appear when trying to understand intertwining operators and the new kind of Jacobi-Cauchy identity they obey. First one...
has to deal with fusion rules,
\[ N(M_1, M_2, M_3) = \dim(I(M_1, M_2, M_3)), \]
which give the dimension of the space of intertwining operators determined by a triple of modules. It is a basic principle of VOAs’s that there is a one-to-one correspondence between vectors \( v \) in a simple VOA \( V \) and vertex operators \( Y_M(v, z) \) acting on an irreducible \( V \)-module \( M \). One can think of this as a map
\[ Y_M(\cdot, z) : V \to \text{End}(M)[[z, z^{-1}]] \]
which obeys the various axioms defining a \( V \)-module. The fusion rule in this case is always \( N(V, M, M) = 1 \) and one axiom normalizes \( Y_M \) so it is uniquely determined. Given three \( V \)-modules, \( M_1, M_2, M_3 \), one can think of an intertwining operator as a map
\[ Y(\cdot, z) : M_1 \to \text{Hom}(M_2, M_3)\{\{z, z^{-1}\}\} \]
which obeys the axioms for intertwining operators. (The notation \( \{\{z, z^{-1}\}\} \) indicates rational powers of \( z \).) It is quite possible that the fusion rule is \( N(M_1, M_2, M_3) = 1 \) and in that case one does not have a one-to-one correspondence between vectors \( w \) in module \( M_1 \) and operators \( Y(w, z) \) whose components send \( M_2 \) to \( M_3 \). It would seem that this is a kind of labeling problem, there not being enough “copies” of the vectors in \( M_1 \) to distinguish the \( n \) linearly independent intertwiners which could be taken as a basis for the space of all intertwiners. It is also possible to have four modules \( M_1, \ldots, M_4 \) with \( M_3 \neq M_4 \), with fusion rules \( N(M_1, M_2, M_3) \geq 1 \) and \( N(M_1, M_2, M_4) \geq 1 \). This also indicates a labeling problem, showing the inadequacy of the notation \( Y(w_1, z)w_2 \), where knowing that \( w_1 \in M_i \) still does not determine which module contains the outcome.

Another new feature which appears is the nature of the correlation functions,

\[ (Y(w_1, z_1)Y(w_2, z_2)w_3, w_4) \quad \text{and} \quad (Y(Y(w_1, z)w_2, z_2)w_3, w_4), \]

made from two intertwiners. These are series which converge in certain domains to functions which, after factoring out some rational powers of \( z_1 \) and \( z_2 \), can be expressed as power series in \( z_2/z_1 \) and \( z/z_2 \) satisfying certain differential equations. One way of thinking of the usual Jacobi-Cauchy identity for a VOA \( V \) is as follows. The three series

\[ (Y(v_1, z_1)Y(v_2, z_2)v_3, v_4), \quad (Y(v_2, z_2)Y(v_1, z_1)v_3, v_4) \]

and

\[ (Y(Y(v_1, z_1 - z_2)v_2, z_2)v_3, v_4) \]

converge in their respective domains, \(|z_1| > |z_2|\), \(|z_2| > |z_1|\), and \(|z_2| > |z_1 - z_2|\), to the same rational function \( f(z_1, z_2) \) in the ring
\[ R = \mathbb{C}[z_1, z_1^{-1}, z_2, z_2^{-1}, (z_1 - z_2)^{-1}]. \]

For fixed \( z_2 \neq 0 \), these are functions of \( z_1 \) with possible poles only at \( z_1 = 0 \), \( z_1 = \infty \) and \( z_1 = z_2 \). The Jacobi-Cauchy identity is just the statement of the Cauchy residue theorem applied to \( f(z_1, z_2)g(z_1, z_2) \), where \( g(z_1, z_2) \in R \) is arbitrary, and the residues at each of the three points are computed from the three series giving \( f \) and appropriate series expansions of \( g \). But the kinds of correlation functions obtained from intertwiners generally involve hypergeometric functions to which the treatment just described does not apply.
The purpose of this paper is to show how both of these new features can be handled in a simple but nontrivial example which may have important applications. In the monograph [FFR] we constructed certain vertex operator superalgebras (VOSA’s) and their twisted modules from Clifford algebras and their spinor representations. These “fermionic” constructions extend the corresponding constructions of the orthogonal affine Kac-Moody algebras of type $D_n^{(1)}$ in [FF], (See [Fr1], [Fr2]). In [W] vertex operator para-algebras were constructed from the bosonic constructions of level $-\frac{1}{2}$ representations of symplectic affine Kac-Moody algebras of type $C_n^{(1)}$. It is well known to physicists, and follows immediately from the work in [FFR], that a spinor construction from one fermion gives a VOSA and a twisted module for it. These are known in the physics literature as the Neveu-Schwarz and Ramond sectors, respectively, and they each decompose into two irreducible modules for the Virasoro algebra with central charge $c = \frac{1}{2}$. Using the usual notation for labeling Virasoro modules, the two components into which the Neveu-Schwarz sector decomposes are labeled by $h = 0$ and $h = \frac{1}{2}$, and the two coming from the Ramond sector are both $h = \frac{1}{16}$. It is very interesting and important that in this construction one naturally has two copies of the $h = \frac{1}{16}$ Virasoro module. That enables us to define unique intertwining operators for each vector in the Ramond sector, such that the usual Ising fusion rules for just three modules are replaced by fusion rules given by the group $\mathbb{Z}_4$. This behavior is just like the behavior of vertex operator para-algebras defined in [FFR]. (See also [DL].) It means that the VOA $V$ and its modules are indexed by a finite abelian group $\Gamma$ such that $V = V_0$ ($0 \in \Gamma$ is the identity element) and the fusion rules are $N(V_a, V_b, V_c) = 1$ if $a + b = c$ in $\Gamma$, zero otherwise. The important question is whether this is a rare special situation, or if there are other natural constructions of VOAs where multiple copies of the modules allow unique labeling of intertwining operators and where fusion rules are replaced by a group law.

In the example studied here we find that the hypergeometric functions to which the correlation function converge, come in pairs, as bases for the two dimensional spaces of solutions of certain differential equations. In order to relate them to each other, we must use Kummer’s quadratic transformation formula. This involves certain substitutions which lift the correlation functions of $t = z_2/z_1$ to functions of $x$ on a four-sheeted covering of the $t$-sphere, branched at $t = 0, 1, \infty$ with possible poles only at $x = \alpha \in \{0, \infty, 1, -1, i, -i\}$. We may then find the $2 \times 2$ matrices $B_\alpha$ which relate the $2 \times 4$ matrices of transformed correlation functions at $x = 0$ to those at $x = \alpha$. The matrix-valued functions have possible poles only at those six points, so after multiplying the matrix-valued functions by any function $g(x)$ in the ring

$$\mathcal{R}_x = \mathbb{C}[x, x^{-1}(x^4 - 1)^{-1}]$$

the Cauchy residue theorem gives that the sum of their residues at the six points adds up to zero. Expressing the residues in terms of the series and expanding the function $g(x)$ as an appropriate series, we get a “matrix” Jacobi-Cauchy identity. It is, of course, actually a generating function of identities, equivalent to infinitely many identities for the components of the intertwining operators. It may take some time to sort out which ones are the most important, but we can already point out some interesting ones.

A very interesting aspect of this example is the structure of the matrices $B_\alpha$. In order to find those matrices one must choose some linear fractional transformations...
relating the variable $x = x_0$ to the variables $x_\alpha$ which are local variables at the poles. There are several sign choices which can be made, and these correspond to choices of braiding. It is not so surprising that these matrices provide a representation of a braid group. The details of this aspect of the example have not been completely worked out yet, and will be studied later. There should be an interesting connection with the work in [MaS].

As a final motivation for the detailed study of this special example, we would like to mention the possible application to a spinor construction of the moonshine module for the monster group. It has been noted by Dong, Mason and Zhu [DMZ] that there are 48 commuting $c = \frac{1}{2}$ Virasoro algebras in the moonshine module $V^\sharp$ considered as a VOA. It means that $V^\sharp$ decomposes into a sum of tensor products of 48 Virasoro modules, each of which is one of the $h = 0$, $h = \frac{1}{2}$ or $h = \frac{1}{16}$ modules. Although some information is known about this decomposition, the complete picture is not clear. But since there is a spinor construction of each of these modules, there is some hope that a spinor construction of $V^\sharp$ is possible. In fact, we hope that the new light we have shed on the $c = \frac{1}{2}$ minimal model will be of help in achieving that goal.

2. Construction of Vertex Operator Superalgebra and Module

Let $E = \mathbb{C}e$ with $\langle e, e \rangle = 2$ and let $Z = Z$ or $Z = Z + \frac{1}{2}$. Let $E(Z)$ be the vector space with basis $\{e(m) \mid m \in Z\}$ and the symmetric form

$$\langle e(m), e(n) \rangle = \langle e, e \rangle \delta_{m,-n} = 2\delta_{m,-n}.$$ 

Let $\text{Cliff}(Z)$ be the Clifford algebra generated by $E(Z)$ and that form. Let $E(Z) = E(Z)^+ \oplus E(Z)^-$ be the polarization where $E(Z)^+$ is spanned by $\{e(m) \mid 0 < m \in Z\}$ and $E(Z)^-$ is spanned by $\{e(m) \mid 0 \geq m \in Z\}$. Define $\mathcal{J}(Z)$ to be the left ideal in $\text{Cliff}(Z)$ generated by $E(Z)^+$, so that

$$\text{CM}(Z) = \text{Cliff}(Z)/\mathcal{J}(Z)$$

is a left $\text{Cliff}(Z)$-module. One has the parity decomposition

$$\text{CM}(Z) = \text{CM}(Z)^0 \oplus \text{CM}(Z)^1$$

where $\text{CM}(Z)^i$, $i = 0, 1$, is the subspace with basis

$$\{e(-m_1) \ldots e(-m_r) \text{vac}(Z) \mid m_1 > \ldots > m_r \geq 0, \ m_1, \ldots, m_r \in Z, \ r \equiv i \mod 2\}$$

and $\text{vac}(Z) = 1 + \mathcal{J}(Z)$. Define the vacuum space

$$\text{VAC}(Z) = \{v \in \text{CM}(Z) \mid E(Z)^+ \cdot v = 0\}.$$ 

Then $\text{VAC}(Z + \frac{1}{2})$ is one-dimensional, spanned by

$$\text{vac} = \text{vac}(Z + \frac{1}{2}) = 1 + \mathcal{J}(Z + \frac{1}{2}),$$

and $\text{VAC}(Z)$ is two-dimensional, spanned by

$$\text{vac}' = \text{vac}(Z) = 1 + \mathcal{J}(Z) \quad \text{and} \quad e(0)\text{vac}'.$$

It is easy to see that $\text{CM}(Z + \frac{1}{2})$ is an irreducible $\text{Cliff}(Z + \frac{1}{2})$-module, but $\text{CM}(Z)$ decomposes into two irreducible $\text{Cliff}(Z)$-modules. Note that

$$\text{vac}'_+ = \text{vac}' + e(0)\text{vac}' \quad \text{and} \quad \text{vac}'_- = \text{vac}' - e(0)\text{vac}'$$
are eigenvectors for \( e(0) \) with eigenvalues +1 and −1, respectively, because the relations in \( \text{Cliff}(\mathbb{Z}) \) give \( e(0)^2 = 1 \). We then have the alternative decomposition into two irreducible \( \text{Cliff}(\mathbb{Z}) \)-modules,

\[
\text{CM}(\mathbb{Z}) = \text{CM}(\mathbb{Z})^+ \oplus \text{CM}(\mathbb{Z})^-
\]

where \( \text{CM}(\mathbb{Z})^\pm \) is the subspace with basis

\[
\{ e(-m_1) \ldots e(-m_r) \text{vac}_\pm | m_1 > \ldots > m_r > 0, \; m_1, \ldots, m_r \in \mathbb{Z} \}.
\]

Later we will need the vector space isomorphism

\[
\theta : \text{CM}(\mathbb{Z}) \rightarrow \text{CM}(\mathbb{Z})
\]

defined by

\[
\theta(\text{vac}') = e(0)\text{vac}' \quad \text{and} \quad \theta(e(m)v) = e(m)\theta(v)
\]

for any \( m \in \mathbb{Z} \) and \( v \in \text{CM}(\mathbb{Z}) \). It is clear that \( \theta \) is an involution switching \( \text{CM}(\mathbb{Z})^0 \) with \( \text{CM}(\mathbb{Z})^1 \), and that \( \text{CM}(\mathbb{Z})^+ \) and \( \text{CM}(\mathbb{Z})^- \) are the +1 and −1 eigenspaces, respectively, for \( \theta \).

Define the \( \text{Vir} \) operators

\[
L(k) = -\frac{1}{4} \sum_{n \in \mathbb{Z}} (n + \frac{1}{2}) \circ e(n)e(k-n) \quad \text{for } k \neq 0,
\]

\[
L(0) = \frac{1 + \iota}{32} - \frac{1}{4} \sum_{n \in \mathbb{Z}} (n + \frac{1}{2}) \circ e(n)e(-n)
\]

where \( \iota = 1 \) if \( Z = \mathbb{Z} \) and \( \iota = -1 \) if \( Z = \mathbb{Z} + \frac{1}{2} \).

**Theorem 1.** The operators \( L(k), \; k \in \mathbb{Z} \), and the identity operator, represent a \( c = \frac{1}{2} \) Virasoro algebra \( \text{Vir} \) on \( \text{CM}(\mathbb{Z}) \). In particular, for \( k, n \in \mathbb{Z}, \; m \in \mathbb{Z} \), we have

\[
[L(k), e(m)] = -(m + \frac{1}{2})k \; e(m+k),
\]

\[
[L(k), L(n)] = (k-n)L(k+n) + \frac{1}{32}(k^3 - k)\delta_{k,-n}1.
\]

The parity decomposition of \( \text{CM}(\mathbb{Z}) \) is a decomposition into two irreducible \( \text{Vir} \)-modules. The highest weight vectors in these modules are \( \text{vac}, \; e(-\frac{1}{2})\text{vac}, \; \text{vac}' \) and \( e(0)\text{vac}' \), whose weights are 0, \( \frac{1}{16} \), \( \frac{1}{16} \), and \( \frac{1}{16} \), respectively. The decomposition of \( \text{CM}(\mathbb{Z}) \) into two irreducible \( \text{Cliff}(\mathbb{Z}) \)-modules is also a decomposition into two irreducible \( \text{Vir} \)-modules. The highest weight vectors in these modules are \( \text{vac}'_+ \) and \( \text{vac}'_- \), whose weights are both \( \frac{1}{16} \). The operators \( L(k) \) commute with \( \theta \) on \( \text{CM}(\mathbb{Z}) \).

As usual we can define a positive Hermitian form \( \langle , \rangle \) on \( \text{CM}(\mathbb{Z}) \) such that \( e(m)^* = e(-m) \) and \( L(k)^* = L(-k) \), where * denotes adjoint. The eigenspaces of \( L(0) \) provide \( \text{CM}(\mathbb{Z}) \) with a grading. If \( u \) is an eigenvector for \( L(0) \) write \( \text{wt}(u) \) for the eigenvalue and write \( (\text{CM}(\mathbb{Z}))_n \) for the \( n \)-eigenspace. For \( u = e(-m_1) \ldots e(-m_r)\text{vac}(Z) \in \text{CM}(\mathbb{Z}) \) we have

\[
L(0)u = \left( m_1 + \ldots + m_r + \frac{1 + \iota}{32} \right) u.
\]
Let $W$ be any subspace of $CM(Z)$ which is a direct sum of $L(0)$ eigenspaces, $(W)_n$. The homogeneous character of $W$ is defined to be
\[
ch(W) = \sum_n \dim(W)_n q^n,
\]
a formal series in $q$. The homogeneous characters of the Clifford modules are then
\[
ch(CM(Z + \frac{1}{2})) = \prod_{0 \leq n \in \mathbb{Z}} (1 + q^{n + \frac{1}{2}})
\]
and
\[
ch(CM(\mathbb{Z})) = 2q^{1/16} \prod_{1 \leq n \in \mathbb{Z}} (1 + q^n).
\]

As in the spinor construction of $D_n^{(1)}$ we construct a vertex operator superalgebra on $CM(Z + \frac{1}{2})$ and a (twisted) representation on $CM(\mathbb{Z})$. This is done by defining a vertex operator $Y(v, \zeta)$ on $CM(Z + \frac{1}{2})$ and on $CM(\mathbb{Z})$ for any $v \in CM(Z + \frac{1}{2})$. Actually $Y(v, \zeta)$ is a generating function of operators
\[
Y(v, \zeta) = \sum_{n+1-wt(v) \in \frac{1}{2}\mathbb{Z}} Y_{n+1-wt(v)}(v)\zeta^{-n-1} = \sum_{n \in \frac{1}{2}\mathbb{Z}} \{v\}_n\zeta^{-n-1}
\]
where
\[
wt(Y_m(v)v) = wt(w) - m.
\]
The definition of $Y(v, \zeta)$ on $CM(\mathbb{Z})$ is more complicated than it is on $CM(Z + \frac{1}{2})$, but there is a common part which we denote by $\hat{Y}(v, \zeta)$.

Recall that $\text{vac} = \text{vac}(Z + \frac{1}{2})$ and $\text{vac}^c = \text{vac}(\mathbb{Z})$. On $CM(\mathbb{Z})$ define $\hat{Y}(\text{vac}, \zeta) = 1$ (the identity operator), and for $0 \leq n \in \mathbb{Z}$ let
\[
\hat{Y}(e(-n - \frac{1}{2})\text{vac}, \zeta) = n!^{-1}(d/d\zeta)^n \sum_{m \in \mathbb{Z}} e(m)\zeta^{-m-\frac{1}{2}}.
\]
Using the fermionic normal ordering $\xi e(n_1) \cdots e(n_r)\xi$ of a product of Clifford generators, for vectors of the form
\[
v = e(-n_1 - \frac{1}{2}) \cdots e(-n_r - \frac{1}{2})\text{vac} \in CM(Z + \frac{1}{2})
\]
we define
\[
\hat{Y}(v, \zeta) = \xi \hat{Y}(e(-n_1 - \frac{1}{2})\text{vac}, \zeta) \cdots \hat{Y}(e(-n_r - \frac{1}{2})\text{vac}, \zeta) \xi
\]
and extend the definition to all $v \in CM(Z + \frac{1}{2})$ by linearity. Then
\[
\hat{Y}_m(e(-\frac{1}{2})\text{vac}) = e(m)
\]
is a Clifford generator. Furthermore, with
\[
\omega = L(-2)\text{vac} = \frac{1}{4} e(-\frac{3}{2}) e(-\frac{1}{2})\text{vac},
\]
we have
\[
\hat{Y}(\omega, \zeta) = \begin{cases} \ L(\zeta) & \text{on } CM(Z + \frac{1}{2}) \\ \ L(\zeta) - \frac{1}{16} \zeta^{-2} & \text{on } CM(\mathbb{Z}) \end{cases}
\]
where $L(\zeta) = \sum_{k \in \mathbb{Z}} L(k)\zeta^{-k-2}$ is the generating function of the Virasoro operators.
In order to define the operators $Y(v, \zeta)$ we need the additional quadratic operator

$$\Delta(\zeta) = \frac{1}{2} \sum_{0 \leq m, n \in \mathbb{Z}} C_{mn} e(m + \frac{1}{2}) e(n + \frac{1}{2}) \zeta^{-m-n-1}$$

whose definition involves the combinatorial coefficients

$$C_{mn} = \frac{m-n}{m+n+1} \binom{-\frac{1}{2}}{m} \binom{-\frac{1}{2}}{n}.$$

For $v \in \text{CM}(\mathbb{Z} + \frac{1}{2})$ we define

$$Y(v, \zeta) = \begin{cases} \hat{Y}(v, \zeta) & \text{on } \text{CM}(\mathbb{Z} + \frac{1}{2}) \\ \hat{Y}(\exp(\Delta(\zeta))v, \zeta) & \text{on } \text{CM}(\mathbb{Z}) \end{cases}$$

Note that $\exp(\Delta(\zeta))v$ is a finite sum of vectors whose weights are between 0 and $\text{wt}(v)$. In particular,

$$\exp(\Delta(\zeta))\omega = \omega + \frac{1}{16} r^2 \text{vac},$$

so $Y(\omega, \zeta) = L(\zeta)$ on both $\text{CM}(\mathbb{Z} + \frac{1}{2})$ and $\text{CM}(\mathbb{Z})$.

**Theorem 2.** We have $(\text{CM}(\mathbb{Z} + \frac{1}{2}), Y(\ , \zeta), \text{vac}, \omega)$ is a vertex operator superalgebra and $(\text{CM}(\mathbb{Z}), Y(\ , z))$ is a (twisted) vertex operator superalgebra module.

**Corollary 3.** Let $v_i \in \text{CM}(\mathbb{Z} + \frac{1}{2})^{\alpha_i}$ for $i = 1, 2$. Then for any $r \in \mathbb{Z}$, for $m, n \in \mathbb{Z}$ on $\text{CM}(\mathbb{Z} + \frac{1}{2})$, and for $m \in \mathbb{Z} + \frac{1}{2} \alpha_1$, $n \in \mathbb{Z} + \frac{1}{2} \alpha_2$ on $\text{CM}(\mathbb{Z})$, we have

$$\sum_{0 \leq i \leq \mathbb{Z}} (-1)^{i} \binom{r}{i} \{v_1\}_{m+i} + (-1)^{\alpha_1 \alpha_2 + r} \{v_2\}_{n+i} \{v_1\}_{m+i}$$

$$= \sum_{0 \leq k \leq \mathbb{Z}} \binom{m}{k} \{v_1\}_{m+k} \{v_2\}_{n+k}.$$

The sum over $k$ is finite, and we may take $0 \leq k \leq \text{wt}(v_1) + \text{wt}(v_2) - r - 1$.

**Corollary 4.** For $v \in \text{CM}(\mathbb{Z} + \frac{1}{2})$, $m \in \mathbb{Z}$, on $\text{CM}(\mathbb{Z})$ we have

$$[L(m), Y(v, z)] = \sum_{0 \leq k \leq \mathbb{Z}} \binom{m+1}{k} z^{m+1-k} Y(L(k-1)v, z)$$

and the sum is finite. If $L(n)v = 0$ for all $n > 0$, then we have

$$[L(m), Y(v, z)] = z^{m+1} \frac{d}{dz} Y(v, z) + (m+1)z^m Y(L(0)v, z)$$

which means that

$$[L(m), Y_{n-m}(v)] = (-n + m \ \text{wt}(v)) Y_n(v).$$

**Corollary 5.** For $v \in \text{CM}(\mathbb{Z} + \frac{1}{2})$, $m \in \mathbb{Z}$, on $\text{CM}(\mathbb{Z})$ we have

$$Y(L(-m-1)v, z) = \sum_{0 \leq i \leq \mathbb{Z}} \binom{m+i-1}{i} z^i L(-m-i-1)Y(v, z) - (-1)^m z^{-m-i} Y(v, z)L(i-1).$$
Let

\[ V_0 = \text{CM}(Z + \frac{1}{2})^0, \quad V_2 = \text{CM}(Z + \frac{1}{2})^1, \]
\[ V_1 = \text{CM}(Z)^0, \quad V_3 = \text{CM}(Z)^1, \]
\[ V = V_0 \oplus V_1 \oplus V_2 \oplus V_3, \]

and extend the Hermitian form \((\cdot, \cdot)\) to \(V\) so that \(\text{CM}(Z + \frac{1}{2})\) and \(\text{CM}(Z)\) are orthogonal. We give the set of subscripts \(\{0, 1, 2, 3\}\) used to index these Vir-modules (sectors) the group structure of \(Z_4\). In the following table we give an orthonormal basis for the space \((V_i)_\Delta\) of vectors of minimal weight \(\Delta_i\) in sector \(V_i\). These are vacuum vectors for Vir.

| \(V_i\) | \(u_i\) | \(\Delta_i\) |
|--------|--------|---------|
| \(V_0\) | \(u_0 = \text{vac}\) | \(\Delta_0 = 0\) |
| \(V_1\) | \(u_1 = \text{vac}'\) | \(\Delta_1 = \frac{1}{16}\) |
| \(V_2\) | \(u_2 = \frac{1}{\sqrt{2}} e\left(-\frac{1}{2}\right) \text{vac}\) | \(\Delta_2 = \frac{1}{2}\) |
| \(V_3\) | \(u_3 = e(0) \text{vac}'\) | \(\Delta_3 = \frac{1}{16}\) |

For \(m, n \in Z_4\), define

\[ \Delta(m, n) = \Delta_m + \Delta_n - \Delta_{m+n}. \]

Then we have \(\Delta(0, n) = 0\) and

\[ \Delta(1, 1) = -\frac{3}{8}, \quad \Delta(1, 2) = \frac{1}{2}, \quad \Delta(1, 3) = \frac{1}{8}, \]
\[ \Delta(2, 2) = 1, \quad \Delta(2, 3) = \frac{1}{2}, \quad \Delta(3, 3) = -\frac{3}{8}. \]

For \(m, n, p \in Z_4\), define the totally symmetric function

\[ \Delta(m, n, p) = \Delta(m, n) + \Delta(m, p) - \Delta(m, n + p) \]
\[ = \Delta_m + \Delta_n + \Delta_p - \Delta_{m+n} - \Delta_{m+p} - \Delta_{n+p} + \Delta_{m+n+p}. \]

Then we have \(\Delta(0, n, p) = 0\) and

\[ \Delta(1, 1, 1) = -\frac{3}{8}, \quad \Delta(1, 1, 2) = 0, \quad \Delta(1, 1, 3) = -\frac{1}{4}, \]
\[ \Delta(1, 2, 2) = 1, \quad \Delta(1, 2, 3) = 1, \quad \Delta(1, 3, 3) = -\frac{1}{2}, \]
\[ \Delta(2, 2, 2) = 2, \quad \Delta(2, 2, 3) = 1, \quad \Delta(2, 3, 3) = 0, \quad \Delta(3, 3, 3) = -\frac{5}{4}. \]

### 3. Intertwining Operators

We wish to extend the definition of vertex operators so that \(Y(v_1, z)v_2\) is defined for all \(v_1, v_2 \in V\). The new operators we need to define, when \(v_1 \in V_1 \oplus V_3\) are called “intertwining operators”. If \(v_i \in V_n\), then our basic assumptions are that the components of \(Y(v_1, z)v_2\) are in \(V_{n_1+n_2}\), that

\[ [L(-1), Y(v_1, z)] = \frac{d}{dz} Y(v_1, z) \]

and that Corollaries 4 and 5 are valid for all \(v \in V\). Let us see to what extent these assumptions determine the intertwiners. Since the form \((\cdot, \cdot)\) on \(V\) is nondegenerate, \(Y(v_1, z)v_2\) is determined if the one-point function \((Y(v_1, z)v_2, v_3)\) is known for all
where we have used the one-point function is zero). For any \(0 < m \in \mathbb{Z}\) we have

\[
(Y(v_1, z)v_2, L(-m)v_3) = (L(m)Y(v_1, z)v_2, v_3)
\]

\[
= (Y(v_1, z)L(m)v_2, v_3) + ([L(m), Y(v_1, z)]v_2, v_3)
\]

\[
= (Y(v_1, z)L(m)v_2, v_3) + \sum_{0 \leq k \in \mathbb{Z}} (m + 1) m^{m+1-k}(Y(L(k-1)v_1, z)v_2, v_3)
\]

\[
= (Y(v_1, z)L(m)v_2, v_3) + z^{m+1} \frac{d}{dz} (Y(v_1, z)v_2, v_3) + (m + 1) m^{m} \lambda_1 (Y(v_1, z)v_2, v_3)
\]

\[
+ \sum_{1 < k \in \mathbb{Z}} 1 \leq k \in \mathbb{Z} m + 1 \left( \frac{m + 1}{k} \right) z^{m+1-k}(Y(L(k-1)v_1, z)v_2, v_3)
\]

where we have used

\[
Y(L(-1)v_1, z) = [L(-1), Y(v_1, z)] = \frac{d}{dz} Y(v_1, z)
\]

which comes from Corollary 5 with \(m = 0\), and our assumptions. This shows that \((Y(v_1, z)v_2, L(-m)v_3)\) is determined by the one-point functions \((Y(v_1', z)v_2', v_3)\) where \(wt(v_1') \leq wt(v_1)\) and \(wt(v_2') \leq wt(v_2)\). This reduces the problem to the case when \(v_3\) has minimal weight in its sector, that is, when \(v_3\) is a vacuum vector for \(\text{Vir}\).

Assuming that \(L(k)v_3 = 0\) for all \(0 < k \in \mathbb{Z}\), for \(0 \leq m \in \mathbb{Z}\) we have

\[
(Y(L(-m-1)v_1, z)v_2, v_3) = 
\]

\[
\sum_{0 \leq i \in \mathbb{Z}} (m + i - 1) \left[ z^i (L(-m - i - 1)Y(v_1, z)v_2, v_3) 
\right.
\]

\[
- (-1)^m z^{-m-i} (Y(v_1, z)L(i-1)v_2, v_3)
\]

\[
= \sum_{0 \leq i \in \mathbb{Z}} (m + i - 1) \left[ z^i (Y(v_1, z)v_2, L(m + i + 1)v_3) 
\right.
\]

\[
- (-1)^m z^{-m-i} (Y(v_1, z)L(i-1)v_2, v_3)]
\]

But since \(m \geq 0\) and \(i \geq 0\), \(L(m + i + 1)v_3 = 0\) by assumption, so the above equals

\[
- (-1)^m \sum_{1 < i \in \mathbb{Z}} (m + i - 1) z^{-m-i} (Y(v_1, z)L(i-1)v_2, v_3)
\]

\[
- (-1)^m z^{-m} (Y(v_1, z)L(-1)v_2, v_3) - (-1)^m z^{-m-1} \lambda_2 (Y(v_1, z)v_2, v_3)
\]

Now we use the fact that

\[
(Y(v_1, z)L(-1)v_2, v_3) = (L(-1)Y(v_1, z)v_2, v_3) - ([L(-1), Y(v_1, z)]v_2, v_3)
\]

\[
= (Y(v_1, z)v_2, L(1)v_3) - \frac{d}{dz} (Y(v_1, z)v_2, v_3)
\]

\[
= - \frac{d}{dz} (Y(v_1, z)v_2, v_3).
\]
So \( (Y(L(-m-1)v_1, z)v_2, v_3) \) for \( m \geq 0 \) and \( v_3 \) a vacuum vector is determined by the one-point functions \( (Y(v_1, z)v_2, v_3) \) for \( wt(v_2') \leq wt(v_2) \). Thus we are reduced to the case when \( v_1 \) and \( v_3 \) are vacuum vectors.

With that assumption, for \( 0 < m \in \mathbb{Z} \), we have

\[
(Y(v_1, z)L(-m)v_2, v_3) = (L(-m)Y(v_1, z)v_2, v_3) - ([L(-m), Y(v_1, z)]v_2, v_3)
\]

\[
(Y(v_1, z)v_2, L(m)v_3) = \sum_{0 \leq k \in \mathbb{Z}} \binom{-m+1}{k} z^{-m+1-k} (Y(L(-1)v_1, z)v_2, v_3)
\]

\[
= -z^{-m+1} (Y(L(-1)v_1, z)v_2, v_3) - (m+1)z^{-m} (Y(L(0)v_1, z)v_2, v_3)
\]

\[
= -z^{-m+1} \frac{d}{dz} (Y(v_1, z)v_2, v_3) + (m-1)z^{-m} \lambda_1 (Y(v_1, z)v_2, v_3)
\]

showing that \( (Y(v_1, z)L(-m)v_2, v_3) \) is determined by \( (Y(v_1, z)v_2, v_3) \). Thus, we have reduced the general one-point function to the special case when \( v_1, v_2 \) and \( v_3 \) are vacuum vectors. These complex numbers are called the structure constants, and we will see if they can be consistently determined by conditions we want for the two-point functions.

4. Two-Point Functions and Hypergeometric Differential Equations

For \( 1 \leq i \leq 4 \) let \( v_i \in V_n \), with \( wt(v_i) = |v_i| = N_i + \Delta_n \), for \( 0 \leq N_i \in \mathbb{Z} \) and suppose \( n_1 + n_2 + n_3 = n_4 \). Let

\[
G(v_1, v_2, v_3, v_4; z_1, z_2) = (Y(v_1, z_1)Y(v_2, z_2)v_3, v_4),
\]

\[
H(v_1, v_2, v_3, v_4; z, z_2) = (Y(v_1, z)v_2, v_3)Y(v_2, z_2)v_3, v_4).
\]

Then we have

\[
G(v_1, v_2, v_3, v_4; z_1, z_2) = \sum_{0 \leq k \in \mathbb{Z}} \binom{z_2}{z_1}^k \Phi_k(v_1, v_2, v_3, v_4)
\]

where

\[
\Phi_k = \Phi_k(v_1, v_2, v_3, v_4) = (Y_{k+\Delta_n_2+n_3-|v_4|}(v_1) \ Y_{k-\Delta_n_2+n_3+|v_3|}(v_2)v_3, v_4)
\]

and

\[
H(v_1, v_2, v_3, v_4; z, z_2) = \sum_{0 \leq k \in \mathbb{Z}} \binom{z}{z_2}^k \Psi_k(v_1, v_2, v_3, v_4)
\]

where

\[
\Psi_k = \Psi_k(v_1, v_2, v_3, v_4) = (Y_{|v_3|-|v_4|}(Y_{-k-\Delta_n_1+n_2+|v_2|}(v_1)v_2)v_3, v_4).
\]

**Definition 6.** For \( m, n, p \in \mathbb{Z}_+ \) let

\[
A_{mn} = (Y_{\Delta_n-\Delta_{m+n}}(u_m)u_n, u_{m+n}),
\]

\[
K_{mnp} = \Phi_0(u_m, u_n, u_p, u_{m+n+p}) = A_{np}A_{m,n+p},
\]

\[
M_{mnp} = \Psi_0(u_m, u_n, u_p, u_{m+n+p}) = A_{mn}A_{m+n,p}.
\]
LEMMA 7. Let \( v \in V_i \), \( 0 \leq i \leq 3 \), be of weight \( \Delta_i \). Then we have \( L(-1)^2v = \gamma L(-2)v \) where \( \gamma \) is given by the following table:

\[
\begin{array}{cccc}
  i & 0 & 1 & 2 & 3 \\
  \gamma & 0 & \frac{4}{7} & \frac{4}{3} & \frac{4}{7} \\
\end{array}
\]

THEOREM 8. For \( 1 \leq i \leq 4 \) let \( v_i \in V_{n_i} \) be vacuum vectors for \( \text{Vir} \). For \( i = 1, 2 \) let \( Y_i = Y(v_i, z_i) \), suppose that \( L(-1)^2v_3 = \gamma L(-2)v_3 \) and let

\[
G = G(v_1, v_2, v_3, v_4; z_1, z_2) = (Y_1Y_2v_3, v_4).
\]

Then \( G \) satisfies the partial differential equation

\[
(\partial_1 + \partial_2)^2G + \gamma(z_1^{-1}\partial_1 + z_2^{-1}\partial_2)G - \gamma(z_1^{-2}\Delta_{n_1} + z_2^{-2}\Delta_{n_2})G = 0.
\]

PROOF. We have

\[
(Y_1Y_2L(-1)^2v_3, v_4) = (Y_1L(-1)Y_2L(-1)v_3, v_4) - (Y_1[L(-1), Y_2]L(-1)v_3, v_4)
\]

\[
= (L(-1)Y_1Y_2L(-1)v_3, v_4) - ([L(-1), Y_1]Y_2L(-1)v_3, v_4)
\]

\[
= -(\partial_1 + \partial_2)(Y_1Y_2L(-1)v_3, v_4)
\]

\[
= (\partial_1 + \partial_2)^2(Y_1Y_2v_3, v_4)
\]

and

\[
(Y_1Y_2L(-2)v_3, v_4) = (Y_1L(-2)Y_2v_3, v_4) - (Y_1[L(-2), Y_2]v_3, v_4)
\]

\[
= -([L(-2), Y_1]Y_2v_3, v_4) - (Y_1[L(-2), Y_2]v_3, v_4)
\]

\[
= -(z_1^{-1}\partial_1 - z_1^{-2}\Delta_{n_1})(Y_1Y_2v_3, v_4)
\]

\[
- (z_2^{-1}\partial_2 - z_2^{-2}\Delta_{n_2})(Y_1Y_2v_3, v_4)
\]

so the relation

\[
(Y_1Y_2L(-1)^2v_3, v_4) = \gamma(Y_1Y_2L(-2)v_3, v_4)
\]

gives the result. \( \blacksquare \)

Let \( v_i = u_n \), for \( 1 \leq i \leq 4 \), and suppose \( n_4 = n_1 + n_2 + n_3 \). If we write

\[
G_{n_1n_2n_3}(z_1, z_2) = K_{n_1n_2n_3}z_1^{-A}z_2^{-B}\left(1 - \frac{z_2}{z_1}\right)^{-C}F(z_2/z_1)
\]

for

\[
A = \Delta(n_1, n_2 + n_3), \quad B = \Delta(n_2, n_3), \quad C = \Delta(n_1, n_2)
\]

then the differential equation for \( G \) becomes a differential equation for \( F \). Letting \( x = z_2/z_1 \) and using the fact that

\[
\Delta(n, n_3)(\Delta(n, n_3) + 1) = \gamma(\Delta(n, n_3) + \Delta_n)
\]

for any \( n = 0, 1, 2, 3 \), we get the ordinary differential equation

\[
x(1-x)F'' + [(\gamma - 2B) + (2A + 2 - 2C - \gamma)x]F' + [2AB - 2BC + \gamma C]F = 0
\]
for $F$. The hypergeometric function

$$2F_1(a, b, c; z) = \sum_{n=0}^{\infty} \frac{(a)_n (b)_n}{n! (c)_n} z^n$$

where $(a)_n = a(a+1) \ldots (a+n-1)$, is a solution to the hypergeometric differential equation

$$x(1-x)w'' + (c - (a + b + 1)x)w' - abw = 0.$$ 

Therefore, we find that

$$G_{n_1n_2n_3}(z_1, z_2) = K_{n_1n_2n_3} z_1^{-A} z_2^{-B} \left( 1 - \frac{z_2}{z_1} \right)^{-C} 2F_1(a, b, c; z_2/z_1)$$

where

$$c = \gamma - 2B, \quad ab = (2B - \gamma)C - 2AB, \quad a + b = 2A - 2C - \gamma + 1.$$ 

In fact, we find that $a = -\Delta(n_1, n_2, n_3)$.

**Theorem 9.** For $1 \leq i \leq 4$ let $v_i \in V_{n_i}$ be vacuum vectors for $\text{Vir}$. Suppose that $L(-1)^2v_3 = \gamma L(-2)v_3$ and let

$$H = H(v_1, v_2, v_3, v_4; z, z_2) = (Y(Y(v_1, z)v_2, z_2)v_3, v_4).$$

Then $H$ satisfies the partial differential equation

$$\partial^2 H + \gamma(z_2^{-1}\partial_z - (z_2 + z)^{-1}z_2^{-1}z\partial_z)H - \gamma((z_2 + z)^{-2}\Delta_n + z_2^{-2}\Delta_n)H = 0.$$ 

Let $v_i = u_n$, for $1 \leq i \leq 4$, and suppose $n_4 = n_1 + n_2 + n_3$. If we write

$$H_{n_1n_2n_3}(z, z_2) = M_{n_1n_2n_3} z_2^{-A'} z^{-B'} \left( 1 - \frac{z}{z_2} \right)^{-C'} F(z/z_2)$$

for

$$A' = \Delta(n_1 + n_2, n_3), \quad B' = \Delta(n_1, n_2), \quad C' = \Delta(n_1, n_3)$$

then the differential equation for $H$ becomes a differential equation for $F$. Letting $x = z/z_2$ and using the facts that

$$\Delta(n, n_3)(\Delta(n_1, n_3) + 1) = \gamma(\Delta(n, n_3) + \Delta_n)$$

for any $n = 0, 1, 2, 3$, and

$$(A' - C')(A' + C' + 1 - \gamma) = \gamma(\Delta_n - B')$$

we get the ordinary differential equation

$$x(1+x)F'' + [(2A' + 2 - 2\gamma) + (2A' + 2 - 2C' - \gamma)x]F' - [2(A' - C')C' + \gamma B']F = 0$$

for $F$. Therefore, we find that

$$H_{n_1n_2n_3}(z, z_2) = M_{n_1n_2n_3} z_2^{-A'} z^{-B'} \left( 1 - \frac{z}{z_2} \right)^{-C'} 2F_1(a', b', c'; -z/z_2)$$

where

$$c' = 2(A' + 1 - \gamma), \quad a'b' = 2(C' - A')C' - \gamma B', \quad a' + b' = 2A' - 2C' - \gamma + 1.$$ 

In fact, we find that $a' = a = -\Delta(n_1, n_2, n_3)$. 

5. Transformation Formulas and Rationalization

The following Lemmas are well-known results in the theory of hypergeometric functions. The formula in Lemma 10 can easily be obtained from formula (2) on page 92 of [L], and the formulas in Lemma 11 are the formulas numbered (1.4.5) and (1.4.13) on page 14 of [S].

**Lemma 10.** (Kummer’s Quadratic Transformation Formula) For $|4z| < |1−z|^2$ we have

$$2F_1(a,b,1+a-b;z) = (1-z)^{-a} 2F_1\left(\frac{1}{2}a,\frac{1}{2}+\frac{1}{2}a-b,1+a-b; -4z/(1-z)^2\right).$$

**Lemma 11.** (Gauss Recurrence Relations for Contiguous Functions) For $a$ and $b$ nonzero, we have

$$(c−a−1) \ 2F_1(a,b,c;z) + a \ 2F_1(a+1,b,c;z) = (c−1) \ 2F_1(a,b,c−1;z),$$

$$(c−a) \ 2F_1(a,b,c;z) + (c−a)z \ 2F_1(a,b,c+1;z) = c \ 2F_1(a,b−1,c;z).$$

**Corollary 12.** For $|4z| < |1−z|^2$ we have

$$2F_1\left(\frac{1}{2},\frac{3}{4},\frac{3}{4};-4z/(1-z)^2\right) = (1-z)^{\frac{1}{2}},$$

$$2F_1\left(-\frac{1}{4},\frac{1}{4},\frac{1}{2};-4z/(1-z)^2\right) = (1-z)^{-\frac{1}{2}},$$

$$2F_1\left(\frac{5}{4},\frac{3}{4},\frac{3}{4};-4z/(1-z)^2\right) = \frac{(1-z)^{\frac{3}{2}}}{1+z},$$

$$2F_1\left(\frac{1}{4},\frac{3}{4},\frac{1}{2};-4z/(1-z)^2\right) = \frac{(1-z)^{\frac{1}{2}}}{1+z}.$$

**Proof.** The first two equations follow from Kummer’s quadratic transformation formula by taking $a = \frac{1}{2}$ or $a = -\frac{1}{2}, b = 0$. The last two equations follow from the Gauss recurrence relations by taking $a = \frac{1}{4}, b = \frac{3}{4}, c = \frac{3}{2}$ or $c = \frac{1}{2}$.

We wish to rationalize the correlation functions so that we can apply the usual contour integration techniques to obtain algebraic relations for the vertex operators. To do this we will use substitutions which give four sheeted coverings of the $t$-plane, where $t = z_2/z_1$. The functions $G$ and $H$ have possible poles at $t = 0$, $t = 1$ and $t = \infty$, as well as various cuts, but the four sheeted coverings are branched at these points, and each of these three points has only two points lying above it. First, in $G_{n_1n_2n_3}(z_1, z_2)$, we use the substitution

$$t^{1/2} = \left(\frac{z_2}{z_1}\right)^{\frac{1}{2}} = \frac{2x_0}{1+x_0^2} = \frac{2x_{\infty}}{1+x_{\infty}^2}.$$

In $G_{n_2n_1n_3}(z_2, z_1)$ we use the substitution

$$t^{-1/2} = \left(\frac{z_1}{z_2}\right)^{\frac{1}{2}} = \frac{2x_1}{1+x_1^2} = \frac{2x_{-1}}{1+x_{-1}^2}.$$
In $H_{n_1n_2n_3}(z, z_2)$ we use the substitution

$$(t^{-1} - 1)^{1/2} = \left(\frac{z_1 - z_2}{z_2}\right)^{1/2} = \frac{2x_1}{1 - x_1^2} = \frac{2x_{-1}}{1 - x_{-1}^2}.$$ 

In this notation, for $\alpha \in \{0, \infty, 1, -1, -i, i\}$, the variable $x_\alpha$ is local at the point $\alpha$ on the four-sheeted cover. These points are all related to each other by linear fractional transformations, and we let $x$ be a global variable on the genus zero covering. Below we will discuss the regions of absolute convergence after the substitutions have been made. Let

$$R_x = \mathbb{C}[x, x^{-1}(x^4 - 1)^{-1}]$$

be the ring of rational functions in $x$ with possible poles at those six points. Note that if $f(x) \in R_x$ and $\mu(x)$ is any of the linear fractional transformations $I(x) = x$, $A(x) = \frac{1}{x}$, $B(x) = \frac{x + i}{1x + 1}$, $C(x) = \frac{ix + 1}{x + 1}$, $D(x) = \frac{x - 1}{x + 1}$ or $E(x) = \frac{1 + x}{1 - x}$, then $f(\mu(x)) \in R_x$. Also note that $R_x$ is preserved by the operator $d/dx$.

Note that

$$1 - \frac{z_2}{z_1} = 1 - t = \frac{(1 - x_0^2)^2}{(1 + x_0^2)^2} = \frac{(1 - x_{-i}^2)^4}{(1 + x_{-i}^2)^2}$$

and

$$1 + \frac{z}{z_2} = t^{-1} = \frac{(1 + x_0^2)^2}{(1 - x_0^2)^2} = \frac{(1 + x_{-i}^2)^4}{(1 - x_{-i}^2)^2}.$$ 

The $S_3$ permutation group acting on the three points $t = 0, 1, \infty$, lifts to an $S_4$ permutation group acting on the six points $0, \infty, i, -i, 1, -1$. For $a \in \{1, -1, i, -i\}$ let $F_a(x) = ax$. The group of 24 linear fractional transformations giving these permutations is generated by $B(x)$ and $D(x)$, each of which has order 4. It consists of the compositions of the four functions $F_a$, with the six functions $I, A, B, C, D$ and $E$. One has the relations $BDB^{-1} = F_1$, $DBD^{-1} = F_{-1}$, $F_{-1}DF_{-1} = D^{-1}$ and $F_1DF_1 = B$. It is easy to check that the correspondence $B \leftrightarrow (1, 2, 3, 4)$, $D \leftrightarrow (1, 3, 2, 4)$ and $F_i \leftrightarrow (1, 2, 4, 3)$ determines an isomorphism between this group of 24 transformations and the permutation group $S_4$. In this paper we will not use all 24 transformations, but we will just choose enough to relate local variables at each of the six points. However, we believe that it will be necessary to use all 24 transformations in order to fully understand the algebraic structure of the $2 \times 2$ $B$ matrices defined just before Theorem 15. That will be a subject for future investigation.

We can choose local variables $x_\alpha$ such that

$$x_\infty = \frac{1}{x_0}, \quad x_1 = \frac{1}{x_{-i}}, \quad x_1 = \frac{-1}{x_{-1}}.$$  

The relations between $x_0$ and $x_\alpha$ are determined, up to some sign choices, by their relationship to $t$. We make the choices

$$x_0 = \frac{x_1 + i}{ix_1 + 1} \quad \text{so} \quad x_0 = \frac{-x_{-i} + i}{ix_{-i} - 1}, \quad x_0 = \frac{x_1 + 1}{-x_1 + 1} \quad \text{so} \quad x_0 = \frac{x_{-1} - 1}{x_{-1} + 1},$$

so that

$$x_1 = \frac{-x_0 + i}{ix_0 - 1} \quad \text{and} \quad x_1 = \frac{x_0 - 1}{x_0 + 1}.$$  

Until further notice we assume that $n_1, n_2, n_3 \in \{1, 3\}$. 
Theorem 13. For $\alpha = 0$ or $\alpha = \infty$, after the substitution $(z_2/z_1)^{1/2} = 2x_\alpha/(1 + x_\alpha^2)$, the series $\sum_{n=1}^{\infty} G_{n_1n_2n_3}(z_1, z_2)$ converges absolutely to a function of $x_\alpha$ in the domain $|x_\alpha| < \sqrt{3 - 2\sqrt{2}}$ and in that domain we have

$$(1 - x_\alpha^4)^{\frac{1}{2}} z_\alpha^2 G_{n_1n_2n_3}(z_1, z_2) = \begin{cases} 2x_\alpha K_{n_1n_2n_3} & \text{if } n_2 = n_3 \\ K_{n_1n_2n_3} & \text{if } n_2 \neq n_3 \end{cases}$$

For $\alpha = i$ or $\alpha = -i$, the above assertions with $z_1$ and $z_2$ switched and with $n_1$ and $n_2$ switched, are true.

Proof. In the expression for $G_{n_1n_2n_3}(z_1, z_2)$ obtained after Theorem 8 we see it as a series in $t = z_2/z_1$ which converges absolutely for $|t| < 1$. But in order to use Corollary 12 with $z = -x_\alpha^2$ we need $\sqrt{\frac{2x_\alpha^2}{1 + x_\alpha^2}} < 1$. Using polar coordinates $x_\alpha = re^{i\theta}$ this condition is equivalent to $4r^2 < 1 - 2r^2 \cos(2\theta) + r^4$. This is certainly true when $4r^2 < 1 - 2r^2 + r^4$, that is, when $0 < r^4 - 6r^2 + 1$. The parabola $y = x^2 - 6x + 1$ is positive for $x < 3 - 2\sqrt{2}$ so with $0 < r < \sqrt{3 - 2\sqrt{2}}$ we are guaranteed to have the desired condition.

Using the values of $A, B, C, a, b, c$ in the tables, and Corollary 12, after some algebra one gets the explicit formula stated in the theorem.

Theorem 14. For $\alpha = 1$ or $\alpha = -1$, after the substitution $(z/z_1)^{1/2} = 2x_\alpha/(1 + x_\alpha^2)$, the series $\sum_{n=1}^{\infty} H_{n_1n_2n_3}(z, z_2)$ converges absolutely to a function of $x_\alpha$ in the domain $|x_\alpha| < \sqrt{3 - 2\sqrt{2}}$ and in that domain we have

$$(1 - x_\alpha^4)^{\frac{1}{2}} z_\alpha^2 H_{n_1n_2n_3}(z, z_2) = \begin{cases} 2x_\alpha M_{n_1n_2n_3} & \text{if } n_1 = n_2 \\ M_{n_1n_2n_3} & \text{if } n_1 \neq n_2 \end{cases}$$

Proof. In the expression for $H_{n_1n_2n_3}(z, z_2)$ obtained after Theorem 9 we see it as a series in $t^{-1} - 1 = z/z_2$ which converges absolutely for $|z/z_2| < 1$. But in order to use Corollary 12 with $z = -x_\alpha^2$ we need $\sqrt{\frac{2x_\alpha^2}{1 + x_\alpha^2}} < 1$. Using polar coordinates $x_\alpha = re^{i\theta}$ this condition is equivalent to $4r^2 < 1 - 2r^2 \cos(2\theta) + r^4$. This is certainly true when $4r^2 < 1 - 2r^2 + r^4$. So the analysis proceeds just as in Theorem 13.

Using the values of $A', B', C', a', b', c'$ in the tables, and Corollary 12, after some algebra one gets the explicit formula stated in the theorem.

In order to get the most general form of the Jacobi identity, we will eventually apply the Cauchy residue theorem to matrix valued differential forms on the four sheeted covering. Let

$$[G(z_1, z_2)] = \begin{bmatrix} G_{111}(z_1, z_2) & G_{311}(z_1, z_2) & G_{333}(z_1, z_2) & G_{133}(z_1, z_2) \\ G_{331}(z_1, z_2) & G_{131}(z_1, z_2) & G_{113}(z_1, z_2) & G_{313}(z_1, z_2) \end{bmatrix},$$

$$[G(z_2, z_1)] = \begin{bmatrix} G_{111}(z_2, z_1) & G_{311}(z_2, z_1) & G_{333}(z_2, z_1) & G_{133}(z_2, z_1) \\ G_{331}(z_2, z_1) & G_{131}(z_2, z_1) & G_{113}(z_2, z_1) & G_{313}(z_2, z_1) \end{bmatrix},$$

and

$$[H(z, z_2)] = \begin{bmatrix} H_{111}(z, z_2) & H_{311}(z, z_2) & H_{131}(z, z_2) & H_{331}(z, z_2) \\ H_{311}(z, z_2) & H_{131}(z, z_2) & H_{313}(z, z_2) & H_{133}(z, z_2) \end{bmatrix}. $$
Note that in the matrix \( G(z_1, z_2) = [G_{n_1n_2n_3}(z_1, z_2)] \) the first row has \( n_2 = n_3 \), the second row has \( n_2 \neq n_3 \), while each column has the same \( n_3 \) but different values of \( n_1 \). The \( [G(z_2, z_1)] \) matrix has the same pattern of subscripts as the \( [G(z_1, z_2)] \) matrix, but the variables \( z_1 \) and \( z_2 \) are switched. In the matrix \( [H(z, z_2)] \) the first row has \( n_1 = n_2 \), the second row has \( n_1 \neq n_2 \), while each column has the same \( n_2 \) and the same \( n_3 \). Then, for \( \alpha = 0 \) or \( \alpha = \infty \), we have

\[
(1 - x_\alpha^4)^{1/2} \frac{1}{x_2^2} [G(z_1, z_2)]_\alpha = \begin{bmatrix}
2K_{111}x_\alpha & 2K_{311}x_\alpha & 2K_{333}x_\alpha & 2K_{133}x_\alpha \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix},
\]

for \( \alpha = i \) or \( \alpha = -i \), we have

\[
(1 - x_\alpha^4)^{1/2} \frac{1}{x_1^2} [G(z_2, z_1)]_\alpha = \begin{bmatrix}
2K_{111}x_\alpha & 2K_{311}x_\alpha & 2K_{333}x_\alpha & 2K_{133}x_\alpha \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix},
\]

and for \( \alpha = 1 \) or \( \alpha = -1 \), we have

\[
(1 - x_\alpha^4)^{1/2} \frac{1}{x_\alpha^2} [H(z, z_2)]_\alpha = \begin{bmatrix}
2M_{111}x_\alpha & 2M_{331}x_\alpha & 2M_{133}x_\alpha & 2M_{333}x_\alpha \\
M_{331} & M_{131} & M_{113} & M_{313}
\end{bmatrix}.
\]

These equalities mean that the left sides are series which, after an appropriate substitution, converge absolutely in a small disk around the appropriate \( x_\alpha \) to the globally defined matrix valued functions given on the right sides.

For any \( f(x) \in \mathcal{R}_x \) we can use linear fractional transformations to express the globally defined matrix valued differential form

\[
\left[\begin{array}{cccc}
2K_{111}x & 2K_{311}x & 2K_{333}x & 2K_{133}x \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{array}\right] f(x) dx
\]

in terms of the appropriate local coordinate variable \( x_\alpha \) at each of the six possible poles. The residue at each pole is then easily found. By the residue theorem, the sum of all the residues is zero, giving us a relation among the correlation functions. That relation is the generalization of the Jacobi Identity which we seek. The residue at \( x = 0 \) can be found immediately from the global expression. To find the residue at \( x = \infty \), use \( x_\infty = x_0^{-3} \) and find the residue at \( x_\infty = 0 \). Leaving off the function \( f(x) \) and the differential \( dx \) for the moment, we have

\[
\frac{1}{x_\infty} \left[\begin{array}{cccc}
2K_{111}x_\infty & 2K_{311}x_\infty & 2K_{333}x_\infty & 2K_{133}x_\infty \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{array}\right] = \begin{bmatrix}
\frac{1}{2K_{111}} & 0 & \frac{2K_{111}}{K_{331}} \\
0 & \frac{2K_{331}}{K_{333}} & 0
\end{bmatrix}
\]

if and only if the following conditions are consistent:

\[
K_{111}K_{131} = K_{331}K_{311}, \quad K_{111}K_{113} = K_{331}K_{333}, \quad K_{111}K_{313} = K_{331}K_{133}.
\]
To find the residue at \( x = i \) use \( x_0 = (x_1 + i)/(ix_1 + 1) \) and find the residue at \( x_1 = 0 \). Without imposing any further conditions, we have

\[
\begin{bmatrix}
2K_{111}x_0 & 2K_{311}x_0 & 2K_{333}x_0 & 2K_{133}x_0 \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix}
= \begin{bmatrix}
2K_{111}x_1 + i & 2K_{311}x_1 + i & 2K_{333}x_1 + i & 2K_{133}x_1 + i \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix}
\]

\[
= \frac{1}{ix_1 + 1} \begin{bmatrix}
2K_{111}(x_1 + i) & 2K_{311}(x_1 + i) & 2K_{333}(x_1 + i) & 2K_{133}(x_1 + i) \\
K_{331}(ix_1 + 1) & K_{131}(ix_1 + 1) & K_{113}(ix_1 + 1) & K_{313}(ix_1 + 1)
\end{bmatrix}
\]

\[
= \frac{1}{ix_1 + 1} \begin{bmatrix}
1 & 2iK_{111} & 2iK_{311} & 1 \\
1 & K_{331} & K_{131} & K_{113}
\end{bmatrix}
\begin{bmatrix}
2K_{111}x_1 & 2K_{311}x_1 & 2K_{333}x_1 & 2K_{133}x_1 \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix}
\]

\[
= (1 - x_1^2) \frac{1}{i} x_1 \frac{1}{ix_1 + 1} \begin{bmatrix}
1 & 2iK_{111} & 2iK_{311} & 1 \\
1 & K_{331} & K_{131} & K_{113}
\end{bmatrix}
\begin{bmatrix}
G(z_2, z_1)\end{bmatrix}.
\]

To find the residue at \( x = -i \) use \( x_0 = (-x_{-1} + i)/(ix_{-1} - 1) \) and find the residue at \( x_{-1} = 0 \). Without imposing any new conditions, we have

\[
\begin{bmatrix}
2K_{111}x_0 & 2K_{311}x_0 & 2K_{333}x_0 & 2K_{133}x_0 \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix}
= \begin{bmatrix}
2K_{111}(x_{-1} - i) & 2K_{311}(x_{-1} - i) & 2K_{333}(x_{-1} - i) & 2K_{133}(x_{-1} - i) \\
K_{331}(ix_{-1} - 1) & K_{131}(ix_{-1} - 1) & K_{113}(ix_{-1} - 1) & K_{313}(ix_{-1} - 1)
\end{bmatrix}
\]

\[
= \frac{1}{ix_{-1} - 1} \begin{bmatrix}
-1 & 2iK_{111} & 2iK_{311} & -1 \\
1 & K_{331} & K_{131} & K_{113}
\end{bmatrix}
\begin{bmatrix}
2K_{111}x_{-1} & 2K_{311}x_{-1} & 2K_{333}x_{-1} & 2K_{133}x_{-1} \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix}
\]

\[
= (1 - x_{-1}^2) \frac{1}{i} x_{-1} \frac{1}{ix_{-1} - 1} \begin{bmatrix}
-1 & 2iK_{111} & 2iK_{311} & -1 \\
1 & K_{331} & K_{131} & K_{113}
\end{bmatrix}
\begin{bmatrix}
G(z_2, z_1)\end{bmatrix}.
\]

To find the residue at \( x = -1 \) use \( x_0 = (x_{-1} - 1)/(x_{-1} + 1) \) and find the residue at \( x_{-1} = 0 \). Assuming the previous consistency conditions are true, we have

\[
\begin{bmatrix}
2K_{111}x_0 & 2K_{311}x_0 & 2K_{333}x_0 & 2K_{133}x_0 \\
K_{331} & K_{131} & K_{113} & K_{313}
\end{bmatrix}
= \begin{bmatrix}
2K_{111}(x_{-1} - 1) & 2K_{311}(x_{-1} - 1) & 2K_{333}(x_{-1} - 1) & 2K_{133}(x_{-1} - 1) \\
K_{331}(x_{-1} + 1) & K_{131}(x_{-1} + 1) & K_{113}(x_{-1} + 1) & K_{313}(x_{-1} + 1)
\end{bmatrix}
\]

\[
= \frac{1}{x_{-1} + 1} \begin{bmatrix}
2K_{111} & 2K_{311} & 2K_{333} & 2K_{133} \\
M_{331} & M_{131} & M_{113} & M_{313}
\end{bmatrix}
\begin{bmatrix}
M_{111} & M_{131} & M_{331} & M_{313}
\end{bmatrix}
\]

\[
= (1 - x_{-1}^2) \frac{1}{x_{-1} + 1} \begin{bmatrix}
2K_{111} & 2K_{311} & 2K_{333} & 2K_{133} \\
M_{331} & M_{131} & M_{113} & M_{313}
\end{bmatrix}
\begin{bmatrix}
H(z, z_2)\end{bmatrix}.
\]

if and only if the following conditions hold:

\[
\frac{K_{111}}{K_{133}} = \frac{M_{111}}{M_{333}} = \frac{M_{311}}{M_{133}}, \quad \frac{K_{111}}{M_{311}} = \frac{M_{111}}{M_{133}}, \quad \frac{K_{111}}{K_{333}} = \frac{M_{111}}{M_{133}} = \frac{M_{111}}{M_{313}}.
\]
To find the residue at $x = 1$ use $x_0 = (x_1 + 1)/(-x_1 + 1)$ and find the residue at $x_1 = 0$. Without imposing any new conditions, we have

\[
\begin{bmatrix}
2K_{111}x_0 & 2K_{311}x_0 & 2K_{333}x_0 & 2K_{133}x_0 \\
K_{331} & K_{311} & K_{113} & K_{313}
\end{bmatrix} = \frac{1}{-x_1 + 1} \begin{bmatrix}
2K_{111}(x_1 + 1) & 2K_{311}(x_1 + 1) & 2K_{333}(x_1 + 1) & 2K_{133}(x_1 + 1) \\
K_{331}(-x_1 + 1) & K_{311}(-x_1 + 1) & K_{113}(-x_1 + 1) & K_{313}(-x_1 + 1)
\end{bmatrix}
\]

\[
= \frac{1}{-x_1 + 1} \begin{bmatrix}
\frac{K_{111}}{M_{111}} & \frac{2K_{111}}{M_{111}} & \frac{2K_{111}}{M_{111}} & \frac{2K_{111}}{M_{111}} \\
\frac{2K_{111}}{M_{111}} & \frac{K_{311}}{M_{311}} & \frac{K_{311}}{M_{311}} & \frac{K_{311}}{M_{311}}
\end{bmatrix} \begin{bmatrix}
2M_{111}x_1 & 2M_{311}x_1 & 2M_{311}x_1 & 2M_{333}x_1 \\
M_{311} & M_{311} & M_{311} & M_{311}
\end{bmatrix}
\]

\[
= (1 - x_1^4) \frac{1}{x_1^2} \begin{bmatrix}
\frac{K_{111}}{M_{111}} & \frac{2K_{111}}{M_{111}} & \frac{2K_{111}}{M_{111}} & \frac{2K_{111}}{M_{111}} \\
\frac{2K_{111}}{M_{111}} & \frac{K_{311}}{M_{311}} & \frac{K_{311}}{M_{311}} & \frac{K_{311}}{M_{311}}
\end{bmatrix} \begin{bmatrix}
H(z, z_2)\end{bmatrix}.
\]

Using Definition 6, the consistency conditions we have found translate into the following conditions on the structure constants $A_{mn}$:

\[
\frac{A_{30}}{A_{10}} = \frac{A_{12}}{A_{32}} = \frac{A_{11}}{A_{33}} = \frac{A_{31}}{A_{13}}, \quad A_{30}A_{31} = 1, \quad A_{21} = A_{23}, \quad A_{01} = A_{03}.
\]

In fact, we know quite a bit more about the structure constants $A_{mn}$. Since $Y(u_0, z) = Y(\text{vac}, z) = 1$, we have $A_{0n} = 1$ for any $n$. We also want

\[
Y(v, z)\text{vac} = e^{zL(-1)}v \in \mathcal{V}[z]
\]

which implies the “creation property”

\[
\lim_{z \to 0} Y(v, z)\text{vac} = Y_{-\text{wt}(v)}(v)\text{vac} = v.
\]

These give $A_{m0} = 1$ for any $m$. We also have

\[
A_{21} = (Y_0(u_2)u_1, u_3) = \frac{1}{\sqrt{2}}(e(0)\text{vac}', e(0)\text{vac}') = \frac{1}{\sqrt{2}},
\]

\[
A_{22} = (Y_{1/2}(u_2)u_2, u_3) = \frac{1}{2}(e(e)\text{vac}, \text{vac}) = \frac{1}{2}(e, e)(\text{vac}, \text{vac}) = 1,
\]

\[
A_{23} = (Y_0(u_2)u_3, u_1) = \frac{1}{\sqrt{2}}(e(0)e(0)\text{vac}', \text{vac}') = \frac{1}{\sqrt{2}}.
\]

We also want the “symmetry” condition, generalizing what is called “skew-symmetry” in [FHL],

\[
z^\Delta(n_1, n_2)Y(v_1, z)v_2 = (-z)^\Delta(n_1, n_2)ez^{zL(-1)}Y(v_2, -z)v_1
\]

for $v_i \in \mathcal{V}_{n_i}$. With $v_1 = u_m$ and $v_2 = u_n$, after pairing with $u_{m+n}$, this gives $A_{mn} = A_{nm}$. Along with the above constraints, this determines all the structure constants $A_{mn}$ except $A_{11}$, which we normalize to $1/\sqrt{2}$, and $A_{13}$, which we normalize to 1. Here is a table summarizing the results.

| $A_{mn}$ | $n = 0$ | $n = 1$ | $n = 2$ | $n = 3$ |
|----------|---------|---------|---------|---------|
| $m = 0$  | 1       | 1       | 1       | 1       |
| $m = 1$  | 1       | $\frac{1}{\sqrt{2}}$ | $\frac{1}{\sqrt{2}}$ | 1       |
| $m = 2$  | 1       | $\frac{1}{\sqrt{2}}$ | 1       | $\frac{1}{\sqrt{2}}$ |
| $m = 3$  | 1       | 1       | $\frac{1}{\sqrt{2}}$ | $\frac{1}{\sqrt{2}}$ |
DEFINITION. Define the matrices

\[ B_0 = \begin{bmatrix} 1 & 0 \\ 0 & 1 \end{bmatrix}, \quad B_\infty = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}, \quad B_i = \begin{bmatrix} 1 & i \\ i & 1 \end{bmatrix}, \]

\[ B_{-i} = \begin{bmatrix} -1 & i \\ i & -1 \end{bmatrix}, \quad B_{-1} = \begin{bmatrix} 1 & -1 \\ 1 & 1 \end{bmatrix}, \quad B_1 = \begin{bmatrix} 1 & 1 \\ -1 & 1 \end{bmatrix}. \]

THEOREM 15. With \( A_{mn} \) as given in the above table, and with notations as defined above, we have

\[
(1 - x_0^4)^{\frac{1}{4} z_2^{\frac{1}{2}}} (G(z_1, z_2))_0 \\
\sim (1 - x_\infty^4)^{\frac{1}{4} z_1^{\frac{1}{2}}} x_\infty^{-1} B_\infty (G(z_1, z_2))_\infty \\
\sim (1 - x_i^4)^{\frac{1}{4} z_i^{\frac{1}{2}}} (ix_i + 1)^{-1} B_i (G(z_2, z_1))_i \\
\sim (1 - x_{-i}^4)^{\frac{1}{4} z_{-i}^{\frac{1}{2}}} (ix_{-i} - 1)^{-1} B_{-i} (G(z_2, z_1))_{-i} \\
\sim (1 - x_{-1}^4)^{\frac{1}{4} z_{-1}^{\frac{1}{2}}} (x_{-1} + 1)^{-1} B_{-1} [H(z, z_2)]_{-1} \\
\sim (1 - x_1^4)^{\frac{1}{4} z_1^{\frac{1}{2}}} (-x_1 + 1)^{-1} B_1 [H(z, z_2)]_1
\]

where \( \sim \) means that these series converge absolutely in their appropriate domains to the same globally defined matrix valued function

\[
\begin{bmatrix} x_0 & x_0 & x_0 & x_0 \\ 1 & 1 & 1 & 1 \end{bmatrix}
\]
on the four sheeted covering.

Note that if we associate to a matrix \( M = \begin{bmatrix} a & b \\ c & d \end{bmatrix} \) a linear fractional transformation \( f(x) = \frac{ax + b}{cx + d} \) then we associate to the matrix \( B_\alpha \) the linear fractional transformation

\[ f_\alpha(x_\alpha) = x_0 = \frac{ax_\alpha + b}{cx_\alpha + d}. \]

6. Inductive formulas

Now let us see how the general two-point functions are determined inductively.

THEOREM 16. Let \( v_i \in V_{n_i}, \ 1 \leq i \leq 4, \) be eigenvectors for \( L(0) \) with \( L(0)v_i = wt(v_i)v_i = |v_i|v_i. \) For \( i = 1, 2 \) let \( Y_i = Y(v_i, z_i), \partial_i = \partial/\partial z_i, \) and recall the notation

\[ G(v_1, v_2, v_3, v_4; z_1, z_2) = (Y_1 Y_2 v_3, v_4). \]
Then for any \( k \in \mathbb{Z} \) we have

\[
G(v_1, v_2, v_3, L(-k)v_4; z_1, z_2) = G(v_1, v_2, L(k)v_3, v_4; z_1, z_2) \\
+ (z_1^{k+1} \partial_1 + z_2^{k+1} \partial_2)G(v_1, v_2, v_3, v_4; z_1, z_2) \\
+ (k + 1)(z_1^k) |v_1| + z_2^k |v_2|)G(v_1, v_2, v_3, v_4; z_1, z_2) \\
+ \sum_{i \geq 1} \binom{k+1}{i+1} z_1^{k-i} G(L(i)v_1, v_2, v_3, v_4; z_1, z_2) \\
+ \sum_{i \geq 1} \binom{k+1}{i+1} z_2^{k-i} G(v_1, L(i)v_2, v_3, v_4; z_1, z_2).
\]

**Proof.** We have

\[
G(v_1, v_2, v_3, L(-k)v_4; z_1, z_2) = (L(k)Y_1 Y_2 v_3, v_4) \\
= ([L(k), Y_1] Y_2 v_3, v_4) + (Y_1[L(k), Y_2] v_3, v_4) + (Y_1 Y_2 L(k) v_3, v_4) \\
= \sum_{i \geq 0} \binom{k+1}{i} z_1^{k+1-i} (Y(L(i-1)v_1, z_1) Y_2 v_3, v_4) \\
+ \sum_{i \geq 0} \binom{k+1}{i} z_2^{k+1-i} (Y_1 Y(L(i-1)v_2, z_2) v_3, v_4) \\
+ (Y_1 Y_2 L(k) v_3, v_4)
\]

giving the result after separating the \( i = 0 \) and the \( i = 1 \) terms and reindexing. \( \blacksquare \)

**Theorem 17.** Let \( v_i \in \mathcal{V}_{n_i}, 1 \leq i \leq 4, \) be eigenvectors for \( L(0) \) with \( L(0) v_i = wt(v_i) v_i = |v_i| v_i. \) Let \( \partial_1 = \partial / \partial z_1, \partial = \partial / \partial z, \) and recall the notation

\[
H(v_1, v_2, v_3, v_4; z, z) = (Y(Y(v_1, z)v_2, z_2) v_3, v_4).
\]

Then for any \( k \in \mathbb{Z} \) we have

\[
H(v_1, v_2, v_3, L(-k)v_4; z, z_2) \\
= H(v_1, v_2, L(k)v_3, v_4; z, z_2) \\
+ z_2^{k+1} \partial_2 H(v_1, v_2, v_3, v_4; z, z_2) \\
+ (k + 1)(z_2^k) |v_2| + (z_2 + z)^k |v_1|)H(v_1, v_2, v_3, v_4; z, z_2) \\
+ [(z_2 + z) z_2^{k+1} - z_2^{k+1}] \partial H(v_1, v_2, v_3, v_4; z, z_2) \\
+ \sum_{i \geq 1} \binom{k+1}{i+1} z_2^{k-i} H(v_1, L(i)v_2, v_3, v_4; z, z_2) \\
+ \sum_{j \geq 1} \binom{k+1}{j+1} (z_2 + z)^{k-j} H(L(j)v_1, v_2, v_3, v_4; z, z_2).
\]

**Proof.** For brevity, let us write

\[
H = H(v_1, v_2, v_3, v_4; z, z_2), \quad H(L(k)v_3) = H(v_1, v_2, L(k)v_3, v_4; z, z_2), \\
H(L(j)v_1) = H(L(j)v_1, v_2, v_3, v_4; z, z_2)
\]
We have

\[ H(L(i)v_2) = H(v_1, L(i)v_2, v_3, v_4; z, z_2). \]

and

\[ H(v_1, v_2, v_3, L(-k)v_4; z, z_2) \]

\[ = ([L(k), Y(Y(v_1, z)v_2)]v_3, v_4) + (Y(Y(v_1, z)v_2)L(k)v_3, v_4) \]

\[ = \sum_{i \geq 0} \binom{k+1}{i} z_2^{k+1-i}Y(L(i-1)Y(v_1, z)v_2, z_2)v_3, v_4) + H(L(k)v_3) \]

\[ = z_2^{k+1} \partial \partial H + H(L(k)v_3) + \sum_{i \geq 1} \binom{k+1}{i} z_2^{k-i}(Y([L(i), Y(v_1, z)]v_2, z_2)v_3, v_4) \]

\[ + (k+1)z_2^k|v_2|H + \sum_{i \geq 1} \binom{k+1}{i} z_2^{k-i}(Y(Y(v_1, z)L(i)v_2, z_2)v_3, v_4) \]

\[ = z_2^{k+1} \partial \partial H + H(L(k)v_3) \]

\[ + \sum_{i \geq 0} \binom{k+1}{i} z_2^{k-i} \left( z_2^{i+1} \partial H + (i+1)z_2^i|v_1|H + \sum_{j \geq 1} \binom{i+1}{j} z_2^{j-i}H(L(j)v_1) \right) \]

\[ + (k+1)z_2^k|v_2|H + \sum_{i \geq 1} \binom{k+1}{i} z_2^{k-i}H(L(i)v_2) \]

which gives the result after using

\[ \binom{k+1}{i}(i+1) = (k+1)\binom{k}{i} \]

and

\[ (z_2 + z)^m = z_2^m \left( 1 + \frac{z}{z_2} \right)^m = z_2^m \sum_{i \geq 0} \binom{m}{i} \left( \frac{z}{z_2} \right)^i. \]

For \( 1 \leq i \leq 4 \) let \( v_i \in V_{n_i} \) with \( wt(v_i) = |v_i| = N_i + \Delta_{n_i} \) for \( 0 \leq N_i \in \mathbb{Z} \). For \( n_1, n_2, n_3 \in \{ 1, 3 \} \) we have

\[ \Delta(n_1, n_2 + n_3) = \begin{cases} 0 & \text{if } n_2 + n_3 = 0 \\ \frac{1}{8} & \text{if } n_2 + n_3 = 2 \end{cases} \]

and

\[ \Delta(n_2, n_3) = \begin{cases} 1 & \text{if } n_2 + n_3 = 0 \\ -\frac{3}{8} & \text{if } n_2 + n_3 = 2 \end{cases} \]
so that

\[ \Delta(n_1, n_2 + n_3) + \Delta(n_2, n_3) = \frac{1}{s} \]

for \( n_1, n_2, n_3 \in \{1, 3\} \). Let \( N = N_1 + N_2 + N_3 - N_4 \). With \( t = z_2/z_1 \) and \( \Delta = \Delta(n_1, n_2 + n_3) \) we have

\[ G(v_1, v_2, v_3, v_4; z_1, z_2) = t^{N_1 - N_4 + \Delta} z_2^{-N - \frac{1}{s}} \Phi(v_1, v_2, v_3, v_4; t) \]

where

\[ \Phi(v_1, v_2, v_3, v_4; t) = \sum_{0 \leq k \in \mathbb{Z}} t^k \Phi_k(v_1, v_2, v_3, v_4) \]

is a power series in \( t \). Similarly, with \( s = z/z_2 = t^{-1} - 1 \) and \( \tilde{\Delta} = \Delta(n_1 + n_2, n_3) \) we have

\[ H(v_1, v_2, v_3, v_4; z, z_2) = s^{N_3 - N_4 + \tilde{\Delta}} z^{-N - \frac{1}{s}} \Psi(v_1, v_2, v_3, v_4; s) \]

where

\[ \Psi(v_1, v_2, v_3, v_4; s) = \sum_{0 \leq k \in \mathbb{Z}} s^k \Psi_k(v_1, v_2, v_3, v_4) \]

is a power series in \( s \).

We choose the relationship \( s^{1/2} = (t^{-1} - 1)^{1/2} \) such that we have \( (1 - x_0^2)/2x_0 = -2x_1/(1 - x_1^2) \). We wish to rewrite the recursions for \( G \) and \( H \) given in the last two theorems as recursions for the functions

\[ \tilde{\Phi}(v_1, v_2, v_3, v_4; x) = (1 - x^4)^{\frac{1}{2}} z_2^{N - \frac{1}{s}} G(v_1, v_2, v_3, v_4; z_1, z_2) \]

\[ = (1 - x^4)^{\frac{1}{2}} t^{N_1 - N_4 + \Delta} \Phi(v_1, v_2, v_3, v_4; t) \]

where \( x = x_0 \) or \( x = x_\infty \) and \( t^{1/2} = 2x/(1 + x^2) \), and

\[ \tilde{\Psi}(v_1, v_2, v_3, v_4; w) = (1 - w^4)^{\frac{1}{2}} z_2^{N - \frac{1}{s}} H(v_1, v_2, v_3, v_4; z, z_2) \]

\[ = (1 - w^4)^{\frac{1}{2}} s^{N_3 - N_4 + \tilde{\Delta}} \Psi(v_1, v_2, v_3, v_4; s) \]

where \( w = x_1 \) or \( w = x_\infty \) and \( s^{1/2} = 2w/(1 - w^2) \).

We will later apply the first of these recursions to the functions

\[ \tilde{\Phi}(v_2, v_1, v_3, v_4; y) = (1 - y^4)^{\frac{1}{2}} z_1^{N - \frac{1}{s}} G(v_2, v_1, v_3, v_4; z_2, z_1) \]

\[ = (1 - y^4)^{\frac{1}{2}} t^{-N_2 + N_4 - \Delta'} \Phi(v_2, v_1, v_3, v_4; t^{-1}) \]

where \( y = x_1 \) or \( y = x_\infty \) and \( \Delta' = \Delta(n_2, n_1 + n_3) \). These will be obtained from the first kind of recursions by switching \( v_1 \) with \( v_2, z_1 \) with \( z_2 \), and \( n_1 \) with \( n_2 \), and by replacing \( t \) by \( t^{-1} \). Define the matrices

\[ [\tilde{\Phi}_{\top \text{top}}]_{\alpha} = (1 - x_0^4)^{\frac{1}{2}} z_2^{\frac{1}{s}} [G(z_1, z_2)]_{\alpha} \]

for \( \alpha = 0 \) or \( \alpha = \infty \),

\[ [\tilde{\Phi}_{\top \text{top}}]_{\alpha} = (1 - x_0^4)^{\frac{1}{2}} z_2^{\frac{1}{s}} [G(z_2, z_1)]_{\alpha} \]

for \( \alpha = i \) or \( \alpha = -i \), and

\[ [\tilde{\Psi}_{\top \text{top}}]_{\alpha} = (1 - x_0^4)^{\frac{1}{2}} z_1^{\frac{1}{s}} [H(z, z_2)]_{\alpha} \]
for $\alpha = 1$ or $\alpha = -1$. Then our earlier work, which will give the base cases of our inductions, can be written as

$$[\hat{\Phi}_{top}]_0 \sim x_{\infty}^{-1} B_{\infty} \left[ \hat{\Phi}_{top} \right]_{\infty}$$

$$\sim (ix_1 + 1)^{-1} B_i \left[ \hat{\Phi}_{top} \right]_i \sim (ix_1 - 1)^{-1} B_{-i} \left[ \hat{\Phi}_{top} \right]_{-i}$$

$$\sim (x_1 + 1)^{-1} B_{-1} \left[ \hat{\Phi}_{top} \right]_{-1} \sim (x_1 + 1)^{-1} B_1 \left[ \hat{\Phi}_{top} \right]_1$$

The general case requires us to define $2 \times 4$ matrices which are analogs of $[\hat{\Phi}_{top}]_\alpha$ and $[\hat{\Psi}_{top}]_\alpha$ with the “top” vectors $u_n$, replaced by general vectors. There is no loss of generality in assuming that these vectors $v_i$ are $L(0)$-eigenvectors with $wt(v_i) = N_i + \Delta_{n_i}$, $1 \leq i \leq 4$. We must do this in such a way that our induction formulas imply that the above top $\sim$ relations hold for the more general matrices. This means that we need a more general description than the pattern of subscripts defining the matrices $[G(z_1, z_2)]$, $[G(z_2, z_1)]$ and $[H(z, z_2)]$. We will use the isomorphism $\theta$ on $\text{CM}(\mathbb{Z})$ defined at the beginning of this paper to give such a description. Assume that $v_1, v_2, v_3, v_4 \in V_1$ and $v_4 \in V_3$ are $L(0)$-eigenvectors with weights as given above. In the entries of the following matrices we will write the functions $\hat{\Phi}(v_1, v_2, v_3, v_4; x_\alpha)$ and $\hat{\Psi}(v_1, v_2, v_3, v_4; x_\alpha)$ more briefly as just $\hat{\Phi}(v_1, v_2, v_3, v_4)$ and $\hat{\Psi}(v_1, v_2, v_3, v_4)$. For $\alpha = 0$ or $\alpha = \infty$, define the matrix

$$[\hat{\Phi}]_\alpha = [\hat{\Phi}(v_1, v_2, v_3, v_4; x_\alpha)] =$$

$$\begin{bmatrix}
\hat{\Phi}(v_1, v_2, v_3, v_4) & \hat{\Phi}(v_1, v_2, v_3, v_4) & \hat{\Phi}(v_1, v_2, v_3, v_4) & \hat{\Phi}(v_1, v_2, v_3, v_4)
\end{bmatrix}.$$  

For $\alpha = i$ or $\alpha = -i$ define the matrix

$$[\hat{\Phi}]_\alpha = [\hat{\Phi}(v_1, v_2, v_3, v_4; x_\alpha)] =$$

$$\begin{bmatrix}
\hat{\Phi}(v_2, v_1, v_3, v_4) & \hat{\Phi}(v_2, v_1, v_3, v_4) & \hat{\Phi}(v_2, v_1, v_3, v_4) & \hat{\Phi}(v_2, v_1, v_3, v_4)
\end{bmatrix}.$$  

For $\alpha = 1$ or $\alpha = -1$ define the matrix

$$[\hat{\Psi}]_\alpha = [\hat{\Psi}(v_1, v_2, v_3, v_4; x_\alpha)] =$$

$$\begin{bmatrix}
\hat{\Psi}(v_1, v_2, v_3, v_4) & \hat{\Psi}(v_1, v_2, v_3, v_4) & \hat{\Psi}(v_1, v_2, v_3, v_4) & \hat{\Psi}(v_1, v_2, v_3, v_4)
\end{bmatrix}.$$  

In our inductions we will see such matrices with one of the vectors, say $v_i$, replaced by $L(-k)v_i$. We will denote the above matrices with such a replacement by $[\hat{\Phi}(L(-k)v_i)]_\alpha$ and $[\hat{\Psi}(L(-k)v_i)]_\alpha$.

Let $\Phi' = \frac{\partial}{\partial \sigma} \Phi$, $\Psi' = \frac{\partial}{\partial \sigma} \Psi$ and let us use notations such as $\hat{\Phi}(L(i)v_1) = \hat{\Phi}(L(i)v_1, v_2, v_3, v_4; x)$ as we did in the proof of Theorem 17. We have

$$\partial_1 G = \frac{N_4 - N_1 - \Delta}{z_1} G - \frac{z_2}{z_1} N_1 - N_4 + \Delta_{z_2} - \frac{N}{8} \Phi'$$

$$\partial_2 G = \frac{\Delta - N_2 - N_4 - \frac{1}{4} \Delta}{z_2} G + \frac{1}{z_1} N_1 - N_4 + \Delta_{z_2} - \frac{N}{8} \Phi'$$

$$\partial H = -\frac{N_1 - N_2 - \frac{1}{4} + \Delta}{z} H + \frac{1}{z_2} N_1 - N_4 + \Delta_{z_2} - \frac{N}{8} \Psi'$$

$$\partial_2 H = \frac{N_4 - N_3 - \Delta}{z_2} H - \frac{z_2}{z_1} N_3 - N_4 + \Delta_{z_2} - \frac{N}{8} \Psi'.$$
Theorem 18. Define the operator
\[
\mathcal{L}_x = \frac{x(1 + x^2)}{2(1 - x^2)} \frac{d}{dx} + \frac{x^4}{2(1 - x^2)^2} = \frac{x(1 + x^2)}{2(1 - x^2)} \left[ \frac{d}{dx} + \frac{x^3}{1 - x^4} \right].
\]

Then for any \( k \in \mathbb{Z} \) we have
\[
\dot{\Phi}(L(-k)v_4) = \dot{\Phi}(L(k)v_3) - (N + \frac{1}{8})\dot{\Phi} + (1 - t^{-k})\mathcal{L}_x \dot{\Phi}
+ \sum_{i \geq 0} \left( k + 1 \right) \left( t^{-i}\dot{\Phi}(L(i)v_1) + \dot{\Phi}(L(i)v_2) \right).
\]

Proof. For any \( k \in \mathbb{Z} \) we have
\[
\dot{\Phi}(L(-k)v_4) = (1 - x^4)^{1/2} \sum_{i=2}^{N-k+1/8} G(v_1, v_2, v_3, L(-k)v_4; z_1, z_2)
= (1 - x^4)^{1/2} \sum_{i=2}^{N-k+1/8} G(v_1, v_2, L(k)v_3, v_4; z_1, z_2)
+ (1 - x^4)^{1/2} \sum_{i=2}^{N-k+1/8} (z_1^{k+1}\partial_1 + z_2^{k+1}\partial_2) G(v_1, v_2, v_3, v_4; z_1, z_2)
+ (1 - x^4)^{1/2} \sum_{i=2}^{N-k+1/8} \left( k + 1 \right) z_1^{k-i} G(L(i)v_1, v_2, v_3, v_4; z_1, z_2)
+ (1 - x^4)^{1/2} \sum_{i=2}^{N-k+1/8} \left( k + 1 \right) z_2^{k-i} G(v_1, L(i)v_2, v_3, v_4; z_1, z_2)
= \dot{\Phi}(L(k)v_3) + ((N_4 - N_1 - \Delta)t^{-k} + (\Delta - N_2 - N_3 - \frac{1}{8}))\dot{\Phi}
+ (t - t^{-k})t^{N_4 - N_4 + \Delta}(1 - x^4)^{1/2}\Phi' + (k + 1)(t^{-k}|v_1| + |v_2|)\dot{\Phi}
+ \sum_{i \geq 1} \left( k + 1 \right) t^{-i}\dot{\Phi}(L(i)v_1) + \sum_{i \geq 1} \left( k + 1 \right) \dot{\Phi}(L(i)v_2).
\]

Note that
\[
\frac{d\Phi}{dx} = \frac{d\Phi}{dt} \frac{dt}{dx} \quad \text{and} \quad \frac{dt}{dx} = \frac{8x(1 - x^2)}{(1 + x^2)^3} = \frac{8x(1 - x^4)}{(1 + x^2)^4}
\]
so that
\[
\Phi' = \frac{d\Phi}{dt} = \frac{d\Phi}{dx} \frac{1 + x^2}{8x(1 - x^4)}.
\]

From
\[
\frac{d}{dx} \dot{\Phi}(x) = \frac{d}{dx} \left( (1 - x^4)^{1/2} t^{N_4 - N_4 + \Delta} \Phi(t) \right)
= -\frac{x^3}{1 - x^4} \dot{\Phi}(x) + \frac{N_4 - N_4 + \Delta}{t} \frac{dt}{dx} \dot{\Phi}(x) + (1 - x^4)^{1/2} t^{N_4 - N_4 + \Delta} \frac{d\Phi}{dx}
\]
we get
\[
(1 - x^4)^{1/2} t^{N_4 - N_4 + \Delta} \frac{d\Phi}{dt} = \left( \frac{dt}{dx} \right)^{-1} \frac{d\Phi}{dx} + \frac{x^3}{1 - x^4} \left( \frac{dt}{dx} \right)^{-1} \dot{\Phi} - \frac{N_4 - N_4 + \Delta}{t} \dot{\Phi}.
\]
This gives us

\[
(t - t^{1-k})t^{N_4-N_1+\Delta}(1 - x^4)^{\frac{1}{4}} \Phi'
\]

\[
= (1 - t^{-k}) \left( \frac{x(1 + x^2)}{2(1 - x^2)} \frac{d}{dx} + \frac{x^4}{2(1 - x^2)^2} + (N_4 - N_1 - \Delta) \right) \Phi
\]

\[
= (1 - t^{-k})(\mathcal{L}_x + (N_4 - N_1 - \Delta)) \tilde{\Phi}
\]

which gives the result. ■

Note that the operator \( \mathcal{L}_x \) and multiplication by any integral power of \( t^{\frac{1}{2}} \) preserve the ring \( R_x \).

**Lemma 19.** For any \( g \in \mathbb{C}(x) \), if \( x = u^{-1} \), we have

\[
\mathcal{L}_x(xg(x^{-1})) = u^{-1} \mathcal{L}_u(g(u)).
\]

**Proof.** We have

\[
\mathcal{L}_x(xg(x^{-1})) = \frac{x(1 + x^2)}{2(1 - x^2)} \left( x \frac{dg}{du} \frac{du}{dx} + g(x^{-1}) + \frac{x^4}{1 - x^4} g(x^{-1}) \right)
\]

\[
= \frac{u^2 + 1}{2u(u^2 - 1)} \left( -u \frac{dg}{du} + g(u) + \frac{1}{u^4 - 1} g(u) \right)
\]

\[
= \frac{1 + u^2}{2(1 - u^2)} \frac{dg}{du} + \frac{u^3}{2(1 - u^2)^2} g(u)
\]

\[
= u^{-1} \mathcal{L}_u(g(u)).
\]

■

**Lemma 20.** For any \( g \in \mathbb{C}(x) \), if \( x = \frac{y+i}{iy+1} \), \( t^{1/2} = \frac{2x}{1+x^2} \) and \( N \in \mathbb{Z} \), we have

\[
\mathcal{L}_x(t^N(iy \pm 1)^{-1}g(x)) = \frac{-t^N}{iy \pm 1} (\mathcal{L}_y - N - \frac{1}{iy \pm 1}) g \left( \frac{\pm y + i}{iy \pm 1} \right).
\]
PROOF. We have

\[
\mathcal{L}_x(t^N (iy \pm 1)^{-1} g(x)) \\
= \frac{x(1 + x^2)}{2(1 - x^2)} \left[ \frac{t^N}{iy \pm 1} \frac{dy}{dy} + t^N g(x) \frac{d}{dx} (iy \pm 1)^{-1} \\
+ N t^{N-1} \frac{dt}{dx} (iy \pm 1)^{-1} g(x) + t^N (iy \pm 1)^{-1} \frac{x^3}{1 - x^2} g(x) \right] \\
= \frac{x(1 + x^2)}{2(1 - x^2)} \left[ \frac{t^N (iy \pm 1)^2}{iy \pm 1} \frac{d}{dy} - \frac{t^N i}{2} \\
+ \frac{N t^{N-1} 2x}{1 + x^2} \frac{2(1 - x^2)}{(1 + x^2)^2} (iy \pm 1)^{-1} + t^N (iy \pm 1)^{-1} \frac{x^3}{1 - x^2} \right] g(x) \\
= \frac{-t^N}{iy \pm 1} (1 + y^2) \left[ \frac{d}{dy} - \frac{i^{y + 1}}{(iy \pm 1)} \right] 2N(1 - y^2) \\
\quad + \frac{3y^2 - 1}{4y(1 - y^2)} - \frac{2N(1 - y^2)}{y(1 + y^2)} \right] g \left( \frac{\pm y + i}{iy \pm 1} \right) \\
= \frac{-t^N}{iy \pm 1} (1 + y^2) \left[ \frac{d}{dy} + \frac{y^3 - 1}{4y(1 - y^2)} - \frac{1 - y^2}{y(1 + y^2)} - \frac{2N(1 - y^2)}{y(1 + y^2)} \right] g \left( \frac{\pm y + i}{iy \pm 1} \right) \\
= \frac{-t^N}{iy \pm 1} \left[ \mathcal{L}_y - \frac{y^2}{2(1 - y^2)} \right] g \left( \frac{\pm y + i}{iy \pm 1} \right) \\
= \frac{-t^N}{iy \pm 1} (\mathcal{L}_y - \frac{1}{2}) g \left( \frac{\pm y + i}{iy \pm 1} \right)
\]

\[\blacksquare\]

Lemma 21. For any \( g \in \mathbb{C}(x) \), if \( x = \frac{w + 1}{w^2 + 1} \), \( s^{1/2} = \frac{2w}{1 - w^2} \) and \( N \in \mathbb{Z} \), we have

\[
\mathcal{L}_x(s^{-N}(\mp w + 1)^{-1} g(x)) = -s^{-N} \frac{1}{\mp w + 1} (s^{-1} \mathcal{L}_w - (N + \frac{1}{s})(1 + s^{-1})) g \left( \frac{w \pm 1}{\mp w + 1} \right).
\]
Proof. We have
\[
\mathcal{L}_x(s^{-N}(\mp w + 1)^{-1}g(x)) = \frac{x(1 + x^2)}{2(1 - x^2)} \left[ \frac{-s^{-N}}{\mp w + 1} \frac{dg}{dw} + s^{-N} g(x) \frac{dw}{dx} \frac{d}{dx} \frac{1}{w + 1} \right.
\]
\[
+ \frac{1}{\mp w + 1} g(x) \frac{dw}{dx} \frac{1}{w + 1} s^{-N} \frac{1}{(\mp w + 1)(1 - x^4)} g(x) \]
\[
= \frac{x(1 + x^2)}{2(1 - x^2)} \left[ \frac{-s^{-N}}{\mp w + 1} \frac{1}{2} \frac{d}{dw} \pm s^{-N} \frac{1}{2} \frac{1}{\mp w + 1} \frac{x^3}{w(1 - w^2)} \right]
\]
\[
- N(\mp w + 1)^2 \frac{1 + w^2}{w(1 - w^2)} g(x)
\]
\[
= \frac{x(1 + x^2)}{4(1 - x^2)} \left[ \frac{d}{dw} \pm \frac{1}{\mp w + 1} \right]
\]
\[
- \frac{2N(1 + w^2)}{w(1 - w^2)} \left[ \frac{2x^3}{w(1 - w^2)} \right] g(x)
\]
\[
= \frac{-s^{-N}(1 - w^2)(1 + w^2)}{8w} \left[ \frac{d}{dw} \pm \frac{1}{\mp w + 1} \right]
\]
\[
- \frac{2N(1 + w^2)}{w(1 - w^2)} \frac{(w \pm 1)^3}{4(\mp w + 1)(1 + w^2)} g(x)
\]
\[
= \frac{-s^{-N}(1 - w^2)(1 + w^2)}{8w} \left[ \frac{d}{dw} \pm \frac{1}{1 - w^4} \right] (\frac{8N + 1)(1 + w^2)}{4w(1 - w^2)} g(x)
\]
\[
= \frac{-s^{-N}}{\mp w + 1} \left[ \frac{(1 - w^2)(1 + w^2)}{8w} \left( \frac{d}{dw} \pm \frac{w^3}{1 - w^4} \right) \right] (\frac{1}{1 - w^2}) g(x)
\]
\[
= \frac{-s^{-N}}{\mp w + 1} \left[ s^{-1} \mathcal{L}_w - (N + \frac{1}{8}) (1 + s^{-1}) g \left( \frac{w \pm 1}{\mp w + 1} \right) \right].
\]

\textbf{Theorem 22.} For any \( k \in \mathbb{Z} \) we have

\[
\tilde{\Psi}(L(-k)v_1) = \tilde{\Psi}(L(k)v_1) - (N + \frac{1}{8}) s^{-k-1}(1 + s)^k \tilde{\Psi} + s^{-k-1}[(1 + s)^k - 1] \mathcal{L}_w \tilde{\Psi}
\]
\[
\quad + \sum_{i \geq 0} \left( \frac{k + 1}{i + 1} \right) \left[ s^{i-k} \tilde{\Psi}(L(i)v_2) + \left( \frac{1 + s}{s} \right)^{k-i} \tilde{\Psi}(L(i)v_1) \right].
\]
Proof. For any $k \in \mathbb{Z}$ we have

\[ \tilde{\Psi}(L(-k)v_4) = (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \Psi(v_1, v_2, v_3, L(-k)v_4; z, z_2) \]

\[ = (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \Psi(v_1, v_2, L(k)v_3, v_4; z, z_2) \]

\[ + (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \Psi(v_1, v_2, v_3, v_4; z, z_2) \]

\[ + (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \Psi(v_1, v_2, v_3, v_4; z, z_2) \]

\[ + (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \Psi(v_1, v_2, v_3, v_4; z, z_2) \]

\[ = \tilde{\Psi}(L(k)v_3) + (N_4 - N_3 - \bar{\Delta}) s^{-k} \tilde{\Psi} - s^{1-k}(1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \Psi' \]

\[ - (N_1 + N_2 + \frac{1}{s} - \bar{\Delta}) s^{-k-1}[(1 + s)^{k+1} - 1] \tilde{\Psi} \]

\[ + s^{-k}[(1 + s)^{k+1} - 1] s^{N_3 - N_4 + \bar{\Delta}} (1 - w^4)^{\frac{1}{4}} \tilde{\Psi} \]

\[ + \sum_{i \geq 0} \left( \frac{k + 1}{i + 1} \right) s^{i-k}(1 + s)^{k+i} \tilde{\Psi}(L(i)v_1) \]

Note that

\[ \frac{d \Psi}{dw} = \frac{d \Psi}{ds} \frac{ds}{dw} \quad \text{and} \quad \frac{ds}{dw} = \frac{8w(1 + w^2)}{(1 - w^4)^3} = \frac{8w(1 - w^4)}{(1 - w^4)^4} \]

so that

\[ \Psi' = \frac{d \Psi}{ds} = \frac{d \Psi}{dw} \frac{(1 - w^4)^{\frac{1}{4}}}{8w(1 - w^4)}. \]

From

\[ \frac{d}{dw} \tilde{\Psi}(w) = \frac{d}{dw} \left( (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \Psi(s) \right) \]

\[ = \frac{-w^3}{1 - w^4} \tilde{\Psi}(w) + s^{N_3 - N_4 + \bar{\Delta}} \frac{ds}{dw} \tilde{\Psi}(w) + (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \frac{d \Psi}{dw} \]

we get

\[ (1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \frac{d \Psi}{ds} = \left( \frac{ds}{dw} \right)^{-1} \frac{d \tilde{\Psi}}{dw} + \frac{w^3}{1 - w^4} \left( \frac{ds}{dw} \right)^{-1} \tilde{\Psi} = \frac{s^{N_3 - N_4 + \bar{\Delta}}}{s} \tilde{\Psi}. \]

The two terms involving $\Psi'$ in the above expression for $\tilde{\Psi}(L(-k)v_4)$ combine to give

\[ s^{-k}(1 + s)[(1 + s)^k - 1](1 - w^4)^{\frac{1}{4}} s^{N_3 - N_4 + \bar{\Delta}} \frac{d \Psi}{ds} \]
and since \(1 + s = \frac{(1 + w^2)^2}{(1 - w^2)^2}\) this gives us

\[
\begin{align*}
& s^{-k}(1 + s)[(1 + s)^k - 1](1 - w^4) \frac{1}{8} s N_3 - N_4 + \bar{\Delta} \Psi' \\
= & s^{-k}[1 + s]^{k - 1} \left( \frac{1 - w^4}{8w} \frac{d}{dw} + \frac{w^2}{8} - \frac{(N_3 - N_4 + \bar{\Delta})(1 + s)}{s} \right) \tilde{\Psi} \\
= & s^{-k}[1 + s]^{k - 1} \left( \frac{L_w}{s} - \frac{(N_3 - N_4 + \bar{\Delta})(1 + s)}{s} \right) \tilde{\Psi}.
\end{align*}
\]

Substituting this in the earlier expression, after some simplification, we get the result. \(\blacksquare\)

Note that the operator \(L_w\) and multiplication by any rational function in \(s^\frac{1}{2}\) preserve the ring \(\mathcal{R}_w\).

Now let us return to the problem of determining the general two-point functions inductively.

**Theorem 23.** For \(1 \leq i \leq 4\) let \(v_i \in V_{n_i}\) be eigenvectors for \(L(0)\) with \(L(0)v_i = wt(v_i)v_i = |v_i|v_i\). For \(i = 1, 2\) let \(Y_i = Y(v_i, z_i), \partial_i = \partial/\partial z_i\). Then for any \(k \in \mathbb{Z}\) we have

\[
G(L(-k)v_1, v_2, v_3, v_4; z_1, z_2)
= \sum_{i \geq 0} \left( \frac{k + i - 2}{i} \right) z_1^i G(v_1, v_2, v_3, L(k + i)v_4; z_1, z_2) \\
+ (-1)^k (z_1 - z_2)^{1-k} \partial_2 G(v_1, v_2, v_3, v_4; z_1, z_2) \\
+ (-1)^k \sum_{j \geq 0} (-1)^{j+1} \left( \frac{1 - k}{j + 1} \right) (z_1 - z_2)^{-k-j} G(v_1, L(j)v_2, v_3, v_4; z_1, z_2) \\
+ (-1)^k \sum_{i \geq 0} \left( \frac{k + i - 1}{i + 1} \right) z_1^{-k-1} G(v_1, v_2, L(i)v_3, v_4; z_1, z_2) \\
+ (-1)^k z_1^{-k} (G(v_1, v_2, v_3, L(1)v_4; z_1, z_2) - (\partial_1 + \partial_2)G(v_1, v_2, v_3, v_4; z_1, z_2)).
\]
Proof. We have
\[ G(L(-k)v_1, v_2, v_3; z_1, z_2) = (Y(L(-k)v_1, z_1)Y_2v_3, v_4) \]
\[ = \sum_{i \geq 0} \binom{k+i-2}{i} z_1^i (L(-k-i)Y_1Y_2v_3, v_4) \]
\[ + (-1)^k \sum_{i \geq 0} \binom{k+i-2}{i} z_1^{k+1-i} (Y_1L(i-1)Y_2v_3, v_4) \]
\[ = \sum_{i \geq 0} \binom{k+i-2}{i} z_1^i G(v_1, v_2, v_3; L(k+i)v_4; z_1, z_2) \]
\[ + (-1)^k \sum_{i \geq 0} \binom{k+i-2}{i} z_1^{k+1-i} \left( [Y_1[L(i-1), Y_2]v_3, v_4) \right. \]
\[ + (Y_1Y_2L(i-1)v_3, v_4) \]
\[ = \sum_{i \geq 0} \binom{k+i-2}{i} z_1^i G(v_1, v_2, v_3; L(k+i)v_4; z_1, z_2) \]
\[ + (-1)^k \sum_{i \geq 0} \binom{k+i-2}{i} z_1^{k+1-i} \sum_{j \geq 0} \binom{i}{j} z_2^j Y_1Y(L(j-1)v_2, z_2)v_3, v_4) \]
\[ + (-1)^k \sum_{i \geq 0} \binom{k+i-2}{i} z_1^{k+1-i} (Y_1Y_2L(i-1)v_3, v_4) \]
\[ = \sum_{i \geq 0} \binom{k+i-2}{i} z_1^i G(L(k+i)v_4) + (-1)^k z_1^{k-1} \sum_{i \geq 0} \binom{k+i-2}{i} \left( \frac{z_2}{z_1} \right)^i \partial_2 G \]
\[ + (-1)^k \sum_{j \geq 0} \sum_{i \geq 0} \binom{k+i-2}{i-j+1} \left( \frac{z_2}{z_1} \right)^{i-j} \partial_2 G \]
\[ + (-1)^k \sum_{i \geq 0} \binom{k+i-1}{i} z_1^{k-i} G(L(i)v_3) + (-1)^k z_1^{k-1} (Y_1Y_2L(-1)v_3, v_4) \]
\[ = \sum_{i \geq 0} \binom{k+i-2}{i} z_1^i G(L(k+i)v_4) + (-1)^k z_1^{k-1} \partial_2 G \sum_{i \geq 0} \binom{k+i-2}{i} \left( \frac{z_2}{z_1} \right)^i \]
\[ + (-1)^k \sum_{j \geq 0} z_1^{-j-k} G(L(j)v_2) \sum_{i \geq 0} \binom{k+i-2}{i-j+1} \left( \frac{z_2}{z_1} \right)^{i-j} \]
\[ + (-1)^k \sum_{i \geq 0} \binom{k+i-1}{i+1} z_1^{k-i} G(L(i)v_3) \]
\[ + (-1)^k z_1^{k-1} (G(L(1)v_4) - ([L(-1), Y_1]Y_2v_3, v_4) - (Y_1[L(-1), Y_2]v_3, v_4)). \]

We may write the last line as
\[ (-1)^k z_1^{k-1} (G(L(1)v_4) - (\partial_1 + \partial_2)G). \]

Also, note that
\[ \binom{k+i-2}{i} = (-1)^i \binom{1-k}{i} \]
so
\[ \sum_{i \geq 0} \binom{k+i-2}{i} \left( \frac{z_2}{z_1} \right)^i = \sum_{i \geq 0} (-1)^i \binom{1-k}{i} \left( \frac{z_2}{z_1} \right)^i = (1 - \frac{z_2}{z_1})^{1-k} \]
and therefore,
\[ (-1)^k z_1^{1-k} \partial_2 G \sum_{i \geq 0} \binom{k+i-2}{i} \left( \frac{z_2}{z_1} \right)^i = (-1)^k (z_1 - z_2)^{1-k} \partial_2 G. \]

In addition, we have
\[ \sum_{i \geq 0} (-1)^i \binom{1-k}{i} \frac{i}{j+1} t^{i-j-1} = \frac{1}{(j+1)!} \partial_{t}^{j+1} \sum_{i \geq 0} (-1)^i \binom{1-k}{i} t^i \]
so that
\[ (-1)^k \sum_{j \geq 0} \frac{1}{z_2^{j-k}} G(L(j)\nu_2) \sum_{i \geq 0} \binom{k+i-2}{i} \left( \frac{i}{j+1} \right) \left( \frac{z_2}{z_1} \right)^i = (-1)^k \sum_{j \geq 0} \frac{1}{z_2^{j-k}} G(L(j)\nu_2) (-1)^j \binom{1-k}{j+1} \left( 1 - \frac{z_2}{z_1} \right)^{j-k} \]
which gives the result.

**Theorem 24.** For $1 \leq i \leq 4$ let $v_i \in V_n$ be eigenvectors for $L(0)$ with $L(0)v_i = wt(v_i)v_i = |v_i||v_i|v_i$. For $i = 1, 2$ let $Y_i = Y(v_i, z_i)$, $\partial_i = \partial/\partial z_i$. Then for any $k \in \mathbb{Z}$ we have
\[
G(v_1, L(-k)v_2, v_3, v_4; z_1, z_2) = \sum_{i \geq 0} \binom{k+i-2}{i} z_2^i G(v_1, v_2, v_3, L(k+i)v_4; z_1, z_2) \\
+ (-1)^k \sum_{i \geq 0} \binom{k+i-1}{i+1} z_2^{k-i} G(v_1, v_2, L(i)v_3, v_4; z_1, z_2) - (\partial_1 G)(z_1 - z_2)^{1-k} \\
+ \sum_{j \geq 0} G(L(j)v_1, v_2, v_3, v_4; z_1, z_2) (-1)^j z_2^{-j-k}. \\
\sum_{i \geq 0} (-1)^i \binom{1-k}{i} \binom{i+j+k}{j+1} z_2^{i+j+k} \\
+ (-1)^k z_2^{1-k} (G(v_1, v_2, v_3, L(1)v_4; z_1, z_2) - (\partial_1 + \partial_2) G(v_1, v_2, v_3, v_4; z_1, z_2)).
\]
We may rewrite the second line in the last expression as

\[ G(v_1, L(-k)v_2, v_3; z_1, z_2) = (Y_1 Y(L(-k)v_2, z_2)v_4) \]

\[ = \sum_{i \geq 0} \binom{k + i - 2}{i} z_2^i (Y_1 L(-k - i)Y_2 v_3, v_4) \]

\[ + (-1)^k \sum_{i \geq 0} \binom{k + i - 2}{i} z_2^{i+1} (Y_1 Y_2 L(i - 1)v_3, v_4) \]

\[ = \sum_{i \geq 0} \binom{k + i - 2}{i} z_2^i (L(-k - i)Y_1 Y_2 v_3, v_4) \]

\[ - \sum_{i \geq 0} \binom{k + i - 2}{i} z_2^i ([L(-k - i), Y_1]Y_2 v_3, v_4) \]

\[ + (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} z_2^{-i} G(L(i)v_3) \]

\[ + (-1)^k z_2^{-k}(G(L(1)v_4) - (\partial_1 + \partial_2)G) \]

\[ = \sum_{i \geq 0} \binom{k + i - 2}{i} z_2^i G(L(i)v_4) \]

\[ - \sum_{i \geq 0} \binom{k + i - 2}{i} z_2^i \sum_{j \geq 0} \binom{-k - i + 1}{j} z_1^{1-i-j-k} (Y(L(j - 1)v_1, z_1)Y_2 v_3, v_4) \]

\[ + (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} z_2^{-i} G(L(i)v_3) \]

\[ + (-1)^k z_2^{-k}(G(L(1)v_4) - (\partial_1 + \partial_2)G) \]

We may rewrite the second line in the last expression as

\[ - \sum_{j \geq 0} G(L(j - 1)v_1)(-1)^j z_2^{1-j-k} \]

\[ \sum_{i \geq 0} (-1)^i \binom{1 - k}{i} \binom{i + j + k - 2}{j} \left( \frac{z_2}{z_1} \right)^{i+j+k} \]

\[ = - (\partial t G)(z_1 - z_2)^{1-k} \]

\[ + \sum_{j \geq 0} G(L(j)v_1)(-1)^j z_2^{-j-k} \sum_{i \geq 0} (-1)^i \binom{1 - k}{i} \binom{i + j + k - 1}{j + 1} \left( \frac{z_2}{z_1} \right)^{i+j+k} \]

giving the result. Note that the \( j = 0 \) term in the last line simplifies to

\[ (k - 1)|v_1|G(z_1 - z_2)^{-k}. \]
Theorem 25. For any \( k \in \mathbb{Z} \) we have

\[
H(L(-k)v_1) = \sum_{i \geq 0} (-1)^i \binom{1-k}{i} (z_2 + z)^i H(L(k + i)v_4)
+ (-1)^k (z_2 + z)^{1-k} (H(L(1)v_4) - \partial_2 H)
+ (-1)^k \sum_{j \geq 0} H(L(j)v_3) z^{-j-k} \sum_{i \geq 0} \binom{k + i - 1}{i + 1} \left( i + j + k - 1 \right) \left( z \over z_2 \right)^i j^{i+j+k}
+ (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} z^{-k-1} H(L(i)v_2)
+ (-1)^k z^{1-k} (\partial_2 H - \partial H)
\]

and

\[
H(L(-k)v_2) = \sum_{i \geq 0} \binom{k - 2}{i} z_2^i H(L(k + i)v_4)
+ (-1)^k z_2^{-k} (H(L(1)v_4) - \partial_2 H)
+ (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} z_2^{-k-1} H(L(i)v_3)
- z^{1-k} \partial H - \sum_{i \geq 0} \binom{1-k}{i + 1} z^{-k-1} H(L(i)v_1)
\]

Theorem 26. For any \( k \in \mathbb{Z} \) we have

\[
\tilde{\Phi}(L(-k)v_1) = \sum_{i \geq 0} \binom{k + i - 2}{i} \xi^{-i} \tilde{\Phi}(L(k + i)v_4)
+ (-1)^k (N + {\textstyle 1 \over t} + 1)^k \partial_{(1 - t)}^{k-1} \tilde{\Phi}
+ (-1)^k k^{k-1} \partial_{(1 - t)} \partial \tilde{\Phi}
+ (-1)^k \sum_{j \geq 0} (-1)^{j+1} \binom{1-k}{j+1} \left( {t \over (1-t)} \right)^{j+k} \tilde{\Phi}(L(j)v_2)
+ (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} \partial_{(1 - t)}^{k-1} \tilde{\Phi}(L(i)v_3)
+ (-1)^k k^{k-1} \tilde{\Phi}(L(1)v_4)
\]
and
\[
\tilde{\Phi}(L(-k)v_2) = \sum_{i \geq 0} \binom{k+i-2}{i} \tilde{\Phi}(L(k+i)v_4) \\
+ (-1)^k \sum_{i \geq 0} \binom{k+i-1}{i+1} \tilde{\Phi}(L(i)v_3) \\
+ [t^k(1-t)^{-k}(-1)^k](1-t)\mathcal{L}_x \tilde{\Phi} \\
+ \sum_{j \geq 0} (-1)^j \tilde{\Phi}(L(j)v_1) \sum_{i \geq 0} (-1)^i \left(1-k \atop i\right) \left(i+j+k-1 \atop j+1\right) t^{i+j+k} \\
+ (-1)^k \tilde{\Phi}(L(1)v_4) + (-1)^k(N + \frac{1}{8}) \tilde{\Phi}.
\]

**Theorem 27.** For any \( k \in \mathbb{Z} \) we have
\[
\tilde{\Psi}(L(-k)v_1) = \sum_{i \geq 0} (-1)^i \left(1-k \atop i\right) \left(\frac{1+s}{s}\right)^i \tilde{\Psi}(L(k+i)v_4) \\
+ (-1)^k \left(\frac{1+s}{s}\right)^{1-k} \tilde{\Psi}(L(1)v_4) \\
+ (-1)^k \sum_{j \geq 0} \tilde{\Psi}(L(j)v_3) \sum_{i \geq 0} \left(1-k \atop i\right) \left(i+j+k-1 \atop j+1\right) s^{i+j+k} \\
+ (-1)^k \left[\frac{s}{1+s}\right)^k - 1 \right] \mathcal{L}_w \tilde{\Psi} \\
+ (-1)^k \sum_{i \geq 0} \binom{k+i-1}{i+1} \tilde{\Psi}(L(i)v_2) + (-1)^k(N + \frac{1}{8}) \tilde{\Psi}
\]

and
\[
\tilde{\Psi}(L(-k)v_2) = \sum_{i \geq 0} \binom{k+i-2}{i} s^{-i} \tilde{\Psi}(L(k+i)v_4) \\
+ (-1)^k s^{k-1} \tilde{\Psi}(L(1)v_4) + (N + \frac{1}{8}) \tilde{\Psi} \\
+ (-1)^k \sum_{i \geq 0} \binom{k+i-1}{i+1} s^{k+i} \tilde{\Psi}(L(i)v_3) \\
- \sum_{i \geq 0} \binom{1-k}{i+1} \tilde{\Psi}(L(i)v_1) + \frac{1}{1+s}(-1)^k s^k - 1 \mathcal{L}_w \tilde{\Psi}.
\]

**Theorem 28.** (Rationality) For \( 1 \leq i \leq 4 \) let \( v_i \in \mathbf{V}_{n_i} \) be eigenvectors for \( L(0) \)
with \( L(0)v_i = wt(v_i)v_i = |v_i|v_i \). Suppose that \( n_i \in \{1,3\} \), \( n_4 = n_1 + n_2 + n_3 \mod 4 \), \( wt(v_i) = N_i + \Delta_{n_i} \) and \( N = N_1 + N_2 + N_3 - N_4 \). Then, after the substitution \( (z_2/z_1)^{1/2} = 2x/(1+x^2) \), the series
\[
\tilde{\Phi}(v_1, v_2, v_3, v_4; x) = (1-x^4)^{\frac{1}{4}} z_2^{N+\frac{1}{8}} G(v_1, v_2, v_3, v_4; z_1, z_2)
\]
converges absolutely in the domain \( |x| < \sqrt{3-2\sqrt{2}} \) to a rational function in the ring \( \mathcal{R}_x = \mathbb{C}[x, x^{-1}, (x^4-1)^{-1}] \).
PROOF. We proof the statement by induction on $M = N_1 + N_2 + N_3 + N_4$. The base case, when $N_i = 0$ for $1 \leq i \leq 4$, is given by Theorem 13. The result of Theorem 18 with $k > 0$ inductively reduces the general case to the case where $N_i = 0$, and with $k < 0$ it reduces further to the case where $N_3 = 0$ also. The two results of Theorem 26 with $k > 0$ further reduce one to the base case.

**Theorem 29.** For any $v_1, v_2, v_3 \in V_1$, $v_4 \in V_3$, we have

$$[\tilde{\Phi}]_0 \sim \frac{1}{x_\infty} B_\infty [\tilde{\Phi}]_\infty.$$

**Proof.** It suffices to prove this for homogeneous vectors $v_i$ with $wt(v_i) = N_i + \Delta_{n_i}$, where $v_i \in V_{n_i}$. We will prove this using Theorem 18, Theorem 26, and Lemma 19, by induction on $N_1 + N_2 + N_3 + N_4$. The base case, when all $N_i = 0$, has been established already. First note that since $wt(v_i) = wt(\theta(v_i))$, the $N$ in Theorems 18 and 26 is the same for each of the entries in the matrices $[\tilde{\Phi}]_0$ and $[\tilde{\Phi}]_\infty$. Also, $t = 4x_0^2/(1 + x_0^2)^2 = 4x_\infty^2/(1 + x_\infty^2)^2$, so the $t$ in Theorems 18 and 26 is the same whether $x$ is $x_0$ or $x_\infty$. First we will do the inductive step which reduces the weight of $v_4$. Assume the statement is true as stated for all choices of four vectors whose weights add up to be less than or equal to $N_1 + N_2 + N_3 + N_4$. We will show that it is then true with $v_4$ replaced by $L(-k)v_4$ for any $0 < k \in \mathbb{Z}$. We have

$$[\tilde{\Phi}(L(-k)v_4)]_0 =$$

$$[\tilde{\Phi}(L(k)v_3)]_0 - (N + \frac{1}{8})[\tilde{\Phi}]_0 + (1 - t^{-k}) \mathcal{L}_{x_0}[\tilde{\Phi}]_0$$

$$+ \sum_{i \geq 0} \left( \frac{k + 1}{i + 1} \right) \left( t^{i-k}[\tilde{\Phi}(L(i)v_1)]_0 + [\tilde{\Phi}(L(i)v_2)]_0 \right)$$

$$\sim \frac{1}{x_\infty} B_\infty [\tilde{\Phi}(L(k)v_3)]_\infty - (N + \frac{1}{8}) \frac{1}{x_\infty} B_\infty [\tilde{\Phi}]_\infty + (1 - t^{-k}) \mathcal{L}_{x_0} \frac{1}{x_\infty} B_\infty [\tilde{\Phi}]_\infty$$

$$+ \sum_{i \geq 0} \left( \frac{k + 1}{i + 1} \right) \frac{1}{x_\infty} B_\infty \left( t^{i-k}[\tilde{\Phi}(L(i)v_1)]_\infty + [\tilde{\Phi}(L(i)v_2)]_\infty \right)$$

$$= \frac{1}{x_\infty} B_\infty \left( \tilde{\Phi}(L(k)v_3)]_\infty - (N + \frac{1}{8})[\tilde{\Phi}]_\infty + (1 - t^{-k}) \mathcal{L}_{x_\infty} [\tilde{\Phi}]_\infty \right)$$

$$+ \frac{1}{x_\infty} B_\infty \sum_{i \geq 0} \left( \frac{k + 1}{i + 1} \right) \left( t^{i-k}[\tilde{\Phi}(L(i)v_1)]_\infty + [\tilde{\Phi}(L(i)v_2)]_\infty \right)$$

$$= \frac{1}{x_\infty} B_\infty [\tilde{\Phi}(L(-k)v_4)]_\infty.$$

But the same calculation with $0 > k \in \mathbb{Z}$ shows that the statement is also true with $v_3$ replaced by $L(k)v_3$.

Applying the two parts of Theorem 26 for $0 < k \in \mathbb{Z}$, one similarly gets that the statement is true with $v_i$ replaced by $L(-k)v_i$, for $i = 1, 2$. Lemma 19 plays a crucial role, giving

$$\mathcal{L}_{x_0} \frac{1}{x_\infty} [\tilde{\Phi}]_\infty = \frac{1}{x_\infty} \mathcal{L}_{x_\infty} [\tilde{\Phi}]_\infty.$$


Theorem 30. Let \( v_1, v_2, v_3 \in V_1 \) and \( v_4 \in V_3 \) with \( wt(v_i) = |v_i| = N_i + \Delta_{n_i} \) and \( N = N_1 + N_2 + N_3 - N_4 \). Then we have

\[
[\hat{\Phi}]_0 \sim \frac{t^N}{ix_1 + 1} B_i[\hat{\Phi}]_i \sim \frac{t^N}{ix_{i-1} + 1} B_{-i}[\hat{\Phi}]_{-i}.
\]

Proof. We will prove this using Theorem 18, Theorem 26, and Lemma 20, by induction on \( N_1 + N_2 + N_3 + N_4 \). The base case, when all \( N_i = 0 \), has been established already. Since \( wt(v_i) = wt(\theta(v_i)) \), the \( N \) in Theorems 18 and 26 is the same for each of the entries in the matrices \([\hat{\Phi}]_0\) and \([\hat{\Phi}]_{\pm 1}\). First we will do the inductive step which reduces the weight of \( v_4 \). Assume the statement is true as stated for all choices of four vectors whose weights add up to be less than or equal to \( N_1 + N_2 + N_3 + N_4 \). We will show that it is then true with \( v_4 \) replaced by \( L(-k)v_4 \) for any \( 0 < k \in \mathbb{Z} \). We have

\[
\begin{align*}
[\hat{\Phi}(L(-k)v_4)]_0 &= [\hat{\Phi}(L(k)v_3)]_0 - (N + \frac{1}{8})[\hat{\Phi}]_0 + (1 - t^{-k})L_{x_0}[\hat{\Phi}]_0 \\
&+ \sum_{i \geq 0} \binom{k + 1}{i + 1} \left( t^{i-k}[\hat{\Phi}(L(i)v_1)]_i + [\hat{\Phi}(L(i)v_2)]_i \right) \\
&\sim \frac{t^{N-k}}{ix_1 + 1} B_i[\hat{\Phi}(L(k)v_3)]_i - (N + \frac{1}{8}) \frac{t^N}{ix_1 + 1} B_i[\hat{\Phi}]_i + (1 - t^{-k})L_{x_0} \frac{t^N}{ix_1 + 1} B_i[\hat{\Phi}]_i \\
&+ \sum_{i \geq 0} \binom{k + 1}{i + 1} \left( t^{i-k}[\hat{\Phi}(L(i)v_1)]_i + [\hat{\Phi}(L(i)v_2)]_i \right) \\
&= \frac{t^{N-k}}{ix_1 + 1} B_i \left[ [\hat{\Phi}(L(k)v_3)]_i - (N + \frac{1}{8}) t^k[\hat{\Phi}]_i + (1 - t^{-k}) \left( -t^k(L_{x_1} - N - \frac{1}{8})[\hat{\Phi}]_i \right) \\
&+ \sum_{i \geq 0} \binom{k + 1}{i + 1} \left( [\hat{\Phi}(L(i)v_1)]_i + t^{k-i}[\hat{\Phi}(L(i)v_2)]_i \right) \right] \\
&= \frac{t^{N-k}}{ix_1 + 1} B_i \left[ [\hat{\Phi}(L(k)v_3)]_i + (1 - t^k)L_{x_1}[\hat{\Phi}]_i - (N + \frac{1}{8})[\hat{\Phi}]_i \\
&+ \sum_{i \geq 0} \binom{k + 1}{i + 1} \left( [\hat{\Phi}(L(i)v_1)]_i + t^{k-i}[\hat{\Phi}(L(i)v_2)]_i \right) \right] \\
&= \frac{t^{N-k}}{ix_1 + 1} B_i[\hat{\Phi}(L(-k)v_4)]_i.
\end{align*}
\]

In the last step we used Theorem 18 with \( v_1 \) and \( v_2 \) switched, \( z_1 \) and \( z_2 \) switched, and therefore, \( t \) replaced by \( t^{-1} \). The same calculation with \( 0 > k \in \mathbb{Z} \) shows that the statement is also true with \( v_3 \) replaced by \( L(k)v_3 \).

We now apply the two parts of Theorem 26 for \( 0 < k \in \mathbb{Z} \) to get that the statement is true with \( v_i \) replaced by \( L(-k)v_i \), for \( i = 1, 2 \). Lemma 20 plays a
crucial role. We have

\[
[\tilde{\Phi}(L(-k)v_1)]_0 \\
= \sum_{i \geq 0} \binom{k + i - 2}{i} t^{-i}[\tilde{\Phi}(L(k + i)v_4)]_0 \\
+ (-1)^k (N + \frac{1}{k}) t^{k-1}[1 - (1 - t)^{1-k}][\tilde{\Phi}]_0 \\
+ (-1)^k t^{k-1}(1 - t)[(1 - t)^{-k} - 1]|\mathcal{L}_{\rho_0}[\tilde{\Phi}]_0 \\
+ (-1)^k \sum_{j \geq 0} (-1)^{j+1} \binom{1 - k}{j + 1} \left( \frac{t}{1-t} \right)^{j+k} [\tilde{\Phi}(L(j)v_2)]_0 \\
+ (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} t^{k+i}[\tilde{\Phi}(L(i)v_3)]_0 + (-1)^k t^{k-1}[\tilde{\Phi}(L(1)v_4)]_0
\]
\[
\sim \sum_{i \geq 0} \binom{k + i - 2}{i} t^{-i} \frac{t^{N+k+i}}{i!_x + 1} B_i[\tilde{\Phi}(L(k + i)v_4)]_i \\
+ (-1)^k (N + \frac{1}{8}) t^{k-1} (1 - (1 - t)^{1-k}) \frac{t^N}{i!_x + 1} B_i[\tilde{\Phi}]_i \\
+ (-1)^k t^{k-1} (1 - t) (1 - t)^{-k - 1} \mathcal{L}_{x_0} \frac{t^N}{i!_x + 1} B_i[\tilde{\Phi}]_i \\
+ (-1)^k \sum_{j \geq 0} (-1)^{j+1} \binom{1 - k}{j + 1} \left( \frac{t}{1 - t} \right)^{j+k} \frac{t^{N-j}}{i!_x + 1} B_i[\tilde{\Phi}(L(j)v_2)]_i \\
+ (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} t^{N-i} \frac{t^{N-i}}{i!_x + 1} B_i[\tilde{\Phi}(L(i)v_3)]_i \\
+ (-1)^k \frac{t^{N+1}}{i!_x + 1} B_i[\tilde{\Phi}(L(v_4))]_i \\
= \sum_{i \geq 0} \binom{k + i - 2}{i} t^{-i} \frac{t^{N+k+i}}{i!_x + 1} B_i[\tilde{\Phi}(L(k + i)v_4)]_i \\
+ (-1)^k (N + \frac{1}{8}) t^{k-1} (1 - (1 - t)^{1-k}) \frac{t^N}{i!_x + 1} B_i[\tilde{\Phi}]_i \\
+ (-1)^k t^{k-1} (1 - t) (1 - t)^{-k - 1} \left[ \frac{-t^N}{i!_x + 1} B_i(\mathcal{L}_{x_1} - N - \frac{1}{8}) \right] [\tilde{\Phi}]_i \\
+ (-1)^k \sum_{j \geq 0} (-1)^{j+1} \binom{1 - k}{j + 1} (1 - t)^{-j-k} \frac{t^{N+k}}{i!_x + 1} B_i[\tilde{\Phi}(L(j)v_2)]_i \\
+ (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} \frac{t^{N+k}}{i!_x + 1} B_i[\tilde{\Phi}(L(i)v_3)]_i + (-1)^k \frac{t^{N+k}}{i!_x + 1} B_i[\tilde{\Phi}(L(v_4))]_i \\
= \frac{t^{N+k}}{i!_x + 1} B_i \left[ \sum_{i \geq 0} \binom{k + i - 2}{i} [\tilde{\Phi}(L(k + i)v_4)]_i \right] \\
+ (-1)^k (N + \frac{1}{8}) t^{-1} (1 - (1 - t)^{1-k}) [\tilde{\Phi}]_i \\
- (-1)^k t^{-1} (1 - t) (1 - t)^{-k - 1} (\mathcal{L}_{x_1} - N - \frac{1}{8}) [\tilde{\Phi}]_i \\
+ (-1)^k \sum_{j \geq 0} (-1)^{j+1} \binom{1 - k}{j + 1} (1 - t)^{-j-k} [\tilde{\Phi}(L(j)v_2)]_i \\
+ (-1)^k \sum_{i \geq 0} \binom{k + i - 1}{i + 1} [\tilde{\Phi}(L(i)v_3)]_i + (-1)^k [\tilde{\Phi}(L(v_4))]_i \\
= \frac{t^{N+k}}{i!_x + 1} B_i \left[ \sum_{i \geq 0} \binom{k + i - 2}{i} [\tilde{\Phi}(L(k + i)v_4)]_i \right] \\
+ (-1)^k (N + \frac{1}{8}) [\tilde{\Phi}]_i + \left[ t^{-k} (1 - t)^{-k} - (-1)^k (1 - t^{-1}) \mathcal{L}_{x_1} [\tilde{\Phi}]_i \\
+ \sum_{j \geq 0} (-1)^j [\tilde{\Phi}(L(j)v_2)]_i \sum_{i \geq 0} \binom{1 - k}{i} \binom{i + j + k - 1}{j + 1} t^{i-j-k} \right]
\]
\[
(\Phi(L(i)v_3)]_i + (-1)^k \Phi(L(1)v_4))_i \]
\[
= \frac{t^{N+k}}{L_1} B_1 [\Phi(L(-k)v_1)]_i.
\]

In the last step we used the second part of Theorem 26 with \(v_1\) and \(v_2\) switched, \(z_1\) and \(z_2\) switched, and therefore, \(t\) replaced by \(t^{-1}\).

The calculation for \([\Phi(L(-k)v_2)]_0\) is similar, completing the inductive proof of the first part of the theorem. The second part, with \(x_{-i}\) in place of \(x_1\), \(B_{-i}\) in place of \(B_1\), and certain sign changes, is proved in exactly the same way.

\textbf{Theorem 31.} Let \(v_1, v_2, v_3 \in V_1\) and \(v_4 \in V_3\) with \(wt(v_i) = |v_i| = N_i + \Delta_n\), and \(N = N_1 + N_2 + N_3 - N_4\). Then we have

\[
[\Phi]_0 \sim \frac{s^{-N}}{-x_1 + 1} B_1 [\Psi]_1 \sim \frac{s^{-N}}{x_1 - 1} B_{-1} [\Psi]_{-1}.
\]

\textbf{Proof.} We will prove this using Theorems 18, 22, 27, and Lemma 21, by induction on \(N_1 + N_2 + N_3 - N_4\). The base case, when all \(N_i = 0\), has been established already. First note that since \(wt(v_i) = wt(\theta(v_i))\), the \(N\) in Theorems 18 and 27 is the same for each of the entries in the matrices \([\Phi]_0\) and \([\Psi]_{\pm 1}\). First we will do the inductive step which reduces the weight of \(v_4\). Assume the statement is true as stated for all choices of four vectors whose weights add up to be less than or equal to \(N_1 + N_2 + N_3 + N_4\). We will show that it is then true with \(v_4\) replaced by \(L(-k)v_4\) for any \(0 < k \in \mathbb{Z}\). We have

\[
[\Phi(L(-k)v_4)]_0 = [\Phi(L(k)v_3)]_0 - (N + \frac{1}{8})[\Phi]_0 + (1 - t^{-k}) L_{x_0} [\Phi]_0
\]
\[
+ \sum_{i \geq 0} \binom{k + 1}{i} \left( t^{-k} \Phi(L(i)v_1)]_0 + [\Phi(L(i)v_2)]_0 \right)
\]
\[
\sim \frac{s^{-N+k}}{-x_1 + 1} B_1 [\Psi(L(k)v_3)]_1 - (N + \frac{1}{8}) \frac{s^{-N}}{-x_1 + 1} B_1 [\Psi]_1
\]
\[
+ (1 - t^{-k}) L_{x_0} \frac{s^{-N}}{-x_1 + 1} B_1 [\Psi]_1
\]
\[
+ \sum_{i \geq 0} \binom{k + 1}{i} \frac{s^{-N+i}}{-x_1 + 1} B_1 \left( t^{-k} [\Psi(L(i)v_1)]_1 + [\Psi(L(i)v_2)]_1 \right)
\]
\[
= \frac{s^{-N+k}}{-x_1 + 1} B_1 \left( [\Psi(L(k)v_3)]_1 - (N + \frac{1}{8}) s^{-k} [\Psi]_1 - (1 - t^{-k}) s^{-k} (s^{-1} L_{x_1} - (N + \frac{1}{8})(1 + s^{-1})) [\Psi]_1
\]
\[
+ \sum_{i \geq 0} \binom{k + 1}{i} \left( \left( \frac{s + 1}{s} \right)^{k-i} [\Psi(L(i)v_1)]_1 + s^{-k} [\Psi(L(i)v_2)]_1 \right)
\]
\[
\begin{align*}
&= s^{-N+k} \frac{B_1}{-x_1 + 1} \left[ \tilde{\Psi}(L(k)v_3)_1 - (N + \frac{1}{s})s^{-k}[\tilde{\Psi}]_1 + ((1 + s)^k - 1)s^{-k-1}L_{x_1}[\tilde{\Psi}]_1 \\
&\quad + (1 - (1 + s)^k)s^{-k}(1 + s^{-1})(N + \frac{1}{s})[\tilde{\Psi}]_1 \\
&\quad + \sum_{i \geq 0} \binom{k + 1}{i + 1} \left[ \left( \frac{s + 1}{s} \right)^{k-i} [\tilde{\Psi}(L(i)v_1)_1] + s^{i-k}[\tilde{\Psi}(L(i)v_2)_1] \right] \right] \\
&= s^{-N+k} \frac{B_1}{-x_1 + 1} \left[ \tilde{\Psi}(L(k)v_3)_1 - (N + \frac{1}{s})s^{-k-1}((1 + s)^{k+1} - 1)[\tilde{\Psi}]_1 \\
&\quad + s^{-k-1}((1 + s)^k - 1)L_{x_1}[\tilde{\Psi}]_1 \\
&\quad + \sum_{i \geq 0} \binom{k + 1}{i + 1} \left[ \left( \frac{s + 1}{s} \right)^{k-i} [\tilde{\Psi}(L(i)v_1)_1] + s^{i-k}[\tilde{\Psi}(L(i)v_2)_1] \right] \right] \\
&= s^{-N+k} \frac{B_1}{-x_1 + 1} [\tilde{\Psi}(L(-k)v_4)_1] \\
\end{align*}
\]

We used Theorem 22 in the last step.

The same calculation with \(0 > k \in \mathbb{Z}\) shows that the statement is also true with \(v_3\) replaced by \(L(k)v_3\).

Applying the two parts of Theorem 27 for \(0 < k \in \mathbb{Z}\), one similarly gets that the statement is true with \(v_i\) replaced by \(L(-k)v_i\), for \(i = 1, 2\). Lemma 21 plays a crucial role.

We are, at last, ready to state the new “matrix” Jacobi-Cauchy Identity which is valid for the \(c = \frac{1}{2}\) minimal model. This is the main objective of this paper, but considerable further work remains to be done in order to understand other minimal models and the WZW models. That will be the subject of future investigations.

**Theorem 32.** *(Matrix Jacobi-Cauchy Identity)* Let \(v_1, v_2, v_3 \in V_1\) and \(v_4 \in V_3\) with \(w(t) = \|v_i\| = N_i + \Delta_{n_i}\) and \(N = N_1 + N_2 + N_3 - N_4\). Let \(f(x)\) be any function in \(R_x\). Let \(C_0\) be a small positively oriented circle with center \(x_0 = 0\) and for \(\alpha \in \{\infty, 1, -1, i, -i\}\) let \(C_{\alpha}\) be the circle obtained from \(C_0\) by the appropriate Möbius transformation sending \(0\) to \(\alpha\). Then we have

\[
0 = \oint_{C_0} |\Phi|_1 f(x_0) dx_0 \\
+ \oint_{C_{\infty}} \frac{-1}{x_{\infty}^3} B_{\infty} |\tilde{\Phi}|_1 f(1/x_{\infty}) dx_{\infty} \\
+ \oint_{C_1} \frac{2t^N}{(1x_1 + 1)^3} B_1 |\tilde{\Phi}|_1 f \left( \frac{x_1 + 1}{1x_1 + 1} \right) dx_1 \\
+ \oint_{C_{-1}} \frac{2t^N}{(1x_{-1} + 1)^3} B_{-1} |\tilde{\Phi}|_1 f \left( \frac{-x_{-1} + 1}{1x_{-1} + 1} \right) dx_{-1} \\
+ \oint_{C_1} \frac{2s^{-N}}{(1x_1 + 1)^3} B_1 |\tilde{\Phi}|_1 f \left( \frac{x_1 + 1}{-x_1 + 1} \right) dx_1 \\
+ \oint_{C_{-1}} \frac{2s^{-N}}{(1x_{-1} + 1)^3} B_{-1} |\tilde{\Phi}|_1 f \left( \frac{-x_{-1} + 1}{x_{-1} + 1} \right) dx_{-1}.
\]
PROOF. Apply the Cauchy residue theorem to $f(x)$ times the globally defined matrix valued function $G(x)$ to which each of the expressions in Theorems 29 - 31 converge. It says that the sum of the residues at the six possible poles is zero, that is,

$$0 = \sum_{\alpha} \oint_{C_{\alpha}} G(x_0)f(x_0)dx_0.$$ 

Let $$x_0 = \mu_\alpha(x_\alpha) = \frac{a_\alpha x_\alpha + b_\alpha}{c_\alpha x_\alpha + d_\alpha}$$
denote the Möbius transformation chosen before Theorem 13 to relate $x_0$ to $x_\alpha$. Then the chain rule gives $dx_0 = \frac{a_\alpha dx_\alpha - b_\alpha c_\alpha}{(c_\alpha x_\alpha + d_\alpha)^2} dx_\alpha$. For each $\alpha$ we write the corresponding integral with $G(x_0)f(x_0)$ represented by the series in $x_\alpha$ which converges to it in the neighborhood of $x_0 = \alpha$, and we write $dx_0$ as the appropriate chain rule factor times $dx_\alpha$. \[\blacksquare\]

Just as Corollary 3 was obtained from Theorem 2, we can obtain infinitely many explicit identities for products of components of intertwining operators from Theorem 32 by making explicit choices for the test function $f(x)$. One computes the integral in each term of the Matrix Jacobi-Cauchy Identity (MJCI) by expanding the integrand as a series in the local variable $x_\alpha$, and then finding the residue as the coefficient of $x_\alpha^{-1}$. The algebra involved is tedious but straightforward, so we will not present it here. The most general function $f(x) \in R_x$ is a linear combination of functions of the form

$$f(x) = x^{m_0}(1 + ix)^{m_1}(1 - ix)^{m_2}(1 + x)^{m_3}(1 + x)^{m_4}$$

where $m_0, m_1, m_2, m_3, m_4 \in \mathbb{Z}$ are five independent parameters. Since the MJCI is linear in $f(x)$, it suffices to compute the identity just for $f(x)$ of that form. In fact, using a few simple combinatorial identities, there is a considerable simplification of the result if we restrict $f(x)$ to be a rational function of the variable $t$, say $t^r(1 - t)^s$. This seems a natural restriction because the correlation functions made from intertwining operators were defined from series in $z_1$ and $z_2$ which could be written in terms of $t$. Only later did we have to express them in terms of the local variables $x_\alpha$ in order to use properties of the hypergeometric functions to relate the functions at the six poles. It makes the local variables seem like a necessary but artificial technical construction, and one might think that the final answer should reflect the fact that there were only three possible poles in the $t$-plane. This may not be the last word on that subject, but our results seem to show that with that restriction on $f$ there are six terms in the MJCI, but the second row of the matrix yields a trivial identity. We find a slightly simpler result if we restrict the test function to be of the form $f(x) = x^2 t^r(1 - t)^s$. We give the results in the next three corollaries.

If we were to write out each entry of each $2 \times 4$ matrix in the identity, then the result would not fit across the page, and the pattern would be very similar in each column. So we will just show the first column of the answer in Corollary 33. The other columns are easily obtained from the first one by modifying the pattern of vectors $v_1, v_2, v_3, v_4$ in the first row and $\theta v_1, \theta v_2, v_3, v_4$ in the second row, as shown in the matrices $[\tilde{\Phi}]_\alpha$ and $[\tilde{\Psi}]_\alpha$ defined before Theorem 18. In Corollaries 34 and 35, since the second row of the matrix yields a trivial identity, we only give the identity coming from the first row.
Corollary 33. Let $v_1, v_2, v_3 \in V_1$ and $v_4 \in V_3$ with $wt(v_i) = |v_i| = N_i + \Delta_{n_i}$ and $N = N_1 + N_2 + N_3 - N_4$. Let

$$f(x) = x^{m_0}(1 + lx)^{m_1}(1 - lx)^{m_2}(1 - x)^{m_3}(1 + x)^{m_4}$$

for $m_0, m_1, m_2, m_3, m_4 \in \mathbb{Z}$, and let $m = m_0 + m_1 + m_2 + m_3 + m_4$. Define the following constants in terms of those parameters:

$$A_{\infty} = (-1)^{m_1+m_3+1}(i)^{m_2+m_4},$$
$$A_i = 2^{m_1+m_3+1}(i)^{m_0+m_1}(1+i)^{m_2+m_3},$$
$$A_{i-1} = 2^{m_1+m_3+1}(i)^{m_0+m_1}(1+i)^{m_2+m_3},$$
$$A_{-1} = 2^{m_1+m_3+1}(i)^{m_0+m_1}(1+i)^{m_2+m_3},$$

and for each $k \geq 0$ define

$$Q_k = 2(k + N_1 - N_4), \quad R_k = 2(k - N_1 - N_3), \quad S_k = 2(k - N_1 - N_2).$$

In the following formula, for each $k \geq 0$, and for each $\alpha \in \{0, \infty, i, -i, 1, -1\}$, $\sum_{\alpha}$ and $\sum_{\alpha}$ denote summations over all integers $p_1, p_1, p_1, p_1, p^{-1} \geq 0$ such that the sum $p_1 + p_1 + p_1 + p^{-1}$ equals a fixed value, $p_1$, depending on $k$ and some of the given parameters. The fixed values are as follows. For $\sum_0$, $p = m_0 - 2 - Q_k$, for $\sum_{0}$, $p = m_0 - 2 - Q_k$, for $\sum_{\infty}$, $p = m_1 + 2 - Q_k$, for $\sum_{i}$, $p = m_1 + 2 - Q_k$, for $\sum_{i-1}$, $p = m_1 + 2 - Q_k$, for $\sum_{i}$, $p = m_1 + 2 - Q_k$, for $\sum_{i+1}$, $p = m_1 + 2 - Q_k$, for $\sum_{i+1}$, $p = m_1 + 2 - Q_k$, for $\sum_{i+1}$, $p = m_1 + 2 - Q_k$, for $\sum_{0}$, $p = m_2 - 2 - Q_k$, for $\sum_{0}$, $p = m_2 - 2 - Q_k$, for $\sum_{\infty}$, $p = m_1 + 2 - Q_k$, for $\sum_{i}$, $p = m_1 + 2 - Q_k$, for $\sum_{i}$, $p = m_1 + 2 - Q_k$, for $\sum_{i+1}$, $p = m_2 - 2 - Q_k$, for $\sum_{i+1}$, $p = m_2 - 2 - Q_k$, and for $\sum_{i+1}$, $p = m_2 - 2 - Q_k$. Within the summations we use the notations

$$C_1 = \left( \frac{1}{p_1} + m_1 \right), \quad C_{-1} = \left( \frac{1}{p_1} + m_1 \right), \quad C_i = \left( \frac{1}{p_1} + m_1 \right), \quad C_{-i} = \left( \frac{1}{p_1} + m_1 \right),$$

and

$$D = (-1)^{p_1+p_{i-1}}(i)^{p_1+p_{i-1}}.$$
Then we have the identity

\[ 0 = \sum_{0 \leq k \in \mathbb{Z}} (2^{Q_k}) \left[ \sum_{i} C_{i} C_{-i} \left( \frac{1}{4} + m_{i} - Q_{k}^{-1} \right) \left( \frac{1}{4} + m_{-i} - Q_{k}^{-1} \right) D2\Phi_{k}^{\ast} \right] \]

\[ + 2^{Q_k} A_{\infty} B_{\infty} \left[ \sum_{i} C_{i} C_{-i} \left( \frac{1}{4} + m_{i} - Q_{k}^{-1} \right) \left( \frac{1}{4} + m_{0} - R_{k}^{-1} \right) D2\Phi_{k}^{\ast} \right] \]

\[ + 2^{R_k} A_{-i} B_{i} \left[ \sum_{i} C_{i} C_{-i} \left( \frac{1}{4} + m_{i} - R_{k}^{-4} \right) \left( \frac{1}{4} + m_{0} - R_{k}^{-1} \right) D2\Phi_{k}^{\ast} \right] \]

\[ + 2^{R_k} A_{-i} B_{i} \left[ \sum_{i} C_{i} C_{-i} \left( \frac{1}{4} + m_{i} - S_{k}^{-4} \right) \left( \frac{1}{4} + m_{0} - S_{k}^{-1} \right) D\Psi_{k} \right] \]

\[ + 2^{S_k} A_{i} B_{1} \left[ \sum_{i} C_{i} C_{-i} \left( \frac{1}{4} + m_{i} - S_{k}^{-4} \right) \left( \frac{1}{4} + m_{0} - S_{k}^{-1} \right) D\Psi_{k} \right] \]

\[ + 2^{S_k} A_{-i} B_{1} \left[ \sum_{i} C_{i} C_{-i} \left( \frac{1}{4} + m_{i} - S_{k}^{-4} \right) \left( \frac{1}{4} + m_{0} - S_{k}^{-1} \right) D\Psi_{k} \right] . \]

**Corollary 34.** Let \( v_1, v_2, v_4 \in \mathbf{V}_1 \) and \( v_4 \in \mathbf{V}_3 \) with \( \text{wt}(v_i) = |v_i| = N_i + \Delta_{n_i} \) and \( N = N_1 + N_2 + N_3 - N_4 \). For any \( r, s \in \mathbb{Z} \), define

\[ a = \frac{1}{4} + 2r - 4, \quad b = r + s - 1, \quad c = -s - 1. \]
With notation as in Corollary 33, for any \( r, s \in \mathbb{Z} \), we have

\[
0 = 2^{2r+2(N_1-N_4)} \sum_{0 \leq k \in \mathbb{Z}} 2^{-2k} \Phi_k \sum_{0 \leq q \in \mathbb{Z}} \left( \frac{1}{4} + 2s \right) \left( \frac{1}{4} - 2(r + s) - Q_k - 1 \right) (-1)^q
\]

\[
- 2^{2r+2(N_1-N_4)} \sum_{0 \leq k \in \mathbb{Z}} 2^{-2k} \Phi_k^\theta \sum_{0 \leq q \in \mathbb{Z}} \left( \frac{1}{4} + 2s \right) \left( \frac{1}{4} - 2(r + s) - Q_k \right) (-1)^q
\]

\[
+ (-1)^s 2^{-2b-2(N_1+N_3)} \sum_{0 \leq k \in \mathbb{Z}} 2^{-2k} \Phi_k^*. \]

\[
\sum_{0 \leq q \in \mathbb{Z}} \left( \frac{1}{4} + 2s \right) \left( \frac{a - R_k}{b - R_k/2 - q} \right) \left( \frac{a - R_k}{b - R_k/2 - 1 - q} \right) (-1)^q
\]

\[
- (-1)^s 2^{-2b-2(N_1+N_3)} \sum_{0 \leq k \in \mathbb{Z}} 2^{-2k} \Phi_k^* \cdot \]

\[
\sum_{0 \leq q \in \mathbb{Z}} \left( \frac{1}{4} - 2(r + s) \right) \left( \frac{a - S_k}{q - 1} \right) (-1)^q
\]

\[
- 2^{-2c-2(N_1+N_2)} \sum_{0 \leq k \in \mathbb{Z}} 2^{-2k} \Psi_k \cdot \]

\[
\sum_{0 \leq q \in \mathbb{Z}} \left( \frac{1}{4} - 2(r + s) \right) \left( \frac{a - S_k}{q - 1} \right) (-1)^q.
\]

**Corollary 35.** Let \( v_1, v_2, v_3 \in \mathbf{V}_1 \) and \( v_4 \in \mathbf{V}_3 \) with \( \text{wt}(v_i) = |v_i| = N_i + \Delta_n \), \( N = N_1 + N_2 + N_3 - N_4 \) and \( \Gamma = N_1 + N_2 + N_3 + N_4 \). With notation as in Corollary 33, for any \( r, s \in \mathbb{Z} \), we have

\[
\sum_{0 \leq k \in \mathbb{Z}} 2^{-2k} \sum_{0 \leq q \leq k} \left( \frac{1}{4} + 2r + 2(N_1 + N_2) \right) (-1)^q.
\]

\[
\left[ \left( \frac{1}{4} - 2r + S_k - 1 \right) \Phi_{r+s+\Gamma-k} + (-1)^r N_1 + N_2 + 1 \Phi_{s-1-k} \right]
\]

\[
- \left( \frac{1}{4} - 2r + S_k \right) \Phi_{r+s+\Gamma-k} + (-1)^r N_1 + N_2 + 1 \Phi_{s-1-k} \right]
\]

\[
= \sum_{0 \leq k \in \mathbb{Z}} 2^{-2k} \sum_{0 \leq q \leq k} \left( \frac{1}{4} + 2s + 2(N_1 + N_3) \right) (-1)^q.
\]

\[
\left[ \left( \frac{1}{4} - 2s + R_k \right) \Psi_{r-1-k} - \left( \frac{1}{4} - 2s + R_k - 1 \right) \Psi_{r-1-k} \right].
\]
### Spinor Construction of the $c = 1/2$ Minimal Model

| $n_1 = 1$ | $n_2 = 1$ | $n_1 = 3$ | $n_2 = 3$ |
|-----------|-----------|-----------|-----------|
| $n_3$ | 0 | 1 | 2 | 3 | 0 | 1 | 2 | 3 |
| $a$ | 0 | $\frac{5}{4}$ | 0 | $\frac{1}{4}$ | $a$ | 0 | $\frac{1}{4}$ | 0 | $\frac{5}{4}$ |
| $b$ | 1 | $\frac{3}{4}$ | $\frac{3}{4}$ | $\frac{1}{4}$ | $b$ | 1 | $\frac{3}{4}$ | $\frac{3}{4}$ | $\frac{1}{4}$ |
| $c$ | 0 | $\frac{3}{2}$ | $\frac{1}{3}$ | $\frac{1}{2}$ | $c$ | 0 | $\frac{1}{2}$ | $\frac{1}{3}$ | $\frac{3}{2}$ |
| $a'$ | 0 | $\frac{3}{4}$ | 0 | $\frac{1}{4}$ | $a'$ | 0 | $\frac{1}{4}$ | 0 | $\frac{3}{4}$ |
| $b'$ | 1 | $\frac{3}{4}$ | $\frac{2}{3}$ | $\frac{3}{4}$ | $b'$ | 1 | $\frac{3}{4}$ | $\frac{2}{3}$ | $\frac{3}{4}$ |
| $c'$ | 2 | $\frac{3}{4}$ | $\frac{3}{4}$ | $\frac{3}{4}$ | $c'$ | 2 | $\frac{3}{4}$ | $\frac{3}{4}$ | $\frac{3}{4}$ |
| $A$ | $\frac{3}{8}$ | $\frac{1}{2}$ | $\frac{1}{8}$ | 0 | $A$ | $\frac{3}{8}$ | 0 | $\frac{1}{8}$ | $\frac{1}{2}$ |
| $B$ | 0 | $\frac{3}{8}$ | $\frac{1}{3}$ | $\frac{1}{8}$ | $B$ | 0 | $\frac{1}{2}$ | $\frac{1}{3}$ | $\frac{1}{8}$ |
| $C$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $C$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ |
| $A'$ | 0 | $\frac{1}{2}$ | $\frac{1}{2}$ | $\frac{1}{2}$ | $A'$ | 0 | $\frac{1}{2}$ | 1 | $\frac{1}{2}$ |
| $B'$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $B'$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ |
| $C'$ | 0 | $\frac{3}{8}$ | $\frac{3}{8}$ | $\frac{3}{8}$ | $C'$ | 0 | $\frac{1}{8}$ | $\frac{1}{2}$ | $\frac{3}{8}$ |

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DEPT. OF MATH. SCI., THE STATE UNIVERSITY OF NEW YORK, BINGHAMTON, NEW YORK 13902-6000

MATH. DEPT., EAST CAROLINA UNIVERSITY, GREENVILLE, NORTH CAROLINA 27858-4353

MATH. DEPT., BROOME COMMUNITY COLLEGE, BINGHAMTON, NEW YORK 13902-1017