1. Introduction

Fourier transforms have been widely used in image processing, pattern recognition and other engineering fields [1]. By representing image as hypercomplex numbers, especially the quaternions discovered by Hamilton [2], Hypercomplex Fourier transform is proposed as generalization of quaternion Fourier transform for color image processing [3], [4]. Efficient algorithm for quaternion Fourier transform is discussed by using two complex two dimensional Fourier transforms [5]. The relationship between right-side quaternion Fourier transform and left-side quaternion Fourier transform is established [6]. Fourier transform for biquaternion-valued signals and its fast algorithm that based on four complex two dimension Fourier transforms is proposed [7]. Based on hypercomplex Fourier transform, effective algorithms for motion estimation in color image sequences are studied [8]. Quaternion Fourier-Mellin moments are proposed as rotation and scale invariant feature by using quaternion Fourier transform [9]. Rather than separating a color image into several scalar images, Hypercomplex Fourier transform treats it as vector field and acts as holistic manner.

By applying Fourier analysis to polar and spherical coordinates, Polar Fourier Descriptor (PFD) and Spherical Fourier Descriptor (SFD) are proposed as rotation invariant descriptors for analyzing 2D and 3D images, and they demonstrated superior performances comparable with other methods [10]. PFD introduces Fourier-Bessel series that is mainly used on physics-related applications [11], [12] to image analysis. Different from other Fourier descriptors that have been used for shape description [13] and image retrieval [14], [15], PFD and SFD hold orthogonal property and can characterize the image using a set of mutually independent functions. Unfortunately, the high computational complexity is the constraint for widely use because the coefficients computation involves many Bessel function, associated Legendre polynomials [16] and trigonometric computations. Our previous work [17] studied fast algorithms to reduce the computational complexity.

This paper focuses on hypercomplex polar Fourier analysis and its properties. Inspired by the hypercomplex Fourier transforms, we establish theory for polar Fourier analysis with hypercomplex numbers representation. The proposed transform is reversible that means can be used for signal reconstruction as shown in Fig. 1. Hypercomplex Polar Fourier Descriptor (HPFD) is proposed as rotation invariant feature that can be used to represent image visual patterns. HPFD is not scale invariant comparing to [9]. Due to non commutative property of hypercomplex multiplication, both left-side and right-side hypercomplex polar Fourier analysis are studied. The proposed method treats image in a holistic manner and visual patterns are directly extracted from color images. To demonstrate the usefulness of proposed method as image analysis tool, experiments like image reconstruction, color plate test and image database retrieval are designed.

The organization of this paper is as follows. The basic theories of polar Fourier analysis, quaternion number and hypercomplex Fourier transform including mathematics descriptions are provided in Sect. 2. The proposed hypercomplex polar Fourier analysis with its properties are presented in Sect. 3. In Sect. 4, three experiments are designed to demonstrate the properties of the proposed method. The experimental results illustrate the effectiveness of our proposed method. Finally, Sect. 5 concludes this study.
2.1 Polar Fourier Analysis

Given a 2D image function \(f(x, y)\), it can be transformed from cartesian coordinates to polar coordinates \(f(r, \varphi)\), where \(r\) and \(\varphi\) denote radius and azimuth respectively. It is defined on the unit circle that \(r \leq 1\), and can be expanded with respect to the basis functions \(\Psi_{nm}(r, \varphi)\) as

\[
f(r, \varphi) = \sum_{n=1}^{\infty} \sum_{m=-\infty}^{\infty} P_{nm} \Psi_{nm}(r, \varphi),
\]

where the coefficient is

\[
P_{nm} = \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} f(r, \varphi) \Psi_{nm}^{*}(r, \varphi) r dr d\varphi.
\]

The basis function is given by

\[
\Psi_{nm}(r, \varphi) = R_{nm}(r) \Phi_{m}(\varphi),
\]

where

\[
R_{nm}(r) = \frac{1}{\sqrt{N_{nm}}} J_{m}(x_{nm} r),
\]

in which \(J_{m}\) is the \(m\)-th order first class Bessel series [16], and

\[
\Phi_{m}(\varphi) = \frac{1}{\sqrt{2\pi}} e^{im\varphi}.
\]

\(N_{nm}\) can be deduced by imposing boundary conditions according to the Sturm-Liouville (S-L) theory [18]. Two boundary conditions are interesting. With zero-value boundary condition,

\[
N_{nm}^{(m)} = \frac{1}{2} \left(1 - \frac{m^2}{x_{nm}^2}\right) J_{m}^2(x_{nm}),
\]

in which \(x_{nm}\) is the \(n\)th positive root for \(J_{m}(x)\).

Rewrite (2) with (3)–(7),

\[
P_{nm} = \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} f(r, \varphi) R_{nm}(r) e^{-im\varphi} r dr d\varphi.
\]

\(|P_{nm}|\) is rotation invariant and is called Polar Fourier Descriptors (PFD). \(P_{nm}\) is complex number and its real part is

\[
Re(P_{nm}) = \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} f(r, \varphi) R_{nm}(r) \cos(m\varphi) r dr d\varphi,
\]

and its imaginary part is

\[
Im(P_{nm}) = \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} f(r, \varphi) R_{nm}(r) \sin(m\varphi) r dr d\varphi,
\]

these two equations are used to deduce the relationship between Hypercomplex polar Fourier descriptor and conventional PFD as shown in Sect.3.4. By using mathematical properties of trigonometric functions and associated Legendre polynomials, fast algorithms [17] are proposed to compute \(P_{nm}\) efficiently from digital images. Its computation time is one eighth of traditional one [10].

2.2 Quaternion Number

As a type of hypercomplex number and generalization of complex number, the quaternion was formally discusses by Hamilton in 1843 [2]. Its properties and applications have been studied [19]. Complex number has two components,
the real part and imaginary part. Quaternion has one real part and three imaginary parts. Given \(a, b, c, d \in \mathbb{R}\), a quaternion \(q \in \mathbb{H}\) (denotes Hamilton) is defined as

\[
q = S(q) + V(q), \quad S(q) = a, \quad V(q) = bi + cj + dk \tag{11}
\]

where \(S(q)\) is scalar part and \(V(q)\) is vector part. \(i, j, k\) are imaginary operators obeying the following rules

\[
i^2 = j^2 = k^2 = -1, \quad ij = -ji = k, \quad \text{and} \quad jk = -kj = i,
\tag{12}
\]

From Eq. (12), the multiplication rule of quaternions is not commutative. The conjugate of a quaternion \(q\) is

\[
\overline{q} = S(q) - V(q) = a - bi - cj - dk.
\tag{13}
\]

The norm of quaternion \(q\) is

\[
\|q\| = \sqrt{a^2 + b^2 + c^2 + d^2}.
\tag{14}
\]

Quaternion \(q\) is named as unit quaternion if it is in set

\[
U = \{q | q \in \mathbb{H}, \|q\| = 1\}.
\tag{15}
\]

If quaternion \(q\) in following set,

\[
\mathcal{P} = \{q | q \in \mathbb{H}, S(q) = 0\},
\tag{16}
\]

it is called pure quaternion. The quaternions belonging to set

\[
\mathcal{S} = \{q | q \in U, q \in \mathcal{P}\},
\tag{17}
\]

are called unit pure quaternion. For two quaternions \(p\) and \(q\), following rule holds

\[
\overline{p} \cdot q = \overline{q} \cdot \overline{p}.
\tag{18}
\]

Euler formula holds for hypercomplex numbers,

\[
e^{i\phi} = \cos(\phi) + i \sin(\phi)
\tag{19}
\]

We also have: \(\|e^{i\phi}\| = 1\) The quaternion \(q\) can be represented in polar form: \(q = \|q\|e^{i\phi}\).

Color image can be represented in pure quaternion form [4]

\[
f(x, y) = f_R(x, y)i + f_G(x, y)j + f_B(x, y)k,
\tag{20}
\]

where \(f_R(x, y), f_G(x, y), \text{and } f_B(x, y)\) are the red, green and blue components of the pixel, respectively.

2.3 Hypercomplex Fourier Transform

As the generalization of traditional Fourier transform, hypercomplex Fourier transform, its extensions and applications are studied [3]–[8]. Because of the noncommutative property of quaternion multiplication, three definitions for quaternion Fourier transform (QFT) are defined. The QFTs are defined by placing the integral kernels on the left side, right side and two sides of a quaternion function \(f(x, y)\). Left-side QFT is defined as,

\[
\mathcal{F}^{(0)}(\omega, \nu) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-i(\omega x + \nu y)} f(x, y) dx dy,
\tag{21}
\]

right-side QFT is defined as,

\[
\mathcal{F}^{(1)}(\omega, \nu) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f(x, y) e^{-i(\omega x + \nu y)} dx dy,
\tag{22}
\]

two-sides QFT is defined as,

\[
\mathcal{F}^{(2)}(\omega, \nu) = \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} e^{-i(\omega x + \nu y)} f(x, y) e^{-i(\omega x + \nu y)} dx dy,
\tag{23}
\]

where \(\mu_1\) and \(\mu_2\) are two unit pure quaternions that are orthogonal. Their relationships are studied [6].

3. Hypercomplex Polar Fourier Analysis and Its Properties

Inspired by Hypercomplex Fourier transform, we propose Hypercomplex Polar Fourier analysis. By introducing hypercomplex number to polar Fourier analysis, we define the transform function in Sect. 3.1. Its rotation invariance property is introduced in Sect. 3.2. In Sect. 3.3 relationship between right-side hypercomplex polar Fourier analysis and left-side hypercomplex polar Fourier analysis is established. Expansion of hypercomplex Polar Fourier analysis and its relationship with conventional Polar Fourier analysis are discussed in Sect. 3.4.

3.1 Hypercomplex Polar Fourier Descriptor

Given a 2D function \(f(x, y)\), it can be transformed from cartesian coordinate to polar coordinate \(f(r, \varphi)\), where \(r\) and \(\varphi\) denote radius and azimuth respectively. The following equations transform from cartesian coordinate to polar coordinate,

\[
r = \sqrt{x^2 + y^2},
\tag{24}
\]

and

\[
\varphi = \arctan \frac{y}{x}.
\tag{25}
\]

Hypercomplex Polar Fourier analysis involves points within the largest inner circle of the image. After normalization, it is defined on the unit circle that \(r \leq 1\) and can be expanded with respect to the basis function. Due to the noncommutative property of quaternion multiplication, here we define left-side Hypercomplex Polar Fourier analysis and right-side Hypercomplex Polar Fourier analysis.

Left-side Hypercomplex Polar Fourier analysis is defined as

\[
f(r, \varphi) = \sum_{n=1}^{\infty} \sum_{m=-\infty}^{\infty} R_{nm}(r) e^{im\varphi} \mathcal{H}_{nm}^{(l)},
\tag{26}
\]

where the coefficient is

\[
\mathcal{H}_{nm}^{(l)}[f(r, \varphi); \mu] = \frac{1}{\sqrt{2\pi}} \int_{0}^{2\pi} \int_{0}^{\infty} R_{nm}(r) e^{-im\varphi} f(r, \varphi) r dr d\varphi,
\tag{27}
\]
where $\mu$ is unit pure quaternion and is defined as $\mu = \frac{1}{\sqrt{3}}i + \frac{1}{\sqrt{3}}j + \frac{1}{\sqrt{3}}k$.

Right-side hypercomplex polar Fourier analysis is defined as

$$f(r, \varphi) = \sum_{n=-\infty}^{\infty} \sum_{m=-\infty}^{\infty} HP^r nm f(r) e^{i m \varphi}.$$  \hfill (28)

where the coefficient is

$$HP^r nm[f(r, \varphi); \mu] = \frac{1}{2\pi} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r)f(r, \varphi) e^{-i m \varphi} r dr d\varphi.$$  \hfill (29)

The basis functions with different $m$, $n$ values are shown in Fig. 2. Both left-hand hypercomplex polar Fourier analysis and right-hand hypercomplex polar Fourier analysis are reversible. Figure 1 shown that by using $HP^r nm$, image can be reconstructed. With $n$ increases bigger, more detail part of the image can be reconstructed.

3.2 Rotation Invariance

Given an image $f(r, \varphi)$, after rotated by an angle $\alpha$ the image is $f(r, \varphi + \alpha)$. We have

$$HP^r nm = \frac{1}{2\pi} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r) e^{-im(\varphi + \alpha)} f(r, \varphi + \alpha) r dr d\varphi$$

$$= e^{-i m \alpha} \frac{1}{2\pi} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r) e^{-im \varphi} f(r, \varphi) r dr d\varphi$$

$$= e^{-i m \alpha} HP nm.$$  \hfill (30)

After applying norm operation, we have

$$\|HP nm\| = \|e^{-i m \alpha} HP nm\|$$

$$= \|e^{-i m \alpha}\| \cdot \|HP nm\| = \|HP nm\|.$$  \hfill (31)

As shown in Eq. (31), $\|HP nm\|$ is rotation invariant and is named as Hypercomplex Polar Fourier Descriptor (HPFD). HPFD can be used to represent visual patterns. As hypercomplex polar Fourier analysis uses hypercomplex number representation, HPFD can directly represent patterns from color image.

3.3 Relationship between Right-Side and Left-Side Hypercomplex Polar Fourier Analysis

In this subsection, we discuss about the relationship between right-side hypercomplex polar Fourier analysis coefficient $HP nm$ and left-side one $HP^l nm$. Following the conjugate quaternion multiplication rule as shown in Eq. (18), conjugate operation is applied to $HP^r nm$.

$$\begin{align*}
HP nm[f(r, \varphi); \mu] &= \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r)f(r, \varphi) e^{-i m \varphi} r dr d\varphi \\
&= \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r)e^{-i m \varphi} \cdot f(r, \varphi) r dr d\varphi \\
&= \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r)e^{i m \varphi} \cdot f(r, \varphi) r dr d\varphi \\
&= HP^l nm[f(r, \varphi); -\mu]
\end{align*}$$  \hfill (32)

Equation (32) shows that we can get right-side hypercomplex polar Fourier analysis from left-side one. They have equivalent effect on describing image patterns. In this paper, we use right-side one and denoted as $HP nm$.

3.4 Expansion of $HP nm$

In this subsection, we discuss about the expansion of hypercomplex polar Fourier analysis coefficient and its relationship with conventional polar Fourier analysis coefficient. By substitute Eqs. (9), (10), (19), and (20), we have

$$\begin{align*}
HP nm &= \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r)f(r, \varphi) e^{-i m \varphi} r dr d\varphi \\
&= \frac{1}{\sqrt{2\pi}} \int_{0}^{1} \int_{0}^{2\pi} R_{nm}(r)(fr i + fg j + fb k) \\
&\quad \cdot (\cos(-m \varphi) + \mu \sin(-m \varphi)) r dr d\varphi \\
&= \frac{i}{\sqrt{5}} (\text{Im}(P nm(f r)) + \text{Im}(P nm(f g)) + \text{Im}(P nm(f b))) \\
&\quad + j(\text{Re}(P nm(f r)) + \text{Im}(P nm(f g))) \\
&\quad + k(\text{Re}(P nm(f g)) + \text{Im}(P nm(f b))) \\
&= \frac{1}{\sqrt{5}} (\text{Im}(P nm(f r)) + \text{Im}(P nm(f g)) + \text{Im}(P nm(f b))) \\
&\quad + \left\{ \text{Re}(P nm(f r)) + \frac{1}{\sqrt{3}} [\text{Im}(P nm(f g)) - \text{Im}(P nm(f b))] \right\} i \\
&\quad + \left\{ \text{Re}(P nm(f g)) + \frac{1}{\sqrt{3}} [\text{Im}(P nm(f b)) - \text{Im}(P nm(f r))] \right\} j \\
&\quad + \left\{ \text{Re}(P nm(f b)) + \frac{1}{\sqrt{3}} [\text{Im}(P nm(f r)) - \text{Im}(P nm(f g))] \right\} k
\end{align*}$$  \hfill (33)
is calculated. The smaller the relative error is, the better it works under rotation.

As shown in Table 1, HPFD holds good invariance property under rotation. PFDs of the R, G, B images are calculated and integrated by average. The results are shown in Table 2. From the tables we can observe that mean value and standard deviation of HPFD relative error is smaller than that of PFD relative error. This experiment shows the rotation invariance property of HPFD and demonstrates that processing color image in a holistic way is robust.

4.2 Color Plate

In this experiment, the purpose is to compare the proposed HPFD and PFD for color plate test. As shown in Fig. 4 color plate images were used for color blind test. Figures 4 (a)–(d) are different images in color space. We can observe that they represent 1, 2, 3 and 4 respectively. Unfortunately they share same gray level image as shown in Fig. 4 (e). Both HPFD \( \{ HP_{nm} \mid m = 1, 2, 3, 4, 5, n = 1, 2, 3, 4, 5 \} \) and PFD \( \{ P_{mn} \mid m = 1, 2, 3, 4, 5, n = 1, 2, 3, 4, 5 \} \) are extracted for these four images. Features are extracted and compared with each other by normalized cross correlation,

\[
ncc(P_m, P) = \left( \frac{P_m}{\|P_m\|} \cdot \frac{P}{\|P\|} \right),
\]

where \( \langle \cdot, \cdot \rangle \) is the inner product, \( \| \cdot \| \) is the \( L^2 \) norm and \( P_m \) is the features of match image.

As shown in Table 3 PFD failed to classify these four images. HPFD that process color image in a holistic way can successfully discriminate color images as demonstrated in Table 4.

![Fig. 3](image-url) Standard images for rotation invariance.

![Fig. 4](image-url) Color plate images.
Table 1 Relative error of HPFD under rotation.

| Image | $\eta_{11}$ | $\eta_{12}$ | $\eta_{13}$ | $\eta_{21}$ | $\eta_{22}$ | $\eta_{23}$ | $\eta_{31}$ | $\eta_{32}$ | $\eta_{33}$ | Mean | Stdev |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------|-------|
| a     | 0.016       | 0.014       | 0.091       | 0.015       | 0.011       | 0.180       | 0.040       | 0.047       | 0.048       | 0.027  | 0.036 |
| b     | 0.014       | 0.004       | 0.016       | 0.003       | 0.007       | 0.002       | 0.026       | 0.048       | 0.010       | 0.024  | 0.033 |
| c     | 0.012       | 0.046       | 0.020       | 0.001       | 0.022       | 0.011       | 0.010       | 0.034       | 0.021       | 0.015  | 0.011 |
| d     | 0.007       | 0.001       | 0.002       | 0.007       | 0.001       | 0.023       | 0.012       | 0.005       | 0.060       | 0.025  | 0.037 |
| e     | 0.035       | 0.052       | 0.055       | 0.001       | 0.007       | 0.045       | 0.041       | 0.009       | 0.021       | 0.026  | 0.035 |
| f     | 0.006       | 0.013       | 0.040       | 0.019       | 0.009       | 0.008       | 0.016       | 0.176       | 0.007       | 0.029  | 0.040 |
| g     | 0.004       | 0.004       | 0.003       | 0.014       | 0.021       | 0.032       | 0.011       | 0.012       | 0.032       | 0.022  | 0.030 |
| h     | 0.005       | 0.002       | 0.010       | 0.002       | 0.003       | 0.023       | 0.019       | 0.015       | 0.004       | 0.020  | 0.028 |

Table 2 Relative error of PFD under rotation.

| Image | $\eta_{11}$ | $\eta_{12}$ | $\eta_{13}$ | $\eta_{21}$ | $\eta_{22}$ | $\eta_{23}$ | $\eta_{31}$ | $\eta_{32}$ | $\eta_{33}$ | Mean | Stdev |
|-------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------------|-------|-------|
| a     | 0.032       | 0.014       | 0.105       | 0.017       | 0.024       | 0.182       | 0.108       | 0.052       | 0.049       | 0.033  | 0.039 |
| b     | 0.012       | 0.010       | 0.064       | 0.007       | 0.001       | 0.027       | 0.037       | 0.017       | 0.035       | 0.051  |       |
| c     | 0.013       | 0.039       | 0.021       | 0.003       | 0.025       | 0.012       | 0.010       | 0.035       | 0.019       | 0.018  | 0.011 |
| d     | 0.011       | 0.006       | 0.003       | 0.024       | 0.024       | 0.019       | 0.016       | 0.064       | 0.038       | 0.058  |       |
| e     | 0.044       | 0.052       | 0.075       | 0.003       | 0.015       | 0.053       | 0.071       | 0.009       | 0.047       | 0.038  | 0.054 |
| f     | 0.005       | 0.041       | 0.042       | 0.055       | 0.009       | 0.006       | 0.096       | 0.355       | 0.009       | 0.042  | 0.064 |
| g     | 0.004       | 0.029       | 0.003       | 0.015       | 0.023       | 0.062       | 0.015       | 0.016       | 0.031       | 0.033  | 0.046 |
| h     | 0.017       | 0.023       | 0.009       | 0.016       | 0.042       | 0.021       | 0.061       | 0.016       | 0.023       | 0.031  | 0.043 |

Table 3 Similarity by PFD.

| a     | b     | c     | d     |
|-------|-------|-------|-------|
| 1.000 | 1.000 | 1.000 | 1.000 |

Table 4 Similarity by HPFD.

| a     | b     | c     | d     |
|-------|-------|-------|-------|
| 1.000 | 0.451 | 0.122 | 0.000 |

4.3 Color Image Retrieval

This experiment is designed to demonstrate effectiveness of the proposed method HPFD for color image retrieval. Content based image retrieval uses visual patterns to analyze actual content of images. Local binary pattern (LBP) treats images as local visual textures. By applying uniform operation LBP achieves rotation invariance [23]. Coordinated clusters representation (CCR) extracts spatial correlation between pixel intensities using the distribution function of the occurrence of texture units [24]. CCR and LBP work on gray image. Valuable information are lost by treating color image as gray level. Extending CCR to color image by color quantization, multilayer coordinated clusters representation (ML-CCR) has better retrieval result [25].

In this experiment we use Outex image database [22] that same as [25] (see Fig. 5). Outex image database is taken by rotating hardware device by following angles 0°, 5°, 10°, 15°, 30°, 45°, 60°, 75°, 90°. To search image database, proposed retrieval algorithm works as following steps:

1. For the images $\{f_i(x,y)\}_{i=1,2...}$ in database, every image is processed one by one;
2. Given an image, interest points $\{I_i|i=1,2,...,T\}$ are extracted by interest points detector [26], where $T$ is total number of the interest points;
3. For image patch that is near interest point $I_i$ within radius $R$, hypercomplex polar Fourier descriptor $[HP_{nm}]$ is extracted, in our experiment 25 features ($m = 1, 2, 3, 4, 5$ and $n = 1, 2, 3, 4, 5$) are computed;
4. Normalized cross correlation as shown in Eq. (35) is used to compare similarity of different image patches when retrieve the images. If the $ncc$ is larger than predefined threshold $\tau$. It is treated as matched image patch;
5. Similarity between two images depends on the number of total interest points $T$ and the number of matched ones $M$;

$$sim(f_i(x,y), f_j(x,y)) = \frac{M}{T}. \quad (36)$$

6. The retrieved images are ordered by the similarity value $sim(\cdot, \cdot)$.

The detail experimental results are shown in Table 5. From the result we can observe that CCR and LBP work in gray image. CCR performs worse than LBP with uniform operation. ML-CCR works better than CCR after color quantization. Proposed image retrieval algorithm has promising accuracy. By treating color image in a holistic manner, proposed HPFD is effective for color textures and performs better than PFD. In RGB color space proposed algorithm using HPFD achieves best retrieval rate. This experiment testifies the effectiveness of the proposed method for color image retrieval.

5. Conclusions

In this paper, Hypercomplex Polar Fourier Analysis theory is proposed and its applications are studied. Inspired
by hypercomplex Fourier transform, hypercomplex number theory is introduced to polar Fourier analysis. By treating image in a holistic manner, hypercomplex polar Fourier analysis and mathematical properties are discussed. Hypercomplex Polar Fourier Descriptor that holds rotation invariance property is proposed. The relationship between left-side and right-side Hypercomplex polar Fourier analysis is established. By expanding the hypercomplex polar Fourier analysis coefficient, the relationship between the proposed one and conventional one has been found. Extensive experiments like image reconstruction, rotation invariance evaluation, color plate test and image database retrieval are designed to demonstrate the usefulness of the proposed method. Based on the experimental results, we can find that proposed method can extract valuable information from color images. Future works focus on extensions for spherical Fourier analysis and fast algorithms.

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