Stable solutions of $-\Delta u = f(u)$ in $\mathbb{R}^N$

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Abstract

Several Liouville-type theorems are presented for stable solutions of the equation $-\Delta u = f(u)$ in $\mathbb{R}^N$, where $f > 0$ is a general convex, non-decreasing functions. Extensions to solutions which are merely stable outside a compact set are discussed.

1 Introduction

For $N \geq 1$ and $f \in C^1(\mathbb{R})$ consider the equation

\[ -\Delta u = f(u) \quad \text{in} \quad \mathbb{R}^N. \]

The aim of this paper is to classify solutions $u \in C^2(\mathbb{R}^N)$ which are stable i.e. such that for all $\varphi \in C^1_c(\mathbb{R}^N)$,

\[ \int_{\mathbb{R}^N} f'(u) \varphi^2 \, dx \leq \int_{\mathbb{R}^N} |\nabla \varphi|^2 \, dx. \]

For some of our results, we shall assume in addition $u > 0$ in $\mathbb{R}^N$ and/or $u \in L^\infty(\mathbb{R}^N)$. We shall also discuss extensions to solutions which are merely stable outside a compact set (i.e. (2) holds for test functions supported in the complement of a given compact set $K \subset \subset \mathbb{R}^N$).

Stable radial solutions of (1) are by now well-understood: by the work of Cabré and Capella [4], refined by Villegas in [14], every bounded radial stable solution of (1) must be constant if $N \leq 10$. The result holds for any nonlinearity $f \in C^1(\mathbb{R})$. Conversely, there exist unbounded radial stable solutions in any dimension. Take for example, $u(x) = |x|^2/2N$ solving (1) with $f(u) = -1$. Also, there are examples of bounded radial stable solutions when $N \geq 11$. See e.g. [14], [9]. When dealing with nonradial solutions, much less is known. In the case $N = 2$, any stable solution of (1) with bounded gradient is one-dimensional (i.e. up to a rotation of space, $u$ depends only on one variable) under the sole assumption that
f is locally Lipschitz continuous (see [10]). In arbitrary dimension, a complete analysis of stable solutions and solutions which are stable outside a compact set is provided for two important nonlinearities \( f(u) = |u|^{p-1}u, \quad p > 1 \) and \( f(u) = e^u \) in [7], [9], [8] and [5].

Under a mere nonnegativity assumption on the nonlinearity, we begin this paper by stating that up to space dimension \( N = 4 \), bounded stable solutions of (1) are trivial:

**Theorem 1.1** Assume \( f \in C^1(\mathbb{R}), \quad f \geq 0 \) and \( 1 \leq N \leq 4 \). Assume \( u \in C^2(\mathbb{R}^N) \) is a bounded, stable solution of (1). Then, \( u \) is constant.

**Remark 1.2** It would be interesting to know whether Theorem 1.1 still holds if one assumes that \( u \) is unbounded but \( \nabla u \) is bounded.

### 1.1 Power-type nonlinearities

For our next set of results, we restrict to the following class of nonlinearities

\[
 f \in C^0(\mathbb{R}^+) \cap C^2(\mathbb{R}^+_*), \quad f > 0 \text{ is nondecreasing and convex in } \mathbb{R}^+_*.
\]

As demonstrated in [9] for the particular case of the power nonlinearities \( f(u) = |u|^{p-1}u \), two critical exponents play an important role, namely the classical Sobolev exponent

\[
 p_s(N) = \frac{N + 2}{N - 2}, \quad \text{for } N \geq 3
\]

and the Joseph-Lundgren exponent

\[
 p_c(N) = \frac{(N - 2)^2 - 4N + 8\sqrt{N - 1}}{(N - 2)(N - 10)}, \quad \text{for } N \geq 11.
\]

In order to relate the nonlinearity \( f \) and the above exponents, we introduce a quantity \( q \) defined for \( u \in \mathbb{R}^+_* \) by

\[
 q(u) = \frac{f'^2}{ff''}(u) = \frac{(\ln f')'(u)}{(\ln f')''(u)}
\]

whenever \( ff''(u) \neq 0 \), \( q(u) = +\infty \) otherwise. When \( f(u) = |u|^{p-1}u, \quad p \geq 1 \), \( q \) is independent of \( u \) and coincides with the conjugate exponent of \( p \) i.e. \( \frac{1}{p} + \frac{1}{q} = 1 \). In this section, we assume that \( q(u) \) converges as \( u \to 0^+ \) and denote its limit:

\[
 q_0 = \lim_{u \to 0^+} q(u) \in \mathbb{R}.
\]

**Remark 1.3** If \( u \in C^2(\mathbb{R}^N), u \geq 0 \) solves (1), and [3] holds, then \( f(0) = 0 \).

In dimension \( N = 1, 2 \), this follows directly from the classical Liouville theorem for superharmonic nonnegative functions. For a proof in dimension \( N \geq 3 \), see Step 6. in Section 6. We then observe that
Lemma 1.4 If \( f \in C^0(\mathbb{R}^+) \cap C^2(\mathbb{R}^+) \) is convex nondecreasing, \( f(0) = 0 \) and (7) holds, then in fact \( q_0 \in [1, +\infty) \).

**Proof.** Indeed, assume by contradiction there exists \( \theta > 1 \) such that 
\[
0 \leq q(u) \leq \frac{1}{\theta}u
\]
in a neighbourhood of 0. Consequently, near 0,
\[
\frac{f''}{f'} - \theta \frac{f'}{f} \geq 0.
\]
So, \( f'/f^\theta \) is nondecreasing hence bounded above near 0. Integrating again, we deduce that \( f^{1-\theta}(u) \leq Cu + C' \) near 0, which is not possible if \( f(0) = 0 \).
\( \square \)

Define now \( p_0 \in \mathbb{R} \), the conjugate exponent of \( q_0 \) by
\[
\frac{1}{p_0} + \frac{1}{q_0} = 1.
\]
The exponent \( p_0 \) must be understood as a measure of the “flatness” of \( f \) at 0. All nonlinearities \( f \) such that (8) holds and which either are analytic at the origin or have at least one non-zero derivative at the origin or are merely of the form \( f(u) = u^p g(u) \), where \( p \geq 1 \) and \( g(0) \neq 0 \), satisfy (7). Exponentially flat functions such as \( f(u) = e^{-1/u^2} \) also qualify (with \( p_0 = +\infty \)). However, there should exist (convex increasing) nonlinearities failing (7). This being said, we establish the following theorem.

**Theorem 1.5** Assume \( f \in C^0(\mathbb{R}^+) \cap C^2(\mathbb{R}^+) \) is nondecreasing, convex, \( f > 0 \) in \( \mathbb{R}^+ \) and (7) holds. Assume \( u \in C^2(\mathbb{R}^N) \) is a bounded, nonnegative, stable solution of (1). Then, \( u \equiv 0 \) if either of the following conditions holds

1. \( 1 \leq N \leq 9 \),
2. \( N = 10 \) and \( p_0 < +\infty \), where \( p_0 \) is given by \( 8 \),
3. \( N \geq 11 \) and \( p_0 < p_c(N) \), where \( p_0 \) is given by \( 8 \) and \( p_c(N) \) by (5).

**Remark 1.6** Theorem 1.5 was first proved by A. Farina, when \( f(u) = |u|^{p-1}u \). See [9]. As observed e.g. in [9], for \( N \geq 11 \), there exists a non constant bounded positive stable solution for \( f(u) = |u|^{p-1}u \) as soon as \( p \geq p_c(N) \). So our result is sharp in the class of power-type nonlinearities for \( N \geq 11 \). We do not know whether Theorem 1.5 remains true when \( N = 10 \) and \( p_0 = +\infty \). We do not know either if for \( N \leq 10 \), assumption (7) can be completely removed. See Theorem 1.11 in Section 1.2 for partial results in this direction. See also [14] for a positive answer in the radial case.

1.2 Some generalizations : unbounded and sign-changing solutions, beyond power-type nonlinearities

First, we discuss the case of unbounded solutions. When \( f(u) = |u|^{p-1}u \), the assumption \( u \in L^\infty(\mathbb{R}^N) \) is unnecessary, see [9]. For general power-type nonlinearities, Theorem 1.5 remains true for unbounded solutions under an additional assumption on the behaviour of \( f \) at \(+\infty\) :
Corollary 1.7 Assume as before that $f \in C^0(\mathbb{R}^+) \cap C^2(\mathbb{R}^*_+) \cap C^2(\mathbb{R}_+^*)$ is nondecreasing, convex, $f > 0$ in $\mathbb{R}_+^*$ and \(1\) holds. Let $p_\infty \in \mathbb{R}$ defined by

\[
q_\infty := \limsup_{u \to +\infty} q(u),
\]

\[
1/p_\infty + 1/q_\infty = 1.
\]

Let $u \in C^2(\mathbb{R}^N)$ denote a nonnegative, stable solution of \(1\). Then, $u \equiv 0$ if either of the following conditions hold

1. $1 \leq N \leq 9$ and $1 < p_\infty$,
2. $N = 10$, $p_0 < +\infty$ and $1 < p_\infty < +\infty$,
3. $N \geq 11$, $p_0 < p_c(N)$ and $1 < p_\infty < p_c(N)$.

Next, we look at solutions which may change sign. When $f(u) = |u|^{p-1}u$, the assumption $u \geq 0$ is also unnecessary, see \([9]\). For power-type nonlinearities, Theorem 1.5 can be extended to the case of solutions of arbitrary sign if $f$ is odd :

Corollary 1.8 Assume that $f \in C^0(\mathbb{R}) \cap C^2(\mathbb{R}_+^*)$ is nondecreasing and that when restricted to $\mathbb{R}_+^*$, $f$ is convex and $f > 0$. Assume \(7\) holds. Assume in addition that $f$ is odd. Let $u \in C^2(\mathbb{R}^N)$ denote a bounded, nonnegative, stable solution of \(1\). Then, $u \equiv 0$ if either of the following conditions hold

1. $1 \leq N \leq 9$ and $1 < p_\infty$,
2. $N = 10$ and $1 < p_0 < +\infty$,
3. $N \geq 11$ and $1 < p_0 < p_c(N)$.

Remark 1.9 The above Corollary remains true if $f$ is not odd but simply if $f(0) = 0$ and the assumptions made on $f$ also hold for $f$ defined for $u \in \mathbb{R}^+$ by $f(u) = -f(-u)$.

Corollary 1.10 Assuming in addition $1 < p_\infty$ if $N \leq 9$ (respectively $1 < p_\infty < +\infty$ if $N = 10$ and $1 < p_\infty < p_c(N)$ when $N \geq 11$), Corollary \(1.8\) remains valid for any stable solution. That is, one can drop the assumptions $u \geq 0$ and $u \in L^{\infty}(\mathbb{R}^N)$.

Finally, we study nonlinearities for which \(7\) fails. To do so, we introduce $q_0, q_\infty \in \mathbb{R}$ defined by

\[
q_0 = \limsup_{u \to 0^+} q(u), \quad q_\infty = \liminf_{u \to 0^+} q(u).
\]

Theorem 1.11 Assume $f \in C^0(\mathbb{R}^+) \cap C^2(\mathbb{R}^*_+) \cap C^2(\mathbb{R}_+^*)$ is nondecreasing, convex, $f > 0$ in $\mathbb{R}_+^*$ and let $q_0, q_\infty$ defined by \(11\). Assume $u \in C^2(\mathbb{R}^N)$ is a bounded, nonnegative, stable solution of \(1\). Then, $u \equiv 0$ if either of the following conditions hold

1. $3 \leq N$ and $q_0 > 2/N$,
2. $1 \leq N \leq 6$ and $q_\infty < \infty$,
3. $1 \leq N$ and $4/(1 + 1/\sqrt{q_0}) > 1/q_0$. 
Remark 1.12 The above theorem is of particular interest when \( f' \) is convex or concave near the origin. Assume \( f(0) = f'(0) = 0 \) (this is not restrictive, see Remark 3.3). Apply Cauchy’s mean value theorem: given \( u \in \mathbb{R}^+ \), there exists \( v \in (0, u) \) such that

\[
q(u_n) = \frac{f'^2}{ff''} \bigg|_{u_n} = \frac{2f'f''}{ff'' + ff'''} \bigg|_{u_n}.
\]

If \( f''' \geq 0 \) near 0, we deduce that \( q_0 \leq 2 \). By case 2 of the Theorem, we conclude that if \( f' \) is convex near 0 and \( N \leq 6 \), then \( u \equiv 0 \). Similarly, if \( f' \) is concave near 0, \( q_0 \geq 2 \). By case 3 of the Theorem, we conclude that if \( f' \) is concave near 0 and \( N \leq 9 \) (or \( N = 10 \) and \( q_0 < +\infty \)), then \( u \equiv 0 \).

Remark 1.13 Our methods yield absolutely no result under the assumption \( 10 \geq N \geq 5 \) and

\[
q_0 \leq \frac{N - 2}{4} < q_0 = \infty.
\]

1.3 Solutions which are stable outside a compact set

Set aside the case where \( f \) is a power or an exponential nonlinearity, little is known about the classification of solutions of (1) which are stable outside a compact set. Even in the radial case. Now, recall the definition of the critical exponents given in (4) and (5). As demonstrated in [9], the nonlinearities \( f(u) = |u|^{p-1}u, p = p_\ast(N), N \geq 3 \) and \( p \geq p_\ast(N), N \geq 11 \) must be singled out. For such values of \( p \), radial solutions which are stable outside a compact set are nontrivial and completely classified, while for other values of \( p > 1 \), all solutions which are stable outside a compact set (whether radial or not) must be constant. See [9]. When dealing with more general nonlinearities, the first basic step consists in determining the behaviour of a solution \( u \) at infinity. This can be done by exploiting the classification of stable solutions obtained in Theorem 1.5 and Corollary 1.8:

Proposition 1.14 Assume \( f \in C^0(\mathbb{R}) \). Assume \( u = 0 \) is the only bounded stable \( C^2 \) solution of (1). If \( u \in C^2(\mathbb{R}^N) \) is a bounded solution of (1) which is stable outside a compact set, then,

\[
\lim_{|x| \to \infty} u(x) = 0.
\]

Remark 1.15 As follows from the proof, the same result is valid for bounded positive solutions which are stable outside a compact set, under the weaker assumption that all bounded positive stable solutions of the equation are constant.

Remark 1.16 If \( f'(0) > 0 \), then in fact there exists no bounded solution of (1) which is stable outside a compact set. See the proof of Proposition 1.14.
**Remark 1.17** Clearly, if we assume instead that \( f \) vanishes only at \( u_0 \neq 0 \) then \( \lim_{|x| \to \infty} u(x) = u_0 \). Similarly, we leave the reader check that if the set of zeros of \( f \) is totally disconnected and the only bounded stable solutions of the equation are constant, then \( \lim_{|x| \to \infty} u(x) = u_0 \), where \( u_0 \) is a zero of \( f \).

**Remark 1.18** We do not know if a version of Proposition 1.14 holds if one assumes that \( f \) vanishes only at \(-\infty \) or \(+\infty \). If \( f(u) = e^u \) and \( N = 2 \) (see e.g. [8]), there exist (infinitely many) solutions of (1) which are stable outside a compact set and such that

\[
\lim_{|x| \to \infty} u(x) = -\infty.
\]

**Proof of Proposition 1.14** For \( k \geq 1 \), let \( \tau_k \in \mathbb{R}^N \) such that \( \lim_{k \to \infty} |\tau_k| = +\infty \) and let \( u_k(x) = u(x + \tau_k) \) for \( x \in \mathbb{R}^N \). Standard elliptic regularity implies that a subsequence of \( (u_k) \) converges in the topology of \( C^0_{\text{loc}}(\mathbb{R}^N) \) to a solution \( v \) of (1). In addition, since \( u \) is stable outside a compact set, \( v \) is stable. Therefore, \( v \) is constant and \( f(v) = 0 \), so \( v = 0 \). If \( f'(0) > 0 \), then \( v = 0 \) is clearly unstable, which is absurd. This proves Remark 1.16.

In addition, since \( v = 0 \) is the unique cluster point of \( (u_k) \), the whole sequence must converge to 0. Proposition 1.14 follows.

In light of Proposition 1.14, it is natural to try to characterize the speed of decay of our solutions as \( |x| \to \infty \). When \( f \) is power-type, we have the following:

**Theorem 1.19** Assume \( f \in C^0(\mathbb{R}_+) \cap C^2(\mathbb{R}_+) \) is nondecreasing, convex, \( f > 0 \) in \( \mathbb{R}_+ \), \( f(0) = 0 \) and (1) holds. Assume \( u \in C^2(\mathbb{R}^N) \) is a bounded positive solution of (1), which is stable outside a compact set. If either of the following conditions holds

1. \( 1 \leq N \leq 9 \),
2. \( N = 10 \) and \( p_0 < +\infty \),
3. \( N \geq 11 \) and \( p_0 < p_4(N) \),

then there exists a constant \( C > 0 \) such that for all \( x \in \mathbb{R}^N \) sufficiently large,

\[
\text{(11)} \quad u(x) \leq Cs(|x|).
\]

In the above inequality, the speed of decay \( s(R) \) is defined for \( R > 0 \) as the unique solution \( s = s(R) \) of

\[
\text{(12)} \quad f(A_1 R^2 f(s)) = A_2 f(s),
\]

where \( A_1, A_2 \) are two positive constants depending on \( N \) only. In other words, \( s \) is given by \( s(R) = f^{-1} \left( C_1 R^{-2} g(C_2 R^{-2}) \right) \) where \( C_1, C_2 \) are two positive constants depending on \( N \) only and \( g \) is the inverse function of \( t \mapsto f(t)/t \).

**Remark 1.20** In the above theorem, we have implicitly assumed that the functions \( f \) and \( t \mapsto f(t)/t \) are invertible in a neighborhood of 0. This is indeed true: by convexity of \( f \), \( t \mapsto f(t)/t \) is nondecreasing. By Step 6 in
Section 6, we must have \( f(0) = 0 \) and \( \lim_{t \to 0^+} \frac{f(t)}{t} = 0 \). If there existed two values \( 0 < t_1 < t_2 \) such that \( \frac{f(t_1)}{t_1} = \frac{f(t_2)}{t_2} \), then, by convexity, \( f \) would be linear on \((t_1, t_2)\), hence on \((0, t_2)\) by convexity. This contradicts \( \lim_{t \to 0^+} \frac{f(t)}{t} = 0 \). So, \( t \to f(t)/t \) is invertible for \( t > 0 \) small and so must be \( f \).

**Remark 1.21** Equation (12) looks somewhat complicated at first glance. For many nonlinearities (including \( f(u) = |u|^{p-1} u \)), one can actually set the constants \( A_1, A_2 \) equal to 1. (12) then takes the simplified form

\[
\frac{f(s)}{s} = R^{-2}.
\]

In particular, when \( f(u) = |u|^{p-1} u \), we recover the familiar speed \( s(R) = R^{-\frac{2}{p-1}} \).

**Remark 1.22** If \( p_0 < \infty \), for all \( \epsilon > 0 \), there exists \( C > 0 \) such that

\[
s(R) \leq CR^{-\frac{2}{p_0-1}+\epsilon} \quad \text{for } R \geq 1.
\]

However, even when \( p_0 < \infty \), there should exist nonlinearities \( f \) failing the estimate \( s(R) \leq CR^{-\frac{2}{p_0-1}} \).

**Proof of Remark 1.22** An easy calculation shows that for all \( \delta > 0 \) small, there exists \( C, \epsilon > 0 \) such that \( C^{-1} u^{p_0+\delta} \leq f(u) \leq C u^{p_0-\delta} \) and \( C^{-1} u^{p_0+\delta-1} \leq f'(u) \leq C u^{p_0-\delta-1} \) for \( u \in (0, \epsilon) \) provided (7) holds and \( p_0 < +\infty \). Plugging this information into the definition of \( s(R) \) yields the desired conclusion.

From here on, our aim is to prove a Liouville-type result for solutions which are stable outside a compact set. As follows from the analysis in [9], we must distinguish the sub and the supercritical case. We first consider the case where \( p_0 \) is subcritical i.e.

\[
(13) \quad p_0 < \infty, \quad N \leq 2 \quad \text{or} \quad p_0 < p_S(N), \quad N \geq 3.
\]

In this case, we make the following extra global assumption on \( f \):

\[
(14) \quad (p_0 + 1) F(s) \geq sf(s) \quad \text{for all } s \in \mathbb{R},
\]

where \( F \) denotes the antiderivative of \( f \) vanishing at 0. Then, we have

**Theorem 1.23** Assume \( f \in C^0(\mathbb{R}^+) \cap C^2(\mathbb{R}^+) \) is nondecreasing, convex, \( f > 0 \) in \( \mathbb{R}_+^* \) and (14) holds. Assume \( u \in C^2(\mathbb{R}^N) \) is a bounded, nonnegative solution of (11), which is stable outside a compact set. Assume \( p_0 \) is subcritical (i.e. (13) holds) and \( f \) satisfies the global inequality (14). Then, \( u = 0 \).

We turn next to the supercritical case. We say that \( p_0 \) is in the supercritical range if

\[
(15) \quad \begin{cases} 
  p_S(N) < p_0 < +\infty, & 3 \leq N \leq 10, \\
  p_S(N) < p_0 < p_0(N), & N \geq 11.
\end{cases}
\]
In this case, we begin by showing that the asymptotic decay estimate (11) can be further improved. Namely, we show that not only \( u(x) = O(s(|x|)) \) but in fact \( u(x) = o(s(|x|)) \). The price we pay is the following set of assumptions: we request that near the origin, there exist constants \( \varepsilon, c_1, c_2 > 0 \) such that

\[
\begin{align*}
(16) & \quad f(u) \geq c_1 u^{p_0} & \text{for } u \in (0, \varepsilon) \\
(17) & \quad f'(u) \leq c_2 u^{p_0-1} & \text{for } u \in (0, \varepsilon).
\end{align*}
\]

By convexity of \( f \), the above inequalities reduce to one when \( f(0) = 0 \):

\[
\begin{align*}
(18) & \quad c_2 u^{p_0} \geq u f'(u) \geq f(u) \geq c_1 u^{p_0} & \text{for } u \in (0, \varepsilon),
\end{align*}
\]

Compare this assumption with the already known estimate given in the proof of Remark 1.22.

**Theorem 1.24** Make the same assumptions as in Theorem 1.19. Assume in addition that \( f \) satisfies the local estimates (16), (17). For \( p_0 \) in the supercritical range (15), any bounded positive solution \( u \in C^2(\mathbb{R}^N) \) of (1), which is stable outside a compact set, satisfies

\[
\begin{align*}
(19) & \quad u(x) = o\left( |x|^{-\frac{2}{p_0-1}} \right) & \text{and } |\nabla u(x)| = o\left( |x|^{-\frac{p_0-1}{p_0-2}} \right) \quad \text{as } |x| \to \infty.
\end{align*}
\]

Finally, to obtain the Liouville theorem in the supercritical range, we assume in addition that

\[
(20) \quad (p_0 + 1)F(s) \leq sf(s) \quad \text{for all } s \in \mathbb{R}.
\]

Note that the inequality is reversed compared to (14). Also note that since \( f \) is nondecreasing, we automatically have \( F(s) \leq sf(s) \). (20) can thus be seen as an improved global convexity assumption on \( F \). We have

**Theorem 1.25** Assume \( f \in C^2(\mathbb{R}^+) \) is nondecreasing, convex, \( f > 0 \) in \( \mathbb{R}^+ \) and (6) holds. Assume \( u \in C^2(\mathbb{R}^N) \) is a bounded, nonnegative solution of (1), which is stable outside a compact set. Assume \( p_0 \) is in the supercritical range (15) and \( f \) satisfies the local bounds (16), (17) as well as the global inequality (20). Then, \( u \equiv 0 \).

**Remark 1.26** As mentioned in Remark 1.6, the above theorem is false for exponents \( p_0 \geq p_c(N) \), \( N \geq 11 \) or \( p_0 = p_S(N) \), \( N \geq 3 \).

**Remark 1.27** For the nonlinearity \( f(u) = |u|^{p-1}u \), all the extra assumptions (14), (20), (16), (17) are automatically satisfied.

The rest of the paper is organized as follows. In Section 2, we prove Theorem 1.1. Theorem 1.5 is the object of Section 3. In Section 4, we discuss the extensions given in Corollaries 1.7, 1.8 and 1.10. Theorem 1.11 which deals with nonlinearities which are not of power-type, is proved in Section 5. Section 6 is devoted to the proof of Theorem 1.19 pertaining to the rate of decay of solutions which are stable outside a compact set. The refined asymptotics obtained in Corollary 1.24 is also derived in this section. Section 7 covers Theorem 1.23 dealing with subcritical nonlinearities, while the supercritical case is addressed in Section 8.
The case of low dimensions $1 \leq N \leq 4$ : proof of Theorem 1.1

The proof bears resemblances with an argument found in [2]. It relies on two simple arguments: a growth estimate of the Dirichlet energy on balls and a Liouville-type result for certain divergence-form equations (mainly due to Berestycki, Caffarelli and Nirenberg [3]), which applies to solutions with controlled energy. The specific form of the aforementioned equation is obtained by linearizing (1) and taking advantage of the stability assumption. The limitation $N \leq 4$ arises from the energy estimate on balls.

**Proof.** For $R > 0$, let $B_R$ denote the ball of radius $R$ centered at the origin. We begin by proving that there exists a constant $C > 0$ independent of $R > 0$ such that

$$\int_{B_R} |\nabla u|^2 \, dx \leq CR^{N-2}. \tag{21}$$

Let $M \geq \|u\|_{\infty}$, $\varphi \in C^2_c(\mathbb{R}^N)$ and multiply (1) by $(u - M)\varphi$:

$$\int_{\mathbb{R}^N} -\Delta u (u - M) \varphi \, dx = \int_{\mathbb{R}^N} f(u)(u - M) \varphi \, dx.$$

Integrating by parts and recalling that $f \geq 0$, it follows that

$$\int_{\mathbb{R}^N} |\nabla u|^2 \varphi \, dx + \int_{\mathbb{R}^N} (u - M) \nabla u \nabla \varphi \, dx = \int_{\mathbb{R}^N} f(u)(u - M) \varphi \, dx \leq 0,$$

whence,

$$\int_{\mathbb{R}^N} |\nabla u|^2 \varphi \, dx \leq - \int_{\mathbb{R}^N} \frac{1}{2} \nabla (u - M)^2 \nabla \varphi \, dx = \int_{\mathbb{R}^N} \frac{(u - M)^2}{2} \Delta \varphi \, dx \leq 2M^2 \int_{\mathbb{R}^N} |\nabla \varphi| \, dx.$$

Let $\varphi_0$ denote any nonnegative test function such that $\varphi_0 = 1$ on $B_1$ and apply the above inequality with $\varphi(x) = \varphi_0(x/R)$. We obtain (21).

Since $u$ is stable, there exists a solution $v > 0$ of the linearized equation

$$-\Delta v = f'(u)v \quad \text{in } \mathbb{R}^N. \tag{22}$$

Let $\sigma_j = \frac{1}{v} \frac{\partial u}{\partial x_j}$ for $j = 1, \ldots, N$. Then, since $v$ and $\partial u/\partial x_j$ both solve the linearized equation (22), it follows that

$$-\nabla \cdot (v^2 \nabla \sigma_j) = 0 \quad \text{in } \mathbb{R}^N. \tag{23}$$

It is known that any solution $\sigma \in H^{1}_{\text{loc}}(\mathbb{R}^N)$ of (22) such that

$$\int_{B_R} v^2 \sigma^2 \leq CR^2,$$
must be constant (see Proposition 2.1 in [2]). By (21), we deduce that if \( N \leq 4 \), then \( \sigma_j \) is constant, i.e. there exists a constant \( C_j \) such that
\[
\frac{\partial u}{\partial x_j} = C_j v.
\]
In particular, the gradient of \( u \) points in a fixed direction i.e. \( u \) is one-dimensional and solves
\[
-\Delta u = f(u) \quad \text{in } \mathbb{R}.
\]
Since \( f \geq 0 \) and \( u \) is bounded, this is possible only if \( u \) is constant and \( f(u) = 0 \).

\[\square\]

3 The Liouville theorem for stable solutions: proof of Theorem 1.5

The proof is split into two separate cases, according to the value of \( q_0 \). We first consider the case \( q_0 > \frac{N}{2} \). It suffices to prove the following lemma.

**Lemma 3.1** Assume \( f \in C^2(\mathbb{R}^+), \ f > 0 \) is nondecreasing, convex and
\[
q_0 := \liminf_{u \to 0^+} q(u) > \frac{N}{2}.
\]
Assume \( u \in C^2(\mathbb{R}^N), \ u \geq 0 \) and
\[
-\Delta u \geq f(u) \quad \text{in } \mathbb{R}^N.
\]
Then, \( u \equiv 0 \).

**Remark 3.2** A stronger version of the above lemma has been recently proved by L. D’Ambrosio and E. Mitidieri ([6]).

**Proof.** Assume by contradiction that \( u \neq 0 \). By the Strong Maximum Principle, \( u > 0 \).

**Step 1.** Since \( q_0 > \frac{N}{2} \), there exists \( q > \frac{N}{2} \) such that
\[
\frac{f''(q)}{f'^2} < \frac{1}{q}.
\]
in a neighborhood of 0. Equivalently, \( \frac{f'}{f'} - \frac{1}{q} < 0 \). Hence, the function \( \frac{f''}{f'^2} \) is decreasing near 0. In particular, there exists a constant \( C > 0 \) such that \( \frac{f''}{f'^2} \geq C \) near 0, which implies that for some \( p < \frac{N}{N-2} \), \( c_1 > 0 \),
\[
f(u) \geq c_1 u^p.
\]
The above inequality holds in a neighborhood of 0.

**Step 2.** Since \( p < p_s(N) \), there exists \( \varphi > 0 \) solving
\[
-\Delta \varphi = c_1 \varphi^p \quad \text{in } B_1
\]
\[
\varphi = 0 \quad \text{on } \partial B_1.
\]
We are going to prove that a rescaled version of $\varphi$ must lie below $u$. Let indeed $R > 0$ and $\varphi_R(x) = R^{-\frac{N}{p}} \varphi(x/R)$ for $x \in B_R$, $\varphi_R(x) = 0$ for $|x| \geq R$. Then,

$$
\begin{cases}
-\Delta \varphi_R = c_1(\varphi_R)^p & \text{in } B_R \\
\varphi_R = 0 & \text{on } \partial B_R.
\end{cases}
$$

Furthermore, since $p < \frac{N}{N-2}$,

$$
\frac{\|\varphi_R\|_{L^\infty(B_R)}}{R^{N-p}} \leq \frac{R^{-\frac{N}{p}}}{R^{N-2}} \|\varphi\|_{L^\infty(B_1)} \to 0, \quad \text{as } R \to +\infty.
$$

**Step 3.** Since $u > 0$ is superharmonic, there exists a constant $c > 0$ such that

$$
u(x) \geq c |x|^{2-N} \quad \text{for } |x| \geq 1.
$$

Indeed, the above inequality clearly holds for $|x| = 1$, with $c = \min_{|x| = 1} u$. In addition, the function $z = u - c |x|^{2-N}$ is superharmonic in $[1 \leq |x| \leq M]$. By the Maximum Principle, $z \geq \min(0, \min_{|x| = M} z(x))$, in $[1 \leq |x| \leq M]$. Hence, $z \geq \liminf_{M \to \infty} \min(0, \min_{|x| = M} z(x)) = 0$. (28) is established.

**Step 4.** Collecting (27) and (28), we obtain for $R > 0$ sufficiently large

$$
u \geq \varphi_R.$$

We conclude using the celebrated sliding method: first, by (27), $\|\varphi_R\|_{L^\infty} \to 0$ as $R \to \infty$, so that by (25), $f(\varphi_R) \geq c_1 (\varphi_R)^p$, provided $R$ is sufficiently large. In particular,

$$-\Delta(u - \varphi_R) \geq f(u) - f(\varphi_R) \geq 0.$$

By the Strong Maximum Principle, $u > \varphi_R$. Next, we slide $\varphi_R$ in a given direction, say $\tilde{\varphi}_{R,t}(x) = \varphi_R(x + te_1)$, where $e_1 = (1, 0, \ldots, 0)$. We want to prove that $u \geq \tilde{\varphi}_{R,t}$ for all $t \geq 0$. If not, there exists $t_0 \in (0, +\infty)$ such that $u \geq \tilde{\varphi}_{R,t_0}$ and $u(x_0) = \tilde{\varphi}_{R,t_0}(x_0)$ at some point $x_0 \in \mathbb{R}^N$. But again we have

$$-\Delta(u - \varphi_{R,t_0}) \geq f(u) - f(\varphi_{R,t_0}) \geq 0,$$

and the Strong Maximum Principle would imply that $u \equiv \tilde{\varphi}_{R,t_0}$. This is not possible since $\varphi_{R,t_0}$ is compactly supported while $u$ is not. The above argument holds if $e_1$ is replaced by any other direction $e \in S^{N-1}$. In particular, $u \geq \max \varphi_R > 0$, which is possible, since $u$ is superharmonic, only if $u$ is constant. Since, $f > 0$, we obtain a contradiction. Hence, $u \equiv 0$.

\[\square\]

**Remark 3.3** If $f(0) \neq 0$ or $f'(0) \neq 0$, then (24) clearly holds in a neighborhood of 0 and we may work as above to conclude that $u$ is constant. We may therefore assume for the rest of the proof that $f(0) = f'(0) = 0$.

We turn next to the case $q_0 \leq N/2$, which is a consequence of the following theorem.
Theorem 3.4 Assume $f \in C^2(\mathbb{R}^+)$ is nondecreasing, convex, $f > 0$ in $\mathbb{R}^+$, \ref{7} holds and $q_0 < +\infty$. Then, the differential inequality
\begin{equation}
- \Delta u \leq f(u) \quad \text{in } \mathbb{R}^N
\end{equation}
does not admit any solution $u \in C^2(\mathbb{R}^N) \cap L^\infty(\mathbb{R}^N)$, $u > 0$ such that \ref{2} holds, if either of the following conditions holds
1. $1 \leq N \leq 9$,
2. $N = 10$ and $p_0 < +\infty$,
3. $N \geq 11$ and $p_0 < p_c(N)$.

Remark 3.5 With no change to the proof, Theorem 3.4 remains true if $u$ is only assumed to be locally Lipschitz continuous. The differential inequality \ref{29} must then be understood in the weak sense i.e.
\begin{equation}
\int_{\mathbb{R}^N} \nabla u \nabla \varphi \, dx \leq \int_{\mathbb{R}^N} f(u) \varphi \, dx,
\end{equation}
for all Lipschitz functions $\varphi \geq 0$ with compact support.

It remains to prove Theorem 3.4. We begin with the following weighted-Poincaré inequality.

Lemma 3.6 Assume $\Omega$ is an arbitrary open set in $\mathbb{R}^N$. Let $u \in C^2(\Omega)$, $u \geq 0$ satisfy
\begin{equation}
- \Delta u \leq f(u) \quad \text{in } \Omega.
\end{equation}
Assume in addition that for all $\varphi \in C^1_c(\Omega)$,
\begin{equation}
\int_{\Omega} f'(u) \varphi^2 \, dx \leq \int_{\Omega} |\nabla \varphi|^2 \, dx.
\end{equation}
Let $\phi \in W^{1,\infty}_{\text{loc}}(\mathbb{R};\mathbb{R})$ denote a convex function and $\eta \in C^1_c(\mathbb{R}^N)$. Let
\begin{equation}
\psi(u) = \int_0^u \phi^2(t) \, dt.
\end{equation}
Then,
\begin{equation}
\int_{\Omega} [(f' \phi^2 - f \psi) \circ u] \eta^2 \, dx \leq \int_{\Omega} [\phi^2 \circ u] |\nabla \eta|^2 \, dx.
\end{equation}

Remark 3.7 If $\phi$ is not convex, then the following variant of \ref{31} holds.
\begin{equation}
\int_{\Omega} [(f' \phi^2 - f \psi) \circ u] \eta^2 \, dx \leq \int_{\Omega} [K \circ u] \Delta(\eta^2) \, dx - \int_{\Omega} [\phi^2 \circ u] \eta \Delta \eta \, dx,
\end{equation}
where $K(u) = \int_0^u \psi(s) \, ds$.

Proof. Multiply \ref{29} by $\psi(u)\eta^2$ and integrate by parts:
\begin{align*}
\int_{\Omega} \nabla u \nabla (\psi(u)\eta^2) \, dx &\leq \int_{\Omega} f(u)\psi(u)\eta^2 \, dx \\
\int_{\Omega} \phi'(u) \eta^2 |\nabla u|^2 \, dx + \int_{\Omega} \psi(u)\nabla u \nabla \eta^2 \, dx &\leq \int_{\Omega} \phi'(u) \eta^2 |\nabla u|^2 \, dx - \int_{\Omega} K(u) \Delta \eta^2 \, dx.
\end{align*}
where \( K(u) = \int_0^u \psi(s) \, ds \). Hence,

\[
(33) \quad \int_\Omega \phi'(u)^2 |\nabla u|^2 \eta^2 \, dx \leq \int_\Omega K(u) \Delta \eta^2 \, dx + \int_\Omega f(u) \psi(u) \eta^2 \, dx
\]

Next, we apply (30) with \( \varphi = \phi(u) \eta \) and obtain

\[
\int_\Omega f'(u) \phi(u) \eta^2 \, dx \leq \int_\Omega |\nabla (\phi(u) \eta)|^2 \, dx = \int_\Omega |\phi'(u)\eta \nabla u + \phi(u) \nabla \eta|^2 \, dx
\]

\[
\leq \int_\Omega \phi'(u)^2 \eta^2 |\nabla u|^2 \, dx + \int_\Omega \phi(u)^2 |\nabla \eta|^2 \, dx + 2 \int_\Omega \phi(u) \phi'(u) \eta \nabla \eta \nabla u \, dx
\]

\[
\leq \int_\Omega \phi'(u)^2 \eta^2 |\nabla u|^2 \, dx + \int_\Omega \phi(u)^2 |\nabla \eta|^2 \, dx + \frac{1}{2} \int_\Omega \nabla \eta^2 \nabla \phi(u)^2 \, dx
\]

\[
\leq \int_\Omega \phi'(u)^2 \eta^2 |\nabla u|^2 \, dx + \int_\Omega \phi(u)^2 \left( |\nabla \eta|^2 - \frac{1}{2} \Delta \eta^2 \right) \, dx
\]

Plug (33) in the above. Then,

\[
\int_\Omega (f'(u) \phi(u)^2 - f(u) \psi(u)^2) \eta^2 \, dx \leq \int_\Omega K(u) \Delta \eta^2 \, dx + \int_\Omega \phi(u)^2 \left( |\nabla \eta|^2 - \frac{1}{2} \Delta \eta^2 \right) \, dx
\]

This proves Remark 3.7. Finally, when \( \phi \) is convex,

\[
\psi(u) = \int_0^u \phi^2(s) \, ds \leq \phi'(u) \phi(u).
\]

Integrating, we obtain that \( K \leq \frac{1}{2} \phi^2 \) and (31) follows. \( \square \)

**Proof of Theorem 3.4 continued.** Take \( \alpha > 1 \) and \( \phi = f^\alpha \). In order to take advantage of Lemma 3.4, we need to make sure that the quantity \( (f' \phi^2 - f \psi) \circ u \) remains nonnegative and better, bounded below by some positive function of \( u \). Clearly, the best one can hope for is an inequality of the form

\[
(f' \phi^2 - f \psi) \circ u \geq c f' \phi^2 \circ u.
\]

To obtain such an inequality, we apply L'Hôpital's Rule:

\[
\lim_{0^+} \frac{f' \phi^2}{f \psi} = \lim_{0^+} \frac{f' f^{2\alpha-1}}{f' f^{2\alpha-1} - \psi}
\]

\[
= \lim_{0^+} \frac{f' f^{2\alpha-1} + (2\alpha - 1) f^{2\alpha - 2} f'^2}{\alpha^2 f^{2\alpha - 2} f'^2}
\]

\[
= \frac{1}{\alpha^2} (1/q_0 + 2\alpha - 1) > 1,
\]

where the last inequality holds if \( \alpha \in [1, 1+1/\sqrt{q_0}) \). Note that this interval is nonempty since we assumed \( q_0 < +\infty \). Hence, for some constant \( c > 0 \),

\[
(34) \quad f' \phi^2 - f \psi \geq c f' \phi^2
\]

in a neighbourhood \([0, \varepsilon]\) of the origin. Modifying \( \phi \), the above inequality can be extended to a given compact interval \([0, M]\) as follows. Take \( \phi \in \)
$W^{1,\infty}_{\text{loc}}(\mathbb{R}; \mathbb{R})$ defined by

$$
\phi(u) = \begin{cases} 
(f(u))^\alpha & \text{if } 0 \leq u \leq \epsilon \\
(f(\epsilon)^{\alpha-1} f(u) \exp \left( \int_{\epsilon}^u \sqrt{f'} \, ds \right) & \text{if } u > \epsilon
\end{cases}
$$

where $\epsilon, \alpha$ are chosen as before. Then $\phi \in W^{1,\infty}_{\text{loc}}(\mathbb{R}; \mathbb{R})$. For $u > \epsilon$, we claim that the quantity $f'\phi^2 - \psi$ is constant. Indeed,

$$
\frac{f'}{f} \phi^2 - \psi = \left( \frac{f'}{f} \right)' \phi^2 + 2 \frac{f'}{f} \phi' \phi' - \phi^2
= \left( \frac{f''}{f} - \frac{f'^2}{f^2} \right) \phi^2 + 2 \frac{f'}{f} \phi' \phi' - \phi^2
= \frac{f''}{f} \phi^2 - \left( \frac{f'}{f} \phi - \phi' \right)^2 = \phi^2 \left( \frac{f''}{f} - \left( \frac{f'}{f} - \frac{\phi'}{\phi} \right)^2 \right)
= 0,
$$

where we used the definition of $\phi$ in the last equality. So for $u > \epsilon$,

$$
f'\phi^2 - f \psi = f \left( \frac{f'}{f} \phi^2 - \psi \right) = f \left( \frac{f(\epsilon)}{f(\epsilon)} \phi^2(\epsilon) - \psi(\epsilon) \right)
\geq f'(\epsilon) \phi^2(\epsilon) - f(\epsilon) \psi(\epsilon) \geq c_6 > 0,
$$

where we used (34) at $u = \epsilon$. Since $f'\phi^2$ is bounded above by a constant on any compact interval of the form $[\epsilon, M]$, we conclude that (34) holds throughout $[0, M]$ for a constant $c > 0$ perhaps smaller. We have just proved that given $\alpha \in [1, 1 + 1/\sqrt{q_0})$ and a bounded positive function $u$, there exists $c > 0$ such that

$$
[f'\phi^2 - f \psi] \circ u \geq c [f'\phi^2] \circ u.
$$

Recall that we established the above inequality in order to apply Lemma 3.6. Unfortunately, since the function $\phi$ we introduced in (35) may not be convex, we cannot apply Lemma 3.6 directly. We make use of (32) instead. In order to obtain a meaningful result, we need to understand how the different functions of $u$ introduced in (32) compare. By definition of $\phi$, we easily deduce the following set of inequalities

$$
[f'\phi^2 - f \psi] \circ u \geq c f' f^{2\alpha} \circ u \circ u \leq C f^{2\alpha} \circ u
$$

So, we just need to relate $f$ and $f'$ to be able to compare all quantities involved in the estimate. Fix $q_1 < q_0$. By definition of $q_0$, there exists a neighborhood of zero where

$$
\frac{f''}{f'^2} \leq 1/q_1.
$$
In particular, \( f'/f^{1/q_1} \) is nonincreasing and in a neighborhood of zero we have

\[
(38) \quad f' \geq cf^{1/q_1}.
\]

By continuity, up to choosing \( c > 0 \) smaller, the above inequality holds in the whole range of a given bounded positive function \( u \). Recall now (37), (38) and apply (32). The estimate reduces to

\[
\int_{\mathbb{R}^N} [f^{1/q_1+2\alpha} \circ u] \eta^2 \, dx \leq C \int_{\mathbb{R}^N} \left[ f^{2\alpha} \circ u \right] \left( |\nabla \eta|^2 + |\eta \Delta \eta| \right) \, dx
\]

Choose \( \eta = \zeta^m \), \( m \geq 1 \), \( \zeta \in C^2_c(\mathbb{R}^N) \), \( 1 \geq \zeta \geq 0 \):

\[
\int_{\mathbb{R}^N} [f^{1/q_1+2\alpha} \circ u] \zeta^{2m} \, dx \leq C \int_{\mathbb{R}^N} \left[ f^{2\alpha} \circ u \right] \left( \zeta^{2m-2} |\nabla \zeta|^2 + \zeta^{2m-1} |\Delta \zeta| \right) \, dx
\]

Using Hölder’s inequality, it follows that

\[
\int_{\mathbb{R}^N} [f^{1/q_1+2\alpha} \circ u] \zeta^{2m} \, dx \leq C \left( \int_{\mathbb{R}^N} \left[ f^{2\alpha m'} \circ u \right] \zeta^{2m} \, dx \right)^{1/m} \left( \int_{\mathbb{R}^N} \left( |\nabla \zeta|^2 + |\Delta \zeta| \right) \, dx \right)^{1/m}.
\]

Assume temporarily that

\[
(39) \quad f^{1/q_1+2\alpha} \circ u \geq c f^{2\alpha m'} \circ u.
\]

Then, the inequality simplifies to

\[
\int_{\mathbb{R}^N} [f^{2\alpha m'} \circ u] \zeta^{2m} \, dx \leq C \int_{\mathbb{R}^N} \left( |\nabla \zeta|^2 + |\Delta \zeta| \right)^m.
\]

Choose now \( \zeta \) such that \( \zeta \equiv 1 \) in \( B_R \) and \( |\nabla \zeta| \leq C/R \), \( |\Delta \zeta| \leq C/R^2 \):

\[
(40) \quad \int_{\mathbb{R}^N} [f^{2\alpha m'} \circ u] \zeta^{2m} \, dx \leq CR^{N-2m},
\]

The above inequality is true as soon as (39) holds, which itself reduces to choosing the exponents such that

\[
2\alpha m' \geq 1/q_1 + 2\alpha.
\]

This holds for some \( q_1 < q_0 \) provided \( 2\alpha(m' - 1) > 1/q_0 \). Since \( \alpha \) can be chosen arbitrarily close to \( 1 + 1/\sqrt{q_0} \) and restricting to \( m' \) less than but as close as we wish to \( \frac{N}{N-2} \), we finally need only assume

\[
(41) \quad \frac{4}{N-2} (1 + 1/\sqrt{q_0}) > 1/q_0.
\]

Since \( m' < \frac{N}{N-2} \), \( N-2m < 0 \). So, the right-hand-side of (41) converges to 0 as \( R \to \infty \), whence \( f \circ u = 0 \) and \( u = 0 \), as desired. Solving (11) for \( q_0 \) yields the conditions stated in Theorem 3.4. \( \square \)
4 Extensions to unbounded and sign-changing solutions

We deal first with possibly unbounded solutions.

**Proof of Corollary 1.7.** Note that by Lemma 3.1 we need only consider the case \( q_0 < +\infty \). We modify the rest of the proof of Theorem 3.4 as follows: take \( \phi \in W^{1,\infty}(\mathbb{R};\mathbb{R}) \) defined by

\[
\phi(u) = \begin{cases} 
    f(u)^\alpha & \text{if } 0 \leq u \leq \epsilon \\
    f(\epsilon)^{\alpha-1} f(u) \exp \left( \int_\epsilon^u \sqrt{f'} \, ds \right) & \text{if } \epsilon < u \leq 1/\epsilon \\
    f(u)^\beta + A & \text{if } u > 1/\epsilon,
\end{cases}
\]

where \( \alpha \) is chosen in \([1, 1 + 1/\sqrt{q_0}]\) as previously, \( \beta \) in \([1, 1 + 1/\sqrt{q_0}]\) and \( A \) such that \( \phi \) is \( W^{1,\infty}_{\text{loc}}(\mathbb{R};\mathbb{R}) \). Then, (40) holds if in addition

\[
\liminf_{u \to +\infty} \frac{f'(\phi^2)}{f'}(u) > 1.
\]

We leave the reader check that this is true under assumption (9), for \( \beta \in [1, 1 + 1/\sqrt{q_0}] \). Apply (32) with \( \eta = \zeta^m, \ m \geq 1, \ \zeta \in C_c^\infty(\mathbb{R}^N), \ 0 \leq \zeta \leq 1 \):

\[
\int_{\mathbb{R}^N} [f' \phi^2 \circ u] \zeta^{2m} \, dx \leq C \int_{\mathbb{R}^N} [(\phi^2 + K) \circ u] \zeta^{2m-2} \left( |\nabla \zeta|^2 + |\Delta \zeta| \right) \, dx
\]

\[
\leq C \left( \int_{\mathbb{R}^N} [(\phi^2 + K)^{m'} \circ u] \zeta^{2m} \, dx \right)^{1/m'} \left( \int_{\mathbb{R}^N} \left( |\nabla \zeta|^2 + |\Delta \zeta| \right)^m \, dx \right)^{1/m}
\]

By definition of \( \phi \) and (38), there exists constants \( c, c' > 0 \) such that for \( u \in [0, 1] \), \( f' \phi^2(u) \geq c f' f^{2\alpha}(u) \geq c' f^{2\alpha + q_1}(u) \), where \( q_1 < q_0 \). We also clearly have \((\phi^2 + K)^{m'}(u) \leq C f^{2\alpha m'}\) for \( u \in [0, 1] \). So,

\[
f' \phi^2 \geq c (\phi^2 + K)^{m'} \quad \text{on } [0, 1],
\]

provided that \( 2\alpha m' \geq 1/q_1 + 2\alpha \). Similarly, the reader will easily check using (9) that given \( q_2 < q_{2\alpha} \), there exists \( c > 0 \) such that

\[
f' \geq c f^{1/\alpha} \quad \text{in } [1, +\infty),
\]

whence \( f' \phi^2 \geq c (\phi^2 + K)^{m'} \) in \([1, +\infty)\) provided that \( 2\beta m' \geq 1/q_2 + 2\alpha \). We conclude that

\[
f' \phi^2 \circ u \geq c (\phi^2 + K)^{m'} \circ u,
\]

provided that \( 2\alpha m' \geq 1/q_1 + 2\alpha \) and \( 2\beta m' \geq 1/q_2 + 2\alpha \). Since \( \alpha \) can be chosen arbitrarily close to \( 1 + 1/\sqrt{q_0} \), \( \beta \) to \( 1 + 1/\sqrt{q_{2\alpha}} \), \( q_1 \) to \( q_0 \), \( q_2 \) to \( q_{2\alpha} \).
and \( m' \) to \( N/(N-2) \), we conclude that suitable parameters can be chosen provided (41) and

\[
\frac{4}{N-2} \left( 1 + \frac{1}{\sqrt{q_0}} \right) > \frac{1}{q_0^\infty}
\]

hold. These inequalities are true under the assumptions of Remark 1.7.

So, collecting (42) and (43), we obtain for some \( m > N/2 \),

\[
\int_{\mathbb{R}^N} \left( (\varphi^2 + K)^{m'} \circ u \right) \zeta^{2m} \, dx \leq C \int_{\mathbb{R}^N} \left( |\nabla \zeta|^2 + |\Delta \zeta| \right)^{m'} \, dx.
\]

Choose at last \( \zeta \) such that \( \zeta \equiv 1 \) in \( B_R \) and \( |\nabla \zeta| \leq C/R \), \( |\Delta \zeta| \leq C/R^2 \); the right-hand side of (44) converges to 0 as \( R \rightarrow \infty \) and the conclusion follows.

We work next with sign-changing solutions.

**Proof of Corollaries 1.8 and 1.10** We simply remark that if \( u \in C^2(\mathbb{R}^N) \) is a solution of (1), then \( u^+ \) (respectively \( u^- \)) is locally Lipschitz continuous and solves the differential inequality (29) (respectively \( -\Delta u \leq \tilde{f}(u^-) \)) in \( \mathbb{R}^N \), where \( \tilde{f}(t) := -f(-t) \) for \( t \in \mathbb{R} \). Since we assumed \( q_0 < +\infty \), we may then apply Theorem 3.4 and Remark 3.5. Corollary 1.8 follows. For Corollary 1.10, we replace Theorem 3.4 by the adaptation presented in the proof of Corollary 1.7.

\[\square\]

## 5 Beyond power-type nonlinearities

**Proof of Theorem 1.11** Case 1 of the theorem was proved in Lemma 3.1. For cases 2 and 3 take \( \alpha \geq 1 \) and \( \varphi = f^\alpha \). Let \( L = \liminf_{0^+} f' \varphi^2 / f \psi \) and let \( (u_n) \) denote a sequence along which \( f' \varphi^2 / f \psi \) converges to \( L \). By Remark 3.3, we may always assume that \( f(0) = 0 \). So, applying Cauchy’s mean value theorem, there exists \( v_n \in (0, u_n) \) such that

\[
\frac{f' \varphi^2}{f \psi}(u_n) = \frac{f' f^{2\alpha-1}}{f \psi}(v_n) = \frac{f'' f^{2\alpha-1} + (2\alpha - 1) f^{2\alpha-2} f'^2}{\alpha^2 f^{2\alpha-2} f'^2} \bigg|_{u=v_n}
\]

Passing to the limit, we obtain

\[
L = \liminf_{0^+} \frac{f' \varphi^2}{f \psi} \geq \frac{1}{\alpha^2} \left( \frac{1}{q_0} + 2\alpha - 1 \right) > 1,
\]

where the last inequality holds if \( \alpha \in [1, 1 + 1/\sqrt{q_0}] \). Note that this interval is nonempty since we assumed \( q_0 < \infty \). At this point, we repeat the steps performed in the proof of Theorem 3.4: from equation (45), we deduce that (44) holds in a neighborhood \( [0, \varepsilon] \) of the origin. Modifying \( \varphi \) as in (36), the verbatim arguments lead to (37) and (38). For the rest of the proof, we argue slightly differently according to the case considered.
Case 2 of Theorem 1.11 In place of (38), we simply use the convexity of \( f \). Since \( u \) is bounded, there exists a constant \( c > 0 \) such that
\[
\frac{f'(u)}{u} \geq cf(u).
\]
So, (40) holds for some \( m > N/2 \) whenever
\[
\frac{2}{N} \left( 1 + \frac{1}{\sqrt{q_0}} \right) > 1,
\]
which is true for \( N \leq 6 \), provided \( q_0 < \infty \). Following the proof of Theorem 3.4, we obtain case 2 of Theorem 1.11.

Case 3 of Theorem 1.11 By definition of \( q_0 \), (38) now holds for \( q_1 < q_0 \).

Resuming our inspection of the proof of Theorem 3.4, we see that (40) holds under assumption 3 of Theorem 1.11 and the desired conclusion follows. \( \square \)

6 Speed of decay: proof of Theorem 1.19

In this section, we characterize the speed of decay of solutions which are stable outside a compact set. To do so, we shall again take advantage of Lemma 3.6 or actually its general form (32), with a different choice of test function \( \phi \circ u \). We divide the proof in several steps.

Step 1. We begin by proving the usual estimate
\[
[f' \phi^2 - f \psi](u) \geq c[f' \phi^2](u)
\]
where this time \( \phi(u) = \left( \frac{f(u)}{u} \right)^{\alpha} \) and \( \alpha \) is chosen in a suitable range.

First, by Lemma 3.4 and Remark 3.3, we may restrict to the case where \( q_0 < +\infty \), whence \( p_0 > 1 \), and we may also assume \( f(0) = f'(0) = 0 \). By Proposition 1.14, \( \lim_{|x| \to \infty} u(x) = 0 \). For \( u \in \mathbb{R}^+ \), take \( \phi \in W^{1,\infty}_{\text{loc}}(\mathbb{R}; \mathbb{R}) \) defined by
\[
\phi(u) = \left( \frac{f(u)}{u} \right)^{\alpha},
\]
where \( \alpha > \frac{1}{2} \). We begin by computing
\[
L = \liminf_{u \to 0^+} \frac{f' \phi^2}{f \psi}(u).
\]
Let \( (u_n) \) denote a sequence along which \( f' \phi^2 / f \psi \) converges to \( L \). Observe that since \( f(0) = f'(0) = 0 \), then \( \psi(0) = 0 \) and
\[
\lim_{u \to 0} f' f^{2\alpha - 1} u^{-2\alpha} = \lim_{u \to 0} \left( \frac{f(u)}{u} \right)^{2\alpha - 1} = 0,
\]
if \( \alpha > 1/2 \). So, applying Cauchy’s mean value theorem, there exists
\( v_n \in (0, u_n) \) such that

\[
\frac{f' \phi^2}{f \psi}(u_n) = \left. \frac{f' f^{2\alpha - 2} u^{-2\alpha}}{\psi} \right|_{u = u_n} = \left. \frac{f'' f^{2\alpha - 1} u^{-2\alpha} + (2\alpha - 1) f'^2 f^{2\alpha - 2} u^{-2\alpha} - 2\alpha f' f^{2\alpha - 2} u^{-2\alpha - 1}}{\alpha^2 u^{-2\alpha - 2} f^{2\alpha} (-1 + u f' / f)^2} \right|_{u = v_n} = \left. \frac{f'' u^2 / f + (2\alpha - 1) f'^2 u^2 / f^2 - 2\alpha u f'/ f}{\alpha^2 (-1 + u f' / f)^2} \right|_{u = v_n} = \left. \frac{f f'' / f^2 + (2\alpha - 1) - 2\alpha f/(uf' )}{\alpha^2 (1 - f/(uf')^2} \right|_{u = v_n}
\]

For \( u \in \mathbb{R}_+^* \), let

\[
p(u) = \left. \frac{uf'(u)}{f(u)} \right|_{u = v_n}
\]

It follows that

\[
\frac{f' \phi^2}{f \psi}(u_n) = \left. \frac{1/q + 2\alpha - 1 - 2\alpha/p}{\alpha^2 (1 - 1/p)^2} \right|_{u = v_n} = \left. 1 + \frac{1/q - (\alpha(1 - 1/p) - 1)}{\alpha^2 (1 - 1/p)^2} \right|_{u = v_n}
\]

We claim that (7) implies

\[
p_0 = \lim_{u \to 0^+} p(u),
\]

where \( p_0 \) is the conjugate exponent of \( q_0 \) i.e. (3) holds. Take indeed any cluster point \( p_1 \) of \( p \) and a sequence \( (u_n) \) such that \( p \) converges to \( p_1 \) along \( (u_n) \). Applying Cauchy’s mean value theorem, there exists \( v_n \in (0, u_n) \) such that

\[
p(u_n) = \left. \frac{f' + uf''}{f'} \right|_{u = v_n} = 1 + p/q(v_n).
\]

Let \( p_0 = \liminf_{u \to 0^+} p(u) \) and \( \overline{p}_0 = \limsup_{u \to 0^+} p(u) \). Pass to the limit as \( n \to +\infty \):

\[
1 + p_0/q_0 \leq p_1 \leq 1 + \overline{p}_0/q_0.
\]

Applying the above inequality to \( p_1 = \overline{p}_0, \overline{p}_0 \), we obtain

\[
\overline{p}_0 (1 - 1/q_0) \leq 1 \leq \overline{p}_0 (1 - 1/q_0)
\]

and (51) follows. Next, we apply (51) in (50). Thus,

\[
L = 1 + \frac{1/q_0 - (\alpha/q_0 - 1)^2}{\alpha^2 / q_0^2}.
\]

So, \( L > 1 \) if

\[
\alpha \in (q_0 - \sqrt{q_0}, q_0 + \sqrt{q_0}).
\]
We conclude that given \( \alpha > 1/2 \) in the range 52, there exists \( c > 0 \) such that for \( u \) small enough

\[
[f' \phi^2 - f \psi](u) \geq c[f' \phi^2](u) \geq c \left( \frac{f(u)}{u} \right)^{2\alpha + 1},
\]

where we used the convexity of \( f \) in the last inequality. Note that since \( u(x) \to 0 \) as \( |x| \to +\infty \), the above inequality holds for \( u = u(x) \) and \( x \) in the complement of a ball of large radius.

**Step 2.** Next, we need to estimate the other functions of \( u \) appearing in (32). We claim that for small values of \( u \),

\[
K(u) \leq C \left( \frac{f(u)}{u} \right)^{2\alpha}.
\]

To see this, it suffices to prove that \( \limsup_{u \to 0} K(u)/\phi^2(u) < \infty \). Take a sequence \((u_n)\) converging to zero and apply Cauchy’s mean value theorem: there exists \( v_n \in (0, u_n) \) such that

\[
\frac{K(u_n)}{\phi^2(u_n)} = \frac{\psi}{2\phi}(v_n).
\]

It follows from (53) that \( f' \phi^2 - f \psi \geq 0 \) for small \( u \). So, \( \psi(v_n) \leq [f' \phi^2/f](v_n) \) for large \( n \) so that

\[
\frac{K(u_n)}{\phi^2(u_n)} \leq \frac{f'(\phi^2)}{2f\phi}(v_n) = \frac{1}{2\alpha(1 - \frac{1}{p(v_n)})}.
\]

Recalling (51) and since we assumed that \( p_0 > 1 \), (54) follows.

**Step 3.** In this step, we prove an estimate of the form

\[
\int_{B_R(x_0)} \left( \frac{f(u)}{u} \right)^{2\alpha + 1} \zeta^{2m} \, dx \leq C R^{N-2m},
\]

where \( m = 2\alpha + 1 \) and \( B_R(x_0) \) is a suitably chosen ball shifted towards infinity.

Choose \( \zeta \in C^2_c(\mathbb{R}^N) \), \( 0 \leq \zeta \leq 1 \) supported outside a ball \( B_{R_0}(0) \) of large radius, so that (32) holds for functions supported outside \( B_{R_0}(0) \) and that (52) and (54) hold for \( u = u(x), \ z \in \text{supp} \zeta \). By Lemma 3.6, we may apply (32) with \( \eta = \zeta \), \( m \geq 1 \). Using (51), (53) and the convexity of \( f \), we obtain for \( \alpha > 1/2 \) in the range (52)

\[
\int_{\mathbb{R}^N} \left( \frac{f(u)}{u} \right)^{2\alpha + 1} \zeta^{2m} \, dx \leq \int_{\mathbb{R}^N} f'(u) \left( \frac{f(u)}{u} \right)^{2\alpha} \zeta^{2m} \, dx
\]

\[
\leq C \int_{\mathbb{R}^N} \left( \frac{f(u)}{u} \right)^{2\alpha} \zeta^{2m-2} \left( |\nabla \zeta|^2 + |\Delta \zeta| \right) \, dx.
\]

Fix \( m = 2\alpha + 1 \) and apply Hölder’s inequality. It follows that

\[
\int_{\mathbb{R}^N} \left( \frac{f(u)}{u} \right)^{2\alpha + 1} \zeta^{2m} \, dx \leq C \int_{\mathbb{R}^N} \left( |\nabla \zeta|^2 + |\Delta \zeta| \right)^{2m} \, dx.
\]
We work on balls shifted towards infinity. More precisely, we take a point $x_0 \in \mathbb{R}^N$ such that $|x_0| > 10R_0$ and set $R = |x_0|/4$. Then, $B(x_0, 2R) \subset \{x \in \mathbb{R}^N : |x| \geq R_0\}$ and we may apply (55) with $\zeta = \varphi(|x-x_0|/R)$ and $\varphi \in C^2_c(\mathbb{R})$ given by

$$\varphi(t) = \begin{cases} 1 & \text{if } |t| \leq 1, \\ 0 & \text{if } |t| \geq 2. \end{cases}$$

We get

$$\int_{B_R(x_0)} \left( \frac{f(u)}{u} \right)^{2\alpha+1} dx \leq C_3 R^{N-2m}.$$

**Step 4.** In this step, we prove the estimate

$$R^\varepsilon \|f(u)/u\|_{L^{N/(N-\varepsilon)}(B(x_0,R))} \leq C$$

By Lemma 4.1, $q_0 \geq 1$. Under the assumptions of Theorem 1.19, we can choose the exponent $m$ so large that for small $\varepsilon > 0$, $m > N/(2-\varepsilon)$ (recall that $m = 2\alpha + 1$ and $\alpha > 1/2$ can be chosen freely in the range [52]).

Furthermore, by Hölder’s inequality and (56), we obtain

$$R^\varepsilon \|f(u)/u\|_{L^{N/(N-\varepsilon)}(B(x_0,R))} \leq CR^\varepsilon \left(R^{N-2m}\right)^{1/m} R^{2-\varepsilon - \frac{N}{2m}} = C.$$

**Step 5.** Now, we think of $u$ as a solution of a linear problem, namely

$$-\Delta u = \frac{f(u)}{u} u := V(x)u \quad \text{in } \mathbb{R}^N.$$

According to classical results of J. Serrin [12] and N. Trudinger [13] (see also Theorem 7.1.1 on page 154 of [11]), for any $p \in (1, +\infty)$ and any $x_0 \in \mathbb{R}^N$, there exists a constant

$$C_S = C_S(R^\varepsilon \|V\|_{L^{N/(N-\varepsilon)}(B(x_0,2R))}) > 0$$

such that

$$\|u\|_{L^\infty(B_R(x_0))} \leq C_S R^{-N/p} \|u\|_{L^p(B_{2R}(x_0))}.$$

Note that for our choice of $x_0$, equation (57) holds and so $C_S$ is a true constant, independent of $R$ and $x_0$.

**Step 6.** The inequality (59) gives a pointwise estimate in terms of an integral average of $u$. In order to control the latter, we consider $\bar{u}$ the average of $u$ over the sphere $\partial B_r(x_0)$, defined for $r > 0$ by $\bar{u}(r) = \int_{\partial B_r(x_0)} u \, d\sigma$. We claim that there exists $C = C(N) > 0$ such that

$$\frac{f(\bar{u}(r))}{\bar{u}(r)} \leq \frac{C}{r^\varepsilon}.$$

To prove this, we first observe that since $f$ is convex, $\bar{u}$ satisfies the differential inequality

$$-\bar{u}'' - \frac{N-1}{r} \bar{u}' \geq f(\bar{u}).$$
Now, since \( f \geq 0 \), \( \tilde{u}' \leq 0 \). In particular \( r \mapsto f(\tilde{u}(r)) \) is nonincreasing. Fix \( \lambda \in (0, 1) \) and integrate the differential inequality between 0 and \( r \):

\[
-\tilde{u}'(r) \geq r^{1-N} \int_0^r s^{N-1} f(\tilde{u}(s)) \, ds \geq r^{1-N} \int_0^{\lambda r} s^{N-1} f(\tilde{u}(s)) \, ds \geq \frac{\lambda^N r f(\tilde{u}(\lambda r))}{N}.
\]

Integrate a second time between \( r \) and \( r/\lambda \). Then,

\[
\tilde{u}(r) \geq \tilde{u}(r/\lambda) + \frac{\lambda^N}{N} \int_{r/\lambda}^r s f(\tilde{u}(s)) \, ds \geq r^2 f(\tilde{u}(r)) \frac{\lambda^N}{2N} \left( \frac{1}{\lambda^2} - 1 \right).
\]

Taking \( \lambda = \frac{N-2}{N} \), \( \text{(61)} \) follows with \( C = \frac{1}{N} \left( \frac{N-2}{N} \right)^N \left( \left( \frac{N-2}{N} \right)^2 - 1 \right) \).

**Step 7.** Recall that we are trying to establish an \( L^p \) estimate, \( p > 1 \) in order to use \( \text{(50)} \). To start with, we use \( \text{(60)} \) to obtain an \( L^1 \) estimate. Indeed, since \( f \) is convex for small \( t \), by Remark 1.20, \( \tilde{u}(r) \geq \tilde{u}(r/\lambda) \) and \( f(\tilde{u}(s)) \leq g(\tilde{u}(s)) \), such that \( \int_{\Omega} f(\tilde{u}(s)) \, ds \leq \int_{\Omega} g(\tilde{u}(s)) \, ds \). Namely, we prove that there exist constants \( C_1, C_2 > 0 \) depending on \( N \) only, such that

\[
\int_{B_R(x_0)} f(u) \, dx \leq C_1 R^{-2} g(C_2/R^2), \tag{61}
\]

where \( g \) is the inverse function of \( t \mapsto \frac{f(t)}{t} \), which exists for small values of \( t \) by Remark 1.20. For simplicity, we write \( B_R \) in place of \( B_R(x_0) \) in what follows. To prove \( \text{(61)} \), observe that for \( r \in (R, 2R) \),

\[
\int_{B_r} f(u) \, dx \leq c_N R^{N-2} \int_{B_r} \frac{1}{r^{1-N}} \, dr \int_{B_r} f(u) \, dx = c_N R^{N-2} \int_{B_r} \frac{1}{r^{1-N}} \, dr \int_{\partial B_r} -\Delta u \, d\sigma = c_N R^{N-2} \int_{B_R} \frac{1}{r^{1-N}} \, dr \int_{\partial B_r} \frac{\partial u}{\partial n} \, d\sigma = c_N R^{N-2} \int_{B_r} \tilde{u}' \, dr \leq c_N R^{N-2} \tilde{u}(R).
\]

Estimate \( \text{(61)} \) follows, using \( \text{(60)} \).

**Step 8.** The assumptions on \( f \) allow us to convert \( \text{(61)} \) into an \( L^p \) estimate. Indeed, since \( q_0 < \infty \) (in fact, one only needs \( \frac{q_0}{q_0} < \infty \)), one can easily check that there exists \( p > 1 \) such that the function \( h(t) = t^{1/p} \) is convex for small \( t \). By Jensen’s inequality,

\[
\frac{1}{R} \int_{B_R} u^p \, dx \leq \int_{B_R} f(u) \, dx \leq C_1 R^{-2} g(C_2/R^2).
\]

By Remark 1.20, \( f \) is invertible and so is \( h \). Composing by \( h^{-1} \), we obtain

\[
\int_{B_R} u^p \, dx \leq C R^N h^{-1}(C_1 R^{-2} g(C_2/R^2)).
\]
Combining this with (59), we finally obtain
\[ \|u\|_{L^\infty(B_R)} \leq C R^{-N/p} \left( R^N h^{-1} \left( C_1 R^{-2} g(C_2/R^2) \right) \right)^{1/p} = C f^{-1} \left( (C_1 R^{-2} g(C_2/R^2)) \right) = C s(R). \]

□

We conclude this section by proving Corollary 1.24. Namely, we improve the rate of decay from $O(s(|x|))$ to $o(s(|x|))$, when additional information on the nonlinearity is available.

**Proof of Corollary 1.24.** To start with, observe that under assumption (18), there exists a constant $C > 0$ such that
\[ s(R) \leq C R^{-2/p} - 1. \]
Recall now (55). We choose a suitable cut-off function $\zeta \in C^2_c(\mathbb{R}^N)$ as follows. Let $\varphi \in C^2_c(\mathbb{R})$ satisfying $0 \leq \varphi \leq 1$ everywhere on $\mathbb{R}$ and
\[ \varphi(t) = \begin{cases} 1 & \text{if } |t| \leq 1, \\ 0 & \text{if } |t| \geq 2. \end{cases} \]
For $s > 0$, let $\theta_s \in C^2_c(\mathbb{R})$ satisfying $0 \leq \theta_s \leq 1$ everywhere on $\mathbb{R}$ and
\[ \theta_s(t) = \begin{cases} 0 & \text{if } |t| \leq s + 1, \\ 1 & \text{if } |t| \geq s + 2. \end{cases} \]
Given $R > R_0 + 3$, we define $\zeta$ at last by
\[ \zeta(x) = \begin{cases} \theta_{R_0}(|x|) & \text{if } |x| \leq R_0 + 3, \\ \varphi(|x|/R) & \text{if } |x| \geq R_0 + 3. \end{cases} \]
Applying (55) with $\zeta$ as above, we deduce that for some constants $C_1, C_2 > 0$,
\[ \int_{B_R \setminus B_{R_0+2}} \left( \frac{f(u)}{u} \right)^{2\alpha + 1} \, dx \leq C_1 + C_2 R^{N - 2m}. \]
Recall that (63) holds for $m = 2\alpha + 1$ and any $\alpha > 1/2$ such that $q_0 - \sqrt{q_0} < \alpha < q_0 + \sqrt{q_0}$. In fact, the restriction $\alpha > 1/2$ can be lifted and replaced by $\alpha > 0$. Indeed, the restriction $\alpha > 1/2$ was used for the sole purpose of proving (18). But (18) clearly holds under the finer assumption (18) for any $\alpha > 0$.

We would like to choose $\alpha$ such that $m := 2\alpha + 1 = N/2$. Since $p_0$ is in the supercritical range (14), straightforward algebraic computations show that such a choice is indeed possible in the range $q_0 - \sqrt{q_0} < \alpha < q_0 + \sqrt{q_0}$. By (63), we deduce that
\[ \int_{\mathbb{R}^N} u^{(p_0-1)\frac{2}{N}} < \infty. \]
In particular, given \( \eta > 0 \) small, there exists \( R > 0 \) so large that given any point \( x_0 \in \mathbb{R}^N \) such that \( |x_0| = 4R \),
\[
\int_{B_R(x_0)} u^{(p_0-1)\frac{N}{2}} < \eta.
\]
We apply again (59), this time with \( p = (p_0 - 1)\frac{N}{2} \) and obtain
\[
\|u\|_{L^\infty(B_R(x_0))} \leq C_S R^{-N/p} \|u\|_{L^p(B_{2R}(x_0))} \leq C_S R^{-\frac{N}{2p-1}}.
\]
This shows that \( u(x) = o(|x|^{-\frac{2}{p_0}}} \). It remains to prove the estimate on \( |\nabla u| \). Observe that any partial derivative \( v = \partial u/\partial x_i \) solves the linearized equation
\[
-\Delta v = f'(u) v \quad \text{in } \mathbb{R}^N.
\]
Apply again the Serrin inequality (59), this time with potential \( \tilde{V}(x) = f'(u) \) and solution \( v \). Since \( 0 \leq f'(u) \leq C u^{p_0-1} \), the potential \( \tilde{V} \) is equivalent to \( V(x) = f(u)/u \) and so the Serrin constant \( C_S \) is again independent of \( R \) and \( x_0 \) under our assumptions. We get
\[
\|v\|_{L^\infty(B_R(x_0))} \leq C_S R^{-N/p} \|v\|_{L^p(B_{2R}(x_0))}.
\]
Serrin’s Theorem (cf. Theorem 1 on page 256 of [12]) also gives the estimate
\[
\|\nabla u\|_{L^p(B_2(x_0))} \leq C_S R^{-1} \|u\|_{L^p(B_{2R}(x_0))}
\]
for solutions of (58). Collecting these inequalities, we obtain
\[
\|\nabla u\|_{L^\infty(B_R(x_0))} \leq C_S R^{-N/p-1} \|u\|_{L^p(B_{2R}(x_0))}.
\]
Using that \( u(x) = o(|x|^{-\frac{2}{p_0}}) \), we obtain the desired estimate. \( \square \)

7 Proof of Theorem 1.23: the subcritical case

By Remark 1.22 since \( p_0 \) is subcritical, we have
\[
\int_{\mathbb{R}^N} f(u)u \, dx < +\infty \quad \text{and} \quad \int_{\mathbb{R}^N} F(u) \, dx < +\infty.
\]
Multiply equation (1) by \( u\zeta \), where \( \zeta \) is a standard cut-off i.e. \( \zeta \equiv 1 \) in \( B_R \), \( \zeta \equiv 0 \) in \( B_{2R} \) and \( |\nabla \zeta| \leq C/R, |\Delta \zeta| \leq C/R^2 \). Then integrate:
\[
\begin{align*}
\int_{\mathbb{R}^N} |\nabla u|^2 \zeta \, dx &+ \int_{\mathbb{R}^N} u\nabla u \nabla \zeta \, dx = \int_{\mathbb{R}^N} f(u)u\zeta \, dx. \\
\int_{\mathbb{R}^N} |\nabla u|^2 \zeta \, dx - \frac{1}{2} \int_{\mathbb{R}^N} u^2 \Delta \zeta \, dx & \geq \int_{\mathbb{R}^N} f(u) \zeta \, dx.
\end{align*}
\]
By Remark 1.22 the second term in the left-hand side of the above equality converges to 0 as \( R \to +\infty \). Hence, by monotone convergence we have
\[
\int_{\mathbb{R}^N} |\nabla u|^2 \, dx = \int_{\mathbb{R}^N} uf(u) \, dx < +\infty.
\]
As in the classical Pohozaev identity, we may now multiply the equation by \( x \cdot \nabla u \zeta \) and obtain

\[
\int_{\mathbb{R}^N} |\nabla u|^2 \, dx = \frac{2N}{N-2} \int_{\mathbb{R}^N} F(u) \, dx.
\]

We now collect (66) and (67). By assumption (14), if \( u \) is not identically zero, then

\[
\int_{\mathbb{R}^N} |\nabla u|^2 \, dx = \int_{\mathbb{R}^N} uf(u) \, dx \leq (p_0+1) \int_{\mathbb{R}^N} F(u) \, dx < \frac{2N}{N-2} \int_{\mathbb{R}^N} F(u) \, dx = \int_{\mathbb{R}^N} |\nabla u|^2 \, dx,
\]

a contradiction. \( \square \)

8 Proof of Theorem 1.25: the supercritical case

In what follows, we prove Theorem 1.25 in the supercritical case i.e. when \( p_0 \) is in the range (15) and \( f \) satisfies (16), (17) and (20). In polar coordinates, a function \( u \) takes the form \( u(r, \sigma) \), where \( r \in \mathbb{R}_+^* \), \( \sigma \in S^{N-1} \), \( N \geq 2 \), while its Laplacian is given by

\[
\Delta u = u_{rr} + \frac{N-1}{r} u_r + \frac{1}{r^2} \Delta_{S^{N-1}} u.
\]

Recall the classical Emden change of variables and unknowns \( t = \ln r \) and \( u(r, \sigma) = r^{-\alpha} v(t, \sigma) \), where \( \alpha = \frac{2}{p_0-1} \). Then,

\[
\begin{align*}
  v(t, \sigma) &= e^{\alpha t} u(e^t, \sigma), \\
  v_t(t, \sigma) &= e^{\alpha t} (e^{2t} u_r + \alpha u), \\
  v_{tt}(t, \sigma) &= e^{\alpha t} (e^{2t} u_{rr} + (2\alpha + 1)e^{t} u_r + \alpha^2 u) \\
  \Delta_{S^{N-1}} v &= e^{\alpha t} \Delta_{S^{N-1}} u.
\end{align*}
\]

Writing

\[
\alpha = \frac{2}{p_0-1}, \quad A = (N-2-2\alpha), \quad B = \alpha^2 + \alpha A,
\]

we obtain

\[
\begin{align*}
v_{tt} + Av_t &= e^{(\alpha+2)t} \left( u_{rr} + \frac{N-1}{r} u_r \right) + Be^{\alpha t} u \\
&= e^{(\alpha+2)t} \left( -e^{-2t} \Delta_{S^{N-1}} u - f(u) \right) + Be^{\alpha t} u \\
&= -e^{(\alpha+2)t} \left( f(e^{-\alpha t} v) \right) - e^{\alpha t} \Delta_{S^{N-1}} v + Bv.
\end{align*}
\]

To summarize, \( v \) solves

\[
v_{tt} + Av_t + Bv + \Delta_{S^{N-1}} v + f(e^{-\alpha t} v)e^{(\alpha+2)t} = 0 \quad \text{for } t \in \mathbb{R}, \sigma \in S^{N-1}.
\]
Multiply the above equation by \( v_t \) and integrate over \( S^{N-1} \). For \( t \in \mathbb{R} \), we find

\[
(71) \quad \int_{S^{N-1}} \left( \frac{v_t^2}{2} \right)_t \, d\sigma + A \int_{S^{N-1}} v_t^2 \, d\sigma + B \int_{S^{N-1}} \left( \frac{v^2}{2} \right)_t \, d\sigma
\]

\[
- \int_{S^{N-1}} \left( \frac{\nabla_{S^{N-1}} v^2}{2} \right)_t \, d\sigma + \int_{S^{N-1}} f(ve^{-\alpha t})v_t e^{(\alpha+2)t} \, d\sigma = 0
\]

Let \( F \) denote the antiderivative of \( f \) such that \( F(0) = 0 \). Then,

\[
\frac{d}{dt} \left[ F(ve^{-\alpha t})e^{(p_0+1)\alpha t} \right] =
\]

\[
f(ve^{-\alpha t})(ve^{-\alpha t} - \alpha ve^{-\alpha t}) e^{(p_0+1)\alpha t} + F(ve^{-\alpha t}) \alpha (p_0 + 1) e^{(p_0+1)\alpha t}.
\]

So,

\[
f(ve^{-\alpha t})v_t e^{p_0 \alpha t} =
\]

\[
\frac{d}{dt} \left[ F(ve^{-\alpha t})e^{(p_0+1)\alpha t} \right] + \alpha f(ve^{-\alpha t}) v_t e^{p_0 \alpha t} - \alpha F(ve^{-\alpha t})(p_0 + 1) e^{(p_0+1)\alpha t}.
\]

Applying (20), we conclude that

\[
f(ve^{-\alpha t})v_t e^{p_0 \alpha t} \geq \frac{d}{dt} \left[ F(ve^{-\alpha t})e^{(p_0+1)\alpha t} \right].
\]

Using this inequality in (71), we obtain

\[
\int_{S^{N-1}} \left( \frac{v_t^2}{2} \right)_t \, d\sigma + A \int_{S^{N-1}} v_t^2 \, d\sigma + B \int_{S^{N-1}} \left( \frac{v^2}{2} \right)_t \, d\sigma
\]

\[
- \int_{S^{N-1}} \left( \frac{\nabla_{S^{N-1}} v^2}{2} \right)_t \, d\sigma + \int_{S^{N-1}} \frac{d}{dt} \left[ F(ve^{-\alpha t})e^{(p_0+1)\alpha t} \right] \, d\sigma \leq 0.
\]

Integrating for \( t \in (-s, s), s > 0 \), we then derive

\[
(72) \quad \frac{1}{2} \left[ \int_{t=-s}^{t=s} v_t^2 \, dt \right]_{t=-s} + A \int_{t=-s}^{t=s} \int_{S^{N-1}} v_t^2 \, d\sigma \, dt + B \int_{t=-s}^{t=s} \left( \frac{v^2}{2} \right)_t \, d\sigma
\]

\[
- \frac{1}{2} \left[ \int_{t=-s}^{t=s} \left( \frac{\nabla_{S^{N-1}} v^2}{2} \right)_t \, d\sigma \right]_{t=-s} + \int_{S^{N-1}} \left. F(ve^{-\alpha t})e^{(p_0+1)\alpha t} \right|_{t=-s} \, d\sigma \leq 0.
\]

Recall the definition of \( v \) given in (83) and use the improved decay estimates (19): we see that \( v(t, \cdot), v_t(t, \cdot), |\nabla_{S^{N-1}} v(t, \cdot)| \) converge to 0 as \( t \to \pm \infty \), uniformly in \( \sigma \in S^{N-1} \). Passing to the limit as \( s \to +\infty \) in (22), we finally obtain

\[
(73) \quad A \int_{\mathbb{R}} \int_{S^{N-1}} v_t^2 \, d\sigma \, dt + \limsup_{s \to +\infty} \int_{S^{N-1}} F(ve^{-\alpha s})e^{(p_0+1)\alpha s} \, d\sigma \leq 0.
\]

Since \( p_0 > \frac{N+2}{2}\), it follows from (89) that \( A > 0 \). So, both terms in (73) are nonnegative. In particular, \( v_t \equiv 0 \) and \( v \) is a function depending only
on $\sigma$. Since $\lim_{t \to +\infty} v(t, \sigma) = 0$ by \[19\], we deduce that $v \equiv 0$ and $u \equiv 0$ as claimed. 

\[\square\]

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