PROPERTIES OF THE FAST FORWARD SHOCK DRIVEN BY THE 2012 JULY 23 EXTREME CORONAL MASS EJECTION

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ABSTRACT

Late on 2012 July 23, the STEREO-A spacecraft encountered a fast forward shock driven by a coronal mass ejection (CME) launched from the Sun earlier that same day. The estimated travel time of the disturbance (~20 hr), together with the massive magnetic field strengths measured within the ejecta (>100 nT), made it one of the most extreme events observed during the space era. In this study, we examine the properties of the shock wave. Because of an instrument malfunction, plasma measurements during the interval surrounding the CME were limited, and our approach has been modified to capitalize on the available measurements and suitable proxies, where possible. We were able to infer the following properties. First, the shock normal was pointing predominantly in the radial direction (n = 0.97e_r − 0.09e_i − 0.23e_o). Second, the angle between n and the upstream magnetic field, θ_Bn, was estimated to be ≈34°, making the shock “quasi-parallel,” and supporting the idea of an earlier “preconditioning” ICME. Third, the shock speed was estimated to be ≈3300 km s⁻¹. Fourth, the sonic Mach number, M_s, for this shock was ~28. We support these results with an idealized numerical simulation of the ICME. Finally, we estimated the change in ram pressure upstream of the shock to be ~5 times larger than the pressure from the energetic particles, suggesting that this cosmic-ray-modified shock had not reached steady-state, but instead, had been caught in an early, transient phase in its evolution.

Key words: shock waves – solar wind – Sun: coronal mass ejections (CMEs) – Sun: flares

1. INTRODUCTION

Coronal mass ejections (CMEs) are the spectacular result of the explosive release of energy stored in the magnetic field of the solar corona. While most CMEs propagate away from the Sun at speeds comparable to that of the ambient solar wind, a few have properties that could wreak havoc should they intercept Earth’s orbital trajectory (Baker et al. 2013). These so-called “extreme events,” whose likelihood of occurrence has been shown to follow a power law distribution (e.g., Riley et al. 2012) and hence occur more frequently that might otherwise be anticipated, are still rare events. By definition, only a handful have been witnessed in modern times, the most famous of which is perhaps the Carrington event of 1859 (Carrington 1859). On 2012 July 23, however, one of the two STEREO spacecraft measured an event of at least comparable strength. Thus, detailed studies of this event are crucial for improving our understanding of: (1) what conditions are required to these events to develop; (2) what physical processes produce such events; and (3) what properties can be anticipated.

On 2012 July 23, NASA’s STEREO-A spacecraft, which was located at 0.96 au and 121° ahead of the Earth, measured what is undoubtedly the most extreme interplanetary counterpart of a CME (henceforth, ICME) observed during the space era. The structure, which was described in detail by Russell et al. (2013), consisted of a fast forward shock driven by what appeared to be a pair of abutting magnetic clouds, whose peak field strength exceeded 100 nT. EUVI observations by the SECCHI instrument suggested that a CME was launched at 0208 UT, while in situ measurements suggest that the leading edge of the cloud arrived at 2255 UT, preceded by the shock at 2055 UT (Russell et al. 2013). Thus, it took 20.78 hr for the CME (identified as the leading edge of the magnetic cloud) to travel from the Sun to 1 au, implying an average transit speed of ~2000 km s⁻¹.

At the Sun, two prominence eruptions, separated by approximately 10-15 minutes likely produced the compound ICME at 1 au (Liu et al. 2014). Moreover, the observations by COR 2 on board STEREO-B further suggest that the CME-driven shock was likely already well developed low in the corona. Time-elongation maps show two adjacent tracks supporting the idea of two CMEs being launched closely in time, and merging by the time they reached COR2’s field of view (Liu et al. 2014). Estimates for the initial speed ranged from 2500 ± 500 km s⁻¹ (Baker et al. 2013) to 3050 km s⁻¹ (Liu et al. 2014).

The 2012 July 23, CME and its interplanetary counterpart have been discussed in detail in a number of other publications. Liu et al. (2014) and Temmer & Nitta (2015), in particular, described the available remote solar observations made by both STEREO-A and STEREO-B and we do not discuss them further here. Russell et al. (2013) considered the properties at, and upstream of the ICME proposing that the event represented a relatively unique example of a “cosmic-ray-modified” (CRM) shock. Baker et al. (2013) considered the space weather implications of the event, addressing the likely consequences to the Earth’s magnetosphere should an ICME like this have intercepted the Earth.

In this study, we analyze the in situ measurements by the STEREO-A spacecraft of the shock driven by the July 23 ICME. In particular, we focus on the properties of the shock driven by the extreme ICME as well as the energetic particle signatures associated with it, and we derive a set of simplified Rankine–Hugoniot relations that can be justified based on the
limited availability of in situ measurements. Additionally, we investigate the interval upstream of the shock to determine whether or not the shock conditions were modified in any significant way by the presence of energetic particles. To support our inferences, we have undertaken a suite of illustrative MHD simulations of pulse-like ejecta, which capture the basic features of the observations, including the properties of the shock. In Section 2 we review the available observations of the shock. In Section 3, we infer the basic properties of the shock, including its orientation, the angle between the shock normal and the upstream magnetic field, and the shock speed. In Section 4 we compare the various pressure terms associated with the region upstream of the shock to investigate how significant the contribution of energetic particles was, and ascertain whether the event represented a classic “steady-state” CRM shock. Next, in Section 5 we develop a simple MHD model of the ejecta propagating from the upper corona to 1 AU, which captures the basic features of the observations. Finally, in Section 6 we summarize the main points of this study, discuss some of the limitations, assumptions, and caveats brought about by the incomplete observations and the idealized nature of the simulations. We also suggest areas that might be pursued to further our understanding of this unique event.

2. IN SITU MEASUREMENTS FROM STEREO-A

In this section, we describe the main features of the available plasma, magnetic field, and energetic particle measurements.

2.1. Plasma Measurements

The Plasma and Suprathermal Ion Composition (PLASTIC) investigation (Galvin et al. 2008) on board STEREO-A produced the only available, but incomplete estimates of the plasma conditions during and surrounding the event. Initial estimates from the realtime Beacon feed were later shown to be incorrect (Baker et al. 2013), with the maximum speed estimated to be \(<1300\, \text{km}\, \text{s}^{-1}\), and the complete absence of a shock front. Subsequently, more careful analysis of the PLASTIC data was only able to recover the bulk solar wind speed, not the plasma density, temperature, or transverse velocity components, either within, or upstream of the disturbance.

To circumvent some of these issues, Liu et al. (2014) used \(>45\, \text{eV}\) electron density measurements as a proxy for the solar wind plasma density by multiplying each value by a factor of five. Similarly, they derived a plasma temperature based on the solar wind speed. For our purposes, the latter parameter probably cannot be used as a reliable estimate for plasma temperature variations during the event, and, at best, can be used as a proxy for the background value of the proton temperature upstream of the shock. The electron-derived density is more promising; however, we must be cautious of any quantitative estimates of shock parameters based on the inferred shock jump.

The bottom panel of Figure 1 shows bulk solar wind speed as estimated from both proton fits (solid black line) and \(O^7+\) and \(O^8+\) fits (blue circles). Unfortunately, no directional information for the solar velocity has so far been recovered from the raw data. The vertical dashed lines mark boundaries associated with the event as identified by Russell et al. (2013). We note that each of the identified boundaries appear to be co-located with structure in the solar wind speed (1) a small jump in speed (boundary 1); (2) the start of a gradual rise in speed (boundary 2); (3) a sharp (at least within the resolution of the measurements) jump in speed corresponding to the location of a fast-mode shock (Russell et al. 2013) (boundary 3); and (4) a modest drop in speed (boundary 4).

2.2. Magnetic Field Measurements

Measurements of the in situ magnetic field were made by the IMPACT instrument (Luhmann et al. 2008). The unit normal vectors of the field as well as the field magnitude are summarized in Figure 1. Based on the smooth rotations of the magnetic field at the beginning of, and during a large interval during July 24, Russell et al. (2013) inferred the presence of the two ICMEs shown by the yellow shading. Additionally, Liu et al. (2014) presented time-elongation maps of running differences from both Solar and Heliospheric Observatory and STEREO B, which clearly show the tracks of two closely separated CMEs propagating away from the Sun and consistent with both the timing of two consecutive prominence eruptions as well as the arrival times of the ICME structures at STEREO A. Although there is space between CME 1 and 2, the field strength profile suggests that the leading boundary of CME 2 may be advanced earlier in time, even to the point that no plasma separates the two structures. We note also that this boundary corresponds with the modest dip and rise in solar wind speed, which could be interpreted as a reverse shock, formed from the expansion of the first CME.

The boundaries labeled 1 through 4 are clearly seen in the magnetic field measurements. Boundary 1 corresponds to a small rise in field strength, and a large change in the orientation of the interplanetary field, boundary 2, is seen as a drop in field strength, boundary 3 corresponds to the shock, while boundary 4 marks the leading edge of the complex ejecta.

2.3. Energetic Particle Measurements

STEREO-A has three energetic ion detectors on board: SEPT, LET, and HET, each of which measures a progressively higher band of energies. Figure 2 summarizes these measurements during the time of transit of the CME and its associated disturbance. The individual traces show the measured intensity in a particular band, and each of the three thick curves shows the sum of the intensities over all energies measured by that instrument. We note the following points, some of which were also made by Russell et al. (2013). First, the particle intensities increase dramatically shortly after the CME was launched at the Sun (02:08 UT). Second, the intensities flatten out between boundaries 1 and 2. Third, the intensities increase sharply between boundaries 2 and 3. Fourth, between boundaries 3 and 4, the intensities either decrease (HET), plateau (LET), or modestly increase (SEPT). Following boundary 4, the intensities all generally increase over several hours, then decrease, coincident with the inferred location of CME 1. Fifth, all intensities once again increase through CME 1. Sixth, beyond the trailing edge of CME 1, the intensities all decay to lower levels, flattening out by, or shortly after the trailing edge of CME 2.

3. ANALYSIS OF THE FAST FORWARD SHOCK

As noted earlier, the fast forward shock was only partially observed by STEREO-A. Specifically, in terms of thermal
plasma parameters, only the bulk solar wind velocity was captured and at relatively low resolution. We inferred a proton density across the shock by taking the measured \( > 45 \text{ eV} \) electron density and multiplying it by a factor of five (Liu et al. 2014). Magnetic field measurements, on the other hand were continuous throughout the interval with a cadence of 1 second (Figure 1).

Figure 3 summarizes the three components of the magnetic field (in RTN coordinates), the magnetic field strength, the "proton" number density, and the bulk solar wind speed. The magnetic field vectors have been smoothed and interpolated onto the resolution of the density (15–20 s) to facilitate a more accurate calculation of the shock parameters. The yellow regions indicate the upstream (left) and downstream (right) intervals used in our shock analysis. The position of the shock is given by the dotted vertical line marked “3,” consistent with the labeling by Russell et al. (2013). These intervals were chosen to best capture the asymptotic states on either side of the shock. Because of the low resolution of the plasma velocity data, the upstream window was moved earlier in time. It is worth noting that there does not appear to be any indication of self-excited magnetic fluctuations upstream of the shock: the components appear to be relatively smooth during the time period approaching boundary 3 (See also Figure 1).

There are a number of techniques for computing the properties of fast-mode shocks in the solar wind (e.g., Riley et al. 1996). However, given the availability and higher resolution of the magnetic field vectors, it makes sense to emphasize them in our analysis. Magnetic coplanarity, in particular, is a technique for estimating the orientation of the shock normal, relying on the fact that the change in the magnetic field direction lies in the plane of the shock:

\[
\Delta \mathbf{B} \cdot \mathbf{n} = 0
\]  

(1)

where \( \Delta \mathbf{B} = \mathbf{B}_2 - \mathbf{B}_1 \), and \( \mathbf{B}_1 \) and \( \mathbf{B}_2 \) are the magnetic field vectors upstream and downstream the shock, respectively. Thus, the unit normal can be written:

\[
\mathbf{n}_{mc} = \pm \frac{(\mathbf{B}_2 \times \mathbf{B}_1) \times \Delta \mathbf{B}}{|(\mathbf{B}_2 \times \mathbf{B}_1) \times \Delta \mathbf{B}|}
\]  

(2)

The relationship between these parameters is illustrated in Figure 4. It is worth noting that the coplanarity approach breaks down in the limit that the angle between the unit normal and the upstream magnetic field, \( \theta_{Bn} \rightarrow 0^\circ \) or \( \theta_{Bn} \rightarrow 90^\circ \). In the classic picture of a fast-mode forward shock, both the magnetic field and velocity vectors are deflected away from the shock normal across the shock. And, while the bulk solar wind speed increases across the shock in the rest frame of the spacecraft (Figures 1 and 3), when transformed to the rest frame of the shock, the plasma slows down (Figure 4(c)). Panel (c) also emphasizes how, since we only have information about the bulk solar wind, we must make an assumption that the flow is essentially radial across the shock. This, as we show below, is a reasonable approximation since the outward normal to the shock front is essentially radial, as is the observed solar wind flow upstream of the event.

Rather than computing the shock normal (Equation (2)) once for the average parameters in the upstream and downstream regions, we have found it more reliable to match each point upstream with each point downstream, display the shock normal orientations graphically looking for clustering, then compute the average polar and azimuthal angles, \( \theta_n \) and \( \phi_n \), in heliographic coordinates (Riley et al. 1996). This also allows us...
to estimate, at least heuristically, the likely uncertainties in our estimate. These results are shown in Figure 5.

The individual shock orientations in Figure 5 have been color-coded according to whether they are outward-normals or inward normals. By convention, we consider only the outward-normals (red). We note that most are well clustered close to the radial direction. The best estimate for the unit shock normal was: \( \mathbf{n} = 0.97 \mathbf{e}_r - 0.09 \mathbf{e}_p - 0.23 \mathbf{e}_n \), or in terms of angular components, \( \theta_{\text{best}} \sim 13^\circ \pm 10^\circ \) and \( \phi_{\text{best}} \sim 5^\circ \pm 7^\circ \).

With the shock normal direction determined, we can then compute the angle between the upstream magnetic field and the shock normal, which has significance for understanding the types of particle acceleration processes that might be at work for this specific shock (e.g., Zank et al. 2000). This so-called

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**Figure 2.** In situ measurements of energetic proton intensities prior to, and throughout the ICME interval. Red curves are from the SEPT instrument, which measures the energy range 0.1–1.8 MeV, green curves are from the LET instrument, which measures from 1.8 to 13.6 MeV, and blue curves are from the HET instrument, measuring from 13.6 to 100 MeV.
\[ \theta_{Bn} \text{ parameter is defined by} \]
\[ \cos(\theta_{Bn}) = \frac{B_1 \cdot n}{B_1}. \]  

Again, rather than computing a single value for the average upstream-downstream windows, we follow González-Esparza et al. (1996) and pair each upstream point with each downstream point and compute all possible \( \theta_{Bn} \) values. The distribution of these is shown in Figure 6. The mean, median, and modal values all cluster at \( \sim 34^\circ \), in agreement with a Gaussian fit to the histogram, suggesting that the shock could be described as quasi-parallel.

To estimate the speed of the shock requires some consideration, given the lack of reliable plasma measurements. We begin by writing the jump relations for oblique (i.e., not purely parallel or perpendicular) shocks (Priest 2014):

\[ \rho_2 v_{2\perp} = \rho_1 v_{1\perp} \]  
\[ B_{2x} = B_{1x} \]  
\[ v_{2x} B_{2y} - v_{2y} B_{2x} = v_{1x} B_{1y} - v_{1y} B_{1x} \]

where \( \rho, v, \) and \( B \) have their usual meanings of density, speed, and field strength. The subscripts \( x \) and \( y \) refer to directions parallel and perpendicular to the shock normal, and the 1’s and 2’s.
2’s refer to conditions upstream and downstream, respectively. We have omitted the momentum and energy conservation relations from this analysis because there is limited information concerning the plasma parameters, particularly, the transverse velocity components, temperature, and to a lesser extent density. Focusing on mass conservation, Equation (4) can be rewritten in the spacecraft frame of reference as

\[
\rho_2 (v_{2x} - v_{sh}) = \rho_1 (v_{1x} - v_{sh}).
\]

Rearranging, we can estimate the speed of the shock, in the spacecraft’s frame of reference, to be

\[
v'_{sh} = \frac{\rho_2 v_{2x} - \rho_1 v_{1x}}{\rho_2 - \rho_1}.
\]

Or, more generally,

\[
v'_sh = \frac{1}{N} \sum_{i=1}^{N} \frac{\Delta[\rho_i v'_i]}{\Delta[\rho_i]} \cdot n,
\]

where \(i\) runs across all measurements within the upstream and downstream windows. Thus, we can estimate the speed of the shock relative to the upstream solar wind speed to be

\[
v''_{sh} = v'_sh - v'_1 \cdot n.
\]

It is instructive to inquire about the sensitivity of the shock speed with respect to the density measurements. Assuming for now that \(v'_1 \rightarrow v'_1\), we can write the speed of the shock in the spacecraft frame of references as

\[
v'_{sh} = \frac{\rho_2 v_{2x} - \rho_1 v_{1x}}{\rho_2 - \rho_1}.
\]

Defining: \(v'_2 = v'_1 + \Delta v'\), we can rewrite this expressions as follows:

\[
v'_sh \sim \frac{\Delta v'}{1 - \rho_1/\rho_2} + v'_1.
\]

Thus, for a strong shock: \(\rho_2/\rho_1 \rightarrow 4\)

\[
v'_sh \rightarrow \frac{1}{3} (4v'_2 - v'_1).
\]

Using Equation (9), we can estimate the speed of the shock in the rest frame of the spacecraft based on the jump in density to obtain: \(v'_{sh} = 3377\) km s\(^{-1}\). As a rudimentary check, we can compare this number with the value we would estimate in the limit of a strong shock (Equation (13)), \(v'_sh \rightarrow \frac{1}{3} (4 \times 2250 - 900) \sim 2700\) km s\(^{-1}\). As an even more basic check, in the limit that the shock were perpendicular, Equation (6) implies that the ratio of the upstream to downstream perpendicular components of the magnetic field mimic the jump in density (Equation (4)), thus, \(v'_{sh} (B) = 2752\) km s\(^{-1}\). These are, of course, gross over-simplifications. Nevertheless, they provide basic support for the estimated shock speed of 3377 km s\(^{-1}\).

Finally, we can estimate the Sonic, Alfvénic, and magneto-sonic (fast-mode) Mach numbers for this event. The Sonic Mach number is given by

\[
M_s = \frac{v_1}{C_{s1}}
\]

where \(v_1\) is the upstream solar wind speed in the shock’s frame of reference and \(C_{s1} = (\gamma P_i/\rho_i)^{1/2}\). Assuming \(P_0 = 2nk_BT\), allows us to write \(C_{s1} = (2\gamma k_BT/m_p)^{1/2}\), where \(k_B\) is the Boltzmann constant and \(m_p\) is the mass of a proton. Setting...
\[ \gamma = 5/3 \] and using the inferred—but likely unreliable—proton temperature upstream of the shock (Liu et al. 2014) of \( T_p \sim 2 \times 10^5 \) K results in \( C_{11} \sim 74 \text{ km s}^{-1} \), and, hence, with \( v_1 \sim 2100 \text{ km s}^{-1} \) (see Figure 8), a sonic Mach number, \( M_s \sim 28 \). Assuming a canonical value for the Alfvén speed in the solar wind, \( V_A \sim 100 \text{ km s}^{-1} \), produces an estimate for the Alfvén Mach number, \( M_A \sim 21 \). Finally, assuming propagation perpendicular to the field, we can estimate an upper limit to the magnetosonic (fast-mode speed), \( V_f \sim (C_s^2 + V_A^2)^{1/2} \), yielding a value for the magnetosonic Mach number, \( M_f \sim 17 \).

4. ANALYSIS OF THE RAM, THERMAL, MAGNETIC, AND ENERGETIC PARTICLE PRESSURES

We next turn our attention to various pressure terms related to the ICME and its associated disturbance. In particular, we want to understand whether, and/or to what extent, the 2012 July 23, event was a CRM shock, as was proposed by Russell et al. (2013).

Russell et al. (2013) demonstrated that the pressure exerted by the energetic particles (\( P_{ep} \)) significantly exceeded that of the magnetic pressure (\( P_{mag} \)). A CRM shock can be generally defined as one in which energetic particles are present in sufficient numbers such that they create a precursor or foreshock on the length-scale of the particles. This is clearly the case here. However, a stricter definition of a “steady-state” CRM shock, as suggested by Terasawa (1999), requires that the change in the ram pressure of the gas, \( P_{ram} = \rho v \Delta v \), be balanced by the total pressure, \( P_{total} = P_{ep} + P_{th} + P_{mag} \).

The thermal and magnetic pressures are computed as usual, with \( P_{th} = 2n_e k_B T_p \) and \( P_{mag} = \frac{\rho B^2}{2\mu_0} \) (e.g., Riley & Gosling 1998). The pressure exerted by the energetic particles is estimated as follows:

\[ P_{ep} = 4\pi m_p \sum_{i=1}^{N} I \nu \Delta E \quad (15) \]

where \( \nu = \sqrt{\frac{2E}{m_p}} \), \( I \) is the measured intensity, \( \Delta E \) is width of each energy bin, and \( i \) runs from 1 to \( N \), the total number of energy bins.

Figure 7 compares the relative pressure terms, including the ram, magnetic, energetic particle, and gas pressures. It also breaks out the contributions within the three different instruments (LET, SEPT, and HET). We note that the ram pressure always dominates over the other pressure terms by as much as two orders of magnitude. However, and as pointed out by Russell et al. (2013), although the magnetic pressure term is generally much larger than the energetic particle pressure, this is not the case ahead of the shock front (boundary 3), and particularly in the region immediately ahead of it (between boundaries 2 and 3). There, \( P_{ep} \gg P_{mag} \).

To assess how significant the contribution of the energetic-particle pressure is to the dynamics of the shock, and particularly to investigate whether the event represents a steady-state CRM shock, we should consider how the energetic particle pressure compares with the change in ram pressure (Terasawa 1999; Lario et al. 2015). To do this, we must first transform the speed measurements from their spacecraft frame of reference to that of the shock frame. This is shown in Figure 8. We note that, in passing across the shock (boundary 3), the solar wind flow slows from \( >2000 \text{ km s}^{-1} \) to \( \sim 750 \text{ km s}^{-1} \). Setting the change in the ram pressure to be zero at the location of boundary 2, we can then compute \( \Delta P_{ram} \).

This is shown and compared with the changes in the other magnetic pressure terms in Figure 9. We make the following remarks. First, between boundary 2 and 3, \( P_{ep} \) dominates over
Figure 7. Comparison of various plasma and magnetic field pressures: ram pressure (red); magnetic pressure (blue); three components of energetic particle pressure (brown, purple, and magenta); total energetic particle pressure (black); and gas pressure (aqua). The four vertical dashed lines (1–4) are the same as those in Figure 1.
both $P_{\text{mag}}$ and $P_{\text{th}}$. Second, the change in the ram pressure dominates over any of the other pressure terms, including the energetic particle pressure as well as the sum of them. Third, the variations in $P_{\text{ep}}$ and $P_{\text{ram}}$ are, however, in the opposite sense such that, at least to some extent, they offset one another. Similar comparisons between $P_{\text{ep}}$ and $P_{\text{ram}}$ can be found in Lario et al. (2015).

5. MHD MODELING

To confirm the reasonableness of our analysis, we also developed some simple MHD numerical simulations mimicking the launch of a CME and its propagation through the inner heliosphere. The model is highly idealized, and, since it does not capture the mediation of the shock structure by energetic

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**Figure 8.** Time series of solar wind speed in (top) spacecraft frame and (bottom) shock frame. The solid black lines are based on proton fits while the blue circles are based on fits to $O^{7+}$ and $O^{6+}$.

**Figure 9.** Time series of the change in ram (blue), energetic particle (red), gas (green), and magnetic (purple) pressures for the region bounded between boundaries 2 and 3, i.e., immediately upstream of the shock.
particles (e.g., Zank et al. 2014), is intended only to provide basic support for the inferences drawn from the observations.

5.1. Model Description

We simulate the 2012 July 23, ICME using the PLUTO astrophysical MHD code (Mignone et al. 2007). The code is ideally suited for solving the MHD equations under conditions of high Mach number flows. The code is modern, modular, and user-friendly, allowing the user to easily modify the boundary conditions for custom runs. It also contains a number of sophisticated features that are unnecessary for the simulations we undertook, including Adaptive Mesh Refinement (AMR) and the ability to run on massively parallel architectures. The runs summarized here were performed on a desktop computer. Given that only one component of the velocity was measured ($V_r$), we ran the code in a 1D spherical coordinate system ($r$), first setting the inner radial boundary at 30 $R_S$ to some reasonable ambient values (e.g., Riley et al. 1997; Riley & Gosling 1998) and allowing the solution to achieve a steady-state equilibrium. We set the mean molecular weight, $\mu = 0.6$ to reflect a completely ionized plasma primarily consisting primarily of hydrogen with a small component of helium. For simplicity, we set the gravitational constant to zero, a reasonable approximation for simulations starting in the high corona. We then introduced a perturbation at the inner boundary to mimic the passage of a fast ICME through it. We varied the initial speed, density, and duration of the initially smoothly varying ($\sin^2$ profile) pulse in an attempt to mimic the gross features of the ejecta and associated shock observed at 1 au. Unlike most simulations of ICMEs in the inner heliosphere, since we are restricting the model to 1D we are also able to specify a transverse component of the magnetic field within the ejecta, thus providing a more accurate contribution to the magnetic pressure of the ICME. Of course, we cannot model any toroidal field pattern, which, in reality was observed for this event.

5.2. Model Results

Figure 10 illustrates one of the simulation results. Panels (a) through (d) show time series of the speed, density, magnetic field strength, and temperature of the ICME. The start of the time axis is arbitrary in the sense that it is measured from the initiation of the simulation, which included a substantial period for the solution to reach equilibrium prior to the launch of the CME. Comparing with the observations, the speed profile matches relatively well, with an abrupt jump up to almost 2500 km s$^{-1}$ and subsequent decay. There is even the suggestion of a reverse wave in the observations during the early declining speed profile, which is quite prominent in the model. Since neither density or temperature could be recovered from the plasma instrument data, we can only speculate on whether these are good facsimiles of the observations. The magnetic field measurements appear reasonable at the leading portion of the event, but, since we do not include what we believe was a second ICME following the first one, we cannot address the structure within the trailing portion of the event.

In Figure 10(e) we show the speed of the solar wind and embedded ICME as a function of time ($x$-axis) and distance from the Sun ($y$-axis). This illustrates how an initially superfast velocity pulse bifurcates into two distinct waves; a fast forward wave to the left, and a fast reverse wave further to the right. With increasing distance from the Sun, the two separate. We can also use this visualization to directly estimate the speed of the modeled fast-mode shock. The solid white line is drawn tangent to the shock front at 1 au, and has a slope of 2967 km s$^{-1}$, roughly consistent with the speeds estimated using the in situ measurements above.

Figure 10. Results from an idealized 1D MHD simulation using the PLUTO code. (a)–(d) Time series of velocity ($v$), density ($n$), transverse magnetic field ($B$), and temperature ($T$) at 1 au. (e) Velocity map showing the evolution of speed as a function of time ($x$-axis) and distance from the Sun ($y$-axis). The white line is a tangent to the location of the shock at ~1 au.
6. DISCUSSION

In summary, our study suggests that the shock driven by the July 23/24, ICME complex was propagating approximately radially \((n = 0.97e_r - 0.09e_\theta - 0.23e_\phi)\), with a speed of \(\sim 3300 \text{ km s}^{-1}\) in the spacecraft frame of reference. The upstream speed was estimated to be \(\sim 2100 \text{ km s}^{-1}\), suggesting that the sonic Mach number of the shock, \(M_s \sim 28\), must be faster than the peak speed of the disturbance, otherwise flow upstream of the shock front could not flow into the shock and be decelerated.

Our analysis of the various pressure terms surrounding the shock suggest that the energetic particle pressure was not sufficiently large to offset the change in ram pressure. At most, it could account for 20%. Thus, we find no evidence that this CRM shock had reached a steady-state Terasawa (1999), which would require that the change in ram pressure, \(\rho v^2\), should be balanced by the increase in cosmic ray pressure. Instead, we found here, that although the changes did attempt to offset one another, the pressure from the energetic particles could only account for 20% of the change in the ram pressure. It is likely, however, the shock was modified by the presence of the energetic particles, as evidenced by: (1) the boundary marked “2” in Figures 1 and 2; and (2) the interval between “2” and “3.” In spite of this, there are other explanations for these variations, not least of which is that the solar wind is not generally observed to be in pressure balance along a radial trace (e.g., McComas et al. 1996). If we infer that the observed structure is due to the presence of the energetic particles, one interpretation of the measurements is that we observed the CRM early in its evolution. Indeed, it is quite possible that all shocks, whether or not they are mediated by cosmic rays, are constantly evolving (e.g., Zank et al. 2000). If we were able to observe it evolve, we may have seen the pressure exerted by the energetic particles continue to increase until, at some point, it would have matched the variation in ram pressure. This would likely have resulted in more significant substantial modifications to the magnetic field and thermal plasma properties.

We must also recognize that our computation of the energetic particle pressure is likely an underestimate. The instruments on board the STEREO spacecraft, while capturing a large dynamic range of energies cannot capture all of them. In particular, there may be a significant, and unmeasured component between the thermal peak of the plasma and the lowest-energy of the energetic particle detectors (\(\sim 20–30 \text{ keV}\)). We do not believe, however, that such a component could represent an additional 400%, which is what would be required to balance the offset in ram pressure (see also Lario et al. 2015).

The application of MHD model in this study should be viewed with caution. Since it contains no contribution from energetic particles, it cannot address the actual mediation of the shock by those particles. We believe that it is still valid for providing basic estimates of the dynamical properties of the shock, which are governed primarily by the dynamical properties of the plasma. However, clearly, to understand the actual mediation process, would require development of a multi-component plasma model, such as that by Zank et al. (2014). We are currently investigating different approaches that would allow us to more consistently model the evolution of such CRM shocks.

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