Generalized Bregman envelopes and proximity operators

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Abstract

Every maximally monotone operator can be associated with a family of convex functions, called the Fitzpatrick family or family of representative functions. Surprisingly, in 2017, Burachik and Martínez-Legaz showed that the well-known Bregman distance is a particular case of a general family of distances, each one induced by a specific maximally monotone operator and a specific choice of one of its representative functions. For the family of generalized Bregman distances, sufficient conditions for convexity, coercivity, and supercoercivity have recently been furnished. Motivated by these advances, we introduce in the present paper the generalized left and right envelopes and proximity operators, and we provide asymptotic results for parameters. Certain results extend readily from the more specific Bregman context, while others only extend for certain generalized cases. To illustrate, we construct examples from the Bregman generalizing case, together with the natural “extreme” cases that highlight the importance of which generalized Bregman distance is chosen.

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1. Introduction

In this paper, unless stated otherwise, $\left( X, \| \cdot \| \right)$ is a reflexive Banach space with dual $\left( X^*, \| \cdot \|_* \right)$, and $\Gamma_0(X)$ is the set of all proper lower semicontinuous convex functions from $X$ to $]-\infty, +\infty[.$

In 1962, Moreau [33] introduced what has come to be known as the Moreau envelope,

$$
\text{env}_{\gamma, \theta} : X \to [-\infty, +\infty] : y \mapsto \inf_{x \in X} \left\{ \theta(x) + \frac{1}{\gamma} D_{\| \cdot \|_2/2}(x, y) \right\}
$$

and its corresponding proximity operator

$$
\text{Prox}_{\gamma, \theta} : X \to X : y \mapsto \arg\min_{x \in X} \left\{ \theta(x) + \frac{1}{\gamma} D_{\| \cdot \|_2/2}(x, y) \right\},
$$

where $D_{\| \cdot \|_2/2} : (x, y) \mapsto \| x - y \|_2/2$. Moreau worked in a Hilbert space and with parameter $\gamma = 1$, and then, Attouch [1, 2] introduced the more general parameter $\gamma \in [0, +\infty[$; see also [5, Chapter 12].

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In 1967, Bregman [11] introduced the distance associated with a differentiable convex function $f$

$$D_f : X \times X \to [0, +\infty] : (x, y) \mapsto \begin{cases} f(x) - f(y) - \langle \nabla f(y), x - y \rangle & \text{if } y \in \text{int dom } f, \\ +\infty & \text{otherwise,} \end{cases}$$

which now bears his name. When $f$ is the energy, namely $f = \| \cdot \|_2^2$, it is clear that, for all $x, y \in X$, $D_f(x, y) = \| x - y \|_2^2$ is the Euclidean distance squared. When $f$ is not the energy, the distance may fail to be symmetric and so one is led to consider the left and right envelopes defined by

$$\leftarrow \text{env}_{\gamma, \theta} : X \to [-\infty, +\infty] : y \mapsto \inf_{x \in X} \left\{ \theta(x) + \frac{1}{\gamma} D_f(x, y) \right\}$$

and

$$\rightarrow \text{env}_{\gamma, \theta} : X \to [-\infty, +\infty] : x \mapsto \inf_{y \in X} \left\{ \theta(y) + \frac{1}{\gamma} D_f(x, y) \right\},$$

where the left and right proximity operators are defined as in (2), with $D_f$ in place of $D_{\| \cdot \|_2^2}$.

The asymptotic properties of the envelopes and proximity operators for differentiable $f$ with respect to the parameter $\gamma$ were explored in [7]. Bregman distances admit proximal point methods while also casting light on those constructed from the classical Moreau envelopes; see, for example, [4, 6, 14, 15, 17, 20, 21, 23, 28, 32], as well as [16, Chapter 6].

Recently, Burachik and Martínez-Legaz [18] have introduced two distances based on a representative function $h$ of a maximally monotone operator $T$:

$$D_T^{\circ, h}(x, y) := \inf_{v \in Ty} (h(x, v) - \langle x, v \rangle)$$

and

$$D_T^{\circ, h}(x, y) := \sup_{v \in Ty} (h(x, v) - \langle x, v \rangle).$$

When $T = \nabla f$ and $h(x, \nabla f(y)) = (f \oplus f^*)(x, \nabla f(y)) := f(x) + f^*(\nabla f(y))$ (which is the Fenchel–Young representative), these distances reduce (under mild domain conditions), to the Bregman distance $D_f(x, y)$. We therefore call these more general distances as the generalized Bregman distances (or GBDs).

Bregman proximal methods may be desirable for problems of high dimension. For certain objectives, using a different Bregman distance than the square norm reduces the computational complexity of computing a proximal update. For an example of reduction from $n^3$ to $n^2$ with SDP-representable constraints, see [22, 31]). Their work illustrates that a well selected Bregman distance should complement the problem structure. To that end, choices from the broader class of GBDs may turn out to be useful.

In [24], the authors devise a prox-Bregman technique for feature extraction in machine learning, with an application to gene expression problems, where outliers are present while data is noisy and sometimes missing. The latter properties are known to prevent other approaches—such as principal component analysis, cluster analysis, and polytomous logistic regression—from delivering useful results. In particular, the Bregman distance is built from the Boltzmann–Shannon entropy, because this choice naturally enforces nonnegativity constraints. This distance is equal almost everywhere to the GBD for the Fenchel–Young representative of the logarithm; we study here the broader GBD family for the logarithm, noting that more choices of Bregman distances may result in more efficient methodologies.
Bregman distances also have a prominent role in the solution of important variational problems. An example of this is its use for solving the equilibrium problem in Banach spaces, see, e.g., [27] as well as [17]. This is one reason we choose to work in the more general Banach space setting.

More recently, [13] has provided a framework of sufficient conditions for coercivity and supercoercivity of the left and right GBDs. It has also shown how such properties are useful for establishing coercivity of the sum of the distance together with a function in $\Gamma_0(X)$.

Hence, it is natural to use these new coercivity properties for carrying out a detailed analysis of the envelopes and proximity operators that are obtained when the GBD replaces the Bregman distance in (4a) and (4b). In particular, ours can be seen as a unifying analysis which includes Moreau envelopes as a particular case. The goal of the present work is to furnish this analysis. We characterize the domains of the envelopes. We then show under what conditions the GBD envelopes possess the same advantageous properties that we have when specializing to Bregman case, and under what conditions those properties may be lost. We will illustrate with the same GBDs used in [13]. We show, in particular, that the GBDs that arise from using the Fitzpatrick representative generically share the same desirable properties as their Bregman-generalizing counterparts. Such results will be important if some Fitzpatrick cases possess computational advantages over their Bregman counterparts or admit envelopes that are useful for examining existing algorithms through their dual characterizations.

Outline and contributions

In Section 2, we recall the generalized Bregman distances, along with some of their basic properties. We also recall the coercivity framework as well as the computed distances recently established in [13]. Moreover, we explain why these distances are important, since we use them to build the envelopes and proximity operators in our examples.

In Section 3, we introduce the left and right GBD envelopes and their associated proximity operators. We characterize the domains of the envelopes, and we provide sufficient conditions to guarantee the attainment of minimizers so that the proximity operators have nonempty images. The sufficient conditions rely upon the framework for coercivity established in [13].

In Section 4, we provide asymptotic results for the parameter $\gamma$. We then show how the results in the setting of GBDs vary from those we obtain more easily when specializing to Bregman distances. We illustrate all examples with both left and right versions, along with images of the envelope nets for a selection of $\gamma$ values. For all examples, we include three prototypical cases: the case of the distance constructed from the Fenchel–Young representative (which, under certain conditions, coincides with the classical Bregman distance), as well as the distances constructed from the smallest and largest members of the representative function set.

We conclude in Section 5, and we provide explicit forms for all of our computed examples and proximity operators in Appendix A.

2. Preliminaries

Given a nonempty subset $C$ of $X$, we denote by $\iota_C : X \to ]-\infty, +\infty]$ the indicator function of $C$, i.e., $\iota_C(x) := 0$ when $x \in C$ and $\iota_C(x) := +\infty$ otherwise. We will denote by $\text{int}(C)$ the interior of $C$ and by $\overline{C}$ the closure of $C$.

Let $f : X \to ]-\infty, +\infty]$. The domain of $f$ is defined by $\text{dom } f := \{ x \in X : f(x) < +\infty \}$,
the lower level set of $f$ at height $\xi \in \mathbb{R}$ by $\text{lev}_{\leq \xi} f := \{x \in X : f(x) \leq \xi\}$, and the epigraph of $f$ by $\text{epi} f := \{(x, \rho) \in X \times \mathbb{R} : f(x) \leq \rho\}$. We say that $f$ is proper if $\text{dom} f \neq \emptyset$ and lower semicontinuous (lsc) at $\bar{x}$ if $f(\bar{x}) \leq \lim \inf_{x \to \bar{x}} f(x)$. Unless specifically mentioned, these concepts are with respect to the strong (norm) topology. The function $f$ is said to be convex if

$$\forall x, y \in X, \forall \lambda \in [0, 1], \quad f((1 - \lambda)x + \lambda y) \leq (1 - \lambda)f(x) + \lambda f(y);$$

coercive if $\lim_{\|x\| \to +\infty} f(x) = +\infty$; and supercoercive if $\lim_{\|x\| \to +\infty} f(x)/\|x\| = +\infty$.

For a proper function $f : X \to ]-\infty, +\infty]$, its $\varepsilon$-subdifferential ($\varepsilon \in \mathbb{R}_+$) is the point-to-set mapping $\partial_{\varepsilon} f : X \nrightarrow X^*$ given by

$$\partial_{\varepsilon} f(x) := \{v \in X^* : \forall y \in X, \langle y, v \rangle \leq f(y) - f(x) + \varepsilon\},$$

its subdifferential is $\partial f := \partial_0 f$, and its Fenchel conjugate is the function $f^* : X^* \to ]-\infty, +\infty]$ given by

$$f^*(v) := \sup_{x \in X}\{\langle x, v \rangle - f(x)\}.$$

From the definition, we directly obtain the Fenchel–Young inequality

$$\forall (x, v) \in X \times X^*, \quad f(x) + f^*(v) \geq \langle x, v \rangle$$

and for $\varepsilon \in \mathbb{R}_+$, we also have the following well-known characterization of $\partial_{\varepsilon} f$:

$$f(x) + f^*(v) \leq \langle x, v \rangle + \varepsilon \iff v \in \partial_{\varepsilon} f(x).$$

Given a point-to-set operator $T : X \nrightarrow X^*$, its domain is $\text{dom} T := \{x \in X : Tx \neq \emptyset\}$, its range is $\text{ran} T := T(X)$, and its graph is $\mathcal{G}(T) := \{(x, x^*) \in X \times X^* : x^* \in Tx\}$. We say that $T$ is maximally monotone if

$$(x, u) \in \mathcal{G}(T) \iff \forall (y, v) \in \mathcal{G}(T), \quad \langle x - y, u - v \rangle \geq 0.$$  

More properties and facts on maximally monotone operators can be found in [5, 16].

2.1. Representative functions

Let $S : X \nrightarrow X^*$ be a maximally monotone operator. Following [18, Definition 2.3], we say that a function $h : X \times X^* \to ]-\infty, +\infty]$ represents $S$ if it satisfies the following conditions:

(a) $h$ is convex and norm $\times$ weak* lower semicontinuous in $X \times X^*$ (the weak* topology in $X^*$ is the smallest topology that makes continuous the linear functionals induced by $x \in X$).

(b) $\forall (x, v) \in X \times X^*$, $h(x, v) \geq \langle x, v \rangle$.

c) $h(x, v) = \langle x, v \rangle \iff (x, v) \in \mathcal{G}(S)$.

In this situation, we denote $h \in \mathcal{H}(S)$ and call $\mathcal{H}(S)$ the Fitzpatrick family of $S$. We will make use, in particular, of three prototypical members of $\mathcal{H}(S)$. These are as follows.

(i) The Fitzpatrick function of $S$, denoted as $F_S$, is defined by

$$F_S(x, y) := \sup_{(z, w) \in \mathcal{G}(S)} \{\langle z - x, y - w \rangle + \langle x, y \rangle\}.$$  

It is well known that $F_S$ is the smallest member of $\mathcal{H}(S)$ in the sense that $F_S \leq h$ for any $h \in \mathcal{H}(S)$, see [29];
Proposition 2.1 (GBDs specialize to Bregman distances).

We recall this result in the following proposition.

Young representative is used [18, Proposition 3.5], under mild domain conditions illuminated in [13, Proposition 2.2].

It is known that the GBDs specialize to the Bregman distances in the case where the Fenchel–Young representative function is everywhere equal. However, if \( f \) is the Boltzmann–Shannon (see (34)), then \( \partial f = \emptyset \), and the two kinds of distances fail to be equal on the set \( \{(0, y) \mid y > 0\} \) (see [13] for more details).

As a motivation for considering these new distances, we provide below connections between our generalized distances and solutions of variational problems. First, we consider the problem of finding zeros of a sum of operators, and second, the problem of minimizing a DC (difference of convex) function. In both cases, we need \( S \) different than \( T \), with an operator \( T \) which may not be monotone.
Remark 2.2. In the next proposition, we use the Eberlein–Šmulian theorem, which states that a subset of a Banach space is weakly compact if and only if it is weakly sequentially compact (see [26, Chapter III, page 18]). We also use the fact that, if $X$ is a reflexive Banach space and a map $V : X \rightarrow X^*$ is locally bounded at a point in the interior of its domain, then there is a neighbourhood of that reference point which is norm-closed and bounded, and hence weakly compact (by Bourbaki–Alaoglu’s theorem and reflexivity). We then use the Eberlein–Šmulian theorem to deduce that the given neighbourhood is in fact weakly sequentially compact.

Given $h \in \mathcal{H}(S)$, the enlargement $S^h_\varepsilon$ of $S$ is defined by

$$ S^h_\varepsilon x := \{ v \in X^* : h(x,v) - \langle x,v \rangle \leq \varepsilon \}. \tag{17} $$

More details on $S^h_\varepsilon$ can be found, e.g., in [16, 19]. We will show that the generalized distances can be used to define approximate solutions of problem

$$ \text{find } x \in X \text{ such that } 0 \in S^h_\varepsilon x + Tx. \tag{18} $$

The proof of the next result follows closely the one in [18, Proposition 3.7], but we include it here for the convenience of the reader.

**Proposition 2.2.** Let $X$ be a reflexive Banach space. Suppose that $S : X \rightrightarrows X^*$ is a maximally monotone operator and $T : X \rightrightarrows X^*$ is a point-to-set operator. Fix any $h \in \mathcal{H}(S)$, $\varepsilon \in \mathbb{R}_+$, and $x \in X$. Consider the following statements.

(a) $0 \in S^h_\varepsilon x + Tx$.
(b) $D^h_{-T}(x,x) \leq \varepsilon$.

Then (a) $\implies$ (b). Moreover, if dom $T$ is open and $T$ is locally bounded with weakly closed images, then the two statements are equivalent.

**Proof.** (a) $\implies$ (b): Note that (a) implies the existence of $w \in (-Tx) \cap S^h_\varepsilon x$. By definition of $D^h_{-T}$, we have

$$ D^h_{-T}(x,x) = \inf_{w \in -Tx} h(x,v) - \langle x,v \rangle \leq h(x,w) - \langle x,w \rangle \leq \varepsilon, \tag{19} $$

where we used the fact that $w \in S^h_\varepsilon x$ (see (17)) in the rightmost inequality.

(b) $\implies$ (a): It follows from (b) that $D^h_{-T}(x,x) < +\infty$, and so $x \in \text{dom}(-T) = \text{dom} T$. Now, assume that dom $T$ is open and $T$ is locally bounded with weakly closed images. Then, the same properties hold for $-T$ too. Consequently, the set $-Tx$ is contained in a neighbourhood which is norm-closed and bounded. Using now Remark 2.2, we have that the set $-Tx$ is contained in a neighbourhood which is weakly sequentially compact. Using also the assumption that $h(x, \cdot)$ is weakly continuous, we conclude that the infimum in the expression for $D^h_{-T}(x,x)$ must be attained at some point in $-Tx$. Namely, there exists $v \in -Tx$ such that

$$ h(x,v) - \langle x,v \rangle = D^h_{-T}(x,x) \leq \varepsilon, \tag{20} $$

which implies that $v \in S^h_\varepsilon x$. Since $-v \in Tx$, we get (a). ■

Note that, if $x$ satisfies condition (a) in Proposition 2.2, it can be seen as an approximate solution of (18). Indeed, by taking $\varepsilon = 0$, condition (a) becomes (18). In the latter case (i.e., when $\varepsilon = 0$), condition (b) in Proposition 2.2 can be seen as a necessary optimality condition for problem (18). The condition becomes sufficient when $T$ verifies additional hypotheses.
We show next that an optimality condition for minimizing a DC function can be expressed by means of the sharp distance. In the proposition below, the equivalence between statements (a) and (b) is well known in finite dimensional spaces (see, e.g. [30, Theorem 3.1]). The analogous result in Banach spaces is hard to track down, so we decided to include its proof here.

**Proposition 2.3.** Let \( f: X \to ]-\infty, +\infty] \) and \( g: X \to \mathbb{R} \) be proper lower semicontinuous convex functions. Then, the following statements are equivalent

(a) \( x \) is a global minimum of \( f - g \) on \( X \).

(b) For all \( \varepsilon \in \mathbb{R}_+ \), \( \partial_\varepsilon g(x) \subseteq \partial_\varepsilon f(x) \).

(c) For all \( \varepsilon \in \mathbb{R}_+ \), \( D_{\partial_\varepsilon g}^f f^* (x, x) \leq \varepsilon \).

**Proof.**

(a) \( \Rightarrow \) (b): Assume that \( x \) is a global minimum of \( f - g \) on \( X \). Then, for all \( y \in X \),

\[
( f(x) - g(x) ) \leq ( f(y) - g(y) ),
\]

and so \( g(y) - g(x) \leq f(y) - f(x) \). Now, let any \( \varepsilon \in \mathbb{R}_+ \) and any \( v \in \partial_\varepsilon g(x) \). We have, for all \( y \in X \),

\[
\langle y - x, v \rangle + \varepsilon \leq g(y) - g(x) \leq f(y) - f(x),
\]

which implies that \( v \in \partial_\varepsilon f(x) \). Therefore, \( \partial_\varepsilon g(x) \subseteq \partial_\varepsilon f(x) \).

(b) \( \Rightarrow \) (a): Assume that \( x \) is not a global minimum of \( f - g \) on \( X \). That is, there exists \( \overline{x} \in X \) such that \( f(\overline{x}) - g(\overline{x}) < f(x) - g(x) \). Then, we can pick \( 0 < \varepsilon_0 < [g(\overline{x}) - g(x)] - [f(\overline{x}) - f(x)] \) and \( u \in \partial_\varepsilon g(\overline{x}) \) (see [36, Theorem 2.4.4(iii)]). By definition, for all \( y \in X \),

\[
\langle y - \overline{x}, u \rangle \leq g(y) - g(\overline{x}) + \varepsilon_0,
\]

which can be written as

\[
\langle y - x, u \rangle \leq g(y) - g(x) + \varepsilon,
\]

where \( \varepsilon := g(x) - g(\overline{x}) + \varepsilon_0 - \langle x - \overline{x}, u \rangle \geq 0 \). Since \( y \in X \) is arbitrary, the inequality above yields \( u \in \partial_\varepsilon g(x) \). On the other hand,

\[
\langle \overline{x} - x, u \rangle = g(\overline{x}) - g(x) - \varepsilon_0 + \varepsilon > f(\overline{x}) - f(x) + \varepsilon,
\]

which implies that \( u \notin \partial_\varepsilon f(x) \). Hence, (b) does not hold. We deduce that if (b) holds, then so does (a).

We have shown the equivalence between (a) and (b). To see the one between (b) and (c), we note that

\[
D_{\partial_\varepsilon g}^f f^* (x, x) = \sup_{v \in \partial_\varepsilon g(x)} \left( (f \oplus f^*)(x, v) - \langle x, v \rangle \right) = \sup_{v \in \partial_\varepsilon g(x)} (f(x) + f^*(v) - \langle x, v \rangle). \tag{25}
\]

Fix any \( \varepsilon \in \mathbb{R}_+ \), the above expression and characterization (10) of \( \partial_\varepsilon f \) imply that

\[
D_{\partial_\varepsilon g}^f f^* (x, x) \leq \varepsilon \iff \forall v \in \partial_\varepsilon g(x), \quad f(x) + f^*(v) - \langle x, v \rangle \leq \varepsilon \tag{26a}
\]

\[
\iff \forall v \in \partial_\varepsilon g(x), \quad v \in \partial_\varepsilon f(x) \tag{26b}
\]

\[
\iff \partial_\varepsilon g(x) \subseteq \partial_\varepsilon f(x) \tag{26c}
\]

which completes the proof.

We will make use of the following lemma to simplify our analysis of the asymptotic behaviour in Section 4.
Lemma 2.1. Let $f \in \Gamma_0(X)$ and suppose that $h \in \mathcal{H}(\partial f)$ satisfies
\[
\forall (x, v) \in \text{dom } f \times \text{ran } \partial f, \quad h(x, v) \leq (f \oplus f^*)(x, v) = f(x) + f^*(v).
\] (27)
Then the following hold:

(i) $\text{dom } D^{h,h}_{\partial f} = \text{dom } \partial f \times \text{dom } \partial f$.

(ii) $\text{dom } \partial f \times \text{int}(\text{dom } \partial f) \subset \text{dom } D^{h,h}_{\partial f} \subseteq \text{dom } \partial f \times \text{dom } \partial f$. Consequently, when $\text{dom } \partial f$ is open, then $\text{dom } D^{h,h}_{\partial f} = \text{dom } \partial f \times \text{dom } \partial f$.

Proof. Let $(x, y) \in \text{dom } \partial f \times \text{dom } \partial f$. It follows from the assumption on $h$ and Proposition 2.1 that
\[
D^{h,h}_{\partial f}(x, y) \leq D^{*,f \oplus f^*}_{\partial f}(x, y) = D^*_f(x, y),
\] (28)
where $* \in \{b, *\}$.

(i): By definition, we have that $\text{dom } D^{h,h}_{\partial f} \subseteq \text{dom } \partial f \times \text{dom } \partial f$. Hence, it is enough to prove the opposite inclusion. Indeed, fix any $v_0 \in \partial f(y)$. By (28) for $* = b$ and then by Cauchy–Schwarz inequality, we have that
\[
D^{h,h}_{\partial f}(x, y) \leq D^b_f(x, y) = f(x) - f(y) + \inf_{v \in \partial f(y)} \langle y - x, v \rangle
\]
\[
\leq f(x) - f(y) + \|y - x\| \cdot \|v_0\| < +\infty,
\] (29b)
Here, the final inequality follows from the fact that $x, y \in \text{dom } \partial f \subseteq \text{dom } f$. Thus $(x, y) \in \text{dom } D^{h,h}_{\partial f}$, and we deduce that $\text{dom } D^{h,h}_{\partial f} = \text{dom } \partial f \times \text{dom } \partial f$.

(ii): As in part (i), we always have that $\text{dom } D^{h,h}_{\partial f} \subseteq \text{dom } \partial f \times \text{dom } \partial f$. For the leftmost inclusion, assume that $(x, y) \in \text{dom } \partial f \times \text{int}(\text{dom } \partial f)$. Since $y \in \text{int}(\text{dom } \partial f)$ and $\partial f$ is maximally monotone, the set $\partial f(y)$ is bounded, so there exists a constant $M(y) \geq 0$ such that $\|v\| \leq M(y)$ for every $v \in \partial f(y)$. Altogether, (28) for $* = h$ and Cauchy–Schwarz inequality give
\[
D^{*,h}_{\partial f}(x, y) \leq D^h_f(x, y) = f(x) - f(y) + \sup_{v \in \partial f(y)} \langle y - x, v \rangle
\]
\[
\leq f(x) - f(y) + \|y - x\| \cdot M(y) < +\infty,
\] (30b)
because $x, y$ are fixed. This proves both inclusions. The last statement in (ii) follows directly from the first one.

Remark 2.3. The rightmost inclusion in Lemma 2.1(ii) might be strict, in contrast to part (i). Let $B := \{(a, b) \in \mathbb{R}^2 : a^2 + b^2 \leq 1\}$ the unit ball in two dimensions and consider $f := \iota_B$ the indicator function of the unit ball. Take $y = (1, 0) \in B$, and any $x = (x_1, x_2) \in B$ such that $x_1 < 1$ (i.e., any $B \ni x \neq y$). Then $\partial f(y) = \{(t, 0) : t \geq 0\}$ and $f(x) = f(y) = 0$, thus
\[
D^{*,f \oplus f^*}_{\partial f}(x, y) = \sup_{t \geq 0} \langle y - x, ty \rangle = (1 - x_1) \sup_{t \geq 0} t = +\infty.
\] (31)
Therefore, $(x, y) \notin \text{dom } D^{*,f \oplus f^*}_{\partial f}$ for all $x \neq y$.

2.3. Examples of important generalized Bregman distances

For our examples in this section, $X = X^* = \mathbb{R}$ and, $T = S = \partial f$ is point-to-point on $\text{int dom } f$ in which case we simply write $D^h$ for a specific choice of $h \in \mathcal{H}(\partial f)$ (not to be confused with $D_f$, the classical Bregman distance for $f$). In these cases, we will refer to the representative function used by its name. Specifically,
When \( h = F_S \) is the Fitzpatrick function for a maximally monotone operator \( S \), we will write \( D_{F_S} \).

(ii) When \( h = \sigma_S \), the largest member of \( \mathcal{H}(S) \), we will write \( D_{\sigma_S} \).

(iii) When \( h = f \oplus f^* \in \mathcal{H}(\partial f) \) for \( f \in \Gamma_0(X) \) is the Fenchel–Young representative, we will denote this by \( D_{f \oplus f^*} \).

Remark 2.4 (The lower closed distance). The function \( D_{\ast,h}^h(\cdot,y) \) may not be lower semicontinuous at \( x \in \overline{\text{dom}} \partial f \setminus \text{dom} \partial f \). Additionally, for \( y \notin \text{int dom}(T) \), the distance may not be lower semicontinuous with respect to the right variable either. For more details on the semicontinuity properties of the GBDs, see [18, section 3]. For these reasons, [13] introduced the lower closed GBD \( \overline{D}_{T}^{\ast,h} \) defined by

\[
\text{epi} \overline{D}_{T}^{\ast,h} = \overline{\text{epi}} D_{T}^{\ast,h},
\]

where, as before, \( \ast \in \{ \flat, \sharp \} \). The lower closed distances \( \overline{D}_{F_S}^{\ast,h}, \overline{D}_{\sigma_S}^{\ast,h}, \text{ and } \overline{D}_{f \oplus f^*}^{\ast,h} \) are defined analogously (with \( D_{F_S}, D_{\sigma_S} \) and \( D_{f \oplus f^*} \) as in (i)–(iii) above). For all our computed examples, in the cases when \( \overline{D}^h \) and \( D^h \) do not agree, we will compute with \( \overline{D}^h \) so as to have a lower semicontinuous distance.

The authors in [7, 13] illustrated their findings with energy, whose Bregman distance specializes to the Moreau case and the Boltzmann–Shannon entropy, whose importance we will soon recall. Naturally, we will illustrate our results about envelopes and proximity operators using the GBDs associated with these operators that were computed in [13]. They are as follows.

Example 2.1 (Energy). In the case where \( f : x \mapsto \frac{1}{2}x^2 \) is the energy, we have \( \partial f = \text{Id} \). The distances constructed from the smallest and biggest members of \( \mathcal{H}(\text{Id}) \) are

\[
D_{\text{Id}}^{\ast,h}(x,y) = \frac{1}{4}(x-y)^2 \quad \text{and} \quad D_{\text{Id}}^{\sigma,h} = \iota_{\mathcal{G}(\text{Id})}.
\]

Already from this example, we see that we should not expect all asymptotic properties of Bregman envelopes to extend to GBD envelopes, because envelopes associated with the distance \( D_{\text{Id}}^{\sigma,h} \) will always be vacuously equal to the function being regularized, while their associated proximity operators will vacuously be equal to \( \text{Id} \).

Example 2.2 (Kullback–Leibler divergence and GBD \( \overline{D}_{\text{ent}}^{\text{int} \oplus \text{ent}^*} \)). The (negative) Boltzmann–Shannon entropy is defined as

\[
\text{ent} : \mathbb{R} \to ]-\infty, +\infty] : x \mapsto \begin{cases} x \log x - x & \text{if } x > 0, \\ 0 & \text{if } x = 0, \\ +\infty & \text{otherwise}. \end{cases}
\]

The Boltzmann–Shannon entropy is particularly important and natural to consider, because its derivative is \( \log \), its conjugate is \( \text{ent}^* = \exp \), and its associated Bregman distance is the Kullback–Leibler divergence,

\[
D_{\text{ent}} : (x,y) \mapsto \begin{cases} x(\log(x) - \log(y)) - x + y & \text{if } y > 0, \\ y & \text{if } y > 0 \text{ and } x = 0, \\ +\infty & \text{otherwise}, \end{cases}
\]
which is frequently used as a measure of distance between positive vectors in information theory, statistics, and portfolio selection. The GBD associated with the Fenchel–Young representative \( \text{ent} \oplus \text{ent}^* \in \mathcal{H}(\log) \) is

\[
\mathcal{D}_{\text{ent} \oplus \text{ent}^*} : (x, y) \mapsto \begin{cases} 
  x(\log(x) - \log(y)) - x + y & \text{if } x, y > 0, \\
  +\infty & \text{otherwise}.
\end{cases} \tag{36}
\]

Thus, it may be seen that the Bregman distance of the Boltzmann–Shannon entropy is the special case of the GBD for the Fenchel–Young representative of the logarithm function, except on the set \( \text{dom } f \setminus \text{dom } \partial f \times \text{dom } \partial f = \{0\} \times ]0, +\infty[ \) (see Proposition 2.1 and Remark 2.4). Its lower closure is given by

\[
\overline{\mathcal{D}}_{\text{ent} \oplus \text{ent}^*} : (x, y) \mapsto \begin{cases} 
  x(\log(x) - \log(y)) - x + y & \text{if } y > 0, x \geq 0, \\
  0 & \text{if } y = x = 0, \\
  +\infty & \text{otherwise}.
\end{cases} \tag{37}
\]

and is shown in Figure 1b. Hence, this new distance allows us to extend the domain of the classical Bregman distance to the boundary points.

**Example 2.3 (Kullback–Leibler divergence and GBD \( \mathcal{D}_{\log}^{F} \)).** The GBD constructed with the Fitzpatrick representative is

\[
\mathcal{D}_{\log}^{F} : \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow [0, +\infty] \tag{38}
\]

where \( \mathcal{W} \) is the principal branch of the Lambert \( \mathcal{W} \) function. The above expression simplifies, except on the set \( \{0\} \times [0, +\infty[ \), to the lower closed version

\[
\overline{\mathcal{D}}_{\log}^{F} : \mathbb{R}_+ \times \mathbb{R}_+ \rightarrow [0, +\infty] \tag{39}
\]

\[
(x, y) \mapsto \begin{cases} 
  +\infty & \text{if } x < 0 \text{ or } y < 0 \text{ or } (x > 0 \text{ and } y = 0), \\
  ye^{-1} & \text{if } x = 0 \text{ and } y \geq 0, \\
  x \left( \mathcal{W} \left( \frac{xe}{y} \right) + \frac{1}{\mathcal{W}(\frac{x}{y})} - 2 \right) & \text{otherwise}.
\end{cases}
\]
This distance is shown in Figure (1a). Taking the closure of the epigraph of $\overline{D}^{F_{\log}}(0, y) = ye^{-1}$, the difference we see in (39). We opt to use the latter lower semicontinuous version of the distance in our later examples of proximity operators and envelopes. For information on the computation of $F_{\log}$ and $D^{F_{\log}}$, see [9, Example .17.6] and [13, Example 3.2], respectively.

**Example 2.4 (Kullback–Leibler divergence and GBD $D^{\sigma_{\log}}$).** The GBD constructed with the biggest member of $H(\log)$ is

$$D^{\sigma_{\log}} : (x, y) \mapsto -x \log(y) + \begin{cases} x \log(x) & \text{if } \log(y) \leq \log(x), \\ +\infty & \text{otherwise}, \end{cases}$$

which may be recognized as equal, except at the point $(0, 0)$, to the lower closed version

$$D^{\sigma_{\log}} : (x, y) \mapsto \begin{cases} x \log(x) - x \log(y) & \text{if } 0 < y \leq x, \\ 0 & \text{if } x = y = 0, \\ +\infty & \text{otherwise}, \end{cases}$$

which is shown in Figure (1c).

### 3. Envelopes and proximity operators

We next define formally the envelopes and the proximity operators.

**Definition 3.1.** Given $\theta : X \to ]-\infty, +\infty]$ and $\gamma \in \mathbb{R}^{++}$, the left and right $D^{\tau,h}_{\star}$-envelopes of $\theta$ with parameter $\gamma$ are respectively defined by

$$\mathcal{E}_{\gamma, b}^{\star,h} : X \to ]-\infty, +\infty] : y \mapsto \inf_{x \in X} \left( \theta(x) + \frac{1}{\gamma} D^{\star,h}_{\tau}(x, y) \right)$$

and

$$\mathcal{E}_{\gamma, b}^{\star,h} : X \to ]-\infty, +\infty] : x \mapsto \inf_{y \in X} \left( \theta(y) + \frac{1}{\gamma} D^{\star,h}_{\tau}(x, y) \right).$$

The left and right proximity operator of $\theta$ with parameter $\gamma$ are respectively defined by

$$\mathcal{P}_{\gamma, b}^{\star,h} : X \Rightarrow X : y \mapsto \arg\min_{x \in X} \left( \theta(x) + \frac{1}{\gamma} D^{\star,h}_{\tau}(x, y) \right)$$

and

$$\mathcal{P}_{\gamma, b}^{\star,h} : X \Rightarrow X : x \mapsto \arg\min_{y \in X} \left( \theta(y) + \frac{1}{\gamma} D^{\star,h}_{\tau}(x, y) \right).$$

As before, the symbol $\star$ can be either $\flat$ or $\sharp$. When $T$ is point to point, we remove the symbol $\star$. When the symbol $\dagger$ appears next to the name of the representative function with the envelope or proximity operator, it is understood that the distance being used is the closed GBD $\overline{D}^{\tau,h}_{\star}$. When the Bregman distance (15a) or (15b) is used, we remove the name of the representative function in the envelopes and proximity operators.

**Remark 3.1 (A selection operator for the proximity operator).** We will find it useful to employ a selection map for the proximity operators.

(i) If $\mathcal{E}_{\gamma, \dagger}^{\star,h}(y) \in \overline{D}_{\gamma, \dagger}^{\star,h}(y)$, then

$$\mathcal{E}_{\gamma, \dagger}^{\star,h}(y) = \theta(\mathcal{E}_{\gamma, \dagger}^{\star,h}(y)) + \frac{1}{\gamma} D_{\tau}^{\star,h}(\mathcal{E}_{\gamma, \dagger}^{\star,h}(y), y) \geq \theta(\mathcal{E}_{\gamma, \dagger}^{\star,h}(y)).$$

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(ii) If \( \overrightarrow{s}_{\gamma, \theta}^{*, h}(x) \in \overrightarrow{\partial}_{\gamma, \theta}(x) \), then
\[
\overrightarrow{\text{env}}_{\gamma, \theta}(x) = \theta(\overrightarrow{s}_{\gamma, \theta}^{*, h}(x)) + \frac{1}{\gamma} \partial_{T}^{*, h}(x, \overrightarrow{s}_{\gamma, \theta}^{*, h}(x)) \geq \theta(\overrightarrow{s}_{\gamma, \theta}^{*, h}(x)).
\] (45)

Sufficient conditions for the images of the proximity operators to be nonempty will be provided in Propositions 3.4 and 3.5; we only use selection operators in such cases.

**Example 3.1 (Energy).** Let \( f \) be the energy and \( \theta : x \mapsto |x - 1/2| \). In this case, \( \partial f = \text{Id} \), and the distances \( \mathcal{D}^{\text{Fid}} \) and \( \mathcal{D}^{\text{pdf}} \) are given in Example 2.1 and are both lsc. It is straightforward to determine that their corresponding envelopes and proximity operators are given by:

(i) \( \mathcal{D}^{\text{Fid}} \): the corresponding GBD envelopes (both left \( \overrightarrow{\text{env}}_{\gamma, \theta}^{\text{Fid}} \) and right \( \overrightarrow{\text{env}}_{\gamma, \theta}^{\text{Fid}} \)) are equal to the Moreau envelope with parameter \( 2\gamma \), and the corresponding proximity operators are equal to the respective Moreau proximity operators with parameter \( 2\gamma \).

(ii) \( \mathcal{D}^{\text{pdf}} \): the left and right proximity operators are both necessarily Id, and our left and right envelopes for \( \theta \) are exactly equal to \( \theta \) for both the right and left envelopes, a fact that would hold true with any other choice of \( \theta \).

In the following result, part (i) extends [7, Proposition 2.1] and its proof is the same as the one in [5, Proposition 12.22(i)]. Parts (ii) and (iii) are new and establish relationships between the domain of left and right envelopes with those of \( S \) and \( T \).

**Proposition 3.1.** Let \( \theta : X \mapsto ]-\infty, +\infty[ \) and let \( \gamma, \mu \in \mathbb{R}_{++} \). Then the following hold:

(i) \( \overrightarrow{\text{env}}_{\mu, \gamma, \theta}^{*, h} = \gamma \overrightarrow{\text{env}}_{\mu, \gamma, \theta}^{*, h} \) and \( \overrightarrow{\text{env}}_{\mu, \gamma, \theta}^{*, h} = \gamma \overrightarrow{\text{env}}_{\mu, \gamma, \theta}^{*, h} \).

(ii) \( \text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} \subseteq \text{dom} T \) and \( \text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} \subseteq \text{dom} S \). Moreover,
\[
\text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} = \bigcup_{x \in \text{dom} \theta, \epsilon \in \mathbb{R}_{+}} T^{-1}(S_{\epsilon}^{h}x) \quad \text{and}
\]
\[
\text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} = \left\{ x \in X : \text{dom} \theta \cap \bigcup_{\epsilon \in \mathbb{R}_{+}} T^{-1}(S_{\epsilon}^{h}x) \neq \emptyset \right\} .
\] (46a, 46b)

(iii) If \( \text{dom} S \cap \text{dom} \theta \neq \emptyset \) and \( (\text{dom} \theta \cap \text{dom} S) \times \text{dom} T \subseteq \text{dom} \mathcal{D}^{*, h} \), then \( \text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} = \text{dom} T \).

If \( \text{dom} T \cap \text{dom} \theta \neq \emptyset \) and \( \text{dom} S \times (\text{dom} \theta \cap \text{dom} S) \subseteq \text{dom} \mathcal{D}^{*, h} \), then \( \text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} = \text{dom} S \).

**Proof.** (i): This is straightforward from the definition.

(ii): We observe that
\[
y \in \text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} \iff \inf_{x \in X} \left( \theta(x) + \frac{1}{\gamma} \mathcal{D}^{*, h}_T(x, y) \right) = \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h}(y) < +\infty \] (47a)
\[
\iff \exists x \in X, \quad \theta(x) + \frac{1}{\gamma} \mathcal{D}^{*, h}_T(x, y) < +\infty \] (47b)
\[
\iff \exists x \in \text{dom} \theta, \quad \mathcal{D}^{*, h}_T(x, y) < +\infty, \] (47c)

since it always holds that \( \theta(x) > -\infty \) and \( \mathcal{D}^{*, h}_T(x, y) \geq 0 \). On the one hand, (47c) implies that \( y \in \text{dom} T \), and hence \( \text{dom} \overrightarrow{\text{env}}_{\gamma, \theta}^{*, h} \subseteq \text{dom} T \). To prove the first equality in (ii), note that, by definition of \( \mathcal{D}^{*, h}_T \),
\[
\mathcal{D}^{*, h}_T(x, y) < +\infty \iff \sup_{v \in Ty} (h(x, v) - \langle x, v \rangle) < +\infty \] (48a)
Then the following hold:

\[ \exists \varepsilon \in \mathbb{R}_+, \; \forall v \in T y, \; h(x, v) - \langle x, v \rangle \leq \varepsilon \quad (48h) \]

\[ \exists \varepsilon \in \mathbb{R}_+, \; T y \subseteq S^h_{\varepsilon} x \quad (48c) \]

\[ y \in \bigcup_{\varepsilon \in \mathbb{R}_+} T^{-1}(S^h_{\varepsilon} x). \quad (48d) \]

Combining with (47) yields

\[ \text{dom } \overline{\text{env}}^{x,h}_{\gamma,\theta} = \bigcup_{x \in \text{dom } \theta, \; \varepsilon \in \mathbb{R}_+} T^{-1}(S^h_{\varepsilon} x). \quad (49) \]

The proof for the right envelope is analogous.

(iii): We will only prove the first claim because the second one is similar. In view of (ii), it suffices to prove that \( \text{dom } T \subseteq \text{dom } \overline{\text{env}}^{x,h}_{\gamma,\theta} \). Let \( y \in \text{dom } T \). By assumption, there exists \( x_0 \in \text{dom } S \cap \text{dom } \theta \).

Then \((x_0, y) \in (\text{dom } S \cap \text{dom } \theta) \times \text{dom } T \subseteq \text{dom } D_T^{x,h} \) which gives \( D_T^{x,h}(x_0, y) < +\infty \). Using (47), we obtain that \( y \in \text{dom } \overline{\text{env}}^{x,h}_{\gamma,\theta} \). This completes the proof.

The following proposition compares minimum values of the envelopes with those of the reference function \( \theta \) over the domains of \( S \) and \( T \).

**Proposition 3.2.** Let \( \theta : X \to ]-\infty, +\infty] \), \( x \in \text{dom } S \), \( y \in \text{dom } T \), and \( \gamma, \mu \in \mathbb{R}_+ \) with \( \gamma \leq \mu \).

Then the following hold:

(i) Suppose that \( \text{dom } S \cap \text{dom } \theta \neq \emptyset \) and that \( T z \subseteq S z \) for all \( z \in \text{dom } T \). Then

\[ \inf \theta(\text{dom } S) \leq \overline{\text{env}}^{x,h}_{\mu,\theta}(y) \leq \overline{\text{env}}^{x,h}_{\gamma,\theta}(y) \leq \theta(y) \quad (50a) \]

\[ \text{and } \inf \theta(\text{dom } S) \leq \overline{\text{env}}^{x,h}_{\mu,\theta}(y) \leq \overline{\text{env}}^{x,h}_{\gamma,\theta}(y) \leq \overline{\text{env}}^{x,h}_{\gamma,\theta}(y) \leq \theta(y). \quad (50b) \]

Consequently, \( \inf \theta(\text{dom } S) \leq \overline{\text{env}}^{x,h}_{\gamma,\theta}(X) \leq \inf \theta(\text{dom } T) \), with equality throughout when \( \text{dom } S \subseteq \text{dom } T \). Moreover, there exist \( \alpha, \beta \in [\inf \theta(\text{dom } S), \theta(y)] \) such that

\[ \overline{\text{env}}^{x,h}_{\gamma,\theta}(y) \downarrow \alpha \text{ as } \gamma \uparrow +\infty \text{ and } \overline{\text{env}}^{x,h}_{\gamma,\theta}(y) \uparrow \beta \text{ as } \gamma \downarrow 0. \quad (51) \]

(ii) Suppose that \( \text{dom } T \cap \text{dom } \theta \neq \emptyset \) and that \( T z \subseteq S z \) for all \( z \in \text{dom } S \). Then

\[ \inf \theta(\text{dom } T) \leq \overline{\text{env}}^{x,h}_{\mu,\theta}(x) \leq \overline{\text{env}}^{x,h}_{\gamma,\theta}(x) \leq \theta(x) \quad (52a) \]

\[ \text{and } \inf \theta(\text{dom } T) \leq \overline{\text{env}}^{x,h}_{\mu,\theta}(x) \leq \overline{\text{env}}^{x,h}_{\gamma,\theta}(x) \leq \overline{\text{env}}^{x,h}_{\gamma,\theta}(x) \leq \theta(x). \quad (52b) \]

Consequently, \( \inf \theta(\text{dom } T) \leq \inf \overline{\text{env}}^{x,h}_{\gamma,\theta}(X) \leq \inf \theta(\text{dom } S) \), with equality throughout when \( \text{dom } T \subseteq \text{dom } S \). Moreover, there exist \( \alpha, \beta \in [\inf \theta(\text{dom } T), \theta(x)] \) such that

\[ \overline{\text{env}}^{x,h}_{\gamma,\theta}(x) \downarrow \alpha \text{ as } \gamma \uparrow +\infty \text{ and } \overline{\text{env}}^{x,h}_{\gamma,\theta}(x) \uparrow \beta \text{ as } \gamma \downarrow 0. \quad (53) \]

**Proof.** The proof for the right envelopes follows the same steps as those for the left ones, and hence, the details are omitted. The assumption of \( T z \subseteq S z \) for all \( z \in \text{dom } T \), together with [18, Remark 3.3(c)], implies that

\[ \forall z \in \text{dom } T, \quad D_T^{x,h}(z, z) = 0. \quad (54) \]

As \( \mu \geq \gamma > 0 \), we have that, for all \( x \in \text{dom } S \),

\[ \theta(x) \leq \theta(x) + \frac{1}{\mu} D_T^{x,h}(x, y) \leq \theta(x) + \frac{1}{\gamma} D_T^{x,h}(x, y). \quad (55) \]
Taking the infimum over \( x \in \text{dom } S \), with noting that \( D_T^\mu(x,y) = +\infty \) for \( x \notin \text{dom } S \), yields

\[
\inf_{x \in \text{dom } S} \theta(x) + \frac{1}{\mu} D_T^\mu(x,y) = \inf_{x \in X} \theta(x) + \frac{1}{\mu} D_T^\mu(x,y) = \frac{1}{\mu} \hat{\text{env}}_{\mu,\theta}^{\star,h}(y) \quad (56a)
\]

\[
\leq \inf_{x \in \text{dom } S} \theta(x) + \frac{1}{\gamma} D_T^\gamma(x,y) = \inf_{x \in X} \theta(x) + \frac{1}{\gamma} D_T^\gamma(x,y) = \frac{1}{\gamma} \hat{\text{env}}_{\gamma,\theta}^{\star,h}(y) \quad (56b)
\]

\[
\leq \theta(y) + \frac{1}{\gamma} D_T^\gamma(y,y) = \theta(y), \quad (56c)
\]

where the last equality is due to (54). This proves (50a).

Next, for all \( x \in \overline{\text{dom } S} \), it holds that \( \theta(x) \leq \theta(x) + \frac{1}{\mu} D_T^\mu(x,y) \leq \theta(x) + \frac{1}{\gamma} D_T^\gamma(x,y) \), and hence

\[
\inf_{x \in \overline{\text{dom } S}} \theta(x) \leq \frac{1}{\mu} \hat{\text{env}}_{\mu,\theta}^{\star,h}(y) \leq \frac{1}{\gamma} \hat{\text{env}}_{\gamma,\theta}^{\star,h}(y), \quad (57)
\]

where we used the fact that \( D_T^\gamma(x,y) = +\infty \) for \( x \notin \overline{\text{dom } S} \). Noting also that \( D_T^\gamma \leq D_T^\mu \), we have \( \hat{\text{env}}_{\gamma,\theta}^{\star,h}(y) \leq \hat{\text{env}}_{\mu,\theta}^{\star,h}(y) \), which combined with (57) and (50a) implies (50b).

Now, taking infimum over \( y \in \text{dom } T \) in (50a) and using the fact that \( \hat{\text{env}}_{\gamma,\theta}^{\star,h} \subseteq \text{dom } T \) (see Proposition 3.1(ii)), we obtain that

\[
\inf_{x \in \text{dom } S} \theta(x) \leq \inf \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \leq \inf \theta(\text{dom } T) \quad (58)
\]

If \( \text{dom } S \subseteq \text{dom } T \), then \( \inf \theta(\text{dom } S) \geq \inf \theta(\text{dom } T) \), and the equalities in (58) must hold. The remaining conclusion follows directly from (50a) and the fact that \( \gamma \leq \mu \). \( \blacksquare \)

**Remark 3.2.** Suppose that \( \text{dom } T = \text{dom } S : = D \) and we want to solve the optimization problem

\[
\min \theta(x) \quad \text{s.t. } x \in D. \quad (59)
\]

It is interesting to be able to state relationships between the optimal value of the problem and \( \inf \hat{\text{env}}_{\gamma,\theta}^{\star,h}(D) \) as well as \( \inf \hat{\text{env}}_{\gamma,\theta}^{\star,h}(D) \). It is also important to establish relationships between the sets \( \text{argmin } \theta(D) \), \( \hat{\text{env}}_{\gamma,\theta}^{\star,h}(D) \), and \( \hat{\text{env}}_{\gamma,\theta}^{\star,h}(D) \). We establish these relationships in the next result.

**Proposition 3.3.** Suppose that \( \text{dom } T = \text{dom } S =: D \) and that \( Tz \subseteq Sz \) for all \( z \in D \). Let \( \theta : X \to [-\infty, +\infty] \) with \( D \cap \text{dom } \theta \neq \emptyset \), let \( \gamma \in \mathbb{R}_{++} \), and let \( x, y \in D \). Set

\[
\widetilde{A} := \bigcup_{x \in \text{argmin } \theta(D)} \{ y \in D : Ty \cap Sx = \emptyset \}, \quad \widetilde{B} := \bigcup_{x \in \text{argmin } \theta(D)} \{ y \in D : Ty \subseteq Sx \} \quad (60a)
\]

and

\[
\bar{A} := \bigcup_{y \in \text{argmin } \theta(D)} \{ x \in D : Ty \cap Sx = \emptyset \}, \quad \bar{B} := \bigcup_{y \in \text{argmin } \theta(D)} \{ x \in D : Ty \subseteq Sx \}. \quad (60b)
\]

Then the following hold:

(i) \( \inf \theta(D) = \inf \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) = \inf \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \) and \( \text{argmin } \theta(D) \subseteq \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \) \cap \( \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \).

(ii) \( \widetilde{A} \subseteq \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \) and \( \widetilde{A} \subseteq \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \).

(iii) \( \text{If } P_{\gamma,\theta}^{|h}(y) \neq \emptyset \text{ for all } y \in \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X), \text{ then } \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \subseteq \bar{B}. \) Consequently, \( \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \subseteq \bar{B} \subseteq \bar{A} \subseteq \text{argmin } \hat{\text{env}}_{\gamma,\theta}^{\star,h}(X) \).
(iv) If $\overline{P}_{\gamma,\theta}(y) \neq \emptyset$ for all $y \in \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X)$, then $\text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X) \subseteq \overline{B}$. Consequently, $\text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X) \subseteq \overline{B} \subseteq \overline{A} \subseteq \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X)$.

Proof. (i): Since dom $T = \text{dom} S = D$, Proposition 3.2 implies that $\inf \theta(D) = \inf \overline{\text{envar}}_{\gamma,\theta}^h(X) = \inf \overline{\text{envar}}_{\gamma,\theta}^h(X)$. Now, let $z \in \text{argmin} \theta(D)$. Then $z \in D$ and, by assumption, $Tz \subseteq S\gamma$, from which we have $D_T^h(z,z) = 0$. Therefore, $\theta(z) + \frac{1}{\gamma}D_T^h(z,z) = \theta(z) = \inf \theta(D) = \inf \overline{\text{envar}}_{\gamma,\theta}^h(X)$, which implies that $z \in \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X)$ and also $z \in \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X)$. We obtain that $\text{argmin} \theta(D) \subseteq \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X) \cap \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X).

(ii): Let any $y \in \overline{A}$. Then $y \in D$ and there exists $x \in \text{argmin} \theta(D)$ such that $Ty \cap Sx \neq \emptyset$. By [18, Remark 3.3(b)], $D_T^h(x,y) = 0$. Using (i) with $*=b$, we have

$$\inf \theta(D) = \inf \overline{\text{envar}}_{\gamma,\theta}^b(X) \leq \overline{\text{envar}}_{\gamma,\theta}^b(y) \leq \theta(x) + \frac{1}{\gamma}D_T^b(x,y) = \theta(x) = \inf \theta(D),$$

which implies that $y \in \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^b(X)$. Hence, $\overline{A} \subseteq \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^b(X)$. Similarly, we have that $\overline{A} \subseteq \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X)\cap \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^b(X).

(iii): Let any $y \in \text{argmin} \overline{\text{envar}}_{\gamma,\theta}^h(X)$. By assumption, there exists $x \in X$ such that $\theta(x) + \frac{1}{\gamma}D_T^h(x,y) = \overline{\text{envar}}_{\gamma,\theta}^h(y) < +\infty$. Then, we must have $x \in \text{dom} S = D$ and, by (i) with $*=\sharp$, $\inf \theta(D) = \inf \overline{\text{envar}}_{\gamma,\theta}^h(X) = \overline{\text{envar}}_{\gamma,\theta}^h(y) = \theta(x) + \frac{1}{\gamma}D_T^h(x,y) \geq \theta(x) \geq \inf \theta(D).$ (62)

Therefore, $\theta(x) = \inf \theta(D)$ and $D_T^h(x,y) = 0$. While the former implies $x \in \text{argmin} \theta(D)$, the latter implies $Ty \subseteq Sx$ (see [18, Proposition 3.7(b)]). We deduce that $y \in \overline{B}$. (iv): This is similar to (iii). 

Proposition 3.3 shows that the envelopes can be used to automatically impose the constraints. Namely, they transform the original constrained problem into an unconstrained one. This remark justifies the assumption imposed in the next proposition.

For $A \subseteq X$, denote by $\overline{A}^w$ its weak closure. Namely, $\overline{A}^w$ contains all the (weak) limits of weakly convergent sequences contained in $A$. Recall that a set is said to be precompact when its closure is compact.

**Proposition 3.4 (Left proximity operators).** Let $\theta \in \Gamma_0(X)$ and $y \in \text{dom} T$. Suppose that dom $S \cap \text{dom} \theta \neq \emptyset$ and $(\text{dom} S \cap \text{dom} \theta) \times \{y\} \subseteq \text{dom} D_T^h$. Then the following hold:

(i) Suppose that $\varphi_\mu(\cdot) := \theta(\cdot) + \frac{1}{\mu}D_T^h(\cdot,y) \text{ is coercive for some } \mu \in \mathbb{R}_+$. Then, for all $\gamma \in ]0,\mu]$, $\emptyset \neq \overline{P}_{\gamma,\theta}^h(y) \subseteq \text{dom} S \cap \text{dom} \theta$. If $Tz \subseteq S\gamma$ for all $z \in \text{dom} T$, then $P := \bigcup_{\gamma \in ]0,\mu]} \overline{P}_{\gamma,\theta}^h(y) \subseteq \text{lev}_{\leq \theta(y)} \varphi_\mu.$ (63)

If, in addition, $y \in \text{dom} \theta$, then $P$ is weakly precompact.

(ii) Suppose that $\theta$ is coercive. Then, for all $\gamma \in \mathbb{R}_+$, $\emptyset \neq \overline{P}_{\gamma,\theta}^h(y) \subseteq \text{dom} S \cap \text{dom} \theta$. If $Tz \subseteq S\gamma$ for all $z \in \text{dom} T$, then $P := \bigcup_{\gamma \in \mathbb{R}_+} \overline{P}_{\gamma,\theta}^h(y) \subseteq \text{lev}_{\leq \theta(y)} \theta.$ (64)

If, in addition, $y \in \text{dom} \theta$, then $P$ is weakly precompact.
Proof. For each $\gamma \in \mathbb{R}_{++}$, set $\varphi_\gamma(\cdot) := \theta(\cdot) + \frac{1}{\gamma} D^{h}_{T} (\cdot, y)$. It follows from $dom \ S \cap dom \theta \neq \emptyset$ and $(dom \ S \cap dom \theta) \times \{y\} \subseteq dom \ D^{h}_{T}$ that $\varphi_\gamma$ is proper. By the same argument as in [18, Lemma 3.17(b)], $\varphi_\gamma$ is (strongly) lsc on $X$, and so is $\varphi_\gamma$. Since convexity of $\varphi_\gamma$ follows from that of $\theta$ and $D^{h}_{T}(\cdot, y)$, we obtain that $\varphi_\gamma \in \Gamma_0(X)$.

(i): Let $\gamma \in [0, \mu]$. Then $\varphi_\gamma \geq \varphi_\mu$, and the coercivity of $\varphi_\gamma$ follows from the assumption that $\varphi_\mu$ is coercive. By combining with the fact that $\varphi_\gamma \in \Gamma_0(X)$ and using [35, Theorem 5.4.4], there exists $z_\gamma \in X$ such that $\varphi_\gamma(z_\gamma) = \min_{x \in X} \varphi_\gamma(x) < +\infty$. We obtain that $\theta(z_\gamma) + \frac{1}{\gamma} D^{h}_{T}(z_\gamma, y) = \overline{\text{env}}_{\gamma, \theta}(y) < +\infty$, and so $\overline{\text{P}}^{h}_{\gamma, \theta}(y) \neq \emptyset$. Now, take an arbitrary $s_\gamma \in \overline{\text{P}}^{h}_{\gamma, \theta}(y)$. Then $\theta(s_\gamma) + \frac{1}{\gamma} D^{h}_{T}(s_\gamma, y) = \overline{\text{env}}_{\gamma, \theta}(y) < +\infty$. Since $\theta(s_\gamma) > -\infty$ and $D^{h}_{T}(s_\gamma, y) \geq 0$, we must have that $\theta(s_\gamma) < +\infty$, which yield $s_\gamma \in dom \ S \cap dom \theta$. Hence, $\overline{\text{P}}^{h}_{\gamma, \theta}(y) \subseteq dom \ S \cap dom \theta$.

Next, assume that $Tz \subseteq Sz$ for all $z \in dom \ T$. We have from the rightmost inequality in (50a) of Proposition 3.2(i) that, for all $\gamma \in [0, \mu]$ and $s_\gamma \in \overline{\text{P}}^{h}_{\gamma, \theta}(y)$,

\[
\theta(y) \geq \overline{\text{env}}_{\gamma, \theta}(y) = \theta(s_\gamma) + \frac{1}{\gamma} D^{h}_{T}(s_\gamma, y) \geq \varphi_\mu(s_\gamma) = \theta(s_\gamma) + \frac{1}{\mu} D^{h}_{T}(s_\gamma, y).
\]

Therefore,

\[
P = \bigcup_{\gamma \in [0, \mu]} \overline{\text{P}}^{h}_{\gamma, \theta}(y) \subseteq \text{lev}_{\theta}(y) \varphi_\mu = \{z \in X : \varphi_\mu(z) \leq \theta(y)\}.
\]

Now, assume that $y \in dom \ theta$, so $\theta(y) < +\infty$. Since $\varphi_\mu$ is convex and lsc, it is weakly lsc. Moreover, $\varphi_\mu$ is coercive, so its level set $\text{lev}_{\theta}(y) \varphi_\mu$ is bounded and weakly closed. By [12, Theorem 3.17], $\text{lev}_{\theta}(y) \varphi_\mu$ is weakly compact. This directly implies that $P^w \subseteq \text{lev}_{\theta}(y) \varphi_\mu$. Being a weakly closed subset of a weakly compact set, $P^w$ is also weakly compact. Hence, $P$ is weakly precompact.

(ii): Since $\theta$ is coercive, we have that $\varphi_\mu$ is also coercive for all $\mu \in \mathbb{R}_{++}$. The first conclusion follows from (i). Now, assume that $Tz \subseteq Sz$ for all $z \in dom \ T$. Then, by the rightmost inequality in (50a) of Proposition 3.2(i), for all $\gamma \in \mathbb{R}_{++}$ and $s_\gamma \in \overline{\text{P}}^{h}_{\gamma, \theta}(y)$,

\[
\theta(y) \geq \overline{\text{env}}_{\gamma, \theta}(y) = \theta(s_\gamma) + \frac{1}{\gamma} D^{h}_{T}(s_\gamma, y) \geq \theta(s_\gamma).
\]

The rest of the proof is similar to that of (i).

\begin{proposition}[Right proximity operators]
\textit{Let $\theta : X \to [-\infty, +\infty]$ be proper and lsc, and let $x \in dom \ S$. Suppose that $X$ is finite-dimensional, that $dom \ T \cap dom \theta \neq \emptyset$, that $\{x\} \times (dom \ T \cap dom \theta) \subseteq dom \ D^{h}_{T}$, and that $D^{*, h}_{T}(\cdot, \cdot)$ is lsc. Then the following hold:}

(i) Suppose that $\varphi_\mu(\cdot) := \theta(\cdot) + \frac{1}{\mu} D^{h}_{T}(x, \cdot)$ is coercive for some $\mu \in \mathbb{R}_{++}$. Then, for all $\gamma \in [0, \mu]$,

$\emptyset \neq \overline{\text{P}}^{h}_{\gamma, \theta}(x) \subseteq dom \ T \cap dom \theta$. If $Tz \subseteq Sz$ for all $z \in dom \ S$, then

\[
P := \bigcup_{\gamma \in [0, \mu]} \overline{\text{P}}^{h}_{\gamma, \theta}(x) \subseteq \text{lev}_{\theta}(x) \varphi_\mu.
\]

If, in addition, $x \in dom \ theta$, then $P$ is bounded.

(ii) Suppose that $\theta$ is coercive. Then, for all $\gamma \in \mathbb{R}_{++}$, $\emptyset \neq \overline{\text{P}}^{h}_{\gamma, \theta}(x) \subseteq dom \ T \cap dom \theta$. If $Tz \subseteq Sz$ for all $z \in dom \ S$, then

\[
P := \bigcup_{\gamma \in \mathbb{R}_{++}} \overline{\text{P}}^{h}_{\gamma, \theta}(x) \subseteq \text{lev}_{\theta}(x) \theta.
\]

If, in addition, $x \in dom \ theta$, then $P$ is bounded.
\end{proposition}
Proof. Arguing as in the proof of Proposition 3.4, for all γ ∈ ]0, μ] in case (i) and for all γ ∈ ℝ_+ in case (ii), ϕγ(·) := θ(·) + 1/γ DT⋆,h(x, ·) is proper, lsc, and coercive. Since \( \overline{\text{envelope}}_{γ, θ}(x) = \inf_{y \in X} \varphi_γ(y) < +\infty \), we can take a sequence \((y_n)_{n \in \mathbb{N}} \) in X such that \( \varphi_γ(y_n) \to \overline{\text{envelope}}_{γ, θ}(x) \) as \( n \to +\infty \). We derive from the coercivity of \( \varphi_γ \) that \((y_n)_{n \in \mathbb{N}} \) is bounded, and so there is a subsequence \((y_{n_k})_{k \in \mathbb{N}} \) converging to some \( z_γ \in X \). As \( \varphi_γ \) is lsc, \( \varphi_γ(z_γ) \leq \liminf_{n \to +\infty} \varphi_γ(y_n) = \overline{\text{envelope}}_{γ, θ}(x) = \inf_{y \in X} \varphi_γ(y) \leq \varphi_γ(z_γ) \). Therefore, \( \overline{\text{envelope}}_{γ, θ}(x) = \varphi_γ(z_γ) = θ(z_γ) + \frac{1}{γ} D_{T}^{(γ, θ)}(x, z_γ) \), which implies that \( \overline{\text{envelope}}_{γ, θ}(x) \neq \emptyset \). Proceeding as in the proof of Proposition 3.4(i), we have \( \overline{\text{envelope}}_{γ, θ}(x) \subseteq \text{dom } T \cap \text{dom } θ \).

We now prove the second conclusion of (i). By the assumption that \( Tz \subseteq Sz \) for all \( z \in \text{dom } S \), the rightmost inequality in (52a) of Proposition 3.2(ii) implies that, for all \( γ \in ]0, μ] \) and \( s_γ \in \overline{\text{envelope}}_{γ, θ}(x) \),

\[
θ(x) ≥ \overline{\text{envelope}}_{γ, θ}(x) = θ(s_γ) + \frac{1}{γ} D_{T}^{(γ, θ)}(x, s_γ) ≥ \varphi_μ(s_γ) = θ(s_γ) + \frac{1}{μ} D_{T}^{(γ, θ)}(x, s_γ).
\]

We deduce that

\[
P = \bigcup_{γ \in ]0, μ]} \overline{\text{envelope}}_{γ, θ}(x) \subseteq \text{lev}_{θ(x)} \varphi_μ = \{z \in X : \varphi_μ(z) ≤ θ(x)\}.
\]

Combining this fact with the coercivity of \( \varphi_μ \) and the additional assumption that \( θ(x) < +\infty \), we obtain the boundedness of \( P \). The second conclusion of (ii) follows by the same argument as in the proof of Proposition 3.4(ii).

4. Asymptotic behaviour properties

Moreau first considered the envelope that has come to bear his name in the setting of \( γ = 1 \) [33]. He was interested, in particular, in the characterization of infimal convolution as epigraph addition; see [34]. Attouch introduced the more general parameter \( γ \) for regularizing convex functions [1, 2] and later with Wets for nonconvex functions [3]. When the regularized function is the sum of a convex objective function \( θ \) together with the indicator function for a constraint set, the Moreau envelope provides a smooth regularization with full domain. Recovery of the regularized function \( θ \) as \( γ \downarrow 0 \) is important for algorithms that use the Moreau envelope as a surrogate for \( θ \), while the asymptotic properties as \( γ \uparrow +\infty \) shed light on other properties of the regularization. In what follows, we will analyse both.

We say that a maximally monotone operator \( S \) is strictly monotone over a subset \( B \subseteq \text{dom } S \) if for every \( z, z' \in B \) we have

\[
⟨z - z', w - w'⟩ = 0 \text{ with } w \in Tz, w' \in Tz' \text{ implies } z = z'.
\]

Because the proximity operators are generically set-valued operators, when their images are nonempty we will make use of selection operators \( \overline{s}^{*, h}_{γ, θ}, \overline{s}^{*, h}_{γ, θ} \) that satisfy \( \overline{s}^{*, h}_{γ, θ}(y) \in \overline{\text{envelope}}_{γ, θ}(y) \) and \( \overline{s}^{*, h}_{γ, θ}(x) \in \overline{\text{envelope}}_{γ, θ}(x) \).

**Theorem 4.1 (Asymptotic left behaviour when \( γ \downarrow 0 \)).** Let \( θ \in Γ_0(X) \) and let \( y \in \text{dom } T \cap \text{dom } θ \). Suppose that \( \text{dom } S \cap \text{dom } θ \neq \emptyset \), that \( (\text{dom } S \cap \text{dom } θ) \times \{y\} \subseteq \text{dom } D_{T}^{γ, h} \), that \( Tz \subseteq Sz \) for all \( z \in \text{dom } T \), and that \( \varphi_μ(·) := θ(·) + \frac{1}{μ} D_{T}^{γ, h}(·, y) \) is coercive for some \( μ \in ℝ_+ \). For each \( γ \in ]0, μ] \), let \( s_γ := \overline{s}^{*, h}_{γ, θ}(y) \in \overline{\text{envelope}}_{γ, θ}(y) \). Then the following hold:
(i) \( D_T^{\sharp,h}(s_\gamma, y) \to 0 \) as \( \gamma \downarrow 0 \).

(ii) For every weak cluster point \( z \) of \( (s_\gamma)_{\gamma \in [0,\mu]} \) as \( \gamma \downarrow 0 \), it holds that \( D_T^{\sharp,h}(z, y) = 0 \), \( Ty \subseteq Sz \), and \( z \in \text{lev} \leq \theta(y) \).

(iii) If \( T = S \) and \( S \) is strictly monotone over \( \text{dom} S \cap \text{dom} \theta \), then, as \( \gamma \downarrow 0 \),

\[
s_\gamma \to y, \quad \delta_{\text{inv}}^\bullet_{\gamma,y}(y) \uparrow \theta(y), \quad \theta(s_\gamma) \to \theta(y), \quad \text{and} \quad \frac{1}{\gamma} D_T^{\sharp,h}(s_\gamma, y) \to 0. \tag{73}
\]

Proof. By the rightmost inequality in (50a) of Proposition 3.2(i), for all \( \gamma \in [0,\mu] \),

\[
\theta(y) \geq \delta_{\text{inv}}^\bullet_{\gamma,y}(y) = \theta(s_\gamma) + \frac{1}{\gamma} D_T^{\sharp,h}(s_\gamma, y) \geq \theta(s_\gamma). \tag{74}
\]

(i): Since \( \theta \in \Gamma_0(X) \), we can apply [16, Proposition 3.4.17] to conclude the existence of \( u \in X^* \) and \( \eta \in \mathbb{R} \) such that \( \theta \geq \langle \cdot, u \rangle + \eta \) (equivalently, dom \( \theta^* \neq \emptyset \)). Using (74) and Cauchy–Schwarz inequality, we have that, for all \( \gamma \in [0,\mu] \),

\[
\theta(y) \geq \theta(s_\gamma) + \frac{1}{\gamma} D_T^{\sharp,h}(s_\gamma, y) \geq \langle s_\gamma, u \rangle + \eta + \frac{1}{\gamma} D_T^{\sharp,h}(s_\gamma, y) \tag{75a}
\]

\[
\geq -\rho\|u\| + \eta + \frac{1}{\gamma} D_T^{\sharp,h}(s_\gamma, y), \tag{75b}
\]

which rearranges as

\[
0 \leq D_T^{\sharp,h}(s_\gamma, y) \leq \gamma (\theta(y) + \rho\|u\| - \eta) \to 0 \quad \text{as} \quad \gamma \downarrow 0. \tag{76}
\]

Therefore, \( D_T^{\sharp,h}(s_\gamma, y) \to 0 \) as \( \gamma \downarrow 0 \).

(ii): Let \( (s_k(\gamma)) \) be a subnet of \( (s_\gamma)_{\gamma \in [0,\mu]} \) weakly converging to \( z \) as \( k(\gamma) \to 0 \). Note that \( D_T^{\sharp,h}(\cdot, y) \) and \( \theta \) are weakly lsc since they are convex and lsc. Applying (76) to subnet \( (s_k(\gamma)) \) and using the weak lsc of \( D_T^{\sharp,h}(\cdot, y) \), we derive that

\[
0 \leq D_T^{\sharp,h}(z, y) \leq \liminf_{k(\gamma) \downarrow 0} D_T^{\sharp,h}(s_k(\gamma), y) \leq \liminf_{k(\gamma) \downarrow 0} k(\gamma)(\theta(y) + \rho\|u\| - \eta) = 0,
\]

which yields \( D_T^{\sharp,h}(z, y) = 0 \). Therefore, \( Ty \subseteq Sz \) due to the definition of \( D_T^{\sharp,h} \) and property (c) of \( h \).

Next, by applying the first inequality in (74) to subnet \( (s_k(\gamma)) \) and using the weak lsc of \( \theta \),

\[
\theta(y) \geq \liminf_{k(\gamma) \downarrow 0} \left( \theta(s_k(\gamma)) + \frac{1}{k(\gamma)} D_T^{\sharp,h}(s_k(\gamma), y) \right) \geq \liminf_{k(\gamma) \downarrow 0} \theta(s_k(\gamma)) \geq \theta(z), \tag{78}
\]

and so \( z \in \text{lev} \leq \theta(y) \theta \).

(iii): Let \( z \) be an arbitrary weak cluster point \( z \) of \( (s_\gamma)_{\gamma \in [0,\mu]} \) as \( \gamma \downarrow 0 \). By assumption and (ii), \( Ty \subseteq Tz \). Since \( y \in \text{dom} T \), taking \( v \in Ty \subseteq Tz \), we have that \( 0 = \langle z - y, v - v \rangle \) with \( v \in Tz \) and \( v \in Ty \). The strict monotonicity of \( T \) implies that \( z = y \). We deduce that \( s_\gamma \to y \) as \( \gamma \downarrow 0 \). Now, recall from Proposition 3.2(i) that \( \delta_{\text{inv}}^\bullet_{\gamma,y}(y) \uparrow \beta \) as \( \gamma \downarrow 0 \) for some \( \beta \in \mathbb{R} \). Using (74) and the weak lsc of \( \theta \), we obtain that

\[
\theta(y) \geq \beta \geq \liminf_{\gamma \downarrow 0} \theta(s_\gamma) \geq \theta(y) \geq \limsup_{\gamma \downarrow 0} \theta(s_\gamma), \tag{79}
\]

which yields \( \beta = \theta(y) = \lim_{\gamma \downarrow 0} \theta(s_\gamma) \). Again using (74), this implies \( \frac{1}{\gamma} D_T^{\sharp,h}(s_\gamma, y) \to 0 \), and we are done. ■
Theorem 4.2 (Asymptotic right behaviour when $\gamma \downarrow 0$). Let $\theta : X \to ]-\infty, +\infty]$ be proper and lsc, and let $x \in \text{dom} S \cap \text{dom} \theta$. Suppose that $X$ is finite-dimensional, that $\text{dom} T \cap \text{dom} \theta \neq \emptyset$, that $\{x\} \times (\text{dom} T \cap \text{dom} \theta) \subseteq \text{dom} D_{T}^{h}$, that $D_{T}^{h}(x, \cdot)$ is lsc, and that $\varphi(\cdot) := \theta(\cdot) + \frac{1}{\mu} D_{T}^{h}(x, \cdot)$ is coercive for some $\mu \in \mathbb{R}_{++}$. For each $\gamma \in [0, \mu]$, let $s_{\gamma} := \frac{\varphi}{\gamma}(x) \in \overline{P}_{\gamma}^{h}(x)$. Then the following hold:

(i) $D_{T}^{h}(x, s_{\gamma}) \to 0$ as $\gamma \downarrow 0$.

(ii) For every cluster point $z$ of $(s_{\gamma})_{\gamma \in [0, \mu]}$ as $\gamma \downarrow 0$, it holds that $D_{T}^{h}(x, z) = 0$ and $z \in \text{lev}_{\leq \theta}(x)$.

(iii) If $T = S$ and $S$ is strictly monotone over $\text{dom} S \cap \text{dom} \theta$, then, as $\gamma \downarrow 0$,

$$s_{\gamma} \to x, \quad \text{env}_{\gamma, \theta}(x) \uparrow \theta(x), \quad \theta(s_{\gamma}) \to \theta(x), \quad \text{and} \quad \frac{1}{\gamma} D_{T}^{h}(x, s_{\gamma}) \to 0. \quad (80)$$

Proof. This is proved similarly to Theorem 4.1 by using Proposition 3.2(ii). \hfill \blacksquare

It is worthwhile to connect these asymptotic results with previous ones in the literature. When $T = S = \nabla f$ for a strictly convex and differentiable $f : \mathbb{R}^{j} \to \mathbb{R}_{\infty}$, then $(Tz \subseteq Sz) \iff Tz = Sz$ and $(D_{f}(z, y) = 0) \iff z = y$. In this specific case, Theorems 4.1 and 4.2 show both [7, Proposition 3.2] and [7, Theorem 3.3]. Of course, Theorems 4.1 and 4.2 are stronger. In addition to not requiring right convexity of the distance, these results also include envelopes that are not classical Bregman envelopes. We include several such examples of non-classical left envelopes in Figure 2 and of non-classical right envelopes in Figure 3.

Theorem 4.3 (Asymptotic left behaviour when $\gamma \uparrow +\infty$). Let $\theta : X \to ]-\infty, +\infty]$, $y \in \text{dom} T$, and $\gamma \in \mathbb{R}_{++}$. Suppose that $\text{dom} S \cap \text{dom} \theta \neq \emptyset$, that $(\text{dom} S \cap \text{dom} \theta) \times \{y\} \subseteq \text{dom} D_{T}^{h}$, and that $Tz \subseteq Sz$ for all $z \in \text{dom} T$. Then the following hold:

(i) $\text{env}_{\gamma, \theta}(y) \downarrow \inf \theta(\text{dom} S)$ as $\gamma \uparrow +\infty$. Consequently, if $\inf \theta(\text{dom} S) = \inf \theta(\text{dom} S)$, then $\text{env}_{\gamma, \theta}(y) \downarrow \inf \theta(\text{dom} S)$ as $\gamma \uparrow +\infty$.

(ii) Suppose that $\theta \in \Gamma_{0}(X)$ and $\theta$ is coercive. For each $\gamma \in \mathbb{R}_{++}$, let $s_{\gamma} := \frac{\varphi}{\gamma}(y) \in \overline{P}_{\gamma}^{h}(y)$. Then

$$\theta(s_{\gamma}) \to \inf \theta(\text{dom} S) \quad \text{as} \quad \gamma \uparrow +\infty. \quad (81)$$

Moreover, if $\inf \theta(\overline{\text{dom}}^{w} S) = \inf \theta(\text{dom} S)$, then all weak cluster points of $(s_{\gamma})_{\gamma \in \mathbb{R}_{++}}$ as $\gamma \uparrow +\infty$ lie in $\argmin \theta(\overline{\text{dom}}^{w} S) \neq \emptyset$. If additionally $\argmin \theta(\overline{\text{dom}}^{w} S)$ is a singleton, then $s_{\gamma} \to \argmin \theta(\overline{\text{dom}}^{w} S)$ as $\gamma \uparrow +\infty$.

(iii) Suppose that $\theta \in \Gamma_{0}(X)$, $\theta$ is coercive, and $\inf \theta(\text{dom} S) = \inf \theta(\text{dom} S)$. For each $\gamma \in \mathbb{R}_{++}$, let $s_{\gamma} := \frac{\varphi}{\gamma}(y) \in \overline{P}_{\gamma}^{h}(y)$. Then

$$\theta(s_{\gamma}) \to \inf \theta(\text{dom} S) \quad \text{as} \quad \gamma \uparrow +\infty. \quad (82)$$

Moreover, if $\inf \theta(\overline{\text{dom}}^{w} S) = \inf \theta(\text{dom} S)$, then all weak cluster points of $(s_{\gamma})_{\gamma \in \mathbb{R}_{++}}$ as $\gamma \uparrow +\infty$ lie in $\argmin \theta(\overline{\text{dom}}^{w} S) \neq \emptyset$. If additionally $\argmin \theta(\overline{\text{dom}}^{w} S)$ is a singleton, then $s_{\gamma} \to \argmin \theta(\overline{\text{dom}}^{w} S)$ as $\gamma \uparrow +\infty$.

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1 In [7], the authors assume joint convexity and coercivity of $D_{f}$ to obtain non-emptiness of the right proximity operator images by [6, Proposition 3.5]; the latter result relies on the lower semicontinuity of the right distance as shown in [6, Lemma 2.6]. Thus, our rather weak assumption that the right distance be lower semicontinuous is much less restrictive than the assumptions in [7].
Proof. (i): In view of Proposition 3.2(i),
\[ \overline{\text{env}}_{\gamma,\theta}^{x,h}(y) \downarrow \alpha \geq \inf \theta(\text{dom } S) \quad \text{as} \quad \gamma \uparrow +\infty. \]  
By definition, for all \( x \in \text{dom } S \cap \text{dom } \theta, \)
\[ \overline{\text{env}}_{\gamma,\theta}^{x,h}(y) \leq \theta(x) + \frac{1}{\gamma} D_T^{x,h}(x, y), \]  
Letting \( \gamma \uparrow +\infty \) and using the assumption that \((\text{dom } S \cap \text{dom } \theta) \times \{ y \} \subseteq \text{dom } D_T^{x,h}, \) we derive that, for all \( x \in \text{dom } S \cap \text{dom } \theta, \) \( \alpha \leq \theta(x), \) and so \( \alpha \leq \inf \theta(\text{dom } S \cap \text{dom } \theta) = \inf \theta(\text{dom } S). \) Combining with (83) implies that \( \overline{\text{env}}_{\gamma,\theta}^{x,h}(y) \downarrow \inf \theta(\text{dom } S) \) as \( \gamma \uparrow +\infty. \) In turn, by invoking (50b), we get the second conclusion.

(ii): According to Proposition 3.4(ii), for all \( \gamma \in \mathbb{R}_{++}, \) \( \emptyset \neq \overline{\text{dom}}_{\gamma,\theta}^{x,h}(y) \subseteq \text{dom } S \cap \text{dom } \theta. \) Since \( s_\gamma \in \overline{\text{dom}}_{\gamma,\theta}^{x,h}(y), \) we have that \( s_\gamma \in \text{dom } S \cap \text{dom } \theta, \) and so
\[ \inf \theta(\text{dom } S) \leq \theta(s_\gamma) \leq \theta(s_\gamma) + \frac{1}{\gamma} D_T^{x,h}(s_\gamma, y) = \overline{\text{env}}_{\gamma,\theta}^{x,h}(y). \]  
By combining with (i), \( \theta(s_\gamma) \to \inf \theta(\text{dom } S) \) as \( \gamma \uparrow +\infty. \)

Now, if \( \inf \theta(\overline{\text{dom}}^{\text{w}} S) = \inf \theta(\text{dom } S), \) then we also have that \( \theta(s_\gamma) \to \inf \theta(\overline{\text{dom}}^{\text{w}} S) \) as \( \gamma \uparrow +\infty. \) The conclusion follows from [7, Lemma 3.1].

(iii): Similar to Proposition 3.4(ii), we have that, for all \( \gamma \in \mathbb{R}_{++}, \) \( \emptyset \neq \overline{\text{dom}}_{\gamma,\theta}^{x,\gamma}(y) \subseteq \text{dom } S \cap \text{dom } \theta. \) Thus, \( s_\gamma \in \overline{\text{dom}} S \cap \text{dom } \theta \) and
\[ \inf \theta(\overline{\text{dom}} S) \leq \theta(s_\gamma) \leq \theta(s_\gamma) + \frac{1}{\gamma} D_T^{x,\gamma}(s_\gamma, y) = \overline{\text{env}}_{\gamma,\theta}^{x,\gamma}(y). \]  
By assumption and (i), \( \overline{\text{env}}_{\gamma,\theta}^{x,\gamma}(y) \to \inf \theta(\text{dom } S) = \inf \theta(\overline{\text{dom}} S) \) as \( \gamma \uparrow +\infty, \) and hence \( \theta(s_\gamma) \to \inf \theta(\text{dom } S) \) as \( \gamma \uparrow +\infty. \) Finally, proceeding as in (ii), we complete the proof. \( \blacksquare \)

Theorem 4.4 (Asymptotic right behaviour when \( \gamma \uparrow +\infty \)). Let \( \theta : X \to [-\infty, +\infty], \) \( x \in \text{dom } S, \) and \( \gamma \in \mathbb{R}_{++}. \) Suppose that \( \text{dom } T \cap \text{dom } \theta \neq \emptyset, \) that \( \{ x \} \times (\text{dom } T \cap \text{dom } \theta) \subseteq \text{dom } D_T^{x,h}, \) and that \( Tz \subseteq Sz \) for all \( z \in \text{dom } S. \) Then the following hold:

(i) \( \overline{\text{env}}_{\gamma,\theta}^{x,h}(x) \downarrow \inf \theta(\text{dom } T) \) as \( \gamma \uparrow +\infty. \) Consequently, if \( \inf \theta(\overline{\text{dom}} T) = \inf \theta(\text{dom } T), \) then \( \overline{\text{env}}_{\gamma,\theta}^{x,\gamma,h}(x) \downarrow \inf \theta(\text{dom } T) \) as \( \gamma \uparrow +\infty. \)

(ii) Suppose that \( X \) is finite-dimensional, that \( \theta \) is lsc and coercive, and that \( D_T^{x,h}(x, \cdot) \) is lsc. For each \( \gamma \in \mathbb{R}_{++}, \) let \( s_\gamma := \overline{\text{env}}_{\gamma,\theta}^{x,h}(x) \in \overline{\text{dom}}_{\gamma,\theta}^{x,h}(x). \) Then
\[ \theta(s_\gamma) \to \inf \theta(\text{dom } T) \quad \text{as} \quad \gamma \uparrow +\infty. \]  
Moreover, if \( \inf \theta(\overline{\text{dom}} T) = \inf \theta(\text{dom } T), \) then all cluster points of \( \{ s_\gamma \}_{\gamma \in \mathbb{R}_{++}} \) as \( \gamma \uparrow +\infty \) lie in \( \arg \min \theta(\text{dom } T) \neq \emptyset. \) If additionally \( \arg \min \theta(\overline{\text{dom}} T) \) is a singleton, then \( s_\gamma \to \arg \min \theta(\overline{\text{dom}} T) \) as \( \gamma \uparrow +\infty. \)

(iii) Suppose that \( X \) is finite-dimensional, that \( \theta \) is lsc and coercive, and that \( \inf \theta(\overline{\text{dom}} T) = \inf \theta(\text{dom } T). \) For each \( \gamma \in \mathbb{R}_{++}, \) let \( s_\gamma := \overline{\text{env}}_{\gamma,\theta}^{x,\gamma,h}(x) \in \overline{\text{dom}}_{\gamma,\theta}^{x,\gamma,h}(x). \) Then
\[ \theta(s_\gamma) \to \inf \theta(\text{dom } T) \quad \text{as} \quad \gamma \uparrow +\infty. \]  
Moreover, all cluster points of \( \{ s_\gamma \}_{\gamma \in \mathbb{R}_{++}} \) as \( \gamma \uparrow +\infty \) lie in \( \arg \min \theta(\overline{\text{dom}} T) \neq \emptyset. \) If additionally \( \arg \min \theta(\overline{\text{dom}} T) \) is a singleton, then \( s_\gamma \to \arg \min \theta(\overline{\text{dom}} T) \) as \( \gamma \uparrow +\infty. \)
Proof. This is analogous to the proof of Theorem 4.3 and uses Proposition 3.2(ii) and Proposition 3.5(ii). We note for (iii) that $\overline{D}^{\ast,h}_T(x, \cdot)$ is lsc.

Remark 4.1. We note that the condition $\inf \theta(\overline{\text{dom}}^{-\theta}S) = \inf \theta(\text{dom} S)$ in Theorem 4.3 is satisfied as soon as either

(i) $\text{dom} S$ is weakly closed, or
(ii) $\theta \in \Gamma_0(X)$, $\text{dom} S$ is convex, and $\text{int} \text{dom} S \cap \text{dom} \theta \neq \emptyset$.

Indeed, the former case is obvious, while the latter case follows from [5, Proposition 11.1(iv)] (whose proof is still valid in a Banach space). Analogous statements hold true for the finite-dimensional counterpart $\inf \theta(\overline{\text{dom}} T) = \inf \theta(\text{dom} T)$ in Theorem 4.4.

It is worthwhile to remark on the importance of the domain conditions imposed in the left Theorem 4.3(i)–(ii), and in the right Theorem 4.4(i)–(ii). In particular, the distance $D^{\text{log}}$ does not satisfy them for all $x, y \in \text{dom} \log$, and we use it to derive envelopes for $\theta = | \cdot | - 1/2$ in Figures 2c and 3c that do not have the asymptotic properties (i)–(ii) for every $x, y \in \text{dom} \log$. Of course, the domain conditions we have imposed in Proposition 3.3, Theorem 4.3, and Theorem 4.4 are still quite broad in what they cover. Corollary 4.1 will showcase how the corresponding asymptotic guarantees subsume those of [7, Proposition 2.2], while generalizing them to many other classes of distances and envelopes. In particular, we illustrate with the GBD $D^{\text{Flog}}$ by constructing its generalized left and right envelopes in Figures 2a and 3a. It may be seen from the figures that these new envelopes respectively satisfy the asymptotic guarantees of Theorem 4.3(i)–(ii) and Theorem 4.4(i)–(ii).

**Corollary 4.1.** Let $f \in \Gamma_0(X)$ with $D := \text{dom} \partial f$. Suppose that $T = \text{dom} S = \partial f$ and that $h \in \mathcal{H}(\partial f)$ satisfies

$$\forall (x, v) \in \text{dom} f \times \text{ran} \partial f, \quad h(x, v) \leq (f + f^\ast)(x, v) = f(x) + f^\ast(v).$$

Let $\theta : X \to \mathbb{R}_+$ with $D \cap \text{dom} \theta \neq \emptyset$, let $\gamma \in \mathbb{R}_{++}$, and let $x, y \in D$. Then the following hold:

(i) As $\gamma \uparrow +\infty$,

(a) $\overline{\text{env}}_{\gamma,\theta}^h(y) \downarrow \inf \theta(D)$ and $\overline{\text{env}}_{\gamma,\theta}^h(x) \downarrow \inf \theta(D)$;
(b) $\overline{\text{env}}_{\gamma,\theta}^{h,\ast}(y) \downarrow \inf \theta(D)$ and $\overline{\text{env}}_{\gamma,\theta}^{h,\ast}(x) \downarrow \inf \theta(D)$;
(c) Classic Bregman envelopes satisfy $\overline{\text{env}}_{\gamma,\theta}^\gamma(y) \downarrow \inf \theta(D)$ and $\overline{\text{env}}_{\gamma,\theta}^\gamma(x) \downarrow \inf \theta(D)$.

(ii) Suppose further that $\text{dom} \partial f$ is open. Then, as $\gamma \uparrow +\infty$,

(a) $\overline{\text{env}}_{\gamma,\theta}^h(y) \downarrow \inf \theta(D)$ and $\overline{\text{env}}_{\gamma,\theta}^{h,\ast}(x) \downarrow \inf \theta(D)$;
(b) $\overline{\text{env}}_{\gamma,\theta}^{h,\ast}(y) \downarrow \inf \theta(D)$ and $\overline{\text{env}}_{\gamma,\theta}^{h,\ast}(x) \downarrow \inf \theta(D)$;
(c) Classic Bregman envelopes satisfy $\overline{\text{env}}_{\gamma,\theta}^{\gamma,z}(y) \downarrow \inf \theta(D)$ and $\overline{\text{env}}_{\gamma,\theta}^{\gamma,z}(x) \downarrow \inf \theta(D)$.

Proof. (i): By Lemma 2.1(i), $\text{dom} D^\gamma_h = D \times D$, so $D^\gamma_h$ satisfies Theorem 4.3(i) and Theorem 4.4(i), and we therefore get (i)(a) and (i)(b).

Now, since $y \in D = \text{dom} \partial f$, in view of Proposition 2.1 and Definition 3.1, we have that $\overline{\text{env}}_{\gamma,\theta}^\gamma(y) = \overline{\text{env}}_{\gamma,\theta}^{f+g}(y)$ and $\overline{\text{env}}_{\gamma,\theta}^{\gamma}(x) = \overline{\text{env}}_{\gamma,\theta}^{f+g}(x)$. Thus (i)(c) follows by applying (i)(a) with $h = f + f^\ast$.

(ii): As $\text{dom} \partial f$ is open, Lemma 2.1(ii) implies that $\text{dom} D_{\partial f}^{h,\ast} = D \times D$. The proof is then completed by a similar argument as in (i).

The results in Corollary 4.1(i)(c)&(ii)(c) for classical Bregman distances reduce to the ones in [7, Proposition 2.2] when $f$ is a differentiable convex function. The following corollary provides analogous extensions for the generalized proximity operators as well. We denote by $\overline{P}_{\gamma,\theta}^f, \overline{P}_{\gamma,\theta}^h$ the classical Bregman proximity operators associated with the classical Bregman envelopes $\overline{\text{env}}_{\gamma,\theta}^f, \overline{\text{env}}_{\gamma,\theta}^h$. 


Corollary 4.2. Let \( f \in \Gamma_0(X) \) with \( D := \text{dom } \partial f \) open. Suppose that \( T = S = \partial f \) and that \( h \in \mathcal{H}(\partial f) \) satisfies
\[
\forall (x, v) \in \text{dom } f \times \text{ran } \partial f, \quad h(x, v) \leq (f \oplus f^*)(x, v) = f(x) + f^*(v). \tag{90}
\]
Let \( \theta \in \Gamma_0(X) \) be coercive with \( \text{int } D \cap \text{dom } \theta \neq \varnothing \), let \( \gamma \in \mathbb{R}_{++} \), and let \( y \in D \). Suppose that one of the following holds:
\begin{enumerate}[(i)]
\item For each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \frac{\phi}{\phi} \gamma^h(y) \in \overline{\Gamma}_{\gamma, \theta}^h(y); \)
\item For each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \frac{\phi}{\phi} \gamma^h(y) \in \overline{\Gamma}_{\gamma, \theta}^h(y); \)
\item For each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \frac{\phi}{\phi} \gamma^h(y) \in \overline{\Gamma}_{\gamma, \theta}^h(y). \)
\end{enumerate}
Then \( \theta(s_\gamma) \to \inf \theta(D) \) as \( \gamma \uparrow +\infty \). Moreover, the net \((s_\gamma)_{\gamma \in \mathbb{R}_{++}}\) is bounded with all cluster points as \( \gamma \uparrow +\infty \) lying in \( \text{argmin } \theta(D^\theta) \neq \varnothing \). If additionally \( \text{argmin } \theta(D^\theta) \) is a singleton, then \( s_\gamma \to \text{argmin } \theta(D^\theta) \) as \( \gamma \uparrow +\infty \).

Proof. We first have from Lemma 2.1(ii) that \( \mathcal{D}_{\partial f}^{\gamma, h} = D \times D \). In view of Remark 4.1, \( \inf \theta(D^\theta) = \inf \theta(D) \). So, the conditions of Theorem 4.3 are satisfied, and we have the desired result in cases (i), and (ii).

As shown in the proof of Corollary 4.1(i), \( \overline{\text{env}}_{\gamma, \theta}^*(y) = \overline{\text{env}}_{\gamma, \theta}^* f \oplus f^*(y) \), which implies that \( \overline{\Gamma}_{\gamma, \theta}^* = \overline{\Gamma}_{\gamma, \theta}^* f \oplus f^* \). Therefore, the desired result in case (iii) follows from (i) with \( h = f \oplus f^* \).

\[\blacksquare\]

Corollary 4.3. Let \( f \in \Gamma_0(X) \) with \( D := \text{dom } \partial f \). Suppose that \( T = S = \partial f \) and that \( h \in \mathcal{H}(\partial f) \) satisfies
\[
\forall (x, v) \in \text{dom } f \times \text{ran } \partial f, \quad h(x, v) \leq (f \oplus f^*)(x, v) = f(x) + f^*(v). \tag{91}
\]
Let \( \theta : X \to ]-\infty, +\infty[ \) be lsc and coercive with \( \text{int } D \cap \text{dom } \theta \neq \varnothing \), let \( \gamma \in \mathbb{R}_{++} \), and let \( x \in D \). Suppose that \( X \) is finite-dimensional and that one of the following holds:
\begin{enumerate}[(i)]
\item \( \mathcal{D}_{\partial f}^T(x, \cdot) \) is lsc and, for each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \overline{\mathcal{D}}_{\gamma, \partial}^h(x) \in \overline{\mathcal{G}}_{\gamma, \theta}^h(x); \)
\item \( \mathcal{D}_{\partial f}^T(x, \cdot) \) is lsc and, for each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \overline{\mathcal{D}}_{\gamma, \partial}^h(x) \in \overline{\mathcal{G}}_{\gamma, \theta}^h(x); \)
\item \( \mathcal{D}_{\partial f}^T(x, \cdot) \) is lsc, and, for each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \overline{\mathcal{D}}_{\gamma, \partial}^h(x) \in \overline{\mathcal{G}}_{\gamma, \theta}^h(x); \)
\item \( \text{dom } \partial f \) is open, \( \mathcal{D}_{\partial f}^T(x, \cdot) \) is lsc, and, for each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \overline{\mathcal{D}}_{\gamma, \partial}^h(x) \in \overline{\mathcal{G}}_{\gamma, \theta}^h(x); \)
\item \( \text{dom } \partial f \) is open, \( \mathcal{D}_{\partial f}^T(x, \cdot) \) is lsc, and, for each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \overline{\mathcal{D}}_{\gamma, \partial}^h(x) \in \overline{\mathcal{G}}_{\gamma, \theta}^h(x); \)
\item \( \text{dom } \partial f \) is open, \( \mathcal{D}_{\partial f}^T(x, \cdot) \) is lsc, and, for each \( \gamma \in \mathbb{R}_{++} \), \( s_\gamma := \overline{\mathcal{D}}_{\gamma, \partial}^h(x) \in \overline{\mathcal{G}}_{\gamma, \theta}^h(x). \)
\end{enumerate}
Then \( \theta(s_\gamma) \to \inf \theta(D) \) as \( \gamma \uparrow +\infty \). Moreover, the net \((s_\gamma)_{\gamma \in \mathbb{R}_{++}}\) is bounded with all cluster points as \( \gamma \uparrow +\infty \) lying in \( \text{argmin } \theta(D^\theta) \neq \varnothing \). If additionally \( \text{argmin } \theta(D^\theta) \) is a singleton, then \( s_\gamma \to \text{argmin } \theta(D^\theta) \) as \( \gamma \uparrow +\infty \).

Proof. When \( f \) is differentiable, the results for the classical Bregman envelopes given in Corollaries 4.2 and 4.3 generalize those in [7, Theorem 3.5].

Examples of envelopes and proximity operators

Theorems 4.1–4.4 and Corollaries 4.1, 4.2, and 4.3 are important for several reasons. They reveal that some of the asymptotic results provided in [7, Propositions 2.2 & 3.2, Theorems 3.3 & 3.5]
for Bregman envelopes are only a special case of a class results that hold for envelopes constructed from representative functions for maximally monotone operators. We also note that we have also here provided a clarification of the domain conditions in the exposition of [7, Propositions 2.2 & 3.2], namely, that the asymptotic results are, of course, restricted to the domain of the distance operator.

We illustrate these connections with the envelopes that correspond to the distances $D_{F_{\log}}$, $D_{\text{ent} \oplus \text{ent}^*}$, and $D_{\sigma_{\log}}$ from Examples 2.3, 2.2, and 2.4 respectively, which are illustrated in Figure 1. The derivation of these distances may be found in [13]. The left envelopes are shown in Figure 2, and the right envelopes are shown in Figure 3. For both figures, we use the closed versions of the distances. The explicit forms for the envelopes and their proximity operators are given in Appendix A.

Let us first discuss how these examples illustrate Theorems 4.1 & 4.2. As the parameter $\gamma \to 0$, all of the envelopes in Figures 2 and Figure 3 exhibit the behaviour of approaching $\theta$, the Legendre function being regularized. This is, at first, less clear when the representative function employed is $\sigma_{\log}$ as in Figures 2c and 3c, and so some clarification is in order. For any $\gamma \in ]0, +\infty[\), the function $\hat{\text{env}}_{\gamma, \theta}^{\sigma_{\log}}$ is exactly equal to $\theta$ on $[0, 1/2]$, while the function $\tilde{\text{env}}_{\gamma, \theta}^{\sigma_{\log}}$ is exactly equal to $\theta$
on [1/2, 1]. This is why the net of curves collapses to a single line segment on [0, 1/2] in Figure 2c and on [1/2, 1] in Figure 3c. The reason for this may be found by scrutinizing the distance $\mathcal{D}^{\sigma, \log}$ in (41) and in Figure 1c, and observing that the distance takes the value infinity whenever the right variable is greater than the left. For this reason, the sum $\theta(x) + \mathcal{D}^{\sigma, \log}(x, y)$ is minimized at $y$ for $y \geq 1/2$, while the sum $\theta(x) + \mathcal{D}^{\sigma, \log}(x, \cdot)$ is minimized at $x$ for $x \leq 1/2$.

The case of $\mathcal{D}^{\sigma, \log}$ is also instrumental in understanding Theorems 4.3 & 4.4 and Corollary 4.1. For the reasons we have just discussed, the condition $\theta(\bar{\mathcal{E}}_{\sigma, \gamma}^{\sigma, \log}(y)) \rightarrow \inf \theta(U)$ as $\gamma \uparrow +\infty$ fails to hold for $y \in [1/2, 1]$. Consequently, for $y \in [1/2, 1]$ the condition $\sup_{\sigma} \mathcal{E}^{\sigma, \log}(y) \downarrow \inf \theta(U)$ as $\gamma \uparrow +\infty$ does not hold. An analogous situation arises for $\mathcal{E}^{\sigma, \log}(x)$ in the case of $x \in [0, 1/2]$. As previously mentioned in Examples 2.1 and 3.1, $\mathcal{D}^{\sigma, \log} = \mathcal{E}^{\sigma, \log}$ is an even more dramatic case where the GBD envelope does not asymptotically approach $\inf \theta(U)$.

On the other hand, for $y \in [0, 1/2]$ we have that $\theta(\bar{\mathcal{E}}_{\sigma, \gamma}^{\sigma, \log}(y)) \rightarrow \inf \theta(U)$ and $\mathcal{E}_{\gamma, \theta}^{\sigma, \log}(y) \downarrow \inf \theta(U)$ as $\gamma \uparrow +\infty$. Similarly, for $x \in [1/2, 1]$ we have that $\theta(\bar{\mathcal{E}}_{\sigma, \gamma}^{\sigma, \log}(y)) \rightarrow \inf \theta(U)$ and $\mathcal{E}_{\gamma, \theta}^{\sigma, \log}(y) \downarrow \inf \theta(U)$ as $\gamma \uparrow +\infty$.

The loss of some desirable asymptotic properties for the largest member of $\mathcal{H}(\partial f)$ highlights the advantage of Corollary 4.2, which assures us that $\mathcal{E}_{\gamma, \theta}^{\sigma, \log}(y) \downarrow \inf \theta(U)$ and $\mathcal{E}_{\gamma, \theta}^{\log}(x) \downarrow \inf \theta(U)$ as $\gamma \uparrow +\infty$, because $F_{\log} \leq \text{ent} \oplus \text{ent}^*$. We see this property illustrated in Figures 2b and 3a. Comparing with Figures 2b and 3b, we can also see the essential property from the proof of Corollary 4.2: that envelopes built from smaller representative functions than the Fenchel–Young representative are majorized thereby.

Finally, from a theoretical standpoint, the case of $\mathcal{E}_{\gamma, \theta}^{\sigma, \log}$ is illustrative of why we had to employ selection operators in our analysis of the proximity operators, because it is set valued for $x = 0$ and $e = 1/\gamma$.

5. Conclusion

In Section 2, we recalled the theory of GBDs [18] and the coercivity framework established in [13]. We also introduced the specific computed distances from [13] that we have used to build the envelopes and proximity operators in the current exposition, along with an explanation of why they are natural distances to consider. In Section 3, we introduced the left and right envelopes for the GBDs, along with their associated proximity operators. In Section 4, we provided a selection of asymptotic results. The examples in Section 4 illustrate how the results in the setting of GBDs vary from those we obtain more easily when specializing to Bregman distances.

Our analysis also yields results on the Bregman case when specializing thereto by using the Fenchel–Young representative. Pleasingly, the desirable asymptotic properties for Bregman distances extend to GBDs constructed from Fitzpatrick representatives, which suggests that such distances may be a useful subject for specialized investigation. Many important optimization algorithms may be studied as special cases of gradient descent applied to envelopes; now that a sufficient coercivity framework has been developed [13] and distances with desirable asymptotic envelope properties identified, two natural follow-up questions present themselves. The first is: excluding the already known Bregman cases, are there useful descent algorithms—discovered or undiscovered—whose analysis may fit within such a framework? The second is: are there previously unknown GBDs—for example, GBDs constructed from Fitzpatrick representatives—whose forms admit computational advantages over their Bregman counterparts?
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A. Appendix: Closed forms for envelopes and proximity operators

For all our examples, we use the closed distances as described in Remark 2.4. The function denoted \( W \) is the principal branch of the Lambert \( W \) function, whose occurrences in variational analysis have been discussed in, for example, [8, 10, 25].

Example A.1 (Left prox and envelope for \( D_{F_{\log}} \)). Beginning with the smallest member of \( \mathcal{H}(\log) \), we first consider the left envelope and corresponding proximity operator characterized by

\[
\begin{align*}
\overrightarrow{\text{env}}_{\gamma, \theta}^{\dagger} F_{\log}(x) &= \inf_{y \in \mathbb{R}_+} \{ \theta(y) + \frac{1}{\gamma} D_{F_{\log}}(y, x) \} \\
&= \theta\left( \overrightarrow{\text{s}}_{\gamma, \theta}^{\dagger} F_{\log}(x) \right) + \frac{1}{\gamma} D_{F_{\log}} \left( \overrightarrow{\text{s}}_{\gamma, \theta}^{\dagger} F_{\log}(x), x \right),
\end{align*}
\]

where \( F_{\log} \) is given in [9, Example 3.6] and \( D_{F_{\log}} \) is in (39). We have that

\[
\overrightarrow{\text{env}}_{\gamma, \theta}^{\dagger} F_{\log}(x) = \begin{cases} 
\left( \frac{1}{\gamma} + 1 \right) e^{\gamma} x & \text{if } x \leq \frac{e^{-\gamma}}{2+2\gamma}; \\
\left( \frac{1}{\gamma} - 1 \right) e^{-\gamma} x & \text{if } \frac{e^{-\gamma}}{2-2\gamma} < x; \\
\frac{1}{2} & \text{otherwise},
\end{cases}
\]

and

\[
\overleftarrow{\text{env}}_{\gamma, \theta}^{\dagger} F_{\log}(x) = \begin{cases} 
\frac{1}{2} - e^{\gamma} x & \text{if } x \leq \frac{e^{-\gamma}}{2+2\gamma}; \\
\frac{1}{2} & \text{if } \frac{e^{-\gamma}}{2-2\gamma} < x; \\
\left( \frac{W(e^{\frac{e^{-\gamma}}{2\gamma}})}{2\gamma W\left( \frac{e^{-\gamma}}{2\gamma} \right)} - 1 \right)^2 & \text{otherwise}.
\end{cases}
\]

The envelope is shown in Figure 2a.

Example A.2 (Right prox and envelope for \( D_{F_{\log}} \)). We next consider the right envelope and corresponding proximity operator characterized by

\[
\begin{align*}
\overleftarrow{\text{env}}_{\gamma, \theta}^{\dagger} F_{\log}(x) &= \inf_{y \in \mathbb{R}_+} \{ \theta(y) + \frac{1}{\gamma} D_{F_{\log}}(y, x) \} \\
&= \theta\left( \overleftarrow{\text{s}}_{\gamma, \theta}^{\dagger} F_{\log}(x) \right) + \frac{1}{\gamma} D_{F_{\log}} \left( \overleftarrow{\text{s}}_{\gamma, \theta}^{\dagger} F_{\log}(x), x \right),
\end{align*}
\]

where \( \overleftarrow{s}_{\gamma, \theta}^{\dagger} F_{\log}(x) \in \overleftarrow{\text{s}}_{\gamma, \theta}^{\dagger} F_{\log}(x) \).
We use the selection operator \( \overrightarrow{s}^{F_{\log}}_{\gamma, \theta} \) because, in this case, the prox operator \( \overrightarrow{P}^{F_{\log}}_{\gamma, \theta} \) is set-valued:

\[
\overrightarrow{P}^{F_{\log}}_{\gamma, \theta}(x) = \begin{cases} 0 & \text{if } x = 0 \text{ and } e < \frac{1}{\gamma}; \\ [0, \frac{1}{2}] & \text{if } x = 0 \text{ and } \frac{1}{\gamma} = e; \\ \frac{1}{2} & \text{if } x = 0 \text{ and } \frac{1}{\gamma} < e; \\ -\frac{\gamma x W\left(-\frac{1}{\gamma}\right)}{W\left(-\frac{1}{\gamma}\right)+1} & \text{if } 0 < x < -\frac{\gamma(W(\gamma) + 1)}{2W(\gamma)} \text{ and } e < \frac{1}{\gamma}; \\ \frac{\gamma x W\left(\frac{1}{\gamma}\right)}{W\left(\frac{1}{\gamma}\right)+1} & \text{if } \frac{\gamma(W(\gamma) + 1)}{2W(\gamma)} < x; \\ \frac{1}{2} & \text{otherwise.} \end{cases}
\]

The corresponding right envelope is

\[
\overleftarrow{\text{env}}^{F_{\log}}_{\gamma, \theta}(x) = \begin{cases} \frac{1}{2} & \text{if } x = 0 \text{ and } e \leq \frac{1}{\gamma}; \\ \frac{1}{2e\gamma} + \frac{x W(\gamma)}{\gamma(W(\gamma)+1)} - \frac{1}{2} + \frac{x(W(e^{\gamma W(\gamma)+1}) - 1)^2}{\gamma W(e^{\gamma W(\gamma)+1})} & \text{if } x = 0 \text{ and } \frac{1}{\gamma} < e; \\ \frac{1}{2} + \frac{x(W(e^{\gamma W(-\gamma) + 1}) - 1)^2}{\gamma W(e^{\gamma W(-\gamma) + 1})} & \text{if } \gamma(W(\gamma) + 1) \leq 2W(\gamma) < x; \\ \frac{x(W(2x) - 1)^2}{\gamma W(2x)} & \text{if } 0 < x < -\frac{\gamma(W(-\gamma) + 1)}{2W(-\gamma)} \text{ and } e < \frac{1}{\gamma}; \\ \frac{x e^{-\gamma - 1}}{1 - e^{-\gamma - 1}} & \text{if } 0 \leq x \leq \frac{1}{2}e^{-\gamma - 1} \text{ and } 1 \leq \gamma; \\ x & \text{if } x \geq \frac{1}{2} \text{ or } \gamma < 1; \\ \frac{1}{2} & \text{otherwise.} \end{cases}
\]

The envelope is shown in Figure 3a.

**Example A.3 (Left prox and envelope for \( \mathcal{D}^{\sigma_{\log}} \)).** Turning to the biggest of the representative functions for the logarithm, we next consider the left envelope and corresponding proximity operator characterized by

\[
\hat{\text{env}}_{\gamma, \theta}^{\sigma_{\log}}(x) = \inf_{y \in \mathbb{R}_+} \left\{ \theta(y) + \frac{1}{\gamma} \mathcal{D}^{\sigma_{\log}}(y, x) \right\} = \theta(\overrightarrow{P}^{\sigma_{\log}}_{\gamma, \theta}(x)) + \frac{1}{\gamma} \mathcal{D}^{\sigma_{\log}}(\overrightarrow{P}^{\sigma_{\log}}_{\gamma, \theta}(x), x).
\]

where \( \mathcal{D}^{\sigma_{\log}} \) is as in 41. We have that

\[
\overrightarrow{P}^{\sigma_{\log}}_{\gamma, \theta}(x) = \begin{cases} \frac{x}{e^{-\gamma + 1}} & \text{if } x \leq \frac{1}{2}e^{-\gamma + 1} \text{ and } 1 \leq \gamma; \\ x & \text{if } x \geq \frac{1}{2} \text{ or } \gamma < 1; \\ \frac{1}{2} & \text{otherwise.} \end{cases}
\]

The corresponding envelope is

\[
\hat{\text{env}}_{\gamma, \theta}^{\sigma_{\log}}(x) = \begin{cases} 0 & \text{if } x = 0; \\ x - \frac{1}{2} & \text{if } x \geq \frac{1}{2}; \\ \frac{1}{2} - x & \text{if } x < \frac{1}{2} \text{ and } \gamma < 1; \\ -\frac{e^{\gamma - 1}}{\gamma} (\log(xe^{-\gamma - 1}) + \gamma + \log(x)) + \frac{1}{2} & \text{if } \frac{1}{2}e^{-\gamma - 1} \text{ and } 1 \leq \gamma; \\ -\frac{1}{2\gamma} \log(2x) & \text{otherwise.} \end{cases}
\]

The envelope is shown in Figure 2c.
**Example A.4 (Right prox and envelope for $\mathcal{D}^{\text{log}}$).** We consider the right envelope and corresponding proximity operator characterized by

$$
\overrightarrow{\text{env}}_{\gamma,\theta}^{\sigma_{\text{log}}}(x) = \inf_{y \in \mathbb{R}_+} \left\{ \theta(y) + \frac{1}{\gamma} \mathcal{D}^{\text{log}}(x, y) \right\}
= \theta(\overrightarrow{P}_{\gamma,\theta}^{\sigma_{\text{log}}}(x)) + \frac{1}{\gamma} \mathcal{D}^{\text{log}} \left( x, \overrightarrow{P}_{\gamma,\theta}^{\sigma_{\text{log}}}(x) \right).
$$

The corresponding proximity operator is

$$
\overrightarrow{P}_{\gamma,\theta}^{\sigma_{\text{log}}}(x) = \begin{cases} 
\frac{1}{2} & \text{if } \frac{1}{2} < x \text{ and } x \leq \frac{1}{2}\gamma; \\
\frac{1}{\gamma} & \text{if } 1 \leq \gamma \text{ and } \frac{1}{2}\gamma < x; \\
x & \text{otherwise},
\end{cases}
$$

while the corresponding envelope is

$$
\overrightarrow{\text{env}}_{\gamma,\theta}^{\sigma_{\text{log}}}(x) = \begin{cases} 
\frac{1}{2} - x & \text{if } x \leq \frac{1}{2}; \\
x - \frac{1}{2} & \text{if } \frac{1}{2} < x \text{ and } \gamma \leq 1; \\
-\frac{1}{2} + \frac{x}{\gamma}(1 + \log(\gamma)) & \text{if } 1 \leq \gamma \text{ and } \frac{1}{2}\gamma < x; \\
x \log(2x) & \text{otherwise}.
\end{cases}
$$

The envelope is shown in Figure 3c.

The operators in Example A.5 (and their computation) may be found in [7], with the minor modification that here we are computing with the lower closure of the distance and so obtain closed forms which differ at zero. We include them here for their comparison with the new GBDs for the logarithm.

**Example A.5 (Proxes and envelopes for $\mathcal{D}^{\text{ent} \oplus \text{ent}^*}$).** We next consider the case when $\mathcal{D}^{\text{ent} \oplus \text{ent}^*}$ is the closed GBD for the Fenchel–Young representative of $\log$ (37), a case whose relationship to the Bregman distance for the Boltzmann–Shannon entropy is discussed in Example 2.2. The left proximity operator and envelope are given by

$$
\overleftarrow{P}_{\gamma,\theta}^{\text{ent} \oplus \text{ent}^*}(y) = \begin{cases} 
y \exp(\gamma), & \text{if } 0 \leq y < \frac{1}{2} \exp(-\gamma); \\
y \exp(-\gamma), & \text{if } y > \frac{1}{2} \exp(\gamma); \\
\frac{1}{2}, & \text{otherwise},
\end{cases}
$$

and

$$
\overleftarrow{\text{env}}_{\gamma,\theta}^{\text{ent} \oplus \text{ent}^*}(y) = \begin{cases} 
y(1-e^{-\gamma}) + \frac{1}{\gamma} & \text{if } 0 \leq y < \frac{1}{2} \exp(-\gamma); \\
y(1-e^{-\gamma}) - \frac{1}{\gamma} & \text{if } \frac{1}{2} \exp(\gamma) < y; \\
2y - \ln(y) - 1 - \ln(2) & \text{if } \frac{1}{\gamma} < y; \\
\frac{2y - \ln(y) - 1 - \ln(2)}{2\gamma}, & \text{otherwise}.
\end{cases}
$$

For details, see [7, Example 4.1(ii)]. The envelope is shown in Figure 2b. The right proximity operator and envelope are given by

$$
\overrightarrow{P}_{\gamma,\theta}^{\text{ent} \oplus \text{ent}^*}(x) = \begin{cases} 
x \frac{1-e^{-\gamma}}{\gamma}, & \text{if } 0 \leq x < \frac{1-\gamma}{2}; \\
x \frac{1+e^{-\gamma}}{1+\gamma}, & \text{if } x > \frac{1+\gamma}{2}; \\
\frac{1}{2}, & \text{otherwise}.
\end{cases}
$$
\[
\text{env}_{\gamma, \theta}^{\top} \circ \text{ent}^\star (x) = \begin{cases} 
\ln(1 - \gamma) x + \frac{1}{2}, & \text{if } 0 \leq x < \frac{1 - \gamma}{2}, \\
\ln(1 + \gamma) x - \frac{1}{2}, & \text{if } x > \frac{1 + \gamma}{2}, \\
\frac{1}{\gamma} \left( x \ln(2x) - x + \frac{1}{2} \right), & \text{otherwise}.
\end{cases}
\]

For details, see [7, Example 4.1(ii)]. The envelope is shown in Figure 3b.

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