Boundary value problems for Dirac–type equations, with applications

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Abstract

We prove regularity for a class of boundary value problems for first order elliptic systems, with boundary conditions determined by spectral decompositions, under coefficient differentiability conditions weaker than previously known. We establish Fredholm properties for Dirac-type equations with these boundary conditions. Our results include sharp solvability criteria, over both compact and non-compact manifolds; weighted Poincaré and Schrödinger-Lichnerowicz inequalities provide asymptotic control in the non-compact case. One application yields existence of solutions for the Witten equation with a spectral boundary condition used by Herzlich in his proof of a geometric lower bound for the ADM mass of asymptotically flat 3-manifolds.

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1 Introduction

Elliptic systems based on the Dirac equation arise frequently in problems in geometry and analysis. Applications to positive mass and related conjectures in general relativity motivate this paper, and involve boundary value problems on compact and non-compact domains [31, 37, 38, 64].

Previous existence and regularity results [6, 12, 16, 40, 50] are insufficient for these applications, for various reasons. The Agmon-Douglas-Nirenberg approach based on freezing coefficients and explicit kernels for the constant coefficient inverse operator, leads only to boundary conditions of Lopatinski-Shapiro type [44]. The pseudo-differential operator approach [40, 56] handles non-local boundary conditions such as the spectral projection condition of Atiyah-Patodi-Singer [6], but the assumptions of smooth coefficients and product-type boundary metric [6, 12, 16, 40] are unnatural and, as we shall show, unnecessary.

In this paper we provide an essentially elementary proof of existence and regularity for first order elliptic systems with “Dirac-type” boundary value conditions. These encompass both pointwise (Lopatinski-Shapiro) and non-local (spectral) boundary conditions, and do not require product metric structures on the boundary. We obtain explicit necessary and sufficient conditions which ensure the solvability of natural inhomogeneous boundary value problems, over both compact and non-compact manifolds with compact boundary.

The coefficient regularity conditions, for both the elliptic system and the boundary conditions, are rather general. For example, they are weaker than those in the pseudo-differential operator approach of Marschall [48]. It seems likely that the boundary conditions will admit some generalizations; the boundary data is $H^{1/2}$ whereas there are recent results for a certain constant coefficient Dirac equation with $L^2$ boundary values on a Lipschitz hypersurface [1].

Note that there is an extensive literature on applications of Dirac operators to index problems on compact and non-compact manifolds [12, 18] which we do not address, although many aspects of our results are no doubt relevant to such
applications; the results here are focussed on applications to energy theorems in general relativity.

The motivating example of the Dirac (Atiyah-Singer) operator is described in some detail in §2, where the Schrödinger-Lichnerowicz identity with suitable boundary conditions combines with a Lax-Milgram argument to reduce the existence question to that of showing that a weak ($L^2$) solution of an adjoint problem is in fact a strong ($H^1$) solution. This weak-strong regularity property turns out to be the key technical step, and the focus of much of the paper. The difficult case is regularity at the boundary; interior regularity is established in §3 using standard Fourier techniques, for general first order elliptic systems.

§4 reviews conditions under which a symmetric operator has a complete set of eigenfunctions; these are used to control the boundary operator in later sections. In §5 we prove regularity results at the boundary, for a class of operators much broader than Dirac equations, with weak assumptions on the continuity/regularity of the operator coefficients. The main technical tools are the $H^1$ identity (5.15), and some basic spectral theory. The boundary conditions of §5 follow from the requirements of the arguments of the regularity theorem, and some additional work is required to apply them to first order systems. This is carried out in §6, for equations of Dirac-type near the boundary, for which the boundary operator is self-adjoint. The resulting boundary conditions are naturally presented in terms of graphs over the space of negative eigenfunctions of the boundary operator.

The boundary value problems considered have a Fredholm property, and admit an explicit solvability criteria involving solutions of the homogeneous adjoint problem. These properties are established for compact manifolds with boundary in §7, and for a large class of non-compact manifolds with boundary in §8. The analysis of the non-compact case relies on two a priori inequalities: a weighted Poincaré inequality, and a Schrödinger-Lichnerowicz inequality. These inequalities imply the manifold is non-parabolic at infinity in the sense of [18]. The weighted Poincaré inequality is established in §9 in a number of cases, including the important cases of manifolds with asymptotically flat or hyperbolic ends. The Schrödinger-Lichnerowicz inequality follows in applications from an $H^1$ estimate derived from an identity of Schrödinger-Lichnerowicz type.

In section 10 we show that common pointwise and spectral boundary conditions for the Dirac equation are elliptic in the sense of our conditions. These calculations form the basis for §11, which verifies several positive mass theorems [31, 37, 64]. Appendix A collects some relevant properties of tensor and spinor fields on manifolds with $W^{k+1,p}$ differentiable structure and $W^{k,p}$ metric, $k > n/p$.

## 2 The model problem

In this section we use the Riemannian Dirac equation to illustrate and motivate the existence and regularity results of the following sections.

Consider an oriented manifold $M$ with Riemannian metric $g$ and a representation $c : Cl(TM) \to \text{End}(S)$ of the Clifford algebra $Cl(TM)$ on some bundle
which satisfies the compatibility relation
\[ c(v)c(w) + c(w)c(v) = -2g(v,w) . \]

Clifford representations are discussed in detail in [5, 45]. S carries an invariant inner product, \( \langle c(v)\psi, c(v)\psi \rangle = |v|^2 \langle \psi, \psi \rangle = |v|^2 |\psi|^2 \), with respect to which \( c(v) \) is skew-symmetric, for all vectors \( v \).

A Dirac connection [12, 45] is a connection on the space of sections of \( S \) which satisfies the compatibility relation
\[ d\langle \phi, c(v)\psi \rangle = \langle \nabla \phi, c(v)\psi \rangle + \langle \phi, c(v)\nabla \psi \rangle + \langle \phi, c(\nabla v)\psi \rangle , \tag{2.1} \]
where \( \nabla \) also denotes the Levi-Civita connection on vector fields.

Spin manifolds provide the fundamental example, with \( S \) a bundle of spinors associated with a Spin principal bundle which double covers the Riemannian orthonormal frame bundle. In this case there is a covariant derivative \( \nabla \) defined in terms of a local orthonormal frame \( e_k \), \( k = 1, \ldots, n \), with Riemannian connection matrix \( \omega_{ij}(e_k) = g(e_i, \nabla e_j) \), by
\[ \nabla_{e_k} \psi = D_{e_k} \psi^I \phi_I - \frac{1}{4} \psi^I \omega_{ij}(e_k)c(e^i e^j)\phi_I , \tag{2.2} \]
where \( \psi = \psi^I \phi_I \) and \( \phi_I \), \( I = 1, \ldots, \dim S \), is a choice of spin frame associated with the orthonormal frame \( e_k \). The expression (2.2) may be abbreviated to \( \nabla = d - \frac{1}{4} \omega_{ij} e^i e^j \). Note that there are other examples of Dirac bundles and connections, eg. [45, example II.5.8].

The Dirac operator of a Dirac connection \( \nabla \) is
\[ D\psi = c(e^i)\nabla_{e_i} \psi ; \tag{2.3} \]
in the spin case this is sometimes called the Atiyah-Singer operator. When the spinor representation is irreducible\(^1\), a classical and very important computation [55] shows that
\[ D^2\psi = \nabla^* \nabla \psi + \frac{1}{4} R(g)\psi , \tag{2.4} \]
where \( R(g) \) is the (Ricci) scalar curvature of \( g \). This leads to the Schrödinger-Lichnerowicz identity [46, 55]
\[ (|\nabla \psi|^2 + \frac{1}{4} R(g)|\psi|^2 - |D\psi|^2) \ast 1 = d \left( \langle \psi, (c(e_i e_j) + g_{ij})\nabla^j \psi \rangle \ast e^i \right) , \tag{2.5} \]
which when integrated over the compact manifold \( M \) with boundary\(^2\) \( Y \) becomes
\[ \int_M \left( |\nabla \psi|^2 + \frac{1}{4} R(g)|\psi|^2 - |D\psi|^2 \right) = \oint_Y \langle \psi, c(ne^A) \nabla_A \psi \rangle . \tag{2.6} \]
Here \( n \) is the outer normal vector at \( Y = \partial M \) and \( \{ e_A \} \) is a compatible orthonormal frame on \( Y \). The boundary term may be simplified by introducing the boundary covariant derivative
\[ \nabla = d - \frac{1}{4} \omega_{ABC}(e^A e^B) , \]

\(^1\)Reducible representations lead to interesting formulas with \( \frac{1}{4} R(g) \) replaced by more complicated curvature endomorphisms, c.f. §11

\(^2\)Throughout this paper we use the geometer’s convention, that a manifold with boundary contains its boundary as a point set.
and the boundary Dirac operator\(^3\)

\[ D_Y \psi = c(ne^A) \nabla_A \psi . \quad (2.7) \]

Denoting the mean curvature by \( H = H_Y = g(n, \nabla e_A e^A) \) gives

\[
\oint_Y \langle \psi, c(ne^A) \nabla_A \psi \rangle = \oint_Y \langle \psi, D_Y \psi + \frac{1}{2} H \psi \rangle .
\]  \((2.8)\)

We use conventions which give \( H = 2/r > 0 \) for \( M = \mathbb{R}^3 - B(0, r) \), the exterior of a ball of radius \( r \), with the outer normal \( n = -\partial_r \). If \( x \) is a Gaussian boundary coordinate \((x \geq 0 \text{ in } M, x = 0 \text{ on } Y \text{ and } \partial_x = -n)\), then near the boundary we have

\[ D\psi = -c(n)(\partial_x + D_Y + \frac{1}{2} H)\psi . \quad (2.9) \]

We now seek boundary conditions for which the equation \( D\psi = f \) is solvable, following a well-known argument \([32, 37, 51]\). Suppose \( M \) is a compact 4 manifold with non-negative scalar curvature, \( R(g) \geq 0 \), and \( K : H^{1/2}(Y) \to H^{1/2}(Y) \) is a bounded linear operator such that

\[
\oint_Y \langle \psi, D_Y \psi + \frac{1}{2} H \psi \rangle \leq 0 \quad \text{whenever } K\psi = 0 . \quad (2.10)
\]

Suppose further that \( M \) admits no parallel spinors. Define the space \( H^1_K(M) \) as the completion of the smooth spinor fields with compact support (in \( M \cup Y \)) which satisfy the boundary condition \( K\psi = 0 \), in the norm

\[ \|\psi\|^2_{H^1_K(M)} := \int_M (|\nabla \psi|^2 + \frac{1}{4} R(g)|\psi|^2) . \quad (2.11) \]

The boundary condition (2.10) combined with the Lichnerowicz identity (2.6) and the curvature condition \( R(g) \geq 0 \) now ensures that the bilinear form

\[ a(\psi, \phi) = \int_M \langle D\psi, D\phi \rangle, \quad \phi, \psi \in H^1_K(M) , \]

is strictly coercive, \( a(\psi, \psi) \geq \|\psi\|^2_{H^1_K(M)} \). For any spinor field \( f \in L^2(M) \), the linear functional \( \phi \mapsto \int_M \langle f, D\phi \rangle \) is bounded on \( H^1_K(M) \). Coercivity and the Lax-Milgram lemma show there is a unique \( \psi \in H^1_K(M) \) such that

\[ \int_M \langle D\psi - f, D\phi \rangle = 0 \quad \forall \phi \in H^1_K(M) , \]

and we would like to deduce that \( D\psi = f \). Now \( \Psi := D\psi - f \in L^2(M) \) is a weak solution of the Dirac equation; that is,

\[ \int_M \langle \Psi, D\phi \rangle = 0 \quad \forall \phi \in H^1_K(M) . \quad (2.12) \]

\(^3\)Both \( e^A \to c(e^A) \) and \( e^A \to c(ne^A) \) give representations of the Clifford algebra of the boundary tangent space; the choice of \( c(ne^A) \) is made here for convenience \([37]\).

\(^4\)The case of an \((M, g)\) which is asymptotically flat with compact interior, which is relevant to the positive mass theorem, is discussed along similar lines in §8 and 11.
If we could show that $\Psi$ is in fact a strong solution, that is, $\Psi \in H^1(M)$, then we could integrate by parts to conclude
\[
\int_M \langle D\Psi, \phi \rangle + \oint_Y \langle \Psi, c(n)\phi \rangle = 0 \quad \forall \phi \in H^1_K(M),
\]
and thus $D\Psi = 0$ and $\oint_Y \langle \Psi, c(n)\phi \rangle = 0$ for all $\phi \in H^{1/2}(Y)$ such that $K\phi = 0$. This would give the boundary condition $\Psi|_Y \in c(n)(\ker K)^\perp$, which we suppose may be re-expressed as $\tilde{K}\Psi = 0$, for some “adjoint” boundary operator $\tilde{K}$. This would give $\Psi \in H^1_{\tilde{K}}$, so if finally we suppose that $\tilde{K}$ also satisfies the boundary positivity condition (2.10), then we could conclude from $a(\Psi, \Psi) = 0$ and the coercivity of $a(\cdot, \cdot)$ with respect to the norm $\| \cdot \|_{H^1_{\tilde{K}}}$, that $\Psi = 0$ as desired.

The key technical difficulty in this classical argument lies in establishing the “Weak-Strong” property, that weak $(L^2)$ solutions lie in $H^1$. In the following sections we will prove this property for a large class of elliptic systems, under rather general boundary conditions; see §5 and §6.

Two model boundary operators illustrate the possibilities for achieving the required conditions. The $APS$ (or spectral projection [6]) condition arose in Herzlich’s work [37]:
\[
K = P_+, \tag{2.13}
\]
where $P_+$ is the $L^2(M)$-orthogonal projection onto the positive spectrum eigenspace of the boundary Dirac operator $D_Y$. Using the relation $c(n)D_Y = -D_Yc(n)$, which shows that the spectrum of $D_Y$ is symmetric about $0 \in \mathbb{R}$, we find that $\tilde{K} = K$, provided there are no zero eigenvalues.

The eigenvalue estimate for $Y \simeq S^2$ of Hijazi and Bär [7, 39]
\[
|\lambda(D_Y)| \geq \sqrt{4\pi/\text{area}(Y)}, \tag{2.14}
\]
shows that in this case there are no zero eigenvalues. In addition, if we have the mean curvature condition

\[
H_Y \leq \sqrt{16\pi/\text{area}(Y)}, \tag{2.15}
\]
then $K$ (and $\tilde{K}$) will satisfy the boundary positivity condition (2.10). In conclusion, if $Y = \partial M \simeq S^2$ satisfies (2.15), then (assuming the Weak-Strong property can be established) the above argument shows $\Psi = 0$ and thus the equation $D\Psi = f$ with boundary condition $P_+\Psi = 0$ is uniquely solvable, for any $f \in L^2(M)$.

The chirality condition was used in [30, 31]. For a slightly simplified version of [31], suppose $M$ is a totally geodesic hypersurface in a Lorentz spacetime, with future unit normal vector $e_0$, and consider the connection on spacetime spinors, restricted to $M$. Along $Y = \partial M$ we define
\[
\epsilon = c(e_0 n), \tag{2.16}
\]
which satisfies the chiral conditions
\[
\epsilon^2 = 1, \quad \epsilon c(n) + c(n)\epsilon = 0, \quad \epsilon D_Y + D_Y\epsilon = 0, \tag{2.17}
\]
and then the boundary operators

\[ \mathcal{K}_\pm = \frac{1}{2}(1 \pm \epsilon). \]  

(2.18)

Assuming either of the two conditions \( \mathcal{K}_\pm \psi = 0 \) gives \( \epsilon \psi = \mp \psi \) which implies

\[ \langle \psi, D_Y \psi \rangle = \mp \langle \psi, D_Y \epsilon \psi \rangle = \pm \langle \psi, \epsilon D_Y \psi \rangle = \pm \langle \epsilon \psi, D_Y \psi \rangle = -\langle \psi, D_Y \psi \rangle = 0. \]

If we further assume that \( H_Y \leq 0 \) then (2.10) follows directly. In general relativity the condition \( H_Y \leq 0 \) is the defining property for \( Y \) to be a trapped surface.

Since the \( \mathcal{K}_\pm \)'s are complementary orthogonal projections, we have \( (\ker \mathcal{K}_\pm)^\perp = \ker \mathcal{K}_\mp \), so \( \psi \in \mathcal{C}(n)(\ker \mathcal{K}_\pm)^\perp \) exactly when \( \mathcal{C}(n) \psi \in \ker \mathcal{K}_\mp \), and \( \mathcal{K}_\mp = \mathcal{K}_\pm \). In this case we conclude (still assuming the Weak-Strong property can be established) that if \( H_Y \leq 0 \) then \( D \psi = f \), with either of the boundary conditions \( \epsilon \psi = \pm \psi \), is uniquely solvable. These examples are discussed further in §10.

3 Interior Regularity

In this section we establish regularity away from the boundary for weak \((L^2)\) solutions of first order elliptic systems. We consider equations of the form

\[ Lu := a^j \partial_j u + bu = f, \]  

(3.1)

where \( u, f \) are sections respectively of \( N \)-dimensional real vector bundles \( E, F \), both over an \( n \)-dimensional manifold \( M \) without boundary, and \( a^j, b, j = 1, \ldots, n \), are sections of the bundle of endomorphisms of \( E \) to \( F \). We assume that \( E, F \) are equipped with fixed smooth inner products, denoted by \( \langle \cdot, \cdot \rangle \). The length determined by \( \langle \cdot, \cdot \rangle \) will be denoted invariably by \( |u|^2 = \langle u, u \rangle \). To simplify notation, the respective bundles usually will be understood, and thus \( L^2(M) \) will generally mean \( L^2(\Gamma(E)) \), the space of \( L^2 \) sections of \( E \), or \( L^2(\Gamma(F)) \), depending on context.

Remark 3.1 There is no loss of generality in considering real bundles, since complex and quaternionic bundles may be viewed simply as real bundles with additional algebraic structure. For example, a Hermitean vector space of dimension \( n \) is equivalent to a real vector space of dimension \( 2n \) with a skew endomorphism \( J \) satisfying \( J^2 = -1 \), with the Hermitean inner product \( \langle \cdot, \cdot \rangle \) and real inner product \( \langle \cdot, \cdot \rangle \) related by \( \langle u, v \rangle = \langle u, v \rangle - i\langle u, Jv \rangle \).

Define the indices \( \hat{2} = 2(n), n^* = n^*(n) \) by

\[
\hat{2} = \begin{cases} 
2n, & \text{for } n \geq 3, \\
10^6, & \text{for } n = 2, \\
\infty, & \text{for } n = 1,
\end{cases}
\]

\[ n^* = \begin{cases} 
2, & \text{for } n = 1, \\
\frac{1}{2}, & \text{for } n = 2, \\
\frac{2}{1-2/2}, & \text{for } n \geq 3.
\end{cases}
\]

If \( M \) has boundary \( \partial M \neq \emptyset \), then the interior \( \tilde{M} = M - \partial M \) is a (noncompact) manifold without boundary, to which the results of this section will apply.
where $10^6$ represents any large constant. Note that if $M$ admits a Sobolev inequality with constant $C_S$

$$\|u\|_{L^2} \leq C_S \|u\|_{H^1},$$

then we also have

$$\|fu\|_{L^2} \leq C_S \|f\|_{L^n} \|u\|_{H^1}. \quad (3.3)$$

Another basic fact is the inequality

$$\|fg\|_{W^{1,p}} \leq C \left( \|f\|_{L^\infty} \|g\|_{W^{1,p}} + \|g\|_{L^\infty} \|f\|_{W^{1,p}} \right),$$

which shows that $W^{1,n^*} \cap C^0$ (in particular) forms a ring under addition and multiplication of functions. For $n = 1, 2$ the $C^0$ is superfluous here, of course.

With one exception, it suffices to assume throughout that the underlying manifold has a $C^\infty$ differentiable structure. The exceptional point arises in §10 in the construction of approximately Gaussian coordinates in a neighbourhood of the boundary, when the metric has low regularity. The description in Appendix A of $W^{k+1,p}$ differential structures, $k > n/p$, establishes the necessary consistency conditions in this case.

We will assume that $a^j, b$ satisfy the regularity conditions

$$a^j \in W^{1,n^*}_{\text{loc}}(M) \cap C^0(M), \quad b \in L^{n^*}_{\text{loc}}(M). \quad (3.4)$$

The conditions (3.4) are preserved by bundle frame changes in $W^{1,n^*} \cap C^0$, by the above ring property. In particular, even if the bundle metrics $\langle \cdot, \cdot \rangle$ on $E, F$ are only in $W^{1,n^*} \cap C^0$, by the Gram-Schmidt process we may construct $W^{1,n^*} \cap C^0$ frame changes which make the metric coefficients constant. Since this changes the operator coefficients $a^j, b$ respectively by $W^{1,n^*} \cap C^0, W^{n^*}$ affine linear transformations, there is no loss of generality in assuming the metrics on $E, F$ to be locally constant.

The conditions (3.4) mean that $M$ can be covered by open neighbourhoods $\mathcal{O}_\alpha$ with $W^{1,n^*} \cap C^0$ bundle transition functions, such that the local coefficients $a^j, b$ satisfy the stated regularity. Frame changes satisfying Sobolev conditions are also discussed in detail in Appendix A.

We require that $a^j$ satisfy the ellipticity condition, that for each $p \in M$ there is a coordinate neighbourhood $p \in U \subset M$ and a constant $\eta > 0$ such that

$$\eta^2 |\xi|^2 |V|^2 \leq |\xi_j a^j(x)V|^2 \leq \eta^{-2} |\xi|^2 |V|^2, \quad (3.5)$$

for all $x \in U, \xi \in T^*_xM$ and $V \in E_x$, where $|\xi|^2$ is measured by a fixed background metric $\hat{g}$, which we may assume to be $C^\infty$. Note that (3.5) implies the fibres of $E, F$ must be of the same dimension.

A weak solution of (3.1) is $u \in L^2_{\text{loc}}(E)$ such that

$$\int_M \langle L^\dagger \phi, u \rangle \, dv_M = \int_M \langle \phi, f \rangle \, dv_M, \quad (3.6)$$
for all $\phi \in C^\infty_c(M)$, where $dv_M = \gamma dx$, $\gamma > 0$, is a coordinate-invariant volume measure on $M$ with $\gamma \in W^{1,n}(U) \cap C^0(U)$ and $dx$ is coordinate Lebesgue measure, in any local coordinate neighbourhood $U$. Here the formal adjoint $L^\dagger$ is defined with respect to $dv_M$ and the inner products on $E,F$. Thus in local coordinates,

$$L^\dagger \phi = -a^i \partial_i \phi + \langle b - \gamma^{-1} \partial_j (a^i \gamma) \rangle \phi,$$

(3.7)

where the transposes $a^i$ are defined with respect to the local framing forms of the inner products of $E,F$.

The proof proceeds by establishing various special cases, starting with a constant coefficient operator acting on sections of a trivial bundle $E$ over the torus $\mathbb{T}^n$. This type of argument is very standard.

**Proposition 3.2** Suppose $u \in L^2(\mathbb{T}^n)$ is a weak solution of $L_0 u = f$ where $f \in L^2(\mathbb{T}^n)$, $L_0 = a^j_0 \partial_j$ with $a^j_0$ constant and satisfying the ellipticity condition (3.5). Then $u \in H^1(\mathbb{T}^n)$.

**Proof:** We regard $\mathbb{T}^n = \mathbb{R}^n / \mathbb{Z}^n$. Fix a mollifier $\phi_\epsilon = \epsilon^{-n} \phi((x-y)/\epsilon) \in C^\infty(\mathbb{R}^n)$ with $\phi(-x) = \phi(x)$, and set $u_\epsilon = \phi_\epsilon \ast u \in C^\infty(\mathbb{T}^n)$. Then

$$L_0 u_\epsilon = \int_{\mathbb{T}^n} a^j_0 \frac{\partial}{\partial x^j} \phi_\epsilon(x-y)u(y) \, dy$$

and thus the definition of weak solution gives

$$\int_{\mathbb{T}^n} \langle \psi, L_0 u_\epsilon \rangle \, dx = \int_{\mathbb{T}^n} \int_{\mathbb{T}^n} \phi_\epsilon(x-y) \langle L_0^\ast \psi(x), u(y) \rangle \, dy \, dx$$

$$= \int_{\mathbb{T}^n} \int_{\mathbb{T}^n} \langle \phi_\epsilon \ast \frac{\partial}{\partial y^j} \psi(y-x), u(y) \rangle \, dy \, dx$$

$$= \int_{\mathbb{T}^n} \langle L_0^\ast (\phi_\epsilon \ast \psi)(y), u(y) \rangle \, dy$$

$$= \int_{\mathbb{T}^n} \langle \phi_\epsilon \ast \psi(y), f(y) \rangle \, dy$$

$$= \int_{\mathbb{T}^n} \langle \psi(y), \phi_\epsilon \ast f(y) \rangle \, dy.$$

Thus $L_0 u_\epsilon = f_\epsilon = \phi_\epsilon \ast f$, and we note that $f_\epsilon \to f$ strongly in $L^2$. Now the ellipticity condition (3.5) and the Plancherel theorem ensure that for all $v \in H^1(\mathbb{T}^n)$,

$$\int_{\mathbb{T}^n} |\partial v|^2 \, dx \leq \int_{\mathbb{T}^n} |\xi|^2 |\hat{\psi}|^2 \, d\xi$$

$$\leq \eta^{-1} \int_{\mathbb{T}^n} |a^j_0 \xi_j \hat{\psi}|^2 \, d\xi$$

$$= \eta^{-1} \int_{\mathbb{T}^n} |L_0 v|^2 \, dx,$$

and thus

$$\int_{\mathbb{T}^n} |\partial u_\epsilon|^2 \, dx \leq \eta^{-1} \int_{\mathbb{T}^n} |f_\epsilon|^2 \, dx.$$

Since $u,f \in L^2$, it follows that $u_\epsilon \to u$ strongly in $H^1$. 


PROPOSITION 3.3 Under the conditions of Proposition 3.2, the map \( \mathcal{L}_0 + \lambda : H^1(\mathbb{T}^n) \rightarrow L^2(\mathbb{T}^n) \) where \( \lambda = \pi \eta \), is uniquely invertible, and for all \( u \in H^1(\mathbb{T}^n) \),
\[
\|u\|_{H^1} \leq \sqrt{5/\eta} \|(\mathcal{L}_0 + \lambda)u\|_{L^2}.
\] (3.8)

PROOF: Write \( u = \sum_{k \in \mathbb{Z}^n} u_k e^{2\pi i k \cdot x} \), where the coefficients \( u_k = \int_{\mathbb{T}^n} u(x) e^{-2\pi i k \cdot x} \, dx \) are valued in \( \mathbb{C}^N \), the complexification of the real vector space modelling the fibres of \( E \). We then have
\[
\int_{\mathbb{T}^n} |(\mathcal{L}_0 + \lambda)u|^2 \, dx = \sum_{k \in \mathbb{Z}^n} |(2\pi i k \cdot a_0^i + \lambda)u_k|^2,
\]
and using the vector length inequality \(|a + b|^2 \geq \chi|a|^2 - \chi/(1 - \chi)|b|^2\) with \( \chi = 1/2 \), we find
\[
|(2\pi i k \cdot a_0^i + \lambda)u_k|^2 \geq \frac{1}{2}|2\pi i k \cdot a_0^i u_k|^2 - \lambda^2|u_k|^2.
\]
For \( k \neq 0 \) this is greater than \( \pi^2 \eta^2 |u_k|^2 \), whilst for \( k = 0 \) we have \( |(2\pi i k \cdot a_0^i + \lambda)u_k|^2 = \lambda^2 |u_k|^2 = \pi^2 \eta^2 |u_k|^2 \), hence
\[
\int_{\mathbb{T}^n} |(\mathcal{L}_0 + \lambda)u|^2 \, dx \geq \sum_{k \in \mathbb{Z}^n} \pi^2 \eta^2 |u_k|^2 = \pi^2 \eta^2 \int_{\mathbb{T}^n} |u|^2 \, dx,
\]
which shows \( \mathcal{L}_0 + \lambda \) has trivial kernel. Choosing \( \chi = 1 - 1/(2|k|) \) shows in fact that
\[
|(2\pi i k \cdot a_0^i + \lambda)u_k|^2 \geq \pi^2 \eta^2 (2|k| - 1)|u_k|^2,
\]
for all \( k \in \mathbb{Z}^n \) and all \( u_k \in \mathbb{C}^N \). Since \( 2|k| - 1 \geq 1 \) for all \( k \in \mathbb{Z}^n \), we obtain (3.8). Moreover, this shows also that the \( N \times N \) complex matrices \( 2\pi i k \cdot a_0^i + \lambda \) are invertible for any \( k \in \mathbb{Z}^n \), which gives a direct construction of the inverse of the operator \( \mathcal{L}_0 + \lambda \).

THEOREM 3.4 Suppose \( u \in L^2(\mathbb{T}^n) \) is a weak solution of
\[
\mathcal{L}_0 u + B_0 u + B_1 u = f
\] (3.9)
where \( f \in L^2 \) and \( \mathcal{L}_0 = a_0^i \partial_j \) is a constant coefficient first order operator satisfying the conditions of Proposition 3.3 with ellipticity constant \( \eta \), where \( B_1 : L^2 \rightarrow L^2 \) is bounded, and where \( B_0 : H^1 \rightarrow L^2 \) is a linear map satisfying
\[
\|B_0\|_{H^1 \rightarrow L^2} \leq \eta/3, \quad \|B_0^\dagger\|_{H^1 \rightarrow L^2} \leq \eta/3,
\] (3.10)
where \( B_0^\dagger \) is the \( L^2(\mathbb{T}^n) \)-adjoint of \( B_0 \). Then \( u \in H^1(\mathbb{T}^n) \) is a strong solution of (3.9), and there is a constant \( C \), depending only on \( \eta \) and \( \|B_1\|_{L^2 \rightarrow L^2} \), such that
\[
\|u\|_{H^1} \leq C (\|f\|_{L^2} + \|u\|_{L^2}).
\] (3.11)
Proof: Construct the iteration sequence \( w^{(k)} \in H^1, k = 0, 1, \ldots \) by defining \( w^{(k+1)} \) to be the solution of

\[
(L_0 + \lambda)w^{(k+1)} = -B_0w^{(k)} + \tilde{f},
\]

with \( w^{(0)} = 0 \), where \( \tilde{f} = f + \lambda u - B_1u \in L^2 \) by the assumptions. This equation with \( \lambda = \pi \eta \) is uniquely solvable by Proposition 3.3. The difference \( v^{(k+1)} = w^{(k+1)} - w^{(k)} \) satisfies \( (L_0 + \lambda)v^{(k+1)} = -B_0v^{(k)} \) and the estimate (3.8) shows that

\[
\frac{\eta}{\sqrt{5}} \|v^{(k+1)}\|_{H^1} \leq \|B_0v^{(k)}\|_{L^2} \leq \frac{\eta}{3} \|v^{(k)}\|_{H^1}.
\]

The iteration is thus a contraction and converges in \( H^1 \), to \( w \in H^1 \) satisfying \( (L_0 + B_0 + \lambda)w = f \), and then \( v = u - w \in L^2 \) is a weak solution of \( (L_0 + B_0 + \lambda)v = 0 \). Now \( L_0^t \) is also elliptic with the same ellipticity constant \( \eta \), so there is \( z \in H^1 \) satisfying \( (L_0^t + B_0^t + \lambda)z = v \). Since \( v \) is a weak solution,

\[
\int_{\mathbb{T}^n} \langle (L_0^t + B_0^t + \lambda)\phi, v \rangle \, dx = 0 \quad \forall \phi \in H^1(\mathbb{T}^n),
\]

we may test with \( \phi = z \) to see that \( \int |v|^2 = 0 \) and \( v = 0 \). Thus \( u = v + w \in H^1 \) as required. By Proposition 3.3 and (3.10), we have

\[
\frac{\eta}{\sqrt{5}} \|u\|_{H^1} \leq \|L_0 + B_0 + B_1\|_{L^2} \|u\|_{L^2} + \|B_0\|_{L^2} \|u\|_{L^2} + \|\lambda u\|_{L^2}
\]

\[
\leq \|f\|_{L^2} + \eta \|u\|_{H^1} + (\|B_1\|_{L^2 \to L^2} + \eta \pi) \|u\|_{L^2}.
\]

Since \( \sqrt{5} < 3 \), the estimate (3.11) follows.

Next we consider operators with non-constant coefficients. Let \( C_S \) be the \( \mathbb{T}^n \) Sobolev constant

\[
\|u\|_{L^2(\mathbb{T}^n)} \leq C_S \|u\|_{H^1(\mathbb{T}^n)} ,
\]

where \( \hat{2} \) is defined in (3.2).

Proposition 3.5 Suppose \( u \in L^2(\mathbb{T}^n) \) is a weak solution of the system of equations

\[
Lu := a^j \partial_j u + bu = f
\]

where \( f \in L^2 \) and the coefficients \( a^j \in W^{1,n^*} \cap C^0, b \in L^{n^*} \) satisfy

\[
\|a^j - a_0^j\|_{L^\infty} \leq \frac{\eta}{10}
\]

\[
\|\partial_j a^j\|_{L^{n^*}} \leq \frac{\eta}{10 C_S}
\]

where \( a_0^j, j = 1, \ldots, n, \) are constant matrices with ellipticity constant \( \eta \). Then \( u \in H^1(\mathbb{T}^n) \) is a strong solution of (3.14).

Proof: It will suffice to show that \( L \) admits a decomposition satisfying the conditions of Theorem 3.4. Since \( L^\infty \) is dense in \( L^{n^*} \), for any \( \epsilon > 0 \) we may
find $b_0 \in L^{n^*}$, $b_1 \in L^\infty$, such that $b = b_0 + b_1$ and $\|b_0\|_{L^{n^*}} < \epsilon$. We choose $\epsilon = \eta/(10CS)$. Then $B_0u := b_0u + (a^j - a^j_0)\partial_j u$ satisfies

$$\|B_0u\|_{L^2} \leq \|b_0\|_{L^{n^*}} \|u\|_{L^2} + \|a^j - a^j_0\|_{L^\infty} \|\partial u\|_{L^2}.$$ 

Using (3.16) and the Sobolev inequality (3.13) gives

$$\|B_0u\|_{L^2} \leq \frac{\eta}{10}(\|u\|_{H^1} + \|\partial u\|_{L^2}) \leq \frac{\eta}{3}\|u\|_{H^1},$$

so $\|B_0\|_{H^1 \to L^2} \leq \eta/3$. Clearly $B_1u := b_\infty u$ is bounded on $L^2$, and it remains to verify the $H^1 \to L^2$ bound on the adjoint operator

$$B^*_0 w := t b_0 w - (t^a a^j - t^a a^j_0)\partial_j w - \partial_j(t^a a^j - t^a a^j_0)w.$$ 

Again using the Sobolev inequality and the conditions (3.15),(3.16) we find

$$\|B^*_0 w\|_{L^2} \leq CS\|b_0\|_{L^{n^*}} \|w\|_{H^1} + \|t^a a^j - t^a a^j_0\|_{L^\infty} \|\partial w\|_{L^2} + CS\|\partial_j a^j\|_{L^{n^*}} \|w\|_{H^1}$$

$$\leq \frac{\eta}{3}\|w\|_{H^1},$$

so the conditions of Theorem 3.4 are met and the result follows.

On a general compact manifold we define the Sobolev space $H^1(M)$ by the norm

$$\|u\|_{H^1(M)}^2 = \int_M (|\nabla u|^2 + |u|^2) \, dv_M,$$  \hfill (3.17)

where the lengths $|u|^2$, $|\nabla u|^2$ are measured using the metric $\langle \cdot, \cdot \rangle$ on sections of $E$ and a fixed smooth background metric $\hat{g}$ on $TM$, and where $\nabla$ is a (covariant) derivative defined in local coordinates on $M$ and a local framing on $E$ by

$$\nabla_i = \partial_i - \Gamma_i.$$  \hfill (3.18)

We assume the charts on $E, M$ are such that

$$\Gamma_i \in L^{n^*}_{\text{loc}}.$$  \hfill (3.19)

Note we do not require that $\nabla$ be compatible with the metric on $E$. If $M$ is compact then the space $H^1(M)$ is independent of the choice of covariant derivative:

**Lemma 3.6** Suppose $M$ is compact and $\nabla, \hat{\nabla}$ are covariant derivatives satisfying (3.19). Then there is $C > 0$ such that for all $u \in H^1(M),$

$$C^{-1} \int_M (|\nabla u|^2 + |u|^2) dv_M \leq \int_M (|\hat{\nabla} u|^2 + |u|^2) dv_M \leq C \int_M (|\nabla u|^2 + |u|^2) dv_M.$$  \hfill (3.20)

Moreover, there is a constant $C_S$, depending on $M, \nabla$, such that

$$\left( \int_M |u|^2 \, dv_M \right)^{2/3} \leq C_S \int_M (|\nabla u|^2 + |u|^2) \, dv_M.$$  \hfill (3.21)
Proof: There is a finite covering of $M$ by charts $U_\alpha$ with a corresponding partition of unity $\phi_\alpha$. Using the Sobolev inequality for $U_\alpha \subset \mathbb{R}^n$, in each chart we may estimate the localisation $u_\alpha = \phi_\alpha u$ by

$$
\int_{U_\alpha} |\partial u_\alpha|^2 \, dx \leq C \int_M (|\nabla u_\alpha|^2 + |u_\alpha|^2) \, dv_M ,
$$

where $C$ depends also on the decomposition $\Gamma = \Gamma^\infty + \Gamma^{n^*} \in L^\infty + L^{n^*}$, with $\Gamma^{n^*}$ small. Again using the $\mathbb{R}^n$ Sobolev inequality and $\Gamma, \tilde{\Gamma} \in L^{n^*}$ we have

$$
\int_M (|\nabla u|^2 + |u|^2) \, dv_M \leq C \sum_\alpha \int_{U_\alpha} (|\nabla u_\alpha|^2 + |u_\alpha|^2) \, dx
\leq C \sum_\alpha \int_{U_\alpha} (|\partial u_\alpha|^2 + |u_\alpha|^2) \, dx
\leq C \sum_\alpha \int_{U_\alpha} (|\nabla u_\alpha|^2 + |u_\alpha|^2) \, dv_M ,
$$

from which the equivalence of the norms follows easily. The Sobolev inequality follows from very similar arguments.

We may now complete the proof of interior regularity.

Theorem 3.7 Suppose $M$ is a $C^\infty$ $n$-dimensional manifold without boundary, and $E, F$ are real vector bundles over $M$, each with fibres modelled on $\mathbb{R}^N$. Suppose $u \in L^2_{\text{loc}}(M)$ is a weak solution of $Lu = f$, where $L$ is a first order operator satisfying the conditions (3.4, 3.5). Then $u \in H^1_{\text{loc}}(M)$ and $u$ is a strong solution of $Lu = f$. Moreover, if $M$ is compact there is a constant $C > 0$, depending on $a^j, b$ and $\Gamma$, such that for all $u \in H^1(M)$,

$$
\|u\|_{H^1(M)} \leq C (\|Lu\|_{L^2(M)} + \|u\|_{L^2(M)}) .
$$

Proof: Since $L$ is locally of the form $Lu = a^j \partial_j u + bu$ with $a^j \in W^{1,n^*}_{\text{loc}} \cap C^0$, $b \in L^1_{\text{loc}}$, for each $p \in M$ there is a coordinate neighbourhood $U$ and a constant $\eta > 0$ such that $\eta$ is the ellipticity constant of $a^j_0 = a^j(p)$, and with respect to the local trivialisation of $E|_U \simeq U \times \mathbb{R}^N$ we have the bounds

$$
\|a^j - a^j_0\|_{L^\infty(U)} \leq \frac{\eta}{10},
\|\partial_j a^j\|_{L^{n^*}(U)} \leq \frac{\eta}{10CS},
$$

where we assume without loss of generality that $U = Q_R = (0, R)^n$ is a cube of side length $R \leq 1$. By paracompactness there is a locally finite countable covering $\{p_\alpha, U_\alpha\}_{\alpha \in \mathbb{Z}}$ of $M$ by such charts, with a subordinate $C^\infty$ partition of unity $\{\phi_\alpha\}_{\alpha \in \mathbb{Z}}$. Noting that $\text{supp}(\phi_\alpha u) \subset Q_R$ and that $\phi_\alpha u$ satisfies

$$
\mathcal{L}(\phi_\alpha u) = \phi_\alpha f + a^j \partial_j \phi_\alpha u
$$

weakly, we see that it suffices to consider the case where $\text{supp} u \subset Q_R$. Assuming this, rescaling by $y = x/R, x \in Q_R$ and defining $\tilde{u}(y) = u(x), \tilde{f}(y) = Rf(x)$,
Thus for any $C$ for some integer $k$ and by Theorem 3.7, where the coefficients of $L$ so by the argument:

In particular we have $\tilde{b} \in L^{n^*}(\mathbb{T}^n)$ and

$$\|\tilde{a}^j - a^j_0\|_{L^\infty(\mathbb{T}^n)} = \|a^j - a^j_0\|_{L^\infty(Q_R)} \leq \eta/10,$$

$$\|\partial_y^i \tilde{a}^j\|_{L^{n^*}(\mathbb{T}^n)} \leq \|\partial_y^i a^j\|_{L^n(Q_R)} \leq \eta/10 .$$

The conditions of Proposition 3.5 are satisfied, so $\tilde{u} \in H^1(\mathbb{T}^n)$ and thus $u \in H^1_{\text{loc}}(M)$.

When $M$ is compact there is a finite covering by charts $\{p_\alpha, U_\alpha\}$, and by Theorem 3.4, in each chart we may estimate the localisation $u_\alpha = \phi_\alpha u$ by

$$\|u_\alpha\|_{H^1(U_\alpha)} \leq C_\alpha (\|L u_\alpha\|_{L^2(M)} + \|u_\alpha\|_{L^2(M)}),$$

where the $H^1(U_\alpha)$ norm uses the coordinate partial derivatives $\partial_l$ in $U_\alpha$. To estimate $\int_{U_\alpha} |\nabla u_\alpha|^2$, note that the Sobolev inequality (3.3) in $U_\alpha$ gives

$$\int_{U_\alpha} |\Gamma u_\alpha|^2 dv_M \leq C\|\Gamma\|_{L^{n^*}(U_\alpha)}^2 \int_{U_\alpha} (|\partial u_\alpha|^2 + |u_\alpha|^2) dv_M ,$$

so by the $H^1(U_\alpha)$ estimate we have

$$\|u_\alpha\|_{H^1(M)} \leq C_\alpha (\|L u_\alpha\|_{L^2(M)} + \|u_\alpha\|_{L^2(M)}),$$

for some constant $C_\alpha$ depending also on $\|\Gamma\|_{L^{n^*}(U_\alpha)}$. Since $u = \sum u_\alpha$ and $L u_\alpha = \phi_\alpha L u + \partial_j(\phi_\alpha) a^j u$, with $|\partial \phi_\alpha| \leq c$ and $|\phi_\alpha| \leq 1$, the estimate (3.22) follows easily.

The constant $C$ of (3.22) can be controlled by $\|a^j\|_{W^{1,p}}$, $\|b\|_{L^p}$ for any $p > n^*$, or by otherwise controlling the decompositions $\partial_j a^j, b \in L^\infty + L^{n^*}$.

Higher regularity follows easily from Theorem 3.7 by a standard bootstrap argument:

**Theorem 3.8** Suppose $u \in L^2_{\text{loc}}$ is a weak solution of $Lu = f$ in the situation of Theorem 3.7, where the coefficients of $Lu = f$ satisfy the regularity conditions

$$a^j \in W^{k,n^*}_{\text{loc}} \cap C^0, \ b \in W^{k,n^*}_{\text{loc}}, \ and \ f \in H^k_{\text{loc}}, \ (3.23)$$

for some integer $k \geq 1$. Then $u \in H^{k+1}_{\text{loc}}$. If $M$ is a compact manifold without boundary then there is a constant $C = C(k,\mathcal{L})$, depending on $k$ and $\|a^j\|_{W^{k,n^*}}, \|b\|_{W^{k,n^*}}$, such that

$$\|u\|_{H^{k+1}(M)} \leq C(\|f\|_{H^k(M)} + \|u\|_{H^k(M)}) . \ (3.24)$$

Thus for any $u \in L^2(M)$ such that $Lu$ (defined weakly) satisfies $Lu \in H^k(M)$, we have

$$\|u\|_{H^{k+1}(M)} \leq C(\|Lu\|_{H^k(M)} + \|u\|_{L^2(M)}) . \ (3.25)$$
Proof: For simplicity we first treat the case \( k = 1 \). Theorem 3.7 shows \( u \in H^1_{\text{loc}} \), so the vector of first derivatives \( \partial u \in L^2_{\text{loc}} \) itself is a weak solution of the system of equations

\[
\mathcal{L} \partial u + \partial (u^j) \partial_j u = \partial f - \partial (b) u.
\] (3.26)

Since \( \partial a^j \in L^n^* \) and

\[
\| \partial (b) u \|_{L^2} \leq C \| b \|_{W^{1,n^*}} \| u \|_{H^2},
\]

so \( \| \partial (b) u \|_{L^2} \) is bounded, this system satisfies the conditions of Theorem 3.7, hence \( u \in H^2_{\text{loc}} \). The general induction step applies a similar argument: if the result is established \( \forall k \leq K - 1 \), and if \( L u = f \) with coefficient conditions (3.23) with \( k = K \), then \( \partial u \) satisfies an elliptic system (3.26) of the same form with coefficient conditions (3.23) with \( k = K - 1 \), so by induction \( \partial u \in H^K(M) \) and thus \( u \in H^{K+1}(M) \) as required. The estimates (3.24), (3.25) follow easily by a similar argument and Theorem 3.7. \( \blacksquare \)

The coefficient conditions in Theorem 3.8 are not optimal in most cases. For example, if \( n = 3 \) then \( b \in W^{1,2} \) suffices to show \( u \in H^2 \) (rather than \( b \in W^{1,3} \)). This follows by interpolation,

\[
\| \partial b u \|_{L^2} \leq \| \partial b \|_{L^2} \| u \|_{L^\infty} \\
\leq \epsilon \| u \|_{H^2} + C(\epsilon, \| \partial b \|_{L^2}) \| u \|_{L^2},
\]

which shows that \( \partial b u \) may be thought of as the sum of a small second order operator, and a large bounded operator on \( L^2 \). The small operator term may be absorbed as a perturbation of \( \mathcal{L} \), and the remainder contributes to the right hand side source term.

4 Spectral Condition

In this section we review conditions under which an operator will have a complete set of eigenfunctions. These conditions will be used in §5 to analyse boundary conditions, and thus the case of most interest concerns operators on a compact manifold without boundary, and in particular the first order elliptic systems considered in §3. However, the main result, Theorem 4.1, is stated in slightly more generality, which could be used to extend the eigenfunction representation to operators on manifolds with boundary.

Let \( H \) be a closed subspace of \( W^{1,2}(Y) \), with the induced norm, where \( Y \) is a compact manifold perhaps with boundary, and as in §3, it is understood that these spaces refer to sections of a (real) vector bundle \( E \) over \( Y \).

The abstract spectral theorem for the map \( A : H \to L^2(Y) \) uses the following conditions:

(C0) \( A : H \to L^2(Y) \) is linear and bounded in the \( W^{1,2} \) topology on \( H \).

(C1) The Gårding inequality holds: there exists a constant \( C \) such that for all \( \psi \in H \) we have

\[
\| \psi \|_H^2 \leq C \int_Y (\langle A \psi, A \psi \rangle + \langle \psi, \psi \rangle) \, dv_Y.
\] (4.1)
(C2) Weak solutions are strong solutions (“elliptic regularity”): If $\phi \in L^2(Y)$ satisfies
\[ \int_Y \langle A\psi, \phi \rangle \, dv_Y = 0, \quad \forall \psi \in H, \] (4.2)
then $\phi \in H$.

(C3) $A$ is symmetric:
\[ \forall \phi, \psi \in H \quad \int_Y \langle A\phi, \psi \rangle \, dv_Y = \int_Y \langle \phi, A\psi \rangle \, dv_Y. \] (4.3)

(C4) density:
\[ H \text{ is dense in } L^2(Y). \] (4.4)

Note that in the case $\partial Y \neq \emptyset$, the space $H$ must incorporate boundary conditions, and these will play an important role in verifying (C2), as will be seen in §5.

The main result of this section is the following:

**Theorem 4.1** Under the conditions (C0)–(C4), there exists a countable orthonormal basis of $L^2$ consisting of eigenfunctions of $A$, with eigenvalues all real and having no accumulation point in $\mathbb{R}$.

**Proof:** Let $\text{Ker}(A) \subset H$ be the kernel of $A$; it is a standard fact that $\text{Ker}(A)$ is finite dimensional when the Gårding inequality holds — we give the proof for completeness. Let $\{\psi_i\}_{i=1}^I$, $I \leq \infty$, be an $L^2$–orthonormal basis of $\text{Ker}(A)$, the equation $A\psi_i = 0$ together with (4.1) shows that $\{\psi_i\}_{i=1}^I$ is bounded in $W^{1,2}$. The Rellich theorem [35, Theorem 7.22] implies that from the sequence $\psi_i$ we can extract a subsequence $\psi_{i_j}$ converging strongly in $L^2$, weakly in $W^{1,2}$. The Gårding inequality (4.1) with $\psi$ replaced by $\psi_{i_j} - \psi_{i_k}$ shows that $\psi_{i_j}$ is Cauchy in $W^{1,2}$, hence converges in norm to some $\psi \in W^{1,2}$. By continuity of $A$, condition (C0), we have $A\psi = 0$, by continuity of $L^2$ norm on $W^{1,2}$ it holds that $\|\psi\|_{L^2} = 1$, and it easily follows that $\psi \in \{\psi_i\}_{i=1}^I$. We have thus shown that $\{\psi_i\}_{i=1}^I$ is compact, which yields $I < \infty$, as desired.

Let now
\[ \hat{H} = \{ \psi \in H : \forall \phi \in \text{Ker}(A) \int_Y \langle \phi, \psi \rangle \, dv_Y = 0 \}. \]

For $\phi \in L^2$ the map $H \ni \psi \to \int_Y \langle \phi, \psi \rangle \, dv_Y \in \mathbb{R}$ is continuous in the $L^2$ topology (and therefore also in the $W^{1,2}$ topology), thus $\hat{H}$ is closed (being an intersection of closed spaces), and hence a Banach space. We note the following:

**Lemma 4.2** There exists a constant $C$ such that
\[ \forall \psi \in \hat{H} \quad \|\psi\|_{L^2} \leq C\|A\psi\|_{L^2}. \] (4.5)

**Proof:** Suppose that this is not the case, then there exists a sequence $\psi_n \in \hat{H}$ such that
\[ \|\psi_n\|_{L^2} \geq n\|A\psi_n\|_{L^2}. \] (4.6)
Rescaling \( \psi_n \) if necessary we can without loss of generality assume that \( \| \psi_n \|_{L^2} = 1 \). The inequality (4.1) shows that \( \psi_n \) is bounded in \( W^{1,2} \) norm. By the Rellich theorem [35, Theorem 7.22] we can extract a subsequence, still denoted \( \psi_n \), converging to \( \psi_\infty \in H \), weakly in \( W^{1,2} \) and strongly in \( L^2 \). Equation (4.6) shows that the sequence \( A\psi_n \) converges to zero in \( L^2 \), and (4.1) with \( \psi \) replaced with \( \psi_n - \psi_m \) shows that \( \psi_n \) is Cauchy in the \( W^{1,2} \) norm. Continuity of \( A \) and Equation (4.6) imply that \( A\psi_\infty = 0 \), and since \( A \) has no kernel on \( \hat{H} \) we obtain \( \psi_\infty = 0 \), which contradicts \( \| \psi_\infty \|_{L^2} = 1 \), and the lemma follows. ■

Returning to the proof of Theorem 4.1, define \( \text{Im}(A) \) to be the image of \( \hat{H} \) under \( A \). Then \( \text{Im}(A) \) is a closed subspace of \( L^2 \), which can be seen as follows: Let \( \psi_i \) be any sequence in \( \hat{H} \) such that the sequence \( \chi_i \equiv A\psi_i \) converges in \( L^2 \) to \( \chi_\infty \in L^2 \). The inequality (4.5) shows that \( \psi_i \) is Cauchy in \( L^2 \), which together with the Gårding inequality shows that \( \psi_i \) is Cauchy in the \( W^{1,2} \) norm. As \( \hat{H} \) is closed, it follows that there exists \( \psi_\infty \in \hat{H} \) such that \( \psi_i \) converges to \( \psi_\infty \) in the \( W^{1,2} \) norm, and the equality \( \chi_\infty = A\psi_\infty \) follows from continuity of \( A \).

Let \( \phi \in L^2 \) be any element of \( \text{Im}(A) \perp \), the \( L^2 \) orthogonal of \( \text{Im}(A) \); by definition we have

\[
\forall \psi \in H \quad \int_Y \langle \phi, A\psi \rangle \, dv_Y = 0 .
\]

The hypothesis (C2) of elliptic regularity implies that \( \phi \in H \), so we can use the symmetry of \( A \) to conclude

\[
\forall \psi \in H \quad \int_Y \langle A\phi, \psi \rangle \, dv_Y = 0 .
\]

Density of \( H \) in \( L^2 \) implies \( A\phi = 0 \), thus

\[
\text{Im}(A) \perp = \text{Ker}(A) .
\]

(4.7)

Define \( \hat{A} : \hat{H} \rightarrow \text{Im}(A) \) by \( \hat{A}\psi = A\psi \). By the definition of all the objects involved the map \( \hat{A} \) is continuous, surjective and injective, hence bijective. Let \( \hat{K} : \text{Im}(A) \rightarrow \hat{H} \) denote its inverse, then \( \hat{K} \) is continuous by the open mapping theorem. Let \( i \) be the embedding of \( W^{1,2}(Y) \) into \( L^2(Y) \); we have \( i(\hat{H}) \subset \text{Ker}(A) \perp \) which coincides with \( \text{Im}(A) \) by (4.7). It follows that for all \( \chi \in \text{Im}(A) \) we have \( i \circ \hat{K}(\chi) \in \text{Im}(A) \), so that \( i \circ \hat{K} \) defines a map of \( \text{Im}(A) \) into \( \text{Im}(A) \), which we will denote by \( K \). Now \( \hat{K} \) is continuous and \( i \) compact, which implies compactness of \( K \).

We note that \( \text{Im}(A) \) is a closed subset of the Hilbert space \( L^2 \), hence a Hilbert space with respect to the induced scalar product. The operator \( K \) is self-adjoint with respect to this scalar product, which can be seen as follows: let \( \psi_a = K\phi_a, \phi_a \in \text{Im}(A), a = 1, 2, \) thus \( \psi_a \in H \) and \( A\psi_a = \phi_a \). We then have

\[
\int_Y \langle \phi_1, K\phi_2 \rangle \, dv_Y = \int_Y \langle A\psi_1, \psi_2 \rangle \, dv_Y = \int_Y \langle \psi_1, A\psi_2 \rangle \, dv_Y = \int_Y \langle K\phi_1, \phi_2 \rangle \, dv_Y ,
\]

as desired. By the spectral theorem for compact self-adjoint operators [63] there exists a countable \( L^2 \)-orthonormal basis of \( \text{Im}(A) \) consisting of eigenfunctions of \( K \):

\[
K\phi_\alpha = \mu_\alpha \phi_\alpha ,
\]

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with eigenvalues $\mu_\alpha$ accumulating only at 0. Since $K$ is invertible we have $\mu_\alpha \neq 0$, hence

$$A \phi_\alpha = \lambda_\alpha \phi_\alpha, \quad \lambda_\alpha = \mu_\alpha^{-1}.$$  

The required basis of $L^2$ is obtained by completing $\{\phi_\alpha\}$ with any $L^2$–orthonormal basis of the finite dimensional kernel of $A$.

**Definition 4.3** $A$ is said to satisfy the spectral condition if $A$ is an operator on $C^\infty$ sections of $E$ over $Y$ which is symmetric with respect to the $L^2$ integration pairing with measure $dv_Y$ and inner product $\langle \cdot, \cdot \rangle$, and there is a countable orthonormal basis $\{\phi_\alpha\}_{\alpha \in \Lambda}$ of $L^2\Gamma(E)$ consisting of eigenfunctions,

$$A \phi_\alpha = \lambda_\alpha \phi_\alpha, \quad \alpha \in \Lambda,$$  

(4.8)

such that the eigenvalues $\lambda_\alpha \in \mathbb{R}$, counted as always with multiplicity, have no accumulation point in $\mathbb{R}$.

**Corollary 4.4** Suppose $Y$ is a compact manifold without boundary and $A : H^1(Y) \to L^2(Y)$ is an elliptic system between sections of the bundles $E$, $F$, which satisfies the conditions (3.4,3.5) of Theorem 3.7. If $A = A^\dagger$ is formally self-adjoint (see (3.7)), then $A$ satisfies the spectral condition, Definition 4.3.

**Proof:** Take $H = H^1(Y)$. Condition (C0) follows from the coefficient bounds (3.4) and the inequality (3.3), and condition (C1) is conclusion (3.22) of Theorem 3.7, which also provides condition (C2). Finally, (C3) follows from the definition (3.7) of the $L^2$-adjoint $A^\dagger$, since integration by parts is permitted in $H$, and (C4) is standard. The conclusions now follow from Theorem 4.1.

**Corollary 4.5** Suppose $Y$ is a compact manifold without boundary and $A : H^1(Y) \to L^2(Y)$ is an elliptic system between sections of the bundles $E$, $F$, which satisfies the conditions of Theorem 3.7. There are bases $\phi_\alpha \in L^2(E), \psi_\alpha \in L^2(F), \alpha \in \Lambda$, with real numbers $\lambda_\alpha$ having no accumulation point in $\mathbb{R}$, which satisfy

$$A \phi_\alpha = \lambda_\alpha \psi_\alpha, \quad A^\dagger \psi_\alpha = \lambda_\alpha \phi_\alpha.$$  

(4.9)

The fields $\phi_\alpha, \psi_\alpha$ are all $H^1(Y)$.

**Proof:** This follows directly by applying Corollary 4.4 to the formally self-adjoint operator

$$A = \begin{bmatrix} 0 & A^\dagger \\ A & 0 \end{bmatrix},$$  

(4.10)

which acts between sections of the bundle $E \oplus F$.  

\[ \text{18} \]
5 Boundary Regularity

In this section we introduce a broad class of boundary conditions which are elliptic in the sense that the Weak-Strong property (C2) can be established, at least for solutions supported near the boundary. When combined with the interior regularity results of §3, this will give the Weak-Strong property for compact manifolds with boundary (§6), and for a large class of noncompact manifolds with compact boundary (§8). The main result is the boundary regularity Theorem 5.11, and the primary ingredient in the arguments is the energy identity (5.15) cf. [6] and (2.6).

We consider operators which may be written abstractly in the form

\[ L = L_0 + B = \partial_x + A + B, \]  

acting on sections of a (real) vector bundle \( E \) over \( Y \times I \), where \( Y \) is a compact manifold without boundary\(^6\), and for some constant \( \delta > 0 \),

\[ I = [0, \delta]. \]

Let \( E|_Y = i^*E \) be the pullback bundle over \( Y \), where \( i : Y \to Y \times I, \ y \mapsto (y,0) \). We assume that \( A \) is an operator on sections of \( E|_Y \) which is formally self-adjoint with respect to the pairing defined by integration over \( Y \) with the measure \( dv_Y \) and the real inner product \( \langle \cdot, \cdot \rangle \) on the fibres of \( E|_Y \). The operator \( A \) and the inner product extend naturally to act on sections of \( E \) over \( Y \times I \), and we likewise extend the definition of the integration pairing by using the product measure \( dv_Y dx \) on \( Y \times I \). Thus, \( A \) is \( x \)-independent, but we allow \( B \) to depend upon \( x \).

We assume also that \( A \) satisfies the spectral condition, Definition 4.3, so there is a countable index set \( \Lambda \) and an orthonormal basis \( \{ \phi_\alpha \}_{\alpha \in \Lambda} \) of \( L^2(E|_Y) \) consisting of eigenfunctions

\[ A \phi_\alpha = \lambda_\alpha \phi_\alpha, \quad \alpha \in \Lambda, \]  

with eigenvalues \( \lambda_\alpha \in \mathbb{R} \) having no accumulation points in \( \mathbb{R} \).

A formally self-adjoint first order elliptic operator with the coefficient conditions of Theorem 3.7, will satisfy these conditions, by Corollary 4.4.

Although we have in mind primarily the case where \( A, B \) are first order differential (Dirac-type) operators, the results here will be presented in an abstract form, because they could be applied more widely. For example, \( A = -\Delta_Y \) will also satisfy the spectral conditions, so the boundary regularity result Theorem 5.11 may also be applied to the heat equation.

We fix an eigenvalue cutoff parameter \( \kappa > 0 \), which is used to partition the index set \( \Lambda \) into

\[ \Lambda^+ = \{ \alpha \in \Lambda, \lambda_\alpha \geq \kappa \}, \]  

\[ \Lambda^- = \{ \alpha \in \Lambda, \lambda_\alpha \leq -\kappa \}, \]  

\[ \Lambda^0 = \{ \alpha \in \Lambda, |\lambda_\alpha| < \kappa \}. \]

\(^6\)Although many of the arguments of this section may be extended to allow \( \partial Y \neq \emptyset \), this would introduce technical complications which are not relevant to the applications we have in mind.
and we set Λ' = Λ⁺ ∪ Λ⁻. It will be useful also to introduce a scale parameter

\[ \theta_0 = \kappa^{-1} \max_{\alpha \in \Lambda^0} |\lambda_\alpha| < 1, \quad (5.6) \]

which measures the size of the “small” eigenvalues. For example, we could choose κ to be the smallest nonzero eigenvalue, \( \kappa = \inf_{\lambda_\alpha \neq 0} |\lambda_\alpha| \), in which case \( \theta_0 = 0 \). Choosing κ appropriately will lead to estimates for \( L \) which are uniform under perturbations of \( A \) which create or destroy small and zero eigenvalues.

The eigenfunction expansion \( u = \sum_{\alpha \in \Lambda} u_\alpha \phi_\alpha \) of \( u \in L^2(Y) \), where

\[ u_\alpha := \oint_Y \langle u, \phi_\alpha \rangle \, dv_Y, \]

leads to projection operators \( P_+, P_-, P_0, P' \), defined by

\[ P_\pm u = \sum_{\alpha \in \Lambda^\pm} u_\alpha \phi_\alpha, \]

\[ P_0 u = \sum_{\alpha \in \Lambda^0} u_\alpha \phi_\alpha, \]

and \( P' = 1 - P_0 = P_+ + P_- \).

For \( s \geq 0 \), the Sobolev-type space \( H^s_*(Y) \) is defined as the completion of the space of smooth sections \( C^\infty(Y) \), with respect to the norm

\[ \|u\|_{H^s_*(Y)}^2 = \sum_{\alpha \in \Lambda'} |\lambda_\alpha|^{2s} |u_\alpha|^2 + \kappa^{2s} \sum_{\alpha \in \Lambda^0} |u_\alpha|^2. \quad (5.9) \]

The space \( H^1_*(Y \times I) \) is likewise the completion of \( C^\infty(Y \times I) \) with respect to the norm

\[ \|u\|_{H^1_*(Y \times I)}^2 = \int_0^\delta \left( \sum_{\alpha \in \Lambda'} |u_\alpha'|^2 + \sum_{\alpha \in \Lambda} |\lambda_\alpha|^2 |u_\alpha|^2 + \kappa^2 \sum_{\alpha \in \Lambda^0} |u_\alpha|^2 \right) \, dx \]

\[ = \int_0^\delta \oint_Y \left( |\partial_x u|^2 + |Au|^2 + \kappa^2 |P_0 u|^2 \right) \, dv_Y \, dx, \quad (5.10) \]

where \( ' = \frac{d}{dx} \). Of course in the typical case where \( A \) is a first order elliptic operator, these norms will be equivalent to the usual Sobolev norms, defined using the Fourier transform. Note that the normalization (5.9) ensures that the \( L^2 \) norm is controlled by the Sobolev norm:

\[ \|u\|_{L^2(Y)} \leq \kappa^{-s} \|u\|_{H^s_*(Y)}, \quad s \geq 0. \]

In addition, this formulation leads simply to a useful trace lemma, stated in terms of the parameter \( \ell \),

\[ \ell = \kappa \delta, \quad (5.11) \]

which measures the thickness of the boundary layer \( Y \times [0, \delta] \) in units of \( \kappa^{-1} \).
Lemma 5.1 The restriction map \( r_Y : u \mapsto r_Y u = u(0, \cdot) \) from \( C^\infty(Y) \) to \( C^\infty(Y \times I) \), \( I = [0, \delta] \), extends to a bounded linear map \( r_Y : H^1_s(Y \times I) \to H^1_s(Y) \) satisfying
\[
\|r_Y u\|_{H^1_s(Y)}^2 \leq c_1 \|u\|_{H^1_s(Y \times I)}^2,
\]
where \( c_1 = c_1(\ell) = \ell^{-1}(1 + \sqrt{1 + \ell^2}) \). The map \( x \mapsto r_{Y,x} u \) (where \( r_{Y,x} u = u(x, \cdot) \)) is the restriction to \( Y \times \{x\} \), is likewise bounded and continuous in \( x \) from \( I \) to \( H^1_s(Y) \). Moreover, \( r_Y \) is surjective: there is an extension map \( e_Y : H^1_s(Y) \to H^1_s(Y \times I) \) such that \( r_Y e_Y u = u \) for all \( u \in H^1_s(Y) \) and \( e_Y \) satisfies \( e_Y \circ r_Y = \text{id} \) and it follows easily that \( \eta > 0 \) for all \( \alpha \in \Lambda \) denoting the spectral coefficients, and with \( \tilde{\chi}(x) = \chi(x/\delta) \), we find that
\[
|u_\alpha(0)|^2 = -2 \int_0^\delta (\tilde{\chi} u_\alpha, \frac{d}{dx}(\tilde{\chi} u_\alpha)) \, dx
\leq \int_0^\delta ((2 \tilde{\chi}'|\tilde{\chi}'| + \eta \tilde{\chi}^2)|u_\alpha|^2 + \eta^{-1} \tilde{\chi}^2|u'_\alpha|^2) \, dx
\]
for any \( \eta > 0 \). For \( \alpha \in \Lambda' \) we take \( \eta = a|\lambda_\alpha| \) and with an appropriate choice of \( \chi \) we find
\[
|\lambda_\alpha||u_\alpha(0)|^2 \leq \int_0^\delta (a^{-1}|u'_\alpha|^2 + |\lambda_\alpha|^2(a + 2/\ell)|u_\alpha|^2) \, dx.
\]
Likewise for \( \alpha \in \Lambda^0 \), setting \( \eta = a \kappa \) gives
\[
\kappa|u_\alpha(0)|^2 \leq \int_0^\delta (a^{-1}|u'_\alpha|^2 + \kappa^2(a + 2/\ell)|u_\alpha|^2) \, dx.
\]
Choosing \( a = \ell^{-1}(\sqrt{1 + \ell^2} - 1) \) and combining the two estimates gives (5.12) for all \( u \in C^\infty(Y \times [0, \delta]) \). But this space is dense in \( H^1_s(Y \times I) \) by definition, and it follows easily that \( r_Y u \) is defined and (5.12) is valid for all \( u \in H^1_s(Y \times I) \).

A very similar argument shows that for \( x \in [0, \delta] \),
\[
\|r_{Y,x} u\|_{H^1_s(Y)}^2 \leq \ell^{-1}(2 + \sqrt{4 + \ell^2})\|u\|_{H^1_s(Y \times I)}^2.
\]

To establish continuity of \( x \mapsto r_{Y,x} u \) as a map \([0, \delta] \to H^1_s(Y)\), note first that for any \( v \in H^1_s(Y \times [x_0, x_1]) \), \( x_0 < x_1 \), the spectral coefficients \( v_\alpha \) lie in \( H^1([x_0, x_1]) \) and we may compute:
\[
||v_\alpha(x_1)|^2 - |v_\alpha(x_0)|^2| \leq 2 \int_{x_0}^{x_1} \langle v_\alpha, v'_\alpha \rangle \, dx
\leq \eta_\alpha^{-1} \int_{x_0}^{x_1} (|v'_\alpha|^2 + \eta^2_\alpha |v_\alpha|^2) \, dx.
\]
Choosing $\eta_\alpha = |\lambda_\alpha|$ for $\alpha \in \Lambda'$ and $\eta_\alpha = \kappa$ for $\alpha \in \Lambda^0$ and summing gives

\[
\left| \|r_{Y,x_1}v\|_{H^1(Y \times I)}^2 - \|r_{Y,x_0}v\|_{H^1(Y \times I)}^2 \right| \leq \int_0^1 \left( \sum_{\alpha \in \Lambda'} |u_{\alpha}^k|^2 + \sum_{\alpha \in \Lambda} |\lambda_\alpha|^2 |u_\alpha|^2 + \sum_{\alpha \in \Lambda^0} \kappa^2 |u_\alpha|^2 \right) dx
\]

\[
\leq \|v\|_{H^1(Y \times [x_0,x_1])}. \quad (5.14)
\]

Given $u \in H^1_s(Y \times I)$ and $\bar{x} \in [0, \delta)$, $\epsilon \in (0, (\delta - \bar{x})/2)$, we set

\[
v(x) = u(\bar{x} + \epsilon + x) - u(\bar{x} + \epsilon - x),
\]

where $x \in [-\epsilon, \epsilon]$ and the $Y$-dependence of $u, v$ is understood. Applying (5.14) with $x_0 = 0$, $x_1 = \epsilon$, gives $v(x_0) = 0$, $v(x_1) = u(\bar{x} + 2\epsilon) - u(\bar{x})$ and

\[
\left| \|r_{Y,\bar{x}+2\epsilon}u - r_{Y,\bar{x}}u\|_{H^1(Y \times [\bar{x}, \epsilon])}^2 \right| \leq \int_0^\delta \sum_{\alpha \in \Lambda'} |\lambda_\alpha|^2 |u_{\alpha}^k|^2 \left( \chi^2(x/\eta_\alpha) + \frac{1}{3} \chi^2(x/\eta_\alpha) \right) dx
\]

\[
+ \int_0^\delta \sum_{\alpha \in \Lambda^0} \kappa^2 |u_{\alpha}^k|^2 \left( \chi^2(x/\eta_\alpha) + \frac{1}{3} \chi^2(x/\eta_\alpha) \right) dx.
\]

Using the bounds $\int_0^\infty \chi^2(x)dx \leq 1/3$, $\int_0^\infty \chi^2(x)dx \leq 1$, and noting that

\[
\int_0^\delta \psi^2(x/\eta)dx \leq \eta \int_0^\infty \psi^2(x)dx
\]

for any $\psi$, we have

\[
\left| \|r_{Y,\bar{x}}u\|_{H^1(Y \times I)}^2 \right| \leq \frac{2}{\sqrt{3}} \left( \sum_{\alpha \in \Lambda'} |\lambda_\alpha|^2 |u_{\alpha}^k|^2 + \sum_{\alpha \in \Lambda^0} \kappa^2 |u_{\alpha}^k|^2 \right)
\]

\[
\leq \frac{2}{\sqrt{3}} \|\tilde{u}^k\|_{H^1(Y \times I)}^2.
\]

Hence the sequence $\{\tilde{u}^k\}$ is uniformly bounded, and a similar argument shows that it is also Cauchy, with limit $\tilde{u} = e_Yu \in H^1_s(Y \times I)$. It follows easily that the
sequence has boundary values converging to \( u \in H^{1/2}_*(Y) \), and \( u, e_Y u \) satisfy the bound (5.13).

The next result relates \( H^1 \) estimates to boundary conditions, and is the key to understanding the nature of ellipticity for boundary data. It may be considered as a generalization either of the integration by parts formula for the Dirac operator (2.6), or of the estimate underlying the analysis in [6]. We use \( u(0), u(\delta) \) to denote the restrictions \( r_Y u = u|_{Y \times \{0\}}, r_{Y, \delta} u = u|_{Y \times \{\delta\}} \) respectively.

**Lemma 5.2** Suppose \( f \in L^2(Y \times I) \) and \( u \in H^1(Y \times I) \) satisfies \( L_0 u = f \), then

\[
\|u\|_{H^1_*(Y \times I)}^2 \leq \|(1 - P_0)f\|_{L^2(Y \times I)}^2 + (1 + \theta_0^2)\|P_0 f\|_{L^2(Y \times I)}^2 + 3\kappa^2\|P_0 u\|_{L^2(Y \times I)}^2 + \sum_{\alpha \in \Lambda^+} \lambda_{\alpha} (|u_{\alpha}(0)|^2 - |u_{\alpha}(\delta)|^2) + \sum_{\alpha \in \Lambda^-} |\lambda_{\alpha}| (|u_{\alpha}(\delta)|^2 - |u_{\alpha}(0)|^2)
\]

(5.15)

**Proof:** The coefficient functions \( u_{\alpha}(x) \) are measurable and, by Fubini's theorem, square-integrable over \([0, \delta]\). Testing the weak formulation with \( \phi(x, y) = \chi(x)\phi_{\alpha}(y) \) where \( \chi \in C^\infty_c((0, \delta)) \) shows that \( u_{\alpha} \) satisfies

\[
\int_{0}^{\delta} (-u_{\alpha}' + u_{\alpha}\lambda_{\alpha}\chi - f_{\alpha}\chi) \, dx = 0
\]

(5.16)

for all \( \chi \in C^\infty_c((0, \delta)) \). Because \( u \in H^1_*\{Y \times I\} \), the spectral coefficient \( u_{\alpha}(x) \) is differentiable for a.e. \( x \in [0, \delta] \), with \( u_{\alpha}' \) square-integrable, and (5.16) shows that it satisfies the ordinary differential equation \( u_{\alpha}'(x) + \lambda_{\alpha} u_{\alpha}(x) = f_{\alpha}(x) \). The trace lemma also shows that the restrictions \( u_{\alpha}(0), u_{\alpha}(\delta) \) are well defined. From the ODE we derive the fundamental identity

\[
\int_{0}^{\delta} |f_{\alpha}|^2 \, dx = \int_{0}^{\delta} |u_{\alpha}' + \lambda_{\alpha} u_{\alpha}|^2 \, dx = \int_{0}^{\delta} (|u_{\alpha}'|^2 + \lambda_{\alpha}^2 |u_{\alpha}|^2) \, dx + \lambda_{\alpha} (|u_{\alpha}(\delta)|^2 - |u_{\alpha}(0)|^2).
\]

(5.17)

Summing over \( \alpha \in \Lambda^+ \cup \Lambda^- \) and noting that the boundary restrictions \( u(0), u(\delta) \) are in \( H^{1/2}_*(Y) \) by Lemma 5.1 since \( u \in H^1(Y \times I) \) by assumption, we find

\[
\|P' u\|_{H^1_*\{Y \times I\}}^2 = \int_{0}^{\delta} \sum_{\alpha \in \Lambda^+ \cup \Lambda^-} (|u_{\alpha}'|^2 + |\lambda_{\alpha}|^2 |u_{\alpha}|^2) \, dx = \int_{0}^{\delta} \int_{Y} |P' f|^2 \, dv_Y \, dx + \sum_{\alpha \in \Lambda^+ \cup \Lambda^-} \lambda_{\alpha} (|u_{\alpha}(0)|^2 - |u_{\alpha}(\delta)|^2).
\]

(5.18)
For $\alpha \in \Lambda^0$ we use $u'_\alpha = f_\alpha - \lambda_\alpha u_\alpha$ to estimate

$$\|P_0 u\|_{H^1(Y \times I)}^2 = \int_0^\delta \sum_{\alpha \in \Lambda^0} (|u'_\alpha|^2 + \kappa^2 |u_\alpha|^2) \, dx$$

$$\leq \int_0^\delta \sum_{\alpha \in \Lambda^0} ((1 + \varepsilon) |f_\alpha|^2 + (\kappa^2 + (1 + \varepsilon^{-1}) \kappa_0^2) |u_\alpha|^2)$$

$$\leq 3\kappa^2 \|P_0 u\|_{L^2(Y \times I)}^2 + (1 + \theta_0^2) \|P_0 f\|_{L^2(Y \times I)}^2, \quad (5.19)$$

having chosen $\varepsilon = \theta_0^2$. Combining (5.18) and (5.19) gives (5.15).

**Remark 5.3** The above proof could be generalized to allow $u \in L^2$ and to show then that $u$ is in $H^{1}_{\text{loc}}$, but this refinement is unnecessary as we soon will show a more general regularity theorem. Working with $u \in H^1$ allows us to use the boundary terms with impunity—a freedom that is not possible with weak solutions at this stage.

The fundamental estimate (5.15) shows that in order to obtain a useful *a priori* elliptic estimate for a general solution of $L_0 u = f$, it is necessary to impose boundary conditions which control $P_+ u(0)$ (and $P_- u(\delta)$). Motivated by the examples of the spectral and pointwise boundary conditions for the Dirac equation (see §2), we introduce a class of boundary conditions which allow us to exploit the “good” terms in $P_- u(0)$ in (5.15) to provide the required control. The effect of the parameterization below is to describe the class of admissible boundary data as graphs over the complementary subspace of “good” data $(1 - P_+) H^{1/2}_s(Y)$. The first justification of this approach is the following existence result and its corresponding elliptic estimate (5.24).

**Lemma 5.4** Let $P = P_{\Lambda^+ \cup \hat{\Lambda}}$ be the spectral projection determined by $\Lambda^+$ and some subset $\hat{\Lambda} \subset \Lambda^0$ of the set of small eigenvalues. Let $\sigma \in PH^{1/2}_s(Y)$ and $f \in L^2(Y \times I)$ be given, and suppose $K : (1 - P) H^{1/2}_s(Y) \to PH^{1/2}_s(Y)$ is a continuous linear operator, so there is a constant $k \geq 0$ such that for all $w \in H^{1/2}_s(Y)$,

$$\|K(1 - P)w\|_{H^{1/2}_s} \leq k \|(1 - P)w\|_{H^{1/2}_s}. \quad (5.20)$$

Then there exists a solution $u \in H^{1}_s(Y \times I)$ to the boundary value problem

$$L_0 u = f \quad (5.21)$$

$$P_0 u(0) = \sigma + K(1 - P)u(0) \quad (5.22)$$

$$P_0 u(\delta) = 0. \quad (5.23)$$

Moreover, the solution $u$ satisfies the estimate

$$\|u\|_{H^{1}_s(Y \times I)}^2 \leq c_4 (\|f\|_{L^2(Y \times I)}^2 + \|\sigma\|_{H^{1/2}_s}^2) \quad (5.24)$$

where the constant $c_4$ depends on $\ell, \theta_0$ and $k$. 

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PROOF: The solution to an ordinary differential equation \( u'(x) + \lambda u = f \) may be written in either of the two forms

\[
    u(x) = \begin{cases} 
        e^{-\lambda x}u(0) + \int_0^x e^{\lambda(s-x)} f(s) ds \\
        e^{\lambda(x-x)}u(x) - \int_x^\delta e^{\lambda(s-x)} f(s) ds. 
    \end{cases} \tag{5.25}
\]

Consider first the spectral coefficients \( u_\alpha(x) \) for \( \alpha \in \Lambda^- \cup \hat{\Lambda}' \), where \( \hat{\Lambda}' = \Lambda_0 \setminus \hat{\Lambda} \). The boundary condition (5.23) is achieved for \( u_\alpha \) by letting \( u_\alpha(\delta) = 0 \), so we define

\[
    u_\alpha(x) = -\int_x^\delta e^{\lambda_\alpha(s-x)} f_\alpha(s) ds, \quad \alpha \in \Lambda^- \cup \hat{\Lambda}', \tag{5.26}
\]

where \( f_\alpha(x) \) is the spectral coefficient of \( f \). Note that \( f_\alpha \in L^2(I) \), so the integral in (5.26) is well-defined. The identity (5.17) and \( u_\alpha(\delta) = 0 \) shows that

\[
    \int_0^\delta (|u_\alpha'|^2 + \lambda_\alpha^2 |u_\alpha|^2) dx = \lambda_\alpha |u_\alpha(0)|^2 + \int_0^\delta |f_\alpha|^2 dx, \quad \forall \alpha \in \Lambda^- \cup \hat{\Lambda}' . \tag{5.27}
\]

It follows that for all \( \alpha \in \Lambda^- \),

\[
    |\lambda_\alpha| |u_\alpha(0)|^2 \leq \int_0^\delta |f_\alpha|^2 dx - \int_0^\delta (|u_\alpha'|^2 + \lambda_\alpha^2 |u_\alpha|^2) dx. \tag{5.28}
\]

To control the small eigenvalues \( \alpha \in \hat{\Lambda}' \) we use an elementary lemma, the proof of which is an exercise:

**Lemma 5.5** For any \( f \in L^2([0, \delta]) \) and \( \lambda \in \mathbb{R} \),

\[
    \int_0^\delta \left( \int_0^\delta e^{\lambda(s-x)} f(s) ds \right)^2 dx \leq \begin{cases} 
        \frac{1}{2} \delta^2 e^{2\lambda \delta} \int_0^\delta f^2(x) dx & \lambda > 0 \\
        \frac{1}{2} \delta^2 \int_0^\delta f^2(x) dx & \lambda \leq 0. 
    \end{cases} \tag{5.29}
\]

From (5.26) and Lemma 5.5 it follows that for \( \alpha \in \hat{\Lambda}' \),

\[
    \int_0^\delta \kappa^2 |u_\alpha|^2 dx \leq \frac{1}{2} \ell^2 e^{2\theta_0} \int_0^\delta |f_\alpha|^2 dx .
\]

Using \( u_\alpha' = f_\alpha - \lambda_\alpha u_\alpha \) as in (5.19) we obtain

\[
    \int_0^\delta (|u_\alpha'|^2 + \kappa^2 |u_\alpha|^2) dx \leq (1 + c_2) \int_0^\delta |f_\alpha|^2 dx , \tag{5.30}
\]

where

\[
    c_2 = c_2(\ell, \theta_0) = \theta_0^2 + \frac{3}{2} \ell^2 e^{2\theta_0} . \tag{5.31}
\]

Combining (5.27) and (5.30) shows that

\[
    u(-)(x, y) := \sum_{\alpha \in \Lambda^- \cup \hat{\Lambda}'} u_\alpha(x) \phi_\alpha(y)
\]
is a sum converging in $H_*^1(Y \times I)$, and $u^{(-)}$ satisfies

$$
\|u^{(-)}\|_{H_*^1(Y \times I)}^2 \leq \|(1-P)f\|_{L^2(Y \times I)}^2 + c_2\|P_{\Lambda'}f\|_{L^2(Y \times I)}^2 - \sum_{\alpha \in \Lambda^{\prime}} |\lambda_\alpha| |u_\alpha(0)|^2 ,
$$

(5.32)

where $1 - P = P_{\Lambda'}$. For $\alpha \in \hat{\Lambda}'$ such that $\lambda_\alpha \neq 0$, using (5.26) we find that

$$
|u_\alpha(0)|^2 \leq \left( \int_0^\delta e^{\lambda_\alpha s} f_\alpha(s) ds \right)^2 \leq \frac{1}{2\lambda_\alpha} (e^{2\lambda_\alpha \delta} - 1) \int_0^\delta |f_\alpha|^2 dx ,
$$

while if $\lambda_\alpha = 0$ then $|u_\alpha(0)|^2 \leq \delta \int_0^\delta |f_\alpha|^2 dx$. Defining

$$
c_3 = \ell e^{2\theta_\alpha},
$$

(5.33)

it follows that

$$
\kappa |u_\alpha(0)|^2 \leq c_3 \int_0^\delta |f_\alpha|^2 dx , \quad \forall \alpha \in \hat{\Lambda}'.
$$

Thus, combining with (5.32) we have

$$
\|u^{(-)}\|_{H_*^1(Y \times I)}^2 + \|u^{(-)}(0)\|_{H_*^{1/2}}^2 \leq \|(1-P)f\|_{L^2(Y \times I)}^2 + (c_2 + c_3)\|P_{\Lambda'}f\|_{L^2(Y \times I)}^2 .
$$

(5.34)

For $\alpha \in \Lambda^+ \cup \hat{\Lambda}$ we use (5.25) to define $u_\alpha$ by

$$
u_\alpha(x) = e^{-\lambda_\alpha x}(\sigma_\alpha + K_\alpha u^{(-)}(0)) + \int_0^x e^{\lambda_\alpha (s-x)} f_\alpha(s) ds,
$$

(5.35)

where $\sigma_\alpha$, $K_\alpha u^{(-)}(0)$ denote the $\phi_\alpha$ coefficients of $\sigma$ and $K u^{(-)}(0)$ respectively. Note in particular that (5.34) shows that $u^{(-)}(0) \in H_*^{1/2}(Y)$, so $K u^{(-)}(0) \in H_*^{1/2}(Y)$ by the hypothesis (5.20), hence the coefficients $K_\alpha u^{(-)}(0)$ are well defined.

For $\alpha \in \Lambda^+$ we estimate using (5.17) and (5.22):

$$
\int_0^\delta (|u'_\alpha|^2 + \lambda_\alpha^2) dx \leq \lambda_\alpha |\sigma_\alpha + K_\alpha u^{(-)}(0)|^2 + \int_0^\delta |f_\alpha|^2 dx \leq 2\lambda_\alpha (|\sigma_\alpha|^2 + |K_\alpha u^{(-)}(0)|^2) + \int_0^\delta |f_\alpha|^2 dx .
$$

(5.36)

For $\alpha \in \hat{\Lambda}$ we estimate directly from (5.35):

$$
\kappa^2 \int_0^\delta |u_\alpha|^2 dx \leq 3\kappa^2 (|\sigma_\alpha|^2 + |K_\alpha u^{(-)}(0)|^2) \int_0^\delta e^{-2\lambda_\alpha x} dx \leq 3\kappa^2 \left( \int_0^\delta e^{\lambda_\alpha (s-x)} f_\alpha(s) ds \right)^2 dx \leq 3c_3(3\kappa (|\sigma_\alpha|^2 + |K_\alpha u^{(-)}(0)|^2) + \frac{\delta}{2} c_3 \int_0^\delta |f_\alpha|^2 dx ,
$$

(5.37)
where Lemma 5.5 has been used to control the final term. Using \( u'_\alpha = f_\alpha - \lambda_\alpha u_\alpha \) to estimate \(|u'_\alpha|^2 \leq (1 + \varepsilon)|f_\alpha|^2 + (1 + \varepsilon^{-1})\lambda_\alpha^2|u_\alpha|^2\) with \( \varepsilon = \theta_0^2 \), (5.37) gives for \( \alpha \in \Lambda \),

\[
\int_0^\delta (|u'_\alpha|^2 + \kappa^2|u_\alpha|^2) \, dx \leq 9\varepsilon_3\kappa(|\sigma_\alpha|^2 + |K_\alpha u(-)(0)|^2)
+ (1 + 3\varepsilon_2) \int_0^\delta |f_\alpha|^2 \, dx.
\]  
(5.38)

Combining (5.36) and (5.38) we have (setting \( u^{(+)} = \sum_{\Lambda+u\Lambda} u_\alpha \phi_\alpha \))

\[
\|u^{(+)}\|_{H^1_2(Y \times I)}^2 \leq \|Pf\|_{L^2(Y \times I)}^2 + 3\varepsilon_2\|P_\Lambda f\|_{L^2(Y \times I)}^2 
+ 2(\|P_\sigma\|_{H^{1/2}_2}^2 + \|P_\sigma K u(-)(0)\|_{H^{1/2}_2}^2) 
+ 9\varepsilon_3(\|P_\sigma\|_{H^{1/2}_2}^2 + \|P_\Lambda K u(-)(0)\|_{H^{1/2}_2}^2),
\]  
(5.39)

where \( P_\Lambda = P_{\Lambda+}, P = P_+ + P_\Lambda \). Since we have already shown that \( K_\alpha u(-)(0) \in H^{1/2}_2(Y) \), all terms on the right hand side of (5.39) are bounded, which shows that \( u^{(+)} \) is well-defined in \( H^1(Y \times I) \).

With \( u = u^{(+)} + u^{(-)} \), we add an appropriate multiple of (5.34) to (5.39) to control the bad terms in \( Ku^{(-)}(0) \) with the good term \( u^{(-)}(0) \) of (5.34). This gives the elliptic estimate (5.24):

\[
\|u\|_{H^1_2(Y \times I)}^2 \leq \|u^{(+)}\|_{H^1_2(Y \times I)}^2 + \max(1, 2k^2, 9\varepsilon_3k^2)\|u^{(-)}\|_{H^1_2(Y \times I)}^2 
\leq c_4^2(\|f\|_{L^2(Y \times I)}^2 + \|\sigma\|_{H^{1/2}_2}^2),
\]  
where \( c_4 = c_4(\ell, \theta_0, k) \) as required. The definitions (5.26), (5.35) ensure \( u \) is a solution satisfying the boundary conditions (5.22), (5.23).

Explicitly, we may take \( c_4^2 = 3c_2 + (k^2 + 1)(2 + 9c_3) \) in general, and \( c_4^2 = 2\max(1, k^2) \) if \( \theta_0 = 0 \).

The next result is the key to handling operators with coefficients depending on \( x \). Recall that the operator norm \( \|B\|_{\text{op}} \) of a linear map \( B : X_1 \to X_2 \) between Banach spaces is the smallest constant such that

\[
\|Bu\|_{X_2} \leq \|B\|_{\text{op}}\|u\|_{X_1}, \quad \forall u \in X_1.
\]  
(5.40)

**Lemma 5.6** Suppose \( L_0, A, f, \sigma, K \) are as in Lemma 5.4, and suppose \( B : H^1_2(Y \times I) \to L^2(Y \times I) \) is a linear map satisfying

\[
c_4\|B\|_{\text{op}} < 1.
\]  
(5.41)

Then there exists \( u \in H^1_2(Y \times I) \) satisfying

\[
(L_0 + B)u = f
\]
and the boundary conditions (5.22), (5.23), such that

\[
\|u\|_{H^1_2(Y \times I)}^2 \leq \frac{c_4}{1 - c_4\|B\|_{\text{op}}^2}(\|f\|_{L^2(Y \times I)}^2 + \|\sigma\|_{H^{1/2}_2}^2).
\]  
(5.42)
Proof: Let $u^{(0)} \in H^1(Y \times I)$ be any function satisfying the boundary conditions (5.22), (5.23); the trace lemma 5.1 ensures the existence of a suitable $u^{(0)}$. Construct a sequence $\{u^{(k)}\} \subset H^1(Y \times I)$ by solving the problems

\begin{align}
L_0u^{(k)} &= f - Bu^{(k-1)} \\
P u^{(k)}(0) &= \sigma + K(1 - P)u^{(k)}(0) \\
(1 - P)u^{(k)}(\delta) &= 0, \quad n = 1, 2, \ldots.
\end{align}

Lemma 5.4 ensures this problem has a solution for every $n \geq 1$, and the difference $u^{(k)} = u^{(k)} - u^{(k-1)}$ satisfies

\begin{align}
L_0u^{(k)} &= -Bu^{(k-1)} \\
P u^{(k)}(0) &= K(1 - P)u^{(k)}(0) \\
(1 - P)u^{(k)}(\delta) &= 0.
\end{align}

The elliptic estimate (5.24) gives

$$\|u^{(k)}\|_{H^1(Y \times I)} \leq c_4 \|Bu^{(k-1)}\|_{L^2(Y \times I)}.$$ 

If $\|B\|_{op} < 1/c_4$ then the iteration is a contraction and thus the sequence $u^{(k)}$ is Cauchy, converging to $u = \lim_{n \to \infty} u^{(k)}$ strongly in $H^1(Y \times I)$. Taking the limit of (5.43) shows that $(L_0 + B)u = f$, and boundedness of the trace operator $r_Y$ shows that $u$ satisfies the boundary conditions (5.22)–(5.23). The elliptic estimates (5.24) satisfied by $u^{(k)}$ are preserved in the limit, so $u$ satisfies

$$\|u\|_{H^1(Y \times I)} \leq c_4 \|f - Bu\|_{L^2(Y \times I)} + \|\sigma\|_{H^1(Y \times I)},$$

from which (5.42) follows easily. \hfill \blacksquare

Observe that the proof of Lemma 5.6 relies on just two properties of the operator $L_0$; namely, the solvability of the problem (5.43) with boundary conditions (5.44), (5.45), and the elliptic estimate (5.24), which provides the size bound (5.41) for the perturbation $B$. This suggest that it should be possible to extend this existence result to more general operators $L = L_0 + B$, for which a strictly coercive estimate such as (5.24) can be established.

Consider, for example, the case where $E$ has a complex structure $J : E \to E$, $J^2 = -1$, and $A$ is a normal operator ([A, $A^\dagger$] = 0), so $A = A_0 + JA_1$ where $A_0, A_1$ are self-adjoint and commuting, $A_0$ satisfies the spectral condition, and both commute with $J$. Then $A$ admits an eigenfunction basis

$$A\phi_\alpha = (\lambda_\alpha + \mu_\alpha J)\phi_\alpha, \quad \lambda_\alpha, \mu_\alpha \in \mathbb{R}, \forall \alpha \in \Lambda,$$

and the results of this section extend with only minor modifications, provided the eigenvalues $\lambda_\alpha, \mu_\alpha$ satisfy the sectorial condition

$$\sup_{\alpha \in \Lambda} |\mu_\alpha|/(1 + |\lambda_\alpha|) < \infty.$$

Before stating the main uniqueness theorem, a definition of weak solution with boundary conditions is required. Note that although the definition is consistent with just $L^2$ boundary data, the regularity theorem 5.11 will require data in $H^{1/2}$.
Definition 5.7 Suppose \( L = \partial_x + A + B \) where \( A \) satisfies the spectral conditions (Definition 4.3) and \( B : H^1_+(Y \times I) \to L^2(Y \times I) \) is a bounded linear operator for which there exists an \( L^2 \)-adjoint \( B^\dagger : H^1_+(Y \times I) \to L^2(Y \times I) \) such that:

\[
\int_{Y \times I} \langle Bu, v \rangle \, dv_Y \, dx = \int_{Y \times I} \langle u, B^\dagger v \rangle \, dv_Y \, dx, \quad \forall \, u, v \in H^1_+(Y \times I).
\] (5.46)

Suppose further that \( P = P_+ + P_\Lambda \) (as in Lemma 5.4), that \( K : (1 - P)L^2(Y) \to PL^2(Y) \) is a bounded linear map with \( L^2 \)-adjoint \( K^\dagger : PL^2(Y) \to (1 - P)L^2(Y) \), and let \( \sigma \in PL^2(Y) \), \( f \in L^2(Y \times I) \) be given. A weak solution of the boundary value problem

\[
Lu = f
\] (5.47)

\[
P u(0) = \sigma + K(1 - P)u(0)
\] (5.48)

\[
(1 - P)u(\delta) = 0
\] (5.49)

is a field \( u \in L^2(Y \times I) \) satisfying (with \( L^\dagger = -\partial_x + A + B^\dagger \))

\[
\int_{Y \times I} \langle u, L^\dagger \phi \rangle \, dv_Y \, dx = \int_{Y \times I} \langle f, \phi \rangle \, dv_Y \, dx + \oint_Y \langle \sigma, \phi(0) \rangle \, dv_Y
\] (5.50)

for all \( \phi \in H^1_+(Y \times I) \) satisfying the adjoint boundary conditions

\[
(1 - P + K^\dagger P)\phi(0) = 0
\] (5.51)

\[
P \phi(\delta) = 0.
\] (5.52)

The boundary values \( \phi(0), \phi(1) \) both lie in \( H^{1/2}_+(Y) \) by the trace lemma, so the adjoint boundary conditions are well-defined on the space of test fields. Since \( C^\infty \) fields are dense in \( H^1_+(Y \times I) \) and in \( H^{1/2}_+(Y) \), to verify the weak equation (5.50) it suffices to test just with \( C^\infty \) fields \( \phi \); however the uniqueness argument of Lemma 5.10 requires the use of an \( H^1_+ \) test field.

The structure of the adjoint boundary condition (5.51) is explained by the next lemma, which is applied with \( v = u(0) - \sigma \) and \( H = L^2(Y) \).

Lemma 5.8 If \( H \) is a Hilbert space, \( P : H \to H \) is an orthogonal projection and \( K : \ker P \to \text{range } P \) is bounded, and if \( v \in H \) satisfies

\[
\langle v, \phi \rangle_H = 0 \quad \forall \, \phi \in \ker(1 - P + K^\dagger P)
\] (5.53)

(where \( K^\dagger \) is the adjoint of \( K \) in \( H \)), then \( v \in \ker(P - K(1 - P)) \).

Proof: Since \( \ker P = \text{range}(1 - P) \perp \text{range } P \), it follows that \( P \) is self-adjoint and there is an orthogonal decomposition \( H = (1 - P)H \oplus PH \). Setting \( \phi_1 = (1 - P)\phi, \phi_2 = P\phi \), the condition \( \phi = \phi_1 + \phi_2 \in \ker(1 - P + K^\dagger P) \) is equivalent to \( \phi_1 = -K^\dagger \phi_2 \), which exhibits \( \ker(1 - P + K^\dagger P) \) as a graph over \( PH \). Similarly decomposing \( v = v_1 + v_2 \), the condition \( \langle v, \phi \rangle = 0 \) is equivalent to \( \langle v_2 - Kv_1, \phi_2 \rangle = 0 \). Since this holds for all \( \phi_2 \in PH \), it follows that \( v_2 = Kv_1 \), or equivalently, \( v \in \ker(P - K(1 - P)) \).

\[\blacksquare\]
In other words, \( H = \ker(P - K(1 - P)) \oplus \ker(1 - P + K\dagger P) \) is an orthogonal splitting of \( H \), where \( P - K(1 - P), 1 - P + K\dagger P \) are projections, which are not orthogonal in general.

Using Lemma 5.8 we next show that an \( H^1 \) weak solution of the boundary value problem (5.47)-(5.49), in fact satisfies the equation (5.47) and the boundary conditions (5.48,5.49) in the strong sense:

**Lemma 5.9** If \( u \in H^1_0(Y \times I) \) is a weak solution of (5.47) with the boundary conditions (5.48), (5.49), then \( u \) satisfies the equation \( Lu = f \) in the sense of strong \( (H^1) \) derivatives, and the restrictions \( u(0) = r_Y(u), u(\delta) = r_{Y,\delta}u \) satisfy the boundary conditions (5.48),(5.49) in \( L^2(Y) \). Conversely, if \( u \in H^1_0(Y \times I) \) is a strong solution of (5.47,5.48,5.49), then \( u \) is also a weak solution.

**Proof:** Integration by parts gives
\[
\int_{Y \times I} \langle u, L^\dagger \phi \rangle = \int_{Y \times I} \langle Lu, \phi \rangle + \int_Y \langle u(0), \phi(0) \rangle - \int_Y \langle u(\delta), \phi(\delta) \rangle
\]
for any \( u, \phi \in H^1_0(Y \times I) \). Testing \( u \) with arbitrary \( \phi \in C^\infty(Y \times I) \) shows that a \( H^1 \) weak solution satisfies \( Lu = f \) in the sense of strong derivatives. Comparing this formula with (5.50) shows also that
\[
\int_Y \langle u(0) - \sigma, \phi(0) \rangle = 0, \quad \int_Y \langle u(\delta), \phi(\delta) \rangle = 0,
\]
for all \( \phi(0), \phi(\delta) \) satisfying the adjoint boundary conditions (5.51), (5.52). Since \( H^{1/2}_0(Y) \) is dense in \( \ker(1 - P + K\dagger P) \subset L^2(Y) \), Lemma 5.8 may be applied with \( v = u(0) - \sigma \) to show the boundary condition (5.48) holds in \( L^2(Y) \), and (5.49) follows similarly.

To show the converse, integration by parts again gives
\[
\int_{Y \times I} \langle u, L^\dagger \phi \rangle - \langle Lu, \phi \rangle
\]
\[
= \int_Y \langle u(0), \phi(0) \rangle - \langle u(\delta), \phi(\delta) \rangle
\]
\[
= \int_Y \langle \sigma + (1 + K)(1 - P)u(0), \phi(0) \rangle - \langle Pu(\delta), \phi(\delta) \rangle
\]
\[
= \int_Y \langle \sigma, \phi(0) \rangle + \langle u(0), (1 - P + K\dagger P)\phi(0) \rangle - \langle u(\delta), P\phi(\delta) \rangle,
\]
and the final two terms vanish by the adjoint boundary conditions (5.51,5.52).

By solving an adjoint problem, we now show that weak solutions of (5.47)-(5.49) are unique.

**Lemma 5.10** Let \( u \in L^2(Y \times I) \) be a weak solution of the boundary value problem (5.47)-(5.49), with \( \sigma \in L^2(Y) \) and \( f \in L^2(Y \times I) \). Suppose that the operator \( L = \partial_x + A + B \) satisfies the conditions of Lemma 5.6 and Definition 5.7, and the \( L^2(Y \times I) \)-adjoint \( B^\dagger : H^1_0(Y \times I) \rightarrow L^2(Y \times I) \) satisfies
\[
c_4 \| B^\dagger \|_{ap} < 1.
\]
Suppose also that the boundary operators $K,K^\dagger$ of Definition 5.7 satisfy
\begin{align}
\|K(1-P)w\|_{H^s_{1/2}} &\leq k \| (1-P)w\|_{H^s_{1/2}}, \quad (5.55) \\
\|K^\dagger Pw\|_{H^s_{1/2}} &\leq k \|Pw\|_{H^s_{1/2}}. \quad (5.56)
\end{align}
for some constant $k \geq 0$ and all $w \in H^s_{1/2}(Y)$. Then $u$ is unique.

**Proof:** It will suffice to show that any weak solution $\tilde{u}$ of (5.47)–(5.49) with $\sigma = 0$, $f = 0$, must vanish. Consider the adjoint problem $L^\dagger \phi = \tilde{u}$ with boundary conditions (5.51),(5.52); writing $L^\dagger \phi = \tilde{u}$ as $(\partial_x - A - B^\dagger)\phi = -\tilde{u}$, we see that $L^\dagger$, $K^\dagger$ satisfy the conditions required by Lemma 5.6, since interchanging $A \leftrightarrow -A$ means replacing $P$ by $1-P$, and perhaps changing a finite number of eigenfunctions in $\hat{\Lambda}$ (without modifying $\Lambda_0$). The elliptic estimate (5.42) does not depend on $\hat{\Lambda}$. Thus, by Lemma 5.6 there exists a solution $\phi \in H^s_1(Y \times I)$ of this boundary value problem. By construction, $\phi$ satisfies the boundary conditions required of test functions in (5.50), so testing $\tilde{u}$ in (5.50) with $\phi$ gives
\[
\int_{Y \times I} |\tilde{u}|^2 = \int_{Y \times I} \langle \tilde{u}, L^\dagger \phi \rangle = 0
\]
and thus $\tilde{u} = 0$. \hfill ■

It is easy to check that (5.56) is equivalent to requiring that $K : (1-P)H^s_{1/2}(Y) \to PH^s_{1/2}(Y)$ is bounded, with constant $k$.

We now obtain the main result on boundary regularity of weak solutions. Note that although the definition of weak solution assumes boundary data $\sigma \in L^2(Y)$ only, and uniqueness of weak solutions holds also in this generality, this condition is incompatible with regularity $u \in H^s_1(Y \times I)$, which would imply (by simple restriction) that $\sigma \in H^s_{1/2}(Y)$. However, some results for $L^2$ boundary conditions on domains with uniformly Lipschitz boundary are known [1, 2], so it is plausible that the results here could be extended.

**Theorem 5.11** Suppose $u \in L^2(Y \times I)$ is a weak solution of the boundary value problem (5.47)–(5.49) with operator $L = \partial_x + A + B_0 + B_1$, where $A$ satisfies the spectral conditions (Definition 4.3), $B_0$ satisfies the size condition (5.41) with $L^2$-adjoint $B_0^\dagger$ satisfying (5.54), and $B_1 : L^2(Y \times I) \to L^2(Y \times I)$ is bounded. Further suppose the boundary operators $K,K^\dagger$ satisfy (5.55,5.56), and $\sigma \in PH^s_{1/2}(Y)$. Then $u \in H^s_1(Y \times I)$ (so $u$ is a strong solution) and $u$ satisfies the a priori estimate
\[
\|u\|_{H^s_1(Y \times I)} \leq \frac{c_4}{1 - c_4 \|B_0\|_{op}} (\|f\|_{L^2(Y \times I)} + \|\sigma\|_{H^s_{1/2}} + \|B_1\|_{L^2 \to L^2} \|u\|_{L^2(Y \times I)}).
\]

**Proof:** Since $\|B_1 u\|_{L^2(Y \times I)} \leq \|B_1\|_{op} \|u\|_{L^2(Y \times I)}$, $u$ satisfies $\tilde{L}u := (\partial_x + A + B_0)u = \tilde{f}$ where $\tilde{f} = f - B_1 u \in L^2(Y \times I)$. Lemma 5.6 constructs a solution $\tilde{u} \in H^s_1(Y \times I)$ of $\tilde{L}\tilde{u} = \tilde{f}$ satisfying the same boundary conditions, and it follows that $\tilde{u}$ is also a weak solution. By the Uniqueness Lemma 5.10 we have $u = \tilde{u}$ and thus $u \in H^s_1(Y \times I)$, as required. The estimate (5.42) of Lemma 5.6 (with $f$ replaced by $\tilde{f}$) leads directly to (5.57). \hfill ■
6 Boundary regularity for first order systems

In this section we determine conditions under which the boundary regularity results of §5 apply to a first order equation of Dirac type (see (6.7), (6.9)) at the boundary, with suitable boundary operator, to show $H^1$ regularity of an $L^2$ weak solution.

We assume $M$ is a smooth manifold with compact boundary $Y$, $E \to M$ and $F \to M$ are real vector bundles over $M$ with scalar products, and $\mathcal{L}$ is a first order elliptic operator on sections of $E$ to sections of $F$, which in local coordinates $x^j, j = 1, \ldots, n$ takes the form

$$\mathcal{L}u = a^j \partial_j u + bu, \quad (6.1)$$

where $a^j, b$ are homomorphisms of $E$ to $F$ as before. Note that we do not assume $Y$ to be connected.

To apply the preceding results, the coefficients must satisfy the interior regularity conditions (3.4), and the boundary restrictions must be defined and satisfy the corresponding conditions in dimension $n-1$,

$$a^j|_Y \in W^{1,(n-1)^*}(Y) \cap C^0, \quad j = 1, \ldots, n, \quad b|_Y \in L^{(n-1)^*}(Y). \quad (6.2)$$

Conditions (3.4,3.5) and (6.2) will be assumed throughout this section.

Remark 6.1 The $H^s$ conditions

$$a^j \in W^{s,2}_{\text{loc}}(M) \cap C^0(M), \quad b \in W^{s-1,2}_{\text{loc}}(M), \quad (6.3)$$

where

$$s = n/2 \quad \text{for} \quad n \geq 4, \quad s > 3/2 \quad \text{for} \quad n = 3, \quad s = 3/2 \quad \text{for} \quad n = 2, \quad (6.4)$$

imply the interior (3.4) and boundary (6.2) coefficient regularity conditions, through the Sobolev embedding and trace theorems [60]. The $C^0$ condition in (6.3) is superfluous for $n = 2, 3$.

Let $x = x^n$ be a boundary coordinate, defining a tubular neighbourhood $Y \times [0, 1] \subset M$ of $Y$ with local coordinates $(y^i, x) \in Y \times [0, 1]$ (where we identify $Y$ with $Y \times \{0\}$). Let $dv_M$ be a volume measure on $M$, and define $dv_Y = (-1)^{n-1} \partial_x \mathcal{L} dv_M|_Y$ on $Y \times \{0\}$. The local coordinate integration factor $\gamma$ is defined in $Y \times [0, 1]$ by $dv_M = \gamma dy dx$, where $dy dx$ is coordinate Lebesgue measure. We assume the local coordinate condition

$$\gamma \in (W^{1,n^*} \cap C^0)(Y \times [0, 1]). \quad (6.5)$$

In order to directly apply the results of the previous section, we assume that $\gamma = \gamma(0)$ is independent of $x$ in $Y \times [0, 1]$, so $dv_M = dv_Y dx$. This involves

\[ \text{As in §3, this means that we can cover } Y \text{ by a finite number of coordinate charts } \mathcal{G}_\alpha \text{ so that } \gamma \text{ has the stated regularity in the local coordinates on } \mathcal{G}_\alpha \times [0, 1]. \]
no loss of generality, as the \( x \)-dependence of \( \gamma \) in the integral form (6.15) of the equation can be absorbed through a rescaling of the coefficients \( a^i, b \). Since the restrictions to \( Y \times \{0\} \) are unchanged, this does not affect the boundary operator \( A \).

To minimize confusion with the outer unit normal \( n = -\partial_x \) we set

\[
\nu := t^i a^n ,
\]  

(6.6)

and for simplicity we assume

\[
t^\nu = \nu^{-1} .
\]  

(6.7)

This is satisfied by the Dirac operator. Equation (6.7) can also be achieved in several other situations of interest by pre-multiplying \( L \) by a suitable homomorphism, or by making a frame change in \( F \) (this can be done \textit{e.g.} when \( F \) is trivial). Note that such a pre-multiplication does not affect the values of \( \tilde{a}^i, \tilde{b} \), where we define

\[
\tilde{a}^i := \nu a^i|_Y , \quad i = 1, \ldots, n-1 , \quad \tilde{b} := \nu b|_Y .
\]  

(6.8)

By extending independent of \( x \) we regard \( \tilde{a}^i, \tilde{b} \) as defined on \( Y \times [0,1] \). We assume the important boundary symmetry condition

\[
\tilde{a}^i = -t^i \tilde{a}^i , \quad i = 1, \ldots, n-1 ,
\]  

(6.9)

where the transpose \( t^i \tilde{a}^i \) is taken with respect to the inner product on \( E \). We wrap up these conditions into a definition.

**Definition 6.2** A first order system (6.1) is of boundary Dirac type if the coefficients \( a^j \) satisfy the conditions (6.7,6.9) in some neighbourhood of the boundary.

As discussed in §10, this class includes the examples of §2 and §11. These conditions will be assumed henceforth.

Using (6.9) we define the boundary operator

\[
Au := \sum_{i=1}^{n-1} \tilde{a}^i \partial_i u + \tilde{a}_0 u + \tilde{b}_0 u ,
\]  

(6.10)

where

\[
\tilde{a}_0 = \frac{1}{2} \sum_{i=1}^{n-1} (\partial_i \tilde{a}^i + \tilde{a}^i \partial_i \log \gamma) ,
\]  

(6.11)

and \( \tilde{b}_0 = b_0|_Y \) for some symmetric endomorphism \( b_0 \) of \( E \). We require that \( b_0 \in L^{n^2}(Y \times I) \) and \( \tilde{b}_0 \in L^{(n-1)^2}(Y) \), compare (3.4), (6.2). Then \( A \) is formally self-adjoint (\( A^\dagger = A \)) on the bundle \( E|_Y \) over \( Y \), with respect to the measure \( dv_Y \).

Note that the choice of zero-order term \( b_0 \) gives some freedom in the definition of the boundary operator \( A \), which is thus not uniquely determined by \( L \). Near the boundary, \( Lu = t^\nu (\partial_x + A + B) \), which may be expressed as

\[
\tilde{L}u := (\partial_x + A + B)u = \tilde{f} ,
\]  

(6.12)
where $\tilde{L}u = \nu Lu$, $\tilde{f} = \nu f$, and $B$ denotes the difference

$$Bu = \sum_{i=1}^{n-1} (\nu a^i - \tilde{a}^i) \partial_i u + (\nu b - \tilde{a}_0 - \tilde{b}_0)u . \quad (6.13)$$

By Corollary 4.4, under the above conditions, $A$ will satisfy the spectral condition 4.3. Denote the eigenvalue index set by $\Lambda$ and fix a cutoff $\kappa$ as in §5. Similarly let $\Lambda^+ = \{\alpha \in \Lambda : \lambda_\alpha \geq \kappa\}$, fix some subset $\hat{\Lambda} \subset \{\alpha \in \Lambda : |\lambda_\alpha| < \kappa\}$ and let $P = P_{\Lambda^+} + P_{\hat{\Lambda}}$ be the associated spectral projection operator. Note that Theorem 3.7 (see (3.22)) shows that the $H^s$ norms defined using $A$ will be equivalent to the corresponding $H^s$ norms defined on $Y$ and $Y \times I$, at least for $s = 0,1$; it seems likely that this will hold, by interpolation, for all $s \in [0,1]$. If the coefficient regularity allows an $H^{k+1}$ elliptic estimate (cf. Theorem 3.8) then this should extend to $s \in [0,k+1]$.

The definition of weak solution on a manifold with boundary which we are about to give is slightly simpler than the tubular neighbourhood Definition 5.7 of §5, since the conditions (5.49), (5.52) may be imposed by localising with a boundary cutoff function; see the proof of Theorem 6.4. Let $H^1_c(M)$ denote the dense subspace of $H^1(M)$ consisting of functions of compact support, where we recall that because $M$ is a manifold with boundary $Y = \partial M$, $H^1_c(M)$ includes functions which are non-zero on $Y$. As in §5, the boundary condition is expressed using a positive spectrum projection $P : L^2(Y) \to L^2(Y)$ and a bounded linear map $K : (1-P)L^2(Y) \to PL^2(Y)$ and its $L^2$ adjoint $K^\dagger$.

**Definition 6.3** Let $f \in L^2_{\text{loc}}(M)$ and $\sigma \in PL^2(Y)$ be given. A section $u \in L^2_{\text{loc}}(M)$ is a weak solution of $Lu = f$ with boundary condition

$$Pu_0 = \sigma + K(1-P)u_0 , \quad (6.14)$$

if

$$\int_M \langle u, \mathcal{L}^\dagger \phi \rangle dv_M = \int_M \langle f, \phi \rangle dv_M + \int_Y \langle \sigma, \nu \phi_0 \rangle dv_Y , \quad (6.15)$$

for all $\phi \in H^1_c(M)$ satisfying the boundary condition

$$(1-P + K^\dagger P)(\nu \phi_0) = 0 , \quad (6.16)$$

where $\mathcal{L}^\dagger$ is the $L^2$ adjoint given by (3.7).

Note we are using the notation $u_0, \phi_0$, etc., to denote the restriction (trace) on the boundary $Y$. The additional term $\nu$ in (6.15,6.16) (cf. (5.50,5.51)) arises from the relation $\mathcal{L} = \nu(\partial_x A + B)$ between $\mathcal{L}$ and the boundary form $\partial_x A + B$ used in §5.

The boundary condition (6.14) restricts $u_0 = u|_Y$ to lie in the affine subspace of $L^2(Y)$ given by the graph of $x \mapsto \sigma + Kx$ over the negative spectrum subspace $x \in (1-P)L^2(Y)$. It will be useful to re-express (6.14) as

$$Ku_0 = \sigma , \quad (6.17)$$
where we have introduced the operator $\mathcal{K}$ on $L^2(Y)$,

$$\mathcal{K} := P - K(1 - P) ,$$

and likewise to re-express the “adjoint” boundary condition (6.16) as

$$\mathcal{K}^\dagger \phi_0 = 0 ,$$

where we define

$$\mathcal{K}^\dagger := \nu^{-1}(1 - P + K^\dagger P)\nu .$$

The next result generalizes the interior weak-strong Theorem 3.7 to boundary value problems.

**Theorem 6.4** Suppose $\mathcal{L}$ and $A$ satisfy the conditions (3.4,3.5,6.2, 6.5,6.7,6.9), and suppose $\sigma \in PH^{1/2}_*(Y)$, $f \in L^2_{\text{loc}}(M)$. Further suppose $K : (1 - P)L^2(Y) \to PL^2(Y)$ is bounded linear and satisfies (5.55), with $L^2$ adjoint $K^\dagger$ satisfying (5.56). Assume $u \in L^2_{\text{loc}}(M)$ is a weak solution of $\mathcal{L}u = f$ with the boundary condition $Ku_0 = \sigma$ (6.17). Then $u \in H^1_{\text{loc}}(M)$ and $u$ is a strong solution. Moreover, there are constants $\delta \in (0,1]$, $c_5$, depending only on $\kappa,k$ and $a^i,b$, and intervals $I = [0,\delta/2]$, $I = [0,\delta]$ such that

$$\|u\|_{H^1(Y \times I)} \leq c_5(\|f\|_{L^2(Y \times I)} + \|\sigma\|_{H^{1/2}_*(Y)} + \|u\|_{L^2(Y \times I)}) .$$

**Proof:** Theorem 3.7 ensures $u \in H^1_{\text{loc}}(\hat{M})$, where $\hat{M}$ is the interior of $M$, so it suffices to consider $u$ compactly supported in $Y \times [0,\delta)$, for any choice of $\delta \in (0,1)$. In particular, because $u$ then vanishes near $Y \times \{\delta\}$, it follows from (6.14) that $u$ is a weak solution with boundary conditions, in the sense of Definition 5.7.

It will suffice to show, for a sufficiently small choice of $\delta > 0$, that we may decompose $B = B_0 + B_1$ into pieces satisfying the size conditions of Theorem 5.11. Write $B = \beta\partial_t + \beta$ where

$$\beta^i(y,x) = (a^a(y,x))^{-1}a^i(y,x) - (a^a(y,0))^{-1}a^i(y,0), \quad i = 1, \ldots, n-1,$$

so $\beta^i \in W^{1,n*} \cap C^0$ and $\beta^i(y,0) = 0$. Since the constant $c_4$ of Lemma 5.4 depends only on $\theta_0 < 1$, $\ell = \kappa\delta$ and the constant $k$ of (5.55,5.56), it is bounded uniformly in $\delta \leq 1$. Consequently for any $\epsilon > 0$ there is $\delta_0 > 0$ such that $c_4\|\beta^i\|_{L^\infty(Y \times [0,\delta])} < \epsilon$ for all $\delta \leq \delta_0$.

Likewise, since $\gamma \in W^{1,n*} (6.5)$, we have $\beta \in L^n$ and there is a decomposition $\beta = \beta_0 + \beta_1$ with $c_4 C_S \|\beta_0\|_{L^n(Y \times [0,1])} \leq \epsilon$, where $C_S$ is the Sobolev constant on $Y \times [0,1]$, and $\beta_1 \in L^\infty$. Then $B_0 = \beta^i\partial_t + \beta_0$ satisfies (5.41), as does $B_0^\dagger$ (possibly after decreasing $\delta$), and $B_1 = \beta_1$ is bounded on $L^2$. Theorem 5.11 now applies and shows $u \in H^1(Y \times [0,\delta])$, since $H^1(Y \times I) = H^1_0(Y \times I)$ as remarked above. The elliptic estimate (6.21) follows by applying (5.57) to $\tilde{u} = \chi u$, where $\chi = \chi(x)$ is a cutoff function, $\chi(x) = 1$ for $0 \leq x \leq 2\delta$, $\chi(x) = 0$ for $x \geq \frac{3}{4}\delta$.
Corollary 6.5 Suppose \( \mathcal{L}, A, K, \mathcal{K} \) satisfy the conditions of Theorem 6.4. Then for all \( u \in H^1_{loc}(M) \) we have the boundary estimate
\[
\|u\|_{H^1(Y \times I')} \leq C_0(\|\mathcal{L}u\|_{L^2(Y \times I)} + \|Ku_0\|_{H^{1/2}(Y)} + \|u\|_{L^2(Y \times I)}) .
\]  

Proof: If \( u \in H^1_{loc}(M) \) then \( f := \mathcal{L}u \in L^2_{loc}(M) \), \( \sigma := \mathcal{K}u_0 \in H^{1/2}(Y) \), and \( u \) is a strong solution. Since integration by parts may be applied to show \( u \) satisfies the weak equation (6.15), Theorem 6.4 applies and gives (6.22).

A bootstrap argument, slightly more complicated than that used for the interior bounds Theorem 3.8, leads to higher, \( H^{1+k} \), regularity. Rather than stating complicated conditions for general \( k \), we describe the details only for the case \( k = 1 \) (\( u \in H^2(Y \times I) \)). The coefficient regularity conditions are most likely not optimal.

Theorem 6.6 In the setting of Theorem 6.4 let \( u \in H^1(Y \times I) \) be the solution and suppose the following additional regularity conditions are satisfied,
\[
a^2, b \in W^{1, \infty}(Y \times I) ,
\]
\[
\gamma \in W^{2,n^*}(Y \times [0,1]) ,
\]
\[
f \in H^1(Y \times I) , \quad \sigma \in H^{3/2}(Y) ,
\]
\[
[A, K](1 - P) : (1 - P)H^{1/2}(Y) \to PH^{1/2}(Y) \text{ is bounded}.
\]

Then there exists \( \delta'' \leq \delta/2 \) such that \( u \in H^2(Y \times I'') \), where \( I'' = [0, \delta''] \), and there is a constant \( C_0 \) depending on the coefficient bounds (6.23)-(6.26), such that
\[
\|u\|_{H^2(Y \times I'')} \leq C_0(\|f\|_{H^1(Y \times I)} + \|\sigma\|_{H^{3/2}(Y)} + \|u\|_{L^2(Y \times I)}) .
\]

Remark 6.7 For the APS and chiral boundary conditions (2.13), (2.18), \( A \) commutes with \( K \) and thus (6.26) is trivially satisfied.

Proof: The idea is to show that \( Au \) satisfies a similar boundary value problem. For convenience, let \( \bar{H}^0_0(Y \times I) \), \( I = [0, \delta] \), denote the \( H^1 \) completion of the \( C^\infty \) functions of compact support in \( Y \times [0, \delta] \), where \( \delta \) is the constant of Theorem 6.4. In particular, functions in \( \bar{H}^0_0(Y \times I) \) have vanishing trace on \( Y \times \{\delta\} \). For any \( v, \psi \in C_c^\infty(Y \times [0, \delta]) \), we have the identity
\[
\int_{Y \times I} \langle Av, \bar{L}^1\psi \rangle \, dx \, dv_Y = \int_{Y \times I} \left( \langle [\bar{L}, A]v, \psi \rangle \right. + \left. \langle \bar{L}v, A\psi \rangle \right) \, dx \, dv_Y
\]
\[
+ \iiint_Y \langle v_0, A\psi_0 \rangle \, dv_Y .
\]

Since \( A \) is formally self-adjoint with respect to \( dv_Y \), this formula follows by direct calculation. The terms with \( \bar{L} \psi, \bar{L}v \) are well-defined for \( v, \psi \in \bar{H}^0_0(Y \times I) \).

Since \( v_0, \psi_0 \in H^{1/2}(Y) \) by Lemma 5.1, the boundary integral extends also by writing it as
\[
\iiint_Y \langle v_0, A\psi_0 \rangle \, dv_Y = \iiint_Y \langle Jv_0, J^{-1}A\psi_0 \rangle \, dv_Y .
\]
Here $J = (1 + |A|)^{1/2}$ is defined as $J u = \sum_{\alpha \in \Lambda} u_\alpha (1 + |\lambda_\alpha|)^{1/2} \psi_\alpha$, with $u = \sum_{\alpha \in \Lambda} u_\alpha \psi_\alpha$; $J^{-1}$ is defined similarly. This shows that

$$\left| \int_Y \langle v_0, A \psi_0 \rangle \, dv_Y \right| \leq c \|v_0\|_{H^{1/2}(Y)} \|\psi_0\|_{H^{1/2}(Y)},$$

for all $v_0, \psi_0 \in H^{1/2}(Y)$, where the constant $c$ is determined by $A$.

More care is required to control the commutator $[\tilde{L}, A]$, which takes the form

$$[\tilde{L}, A] v = \alpha^{ij} \partial^2_{ij} v + \alpha^i_1 \partial_i v + \alpha_2 v$$

where

$$\alpha^{ij} = [\nu a^i, \bar{a}^j],$$

$$\alpha^i_1 = \nu a^j \partial_j \bar{a}^i - \bar{a}^j \partial_j (\nu a^i) + [\nu a^i, \bar{a}_0],$$

$$\alpha_2 = \nu a^i \partial_i \bar{a}_0 - \bar{a}^i \partial_i (\nu b).$$

Observe that $\alpha^{ij}|_Y = 0$. The coefficient conditions (6.23) and $v \in H^1$ ensure that $\alpha^i_1 \partial_i v$ is in $L^2$ and hence may be combined with the source term $A \tilde{f}$. Likewise (6.23) ensures $\alpha_2 v$ is bounded in $L^2$.

Let $\lambda_0 \in \mathbb{R} \setminus \Lambda$, so $A - \lambda_0$ has trivial kernel and satisfies elliptic estimates $\|v\|_{H^{s+1}} \leq c \|(A - \lambda_0)v\|_{H^s}$ for $s = 0, 1$ at least. Since $A$ is self-adjoint and elliptic, the cokernel of $A - \lambda_0$ is also trivial, so $A - \lambda_0 : H^{s+1} \to H^s$ is invertible. Now decompose $\alpha^{ij} \partial^2_{ij} v = B_2 \partial^2 v + B_3 v$ where

$$B_2 = \alpha^{ij} \partial^2_{ij} (A - \lambda_0)^{-1}$$

is bounded from $H^1 \to L^2$, and

$$B_3 = -\lambda_0 \alpha^{ij} \partial^2_{ij} (A - \lambda_0)^{-1}$$

is also bounded from $H^1 \to L^2$. Note that by perhaps decreasing $\delta$ we may ensure that $B_2$ and $B_3$ satisfy a smallness condition similar to (5.41).

Direct calculation (noting that $[A, P] = 0$) establishes the boundary formula

$$\int_Y \langle (1 + K)(1 - P)v_0, A \psi_0 \rangle \, dv_Y = \int_Y \langle A v_0, (1 - P + K^P) \psi_0 \rangle \, dv_Y$$

$$+ \int_Y \langle [A, K](1 - P)v_0, \psi_0 \rangle \, dv_Y \quad \text{(6.30)}$$

for all $v_0, \psi_0 \in H^{1/2}(Y)$, since $K$ satisfies (6.26) and (5.55) by assumption.

Now $u \in \tilde{H}^1_0(Y \times I)$ satisfies $\tilde{L} u = \tilde{f}$ and $u_0 = \sigma + (1 + K)(1 - P)u_0$. Substituting $u$ for $v$ in (6.28) and using these relations, shows that $u$ satisfies

$$\int_{Y \times I} \langle A u, (\tilde{L} - B_2)^\dagger \psi \rangle \, dx \, dv_Y = \int_{Y \times I} \langle A \tilde{f} + \alpha^i_1 \partial_i u + \alpha_2 u, \psi \rangle \, dx \, dv_Y$$

$$+ \int_Y \langle A \sigma + [A, K](1 - P)u_0, \psi_0 \rangle \, dv_Y$$

$$+ \int_Y \langle A u_0, (1 - P + K^P) \psi_0 \rangle \, dv_Y \quad \text{(6.31)}$$
In particular, if \( \psi_0 \in \ker(1-P+K^\dagger P) \cap H^{1/2}_s(Y) \) then \( w = Au \in L^2(Y \times I) \) satisfies

\[
\int_{Y \times I} \langle w, (\tilde{L} - B_2)\psi \rangle \, dx \, dv_Y = \int_{Y \times I} \langle \tilde{f}_1, \psi \rangle \, dx \, dv_Y + \oint_Y \langle \sigma_1, \psi_0 \rangle \, dv_Y,
\]

for all \( \psi \in H^1(Y \times I) \) such that \( \psi \in \ker(1-P+K^\dagger P) \), where

\[
\tilde{f}_1 = A\tilde{f} + \alpha_1^i \partial_i u + \alpha_2 u \in L^2, \quad \sigma_1 = A\sigma + [A,K](1-P)u_0 \in H^{1/2}_s(Y).
\]

In other words, \( w \in L^2(Y \times I) \) is a weak solution of the problem

\[
(\tilde{L} - B_2)w = \tilde{f}_1, \quad Pw_0 = \sigma_1 + K(1-P)w_0.
\]

By shrinking the boundary layer we may assume \( \|B_2\|_{H^1 \to L^2} \) and \( \|B_2^\dagger\|_{H^1 \to L^2} \) are sufficiently small that the conditions of Theorem 6.4 are met, so \( w = Au \in H^1(Y \times [0,\delta]) \). The equation now gives \( \partial_x u = \tilde{f} - Au - Bu \in H^1 \) and thus \( u \in H^2(Y \times [0,\delta]) \).

### 7 Fredholm properties on compact manifolds

The interior and boundary estimates of § 6 lead to solvability (Fredholm) results, by standard arguments. The main interest lies in identifying the cokernel, and we give a simple necessary and sufficient condition for solvability, in Theorem 7.3. This section treats only compact manifolds, leaving the more difficult case of non-compact manifolds to the following section. Because more detailed descriptions are given in § 8, some of the arguments are only briefly summarised here.

Throughout this section we assume the coefficients \( a^i, j = 1, \ldots, n \) and \( b \) of \( \mathcal{L} \) satisfy the conditions of § 6, namely (3.4),(3.5), (6.2), (6.5), (6.7), (6.9); \( \mathcal{L}^\dagger \) is given by (3.7), and the boundary operators \( K, K^\dagger \) satisfy (5.55,5.56), where \( P = P_\Lambda + P_\hat{\Lambda} \) is a positive spectrum projection of \( A \) (6.10), and \( K, K^\dagger \) are defined by (6.18,6.20).

Recall the Sobolev space \( H^1(M) \) of sections of \( E \) over \( M \) is defined by the norm (3.17)

\[
\|u\|_{H^1(M)}^2 = \int_M (|\nabla u|^2 + |u|^2) \, dv_M,
\]

where lengths are measured using the metric \( \langle \cdot, \cdot \rangle \) on \( E \) and a fixed smooth background metric \( \tilde{g} \) on \( TM \), and the connection \( \nabla \) satisfies (3.18,3.19). Note again that \( \nabla \) need not be compatible with the metric on \( E \), and the space \( H^1(M) \) is independent of the choice of \( \nabla \).

The following basic elliptic estimate extends (3.22) of Theorem 3.7 to manifolds with boundary, using the boundary neighbourhood estimate (6.21) of Theorem 6.4.
Proof: The argument used in Theorem 3.7 to prove the interior estimate (3.22) may be applied using Theorem 6.4, estimate (6.21), to estimate \( \|u_\alpha\|_{H^1(U_\alpha)} \) over boundary neighbourhoods \( U_\alpha \). The remaining details are unchanged. \( \blacksquare \)

Theorem 7.2 The linear operator
\[
(\mathcal{L}, \mathcal{K}) : H^1(M) \to L^2(M) \times PH^{1/2}_*(Y)
\]
is semi-Fredholm (i.e. has finite dimensional kernel and closed range).

Proof: Suppose \( \{u_k\}_1^\infty \) is a sequence in \( \ker(\mathcal{L}, \mathcal{K}) \), normalised by \( \|u_k\|_{H^1(M)} = 1 \). To show the kernel is finite dimensional, it suffices to show there is a subsequence converging in \( H^1(M) \). By Rellich’s lemma there is a subsequence (which we also denote \( u_k \)) which converges strongly in \( L^2(M) \), to \( \bar{u} \in L^2(M) \) say. The elliptic estimate applied to the differences \( u_j - u_k \) shows that the sequence is Cauchy in \( H^1(M) \) and thus converges strongly to \( \bar{u} \in H^1(M) \). Since (7.3) is bounded, it follows that \( \bar{u} \in \ker(\mathcal{L}, \mathcal{K}) \), so the unit ball in the kernel is compact and hence the kernel is finite dimensional.

To show the range is closed, let \( \bar{H}^1(M) \) be the finite codimension subspace of \( H^1(M) \) defined by the condition
\[
\int_M \left( (\nabla u, \nabla \phi) + (u, \phi) \right) dv_M = 0 \quad \forall \ \phi \in \ker(\mathcal{L}, \mathcal{K}).
\]
A Morrey-type argument by contradiction using (7.2) shows there is a constant \( C > 0 \) such that for all \( u \in \bar{H}^1(M) \),
\[
C^{-1} \int_M |u|^2 dv_M \leq \int_M |\mathcal{L}u|^2 dv_M + \int_Y |J\mathcal{K}u_0|^2 dv_Y,
\]
where \( J = (1+|A|)^{1/2} \). Now suppose \( \{u_k\}_1^\infty \subset H^1(M) \) is such that \( \mathcal{L}u_k = f_k \to f \in L^2(M) \) and \( \mathcal{K}(u_k)_0 = s_k \to \sigma \in PH^{1/2}_*(Y) \). (Note that by the definition (6.18) of \( \mathcal{K} \), the range of \( \mathcal{K} \) is a subspace of \( PH^{1/2}_*(Y) \)). Since the kernel is finite dimensional we may normalise \( u_k \in \bar{H}^1(M) \), and then (7.4) and (7.2) show that \( \{u_k\}_1^\infty \) is bounded in \( H^1(M) \). It then follows as above that there is a subsequence converging strongly in \( H^1(M) \) to \( \bar{u} \), and that \( \mathcal{L}\bar{u} = \lim_{k \to \infty} f_k = f \) and \( \mathcal{K}\bar{u}_0 = \lim_{k \to \infty} s_k = \sigma \), so the range of \( (\mathcal{L}, \mathcal{K}) \) is closed. \( \blacksquare \)

The general boundary value problem
\[
\begin{align*}
\mathcal{L}u &= f \quad \text{in } M \\
\mathcal{K}u_0 &= \sigma \quad \text{on } Y
\end{align*}
\]
is solvable for \( u \in H^1(M) \) provided \((f, \sigma)\) satisfies the condition (7.6) of the following main result.
Theorem 7.3 \((f, \sigma) \in \mathcal{L}^2(Y) \times PH_{x}^{1/2}(Y)\) lies in the range of \((\mathcal{L}, \mathcal{K})\) (that is, (7.5) admits a solution \(u \in H^1(M)\)), if and only if

\[
\int_{M} \langle f, \phi \rangle \, dv_M + \oint_{Y} \langle \sigma, \nu \phi_0 \rangle \, dv_Y = 0 \quad \forall \, \phi \in \ker(\mathcal{L}^\dagger, \mathcal{K}^\dagger). \tag{7.6}
\]

Proof: If \(u \in H^1(M)\) satisfies \(\mathcal{L}u = f\) and \(\mathcal{K}u_0 = \sigma\) then \(u\) is also a weak solution. Condition (7.6) then follows directly from the definition 6.3 of weak solution, hence (7.6) is a necessary condition for solvability.

To establish the converse, consider first the case \(\sigma = 0\). Thus we suppose \(f \in \mathcal{L}^2(M)\) satisfies

\[
\int_{M} \langle f, \phi \rangle \, dv_M = 0 \quad \forall \, \phi \in \ker(\mathcal{L}^\dagger, \mathcal{K}^\dagger),
\]

and we must find \(u \in H^1(M)\) satisfying \(\mathcal{L}u = f\), \(\mathcal{K}u_0 = 0\).

By Lemma 5.1 the trace map \(r_Y : u \mapsto u_0\) is bounded, hence

\[
\tilde{H}^1_K := \{ u \in H^1(M) : \mathcal{K}u_0 = 0, \quad \int_{M} \langle \nabla u, \nabla \phi \rangle + \langle u, \phi \rangle \, dv_M = 0 \quad \forall \, \phi \in \ker(\mathcal{L}, \mathcal{K}) \}
\]

is a closed subspace of \(H^1(M)\). The argument of Theorem 7.2 (ii) shows there is a constant \(C\) such that

\[
\int_{M} |\nabla u|^2 + |u|^2 \, dv_M \leq C \int_{M} |\mathcal{L}u|^2 \, dv_M \tag{7.8}
\]

for all \(u \in \tilde{H}^1_K(M)\). In particular, \(\int_{M} |\mathcal{L}u|^2 \, dv_M\) is strictly coercive on \(\tilde{H}^1_K\), so the Lax-Milgram lemma gives \(u \in \tilde{H}^1_K\) satisfying

\[
\int_{M} \langle f, \mathcal{L} \phi \rangle \, dv_M = \int_{M} \langle \mathcal{L}u, \mathcal{L} \phi \rangle \, dv_M
\]

for all \(\phi \in \tilde{H}^1_K\). This equality also holds if \(\phi \in \ker(\mathcal{L}, \mathcal{K})\), so \(\Psi = \mathcal{L}u - f\) satisfies

\[
\int_{M} \langle \Psi, \mathcal{L} \phi \rangle \, dv_M = 0 \quad \forall \, \phi \in H^1(M), \quad \mathcal{K} \phi_0 = 0. \tag{7.9}
\]

Lemma 5.8 and the identity

\[
\int_{M} \langle \Psi, \mathcal{L} \phi \rangle \, dv_M = \int_{M} \langle \mathcal{L}^\dagger \Psi, \phi \rangle \, dv_M - \oint_{Y} \langle \nu \Psi_0, \phi_0 \rangle \, dv_Y \tag{7.10}
\]

show that (7.9) is the weak form of the adjoint problem

\[
\mathcal{L}^\dagger \Psi = 0, \quad \mathcal{K}^\dagger \Psi_0 = 0. \tag{7.11}
\]

By (3.7), \(\mathcal{L}^\dagger\) is elliptic with boundary representation

\[
\mathcal{L}^\dagger = -\nu(\partial_x + \hat{A} + \hat{B}),
\]

where \(\hat{A} = -\nu^{-1} A \nu\) since \(A^\dagger = A\), and \(\hat{B} = -\nu^{-1} B^\dagger \nu\). By (6.8,6.9) the leading terms in \(\hat{A}\) are \(\hat{a}^i \partial_i\) so \(\hat{A}\) is elliptic on \(Y\), and self-adjoint by (6.7). Since \(\hat{A}(\nu^{-1} \phi_\alpha) = -\lambda_\alpha \nu^{-1} \phi_\alpha\) if \(A \phi_\alpha = \lambda_\alpha \phi_\alpha\), we see that \(\hat{A}\) satisfies the spectral properties.
conditions, and \( \text{spec} \hat{A} = -\text{spec} A \). (Note that in the usual case of Dirac operators, \( \hat{A} = A \) and the spectrum is symmetric). Now \( \hat{P} := 1 - \nu^{-1}P_N \) is a positive eigenspace projector for \( \hat{A} \), with eigenvalues \(-\lambda_\alpha\) for \( \alpha \in \Lambda^- \cup (\Lambda^0 \setminus \hat{\Lambda}) \), and the boundary operator satisfies

\[
\mathcal{K}^\dagger \Psi_0 = (\hat{P} + \nu^{-1}K^\dagger \nu (1 - \hat{P})) \Psi_0 .
\]  

(7.12)

Since \( \mathcal{K} = -\nu^{-1}K^\dagger \nu \) maps negative eigenvectors (of \( \hat{A} \)) to positive eigenvectors, it follows that \( \mathcal{K}^\dagger \Psi_0 = 0 \) is an elliptic boundary condition for \( L^\dagger \). The boundedness conditions (5.55, 5.56) for \( \hat{K} \) follow from the corresponding conditions for \( K \).

Since \( (L^\dagger, \mathcal{K}^\dagger) \) is elliptic and satisfies the conditions for Theorem 6.4, we conclude that \( \Psi \in H^1(M) \) and \( \Psi \) satisfies the strong form (7.11).

Since \( \Psi \in \ker(L^\dagger, \mathcal{K}^\dagger) \), assumption (7.6) with \( \sigma = 0 \) gives

\[
\int_M \langle f, \Psi \rangle \, dv_M = 0 .
\]

By construction \( \mathcal{K} u_0 = 0 \), so we may use \( u \) as a test function in the weak form (7.9) of the equation satisfied by \( \Psi \), giving

\[
\int_M \langle L u, \Psi \rangle \, dv_M = 0 .
\]

It follows from \( \Psi = L u - f \) that \( \Psi = 0 \) and thus \( u \) is the required solution.

Now consider the case \( \sigma \neq 0 \). By Lemma 5.1 there is an extension \( v = e_Y(\sigma) \in H^1(M) \) supported in a neighbourhood of \( Y \) such that \( v_0 = \sigma, \|v\|_{H^1(M)} \leq 2\|\sigma\|_{H^{1/2}} \). Let \( \tilde{f} = f - L v \) and consider the equation

\[
L \tilde{u} = \tilde{f}, \quad K \tilde{u}_0 = 0 .
\]  

(7.13)

The previous case shows there is a solution provided \( \tilde{f} \) satisfies

\[
\int_M \langle \tilde{f}, \psi \rangle \, dv_M = 0 \quad \forall \, \psi \in \ker(L^\dagger, \mathcal{K}^\dagger) \subset H^1(M) .
\]

Now (7.10) shows that for all \( \psi \in \ker(L^\dagger, \mathcal{K}^\dagger) \),

\[
\int_M \langle \tilde{f}, \psi \rangle \, dv_M = \int_M \langle f, \psi \rangle \, dv_M - \int_M \langle v, L^\dagger \psi \rangle \, dv_M + \int_Y \langle v_0, \nu \psi_0 \rangle \, dv_Y = \int_M \langle f, \psi \rangle \, dv_M + \int_Y \langle \sigma, \nu \psi_0 \rangle \, dv_Y .
\]

Thus if (7.6) is satisfied then there exists a solution \( \tilde{u} \) of (7.13), and then \( u = \tilde{u} + v \) is the required full solution. This establishes sufficiency for the condition (7.6).

We note two important consequences of Theorems 7.2, 7.3.

**Corollary 7.4** (7.5) admits a solution for all \( (f, \sigma) \in L^2(M) \times PH^{1/2}_\psi(Y) \) if and only if \( \ker(L^\dagger, \mathcal{K}^\dagger) = \{0\} \).
Corollary 7.5 $(L, K) : H^1(M) \to L^2(M) \times PH_s^{1/2}(Y)$ is Fredholm.

Proof: The argument of Theorem 7.3 shows that $(L^\dagger, K^\dagger)$ is elliptic and thus has finite dimensional kernel by Theorem 7.2. Now (7.6) shows that the range of $(L, K)$ has finite codimension. ■

8 Fredholm properties on complete noncompact manifolds

In this section we establish conditions under which the Fredholm and existence results of the previous section for the operator $(L, K) : H^1(M) \to L^2(M) \times H_s^{1/2}(Y)$, may be extended to non-compact manifolds. This includes in particular, a generalisation of the solvability criterion (7.6) of Theorem 7.3. Results of this type may be applied to establish positive mass results in general relativity, for example.

The non-compactness of $M$ causes some difficulties not found in the compact case. A classical result [45, 65] shows that a Dirac operator $D$ on a non-compact manifold is essentially self-adjoint on $L^2(M)$. However, this elegant result is useless for our purposes, since it implies only that $\{(\phi, D\phi) : \phi \in \text{dom} D \subset L^2(M)\}$ is closed in the graph topology on $L^2(M) \times L^2(M)$. This is weaker than the closed range property, which is necessary for useful solvability criteria. In fact, because $L^2(M)$ often does not encompass natural decay rates of solutions, the self-adjoint closure may not have closed range. In such cases the Dirac operator defined on $L^2(M)$ will not be semi-Fredholm. This is shown explicitly in the following example.

Consider the self-adjoint closure $\overline{D} : \text{dom} \overline{D} \subset L^2(\mathbb{R}^3) \to L^2(\mathbb{R}^3)$ of the constant coefficient Dirac operator $D = \gamma^i \partial_i$, and let $f = Du$, $u = (1 - \chi)|x|^{-1}\psi$, where $\chi(r)$ is a smooth compactly supported function identically one around 0 and $\psi$ is a constant spinor on $\mathbb{R}^3$. Clearly $f \in L^2(\mathbb{R}^3)$ but $u \notin L^2(\mathbb{R}^3)$, so in particular, $u \notin \text{dom} \overline{D}$. However, $f$ still lies in the closure of the range of $\overline{D}$, since $D(\chi_R u) = \chi_R f + D\chi_R u \to f$ in $L^2(\mathbb{R}^3)$, where $\chi_R(x) = \chi(x/R)$, but $\chi_R u$ can not converge in $L^2(\mathbb{R}^3)$. Clearly $(u, f) \notin \text{graph} \overline{D}$ since $u \notin L^2(\mathbb{R}^3)$, and it can be shown (using the corresponding Schrödinger-Lichnerowicz identity) that there is no $\tilde{u} \in L^2(\mathbb{R}^3)$ satisfying $D\tilde{u} = f$. Thus the self-adjoint closure $\overline{D}$ does not have closed range.

In order to obtain an operator with closed range, it is thus necessary to enlarge the domain, which raises the question of determining the appropriate decay rate. We sidestep this problem by using the $L^2$ size of the covariant derivative as a norm. To obtain sufficient control on the $L^2_{\text{loc}}$ behaviour, we then must postulate a weighted Poincaré inequality (8.3). The existence of such inequalities can be established for the applications of most interest in general relativity; see Proposition 8.3 and §9.

The elliptic estimate (7.2) plays a central role in the analysis over a compact manifold, but its noncompact analogue cannot be obtained directly by similar localisation arguments. However, in cases of geometric interest an identity of
Schrödinger-Lichnerowicz form (generalising (2.5)) is available, and can be used to construct suitable global estimates.

The weighted Poincaré and Schrödinger-Lichnerowicz estimates are the two additional ingredients needed for establishing solvability and Fredholm properties on a non-compact manifold.

For ease of further reference, let us summarize the hypotheses which will be made throughout this section:

**Hypotheses 8.1** $M$ is a non-compact manifold with compact boundary $Y$, which is complete with respect to a $C^\infty$ background metric $\hat{g}$. The case $Y = \emptyset$ is admitted. The operator $L = a^j \partial_j + b$ satisfies the global uniform ellipticity and boundedness condition

$$\eta^2 |V|^2 \leq \hat{g}_{jk}(a^j(x)V, a^k(x)V) \leq \eta^{-2} |V|^2,$$

(8.1)

for some $\eta > 0$, for all $V \in E_x$ and all $x \in M$. The coefficients of $L$ satisfy the interior regularity conditions (3.4), and the boundary regularity and structure conditions of §6, namely (6.2), (6.5), (6.7), (6.9). Let $A$ be the boundary operator and $P$ its associated positive spectrum projection, as in §6. The boundary operator $K : (1 - P)L^2(Y) \to PL^2(Y)$ satisfies (5.55,5.56), and $K, K^\dagger$ are defined in (6.18,6.20). The connection $\nabla = \partial - \Gamma$ satisfies (3.18,3.19) and we note again that $\nabla$ need not be compatible with the metric on $E$ — this is important in some applications.

We may express $L$ in terms of $\nabla$ by

$$L = a^j \nabla_j + (b + a^j \Gamma_j) = a^j \nabla_j + \beta,$$

where $\beta \in L^\alpha_{loc}(M)$. Additional, rather weak, decay conditions will be imposed on $\beta$ (8.8), on the negative part of the curvature endomorphism $\rho$ (8.13), and on $\Gamma^S = \frac{1}{2}(\Gamma + i\Gamma)$ in §9.

**Definition 8.2** The covariant derivative $\nabla$ on $E$ over $M$ admits a weighted Poincaré inequality if there is a weight function $w \in L^1_{loc}(M)$ with $\text{ess inf}_\Omega w > 0$ for all relatively compact $\Omega \Subset M$, such that for all $u \in C^1_c(M)$ we have

$$\int_M |u|^2 \, w \, dv_M \leq \int_M |\nabla u|^2 \, dv_M.$$

(8.3)

Here the length $|\nabla u|^2$ is measured by the metric on $E$ and the background Riemannian metric $\hat{g}$ on $M$, and $dv_M$ is the volume measure of $\hat{g}$. It is clear that the weight function $w$ can be chosen to be smooth.

The semi-norm

$$\|u\|_{2, \nabla}^2 = \int_M |\nabla u|^2 \, dv_M$$

(8.4)

on $C^\infty_c(M)$ may be completed to form the space

$$\mathbb{H} := \| \cdot \|_{\nabla}:\text{-completion of } C^\infty_c(E),$$

(8.5)
which consists of equivalence classes of $\mathbb{H}$-convergent sequences in $C^\infty_c(M)$. The weighted Poincaré inequality (8.3) ensures that an $\mathbb{H}$-convergent sequence converges locally in $L^2$, so the equivalence classes may be identified with cross-sections in the usual Lebesgue sense: with cross-sections having coefficient functions agreeing $dv_M$–a.e.

If there is no weighted Poincaré inequality, then it may be that $\mathbb{H}$ cannot be identified with a space of Lebesgue-measurable cross-sections in this sense. For example, the trivial spinor bundle over $M = T^2 \times \mathbb{R}$ with the flat connection $\nabla_i = \partial_i$ admits a global parallel spinor $\nabla \psi = 0$ which is approximated in the $\mathbb{H}$-seminorm by $\psi_k = \chi(x/k)\psi$ for $\chi \in C^\infty_c(\mathbb{R})$, $\chi = 1$ on $[-1,1]$. Now $\int_M |\nabla \psi_k|^2 dv_M \to 0$, but $\lim_{k \to \infty} \psi_k = \psi \neq 0$, so the $\mathbb{H}$-equivalence class $[0]$ contains $\psi \neq 0$ everywhere. In other words, (8.4) does not define a norm on spinors in this example. This shows, *inter alia*, that (8.3) will not hold in all cases.

More generally, a weighted Poincaré inequality fails for manifolds of the form $N \times \mathbb{R}$, where $N$ is compact and itself admits a parallel spinor. It follows from the proof of Theorem 9.3 below that in such cases the orthogonal complement in $\mathbb{H}$ of the subspace of all parallel spinors will admit a weighted Poincaré inequality. Note also that the presence of a weighted Poincaré inequality (8.3) does not imply there are no global parallel spinors — $\mathbb{R}^3$ provides a simple counterexample.

However, weighted Poincaré inequalities can be demonstrated in many cases of interest. In the next section we will prove:

**Proposition 8.3** A covariant derivative $\nabla$ on $E$ admits a weighted Poincaré inequality if any one of the following conditions holds:

1. there is a relatively compact domain $\Omega \subset M$ and a constant $c > 0$ such that

   $$\int_\Omega |u|^2 dv_M \leq c \int_M |\nabla u|^2 dv_M$$

   (8.6)

   for all $u \in C^\infty_c(M)$;

2. there are no nontrivial globally parallel sections ($\nabla u = 0 \Rightarrow u = 0$);

3. $M$ has a weakly asymptotically flat end $\widetilde{M}$ (see Definition 9.4), with $\dim M \geq 3$;

4. $M$ has a weakly asymptotically hyperboloidal end (see Definition 9.9), with $\dim M \geq 2$.

When $M$ is non-compact, the global Gårding inequality (generalizing (7.2)) cannot be constructed from local estimates. Motivated by some classical and fundamental identities, we instead introduce the following definition.

**Definition 8.4** The operator pair $(\mathcal{L}, \mathcal{K})$ admits a Schrödinger-Lichnerowicz estimate if there is $C > 0$ and a non-negative function $\rho$ such that

*The function $\rho$ here should not be confused with the energy density arising in general relativity: in Section 11 $\rho$ will be zero.*
\( u \in C^1_c(M) \),

\[
C^{-1} \int_M |\nabla u|^2 \, dv_M \leq \int_M (|\mathcal{L} u|^2 + \rho |u|^2) \, dv_M + \int_Y |J \mathcal{K} u_0|^2 \, dv_Y,
\]

where \( J = (1 + |A|)^{1/2} \).

**Lemma 8.5** Suppose that the Schrödinger-Lichnerowicz estimate (8.7) holds for all \( u \in C^1_c(M) \) with \( \rho \) and \( \beta = \mathcal{L} - a_j \nabla_j \) satisfying \( \rho \in \mathbb{L}^n_{\text{loc}}/2 \), \( \beta \in \mathbb{L}^n_{\text{loc}} \), and

\[
\lim_{R \to \infty} \sup_{M \setminus M_R} \frac{\rho + |\beta|^2}{w} < \infty,
\]

where \( \{M_R\}_{R \to \infty} \) is an exhaustion of \( M \). Then \( \mathcal{L} : \mathbb{H} \to L^2(M) \) is bounded and (8.7) holds for all \( u \in \mathbb{H} \).

**Proof:** It will suffice to show that the individual terms of the right-hand-side of (8.7) are bounded by \( \|u\|^2_{L^2} \). Now

\[
\int_M |\mathcal{L} u|^2 \leq C \int_M |\nabla u|^2 + 2 \int_M |\beta|^2 |u|^2,
\]

and we use (8.8) and (8.3) to estimate

\[
\int_{M \setminus M_R} (\rho + |\beta|^2) |u|^2 \leq \sup_{M \setminus M_R} \frac{\rho + |\beta|^2}{w} \int_{M \setminus M_R} |u|^2 w
\]

\[
\leq \sup_{M \setminus M_R} \frac{\rho + |\beta|^2}{w} \int_{M \setminus M_R} |\nabla u|^2
\]

\[
\leq C \int_M |\nabla u|^2,
\]

for some \( R < \infty \). Let \( \chi_R \in C^\infty_c(M) \) be a cut-off function with support contained in \( M_{2R} \), \( \chi_R = 1 \) on \( M_R \). Then

\[
\int_{M_R} (\rho + |\beta|^2) |u|^2 \leq \int_{M_{2R}} (\rho + |\beta|^2) |\chi_R u|^2
\]

\[
\leq \left( \|\rho\|_{L^{n/2}(M_{2R})} + \|\beta\|_{L^n_{\text{loc}}(M_{2R})} \right) \|\chi_R u\|_{L^n_{\text{loc}}(M_{2R})}^2.
\]

Applying the Sobolev inequality for \( \nabla \) on the compact set \( M_{2R} \) and the weighted Poincaré inequality show that the last term is controlled by \( \int_M |\nabla u|^2 \). Finally, the \( K \)-bound (5.55) and the restriction Lemma 5.1 show that the boundary term is also controlled by \( \int_M |\nabla u|^2 \).

Schrödinger-Lichnerowicz identities hold for many common examples, and can easily be adapted to produce estimates of the form (8.7). We will not attempt to give general conditions which imply such inequalities — it is simpler to ask only that (8.7) be established separately in any particular case of interest.
Proof: Suppose a cutoff function supported in $\bar{Y}$ for some $u$. Lemma 8.5 shows that the estimate in the homogeneous case implies the general estimate $K$ the special case of homogeneous boundary data ($\leq \sqrt{16\pi}/\text{Area}(Y)$), then the argument in §2 shows that the boundary term in (8.10) is not greater than

$$
\int_Y \langle P_+\psi_0, D_Y P_+\psi_0 \rangle d\nu_Y \leq \|K\psi_0\|_{H^{1/2}_Y}^2
$$

and (8.7) follows immediately, with

$$
\rho = \max(0, -\frac{1}{4}R(g)) .
$$

Since $\beta = 0$ in this example, the inequality holds for all $u \in \mathbb{H}$ provided $\rho$ satisfies (8.8). For general mean curvatures $H_Y \in L^{\infty}(Y)$, note again that

$$
\int_Y \langle \psi_0, D_Y \psi_0 \rangle d\nu_Y \leq \|P_+\psi_0\|_{H^{1/2}_Y}^2 .
$$

If $H_Y \in L^{\infty}(Y)$ then $\int_Y |H_Y| \psi_0|^2 \leq \|H_Y\|_{L^{\infty}(Y)} \|J\psi_0\|_{H^{1/2}_Y}^2$. Using a fractional Sobolev inequality, the control on $H_Y$ may be weakened to $H_Y \in L^p(Y)$, $p = n - 1$ for $n \geq 3$ and $p > 1$ for $n = 2$. Lemma 5.1 shows that $\|\psi_0\|_{H^{1/2}_Y} \leq C\|\tilde{\psi}_0\|_{H^1(Y \times I')}$, where $\tilde{\psi} = \chi \psi$ and $\chi = \chi(x)$ is a cutoff function supported in $I' = [0, \delta/2]$, as in the proof of Theorem 6.4. Now Corollary 6.5 shows that

$$
C^{-1}\|\tilde{\psi}\|_{H^1(Y \times I')} \leq \int_{Y \times I} (|D\tilde{\psi}|^2 + |\tilde{\psi}|^2) d\nu_M + \int_Y |JP_+\psi_0|^2 d\nu_Y,
$$

which provides the required Schrödinger-Lichnerowicz estimate (8.7).

In applications, a Schrödinger-Lichnerowicz estimate is usually obtained in the special case of homogeneous boundary data ($Ku_0 = 0$). The above trick shows that the estimate in the homogeneous case implies the general estimate (8.7):

**Lemma 8.6** Under the hypotheses of Lemma 8.5, suppose there is $\tilde{C} > 0$ such that for all $u \in \mathbb{H}$ with $Ku_0 = 0$ we have

$$
\tilde{C}^{-1}\int_M |\nabla u|^2 d\nu_M \leq \int_M (|\mathcal{L}u|^2 + \tilde{\rho}|u|^2) d\nu_M,
$$

for some $\tilde{\rho}$. Then there is $C > 0$ such that (8.7) holds for all $u \in \mathbb{H}$.

**Proof:** Suppose $u \in \mathbb{H}$ and let $\tilde{u} = u - \chi u$, where $\chi = \chi(x) \in C^\infty(M)$ is a cutoff function supported in $Y \times I'$ as in the proof of Theorem 6.4. Then
\[ \mathcal{K}\bar{u}_0 = 0 \] so (8.12) applies to \( \bar{u} \), giving
\[
\int_M |\nabla u|^2 \, d\nu_M \leq 2 \int_M (|\nabla \bar{u}|^2 + |\nabla (\chi u)|^2) \, d\nu_M
\]
\[
\leq C \int_M (|\mathcal{L}\bar{u}|^2 + \bar{\rho}|\bar{u}|^2) \, d\nu_M + 2 \int_{Y \times P} |\nabla (\chi u)|^2 \, d\nu_M
\]
\[
\leq C \int_M (|\mathcal{L}u|^2 + (\bar{\rho} + |d\chi|^2)|u|^2) \, d\nu_M + 2 \int_{Y \times P} |\nabla (\chi u)|^2 \, d\nu_M .
\]

Now it follows easily from Corollary 6.5 that
\[
C^{-1} \int_{Y \times P} |\nabla (\chi u)|^2 \, d\nu_M \leq \int_{Y \times I} (|\mathcal{L}u|^2 + |u|^2) \, d\nu_M + \int_Y |JKu_\theta|^2 \, d\nu_Y,
\]
which gives the required inequality. \( \square \)

**Theorem 8.7** Under the hypotheses 8.1, suppose \((M, \nabla, \mathcal{L}, \mathcal{K})\) admits a weighted Poincaré inequality (8.3) and a Schrödinger-Lichnerowicz inequality (8.7) with \( \rho \) and \( \beta \) satisfying the conditions of Lemma 8.5. If \( \rho \in L_{\text{loc}}^p(M) \) for some \( p > n^*/2 \), and if
\[
\lim_{R \to \infty} \sup_{M \setminus M_R} \frac{\rho}{w} = 0,
\]
where \( \{M_R\}_{R \to \infty} \), is any exhaustion of \( M \), then
\[
(\mathcal{L}, \mathcal{K}) : \mathbb{H} \to L^2(M) \times H^{1/2}_\#(Y)
\]
is semi-Fredholm.

**Proof:** Lemma 8.5 gives \( \mathcal{L}u \in L^2(M) \) for \( u \in \mathbb{H} \). We first show the unit ball in the kernel is compact. Let \( \{u_k\}_{k=1}^\infty \) be a sequence in the kernel of \( (\mathcal{L}, \mathcal{K}) \), normalised by \( \|u_k\|_\mathbb{H} = 1 \). Weak compactness of bounded sets in \( \mathbb{H} \) shows there is \( \bar{u} \in \mathbb{H} \) and a subsequence, which we also denote by \( u_k \), such that \( u_k \rightharpoonup \bar{u} \in \mathbb{H} \) and \( \|\bar{u}\|_\mathbb{H} \leq \liminf \|u_k\|_\mathbb{H} = 1 \).

Since (8.13) is independent of the choice of exhaustion, we may suppose for definiteness that \( M_R = \{x \in M : d(x) < R\} \) where \( d(x) \) is the smoothed distance function from some fixed base point. Let \( \chi \in C^\infty_c(\mathbb{R}) \) satisfy \( \chi(x) = 1 \) for \( x \leq 1 \), \( \chi(x) = 0 \) for \( x \geq 2 \) and \( 0 \leq \chi(x) \leq 1 \), \( |\chi'(x)| \leq 2 \) for all \( x \). Then the functions \( \chi_R(x) = \chi(d(x)/R) \) form support functions for the exhaustion \( M_R \) which satisfy \( \text{supp} \chi_R \subset M_{2R} \), \( \chi_R = 1 \) on \( M_R \) and \( |d\chi_R| \leq 2 \). Using the weighted Poincaré inequality we have
\[
\int_M |\nabla (\chi_R u_k)|^2 \, d\nu_M \leq 2 \int_{M_{2R}\setminus M_R} |d\chi_R|^2 |u_k|^2 \, d\nu_M + 2 \int_{M_{2R}} |\nabla u_k|^2 \, d\nu_M
\]
\[
\leq 2(1 + 2 \sup_{M_{2R}\setminus M_R} w^{-1}) \int_M |\nabla u_k|^2 \, d\nu_M ,
\]
which shows that for any \( R > 1 \) the sequence \( \chi_R u_k \) is bounded in \( H^1(M_{2R}) \). Since \( \chi_R u_k \rightharpoonup \chi_R \bar{u} \) in \( H^1(M_{2R}) \), the Rellich lemma implies \( \chi_R u_k \to \chi_R \bar{u} \) strongly in \( L^q(M_{2R}) \) for any \( q < 2 = 2n/(n-2) \) and any \( R > 1 \).
Applying (8.7) to any difference \( u_j - u_k \) gives
\[
\int_M |\nabla (u_j - u_k)|^2 \, dv_M \leq \int_M \rho |u_j - u_k|^2 \, dv_M
\]
\[
\leq \|ho\|_{L^p(M_R)} \|u_j - u_k\|^2_{L^q(M_R)} + \sup_{M \setminus M_R} \frac{\rho}{w} \int_M |u_j - u_k|^2 \, w \, dv_M
\]
(8.15)
where, since \( p > n^*/2 \), we have \( q = \frac{2p}{p-1} < 2 \). Now (8.3) and \( \|u_k\|_{\mathbb{H}} = 1 \) combine to show that
\[
\int_M |u_j - u_k|^2 \, w \, dv_M \leq 4,
\]
so by (8.13), for any \( \epsilon > 0 \) there is \( R = R(\epsilon) \) such that the second term of (8.15) is less than \( \epsilon/2 \) for all \( j, k \). Since \( u_k \) converges in \( L^q(M_R) \) there is \( N = N(\epsilon, R) \) such that the first term is less than \( \epsilon/2 \) for all \( j, k \geq N \). This shows \( u_k \) is a Cauchy sequence, hence strongly convergent to \( \bar{u} \), in \( \mathbb{H} \).

As noted above, \( \|Lu\|_{L^2(M)} \leq C\|u\|_{\mathbb{H}} \) and thus
\[
\int_M |\mathcal{L}u|^2 \, dv_M = \int_M |\mathcal{L}(\bar{u} - u_k)|^2 \, dv_M
\]
\[
\leq C \int_M |\nabla (\bar{u} - u_k)|^2 \, dv_M
\]
\[
\to 0 \quad \text{as } k \to \infty,
\]
which shows that \( \mathcal{L}\bar{u} = 0 \). Similarly, since \( \mathcal{K} : H^{1/2}_s(Y) \to H^{1/2}_s(Y) \) is bounded, for any \( u \in \mathbb{H} \) we have
\[
\oint_Y |J\mathcal{K}u_0|^2 \, dv_Y \leq c\|\mathcal{K}u_0\|_{H^{1/2}_s(Y)} \leq ck\|u_0\|_{H^{1/2}_s(Y)}
\]
\[
\leq C \int_M |\nabla u|^2 \, dv_M,
\]
by (5.55) and the trace lemma 5.1. Choosing \( u = \bar{u} - u_k \) gives
\[
\oint_Y |J\mathcal{K}\bar{u}_0|^2 \, dv_Y \leq c \int_M |\nabla (\bar{u} - u_k)|^2 \, dv_M = o(1),
\]
which shows also that \( \mathcal{K}\bar{u}_0 = 0 \). Thus \( \bar{u} \in \ker(\mathcal{L}, \mathcal{K}) \) and the kernel is finite dimensional.

To show the closed range property, observe that by (8.13) and (8.3), the elliptic estimate (8.7) may be strengthened to
\[
C^{-1} \int_M (|\nabla u|^2 + |u|^2 w) \, dv_M \leq \int_M |\mathcal{L}u|^2 \, dv_M + \int_M \rho |u|^2 \, dv_M + \oint_Y |J\mathcal{K}u_0|^2 \, dv_Y,
\]
(8.16)
for some relatively compact domain \( \Omega \subset M \). Now we claim there is a constant \( C > 0 \) such that
\[
\int_\Omega \rho |u|^2 \, dv_M \leq C \left( \int_M |\mathcal{L}u|^2 \, dv_M + \oint_Y |J\mathcal{K}u_0|^2 \, dv_Y \right),
\]
(8.17)
for all \( u \in \mathbb{H} \) such that
\[
\int_M \langle \nabla u, \nabla \phi \rangle \, dv_M = 0 \quad \forall \, \phi \in \ker(\mathcal{L}, \mathcal{K}).
\] (8.18)

Suppose (8.17) fails, so there is a sequence \( u_k \in \mathbb{H}, \, k = 1, 2, \ldots, \) such that (8.18) holds for each \( u_k, \) and
\[
\int_{\Omega} |\rho|u_k|^2 \, dv_M = 1, \quad \int_M |\mathcal{L}u_k|^2 \, dv_M + \oint_Y |J\mathcal{K}(u_k)|^2 \, dv_Y \leq 1/k.
\]
The sequence is bounded in \( \mathbb{H} \) by (8.16), so by passing to a subsequence we may assume \( u_k \) converges weakly to \( \bar{u} \in \mathbb{H} \) and strongly in \( L^q(\Omega), \, q = 2p/(p-1) < 2 \) as before. Applying (8.16) to \( u_j - u_k \) shows the sequence is Cauchy and thus converges strongly in \( \mathbb{H}. \) It follows that
\[
\int_M |\mathcal{L}\bar{u}|^2 \, dv_M + \oint_Y |J\mathcal{K}\bar{u}_0|^2 \, dv_Y = 0,
\]
so \( \bar{u} \in \ker(\mathcal{L}, \mathcal{K}). \) Strong convergence shows that (8.18) is also satisfied by \( \bar{u}, \) so testing (8.18) for \( \bar{u} \) with \( \phi = \bar{u} \) shows that \( \bar{u} = 0. \) However, strong convergence in \( L^q(\Omega) \) shows that \( \int_{\Omega} |\rho|\bar{u}|^2 \, dv_M = 1, \) which is a contradiction and establishes the claim (8.17).

Combining (8.17) with (8.16) gives
\[
\int_M (|\nabla u|^2 + |u|^2 w) \, dv_M \leq C \left( \int_M |\mathcal{L}u|^2 \, dv_M + \oint_Y |J\mathcal{K}u|^2 \, dv_Y \right)
\] (8.19)
for all \( u \in \mathbb{H} \) satisfying (8.18). Now suppose \( u_k \in \mathbb{H} \) is a sequence such that \( \mathcal{L}u_k = f_k \to f \in L^2(M) \) and \( \mathcal{K}(u_k)^0 = s_k \to s \in H^{1/2}_s(Y). \) These convergence properties are retained if we replace \( u_k \) by \( u_k + y_k \) for any convergent sequence \( y_k \in \ker(\mathcal{L}, \mathcal{K}), \) so we may assume the \( u_k \) all satisfy (8.18). In particular, applying (8.19) to \( u_j - u_k \) shows that \( u_k \) is Cauchy in \( \mathbb{H} \) and converges to \( \bar{u} \) satisfying \( \mathcal{L}\bar{u} = f, \, \mathcal{K}\bar{u}_0 = s. \) This shows \( (\mathcal{L}, \mathcal{K}) \) has closed range.

By Definition 6.3, \( u \) is a weak solution of
\[
\mathcal{L}u = f, \quad \mathcal{K}u_0 = \sigma,
\] (8.20)
for \( f \in L^2(M), \, \sigma \in PH^1_s(Y), \) if \( u \in L^2_{\text{loc}}(M) \) and
\[
\int_M \langle u, \mathcal{L}^\dagger \phi \rangle \, dv_M = \int_M \langle f, \phi \rangle \, dv_M + \oint_Y \langle \sigma, \nu \phi_0 \rangle \, dv_Y,
\] (8.21)
for all \( \phi \in H^1_s(M) \) such that \( \mathcal{K}^\dagger \phi_0 = 0. \) Similarly, the argument of Theorem 7.3 shows that the weak form of the adjoint problem
\[
\mathcal{L}^\dagger u = g, \quad \mathcal{K}^\dagger u_0 = \tau,
\] (8.22)
for \( g \in L^2(M), \, \tau \in PH^1_s(Y), \) \( \hat{P} = 1 - \nu^{-1}P\nu, \) is that \( u \in L^2_{\text{loc}}(M) \) and
\[
\int_M \langle u, \mathcal{L} \phi \rangle \, dv_M = \int_M \langle g, \phi \rangle \, dv_M - \oint_Y \langle \tau, \nu^{-1} \phi_0 \rangle \, dv_Y
\] (8.23)
for all \( \phi \in H^1_s(M) \) such that \( \mathcal{K} \phi_0 = 0. \)

We now extend the solvability criterion (Fredholm alternative) of Theorem 7.3 to the non-compact case.
Theorem 8.8 Under the conditions of Theorem 8.7, suppose the formal adjoint \((L^\dagger, K^\dagger)\) also satisfies a Schrödinger-Lichnerowicz estimate (8.7) with the same covariant derivative \(\nabla\) and with a curvature term \(\hat{\rho}\) satisfying (8.13). Then the system (8.20) with \((f, \sigma) \in L^2(M) \times PH^{1/2}(Y)\) has a solution \(u \in \mathbb{H}\) if and only if \((f, \sigma)\) satisfies
\[
\int_M \langle f, \phi \rangle \, dv_M + \oint_Y \langle \sigma, \nu \phi_0 \rangle \, dv_Y = 0 ,
\]
for all \(\phi \in \mathbb{H} \cap L^2(M)\) satisfying \(L^\dagger \phi = 0, K^\dagger \phi_0 = 0\). In particular, the system (8.20) is solvable for all \((f, \sigma) \in L^2(M) \times PH^{1/2}(Y)\) if and only if there are no \(0 \neq \Psi \in \mathbb{H} \cap L^2(M)\) satisfying \(L^\dagger \Psi = 0, K^\dagger \Psi_0 = 0\).

Remark 8.9 We emphasise that in Theorem 8.8 it is not necessary to impose conditions on \(\hat{\rho}\) other than (8.13), and no conditions on the map \(\hat{\beta} := L^\dagger - \dot{t}a^i \nabla_i\) are needed.

Remark 8.10 See Theorem 11.9 for an example where \(L^\dagger \neq L\), with \(L^\dagger\) satisfying two Lichnerowicz-Schrödinger identities with respect to two different connections.

Proof: The necessity of (8.24) follows immediately from the weak form (8.21). To show sufficiency, the argument of Theorem 7.3 applies to reduce to the case \(\sigma = 0\), which we now consider.

Let \(\mathbb{H}_K = \{u \in \mathbb{H} : K u_0 = 0\}\). The elliptic estimate (8.7) gives
\[
\int_M |\nabla u|^2 \, dv_M \leq C \int_M (|L u|^2 + |\rho| u|^2) \, dv_M , \quad \forall u \in \mathbb{H}_K .
\]
The arguments used to show (8.16) and (8.17) apply and give
\[
\int_M |\nabla u|^2 \, dv_M \leq C \int_M |L u|^2 \, dv_M \quad \forall u \in \mathbb{H}_K ,
\]
where we define
\[
\mathbb{H}_K := \{u \in \mathbb{H}_K : \int_M \langle \nabla u, \nabla \phi \rangle \, dv_M = 0 \quad \forall \phi \in \ker(L, K)\} .
\]
Thus the bilinear form \(u \mapsto \int_M |L u|^2 \, dv_M\) is strictly coercive on the Hilbert space \(\mathbb{H}_K\), and for each \(f \in L^2(M)\) the map \(\phi \mapsto \int_M \langle f, L \phi \rangle \, dv_M\) is bounded on \(\mathbb{H}_K\). The Lax-Milgram lemma shows there is \(u \in \mathbb{H}_K\) satisfying
\[
\int_M \langle L u, L \phi \rangle \, dv_M = \int_M \langle f, L \phi \rangle \, dv_M \quad \forall \phi \in \mathbb{H}_K .
\]
Thus setting \(\Psi = L u - f\) we have
\[
\int_M \langle \Psi, L \phi \rangle \, dv_M = 0 \quad \forall \phi \in \mathbb{H}_K ,
\]
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since \( \phi \in \ker(\mathcal{L}, \mathcal{K}) \) will also satisfy the relation (8.27). Lemma 8.5 shows that \( \Psi \in L^2(M) \) and from Definition 6.3 and (8.27) we see that \( \Psi \) is a weak solution of
\[
\mathcal{L}^\dagger \Psi = 0, \quad \mathcal{K}^\dagger \Psi = 0.
\]
If there are no such non-trivial \( \Psi \) then \( \mathcal{L}u = f \), and \( u \) is the required solution.

The arguments of Theorem 7.3 show that \((\mathcal{L}^\dagger, \mathcal{K}^\dagger)\) is elliptic and Theorem 6.4 applies to show \( \Psi \in H^1_{\text{loc}}(M) \). Let \( M_R \) be the exhaustion of \( M \) constructed in Theorem 8.7, with associated cutoff functions \( \chi_R \in C^\infty(M) \), and let \( \Psi_k = \chi_k \Psi \in H^1(M) \subset \mathbb{H} \). The assumed Schrödinger-Lichnerowicz estimate (8.7) for \((\mathcal{L}^\dagger, \mathcal{K}^\dagger)\) gives (with \( \mathcal{L}^\dagger \) curvature term \( \hat{\rho} \))
\[
\int_M |\nabla(\Psi_k - \Psi_l)|^2 \, dv_M \leq C \int_M \left( |\mathcal{L}^\dagger(\Psi_k - \Psi_l)|^2 + \hat{\rho}|\Psi_k - \Psi_l|^2 \right) \, dv_M. \tag{8.28}
\]
Since \( \mathcal{L}^\dagger \Psi = 0 \) we have
\[
\int_M |\mathcal{L}^\dagger(\Psi_k - \Psi_l)|^2 \, dv_M \leq c \int_M \left( |d\chi_k|^2 |\Psi|^2 + |d\chi_l|^2 |\Psi|^2 \right) \, dv_M \to 0,
\]
because \( \Psi \in L^2(M), \ |d\chi_k| \leq 2 \) and \( \text{supp} \, d\chi_k \subset M_{2k} \setminus M_k \). Now
\[
\int_M \hat{\rho}|\Psi_k - \Psi_l|^2 \, dv_M \leq \epsilon \int_M |\Psi_k - \Psi_l|^2 \, w \, dv_M
\]
by the condition (8.13) on \( \hat{\rho} \), for sufficiently large \( k,l \). By the weighted Poincaré inequality (8.3), this is in turn bounded by \( \epsilon \) times the left side of (8.28) and may therefore be discarded in (8.28) by choosing \( \epsilon \) sufficiently small. It follows that \( \Psi_k \) is a Cauchy sequence in \( H^1 \), so \( \Psi \in H^1_{\text{loc}} \) and thus \( \mathcal{L}^\dagger \Psi = 0, \mathcal{K}^\dagger \Psi = 0 \).

If there is no such \( \Psi \neq 0 \) then \( \mathcal{L}u = f \), and \( u \) is the required solution. More generally we have \( \mathcal{L}u = f + \Psi, \ u \in \mathbb{H} \), and since \( \int_M (\mathcal{L}u, \Psi) \, dv_M = 0 \) by (8.27), the condition (8.24) (with \( \sigma = 0 \) and \( \phi = \Psi \)) shows that \( \Psi = 0 \) and we have solved \( \mathcal{L}u = f \), as required.

\section{9 Weighted Poincaré Inequalities}

Before proceeding with the analysis, define the \textit{symmetric part} \( \Gamma^S \) of the connection \( \nabla \) by the formula
\[
\langle \phi, \Gamma^S(X) \psi \rangle := \frac{1}{2} \left( X \langle \phi, \psi \rangle - \langle \phi, \nabla_X \psi \rangle - \langle \nabla_X \phi, \psi \rangle \right), \tag{9.1}
\]
for all smooth sections \( \phi, \psi \) of \( E \) and all smooth vector fields \( X \): One easily checks that (9.1) defines a linear map \( \Gamma^S(X) \) from fibers of \( E \) to fibers of \( E \), symmetric with respect to the scalar product \( \langle \cdot, \cdot \rangle \), with the map \( X \to \Gamma^S(X) \) being linear as well. Clearly, \( \nabla \) is compatible with \( \langle \cdot, \cdot \rangle \) if and only if \( \Gamma^S \) vanishes. If \( \Gamma \) is defined by (8.2), then
\[
\Gamma^S = \frac{1}{2}(\Gamma + \mathcal{I} \Gamma).
\]

We establish Proposition 8.3 via a special case, based on an argument of Geroch–Perng [32]:

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Lemma 9.1 Let $\Omega, \tilde{\Omega}$ be any two relatively compact domains in $M$, and assume that
\[ \Gamma^S \in L^*_{\text{loc}}(M). \] (9.2)
There is a constant $\epsilon > 0$ such that for all sections $u \in H^1_{\text{loc}}(M)$ of $E$ we have
\[ \epsilon \int_{\Omega} |u|^2 \, dv_M \leq \int_{\Omega} |u|^2 \, dv_M + \int_M |\nabla u|^2 \, dv_M. \] (9.3)

Proof: Let $q$ be any point of $\tilde{\Omega}$, fix $p \in \Omega$ and let $r_p$ be small enough that the $\hat{g}$-geodesic ball $B(p, r_p)$ of radius $r_p$ and centred at $p$, lies within $\Omega$. Let $X$ be a $C^\infty$ compactly supported vector field, such that the associated flow $\phi_t$ satisfies $\phi_t(B(p, r_p)) \supset B(q, r_q)$ for some $r_q > 0$. (Since $M$ is $C^\infty$ and connected, it is always possible to construct such an $X$.) Let $\Omega_t = \phi_t(B(p, r_p))$.

By direct calculation and Hölder’s inequality we have, for any $u \in H^1_{\text{loc}}(M)$,
\[
\frac{d}{dt} \int_{\Omega_t} |u|^2 \, dv_M = \int_{\Omega_t} (2\langle u, (\nabla_X + \Gamma^S)u \rangle + |u|^2 \text{div}_\hat{g}X) \, dv_M \\
\leq C \left( \int_{\Omega_t} (|u|^2 + |\nabla u|^2) \, dv_{\hat{g}} + ||\Gamma^S||_{L^{n+2}(\Omega_t)} ||u||^2_{L^2(\Omega_t)} \right),
\]
where $C$ depends on $||X||_{L^\infty}$, $||\text{div}_\hat{g}X||_{L^\infty}$. By the Sobolev inequality in the coordinate ball $\Omega_t$ for functions, $||f||_{L^2(\Omega_t)} \leq C(||\partial f||_{L^2(\Omega_t)} + ||f||_{L^2(\Omega_t)})$. Applying this to $f = |u|$ gives $||u||_{L^2(\Omega_t)} \leq C(||Du||_{L^2(\Omega_t)} + ||u||_{L^2(\Omega_t)})$, where $D$ is any metric-compatible connection. Since $\Gamma^S \in L^*_{\text{loc}}$ may be written as $\Gamma_1 + \Gamma_2$, $\Gamma_1 \in L^\infty$, $||\Gamma_2||_{L^{n+*}} \leq \epsilon$, the Sobolev inequality gives
\[ ||u||_{L^2(\Omega_t)} \leq C \left( ||\nabla u||_{L^2(\Omega_t)} + ||u||_{L^2(\Omega_t)} \right), \]
for some constant $C$ depending on $\Gamma$. Defining $F(t) = \int_{\Omega_t} |u|^2 \, dv_{\hat{g}}$, we have
\[ \frac{d}{dt} F(t) \leq CF(t) + C \int_M |\nabla u|^2 \, dv_M, \]
and Gronwall’s lemma gives $F(1) \leq e^{C} F(0) + \int_M |\nabla u|^2 \, dv_M$. Thus there is $\epsilon > 0$ such that
\[ \epsilon \int_{B(q, r_q)} |u|^2 \, dv_M \leq \int_{\Omega} |u|^2 \, dv_M + \int_M |\nabla u|^2 \, dv_M. \]
Since $\tilde{\Omega}$ has compact closure, it is covered by finitely many such balls $B(q, r_q)$ and (9.3) follows.

Corollary 9.2 Under condition (9.2), if there is a domain $\Omega \subset M$ and a constant $\epsilon > 0$ such that
\[ \epsilon \int_{\Omega} |u|^2 \, dv_M \leq \int_{\Omega} |\nabla u|^2 \, dv_M \] (9.4)
for all $u \in C^1_c(M)$, then $M$ admits a weighted Poincaré inequality (8.3).
Proof: By paracompactness and Lemma 9.1, there is a countable locally finite covering of \( M \) by domains \( \Omega_k \) and constants \( 1 \geq \epsilon_k > 0, \ k \in \mathbb{Z}^+ \), such that for each \( k \),
\[
\epsilon_k \int_{\Omega_k} |u|^2 \, dv_M \leq \int_{\Omega} |u|^2 \, dv_M + \int_M |\nabla u|^2 \, dv_M .
\]
This is in turn bounded uniformly by (9.4), so the function
\[
w(x) = \sum_{k: x \in \Omega_k} \frac{2^{-k} \epsilon \epsilon_k}{1 + \epsilon}
\]
is bounded, strictly positive, and satisfies
\[
\int_M |u|^2 \, w \, dv_M \leq \int_M |\nabla u|^2 \, dv_M ,
\]
which is the required weighted Poincaré inequality.

This establishes part (i) of Proposition 8.3, and we next turn to the proof of part (ii).

**Theorem 9.3** Suppose that \( M \) has a locally finite cover such that
\[
\nabla_i = \partial_i - \Gamma_i , \quad \text{with} \quad \Gamma_i \in L^\infty_{\text{loc}} .
\]
If there are no global \( \nabla \)-parallel sections of the bundle \( E \), then \( M \) admits a weighted Poincaré inequality. Equivalently, if \( M \) does not admit a weighted Poincaré inequality then \( M \) admits a global \( \nabla \)-parallel section.

Proof: Assume \( M \) does not admit a weighted Poincaré inequality, so by Corollary 9.2, for each domain \( \Omega \subset M \) and each constant \( \epsilon > 0 \), there is \( u \in H^1_{\text{loc}}(M) \) such that (9.4) fails. In particular, fixing \( \Omega \), for each \( k > 0 \) there is \( u_k \in H^1_{\text{loc}}(M) \) such that
\[
\int_M |u_k|^2 \, dv_M = 1 , \quad \int_M |\nabla u_k|^2 \, dv_M \leq k^{-1} .
\]
It follows that \( \nabla u_k \to 0 \) strongly in \( L^2(M) \). Under (9.6) Rellich’s lemma holds, so there is a subsequence converging strongly to \( u \in L^2(\Omega) \). Then \( \nabla u = 0 \) and \( u \neq 0 \) in \( \Omega \).

Now let \( M_j, \ j = 1, 2, \ldots \) be the exhaustion of \( M \) from Theorem 8.7, and let \( u_j \in H^1(M_j) \) be the corresponding parallel spinors, constructed in the preceding paragraph. Since \( u_j \neq 0 \) there is \( M'_j \subset M_j \) such that \( \int_{M'_j} |u_j|^2 \neq 0 \). Lemma 9.1 applied with \( M_j \) replacing \( M \) shows there is \( \eta_j > 0 \) such that for all \( v \in H^1_{\text{loc}}(M_j) \),
\[
\eta_j \int_{M'_j} |v|^2 \, dv_M \leq \int_{M_0} |v|^2 \, dv_M + \int_{M_j} |\nabla v|^2 \, dv_M .
\]
In particular this implies \( \int_{M_j} |u_j|^2 \, dv_M \neq 0 \) and we may impose the normalisation \( \int_{M_j} |u_j|^2 \, dv_M = 1 \). By Rellich’s lemma there is \( \bar{u}_1 \in H^1(M_1) \) and a subsequence, also denoted by \( u_j \), such that \( u_j \to \bar{u}_1 \) in \( H^1(M_1) \) and \( \int_{M_1} |\bar{u}_1|^2 = 1, \ \nabla \bar{u}_1 = 0 \).
Again by Lemma 9.1, for each $k \geq 1$ there is $\epsilon_k > 0$ such that

$$\epsilon_k \int_{M_k} |v|^2 \, dv_M \leq \int_{M_1} |v|^2 \, dv_M + \int_{M_{k+1}} |\nabla v|^2 \, dv_M, \quad \forall v \in H^1_{0,loc}(M_{k+1}) .$$

Setting $v = u_i - u_j$, $i,j > k$, shows that the sequence $u_j$ is Cauchy in $L^2(M_k)$ and therefore converges strongly in $L^2(M_k)$ for all $k \geq 1$ to some nontrivial $\tilde{u} \in L^2_{0,loc}(M)$, and $\nabla \tilde{u} = 0$.

Another application of Corollary 9.2 leads to Proposition 8.3 part 3, for asymptotically flat manifolds. In fact the proof works for a much broader class of manifolds:

**Definition 9.4** A weakly asymptotically flat end $\tilde{M} \subset M$ of a Riemannian manifold $M$ with metric $g$ is a connected component of $M \setminus K$ for some compact set $K$, such that $\tilde{M} \simeq \mathbb{R}^n \setminus B(0,1)$ and there is a constant $\eta > 0$ such that

$$\eta \delta_{ij} \xi^i \xi^j \leq g_{ij}(x) \xi^i \xi^j \leq \eta^{-1} \delta_{ij} \xi^i \xi^j ;$$

for all $x \in \mathbb{R}^n \setminus B(0,1)$ and all vectors $\xi \in \mathbb{R}^n$.

**Theorem 9.5** Suppose $(M,g)$ is a (connected) Riemannian manifold of dimension $n \geq 3$, $g \in C^0(M)$, and $M$ has a weakly asymptotically flat end $\tilde{M}$. Suppose also the connection $\nabla_i = \partial_i - \Gamma_i$ on $E$ satisfies $\Gamma \in L^\infty_{0,loc}(M)$ and the decay conditions

$$\|r^{-1} \Gamma^S\|_{L^{n/2}(\tilde{M})} + \|\Gamma^S\|_{L^n(\tilde{M})} < \infty ,$$

where $\Gamma^S$ is the symmetric, scalar product incompatible, component of $\nabla$ defined by Equation (9.1). Then $M$ admits a weighted Poincaré inequality.

**Remark 9.6** The restriction $\dim M \geq 3$ is rather harmless as far as the applications to the positive mass theorems are concerned, since the notion of asymptotic flatness for two dimensional manifolds, relevant to general relativistic applications, has to be defined in a completely different way. An adequate analogue of mass here when $\dim M = 2$ is provided by the Shiohama theorem [57].

**Remark 9.7** The decay condition (9.8) is independent of the choice of flat background metric $\tilde{g}_{ij} = \delta_{ij}$: Equation (9.1) shows that $\Gamma^S$ is a tensor. By comparison with the $g$-distance function from any chosen point $p$, the function $r$ is equivalent to this distance function, which implies the result.

**Remark 9.8** The proof below establishes the inequality (9.4) for spinors supported in $\Omega := \mathbb{R}^3 \setminus B(0,R)$ for some $R$ without assuming that $\Gamma \in L^\infty_{0,loc}(M)$.

**Proof:** Let $r = (\sum (x^i)^2)^{1/2} \in C^\infty(\tilde{M})$ and $\chi = \chi(r) \in C^1_c(\tilde{M})$ satisfy, for some $R_0 > 1$ and $k \geq 10$,

$$\chi(r) = \frac{\log(r/R_0)}{\log k}, \quad 2R_0 \leq r \leq (k-1)R_0$$

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and \( \chi(r) = 1 \) for \( r > kR_0 \), \( \chi(r) = 0 \) for \( r \leq R_0 \). Then \( |\chi'(r)| \leq 2/(r \log k) \), so for any section \( u \in C^1_c(M) \)

\[
\int_M |\nabla(\chi u)|^2 \, dv_M \leq 2 \int_M |\nabla u|^2 \, dv_M + \frac{4}{(\log k)^2} \int_{R_0 \leq r \leq kR_0} \frac{1}{r^2} |u|^2 \, dv_M . \tag{9.9}
\]

Now \( \Delta_0 (r^{2-n}) = 0 \) for \( r \geq 1 \) in \( \mathbb{R}^n \), \( n \geq 3 \), so for any \( v \in C^1_c(\mathbb{R}^n \setminus B(0, R_0)) \) we have

\[
0 = -\int_{\mathbb{R}^n} \partial_i(\partial_i (r^{2-n}) |v|^2 r^{n-2}) \, dx
= (n-2)^2 \int_{\mathbb{R}^n} r^{-2} |v|^2 \, dx + (n-2) \int_{\mathbb{R}^n} r^{-1} 2\langle v, (\nabla r + \Gamma^S_r)v \rangle \, dx ,
\]

where \( \Gamma^S_r = r^{-1} x^i \Gamma^S_{ir} \) and lengths are measured by \( \tilde{g} \) and the metric on \( E \). Using Hölder’s inequality we obtain

\[
\frac{(n-2)^2}{4} \int_{\mathbb{R}^n} r^{-2} |v|^2 \, dx \leq \int_{\mathbb{R}^n} |\nabla v|^2 \, dx + (n-2) \int_{\mathbb{R}^n} r^{-1} |v|^2 |\Gamma^S_r| \, dx .
\]

The Sobolev inequality in \( \mathbb{R}^n \), \( n \geq 3 \),

\[
\left( \int_{\mathbb{R}^n} |v|^2 \, dx \right)^{1-2/n} \leq C_S \int_{\mathbb{R}^n} |Dv|^2 \, dx ,
\]

where \( D = \nabla + \Gamma^S \) is the metric-compatible connection, gives the estimate

\[
\int_{\mathbb{R}^n} |Dv|^2 \, dx \leq 2 \int_{\mathbb{R}^n} (|\nabla v|^2 + |v|^2 |\Gamma^S|^2) \, dx
\leq 2 \int_{\mathbb{R}^n} |\nabla v|^2 \, dx + 2 C_S \|\Gamma^S\|_{L^2(\mathbb{R}^n \setminus B(0, R_0))} \int_{\mathbb{R}^n} |Dv|^2 \, dx
\leq 4 \int_{\mathbb{R}^n} |\nabla v|^2 ,
\]

provided \( 2C_S \|\Gamma^S\|_{L^2(\mathbb{R}^n \setminus B(0, R_0))} \leq \frac{1}{4} \). Now (9.8) implies there is \( R_0 < \infty \) such that this condition will be satisfied, so for any \( v \in C^1_c(\mathbb{R}^n \setminus B(0, R_0)) \) we have

\[
\int_{\mathbb{R}^n} r^{-1} |\Gamma^S_r|^2 |v|^2 \, dx \leq \|r^{-1} \Gamma^S\|_{L^{n/2}(\mathbb{R}^n)} C_S \int_{\mathbb{R}^n} |Dv|^2 \, dx
\leq 4 C_S \|r^{-1} \Gamma^S\|_{L^{n/2}(\mathbb{R}^n)} \int_{\mathbb{R}^n} |\nabla v|^2 \, dx .
\]

Hence there is \( \epsilon > 0 \) such that for all \( v \in C^1_c(\bar{M} \cap \{ r > R_0 \}) \),

\[
\epsilon \int_{\bar{M}} r^{-2} |v|^2 \, dv_M \leq \int_{\bar{M}} |\nabla v|^2 \, dv_M . \tag{9.10}
\]

Combining (9.10) with \( v = \chi u \) and (9.9) gives

\[
\int_{\{ r > kR_0 \}} r^{-2} |u|^2 \, dv_M \leq \int_{\bar{M}} r^{-2} |\chi u|^2 \, dv_M
\leq C \int_{\bar{M}} |\nabla (\chi u)|^2 \, dv_M
\leq C \int_{\bar{M}} |\nabla u|^2 \, dv_M + \frac{C}{(\log k)^2} \int_{\bar{M}} r^{-2} |u|^2 \, dv_M ,
\]

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where now $|\nabla u|^2 = g^{ij}(\nabla_i u, \nabla_j u)$. If $k$ is chosen so that $C/(\log k)^2 \leq \frac{1}{2}$ then the last term may be absorbed into the left hand side, giving

$$
\int_{r \geq kR_0} r^{-2}|u|^2 \, dv_M \leq C \int_M |\nabla u|^2 \, dv_M .
$$

(9.11)

Lemma 9.1 now applies and gives the required weighted Poincaré inequality.

In order to prove part 4. of Proposition 8.3 the following Definition is needed:

**Definition 9.9** A weakly hyperboloidal end $\tilde{M} \subset M$ is a connected component of $M \backslash K$ for some compact set $K$, such that $\tilde{M} \simeq (0, x_0) \times \mathcal{N}$, where $(\mathcal{N}, h)$ is a (boundaryless) compact Riemannian manifold with continuous metric $h$, with $g|_{\tilde{M}}$ being uniformly equivalent to $\tilde{g} \equiv x^{-2}(dx^2 + h)$.

Here $x$ is the coordinate running along the $(0, x_0)$ factor of $(0, x_0) \times \mathcal{N}$.

We have the following hyperboloidal counterpart of Theorem 9.5:

**Theorem 9.10** Suppose $(M, g)$ is a (connected) Riemannian manifold of dimension $n \geq 2$, $g \in C^0(M)$, and $M$ has a weakly hyperboloidal end $\tilde{M}$. Suppose also the connection $\nabla_i = \partial_i - \Gamma_i$ on $E$ satisfies $\Gamma \in L^n_{\text{loc}}(M)$ and the decay condition

$$
\limsup_{x \to 0} |x \Gamma^S_x| < \frac{n-1}{2}
$$

(9.12)
in $\tilde{M}$, where $\Gamma^S_x$ is the symmetric part of $\nabla \partial_x$, with norm understood as that of an endomorphism of fibres of $E$. Then $M$ admits a weighted Poincaré inequality.

**Proof:** This is essentially McKean’s inequality [49]; we follow the proof in [22]. Let, first, $f$ be a function in $C^1([0, x_0] \times \mathcal{N})$ with $f = 0$ at $\{x = 0\}$; we have

$$
f^2(x, v) = 2 \int_0^x f(s, v) \frac{\partial f(s, v)}{\partial x} \, ds \leq \frac{n-1}{2} \int_0^x f^2(s, v) \, ds + \frac{2}{n-1} \int_0^x s \left( \frac{\partial f}{\partial x}(s, v) \right)^2 \, ds .
$$

(9.13)

Here we use the symbol $v$ to label points in $\mathcal{N}$. Integrating on $[0, x_0] \times \mathcal{N}$, a change of the order of integration in $x$ and $s$ together with some obvious manipulations gives

$$
\int_{[0, x_0] \times \mathcal{N}} f^2 x^{-n} \, dx \, d\mu_h \leq \frac{4}{(n-1)^2} \int_{[0, x_0] \times \mathcal{N}} \left( x \frac{\partial f}{\partial x} \right)^2 x^{-n} \, dx \, d\mu_h
$$

$$
\leq \frac{4}{(n-1)^2} \int_{[0, x_0] \times \mathcal{N}} \tilde{g}(df, df) x^{-n} \, dx \, d\mu_h .
$$

(9.14)

This is the desired inequality on $\tilde{M}$ with metric $\tilde{g}$ for functions, with weight function $w = (n-1)^2/4$. The result for general weakly asymptotically hyperboloidal metrics and for functions follows immediately from the above, using uniform equivalence of $g$ with $\tilde{g}$ on the asymptotic region, and using Lemma 9.1.
Let, finally, \( v \) be a smooth compactly supported section of a Riemannian bundle with not-necessarily-compatible connection \( \nabla \). Let \( \phi \) be any smooth compactly supported function equal to 1 on the support of \( v \), set

\[
f_\epsilon = \phi \sqrt{\epsilon + \langle v, v \rangle}.
\]

We have

\[
\left| \frac{\partial f_\epsilon}{\partial x} \right|^2 = |d_x \phi|^2 (\epsilon + \langle v, v \rangle) + \phi^2 \frac{\langle v, (\nabla_x + \Gamma_x^S)v \rangle \langle v, (\nabla_x + \Gamma_x^S)v \rangle}{\epsilon + \langle v, v \rangle} \\
\leq \epsilon |d\phi|^2 + \phi^2 |(\nabla_x + \Gamma_x^S)v|^2.
\]

The first line of (9.14) yields

\[
\int_M f_\epsilon^2 x^{-n} dx d\mu_h = \int_M \phi^2 (\epsilon + \langle v, v \rangle) x^{-n} dx d\mu_h \\
\leq \frac{4}{(n-1)^2} \int_M x^2 (\epsilon |d\phi|^2 + \phi^2 |(\nabla_x + \Gamma_x^S)v|^2) x^{-n} dx d\mu_h.
\]

Passing with \( \epsilon \) to zero gives

\[
\int_M \langle v, v \rangle x^{-n} dx d\mu_h \leq \frac{4}{(n-1)^2} \int_M x^2 |(\nabla_x + \Gamma_x^S)v|^2 x^{-n} dx d\mu_h \\
\leq \frac{4}{(n-1)^2} \int_M \left( (1 + \frac{1}{\delta}) |\nabla v|_g^2 + x^2 (1 + \delta) |\Gamma_x^S v|^2 dx \right) x^{-n} dx d\mu_h,
\]

for any \( \delta > 0 \), and if condition (9.12) holds the last term can be carried over to the left hand side, leading to

\[
C^{-1} \int_M \langle v, v \rangle dv_M \leq \int_M |\nabla v|^2_g dv_M.
\]

Lemma 9.1 gives then the desired inequality, with a weight function \( w \) equal to \( 1/C \) in the asymptotic region.

10 Examples and Applications

The structure and regularity conditions may be readily verified in situations of interest, which we illustrate by considering the Dirac operator examples of §2.

Suppose \( M \) is a Riemannian spin manifold. Fix local coordinates \((x^\mu)\) and a local orthonormal framing \( e_i = e_i^\mu \partial_\mu \) of the tangent bundle \( TM \), and let \( \phi_I, I = 1, \ldots, \dim S \) denote an associated spinor frame, determined by some choice of representation \( c : Cl_n \to \text{End}(S) \). The Dirac operator \( \mathcal{D} \) defined by (2.2)-(2.3) is

\[
\mathcal{D} = e_i^\mu \gamma_i^j \partial_\mu - \frac{1}{4} \omega_{ij}(\partial_\mu) e_k^\mu \gamma^k \gamma^i \gamma^j,
\]

where the skew-symmetric matrices \( \gamma^i = c(e_i) \in \text{End}(S) \) are constant in the local spinor frame and satisfy the Clifford relation

\[
\gamma^i \gamma^j + \gamma^j \gamma^i = -2 \delta^{ij}.
\]
Clearly $\mathcal{D}$ has the form $a^{\mu} \partial_{\mu} + b$ where

$$
a^{\mu} = \sum_{i=1}^{n} e_{i}^{\mu} \gamma^{i},
$$

$$
b = -\frac{1}{4} \sum_{i,j,k,\mu=1}^{n} \omega_{ij}(\partial_{\mu}) e_{k}^{\mu} \gamma^{k} \gamma^{i} \gamma^{j}.
(10.3)
$$

If $g_{\mu\nu} \in W^{1,n}_{loc} \cap C^{0}_{loc}$ then by the Gram-Schmidt construction, the local orthonormal frame may be chosen so that the coefficients also satisfy $e_{i}^{\mu} \in W^{1,n}_{loc} \cap C^{0}_{loc}$, and then $a^{\mu}, b$ also satisfy (3.4), cf. Proposition A.9, Appendix A. The Clifford identity shows

$$
|\xi^{\mu} a^{\mu} V|^{2} = g_{\mu\nu} |\xi^{\mu} V|^{2} |V|^{2}
$$

pointwise, which implies (3.5) so Theorem 3.7 may be applied to establish the $H^{1}_{loc}$ interior regularity of $L^{2}$ weak solutions.

For boundary regularity we assume there is a diffeomorphism of $Y \times I$ with a neighbourhood of $Y \times \{0\} = \partial M$ in $M$, such that for any chart of $Y$, the associated chart of adapted coordinates $(y^{A}, x)$, $x \geq 0$ satisfies

$$
g_{xA}(y,0) = 0, \quad A = 1, \ldots, n-1,
$$

$$
g_{xx}(y,0) = 1,
(10.4)
$$

and

$$
g_{\mu\nu}|_{Y} \in W^{1,(n-1)}(Y) \cap C^{0}(Y).
(10.5)
$$

(Recall that the symbol "|$_{Y}$" stands for "|$_{Y \times \{0\}}$".)

For smooth metrics this follows easily using Gaussian coordinates about $Y$. Geodesic uniqueness may not be available in the more general case of a $W^{k+1,p}$ manifold with metric $g_{\mu\nu} \in W^{k,p}$ for $k > n/p$; in this case the existence of boundary coordinates satisfying (10.4) is guaranteed by Proposition A.10.

Then (6.5) follows from the regularity conditions on $g_{\mu\nu}$, (6.2) follows from (10.5), and (6.9) follows from (10.4), the Clifford relations and the skew-symmetry of the $\gamma^{i}$. In terms of an adapted frame $e_{i}$, where $e_{n}|_{Y} = -\partial_{x^{n}}$ is the outer normal at $Y = \partial M$, the boundary operator (6.10) may be taken as

$$
A = \mathcal{D}_{Y} = -\sum_{i=1}^{n-1} e_{i}^{\mu} \gamma^{i} \gamma^{j} \partial_{\mu} + \frac{1}{4} \sum_{i,j,k=1}^{n-1} \omega_{ij}(\partial_{\mu}) e_{k}^{\mu} \gamma^{k} \gamma^{i} \gamma^{j},
(10.6)
$$

by an appropriate choice of $\tilde{b}_{0}$ in (6.10). Again note that other choices of $A$ are possible, such as $\mathcal{D}_{Y} + F$ for any function or symmetric endomorphism $F$.

The boundary condition (2.13)

$$
P_{+}\psi = \sigma, \quad \sigma \in P_{+}H^{1/2}(Y),
(10.7)
$$

where $P_{+}$ is the orthogonal projection to the positive eigenspace of $A$, corresponds via (6.14) to $K = 0$, which clearly satisfies the conditions of Theorem 6.4 for $K, K^{\dagger}$. From Theorem 6.4 it follows that the weak-strong property and the elliptic estimate (6.21) hold at the boundary for the boundary condition (10.7).
Boundary operators of the type (2.18) were used in [30, 31, 47], for example. More generally suppose there is an endomorphism \( \epsilon : S \to S \) acting on sections of \( E \), which satisfies

\[
\epsilon^2 = 1, \quad t \epsilon = \epsilon, \quad \epsilon A + A \epsilon = 0.
\]

(10.8)

Note that if there is a splitting \( E = E_0 \oplus F_0 \) such that \( A \) has the form (4.10) then \( \epsilon = \begin{bmatrix} I & 0 \\ 0 & -I \end{bmatrix} \) will satisfy (10.8). Conversely, if (10.8) holds then setting \( E_0, F_0 \) equal to the \( \pm 1 \) eigenspaces of \( \epsilon \) shows that \( A \) may be written in the supersymmetric form (4.10).

If \( A\psi = \lambda \psi \) then \( A(\epsilon \psi) = -\epsilon A\psi = -\lambda \epsilon \psi \), so the spectrum of \( A \) is symmetric and \( \epsilon \) interchanges the positive and negative eigenspaces. Let \( P_+ \) \( (P_-) \) be orthogonal projection to the positive \( (\) negative) eigenspaces, and consider the eigenspace splitting \( L^2(Y) = H_+ \oplus H_- \oplus H_0^+ \oplus H_0^- \), where \( H_0 = \ker A \) and \( H_0 = H_0^+ \oplus H_0^- \) is the decomposition into \( \pm 1 \) eigenspaces of \( \epsilon \). There is an isometric isomorphism \( \epsilon : H_+ \to H_- \) such that \( \epsilon \) has the block decomposition

\[
\epsilon = \begin{bmatrix}
  e^{-1} & \\
  e & 1 \\
  & -1
\end{bmatrix}, \text{ acting on } H_+ \oplus H_- \oplus H_0^+ \oplus H_0^-.
\]

It follows that the action of \( \mathcal{K}_+ = \frac{1}{2}(1 + \epsilon) \) is given by

\[
\mathcal{K}_+ \psi = \frac{1}{2}(1 + \epsilon) \begin{bmatrix}
p \\
q \\
r^+
\end{bmatrix} = \begin{bmatrix}
\frac{1}{2}(p + e^{-1}q) \\
\frac{1}{2}(ep + q) \\
r^+
\end{bmatrix}.
\]

(10.9)

Hence the boundary condition \( \mathcal{K}_+ \psi = \sigma \) where \( \sigma = \epsilon \sigma = t[\sigma_+, \epsilon \sigma_+, \sigma_0^+, 0] \), is equivalent to the component conditions \( \frac{1}{2}(p + e^{-1}q) = \sigma_+ \) and \( r^+ = \sigma_0^+ \). This may be expressed in the form (6.14) if we define \( P, K \) by

\[
P = P_+ + P_0^+ = \begin{bmatrix}
1 & 0 \\
0 & 1 \\
0 & 0
\end{bmatrix}, \quad K = \begin{bmatrix}
e^{-1} & 0 \\
0 & 0
\end{bmatrix},
\]

(10.10)

since then

\[
P\psi - K(1 - P)\psi = \begin{bmatrix}
p & 0 \\
0 & r^+
\end{bmatrix} + \begin{bmatrix}
e^{-1}q & 0 \\
0 & 0
\end{bmatrix} = \begin{bmatrix}
2\sigma_+ \\
0 \\
\sigma_0^+
\end{bmatrix}
\]

(10.11)

is equivalent to \( \mathcal{K}_+ \psi = \sigma \) as above. Clearly \( K \) is bounded on both \( L^2(Y) \) and \( H_+^{1/2}(Y) \) as required by the regularity theorems of §5. Similarly we find that the boundary condition \( \mathcal{K}_- \psi = \sigma \) is equivalent to \( \frac{1}{2}(p - e^{-1}q) = \sigma_- \) and
\[ r^- = \sigma_0^-, \] so an equivalent spectral projection condition may be constructed using \( \hat{P} = P_+ + \hat{P}_0^+ \) and \( \hat{K} = -K \), so

\[
\hat{P}\psi - \hat{K}(1 - \hat{P})\psi = \begin{bmatrix}
p - q^{-1}q \\
0 \\
0 \\
r^- \\
\sigma_0^-
\end{bmatrix} = \begin{bmatrix}
2\sigma_+ \\
0 \\
0 \\
0
\end{bmatrix} . \tag{10.12}
\]

## 11 Positive mass theorems

Our motivation for the present work arose from positive energy theorems, and we shall present here some such theorems which follow from our work elsewhere in the paper. The main point is to give a complete proof of Herzlich’s inequality, cf. Theorem 11.7 below. In addition, our remaining results in this section improve the previous ones [8, 11, 19, 20, 25, 37, 38, 51, 54, 62, 64, 67] in two respects: 1) the low differentiability of the metric; 2) we do not require \( \bar{M} \) to have a compact interior. This second aspect of our results is critical for some applications of the positive mass theorem to black holes uniqueness theory [17, 23, 24, 53]. Some of the arguments already presented in other sections will be repeated in the proofs below, whenever useful for the clarity of presentation.

A set \((M, g, K)\) will be called initial data for Einstein equation if \((M, g)\) is a three-dimensional Riemannian manifold, and \(K\) is a symmetric tensor on \(M\); this is a slight abuse of terminology as we are not requiring any constraints to be satisfied. Only complete \((M, g)\)'s will be considered, with boundary either compact or empty. Given such a triple we set

\[
\mu := R - |K|^2 + (\text{tr}K)^2 , \tag{11.1a}
\]
\[
\nu^j := 2\mathcal{D}i(K^{ij} - \text{tr}Kg^{ij}) . \tag{11.1b}
\]

In a field theoretic framework one should provide some further initial data for the complete system of equations in the model under consideration; \(\mu\) and \(\nu\) correspond then to the energy and momentum densities of the matter fields while Equations (11.1) become constraint equations. Now, we are not assuming anything about matter fields, so \(\mu\) and \(\nu\) should be thought of as derived from the data \((M, g, K)\), as in (11.1).

Throughout this section we shall be working in a space of spinors which carries a representation \(c\) of the Clifford algebra associated with the \((n + 1)\)-dimensional Lorentzin metric

\[
\gamma := -\theta^0 \otimes \theta^0 + \sum_{i=1}^n \theta^i \otimes \theta^i = -\theta^0 \otimes \theta^0 + g , \tag{11.2}
\]

with \(\theta^i\) denoting a co-frame dual to a frame \(e_i\). We assume that the \(c(e_i)\)'s are antisymmetric, and that \(c(e_0)\) is symmetric. The symbol \(D\) will be used to denote the canonical spinor connection on \((M, g)\) defined by Equation (2.2) (and denoted by \(\nabla\) there). The connection

\[
\nabla_j := D_j + \frac{1}{2} K_{ij} c(e_i)c(e_0) \tag{11.3}
\]

\(^{*}\)The results here generalize without any difficulties to spin manifolds of higher dimensions, so that the restriction \(n = 3\) is only made for simplicity of presentation.
will be called the *space-time* spin connection on $M$; $\nabla$ is sometimes referred to as the *Sen* connection. We note that $\nabla$ is not compatible with the positive definite metric $\langle \cdot, \cdot \rangle$:

$$
\partial_j \langle \phi, \psi \rangle = \langle \nabla_j \phi, \psi \rangle + \langle \phi, \nabla_j \psi \rangle - \langle \phi, K^i_j c(e_i) c(e_0) \psi \rangle .
$$

(11.4)

However, $\nabla$ is compatible with the Lorentz-invariant (and hence indefinite) inner product $(\phi, \psi) := \langle \phi, c(e_0) \psi \rangle$. The identity associated with $\nabla$, which replaces the identity (2.6) of Schrödinger-Lichnerowicz, takes the form

$$
\int_\Omega \left( \frac{1}{2} |\nabla \psi|^2 + \frac{1}{2} (\mu |\psi|^2 + \nu^i \langle \psi, c(e_i) \psi \rangle) - |\mathcal{D} \psi|^2 \right) = \int_{\partial \Omega} \langle \psi, c(ne^A) \nabla_A \psi \rangle ,
$$

where

$$
\mathcal{D} := g^{ij} c(e_i) \nabla_j .
$$

(11.5)

For sufficiently differentiable $(g, K)$'s, as will be made precise below, the identity (11.5) holds in the following circumstances:

1. If $\psi$ is a $H^1_{\text{loc}}$ spinor field, we may take as $\Omega$ a domain in $M$ with compact closure and differentiable boundary $\partial \Omega$;

2. If $\psi$ is a compactly supported $C^1$ spinor field, then Equation (11.5) holds with $\Omega = M$, and $\partial \Omega = \partial M$; in particular no boundary term is present if $M$ has no boundary;

3. Suppose $(M, \nabla)$ admits a weighted Poincaré inequality, assume $\partial M = \emptyset$, and let $\mathbb{H}$ be the space defined in (8.5). We then have the following:

**Lemma 11.1** Suppose that $\partial M = \emptyset$. The function

$$
C^1_c(M) \ni \psi \to G(\psi) := \int_M \left( \mu |\psi|^2 + \nu^i \langle \psi, c(e_i) c(e_0) \psi \rangle \right)
$$

extends by continuity to a continuous function on $\mathbb{H}$, still denoted by the same symbol.

**Proof:** For $\psi, \chi \in C^1_c(M)$ the identity (11.9) gives

$$
G(\psi) - G(\chi) = 4 \int_M \left( - \langle \nabla \psi, \nabla \psi \rangle + \langle \nabla \chi, \nabla \chi \rangle + \langle \mathcal{D} \psi, \mathcal{D} \psi \rangle - \langle \mathcal{D} \chi, \mathcal{D} \chi \rangle \right)
= 4 \int_M \left( \langle \nabla \chi - \nabla \psi, \nabla \psi + \nabla \chi \rangle + \langle \mathcal{D} \chi + \mathcal{D} \psi, \mathcal{D} \psi - \mathcal{D} \chi \rangle \right)
\leq C \|\psi + \chi\|_{\mathbb{H}} \|\psi - \chi\|_{\mathbb{H}} ;
$$

in the last step we have used the fact that the $|c(e_i)|$ are uniformly bounded. ■

Lemma 11.1 implies that the left-hand-side of (11.5) is continuous on $\mathbb{H}$ for any measurable $\Omega \subset M$. Since compactly supported $C^1$ fields are by definition dense in $\mathbb{H}$, one easily checks, using continuity, that (11.5) holds with $\Omega = $
and with vanishing right-hand-side for all \( \psi \in \mathbb{H} \). (Nonempty compact boundaries \( \partial M \) will be considered shortly.)

We shall say that \( M_{\text{ext}} \subset M \) is an asymptotically flat end if \( M_{\text{ext}} \) is diffeomorphic to \( \mathbb{R}^3 \setminus B(0, R) \) for some \( R \), with

\[
\begin{align*}
& \quad r^{-1}(g_{ij} - \delta_{ij}) , \quad \partial_k g_{ij} , \quad K_{ij} \in L^2(M_{\text{ext}}) , \\
& \quad \partial_k g_{ij} = o(r^{-3/2}) , \quad K_{ij} = o(r^{-3/2}) , \\
& \quad \mu , \nu \in L^1(M_{\text{ext}}) ,
\end{align*}
\]

compare Definition 9.4. Those conditions guarantee that the ADM four-momentum of the data set is finite and well defined, as follows from what is said in [21] (compare [8]): (11.7a) and (11.7c) guarantee convergence of the mass and momentum integrals, while (11.7b) guarantees geometric invariance.

One of the ingredients of Witten-type proofs of positive energy theorems is the introduction of appropriate boundary conditions on the spinor field in the asymptotic regions. In the asymptotically flat case this is straightforward: one chooses a \( g \)-orthonormal triad such that, in the coordinate system of (11.7),

\[
\begin{align*}
& \quad dx^k(e_i - \partial_i) \to_{r \to \infty} 0 , \quad \partial_i \left( dx^k(e_j) \right) \in L^2(M_{\text{ext}}) ;
\end{align*}
\]

this is easily achieved by a Gram-Schmidt orthonormalisation of the frame \( \{\partial_i\} \). Then a spin frame on \( M_{\text{ext}} \) is introduced, such that the \( c(e_i) \)'s are represented by constant matrices, as in Section 10. The boundary condition then is that the spinor field \( \psi \), which will be required to solve the generalized Dirac equation,

\[
\mathcal{D}\psi = g^{ij} c(e_i) \nabla_j \psi = 0 ,
\]

asymptotes, as \( r \) tends to infinity, to a spinor \( \psi_{\infty} \) which, for \( r \geq R \) for some \( R \), has constant entries in the spin frame above. It is convenient to choose \( \psi_{\infty} \) so that \( \psi_{\infty} \) is smooth, and supported in \( M_{\text{ext}} \). The procedure is somewhat more delicate in the asymptotically hyperboloidal setting; an elegant geometric framework for such constructions has been provided in [4, 14].

Consider the identity (11.5) with a spinor field \( \psi = \psi_{\infty} + \chi \), with \( \chi \) differentiable and compactly supported, while \( \partial \Omega = S_R \), a coordinate sphere of radius \( R \) in the exterior region, with \( R \) large enough that \( \chi \) vanishes there. A classical calculation along the lines of [8] shows that the boundary term in (11.5) is then proportional to

\[
4\pi p^\alpha \langle \psi_{\infty} , c(e^\alpha e^0)\psi_{\infty} \rangle + o(1) ,
\]

where \( p^\alpha \) is the ADM four-momentum of \( (M_{\text{ext}}, g) \), with \( o(1) \to 0 \) as \( R \) tends to infinity. Passing to this limit we thus have

\[
\int_M \left( |\nabla \psi|^2 + \frac{1}{4} \left( \mu |\psi|^2 + \nu \langle \psi , c(e_i)c(e_0)\psi \rangle \right) - |\mathcal{D}\psi|^2 \right) = 4\pi p^\alpha \langle \psi_{\infty} , c(e^\alpha e^0)\psi_{\infty} \rangle ,
\]

still for \( C^1 \) compactly supported \( \chi \)'s. But the left-hand-side of (11.9) is continuous on \( \mathbb{H} \), which is shown by a calculation similar to that in Lemma 11.1: Let
\( F(\chi) \) denote the left-hand-side of Equation (11.9) with \( \psi = \psi_\infty + \chi \) there, let \( \chi_i \in \mathbb{H} \) converge in \( \mathbb{H} \) to \( \chi \in \mathbb{H} \), so we have

\[
F(\chi) - F(\chi_i) = \| \chi \|_\mathbb{H}^2 - \| \chi_i \|_\mathbb{H}^2 \\
+ 2 \int_M \langle \nabla^k \psi_\infty, \nabla_k (\chi - \chi_i) \rangle \\
- 2 \int_M \langle \mathcal{D} \psi_\infty, \mathcal{D} (\chi - \chi_i) \rangle \\
+ \frac{1}{2} \int_M \langle \psi_\infty, \left( \mu + \nu^c e_k c(e_0) \right) (\chi - \chi_i) \rangle.
\]

Because \( \nabla \psi_\infty \in L^2(M) \), the first three terms above converge to zero as \( i \to \infty \). The convergence of the final term can be justified by applying the Cauchy-Schwarz inequality

\[
\left| \int_M \langle \psi_\infty, \left( \mu + \nu^j c(e_j) c(e_0) \right) (\chi - \chi_i) \rangle \right| \\
\leq \left( \int_M \langle \psi_\infty, \left( \mu + \nu^j c(e_j) c(e_0) \right) \psi_\infty \rangle \right)^{1/2} \\
\times \left( \int_M \langle (\chi - \chi_i), \left( \mu + \nu^j c(e_j) c(e_0) \right) (\chi - \chi_i) \rangle \right)^{1/2} \\
\leq C(\| \mu \|_{L^1} + \| \nu \|_{L^1}) \left( \| \chi + \chi_i \|_\mathbb{H} \| \chi - \chi_i \|_\mathbb{H} \right)^{1/2};
\]

in the last step of the calculation of Lemma 11.1 has been used. Now, \( F(\chi_i) = F(0) \), and density implies that (11.9) remains true for any \( \psi \) of the form \( \psi_\infty + \chi \), with \( \chi \in \mathbb{H} \).

We are ready now to prove the following version of the positive energy theorem, the regularity conditions of which have been chosen as a compromise between those needed for solvability of the Dirac equation (11.8) (cf. Remark 6.1, p. 32), those needed for a well defined notion of ADM mass, and those needed for a Banach manifold structure for the set of solutions of the general relativistic vacuum constraint equations.

**Theorem 11.2** Let \((M, g, K)\) be initial data for the Einstein equations with \( g \in W^{2,2}_{\text{loc}} \), \( K \in W^{1,2}_{\text{loc}} \), with \((M, g)\) complete (without boundary). Suppose that \( M \) contains an asymptotically flat end and let \( p_\alpha = (m, \vec{p}) \) be the associated ADM four-momentum.\(^{10}\) If

\[
\mu \geq |\nu|_g, \quad (11.10)
\]

then

\[
m \geq |\vec{p}|_g, \quad (11.11)
\]

\(^{10}\)There is a signature-dependent ambiguity in the relationship between \( p^0, p_0 \) and the mass \( m \): in the space-time signature \((- , +, +, +)\) used in this paper this sign is determined by the fact that \( p_0 \), obtained by Hamiltonian methods, is usually positive in Lagrangean theories on Minkowski space-time such as the Maxwell theory, while the mass \( m \) is a quantity which is expected to be positive.
with equality if and only if \( m \) vanishes. Further, in that last case there exists a non-trivial covariantly constant (with respect to the space-time spin connection) spinor field on \( M \).

**Remark 11.3** Under the supplementary assumption of smoothness of \( g \) and \( K \), it has been shown in [10] that the existence of a covariantly constant spinor implies that the initial data can be isometrically embedded into Minkowski space-time, cf. also [66]. We expect this result to remain true under the current hypotheses, but we have not attempted to prove this.

**Proof:** Suppose that for all \( \psi_\infty \) we can establish existence of \( \chi = \chi[\psi_\infty] \in \mathbb{H} \) such that \( \psi_\infty + \chi \) satisfies the Dirac equation (11.8). Equation (11.9) would then show that the quadratic form

\[
\psi_\infty \rightarrow 4\pi p_\alpha(\psi_\infty, c(e^\alpha e^0)\psi_\infty)
\]

is non-negative, and the Theorem follows by a standard calculation. The existence of \( \chi \) will be a consequence of Theorem 8.8, provided that the relevant hypotheses are met. We have

\[
\mathcal{D} = c(e^i)D_i - \frac{1}{2} \text{tr}_g Kc(e_0) \implies \mathcal{D}^\dagger = \mathcal{D}.
\]

Equation (11.9) with \( \psi_\infty = 0 \) shows that the Schrödinger-Lichnerowicz estimate of Definition 8.4, with \( Y = \emptyset \) and \( \rho = 0 \), holds both for \( \mathcal{L} := \mathcal{D} \) and its formal adjoint \( \mathcal{D}^\dagger = \mathcal{D} \). Next, we note that the symmetric part \( \Gamma^S \) of the connection (11.3) is

\[
\Gamma^S = \frac{1}{2} K^i_j c(e_i)c(e_0) \otimes dx^j
\]

which does not vanish for non-zero \( K \)'s, but satisfies nevertheless the fall-off condition (9.8) by (11.7b). It follows from Theorem 9.5 that the weighted Poincaré inequality holds. The regularity conditions on the metric imply that the requirements of Hypothesis 8.1 with \( \dot{g} = g \) are met: for trivial bundles, or for smooth initial data, this is a straightforward calculation, compare Remark 6.1; for non-trivial bundles Proposition A.9, Appendix A, has to be invoked. The map \( \beta \) of Equation (8.9) is zero, as is the curvature term \( \rho \) in the Schrödinger-Lichnerowicz inequality (8.7), by the energy condition \( \mu \geq |\nu|_g \). From what has been said it follows that spinor fields in \( \mathbb{H} \) which are also in the kernel of \( \mathcal{D} \) are covariantly constant; they then have constant length, and are not in \( L^2 \) if they are non-zero. Theorem 8.8 now shows that for any \( \psi_\infty \) there exists a solution \( \chi \in \mathbb{H} \) of the equation

\[
\mathcal{D}\chi = -\mathcal{D}\psi_\infty,
\]

and the existence of the desired \( \psi \) follows.

Let us now turn our attention to manifolds with boundary. We shall say that a boundary \( \partial M \) is *future-trapped* if

\[
\theta_+ := H + \sum_{A=2,3} K(e_A, e_A) \leq 0. \tag{11.12}
\]
Here $H$ is the mean curvature of $\partial M$ with respect to an inner-pointing normal, while the $e_A$’s form an ON basis for $T\partial M$. A future-trapped boundary in the sense above is future-trapped in the usual sense [36] for a surface in space-time. The following result generalises one by Herzlich\footnote{The proof in [38] is the rigorous version of an argument proposed in [31]; it also extends that argument, as in [31] only marginally trapped boundaries are considered.} [38]:

**Theorem 11.4** Under the remaining hypotheses of Theorem 11.2, suppose instead that $M$ has a differentiable, compact, future-trapped boundary $\partial M$. Then the conclusions of Theorem 11.2 hold.

**Remark 11.5** One expects that the equality case cannot occur in (11.11), and a possible argument could proceed as follows: First, the existence of a covariantly constant spinor implies existence of a non-spacelike, covariantly constant, Killing vector field in the associated space-time. Further, if the metric is $C^2$ and $K$ is $C^1$, then the space-time metric fulfills the Einstein equations with a null fluid as a source [10, Appendix B]; this conclusion is expected to hold under the weaker differentiability conditions considered here. By reduction of the field equations, this should imply smoothness of the metric. (Alternatively, one could assume at the outset that $g$ is $C^3$ and $K$ is $C^2$, in which case the argument presented in the current remark settles the issue). Topological censorship results [28] applied to the Killing development [10] of the initial data show that the boundary is then the union of a finite number of spheres. Arguing as in the proof of Theorem 4.6 of [25], the restriction to the boundary of the covariantly constant spinor would be harmonic, which is impossible by the Hijazi-Bär inequality (2.14) [7, 39].

**Remark 11.6** Past-trapped boundaries are defined by changing the sign of $K$ in (11.12); as the remaining hypotheses of Theorem 11.4 are invariant under this change of sign, an identical result holds for compact past-trapped $\partial M$’s.

**Proof:** The proof follows closely that of Theorem 11.2, the main difference being the need to impose suitable boundary conditions. Indeed, when $\partial M$ is non-empty Equation (11.9) becomes

$$
\int_M \left( |\nabla \psi|^2 + \frac{1}{4} \left( \mu |\psi|^2 + \nu \langle \psi, c(e_i)c(e_0)\psi \rangle \right) - |\mathcal{D} \psi|^2 \right) = 4\pi p_\alpha \langle \psi_\infty, c(e^\alpha e^0)\psi_\infty \rangle + \int_{\partial M} \langle \psi, c(n)c(e^A)\nabla_A \psi \rangle
$$

$$
= 4\pi p_\alpha \langle \psi_\infty, c(e^\alpha e^0)\psi_\infty \rangle + \int_{\partial M} \langle \psi, \mathcal{D}_\partial M \psi + \frac{1}{2} \left( H - \sum_A \left( K_{AAC}(n) - K_{A1c(e_A)} \right) c(e_0) \psi \right) \rangle,
$$

for, say, continuously differentiable $\psi$’s of the form $\psi = \psi_\infty + \chi$, with $\chi$ compactly supported, and $\psi_\infty$ as in the proof of Theorem 11.2. Further, $\mathcal{D}_\partial M$ is the Dirac boundary operator defined by Equation (2.7), and Equation (2.8) has
been used. Finally, $e_i$ is an ON frame on $\partial M$ with $n \equiv e_1$ normal to $\partial M$. Following [33] we impose the boundary condition

$$K_- := \frac{1}{2}(1 - \epsilon)\psi = 0 \quad \text{on } \partial M, \quad (11.14)$$

where $\epsilon := -c(n)c(e_0)$. We then have

$$\langle \psi, c(e_A)c(e_0)\psi \rangle = -\langle \psi, c(e_A)c(e_0)c(n)c(e_0)\psi \rangle$$

$$= -\langle \psi, c(e_0)c(n)c(e_0)c(e_0)\psi \rangle$$

$$= -\langle c(n)^t c(e_0)^t \psi, c(e_A)c(e_0)\psi \rangle$$

$$= \langle c(n)c(e_0)\psi, c(e_A)c(e_0)\psi \rangle = -\langle \psi, c(e_A)c(e_0)\psi \rangle,$$

which shows that the last term in the last line of Equation (11.13) vanishes. Then

$$\langle \psi, D_{\partial M}\psi \rangle = \langle \psi, D_{\partial M}\epsilon\psi \rangle$$

$$= -\langle \epsilon\psi, D_{\partial M}\psi \rangle$$

$$= -\langle \epsilon\psi, D_{\partial M}\psi \rangle = -\langle \psi, D_{\partial M}\psi \rangle,$$

which shows that the first term in the last line of Equation (11.13) vanishes.

Next,

$$\langle \psi, \left( H - \sum_A K_{AA}c(n)c(e_0) \right) \psi \rangle = \langle \psi, \left( H + \sum_A K_{AA} \right) \psi \rangle = \theta_+ \langle \psi, \psi \rangle,$$

which shows that the sum of the second and third term in the last line of Equation (11.13) gives a non-positive contribution when $\partial M$ is trapped. When $\mu \geq |\nu|g$, $\psi_\infty = 0$, and (11.14) holds, from Equation (11.13) we obtain

$$\int_M (|\nabla \psi|^2 + \frac{1}{4} (\mu |\psi|^2 + \nu^t \langle \psi, c(e_i)c(e_0)\psi \rangle)) - \frac{1}{2} \int_{\partial M} \theta_+ \langle \psi, \psi \rangle = \int_M |D\psi|^2,$$

so conditions (11.10), (11.12) give

$$\int_M |\nabla \psi|^2 \leq \int_M |D\psi|^2,$$

(11.15)

for all $\psi \in C^1_c(M)$ which satisfy (11.14). Define

$$\mathbb{H}_{K_-} := \{ \psi \in \mathbb{H}, K_- \psi = 0 \text{ on } \partial M \}, \quad (11.16)$$

where $\mathbb{H}$ is defined in (8.5). If we let

$$G'(\psi) := \int_M (\frac{1}{4} (\mu |\psi|^2 + \nu^t \langle \psi, c(e_i)c(e_0)\psi \rangle)) - \frac{1}{2} \int_{\partial M} \theta_+ \langle \psi, \psi \rangle,$$

(11.17)

then the calculation of the proof of Lemma 11.1 shows that $G'(\psi)$ can be extended by continuity to a continuous function on $\mathbb{H}_{K_-}$. The boundary integral
in (11.17) is continuous, so the volume integral is also continuous on $\mathbb{H}_K^−$, which implies that Equations (11.15) holds for all $\psi \in \mathbb{H}_K^−$. Lemma 8.6 establishes the Schrödinger-Lichnerowicz estimate (8.7) with $\rho = 0$ for $(\mathcal{D}, K^−)$.

As explained in Section 10, the boundary value problem determined by Equation (11.14) belongs to the family of problems considered in Theorem 8.8. If both $M$ and $\partial M$ are simultaneously parallelizable, and if the metric $g$ is a product near $\partial M$, then the regularity conditions of Theorem 8.8 are met by hypothesis; the general case is handled by Propositions A.9 and A.10, Appendix A. Repeating now the arguments of the proof of Theorem 11.2 gives the non-negativity of $p_0$.

It is expected that the positivity statement of Theorem 11.4 can be strengthened to the so-called Penrose inequality when trapped boundaries occur. This question remains wide open, except in the special case $K_{ij} = 0$ [15, 42]. An interesting related inequality has been, essentially, proved by Herzlich [37]; however, the arguments of that last reference do not include a sufficient justification of existence of the required spinor field, except in the rather special case of a smooth metric which is a product near the boundary, as analyzed by Bunke [16]. Here we fill this gap and establish the following:

**Theorem 11.7** Let $(M,g)$ be a complete Riemannian manifold with $g \in W^{2,2}$, and suppose that $M$ has a boundary $\partial M$ diffeomorphic to $S^2$, with non-positive inwards pointing mean curvature. Suppose that the curvature scalar $R(g)$ of the metric $g$ is non-negative, and that $M$ contains an asymptotically flat end with mass $m$. If $\sigma$ is the dimensionless quantity defined as

$$\sigma := \sqrt{\frac{\text{Area}(\partial M)}{\pi}} \inf_{f \in C_0^\infty(M), f \neq 0} \frac{\|df\|^2_{L^2(M)}}{\|f\|^2_{L^2(\partial M)}} \,,$$

then

$$m \geq \sigma \frac{\sigma}{1 + \sigma} \sqrt{\frac{\text{Area}(\partial M)}{4\pi}}.$$ 

Moreover, if the metric is smooth, then equality is achieved if and only if $(M,g)$ can be isometrically embedded in the Schwarzschild space-time with mass $\sqrt{\text{Area}(\partial M)}/16\pi$.

**Remark 11.8** If $M$ is the union of a compact set with a finite number of asymptotically flat ends, then $\sigma > 0$.

**Proof:** The details of the argument follow closely those of the proof of Theorem 11.4, the pointwise boundary conditions (11.14) being replaced by the spectral boundary conditions (2.10) with $K$ given by (2.13); compare the discussion of Section 2, as well as that in the paragraph following Equation (10.7). The main elements missing in the arguments of [37] are provided by the boundary regularity results of Section 5; those are the key to the proof of Theorem 8.8.}

---

12Similarly to Theorem 11.7, for the results in [15, 42] it actually suffices that $R \geq 0 \Leftrightarrow \mu \geq -|K^\sigma_{ij} + (\text{tr}_h K)^\sigma|$, and that $\text{tr}_h K$ vanishes on $\partial M$, where $\text{tr}_h$ is the trace of the restriction of $K$ to $\partial M$. 

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The reader is referred to [38] and [23, p. 679] for the analysis of the equality case, cf. also [9].

Following [31, 34], let us pass now to inequalities with an electric charge contribution. A set \((M, g, K, E, B)\) will be called \textit{initial data for the Einstein-Maxwell equations} if \((M, g)\) is a three dimensional Riemannian manifold, \(K\) is a symmetric tensor on \(M\), while \(E\) and \(B\) are vector fields on \(M\); as before, this is a serious abuse of terminology, as we are not requiring any constraint equations to be satisfied. Given such a triple we set

\[
\text{div } E := D_i E^i, \\
\text{div } B := D_i B^i, \\
\mu := R - |K|^2_g + (\text{tr}K)^2 - 2|E|^2_g - 2|B|^2_g, \\
\nu_i := 2D_j (K^j_i - \text{tr}K \delta^j_i) + 4\epsilon_{ijk} E^j B^k.
\] (11.18)

Here \(D\) is the Levi-Civita connection associated with the metric \(g\). In a general relativistic context, \(\text{div } E\) is the electric charge density, \(\text{div } B\) is the magnetic charge density (usually zero, whether electro-vacuum or not), \(\mu\) is the energy density remaining after subtracting the electro-magnetic contribution, and \(\nu_i\) is the left-over matter current; \(\mu, \text{div } E, \text{div } B\) and \(J_i\) vanish when the Einstein-Maxwell constraint equations hold.

Let a new connection \(\nabla\) be defined as

\[
\nabla_i := D_i + \frac{1}{2} K_{ij} c(e^j)c(e_0) - \frac{1}{2} c(E)c(e_0)c(e_0) - \frac{1}{4} \epsilon_{ijkl} B^j c(e^k)c(e^l)c(e^i); \quad (11.19)
\]

The connection \(\nabla\) will be called the \textit{space-time Einstein-Maxwell spin connection} on \(M\). \(\nabla\) is again not metric compatible, with symmetric part \(\Gamma^S\) given by

\[
\Gamma^S = \left(\frac{1}{2} K_{ij} c(e^j)c(0) - E_i c(0) - \frac{1}{4} \epsilon_{ijkl} B^j c(e^k)c(e^l)c(e^i)\right) \otimes \theta^i, \quad (11.20)
\]

where, as before, \(\theta^i\) is the co-frame dual to \(e_i\). In this context the asymptotic flatness conditions have to be complemented by conditions on \(E\) and \(B\): we shall require

\[
E, B \in L^2(M_{\text{ext}}), \quad \text{div } E, \text{div } B \in L^1(M_{\text{ext}}), \quad E = o(r^{-1}), \quad B = o(r^{-1}). \quad (11.21)
\]

Following an argument proposed by Gibbons and Hull [34] we have:

**Theorem 11.9** Let \((M, g, K, E, B)\) be initial data for Einstein-Maxwell equations with \(g \in W^{2,2}_{\text{loc}}, K, E, B \in W^{1,2}_{\text{loc}}, \) with \((M, g)\) complete (without boundary). Suppose that \(M\) contains an asymptotically flat end \(M_{\text{ext}}\) with \(E\) and \(B\) satisfying the fall-off conditions (11.21) there, and let \(p_\alpha = (m, \vec{p})\) be the associated ADM four-momentum. Let \(Q\) and \(P\) be the total electric and magnetic charge of \(M_{\text{ext}}\),

\[
Q = \lim_{R \to \infty} \frac{1}{4\pi} \int_{r=R} E^i dS_i, \quad P = \lim_{R \to \infty} \frac{1}{4\pi} \int_{r=R} B^i dS_i.
\]
If
\[ \mu \geq \sqrt{|\nu|^2 + |\text{div } E|^2 + |\text{div } B|^2} , \]

then
\[ m \geq \sqrt{|\vec{p}|^2 + Q^2 + P^2} , \]

where \( |\vec{p}|_{\delta} \equiv \sqrt{\sum(p_i)^2} \), with equality if and only if there exists a spinor field on \( M \) which is covariantly constant with respect to the Einstein-Maxwell space-time spin connection (11.19).

**Remark 11.10** Under the hypothesis of smoothness of the metric, Tod [61] has found the local form of the metrics which admit covariantly constant spinors as above; however, no classification of globally regular such space-times is known. It is expected that the only singularity-free solutions here have vanishing Maxwell field, or belong to the standard Majumdar-Papapetrou family (cf., e.g., [27]). It would be of interest to fill this gap.

**Remark 11.11** Charged matter might violate (11.22); however, there might exist a constant \( \alpha \in (0, 1) \) such that
\[ \mu \geq \sqrt{|\nu|^2 + \alpha^2(|\text{div } E|^2 + |\text{div } B|^2)} . \]

Replacing in (11.19) the fields \( E \) and \( B \) by \( \alpha E \) and \( \alpha B \), an essentially identical argument leads to
\[ m \geq \sqrt{|\vec{p}|^2 + \alpha^2(Q^2 + P^2)} . \]

**Proof:** For the connection (11.19) the identity (11.9) becomes [34]
\[
\int_M \left( |\nabla \psi|^2 - |\mathcal{D} \psi|^2 
+ \frac{1}{4} \langle \psi, (\mu + \nu^i c(e_i)c(e_0) - \text{div } Ec(e_0) - \text{div } Bc(n)c(e_2)c(e_3)) \psi \rangle 
= 4\pi \langle \psi_\infty, [p_\alpha c(e^0)c(e_0) + Qc(e_0) - Pc(n)c(e_2)c(e_3)] \psi_\infty \rangle , \right. 
\]

again for \( \psi \) of the form \( \psi_\infty + \chi \), with \( C^1 \) compactly supported \( \chi \)'s. The Dirac operator
\[ \mathcal{D} := c(e^i)\nabla_i = c(e^i)D_i - \frac{1}{2} \left( \text{tr}_g K - c(E) \right) c(e_0) - \frac{1}{4} \epsilon_{ijkl}B^j c(e^k)c(e^l) \]
is not formally self-adjoint, we have instead
\[ \mathcal{D}^\dagger = c(e^i)D_i - \frac{1}{2} \left( \text{tr}_g K - c(E) \right) c(e_0) + \frac{1}{4} \epsilon_{ijkl}B^j c(e^k)c(e^l) . \]

This shows that the adjoint of \( \mathcal{D} \) coincides with \( \mathcal{D} \) modulo the replacement
\[ B \rightarrow -B . \]

The arguments follow now the previous ones, basing on the identity (11.26). We simply note that (11.22) implies non-negativity of the quadratic form appearing
in the second line of (11.26). Similarly, positivity of the quadratic form defined by the third line of Equation (11.26) implies (11.23). Some comments are in order here, related to the fact that $L$ is not formally self-adjoint when the magnetic field does not vanish. Since we are not assuming interior compactness of $M$, $M$ could have other asymptotic regions in which $B$ could grow in an uncontrollable way, so that $L^\dagger$ will not map $H$ into $L^2$. Now, $L^\dagger$ differs from $L$ by a change of the sign of $B$, which implies that $L^\dagger$ also satisfies a Schrödinger-Lichnerowicz identity with a connection in which $B$ is replaced by $-B$. The arguments already given show that the weak equation $L^\dagger \phi = 0$ has no $L^2$ solutions, and Corollary 8.8 provides the desired isomorphism property of $L$. ■

In the presence of boundaries we have:

**Theorem 11.12** Under the remaining hypotheses of Theorem 11.9, suppose instead that $M$ has a compact future-trapped boundary $\partial M$. Then the conclusions of Theorem 11.9 hold.

**Proof:** This is a repetition of the argument of the proof of Theorem 11.4; one imposes again the boundary condition (11.14), and we only need to check that (11.15) still holds. This is indeed the case, which is established as follows: the electromagnetic field leads to a supplementary contribution

$$\int_{\partial M} \langle \psi, \left[ E^i c(e_0) - B^i c(e^1) c(e^2) c(e^3) \right] \psi \rangle n_i$$

to the boundary integral (11.13). When (11.14) holds we have

$$\langle \psi, c(e_0) \psi \rangle = -\langle \psi, c(e_0) c(n) c(e_0) \psi \rangle = -\langle \psi, c(n) \psi \rangle$$

$$= -\langle c(n) \psi, \psi \rangle = -\langle c(e_0) c(n) c(e_0) \psi, \psi \rangle = -\langle c(e_0) \psi, \psi \rangle = -\langle \psi, c(e_0) \psi \rangle,$$

hence

$$\langle \psi, c(e_0) \psi \rangle = 0.$$

Similar manipulations show that Equation (11.14) implies

$$\langle \psi, c(e^1) c(e^2) c(e^3) \psi \rangle = 0,$$

and the result follows. ■

We finish this section by noting that positive energy results follow by identical arguments for asymptotically hyperboloidal manifolds [4, 25, 26, 29, 33, 52, 62, 67]; here Theorem 9.10 should be used instead of Theorem 9.5. The definition of mass in that case is considerably more delicate, we refer the reader to [25, 26] for details.
A Fields on manifolds of $W^{k+1,p}$ differentiability class

Consider a smooth manifold $M$; on such a manifold one can define in a geometrically invariant way tensor fields which are of $C^\infty$ differentiability class, or of $C^k$ class, or of $W^{k,p}_\text{loc}$ class. For example, one says that a tensor field is of $W^{k,p}_\text{loc}$ class if there exists a covering of $M$ by coordinate patches such that the coordinate components of the tensor in question are in $W^{k,p}_\text{loc}$ in each of the coordinate patches. Since the transition functions when going from one coordinate system to another are smooth, this property will be true in any coordinate system.

Let, now, $(M,g)$ be a smooth manifold with a pseudo–Riemannian metric $g$ which is of $W^{k,p}_\text{loc}$ differentiability class. For various arguments it is convenient to use local coordinate systems which are adapted to the metric, such as geodesic coordinates, or harmonic coordinates. In this case the transition functions to the adapted coordinate system will not belong to the original smooth atlas on $M$ in general. At this point there are two strategies possible: either to enlarge the atlas on $M$ to contain those new coordinate systems, or to ignore this issue and try to analyze the problems that arise on an ad hoc basis. For nearly all of this paper the ad hoc approach, working entirely within a $C^\infty$ structure on $M$, is quite adequate. However, the proofs of Theorems 11.7 and 11.12 require the existence of approximately Gaussian coordinates near a boundary or near a hypersurface of $M$ (cf. Lemma A.10 below). Direct construction of such coordinates with respect to the $W^{k,p}_\text{loc}$ metric $g$ produces a coordinate change which is not $C^\infty$, which forces us to analyse the problems involved when constructing systematically manifolds of $W^{k+1,p}_\text{loc}$ differentiability class. For this reason we will present such a construction here. For technical reasons we shall always assume that

$$p \in [1, \infty] \, , \quad k \in \mathbb{N} \, , \quad kp > n \, ; \quad (A.1)$$

these restrictions are more than sufficient for our purposes. Generalising the condition $k \in \mathbb{N}$ to $k \in \mathbb{R}^+$ would require an analogue of Lemma A.2 for non-integral $k, \ell$, which seems not to be available. Condition (A.1) and the Sobolev embedding $W^{k+1,p}_\text{loc}(\Omega) \subset C^1(\Omega)$ (for appropriately regular open domains $\Omega \subset \mathbb{R}^n$) mean that we will consider only manifolds which are at least of $C^1$ differentiability class.

Consider, thus, a connected paracompact Hausdorff manifold $M$ of $C^1$ differentiability class. We shall say that $M$ is of $W^{k+1,p}_\text{loc}$ differentiability class if $M$ has an atlas for which all the transition functions are of $W^{k+1,p}_\text{loc}$ differentiability class. Unless indicated otherwise, the Lebesgue measure in local coordinates is used.

A tensor field with components which are $C^\infty$ with respect to some coordinate chart (belonging to a $C^\infty$ sub-atlas of the $W^{k+1,p}_\text{loc}$ atlas), will not generally have smooth components in all $W^{k+1,p}_\text{loc}$ charts. In this situation a $C^\infty$ tensor field “comes equipped” with a preferred atlas of coordinate charts in which it has smooth coordinate components. This is a priori the case for tensor fields of any differentiability class on $W^{k+1,p}_\text{loc}$ manifolds, and it is of interest to single out those classes of tensor fields, the coordinate components of which will be
of a prescribed differentiability class in every coordinate system of the $W^{k+1,p}_{\text{loc}}$ atlas on $M$. Differentiability classes of this type will be referred to as invari-
antly defined. Our next result describes some such classes of tensor fields. It
is convenient to introduce the following notation: let $x, y \in \mathbb{R}$, we shall write $x > y$ if the following holds:

$$x > y \iff \begin{cases} x \geq y, & \text{if } y > 0, \\ x > y, & \text{if } y \leq 0. \end{cases} \quad (A.2)$$

(We note that for $x \geq 0$ the only value of $x$ at which “$>$” does not coincide
with “$\geq$” is $x = 0$.) In this notation the the Sobolev embedding theorem can
be stated as:

$$W^{s,t}_{\text{loc}} \subset W^{u,v}_{\text{loc}} \iff u \leq s \quad \text{and} \quad \frac{1}{v} \succ \frac{1}{t} - \frac{s-u}{n}. \quad (A.3)$$

**Proposition A.1** Let $(M, g)$ be a $W^{k+1,p}_{\text{loc}}$ manifold, $kp > n$, $p \in [1, \infty]$.

1. Let $(\ell, q)$ be such that the Sobolev embedding

$$W^{k+1,p}_{\text{loc}} \subset W^{\ell,q}_{\text{loc}}$$

holds (which is equivalent to the condition

$$\frac{1}{q} \succ \frac{1}{p} + \frac{\ell - k - 1}{n}, \quad (A.4)$$

with $\succ$ defined in (A.2)). Then the space of $W^{\ell,q}_{\text{loc}}$ scalar fields on $M$ is
invariantly defined.

2. Let $(\ell, q)$ be such that the Sobolev embedding

$$W^{k,p}_{\text{loc}} \subset W^{\ell,q}_{\text{loc}}$$

holds (which is equivalent to the condition

$$\frac{1}{q} \succ \frac{1}{p} + \frac{\ell - k}{n}. \quad (A.5)$$

Then the space of $W^{\ell,q}_{\text{loc}}$ tensor fields on $M$ is invariantly defined.

**Proof:** Point 1 is a straightforward consequence of the following Lemma:

**Lemma A.2** Let $\Omega, \mathcal{U} \subset \mathbb{R}^n$ and let $\psi : \Omega \to \mathcal{U}$ be a $C^1$ diffeomorphism such
that $\psi \in W^{k+1,p}_{\text{loc}}(\Omega; \mathbb{R}^n)$, $kp > n$. If $(\ell, q)$ is such that the Sobolev embedding
$W^{k+1,p}_{\text{loc}} \subset W^{\ell,q}_{\text{loc}}$ holds, cf. Equations (A.4) and (A.2), then for all $F \in W^{\ell,q}_{\text{loc}}(\mathcal{U})$
we have

$$F \circ \psi \in W^{\ell,q}_{\text{loc}}(\Omega).$$

**Remark A.3** In [13, 58] some partial results can be found concerning sharpness
of this result.
Proof: We have, for $0 \leq |\alpha| \leq \ell (\leq k + 1)$, 

$$
\frac{\partial^\alpha (F \circ \psi)}{\partial \alpha} = \sum C(\alpha_1, \ldots, \alpha_m) \partial^{\alpha_1} \psi \cdots \partial^{\alpha_m} \psi F(m) \circ \psi,
$$

where the sum is taken over sets $(\alpha_1, \ldots, \alpha_m)$ satisfying $\alpha_1 + \cdots + \alpha_m = \alpha$, with $|\alpha_i| \geq 1$. For any compact $K \subset \Omega$ it follows that 

$$
\frac{\|\partial^{\alpha_1} \psi\|_{L^s(K)}}{s(\alpha_1)} + \cdots + \frac{1}{s(\alpha_m)} + \frac{1}{t} \leq \frac{1}{q}.
$$

(A.6)

Here we have used the generalized Hölder inequality, and the change of variables theorem to pass from $\|F(m) \circ \psi\|_{L^s(K)}$ to $\|F(m)\|_{L^t(\psi(K)\psi)}$. By Sobolev’s embedding we have $F(m) \in L^r(\psi(K))$ for all $r$ satisfying

$$
\frac{1}{r} > \frac{1}{q} + \frac{m - \ell}{n}.
$$

(A.7)

Consider, first, those terms in (A.6) for which the right hand side of (A.8) is positive (if any). Let $r$ be defined by Equation (A.8) with $>$ replaced by $=.$ Set

$$
\frac{1}{s(\alpha_i)} = \frac{|\alpha_i| - 1}{n};
$$

(A.9)

since $kp > n$ we have

$$
\frac{1}{s(\alpha_i)} > \frac{1}{p} - \frac{k}{n} + \frac{|\alpha_i| - 1}{n},
$$

(A.10)

and Sobolev’s embedding theorem implies that $\|\partial^{(\alpha_i)} \psi\|_{L^s(\alpha_i)(K)}$ is finite. With this choice of $r$ and of the $s(\alpha_i)$’s we have

$$
\sum \frac{1}{s(\alpha_i)} + \frac{1}{r} = \frac{|\alpha| - m}{n} + \frac{1}{q} + \frac{m - \ell}{n} = \frac{|\alpha| - \ell}{n} + \frac{1}{q} \leq \frac{1}{q},
$$

so that those terms will give a finite contribution to the right hand side of (A.6) by setting $t = r$.

Consider, next, those terms in (A.6) for which the right hand side of (A.8) vanishes. If all the $\alpha_i$’s have length one the term in question will give a finite contribution to the right hand side of (A.6) by setting $t = q$. If one of the $\alpha_i$’s, say $\alpha_1$, has length larger than 1, for $i \geq 2$ we choose the $\alpha_i$’s as in (A.9), while we set $1/s(\alpha_1) = (|\alpha_1| - 1)/n - \epsilon > 0$, with $0 < \epsilon$ so chosen that (A.10) still holds, $\epsilon < (kp - n)/2pn$. Choosing $1/t = \epsilon$ will lead to a finite contribution in (A.6).

It remains to consider those terms in (A.6) for which the right hand side of (A.8) is negative. In this case we set $t = \infty$, and

$$
\frac{1}{s(\alpha_i)} = \frac{|\alpha_i|}{\ell q} \implies \sum \frac{1}{s(\alpha_i)} = \frac{|\alpha|}{\ell q} \leq \frac{1}{q}.
$$

(A.11)
By Sobolev’s embedding \( \| \partial^{\alpha_1} \psi \|_{L^s(\alpha_1)(K)} \) will be finite when (A.10) holds. Now Equation (A.10) with \( s(\alpha_i) \) defined by (A.11) is equivalent to

\[
\frac{|\alpha_i|}{\ell} \left( \frac{1}{q} - \frac{\ell}{n} \right) > \frac{1}{p} - \frac{k-1}{n} .
\]  

(A.12)

The right hand side of (A.12) is negative. If the left hand side is positive or vanishes there is nothing to check. If both sides are negative the worst case is obtained with \( |\alpha_i| = \ell \), and the inequality holds when (A.4) is an inequality. The simple analysis of the case of equality in (A.4) is left to the reader.

Before returning to the proof of Proposition A.1 we need one more Lemma:

**Lemma A.4** Let \( 0 \leq m \leq \ell \leq k \), \( q, p \in [1, \infty) \), \( kp > n \). Suppose that \( (\ell, q) \) is such that the Sobolev embedding \( W^{k,p}_{\text{loc}} \subset W^{\ell,q}_{\text{loc}} \) holds, cf. Equations (A.5) and (A.2). Then the product map

\[
W^{k-m,p}_{\text{loc}} \times W^{\ell,q}_{\text{loc}} \ni (f, g) \rightarrow fg \in W^{\ell-m,q}_{\text{loc}}
\]

is continuous.

**Proof:** For any \( 0 \leq |\alpha| \leq \ell - m \) the Leibniz rule gives

\[
\partial^{\alpha}(fg) = \sum_{\alpha_1+\alpha_2=\alpha} C_{\alpha_1,\alpha_2} \partial^{\alpha_1} f \partial^{\alpha_2} g ,
\]

so that on any compact set \( K \subset M \) the Hölder inequality gives

\[
\| \partial^{\alpha}(fg) \|_{L^q(K)} \leq C \sum_{\alpha_1+\alpha_2=\alpha} \| \partial^{\alpha_1} f \|_{L^s(\alpha_1)(K)} \| \partial^{\alpha_2} g \|_{L^s(\alpha_2)(K)} , \quad (A.13)
\]

\[
\frac{1}{s(\alpha_1)} + \frac{1}{s(\alpha_2)} \leq \frac{1}{q} .
\]  

(A.14)

Let

\[
a(\alpha_1) = \frac{1}{p} + \frac{|\alpha_1| - k + m}{n} ,
\]

\[
a(\alpha_2) = \frac{1}{q} + \frac{|\alpha_2| - \ell}{n} .
\]

By Sobolev’s embedding we will have \( \partial^{\alpha_1} f \in L^{s(\alpha_1)}(K) \), \( \partial^{\alpha_2} g \in L^{s(\alpha_2)}(K) \) when

\[
\frac{1}{s(\alpha_i)} > a(\alpha_i) .
\]  

(A.15)

We have the following cases:

- If \( a(\alpha_1) \leq 0 \) and \( a(\alpha_2) \leq 0 \) we set \( s(\alpha_i) = q/2 \), and we obtain

\[
\| \partial^{\alpha_1} f \|_{L^{s(\alpha_1)}(K)} \| \partial^{\alpha_2} g \|_{L^{s(\alpha_2)}(K)} \leq C \| f \|_{W^{k-m,p}(K)} \| g \|_{W^{\ell,q}(K)} \quad (A.16)
\]
• If \( a(\alpha_1) > 0 \) and \( a(\alpha_2) > 0 \) we set \( 1/s(\alpha_i) = a(\alpha_i) \) so that (A.15) holds, and we obtain
\[
\frac{1}{s(\alpha_1)} + \frac{1}{s(\alpha_2)} = \frac{1}{q} + \frac{1}{p} + \frac{|\alpha| - k - \ell + m}{n} \leq \frac{1}{q} + \frac{1}{p} - \frac{k}{n} < \frac{1}{q},
\]
since \( kp > n \), so that (A.14) holds. We note that (A.16) is again satisfied.

• If \( a(\alpha_1) = 0 \) and \( a(\alpha_2) > 0 \) we have
\[
\frac{|\alpha_2|}{n} = \frac{|\alpha| - |\alpha_1|}{n} = \frac{|\alpha| - k + m}{n} + \frac{1}{p},
\]
so that
\[
a(\alpha_2) = \frac{1}{q} + \frac{1}{p} + \frac{|\alpha| - k - \ell + m}{n} \leq \frac{1}{q} + \frac{1}{p} - \frac{k}{n} < \frac{1}{q}. \tag{A.17}
\]
Let \( \epsilon \) be any number satisfying \( 0 < \epsilon < (kp - n)/np \), set
\[
\frac{1}{s(\alpha_1)} = \frac{\epsilon}{2}, \quad \frac{1}{s(\alpha_2)} = a(\alpha_2) + \frac{\epsilon}{2}.
\]
Decreasing \( \epsilon \) if necessary we will have \( s(\alpha_2) > 0 \). Then (A.14), (A.15) and (A.16) hold by the calculation in Equation (A.17). A similar analysis takes care of the case \( a(\alpha_1) > 0 \) and \( a(\alpha_2) = 0 \).

• If \( a(\alpha_1) < 0 \) and \( a(\alpha_2) > 0 \) we set \( s(\alpha_1) = \infty \) and \( s(\alpha_2) = q \).

• If \( a(\alpha_1) > 0 \) and \( a(\alpha_2) < 0 \) we set \( s(\alpha_1) = q \) and \( s(\alpha_2) = \infty \); (A.14) obviously holds, while
\[
\frac{1}{s(\alpha_1)} - a(\alpha_1) = \frac{1}{q} - \frac{1}{p} + \frac{k - m - |\alpha_1|}{n} \geq \frac{1}{q} - \frac{1}{p} + \frac{k - \ell}{n}
\]
which is non-negative by (A.5), hence (A.15) and (A.16) hold again.

This establishes that \( fg \in W^{l-m,q}_{loc} \). The continuity follows immediately from the inequality
\[
\|fg\|_{W^{l-m,q}(K)} \leq C\|f\|_{W^{k-m,p}(K)}\|g\|_{W^{l,q}(K)}
\]
which has been established during the proof.

We can pass now to the proof of point 2 of Proposition A.1. Let two coordinate systems on \( M \) be given related to each other by a map \( \psi \in W^{k+1,p}_{loc} \), set \( \chi \equiv \psi^{-1} \). Let \( \mu^{\alpha_1...\alpha_k} \beta_1...\beta_s \) and \( \hat{\mu}^{\mu_1...\mu_k} \nu_1...\nu_s \) be the coordinate components of a tensor field \( t \), with \( \mu^{\alpha_1...\alpha_k} \beta_1...\beta_s \in W^{l,q} \). We have the transformation rule
\[
\hat{\mu}^{\mu_1...\mu_k} \nu_1...\nu_s(x) = \mu^{\alpha_1...\alpha_k} \beta_1...\beta_s(\psi(x)) \frac{\partial \psi^{\beta_1}}{\partial x^{\nu_1}}(x) \cdots \frac{\partial \psi^{\beta_s}}{\partial x^{\nu_s}}(x) \frac{\partial \chi^{\mu_1}}{\partial x^{\alpha_1}}(\psi(x)) \cdots \frac{\partial \chi^{\mu_k}}{\partial x^{\alpha_k}}(\psi(x)). \tag{A.18}
\]
Now the matrix $\frac{\partial \chi^\mu}{\partial x^\alpha} \circ \psi$ is the inverse matrix to $\frac{\partial \psi^\beta}{\partial x^\nu}$, so the components of the former are rational function of those of the latter. We recall the Gagliardo–Moser–Nirenberg inequalities (cf., e.g. [41, Corollaries 6.4.4 and 6.4.5])

$$\forall \, f, g \in W^{\ell,q} \cap L^\infty \quad \|fg\|_{W^{\ell,q}} \leq C_1 (\|f\|_{L^\infty} \|g\|_{W^{\ell,q}} + \|f\|_{W^{\ell,q}} \|g\|_{L^\infty}) \quad (A.19)$$

$$\forall \, f \in W^{\ell,q} \cap L^\infty \quad \|F(f)\|_{W^{\ell,q}} \leq C_2 (\|f\|_{L^\infty}) (1 + \|f\|_{W^{\ell,q}}) \quad (A.20)$$

for some $f$ and $g$ independent constant $C_1$, and for some constant $C_2(\|f\|_{L^\infty})$ depending upon $f$ only through its $L^\infty$ norm. Here one assumes that $F$ is a smooth function of its argument which is allowed to take values in $\mathbb{R}^N$, and the integrals are taken over compact sets. Equations (A.19)–(A.20) show that the $\frac{\partial \chi^\mu}{\partial x^\alpha} \circ \psi$'s are $W^{k,p}_{loc}$ functions of their arguments. Lemma A.4 implies that

$$\frac{\partial \psi^\beta_1}{\partial x^{\alpha_1}}(x) \cdots \frac{\partial \psi^\beta_s}{\partial x^{\alpha_s}}(x) \frac{\partial \chi^\mu_1}{\partial x^{\alpha_1}}(\psi(x)) \cdots \frac{\partial \chi^\mu_k}{\partial x^{\alpha_k}}(\psi(x)) \in W^{k,p}_{loc}.$$

It follows that the right hand side of Equation (A.18) is of the form

$$t \circ \psi A, \quad t \in W^{\ell,q}_{loc}, \quad \psi \in W^{k+1,p}_{loc}, \quad A \in W^{k,p}_{loc}.$$

Lemma (A.2) implies that $t \circ \psi \in W^{\ell,q}_{loc}$, and Lemma A.4 with $m = 0$ shows that the right hand side of Equation (A.18) is in $W^{\ell,q}_{loc}$, as desired. 

We wish to extend the above discussion to spinor fields; this requires the introduction of orthonormal frames, and hence of the metric. Consider, then, a $W^{k+1,p}_{loc}$ manifold $M$ with a strictly positive definite symmetric two-covariant tensor field $g$. We shall say that $(M,g)$ is a pseudo–Riemannian $W^{k+1,p}_{loc}$ manifold if $M$ is a $W^{k+1,p}_{loc}$ manifold and if $g$ is a pseudo–Riemannian metric of $W^{k,p}_{loc}$ differentiability class. This is an invariantly defined notion by Proposition A.1. Before proceeding further we note the following:

**Proposition A.5** Let $(M,g)$ be a $W^{k+1,p}_{loc}$ manifold with a pseudo–Riemannian metric of $W^{k,p}_{loc}$ differentiability class, $kp > n$, $p \in [1, \infty]$. Then the following hold

1. In any coordinate system in the $W^{k+1,p}_{loc}$ atlas the Christoffel coefficients $\Gamma^i_{jk}$ satisfy

$$\Gamma^i_{jk} \in W^{k-1,p}_{loc}.$$

2. The Riemann tensor is of $W^{k-2,p}_{loc}$ differentiability class.

3. The curvature scalar $R \equiv g^{ij} R^{ikj}$ is of $W^{k-2,p}_{loc}$ differentiability class.

4. Assume that $\ell \geq 1$ and suppose that $(\ell, q)$ is such that the Sobolev embedding $W^{k,p}_{loc} \subset W^{\ell,q}_{loc}$ holds, cf. Equations (A.5) and (A.2). Let $t$ be a tensor field of $W^{\ell,q}_{loc}$ differentiability class, then for any vector field $X \in W^{k,p}_{loc}$ we have

$$X^i \nabla_i t \in W^{\ell-1,q}_{loc}.$$
Proof: 1. By definition of the $\Gamma^i_{jk}$'s we have

$$\Gamma^i_{jk} = \frac{1}{2} g^{it} \left( \frac{\partial g_{ti}}{\partial x^j} + \frac{\partial g_{tk}}{\partial x^j} - \frac{\partial g_{jk}}{\partial x^t} \right).$$

By (A.19) we have $g^{it} \in W^{k,p}_{loc}$, by definition the derivatives of the metric are in $W^{k-1,p}_{loc}$, and Lemma A.4 with $m = 0$ and $(\ell,q) = (k-1,p)$ gives the result.

2. By definition of the curvature tensor we have

$$R^i_{jkl} = \frac{\partial \Gamma^i_{jk}}{\partial x^l} - \frac{\partial \Gamma^i_{jl}}{\partial x^k} + \Gamma^i_{mk} \Gamma^m_{jlk} - \Gamma^i_{ml} \Gamma^m_{jkl},$$

Lemma A.4 with $m = 1$ and $(\ell,q) = (k-1,p)$ shows that the product terms above are in $W^{k-2,p}_{loc}$, and the result follows from point 1.

3. This claim follows immediately from point 2, from $g^{it} \in W^{k,p}_{loc}$ and from Lemma A.4 with $m = 0$ and $(\ell,q) = (k-2,p)$.

4. Let $t$ be a tensor field of $W^{\ell,q}_{loc}$ differentiability class, in local coordinates we have

$$\nabla_t t^{\alpha_1 \ldots \alpha_k}_{\beta_1 \ldots \beta_s} = \partial_t t^{\alpha_1 \ldots \alpha_k}_{\beta_1 \ldots \beta_s} + \Gamma^i_{\alpha \sigma} t^{\sigma \ldots \alpha_k}_{\beta_1 \ldots \beta_s} + \ldots - \Gamma^s_{i \beta_1} t^{\alpha_1 \ldots \alpha_k}_{\sigma \ldots \beta_s} + \ldots.$$

The $\Gamma$'s are in $W^{k-1,p}_{loc}$ by point 1, thus the product terms are in $W^{\ell-1,q}_{loc}$ by Lemma A.4 with $m = 1$. The claim about $X^i \nabla_t t$ follows again from Lemma A.4.

Let $(M,g)$ be a $W^{k+1,p}_{loc}$ pseudo–Riemannian manifold and let $\mathcal{O}N_{M,g}$ be the bundle of $g$–orthonormal frames on $M$. We can equip $\mathcal{O}N_{M,g}$ with a $W^{k,p}_{loc}$ structure by considering only those $g$–orthonormal sets of vector fields which are all of $W^{k,p}_{loc}$ differentiability class. Let us start by showing that the set of such (locally defined) frames is not empty. On $\mathcal{O}$, the domain of a coordinate system $(x^i)$, we can construct a $g$–orthonormal frame $e_j = e_j^i \partial / \partial x^i$ by performing a Gram–Schmidt orthonormalisation of the basis $\{\partial / \partial x^i\}$. By construction the coordinate coefficients $e_j^i$ of the vector fields $e_j$ are smooth functions of $g_{ij}$ (at least on a neighborhood of the range of values taken by $g_{ij}$), where the $g_{ij}$'s are the coordinate coefficients of the metric $g$, $g = g_{ij} dx^i dx^j$. Since $kp > n$, (A.19)–(A.20) applied to the $e_j^i$ considered as functions of the $g_{ij}$ shows that the vector fields $e_j$ are indeed of $W^{k,p}_{loc}$ differentiability class, as desired.

The following shows that the $W^{k,p}_{loc}$ structure of $\mathcal{O}N_{M,g}$ is an invariantly defined property of a $W^{k+1,p}_{loc}$ pseudo–Riemannian manifold:

Proposition A.6 Any two (globally or locally defined) $g$–orthonormal frames of $W^{k,p}_{loc}$ differentiability class are related to each other by a $O(n)$–rotation of $W^{k,p}_{loc}$ differentiability class.

Proof: Consider two locally defined $g$–orthonormal frames $e_i$ and $f_i$, $i = 1, \ldots, n = \dim M$, of $W^{k,p}_{loc}$ differentiability class. In particular each of the $e_i$ and $f_i$ is a vector field of $W^{k,p}_{loc}$ differentiability class, which is invariantly defined by Proposition A.1, so that it is sufficient to prove the result in any
coordinate system in the $W^{k+1,p}_{\text{loc}}$ atlas on $M$. In such a coordinate system $\{x^i\}$ we can write $e_j = e_j^i \frac{\partial}{\partial x^i}$, $f_j = f_j^i \frac{\partial}{\partial x^i}$, for some functions $e_j^i, f_j^i \in W^{k,p}_{\text{loc}}$. Since both frames are orthonormal there exists an $O(n)$–valued function $w_i^j$ such that

$$e_i = w_i^j f_j.$$  \hfill (A.21)

It follows that

$$w_i^j = e_i^k f_j^k,$$

where $f_j^k$ is the matrix inverse to $f_j^k$. We have $f_j^k \in W^{k,p}_{\text{loc}}$ by (A.20), thus $w_i^j \in W^{k,p}_{\text{loc}}$ by (A.19), hence the result. \hfill \blacksquare

Now suppose that $M$ has a spin structure, namely a Spin–principal bundle $\tilde{\mathcal{F}}$ which double-covers the principal bundle $\mathcal{F}$ of $g$–orthonormal frames of $(M,g)$:

$$0 \to \mathbb{Z}_2 \to \tilde{\mathcal{F}} \xrightarrow{\pi} \mathcal{F} \to M.$$  \hfill (A.22)

We note that the obstruction to the existence of such structures is purely topological, (cf., e.g., [45, Chapter II]) and therefore independent of the choice of the metric and differentiability class. A bundle of spinors $\mathcal{V} = \tilde{\mathcal{F}} \times_T V$ is a vector bundle associated to $\tilde{\mathcal{F}}$ and a representation $T : \text{Spin} \to \text{End}(V)$, for some finite-dimensional vector space $V$. A choice of $g$–orthonormal frame $e = (e_i)$ of $W^{k,p}_{\text{loc}}$ differentiability class defined on an open set $O \subset M$ determines a local section of $\mathcal{F}$. This lifts to a section of $\tilde{\mathcal{F}}$, which in turn is associated with a local orthonormal frame $\phi = (\phi_1)$ in $\mathcal{V}$. Let $U$ be another open set with a $g$–orthonormal frame $e' = (e'_i)$, so by Proposition A.6 there exists an $O(n)$ valued map $w = (w_i^j)$ of $W^{k,p}_{\text{loc}}$ differentiability class such that the frames $e, e'$ are related by $e_i = w_i^j e'_j$ on $O \cap U$. The map $w : O \cap U \to \text{SO}$ lifts to $\tilde{w} : O \cap U \to \text{Spin}$. This lift is not unique, but the possible lifts differ only by a fixed nontrivial element $z$ of the centre $Z(\text{Spin}) \simeq \mathbb{Z}_2$. The corresponding spin frames $\phi, \phi'$ are related by $\phi = T(\tilde{w}) \phi'$ or $T(z \tilde{w}) \phi'$. Analyticity of the local inverse $\pi^{-1}(\cdot)$ and the inequality (A.20) show that $T(\tilde{w}), T(z \tilde{w}) \in W^{k,p}_{\text{loc}}$, and it follows from (A.19) that the spin frames $\phi$ on $U$ and $\phi'$ on $O$ are $W^{k,p}_{\text{loc}}$ compatible on $U \cap O$. This establishes the following result:

**Proposition A.7** Let $(M,g)$ be a $W^{k+1,p}_{\text{loc}}$ spin manifold with a pseudo–Riemannian metric of $W^{k,p}_{\text{loc}}$ differentiability class. Then every spinor bundle carries a natural $W^{k,p}_{\text{loc}}$ differentiable structure.

An argument similar to that of Proposition A.1 shows:

**Proposition A.8** Let $(M,g)$ be a $W^{k+1,p}_{\text{loc}}$ spin manifold with a pseudo–Riemannian metric of $W^{k,p}_{\text{loc}}$ differentiability class, $kp > n, p \in [1, \infty]$. Let $(\ell, q)$ be such that the Sobolev embedding

$$W^{k,p}_{\text{loc}} \subset W^{\ell,q}_{\text{loc}}$$

holds, cf. Equations (A.5) and (A.2). Then the space of $W^{\ell,q}_{\text{loc}}$ spinor fields is invariantly defined.
To proceed further, we recall the definition of the covariant
derivative of a spinor field. Let \( V, e_i, O \subset M \) and \( \gamma_i \) be as before, and let \( \phi = (\phi_I) \) be the spinor frame corresponding to the orthonormal frame \( e = (e_i) \). This defines a preferred local spin frame, with respect to which the Clifford action is represented by locally constant matrices \( \gamma_i \). Let \( \psi \) be a spinor field over \( O \); the spinor covariant derivative of \( \phi \) is given in terms of the orthonormal frame connection matrix \( \omega_{ij}(e_k) = g(e_i, \nabla_{e_k} e_j) \) and the spinor frame components \( \psi = \psi^I \phi_I \) by (2.2), and the Dirac operator of \( \nabla \) on \( S \) is defined by

\[
\mathcal{D}_\psi = \gamma^i \nabla_{e_i} \psi .
\]

(A.23)

**Proposition A.9** Let \((M, g)\) be a \( W^{k+1,p}_{loc} \) manifold with a pseudo–Riemannian metric of \( W^{k,p}_{loc} \) differentiability class, \( kp > n \), \( p \in [1, \infty] \). Then the following hold

1. Let \( e^i \) be any \( g \)-orthonormal frame of \( W^{k,p}_{loc} \) differentiability class, then the spin connection coefficients \( \omega_k \) defined as \( \nabla_{e_k} \psi = e_k(\psi) + \omega_k \psi \) satisfy \( \omega_k \in W^{k-1,p}_{loc} \).

2. If \((\ell, q)\) is as in Proposition A.8 with \( \ell \geq 1 \), and if \( X \) is a vector field of \( W^{k,p}_{loc} \) differentiability class, then \( \nabla_X \) maps continuously \( W^{\ell,q}_{loc} \) spinor fields to \( W^{\ell-1,q}_{loc} \) spinor fields:

\[
W^{\ell,q}_{loc} \ni \phi \rightarrow \nabla_X \phi \in W^{\ell-1,q}_{loc} .
\]

In particular the Dirac operator maps continuously \( W^{\ell,q}_{loc} \) to \( W^{\ell-1,q}_{loc} \).

**Proof:** To prove point 1 choose a spin frame in which the \( c(e^i) \)'s are point independent matrices. Then

\[
\omega_k \equiv -\frac{1}{4} c(e^i) c(e^j) \omega_{ij}(e_k) ,
\]

with \( \omega_{ij}(e_k) \equiv g(e_i, \nabla_{e_k} e_j) \). The claim that \( \omega_{ij}(e_k) \in W^{k-1,p}_{loc} \) follows immediately from point 4 of Proposition A.5 and from Lemma A.4. The result in any spin frame follows from the transformation rule of the connection coefficients under changes of frames and from Lemma A.4. The proof of point 2 follows that of point 4 of Proposition A.5 and will be omitted.

Given a smooth metric in a neighbourhood of a compact boundary \( \partial M \), geodesics normal to the boundary determine a diffeomorphism of \( Y \times I \) with a neighbourhood of \( \partial M \cong Y \), such that in adapted coordinates \( v = (y^A, x) \), \( x \in [0, x_0) \), \( y^A \in U_i \) we have

\[
g^{xx} \equiv 1, \quad g^{xA} \equiv 0.
\]

(A.24)

The diffeomorphism determines a *tubular neighbourhood* of \( \partial M \) and the resulting coordinates are called *Gaussian coordinates*. If the metric has only low differentiability then uniqueness of the geodesic equation may fail, and the existence of Gaussian coordinates becomes problematic. However, for our applications it is sufficient for (A.24) to hold only approximately near \( \partial M \), in which case we may rely on the following result.
Proposition A.10 (Almost Gaussian tubular neighbourhood coordinates for \( \partial M \)). Let \( k \in \mathbb{N}, \ell \in \mathbb{N} \cup \{0\} \), and suppose \((M,g)\) be a \( W^{k+1,p}_{\text{loc}} \) Riemannian manifold with metric \( g \in W^{k,p}_{\text{loc}}(M) \), \((k-\ell)p > n \). Let \( Y \subset M \) be a compact connected component of the boundary of \( M \) with \( Y \) of \( W^{k+1,p}_{\text{loc}} \) differentiability class. There is a neighbourhood \( \mathcal{O} \) of \( Y \subset M \) and \( x \in W^{k+1,p}(\mathcal{O}) \), and a diffeomorphism \( \mathcal{O} \cong Y \times I \), \( I = [0,x] \), which determines coordinates \((v^i) = (y^A,x) \in \mathcal{O} \) such that \( Y \cap \mathcal{O} = \{ x = 0 \} \) and

\[
\begin{align*}
  g(du^i,du^j) &= g^{ij} \in W^{k,p}(\mathcal{O}), \\
  g(dx, dx) &= 1 = O(x^\ell+\sigma), \\
  g(dx, dy^A) &= O(x^\ell+\sigma),
\end{align*}
\]

for some \( \sigma > 0 \).

Remarks: 1. A similar result for \( C^{k,1} \) metrics, \( k \geq 1 \), follows from [3, Appendix B].
2. Similar results hold for pseudo–Riemannian manifolds provided \( Y \) is non–characteristic, and when \( Y \) is a hypersurface in \( M \).

Proof: If \( k = \infty \) we can use Gauss coordinates near \( Y \), and the result follows. Suppose thus that \( k < \infty \), let \( x \) be any defining function for \( Y \) and let \( \mathcal{O}_\alpha \) be any conditionally compact coordinate neighborhood of \( Y \), with \( g^{ij} \equiv g(dx^i,dy^j) \in W^{k,p}(\mathcal{O}_\alpha) \). Passing to a subset of \( \mathcal{O}_\alpha \) if necessary without loss of generality we may assume \( \mathcal{O}_\alpha \approx [0,x_0] \times U_\alpha, U_\alpha \subset Y \). Coordinate systems of this form will be called cylindrical.

We construct a suitable \( W^{k+1,p} \) coordinate change \((\bar{y}^A, \bar{x}) \) in \( \mathcal{O}_\alpha \times I \) by noting first that \( \bar{d}x = \frac{\partial \bar{x}}{\partial x} dx + \frac{\partial \bar{x}}{\partial y} dy \), \( \bar{dy}^A = \frac{\partial \bar{y}^A}{\partial x} dx + \frac{\partial \bar{y}^A}{\partial y} dy \). Thus if \( \bar{x} \) is also a boundary coordinate, so \( \bar{x}(y,0) = 0 \) and \( \frac{\partial \bar{x}}{\partial y} = 0 \) on \( Y \), then the metric coefficients satisfy

\[
\begin{align*}
  g^{\bar{x}\bar{x}} &= g(dx, dx) \\
  &= \left( \frac{\partial \bar{x}}{\partial x} \right)^2 \frac{g^{xx}}{\partial x} + 2 \frac{\partial \bar{x}}{\partial x} \frac{\partial \bar{x}}{\partial y} \frac{g^{xA}}{\partial y} + \frac{\partial \bar{x}}{\partial y} \frac{\partial \bar{x}}{\partial y} g^{AB} \\
  &= \left( \frac{\partial \bar{x}}{\partial x} \right)^2 g^{xx} \text{ on } Y = \{ x = 0 \}, \\
  g^{\bar{x}\bar{A}} &= g(dx, dy^A) \\
  &= \frac{\partial \bar{x}}{\partial x} \left( \frac{\partial \bar{y}^A}{\partial x} g^{xx} + \frac{\partial \bar{y}^A}{\partial y} g^{xB} \right) \text{ on } Y.
\end{align*}
\]

Since \( g^{xx} \in W^{k,p} \), the restriction \( g^{xx}|_Y \) lies in the Besov space \( \Lambda_{k-1/p}^{p,p}(Y) \) (see [59, \S VI.4.4], or [43, Theorem VII.1]) and there is an extension \( \bar{x} = \bar{x}(y,x) \in W^{k+1,p}(\mathcal{U}_\alpha \times I) \) satisfying the conditions

\[
\bar{x}(y,0) = 0, \quad \frac{\partial \bar{x}}{\partial x}(y,0) = (g^{xx})^{-1/2}(y,0),
\]

for \( y = (y^A) \in \mathcal{O}_\alpha \) ([59, \S VI.6], [43, Theorem VII.3]). This implies

\[
g^{\bar{x}\bar{x}} = g(dx, dx) \in W^{k,p}(\mathcal{U}_\alpha \times I)
\]
and $g^{xx} = 1$ when $x = 0$. Similarly, there is $f^A(y, x) \in W^{k+1,p}(U_\alpha \times I)$ such that

$$f^A(y, 0) = 0, \quad \frac{\partial f^A}{\partial x}(y, 0) = -\frac{g^{xA}}{g^{xx}}(y, 0),$$

so the coordinates $(\bar{y}, \bar{x})$, $\bar{y}^A(y, x) = y^A + f^A(y, x)$ also satisfy

$$g^{\bar{x}\bar{x}}(y, 0) = g(dx, dy^A) = 0$$
on $Y$, since $dy^A = dy^A - g^{xA}/g^{xx} \, dx$.

As shown in Proposition A.1, in the new coordinate system $(\bar{v}^i) \equiv (\bar{y}^A, \bar{x})$ we still have $g(d\bar{v}^i, d\bar{v}^j) \in W^{k,p}(\mathcal{O}_\alpha)$, so that by embedding theorems the metric coefficients are $\sigma$–Hölder continuous on $\mathcal{O}_\alpha$, for some $\sigma > 0,$ and

$$g^{\bar{x}\bar{x}} = O(x^\sigma), \quad g^{\bar{x}\bar{A}} = O(x^\sigma). \quad (A.28)$$

Let $\phi, f^A \in W^{k+1,p}(\mathcal{O}_\alpha)$, and consider the effect of the change

$$\bar{x} = x + \phi(y, x), \quad \bar{y}^A = y^A + f^A(y, x), \quad (A.29)$$

where $\phi(y, 0) = 0$, $f^A(y, 0) = 0$. Then

$$g^{\bar{x}\bar{x}} = g^{xx} + 2g^{xi} \frac{\partial \phi}{\partial v^i} + g^{ij} \frac{\partial \phi}{\partial v^i} \frac{\partial \phi}{\partial v^j}, \quad (A.31)$$

$$g^{\bar{x}\bar{A}} = g(dx, dy^A) = g^{xA} + g^{xi} \frac{\partial f^A}{\partial v^i} + g^{Ai} \frac{\partial \phi}{\partial v^i} + g^{ij} \frac{\partial \phi}{\partial v^i} \frac{\partial f^A}{\partial v^j}. \quad (A.32)$$

Suppose that for some $\ell \geq 0$ we have

$$g^{xx} - 1 = O(x^{\ell+\sigma}), \quad g^{xA} = O(x^{\ell+\sigma}). \quad (A.33)$$

This holds for $\ell = 0$ by (A.28) and we establish the general case by induction. Again by restriction and extension results [43,59] there exist $\phi, f^A \in W^{k+1,p}(\mathcal{O}_\alpha)$ satisfying

$$\left. \frac{\partial^{l+1}\phi}{\partial x^l} \right|_{(y,0)} = -\frac{1}{2} \left. \frac{\partial g^{xx}}{\partial x^l} \right|_{(y,0)}, \quad \left. \frac{\partial^{l+1} f^A}{\partial x^l} \right|_{(y,0)} = -\left. \frac{\partial g^{xA}}{\partial x^l} \right|_{(y,0)},$$

while all the lower order $x$–derivatives of $\phi, f^A$ vanish at $x = 0$. Passing to coordinates $(\bar{y}, \bar{x})$ on a (possibly smaller) cylindrical neighborhood $\mathcal{O}_\alpha$, one finds from (A.31)–(A.32) that (A.33) still holds and moreover,

$$g^{\bar{x}\bar{x}} - 1 = O(x^{\ell+1+\sigma}), \quad g^{\bar{x}\bar{A}} = O(x^{\ell+1+\sigma}).$$

Dropping bars one finds that (A.33) holds with $\ell$ replaced by $\ell + 1$, and the induction step is complete.

Finally we show that the local charts can be combined to form a tubular neighbourhood diffeomorphism. It follows from (A.31) that if $x, \bar{x}$ both satisfy
(A.28) and vanish on $Y$, then $g(dx, d\bar{x}) = 1$. In particular, by combining the functions $\bar{x}_\alpha$ from each of the local coordinate charts $O_\alpha$ using a subordinate partition of unity $\phi_\alpha$, the function $x = \Sigma_\alpha \phi_\alpha \bar{x}_\alpha$ satisfies $x \in W^{k+1,p}(Y \times I)$ and $x = 0$, $g^{xx} = 1$ on $Y$.

In order to construct a diffeomorphism with $Y \times I$ we need to construct a similar averaging of the $\bar{y}^A$ coordinate functions. Fix a smooth embedding $\Phi : Y \to \mathbb{R}^K$ and let $\Pi_{\Phi(Y)} : N \subset \mathbb{R}^K \to \Phi(Y)$ be the orthogonal projection in $\mathbb{R}^K$ from a tubular neighbourhood $N$ back to $\Phi(Y)$. Let $y_\alpha = (y^A_\alpha) : U_\alpha \subset Y \to \mathbb{R}^{n-1}$ denote both the coordinates of a $C^\infty$ chart on $Y$, and their natural extension to $y_\alpha = (\tilde{y}^A_\alpha) : \tilde{O}_\alpha = U_\alpha \times I \subset Y \times I \to \mathbb{R}^{n-1}$. Let $\bar{y}_\alpha = (\bar{y}^A_\alpha) : O_\alpha \to \mathbb{R}^{n-1}$ be the functions constructed above, so there is a neighbourhood $\tilde{O}_\alpha \subset O_\alpha$ containing $Y = Y \times \{0\}$ such that $\bar{y}^{-1}_\alpha \circ \bar{y}_\alpha : \tilde{O}_\alpha \to Y$. Choose a finite covering $\tilde{O}_\alpha$ of $Y \times I$ with subordinate partition of unity $\tilde{\phi}_\alpha$ and define $\Psi : Y \times I \to Y$

\[
\Psi(p) = \Phi^{-1} \circ \Pi_{\Phi(Y)} \left( \sum_\alpha \tilde{\phi}_\alpha(p) \Phi(\bar{y}^{-1}_\alpha \circ \bar{y}_\alpha(p)) \right).
\]

Since $\tilde{y}^A_\alpha(y,0) = y^A$, $\Psi|_{Y \times \{0\}} = Id$ and $(\Psi, x)$ defines a diffeomorphism of $Y \times I$. Now for any $C^\infty$ chart $y = (y^A)$ on $Y$, $\tilde{y}^A := y^A \circ \Psi$ defines a chart on $Y \times I$ by $p \mapsto (\tilde{y}^A(p), x(p))$, which satisfies $\tilde{y}^A(y,0) = y^A$. Moreover, $d\tilde{y}^A(y,0) = dy^A(y,0)$, so $g^{xx}(y,0) = 0$. The condition $g^{xx}(y,0) = 1$ is not affected by changes in the $y$-coordinate, so $(\Psi, x)$ defines the required tubular neighbourhood.

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