Probing Script Knowledge from Pre-Trained Models

Zijia Jin¶, Xingyu Zhang♮, Mo Yu♣, Lifu Huang♠
¶New York University, ♮Xi’an Jiaotong University, ♣WeChat AI, ♠Virginia Tech
¶zj2076@nyu.edu, ♮xy.zhang@stu.xjtu.edu.cn, ♣moyumyu.tencent.com, ♠lifuh@vt.edu

Abstract
Script knowledge is critical for humans to understand the broad daily tasks and routine activities in the world. Recently researchers have explored the large-scale pre-trained language models (PLMs) to perform various script related tasks, such as story generation, temporal ordering of event, future event prediction and so on. However, it’s still not well studied in terms of how well the PLMs capture the script knowledge. To answer this question, we design three probing tasks: inclusive sub-event selection, starting sub-event selection and temporal ordering to investigate the capabilities of PLMs with and without fine-tuning. The three probing tasks can be further used to automatically induce a script for each main event given all the possible sub-events. Taking BERT as a case study, by analyzing its performance on script induction as well as each individual probing task, we conclude that the stereotypical temporal knowledge among the sub-events is well captured in BERT, however the inclusive or starting sub-event knowledge is barely encoded.

1 Introduction
A script is a structure that describes a stereotyped sequence of events that happen in a particular scenario (Schank and Abelson, 1975, 2013). It allows human to keep track of the states and procedures that are necessary to complete various tasks from daily lives to scientific processes. Taking the task of Eating in a Restaurant as an example. A classic example script for this task may consist of a chain of subevents, such as Enter→Order→Eat→Pay (and Tip)→Leave. The script knowledge has shown benefit to many downstream applications, such as story generation (Li et al., 2013, 2018; Guan et al., 2019; Zhai et al., 2019; Lin et al., 2022), machine reading comprehension (Tian et al., 2020; Ostermann et al., 2018; Sugawara et al., 2018), commonsense reasoning (Ding et al., 2019; Huang et al., 2019; Bauer and Bansal, 2021) and so on.

Recent large-scale pre-trained language models (PLMs) (Devlin et al., 2019; Liu et al., 2019; Raffel et al., 2019; Raffel et al., 2019) have shown competitive performance on many natural language processing tasks. Abundant studies have demonstrated that these models either directly capture certain types of syntactic (Goldberg, 2019; Clark et al., 2019; Htut et al., 2019; Rosa and Mareček, 2019), factual (Petroni et al., 2019a, 2020; Bouraoui et al., 2020; Wang et al., 2020) and commonsense knowledge (Zhou et al., 2020; Rajani et al., 2019; Lin et al., 2020) during the pre-training or acquire inductive capability to more efficiently induce such knowledge from natural language text (Pandit and Hou, 2021; Bosselut et al., 2019). However, as another important type of cognitive and schematic knowledge describing human routine activities, scripts are not yet well probed in the language models by prior studies.

To investigate how well the pre-trained language models have captured the script knowledge, in this work, we design three probing tasks and language model prompting methods to probe the script knowledge from PLMs, and further leverage the language model prompting methods to induce the scripts given the main events. Specifically, we aim to answer the following two research questions:

Whether and what script knowledge is captured by the pre-trained language models. To answer this question, we design three sub-tasks to probe the script knowledge, including inclusive sub-event selection (i.e., whether a sub-event is included or excluded in a main event or task), starting sub-event selection (i.e., which sub-event is the start of the script for a particular main event), and sub-event temporal ordering (i.e., predicting a temporal before or after relation between two sub-events). On these sub-tasks, we explore both template-based and soft prompting methods to query the knowledge from pre-trained language models. By investigating their performance gaps to
the fine-tuning results, we find that both the inclusive and starting sub-event selection sub-tasks have relatively poorer performance than that of temporal ordering, which is likely due to the lack of relevant objectives to encourage the models to capture such knowledge during pre-training, and further suggests future research directions to enhance the PLMs to better capture the script knowledge.

How to better generate the scripts from these pre-trained models. With the language model prompting methods, we can select the inclusive sub-events of a particular script, the starting sub-event and subsequent events by predicting the temporal order among all the inclusive sub-events, which can ultimately generate a sequence of events as the script of a main event. Thus, we further design a benchmark dataset to fine-tune the models for the three sub-tasks and evaluate their performance on generating the whole scripts for various main events from diverse domains and topics.

The contributions of this work can be summarized as follows:
• We are the first to formulate the sub-tasks and set up benchmark datasets to probe the script knowledge from pre-trained language models.
• We are the first to research on the generation and evaluation of the whole scripts from pre-trained language models.

2 Related Work

Script Knowledge The definition of Script Knowledge was first proposed in 1981 (Feigenbaum et al., 1981), which aims to detect the relation between two events. Chambers and Jurafsky (2008) created the first unsupervised data-driven method based on point-wise mutual information (PMI) to automatically extract narrative event chains. Recently, researchers explored deep neural networks, especially large-scale pre-train language models to predict the temporal relation between two events (Pustejovsky et al., 2003; Chambers, 2013; Ferraro and Durme, 2016; Reimers et al., 2016) or generate the future event (Pichotta and Mooney, 2014; Jans et al., 2012; Zhang et al., 2020). Comparing with these studies, our work focuses more on investigating how well the PLMs encode or capture the script knowledge from pre-training and their bottleneck, suggesting possible directions for future research.

Language Model Probing Probing is a popular way to detect what knowledge is encoded in PLMs. At first, probing method is designed for detecting morphology knowledge (Belinkov et al., 2017), syntactic knowledge (Peters et al., 2018) and semantic knowledge (Tenney et al., 2019). Then researchers began to pay more attention to more complex knowledge like commonsense knowledge. The two main standard approaches in probing commonsense knowledge is building classifiers (Hewitt and Liang, 2019) or filling text in the gap (Petroni et al., 2019b). In our study, we extend the accuracy based methods and designed a series of downstream tasks specific to Scripts Knowledge.

3 Method

3.1 Script Knowledge Probing

Our first goal is to probe the script knowledge from pre-trained language models. To do so, we divide the script knowledge into three categories: the Inclusive and starting relation between each sub-event and main event, indicating whether the sub-event should be included in or the start of the script of a particular main event, and the temporal relation (i.e., Before or After) among the sub-events. To probe these knowledge from PLMs, we design the following tasks.

Task 1: Inclusive Sub-event Selection As Figure 1 shows, given a main event, e.g., “Clean laundry”, and a candidate sub-event, e.g., “Gather dirty clothes.”, we aim to have the language model to determine whether the sub-event belongs to the script of the target main event. To do so, we use [MASK] to connect them into a whole sequence and use a PLM to encode the sequence into contextual representations. In order to predict the Inclusive relation, we apply a linear function (i.e., a MLM head) to project the [MASK] into a probability distribution over the whole vocabulary of the PLM. By exploring many candidate tokens from the target vocabulary to represent each relation, we finally select “include” to denote the Inclusive relation and “except” for Exclusive.

Task 2: Starting Sub-event Selection Given a main event and a set of sub-events that are predicted to belong to the script of the main event, we aim to select the most probable sub-event as the start of the script. We formulate it as a sequence classification problem. We concatenate the main event and each sub-event candidate with a prompt ”start with”, e.g., Taking bus start with finding bus stop, and use a MLP layer to predict a score indicating how likely
the sub-event is the start of the script of the main event, based on the contextual representation of the [CLS]. As a result, we use the sub-event with the highest score as the first sub-event. We design a margin based loss function to encourage the score of the positive start sub-event to be higher than others.

\[ L(s^*, s_i) = \sum_{s_i \in \hat{S}} \max(score(s_i) + m - score(s^*), 0) \]

where \( s^* \) represents the positive start sub-event of a particular script and \( \hat{S} \) denotes the set of other sub-events from the same script. The margin \( m \) is a hyper-parameter, which is set as 1.0 in our experiment. During inference, given a set of candidate sub-events, we compare their scores and select the one with the highest score as the starting sub-event.

**Task 3: Sub-event Temporal Ordering**  
This probing task is to show the capability of the PLMs on correctly organizing the sub-events into a temporally ordered event sequence. To do so, we design a new language model probing approach following (Petroni et al., 2019c). As shown in Figure 1, given two subevents, e.g., "put clothes in dryer." and "turn on dryer." we use [MASK] to connect them into a sequence and use a PLM to encode it. The temporal relation is predicted by comparing the probability of tokens “before” and “after” based on the contextual representation of [MASK].

### 3.2 Script Induction with PLMs

The second goal in this work is to design a simple yet effective approach to automatically induce scripts based on PLMs. Given a particular main event and a set of candidate sub-events, to induce the script for the target main event, we design a pipeline approach consisting of three steps: (1) selecting a subset of inclusive sub-events from all the candidates; (2) determining the starting sub-event; and (3) ordering all the inclusive sub-events by predicting the temporal relation between each pair of them. These three steps correspond to the three approaches designed for script knowledge probing.

#### 4 Experiment Setup

We take BERT-base-uncased (Devlin et al., 2019) as the target PLM to investigate how well it encodes the script language via the three probing tasks. We combine three script datasets, including DeScript (Wanzare et al., 2016), OMICS (Gupta and Kochenderfer, 2004) and Stories (Trinh and Le, 2018), where each main event is annotated with 7 to 122 scripts written by different crowd-sourcing workers. We sample 60 main events as the evaluation set, 39 main events as the development set and use the remaining 98 main events for training. For the main events in training and development sets, we keep all the scripts, while for each main event in the evaluation set, we only keep the longest script as the target. Table 1 shows the statistics of each dataset.

| Datasets   | # Main Events | # Scripts |
|------------|---------------|-----------|
| Training   | 98            | 4,685     |
| Development| 39            | 1,791     |
| Test       | 60            | 60        |

Table 1: Data statistics for training, development and evaluation Sets.
from other main events’ scripts. For evaluation, as the inclusive sub-event selection requires a pool of all the possible candidate events, we combine the sub-events of all scripts in the evaluation dataset. To create the training samples for the *start sub-event selection* task, we use the first sub-event of each script as the positive sample and all the remaining sub-events from the same script as the negative samples. During the inference, we select the starting sub-event from the inclusive sub-events predicted by the inclusive sub-event selection approach. We use accuracy as the evaluation metric. Finally, for the temporal ordering task, we create each training sample based on each sub-event together with one of its following sub-events. We randomly shuffle the order of each pair of sub-events and create its corresponding label: "before" or "after". To evaluate the quality of the temporal ordering among all the sub-events, we first generate a script based on the predicted temporal order and then use ROUGE-L to evaluate the longest common subsequence between the generated script and the gold script.

We compare the following approaches for each probing task as well as the script induction:

**BERT Pre-trained:** Directly use the pre-trained BERT model to make the predictions on the evaluation set.

**BERT Fine-tuning:** Fine-tune BERT with task-specific training data and evaluate those fine-tuned models on the evaluation set.

**BERT Ptuning:** Following the Ptuning framework (Liu et al., 2021), fine-tune the parameters of both BERT model and prompt tokens.

**BERT Ptuning Freeze:** Only fine-tune the prompt tokens while freezing the parameters of BERT model.

### 5 Results and Analysis

#### 5.1 Overall Script Induction

We first show the results of end-to-end script induction given each main event and the pool of all candidate sub-events. As Table 2 shows, without any fine-tuning, BERT-Pretrained can barely induce any reasonable scripts. The high precision and low recall indicates that the bottleneck is likely in correctly selecting the inclusive sub-events for each main event. However, with fine-tuning either on the whole BERT parameters or a few prompt parameters, the script induction performance can be improved significant, demonstrating that the pre-trained BERT actually captures certain level of script knowledge but requires external probes to induce such knowledge from it. Finally, by analyzing the performance of fine-tuning approaches, we notice a more significant improvement on recall. We conjecture that with fine-tuning, the inclusive sub-event selection is more likely to be improved.

| Method               | Rouge-L | Rec  | Prc  | F-score |
|----------------------|---------|------|------|---------|
| BERT-Pretrained      | 3.25    | 22.60| 4.81 |         |
| BERT-Finetuning      | 37.19   | 28.07| 28.73|         |
| BERT-Ptuning         | 48.70   | 28.78| 32.52|         |
| BERT-Ptuning-Freeze | 85.16   | 0.41 | 0.80 |         |

Table 2: Performance of script induction

#### 5.2 Probing on Individual Tasks

We further analyze the capability of BERT on encoding each type of script knowledge based on the three probing tasks. To avoid error propagation, for both starting sub-event selection and temporal ordering, we use the gold inclusive sub-events of each main input as input.

As Table 3 shows, for inclusive sub-event selection, without fine-tuning, both BERT-Pretrained and BERT-Ptuning-Freeze cannot correctly select any inclusive sub-events. This is likely due to the discrepancy between the pre-training objectives of BERT (i.e., MASK language modeling and next sentence prediction) with the objective of inclusive sub-event selection. With fine-tuning, the performance of both BERT-Finetuning and BERT-Ptuning is improved significantly, which is aligned with our assumption in Section 5.1. Starting sub-event selection is hard to all the approaches, which is likely due to two reasons: one is the limited training samples, and the other is that though we formulate each sub-task as mask prediction to better induce the knowledge from BERT, the pattern “Main_Event starts with Sub_Event” is less likely to appear in the unlabeled corpus than other patterns, such as “Main_Event includes Sub_Event” and “Event_A before/after Event_B”. Finally, all the approaches show consistently descent performance on temporal ordering, no matter whether BERT is fine-tuned or not, demonstrating that BERT has well captured the relations among the events with stereotypical temporal orders, possibly
Table 3: Performance on each individual task.

| Method                     | Inclusive Subevent Selection | Starting Subevent Selection | Temporal Ordering |
|----------------------------|-------------------------------|-----------------------------|-------------------|
|                            | Rec  | Prec | F-score | Accuracy | Rouge-L F1 |
| BERT-Pretrained            | 7.44 | 0.64 | 1.17    | 18.33     | 63.79      |
| BERT-Finetuning            | 33.83| 44.71| 38.51   | 21.66     | 62.87      |
| BERT-Ptuning               | 31.16| 56.24| 40.10   | 20.00     | 63.62      |
| BERT-Ptuning-Freeze        | 98.69| 0.52 | 1.03    | 28.33     | 66.02      |

due to the next sentence prediction objective during pre-training.

6 Conclusion

In this work, we investigate the capability of large-scale pre-trained language models (PLMs) on capturing three aspects of script knowledge: inclusive sub-event knowledge, starting sub-event knowledge and temporal knowledge among the sub-events from the same script. These three types of knowledge can be further leveraged to automatically induce a script for each main event given all the possible sub-events. We use BERT as a target PLM. By analyzing its performance on script induction as well as each individual probing task, we achieve the conclusions that the stereotypical temporal knowledge among the sub-events is well captured in BERT, however the inclusive and starting sub-event knowledge are not well encoded.

7 Limitations

In this paper, we design a three-stages method to evaluate PLMs’ performance in Scripts Knowledge. Although we design those three tasks with pre-prepared candidates as inputs, a more practical condition in real life needs the PLMs to generate scripts from scratch. We plan to use generate models like GPT in the next paper to solve open-domain scripts generation tasks. Moreover, the datasets we used in this paper mostly focused on daily life which not include much scrips knowledge in other domains.

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Appendix

A.1 Examples of Errors

In this section, we’d like to use a couple of examples of errors to show that what kind of information are usually being missed by PLMs. We choose 2 scripts as inputs and test BERT’s (without Finetuning) ability to choose the right candidates and order them.

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