ON PITFALLS OF MEASURING OCCLUSION ROBUSTNESS THROUGH DATA DISTORTION

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ABSTRACT

Over the past years, the crucial role of data has largely been shadowed by the field’s focus on architectures and training procedures. We often cause changes to the data without being aware of their wider implications. In this paper we show that distorting images without accounting for the artefacts introduced leads to biased results when establishing occlusion robustness. To ensure models behave as expected in real-world scenarios, we need to rule out the impact added artefacts have on evaluation. We propose a new approach, iOcclusion, as a fairer alternative for applications where the possible occluders are unknown.

1 INTRODUCTION

Correctly assessing the ability of a model to perform despite input alterations is crucial for obtaining reliable systems. Despite their incontestable success in a number of visual tasks, deep models are not fully trusted for real-world applications because of their sensitivity to input changes. This is an active area of research and proposed solutions are both at a data level (DeVries & Taylor, 2017; Yun et al., 2019) as well as algorithm (Globerson & Roweis, 2006; Kortylewski et al., 2020; Zhu et al., 2019; Xu et al., 2020) level. A widely adopted method for measuring occlusion robustness is through the accuracy obtained after superimposing a rectangular patch on an image (Chun et al., 2020; Yun et al., 2019; Fawzi & Frossard, 2016; Yun et al., 2019; Zhong et al., 2020; Kokhlikyan et al., 2020). In this paper, we refer to this approach as CutOcclusion due to its similarity to the CutOut augmentation (DeVries & Taylor, 2017) and argue it can be misleading, especially in comparative studies and applications where there is no prior knowledge about the exact shape of the possible occluders. Subsequently, to address the unfairness observed, we introduce iOcclusion, a measure that could form the baseline for future robustness studies.

2 IS OCCLUSION ROBUSTNESS MEASURED FAIRLY?

To verify the existence of the aforementioned bias, we need to compare models with different behaviours. To do this in a controlled manner, we make use of data augmentation. We focus on two popular mixed-sample augmentations, MixUp (Zhang et al., 2017b) and CutMix (Yun et al., 2019). MixUp linearly interpolates between two images to obtain a new training example, while CutMix superimposes onto a sample a rectangular region taken from another image. We also use FMix due to its irregularly shaped masks sampled from Fourier space, which will play an important role in our analysis. See Section A of the Supplementary Material for samples obtained with each method. We train PreAct-ResNet18 (He et al., 2016) and VGG (Simonyan & Zisserman, 2014) models on CIFAR-10/100 (Krizhevsky et al., 2009), FashionMNIST (Xiao et al., 2017) with these above augmentations. See Section B for experimental details.

For the four types of models (basic, MixUp, FMix and CutMix) we look at the increase in misclassifications per category, when presented with CutOccluded images. That is, from the number of incorrect predictions of a model evaluated on modified data, we subtract the incorrect predictions when testing on original data. If one of the classes has a significant increase, this indicates that the distortion introduces features the model associates with that class. For all data sets, the basic model tends to wrongly predict a specific class, while between the augmented models at least one is
invariant to this distortion. For example, on CIFAR-10, the basic and MixUp models tend to mis-
classify CutOccluded images as “Truck” (Figure 1). This is not at all surprising, given that the strong
horizontal and vertical edges are highly indicative of this class. Section C contains more examples.

Admittedly, this experiment is not meant to provide a rigorous account of the bias and a compar-
ison between the precise extent of the bias identified in various models is not possible at this stage.
Nonetheless, it is sufficient to capture the broad phenomenon. Thus, by occluding images using
a particularly shaped patch one implicitly measures a model’s affinity to certain features, albeit
those features might be discriminative. This deems such a method inappropriate for fairly assessing
robustness. Moreover, we identify similar issues in the case of texture bias identification and aug-
mentation analyses. In the interest of space, we omit the results from the current paper, but believe
this observation calls for more principled uses of data distortion in model evaluation.

A related observation was made independently of us by Hooker et al. (2019) who note the pitfalls of
image manipulation in the context of interpretability methods. They focus on the distributional shift
induced when removing image regions to determine feature importance. That is, they point out that
when simply superimposing uniform patches over image features, it is difficult to assess how much of
the reduction in accuracy is caused by the absence of those features and how much is due to images
becoming out of distribution. To address this, the most important features both on train and test
data are masked out, closing the gap between the two sets. They then train and respectively evaluate
models on the newly generated images. Here we study a similar problem. We are interested in ruling
out the overlap between the model’s learned representations and the information that is introduced
by the robustness measurement method. Unlike for interpretability methods, the subject of occlusion
studies is the model itself and, as such, training with a modified version of the data is not a viable
option. In the following section we explore ways of overcoming this bias when measuring occlusion
robustness.

2.1 iOCLUSION

We propose a simple measure that aims to decouple the machine’s edge bias from the occlusion
robustness, which we refer to as “invariant Occlusion” (iOclusion). Invariant Occlusion reflects the
change in the interplay between performance on seen and unseen data. Formally,

\[
iOclusion_i = \left| \frac{A(D^i_{\text{train}}) - A(D^i_{\text{test}})}{A(D_{\text{train}}) - A(D_{\text{test}})} \right|
\]  

(1)

where \(A(D)\) denotes the accuracy on a given data set \(D\), and \(D^i\) is the data set resulting from
removing \(i\%\) pixels of each image. The intuition is that on train data robust models are less sensitive
to the artefacts of the occlusion policy for small levels of occlusion, resulting in a large difference
in accuracy from that on unseen data. The performance of both train and test gets close to random
as the percentage of sample occlusion approaches 90% and we expect the gap to fall off quicker
for less robust models. This change in interplay is taken with respect to the generalisation gap of
the model. Thus, the denominator plays a normalisation role such that the quality of the model fit
Table 1: iOcclusion and CutOcclusion at a 30% obstruction level. Note that there is a difference in scale and the two should not be directly compared. We are interested in how the methods situate the models with respect to each other. When measuring the robustness with CutOcclusion, RM3 appears significantly less robust than CutMix due to its sensitivity to patching with rectangles, while iOcclusion highlights the robustness specific to FMix-like masks.

|            | basic  | MixUp  | CutMix | FMix  | RM        | RM3        |
|------------|--------|--------|--------|-------|-----------|------------|
| CutOcclusion | 40.59±2.27 | 52.64±1.77 | 82.43±1.60 | 82.67±0.29 | 53.50±4.76 | 66.43±6.33 |
| iOcclusion  | 0.19±0.01  | 0.56±0.13  | 1.16±0.09  | 1.51±0.04  | 0.63±0.29  | 1.45±0.19  |

in itself does not interfere with the robustness measure. In this paper we choose to generate masks using Grad-CAM (Selvaraju et al., 2017), such that the area with most salient i% pixels is covered. It must be noted that this method implicitly assumes there could be multiple occluders. We also experiment with using rectangular or Fourier-sampled masks and conclude that although random masking makes the process noisier, the exact choice of masking method is of secondary importance.

In Figure 2 we evaluate the robustness using our method. Note that unlike the typical measure, iOcclusion is not necessarily a proper fraction. The higher robustness of FMix over CutMix is justified through the sparsity of FMix masking, as well as the way the two determine the size of the occluding patch. Although they sample the size from the same distribution, in CutMix part of the rectangle can be outside the image, which results in less occluded images overall. Thus, we will generally use the basic and FMix models as reference for least and most robust respectively.

2.2 Evaluation

Assessing the correctness of such a measure is difficult in the absence of a basic. For the rest of this section we will build varied experiments to attest the validity of our method. We begin by empirically confirming iOcclusion rules out the edge bias in CutOcclusion. We would like to train with an augmentation that has irregularly shaped masks, but at the same time doesn’t have the variation of FMix, which causes it to be insensitive to CutMix’s edges. To this end, we create two variations of FMix with which we train: RM (Random Mask) — where a single mask is sampled for the entire training; and RM3 — where for each batch one of three fixed masks is chosen uniformly at random. As for all our experiments, we do 5 repeats, for each one sampling different fixed masks. As desired, unlike FMix and CutMix, the models trained with the fixed-mask augmentation versions are highly sensitive to the edge artefacts of CutOcclusion (see Section E). Note that to allow a fairer comparison to other methods, for CutOcclusion we do not allow the obstructing patch to lie outside the image such that the fraction removed is exact. The results in Table 1 are obtained for a fraction of 0.3 pixels removed. Our measure reflects the robustness of training with three fixed random masks (RM3), situating it closer to masking methods rather than interpolative. Furthermore, iOcclusion captures the large variance in training with a fixed random mask, which shows they can range from providing almost masking-MSDA robustness to worse than MixUp.

Additionally, since occlusion in real-life scenarios could also be caused by objects that have a texture of their own, an appropriate measure must not be sensitive to the occluder’s pattern. We verify this by superimposing patches from images belonging to a different data set. For this, we perform the same operation on input as mixed-sample masking MSDAs, where the mask is given by Grad-CAM. We choose to mask with images from different data sets to avoid the side-effects of samples belonging to two classes simultaneously. The randomness introduced by the texture is naturally making the the process noisier. Nonetheless, we find again iOcclusion to better rule out the specifics of the occluding patch, whereas CutOcclusion provides significantly different results to its uniform variation of FMix, which causes it to be insensitive to CutMix’s edges. To this end, we create two versions of FMix with which we train: RM (Random Mask) — where a single mask is sampled for the entire training; and RM3 — where for each batch one of three fixed masks is chosen uniformly at random. As for all our experiments, we do 5 repeats, for each one sampling different fixed masks. As desired, unlike FMix and CutMix, the models trained with the fixed-mask augmentation versions are highly sensitive to the edge artefacts of CutOcclusion (see Section E). Note that to allow a fairer comparison to other methods, for CutOcclusion we do not allow the obstructing patch to lie outside the image such that the fraction removed is exact. The results in Table 1 are obtained for a fraction of 0.3 pixels removed. Our measure reflects the robustness of training with three fixed random masks (RM3), situating it closer to masking methods rather than interpolative. Furthermore, iOcclusion captures the large variance in training with a fixed random mask, which shows they can range from providing almost masking-MSDA robustness to worse than MixUp.

Another problem that occurs when purely looking at post-masking accuracy is weaker models would erroneously appear less robust. We show this by reversing the problem: we evaluate the same model on two subsets of the CIFAR-100 data set: typical and atypical images as categorised by Feldman & Zhang (2020). Each tail example from the train set has a corresponding one in the test set. CutOcclusion would indicate that models are significantly more robust to occluding typical examples (see Figure 3). However, a closer analysis makes us doubt this conclusion. The raw accuracy on both train and test data for tail examples is lower than for the typical ones and the decrease in performance...
Figure 3: CutOcclusion (left) and iOcclusion (right) for the basic and FMix models on two subsets of the same data set, which we refer to as tail and typical. Evaluating the models with iOcclusion on the two types of samples leads robustness levels that do not differ outside the margin of error. However, CutOcclusion finds the models to be less robust on tail data.

Table 2: Robustness to occluding with patches covering 50% of each image (for a full range of percentages, see Section F). The models are trained with and without masking augmentation on data with randomised labels. CutOcclusion makes no difference between regular and augmented training.

|                | basic random | FMix random | FMix clean |
|----------------|--------------|-------------|------------|
| CutOcclusion   | 10.24 ± 0.27 | 9.78 ± 0.18 | 63.63 ± 4.54 |
| iOcclusion     | 14.63 ± 1.12 | 47.94 ± 19.84 | 82.36 ± 10.06 |

when masking out image regions is the same for the two subsets. By definition, iOcclusion allows a fair comparison of robustness regardless of the overall performance of a model.

Lastly, we train models on CIFAR-10 with randomly assigned labels as is done in Zhang et al. (2017a) with and without FMix, until examples are memorised. Since all labels are corrupted, the accuracy on the test set before and after occlusion is no greater than random. However, the robustness of the augmentation-trained model can be seen on the training data, as captured by our metric. On the other hand, CutOcclusion makes no distinction between learning with regular and augmented data (Table 2). Despite being such a peculiar case, it shows the comprehensiveness gained by accounting for the degradation on test data in relation to that on train.

Thus, as we evidenced through controlled experiments, there are many cases that CutOcclusion does not properly address. From a model analysis perspective, correctly assessing the occlusion robustness could lead to better understanding and development of models and training procedure. Equally important, it has applicability for real-world deployments where no prior knowledge exists about the possible shapes of the obstructions. The strength of the bias will depend on the data in question. Thus, some applications will be more heavily affected than others. However, we have seen that for natural images as is the case for CIFAR-10 and CIFAR-100 or ImageNet (Russakovsky et al., 2015), this bias does exist. We believe the edge artefacts are very likely to interfere with learned representations since they are such fundamental features. Thus, accounting for the bias is necessary to ensure a correct robustness assessment.

3 Conclusions

Distorting data without investigating its broader effects is particularly problematic when applied in analyses, as is the case of occlusion robustness measurement. We show the typical approach, CutOcclusion, is biased. This deems it inappropriate for evaluating models for real-world applications, where there is a variety of possible occluding objects. We propose iOcclusion as a basic for future robustness studies and design a number of experiments to validate it. In a broader sense, the purpose of our paper is to encourage better practice when dealing with data distortions.
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Supplementary Material

A Augmentation Examples

Figure 4 provides examples of new samples obtained with MixUp, CutMix, and FMix. For each pair of images, we sample a mixing coefficient $\lambda \sim \text{Beta}(1, 1)$ for all three augmentations. For a large value of $\lambda$, as is the case in the first column, it can be seen that CutMix covers less of Image 1 than FMix. As mentioned in the main body of the paper, this is because CutMix allows the masking patch to lay outside of the image.

B Experimental Details

Throughout the paper, we use PreAct-ResNet18 (He et al., 2016) models, trained for 200 epochs with a batch size of 128. For the MSDA parameters we use the same values as Harris et al. (2020). All models are augmented with random crop and horizontal flip and are averaged across 5 runs. We optimise using SGD with 0.9 momentum, learning rate of 0.1 up until epoch 100 and 0.001 for the rest of the training. This is due to an incompatibility with newer versions of the PyTorch library of the official implementation of Harris et al. (2020), which we use as a starting point. However, the difference in learning rate schedule between our work and prior art does not affect our findings since we are not introducing a new method to be applied at training time. In our case, it is sufficient to show that the bias exists in at least one configuration. The models were trained on either one of the following: Titan X Pascal, GeForce GTX 1080ti or Tesla V100. For the analysis, a GeForce GTX 1050 was also used.

Training Models

The code for model training is largely based on the open-source official implementation of FMix, which also includes those of MixUp, CutOut, and CutMix. For the experiment where we use the reformulated objective to combine data sets, instead of mixing with a permutation of the batch, as it is done in the original implementation of the mixed-augmentations, we now draw a batch form the desired data set. To ensure a fair comparison, for the basic we also perform inter-batch mixing.
Evaluating Robustness

For the CutOcclusion measurement, we modify open-source code to restrict the occluding patch to lie within the margins of the image to be occluded. This is to ensure that the mixing factor $\lambda$ matches the true proportion of the occlusion. For iOcclusion, the implementation of Grad-CAM is again adapted from publicly available code. With both methods, we evaluate 5 instances of the same model and average over the results obtained.

The added computation time of iOcclusion over the regular CutOcclusion for a fixed occlusion fraction is that of performing Grad-CAM on train and test data, as well as evaluating on the latter. With a batch size of 128, this takes under half an hour.

Analysis of Wrong Predictions

This section provides visual results of the experiments carried out to identify whether CutOcclusion provides biased results. We reintroduce the experiment here. For each class, when presented with regular test data, we count the number of times a sample was incorrectly identified as belonging to that class. We subtract the obtained values from the number of misidentifications on distorted data. Figure 6 shows results for the CIFAR-10 data set when occluding with uniform patches, while Figure 5 shows results for the same problem but where occluding is done with patches corresponding to images from the CIFAR-100 data set. We mix with images from a different data set to avoid issues arising from an image belonging to two classes simultaneously. In Section C, we also show results for more data sets and architectures, while Section I contains the increase in wrong predictions obtained for the RM and RM3 models.
Figure 6: Difference between wrongly predicted classes when testing on original data versus CutOut images. The evaluated models from left to right, top to bottom are trained on CIFAR-10 with: no mixed-data augmentation (basic), MixUp, CutMix, and FMix.
D  TRAINING WITH FIXED RANDOM MASKS

Figure 7 gives the results for CutOcclusion and iOcclusion for training with 1 or 3 random masks sampled from Fourier space. We provide CutMix and MixUp as references and exclude the basic and FMix for visual clarity.

E  OCCLUDING WITH IMAGES FROM ANOTHER DATA SET

Since CutOcclusion does not account for the bias introduced by the occluding method, it is expected that changing the patch to a non-uniform one would greatly affect the results. For CIFAR-10 models, Figure 8 presents the results of occluding with CIFAR-100 images.

F  RANDOMISING LABELS

To assess the sensitivity of CutOcclusion and iOcclusion to the overall performance of the model, we also experiment with randomising all the labels of the CIFAR-10 data set. When evaluated on the unaugmented training data, all the basic models achieve 100% accuracy, while the FMix models reach 99.99 ± 0.01. Figure 9 gives the iOcclusion scores for these models.

G  DISTRIBUTION OF WRONG PREDICTIONS FOR OTHER DATA SETS AND ARCHITECTURES

In this section we include examples of identified bias for more data sets and architectures as follows: Figure 10 for CIFAR-100, Figure 11a for Fashion MNIST (Xiao et al., 2017) and Figure 11b for VGG-16 (Simonyan & Zisserman, 2014) models. In subsequent sections of the paper we also experiment with Tiny ImageNet and ImageNet data sets, as well as BagNet models.

H  CIFAR-100 RESULTS FOR CUTOCCLUSION AND IOCLUSION

Although, as stated in the main paper, we believe it is difficult to make a direct comparison between CutOcclusion and iOcclusion, Figure 12 gives the scores for the two methods on the CIFAR-100 data set. Again, CutOcclusion only assesses the robustness against contiguous patches, making no difference between CutMix and FMix. More importantly, iOcclusion captures the more rapid fall of the masking methods, which in the case of CutOcclusion appear significantly more robust than basic due to their higher invariance to the artefacts introduced.
Figure 8: Comparison of metric sensitivity to textured occlusion. Regular occlusion refers to superimposing uniform patches over CIFAR-10 images, while mixing refers to superimposing part of CIFAR-100 samples. Mixing CutOcclusion provides significantly different results to its regular counterpart.
Figure 9: iOcclusion results for training with clean and corrupted labels for basic and FMix augmentation.

Figure 10: CIFAR-100 results for the basic model for CutOut images.
Figure 11: PreAct-ResNet18 on Fashion-MNIST (left) and VGG-16 on CIFAR-10 (right) when occluding with black patches.

Figure 12: CutOclusion (left) and iOclusion (right) on the CIFAR-100 data set. Note again that there is a difference in scale and for comparing the two methods we look at how they position the models with respect to each other.
Figure 13: Distribution of the increase in wrong predictions when evaluating on CutMix images for
the model trained with one random mask (left) and three random masks (right).

I BIAS OF FIXED RANDOM MASKS

When training with either one or three fixed random masks sampled from Fourier space, the CIFAR-
10-trained models are still predominantly predicting CutMix images as “Truck”, as depicted in Figure[13]. Again, the superimposed patches are taken from CIFAR-100 images.