Effects of anisotropic thermal conduction on wind properties in hot accretion flow

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ABSTRACT
Previous works have clearly shown the existence of winds from black hole hot accretion flow and investigated their detailed properties. In extremely low accretion rate systems, the collisional mean-free path of electrons is large compared with the length-scale of the system, thus thermal conduction is dynamically important. When the magnetic field is present, the thermal conduction is anisotropic and energy transport is along magnetic field lines. In this paper, we study the effects of anisotropic thermal conduction on the wind production in hot accretion flows by performing two-dimensional magnetohydrodynamic simulations. We find that thermal conduction has only moderate effects on the mass flux of wind. But the energy flux of wind can be increased by a factor of \(\sim 10\) due to the increase of wind velocity when thermal conduction is included. The increase of wind velocity is because of the increase of driving forces (e.g. gas pressure gradient force and centrifugal force) when thermal conduction is included. This result demonstrates that thermal conduction plays an important role in determining the properties of wind.

Key words: accretion, accretion discs – black hole physics – hydrodynamics – conduction

1 INTRODUCTION
Hot accretion flow such as advection-dominated accretion flow (ADAF; Narayan & Yi 1994, 1995; Abramowicz et al. 1995) is interesting because it can be used to model the low-luminosity active galactic nuclei (LLAGNs), which are the majority of galaxies at least in the nearby universe, and the hard/quiescent states of black hole X-ray binaries (see Yuan & Narayan 2014 for the latest review of current theoretical understanding of hot accretion flow and its various astrophysical applications).
Numerical simulations of hot accretion flow show that the mass inflow rate (see Equation (1) for definition) decreases with decreasing radius \(\dot{M}_{\text{in}}(r) \propto r^s\) with \(s \sim 0.5 - 1\) (e.g. Stone et al. 1999; Igumenshchev & Abramowicz 1999, 2000; Hawley & Balbus 2002; Pang et al. 2011; Yuan et al. 2012a; Bu et al. 2013). Especially Yuan et al. (2012b) show that the inward decrease of the accretion rate is due to the significant mass loss via wind (see also Narayan et al. 2012; Li et al. 2013). This conclusion is soon confirmed by the 3 million seconds Chandra observations of the accretion flow around the super-massive black hole in the Galactic Center, combined with the modeling to the detected iron emission lines (Wang et al. 2013). Begelman (2012) and Gu (2015) address the question of why wind exists. The detailed properties of wind such as the mass flux, angular distribution, terminal velocity, and fluxes of energy and momentum, have been studied in Yuan et al. (2015) (see also Sadowski et al. 2016) by following the trajectories of the fluid particles. Bu et al. (2016) show that wind production can only occur within the Bondi radius of the accretion flow.
All the simulations mentioned above have neglected the effects of thermal conduction. However, thermal conduction is very important when the accretion rate is very low. In low accretion rate systems, the electron mean free path is very large. In this case, thermal conduction can have a significant influence on the dynamics of the accretion flow (Quataert 2004; Johnson & Quataert 2007), resulting in the transport of thermal energy from the inner (hotter) to the outer (cooler) regions. If the energy flux carried by thermal conduction is substantial, the temperature of the gas in the outer regions can be increased above the virial temperature. Thus, gas in the outer regions is able to escape
from the gravitational potential of the central black hole and form outflows, significantly decreasing the mass accretion rate (Tanaka & Menou 2006; Johnson & Quataert 2007; Sharma et al. 2008; Bu et al. 2011).

If the mean free path of electron is much larger than its gyro-radius, conduction will be anisotropic and along magnetic field lines (Balbus 2000, 2001; Parrish & Stone 2005, 2007; Quataert 2008; Fougart 2016). In many LLAGNs, the electron mean free path is much larger than electron gyroradius (see Tanaka & Menou 2006). Let's take the accretion flow in Galactic Center as an example to compare the electron mean free path to their gyro-radius. From Chandra observations of the accretion flow at the Galactic Center, Sgr A*, the electron mean-free path is estimated to be 0.02 – 1.3 times the Bondi radius, i.e., the electron mean free path \( l \sim 1.3 \times 10^{17}\) cm (Tanaka & Menou 2006). The gyro-radius of electrons is \( R_{\text{gyro}} = m_e v_{\text{th}} c/\eta B \sim 4 \times 10^5 \sqrt{\beta}/n \), where \( m_e \) is electron mass, \( v_{\text{th}} \) is thermal speed of electron, \( c \) is speed of light, \( \eta \) is electron charge, \( B \) is magnetic field, \( \beta \) is the ratio between gas pressure and magnetic pressure, \( n \) is number density of electrons. At \( 10^5 \) cm, \( R_{\text{gyro}} \sim 10^6 \) cm if we assume \( \beta \sim 10 \); Therefore, it is clear that electron mean free path is much larger than its gyro-radius. For the accretion flow at Galactic Center \( n \sim r^{-1/2} \), so \( R_{\text{gyro}} \propto r^{1/4} \) if we assume \( \beta \) is almost constant in the accretion flow. But the electron mean free path \( l \propto r^{-3/2} \) (Tanaka & Menou 2006). As a result, the electron mean free path will become even larger than gyro-radius when approaching the central black hole event horizon.

In this paper, we study the effects of anisotropic thermal conduction on the properties of hot accretion flow by performing two-dimensional magnetohydrodynamic (MHD) simulations. We especially pay attention to the wind properties, such as the mass, momentum and energy fluxes of wind launched from the accretion flow. These quantities are essential for the study of AGN feedback since winds play an important role in the feedback process. For example, the two gamma-ray Bubbles observed by the Fermi-LAT below and above the Galactic plane (Su et al. 2010) may be inflated by the wind from the hot accretion flow in our Galactic Center (Mou et al. 2014). In §2, we will describe the basic equations and the simulation method. In §3, we will present the results. We discuss and summarize our results in §4.

2 NUMERICAL METHOD AND MODELS

2.1 Numerical method

We adopt two-dimensional, spherical coordinates \((r, \theta, \phi)\) and assume axisymmetric \((\partial/\partial \phi = 0)\). We use the Zeus-2D code (Stone & Norman 1992a, 1992b) to solve the MHD equations with anisotropic thermal conduction:

\[
\frac{dp}{dt} + \rho \nabla \cdot \mathbf{v} = 0, \tag{1}
\]

\[
\frac{d\mathbf{v}}{dt} = -\nabla p - \rho \nabla \Phi + \frac{1}{4 \pi} \left( \nabla \times \mathbf{B} \right) \times \mathbf{B} \tag{2}
\]

\[
\frac{d(e/\rho)}{dt} = -p \nabla \cdot \mathbf{v} - \nabla \cdot \mathbf{Q} + \eta \mathbf{J} \tag{3}
\]

\[
\frac{\partial \mathbf{B}}{\partial t} = \nabla \times (\mathbf{v} \times \mathbf{B} - \eta \mathbf{J}) \tag{4}
\]

\[
\mathbf{Q} = -\chi \mathbf{b} (\mathbf{b} \cdot \nabla) T \tag{5}
\]

Here, \( \rho \) is the mass density, \( \mathbf{v} \) is the velocity, \( p \) is the gas pressure, \( \mathbf{J} = c (\nabla \times \mathbf{B})/4\pi \) is the current density, \( \Phi \) is the gravitational potential, \( \mathbf{B} \) is the magnetic field, \( e = p/(\gamma - 1) \) is the internal energy (where \( \gamma \) is the adiabatic index, we set \( \gamma = 5/3 \)), \( \mathbf{b} = \mathbf{B}/|\mathbf{B}| \) is the unit vector in the direction of the magnetic field, \( \eta \) is the explicit resistivity, \( T \) is the gas temperature, \( \mathbf{Q} \) is the heat flux along field lines and \( \chi \) is the thermal diffusivity.

The final terms in Equations (3) and (4) are the magnetic heating and dissipation rate mediated by a finite resistivity \( \eta \). Since the energy equation here is actually an internal energy equation, numerical reconnection inevitably results in loss of energy from the system. By adding the anomalous resistivity, the energy loss can be captured in the form of heating in the current sheet (Stone & Pringle 2001). The exact form of \( \eta \) is the same as that used by Stone & Pringle (2001).

We use the pseudo-Newtonian potential to mimic the general relativistic effects, \( \Phi = -GM_{\text{BH}}/(r - R_s) \), where \( G \) is the gravitational constant and \( M_{\text{BH}} \) is the mass of the central black hole. The self gravity of the gas is neglected. In this paper, we set \( GM_{\text{BH}} = R_s = 1 \). We use \( R_s \) to normalize the length-scale. Time is in unit of the Keplerian orbital time at 100R_s. The black hole in our Galactic Center has a mass \( M_{\text{BH}} \approx 4 \times 10^6 M_{\odot} \), \( M_{\odot} \) is the solar mass. For the black hole in our Galactic Center, the length unit \( (R_s) \) is \( \sim 10^{17} \) cm. The orbital time at 100R_s is \( \sim 3.8 \times 10^5 \) seconds.

Following Sharma et al. (2008), we assume \( \kappa = \chi T/p \) which has the dimensions of a diffusion coefficient \( (\text{cm}^2\text{s}^{-1}) \). In non-relativistic theory, \( \kappa \propto c_s^2 \tau_R \), with \( c_s \) is the sound speed and \( \tau_R \) is the effective mean-free-time due to wave-particle scatterings (Fougart et al. 2016). A nature scale for \( \tau_R \) is the dynamical time \( \sqrt{p}/(GM_{\text{BH}}) \). For the hot accretion flow such as Sgr A*, the temperature of gas is almost virial; therefore, the sound speed is proportional to the Keplerian rotational velocity \( c_s \propto u_k \propto r^{-1/2} \). Thus, for hot accretion flow, \( \kappa \propto r^{r-1/2} \). In this paper, we assume that \( \kappa \equiv \alpha_c (GM_{\text{BH}} r)^{1/2} \). The precise value of \( \alpha_c \), which depends on the microphysical processes, is difficult to calculate. Motivated by the results of Sharma et al. (2006) and Sharma et al. (2007) on the microphysics in collisionless accretion flows, we take \( \alpha_c = 0.2 \). This value is much smaller than the maximum free-streaming thermal conductivity that could be obtained if the electrons are virial.

2.2 Initial conditions and numerical settings

Following Stone et al. (1999), the initial state is an equilibrium torus with constant specific angular momentum which is given by (Papaloizou & Pringle 1984),

\[
\frac{p}{\rho} = \frac{GM_{\text{BH}}}{(n+1)R_0} \left[ \frac{R_0}{r} - \frac{1}{2} \left( \frac{R_0}{r \sin \theta} \right)^2 - \frac{1}{2d} \right]. \tag{6}
\]

Here, \( R_0 \) is the radius of the torus center (density maximum), \( n = (\gamma - 1)/\gamma \) is the polytropic index and \( d = 1.5 \) is the distortion of the equilibrium torus. We assume that at the torus center \( \rho = 1 \) and the torus is embedded in a low-density medium \( \rho_m = 10^{-4} \).

The computational domain is from \( R_{\text{in}} \) = 1.3 or \( 2 R_s \) to \( R_{\text{out}} = 400 R_s \) in radial direction and from \( \theta = 0^\circ \) to \( \theta = 90^\circ \).
θ = 180° in angular direction. The radial grids are logarithmically spaced (grid spacing d r ∝ r). In angular direction, the grids are uniformly spaced. The axisymmetric boundary conditions are used at θ = 0° and 180°. We adopt outflow boundary conditions at both the inner and outer radial boundaries. The standard resolution is 147 × 88. Several modifications to the code were required for the simulations, including implementing the pseudo-Newtonian potential, adding the anomalous resistivity and thermal conduction. The thermal conduction is implemented by using the method based on limiters (Sharma & Hammett 2007), this method can guarantee the heat always flows from hot regions to cold regions.

2.3 Models

Due to the fact that thermal conduction is transported along magnetic field lines, if the magnetic field is much ordered, we expect energy can be transferred from inner to outer region which will affect the dynamics of the flow significantly. If the magnetic field is much tangled, we expect energy can not be transferred to large distance which may result in small effects on the dynamics of the flow. Motivated by this point, we explore two different magnetic configuration: a large scale ordered magnetic field and a relative small scale tangled magnetic field to examine the effects of thermal conduction on hot accretion flow.

The magnetic field which threads the torus initially is generated by a vector potential, i.e. \( \mathbf{B} = \nabla \times \mathbf{A} \). Initializing the field in this way guarantees that it will be divergence-free. We take \( \mathbf{A} \) to be purely azimuthal. In model A series, we assume \( A_0 = \rho^2/\beta_0 \) and \( \beta_0 = 100 \). This will generate a dipolar field (see the left panel of Figure 1). With the value of \( \beta_0 = 100 \), when the flow achieves steady state, the field is much ordered. In model B series, we assume the field is quadrupolar with \( A_0 = \rho^2/\beta_0 r \cos \theta \) (see the right panel of Figure 1). For the quadrupolar filed, the magnetic loops below and above the equatorial plane have opposite polarity. Thus, magnetic reconnection is very strong and finally the magnetic field is prone to be tangled.

Table 1 lists the main parameters in all models presented here, initial magnetic field topology, plasmas parameter \( \beta_0 \), thermal conductivity \( \alpha_c \) and final time \( t_f \) at which each simulation is stopped (all times in this paper are reported in units of the orbital time at \( R_0 = 100 R_\odot \)).

| Name | Field topology | \( \alpha_c \) | \( \beta_0 \) | \( t_f \) |
|------|----------------|-------------|-------------|-----------|
| A0   | dipole         | 0           | 100         | 4         |
| A1   | dipole         | 0.2         | 100         | 4         |
| B0   | quadrupole     | 0           | 50          | 10        |
| B1   | quadrupole     | 0.2         | 50          | 10        |

* Final time at which each simulation is stopped (all times in this paper are reported in units of the orbital time at \( R_0 = 100 R_\odot \)).

3 RESULTS

We analyze the properties of hot accretion flow at the quasi-steady state, i.e., the net accretion rate is independent of radius. The angle integrated mass accretion inflow and outflow rates, \( \dot{M}_{\text{in}} \) and \( \dot{M}_{\text{out}} \), are defined as follows,

\[
\dot{M}_{\text{in}}(r) = 2\pi r^2 \int_0^\pi \rho \min(v_r, 0) \sin \theta \, d\theta d\phi.
\]

\[
\dot{M}_{\text{out}}(r) = 2\pi r^2 \int_0^\pi \rho \max(v_r, 0) \sin \theta \, d\theta d\phi,
\]

and the net mass accretion rate is,

\[
\dot{M}_{\text{acc}}(r) = \dot{M}_{\text{in}}(r) + \dot{M}_{\text{out}}(r).
\]

Note that the above rates are obtained by time-averaging the integrals rather than integrating the time averages.

In numerical simulations, the net mass accretion rate (see Equation (9)) is always used as a diagnostic to see whether a quasi-steady state is achieved (e.g. Stone et al. 1999). If a quasi-steady state is achieved, the net mass accretion rate is almost a constant of radius. From Figure 2 (dotted lines), we can see that the net mass accretion rate is almost a constant of radius. Therefore, the simulations in this paper have reached a quasi-steady state. In the MHD simulations, there is turbulence induced by the magnetorotational instability. Therefore, the physical quantities always vary with time around their mean values. As an example, Figure 3 shows the mass flux of outflow at \( r = 20 R_\odot \) in model A1. It is clear that after \( t=1.2 \) orbits, a quasi-steady state is achieved, the mass flux of outflow oscillates with very small amplitude around its mean value.

3.1 Dipolar field models

At first we analyze model A series, all the data are time averaged from \( t = 1.5 \) to 1.6 orbits except the snapshot data is at time \( t = 1.6 \) orbits. Figure 2 shows the radial profiles of the time-averaged mass inflow rate \( \dot{M}_{\text{in}} \), outflow rate \( \dot{M}_{\text{out}} \) and net rate \( \dot{M}_{\text{acc}} \) in model A0 (without thermal conduction, \( \alpha_c = 0.0 \)) and A1 (with thermal conduction, \( \alpha_c = 0.2 \)). From this figure, it is clear that the mass inflow rate in both models decreases inwards, consistent with those found in previous works (see review in Yuan et al. 2012a). The mass inflow rate in model A1 decreases much quicker towards the black hole than model A0 and the net mass accretion rate in model A1 is about half of that in model A0. This is because the mass outflow rate in model A1 is larger than that in model A0. Note that we count all the gas with positive velocity as the mass outflow rate (see Equation (5)), i.e., the mass outflow rate includes both real outflow (wind) and...
gas which is doing turbulent motions. Thus the crucial issue to quantitatively study the strength of wind is to get rid of the contamination of turbulence. This is achieved in Yuan et al. (2015) by using a trajectory approach. Based on the general relativistic magnetohydrodynamic (GRMHD) simulation data of hot accretion flow (without thermal conduction), they convincingly show that the mass flux of real outflow is \( \sim 60\% \) of the outflow rate calculated by Equation (8).

While it is essential to use the trajectory approach to calculate the properties of wind such as the mass flux, as shown by Yuan et al. (2015), this approach is technically complicated and the calculation is very time-consuming. Since the aim of the present work is to investigate the effect of thermal conduction, to qualitatively understand the above-mentioned different results between models A0 and A1, we find it is enough to simply use the time-averaged method often adopted in literature. The time-averaged density contour and velocity field are shown in Figure 4. This figure shows the distribution of density contour over-plotted by the poloidal velocity field within \( R = 20 \ R_s \) of models A0 (left panel) and A1 (right panel). In both models, the flow has two components: low temperature high density main disc body around the equator and high temperature low density corona sandwiching it. The main disc body is the inflow region (Sadowski et al. 2013; Yuan et al. 2015). We find that the wind region in model A1 is larger than that in model A0. For example, in model A0, it is inflow in the regions \( 26^\circ < \theta < 45^\circ \) and \( 135^\circ < \theta < 154^\circ \). But in model A1, gas in these two regions becomes wind. The broader wind region in model A1 results in stronger wind and more rapid inward decrease of the inflow rate.

In order to figure out why the inflowing gas becomes wind, we plot magnetic field, heat flux and temperature in Figure 5. In Figure 5, upper-left panel shows the snapshot of logarithm plasma \( \beta \) and magnetic field lines for model A1. Black lines are magnetic field lines; colors show logarithm plasma \( \beta \). Upper-right panel shows the snapshot of conduction energy flux \( Q \) and its divergence for model A1; colors show the divergence of conduction flux \( \nabla \cdot Q \) for model A1. Arrows show the energy flux. Orange denotes regions those are heated by thermal conduction; green denotes regions those are cooled by thermal conduction. Bottom panels show the time-averaged (from \( t = 1.5 \) to 1.6 orbits) logarithm temperature for models A0 (left) and A1 (right), respectively. In model A series, because of a relative small plasma \( \beta \) and dipolar configuration field as the initial condition, the wavelength of the magneto-rotational instability (MRI; Balbus & Hawley 1991; 1998) is large which suppressed the turbulence driven by the MRI. Thus, the magnetic field evolves to a relative strong and ordered magnetic field as the upper-left panel of Figure 5 shows. The thermal conduction flux is mainly along magnetic field lines, so it is also become very ordered. Heat energy is transferred from inner to outer region by thermal conduction. At the equator, the heat is transport from inner to larger radius and plays a cooling role. It is clear that gas in the regions \( 26^\circ < \theta < 45^\circ \) and \( 135^\circ < \theta < 154^\circ \) is heated up by the conduction flux along magnetic field lines. The increase of temperature in those regions results in the increase of gas pressure gradient force. Consequently, the increased gas pressure gradient force makes the inflowing gas changing moving direction and becoming wind. From the energy point of view, the Bernoulli
parameter of the gas in these two regions becomes larger due to thermal conduction thus the gas is easier to become wind. This argument of wind production is similar to that presented in Gu (2015).

Furthermore, to investigate how the nature of outflow changed by thermal conduction, we also calculate the outflow energy fluxes carried out in the form of the kinetic energy and outflow momentum fluxes as follows:

\[ E_{\text{wind}}(r) = 2\pi r^2 \int_0^\pi \frac{1}{2} \rho \max(v_r, 0) v_r^2 \sin \theta d\theta, \]

\[ P_{\text{wind}}(r) = 2\pi r^2 \int_0^\pi \rho \max(v_r, 0) v_r \sin \theta d\theta. \]

Figure 6 shows the energy and momentum fluxes carried by wind. From this figure, it is clear that in both models the energy and momentum fluxes carried by winds increase outward. This is consistent with Yuan et al. (2015). Compared with model A0, the energy flux in model A1 increases by about one order of magnitude. In order to study why the energy and momentum fluxes increase when thermal conduction is included, we plot Figure 7 which shows the angular distributions of various quantities. Let us take the physical values for wind at 10R_s as an example. At 10R_s, the wind mainly occurs around \( \theta = 60^\circ - 70^\circ \). After considering thermal conduction, in the wind region, the density decreases by a factor \( \sim 5 \); but the velocity increases by a factor of \( \sim 4 \). Since \( E_{\text{wind}} \propto \rho v_r^3 \) and \( P_{\text{wind}} \propto \rho v_r^2 \), the energy flux of wind increases by a factor of \( \sim 10 \), the momentum flux by a factor of \( \sim 3 \).

To figure out the reason of why the velocity of wind increases after the inclusion of thermal conduction, we calculate the forces exerting on gas. Based on the GRMHD simulation data, Yuan et al. (2015) (see also Moller & Sadowski 2015) have shown that the wind is mainly driven by the centrifugal force, the gradient force of gas pressure and magnetic pressure. Figure 8 plots the driving force for wind at \( \theta = 65^\circ \) and \( r = 10R_s \) in model A0 (upper panel) and A1 (lower panel). In the case of model A0, the main driving forces are the combination of the gradient force of magnetic pressure and the gas pressure and the centrifugal force. It is clear that after the thermal conduction is included the gas pressure gradient force increases due to the increase of temperature. The magnetic pressure gradient force also increases. The increase of forces results in the larger velocity of wind in model A1 compared with A0.
3.2 Quadrupolar field models

In model A series, the magnetic field is strong and ordered. Therefore, thermal conduction along magnetic field can transport energy from the inner to outer region and affects the wind production significantly. If the magnetic field is tangled one may expect that energy cannot be transferred to large distance. In this case, the effects of conduction may be smaller compared with the case when the magnetic field is ordered. In order to examine this point, we carry out model B series (see Table 1). In this series, the initial magnetic field configuration is quadrupolar (see the right panel of Figure 1). In this case, magnetic reconnection very easily occurs, which can decrease the strength of magnetic field. In this section, the data are usually time averaged from $t = 3.0$ to $t = 3.5$ orbits, except for the snapshot data is at time $t = 3.5$ orbits.

Figure 9 shows the snapshot of logarithm of $\beta$ over-plotted with magnetic field lines (left panel) and the unit vector of conduction energy flux $\mathbf{Q}/|\mathbf{Q}|$ over-plotted with the divergence of conduction flux $\nabla \cdot \mathbf{Q}$ (right panel) of model B1. Recall that in model A series, the magnetic field is ordered and the heat flux is transported mainly along the magnetic field lines so that the heat flux is also ordered as seen in the upper-right panel of Figure 5. But the case is different in model B series. Because the magnetic field is weaker and tangled, as shown in Figure 9 (left panel, solid line), the conduction energy flux (right panel, arrows) is thus not ordered.

Figure 10 shows the mass accretion rates in model B series. It is clear that the mass accretion rates are only slightly changed after thermal conduction is taken into account. In order to study the reason, we plot the angular profiles of some quantities in Figure 11. As shown in the upper-right panel, the angular profiles of temperature in model B1 is flatter than that in model B0, consistent with that found in Johnson & Quataert (2007). Except for the changes of den-
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4 SUMMARY AND DISCUSSION

Previous works have shown that strong winds exist in hot accretion flows (Yuan et al. 2015; see also Yuan et al. 2012b;
Narayan et al. 2012; Li et al. 2013. Those works do not include thermal conduction. In extremely low accretion rate systems such as the accretion flow in Galactic center Sgr A\*, the plasma is very dilute, and the collisional mean-free path of electrons is large and much greater than their gyro-radius. Thus, thermal conduction is dynamically important and anisotropic, along magnetic field lines. In this paper, we have studied the effects of anisotropic thermal conduction on the wind by performing two-dimensional MHD simulations. Two different magnetic field topologies are considered: a strong ordered field and a weaker tangled field. Our simulation results show that thermal conduction has moderate effects on the mass flux of wind in both cases. However, the energy flux of wind can be increased by a factor of 10 due to the increase in wind velocity when thermal conduction is included.

There are still some limitations in our work. Our simulations are two-dimensional and we adopt the one-temperature simplification. Ressler et al. (2015) study the two-temperature hot accretion flow with anisotropic conduction in GRMHD. Their results have shown that electron heating rates depend on the local magnetic field strength and electron thermal conduction modifies the electron temperature in the inner regions of accretion flows. They use a quadrupolar magnetic field and our model B1 is basically consistent with their results, such as the temperature gradient is flatter due to the effects of thermal conduction. But they did not give the results of wind properties.

Finally, we would like to mention that in a weakly collisional accretion flow, the ion mean-free path can be much greater than its gyro-radius, and thus the pressure tensor is anisotropic. In this case, the growth rate of the MRI can increase dramatically at small wave numbers compared with MRI in ideal MHD (Quataert et al. 2002; Sharma et al. 2003). In this regime, the viscous stress tensor is anisotropic, and Balbus (2004) has shown that when anisotropic viscosity is included, the flow is subject to the magnetoviscous instability (MVI; see also Islam & Balbus 2005). An interesting project in the future is to investigate the effects of MVI on wind from hot accretion flows.

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\[\text{Figure 13. Force analysis at radius of } 10R_g \text{ for model B0 (upper-panel, } \theta = 30^\circ) \text{ and model B1 (lower-panel, } \theta = 20^\circ)\]
