Birth and Death Processes in Interactive Random Environments

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Abstract. This paper studies birth and death processes in interactive random environments where the birth and death rates and the dynamics of the state of the environment are dependent on each other. Two models of a random environment are considered: a continuous-time Markov chain (finite or countably infinite) and a reflected (jump) diffusion process. The background is determined by a joint Markov process carrying a specific interactive mechanism, with an explicit invariant measure whose structure is similar to a product form. We discuss a number of queueing and population-growth models and establish conditions under which the above-mentioned invariant measure can be derived.

Next, an analysis of the rate of convergence to stationarity is performed for the models under consideration. We consider two settings leading to either an exponential or a polynomial convergence rate. In both cases we assume that the underlying environmental Markov process has an exponential rate of convergence, but the convergence rate of the joint Markov process is determined by certain conditions on the birth and death rates. To prove these results a coupling method turns out to be useful.

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1. Introduction

Birth-death processes are fundamental stochastic models in applied probability, particularly in queueing. Birth-death processes in random environments have been extensively studied [42, 43, 5, 6] and used in various applications (e.g., in queueing [18, 19, 12], inventory [30], population dynamics [1] and epidemiology [32]). Most of the studies have been focused on models where the transitions of birth and death processes are affected by the environment but not vice versa (see, e.g., [42, 43, 5]).

However, in applications, the influence of the birth-death processes and the environment can be in both directions. For example, service systems can be often modeled as multi-server queues where customer arrivals may depend on performance rating. The joint (queue, rating) dynamics may be modeled as a Markov process where ratings depend on the service quality indicated by congestion (i.e., the size of the queue). The population growth can also be modeled as a birth-death process in a random environment where the environmental changes are influenced by the population size (say, in the case of an overpopulation). In epidemiology, the infection rate may depend on a moving environment, while the dynamics of the environmental state is determined by the number of infected individuals (say, via a specific vaccination or lockdown intervention policy).

Key words and phrases. birth-death processes, interactive random environment, Markov jump process, (jump) diffusion process, invariant measures, product-form formula, exponential/polynomial convergence rate to stationarity.
In this paper, we study birth–death processes in an interactive random environment evolving in such a way that the joint Markov process has a product-form type invariant measure. Consider a birth-death process \( N = \{N(t), t \geq 0\} \) on \( \mathbb{N} = \{0, 1, 2, \ldots\} \) with birth rates \( \lambda_n(z) \) (for the jump \( n \rightarrow n + 1, n \geq 0 \)) and death rates \( \mu_n(z) \) (for the jump \( n \rightarrow n - 1, n \geq 1 \)) depending on an environment variable \( z \) taking values in an environment space \( Z \). The environmental variable, in turn, evolves as a continuous-time Markov process \( Z = \{Z(t), t \geq 0\} \), with transition functions depending on the current state \( N(t) \) of the birth-death process. \(^1\) A combined Markov process \( (N, Z) = \{(N(t),Z(t)), t \geq 0\} \), with states \((n,z)\), is called a birth-death process in an interactive random environment.

The generator \( \mathcal{L} \) of the combined process \( (N, Z) \) is given by
\[
\mathcal{L} f(n, z) = \mathcal{M}_z f(n, z) + r_n(z)^{-1} \mathcal{A}_n f(n, z).
\] (1.1)

Here \( \mathcal{M}_z \) is the generator of the birth-death process with a fixed environment variable \( z \) and \( \mathcal{A}_n \) is the generator of the environment process for a fixed birth-death value \( n \). The parameter \( r_n(z) \) is the cumulative (product) birth-death rate ratio given in (2.2). See further discussions on the joint generator in Remark 3.1.

For the process \( Z \), we consider two models:

(i) The environment space \( Z \) is at most countable, and the environment process is a continuous-time Markov chain with a generating matrix \( \mathcal{A}_n \) depending on \( n \), the state of process \( N(t) \); we call this model a jump environment.

(ii) The environment space \( Z \) is a domain in \( \mathbb{R}^d \), and the environment process is a reflected jump diffusion in this domain, with variable drift vector \( b_n(z) \), diffusion matrix \( \sigma_n(z) \) and jump measures \( \nu_n(z,\cdot) \) dependent on the state \( n \) of process \( N(t) \); this is called a diffusive environment.\(^2\)

In this article, we study the long-time behavior of these models:

(a) existence and uniqueness of a stationary distribution, that is, a probability distribution \( \pi \) on the product space \( \mathcal{X} = \mathbb{N} \times Z \) such that if \( (N(0),Z(0)) \sim \pi \), then \( (N(t),Z(t)) \sim \pi \) for all \( t \geq 0 \), and an explicit form of \( \pi \);

(b) convergence \( (N(t),Z(t)) \rightarrow \pi \) as \( t \rightarrow \infty \) in the total variation distance, and the rate of this convergence (exponential or polynomial).

We adapt and generalize the methods of our previous article [31] devoted to \( \text{M/M/1} \) queues in an interactive random environment. We identify conditions on the birth and death rates and the underlying Markov process under which the rate of convergence can be either exponential or polynomial (Theorems 4.1, 4.2 and 5.1).

We discuss a few examples that are of interest on their own. For example, we have studied infinite-server queues with the arrival and/or service rates being an RBM or reflected Ornstein–Uhlenbeck diffusion (Examples 3.1–3.6). We have also discussed the finite-server queues (infinite-waiting space, blocking/loss model or with abandonment) where the arrival, service and/or abandonment rates are an RBM or reflected diffusion in Examples 3.8 and 3.9. Another example is the population growth model in biology with the growth and death rates dependent on the environment (see Example 2.6 in a jump environment and Example 3.10 with the rates being a three-dimensional RBM in an orthant). We have also briefly

\(^1\)Formally speaking, we deal with a family of birth-death processes depending on the parameter \( z \in Z \) and a family of environmental processes depending on the parameter \( n \in \mathbb{N} \).

\(^2\)The domain and the reflection type may also depend on \( n \); a general type of dependence is encrypted in the symbol \( \mathcal{A}_n \) for the generator of the environmental diffusion.
discussed how the population growth model can be extended to study growth stocks in finance in Examples 2.7 and 3.10. In all these models, we discuss how the conditions for the existence of stationary distributions are verified and provide the explicit expressions for the invariant measures.

1.1. Literature review. Birth-death processes in random environments have been widely studied, see, e.g., [42, 43, 5]. In these models, the birth and death rates are affected by the environments. Economou [10] studied continuous-time Markov chains (CTMC) in random environments where not only the transitions rates of the CTMC depend on the environment, but also a change in the environment can trigger an immediate transition of the CTMC. He identified conditions under which a (generalized) product form stationary distribution may exist. In [4], more general Markov chains in random environments are studied, where the transition probabilities of the Markov chains are affected by the environments. Bacaër and Ed-Darraz [1] studied a linear birth-death process in a finite-state random environment with biology applications, and derived the probability of extinction. In all these studies, the interaction with the environment is one-sided, that is, the dynamics of the environment is not influenced by the state of the Markov chains.

Cornez [6] first studied birth-death processes in random environment with feedback (that is, feedback to the environment process from the state of the birth-death process) and provided sufficient conditions under which the birth-death process component goes extinct or not. In that model, the environment process takes values in a general measurable space, and no explicit stationary distribution is derived. In [18], loss queues with interactive (Markov jump) random environments are considered, and a product-form steady state distribution of the joint queueing-environment process is derived which results in a strong insensitivity property. In [19], the authors consider Jackson networks with interactive (Markov jump) random environments, where customers departing from the network may enforce the environment to jump immediately. In [30], single server queues with state dependent arrival and service rates which are also interactively affected by a Markov jump environment are studied, and both cases of an explicit product-form (separable) steady state distribution and of a non-separable steady-state distribution are considered. In [7], another construction is provided for Markov processes in interactive random environments (pure Markov jump process) that allows simultaneous transitions for the Markov chain and environment states, for which a product form invariant measure is derived and applications to queueing and neural avalanches are discussed. We note the main differences in the construction of the joint queueing-environment process in [18, 19, 30] from our paper: they allow simultaneous changes in the queueing and environment states, while our construction does not. Moreover, the environments in those papers are only a Markov jump process.

We also refer to [12], where a random walk interacting with a random environment of a Jackson/Gordon-Newell network is considered, and an explicit stationary distribution of a product-form type is derived. In [32], an epidemic SIS model in an interactive switching environment is studied, where the infection and recovery rates depend on a finite-state Markov jump process whose transitions also depend on the number of infectives. Large population scaling limits and the associated long-time behaviors are studied.

Our work generalizes the previous work in [31], where an M/M/1 queue in an interactive random environment is studied, with both jump and diffusive environments. The models considered in this paper are more general, and a few new stochastic models are introduced as
discussed above. In addition to exponential rate of convergence, we also establish polynomial rate of convergence to stationarity.

This paper also contributes to the understanding of rate of convergence of birth-death processes. Lindvall [21] developed the coupling approach to estimate the exponential rate of convergence for birth-death processes, which we follow and further develop for our model. Van Doorn [44] identified conditions on the birth and death rates under which the chain is exponentially ergodic by investigating the spectral representation of the transition probabilities, and bounds on the decay parameter were also established. Zeifman [50] used methods of differential equations to derive explicit estimates for the rate of convergence for birth-death processes; this was subsequently applied to some queueing examples, including the M/M/K and M/M/K/0 models. In [51], this approach has been extended to nonhomogeneous birth-death processes for which upper and lower bounds on the rate of convergence were derived; consequently, a number of queueing examples have been studied, including M\textsubscript{t}/M\textsubscript{t}/K and M\textsubscript{t}/M\textsubscript{t}/K/0. Van Doorn and Zeifman [46] study the rate of convergence of the Erlang loss system. We also refer to [47, 45, 52] for further studies on the related topics and queueing models.

1.2. Organization of the article. In Section 2, we state the model and results for the jump environment. In Section 3, we do the same for the diffusive environment. A few examples are provided in both sections. In Section 4, we state and prove the results on the exponential rates of convergence to stationarity. In Section 5, we do the same for polynomial convergence. Appendix A contains proofs of results from Sections 2 and 3. Appendix B provides a technical comparison lemma from [31].

1.3. Notation. We let \( N = \{0, 1, 2, \ldots \} \) and \( \mathbb{R}_+ := [0, \infty) \) be the sets of all nonnegative integer and real numbers, respectively. Let \( \mathbb{R}^d \) be the space of \( d \)-dimensional real numbers. The total variation distance between two probability measures \( P \) and \( Q \) on the same space \( \mathcal{E} \) is defined as

\[
\|P - Q\|_{TV} = \sup_{A \subseteq \mathcal{E}} |P(A) - Q(A)|.
\]  

(1.2)

The space of twice continuously differentiable functions on the space \( \mathcal{E} \) is denoted by \( C^2(\mathcal{E}) \). The space of bounded twice continuously differentiable functions with bounded first and second derivatives on the space \( \mathcal{E} \) is denoted by \( C^2_b(\mathcal{E}) \).

2. Jump Environment

2.1. Model construction. Consider a birth-death process in an interactive jump environment described as follows. Let \( \mathcal{Z} \) be a finite or countable state space for the environment. We define a two-component Markov process \((N, Z)\) taking values in the countable state space \( \mathbb{N} \times \mathcal{Z} \), with the following generator matrix \( R = (R((n, z), (n', z'))): \)

\[
R((n, z), (n + 1, z)) = \lambda_n(z), \quad R((n, z), (n - 1, z)) = \mu_n(z),
\]

\[
R((n, z), (n', z')) = r_n(z)^{-1} r_n(z, z')
\]

\[
R((n, z), (n', z')) = 0, \quad n \neq n', \quad z \neq z',
\]

(2.1)

where for each \( z \in \mathcal{Z} \),

\[
r_n(z) = \prod_{k=1}^{n} \frac{\lambda_k(z)}{\mu_k(z)} \quad \text{for} \quad n \geq 1, \quad \text{and} \quad r_0(z) \equiv 1,
\]

(2.2)
The transition kernel converges to this invariant measure in the total variation distance:

\[ \lim_{t \to \infty} \|P^t((n,z),\cdot) - \pi(\cdot)\|_{TV} = 0 \]

where \( \pi(n,z) := \frac{\eta(n,z)}{\Xi} \) and \( \eta(n,z) := r_n(z)v(z) \) are positive such that

\[ \sum_{j=1}^{\infty} r_j(z) = \sum_{j=1}^{\infty} \prod_{k=1}^{j} \frac{\lambda_{k-1}(z)}{\mu_k(z)} < \infty. \]

Observe that the detailed balance equations in (2.3) and (2.4) also hold by replacing \( \kappa_n(z) \) with \( r_n(z) \). This is not surprising: \( \kappa_n \) are a normalized \( r_n \) with \( \sum_{n=0}^{\infty} \kappa_n = 1 \). When the environment is in state \( z \), the birth rate of \( N(t) \) in the state \( n \) is \( \lambda_n(z) \) while the death rate is \( \mu_n(z) \). When the birth-death process is in state \( n \), the transition of the environment from state \( z \) to \( z' \) occurs at the rate \( \tau_n(z,z')/r_n(z) \). Note that the last equation in (2.1) forbids simultaneous jumps for \( N \) and \( Z \). The pair \((N,Z)\) yields a Markov process in the state space \( \mathbb{N} \times \mathbb{Z} \) with the generator \( R \). We denote its transition kernel by \( P^t((n,z),\cdot) \).

2.2. Main results on the stationary distribution. We make the following assumption on the matrix \( T_n \).

**Assumption 2.2.** There exists a function \( v : \mathbb{Z} \to \mathbb{R}_+ \) satisfying

\[ v(z) \sum_{z' \in \mathbb{Z}} \tau_n(z,z') = \sum_{z' \in \mathbb{Z}} v(z') \tau_n(z',z), \quad \text{for all } n \in \mathbb{N}, z \in \mathbb{Z}; \quad (2.6) \]

and

\[ \Xi := \sum_{(n,z)} r_n(z)v(z) = \sum_{(n,z)} \prod_{k=1}^{n} \frac{\lambda_{k-1}(z)}{\mu_k(z)} v(z) < \infty. \quad (2.7) \]

**Theorem 2.1.** Under Assumptions 2.1 and 2.2, the Markov process \((N,Z)\) \( \mathbb{N} \times \mathbb{Z} \) is irreducible, aperiodic, and positive recurrent. It has a unique invariant probability measure

\[ \pi(n,z) := \eta(n,z)/\Xi, \quad \forall (n,z) \in \mathbb{N} \times \mathbb{Z}, \quad (2.8) \]

with

\[ \eta(n,z) := r_n(z)v(z), \quad \forall (n,z) \in \mathbb{N} \times \mathbb{Z}, \quad (2.9) \]

The transition kernel converges to this invariant measure in the total variation distance:

\[ \|P^t((n,z),\cdot) - \pi(\cdot)\|_{TV} \to 0 \quad \text{as } t \to \infty, \quad \text{for all } (n,z) \in \mathbb{N} \times \mathbb{Z}. \quad (2.10) \]
Remark 2.1. Observe that the function $v$ in (2.6) is independent of $n$, which is crucial to the product-form of the invariant measure $\pi$. The condition in (2.6) will hold if $\tau_n(z,z')$ takes the form $\tau_n(z,z') = \beta_n \tau(z,z')$ for some constant $\beta_n > 0$. However, one can construct examples of $\tau_n(z,z')$ of more complicated forms that still guarantee the existence of a function $v$ satisfying (2.6) (see, e.g., Examples 2.1 and 2.2 in [31]). We also refer to Section 3.5 for discussions on the diffusive setting. (Constructions similar to those from Section 3.5 can be done in the discrete setting too.)

2.3. Examples. We start with classic queues: M/M/1, M/M/$\infty$, M/M/K, M/M/K/0. In Examples 2.1-2.5, the parameter $\lambda(z)$ takes nonnegative values while $\mu(z)$ and $\gamma(z)$ are strictly positive: $0 \leq \lambda(z) < \infty$ and $0 < \mu(z), \gamma(z) < \infty$. In all examples in this section, as long as condition (2.7) is fulfilled, there exists a finite invariant measure $\eta$ for process $(N,Z)$ on $\mathbb{N} \times \mathbb{Z}$. The unique invariant probability distribution $\pi(n,z)$ is then obtained by normalization.

Example 2.1. The M/M/1 queue was already studied in [31]: here $\lambda_n(z) = \lambda(z)$ and $\mu_n(z) = \mu(z)$ for $n \geq 0$ and $z \in \mathbb{Z}$. Hence, $r_n(z) = \rho(z)^n$ where $\rho(z) := \lambda(z)/\mu(z)$ is the traffic intensity satisfying $\rho(z) \in (0, 1)$ for all $z \in \mathbb{Z}$. Also, $\kappa_0(z) = 1 - \rho(z)$, and

$$\kappa_n(z) = \kappa_0(z)\rho(z)^n = (1 - \rho(z))\rho(z)^n, \quad n \geq 1, \quad z \in \mathbb{Z}. $$

Condition (2.7) means that, as in [31, Assumption 2.2],

$$\Xi = \sum_{(n,z)} \rho(z)^n v(z) = \sum_z \frac{v(z)}{1 - \rho(z)} < \infty. $$

Then $\eta(n,z) = \rho(z)^n v(z)$ yields a finite invariant measure for process $(N,Z)$.

Example 2.2. For an M/M/$\infty$ queue, $\lambda_n(z) = \lambda(z)$ and $\mu_n(z) = n\mu(z)$ for all $n$ and $z \in \mathbb{Z}$. Hence,

$$r_n(z) = \frac{\rho(z)^n}{n!}, \quad \text{where} \quad \rho(z) := \frac{\lambda(z)}{\mu(z)} \in (0, \infty) $$

is the offered load. The sum of all these $r_n(z)$ is $\sum_{n=0}^{\infty} r_n(z) = e^{\rho(z)}$. Thus, after normalizing, we get

$$\kappa_0(z) = e^{-\rho(z)}, \quad \text{and} \quad \kappa_n(z) = e^{-\rho(z)} \frac{\rho(z)^n}{n!}, \quad n \geq 1, \quad z \in \mathbb{Z}. $$

Condition (2.7) takes the following form

$$\Xi = \sum_{(n,z)} \frac{\rho(z)^n}{n!} v(z) = \sum_z e^{\rho(z)} v(z) < \infty. $$

Consequently, $\eta(n,z) = \rho(z)^n v(z)/n!$ yields a finite invariant measure for $(N,Z)$, and $\pi(n,z) = \eta(n,z)/\Xi$ is a unique invariant probability distribution.

Example 2.3. Let us fix an integer $K \geq 1$. For an M/M/K queue, $\lambda_n(z) = \lambda(z)$ and $\mu_n(z) = \mu(z)(n \wedge K)$ for all $n \geq 0$ and $z \in \mathbb{Z}$. Hence,

$$r_n(z) = \begin{cases} \frac{\rho(z)^n}{n!}, & \text{for } n < K, \\ \frac{\rho(z)^n}{K!K^{n-K}}, & \text{for } n \geq K, \end{cases} \quad \text{(2.11)}$$
where \( \rho(z) = \lambda(z)/\mu(z) \) is the offered load, and \( \varrho(z) = \rho(z)/K \) is the traffic intensity. Also,

\[
\kappa_0(z) = \left( \sum_{n=0}^{K-1} \frac{\rho(z)^n}{n!} + \frac{\rho(z)^K}{K!} \frac{1}{1 - \rho(z)} \right)^{-1} ;
\]

\[
\kappa_n(z) = \begin{cases} 
\kappa_0(z) \left( \frac{\rho(z)^n}{n!} \right), & n < K; \\
\kappa_0(z) \left( \frac{\rho(z)^n}{K^n} \right), & n \geq K.
\end{cases}
\]

We assume that the traffic intensity \( \varrho(z) = \rho(z)/K < 1 \) for all \( z \). Condition (2.7) now means that

\[
\Xi = \sum_{(n,z)} r_n(z)v(z) = \sum_z \left( \sum_{n=0}^{K-1} \frac{\rho(z)^n}{n!} + \sum_{n=K}^\infty \frac{\rho(z)^n}{K!K^{n-K}} \right) v(z) < \infty.
\]

Then the formula

\[
\eta(n, z) = \begin{cases} 
\frac{\rho(z)^n}{n!} v(z), & \text{for } n < K; \\
\frac{\rho(z)^n}{K^n} v(z), & \text{for } n \geq K.
\end{cases}
\]

gives a finite invariant measure for \((N, Z)\).

It is clear that the M/M/1 model in [31] is a special case of this model.

Example 2.4. For an M/M/K/0 queue, \( \lambda_n(z) = \lambda(z) \mathbf{1}(0 \leq n \leq K) \), and \( \mu_n(z) = n\mu(z) \) for \( 0 \leq n \leq K \) and \( z \in \mathbb{Z} \). (The form of rates \( \mu_n(z) \) for \( K \) is chosen for convenience.) Hence, \( r_n(z) = \rho(z)^n/n! \) where \( \rho(z) = \lambda(z)/\mu(z) \), \( n = 0, \ldots , K, \ z \in \mathbb{Z} \). Next,

\[
\kappa_0(z) = \left( \sum_{n=0}^K \frac{\rho(z)^n}{n!} \right)^{-1}, \quad \text{and} \quad \kappa_n(z) = \kappa_0(z) \frac{\rho(z)^n}{n!}, \quad n = 1, \ldots , K.
\]

Condition (2.7) is written as

\[
\Xi = \sum_z \left( \sum_{n=0}^K \frac{\rho(z)^n}{n!} \right) v(z) < \infty.
\]

A finite invariant measure for \((N, Z)\) is given by \( \eta(n, z) = \rho(z)^n v(z) \mathbf{1}(0 \leq n \leq K)/n! \).

A similar construction works for an M/M/K/1 model, where \( \lambda_n(z) = \lambda(z) \mathbf{1}(0 \leq n \leq K + \ell) \) and \( \mu_n(z) = (n K + \ell K) \mu(z) \).

Example 2.5. For an M/M/K+M queue, \( \lambda_n(z) = \lambda(z), \mu_n(z) = \mu(z)(n K + \ell) + \gamma(z)(n K + \ell) \) for \( n \geq 0 \) and \( z \in \mathbb{Z} \). Here, the rates \( \lambda(z), \mu(z) \) and \( \gamma(z) \) represent the arrival, service and abandonment rates, respectively. Hence,

\[
r_n(z) = \begin{cases} 
\frac{\rho(z)^n}{n!}, & \text{for } n < K; \\
\frac{\rho(z)^n}{K^n} \beta(z)^n, & \text{for } n \geq K,
\end{cases} \quad (2.12)
\]

where \( \rho(z) = \lambda(z)/\mu(z) \) is the offered load, \( \varrho(z) = \rho(z)/K \) is the traffic intensity, and \( \beta(z) = \lambda(z)/\gamma(z) \). For this model, the traffic intensity \( \varrho(z) \) is allowed to take any positive value, less than 1 (underloaded), equal to 1 (critically loaded) or larger than 1 (overloaded). In this model we have

\[
\kappa_0(z) = \left( \sum_{n=0}^{K-1} \frac{\rho(z)^n}{n!} + \frac{\rho(z)^K}{K!} e^{\beta(z)} \right)^{-1} ;
\]
\[ \kappa_n(z) = \begin{cases} \kappa_0(z) \frac{(\rho(z))^{n}}{n!}, & n < K; \\ \kappa_0(z) \frac{\rho(z) K \beta(z)^{n-K}}{K! (n-K)!}, & n \geq K. \end{cases} \]

Condition (2.7) reads

\[ \Xi = \sum_{(n,z)} r_n(z)v(z) = \sum_{z} \left( \sum_{n=0}^{K-1} \frac{\rho(z)^n}{n!} + \frac{\rho(z)^K}{K!} e^{\beta(z)} \right) v(z) < \infty. \]

A finite invariant measure has the form

\[ \eta(n, z) = \begin{cases} \frac{\rho(z)^n}{n!} v(z), & \text{for } n < K, \\ \frac{\rho(z)^K}{K! (n-K)!} v(z), & \text{for } n \geq K. \end{cases} \]

Example 2.6 below emerges in biological reproduction and population growth.

**Example 2.6.** Here we consider a linear growth model with immigration ([33, Example 6.4]): for each \( z \in \mathbb{Z} \), \( \lambda_n(z) = n(\lambda(z) + \theta(z)) \) for \( n \geq 0 \) and \( \mu_n(z) = n\mu(z) \) for \( n \geq 1 \). In this model each individual in the population gives birth at a rate \( \lambda(z) > 0 \); in addition, there is an exponential rate of growth of the population \( \theta(z) > 0 \) due to an external source (immigration). The death rate is given by \( n\mu(z) \). Hence,

\[ r_n(z) = \frac{\prod_{k=1}^{n} (k-1) \lambda(z) + \theta(z))}{n! \mu(z)^n} = \frac{\rho(z)^n}{n!} \prod_{k=1}^{n} \left[ 1 + \frac{\theta(z)}{\lambda(z)} \right] \]

for \( n \geq 0, z \in \mathbb{Z} \),

where \( \rho(z) = \lambda(z)/\mu(z) \in (0, \infty) \). We also have

\[ \kappa_0(z) = \left( 1 + \sum_{j=1}^{\infty} \frac{\rho(z)^j}{j!} \prod_{k=1}^{j} ((k-1) + \theta(z)/\lambda(z)) \right)^{-1}. \]

\[ \kappa_n(z) = \kappa_0(z) \frac{\rho(z)^n}{n!} \prod_{k=1}^{n} ((k-1) + \theta(z)/\lambda(z)), \quad n \geq 1. \]

Condition (2.7) in this case is

\[ \Xi = \sum_{(n,z)} r_n(z)v(z) = \sum_{(n,z)} \frac{\rho(z)^n}{n!} \prod_{k=1}^{n} (k-1 + \theta(z)/\lambda(z)) v(z) < \infty. \]

A finite invariant measure on \( \mathbb{N} \times \mathbb{Z} \) has the form

\[ \eta(n, z) = r_n(z)v(z) = \frac{\rho(z)^n}{n!} \prod_{k=1}^{n} ((k-1) + \theta(z)/\lambda(z)) v(z), \quad \text{for } n \geq 0, z \in \mathbb{Z}. \]

**Example 2.7.** The model from Example 2.6 can be modified to model growth stocks such as Internet or biotech as proposed in [17]. In that setting, the parameters \( \lambda(z) \) and \( \mu(z) \) represent the instantaneous appreciation and depreciation of the stock price due to market fluctuations, and the parameter \( \theta(z) \geq 0 \) represents the rate of increase in the stock price due to non-market factors such as the effect of additional shares via public offering. One can also include in the death rate an additional external effect parameter, that is, \( \mu_n(z) = n\mu(z) + \vartheta(z) \), where \( \vartheta(z) \geq 0 \) captures the rate of decrease in the stock price due to
non-market factors such as dividend payments (for most growth stocks, dividends are zero). In this case, we have
\[ r_n(z) = \prod_{k=1}^{n} \frac{(k-1)\lambda(z) + \theta(z)}{k\mu(z) + \vartheta(z)}; \]
the rest of the construction is carried as in Example 2.6. The invariant measure \( \eta \) can be used to study the size distribution of growth stocks. Such a model captures seasonal and environmental/external effects that may impact the growth of stock values.

3. Diffusive environment

In this section, we consider birth-death processes with diffusive rates, where the environment process can be a general reflected jump diffusion process. We include the case of oblique reflection, and consider piecewise smooth domains. There is a well-developed theory of such processes \([40, 41]\); see also an extensive bibliography in \([36]\).

3.1. Reflected jump diffusion process. Let us introduce a setting for models with a diffusive environment. We consider a jump diffusion process \( \tilde{Z}_n(t) \) moving in a piecewise smooth domain \( D \subset \mathbb{R}^d \) with smooth drift function \( z \in D \mapsto b_n(z) \) and non-degenerate diffusion matrix function \( z \in D \mapsto \sigma_n(z) \), depending on \( n \in \mathbb{N} \), and with jumps and reflections described below. \(^3\)

A domain in \( \mathbb{R}^d \) is the closure of an open connected subset. A domain is called smooth if its boundary is a \((d-1)\)-dimensional \( C^2 \) manifold. Consider an intersection of \( m \) smooth domains \( D_1, \ldots, D_m : D = \bigcap_{i=1}^{m} D_i \), and assume that it has a boundary \( \partial D \) with \( m \) \((d-1)\)-dimensional faces: \( F_i := \partial D \cap \partial D_i \). Then \( D \) is called a piecewise smooth domain in \( \mathbb{R}^d \). Denote by \( n_i(z) \) the inward unit normal vector to \( \partial D_i \) at \( z \in F_i \). An example is a convex polyhedron with \( D_i \) being half-spaces.

Define a continuous function \( \gamma_i : F_i \to \mathbb{R}^d \) satisfying \( \gamma_i(z) \cdot n_i(z) > 0 \). Let \( \ell_i = \{\ell_i(t) : t \geq 0\} \) be continuous nondecreasing processes such that \( \ell_i \) can only grow on \( F_i \), for \( i = 1, \ldots, m \). Given \( n \in \mathbb{N} \) and \( z \in D \), let \( \varpi_n(z, \cdot) \) be a finite measure on \( D \) such that \( \varpi_n(z, \cdot) \Rightarrow \varpi(z^0, \cdot) \) as \( z \to z^0 \) in \( D \) (weak continuity). Let \( J_n(t) \) be a process that is right continuous piecewise constant, with jump measure \( \varpi(\cdot, \cdot) \) (in the course of process \( \tilde{Z}_n \) it will be \( \varpi_n(\tilde{Z}_n(t) \cdot, \cdot) \)). The process \( \tilde{Z}_n(t) \) is defined as the solution to the stochastic differential equation
\[ d\tilde{Z}_n(t) = b_n(\tilde{Z}_n(t))dt + \sigma_n(\tilde{Z}_n(t))dW(t) + dJ_n(t) + \sum_{i=1}^{m} \gamma_i(\tilde{Z}_n(t))d\ell_i(t), \quad (3.1) \]
where \( W(t) \) is a standard \( d \)-dimensional Wiener process adapted to the natural filtration. The generator \( A_n \) of \( \tilde{Z}_n \) takes the form
\[ A_n g(z) = b_n(z) \cdot \nabla g(z) + \frac{1}{2} \text{tr} (\sigma_n(z)^T \sigma_n(z) \nabla^2 g(z)) + \int_D (g(z') - g(z)) \varpi_n(z, dz'), \quad (3.2) \]
and acts on a function \( g \in \mathcal{D}_z \) where
\[ \mathcal{D}_z := \{g \in C_0^2(D) : \gamma_i(\tilde{z}) \cdot \nabla g(\tilde{z}) = 0, \tilde{z} \in F_i, i = 1, \ldots, m\}. \]

In models where the environment process is a jump diffusion in domain \( D \), we set \( Z = D \).

\(^3\)We do not discuss at this point the exact conditions guaranteeing the existence and uniqueness of process \( \tilde{Z}_n(t) \) in a general setting. In the considered examples, the existence and uniqueness will be directly verified.
3.2. Joint generator. The joint Markov process $(N, Z)$ on $\mathbb{N} \times \mathcal{Z}$ has the following generator:

$$
\mathcal{L}f(n, z) = \mathcal{M}_z f(n, z) + \beta_n r_n(z)^{-1} \mathcal{A}_n f(n, z),
$$

(3.3)

for any function $f$ in the domain of $\mathcal{L}$:

$$
\mathcal{D} = \{f : \mathbb{N} \times \mathcal{Z} \to \mathbb{R} \mid f(n, \cdot) \in \mathcal{D}_z \forall n \in \mathbb{N}\}.
$$

Here, $\beta_n$ is the variability coefficient for the diffusive environment depending on the state $n$, while $r_n(z)$ is the impact factor from the birth-death process as defined in (2.2). Also,

$$
\mathcal{M}_z g(n) = \lambda_n(z) (g(n + 1) - g(n)) + 1_{n \neq 0} \mu_n(z) (g(n - 1) - g(n)),
$$

(3.4)

for any function $g$ in the domain of $\mathcal{M}_z$ for each given $z \in \mathcal{Z}$. Denote by $P^t((n, z), \cdot)$ the transition kernel of $(N, Z)$ for $(n, z) \in \mathbb{N} \times \mathcal{Z}$. The joint Markov Process $(N, Z)$ evolves as follows:

- If $N(t) = n \in \mathbb{N}$, then the component $Z(t)$ evolves as a reflected jump diffusion in $\mathcal{Z}$ with generator $\beta_n(r_n(z))^{-1} \mathcal{A}_n$.
- If $Z(t) = z \in \mathcal{Z}$, then the component $N(t)$ jumps from $n$ to $n+1$ with rate $\lambda_n(z)$ and to $n-1$ with rate $\mu_n(z)$ (when $n \neq 0$). That is, $N(t)$ evolves as a continuous-time Markov chain with the generator $\mathcal{M}_z$ in (3.4).

Remark 3.1. Under Assumption 2.1, we have $r_n(z) \to 0$ as $n \to \infty$ for each $z$, so that $r_n(z)^{-1} \to \infty$ as $n \to \infty$. It may appear that in the joint generator in (3.3), the second component gets large when $n$ is large, i.e., the environment changes the states faster for larger values of $n$. However, $\beta_n$ can be relatively small so that $\beta_n r_n(z)^{-1}$ is not large when $n$ is large. In general, the generator $\mathcal{A}_n$ also depends on $n$, as will be discussed in Section 3.5 (see equation (3.18)).

For example, consider a Markovian queueing system in a random environment where the service speed is increasing with the congestion level, while servers tend to break more frequently when the service speed is high. The repairing rate may be also larger in that setting, so that the environment dynamics tends to evolve faster. However, external factors may prevent this from happening, for instance, the high cost of increasing service and/or repair speed. Our formulation can be used to cover all these settings. \hfill \Box

3.3. Main results on the stationary distribution. For simplicity, we will suppose in this section that the generator $\mathcal{A}_n$ does not depend on $n$: $\mathcal{A}_n = \mathcal{A}$. Consequently, the subscript $n$ is omitted from the related notation. Next, we make the following assumption.

Assumption 3.1. The reflected jump diffusion with generator $\mathcal{A}$ is positive recurrent, and has a unique invariant measure $\nu$, together with boundary measures $\nu_{F_i}$, $i = 1, \ldots, m$. That is, there exists a stationary version of the process $\tilde{Z}^* = \{\tilde{Z}^*(t) : t \geq 0\}$ such that for all $t \geq 0$ $\tilde{Z}^*(t) \sim \nu$ and for each $i = 1, \ldots, m$ and bounded function $f : F_i \to \mathbb{R}$,

$$
\mathbb{E} \int_0^t f(\tilde{Z}^*(s)) d\xi_i(s) = t \int_{F_i} f(z) \nu_{F_i}(dz).
$$

Moreover, the measure $\nu$ satisfies

$$
\Xi := \sum_{n=0}^{\infty} \int_{\mathcal{Z}} r_n(z) \nu(dz) < \infty.
$$

(3.5)
Theorem 3.1. Under Assumptions 2.1 and 3.1, the process \((N, Z)\) has a finite invariant measure \(\eta\) on \(\mathbb{N} \times \mathbb{Z}\):

\[
\eta\{n\}, dz = r_n(z)\nu(dz).
\] (3.6)

The corresponding probability measure is

\[
\pi\{n\}, dz = \Xi^{-1}r_n(z)\nu(dz).
\] (3.7)

The boundary measures \(\pi_i\) for \(F_i\) are given by

\[
\pi_i\{n\}, dz = \Xi^{-1}r_n(z)\nu_{F_i}(dz).
\] (3.8)

The process \((N, Z)\) is ergodic: for each \((n, z) \in \mathbb{N} \times \mathbb{Z}\),

\[
\|P_t((n, z), \cdot) - \pi(\cdot)\|_{TV} \to 0 \text{ as } t \to \infty.
\] (3.9)

Remark 3.2. Note that the coefficient \(\beta_n\) does not appear in the invariant measure \(\eta\{n\}, dz\) in (3.6). In the jump environment with the joint generator (2.1), we had

\[
R[(n, z), (n, z')] = r_n(z^{-1}r_n(z, z')
\]

where \(r_n(z, z')\) depends on \(n\). In that setting, the measure \(\nu\) in Assumption 2.2 is also independent on \(n\). In the construction of the joint generator \(\mathcal{L}\) in (3.3), the second component \(\beta_n r_n(z)^{-1}A\) is purposely made in the multiplicative form \(\beta_n A\) such that the dependence on \(n\) is through the constant \(\beta_n\). However, this multiplicative construction does not entail any effect of \(\beta_n\) upon the invariant measure. In Section 3.5, we discuss a more general construction where the generator \(\mathcal{A}_n\) of the reflected (jump) diffusion process depends on the state of the birth-death process through the reflection domains. It is interesting to study further more general constructions of \(\mathcal{A}_n\) with dependence on \(n\). □

3.4. Examples. An M/M/1 queue with diffusive rates was already considered in [31, Section 3] and can be regarded as a special case of the M/M/K queue below, so it is omitted for brevity. We start with some cases of M/M/\(\infty\) queues with diffusive rates in Examples 3.1 -3.6. For simplicity, in these examples the drift and the diffusion coefficients are taken to be constant, although an extension of the argument to the case where these coefficients varying with \(n\) and \(z\) is straightforward. Also the jump process \(J(t)\) is disregarded, as well as the reflection processes \(\ell_i(t)\). We also repeatedly use the notation \(\tilde{Z}(t)\) as an alternative to \(Z(t)\), to describe an environmental process per se, for a fixed value \(n \in \mathbb{N}\).

Our goal is to construct a finite invariant \(\eta\) for the joint Markov process \((N, Z)\). The invariant probability distribution \(\pi\) will be obtained after the normalization.

Example 3.1. In this example, the arrival rate \(\lambda(\cdot)\) is a reflected Brownian motion (RBM) in the positive half-line \(\mathbb{R}_+\) (i.e., \(Z = D = (0, \infty)\)), with a negative drift \(-c\) and diffusion coefficient \(\sigma: \lambda(\cdot) = \tilde{Z}\) where \(\tilde{Z}(t) = -ct + \sigma W(t) + \ell(t)\) with \(c, \sigma > 0\) and \(\ell(t)\) is the regulating process (continuous and nondecreasing, \(\ell(0) = 0\) and \(\ell(t)\) only increases at times when \(\tilde{Z}(t) = 0\). Also, let the service rate \(\mu(t) \equiv \mu\) be a constant. The process \(\tilde{Z}\) has the exponential stationary distribution

\[
\nu(dz) = \frac{2c}{\sigma^2} \exp\left(-\frac{2c}{\sigma^2} z\right) dz, \quad z > 0.
\] (3.10)

We also have \(r_n(z) = (z/\mu)^n/n!\) where \(n \in \mathbb{N}\). Condition (3.5) means that

\[
\Xi = \sum_{n=0}^{\infty} \int_{0}^{\infty} r_n(z)\nu(dz) = \int_{0}^{\infty} \left(\sum_{n=0}^{\infty} \frac{(z/\mu)^n}{n!}\right) \frac{2c}{\sigma^2} \exp\left(-\frac{2c}{\sigma^2} z\right) dz
\]
\[ \begin{align*}
&= \int_{0}^{\infty} e^{z/\mu} \frac{2c}{\sigma^2} \exp \left( - \frac{2c}{\sigma^2} z \right) dz = \frac{2c}{\sigma^2} \int_{0}^{\infty} e^{-\left( \frac{2c}{\sigma^2} - 1/\mu \right) z} dz \\
&= \frac{2c}{\sigma^2} \left( \frac{2c}{\sigma^2} - 1/\mu \right)^{-1} < \infty,
\end{align*} \]

which is the case when

\[ \frac{2c}{\sigma^2} - \frac{1}{\mu} > 0. \]  

(3.11)

Under condition (3.11), a finite invariant measure of the joint process \((N, Z)\) on \(\mathbb{N} \times \mathbb{R}_+\) is given by:

\[ \eta(n, dz) = r_n(z) \nu(dz) = \frac{(z/\mu)^n}{n!} \frac{2c}{\sigma^2} \exp \left( - \frac{2c}{\sigma^2} \left( z - \mu_0 \right) \right) dz. \]

(3.12)

Example 3.2. Let \(\lambda(.) \equiv \lambda\) be a constant and \(\mu(t)\) be an RBM with a negative drift in \((\mu_0, \infty)\) with \(\mu_0 > 0\). We have the same invariant measure \(\nu(dz)\) from (3.10), shifted by \(\mu_0\), with the density

\[ \nu(dz) = \frac{2c}{\sigma^2} \exp \left( - \frac{2c}{\sigma^2} \left( z - \mu_0 \right) \right) dz, \quad z > \mu_0. \]

Next, \(r_n(z) = (\lambda/z)^n/n!\). The condition (3.5) is satisfied:

\[ \Xi = \sum_{n=0}^{\infty} \int_{\mu_0}^{\infty} r_n(z) \nu(dz) = \int_{\mu_0}^{\infty} \left( \sum_{n=0}^{\infty} \frac{(\lambda/z)^n}{n!} \right) \frac{2c}{\sigma^2} \exp \left( - \frac{2c}{\sigma^2} \left( z - \mu_0 \right) \right) dz \\
= \int_{\mu_0}^{\infty} \exp \left( \frac{2c}{\sigma^2} \left( z - \mu_0 \right) \right) dz < \infty. \]

(If we set \(\mu_0 = 0\), then this integral would be infinite.) A finite invariant measure of the joint process \((N, Z)\) is

\[ \eta(n, dz) = r_n(z) \nu(dz) = \frac{(\lambda/z)^n}{n!} \frac{2c}{\sigma^2} \exp \left( - \frac{2c}{\sigma^2} \left( z - \mu_0 \right) \right) dz. \]

Example 3.3. Here we assume that the pair \((\lambda, \mu)\) forms a two-dimensional RBM in the shifted positive quadrant \(\mathbb{R}_+ \times (\mu_0, \infty)\) (the restriction on \(\mu_0 > 0\) emerges in (3.13) below). Specifically, \(\lambda(t) = \tilde{Z}_1\) and \(\mu(t) = \tilde{Z}_2(t), \ t \geq 0\), where \(\tilde{Z} = (\tilde{Z}_1, \tilde{Z}_2)\) is an RBM in \(Z = \mathbb{R}_+ \times (\mu_0, \infty)\), given by \(\tilde{Z}(t) = ct + \sigma W(t) + RY(t), \ c = (c_1, c_2)^T \in \mathbb{R}^2\) is a drift vector, \(\sigma\) is a \(2 \times 2\) positive-definite diffusion matrix, \(R\) is a (non-singular) reflection matrix, and \(Y(t) = (Y_1(t), Y_2(t))^T\) is a regulating process (continuous and nondecreasing, with \(Y(0) = 0\) and \(Y_i\) increasing at times when \(\tilde{Z}_i(t) = 0\) for \(i = 1, 2\). Suppose the process \(\tilde{Z}\) is positive recurrent, and the skew-symmetry condition is satisfied: \(2\Sigma = RD + DR^T\) where \(\Sigma = \sigma^2\) and \(D = \text{diag}(\Sigma_{ii}, \ i = 1, 2)\). It is shown in [15] that the invariant measure \(\nu\) for \(\tilde{Z}\) has an explicit product form:

\[ \nu(dz_1, dz_2) = \alpha_1 \alpha_2 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0)} dz_1 dz_2, \quad z_1 > 0, \ z_2 > \mu_0, \]

where \(\alpha_i = 2c_i \xi_i/\Sigma_{ii}\) and \(\xi = R^{-1}c\). See also the survey [49]. Assume that

\[ \mu_0 > \frac{1}{\alpha_1}. \]  

(3.13)

We have \(r_n(z) = (z_1/z_2)^n/n!\). We also obtain

\[ \Xi = \sum_{n=0}^{\infty} \int_{0}^{\infty} \int_{\mu_0}^{\infty} \frac{1}{n!} \left( \frac{z_1}{z_2} \right)^n \alpha_1 \alpha_2 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0)} dz_1 dz_2. \]
\[ = \int_0^\infty \int_{\mu_0}^\infty e^{z_1/2} \alpha_1 \alpha_2 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0)} dz_1 dz_2 \]
\[ = \alpha_1 \alpha_2 \int_{\mu_0}^\infty \left( \int_0^\infty e^{-(\alpha_1 - 1/2)z_1} dz_1 \right) e^{-\alpha_2 (z_2 - \mu_0)} dz_2 \]
\[ = \alpha_1 \alpha_2 \int_{\mu_0}^\infty \frac{1}{\alpha_1 - 1/2} e^{-\alpha_2 (z_2 - \mu_0)} dz_2 \]
\[ < \alpha_1 \alpha_2 \int_{\mu_0}^\infty \frac{1}{\alpha_1 - 1/\mu_0} e^{-\alpha_2 (z_2 - \mu_0)} dz_2 \]
\[ = \frac{\alpha_1 \alpha_2}{\alpha_1 - 1/\mu_0} \times \frac{1}{\alpha_2} = \frac{\alpha_1}{\alpha_1 - 1/\mu_0} < \infty. \]

Here in the fourth and fifth lines we have used the condition (3.13). Thus, a finite invariant measure of the joint process \((N, Z)\) on \(\mathbb{N} \times \mathbb{Z}\) is given by

\[ \eta(n, dz_1, dz_2) = r_n(z) \nu(dz) = \frac{(z_1/2)^n}{n!} \alpha_1 \alpha_2 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0)} dz_1 dz_2. \]

**Example 3.4.** Let us modify Example 3.1 to make the arrival rate a reflected Ornstein-Uhlenbeck process: \(\lambda(t) = \bar{Z}(t)\), where \(\bar{Z}\) solves the stochastic differential equation with reflection on \(\mathbb{R}_+\):

\[ d\bar{Z}(t) = -c\bar{Z}(t) dt + \sigma dW(t) + d\ell(t), \quad (3.14) \]

where \(c, \sigma > 0\) and \(\ell(t)\) is the regulating process. By [48], the invariant measure for \(\bar{Z}\) is one-sided Gaussian:

\[ \nu(dz) = \exp \left( -\frac{2c}{\sigma^2} z^2 \right) dz, \quad z > 0. \quad (3.15) \]

Similarly to Example 3.1, \(r_n(z) = (z/\mu)^n / n!\). Condition (3.5) is satisfied for any \(\mu > 0\) since

\[ \int_0^\infty \sum_{n=0}^\infty r_n(z) \nu(dz) dz = \int_0^\infty \exp \left( \frac{z}{\mu} - \frac{2c}{\sigma^2} z^2 \right) dz \]
\[ = \exp \left( \frac{\sigma^2}{2cm^2} \right) \int_0^\infty \exp \left( -\frac{2c}{\sigma^2} (z - \frac{\sigma^2}{4cm})^2 \right) dz = \sigma \sqrt{\frac{\pi}{2c}} \Phi \left( -\frac{\sigma^2}{4cm} \right) < \infty, \]

where \(\Phi(\cdot)\) is the cumulative distribution function of the standard normal distribution. Thus, a finite invariant measure of the joint process \((N, Z)\) is given by

\[ \eta(n, dz) = r_n(z) \nu(dz) = \frac{(z/\mu)^n}{n!} \exp \left( -\frac{2c}{\sigma^2} z^2 \right) dz. \]

**Example 3.5.** Next, let us modify Example 3.2 to make the service rate a reflected Ornstein-Uhlenbeck process (3.14), but on \([\mu_0, \infty)\) for some \(\mu_0 > 0\). Its stationary distribution has density proportional to \(\nu\) from (3.15). Here we have \(r_n(z) = (\lambda/z)^n / n!\). So condition (3.5) is satisfied for any \(\lambda \geq 0\) by verifying that

\[ \int_{\mu_0}^\infty \sum_{n=0}^\infty r_n(z) \nu(dz) dz = \int_{\mu_0}^\infty \exp \left[ \frac{\lambda}{z} - \frac{2c}{\sigma^2} (z - \mu_0)^2 \right] dz < \infty. \]

(The integral is finite since \(z > \mu_0 > 0\).) Then the invariant measure of the joint process \((N, Z)\) is given accordingly.
One could also consider the model where the arrival and service form a two-dimensional reflected Ornstein-Uhlenbeck process in the positive orthant $\mathbb{R}_+ \times (\mu_0, \infty)$. However, the explicit expression for its invariant measure is not known.

Examples 3.4 and 3.5 can be extended to one-dimensional reflected diffusions with a piecewise linear drift, which will have truncated Gaussian invariant measures, see [2].

Example 3.6. Examples 3.1–3.5 can be modified to include constrained diffusions. For instance, one can think of an $M/M/\infty$ queue where the diffusive pair $(\lambda, \mu) = \tilde{Z}$ moves within a compact domain $D \subset \mathbb{R}_+ \times \mathbb{R}_+$ with a piecewise smooth boundary $\partial D$ and with the normal reflection at $\partial D$. For general ‘nice’ drift and diffusion coefficients, the Lebesgue measure on $D$ will be invariant for the process $\tilde{Z}$, and the above-type calculations could be carried through, guaranteeing a finite invariant measure for the joint process $(N, Z)$.

Example 3.7. Let us modify Example 3.1 to include Poisson jumps. Consider a jump diffusion process $\tilde{Z}$ on half-line $\mathbb{R}_+$ with constant negative drift $-c$ and diffusion coefficient $\sigma > 0$, and with i.i.d. jumps with intensity $\kappa$ and a distribution of jump size $K(dz)$ (so that $\kappa K(\cdot)$ is the spectral measure), supported on $\mathbb{R}_+$ (so that the jumps are to the right). The generator of $\tilde{Z}$ is given by

$$\mathcal{L}f(x) = -cf'(x) + \frac{\sigma^2}{2}f''(x) + \kappa \int_0^\infty [f(x + y) - f(x)] K(dy), \quad x > 0,$$

for $f : \mathbb{R}_+ \to \mathbb{R}$ in $C^2$ with condition $f'(0) = 0$. The combined drift in $\tilde{Z}$ equals $-c + \kappa K$ where $K := \int_0^\infty y K(dy)$. If this drift is negative (assuming $c > \kappa K$), then the process $\tilde{Z}$ is ergodic, see [35, Section 6]. Let $\nu$ denote the stationary distribution of $\tilde{Z}$. The MGF $\Psi_\nu(u) = \int_0^\infty e^{uy} \nu(dy)$ can be determined by rewriting (3.16) in terms of the Laplace transform. Denote by $\Psi_K$ the MGF of the jump measure $K$: $\Psi_K(u) = \int_0^\infty e^{uy} K(dy)$. After adjusting the notation of [25, Example 4.3], the MGF $\Psi_\nu$ becomes

$$\Psi_\nu(u) := \frac{Mu}{F(u)}, \quad \text{where} \quad F(u) := cu - \frac{1}{2} \sigma^2 u^2 - \kappa \Psi_K(u) + \kappa. \quad (3.17)$$

Note that $F$ is a concave function, and it has two zeros: $u = 0$ and $u = u_0 > 0$. The latter is true since $F'(0) = c - \kappa \Psi_K(0) = c - \kappa K > 0$. Similarly to Example 3.1, the quantity $\Xi$ is equal to the value of the MGF of this stationary distribution: $\Xi = \Psi_\nu(\mu^{-1})$. Therefore, $\Xi < \infty$ if $\mu^{-1} < u_0$. This condition is an analogue of (3.11).

Similar extensions of continuous diffusive cases to jump-diffusion cases could be done for the previous examples.

Example 3.8. In this example, we consider $M/M/K$ queues with the following types of diffusive arrival and/or service rates:

(a) $\lambda$ is an RBM in $[0, \mu K]$ where $\mu = \text{const};$
(b) $\lambda = \text{const}$ and $\mu$ is an RBM with a negative drift in $[\mu_0, \infty)$ where $\mu_0 > \lambda/K;$
(c) $(\lambda, \mu)$ is a two-dimensional RBM in a wedge $\{z = (z_1, z_2) \in \mathbb{R}_+^2 : z_1 \leq z_2 K\}$.

In all three cases, we have $r_n(z)$ given by (2.11) in Example 2.3. Case (a) is similar to the one discussed in Example 3.7. In Case (b), we have an invariant measure $\nu(dz)$ given in (3.5), so condition (3.5) requires that

$$\Xi = \sum_n \int_{\mu_0}^\infty r_n(z) \nu(dz).$$
The cases where only one or two of the three parameters are diffusive can be considered in a similar manner.

For the linear population growth model with immigration from Example 3.10, the parameters \( \lambda, \mu, \theta \) can again be all diffusive, represented by a three-dimensional RBM \( \tilde{Z} \) in \( \mathbb{R}_+ \times (\mu_0, \infty) \times \mathbb{R}_+ \), as was discussed in Example 3.9. The constant \( \mu_0 \) must satisfy \( \mu_0 > 1/\alpha_1 \). The process \( \tilde{Z} \) has a product-form invariant measure \( \nu(dz_1, dz_2, dz_3) = \alpha_1 \alpha_2 \alpha_3 \exp(-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0) - \alpha_3 (z_3 - \gamma_0)) dz_1 dz_2 dz_3 \).

Let us assume that constants \( \mu_0 > 0 \) and \( \gamma_0 > 0 \) satisfy \( \gamma_0 > 1/\alpha_1 \) where \( \alpha_1 = 2c_1 \xi_1/\Sigma_{11} \). Cf. Example 3.3.

We have the same formula for \( r_n(z) \) as in (2.12), with \( \rho(z) = z_1/z_2 \) and \( \beta(z) = z_1/z_3 \). Thus, condition (3.5) requires that

\[
\Xi = \sum_{n} \int_{\mathbb{R}_+ \times (\mu_0, \infty) \times \gamma_0, \infty} r_n(z) \nu(dz) = \int_{\mathbb{R}_+ \times (\mu_0, \infty) \times \gamma_0, \infty} \left( \sum_{n=0}^{K-1} \frac{(z_1/z_2)^n}{n!} + \frac{(z_1/z_2)^K}{K!} e^{z_1/z_3} \right) \times \alpha_1 \alpha_2 \alpha_3 \exp(-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0) - \alpha_3 (z_3 - \gamma_0)) dz_1 dz_2 dz_3 < \infty.
\]

It is easy to check, similarly to Example 2.5, that the first component of the integral is finite as \( z_2 > \mu_0 > 0 \) while the second and third components are finite for \( z_2 > \mu_0 > 0 \) and \( z_3 > \gamma_0 > 1/\alpha_1 \). Thus, a finite invariant measure for \((N, Z)\) is

\[
\eta(\{n\}, dz_1, dz_2, dz_3) = \left( \sum_{n=0}^{K-1} \frac{(z_1/z_2)^n}{n!} + \frac{(z_1/z_2)^K}{K!} e^{z_1/z_3} \right) \times \alpha_1 \alpha_2 \alpha_3 \exp(-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0) - \alpha_3 (z_3 - \gamma_0)) dz_1 dz_2 dz_3.
\]

The cases where only one or two of the three parameters are diffusive can be considered in a similar manner.

Example 3.10. For the linear population growth model with immigration from Example 2.6, the parameters \( \lambda, \mu, \theta \) can again be all diffusive, represented by a three-dimensional RBM \( \tilde{Z} \) in \( \mathbb{R}_+ \times (\mu_0, \infty) \times \mathbb{R}_+ \), as was discussed in Example 3.9. The constant \( \mu_0 \) must satisfy \( \mu_0 > 1/\alpha_1 \). The process \( \tilde{Z} \) has a product-form invariant measure \( \nu(dz_1, dz_2, dz_3) = \int_{\mathbb{R}_+ \times (\mu_0, \infty) \times \mathbb{R}_+} \left( \sum_{n=0}^{K-1} \frac{(z_1/z_2)^n}{n!} + \frac{(z_1/z_2)^K}{K!} e^{z_1/z_3} \right) \times \alpha_1 \alpha_2 \alpha_3 \exp(-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0) - \alpha_3 (z_3 - \gamma_0)) dz_1 dz_2 dz_3. \)
\[ \alpha_1 \alpha_2 \alpha_3 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0) - \alpha_3 z_3} d_1 d_2 d_3. \] Here we have the same formula for \( r_n(z) \) as in (2.13) with \( \rho(z) = z_1 / z_2 \). Condition (3.5) requires now that
\[
\Xi = \sum_{R_+ \times \{\mu_0, \infty\} \times R_+} (z_1 / z_2)^n \prod_{k=1}^n \left( k - 1 + \frac{z_3}{z_1} \right) \times \alpha_1 \alpha_2 \alpha_3 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0) - \alpha_3 z_3} d_1 d_2 d_3 < \infty
\]
which is finite under the condition \( z_2 > \mu_0 > 1 / \alpha_1 \), similarly to Example 3.9. Thus a finite invariant measure of \((N, Z)\) is
\[
\eta(\{n\}, d_{z_1}, d_{z_2}, d_{z_3}) = \left( \frac{z_1 / z_2}{n!} \prod_{k=1}^n \left( k - 1 + \frac{z_3}{z_1} \right) \times \alpha_1 \alpha_2 \alpha_3 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0) - \alpha_3 z_3} \right) d_{z_1} d_{z_2} d_{z_3}.
\]

The growth stock model in Example 2.7 with four parameters can also be considered analogously, with the parameters evolving as a four-dimensional RBM in a subset of \( \mathbb{R}_+^4 \).

3.5. **Reflected jump diffusion environment with a variable domain.** In this section we consider a more general setup where the domain of the (jump) diffusion varies with the state \( n \) of the birth-death process. Such a setup was considered in Section 3.4 of [31]; here we review the construction and provide an example.

For each \( n \in \mathbb{N} \), let \( D_n \subset \mathbb{R}^d \) be a piecewise smooth domain with \( m_n \) faces \( F_1^{(n)}, \ldots, F_{m_n}^{(n)} \) of the boundary \( \partial D_n \) and reflection vector fields \( f_i^{(n)} : F_i^{(n)} \to \mathbb{R}^d \). Set \( Z = \bigcup_{n \in \mathbb{N}} D_n \). We construct the joint Markov process \((N, Z)\) on \( \mathbb{N} \times Z \) via the following generator \( \mathcal{L} \) and its domain \( \mathcal{D} \):
\[
\mathcal{L} f(n, z) = \mathcal{M}_z f(n, z) + \beta_n r_n(z)^{-1} A_n f(n, z),
\]
\[
\mathcal{D} = \{ f : \mathbb{N} \times Z \to \mathbb{R} : f(n, \cdot) \in D^n_z \quad \forall n \in \mathbb{N} \}. 
\]

The generator \( A_n \) and its domain \( D^n_z \) are given by
\[
A_n g(z) = b_n(z) \cdot \nabla g(z) + \frac{1}{2} \text{tr}(\sigma_n(z)^\top \sigma(z) \nabla^2 g(z)) + \int_{D_n} (g(z') - g(z)) \varpi_n(z, dz'),
\]
\[
D^n_z = \{ g \in C^2_b(D_n) : \gamma_i(\tilde{z}) \cdot \nabla g(\tilde{z}) = 0, \tilde{z} \in F_i^{(n)} \},
\]

We modify the conditions in Assumption 3.1 as follows. Here we assume that the reflected jump diffusion with generator \( A_n \) is positive recurrent and has a finite invariant measure \( \nu_n \), with boundary measures \( v_{F_i^{(n)}} \), \( i = 1, \ldots, m_n \). Moreover, the measures \( \nu_n \) satisfy the property similar to (3.5)
\[
\Xi := \sum_{n=0}^\infty \int_{D_n} r_n(z) \nu_n(dz) < \infty.
\]

Then, by modifying the proof of Theorem 3.1, we can show that under the above conditions, the joint Markov process \((N, Z)\) has a unique invariant probability distribution
\[
\pi(\{n\}, dz) = \Xi^{-1} r_n(z) \nu_n(dz),
\]
and the corresponding boundary measures \( \pi_{F_i^{(n)}}^{(n)} \) on \( F_i^{(n)} \) (if there is a reflection) are given by
\[
\pi_{F_i^{(n)}}(\{n\}, dz) = \Xi^{-1} r_n(z) v_{F_i^{(n)}}^{(n)}(dz), \quad i = 1, \ldots, m_n.
\]
Example 3.11. Recall that in Examples 3.1–3.6, we have discussed the M/M/∞ queues with arrival and/or service rates being a reflected diffusion. However, the domain may depend on the state of the queue. For instance, Example 3.2, one can consider the service rate being an RBM with a negative drift in (μ_n, ∞) where μ_n > 0. We then obtain an invariant measure

$$\nu_n(dz) = \frac{2c}{\sigma^2} \exp\left(-\frac{2c}{\sigma^2}(z - \mu_n)\right)dz, \quad z > \mu_n.$$  

Condition (3.20) takes the form

$$\Xi = \sum_{n=0}^{\infty} \int_{\mu_n}^{\infty} r_n(z)\nu_n(dz) = \sum_{n=0}^{\infty} \int_{\mu_n}^{\infty} \left(\frac{\lambda/z}{n!}\right)^n \frac{2c}{\sigma^2} \exp\left(-\frac{2c}{\sigma^2}(z - \mu_n)\right)dz < \infty.$$  

A finite invariant measure for (N, Z) reads

$$\eta(\{n\}, dz) = r_n(z)\nu_n(dz) = \left(\frac{\lambda/z}{n!}\right)^n \frac{2c}{\sigma^2} \exp\left(-\frac{2c}{\sigma^2}(z - \mu_n)\right)dz.$$  

Similar extensions can be done in the other examples in Section 3.4.

4. Exponential Convergence to Stationarity

In this section we study the rate of convergence to stationarity of the joint Markov process (N, Z) constructed in the previous two sections. We focus on the diffusive random environment; the jump environment can be studied similarly. We consider convergence in the total variation distance, cf. (1.2). If P^t(x, ·) is the transition function of a process, and π is its stationary distribution, we say that r(·) is the convergence rate if for all x and t > 0 we get:

$$\|P^t(x, \cdot) - \pi(\cdot)\|_{TV} \leq C(x) r(t)$$

for some C(x). We consider two scenarios where the convergence rate is exponential: r(t) = e^{-ct} with a constant c > 0. In each scenario, we assume an exponential convergence rate for the process of random environment. Likewise, in each scenario, we impose conditions on the birth and death rates which result in an exponential rate for the process (N, Z). In the first scenario, the underlying birth-death process satisfies a stability condition (4.3) in Assumption 4.1, which covers queueing models such as M/M/1 and M/M/K queues. On the other hand, in the models like M/M/∞, M/M/K/0 and M/M/K+M, the underlying birth-death process does not require any condition for stability. In those models only mild assumptions upon the birth and death rates are needed, summarized in Assumption 4.4 as we discuss in the second scenario.

Classic articles on exponential convergence for a general Markov process are [27, 28]. They use Lyapunov functions V for which \(\mathcal{G}V \leq -kV\) outside a ‘small’ set in the state space of the process. Here \(\mathcal{G}\) is the generator of the Markov process, and k > 0 is a constant. There exists a substantial literature on this topic.

An important property of continuous-time Markov processes on the real line \(\mathbb{R}\) is stochastic ordering: two copies X_1 and X_2 of a process starting from points x_1 ≤ x_2 can be coupled so that X_1(t) ≤ X_2(t) for all t ≥ 0 a.s. Many common processes satisfy this property, including birth-death processes and reflected diffusions on the half-line. The second author of this article combined the approach from [27, 28] with stochastic ordering and a coupling argument to estimate explicit rates of exponential convergence; cf [35].
In this article, we use a coupling argument to establish the rates of convergence by adapting the methods from [21] and also generalizing the approach used in [31] for M/M/1 queues in a random environment.

4.1. The first scenario. Define

\[ q_i(z) := \lambda_i(z) + \mu_i(z), \quad p_i(z) = \frac{\lambda_i(z)}{q_i(z)}, \quad i \in \mathbb{N}, \quad z \in \mathbb{Z}. \] (4.1)

Assumption 4.1. The parameters \( p_i(z) \) and \( q_i(z) \) of the birth-death process satisfy the following bounds:

\[ \overline{q} := \inf_{z \in \mathbb{Z}} \inf_i q_i(z) > 0, \] (4.2)

\[ \overline{p} := \sup_{z \in \mathbb{Z}} \sup_i p_i(z) < 1/2. \] (4.3)

Remark 4.1. Condition (4.3) in Assumption 4.1 was imposed to get an exponential rate of convergence of a birth-death process (without environment states) in [21, Proposition 2]. For queueing examples with a finite number of servers, the second condition \( \overline{p} < 1/2 \) in (4.3) implies that the traffic intensity is less than one. In the linear population growth model in Example 3.10, a sufficient condition for this property to hold is that \( \lambda(z) < \mu(z) \) for each \( z \).

In addition, condition (4.3) is used in the coupling argument where a dominating embedded Markov chain with a parameter \( \overline{p} \) is introduced. This is critical in Step 4 of the proof of Theorem 4.1 below. See also Remark 4.2.

We now introduce an assumption of an exponential rate of convergence for the environmental process with generator \( A \) (which is the same as [31, Assumption 4.1]). It imposes an exponential-tail condition on the coupling time for the environmental process. Examples of processes satisfying this assumption are also given in [31, Section 4.3.2], for instance, a RBM on \([0, a]\) in [16, Chapter 2, Problem 8.2].

Assumption 4.2. There exist constants \( \alpha > 1 \) and \( \gamma > 0 \) such that for all \( z_1, z_2 \in \mathbb{Z} \) the processes \( Z_1 \) and \( Z_2 \) with generator \( A \), starting from \( Z_1(0) = z_1 \) and \( Z_2(0) = z_2 \), can be coupled in time \( \tau_{z_1,z_2} := \inf\{t \geq 0 : Z_1(t) = Z_2(t)\} \), with

\[ \mathbb{P}(\tau_{z_1,z_2} \geq t) \leq \alpha e^{-\gamma t}. \] (4.4)

Next, we define the following auxiliary function:

\[ \theta(\alpha, \beta, \gamma, a) := \frac{\beta}{\beta - a} - \frac{a\gamma}{(\beta - a)(\beta + \gamma - a)} \alpha^{-(\beta - a)/\gamma}, \] (4.5)

for any \( \alpha > 1, \beta, \gamma > 0 \) and \( a \geq 0 \). This quantity appears to be an upper bound for the MGF of the minimum of an exponential random variable and an independent variable with exponential tail (see Lemma 6.1 in Appendix B and [31, Lemma 6.1]). Also, define

\[ g(s) := \frac{1 - \sqrt{1 - bs^2}}{2ps}, \quad \text{with} \quad b := 4\overline{p}(1 - \overline{p}), \] (4.6)

\[ G(u) := g \left( \frac{\overline{q}}{\overline{q} - u} \right). \]

Remark 4.2. Following [11, Section 14.5], consider a discrete-time random walk \( S = (S_n)_{n \geq 0} \) on the set of integers \( \mathbb{Z} \) taking steps +1 and −1 with probabilities \( p \) and \( 1 - p \). By Assumption 4.1, the overall direction of this random walk is downward since \( \overline{p} < 1/2 \), that is,
\( \mathbb{E}[S_n - S_0] < 0 \) as \( n \to \infty \). Starting from \( S_0 = 0 \), the hitting time \( \tau := \min\{n > 0 : S_n = 0\} \) is a.s. finite, and has a probability–generating function:

\[
\mathbb{E}[s^{\tau}] = g(s), \quad 0 \leq s \leq b^{-1/2}.
\]

(4.7)

Note that \( b < 1 \) since \( \bar{\rho} < 1/2 \) under Assumption 4.1. Since \( \tau \geq 1 \), the function \( g(s) \) is increasing on \([0, b^{-1/2}]\); its maximal value is achieved at \( s = b^{-1/2} \) and equals

\[
g(b^{-1/2}) = \frac{1}{2\bar{\rho}b^{-1/2}} = \left[ \frac{1 - \bar{\rho}}{\bar{\rho}} \right]^{1/2}.
\]

(4.8)

Accordingly, the function \( G \) is defined for \( u \in [0, u_*] \) with \( u_* < q \) solving the equation \( \bar{\rho}/(\bar{q} - u_*) = b^{-1/2} \). This solution exists, and is unique and nonnegative.

Now, let us compute

\[
G(u^*) = g(b^{-1/2}) = (2q b^{-1/2})^{-1} = \frac{\sqrt{\bar{\rho}(1 - \bar{\rho})}}{\bar{q}},
\]

\[
\theta(\alpha, q, \gamma, u^*) = \frac{\bar{q}}{\bar{q} - u^*} - \frac{u^* \gamma}{(\bar{q} - u^*)(\bar{q} - u^* + \gamma)} \alpha^{-(\bar{q} - u^*)/\gamma}
\]

\[
= \frac{1}{\sqrt{4\bar{\rho}(1 - \bar{\rho})}} \left( 1 - \frac{\sqrt{4\bar{\rho}(1 - \bar{\rho})}}{\bar{\gamma} - \bar{q} \sqrt{4\bar{\rho}(1 - \bar{\rho})}} + \frac{1}{\bar{\gamma} - \bar{q} \sqrt{4\bar{\rho}(1 - \bar{\rho})}} \right).
\]

Assumption 4.3. Recall that \( \nu \) is the invariant measure for the process with the generator \( A \) on the state-space \( Z \). Assume the following integrability condition holds, upon the measure \( \nu \) and the cumulative birth-death ratio functions \( r_n(z) \) (see (2.2)):

\[
\sup_{u \in [0, u^*]} \sum_{n=0}^{\infty} G^n(u) \int_Z r_n(z) \nu(dz) < \infty.
\]

(4.9)

Remark 4.3. Recall the condition (3.5), which is necessary for the existence of the invariant measure. Condition (4.9) is required in Step 1 of the proof of Theorem 4.1 below.

For a single-server queue with the arrival and service rates represented by \( z \), \( z \in \mathbb{R}_+^* \), where \( Z = \{ (z_1, z_2) \in \mathbb{R}_+^2 : z_1 < z_2 \} \), and \( r_n(z) = \rho(z)^{-n} \) where \( \rho(z) = z_1/z_2 \), condition (4.9) requires that

\[
\sum_{n=0}^{\infty} G(u)^n \int_Z \rho(z)^{-n} \nu(dz) = \int_Z \left( 1 - \frac{G(u)}{z_2/z_1} \right)^{-1} \nu(dz) < \infty,
\]

provided that \( u \in [0, u^*] \) such that \( G(u) < z_2/z_1 \) for \( z = (z_1, z_2) \in Z \).

For an infinite-server queue in Example 3.1, condition (4.9) can be written as

\[
\sum_{n=0}^{\infty} \int_0^{\infty} \left( \frac{G(u)z/\mu}{n!} \right)^n \frac{2c}{\sigma^2} \exp \left( - \frac{2c}{\sigma^2} z \right) dz = \frac{2c}{\sigma^2} \left( \frac{2c}{\sigma^2} + \frac{G(u)/\mu}{2c} \right)^{-1} < \infty.
\]

This holds for all \( u \in [0, u^*] \) such that

\[
\frac{2c}{\sigma^2} - \frac{G(u)}{\mu} > 0.
\]

In Example 3.2, condition (4.9) is equivalent to

\[
\sum_{n=0}^{\infty} \int_{\mu_0}^{\infty} \frac{(\lambda G(u)/z)^n}{n!} \frac{2c}{\sigma^2} e^{-2c(z-\mu_0)/\sigma^2} dz = \frac{2c}{\sigma^2} \int_{\mu_0}^{\infty} e^{\lambda G(u)/z - 2c(z-\mu_0)/\sigma^2} dz < \infty.
\]
In this model, \( \lambda \) is any positive constant, so this also holds for any \( u \in [0, u^*] \) since 
\[
\sup_{u \in [0, u^*]} \lambda G(u) < \infty.
\]

In Example 3.3, condition (4.9) is guaranteed when
\[
\sum_{n=0}^{\infty} G(u)^n \int_0^\infty \int_0^\infty \frac{1}{n!} \left( \frac{z_1}{z_2} \right)^n \alpha_1 \alpha_2 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0)} dz_1 dz_2
\]
\[
= \int_0^\infty \int_0^\infty e^{G(u)z_1/\mu_0} \alpha_1 \alpha_2 e^{-\alpha_1 z_1 - \alpha_2 (z_2 - \mu_0)} dz_1 dz_2
\]
\[
= \alpha_1 \alpha_2 \int_0^\infty \left( \int_0^\infty e^{-(\alpha_1-G(u)/\mu_0)} z_1 dz_1 \right) e^{-\alpha_2 (z_2 - \mu_0)} dz_2
\]
\[
= \alpha_1 \alpha_2 \int_0^\infty \frac{1}{\alpha_1 - G(u)/\mu_0} e^{-\alpha_2 (z_2 - \mu_0)} dz_2
\]
\[
< \alpha_1 \alpha_2 \int_0^\infty \frac{1}{\alpha_1 - G(u)/\mu_0} e^{-\alpha_2 (z_2 - \mu_0)} dz_2
\]
\[
= \frac{\alpha_1}{\alpha_1 - G(u)/\mu_0} \times \frac{1}{\alpha_2} = \frac{\alpha_1}{\alpha_1 - G(u)/\mu_0} < \infty.
\]

This will require that \( \mu_0 > \sup_{u \in [0, u^*]} G(u)/\alpha_1 \). Other models can be treated similarly. \( \Box \)

**Remark 4.4.** Inequality (4.9) can be deduced from the following sufficient condition:
\[
\sup_{z \in Z} \frac{\lambda_{i-1}(z)}{\mu_i(z)} \leq \frac{\overline{p}}{1 - \overline{p}}. \tag{4.10}
\]

For example, for a single-server queue, the condition in (4.10) is equivalent to
\[
\sup_{z} \mu^{-1}(z) \left( \lambda(z) - \mu(z) \frac{\overline{p}}{1 - \overline{p}} \right) \leq 0.
\]

It indicates that, in addition to the stability condition \( \lambda(z) < \mu(z) \), we require that
\( \lambda(z) \leq \overline{p} \mu(z)/(1 - \overline{p}) \) for all \( z \in Z \). For a \( K \)-server queue in Example 3.8, condition (4.10) is equivalent to
\[
\sup_{z \in Z} \sup_i \frac{\lambda(z) - \mu(z)(i \wedge K)\overline{p}/(1 - \overline{p})}{\mu(z)(i \wedge K)} \leq 0.
\]

It indicates that, in addition to the stability condition \( \lambda(z) < \mu(z)K \), we require that
\( \lambda(z) \leq \overline{p} \mu(z)K/(1 - \overline{p}) \) for all \( z \in Z \).

To check that condition (4.10) implies (4.9), we will show the following claim: There exists a constant \( c \in (0, 1) \) such that for all \( z \in Z \) and \( u \in (0, u^*) \),
\[
\lim_{n \to \infty} \frac{G^n(u) \cdot r_n(z)}{G^{n-1}(u) \cdot r_{n-1}(z)} \leq c. \tag{4.11}
\]

Then, combining (4.11) with the observation that the term corresponding to \( n = 0 \) is
\( G(u)^0 r_0(z) = 1 \), we get that the series inside the integral in (4.9) is estimated from above by
\( 1 + c + c^2 + \ldots = 1/(1 - c) \). Integrating this with respect to the probability measure \( \nu \), we complete the derivation of (4.9).

Let us now verify the claim in (4.11). We can replace \( G(u) = g(s) \) for \( s = \overline{q}/(\overline{q} - u) \). Using (2.2), we can replace
\[
\frac{r_n(z)}{r_{n-1}(z)} = \frac{\lambda_{n-1}(z)}{\mu_n(z)}. \tag{4.12}
\]
Combining (4.12) with (4.10) and (4.8) in Remark 4.2, we get that the left-hand side of (4.11) is bounded by \( c = [p/(1 - p)]^{3/2} \).

Here is the result on exponential convergence in the first scenario, extending [31, Theorem 4.1].

**Theorem 4.1.** Suppose that Assumptions 3.1, 4.1, 4.2, and 4.3 hold true. Then there exists a constant \( C > 0 \) such that for all \( n \in \mathbb{N} \) and \( z \in \mathbb{Z} \), the transition probabilities for the Markov process \((N, Z)\) satisfy

\[
\|P^t((n, z), \cdot) - \pi(\cdot)\|_{TV} \leq C(1 + G(u)^n)e^{-\kappa t}.
\]

(4.13)

Here \( \pi(\cdot) \) is given in (3.7) and \( \kappa = (1 - \varepsilon)u \), where \( \varepsilon \in (0, 1) \), and \( u \in (0, u^*] \) satisfy

\[
G(u)\theta(\alpha, q, \gamma, u) = \left(1 - \alpha^{-q/\gamma} \frac{\gamma}{q + \gamma}\right)^{-\varepsilon/(1 - \varepsilon)}.
\]

(4.14)

**Remark 4.5.** The bound (4.14) holds for some \( u \) in a right neighborhood of zero. Indeed, its left-hand side is continuous in \( u \), and its right-hand side is independent of \( u \). Next, the left-hand side value at \( u = 0 \) is equal to 1 (since \( G(1) = g(0) = 1 \), and \( \theta(\alpha, q, \gamma, 0) = 1 \)). The right-hand side is greater than 1 (since \( -\varepsilon/(1 - \varepsilon) < 0 \)).

**Proof.** We modify the proof of [31, Theorem 4.1] and rectify the coupling argument for the joint Markov process \((N, Z)\). The general idea of coupling is to take two copies \((N_1, Z_1)\) and \((N_2, Z_2)\) of the process \((N, Z)\) starting from initial states \((n_1, z_1)\) and \((n_2, z_2)\) and run them jointly, achieving the coupling time \( \tau = \tau(n_1, z_1), (n_2, z_2) \) with \( \mathbb{E}[e^{\kappa \tau}] < \infty \) for some constant \( \kappa > 0 \). Here and below,

\[
\tau := \inf\{t \geq 0 : N_1(t) = N_2(t), Z_1(t) = Z_2(t)\}.
\]

(4.15)

Then Lindvall’s inequality [21] can be applied to obtain the bound

\[
\|P^t((n_1, z_1), \cdot) - P^t((n_2, z_2), \cdot)\|_{TV} \leq \mathbb{E} [e^{\kappa \tau}] e^{-\kappa t}.
\]

To produce the coupling, we need to first wait for the birth-death components \( N_1, N_2 \) being coupled at state \( n = 0 \) and then wait until either the environment processes are coupled or the birth-death processes have a birth in which case the coupling process restarts anew. The main task is to estimate the expected value \( \mathbb{E}[e^{\kappa \tau}] \) for the coupling time \( \tau \) and identify the exponent \( \kappa \). The proof is divided into seven steps, similarly to [31, Theorem 4.1], but some steps require substantial changes as highlighted below.

**Step 1.** Observe that to prove (4.13), it suffices to show

\[
\|P^t((n_1, z_1), \cdot) - P^t((n_2, z_2), \cdot)\|_{TV} \leq (G(u)^{n_1} + G(u)^{n_2}) e^{-\kappa t}.
\]

This is because we can obtain (4.13) from the above by using the definition of the total variation distance, and integrating with respect to \((n_2, z_2) \sim \pi\); integrability is guaranteed under Assumption 4.3. In turn, it suffices to show that

\[
\|P^t((n_1, z_1), \cdot) - P^t((n_2, z_2), \cdot)\|_{TV} \leq G(u)^{n_1} e^{-\kappa t}.
\]

**Step 2.** In view of Lindvall’s inequality [21], we need to prove that for the coupling time \( \tau \), we have \( \mathbb{E} [e^{\kappa \tau}] < \infty \), so that

\[
\|P^t((n_1, z_1), \cdot) - P^t((n_2, z_2), \cdot)\|_{TV} \leq 2\mathbb{P}(\tau > t) \leq 2\mathbb{E} [e^{\kappa \tau}] e^{-\kappa t}.
\]

(4.16)
**Step 3.** The coupling time $\tau$ can be written in terms of auxiliary random variables $\tau_j$, $\eta_j$, $\zeta_j$ and a stopping time $J$. Formally:

$$\tau = \sum_{j=0}^{J} \tau_j + \zeta_J.$$  

(4.17)

Here the initial random times are defined as

$$\tau_0 := \inf\{t \geq 0 \mid N_1(t) = N_2(t) = 0\},$$
$$\eta_0 := \inf\{t \geq 0 : N_1(\tau_0 + t) \lor N_2(\tau_0 + t) = 1\},$$
$$\zeta_0 := \inf\{t \geq 0 : Z_1(\tau_0 + t) = Z_2(\tau_0 + t)\},$$

where $\overline{\lambda} = \sup_z \sup_i \lambda_i(z)$. The subsequent random times are defined iteratively: for $j \geq 1$,

$$\tau_j := \inf\left\{ t \geq \eta_{j-1} : N_1 \left( \sum_{0 \leq l \leq j-1} \tau_l + t \right) = N_1 \left( \sum_{0 \leq l \leq j-1} \tau_l + t \right) = 0 \right\},$$
$$\eta_j := \inf\left\{ t \geq 0 : N_1 \left( \sum_{0 \leq l \leq j} \tau_l + t \right) \lor N_2 \left( \sum_{0 \leq l \leq j} \tau_l + t \right) = 1 \right\},$$
$$\zeta_j := \inf\left\{ t \geq 0 : Z_1 \left( \sum_{0 \leq l \leq j} \tau_l + t \right) = Z_2 \left( \sum_{0 \leq l \leq j} \tau_l + t \right) \right\}.$$

Finally, the stopping time $J$ is defined by

$$J = \min\{j \geq 0 : \zeta_j < \eta_j\}.$$  

(4.18)

Observe that if $\zeta_0 < \eta_0$, then $\tau_0 + \zeta_0$ gives the coupling time $\tau$ for $(N_1, Z_1)$ and $(N_2, Z_2)$. Otherwise, if $\zeta_0 > \eta_0$ and $\zeta_1 < \eta_1$, then $\tau_0 + \tau_1 + \zeta_1$ gives the coupling time, and so on. The procedure continues until the coupling time $\tau$ from (4.17).

**Step 4.** Here we show that for processes $(N_1, Z_1)$ and $(N_2, Z_2)$,

$$\mathbb{E}[e^{\eta_k}] \leq G(u)^{n_1^{(k)n_2}}, \quad k = 0, 1, \ldots$$  

(4.19)

First, let us study the case of $\tau_0$. Consider an embedded discrete-time Markov chain $\{N^*_z(l), l \geq 0\}$ on the state-space $\mathbb{N}$ with the transition probability from $i$ to $i+1$ given by $p_i(z)$ and that from $i$ to $i-1$ given by $1 - p_i(z)$. Cf. (4.1). Such a chain is dominated by the Markov chain $\{N^*_l(l), l \geq 0\}$ on $\mathbb{N}$ with the transition probabilities of jumps up and down $\overline{\eta}$ and $1 - \overline{\eta}$. (From the left-most state $n = 0$ both chains jump up with probability 1.)

More precisely, let $V := \min\{l \geq 0 \mid N^*_l(l) = 0\}$. Assumption 4.1 implies the following stochastic domination:

$$\tau_0 \leq U_1 + \ldots + U_V$$

where $U_i \sim \text{Exp}(\overline{\eta})$ are i.i.d. random variables independent of $V$.  

(4.20)

Indeed, the waiting times for jumps in the processes $N_1$ and $N_2$ have intensity at least $\overline{\eta}$, and in both processes, the embedded chain $\{N^*_z(l), l \geq 0\}$ has a stronger drift towards the state $n = 0$ than the chain $\{N^*_l(l), l \geq 0\}$. For $U_i$, the MGF is $\mathbb{E}[e^{uU_i}] = \overline{\eta}/(\overline{\eta} - u)$. Also,

$$\mathbb{E}\left[e^{u(U_1 + \ldots + U_V)}\right] = \mathbb{E}\left[(\mathbb{E}[e^{uU_1}])^V\right] = \mathbb{E}\left[\left(\frac{\overline{\eta}}{\overline{\eta} - u}\right)^V\right].$$
Combining this with (4.7), we get the estimate (4.19) for $\tau_0$. For $\tau_i$ with $i \geq 1$ we apply a similar argument and get inequality (4.19) with $n_1 \lor n_2$ replaced by 1.

Step 5. Use the same argument as in Step 5 of the proof of [31, Theorem 4.1]. Apply Assumption 4.2 and Lemma 6.1 from Appendix B. As a result, the random variable $J$ is stochastically dominated by a geometric random variable $J$ with parameter

$$J = \frac{\gamma}{\lambda + \gamma},$$

which has the probability-generating function

$$E[s^J] = \frac{\bar{J}s}{1 - (1 - \bar{J})s}, \quad s \in [0, 1/(1 - \bar{J})].$$

Recall, $\gamma > 0$ is the value introduced in (4.4).

Step 6. Consequently, under Assumption 4.2, by Lemma 6.1 we obtain

$$E[e^{u(\tau_0)}] \leq \theta(\alpha, \bar{q}, \gamma, u), \quad k = 0, 1, \ldots$$

Step 7. Finally we derive the upper bound for the MGF of the coupling time $\tau$. We have from Steps 4 and 6 that

$$\psi(u) := E[e^{u(\tau_0 + \zeta_0)}] \leq G(u)^{n_1 \lor n_2} \theta(\alpha, \bar{q}, \gamma, u).$$

By applying the optimal stopping theorem to the martingale

$$M_\ell = \exp \left( u \sum_{k=0}^\ell (\tau_k + \zeta_k \wedge \eta_k) - \ell \ln \psi(u) \right), \quad \ell = 0, 1, \ldots,$$

and the stopping time $J$, we obtain that

$$E[M_\ell] = E[M_0] = E[e^{u(\tau_0 + \zeta_0)}] \leq G(u) \theta(\alpha, \bar{q}, \gamma, u).$$

Now, we have $E[M_\ell] = E[\exp \left( u(\tau - J \ln \psi(u)) \right)]$. Using Hölder’s inequality, we get

$$E[\exp \left( (1 - \epsilon)uJ \right)] \leq (E[M_\ell])^{1-\epsilon} \cdot \left( E[\psi(u)^{(1-\epsilon)J/\epsilon}] \right)^{\epsilon}.$$

Here $\epsilon \in (0, 1)$ is the value from (4.14). Using the result in Step 5 with $s = \psi(u)^{(1-\epsilon)/\epsilon}$, we obtain inequality (4.13). □

4.2. The second scenario. We next consider the second scenario, starting with the following assumption.

**Assumption 4.4.** In addition to (4.2), assume that there exist constants $\tilde{\lambda} > 0$ and $\tilde{\mu} > 0$ such that $\lambda_n(z) \leq \tilde{\lambda}$ and $\mu_n(z) \geq \tilde{\mu} n$ for all $z$ and $n$.

**Remark 4.6.** Assumption 4.4 applies to the models $M/M/\infty$, $M/M/K/0$ and $M/M/K+M$ (cf. Examples 2.5 and 3.9) which do not require a stability condition like (4.3). The idea is to use an infinite-server queue to dominate the process $N$ in these models. For example, in Example 3.9, one can assume that there exist constants $\tilde{\lambda}$ and $\tilde{\mu}$ such that for all $n$,

$$\sup_z \lambda_n(z) \leq \tilde{\lambda}, \quad \inf_n \mu_n(z) \geq \tilde{\mu} n.$$
(Note that inf \( \{ \mu(z)(n \wedge K) + (n - K)^+ \gamma(z) \} \geq \inf \{ \mu(z) \wedge \gamma(z) \} \[(n \wedge K) + (n - K)^+ \] = \inf \{ \mu(z) \wedge \gamma(z) \} n \). Then the M/M/K+M queueing process is dominated by the birth-death process with birth and death rates \( \bar{\lambda} \) and \( \bar{\mu} \), respectively.

We will expand on the last remark and refer to the birth-death process with rates \( \bar{\lambda} \) and \( \bar{n} \bar{\mu} \) as \( \bar{N} = (\bar{N}(t), t \geq 0) \), assuming that \( \bar{N}(0) = 1 \). In other words, \( \bar{N} \) is a M/M/∞ queueing process; it will be used for the purpose of stochastic domination in the proof of Theorem 4.2 below. More precisely, consider the busy period

\[
\tau := \inf\{t > 0 : \bar{N}(t) = 0\}. \tag{4.21}
\]

The MGF \( \bar{G}(u) = \mathbb{E}[e^{u\tau}] \) is finite for all \( u > 0 \) and can be expressed by using Kummer’s function [14, Proposition 4.1] (see also [39, Theorem 1]). The explicit expression for \( \bar{G}(u) \) is not essential for our results and omitted for brevity.

**Theorem 4.2.** Under Assumptions 3.1, 4.2, 4.3 and 4.4, the results in Theorem 4.1 hold with \( \bar{G}(u) = \mathbb{E}[e^{u\tau}] \). This includes (4.14) with \( \varepsilon \in (0, 1) \), \( u > 0 \), and \( \bar{G} \) in place of \( G \).

**Proof.** We follow the same steps as in the proof of Theorem 4.1. The arguments in Steps 1–3 and 5–7 remain valid without changes. In Step 4, we consider the MGF \( \bar{G}(u) \): it is instrumental as the above process \( \bar{N} \) can be used to dominate components \( N_1 \) and \( N_2 \) in the processes \((N_1, Z_1)\) and \((N_2, Z_2)\) with initial states \((n_1, z_1)\) and \((n_2, z_2)\) (cf. (4.15)). As before, let \( \tau = \tau_{(n_1, z_1), (n_2, z_2)} \) denote the coupling time for processes \((N_1, Z_1)\) and \((N_2, Z_2)\). Suppose that \( \tau \) satisfies

\[
\mathbb{E}[e^{u\tau}] \leq \bar{G}(u)^{n_0}, \text{ where } n_0 = n_1 \lor n_2. \tag{4.22}
\]

Then the rest of the argument is completed as in Theorem 4.1. Hence, we focus on the proof of (4.22). To this end, given \( n \), we set

\[
\tau_0 = \inf\{t \geq 0 : \bar{N}(t) = n\};
\]

\[
\tau_k = \inf\{t \geq \tau_{k-1} : \bar{N}(t + \tau_{k-1}) = n - k\} \text{ for } k = 1, \ldots, n.
\]

Then \( \tau_n \equiv \tau \). Let us show that for all \( k = 1, \ldots, n \),

\[
\mathbb{E}[e^{u\tau_k}] \leq \bar{G}(u)^k. \tag{4.23}
\]

Use induction by \( k \). For \( k = 0 \), the bound holds trivially. For the induction step: given \( k \geq 1 \),

\[
\mathbb{E}[e^{u\tau_k}] = \mathbb{E}[\mathbb{E}[e^{u\tau_k} | \tau_{k-1}]] = \mathbb{E}[e^{u\tau_{k-1}} \mathbb{E}[e^{u(\tau_k - \tau_{k-1})} | \tau_{k-1}]] = \mathbb{E}[e^{u\tau_k}]. \tag{4.24}
\]

Consider the process \( \tilde{N} = \{\tilde{N}(t), t \geq 0\} \) where \( \tilde{N}(t) = \bar{N}(t + \tau_{k-1}) - (n - k) \). If we let it run only until the time \( t = \tau_k - \tau_{k-1} \), this behaves as a birth-death process with birth rate \( \bar{\lambda} \) and death rate \( \bar{\mu}(n - k + m) \) at state \( m \), starting from \( \tilde{N}(0) = 1 \). The hitting time of 0 by the process \( \tilde{N} \) (that is, the busy time) is \( \tau_k - \tau_{k-1} \). Next, the birth rates of this new process \( \tilde{N} \) coincide with the birth rates of \( \bar{N} \) whereas the death rates of \( \tilde{N} \) are at least as large as in \( \bar{N} \). Thus, \( \tau_k - \tau_{k-1} \) is stochastically dominated by \( \tau \), the busy period in \( \bar{N} \) whose MGF is \( \bar{G}(u) \), that is, \( \tau_k - \tau_{k-1} \leq \tau \). Therefore, for \( u > 0 \),

\[
\mathbb{E}[e^{u(\tau_k - \tau_{k-1})} | \tau_{k-1}] \leq \bar{G}(u) \tag{4.25}
\]

Suppose that (4.23) is true for \( k - 1 \) instead of \( k \). Combining this assumption with (4.24) and (4.25), we get (4.23) for \( k \). This completes the proof of (4.23) and with it the proof of (4.22).

\[\Box\]
5. POLYNOMIAL CONVERGENCE TO STATIONARITY

In this section, instead of the conditions on the birth and death rates in Assumptions 4.1 and 4.4, we make the following Assumption 5.1 such that the joint Markov process \((N, Z)\) has a polynomial rate of convergence, while the generator of environment \(A\) satisfies Assumption 4.2 with an exponential rate of convergence.

Subexponential/subgeometric convergence has been studied less than geometric. Nevertheless, over the last few decades it has amassed a substantial literature. In [13, 9] it was studied for general continuous time Markov processes, using a modified Lyapunov condition: \(\mathcal{L}V \leq -\varphi(V)\) for a sublinear function \(\varphi\) (here \(\mathcal{L}\) is the generator of this Markov process). Continuous-time Markov chains on the state space \(\mathbb{N}\) with subgeometric convergence were studied in [23], including applications to birth-death process. Another related article is [24], giving estimates for hitting time moments. A slightly different approach was taken in [3]. Combining the approach from [13, 9] with stochastic ordering property, subgeometric convergence results are also recently developed in [37]. See also the subexponential upper and lower bounds in Wasserstein distance for general Markov processes in [34].

**Assumption 5.1.** There exist constants \(\overline{\lambda}_n\) and \(\bar{\mu}_n\) such that \(\lambda_n(z) \leq \overline{\lambda}_n\) and \(\mu_n(z) \geq \bar{\mu}_n\) for each \((n, z) \in \mathbb{N} \times Z\). Moreover, there exist a nondecreasing function \(V : \mathbb{N} \rightarrow [0, \infty)\) with \(V(0) = 0\) and a constant \(\overline{C}_V > 0\) such that the generator \(\overline{\mathcal{L}}\) of the birth-death process \(\overline{N} = \{\overline{N}(t), t \geq 0\}\) with rates \(\overline{\lambda}_n\) and \(\bar{\mu}_n\) satisfies

\[
\overline{\mathcal{L}}V(n) := \overline{\lambda}_n(V(n + 1) - V(n)) + \bar{\mu}_n(V(n - 1) - V(n)) \leq -\overline{C}_V, \quad n \geq 1. \tag{5.1}
\]

**Remark 5.1.** It is clear that if \(\lambda_n(z) \leq \overline{\lambda}_n\) and \(\mu_n(z) \geq \bar{\mu}_n\) for each \(z\) and \(n\), then the process \(N\) can be dominated by \(\overline{N}\) described above. Taking \(V(n) = n + 1\), the condition in (5.1) becomes \(\overline{\lambda}_n - \bar{\mu}_n \leq -\overline{C}_V\). We can rewrite it as \(\inf_{n \geq 1} (\overline{\mu}_n - \overline{\lambda}_n) > 0\). For example, consider \(\lambda_n(z) = \overline{\lambda}(z)\) and \(\mu_n(z) = \bar{\mu}(z) + n^{1/2}\) with \(\overline{\lambda}(z) \equiv \bar{\mu}(z)\) for all \(z\). (This can be regarded as a single-server queue with state-dependent service rates.) \(\square\)

In the following lemma, we drive a bound for the expected hitting time for the dominating process under the conditions in Assumption 5.1. The proof of the lemma is postponed until the end of this section.

**Lemma 5.1.** Let \(P^t(n, \cdot)\) denote the transition function of the dominating process \(\overline{N}\) in Assumption 5.1. The hitting time \(\tau_0 := \inf\{t \geq 0 \mid \overline{N}(t) = 0\}\) of 0 satisfies

\[
\mathbb{E}_n[\tau_0 \mid \overline{N}(0) = n] \leq \frac{V(n)}{\overline{C}_V}. 
\]

The process \(\overline{N}\) has a unique stationary distribution \(\pi\). Furthermore, \(\mathbb{E}_\pi[V] < \infty\), and

\[
\|P^t(n, \cdot) - \pi(\cdot)\|_{TV} \leq \frac{2(\mathbb{E}_\pi[V] + V(n))}{\overline{C}_V} \times \frac{1}{t}, \quad t > 0, \quad n \in \mathbb{N}. \tag{5.2}
\]

Now we state the main result on polynomial convergence.

**Theorem 5.1.** Under Assumptions 3.1, 4.2 and 5.1, there exists a constant \(C\) such that for joint process \((N, Z)\), we have

\[
\|P^t((n, z), \cdot) - \pi(\cdot)\|_{TV} \leq \frac{C(1 + V(n))}{t}, \quad t > 0, \quad (n, z) \in \mathbb{N} \times Z. \tag{5.3}
\]
Proof. We again follow the approach from [31] with a seven-step proof, as in Theorems 4.1 and 4.2. Here we estimate the expectation of the coupling time directly. Under Assumption 5.1, the component \(N \in (N,Z)\) is dominated by \(\overline{N}\). We modify Steps 1–7 from the proof of Theorem 4.1 as follows.

**Step 1:** Here we show that the stationary distribution \(\pi\) for the process \((N,Z)\) satisfies \(E_\pi[V] < \infty\). Indeed, by Assumption 5.1, this stationary distribution \(\pi\) for the component \(N\) is stochastically dominated by \(\overline{\pi}\), the stationary distribution of the process \(\overline{N}\). Consequently, \(E_\pi[V] \leq E_{\overline{\pi}}[V]\) and \(E_{\pi}[V] < \infty\) by Lemma 5.1. Next, we must prove the version of (5.3) with two starting points:

\[
\|P^t((n_1, z_1), \cdot) - P^t((n_2, z_2), \cdot)\|_{TV} \leq \frac{C(V(n_1) + V(n_2))}{t}.
\]  

(5.4)

Similarly to Step 1 in the proof of Theorem 4.1, the bound \(E_\pi[V] < \infty\), together with (5.4), gives us the required result (5.3).

The next six steps are devoted to the proof of (5.4). For brevity, in each step we only highlight the changes compared to the same step in the proof of Theorem 4.1.

**Step 2:** Instead of (4.16), we use the Markov inequality for the coupling time \(\tau = \tau_{(n_1, z_1), (n_2, z_2)}\):

\[
\|P^t((n_1, z_1), \cdot) - P^t((n_2, z_2), \cdot)\|_{TV} \leq 2E(\tau > t) \leq \frac{2E[\tau]}{t}, \quad t > 0.
\]

(5.5)

**Step 3:** Here we obtain the same expression for the coupling time \(\tau\) as in (4.17).

**Step 4:** We use random variables \(\tau_j, \zeta_j, \eta_j\) as defined earlier. Instead of estimating the MGF, we get estimates for the mean of the stopping time, and this serves as the backbone of our proof. The required property is already established in Lemma 5.1: \(E[\tau_0] \leq V(n_1 \lor n_2)/\overline{C}_V\) for \(j = 0\), and similarly with \(n_1 \lor n_2\) replaced by \(1\) for \(j \geq 1\): \(E[\tau_j] \leq V(1)/\overline{C}_V\). Combining these estimates, we get:

\[
E[\tau_j] \leq \frac{V(n_1 \lor n_2 \lor 1)}{\overline{C}_V}.
\]

(5.6)

**Step 5:** Recall the stopping time \(\widehat{J}\) in (4.18). Note that it is stochastically dominated by a geometric random variable \(\overline{J}\) with parameter \(\overline{\gamma} = \overline{P}(\zeta_k < \eta_k)\). By Lemma 6.1, we get

\[
\overline{\gamma} = \frac{\gamma}{\overline{\lambda} + \gamma} \alpha^{-\overline{\lambda}/\gamma}.
\]

(5.7)

Thus, the expectation of \(\overline{J}\) is given by

\[
E[\overline{J}] = (1 - \overline{\gamma})\overline{\gamma}^{-1} \leq \overline{\gamma}^{-1} = \frac{\overline{\lambda} + \gamma}{\gamma} \alpha^{\overline{\lambda}/\gamma}.
\]

(5.8)

**Step 6:** Continuing Step 4, we get estimates for the mean:

\[
E[\zeta_j \lor \eta_j] \leq E[\eta_j] \leq \overline{\lambda}^{-1}.
\]

(5.9)

Let \(\xi_j = \tau_j + \zeta_j \lor \eta_j\). By Assumption 5.1 and (5.9), combined with (5.6), we have

\[
E[\xi_k] = E[\tau_k + \zeta_k \lor \eta_k] \leq E[\tau_j] + \overline{\lambda}^{-1} \leq \overline{C}_V := \frac{V(n_1 \lor n_2 \lor 1)}{\overline{C}_V} + \overline{\lambda}^{-1} < \infty, \quad k \geq 1.
\]

(5.10)

**Step 7:** We have the following estimates of the expectation of the coupling time. Define the random walk \(S_k := \xi_0 + \xi_1 + \ldots + \xi_k, \quad k \geq 0\). Then its centered version \(M_k = S_k - E[S_k]\), \(k \geq 0\), is a martingale. From the estimate (5.10), we get that the process \(\{S_k - k\overline{C}_V : k \geq 0\},\)
is a supermartingale. Applying the optional stopping theorem with the stopping time $J$, we get

$$E[S_J] \leq E[J] \cdot C_\xi + E[S_0].$$

Combining this estimate with (5.8) and (5.10), we get

$$E[S_J] \leq C_\xi \cdot \left(1 + \frac{\lambda + \gamma}{\gamma} \right).$$

Applying Lindvall’s inequality from [22, Chapter 1] we complete the proof of (5.4), and with it the proof of the main result (5.3). □

**Proof of Lemma 5.1.** We adapt the proof of [37, Theorem 1]. Assume that $\mathbb{N}(0) = n$. From the condition (5.1), we get that the process $Y(t) = \mathcal{C}_V(t \wedge \tau_0) + V(N(t \wedge \tau_0))$ is a nonnegative local supermartingale. By Fatou’s lemma, it is a true supermartingale. Then by the optional stopping theorem: $E[Y(\tau_0)] \leq E[Y(0)] = V(N(0)) = V(n)$. Next, $Y(\tau_0) = \mathcal{C}_V\tau_0 + V(N(\tau_0)) = \mathcal{C}_V\tau_0$. Combining these observations, we complete the proof that

$$E[\tau_0] \leq \frac{V(n)}{C_V}. \quad (5.11)$$

Next, $\mathcal{P}^t(x, y) > 0$ for all $x, y \in \mathbb{N}$ and $t > 0$. Apply the classification adopted in [27] on transient, null recurrent, and positive recurrent processes with counting reference measure. The singleton $\{0\}$ has a positive reference measure. Therefore, the process $\mathbb{N}$ is positive recurrent. Consequently, $\mathbb{N}$ has a unique stationary distribution $\pi$, and we have convergence $\|P^t(n, \cdot) - \pi(\cdot)\|_{TV} \to 0$ for any initial state $n$. Recall the condition $\mathcal{L}V \leq -\mathcal{C}_V$. It holds for all $n \in \mathbb{N}$, except $n = 0$. Using the terminology of [27], the singleton $\{0\}$ is a small set. Thus, $E_\pi[V] < \infty$.

Consider now two versions $\mathbb{N}_1$ and $\mathbb{N}_0$ of the process $\mathbb{N}$, one starting from the state $n$, and the other from the stationary distribution $\pi$ (the stationary version). Both are dominated by the version $\mathbb{N}_*$ starting from $n \vee \pi^*$ where $\pi^* \sim \pi$:

$$\mathbb{N}_0(t) \leq \mathbb{N}_*(t) \quad \text{and} \quad \mathbb{N}_1(t) \leq \mathbb{N}_*(t) \quad \text{for all} \quad t \geq 0.$$

Hence, for the hitting time $\tau_* := \inf\{t \geq 0 \mid \mathbb{N}_*(t) = 0\}$ we also have $\mathbb{N}_0(\tau_*) = \mathbb{N}_1(\tau_*) = 0$. Couple the processes $\mathbb{N}_0$ and $\mathbb{N}_1$ so that $\mathbb{N}_0(t) = \mathbb{N}_1(t) = 0$ for $t > \tau_*$. By a standard coupling argument,

$$\|P^t(n, \cdot) - \pi(\cdot)\|_{TV} = \text{sup} \left\{ \|\mathbb{P}(\mathbb{N}_0(t) \in A) - \mathbb{P}(\mathbb{N}_1(t) \in A)\| : A \subseteq \mathbb{N} \right\} \leq 2\mathbb{P}(\tau_* > t) \leq \frac{2E[\tau_*]}{t}. \quad (5.12)$$

Here we used stationarity of the process $\mathbb{N}_1$: for every $t \geq 0$, $\mathbb{N}_1(t) \sim \pi$. Combining (5.12) with (5.11) yields

$$\|P^t(n, \cdot) - \pi(\cdot)\|_{TV} \leq \frac{2E[V(n \vee \pi^*)]}{C_Vt}, \quad \pi^* \sim \pi. \quad (5.13)$$

Finally, let us estimate $E[V(n \vee \pi^*)]$. Since $V$ is nondecreasing,

$$V(\max(n, N)) = \max(V(n), V(N)) \leq V(n) + V(N).$$

Taking expectation, we get

$$E[V(n \vee \pi^*)] \leq V(n) + E[V(\pi^*)] = V(n) + E_\pi[V]. \quad (5.14)$$
Combining (5.13) with (5.14), we get the estimate in the statement of Lemma 5.1.

Remark 5.2. It is reasonable to expect that convergence of the joint process \((N, Z)\) will be at the slower of the two rates: the one of the birth-death process in itself and the one of the environment process. As we have shown in Theorem 5.1, the convergence rate for \(X = (N, Z)\) is \(1/t\), which is the slower of the rates for the two components. It would be interesting to consider more general subexponential convergence rates \(\psi(t)\), such as \(t^{-\alpha}\) or \(\exp\left[-c(\ln t)^{1-\varepsilon}\right]\) for \(\alpha, \varepsilon > 0\). For example, the birth-death process with arrival rates 1 (independent of the position) and service rates \(r_n\) has polynomial rate of convergence \(t^{-c}\) for any \(c > 0\) (see [24, Example 1.9]). Such results would require proving that \(\mathbb{E}[\psi(S_T)] < \infty\), which can be harder than proving that \(S_T\) has finite mean or finite exponential moments. It would be interesting to further investigate the polynomial rate of convergence for such models in future work.

6. Appendix

6.1. Appendix A: Proofs of Theorems 2.1 and 3.1.

Proof of Theorem 2.1. The irreducibility and aperiodicity properties are straightforward. For the measure \(\eta(n, z)\) in (2.9) to be finite, by Assumption 2.2,

\[
\sum_{(n, z)} \eta(n, z) = \sum_{(n, z)} r_n(z)v(z) = \Xi < \infty. 
\]

To verify that \(\eta(n, z)\) in (2.9) is an invariant measure, we prove that \(\eta R = 0\):

\[
-\eta(n, z)R[(n, z), (n, z)] \\
= \eta(n - 1, z)R[(n - 1, z), (n, z)] + \eta(n + 1, z)R[(n + 1, z), (n, z)] \\
+ \sum_{z' \neq z} \eta(n, z')R[(n, z'), (n, z)], \quad n = 1, 2, \ldots, \quad z \in \mathbb{Z}; \\
\tag{6.1}
\]

\[
-\eta(0, z)R[(0, z), (0, z)] \\
= \eta(1, z)R[(1, z), (0, z)] + \sum_{z' \neq z} \eta(0, z')R[(0, z'), (0, z)], \quad n = 0, \quad z \in \mathbb{Z}. 
\]

For (6.1) with \(n \geq 1\), the left-hand side is

\[
\eta(n, z) \sum_{(n', z') \neq (n, z)} R[(n, z), (n', z')] \\
= \eta(n, z)(R[(n, z), (n + 1, z)] + R[(n, z), (n - 1, z)] + \sum_{z' \neq z} R[(n, z), (n, z')]) \\
= r_n(z)v(z)(\lambda_n(z) + \mu_n(z) + \sum_{z' \neq z} r_n(z)^{-1} \tau_n(z, z')) \\
= r_n(z)v(z)(\lambda_n(z) + \mu_n(z)) + v(z) \sum_{z' \neq z} \tau_n(z, z'), 
\]

and the right-hand side is equal to

\[
r_{n-1}(z)v(z)\lambda_{n-1}(z) + r_{n+1}v(z)\mu_{n+1}(z) + \sum_{z' \neq z} r_n(z')v(z')r_n(z')^{-1} \tau_n(z', z) 
\]
We get equality thanks to the assumption in (2.6) and the detailed balance equation in (2.3). For (6.1) with \( n = 0 \), the left-hand side is

\[
\eta(0, z) \sum_{z' \not= z} R([0, z], (0, z')) = r_0(z)v(z)(R([0, z], (1, z)] + \sum_{z' \not= z} R([0, z], (0, z')))
\]

\[
= r_0(z)v(z)(\lambda_0(z) + \sum_{z' \not= z} r_0(z)^{-1} \tau_0(z, z')) = r_0(z)v(z) \lambda_0(z) + v(z) \sum_{z' \not= z} \tau_0(z, z'),
\]

and the right-hand side is

\[
r_1(z)v(z)\mu_1(z) + \sum_{z' \not= z} r_0(z')v(z')r_0(z')^{-1} \tau_0(z', z) = r_1(z)v(z)\mu_1(z) + \sum_{z' \not= z} v(z')\tau_0(z', z).
\]

This again leads to the equality thanks to (2.6) and (2.4) for \( n = 0 \). Thus we have shown that \( \pi(n, z) \) in (2.8) is an invariant probability measure. The positive recurrence property follows from [29, Theorem 3.5.3] (see also [38, Theorem 2.7.18]). The ergodicity property of convergence in total variation follows from [26].

**Proof of Theorem 3.1.** The proof follows from an analogous argument as that of Theorem 3.1 in [31], so we only highlight the differences. We apply [20], and use their notation as follows: let \( E = \mathbb{N} \times \mathcal{Z} \) and \( U = \{0, 1, \ldots, m\} \), where “0” indicates \( \mathcal{Z} \) and \( i = 1, \ldots, m \) for the faces \( F_1, \ldots, F_m \) of the boundary, and for \( n \in \mathbb{N}, z \in \mathcal{Z} \) and \( u \in U, \)

\[
\mu_0(\{u\} \times \{n\} \times dz) = \mathbf{1}_{u=0} r_n(z) v(dz), \quad \mu_1(\{u\} \times \{n\} \times dz) = \mathbf{1}_{u \not= 0} r_n(z) \nu_i(dz),
\]

\[
\mu^E(\{n\} \times dz) = r_n(z) v(dz), \quad \nu^E(\{n\} \times dz) = r_n(z)(\nu_{F_1}(dz) + \cdots + \nu_{F_m}(dz)),
\]

\[
\eta_0((n, z), \{u\}) = \mathbf{1}_{u=0}, \quad \eta_1((n, z), \{u\}) = \mathbf{1}_{u \not= 0},
\]

\[Af((n, z), u) := \beta_n^{-1} r_n(z) f(n, z),\]

\[Bf((n, z), u) := \mathbf{1}_{u \not= 0, z \in \partial D, i = 1, \ldots, m} \gamma u(z) \cdot \nabla f(z).\]

To check [20, Condition 1.2] on the absolutely continuous generator \( A \) and the singular generator \( B \), we can verify the conditions (i)-(v) in the same way as in the proof of [31, Theorem 3.1]. For the main condition in [20, Theorem 1.7, (1.17)], we need to show that the generators \( A \) and \( B \) satisfy

\[
\int_{E \times U} Af(x, u)\mu_0(dx \times du) + \int_{E \times U} Bf(x, u)\mu_1(dx \times du) = 0. \tag{6.2}
\]

By the definitions of \( A \) and \( B \), we can write the left hand side as

\[
\sum_{n=0}^{\infty} \int_{\mathcal{Z}} \beta_n^{-1} r_n(z) \mathcal{M}_z f(n, z) v(dz)
\]

\[+ \sum_{n=0}^{\infty} \left( \int_{\mathcal{Z}} Af(n, z) v(dz) + \sum_{i=1}^{m} \int_{F_i} \gamma_i(z) \cdot \nabla f(z) \nu_{F_i}(dz) \right)\]

The sum of the last two terms is equal to zero, because the basic adjoint relationship holds for the reflected jump diffusion process \( \tilde{Z} \) (see, e.g., [49]), that is, for \( f \in C^2_b(Z) \),

\[
\int_{\mathcal{Z}} Af(n, z) v(dz) + \sum_{i=1}^{m} \int_{F_i} \gamma_i(z) \cdot \nabla f(z) \nu_{F_i}(dz) = 0.
\]
For each $z \in \mathbb{Z}$, the birth-death process $N(t)$ has the stationary distribution given in (2.2) and (2.5), which satisfy $r_n(z)M_z f(n, \cdot) = 0$ for each $z \in \mathbb{Z}$ and $n \in \mathbb{Z}$. Multiplying this by $\beta_n^{-1}$ and integrating over $z \in \mathbb{Z}$, we get:

$$\sum_{n=0}^{\infty} \int_{\mathbb{Z}} \beta_n^{-1} r_n(z)M_z f(n, z) \nu(dz) = 0.$$ 

Thus we have verified that (6.2) holds. The rest of the proof follows the same argument as the proof of [31, Theorem 3.1].

6.2. Appendix B: A Comparison Lemma.

**Lemma 6.1** (Lemma 5.1 in [31]). Fix constants $\alpha > 1$, $\beta, \gamma > 0$. Take two independent random variables $\xi \sim \text{Exp}(\beta)$ and $\eta > 0$ with $\mathbb{P}(\eta > u) \leq \alpha e^{-\gamma u}$ for $u \geq 0$. Then

$$\mathbb{P}(\eta < \xi) \geq \frac{\alpha^{-\beta/\gamma} \gamma}{\beta + \gamma}.$$  (6.3)

For $a \in [0, \beta + \gamma)$, the moment-generating function for $\xi \land \eta$ satisfies

$$\mathbb{E}[e^{a(\xi \land \eta)}] \leq \theta(\alpha, \beta, \gamma, a),$$  (6.4)

where the function $\theta$ is defined in (4.5).

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