No-Touch Radiofrequency Ablation: A Comparison of Switching Bipolar and Switching Monopolar Ablation in Ex Vivo Bovine Liver

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Objective: To evaluate the feasibility, efficiency, and safety of no-touch switching bipolar (SB) and switching monopolar (SM) radiofrequency ablation (RFA) using ex vivo bovine livers.

Materials and Methods: A pork loin cube was inserted as a tumor mimicker in the bovine liver block; RFA was performed using the no-touch technique in the SM (group A1; 10 minutes, n = 10, group A2; 15 minutes, n = 10) and SB (group B; 10 minutes, n = 10) modes. The groups were compared based on the creation of confluent necrosis with sufficient safety margins, the dimensions, and distance between the electrode and ablation zone margin (DEM). To evaluate safety, small bowel loops were placed above the liver surface and 30 additional ablations were performed in the same groups.

Results: Confluent necroses with sufficient safety margins were created in all specimens. SM RFA created significantly larger volumes of ablation compared to SB RFA (all \( p < 0.001 \)). The DEM of group B was significantly lower than those of groups A1 and A2 (all \( p < 0.001 \)). Although thermal injury to the small bowel was noted in 90%, 100%, and 30% of the cases in groups A1, A2, and B, respectively, full depth injury was noted only in 60% of group A2 cases.

Conclusion: The no-touch RFA technique is feasible in both the SB and SM modes; however, SB RFA appears to be more advantageous compared to SM RFA in the creation of an ablation zone while avoiding the unnecessary creation of an adjacent parenchymal ablation zone or adjacent small bowel injuries.

Keywords: Minimally invasive; Bovine; Preclinical; Radiofrequency ablation; No-touch technique; Hepatocellular carcinoma

INTRODUCTION

Radiofrequency ablation (RFA) is the most widely used percutaneous thermal ablation technique for treating primary and metastatic hepatic tumors; it is widely accepted as a potential curative treatment option for early stage hepatocellular carcinoma (HCC) in nonsurgical candidates (1-4). However, RFA has a higher local tumor progression rate compared to surgery (5, 6). Typically, RFA is executed by deploying a monopolar multi-tined or internally cooled electrode into the tumor under the guidance of imaging modalities such as ultrasonography or computed tomography. With the existing single monopolar electrodes, the generation of a sufficient ablation volume including the tumor and a sufficient peritumoral margin (> 5 mm) is not always possible, and requires multiple overlapping ablations (7). To ensure larger or more uniform ablation zones, substantial efforts have been made for improving ablation systems, such as the development of the switching monopolar (SM) or multipolar approach; the modulation of
tissue characteristics including tissue perfusion, thermal, or electrical conductivity; and the combination of RFA with other therapies such as arterial embolization or liposomal doxorubicin (7-13). However, they inevitably increased complexity, complications, and potential toxicity of any compound regimen, and therefore, limitations in clinical efficacy persist (7). Furthermore, with multiple overlapping ablations, tumor seeding along the puncture route, particularly for tumors located on the liver surface, is another concern of the conventional RFA, although this risk can be lowered by tract ablation (14-18).

Recently, a few studies (19-22) demonstrated that multipolar RFA with multiple electrodes could be used for “no-touch” techniques and achieved promising results of high technical success rate, local tumor progression-free survival rate, and no tract seeding episodes in patients with HCCs. Because no-touch RFA is performed by inserting multiple electrodes outside tumors, thus avoiding a direct puncture to the tumors, the risk of tract seeding must be extremely low. However, to create complete necrosis of the target tumor between the electrodes, the mean ablation time was kept relatively long (18.5–27.2 minutes) and a large amount of radiofrequency (RF) energy had to be delivered, which resulted in a large ablation zone outside of the target tumor (19-22). In fact, theoretically, the deposition of a high density current into the target tissue including the tumor would be more easily achievable in the bipolar mode than in the monopolar mode having a centrifugal current flow from the electrode, which might reduce the ablation of the tissue positioned lateral to the electrodes (7). Although multipolar or switching bipolar (SB) RFA has been used for achieving no-touch ablation efficiency (23-25), no study has compared the monopolar and bipolar modes for the no-touch technique to date.

Therefore, we attempted to evaluate the ex vivo feasibility, efficiency, and safety of the no-touch technique in SB and SM modes using a separable clustered multiple electrode and a prototype RFA system that allows the automatic switching of RF energy delivery among the electrodes in either the bipolar or monopolar modes based on impedance spikes.

**MATERIALS AND METHODS**

**The RFA System**

To perform bipolar RFA, we developed a prototype of the multichannel RF system that allowed the automatic switching of RF energy delivery among the three electrodes depending on RF energy delivery among both the monopolar and bipolar modes. In the monopolar mode, the switching between multiple electrodes occurred depending on impedance changes to use the inherent off time of the power pulsing algorithm to deliver energy through another electrically independent electrode, and similarly, the bipolar mode switching between one of the electrode pairs occurred depending on the impedance spikes (7, 10, 26). In both the SM and SB modes, if the impedance of one of the electrodes or one of the electrode pairs increased to 50 Ohm above the baseline impedance, the energy delivery switched automatically to the other electrode or other electrode pair (27).

We used a separable clustered electrode (Octopus® electrode; STARmed, Goyang, Korea) with three internally cooled electrodes, each with a 2.5-cm long active tip for the no-touch technique (27).

We maintained each tip temperature below 25°C by infusing the normal saline solution at 0°C into the lumen of each electrode using a peristaltic pump (VIVA Pump; STARmed). We continuously monitored the technical parameters, such as power output, impedance, applied currents, and total delivered energy, and recorded them using VIVA Monitor Software V 1.0 (STARmed).

**The Ex Vivo Experimental Setting**

We separately performed two-phase experimental studies to evaluate the efficacy and safety of the SM and SB modes of the no-touch RFA technique.

In the first experiment, to compare the efficacies of the SM- and SB-RFA techniques, we prepared 30 bovine liver blocks, slicing each explanted bovine liver into 12 x 12 x 7-cm³ liver blocks. After we made a small incision at the center of each liver block, we inserted a 1.2 x 1.2 x 1.2-cm³ pork loin cube with an approximate diagonal line length of 2 (1.2 x √3 ≈ 2.0) cm as a tumor mimicker while maintaining its diagonal line as parallel to the liver surface as possible. Subsequently, we placed each of the Octopus electrodes meticulously using the no-touch technique in a triangular array with a 2.5-cm inter-electrode distance through an acrylic plate that contained multiple holes at 5-mm intervals (27). Three electrodes were inserted at the same depth (4–5 cm) in the liver. We inserted a thermometer at the center of the ablation zone to monitor the tissue temperature in real time. Subsequently, we performed the RFA after immersing a liver block in a 50 x 20 x 25-cm³ saline-filled bath at room temperature. We then
recorded the elapsed times to reach 50, 60, 70, 80, and 90°C of tissue temperature.

In the second experiment, to evaluate the safety of SM- and SB-RFA, we checked the presence of organ injury as a safety parameter. Specifically, we prepared 30 additional 10 x 8 x 7.5-cm³ bovine liver blocks and immersed them in a 30 x 20 x 20-cm³ saline-filled bath. We inserted electrodes in a triangular array using the same acrylic plate with a 2.5-cm inter-electrode distance and placed one of the electrodes 14 mm below the upper surface of the liver; subsequently, we placed bovine small bowel loops just above the liver block (Fig. 1). We then placed a thermometer between the liver and small bowel loops and recorded the temperature; we also measured the surface temperature of the small bowel in contact with the liver surface using a thermal imaging camera (Fluke Ti90; Fluke Corp., Everett, WA, USA) at the end of each ablation.

Ablation Protocols
In each experiment, we performed 30 ablations. In the SM mode, RF energy (maximum 200 W) was delivered to one of the three electrodes and was automatically switched among the three electrodes depending on the elevation of the tissue impedance for 10 minutes (group A1, n = 10) or 15 minutes (group A2, n = 10). In the SB mode, the RF energy (maximum 100 W) was delivered to one of the electrode pairs and was switched in the same manner for 10 minutes (group B, n = 10) (Fig. 2). The 10-minute ablation time in the SB mode was based on previous studies that reported that bipolar RFA could be performed with relatively faster ablation and monopolar RFA (7, 23, 25). Therefore, we evaluated the ablative efficiency of the SM mode in two groups using the same as well as a longer duration than the SB mode in groups A1 and A2 (10 and 15 minutes, respectively) (23, 25).

![Fig. 1](image_url). *Ex vivo* study to evaluate adjacent bowel injury during RFA. Photograph shows segment of small bowel wall neighboring upper surface of liver block that was dipped into 30 x 20 x 20-cm³ saline-filled acrylic bath at room temperature. Note that one of Octopus electrodes is inserted into bovine liver 14 mm below liver upper surface, and thermocouple is placed between small bowel wall and liver surface for real time temperature measurement.

![Fig. 2](image_url). Diagram showing typical patterns of switching monopolar and switching bipolar modes. In switching bipolar mode, pair of electrodes is activated.
Size Measurement and Shape Analysis of the Ablation Zones

We cut the ablated bovine liver blocks along the electrode tract and sliced in the transverse plane perpendicular to the axis of the electrode tracks. We considered the ablation technically successful when the RF-induced ablation zone showed > 5-mm peritumoral ablation margins outside the tumor mimicker in all dimensions of the slices (28-30). To prevent any bias in the ablation size measurements, we photographed the slices alongside a ruler on a copy stand using a digital camera (Nikon Coolpix S6900; Nikon Inc., Tokyo, Japan). Two observers (blinded, with 5 years of experience in the RFA procedure and experiments, and a technician with 10 years of experience in RFA experiments) measured the vertical diameter (Dv) at the vertical plane as well as the long-axis diameter (Dmx) and the short-axis diameter (Dmi) of the RF-induced ablation zones at the transverse plane with the maximum area on consensus (31). Furthermore, we measured the distances between the electrode and the outer margin of the ablation zone (DEM) on the same plane and calculated the mean value of the three DEMs (Fig. 3). We also measured all diameters and distances of the ablation zone including the central white and peripheral red zones. We performed all measurements on image files of the slices using Image J software (https://imagej.nih.gov) and calculated the volume of the ablation zone using the following formula by approximating the shape of the lesion to an ellipsoid: Volume = \( \pi \times D_v \times D_{mx-eff} \times D_{mi-eff} \times D_v \).

We calculated the effective ablation volumes (Volume-eff) using the formula: Volume-eff = \( \pi \times D_{mi}^3 \), where Dmi was the shortest diameter among all the measured ones.

We quantitatively evaluated the shape of the RF-induced ablation zone using the ratio between the Dmi and Dmx and the circularity defined by the following formula: Circularity = \( 4\pi A / P^2 \), where A was the area of the measured zone and P was the perimeter of the area (25); we obtained this value by drawing the region of interest along the ablation margin on a transverse plane using the Image J software.

Assessing Thermal Injury to the Small Bowel

In the second experiment, we immediately checked the presence of small bowel injury after the ablation procedure to evaluate adjacent organ injury; we fixed injured bowel segments or bowel segments that most closely neighbored the ablation zone in 40 g/L formaldehyde solution, cut them into 3-mm thick slices, embedded them in paraffin, and stained them with hematoxylin and eosin for light microscopy. We graded the presence and depth of thermal injury to the small bowel as follows: 0, no injury; 1, partial thickness injury of the muscular layer; and 2, full thickness injury of the small bowel wall including mucosal injury (32, 33).

Statistical Analysis

For each ex vivo experiment, the results are presented as the mean ± standard deviation (SD). We then compared the volumes of the ablation zones using the following formula according to the same approximation of the shape to an ellipsoid: Volume = \( \pi \times D_v \times D_{mx-eff} \times D_{mi-eff} \times D_v \)
the measured values and the technical parameters of the three groups (A1 vs. A2 vs. B) using analysis of variance (ANOVA), using Bonferroni correction for post hoc analysis. To compare the variability of the ablation volume among the three groups, we calculated the coefficient of variation of the ablation volume as the ratio of the SD to the mean volume of the ablation zone. Regarding the proportion of the organ injury, we used the chi-squared test. For the ANOVAs, we considered \( p \) values < 0.05 statistically significant, and for the multiple pairwise comparisons between two groups, we considered \( p \) values < 0.017 statistically significant by Bonferroni correction. We performed all statistical analyses using MedCalc statistical software, version 12.2.1 (MedCalc Software, Mariakerke, Belgium).

**RESULTS**

**Technical Parameters**

The mean impedance of the SB mode was significantly higher than that of the SM mode (all \( p < 0.001 \)) (Table 1), and the mean delivered RF power and total amounts of delivered energy were also significantly lower in the SB mode than in the SM mode (all \( p < 0.001 \)).

**Technical Success, Ablation Size Measurement, and Shape Analysis**

None of the specimens showed technical failure or partial confluent or separated ablation (Table 2, Fig. 3).

**Ablation Size Measurements**

The mean \( D_m \) of the ablation areas in groups A1, A2, and B were \( 4.98 \pm 0.23 \), \( 5.24 \pm 0.26 \), and \( 4.49 \pm 0.13 \) cm, respectively (\( p < 0.001 \)) (Table 3). The SM-RFA (groups A1 and A2) generated significantly larger gross ablation volumes than SB-RFA (group B): group A1: \( 65.9 \pm 8.6 \) cm\(^3\); group A2: \( 73.6 \pm 10.0 \) cm\(^3\); and group B: \( 52.1 \pm 5.0 \) cm\(^3\) (\( p < 0.001 \)). The effective ablation volumes were \( 57.7 \pm 9.8 \), \( 57.9 \pm 7.3 \), and \( 46.8 \pm 3.1 \) cm\(^3\) in groups A1, A2, and B, respectively, and were significantly larger for SM-RFA than

Table 1. Measured Values of Technical Parameters According to Power Application Modes

| Parameters                  | Group A1 (n = 10) | Group A2 (n = 10) | Group B (n = 10) | \( P \) | A1 vs. A2 | A1 vs. B | A2 vs. B |
|-----------------------------|-------------------|-------------------|------------------|--------|-----------|---------|---------|
| Total delivered energy (Kcal) | 12.0 ± 0.8        | 14.6 ± 1.3        | 9.0 ± 0.9        | < 0.001 | < 0.001   | < 0.001 | < 0.001 |
| Average watt (W)             | 110.8 ± 6.1       | 95.5 ± 6.4        | 77.6 ± 5.2       | < 0.001 | < 0.001   | < 0.001 | < 0.001 |
| Impedance (Ohm)              | 58.8 ± 1.4        | 61.5 ± 1.6        | 93.6 ± 12.4      | < 0.001 | 0.001     | < 0.001 | < 0.001 |

Table 2. Results of Technical Success Rate, and Shape Analysis of RF-Induced Ablation Zones in Each Group

| Parameters                | Group A1 (n = 10) | Group A2 (n = 10) | Group B (n = 10) | \( P \) |
|---------------------------|-------------------|-------------------|------------------|--------|
| Technical success         | 100 (10/10)       | 100 (10/10)       | 100 (10/10)      | 1      |
| Confluent ablation        | 100 (10/10)       | 100 (10/10)       | 100 (10/10)      | 1      |
| Partial confluent ablation| 0 (0/10)          | 0 (0/10)          | 0 (0/10)         | 1      |
| Separated ablation        | 0 (0/10)          | 0 (0/10)          | 0 (0/10)         | 1      |

Table 3. Results of Ablation Size Measurement in Each Group

| Parameters                  | Group A1 (n = 10) | Group A2 (n = 10) | Group B (n = 10) | \( P \) | A1 vs. A2 | A1 vs. B | A2 vs. B |
|-----------------------------|-------------------|-------------------|------------------|--------|-----------|---------|---------|
| \( D_m \) (cm)              | 5.24 ± 0.23       | 5.58 ± 0.29       | 4.78 ± 0.20      | < 0.001| 0.01      | < 0.001 | < 0.001 |
| \( D_m \) (cm)              | 4.98 ± 0.23       | 5.24 ± 0.26       | 4.49 ± 0.13      | < 0.001| 0.03      | < 0.001 | < 0.001 |
| \( D_m \) (cm)              | 4.81 ± 0.29       | 4.79 ± 0.20       | 4.63 ± 0.24      | 0.384  |           |         |         |
| Gross ablation volume (cm\(^3\)) | 65.9 ± 8.6        | 73.6 ± 10.0       | 52.1 ± 5.0       | < 0.001| 0.083     | 0.001   | < 0.001 |
| Effective ablation volume (cm\(^3\)) | 57.7 ± 9.8        | 57.9 ± 7.3        | 46.8 ± 3.1       | < 0.001| 0.963     | 0.006   | < 0.001 |
| DEM (cm)                    | 1.67 ± 0.10       | 1.86 ± 0.18       | 1.39 ± 0.08      | < 0.001| 0.013     | < 0.001 | < 0.001 |
| CV of volume (%)            | 13                | 13.6              | 9.6              |        |           |         |         |

CV = coefficient of variation, DEM = distance between electrode and ablation zone margin, \( D_m \) = minimum diameter of the ablative zone, \( D_m \) = maximum diameter of the ablative zone, \( D_v \) = vertical diameter of the ablative zone.
Ablation Shape Analysis

The circularities of the ablative zones were 0.95 ± 0.05 in group A1, 0.97 ± 0.01 in group A2, and 0.94 ± 0.06 in group B ($p = 0.334$), suggesting that there were no significant differences in the quantitative values of the shape analysis among the three groups; however, DEM was significantly lower in group B (1.39 ± 0.08 cm) than in groups A1 (1.67 ± 0.10 cm) and A2 (1.86 ± 0.18 cm) ($p < 0.001$).

Elapsed Time

He elapsed times to reach 60, 70, 80, and 90°C were significantly faster in the SB-RFA group than in the SM-RFA group (groups A1 and A2: $p = 0.002$ for 60°C; $p < 0.001$ for 70, 80, and 90°C; $p = 0.681$ for 50°C) (Table 4).

The Second Experiments

We noted thermal injury to the small bowel in 90% (9/10), 100% (10/10), and 30% (3/10) of the cases in groups A1, A2, and B, respectively (A1 vs. B, $p = 0.008$; A2 vs. B, $p = 0.001$; A1 vs. A2, $p = 0.317$) (Fig. 4). We observed six cases of grade 2 small bowel injury only in group A2 (6/10), and all thermal injuries of the small bowel noted in group A1 and B were grade 1 (A2 vs. A1 and B for grade 2 injury, $p = 0.004$). The mean final temperatures measured by a thermocouple placed between the liver surface and the small bowel after the completion of ablation were 59.1 ± 7.4, 65.1 ± 8.6, and 49.4 ± 6.7°C in groups A1, A2, and B, respectively. The surface temperatures of the small bowel neighboring the ablation zone measured by a thermal imaging camera were also significantly lower in the SB group than in the SM groups and significantly lower in group A1 than in group A2 (all $p < 0.001$): 48.4 ± 3.2, 56.7 ± 3.5, and 40.5 ± 2.3°C in groups A1, A2, and B, respectively.

Table 4. Elapsed Times to Reach Specific Temperatures in Each Group

| Temperature | SM-RFA (Seconds) | SB-RFA (Seconds) | $P$  |
|-------------|------------------|------------------|------|
| 50°C        | 83.1 ± 22.8      | 80.8 ± 5.6       | 0.681|
| 60°C        | 109.1 ± 14.5     | 96.2 ± 6.0       | 0.002|
| 70°C        | 130.1 ± 15.2     | 108.6 ± 7.8      | <0.001|
| 80°C        | 154.0 ± 18.5     | 121.6 ± 9.6      | <0.001|
| 90°C        | 185.6 ± 26.0     | 137.9 ± 11.8     | <0.001|

RFA = radiourequency ablation, SB = switching bipolar, SM = switching monopolar
As a secondary safety parameter, we evaluated DEM in the ablation zones and measured tissue temperature from the area between the bowel and the liver capsule above the ablation zone. Therefore, based on our study results, we believe that the SB mode might exhibit a better safety profile than the SM mode during no-touch RFA.

Conventional monopolar technique requires precise placement of the electrode within the target tumor, ideally along the its central axis because it creates an ablation zone from the center of the tumor to the periphery owing to the condensed deposition of electrical current in the tissue surrounding the electrode. Therefore, there might be some risk of track seeding or peritoneal seeding after RFA and a relatively higher risk of local recurrence related to the failure to generate a sufficient safety margin around the tumor (16). Indeed, there is a trade-off between generating a sufficient peritumoral margin to lower recurrence after RFA and preventing unintended adjacent thermal injury. Moreover, after Llovet et al. (35) reported a high rate (12.5%) of tumor tract seeding in 32 patients with HCC who had been treated with RFA; with increased use, tumor tract seeding after percutaneous RFA was found to be a major issue, particularly in patients with a curative chance (36). However, according to a recent systematic review of tumor seeding after percutaneous diagnostic and therapeutic approaches for HCC (15), the mean risk for seeding after

**Fig. 4. Comparison of adjacent small bowel thermal injury during RFA in groups A2 and B.**

A, B. Vertical cut surface of ablated specimens and adjacent small bowel in group A2. Note that ablated area extended to liver surface and there is color change of small bowel wall by thermal injury (arrow). C, D. Vertical cut surfaces of ablated specimens and adjacent small bowel in group B. Note that liver surface was not ablated and adjacent small bowel showed no thermal injury.
RFA alone was 1.73% (range, 0–5.56%), and after RFA with biopsy, the mean risk for seeding was 2.5%. Nonetheless, considering that immune suppression is essentially used for liver transplantation and waiting time for liver transplantation is quite long (usually longer than 1 year), when RFA is used to manage patients with liver cirrhosis and small HCCs, it would be ideal to avoid unnecessary liver parenchymal damage in the area surrounding the target tumor and also to avoid any risk of tumor seeding. In fact, the no-touch technique could be quite valuable for preventing track seeding after RFA, which is very important in patients who are on the waiting list for liver transplantation or patients with tumors located on the liver surface (36, 37). However, for no-touch RFA with multiple electrodes placed outside the tumor, the peritumoral ablation size could be larger than that for conventional RFA methods with tumor puncture. In the present study results, the SB mode showed less DEM than the SM mode. Therefore, we believe that the SB mode can be more optimal for no-touch RFA than the SM mode. Assuming that the ablation zone of each electrode in the SM-RFA is circular in the transverse plane, the diameter of ablation zone should be larger than interelectrode distance / \sqrt{3} to induce non-separated coagulation. This indicates that the minimal DEM in the SM mode should be interelectrode distance / \sqrt{3}, and with a 2.5-cm interelectrode distance, the minimal DEM was approximately 1.4 cm. In the present study, the mean DEM values were larger than 1.4 cm in the SM mode (groups A1 and A2) and smaller than 1.4 cm in the SB mode (group B). Additionally, in the second experiment, to show the adjacent organ injury, we placed the electrode 1.4 cm below the liver surface considering the calculated minimal DEM.

The present study has a number of limitations. First, we established the initial feasibility and safety of ex vivo no-touch RFA using a newly developed RF generator with SB and SM modes was established, but, as previously mentioned, we might not have been able to properly assess various effects including the heat sink phenomenon and physical thermal insulation barriers such as the liver capsule. Second, we did not compare our SB-RFA system with the previously reported multipolar RFA systems that showed promising outcomes for no-touch ablation (22). Third, we only tested no-touch linear electrode insertion for maximum intervals of 25 mm; considering that there were no technical failures in generating confluent ablation in the three groups, additional examinations at larger inter-electrode intervals > 25 mm could be valuable. However, we believe that the no-touch technique could be ideally applicable to small tumors in vivo in the human liver, likely with maximum diameters of 2–2.5 cm. Finally, we performed the RF ablations using a tumor mimicker model from a pork loin cube; therefore, the thermal efficiency of the current RF system in the present study might not translate into real clinical practice owing to the different tissue textures of target tumors.

In conclusion, our results demonstrated that the no-touch technique is feasible using both the SB and SM modes; however, SB-RFA may exhibit a better safety profile, a smaller adjacent parenchymal ablation zone, and less frequent adjacent small bowel injuries than SM-RFA.

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