Mean-field approach to Random Apollonian Packing

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We revisit the scaling properties of growing spheres randomly seeded in $d = 2, 3$ and 4 dimensions using a mean-field approach. We model the insertion probability without assuming a priori a functional form for the radius distribution. The functional form of the insertion probability shows an unprecedented agreement with numerical simulations in $d = 2, 3$ and 4 dimensions. We infer from the insertion probability the scaling behavior of the Random Apollonian Packing and its fractal dimensions. The validity of our model is assessed with sets of 256 simulations each containing 20 million spheres in 2, 3 and 4 dimensions.

I. INTRODUCTION

Bubble nucleation is a phenomenon ubiquitous in physics, with applications ranging from the geometry of tree crowns [1], the structure of porous media [2] and the generalized problem of sphere packing [3] to the description of cosmic voids [4] and the signatures of cosmological phase transitions in terms of topological defects [5] and in gravitational waves [8, 9].

In this article, we study the universal properties of a simple, yet broad class of sphere packing models dubbed “Packing-Limited-Growth” (PLG). Such mechanisms entail objects being seeded randomly, growing and stopping upon collision with other objects. A simple model of PLG is the ABK model, named after Andrienko, Brilliantov and Krapivsky [10, 11]. In their setting, $d$-dimensional spheres are seeded randomly in space and time and grow linearly with time. They determine the fractal dimension for $d = 1$ and make a prediction for higher dimensions

$$\gamma \approx d + 1 - d \exp \left[ \frac{2(d - 2d+1 + 3)}{d + 2} \right] = \begin{cases} 2.554 & d = 2 \\ 3.945 & d = 3 \\ 4.999 & d = 4 \end{cases},$$

independently of the growth velocity. More generally, it is claimed that the fractal dimension is independent of the specifics of the growth dynamics [12] and the shape of the objects [13].

In this article, we examine a related mechanism referred to as “Random Apollonian Packing” (RAP) and illustrated in Fig. 1 [14, 15]. Here, $d$-dimensional spheres are seeded one at a time randomly in space in a finite-sized volume $V_{tot}$, and take the largest possible radius that avoids overlap. This mechanism is inspired by the well-known Apollonian packing [16, 17] and is a limit of the ABK model when the growth velocity is infinitely large.

The interest of the RAP mechanism is that it is thought to share universal properties with the more general ABK mechanism but can be approached from a completely different angle. Namely, the ABK mechanism is dynamical – multiple spheres are growing at the same time and collide with one another – whereas the RAP mechanism is sequential – spheres are added one at a time in a static environment. In this sense, our work intends to improve on Ref [12] in that we also model the insertion probability of spheres.

In Section II we present our mean-field approach to model the cumulative insertion probability $P_{ins,n}(r' > r)$. We show in Section III how to calculate the fractal dimension in this framework. Then, Sections IV and V present two approximations with increasing accuracy for the “surface model” and the computation of the fractal dimension. Finally, we assess the validity of our model with numerical simulations in $d = 2, 3$ and 4 in Section VI and make the connection with Ref [12].

FIG. 1: Visualization of a 2$d$ RAP containing $10^6$ spheres.
As illustrated in Fig. 2, the geometry of \( V_n(r) \) is very complex for \( d \geq 2 \), and the purpose of this article is to provide an approximation for this function.

As a mean-field approximation we estimate that the volume \( V_n(r) \), as a function of \( r \), grows by adding successive infinitesimal layers of thickness \( \delta r \) and “surface” \( S_n(r) \). Each of these new layers has an independent probability to be already included in the volume \( V_n(r) \), see Fig. 2. We make the assumption that a fraction \( V_n(r)/\Phi_n \) of these layers is already accounted for

\[
V_n(r + \delta r) = V_n(r) + S_n(r)\delta r \left[ 1 - \frac{V_n(r)}{\Phi_n} \right].
\]

In the limit \( \delta r \to 0 \), \( P_{\text{ins},n+1} \) is solution to an ordinary differential equation

\[
\frac{dP_{\text{ins},n+1}(r' > r)}{dr} = -\frac{S_n(r)}{\Phi_n}P_{\text{ins},n+1}(r' > r),
\]

which can be integrated

\[
P_{\text{ins},n+1}(r' > r) = \exp \left[ -\int_0^r \frac{S_n(r')}{\Phi_n} \, dr' \right].
\]

As expected, \( P_{\text{ins},n+1}(r' > 0) = 1 \) and the insertion probability naturally vanishes at large \( r \).

In this framework, we define the radius cumulative distribution after the \( n \)-th injection \( \mathcal{N}_n(r' > r) \) as the sum of the \( n \) first insertion cumulative distributions

\[
\mathcal{N}_n(r' > r) \equiv \sum_{k=1}^n P_{\text{ins},k}(r' > r).
\]

The expectation values for the powers of the radius \( \langle r^\alpha \rangle_n \), \( \alpha > 0 \), at the \( n \)-th injected sphere is obtained by integration over the insertion probability

\[
\langle r^\alpha \rangle_n \equiv -\int_0^\infty r^\alpha \frac{d}{dr} P_{\text{ins},n}(r' > r) \, dr
\]

\[
= \alpha \int_0^\infty r^{\alpha-1} P_{\text{ins},n}(r' > r) \, dr.
\]

The remaining pore space \( \Phi_n \) after the \( n \)-th injection depends, in principle, on the actual realization of this mechanism. However, in the following, we approximate it by its expectation value

\[
\Phi_n = \Phi_{\text{tot}} - V_d \sum_{k=1}^n \langle r^d \rangle_n,
\]

with \( \Phi_{\text{tot}} \) the total available volume and \( V_d \) the volume of a unit sphere in \( d \) dimensions.

### III. LARGE N LIMIT AND FRACTAL DIMENSION

Since the RAP presents a fractal behavior, we postulate that the moments \( M_n(n) \) describing the radius distribution can be approximated by power-laws at large
insertion number \( n \)

\[
M_0(n) \equiv \sum_{k=1}^{n} \langle r^\alpha \rangle_k \sim m_\alpha n^{\lambda_\alpha} \tag{10}
\]

with unknown coefficients \( m_\alpha, \lambda_\alpha \) and \( \alpha \) a real number in \([0,d]\). Furthermore, we also postulate that the pore space converges to 0 according to a power-law

\[
\Phi_n \sim m_d V_d n^{-\lambda_d}, \tag{11}
\]

with \( \lambda_d < 0 \). We discuss the validity of these two postulates in Section VI.

With this convention, the expectation value of \( r^\alpha \) for \( \alpha \in [0,d] \) is

\[
\langle r^\alpha \rangle_n \sim m_\alpha |\lambda_\alpha| n^{\lambda_\alpha - 1}. \tag{12}
\]

In particular, \( M_0(n) \) is the number of inserted spheres and \( (m_0, \lambda_0) = (1, 1) \).

Given a functional form for \( S_n(r) \), we argue that the fractal properties of the RAP are completely determined. We make different prescriptions for \( S_n(r) \) in Sections IV and V. To keep the discussion general, we only assume in this section that \( S_n(r) \) is a polynomial

\[
S_n(r) = \sum_{\alpha \in S} s_\alpha(n) r^\alpha, \tag{13}
\]

with \( S \) a discrete set of numbers, not necessarily integers, in the range \([0,d-1]\).

By construction, the insertion probability is normalized

\[
- \int_0^\infty \frac{d}{dr} P_{\text{ins},n+1}(r') \, dr' = 1, \tag{14}
\]

which, upon using Eqs. (5), (8b) and (13), establishes

\[
\forall n, \quad \Phi_n = \sum_{\alpha \in S} s_\alpha(n) (\alpha + 1) \langle r^{\alpha + 1} \rangle_{n+1}. \tag{15}
\]

In the large \( n \) limit, a change of variable in Eq. (8b) absorbs the dependence on \( n \)

\[
m_\alpha |\lambda_\alpha| = \alpha \int_0^\infty P_{\text{ins},n} \left[ r' > n^{(\lambda_\alpha - 1)/\alpha} x \right] x^{\alpha - 1} \, dx. \tag{16}
\]

Since this equation is valid for any \( n \) sufficiently large, we postulate that the dependence on \( n \) vanishes exactly in the argument of \( P_{\text{ins},n} \). Therefore

\[
f(x, \alpha) \equiv n \rightarrow \infty P_{\text{ins},n} \left[ r' > n^{(\lambda_\alpha - 1)/\alpha} x \right] \tag{17}
\]

with \( f \) function of only one argument. Similarly, the cumulative radius distribution of Eq. (7) can be expressed in terms of \( f \).

\[
\mathcal{N}_n(r') \sim \sum_{k=1}^{n} f \left[ rk^{(1-\lambda_\alpha)/\alpha}, \alpha \right]. \tag{18}
\]

The fractal dimension \( \gamma \) of the RAP, defined using the slope of the radius cumulative distribution at large \( n \), is therefore related to the different \( \lambda_\alpha \)'s according to

\[
\gamma - 1 \equiv \lim_{n \rightarrow \infty} \frac{d \ln \mathcal{N}_n(r') > r}{d \ln r} = \frac{\alpha}{1 - \lambda_\alpha}. \tag{19}
\]

Consequently, the power-law exponents can all be expressed in terms of a single exponent, that we arbitrarily chose to be \( \lambda_1 \)

\[
\lambda_\alpha = \alpha \lambda_1 - (\alpha - 1). \tag{20}
\]

Note that this is consistent with the rather crude approximation that \( \langle r^{\alpha} \rangle_n \sim (r')_n \).

IV. SURFACE MODEL I: UNIFORM DISTRIBUTION

It should be clear from the previous section that the fractal dimension and the power-law exponents are determined by the yet unspecified function \( S_n(r) \). Our first attempt to model this function is \( S_n^{(1)}(r) \), where we make the assumption that all the \( n \) first spheres are uniformly distributed across the available volume \( V_d \). In which case, \( S_n^{(1)}(r) \) sums the surfaces of spheres with radius \( (r+r') \) centered around the \( n \) preceding spheres having radius \( r' \) with probability \( -d \mathcal{N}_n(r') \, dr \)

\[
S_n^{(1)}(r) = -d V_d \int_0^\infty (r + r')^{d-1} \mathcal{N}_n \, dr’. \tag{21}
\]

In this first model, the set \( S \) contains all the integers between 0 and \( d-1 \), and

\[
s_k(n) = d V_d C_k^{d-1} M_{d-k-1}(n), \tag{22}
\]

with \( C_k^n \) the binomial coefficients. Given a functional form for \( S_n(r) \), Eqs. (15) and (16) form a closed set of equations in the large \( n \) limit. As an example, we explicitly show the computation for \( d = 2 \) in this section, and we direct the interested reader to Appendix A for \( d = 3,4 \).

In two dimensions, the “surface” \( S_n(r) \) is the sum of perimeters at a distance \( r \) from the circles of radius \( r' \)

\[
S_n^{(1)}(r) = -2 \pi \int_0^\infty (r + r') \mathcal{N}_n \, dr’. \tag{23}
\]

Therefore \( S = \{0,1\} \) and the coefficients \( s_\alpha(n) \) in the large \( n \) limit are

\[
s_0(n) = 2M_1(n) \pi \approx 2m_1 \pi n^{\lambda_1} \tag{24a}
\]

\[
s_1(n) = 2M_0(n) \pi \approx 2 \pi n. \tag{24b}
\]

Eq. (15), the asymptotic limit yields

\[
m_2 \pi n^{2 \lambda_2} = 2 \pi m_1 n^{\lambda_1} (r)_n + \pi n (r^2)_n \tag{25a}
\]

\[
\Rightarrow m_2 \pi n^{2 \lambda_2} = 2m_1^2 \lambda_1 n^{2 \lambda_1 - 1} - m_2 \lambda_2 n^{\lambda_2}. \tag{25b}
\]
TABLE I: On the left columns, the power-law exponents predicted by the mean-field theory. On the right columns, the power-law exponents directly measured over an ensemble average of $2 \times 10^3$ spheres each. Uncertainties on the determination of the $\lambda_s$ from simulations are in Fig. 7. As explained in Section VI, we do not provide a direct estimate of the fractal dimension from the simulation.

| Exponent | Uniform distribution | Identical twins | Simulations |
|----------|----------------------|-----------------|-------------|
|         | $d = 2$ | $d = 3$ | $d = 4$ | $d = 2$ | $d = 3$ | $d = 4$ |
| $\lambda_1$ | 0.3789 | 0.6313 | 0.7369 | 0.3614 | 0.6285 | 0.7362 | 0.361 | 0.634 | 0.738 |
| $\lambda_2$ | -0.2421 | 0.2625 | 0.4737 | -0.2771 | 0.2571 | 0.4724 | -0.2778 | 0.265 | 0.476 |
| $\lambda_3$ | - | -1.062 | 0.2106 | - | -0.1144 | 0.2086 | - | -0.097 | 0.207 |
| $\lambda_4$ | - | - | -0.0526 | - | - | -0.0552 | - | - | -0.044 |
| $\gamma$ | 2.6101 | 3.7119 | 4.8002 | 2.5660 | 3.6921 | 4.7909 | - | - | - |

V. SURFACE MODEL II: IDENTICAL TWINS

In a refined attempt to model the “surface” function $S_n^{(2)}(r)$, we approximate the a priori complex network of sphere collisions by the first order correction due to having one collision with a sphere of identical radius. In other words, we consider isolated pairs of “identical twins” to account for the close-range effect of having at least one neighbor for each sphere. We illustrate it in Fig. 3.

Let us have two spheres of radius $r'$ in $d$ dimensions tangent to one another, the “surface” located at a distance $r$ from the two spheres is truncated by $2\Omega(\phi)$, the area of the unit hyperspherical cap of half-angle at the summit $\phi = \arccos[r'/(r + r')]$

$$\Omega(\phi) = \frac{dV_d}{2} I_{\text{sin}^2 \phi} \left( \frac{d-1}{2} \frac{1}{2} \right).$$  \hspace{1cm} (28)$$

$I$ is the regularized incomplete beta function. The presence of this “identical twin” for small $r$ modifies the shape of the surface function $S_n(r)$

$$S_n^{(2)}(r) \equiv S_n^{(1)} - \left( \frac{2\pi r}{\Gamma(\frac{d+1}{2})} \right) M_{d-1} \left( n \right).$$  \hspace{1cm} (29)$$

For even dimensions, the surface function now includes half-integer powers of $r$.

As in the previous section, we compute the power-law exponents in two dimensions and give the higher dimensional derivation in Appendix B. The values predicted for the power-law exponents are collected in Table I. For $d = 2$, the surface function is a sum of three terms with $S = \{0, 1/2, 1\}$

$$s_0(n) = 2M_1(n)\pi = 2m_1\pi n^{\lambda_1},$$  \hspace{1cm} (30a)$$
$$s_{1/2}(n) = -2\sqrt{2}M_{1/2}(n) = -2\sqrt{2}m_{1/2}n^{\lambda_{1/2}},$$  \hspace{1cm} (30b)$$
$$s_1(n) = 2M_0(n)\pi = 2\pi n.$$  \hspace{1cm} (30c)$$

Eq. (16) for $\alpha \in \{1/2, 1, 2\}$ forms a closed-system of three equations.
\[
\frac{m_{1/2}^{1/2}}{m_1^{1/2}} \lambda_{1/2} = \frac{1}{2} \int_0^\infty \frac{1}{\sqrt{x}} \exp \left[ -\frac{m_2^2}{m_1^2} \left( x^2 + 2x - \frac{4\sqrt{2} m_{1/2}^3}{3\pi m_1^{3/2}} \right) \right] dx ,
\]
(31a)

\[
\lambda_1 = \int_0^\infty \exp \left[ -\frac{m_2^2}{m_1^2} \left( x^2 + 2x - \frac{4\sqrt{2} m_{1/2}^3}{3\pi m_1^{3/2}} \right) \right] dx ,
\]
(31b)

\[
-\frac{m_2^2}{m_1^2} \lambda_2 = 2 \int_0^\infty x \exp \left[ -\frac{m_2^2}{m_1^2} \left( x^2 + 2x - \frac{4\sqrt{2} m_{1/2}^3}{3\pi m_1^{3/2}} \right) \right] dx .
\]
(31c)

FIG. 4: Illustration of the space partitioning method used in the numerical simulation. Each node of the tree consists of a set of spheres and a bounding box. After the insertion of \( O(100) \) spheres, the node is divided into two children nodes and the set of spheres is split into the two children nodes. Each of the children’s bounding boxes (in red and blue) is designed to enclose at least half of the spheres of the parent node. Overlap usually occurs between the bounding boxes of the two children. A few spheres may not fit in either of the children nodes, in which case they remain associated with the parent node.

with three unknowns \( \lambda_1, m_{1/2}/m_1^{1/2}, m_2/m_1^2 \). This system can be solved with a root finding algorithm, and we find

\[
\lambda_1 \approx 0.3614, \quad \frac{m_{1/2}}{m_1^{1/2}} \approx 0.7981, \quad \frac{m_2}{m_1^2} \approx 0.8188.
\]

VI. NUMERICAL SIMULATIONS

A step in the simulation starts by selecting a random nucleation site inside a \( d \)-dimensional square box. The sphere takes the largest radius possible to avoid overlap with other spheres or with the boundaries of the box. The closest sphere is determined using a space-partitioning method, illustrated in Fig. 4, which reduces the complexity from \( O(n) \) to \( O(\ln n) \). If the nucleation site lies inside a preexisting sphere, it is discarded and a new nucleation site is drawn. As the number of spheres increases, the rejection rate increases thus making the insertion of spheres increasingly challenging, especially in low dimensions.

First, we perform a series of numerical simulation to validate our model for the insertion probability of Eq. (6). To this end, we attempt \( 10^6 \) test insertions in fixed RAPs of \( 10^4, 10^5, 10^6 \) and \( 10^7 \) spheres. We compare in Fig. 5 this numerical result with our two models: the Uniform Distribution (UD) and the Identical Twins (IT) models. Since the realization of the RAP is known and fixed, we use for the \( M_n(n) \)s the actual radii in the simulation instead of their expectation values. Overall, we find a good agreement in \( d = 2 \) and 3 and observe a small discrepancy for \( d = 4 \) that vanishes as \( n \) gets larger. We interpret this deviation at \( d = 4 \) as a boundary effect that we do not account for in the model. Even after 10 million insertions, more than half of the simulation box is still empty and the surface of the bounding box is equivalent to the surface of the packed spheres.
In this article, we presented a “mean-field inspired” model to understand the properties of Random Apollonian Packings, a prototypical example of sphere packing. This model gives a prediction for the insertion
FIG. 7: Estimation of the exponents $|\lambda_i|$ from an ensemble average of 256 simulations of $2 \times 10^7$ spheres. The dashed black curves are the fit to the data accounting for its approach to its asymptotic value as in Eq. (33). The dashed gray curves are the asymptotic values found.
probability with unprecedented support by simulations in $d = 2$, 3 and, to a smaller extent, in $d = 4$. The agreement between the model and the simulation weakens the higher the dimension and the lower the number of inserted spheres. This is to be expected since, in this regime the available space $V_{\text{tot}}$ is rather empty and boundary effects remain important, hence our mean-field approximation breaks down.

Then, we presented a systematic method to determine the asymptotic behavior of the moments $M_{\alpha}(n)$ directly from the insertion probability without assuming a priori a functional form for the radius distribution $N_{\alpha}(r)$. We find very good agreement in two dimensions, however for $d = 3$ and 4, our simulations have clearly not yet reach the fractal regime to make an accurate comparison. Nonetheless, our estimations for the power-law exponents $\lambda_i$s are broadly consistent with values inferred from the simulations.

We stress that the simulations in 4 dimensions are still far from the expected power-law behavior, as can be assessed in Figs. 7 and 8. Indeed, we observe that less than half the available volume is occupied by spheres and that the surface of the bounding box is of the same order as the surface of the spheres even after 20 million insertions.

It is unclear whether our best fits for the power-law exponents reflect the fractal regime or a transient regime suffering from a boundary effect.

In summary, the method presented in this article gives us an analytical handle on both the global scaling properties of this "Packing-Limited Growth" problem and the step-by-step properties in the form of the insertion probability.

In the future, we plan to apply this mean-field approach to broader classes of "Packing-Limited Growth" problems, such as extensions with nonspherical particles. We also plan to investigate boundary effects in higher dimensions, by allowing different boundary topologies and by running simulations with an even larger number of spheres.

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Appendix A: Uniform distribution models in higher dimensions

1. Dimension $d = 3$

In three dimensions, the surface function of the uniform density model is given by

$$S^{(1)}_{\text{u}}(r) = -4\pi \int_0^\infty (r + r')^2 \frac{dN_n}{d\sigma} \frac{d\sigma}{dr'} dr'$$  \hspace{1cm} (A1)
Therefore $S = \{0, 1, 2\}$ and

\[
\begin{align*}
  s_0(n) &= 4\pi M_2(n) = 4m_2\pi n^{\lambda_2} \quad \text{(A2a)} \\
  s_1(n) &= 8\pi M_1(n) = 8m_1\pi n^{\lambda_1} \quad \text{(A2b)} \\
  s_2(n) &= 4\pi M_0(n) = 4\pi n \quad \text{(A2c)}
\end{align*}
\]

At large $n$, Eq. (15) fixes the value $m_3 = 3m_1m_2$ and we have the following set of closed equations for $\alpha \in \{1, 2\}$

\[
\begin{align*}
  m_1\lambda_1 &= \int_0^{\infty} \exp\left(-\frac{3m_2x + 3m_1x^2 + x^3}{3m_1m_2}\right) dx \\
  m_2\lambda_2 &= 2\int_0^{\infty} x \exp\left(-\frac{3m_2x + 3m_1x^2 + x^3}{3m_1m_2}\right) dx.
\end{align*}
\]

A root-finding algorithm finds

\[
\lambda_1 \approx 0.6313, \quad \frac{m_2}{m_1} \approx 2.336.
\]

2. Dimension $d = 4$

In four dimensions, the surface function is given by

\[
S_n(r) = -4V_4 \int_0^{\infty} (r + r')^3 \frac{dN_n}{dr} dr' \quad \text{(A4)}
\]
where $V_4$ is the volume of the four-dimensional unit sphere. $\mathbb{S} = \{0, 1, 2, 3\}$ with at large $n$

\begin{align}
  s_0(n) &= 4V_4M_3(n) = 4V_4m_3n^{\lambda_3} \\
  s_1(n) &= 12V_4M_2(n) = 12V_4m_2n^{\lambda_2} \\
  s_2(n) &= 12V_4M_1(n) = 12V_4m_1n^{\lambda_1} \\
  s_3(n) &= 4V_4M_0(n) = 4V_4n. 
\end{align}

One obtains a closed set of equations for $\alpha \in \{1, 2, 3\}$

\begin{align*}
  m_1\lambda_1 &= \int_0^\infty \exp \left( -\frac{4m_3x + 6m_2x^2 + 4m_1x^3 + x^4}{4m_1m_3 + 3m_2^2} \right) dx \\
  m_2\lambda_2 &= 2 \int_0^\infty x \exp \left( -\frac{4m_3x + 6m_2x^2 + 4m_1x^3 + x^4}{4m_1m_3 + 3m_2^2} \right) dx \\
  m_3\lambda_3 &= 3 \int_0^\infty x^2 \exp \left( -\frac{4m_3x + 6m_2x^2 + 4m_1x^3 + x^4}{4m_1m_3 + 3m_2^2} \right) dx.
\end{align*}

A root-finding algorithm finds

\[
\lambda_1 \approx 0.7369, \quad \frac{m_2}{m_1^2} \approx 1.6428, \quad \frac{m_3}{m_1^2} \approx 4.6867.
\]

**Appendix B: Identical twins model in higher dimensions**

1. **Dimension $d = 3$**

Since it is an odd dimension, the surface function only contains integer powers of $r$. The decomposition of $S_\alpha(r)$ is only modified for $\alpha = 1$ so that

\begin{align}
  s_0(n) &= 4\pi M_2(n) = 4m_2\pi n^{\lambda_2} \\
  s_1(n) &= 6\pi M_1(n) = 6m_1\pi n^{\lambda_1} \\
  s_2(n) &= 4\pi M_0(n) = 4\pi n.
\end{align}

The power-law parameters satisfy the following closed-set of equations for $\alpha \in \{1, 2, 3\}$

\begin{align*}
  m_1\lambda_1 &= \int_0^\infty \exp \left( -\frac{3m_2x + 9m_1x^2/4 + x^3}{m_3} \right) dx \\
  m_2\lambda_2 &= 2 \int_0^\infty x \exp \left( -\frac{3m_2x + 9m_1x^2/4 + x^3}{m_3} \right) dx \\
  -m_3\lambda_3 &= 3 \int_0^\infty x^2 \exp \left( -\frac{3m_2x + 9m_1x^2/4 + x^3}{m_3} \right) dx.
\end{align*}

A root-finding algorithm finds

\[
\lambda_1 \approx 0.6285, \quad \frac{m_2}{m_1^2} \approx 2.4071, \quad \frac{m_3}{m_1^2} \approx 6.6972.
\]

This is consistent with the constraint coming from Eq. \([15]\)

\[
m_3 = \frac{3m_1m_2(10\lambda_1 - 3)}{4(3\lambda_1 - 1)}.
\]
2. Dimension $d = 4$

In four dimensions, the identical twins model adds a half-integer power of $r$ to the decomposition of $S_n(r)$

\[
\begin{align*}
  s_0(n) &= 4V_4M_3(n) = 4V_4m_3n^{\lambda_3} \\
  s_1(n) &= 12V_4M_2(n) = 12V_4m_2n^{\lambda_2} \\
  s_{3/2}(n) &= -\frac{16\sqrt{2}}{3\pi}V_4M_{3/2}(n) = -\frac{16\sqrt{2}}{3\pi}V_4m_{3/2}n^{\lambda_{3/2}} \\
  s_2(n) &= 12V_4M_1(n) = 12V_4m_1n^{\lambda_1} \\
  s_3(n) &= 4V_4M_0(n) = 4V_4n.
\end{align*}
\]  

(B4a) 

(B4b) 

(B4c) 

(B4d) 

(B4e)

The power-law parameters satisfy the following closed-set of equations for $\alpha \in \{1, 3/2, 2, 3\}$

\[
\begin{align*}
  m_1\lambda_1 &= \int_0^{\infty} \exp \left( -\frac{x^4 + 4m_1x^3 - \frac{32\sqrt{2}}{15\pi}m_{3/2}x^{5/2} + 6m_2x^2 + 4m_3x}{m_4} \right) dx \\
  m_{3/2}\lambda_{3/2} &= \frac{3}{2} \int_0^{\infty} \sqrt{x} \exp \left( -\frac{x^4 + 4m_1x^3 - \frac{32\sqrt{2}}{15\pi}m_{3/2}x^{5/2} + 6m_2x^2 + 4m_3x}{m_4} \right) dx \\
  m_2\lambda_2 &= 2 \int_0^{\infty} x \exp \left( -\frac{x^4 + 4m_1x^3 - \frac{32\sqrt{2}}{15\pi}m_{3/2}x^{5/2} + 6m_2x^2 + 4m_3x}{m_4} \right) dx \\
  m_3\lambda_3 &= 3 \int_0^{\infty} x^2 \exp \left( -\frac{x^4 + 4m_1x^3 - \frac{32\sqrt{2}}{15\pi}m_{3/2}x^{5/2} + 6m_2x^2 + 4m_3x}{m_4} \right) dx \\
  -m_4\lambda_4 &= 4 \int_0^{\infty} x^3 \exp \left( -\frac{x^4 + 4m_1x^3 - \frac{32\sqrt{2}}{15\pi}m_{3/2}x^{5/2} + 6m_2x^2 + 4m_3x}{m_4} \right) dx.
\end{align*}
\]

A root-finding algorithm finds

\[
\begin{align*}
  \lambda_1 &\approx 0.7362, \quad \frac{m_{3/2}}{m_1^{3/2}} \approx 1.2208, \quad \frac{m_2}{m_1^2} \approx 1.6611, \quad \frac{m_3}{m_1^3} \approx 4.8320, \quad \frac{m_4}{m_1^4} \approx 26.522.
\end{align*}
\]