A Case Study of Optimization and Application of Soft-Rock Roadway Support in Xiaokang Coal Mine, China

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The roadway of S2S2 fully mechanized caving face (FMCF) in Xiaokang Coal Mine is one of the most typical deep-buried soft-rock roadways in China and had been repaired several times. In order to figure out the failure reasons of the original roadway support, the geological conditions were investigated, the surrounding rock stress was monitored, the rib displacement, roof separation, and floor heave were in situ measured, and the performance of the U-shaped steel support was simulated. The above analysis results indicated that the support failure was mainly caused by (1) the unreasonable arch roadway section, (2) the high and complex surrounding rock stress, (3) the failure control of the floor heave, and (4) the inadequate self-supporting capacity of the surrounding rock. For optimizing, the roadway section was changed to circle and a new full-section combined support system of “belt-cable-mesh-shotcrete and U-shaped steel-filling behind the support” was adopted, which could specifically control the floor heave, allow the roadway deformation in control, and improve the self-supporting ability and stress field of the surrounding rock. To determine the support parameters, the selected U-shaped steel support was verified by simulation, and various bolt-cable support schemes were simulated and compared. Finally, such an optimized support scheme was applied in the roadway of the next replacement FMCF. The in situ monitoring showed that the rib-to-rib convergence and roof-to-floor convergence were both controlled within 600 mm, which indicated that the roadway was effectively controlled. This case study has important reference value and guiding function for the optimal design of the soft-rock roadway support with similar geological conditions.

1. Introduction

As coal mining depth increases, the roadway support is generally faced with the difficult problems caused by soft rock and high ground stress [1–3]. In addition, the severe strata behavior, the large and long-time roadway deformation, serious floor heave, and serious support structure damage lead to over 70% of the repair rate in such kind of roadways [4–6]. The induced vicious cycle of “digging and repairing” during mining [7–9] wastes a lot of manpower and material, directly affects the efficient production of coal mine, and endangers the safety of human life and property [10–12].

The research on the theory and technology of the soft-rock roadway support under high ground stress is active, and a series of research results have been obtained. For instance, He et al. [13] proposed the coupling support concept of roadway and developed the technical system of active support; Kang and Wang [14] put forward the theory of high pretensioned stress and intensive bolting system and developed a complete technology of bolt support for coal mine; Gao et al. [15] developed the concrete-filled steel tube support technology; Jiang et al. [16] analyzed the mechanism of different types of roadway floor heaves and proposed corresponding prevention and control measures. In addition, Yang et al. [17] revealed the deformation and failure
mechanism of deep soft-rock roadway and put forward a new "bolt-cable-mesh-shotcrete + shell" combined support; Shen [18] optimized the spacing and pretightening force of the bolt and anchor cable by UDEC; Kang et al. [19] analyzed the soft-rock roadway deformation and failure characteristics with different support types by the numerical simulation method; Wang et al. [20] first adopted grouting to enhance the surrounding rock's self-bearing ability and then used the bolt to control the deformation and failure of the soft surrounding rock.

These studies laid the theoretical foundation and provided new ideas and methods for the support of deep-buried soft-rock roadway. As for specific applications, the geological conditions and the key factors affecting the stability of surrounding rocks are complex and numerous [20–23]. Hence, the design and optimization of the support scheme should be carried out according to the in situ conditions and a suitable support theory and technology should be adopted [24–27].

In Xiaokang Coal Mine, during the first fully mechanized caving face (FMCF) of S1W3, during the whole mining period, the cumulative roof-to-floor convergence of the two mining roadways is 3800 mm and 6500 mm, respectively, and the cumulative rib-to-rib convergence is 1400 mm and 3200 mm, respectively, which is 10–20 times and 2–3 times that of other mines where the surrounding rock is relatively stable and soft. Coupled with serious floor heave and complex surrounding rock stress, the soft-rock roadway in Xiaokang Coal Mine is extremely difficult to maintain in China and even in the world [28].

The purpose of this paper is to optimize and design the support scheme of the deep-buried soft-rock roadway in Xiaokang Coal Mine based on the initial soft-rock roadway support system in S2S2 FMCF. Thus, the performance of the original support scheme in S2S2 FMCF was first analyzed by in situ measurement and numerical simulation to figure out the failure mechanism, based on which the corresponding control technology was developed and the support scheme was optimized. Finally, the new proposed support scheme was carried out in the roadway of the next replacement FMCF, and the in situ monitoring was carried out to identify the effect of the new support system.

2. Engineering Background

2.1. The Geological Conditions. As shown in Figure 1, Xiaokang Coal Mine with an area of 28.99 km² is located in Liaoning Province, China. Its north-south length is 6.03 km and the east-west width is 4.81 km.

In Xiaokang Coal Mine, the S2S2 FMCF and its replacement FMCF are both located in southern No. 2 mining area (S2) and share the same geological conditions. The width of the S2S2 FMCF is 232 m, and the advancing length is 1281 m. As for the coal seam, the thickness is 7.50 m to 10.24 m, with an average of 8.50 m; the buried depth is 640 m to 720 m, with an average of 665 m; and the dip is 3° to 10°, with an average of 5°.

The immediate roof of the coal seam is oil shale with stepped fracture. It is carbonaceous, oil-rich, and easily weathered and would be crushed after drying, which make it not easy to maintain. Its thickness is 6.31 m to 14.2 m with an average of 8.5 m. The mining height of the machine is 2.8 m, the coal drawing height is 5.7 m, and the caving ratio is 1: 2.04. The basic roof is mainly composed of mudstone with obvious beddings and joints. Its thickness is 11.2 m to 21.3 m with an average of 15.6 m.

The thickness of the coal seam floor is 6.51 m to 12.3 m with an average of 7.62 m. It was relatively highly cemented by argillaceous material. More than 50% of the clay minerals in floor strata are Aemon interbeds, and the other clay minerals are mainly kaolin and illite, so they are easy to be weathered and have strong dilatability, resulting in a very serious floor heave.

2.2. The Initial Support Scheme. The arch-section mining roadways of the S2S2 FMCF with a sectional area of 13.7 m² initially adopted the combined support scheme of "bolt-mesh-shotcrete and U-shaped steel". The specific support parameters are as follows.

As shown in Figure 2(a), the anchor bolts were just installed at the top and shoulder of the roadway. The anchor bolt used the thread steel of M22 × 2400 mm with a spacing of 800 × 800 mm and a pretightening force of 60 kN. The lengthened resin anchorage was applied with two Z2335 resin anchor agents and one Z2540 resin anchor agent in each hole. The high-intensity tray of 120 mm × 120 mm × 10 mm was selected. The U36 steel support was adopted with a spacing of 1000 mm. The rhombic metal mesh was used with a bar of 8 mm and a grid spacing of 100 mm. The back-filling thickness was 300 mm. There almost no support was conducted to control the floor. The support effect is shown in Figure 2(b).

2.3. Complex Stress Field of the Roadway Surrounding Rock. To reveal the stress environment of the roadway in the S2S2 face, three observation stations of P1, P2, and P3 were arranged at a distance of 50 m, 500 m, and 1000 m away from the open-off cut, respectively, as shown in Figure 3(a). The stresses were measured by using the SYY-56 hydrofracturing in situ stress measurement device in the drilling of the roadway surrounding rock, as shown in Figure 3(b). The drilling depth was 10 m and the bore diameter was 56± 2 mm. The horizontal stresses on the two ribs and the vertical stresses on the roof are shown in Figure 3(c).

The results indicated that the rock stress varied with the positions along the roadway: at P1 position, the stress on the two ribs (21 MPa) is two times that of the roof (10 MPa), while at P2 position the roof stress (21 MPa) is two times that of the ribs (10 MPa), and when it turns to P3 position, the right rib stress is the largest. It can be concluded that the rock stresses were not even around the roadway and changed along the length direction, and such high and uneven stress field far exceed the resistance of the surrounding rock which only has a saturated compressive strength of 3 MPa–5 MPa, resulting in large displacement and damage depth of the roadway and high pressure on the support structures. Under the complex and uneven stress field at different positions, the
performance of the U-shaped steel support will be simulated and analyzed in Section 3. In addition, in the new optimized support scheme, the selected U-shaped steel must adapt to such complex stress field environment which will be verified in Section 4.

2.4. The Roadway Deformation and Failure Characteristics. In order to analyze the roadway deformation and failure characteristics, three observation stations were set at observation stations of P1, P2, and P3 to monitor the rib-to-rib convergence, roof separation, and floor heave during the stopping period under the influence of mining.

2.4.1. Displacement of Ribs. The crossing method is commonly used to measure the displacement of ribs, as shown in Figure 4. The pegs were used to fix the ends of the line on two ribs, roof, and floor of the roadway at P1 observation station (50 m away from the open-off cut). The surrounding rock on ribs moved inward towards the roadway under the actions of the horizontal stress causing the lateral displacement of the
surrounding rock. A tape was used to measure the displacement on ribs, as Figure 4(b). The monitoring results of rib-to-rib convergence are shown in Figure 5.

Figure 5 indicates that (1) there were three stages of rib-to-rib convergence, that is, slow stage, accelerated stage, and instability stage, with the corresponding periods of 0–4 days, 4–10 days, and 10–18 days, respectively; (2) the rib-to-rib convergence was 99 mm, 783 mm, and 1300.5 mm in the three stages, respectively, and the total convergence was 2182.5 mm, and the average speed was 138.9 mm/d since 4 to 18 days; and (3) at the instability stage, the failure of the U-shaped steel support and the anchor bolt occurred and the roadway ribs were out of control.

2.4.2. Roof Separation. The roadway roof activities mainly include bending deformation, separation, and caving, which could be monitored by using the SMJ-2 roof separation device. The SMJ-2 is made up of anchor head of the base point, measuring line, casting, external cylinder, and internal cylinder. As shown in Figure 6(a), the roof separation device was mainly used to monitor the roof separation values within depths of 0–2.4 m and 0–8.0 m in the roof strata. The anchor head of the deep base point (8.0 m) was fixed within the stable deep bedrock, and the anchor head of the shallow base point (2.4 m) was fixed at the anchor end. The observation station was 500 m away from the open-off cut (i.e., P2 observation station).

The results of the shallow base points could be seen in Figure 6(b), which indicated that (1) the roadway roof experienced three stages, that is, the slow stage, accelerated stage, and stable stage with the periods of 0–4 days, 4–11 days, and 11–18 days, respectively; (2) the roof subsidence amounts were 101.6 mm, 843.4 mm, and 84.0 mm at the three stages, respectively, and the total amount was...
1029 mm; and (3) at the stable stage, the roof deformation basically kept unchanged because a single prop was used for timely maintenance.

2.4.3. The Amount of Floor Heave. The floor heave is caused by the uplift of the roadway floor due to mining, as shown in Figure 7(a). It could reduce the roadway section, hinder the transportation and pedestrians, affect mine ventilation, and greatly limit the safe production of the mine. In the worst situation, the roadway has to be abandoned. To solve the severe floor heave, a lot of manpower and material resources are needed. The floor heave amounts were obtained 1000 m away from the cut-open, as shown in Figure 7(b).

Figure 7(b) indicates that (1) the roadway roof experienced three stages, that is, slow stage, accelerated stage, and stable stage with the periods of 0–6 days, 6–15 days, and 15–18 days, respectively; (2) the floor heave amounts were 168.0 mm, 828.0 mm, and 48.8 mm, respectively, at the three stages, and the total floor heave amount was 1044.8 mm; and (3) at the stable stage, the floor deformation basically remained unchanged. As the original arched roadway adopted an open support system with no measurement to control the floor heave, the serious floor heave is mainly caused by stress extrusion and floor rock water expansion.

3. Numerical Analysis of Deformation and Failure Characteristics of the U-Shaped Steel Support

A shed is often used for soft-rock roadway support. In this support method, the bearing capacity of the U-shaped steel support is the basis to ensure the control effects of the roadway surrounding rock. When the loads applied on the U-shaped steel support exceed its bearing capacity, the support will undergo significant deformation and failure. According to the obtained roadway surrounding rock stresses in Section 2.3, the numerical simulation method was used to analyze the deformation and failure characteristics of the U-shaped steel support in this part.

3.1. The Numerical Model

3.1.1. The Constitutive Model of the Material. The materials of the U-shaped steel are usually 20MnK, 25MnK, and 20MnVK. According to the requirements of international standard GB/T228-2010, the aforementioned three materials were used to make tensile specimens with circular cross sections with a size of 100 × Φ10 mm to conduct tensile tests at room temperature. The tensile testing machine is shown in Figure 8(a). It could realize automatic data acquisition, processing and storage, and real-time display of test status and curves.

Figure 8(b) shows the stress-strain curve of the specimens, which have undergone the elastic stage, yield stage, strengthened stage, and failure stage. The properties of the stress-strain curve were used to determine the materials' elastic modulus $E_1$, yield limit $\sigma_y$, and tensile limit $\sigma_b$. The bilinear isotropic hardening model was used to select the material type. The MATLAB was used to write program and fix the material’s tangent modulus $E_2$. The electrical measurement method was applied to get the Poisson ratios $\mu$. Table 1 shows the detailed results.

3.1.2. Model Establishment. The establishment of the U-shaped steel support could be divided into the establishment of the solid model, the selection of the element type, the constitutive model of materials, and the boundary conditions. The specific process is as follows:

(1) The establishment of the solid model: according to the international standards of U-shaped steel, a 3D modeling software was applied to build an U36 section model, which was then saved in sat.file.
format and imported into the solver. Finally, the U-shaped steel support contour along the axial direction was constructed.

(2) The selection of the element type: the U-shaped steel support with shed is composed of a straight beam and a curved beam. Therefore, the straight beam element CBEAM and the curved beam element CBEAN were used in the numerical model. The former one required the neutral axis to coincide with the shear center and did not consider the effects of warping on the torsional stiffness as well as the influence of transverse shear. The curved beam did not require the neutral axis to coincide with the shear center, and it also considered the impacts of warping on the torsional stiffness as well as the influence of transverse shear.

(3) The constitutive model of materials: based on the stress-strain curve of the pull-out test of the U-shaped steel support metal materials, the bilinear isotropic hardening elastic-plastic material model was selected. Table 1 shows the concrete parameters [28, 29].

(4) The boundary conditions: the constraint was simply supported at both ends [30–33]. According to the measured results of the roadway stress field obtained in Section 2.3, three types of the corresponding loads were applied on the axis of the U-shaped steel support. The above four steps were used to establish

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**Table 1: Main parameters of the U-shaped steel support.**

| Type | Material | Elastic modulus $E_1$ (GPa) | Poisson ratio $\mu$ | Tangent modulus $E_2$ (GPa) | Yield strength $\sigma_y$ (MPa) | Tensile strength $\sigma_b$ (MPa) |
|------|----------|-----------------------------|-------------------|-----------------------------|-------------------------------|-------------------------------|
| 25U  | 25MnK    | 206                         | 0.3               | 21                          | 335                           | 530                           |
| 29U  | 25MnK    | 206                         | 0.3               | 21                          | 335                           | 530                           |
| 36U  | 20MnK    | 210                         | 0.3               | 19                          | 350                           | 530                           |
| 40U  | 20MnVK   | 215                         | 0.3               | 20                          | 390                           | 580                           |

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Figure 7: Roadway floor heave. (a) Floor heave; (b) floor deformation.

Figure 8: Pull-out test. (a) The synthetic material tensile testing machine; (b) the stress-strain curve.
the U-shaped steel support numerical model, as shown in Figure 9.

3.2. The Deformation and Failure Characteristics. The deformation and failure characteristics of the U-shaped steel support at $P_1$, $P_2$, and $P_3$ observation stations were extracted and compared with field measurement, as shown in Figures 10(a)–10(c), respectively.

It could be obtained that

1. The U-shaped steel support presented various deformation and failure characteristics under different stress states.

2. As shown in Figure 10(a), the stresses on the two ribs of the roadway were greatly larger than the vertical stresses, which leads to the two sides of the U-shaped steel support being obviously moved inward at $P_1$ observation station. The maximum Mises stress was 440 MPa at the leg of the shed. It was beyond the limit of the material and caused bending and failure.

3. As shown in Figure 10(b), the vertical stresses on the top of the U-shaped steel shed were significantly larger than those on two legs, and obvious subsidence could be found on top of the U-shaped steel support at $P_2$ observation station, 50 m away from the cut-open. The maximum Mises stress was 463 MPa at the top.

4. As shown in Figure 10(c), the stresses on the right side of U-shaped steel shed were obviously larger than those on the left side, and the U-shaped steel support inclined to the left. The maximum Mises stress was 650 MPa at the right side of the shed leg and caused bedding.

The analyses indicated that the arch roadway had poor adaptability under uneven and complex stress environment, and the stresses acted on the support by the surrounding rock exceeded its bearing capacity.

4. Optimization and Design of Soft-Rock Roadway Support under Complex Stress Field

As analyzed and discussed above, it is the precise factors such as the roadway being deep-buried, the surrounding rocks being weak and easy to expand and undergo weathering, the floor control not being included in the support system, the support structure not being able to fully mobilize the self-supporting capacity of surrounding rocks, the roadway section being unreasonable, etc., that finally cause the complex surrounding rock stress and the serious roadway deformation and failure.

In order to overcome the support difficulty of a deep-buried soft-rock roadway, the floor heave control must be incorporated into the support system [34]. However, as previously discussed, in the initial open support system, the roadway was constructed with an arc section and the floor reinforcement and control was ignored, so the self-supporting capacity of surrounding rocks failed to be effectively manipulated and the support performance of the U-shaped steel could not be fully developed as analyzed in Section 3. Even if floor bolts were added later, the floor heave was still out of control.

Thus, aimed at overcoming the aforementioned support defects, which make the original supporting system unable to adapt to the deformation and failure characteristics of the deep-buried soft-rock roadway, it is critical to select an appropriate roadway section and improve the supporting system. According to the experience from the existing roadway support in Xiaokang Coal Mine, it is more reasonable for the roadway section to select circle than arch and ellipse. In order to reduce the actions of the surrounding rock on the support, the section size should be reduced as much as possible. To meet the minimum requirements of transportation and ventilation, the roadway section was designed with a diameter of 4.6 m and a net area of 13.9 m².

Furthermore, matching with the redesigned circular roadway section, a new full-section combined support scheme of “belt-mesh-cable-shotcrete + U-shaped steel and wall back filling” was suggested, in which the positive support of the “belt-mesh-cable” could improve the self-supporting ability of the surrounding rock, and the passive and rigid support of the “U-shaped steel and wall back filling” not only allows the roadway deformation in control to relieve the surrounding rock pressure, but also effectively resists excessive deformation to ensure that the roadway can be normally used. In this way, the new support system was expected to control the displacement and failure of such deep-buried soft-rock roadway.

4.1. Parameters of the U-Shaped Steel Support. To verify the bearing capacity of the U36 support with the diameter of 4.6 m under a complex stress field environment, the numerical simulation of the circular section U-shaped steel support was constructed. The in situ stress values obtained in Section 2.3 were applied.

As shown in Figure 11, when the circular section support was dominated by horizontal stress, vertical stress, and right horizontal stress, the corresponding deformation amounts were 465 mm, 636 mm, and 763 mm, respectively, and the maximum Mises stresses were 293 MPa, 312 MPa, and 342 MPa, respectively. It implied that the circular U-shaped
steel support had high ability to resist deformation, and the roadway deformation was well controlled to a certain degree.

4.2. The Filling behind the Support. During the process of construction, it is inevitable to leave a certain space between the U-shaped steel shed and the surrounding rock. Therefore, at the beginning, the shed almost has no support effect on the roadway, and its supporting resistance could not exert timely, resulting in the roadway deformation. Then, the surrounding rock will contact the U-shaped steel shed unevenly, leading the support to suffer extremely complex stress, which is manifested as the uneven distribution of the U-shaped steel support load around the roadway and along the axial direction of the roadway. This is the main cause of bending, torsional deformation, and bearing capacity loss of the shed. However, the filling behind the shed support could eliminate such space, make the shed support and the surrounding rock come in close contact and make the shed suffer uniform load, so as to give full play to the supporting performance of the U-shaped steel shed.

The characteristics of the filling materials are as follows:

1. The curing time of the filling materials should be short and the intensity should increase rapidly. That is, the filling materials should have certain early and later intensity.

2. The filling materials should have certain compressibility. In the case of the surrounding rock deformation, the filling material could produce yielding effects.

3. After curing, the filling materials should not undergo volume shrinkage, and they should have slight expansion.

4. The filling materials should have abundant sources of raw materials, and also should be low-cost, easy to transport, and easy to construct underground.

5. The filling materials should have favorable processing properties such as pumpability and timely support.

According to the above requirements and based on the existing engineering experience, the mixing proportions of the filling materials were given as follows:

Figure 10: The deformation and failure characteristics of the U-shaped steel support. (a) At P1 observation station, 50 m; (b) at P2 observation station, 500 m; (c) at P3 observation station, 1000 m.
(1) The raw materials of back wall filling consisted of cement, gypsum, coal ash, and plasticizer. The 425# ordinary Portland cement and dihydrate gypsum were used [35–37]. The coal ash was the high-quality fly ash discharged from power plants.

(2) According to multiple trial ratios and on-site engineering experience, the cement-gypsum-coal ash ratio was 1:1:3. The water-cement ratio was 0.4. The admixture dosages accounted for 2% of the cement weight [38].

4.3. Parameters of Anchor Bolt and Cable. Another key to control the surrounding rock is to select the parameters of the anchor bolt and cable appropriately. Scholars have put forward many theories, such as the suspension theory and loose circle theory. These theories are useful to determine these parameters. In recent years, the prestress theory [39, 40] has been proposed, which suggests that a complete compressive stress layer within the surrounding rock of the roadway should be formed under the action of prestressed anchor bolt and prestressed anchor cable. The prestress theory has been generally accepted and has been widely used in industrial practice to provide basis for the determination of the anchor bolt and cable parameters.

According to the theory, without considering the original rock stress, if there exists a near-zero compressive stress layer within the supporting area of the anchor cable and bolt, it means that the bolt and cable fail to reinforce the surrounding rock in this area. If the compressive stress zones generated by different bolts and cables are isolated from each other, and a continuous ring of compressive stress is not formed, it means that the integral support effect of bolts and cables has not fully played [41–43]. Therefore, reasonable and effective bolt-cable support should generate as high compressive stress as possible within their support range, eliminate as much as possible the area of near-zero compressive stress, and make the area of compressive stress contiguous to form as large as possible the scale of compressive stress circle layer.

Thus, in order to clearly reflect the stress field generated by the prestressed anchor bolt and cable in the surrounding rock, the supporting effect is simulated numerically without considering the original rock stress, and the alternative support parameters are considered as shown in Figure 12: bolts with different spaces of 1200 mm, 1000 mm, and 800 mm, lengths of 1.8 m, 2.2 m, and 2.4 m, and pretightening forces of 40 kN, 60 kN, and 100 kN, and cables with different lengths of 5.3 m, 6.3 m, and 7.3 m and pretightening force of 60 kN, 105 kN, and 150 kN. In addition, the simulation scheme is listed in Table 2.

As shown in Figure 12(a), under the pretightening force of 100 kN and the length of 2.4 m, with the decrease in the bolt support space from 1200 mm to 800 mm, the compressive stress in the surrounding rock increases continuously, and the isolated compressive stress area begins to form a continuous compressive stress circle layer, and its range is obviously expanded outward. When the bolt spacing is 800 mm, the continuous compressive stress circle layer has formed in the whole length of the bolt, and there is basically no near-zero compressive stress area and isolated compressive stress area. That is, the space of 800 mm is better than 1000 mm and 1200 mm.

As shown in Figures 12(b) and 12(d), for both the anchor bolt and the cable, the increase in the pretightening force has a significant control effect on the magnitude of compressive...
5.3 m 6.3 m 7.3 m Maximum
40 kN 60 kN 100 kN

1.8 m 2.2 m 2.4 m Maximum
60 kN 105 kN 150 kN

1.6 m, and a density of 7. kVıhe combined sup-

1200mm 1000mm 800mm Maximum
principal stress

1.2000 E + 04
1.5000 E + 04
1.8000 E + 04
2.1000 E + 04
2.4000 E + 04
2.5182 E + 04
9.0000 E + 03
6.0000 E + 03
3.0000 E + 03
5.1030 E – 02

1.0, the support had the best bearing capacity, and the space between two sheds was 800 mm.

5. Engineered Application

5.1. The Scheme. First, instead of blasting, the road header was used to cut the roadway profile, which could reduce the impact of driving activities. Then, the anchor bolt and cable were applied. The diamond wire mesh was arranged on the roadway surface, and the U-shaped steel support shed was set. Finally, the filling behind the support was applied. The specific support parameters are shown in Figure 13.

U-shaped steel support: the diameter of the roadway section was 4.6 m. 5 sets of U-shaped screw type connectors were set at each lap section. A set of strong draw plates was applied in the middle of the U-shaped steel to enhance the whole supporting capacity. The central angle of the round vault was 90°. To make the support have better bearing capacity and yieldable performance, the curve radius $R_1$ of the vault should meet $N = R_2/R_1$. The curve radius of the lateral arch was $R_2$. Therefore, when $N = 1.0$, the support had the best bearing capacity, and the space between two sheds was 800 mm.
Anchor bolt: the left-hand threaded steel bolt without longitudinal reinforcement was used for the anchor bolt. The yield strength was 600 MPa and the tensile strength was 800 MPa. The bolt had a diameter of 22 mm and a length of 2.4 m. The interval of the bolt was 0.8 m × 0.8 m. The resin full-column anchorage was
used, and the pretightening force of the bolt was 100 kN. The high-intensity tray was used with the size of 130 mm × 130 mm × 10 mm.

Anchor cable: the anchor cable had a diameter of 21.8 mm and a length of 7.3 m. The pretightening force of the anchor cable was 150 kN. A total of 7 cables were adopted. The high-intensity tray was used with the size of 300 mm × 300 mm × 16 mm.

Shotcrete and filling behind the support: the first spraying thickness is 50 mm, and the second spraying thickness is 100 mm.

Other supports: the W-type steel band had a thickness of 4 mm and a width of 250 mm. The self-made 10# diamond metal net with a mesh spacing of 40 mm × 40 mm was installed to protect the roof.

5.2. The Monitoring Scheme of the Roadway. In order to verify that the proposed new support method could effectively control the deformation and failure of the mining roadway with soft rocks under complex geological conditions, the roadway of the replacement workface of S2S2 FMCF in Xiaokang Coal Mine was taken as the example. 5 observation stations were distributed evenly in the roadway to monitor the surface displacement of the soft-rock roadway under the mining influence. The crossing method was also applied to monitor the rib-to-rib convergence and the roof-to-floor convergence. Figure 14 shows the specific monitoring method.

5.3. The Roadway Deformation Monitoring. The support quality of the roadway was judged by comparing the monitoring data with those of the original data. The underground roadway deformation was monitored continuously, and the rib-to-rib convergence and roof-to-floor convergence were monitored and given every other day, as shown in Figure 15.

Figure 15 indicates that

(1) Within 20 days of roadway monitoring, the rib-to-rib convergence was 616 mm, 545 mm, 467 mm, 340 mm, and 581 mm from No. 1 to No. 5 observation points, respectively. That of original support scheme was 2182.5 mm. Therefore, the deformation of the ribs was effectively controlled.

(2) Within 20 days of roadway monitoring, the roof-to-floor convergence was 450 mm, 438 mm, 348 mm, 441 mm, and 570 mm from No. 1 to No. 5 observation points, respectively. Compared with the original support scheme with a roof separation of 1029 mm and a floor heave of 1045 mm, the roadway roof and floor deformations were well controlled.

The obtained roadway deformation laws verify that the new support scheme could effectively control the surrounding rock deformation.

6. Conclusions

Based on the on-site monitoring and numerical simulation of the original roadway support effect, the U-shaped steel support, the anchor cable, and the bolt were optimized and verified, a new full-section combined support system of “belt-cable-mesh-shotcrete and U-shaped steel-filling behind the support” was proposed, and the support effects were simulated and in situ measured. The main conclusions are as follows:

(1) The roadway in the S2S2 working face underwent serious deformation and damage with a rib-to-rib convergence of 2183 mm, a roof separation of 1029 mm, and a floor heave of 1045 mm. In addition, it was the overload pressure that caused the failure of the U-shaped steel support.

The in situ measurement and simulation results indicated that it was the unreasonable roadway section and the failure control of the floor heave that weakened the self-supporting capacity of the surrounding rock, caused the complex surrounding rock stress, and finally resulted in the failure of the initial soft-rock roadway support.

(2) For optimization, the roadway section in the replacement FMCF was changed from arch to circle and a new full-section combined support scheme of “belt-cable-mesh-shotcrete and U-shaped steel-filling behind the support” was proposed.

The redesigned U-shaped steel support was verified by simulation and it exhibited high adaptability to different types of surrounding rock stress, and the roadway deformation could be effectively controlled within 770 mm. The support parameters of the belt and cable were determined by simulation with the pretightening theory.

(3) The optimized full-section combined support scheme was practiced and applied in the roadway of the replacement FMCF. In addition, the in situ measured rib-to-rib convergence and roof-to-floor convergence were both controlled within 600 mm, i.e., the roadway deformation and failure were controlled effectively.

Data Availability

The data used to support the findings of this study are included within the article.

Conflicts of Interest

The authors declare that they have no conflicts of interest.

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