On regularity of maximal distance minimizers in $\mathbb{R}^n$

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Abstract

We study the properties of sets $\Sigma$ which are the solutions of the maximal distance minimizer problem, i.e. of sets having the minimal length (one-dimensional Hausdorff measure) over the class of closed connected sets $\Sigma \subset \mathbb{R}^n$ satisfying the inequality

$$\max_{y \in M} \text{dist} (y, \Sigma) \leq r$$

for a given compact set $M \subset \mathbb{R}^n$ and some given $r > 0$. Such sets can be considered as the shortest networks of radiating Wi-Fi cables arriving to each customer (for the set $M$ of customers) at a distance at most $r$.

In this paper we prove that any maximal distance minimizer $\Sigma \subset \mathbb{R}^n$ has at most 3 tangent rays at each point and the angle between any two tangent rays at the same point is at least $2\pi/3$. Moreover, at the plane (for $n = 2$) we show that the number of points with three tangent rays is finite and maximal distance minimizer is a finite union of simple curves with continuous one-sided tangents.

All the results are proved for the more general class of local minimizers, i.e. sets which are optimal under a perturbation of a neighbourhood of their arbitrary point.

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1 Introduction

For a given compact set $M \subset \mathbb{R}^n$ consider the functional

$$F_M (\Sigma) := \sup_{y \in M} \text{dist} (y, \Sigma),$$

where $\Sigma$ is a closed subset of $\mathbb{R}^n$ and $\text{dist} (y, \Sigma)$ stands for the Euclidean distance between $y$ and $\Sigma$ (naturally, $F_M (\emptyset) := +\infty$). The quantity $F_M (\Sigma)$ will be called the energy of $\Sigma$. Consider the class of closed connected sets $\Sigma \subset \mathbb{R}^n$ satisfying $F_M (\Sigma) \leq r$ for some $r > 0$. We are interested in the properties of sets of the minimal length (one-dimensional Hausdorff measure) $\mathcal{H}^1 (\Sigma)$ over the mentioned class. Such sets will be further called minimizers.

Let $B_\rho (x)$ be the open ball of radius $\rho$ centered at a point $x$, and let $B_\rho (M)$ be the open $\rho$-neighborhood of $M$ i.e.

$$B_\rho (M) := \bigcup_{x \in M} B_\rho (x).$$

It is easy to see that the set $\Sigma$ is bounded (and, thus, compact), since $\Sigma \subset \overline{B_\rho (\text{conv} M)}$, where $\text{conv} M$ stands for the convex hull of the set $M$. In [7] (for the plane) and in [8] (for $\mathbb{R}^n$) the following properties of minimizers have been proven:

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(a) It is known that for all $r > 0$ the set of minimizers is non-empty.

(b) A minimizer cannot contain loops (homeomorphic images of circles).

Also, since $\Sigma$ is a connected closed set of a finite length, the following statements hold.

(c) $\Sigma$ has a tangent line at almost every point of $\Sigma$.

(d) The set $\Sigma$ is Ahlfors regular, i.e. there exist such constants $c > 0$ and $C > 0$ that for every point $x \in \Sigma$ and a sufficiently small $\rho > 0$ the inequality

$$ c \rho \leq \mathcal{H}^1(\Sigma \cap B_\rho(x)) \leq C \rho $$

holds.

In this work we show that

$$ \mathcal{H}^1(\Sigma \cap B_\rho(x)) = \text{ord}_x \Sigma \cdot \rho + o(\rho), $$

where $\text{ord}_x \Sigma \in \{1, 2, 3\}$ is defined as follows.

**Definition 1.1.** We will say that the order of a point $x$ in the set $\Gamma \subset \mathbb{R}^n$ is $m$ (and write $\text{ord}_x \Gamma = m$) if there exists such $\rho = \rho(x) > 0$ that for any open set $U \ni x$ with $\text{diam} U < \rho$ the inequality $|\Gamma \cap \partial U| \geq m$ holds (where $|A|$ is the number of elements in the set $A$), and for any positive $\varepsilon < \rho$ there exists an open set $V \ni x$ with $\text{diam} V < \varepsilon$ and $\varepsilon(\Gamma \cap \partial V) = m$.

The main result of this article is the following theorem (see Definition 2.12 for the notion of one-sided tangents).

**Theorem 1.2.** Let $\Sigma$ be a minimizer for a compact set $M \subset \mathbb{R}^n$ and $r > 0$. Then there are at most three tangent rays at any point of $\Sigma$, and the pairwise angles between the tangent rays are at least $2\pi/3$. Moreover, if $n = 2$, then $\Sigma$ is a finite union of simple curves with continuous one-sided tangents.

It is known (see [4]) that, as any minimizer $\Sigma$ for a compact set $M \subset \mathbb{R}^n$ and $r > 0$ has a finite length, the following lemma holds:

**Lemma 1.3.** Let $\Sigma$ be a minimizer for a compact set $M \subset \mathbb{R}^n$ and $r > 0$, and let $x \in \Sigma$ be a point of order $n$: $\text{ord}_x \Sigma = n$. Then there exists $\rho = \rho(x) > 0$ such that for any positive $\varepsilon < \rho$ the set $\Sigma \cap B_\varepsilon(x)$ contains $n$ arcs with one end at $\partial B_\varepsilon(x)$ and another end at $x$, such that any pair of these arcs intersects only at point $x$.

Note that Theorem 1.2 implies that in the planar case the set $\Sigma \cap B_\varepsilon(x)$ coincides with these arcs.

**Definition 1.4.** Let $M \subset \mathbb{R}^n$ be a compact set and let $r > 0$. A connected set $\Sigma \subset \mathbb{R}^n$ is called a local minimizer if $F_M(\Sigma) \leq r$ and there exists $\varepsilon > 0$ such that for any connected set $\Sigma'$ satisfying $F_M(\Sigma') \leq r$ and $\text{diam}(\Sigma \triangle \Sigma') \leq \varepsilon$ the inequality $\mathcal{H}^1(\Sigma) \leq \mathcal{H}^1(\Sigma')$ holds, where $\triangle$ is the symmetric difference.

Any minimizer is also a local minimizer, so Theorem 1.2 is a direct corollary of the following theorem.

**Theorem 1.5.** Let $\Sigma \subset \mathbb{R}^n$ be a local minimizer for a compact set $M \subset \mathbb{R}^n$ and $r > 0$. Then $\Sigma$ has the same properties as in Theorem 1.2.

**Proof.** See Corollary 3.8, Theorem 4.3 and Lemma 4.4.

We should also mention the problem of minimizing the average distance functional (for more details about this problem, see the survey [6] and [5]). Maximum and average distance minimizers have a number of similar geometric and topological properties (see [3]). For example, it was proved (see [1]) that any minimizer of the average distance in $\mathbb{R}^2$ is a finite plane graph. Theorem 1.2 implies that any maximal distance minimizer in $\mathbb{R}^2$ is also a finite plane graph. Note that this is not true for the Steiner problem (which is defined in
Subsection 1.1: an example of a Steiner tree which cannot be represented as a finite plane graph can be found in [9].

The article is organized as follows. Subsection 1.1 contains the statement of the Steiner problem and some technical statements about Steiner trees (an advanced reader can skip this subsection). Section 2 introduces notation, basic definitions and some elementary statements. Section 3 contains the proof of the part of Theorem 1.3 about tangent rays. Subsection 3.1 contains several technical results which are used in the next section. Finally, Section 4 deals with the planar part of Theorem 1.5.

This work is a revised version of the work [10]. Although the finiteness of the number of branching points (i.e. points with three tangent rays) in space remains an open problem, the proof in the planar case follows from statements, most of which are shown to also be true in space (see Subsection 3.1). This provides a starting point for either proving or refuting the spatial claim.

1.1 Steiner problem

Let \( C \subset \mathbb{R}^n \) be a compact set (in particular, often \( C = \{A_1, \ldots, A_m\} \) is supposed to be the finite set of points). Then the shortest (having a minimal one-dimensional Hausdorff measure) closed set \( S \) such that \( S \cup C \) is a connected set (if \( C \) is a finite set of points then one can write \( C \subset S \)) is called a Steiner tree. It is known that a Steiner tree \( S \) exists (but may be not unique), coincides with a (finite if \( C \) is finite) union of straight segments and does not have cycles.

Let \( C = \{A_1, \ldots, A_m\} \) be a finite set. Its Steiner tree \( S \) is a finite connected acyclic graph, i.e. an embedded tree. When speaking of this tree, without loss of generality, we always consider the graph with the minimal possible vertex set. It is known that vertices of this graph cannot have degree greater than 3, and that only the vertices \( A_i \) can have degree 1 and 2. Therefore, all other vertices have degree 3 and are called Steiner points or branching points. It follows that the number of Steiner points does not exceed \( m - 2 \).

The pairwise angles between edges incident to an arbitrary vertex are at least \( 2\pi/3 \). Thus, a Steiner point has exactly three edges with pairwise angles \( 2\pi/3 \). If all vertices \( A_i \) have degree 1, then the number of Steiner points is equal to \( m - 2 \) (the converse is also true), and \( S \) is called a full Steiner tree. A set, each connected component of which is a (full) Steiner tree, is called a (full) Steiner forest.

For a given three-point set \( C = \{A_1, A_2, A_3\} \) a Steiner tree is unique, and,

- if the maximal angle of the triangle \( \triangle A_1A_2A_3 \) is at least \( 2\pi/3 \), i.e. \( \angle A_kA_iA_m \geq 2\pi/3 \) for some \( \{k, l, m\} = \{1, 2, 3\} \), then the Steiner tree is the union of two segments \([A_kA_l] \cup [A_lA_m]\);

- otherwise, the Steiner tree is the union of three segments \([A_1F] \cup [A_2F] \cup [A_3F]\), where \( F \) is the Fermat–Toricelli point, i.e. the point satisfying

\[
\angle A_1FA_2 = \angle A_2FA_3 = \angle A_3FA_1 = 2\pi/3.
\]

Note that such \( F \) belongs to the plane \((A_1A_2A_3)\).

The proof of the listed properties of Steiner trees and other interesting information about them one can find in the book [3] and in [2].

Remark 1.6. Let \( S \) be a Steiner forest for a finite set \( C = \{A_1, \ldots, A_m\} \). For each vertex \( A_i \) and for each of its incident edges \( XA_i \) of \( S \) consider a unit vector codirectional with the vector \( \overrightarrow{XA_i} \). Then the sum of all these unit vectors is zero.

To check Remark 1.6 one can consider a full Steiner tree (as Steiner forest is a union of full Steiner trees) and prove the statement by induction on the number of Steiner points.

Recall the following widely known facts.

Proposition 1.7. For any point \( X \in \mathbb{R}^n \) there exist no more than three segments incident to \( X \) with pairwise angles at least \( 2\pi/3 \). In the case of three segments, they are coplanar, and pairwise angles between them are equal to \( 2\pi/3 \).
Proposition 1.8. Let $A, B, C \in \mathbb{R}^n$ be three different points such that all angles of the triangle $\triangle ABC$ are strictly less than $2\pi/3$, and the lengths of the sides $AB$ and $BC$ are equal to $\varepsilon$. Then

$$2\varepsilon - \mathcal{H}^1(\text{St}(A, B, C)) = d\varepsilon,$$

where $\text{St}(A, B, C)$ is a Steiner tree for the set $\{A, B, C\}$ and $d > 0$ is a constant depending only on the angles of the triangle $\triangle ABC$.

2 Notation and definitions

- For a given set $X \subset \mathbb{R}^n$ the sets $\overline{X}$, $\text{Int}(X)$ and $\partial X$ represent its closure, interior and boundary, respectively, and $\text{conv} X$ denotes its convex hull.

- Let $B, C \in \mathbb{R}^n$ be points. Then $[BC]$ denotes the segment with endpoints at $B$ and $C$, $\overrightarrow{BC}$ denotes the vector starting at $B$ and ending at $C$, both $[BC)$ and $(CB)$ denote the ray which starts at $B$ and contains $C$, and $(BC)$ denotes the line which contains $B$ and $C$.

- The symbol $\angle$ is applicable to two lines, two rays, two vectors or three points. It denotes the unique angle between the objects (in case of three points, $\angle ABC = \angle(\overrightarrow{BA}, \overrightarrow{BC})$) belonging to $[0, \pi]$ for rays, vectors and points, and to $[0, \pi/2]$ for lines.

- Given a sequence of rays $(a_k b_k)$, we say that $(a_k b_k) \to (ab)$ if $b_k \to b$ and $\angle((a_k b_k), (ab)) \to 0$.

- We will say that two vectors, rays or lines are $\gamma$-orthogonal to each other if the angle between them differs from $\pi/2$ by at most $\gamma$. Similarly, we will say that two vectors, rays or lines are $\gamma$-parallel to each other if the angle between them differs from $0$ by at most $\gamma$. We will sometimes abuse the notation and say that a ray $[AB]$ or a vector $\overrightarrow{AB}$ is $\gamma$-orthogonal ($\gamma$-parallel) to a line $(CD)$ if the line $(AB)$ is $\gamma$-orthogonal ($\gamma$-parallel) to $(CD)$.

- Given two vectors $\overrightarrow{a}$, $\overrightarrow{b} \in \mathbb{R}^n$, the dot product between them is denoted by $\langle \overrightarrow{a}, \overrightarrow{b} \rangle := \sum_{i=1}^{n} a_i b_i$.

- The supremum of the distance between a pair of points from a set $X \subset \mathbb{R}^n$ will be referred to as the diameter of $X$:

$$\text{diam } X := \sup_{a, b \in X} \text{dist}(a, b).$$

- For a (usually finite) set $X \subset \mathbb{R}^n$, its cardinality, i.e. the number of elements in the set, is denoted by $\sharp X$.

- We will write $f(\varepsilon) = o_\varepsilon(g(\varepsilon))$ if and only if $\frac{f(\varepsilon)}{g(\varepsilon)} \to 0$ as $\varepsilon \to 0$. In particular, $f(\varepsilon) = o_\varepsilon(1)$ if and only if $f(\varepsilon) \to 0$ as $\varepsilon \to 0$. If the dependence on $\varepsilon$ is clear from the context, we will often write $o(\cdot)$ instead of $o_\varepsilon(\cdot)$.

Remark 2.1. If $\Gamma \subset \mathbb{R}^n$ is a connected set of a positive length, then $\text{ord}_\varepsilon \Gamma > 0$ if and only if $x \in \overline{\Gamma}$.

Definition 2.2. We will say that the circular order of a point $x$ in the set $\Gamma \subset \mathbb{R}^n$ is $m$ (and write $\text{ordball}_\varepsilon \Gamma = m$) if there exists $\rho = \rho(x) > 0$ such that for any positive $\varepsilon < \rho$ the inequality $\sharp(\Gamma \cap \partial B(\varepsilon)) \geq m$ holds, and for any positive $\varepsilon < \rho$ there exists a positive $\delta < \varepsilon$ such that $\sharp(\Gamma \cap \partial B(\delta)) = m$.

Remark 2.3. For any set $\Gamma \subset \mathbb{R}^n$ and any $x \in \Gamma$ the inequality $\text{ordball}_\varepsilon \Gamma \geq \text{ord}_\varepsilon \Gamma$ holds.

The proof is from the paper [10].
Proof. Suppose the opposite is true, i.e. \( \ord x \Gamma < \ord \Gamma \). By the definition of \( \ord \), there exists \( \rho > 0 \) such that for any open set \( U \ni x \) with \( \text{diam} U < \rho \) the inequality \( \sharp(\Gamma \cap \partial U) \geq \ord x \Gamma \) holds. Thus for each positive \( \varepsilon < \frac{\rho}{3} \) we have
\[
\sharp(\Gamma \cap \partial B_\varepsilon(x)) \geq \ord x \Gamma.
\]
On the other hand, by the definition of \( \ordball \), there exists such positive \( \delta < \frac{\rho}{3} \) that
\[
\sharp(\Gamma \cap \partial B_\delta(x)) = \ordball x \Gamma < \ord \Gamma.
\]
We got a contradiction.

Remark 2.4. Let \( \Gamma \subset \mathbb{R}^n \) be a connected set of a finite length and let \( x \in \Gamma \). Then, due to coarea inequality, there exists \( \rho = \rho(x) > 0 \) such that for any positive \( \varepsilon < \rho \) the inequality
\[
\mathcal{H}^1(\Gamma \cap B_\varepsilon(x)) \geq \ordball x \Gamma \cdot \varepsilon
\]
holds. In particular, it implies the finiteness of the order and the circular order:
\[
\ord x \Gamma \leq \ordball x \Gamma < \infty.
\]

Remark 2.5. Let \( \Gamma \subset \mathbb{R}^n \) be a closed connected set of a finite length and let \( x \in \Gamma \). By Remark 2.4, \( \ord x \Gamma_1 > 0 \) for any connected component \( \Gamma_1 \) of \( \Gamma \setminus \{x\} \), so \( \ord x \Gamma \) is at least the number of such connected components. By Remark 2.4, \( \ord x \Gamma < \infty \), so the number of connected components of \( \Gamma \setminus \{x\} \) is finite for any \( x \in \Gamma \).

Definition 2.6. Let \( \Gamma \subset \mathbb{R}^n \) be a closed connected set of a finite length and let \( x \in \Gamma \). We will say that \( \varepsilon > 0 \) is \((\Gamma, x)\)-nice if \( \sharp(\Gamma \cap \partial B_\varepsilon(x)) = \ordball x \Gamma \) and for every connected component \( \Gamma_1 \) of \( \Gamma \setminus \{x\} \) the inequality \( \sharp(\Gamma_1 \cap \partial B_\varepsilon(x)) > 0 \) holds.

Definition 2.7. Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^n \) and \( r > 0 \). A point \( x \in \Sigma \) is energetic if for every \( \varepsilon > 0 \) the inequality
\[
F_M(\Sigma \setminus B_\varepsilon(x)) > F_M(\Sigma)
\]
holds.

The set of all energetic points of \( \Sigma \) is denoted by \( G_\Sigma \). Each local minimizer \( \Sigma \) can be split into three disjoint subsets:
\[
\Sigma = E_\Sigma \sqcup X_\Sigma \sqcup S_\Sigma,
\]
where \( X_\Sigma \subset G_\Sigma \) is the set of isolated energetic points (i.e. every \( x \in X_\Sigma \) is energetic and there exists \( \rho = \rho(x) > 0 \) such that \( G_\Sigma \cap B_\rho(x) = \{x\} \)), \( E_\Sigma := G_\Sigma \setminus X_\Sigma \) is the set of non-isolated energetic points and \( S_\Sigma := \Sigma \setminus G_\Sigma \) is the set of non-energetic points.

For every energetic point \( x \in G_\Sigma \) there exists a point, corresponding to \( x \), i.e. such a point \( y(x) \in M \) that \( \text{dist}(x, y(x)) = r \) and \( \Sigma \cap B_r(y(x)) = \emptyset \). We will refer to this property as the basic property of energetic points. Note that an energetic point \( x \in G_\Sigma \) may have several points corresponding to it, and a non-energetic point \( x \in S_\Sigma \) may also have a corresponding point.

Remark 2.8. Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^n \) and \( r > 0 \), and let \( x \in S_\Sigma \) be a non-energetic point. Then \( \ord x \Sigma = \ordball x \Sigma \in \{2, 3\} \), and there exists such \( \rho = \rho(x) > 0 \) that
- if \( \ord x \Sigma = 2 \), then \( \overline{\Sigma \cap B_\rho(x)} \) is a segment with endpoints at \( \partial B_\rho(x) \) which contains \( x \);
- if \( \ord x \Sigma = 3 \), then \( \overline{\Sigma \cap B_\rho(x)} \) is a regular tripod centered at \( x \), i.e. the union of three segments with one endpoint at \( x \) and another at \( \partial B_\rho(x) \), and pairwise angles \( 2\pi/3 \) between them.
Definition 3.1. The ray of
Remark 2.13. If
Definition 2.11. Let
We will say that the ray
exists a sequence of points
Let k ∈ ∪ {y ∈ Σ : y ∈ GΣ} be a sequence of energetic points converging to a non-isolated energetic point x ∈ EΣ: xk → x. By the basic property of energetic points, for every point xk ∈ GΣ there exists a corresponding point yk = yk(xk) ∈ M. Let y be an arbitrary limit point of the set {yk}. Then y ∈ M and Σ ∩ Bε(y) = ∅, i.e. y corresponds to x.
Definition 2.12. We will say that the ray (ax) is a one-sided tangent of the set Γ ⊂ R^n at the point x ∈ Γ if there exists a connected component Γ1 of Γ \ {x} with the property that any sequence of points xk ∈ Γ1 such that xk → x satisfies ∠xxα → 0. In this case we will also say that (ax) is tangent to the connected component Γ1.
Remark 2.13. If (ax) is a one-sided tangent of the set Γ ⊂ R^n at the point x ∈ Γ, then it is also a tangent ray of Γ at x, but not vice versa.

3 Results
Definition 3.1. Let Σ be a local minimizer for a compact set M ⊂ R^n and r > 0. Given any x ∈ Σ and any ε > 0, define the set
\[ U(x, ε) := \left\{ u ∈ M \mid \text{dist} (u, Σ ∩ Bε(x)) \leq r, \text{dist} (u, Σ \setminus Bε(x)) \geq r \right\}. \]
Remark 3.2. Let Σ be a local minimizer for a compact set M ⊂ R^n and r > 0. For any x ∈ Σ the set \( \bigcap_{ε > 0} U(x, ε) \) is precisely the set of corresponding points. In particular, if U(x, ε) = ∅ for some ε > 0, then a point x ∈ Σ is non-energetic.
Remark 3.3. Let Σ be a local minimizer for a compact set M ⊂ R^n and r > 0, and let x ∈ GΣ be an energetic point. Then for any u ∈ U(x, ε) there exists a corresponding point y(x) such that ∠uxy(x) = o_ε(1).
Proof. Consider the contrary, then there exists a constant c > 0 and sequences εi → 0 and ui ∈ U(x, εi) such that ∠uxi,yi(x) ≥ c for any corresponding point y(x). Due to compactness, there exists a converging subsequence uik → y for some limit point y. By Remark 3.2 y ∈ \( \bigcap_{ε > 0} U(x, ε) \) corresponds to x. But then ∠uki,y ≥ ε for any k, so 0 = ∠xy ≥ c, which is a contradiction.
Note that for any u ∈ U(x, ε) the inequality |ux| ≤ r + ε holds. In the following lemma we show that ε on the right hand side can be replaced by o(ε).
Lemma 3.4. Let $\Sigma$ be a local minimizer for a compact set $M \subset \mathbb{R}^n$ and $r > 0$, and let $x \in G_\Sigma$ be an energetic point. Then for any $u \in U(x, \varepsilon)$ the inequality $|xu| \leq r + o(\varepsilon)$ holds.

Proof. Consider an arbitrary point $u \in U(x, \varepsilon)$ and let a point $z \in \Sigma \cap B_\varepsilon(x)$ be such that $|uz| \leq r$ (see pic. 1). Let $y(x)$ be such a corresponding point that $\angle uxy(x) = o_{\varepsilon}(1)$ as in Remark 3.3. By the definition of a corresponding point, $z \notin B_r(y(x))$. Then

$$\angle zux \geq \angle zxy - \angle uxy \geq \frac{\pi}{2} - o_{\varepsilon}(1),$$

so

$$\angle uzx \leq \pi - \angle zux - \angle zux \leq \frac{\pi}{2} + o_{\varepsilon}(1).$$

Define $z'$ as the base of the perpendicular from $x$ to $(zu)$, if $\angle uzx < \pi/2$, and as equal to $z$, otherwise. Then $\angle uz'x = \pi/2 + o_{\varepsilon}(1)$.

Consider the triangle $\Delta z'zu$. In this triangle $|z'u| \leq |zu| \leq r$, $|xz'| \leq |xz| \leq \varepsilon$ and $\angle uz'x = \pi/2 + o_{\varepsilon}(1)$.

Then, by the law of cosines,

$$|xu| = \sqrt{|xz'|^2 + |z'u|^2 - 2 \cos \angle uz'x \cdot |z'u| \cdot |xz'|} \leq \sqrt{r^2 + \varepsilon^2 + \varepsilon \cdot o_{\varepsilon}(1)} = r + o(\varepsilon).$$

\hfill \blacksquare

Lemma 3.5. Let $r > 0$. There exists $c = c(n) > 0$ and $\rho = \rho(n, r) > 0$ such that for any positive $\varepsilon < \rho$ and any $x \in \mathbb{R}^n$ there exists a connected set $S(x, \varepsilon) \ni x$ satisfying $B_{r+\varepsilon}(x) \subset B_r(S(x, \varepsilon))$ and $H^1(S(x, \varepsilon)) = c\varepsilon$. 

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Proof. Let \( x = (x_1, \ldots, x_n) \), let \( c' := 4\sqrt{n} \), and let \( V \) be the set consisting of \( 2^n \) points which differ from \( x \) by \( c'\varepsilon \) at each coordinate. Let \( S = S(x, \varepsilon) \) be a Steiner tree on the set \( V \cup \{x\} \). Note that \( S \) is connected, \( x \in S \) and \( \mathcal{H}^1(S) = c\varepsilon \) for some \( c = c(n) \).

Let \( y = (y_1, \ldots, y_n) \in B_{r+\varepsilon}(x) \). Due to symmetry, we can assume that \( l_i := y_i - x_i \geq 0 \) for \( 1 \leq i \leq n \). Let \( l := \text{dist}(y, x) \) and note that \( 0 \leq l \leq r + \varepsilon \) and that \( l_i \geq l/\sqrt{n} \) for some \( i \). Let \( v := (x_1 + c\varepsilon, \ldots, x_n + c\varepsilon) \). Note that \( v \in V \), so \( v \in S \). Let us estimate the distance from \( y \) to \( v \):

\[
(\text{dist}(y,v))^2 = \sum_{i=1}^{n} (l_i - c\varepsilon)^2 = l^2 - 2c\varepsilon \sum_{i=1}^{n} l_i + o(\varepsilon) \leq l^2 - \frac{2lc'}{\sqrt{n}}\varepsilon + o(\varepsilon) = l^2 - 8\varepsilon + o(\varepsilon).
\]

If \( l < \frac{\varepsilon}{2} \), then \( (\text{dist}(y,v))^2 \leq \frac{\varepsilon^2}{4} + o(\varepsilon) \leq r^2 \) for a sufficiently small \( \varepsilon \). On the other hand, if \( l \geq \frac{\varepsilon}{2} \), then

\[
(\text{dist}(y,v))^2 \leq (r + \varepsilon)^2 - 4r \varepsilon + o(\varepsilon) = r^2 - 2r \varepsilon + o(\varepsilon) \leq r^2
\]

if \( \varepsilon \) is small enough. This concludes the proof of the lemma.

By combining Lemma 3.4 and Lemma 3.5 we get the following corollary.

**Corollary 3.6.** Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^n \) and \( r > 0 \), and let \( x \in \Sigma \). Then there exists \( \rho = \rho(x) > 0 \) such that for any positive \( \varepsilon < \rho \) there exists a connected set \( S^*(x, \varepsilon) \ni x \) satisfying \( \mathcal{H}^1(S^*(x, \varepsilon)) = o(\varepsilon) \) and

\[
F_M(\Sigma \setminus B_c(x) \cup S^*(x, \varepsilon)) \leq F_M(\Sigma).
\]

**Lemma 3.7.** Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^n \) and \( r > 0 \), and let \( x \in \Sigma \). There exists \( \rho = \rho(x) > 0 \) such that

1. for any positive \( \varepsilon < \rho \) the equality \( \mathcal{H}^1(\Sigma \cap B_{c}(x)) = \text{ordball}_{x} \Sigma \cdot \varepsilon + o(\varepsilon) \) holds;
2. for any \( (\Sigma, x) \)-nice \( \varepsilon < \rho \) and any \( A, B \in \Sigma \cap \partial B_{c}(x) \), \( A \neq B \), the inequality \( \angle AxB \geq 2\pi/3 - o_{\varepsilon}(1) \) holds;
3. for any \( (\Sigma, x) \)-nice \( \varepsilon < \rho \) there exists \( (\Sigma, x) \)-nice \( \delta < \varepsilon \) such that \( \delta = \varepsilon \cdot (1 - o_{\varepsilon}(1)) \).

**Proof.**

1. Let us start by showing that the claim holds for any \( (\Sigma, x) \)-nice \( \varepsilon < \rho \). Indeed, assume the contrary, then, in view of Remark 3.4 there exists \( c > 0 \) and a sequence \( (\Sigma, x) \)-nice \( \varepsilon_k > 0 \) such that \( \varepsilon_k \to 0 \) and \( \mathcal{H}^1(\Sigma \cap B_{c_k}(x)) \geq (\text{ordball}_x \Sigma + c) \cdot \varepsilon_k \) for every \( k \). Then, for a sufficiently big \( k \), the set

\[
\Sigma \setminus B_{c_k}(x) \cup S^*(x, \varepsilon_k) \cup \bigcup_{A \in \Sigma \cap \partial B_{c_k}(x)} [Ax],
\]

where \( S^*(x, \varepsilon_k) \) is from Corollary 3.6 is connected, has the energy not greater than \( \Sigma \) and is shorter than \( \Sigma \), which is not possible.

Now, assume that the claim is false if \( \varepsilon < \rho \) is allowed not to be \( (\Sigma, x) \)-nice. Then there exists \( c > 0 \) and a sequence \( \varepsilon_k > 0 \) such that \( \varepsilon_k \to 0 \), \( \mathcal{H}^1(\Sigma \cap B_{c_k}(x)) \geq (\text{ordball}_x \Sigma + c) \cdot \varepsilon_k \) and \( \mathcal{H}^1(\Sigma \cap \partial B_{c_k}(x)) \geq \text{ordball}_x \Sigma + 1 \). Let \( \delta_k \geq \varepsilon_k \) be the infimum of \( (\Sigma, x) \)-nice \( \delta > \varepsilon_k \). On the one hand, \( \delta_k \) is a limit point of some sequence of \( (\Sigma, x) \)-nice \( \varepsilon < \rho \), so \( \mathcal{H}^1(\Sigma \cap B_{\delta_k}(x)) = \text{ordball}_x \Sigma \cdot \delta_k + o(\delta_k) \). On the other hand, due to coarea inequality,

\[
\mathcal{H}^1(\Sigma \cap B_{\delta_k}(x)) \geq (\text{ordball}_x \Sigma + c) \cdot \varepsilon_k + (\text{ordball}_x \Sigma + 1) \cdot (\delta_k - \varepsilon_k) \geq (\text{ordball}_x \Sigma + \min(c, 1)) \cdot \delta_k
\]

for every \( k \). We have a contradiction.
2. Assume the contrary, i.e. that there exists \( c > 0 \), a sequence of \((\Sigma, x)\)-nice \(\varepsilon_k\), and \(A_k, B_k \in \Sigma \cap \partial B_{r_k}(x)\), \(A_k \neq B_k\) for each \( k \), such that \(\varepsilon_k \to 0\) and \(\angle A_k x B_k < 2\pi/3 - c\). Then, for a sufficiently big \( k \), the set

\[
\Sigma \setminus B_{r_k}(x) \cup S^*(x, \varepsilon_k) \cup \mathcal{S}(A_k, x, B_k) \cup \bigcup_{C \in (\Sigma \cap \partial B_{r_k}(x)) \setminus \{A_k, B_k\}} [C, x],
\]

where \( S^*(x, \varepsilon_k) \) is from Corollary 3.6 and \(\mathcal{S}(A_k, x, B_k)\) is a Steiner tree on the set \(\{A_k, x, B_k\}\), is connected and has the energy not greater than \(\Sigma\). In view of Proposition 3.8 and item 4 it is also shorter than \(\Sigma\) if \( k \) is sufficiently big. It is not possible, so our assumption is false.

3. Assume the contrary, then there exists \( c > 0 \) and a sequence of \((\Sigma, x)\)-nice \(\varepsilon_k\) such that \(\varepsilon_k \to 0\) and \(\gamma(\Sigma \cap \partial B_{r_k}(x)) \geq \text{ordball}_x \Sigma + 1\) for every \( \delta \) satisfying \((1 - c) \cdot \varepsilon_k \leq \delta < \varepsilon_k\). Let \( 0 < \delta_k \leq (1 - c) \cdot \varepsilon_k \) be the supremum of \((\Sigma, x)\)-nice \(\delta < \varepsilon_k\). Then, due to coarea inequality,

\[
\mathcal{H}^1(\Sigma \cap B_{r_k}(x)) \geq \text{ordball}_x \Sigma \cdot \delta_k + (\text{ordball}_x \Sigma + 1) \cdot (\varepsilon_k - \delta_k) \geq (\text{ordball}_x \Sigma + c) \cdot \varepsilon_k
\]

for every \( k \), which contradicts item 4.

\[
\square
\]

**Corollary 3.8.** Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^n \) and \( r > 0 \), and let \( x \in \Sigma \).

1. The angle between any pair of one-sided tangents of \( \Sigma \) at \( x \) is at least \(2\pi/3\). In view of Proposition 3.8 all one-sided tangents of \( \Sigma \) at \( x \) are coplanar.

2. The equality \(\text{ord}_x \Sigma = \text{ordball}_x \Sigma\) holds. Moreover, \( 1 \leq \text{ord}_x \Sigma \leq 3 \).

3. There are exactly \(\text{ord}_x \Sigma\) one-sided tangents of \( \Sigma \) at \( x \) and exactly \(\text{ord}_x \Sigma\) connected components of \(\Sigma \setminus \{x\}\) with one-to-one correspondence between them, i.e. every connected component has a one-sided tangent, and every one-sided tangent is tangent to exactly one connected component. It follows that the same is true if we replace “one-sided tangents” with “tangent rays”.

4. Let \( \Sigma_1 \) be an arbitrary connected component of \(\Sigma \setminus \{x\}\). Then \(\text{ord}_x \Sigma_1 = \text{ordball}_x \Sigma_1 = 1\), and for any \( \varepsilon > 0 \) the equality \(\mathcal{H}^1(\Sigma_1 \cap B_{r_k}(x)) = \varepsilon + o(\varepsilon)\) holds.

**Proof.** Item 4 of Lemma 3.7 immediately implies item 4 of this corollary and the part of item 4 of this corollary, namely, the claim that every one-sided tangent of \(\Sigma\) at \( x \) is tangent to exactly one connected component of \(\Sigma \setminus \{x\}\).

Due to item 3 of Lemma 3.7 there is a sequence of \((\Sigma, x)\)-nice \(\varepsilon_k \to 0\) such that \(\varepsilon_{k+1} = (1/2 + o\varepsilon_k(1)) \cdot \varepsilon_k\) for every \( k \). In view of item 4 of Lemma 3.7

\[
\mathcal{H}^1(\Sigma \cap B_{r_k}(x) \setminus B_{r_{k+1}}(x)) = (\varepsilon_k - \varepsilon_{k+1}) \cdot (\text{ordball}_x \Sigma + o\varepsilon_k(1)). \quad (1)
\]

Let \( t := \text{ordball}_x \Sigma \), and let \(\{A_1^k, \ldots, A_t^k\} := \Sigma \cap \partial B_{r_k}(x)\). Then, due to (1), up to a re-enumeration of \(A_i^k\) for each fixed \( k \), we have \(\angle A_i^k x A_{i+1}^k = o\varepsilon_k(1)\) for \( 1 \leq i \leq t \). Then there exist points \(A_1, \ldots, A_t\) such that \((A_i^k x) \to (A_i x)\) for \( 1 \leq i \leq t \). Due to item 2 of Lemma 3.7 the inequality \(\angle A_i x A_j \geq 2\pi/3\) holds for any \( i \neq j \). In particular, it follows that \( t \leq 3 \).

To show that \((A_1 x), \ldots, (A_t x)\) are \( t \) one-sided tangents each tangent to its own connected component of \(\Sigma \setminus \{x\}\), it is sufficient to show that for any \( z \in \Sigma \setminus \{x\}\) we have

\[
\min_{1 \leq i \leq t} \angle z x A_i = o(|z x|)(1).
\]

Assume that is not so, i.e. there exists \(\gamma > 0\) and a point \( z \in \Sigma \setminus \{x\}\) such that \(|z x|\) is arbitrarily small and

\[
\min_{1 \leq i \leq t} \angle z x A_i \geq \gamma.
\]
Let $\varepsilon'$ be the infimum of $(\Sigma, x)$-nice $\varepsilon \geq |xz|$. In view of item 3 of Lemma 3.7, we have $|xz| = \varepsilon'(1-\rho(1))$. Due to item 1 of Lemma 3.7, $H^1(\Sigma \cap B_{\varepsilon'}(x) \setminus B_{|xz|}(x)) = \rho(1)$, so there is $z' \in \Sigma \cap \partial B_{\varepsilon'}(x)$ such that $|zz'| = \rho(\varepsilon')$, i.e.

$$
\min_{1 \leq i \leq t} \angle z' x A_i \geq \gamma - \rho(1).
$$

Let $k$ be such that $\varepsilon_{k+1} \leq \varepsilon' < \varepsilon_k$. Note that for any $1 \leq i \leq t$ we have

$$
|A^i_k z'| + |z' A^i_{k+1}| \geq \sqrt{\left(\sin \gamma - \rho(1)\right)^2 \cdot (\varepsilon')^2 + (\varepsilon_k - \varepsilon')^2 + \sqrt{\sin \gamma - \rho(1)^2} \cdot \varepsilon_k^2 + (\varepsilon' - \varepsilon_{k+1})^2}
$$

$$
\geq (\varepsilon_k - \varepsilon_{k+1}) \cdot \left(\sqrt{\sin^2 \gamma + 1 + \rho(1)}\right) \geq (\varepsilon_k - \varepsilon_{k+1}) \cdot \left(1 + \frac{\sin^2 \gamma}{3} + \rho(1)\right).
$$

Then, due to item 1 of Lemma 3.7,

$$(t + \rho(1)) \cdot \varepsilon_k = H^1(\Sigma \cap B_{\varepsilon_k}(x))
= H^1(\Sigma \cap B_{\varepsilon_{k+1}}(x)) + H^1(\Sigma \cap B_{\varepsilon'}(x) \setminus B_{\varepsilon_{k+1}}(x)) + H^1(\Sigma \cap B_{\varepsilon_k}(x) \setminus B_{\varepsilon'}(x))
\geq t \cdot \varepsilon_{k+1} + (t - 1) \cdot (\varepsilon_k - \varepsilon_{k+1}) + (\varepsilon_k - \varepsilon_{k+1}) \cdot \left(1 + \frac{\sin^2 \gamma}{3} + \rho(1)\right)
\geq \left(t + \frac{\sin^2 \gamma}{6} + \rho(1)\right) \cdot \varepsilon_k,
$$

which is a contradiction.

We have shown that there are $t = \text{ordball}_x \Sigma \geq \text{ord}_x \Sigma$ one-sided tangents of $\Sigma$ at $x$. Each of them is tangent to its own connected component of $\Sigma \setminus \{x\}$. Since $\text{ord}_x \Sigma > 0$ for any connected component $\Sigma_i$ of $\Sigma \setminus \{x\}$, it follows that $\text{ord}_x \Sigma = \text{ordball}_x \Sigma$, and that there are no more connected components, i.e. each connected component of $\Sigma \setminus \{x\}$ indeed has a one-sided tangent. That concludes the proof of items 2 and 3 of this corollary.

Finally, item 4 follows from previous items of this corollary and item 1 of Lemma 3.7.

### 3.1 Technical results

In view of Corollary 3.8 from this point on we are going to make no distinction between $\text{ord}_x \Sigma$ and $\text{ordball}_x \Sigma$, and will always write $\text{ord}_x \Sigma$.

**Lemma 3.9.** Let $\Sigma$ be a local minimizer for a compact set $M \subset \mathbb{R}^n$ and $r > 0$, let $x \in G_{\Sigma}$ be an energetic point and let $\{(a_i, x)|_{i=1}^{\text{ord}_{x} \Sigma}\}$ be the set of all one-sided tangents of $\Sigma$ at $x$. Let

$$
N(x) := \left\{ z \in \mathbb{R}^n \mid z = \sum_{i=1}^{n} \alpha_i \langle x, y_i(x) \rangle, \ y_i(x) \text{ corresponds to } x, \ \alpha_i \geq 0 \right\},
$$

i.e. $N(x)$ is the conical hull of all vectors starting at $x$ and ending at some point, corresponding to $x$. Then

$$
\mathcal{S}(x) := \sum_{i=1}^{\text{ord}_x \Sigma} \frac{a_i x}{|a_i x|} \in N(x).
$$

**Proof.** Assume the contrary, then $\{\mathcal{S}(x)\}$ and $N(x)$ are two disjoint nonempty closed convex sets. Moreover, the set $\{\mathcal{S}(x)\}$ is compact, and $N(x)$ is a cone, so there exists a hyperspace separating $\{\mathcal{S}(x)\}$ from $N(x)$, i.e. a unit vector $\bar{h} \in \mathbb{R}^n$ such that $\langle \mathcal{S}(x), \bar{h} \rangle = -\rho < 0$ and $\langle \bar{h}, \bar{h} \rangle \geq 0$ for any $\bar{h} \in N(x)$.

Let $\varepsilon$ be $(\Sigma, x)$-nice, and let $\{A_i|_{i=1}^{\text{ord}_x \Sigma} := \Sigma \cap \partial B_{x}(x)\}$ be such that $\angle a_i x A_i = \rho(1)$. Let $\mathcal{S} := \sum_{i=1}^{\text{ord}_x \Sigma} A_i x$, then $\langle \mathcal{S}, \bar{h} \rangle = -\rho + \rho(1)$. By Lemma 3.3, where exists $\delta = \rho(\varepsilon)$ such that $|ux| \leq r + \delta$ for any $u \in U(x, \varepsilon)$.

Let $x' = x + k \delta \hat{h}$ for some constant $k > 0$ which we will choose later. Then

$$
\sum_{i} |A_i x'| = \sum_{i} |A_i x + xx'| = \sum_{i} \sqrt{\varepsilon^2 + k^2 \delta^2 + 2k \delta (A_i x, \bar{h})} = \sum_{i} \varepsilon \cdot \sqrt{1 + (k \delta / \varepsilon)^2 + 2(k \delta / \varepsilon)^2} \cdot (A_i x, \bar{h}) =
$$

...
$$\sum_i \varepsilon \cdot (1 + (k\delta/\varepsilon^2)\langle A_i x, \tilde{h} \rangle + o_c(\delta/\varepsilon)) = \text{ord}_x \Sigma \cdot \varepsilon + \langle \tilde{S}', \tilde{h} \rangle \cdot (k\delta/\varepsilon) + o_c(\delta) = \text{ord}_x \Sigma \cdot \varepsilon - pk\delta + o_c(\delta).$$

Let $u \in U(x, \varepsilon)$. By Remark 3.3, there exists a corresponding point $y(x)$ such that $\angle uxy(x) = o_c(1)$, so $\langle \tilde{x}u, \tilde{h} \rangle \geq -o_c(1)$. Then

$$|x'u| = |x'x + \tilde{x}u| \leq \sqrt{k^2\delta^2 + (r + \delta)^2} - 2k\delta(\tilde{x}u, \tilde{h}) \leq \sqrt{(r + \delta)^2 + o_c(\delta)} = r + \delta + o_c(\delta).$$

Then, by Lemma 3.5, there exists a connected set $S \ni x'$ of length $c \cdot (\delta + o_c(\delta))$ for some fixed $c > 0$ such that $U(x, \varepsilon) \subset B_{r+\delta+o_c(\delta)}(x') \subset B_r(S)$. Then the set

$$\Sigma \setminus B_r(x) \cup \bigcup_{i=1}^{\text{ord}_x \Sigma} \mathbb{R} A_i x' \cup S$$

is connected, is shorter than $\Sigma$ if $k > c/\rho$ and $\varepsilon$ is small enough, and has the energy not larger than $\Sigma$. It is not possible, since $\Sigma$ is a local minimizer.

**Proposition 3.10.** Let $\Sigma$ be a local minimizer for a compact set $M \subset \mathbb{R}^n$ and $r > 0$. Let $x \in E_S$ be a non-isolated energetic point, and let $\Sigma_1$ be a connected component of $\Sigma \setminus \{x\}$ with one-sided tangent $(ax)$.

1. Let $\Sigma_1$ contain a sequence of energetic points $x_k \in \Sigma_1 \cap G_S$ converging to $x$: $x_k \to x$. Let a sequence of their corresponding points $y(x_k)$ converge to a point $y_1$ such that vector $\bar{xy}(\bar{x})$ is $o_{|\bar{x}|}(1)$-parallel to $\bar{xy}$ and vector $\bar{xy}$ is orthogonal to $a\bar{x}$.

2. Let $\bar{x} \in \Sigma_1 \cap G_S$ be an energetic point, and let $y(\bar{x})$ be any of its corresponding points. Then there exists a point $y = y(x)$ corresponding to $x$ such that vector $\bar{xy}(\bar{x})$ is $o_{|\bar{x}|}(1)$-parallel to $\bar{xy}$ and vector $\bar{xy}$ is orthogonal to $a\bar{x}$.

3. Let $\bar{x} \in \Sigma_1$ be a point with ord $\Sigma = 1$. Note that, due to Remark 3.3, $\bar{x}$ is energetic: $\bar{x} \in G_S$. Then the one-sided tangent $(\bar{a}\bar{x})$ of $\Sigma$ at $\bar{x}$ is $o_{|\bar{x}|}(1)$-orthogonal to $(ax)$.

4. Let $\bar{x} \in \Sigma_1$ be a point with ord $\Sigma = 2$, and let $(\bar{a}\bar{x})$ and $(\bar{b}\bar{x})$ be one-sided tangents of $\Sigma$ at $\bar{x}$. Then $|\angle((\bar{a}\bar{x}), (ax)) - \angle((\bar{b}\bar{x}), (ax))| = o_{|\bar{x}|}(1)$.

**Proof.** Let us start with a claim slightly weaker than item (2).

(a) Let $\bar{x} \in \Sigma_1 \cap G_S$ be an energetic point, and let $y(\bar{x})$ be any of its corresponding points. Then $\bar{xy}(\bar{x})$ is $o_{|\bar{x}|}(1)$-orthogonal to $a\bar{x}$.

Indeed, note that $y(\bar{x}) \in U(x, |\bar{x}|\varepsilon)$, so, by Remark 3.3, $\angle y(x)xy(\bar{x}) = o_{|\bar{x}|}(1)$ for some corresponding point $y(x)$. Then, on the one hand, $\Sigma \cap B_r(y(x)) = \emptyset$, so

$$\angle \bar{xy}(\bar{x}) \geq \pi/2 - o_{|\bar{x}|}(1), \text{ and } \angle \bar{xy}(\bar{x}) \geq \angle \bar{xy}(\bar{x}) - \angle y(\bar{x})xy(\bar{x}) \geq \pi/2 - o_{|\bar{x}|}(1).$$

On the other hand, $\Sigma \cap B_r(y(\bar{x})) = \emptyset$, so $\angle \bar{xy}(\bar{x}) \geq \pi/2 - o_{|\bar{x}|}(1)$. Then, considering the sum of angles in triangle $\triangle \bar{xy}(\bar{x})$, we have $\angle \bar{xy}(\bar{x}) = \pi/2 + o_{|\bar{x}|}(1)$, i.e. $\bar{xy}(\bar{x})$ is $o_{|\bar{x}|}(1)$-orthogonal to $a\bar{x}$. Finally, $\angle \bar{xy} = o_{|\bar{x}|}(1)$, so $\bar{xy}(\bar{x})$ is $o_{|\bar{x}|}(1)$-orthogonal to $a\bar{x}$.

Now let us turn to the claims of the Proposition.

1. Due to Remark 2.10, $y$ corresponds to $x$. In view of (a) $\bar{xy}(\bar{x})$ is $o_{|\bar{x}|}(1)$-orthogonal to $a\bar{x}$, so $\bar{xy}$ is orthogonal to $a\bar{x}$.

2. Assume the contrary, then there exist a constant $c > 0$ and sequences of energetic points $x_k \in \Sigma_1 \cap G_S$ and their corresponding points $y(x_k)$ such that $x_k \to x$ and $\angle \bar{xy}(\bar{x}) \geq c$ for any $k$ and any corresponding to $x$ point $y = y(x)$ with $\widetilde{xy}$ orthogonal to $a\bar{x}$. One can choose a converging subsequence $y(x_k) \to y$. Then, due to item (1), $y$ corresponds to $x$, and $\bar{xy}$ is orthogonal to $a\bar{x}$. But $x_k \to x$ and $y(x_k) \to y$, so $\angle (x_k, y(x_k), \overrightarrow{xy}) \to 0$, which is a contradiction.
Item [3] and item [4] for energetic \( \bar{x} \) immediately follow from item [2] and Lemma 3.9. Item [4] for non-energetic \( \bar{x} \) follows from Remark 2.8.

**Definition 3.11.** For any set \( \Gamma \subset \mathbb{R}^n \) such that there is a unique path between any pair of points in \( \Gamma \) and for any \( a, b \in \Gamma \) we will denote by \( \Gamma(a, b) \) the unique path in \( \Gamma \) connecting \( a \) and \( b \).

**Definition 3.12.** For any points \( x_1, \ldots, x_k \in \mathbb{R}^n \) such that any two segments from \([x_1 x_2], \ldots, [x_{k-1} x_k]\) intersect only, possibly, at endpoints, we will denote by \( x_1 \cdots x_k \) a polygonal chain connecting \( x_1, \ldots, x_k \), i.e. a union of segments \([x_1 x_2], \ldots, [x_{k-1} x_k]\).

**Lemma 3.13.** Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^n \) and \( r > 0 \). Let \( x \in \Sigma \), and let \( \Sigma_i \) be a connected component of \( \Sigma \setminus \{x\} \) with one-sided tangent \( (ax) \). Let \( x_i \in \Sigma_i \) be a sequence such that \( x_i \to x \) and the path \( \Sigma(x_1, x_i) \) coincides with the polygonal chain \( x_1 \cdots x_i \) for any \( i > 1 \). Then there exists an infinite subsequence \( x_{i_k} \) such that \( \angle((x_{i_k} x_{i_k+1}), (ax)) \to 0 \).

**Proof.** Assume the contrary, i.e. there exists a positive \( c < \pi/2 \) such that \( \angle((x_i x_{i+1}), (ax)) \geq c \) for every sufficiently big \( i \). Denote by \( \bar{x}_i \) the orthogonal projection of \( x_i \) onto \( (ax) \), then \( |\bar{x}_i \bar{x}_{i+1}| \leq |x_i x_{i+1}| \cdot \cos c \) for every sufficiently big \( i \). By the definition of a one-sided tangent, \( \angle x_i x a \to 0 \), so \( |\bar{x}_i \bar{x}| = |x_i x| \cdot (1 + o_{|x_i x|}(1)) \). Due to item [3] of Lemma 3.7 for every sufficiently big \( i \) there exists a \( (\Sigma, x) \)-nice \( \delta_i \geq |x_i x| \) such that \( \delta_i = |x_i x| \cdot (1 + o_{|x_i x|}(1)) \). Note that \( \Sigma(x_i, x) \subset B_{\delta_i}(x) \) if \( i \) is big enough. Then for every sufficiently big \( i \) we have

\[
\mathcal{H}^1(\Sigma_1 \cap B_{\delta_i}(x)) \geq \mathcal{H}^1(\Sigma(x_i, x)) = \sum_{j=1}^{\infty} |x_j x_{j+1}| \geq \sum_{j=1}^{\infty} \frac{|\bar{x}_j \bar{x}_{j+1}|}{\cos c} \geq \frac{|x_i x|}{\cos c} \cdot \delta_i \cdot \left( \frac{1}{\cos c} + o_{|x_i x|}(1) \right),
\]

which contradicts item [4] of Corollary 3.8.

The following proposition is an analogue of Remark 2.8 for isolated energetic points. Even though it is true in general case (\( \mathbb{R}^n \) for \( n > 2 \)), in view of Remark 2.9 we are able to use it in a meaningful way only in planar case.

**Proposition 3.14.** Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^n \) and \( r > 0 \). For any isolated energetic point \( x \in X_\Sigma \) there exists such \( \rho = \rho(x) > 0 \) that the set \( \Sigma \cap \overline{B}_\rho(x) \) is a union of ord.\( \Sigma \)-segments with one end at \( x \) and another at \( \partial B_\rho(x) \), with pairwise angles between them at least \( 2\pi/3 \). In view of Proposition 1.7 these segments are coplanar.

**Proof.** Let \( \varepsilon \) be \( (\Sigma, x) \)-nice and such that \( G_\Sigma \cap \overline{B}_\varepsilon(x) = \{x\} \). There exists a sequence of \( (\Sigma, x) \)-nice \( \varepsilon_i < \varepsilon \) such that \( \varepsilon_i \to 0 \). For each \( i \) define the set

\[
\Sigma_i := \Sigma \cap \overline{B}_{\varepsilon_i}(x) \setminus B_{\varepsilon_i}(x).
\]

We can assume that \( \varepsilon \) is small enough that \( \Sigma \) is the shortest set among all sets \( \Sigma' \) with diam \( (\Sigma \triangle \Sigma') \leq \varepsilon \) and \( F_M(\Sigma') \leq r \). Thus a closed set \( \Sigma_i \subset \Sigma \) is a Steiner forest. Note that \( \Sigma_i \) has ord.\( \Sigma \)-connected components, one corresponding to each connected component of \( \Sigma \setminus \{x\} \). Moreover, each component of \( \Sigma_i \) is a Steiner tree on two vertices (one from \( \partial B_{\varepsilon_i}(x) \) and another from \( \partial B_{\varepsilon_i}(x) \), i.e. a segment. It follows that the set \( \Sigma \cap \overline{B}_\varepsilon(x) = \{x\} \cup \bigcup_{i=1}^{\infty} \Sigma_i \) is also a union of ord.\( \Sigma \)-segments with one end at \( x \) and another at \( \partial B_{\varepsilon_i}(x) \). In view of item [4] of Corollary 3.8 the pairwise angles between these segments are at least \( 2\pi/3 \).

**4 Planar results**

Note that an energetic point \( x \in G_\Sigma \) in \( \mathbb{R}^2 \) cannot have ord.\( \Sigma \) > 2 (due to item [1] of Corollary 3.8), but it is possible in \( \mathbb{R}^n \) when \( n > 2 \) (see Example 2.9).
Lemma 4.1. Let $\Sigma$ be a local minimizer for a compact set $M \subset \mathbb{R}^2$ and $r > 0$, let $x \in E_\Sigma$ be a non-isolated energetic point, and let $\Sigma_1$ be a connected component of $\Sigma \setminus \{x\}$ with one-sided tangent $(ax)$. Then there exists $\rho = \rho(x) > 0$ such that, if $\bar{x} \in \Sigma_1 \cap B_\rho(x) \cap E_\Sigma$ is a non-isolated energetic point, then $\text{ord } \Sigma = 2$, and every one-sided tangent $\langle \bar{a} \bar{x} \rangle$ of $\Sigma$ at $\bar{x}$ is $o_{|\bar{x}|}(1)$-parallel to $(ax)$.

Proof. Let $x_k \to \bar{x}$ and $y(x_k)$ be sequences satisfying conditions of item 1 of Proposition 3.10, let $\langle \bar{a} \bar{x} \rangle$ be the one-sided tangent to the connected component of $\Sigma_1 \setminus \{\bar{x}\}$ containing $x_k$, and let $y(x_k) \to y(\bar{x})$. Then $\bar{a} \bar{y}(\bar{x})$ is orthogonal to $\bar{a} \bar{x}$. On the other hand, in view of item 2 of Proposition 3.10, $\bar{a} \bar{y}(\bar{x})$ is $o_{|\bar{x}|}(1)$-orthogonal to $\bar{a} \bar{x}$. It follows that $\langle \bar{a} \bar{x} \rangle$ is $o_{|\bar{x}|}(1)$-parallel to $(ax)$.

If $\text{ord } \Sigma = 1$, then, in view of item 3 of Proposition 3.10, $\langle \bar{a} \bar{x} \rangle$ would be simultaneously $o_{|\bar{x}|}(1)$-parallel and $o_{|\bar{x}|}(1)$-orthogonal to $(ax)$, which is impossible when $\rho \geq |\bar{x}|$ is sufficiently small. On the other hand, $\text{ord } \Sigma \neq 3$ since a branching point is always non-energetic in $\mathbb{R}^2$, so $\text{ord } \Sigma = 2$.

Finally, the second one-sided tangent $\langle \bar{a} \bar{x} \rangle$ of $\Sigma$ at $\bar{x}$ is also $o_{|\bar{x}|}(1)$-parallel to $(ax)$ due to item 4 of Proposition 3.10.

Proposition 4.2. Let $\Sigma$ be a local minimizer for a compact set $M \subset \mathbb{R}^2$ and $r > 0$, let $x \in E_\Sigma$ be a non-isolated energetic point, and let $\Sigma_1$ be a connected component of $\Sigma \setminus \{x\}$ with one-sided tangent $(ax)$. Then for any polygonal chain $x_1-x_2-x_3-x_4-x_5 \subset \Sigma_1$, where $x_i \in X_\Sigma$, $\text{ord } x_\Sigma = 2$ for $1 \leq i \leq 5$, one has $\max_{1 \leq i \leq 4} \angle((x_i,x_{i+1}),(ax)) = o_\rho(1)$, where $\rho := \max_{1 \leq i \leq 5} |x_i|$.

Proof. Assume the contrary, i.e. there exists $c > 0$ such that for any $\rho > 0$ there exists a polygonal chain described above satisfying $|x_i| \leq \rho$ for $1 \leq i \leq 5$ and $\angle((x_i x_{i+1}), \langle ax \rangle) \geq c$ for some $1 \leq j \leq 4$. Let $y_i = y_i(x_i)$ be an arbitrary corresponding to $x_i$ point for $1 \leq i \leq 5$. Due to item 3 of Proposition 3.10

\[ \angle(x_i y_i, \bar{a} \bar{x}) = \pi/2 + o_\rho(1) \text{ for } 1 \leq i \leq 5. \]

In view of item 3 of Proposition 3.10, $\angle((x_i x_{i+1}), \langle ax \rangle) - \angle((x_i x_{i-1}), \langle ax \rangle) = o_\rho(1)$ for $2 \leq i \leq 4$, so

\[ \angle((x_i x_{i+1}), \langle ax \rangle) = \alpha + o_\rho(1) \text{ for } 2 \leq i \leq 4 \text{ and some } \alpha \geq c. \tag{2} \]

By the definition of a corresponding point, $\angle((x_i y_i, x_i x_{i+1}) \geq \pi/2$ for $1 \leq i \leq 5$ whenever $x_{i+1}$ is defined, so

\[ \angle(x_i y_i, x_i x_{i+1}) = \pi/2 + \alpha + o_\rho(1) \text{ for } 1 \leq i \leq 5 \text{ whenever } x_{i+1} \text{ is defined.} \]

It follows that

\[ \angle(x_i x_{i-1}, x_i x_{i+1}) = \pi - 2\alpha + o_\rho(1) \text{ for } 2 \leq i \leq 4 \tag{3} \]

and

\[ \angle(x_i y_i, x_i x_{i+1}) = \pi + o_\rho(1) \text{ for } 1 \leq i \leq 4. \]

For $2 \leq i \leq 4$, by orthogonally projecting each summand in the equation

\[ y_i x_{i+1} = y_i x_{i-1} + x_{i-1} x_i + x_i x_{i+1} \]

onto $(y_i-1 x_{i+1})$, we get

\[ r \leq |y_i-1 x_{i+1}| \leq r + |x_i-1 x_i|(1 + o_\rho(1)) \sin \alpha - |x_i x_{i+1}|(1 + o_\rho(1)) \sin \alpha, \]

i.e. $|x_i-1 x_i|/|x_i x_{i+1}| \geq 1 + o_\rho(1)$. Applying the same arguments to $y_{i+1} x_{i-1}$, we get $|x_i x_{i+1}|/|x_{i-1} x_i| \geq 1 + o_\rho(1)$, so

\[ |x_i x_{i+1}| = l \cdot (1 + o_\rho(1)) \text{ for } 1 \leq i < 5 \text{ and some } 0 < l \leq 2\rho. \tag{4} \]

It follows from (2), (3) and (4) that $\angle((x_2 x_4), (x_2 x_3)) = \alpha + o_\rho(1)$ and $\angle((x_2 x_4), (x_3 x_4)) = \alpha + o_\rho(1)$, so

\[ |x_2 x_3| + |x_3 x_4| - |x_2 x_4| = 2(1 - \cos \alpha)(1 + o_\rho(1)) \cdot l. \]
Identities (2), (3) and 4 also imply that $\angle((x_1x_5),(x_1x_3)) = o_\rho(1)$, so $\delta := \text{dist } ([x_1x_5], x_3) = o_\rho(l)$. It follows that $([x_2x_3] \cup [x_3x_4]) \subset \text{conv } \{([x_1, x_2, x_4, x_5]) \cup B_\delta([x_1x_5]), \text{i.e.}.

$$
B_r([x_2x_3] \cup [x_3x_4]) \subset B_r([x_1x_2] \cup [x_2x_4] \cup [x_4x_5]) \cup B_r+\delta([x_1x_5])
$$

Note that $B_{r+\delta}(\{x_1, x_3\}) \subset B_{r+\delta}(\{x_1, x_5\})$ for some $\delta' = o_\rho(l)$, since

$$
\sqrt{(r + \delta)^2 + \left(\frac{|x_1x_5|}{2}\right)^2} = \sqrt{r^2 + o_\rho(l)} = r + o_\rho(l).
$$

Let the sets $S_j := S(x_j, \delta'), H^1(S_j) = c\delta' = o_\rho(l), j \in \{1, 5\}$, be from Lemma 3.5. We see that the set

$$
\Sigma \setminus [x_2x_3] \cup [x_3x_4] \cup S_1 \cup S_5
$$

is connected and has energy not larger than $\Sigma$. It is also shorter than $\Sigma$ if $\rho$ is small enough, which contradicts the definition of a local minimizer.

**Theorem 4.3.** Let $\Sigma$ be a local minimizer for a compact set $M \subset \mathbb{R}^2$ and $r > 0$. There is a finite number of branching points in $\Sigma$.

**Proof.** Assume the contrary, then the set of branching points is infinite and thus has a limit point. Let $x \in \Sigma$ be such a limit point, and let $\Sigma'$ be a connected component of $\Sigma \setminus \{x\}$ which contains an infinite sequence of branching points converging to $x$. Let $(ax)$ be the unique one-sided tangent of $\Sigma'$ at $x$. Note that, due to Remark 2.8 and Proposition 3.10, $x$ is a non-isolated energetic point: $x \in E_2$.

Given a $(\Sigma, x)$-nice $\varepsilon > 0$, let $x' \in (\Sigma' \cap \partial B_\varepsilon(x))$. Also, for any branching point $z \in \Sigma' \cap B_\varepsilon(x)$ let us denote by $\Sigma_z$ the unique connected component of $\Sigma \setminus \{z\}$ not containing either of $x, x'$. Let us study the structure of $\Sigma_z$ when $\varepsilon$ is small enough.

(a) There exists $\rho = \rho(x) > 0$ such that for any $(\Sigma, x)$-nice $\varepsilon < \rho$ and any branching point $z \in \Sigma' \cap B_\varepsilon(x)$ there exists a corresponding to $x$ point $y = y(x)$ with $xy(x)$ orthogonal to $\vec{ax}$ such that for every energetic point $\bar{x} \in \Sigma_z \cap G_{\Sigma}$ and its corresponding point $y(\bar{x})$ vector $\vec{xy(\bar{x})}$ is $o_\varepsilon(1)$-parallel to $xy(x)$.

Moreover,

- if $\text{ord } z \Sigma = 1$, and $(\vec{ax})$ is the one-sided tangent of $\Sigma$ at $\bar{x}$, then $\vec{ax}$ is $o_\varepsilon(1)$-parallel to $\vec{xy(x)}$;
- if $\text{ord } z \Sigma = 2$, $(\vec{ax})$ and $(\vec{bx})$ are one-sided tangents of $\Sigma$ at $\bar{x}$, then $|\angle(\vec{ax},\vec{xy(x)}) - \angle(\vec{bx},\vec{xy(x)})| = o_\varepsilon(1)$.

Assume the contrary, then, in view of item 2 of Proposition 3.10 there exist two corresponding to $x$ points $y_1(x)$ and $y_2(x)$, with vectors $\vec{xy_1(x)}$ and $\vec{xy_2(x)}$ orthogonal to $\vec{ax}$ (so $xy_1(x) = -xy_2(x)$) such that for $i \in \{1, 2\}$ there exists an energetic point $\bar{x}_i \in \Sigma_z \cap G_{\Sigma}$ with a corresponding point $y(\bar{x}_i)$ such that vector $\vec{\bar{x}_i}y(\bar{x}_i)$ is $o_\varepsilon(1)$-parallel to $xy(x)$.

By the definition of a one-sided tangent, any point $p \in \Sigma \cap B_\varepsilon(x)$ satisfies $\angle pxa < \delta$ for some $\delta = o_\varepsilon(1)$.

Let $Q := \{p \in B_\varepsilon(x) \mid \angle pxa \leq \delta\}$, then $\Sigma' \cap B_\varepsilon(x) \subset Q$. Note that $\Sigma'(x', x)$ splits the set $Q$ into two simply connected sets; denote by $A$ one of these sets which contains both $\bar{x}_1$ and $\bar{x}_2$. For $i \in \{1, 2\}$ denote $B_i := \{p \in B_{r+\varepsilon}(x) \setminus B_{r-\varepsilon}(x) \mid \angle pxy_i(x) \leq \gamma\}$, where $\gamma := \max_\Sigma \angle(xy_i(x)) = o_\varepsilon(1)$. By definition, $y_1(\bar{x}_i) \in B_i$ for $i \in \{1, 2\}$. Note that it is true for one of $i \in \{1, 2\}$ that any segment connecting a point from $B_i$ with a point from $A$ intersects $\Sigma(x', x)$ at a point which intersects one of segments $[\bar{x}_1y(\bar{x}_1)], [\bar{x}_2y(\bar{x}_2)]$ at an internal point of a segment, which contradicts the definition of a corresponding point.

(b) There exists $\rho = \rho(x) > 0$ such that for any $(\Sigma, x)$-nice $\varepsilon < \rho$ and for every branching point $z \in \Sigma' \cap B_\varepsilon(x)$ the set $\Sigma_z$ is a segment which is $o_\varepsilon(1)$-perpendicular to $(ax)$.

Let us consider an arbitrary point $t_1$ of $\Sigma_z$ with $\text{ord } t_1 \Sigma = 1$. We are going to build a sequence of points $t_i \in (\Sigma_z \cup \{z\})$ such that
i. $\Sigma(t_i, t_j) = t_i - \cdots - t_j$ for every $i > 1$;

ii. $\angle((t_i, t_{i-1}, xy(x)) \leq \pi/3 + \gamma$ for every $i > 1$, where $y(x)$ is from [a] and $\gamma = \angle(t_2, t_1, xy(x)) = o_\varepsilon(1)$;

iii. $t_i$ is a branching point for every $i > 1$.

In view of Remark 2.8, $t_1$ is an energetic point: $t_1 \in \Sigma$. Then, in view of Lemma 4.1, $t_1$ is an isolated energetic point: $t_1 \in X_\Sigma$. Let $(a_1 t_1)$ be the one-sided tangent of $\Sigma$ at $t_1$, then, due to [a]

$\gamma := \angle(a_1 t_1, xy(x)) = o_\varepsilon(1)$. By Proposition 3.13, we have $\Sigma(t_1, B_3(t_1)) \subset \Sigma$ for any sufficiently small $\delta > 0$; choose maximal possible such $\delta$ and define $t_2$ as the unique point in $(a_1 t_1) \cap \partial B_3(t_1)$. Items [b] and [c] for $i = 2$ hold by the construction. Note that [c] and [a] imply that $t_2$ is non-energetic if $\varepsilon$ is small enough, so, due to Remark 2.8, $\text{ord}_t \Sigma \in \{2, 3\}$. Since $\delta$ in the definition of $t_2$ was maximal possible, from the same Remark $\Sigma$ it follows that $\text{ord}_t \Sigma \neq 2$, so [c] for $i = 2$ also holds.

Now, suppose we have already chosen points $t_1, \ldots, t_j$, such that conditions [a] [b] [c] hold for $i \leq j$. If $t_j = z$, we stop. Otherwise, since $t_j$ is a branching point, there exists a one-sided tangent $(a_j t_j)$ of $\Sigma$ at $t_j$ such that $\angle(a_j t_j, xy(x)) \leq \pi/3 + \gamma$. Let $\delta > 0$ be maximal possible such that $\Sigma(a_j t_j, B_3(t_j)) \subset \Sigma$, and choose $t_{j+1}$ as the unique point in $(a_j t_j) \cap \partial B_3(t_j)$. Again, [b] and [c] for $i = j + 1$ hold by the construction, and the same arguments as in the case $i = 2$ show [c] for $i = j + 1$.

Assume that $t_i \neq z$ for every $i$. Then the infinite sequence of branching points $t_i$ converges to some point, which is non-isolated energetic due to Remark 2.8 and Proposition 3.14, $t_i \rightarrow \bar{x} \in E_\Sigma(\Sigma \cup \{z\})$. Let $(\bar{x} \bar{x})$ be the one-sided tangent to a connected component of $\Sigma \setminus \{x\}$ which contains the sequence $t_i$. Due to Lemma 4.1, $(\bar{x} \bar{x})$ is $o_\varepsilon(1)$-parallel to $(ax)$. Thus, for every $i > 1$ we have

$\angle((t_i, t_{i-1}, (\bar{x} \bar{x}))) \geq \angle((t_i, t_{i-1}, (ax))) - o_\varepsilon(1) > \frac{\pi}{2} - \frac{\pi}{3} - \gamma - o_\varepsilon(1) \geq \frac{\pi}{7},$

if $\varepsilon$ is small enough. This contradicts Lemma 3.13.

It follows that $t_i = z$ for some $i > 1$. Note that in the arguments above there were two possible choices for $t_3$, so, if $t_2 \neq z$, we would have two different paths from $t_1$ to $z$ in $\Sigma$, which is not possible. Therefore, $t_2 = z$, $\Sigma = [t_1, z]$, and $\angle(z \bar{z}, \bar{x} \bar{x}) = \pi/2 - \angle(z \bar{z}, xy(x)) = \pi/2 - \gamma = \pi/2 - o_\varepsilon(1)$.

Now let us return to the proof of the theorem. Let $\varepsilon$ be $(\Sigma, x)$-nice and satisfy $\varepsilon < \rho$, where $\rho$ is from [b]. Recall that $\Sigma$ contains a sequence of branching points converging to $x$, so there exists a branching point $x_1 \in \Sigma \cap B(x)$. We are going to build a sequence of points $x_i$ such that

i*. $\Sigma(x_i, x_i) = x_1 - \cdots - x_i \subset \Sigma(x_1, x)$ for every $i > 1$;

ii*. $\angle((x_i, x_{i+1}), (ax)) \geq \pi/6 - \gamma$ for every $i$, where $\gamma = o_\varepsilon(1)$ does not depend on $i$;

iii*. $x_i$ is either a branching point or an isolated energetic point of order 2 for every $i$.

Suppose $x_1, \ldots, x_i$ are already defined. Let $(a_i x_i)$ be the one-sided tangent of $\Sigma(x_i, x)$ at $x_i$. Let $\delta > 0$ be maximal possible such that $\Sigma(a_i x_i) \subset \Sigma(x_i, x)$, and set $x_{i+1}$ as the unique point in $(a_i x_i) \cap \partial B_3(x_i)$. Item [c] follows by the construction. Note that if $x_i$ is a branching point, then $\angle((x_i, x_{i+1}), (ax)) \geq \pi/6 - \gamma'$, where $\gamma' = o_\varepsilon(1)$ is from [b] and does not depend on $i$. Otherwise, in view of Proposition 4.2, there is a branching point $x_j$ for some $j \geq i - 4$ if $\varepsilon$ is small enough. Then we have

$\angle((x_i, x_{i+1}), (ax)) \geq \angle((x_j, x_{j+1}), (ax)) - (i - j)\gamma'' \geq \pi/6 - \gamma' - 4\gamma'' = \pi/6 - \gamma,$

where $\gamma'' = o_\varepsilon(1)$ is from item [c] of Proposition 3.14 and $\gamma := \gamma' + 4\gamma'' = o_\varepsilon(1)$ does not depend on $i$. Thus item [c] holds. Finally, to see that item [ii] holds, note that if $x_{i+1}$ is not a branching point, then it is an energetic point of order 2, which cannot be non-isolated due to Lemma 4.1.

Note that conditions [c] and [c] imply that $x_i \neq x$ for every $i$. Then the sequence $x_i$ converges to some point $\bar{x}: x_i \rightarrow \bar{x}$. Let $(\bar{x} \bar{x})$ be the one-sided tangent to the connected component of $\Sigma \setminus \{\bar{x}\}$ containing $x_i$. Note that either $\bar{x} = x$ and $(\bar{x} \bar{x}) = (ax)$, or $(\bar{x} \bar{x})$ is $o_\varepsilon(1)$-parallel to $(ax)$ due to Lemma 4.1. Either way, we have a contradiction between item [ii] and Lemma 3.13. □
Lemma 4.4. Let \( \Sigma \) be a local minimizer for a compact set \( M \subset \mathbb{R}^2 \) and \( r > 0 \) and let \( x \in \Sigma \). Let \( \Sigma_1 \) be a connected component of \( \Sigma \setminus \{x\} \) with one-sided tangent \( \{ax\} \) and let \( \bar{x} \in \Sigma_1 \\

1. For any one-sided tangent \( (\bar{a}x) \) of \( \Sigma \) at \( \bar{x} \) the equality \( \angle((\bar{a}x),(ax)) = o_{\|x\|}(1) \) holds.

2. Let \( (\bar{a}x) \) be a one-sided tangent at \( \bar{x} \) of any connected component of \( \Sigma \setminus \{\bar{x}\} \) not containing \( x \). Then \( \angle((\bar{a}x),(ax)) = o_{\|x\|}(1) \).

Proof. First, note that if \( x \notin E_\Sigma \), then, due to Remark 2.8 and Proposition 3.14 there is \( \rho > 0 \) such that \( \Sigma_1 \cap B_\rho(x) \subset \{ax\} \), and claims of the lemma are true. Thus we can assume that \( x \in E_\Sigma \).

1. Assume the contrary, i.e. there exists some positive \( c < \pi/2 \) and a sequence \( x_k \in \Sigma_1 \) such that \( x_k \to x \) and \( \angle((a_kx_k),(ax)) \geq c \) for any \( k \), where \( (a_kx_k) \) is some one-sided tangent of \( \Sigma \) at \( x_k \). In view of Lemma 4.1 and Theorem 4.3, we can assume that there are no branching points and no non-isolated energetic points in the sequence \( x_k \). Then, in view of item 1 of Proposition 3.10, we can assume that each \( (a_kx_k) \) is a one-sided tangent of a connected component of \( \Sigma \setminus \{x_k\} \) not containing \( x \).

Given \( x_k \) for a sufficiently big \( k \), we build a polygonal chain \( l_1 - l_2 - l_3 - l_4 - l_5 \) as follows: set \( l_1 := x_k \) if \( x_k \in X_{\Sigma} \), otherwise note that \( (b_kx_k), x_k \), where \( a_kx_k = b_kx_k \), is the one-sided tangent of \( \Sigma(x_k,x) \) at \( x_k \), let \( \delta > 0 \) be maximal possible such that \( ((b_kx_k) \cap B_{\delta}(x_k)) \subset \Sigma(x_k,x) \), and choose \( l_1 \) as the unique point in \( (b_kx_k) \cap \partial B_{\delta}(x_k) \). Note that in the latter case \( l_1 \neq x \) as \( \angle((x_kl_1),(ax)) = \angle((a_kx_k),(ax)) \geq c \). In either case, \( l_1 \in X_{\Sigma} \).

Now, given \( l_i \in X_{\Sigma} \) for \( 1 \leq i \leq 4 \), let \( (bl_i) \) be the one-sided tangent of \( \Sigma(l_i,x) \) at \( l_i \), let \( \delta > 0 \) be maximal possible such that \( ((bl_i) \cap B_{\delta}(l_i)) \subset \Sigma(l_i,x) \), and choose \( l_{i+1} \) as the unique point in \( (bl_i) \cap \partial B_{\delta}(l_i) \). Due to item 1 of Proposition 3.10, \( \angle((l_il_{i+1}),(ax)) \geq c - o_{\|x\|}(1) \), so \( l_{i+1} \neq x \) if \( k \) is big enough.

We have shown that for any sufficiently big \( k \) there exists a polygonal chain \( l_1 - l_2 - l_3 - l_4 - l_5 \subset \Sigma_1 \) such that \( l_i \in X_{\Sigma} \), \( \operatorname{ord}_l \Sigma = 2 \) for \( 1 \leq i \leq 5 \), and \( \angle((l_il_{i+1}),(ax)) \geq c - o_{\|x\|}(1) \) for \( 1 \leq i \leq 4 \). This is a contradiction with Proposition 1.2.

2. Assume the contrary, then there exists \( c > 0 \) and \( \bar{x} \in \Sigma_1 \) such that \( \|\bar{x}\| \) is arbitrarily small and \( \angle((\bar{a}x),(ax)) \geq c \). Let \( (\bar{b}\bar{x}) \) be the one-sided tangent of a connected component of \( \Sigma \setminus \{\bar{x}\} \) not containing \( x \). Due to item 1 we have \( \angle((\bar{a}x),(ax)) \geq \pi - o_{\|x\|}(1) \). Let \( (\bar{b}\bar{x}) \) be the one-sided tangent of \( \Sigma(\bar{x},x) \) at \( \bar{x} \).

It follows that \( \bar{x} \) is not the farthest from \( x \) point in \( \Sigma(\bar{x},x) \); let \( x' \neq \bar{x} \) be the farthest from \( x \) point in \( \Sigma(\bar{x},x) \). Let \( (a'_x x') \) and \( (a'_x x') \) be one-sided tangents of \( \Sigma(\bar{x},x') \) and \( \Sigma(x',x) \) at \( x' \) respectively. Since \( x' \) is farthest from \( x \) in \( \Sigma(\bar{x},x) \), we have \( \angle((a'_x x'),(ax)) = \angle((a'_x x'),(ax)) \geq \pi/2 \) for \( i \in \{1,2\} \). On the other hand, due to Corollary 3.8, \( \angle((a'_x x'),(ax)) = o_{\|x\|}(1) \) for \( i \in \{1,2\} \), so \( \angle((a'_x x'),(ax)) \geq \pi - o_{\|x\|}(1) \), which contradicts item 1 of Corollary 3.8.

\( \square \)

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