Self-organization of hierarchical structures in nonlocally coupled replicator models

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Abstract
We study a simple replicator model with non-symmetric and nonlocal interactions. Hierarchical structures with prey-predator relations are self-organized from a homogeneous state, induced by the dynamical instability of nonlinear interactions.
Ecological systems and evolution dynamics have been studied as examples of complex systems [1, 2]. The replicator models are often used to study biological evolution among mutually interacting species [3]. The time evolution of population $x_i$ of the $i$th species obeys an equation

$$\frac{dx_i}{dt} = x_i(f_i + \sum_j w_{i,j}x_j - c_0), \text{ for } i = 1, \ldots, N$$

(1)

where $N$ is the total number of species, $f_0$ is the natural growth rate of the $i$th species, $w_{i,j}$ denotes the strength of the interaction from the $j$th species to the $i$th species, $f_i = f_0 + \sum_j w_{i,j}x_j$ is the growth rate for the $i$th species, and $c_0 = \sum_{i=1}^{N} f_i x_i / \sum_{i=1}^{N} x_i$ is the average value of the growth rate. The sum of $x_i$ is conserved in the time evolution of Eq. (1). If the sum is assumed to be 1, $x_i$ has a meaning of the population ratio of the $i$th species. The above equation implies that the populations of the species which have the growth rate larger than the average value increase. If $w_{i,j}$'s are all zero, only the species with the largest natural growth rate survives. It implies the survival of the fittest species. If $w_{i,j}$'s are not all zero, the coexistence of several species is possible. Complex dynamics and statistical properties of the replicator models with random interactions have been studied [4]. Steady evolution called "Red Queen" evolution can be modeled with this type of equation [5]. We consider the case of $f_0 = \text{const.}$ in this work, that is, all species are equivalent by nature in the evolution dynamics.

The population dynamics using Eq. (1) is closely related with the Lotka-Volterra type equations, which have been more intensively studied in ecological systems [6]. In the usual Lotka-Volterra models, the interaction strength $\{w_{i,j}\}$'s are usually assumed to be constant. They are usually non-symmetric, that is, $w_{i,j} \neq w_{j,i}$. In the prey-predator relation, where the $j$th species is a prey of the $i$th species and the $i$th species is a predator of the $j$th species, $w_{i,j} > 0$ and $w_{j,i} < 0$. In the competitive relation between two species with equivalent strength, the interactions may be symmetric as $w_{i,j} = w_{j,i} < 0$. However, we can consider some cases where the interaction strengths change dynamically. For example, there are some models, in which $w_{i,j}$ is a function of the populations $x_i$ and $x_j$. In the population dynamics of trees in forests, competition between trees is not symmetric in general. Larger trees prevent the growth of lower trees, but the lower trees do not seriously affect the larger trees. Assuming that $x_i$ is the height of a tree at the $i$th position, Yokozawa and Hara proposed a model, in which $W(x_i, x_j) = w_{i,j}x_j$ is expressed as $W(r) = r^3$ for $0 < r < R_c$ and $W(r) = R_c^3$ for $r > R_c$, where $r = x_j / x_i$. [7] We proposed a similar form of nonlinear interactions expressed as

$$w_{i,j} = \begin{cases} 0, & \text{for } r < d_1, \\ a_1(r - d_1), & \text{for } d_1 \leq r < d_2, \\ a_2(r - d_0), & \text{for } d_2 \leq r < d_3, \\ a_3(r - d_4), & \text{for } d_3 \leq r < d_4, \\ 0, & \text{for } d_4 \geq r, \end{cases}$$

(2)
where \( r = x_j/x_i, \) \( d_1 = 1/d_4, d_2 = 1/d_3, d_1 < d_2 < d_0 < 1 < d_3 < d_4, \) and \( a_1 > 0, a_2 < 0, a_3 > 0. \) The interaction \( w_{i,j}(r) \) is a continuous and piecewise linear function of the ratio \( r = x_j/x_i. \) This form of interaction seems to be peculiar, but it is one of the simplest forms of continuous functions, by which both the mutually equivalent competitive relation and the prey-predator relation can be described. The interaction is competitive and equivalent, i.e., \( w_{i,j} = w_{j,i} = a_2(1 - d_0) < 0, \) when the population sizes of the \( i \)th and \( j \)th species are equal. Even if the population sizes between the two species are not completely equal but are nearly equal \((d_0 < r < (1/d_0)), \) the interactions are competitive, i.e., \( w_{i,j} < 0, w_{j,i} < 0. \) If the ratio \( r = x_j/x_i \) of the population sizes is even smaller and satisfies \( d_1 < r < d_0, \) the \( j \)th species becomes a prey of the \( i \)th species (that is, the \( i \)th species is a predator of the \( j \)th species), i.e., \( w_{i,j} > 0, w_{j,i} < 0. \) If the ratio \( r \) of the population sizes is even larger and satisfies \((1/d_0) < r < d_4, \) the \( i \)th species becomes a prey of the \( j \)th species (that is, the \( j \)th species is a predator of the \( i \)th species), i.e., \( w_{i,j} < 0, w_{j,i} > 0. \) If the ratio \( r \) is too large \((r > d_4) \) or too small \((r < d_1), \) the interaction becomes negligible, i.e., \( w_{i,j} = w_{j,i} = 0. \) The ecological relations change dynamically with the ratio of the population sizes in our model ecological system. Parameter values of \( a_1 = 2, a_2 = 2, d_1 = 3, d_2 = 1, d_3 = 2, d_4 = 3, a_2 = 3, a_1 = a_2(d_2 - d_0)/(d_2 - d_1) \) and \( a_3 = a_2(d_0 - d_3)/(d_2 - d_3) \) are used in the numerical simulations. A homogeneous solution \( x_i = 1/N \) for every \( i \) is a solution of Eq. (1), owing to the symmetry of the coupled equations. However, the homogeneous solution is not always stable. The present author, and Yokozawa and Hara found that layered structures are self-organized in a globally coupled model and a locally coupled model with the nearest and next-nearest neighbor interactions, as a result of the instability of the homogeneous solution.\(^4,5\)

In this paper, we study a nonlocally coupled model based on Eq. (1) with nonlinear interactions of the form Eq. (2). The position of the \( i \)th element is located in a one-dimensional lattice or randomly distributed in two dimensions. We assume further that the interaction \( w_{i,j} \) takes the value of Eq. (2) only if the distance between the \( i \)th and \( j \)th elements is smaller than a value determined by a function \( f(\bar{x}), \) where \( \bar{x} \) is the average population size \((x_i + x_j)/2. \) We use a simple function \( f(\bar{x}) = \alpha \bar{x} \) in numerical simulations. The function \( f(\bar{x}) \) expresses the range of the interaction, and the function \( f(\bar{x}) = \alpha \bar{x} \) implies that the interaction range increases in proportion to the population size.

Firstly, we study a one-dimensional model. Each species is located at \( i, \) where \( 1 \leq i \leq N. \) The homogeneous solution is \( x_i = x_s = 1/N. \) The interaction strength \( w_{i,j} \) takes the value of \( a_2(1 - d_0) \) for a pair of the same population size. The linearized equation for a small perturbation \( \delta x_i = x_i - x_s \) around the homogeneous solution obeys

\[
\frac{d\delta x_i}{dt} = x_s \left\{ \sum_j a_2(2 - d_0)\delta x_j - a_2 \sum_j \delta x_j \right\}, \text{ for } i = 1, \ldots, N, \tag{3}
\]

where the sum is taken for the range satisfying \( |j - i| < \alpha/N. \) The eigenvalue of the linearized equation can take positive values for \( \alpha/N > 1. \) For example, if the
site number satisfying $|j - i| < \alpha/N$ is 5, the eigenvalue $\lambda_k$ for the wavenumber $k$ is expressed as $\lambda_k = x_s a_2 \{(2 - d_0)(1 + 2 \cos k + 2 \cos 2k) - 5\}$, and therefore $\lambda_k > 0$ for $\cos^{-1}\{(−1 + \sqrt{5} + 20/(2 - d_0))/4\} < k < \pi$. Under the condition, the homogeneous state becomes unstable. We have performed numerical simulations for $N = 200$. The initial condition was $x_i = 1/N(1 + \delta x_i(0))$, where $\delta x_i(0)$ was chosen as a random number between -0.01 and 0.01. Figure 1 displays the population size $x_i$ for (a) $\alpha = 180$, (b) $\alpha = 300$, (c) $\alpha = 1000$, (d) $\alpha = 4000$. Solid lines denote pairs with prey-predator relations.

![Figure 1: Profiles of population sizes $x_i$ for a one-dimensional model Eq. (1) with $N = 200$ and (a) $\alpha = 180$, (b) $\alpha = 300$, (c) $\alpha = 1000$, (d) $\alpha = 4000$. Solid lines denote pairs with prey-predator relations.](image-url)
the competition among the local winners like a tournament. For $\alpha = 4000$, there appears an element which dominates the whole region, and a hierarchical structure from top to bottom is created. Which element dominates the whole region depends on the initial conditions.

Next, we consider a two-dimensional model. The position of the $i$th element is randomly distributed inside a circle of radius 10. The population size at the

Figure 2: Hierarchical structure for Eq. (1) with $N = 400$ in two dimensions. Each element is randomly distributed in a circle of radius 10. The parameter value of $\alpha = 800$. Figure 2(a) is the network with larger size populations, which satisfies $x_i > 0.005$, and (b) is the network with the smaller size populations. The area of the square at each site is proportional to $x_i$. Figure 2(c) is a histogram of the population size.$i$th element is denoted as $x_i$. The system size is $N = 400$. The initial conditions are $x_i = 1/N(1 + \delta x_i(0))$, where $\delta x_i(0)$ is a random number between -0.01 and 0.01. As a result of the time evolution by Eq. (1), a two-dimensional hierarchical structure is naturally created. As the parameter value $\alpha$ is increased, we have observed development of hierarchical structures as in the one-dimensional model. Figure 2 displays a developed hierarchical network for $\alpha$ is 800. The prey-predator relations are displayed in this figure. To show the network clearly, we have classified the set of $i$ into two groups. Figure 2(a) is a network for larger size populations, which satisfies $x_i > 0.005$, and Fig. 2(b) is a network for the smaller size populations, which satisfies $x_i < 0.005$. The population size $x_i$ is expressed
by the area of the square located at the \( i \)th position. The elements, which have larger populations, dominate the larger regions. The average number of preys for each element is 4.3 in this simulation. Figure 2(c) displays a histogram of population size. It is seen from this histogram that a layered structure with 7 levels is created.

To summarize, we have proposed a nonlocally coupled replicator model for the self-organization of hierarchical structures. The interaction range was assumed to be proportional to the population size, and the nonlinear interactions between two species are assumed to depend on the ratio of the population sizes. Owing to the two assumptions, a hierarchical structure of the interaction network is self-organized. The parameter \( \alpha \) determines the level number of hierarchical structures. For large \( \alpha \), a self-similar-like hierarchical structure is created, in which the population sizes and interaction ranges increase geometrically as the level is increased. The stationary solutions to Eq. (1) are not unique as shown in a globally coupled model \footnote{8}, however, similar forms of hierarchical structures were obtained from different initial conditions. If the initial condition is completely localized as \( x_i = 1 \) for \( i = N/2 \) and \( x_i = 0 \) for the other \( i \), the localized state is maintained in the time evolution of Eq. (1), since new populations cannot be born from zero. As a natural modified model, a diffusion process may be introduced in the population dynamics as

\[
\frac{dx_i}{dt} = x_i \left( \sum_j w_{i,j} x_j - c_0 \right) + D(x_{i+1} - 2x_i + x_{i-1}), \quad \text{for } i = 1, \ldots, N, \quad (4)
\]

where \( D \) is a diffusion constant. The diffusion process corresponds to the migration in ecosystems. New populations are migrated at the sites where \( x_i = 0 \) originally, and then the localized state becomes unstable. We have checked that similar hierarchical structures are naturally created from the localized initial conditions even for very small \( D \). We have used a special form of interactions. However, the dynamical instability of the homogeneous state is due to the negative derivative of \( dw_{i,j}(r)/dr \) at \( r = 1 \) and other forms of interactions with the same characteristics can induce similar hierarchical structures. The self-organization of the hierarchical structure owing to mutual interactions is suggestive of the formation of complex networks in ecosystems, economic and social systems \footnote{9}.

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