ISS ESTIMATES IN THE SPATIAL SUP-NORM FOR NONLINEAR 1-D PARABOLIC PDES

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Abstract. This paper provides novel Input-to-State Stability (ISS)-style maximum principle estimates for classical solutions of nonlinear 1-D parabolic Partial Differential Equations (PDEs). The derivation of the ISS-style maximum principle estimates is performed in two ways: by using an ISS Lyapunov Functional for the sup norm and by exploiting well-known maximum principles. The estimates provide fading memory ISS estimates in the sup norm of the state with respect to distributed and boundary inputs. The obtained results can handle parabolic PDEs with nonlinear and non-local in-domain terms/boundary conditions. Three illustrative examples show the efficiency of the proposed methodology for the derivation of ISS estimates in the sup norm of the state.

2020 Mathematics Subject Classification. 35K10,93D20,93C20.

May 19, 2021.

1. Introduction

Rapid progress in the development of Input-to-State Stability (ISS) theory for systems modeled by Partial Differential Equations (PDEs) took place during the last decade (see for instance [3,7,8,9,12,14,16,20,21,22,28,29,30]). Researchers dealt with the two major problems that arise in the study of PDEs with inputs and do not appear in the study of finite-dimensional systems or delay systems: (i) the selection of the state norm (functional norms are not equivalent), and (ii) the presence of boundary inputs (the boundary inputs enter through unbounded operators). Many methodologies have been used for the derivation of ISS estimates (Lyapunov functionals, spectral methods, semigroup methods, etc.). The development of ISS theory for PDEs has produced novel results which can be used for various purposes in control theory and practice. ISS theory for PDEs has been used for the stability analysis of coupled PDEs (see [3,16]), for feedback design purposes in linear and semilinear PDEs (see [13,15,26]) and for observer design purposes (see [17]) for various infinite-dimensional systems.

Although the sup norm is the most useful norm (because it can provide point-wise estimates), there are few ISS estimates in the literature for the sup norm of the solution of parabolic PDEs. The scarcity of ISS estimates in the state sup norm is justified by the absence of ISS Lyapunov functionals which are related to the sup norm. ISS estimates in the sup norm were provided in the work [12], where numerical approximations of the solution of a linear 1-D parabolic PDE were exploited. The methodology was later generalized in [16] by introducing the notion of an ISS Lyapunov functional under discretization. Input-to-Output Stability (IOS) estimates for the

Keywords and phrases: ISS, parabolic PDEs, maximum principles, boundary disturbances.

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state sup norm were provided for certain semilinear parabolic PDEs in [28]. Indeed, in [28] the state sup norm was estimated by using the $H^1(0, 1)$ norm of the initial condition and consequently, the provided estimates were IOS estimates with output map being the state in the space $L^\infty(0, 1)$ while the state space was the Sobolev space $H^1(0, 1)$. ISS estimates of the $H^1(0, 1)$ norm of the state for certain linear 1-D parabolic PDEs were also provided in [14]. These estimates can be used for the derivation of estimates of the sup norm by using auxiliary tools (e.g., Agmon’s inequality).

The present work provides ISS estimates in the sup norm for nonlinear and non-local 1-D parabolic PDEs by using a completely different methodology than the methodology used in [12,16]. Instead of exploiting numerical approximations of the solution of the PDE problem, here we construct an ISS Lyapunov functional for the sup norm. To that purpose, we consider classical solutions of the 1-D parabolic PDE (as in [12,16] but less regular approximations of the solution of the PDE problem, here we construct an ISS Lyapunov functional using a completely different methodology than the methodology used in [12,16]. Instead of exploiting numerical tools (e.g., Agmon’s inequality).

The structure of the paper is as follows. Section 2 contains the statements of the results of the paper that can be proved by means of an ISS Lyapunov functional procedure (Theorem 2.1, Theorem 2.2 and Corollary 2.3). The results are used in Section 3 in three (carefully chosen) illustrative examples, which show how easily the main results can be applied to nonlinear parabolic PDEs. The statements of the results that can be proved by using maximum principles (Theorem 4.1 and Theorem 4.2) are given in Section 4 and a detailed comparison with Theorem 2.1 and Theorem 2.2 is also performed. The proofs of all results are provided in Section 5, where some interesting auxiliary results are also stated and proved. Section 6 gives the concluding remarks of the present work.

Notation. Throughout this paper, we adopt the following notation.

* Let $U \subseteq \mathbb{R}^n$ be a set with non-empty interior and let $\Omega \subseteq \mathbb{R}$ be a set. By $C^0(U; \Omega)$, we denote the class of continuous mappings on $U$, which take values in $\Omega$. By $C^k(U; \Omega)$, where $k \geq 1$, we denote the class of continuous functions on $U$, which have continuous derivatives of order $k$ on $U$ and take values in $\Omega$. When $\Omega \subseteq \mathbb{R}$ is not explicitly given, i.e., when we write $C^k(U)$, we mean that $\Omega = \mathbb{R}$. For $\eta \in C^1([0, 1])$, $\eta'(x)$ denotes the derivative with respect to $x \in [0, 1]$.

* $\mathbb{R}_+$ denotes the set of non-negative real numbers. A function $\rho : \mathbb{R}_+ \to \mathbb{R}_+$ is said to be positive definite if $\rho(s) > 0$ for all $s > 0$ and $\rho(0) = 0$. A positive definite function $\rho \in C^0(\mathbb{R}_+; \mathbb{R}_+)$ is said to be a function of class $K_\infty$ if $\rho$ is increasing with $\rho(\mathbb{R}_+) = \mathbb{R}_+$. The sign function $\text{sgn}(x)$ is defined by $\text{sgn}(x) = x/|x|$ for $x \neq 0$ and $\text{sgn}(0) = 0$. 

Let $u \in C^0(I \times [0,1])$ be given, where $I \subseteq \mathbb{R}$ is an interval. We use the notation $u[t]$ to denote the profile at certain $t \in I$, i.e., $(u[t])(x) = u(t,x)$ for all $x \in [0,1]$. $L^\infty(0,1)$ denotes the set of equivalence classes of Lebesgue measurable functions $f : [0,1] \to \mathbb{R}$ for which $\|f\|_\infty = \text{ess sup}_{x \in (0,1)} |f(x)| < +\infty$.

2. ISS in the Spatial Sup-Norm

Our first main result provides an estimate of a weighted sup norm of the solution of a PDE with space and time-varying coefficients. The estimate depends only on the initial condition, the distributed perturbation term that may be present in the PDE and the boundary values of the solution.

**Theorem 2.1:** Let $T > 0$, $a,b,c : (0,T) \times (0,1) \to \mathbb{R}$, $f : (0,T) \times (0,1) \to \mathbb{R}$ with $\sup_{0<t<1,0<x<T} (|f(t,x)|) < +\infty$ be given. Let $u \in C^0([0,T] \times [0,1])$ be a given function with $u[t] \in C^2((0,1))$ for almost all $t \in (0,T)$, for which the derivative $\frac{\partial u}{\partial t}(t,x)$ is a continuous function on $(0,T) \times [0,1]$ and satisfies the equation

$$\frac{\partial u}{\partial t}(t,x) = a(t,x)\frac{\partial^2 u}{\partial x^2}(t,x) + b(t,x)\frac{\partial u}{\partial x}(t,x) + c(t,x)u(t,x) + f(t,x),$$

for almost all $t \in (0,T)$ and for all $x \in (0,1)$ (2.1)

Suppose that

$$a(t,x) \geq 0,$$  

for all $t \in (0,T)$, $x \in (0,1)$ (2.2)

and that there exist a constant $\sigma > 0$ and a positive function $\eta \in C^2([0,1];(0, +\infty))$ such that

$$a(t,x)\eta''(x) + b(t,x)\eta'(x) + (\sigma + c(t,x))\eta(x) \leq 0,$$  

for all $t \in (0,T)$, $x \in (0,1)$ (2.3)

Then the following estimate holds for all $\zeta \in [0,\sigma)$ and $t \in (0,T]$:

$$\|u[t]\|_{\infty,\eta} \leq \max \left( \exp(-\zeta t) \|u[0]\|_{\infty,\eta}, \sup_{0<s\leq t} \left( \max \left( \frac{|u(s,0)|}{\eta(0)}, \frac{|u(s,1)|}{\eta(1)}, \frac{\|f[s]\|_{\infty,\eta}}{\sigma - \zeta} \right) \right) \right) \exp(-\zeta (t-s))$$

(2.4)

where

$$\|u[t]\|_{\infty,\eta} := \max_{0\leq x \leq 1} \left( \frac{|u(t,x)|}{\eta(x)} \right), \quad \|f[t]\|_{\infty,\eta} := \sup_{0<s\leq 1} \left( \frac{|f(t,x)|}{\eta(x)} \right).$$

Moreover, the functional $V(u) = \|u\|_{\infty,\eta}$ satisfies the following implication for all $\varepsilon > 0$, $\zeta \in [0,\sigma)$ and $t \in (0,T)$ a.e.:

$$V(u[t]) \geq \varepsilon + \max \left( \frac{|u(t,0)|}{\eta(0)}, \frac{|u(t,1)|}{\eta(1)}, \frac{\|f[t]\|_{\infty,\eta}}{\sigma - \zeta} \right) \Rightarrow \frac{d}{dt} (V(u[t])) \leq -\zeta V(u[t])$$

(2.6)

Estimate (2.4) is an ISS-style maximum principle estimate which (like ordinary maximum principles; see [3,10,23]) provides a bound for the sup norm of the state that depends only on the sup norm of the initial condition, the source terms in the PDE ($f$) and the boundary values of the solution. However, unlike ordinary maximum principles, estimate (2.4) takes into account the exponential decay of the effect of the initial condition and the fact that past input values have less effect on the current value of the solution than more recent input values (fading memory effect). The ISS-style maximum principle estimate (2.4) provides in a direct way a fading memory ISS estimate when Dirichlet boundary inputs are present, i.e. when we have the boundary conditions $u(t,0) = d_0(t)$, $u(t,1) = d_1(t)$, for all $t \in [0,T]$.
where \(d_0, d_1 \in C^0([0, T])\) are the boundary disturbance inputs.

The proof of Theorem 2.1 relies on showing that the weighted sup norm of the solution \(V(u) = \|u\|_{\infty, \eta}\) (defined by (2.5)) is an ISS Lyapunov functional for the PDE system (2.1) with inputs the boundary values of the state \(u(t, 0), u(t, 1)\) and the distributed perturbation term \(f\) that appears in the PDE (2.1). An ISS Lyapunov functional for the PDE system (2.1) satisfies the following properties (see also [16] Chapter 1 for a slightly more demanding notion of an ISS Lyapunov functional for (2.1)):

1. there exist functions \(a_1, a_2 \in K_{\infty}\) such that the inequality \(a_1(\|u\|_{\infty}) \leq V(u) \leq a_2(\|u\|_{\infty})\) holds for all \(u \in C^0([0, 1])\),

2. for every \(t_0 > 0\), \(T > t_0\), the mapping \([t_0, T] \ni t \to V(u[t])\) is absolutely continuous for every solution \(u[t]\) of (2.1),

3. there exist a set of functions \(B \subseteq L^\infty(0, 1)\), a semi-norm \(G\) of \(D := \mathbb{R} \times \mathbb{R} \times B\), a positive definite function \(\rho \in C^0(\mathbb{R}_+; \mathbb{R}_+)\) and a function \(\gamma \in K\) such that the following implication holds with \(d[t] = (u(t, 0), u(t, 1), f[t]) \in D\) for every solution \(u[t]\) of (2.1), for every \(T > 0, t \in (0, T]\) for which \(\frac{d}{dt}V(u[t])\) exists and every \(\varepsilon > 0\): if \((u[t], d[t]) \in C^0(0, 1) \times D\) satisfy \(V(u[t]) \geq \gamma(G(d[t])) + \varepsilon\) then \(\frac{d}{dt}V(u[t]) \leq -\rho(V(u[t]))\).

Property (i) holds for \(V(u) = \|u\|_{\infty, \eta}\); notice that (2.5) implies that \(\frac{\|u\|_{\infty, \eta}}{\max_{0 < s \leq t}(\eta(s))} \leq \|u\|_{\infty, \eta} \leq \frac{\|u\|_{\infty, \eta}}{\min_{0 < s \leq t}(\eta(s))}\) for all \(u \in C^0([0, 1])\). This explains why estimate (2.4) can give estimates of the sup norm of the state and this feature justifies the fact that the functional \(V(u) = \|u\|_{\infty, \eta}\) is a coercive functional. The above properties enable us to derive estimate (2.4) by invoking the continuity of the mapping \([0, T] \ni t \to V(u[t])\). When \(\zeta = 0\) then we get from (2.4) the estimate:

\[
\|u[t]\|_{\infty, \eta} \leq \max \left(\|u[0]\|_{\infty, \eta}, \sup_{0 < s \leq t} \left(\max \left(\frac{|u(s, 0)|}{\eta(0)}, \frac{|u(s, 1)|}{\eta(1)}, \frac{\|f[s]\|_{\infty, \eta}}{\sigma}\right)\right)\right)
\]

which is nothing else but a maximum principle for the solution of (2.1) (see [4, 10, 23]).

Theorem 2.1 holds for classical solutions of the PDE (2.1). Existence and uniqueness results for classical solutions of (nonlinear) parabolic PDEs are given in [4, 18].

A disadvantage of Theorem 2.1 is the fact that Theorem 2.1 can provide ISS estimates only when boundary disturbances appear in Dirichlet boundary conditions. However, boundary disturbances can appear in other types of boundary conditions as well (e.g., Neumann or Robin boundary conditions). Our next main result provides an estimate of a weighted sup norm of the solution of the PDE (2.1) that depends on the initial condition, the distributed perturbation term that may be present in the PDE and the boundary values of the solution and its spatial derivative.

**Theorem 2.2:** Let \(T > 0, a, b, c : (0, T) \times (0, 1) \to \mathbb{R}, f : (0, T) \times (0, 1) \to \mathbb{R}\) with \(\sup_{0 < x < 1, 0 < t \leq T} |f(t, x)| < +\infty\) be given. Let \(u \in C^0([0, T] \times [0, 1])\) be a given function with \(u[t] \in C^2((0, 1))\) for almost all \(t \in (0, T)\), for which the derivatives \(\frac{\partial}{\partial x}(t, 0), \frac{\partial}{\partial x}(t, 0)\) exist for all \(t \in (0, T)\) and the derivative \(\frac{\partial}{\partial x}(t, x)\) is a continuous function on \((0, T) \times [0, 1]\) that satisfies equation (2.1). Suppose that (2.2) holds and that there exist a constant \(\sigma > 0\) and a positive function \(\eta \in C^2([0, 1]; (0, +\infty))\) such that (2.3) holds. Then the following estimate holds for all \(\zeta \in (0, \sigma), g_0, g_1 : (0, T) \to (0, +\infty), k_0, k_1 : (0, T) \to [1, +\infty)\) and \(t \in (0, T)\):

\[
\|u[t]\|_{\infty, \eta} \leq \max \left(\exp(-\zeta t) \|u[0]\|_{\infty, \eta}, \sup_{0 < s \leq t} \left(\max \left(\frac{r_0(s) - k_0(t)}{\sigma - \zeta}, \frac{\|f[s]\|_{\infty, \eta}}{\sigma - \zeta}\right)\right)\right) \exp(-\zeta(t - s))
\]

where \(\|u[t]\|_{\infty, \eta}, \|f[t]\|_{\infty, \eta}\) are defined by (2.5) and
Moreover, the functional $V(u) = \|u\|_{\infty, \eta}$ satisfies the following implication for all $\varepsilon > 0$, $\zeta \in [0, \sigma)$ and $t \in (0, T)$ a.e.:

$$V(u[t]) \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_{\infty, \eta}}{\sigma - \zeta} \right) \Rightarrow \frac{d}{dt} (V(u[t])) \leq -\zeta V(u[t]). \quad (2.10)$$

It should be noted that estimate (2.7) is a more accurate ISS-style maximum principle estimate than estimate (2.4): notice that definitions (2.8), (2.9) imply that $r_0(t) \leq \frac{|u(t, 0)|}{\eta(0)}$, $r_1(t) \leq \frac{|u(t, 1)|}{\eta(1)}$ for all $t \in (0, T]$. However, there is a price to pay for obtaining the more accurate estimate (2.7): the solution has to be differentiable with respect to $x$ up to the boundary of the domain. This additional regularity requirement does not appear in Theorem 2.1. This additional regularity requirement is justified by the fact that Theorem 2.2 is a tool for handling boundary conditions which involve the spatial derivative at the boundary of the domain. As in Theorem 2.1, it should be emphasized that Theorem 2.2 does not only show the solution estimate (2.7) but also shows that the functional $V(u) = \|u\|_{\infty, \eta}$ is an ISS Lyapunov functional for the PDE system (2.1) whose inputs are the distributed perturbation term $f$ and the boundary disturbances in any of the following combinations: $d_0(t) = g_0(t) \frac{\partial u}{\partial x}(t, 0) - \left( \frac{g_{0}(t) \eta'(0)}{\eta(0)} + k_0(t) \right) u(t, 0)$ or $d_0(t) = u(t, 0)$, and $d_1(t) = u(t, 1)$ or $d_1(t) = g_1(t) \frac{\partial u}{\partial x}(t, 1) - \left( \frac{g_{1}(t) \eta'(1)}{\eta(1)} - k_1(t) \right) u(t, 1)$.

The functions $g_0, g_1 : (0, T] \to (0, +\infty)$, $k_0, k_1 : (0, T] \to [1, +\infty)$ are arbitrary and can be selected in an appropriate way in order to handle even nonlinear boundary conditions (see Example 3.2 in next section). However, when standard Neumann or Robin boundary conditions hold at the boundary then we obtain as a corollary of Theorem 2.2 the following result.

**Corollary 2.3:** Let $T > 0$, $a, b, c : (0, T) \times (0, 1) \to \mathbb{R}$, $f : (0, T) \times (0, 1) \to \mathbb{R}$ with $\sup_{0 < x < 1, 0 < t \leq T} |f(t, x)| < +\infty$, $u \in C^0([0, T] \times [0, 1])$ with $u[t] \in C^2((0, 1))$ for almost all $t \in (0, T)$, for which the derivative $\frac{\partial u}{\partial t}(t, x)$ exists and is a continuous function on $(0, T) \times [0, 1]$, the derivatives $\frac{\partial u}{\partial x}(t, 0)$, $\frac{\partial u}{\partial x}(t, 1)$ exist for all $t \in (0, T]$ and equation (2.1) holds. Let $\mu_0, \mu_1 > 0$, $\lambda_0, \lambda_1 \in \mathbb{R}$ be given constants. Suppose that (2.2) holds and that there exist a constant $\sigma > 0$ and a positive function $\eta \in C^2([0, 1]; (0, +\infty))$ such that (2.3) holds. Moreover, suppose that one of the following conditions hold:

$$\mu_0 \eta'(0) - \lambda_0 \eta(0) < 0 \quad (2.11)$$

$$\mu_1 \eta'(1) + \lambda_1 \eta(1) > 0 \quad (2.12)$$

$$\mu_0 \eta'(0) - \lambda_0 \eta(0) < 0 \text{ and } \mu_1 \eta'(1) + \lambda_1 \eta(1) > 0 \quad (2.13)$$

Then estimate (2.7) holds for all $\zeta \in [0, \sigma)$ and $t \in (0, T]$, where

$$r_0(t) := \min \left( \frac{|u(t, 0)|}{\eta(0)}, \frac{1}{|\mu_0 \eta'(0) - \lambda_0 \eta(0)|} \left| \mu_0 \frac{\partial u}{\partial x}(t, 0) - \lambda_0 u(t, 0) \right| \right),$$

$$r_1(t) := \min \left( \frac{|u(t, 1)|}{\eta(1)}, \frac{1}{|\mu_1 \eta'(1) - \lambda_1 \eta(1)|} \left| \mu_1 \frac{\partial u}{\partial x}(t, 1) - \lambda_1 u(t, 1) \right| \right), \quad \text{for } t \in (0, T], \text{ if (2.11) holds} \quad (2.14)$$
\begin{align}
  r_1(t) & := \min \left( \frac{|u(t,1)|}{\eta(1)}, \frac{1}{\mu_1 \eta(1) + \lambda_1 \eta(1)} \right) \left[ \mu_1 \frac{\partial u}{\partial x}(t,1) + \lambda_1 u(t,1) \right], \\
  r_0(t) & := \frac{|u(t,0)|}{\eta(0)}, \quad \text{for } t \in (0, T], \text{ if (2.15) holds}
\end{align}

\begin{align}
  r_1(t) & := \min \left( \frac{|u(t,1)|}{\eta(1)}, \frac{1}{\mu_1 \eta(1) + \lambda_1 \eta(1)} \right) \left[ \mu_1 \frac{\partial u}{\partial x}(t,1) + \lambda_1 u(t,1) \right], \\
  r_0(t) & := \frac{|u(t,0)|}{\eta(0)}, \quad \text{for } t \in (0, T], \text{ if (2.16) holds}
\end{align}

The ISS-style maximum principle estimate (2.7), with \( r_0, r_1 \) defined by (2.14) or (2.15) or (2.16), provides in a direct way a fading memory ISS estimate when we have the boundary conditions

\[ \mu_0 \frac{\partial u}{\partial x}(t,0) - \lambda_0 u(t,0) = d_0(t), \quad u(t,1) = d_1(t), \quad \text{for all } t \in [0, T] \quad \text{(when (2.14) holds)} \]

or

\[ u(t,0) = d_0(t), \quad \mu_1 \frac{\partial u}{\partial x}(t,1) + \lambda_1 u(t,1) = d_1(t), \quad \text{for all } t \in [0, T] \quad \text{(when (2.15) holds)} \]

or

\[ \mu_0 \frac{\partial u}{\partial x}(t,0) - \lambda_0 u(t,0) = d_0(t), \quad \mu_1 \frac{\partial u}{\partial x}(t,1) + \lambda_1 u(t,1) = d_1(t), \quad \text{for all } t \in [0, T] \quad \text{(when (2.16) holds)} \]

where \( d_0, d_1 \in C^0([0, T]) \) are boundary disturbance inputs. However, it should be noted here that the ISS-style maximum principle estimate (2.7), with \( r_0, r_1 \) defined by (2.14) or (2.15) or (2.16), may also be useful in other cases which are rarely encountered in the literature. For example, if (2.13) holds and if the following nonlinear boundary conditions are valid

\[ \left( \mu_0 \frac{\partial u}{\partial x}(t,0) - \lambda_0 u(t,0) \right) u(t,0) = 0, \quad \left( \mu_1 \frac{\partial u}{\partial x}(t,1) + \lambda_1 u(t,1) \right) u(t,1) = 0, \quad \text{for all } t \in [0, T] \]

then the ISS-style maximum principle estimate (2.7), with \( r_0, r_1 \) defined by (2.16) gives the exponential decay estimate

\[ ||u(t)||_{\infty, \eta} \leq \exp(-\zeta t) ||u(0)||_{\infty, \eta} \]

for zero source terms (i.e., when \( f(t, x) \equiv 0 \)). This is a case where we can determine the asymptotic behavior of the solution even when we do not know exactly what happens at the boundary (i.e., for some \( t \in [0, T] \) we may have \( \mu_0 \frac{\partial u}{\partial x}(t,0) = \lambda_0 u(t,0) \) or \( u(t,0) = 0 \); similarly for \( x = 1 \)).

Conditions (2.11), (2.12), (2.13) are not new: they have also appeared in [12,16], where a completely different proof methodology was applied (the solution was approximated by a numerical scheme). However, here we do not follow the proof methodology in [12,16] and we obtain Corollary 2.3 under weaker requirements for the solution.
3. Illustrative Examples

In this section we present three examples that illustrate the use of the main results for the derivation of ISS estimates for nonlinear 1-D parabolic PDEs. In all examples we assume the existence of classical solutions for illustration purposes. However, in practice the ISS-style maximum principle estimates can be used in conjunction with standard existence results in order to establish the existence of global solutions, i.e., solutions that are defined for all \( t \geq 0 \). Typically, the existence of global solutions for nonlinear reaction-diffusion PDEs depends on whether we can obtain bounds of the sup norm of the state (see for example [2,25]) and the ISS-style maximum principle estimates provided by Theorem 2.1 and Theorem 2.2 can provide such bounds.

Example 3.1 (A Nonlinear Reaction-Diffusion PDE): Consider the nonlinear reaction-diffusion PDE

\[
\frac{\partial u}{\partial t}(t,x) = \kappa(u(t,x)) \frac{\partial^2 u}{\partial x^2}(t,x) + r(u(t,x))u(t,x) + f(t,x), \quad \text{for all } (t,x) \in (0,T] \times [0,1]
\]  
(3.1)

\[
u(t,0) = d_0(t), \quad u(t,1) = d_1(t), \quad \text{for all } t \in [0,T]
\]  
(3.2)

where \( d_0, d_1 \in C^0([0,T]) \) are boundary inputs, \( f \in C^0([0,T] \times [0,1]) \) is a distributed in-domain input and \( \kappa, r \in C^0(\mathbb{R}) \) are functions which satisfy the following conditions

\[
\kappa(u) > 0, \quad \text{for all } u \in \mathbb{R}
\]  
(3.3)

\[
\sup \left\{ \frac{\sigma + r(u)}{\kappa(u)} : u \in \mathbb{R} \right\} < \pi^2
\]  
(3.4)

where \( \sigma > 0 \) is a constant. We show next that there exists sufficiently small \( \phi > 0 \) such that the following estimate holds for all \( \zeta \in [0,\sigma) \) and \( t \in (0,T] \)

\[
\|u[t]\|_{\infty,\eta} \leq \max \left( \exp (-\zeta t) \|u[0]\|_{\infty,\eta}, \sup_{0 \leq s \leq t} \left( \max \left( \frac{|d_0(s)|}{\eta(0)}, \frac{|d_1(s)|}{\eta(1)}, \frac{\|f[s]\|_{\infty,\eta}}{\sigma - \zeta} \right) \exp (-\zeta (t-s)) \right) \right)
\]  
(3.5)

with \( \eta(x) = \sin(\theta x + \phi), \quad x \in [0,1], \) for every \( d_0, d_1 \in C^0([0,T]), f \in C^0([0,T] \times [0,1]) \) and for every (classical) solution \( u \in C^0([0,T] \times [0,1]) \cap C^1([0,T] \times [0,1]) \) with \( u[t] \in C^2([0,1]) \) for \( t \in (0,T] \) of (3.1), (3.2).

Indeed, inequality (3.4) shows that there exist a constant \( \theta \in (0,\pi) \) (sufficiently close to \( \pi \)) such that

\[
\theta^2 \geq \frac{\sigma + r(u)}{\kappa(u)}, \quad \text{for all } u \in \mathbb{R}
\]  
(3.6)

Let \( \phi > 0 \) be a constant sufficiently small so that \( \phi + \theta < \pi \). Notice that for every solution of (3.1), (3.2), equation (2.1) holds with

\[
a(t,x) = \kappa(u(t,x)), \quad b(t,x) = 0, \quad c(t,x) = r(u(t,x)).
\]  
(3.7)

Inequalities (3.3), (3.6) and definitions (3.7) guarantee that (2.2) and (2.3) hold with \( \eta(x) = \sin(\theta x + \phi) \). Theorem 2.1 guarantees that for every \( T > 0 \), for every \( d_0, d_1 \in C^0([0,T]), f \in C^0([0,T] \times [0,1]) \) and for every (classical) solution \( u \in C^0([0,T] \times [0,1]) \cap C^1([0,T] \times [0,1]) \) with \( u[t] \in C^2([0,1]) \) for \( t \in (0,T] \) of the PDE problem (3.1), (3.2), estimate (3.5) holds.

It should be noted here that the stability conditions (3.3), (3.4) give a sharp characterization of the stability for the PDE problem (3.1), (3.2). Indeed, when \( \kappa(u) \equiv p > 0, r(u) \equiv ps^2 \) (and consequently \( \sup \left\{ \frac{r(u)}{\kappa(u)} : u \in \mathbb{R} \right\} = \pi^2 \)), \( d_0 = d_1 \equiv 0, f \equiv 0 \) then there are solutions of the (linear) PDE problem (3.1), (3.2) that do not tend to zero (namely solutions of the form \( u(t,x) = A \sin(\pi x) \) where \( A \in \mathbb{R} \)). Therefore, estimate (3.5) cannot hold in this case. \(<\)
The following example illustrates how Theorem 2.2 can be used for the derivation of ISS estimates for parabolic PDEs with nonlinear and non-local boundary conditions. Moreover, the example shows that we can study parabolic PDEs for which the diffusion coefficient is a non-local functional of the state. This situation is important because it arises in many phenomena related to turbulent flows (see [5,6]) as well as in the work of O. A. Ladyzhenskaya (see [19]) on the modification of the Navier-Stokes equations and in feedback control of fluid flows (see [1]).

**Example 3.2 (Heat Equation with Nonlinear and Non-Local Boundary Conditions):** Consider the following nonlinear and non-local 1-D parabolic PDE:

\[
\frac{\partial u}{\partial t}(t, x) = \kappa(u[t]) \frac{\partial^2 u}{\partial x^2}(t, x) + f(t, x), \text{ for all } (t, x) \in (0, T] \times [0, 1]
\] (3.8)

\[
\frac{\partial u}{\partial x}(t, 0) = (\lambda_0 + \beta_0(u[t])) u(t, 0) + d_0(t), \text{ for all } (t, 1) = - (\lambda_1 + \beta_1(u[t])) u(t, 1) + d_1(t)
\] (3.9)

where \(d_0, d_1 \in C^0([0, T])\) are the boundary disturbances, \(f \in C^0([0, T] \times [0, 1])\) is the distributed disturbance, \(\kappa : C^1([0, 1]) \to \mathbb{R}, \beta_0, \beta_1 : C^0([0, 1]) \to \mathbb{R}_+\) are given non-negative functionals and \(\lambda_0, \lambda_1 > 0\) are constants.

We assume that there exists a constant \(\kappa^* > 0\) for which \(\kappa(u) \geq \kappa^*\) for all \(u \in C^0([0, 1])\). Let \(\theta \in (0, \frac{\pi}{2})\) be a constant sufficiently small so that \(\theta \tan(\theta) < \lambda_1\). We show next that every classical solution of (3.8), (3.9) \(u \in C^0([0, T] \times [0, 1]) \cap C^1((0, T] \times [0, 1])\) with \(u[t] \in C^2((0, 1))\) for \(t \in (0, T]\) satisfies the following estimate holds for all \(\zeta \in [0, \kappa^*\theta^2]\) and \(t \in (0, T]\)

\[
\|u[t]\|_{\infty, \eta} \leq \max \left(\exp(-\zeta t) \|u[0]\|_{\infty, \eta}, \sup_{0 < s \leq t} \left(\max \left(\frac{|d_0(s)|}{\lambda_0}, \frac{|d_1(s)|}{\lambda_1 \cos(\theta) - \eta \sin(\theta)}, \frac{\|f[s]\|_{\infty, \eta}}{\kappa^* \theta^2 - \zeta}\right) \exp(-\zeta(t - s))\right) \right)
\] (3.10)

with \(\eta(x) = \cos(\theta x)\) for \(x \in [0, 1]\). Indeed, notice that for every solution of (3.8), (3.9), equation (2.1) holds with

\[
a(t, x) = \kappa(u[t]), b(t, x) \equiv 0, c(t, x) \equiv 0.
\] (3.11)

Moreover, due to the fact that \(\kappa(u) \geq \kappa^*\) for all \(u \in C^1([0, 1])\), inequalities (2.2) and (2.3) hold with \(\sigma = \kappa^*\theta^2\) and \(\eta(x) = \cos(\theta x)\). Estimate (3.10) is a direct consequence of Theorem 2.2 with \(g_0(t) = \frac{1}{\beta_0(u[t]) + \lambda_0}, k_0(t) = k_1(t) \equiv 1\) and \(g_1(t) = \frac{1}{\beta_1(u[t]) + \lambda_1 - \theta \tan(\theta)}\).

The final example shows that the main results of the present work can be used for the study of realistic problems where the physical properties of a material are nonlinear functions of thermodynamic variables (such as temperature or pressure).

**Example 3.3 (The “real” heat equation):** Thermal conductivity \(k\) and volumetric heat capacity \(c\) are quantities that depend on the temperature \(u\) of a solid material. Consequently, by exploiting the conservation of energy and Fourier’s law, we obtain the following equation for a 1-D spatial domain:

\[
\frac{\partial u}{\partial t}(t, x) = \frac{k(u(t, x))}{c(u(t, x))} \frac{\partial^2 u}{\partial x^2}(t, x) + \frac{k'(u(t, x))}{c(u(t, x))} \left(\frac{\partial u}{\partial x}(t, x)\right)^2, \text{ for all } (t, x) \in (0, T] \times [0, 1]
\] (3.12)

Equation (3.12) is important for certain solids when the temperature variation is large. Therefore, we are led to the study of the PDE problem

\[
\frac{\partial u}{\partial t}(t, x) = \kappa(u(t, x)) \frac{\partial^2 u}{\partial x^2}(t, x) + g(u(t, x)) \left(\frac{\partial u}{\partial x}(t, x)\right)^2, \text{ for all } (t, x) \in (0, T] \times [0, 1]
\] (3.13)
Moreover, we assume that there exists $\kappa$ satisfies the condition $\gamma$ estimate holds for all $u$ of the form $u_k$ and volumetric heat capacity $c$.

Next define:

$$u(t,0) = d_0(t), \quad u(t,1) = d_1(t), \quad \text{for all } t \in [0,T]$$

(3.14)

where $d_0, d_1 \in C^0([0,T])$ are boundary disturbances and $\kappa, g \in C^0(\mathbb{R})$ are given functions with $\kappa(u) > 0$ for all $u \in \mathbb{R}$. We assume that the increasing function $\gamma : \mathbb{R} \to \mathbb{R}$ defined by

$$\gamma(u) := \int_0^u \exp \left( \int_0^s \frac{g(l)}{\kappa(l)} dl \right) ds, \quad \text{for } u \in \mathbb{R}$$

satisfies the condition $\gamma(\mathbb{R}) = \mathbb{R}$ or equivalently,

$$\lim_{u \to \pm \infty} (\gamma(u)) = \pm \infty$$

Moreover, we assume that there exists $\kappa^* > 0$ such that

$$\kappa(u) \geq \kappa^* \text{ for all } u \in \mathbb{R}.$$  

(3.17)

It should be noticed here that the “real” heat equation problem (3.12) is accompanied by constraints of the form $u \in (u_{\min}, u_{\max})$, where $u_{\min}$ corresponds to the absolute zero temperature (3rd law of thermodynamics) and $u_{\max}$ corresponds to the melting point. In this case, one can smoothly extend the thermal conductivity $k$ and volumetric heat capacity $c$ out of the interval $(u_{\min}, u_{\max})$ so that conditions (3.16), (3.17) hold with $\kappa(u) = k(u)/c(u)$ and $g(u) = k'(u)/c(u)$.

The invertible transformation $w(t,x) = \gamma (u(t,x))$ transforms the PDE problem (3.13), (3.14) to the following PDE problem

$$\frac{\partial w}{\partial t}(t,x) = \kappa \left( \gamma^{-1}(w(t,x)) \right) \frac{\partial^2 w}{\partial x^2}(t,x), \quad \text{for all } (t,x) \in (0,T] \times [0,1]$$

(3.18)

$$w(t,0) = \tilde{d}_0(t) = \gamma (d_0(t)), \quad w(t,1) = \tilde{d}_1(t) = \gamma (d_1(t)), \quad \text{for all } t \in [0,T]$$

(3.19)

Following the analysis presented in Example 3.1, for every $\phi \in (0, \pi/2)$ every (classical) solution $w \in C^0([0,T] \times [0,1]) \cap C^1((0,T] \times [0,1])$ with $w[t] \in C^2([0,1])$ for $t \in (0,T]$ of (3.18), (3.19) satisfies the following estimate holds for all $\zeta \in (0, \kappa^*(\pi - 2\phi)^2)$ and $t \in (0,T]$

$$\|w[t]\|_{\infty,\eta} \leq \max \left( \exp (-\zeta t) \|w[0]\|_{\infty,\eta}, \frac{1}{\sin(\phi)} \sup_{0<s\leq t} \left( \max \left( \left| \tilde{d}_0(s) \right|, \left| \tilde{d}_1(s) \right| \right) \exp \left( -\zeta (t - s) \right) \right) \right)$$

(3.20)

with $\eta(x) = \sin ((\pi/2)\phi x + \phi)$ for $x \in [0,1]$. Exploiting definition (2.5), we get from (3.20) for all $\zeta \in (0, \kappa^*(\pi - 2\phi)^2)$ and $t \in (0,T]$

$$\|w[t]\|_{\infty} \leq \frac{1}{\sin(\phi)} \max \left( \exp (-\zeta t) \|w[0]\|_{\infty}, \sup_{0<s\leq t} \left( \max \left( \left| \tilde{d}_0(s) \right|, \left| \tilde{d}_1(s) \right| \right) \exp \left( -\zeta (t - s) \right) \right) \right)$$

(3.21)

Next define:

$$\gamma_1(s) := \min \left( \gamma(s), -\gamma(-s) \right), \quad \text{for } s \geq 0$$

(3.22)

$$\gamma_2(s) := \max \left( \gamma(s), -\gamma(-s) \right), \quad \text{for } s \geq 0$$

(3.23)

Condition (3.16) guarantees that both functions $\gamma_1, \gamma_2$ are of class $K_\infty$ and satisfy the following property:

$$\gamma_1(|u|) \leq |\gamma(u)| \leq \gamma_2(|u|), \quad \text{for all } u \in \mathbb{R}$$

(3.24)
Using the fact that \(w(t, x) = \gamma(u(t, x))\), (3.19) and (3.24), we obtain from (3.21) for all \(\zeta \in (0, \kappa^*(\pi - 2\phi)^2)\) and \(t \in (0, T)\):

\[
\|u[t]\|_{\infty} \leq \max \left(\omega_\zeta \left(\|u[0]\|_{\infty}, t\right), \sup_{0 < s \leq t} \left(\max \left(\omega_\zeta \left(|d_0(s)|, t - s\right), \omega_\zeta \left(|d_1(s)|, t - s\right)\right)\right)\right)
\]

(3.25) where \(\omega_\zeta(s, t) := \gamma_1^{-1} \left(\frac{\exp(-\zeta t)}{\sin(\phi)} \gamma_2(s)\right)\). The fading memory ISS estimate (3.25) shows that the gain functions for each one of the boundary disturbances is \(\omega_\zeta(s, 0) := \gamma_1^{-1} \left(\frac{\gamma_2(s)}{\sin(\phi)}\right)\). Crystalline semiconductors, crystalline quartz and crystalline ceramics, used in the manufacture of quartz clocks and various kinds of electronic devices, including diodes, transistors, and integrated circuits, are known to have a thermal conductivity that scales as \(1/u\) (see [24]). With further calculations, which would need to be mindful of the absolute zero and melting point limits on the temperature, one could pursue deriving a growth rate on the ISS gain \(\omega_\zeta(s, 0) := \gamma_1^{-1} \left(\frac{\gamma_2(s)}{\sin(\phi)}\right)\).  

4. Comparison with Maximum Principles

Since Theorem 2.1 and Theorem 2.2 provide solution estimates that are similar to conventional maximum principle estimates, the reader may wonder why don’t we use maximum principles for the derivation of these ISS-style maximum principle estimates. Before we answer this important question, we first give the ISS-style maximum principle estimates that can be proved by using well-known maximum principles. The proofs of the following two results are provided in Section 5.

**Theorem 4.1:** Let \(T > 0, a, b, c : (0, T) \times (0, 1) \to \mathbb{R}, f : (0, T) \times (0, 1) \to \mathbb{R} \) with \(\sup_{0 < t < 1, 0 < t < T} (|f(t, x)|) < +\infty\) be given. Suppose that \(u \in C^0([0, T] \times [0, 1])\) is a given function with \(u[t] \in C^2((0, 1))\) for all \(t \in (0, T)\), for which the derivative \(\frac{\partial u}{\partial t}(t, x)\) exists, is a continuous function on \((0, T) \times (0, 1)\) and satisfies

\[
\frac{\partial u}{\partial t}(t, x) = a(t, x)\frac{\partial^2 u}{\partial x^2}(t, x) + b(t, x)\frac{\partial u}{\partial x}(t, x) + c(t, x)u(t, x) + f(t, x),
\]

for all \(t \in (0, T)\) and for all \(x \in (0, 1)\)

(4.1)

Moreover, suppose that (2.2) holds and that there exist a constant \(\sigma > 0\) and a function \(\eta \in C^2([0, 1]; (0, +\infty))\) such that (2.3) holds. Then the following estimate holds for all \(\zeta \in [0, \sigma]\) and \(t \in (0, T)\):

\[
\|u[t]\|_{\infty, \eta} \leq \max \left(\exp(-\zeta t) \|u[0]\|_{\infty, \eta}, \sup_{0 < s < t} \left(\max \left(\frac{|u(s, 0)|}{\eta(0)}, \frac{|u(s, 1)|}{\eta(1)}, \frac{\|f[s]\|_{\infty, \eta}}{\sigma - \zeta}\right)\right)\right)
\]

(4.2)

where \(\|u[t]\|_{\infty, \eta}\) and \(\|f[t]\|_{\infty, \eta}\) are defined by (2.5).

**Theorem 4.2:** Let \(T > 0, a, b, c : (0, T) \times (0, 1) \to \mathbb{R}, f : (0, T) \times (0, 1) \to \mathbb{R} \) with \(\sup_{0 < t < 1, 0 < t < T} (|f(t, x)|) < +\infty\) be given. Suppose that \(u \in C^0([0, T] \times [0, 1])\) is a given function with \(u[t] \in C^2((0, 1)) \cap C^1([0, 1])\) for all \(t \in (0, T)\), for which the derivative \(\frac{\partial u}{\partial T}(t, x)\) is a continuous function on \((0, T) \times (0, 1)\) and satisfies (4.1). Moreover, suppose that (2.2) holds and that there exist a constant \(\sigma > 0\) and a positive function \(\eta \in C^2([0, 1]; (0, +\infty))\) such that (2.3) holds. Then the following estimate holds for all \(\zeta \in [0, \sigma]\), \(g_0, g_1 : (0, T) \to [0, +\infty), k_0, k_1 : (0, T) \to [1, +\infty)\) and \(t \in (0, T)\):

\[
\|u[t]\|_{\infty, \eta} \leq \max \left(\exp(-\zeta t) \|u[0]\|_{\infty, \eta}, \sup_{0 < s < t} \left(\exp(-\zeta(t - s)) \max \left(\varphi_0(s), \varphi_1(s), \frac{\|f[s]\|_{\infty, \eta}}{\sigma - \zeta}\right)\right)\right)
\]

(4.3)

where
Since Proof: following equality holds: \[ \phi_0(t) := \frac{1}{\eta(0)} \min \left( \|u(t,0)\|, \left| g_0(t) \frac{\partial u}{\partial x}(t,0) - \left( k_0(t) + \frac{g_0(t)\eta'(0)}{\eta(0)} \right) u(t,0) \right| \right), \text{ for } t \in (0,T) \] (4.4)

\[ \phi_1(t) := \frac{1}{\eta(1)} \min \left( \|u(t,1)\|, \left| g_1(t) \frac{\partial u}{\partial x}(t,1) + \left( k_1(t) - \frac{g_1(t)\eta'(1)}{\eta(1)} \right) u(t,1) \right| \right), \text{ for } t \in (0,T) \] (4.5)

and \( \|u[t]\|_{\infty,\eta}, \|f[t]\|_{\infty,\eta} \) are defined by (2.5).

Now we are ready to compare Theorem 2.1 with Theorem 4.1 and Theorem 2.2 with Theorem 4.2. The estimates provided by Theorem 2.1 and Theorem 2.2 are almost identical to the estimates provided by Theorem 4.1 and Theorem 4.2. However, there are some important differences between Theorem 2.1, Theorem 2.2 and Theorem 4.1, Theorem 4.2:

1. **Regularity with respect to time.** The solutions in Theorem 2.1 and Theorem 2.2 are assumed to be more regular with respect to time than the solutions in Theorem 4.1 and Theorem 4.2. More specifically, Theorem 2.1 and Theorem 2.2 assume that the time derivative \( \frac{\partial u}{\partial t}(t,x) \) can be extended continuously to the boundary of the domain, i.e., to the points \( x = 0 \) and \( x = 1 \). This assumption is not needed in Theorem 4.1 and Theorem 4.2.

2. **Regularity with respect to the spatial variable.** It should be noted that Theorem 2.1 and Theorem 2.2 do not assume that the solution is of class \( C^2((0,1)) \) for all \( t \in (0,T) \) (Theorem 2.1 and Theorem 2.2 assume that the solution is of class \( C^2((0,1)) \) for almost all \( t \in (0,T) \)). On the other hand, Theorem 4.1 and Theorem 4.2 assume that the solution is of class \( C^2((0,1)) \) for all \( t \in (0,T) \).

3. **ISS Lyapunov functional.** Theorem 2.1 and Theorem 2.2 guarantee that the functional \( V(u) = \|u\|_{\infty,\eta} \) is an ISS Lyapunov functional for the PDE system (2.1). This is an important feature because ISS Lyapunov functionals have been proved very useful for the analysis of control systems and the design of feedback stabilizers. Unfortunately, Theorem 4.1 and Theorem 4.2 (due to the fact that their proof is not based on Lyapunov functionals but on maximum principles) cannot provide an ISS Lyapunov functional for the PDE system (2.1).

4. **Validity of the PDE.** It should be noted that Theorem 2.1 and Theorem 2.2 do not assume that the PDE (2.1) is valid for all \( t \in (0,T) \) and for all \( x \in (0,1) \) (Theorem 2.1 and Theorem 2.2 assume that (2.1) holds for almost all \( t \in (0,T) \) and for all \( x \in (0,1) \)). On the other hand, Theorem 4.1 and Theorem 4.2 assume that the PDE (2.1) is valid for all \( t \in (0,T) \) and for all \( x \in (0,1) \) (i.e., (4.1) holds).

The above differences may be important in certain cases and the reader can select which result is more convenient for her purposes.

5. **Proofs of Main Results**

For the proofs of Theorem 2.1 and Theorem 2.2 we need some auxiliary results. The first auxiliary result provides a sufficient condition that guarantees that the sup norm is an absolutely continuous function of time.

**Lemma 5.1:** Let \( b > a \) be given real numbers and let \( u \in C^0([a,b] \times [0,1]) \) be a given function for which the derivative \( \frac{\partial u}{\partial t}(t,x) \) exists and is a continuous function on \( [a,b] \times [0,1] \). Then the mapping \( [a,b] \ni t \to \|u[t]\|_{\infty} \) is a Lipschitz mapping. Moreover, for every \( t \in [a,b] \) for which the limit \( \lim_{h \to 0^+} \left( \frac{\|u[t+h]\|_{\infty} - \|u[t]\|_{\infty}}{h} \right) \) exists, the following equality holds:

\[
\lim_{h \to 0^+} \left( \frac{\|u[t+h]\|_{\infty} - \|u[t]\|_{\infty}}{h} \right) = \lim_{h \to 0^+} \left( \frac{\|u[t+h] - \frac{\partial u}{\partial t}[t]}{h} \right)
\]

(5.1)

**Proof:** Since \( \frac{\partial u}{\partial t} \) is continuous on the compact set \( [a,b] \times [0,1] \), it clearly follows that \( t \to u(t,x) \) is Lipschitz uniformly in \( x \). In particular, the following inequality holds for all \( t_1, t_2 \in [a,b] \):

\[ \|u[t_2]\|_\infty - \|u[t_1]\|_\infty \leq |t_2 - t_1| \max_{a \leq s \leq b, 0 \leq x \leq 1} \left( \left| \frac{\partial u}{\partial t}(s, x) \right| \right) \] (5.2)

Inequality (5.2) shows that the mapping \([a, b] \ni t \mapsto \|u[t]\|_\infty\) is a Lipschitz mapping.

Equation (5.1) is clear from inverse triangle inequality and Taylor’s theorem, which allow us to show that

\[ \lim_{h \to 0^+} \left( \frac{\|u[t] + h \frac{\partial u}{\partial t}[t]\|_\infty - \|u[t + h]\|_\infty}{h} \right) = 0, \text{ for all } t \in [a, b] \] (5.3)

Equality (5.1) is a direct consequence of equation (5.3). \(<\)

The second auxiliary result is a technical lemma that provides a formula for a specific limit. This specific limit was encountered in the statement of Lemma 5.1 and consequently, the formula that the following lemma provides, plays a crucial role.

**Lemma 5.2:** Let \(u, w \in C^0([0, 1])\) be given functions and suppose that the limit \(\lim_{h \to 0^+} \left( \frac{\|u + hw\|_\infty - \|u\|_\infty}{h} \right)\) exists. Then \(\lim_{h \to 0^+} \left( \frac{\|u + hw\|_\infty - \|u\|_\infty}{h} \right) \leq \|w\|_\infty\). Moreover, if \(\|u\|_\infty > 0\) then

\[ \lim_{h \to 0^+} \left( \frac{\|u + hw\|_\infty - \|u\|_\infty}{h} \right) \leq \max_{x \in I} (\text{sgn}(u(x))w(x)) \] (5.4)

where \(I = \{ y \in [0, 1] : |u(y)| = \|u\|_\infty \}\).

**Proof:** The fact that \(\lim_{h \to 0^+} \left( \frac{\|u + hw\|_\infty - \|u\|_\infty}{h} \right) \leq \|w\|_\infty\) follows from the inequality \(\|u + hw\|_\infty \leq \|u\|_\infty + h \|w\|_\infty\) that holds for all \(h > 0\).

Next we assume that \(\|u\|_\infty > 0\) and we show that (5.4) holds. Let \(\varepsilon \in (0, \|u\|_\infty)\) be given and define the sets:

\[ I^+_\varepsilon = \{ y \in [0, 1] : u(y) \geq \|u\|_\infty - \varepsilon \}, I^-_\varepsilon = \{ y \in [0, 1] : u(y) \leq -\|u\|_\infty + \varepsilon \}, I_\varepsilon = I^+_\varepsilon \cup I^-_\varepsilon \] (5.5)

By virtue of continuity of \(u\) each of the sets \(I_\varepsilon, I^+_\varepsilon, I^-_\varepsilon\) is compact and \(I_\varepsilon\) is non-empty (but notice that one of the sets \(I^+_\varepsilon, I^-_\varepsilon\) may be empty). Definitions (5.5) imply that for all \(y \in [0, 1] \setminus I_\varepsilon\) we have:

\[ |u(y) + hw(y)| \leq |u(y)| + h|w(y)| \leq \|u\|_\infty - \varepsilon + h \|w\|_\infty \] (5.6)

Since \(\|u + hw\|_\infty \geq \|u\|_\infty - h \|w\|_\infty\), we conclude that for \(y \in [0, 1] \setminus I_\varepsilon\) and \(h > 0\) sufficiently small (so that \(2h \|w\|_\infty < \varepsilon\)), it holds that \(|u(y) + hw(y)| < \|u\|_\infty\). Thus we conclude that \(\|u + hw\|_\infty = \max_{x \in I_\varepsilon} (|u(x) + hw(x)|)\) for all \(h > 0\) sufficiently small, which also implies that

\[ \|u + hw\|_\infty = \max_{x \in I_\varepsilon} (|u(x) + hw(x)|) = \max_{x \in I_\varepsilon} (|u(x) + hw(x)| - |u(x)| + |u(x)|) \leq \max_{x \in I_\varepsilon} (\text{sgn}(u(x))w(x)) + \|u\|_\infty \] (5.7)

for all \(h > 0\) sufficiently small. The last equality in (5.7) is obtained by distinguishing the cases \(x \in I^+_\varepsilon, x \in I^-_\varepsilon\), using definitions (5.5) and assuming that \(h \|w\|_\infty < \|u\|_\infty - \varepsilon\). Inequality (5.7) and the fact that \(\varepsilon \in (0, \|u\|_\infty)\) is arbitrary imply the following inequality:

\[ \lim_{h \to 0^+} \left( \frac{\|u + hw\|_\infty - \|u\|_\infty}{h} \right) \leq \max_{x \in I_\varepsilon} (\text{sgn}(u(x))w(x)), \text{ for all } \varepsilon \in (0, \|u\|_\infty) \] (5.8)

We show next by contradiction that (5.4) holds. Assume that \(\lim_{h \to 0^+} \left( \frac{\|u + hw\|_\infty - \|u\|_\infty}{h} \right) > \max_{x \in I_\varepsilon} (\text{sgn}(u(x))w(x))\).

Define
Consider a sequence \( \{y_n \in [0,1] \}_{n=0}^{\infty} \) that satisfies \( y_n \in I_\varepsilon \) and \( \text{sgn}(u(y_n))w(y_n) = \max_{x \in I_\varepsilon} (\text{sgn}(u(x))w(x)) \) with 
\( \varepsilon = 2^{-n-1} \|u\|_\infty \) for \( n = 0, 1, 2, \ldots \). Clearly, this sequence is bounded and consequently, it contains a convergent subsequence. Without loss of generality, we denote this convergent subsequence by \( \{x_n \in [0,1] \}_{n=0}^{\infty} \). Define \( \lim_{n \to +\infty} (x_n) = x^* \) and notice that since for each \( n = 0, 1, 2, \ldots \), there exists \( m \geq n \) with \( x_n = y_m \in I_\varepsilon \) and \( \varepsilon = 2^{-m-1} \|u\|_\infty \), it follows from definitions (5.5) that \( \|u\|_\infty (1 - 2^{-n-1}) \leq \|u\|_\infty (1 - 2^{-m-1}) \leq |u(x_n)| \). Continuity of \( u \) and the fact that \( I = \{ y \in [0,1] : \|u(y)\| = \|u\|_\infty \} \) imply that \( x^* \in I \).

Since for each \( n = 0, 1, 2, \ldots \) there exists \( m \geq n \) with \( x_n = y_m \in I_\varepsilon \) and \( \text{sgn}(u(y_m))w(y_m) = \max_{x \in I_\varepsilon} (\text{sgn}(u(x))w(x)) \) with \( \varepsilon = 2^{-m-1} \|u\|_\infty \), it follows from (5.8) and (5.9) that

\[
\text{sgn}(u(x_n))w(x_n) \geq p + \max_{x \in I} (\text{sgn}(u(x))w(x)) \quad \text{for all } n = 0, 1, 2, \ldots \tag{5.10}
\]

Since \( x^* \in I \) we must have either \( u(x^*) = \|u\|_\infty > 0 \) or \( u(x^*) = -\|u\|_\infty < 0 \). Consequently, since \( \lim_{n \to +\infty} (x_n) = x^* \) and since \( u \) is continuous, we must have either \( u(x_n) = 0 \) or \( u(x_n) < 0 \) for sufficiently large \( n \).

When \( u(x_n) > 0 \) for sufficiently large \( n \), we get by virtue of continuity of \( u \) and (5.10) that

\[
\text{sgn}(u(x_n))w(x_n) \to w(x^*) = \text{sgn}(u(x^*))w(x^*) \geq p + \max_{x \in I} (\text{sgn}(u(x))w(x))
\]

The above inequality together with the fact that \( \text{sgn}(u(x^*))w(x^*) \leq \max_{x \in I} (\text{sgn}(u(x))w(x)) \) (a consequence of the fact that \( x^* \in I \)) implies that \( p \leq 0 \); a contradiction with (5.9). Similarly, we obtain a contradiction when \( u(x_n) < 0 \) for sufficiently large \( n \).

The proof is complete. \( \triangle \)

We are now ready to derive estimates for the solution of the PDE (2.1) under assumption (2.2). The third auxiliary result provides an estimate under an additional assumption for the coefficient of the reaction term \( c(t,x) \).

**Lemma 5.3:** Let \( T > 0 \), \( a,b,c : (0,T) \times (0,1) \to \mathbb{R} \), \( f : (0,T) \times (0,1) \to \mathbb{R} \) with \( \sup_{0 < t < 1, 0 < t \leq T} (|f(t,x)|) < +\infty \) be given. Let \( u \in C^0([0,T] \times [0,1]) \) be a given function with \( u[t] \in C^2((0,1)) \) for almost all \( t \in (0,T) \), for which the derivative \( \frac{du}{dt} \) is a continuous function on \( (0,T) \times [0,1] \) and satisfies equation (2.1). Suppose that inequality (2.2) holds and that

\[
\sigma := -\sup_{0 < t < 1, t \in (0,T)} (c(t,x)) > 0 \tag{5.11}
\]

Then the following estimate holds for all \( \zeta \in [0,\sigma] \) and \( t \in (0,T] \):

\[
\|u[t]\|_\infty \leq \max\left(\exp(-\zeta t) \|u[0]\|_\infty, \sup_{0 < s \leq t} \left( \max\left(\|u(s,0)\|, |u(s,1)|, \|\frac{\|f[s]\|_\infty}{\sigma - \zeta}\right) \right) \right) \tag{5.12}
\]

Moreover, the functional \( V(u) = \|u\|_\infty \) satisfies the following implication for all \( \varepsilon > 0 \), \( \zeta \in [0,\sigma] \) and \( t \in (0,T) \) a.e.:

\[
V(u[t]) \geq \varepsilon + \max\left(\|u(t,0)\|, |u(t,1)|, \frac{\|f[t]\|_\infty}{\sigma - \zeta}\right) \Rightarrow \frac{d}{dt} (V(u[t])) \leq -\zeta V(u[t]) \tag{5.13}
\]
\textbf{Proof:} Let (arbitrary) $\zeta \in [0, \sigma)$, $t_1, t_2 \in (0, T)$ with $t_1 < t_2$ be given. Lemma 5.1 implies that the mapping $[t_1, t_2] \ni t \rightarrow \|u(t)\|_\infty$ is an absolutely continuous mapping. Moreover, there exists a Lebesgue measure zero set $N \subset [t_1, t_2]$ such that the following equation holds:

$$
\frac{d}{dt} \left( \|u(t)\|_\infty \right) = \lim_{h \to 0^+} \frac{\left( \|u(t) + h \frac{\partial u}{\partial t}(t)\|_\infty - \|u(t)\|_\infty \right)}{h}, \text{ for all } t \in [t_1, t_2] \setminus N
$$

Moreover, we assume that the Lebesgue measure zero set $N \subset [t_1, t_2]$ has been selected in such a way that (2.1) holds for all $t \in [t_1, t_2] \setminus N$ and for all $x \in (0, 1)$ and $u(t) \in C^2((0, 1))$ for all $t \in [t_1, t_2] \setminus N$.

Lemma 5.2 implies that

$$
\frac{d}{dt} (\|u(t)\|_\infty) \leq \max_{x \in I(t)} \left( \text{sgn}(u(t, x)) \frac{\partial u}{\partial t}(t, x) \right), \text{ for all } t \in [t_1, t_2] \setminus N \text{ with } \|u(t)\|_\infty > 0
$$

where $I(t) = \{ y \in [0, 1] : |u(t, y)| = \|u(t)\|_\infty \}$. Let (arbitrary) $\varepsilon > 0$ be given. Inequality (5.15) guarantees that the following implication holds for all $t \in [t_1, t_2] \setminus N$:

$$
\|u(t)\|_\infty \geq \varepsilon + \max \left( |u(t, 0)|, |u(t, 1)|, \frac{f(t)}{\sigma - \zeta} \right) \Rightarrow \frac{d}{dt} (\|u(t)\|_\infty) \leq \max_{x \in I(t)} \left( \text{sgn}(u(t, x)) \frac{\partial u}{\partial t}(t, x) \right)
$$

Pick any $t \in [t_1, t_2] \setminus N$. If $x \in I(t)$ is an interior point of $[0, 1]$ (i.e., $x \in (0, 1)$) and satisfies $u(t, x) = \|u(t)\|_\infty$ then $u$ has a maximum at $x$ and consequently (since $u(t) \in C^2((0, 1))$) $\frac{\partial^2 u}{\partial x^2}(t, x) \leq 0$, $\frac{\partial u}{\partial x}(t, x) = 0$. It follows from (2.1) and (2.2) that $\text{sgn}(u(t, x)) \frac{\partial u}{\partial x}(t, x) \leq c(t, x) \|u(t)\|_\infty + f(t, x)$ for every $x \in I(t) \cap (0, 1)$ with $u(t, x) = \|u(t)\|_\infty$. If $x \in I(t)$ is an interior point of $[0, 1]$ (i.e., $x \in (0, 1)$) and satisfies $u(t, x) = -\|u(t)\|_\infty$ then $u$ has a minimum at $x$ and consequently (since $u(t) \in C^2((0, 1))$) $\frac{\partial^2 u}{\partial x^2}(t, x) \geq 0$, $\frac{\partial u}{\partial x}(t, x) = 0$. It follows from (2.1) and (2.2) that $\text{sgn}(u(t, x)) \frac{\partial u}{\partial x}(t, x) \leq c(t, x) \|u(t)\|_\infty - f(t, x)$ for every $x \in I(t) \cap (0, 1)$ with $u(t, x) = -\|u(t)\|_\infty$. Combining both cases, we obtain:

$$
\text{If } t \in [t_1, t_2] \setminus N \text{ and } x \in I(t) \cap (0, 1) \text{ then } \text{sgn}(u(t, x)) \frac{\partial u}{\partial t}(t, x) \leq c(t, x) \|u(t)\|_\infty + |f(t, x)|
$$

Notice that the inequality $\|u(t)\|_\infty \geq \varepsilon + \max \left( |u(t, 0)|, |u(t, 1)|, \frac{f(t)}{\sigma - \zeta} \right)$ implies that $I(t) \subseteq (0, 1)$. Consequently, we obtain from (5.11), (5.16) and (5.17) for all $t \in [t_1, t_2] \setminus N$:

$$
\|u(t)\|_\infty \geq \varepsilon + \max \left( |u(t, 0)|, |u(t, 1)|, \frac{f(t)}{\sigma - \zeta} \right) \Rightarrow \frac{d}{dt} (\|u(t)\|_\infty) \leq -\zeta \|u(t)\|_\infty
$$

Implication (5.13) is a direct consequence of (5.18) and the fact $t_1, t_2 \in (0, T)$ are arbitrary. If $\zeta > 0$ then implication (5.18) and Lemma 2.14 on page 82 in [11] imply that the following estimate holds for all $t \in [t_1, t_2]$:

$$
\|u(t)\|_\infty \leq \varepsilon + \\
\max \left( \exp(-\zeta (t - t_1)) \|u(t_1)\|_\infty, \sup_{t_1 \leq s \leq t} \left( \max \left( |u(s, 0)|, |u(s, 1)|, \frac{|f(s)|}{\sigma - \zeta} \right) \exp(-\zeta (t - s)) \right) \right)
$$

Since $\varepsilon > 0$ is arbitrary, we conclude from (5.19) that the following estimate holds for all $t \in [t_1, t_2]$:
\[ \|u(t)\|_{\infty} \leq \max \left( \exp (-\zeta (t-t_1)) \|u(t_1)\|_{\infty}, \sup_{0<s\leq t} \left( \max \left( |u(s,0)|, |u(s,1)|, \frac{\|f(s)\|_{\infty}}{\sigma - \zeta} \right) \exp (-\zeta (t-s)) \right) \right) \] (5.20)

Finally, since \( t_1, t_2 \in (0, T) \) are arbitrary and since \( u \in C^0([0,T] \times [0,1]) \) (which implies that \( \lim_{t_1 \to 0^+(t_1)} (\|u(t_1)\|_{\infty}) = \|u[0]\|_{\infty} \) and \( \lim_{t_2 \to T^-} (\|u(t_2)\|_{\infty}) = \|u[T]\|_{\infty} \)), we conclude from (5.20) that (5.12) holds for all \( t \in (0, T] \) and \( \zeta \in (0, \sigma) \). Continuity arguments guarantee that estimate (5.12) holds for \( \zeta = 0 \) as well. The proof is complete. \( \triangle \)

We are now ready to give the proof of Theorem 2.1.

**Proof of Theorem 2.1:** Theorem 2.1 is a direct consequence of Lemma 5.3 applied to the function \( w \in C^0([0,T] \times [0,1]) \) defined by

\[ w(t, x) = u(t,x)/\eta(x), \text{ for all } t \in [0,T], \ x \in [0,1] \] (5.21)

The function \( w \in C^0([0,T] \times [0,1]) \) satisfies the following properties:

1. \( w[t] \in C^2((0,1)) \) for almost all \( t \in (0, T) \),
2. the derivative \( \frac{\partial w}{\partial t}(t, x) \) exists, is a continuous function on \( (0, T) \times [0,1] \).
3. the following equation holds for almost all \( t \in (0, T) \) and for all \( x \in (0,1) \):

\[ \frac{\partial w}{\partial t}(t, x) = a(t, x) \frac{\partial^2 w}{\partial x^2}(t, x) + \left( 2a(t, x) \frac{\partial w}{\partial x}(t, x) + b(t, x) \right) \frac{\partial w}{\partial x}(t, x) + \frac{1}{\eta^2(x)} \left( a(t, x) \eta''(x) + b(t, x) \eta'(x) + c(t, x) \eta(x) \right) w(t, x) + \frac{f(t,x)}{\eta(x)} \] (5.22)

Notice that definition (5.21) implies that \( \|u[t]\|_{\infty, \eta} = \|u[t]\|_{\infty} \) for all \( t \in [0,T] \).

The proof is complete. \( \triangle \)

For the proof of Theorem 2.2 we need an additional auxiliary result, which provides an estimate for the solution of (2.1) under (2.2) and (5.11). The estimate is different from the one provided by Lemma 5.3 and the solution of (2.1) is assumed to be differentiable with respect to \( x \) at the boundary of the domain.

**Lemma 5.4:** Let \( T > 0, a, b, c : (0, T) \times (0,1) \to \mathbb{R}, f : (0, T) \times (0,1) \to \mathbb{R} \) with \( \sup_{0 < x < 1, 0 < t \leq T} (|f(t,x)|) < +\infty \) be given. Let \( u \in C^0([0,T] \times [0,1]) \) be a given function with \( u[t] \in C^2((0,1)) \) for almost all \( t \in (0, T) \), for which the derivatives \( \frac{\partial^2 u}{\partial x^2}(t,0), \frac{\partial^2 u}{\partial x^2}(t,1) \) exist for all \( t \in (0, T) \) and the derivative \( \frac{\partial u}{\partial x}(t, x) \) is a continuous function on \( (0, T) \times [0,1] \) that satisfies equation (2.1). Suppose that (2.2) and (5.11) hold. Then the following estimate holds for all \( \zeta \in [0, \sigma), g_0, g_1 : (0, T] \to (0, +\infty), k_0, k_1 : (0, T] \to [1, +\infty) \) and \( t \in (0, T] \):

\[ \|u[t]\|_{\infty} \leq \max \left( \exp (-\zeta t) \|u[0]\|_{\infty}, \sup_{0 < x < 1, 0 < t \leq T} \left( \max \left( r_0(s), r_1(s), \frac{\|f[s]\|_{\infty}}{\sigma - \zeta} \right) \exp (-\zeta (t-s)) \right) \right) \] (5.23)

where

\[ r_0(t) := \min \left( \|u(t,0)\|, \|g_0(t) \frac{\partial u}{\partial x}(t,0) - k_0(t) u(t,0)\|, \right), \]
\[ r_1(t) := \min \left( \|u(t,1)\|, \|g_1(t) \frac{\partial u}{\partial x}(t,1) + k_1(t) u(t,1)\| \right), \text{ for } t \in (0, T] \] (5.24)

Moreover, the functional \( V(u) = \|u\|_{\infty} \) satisfies the following implication for all \( \varepsilon > 0, \zeta \in [0, \sigma) \) and \( t \in (0, T) \) a.e.:
Proof: Let \((t, t_1, t_2) \in (0, T)\) with \(t_1 < t_2\) be given. Lemma 5.1 implies that the mapping \([t_1, t_2] \ni t \mapsto \|u(t)\|_\infty\) is an absolutely continuous mapping. Moreover, there exists a Lebesgue measure zero set \(N \subset [t_1, t_2]\) such that equation (5.14) holds. Moreover, we assume that the Lebesgue measure zero set \(N \subset [t_1, t_2]\) has been selected in such a way that (2.1) holds for all \(t \in [t_1, t_2]\) and for all \(x \in (0, 1)\) and \(u(t) \in C^2((0, 1))\) for all \(t \in [t_1, t_2]\setminus N\). Lemma 5.2 implies that (5.15) holds with \(I(t) = \{ y \in [0, 1] : \|u(t, y)\| = \|u(t)\|_\infty \} \). Let (arbitrary) \(\varepsilon > 0\) be given. Inequality (5.15) guarantees that the following implication holds for all \(t \in [t_1, t_2]\setminus N\):

\[
\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right) \Rightarrow \frac{d}{dt} (\|u[t]\|_\infty) \leq -\zeta \|u[t]\|_\infty
\] (5.25)

Pick any \(t \in [t_1, t_2]\setminus N\). Working exactly as in the proof of Lemma 5.3 we show that implication (5.17) holds.

We next show that the condition \(\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right) \) implies that \(I(t) \subseteq (0, 1)\). Suppose that \(\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right)\) and \(0 \in I(t)\). Definition (5.24) implies that \(r_0(t) = \|g_0(t)\|_{\mathcal{X}}\) \(0 < k_0(t)u(t, 0)\) which combined with the fact \(\|u[t]\|_\infty > r_0(t)\) gives

\[
k_0(t)u(t, 0) - \|u[t]\|_\infty < g_0(t) \frac{\partial u}{\partial x} (t, 0) < \|u[t]\|_\infty + k_0(t)u(t, 0) \] (5.27)

If \(u(t, 0) = \|u[t]\|_\infty\) then (5.27) in conjunction with the facts that \(k_0(t) \geq 1\), \(g_0(t) > 0\) gives \(\frac{\partial u}{\partial x} (t, 0) > 0\), which contradicts the fact that \(u\) has a maximum at \(x = 0\). If \(u(t, 0) = -\|u[t]\|_\infty\) then (5.27) in conjunction with the facts that \(k_0(t) \geq 1\), \(g_0(t) > 0\) gives \(\frac{\partial u}{\partial x} (t, 0) < 0\), which contradicts the fact that \(u\) has a minimum at \(x = 0\).

We conclude that the condition \(\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right)\) implies that \(0 \notin I(t)\).

Suppose that \(\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right)\) and \(1 \in I(t)\). Definition (5.24) implies that \(r_1(t) = \|g_1(t)\|_{\mathcal{X}} < 1\) \(r_1(t, 1)\) which combined with the fact \(\|u[t]\|_\infty > r_1(t)\) gives

\[
-k_1(t)u(t, 1) - \|u[t]\|_\infty < g_1(t) \frac{\partial u}{\partial x} (t, 1) < \|u[t]\|_\infty - k_1(t)u(t, 1) \] (5.28)

If \(u(t, 1) = \|u[t]\|_\infty\) then (5.28) in conjunction with the facts that \(k_1(t) \geq 1\), \(g_1(t) > 0\) gives \(\frac{\partial u}{\partial x} (t, 1) < 0\), which contradicts the fact that \(u\) has a maximum at \(x = 1\). If \(u(t, 1) = -\|u[t]\|_\infty\) then (5.28) in conjunction with the facts that \(k_1(t) \geq 1\), \(g_1(t) > 0\) gives \(\frac{\partial u}{\partial x} (t, 1) > 0\), which contradicts the fact that \(u\) has a minimum at \(x = 1\).

We conclude that the condition \(\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right)\) implies that \(1 \notin I(t)\).

Since the inequality \(\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right)\) implies that \(I(t) \subseteq (0, 1)\), we obtain from (5.11), (5.26) and (5.17) for all \(t \in [t_1, t_2]\setminus N:\n
\[
\|u[t]\|_\infty \geq \varepsilon + \max \left( r_0(t), r_1(t), \frac{\|f[t]\|_\infty}{\sigma - \zeta} \right) \Rightarrow \frac{d}{dt} (\|u[t]\|_\infty) \leq -\zeta \|u[t]\|_\infty
\] (5.29)

Implication (5.25) is a direct consequence of (5.29) and the fact \(t_1, t_2 \in (0, T)\) are arbitrary. If \(\zeta > 0\) then implication (5.29) and Lemma 2.14 on page 82 in [11] imply that the following estimate holds for all \(t \in [t_1, t_2]::

\[
\|u[t]\|_\infty \leq \varepsilon + \max \left( \exp \left( -\zeta (t - t_1) \right) \|u[t_1]\|_\infty, \sup_{t_2 \leq s \leq t} \left( \max \left( r_0(s), r_1(s), \frac{\|f[s]\|_\infty}{\sigma - \zeta} \right) \exp \left( -\zeta (t - s) \right) \right) \right)
\] (5.30)
Proof:
Let \( \partial_u \) be given. Suppose that \( \varepsilon > 0 \) is arbitrary, we conclude from (5.30) that the following estimate holds for all \( t \in [t_1, t_2] \):

\[
\|u\|_\infty \leq \max \left( \exp (-\zeta (t - t_1)), \|u_0\|_\infty \right) \max_{t_1 \leq s \leq t} \left( \max \left( r_0(s), r_1(s), \frac{\|f(s)\|_\infty}{\sigma - \zeta} \right) \exp (-\zeta (t - s)) \right)
\] (5.31)

Finally, since \( t_1, t_2 \in (0, T) \) are arbitrary and since \( u \in C^0([0, T] \times [0, 1]) \) (which implies that \( \lim_{t_1 \to 0^+} (\|u(t_1)\|_\infty) = \|u[0]\|_\infty \) and \( \lim_{t_2 \to T^-} (\|u[t_2]\|_\infty) = \|u[T]\|_\infty \)), we conclude from (5.31) that (5.23) holds for all \( t \in (0, T] \) and \( \zeta \in (0, \sigma) \).

Continuity arguments guarantee the fact that estimate (5.23) holds for \( \zeta = 0 \) as well. The proof is complete. \( \Box \)

We are now ready to provide the proof of Theorem 2.2.

Proof of Theorem 2.2: Theorem 2.2 is a direct consequence of Lemma 5.4 applied to the function \( w \in C^0([0, T] \times [0, 1]) \) defined by (5.21). \( \Box \)

We next provide the proof of Corollary 2.3.

Proof of Corollary 2.3: We simply apply Theorem 2.2 with

1. \( g_0(t) \equiv \frac{\mu_0 \eta(0)}{\mu_0 + \eta(0)}, \) \( k_0(t) \equiv 1 \) and arbitrary \( g_1 : (0, T) \to (0, +\infty), k_1 : (0, T) \to [1, +\infty) \) when (2.11) holds,
2. \( g_1(t) \equiv \frac{\mu_1 \eta(1)}{\mu_1 + \eta(1)}, \) \( k_1(t) \equiv 1 \) and arbitrary \( g_0 : (0, T) \to (0, +\infty), k_0 : (0, T) \to [1, +\infty) \) when (2.12) holds,
3. \( g_0(t) \equiv \frac{\mu_0 \eta(0)}{\mu_0 + \eta(0)}, \) \( k_0(t) \equiv 1, g_1(t) \equiv \frac{\mu_1 \eta(1)}{\mu_1 + \eta(1)}, k_1(t) \equiv 1, \) when (2.13) holds.

The proof is complete. \( \Box \)

For the proofs of Theorem 4.1 and Theorem 4.2 we also need some auxiliary results. The following two lemmas provide well-known maximum principles and are given here only for completeness reasons (they are nothing new but we have not been able to find a similar statement to the statement of Lemma 5.6 in the literature).

Lemma 5.5: Let \( T > 0, a, b, c : (0, T) \times (0, 1) \to \mathbb{R}, f : (0, T) \times (0, 1) \to \mathbb{R} \) with \( \sup_{0 < \tau < 1, 0 < \sigma < T} (f(t, x)) < 0 \) be given. Suppose that \( u \in C^0([0, T] \times [0, 1]) \) is a given function with \( u[t] \in C^2((0, 1)) \) for all \( t \in (0, T) \), for which the derivative \( \frac{\partial f}{\partial T}(t, x) \) is a continuous function on \( (0, T) \times (0, 1) \) and satisfies (4.1). Moreover, suppose that (2.2) holds and that

\[
c(t, x) \leq 0, \text{ for all } t \in (0, T), x \in (0, 1)
\] (5.32)

\[
u(0, x) \leq 0, \text{ for all } x \in [0, 1]
\] (5.33)

\[
\begin{align*}
u(t, 0) & \leq 0 \text{ and } u(t, 1) \leq 0, \text{ for all } t \in [0, T] \\
\max \{ u(t, x) : t \in [0, T] \times [0, 1] \} & \leq 0.
\end{align*}
\] (5.34)

Then \( \max \{ u(t, x) : t \in [0, T] \times [0, 1] \} \leq 0. \)

Proof: Let \( t_2 \in (0, T) \) be given (arbitrary). Suppose that \( \max \{ u(t, x) : t \in [0, t_2] \times [0, 1] \} > 0. \) Then (by continuity of \( u \) and (5.33), (5.34)) there exists \( (t^*, x^*_t) \in (0, t_2] \times (0, 1) \) such that

\[
u(t^*, x^*_t) = \max \{ u(t, x) : t \in [0, t_2] \times [0, 1] \} > 0.
\]
If $t^* \in (0, t_2)$ then $\frac{\partial u}{\partial t}(t^*, x^*) = \frac{\partial u}{\partial x}(t^*, x^*) = 0$ and $\frac{\partial^2 u}{\partial x^2}(t^*, x^*) \leq 0$, and we obtain from (2.1), (2.2), (5.32) and the fact that
\[
\sup_{0 < x < 1, 0 < t < T}(f(t, x)) < 0:
\]
\[
\frac{\partial u}{\partial t}(t^*, x^*) = a(t^*, x^*)\frac{\partial^2 u}{\partial x^2}(t^*, x^*) + b(t^*, x^*)\frac{\partial u}{\partial x}(t^*, x^*) + c(t^*, x^*)u(t^*, x^*) + f(t^*, x^*)
\]
\[
= a(t^*, x^*)\frac{\partial^2 u}{\partial x^2}(t^*, x^*) + c(t^*, x^*)u(t^*, x^*) + f(t^*, x^*) < 0
\]
\[
(5.35)
\]
The above inequality contradicts the fact that $\frac{\partial u}{\partial t}(t^*, x^*) = 0$. If $t^*_2 = 0$ then $\frac{\partial u}{\partial t}(t^*, x^*) \geq 0$, $\frac{\partial u}{\partial x}(t^*, x^*) = 0$ and $\frac{\partial^2 u}{\partial x^2}(t^*, x^*) \leq 0$. Once again, using (2.1), (2.2), (5.32) and the fact that $\sup_{0 < x < 1, 0 < t < T}(f(t, x)) < 0$, we obtain inequality (5.35), which contradicts the fact that $\frac{\partial u}{\partial t}(t^*, x^*) \geq 0$.

Therefore, we conclude that $\max \{u(t, x) : t \in [0, t_2] \times [0, 1]\} \leq 0$. Since $t_2 \in (0, T)$ is arbitrary and $u \in C^0([0, T] \times [0, 1])$, we obtain that $\max \{u(t, x) : t \in [0, T] \times [0, 1]\} = 0$.

**Lemma 5.6:** Let $T > 0$, $a, b, c : (0, T) \times (0, 1) \to \mathbb{R}$, $f : (0, T) \times (0, 1) \to \mathbb{R}$ with $\sup_{0 < x < 1, 0 < t < T}(f(t, x)) < 0$ be given. Suppose that $u \in C^1([0, T] \times [0, 1])$ is a given function with $u(t) \in C^2((0, 1)) \cap C^1([0, 1])$ for all $t \in (0, T)$, for which the derivative $\frac{\partial u}{\partial t}(t, x)$ is a continuous function on $(0, T) \times (0, 1)$ and satisfies (4.1). Suppose that (2.2), (5.32), (5.33) hold and that there exist functions $g_0, g_1 : (0, T) \to [0, +\infty)$, such that the following conditions hold for all $t \in (0, T)$:
\[
\min \left( u(t, 1), g_1(t) \frac{\partial u}{\partial x}(t, 1) + u(t, 1) \right) \leq 0
\]
\[
(5.36)
\]
\[
\min \left( u(t, 0), u(t, 0) - g_0(t) \frac{\partial u}{\partial x}(t, 0) \right) \leq 0
\]
\[
(5.37)
\]
Then $\max \{u(t, x) : t \in [0, T] \times [0, 1]\} = 0$.

**Proof:** Let $t_2 \in (0, T)$ be given (arbitrary). Suppose that $\max \{u(t, x) : t \in [0, t_2] \times [0, 1]\} > 0$. Then (by continuity of $u$ and (5.33)) there exists $(t^*, x^*) \in (0, t_2] \times [0, 1]$ such that $u(t^*, x^*) = \max \{u(t, x) : t \in [0, t_2] \times [0, 1]\} > 0$. We next show that $x^* \in (0, 1)$. Indeed, if $x^* = 1$ then $\frac{\partial u}{\partial x}(t^*, 1) \geq 0$. Moreover, (5.36) and the fact that $u(t^*, 1) \geq 0$ imply that $g_1(t^*) \frac{\partial u}{\partial x}(t^*, 1) + u(t^*, 1) \leq 0$. However, since $g_1(t^*) \geq 0$ and $\frac{\partial u}{\partial x}(t^*, 1) \geq 0$ we obtain $g_1(t^*) \frac{\partial u}{\partial x}(t^*, 1) + u(t^*, 1) \geq u(t^*, 1)$, a contradiction. Similarly, if $x^* = 0$ then $\frac{\partial u}{\partial x}(t^*, 0) \leq 0$. Moreover, (5.37) and the fact that $u(t^*, 0) \geq 0$ imply that $g_0(t^*) \frac{\partial u}{\partial x}(t^*, 0) - u(t^*, 0) \geq 0$. However, since $g_0(t^*) \geq 0$ and $\frac{\partial u}{\partial x}(t^*, 0) \leq 0$ we obtain $g_0(t^*) \frac{\partial u}{\partial x}(t^*, 0) - u(t^*, 0) \leq -u(t^*, 0) < 0$, a contradiction.

The rest of the proof is exactly the same with the proof of Lemma 5.5.

The following two lemmas are consequences of Lemma 5.5 and Lemma 5.6.

**Lemma 5.7:** Let $T > 0$, $a, b, c : (0, T) \times (0, 1) \to \mathbb{R}$, $f : (0, T) \times (0, 1) \to \mathbb{R}$ with $\sup_{0 < x < 1, 0 < t < T}(\|f(t, x)\|) < +\infty$ be given. Suppose that $u \in C^0([0, T] \times [0, 1])$ is a given function with $u(t) \in C^2((0, 1))$ for all $t \in (0, T)$, for which the derivative $\frac{\partial u}{\partial t}(t, x)$ is a continuous function on $(0, T) \times (0, 1)$ and satisfies (4.1). Moreover, suppose that (2.2) and (5.11) hold. Then the following estimate holds for all $t \in (0, T)$:
\[
\|u(t)\| \leq \max \left( \|u(0)\|, \sup_{0 < s < t} \left( \max \{\|u(s, 0)\|, \|u(s, 1)\|, \sigma^{-1} \|f(s)\|\} \right) \right)
\]
\[
(5.38)
\]

**Proof:** Let $t_2 \in (0, T)$, $\varepsilon > 0$ be arbitrary given constants and define
\[
M(t_2) := \varepsilon + \max \left( \|u(0)\|, \sup_{0 < t < t_2} \left( \max \{\|u(s, 0)\|, \|u(s, 1)\|, \sigma^{-1} \|f(s)\|\} \right) \right)
\]
\[
(5.39)
\]
The function $\tilde{u}(t,x) = u(t,x) - M(t_2)$ satisfies all requirements of Lemma 5.5 with $t_2$ in place of $T$ and $\hat{f}(t,x) = f(t,x) + c(t,x)M(t_2)$ in place of $f(t,x)$. Notice that by virtue of (5.11) we get $\hat{f}(t,x) \leq f(t,x) - \sigma M(t_2)$ for all $t \in (0,t_2)$, $x \in (0,1)$ and since (5.39) implies that $M(t_2) \geq \varepsilon + \sigma^{-1} \|f[t]\|_{\infty} \geq \varepsilon + \sigma^{-1} f(t,x)$ for all $t \in (0,t_2)$, $x \in (0,1)$, we obtain that $\sup_{0 < x < 1, 0 < t < t_2} (\hat{f}(t,x)) \leq -\sigma \varepsilon < 0$. Consequently, we obtain from Lemma 5.5:

$$u(t,x) \leq M(t_2) \text{ for all } t \in [0,t_2], \ x \in [0,1]$$  (5.40)

The function $\tilde{u}(t,x) = -u(t,x) - M(t_2)$ satisfies all requirements of Lemma 5.5 with $t_2$ in place of $T$ and $\hat{f}(t,x) = -f(t,x) - c(t,x)M(t_2)$ in place of $f(t,x)$. Notice that by virtue of (5.11) we get $\hat{f}(t,x) \leq -f(t,x) - \sigma M(t_2)$ for all $t \in (0,t_2), \ x \in (0,1)$ and since (5.39) implies that $M(t_2) \geq \varepsilon + \sigma^{-1} \|f[t]\|_{\infty} \geq \varepsilon - \sigma^{-1} f(t,x)$ for all $t \in (0,t_2), \ x \in (0,1)$, we obtain that $\sup_{0 < x < 1, 0 < t < t_2} (\hat{f}(t,x)) \leq -\varepsilon \sigma < 0$. Consequently, we obtain from Lemma 5.5:

$$-u(t,x) \leq M(t_2) \text{ for all } t \in [0,t_2], \ x \in [0,1]$$  (5.41)

Combining (5.40) and (5.41) we get the estimate $\|u[t_2]\|_{\infty} \leq M(t_2)$. The fact that $t_2 \in (0,T)$ and $\varepsilon > 0$ are arbitrary in conjunction with definition (5.39) implies that (5.38) holds. <

**Lemma 5.8:** Let $T > 0, \ a, b, c : (0,T) \times (0,1) \to \mathbb{R}, \ f : (0,T) \times (0,1) \to \mathbb{R}$ with $\sup_{0 < x < 1, 0 < t < T} (\|f(t,x)\|_{\infty}) < +\infty$ be given. Suppose that $u \in C^0([0,T] \times [0,1])$ is a function with $u[t] \in C^2((0,1)) \cap C^1([0,1])$ for all $t \in (0,T)$, for which the derivative $\frac{\partial u}{\partial x}(t,x)$ is a continuous function on $(0,T) \times (0,1)$ and satisfies (4.1). Suppose that (2.2), (5.11) hold. Then the following estimate holds for all $g_0, g_1 : (0,T) \to [0, +\infty), \ k_0, k_1 : (0,T) \to [1, +\infty)$ and $t \in (0,T)$:

$$\|u[t]\|_{\infty} \leq \max \left( \|u[0]\|_{\infty}, \sup_{0 < s < t} (\max (\varphi_0(s), \varphi_1(s), \sigma^{-1} \|f[s]\|_{\infty})) \right)$$  (5.42)

where

$$\varphi_0(t) := \min \left( \|u(t,0)\|, \left|g_0(t) \frac{\partial u}{\partial x}(t,0) - k_0(t) u(t,0)\right|, \text{ for } t \in (0,T) \right)$$  (5.43)

$$\varphi_1(t) := \min \left( \|u(t,1)\|, \left|g_1(t) \frac{\partial u}{\partial x}(t,1) + k_1(t) u(t,1)\right|, \text{ for } t \in (0,T) \right)$$  (5.44)

**Proof:** Let $t_2 \in (0,T), \ v > 0$ be arbitrary given constants and define

$$M(t_2) := \varepsilon + \max \left( \|u[0]\|_{\infty}, \sup_{0 < s < t_2} (\max (\varphi_0(s), \varphi_1(s), \sigma^{-1} \|f[s]\|_{\infty})) \right)$$  (5.45)

The function $\tilde{u}(t,x) = u(t,x) - M(t_2)$ satisfies all requirements of Lemma 5.6 with $t_2$ in place of $T$ and $\hat{f}(t,x) = f(t,x) + c(t,x)M(t_2)$ in place of $f(t,x)$. Notice that by virtue of (5.11) we get $\hat{f}(t,x) \leq f(t,x) - \sigma M(t_2)$ for all $t \in (0,t_2), \ x \in (0,1)$ and since (5.39) implies that $M(t_2) \geq \varepsilon + \sigma^{-1} \|f[t]\|_{\infty} \geq \varepsilon - \sigma^{-1} f(t,x)$ for all $t \in (0,t_2), \ x \in (0,1)$, we obtain that $\sup_{0 < x < 1, 0 < t < t_2} (\hat{f}(t,x)) \leq -\sigma \varepsilon < 0$. Moreover, notice that definitions (5.43), (5.44), (5.45) and the fact that $k_0(t) \geq 1, k_1(t) \geq 1$ for all $t \in (0,T)$, imply that

$$\min \left( \|u(t,1)\|, \left|\frac{g_1(t) \partial u}{\partial x}(t,1) + u(t,1)\right|, \right) \leq \min \left( \|u(t,1)\|, \left|\frac{g_1(t) \partial u}{\partial x}(t,1) + u(t,1)\right|, \right) \leq \varphi_1(t) \leq M(t_2)$$

and
for all \( t \in (0, t_2) \). Consequently, \( \min \left( \tilde{u}(t, 1), 0 \right) - \frac{g(t)}{k_1(t)} \frac{\partial u}{\partial x}(t, 1) + \tilde{u}(t, 1) \leq 0 \) and \( \min \left( \tilde{u}(t, 0), 0 \right) - \frac{g(t)}{k_0(t)} \frac{\partial u}{\partial x}(t, 0) \leq 0 \) for all \( t \in (0, t_2) \). By using Lemma 5.6 we obtain estimate (5.40).

The function \( \tilde{u}(t, x) = -u(t, x) - M(t_2) \) satisfies all requirements of Lemma 5.6 with \( t_2 \) in place of \( t \) and \( \tilde{f}(t, x) = -f(t, x) + c(t, x)M(t_2) \) in place of \( f(t, x) \). Notice that by virtue of (5.11) we get \( \tilde{f}(t, x) \leq -f(t, x) - \sigma M(t_2) \) for all \( t \in (0, t_2), x \in (0, 1) \) and since (5.39) implies that \( M(t_2) \geq \varepsilon + \sigma^{-1} \|f(t)\|_\infty \geq \varepsilon - \sigma^{-1} f(t, x) \) for all \( t \in (0, t_2), x \in (0, 1) \), we obtain that

\[
\sup_{0 < t < 1, 0 \leq s < t_2} (\tilde{f}(t, s)) \leq -\sigma \varepsilon < 0.
\]

Moreover, notice that definitions (5.43), (5.44), (5.45) imply that

\[
\min \left( -u(t, 1), -\frac{g(t)}{k_1(t)} \frac{\partial u}{\partial x}(t, 1) - u(t, 1) \right) \
\leq \min \left( |u(t, 1)|, |\frac{g(t)}{k_1(t)} \frac{\partial u}{\partial x}(t, 1) + u(t, 1)| \right) \
\leq \min \left( |u(t, 1)|, k_1(t) \left( \frac{g(t)}{k_1(t)} \frac{\partial u}{\partial x}(t, 1) + u(t, 1) \right) \right) \leq \varphi_1(t) \leq M(t_2)
\]

and

\[
\min \left( -u(t, 0), -u(t, 0) + \frac{g(t)}{k_0(t)} \frac{\partial u}{\partial x}(t, 0) \right) \
\leq \min \left( |u(t, 0)|, |\frac{g(t)}{k_0(t)} \frac{\partial u}{\partial x}(t, 0) - u(t, 0)| \right) \
\leq \min \left( |u(t, 0)|, k_0(t) \left( \frac{g(t)}{k_0(t)} \frac{\partial u}{\partial x}(t, 0) - u(t, 0) \right) \right) \leq \varphi_0(t) \leq M(t_2)
\]

for all \( t \in (0, t_2) \). Consequently, \( \min \left( \tilde{u}(t, 1), 0 \right) - \frac{g(t)}{k_1(t)} \frac{\partial u}{\partial x}(t, 1) + \tilde{u}(t, 1) \leq 0 \) and \( \min \left( \tilde{u}(t, 0), 0 \right) - \frac{g(t)}{k_0(t)} \frac{\partial u}{\partial x}(t, 0) \leq 0 \) for all \( t \in (0, t_2) \). Consequently, we obtain from Lemma 5.6 estimate (5.41).

Combining (5.40) and (5.41) we get the estimate \( \|u(t_2)\|_\infty \leq M(t_2) \). The fact that \( t_2 \in (0, T) \) and \( \varepsilon > 0 \) are arbitrary in conjunction with definition (5.45) implies that (5.42) holds.

We are now ready to give the proof of Theorem 4.1.

**Proof of Theorem 4.1:** Let \( \zeta \in [0, \sigma) \) be a given constant (arbitrary). Theorem 4.1 is a direct consequence of Lemma 5.7 applied to the function \( w \in C^0([0, T] \times [0, 1]) \) defined by

\[
w(t, x) = \exp(\zeta t)u(t, x)/\eta(x), \quad \text{for all } t \in [0, T], \: x \in [0, 1]
\]

(5.46)
The function \( w \in C^0([0, T] \times [0, 1]) \) satisfies the following properties:

1. \( w[t] \in C^2((0, 1)) \) for almost all \( t \in (0, T) \),
2. the derivative \( \frac{\partial w}{\partial t}(t, x) \) exists, is a continuous function on \( (0, T) \times (0, 1) \),
3. the following equation holds for all \( t \in (0, T) \) and \( x \in (0, 1) \):

\[
\frac{\partial w}{\partial t}(t, x) = a(t, x) \frac{\partial^2 w}{\partial x^2}(t, x) + \left( 2a(t, x) \frac{\eta'(x)}{\eta(x)} + b(t, x) \right) \frac{\partial w}{\partial x}(t, x) + \frac{1}{\eta(x)} (a(t, x) \eta''(x) + b(t, x) \eta'(x) + (c(t, x) + \zeta) \eta(x)) w(t, x) + \exp(\zeta t) \frac{f(t, x)}{\eta(x)}
\]

(5.47)

Notice that definition (5.46) implies that \( \|u[t]\|_{\infty, \eta} = \exp(-\zeta t) \|w[t]\|_\infty \) for all \( t \in [0, T] \). The proof is complete.

\( \triangle \)
Finally, we give the proof of Theorem 4.2.

**Proof of Theorem 4.2:** Let \( \zeta \in [0, \sigma) \) be a given constant (arbitrary). Theorem 2.2 is a direct consequence of Lemma 5.8 applied to the function \( w \in C^\alpha([0, T] \times [0, 1]) \) defined by (5.46). \( \blacksquare \)

### 6. Concluding Remarks

The present paper provided tools for the derivation of ISS estimates in the sup norm of the state. More specifically, we provided novel ISS-style maximum principle estimates which are valid for classical solutions of parabolic PDEs. The obtained results can be applied to nonlinear 1-D parabolic PDEs, as illustrated by three illustrative examples.

However, the main results have some disadvantages. The main disadvantages of the main results of the paper are:

1) the fact that they can only be applied to PDEs for which classical solutions can be proved to exist (at least locally; see [4,18]). In some cases, we are in a position to prove the existence of a continuous solution (so that the sup norm estimates make sense) which satisfies the PDE in a weak sense (see for example [27]). For such cases, Theorem 2.1 and Theorem 2.2 cannot be applied. Therefore, there is a need to extend the results for weaker notions of solutions. This is going to be the topic of future research.

2) the fact that they can only be applied to parabolic PDEs with one spatial dimension. The extension to parabolic PDEs with \( n \)-dimensional domains is going to be another topic of future research.

**Acknowledgements:** The authors would like to thank Professor Renkun Chen for discussions about the dependence of heat conductivity of solids on temperature. The authors would also like to thank the anonymous reviewer who suggested to us the use of maximum principles for the derivation of the ISS estimates.

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