Elliptic Curves as Attractors in $\mathbb{P}^2$

Part 1: Dynamics

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Abstract

A study of rational maps of the real or complex projective plane of degree two or more, concentrating on those which map an elliptic curve onto itself, necessarily by an expanding map. We describe relatively simple examples with a rich variety of exotic dynamical behaviors which are perhaps familiar to the applied dynamics community but not to specialists in several complex variables. For example, we describe smooth attractors with riddled or intermingled attracting basins, and we observe “blowout” bifurcations when the transverse Lyapunov exponent for the invariant curve changes sign. In the complex case, the elliptic curve (a topological torus) can never have a trapping neighborhood, yet it can have an attracting basin of large measure (perhaps even of full measure). We also describe examples where there appear to be Herman rings (that is topological cylinders mapped to themselves with irrational rotation number) with open attracting basin. In some cases we provide proofs, but in other cases the discussion is empirical, based on numerical computation.

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1 Introduction

In the paper “Self-maps of $\mathbb{P}^2$ with invariant elliptic curves”, Bonifant and Dabija (see [BD]) constructed a number of examples of rational maps $f$ of the real or complex projective plane of degree $d \geq 2$ with an elliptic curve $C = f(C)$ as invariant subset. This case of a curve of genus one is of particular interest, since genus zero examples are easy to construct while higher genus examples cannot exist. (Compare Remarks 1.2 and 2.1.) The present paper studies the extent to which such an invariant elliptic curve $C \subset \mathbb{P}^2$ can be an “attractor”. Here we must distinguish between possible degrees of attraction. By definition, a compact set $A = f(A) \subset \mathbb{P}^2$ will be called:

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• a measure-theoretic attracting set if its attracting basin, consisting of all points whose orbits converge to $A$, has positive Lebesgue measure, and

• a trapped attracting set if there it has a compact trapping neighborhood $N$ such that $f(N) \subset N$ and $A = \cap_{n} f^{n}(N)$.

In both cases, the word attractor will be reserved for an attracting set $A$ which contains a dense orbit.$^{1}$ A measure-theoretic attractor will be called a global attractor if its attracting basin has full measure in the ambient space $\mathbb{P}^2$.

In both the real and complex cases, we provide examples in which a smooth elliptic curve $C$ is a measure-theoretic attractor. In fact there are examples in which there are two distinct smooth measure-theoretic attractors whose attracting basins are thoroughly intermingled, so that they have the same topological closure. We provide an example of a singular real elliptic curve which is a trapped attractor; but we prove that a complex elliptic curve can never be a trapped attractor. In fact, it seems likely that the attracting basin of a complex elliptic curve cannot have interior points, so that the set of points not attracted to $C$ must be everywhere dense. (Compare Lemma 4.5 as well as Proposition 6.3.)

We describe examples in which it seems possible that the elliptic curve is a global attractor so that its attracting basin has full measure. We also provide a family of examples where there appears to be a pair of Herman rings as attractor, with an open neighborhood as attracting basin. However, in many cases the dynamical behavior is sufficiently confusing that we are not even sure what to conjecture.

An Outline of the Following Sections. Section 2 describes some basic ideas, including the transverse Lyapunov exponent along an invariant elliptic curve, which is a primary indicator of whether or not the curve is attracting. Methods for actually computing this transverse exponent will be described in Part 2, the sequel to this paper; however, the conclusions of these computations are often quoted below. Section 3 describes the very restrictive class of rational maps with a first integral. These are used in Sec. 4 to construct a three parameter family of more interesting rational maps of degree four. Section 5 studies eight explicit examples, with conjectured descriptions based on numerical computation. In the first three examples, all observed randomly chosen orbits seem to converge to the Fermat curve $x^3 + y^3 + z^3 = 0$, both in the real case with ambient space $\mathbb{P}^2(\mathbb{R})$ and in the complex case with ambient space $\mathbb{P}^2(\mathbb{C})$. This suggests that the real or complex Fermat curve may be a global attractor, with attracting basin of full measure. (However, other attractors with basins of extremely small measure could easily be missed by such random samples.) Example 5.4 suggests that a cycle of two Herman rings can be a measure theoretic attractor in $\mathbb{P}^2(\mathbb{C})$ (perhaps even a global attractor) for such a map with invariant elliptic curve. In Example 5.5 there is an attracting fixed point at the “north pole”, while the “equator” forms a measure theoretic attractor, while in Example 5.6 a typical orbit bounces between three near-attractors. This section concludes with examples of lower degree maps which have a smooth invariant elliptic curve. In particular, Example 5.8 describes a degree 3 map of $\mathbb{P}^2(\mathbb{C})$ which appear to have the Fermat curve as a global attractor. All of these conclusions have been empirical. However, Secs. 6 and 7 provide cases with explicit proofs. Example 6.1 describes maps with three different attractors with thoroughly intermingled basins, all of positive measure. (Compare [AKYY].) Two of these basins are dense in the Julia set, while the third

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$^{1}$For some purposes it is important to have a more restrictive definition, as in [AK]. Compare the discussion of “Milnor attractors” in [Ko] or [ABS]. For other concepts of attractor, see Remark 6.1 as well as [GuHS], and for exotic examples see [AKYY], [Kn], [MMP], [ABS], [OS], [OSAYK]. For dynamics in $\mathbb{P}^2(\mathbb{C})$ see [FS2], [FW], [JW], [Si], [U2].
basin, which is everywhere dense, is equal to the Fatou set. Theorem \[7\] provides examples of singular real elliptic curves which are trapped attractors under suitable rational maps; while Theorem \[7,3\] shows that a complex elliptic curve can never be a trapped attractor. (We don’t know whether non-singular real curves can be trapped attractors.) Section \[8\] provides a more general discussion of Herman rings. The transverse Lyapunov exponent for a (complex 1-dimensional) Herman ring or Siegel disk in \(\mathbb{P}^2(\mathbb{C})\) provides a strict criterion for attraction or repulsion. This exponent is no longer constant, as it was in the case of an elliptic curve, but is rather a convex piecewise linear function on the ring or disk, constant on each invariant circle. We prove the persistence of invariant circles in \(\mathbb{P}^2(\mathbb{R})\) under suitable hypotheses, but our results are not strong enough to prove the conjecture that the associated Herman rings in \(\mathbb{P}^2(\mathbb{C})\) are also persistent. Section \[9\] concludes the discussion by providing a brief outline of open problems.

We will usually concentrate on the complex case, although many of the illustrations will necessarily illustrate the real case.

**Remark 1.1. Computation.** Numerical computations are extremely delicate near the invariant curve \(\mathcal{C}\). Thus it is essential to work with multiple precision arithmetic; but even so, numerical simulation of the dynamics must be understood as a hint of the true state of affairs, rather than a definitive answer. One surprising aspect of these maps is that in some cases orbits tend to spend quite a bit of time extremely close to \(\mathcal{C}\) even when the transverse exponent is positive. (Compare Figs. \[5\] and \[8\]) In a similar situation, Maistrenko, Maistrenko and Popovich (see [MMP, p. 2713]) report that, in the presence of a small positive value of the transverse exponent: “a trajectory may spend a very long time in the neighborhood of the invariant subspace. From time to time, the repulsive character of the chaotic set manifests itself, and the trajectory exhibits a burst in which it moves far away from the invariant subspace, to be reinjected again into the proximity of this subspace. ··· The positive value of the Lyapunov exponent applies over long periods of time. For shorter time intervals, the net contribution ··· may be negative, and the trajectory is attracted to the chaotic set.” (Similar behavior was described in [PST].)

**Remark 1.2. Genus Zero.** Attracting curves of genus zero are easy to construct. (Compare Example \[5\]) Thus, for the map \((x : y : z) \mapsto (x : y : z/2)\), the line \(z = 0\) is an attracting curve with the region \(|z|^2 < |x|^2 + |y|^2\) as trapping neighborhood. Similarly, if \((x : y) \mapsto (f_1(x, y) : f_2(x, y))\) is any rational map of \(\mathbb{P}^1\) of degree \(d \geq 2\), then the line \(z = 0\) is a trapped attracting curve for the map \((x : y : z) \mapsto (f_1(x, y) : f_2(x, y) : z^d)\). In particular, if we start with a map of \(\mathbb{P}^1\) which has a dense orbit (for example a Lattès map—compare Remark \[13\]), then we obtain a trapped attractor.

## 2 Rational Maps and the Transverse Lyapunov Exponent.

Let \(f\) be a rational map of \(\mathbb{P}^2 = \mathbb{P}^2(\mathbb{C})\). We can write \(f : \mathbb{P}^2 \setminus \mathcal{I} \to \mathbb{P}^2\), where

\[
f(x : y : z) = (f_1(x, y, z) : f_2(x, y, z) : f_3(x, y, z))
\]

using homogeneous coordinates \((x : y : z)\) where \((x, y, z) \in \mathbb{C}^3 \setminus \{(0, 0, 0)\}\) are well defined up to multiplication by a common non-zero factor. Here \(f_1, f_2, f_3\) are to be homogeneous polynomials of the same degree \(d = d(f) \geq 2\) with no common factor, and \(\mathcal{I} = \mathcal{I}(f)\), the *indeterminacy set*, is the finite set consisting of all common zeros of \(f_1, f_2, f_3\). By definition, \(d\) is the *algebraic degree* of \(f\). Such a rational map \(f\) is called *regular* if \(\mathcal{I}_f\) is vacuous so that \(f\) is an everywhere defined holomorphic map
from $\mathbb{P}^2$ to itself. The topological degree of $f$ as a map from $\mathbb{P}^2$ to itself is then equal to $d^2$, while the algebraic number of fixed points is $d^2 + d + 1$. However, if $I \neq \emptyset$, then there will be fewer fixed points (or sometimes an entire curve of fixed points), and a generic point will have fewer than $d^2$ preimages.

Now consider an algebraic curve $C \subset \mathbb{P}^2$, defined by a homogeneous equation $\Phi(x, y, z) = 0$ of degree $\deg(C) \geq 1$. We will say that a rational map $f$ is well defined on $C$ if the intersection $C \cap I_f$ is empty so that $f$ is defined and holomorphic throughout a neighborhood of $C$. It then follows that the image $C' = f(C)$ is itself an algebraic curve of degree $\deg(C') \geq 1$. Furthermore, the degree of the restriction $f|_C : C \to C'$ is determined by the relation\(^2\)

$$d(f) \deg(C) = d(f|_C) \deg(C'). \quad (1)$$

**Definition.** An algebraic curve $C \subset \mathbb{P}^2$ will be called invariant under $f$ if $f$ is well defined on $C$ and if $f(C) = C$. It then follows from Eq. (1) that the degree of the restriction $f|_C : C \to C$ is precisely equal to $d(f)$, the degree of the equations which define $f$.

**Remark 2.1. Curves of Higher Genus.** As one consequence of this discussion, it follows that a curve of genus $g \geq 2$ can never be invariant under a map of $\mathbb{P}^2$ of degree $d \geq 2$. For it follows from the Riemann-Hurwitz formula (see for example [M3]) that a curve of genus $\geq 2$ does not admit any self-maps of degree $\geq 2$.

On the other hand, if $C$ contains points of indeterminacy then these remarks break down. For example, $C \setminus (I \cap C)$ may consist entirely of fixed points, or may map to a single point under $f$. In cases where $I \cap C$ may be nonempty, but the image $f(C \setminus (I \cap C))$ is contained in $C$, the curve $C$ will be called weakly $f$-invariant. If $C$ is smooth and weakly invariant, then $f$ extends uniquely to a holomorphic map from $C$ to itself; but the degree on $C$ may be smaller than $d(f)$. (Compare Remarks 1.2 and 5.3 below.)

Let $D(n) = nD(1)$ be the divisor class on $C$ which is obtained by intersecting $C$ with a generic curve of degree $n$ in $\mathbb{P}^2$. A given holomorphic map $g : C \to C$ of degree $d > 0$ extends to a rational map of $\mathbb{P}^2$ which is well defined on $C$ if and only if

$$g^*D(1) = D(d).$$

(See [BD] §2.) If $d < \deg(C)$ then this extension is unique; but if $d \geq \deg(C)$ then there exists a $3^{(d-\deg(C)+2)}$ dimensional family of such extensions since we can always replace the associated homogeneous polynomial map $F : C^3 \to C^3$ by $F + \Phi H$ where $\Phi = 0$ is the defining equation for $C$ with $d(\Phi) = \deg(C)$, and where $H : C^3 \to C^3$ is any homogeneous map of degree $d - d(\Phi)$. In this case, a generic extension will be regular (that is, defined and holomorphic everywhere).

One particular virtue of an elliptic curve $C \subset \mathbb{P}^2$ is that any holomorphic self-map must be linear in terms of suitable coordinates. In fact such a curve is conformally isomorphic to some flat torus $C/\Omega$, where $\Omega$ is a lattice. More precisely, there is a holomorphic uniformizing map

$$v : C/\Omega \to C$$

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\(^2\)Proof Outline: A generic line $L$ intersects $C'$ in $\deg(C')$ distinct points, none of which is a critical value of $f|_C$. Each of these has $\deg(f|_C)$ preimages in $C$. On the other hand by Bezout’s Theorem, the curve $f^{-1}(L)$ of degree $d(f)$ will intersect $C$ in $d(f) \deg(C')$ points, counted with multiplicity. In fact, for generic $L$, each of these intersections will be transverse, and it follows that $d(f) \deg(C) = d(f|_C) \deg(C')$, as required.
which is biholomorphic in the case of a smooth elliptic curve, and is one-to-one except on finitely many singular points in the case of a singular curve. Any holomorphic self-map of \( C \) lifts to a holomorphic self-map of \( C/\Omega \) which is necessarily linear, \( t \mapsto at + b \). It follows easily that the normalized Lebesgue measure on \( C/\Omega \) pushes forward to a canonical smooth probability measure \( \lambda \) on \( C \) which is invariant under every non-constant self-map. The derivative \( a \) of the linear map on \( C/\Omega \) will be called the *multiplier* of \( f \) on \( C \). Note that the product \( a\Omega \) is a sublattice of finite index in \( \Omega \), and that \( |a|^2 \) is equal to the index of this sublattice. Equivalently, \( |a|^2 \) is the topological degree of \( f \) considered as a map from \( C \) to itself. In particular, \( |a|^2 \) is equal to the algebraic degree \( d \) of \( f \) whenever \( C \subset \mathbb{P}^2 \) is invariant under the rational map \( f \). Since we always assume that \( d \geq 2 \), it follows that this canonical measure \( \lambda \) is ergodic.

In the case of an elliptic curve defined by equations with real coefficients, the real curve

\[ C_\mathbb{R} = C \cap \mathbb{P}^2(\mathbb{R}) \]

has at most two connected components. In the case where there are two components, if \( C_\mathbb{R} \) is mapped into itself by a rational map \( f \) of \( \mathbb{P}^2(\mathbb{R}) \), then at least one of the two components, say \( C_\mathbb{R}^0 \), must map onto itself under \( f \) (or at least under \( f \circ f \)). In this case we have a uniformizing map \( \mathbb{R}/\mathbb{Z} \to C_\mathbb{R}^0 \), such that \( f \) (or \( f \circ f \)) corresponds to a map on \( \mathbb{R}/\mathbb{Z} \) which is linear with constant integer multiplier. Such an invariant component \( C_\mathbb{R}^0 \) has a canonical invariant probability measure.

**The Transverse Lyapunov Exponent.** Let \( C \) be a smooth curve, invariant under the rational map \( f \). We will describe an associated real number which is conjectured to be negative if and only if \( C \) is a measure theoretic attractor. To fix ideas we will concentrate on the complex case, but constructions in the real case are completely analogous. The notation \( T\mathbb{P}^2|_C \) will be used for the complex 2-plane bundle of vectors tangent to \( \mathbb{P}^2(\mathbb{C}) \) at points of the submanifold \( C \), and the abbreviated notation \( T_A C \) will be used for the “transverse” complex line bundle over \( C \) having the quotient vector space

\[ T_A(C, p) = T(\mathbb{P}^2, p)/T(C, p) \]

as typical fiber. In other words, there is a short exact sequence \( 0 \to TC \to T\mathbb{P}^2|_C \to T_A C \to 0 \) of complex vector bundles over \( C \). It is sometimes convenient to refer to \( T_A C \) as the “normal bundle” of \( C \), although that designation isn’t strictly correct. If \( f : \mathbb{P}^2 \to \mathbb{P}^2 \) with \( f(C) \subset C \), then \( f \) induces linear maps

\[ f_A^t(p) : T_A(C, p) \to T_A(C, f(p)) \quad \tag{2} \]

and these linear maps collectively form a fiberwise linear self-map \( f_A' : T_A C \to T_A C \).

Now choose a metric on this complex normal bundle. That is, choose a norm \( ||\vec{v}||_A \) on each quotient vector space \( T_A C \) which depends continuously on \( \vec{v} \), vanishes only on zero vectors, and satisfies \( ||t\vec{v}||_A = |t| ||\vec{v}||_A \). Then the linear map \( f_A' \) of Eq. (2) has an operator norm

\[ ||f_A'(p)|| = ||f_A'\vec{v}||_A/||\vec{v}||_A \quad \tag{3} \]

which is well defined and satisfies the chain rule. Here \( \vec{v} \) can be any non-zero vector in the fiber \( T_A(C, p) \) over \( p \). By definition, the *transverse Lyapunov exponent* along the invariant curve \( C \) is equal to the rate of exponential growth

\[ L_{\text{Lyap}} C = \lim_{k \to \infty} (1/k) \log \|f_A^{\circ k}(p)\| \]
for almost every choice of initial point \( p \in C \). By the Birkhoff Ergodic Theorem, this coincides with the average value

\[
\text{Lyap}_C(f) = \int_C \log \|f'(p)\| \, d\lambda(p).
\]

Using the fact that the measure \( \lambda \) is invariant under \( f \), it is not hard to check directly that this average value is independent of the choice of metric.

Thus a negative value of \( \text{Lyap}_C \) means that under iteration of \( f \) almost any point which is “infinitesimally close” to \( C \) will converge towards \( C \). A key role in this case is played by the stable sets of the various points \( p \in C \). By definition, the stable set of \( p \) is the union of all connected sets containing \( p \) for which the diameter of the \( n \)-th forward image tends to zero as \( n \to \infty \). Many such stable sets are smooth curves. With a little imagination, some of these are clearly visible in Figs. 3 through 11. It is natural to expect that negative values of \( \text{Lyap}_C \) will imply that \( C \) is a measure-theoretic attractor. (A sketch of a proof is given in [AKYY]; and a very special case will be proved in Theorem 6.2 below.)

On the other hand, if \( \text{Lyap}_C > 0 \) then almost any “infinitesimally close” point will be pushed away from \( C \). It seems natural to conjecture that positive values of \( \text{Lyap}_C \) should imply that the attracting basin of \( C \) has measure zero. However, this seems like a difficult question. (Compare Remark 6.7.)

The term blowout bifurcation has been introduced in [OS] for a transition in which a transverse Lyapunov exponent crosses through zero. (Compare [MMP] or [AAN].)

### 3 Maps with First Integral.

By definition, a first integral for a dynamical system is a non-constant function which is constant on each orbit. In particular, by a first integral for a rational map \( f : \mathbb{P}^2 \setminus I_f \to \mathbb{P}^2 \) we will mean a rational function \( \eta : \mathbb{P}^2 \setminus I_\eta \to \mathbb{P}^1 \), with values in the projective line, which satisfies

\[
\eta(f(x : y : z)) = \eta(x : y : z)
\]

whenever both sides are defined. Identifying \( \mathbb{P}^1 \) with the Riemann sphere \( \hat{\mathbb{C}} = \mathbb{C} \cup \{\infty\} \), we will write

\[
\eta(x : y : z) = \Phi(x, y, z)/\Psi(x, y, z) \in \hat{\mathbb{C}},
\]

where \( \Phi \) and \( \Psi \) are homogeneous polynomials of the same degree without common factor. It follows that \( \mathbb{P}^2 \) has a somewhat singular “foliation” by algebraic curves of the form

\[
\alpha \Phi(x, y, z) + \beta \Psi(x, y, z) = 0,
\]

which intersect only in the finite set \( I_\eta \) consisting of common zeros of \( \Phi \) and \( \Psi \), and such that each of these curves is weakly invariant under \( f \) as defined in [2]. (A point can be contained in two such curves only if it is either periodic, or a point of indeterminacy for \( f \).) Such maps are exceedingly special. For example we have the following.

**Lemma 3.1. Some Maps with First Integral.** Let \( f \) be a rational map with first integral, such that a generic point of \( \mathbb{P}^2 \) is contained in an elliptic curve which is mapped to itself with degree \( d \geq 2 \). Then:

- There are no dense orbits, since every orbit is contained in a weakly invariant curve.
Periodic points, repelling along this curve, are everywhere dense. Hence the Fatou set, that is the union of open sets on which the iterates of f form a normal family, is empty.

For most values of n there are infinitely many fixed points of \( f^n \), with at least one in each weakly invariant curve. Hence there must be an entire algebraic curve of such points.

The indeterminacy set \( I_f \) is necessarily non-empty.

The last statement follows since there are infinitely many points of fixed period \( n \), or since a generic point has \( d \) preimages in the invariant curve which passes through it, but also just \( d \) (rather than \( d^2 \)) preimages in all of \( \mathbb{P}^2 \). The other statements are easily verified. \( \square \)

Here is a class of examples which generalize a construction due to A. Desboves (see [De]). For any smooth cubic curve \( C \subset \mathbb{P}^2 \), there is a canonical map \( f : C \rightarrow C \) called the tangent process, constructed as follows. For any point \( p \in C \), let \( L_p \subset \mathbb{P}^2 \) be the unique line which is tangent to \( C \) at \( p \). Then the image \( f(p) \) is defined by the equation

\[
L_p \cap C = \{ p \} \cup \{ f(p) \}.
\]

In fact if we choose the parametrization \( v : \mathbb{C}/\mathbb{Z} \rightarrow \mathbb{C} \) correctly, then three points \( t_j \) of \( \mathbb{C}/\mathbb{Z} \) will correspond to collinear points of \( C \) if and only if \( t_1 + t_2 + t_3 = 0 \). In our case, since there is a double intersection at \( p \), we obtain the equation \( 2t_1 + t_3 = 0 \) or \( t_1 \mapsto t_3 = -2t_1 \). Thus \( f \) has multiplier \(-2\) and degree 4.

Now start with two distinct cubic curves in \( \mathbb{P}^2 \), described by homogeneous equations \( \Phi(x, y, z) = 0 \) and \( \Psi(x, y, z) = 0 \). Then there is an entire one-parameter family of such curves (Eq. (5)) filling out the projective plane. In fact, any point of \( \mathbb{P}^2 \) which is not a common zero of \( \Phi \) and \( \Psi \) belongs to a unique curve

\[
\Phi/\Psi = \text{constant} = -\beta/\alpha \in \hat{\mathbb{C}}.
\]

If a generic curve in our one parameter family is smooth, then a generic point \( p \in \mathbb{P}^2 \) belongs to a unique smooth curve \( C_p \) in the family. Applying the tangent process at \( p \), we obtain a well defined image point \( f(p) \in C_p \). Since \( p \) is generic, this extends to a uniquely defined rational map of \( \mathbb{P}^2 \) which carries each curve of our family into itself.

Let us specialize to the classical example, with \( \Phi(x, y, z) = x^3 + y^3 + z^3 \) and \( \Psi(x, y, z) = 3xyz \), as studied by Desboves (where the factor 3 is inserted for later convenience). The corresponding foliation of the real projective plane \( \mathbb{P}^2(\mathbb{R}) \) by the curves of Eq. (5) is illustrated in Fig. 11. This foliation has three kinds of singularities, all represented in the figure. There are:

(a) Three singularities where two of the three coordinates \( x, y, z \) are zero. These all lie in the real plane \( \mathbb{P}^2(\mathbb{R}) \subset \mathbb{P}^2(\mathbb{C}) \).

(b) Three singularities in the real plane (or nine in the complex plane) where all of these curves intersect. Each of these lies along just one of the three coordinate axes.

(c) One real singularity (or nine complex singularities) where \( x^3 = y^3 = z^3 \), represented by the center in the upper right of Fig. 11.

According to Desboves, the tangent processes for these various curves \( \Phi/\Psi = k \) fit together to yield a well defined rational map \( f_0 : \mathbb{P}^2 \setminus \mathcal{I} \rightarrow \mathbb{P}^2 \) which is given by the formula

\[
f_0(x : y : z) = (x(y^3 - z^3) : y(z^3 - x^3) : z(x^3 - y^3)). \tag{6}
\]

The indeterminacy set \( \mathcal{I} = \mathcal{I}(f_0) \) for this classical Desboves map consists of the twelve points of type (a) and (c), as listed above. This particular example has the advantage (as compared with a generic
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Fig. 1: “Foliation” of the real projective plane by the family of elliptic curves $\Phi/\Psi = k \in \hat{\mathbb{C}}$, where $\Phi = x^3 + y^3 + z^3$ and $\Psi = 3xyz$. Here $\mathbb{P}^2(\mathbb{R})$ is represented as a unit 2-sphere with antipodal points identified. These real curves intersect only at their three common inflection points, which look dark in the figure. In the limiting case as $k \to \infty$, the curve $\Phi = k\Psi$ degenerates to the union $xyz = 0$ of the three coordinate lines, which intersect at the points $(-1,0,0)$, $(0,1,0)$ and $(0,0,1)$ respectively near the left, top, and center of the figure.

choice for $\Phi$ and $\Psi$) that most of the curves in our one parameter family are non-singular, and contain no points of indeterminacy. The only exceptions are the curves $\Phi = k\Psi$ with $k^3 = 1$, which are singular at points of indeterminacy of type (c), and the degenerate case $\Psi = 0$ (corresponding to $k = \infty \in \hat{\mathbb{C}}$) with singular indeterminacy points of type (a). The foliation singularities of type (b), where all of the curves intersect, are all fixed points at which the value $f_0(p) = p$ is well defined.

For further examples of rational maps of $\mathbb{P}^2$ with first integral, see Example 6.8 and Remark 6.8.

4 The Desboves Family.

Let $\Phi(x, y, z)$ be the homogeneous polynomial $x^3 + y^3 + z^3$. The Fermat curve $\mathcal{F}$ is defined as the locus of zeros $\Phi(x, y, z) = 0$ in the projective plane $\mathbb{P}^2$. (Here we can work either over the real numbers or over the complex numbers.) Most of the examples in [5] will belong to a family of 4th-degree rational maps of $\mathbb{P}^2$ which carry this Fermat curve into itself, as introduced in [BD, §6.3]. We will call these Desboves maps, since they arise from a simple perturbation of the classical Desboves map $f_0$ of Eq. (3). Evidently $f_0$ lifts to a homogeneous polynomial map

$$F_0(x, y, z) = \left( x(y^3 - z^3), y(z^3 - x^3), z(x^3 - y^3) \right)$$

from $\mathbb{C}^3$ to itself. Geometrically, $f_0$ is defined by the property that the line from $p$ to $f_0(p)$ is tangent to the elliptic curve $(x^3 + y^3 + z^3)/3xyz = k$ which passes through the point $p$. Its set of
fixed points on each smooth curve in our family coincides with the intersection

\[ x^3 + y^3 + z^3 = 3xyz = 0 , \]

and can also be identified with the set of points of inflection on any one of these curves, or as the set of points where all of these curves intersect. This map \( f_0 \) is not everywhere defined: it has a twelve point set of points of indeterminacy as described at the end of \( \S 3 \). However, for any specified curve \( \Phi_k(x, y, z) = x^3 + y^3 + z^3 - 3kxyz = 0 \) in our family, if we replace \( F_0 \) by the sum

\[ F_L(x, y, z) = F_0(x, y, z) + L(x, y, z) \Phi_k(x, y, z) \]

where \( L \) is any linear map from \( \mathbb{C}^3 \) to itself, then we obtain a new map \( f_L \) of \( \mathbb{P}^2(\mathbb{C}) \) which coincides with \( f_0 \) on the particular curve \( \Phi_k(x, y, z) = 0 \). For a generic choice of \( L \), the resulting map \( f_L \) of \( \mathbb{P}^2(\mathbb{C}) \) is well defined everywhere.

To simplify the discussion, we will restrict attention to the case \( k = 0 \), taking

\[ \Phi(x, y, z) = \Phi_0(x, y, z) = x^3 + y^3 + z^3 , \]

and will take a linear map \( L \) which is described by a diagonal matrix,

\[ L(x, y, z) = (a x, b y, c z) . \]

**Definition 4.1. Desboves Maps.** The resulting 3-parameter family of maps of the real or complex projective plane will be called the family of Desboves maps. These maps \( f = f_{a,b,c} \) are given by the formula

\[ f(x : y : z) = \left( x(y^3 - z^3 + a \Phi) : y(z^3 - x^3 + b \Phi) : z(x^3 - y^3 + c \Phi) \right) , \tag{7} \]

where \( a, b, c \) are the parameters. Each such \( f \) maps the Fermat curve \( \mathcal{F} \), defined by the equation \( \Phi(x, y, z) = 0 \), into itself. Furthermore, each \( f \) maps each of the coordinate lines \( x = 0 \) or \( y = 0 \) or \( z = 0 \) into itself.

For special values of the parameters, the map \( f \) may have points of indeterminacy (but never on the curve). However, for a generic choice of parameters \( f \) is everywhere defined. More explicitly, it is not hard to see that \( f \) is an everywhere defined holomorphic map from \( \mathbb{P}^2 \) to itself if and only if we avoid a union of seven hyperplanes in the space \( \mathbb{C}^3 \) of parameters, defined by the equation

\[ abc(a + b + c)(a + 1 - b)(b + 1 - c)(c + 1 - a) = 0 . \tag{8} \]

**Remark 4.2. Fixed Points.** Generically, each Desboves map has 21 distinct fixed points (nine with \( xyz \neq 0 \), nine on the Fermat curve with just one of the coordinates equal to zero, and three with two coordinates equal to zero). However, there are two kinds of exception:

- If the product \( abc(a + b + c) \) is zero, then one or more of the fixed points will be replaced by an indeterminacy point.
- If one or more of the differences \( b - a, c - b, \) or \( a - c \) is equal to +1, then there is not only an indeterminacy point but also an entire line of fixed points.
In any case, there are exactly nine fixed points on the complex Fermat curve $\mathcal{F}$, forming the intersection of $\mathcal{F}$ with the locus $xyz = 0$. Consider for example the three points $(0 : \sqrt[3]{-1} : 1)$ obtained by intersecting the curve $\mathcal{F}$ with the invariant line $x = 0$. If we introduce the coordinate $Y = y/z \in \hat{\mathbb{C}}$ on this line, then the restriction of the map $f$ to this line is a rational map given by the formula

$$Y \mapsto Y \frac{bY^3 + (b + 1)}{(c - 1)Y^3 + c},$$

with fixed points at $Y = 0$, at $Y = \infty$, and at the three points $Y^3 = -1$. A brief computation shows that the derivative of this one variable map at these five fixed points is respectively

$$(b + 1)/c, \ (c - 1)/b, \ \text{and} \ 3(c - b) - 2, \ \text{where the last is counted three times}.$$ (9)

(Something very special occurs when $c = b + 1$. In that case, all five derivatives are $+1$, and in fact it is easy to check that every point on the line $x = 0$ is fixed under $f$.) Similarly, permuting the coordinates cyclically, we obtain corresponding formulas for the invariant lines $y = 0$ and $z = 0$.

**Remark 4.3. The Attracting Basin.** According to [BD, Theorem 5.4], if $C = f(C)$ is any invariant elliptic curve, then the set of iterated preimages of any point of $C$ is everywhere dense in the Julia set $J(f)$ (the complement of the Fatou set). It seems likely that the following further statement is true:

**Conjecture 4.4.** The entire attracting basin $B(C)$, consisting of all points whose forward orbits converge to $C$, is contained in the Julia set $J(f)$; hence the closure $\overline{B(C)}$ is precisely equal to $J(f)$.

An immediate consequence would be the following.

**Lemma 4.5. No Interior Points?** If this conjecture is true, then for any map $f_{a,b,c}$ in the Desboves family, the attracting basin $B(F)$ has no interior points. In other words, the closure of the complementary set $\mathbb{P}^2(\mathbb{C}) \setminus B(F)$, consisting of points which are not attracted to $F$, is the entire plane $\mathbb{P}^2(\mathbb{C})$.

**Proof.** The conjecture asserts that points outside of the Julia set are not in the basin $B = B(F)$, so we need only show that every point of $J$ can be approximated by points outside of $B$. Since the average of the differences $c - b$, $b - a$, $a - c$ is zero, it follows from (9) that the average of the transverse derivatives at the fixed points of $f$ in $\mathcal{F}$ is $-2$. Hence at least one of these fixed points is strictly repelling. Suppose for example that the point $(0 : -1 : 1)$ is repelling within the line $x = 0$. Then the intersection of the basin $B$ with this line consists only of countably many iterated preimages of $(0 : -1 : 1)$. Therefore there are points $(0 : y : z)$ arbitrarily close to $(0 : -1 : 1)$ which are not in this basin. Since every point of $J$ can be approximated by iterated preimages of $(0 : -1 : 1)$, it can also be approximated by iterated preimages of such points $(0 : y : z)$, as required.

On the other hand, some of these fixed points on $\mathcal{F}$ may be attracting in the transverse direction. For example, if $|3(c - b) - 2| < 1$ then each of the three fixed points where $\mathcal{F}$ intersects the line $x = 0$ is a saddle, repelling along the Fermat curve, but attracting along this line, which intersects it transversally. The **stable manifold** for such a saddle point can be identified with its immediate attracting.
Fig. 2: Graph of the transverse exponents along the real and complex Fermat curves as functions of the middle parameter $b$ for the “two-thirds family” of Definition 4.6 with Desboves parameters $(b - \frac{2}{3}, b, b + \frac{2}{3})$. The lower graph represents the real case, with a transverse exponent which is strictly smaller (more attracting). In both cases the function is even, with a sharp minimum at $b = \pm \frac{1}{9}$. The box encloses the region $-1 \leq b \leq 1$ with $-2.1 \leq \text{Lyap}_F \leq 1$.

basin within the line $x = 0$. It is not hard to check that this stable manifold is contained in the Julia set. Hence its iterated preimages must be dense in the Julia set.

The attraction within this stable manifold will be particularly strong if $c - b = \frac{2}{3}$, so that the transverse derivative $3(c - b) - 2$ is zero, or in other words so that the associated fixed point is transversally superattracting. Similarly, the transverse derivative at the three points where $y = 0$ (or respectively $z = 0$) is zero if and only if $a - c = \frac{2}{3}$ (or respectively $b - a = \frac{2}{3}$).

**Definition 4.6. The Two-Thirds Family.** We will say that $f$ belongs to the **two-thirds family** if two of the three differences $b - a$, $c - b$ and $a - c$ are equal to $\frac{2}{3}$, or equivalently if two out of three of the fixed points on the Fermat curve are transversally superattracting. Since the average of the three values of the transverse derivative is always $-2$, if two out of three values are zero then it follows that the remaining one is $-6$ (rather strongly repelling). To fix our ideas, let us suppose that

$$(a, b, c) = (b - \frac{2}{3}, b, b + \frac{2}{3})$$

so that the transverse derivative is zero when $x = 0$ or $z = 0$. The associated transverse Lyapunov exponent, plotted as a function of $b$, is shown in Fig. 2. In the real case, this transverse exponent is negative (that is attracting) if and only if $|b| < 0.901 \cdots$, while in the complex case is is negative if and only if $b < 0.274 \cdots$. See Part 2 of this paper for such computations.

**Remark 4.7. Symmetries.** We conclude this section with some more technical remarks. If we permute the three parameters $(a, b, c)$ cyclically, then clearly we obtain a new map $f_{b,c,a}$ which is holomorphically conjugate to $f_{a,b,c}$. We can generalize this construction very slightly by allowing odd permutations also, but changing signs. If $S_3$ is the symmetric group consisting of all permutations
coordinates in each of the four stacked graphs represent respectively x-orbit for the associated complex map. Here each orbit point (x = 0) shows up as a blue circle, since orbits in the invariant line and subsequent figures use various modifications of this scheme. As an example, in Fig. 3 the red to blue according as their orbits converge more rapidly or more slowly towards this Fermat curve, sometimes refer to the coordinate point (0 : 1 : 0) near the top of the picture as the z-axis, pointing almost vertically, are close to the plane of the paper, while the z-axis points out of the paper. (Because of this choice of orientation, we will sometimes refer to the coordinate point (0 : 1 : 0) near the top of the picture as the north pole.) The Fermat curve x^3 + y^3 + z^3 = 0 is traced out in white. In Figs. and other points are colored from red to blue according as their orbits converge more rapidly or more slowly towards this Fermat curve, and subsequent figures use various modifications of this scheme. As an example, in Fig. 3 the equator y = 0 shows up as a blue circle, since orbits in the invariant line y = 0 cannot converge to F, hence orbits near this line cannot converge rapidly towards F.

The graphs to the right of Figs. illustrate some more or less typical randomly chosen orbit for the associated complex map. Here each orbit point (x : y : z) has been normalized so that |x|^2 + |y|^2 + |z|^2 = 1. The horizontal coordinate measures the number of iterations, while the vertical coordinates in each of the four stacked graphs represent respectively |x|^2, |y|^2, |z|^2, and |Φ(x, y, z)|.

Remark 4.8. A Closely Related Map. It is sometimes convenient to eliminate these last symmetries by passing to the quotient space P^2/G which is isomorphic to P^2 itself, but with coordinates (x^3 : y^3 : z^3). If we introduce variables ξ = x^3, η = y^3, and ζ = z^3, and set φ = ξ + η + ζ, then the map (x : y : z) → (ξ : η : ζ) transforms the Fermat curve F to a line φ = 0. Under this transformation, the Desboves map for which is isomorphic to Z/3 × Z/3 of symmetries of the projective plane. In fact f ◦ g = g ◦ f for each g in the group G consisting of all automorphisms

\[ g(x : y : z) = (αx : βy : z) \quad \text{with} \quad α^3 = β^3 = 1. \] (12)

Note on Pictorial Conventions. Each of the color pictures which follow shows the real projective plane, represented as a unit 2-sphere with antipodal points identified, oriented as in Fig. 1. Thus the x-axis, pointing towards the right, and the y-axis, pointing almost vertically, are close to the plane of the paper, while the z-axis points out of the paper. (Because of this choice of orientation, we will sometimes refer to the coordinate point (0 : 1 : 0) near the top of the picture as the north pole.) The Fermat curve x^3 + y^3 + z^3 = 0 is traced out in white. In Figs. and other points are colored from red to blue according as their orbits converge more rapidly or more slowly towards this Fermat curve, and subsequent figures use various modifications of this scheme. As an example, in Fig. 3 the equator y = 0 shows up as a blue circle, since orbits in the invariant line y = 0 cannot converge to F, hence orbits near this line cannot converge rapidly towards F.

5 Empirical Examples.

This section will provide empirical discussions of six examples from the Desboves family of degree four maps, as described in plus two examples of lower degree maps. Four of the six examples from the Desboves family, belong to the “two-thirds” subfamily of Definition 4.6.
Fig. 3: (Example 5.2) On the left: dynamics on the real projective plane for the Desboves map in the two-thirds family with parameters \((a, b, c) = (-\frac{5}{9}, \frac{1}{9}, \frac{7}{9})\). The sphere is oriented as in Fig. 1. On the right: plot of \(|x|^2, |y|^2, |z|^2\) and \(|\Phi|\) as functions of the number of iterations for a typical randomly chosen complex orbit. Here each orbit point \((x : y : z)\) has been normalized so that \(|x|^2 + |y|^2 + |z|^2 = 1\). In this run, it took 23 iterations to come close enough to the Fermat curve so that \(|\Phi|\) appears to be zero on the graph.

Fig. 4: (See Example 5.3) For the map with Desboves parameters \((\frac{1}{3}, 0, -\frac{1}{3})\), the Fermat curve again seems to attract all or nearly all orbits in both the real and complex cases.
Fig. 5: (Example 5.4) Dynamics for the parameters \((-\frac{1}{5}, \frac{7}{15}, \frac{11}{15})\). Left: In the real case there are two attractors. The basin of the Fermat curve is colored as in Figs. 3, 4. However, the two small white circles also form an attractor. The corresponding basin is shown in dark grey. Right: A typical randomly chosen orbit for the complex map. This orbit often comes very close to the Fermat curve during the first 4000 iterations, but then seems to converge to a cycle of two Herman rings.

Fig. 6: (Example 5.5) Plots for the map with Desboves parameters \((-1.4, -0.8, 1.4)\). Here the coloring is as in the previous figures except that it describes convergence to the “equator” \(y = 0\), rather than to the invariant Fermat curve. For this map, the “north pole” \((0:1:0)\) also attracts many orbits.
Example 5.1. The Fermat Curve as a Global Attractor? If we choose Desboves parameters 
\((b - \frac{2}{3}, b, b + \frac{2}{3})\) with \(|b|\) small, then the transverse Lyapunov exponent is negative in both the real 
and complex cases. Numerical computation suggests that nearly all orbits actually converge to the 
Fermat curve. (Perhaps even all but a set of measure zero?) As an example, consider the case 
\((a, b, c) = (-\frac{2}{3}, 0, \frac{2}{3})\). Using the Gnu multiple precision arithmetic package, and starting with several 
thousand randomly chosen points on the real or complex projective plane, one can check that all orbits 
land on the curve, to the specified accuracy, within a few hundred iterations. Of course, even if we 
could work with infinite precision arithmetic, such a computation could not prove that a given orbit 
converges to the curve, and also could not rule out the possibility of other attractors with extremely 
small basins. In fact it seems possible that periodic attractors with high period and small basin exist 
for a dense open set of parameter values. This case \(b = 0\) is rather special in one way, since the map 
\(f_{-2/3,0,2/3}\) has points of indeterminacy; namely those points where \((x^3 : y^3 : z^3)\) is equal to either 
\((1 : 7 : 1)\) or \((0 : 1 : 0)\). However, the behavior for small non-zero values of \(b\) seems qualitatively similar.

Example 5.2. An Even Stronger Attractor. The case \(b = \pm \frac{1}{3}\) yields a even more strongly 
attracting Fermat curve, as illustrated in Fig. 8. The transverse derivative has a simple zero at the 
point (-1, 1, 0)/\(\sqrt{2}\) to the upper left of the figure, and a double zero at the point (0, -1, 1)/\(\sqrt{2}\) near the 
bottom. A numerical search suggests that this is the most attracting example within the real or 
complex Desboves family, in the sense that the transverse exponent takes its most negative value of 
\(-2.0404\ldots\) for the real map or \(-0.6801\ldots\) for the complex map. Certainly these are the extreme 
values for real parameters within the two-thirds family, as graphed in Fig. 2.

Example 5.3. Another Global Attractor? If we take Desboves coordinates \((\frac{1}{3}, 0, -\frac{1}{3})\), then 
again the Fermat curve seems to attract nearly all orbits. Compare Fig. 10. Here the transverse 
derivative has a double zero at the fixed point \((-1 : 0 : 1)\) in the middle of the large red region. It is 
a curious fact that the transverse exponents in this case are precisely the same as those for Example 
81, namely \(-1.456\ldots\) for the real map, or \(-.549\ldots\) for the complex map.

Example 5.4. A Cycle of Herman Rings? Now suppose that we choose Desboves parameters 
in the two-thirds family, with \((a, b, c)\) equal to \((-\frac{1}{3}, \frac{7}{15}, \frac{17}{15})\). Here the transverse exponent is \(-.509\ldots\) 
for the real map, but \(+.402\ldots\) for the complex map. Thus we can expect the Fermat curve to be an 
attractor in the real case, but not in the complex case. The left half of Fig. 11 illustrates the dynamics 
in the real case. Numerical computation suggests that some 83% of the orbits converge to the Fermat 
curve, while the remaining 17% converge to a pair of small circle. The attractive basin for this pair 
of circles is conjecturally a dense open subset of \(\mathbb{P}^2(\mathbb{R})\). The map \(f = f_{a,b,c}\) carries each of these 
circles to the other, reversing orientation, while \(f \circ f\) carries each circle to itself with rotation number 
\(\pm 0.18587\ldots\). Of course such a phenomenon can be expected to be highly sensitive to small changes in 
the parameters—We cannot really distinguish between a rotation circle with irrational rotation number 
and one with a rational rotation number which has very large denominator (although the later would 
necessarily contain a periodic orbit).

In the complex case, the Fermat curve is no longer an attractor. In fact, almost all orbits seem to 
eventually land near this cycle of circles and then to behave just like an orbit on a pair of nearby circles 
with the same rotation number. This suggests that most orbits converge to a cycle of two Herman rings 
in \(\mathbb{P}^2(\mathbb{C}),\) with the pair of real circles as their central circles. (For a more detailed discussion of Herman 
rings in \(\mathbb{P}^2(\mathbb{C}),\) see [3]) Again we must be cautious, since such a phenomenon must be highly sensitive 
to perturbations; but the empirical evidence certainly suggests the existence of a cycle of two Fatou
components which could only be the immediate basins for attracting Herman rings.\footnote{The convergence is very slow, and there may be other much more chaotic attractors.} These attracting circles persist under small perturbation of the parameters. (Compare Theorem 8.9.) A plot of the rotation number for these circles as a function of the parameter $c$, keeping $a$ and $b$ fixed, is shown in Fig. 7. It seems empirically that Herman rings also persist under perturbation, but we have been unable to justify this statement theoretically.

Example 5.5. The Line $z = 0$ as a Measure Theoretic Attractor? (Compare Fig. 6.) For the parameter values $(a, b, c) = (-1.4, -0.8, 1.4)$, the Lyapunov exponent turns out to be strictly positive, equal to $0.247 \cdots$ in the real case, or to $0.352 \cdots$ in the complex case. The invariant Fermat curve does not seem to play any significant dynamical role in this case. On the other hand, the equator $y = 0$ seems to be at least a measure-theoretic attractor; and there is also an attracting fixed point at the north pole $(0 : 1 : 0)$. In fact many randomly chosen real or complex orbits converge to the north pole $(0 : 1 : 0)$, but even more seem to converge to the equator.

Example 5.6. A Composite “Almost” Attractor. For the real or complex map with Desboves parameters $(\frac{1}{3}, 1, \frac{5}{3})$ as illustrated in Fig. 8, typical orbits seem to spend a great deal of time quite

\footnote{For the description of possible Fatou components in $\mathbb{P}^2$, compare [FS1], [U1].}
Fig. 8:  (Example 5.6) On the left: Corresponding figure for the real Desboves map with parameters \((\frac{1}{3}, 1, \frac{5}{3})\), again describing convergence to (or at least coming close to) the Fermat curve. On the right: One randomly chosen orbit for the complex map through 10000 iterations.

Fig. 9:  (Example 5.5) Plots for the “elementary map” with parameters \((a, b, c) = (-1, \frac{1}{3}, 1)\). In this case, every great circle through the north pole \((0 : 1 : 0)\) maps to a great circle through the north pole. There are three attractors: the Fermat curve \(F\), the equator \(\{y = 0\}\), and the north pole, each marked in white. The corresponding attracting basins are colored red, blue, and grey respectively. (However, the closely intermingled blue and red yield a purple effect.) The graphs on the right show an orbit which nearly converges to \(\{y = 0\}\) but then escapes towards \(F\).
Fig. 10: (Example 7.1) The Cassini quartic with parameter $k = \frac{1}{8}$, shown in black, consists of an outer circle $C_0$ with two self-intersections and a much smaller inner circle $C_1$. Here the warmer colors describe convergence towards $C_0$ for the rational map $f_1$ with parameter $a = 1$. The blue region is the basin of a superattracting fixed point at $(0 : 0 : 1)$, while the grey region is the basin of another attracting fixed point directly above it at $(0 : 1 : 2)$.

Fig. 11: Corresponding picture for the same Cassini curve with $k = \frac{1}{8}$, but using the map with parameter $a = \frac{2}{5}$. 
close to the Fermat curve $F$, even though the transverse exponent is strictly positive, equal to 0.081 · · · in the real case or to 1.032 · · · in the complex case. This curve is not an attractor by itself, since nearby orbits eventually get kicked away from it. However, the union

$$A = \{x = 0\} \cup \{y = 0\} \cup \{z = 0\} \cup F,$$

or in other words the variety $xyz \Phi(x, y, z) = 0$, does seem to behave like an attractor, at least in a statistical sense. (Compare [GI].) Typical orbits seem to spend most of the time extremely close to this variety. However, they do not stay in any one of its four irreducible components, but sometimes jump from one component to another. Furthermore, it seems likely that typical orbits will escape completely from a neighborhood of this variety, very infrequently but infinitely often.

Here is a more detailed description, as illustrated in Fig. 12. To fix ideas, we will refer to the real case; but the complex case is not essentially different. A randomly chosen orbit seems to spend most of the time either wandering chaotically very close to the Fermat curve or else almost stationary, very close to one of the four saddle fixed points (the black dots in Fig. 12). However, such an orbit does not seem to stay close to any one of the four components of this variety forever. For example, it is likely to escape from the neighborhood of the Fermat curve $F$ when it comes very close to the strongly repelling point $F \cap \{y = 0\}$ which is circled in Fig. 12. It will then shadow the coordinate line $y = 0$, jumping quickly to a small neighborhood of the saddle point $x = y = 0$, and then slowly coming closer to this point for thousands of iterates. Again it must eventually escape, now shadowing the line $x = 0$ and jumping quickly either towards the saddle point $F \cap \{x = 0\}$ or towards the saddle point $x = z = 0$. In either case it again spends a long time approaching this saddle point, but then escapes. In the first case, it is now very close to the Fermat curve and shadows it for a long time with a highly chaotic orbit before starting the cycle again. In the second case where it escapes near the saddle point $x = z = 0$, it then shadows the line $z = 0$ as it quickly converges towards the saddle point $F \cap \{z = 0\}$, where it again remains for a long time before repeating the cycle.
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Fig. 13: A plot of 200 iterations with a random start for the degree three map of Example 5.8, taking parameters $(a, b, c) = (0, \gamma, -1)/2$.

Remark 5.7. The Concept of Attractor. Such examples have led authors such as [GI] and [AAN] to suggest modified definitions of attractor, emphasizing not the omega-limit set of a typical orbit, but rather its asymptotic probability distribution. To illustrate the effect of such a change, think of a dynamical system in the plane in which orbits spiral out towards a limit cycle $\Gamma$ which consists of a homoclinic loop, beginning and ending at a fixed point $p$. Then the unique “measure theoretic attracting set” for the region inside the loop is the entire loop $\Gamma$. No orbit starting inside actually converges to the point $p$. However, every orbit starting inside the loop spends most of its time apparently converging to $p$, with a statistically insignificant (but infinite) collection of exceptional times. Thus, from the point of view of Gorodetski and Ilyashenko or of Ashwin, Aston and Nicol, the “attractor” is the single point $p$.

Example 5.8. A Family of Degree Three Maps. In the case of a map of degree three (or indeed for any degree which is not a perfect square), the multiplier on an invariant elliptic curve cannot be a real number. Hence we cannot describe both the map and the invariant curve by equations with real coefficients—we can only consider the complex case.

Here is one explicit family of degree three maps which send the Fermat curve $\mathcal{F}$ into itself. As in §4, we start with a rather degenerate self-map of $\mathbb{P}^2$. Let

$$H_0(x, y, z) = (kxyz, y^3 - \gamma z^3, z^3 - \gamma y^3)$$

where $\gamma$ is the cube root of unity $(-1 + i\sqrt{3})/2$ and where $k^3 = 3(\gamma^2 - \gamma)$. (For example $k = \gamma^2 - 1$ or $k = i\sqrt{3}$.) Then the associated map

$$h_0(x : y : z) = (kxyz : y^3 - \gamma z^3 : z^3 - \gamma y^3)$$

of projective space has a first integral $\Phi/\Psi$, where $\Phi(x, y, z) = x^3 + y^3 + z^3$ and $\Psi(x, y, z) = x^3$. In fact
a brief computation shows that
\[ \Phi(H_0(x, y, z))/\Phi(x, y, z) = \Psi(H_0(x, y, z))/\Psi(x, y, z) = 3y^3z^3, \]
and it follows immediately that the rational function \( \Phi/\Psi \) is invariant under \( h_0 \). In particular, the Fermat curve, defined by \( \Phi = 0 \), is \( h_0 \)-invariant. (However, in contrast to the Desboves case of \( \S 4 \), the various elliptic curves \( \Phi/\Psi = \text{constant} \in \mathbb{C}\setminus\{1\} \) are all mutually isomorphic. A similar example will be described in Remark \( \S 6.8 \)) This map \( h_0 \) has just one point of indeterminacy, namely \( (1 : 0 : 0) \), which is not on \( F \).

Like all maps of \( \mathbb{P}^2 \) with first integral, \( h_0 \) is not very interesting as a dynamical system, but it does embed in a family of more interesting maps. Consider the 3-parameter family of homogeneous polynomials
\[ H = H_{a,b,c} = H_0 + (a, b, c) \Phi. \]
Each of the associated maps \( h_{a,b,c} \) of the projective plane carries the Fermat curve \( F \) to itself with degree three and multiplier \( \gamma k \). There is only one fixed point of \( h_{a,b,c} \) on \( F \), namely \( (0 : -1 : 1) \).

First consider the 1-parameter subfamily of maps satisfying the conditions that \( a = b + \gamma c = 0 \), with \( x = 0 \) as invariant line. (The use of these special parameters simplifies the computation of the transverse Lyapunov exponent.) When \( b = \gamma/2 \), the transverse Lyapunov exponent takes its most negative value of \(-1.647918\). Thus \( F \) appears to be more strongly attracting under this map than under any of the complex Desboves maps, where the most negative transverse exponent was \(-0.6801\cdots\). (See Example 5.2. Such computations will be explained in Part 2 of this paper.) In Fig. 13 we show the extraordinary attracting properties of the Fermat curve for this map. Most randomly chosen points seemed to hit the Fermat curve, up to the resolution of the graph, after only 6 or so iterations. (Compare with the right hand sides of Figs.: 3, 4 and 9.)

It is also interesting to consider the subfamily consisting of maps \( h_{a,0,0} \) with \( b = c = 0 \). These are elementary maps , as described in Example 6.1. For this particular elementary family, it appears that the transverse exponent is always non-negative, so that the Fermat curve is never an attractor.

**Example 5.9. The Degree Two Case.** According to \( \text{[BD, Proposition 6.6]} \), up to holomorphic conjugacy, there are exactly 20 distinct examples of holomorphic self-maps of \( \mathbb{P}^2(\mathbb{C}) \) of algebraic degree two with an invariant smooth elliptic curve. See Example 6.9 of their paper for a detailed study of one of these degree two maps. This example, with multiplier equal to \( i \sqrt{2} \), has five attracting cycles, with common basin boundary equal to the Julia set. Four of these are attracting fixed points, and the fifth is an attracting period 2 orbit. Empirically, randomly chosen orbits for this example always seem to converge to one of these five cycles.

### 6 Intermingled Basins

**Example 6.1. Elementary Maps.** Finally we come to examples where we can provide complete proofs. Following \( \text{[BD, p. 16]} \), a rational map of \( \mathbb{P}^2 \) is called elementary, with center \( p_0 \), if every line through \( p_0 \) maps to a line through \( p_0 \). Elementary maps are easier to analyze than more general rational maps since we can separate the variables to simplify the discussion.

In particular, consider a Desboves map \( f = f_{a,b,c} \) as in formula \( \text{7} \) of \( \text{[4]} \) where the parameters \( a, b, c \) satisfy \( a = -1 \) and \( c = 1 \). Then the image \( f(x : y : z) = (x' : y' : z') \) satisfies
\[ x' = x(-x^3 - 2z^3) \quad \text{and} \quad z' = z(2x^3 + z^3). \]
Elliptic Curves as Attractors in $\mathbb{P}^2$, Part I

Fig. 14: On the left: Plot of the transverse Lyapunov exponent along the Fermat curve as a function of the parameter $b$ for the elementary family of Example 6.1, with Desboves parameters $(-1, b, 1)$. On the right: Corresponding plot for the transverse exponent along the line $y = 0$. In both cases, the graph for the complex map lies above the graph for the real map.

It follows that each line $(x : z) = \text{constant}$ through the coordinate point $p_0 = (0 : 1 : 0)$ maps to another line $(x' : z') = \text{constant}'$ through $p_0$. If we set $X = x/z$ and $X' = x'/z'$, then the correspondence

$$\hat{f} : X \mapsto X' = -X \frac{X^3 + 2}{2X^3 + 1}$$

(14)

does not depend on the choice of parameter. This rational map (14) is described as a Lattès map, since it is the image of a rigid map on the torus $\mathcal{F} \cong \mathbb{C}/\Omega$ under the semiconjugacy $(x : y : z) \mapsto (x : z)$ of degree three. (In fact $\hat{f}$ is conformally conjugate to the Lattès map described in Remark 4.8.) It has an ergodic invariant measure which is smooth except at its critical values, the cube roots of $-1$. Over the real numbers, $\hat{f}$ is a covering map from the circle $\mathbb{P}^1(\mathbb{R})$ to itself with topological degree $-2$.

Over either the real or complex numbers, if we think of $\mathbb{P}^2 \setminus \{p_0\}$ as a (real or complex) line-bundle over the projective line $\mathbb{P}^1$ with projection $\pi : (x : y : z) \mapsto (x : z)$, then we have the commutative diagram

$$\begin{array}{ccc}
\mathbb{P}^2 \setminus \{p_0\} & \xrightarrow{f} & \mathbb{P}^2 \setminus \{p_0\} \\
\pi \downarrow & & \pi \downarrow \\
\mathbb{P}^1 & \xrightarrow{\hat{f}} & \mathbb{P}^1
\end{array}$$

(15)

where $f$ carries each fiber into a fiber by a polynomial map, with coefficients which vary with the fiber. As an example, for the two invariant fibers $x = 0$ and $z = 0$ we get the maps

$$(0 : y : 1) \mapsto (0 : by^4 + (1 + b)y : 1) \quad \text{and} \quad (-1 : y : 0) \mapsto (-1 : by^4 + (1 - b)y : 0)$$

respectively. If we exclude the degenerate case $b = 0$ (compare Remark 6.8), then these polynomial maps all have degree four. Furthermore, the center point $p_0 = (0 : 1 : 0)$ is superattracting, and serves as the point at infinity for each one. In the real case, these polynomial maps are all unimodal, while in the complex case they all have $120^\circ$ rotational symmetry.
Since the rational map $\hat{f}$ of the base space has no attracting cycles, it follows that an elementary map with invariant elliptic curve can have no attracting cycles other than its center point.

In this special case of an elementary map, we can give a relatively easy proof that a negative transverse exponent for any invariant elliptic curve implies that this curve is a measure-theoretic attractor. (The most attracting Desboves example, with $b = \frac{1}{3}$, is illustrated in Fig. 9.) However, in the case of an elementary Desboves map $f$ we get a surprising bonus. The invariant line $\{y = 0\}$ is also carried into itself by the Lattès map of Eq. (14). Hence it also has a canonical ergodic invariant measure, and a well defined transverse Lyapunov exponent. According to Fig. 14, for real values of $b$ both of these transverse exponents are strictly negative provided that $|b|$ is fairly small and non-zero.

**THEOREM 6.2. Basins of Positive Measure.** Let $f$ be a real or complex elementary map with an invariant elliptic curve $C$. If the transverse Lyapunov exponent $\text{Lyap}_C$ is strictly negative, then the attracting basin $B(C)$, consisting of points whose orbit converges to $C$, has strictly positive measure. In fact any neighborhood of a point of $C$ intersects $B(C)$ in a set of positive measure. Similarly, if such an $f$ has an invariant line $L$ with strictly negative transverse exponent, then the attracting basin for this line has positive measure, and intersects any neighborhood of a point of this line in a set of positive measure.

In the complex case we can give a much more precise picture. As usual, define the Fatou set to be the largest open set on which the sequence of iterates of $f$ forms a normal family, and define the Julia set $J$ to be its complement in $\mathbb{P}^2(\mathbb{C})$. If $p$ is any point of an invariant elliptic curve, then according to Bonifant and Dabija in [BD, Theorem 5.4 and Proposition 6.16] the iterated preimages of $p$ are everywhere dense in the Julia set; and furthermore:

**PROPOSITION 6.3. The Fatou Set is a Dense Open Basin.** If $f$ is a complex elementary map with smooth invariant elliptic curve, and if the center $p_0$ is not a point of indeterminacy, then $p_0$ is a superattracting fixed point whose basin coincides with the Fatou set. This basin is connected and everywhere dense in $\mathbb{P}^2$. Furthermore, if $U$ is a small neighborhood of a point of the Julia set, then the union of the forward images of $U$ is the entire space $\mathbb{P}^2 \setminus \{p_0\}$.

In particular, it follows that the attracting basin for the elliptic curve has no interior points. Similarly, if there is an invariant line $L$ disjoint from the center $p_0$, then the attracting basin of $L$ cannot have any interior point. It also follows that $f$ is topologically transitive on the Julia set. This means that the orbit of a “generic” point of the Julia set $J$ is everywhere dense in $J$. Such a generic point of $J$ cannot belong to any of the attracting basins $B(C)$, $B(L)$, or $B(p_0)$.

**COROLLARY 6.4. Intermingled Basins.** If a complex elementary map has both an invariant line $L$ which does not pass through its center, and an invariant elliptic curve $C$, then the two topological closures $\overline{B(C)}$ and $\overline{B(L)}$ are both precisely equal to the Julia set. Furthermore, if the transverse Lyapunov exponent for $C$ (or for $L$) is negative, then every neighborhood $U$ of a point of the Julia set intersects $B(C)$ (or respectively $B(L)$) in a set of positive Lebesgue measure.

**Remark 6.5. Three Basins.** In the case where the transverse exponents $\text{Lyap}_C(f)$ and $\text{Lyap}_L(f)$ are both negative, it follows that the basins for these two attractors are intimately intermingled. For the real Desboves map illustrated in Fig. 9 a very rough estimate suggests that about
66% of the points in \( \mathbb{P}^2 \) are attracted to the center \((0 : 1 : 0)\), about 17% to the line \( \{ y = 0 \} \), and about 17% to the Fermat curve. For the associated complex mapping, the figures are 81%, 13%, and 6%. (However, the computation is highly sensitive, and these estimates may well be quite inaccurate.) It may be conjectured that every point outside of a set of measure zero lies in the union of these three attracting basins.

**Remark 6.6. Terminology.** Such exotic behavior has been studied extensively, particularly in the applied dynamics literature. The term “riddled basin” was introduced in [AKY] to indicate an attracting basin whose complement intersects every disk in a set of positive measure. They define two basins to be **intermingled** if every disk which intersects one basin in a set of positive measure also intersects the other basin in a set of positive measure. For a particularly clear example, see [Kn]. Such examples of intermingled basins seem to be known only in cases where the attractors themselves are quite smooth—We don’t know whether there can be two fractal attractors whose basins have the same closure.

**Proof of Theorem 6.2.** Without loss of generality, we may assume that the center of the real or complex elementary map is \((0 : 1 : 0)\). Furthermore, an invariant line with negative transverse exponent certainly cannot pass through this center; so if there is such a line \( \mathcal{L} \), we may assume that it is the line \( \{ y = 0 \} \), as in Fig. 9. (Since we assume that there is an invariant elliptic curve \( \mathcal{C} \), it follows that any invariant line not passing through the center is mapped to itself by a Lattès map, with an absolutely continuous invariant measure so that the transverse exponent is well defined.) Each fiber \((x : z) = \text{constant} \) of the fibration \( \pi(x : y : z) = (x : z) \) has a canonical flat metric

\[
\frac{|dy|}{\sqrt{|dx|^2 + |dz|^2}},
\]

which gives rise to a norm \( \| \vec{v} \|_t \) for vectors tangent to the fiber. Let

\[
\| f'(p) \| = \| f' \vec{v} \|_t / \| \vec{v} \|_t,
\]

be the norm of the partial derivative along the fiber; where \( \vec{v} \) can be any non-zero vector tangent to the fiber at \( p \). (Note that any vector tangent to its fiber must map to a vector tangent to the image fiber.) This norm is well defined, depending only on the base point \( p \) of \( \vec{v} \). At points of the curve \( \mathcal{C} \), we want to compare \( \| \vec{v} \|_t \) with the semi-definite norm \( \| \vec{v} \|_h \) which is obtained by first projecting \( \vec{v} \) to the quotient vector space \( T(\mathbb{P}^2, p)/T(\mathcal{C}, p) \) and then using a positive definite norm in this quotient space. Note that most fibers intersects the degree three curve \( \mathcal{C} \) transversally in three distinct points. There are only a finite number of exceptional fibers which intersect tangentially. Therefore the ratio \( \| \vec{v} \|_h / \| \vec{v} \|_t \geq 0 \) is a continuous function on \( \mathcal{C} \) which vanishes only at these points of tangency. Furthermore, the logarithm \( \ell(p) \) of this ratio has only logarithmic singularities, and hence is an integrable function on \( \mathcal{C} \). Since the measure \( d\lambda \) is \( f \)-invariant, it follows that the difference

\[
\int_{\mathcal{C}} \log \| f'_h \| d\lambda - \int_{\mathcal{C}} \log \| f'_t \| d\lambda = \int_{\mathcal{C}} \ell \circ f d\lambda - \int_{\mathcal{C}} \ell d\lambda
\]

is zero. In other words, the average value \( \int_{\mathcal{C}} \log \| f'_t \| d\lambda \) coincides with the transverse exponent \( \text{Lyap}_f \) of \( \mathcal{C} \).

For any \( p \) and \( q \) belonging to the same fiber, let \( \delta(q, p) \geq 0 \) be the distance of \( q \) from \( p \), using the flat metric of Eq. (16) on this fiber. Then

\[
\delta(f(q), f(p)) = \| f'_t(p) \| \delta(q, p) + o(\delta(q, p))
\]
as \( \delta(q, p) \) tends to 0. This estimate holds uniformly throughout a neighborhood of \( C \). Hence, given any \( \epsilon > 0 \), we can choose \( \delta_0 \) so that
\[
\delta(f(q), f(p)) \leq (\|f_t^t(p)\| + \epsilon) \delta(q, p)
\]  
(17)
when \( p \in C \) and \( \delta(q, p) < \delta_0 \) with \( \pi(p) = \pi(q) \).

Choose \( \epsilon \) small enough so that
\[
\int_C \log (\|f_t^t(p)\| + \epsilon) 
\]  
(18)
converges to the integral of Eq. (17) for almost all \( p_0 \in C \). In particular, for almost all \( p_0 \) it follows that the number
\[
\log (\|f_t^t(p_0)\| + \epsilon) + \log (\|f_t^t(p_1)\| + \epsilon) + \cdots + \log (\|f_t^t(p_{n-1})\| + \epsilon)
\]
\[
= \log \left( (\|f_t^t(p_0)\| + \epsilon) \cdots (\|f_t^t(p_{n-1})\| + \epsilon) \right)
\]
is negative for large \( n \). Hence the maximum
\[
M(p_0) = \max_{n \geq 0} \left( (\|f_t^t(p_0)\| + \epsilon) (\|f_t^t(p_1)\| + \epsilon) \cdots (\|f_t^t(p_{n-1})\| + \epsilon) \right) \geq 1
\]
is well defined, measurable, and finite almost everywhere. If \( \delta(q, p_0) \leq \delta_0/M(p_0) \), then it follows from the inequality of (17) that \( \delta(f^n(q), f^n(p_0)) \leq \delta_0 \) for all \( n \), and also that this distance converges to zero as \( n \to \infty \). Now let \( S \) be the set of positive measure consisting of all \( q \) with \( \delta(q, p) \leq \delta_0/M(p) \) for some \( p \in C \) with \( \pi(p) = \pi(q) \). (Here we take \( \delta_0/\infty \) to be 0.) Then for all \( q \in S \) it follows that the orbit of \( q \) converges to \( C \). Evidently, \( S \) intersects every neighborhood of a point of \( C \) in a set of positive measure. The proof for the basin of the line \( y = 0 \) is completely analogous.

**Remark 6.7. What about Positive Transverse Exponent?** Conversely, it seems natural to conjecture that the basin of \( C \) has measure zero whenever the transverse Lyapunov exponent is positive. However, this cannot be proved simply by reversing the inequalities in the argument above. The problem is that \( \log (\|f_t^t\| - \epsilon) \) is not a meaningful approximation to \( \log \|f_t^t\| \), since \( \|f_t^t\| \) must sometimes be smaller than any given \( \epsilon \). In fact, almost every orbit near \( C \) must pass arbitrarily close to the critical locus of \( f \). But whenever \( p \) is very close to the critical locus, there is a real possibility that \( f(p) \) will be much closer to \( C \) than would have been predicted from the differential inequality. We don’t know whether this effect could be strong enough to make \( C \) a measure theoretic attractor even in some cases where the transverse Lyapunov exponent is positive. (Compare Remark 6.4.)

**Proof of Corollary 6.4** It follows immediately from Proposition 6.4 that the basins of \( C \) and \( \mathcal{L} \) are contained in the Julia set. On the other hand, if \( p \in C \cap \mathcal{L} \) then the iterated preimages of \( p \) are contained in both basins, and are dense in \( J \). Therefore, the closure of either basin is equal to \( J \).
The first half of this section will provide explicit examples of everywhere defined rational maps of \( \mathbb{P}^2 \). As in [BD, §8.6], consider the Cassini quartic curve \( C \) with homogeneous equation \( \Phi(x, y, z) = 0 \), where \(^4\)
\[
\Phi(x, y, z) = \Phi_k(x, y, z) = x^2y^2 - (x^2 + y^2)z^2 + kz^4
\]
depends on a single parameter \( k \neq 0, 1 \). Over the complex numbers, this is an elliptic curve with nodes at the two points \((1 : 0 : 0)\) and \((0 : 1 : 0)\). That is, the uniformizing map \( C/\Omega \to C \subset \mathbb{P}^2(\mathbb{C}) \) has transverse self-intersections at these two points. Define a one-parameter family of homogeneous polynomial maps from \( C^3 \) to itself by the formula \( F(x, y, z) = F_a(x, y, z) = (X, Y, Z) \), where
\[
X = -2xy(x^2 + y^2 - 2kz^2), \quad Y = y^4 - x^4, \quad Z = -a \Phi(x, y, z) + 2xy(x^2 - y^2).
\]
According to [BD], the curve \( C \) is invariant under the induced rational map \( f = f_a : \mathbb{P}^2 \to \mathbb{P}^2 \). It is not hard to check that the singular point \((0 : 1 : 0)\) (the “north pole” in Figs. 10 and 11) is a saddle fixed point of \( f_a \), with eigenvalues \(-2\) and \(0\), and that the point \((0 : 0 : 1)\) (near the center of these figures) is a superattracting fixed point whenever \( a \neq 0 \).

Remark 6.8. The Special Case \( b = 0 \). The above discussion of elementary Desboves maps \( f = f_{-1, b, 1} \) always assumed that the parameter \( b \) is non-zero. For the case \( b = 0 \), we have a much simpler situation. The center \((0 : 1 : 0)\) then becomes a point of indeterminacy. If we think of each fiber \( V \) as a one-dimensional complex vector space, taking \( V \cap L \) to be its zero vector, then each fiber maps linearly to a fiber. In fact it is not hard to see that \( f \) is well defined as a holomorphic map from the complement \( \mathbb{P}^2 \setminus \{(0 : 1 : 0)\} \) onto itself, and that this complement is “foliated” by \( f \)-invariant copies of the Fermat curve, which intersect only along the locus \( F \cap L \). In particular, the map \( f = f_{-1, 0, 1} \) has a first integral. (Compare Lemma 6.1)

7 Trapped Attractors: Existence and Nonexistence.

The first half of this section will provide explicit examples of everywhere defined rational maps of \( \mathbb{P}^2(\mathbb{R}) \) which have a smoothly immersed real elliptic curve as trapped attractor. The second half will prove that a complex elliptic curve, with or without singular points, can never be a trapped attractor.

Example 7.1. A Real Elliptic Curve as Trapped Attractor. This last example will study the case of a singular elliptic curve. As in [BD, §8.6], consider the Cassini quartic curve \( C \) with homogeneous equation \( \Phi(x, y, z) = 0 \), where \(^4\)
\[
\Phi(x, y, z) = \Phi_k(x, y, z) = x^2y^2 - (x^2 + y^2)z^2 + kz^4
\]
depends on a single parameter \( k \neq 0, 1 \). Over the complex numbers, this is an elliptic curve with nodes at the two points \((1 : 0 : 0)\) and \((0 : 1 : 0)\). That is, the uniformizing map \( C/\Omega \to C \subset \mathbb{P}^2(\mathbb{C}) \) has transverse self-intersections at these two points. Define a one-parameter family of homogeneous polynomial maps from \( C^3 \) to itself by the formula \( F(x, y, z) = F_a(x, y, z) = (X, Y, Z) \), where
\[
X = -2xy(x^2 + y^2 - 2kz^2), \quad Y = y^4 - x^4, \quad Z = -a \Phi(x, y, z) + 2xy(x^2 - y^2).
\]
According to [BD], the curve \( C \) is invariant under the induced rational map \( f = f_a : \mathbb{P}^2 \to \mathbb{P}^2 \). It is not hard to check that the singular point \((0 : 1 : 0)\) (the “north pole” in Figs. 10 and 11) is a saddle fixed point of \( f_a \), with eigenvalues \(-2\) and \(0\), and that the point \((0 : 0 : 1)\) (near the center of these figures) is a superattracting fixed point whenever \( a \neq 0 \).

If the parameters \( k \) and \( a \) are real, then the corresponding real curve \( C_\mathbb{R} = C \cap \mathbb{P}^2(\mathbb{R}) \) is connected when \( k < 0 \), but has two connected components when \( k > 0 \). These maps are illustrated in Figs. 10 and 11 for the case \( k = 1/8 > 0 \), with \( C_\mathbb{R} \) in black. Here the smaller nonsingular component maps to the larger singular component. The two branches of \( C_\mathbb{R} \) through the singular point \((1 : 0 : 0)\) map to one of the two branches through the fixed point \((0 : 1 : 0)\) while both branches through \((0 : 1 : 0)\) map

\(^4\)This expression yields curves which are equivalent, under a complex linear change of coordinates, to quartic curves introduced in 1680 by the French-Italian astronomer Giovanni Domenico Cassini, in connection with planetary orbits.
to the other branch through \((0 : 1 : 0)\). (All four branches lie within a single immersed circle which crosses itself twice within the nonorientable manifold \(\mathbb{P}^2(\mathbb{R})\).) Note the identities

\[
F(-x, -y, z) = F(x, y, z) \quad \text{and} \quad F^{o2}(-y, x, z) = F^{o2}(x, y, z),
\]

which imply that the Julia set of \(f_a\) has \(90^\circ\)-rotational symmetry about the point \((0 : 0 : 1)\).

Let \(C^0_{\mathbb{R}}\) be the connected component of the real curve which contains this singular fixed point, and hence maps onto itself. We will prove the following result.

**THEOREM 7.2. A Trapped Attractor.** If \(0 < |k| < 1/4\), and if \(a\) is sufficiently small, then the curve \(C^0_{\mathbb{R}}\) is a trapped attractor for the map \(f_a\) on the real projective plane.

**Proof.** Let \((X, Y, Z) = F(x, y, z)\). The quotient

\[
\Phi_F(x, y, z) = \Phi(X, Y, Z)/\Phi(x, y, z)
\]

is a polynomial of degree 12 in \(x, y, z\), depending on the parameter \(a\). In general this polynomial seems rather complicated, but in the special case \(a = 0\) computation shows that it takes the simple form

\[
\Phi_F(x, y, z) = 16k x^2 y^2(x^2 - y^2)^4.
\]

(21)

As a convenient measure of the distance of a point of \(\mathbb{P}^2\) from the curve \(\Phi = 0\) we take the ratio

\[
r(x : y : z) = |\Phi(x, y, z)|/(x^2 + y^2)^2,
\]

with \(\Phi\) as in (13). This ratio is finite except at the value \(r(0 : 0 : 1) = +\infty\), and it vanishes only on the Cassini curve. We want to prove an inequality of the form

\[
r(X : Y : Z) \leq \lambda r(x : y : z)
\]

(22)

whenever \(r(x : y : z)\) is sufficiently small, where \(\lambda < 1\) is constant. To do this, we consider the ratio

\[
r_f(x, y, z) = \frac{r(X : Y : Z)}{r(x : y : z)} = \frac{|\Phi(X, Y, Z)|}{|\Phi(x, y, z)|} \frac{(x^2 + y^2)^2}{(X^2 + Y^2)^2}.
\]

In the special case \(a = 0\), using the identity (21) and the inequality

\[
X^2 + Y^2 \geq Y^2 = (y^4 - x^4)^2 = (x^2 + y^2)^2(x^2 - y^2)^2,
\]

(23)

together with \(|2xy| \leq x^2 + y^2\), we see that

\[
\frac{r(X : Y : Z)}{r(x : y : z)} \leq \frac{|\Phi(X, Y, Z)|}{|\Phi(x, y, z)|} \frac{(x^2 + y^2)^2}{(x^2 + y^2)^2(x^2 - y^2)^4} = \frac{16|k|xy^2}{(x^2 + y^2)^2} \leq 4|k|.
\]

If \(0 < |k| < 1/4\), then we can choose \(\lambda\) so that \(4|k| < \lambda < 1\). If \(N\) is any compact subset of \(\mathbb{P}^2(\mathbb{R})\) \(\backslash\\{(0 : 0 : 1)\}\), then for any \(a\) which is sufficiently close to zero it then follows by continuity that the required inequality (22) holds uniformly throughout \(N\). Thus all orbits of \(f_a\) in \(N\) converge uniformly towards the subset \(C^0_{\mathbb{R}}\). In the case where there are two components, the image \(f_a(C^0_{\mathbb{R}})\) is necessarily equal to the component \(C^0_{\mathbb{R}} \subset C_{\mathbb{R}}\) which contains the fixed point, so it follows that all orbits in \(N\) converge uniformly to \(C^0_{\mathbb{R}}\). \(\Box\)
Remark 7.3. The Case $a = 0$. In the limiting case $a = 0$, there is no superattracting point, and in fact $(0 : 0 : 1)$ becomes a point of indeterminacy. The proof shows that the basin of $C^0_{\mathbb{R}}$ under this limiting map $f_0$ is its entire domain of definition $\mathbb{P}^2(\mathbb{R}) \setminus \{(0 : 0 : 1)\}$, provided that $0 < |k| < 1/4$.

Now let us work over the complex numbers. We will show that a complex elliptic curve can never be a trapped attractor. The proof will occupy the rest of this section.

THEOREM 7.4. No Complex Trapping. Let $C \subset \mathbb{P}^2 = \mathbb{P}^2(\mathbb{C})$ be an elliptic curve and let $N$ be a neighborhood of $C$. Then there cannot exist any holomorphic map $f : N \to N$ such that $\int_n f^{\infty}(N) = C$.

We first carry out the argument for a smooth elliptic curve (necessarily of degree three), and then show how to modify the proof for a singular curve (necessarily of degree greater than three). The proof for a smooth $C$ will be based on the following construction.

Let $N_\varepsilon$ be the $\varepsilon$-neighborhood consisting of all points with distance less than $\varepsilon$ from $C$, using the standard Fubini-Study metric\footnote{In terms of homogeneous coordinates $(x_0 : x_1 : \cdots : x_n)$ normalized so that $\sum |x_k|^2 = 1$, this metric takes the form $dt^2 = \sum |dx_k|^2 + |\bar{\tau} dx_k|^2$. With this normalization, the Riemannian distance $0 \leq \theta \leq \pi/2$ between two points $(x : y : z)$ and $(u : v : w)$ of $\mathbb{P}^2$ can be computed by the formula $\cos(\theta) = |u\bar{v} + v\bar{w} + w\bar{u}|$.} on $\mathbb{P}^2$. If $C$ is smooth and $\varepsilon$ is sufficiently small, then $N_\varepsilon$ is the total space of a real analytic fibration $\pi : N_\varepsilon \to C$, where $\pi(p)$ is defined to be that point $q \in C$ which is closest to $p$. Furthermore, although this projection map $\pi$ is not holomorphic, each fiber $F_q = \pi^{-1}(q)$ is a holomorphically embedded complex disk which is contained in the complex line orthogonal to $C$ at $q$.

LEMMA 7.5. Curves in a Neighborhood. With $C \subset N_\varepsilon$ as above, any non-constant holomorphic map $\phi : C_1 \to N_\varepsilon$ from an elliptic curve into $N_\varepsilon$ must be an immersion, and must intersect each fiber $F_q$ transversally, so that the composition $\pi \circ \phi$ is a real analytic immersion of $C_1$ onto $C$ of degree $\geq 1$.

Proof. Suppose to the contrary that there exists a critical point for the composition $\pi \circ \phi : C_1 \to C$. It will be convenient to rotate the coordinates for $\mathbb{P}^2$ as follows. Using $(x, y)$ as an abbreviation for the point with coordinates $(x : y : 1)$, we may assume that the critical value in $C \subset \mathbb{P}^2$ has coordinates $(0, 0)$ and that the tangent line to $C$ at this critical value has equation $y = 0$. The fiber through this point is then a disk in the line $x = 0$. Choose a parametrization $t \mapsto (x(t), y(t))$ for $C$ so that $x(0) = y(0) = y'(0) = 0$, and choose a parametrization $s \mapsto (x_1(s), y_1(s))$ for $C_1$ so that the critical point in $C_1$ is $s = 0$, mapping to a point $(x_1(0), y_1(0)) = (0, y_0)$ which lies in the fiber $x = 0$. Now expand the function $x_1(s)$ as a power series

$$x_1(s) = cs^n + \text{(higher order terms)},$$

with $c \neq 0$. Here $n \geq 2$, since otherwise $\phi(C_1)$ would cross the fiber $x = 0$ transversally.

Using coordinates $(x, y)$ for $N_\varepsilon$ and $t$ for $C$, we can think of the real analytic projection $\pi : N_\varepsilon \to C$ as a correspondence $\pi : (x, y) \mapsto t = \tilde{t}(x, y)$. Setting $y = y_0 + \eta$, we can write the power series expansion for $\tilde{t}(x, y)$ at the point $(0, y_0) = (x_1(0), y_1(0))$ as

$$\tilde{t} = x(a_1 + (a_2 x + a_3 \tau + a_4 \eta + a_5 \bar{\eta}) + \cdots) + \bar{\tau}(b_1 + (b_2 x + b_3 \tau + b_4 \eta + b_5 \bar{\eta}) + \cdots),$$

where $a_1, b_1$ are constants, and $a_2, b_2, \ldots, a_5, b_5$ are functions of $y_0$.
where the dots stands for terms of degree \( \geq 2 \) in \( x, \eta, \) and \( \eta \), and where the \( a_j \) and \( b_j \) are complex numbers with \( |a_1| > |b_1| \) since the projection from \( (x, y_0) \) to its image in \( C \) must preserve orientation for \( x \) near 0. (Here we can assume that \( b_2 = a_3 \).) Therefore the composition \( s \mapsto (x_1(s), y_1(s)) \mapsto \hat{t} \) has power series

\[
\hat{t} = a_1 c s^n + b_1 \overline{c s^n} + (\text{higher order terms}).
\]

This proves that the composition \( \pi \circ \phi : C_1 \to C \) has an isolated critical point of local degree \( n \geq 2 \) (and hence multiplicity \( n - 1 \geq 1 \)) at the point \( s = 0 \). Thus every critical point is isolated, and it follows that \( \pi \circ \phi \) is a branched covering, with only finitely many critical points.

As in Remark 2.1 we apply the Riemann-Hurwitz Theorem, which asserts that the Euler characteristic \( \chi(C_1) \) is equal to \( \delta \chi(C) - \nu \), where \( \delta \) is the degree of \( \pi \circ \phi \) and where \( \nu \) is the number of critical points counted with multiplicity. Since \( \chi(C_1) = \chi(C) = 0 \), this proves that \( \nu = 0 \), as required. \( \square \)

In particular, it follows that the composition \( \pi \circ \phi : C' \to C \) is quasiconformal. We will need the following.

**Definitions.** The complex dilatation of a quasi-conformal map \( g(z) \) is the ratio

\[
\mu_g(z) = (\partial g/\partial \overline{z})/(\partial g/\partial z).
\]

(The absolute value \( |\mu_g| < 1 \) is sometimes known as the “small dilatation”, while the ratio

\[
K(z) = (1 + |\mu_g|)/(1 - |\mu_g|) \geq 1
\]

is called the dilatation. The associated Teichmüller distance can be defined by first taking the maximum \( \max K(z) \) as \( z \) ranges over the Riemann surface, and then taking the infimum of \( \log(\max K(z)) \) over an isotopy class of maps.

Now consider an infinite sequence of holomorphic immersions \( \phi_j : C_j \to N_\epsilon \), where each \( C_j \) is a compact Riemann surface of genus one.

**LEMMA 7.6. Converging Quasiconformal Maps.** If the successive images \( \phi_j(C_j) \) converge to \( C \) in the Hausdorff topology (or in other words if the distance of each point of \( \phi_j(C_j) \) from \( C \) converges uniformly to zero), then the complex dilatation of the quasiconformal map \( \pi \circ \phi : C_j \to C \) converges uniformly to zero as \( j \to \infty \).

The proof of Lemma 7.6 will be based on the following preliminary statement, which is needed in order to control first derivatives.

**LEMMA 7.7. Converging Tangent Spaces.** With the \( \phi_j \) as in Lemma 7.6, consider a sequence of points \( \phi_j(p_j) \in \phi_j(C_j) \) converging to a point \( q \in C \). Then the tangent space to \( \phi_j(C_j) \) at \( \phi_j(p_j) \) converges to the tangent space to \( C \) at \( q \). Furthermore, this convergence is uniform as we vary the points \( p_j \) and \( q \).

It will be convenient to describe a tangent vector at a point \( p \in N_\epsilon \) as being parallel to \( C \) if it is orthogonal to the fiber through \( p \), as described in the proof of Lemma 7.5. Thus to prove Lemma 7.7 we must show that the angle \( \theta_j \) between\(^6\) the tangent space at \( \phi_j(p_j) \) and the directions parallel to \( C \)

\(^6\)This angle is measured in the tangent space of \( \mathbb{P}^2 \) at the given point. By definition, the angle \( 0 \leq \theta \leq \pi/2 \) between two complex lines through the origin in a Hermitian vector space is defined by the formula \( \cos(\theta) = |\langle v_1, v_2 \rangle| \), where \( v_1 \) and \( v_2 \) are representative unit vectors. (This can be identified with the geodesic distance between the corresponding points in the projective space of lines through the origin.)
at this point must converge to zero as $j \to \infty$. The proof will use the methods of Lemma 7.5 but with a more flexible construction.

**Proof of Lemma 7.7.** Let $\sigma$ be a $C^\infty$-function which assigns to each point $q \in C$ a complex line $\sigma(q)$ which cuts the curve $C$ transversally at $q$, and let $D_\epsilon(q)$ be the disk of radius $\epsilon$ centered at $q$ within this transverse line. Then the union $N(\sigma, \epsilon)$ of all of these transverse disks forms a neighborhood of $C$. Furthermore, there exists a number $\epsilon_\sigma > 0$ which is small enough so that the projection $\pi_\sigma : N(\sigma, \epsilon_\sigma) \to C$ which sends each such disk to its center $q$ is well defined and smooth. Just as in the proof of Lemma 7.5, any immersion of an elliptic curve into $N(\sigma, \epsilon_\sigma)$ must cut every fiber transversally.

We will construct a compact family $K$ of such transverse line fields $\sigma$. Since a radius $\epsilon_\sigma$ which is small enough for a given $\sigma$ will also work for any nearby $\sigma$, it follows that, for any such $K$, we can choose a number $\epsilon_K > 0$ which is small enough so that $\pi_\sigma$ fibers $N(\sigma, \epsilon_K)$ over $C$ for every $\sigma \in K$. Furthermore, since the distance of the boundary of $N(\sigma, \epsilon_K)$ from $C$ depends continuously on $\sigma$, it follows that the intersection $N(K, \epsilon_K) = \bigcap_{\sigma \in K} N(\sigma, \epsilon_K)$ is itself a neighborhood of $C$.

Now suppose that Lemma 7.7 were false, so that we could find a sequence of points $p_j \in C$ such that the corresponding angles $\theta_j$ did not converge to zero. After passing to an infinite subsequence, we may assume that the images $\phi_j(p_j)$ converge to some point $q_0 \in C$, and that the corresponding angles $\theta_j$ are bounded away from zero, say $\theta_j \geq \alpha > 0$. Choose the compact family $K$ of sections $\sigma$ such that, for any $q$ in some neighborhood $U_0$ of $q_0$, every possible transverse line which intersects $C$ at $q$ at an angle greater than $\alpha/2$ will occur as the value $\sigma(q)$ for some $\sigma \in K$. For example we can construct such a $K$ as follows: First choose a nonzero tangent vector field $\vec{v}(q)$ and a nonzero orthogonal vector field $\vec{w}(q)$, where $q$ varies over some neighborhood $U$ of $q_0$ within $C$. Then choose a $C^\infty$ function $\rho : C \to \mathbb{R}$ which has compact support contained in $U$, and which takes the value $+1$ throughout a smaller neighborhood $U_0$ of $q_0$. For any complex constant $a$, define a transverse line field $q \mapsto \sigma_a(q)$ as follows. For $q \in U$ let $\sigma_a(q)$ be the transverse line spanned by the vector

$$\vec{w}_a(q) = a \rho(q)\vec{v}(q) + \vec{w}(q),$$

while for $q \not\in U$ let $\sigma_a(q)$ be the line orthogonal to $C$. Now we can choose the compact set $K$ to be the set of all $\sigma_a$ with $|a| \leq c$, where $c$ is some large constant.

Then for $j$ sufficiently large, the point $\phi_j(C_j)$ will be contained in the intersection $N(K, \epsilon_K)$. Furthermore, the tangent line to $\phi_j(C_j)$ at $p_j$ will intersect $C$ at a point of the neighborhood $U_0$ and at an angle greater than $\alpha/2$. Hence, for a corresponding choice of $\sigma$, this tangent line will contain the fiber of $\pi_\sigma$ through $p_j$. Since this is impossible, we obtain a contradiction which completes the proof of Lemma 7.7. \qed

**Remark 7.8. Convergence of Nearby Curves.** Lemma 7.7 actually implies the stronger statement that, as $j \to \infty$, each branch of the image curve $\phi_j(C_j)$ converges, with all of its derivatives, to $C$. (The number of such branches is equal to the degree of the map $\pi \circ \phi_j : C_j \to C$.) In fact, given any point $q \in C$, we can rotate coordinates, as in the proof of Lemma 7.5, so that $q$ has coordinates $(x, y) = (0, 0)$, and so that the fiber $\pi^{-1}(q)$ is contained in the line $x = 0$. Then $C$ can be described locally as the graph of a holomorphic function $y = y(x)$, and it follows from Lemma 7.7 that, for large $j$, each branch of the image $\phi_j(C_j)$ can be described as the graph of a holomorphic function $y = y_j(x)$ which converges uniformly to $y(x)$ throughout some neighborhood as $j \to \infty$. It then follows from a theorem of Weierstrass that every iterated derivative $d^n y_j(x)/dx^n$ converges uniformly to $d^n y(x)/dx^n$ throughout a smaller neighborhood.
Proof of Lemma 7.6. With coordinates \((x, y)\) as in the preceding remark, let \(t \mapsto (x(t), y(t))\) be a local parametrization of the curve \(C\) with \(x(0) = y(0) = y'(0) = 0\). It will be convenient to construct new local holomorphic coordinates \((u, v)\) by the formula
\[
(x, y) = (x(u), y(u) + v).
\]
In these new coordinates, the curve \(C\) has equation \(v = 0\). The projection \(\pi\) is then represented by a real analytic map \((u, v) \mapsto \hat{t}(u, v)\), where \(\hat{t}(u, 0) = u\), so that \(\partial \hat{t}/\partial u = 1\) and \(\partial \hat{t}/\partial \pi = 0\), when \(v = 0\). For \(j\) large, we can choose \(s = u\) as parameter for the nearby curve \(\phi_j(C_j)\), so that the parametrization takes the form \(s \mapsto (u_j(s), v_j(s))\) with \(u_j(s) = s\). For the composition \(s \mapsto \hat{t}(s, v_j(s))\), it follows that
\[
\frac{\partial \hat{t}}{\partial s} = \frac{\partial \hat{t}}{\partial u} + \frac{\partial \hat{t}}{\partial v} \frac{dv_j}{ds},
\]
where \(\partial \hat{t}/\partial \pi\) tends to zero as \(v_j \to 0\) by the remarks above, and where \(dv_j/\partial s\) tends to zero as \(v_j \to 0\) by Lemma 7.5. It follows easily that the complex dilatation
\[
\mu_{\pi \circ \phi} = \frac{(\partial \hat{t}/\partial \pi)}{(\partial \hat{t}/\partial s)}
\]
tends to zero as \(j \to \infty\), as required. 

Proof of Theorem 7.4 for an embedded curve. The proof will be based on the fact that any smooth elliptic curve \(C \subset \mathbb{P}^2(\mathbb{C})\) can be approximated arbitrarily closely by other elliptic curves which are not conformally isomorphic to it. For example, after a linear change of coordinates, any such \(C\) is defined by an equation of the form \(x^3 + y^3 + z^3 = 3kxyz\), and by varying the parameter \(k\) we can then find nearby curves which are not conformally isomorphic to \(C\).

Now assume that \(C\) is a trapped attractor. Let \(N_{\varepsilon}\) be a tubular neighborhood, as in Lemma 7.5. Then we can chose a trapping neighborhood \(N_{\text{trap}} \subset N_{\varepsilon}\) and then a smaller tubular neighborhood \(N_{\delta} \subset N_{\text{trap}}\), so that
\[
C \subset N_{\delta} \subset N_{\text{trap}} \subset N_{\varepsilon}.
\]
We will then construct a sequence of real analytic retractions \(g_h : N_{\delta} \to C\) of the form
\[
g_h = f^{-h} \circ \pi \circ f^{oh},
\]
(Compare Fig. 15.) More precisely, since \(f^{oh}\) is many-to-one, we will construct \(g_h : N \to C\) so that
\[
f^{oh} \circ g_h = \pi \circ f^{oh},
\]
with \(g_h\) equal to the identity map on \(C\). (Here \(\pi : N_{\varepsilon} \to C\) is again the orthogonal projection which carries each \(p \in N_{\varepsilon}\) to the closest point of \(C\).) To do this, let us first pass to the universal covering spaces \(\tilde{C} \subset \tilde{N}_{\delta} \subset \tilde{N}_{\varepsilon}\). (Since \(C \cong \mathbb{C}/\Omega\), it follows that \(\tilde{C} \cong \mathbb{C}\).) Then \(f\) and \(\pi\) lift to smooth maps
\[
\tilde{C} \subset \tilde{N}_{\delta} \xrightarrow{\tilde{f}} \tilde{N}_{\varepsilon} \xrightarrow{\tilde{\pi}} \tilde{C},
\]
where we can choose the lift so that \(\tilde{\pi}\) reduces to the identity map on \(\tilde{C}\). Since \(\tilde{f}\) is a linear map of \(\tilde{C} \cong \mathbb{C}\), it follows that \(\tilde{f}^{-1}\) is well defined. Therefore the map
\[
\tilde{g}_k = \tilde{f}^{-k} \circ \tilde{\pi} \circ f^{oh} : \tilde{N}_{\delta} \to \tilde{C}
\]
is well defined; and reduces to the identity map on $\tilde{C}$. Finally, since $\tilde{g}_k$ commutes with the group of deck transformations\footnote{On the other hand, the lifted map $\tilde{f}$ does not commute with deck transformations. In fact, if $\Pi$ is the group of deck transformations, then $f$ induces an embedding $f_\ast : \Pi \to \Pi$, with $f_\ast (\sigma \tilde{p}) = \tilde{f}(\sigma)(\tilde{f}(\tilde{p}))$ for each $\sigma \in \Pi$.} of $\tilde{N}_\delta$ over $N_\delta$, it follows that $\tilde{g}_k$ gives rise to a corresponding retraction $g_k : N_\delta \to C$.

Let $C' \subset N_\delta$ be a smoothly embedded elliptic curve which is not conformally equivalent to $C$. Then it follows using Lemma 7.5 that each $g_h$ maps $C'$ diffeomorphically onto $C$. Furthermore, since the successive images $f^{\circ h}(C')$ must converge towards $C$, it follows from Lemma 7.6 that the complex dilatation of the immersion $\pi \circ f^{\circ h} : C' \to \tilde{C}$ tends to zero as $h \to \infty$. Since $f^{\circ h}$ is biholomorphic on both $C'$ and $C$, this implies that the complex dilatation of $g_h : C' \to \tilde{C}$ also tends to zero as $h \to \infty$. Thus, to complete the proof of Theorem 7.4, we need only note the following well known statement from Teichmüller theory.

**LEMMA 7.9. A Conformal Isomorphism Criterion.** Suppose that there exist quasiconformal homeomorphisms from the elliptic curve $C_1$ to $C_2$ with complex dilatation arbitrarily close to zero. Then $C_1$ must be conformally isomorphic to $C_2$.

**Proof.** This is an immediate consequence of compactness of the space of quasiconformal homeomorphisms with bounded complex dilatation. On a more elementary level, if $C_1 \cong C/\Omega_1$ and $C_2 \cong C/\Omega_2$ where $\Omega_1$ and $\Omega_2$ are unimodular lattices, then the optimal quasiconformal map in any homotopy class is given by a real-linear map, corresponding to a linear transformation $L \in \text{SL}(2, \mathbb{R})$ with $L(\Omega_1) = \Omega_2$. (Compare \cite{K} p. 101.) Such a linear transformation has complex dilatation zero only if $L$ is a rotation. Similarly if a sequence of elements of $\text{SL}(2, \mathbb{R})$ has complex dilatation converging to zero, then some subsequence must converges to a rotation. The conclusion of Lemma 7.9 follows easily. This completes the proof of Theorem 7.4 for the case of an embedded curve. \hfill $\Box$

**Proof in the Singular Case.** Now consider an elliptic curve $C \subset \mathbb{P}^2$ (necessarily of degree four or more) which has singular points, so that the uniformizing map $\iota : C/\Omega \to C$ has either critical points or self-intersections or both. We will first prove the following preliminary statement.

**LEMMA 7.10. The Branches Fold Together.** If $C$ is a trapped attractor under some rational map $f$ of $\mathbb{P}^2$, then the uniformizing map $\iota : C/\Omega \to C$ is necessarily an immersion. In particular, $C$ cannot have any cusps. Furthermore, some iterate $f^{\circ n}$ must map all of the branches of $C$ through any singular point $p$ into a single branch through $f^{\circ n}(p)$.
Proof. Recall that the map \( f \) restricted to \( \mathcal{C} \) lifts to a linear map, which we will denote by \( f^\# \), from \( \mathbb{C}/\Omega \) to itself. First suppose that the uniformizing map \( \iota \) has critical points in \( \mathbb{C}/\Omega \). Since there can be only finitely many, and since the lifted map \( f^\# \) must send critical points to critical points, it follows that there must be a periodic critical point. Thus replacing \( f \) and \( f^\# \) by some iterate, we may assume that there is a fixed critical point. In terms of suitable local coordinates around this point and its image in \( \mathbb{P}^2 \), the map \( \iota \) will have power series expansion of the form \( t \mapsto (x,y) = (t^m + \cdots, t^n + \cdots) \) with \( m > n \geq 2 \). Let \( \lambda \) be the multiplier of \( f^\# \). Then the equation \( \iota(\lambda t) = f(\iota(t)) \) implies that the eigenvalues of the derivative \( f' \) at the critical value are \( \lambda^m \) and \( \lambda^n \). Since \( |\lambda| > 1 \), it follows that this critical value is a repelling fixed point for \( f \); which contradicts the hypothesis that \( \mathcal{C} \) has a trapping neighborhood.

Now suppose that we could find two branches through \( \iota(t_1) = \iota(t_2) = p \) which map to distinct branches under all iterates of \( f \). Since there are only finitely many singular points, these images must eventually cycle periodically. Thus, after replacing \( f \) by an iterate, we could find two distinct branches through some singular point \( q \) which both map to themselves. Since \( f^\# \) has multiplier \( \lambda \), it would follow easily that the eigenvalues of \( f' \) at \( q \) have the form \( \lambda^m \) and \( \lambda^n \), where \( m \geq 1 \) is the intersection number between these two branches. Again this shows that \( q \) is a repelling point, contradicting the hypothesis that \( \mathcal{C} \) has a trapping neighborhood.

The Pulled Back Neighborhood. For any small \( \epsilon > 0 \) we can “pull back” the \( \epsilon \)-neighborhood \( N_\epsilon = N_\epsilon(\mathcal{C}) \) under the immersion \( \iota \) to construct a formal neighborhood of \( N_\epsilon^\# \supset \mathbb{C}/\Omega \). For each \( t \in \mathbb{C}/\Omega \), let \( D_t(t, \iota) \subset \mathbb{P}^2 \) be the open unit disk in the line normal to \( \iota(\mathbb{C}/\Omega) \) at \( \iota(t) \), and let

\[
N_\epsilon^\# = N_\epsilon^\#(\iota) \subset (\mathbb{C}/\Omega) \times \mathbb{P}^2
\]

be the set of all pairs \((t, p) \in \mathbb{C}/\Omega \times \mathbb{P}^2 \) with \( t \in \mathbb{C}/\Omega \) and \( p \in D_t(t, \iota) \). Then \( N_\epsilon^\# \) is a real analytic manifold, and the projection \( \pi(t, p) = t \) is a real analytic fibration of \( N_\epsilon^\# \) over \( \mathbb{C}/\Omega \). Furthermore, if \( \epsilon \) is sufficiently small, then the projection \( \pi(t, p) = p \) will be a local diffeomorphism from \( N_\epsilon^\# \) onto the open neighborhood \( N_\epsilon \subset \mathbb{P}^2 \). Using this local diffeomorphism \( \pi \), we can pull back the complex structure and make \( N_\epsilon^\# \) into a complex manifold.

For the next lemma, we assume that \( f \) has been replaced by a suitable iterate \( f^m \), as in Lemma 7.10.

**Lemma 7.11. Lifting the Trapping Neighborhood.** If the singular curve \( \mathcal{C} \) is a trapped attractor under some rational map \( f \) of \( \mathbb{P}^2 \) which folds branches together as in Lemma 7.10, then \( f \) lifts to a holomorphic map \( f^\# \) from a neighborhood of \( \mathbb{C}/\Omega \) in \( N_\epsilon^\# \) into \( N_\epsilon^\# \), with \( \mathbb{C}/\Omega \) as trapped attractor.

**Proof.** Given a neighborhood \( N_\epsilon^\# = N_\epsilon^\#(\iota) \) as above, by the uniform continuity of \( f \) on the compact set \( N_\epsilon(\mathcal{C}) \), we can choose \( \delta < \epsilon \) so that any curve of length \( < \delta \) in \( N_\epsilon(\mathcal{C}) \) maps to a curve of length \( < \epsilon \) in \( \mathbb{P}^2 \). We can then form the neighborhood \( N_\delta^\#(\iota) \subset N_\epsilon^\#(\iota) \) of \( \mathbb{C}/\Omega \), with image \( \mathcal{C} \subset N_\delta(\mathcal{C}) \subset N_\epsilon(\mathcal{C}) \), and with \( f(N_\delta) \subset N_\epsilon \). We may also assume that \( \delta \) is small enough so that the projection which sends each point of \( N_\delta \) to the closest point of \( \mathcal{C} \) is uniquely defined, except within the \( \epsilon \)-neighborhood of a branch point.

Now let \( T \subset N_\delta \) be a trapping neighborhood for \( \mathcal{C} \) and let \( T^\# \) be the full preimage of \( T \) in \( N_\epsilon^\# \). Then a lifted map \( f^\#: T^\# \rightarrow T^\# \) can be constructed as follows. For each point \((t, p) \in T^\# \subset N_\epsilon^\# \), we can drop a perpendicular of length \( < \delta \) from \( p \) to some point \( q \in \mathcal{C} \). The image under \( f \) will then
be a curve of length \( \epsilon \) joining \( f(p) \) to \( f(q) \in C \). Deforming this curve to a minimal geodesic from \( f(p) \) which meets \( C \) orthogonally, say at \( \hat{q} = \iota(\hat{t}) \), it follows that \((\hat{t}, f(p)) \in T^\# \), and we will set \( f^\#(\hat{t}, p) = (\hat{t}, f(p)) \).

This construction does not appear to be well defined in the neighborhood of a singular point, since there may be perpendiculars of length \( \delta \) from \( p \) to points on two or more branches of \( C \). However, by hypothesis these branches all map to a single branch of \( C \), so that the minimal geodesic from \( f(p) \) to that branch of \( C \) is unique.

Finally, we must show that the intersection \( A^\# \) of the iterated forward images of \( T^\# \) is equal to \( C/\Omega \). Clearly the projection from \( T^\# \) onto \( T \) maps \( A^\# \) onto \( C \). Therefore \( A^\# \) is contained in the preimage of \( C \) in \( T^\# \). This consists of \( C \), together with preimages of the \( \epsilon \)-neighborhoods of the various branch points. (If \( \iota(t_1) = \cdots = \iota(t_k) \), then there are \( k - 1 \) extra preimage branches through each of the points \( t_1, \ldots, t_k \).) But \( f^\# \) maps each of these extra branches back to \( C/\Omega \), so the attractor \( A^\# \) is precisely \( C/\Omega \).

The proof of Theorem 7.4 now proceeds just as in Lemmas 7.5 through 7.9 above. However, to carry out the argument in this new context, we must show that there are nearby curves which are not conformally isomorphic to \( C/\Omega \). In fact, we will prove the following, which will complete the proof.

**Lemma 7.12. Deforming Immersed Curves.** Consider a Riemann surface of genus one of the form \( C/\Omega \), and let \( F_\Omega : C/\Omega \to \mathbb{P}^2 \) be an immersion. Then for any small deformation \( \Omega_t \) of the lattice \( \Omega \), we can construct a corresponding deformation \( F_{\Omega_t} \) of the immersion \( F_\Omega \).

**Proof.** Let \( \hat{\mathbb{P}}^2 \) be the projective plane blown up at the three coordinate points \((1 : 0 : 0), (0 : 1 : 0), \) and \((0 : 0 : 1) \). The following two statements are easily verified.

1. Any holomorphic immersion of a Riemann surface into \( \mathbb{P}^2 \) lifts uniquely to an immersion into \( \hat{\mathbb{P}}^2 \), and any immersion into \( \hat{\mathbb{P}}^2 \) projects to a map into \( \mathbb{P}^2 \) which is an immersion, except possibly over the three coordinate points.

(The qualification is necessary since, for example, the non-immersion \( t \mapsto (t^3 : t^2 : 1) \) from \( \mathbb{P}^1 \) into \( \mathbb{P}^2 \) lifts to an immersion into \( \hat{\mathbb{P}}^2 \).)

2. We can construct a smooth embedding of \( \hat{\mathbb{P}}^2 \) as a hypersurface in \( \mathbb{P}^1 \times \mathbb{P}^1 \) by sending each \((x : y : z) \in \hat{\mathbb{P}}^2 \) to the triple \((f, g, h) \) where

\[
  f = \frac{x}{y}, \quad g = \frac{y}{z}, \quad h = \frac{z}{x}.
\]

with product \( fgh = 1 \).

(The blowup guarantees, for example, that \( x/y \) makes sense, even at the point \((0 : 0 : 1) \). Interpreted in terms of local coordinates for \( \mathbb{P}^1 \), the equation \( fgh = 1 \) is well behaved, even when one or two of these functions take the value \( \infty \). For example, near a point where \( h = \infty \) but \( f \) and \( g \) are finite, we use \( h^{-1} \) as local coordinate, so that the equation takes the form \( h^{-1} = fg \).)

Thus to immerse a Riemann surface \( S \) into \( \mathbb{P}^2 \) we need only find three holomorphic functions \( f, g, h \) from \( S \) to \( \mathbb{P}^1 \) which yield an immersion of \( S \) into \( \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1 \), and which have product equal to 1, taking care that nothing goes wrong over the three coordinate points. (The maps \( f, g, h \) need not
have the same degree. For example the functions \( f(t) = g(t) = t, \ h(t) = 1/t^2 \) from \( \mathbb{P}^1 \) to \( \mathbb{P}^1 \) yield the smooth quadratic variety \( xyz = y^2 \)).

As noted above, \( F_0 \) lifts to an embedding \( t \mapsto (f(t), g(t), h(t)) \) of \( \mathbb{C}/\Omega \) into the subset \( \tilde{\mathbb{P}}^2 \subset \mathbb{P}^1 \times \mathbb{P}^1 \times \mathbb{P}^1 \). Furthermore, each of the functions \( f \) and \( g \) can be expressed as a rational function of the Weierstrass function \( \wp_\Omega(t) \) and its derivative \( \wp'_\Omega(t) \). Choosing some explicit expressions for these rational functions and setting \( h = 1/(fg) \), it follows that the map \( t \mapsto (f(t), g(t), h(t)) \) deforms smoothly as we modify the lattice \( \Omega \). Evidently the requirement that this map project to an immersion into \( \mathbb{P}^2 \) will remain satisfied for all sufficiently small deformations. This completes the proof of Lemma 7.12 and hence of Theorem 7.4. \( \square \)

8 Herman Rings in \( \mathbb{P}^2 \).

By a Herman ring for a rational map \( f \) of \( \mathbb{P}^2 = \mathbb{P}^2(\mathbb{C}) \) we mean a (complex one-dimensional) annulus \( H \) which is smoothly embedded in \( \mathbb{P}^2 \) and which maps to itself by an irrational rotation under \( f \), or under some iterate of \( f \). In Example 5.4 we presented empirical evidence for the existence of attracting Herman rings, invariant under \( f \circ f \), for a substantial collection of maps in the Desboves family with real parameters. This section will explore what we can say more generally about Herman rings in \( \mathbb{P}^2 \). Note first that it is easy to construct special examples.

**Example 8.1. Rings Contained in a Complex Line.** Let \( (z_0 : z_1) \mapsto (p(z_0, z_1) : q(z_0, z_1)) \) be any degree \( d \) rational map of \( \mathbb{P}^1(\mathbb{C}) \) which possesses a Herman ring. (Compare Remark 8.8 and see for example [Sh].) Let \( r(z_0, z_1, z_2) \) be any nonzero homogeneous polynomial of degree \( d - 1 \). Then the map

\[
 f(z_0 : z_1 : z_2) = (p(z_0, z_1) : q(z_0, z_1) : z_2 r(z_0, z_1, z_2))
\]

of \( \mathbb{P}^2(\mathbb{C}) \) clearly has a Herman ring \( H \) which lies in the invariant line \( z_2 = 0 \). We can measure the extent to which this ring is attracting or repelling by using the ratio \( \rho(z_0 : z_1 : z_2) = |z_2|/\sqrt{|z_0|^2 + |z_1|^2} \) as a measure of distance from the line \( z_2 = 0 \). If the ratio

\[
 \frac{\rho(f(z_0 : z_1 : z_2))}{\rho(z_0 : z_1 : z_2)} = |r| \sqrt{\frac{|z_0|^2 + |z_1|^2}{|p|^2 + |q|^2}}
\]

is less than 1 everywhere on \( H \) then this ring will be locally uniformly attracting, while if it is greater than 1 everywhere on \( H \) then it will be locally uniformly repelling. Thus we can always obtain an attracting \( H \) simply by multiplying any given \( r(z_0, z_1, z_2) \) by a constant which is close to zero. Similarly, if \( r(z_0 : z_1 : 0) \) is bounded away from zero throughout \( H \), then we can obtain a repelling \( H \) by multiplying \( r(z_0, z_1, z_2) \) by a large constant. In the first case, note that \( H \) will be contained in the Fatou set, while in the second case it will be contained in the Julia set.

Note however that a Herman ring can never be a trapped attractor, since its boundary points will never be attracted to it. Thus it can never attract a closed neighborhood of itself.

**Example 8.2. The Ueda Construction.** Here is a quite different procedure. (Compare [F] p. 13.) Recall that the \( n \)-fold symmetric product of \( \mathbb{P}^1(\mathbb{C}) \) with itself, that is the quotient \( (\mathbb{P}^1 \times \cdots \times \mathbb{P}^1)/S_n \) of the \( n \)-fold product by the symmetric group \( S_n \) of permutations of the \( n \) coordinates, can be naturally identified with \( \mathbb{P}^n(\mathbb{C}) \). Hence any rational map \( f \) of \( \mathbb{P}^1 \) gives rise to an everywhere defined
rational map \((f \times \cdots \times f)/S_n\) of \(\mathbb{P}^n\). In particular, it gives rise to a map\(^8\) \((f \times f)/S_2\) of \(\mathbb{P}^2\). Now if \(U_1\) and \(U_2\) are disjoint invariant Fatou components in \(\mathbb{P}^1\), then the product \(U_1 \times U_2 \subset \mathbb{P}^1 \times \mathbb{P}^1\) projects diffeomorphically to an invariant Fatou component in \(\mathbb{P}^2\). In particular, if \(U_1\) is a Herman ring and \(U_2\) is the immediate basin of an attracting fixed point, then the image of \(U_1 \times U_2\) in \(\mathbb{P}^2\) is the immediate basin of an attracting Herman ring. Similarly, given two disjoint Herman rings, we obtain their cartesian product as a Fatou component,\(^9\) but given a Herman ring and a parabolic or repelling point we obtain a Herman ring which is contained in the Julia set.

The Transverse Lyapunov Exponent. For any \(f\)-invariant Herman ring or Siegel disk the transverse Lyapunov exponent is defined much as in the case of an \(f\)-invariant elliptic curve, but is even more decisive as a test for attraction or repulsion. However, in these rotation domain cases, this transverse exponent is no longer a constant, but is rather a convex piecewise linear real valued function (constant on each invariant circle). To fix our ideas, we will concentrate on the Herman ring case.

To begin the discussion, note that for any Herman ring \(H \subset \mathbb{P}^2(\mathbb{C})\) (and more generally any annulus) there is an essentially unique conformal embedding \(t : H \to \mathbb{C}/\mathbb{Z}\) which maps \(H\) isomorphically onto a cylinder of the form \(h_0 < \Im(t) < h_1\) in \(\mathbb{C}/\mathbb{Z}\). (More precisely, this embedding is unique up to a translation or change of sign \(t \mapsto \pm t + \text{constant}\). The difference \(h_1 - h_0\) is called the modulus of \(H\).)

We will call \(t\) a canonical parameter on \(H\).

**Lemma 8.3. Holomorphic Tubular Neighborhoods.** Let \(\Gamma_h \subset H \subset \mathbb{P}^2\) be the invariant circle \(\Im(t) = h\) contained in a Herman ring in the complex projective plane. Then we can parametrize some neighborhood \(N = N(\Gamma_h)\) in \(\mathbb{P}^2\) by holomorphic coordinates \((t, u)\), where \(u\) ranges over a neighborhood of zero in \(\mathbb{C}\) and \(t\) ranges over a neighborhood of the circle \(\Im(t) = h\) in \(\mathbb{C}/\mathbb{Z}\). Furthermore these coordinates can be chosen so that we have \(u = 0\) on the intersection \(N \cap H\), with \(t\) the canonical parameter for \(H\).

**Proof.** In the dual projective space consisting of all lines in \(\mathbb{P}^2\), those lines which intersect \(\Gamma_h\) form a real 3-dimensional subset. Hence we can choose a line which misses \(\Gamma_h\). After rotating the coordinates \((x : y : z)\), we may assume that this is the line \(z = 0\). In other words, setting \(X = x/z\), \(Y = y/z\), we can introduce the affine coordinates \((X : Y : 1) = (x : y : z)\) throughout some neighborhood of \(\Gamma_h\). Let \(X = X(t)\), \(Y = Y(t)\) be the canonical parametrization of \(H\) throughout this neighborhood. Then the space of all unit vectors in \(\mathbb{C}^2\) which are multiples of the tangent vector \((\dot{X}(t), \dot{Y}(t))\) for some \((X(t), Y(t)) \in \Gamma_h\) has real dimension 2. Hence we can choose a fixed unit vector \(\vec{V} \in \mathbb{C}^2\) which is not tangent to \(H\) at any point of \(\Gamma_h\). The required coordinates \((t, u)\) are now defined by the formula

\[(t, u) \mapsto (X(t), Y(t)) + u \vec{V}\]

for all \((t, u) \in (\mathbb{C}/\mathbb{Z}) \times \mathbb{C}\) with both \(\Im(t) - h\) and \(|u|\) sufficiently small.

The map \(f\), expressed in terms of these tubular coordinates in a neighborhood of \(\Gamma_h\), has the form \((t, u) \mapsto (T, U)\), where \((t, 0)\) maps to \((t + \alpha, 0)\) for some irrational rotation number \(\alpha\). Evidently we can identify the transverse derivative along \(H_0\) with the partial derivative

\[
\frac{\partial U}{\partial u}(t, 0).
\]

---

\(^8\)More explicitly, if \(f(x : y) = (p(x, y) : q(x, y))\) then the map \((f \times f)/S_2\) can be described by the formula \((x_1 x_2 : x_1 y_2 + y_1 x_2 : y_1 y_2) \mapsto (p_1 p_2 : p_1 q_2 + q_1 p_2 : q_1 q_2)\), where \(p_1 = p(x_1, y_1)\) and \(q_1 = q(x_1, y_1)\).

\(^9\)This construction can even be used to construct a Herman ring (or Siegel disk) in the real projective plane: Start with a rational map of \(\mathbb{P}^1(\mathbb{C})\) with real coefficients which has two complex conjugate Herman rings (or Siegel disks). Carry out the construction described above, and then intersect with \(\mathbb{P}^2(\mathbb{R})\).
The transverse Lyapunov exponent is then defined as the horizontal average

$$\text{Lyap}(t) = \int_0^1 \log \left| \frac{\partial U}{\partial u}(t + \tau) \right| d\tau,$$

where we integrate over the interval $0 \leq \tau \leq 1$. If there are no zeros of $\partial U/\partial u$ in the strip $h_0 < \Im(t) < h_1$, $u = 0$, then $\text{Lyap}(t)$ is an average of harmonic functions, and hence is harmonic. Since this harmonic function is constant on horizontal lines, it must be a linear function of the imaginary part $\Im(t)$. (We will sharpen this statement in Lemma 8.5.) The dynamical implications of this Lyapunov exponent can be described as follows.

**Lemma 8.4. Attraction or Repulsion.** If $\text{Lyap}(t)$ is negative along the invariant circle $\Gamma_h \subset H$, then a neighborhood of $\Gamma_h$ in the Herman ring $H$ is uniformly attracting, and hence is contained in the Fatou set of $f$. On the other hand, if $\text{Lyap}(t)$ is positive, then $\Gamma_h$ is contained in the Julia set.

However, in the intermediate case where $\text{Lyap}(t)$ is identically zero near $\Gamma_h$, we do not have enough information to decide. In fact, using Ueda’s construction (Example 8.2), we can find examples illustrating both possibilities. We can choose $f$ so that a neighborhood of $H$, with its dynamics, is isomorphic to (Herman ring)$\times$(Siegel disk) and hence belong to the Fatou set. On the other hand, we can choose $f$ so that $H$ corresponds to (Herman ring)$\times$(parabolic point), and hence belong to the Julia set.

**Proof of Lemma 8.4.** Recall that the map $f$ restricted to the ring $H$ has the form $t \mapsto t + \alpha$ where the rotation number $\alpha$ is irrational. To simplify the notation, let us translate the canonical parameter $t$ so that it takes real values (modulo one) on our invariant circle, with $h = 0$. Following Hermann Weyl, for any continuous function $g : \mathbb{R}/\mathbb{Z} \to \mathbb{C}$, the successive averages

$$A_n g(t) = (1/n) \sum_{0 \leq j < n} g(t + j\alpha)$$

converge uniformly to the integral $\int_{\mathbb{R}/\mathbb{Z}} g(t) dt$. To prove this, note that any continuous $g$ can be uniformly approximated by trigonometric polynomials of the form $\sum_{|k| \leq N} a_k e^{2\pi i k t}$. But this statement is easily verified for each such trigonometric polynomial.

First suppose that the transverse derivative $\frac{\partial U}{\partial u}(t, 0)$ has no zeros on $\mathbb{R}/\mathbb{Z}$, so that the function $t \mapsto g(t) = \log \left| \frac{\partial U}{\partial u}(t, 0) \right|$ is finite valued near $\mathbb{R}/\mathbb{Z}$. If the average $\text{Lyap}(0)$ of $g$ on $\mathbb{R}/\mathbb{Z}$ is strictly positive (or strictly negative), then we can choose an integer $n > 0$ so that $A_n g(t)$ is strictly positive (or negative) and bounded away from zero on $\mathbb{R}/\mathbb{Z}$, and hence throughout some neighborhood of $\mathbb{R}/\mathbb{Z}$ in $\mathbb{C}/\mathbb{Z}$. Now consider an orbit $(t_0, u_0) \mapsto (t_1, u_1) \mapsto \cdots \mapsto (t_n, u_n)$ near the given circle $\Gamma_0$. Note that

$$\lim_{u_0 \to 0} \frac{u_n}{u_0} = \frac{\partial u_n}{\partial u_0}(t_0, 0) = \prod_{0 \leq j < n} \frac{\partial u_{j+1}}{\partial u_j}(t_0 + j\alpha, 0) = \exp\left(n A_n g(t)\right).$$

Taking the log absolute value of both sides, if $A_n g(t) < \log(c) < 0$ on $\mathbb{R}/\mathbb{Z}$, then $|\partial u_n/\partial u_0| < c^n$ when $u_0 = 0$, and it follows easily that $|u_n| \leq c^n |u_0|$ uniformly throughout a neighborhood of our invariant circle. This proves that some neighborhood $H_0$ in $H$ is uniformly attracted to $\Gamma_0$. Similarly, if $A_n g(t) > \log(c) > 0$, then a neighborhood is uniformly repelled, so that $\Gamma_0$ is contained in the Julia set.
Now suppose that the holomorphic function \( t \mapsto \frac{\partial U}{\partial u}(t,0) \) has zeros along the real axis. The superattracting case where this derivative is identically zero on \( H \) is easily dealt with, so we will assume that these zeros are isolated. If \( \text{Lyap}(0) < 0 \), then we can replace \( g(t) \) by the truncated function \( g_\nu(t) = \max(g(t), \nu) \), where \( \nu \) is some negative real constant. If \( \nu \) is sufficiently negative, then the integral \( \int_0^1 g_\nu(t) \, dt \) will still be negative. Hence we can choose \( n \) so that \( A_n g(t) \leq A_n g_\nu(t) < \log(e) < 0 \), and it again follows that a neighborhood \( H_0 \) of \( \Gamma_0 \) is uniformly attracting. In the case \( \text{Lyap}(0) > 0 \), we cannot assert that a neighborhood is uniformly repelling when it contains zeros of \( \partial U/\partial u \). However, it is not hard to check that the function \( t \mapsto \text{Lyap}(\Im(t)) \) is continuous, and hence is positive throughout a neighborhood. Since the Julia set of \( f \) is closed, we can at least conclude that \( \Gamma_0 \) is contained in the Julia set.

**Lemma 8.5.** **Piecewise Linearity.** Let \( H \subseteq \mathbb{P}^2 \) be a Herman ring with canonical parameter \( t \in \mathbb{C}/\mathbb{Z} \), where \( h_0 < \Im(t) < h_1 \). Then the function \( \text{Lyap} : (h_0, h_1) \to \mathbb{R} \) is convex and piecewise linear, with a jump in derivative at \( h \) if and only if the transverse derivative \( \partial U/\partial u \) has a zero on the circle \( \Im(t) = h \). In fact the change in derivative at \( h \) is equal to \( 2\pi \) times the number of zeros of \( \partial U/\partial u \) on this circle, counted with multiplicity.

**Proof.** We will adapt a classical argument due to Jensen. (See for example [MK Appendix A].) It will be convenient to use the abbreviated notation \( \phi(t) = \partial U/\partial u \) for the transverse derivative evaluated at \( (t,0) \), and \( \phi'(t) \) for its derivative. If \( \phi \) has no zeros on the circle \( \Im(t) = h \), then we can compute the derivative of the transverse Lyapunov exponent by differentiating under the integral sign. Setting \( t = \tau + ih \), we have

\[
\frac{\partial}{\partial h} \log |\phi(t)| = \frac{\partial}{\partial h} \Re \left( \log \phi(t) \right) = \Re \left( \frac{d \log \phi(t)}{dt} \frac{\partial t}{\partial h} \right) = \Re \left( \frac{\phi'}{\phi} \right)
\]

and therefore

\[
\text{Lyap}'(h) = \frac{d}{dh} \int_0^1 \log |\phi(\tau + ih)| \, d\tau = \Re \int_0^1 i \frac{\phi'}{\phi} \, d\tau,
\]

where \( \phi' \) and \( \phi \) are evaluated at \( t = \tau + ih \) for \( 0 \leq \tau \leq 1 \) with \( h \) constant. Briefly, we can write

\[
\text{Lyap}'(h) = \Re \int_{[0,1] \times \{h\}} i \frac{d\phi}{\phi}.
\]

Given two numbers \( h_0 \leq h_1 \) such that \( \phi \) has no zeros at height \( h_0 \) or \( h_1 \), we can now compute the difference \( \text{Lyap}'(h_1) - \text{Lyap}'(h_0) \) as follows. Translating the parameter \( t \) horizontally if necessary we may assume also that \( \phi \) has no zeros on the vertical line \( \Re(t) = 0 \). Let \( R \) be the rectangle consisting of all \( t \in \mathbb{C} \) with \( 0 \leq \Re(t) \leq 1 \) and \( h_0 \leq \Im(t) \leq h_1 \). Integrating in the positive direction around the boundary of \( R \), since the integrals around the left and right sides cancel out, we obtain

\[
\text{Lyap}'(h_0) - \text{Lyap}'(h_1) = \Re \oint_{\partial R} i \frac{d\phi}{\phi}.
\]

But the integral \( \oint_{\partial R} d\phi/\phi \) is equal to \( 2\pi i N(R) \), where \( N(R) \) is the number of zeros of \( \phi \) in \( R \), so this equation reduces to \( \text{Lyap}'(h_1) - \text{Lyap}'(h_0) = 2\pi N(R) \). This proves Lemma 8.5. \( \square \)

**Remark 8.6.** **Siegel Disks** There is an analogous statement for the transverse exponent of a Siegel disk in \( \mathbb{P}^2 \). Let us parametrize the Siegel disk by the unit disk \( \mathbb{D} \) consisting of all \( z \in \mathbb{C} \) with \( |z| = r < 1 \).
taking $z = 0$ for the center point. Then the transverse Lyapunov exponent can be expressed as a convex piecewise linear function of $\log(r)$. In fact, it is determined up to an additive constant by the identity

$$\frac{d \text{Lyap}}{d \log(r)} = N(\mathcal{D}_r) \geq 0,$$

where $N(\mathcal{D}_r)$ is the number of zeros of the transverse derivative, counted with multiplicity, in the disk of radius $r$. The proof, similar to that above, is essentially Jensen’s original computation.

**Herman Rings for Maps with Real Coefficients.** Most known examples of Herman rings have been specially constructed. The surprise in Example 5.4 was to find an apparent example which appeared out of the blue, with no obvious reason to expect it. The set of complex rational maps of specified degree with a Herman ring presumably has measure zero, so that a randomly chosen example will never have a Herman ring. However, if we consider rational maps with real coefficients then the situation is different, and the discussion in Example 5.4 suggests that the set of real parameters which give rise to a complex Herman ring should have positive Lebesgue measure.

Let $f$ be a rational map of $\mathbb{P}^2$ with real coefficients, and suppose that there exists an embedded $f$-invariant circle $\Gamma \subset \mathbb{P}^2(\mathbb{R})$ with irrational rotation number. If $\Gamma$ is smooth of class $C^2$, then according to Denjoy’s Theorem the restriction $f|_{\Gamma}$ is topologically conjugate to a circle rotation. In particular, there is a canonical $f$-invariant probability measure $d\mu$ with support equal to the entire circle. The transverse Lyapunov exponent of $\Gamma$ in $\mathbb{P}^2(\mathbb{R})$ is then well defined. Just as in the proof of Lemma 8.4, a positive Lyapunov exponent implies that $\Gamma$ is uniformly repelling, and similarly, a negative exponent implies that $\Gamma$ is uniformly attracting and hence is a trapped attractor.

In the real analytic case we can complexify the circle $\Gamma$.

**Lemma 8.7. From Circle to Ring.** Let $f$ be a rational map of $\mathbb{P}^2(\mathbb{R})$. If $\Gamma$ is a real analytic $f$-invariant circle with Diophantine rotation number, then the associated map from $\mathbb{P}^2(\mathbb{C})$ to itself possesses a Herman ring $H \supset \Gamma$. Furthermore, the transverse Lyapunov exponent of $\Gamma$ in $\mathbb{P}^2(\mathbb{R})$ is then well defined. Just as in the proof of Lemma 8.4, a positive Lyapunov exponent implies that $\Gamma$ is uniformly repelling, and similarly, a negative exponent implies that $\Gamma$ is uniformly attracting and hence is a trapped attractor.

If we exclude the special case where the transverse exponent is exactly zero, then it follows that $\Gamma$ is repelling (or attracting) in the real projective plane if and only if a neighborhood of $\Gamma$ in $H$ is repelling (or attracting) in the complex projective plane.

**Remark 8.8. The One-Dimensional Case.** It is interesting to compare the situation in one variable. For any odd number $d \geq 3$, the set of degree $d$ rational maps which carry the real projective line $\mathbb{P}^1(\mathbb{R})$ diffeomorphically onto itself is open, and all possible rotation numbers are realized. If such a map has Diophantine rotation number, then a similar argument shows that the corresponding rational map of $\mathbb{P}^1(\mathbb{C})$ contains a Herman ring.

**Proof of Lemma 8.7.** By a theorem of Herman, as sharpened by Yoccoz, (see [Y]), any orientation preserving real analytic diffeomorphism of a circle with Diophantine rotation number $\alpha$ is real analytically conjugate to the rigid rotation $t \mapsto t + \alpha \pmod{\mathbb{Z}}$ of the standard circle $\mathbb{R}/\mathbb{Z}$. That is, there is a real analytic diffeomorphism $h : \mathbb{R}/\mathbb{Z} \to \Gamma \subset \mathbb{P}^2(\mathbb{R})$ so that $f(h(t)) = h(t + \alpha)$. Since $h$ is real analytic, it extends to a complex analytic diffeomorphism from a neighborhood of $\mathbb{R}/\mathbb{Z}$ in the cylinder $\mathbb{C}/\mathbb{Z}$ into the complex projective plane. The image of this extended map on some neighborhood $\{t \bmod{\mathbb{Z}} : |\Im(t)| < \epsilon\}$ is the required Herman ring $H \subset \mathbb{P}^2(\mathbb{C})$. Evidently the translation $t \mapsto t + \alpha$ on
this neighborhood is conjugate to the rational map \( f \) on \( H \). Further details are straightforward, since any norm on the normal bundle of \( H \) in \( \mathbb{P}^2(\mathbb{C}) \) will restrict to a norm on the normal bundle of \( \Gamma \) in \( \mathbb{P}^2(\mathbb{R}) \).

Now consider a \( C^\infty \)-smoothly embedded circle \( \Gamma_0 \) in a real 2-dimensional manifold \( M \). Let \( f_0 : M \to M \) be a \( C^\infty \)-smooth map which restricts to an irrational rotation on \( \Gamma_0 \), and which has negative transverse exponent on \( \Gamma_0 \). As noted above, this implies that \( \Gamma_0 \) is a trapped attractor. Let \( N \subset M \) be a trapping neighborhood, with \( f_0(N) \subset \text{interior}(N) \).

**THEOREM 8.9. Persistence of Invariant Circles.** In this situation, for any \( C^\infty \)-map \( f_\tau \) which is close enough to \( f_0 \) in the \( C^1 \)-topology, the intersection

\[
\Gamma_\tau = \bigcap_n f_\tau^n(N)
\]

of the iterated forward images of \( N \) under \( f_\tau \) will be a topological circle; and \( f_\tau \) will map this circle homeomorphically onto itself with a rotation number \( \rho_\tau \) which varies continuously with \( \tau \). Furthermore, for any finite \( k \), if \( f_\tau \) is \( C^1 \)-sufficiently close to \( f_0 \), then \( \Gamma_\tau \) will be \( C^k \)-smooth.

Here we can expect the continuous function \( \tau \mapsto \rho_\tau \) to have an interval of constancy whenever \( \rho_\tau \) takes a rational value. In fact, a generic map \( f_\tau \) with \( \rho_\tau = p/q \) will have an attracting period \( q \) orbit contained in \( \Gamma_\tau \). In this case, \( \Gamma_\tau \) cannot contain any dense orbit. Evidently such an attracting orbit will be stable under perturbation.

**Proof of Theorem 8.9.** If a neighborhood of \( \Gamma_0 \) is orientable, then we can choose local coordinates \( t \in \mathbb{R}/\mathbb{Z} \) and \(-\epsilon < x < \epsilon \) throughout some neighborhood of \( \Gamma_0 \) so that \( \Gamma_0 \) is given by the equation \( x = 0 \), and is mapped to itself by \( t \mapsto t + \alpha \) with \( \alpha \) irrational. In the non-orientable case, we can first pass to the 2-fold orientable covering of a neighborhood and then choose such coordinates.

We will denote the map \( f_0 \) in these coordinates by \( f_0(t, x) = (T, U) \). It will be convenient to use abbreviated notations such as

\[
\partial_t U = \frac{\partial}{\partial t} U(t, x), \quad \partial_x U = \frac{\partial}{\partial x} U(t, x).
\]

Given \( 0 < c < 1 \), after replacing \( f_0 \) by some high iterate, we may assume that \( |\partial_x U| < c \) when \( x = 0 \). Furthermore, after a carefully chosen change of coordinates, we will show that \( \partial_x T = 0 \) when \( x = 0 \), so that

\[
\begin{align*}
\partial_t T &= 1, & \partial_x T &= 0, \\
\partial_t U &= 0, & |\partial_x U| &< c
\end{align*}
\]  

(24)

along the circle \( x = 0 \). In order to construct this change of coordinates, we first introduce the smooth functions

\[
r_n = r_n(t) = \partial_x U(t + n\alpha, 0), \quad s_n = s_n(t) = \partial_x T(t + n\alpha, 0),
\]

with \( |r_n| < c \). Now introduce the change of coordinates

\[
(t, x) \leftrightarrow (\hat{t}, x) \quad \text{where} \quad \hat{t} = t + (s_0 + r_0 s_1 + r_0 r_1 s_2 + \cdots) x.
\]

A brief calculation shows that the induced map \( (\hat{t}, x) \to (\hat{T}, U) \) in these new coordinates satisfies the required condition \( \partial_x \hat{T} = 0 \) when \( x = 0 \). Henceforth, we will omit the hat and simply assume that \( \partial_x T = 0 \) along the circle \( x = 0 \).
Given any $0 < \eta < 1$, we can first choose a trapping neighborhood $N = \{(t, x) : |x| \leq b_0\}$ for $\Gamma_0$ which is small enough so that the inequalities

$$
|\partial_t T - 1| < \eta, \quad |\partial_x T| < \eta,
$$

$$
|\partial_t U| < \eta, \quad |\partial_x U| < c,
$$

are valid throughout this neighborhood. We can then choose $f_\tau$ close enough to $f_0$, so that $f_\tau(N) \subset \text{interior}(N)$, so that these inequalities remain true for the map $f_\tau(t, x) = (T, U)$.

Now consider a curve $t \mapsto x(t)$ with slope $v(t) = dx/dt$. Setting $f_\tau(t, x(t)) = (T, U)$, we have

$$
\frac{dT(t, x(t))}{dt} = \frac{\partial T}{\partial t} + \frac{dx}{dt} \frac{\partial T}{\partial x}
$$

or briefly $D_t T = (\partial_t + v \partial_x)T$,

and similarly $D_t X = (\partial_t + v \partial_x)X$. Given some upper bound $b_1$ for $|v| = |dx/dt|$, we can estimate that

$$
D_t T > 1 - \eta - b_1 \eta \quad \text{and} \quad |D_t X| < \eta + b_1 c,
$$

and hence

$$
\left| \frac{dX}{dT} \right| = \left| \frac{D_t X}{D_t T} \right| < \frac{\eta + b_1 c}{1 - \eta - b_1 \eta}.
$$

If $\eta$ is sufficiently small, then this upper bound will be strictly less than $b_1$. More precisely, if

$$
0 < \eta < \frac{b_1(1 - c)}{1 + b_1 + b_1^2},
$$

then a brief computation shows that $D_t T > 0$ and that $(\eta + b_1 c)/(1 - \eta - b_1 \eta) < b_1$. It will then follow that the image curve is the graph of a well defined function $X = X(T)$, and furthermore that the slope of this image curve is bounded by the same constant,

$$
|dX/dT| < b_1.
$$

It follows inductively that each iterated forward image of the initial curve will again be a well defined curve with $|\text{slope}| < b_1$.

As trapping neighborhood $N$ we can choose a union of horizontal circles $x = \hat{x}$ with $-b_0 \leq \hat{x} \leq b_0$. Then each iterated image $f_\tau^m(N) \subset N$ will be a corresponding union of a continuum of curves of the form $x_n = x_n(t)$ with $|dx_n/dt| \leq b_1$. If $x_N(t)$ is the infimum of these curves and $x_n^+(t)$ is the supremum, then it follows easily that the $n$-th forward image of $N$ is given by

$$
f_\tau^m(N) = \{(x, t) : x_n(t) \leq x \leq x_n^+(t)\}.
$$

Here the upper and lower boundaries both satisfy a Lipschitz condition

$$
|x_n^+(t_1) - x_n^+(t_0)| \leq b_1|t_1 - t_0|.
$$

On the other hand, it is easy to check that the Jacobian determinant is bounded by

$$
|\text{Jacobian}| < (1 + \eta)c + \eta^2,
$$
and we may assume that this upper bound is strictly less than one. Hence the areas of these successive images shrink to zero. Thus \( \int_0^1 (x_n^+(t) - x_n^-(t)) \, dt \) tends to zero as \( n \to \infty \). It follows easily that the upper and lower bounding curves tend to a common Lipschitz limit. This proves that the attracting set

\[ \Gamma_T = \bigcap_{n \geq 0} f(T)^n(N) \]

is itself the graph of a function \( t \mapsto \lim_{n \to \infty} x_n^+(t) \) which is continuous (and in fact Lipschitz with Lipschitz constant \( b_1 \)).

In order to prove that this attracting curve is \( C^1 \) smooth, we must estimate second derivatives. Computations show that

\[ \frac{d^2X}{dT^2} = \frac{(D^2_X)X(D_T) - (D^2_TX)(D_X)}{(D_T)^2} , \]

where

\[ D^2_T = \partial^2_t + 2v\partial_t \partial_x + v^2\partial^2_x + (dv/dt)\partial_x . \]

Separating out the \( dv/dt = d^2x/dt^2 \) terms, we can write this as

\[ \frac{d^2X}{dT^2} = A_2 + B_2 \frac{d^2x}{dt^2} , \tag{26} \]

where \( A_2 \) is uniformly bounded and where

\[ B_2 = \frac{\partial^2_tX}{(D_T)^2} - \frac{(\partial^2_tX)(D_X)}{(D_T)^3} , \]

so that

\[ |B_2| < \frac{c}{(1 - \eta - b_1\eta)^2} + \frac{\eta(\eta + b_1)}{(1 - \eta - b_1\eta)^3} . \]

Evidently, if \( \eta \) is small enough, then \( |B_2| < \text{constant} < 1 \). We can then choose a constant

\[ b_2 > |A_2|/(1 - |B_2|) , \quad \text{so that} \quad b_2 > A_2 + B_2 b_2 . \]

Then if \( |d^2x/dt^2| < b_2 \), it follows that \( |d^2X/dT^2| < b_2 \). Thus, with these choices, the successive forward images of \( \Gamma_0 \) will be curves \( x_n = x_n(t) \) which converge uniformly to a limit, with both \( |dx_n/dt| \) and \( |d^2x_n/dt^2| \) uniformly bounded.

Now we can continue inductively. By successively differentiating the formula (26) we find formulas of the form

\[ \frac{d^kX}{dT^k} = A_k + B_k \frac{d^kx}{dt^k} , \]

where \( A_k \) depends not only on the iterated partial derivatives of \( T(t, x) \) and \( X(t, x) \) but also on the derivatives \( d^\ell x/dt^\ell \) with \( \ell < k \), and where

\[ B_{k+1} = B_k/D_T < B_k/(1 - \eta - b_1\eta) . \]

Thus, choosing \( \eta \) small enough so that \( B_k < \text{constant} < 1 \), we can find a suitable upper bound \( b_k \) for \( |d^kx/dt^k| \) which is preserved when we replace a curve \( \Gamma \) by \( f(T)(\Gamma) \). Thus, given any finite \( k \), we can choose \( \eta \) small enough so that the iterated forward images of a curve \( x = x(t) \) which satisfies the inequalities

\[ |d^\ell x/dt^\ell| \leq b_\ell \quad \text{for all} \quad \ell \leq k \]

will be a curve which satisfies these same inequalities.

To complete the proof of Theorem 8.9, we need the following.
**Lemma 8.10. A Derivative Inequality.** If a $C^2$-smooth function $x = x(t)$ satisfies uniform inequalities $|x(t)| < \alpha$ and $|d^2x/dt^2| < \beta$, then it follows that

$$|dx/dt| < \sqrt{2\alpha\beta}.$$ 

**Proof.** Suppose, for example, that the first derivative $x' = dx/dt$ satisfied $x'(0) \geq \sqrt{2\alpha\beta}$ with $x(0) \geq 0$. Using the lower bound $x''(t) \geq -\beta$ and integrating twice, we see that

$$x'(t) > \sqrt{2\alpha\beta} - \beta t \quad \text{and} \quad x(t) > \sqrt{2\alpha\beta} t - \beta t^2/2$$

for $t > 0$. In particular, substituting $t_0 = \sqrt{2\alpha/\beta}$, it would follow that $x(t_0) > \alpha$, thus contradicting the hypothesis. Other cases can be handled similarly. \hfill $\Box$

The proof of Theorem 8.9 concludes as follows. Again let $x_n = x_n(t)$ be the $n$-th forward image of $\Gamma_0$ under $f_\tau$. As $m$ and $n$ tend to infinity, the difference $x_n(t) - x_m(t)$ tends to zero, while the difference $x''_n(t) - x''_m(t)$ remains uniformly bounded. Thus it follows from Lemma 8.10 that the difference $x'_n(t) - x'_m(t)$ converges uniformly to zero. Similarly, it follows inductively that differences of higher derivatives converge to zero. This completes the proof that the limit curve $\Gamma_\tau$ is $C^k$-smooth for any specified $k < \infty$. Further details of the proof are not difficult. \hfill $\Box$

Note that this argument does not produce a $C^\infty$ curve, since we need to impose tighter and tighter restrictions on $f_\tau$ in order to get successive higher derivatives. The argument certainly does not produce a real analytic curve, which is what we would need in order to show that $\Gamma_\tau$ is contained in a Herman ring. We have no idea how to prove real analyticity, even assuming that the rotation number $\rho_\tau$ is Diophantine.\hspace{1em}10

**9 Open Problems.**

The results of this note leave a number of conjectures and open questions. Here is a brief list.

**Conjecture 9.1.** For any $f$-invariant elliptic curve $C \subset \mathbb{P}^2(\mathbb{C})$, the basin of attraction, consisting of all points whose orbits converge to $C$, is contained in the Julia set of $f$. (Intuitive proof: Otherwise the basin would have to contain an open set $U$ such that every sequence of iterates of $f$ on $U$ contains a subsequence converging to a constant $c \in C$. This looks very unlikely, given the fact that $f$ is highly expanding in directions tangent to $C$.)

The following two conjectures are closely related. Compare the discussion in Remark 4.3.

**Conjecture 9.2.** Such an attracting basin cannot contain any nonvacuous open set. In other words, the set of all points not attracted to $C$ is always everywhere dense.

**Conjecture 9.3.** Every invariant complex elliptic curve contains a repelling periodic point. (In all examples known to us there is a repelling fixed point.)

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\hspace{1em}10It is interesting to compare the boundaries of Siegel disks for rational maps of $\mathbb{P}^1$. These are simple closed curves in all known cases. They can never be real analytic, but in the non-Diophantine case they can be $C^\infty$-smooth. (Compare [ABC].) In the Diophantine case, such a boundary necessarily contains a critical point, and hence cannot be smooth. (See [Gh].)
Conjecture 9.4. In the space of complex Desboves maps with real coefficients, there is a subset of positive measure consisting of maps which have a cycle of attracting Herman rings. (Compare §8 and Example 5.4.)

There are also many questions where we have no idea what to guess.

- To what extent are maps with an attracting periodic orbit common in the space of all degree $d$ maps preserving a given elliptic curve? For example, do they form a dense open set?
- Can an invariant elliptic curve be a global attractor, with an attracting basin of full measure? We have constructed a number of examples where this seems to be true empirically; but how can one exclude the possibility of other attractors with basins of very small measure?
- Can a smooth real elliptic curve be a trapped attractor?
- What can one say about the dynamics when the elliptic curve has positive transverse Lyapunov exponent? Could such a map have an absolutely continuous invariant measure? Is it true that an elliptic curve can never be a measure-theoretic attractor when its transverse exponent is positive? (Compare Remarks 1.1 and 6.7)
- What other kinds of attractor can occur for a rational map with invariant elliptic curve? Can there be fractal attractors? Can there be a set of dense orbits of positive measure, or even of full measure? Can the Julia set have positive measure, even when it has no proper sub-attractors?

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