Super-\(A\)-polynomial for knots and BPS states

Hiroyuki Fuji\(^a,b\), Sergei Gukov\(^a,c\), Piotr Sułkowski\(^a,d,e,*\)

\(^a\) California Institute of Technology, Pasadena, CA 91125, USA  
\(^b\) Nagoya University, Department of Physics, Graduate School of Science, Furo-cho, Chikusa-ku, Nagoya 464-8602, Japan  
\(^c\) Max-Planck-Institut für Mathematik, Vivatsgasse 7, D-53111 Bonn, Germany  
\(^d\) Institute for Theoretical Physics, University of Amsterdam, Science Park 904, 1090 GL, Amsterdam, The Netherlands  
\(^e\) Faculty of Physics, University of Warsaw, ul. Hoża 69, 00-681 Warsaw, Poland  

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Abstract

We introduce and compute a 2-parameter family deformation of the \(A\)-polynomial that encodes the color dependence of the superpolynomial and that, in suitable limits, reduces to various deformations of the \(A\)-polynomial studied in the literature. These special limits include the \(t\)-deformation which leads to the "refined \(A\)-polynomial" introduced in the previous work of the authors and the \(Q\)-deformation which leads, by the conjecture of Aganagic and Vafa, to the augmentation polynomial of knot contact homology. We also introduce and compute the quantum version of the super-\(A\)-polynomial, an operator that encodes recursion relations for \(\mathcal{S}\)'-colored HOMFLY homology. Much like its predecessor, the super-\(A\)-polynomial admits a simple physical interpretation as the defining equation for the space of SUSY vacua (= critical points of the twisted superpotential) in a circle compactification of the effective 3d \(\mathcal{N} = 2\) theory associated to a knot or, more generally, to a 3-manifold \(M\). Equivalently, the algebraic curve defined by the zero locus of the super-\(A\)-polynomial can be thought of as the space of open string moduli in a brane system associated with \(M\). As an inherent outcome of this work, we provide new interesting formulas for colored superpolynomials for the trefoil and the figure-eight knot.

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* Corresponding author at: California Institute of Technology, Pasadena, CA 91125, USA.  
E-mail address: psulkows@theory.caltech.edu (P. Sułkowski).

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1. Introduction and summary

The exact solution of $SL(2, \mathbb{C})$ Chern–Simons theory with a Wilson loop is determined by an algebraic curve \[ C: \{(x, y) \in \mathbb{C}^* \times \mathbb{C}^* \mid A(x, y) = 0\}, \] namely the zero locus of the $A$-polynomial [2], which plays a role similar to that of the Seiberg–Witten curve in $\mathcal{N} = 2$ gauge theory. Various aspects of the $SL(2, \mathbb{C})$ Chern–Simons partition function and its relation to algebraic curves that appear in topological strings and supersymmetric gauge theories were further studied in [3–13].

In particular, quantization of Chern–Simons theory turns a classical polynomial $A(x, y)$ into an operator of the form
\[ \hat{A}(\hat{x}, \hat{y}; q) = a_k \hat{y}^k + a_{k-1} \hat{y}^{k-1} + \cdots + a_1 \hat{y} + a_0, \]\[ \hat{x} = q^{1/2} \hat{x} \hat{y} \] that follows directly from the symplectic structure on the classical phase space of Chern–Simons theory (see [14] for a review). As a result, the algebraic curve (1.1) that describes classical solutions in $SL(2, \mathbb{C})$ Chern–Simons theory upon quantization turns into a Schrödinger-like equation
\[ \hat{A}Z_{CS} = 0, \] which leads to a set of recursion relations on polynomial invariants of the knot $K$. Indeed, depending on whether the holonomy eigenvalues $x$ and $y$ take values in the maximal torus of the group $G = SU(2)$ or its complexification $G_{\mathbb{C}} = SL(2, \mathbb{C})$, the same Eq. (1.4) applies equally well to Chern–Simons theory with the compact gauge group $SU(2)$ that computes the colored Jones polynomial $J_n(K; q)$ and to its analytic continuation that localizes on $SL(2, \mathbb{C})$ flat connections.

In the former case, it leads to the so-called quantum volume conjecture [1]:
\[ \hat{A}(\hat{x}, \hat{y}; q) = 0 \iff a_k J_{n+k}(q) + \cdots + a_1 J_{n+1}(q) + a_0 J_n(q) = 0 \] which in the mathematical literature was independently proposed around the same time [15] and is known as the AJ-conjecture. The operators $\hat{x}$ and $\hat{y}$ act on the colored Jones polynomial as
\[ \hat{x} J_n = q^n J_n, \quad \hat{y} J_n = J_{n+1}. \] In particular, one can easily verify that these operations obey the commutation relation (1.3) and that the Schrödinger-like equation (1.4) with $\hat{A}(\hat{x}, \hat{y}; q)$ of the form (1.2) is equivalent to the recursion relation (1.5) that describes the “color behavior” of the colored Jones polynomial.

Besides the “non-commutative” deformation (1.2)–(1.3), the $A$-polynomial also admits two commutative deformations that in a similar way encode the “color behavior” of two natural generalizations of the colored Jones polynomial: the $t$-deformation that corresponds to the categorification of colored Jones invariants [16] and $Q$-deformation that corresponds to extending $J_n(K; q)$ to higher rank knot polynomials [17]. A natural question is whether these two deformations can be combined in a single unifying structure?

The answer turns out to be “yes” and we call this unifying knot invariant the super-$A$-polynomial since it describes how the $S^n-1$-colored superpolynomials $\mathcal{P}_n(a, q, t)$ depend on
Fig. 1. Various specializations of the super-$A$-polynomial.

color, \( i.e. \) on the representation \( R = S^{n-1} \), much in the same way as \( A \)-polynomial does it for the colored Jones polynomial.\(^1\) We remind that, in the context of BPS states, the superpolynomial is defined as a generating function of refined open BPS invariants on a rigid Calabi–Yau 3-fold \( X \) in the presence of a Lagrangian brane supported on \( L \subset X \):

\[
P(a,q,t) := \text{Tr}_{BPS}^\text{ref} a^\beta q^P t^F, \quad \beta \in H_2(X, L)
\]  

(1.7)

and, in application to knots, the superpolynomial \( P(K; a,q,t) \) is defined as a Poincaré polynomial of the triply-graded homology theory \( \mathcal{H}(K) \) that categorifies the HOMFLY polynomial \( P(K; a,q) \), see [18] for details. According to the conjecture of [19], these two definitions give the same result when \( X \) is the total space of the \( \mathcal{O}(-1) \oplus \mathcal{O}(-1) \) bundle over \( \mathbb{C}P^1 \) and \( L \) is the Lagrangian submanifold determined by the knot \( K \subset S^3 \), cf.\([20–22]\). Lagrangian branes of multiplicity \( r = n-1 \) yield the so-called “\( n \)-colored” version of the superpolynomial which, in the context of knot homologies, was recently introduced in [23],

\[
P_n(K; a,q,t) := \sum_{i,j,k} a^i q^j t^k \dim \mathcal{H}^{S^{n-1}}_{i,j,k}(K),
\]

(1.8)

as a Poincaré polynomial of a triply-graded homology theory categorifying the \( S' \)-colored HOMFLY polynomial (see also [16,24,25]).

The main goal of the present paper is to explain that \( S^{n-1} \)-colored superpolynomials \( P_n(K; a,q,t) \) depend on color (\( i.e. \) on the representation \( R = S^{n-1} \)) in a simple and controllable way, governed by the super-\( A \)-polynomial \( A^{\text{super}}(x,y;a,t) \) and by its quantization \( \hat{A}^{\text{super}}(\hat{x},\hat{y};a,q,t) \). Specifically, based on the physics arguments and the study of examples, we propose the following analog of the generalized volume conjecture [1] or its refined version [16]:

**Conjecture 1.** In the limit

\[
q = e^{\hbar} \to 1, \quad a = \text{fixed}, \quad t = \text{fixed}, \quad x = q^n = \text{fixed}
\]

(1.9)

\(^1\) In fact, in the context of open BPS invariants, the super-\( A \)-polynomial has already been computed and studied in [16, Section 4] for several prominent Calabi–Yau geometries.
Table 1
Quantum super-A-polynomial and its specializations lead to recursion relations for various $\mathfrak{S}^n$-colored knot invariants.

| Quantum operator | Provides recursion for | Classical limit |
|------------------|------------------------|-----------------|
| $\hat{A}^{\text{super}}(\hat{x}, \hat{y};a,q,t)$ | colored superpolynomial | $A^{\text{super}}(x,y;a,t)$ |
| $\hat{A}^{\text{ref}}(\hat{x}, \hat{y};q,t)$ | colored $\mathfrak{sl}(2)$ homology | $A^{\text{ref}}(x,y;a,t)$ |
| $\hat{A}^{\text{Q-def}}(\hat{x}, \hat{y};a,q)$ | colored HOMFLY | $A^{\text{Q-def}}(x,y;a)$ |
| $\hat{A}(\hat{x}, \hat{y};q)$ | colored Jones | $A(x,y)$ |

the $n$-colored superpolynomials $\mathcal{P}_n(K; a, q, t)$ exhibit the following “large color” behavior:

$$\mathcal{P}_n(K; a, q, t) \overset{n \to \infty}{\sim} \exp \left( \frac{1}{\hbar} \int \log y \frac{dx}{x} + \cdots \right)$$

(1.10)

where ellipsis stand for regular terms (as $\hbar \to 0$) and the leading term is given by the integral on the zero locus of the super-A-polynomial, cf. (1.1):

$$A^{\text{super}}(x,y;a,t) = 0.$$  

(1.11)

Moreover, just like the ordinary $A$-polynomial has its quantum analog (1.2), the super-$A$-polynomial is a characteristic polynomial of a quantum operator $\hat{A}^{\text{super}}(\hat{x}, \hat{y};a,q,t)$ that combines commutative $t$- and $a$-deformations with the non-commutative $q$-deformation (1.3). This “quantum super-A-polynomial” is the most advanced form of life in the world of $A$-polynomials and knot homologies since it contains information about all deformations of the $A$-polynomial and about all $n$-colored superpolynomials:

\[ \text{Conjecture 2. For a given knot } K, \text{ the colored superpolynomial } \mathcal{P}_n(K; a, q, t) \text{ satisfies a recurrence relation of the form (1.5):} \]

$$a_k \mathcal{P}_{n+k}(K; a, q, t) + \cdots + a_1 \mathcal{P}_{n+1}(K; a, q, t) + a_0 \mathcal{P}_n(K; a, q, t) = 0$$  

(1.12)

where $\hat{x}$ and $\hat{y}$ act on $\mathcal{P}_n(K; a, q, t)$ as in (1.6), and where the rational functions $a_i \equiv a_i(\hat{x}, a, q, t)$ are the coefficients of the “quantum super-A-polynomial”

$$\hat{A}^{\text{super}}(\hat{x}, \hat{y};a,q,t) = \sum_i a_i(\hat{x}, a, q, t) \hat{y}^i,$$  

(1.13)

whose characteristic polynomial is $A^{\text{super}}(x,y;a,t)$.

As in (1.5), sometimes we informally write (1.12) in the compact form

$$\hat{A}^{\text{super}}\mathcal{P}^*_n(K; a, q, t) = 0,$$  

(1.14)

which is a quantum version of the classical curve (1.11).

The superpolynomial unifies many polynomial and homological invariants of knots that can be obtained from it via various specializations, applying differentials, etc. For example, for $H$-thin knots the specialization to $a = q^2$ yields the Poincaré polynomial of the colored $\mathfrak{sl}(2)$ knot homology. Therefore, if $K$ is a thin knot (e.g. if $K$ is a two-bridge knot), in the limit $a = q^2$ we

\[ \text{2 That, in turn, contain information about colored } \mathfrak{sl}(N) \text{ knot homologies [23].} \]
expect (1.10) and (1.12) to reproduce the corresponding versions of the refined volume conjectures proposed in [16]. In particular,
\[
\hat{A}^{\text{super}}(\hat{x}, \hat{y}; a = q^2, q, t) = \hat{A}^{\text{ref}}(\hat{x}, \hat{y}; q, t),
\]
(1.15)
and, via further specialization to the classical limit \(q = 1\),
\[
A^{\text{super}}(x, y; a = 1, t) = A^{\text{ref}}(x, y; t).
\]
(1.16)

Similarly, the specialization of the superpolynomial \(P_n(K; a, q, t)\) to \(t = -1\) yields the HOMFLY polynomial or, in the problem at hand, the colored HOMFLY polynomial [23]. Therefore, at \(t = -1\) the recursion relation (1.12) should reduce to the recursion relation for the \(S^n-1\)-colored HOMFLY polynomial, whose characteristic variety — called the \(Q\)-deformed \(A\)-polynomial in [17] — must be contained in \(A^{\text{super}}(x, y; a, t = -1)\) as a factor. To avoid clutter, we include possible extra factors inherited\(^3\) from \(A^{\text{super}}(x, y; a, t)\) in the definition of the \(Q\)-deformed \(A\)-polynomial, so that
\[
A^{\text{super}}(x, y; a, t = -1) = A^{Q\text{-def}}(x, y; a).
\]
(1.17)

Moreover, the authors of [17] proposed an important conjecture that offers a new way of looking at this polynomial (that, in our Fig. 1, occupies the right corner) and identifies it with the augmentation polynomial of knot contact homology [26]. Since we strongly believe this conjecture (and present some evidence for it below), we are going to keep the notation \(A^{Q\text{-def}}(x, y; a)\) but use the names “\(Q\)-deformed \(A\)-polynomial” and “augmentation polynomial” interchangeably in the rest of this paper (often we use both). In fact, one justification for this comes from the fact (see [26, Proposition 5.9] for a proof) that the classical augmentation polynomial, when specialized further to \(a = 1\), reduces to the ordinary \(A\)-polynomial, possibly with some extra factors, which altogether we denote simply by \(A(x, y)\):
\[
A^{\text{super}}(x, y; a = 1, t = -1) = A^{Q\text{-def}}(x, y; a = 1) = A(x, y),
\]
(1.18)
as it should in order to fit perfectly in the diagram in Fig. 1.

Therefore, our super-\(A\)-polynomial \(A^{\text{super}}(x, y; a, t)\) can be viewed, on one hand, as a “refinement” of the augmentation polynomial \(A^{Q\text{-def}}(x, y; a)\) and, on the other hand, as a “\(Q\)-deformation” of the refined \(A\)-polynomial \(A^{\text{ref}}(x, y; t)\), see Fig. 1. Since both of these specializations have been recently computed for a number of simple knots [16,17,25,26], the time is just right for upgrading these results to the full-fledged super-\(A\)-polynomials, see Table 2.

Another interesting specialization of the super-\(A\)-polynomial involves setting \(x = 1\) and provides a much more direct relation between the superpolynomial \(P(a, q, t)\) and the super-\(A\)-polynomial of the same knot, cf. Table 2 (as well as Eq. (3.147) in [16]):
\[
A^{\text{super}}(x = 1, y; a, t) = y^k + y^{k-1}P(a, q = 1, t).
\]
(1.19)

In other words, it means that super-\(A\)-polynomials itself is not much different from the superpolynomial and contains information about the total dimension of the HOMFLY homology and also about the most interesting homological \(t\)-grading. Further discussion of this property of the super-\(A\)-polynomial and related aspects of the colored HOMFLY homology will be discussed elsewhere. Note, that specializing further to \(a = 1\) or \(t = -1\), one can obtain similar properties

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\(^3\) Some of these extra factors will be explained below, in Section 4.
of the polynomials $A^{\text{ref}}(x, y; t)$ or $A^{Q-\text{def}}(x, y; a)$ which, however, lose some important information (e.g. in the specialization to $t = -1$ many terms can cancel, so that $A^{Q-\text{def}}(x = 1, y; a)$ does not know about the total dimension of the HOMFLY homology).

2. Case studies

In this section we illustrate the ideas and the validity of the two conjectures presented in the introduction in explicit examples of various knots. We start with the simplest example of the unknot, and then discuss non-trivial examples of hyperbolic knots, such as figure-eight knot, and the entire family of $(2, 2p + 1)$ torus knots, with a special emphasis on the trefoil. In each case we start our considerations by providing explicit and general formulas for $S^{n-1}$-colored superpolynomials $P_n(a, q, t)$, which are very interesting in their own right. In particular, we provide new expressions for colored superpolynomials for the trefoil and figure-eight knots, in a form which is particularly well suited to derive recursion relations which they satisfy and analyze their asymptotics. Taking advantage of these representations, subsequently we derive classical and quantum super-$A$-polynomials for these knots, discuss their properties and, in appropriate limits, relate them to other more familiar polynomials.

2.1. Unknot

Let us start with the simplest example of the unknot, which we often denote as $\hat{0}$. Despite its simplicity, this is still an interesting and important example; as we will see, some objects associated to the unknot, which are trivial in the non-refined and non-super case, become rather non-trivial when $t$- or $a$-dependence is turned on.

We recall that in the unknot case we must consider unreduced (or, sometimes also called “unnormalized”) knot polynomials — in particular, unreduced colored superpolynomial $\tilde{P}_n(a, q, t)$ — since, by definition, reduced polynomials are normalized by the value of the unknot, so that $P_n(\hat{0}; a, q, t) = 1$. From the viewpoint of the (refined) Chern–Simons theory the unreduced colored superpolynomial is defined as the ratio of partition functions on $S^3$ in the presence and absence of a knot. In case of the unknot this ratio is given by the Macdonald polynomial, and after the change of variables

$$a = A \left(\frac{q_1}{q_2}\right)^{3/2}, \quad q = \frac{1}{q_2}, \quad t = -\sqrt{\frac{q_2}{q_1}},$$

(2.1)
we find that the $S^{n-1}$-colored superpolynomial $\tilde{P}_n(\hat{\Upsilon}; a, q, t) \equiv \tilde{P}^{S^{n-1}}(\hat{\Upsilon}; a, q, t)$ reads

$$\tilde{P}_n(\hat{\Upsilon}; a, q, t) = \frac{Z_{SU(N)}^{ref}(S^3, \hat{\Upsilon}; A^{n-1}; q_1, q_2)}{Z_{SU(N)}^{ref}(S^3, q_1, q_2)} = M_{A^{n-1}}(q_2^\varphi; q_1, q_2)
= (-1)^{n-1} q^{-\frac{n-1}{2}} t^{-\frac{3(n-1)}{2}} \frac{(-at^3; q)_{n-1}}{(q; q)_{n-1}}. \quad (2.2)$$

Note that, in our grading conventions, we need to consider Macdonald polynomials for anti-symmetric representations $\Lambda^{n-1}$, $q_2^\varphi = (q_2^\varphi)_{j=1,...,N}$ with $\varphi_j = \frac{N+1}{2} - j$, and $a = q_2^{N-3/2} q_1^{3/2}$, see [16] for more details. We also use a standard notation for the $q$-Pochhammer symbol, which has the following asymptotics

$$(x, q)_k = \prod_{i=0}^{k-1} (1 - x q^i) \sim e^{\frac{k}{2} (\text{Li}_2(x) - \text{Li}_2(x q^k))}. \quad (2.3)$$

Once the general expression for the colored superpolynomial is found and presented in an appropriate form, the next task is to find a recursion relation it satisfies. In particular, as the homological unknot invariant $(2.2)$ has a product form, we can immediately write down the recursion relation it satisfies:

$$\tilde{P}_n+1(\hat{\Upsilon}; a, q, t) = (-a^{-1} t^{-3} q)^{1/2} \frac{1 + at^3 q^{n-1}}{1 - q^n} \tilde{P}_n(\hat{\Upsilon}; q, t). \quad (2.4)$$

This means that the quantum super-$A$-polynomial for the unknot reads

$$\hat{A}_{\text{super}}(\hat{x}, \hat{y}; a, q, t) = (-a^{-1} t^{-3} q)^{1/2} (1 + at^3 q^{-1} \hat{x}) - (1 - \hat{x}) \hat{y}. \quad (2.5)$$

In the classical limit $q \to 1$ this operator reduces to the classical super-$A$-polynomial defined by

$$A_{\text{super}}(x, y; a, t) = (-a^{-1} t^{-3})^{1/2} (1 + at^3 x) - (1 - x) y. \quad (2.6)$$

The Newton polygon as well as the coefficients of monomials of this polynomial are shown in Fig. 2. On the other hand, in the unrefined limit $t = -1$ the relation $(2.5)$ takes the form

$$\hat{A}_{\text{Q-def}}(\hat{x}, \hat{y}; a, q) = (a^{-1} q)^{1/2} (1 - a q^{-1} \hat{x}) - (1 - \hat{x}) \hat{y}, \quad (2.7)$$

and specializing further to $q = 1$ we get the augmentation polynomial

$$A_{\text{Q-def}}(x, y; a) = a^{-1/2} (1 - ax) - (1 - x) y. \quad (2.8)$$

Interestingly, this polynomial does not factorize, and only in the limit of ordinary $A$-polynomial $a \to 1$ do we get a factorized form with $y - 1$ factor representing the abelian connection

$$A(x, y) = (1 - x)(1 - y). \quad (2.9)$$

It is instructive to show that the super-$A$-polynomial $(2.6)$ can be also derived from the asymptotic analysis of $(2.2)$. Indeed, using the asymptotics $(2.3)$, in the limit $(1.9)$ we can approximate $(2.2)$ as

$$P_n(\hat{\Upsilon}; a, q, t) = \exp \frac{1}{\hbar} \left( \log x \log(-a^{-1} t^{-3})^{1/2} + \text{Li}_2(x) - \text{Li}_2(-at^3 x) + \text{Li}_2(-at^3) - \frac{\pi^2}{6} + \mathcal{O}(\hbar) \right).$$
Fig. 2. Newton polygon for the super-$A$-polynomial of the unknot (left). Red circles denote monomials of the super-$A$-polynomial, and smaller yellow crosses denote monomials of its $a = -t = 1$ specialization. In this example both Newton polygons look the same, so that positions of all circles and crosses overlap. The coefficients of the super-$A$-polynomial are also shown in the matrix on the right. The role of rows and columns is exchanged in these two presentations: a monomial $a_{i,j} x^i y^j$ corresponds to a circle (resp. cross) at position $(i,j)$ in the Newton polygon, while in the matrix on the right it is shown as the entry $a_{i,j}$ in the $(i+1)$th row and in the $(j+1)$th column. These conventions are the same as in [16]. (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

from which identify the potential $\hat{\mathcal{W}} = \int \log y \frac{dx}{x}$ in (1.10) as

$$\hat{\mathcal{W}} = \log x \log((-a^{-1}t^{-3})^{1/2} + \text{Li}_2(x) - \text{Li}_2(-a t^3 x) + \text{Li}_2(-a t^3) - \frac{\pi^2}{6}.$$  

(2.10)

Differentiating it with respect to $x$, we now obtain

$$y = e^{x \hat{\mathcal{W}}} \frac{dx}{x} = (-a^{-1}t^{-3})^{1/2} \frac{1 + at^3 x}{1 - x},$$

(2.11)

which reproduces the defining equation of the super-$A$-polynomial given in (2.6). We also note that for $a = -t = 1$ the potential $\hat{\mathcal{W}}$ vanishes, which is related to the factorization occurring in (2.9) and can be attributed to the fact that the only $SL(2, \mathbb{C})$ flat connections on a solid torus (i.e., complement of the unknot) are abelian flat connections. When $a \neq 1$ or $t \neq -1$, the potential $\mathcal{W}$ is nonzero and presumably can be interpreted as a contribution of “deformed” abelian flat connections. It would be interesting to pursue this interpretation further.

2.2. Figure-eight knot

In this section we illustrate the program presented in the Introduction in the example of the figure-eight knot, also denoted $4_1$. This is a hyperbolic knot, and we stress that it provides a highly non-trivial example, for which many simplifications common in the realm of torus knots (to be discussed in the following sections) do not occur.

To start with, we present the colored superpolynomial (1.7) for this knot, denoted $P_n(4_1; a, q, t)$, in the form most appropriate for finding its recursion relations (1.12). Then, we indeed find such recursion relations, thereby illustrating validity of Conjecture 2 and, in the classical limit $q \to 1$, we find the form of the (classical) super-$A$-polynomial (1.11). We also derive the same super-$A$-polynomial from the analysis of the asymptotics (1.10) of $P_n(4_1; a, q, t)$, thereby confirming the validity of Conjecture 1 for this knot. Finally, we discuss various properties of the classical and quantum super-$A$-polynomial and show that in appropriate limits various familiar results are reproduced.

The form of the superpolynomial for the $4_1$ knot was recently proposed in [25], in certain variables and a grading choice which were natural from the viewpoint of the quantization rule proposed in that paper. For our purposes it is more convenient to make a choice variables and grading conventions as in [16,23]. In Appendix A we summarize how the formula in [25] was
confirm the validity of the expression (2.12) in various special cases: with such a powerful tool, it is not hard to find the recursion, and in


to find a recursion relation satisfied by (2.12) we use the Mathematica package qZeil.m developed by [29]. With such a powerful tool, it is not hard to find the recursion, and in the notations of (1.13) it takes the following four-term form

\[
\hat{A}^{\text{super}}(\hat{x}, \hat{y}; a, q, t) = a_0 + a_1 \hat{y} + a_2 \hat{y}^2 + a_3 \hat{y}^3,
\]

where
Taking the classical limit super-asymptotic behavior of the colored superpolynomial (2.12). This is indeed the case. To show 

\[ z \text{ in Fig. 3, and the corresponding Newton polygon is given in Fig. 4.} \]

The coefficients of the monomials in this polynomial are assembled into a matrix form presented example in Fig. 2.

\[ \text{Fig. 3. Matrix form of the super-}\tilde{A}\text{-polynomial for the figure-eight knot. The conventions are the same as in the unknot example in Fig. 2.} \]

\[
\begin{pmatrix}
0 & -a & t & -a & t^2 & a & t^3 & -1 & 0 \\
0 & a & t & a & t^2 & a & t^3 & -a & t + a & t^2 & a & t^3 & 0 \\
-2 & a & t & 3 & -2 & a & t^2 & -2 & a & t^3 & -2 & a & t^4 & a & t^5 & a & t^2 \\
-2 & a & t^3 & 3 & 2 & a & t^4 & 2 & a & t^5 & 2 & a & t^6 & 2 & a & t^5 & a & t^2 \\
0 & a & t^3 & -2 & a & t^4 & a & t^5 & a & t^6 & -2 & a & t^7 & 2 & a & t^8 & a & t^8 \\
0 & 0 & -a & t^3 & -a & t^4 & a & t^3 & 0 & 0 & -a & t^4 & 10 & 0
\end{pmatrix}
\]

Taking the classical limit \( q \to 1 \) (and clearing the denominators), we find the following classical super-\( A \)-polynomial

\[
A^{\text{super}}(x; y; a, t) = a^2 t^5 (x - 1)^2 x^2 + at^2 x^2 (1 + at^3 x)^2 y^3 + at (x - 1)(1 + t (1 - t))x \\
+ 2at^3 (t + 1) x^2 - 2at^4 (t + 1) x^3 + a^2 t^6 (1 - t) x^4 - a^2 t^8 x^5 y \\
- \left( 1 + at^3 x \right) (1 + at (1 - t)) x + 2at^2 (t + 1) x^2 + 2at^4 (t + 1) x^3 \\
+ a^2 t^5 (t - 1) x^4 + a^3 t^7 x^5. \]

The coefficients of the monomials in this polynomial are assembled into a matrix form presented in Fig. 3, and the corresponding Newton polygon is given in Fig. 4.

According to Conjecture 1, we should be able to reproduce the same polynomial from the asymptotic behavior of the colored superpolynomial (2.12). This is indeed the case. To show this, we introduce the variable \( z = e^{hk} \). Then, in the limit (1.9) with \( z = \text{const} \) the sum over \( k \) in (2.12) can be approximated by the integral

\[
P_n(\mathbf{4}_1; a, q, t) \sim \int dz \, e^{\frac{1}{2}(i \hat{\mathcal{W}}(\mathbf{4}_1; z, x) + O(h))}. \]

The potential \( \hat{\mathcal{W}}(\mathbf{4}_1; z, x) \) can be determined from the asymptotics (2.3):

\[
\hat{\mathcal{W}}(\mathbf{4}_1; z, x) = \pi i \log z - \frac{\pi^2}{6} - (\log a + 2 \log t) \log z - \frac{1}{2} (\log z)^2
\]
Fig. 4. Newton polygon of the super-$A$-polynomial for the figure-eight knot and its $a = - t = 1$ limit. The conventions are the same as in Fig. 2.

\[ + \text{Li}_2(x^{-1}) - \text{Li}_2(x^{-1}z) + \text{Li}_2(-at) - \text{Li}_2(-at^3) + \text{Li}_2(-at^3z) - \text{Li}_2(z). \]  \hfill (2.16)

At the saddle point
\[
\left. \frac{\partial \tilde{W}(4_1; z, x)}{\partial z} \right|_{z = z_0} = 0
\]  \hfill (2.17)

it determines the leading asymptotic behavior (1.10), which at the same time is also computed by the integral along the curve (1.11), implying a key identity
\[
y = \exp \left( x \frac{\partial \tilde{W}(4_1; z_0, x)}{\partial x} \right). \]  \hfill (2.18)

Plugging the expression (2.16) to the above two equations we obtain the following system
\[
\begin{align*}
1 &= \frac{(x - z_0)(1 + atz_0)(1 + at^3xz_0)}{at^2xz_0(z_0 - 1)}, \\
y &= \frac{(x - 1)(1 + at^3xz_0)}{(1 + at^3x)(x - z_0)}. \hfill (2.19)
\end{align*}
\]

Eliminating $z_0$ from these two equations we indeed reproduce the super-$A$-polynomial (2.14). Overall, the above statements verify the validity of Conjectures 1 and 2 for the figure-eight knot.

The relation (1.19) can be checked explicitly from (2.12) and (2.14). The colored super-$A$-polynomial $\mathcal{P}_{n=2}(4_1; a, q, t)$ reduces under $q = 1$ limit
\[
\mathcal{P}(4_1; a, q = 1, t) = a^{-2}t^{-2} + t^{-1} + 1 + t + at^2. \]  \hfill (2.20)

On the other hand, $x = 1$ limit of the super-$A$-polynomial is listed in Table 11. Clearly the relation (1.19) holds for the $4_1$ knot.

Let us now discuss properties of the figure-eight super-$A$-polynomial determined above. First, we show that in appropriate limits it reproduces various known answers. As expected, for $t = -1$ and $a = 1$, the expression (2.14) reduces to
\[
A(x, y) = (x - 1)^2(y - 1)(x^2(y^2 + 1) - (1 - x - 2x^2 - x^3 + x^4)y), \]  \hfill (2.21)

which, apart from the $(x - 1)^2$ factor, reproduces the $A$-polynomial of $K = 4_1$, including the $(y - 1)$ factor representing the contribution of abelian flat connections. We stress that both
factorization and the explicit form of this abelian branch is seen only in the limit $a = -t = 1$ and is completely “mixed” with the other branches otherwise. In general the super-$A$-polynomial (2.14) does not factorize, as is also the case for the unknot and torus knots that will be discussed next.

More generally, after a simple change of variables

$$Q = a, \quad \beta = x, \quad \alpha = y \frac{1 - \beta Q}{Q (1 - \beta)},$$

(2.22)

and for $t = -1$ we find that (2.14) becomes

$$A^{Q \text{-def}}(\alpha, \beta, Q) = Q^2 (1 - \beta)^2 \left[ (\beta^2 - Q \beta^3) + (2\beta - 2Q^2 \beta^4 + Q^2 \beta^5 - 1) \alpha \right]
+ (1 - 2Q\beta + 2Q^2 \beta^4 - Q^3 \beta^5)\alpha^2 + Q^2 (\beta - 1) \beta^2 \alpha^3).$$

Up to the first fraction, the expression in the big bracket reproduces the $Q$-deformed $A$-polynomial given in [17]. A related change of variables, constructed along the lines of Appendix C.2, reveals the form of closely related augmentation polynomial of [26].

2.3. Trefoil knot

In this section, we derive the classical and quantum super-$A$-polynomial for the trefoil knot (i.e. $(2, 3)$ torus knot, also denoted $T^{(2,3)}$ or $3_1$) and verify the validity of Conjectures 1 and 2 for this knot. The analysis follows the same lines as in previous sections, and its starting point is the expression for the colored superpolynomial. We can provide such an expression from two sources. First, the colored superpolynomial for general $(2, 2p + 1)$ torus knot was derived in [16] from the perspective of the refined Chern–Simons theory. This superpolynomial is given in (2.32), as we will need it for the analysis of general torus knots in the next section. Even though in this section we only need $p = 1$ specialization of (2.32), this is still quite an intricate expression. Nonetheless we are able to find its simpler form

$$\mathcal{P}_n(3_1; a, q, t) = \sum_{k=0}^{n-1} q^{n-1} t^{2k} q^{n(k-1)+1} \frac{(q^{n-1}; q^{-1})_k (\frac{-atq^{-1}}{1}, q)_{k+1}}{(q, q)_k}.$$ (2.23)

Another way to derive this formula is to consider constraints arising from the action of various differentials, as also discussed at length in [16]. It turns out that these constraints also lead to the above formula for the colored superpolynomial for the trefoil (even though they are much harder to analyze for other torus knots). We also note that in [16] a specialization $a = q^2$ of (2.23) was used in order to find refined $A$-polynomial. Here we use more general $a$-dependent expression with the goal of finding super-$A$-polynomial. Explicit values of $\mathcal{P}_n(3_1; a, q, t)$ following from (2.23) for low values of $n$ are given in Table 4.

Again, from the explicit form of the colored superpolynomial (2.23) we find the recursion relation it satisfies by using the Mathematica package qZeil.m, see [29]. This recursion relation takes the form

$$\mathcal{P}_n(3_1; q^2, q, -1) = \sum_{k=0}^{n-1} q^{n(k+1)-1} (q^{n-1}; q^{-1})_k, \text{ which provides a simpler form of the Jones polynomial for the trefoil considered in [15,27], } \mathcal{P}_n(3_1; q^2, q, -1) = J_n(3_1; q) = \sum_{k=0}^{n-1} (-1)^k q^{k(k+3)/2+nk} (q^{n-1}; q)_k (q^{-n+1}, q)_{k+1}.$$
Table 4
Colored superpolynomial of the $3_1$ knot for $n = 1, 2, 3, 4.$

| $n$ | $\mathcal{P}_n(3_1; a, q, t)$ |
|-----|--------------------------------|
| 1   | 1                             |
| 2   | $aq^{-1} + aq^2 + a^2 t^3$    |
| 3   | $a^2 q^{-2} + a^2 q (1 + q) t^2 + a^3 (1 + q) t^3 + a^2 q^2 t^4 + a^3 q^3 (1 + q) t^5 + a^4 q^4 t^6$ |
| 4   | $a^3 q^{-3} + a^3 q (1 + q + q^2) t^2 + a^4 (1 + q + q^2) t^3 + a^3 q^2 (1 + q + q^2) t^4 + a^4 q^3 (1 + q) (1 + q + q^2) t^5$ |
$\quad + a^3 q^2 (a^2 + a^2 q + a^2 q^2 + q^3) t^6 + a^4 q^3 (1 + q + q^2) t^7 + a^3 q^3 (1 + q + q^2) t^8 + a^4 q^4 t^9$ |

\[
\begin{pmatrix}
0 & -a & 1 \\
0 & a t^2 & a t^3 \\
0 & -2 a t^2 - 2 a^2 t^3 & 0 \\
-a^2 t^4 & -a^2 t^5 & 0 \\
a^2 t^4 & -a^3 t^5 & 0 \\
a^3 t^6 & 0 & 0
\end{pmatrix}
\]

Fig. 5. Matrix form of the super-$A$-polynomial for the trefoil knot. The conventions are the same as in Fig. 2.

\[\hat{A}^{\text{super}}(\hat{x}, \hat{y}; a, q, t) = a_0 + a_1 \hat{y} + a_2 \hat{y}^2,\]  
\hspace{2cm}\text{(2.24)}

where

\[
a_0 = \frac{a^2 t^4 (\hat{x} - 1) \hat{x}^3 (1 + aq t^3 \hat{x}^2)}{q (1 + at^3 \hat{x})(1 + at^3 q^{-1} \hat{x}^2)},
\]

\[
a_1 = -\frac{a (1 + at^3 \hat{x}^2) (q - q^2 t^2 \hat{x} + t^2 (q^2 + q^3 + at + aq^2 t) \hat{x}^2 + aq^2 t^5 \hat{x}^3 + a^2 q^4 t^6 \hat{x}^4)}{q^2 (1 + at^3 \hat{x})(1 + at^3 q^{-1} \hat{x}^2)},
\]

\[a_2 = 1.\]

At this point we also stress that the simple representation (2.23) is essential for deriving this second order recursion relation; the algorithm qZeil.m applied to the equivalent, but more involved expression (2.32) finds only the sixth order recursion relation.

The classical super-$A$-polynomial for trefoil knot follows from the $q \rightarrow 1$ limit of $\hat{A}^{\text{super}}$ and reads

\[A^{\text{super}}(x, y; a, t) = a^2 t^4 (x - 1) x^3 + (1 + at^3 x) y^2 \]
\[- a (1 - t^2 x + 2t^2 (1 + at)x^2 + at^5 x^3 + a^2 t^6 x^4) y.\]

Matrix form of this polynomial is presented in Fig. 5, and its Newton polygon is shown in Fig. 6.

Let us now show that the same polynomial can be derived from the asymptotic behavior of the colored superpolynomial (2.23). Using integral representation as in (2.15),

\[\mathcal{P}_n(3_1; a, q, t) \sim \int dz e^{\frac{1}{h}(\tilde{\mathcal{V}}(3_1; z; x) + \mathcal{O}(h))},\]

\hspace{2cm}\text{(2.26)}

with the potential

\[\tilde{\mathcal{V}}(3_1; z, x) = -\frac{\pi^2}{6} + (\log z + \log a) \log x + 2(\log t)(\log z) \]
\[+ \log \log z - \log x \log 2 - (at) - (at z) + \log z,\]

\hspace{2cm}\text{(2.27)}
and in the limit (1.9) with $z = e^{\hbar k} = \text{const}$, we find that Eqs. (2.17) and (2.18) take the form

$$\begin{align*}
1 &= t^2 x(x - z_0)(1 + az_0)
\quad / z_0(z_0 - 1), \\
y &= az_0^2(x - 1)
\quad / (x - z_0).
\end{align*}$$

Eliminating $z_0$ from these two equations we reproduce the super-$A$-polynomial (2.25). We conclude that both Conjectures 1 and 2 hold true for the trefoil knot.

We also consider various limits of the super-$A$-polynomial (2.25). For $t = -1$ and $a = 1$ we get

$$A(x, y) = -(x - 1)(y - 1)(y + x^3),$$

which reproduces the well-known $A$-polynomial for the trefoil, including the $y - 1$ factor associated with abelian flat connections (and the overall immaterial factor $x - 1$). More generally, under a change of variables (which in fact is $p = 1$ specialization of more general identification (2.37) valid of $(2, 2p + 1)$ torus knots)

$$Q = a, \quad \beta = x, \quad \alpha = y Q^{-1} \beta^{-6} \left(1 - Q \beta \right),$$

and in $t = -1$ limit, (2.25) reduces (up to an overall factor) to

$$A(\alpha, \beta, Q) = (1 - Q \beta) + (\beta^3 - \beta^4 + 2\beta^5 - 2Q \beta^6 - Q^2 \beta^7 + Q^2 \beta^7) \alpha$$

$$+ (-\beta^9 + \beta^{10}) \alpha^2,$$

which perfectly reproduces the $Q$-deformed or augmentation polynomial for the trefoil knot found in [17,26]. Relations between super-$A$-polynomial, $Q$-deformed $A$-polynomial and augmentation polynomial for torus knots are also discussed in much more detail in Appendix C.2.

2.4. $(2, 2p + 1)$ torus knots

As the last class of examples we discuss the entire family of $(2, 2p + 1)$ torus knots, which are also denoted $T^{(2, 2p + 1)}$. The $S'$-colored superpolynomials for this family were determined from the refined Chern–Simons theory viewpoint in [16]. From this perspective the reduced colored superpolynomial is found as the ratio of (refined) Chern–Simons partition functions in $S^3$ in presence of a given knot and the unknot. (Recall, that the unreduced colored superpolynomial is given as a similar ratio of Chern–Simons partition functions in the presence and absence of
a knot, cf. (2.2).\) This computation, with all technicalities related to consistent refinement of Chern–Simons computation (which involves taking into account appropriate $$\gamma$$-factors and other subtleties) leads to the following expression for the colored superpolynomial for \((2,2p+1)\) torus knot:

$$
\mathcal{P}^S(T^{(2,2p+1)}; a, q, t) = (-1)^p \left( \frac{q_1}{q_2} \right)^{\frac{p}{2}} \frac{Z^\text{ref}_{SU(N)}(\mathcal{S}^3, T^{(2,2p+1)}_{A^r}; q_1, q_2)}{Z^\text{ref}_{SU(N)}(\mathcal{S}^3, \bigcirc A^r; q_1, q_2)}
$$

$$
= \sum_{\ell=0}^{r} \frac{(qt^2; q)_{\ell}(-at^3; q)_{r+\ell}(-aq^{-1}t; q)_{r-\ell}(q; q)_r}{(q; q)_{\ell}(q^2t^2; q)_{r+\ell}(q; q)_{r-\ell}(-at^3; q)_r} \left( 1 - q^{2\ell+1}t^2 \right)
$$

$$
\times (-1)^{n-1} a^{-\frac{3n(n-1)}{2}} t^{-n(n-1)-\ell} \left( \frac{(-1)^{\ell} a}{q} \right) \left( 1 - q^{2\ell+1}t^2 \right)^{2p+1}. \tag{2.32}
$$

Much as in the unknot example (2.2), at intermediate stages we need to compute partition functions for anti-symmetric representations $$A^r$$, and the change of variables (2.1) has been performed in order to present the final result in terms of $$a$$, $$q$$, $$t$$ variables; for more details see [16].

We note that, for $$p = 1$$, the expression (2.32) can be rewritten in much simpler form (2.23), which leads to the desired second order recursion relation (2.24), while direct application of the algorithm qZeil.m to the representation (2.32) with $$p = 1$$ gives only sixth order relation. This shows that recursion relations found directly from (2.32) for arbitrary $$p$$ in general will not be of minimal order; it is certainly interesting to find recursion relations of minimal order for all $$p$$. Relegating this task to future work, in this section we focus on the asymptotic analysis of (2.32), which is sufficient for deriving the classical super-A-polynomials of minimal order for all $$p$$. The knowledge of these classical super-A-polynomials is an important hint in deriving quantum super-A-polynomials of minimal order for general $$p$$.

In the asymptotic limit $$\hbar \to 0$$ limit, the colored superpolynomial $$\mathcal{P}^S(T^{(2,2p+1)}; a, q, t)$$ behaves as

$$
\mathcal{P}^S(T^{(2,2p+1)}; a, q, t) \sim \int dz e^{\frac{i}{\hbar} \tilde{\mathcal{W}}(T^{(2,2p+1)}; z,x) + \mathcal{O}(\hbar)}, \tag{2.33}
$$

with the potential

$$
\tilde{\mathcal{W}}(T^{(2,2p+1)}; z, x) = p \log(a) \cdot \log x - p \log(-t) \cdot \log x + (p + 1)\pi i \log x + \log(x^\frac{1}{2}z^{-1}) \cdot \log t
$$

$$
+ (2p + 1) \left( \pi i \log z + \frac{1}{2} (\log x)^2 - (\log z)^2 \right) + \log(x^\frac{3}{2}z^{-1}) \cdot \log t
$$

$$
+ \text{Li}_2(z) - \text{Li}_2(x) - \text{Li}_2(t^2z) + \text{Li}_2(-at^3x) + \text{Li}_2(t^2xz)
$$

$$
- \text{Li}_2(-at^3x) + \text{Li}_2(xz^{-1}) - \text{Li}_2(-atx^{-1}) + \text{Li}_2(-at) - \text{Li}_2(1), \tag{2.34}
$$

where $$z = q^\ell$$.

For the above potential $$\tilde{\mathcal{W}}(T^{(2,2p+1)}; z, x)$$, the critical point condition can simply be expressed as $$1 = \exp(z \partial \tilde{\mathcal{W}}/\partial z)|_{z = z_0}$$:

$$
1 = -\frac{t^{-2-2p}(x - z_0)z_0^{-2p}(-1 + t^2z_0)(1 + at^3x z_0)}{(-1 + z_0)(at x + z_0)(-1 + t^2z_0)} \tag{2.35}
$$
Table 5
Super-A-polynomials for \((2, 2p + 1)\) torus knots with \(p = 1, 2, 3\). For cases \(p = 4, 5\) see Tables 12 and 13.

| Knot | \(A_{\text{super}} (x; y; a, t)\) |
|------|----------------------------------|
| \(T^{(2,3)}\) | \(y^2 + \frac{1}{1 + at^3}a(-1 + t^2x - 2a t^2x^2 - 2at^3x^2 - at^5x^3 - a^2t^6x^4)y + \frac{1}{1 + at^4x}x\) |
| \(T^{(2,5)}\) | \(y^3 - \frac{a}{1 + at^5x}(1 - t^3x + 2t^4x^2 + 2at^3x^2 - 2a t^3x^2 - 2at^5x^3 + 3t^4x^4 + 4at^4x^5 + a^2t^6x^4) + at^7x^3 - a^2t^8x^3 + 2at^8x^6)y^2 + \frac{a^4 t^6(1 + x)^5}{(1 + at^5x)^2}(2 - t^2x + at^3x + 3t^4x^2 + 4at^5x^3) + a^3 t^4x^3 + 2at^6x^3 + 2at^8x^4 + 2a^2 t^9x^4 + a^3 t^9x^4 + a^4 t^{10}x^6)y - \frac{a^6 t^{12}(-1 + x)^2 x^{10}}{(1 + at^5x)^2}\) |
| \(T^{(2,7)}\) | \(y^4 - \frac{a^3}{1 + at^7x}(1 - t^2x + 2t^3x^3 - 2a t^3x^3 - 2at^5x^3 + 3t^4x^4 + 4at^5x^4 + a^2t^6x^4 - 3t^6x^5 - 4at^7x^5 + a^2 t^8x^5 + 4t^6x^6 + 6at^7x^6 + 2a^2 t^8x^6 + at^9x^7 - 2a^2 t^{10}x^7 + 3a^2 t^{10}x^8) y^3 + \frac{a^6 t^6(-1 + x)^7(3 - 2t^2x + at^3x + 6t^4x^2 + 8at^5x^2 + 2a^3 t^6x^2 - 3t^4x^3 - 2at^5x^3 + a^2 t^6x^3 + 6t^4x^4 + 12t^5x^4 + 10a t^6x^5 + 4a^3 t^7x^4 + 3at^7x^5 + 2a^2 t^8x^5 - a^3 t^9x^5 + 6a^2 t^8x^6 + 8a^3 t^9x^6 + 2a^4 t^{11}x^7 - a^4 t^{12}x^7 + 3a^{4} t^{12}x^8)y^2 - \frac{a^9 t^{16}(-1 + x)^2 x^{14}}{(1 + at^3x)^3}(3 - t^2x + 2at^3x + 4t^3x^2 + 6at^4x^2 + 2a^3 t^4x^2 + 3at^5x^3 + 4a^2 t^6x^3 + a^3 t^7x^3 + 3a^2 t^7x^3 + 4a^3 t^8x^4 + 2a^4 t^9x^4 + 2a^3 t^{10}x^5 + 2a^4 t^{10}x^5 + 2a^4 t^{11}x^6 + 2a^5 t^{11}x^6 + a^6 t^{12}x^8y + \frac{a^{12} t^{24}(-1 + x)^3 x^{21}}{(1 + at^3x)^3}\) |

and

\[
y(x, t, a) = \exp \left( x \frac{\partial \tilde{W}(T^{(2,2p+1)}; z_0, x)}{\partial x} \right) = \frac{a t^{2+2p}(-1 + x)x^{1+2p}(atx + z_0)(1 + at^3x z_0)}{(1 + at^3x)(x - z_0)(-1 + t^2x z_0)}.
\] (2.36)

Eliminating \(z_0\) from the above equations, we find the super-A-polynomial \(A_{\text{super}}(x, y; a, t)\) for any \((2, 2p + 1)\) torus knot. For small values of \(p\), the resulting super-A-polynomials are listed in Tables 5, 12 and 13.5

For \(a = 1\) we find the refined \(A\)-polynomials of [16]. On the other hand, for \(t = -1\) we find the \(Q\)-deformed \(A\)-polynomial of [17] if the following identification of parameters is performed

\[
Q = a, \quad \beta = x, \quad \alpha = y Q^{-p} \beta^{-4p-2} \frac{1 - Q \beta}{1 - \beta},
\] (2.37)

and a related transformation reveals the form of the augmentation polynomial of [26]. Precise derivation of the above variable change, as well as explicit relations between super-A-polynomial, the augmentation polynomial and \(Q\)-deformed \(A\)-polynomial, are discussed in detail in Appendix C.2.

For \(n = 2\) the colored superpolynomial (2.32) becomes

\[
\mathcal{P}(T^{(2,2p+1)}; a, q, t) = \frac{a^p q^{-p}(1 + aqt^3 - q^{2p+1}t^2 p^2(q + at))}{1 - q^2 t^2}.
\] (2.38)

5 In these tables, we omitted the extra factors which appears in the elimination, and picked up the factor that includes the non-abelian branch of the \(SL(2)\) character variety.
For $q = 1$, the superpolynomial reduces to
\[ P(T^{(2,2p+1)}; a, q = 1, t) = \frac{a^p(1 + at^3 - t^{2p+2}(1 + at))}{1 - t^2}. \quad (2.39) \]
Up to $p = 5$, we can compare this limit and the super-$A$-polynomials reduced at $x = 1$ which are given in Table 11, and the relation (1.19) can be confirmed explicitly.

3. Quantizability

In this section we discuss the super-$A$-polynomials that we found from the viewpoint of quantizability, by which we mean the following. For Conjecture 1 to be formulated in a consistent way, we must ensure that the leading term $\int \log \frac{y}{x} dx$ in the integral (1.10) is well-defined, i.e. does not depend on the choice of the integration path on the algebraic curve (1.11). As explained in [1,12], this requirement imposes the following constraints on the periods of the imaginary and real parts of $\log \frac{y}{x}$, respectively,
\[ \oint_{\gamma} \left( \log |x| d(\arg y) - \log |y| d(\arg x) \right) = 0, \quad (3.1) \]
\[ \frac{1}{4\pi^2} \oint_{\gamma} \left( \log |x| d \log |y| + (\arg y) d(\arg x) \right) \in \mathbb{Q}, \quad (3.2) \]
for all closed paths $\gamma$ on the curve (1.11). It turns out that these conditions can be further reformulated and interpreted in a variety of ways. On one hand, it is amusing to observe that the integrand $\eta(x, y) = \log |x| d(\arg y) - \log |y| d(\arg x)$ in (3.1) is the image of the symbol $\{x, y\} \in K_2(C)$ under so-called regulator map, thereby constituting an immediate link to algebraic K-theory [30–32]. As discussed in [12], from this K-theory viewpoint the condition that the curve is quantizable can be rephrased simply as the requirement that $\{x, y\} \in K_2(\mathbb{C}(C))$ is a torsion class. On the other hand, this more abstract condition also translates to the down-to-earth statement that quantizability of the curve requires its defining polynomial to be tempered.

By definition, a polynomial $A(x, y)$ is tempered if all roots of all face polynomials of its Newton polygon are roots of unity. Face polynomials are constructed as follows: we need to construct a Newton polygon corresponding to $A(x, y) = \sum a_{i,j} x^i y^j$, and to each point $(i, j)$ of this polygon we associate the coefficient $a_{i,j}$. We label consecutive points along each face of the polygon by integers $k = 1, 2, \ldots$ and, for a given face, rename monomial coefficients associated to these points as $a_k$. Then, the face polynomial associated to a given face is defined to be $f(z) = \sum_k a_k z^k$. Therefore, the quantizability condition requires that all roots of $f(z)$ constructed for all faces of the Newton polygon must be roots of unity. In what follows we are going to examine super-$A$-polynomials which we found in examples in Section 2 from this perspective.

Ordinary $A$-polynomials have numerical, integer coefficients [2], and therefore the above quantization condition imposes certain constraints on values of these coefficients. For example, the ordinary $A$-polynomial of the figure-eight knot given in (2.21) satisfies these constraints, while its close cousin with only slightly different coefficients, discussed e.g. in [1,12], does not. Meeting these tight constraints might seem much less trivial in the case of $t$- or $a$-deformed curve, when coefficients of the defining polynomial depend on these extra parameters. Nonetheless, we found in [16] that this is indeed possible for refined (i.e. $t$-dependent) $A$-polynomials
Table 6
Face polynomials for the figure-eight knot, corresponding to faces of the octagonal shape formed by non-zero entries of the coefficient matrix in Fig. 3. Faces are labeled by compass directions (with N standing for North, etc.), with the first row $(0, -at, -1, 0)$ of the matrix in Fig. 3 located in the North.

| Face | Face polynomial |
|------|-----------------|
| N    | $z + at$        |
| NE   | $z + at^2$      |
| E    | $at^2(z + at^3)^2$ |
| SE   | $a^{3/8}(z - at^2)$ |
| S    | $a^{3/9}(z + at)$ |
| SW   | $a^{2/5}(z - at^4)$ |
| W    | $a^{2/5}(z - 1)^2$ |
| NW   | $at(z - at^4)$ |

and the outcome is very simple: the quantization condition implies that $t$ has to be a root of unity. Therefore, even though such $t$ cannot be completely arbitrary, it still takes values in a dense set of points (on a unit circle). With this result in mind, the reader should not be surprised that an analogous conclusion applies to the super-$A$-polynomial as well: all super-$A$-polynomials found in Section 2 are tempered (and therefore quantizable) as long as both $a$ and $t$ are roots of unity. Moreover, this condition very nicely fits with the fact that in specialization from colored super-polynomial or HOMFLY polynomial to $sl(N)$ quantum group invariant we substitute $a = q^N$ and in Chern–Simons theory with $SU(N)$ gauge group $q$ is required to be a root of unity, so that $a = q^N$ is automatically a root of unity as well!

Let us now illustrate the above claim in the examples of various knots discussed in Section 2. For each of those knots we construct a Newton polygon and face polynomials of the corresponding super-$A$-polynomials. In order to construct face polynomials it is convenient to write down a matrix representation of the super-$A$-polynomials. For instance, for the unknot the Newton polygon and the corresponding matrix representation are shown in Fig. 2. In this case, it is clear that roots of face polynomials are all roots of unity if $a$ and $t$ are roots of unity. In fact, the unknot is so simple that even a weaker condition is sufficient to hold, namely that the combination $at^3$ is a root of unity.

The matrix coefficients and the Newton polygon for figure-eight knot are given, respectively, in Figs. 3 and 4, and the corresponding face polynomials are presented in Table 6. The face polynomials are manifestly written as products of linear factors, and being tempered requires that both $a$ and $t$ are roots of unity.

An analogous condition holds for $(2, 2p + 1)$ torus knots. In particular, the matrix coefficients and the Newton polygon for the trefoil knot are shown, respectively, in Figs. 5 and 6. Newton polygons of other $(2, 2p + 1)$ torus knots have a similar, hexagonal shape which grows linearly with $p$; in fact, they are identical to Newton polygons for the refined $A$-polynomials presented in [16]. The face polynomials of the super-$A$-polynomials discussed in the present paper are certain $a$-deformations of the refined face polynomials studied in [16], and they also factorize into linear factors as shown in Table 7. By inspection, it is clear that roots of these polynomials are all roots of unity as long as both $a$ and $t$ are roots of unity.
Table 7
Face polynomials for \((2, 2p + 1)\) torus knots, corresponding to faces of the hexagonal shape formed by non-zero entries of the coefficient matrices for \((2, 2p + 1)\) torus knots, such as the matrix for the trefoil in Fig. 3.

| Face          | Face polynomial                                      |
|--------------|------------------------------------------------------|
| first column | \(-(at^{2})^{p(p+1)}(z - 1)^{p}\)                   |
| last column  | \((-1)^{p}(z + at^{3})^{p}\)                        |
| first row    | \(za^{p} - 1\)                                      |
| last row     | \(-(at^{2})^{p(p+1)}(z - (at^{2})^{p})\)           |
| lower diagonal | \((-1)^{p}(at^{3})^{p}(z - a^{p+1}t^{2}p+1)^{p}\) |
| upper diagonal | \((-1)^{p+1}a^{p}(z + a^{p+1}t^{2}p+2)^{p}\)       |

To sum up, we conclude that super-\(A\)-polynomials which we find are quantizable if both \(a\) and \(t\) are roots of unity and we conjecture that this is the case for all knots. Let us note that this condition is also consistent with what we found in [16] in the context of refined mirror curves for BPS states. For example, in that paper we discussed in detail the refined mirror curve for the conifold, which apart from \(t\) variable depends also on the Kähler parameter \(Q\). By a similar analysis as here we found that both \(t\) and \(Q\) have to be roots of unity. On the other hand, in the relation between string theory and Chern–Simons theory the Kähler parameter \(Q\) is interpreted as the variable \(a\) of knot polynomials, and from various other viewpoints (e.g. quantum foam, crystal models, attractor mechanism, etc.) the Kähler parameter is also quantized as \(Q = q^{N}\) with \(N\) being the rank of the Chern–Simons gauge group. Therefore, we see that both knot theory and BPS state perspectives lead to similar and consistent conclusions.

4. Differentials

We wish to emphasize one important point which did not affect our examples and, therefore, was suppressed in our discussion so far. It has to do with various specializations of the super-\(A\)-polynomial illustrated in Fig. 1 or, to be more precise, with analogous specializations of its quantum version that encode recursion relations for various \(S^{r}\)-colored knot invariants, see Table 1.

For example, both \(t = -1\) specializations in Fig. 1 have a clear “quantum” analog, which corresponds to passing from homological to polynomial knot invariants. In the triply-graded case, this operation of taking graded Euler characteristic relates (the Poincaré polynomial of) the colored HOMFLY homology to the colored HOMFLY polynomial, whereas in the doubly-graded cases it relates (the Poincaré polynomial of) the \(n\)-colored Khovanov homology to the colored Jones polynomial \(J_{n}(K; q)\), see e.g. Fig. 2 of [16].

In particular, because the Poincaré polynomials of these homology theories are related to the corresponding knot polynomials by the specialization \(t = -1\), the same is true about recursion relations that describe the “color behavior” of these invariants:

\[
\hat{A}^{\text{super}}(\hat{x}, \hat{y}; a, q, t)|_{t=-1} = \hat{A}^{\text{Q-def}}(\hat{x}, \hat{y}; a, q),
\]

\[
\hat{A}^{\text{ref}}(\hat{x}, \hat{y}; q, t)|_{t=-1} = \hat{A}(\hat{x}, \hat{y}; q). \tag{4.1}
\]

Similarly, a specialization \(\hat{A}^{\text{Q-def}}(\hat{x}, \hat{y}; a, q)|_{a=q^{-2}} = \hat{A}(\hat{x}, \hat{y}; q)\) presents no difficulty since evaluation of the \(n\)-colored HOMFLY polynomial at \(a = q^{-2}\) gives the \(n\)-colored Jones polynomial for
all values of $n$. Therefore, any recursive relation on the former is guaranteed to yield a recursion relation for $J_n(K;q)$ via specialization to $a = q^2$.

On the other hand, the specialization (1.15) is more delicate since, in general, the colored superpolynomial $P_n(K; a, q, t)$ evaluated at $a = q^2$ is not equal to the Poincaré polynomial of the colored Khovanov homology, $P_{\mathfrak{sl}(2),V_n}(q, t)$, where $V_n = S^{n-1}$ is the $n$-dimensional representation of $\mathfrak{sl}(2)$. Instead, the two homology theories are related by a certain differential [23], which at the level of Poincaré polynomials implies a relation

$$P_n(a, q, t) = R_n(a, q, t) + \left(1 + a^{-1}q^2t^{-1}\right)Q_n(a, q, t), \quad (4.2)$$

where $R_n(a, q, t)$ and $Q_n(a, q, t)$ are polynomials with non-negative coefficients, such that $P_{\mathfrak{sl}(2),V_n}(q, t) = R_n(q^2, q, t)$. Hence, when the differential acts non-trivially, a (recursion) relation among colored superpolynomials $P_n(a, q, t)$ does not automatically lead to a recursion relation for $\mathfrak{sl}(2)$ Poincaré polynomials $P_{\mathfrak{sl}(2),V_n}(q, t)$ due to the extra terms $Q_n(a, q, t) \neq 0$. In other words, unless $\hat{A}_{\text{super}}(\hat{x}, \hat{y}; a, q, t)$ annihilates $(1 + a^{-1}q^2t^{-1})Q_n(a, q, t)$ at $a = q^2$, it will not produce an operator $\hat{A}_{\text{ref}}(\hat{x}, \hat{y}; q, t)$ by a simple rule (1.15):

$$\hat{A}_{\text{super}}(\hat{x}, \hat{y}; q^2, q, t)P_{\mathfrak{sl}(2),V_n}(q, t) + (1 + t^{-1})\hat{A}_{\text{super}}(\hat{x}, \hat{y}; q^2, q, t)Q_n(q^2, q, t) = 0. \quad (4.3)$$

Note, this issue does not exist in the unrefined (“decategorified”) case since setting $t = -1$ makes the second term vanish.

This is the only subtle specialization in the “quantum” version of the diagram in Fig. 1. We expect, however, that even this subtlety goes away in the classical limit $q \to 1$. Indeed, all commutative deformations of the $A$-polynomial describe “large color” behavior of various knot polynomials, cf. (1.10). In particular, we expect that the number of generators in the $n$-colored HOMFLY homology killed by the differential (4.2) exhibits slower than exponential growth in the large-$n$ limit (1.9),

$$\lim_{n \to \infty} \frac{1}{n} \log Q_n(a, q, t) = 0, \quad (4.4)$$

and, therefore, does not muddy the waters in the diagram in Fig. 1.

Besides playing a key role in various specializations of homological knot invariants, the differentials endow knot homologies with a very rich structure, which turns out to be very elegant and often so constraining that one can even compute colored superpolynomials based on this structure alone, with a minimal input. In particular, this is how nice formulas like (2.23) can be produced. Referring the reader to [23] for further details, here we merely state a simple rule of thumb: the factors of the form $(1 + a^i q^j t^k)$ that we often see e.g. in (2.4), (2.12), (2.23), and (2.32) come from differentials of $(a, q, t)$-degree $(i, j, k)$, cf. [16, Eq. (3.54)]:

| Differentials | Factors | $(a, q, t)$-grading |
|---------------|---------|---------------------|
| $d_{N>0}$     | $1 + aq^{-N}t$ | $(-1, N, -1)$ |
| $d_{N<0}$     | $1 + aq^{-N}t^3$ | $(-1, N, -3)$ |
| $d_{\text{colored}}$ | $1 + q$ | $(0, 1, 0)$ |
|               | $1 + at$ | $(-1, 0, -1)$ |
|               |         | ...                 |

\[ (4.5) \]

\[ ^6 \text{In the grading conventions of [18,33–35], the factor on the right-hand side reads } (1 + a^{-2}q^4t^{-1}). \]
For example, notice that all terms with \( k > 0 \) in the expression (2.12) for the colored superpolynomial of the figure-eight knot manifestly contain a factor \((1 + aq^{n-1}t^3)\). Hence, the \( S^{n-1} \)-colored superpolynomial of the figure-eight knot has the following structure, cf. (4.2):

\[
P_n(4_1; a, q, t) = 1 + (1 + aq^{n-1}t^3)Q_n(a, q, t), \tag{4.6}
\]

which means that, when evaluated at \( a = -q^{-1}nt^{-3} \), the sum (2.12) collapses to a single \( k = 0 \) term, \( P_n(4_1; a = -q^{-1}nt^{-3}, q, t) = 1 \). A proper interpretation of this fact is that a specialization to \( N = 1 - n \) of the triply-graded \( S^{n-1} \)-colored HOMFLY homology, carried out by the action of the differential \( d_{n-1} \), is trivial. In other words, the differential \( d_N \) with \( N = 1 - n \) is canceling in a theory with \( R = S^{n-1} \).

The reason for this is very simple: specialization to \( N < 0 \) is best understood — in view of the “mirror symmetry” [23] — as a specialization to \( \mathfrak{sl}(-N) \) knot homology colored by a transposed Young diagram \( \mathbf{R}' \). In the present case, it means that the \( \Lambda^{n-1} \)-colored \( \mathfrak{sl}(N) \) knot homology is trivial (i.e. one-dimensional for every knot \( K \)) when \( N = n - 1 \), which, of course, must be the case since the representation \( \mathbf{R}' = \Lambda^N \) of \( \mathfrak{sl}(N) \) is trivial. Similarly, one can explain much of the structure that \( \text{a priori} \) may seem random in the colored superpolynomials and the super-A-polynomials, or even derive them.

5. Physical interpretation

In our previous work, we proposed to interpret the parameter \( t \) responsible for the “refinement” or “categorification” as a twisted mass parameter for the global symmetry \( U(1)_F \) in the effective three-dimensional \( \mathcal{N} = 2 \) theory \( T_M \) associated to the knot complement \( M = S^3 \setminus K \):

\[
M \sim T_M. \tag{5.1}
\]

Moreover, generically, every charged chiral multiplet in a theory \( T_M \) contributes to the effective twisted chiral superpotential a dilogarithm term:

\[
\begin{align*}
\text{chiral field } \phi & \quad \leftrightarrow \quad \text{twisted superpotential,} \\
\Delta \tilde{W}(\vec{x}; t) &= \text{Li}_2((-t)^{n_F} \prod_i (x_i)^{n_i})
\end{align*} \tag{5.2}
\]

where \( n_F \) is the charge of the chiral multiplet under the global \( R \)-symmetry \( U(1)_F \) and \( \{n_i\} \) is our (temporary) collective notation for all other charges of \( \phi \) under symmetries \( U(1)_i \), some of which may be global flavor symmetries and some of which may be dynamical gauge symmetries, depending on the problem at hand.\(^7\) In particular, in the former case, the vev of the corresponding twisted chiral multiplet is usually called the twisted mass parameter \( \tilde{m}_i = \log x_i \), of which \( \tilde{m}_F = \log(-t) \) is a prominent example.

The second commutative deformation parameter \( a \) also admits a similar interpretation as a twisted mass parameter for a global symmetry that we denote \( U(1)_Q \):

\[
\log a = \tilde{m}_Q. \tag{5.3}
\]

\(^7\) Below we shall return to the different role of gauge and global symmetries, but for now we wish to point out a simple rule of thumb that one can read off the matter content of the theory \( T_M \) by counting dilogarithm terms in the function \( \tilde{W}(\vec{x}; t) \).
Calabi–Yau geometry $X$. For example, the effective low-energy theory on a toric brane in the conifold geometry has two chiral multiplets that come from two open BPS states shown in blue and red in Fig. 7. We stress that this brane picture can be directly seen from our results for the unknot: the $a$-deformed curve (2.8) represents a genuine conifold mirror curve $A = 1 - ax - \tilde{y} + x\tilde{y}$, after a simple rescaling $\tilde{y} = a^{1/2}y$ and with Kähler parameter $a$. In this case the structure of two dilogarithms arises as the leading order term in the asymptotic expansion of $t = -1$ specialization of the superpolynomial (2.2) (which is essentially given by the ratio of quantum dilogarithms, as is the case for the brane amplitude in the conifold geometry).

In this example, the symmetry $U(1)_Q$ responsible for the $a$-deformation comes from the 2-cycle in the conifold geometry $X$. (The corresponding gauge field $A_\mu$ comes from the Kaluza–Klein reduction of the RR 3-form field, $C \sim A \wedge \omega$, and becomes the starting point for the geometric engineering of $N = 2$ gauge theories in four dimensions [36].) In a basis of refined open BPS states shown in Fig. 7, one state is charged under the symmetry $U(1)_Q$, while the other state is neutral. Therefore, the effective twisted superpotential $\tilde{W}(x; a, t)$ of the corresponding model has two dilogarithm terms, one of which depends on $a$ and the other does not.

Returning to the general theory $T_M$, now we are ready to explain the connection between the twisted superpotential in this theory and the algebraic curve (1.11) defined as the zero locus of the super-$A$-polynomial. Roughly speaking, the curve (1.11) describes the SUSY vacua in the $N = 2$ theory $T_M$. To make this more precise, we need to recall that among the parameters $x_i$ in (5.2) some correspond to vevs of dynamical fields (and, therefore, need to be integrated out) and some are twisted masses for global flavor symmetries. To make the distinction clearer, let us denote the former by $z_i$ (instead of $x_i$), so that the vevs of dynamical twisted chiral superfields are $\sigma_i = \log z_i$. Then, in order to find SUSY vacua of the theory $T_M$ we need to extremize $\tilde{W}$ with respect to these dynamical fields,

$$
\frac{\partial \tilde{W}}{\partial z_i} = 0.
$$

This is exactly what we did e.g. in (2.17) when we extremized the potential function (2.16) for the figure-eight knot (cf. also (2.27) and (2.35) for the case of $(2, 2p + 1)$ torus knots). Solving these equations for $z_i$ and substituting the resulting values back into $\tilde{W}$ gives the effective twisted superpotential, $\tilde{W}_{\text{eff}}$, that depends only on twisted mass parameters associated with global symmetries of the $N = 2$ theory $T_M$. 

Fig. 7. A toric Lagrangian brane in the conifold bounds two holomorphic disks (shown by red and blue intervals in the base of the toric geometry). (For interpretation of the references to color in this figure legend, the reader is referred to the web version of this article.)

Table 8
Spectrum of the $\mathcal{N} = 2$ theory $T_M$ for the trefoil and figure-eight knots.

| Trefoil knot | Figure-eight knot |
|--------------|-------------------|
| $\phi_1$ | $\phi_1$ |
| $\phi_2$ | $\phi_2$ |
| $\phi_3$ | $\phi_3$ |
| $\phi_4$ | $\phi_4$ |
| $\phi_5$ | $\phi_5$ |
| parameter | $\phi_6$ |
| $U(1)_{\text{gauge}}$ | $U(1)_{\text{gauge}}$ |
| -1 | 0 |
| 0 | -1 |
| 0 | 1 |
| 1 | 0 |
| $U(1)_F$ | $U(1)_F$ |
| 0 | 0 |
| 1 | 1 |
| -1 | -1 |
| $U(1)_Q$ | $U(1)_Q$ |
| 0 | 0 |
| 0 | 1 |
| $U(1)_L$ | $U(1)_L$ |
| 1 | 1 |
| -1 | 0 |

Besides the symmetries $U(1)_F$ and $U(1)_Q$ which are responsible for $t$- and $a$-deformations, respectively, our $\mathcal{N} = 2$ theories $T_M$ come with additional global flavor symmetries, one for each component of the link $K$ (or, more generally, one for every torus boundary of $M$). In particular, if $K$ is a knot — which is what we assume throughout the present paper — then, in addition to $U(1)_F$ and $U(1)_Q$, there is only one extra global symmetry $U(1)_L$ with the corresponding twisted mass parameter that we simply denote $\tilde{m}$; it is $x = e^{\tilde{m}}$ that shortly will be identified with the variable by the same name in the super-$A$-polynomial. In the brane model,

$$
\text{space–time: } \mathbb{R}^4 \times X
$$

$$
\bigcup \mathbb{R}^2 \times L \quad (5.5)
$$

this symmetry $U(1)_L$ can be identified with the gauge symmetry on the D4-brane supported on the Lagrangian submanifold $L \subset X$. The corresponding gauge field is dynamical when $L$ has finite volume, while for non-compact $L$ (of infinite volume) the symmetry $U(1)_L$ is a global symmetry. Moreover, the other global symmetry $U(1)_F$ that plays an important role in our discussion also can be identified in the brane setup (5.5): it corresponds to the rotation symmetry of the normal bundle of $\mathbb{R}^2 \subset \mathbb{R}^4$.

To summarize our discussion so far, we can incorporate $U(1)_Q$ and $U(1)_L$ charges in (5.2) and write the contribution of a chiral multiplet $\phi \in T_M$ to the twisted superpotential as

$$
\text{chiral field } \phi \longleftrightarrow \text{twisted superpotential},
$$

$$
\Delta \tilde{W}(x, z_i; a, t) = \text{Li}_2(a^n q (-t)^n) x^n L \prod_i (z_i)^{n_i}. \quad (5.6)
$$

Using this dictionary and dilogarithm identities, such as the inversion formula $\text{Li}_2(x) = -\text{Li}_2(\frac{x+1}{2}) - \frac{\pi^2}{6} - \frac{1}{2}[\log(-x)]^2$, from (2.16) and (2.27) it is easy to read off the spectrum of the theory $T_M$ for the trefoil knot and for the figure-eight knot. (See Table 8.)

The terms of lower transcendentality degree, i.e. products of ordinary logarithms, also admit a simple interpretation in three-dimensional $\mathcal{N} = 2$ gauge theory $T_M$. Notice that, in the collective notations $\{x_i\}$ for global and gauge symmetries $U(1)_i$ used in (5.2), the dependence of the twisted superpotential $\tilde{W}$ on log $x_i$ is always quadratic, see e.g. (2.16) and (2.27). Such terms correspond to supersymmetric Chern–Simons couplings for $U(1)$ gauge (resp. background flavor) fields:

$$
\frac{k_{ij}}{4\pi} \int A_i \wedge dA_j + \cdots \longleftrightarrow \text{twisted superpotential},
$$

$$
\Delta \tilde{W}(x; a, t) = \frac{k_{ij}}{2} \log x_i \cdot \log x_j. \quad (5.7)
$$

At this point, we should remind the reader that a given $\mathcal{N} = 2$ theory $T_M$ may admit many dual UV descriptions, with different number of gauge groups and charged matter fields [13]. However, all of these dual descriptions lead to the same space of supersymmetric moduli (twisted mass parameters) once all dynamical multiplets are integrated out, i.e. once the twisted superpotential is extremized (5.4) with respect to all $z_i$.  


The resulting “effective” twisted superpotential $\tilde{W}_{\text{eff}}(x; a, t)$ depends only on the twisted mass parameters associated with the global symmetries $U(1)_L$, $U(1)_Q$, and $U(1)_F$. Then, the algebraic curve (1.11) defined as the zero locus of the super-$A$-polynomial is simply a graph of the function $x \frac{\partial \tilde{W}_{\text{eff}}}{\partial x}$, which in a circle compactification of the theory $T_M$ is interpreted as the effective FI parameter:

$$M_{\text{SUSY}} : \quad A^\text{super}(x, y; a, t) = 0 \iff \log y = x \frac{\partial \tilde{W}_{\text{eff}}}{\partial x}(x; a, t).$$  \hspace{1cm} \text{(5.8)}$$

See [7,11] for a similar interpretation of the ordinary $A$-polynomial. The only difference is that, in the present discussion, we also keep track of the $U(1)_F$ and $U(1)_Q$ quantum numbers, which result in the $a$- and $t$-dependence of the twisted superpotential.

6. Concluding remarks

It is important to realize a few key points that make this story work and allow us to define a 2-parameter family deformation of the classical $A$-polynomial.

The first point, realized already in [16], is that the parameter $t$ responsible for categorification in knot theory applications is a commutative deformation parameter. In other words, unlike (1.3), it does not change the algebra of functions in $x$ and $y$, which under the $t$-deformation remains commutative. To appreciate the importance of this point, consider a generating function, $Z_{\text{open}}^{\text{ref}}_{\text{BPS}}(X, L)$, of refined open BPS invariants for a Lagrangian brane in a (toric) Calabi–Yau $X$. To characterize this function — which can be fairly involved — it is often convenient to focus on a difference equation that it obeys, rather than on a function itself. Writing this difference equation in the form of a Schrödinger-like equation $a \text{ la (1.4)},$

$$\hat{A}Z_{\text{ref. BPS}}^{\text{open}}(X, L) = 0,$$

and shifting the focus to the operator $\hat{A}$ is often a smart way to encode the information contained in $Z_{\text{ref. BPS}}^{\text{open}}(X, L)$. In the unrefined case (i.e. when $q_1 = q_2$), the fact that brane partition functions obey such Schrödinger-like equations goes back to the pioneering work [37] on integrable hierarchies and topological strings (see also [38–40]), whose fully refined version, with generic values of both parameters $q_1$ and $q_2$, was studied only recently in [16].

Even if on general grounds one believes that refined brane amplitudes should be annihilated by operators $\hat{A}(x, y)$, there is no a priori reason why the refinement parameter $t = -\frac{q_1}{q_2}$ should not appear in the algebra of $\hat{x}$ and $\hat{y}$. Indeed, it is clear that only a certain combination of parameters $q_1$ and $q_2$, say $f(q_1, q_2)$, can enter the commutation relation

$$\hat{y} \hat{x} = f(q_1, q_2) \hat{x} \hat{y},$$  \hspace{1cm} \text{(6.2)}$$

but a priori $f(q_1, q_2)$ could be a non-trivial function of both $q_1$ and $q_2$. However, a closer look at the physics of refined BPS states quickly shows that $f(q_1, q_2)$ is equal to either $q_1$ or $q_2$, depending on how one orients the brane in space–time. With our choice of conventions, it is the parameter $q_2$ that enters the commutation relation (6.2) in the refined context, and luckily the relation to knot theory variables $q$ and $t$ turns out to be just right [16]:

$$q = q_2, \quad t = -\frac{q_1}{q_2}$$  \hspace{1cm} \text{(6.3)}$$
so that when (6.2) is expressed in terms of \( q \) and \( t \), the parameter \( t \) does not appear in the commutation relation of \( \hat{x} \) and \( \hat{y} \), and therefore plays the role of the commutative deformation parameter. This explains why the “classical” limit (1.9) of refined/homological invariants is simply \( q \to 1 \) with fixed \( t \), as opposed to a more general limit of the form

\[
q^p t^q \to 1, \quad q^r t^s = \text{fixed},
\]

with some “exponents” \( p \), \( q \), \( r \) and \( s \). Note, with this choice of conventions, the so-called Nekrasov–Shatashvili limit [41] corresponds to studying closed refined BPS invariants and setting \( q_1 = 1 \), see Fig. 8. Expansion of the open refined brane amplitude around this limit was recently studied in [40], where it was argued that, at least in some class of examples, the “quantum” curve \( \hat{A}(\hat{x}, \hat{y}, q_2) \) has the same form as the classical curve \( A(x, y) \), i.e. is independent of the parameter \( q_2 \) as long as \( q_1 = 1 \), see also [42]. It would be interesting to study this further and, in particular, to see if the full quantum super-\( A \)-polynomial \( \hat{A}^{\text{super}} \) happens to coincide with the classical super-\( A \)-polynomial \( A^{\text{super}} \) in this class of examples.

The second important point, recently emphasized in [17], provides a similar explanation for the second commutative deformation parameter \( a \) which, when combined with the \( t \)-deformation, gives us the desired 2-parameter family studied in this paper. Indeed, since the highest weight of a \( SU(N) \) representation \( R \) has \( N - 1 \) components, \textit{a priori} one might expect that “color behavior” of \( sl(N) \) polynomial or homological knot invariants, such as \( J_R(K; q) \) or \( \mathcal{P}^{sl(N)}.R(K; q, t) \), is captured by a variety\(^8\) of dimension \( N - 1 \). In particular, when \( N = 2 \) this variety is one-dimensional, defined by a single polynomial \( A(x, y) \), which has to do with the fact that all irreducible representations of \( SU(2) \) are labeled by a single integer \( n = \dim R \).

On the other hand, when \( N > 2 \) the weight space has dimension \( N - 1 \) and the classical limit of recursion relations for \( J_R(K; q) \) or \( \mathcal{P}^{sl(N)}.R(K; q, t) \) is a higher-dimensional algebraic variety, generically defined by \( N - 1 \) equations,

\[
\mathcal{M}_K: \quad A_i(\vec{x}, \vec{y}) = 0, \quad i = 1, \ldots, N - 1,
\]

\(^8\) Cf. [14, Section 2.3] for a higher-rank version of the generalized volume conjecture.
in the “phase space” \((\mathbb{C}^* \times \mathbb{C}^*)^{N-1}/S_N\) of total dimension \(2N-2\). The standard arguments from Chern–Simons theory show that this variety is Lagrangian with respect to the holomorphic symplectic form \(\Omega_J = \frac{i}{\hbar} \sum_{i=1}^{N-1} \frac{dx_i}{x_i} \wedge \frac{dy_i}{y_i}\), thereby endowing it with the structure of the so-called \((A, B, A)\) brane, in the terminology of [43]. This curious fact has many far-reaching applications and consequences [44], but our interest here is merely in a simple fact that one of the defining polynomials in (6.5) is essentially the \(A\)-polynomial of the \(sl(2)\) theory. Indeed, if we restrict our attention to totally symmetric representations, then the system (6.5) collapses to a single equation, \(A^{Q-{\text{def}}}(x, y; a) = 0\), which must contain the ordinary \(A\)-polynomial as a factor since symmetric representations is all one has for \(N = 2\). Furthermore, it was argued in [17] that the \(Q\)-deformed \(A\)-polynomial \(A^{Q-{\text{def}}}(x, y; a)\) is equal to the augmentation polynomial of knot contact homology [26].

Finally, let us make a few remarks on the physical interpretation of the super-\(A\)-polynomial \(A^{\text{super}}(x, y; a, t)\). Even though the interpretation as a space of SUSY vacua described in Section 5 opens many doors for further study, it would still be interesting to understand the interpretation of \(a\)- and \(t\)-deformations in a good old Chern–Simons theory. Such interpretation is not of a purely academic interest: it could help to understand better the role of framing dependence in knot homologies which, up to present day, has been very mysterious. Understanding how framing affects homological knot invariants can help to reconcile different approaches to colored knot homologies, see [23, Section 6.2] for some discussion on this point.

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Appendix A. Colored superpolynomial for figure-eight knot

In this appendix we present how the formula for \(S^r\)-colored superpolynomial for figure-eight knot (2.12) arises (with \(n = r + 1\)), and discuss how its specialization relates to the colored HOMFLY polynomial found in [28]. The formula (2.12) arises essentially from rewriting of the expression conjectured in [25], which is postulated as follows.\(^9\) Firstly, as observed in [35] in some examples and conjectured to be true for every knot \(K\), the so-called “special” polynomial, \(i.e. q_1 \to 1\) limit of the HOMFLY polynomial \(P^R(K; A_f, q_1)\) colored by representation \(R\), has the following property

\[^9\] In typing this appendix we did our best to avoid several misprints which are present in the formulas in [25].
\[
\lim_{q_I \to 1} P^R(K; A_I, q_I) = \left( \lim_{q_I \to 1} P^{[1]}(K; A_I, q_I) \right)^{|R|}.
\] (A.1)

Note that here we use variables \( A_I \) and \( q_I \) which are to be identified with \( A \) and \( q \) used in [25]. In what follows we also use the notation

\[
\{x\} = x - x^{-1}, \quad [x] = \frac{q_I^x - q_I^{-x}}{q_I - q_I^{-1}}
\]

In case of the figure-eight knot it is known that \( P^{[1]}(4_1; A_I, q_I) = 1 + \{A\}^2 \), so that (A.1) takes form

\[
\lim_{q_I \to 1} P^R(4_1; A_I, q_I) = (1 + \{A\}^2)^{|R|} = \sum_{k=0}^{|R|} \frac{|R|!}{k! (|R| - k)!} \{A\}^{2k}.
\] (A.2)

It was postulated in [25] that to introduce the full \( q_I \)-dependence of the (reduced) colored HOMFLY polynomial one should simply replace ordinary numbers in the above expression by their \( q \)-deformations. In particular, for symmetric representation \( S^r \) represented by a Young diagram \([r]\) consisting of one row of \( r \) boxes, this deformation takes the following form

\[
P^{[r]}(4_1; A_I, q_I) = \sum_{k=0}^r \frac{|r|!}{[k]! [r-k]!} \prod_{i=0}^{k-1} \{A_I q_I^{r-i+1}\} \{A_I q_I^{r-i-1}\}.
\] (A.3)

This expression we would like further deform by introducing \( t_I \) dependence, which would encode Poincaré polynomials of homological figure-eight knot invariants. To this end we rewrite the above expression in the form

\[
P^{[r]}(4_1; A_I, q_I, t_I) = \sum_{k=0}^r \sum_{1 \leq i_1 < i_2 < \ldots < i_k \leq r} Z_{i_1}(A_I) Z_{i_2}(A_I q_I) Z_{i_3}(A_I q_I^2) \cdots Z_{i_k}(A_I q_I^{k-1}),
\] (A.4)

where

\[
Z_i(A_I) = \{A_I q_I^{2(r-i)+1}\} \{A_I q_I^{-1}\}.
\]

The expression (A.4) looks like a summation over boxes in a Young diagram, with contributions from each box being given by a function of its arm-length or leg-length. The proposal of [25] is to introduce a familiar generalization of this type of formula, by representing leg-length and arm-length contributions respectively by \( q_I \)- and \( t_I \)-dependent expressions, which can be achieved by a substitution

\[
Z_i(A_I) \to \zeta_i(A_I) = \{A_I q_I^{2(r-i)+1}\} \{A_I t_I^{-1}\} = Z_i(A_I) \frac{\{A_I t_I^{-1}\}}{\{A_I q_I^{-1}\}}.
\] (A.5)

Now we notice that (A.4), with \( Z_i \) replaced by \( \zeta_i \), can be rewritten as

\[
P^{[r]}(4_1; A_I, q_I, t_I)
\]

\[
= \sum_{k=0}^r \sum_{1 \leq i_1 < i_2 < \ldots < i_k \leq r} \zeta_{i_1}(A_I) \zeta_{i_2}(A_I q_I) \zeta_{i_3}(A_I q_I^2) \cdots \zeta_{i_k}(A_I q_I^{k-1})
\]
The contact structure can be introduced by replacing the cotangent bundle
\[ T \text{contact homology} \] in \([56,57]\) is similar to the topological A-model on
the manifold \(A\). In particular, the geometric set-up of the knot contact homology has been recently studied in \([17]\).

Appendix B. Knot contact homology and augmentation polynomial

This is the expression which we have been after. Now a change of variables from \( A_I, q_I, t_I \) to \( a, q, t \), given in (C.7), leads to the final formula (2.12) (where we use \( n = r + 1 \), and the range of summation can be trivially extended to infinity).

For completeness let us also state the formula for the unreduced colored HOMFLY polynomial given by Kawagoe in \([28]\) and used in \([17]\). This formula is written in grading conventions consistent with our notation, so that in terms of our variables \( a \) and \( q \) it takes form

\[
P_n^{\text{Kawagoe}}(4_1; a, q) = \frac{(a, q)_{n-1}}{(q, q)_{n-1}} \sum_{i=0}^{n} \sum_{j=0}^{i} (-1)^{i} a^{\frac{2i+3-3n}{2}} q^{\frac{2j+2+5-4(4i+7n-2a^2)}{2}} \times \frac{((q^{-i}, q)_{j}(q^{1-n}, q)_{i})^{2}(aq^{n-i-j-1}, q)_{i-j}}{(q, q)_{i}(q, q)_{j}(q^{n-i-j}, q)_{i-j}}.
\]

We verified that this formula agrees with \( t = -1 \) specialization of our expression \( P_n(4_1; a, q, t) \) given in (2.12), up to the unknot normalization \( \bar{P}_n(\varnothing; a, q, t) \) given in (2.2) and up to the overall sign

\[
P_n^{\text{Kawagoe}}(4_1; a, q) = (-1)^{n-1} \bar{P}_n(\varnothing; a, q, -1) P_n(4_1; a, q, -1).
\]

The contact structure describes knot invariants as invariants of the Legendrian submanifolds in the contact manifold \([26,45–55]\). In particular, the geometric set-up of the knot contact homology in \([56,57]\) is similar to the topological A-model on \( T^*M \) \([20–22]\), and the string-theoretical interpretation of the knot contact homology has been recently studied in \([17]\).

The contact structure can be introduced by replacing the cotangent bundle \( T^*M \) by the cosphere bundle \( ST^*M \), so that the knot is realized by an intersection with the unit conormal bundle \( L_K \) \([56,57]\). To extract the Legendrian isotopy invariant of \( L_K \), the framework of Legendrian contact homology \([58]\) and the Symplectic Field Theory \([59]\) can be applied, and knot invariants such as the \( A \)-polynomial can be obtained by the transverse knot contact homology \([26,54]\).

In \([26,51,52,54]\), the invariants of the knot contact homology \( HC_s(K) \) have been studied in terms of the differential graded algebra \( \mathcal{A} \) (abbreviated as “DGA”), which was introduced first in \([45]\). The DGA is a pair \((\mathcal{A}, \partial)\) which consists of the tensor algebra \( \mathcal{A} \) with grading and differential \( \partial \) lowering the degree by 1 unit, such that \( \partial^2 = 0 \). The differential is defined in terms of the automorphism \( \phi \in \text{Aut}(\mathcal{A}) \).
In a combinatorial formulation of the knot contact homology [51], the braid group $B_n$ defines the automorphism $\phi$ for the knot DGA $\text{Aut}(A_n)$ for the tensor algebra $A_n$ which consists of $n(n-1)$ generators $a_{ij}$ ($1 \leq i, j \leq n; i \neq j$). Accompanying the higher degree generators, the DGA is freely generated by

$$\{a_{ij}\}_{1 \leq i, j \leq n; i \neq j} \text{ degree 0,}$$

$$\{b_{ij}\}_{1 \leq i, j \leq n; i \neq j} \text{ degree 1,}$$

$$\{c_{ij}\}_{1 \leq i, j \leq n} \text{ degree 1,}$$

$$\{e_{ij}\}_{1 \leq i, j \leq n} \text{ degree 2.}$$  \hspace{1cm} (B.1)

We denote $A$ as the matrix $(a_{ij})$, where we set $a_{ii} = -2$ for all $i$, and similarly for $B := (b_{ij})$, $C := (c_{ij})$, $D := (d_{ij})$. For example, the $(2, 2p + 1)$ torus knot is described by $n = 2$ and braid group element $B = \sigma_1^{2p+1}$.

In the above basis, the automorphism action $\sigma_k (k = 1, \ldots, n - 1)$ for the braid group generator $\sigma_k \in B_n$ reads [51]

$$\phi_{\sigma_k} : \begin{cases} 
    a_{ki} \mapsto -a_{k+1,i} - a_{k+1,k}a_{ki}, & i \neq k, k + 1, \\
    a_{ik} \mapsto -a_{i,k+1} - a_{i,k}a_{k+1}, & i \neq k, k + 1, \\
    a_{k+1,i} \mapsto a_{ki}, & i \neq k, k + 1, \\
    a_{i,k+1} \mapsto a_{ik}, & i \neq k, k + 1, \\
    a_{k+1,k} \mapsto a_{k+1,k}, \\
    a_{i,j} \mapsto a_{ij}, & i, j \neq k, k + 1.
\end{cases} \hspace{1cm} (B.2)$$

In the definition of the differential, the extension map $\phi^\text{ext} : B_n \hookrightarrow B_{n+1} \hookrightarrow \text{Aut}(A_{n+1})$ is used which is the faithful representation of $B_n$. The inclusion $B_n \hookrightarrow B_{n+1}$ is obtained by adding the $(n + 1)$th strand, which does not interact with other $n$ strands. The automorphism $\phi^\text{ext}_B$ acts on $a_{i,n+1}$ and $a_{n+1,i}$ ($i = 1, \ldots, n$) as $n \times n$ matrices $\Phi^L_B$ and $\Phi^R_B$

$$\phi^\text{ext}_B(a_{i,n+1}) = \sum_{\ell=1}^{n} (\Phi^L_B)_{i\ell} a_{\ell,n+1}, \quad \phi^\text{ext}_B(a_{n+1,i}) = \sum_{\ell=1}^{n} a_{n+1,\ell} (\Phi^R_B)_{\ell i}. \hspace{1cm} (B.3)$$

The differential $\partial$ on $A_n$ is defined by

$$\partial A = 0,$$

$$\partial B = (1 - \Phi^L_B) \cdot A,$$

$$\partial C = A \cdot (1 - \Phi^R_B),$$

$$\partial D = B \cdot (1 - \Phi^R_B) - (1 - \Phi^L_B) \cdot C,$$

$$\partial e_i = (B + \Phi^L_B \cdot C)_{ii}. \hspace{1cm} (B.4)$$

In this way, the knot DGA is defined by a pair $(A_n, \partial)$, and the degree-0 transverse homology $HT_0(B)$ is given by

$$HT_0(B) = A_n/(1 - \Phi^L_B) \cdot A \cdot (1 - \Phi^R_B)). \hspace{1cm} (B.5)$$

The knot DGA can also be generalized to the algebra over the ring $R = \mathbb{Z} [\lambda^\pm, \mu^\pm]$, see [26]. Furthermore, in [54] the tensor algebra over $R[U, V]$ has been introduced. In this more general
framework $\phi_B$ and $\phi^\text{ext}$ are not changed, however $A$ is generalized to a pair consisting of $\hat{A}$ and $\check{A}$, such that

\[(\hat{A})_{ij} = \begin{cases} a_{ij}, & i > j, \\ -1 - \mu U, & i = j, \\ \mu U a_{ij}, & i < j, \end{cases} \quad (\check{A})_{ij} = \begin{cases} V a_{ij}, & i > j, \\ -V - \mu, & i = j, \\ \mu a_{ij}, & i < j. \end{cases}\]

The degree-0 infinity transverse homology of $B$ is given by

\[HT_0^\infty(B) = \left( A_n \otimes R[U^{\pm 1}, V^{\pm 1}] \right) / \left( \hat{A} - A'_B \cdot \Phi^L_B \cdot \check{A}, \check{A} - \hat{A} \cdot \Phi^R_B \cdot (A'_B)^{-1} \right),\]

where

\[A'_B = \text{diag}(\lambda, \mu - w(B) U/V - (sl(B) + 1)/2, 1, \ldots, 1),\]

and $w(B)$ and $sl(B)$ denote respectively the writhe and self-linking number.

To extract the topological information of the knot $K$ out of $HT^\infty$, we can consider so-called augmentation polynomial. The augmentation polynomial for $HT^\infty(K)$ is defined as the resultant of the ideal $I_K$ which comes from $\hat{A} - \Lambda'_B \cdot \Phi^L_B \cdot \check{A} = 0, \check{A} - \hat{A} \cdot \Phi^R_B \cdot (A'_B)^{-1} = 0$. Here we assume the abelian basis $a_{ij}$ for tensor algebra $A_n$. To reduce the number of variables, we use one of the conditions of the full DGA, which reads

\[A_0 - A'_B \cdot \Phi_K(A_0) \cdot (A'_B)^{-1} = 0,\]

where $(A_0)_{ij} = a_{ij}$ and $(A_0)_{ii} = 0$. Eliminating extra variables and taking the resultant, we find the augmentation polynomial $\text{Aug}_K(\mu, \lambda; U, V)$. As we will discuss in what follows, this polynomial is closely related to and generalizes the $A$-polynomial.

\section*{B.1. Augmentation polynomial for $(2, 2p + 1)$ torus knots}

As an example, in this section we study the knot contact homology and derive corresponding augmentation polynomials for $(2, 2p + 1)$ torus knots, see Table 9. While these results follow (implicitly) from the analysis in [26,52,54], we find it useful to write the resulting augmentation polynomials explicitly, and relate them directly to $t = -1$ specialization of super-$A$-polynomials for torus knots which we listed in Tables 5, 12 and 13.\(^\text{10}\)

We recall that $(2, 2p + 1)$ torus knots can be constructed from the $2p + 1$ braidings between 2 strands. Therefore the DGA for $B_2$ gives the knot contact homology for this class of torus knots. For $n = 2$ the action of $\phi$ yields simply [51]

\[\phi_{\sigma_1}: a_{12} \mapsto a_{21}, \quad a_{21} \mapsto a_{12},\]

and $\phi^{\text{ext}}_{\sigma_1}$ acts as

\[\phi^{\text{ext}}_{\sigma_1}: \begin{cases} a_{1*} \mapsto -a_{2*} - a_{21}a_{1*}, \\ a_{2*} \mapsto a_{1*}, \\ a_{s1} \mapsto -a_{s2} - a_{1s}a_{12}, \\ a_{s2} \mapsto a_{s1}, \end{cases}\]

where we denoted $*: = n + 1 = 3$. The action of $\phi^{\text{ext}}_{\sigma_1^{2p+1}}$ is obtained by iterating the above action $2p + 1$ times. The matrices for $\Phi^L_{\sigma_1^{2p+1}} (p = 1, 2, 3)$ are found as:

\(^{10}\) The Mathematica package for computing the transverse homology is available from Lenhard Ng’s website [60].
• $p = 1$:

\[
\begin{align*}
\Phi^L_{\sigma_1^3} &= \begin{pmatrix} 2a_{21} - a_{21}a_{12}a_{21} & 1 - a_{21}a_{12} \\ -1 + a_{12}a_{21} & a_{12} \end{pmatrix}, \\
\Phi^R_{\sigma_1^3} &= \begin{pmatrix} 2a_{12} - a_{12}a_{21}a_{12} & -1 + a_{12}a_{21} \\ -1 + a_{21}a_{12} & a_{21} \end{pmatrix}.
\end{align*}
\] (B.12)

• $p = 2$:

\[
\begin{align*}
\Phi^L_{\sigma_1^3} &= \begin{pmatrix} -3a_{21} + 4a_{21}a_{12}a_{21} - a_{21}a_{12}a_{21}a_{12}a_{21} & -1 + 3a_{21}a_{12} - a_{21}a_{12}a_{21}a_{12}a_{21} \\ 1 - 3a_{12}a_{21} - a_{12}a_{21}a_{12}a_{21} & -2a_{12} + a_{12}a_{21}a_{12}a_{21} \end{pmatrix}, \\
\Phi^R_{\sigma_1^3} &= \begin{pmatrix} -3a_{12} + 4a_{12}a_{21}a_{12} - a_{12}a_{21}a_{12}a_{21}a_{12} & 1 - 3a_{12}a_{21} + a_{12}a_{21}a_{12}a_{21}a_{12} \\ -1 + 3a_{21}a_{12} - a_{21}a_{12}a_{21}a_{12}a_{21} & -2a_{21} + a_{21}a_{12}a_{21}a_{12}a_{21} \end{pmatrix}.
\end{align*}
\] (B.13)

• $p = 3$:

\[
\begin{align*}
(\Phi^L_{\sigma_1^3})_{11} &= 4a_{21} - 10a_{21}a_{12}a_{21} + 6a_{21}a_{12}a_{21}a_{12}a_{21} - a_{21}a_{12}a_{21}a_{12}a_{21}a_{12}a_{21}, \\
(\Phi^L_{\sigma_1^3})_{12} &= 1 - 6a_{21}a_{12} + 5a_{21}a_{12}a_{12}a_{12} - a_{21}a_{12}a_{12}a_{12}a_{12}, \\
(\Phi^L_{\sigma_1^3})_{21} &= -1 + 6a_{12}a_{21} - 5a_{12}a_{21}a_{12}a_{21} + a_{12}a_{12}a_{12}a_{12}a_{12}, \\
(\Phi^L_{\sigma_1^3})_{22} &= 3a_{12} - 4a_{12}a_{21}a_{12} + a_{12}a_{21}a_{12}a_{12}, \\
(\Phi^R_{\sigma_1^3})_{11} &= 4a_{12} - 10a_{12}a_{21}a_{12} + 6a_{12}a_{21}a_{12}a_{12}a_{12} - a_{12}a_{21}a_{12}a_{12}a_{12}a_{12}, \\
(\Phi^R_{\sigma_1^3})_{12} &= -1 + 6a_{12}a_{21} + 5a_{12}a_{21}a_{12}a_{12} + a_{12}a_{12}a_{12}a_{12}a_{12}, \\
(\Phi^R_{\sigma_1^3})_{21} &= 1 - 6a_{21}a_{12} - 5a_{21}a_{21}a_{12}a_{12} + a_{21}a_{12}a_{12}a_{12}a_{12}, \\
(\Phi^R_{\sigma_1^3})_{22} &= 3a_{21} - 4a_{21}a_{12}a_{12} + a_{21}a_{12}a_{12}a_{12}a_{12}.
\end{align*}
\] (B.14)

For the write $w(a^{2p+1}) = 2p + 1$ and self-linking number $sl(a^{2p+1}) = 2p - 1$, we can describe the degree-0 infinity transverse homology $HT_0^\infty(T^{(2,2p+1)})$ of $(2, 2p + 1)$ torus knot combinatorially. To find the augmentation polynomial $\text{Aug}_{T^{(2,2p+1)}}(\mu, \lambda; U, V)$, we treat $a_{ij}$ as an abelian variable. The condition (B.9) relates $a_{12}$ and $a_{21}$

\[
a_{21} = \frac{\mu^{2p+1}U^p}{\lambda V^p}a_{12}.
\] (B.17)

and we denote $a_{12} =: x$ in the following.

---

11 The self-linking number $sl(B)$ is defined by

\[
sl(B) = w(B) - n(B),
\] (B.16)

where $n(B)$ denotes the number of braid strands. For $(2, 2p + 1)$-torus knots $n(B) = 2$.

The authors greatly appreciate to Lenhard Ng for explanation on this choice of self-linking number, and pointing out how to correct Table 9, (C.9), and (C.11) by a choice of $sl(B) = 1$. 

With the above prerequisites, the ideals \( \mathcal{I}^{(2,2p+1)} \) for

\[
HT_0^\infty (T^{(2,2p+1)}) \simeq \left( \mathbb{Z}[\lambda, \mu, U, V], \begin{bmatrix} \lambda & \mu & U & V \end{bmatrix} \right) / \mathcal{I}^{(2,2p+1)},
\]

which consist of polynomials \( f_s^{(2,2p+1)}(\mu, \lambda, U, V, x) \) (for \( s = 1, 2 \)), can now be found by appropriate manipulations in the ideal \( \mathcal{I}_K \) in the matrix form: \( \mathcal{I}_K = \{ \hat{A} - A'_{\mu} \cdot \Phi^L_{\mu} \cdot \hat{A}, \hat{A} - A \cdot \Phi^R_{\mu} \cdot (A'_{\mu})^{-1} \} \). We find the following results for several low values of \( p \):

- **\( p = 1 \):**
  \[
  f_1^{(2,3)} = V^2 \lambda + V \lambda \mu - Ux \mu^3 - Ux^2 \mu^4, \\
  f_2^{(2,3)} = V \lambda + UV \lambda \mu - Vx \lambda \mu - Ux^2 \mu^3.
  \]

- **\( p = 2 \):**
  \[
  f_1^{(2,5)} = V^5 \lambda^2 + V^4 \lambda^2 \mu + U^2 V^2 \lambda \mu^5 - U^2 V^3 \lambda^2 \mu^5 - 3U^2 V^2 \lambda^2 \mu^6 + U^4 x^4 \mu^{11}, \\
  f_2^{(2,5)} = V^2 \lambda + V^3 x \lambda + UV^2 \lambda \mu + 2V^2 x \lambda \mu - U^2 x^2 \mu^5 - U^2 x^3 \mu^6.
  \]

- **\( p = 3 \):**
  \[
  f_1^{(2,7)} = V^{10} \lambda^3 + V^9 \lambda^3 \mu - U^3 V^6 \lambda^2 \mu^7 - 3U^3 V^7 \lambda^2 \mu^7 - 6U^3 V^6 \lambda^2 \mu^8 + U^6 V^4 \lambda^4 \mu^{14} + 5U^6 V^3 \lambda^4 \mu^{15} - U^9 x^6 \mu^{22}, \\
  f_2^{(2,7)} = -V^6 \lambda^2 + 2V^7 x \lambda^2 - UV^6 \lambda^2 \mu + 3V^6 x \lambda^2 \mu + U^3 V^3 \lambda^2 \mu^7 - U^3 V^4 \lambda^3 \mu^7 - 4U^3 V^3 \lambda^3 \mu^8 + U^6 x^5 \mu^{15}.
  \]

Finally, the augmentation polynomials can be found as the resultants of \( f_1^{(2,2p+1)} \) and \( f_2^{(2,2p+1)} \) listed above, with respect to the variable \( x \). Explicit augmentation polynomials for \( p = 1, 2, 3 \), which we obtain in this way, are listed in Table 9.\(^{12}\) These augmentation polynomials contain a lot of interesting information, and relate to various incarnations of \( A \)-polynomials studied in knot theory context. Firstly, they are related to \( t = -1 \) specialization of super-\( A \)-polynomials. In particular, setting \( V = 1 \) and performing a change of variables (C.9), we reproduce the results listed in Table 5, with precise identification given in (C.10). Secondly, after the variable change (C.11) these augmentation polynomials reproduce \( Q \)-deformed \( A \)-polynomials derived in [17], see (C.12) for detailed identification. Also note that combining the changes of variables (C.9) and (C.11) gives a direct relation (2.37) between \( t = -1 \) specialization of the super-\( A \)-polynomial and \( Q \)-deformed \( A \)-polynomials of [17]. Finally, upon the specialization \( U = V = 1 \), the augmentation polynomial \( \text{Aug}_K(\mu, \lambda; U, V) \) reduces [26] to the \( SL(2) \) \( A \)-polynomial \( A_K(\mu, \lambda) \) studied in [2].

In view of all the relations discussed above, we expect that the full super-\( A \)-polynomial should also be found from an appropriate \( t \)-deformation of DGA.

\(^{12}\) In this table, we omitted some extra factors which appear in the resultant in the same manner as in super-\( A \)-polynomials.
Table 9
Augmentation polynomials for \( (2, 2p + 1) \) torus knots with \( p = 1, 2, 3 \). For their explicit relations to \( t = -1 \) specialization of super-\( A \)-polynomials, as well as other versions of \( A \)-polynomials arising in knot theory context, see discussion at the end of Section B.1.

| Knot | \( \text{Aug}_K(\mu, \lambda; U, V) \) |
|------|---------------------------------|
| \( \mathcal{T}^{(2,3)} \) | \( V^2(V + \mu)^2 - UV(V^2 + V\mu + 2\mu^2 - 2UV\mu^2 + U\mu^3 + U^2\mu^4)\lambda + U^2\mu^3(1 + U\mu) \) |
| \( \mathcal{T}^{(2,5)} \) | \( V^6(V + \mu)\lambda^3 - U^2V^4(V^4 + 3\mu + 2V^2\mu^2 - 2UV^3\mu^2 + 2V^3\mu - 2U^2V^2\mu^3 + 3\mu^4 \) |
| \( \mathcal{T}^{(2,7)} \) | \( V^{12}(V + \mu)\lambda^4 - U^2V^9(V^6 + V^3\mu + 2V^4\mu^2 - 2UV^3\mu^2 + 2V^3\mu^3 - 2UV^4\mu^3 \) |

Appendix C. Grading conventions and variable changes

There are many different variables and grading conventions used in recent literature on knot theory, refined topological vertex, and Chern–Simons theory; for example, the following symbols are often used: \( q, t, q_1, q_2, q, t, a, A, Q, \) etc. The purpose of this appendix is to summarize transformations and variable changes between those various conventions. We stress that, in general, one has to be particularly careful when different gradings are used — in such cases, transformations between various conventions amount not only to a simple redefinition of variables (for example, transpositions of Young diagrams which label colored superpolynomials may be involved in such a process). Detailed description of such phenomena has been given in [16]. In turn, without repeating this underlying machinery, our task here is merely to provide explicitly variable changes between most often conventions used in literature. Moreover, in the second part of this appendix, we summarize relations between notation used in writing super-\( A \)-polynomials, augmentation polynomials of [26], and \( Q \)-deformed polynomials of [17].

C.1. Choice of grading variables

In the knot theory context, the grading conventions used in this paper are the same as in [16,23]: the quantum parameter entering the commutation relations (1.3) is denoted by \( q \), the HOMFLY polynomial is expressed in terms of \( a \) and \( q \), and the Poincaré polynomial of knot homologies depends on a new parameter \( t \), so that the (colored) superpolynomials depend on variables \( a, q, t \). Moreover, the unrefined limit (reducing Poincaré polynomial to the Euler
characteristic) is obtained from $t \to -1$ limit (with other parameters fixed), and the reduction from the HOMFLY polynomial to $s\langle N \rangle$ quantum group invariant arises upon the substitution $a = q^N$ (with other parameters fixed). In what follows we relate this convention to other choices made in literature.

Firstly, we recall that certain expressions for colored superpolynomials, such as those for the unknot (2.2) and torus knots (2.32) considered in this paper, were derived in [16] from the viewpoint of Chern–Simons theory written in terms of parameters $A, q_1, q_2$. Here we define the normalized refined Chern–Simons amplitude

$$Z^R_{\text{ref}}(K; A, q_1, q_2) := \frac{Z^R_{SU(N)}(S^3; K, q_1, q_2)}{Z^R_{SU(N)}(S^3; \mathcal{O}_R; q_1, q_2)}. \tag{C.1}$$

For $K = T(2,2p+1)$ with $R = S^r$ and $R = A^r$, $Z^R_{\text{ref}}(K; A, q_1, q_2)$ yields

$$R = S^r: \quad Z^S_{\text{ref}}(T^{(2,2p+1)}; A, q_1, q_2) = A^{r/2} q_2^{-r/2} (q_2; q_1)_r \sum_{\ell=0}^r \frac{(q_2; q_1)_r (A; q_1)_r + \ell (q_2^{-1}; A; q_1)_r - \ell}{(A; q_1)_r} \times A^{-r} q_1^{-r} q_2^{r-\ell} \left[ (-1)^{r-\ell} A^2 q_1^{2-2z} q_2^{z-2} \right]^{2p+1}, \tag{C.2}$$

$$R = A^r: \quad Z^A_{\text{ref}}(T^{(2,2p+1)}; A, q_1, q_2) = (-1)^r A^{-r/2} q_2^{-r/2} (q_2; q_1)_r \times \sum_{\ell=0}^r \frac{(q_1; q_2)_r (A^{-1}; q_2)_r + \ell (q_1^{-1}; A^{-1}; q_2)_r - \ell}{(q_1; q_2)_r} \times \frac{A^r q_1^{-r} q_2^{-z} q_1^{z-2} q_2^{2-z}}{(-1)^{r} A^2 q_1^{2-2z} q_2^{z-2}} \left[ (-1)^{r} A^2 q_1^{2-2z} q_2^{z-2} \right]^{2p+1}, \tag{C.3}$$

where $A = q^N$.

In Table 10, we describe the change of variables between the colored superpolynomials $\mathcal{P}^S(K; a, q, t)$ and the refined Chern–Simons amplitude $Z^S_{\text{ref}}(K; A, q_1, q_2)$ for the GS grading. This change of variable can be found by combining (2.1) and further change of variables

$$(A, q_1, q_2) \mapsto (A, q_2^{-1}, q_1^{-1}) \tag{C.4}$$

which exchanges the refined Chern–Simons amplitudes (C.1) between $R = S^r$ and $R = A^r$. For $(2, 2p+1)$ torus knots, $Z^S_{\text{ref}}(T^{(2,2p+1)}; A, q_1, q_2)$ coincides with the colored superpolynomial $\mathcal{P}^S / A^r (T^{(2,2p+1)}; a, q, t)$ by implementing a factor and the change of variables in Table 10

$$\mathcal{P}^S(T^{(2,2p+1)}; a, q, t) = (-1)^{pr} \left( \frac{q_1}{q_2} \right)^{pr/2} Z^S_{\text{ref}}(T^{(2,2p+1)}; A, q_1, q_2), \tag{C.5}$$

$$\mathcal{P}^A(T^{(2,2p+1)}; a, q, t) = (-1)^{pr} \left( \frac{q_2}{q_1} \right)^{pr/2} Z^A_{\text{ref}}(T^{(2,2p+1)}; A, q_1, q_2). \tag{C.6}$$

On the other hand, the colored superpolynomial for figure-eight knot is derived in Appendix A using variables $A_1, q_1, t_1$ (which should be identified respectively with $A, q, t$ in [25]). In order to transform these variables to our grading and $a, q, t$ parameters in which the colored superpolynomial (2.12) is written, we need the following transformation
Table 10
Changes of variables between various conventions used in literature.

| Variables | Change of variables | Inverse relation |
|-----------|---------------------|-----------------|
| Refined SU(N) CS [34] | $(t^N, q, t)$ | $(A, q_1, q_2)$ |
| $(t^N, q, t)$ | $=(A, q_1, q_2)$ | $=(t^N, q, t)$ |
| Refined CS in [25, 35] | $(A_1, q_1, t_1)$ | $(A, q_1, q_2)$ |
| $(A_1, q_1, t_1)$ | $=(A^{1/2}, q^{1/2}, -q^{-1/2})$ | $=(A^{1/2}_1, q^{1/2}_1, t^{1/2}_1)$ |
| GS grading: $\mathcal{P}^{ST}$ [23] | $(a, q, t)$ | $(A, q_1, q_2)$ |
| $(a, q, t)$ | $=(A(q_1/q_2)^{3/2}, q_1, -(q_2/q_1)^{1/2})$ | $=(-at^2, q, qt^2)$ |
| GS grading: $\mathcal{P}^{A^r}$ [23] | $(a, q, t)$ | $(A, q_1, q_2)$ |
| $(a, q, t)$ | $=(A(q_2/q_1)^{1/2}, q_2, -(q_1/q_2)^{1/2})$ | $=(-at, qt^2, q)$ |
| DGR grading [18] | $(a, q, t)$ | $(A, q_1, q_2)$ |
| $(a, q, t)$ | $=(A^{1/2}(q_2/q_1)^{1/4}, q^{1/2}_2, -(q_1/q_2)^{1/2})$ | $=(-a^2t, q^2t^2, q^2)$ |
| HOMFLY in [17] | $(Q, q)$ | $(a, q)$ with $t = -1$ |
| $(Q, q)$ | | $(Q, q)$ |

\[ q_1^2 = q, \quad A_1^2 = -at^3, \quad t_1 = -tq^{1/2}. \] (C.7)

This transformation can be found as a composition of transformations given in the second and the third row of Table 10. More generally, for other pairs of conventions, Table 10 can be used to find how they are related, by reducing them to our $a, q, t$ choice in an intermediate step.

C.2. Conventions for (deformed) A-polynomials and augmentation polynomials

Upon substitution $t = -1$ the super-$A$-polynomial reduces to $a$-deformed version of the $A$-polynomial, which already appeared in literature under two different guises: as the so-called augmentation polynomial of knot contact homology in [26], and as $Q$-deformed $A$-polynomial in [17]. While these three objects are clearly closely related, they were introduced naturally from different perspectives and using different conventions. Here we discuss how to relate these different conventions to each other.

Let us also recapitulate that, firstly, $t = -1$ specialization of super-$A$-polynomial gives a polynomial in variables $x$ and $y$, which depends on a parameter $a$. Secondly, the augmentation polynomial of [26] is written in terms of variables $\lambda$ and $\mu$, and it depends additionally on $U$ and $V$. Thirdly, the $Q$-deformed $A$-polynomial in [17] is a polynomial in $a$ and $\beta$, which depends on a parameter $Q$. One should also be aware that explicit relations between these sets of variables may depend on a particular knot which is studied. In what follows we carefully discuss the form of these relations for $(2, 2p + 1)$ torus knots. Independently, the identification of variables between super-$A$-polynomial and $Q$-deformed $A$-polynomial for the figure-eight knots is given in (2.22).

Let us focus now on the case of $(2, 2p + 1)$ torus knots, and relate first $t = -1$ specialization of super-$A$-polynomial $A_{\text{super}}(x, y; a, -1)$ to the augmentation polynomial $\text{Aug}(\mu, \lambda; U, 1)$. The relation between our variables $(x, y)$ and the variables $(\mu, \lambda)$ can be easily deduced from the specialization to ordinary $A$-polynomial, cf. (1.18). Indeed, as proved in [26, Proposition 5.9], the augmentation polynomial contains $A$-polynomial as a factor. For instance, the ordinary $A$-polynomial for the trefoil knot is given in (2.29), and comparing with the results in [54] we see that the following identification must be made
\[ A^{\text{super}}(x, y; a = 1, t = -1) = -(x - 1)(y - 1)(y + x^3) = -\text{Aug}(\mu, \lambda; U = 1, V = 1) = (\lambda - 1)(\mu + 1)(\lambda - \mu^3). \]

In consequence we deduce the following relation between the variables:

\[ x = -\mu, \quad y = \lambda. \]  

(C.8)

More generally, we would like to understand the role of our parameter \( a \) from the contact homology viewpoint. We find that for \((2, 2p + 1)\) torus knots, if one applies the following identification

\[ x = -\mu, \quad y = \frac{1 + \mu}{1 + U\mu} \lambda, \quad t = -1, \quad a = U, \quad V = 1, \]  

(C.9)

then the super-\( A \)-polynomial and the augmentation polynomial are related as follows

\[ A^{\text{super}}_{T(2, 2p+1)}(x, y; a, t = -1) = \frac{(1 + \mu)^p}{(1 + U\mu)^p+1} \text{Aug}_{T(2, 2p+1)}(\mu, \lambda; U, V = 1). \]  

(C.10)

Note that for \( U = 1 \) the relations (C.9) reduce to (C.8).

On the other hand, one can relate the augmentation polynomial for torus knots to the \( Q \)-deformed \( A \)-polynomial in [17] by the following identification of parameters

\[ \lambda = Q^p \beta^{4p+2} \alpha, \quad \mu = -\beta, \quad U = Q, \]  

(C.11)

which leads to the relation

\[ \text{Aug}_{T(2, 2p+1)}(\mu, \lambda; U, V = 1) = \beta^{p(2p+1)} Q^{p+1} A^{Q,\text{def}}_{T(2, 2p+1)}(\alpha, \beta; Q). \]  

(C.12)

Combining transformations (C.9) and (C.11), one can directly relate super-\( A \)-polynomial to \( Q \)-deformed \( A \)-polynomial. The resulting identification of parameters is given explicitly in (2.37).

Finally let us explain why in (2.22), (2.37), as well as (C.9) a meromorphic factor \( \frac{1 - Q\beta}{1 - \beta} = \frac{1 - ax}{1 - x} \) appears in the change of variable \( y \). This factor is a consequence of the fact that the super-\( A \)-polynomial discussed in this paper arises from analysis of reduced colored superpolynomials, while the augmentation polynomial or \( Q \)-deformed polynomial considered in [17,26] are related to unreduced knot invariants. The reduced superpolynomial differs from the unreduced one by the unknot factor

\[ \hat{\mathcal{P}}^R(K; a, q, t) = \mathcal{P}^R(\bigotimes; a, q, t)\mathcal{P}^R(K; a, q, t). \]  

(C.13)

One explicit example of such a relation is given in (A.7) for figure-eight knot (where the overall sign difference arises from a particular choice of unknot normalization, and this is not relevant in what follows). For the symmetric representation \( R = S^{p-n-1} \), the unreduced colored superpolynomial for the unknot \( \mathcal{P}_n(\bigotimes; a, q, t) \) is given explicitly in (2.2), and obeys the recursion relation (2.4).

Now the recursion relation for the reduced superpolynomial

\[ \hat{A}^{\text{super}}(\hat{x}, \hat{y}; a, q, t)\mathcal{P}_n = 0 \]  

(C.14)

leads to the following recursion for the unreduced superpolynomial

\[ A^{\text{super}}(x, y; a = 1, t = -1) = -(x - 1)(y - 1)(y + x^3) = -\text{Aug}(\mu, \lambda; U = 1, V = 1) = (\lambda - 1)(\mu + 1)(\lambda - \mu^3). \]
\[ 0 = \left[ \bar{P}_n(t) \right] A_{\text{super}}(\hat{x}, y; a, q, t) \bar{P}_n(t) \]
\[ =: A_{\text{super}}(\hat{x}, y; a, q, t) \bar{P}_n. \]

where
\[ \hat{x}' = \bar{P}_n(t) \hat{x} \bar{P}_n(t)^{-1}, \quad \hat{y}' = \bar{P}_n(t) \hat{y} \bar{P}_n(t)^{-1}. \]

Using the recursion relation (2.4), we find
\[ \hat{x}' = \bar{P}_n(t) \hat{x} \bar{P}_n(t)^{-1} \hat{x} = \hat{x}, \]
\[ \hat{y}' = \bar{P}_n(t) \hat{y} \bar{P}_n(t)^{-1} \hat{y} = \left( -at^3 q \right)^{1/2} \frac{1 - q^{n - 1}}{1 + at^3 q^{n - 1}} \hat{y}. \]

Therefore we conclude that in the classical limit \( \hbar \to 0 \), the super-\( A \)-polynomial for reduced and unreduced superpolynomials, \( A_{\text{super}}(x, y; a, t) \) and \( A_{\text{super}}(x', y'; a, t) \), are related by the change of variables
\[ x = x', \quad y = \left( -at^3 \right)^{-1/2} \frac{1 + at^3 x}{1 - x} y'. \]

For \( t = -1 \) this change of variables further reduces to
\[ x = x', \quad y = -a^{-1/2} \frac{1 - ax}{1 - x} y'. \]

This is therefore the origin of the meromorphic factor \( \frac{1 - ax}{1 - x} \) in the change of \( y \)-variables in (2.22), (2.37) and (C.9).

### Appendix D. Super-\( A \)-polynomial for \( x = 1 \), and for (2, 9) and (2, 11) torus knot

| Knot | \( A_{\text{super}}^K(x, y; a, t) \) |
|------|----------------------------------|
| \( T(2,3) \) | \( y^3 - a^{-1} t^{-2} (1 + at)(1 + t^2(1 + at)) y^2 \) |
| \( T(2,5) \) | \( y^2 - a (1 + t^2(1 + at)) y \) |
| \( T(2,7) \) | \( y^3 - a^{-2} (1 + t^2(1 + at)) y^2 \) |
| \( T(2,9) \) | \( y^4 - a^{-3} (1 + t^2(1 + at) + t^4) y^2 \) |
| \( T(2,11) \) | \( y^4 - a^{-4} (1 + t^2(1 + at) + t^4 + t^6) y^2 \) |

| Knot | \( A_{\text{super}}^K(x, y; a, t) \) |
|------|----------------------------------|
| \( T(2,9) \) | \( y^5 - \frac{a^4}{1 + at^3 x} (1 - t^2 x + 2 t^2 x^2 + 2 a^3 x^2 - 2 a t^3 x^3 + 3 t^4 x^4 + 4 a t^5 x^4 + a^2 t^6 x^4 - 3 t^6 x^5) \) |
| | \(- 4 a t^7 x^5 - a^2 t^8 x^5 + 4 a^3 t^8 x^6 + 6 a t^7 x^6 + 2 a^2 t^8 x^6 - 4 t^8 x^7 - 6 a t^9 x^7 - 2 a^2 t^{10} x^7 + 5 t^9 x^8 + 8 a t^9 x^8 + 3 a^2 t^{10} x^8 + a t^{11} x^9 - 3 a^2 t^{12} x^9 + 4 a^2 t^{12} x^{10} y^4 + \frac{a^4 t^{10} (-1 + x) x^9}{(1 + at^3 x)^2} (4 - 3 t^2 x + at^3 x) \) |
| | \(+ 9 t^2 x^2 + 12 a^3 x^2 + 3 a^2 t^4 x^2 - 6 t^4 x^3 - 6 a^2 t^5 x^3 + 12 t^4 x^4 + 24 a t^5 x^4 + 18 a^2 t^6 x^4 + 6 a^3 t^7 x^4 \) |
| Knot | \( A^{\text{super}}_K \times, y; a, t \) |
|------|---------------------------------|
| \( (2,1) \) | \( y^6 - \frac{a^3}{1+at+x} (1 - t^2 x + 2t^2 x^2 + 2at^3 x^2 - 2a^2 t^3 x^2 + 2at^4 x^3 + 4at^5 x^4 + 2t^6 x^4 \) |

\[
\begin{align*}
-6a^6 t^5 & - 9at^7 x^5 - 6a^2 t^8 x^5 - 3a^3 t^9 x^5 + 10a^6 t^9 x^5 + 27a^2 t^{12} x^6 + 16a^3 t^{13} x^6 \\
+ 3a^3 t^{10} x^6 + 4at^9 x^7 - 6a^2 t^{11} x^7 - 2a^2 t^{12} x^7 + 12a^2 t^{13} x^8 + 18a^3 t^{11} x^8 + 6a^4 t^{12} x^8 \\
+ 3a^3 t^{13} x^9 - 3a^3 t^{14} x^9 + 6a^4 t^{14} x^{10} + \frac{(a_{12} + b_0 (1 + at + x)^{18}}{(1 + at + x)^3} - 6 t^2 x + 3at^3 x + 12t^2 x^2 \\
+ 18at^3 x^2 + 6at^4 x^2 - 4t^4 x^3 + 6a^2 t^6 x^3 + 2a^2 t^7 x^3 + 10t^4 x^4 + 24at^5 x^4 + 27a^2 t^6 x^4 \\
+ 16a^3 t^7 x^4 + 3a^4 t^8 x^4 + 6at^7 x^5 + 9at^8 x^5 + 6a^3 t^9 x^5 + 3a^4 t^{10} x^5 + 12a^2 t^8 x^6 + 24a^3 t^9 x^6 \\
+ 18a^4 t^{10} x^6 + 6a^5 t^{11} x^6 + 6a^3 t^{11} x^7 + 6a^4 t^{12} x^7 + 9a^4 t^{12} x^8 + 12a^5 t^{13} x^8 + 3a^6 t^{14} x^8 \\
+ 3a^5 t^{15} x^9 - 6a^6 t^{16} x^9 + 4a^6 t^{16} x^{10} y^2 + \frac{a_{16} (1 + at + x)^{27}}{(1 + at + x)^9} \times (-4 - t^2 x + 3at^3 x + 5t^5 x) \\
+ 8at^3 x^2 + 3at^4 x^3 + 4at^5 x^4 + 6at^6 x^5 + 2a^2 t^7 x^7 + 4a^2 t^8 x^7 + 6a^3 t^9 x^4 + 2a^4 t^8 x^4 \\
+ 3a^3 t^9 x^5 + 4a^4 t^{10} x^5 + 5^5 t^11 x^5 + 3a^4 t^{10} x^6 + 4a^5 t^{11} x^6 + 6^2 t^{12} x^6 + 2a^5 t^{13} x^7 \\
+ 2a^{6} t^{14} x^7 + 2a^{6} t^{14} x^8 + 2a^{6} t^{15} x^8 + a^{7} t^{17} x^9 + a_{8} t^{18} x^{10} y - \frac{a_{20} (1 + at + x)^{36}}{(1 + at + x)^4} \\
\end{align*}
\]

Table 13

Super-\( A \)-polynomial for \( (2, 2p + 1) \) torus knot with \( p = 5 \). For super-\( A \)-polynomials for torus knots with \( p = 1, 2, 3, 4 \) see Tables 5 and 12.
Table 13 (continued)

| Knot | $A_K^{\text{super}}(x, y; a, t)$ |
|------|---------------------------------|
|      | $+ a \frac{a_2^2 a_5 (-1 + a)^3 + 3}{(1 + a^3)^3} \left( 10 - 4 t^2 x + 6 a^3 t + 20 t^2 x^2 + 32 a^4 t^3 x^2 + 12 a^7 t^4 x^2 - 5 t^4 x^3 ight)$ |
|      | $+ 4 a t^3 x + 15 a^2 t^6 x^2 + 6 a^3 t^7 x^3 + 15 t^4 x^4 + 40 a^4 t^8 x^5 + 52 a^7 t^9 x^6 + 36 a^8 t^{10} x^7$ |
|      | $+ 9 a^4 t^{13} x^8 + 10 a^7 t^{15} x^9 + 20 a^2 t^{18} x^{10} + 21 a^3 t^{21} x^{11} + 14 a^4 t^{24} x^{12} + 32 a^5 t^{27} x^{13} + 50 a^6 t^{30} x^{14} x^2 + 20 a^7 t^{33} x^{15} x^2$ |
|      | $+ 48 a^8 t^{36} x^{16} + 48 a^9 t^{39} x^{17} + 24 a^2 t^{42} x^{18} + 4 a^4 t^{45} x^{19} + 12 a^7 t^{48} x^{20} + 21 a^8 t^{51} x^{21} + 21 a^9 t^{54} x^{22} x^2$ |
|      | $+ 14 a^3 t^{57} x^{23} + 5 a^6 t^{60} x^{24} + 18 a^4 t^{63} x^{25} + 36 a^5 t^{66} x^{26} + 26 a^6 t^{69} x^{27} + 8 a^7 t^{72} x^{28} + 9 a^5 t^{75} x^{29} + 10 a^6 t^{78} x^{30} + a^7 t^{81} x^{31} + 12 a^6 t^{84} x^{32} x^2 + 16 a^7 t^{87} x^{33} x^2 + 4 a^8 t^{90} x^{34} x^2$ |
|      | $+ 4 a^7 t^{93} x^{35} - a^8 t^{96} x^{36} + 5 a^8 t^{99} x^{37} + 5 a^8 t^{102} x^{38} y^2 = \frac{a^2 t^{48} (-1 + x)^4 x^{44}}{(1 + a^3)^3} (5 - t^2 x + 4 a t^3 x + 6 t^2 x^2 + 10 a t^2 x^2 + 5 a^2 t^6 x^3 + 8 a^2 t^6 x^3 + 3 a^2 t^7 x^5 + 5 a^2 t^7 x^5 + 8 a^3 t^8 x^4 + 3 a^4 t^8 x^4$ |
|      | $+ 4 a^3 t^9 x^5 + 6 a^4 t^{10} x^5 + 2 a^5 t^{11} x^5 + 4 a^4 t^{10} x^6 + 6 a^5 t^{11} x^6 + 2 a^6 t^{12} x^6 + 3 a^5 t^{13} x^7$ |
|      | $+ 4 a^6 t^{14} x^7 + a^7 t^{15} x^7 + 3 a^6 t^{14} x^8 + 4 a^7 t^{15} x^8 + 4 a^8 t^{16} x^8 + 2 a^7 t^{17} x^9$ |
|      | $+ 2 a^8 t^{18} x^9 + 2 a^8 t^{18} x^{10} + 2 a^9 t^{19} x^{10} + 4 a^9 t^{21} x^{11} + 10 a^{10} t^{22} x^{12} y + \frac{2 a^{10} t^{60} (-1 + x)^5 x^{55}}{(1 + a^3)^3}$ |

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