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Type II defects revisited

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ABSTRACT: Energy and momentum conservation in the context of a type II, purely transmitting, defect, within a single scalar relativistic two-dimensional field theory, places a severe constraint not only on the nature of the defect but also on the potentials for the scalar fields to either side of it. The constraint is of an unfamiliar type since it requires the Poisson Bracket of the defect contributions to energy and momentum with respect to the defect discontinuity and its conjugate to be balanced by the potential difference across the defect. It is shown that the only solutions to the constraint correspond to the known integrable field theories.

KEYWORDS: Field Theories in Lower Dimensions, Integrable Field Theories

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1 Introduction

Defects within (relativistic) integrable field theory models in two dimensions have been studied for some time from both classical and quantum viewpoints (see, for example [1–16]). In essence, a defect always involves a discontinuity of some kind, and in an integrable model experience has shown that this discontinuity is a jump in the field value at a specific point (similar to the discontinuity in velocity across a shock in a fluid flow), with ‘sewing’ conditions across the defect relating the fields on either side in such a manner that suitably adjusted conservation laws are maintained. Characteristically, such defects break space translation invariance and are purely transmitting. Intriguingly, insisting upon sewing conditions that maintain the conservation of energy and momentum seems to be sufficient to guarantee integrability. There is no direct proof of this but there is a body of evidence from many specific cases that indicates it should be the case. So far, there are basically two types of defect that appear to be integrable, called type I (where the defect has no degrees of freedom of its own [4, 5]), and type II (where the defect carries its own degrees
of freedom \cite{12, 17, 18}). However, they can be mixed together as they have been recently, for example, to discuss defects within the $d_s^{(3)}$ series of affine Toda field theories \cite{19, 20}. There may be other possibilities, yet to be found, that for example encompass affine Toda field theories based on the $e_r^{(1)}$, $r = 6, 7, 8$ root systems. The aim of this paper is to take the first step at a systematic classification, by examining defect sewing relations required to preserve energy-momentum conservation, but without specifying the field theories themselves, in order to determine the constraints on the field theory potentials. For type I this is straightforward and was carried out previously demonstrating that, for example, within the class of affine Toda field theories only those based on the roots represented by the extended Dynkin diagrams for $a_r^{(1)}$ can support type I defects \cite{5, 8}. The simplest example of the type I defect is included here for comparison with the type II defect, which is more intricate. For type II, the analysis seems to be far from straightforward and the main part of the paper is classifying the possibilities in the simplest of cases where there is a single scalar field defined on each side of the defect. In either situation, the only possibilities are the known integrable field theories except that the Tzitzéica model ($a^{(2)}_2$ affine Toda) is excluded from the set of models supporting type I defects but can support a type II defect. One intriguing possibility is that integrable models are actually characterised by their ability to support integrable discontinuities. However, a proof of that fact, if true, remains distant.

2 The formalism

In this paper, field theories will be analysed by examining carefully the sewing conditions across a defect taking into account the requirements of energy-momentum conservation including contributions from the defect. For the purposes of this article the defect is taken to be situated at $x = 0$ (though in principle it might be situated anywhere along the $x$-axis), with scalar fields $u$ and $v$ to the left and right of it, respectively. There is no a priori assumption that the fields are of the same type, though they often are. In other words, in their respective domains the two fields satisfy the equations

\[ \partial^2 u = -U'(u), \quad (x < 0); \quad \partial^2 v = -V'(v), \quad (x > 0), \]

where $U(u)$ and $V(v)$ are the potentials. The field equations need to be supplemented by conditions relating the fields $u, v$ and/or their derivatives across the defect. The idea is that by making very few assumptions, not only the defect conditions are specified by the requirements, but also the potentials $U, V$.

2.1 Energy

Consider first the contributions to the total energy and how it might be conserved. The time derivative of the contributions to the total energy from the fields to either side of the defect is given (on using the equations of motion) by

\[ \dot{E} = \int_{-\infty}^{0} \left( \frac{1}{2}(u_t^2 + u_x^2) + U(u) \right)_t dx + \int_{0}^{\infty} \left( \frac{1}{2}(v_t^2 + v_x^2) + V(v) \right)_t dx = [u_t u_x]_0^0 + [v_t v_x]_0^0, \]
assuming the contributions from $\pm \infty$ are zero. Thus, the sewing conditions should be designed to convert the right hand side to a total time derivative of the energy contributed by the defect.

One possibility (type I) is to require:

$$x = 0 : \quad u_x = v_t - \mathcal{E}_u, \quad v_x = u_t + \mathcal{E}_v,$$

where $\mathcal{E}$ depends on both $u$ and $v$ and partial derivatives with respect to $u$ or $v$ are denoted by subscripts, then

$$\dot{E} = -u_t \mathcal{E}_u - v_t \mathcal{E}_v = -\frac{d\mathcal{E}}{dt}.$$ 

Thus, the total energy $E + \mathcal{E}$ is conserved.

Another possibility (type II) is to introduce a quantity $\lambda$, defined only at $x = 0$ but depending on time, and then to set

$$x = 0 : \quad u_x = \lambda_t - \mathcal{E}_u, \quad v_x = \lambda_t + \mathcal{E}_v, \quad u_t - v_t = -\mathcal{E}_\lambda,$$

where now $\mathcal{E}$ depends on $u, v$ and $\lambda$, then

$$\dot{E} = -u_t \mathcal{E}_u - v_t \mathcal{E}_v - \lambda_t \mathcal{E}_\lambda = -\frac{d\mathcal{E}}{dt},$$

and $E + \mathcal{E}$ is conserved as before, though in this case $\mathcal{E}$ has additional dependence on $\lambda$. The defect does not break time translation invariance so it is not surprising that little effort is required to conserve energy, and the energy $\mathcal{E}$ introduced by the impurity is unconstrained.

It is also worth recalling that both sets of sewing relations follow directly from Lagrangian descriptions of the defect:

$$\mathcal{L}(u, v) = \mathcal{L}(u)\theta(-x) + \mathcal{L}_D\delta(x) + \mathcal{L}(v)\theta(x) \quad (2.1)$$

with

$$\mathcal{L}(u) = \frac{1}{2}(u_t^2 - u_x^2) - U(u), \quad \mathcal{L}(v) = \frac{1}{2}(v_t^2 - v_x^2) - V(v), \quad (2.2)$$

and with the type I or type II defect Lagrangian $\mathcal{L}_D$ given by

$$\mathcal{L}_I = uv_t - \mathcal{E}(u, v), \quad \mathcal{L}_{II} = (u - v)\lambda_t - \mathcal{E}(u, v, \lambda). \quad (2.3)$$

In these expressions, subscripts denote derivatives with respect to $t$ and $x$, and the defect energy functional $\mathcal{E}$ depends only on the fields not their time (or space) derivatives.

### 2.2 Momentum

In a similar manner, the time derivative of the contributions to the total field momentum is given by

$$\dot{P} = \int_{-\infty}^{0} (u_t u_x)_t \, dx + \int_{0}^{\infty} (v_t v_x)_t \, dx = \left[ \frac{1}{2}(u_t^2 + u_x^2) - U(u) \right]_0^0 + \left[ \frac{1}{2}(v_t^2 + v_x^2) - V(v) \right]_0^0,$$

with the same assumption as before. Since space translation is broken explicitly by the defect the requirement of overall momentum conservation is expected to impose stringent conditions on the fields. The two cases introduced above will be dealt with separately.
2.2.1 Type I

Using the type I sewing conditions (in this section all fields are evaluated at \(x = 0\)):

\[
\dot{P} = -v_t \mathcal{E}_u - u_t \mathcal{E}_v + \frac{1}{2} \mathcal{E}^2_u - \frac{1}{2} \mathcal{E}^2_v - U(u) + V(v) = -\frac{dP}{dt},
\]

where \(P\) is related to \(E\) and strongly constrained by the following relationships:

\[
\mathcal{E}_u = P_v, \quad \mathcal{E}_v = P_u, \quad \frac{1}{2} (\mathcal{E}^2_u - \mathcal{E}^2_v) = U(u) - V(v). \tag{2.4}
\]

These conditions are powerful. The first pair require that \(E \pm P\) is a function of \(u \mp v\). To examine the third condition, it is convenient to define new variables \(p, q\) by

\[
p = \frac{u + v}{2}, \quad q = \frac{u - v}{2}, \quad \text{at} \quad x = 0,
\]

then the last condition of (2.4) becomes

\[
\frac{\mathcal{E}_p \mathcal{E}_q}{2} = U(p + q) - V(p - q).
\]

Then, since \(E = F(p) + G(q), \quad P = F(p) - G(q)\), for some functions \(F, G\), this requires

\[
\frac{F'(p)G'(q)}{2} = U(p + q) - V(p - q),
\]

which restricts possible choices for the potentials \(U, V\). This is because the difference on the right hand side must factor into a function of \(p\) multiplied by a function of \(q\). From this observation, it is straightforward to find the possible solutions for \(F, G, U, V\). It is enough to note that the left hand side must satisfy

\[
(F'(p)G'(q))_{pp} = (F'(p)G'(q))_{qq}
\]

and hence that

\[
\frac{F'''}{F'} = \frac{G'''}{G'} = k^2,
\]

where \(k\) is constant. For example, if \(k \neq 0\)

\[
F'(p) = \alpha e^{kp} + \beta e^{-kp}, \quad G'(q) = \gamma e^{kq} + \delta e^{-kq},
\]

where \(\alpha, \beta, \gamma, \delta\) are also constants. Also, if \(k = 0\) then

\[
F'(p) = \alpha p + \beta, \quad G'(q) = \gamma q + \delta.
\]

Hence, the allowed potentials can be deduced leading to the following possibilities: the fields \(u, v\) can both be free massive (with the same mass), or free massless, or both be Liouville, or both be sine/sinh-Gordon (with the same parameters). Or, one of \(u\) or \(v\) could be free massless and the other could be Liouville. In the latter case both field theories are conformal.
2.2.2 Type II

Using the type II sewing conditions leads to a different type of constraint on the defect contributions to the total energy and momentum. Considering the field contributions to the momentum, following the same steps as in the previous subsection, gives

\[ \dot{P} = -p_t \mathcal{E}_\lambda - \lambda_t \mathcal{E}_p + \frac{1}{2} \mathcal{E}_u^2 - \frac{1}{2} \mathcal{E}_v^2 - U(u) + V(v) = -\frac{dP}{dt}, \]

which, assuming \( P \) is a function only of \( q, p, \lambda \), and noting \( \frac{dP}{dt} = q_t \mathcal{P}_q + p_t \mathcal{P}_p + \lambda_t \mathcal{P}_\lambda = -\left( \frac{1}{2} \mathcal{E}_\lambda \mathcal{P}_q - p_t \mathcal{P}_p - \lambda_t \mathcal{P}_\lambda \right) \), requires

\[ \mathcal{E}_\lambda = \mathcal{P}_p, \quad \mathcal{E}_p = \mathcal{P}_\lambda, \quad \frac{1}{2} (\mathcal{P}_\lambda \mathcal{E}_q - \mathcal{P}_q \mathcal{E}_\lambda) = U(p + q) - V(p - q). \]

The last of these is intriguing because as far as the defect contribution to the Lagrangian (2.3) is concerned \( \lambda \) and \( q \) are conjugate variables. Thus, the nonlinear relationship states that the Poisson bracket with respect to these conjugate variables of the defect energy and momentum is twice the ‘potential difference’ across the defect.

Now, since \( \mathcal{E}, \mathcal{P} \) are functions of \( \lambda, p, q \) and \( \mathcal{E} \pm \mathcal{P} \) is a function of \( p \pm \lambda \) together with \( q \), it follows that

\[ \mathcal{E} = F(p + \lambda, q) + G(p - \lambda, q), \quad \mathcal{P} = F(p + \lambda, q) - G(p - \lambda, q). \]

Then, explicitly in terms of \( F, G \) the nonlinear Poisson Bracket constraint is:

\[ F_\lambda G_q - F_q G_\lambda = \{ F, G \} = U(p + q) - V(p - q). \quad (2.5) \]

The constraint equation (2.5) is powerful because the left hand side depends on \( \lambda \) while the right hand side does not.

While several examples are known the general solution to (2.5) is not yet clear. The objective in this article is to describe an approach to solving a functional equation of this unfamiliar type in which all four functions \( F, G, U, V \) are strongly constrained. In particular, it is necessary to investigate whether or not there are any solutions beyond those known already all of which correspond to integrable field theories, namely, sine-Gordon, Tzitzića, Liouville and massive or massless free.

3 An approach to solving the Poisson bracket equation

One approach, used with success previously [12], is to guess that solutions for \( F, G \) must be sums of exponentials. An alternative might be to try to be systematic, assume each has a Taylor expansion and write

\[ F(p + \lambda, q) = \sum_{k=0}^{\infty} \frac{(p + \lambda)^k}{2^k k!} f_k(q), \quad G(p - \lambda, q) = \sum_{l=0}^{\infty} \frac{(p - \lambda)^l}{2^l l!} g_l(q). \]
Then the Poisson bracket relation becomes:

\[ F_\lambda G_q - F_q G_\lambda = \frac{1}{2} \sum_{k,l} \frac{(p + \lambda)^k (p - \lambda)^l}{2^k! 2^l!} (f_{k+1} g'_l + f'_k g_{N-k+1}). \]

The latter can be rewritten (grouping together terms of constant \( N = k + l \)) as

\[ F_\lambda G_q - F_q G_\lambda = \frac{1}{2} \sum_{N=0}^{\infty} \sum_{k=0}^{N} \frac{(p + \lambda)^k (p - \lambda)^N-k}{2^k! 2^{N-k}(N-k)!} (f_{k+1} g'_{N-k} + f'_k g_{N-k+1}), \]

which seems to require the coefficients of each term in the set of terms corresponding to a particular \( N \) to be the same (apart from the factorial factors) so that gathering the terms together they can be recognised as being the coefficients in the binomial expansion of \((p + \lambda + p - \lambda)^N = (2p)^N\), which is clearly independent of \( \lambda \), as required. In other words,

\[ F_\lambda G_q - F_q G_\lambda = \frac{1}{2} \sum_{N=0}^{\infty} \sum_{k=0}^{N} \frac{p^N}{N!} h_N(q), \]

where

\[ h_N(q) = f_{k+1} g'_{N-k} + f'_k g_{N-k+1}, \quad k = 0, \ldots, N. \quad (3.1) \]

On the other hand, assuming the potentials also have a Taylor expansion, the right hand side can be written

\[ U(p + q) - V(p - q) = \frac{1}{2} \sum_{N=0}^{\infty} \sum_{k=0}^{N} \frac{p^N}{N!} \left( U^{(N)}(q) - V^{(N)}(-q) \right) \]

where the superscript \((N)\) denotes the \(N^{th}\) derivatives of \( U, V\). Hence, formally,

\[ h_N(q) = U^{(N)}(q) - V^{(N)}(-q). \]

The aim is to find compatible expressions for the \( g, f \) and \( h \) sequences of functions of \( q \) in such a way as to be able to reconstruct the functions \( G \) and \( F \) and then seek potentials \( U, V \) such that (2.5) will be satisfied.

In order to achieve this, assuming that none of the coefficients \( f_k, g_k \) vanish, notice first that the expressions (3.1) can be rearranged to

\[ h_N = \frac{f_{k+1} g_{N-k+1}}{f_{k+1} g_{N-k+1}} = a_{N-k+1} + b_{k+1}, \quad k = 0, \ldots, N, \quad N = 0, 1, 2, \ldots \quad (3.3) \]

where

\[ a_{N-k+1} = \frac{g'_{N-k}}{g_{N-k+1}}, \quad b_{k+1} = \frac{f'_k}{f_{k+1}}. \quad (3.4) \]

4 Special case: the sinh-Gordon model

The simplest special case to analyse assumes the two potentials \( U, V \) are the same and even. In other words \( U(q) = V(q) = U(-q) \) and hence, \( h_N(q) = 0 \) when \( N \) is even. Then
it follows directly from (3.3) and (3.4) that \( a_l = -b_l \) for all positive integers \( l \). Moreover, \( a_l = a_2 \) if \( l \) is an even positive integer and \( a_l = a_1 \) if \( l \) is odd. Hence relations (3.3) can be rewritten to involve only the functions \( a_1, a_2 \). Thus, for instance

\[
\begin{align*}
    a_2 - a_1 &= \frac{h_1}{f_1 g_2} = -\frac{h_1}{f_2 g_1}, \quad N = 1, \\
    a_2 - a_1 &= \frac{h_3}{f_1 g_4} = -\frac{h_3}{f_2 g_3} = \frac{h_3}{f_3 g_2} = -\frac{h_3}{f_4 g_1}, \quad N = 3,
\end{align*}
\]

and so on. Comparing these for different \( N \) then implies relations among the \( f_l, g_l \) themselves. For example,

\[
    h_3 = \frac{h_1 g_3}{g_1} = \frac{h_1 g_4}{g_2}, \quad \Rightarrow \quad \frac{g_3}{g_1} = \frac{g_4}{g_2}.
\]

On the other hand \( a_1 = a_3 \) and \( a_2 = a_4 \), which implies

\[
    \frac{g_3}{g_1} = \frac{g_2'}{g_0'}, \quad \frac{g_4}{g_2} = \frac{g_3'}{g_1'}.
\]

It follows that

\[
    \frac{g_3}{g_1} = \frac{g_3'}{g_1'},
\]

which in turn implies

\[
    g_3 = \alpha g_1,
\]

where \( \alpha \) is a constant. Hence,

\[
    g_2 = \alpha g_0 + c, \quad g_3 = \alpha g_1, \quad g_4 = \alpha^2 g_0 + \alpha c, \quad h_3 = \alpha h_1,
\]

where \( c \) is also a constant. Thus, in general:

\[
    g_{2k+1} = \alpha g_{2k-1}, \quad g_{2k+2} = \alpha g_{2k}, \quad h_{2k+1} = \alpha h_{2k-1}, \quad k = 1, \ldots
\]

implying

\[
    g_{2k+1} = \alpha^k g_1, \quad g_{2k} = \alpha^k g_0 + \alpha^{k-1} c, \quad h_{2k+1} = \alpha^k h_1, \quad k = 1, \ldots
\]

In order to find expressions for members of the sequence of \( \{f_l\} \), remember that \( b_1 = -a_1 \) and \( b_2 = -a_2 \), which implies

\[
    f_1 = -\frac{f_0 g_1}{g_0'}, \quad f_2 = -\frac{f_1 g_2}{g_1'}.
\]

On the other hand, the first line of (4.1) requires

\[
    f_2 = -\frac{f_1 g_2}{g_1'}.
\]

Equating the two expressions for \( f_2 \) gives

\[
    \frac{f_1}{f_1'} = \frac{g_1}{g_1'} \quad \Rightarrow \quad f_1 = \beta g_1,
\]
where $\beta$ is a constant. It follows that

$$f_0' = -\beta g_0', \quad f_2 = -\beta(\alpha g_0 + c), \quad f_3 = \beta \alpha g_1, \quad f_4 = -\beta \alpha(\alpha g_0 + c),$$

and hence

$$f_{2k+1} = \beta \alpha^k g_1, \quad f_{2k} = -\beta(\alpha^k g_0 + \alpha^{k-1} c).$$

Finally, still using (4.1),

$$h_1 = f_1 g_2(a_2 - a_1) = \beta \left( g_1' - \alpha g_0 g_0' - c g_0 \right).$$

In summary:

$$g_{2k+1} = \alpha^k g_1, \quad f_{2k+1} = \beta \alpha^k g_{2k+1}, \quad k = 0, 1, \ldots$$

$$f_0 = -\beta g_0 + d, \quad g_{2k} = \alpha^k g_0 + \alpha^{k-1} c, \quad f_{2k} = -\beta g_{2k}, \quad k = 1, 2, \ldots,$$

$$h_1 = \frac{\beta}{2} \left( g_1^2 - \alpha g_0^2 - 2 c g_0 \right)' \quad h_{2k+1} = \alpha^k h_1, \quad k = 0, 1, \ldots.$$

Here, $g_0, g_1$ are undetermined functions of $q$, and $\alpha, \beta, c,$ and $d$ are constants. Using this data, the reconstructed $F$ and $G$ functions are:

$$F(p + \lambda, q) = -\beta g_0 \cosh \left( \frac{\sqrt{\alpha}(p + \lambda)}{2} \right) - \frac{\beta c}{\alpha} \left( \cosh \left( \frac{\sqrt{\alpha}(p + \lambda)}{2} \right) - 1 \right)$$

$$+ \frac{\beta g_1}{\sqrt{\alpha}} \sinh \left( \frac{\sqrt{\alpha}(p + \lambda)}{2} \right) + d$$

$$G(p - \lambda, q) = g_0 \cosh \left( \frac{\sqrt{\alpha}(p - \lambda)}{2} \right) + \frac{c}{\alpha} \left( \cosh \left( \frac{\sqrt{\alpha}(p - \lambda)}{2} \right) - 1 \right)$$

$$+ \frac{g_1}{\sqrt{\alpha}} \sinh \left( \frac{\sqrt{\alpha}(p - \lambda)}{2} \right).$$

Then

$$F_{\lambda} G_q - F_q G_{\lambda} = \frac{\beta}{2 \sqrt{\alpha}} \left( g_1 g_1' - \alpha g_0 g_0' - c g_0' \right) \sinh(\sqrt{\alpha} p) = U(p + q) - U(p - q).$$

To satisfy this relation requires

$$g_1 g_1' - \alpha g_0 g_0' - c g_0' = A \left( e^{\sqrt{\alpha} q} - e^{-\sqrt{\alpha} q} \right),$$

from which it follows that

$$U(u) = \frac{A \beta}{4 \sqrt{\alpha}} \left( e^{\sqrt{\alpha} u} + e^{-\sqrt{\alpha} u} \right),$$

which correspond to the sinh-Gordon potential.

Note: if $\alpha = 0$, then

$$F(p + \lambda, q) = -\frac{\beta c}{2} \left( \frac{p + \lambda}{2} \right)^2 - \beta g_0 + d + \beta g_1 \left( \frac{p + \lambda}{2} \right),$$

$$G(p - \lambda, q) = \frac{c}{2} \left( \frac{p - \lambda}{2} \right)^2 + g_0 + g_1 \left( \frac{p - \lambda}{2} \right),$$
and

\[ F_\lambda G_q - F_q G_\lambda = U(p + q) - U(p - q) = \frac{\beta p}{2} (g_1 g'_1 - c q_0). \]

The only non-zero solution to this requires

\[ g_1 g'_1 - c q_0 \sim q, \]

and leads to the potential for a free massive scalar field,

\[ U(u) = \frac{\beta}{8} u^2. \]

5 General case

Consider a pair of relations (3.3), which share one of the ratios appearing on their right hand side and then subtract them. If this operation is performed for all possible pairs sharing a common ratio, the following expressions are found

\[
\begin{align*}
    f_{k+1} &= \frac{h_{k+s} g_{s+1} - h_{k+s} r_{s+1}}{g'_s g_{s+1} - g'_s r_{s+1}}, \quad f'_k = \frac{h_{k+s} g'_r - h_{k+s} r'_s}{g'_s g_{s+1} - g'_s r_{s+1}}, \quad r \neq s = 0, 1, \ldots, k = 0, 1, \ldots \\
    g_{k+1} &= \frac{h_{k+s} f_{s+1} - h_{k+s} f_{s+1}}{f'_s f_{s+1} - f'_s r_{s+1}}, \quad g'_k = \frac{h_{k+s} f'_r - h_{k+s} f'_s}{f'_s f_{s+1} - f'_s r_{s+1}}, \quad r \neq s = 0, 1, \ldots, k = 0, 1, \ldots
\end{align*}
\]

(5.1)

where formulas in the first and second lines are obtained taking into account 'f-common' ratios and 'g-common' ratios, respectively.

Consider first only a subset of these expressions. The strategy is to find a solution for the subset and look for a pattern that allows a generalisation of the formulas found to all \( f, g, h \)-functions. Then verify whether these expressions satisfy all (5.1) relations or whether the remaining (5.1) introduce further constraints on the possible solution. The subset adopted contains the expressions, for which the pairs of indices \((r, s)\) in (5.1) are \((0, 1), (1, 2), (0, 2)\). Combine the two expressions obtained for each pair of indices \((r, s)\) by eliminating the \( f \)-functions. Then the relations found are:

\[
\begin{align*}
    g_{k+1} &= \begin{bmatrix} h_k & h_{k+1} & 0 \\ h_0 & h_1 & g_1 \\ h_1 & h_2 & g_2 \\ H_A \end{bmatrix}, &
    g'_k &= \begin{bmatrix} h_k & h_{k+1} & 0 \\ h_0 & h_1 & g'_1 \\ h_1 & h_2 & g'_1 \\ H_A \end{bmatrix}, &
    g_{k+1} &= \begin{bmatrix} h_{k+1} & h_{k+2} & 0 \\ h_2 & h_3 & g_2 \\ h_3 & h_4 & g_3 \\ H_B \end{bmatrix}, \\
    g'_{k+1} &= \begin{bmatrix} h_k & h_{k+1} & 0 \\ h_0 & h_2 & g_0 \\ h_2 & h_3 & g_1 \\ H_C \end{bmatrix}, &
    g'_k &= \begin{bmatrix} h_{k+2} & 0 \\ h_0 & h_2 & g'_0 \\ h_2 & h_3 & g'_0 \\ H_C \end{bmatrix},
\end{align*}
\]

(5.2)
where

\[
H_A = \begin{vmatrix} h_1 & h_0 \\ h_2 & h_1 \end{vmatrix} = g'_0 & g_1 \\ g'_1 & g_2 \end{vmatrix} = G_A F_A, \\
H_B = \begin{vmatrix} h_3 & h_2 \\ h_4 & h_3 \end{vmatrix} = g'_2 & g_3 \\ g'_3 & g_4 \end{vmatrix} = G_B F_B, \\
H_C = \begin{vmatrix} h_2 & h_0 \\ h_4 & h_2 \end{vmatrix} = g'_0 & g_1 \\ g'_2 & g_3 \end{vmatrix} = G_C F_C. \\
(5.4)
\]

The assumption is that \( H_A, H_B, H_C \) are different from zero. The cases in which these determinants are zero do not lead to new results. An example of these cases will be discussed in appendix B.

Look, for instance, at the expressions with \( H_A \). It can be noticed that for \( k = 0 \) and \( k = 1 \) these relations are identically satisfied. Additional information starts to emerge for \( k = 2 \). Similar considerations can be applied to all the other expressions. Then, by expanding the determinants with respect to their \( g \)-column, the first non trivial relations from each expression in (5.2), (5.3) are:

\[
g_3 H_A = g_2 \Lambda - g_1 \Delta, \quad g_1 H_B = g_2 \Gamma - g_3 \Delta, \quad g_2 H_C = g_3 \Lambda + g_1 \Gamma, \quad (5.5)
\]

and

\[
g'_2 H_A = g'_1 \Lambda - g'_0 \Delta, \quad g'_0 H_B = g'_1 \Gamma - g'_2 \Delta, \quad g'_1 H_C = g'_2 \Lambda + g'_0 \Gamma, \quad (5.6)
\]

where

\[
\Lambda = \begin{vmatrix} h_2 & h_3 \\ h_0 & h_1 \end{vmatrix}, \quad \Delta = \begin{vmatrix} h_2 & h_3 \\ h_1 & h_2 \end{vmatrix}, \quad \Gamma = \begin{vmatrix} h_2 & h_3 \\ h_4 & h_3 \end{vmatrix}.
\]

After some algebra, they lead to

\[
g_3 = g_2 \frac{\Lambda}{H_A} - g_1 \frac{\Delta}{H_A}, \quad g'_2 = g'_1 \frac{\Lambda}{H_A} - g'_0 \frac{\Delta}{H_A}, \quad (5.7)
\]

\[
g_2 (\Gamma H_A - \Lambda \Delta) = g_1 (H_B H_A - \Delta^2), \quad g_2 (H_C H_A - \Lambda^2) = g_1 (\Gamma H_A - \Lambda \Delta),
\]

\[
g'_2 (\Gamma H_A - \Lambda \Delta) = g'_1 (H_B H_A - \Delta^2), \quad g'_2 (H_C H_A - \Lambda^2) = g'_1 (\Gamma H_A - \Lambda \Delta),
\]

where the compatibility condition reads

\[
(H_B H_A - \Delta^2) (H_C H_A - \Lambda^2) = (\Gamma H_A - \Lambda \Delta)^2.
\]

Notice that it is possible to write the determinants \( \Lambda, \Delta \) and \( \Gamma \) as products of \( F \) and \( G \)-determinants (5.4). Better still, the latter and the \( H \)-determinants as well can be written as products of only \( F_A, G_A, G_B \) and \( G_C \). In fact

\[
H_A = \frac{F_A}{G_A} G_A^2, \quad H_B = \frac{F_A}{G_A} G_B^2, \quad H_C = \frac{F_A}{G_A} G_C^2, \quad F_B = \frac{F_B}{G_B} G_B, \quad F_C = \frac{F_C}{G_C} G_C, \quad (5.8)
\]

\[
\Lambda = \frac{F_A}{G_A} G_A G_C, \quad \Delta = \frac{F_A}{G_A} G_B G_A, \quad \Gamma = \frac{F_A}{G_A} G_C G_B.
\]
It follows that
\[ H_B H_A - \Delta^2 = H_C H_A - \Lambda^2 = \Gamma H_A - \Lambda \Delta = 0 \]
and also
\[ H_B H_C - \Gamma^2 = \Lambda H_B - \Delta \Gamma = \Delta H_C - \Lambda \Gamma = 0, \]
which is equivalent to
\[
\begin{vmatrix} h_0 & h_1 & h_2 \\ h_1 & h_2 & h_3 \\ h_2 & h_3 & h_4 \end{vmatrix} = 0. \tag{5.9}
\]
The expressions (5.7) become
\[
g_3 = g_2 \frac{G_C}{G_A} - g_1 \frac{G_B}{G_A}, \quad g'_2 = g'_1 \frac{G_C}{G_A} - g'_0 \frac{G_B}{G_A}. \tag{5.10}
\]
Finally from (5.9) it possible to infer the following
\[
h_2 = h_1 \frac{G_C}{G_A} - h_0 \frac{G_B}{G_A}, \quad h_3 = h_2 \frac{G_C}{G_A} - h_1 \frac{G_B}{G_A}, \quad h_4 = h_3 \frac{G_C}{G_A} - h_2 \frac{G_B}{G_A}.
\]
It seems that a pattern starts to emerge. In order to explore it, consider the expressions with \( H_A \) in (5.2) for \( k = 3 \). They lead to
\[
g_4 = g_3 \frac{G_C}{G_A} - g_2 \frac{G_B}{G_A}, \quad g'_3 = g'_2 \frac{G_C}{G_A} - g'_1 \frac{G_B}{G_A}. \tag{5.11}
\]
On the other hand the last expression with \( H_B \) in (5.2) for \( k = 3 \) and the middle expression with \( H_A \) for \( k = 4 \) lead to
\[
h_5 = h_4 \frac{G_C}{G_A} - h_3 \frac{G_B}{G_A}, \quad g'_4 = g'_3 \frac{G_C}{G_A} - g'_2 \frac{G_B}{G_A}. \tag{5.12}
\]
Then, differentiating expressions for \( g_3, g_4 \) in (5.10), (5.11) and comparing them with expressions for \( g'_3, g'_4 \) in (5.11), (5.12), it is found
\[
g_2 \left( \frac{G_C}{G_A} \right)' = g_1 \left( \frac{G_B}{G_A} \right)' \quad \text{and} \quad g_3 \left( \frac{G_C}{G_A} \right)' = g_2 \left( \frac{G_B}{G_A} \right)'.
\]
These expressions are satisfied if \( G_C/G_A \) and \( G_B/G_A \) are constants or if
\[
\frac{g_3}{g_2} = \frac{g_2}{g_1} \Rightarrow G_C = G_A \left( \frac{g_2}{g_1} \right) + G_B \left( \frac{g_1}{g_2} \right)
\]
and
\[
\frac{g_1}{g_2} = \frac{G'_C G_A - G'_A G_C}{G'_B G_A - G'_A G_B} \Rightarrow G_A \left( \frac{g_2}{g_1} \right) \left( G_A - G_B \left( \frac{g_2}{g_1} \right)^2 \right) = 0.
\]
Since \( G_A \neq 0 \) and \( (g_2/g_1)' \neq 0, \) it is found
\[
\frac{G_B}{G_A} = \left( \frac{g_2}{g_1} \right)^2, \quad \frac{G_C}{G_A} = 2 \left( \frac{g_2}{g_1} \right),
\]
\footnote{In fact, \((g_2/g_1)' = 0\) implies \(H_B = 0\), which also must be different from zero.}
where the latter is obtained using the expression for \(g_3\) in (5.10).

Before summarising the results obtained so far, a few words about the \(f\)-functions are necessary. Because of the symmetry between the \(g\) and the \(f\)-functions, an analysis started with expressions similar to the ones in (5.2), (5.3) with the \(g\)-functions replaced by the \(f\)-functions, would have led to similar results. Note also the relations \(F_C/F_A = G_C/G_A\) and \(F_B/F_A = G_B/G_A\) in (5.8). Taking all of this into account, the tentative, uncompleted solutions are:

**Solution A:**

\[
\begin{align*}
\frac{G_C}{G_A} &= \frac{F_C}{F_A} = 2\xi, & \frac{G_B}{G_A} &= \frac{F_B}{F_A} = \xi^2, & \xi &= \frac{g_2}{g_1}, & f_2 &= f_1\xi, \\
g_0' &= \frac{g_1'}{\xi} - \frac{g_2'}{\xi^2}, & f_0' &= \frac{f_1'}{\xi} - \frac{f_1\xi'}{\xi^2} \\
g_{k+1} &= 2\xi g_k - \xi^2 g_{k-1}, & f_{k+1} &= \xi^k f_1, & h_k &= 2\xi h_{k-1} - \xi^2 h_{k-2}, & k &= 2, 3, \ldots
\end{align*}
\]

where \(\xi\) is a function of \(q\) and it cannot be a constant and

**Solution B:**

\[
\begin{align*}
\frac{G_C}{G_A} &= \frac{F_C}{F_A} = a, & \frac{G_B}{G_A} &= \frac{F_B}{F_A} = b, \\
g_2 &= a g_1 - bg_0 + c, & f_2 &= a f_1 - b f_0 + d, \\
g_{k+1} &= ag_k - bg_{k-1}, & f_{k+1} &= af_k - bf_{k-1}, & h_k &= ah_{k-1} - bh_{k-2}, & k &= 2, 3, \ldots
\end{align*}
\]

where \(a, b, c, d\) are constants.

### 5.1 Solution A

For solution A, the missing functions \(h_0\) and \(h_1\) can be found using (3.1). Then, the relations for solutions A can be rewritten in simple forms as

\[
\begin{align*}
g_k' &= \left(\frac{g_1}{\xi}\right)', & f_k' &= \left(\frac{f_1}{\xi}\right)', & g_{k+1} &= \xi^k g_1, & f_{k+1} &= \xi^k f_1, & k &= 0, 1, \ldots \\
\xi(q) &= \frac{g_2}{g_1}, & h_k &= \xi^k \left( g_1 \left(\frac{f_1}{\xi}\right)' + f_1 \left(\frac{g_1}{\xi}\right)' + \frac{k f_1 g_1 \xi'}{\xi^2} \right), & k &= 0, 1, \ldots
\end{align*}
\]

where \(g_0', g_1, g_2, f_0', f_1\) are free functions of \(q\). These expressions can be used to verify that all (5.1) relations are satisfied. Then, \(G\) and \(F\) functions can be reconstructed. They are:

\[
\begin{align*}
F(p + \lambda, q) &= f_0 + \frac{f_1}{\xi} \left( e^{\xi(p+\lambda)/2} - 1 \right), & G(p - \lambda, q) &= g_0 + \frac{g_1}{\xi} \left( e^{\xi(p-\lambda)/2} - 1 \right).
\end{align*}
\]

It follows that

\[
F_\lambda G_q - F_q G_\lambda = \frac{e^{p\xi}}{2} \left( f_1 \left(\frac{g_1}{\xi}\right)' + g_1 \left(\frac{f_1}{\xi}\right)' + p f_1 g_1 \xi' \right).
\]

Given that the function \(\xi\) cannot be a constant, there are no potentials \(U\) and \(V\) such that (2.5) is satisfied.
5.2 Solution B

Solution B seems to be more complicated to analyse. Similarly to what has been done for solution A, it is possible to obtain expressions for $h_0$ and $h_1$ using (3.1). They are:

\[ h_0 = f'_0 g_1 + f_1 g'_0, \]
\[ h_1 = f_1 f'_1 + g'_0 (a f_1 - b f_0 + d) = f_1 g'_1 + f'_0 (a g_1 - b g_0 + c). \] (5.16)

The second line provides a constraint. Before investigating this constraint, it is useful to look at the expressions for $h_2$ provided by (3.1), that is:

\[ h_2 = g_1 f'_2 + g'_0 f_3 = f'_0 g_3 + f_1 g'_2 = g_2 f'_1 + g'_1 f_2. \]

Using (5.14), it is easy to see that the first two expressions for $h_2$ can be rewritten as $h_2 = ah_1 - bh_0$. On the other hand, the third expression becomes

\[ h_2 = h_1 \left( \frac{g'_1}{g_0} + \frac{f'_1}{f_0} \right) - h_0 \left( \frac{g'_1 f'_1}{g_0 f_0} \right), \]

which implies

\[ \frac{g'_1}{g_0} + \frac{f'_1}{f_0} = a, \quad \frac{g'_1 f'_1}{g_0 f_0} = b. \]

Hence

\[ \left( \frac{g'_1}{g_0} \right)^2 - a \left( \frac{g'_1}{g_0} \right) + b = 0 \]

with roots

\[ \alpha = \frac{a}{2} + \sqrt{\frac{a^2 - 4b}{2}}, \quad \beta = \frac{a}{2} - \sqrt{\frac{a^2 - 4b}{2}}, \quad a = \beta + \alpha, \quad b = \alpha \beta. \]

Then

\[ g_1 = \alpha g_0 + \gamma, \quad f_1 = \beta f_0 + \delta, \] (5.17)

where $\gamma$ and $\delta$ are constants.

Before going back to the constraint in (5.16), notice that the tentative solution (5.14) can be rewritten in a more compact formulation using only the functions $g_0, g_1, f_0, f_1, h_0$ and $h_1$, as

\[ g_{k+1} = A_k (a g_1 - b g_0 + c) - A_{k-1} b g_1, \quad f_{k+1} = A_k (a f_1 - b f_0 + d) - A_{k-1} b f_1, \]
\[ h_{k+1} = A_k (a h_1 - b h_0) - A_{k-1} b h_1, \]
\[ A_{k+1} = a A_k - b A_{k-1}, \quad A_0 = 0, \quad A_1 = 1, \quad k = 1, 2, \ldots . \] (5.18)

Then, using (5.17), and the constant $\alpha, \beta$ instead of $a, b$, these expressions become

\[ g_{k+1} = \alpha (A_{k+1} - A_k \beta) g_0 + A_{k+1} \gamma, \quad f_{k+1} = \beta (A_{k+1} - A_k \alpha) f_0 + A_{k+1} \delta, \]
\[ h_{k+1} = A_{k+1} h_1 - \alpha \beta A_k h_0, \]
\[ A_{k+1} = (\alpha + \beta) A_k - \alpha \beta A_{k-1}, \quad A_0 = 0, \quad A_1 = 1, \quad k = 1, 2, \ldots , \] (5.19)
and the $h_0$ and $h_1$ functions in (5.16) are:

$$h_0 = f_0'g_0\alpha + f_0g_0'\beta + f_0'\gamma + g_0'\delta, \quad 2h_1 = (\alpha + \beta)h_0 + g_0'\alpha\delta + f_0'\beta\gamma,$$

where the constants of integrations, $c$ and $d$, have been absorbed into the constants $\gamma$ and $\delta$.

Now it is time to analyse the constraint in (5.16). It reads:

$$(\alpha - \beta)(\beta g_0f_0 + \alpha g_0f_0') + f_0'\gamma\alpha - g_0'\delta\beta = 0.$$  \hspace{1cm} (5.20)

There are two possibilities that will be explored in the next two subsections.

### 5.2.1 Solution B₁

If $\alpha = \beta$ the constraint (5.20) simplifies to

$$f_0'\gamma = g_0'\delta, \quad \Rightarrow \quad f_0 = \frac{\delta}{\gamma} g_0 + \varepsilon,$$  \hspace{1cm} (5.21)

where $\varepsilon$ is a constant and the functions $h_0, h_1$ become

$$h_0 = g_0 g_0' 2\frac{\alpha}{\gamma} + g_0' (2\delta + \alpha\varepsilon), \quad h_1 = \alpha(h_0 + g_0'\delta).$$  \hspace{1cm} (5.22)

Finally, it can be easily notice that $A_k$ in (5.19) can be rewritten as $A_k = k\alpha^{k-1}$ for all $k$. Hence, expressions (5.19) simplify and the solution B₁ is:

$$g_k = \alpha^k g_0 + k \gamma \alpha^{k-1}, \quad f_k = \alpha^k \left(\frac{\delta}{\gamma} g_0 + \varepsilon\right) + k \delta \alpha^{k-1},$$

$$h_k = \alpha^k (h_0 + k g_0'\delta), \quad \text{for } k = 0, 1, 2, \ldots$$  \hspace{1cm} (5.23)

where $g_0$ is a free function of $q$ and $\alpha, \delta, \gamma, \varepsilon$ are constants. The claim is that this solution satisfies all the relations (5.1). Some details will be provided in appendix A.

Hence

$$F(p + \lambda, q) = e^{(p+\lambda)\alpha/2} \left(\frac{\delta}{\gamma} g_0 + \varepsilon + \delta \left(\frac{p + \lambda}{2}\right)\right),$$

$$G(p - \lambda, q) = e^{(p-\lambda)\alpha/2} \left(g_0 + \gamma \left(\frac{p - \lambda}{2}\right)\right),$$

and

$$F_{\lambda}G_q - F_qG_{\lambda} = \frac{e^{p\alpha}}{2} \left(g_0 g_0' 2\frac{\alpha}{\gamma} + g_0' (2\delta + \alpha\varepsilon + 2\delta + \alpha\delta p)\right) = U(p + q) - V(p - q).$$

If $\delta \neq 0$, the presence of the last term proportional to $p$ makes it hopeless to find suitable potentials. However, setting $\delta = 0$ the previous expression becomes

$$F_{\lambda}G_q - F_qG_{\lambda} = \frac{e^{p\alpha}}{2} g_0' \frac{\alpha\varepsilon}{2}.$$  \hspace{1cm} (5.24)

This suggests

$$g_0' \sim (e^{\alpha q} - e^{-\alpha q}) \quad \Rightarrow \quad U(u) = V(u) = \frac{\alpha\varepsilon}{2} e^{\alpha u},$$

or

$$g_0' \sim e^{\alpha q} \quad \Rightarrow \quad U(u) = \frac{\alpha\varepsilon}{2} e^{\alpha u}, \quad V = 0.$$  \hspace{1cm} (5.25)

In the first case, a field satisfying the Liouville potential is located on both sides of the defect and in the second case there is a Liouville field on one side of the defect and a free massless field on the other.
5.2.2 Solution B2

This expression (5.20) can be rewritten as
\[ \frac{g'_0}{f'_0} = \frac{\alpha g_0(\alpha - \beta) + \alpha \gamma}{\beta \delta - \beta f_0(\alpha - \beta)} = \zeta, \]
where \( \zeta \) is a function of \( q \). This leads to two equations that need to be solved
\[ g'_0 = \zeta f'_0, \quad g_0 = \frac{\zeta \delta \beta - \alpha \gamma}{\alpha(\alpha - \beta)} - \frac{\beta}{\alpha} \zeta f_0. \] (5.24)

By differentiating the second equation it is found
\[ \frac{f'_0(\alpha^2 - \beta^2)}{\beta \delta - \beta f_0(\alpha - \beta)} = \frac{\zeta'}{\zeta}, \]
which leads to
\[ f_0 = \frac{\varepsilon \zeta^{-\beta/(\alpha + \beta)}}{\beta(\alpha - \beta)} + \frac{\delta}{(\alpha - \beta)}, \quad g_0 = \frac{\varepsilon \zeta^{\alpha/(\alpha + \beta)}}{\alpha(\alpha - \beta)} - \frac{\gamma}{(\alpha - \beta)}, \] (5.25)
and
\[ h_0 = -f'_0 \frac{\beta \gamma}{(\alpha - \beta)} + g'_0 \frac{\alpha \delta}{(\alpha - \beta)} - h_1 = -f'_0 \frac{\beta^2 \gamma}{(\alpha - \beta)} + g'_0 \frac{\alpha^2 \delta}{(\alpha - \beta)}. \] (5.26)

Looking at expressions (5.19), it can be noticed that
\[ A_{k+1} - \alpha A_k = \beta^{k+1}, \quad A_{k+1} - \beta A_k = \alpha^{k+1}, \quad A_k = \left( \frac{\alpha^k - \beta^k}{\alpha - \beta} \right), \quad k = 0, 1, \ldots \]
Clearly \( \alpha \neq \beta \), which is fine since the case \( \alpha = \beta \) has been explored in the previous subsection. Then the solution B2 is:
\[ f_k = \beta^k f_0 + \delta \left( \frac{\alpha^k - \beta^k}{\alpha - \beta} \right), \quad g_k = \alpha^k g_0 + \gamma \left( \frac{\alpha^k - \beta^k}{\alpha - \beta} \right), \]
\[ h_k = -f'_0 \frac{\beta^{k+1} \gamma}{(\alpha - \beta)} + g'_0 \frac{\alpha^{k+1} \delta}{(\alpha - \beta)}, \quad k = 0, 1, \ldots \] (5.27)
with \( g_0 \) and \( f_0 \) given in (5.25). Once again, all relations (5.1) are satisfied. Details can be found in appendix A. Hence
\[ F(p + \lambda, q) = \frac{\delta}{(\alpha - \beta)} e^{\alpha(p + \lambda)/2} + \left( f_0 - \frac{\delta}{(\alpha - \beta)} \right) e^{\beta(p + \lambda)/2}, \]
\[ G(p - \lambda, q) = \left( g_0 + \frac{\gamma}{(\alpha - \beta)} \right) e^{\alpha(p - \lambda)/2} - \frac{\gamma}{(\alpha - \beta)} e^{\beta(p - \lambda)/2}, \]
\[ F_{\lambda} G_q - F_q G\lambda = g'_0 \frac{\delta}{2(\alpha - \beta)} e^{\alpha p} - f'_0 \frac{\gamma \beta}{2(\alpha - \beta)} e^{\beta p} \]
\[ = \frac{\varepsilon \zeta' \zeta^{-\beta/(\alpha + \beta)}}{2(\alpha - \beta)^2(\alpha + \beta)} \left( \delta \alpha e^{\alpha p} - \gamma \beta \zeta^{-1} e^{\beta p} \right) = U(p + q) - V(p - q). \] (5.28)
Before looking at the most general solution, it is easy to see that a solution is provided by
\[ \zeta \sim e^{\alpha + \beta} \Rightarrow U(u) = \frac{\varepsilon \delta \alpha}{2(\alpha + \beta)^2} e^{\alpha u} \quad V(v) = \frac{\varepsilon \gamma \beta}{2(\alpha + \beta)^2} e^{\beta v}. \]

Notice that this suggests the possibility to have two Liouville potentials on the two sides of the defect with different and arbitrary normalisations. This is not surprising given that no mass is involved and that a type II defect can be seen as the result of a two fused type I defects \[21\].

The most general solution to (5.28) is instead obtained by setting
\[ \frac{\varepsilon \alpha \delta}{2(\alpha - \beta)^2(\alpha + \beta)} \zeta' \zeta^{-\beta/(\alpha + \beta)} = A e^{\alpha q} - B e^{-\alpha q}, \]
\[ \frac{-\varepsilon \beta \gamma}{2(\alpha - \beta)^2(\alpha + \beta)} \zeta' \zeta^{-1-\beta/(\alpha + \beta)} = C e^{\beta q} - D e^{-\beta q}, \]
whose ratio suggests
\[ -\frac{\alpha \delta}{\beta \gamma} \zeta = \left( \frac{A e^{\alpha q} - B e^{-\alpha q}}{C e^{\beta q} - D e^{-\beta q}} \right) \equiv \frac{X(q)}{Y(q)}. \]

Then, the first expression in (5.29) can be rewritten as follows
\[ c(X'Y - Y'X)X^{n-1} = Y^{n+2} \quad \text{with} \quad c \equiv \frac{\varepsilon \gamma^{n+1}}{2 \delta \alpha \beta^2} \frac{n^{3+n}}{(2n+1)^2(n+1)n!}, \]
where \( n = -\beta/(\alpha + \beta) \). This expression has solution only for \( n = 1 \) and \( n = -2 \) (the cases \( n = 0 \) and \( n = -1 \) are excluded since they imply \( b = 0 \) and therefore \( H_B = 0 \)). These two solutions lead to the same \( U \) and \( V \) potentials. Note in fact that by sending \( n \) to \(-n - 1\), (5.30) becomes
\[ c'(Y'X - X'Y)Y^{n-1} = X^{n+2}, \]
where \( c' \) is a constant, unimportant for the current discussion. Clearly, if (5.30) has a solution, then this expression has a solution as well and the two solutions are related by the swapping of \( \alpha \) and \( \beta \). In the end, setting \( n = 1 \) the most general solution to (5.29) is:
\[ \zeta = \frac{18\beta}{\varepsilon \gamma} \left( C e^{\beta q} + D e^{-\beta q} \right) \]
\[ U(u) = C e^{\beta u} - \frac{36 D^2 \delta \beta}{\varepsilon \gamma^2} e^{-2\beta u} \quad V(v) = D e^{\beta v} - \frac{36 C^2 \delta \beta}{\varepsilon \gamma^2} e^{-2\beta v}, \]
which correspond to the Tzitzéica potentials. Once again there is a freedom in the choice of the exponential coefficients, which reflects the freedom of shifting the fields \( u \) and \( v \) by arbitrary constants, as it was the case for the sinh-Gordon potential in section 4. Setting \( \beta = -1 \), \( C = D = 2 \) and \( 36 \delta / \varepsilon \gamma^2 = 1/2 \)
\[ U(u) = V(u) = 2 e^{-u} + e^{2u}, \]
so that a more familiar form for the Tzitzéica potential is recovered.

Finally, note that the sinh-Gordon potential is not a solution of (5.28). In fact, it corresponds to the case \( \alpha = -\beta \), which is explicitly excluded since it would imply \( a = 0 \), and therefore \( H_C = 0 \).
6 Conclusion

This article adds another piece in the complex mosaic that represents integrable field theory. That these models are special is a well-known fact. It turns out that they are the only relativistic field theories able to support a purely transmitting defect, which is defined by the requirement of both energy and momentum conservation. All of this is achieved by preserving their most distinctive feature: integrability. Somehow, demanding both energy and momentum conservation singles out the integrable models. Previously known results concerning the sinh-Gordon, Tzitzéica and Liouville models have been recovered. In addition, it was interesting to see how the possibility to have two differently normalised Liouville models on either side of the defect emerges naturally from the current investigation. This is a possibility that, though not surprising, was not explicitly considered previously.

Nevertheless, the present investigation has a limitation. Only models with a single scalar field have been considered. Previously, multi-scalar field theories supporting type I defects have been analysed and found to be the non-affine and affine Toda fields models based on the \( \mathbb{A}_n^{(1)} \) root data \([5, 8]\). In order to extend the more general investigation to multiple scalar field models, it is useful to borrow an idea presented recently in \([19, 20]\), then applied successfully to the \( \mathbb{A}_n^{(1)} \) affine Toda models, to mix the type I and type II defects in order to increase the range of models that support these kinds of defect and hopefully to demonstrate that this will allow all integrable Toda models. The most general sewing conditions for the type I defects can be found in \([5, 8]\) and are:

\[
\begin{align*}
    u_x &= Au_t + (1 - A) v_t - \mathcal{E}_u, \\
    v_x &= -Au_t + (1 + A) u_t + \mathcal{E}_v,
\end{align*}
\]

where the fields \( u \) and \( v \) are now vectors representing multi-component scalar fields and \( A \) is an antisymmetric matrix. On the other hand the sewing conditions for the type II defect look unchanged with respect to the ones seen previously. In fact they are:

\[
\begin{align*}
    u_x &= \lambda_t - \mathcal{E}_u, \\
    v_x &= \lambda_t + \mathcal{E}_v, \\
    u_t - v_t &= -\mathcal{E}_\lambda,
\end{align*}
\]

where \( u, v \) and \( \lambda \) are now vectors. The mixing idea consists in splitting the space in which the fields live into two pieces. The fields belonging to one part will satisfy type I sewing conditions at the defect and the fields belonging to the other part will satisfy type II sewing conditions. In order to keep track of this aspect, it is convenient to introduce two projection operators, \( \Gamma_1 \) and \( \Gamma_2 \) such that \( \Gamma_1 + \Gamma_2 = 1, \Gamma_1^2 = \Gamma_2 = \Gamma_k, k = 1, 2 \). Momentum conservation leads to the following constraints:

\[
\begin{align*}
    \mathcal{E}_{(\Gamma_1, q)} + 2A\mathcal{E}_{(\Gamma_1, p)} &= -\mathcal{P}_{(\Gamma_1, q)}, \\
    \mathcal{E}_{(\Gamma_2, p)} &= \mathcal{P}_{(\Gamma_2, \lambda)}, \\
    \mathcal{E}_{(\Gamma_2, \lambda)} &= \mathcal{P}_{(\Gamma_2, p)}, \\
    \frac{1}{2} (\mathcal{E}_{(\Gamma_2, q)} \mathcal{P}_{(\Gamma_2, \lambda)} - \mathcal{E}_{(\Gamma_2, \lambda)} \mathcal{P}_{(\Gamma_2, q)} + \mathcal{E}_{(\Gamma_1, p)} \mathcal{E}_{(\Gamma_1, q)}) &= U - V,
\end{align*}
\]

where the usual definition \( p = (u + v)/2, q = (u - v)/2 \) have been used. Note that the subscripts in parentheses indicate derivatives. It is useful to introduce a new field variable
\( \xi = -A \Gamma_1 q \). Then the previous constraints become

\[
E(\Gamma_1 \xi) - 2E(\Gamma_1 p) = -P(\Gamma_1 \xi), \quad E(\Gamma_1 p) = P(\Gamma_1 p), \quad E(\Gamma_2 p) = P(\Gamma_2 p), \quad E(\Gamma_2 \xi) = -P(\Gamma_2 \xi),
\]

which imply

\[
E = F(\Gamma_2 (p + \lambda), \Gamma_2 q, \Gamma_1 (p + \xi)) + G(\Gamma_2 (p - \lambda), \Gamma_2 q, \Gamma_2 \xi),
\]

\[
P = F(\Gamma_2 (p + \lambda), \Gamma_2 q, \Gamma_1 (p + \xi)) - G(\Gamma_2 (p - \lambda), \Gamma_2 q, \Gamma_2 \xi)
\]

and

\[
F(\Gamma_2 \lambda) G(\Gamma_2 q) - G(\Gamma_2 \lambda) F(\Gamma_2 q) - \frac{1}{2} F(\Gamma_1 p) \Gamma_1 AF(\Gamma_1, \xi) - \frac{1}{2} F(\Gamma_1 p) \Gamma_2 AF(\Gamma_2 \xi) = U - V. \quad (6.1)
\]

It can be seen how the first two terms on the left hand side are similar to the terms in the Poisson-Bracket relation (2.5) investigated in the present article. On other hand, the other two terms take into account a mixing represented by the fields \( \xi \), which are not confined to a single subspace. In [19], solutions for an expression similar to (6.1) have been found. However, a complete set of solutions is still missing.

A On the general expressions for solutions B

It was stated that solutions presented in section (5.2) satisfy all relations (5.1). It suffices to look at one set of these equations. Consider, for instance, the first set in the first line. For \( k = 0 \) using (5.18) it is found that

\[
f_1 = \frac{h_1 g_1 - h_0 (ag_0 - bg_0 + c)}{g_1 g_0 - g_0 (ag_0 - bg_0 + c)}.
\]

Notice that the \( s \) and \( r \) dependence disappears. This relation is easily seen to be satisfied using (5.16). For \( k > 0 \) it is convenient to rewrite the relations using (5.19) then

\[
f_{k+1} = -\frac{h_1 g_0 X_{k+1} + h_1 Y_{k+1} - h_0 g_0 b X_k - h_0 b Y_k}{\gamma},
\]

\[
X_{k+2} = (\alpha + \beta) X_{k+1} - \alpha \beta X_k, \quad X_1 = \alpha, \quad X_2 = \alpha \beta, \quad (A.1)
\]

\[
Y_{k+2} = (\alpha + \beta) Y_{k+1} - \alpha \beta Y_k, \quad Y_1 = \gamma, \quad Y_2 = 0, \quad k = 1, 2, \ldots
\]

Before proceeding any further, note that because these relations are obtained using (5.18) or (5.19), the \( r \) and \( s \) must be greater than 1. However, the cases in which \( r \) and/or \( s \) are 0 or 1 have already been considered since they were used in section 5 in order to get expressions (5.2), (5.3).

Consider first solution B_1. Because \( \alpha = \beta \), the constants appearing in (A.1) simplify. They become

\[
X_k = \alpha^k, \quad Y_k = -\gamma (k - 2) \alpha^{k-1}, \quad k = 1, 2, \ldots
\]
Using these expressions in (A.1) together with expressions (5.22) for \( h_0 \) and \( h_1 \), it is not difficult to see that (A.1) reproduces the expressions for \( f_{k+1} \) in (5.23).

Consider now the solution \( B_2 \). Using (5.26) expressions (A.1) become

\[
\frac{h_{k+1}}{h_k} = \frac{g_2}{g_1} = \frac{g_1'}{g_0'}, \quad \Rightarrow \quad h_{k+1} = h_k \frac{g_1'}{g_0'} = h_0 \left( \frac{g_1'}{g_0'} \right)^{k+1}, \quad k = 0, 1, \ldots \quad (B.1)
\]

On the other hand using formulas in the second line of (5.1), it is found that

\[
\frac{g_{k+1}}{g_k} = \frac{h_{k+s} f_{s+1} - h_{k+s} f_{r+1}}{h_r f_{s+1} - h_s f_{r+1}} = \left( \frac{g_1'}{g_0'} \right)^k, \quad \text{and} \quad \frac{g_{k'}}{g_k} = \left( \frac{g_1'}{g_0'} \right)^k, \quad k = 0, 1, \ldots
\]

where (B.1) has been used. The compatibility condition reads

\[
g_0 \left( \frac{g_1'}{g_0'} \right)^k = g_1 \left( \frac{g_1'}{g_0'} \right)^{k-1} + g_1 (k-1) \left( \frac{g_1'}{g_0'} \right)' \left( \frac{g_1'}{g_0'} \right)^{k-2} \quad k = 1, 2, \ldots,
\]

that is

\[
g_1 \left( \frac{g_1'}{g_0'} \right)' = 0, \quad \Rightarrow \quad \left( \frac{g_1'}{g_0'} \right)' = 0,
\]

since \( g_1 \) is different from zero. Then \( g_1' = c g_0' \), where \( c \) is a constant, and \( g_1 = c g_0 + \alpha \). It follows

\[
g_{k+1} = g_0 e^{k+1} + \alpha c^k, \quad h_{k+1} = h_0 e^{k+1} \quad k = 0, 1, \ldots \quad (B.2)
\]

It is easy to verify that \( H_B \) and \( H_C \) are also zero.

---

\(^2\)The case in which \( g_0' \) and \( g_1' \) are zero produces a \( G \) function that is \( q \) independent. This does not lead to new solutions.
Looking at the general formula (3.3), it is possible to notice that the ratio \( g'_{N-k}/g_{N-k+1} \) on the right hand side are all the same and equal to \( g'_0/g_1 \) that is:

\[
\frac{h_N}{f_{k+1}g_{N-k+1}} = \left( \frac{g'_0}{g_1} \right) + \left( \frac{f'_k}{f_{k+1}} \right) \quad k = 0, 1, \ldots
\]

Using (B.2) this leads to

\[
h_0 = \frac{f_{k+1}g'_0 + f'_kg_1}{c^k} = f_1g'_0 + f'_0g_1,
\]

that is

\[
(f_{k+1} - c^k f_1) g'_0 + (f'_k - c^k f'_0) g_1 = 0. \tag{B.3}
\]

Note that the same expression can also be found by using the expressions in the second line of (5.1) with, for instance, \((r, s) = (0, s)\). A solution is

\[
f_{k+1} = c^k f_1, \quad f'_k = c^k f'_0 \quad \Rightarrow \quad f_1 = c f_0 + \beta.
\]

Note that different solutions to (B.3) do not translate into different expressions for the final \( U \) and \( V \) potentials. In fact, their forms depend on \((F_\lambda G_q - F_q G_\lambda)\), which, because of (B.2) is proportional to \( h_0 e^{\alpha q} \). A different choice of \( f \)-functions would have an effect on \( h_0 \), which, in any case, must be proportional to \( A e^{cq} - B e^{-cq} \) where \( A \) and \( B \) are arbitrary constants. In summary:

\[
g_{k+1} = g_0 c^{k+1} + \alpha c^k, \quad f_{k+1} = f_0 c^{k+1} + \beta c^k, \quad h_{k+1} = (c(g_0f_0) + \alpha f_0 + \beta g_0) c^{k+1} \quad k = 0, 1, \ldots
\]

Then

\[
F(p+\lambda, q) = e^{(p+\lambda)c/2} f_0 + \frac{\beta}{c} \left( e^{(p+\lambda)c/2} - 1 \right), \quad G(p-\lambda, q) = e^{(p-\lambda)c/2} g_0 + \frac{\alpha}{c} \left( e^{(p-\lambda)c/2} - 1 \right),
\]

and

\[
F_\lambda G_q - F_q G_\lambda = \frac{e^{\alpha p}}{2} (c(g_0f_0) + \alpha f_0 + \beta g_0)'.
\]

This implies

\[
(c(g_0f_0) + \alpha f_0 + \beta g_0)' \sim (A e^{cq} - B e^{-cq}) \quad \Rightarrow \quad U(u) = \frac{A}{2} e^{cu}, \quad U(u) = \frac{B}{2} e^{cv}.
\]

According to the values of the constants \( A \) and \( B \) there is a Liouville field on both sides of the defect or a Liouville field on one side and a free massless field on the other. A similar analysis can be performed for the cases \( H_B = 0 \) and \( H_C = 0 \).

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