First-passage properties of the Pólya urn process

Tibor Antal\(^1\), E Ben-Naim\(^2\) and P L Krapivsky\(^3\)

\(^1\) Program for Evolutionary Dynamics, Harvard University, Cambridge, MA 02138, USA
\(^2\) Theoretical Division and Center for Nonlinear Studies, Los Alamos National Laboratory, Los Alamos, NM 87545, USA
\(^3\) Department of Physics, Boston University, Boston, MA 02215, USA
E-mail: Tibor-Antal@Harvard.edu, ebn@lanl.gov and paulk@bu.edu

Received 6 May 2010
Accepted 14 June 2010
Published 9 July 2010

Online at stacks.iop.org/JSTAT/2010/P07009
doi:10.1088/1742-5468/2010/07/P07009

Abstract. We study first-passage statistics of the Pólya urn model. In this random process, the urn contains balls of two types. In each step, one ball is drawn randomly from the urn, and subsequently placed back into the urn together with an additional ball of the same type. We derive the probability \(G_n\) that the balls of the two types become equal in number, for the first time, when there are a total of \(2n\) balls. This first-passage probability decays algebraically, \(G_n \sim n^{-2}\), when \(n\) is large. We also derive the probability that a tie ever happens. This probability is between zero and one, so a tie may occur in some realizations but not in others. The likelihood of a tie is appreciable only if the initial difference in the number of balls is of the order of the square root of the total number of balls.

Keywords: exact results, persistence (theory), stochastic particle dynamics (theory), diffusion
1. Introduction

Urn models play a central role in probability theory and combinatorics \cite{1,2}. Since the balls can represent anything from atoms to biological organisms to humans, urn models are widely used in the physical, life, and social sciences \cite{3}.

In this paper, we investigate the classic Pólya urn model \cite{4}–\cite{6}. This urn process is a type of birth process, and it is useful for modeling the spread of infectious diseases, population dynamics, and evolutionary processes in biology \cite{5}, \cite{7}–\cite{10}. Furthermore, this stochastic process is a branching process \cite{11}, and it is used to model data structures in computer science \cite{12}–\cite{14}. Of the myriad other applications, we mention decision making \cite{15}, reinforcement learning \cite{16}, and technology usage \cite{17,18}. We also note that the Pólya urn model is a limiting case of earlier urn models investigated by Laplace \cite{19}, Markov \cite{20}, and Ehrenfest \cite{21}.

The Pólya urn model exhibits rich and interesting phenomenology that includes a strong influence of the initial conditions, large fluctuations from realization to realization, and substantial finite-size corrections \cite{6,22,23}. In this study, we obtain the first-passage properties \cite{24} of the Pólya urn model, and contrast these with the first-passage characteristics of an ordinary random walk \cite{24,25}.

In the Pólya urn model, there are balls of two types: black and white ones. In a basic step, one ball is selected randomly from all balls in the urn. This ball is then returned to the urn together with an additional ball of the same color. Starting with a given configuration of balls, the number of balls increases indefinitely by repeating this step \textit{ad infinitum}. Thus, a configuration \((B,W)\) with \(B\) black balls and \(W\) white balls evolves according to

\[
(B, W) \xrightarrow{} \begin{cases} 
(B+1, W) \quad \text{with probability } \frac{B}{B+W}, \\
(B, W+1) \quad \text{with probability } \frac{W}{B+W}.
\end{cases}
\]
We investigate first-passage properties of the urn process (figure 1). We find that the probability $G_n$ that a tie is reached, for the first time, when there are $n$ balls of each type decays algebraically:

$$G_n \sim n^{-2},$$

for large $n$. This asymptotic behavior holds for arbitrary initial conditions. We also show that the total exit probability, that is, the probability that a tie is ever reached, is less than 1. Hence, an initial imbalance in the number of balls can be locked in, forever. We study how the total exit probability depends on the initial condition and find that it is appreciable only when the imbalance in the number of balls is of the order of the square root of the total number of balls.

The rest of this paper is organized as follows. We derive the first-passage probability in section 2. We then obtain the exit probability by summing the first-passage probability (section 3). We discuss the extreme cases of nearly maximal and extremely small exit probabilities (section 4), and then establish scaling properties of the exit probability (section 5). We generalize the results to near ties in section 6, and conclude in section 7.

### 2. The first-passage probability

Our goal is to quantify the first-passage process, illustrated in figure 1, using the first-passage probability and the total exit probability. For the initial condition $(B, W) = (b, w)$ where, without loss of generality, black balls are in the majority, $b > w$, the first-passage probability $G_n(b, w)$ is the likelihood that a tie is reached, for the first time, when $(B, W) = (n, n)$. In other words $G_n(b, w)$ is the probability that the initial imbalance holds, $B > W$, if and only if $W < n$. The total exit probability $E(b, w)$ is the probability that a tie is ever reached.

These first-passage characteristics are of interest in a variety of contexts, for example, in the growth of bacterial colonies, when bacteria proliferate without resource limitations,
First-passage properties of the Pólya urn process

cell death can be neglected, and the growth can be modeled by branching processes of two types [26,27]. These processes and the Pólya urn model have the same exit probability, which measures the likelihood that the minority species eventually overtakes the majority species. In the context of binary search trees, first-passage statistics quantify the likelihood that two branches of a tree reach perfect balance. Balanced trees are relevant in data structures, because they lead to more efficient searches. Indeed, the Pólya urn process has been used to model such data structures in computer science [28].

As a preliminary step to finding the first-passage probability, we obtain the likelihood that the system reaches configuration \( (B,W) = (m,n) \) starting from \( (B,W) = (b,w) \).

Let us consider, for example, the transition \((1,1) \rightarrow (3,3)\) where one possible path is
\[
(1,1) \rightarrow (1,2) \rightarrow (1,3) \rightarrow (2,3) \rightarrow (3,3).
\]
The likelihood of this path is
\[
\frac{1}{2} \times \frac{2}{3} \times \frac{1}{4} \times \frac{2}{5} = \frac{(1 \cdot 2) \cdot (1 \cdot 2)}{2 \cdot 3 \cdot 4 \cdot 5}.
\]
There are \( \binom{4}{2} = 6 \) distinct routes from \((1,1)\) to \((3,3)\) and they all have the same probability \( \frac{1}{30} \).

In general, all paths from configuration \((b,w)\) to configuration \((m,n)\) have the same probability
\[
\frac{[b(b+1) \cdots (m-1)] \cdot [w(w+1) \cdots (n-1)]}{(b+w)(b+w+1) \cdots (m+n-1)}.
\]
We rewrite this probability using factorials:
\[
\frac{(m-1)!}{(b-1)!} \times \frac{(n-1)!}{(w-1)!} \times \frac{(b+w-1)!}{(m+n-1)!}.
\]
The total number of distinct paths from \((b,w)\) to \((m,n)\) equals the binomial \( \binom{m+n-b-w}{n} \). Hence, the transition probability \( P \) that, starting from configuration \((b,w)\), the system reaches configuration \((m,n)\) is [3]–[6]
\[
P = \binom{m-1}{b-1} \binom{n-1}{w-1} \binom{m+n-1}{b+w-1}^{-1}.
\]
In particular, the probability distribution is flat [4,5], \( P = 1/(m+n-1) \), for the initial condition \((b,w) = (1,1)\).

The number of paths from \((b,w)\) to \((n,n)\) that reach the diagonal \( B = W \) only at the end point equals \( (b-w)/(2n-b-w) \) times the total number of such paths. This result can be established using the reflection principle [1]. Since all paths from \((b,w)\) to \((n,n)\) are equiprobable, the first-passage probability is simply \( G_n(b,w) = (b-w)P/(2n-b-w) \).

By substituting \( m = n \) into equation (4), we obtain our first main result, the first-passage probability:
\[
G_n(b,w) = \frac{b-w}{b+w} \binom{n-1}{b-1} \binom{n-1}{w-1} \binom{2n-1}{b+w}^{-1}.
\]
This quantity decays algebraically,
\[ G_n(b, w) \sim A(b, w)n^{-2}, \] (6)
in the asymptotic limit \( n \gg b, w \). The proportionality constant in (6) is
\[ A(b, w) = \frac{(b - w)(b + w - 1)!}{(b - 1)!(w - 1)!} 2^{b-w}. \]

For the special case \((b, w) = (2, 1)\), the first-passage probability (5) is simply
\[ G_n(2, 1) = \frac{1}{(2n - 3)(2n - 1)}. \] (7)

The probability that a tie is ever reached equals the sum
\[ \frac{1}{13} + \frac{1}{35} + \frac{1}{57} + \cdots = \frac{1}{2}, \]
and hence, there is a finite chance that the initial imbalance in the number of balls is maintained forever. This behavior is different than that of a one-dimensional random walk. In an ordinary random walk, the two elementary transitions in (1) occur with probability \( \frac{1}{2} \), and the first-passage probability decays algebraically, \( G_n \sim n^{-3/2} \), for large \( n \). Yet, the exit probability equals 1, and the random walk is guaranteed to reach the diagonal \( B = W \). Thus, the one-dimensional random walk is recurrent, but the Polya urn process is transient.

3. The exit probability

The exit probability \( E_n(b, w) \) is the likelihood that starting from configuration \((b, w)\), a tie happens by the time the urn contains \( 2n \) balls. The exit probability follows from the first-passage probability:
\[ E_n(b, w) = \sum_{b \leq j \leq n} G_j(b, w). \] (8)

The lower limit reflects that the quickest tie occurs when \((B, W) = (b, b)\). We are especially interested in the total exit probability, \( E(b, w) \equiv \lim_{n \to \infty} E_n(b, w) \). From the identity \( E_n(b, w) - E_{n-1}(b, w) = G_n(b, w) \) and equation (6), we conclude the asymptotic behavior
\[ E(b, w) - E_n(b, w) \simeq A(b, w) n^{-1}, \] (9)
when \( n \gg b, w \). In particular, the quantity \( E_n(2, 1) = (n - 1)/(2n - 1) \), that is the sum of (7), agrees with (9).

To evaluate the total exit probability \( E(b, w) \), we introduce the shorthand notation \( C_k(b, w) \equiv G_{b+k}(b, w) \). With this notation, equation (8) becomes \( E(b, w) = \sum_{k \geq 0} C_k(b, w) \), and
\[ C_k(b, w) = \frac{b - w}{b + w} \left( \frac{b + k - 1}{b - 1} \right) \left( \frac{b + k - 1}{w - 1} \right) \left( \frac{2b + 2k - 1}{b + w} \right), \] (10)
which is obtained by substituting \( n = b + k \) into (5). In particular, the quantity
\[ C_0(b, w) = \frac{\Gamma(b) \Gamma(b + w)}{\Gamma(2b) \Gamma(w)} \]
is the probability that a tie occurs as quickly as possible.

doi:10.1088/1742-5468/2010/07/P07009
In terms of the quantities \( C_k(b, w) \), the total exit probability \( E(b, w) = \sum_{j \geq b} G_j(b, w) \) equals
\[
E(b, w) = \sum_{k \geq 0} C_k(b, w). \tag{11}
\]

We now evaluate the ratio of two consecutive first-passage probabilities:
\[
\frac{C_{k+1}(b, w)}{C_k(b, w)} = \frac{(k + b)(k + (b - w)/2)(k + (b - w + 1)/2)}{(k + 1)(k + b + \frac{1}{2})(k + b - w + 1)}. \tag{12}
\]

Given these ratios, the exit probability can be expressed in terms of the hypergeometric function [29]:
\[
E(b, w) = \frac{\Gamma(b)\Gamma(b + w)}{\Gamma(2b)\Gamma(w)} F\left( b, b - w, b - w + 1; \frac{1}{2}, b - w + 1; 1 \right). \tag{13}
\]

This closed form expression is our second main result. As expected, \( E(b, b) = 1 \) and \( E(b, 0) = 0 \).

We also note that the exit probability satisfies the compact recursion relation
\[
E(b, w) = \frac{b}{b + w} E(b + 1, w) + \frac{w}{b + w} E(b, w + 1), \tag{14}
\]
for all \( b \neq w \). The boundary conditions are \( E(b, b) = 1 \) and \( E(b, 0) = 0 \). This recursion follows directly from the definition of the stochastic process (1), and is reminiscent of the recursion equation for an ordinary random walk \( E(b, w) = \frac{1}{2} E(b + 1, w) + \frac{1}{2} E(b, w + 1) \) [24].

We use this recursion to analyze extremal and scaling properties of \( E(b, w) \) in section 4.

4. Extremal behavior

Intuitively, we expect that when \( b \) is fixed, the exit probability increases monotonically with \( w \). The exit probability is largest when the number of balls is balanced, \( E(b, b) = 1 \), and conversely, the exit probability is smallest when the initial imbalance is maximal, \( E(b, 0) = 0 \). We now discuss the extreme cases of very small and nearly maximal exit probabilities.

When \( w = 1 \), the exit probability decays exponentially with the total number of balls,
\[
E(b, 1) = 2^{1-b}. \tag{15}
\]

To obtain this result, we note that when \( w = 1 \), two of the arguments of the hypergeometric function in (13) coincide and hence,
\[
E(b, 1) = \frac{\Gamma(b)\Gamma(b + 1)}{\Gamma(2b)} F\left( \frac{b}{2}, b - \frac{1}{2}; b + \frac{1}{2}; 1 \right). \tag{16}
\]

We obtain the expression (15) using the Gauss identity for the hypergeometric function:
\[
F(x, y; z; 1) = \frac{\Gamma(z - x - y)}{\Gamma(z - x)} \Gamma(z - y),
\]
and the following two identities for the Gamma function: \( \Gamma(x + 1) = x\Gamma(x) \) and \( \Gamma(\frac{1}{2})\Gamma(2x) = 2^{2x-1}\Gamma(x)\Gamma(x + \frac{1}{2}) \).
First-passage properties of the Pólya urn process

By substituting $E(b,1) = 2^{1-b}$ into the recursion (14), we have $E(b,2) = (b+2)2^{-b}$. Similarly, we obtain $E(b,3) = (b^2 + 5b + 8)2^{-b-2}$ by substituting $E(b,2)$ into (14). In general, the exit probability has the form

$$E(b,w) = \frac{U_w(b)}{(w-1)!} 2^{2-w-b},$$

(17)

where $U_w(b)$ is a polynomial of degree $w-1$ in the variable $b$. From equation (14), these polynomials satisfy the recursion

$$U_{w+1}(b) = 2(b+w)U_w(b) - bU_w(b+1).$$

(18)

Starting with the boundary condition, $U_1(b) = 1$, we have

$$U_w(b) = \begin{cases} 1 & w = 1, \\ b + 2 & w = 2, \\ b^2 + 5b + 8 & w = 3, \\ b^3 + 9b^2 + 32b + 48 & w = 4, \\ b^4 + 14b^3 + 83b^2 + 262b + 384 & w = 5. \end{cases}$$

(19)

Since the coefficient of the dominant term in $U_w(b)$ equals 1, the exit probability decays exponentially with the total initial population,

$$E(b,w) \sim \frac{b^{w-1}}{(w-1)!} 2^{2-b-w},$$

(20)

when $w$ is finite and $b \to \infty$.

To analyze the behavior in the opposite limit of nearly maximal exit probabilities, we consider the special case $w = b - 1$ where the ratio (12) simplifies as follows:

$$\frac{C_{k+1}}{C_k} = \frac{(k+b)(k+\frac{1}{2})}{(k+2)(k+b+\frac{1}{2})}. \tag{21}$$

We now shift the index of the first-passage probability by 1, $D_{k+1} \equiv C_k$, with $D_0 = -1$, and then evaluate the sum (11) to find $E(b, b-1) = 1 - F(b-1, -\frac{1}{2}; b - \frac{1}{2}; 1)$. Further, we express the exit probability through Gamma functions by using the identity (16):

$$E(b, b-1) = 1 - \frac{\Gamma(b-1/2)}{\Gamma(b)\Gamma(1/2)}.$$ \tag{22}

The exit probability increases monotonically with $b$: $E(b, b-1) = 1/2, 5/8, 11/16$ for $b = 2, 3, 4$. Moreover, ties become practically certain, $E(b, b-1) \simeq 1 - 1/\sqrt{\pi b}$, in the limit $b \to \infty$.

Along the same lines, we evaluate $E(b, b-q)$ by substituting the form (22) and the boundary condition $E(b, b) = 1$ into the recursion (14):

$$E(b, b-q) = 1 - \frac{\Gamma(b-1/2)}{\Gamma(b)\Gamma(1/2)} \times \begin{cases} 1 & q = 1, \\ 2 & q = 2, \\ 3b - 5/3 & q = 3, \\ 4b - 2 & q = 4. \end{cases} \tag{23}$$

doi:10.1088/1742-5468/2010/07/P07009
First-passage properties of the Pólya urn process

From these examples, we conclude that \( E(b, b - q) \simeq 1 - q/\sqrt{\pi b} \) when \( q \) is finite and \( b \to \infty \). In other words,

\[
E(b, w) \simeq 1 - \frac{2|b - w|}{\pi \sqrt{b + w}},
\]

(24)

when the initial imbalance \( |b - w| \) is fixed and the total number of balls \( b + w \) diverges. We used the symmetry \( E(x, y) = E(y, x) \), so (24) applies for both \( b > w \) and \( w > b \). This equation implies that a tie is nearly certain whenever the initial discrepancy in the number of balls is much smaller than the square root of the total number of balls. Otherwise, the exit probability is substantially reduced.

5. Typical behavior

The asymptotic behavior (24) suggests that the exit probability is a function of a single variable when the total number of balls is very large. Specifically, the scaling function \( \Phi(z) \), given by

\[
E(b, w) \simeq \Phi(z) \quad \text{with} \quad z = \frac{|b - w|}{\sqrt{b + w}},
\]

(25)

quantifies the exit probability in the limit \( b + w \to \infty \).

To show this scaling behavior, we make the change of variables \((b, w) \to (z, N)\) with the scaling variable \( z = (b - w)/\sqrt{b + w} \) and the time-like variable \( N = b + w \). Here, the case \( b > w \) is considered without loss of generality. We now consider the limit of very large \( N \) and finite \( z \), substitute \( E(b, w) = \tilde{\Phi}(z, N) \) into the recursion equation (14), and expand for very large \( N \). Specifically, we substitute \( b = (N + z\sqrt{N})/2 \) and \( w = (N - z\sqrt{N})/2 \) and the corresponding expressions for \( b+1 \) and \( w+1 \) into (14), and identify the leading terms in the limit \( N \to \infty \). This analysis shows that the scaling function \( \Phi(z) \equiv \lim_{N \to \infty} \tilde{\Phi}(z, N) \) satisfies the differential equation

\[
\frac{d^2\Phi(z)}{dz^2} + z \frac{d\Phi(z)}{dz} = 0.
\]

(26)

The boundary conditions are \( \Phi(0) = 1 \) and \( \Phi(\infty) = 0 \). The solution to (26) subject to these boundary conditions is simply

\[
\Phi(z) = \text{erfc} \left( \frac{z}{\sqrt{2}} \right),
\]

(27)

where \( \text{erfc}(z) \) is the complementary error function [29], \( \text{erfc}(x) = (2/\sqrt{\pi}) \int_x^\infty du \exp(-u^2) \). The scaling function is monotonically decreasing because a larger initial imbalance implies a smaller exit probability (figure 2). The behaviors of the scaling function for small \( z \) and for large \( z \) are as follows:

\[
\Phi(z) \simeq \begin{cases} 
1 - \sqrt{2/\pi} z & \text{if } z \ll 1, \\
\sqrt{2/\pi} z^{-1} \exp(-z^2/2) & \text{if } z \gg 1.
\end{cases}
\]

(28)

The small argument behavior agrees with (24), while the large argument behavior is consistent with (15). Indeed, when \( w = 1 \) and \( b \) is very large, the scaling variable is \( z \simeq \sqrt{b} \), and hence, \( \ln \Phi \sim -z^2 \sim -b \).

doi:10.1088/1742-5468/2010/07/P07009
Figure 2. The scaling function \( \Phi(z) \) given in (27) versus the scaling variable \( z \) (solid line). Also shown is the exit probability \( E(b, w) \), given by the exact expression (13), versus \( z \) for three different values of \( N = b + w \) (symbols).

The scaling form (25) implies that the likelihood of a tie is appreciable only when the initial population difference, \( \Delta = |b - w| \), is of the same order as the square root of the total population, \( N = b + w \), that is,

\[
\Delta \sim \sqrt{N}. \tag{29}
\]

A tie is nearly certain when the discrepancy is small, \( \Delta \ll \sqrt{N} \), but extremely rare when \( \Delta \gg \sqrt{N} \).

6. Near ties

There are a number of generalizations of the first-passage process discussed above. Two natural questions are: (i) what is the probability that the ratio between the majority population and the majority population is always above a fixed threshold and (ii) what is the probability that the difference between the two populations is always above a fixed threshold. In this section, we address the latter problem.

We define \( G_n(b, w; d) \) to be the first-passage probability that starting with configuration \((b, w)\), the difference \( B - W > d \) if and only if \( W < n \). In other words \( G_n(b, w; d) \) is the probability that there are at least \( d \) more black balls throughout the evolution and, moreover, this condition is violated for the first time when \((B, W) = (n + d, n)\). We obtain the first-passage probability

\[
G_n(b, w; d) = \frac{b - w - d}{b + w} \frac{n + d - 1}{b - 1} \frac{n - 1}{w - 1} \frac{2n + d - 1}{b + w}, \tag{30}
\]

by multiplying the probability (4) for transitioning from \((b, w)\) to \((n + d, n)\) with the fraction \((b - w - d)/(2n + d - b - w)\) of these paths that do not cross the line.

\[\text{doi:10.1088/1742-5468/2010/07/P07009}\]
\( B = W + d \) [1]. Of course, this expression matches (5) when \( d = 0 \). Again, the asymptotic behavior in the limit \( n \rightarrow \infty \) is \( G_n \sim n^{-2} \).

The exit probability \( E(b, w; d) \) is the probability that the line \( B = W + d \) is reached at least once during the evolution. By repeating the steps leading to (13), we find the exit probability in terms of a hypergeometric function of higher order:

\[
E(b, w; d) = \frac{\Gamma(b-d)\Gamma(b+w)}{\Gamma(2b-d)\Gamma(w)} F(c_1, c_2, c_3, c_4; e_1, e_2, e_3; 1).
\]

The corresponding arguments are

\[
c_1 = b, \quad c_2 = \frac{b-w-d}{2}, \quad c_3 = \frac{b-w-d+1}{2}, \quad c_4 = b-d,
\]

\[
e_1 = b + \frac{1-d}{2}, \quad e_2 = b - w - d + 1, \quad e_3 = b - \frac{d}{2}.
\]

For near ties, \( d = 1 \), there are many similarities with \( E(b, w) \) of equation (13). For example, the exit probability decays exponentially when the initial imbalance is maximal:

\[
E(b, 1; 1) = \frac{b}{b-1} 2^{1-b}.
\]

Additionally, the exit probability is close to 1 when the initial imbalance is minimal:

\[
E(b, b-2; 1) = 1 - \frac{1}{2(b-1)} - \frac{\Gamma(b-1/2)}{\Gamma(b)\Gamma(1/2)}.
\]

Thus, the behavior \( E(b, b-2; 1) \sim 1 - 1/\sqrt{\pi b} \) is recovered when \( b \rightarrow \infty \).

7. Discussion

In summary, we obtained first-passage characteristics of the Pólya urn process as a function of the initial condition. The first-passage probability that a tie is reached for the first time when there are \( 2n \) balls decays algebraically, \( G_n \sim n^{-2} \), for large \( n \). The probability that a tie ever occurs is less than 1; hence ties are not certain. This exit probability decreases as the initial discrepancy in the number of balls increases. Moreover, there is a universal scaling behavior when the total initial population is very large. This scaling behavior implies that the exit probability is appreciable only when the initial population imbalance is of the order of the square root of the total population.

The key property of the Pólya urn model is that the fraction of white balls approaches a limiting value, but this value fluctuates from realization to realization. In many other urn models, however, the opposite is true, and moreover, the two fractions approach the same limiting value. This is the case for the Friedman urn process [30, 31] which, in its simplest form, is equivalent to the stochastic process

\[
(B, W) \rightarrow \begin{cases} 
(B + 1, W) & \text{with probability } \frac{W}{B+W}, \\
(B, W + 1) & \text{with probability } \frac{B}{B+W}.
\end{cases}
\]

It will be interesting to investigate first-passage properties of this urn process. We conjecture that first-passage statistics are much closer to those of the ordinary random walk.
In the context of population dynamics and evolutionary biology, continuous time processes are more appropriate [11]. The continuous time analog of the Pólya urn model (1) is the two-species branching process, $B \rightarrow B + B$ and $W \rightarrow W + W$, where the two birth rates are equal. This continuous time process is closely related to the discrete time urn process. For instance, our results for the total exit probabilities are valid for the continuous time process as well.

Acknowledgments

We thank A Gabel, S Redner, and V Sood for useful discussions. We also thank an anonymous referee for constructive criticism. We gratefully acknowledge support from the John Templeton Foundation, NSF/NIH grant R01GM078986, DOE grant DE-AC52-06NA25396, and NSF grant CCF-0829541.

References

[1] Feller W, 1968 An Introduction to Probability Theory and Its Applications (New York: Wiley)
[2] Bartlett M S, 1978 An Introduction to Stochastic Processes (Cambridge: Cambridge University Press)
[3] Johnson N L and Kotz S, 1977 Urn Models and their Applications (New York: Wiley)
[4] Markov A A, 1917 Izv. Acad. Sci. 11 177
[5] Eggenberger F and Pólya G, 1923 Z. Angew. Math. Mech. 3 279
[6] Mahmoud H M, 2009 Pólya Urn Models (Boca Raton, FL: CRC Press)
[7] Sigmund K, 1993 Games of Life (Oxford: Oxford University Press)
[8] Hoppe F M, 1984 J. Math. Biol. 20 91
[9] Hoppe F M, 1987 J. Math. Biol. 25 123
[10] Pittel B, 1987 J. Appl. Probab. 24 522
[11] Harris T E, 1989 The Theory of Branching Processes (New York: Dover)
[12] Bagchi A and Pal A K, 1985 SIAM J. Algebr. Discrete Methods 6 394
[13] Aldous D, Flannery B and Palacios J L, 1988 Prob. Eng. Inform. Sci. 2 293
[14] Kotz S, Mahmoud H and Robert P, 2000 Stat. Probab. Lett. 49 163

Mahmoud H M, 2004 Acta Inform. 41 1
[15] Martina C F and Ho Y C, 2002 Inform. Sci. 147 65
[16] Erev I and Roth A, 1998 Am. Econ. Rev. 88 848
[17] Windrum P, 2004 Res. Policy 33 385
[18] Bender J, Huberman B A and Wu F, 2009 J. Econ. Behav. Organ. 72 290
[19] Laplace P S, 1812 Théorie Analytique des Probabilités (Paris: Courier Imprimeur)
[20] Markov A A, 1912 Izv. Acad. Sci. 6 551
[21] Markov A A, 1915 Izv. Acad. Sci. 9 87
[22] Ehrenfest P and Ehrenfest T, 1907 Phys. Z. 8 311
[23] Flajolet P, Cabarbo J and Pekari H, 2005 Ann. Prob. 33 1200
[24] Ben-Naim E and Krapivsky P L, 2004 Phys. Rev. E 69 046113
[25] Redner S, 2001 A Guide to First Passage Processes (Cambridge: Cambridge University Press)
[26] Rudnick J and Gaspari G, 2004 Elements of the Random Walk: An Introduction for Advanced Students and Researchers (New York: Cambridge University Press)
[27] Zheng Q, 1999 Math. Biosci. 162 1
[28] Hallatschek O, Hersen P, Ramanathan S and Nelson D R, 2005 Ecol. Lett. 8 800
[29] Mahmoud H M, 1998 Inform. Process. Lett. 65 41
[30] Abramowitz M and Stegun I A, 1964 Handbook of Mathematical Functions (New York: Dover)
[31] Friedman B, 1949 Commun. Pure Appl. Math. 2 59
[32] Freedman D, 1965 Ann. Math. Stat. 36 956