MagFace: A Universal Representation for Face Recognition and Quality Assessment (Supplementary Material)

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A. Proofs for MagFace

Recall the MagFace loss for a sample $i$ is

$$L_i = -\log \frac{e^{s \cos(\theta_{y_i} + m(a_i))}}{e^{s \cos(\theta_{y_i} + m(a_i))} + \sum_{j=1,j\neq y_i}^{n} e^{s \cos(\theta_j)}} + \lambda_g g(a_i)$$

(1)

Let $A(a_i) = s \cos(\theta_{y_i} + m(a_i))$ and $B = \sum_{j=1,j\neq y_i}^{n} e^{s \cos(\theta_j)}$ and rewrite the loss as

$$L_i = -\log \frac{e^{A(a_i)}}{e^{A(a_i)} + B} + \lambda_g g(a_i)$$

(2)

We first introduce and prove Lemma 1.

**Lemma 1.** Assume that $f_i$ is top-k correctly classified and $m(a_i) \in [0, \pi/2]$. If the number of identities $n$ is much larger than $k$ (i.e., $n \gg k$), the probability of $\theta_{y_i} + m(a_i) \in [0, \pi/2]$ approaches 1.

**Proof.** Denote the angle between feature $f_i$ and center class $W_j$, $j \in \{1, \cdots, n\}$ as $\theta_j$. Assuming the distribution of $\theta_j$ is uniform, it’s easy to prove $P(\theta_j + m(a_i) \in [0, \pi/2]) = \pi/2 - m(a_i)$. Let $p = \pi/2 - m(a_i)$. If $f_i$ is top-k correctly classified, the probability of $\theta_{y_i} + m(a_i) \in [0, \pi/2]$ is the same as the probability of there are at least $k$ $\theta$ to satisfy $\theta + m(a_i) \in [0, \pi/2]$. Then the probability is

$$P(\theta_{y_i} + m(a_i) \in [0, \pi/2]) = \sum_{i=k}^{n} \binom{n}{i} p^i (1-p)^{(n-i)}$$

(3)

$$= 1 - \sum_{i=0}^{k-1} \binom{n}{i} p^i (1-p)^{(n-i)}$$

When $n$ is a large integer and $n \gg k$, each $\binom{n}{i} p^i (1-p)^{(n-i)}$, $i = 1, 2, \cdots, k-1$ converges to 0. Therefore, probability of $\theta_{y_i} + m(a_i) \in [0, \pi/2]$ approaches 1.

Lemma 1 is fundamental for the following proofs. The number of identities is large in real-world applications (e.g., 3.8M for MS1Mv2 [2, 1]). Therefore, the probability of $\theta_{y_i} + m(a_i) \in [0, \pi/2]$ approaches 1 in most cases.

A.1. Requirements for MagFace

In MagFace, $m(a_i), g(a_i), \lambda_g$ are required to have the following constraints:

1. $m(a_i)$ is an increasing convex function in $[l_a, u_a]$ and $m'(a_i) \in (0, K]$, where $K$ is an upper bound;
2. $g(a_i)$ is a strictly convex function with $g'(u_a) = 0$;
3. $\lambda_g \geq \frac{sK}{g'(u_a)}$.

A.2. Proof for Property of Convergence

We prove the property of convergence by showing the strictly convexity of the function $L_i$ (Property 1) and the existence of the optimum (Property 2).

**Property 1.** For $a_i \in [l_a, u_a]$, $L_i$ is a strictly convex function of $a_i$.

**Proof.** The first and second derivatives of $A(a_i)$ are

$$A'(a_i) = -s \sin(\theta_{y_i} + m(a_i)) m'(a_i)$$

(4)

$$A''(a_i) = -s \cos(\theta_{y_i} + m(a_i)) (m'(a_i))^2 - s \sin(\theta_{y_i} + m(a_i)) m''(a_i)$$

According to Lemma 1, we have $\cos(\theta_{y_i} + m(a_i)) \geq 0$ and $\sin(\theta_{y_i} + m(a_i)) \geq 0$ . Because we define $m(a_i)$ to be convex and $g(a_i)$ to be strictly convex when $a_i \in [l_a, u_a]$, $m''(a_i) \geq 0$ and $g''(a_i) > 0$ always hold. Therefore, $A''(a_i) \leq 0$.

The first and second order derivatives of the loss $L_i$ are

$$\frac{\partial L_i}{\partial a_i} = -\frac{B}{e^{A(a_i)} + B} A'(a_i) + \lambda_g g''(a_i)$$

(5)

$$\frac{\partial^2 L_i}{(\partial a_i)^2} = -\frac{B}{e^{A(a_i)} + B} \left( \frac{(e^{A(a_i)} + B) A''(a_i) - B e^{A(a_i)} A'(a_i)^2}{(e^{A(a_i)} + B)^2} \right) + \lambda_g g''(a_i)$$

$$= -\frac{B}{e^{A(a_i)} + B} A'(a_i) + \frac{B^2}{(e^{A(a_i)} + B)^2} e^{A(a_i)} A''(a_i) + \lambda_g g''(a_i)$$

Therefore, $L_i$ is a strictly convex function of $a_i$.
Table A1: Verification accuracy (%) on CFP-FP and IJB-C with different ditributions of margins. Backbone network: ResNet50.

It’s easy to prove that $B > 0, e^{A(a_i)} + B > 0$, the first two part of $\frac{\partial^2 L_i}{\partial a_i^2}$ is non-negative while the third part is always positive. Therefore, $\frac{\partial^2 L_i}{\partial a_i^2} > 0$ and $L_i$ is a strictly convex function with respect to $a_i$. □

Property 2. A unique optimal solution $a_i^*$ exists in $[l_i, u_i]$.

Proof. Because the loss function $L_i$ is a strictly convex function, we have $\frac{\partial L_i}{\partial a_i} > \frac{\partial L_i}{\partial a_i^*}$ if $u_i ≥ a_i^* ≥ l_i$. Next we prove that there exist a optimal solution $a_i^* ∈ [l_i, u_i]$. If it exists, then it is unique because of the strictly convexity.

As $\frac{\partial L_i}{\partial a_i^*} = \frac{B}{e^{A(a) + B} \sin(\theta y_i + m(a))} m'(a_i) + \lambda g'(a_i)$ and considering the constraints $m'(a_i) ∈ (0, K)$, $g'(u_a) = 0$, $\lambda_y ≥ \frac{\sqrt{K}}{-g'(l_a)}$, the values of derivatives of $L_i, u_a$ are

$$\frac{\partial L_i}{\partial u_a}(u_a) = \frac{B}{e^{A(a) + B} \sin(\theta y_i + m(a))} m'(a_i) > 0$$

$$\frac{\partial L_i}{\partial l_a}(l_a) = \frac{B}{e^{A(a) + B} \sin(\theta y_i + m(a))} m'(a_i) + \lambda g'(l_a) < sK + \lambda g'(l_a) \leq 0$$

As $\frac{\partial L_i}{\partial a_i^*}$ is monotonically and strictly increasing, there must exist a unique value in $[l_i, u_i]$ which have a 0 derivative. Therefore, a optimal solution exists and is unique. □

A.3. Proof for Property of Monotonicity

To prove the property of monotonicity, we first show that optimal $a_i^*$ increases with a samller cosine-distance to its class center (Property 3). As $B$ can reveal the overall cos-distances to other class centers, we further prove that increasing $B$ can lead to a larger optimal feature magnitude (Property 4).

Property 3. With fixed $f_i$ and $W_j$, $j ∈ \{1, \cdots, n\}, j \neq y_i$, the optimal feature magnitude $a_i^*$ is monotonically decreasing if the cosine-distance to its class center $W_j y_i$ increases.

Proof. Assuming there are two class center $W_1^{y_i}, W_2^{y_i}$ and their cosine distance with feature $f_i$ are $\theta_1^{y_i}, \theta_2^{y_i}$. Assuming $\theta_1^{y_i} < \theta_2^{y_i}$ (i.e., class center $W_1^{y_i}$ has a smaller distance with feature $f_i$) and the corresponding optimal feature magnitudes are $a_{i,1}^*, a_{i,2}^*$.

The first derivate of $L_i$ is

$$\frac{\partial L_i}{\partial a_i} = \frac{B}{e^{A(a_i) + B}} A'(a_i) + \lambda y g'(a_i)$$

$$= \frac{B}{e^{A(a_i) + B}} \sin(\theta y_i + m(a_i)) + \lambda y g'(a_i)$$

(6)

For $\theta y_i + m(a_i) ∈ (0, \pi/2]$, we have $\cos(\theta y_i + m(a_i)) > \cos(\theta y_i + m(a_i))$ and $\sin(\theta y_i + m(a_i)) < \sin(\theta y_i + m(a_i))$. With $m'(a_i) > 0$, it’s obvious that

$$\frac{\partial L_i}{\partial a_i} = \frac{B}{e^{A(a_i) + B}} \sin(\theta y_i + m(a_i)) + \lambda y g'(a_i)$$

Therefore, we have $\frac{\partial L_i}{\partial a_i} > 0$. Based on the property of optimal solution for strictly convex function, we have $0 = \frac{\partial L_i}{\partial a_i} = \frac{\partial L_i}{\partial a_i} > 0$, which leads to $a_{i,1}^* > a_{i,2}^*$. □

B. Experimental Settings

B.1. Training settings for Figure 3

We adopt ResNet50 as the backbone network. Models are trained on MS1MV2 [2, 1] for 20 epochs with batch size 512 and initial learning rate 0.1, dropped by 0.1 every 5 epochs. 512 samples of the last iteration are used for visualization.
B.2. Settings of $m(a_i), g(a_i)$ and $\lambda_g$

In our experiments, we define function $m(a_i)$ as a linear function defined on $[l_a, u_a]$ with $m(l_a) = l_m, m(u_a) = u_m$ and $g(a_i) = \frac{1}{a_i} + \frac{1}{u_a} a_i$. Therefore, we have

$$m(a_i) = \frac{u_m - l_m}{u_a - l_a} (a_i - l_a) + l_m$$

$$\lambda_g \geq \frac{sk}{g'(l_a)} = \frac{u_m^2 l_a^2}{(u_a^2 - l_a^2)} l_m - l_a$$  \hspace{1cm} (7)

C. Ablation Study on Margin Distributions

In this section, effects of the feature distributions during training are studied. With $(\lambda_g, l_a, u_a)$ fixed to $(35, 10, 110)$, we carefully select various combinations of $l_m, u_m$ to align the mean margin on the training dataset to ArcFace (0.5) in our implementation. Features are distributed more separated if with a larger maximum margin and a smaller minimum margin.

Table A1 shows the recognition results with various hyperparameters. With $(l_m, u_m) = (0.45, 0.65)$, the penalty of magnitude loss degrades the performance of the recognition. With $(l_m, u_m) = (0.25, 1.60)$, the performance is also worse than the baseline as hard samples are assigned to small margins (a.k.a., hard/noisy samples are down-weighted). Parameter $(0.40, 0.80)$ balances the feature distribution and margins for hard/noisy samples, and therefore achieves a significant improvement on benchmarks.

D. Extended Visualization of Figure 6

We present a extended visualization of figure 6 in figure A1 which has more examples of faces with feature magnitudes. All the faces are sample from the IJB-C benchmark. It can be seen that faces with magnitudes around 28 are mostly profile faces while around 35 are high-quality and frontal faces. That is consistent with the profile/frontal peaks in the CFP-FP benchmark and indicates that faces with similar magnitudes show similar quality patterns across benchmarks. In real applications, we can set a proper threshold for the magnitude and should be able to filter similar low-quality faces, even under various scenarios.

Besides directly served as qualities, our feature magnitudes can also be used as quality labels for faces, which avoids human labelling costs. These labels are more suitable for recognition, and therefore can be used to boost other quality models.

E. Authors’ Contributions

Shichao Zhao and Zhida Huang contribute similarly to this work. Besides involved in discussions and help polish the work, shichao zhao mainly conducted experiments on clustering and zhida huang implemented baselines as well as evaluation metrics in quality experiments.
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