Regulation of bi-directional movement of single kinesin-5 Cin8 molecules

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Members of the kinesin-5 family of motor proteins are conserved among eukaryotes, from yeast to humans. Among the cytoskeletal motors, kinesins, myosins and dyneins, kinesin-5 motors are the only ones that function as bipolar homotetramers, with two pairs of catalytic domains located at opposite ends of the active complex.1,2 This special architecture is thought to enable kinesin-5 motors to crosslink and slide apart antiparallel MTs emanating from the opposite poles of the mitotic spindle.3 By this mode of action, kinesin-5 motors are believed to fulfill their essential roles in spindle dynamics such as spindle assembly, maintenance of the bipolar spindle structure prior to the onset of anaphase,3-5 as well as anaphase B spindle elongation.6-11 Since MTs are organized with their plus ends overlapping in the midzone, kinesin-5 can only push spindle poles apart during spindle assembly and elongation via plus-end directed motility between antiparallel MTs. It has indeed been demonstrated in vitro, that the vertebrate kinesin-5 Eg5 moves simultaneously toward the plus ends of two antiparallel MTs that it crosslinks.12,13 This finding was consistent with the 20-year-old dogma that kinesin homologs which carry their catalytic domains at the N-terminus are plus-end directed.14

The majority of the members of the kinesin superfamil are plus-end directed. Minus-end motion was seen only for the structurally distinct kinesin-14 family members which carry the catalytic domain at their C-terminus.15-17 Being non-processive, these motors produce isolated power strokes and can only produce persistent motion in ensembles. Surprisingly, the S. cerevisiae kinesin-5 Cin8 was recently found to move processively in the minus-end direction of MTs in single-molecule fluorescence motility assays under close-to-physiological conditions.18,19 Cin8 was shown to switch directionality to plus-end directed motility in several experimental circumstances: in multi-motor MT gliding assays,18,20 under low-ionic-strength conditions, and when bound between two antiparallel MTs.18,19 Two possible mechanisms for this switch have been suggested: one is that single molecules of Cin8 can move only toward the minus end of MTs and that observed fluorescent traces do not prove that, indeed, individual Cin8 molecules move toward the plus end of MTs and that observed fluorescent traces do not

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 originate from small clusters of motors acting collectively. To address this point, we followed the photo-bleaching of fluorescent Cin8-GFP tetramers, purified from S. cerevisiae cells, while they moved on polarity-marked MTs under low-ionic-strength conditions. Experiments are described in detail in Gerson-Gurwitz et al. and additional data is presented here (Fig. 1). Two buffer conditions were examined: motility buffer (MB) with 30 mM NaCl added (ionic strength 0.132 M) and MB with no added NaCl (ionic strength 0.102 M). We have previously shown that under these conditions, Cin8 moves toward the plus end of MTs for ~60% and ~70% of the time, respectively. To count the number of GFP fluorophores on each moving motor or (possibly) motor aggregate, we measured the intensity of several single spots in a given video recording, both for spots appearing during the recording (i.e., landing from the bulk on the MT) and then moving to the plus-end of the MT, and for spots appearing and remaining stationary on the MT during the recording. To obtain a scale for the intensity, i.e., to determine the intensity of a single GFP, intensities before and after the final bleaching step of immobile motors were analyzed (Fig. 1C). The measured intensity distribution was fitted with a sum of two Gaussians, resulting in a value for the background and a value for the intensity of a single GFP. We then measured the distribution of the initial fluorescence intensities right after landing for both moving and immobile motors. Intensities in a fixed area were averaged for the first three frames (1.5 sec) right after landing.

**Figure 1.** In low-ionic-strength conditions, single Cin8 motors move toward the plus end of MTs. (A) Kymographs of Cin8 moving away from the brightly labeled seed marking the minus end (-) toward the plus end (+) of the MT. Kymograph in the right bottom panel was captured in MB-30; the other two in MB-0 (exact buffer compositions are given below). Scale bars: horizontal: 10 sec; vertical: 3 μm. (B) Exemplary intensity traces of two motors landing on a MT and moving to the MT plus end (black and red) and of a motor landing on a MT and remaining immobile (green). The traces of the moving motors correspond to the two events shown in the left panel of (A). (C) Histogram of fluorescence intensities before and after final bleaching steps of immobile motors, summed from a 800 nm x 800 nm square of camera pixels containing the image of the motor (number of traces /motors: 8). A sum of two Gaussians was fitted to the histogram. The first narrower peak corresponds to the background [compare also to (B)]. The broader second peak represents the intensity of a single GFP. (D) Histogram of initial intensities of Cin8 molecules right after landing, measured in the same arbitrary units as in (C). The intensity of the first three frames (1.5 sec) after landing was averaged for both moving and immobile motors. The histogram has a maximum at 4 times the intensity of a single GFP [compare with (C)]. Materials and Methods: Single-molecule fluorescence assays were performed as described in detail in Gerson-Gurwitz et al. In short, the custom-built total-internal-reflection-fluorescence (TIRF) microscope consisted of a 473 nm laser (Viasho, USA) for excitation, a 100x objective (SFluor, NA 1.49, oil, Nikon, USA), and a CCD camera (Cascade 512B, Roper Scientific, USA) for detection. To observe several colors simultaneously, the fluorescence emission signal was split by dichroic mirrors and directed to separate areas on the CCD camera. Fluorescently Cin8-TEV-GFP-6HIS was overexpressed in S. cerevisiae and affinity purified using the his-tag and a Ni-NTA affinity column (Invitrogen, USA). The low-salt buffers for the motility assays were composed as follows: MB-0: 50 mM Tris/HCl, 30 mM PIPES/KOH, pH 7.2, 2 mM EDTA, 1 mM EGTA, 10% glycerol, 1 mM phenylmethylsulfonyl fluoride and 1 mM dithiothreitol. MB-30: the same as MB-0 but with 30 mM added NaCl. MTs were polymerized from tissue-purified porcine tubulin, essentially as described before, but with Atto-488 (Atto-Tec GmbH, Siegen, Germany) labeled seeds that also fluoresce in the green and in that way mark the minus end of the MTs. Kymographs were generated and analyzed with a custom-written LabView (National Instruments, USA) routine. The fluorescence intensity emitted by single proteins was summed over an area of 5 x 5 camera pixels, corresponding to an area of 800 nm x 800 nm in the specimen plane and was analyzed with ImageJ software (NIH, USA), and histograms and fits were done with OriginPro software (OriginLab Corporation, USA).
(Fig. 1D), during which time the motors moved much less than the size of the chosen area around the spots. Comparison of initial intensities to monomer intensities confirms that both, the motors moving to the plus end of MTs and the stationary motors were tetramers. Furthermore, some of the bleaching traces of Cin8 molecules that moved toward the plus ends of MTs showed four consecutive bleaching steps (Fig. 1B), indicating again that these molecules were tetramers with four GFP molecules. These results demonstrate that, under low-ionic-strength conditions, individual Cin8 molecules can move in the plus-end direction on MTs. While coupling between multiple motors could be an additional mechanism for switching, our results provide support for the existence of the motor-intrinsic switch model.

Since ionic strength generally modulates electrostatic interactions, the unphysiologically low-ionic-strength conditions might mimic the effects of phosphorylation or binding of accessory proteins or of binding geometry to the MTs. A qualitatively similar ionic-strength effect has been reported in the context of cargo regulation of other kinesins. Binding of a cargo vesicle to kinesin-1 or of a second MT to kinesin-5 Eg5 activates these motors, but this activation also occurs spontaneously (i.e., without cargo) at low ionic strength in both cases. Tailhead interaction is mediating this regulation in both cases. It is thus tempting to speculate that for Cin8, cargo regulation is also the physiological switch mechanism. In the case of Cin8, a mechanism detecting the binding of a second MT might not just turn the motor on or off, but lead to the observed switching of directionality. Consistent with this hypothesis, we observed plus-end directed antiparallel sliding of MTs by Cin8 when they entered the overlap zone between antiparallel MTs under high-ionic-strength conditions, while motors on single MTs in the same sample were still minus-end directed. Similarly, it has been previously demonstrated that, while the vertebrate Eg5 does not bind to nor move on single MTs under high-ionic-strength conditions, binding between two antiparallel MTs activates MT sliding, driven by plus-end directed Eg5 motility. A similar activation effect might also occur in multi-motor MT surface-gliding assays, in which surface-attached Cin8 was also demonstrated to be plus-end directed. In MT sliding assays, Cin8 obviously exerts force in the plus-end direction which is reflected in the relative sliding of the MTs, but individual motors between the coupled MTs move on rather erratic tracks such that clear plus-end-directed periods cannot be detected. Cin8 behaves very differently in single-molecule fluorescence experiments between parallel MTs. For the most part, motors continue minus-end motion, apparently not interacting with the second MT. The capability to distinguish relative orientation of bound MTs is consistent with the reported preference of Drosophila kinesin-5 Klp61f for bundling antiparallel MTs. For this kinesin-5, a preferred orientation was due to the ATP-independent binding sites in the C-terminal tails of the molecules. A similar binding mechanism appears to also exist for Cin8 because full-length Cin8 diffusively slides along MTs in ADP buffer. For Xenopus laevis kinesin-5 Eg5 it was found that all MT binding sites in the C-terminal tails were necessary for motor engagement between MTs. It still remains unclear exactly why and how low ionic strength mimics cargo binding. Taking into account the fact that MT attachment of the two pairs of motor domains triggers plus-end directed motility (Fig. 2A), a speculative possibility is that under low-ionic-strength conditions, Cin8 can flex in such a way that the two pairs of catalytic domains interact with the same MT (Fig. 2B) and thus trigger plus-end motility.
directed motility. Alternatively, low-ionic-strength conditions could modify tail–head interactions as in kinesin-1 to trigger plus-end directed motility. One further piece of evidence in favor of a motor-intrinsic mechanism for directional switching is the regulatory influence of plus-end directed motility. Alternatively, low-ionic-strength conditions could modify tail-directed motility. The mechanism by which phosphorylation in the catalytic domain of Cin8 regulates its in vivo function is likely to include the modulation of interactions with the midzone-organizing protein Ase1.8,24 or with kinetochoore proteins. The fact that a deletion construct (Cin8Δ99) and a loop 8 Cdk1 phosphorylation-deficient construct (Cin8-2A) exhibit reduced motility toward the midzone in vivo, suggests that one of the roles of Cin8 phosphorylation in the 99aa insert is to mediate the switch to plus-end directed motility of Cin8 on the mitotic spindle. The question remains how its exceptional motile properties aid Cin8 in performing its roles in mitosis. One can speculate on the basis of the localization of Cin8 in the various stages of mitosis. The ionic strength in S. cerevisiae cells is ~300 mM salt. At this ionic strength, Cin8 is minus-end directed in vitro. Before spindle elongation in anaphase, Cin8 is known to be involved in the positioning of the chromosome kinetochores near the spindle pole bodies.27-29 Cin8 could function at that stage by crosslinking of kinetochoore MTS (kMTs)27 and by aiding the disassembly of long kMTs.30 Since in S. cerevisiae cells each kinetochore is attached to the plus end of a single MT, motion of Cin8 in the minus-end direction of the kMTs might be a part of kinetochore positioning. Cin8 also shows plus-end directed motility in vivo in anaphase spindles,31 even on single MTs or on parallel MT bundles, which implies a further mode of regulation not seen in the in vitro experiments. Regulated bi-directional motility might be important to distribute Cin8 motors between the different locations where they are known to accumulate, i.e., near the spindle poles and in the midzone. In summary, Cin8 has rather unexpectedly extended the spectrum of known kinesin capabilities. It is the first known kinesin that is truly bi-directional and processive in both directions. Found in a low eukaryote, this function might have evolved early and might have been lost in higher eukaryotes. The exact molecular mechanism remains to be clarified, but seems likely to be related to cargo switching known for other kinesins. Our results indicate a role of electrostatic interactions and possibly phosphorylation, and, most importantly, binding geometry between pairs of MTs.

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