D-MODULES OF PURE GAUSSIAN TYPE AND ENHANCED IND-SHEAVES

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Abstract. Differential systems of pure Gaussian type are examples of D-modules on the complex projective line with an irregular singularity at infinity, and as such are subject to the Stokes phenomenon. We employ the theory of enhanced ind-sheaves and the Riemann–Hilbert correspondence for holonomic D-modules of A. D'Agnolo and M. Kashiwara to describe the Stokes phenomenon topologically. Using this description, we perform a topological computation of the Fourier–Laplace transform of a D-module of pure Gaussian type in this framework, recovering and generalizing a result of C. Sabbah.

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1. Introduction

The study of D-modules with irregular singularities has recently experienced new impulses by a remarkable result of A. D’Agnolo and M. Kashiwara, the Riemann–Hilbert correspondence for holonomic D-modules (see [5]). It states that on a complex manifold $X$ there is a fully faithful functor

$$\text{Sol}_E^E : \text{D}^b_{\text{hol}}(\mathcal{D}_X)^{\text{op}} \hookrightarrow \text{E}^b(\mathcal{I}C_X),$$

associating to any holonomic D-module an object in the category of enhanced ind-sheaves from which one can reconstruct the D-module. The construction of the target category is technical, but it is related to sheaf theory of vector spaces and hence of a topological nature. The theory has since been applied to the study of Stokes phenomena and Fourier–Laplace transforms (see e.g. [21], [6], [4], [13]). Other recent approaches to the study of Fourier transforms of Stokes data have been developed in [24] and [27].

In their original article [5, §9.8], the authors give an outlook on a topological study of the Stokes phenomenon of a D-module. In this paper, we develop rigorously these ideas in the case of D-modules of pure Gaussian type $\mathcal{M}$, meromorphic connections on $\mathbb{P} = \mathbb{P}^1(\mathbb{C})$ with a unique (and irregular) singularity at $\infty$ and exponential factors $-\frac{c}{2}z$ in the corresponding Levelt–Turrittin decomposition (for $z'$ a local coordinate at $\infty$). In this precise form they were studied by C. Sabbah in [30] using Deligne’s approach of Stokes-filtered local systems (see [8], [23] and [29]) in order to find a transformation rule for the Stokes data attached to such a module. Similar (and more general) systems of differential equations with exponents of pole order 2 have already been introduced by P. Boalch in [2] and [3] (where they are called “type 3” connections) with a different motivation. In the latter article, the author shows that a large class of certain quiver varieties arises as moduli spaces (wild character varieties) of such systems and uses this result to construct symplectic isomorphisms between these moduli. The study of Fourier–Laplace transforms is especially interesting in the Gaussian case since this class is invariant: The Fourier–Laplace transform of this kind of system has again a formal type with exponential factors of pole order 2. Moreover, studying these connections is a natural step further, given that the theory of enhanced ind-sheaves has already proved to be useful in the case of exponents of pole order 1 (cf. e.g. [4]), which play a prominent role in mirror symmetry.

It is the main purpose of the present article to reconstruct the results of [30] about the Fourier–Laplace transform of Stokes data with the new methods and to show how these computations can without much effort be adapted to more general cases. This research is based upon the dissertation [11].

Let us briefly outline the main ideas and the structure of the article:

In the second section, we recall the basic notation and results from the theories of D-modules and enhanced ind-sheaves.

The third section then collects well-known results about Stokes phenomena: Classically, the Stokes phenomenon manifests itself in the fact that a formal solution of a differential equation has different convergent asymptotic lifts in different sectors around an irregular singularity. In the language of D-modules, this is expressed by the statement that the formal Levelt–Turrittin decomposition can locally (on sufficiently small sectors) be lifted to an analytic decomposition. By the Riemann–Hilbert correspondence, this induces a decomposition of the associated topological object $\text{Sol}_E^E(\mathcal{M})$ (Proposition 3.1).

In Sections 4–7, we introduce the notion of D-modules of pure Gaussian type in the language of D-modules and describe step-by-step the topological object of enhanced solutions $\text{Sol}_E^E(\mathcal{M})$ of such a D-module $\mathcal{M}$: Starting from the Stokes
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phenomenon, which yields a direct sum decomposition on small sectors, we discuss how large the radius and angular width of these sectors may be, introducing notions like Stokes multipliers in this framework. It will finally turn out (Theorem 7.2) that \( \text{Sol}^E_{XY}(M) \) is described by an ordinary sheaf on \( C \times \mathbb{R} \), which in turn is determined by a small set of linear algebra data, the Stokes data. In the spirit of [30], we present Stokes data and a Riemann–Hilbert correspondence for D-modules of pure Gaussian type in Section 8.

We will then use this description to compute the Fourier–Laplace transform of a D-module of pure Gaussian type and describe its Stokes data in terms of the Stokes data of the original system. This computation, too, will involve (constructible) sheaves rather than enhanced ind-sheaves in the end and will therefore reduce to calculations in algebraic topology (cohomology groups with compact support). For this purpose, we recall the notions of Fourier–Laplace transform for D-modules of pure Gaussian type in Section 8 before we carry out our computations in the two final sections.

Compared to the approach via Stokes-filtered local systems, our considerations have various advantages: Although the theory is a priori more involved, it turns out that the actual computations to be made are computations in the theory of sheaves of vector spaces and algebraic topology. In particular, one does not need to deal with filtrations, which are often more intricate to handle. A particularly nice feature of this new approach in dealing with integral transforms is the fact that the functor \( \text{Sol}^E_X \), which we use for translating between D-modules and topology, is compatible with proper direct images. In the context of Stokes filtrations, the Riemann–Hilbert functor does not have this property. Instead, it was necessary to deal with sequences of blow-ups to compute direct images (cf. [10] and [30]), using a result of Mochizuki ([25]). Finally, our method of computation needs less input in the following sense: By results like the stationary phase formula (see [28] and [6]), we could know a priori that the Fourier–Laplace transform of a D-module of pure Gaussian type is again of pure Gaussian type, and we can explicitly write down the exponential factors of the Fourier–Laplace transform. However, this a-priori-knowledge does not enter our arguments, but is rather obtained as a by-product of our computations automatically.

Our main results are the following: We first recover a theorem of C. Sabbah ([30, Theorem 4.2]), who proved an explicit transformation rule for Stokes data in the case where all the parameters \( c \) appearing in the exponential factors share the same argument. In Theorem 10.1, we prove such a transformation rule for enhanced sheaves of pure Gaussian type, which as a corollary (Corollary 10.2) yields the result from loc. cit. We then show how such a result can be generalized to situations with weaker assumptions on the parameters. Therefore, we treat a more general case (Theorem 11.2), illustrating how the methods of the above theorem are naturally adapted to other situations.

2. ENHANCED IND-SHEAVES AND D-MODULES

Let \( X \) be a complex manifold. We denote the field of complex numbers by \( k = \mathbb{C} \). We mainly use the notation of [17] and [5].

Denote by \( \mathcal{D}_X \) the sheaf of rings of differential operators on \( X \), by \( \text{Mod}(\mathcal{D}_X) \) the category of (left) \( \mathcal{D}_X \)-modules and by \( \text{D}^b(\mathcal{D}_X) \) its bounded derived category. Let \( \text{Mod}_\text{hol}(\mathcal{D}_X) \) (resp. \( \text{D}^b_{\text{hol}}(\mathcal{D}_X) \)) be the full subcategory of objects which are holonomic (resp. have holonomic cohomologies). (We refer to [15], [12] and [11] for details on D-modules.)

In [5], the authors introduced the triangulated category \( \text{E}^b(\mathcal{I}k_X) \) of enhanced ind-sheaves on \( X \) as a quotient of the derived category of ind-sheaves on \( X \times (\mathbb{R} \cup \{ \pm \infty \}) \).
Together with the convolution product $\otimes$ it is a tensor category, and an important object is
\[ k_X^E := \lim_{\alpha \to \infty} k_{\{ t \geq \alpha \}}. \]

They proved the following result, which is a generalization of the classical Riemann–Hilbert correspondence (see [14]) to not necessarily regular holonomic D-modules.

**Theorem 2.1** (cf. [5, Theorem 9.5.3]). The functor of enhanced solutions
\[ \text{Sol}_X^E : D^b_{\text{hol}}(\mathcal{D}X)^{\text{op}} \to E^b(\mathcal{I}k_X) \]
is fully faithful.

By this result, the object $\text{Sol}_X^E(\mathcal{M})$ is the topological counterpart of a D-module $\mathcal{M}$, containing all the information about $\mathcal{M}$. In particular, it must encode the Stokes phenomenon.

We refer to [5] for further details on enhanced ind-sheaves (see also [7], [20], [16]). Let us only recall the bifunctor (cf. [5, Definition 4.5.2])
\[ \pi^{-1}(\bullet) \otimes (\bullet) : D^b(k_X) \times E^b(\mathcal{I}k_X) \to E^b(\mathcal{I}k_X), \]
where $\pi : X \times \mathbb{R} \to X$ is the projection. This functor enables us to consider the “restriction” $\pi^{-1}k_Z \otimes K$ of an enhanced ind-sheaf $K \in E^b(\mathcal{I}k_X)$ to a locally closed subset $Z \subseteq X$. (One considers this object rather than the inverse image along the embedding since it keeps track of the behaviour at the boundary of $Z$.) In this way, one can use gluing techniques similar to sheaf theory in $E^b(\mathcal{I}k_X)$ by carrying over sequences of sheaves like
\[ 0 \to k_{Z_1 \cup Z_2} \to k_{Z_1} \oplus k_{Z_2} \to k_{Z_1 \cap Z_2} \to 0 \]
for two closed subsets $Z_1, Z_2 \subseteq X$. Thus, given a description of an enhanced ind-sheaf on two sets, one can obtain a description on their union. In fact, although the third object of a distinguished triangle is generally unique up to (non-unique) isomorphism only, uniqueness will always be guaranteed in our constructions (by [19, Proposition 10.1.17] or [9, Corollary IV.1.5]).

2.1. **Enhanced sheaves.** There is a natural functor $D^b(k_X \times \mathbb{R}) \to E^b(\mathcal{I}k_X)$, and we consider sheaves on $X \times \mathbb{R}$ as enhanced ind-sheaves through this functor. Objects of $D^b(k_X \times \mathbb{R})$ will be called **enhanced sheaves** on $X$. (Note that other authors usually define the category of enhanced sheaves as a certain subcategory of $D^b(k_X \times \mathbb{R})$, cf. [6], [4]. We will not introduce it here, although we actually work in this subcategory.)

There is a convolution product on $D^b(k_X \times \mathbb{R})$ defined by
\[ \mathcal{F} \ast \mathcal{G} := R\mu(q_1^{-1} \mathcal{F} \otimes q_2^{-1} \mathcal{G}), \]
where the maps $\mu, q_1, q_2 : X \times \mathbb{R}^2 \to X \times \mathbb{R}$ are given by $\mu(x, t_1, t_2) = (x, t_1 + t_2)$, $q_1(x, t_1, t_2) = (x, t_1)$ and $q_2(x, t_1, t_2) = (x, t_2)$. Via the natural functor above it corresponds to the convolution functor $\ast$ for enhanced ind-sheaves.

For a locally closed subset $Z \subseteq X$, we will write $\mathcal{F}_Z := \mathcal{F}_{Z \times \mathbb{R}}$.

2.2. **Exponential enhanced (ind-)sheaves.** We recall here the definition of enhanced exponentials as introduced in [6].

Let $U \subseteq X$ be an open subset and let $\varphi, \varphi^-, \varphi^+ : U \to \mathbb{R}$ be continuous functions. Let moreover $Z \subseteq U$ be locally closed with $\varphi^-(x) \leq \varphi^+(x)$ for any $x \in Z$.

We consider the enhanced sheaves
\[ E_{Z|X}^\varphi := \pi^{-1}k_Z \otimes k_{\{ t \geq 0 \}} \in D^b(k_X \times \mathbb{R}), \]
\[ E_{Z|X}^{\varphi, \varphi^+} := \pi^{-1}k_Z \otimes k_{\{ -\varphi^+ \leq t < \varphi^- \}} \in D^b(k_X \times \mathbb{R}), \]
where we write for short \( \{ t + \varphi \geq 0 \} := \{(x, t) \in X \times \mathbb{R} \mid x \in U, t + \varphi(x) \geq 0 \} \), and similarly \( \{ -\varphi^+ \leq t < -\varphi^- \} := \{(x, t) \in X \times \mathbb{R} \mid x \in U, -\varphi^+(x) \leq t < -\varphi^-(x) \} \).

Furthermore, we consider the enhanced ind-sheaves
\[
E_{Z|X}^\varphi := k \otimes E_{Z|X} \subset E^b(\mathbb{A}_X),
\]
\[
E_{Z|X}^{\varphi^+\varphi^-} := k \otimes E_{Z|X}^{\varphi^+\varphi^-} \subset E^b(\mathbb{A}_X).
\]
The following lemma is an easy observation.

**Lemma 2.2.** If \( U \subseteq X \) is open, \( \varphi, \psi \colon U \to \mathbb{R} \) are continuous functions, and \( Z \subseteq U \) is locally closed such that \( \varphi \) is bounded on \( Z \), then there is a canonical isomorphism
\[
E_{Z|X}^\varphi \simeq E_{Z|X}^\psi.
\]

It is a fundamental observation (cf. [5, Corollary 9.4.12]) that \( \text{Sol}^E_X(E_{U|X}^\varphi) \simeq E_{U|X}^{\text{Re} \varphi} \), where \( E_{U|X}^\varphi \) is the exponential D-module for some meromorphic function \( \varphi \in O_X(\ast D) \) with poles on a closed hypersurface \( D \subset X \) and \( U = X \setminus D \).

3. **Stokes phenomena for enhanced solutions**

In dimension one, the Stokes phenomenon describes the fact that around an irregular singularity formal solutions are not necessarily convergent, but admit asymptotic expansions on sufficiently small sectors. In the language of D-modules, this is known as the theorem of Hukuhara–Turrittin, stating that the formal Levelt–Turrittin decomposition lifts to a local analytic decomposition on the real blow-up space (cf. [23]). We now explain how this is expressed in terms of enhanced ind-sheaves.

Let \( X = \mathbb{C} \) and let \( \mathcal{M} \in \text{Mod}_{\text{hol}}(\mathcal{D}_X) \) be a meromorphic connection with pole at 0, i.e. \( \mathcal{M}(\ast 0) \simeq \mathcal{M} \) and \( \text{SingSupp}(\mathcal{M}) = \{0\} \). Assume \( \mathcal{M} \) has an (unramified) Levelt–Turrittin decomposition at 0, i.e.
\[
\mathcal{M}_0 := \bigoplus_{i \in I} (\mathcal{E}_{U|X}^{\varphi_i} \otimes \mathcal{D} \mathcal{R}_i)_{0}
\]
for some finite index set \( I \), meromorphic functions \( \varphi_i \in O_X(\ast 0) \) and regular holonomic \( \mathcal{D}_X \)-modules \( \mathcal{R}_i \). Here, \( \mathcal{M}_0 := \widehat{O}_{X,0} \otimes_{O_{X,0}} \mathcal{M}_0 \) is the formal completion of the stalk.

The following result has been stated in [5, §9.8]. It is also given as a corollary of a more general result in [13, Corollary 3.7]. We give a direct proof in the unramified case.

**Proposition 3.1.** If \( \mathcal{M} \) has a Levelt–Turrittin decomposition at 0, then for any direction \( \theta \in \mathbb{R}/2\pi \mathbb{Z} \), there exist constants \( \varepsilon, R \in \mathbb{R}_{>0} \), determining an open sector \( S_\theta = \{ z \in X \mid 0 < |z| < R, \arg z \in (\theta - \varepsilon, \theta + \varepsilon) \} \), such that we have an isomorphism in \( E^b(\mathbb{A}_X) \)
\[
\pi^{-1}k_{S_\theta} \otimes \text{Sol}^E_X(\mathcal{M}) \simeq \pi^{-1}k_{S_\theta} \otimes \bigoplus_{i \in I} (\mathcal{E}_{U|X}^{\text{Re} \varphi_i} )^{\mathcal{R}_i}.
\]

We first establish the following lemma, which is the crucial step in proving the proposition. We denote by \( \widetilde{\mathcal{X}} \colon \tilde{X} \to X \) the real blow-up of \( X \) at 0 and refer to [5, §7.3 and §9.2] for details and notation regarding D-modules and enhanced De Rham functors on blow-up spaces.

**Lemma 3.2.** Let \( V \subseteq \tilde{X} \) be open and \( N \in D^{\mathcal{A}}(\mathcal{D}_{\tilde{X}}) \). Then there is an isomorphism in \( E^b(\mathbb{A}_{\tilde{X}}) \)
\[
\pi^{-1}k_V \otimes D\mathcal{R}^E_{\tilde{X}}(N) \simeq \pi^{-1}k_V \otimes D\mathcal{R}^E_{\tilde{X}}(N \otimes k^\varphi).
\]
Proof. We will use the notation from [18] here to emphasize the difference between the two functors $\iota_X$ and $\beta_X$ from sheaves to ind-sheaves. (Note that $\beta_X$ is often suppressed in the notational conventions of [5].)

By [18, Lemma 3.3.3] and [18, Proposition 4.2.14], respectively, we have

$$
\iota_X k_V \simeq \lim_{\to} k_{V \cap U} \quad \text{and} \quad \beta_X k_{\mathcal{V}} \simeq \lim_{\to} k_{U \cap \mathcal{V}}
$$

and therefore

$$
\beta_X k_{\mathcal{V}} \otimes \iota_X k_V \simeq \lim_{\to} k_{V \cap U \cap U'} \simeq \iota_X k_V,
$$

since $U \cap U'$ ranges through the family of all relatively compact open subsets of $\tilde{X}$ as $U$ and $U'$ do. This now enables us to use [18, Theorem 5.4.19] and obtain

$$
\pi^{-1}\kappa \otimes DR^E_X(\mathcal{N}) \simeq (\Omega_X^E \otimes_{\beta \pi^{-1}D_X} \beta \pi^{-1}\mathcal{N}) \otimes \iota_X \pi^{-1}\kappa_V
$$

\begin{align*}
&\simeq (\Omega_X^E \otimes_{\beta \pi^{-1}D_X} \beta \pi^{-1}\mathcal{N}) \otimes (\beta \pi^{-1}\kappa_{\mathcal{V}} \otimes \iota_X \pi^{-1}\kappa_V) \\
&\simeq (\Omega_X^E \otimes_{\beta \pi^{-1}D_X} \beta \pi^{-1}\mathcal{N} \otimes \kappa_{\mathcal{V}}) \otimes \iota_X \pi^{-1}\kappa_V \\
&\simeq \pi^{-1}\kappa \otimes DR^E_X(\mathcal{N} \otimes \kappa_{\mathcal{V}}).
\end{align*}

\[ \square \]

Proof of Proposition 3.1. Still using the notation of [5, §7.3 and §9.2] and in particular [5, Corollary 9.2.3], one can compute

\begin{align*}
\pi^{-1}\kappa_{S_\#} \otimes DR^E_X(\mathcal{M}) &\simeq \mathbb{E}!!(\pi^{-1}\kappa_{\omega^{-1}(S_\#)} \otimes \mathcal{R}^E_X(\mathcal{M}^A)) \\
&\simeq \mathbb{E}!!(\pi^{-1}\kappa_{\omega^{-1}(S_\#)} \otimes DR^E_X(\mathcal{M}^A \otimes k_{\omega^{-1}(S_\#)})) \\
&\simeq \mathbb{E}!!(\pi^{-1}\kappa_{\omega^{-1}(S_\#)} \otimes DR^E_X(\mathcal{M}^A \otimes \bigoplus_{i \in I} (\mathcal{E}_{U_i}|_X \mathcal{A})^A \otimes k_{\omega^{-1}(S_\#)})) \\
&\simeq \pi^{-1}\kappa_{S_\#} \otimes \bigoplus_{i \in I} (DR^E_X(\mathcal{E}_{U_i}|_X \mathcal{A}))^A.
\end{align*}

Here (⋆) follows from Lemma 3.2 and (▲) follows from the classical Hukuhara–Turrittin theorem if $\varepsilon$ and $R$ are small enough.

The statement about the solution functor (instead of the De Rham functor) is easily deduced by duality. \[ \square \]

The Stokes phenomenon arises through the fact that the isomorphism from Proposition 3.1 depends on $\theta$. Note that, in contrast to common formulations of the Hukuhara–Turrittin theorem (cf. e.g. [23, Théorème (1.4)]), the statement of Proposition 3.1 does not involve blow-ups.

4. D-modules of pure Gaussian type

Let $\mathbb{P} = \mathbb{P}^1(\mathbb{C})$ be the analytic complex projective line, denote by $\mathbb{C} = \mathbb{P} \setminus \{\infty\}$ the affine chart with local coordinate $z$ at 0 and by $j : \mathbb{C} \hookrightarrow \mathbb{P}$ its embedding.

Definition 4.1. Let $C \subset \mathbb{C}^*$ be a finite (non-empty) subset. A holonomic $D_\mathbb{D}$-module $\mathcal{M}$ is said to be of pure Gaussian type $C$ if the following conditions hold:

(a) $\mathcal{M} \simeq M(\infty)$ (as $D_\mathbb{D}$-modules).

(b) $\text{SingSupp}(\mathcal{M}) = \{\infty\}$.

(c) There exist regular holonomic $D_\mathbb{D}$-modules $\mathcal{R}_c$ such that $\mathcal{M}$ has a Levelt–Turrittin decomposition at $\infty$ of the form

\begin{align*}
\mathcal{M}|_{\infty} &\simeq \bigoplus_{c \in C} \left( \mathcal{E}_{C^0}(-z^2) \otimes D \mathcal{R}_c \right)|_{\infty}.
\end{align*}
In other words, $\mathcal{M}$ is a meromorphic connection on $\mathbb{P}$ with a pole at $\infty$ and an
(unramified) Levelt–Turrittin decomposition at $\infty$ with exponential factors $-\frac{t}{2}z^2$.
(Note that polynomial functions in $z$ extend to meromorphic functions on $\mathbb{P}$.)

The rank of $\mathcal{R}_c$ will be denoted by $r_c$ and the family of these ranks will be
denoted by $\mathbf{r} := (r_c)_{c \in C}$.

Some properties of the enhanced solutions of such D-modules of pure Gaussian
type are collected in the following lemma.

**Lemma 4.2.** Let $\mathcal{M} \in \text{Mod}_{hol}(\mathcal{D}_\mathbb{P})$ be of pure Gaussian type $C$. Then:

(i) $\pi^{-1}k_C \otimes \text{Sol}_E^E(\mathcal{M}) \simeq \text{Sol}_E^E(\mathcal{M})$.

(ii) For any direction $\theta \in \mathbb{R}/2\pi\mathbb{Z}$, there exists a small sector $S_\theta$ at $\infty$ (with
central direction $\theta$) such that

$$\pi^{-1}k_{S_\theta} \otimes \text{Sol}_E^E(\mathcal{M}) \simeq \pi^{-1}k_{S_\theta} \otimes \bigoplus_{c \in C} \left(\mathbb{P}_{C \cup \mathbb{P}}^{-\Re \frac{t}{2}z^2}\right)^{r_c}.$$ 

(iii) For any open $B \subset \mathbb{C}$ such that $\overline{B} \subset \mathbb{C}$ (where $\overline{B}$ denotes the closure of $B$
in $\mathbb{P}$), one has

$$\pi^{-1}k_B \otimes \text{Sol}_E^E(\mathcal{M}) \simeq \pi^{-1}k_B \otimes (k_E^B)^\gamma.$$ 

**Proof.** The statements (i) and (ii) directly follow from Proposition [5, Corollary
9.4.11] and Proposition 3.1, respectively.

The third assertion is proved using [7, Lemma 2.7.6] and the fact that $\mathcal{M}$ is
non-singular outside $\infty$. □

On the other hand, since $\mathbb{P}$ is compact, we have the following statement about
the global structure of $\text{Sol}_E^E(\mathcal{M})$. It is a direct application of [4, Lemma 2.5.1] (cf.
also [5, Definition 4.9.2 and Theorem 9.3.2]).

**Lemma 4.3.** Let $\mathcal{M} \in \text{Mod}_{hol}(\mathcal{D}_\mathbb{P})$ be of pure Gaussian type. Denote by $\tilde{j}: \mathbb{C} \times \mathbb{R} \hookrightarrow
\mathbb{P} \times \mathbb{R}$ the embedding. There exists $\mathcal{F} \in \mathcal{D}^0(k_{\mathbb{C} \times \mathbb{R}})$ such that

$$\text{Sol}_E^E(\mathcal{M}) \simeq k_E^\mathbb{P} \otimes \tilde{j}_*\mathcal{F}.$$ 

Thus, the enhanced solutions of a D-module of pure Gaussian type are deter-
mined by a globally defined enhanced sheaf which restricts to zero on the singularity.
The aim of the next sections will be to describe such an enhanced sheaf, and this
goal is achieved in Theorem 7.2.

5. Stokes directions and width of sectors

Let $C \subset \mathbb{C}^x$ be a finite subset and let $\mathcal{M} \in \text{Mod}_{hol}(\mathcal{D}_\mathbb{P})$ be of pure Gaussian
type $C$.

In this section, we extend the decomposition from Lemma 4.2 (ii) to a decom-
position of $\text{Sol}_E^E(\mathcal{M})$ on sectors around $\infty$ that intersect at most one Stokes line for
each pair $c, d \in C$. That is, we give a more precise description of how “small” the
sectors’ width has to be.

As we have seen, the enhanced solutions of $\mathcal{M}$ are not interesting at the singularity
but in close neighbourhoods, which are then subsets of $\mathcal{C} = \mathbb{P} \setminus \{\infty\}$. Therefore, we
will set up everything in the complex plane.

**Lemma-Definition 5.1.** Let $c, d \in C, c \neq d$. The set

$$\text{St}_{c, d} = \left\{ z \in \mathbb{C} \mid -\Re \frac{c}{2} z^2 = -\Re \frac{d}{2} z^2 \right\}$$

is the union of four closed half-lines with initial point 0, perpendicular to one
another. These half-lines are called the *Stokes lines* of the pair $c, d$. Their directions
(i.e. the arguments of the points on the Stokes lines) are called the \textit{Stokes directions} (of the pair $c, d$).

We say that a direction is \textit{generic} if it is not a Stokes direction for any pair $c, d \in C$.

**Definition 5.2.** A subset $S \subset \mathbb{P}$ is said to be

$\blacktriangleright$ an open sector at $\infty$ if
\[
S = \{ z \in \mathbb{C} \mid R < |z| < \infty, \arg z \in (\theta - \varepsilon, \theta + \varepsilon) \} \subseteq \mathbb{C} \subset \mathbb{P}
\]
for some $R \in \mathbb{R}_{>0}$, $\varepsilon \in \mathbb{R}_{>0}$ and $\theta \in \mathbb{R}/2\pi\mathbb{Z}$.

$\blacktriangleright$ a closed sector at $\infty$ if
\[
S = \{ z \in \mathbb{C} \mid R \leq |z| < \infty, \arg z \in [\theta - \varepsilon, \theta + \varepsilon] \text{ for } |z| \neq 0 \} \subseteq \mathbb{C} \subset \mathbb{P}
\]
for some $R, \varepsilon \in \mathbb{R}_{>0}$ and $\theta \in \mathbb{R}/2\pi\mathbb{Z}$.

(For $\varepsilon = 0$, this includes the case of half-lines.)

The \textit{radius} of such a sector is the number $\frac{1}{R} \in (0, +\infty]$, and its \textit{width} is the number $\min(2\varepsilon, 2\pi) \in [0, 2\pi]$. Note that a closed sector at $\infty$ is topologically closed in $\mathbb{C}$ (but not in $\mathbb{P}$).

We will say that an (open or closed) sector at $\infty$ \textit{contains} a direction $\theta \in \mathbb{R}/2\pi\mathbb{Z}$ if its intersection with the open half-line $\{ z \in \mathbb{C} \setminus \{0\} \mid \arg z = \theta \}$ is non-empty.

On sectors containing no Stokes direction, we can introduce an order on $C$.

**Notation 5.3.** Let $S$ be a sector at $\infty$ and let $c, d \in C$. We write
\[
c <_S d \quad \iff \quad \text{Re} \frac{c}{2} z^2 < \text{Re} \frac{d}{2} z^2 \text{ for all } z \in S \setminus \{0\}.
\]
For $\theta \in \mathbb{R}/2\pi\mathbb{Z}$, we write
\[
c <_{\theta} d \quad \iff \quad \text{Re} \frac{c}{2} z^2 < \text{Re} \frac{d}{2} z^2 \text{ for all } z \in \mathbb{C} \text{ with } z \neq 0 \text{ and } \arg z = \theta.
\]

We now describe morphisms between the exponential enhanced ind-sheaves in the local decomposition of $\text{Sol}^\mathbb{P}(M)$ from Lemma 4.2 (ii). This lemma is analogous to (and inspired by) \cite[Lemma 9.8.1]{5}, \cite[Lemma 5.1.2]{4} and \cite[Lemma 4.3.1]{6}.

**Lemma 5.4.** Consider the meromorphic functions $\varphi_1, \varphi_2$ on $\mathbb{P}$ given by $\varphi_1(z) = -\frac{c}{2} z^2$ and $\varphi_2(z) = -\frac{d}{2} z^2$ for $c, d \in \mathbb{C}^\times$, $c \neq d$. Let $S \subset \mathbb{P}$ be a sector (open or closed) at $\infty$. Then we have
\[
\text{Hom}_{\mathbb{P}}(\mathbb{P}^\mathbb{C}(\mathbb{k})_{\mathbb{P}}(E^\text{Re}\varphi_1), E^\text{Re}\varphi_2) \simeq \text{Hom}_{\mathbb{D}^\mathbb{P}}(\mathbb{k}^\mathbb{C}(\mathbb{E}^\text{Re}\varphi_1), \mathbb{E}^\text{Re}\varphi_2)
\]
\[
\simeq \begin{cases} 
\mathbb{k} & \text{if } \text{Re } \varphi_1 \geq \text{Re } \varphi_2 \text{ on } S \\
0 & \text{otherwise}
\end{cases}
\]

Here, the first isomorphism (from right to left) is induced by the functor $\mathbb{k}^\mathbb{P} \otimes \mathbb{j}_!(\bullet)$ and the second isomorphism is the natural identification of a morphism with multiplication by a complex number.

**Proof.** Using \cite[Proposition 4.7.9, Lemma 4.4.6 and Corollary 3.2.10]{5}, we get
\[
\text{Hom}_{\mathbb{P}}(\mathbb{P}^\mathbb{C}(\mathbb{k})_{\mathbb{P}}(E^\text{Re}\varphi_1), E^\text{Re}\varphi_2)
\]
\[
\simeq \lim_{\text{direct limit}} \text{Hom}_{\mathbb{D}^\mathbb{P}}(\mathbb{k}_{\mathbb{P}}^\mathbb{C}(\mathbb{E}^\text{Re}\varphi_1), \pi^{-1} \mathbb{k}^\mathbb{C}(\mathbb{E}^\text{Re}\varphi_1_{\mathbb{P}}) \otimes \mathbb{k}^\mathbb{D}(\mathbb{E}^\text{Re}\varphi_2_{\mathbb{P}}))
\]
\[
\text{If } \text{Re } \varphi_1 \geq \text{Re } \varphi_2 \text{ at each point of } S, \text{ these Hom-spaces are isomorphic to } \mathbb{k} \text{ for any } a \in \mathbb{R}_{\geq 0} \text{ (and hence also their direct limit). If there are points in } S \text{ where } \text{Re } \varphi_1 \prec \text{Re } \varphi_2, \text{ it is not difficult to see that } \text{Re } (\varphi_2 - \varphi_1) \text{ is not bounded from above on } S. \text{ It follows that the Hom-space is trivial for any } a \in \mathbb{R}_{\geq 0} \text{ (and hence also the direct limit).} \]
The following result shows how automorphisms of the Gaussian model on sectors can be interpreted as block matrices.

**Proposition 5.5.** Let $S \subset \mathbb{P}$ be a sector at $\infty$ and assume that $S$ is not a half-line whose direction is a Stokes direction for some $c, d \in C$. If we choose a numbering of the elements of $C$, i.e., $C = \{c(1), \ldots, c(n)\}$, we have

$$
\text{Aut}_{\mathbb{E}^{\infty}}(k) \left( \pi^{-1}k_S \otimes \bigoplus_{c \in C} \left( E_{\mathbb{C}[\mathbb{P}]}^{-\Re \frac{c}{2} z^2} \right)_{c} \right)
\simeq
\text{Aut}_{\mathbb{P}}(k_{x,a}) \left( \pi^{-1}k_S \otimes \bigoplus_{c \in C} \left( E_{\mathbb{C}[\mathbb{P}]}^{-\Re \frac{c}{2} z^2} \right)_{c} \right)
\simeq
\{ A = (A_{jk})_{j,k=1}^{n} \in k^{r \times r} \mid A_{jk} \in k^{r(c_{j}) \times r(c_{k})}, A_{jj} \text{ is invertible for any } j, \ A_{jk} = 0 \text{ if } \Re \frac{c_{j}}{2} z^2 < \Re \frac{c_{k}}{2} z^2 \text{ for some } z \in S \},
$$

In particular, if $c(1) < s c(2) < \ldots < s c(n)$, then the right hand side consists precisely of the invertible, lower block-triangular matrices with block sizes given by the numbers $r_{c(i)}$.

**Proposition 5.6.** Let $M$ be of pure Gaussian type $C$. For any (open or closed) sector $S$ at $\infty$ of sufficiently small radius intersecting at most one Stokes line for each pair $c, d \in C$, there is an isomorphism

$$
\pi^{-1}k_S \otimes \text{Sol}^{E}_{\mathbb{P}}(M) \simeq \pi^{-1}k_S \otimes \bigoplus_{c \in C} \left( E_{\mathbb{C}[\mathbb{P}]}^{-\Re \frac{c}{2} z^2} \right)_{c}.
$$

**Proof.** Let us write for short $H := \text{Sol}^{E}_{\mathbb{P}}(M)$ and $M := \bigoplus_{c \in C} \left( E_{\mathbb{C}[\mathbb{P}]}^{-\Re \frac{c}{2} z^2} \right)_{c}$.

The following argument enables us to recursively obtain the desired isomorphism by gluing those on small sectors (cf. Lemma 4.2 (ii)): Assume that we are given two open sectors $S_1, S_2 \subset S$ at $\infty$ with isomorphisms

$$
\alpha_j : \pi^{-1}k_{S_j} \otimes H \xrightarrow{\sim} \pi^{-1}k_{S_j} \otimes M
$$

for $j \in \{1, 2\}$ and assume moreover that $S_1 \cap S_2 \not= \emptyset$, that we have $S_1 \not\subseteq S_2$ and $S_2 \not\subseteq S_1$, that $S_2$ contains at most one Stokes direction and no Stokes direction for the same pair $c, d$ is contained in $S_1$.

Choose a numbering of the elements of $C$ such that $c(1) < S_1 \cap S_2, c(2) < S_1 \cap S_2 \ldots < S_1 \cap S_2, c(n)$. The isomorphisms $\alpha_j$ induce two isomorphisms

$$
\tilde{\alpha}_j : \pi^{-1}k_{S_1 \cap S_2} \otimes H \xrightarrow{\sim} \pi^{-1}k_{S_1 \cap S_2} \otimes M.
$$

By Proposition 5.5, the transition isomorphism $\tilde{\alpha}_2 \circ \tilde{\alpha}_1^{-1}$ can be represented by a lower block-triangular matrix $A = (A_{jk})$. One can decompose $A = A' A''$ as follows:

If $S_2$ contains a Stokes direction for the pair $c(j), c(k)$ ($l < l'$), let $A'$ be the block matrix (with the same block structure as $A$) having identity matrices on the diagonal and $A'_{ll'} = A_{ll'}^{-1} A_{ll'}$. All the other blocks of $A'$ are zero. If $S_2$ contains no Stokes direction, let $A' := \mathbb{1}$. Set $A'' := AA'^{-1}$.

It is not difficult to see that, in either of the two cases, the matrix $A'$ represents an automorphism of $\pi^{-1}k_{S_2} \otimes M$ and the matrix $A''$ represents an automorphism of $\pi^{-1}k_{S_1 \cap S_2} \otimes M$ (by the correspondence of Proposition 5.5).

Consider the diagram

$$
\begin{array}{ccc}
\pi^{-1}k_{S_1 \cap S_2} \otimes H & \longrightarrow & \pi^{-1}k_{S_1} \otimes H \oplus \pi^{-1}k_{S_2} \otimes H \\
\downarrow A'_{01} = A''^{-1} A_{01} & & \downarrow A''^{-1} A_{01} \\
\pi^{-1}k_{S_1 \cap S_2} \otimes M & \longrightarrow & \pi^{-1}k_{S_1} \otimes M \oplus \pi^{-1}k_{S_2} \otimes M
\end{array}
$$

Consider the diagram

$$
\begin{array}{ccc}
\pi^{-1}k_{S_1 \cup S_2} \otimes H & \longrightarrow & \pi^{-1}k_{S_1} \otimes H \oplus \pi^{-1}k_{S_2} \otimes H \\
\downarrow A'_{01} = A''^{-1} A_{01} & & \downarrow A''^{-1} A_{01} \\
\pi^{-1}k_{S_1 \cup S_2} \otimes M & \longrightarrow & \pi^{-1}k_{S_1} \otimes M \oplus \pi^{-1}k_{S_2} \otimes M
\end{array}
$$
where the rows are distinguished triangles. By our construction of $A'$ and $A''$, the square on the left of the diagram commutes and the vertical arrows are isomorphisms. Therefore, there exists an isomorphism $\tilde{\alpha}$ completing the diagram to an isomorphism of distinguished triangles.

6. Stokes multipliers and monodromy

Let $C \subset C^x$ be a finite subset and $\mathcal{M} \in \text{Mod}_{\text{hol}}(D_F)$ be of pure Gaussian type $C$. As we have seen, we generally need four sectors to cover a neighbourhood of $\infty$ by sectors on which we have isomorphisms as in Proposition 5.6.

Fix a generic direction $\theta_0$ and choose a numbering of the elements of $C$ such that $c_{(1)} \prec_\theta c_{(2)} \prec_\theta \ldots \prec_\theta c_{(n)}$. Clearly, $\theta_0 + k\frac{\pi}{2}$ (for $k \in \{1, 2, 3\}$) are also generic. By Proposition 5.6, there exists $R \in \mathbb{R}_{>0}$ such that on the closed sectors $\Sigma_k := \{ z \in \mathbb{C} \mid |z| \geq R, \arg z \in [\theta_0 + (k-1)\frac{\pi}{2}, \theta_0 + k\frac{\pi}{2}] \}$, $k \in \mathbb{Z}/4\mathbb{Z}$, we have isomorphisms

$$\alpha_k: \pi^{-1}k_{\Sigma_k} \otimes \text{Sol}_F^E(\mathcal{M}) \overset{\sim}{\to} \pi^{-1}k_{\Sigma_k} \otimes \bigoplus_{c \in C} (\mathbb{E}_{\mathbb{C}[z]}^{\Re z^2})^r_c.$$  

(Note that these isomorphisms are not unique, so this step involves a choice.)

On the half-line $\Sigma_{k, k+1} := \Sigma_k \cap \Sigma_{k+1}$, $\alpha_k$ and $\alpha_{k+1}$ induce isomorphisms (by abuse of notation, we denote them by the same symbols)

$$\alpha_k, \alpha_{k+1}: \pi^{-1}k_{\Sigma_{k, k+1}} \otimes \text{Sol}_F^E(\mathcal{M}) \overset{\sim}{\to} \pi^{-1}k_{\Sigma_{k, k+1}} \otimes \bigoplus_{c \in C} (\mathbb{E}_{\mathbb{C}[z]}^{\Re z^2})^r_c$$

and the transition isomorphism

$$\alpha_{k+1} \circ (\alpha_k)^{-1} \in \text{Aut}_{\text{hol}}(\mathcal{M}) \left( \bigoplus_{c \in C} (\mathbb{E}_{\mathbb{C}[z]}^{\Re z^2})^r_c \right)$$

is represented by an invertible, block-triangular matrix $\sigma_k$ (cf. Proposition 5.5).

**Definition 6.1.** The matrices $\sigma_k$ are called Stokes multipliers (or Stokes matrices) of $\mathcal{M}$.

(Remember that these notions require fixing a generic direction.)

**Proposition 6.2.** The (counterclockwise) product of the Stokes multipliers for a $D$-module of pure Gaussian type is the identity, i.e. $\sigma_4 \sigma_3 \sigma_2 \sigma_1 = 1$.

**Proof.** Choose $\rho > R$ and set $B := \{ z \in \mathbb{C} \mid |z| \leq \rho \}$. There is a canonical isomorphism (see Lemma 2.2)

$$\tau: \pi^{-1}k_B \otimes \bigoplus_{c \in C} (\mathbb{E}_{\mathbb{C}[z]}^{\Re z^2})^r_c \overset{\sim}{\to} \pi^{-1}(k_B^E)^r.$$ 

We set $D_j := \Sigma_j \cap B$, $D_{j,k} := D_j \cap D_k$ and $D := \bigcup_{j \in \mathbb{Z}/4\mathbb{Z}} D_j$. Moreover, we write for short $H := \text{Sol}_F^E(\mathcal{M})$ and $M := \bigoplus_{c \in C} (\mathbb{E}_{\mathbb{C}[z]}^{\Re z^2})^r_c$.

For each $k \in \mathbb{Z}/4\mathbb{Z}$, one has a chain of isomorphisms

$$\pi^{-1}k_{D_k} \otimes H \overset{\text{Stokes}}{\to} \pi^{-1}k_{D_k} \otimes (k_B^E)^r \simeq \pi^{-1}(k_{D_k})^r \otimes k_{E}^r.$$ 

The transition isomorphism on $D_{k,k+1}$ is given by the Stokes multiplier $\sigma_k$ (which can be viewed as an automorphism of the sheaf $(k_{D_k})^r$). Therefore, $\pi^{-1}k_D \otimes H \simeq \pi^{-1}(G)^r \otimes k_{E}^r$, where $G$ is a local system of rank $r$ on $D$ (extended by zero to $\mathbb{C}$) with monodromy given by $\sigma_4 \sigma_3 \sigma_2 \sigma_1$.

On the other hand, by Lemma 4.2, we have an isomorphism $\pi^{-1}k_D \otimes H \simeq \pi^{-1}(k_D^E)^r \otimes k_{E}^r$. Since the functor $\pi^{-1}(\bullet)^r \otimes k_{E}^r$ is fully faithful (see [5, Proposition 4.7.15]), $G$ is isomorphic to the constant local system and hence that their monodromies are equal. \qed
7. A sheaf describing enhanced solutions

The question studied in this section is how large we can choose the radius of the four sectors. It will turn out that the absence of singularities outside the point \( \infty \) enables us to increase the sectors’ radii as far as we like. Hence, we can actually use sectors of infinite radius.

**Lemma-Definition 7.1.** Consider the following set of data:
- a finite subset \( C \subset \mathbb{C}^\times \),
- a generic direction \( \theta_0 \) with respect to \( C \) (which defines an order on \( C \)),
- a family \( \pi = (r_c)_{c \in C} \) of natural numbers \( r_c \in \mathbb{Z}_{>0} \),
- a family \( \sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \) of \((r \times r)\)-matrices (where \( r := \sum_{c \in C} r_c \)) such that \( \sigma_1 \) and \( \sigma_3 \) (resp. \( \sigma_2 \) and \( \sigma_4 \)) are upper (resp. lower) block-triangular, with the block structure given by the numbers \( r_c \) (ordered according to \( \theta_0 \)).

Define the sectors \( S_k := \{ z \in \mathbb{C} \mid \arg z \in [\theta_0 + (k-1)\frac{\pi}{2}, \theta_0 + k\frac{\pi}{2}] \} \) if \( z \neq 0 \), which are closed sectors of infinite radius at \( \infty \), but can also be considered as closed sectors (including the vertex) at \( 0 \). As usual, we set \( S_k \cap S_{k+1} \).

Then there exists an enhanced sheaf \( \mathcal{F}_C^{\sigma, \theta_0} \in \text{Mod}(\mathbb{C} \times \mathbb{C}) \) (or \( \mathcal{F}_C \) for short) on \( \mathbb{C} \) together with isomorphisms
\[
\alpha_k : (\mathcal{F}_C)_S \xrightarrow{\sim} \pi^{-1} k_{S_k} \otimes \bigoplus_{c \in C} \left( E_{C|C}^{\frac{\pi}{c}} z^c \right)^{r_c}
\]
such that the transition isomorphisms \( \alpha_{k+1} \circ \alpha_k^{-1} \), automorphisms of \( \pi^{-1} k_{S_{k+1}} \otimes \bigoplus_{c \in C} \left( E_{C|C}^{\frac{\pi}{c}} z^c \right)^{r_c} \), are given by the matrices \( \sigma_k \). Moreover, the sheaf \( \mathcal{F}_C \) thus defined is unique up to one of these isomorphisms.

If an enhanced sheaf on \( \mathbb{C} \) is isomorphic to one of this form, we will call it an *enhanced sheaf of pure Gaussian type*.

The following theorem shows that this finally is an enhanced sheaf (on \( \mathbb{C} \)) describing globally (on \( \mathbb{P} \)) the enhanced solutions of \( \mathcal{M} \). (In contrast to the formulation of Lemma 4.3, we do not write extension by zero.)

**Theorem 7.2.** Let \( \mathcal{M} \) be a \( \text{D-mod} \) of pure Gaussian type \( C \), \( \pi \) the family of ranks from its Levelt–Turrittin decomposition, \( \theta_0 \) a generic direction and recall the Stokes multipliers \( \sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \) from the previous section. Then there is an isomorphism
\[
\text{Sol}^E(\mathcal{M}) \simeq k^E \otimes \mathcal{F}_C^{\sigma, \theta_0, \pi}.
\]

In the proof of this theorem, let us write \( \mathcal{F} := \mathcal{F}_C^{\sigma, \theta_0, \pi} \). We make use of the following lemma, which gives an alternative description of \( \text{Sol}^E(\mathcal{M}) \) away from the singularity.

**Lemma 7.3.** Let \( B \subset \mathbb{C} \) be a closed ball of finite radius around \( 0 \). Then there is an isomorphism
\[
\pi^{-1} k_B \otimes \text{Sol}^E(\mathcal{M}) \simeq \pi^{-1} k_B \otimes k^E \otimes \mathcal{F}.
\]

**Proof.** We abbreviate \( B_k := B \cap S_k \) and \( B_{k+1} := B \cap S_{k+1} \) for \( k \in \mathbb{Z}/4\mathbb{Z} \), as well as \( H := \text{Sol}^E(\mathcal{M}) \) and \( M := \bigoplus_{c \in C} \left( E_{C|C}^{\frac{\pi}{c}} z^c \right)^{r_c} \).

For any \( k \in \mathbb{Z}/4\mathbb{Z} \), we choose the following isomorphism:
\[
\pi^{-1} k_{B_k} \otimes H \xrightarrow{\vartheta} \pi^{-1} k_{B_k} \otimes (k^E)^r \xrightarrow{\sigma_k} \pi^{-1} k_{B_k} \otimes (k^E)^r \xrightarrow{\pi} \pi^{-1} k_{B_k} \otimes M.
\]

Here, \( \vartheta \) is the isomorphism from Lemma 4.2, \( \tau \) is the canonical isomorphism (see Lemma 2.2), and \( s_1 = 1, s_2 = s_4 = \sigma_2 \sigma_1, s_3 = \sigma_3 \sigma_2 \sigma_1 \). With this choice, the transition maps are given by the \( \sigma_k \). (Note that at this point we use that the monodromy is trivial). Hence, one can construct the desired isomorphism. \( \square \)
Proof of Theorem 7.2. Recall the notations $R$ and $\Sigma_k$ from Section 6. We abbreviate $H := \text{Sol}_F^E(M)$ and $M := \bigoplus_{z \in G} (\mathbb{C} \rightarrow \mathbb{C}^{\mathbb{Z}_2})^r$. Moreover, we choose $\rho > R$ and set $B := \{z \in \mathbb{C} \mid |z| \leq \rho\}$, $\Sigma := \bigcup_{k \in \mathbb{Z}/4\mathbb{Z}} \Sigma_k$, $D := \Sigma \cap B$ and $D_k := D \cap \Sigma_k$ (similarly, $D_{k,k+1} := D \cap \Sigma_{k,k+1}$).

Firstly, one uses (6.1) to obtain an isomorphism

$$\pi^{-1}k_E \otimes H \simeq \pi^{-1}k_{\Sigma} \otimes k_F^\mathbb{P} \otimes \mathcal{F}. \tag{7.1}$$

Secondly, we determine an isomorphism

$$\pi^{-1}k_B \otimes H \simeq \pi^{-1}k_B \otimes k_F^\mathbb{P} \otimes \mathcal{F}. \tag{7.2}$$

The existence of such an isomorphism was shown in Lemma 7.3. However, it is neither canonical nor unique, but depends on the choice of a trivialization $\vartheta: \pi^{-1}k_B \otimes H \simeq \pi^{-1}k_B \otimes (k_F^\mathbb{P})^r$. We choose $\vartheta$ in such a way that the composition

$$\vartheta_1 \circ \alpha_1^{-1} : \pi^{-1}k_{D_1} \otimes k_F^\mathbb{P} \otimes M \xrightarrow{\sim} \pi^{-1}k_{D_1} \otimes (k_F^\mathbb{P})^r$$

is the canonical isomorphism. We can then conclude that (7.1) and (7.2) agree on $D$ and the theorem follows. \hfill $\square$

The next lemma shows that we can “deform” the sectors $S_k$ without crossing a Stokes line and describe a Riemann–Hilbert correspondence for systems of pure Gaussian type.

Lemma 7.4. Let $S_k$, $k \in \mathbb{Z}/4\mathbb{Z}$, be four closed sectors of infinite radius at $\infty$. Assume that $S_k$ contains exactly the same Stokes directions as $S_k$. Then Lemma–Definition 7.1 defines the same sheaf $\mathcal{F}_\sigma^\mathbb{P}$ if we replace $S_k$ by $\bar{S}_k$.

8. Stokes data and a Riemann–Hilbert correspondence for systems of pure Gaussian type

We have reduced to a small set of data necessary for determining a D-module of pure Gaussian type. We use this data to establish a Riemann–Hilbert correspondence for D-modules of pure Gaussian type. In this section, we will not expand on the proofs of equivalences of categories, which are mainly straightforward.

We fix a finite subset $C \subset \mathbb{C}^\infty$ as well as a generic direction $\theta_0$ and consider the sectors $S_z = \{z \in \mathbb{C} \mid \arg z \in [\theta_0 + (k - 1)\pi, \theta_0 + k\pi\} \text{ if } z \neq 0\}$. We also fix a positive integer $r_e$ for any $c \in C$.

Let $\text{Mod}^C_{\text{Gauk}}(D_B)$ be the full subcategory of $\text{Mod}_{\text{hol}}(D_B)$ consisting of objects of pure Gaussian type $C$ and with a Levelt–Turrittin decomposition satisfying $rk \mathcal{R}_c = r_e$ for every $c \in C$.

Let $E^C_{\text{Gauk}}(\mathcal{I}_k)$ be the full subcategory of $E^b(\mathcal{I}_k)$ consisting of objects $H$ satisfying $\pi^{-1}k_C \otimes H \simeq H$ and admitting isomorphisms

$$\pi^{-1}k_{S_k} \otimes H \simeq \pi^{-1}k_{S_k} \otimes \bigoplus_{c \in C} (\mathbb{C} \rightarrow \mathbb{C}^{\mathbb{Z}_2})^r$$

for $k \in \mathbb{Z}/4\mathbb{Z}$. (Note that these isomorphisms are not part of the data.)

Proposition 8.1. The functor $\text{Sol}_F^E$ induces an equivalence between $\text{Mod}^C_{\text{Gauk}}(D_B)$ and $E^C_{\text{Gauk}}(\mathcal{I}_k)$.

Essential surjectivity follows quickly from the description of the essential image of $\text{Sol}_F^E$ by T. Moehizuki (see [26, Lemma 9.8]) and the comparison between enhanced exponentials [6, Corollary 5.2.3] (cf. also [26, Lemma 5.15]).

The results of the previous sections enable us to describe the objects of $E^C_{\text{Gauk}}(\mathcal{I}_k)$ in terms of linear algebra data. Choose a numbering of the elements of $C$ such that $c_1 < \theta_0, c_2 < \theta_0 \cdots < \theta_0, c_{(n)}$. We will write $r_j$ instead of $r_{c(j)}$. 

\begin{itemize}
  \item \textbf{Essential surjectivity follows quickly from the description of the essential image of $\text{Sol}_F^E$ by T. Moehizuki (see [26, Lemma 9.8]) and the comparison between enhanced exponentials [6, Corollary 5.2.3] (cf. also [26, Lemma 5.15]).}
  \item The results of the previous sections enable us to describe the objects of $E^C_{\text{Gauk}}(\mathcal{I}_k)$ in terms of linear algebra data. Choose a numbering of the elements of $C$ such that $c_1 < \theta_0, c_2 < \theta_0 \cdots < \theta_0, c_{(n)}$. We will write $r_j$ instead of $r_{c(j)}$.}
\end{itemize}
Definition 8.2. One defines the category \( \mathcal{D}^{C,\theta_0,\pi} \) of Stokes data of pure Gaussian type \((C,\theta_0,(r_c)_{c \in C})\) as follows:

- An object \( \sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \in \text{Ob} \mathcal{D}^{C,\theta_0,\pi} \) is a family of four block matrices with the properties:
  - The block structure is given by the numbers \( r_j \) (\( j \in \{1,\ldots,n\} \)), i.e. the \( j \)th diagonal block has size \( r_j \times r_j \).
  - The matrices \( \sigma_1 \) and \( \sigma_3 \) are upper block-triangular and the matrices \( \sigma_2 \) and \( \sigma_4 \) are lower block-triangular.
  - The matrix \( \sigma_k \) is invertible for any \( k \in \mathbb{Z}/4\mathbb{Z} \). (With the above properties, this is equivalent to saying that the blocks along the diagonal are invertible.)
  - The product of the \( \sigma_k \) is the identity: \( \sigma_4 \sigma_3 \sigma_2 \sigma_1 = 1 \).

- A morphism \( \delta = (\delta_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \in \text{Hom} \mathcal{D}^{C,\theta_0,\pi} \) between two objects \( \sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \) and \( \tilde{\sigma} = (\tilde{\sigma}_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \) is a family of four block matrices with the properties:
  - The block structure is given by the numbers \( r_j \) (\( j \in \{1,\ldots,n\} \)).
  - The matrix \( \delta_k \) is block-diagonal for every \( k \in \mathbb{Z}/4\mathbb{Z} \).
  - For any \( k \in \mathbb{Z}/4\mathbb{Z} \), one has \( \tilde{\sigma}_k \delta_k = \delta_{k+1} \sigma_k \).

Composition of morphisms is given by matrix multiplication.

Remark. Let us give an explanation of how one could think of objects and morphisms in the category of Stokes data \( \mathcal{D}^{C,\theta_0,\pi} \). This also gives an idea for making a link with the description of Stokes data in [30].

An object consists of four matrices which will correspond to the Stokes matrices describing the transition between the four sectors. We can therefore imagine them to be arranged in a “circle”, i.e. a diagram of the form

One can think of the vertices as vector spaces \( k^r = \bigoplus_{j=1}^n k^{r_j} \) which (by the given grading) have two natural filtrations: The filtration \( F_m k^r = \bigoplus_{j=1}^m k^{r_j} \) is respected by the matrices \( \sigma_1 \) and \( \sigma_3 \), whereas the filtration \( F'_m k^r = \bigoplus_{j=n-m+1}^n k^{r_j} \) is respected by the matrices \( \sigma_2 \) and \( \sigma_4 \).

A morphism between two such diagrams can then be visualized as

and the relations required in Definition 8.2 amount to saying that this diagram is commutative. The matrices \( \delta_k \) respect the grading \( k^r = \bigoplus_{j=1}^n k^{r_j} \), i.e. they are compatible with both filtrations considered above.

An intuitive reason why the \( \sigma_k \) are block-triangular, while the \( \delta_k \) need to be block-diagonal is the following: The matrices \( \sigma_k \) are the transition matrices, which means that they describe isomorphisms on the boundaries of the sectors, where
one has a well-defined ordering of the parameters $c_{(j)}$ (cf. Proposition 5.5). In contrast, the $\delta_k$ are meant to describe morphisms on the sectors $S_k$, where no pair of parameters has a global well-defined order. Therefore, $\delta_k$ must be compatible with any order of the $c_{(j)}$.

**Proposition 8.3.** The functor

$$\mathfrak{G} \mathcal{O}^{C,\theta_0,x} \rightarrow E_{\text{Gauß}}^C(Ik_F), \quad \sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \mapsto k_F^+ \otimes F_{\sigma}$$

is an equivalence of categories, where $F_{\sigma}$ is as in Section 7.

**Corollary 8.4.** There is an equivalence of categories $\text{Mod}^{C,\theta_0,x}(\mathcal{D}_\gamma) \xrightarrow{\sim} \mathfrak{G} \mathcal{O}^{C,\theta_0,x}$.

The corresponding functor assigns to a D-module of pure Gaussian type $M$ its Stokes matrices with respect to the generic direction $\theta_0$.

9. **Analytic and Topological Fourier–Laplace Transform**

Classically, for a module $M$ over the Weyl algebra $\mathbb{C}[z][\partial_z]$, the Fourier–Laplace transform $\tilde{M}$ is the $\mathbb{C}[w][\partial_w]$-module defined as follows: As a set, we have $\tilde{M} = M$, and the structure of a $\mathbb{C}[w][\partial_w]$-module is defined by $w \cdot m := \partial_z m$ and $\partial_w m := -z \cdot m$. The corresponding integral transform is given as follows (see [22]).

Consider the projections

$$\mathbb{P}_z \times \mathbb{P}_w \xrightarrow{P_z} \mathbb{P}_z \xrightarrow{P_w} \mathbb{P}_w$$

where $\mathbb{P}_z$ denotes the complex projective line with affine coordinate $z$ in the chart $\mathbb{C}_z \subset \mathbb{P}_z$ at 0, and similarly for $\mathbb{P}_w$.

**Definition 9.1.** Let $M \in \text{D}^b(\mathcal{D}_{\mathbb{P}_z})$. We define the **Fourier–Laplace transform** $^L M$ of $M$ by

$$^L M := \text{D}p_{w*}(\mathcal{E}_{\mathbb{C}_z \times \mathbb{C}_w}[P_z \times \mathbb{P}_w] \otimes \text{D}p_z^*M) \in \text{D}^b(\mathcal{D}_{\mathbb{P}_w}).$$

This defines a functor $^L(\bullet) : \text{D}^b(\mathcal{D}_{\mathbb{P}_z}) \rightarrow \text{D}^b(\mathcal{D}_{\mathbb{P}_w})$.

In the same spirit, one can define a transform for enhanced ind-sheaves (see [21]) and enhanced sheaves. Consider the projections

$$\mathbb{C}_z \times \mathbb{C}_w \times \mathbb{R} \xrightarrow{\bar{p}} \mathbb{C}_z \times \mathbb{R} \xrightarrow{\bar{q}} \mathbb{C}_w \times \mathbb{R}$$

**Definition 9.2.** Let $F \in \text{D}^b(\mathbb{k}_{C_z \times \mathbb{R}})$ be an enhanced sheaf. We define its **enhanced Fourier–Sato transform** $^\mathcal{L} F$ by

$$^\mathcal{L} F := R\bar{q}_!(E_{\mathbb{C}_z \times \mathbb{C}_w}[\mathbb{C}_z \times \mathbb{C}_w] \otimes \bar{p}^{-1} F)[1] \in \text{D}^b(\mathbb{k}_{C_z \times \mathbb{R}}).$$

This defines a functor $^\mathcal{L}(\bullet) : \text{D}^b(\mathbb{k}_{C_z \times \mathbb{R}}) \rightarrow \text{D}^b(\mathbb{k}_{C_z \times \mathbb{R}})$.

An important observation on our way to describing the Fourier–Laplace transform of a D-module of pure Gaussian type is the compatibility of these transformations with the enhanced solution functor (cf. [21, Theorem 4.17]).

**Lemma 9.3.** Let $M \in \text{Mod}_{\text{hol}}(\mathcal{D}_{\mathbb{P}_z})$ and $\text{Sol}^F_\mathbb{P}_z(M) \simeq k_{\mathbb{P}_z}^+ \otimes F$ for some $F \in \text{Mod}(\mathbb{k}_{C_z \times \mathbb{R}})$. One has an isomorphism in $\text{E}^b(\mathbb{k}_{\mathbb{P}_z})$

$$\text{Sol}^F_\mathbb{P}_z(^L M) \simeq k_{\mathbb{P}_w}^+ \otimes ^\mathcal{L} F.$$
10. Aligned parameters

In [30], C. Sabbah treated the case of a D-module of pure Gaussian type \( C \) with \( \arg c = \arg d \) for any \( c, d \in C \), i.e. the parameter set \( C \) is “aligned” along a half-line through the origin.

10.1. Main statement. Let \( \mathcal{M} \in D_{hol}^{b}(\mathcal{D}_\mathbb{F}) \) be a D-module of pure Gaussian type \( C \), where all the elements of \( C \) have the same argument \( \arg C \).

The directions of the Stokes lines are: \(-\frac{\pi}{4} - \frac{1}{2} \arg C + k \frac{\pi}{4}, k \in \mathbb{Z}/4\mathbb{Z} \). (These values are the same for any pair \( c, d \in C \).) In particular, we can choose \( \theta_0 := -\frac{1}{2} \arg C \) as a generic direction. Note that this involves a choice of \( \frac{\pi}{4} \arg C \), and we choose \( \theta_0 \in \left(-\frac{\pi}{2}, \frac{\pi}{2}\right) \).

It is known from Theorem 7.2 that

\[ \mathcal{S}^E_{\sigma}(\mathcal{M}) \simeq k_{\sigma}^+ \otimes \mathcal{F}_{\sigma}^{C, \theta_0, x}. \]

Therefore, in view of Lemma 9.3, the main step in computing the Fourier–Laplace transform of \( \mathcal{M} \) topologically is the proof of the following statement. Let \( C \) and \( \theta_0 \) be as above. Let \( r_c \in \mathbb{Z}_{\geq 0} \) be a positive integer for any \( c \in C \), and let \( \sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \) be a family of four block matrices (with block structure induced be the numbering on \( C \) with respect to \( \theta_0 \)) such that \( \sigma_k \) is upper (resp. lower) block-triangular for \( k \) odd (resp. even) and \( \sigma_1 \sigma_2 \sigma_1 = 1. \)

**Theorem 10.1.** Let \( C, \theta_0, x \) and \( \sigma \) be as above. We set \( \tilde{C} := -1/C = \left\{ -\frac{1}{c} \mid c \in C \right\}, \theta_0 := \pi - \theta_0 \) and \( \tilde{x} := (r_1 \tilde{c})_{\in \tilde{C}} \). Then there is an isomorphism

\[ \mathcal{L}\mathcal{F}_{\sigma}^{C, \theta_0, x} \simeq \mathcal{F}_{\sigma}^{\tilde{C}, \theta_0, \tilde{x}}. \]

In particular, the gluing matrices \( \sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \) remain the same (although sectors and exponential factors change).

As a corollary, we obtain the following result, which was already obtained in the context of Stokes data attached to Stokes-filtered local systems by C. Sabbah (cf. [30, Lemma 1.4, Theorem 4.2]). The statement is illustrated in Fig. 1.

**Corollary 10.2.** Let \( C \subset \mathbb{C}^\times \) be a finite subset whose elements have constant argument \( \arg C \). Let \( \mathcal{M} \in D_{hol}^{b}(\mathcal{D}_\mathbb{F}) \) be of pure Gaussian type \( C \) and let \( (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \) be Stokes multipliers with respect to the generic direction \( \theta_0 = -\frac{1}{2} \arg C \). Then the Fourier–Laplace transform \( \mathcal{L}\mathcal{M} \) of \( \mathcal{M} \) is of pure Gaussian type \( \tilde{C} = -1/C \) and Stokes multipliers with respect to the generic direction \( \tilde{\theta}_0 := \pi - \theta_0 \) are given by \( (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}} \).

The rest of this section will be concerned with the proof of Theorem 10.1. The idea of the proof is as follows: We choose a decomposition of the plane into four closed sectors \( S_k, k \in \mathbb{Z}/4\mathbb{Z}, \) on which \( \mathcal{F} = \mathcal{F}_{\sigma}^{C, \theta_0, x} \) is trivialized as a direct sum of exponential enhanced sheaves. As usual, write \( S_{k, k+1} := S_k \cap S_{k+1} \). We will first compute the enhanced Fourier–Sato transforms of these exponential enhanced ind-sheaves on the \( S_k \) and \( S_{k, k+1} \) (and hence \( \mathcal{L}(\mathcal{F}_{S_k}) \) and \( \mathcal{L}(\mathcal{F}_{S_{k, k+1}}) \)). Setting \( \mathcal{H}_+ := S_1 \cup S_2 \), \( \mathcal{H}_- := S_3 \cup S_4 \) and \( L := S_1 \cup S_{23} \), we can model the gluing of \( \mathcal{F} \) from the restrictions to sectors in terms of short exact sequences in \( \text{Mod}(k_{\mathbb{C}^\times}) \):

\[
0 \rightarrow \mathcal{F}_{\mathcal{H}_+} \rightarrow \mathcal{F}_{S_1} \oplus \mathcal{F}_{S_2} \rightarrow \mathcal{F}_{S_{12}} \rightarrow 0 \\
0 \rightarrow \mathcal{F}_{\mathcal{H}_-} \rightarrow \mathcal{F}_{S_3} \oplus \mathcal{F}_{S_4} \rightarrow \mathcal{F}_{S_{34}} \rightarrow 0 \\
0 \rightarrow \mathcal{F}_L \rightarrow \mathcal{F}_{S_{14}} \oplus \mathcal{F}_{S_{23}} \rightarrow \mathcal{F}_{(0)} \rightarrow 0 \\
0 \rightarrow \mathcal{F} \rightarrow \mathcal{F}_{\mathcal{H}_+} \oplus \mathcal{F}_{\mathcal{H}_-} \rightarrow \mathcal{F}_L \rightarrow 0
\]
Figure 1. The complex plane covered by four closed sectors, which are determined by the generic directions $\theta_0$ and $\hat{\theta}_0 = \pi - \theta_0$. (The red arrows indicate the Stokes directions.)

If a D-module of pure Gaussian type has a Hukuhara–Turrittin decomposition on each of the sectors $S_k$ (on the left) with exponents $-\frac{1}{2}z^2$ and Stokes multipliers $\sigma_k$, then its Fourier–Laplace transform has a Hukuhara–Turrittin decomposition on the sectors $\hat{S}_k$ (on the right) with exponents $\frac{1}{2}w^2$ and Stokes multipliers $\hat{\sigma}_k = \sigma_k$.

Applying the enhanced Fourier–Sato transform, we obtain distinguished triangles (which will turn out to be just short exact sequences), and we can determine step by step the enhanced Fourier–Sato transforms of $F_{H_1}$, $F_{H_2}$, $F_L$, and finally of $F$. We will give a proof for the case where $\arg C \in (-\frac{\pi}{2}, \frac{\pi}{2})$, i.e. $\text{Re} c > 0$. The arguments for the other cases $\text{Re} c < 0$ and $\text{Re} c = 0$ work completely along the same lines. However, the geometry of the objects involved depends on the sign of $\text{Re} c$.

10.2. Exponential enhanced sheaves on closed sectors. Let us choose the sectors (note that $0 \in S_k$)

\[
\begin{align*}
S_1 &:= \left\{ z \in \mathbb{C} : \arg z \in \left[0, \frac{\pi}{2} - \arg C\right] \text{ if } z \neq 0 \right\}, \\
S_2 &:= \left\{ z \in \mathbb{C} : \arg z \in \left[\frac{\pi}{2} - \arg C, \pi\right] \text{ if } z \neq 0 \right\}, \\
S_3 &:= \left\{ z \in \mathbb{C} : \arg z \in \left[-\pi, -\frac{\pi}{2} - \arg C\right] \text{ if } z \neq 0 \right\}, \\
S_4 &:= \left\{ z \in \mathbb{C} : \arg z \in \left[-\frac{\pi}{2} - \arg C, 0\right] \text{ if } z \neq 0 \right\}.
\end{align*}
\]

Denote the half-lines bounding the sectors by $S_{k,k+1} := S_k \cap S_{k+1}$ for $k \in \mathbb{Z}/4\mathbb{Z}$. It is easy to check that each of these sectors contains exactly one Stokes direction and that they are compatible with the $S_k$ in the sense of Lemma 7.4.

The first aim is to compute the enhanced Fourier–Sato transforms of the enhanced exponentials $\mathbb{E}_{S_k}^{\Re c \frac{1}{2}z^2}$, which are the building blocks of $F^{C,\theta_0,\pi}_\sigma$ on sectors. As mentioned, we assume $c = c_1 + ic_2 \in \mathbb{C}^\times$ with $c_1 > 0$. We will give the proof for $k = 1$.  


We can compute
\begin{equation}
\mathcal{E}^{-\text{Re } \hat{z}^2}_{S_1|\mathbb{C}_z} \simeq \mathcal{H}_p\left(\mathbf{k}_{(t-\text{Re } z \hat{w}^2) \geq 0} \otimes \mathbf{p}^{-1}\left(\pi^{-1}\mathbf{k}_{S_1} \otimes \mathbf{k}_{(t-\text{Re } \hat{z}^2 \geq 0)}\right)\right)[1]
\end{equation}
\[ \simeq \mathcal{H}_p\left(\pi^{-1}\mathbf{k}_{S_1 \times \mathbb{C}_w} \otimes \mathbf{k}_{(t-\text{Re } z \hat{w}^2) \geq 0} \otimes \mathbf{k}_{(t-\text{Re } \hat{z}^2 \geq 0)}\right)[1] \]
\[ \simeq \mathcal{H}_p\left(k\{z, w, t\in \mathbb{C}_z \times \mathbb{C}_w \times \mathbb{R} \mid z \in S_1, t-\text{Re}(z \hat{w} + \hat{z}^2) \geq 0\}[1]. \]

In particular, the stalks of the cohomology sheaves at a point \((\hat{w}, \hat{t}) \in \mathbb{C}_w \times \mathbb{R}\) are determined by the topology of the intersection of two subspaces of \(\mathbb{C}_z\):
\[ \mathcal{H}^l(\mathcal{E}^{-\text{Re } \hat{z}^2}_{S_1|\mathbb{C}_z})(\hat{w}, \hat{t}) \simeq \mathcal{H}^{l+1}(S_1 \cap \{ z \in \mathbb{C}_z \mid \hat{t} - \text{Re}(z \hat{w} + \hat{z}^2) \geq 0\}, k). \]

The inequality \(\hat{t} - \text{Re}(z \hat{w} + \hat{z}^2) \geq 0\) describes a region bounded by the two branches of a hyperbola. The hyperbola can be written in standard form if we write \(z = z_1 + iz_2\) and apply the coordinate transform
\begin{equation}
x_1 := z_1 - \frac{c_2}{c_1} z_2 + \frac{\hat{w}_1}{c_1}, \quad x_2 := z_2 + \frac{c_1 \hat{w}_2 - c_2 \hat{w}_1}{|c|^2}.
\end{equation}

Then, the space to be considered is the intersection of the (hyperbolic) region given by
\[ \frac{c_1}{2} x_1^2 - \frac{|c|^2}{2c_1} x_2^2 \leq \hat{t} - \text{Re}\left(\frac{1}{2|c|} \hat{w}^2\right) \]
and the sector given by
\[ x_1 \geq \frac{\hat{w}_1}{c_1}, \quad x_2 \geq \frac{c_1 \hat{w}_2 - c_2 \hat{w}_1}{|c|^2}. \]

Clearly, the topology of this intersection highly depends on the values of \(\hat{t}, \hat{w}_1\) and \(\hat{w}_2\). It is easy to see that the above compactly supported cohomology groups are trivial unless the intersection has a compact connected component (see Fig. 2, noting that the unbounded components have vanishing cohomology with compact support), and by elementary considerations one can determine the cases in which such a compact connected component exists. This yields the following lemma.

**Lemma 10.3.** There are isomorphisms
\begin{equation}
\mathcal{H}^l(\mathcal{E}^{-\text{Re } \hat{z}^2}_{S_1|\mathbb{C}_z}) \simeq 0 \text{ for } l \neq -1
\end{equation}
and
\begin{equation}
\mathcal{H}^{-1}(\mathcal{E}^{-\text{Re } \hat{z}^2}_{S_1|\mathbb{C}_z})(\hat{w}, \hat{t}) \simeq \begin{cases} k & \text{if } c_2 w_1 - c_1 w_2 \geq 0 \text{ and } -\varphi_{\tau,c}(\hat{w}) \leq \hat{t} < -\varphi_{\tau,c}^+(\hat{w}) \\ \text{otherwise} \end{cases}
\end{equation}
with the continuous functions \(\varphi_{\tau,c}^+, \varphi_{\tau,c}^- : \mathbb{C}_w \to \mathbb{R}\) defined by
\[ \varphi_{\tau,c}(w_1 + iw_2) := \begin{cases} \frac{w_2^2}{2c_1} & \text{if } w_1 \leq 0 \\ 0 & \text{if } w_1 > 0 \end{cases} \]
and
\[ \varphi_{\tau,c}^+(w_1 + iw_2) := \begin{cases} \frac{1}{2c_1|c|^2}(c_1 w_1^2 - c_2 w_2^2 + 2c_2 w_1 w_2) = \text{Re}\left(\frac{1}{2c_1} w^2\right) & \text{if } w_1 \leq 0 \\ -\frac{1}{2c_1|c|^2}(c_2 w_1 - c_1 w_2)^2 = q_{\tau,w}(w) & \text{if } w_1 > 0 \end{cases} \]

Observe that \(\varphi_{\tau,c}^+(w) - \varphi_{\tau,c}^-(w) = \frac{1}{2c_1|c|^2}(c_2 w_1 - c_1 w_2)^2\), so \(\varphi_{\tau,c}^+(w) \geq \varphi_{\tau,c}^-(w)\) for all \(w \in \mathbb{C}_w\).
The cases of the sectors \(S_2, S_3,\) and \(S_4\) are analogous. For the sectors \(S_2\) and \(S_1,\) one needs to introduce the continuous functions \(\varphi_{+}^{+}, \varphi_{-}^{-}: \mathbb{C}_w \to \mathbb{R},\) which are given by

\[
\varphi_{+}^{+}(w_1 + iw_2) := \begin{cases} 0 & \text{if } w_1 < 0 \\ \frac{w_2}{2w_1} & \text{if } w_1 \geq 0 \end{cases}
\]

and

\[
\varphi_{-}^{-}(w_1 + iw_2) := \begin{cases} -\frac{1}{2c_2w_1}(c_2w_2 - c_1w_1)^2 = \eta_k(w) & \text{if } w_1 < 0 \\ \frac{1}{2c_2w_1}(c_1w_2^2 - c_1w_1^2 + 2c_2w_1w_2) = \Re \frac{1}{2w_1} & \text{if } w_1 \geq 0 \end{cases}
\]

Set \(\hat{H}_- := \{w \in \mathbb{C}_w \mid c_2w_1 - c_1w_2 \geq 0\}\) and \(\hat{H}_+ := \{w \in \mathbb{C}_w \mid c_2w_1 - c_1w_2 \leq 0\}.

Note that these half-planes only depend on \(\arg C.\) The stalks suggest the following global statement. (Recall the notation from Section 2.2.)

**Proposition 10.4.** There are isomorphisms in \(\mathcal{D}^b( \mathbb{k}_{\mathbb{C}_w \times \mathbb{R}})\)

\[
\mathcal{E}_{\mathbb{S}_1|\mathbb{C}_w} \simeq \mathcal{E}_{\mathbb{S}_2|\mathbb{C}_w} \simeq \mathcal{E}_{\mathbb{S}_3|\mathbb{C}_w} \simeq \mathcal{E}_{\mathbb{S}_4|\mathbb{C}_w}
\]

**Proof.** We give a proof for the case of \(S_1.\)

Set \(A := \{(z, w, t) \in \mathbb{C}_z \times \mathbb{C}_w \times \mathbb{R} \mid t - \Re(zw + \frac{c}{2}z^2) \geq 0\} \cap (S_1 \times \mathbb{C}_w \times \mathbb{R})\) and recall from (10.1) that \(\mathcal{E}_{\mathbb{S}_1|\mathbb{C}_w} \simeq \mathcal{R}_{\mathbb{H}}k_A.\)

First, consider the set

\[
U := \{(z, w, t) \in \mathbb{C}_z \times \mathbb{C}_w \times \mathbb{R} \mid z \in S_1, t - \Re(zw + \frac{c}{2}z^2) \geq 0, t < -\varphi_{r,c}(w)\}.
\]

It is an open subset of \(A\) and hence we have a distinguished triangle in \(\mathcal{D}^b( \mathbb{k}_{\mathbb{C}_w \times \mathbb{R}})\)

\[
\mathcal{R}_{\mathbb{H}}k_U \longrightarrow \mathcal{R}_{\mathbb{H}}k_A \longrightarrow \mathcal{R}_{\mathbb{H}}k_{A \cap U} \longrightarrow \mathcal{R}_{\mathbb{H}}k_U[1].
\]

By the projection formula, \(\mathcal{R}_{\mathbb{H}}k_{A \cap U} \simeq \mathcal{R}_{\mathbb{H}}(k_A \otimes \overline{q}^{-1}k_{\{w, t \in \mathbb{C}_w \times \mathbb{R} \mid t \geq -\varphi_{r,c}(w)\}}) \simeq \mathcal{R}_{\mathbb{H}}k_A \otimes k_{\{w, t \in \mathbb{C}_w \times \mathbb{R} \mid t \geq -\varphi_{r,c}(w)\}}\) and hence it follows from (10.3) and (10.4) that \(\mathcal{R}_{\mathbb{H}}k_{A \cap U} \simeq 0\) and \(\mathcal{R}_{\mathbb{H}}k_A \simeq \mathcal{R}_{\mathbb{H}}k_U.\)

Next, consider the set

\[
B := \{(z, w, t) \in \mathbb{C}_z \times \mathbb{C}_w \times \mathbb{R} \mid z_1 = \frac{1}{c_1}(\sqrt{2c_1t + w_1^2} - w_1), z_2 = 0, c_2w_1 - c_1w_2 \geq 0, -\varphi_{r,c}(w) \leq t < -\varphi_{r,c}(w)\}
\]

For fixed \(\hat{w}\) and \(\hat{l},\) the corresponding point \(z = \frac{1}{c_1}(\sqrt{2c_1\hat{t} + \hat{w}_1^2} - \hat{w}_1)\) is the rightmost intersection point of the hyperbolic region \(\{t - \Re(z\hat{w} + \frac{c}{2}z^2) \geq 0\}\) with the
horizontal border of the sector $S_1$. Moreover, $B$ is a closed subset of $U$ and we get a distinguished triangle in $D^b(k_{C_u \times \mathbb{R}})$

$$R\tilde{q}_!k_{U\setminus B} \to R\tilde{q}_!k_U \to R\tilde{q}_!k_B \to +1.$$ 

The stalks of the cohomology sheaves of $R\tilde{q}_!k_{U\setminus B}$ are all trivial, and hence $R\tilde{q}_!k_B \cong R\tilde{q}_!k_U$.

Finally, one has

$$\mathcal{L}E^{-\Re z^2}_{\{S_1\}|C_z} \cong E^0_{\{\mathcal{H}_{-}\}|C_w}[1],$$

which induces a homeomorphism $B \cong \{w \in \mathcal{H}_{-}, -\varphi_{t,c}^{+}(w) \leq t < -\varphi_{t,c}^{-}(w)\}$. □

The computations of the enhanced Fourier–Sato transforms of $E^{-\Re \tilde{z}^2}_{\{S_{\kappa,k+1}\}|C_z}$ and $E^{-\Re \tilde{z}^2}_{\{0\}|C_z} = E^0_{\{0\}|C_z}$ are similar.

**Proposition 10.5.** There are isomorphisms in $D^b(k_{C_u \times \mathbb{R}})$

$$\mathcal{L}E^{-\Re \tilde{z}^2}_{\{S_{\kappa}\}|C_z} \cong E^{0}_{\{\hat{\mathcal{H}}_{-}\}|C_w}[1],$$

$$\mathcal{L}E^{-\Re \tilde{z}^2}_{\{S_{\kappa}\}|C_z} \cong E^{0}_{\{\mathcal{H}_{-}\}|C_w}[1],$$

$$\mathcal{L}E^{-\Re \tilde{z}^2}_{\{S_{\kappa}\}|C_z} \cong E^{0}_{\{\hat{\mathcal{H}}_{-}\}|C_w}[1],$$

$$\mathcal{L}E^{-\Re \tilde{z}^2}_{\{0\}|C_z} \cong E^{0}_{\{\mathcal{H}_{-}\}|C_w}[1].$$

Now that we computed the Fourier–Laplace transform of exponentials, let us briefly reflect on the impact of Fourier–Laplace on morphisms between those exponentials: Exponential enhanced sheaves are sheaves of the form $k_{Z}$ for some locally closed $Z \subseteq C \times \mathbb{R}$. A morphism between two exponentials is therefore given by multiplication with an element $a \in k$ (at points where both stalks are $k$, it is multiplication by $a$). Since the enhanced Fourier–Sato transform consists only of tensor products and direct and inverse images along projections, one checks that the induced morphism between the enhanced Fourier–Laplace transforms of the exponentials is again given by multiplication with the same element $a \in k$.

10.3. **Enhanced Fourier–Sato transform of a Gaussian enhanced sheaf.** In this section, we will elaborate on the idea given at the end of Section 10.1 in order to describe the enhanced Fourier–Sato transform of $\mathcal{F}^{G,\theta_0,x}_\sigma$. We write for short $\mathcal{F} := \mathcal{F}^{G,\theta_0,x,\sigma}.$

To make notation easier, we will write $E^x_Z$ instead of $E^x_{\{\mathcal{H}_{+}\}}$ and we shall assume $r_c = 1$ for any $c \in C$. (One can replace any occurrence of a direct sum $\bigoplus_{t \in C} E^x_Z$ by $\bigoplus_{t \in C} (E^x_Z)^{r_c}$ and the word “triangular” by “block-triangular”, and the proof is still valid.)

Recall that we have defined a covering of the plane $C_z$ by four closed sectors $S_k$, $k \in \mathbb{Z}/4\mathbb{Z}$. We set $\mathcal{H}_{+} := S_1 \cup S_2$ and $\mathcal{H}_{-} := S_3 \cup S_4$ as well as $S_{k,k+1} := S_k \cap S_{k+1}$. On these sectors, we have isomorphisms

$$\alpha_k : \mathcal{F}_{S_k} \cong \bigoplus_{c \in C} E^{-\Re \tilde{z}^2}_{S_k}$$

and the gluing morphisms $\alpha_{k+1} \circ \alpha_k^{-1}$ on $S_{k,k+1}$ are given by the Stokes multipliers $\sigma_k$. 
10.3.1. Transform of restrictions to half-planes. Let us start by investigating the short exact sequence in \( \text{Mod}(k_{\mathbb{C} \times \mathbb{R}}) \)

\[
(10.5) \quad 0 \rightarrow \mathcal{F}_{H_{+}} \rightarrow \mathcal{F}_{S_1} \oplus \mathcal{F}_{S_2} \rightarrow \mathcal{F}_{S_{12}} \rightarrow 0.
\]

Via \( \alpha_1 \) and \( \alpha_2 \) (the latter used also for \( \mathcal{F}_{S_{12}} \)), it is isomorphic to

\[
0 \rightarrow \mathcal{F}_{H_{+}} \rightarrow \bigoplus_{c \in C} E_{S_1}^{\text{Re } \hat{z}^2} \oplus \bigoplus_{c \in C} E_{S_2}^{\text{Re } \hat{z}^2} \xrightarrow{\sigma_1 - \hat{\eta}} E_{S_{12}}^{\text{Re } \hat{z}^2} \rightarrow 0.
\]

Applying the enhanced Fourier–Sato transform and using the results of the previous section, we get a distinguished triangle in \( \text{D}^b(k_{\mathbb{C} \times \mathbb{R}}) \)

\[
\mathcal{L}(\mathcal{F}_{H_{+}})[-1] \rightarrow \bigoplus_{c \in C} E_{R_{-}}^{\hat{x}^2} \oplus \bigoplus_{c \in C} E_{R_{-}}^{\hat{x}^2} \xrightarrow{\sigma_1 - 1} \bigoplus_{c \in C} E_{R_{-}}^{0 \eta_1} \rightarrow \bigoplus_{c \in C} E_{R_{-}}^{0 \eta_1} \rightarrow 0.
\]

Since the morphism \( \sigma_1 - 1 \) is an epimorphism in \( \text{Mod}(k_{\mathbb{C} \times \mathbb{R}}) \), the associated long exact sequence yields the following proposition, comprising also the statements for \( \mathcal{H}_{-} \) and \( \mathcal{L} := S_{41} \cup S_{33} \).

**Proposition 10.6.** Let \( \mathcal{F} = \mathcal{F}_c \) be an enhanced sheaf of pure Gaussian type (cf. Lemma-Definition 7.1). The complexes \( \mathcal{L}(\mathcal{F}_{H_{+}}) \), \( \mathcal{L}(\mathcal{F}_{H_{-}}) \) and \( \mathcal{L}(\mathcal{F}_{L}) \) are concentrated in degree \(-1\). More precisely, there are isomorphisms in \( \text{D}^b(k_{\mathbb{C} \times \mathbb{R}}) \)

\[
\mathcal{L}(\mathcal{F}_{H_{+}})[-1] \simeq \ker \left( \sigma_1 - 1: \bigoplus_{c \in C} E_{R_{-}}^{\hat{x}^2} \oplus \bigoplus_{c \in C} E_{R_{-}}^{\hat{x}^2} \rightarrow \bigoplus_{c \in C} E_{R_{-}}^{0 \eta_1} \right),
\]

\[
\mathcal{L}(\mathcal{F}_{H_{-}})[-1] \simeq \ker \left( 1 - \sigma_3: \bigoplus_{c \in C} E_{R_{+}}^{\hat{x}^2} \oplus \bigoplus_{c \in C} E_{R_{+}}^{\hat{x}^2} \rightarrow \bigoplus_{c \in C} E_{R_{+}}^{0 \eta_1} \right),
\]

\[
\mathcal{L}(\mathcal{F}_{L})[-1] \simeq \ker \left( 1 - \sigma_4 \sigma_3: \bigoplus_{c \in C} E_{C_{w}}^{\hat{x}^2} \oplus \bigoplus_{c \in C} E_{C_{w}}^{\hat{x}^2} \rightarrow \bigoplus_{c \in C} E_{C_{w}}^{0} \right).
\]

10.3.2. Transform on the whole plane. We can now examine the sequence

\[
(10.6) \quad 0 \rightarrow \mathcal{F} \rightarrow \mathcal{F}_{H_{+}} \oplus \mathcal{F}_{H_{-}} \rightarrow \mathcal{F}_{L} \rightarrow 0,
\]

which will enable us to describe \( \mathcal{L} \mathcal{F} \) and show that it is of the desired form on sectors.

Let us first make the morphism \( \mathcal{F}_{H_{+}} \oplus \mathcal{F}_{H_{-}} \rightarrow \mathcal{F}_{L} \) more explicit: Sequence (10.5) and similar sequences for \( \mathcal{H}_{-} \) and \( L \) yield commutative diagrams

\[
(10.7) \quad \begin{array}{ccc}
0 & \rightarrow & \mathcal{F}_{H_{+}} \\
\bigoplus_{c \in C} E_{S_1}^{\text{Re } \hat{z}^2} & \rightarrow & \bigoplus_{c \in C} E_{S_2}^{\text{Re } \hat{z}^2} \\
\downarrow \sigma_1 \downarrow \downarrow & & \downarrow \downarrow \downarrow \sigma_1 \downarrow \\
0 & \rightarrow & E_{S_{12}}^{\text{Re } \hat{z}^2} \bigoplus_{c \in C} E_{S_2}^{\text{Re } \hat{z}^2} \xrightarrow{\sigma_1 - 1} E_{S_{12}}^{\text{Re } \hat{z}^2}
\end{array}
\]

and

\[
\begin{array}{ccc}
0 & \rightarrow & \mathcal{F}_{L} \\
\bigoplus_{c \in C} E_{S_{41}}^{\text{Re } \hat{z}^2} & \rightarrow & \bigoplus_{c \in C} E_{S_{23}}^{\text{Re } \hat{z}^2} \\
\downarrow \sigma_1 \downarrow \downarrow & & \downarrow \downarrow \downarrow \sigma_1 \downarrow \\
0 & \rightarrow & E_{S_{12}}^{\text{Re } \hat{z}^2} \bigoplus_{c \in C} E_{S_2}^{\text{Re } \hat{z}^2} \xrightarrow{\sigma_1 - 1} E_{S_{12}}^{\text{Re } \hat{z}^2}
\end{array}
\]
Indeed, generic and the sequence considerations from the previous sections suggest using the following sectors:

\[\text{Proof.} \quad \text{We prove the desired isomorphism for (10.8)} \]

The enhanced Fourier–Sato transform \(F^\ast \) and on \( L \) in particular, the kernels are the ones from Proposition (10.10). Here, the kernels are \( \{ \hat{\theta}_0 \} \) and \( \{ \hat{\theta}_0 + (k - 1) \frac{\pi}{2}, \hat{\theta}_0 + k \frac{\pi}{2} \} \) in the sense of Lemma 7.1. (An a posteriori justification for the choice of the generic direction is given by Proposition 10.8.) We have \( \hat{\mathcal{H}}_+ = \hat{\mathcal{S}}_4 \cup \hat{\mathcal{S}}_1 \) and \( \hat{\mathcal{H}}_- = \hat{\mathcal{S}}_1 \cup \hat{\mathcal{S}}_2 \), and we set \( \hat{\mathcal{S}}_{k+1} = \hat{\mathcal{S}}_k \cap \hat{\mathcal{S}}_{k+1} \).

**Proposition 10.7.** The enhanced Fourier–Sato transform \( F^\ast \) is concentrated in degree zero and for every \( k \in \mathbb{Z}/4\mathbb{Z} \), we have an isomorphism in \( D^b(k_{\mathbb{C}_w \times \mathbb{R}}) \)

\[(F^\ast)_k \simeq \bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_k}^w \partial w^2.\]

In particular, \( F^\ast \) is of pure Gaussian type \( \hat{C} = -1/C \).

**Proof.** We prove the desired isomorphism for \( k = 1 \).

From (10.6), we get a distinguished triangle

\[(10.9) \quad \text{ker}(\sigma_1 - 1)_{\hat{\mathcal{S}}_1} \oplus \text{ker}(1 - \sigma_3)_{\hat{\mathcal{S}}_1} \xrightarrow{\text{ker}(\sigma_4)_{\hat{\mathcal{S}}_1}(1)} \ker(\sigma_4)_{\hat{\mathcal{S}}_1} \rightarrow (F^\ast)_{\hat{\mathcal{S}}_1} \xrightarrow{+1} \]

Here, the kernels are the ones from Proposition 10.6. The first morphism is induced by the ones described in (10.7) and (10.8).

Firstly, we note that \( \ker(1 - \sigma_3)_{\hat{\mathcal{S}}_1} \simeq 0 \) since it is the kernel of the morphism

\[\bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_{11}}^w \partial w^2 \xrightarrow{\oplus E_{\widehat{S}_{11}}^w \partial w^2} \bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_{11}}^w \partial w^2 \xrightarrow{1 - \sigma_4} \bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_{11}}^w \partial w^2 \]

and on \( \widehat{S}_{11} \) we have \( c_2 w_1 - c_1 w_2 = 0 \), hence \( \varphi_{c_1,w}^-(w) = \varphi_{c_1,w}^+(w) \).

Secondly, we determine \( \ker(\sigma_1 - 1)_{\hat{\mathcal{S}}_1} \): It is the first object in the short exact sequence

\[(10.10) \quad 0 \rightarrow \bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_1}^w \partial w^2 \xrightarrow{\oplus E_{\widehat{S}_1}^w \partial w^2} \bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_1}^w \partial w^2 \xrightarrow{1 - \sigma_4} \bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_1}^w \partial w^2 \xrightarrow{\sigma_1 - 1} \bigoplus_{c \in \mathbb{C}} E_{\widehat{S}_1}^w \partial w^2 \rightarrow 0.\]
Thirdly, we find \( \ker(\mathbb{1} - \sigma_4\sigma_3)\mathcal{S}_1 \) as the first object in the short exact sequence

\[
0 \rightarrow \bigoplus_{c \in C} E_{\frac{w}{2\pi} + \sigma_1}^{c} \xrightarrow{\mathbb{1} - \sigma_2\sigma_3} \bigoplus_{c \in C} E_{\frac{w}{2\pi} + \sigma_1}^{c} \oplus \bigoplus_{c \in C} E_{\frac{w}{2\pi} - \sigma_2\sigma_3}^{c} \rightarrow 0.
\]

Finally, there is a commutative diagram in which the sequences (10.10) and (10.11) appear as the columns, and which has exact rows and columns:

\[
\begin{array}{cccc}
0 & 0 & 0 & 0 \\
0 & E_{\frac{w}{2\pi} + \sigma_1}^{c} & E_{\frac{w}{2\pi} + \sigma_1}^{c} & E_{\frac{w}{2\pi} + \sigma_1}^{c} \\
& \mathbb{1} - \sigma_2\sigma_3 & \mathbb{1} - \sigma_2\sigma_3 & \mathbb{1} - \sigma_2\sigma_3 \\
& \sigma_1 - 1 & \sigma_1^{-1} & \sigma_1^{-1} \\
& 0 & 0 & 0
\end{array}
\]

Comparing the upper row of this diagram with the long exact sequence associated to (10.9), the statement of the proposition follows.

10.4. **Stokes multipliers of the Fourier–Laplace transform.** We have seen in Proposition 10.7 that \( \mathcal{F} \) is isomorphic to a direct sum of exponential enhanced sheaves on each of the \( \mathcal{S}_k \) (and such isomorphisms have actually been constructed). Therefore, on each of the half-lines \( \mathcal{S}_{k,k+1} \) we have two trivializing isomorphisms \( \hat{\alpha}_k \) and \( \hat{\alpha}_{k+1} \) coming from the ones on the two adjacent sectors. Our aim is to find matrices \( \hat{\sigma}_k \) representing an automorphism of \( \bigoplus_{c \in C} E_{\frac{w}{2\pi} + \sigma_2}^{w_2} \) such that the following diagram commutes for any \( k \in \mathbb{Z}/4\mathbb{Z} \):

\[
\begin{array}{ccc}
\bigoplus_{c \in C} E_{\frac{w}{2\pi} + \sigma_2}^{c} & \xrightarrow{\hat{\sigma}_k} & \bigoplus_{c \in C} E_{\frac{w}{2\pi} + \sigma_2}^{c} \\
\alpha_k & \sim & \alpha_k \\
\end{array}
\]

Note that \( \bigoplus_{c \in C} E_{\frac{w}{2\pi} + \sigma_2}^{c} = \bigoplus_{c \in C} E_{\frac{w}{2\pi} - \sigma_2}^{c} \) and the order on \( \hat{C} \) with respect to \( \hat{\theta}_0 \) is the one induced by the order on \( C \) with respect to \( \theta_0 \), i.e. \( c < \theta_0 d \) if and only if \( \hat{c} < \theta_0 \hat{d} \).

**Proposition 10.8.** **Gluing matrices for** \( \mathcal{F} \)** **are given by** \( \hat{\sigma}_k = \sigma_k, \ k \in \mathbb{Z}/4\mathbb{Z} \).

**Proof.** Let us give the proof for \( \hat{\sigma}_1 = \sigma_1 \).
By what we learnt in Proposition 10.7, the triangle (10.9) is actually a short exact sequence (identifying $\mathcal{E}_F$ with $H^0(\mathcal{E}_F)$)

$$0 \rightarrow \ker(\sigma_1 - 1) \oplus \ker(1 - \sigma_3) \xrightarrow{(1|\sigma_2) - (\sigma_1|\mathcal{E})} \ker(1 - \sigma_4 \sigma_3) \rightarrow \mathcal{E}_F \rightarrow 0.$$ 

On $\hat{S}_1$ (i.e. applying $(\bullet)_{\hat{S}_1}$), it induces

$$0 \rightarrow \ker(\sigma_1 - 1)_{\hat{S}_1} \xrightarrow{1|\sigma_2} \ker(1 - \sigma_4 \sigma_3)_{\hat{S}_1} \rightarrow (\mathcal{E}_F)_{\hat{S}_1} \rightarrow 0$$

since we proved $\ker(1 - \sigma_3)_{\hat{S}_1} \simeq 0$. We obtained determinations of $\ker(\sigma_1 - 1)_{\hat{S}_1}$ and $\ker(1 - \sigma_4 \sigma_3)_{\hat{S}_1}$ and hence the isomorphism $\hat{\alpha}_1$ as the third vertical arrow in the diagram

(10.13)

Similarly, $\hat{\alpha}_2$ is obtained from the diagram

(10.14)

Now we can take the right square of diagrams (10.13) and (10.14), apply the functor $(\bullet)_{\hat{S}_{12}}$ and identify their first lines, and we obtain

(10.15)

and the purple arrow is the one in question. Therefore, it remains to determine the orange one.

The object $\ker(1 - \sigma_4 \sigma_3)_{\hat{S}_1}$ was determined by the short exact sequence

$$0 \rightarrow \bigoplus_{c \in C} E_{\hat{S}_1}^{c} \xrightarrow{(1, \sigma_2 \sigma_1)} \bigoplus_{c \in C} E_{\hat{S}_1}^{c} \oplus \bigoplus_{c \in C} E_{\hat{S}_1}^{c} \xrightarrow{1 - \sigma_4 \sigma_3} \bigoplus_{c \in C} E_{\hat{S}_1}^{c} \rightarrow 0$$

and the object $\ker(1 - \sigma_4 \sigma_3)_{\hat{S}_{12}}$ by the sequence

$$0 \rightarrow \bigoplus_{c \in C} E_{\hat{S}_2}^{c} \xrightarrow{\sigma_1^{-1} \sigma_2^{-1} \sigma_3} \bigoplus_{c \in C} E_{\hat{S}_2}^{c} \oplus \bigoplus_{c \in C} E_{\hat{S}_2}^{c} \xrightarrow{1 - \sigma_4 \sigma_3} \bigoplus_{c \in C} E_{\hat{S}_2}^{c} \rightarrow 0.$$
Applying the functor \((\bullet)_{S_{12}}\), the second and third objects of both sequences are identified (since \(w_1 = 0\) on \(\hat{S}_{12}\)) and the induced isomorphism between the first objects (which is the orange arrow from \((10.15)\)) is clearly given by \(\sigma_2\sigma_1\). Therefore, it follows from \((10.15)\) that \(\hat{\sigma}_1 = \sigma_1\). □

This concludes the proof of Theorem 10.1.

11. A more general case

In this section, we show how the methods of the previous section can be adapted to a case with weaker assumptions on the parameter set \(C\). In contrast to \([30]\), this yields an explicit solution to the problem of finding a transformation rule for Stokes data in more general cases than in Section 10. Although Corollary 4.19 in loc. cit. provided a theoretical answer by stating that arbitrary parameter configurations can be deformed into those studied in the previous section, this answer was not at all explicit.

We restrict to the case where \(C = \{c, d\}\) consists of two parameters and the ranks of the regular parts are \(r_c = r_d = 1\) (and we suppress \(i_r\) in our notation).

**Condition 11.1.** We say that an ordered pair \((c, d)\) of nonzero complex numbers \(c, d \in \mathbb{C}^\times\) satisfies condition \((\sim)\) if the following is satisfied:

\[(\sim) \quad c_1 > 0, \quad c_2 \geq 0, \quad d_1 > c_1, \quad \text{and} \quad \frac{d_2}{d_1} \geq \frac{c_2}{c_1},\]

where we write \(c = c_1 + ic_2\) and \(d = d_1 + id_2\) with their real and imaginary parts.

**Theorem 11.2.** Let \(C, \theta_0\) and \(\sigma\) be as above. If we set \(\hat{C} := \{-\frac{1}{2}, -\frac{1}{2}\}\) and \(\hat{\theta}_0 := \pi - \theta_0\), there is an isomorphism in \(\mathcal{D}^b(\mathbb{C} \times \mathbb{R})\)

\[\mathcal{L}_{\sigma}C, \theta_0 \cong \mathcal{L}_{\hat{\sigma}}\hat{C}, \hat{\theta}_0.\]

**Corollary 11.3.** Let \(M\) be of pure Gaussian type \(C = \{c, d\}\) such that \((\sim)\) holds. Then \(\hat{M}\) is of pure Gaussian type \(\hat{C} = \{-\frac{1}{2}, -\frac{1}{2}\}\). Moreover, if \(\sigma = (\sigma_k)_{k \in \mathbb{Z}/4\mathbb{Z}}\) is a family of Stokes multipliers for \(M\) with respect to the generic direction \(\theta_0 = -\frac{1}{2} \arg c\), then \(\sigma\) is also a family of Stokes multipliers for \(\hat{M}\) with respect to the generic direction \(\hat{\theta}_0 = \pi - \theta_0\).
Proof of Theorem 11.2. First, we choose a sector decomposition analogously to Section 10.2, replacing \( \arg C \) by \( \arg c \), i.e.

\[
S_1 := \left\{ z \in \mathbb{C}_+ \mid \arg z \in \left[ 0, \frac{\pi}{2} - \arg c \right] \text{ if } z \neq 0 \right\} \quad \text{etc.}
\]

Next, we compute the enhanced Fourier–Sato transforms of the exponentials involved: For the parameter \( c \), this is exactly the same computation that we performed above, i.e.

\[
\mathcal{E}^{-\Re} \hat{z}^2 \simeq \mathcal{E}_{S_1 \mid \mathbb{C}_+}^{\Re} \mathcal{E}_{Y_1 \mid \mathbb{C}_+}^{\Re} 1 \quad \text{etc.}
\]

(see Proposition 10.4, we write \( \varphi^+ \) instead of \( \varphi^{+}_{r,c} \) etc. here). For the exponentials \( \mathcal{E}^{-\Re} \hat{z}^2 \), one proceeds similarly. However, the coordinate transform for the parameter \( d \) (similar to (10.2)) does not transform \( S_{\mathcal{M}} \) into right-angled sectors.

Hence, the geometry of the intersection spaces is more involved, yet it is still not too difficult to determine the compactly supported cohomologies, and we find that

\[
\mathcal{E}^{-\Re} \hat{z}^2 \simeq \mathcal{E}_{S_1 \mid \mathbb{C}_+}^{\Re} \mathcal{E}_{Y_1 \mid \mathbb{C}_+}^{\Re} 1, \quad \mathcal{E}^{-\Re} \hat{z}^2 \simeq \mathcal{E}_{S_2 \mid \mathbb{C}_+}^{\Re} \mathcal{E}_{Y_2 \mid \mathbb{C}_+}^{\Re} 1, \quad \mathcal{E}^{-\Re} \hat{z}^2 \simeq \mathcal{E}_{S_3 \mid \mathbb{C}_+}^{\Re} \mathcal{E}_{Y_3 \mid \mathbb{C}_+}^{\Re} 1, \quad \mathcal{E}^{-\Re} \hat{z}^2 \simeq \mathcal{E}_{S_4 \mid \mathbb{C}_+}^{\Re} \mathcal{E}_{Y_4 \mid \mathbb{C}_+}^{\Re} 1.
\]

Here, the functions \( \psi^+_t, \psi^-_t : \mathbb{C}_w \rightarrow \mathbb{R} \) are defined by

\[
\psi^+_t(w) := \begin{cases} \frac{w^2}{2} & \text{if } w_1 \leq 0 \\ 0 & \text{if } w_1 > 0 \end{cases}
\]

and

\[
\psi^-_t(w) := \begin{cases} \frac{w^2}{2} & \text{if } (c_1 d_2 - c_2 d_1) w_2 \leq -(c_1 d_1 + c_2 d_2) w_1 \\ \frac{w^2}{2} & \text{if } (c_1 d_2 - c_2 d_1) w_2 > -(c_1 d_1 + c_2 d_2) w_1 \end{cases}
\]

where \( \zeta(w) := -\frac{(c_2 d_1 - c_1 d_2)^2}{2c_1 d_1 c_2 d_2 - c_1^2 d_2^2} \) and \( \psi^+_t, \psi^-_t : \mathbb{C}_w \rightarrow \mathbb{R} \) are similar (with cases interchanged). Moreover,

\[
Y_1 := \left\{ w \in \mathbb{C}_w \mid w_2 \leq \min \left( \frac{c_2}{c_1} w_1, \frac{d_2}{d_1} w_1 \right) \right\}, \\
Y_2 := \left\{ w \in \mathbb{C}_w \mid w_2 \leq \max \left( \frac{c_2}{c_1} w_1, \frac{d_2}{d_1} w_1 \right) \right\}, \\
Y_3 := \left\{ w \in \mathbb{C}_w \mid w_2 \geq \max \left( \frac{c_2}{c_1} w_1, \frac{d_2}{d_1} w_1 \right) \right\}, \\
Y_4 := \left\{ w \in \mathbb{C}_w \mid w_2 \geq \min \left( \frac{c_2}{c_1} w_1, \frac{d_2}{d_1} w_1 \right) \right\}.
\]

One can now determine \( \mathcal{E}^{-\Re} \left( \mathcal{F}_{\mathcal{M}} \right) \), \( \mathcal{E}^{-\Re} \left( \mathcal{F}_{\mathcal{K}} \right) \) and \( \mathcal{E}^{-\Re} \left( \mathcal{F}_{\mathcal{L}} \right) \) by enhanced Fourier–Sato transform of short exact sequences (cf. Proposition 10.6). One then proves isomorphisms

\[
\mathcal{E}^{-\Re} \left( \mathcal{F}_{\mathcal{M}} \right) \simeq \mathcal{E}^{-\Re} \left( \mathcal{F}_{\mathcal{K}} \right) \oplus \mathcal{E}^{-\Re} \left( \mathcal{F}_{\mathcal{L}} \right),
\]

where the sectors \( \mathcal{S}_{\mathcal{M}} \) are defined as in Section 10.3 (with \( \arg C \) replaced by \( \arg c \)), i.e.

\[
\mathcal{S}_1 := \left\{ w \in \mathbb{C}_w \mid \arg w \in \left[ -\pi + \arg c, -\frac{\pi}{2} \right] \text{ if } w \neq 0 \right\} \quad \text{etc.}
\]
The main difference is the fact that the supports of the Fourier–Sato transforms of the \( E^{-\Re \frac{u^2}{y_k}} \) (i.e. the sets \( Y_k \)) are not unions of these sectors (see Fig. 4). Therefore, if we want to mimic the proof of Proposition 10.7 (for \( k = 1 \)), we will not have \( \ker(1 - \sigma_3) \simeq 0 \), but the second summand of \( \ker(\sigma_1 - 1) \) “splits” into two parts. The diagram corresponding to (10.12) in this case then looks as follows (we write direct sums vertically):

Although the left part of the diagram becomes more complicated, the cokernel of the morphism in the first line is as desired.

The computation of transition matrices for \( \mathcal{C} \mathcal{F} \) then works analogously to that in the aligned case.

A generalization to more than two parameters (and ranks not equal to 1) is easily possible: One then needs to require that the elements of \( C = \{ c_{(1)}, \ldots, c_{(n)} \} \) satisfy condition (L) “pairwise”, i.e. \( (c_{(k)}, c_{(k+1)}) \) satisfies condition (L) for any \( k \in \{ 1, \ldots, n - 1 \} \).

This result shows that the considerations of Section 10 can – with a little effort, but without serious difficulties – be adapted to more general situations. Our assumptions were chosen in such a way that we were able to reuse some results.

Figure 4. The sets \( Y_k \) and their relative positions with respect to the sectors \( \hat{S}_k \).
from the aligned case. However, under different assumptions on the parameters, one can proceed similarly, as long as one can choose suitable sectors in the domain and target of the Fourier–Laplace transform keeping the topological situation reasonable.

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