INTRAClusters MEDium REHEATING BY RELATIVISTIC JETS

MANEL PERUCHO, VICENT QUILIS, AND JOSÉ-MARÍA MARTÍ
Departament d’Astronomia i Astrofísica, Universitat de València, c/Dr. Moliner 50, E-46100 Burjassot (València), Spain
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ABSTRACT

Galactic jets are powerful energy sources reheatting the intracluster medium in galaxy clusters. Their crucial role in the cosmic puzzle, motivated by observations, has been established by a great number of numerical simulations excluding the relativistic nature of these jets. We present the first relativistic simulations of the very long-term evolution of realistic galactic jets. Unexpectedly, our results show no buoyant bubbles, but large cocoon regions compatible with the observed X-ray cavities. The reheating is more efficient and faster than in previous scenarios, and it is produced by the shock wave driven by the jet, that survives for several hundreds of Myr. Therefore, the X-ray cavities in clusters produced by powerful relativistic jets would remain confined by weak shocks for extremely long periods and their detection could be an observational challenge.

Key words: galaxies: active – galaxies: jets – hydrodynamics – relativistic processes – shock waves – X-rays: galaxies: clusters

Online-only material: color figures

1. INTRODUCTION

Galaxy clusters are formed by dark matter and gas. This last component appears in the form of galaxies and a diffuse hot gas filling the space amid them—the intracluster medium (ICM). The basic laws of physics predict that huge amounts of this gaseous component—ICM—should cool due to bremsstrahlung radiation and fall onto the central galaxies in the clusters. These flows of cold gas would eventually be intimately related with crucial processes in the galaxy formation, like, for instance, the star formation history in galaxies. However, these flows—the so-called cooling flows—have not been observed in most of the clusters, or when observed, they are not as important as expected. In order to reconcile the theoretical results with the observations, several physical mechanisms have been invoked, the most widely accepted being the reheating of the ICM by the active galactic nucleus (AGN) feedback (Fabian 1994; McNamara & Nulsen 2007).

The state-of-the-art picture of the AGN feedback is underpinned on the idea that galactic jets can transport energy from the very center of the galaxy out to the cluster scales. These energy injections would inflate bubbles whose evolution would have two well-differentiated phases: first, a shock-dominated supersonic phase, followed by a second subsonic phase when the bubbles inflated by the jets would be buoyant in the ICM (Cattaneo et al. 2009).

The buoyant bubbles are unstable, due to Rayleigh–Taylor and Kelvin–Helmoltz instabilities, when interacting with the surrounding ICM, leading to a mixture of the hot gas locked in the bubble with the environment. Besides, an additional mixing is produced at the turbulent wake created by the buoyant bubbles rising up in the cluster potential well. All this mixing produces a net gain of internal energy of the ICM resulting in an efficient feedback mechanism able to stop or delay the cooling flows (see, e.g., Churazov et al. 2001; Quilis et al. 2001; Brüggen & Kaiser 2002; Churazov et al. 2002; Ruszkowski & Begelman 2002; Birzan et al. 2004; Dalla Vecchia et al. 2004; Roychowdhury et al. 2004; Brighenti & Mathews 2006; Sternberg & Soker 2008; De Young 2010). The idea that the radio lobes reach pressure equilibrium with their environment in a relatively short time supports the model of buoyant motion of the bubbles inflated by the jets (McNamara & Nulsen 2007). However, the observations of shocks in several sources such as Hercules A (Nulsen et al. 2005), Hydra A (Simionescu et al. 2009), MS0735.6+7421 (McNamara et al. 2005), or HCG 62 (Gitti et al. 2010) may require the relevance of the subsonic buoyant phase to be reconsidered, especially when observational evidence (Kraft et al. 2007; Croston et al. 2007) and numerical simulations (Perucho & Martí 2007; Bordas et al. 2011) have shown that even very modest energy injections—low-power FRI jets—with ages $\gtrsim 10^7$ yr still present relatively strong shocks.

The AGN feedback scenario has mainly been established by a great number of numerical simulations studying the long-term evolution of jets (e.g., Churazov et al. 2001; Quilis et al. 2001; Brüggen & Kaiser 2002; Reynolds et al. 2002; Omma et al. 2004; Omma & Binney 2004; Zanni et al. 2005; Brighenti & Mathews 2006; Vernet et al. 2006, 2007; Cattaneo & Teysier 2007; Brüggen et al. 2007, 2009; Binney et al. 2007; O’Neill & Jones 2010). In these works, the input of jets was modeled by injecting mass, momentum, and energy into a few computational cells with a huge size (for jet scales) and with low (i.e., non-relativistic) flow velocities and temperatures imposed by the Newtonian approach. These inherent constraints could have direct implications on the evolution of the simulated jets since, in order to match the typical momentum and energy fluxes, the jets are set up with unrealistic opening angles, radii, and flux masses when compared with observations. This could be the reason leading, in general, to the formation of weak shock waves (with Mach numbers $M_s \lesssim 5$) and, as a consequence, to an early transition to the subsonic phase in almost all of the simulations performed until now.

In this paper we present, for the first time, the results of a set of very long-term axisymmetric FRII-like jet simulations evolved using a fully relativistic description of the fluid dynamics and thermodynamics, also including a relativistic equation of state. Our approach allows the simulations to reconcile the inferred momentum and energy fluxes of observed jets with reasonable values of the jet flow velocities, opening angles, and mass fluxes. The use of the relativistic equation of state accounts consistently for the relativistic character of electrons in the jet...
and, to a lesser extent, in the cocoon, and the non-relativistic behavior of protons. Also our relativistic models correctly describe, by construction, the deceleration of the relativistic flow and the internal and kinetic energy fluxes across the jet terminal shock that govern the effective energy flux into the cocoon.

2. SIMULATIONS

2.1. Setup

We simulate the jets as energy injections in a realistic environment at a distance as close as 1 kpc to the nucleus of the source and follow the evolution up to several hundreds of kiloparsecs. The jets are injected with an initial radius of 100 pc with flow velocities ranging from \(v_{j} = 0.9 \, c\) to \(v_{j} = 0.99 \, c\), and typical density ratio between the jet material and environment of \(\rho_{j}/\rho_{a} = 5 \times 10^{-4}\). The jets are fed by the injection of energy during 50 Myr (16 Myr in one model), when they are switched off so as to mimic a duty cycle event. The total injected energies range from \(3 \times 10^{59}\) to \(10^{61}\) erg, depending on the jet model (see solid black lines in Figure 3). Our best numerical resolution is \(50 \times 50\) pc. A complete list of all relevant parameters of the simulations is given in Table 1.

All the simulations performed are two-dimensional axisymmetric. The jets are injected in a computational domain filled with an ambient in hydrostatic equilibrium, which is formed by primordial gas with a King-like density profile considering the elliptical galaxy—origin of the jet—and the galaxy cluster. The density profile parameters have been fixed by fitting the X-ray data of the source 3C 31 (Hardcastle et al. 2002). The ambient density at the injection point is 0.1 particles per cubic centimeter. The dark matter halo follows an NFW density profile (Navarro et al. 1997). All these parameters represent a moderate-size galaxy cluster with mass \(10^{14} \, M_{\odot}\) and \(\sim 1\) Mpc virial radius.

The numerical grid is structured as follows: in the radial direction, a grid with the finest resolution extends up to 50 kpc (Model J1) or 100 kpc (Models J2, J3, J4). An extended grid with decreasing resolution was added up to 1 Mpc. The time step during the first part of the simulations, when the jet is still active, was 50–100 years. The boundary conditions in the simulations are reflection at the jet base, to mimic the presence of a counterjet, reflection at the jet axis, and outflow at the end of the grid in the axial and radial directions.

The simulations presented in this paper use the finite-volume code Ratpenat, which solves the equations of relativistic hydrodynamics in conservation form using high-resolution shock-capturing methods. Ratpenat is a hybrid parallel code—MPI + OpenMP—extensively and intensively tested (e.g., Perucho et al. 2010). The code includes the Synge equation of state (Synge 1957) with two populations of particles, namely leptons (electrons and positrons) and baryons (protons). In these simulations, cooling has not been taken into account, as the typical cooling times in the environment are long compared to the simulation times (see Figure 10 in Hardcastle et al. 2002).

2.2. Results

The dynamics of the system are dominated by the jet active phase, where jet head velocities range from 0.01 \(c\) to 0.06 \(c\), consistent with different estimates of the advance velocities of active radio sources (0.02–0.2 \(c\); Carilli & Barthel 1996), implying Mach numbers between 10 (J3) and 30 (J2). The evolution of the supersonic jet generates a characteristic morphology: (1) a bow shock that acts on the ambient medium, (2) a terminal or reverse shock at the head of the jet where the flow is decelerated, and (3) the cocoon inflated by the shocked jet particles and polluted with shocked ICM stirred via instabilities arising at the contact discontinuity between both media, typically hotter and underdense compared with the ambient. After the switch-off, due to the short timescales needed by the relativistic fluid to reach the jet terminal shock, the jet head velocities quickly drop to values \(\sim 10^{-3} \, c\) making the bow shock approach sphericity very fast. During this phase, the Mach numbers of the bow shock fall from \(\sim 10\) to values between 1 and 2.

Figure 1 shows four snapshots of model J2 at representative phases of its evolution (see Section 3.1). The jet is seen in the second panel (also in the first one, although less clearly due to the small size of the system) as a blue or green line on the axis in the density and temperature frames, respectively. The terminal shock at the head of the jet is also seen in this panel, especially in the temperature distribution, as the dark red (saturated) region at the end of the jet. After the jet switch-off, the channel opened by the jet is still seen on the axis in the third and fourth frames although the jet terminal shock has already disappeared. In the four panels, the cocoon is the bluish turbulent region in the density frames (reddish region in the temperature ones), whereas the shocked ambient medium fills the region between the cocoon and the bow shock (yellow/orange/red region in the density frames; light blue region in the temperature frames). The density is low (i.e., smaller than the density in the original unperturbed medium) in the cocoon and high in the shocked ambient region.

The key features that differentiate the simulated jets are the injection power and the duration of the active phase. The location of the bow shock at a given time is largely dependent on these parameters and hence the distance at which the energy is deposited. The morphology of the cocoon also changes for the different models, with the most powerful jet (J2) creating a large cavity and the less powerful one (J3) having its particles distributed closer to the source. The gross properties of models J1 and J4, with the same power and different composition, are very similar.

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Table 1

| Model | Velocity (c) | Density (g cm\(^{-3}\)) | \(X_{e}\) | \(L_{k}\) (erg s\(^{-1}\)) | Max. Resol. (pc cell\(^{-1}\)) | \(t_{\text{off}}\) (Myr) |
|-------|--------------|--------------------------|--------|-----------------|-----------------|------------|
| J1    | 0.9          | \(8.3 \times 10^{-29}\)  | 1.0    | \(10^{45}\)     | 50              | 50         |
| J2    | 0.984        | \(8.3 \times 10^{-29}\)  | 1.0    | \(10^{46}\)     | 100             | 50         |
| J3    | 0.9          | \(8.3 \times 10^{-30}\)  | 1.0    | \(10^{44}\)     | 100             | 50         |
| J4    | 0.9          | \(8.3 \times 10^{-29}\)  | 0.5    | \(10^{45}\)     | 100             | 50         |

Note. From left to right the columns give the model, the injection velocity, the injection density, the leptonic number, the jet power, the maximum resolution, and the switch-off time.
In all the cases studied, the late stages of the simulations show a cocoon composed by jet and ICM-shocked particles completely mixed, forming a low-density region surrounded by the denser shocked ICM, with temperatures within the cocoon not larger than one order of magnitude of those in the shocked medium. All these features postulate the cocoon as an excellent candidate precursor of the X-ray observed cavities. Surprisingly, in all our simulations, covering two orders of magnitude in jet power and a factor of 30 in total injected energy, the pressure jumps between the shocked and the unperturbed ICM persist along the whole simulation, and no buoyant stage is reached. Figure 2 shows the X-ray emission obtained from one snapshot in simulation J2 compared to a real observation.

The minimum cooling times have been calculated at different times during the simulation to check the consistency of the results, taking into account that cooling has not been included. After the medium is perturbed by the jet, minimum cooling times are longer than the simulated ones by more than a factor 10 during the active phase, and by more than 100 or 1000 times the simulated time after the jet switch-off. Significant changes in the results presented in this work are thus not expected if the cooling terms are included.

3. DISCUSSION

3.1. Cavity Evolution

The long-term evolution of the cocoons in our numerical simulations, within the shock-dominated supersonic phase, can be interpreted as undertaking three stages: (1) a short one-dimensional phase, in which the cocoon expansion is governed by the one-dimensional evolution of the jet (up to $t \approx 1.8$ Myr in model J2), (2) a genuinely multidimensional phase in which the cocoon expansion is driven by a decelerating jet as a result of the multidimensional effects affecting the jet propagation, and (3) a Sedov phase (starting at $t = 16$ Myr in model J2), in which the cocoons expand passively once the energy injection of the jet...
has ceased. In this last phase, the expansion on an atmosphere decreasing in density is expected to produce a faster expansion of the cocoon (and consequently a faster pressure decrease) than in the pure Sedov case (constant ambient density). The first two phases are typical of the propagation of supersonic jets and are described in, e.g., Scheck et al. (2002). The third phase is new and follows from the jet switch-off.

Figure 1 shows four snapshots of model J2 at representative stages of its evolution: one-dimensional (first panel), multidimensional (second panel), and Sedov phases (third and fourth panels). In a homogeneous ambient, during the so-called one-dimensional phase, the jet propagates at its estimated one-dimensional speed (Martí et al. 1997). The propagation efficiency of the jet during this phase is maximum and the cocoon inflates at its smallest rate. In the present simulations, the evolution in an atmosphere decreasing in density accelerates the jet propagation speed beyond the one-dimensional estimate and makes the cocoon expansion faster. The onset of the multidimensional phase is triggered by multidimensional, dynamical processes taking place close to the jet’s head. During this phase, the generation of large vortices at the jet/shocked ambient interface (a pair of such vortices is seen at the jet’s head in the density map of the second panel) decelerates the jet, increasing the flux of jet material into the cocoon. As a result, the cocoon expands at a fast rate (helped also by the decreasing ambient density). The third and fourth panels in Figure 1 are representative of the Sedov phase, once the jet has been switched off. Consistently, the jet loses its hot spot (the impact point of the jet on the ambient medium), still seen in the second panel, and the channel opened by the jet starts to be refilled. During this phase, the cocoon continues its expansion (at a smaller rate than in the previous phase since the injection of energy has ceased) and tends to sphericity (since there is no longer any extra momentum transfer in the axial direction).

The temperature is quite homogeneous within the cocoon, and almost constant with time as long as there is a continuous and constant matter and energy injection through the jet. Once the jet is switched off, the cocoon starts to cool down (see the evolution of the cocoon temperature between the third and fourth panels).

At late stages, the velocity field in the cocoon is dominated by the overall cocoon expansion speed ($\leq 3 \times 10^{-3} c$) and the turbulent motions on smaller scales, with local values of the order of 0.04 $c$.

The Begelman–Cioffi model (Begelman & Cioffi 1989; BC) describes the expansion against a uniform ambient medium of the overpressured cocoons raised by the continuous injection of energy from a supersonic jet. In this model the axial expansion of the cocoon (i.e., along the jet) proceeds at the (constant) advance speed determined by the jet, whereas the sideways growth follows from the assumption of the evolution being mediated by a strong shock.

The long-term evolution of the cocoons in our numerical simulations can be consistently described within the so-called extended Begelman–Cioffi model (Scheck et al. 2002; Perucho & Martí 2007; eBC) that allows for a power-law dependence of the jet advance speed with time and a non-uniform ambient medium. In addition, the model can also describe the passive (supersonic) expansion of the cocoon once the jet has ceased its activity (Sedov phase).

In the eBC model, if the advance speed of the bow shock along the axial direction, $v_c$, and the ambient density, $\rho_a$, follow the power laws $v_c \propto \rho_a^\alpha$, $\rho_a \propto r^\beta$, then the cavity’s transversal dimension, $R_c$, and pressure, $P_c$, follow:

$$R_c \propto t^{\frac{1-\beta}{4+\alpha}}, \quad P_c \propto t^{\frac{2(2-\alpha)(2+\beta)}{4+\beta}}. \quad (1)$$
These time dependencies are valid as long as there is a constant injection of energy in the cocoon. Once the jet is switched off (Sedov phase), the evolution follows
\[ R_c \propto t^{\frac{1-\alpha}{\beta}}, \quad P_c \propto t^{\frac{2-\alpha}{1+\alpha}} \]
for the pure Sedov expansion phase, recovered when \( \alpha = -3/5 \) and \( \beta = 0 \), for which \( R_c \propto t^{2/5} \) and \( P_c \propto t^{-6/5} \).

Table 2 displays the parameters \( \alpha \) (derived from the simulations) and \( \beta \) for the three phases of each simulation, and the corresponding exponents for the time dependence of \( R_c \) and \( P_c \), both from the simulations and from the eBC model. According to the data displayed in this table, we can conclude that the eBC model describes consistently the long-term evolution of the cocoons along phases (1) and (2). Concerning the Sedov phase, let us note first that our model produces a faster expansion (time exponent for \( R_c \approx 3/5 \) instead of \( 2/5 \)) and a faster pressure decrease (time exponent for \( P_c \approx -7/5 \) instead of \(-6/5\)), as expected. However, it must be noted that the exponents derived from the simulations reinforce this tendency. The discrepancies between the expected and the obtained time dependencies in this last phase have a clear dependence on jet
The shock in model J2 has processed about 9\% of the ambient medium at the shock speed (a substantial fraction of the point, let us note that the heating front propagates through the ambient medium in the heating process. With respect to the first very high in two aspects, namely the amount of ambient medium at the onset of the Sedov phase (\(t \approx 1.8 \text{ Myr}\)), 1.1 \times 10^7 \text{ kpc}^3 at the onset of the Sedov phase (\(t \approx 16 \text{ Myr}\)), and 0.37 Mpc\(^3\) at the end of the simulation (\(t \approx 160 \text{ Myr}\)).

The transfer of energy to the ambient medium is also very efficient. Indeed, the energetic balance of our simulations (Figure 3) shows that between 95\% and 97\% of the injected energy by the jet is instantaneously transferred to the ambient medium through shock-heating, mixing, and acceleration. The small residual is invested on gaining potential energy or kept by the jet particles. By the end of our simulations, between 10\(^{11}\) and 10\(^{13}\) \(M_\odot\) of ICM gas have been heated up by the shock, depending on the total energy injected during the active phase, in agreement with constraints imposed by observational data (McNamara & Nulsen 2007). Only a small fraction of the reheated ICM gas—from 0.1\% to 1\%—is mixed by instabilities arising at the contact discontinuity between the shocked ambient and the shocked jet fluid. Therefore, the bulk of the heating comes from the action of the shock; mixing with the jet material is negligible from the energetic point of view.

Figure 4 shows the energy per particle inside the shocked region versus time for all four simulations. The energy per particle, including the jet and ambient components, inside the bow shock is always over 1 keV for J1, J2, and J4, whereas it falls below this value after \(\simeq 10^8\) yr in the J3 case. Any effective reheating mechanism able to stop the cooling flows would require energies per particle \(\sim 1\) keV (McNamara & Nulsen 2007). Figure 5 shows the average internal energy per unit volume versus distance to the source at different times, for the case of J2. The plot reveals where the energy is deposited.

\[\text{Figure 4. Energy per particle inside the bow shock vs. time for the four simulations. J1 is represented by red, J2 by black, J3 by yellow, and J4 by blue. (A color version of this figure is available in the online journal.)}\]

\[\text{Figure 5. Average internal energy density vs. radius from the nucleus for simulation J2, at different times. The blue solid line is calculated at } t = 1 \text{ Myr, the green dotted line at } t = 15 \text{ Myr, the blue dashed line at } t = 50 \text{ Myr, and the red solid line at } t = 180 \text{Myr. (A color version of this figure is available in the online journal.)}\]

The values at small radii at the smaller times (mainly 1 and 15 Myr) are influenced by the elongated shape of the bow shock. When the bow shock becomes closer to sphericity at later times, the energy density has its maximum in a wide shell behind the shock front. These facts confirm that the bow shock dominates the energy deposition during the whole evolution. The heating of the cooling region (\(\simeq 20\) kpc; Hardcastle et al. 2002) is very fast (\(< 1\) Myr). It is also remarkable that, after 50 Myr, the energy density falls below the original one. In the case of J2, the injection time was fixed to be 16 Myr, implying that the simulation has been run for \(\simeq 12\) times the active time. Taking into account that the heating mechanism is very fast and acts mainly at the bow shock, as the shock propagates outward, the central regions cool down due to expansion. This fast cooling is the reason why slower heating mechanisms are favored in the literature (Omma & Binney 2004). Nevertheless, there are two aspects to be taken into account: (1) the gas in the inner region is still expanding and (2) considering that this activity period has only implied the injection of \(\simeq 2 \times 10^5 M_\odot\) (which does not represent a large amount of material out of the total amount of matter and energy expected to be present in the surroundings of AGNs), new periods of activity would be expected to occur more often than every 16 Myr–180 Myr (see, e.g., Fabian et al. 2006). We note that even short periods of activity (\(< 1\) Myr) with the same power are enough to heat and empty the ambient inside the cooling region.

The moderate-size galaxy cluster considered in our simulations, with mass \(10^{14} M_\odot\) and 1 Mpc virial radius, does favor the persistence of the bow shock generated in the expansion of the cavities. However, a 10 times more massive cluster with an average density (and pressure) 10 times larger will reduce the volume processed by the shock by the same factor or, equivalently, by roughly a factor of two per spatial dimension. Moreover, large changes in the processed mass are not expected because of the denser ambient medium. Finally, the same amount of injected energy acting on a similar amount of particles would lead to similar values of energy per particle.

\[\text{3.3. Jet/Cavity Energy Balance}\]

The energy injected by the jet is invested primarily in inflating the cavity against the ambient medium and heating the ambient gas remaining within it. Other contributions, such as, e.g., the kinetic energy transferred to the ambient, the change in the
potential gravitational energy of the pushed-aside material, and the energy kept by the jet particles, are neglected in the jet/cavity energy balance estimates in real sources. The energy invested in inflating the cavity is the \( pV \) expansion work exerted on the ambient. It is usually estimated from the volume of the cavity and the average pressure surrounding it. In the case of the cluster MS 0735.6+7421 (McNamara et al. 2005), where the cavities are roughly 200 kpc in diameter and the surrounding pressure is \( 6 \times 10^{-11} \text{ erg cm}^{-3} \), the work required to inflate each cavity against this pressure is \( pV \approx 10^{61} \text{ erg} \). The internal energy in the cavity, i.e., the second term in the jet/cavity energy balance, is usually estimated as being a few times the \( pV \) term (three times in the case of the MS 0735.6+7421 cluster).

Our simulations allow for a check of the hypothesis below the jet/cavity energy balance estimates summarized in the previous paragraph. First of all the results shown in Figure 3 confirm that the kinetic energy in the ambient gas, the change in the potential gravitational energy, and the energy kept by the jet particles are negligible, contributing less than 10% to the global energetics. Now, the expansion work of the cavity can be approximately accounted for through estimates of the cocoon volume and the average pressure of the original ambient medium swept by the jet. For the model J2 (\( t = 180 \text{ Myr} \)), the volume of the cocoon is \( \approx 3.4 \times 10^{7} \text{ kpc}^{3} \) (i.e., about 400 kpc of effective diameter), whereas the averaged pressure is \( \approx 3 \times 10^{-13} \text{ erg cm}^{-3} \) (200 times the pressure used in the MS 0735.6+7421 calculation). The resulting work is \( pV \approx 3 \times 10^{59} \text{ erg} \). Finally, the average internal energy density in the cavity is estimated to be \( 10^{-12} \text{ erg cm}^{-3} \). With these numbers, the minimum total energy needed to inflate one of the cavities in simulation J2 is \( 1.3 \times 10^{60} \text{ erg} \), in good agreement with the total energy injected by the jet (\( 5 \times 10^{59} \text{ erg} \)), reflecting the consistency of our analysis. Finally, as a by-product, we note that our result confirms the factor of three between the internal energy stored in the cavity and the expansion work assumed in the case of the MS 0735.6+7421 cluster, but now under very different conditions: in a two orders of magnitude lighter cluster and for a total injected energy 10 times smaller.

### 3.4. Possible Three-dimensional Effects

We must make a final comment on the two-dimensional nature of the simulations, for it could be seen as an important limitation in our conclusions. In the long term, the evolution of the cavity is driven by its internal pressure, which (1) depends basically of the total energy injected in the cocoon and (2) tends to isotropize the cocoon on a characteristic timescale of its internal sound speed (of the same order or larger than the overall shock advance speed). Both aspects tend to reduce the importance of the early three-dimensional effects in the long-term evolution of cavities, making the conclusions derived from our present axisymmetric simulations more reliable. Moreover, the ambiguity in the initial condition parameter space for the jet and ambient could lead to results with larger dispersion than those arising from possible three-dimensional effects.

### 4. CONCLUSIONS

We have presented the first simulations on the impact of relativistic AGN jets in the heating of the ICM. Our simulations cover the longest spatial and temporal scales considered up to now and additionally, due to their relativistic character, also for the first time, allow for a consistent description of the jets (that have consistent values of the jet flow velocities, radii, opening angles, and mass, momentum, and energy fluxes) within the cluster heating scenario.

Our simulations show that heating by AGN jets is mainly driven by shock heating, resulting in a very fast and efficient process (more than 95% of the energy injected through the jets is transferred to the ambient). As a by-product, our simulations also show that although buoyant cavities could be the very final stage of radio-galactic relics, they are not the main actors in the ICM reheating.

As a result of our simulations, we suggest the idea that most of the observed X-ray cavities are confined by shock waves, though very weak. Although it cannot be concluded that the presence of shock-confined cavities implies the relativistic nature of jets, such shocks in our results last for much longer periods than in previous—Newtonian—works. The confirmation of the existence of such weak shock waves could be an observational challenge that would have crucial implications for our understanding of the galaxy formation and evolution paradigm.

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