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A study on COVID-19 transmission dynamics: Stability analysis of SEIR model with Hopf bifurcation for effect of time delay

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Abstract
This paper deals with a general SEIR model for the coronavirus disease 2019 (COVID-19) with the effect of time delay proposed. We get the stability theorems for disease-free equilibrium and provide adequate situations of the COVID-19 transmission dynamics equilibrium of present and absent cases. A Hopf bifurcation parameter $\tau$ is the effects of time delay and we demonstrate that the locally asymptotic stable is present equilibrium. The Reproduction number is brief in less than or greater than one, and it effectively controlling the COVID-19 infection outbreak, and subsequently reveals insight into understanding the patterns of the flare-up. The numerical experiment is calculated to help the theoretical outcomes.

Keywords: Covid19, SEIR, Stability, Hopf bifurcation.
AMS Subject Classification: 34D20, 34E05, 34K50.

1. Introduction
As of 18 April 2020 (5:00 PM), as per the Ministry of Health and Family Welfare (MoHFW), India, an aggregate of 14792 COVID-19 cases, (counting 76 outside nationals) have been accounted for in 32 sta[1]. These incorporate 2014 who have been released, 1 who has relocated and 488 deaths [2]. Medical clinic segregation of every single confirmed case, tracing and home quarantine of the contacts is ongoing (Globally: 2074529 confirmed, 139378 deaths). The progressing COVID-19 episode, developed in Wuhan, China, has guaranteed more than 2600 lives starting on 24 February 2020 and represented a colossal danger to worldwide general wellbeing [3]-[8]. It has actualized different methods adding current situations uncommon medical clinics and travel limitations to relieve the infection. Here we have indicated that coronavirus ailment has been engendered in the network of China quickly by revealed information and the Government of China make important strides, for example, occasion augmentation, travel limitation, hospitalization and isolate. These vital limitations have been useful to diminish the infection transmission among the populace and this is legitimized by information results [9]-[15]. It is earnest to give increasingly logical data to a superior comprehension of the noval coronavirus and promote control of the outbreak [16].

At the beginning of time episode, was dispersed, and connected to the Market places [17]. It has received outrageous measures to relieve flare-up. On 10 March 2020, the neighborhood legislature of Wuhan controlled every open traffic inside the city and shut all inbound and outbound transportation [18]-[24]. The open frenzy progressing COVID-19 episode helps us the records to remember the 1920 flu pandemic in London, United Kingdom. Besides, its attributes of mellow side effects as a rule and short sequential interim are like pandemic flu, as opposed to the next two coronaviruses [25]. In 1918, critical extents of the passing were from pneumonia followed flu contamination [26]. Hence, it may be sensible to return to the demonstrating system of 1918 flu pandemic, and specifically, to catch the impacts of the individual response and government activity. We assume it will keep going for the following not many days for the occasion and shall refresh. The variables esteem might be evaluated after that data is accessible [27]-[30]. It contends all avoidance and limiting cases might be ordered up to three huge gatherings, that are portrayed a stage work and reaction work, separately. They likewise consider COVID-19 transmission time of 14 days and gigantic resettlement from China [31]. A contact is an individual who encountered any of the accompanying
exposures during the 2 days prior and the 14 days after the beginning of side effects of a plausible or affirmed case [32].

For transmission of COVID-19 among the human population and its stability we have a proposed SEIR pandemic model [33]. Another scientific model in pestilence elements, known as the Warehouse theory, generally has been discussed for quite a while since it was sent by Kermack and McKendrick in 1927. It incorporates a few essential improved models, for example, SIR, SIS, SEIR, etc, among which SEIR is an ordinary model that considers the incubation period into account. The SEIR, a widely utilized scourge model, can show the progressions of individuals between four states: Susceptible (S) (Population not resistant to illness), Exposed (E) (Population as of now in brooding), Infectious (I) (Number of contamination effectively circling), and Recovered (R) (Population not, at this point irresistible because of confinement or in susceptibility or Full recuperation). Here the population total size at time t is defined by N(t), with N(t) = S(t)+E(t)+I(t)+R(t). This system is portrayed by the accompanying nonlinear differential equations [34]:

\[
\begin{align*}
\frac{dS(t)}{dt} &= b + γI(t) - (μ + p)S(t) - βS(t)I(t), \\
\frac{dE(t)}{dt} &= βS(t)I(t) - μE(t) - ηE(t)R(t), \\
\frac{dI(t)}{dt} &= (η + σβ)E(t) - (α + μ + γ)I(t), \\
\frac{dR(t)}{dt} &= pS(t)E(t)R(t) - (μ + σβ)R(t).
\end{align*}
\] (1)

The parameters p, b, γ, β, μ, η, σ, α are positive constants, is the proportion of asymptomatic infection, b is the birth rate of people while newborn cells are created, γ is the incubation period of human infection, β is the transmission rate from one compartment to another compartment, μ is the death rate of people, η is the infectious period of symptomatic infection of people, σ is the infectious period of asymptomatic infection of people, α is the multiple of the transmissibility while infected cells are created from the viruses.

Transmission dynamics generating COVID-19 may require a duration of time delay τ, i.e. the delay of the immune system at time (days) t may be governed on the previous time t−τ. We obtain an immune response of length of incubation period, pS(t)E(t)R(t) = pS(t−τ)E(t−τ)R(t−τ) and duration of patient is infectious. Tian-Mu Chen,et.al [33] investigated the including effect of time delay to acquire the following nonlinear differential equations:

\[
\begin{align*}
\frac{dS(t)}{dt} &= b + γI(t) + εR(t) - (μ + p)S(t) - βS(t)I(t), \\
\frac{dE(t)}{dt} &= βS(t)I(t) - μE(t) - ηE(t)R(t), \\
\frac{dI(t)}{dt} &= (η + σβ)E(t) - (α + μ + γ)I(t), \\
\frac{dR(t)}{dt} &= pS(t−τ)E(t−τ)R(t−τ) - (ε + μ + σβ)R(t),
\end{align*}
\] (2)

where ε is the latent period of human infection in population no longer infectious due to full recovered. The aim of the research work is to discuss on SEIR delay model in (2). If τ = 0, the equation (2) narrates the population inputs between size of population and number of initial infections. The COVID-19 basic reproduction number for the system (2) is defined by

\[R_0 = \frac{(b + γI + εA)β}{μ(μ + p)(α + μ + γ)}.
\]

We have likewise determined the basic reproduction number R_0 classical SIR model and we have seen that if R_0 < 1 disease doesn’t proliferate into the population yet on the off chance that R_0 > 1 infection will spread among the population. We presented an isolated SIR model and SEIR model portraying disease movement under the presumption that all contaminated individuals are separated after the hatching time frame so that they can’t taint others. Ailment movement in these models is controlled by the basic reproduction number R_0, which is diverse contrasted with that for the standard SIR model. In the event that R_0 > 1 (95%, ranges 1.4 to 3.9), at that point the quantity of inertness contaminated people exponentially develops. Be that as it may, if R_0 < 1, at that point the number of contaminated rots exponentially. This investigation of R_0 catches the course of COVID-19 flare-up and subsequently reveals insight into understanding the patterns of the flare-up and gives some preventive, measure not to spread COVID-19 malady (97%, ranges 2.47 to 3.9). This portrays the normal number of recently contaminated cells produced from one tainted cell toward the start of the irresistible procedure.
2. Preliminaries

Let $S(t) = C([-\tau, 0]; \mathbb{R})$ be the continuous norm function of Banach space mappings. The initial conditions for the model (2) are given as follows [35]:

$$
\begin{align*}
S(t) &\geq 0, \quad E(t) \geq 0, \quad I(t) \geq 0, \quad R(t) \geq 0, \quad t \in [-\tau, 0] \\
S(0) &> 0, \quad E(0) > 0, \quad I(0) > 0, \quad R(0) > 0.
\end{align*}
$$

Let $(S(t), E(t), R(t))$ be three main variables of the system with initial conditions and verify that there is a unique solution. The accompanying lemma is helpful for examining the positivity of the bounded solutions.

**Lemma 2.1** In the system $(S(t), E(t), R(t))$ of (2) with initial conditions (3), we assume that

$$
limsup_{t \to +\infty} S(t) \leq \frac{b + \gamma I + eR}{\mu + p}.
$$

**Proof.** If there is $t_1 > 0$ with the end goal that $S(t_1) > \frac{b + \gamma I + eR}{\mu + p}$ and $S(t_1) > 0$, then we have that

$$
S(t_1) = b + \gamma I + eR - (\mu + p)S(t_1) - \beta S(t_1)I(t_1) \leq -\beta S(t_1)I(t_1) \leq 0.
$$

Hence we have utilized $S(t_1) > \frac{b + \gamma I + eR}{\mu + p}$. This is an inconsistency to $S(t_1) > 0$. Along these lines, the finish of Lemma 2.1 is verified.

**Lemma 2.2** Let $(S(t), E(t), I(t), R(t))$ be the system (2) with initial conditions (3). At that point $(S(t), E(t), I(t))$ and $R(t)$ are certain and there exists a positive constant $\Gamma > 0$, to such an extent that $S(t) < \Gamma, E(t) < \Gamma, I(t) < \Gamma$ and $R(t) < \Gamma$ at an adequately huge time $t$.

**Proof.** Consider the equation (2), we get

$$
S(t) = S(0) e^{-\int_0^t (\mu + p) dt} + \int_0^t (b + \gamma I + eR) e^{-\int_0^\eta (\mu + p) dt} d\eta,
$$

$$
E(t) = E(0) e^{-\int_0^t (\mu + p) dt} + \int_0^t \beta S(\eta) I(\eta) e^{-\int_0^\eta (\mu + p) dt} d\eta,
$$

$$
I(t) = I(0) e^{-\int_0^t (\mu + p) dt} + \int_0^t \sigma \beta S(\eta) I(\eta) e^{-\int_0^\eta (\mu + p) dt} d\eta,
$$

$$
R(t) = R(0) e^{-\int_0^t (\mu + p) dt} + \int_0^t p S(\eta) I(\eta) e^{-\int_0^\eta (\mu + p) dt} d\eta.
$$

It is anything but difficult to see that $S(t)$ is positive on the existence interval. At that point, we demonstrate that $E(t)$ is positive. Truth be told, let $t_1 > 0$ be the first run through to such an extent that $E(t_1) = 0$. From equation (2), we get

$$
R(t - 1) = R(0) e^{-\int_0^{t-1} (\mu + p) dt} + \int_0^{t-1} p S(\eta) I(\eta) e^{-\int_0^\eta (\mu + p) dt} d\eta > 0.
$$

Then again, from the second equation of (2), we have $E(t_1) = (t_1)I(t_1) > 0$. This implies $E(t) < 0$ for $t \in (t_1 - 1, t_1]$, where is a subjectively small positive constant, which prompts an inconsistency. It is follows that $E(t) > 0$ and $I(t) > 0$. By the comparative contaction as the above mentioned, it is difficult to obtain that $R(t)$ is positive. Here, we discuss the contenctions for extreme solution of (2).

Here $N(t) = S(t) + E(t) + \int_0^t \frac{\beta \gamma \beta}{\mu + p} I(\eta) e^{-\int_0^\eta (\mu + p) dt} R(t + \tau),$

and assume $q = \min \{p,\frac{\beta \gamma \beta}{\mu + p}\}.$ From (2), we get

$$
\frac{d}{dt} [N(t)] = b + \gamma I + eR - (\mu + p)S(t) - \frac{\mu}{2} E(t) - \eta E(t) R(t) - \frac{\mu (\alpha + \mu + \gamma)}{2 (\eta + \sigma \beta)} I(t) + \frac{\eta (\mu + p)}{b + \gamma I + eR} S(t) E(t) R(t)
$$

$$
- \eta (\epsilon + \mu + \sigma \beta)(\mu + p) \frac{R(t + \tau)}{p(b + \gamma I + eR)}
$$

$$
\leq (b + \gamma I + eR - (\mu + p)S(t) - \frac{\mu}{2} E(t) - \frac{\mu (\alpha + \mu + \gamma)}{2 (\eta + \sigma \beta)} I(t) - \frac{\eta (\epsilon + \mu + \sigma \beta)(\mu + p)}{p(b + \gamma I + eR)} R(t + \tau)
$$

$$
< b + \gamma I + eR - q \left[ S(t) + E(t) + \frac{\mu}{2 (\eta + \sigma \beta)} I(t) + \frac{\eta (\mu + p)}{p(b + \gamma I + eR)} R(t + \tau) \right] = b + \gamma I + eR - q.
$$

Along these lines, $N(t) < \frac{b + \gamma I + eR}{\mu + p}$ for all large $t$. Subsequently, $S(t), E(t), I(t)$ and $R(t)$ are at last limited by any positive constant $\Gamma$. Hence, finishes the verification of Lemma 2.2.
3. Theorems for Stability analysis

There are three equilibria for system (2):

(i) COVID-19 Infection free equilibrium:
\[ E_0 = \left( \frac{\mu + \gamma}{\beta}, 0, 0, 0 \right). \]

(ii) COVID-19 infection absent equilibrium:
\[ E_1 = \left( \frac{\mu + \gamma}{\beta}; (\eta + \sigma) \frac{\beta(b + y + R)}{\mu + p} (\alpha + \mu + \gamma), \frac{\mu + \gamma}{\beta}; \frac{\mu + p + \delta (\alpha + \mu + \gamma)}{\mu + p + \gamma}, 0 \right). \]

(iii) COVID-19 infection present equilibrium:
\[ E = (E_1, E_2, E_3, E_4), \]
where \[ \bar{E}_1 = \frac{p(\alpha + \gamma) + \beta(b + y + R) - \delta (\alpha + \gamma)}{\mu + p}, \]
\[ \bar{E}_2 = \frac{(e + \sigma)(\mu + p) (\alpha + \gamma)}{\mu + p}, \]
\[ \bar{E}_3 = \frac{(\eta + \sigma\beta)(\mu + p)}{\mu + p}, \]
\[ \bar{E}_4 = \frac{1}{\mu + p}(\eta + \sigma\beta)I - \mu E. \]

3.1. Stability of COVID-19 Infection free equilibrium

The nonlinear differential equation of (2) at the point \( E_0 \) is
\[
\begin{align*}
\frac{dS(t)}{dt} &= -(\mu + p)S(t) - \frac{\beta(b + y + R)}{\mu + p} I(t), \\
\frac{dE(t)}{dt} &= -\mu E(t) + \frac{\beta(b + y + R)}{\mu + p} I(t), \\
\frac{dI(t)}{dt} &= (\eta + \sigma\beta) E(t) - (\alpha + \mu + \gamma) I(t), \\
\frac{dR(t)}{dt} &= -(e + \mu + \sigma\beta) R(t),
\end{align*}
\]
(4)

The polynomial equation for (4) is
\[
(\lambda + (\epsilon + \mu + \sigma\beta))(\lambda + (\mu + p)) \lambda + (\alpha + \mu + \gamma)\lambda + (\alpha + \mu + \gamma) - \frac{(\eta + \sigma\beta) \beta(b + \gamma I + \epsilon R)}{(\mu + p)} = 0.
\]
(5)

Two of the roots of the polynomial equation (5) is \( \lambda_1 = -(\epsilon + \mu + \sigma\beta), \lambda_2 = -(\mu + p). \) The other roots are calculated by
\[
\lambda^2 + (\alpha + \mu + \gamma)\lambda + (\alpha + \mu + \gamma) - \frac{(\eta + \sigma\beta) \beta(b + \gamma I + \epsilon R)}{(\mu + p)} = 0.
\]
(6)

If \( R_0 < 1, \) then \( \mu + (\alpha + \mu + \gamma) - \frac{(\eta + \sigma\beta) \beta(b + \gamma I + \epsilon R)}{(\mu + p)} > 0, \) and \( (\mu + (\alpha + \mu + \gamma))^2 - 4\left(\mu + (\alpha + \mu + \gamma) - \frac{(\eta + \sigma\beta) \beta(b + \gamma I + \epsilon R)}{(\mu + p)}\right) > 0. \)

\[ \lambda_3,4 = -\frac{(\mu + (\alpha + \mu + \gamma)) \pm \sqrt{\mu + (\alpha + \mu + \gamma)^2 - 4\left(\mu + (\alpha + \mu + \gamma) - \frac{(\eta + \sigma\beta) \beta(b + \gamma I + \epsilon R)}{(\mu + p)}\right)} \times 2}{2}. \]

The equation (6) has negative real roots. It has the accompanying theorem. If \( R_0 < 1, \) then \( E_0 \) is locally asymptotic stable by developing a Lyapunov functional. If \( R_0 > 1, \) then \( E_0 \) is unstable.

**Theorem 3.1** If \( R_0 < 1, \) then prove that \( E_0 \) is globally asymptotic stable.

**Proof.** For Lyapunov functional,

\[ V = \int \left[ S(t) - \frac{\beta(b + y + R)}{\mu + \eta} \right] + \frac{\beta(b + y + R)}{\mu + \eta} E(t) + mI(t) + \frac{\eta}{\beta} R(t) + \eta \int_{t_0}^t S(\theta) \mu E(\theta) R(\theta) d\theta, \]

where \( m > 0. \) We have
\[
V' = \left[ S(t) - \frac{\beta(b + y + R)}{\mu + \eta} \right] (-\mu + p) \left( S(t) - \frac{\beta(b + y + R)}{\mu + \eta} \right) - \beta S(t) I(t) \right] + \frac{\beta(b + y + R)}{\mu + \eta} \left[ \beta S(t) I(t) - \mu E(t) - \eta E(t) R(t) \right] + m \left[ (\eta + \sigma\beta) E(t) - (\alpha + \mu + \gamma) I(t) \right] - \frac{(\eta + \sigma\beta) \beta(b + \gamma I + \epsilon R)}{p} R(t) + \eta S(t) E(t) R(t).
\]
Since $\beta S(t)I(t) = \beta I(t) \left[ S(t) - \frac{(b+y+R)}{(\mu+p)} \right] + \frac{(b+y+R)}{(\mu+p)} I(t)$, we have

$$ V'(S(t), I(t)) = - (\mu + p) \left( \frac{(b+y+R)}{(\mu+p)} \right)^2 - \beta I(t) \left[ S(t) - \frac{(b+y+R)}{(\mu+p)} \right] \left[ S(t) - \frac{(b+y+R)}{(\mu+p)} \right] - \eta S(t)(t)R(t) - \frac{\eta(\epsilon + \gamma \beta)}{p} R(t). $$

Hence $R_0 < 1$ decreases to

$$ \frac{b+y+R}{(\mu+p)} - (\eta + \epsilon \beta) > 0 \text{ and } (\epsilon + \gamma \beta) m - \frac{\beta(b+y+R)}{(\mu+p)} > 0. $$

Letting $S(t), E(t), R(t)$ be positive and $S(t) \leq \frac{(b+y+R)}{(\mu+p)}$, we have that $V'(S(t), E(t), I(t), R(t)) = \frac{(b+y+R)}{(\mu+p)}, 0, 0, 0$.  

3.2. **Stability of COVID-19 infection absent equilibrium**

Letting $E_1 = (S, E, I, 0) = \left( \frac{(b+y+R)}{(\mu+p)}, \frac{(b+y+R)}{(\mu+p)}, \frac{(b+y+R)}{(\mu+p)}, 0, 0, 0 \right)$, the linearized form of equations of system (2) at $E_1$ is

$$ \left( \frac{dS(t)}{dt} = \left( \mu + (\alpha + \mu + \gamma) \right)^2 + \left( \mu + (\alpha + \mu + \gamma) \right)^2 + \left( \mu + (\alpha + \mu + \gamma) \right)^2, \right) \left( \frac{dE(t)}{dt} = \left( \mu + (\alpha + \mu + \gamma) \right)^2 + \left( \mu + (\alpha + \mu + \gamma) \right)^2 + \left( \mu + (\alpha + \mu + \gamma) \right)^2, \right) \left( \frac{dI(t)}{dt} = \eta E(t) - \left( \mu + (\alpha + \gamma) \right) I(t), \right) \left( \frac{dR(t)}{dt} = pS R(t) \tau - \left( \mu + (\alpha + \gamma) \right) R(t). \right) $$

The characteristic polynomial equation of (7) is

$$ \lambda^3 + a_1 \lambda^2 + a_2 \lambda + a_3 = 0. $$

Clearly, if $R_0 > 1$, we have $a_1 = \mu + (\alpha + \mu + \gamma) + (\mu + p) + \frac{(b+y+R)}{(\mu+p)} > 0$ and $a_2 = (\mu + (\alpha + \mu + \gamma)) (\mu + (\alpha + \mu + \gamma)) (\mu + (\alpha + \mu + \gamma)) > 0$.  

First we obtain

$$ a_1 = \mu + (\alpha + \mu + \gamma) + (\mu + p) + \frac{(b+y+R)}{(\mu+p)} > 0 $$

and

$$ a_2 = (\mu + (\alpha + \mu + \gamma)) (\mu + (\alpha + \mu + \gamma)) (\mu + (\alpha + \mu + \gamma)) > 0.$$

Then

$$ a_3 = (\mu + (\alpha + \mu + \gamma)) (\mu + (\alpha + \mu + \gamma)) (\mu + (\alpha + \mu + \gamma)) > 0. $$

Routh-Hurwitz criteria, (8) has no positive roots. So, we investigate another polynomial equation

$$ \lambda = -pS \tau - (\mu + \gamma) \beta > 0. $$

For $\tau = 0$, $\lambda = \frac{(b+y+R)}{(\mu+p)} > 0$.  

Obviously, if $R_0 < 1 + \frac{(b+y+R)}{(\mu+p)}$, then $\phi < 0$, which illustrates that the roots of (9) for some $\psi > 0$ and $\tau > 0$. From (9), we have

$$ \phi = -\frac{(\epsilon + \gamma \beta) \beta}{\beta p}, \left( \epsilon + \mu + \gamma \beta \right) \beta p \sin \psi, \left( \epsilon + \mu + \gamma \beta \right) \beta p \cos \psi. $$
which implies that $\phi^2 = p^2 \left[ \frac{(\alpha + \mu + \gamma + \beta)(\mu + p)(\alpha + \mu + \gamma)}{\beta(\eta + \gamma)} \right] - (\epsilon + \mu + \sigma \beta)^2$.

Note that if $1 < R_0 < 1 + \frac{p^2(\eta + \gamma)(\alpha + \mu + \gamma)}{\beta(\eta + \gamma)}$, then $\phi^2 < 0$. If $1 < R_0 < 1 + \frac{\rho^2(\alpha + \mu + \gamma)(\alpha + \mu + \gamma)}{p^2(\mu + p)(\alpha + \mu + \gamma)}$, then the COVID-19 infection $E_1$ is locally asymptotic stable. If $1 < R_0 > 1 + \frac{\rho^2(\alpha + \mu + \gamma)(\alpha + \mu + \gamma)}{p^2(\mu + p)(\alpha + \mu + \gamma)}$, then the COVID-19 infection $E_1$ is unstable.

3.3. Stability of COVID-19 infection present equilibrium

In COVID-19 infection, the effects of time delay $\tau$ is a bifurcation parameter and it goes through a stationary values. The COVID-19-present equilibrium occurs direct stability and Hopf bifurcation. As a matter of first importance, we interpret the equilibrium $E = (\vec{S}, \vec{E}, \vec{I}, \vec{R})$ of system (2) to the source. Let $S(t) = S(t) - \vec{S}$, $I(t) = E(t) - \vec{E}$, $I(t) = I(t) - \vec{I}$, $R(t) = R(t) - \vec{R}$. For effortlessness, we likewise use $S(t), E(t), I(t), R(t)$ rather than $S(t), E(t), I(t), R(t)$. The system (2) becomes

$$\begin{align*}
\frac{dS(t)}{dt} &= - \left( \mu + p \right) S(t) - \beta S(t)I(t) - \beta \vec{S} I(t), \\
\frac{dE(t)}{dt} &= \beta S(t)I(t) + \beta \vec{S} I(t) - (\mu + \eta R) E(t) + \beta \vec{S} I(t) - \eta E(t) R(t) - \eta \vec{E} R(t), \\
\frac{dI(t)}{dt} &= (\eta + \sigma \beta) E(t) - (\alpha + \mu + \gamma) I(t), \\
\frac{dR(t)}{dt} &= p S(t - \tau) E(t - \tau) R(t - \tau) + p E(t - \tau) R(t - \tau) + p \vec{S} \vec{E} R(t - \tau) + p \vec{E} \vec{S} R(t - \tau) + p \vec{E} \vec{R} E(t - \tau) - (\epsilon + \mu + \sigma \beta) R(t).
\end{align*}$$

Then, the origin $(0, 0, 0, 0)^T$ is steady state of (11) and the linearized system of equation (11) at the origin is given by

$$\begin{align*}
\frac{dS(t)}{dt} &= - \left( \mu + p \right) S(t) - \beta S(t)I(t) - \beta \vec{S} I(t), \\
\frac{dE(t)}{dt} &= \beta S(t)I(t) + \beta \vec{S} I(t) - (\mu + \eta \vec{R}) E(t) + \beta \vec{S} I(t) - \eta E(t) R(t) - \eta \vec{E} R(t), \\
\frac{dI(t)}{dt} &= (\eta + \sigma \beta) E(t) - (\alpha + \mu + \gamma) I(t), \\
\frac{dR(t)}{dt} &= p S(t - \tau) E(t - \tau) R(t - \tau) + p E(t - \tau) R(t - \tau) + p \vec{S} \vec{E} R(t - \tau) + p \vec{E} \vec{S} R(t - \tau) + p \vec{E} \vec{R} E(t - \tau) - (\epsilon + \mu + \sigma \beta) R(t).
\end{align*}$$

The trivial solution of equation (12) is asymptotic stable and the equation (11) is locally asymptotic stable. The strength of the polynomial equation (12) is given by

$$\Omega(t) = \lambda^4 + x_1 \lambda^3 + x_2 \lambda^2 + x_3 \lambda + x_4 - (x_5 \lambda^3 + x_6 \lambda^2 + x_7 \lambda + x_8) e^{-\lambda t},$$

where

\begin{align*}
x_1 &= (\epsilon + \mu + \sigma \beta)(\mu + p) + \beta \vec{I} + (\alpha + \mu + \gamma) + \mu + \eta \vec{R}, \\
x_2 &= (\epsilon + \mu + \sigma \beta) (\mu + p) + (\epsilon + \mu + \sigma \beta) \beta \vec{I} + (\epsilon + \mu + \sigma \beta) (\alpha + \mu + \gamma) + (\mu + p)(\alpha + \mu + \gamma) + \beta \vec{I}(\alpha + \mu + \gamma) + (\mu + \eta \vec{R})(\epsilon + \mu + \sigma \beta)(\mu + p) + \beta \vec{I}(\alpha + \mu + \gamma) + (\mu + \eta \vec{R})(\epsilon + \mu + \sigma \beta)(\mu + p) + (\epsilon + \mu + \sigma \beta) \beta \vec{I} + (\eta + \sigma \beta) \beta \vec{S} \vec{I}, \\
x_3 &= (\epsilon + \mu + \sigma \beta) (\mu + p)(\alpha + \mu + \gamma) + (\epsilon + \mu + \sigma \beta) \beta \vec{I}(\alpha + \mu + \gamma) + (\mu + \eta \vec{R})(\epsilon + \mu + \sigma \beta)(\mu + p) + (\epsilon + \mu + \sigma \beta) \beta \vec{I} + (\eta + \sigma \beta) \beta \vec{S} \vec{I}, \\
x_4 &= (\epsilon + \mu + \sigma \beta)(\eta + \sigma \beta) \beta \vec{S} \vec{I}, \\
x_5 &= (\epsilon + \mu + \sigma \beta), \\
x_6 &= (\epsilon + \mu + \sigma \beta)(\mu + p) + (\epsilon + \mu + \sigma \beta) \beta \vec{I} + (\epsilon + \mu + \sigma \beta)(\alpha + \mu + \gamma) + (\mu + \mu + \sigma \beta)(\alpha + \mu + \gamma) + (\mu + \eta \vec{R})(\epsilon + \mu + \sigma \beta)(\mu + p) + (\epsilon + \mu + \sigma \beta) \beta \vec{I} - (\epsilon + \mu + \sigma \beta) \eta \vec{R}(\mu + p) + \beta \vec{I} + (\alpha + \mu + \gamma), \\
x_7 &= (\epsilon + \mu + \sigma \beta) (\mu + p)(\alpha + \mu + \gamma) + (\epsilon + \mu + \sigma \beta) \beta \vec{I}(\alpha + \mu + \gamma) + (\mu + \eta \vec{R})(\epsilon + \mu + \sigma \beta)(\mu + p) + (\epsilon + \mu + \sigma \beta) \beta \vec{I} - (\epsilon + \mu + \sigma \beta) \eta \vec{R}(\mu + p) + \beta \vec{I} + (\alpha + \mu + \gamma), \\
x_8 &= (\epsilon + \mu + \sigma \beta)(\eta + \sigma \beta) \beta \vec{S} \vec{I} - (\epsilon + \mu + \sigma \beta)(\mu + p)(\alpha + \mu + \gamma) \eta \vec{R}.
\end{align*}$$

**Theorem 3.2** If the solution of (12) is locally asymptotic stable, then $\tau = 0$ and $R_0 > 1 + \frac{\rho^2(\alpha + \mu + \gamma)(\alpha + \mu + \gamma)}{p^2(\mu + p)(\alpha + \mu + \gamma)}$.

**Proof.** Let $\tau = 0$. From (13),

$$\lambda^4 + (x_1 + x_5) \lambda^3 + (x_2 - x_6) \lambda^2 + (x_3 - x_7) \lambda + x_4 - x_8 = 0.$$

Since $R_0 > 1 + \frac{\rho^2(\alpha + \mu + \gamma)(\alpha + \mu + \gamma)}{p^2(\mu + p)(\alpha + \mu + \gamma)}$, $\vec{S} > 0, \vec{E} > 0, \vec{I} > 0, \vec{R} > 0$. 

6
By the method of Routh-Hurwitz criteria, we get

\[ x_9 = x_1 - x_5 = \beta I + \eta R + 3 \mu + p + \alpha + \gamma > 0, \]

\[ x_{10} = (x_1 - x_3)(x_1 - x_6) - (x_1 - x_7) \]

\[ = ((\mu + p) + \beta I + \gamma) + \mu + \eta R(x_1 - x_3 + x_5 + x_6) + (\mu + \eta R)((\alpha + \mu + \gamma) + A(x_1 + x_3 + x_5 + x_6)) + (\mu + \eta R)(\mu + p + \alpha + \gamma) \]

\[ = (x_1 - x_3) \left[ (x_1 - x_4)(x_3 - x_7) - (x_1 - x_3)(x_4 - x_8) \right] (x_3 - x_7)^2. \]

Let \( m = \mu + \eta R, n = (\mu + p) + \beta I. \) Thus,

\[ x_{11} = [(\alpha + \mu + \gamma)(m - (\mu + p)) + \eta (\alpha + \mu + \gamma)Rn + \eta (\alpha + \mu + \gamma)R(\alpha + \mu + \gamma)]((\alpha + \mu + \gamma)n^2 + mn^2 + (\alpha + \mu + \gamma)^2 n + (\alpha + \mu + \gamma)^2 m + (\alpha + \mu + \gamma)^2 mn + \eta \nu \mu R(n^2 - 2(\alpha + \mu + \gamma)n + 2m(\alpha + \mu + \gamma))] \]

\[ = (x_1 - x_3) \left[ (x_1 - x_6)(x_3 - x_7) - (x_1 - x_3)(x_4 - x_8) \right] (x_3 - x_7)^2. \]

We have \( x_{11} > 0, \) since \( n - (\mu + p) > 0, \)

\[ x_{12} = \left| \begin{array}{ccc}
-1 & x_2 - x_6 & x_4 - x_8 \\
0 & x_1 - x_5 & x_3 - x_7 \\
0 & x_1 - x_5 & x_3 - x_7 \\
\end{array} \right| = a_4 x_{11}. \]

Taking note of that \( a_4 = (\epsilon + \mu + \sigma \mu)(\mu + p)(\alpha + \mu + \gamma)\eta R, \) it is anything but difficult to acquire that \( x_{12} > 0. \) Subsequently, the real parts are negative in (14). This completes the verification of the Theorem 3.2. Here the roots of \( \Omega(\lambda) = 0 \) have negative real roots. Hence, there exists a \( \tau_0 > 0 \) to such that \( \tau \in [0, \tau_0] \) in (13), we have

\[ \Omega(\lambda) = 0, \quad Re(\lambda) < 0 \quad for \quad \tau \in [0, \tau_0), \]

what's more, when \( \tau = \tau_0, \) \( Re(\lambda) < 0. \) To decide this \( \tau_0 \) and the related simply \( \phi_0(\phi_0 > 0) \) imaginary roots, we understand (13) with \( \lambda = \phi_0 I. \) For straightforward, we use \( \tau, \phi \) rather than \( \tau_0, \phi_0. \) From (13), we have

\[ x_1 \phi^4 - x_1 x_3^2 i - x_2 x_3^2 + x_3 x_4 + x_4 - (-x_6 x_3^2 i - x_5 x_3^2 + x_7 + x_8) \]

\[ (\cos \phi T - i \sin \phi T) = 0. \]

Comparing the coefficients of real and imaginary parts, we get

\[ (x_8 - x_6 x_3^2) \cos \phi T + (x_7 - x_5 x_3^2) \sin \phi T = \phi^4 - x_2 x_3^2 + x_4, \]

\[ (x_6 x_3^2 - x_7 x_3^2) \cos \phi T + (x_5 - x_6 x_3^2) \sin \phi T = x_1 x_3^2 - x_3 x_4. \]

\[ \cos \phi T = \frac{1}{\Delta} \left[ \begin{array}{c}
\phi^4 - x_2 x_3^2 + x_4 \\
x_8 - x_6 x_3^2 \\
\end{array} \right], \]

\[ \sin \phi T = \frac{1}{\Delta} \left[ \begin{array}{c}
-x_1 x_2 - x_3 x_5 \\
x_5 x_3^2 - x_4 x_3 \\
\end{array} \right]. \]

where \( \Delta = \left| \begin{array}{cc}
x_3^2 & x_4 x_3 \\
x_8 - x_6 x_3^2 & x_5 x_3^2 - x_4 x_3 \\
\end{array} \right|. \]
\[ (x_8 - x_0 \phi^2)^2 + (x_7 - x_3 \phi^3)^2 = x_5 \phi^6 + (x_6 - 2x_5x_7)\phi^4 + (x_2^2 - 2x_6x_8)\phi^2 + x_5^2 = (e_1 \phi^6 + e_2 \phi^4 + e_3 \phi^2 + e_4) > 0. \]

Here \( \sin^2 \phi \tau + \cos^2 \phi \tau = 1 \), it follows that

\[ \phi^4 + x_{13} \phi^{12} + x_{14} \phi^{10} + x_{15} \phi^8 + x_{16} \phi^6 + x_{17} \phi^4 + x_{18} \phi^2 + x_{19} = 0 \]  

(18)

where

\[ x_{13} = \frac{1}{\Lambda} (c_1^2 + 2x_9x_{10} - e_1^2), \]
\[ x_{14} = \frac{1}{\Lambda} (2c_1c_2 + x_9^2 + 2x_9x_{11} - 2e_1e_3), \]
\[ x_{15} = \frac{1}{\Lambda} (c_2^2 + 2c_1c_3 + 2x_9x_{12} + 2x_{10}x_{11} - e_2^2 - 2e_1e_3), \]
\[ x_{16} = \frac{1}{\Lambda} (2c_1c_4 + 2c_2c_3 + x_9^2 + 2x_{10}x_{12} - 2e_1e_4 - 2e_2e_3), \]
\[ x_{17} = \frac{1}{\Lambda} (c_3^2 + 2c_2c_4 + 2x_{11}x_{12} - e_2^2 - 2e_2e_4), \]
\[ x_{18} = \frac{1}{\Lambda} (2c_3c_4 + x_{11}^2 - 2e_3e_4), \]
\[ x_{19} = \frac{1}{\Lambda} (c_4^2 - e_3^2). \]

Denoting \( x = \phi^2 \), (18) becomes

\[ x^2 + x_{13}x^6 + x_{14}x^4 + x_{15}x^2 + x_{16}x^3 + x_{17}x^2 + x_{18}x + x_{19} = 0 \]  

(19)

First, \( x = 0 \) is not a root of (19) if \( x_8 \neq 0 \). There is no positive real root in (19). Therefore \( \phi = \sqrt{x} \) does not get the solution. Hence bifurcation parameter \( \tau \) does not occur and Hopf bifurcation is not evaluate. The equation (19) always has positive real roots. Let the hypothesis as follows:

\( (\Omega_1) \): Equation (19) is possible one positive real root;
\( (\Omega_2): \Lambda \xi = [4\phi^6 + 3(x_7^2 - 2x_2 - x_3^2)\phi^4 + 2(x_2^2 - x_3^2 + 2x_4 + 5x_5 - 2x_1x_3)\phi^2 + x_1 - x_2^2 + 2x_6x_8 - 2x_2x_4] > 0 \) for any \( \phi > 0 \).

Let \( x_0 \) be the positive roots of (19), denoting \( \phi_0 = \sqrt{x_0} \). From the above, we get

\[ \tau_j = \frac{1}{4\phi_0} \left( \cos^{-1} \left( \frac{c_1\phi_0^6 + c_2\phi_0^6 + c_3\phi_0^6 + c_4\phi_0^6}{c_1\phi_0^6 + c_2\phi_0^6 + c_3\phi_0^6 + c_4\phi_0^6} \right) + 2j\pi \right), j=0,1,2,3,\ldots \]

and

\[ \tau_0 = \frac{1}{4\phi_0} \cos^{-1} \left( \frac{c_1\phi_0^6 + c_2\phi_0^6 + c_3\phi_0^6 + c_4\phi_0^6}{c_1\phi_0^6 + c_2\phi_0^6 + c_3\phi_0^6 + c_4\phi_0^6} \right), j = 0. \]

The set of ordered pair is \( (\phi_0, \tau_0) \) to find the polynomial roots of (13) neighborhood \( \tau_0 \) and differentiating with respect to \( \tau \), we get

\[ \frac{dA}{d\tau} \left|_{\tau=\tau_0} \right. = \frac{-4x_3^3 + 3x_1x_2^2 + 2x_2x_4 + x_3)e^4 \tau}{A(x_3x_4 + x_6x_7 + x_7x_8 + x_8)} + \frac{3x_5x_7^2 + 2x_6x_8 + x_7}{A(x_3x_4 + x_6x_7 + x_7x_8 + x_8)} - \frac{\tau}{A}. \]  

(20)

Letting (20), we have

\[ \text{Re} \frac{dA}{d\tau} \left|_{\tau=\tau_0} \right. = \frac{1}{\phi^4} \left( (3x_1\phi^2 - x_3)[(x_5\phi^3 - x_7\phi)\cos \phi \tau + (x_8 - x_6 \phi^2)\sin \phi \tau] \right. \\
+ (4\phi^6 - 2x_2x_4) [(x_8 - x_6 \phi^2)\cos \phi \tau - (x_5 \phi^3 - x_7 \phi)\sin \phi \tau] \\
+ (x_7 - x_3 \phi^3)(x_5 \phi^3 - x_7 \phi) + 2x_6 \phi (x_8 - x_6 \phi^2) \\
= \frac{1}{\phi^4} \left( (4\phi^6 + 3x_2 - 2x_2 - x_3^2) \phi^4 + 2(x_2^2 - x_3^2 + 2x_4 + 2x_5x_7 - 2x_1x_3) \phi^2 \\
+ x_7 - x_1^2 + 2x_6x_8 - 2x_2x_4 \right), \]

where, \( \nabla = (x_5 \phi^3 - x_7 \phi^2 + (x_8 - x_6 \phi^2)^2 > 0 \). If \( (\Omega_2) \) is satisfied, then (20) > 0 will hold for any \( \phi > 0 \).

So, \( \text{sign}(\text{Re} \frac{dA}{d\tau}) \mid \tau = \tau_0 = \text{sign}(\text{Re} \frac{dA}{d\tau}) \mid \tau = \tau_0 \) \( \Rightarrow \text{sign}(.) = 1 \).

Therefore, the roots of (14) have negative real parts. If \( \tau = \tau_0 \), then other negative real roots have in \( \Omega_1, \lambda = 0 \). In (14), if \( \tau \in [0, \tau_0) \) and \( (\Omega_1, \Omega_2) \) assumption, then the COVID-19 infection is stable. Similarly, if \( \tau > \tau_0 \), then the COVID-19 infection is unstable and equation (2) undertakes bifurcation at \( \tau = \tau_0 \).
4. Numerical Experiment

Let us consider the parameters $b = 0.5$, $\gamma = 0.008$, $\epsilon = 0.1$, $\mu = 0.0018$, $\rho = 0.5$, $\beta = 0.1923$, $\eta = 0.1$, $\sigma = 0.5$, $\alpha = 0.5$ with $(S(0), E(0), I(0), R(0))$ [34]. In the event that (19) has no positive roots, at that point the COVID-19 infection present equilibrium is locally asymptotic stable. On the off chance that $R_0 = 2.47$, at that point COVID-19 disease present equilibrium $E = (3.1, 1.4, 10.01, 2.01)$. From (19), we have that

$$x^2 + 500.01x^6 + 10025x^5 + 23423x^4 + 4099x^3 + 28.1x^2 + 0.1x + 6.110^{-5} = 0,$$

has real negative roots. Therefore the equilibria is locally asymptotic stable and it represents Hopf bifurcation. Obviously, $R_0 = 1.92$, and the COVID-19 infection present equilibrium is $E = (3.01, 1.3, 8.1, 3.3)$. From (19), we have that

$$x^2 + 477.2304x^6 + 47123x^5 + 33257x^4 + 5008x^3 + 27.1x^2 - 1.3x - 0.001 = 0$$

have a positive real roots and others have negative real roots. Accordingly, $\phi_0 = \sqrt{\lambda} = 0.1$ It isn’t hard to evaluate the bifurcation stationary value is $\tau_0 = 1.96$. Also, it is anything but difficult to prove that $\Lambda = 2.8 > 0$, i.e., $(\Omega_2)$ is fulfilled. The phase diagrams of the system (2) is asymptotic stable when $\tau = 0.9 < \tau_0$ (see Figure 1). Also, the phase diagrams of the system (2) undergoes Hopf bifurcation when $\tau = 2 > \tau_0$ (see Figure 2). We utilize the serious cases and deaths in the individual response work, rather than deaths as it were. We additionally increment the power of the legislative activity to such an extent that the model results to a great extent coordinate the watched, with a revealing proportion. To be specific just an extent of the model created cases will be accounted for as a general rule. Consequently it would be testing given a generally brief time frame arrangement, and a few other obscure parameters to be assessed.

5. Conclusion

There is a shortage of epidemiological information about the rising coronavirus, which would be of essential significance to structure and execute auspicious, specially appointed viable general well being intercessions, isolate and travel limitations. We have contemplated a general SEIR model of COVID-19 infection with delay. If $R_0 < 1$, then stability of the disease-free equilibrium derived by Lyapunov techniques. Furthermore the effects of time delay $\tau = 0$, the COVID-19 infection is either absent or present equilibrium when $R_0 > 1$. Here $1 < R_0 < 1 + \frac{\beta\mu\sigma\eta(p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma)}{\mu\sigma\mu + p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma}$, then $E_1$ is stable. If $R_0 > 1 + \frac{\beta\mu\sigma\eta(p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma)}{\mu\sigma\mu + p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma}$, then $E_1$ is unstable. Hence, $\tau > 0$, $1 < R_0 < 1 + \frac{\beta\mu\sigma\eta(p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma)}{\mu\sigma\mu + p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma}$, $E_1$ is stable. The basic reproductive ratio $R_0 > 1 + \frac{\beta\mu\sigma\eta(p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma)}{\mu\sigma\mu + p_0\mu + p_0\rho + p_0\mu + p_0\eta + p_0\gamma}$, if the susceptible cells birth rate is high. Therefore the linearized system of (2) has no real positive roots and the stability is stable. The polynomial equation (19) has a single real positive root when $\tau < \tau_0$. The COVID-19 infection present equilibrium is stable. If $\tau > \tau_0$, the equilibrium solutions are unstable and a Hopf bifurcation occurs. Suppose, the equation (19) has more than one positive roots, it does not exit. In future, The further investigation is needed to this system. The controlling of reproduction number ratios proposes that the outbreak might be more genuine than what has been accounted for up until now, given the specific period of expanding social contacts, justifying powerful, severe general well being measures planned to relieve the weight produced by the spreading of the new infection.

Availability of data and material
To this article have no data sets where generated or analyzed in the current study Data.

Competing Interests
The authors declare there are no competing interests.

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For the writing of this paper all authors are equally contributed and also read and agreed the final copy of the manuscript.

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Figure 1: The phase diagrams of the system (2) is asymptotically stable when $\tau = 0.9$
Figure 2: The phase diagrams of the system (2) undergoes Hopf bifurcation when $\tau = 2$
The phase diagrams of the system (2) is asymptotically stable when $\tau = 0.9$
Figure 2

The phase diagrams of the system (2) undergoes Hopf bifurcation when $\tau = 2$