EVERYWHERE REGULARITY OF CERTAIN TYPES OF PARABOLIC SYSTEMS

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ABSTRACT. In this paper I discuss nonlinear parabolic systems that are generalizations of scalar diffusion equations. More precisely, I consider systems of the form

\[ u_t - \Delta [\nabla \Phi(u)] = 0, \]

where \( \Phi(z) \) is a strictly convex function. I show that when \( \Phi \) is a function only of the norm of \( u \), then bounded weak solutions of these parabolic systems are everywhere Hölder continuous and thus everywhere smooth. I also show that the method used to prove this result can be easily adopted to simplify the proof of the result due to Wiegner \([7]\) on everywhere regularity of bounded weak solutions of strongly coupled parabolic systems.

Keywords: parabolic systems, regularity, PDEs, elliptic systems
Mathematics Subject Classification (2000): 35K40 · 35K55 · 35B65 · 35B35 · 35D10

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1. INTRODUCTION

The theory of regularity of nonlinear scalar elliptic and parabolic equations is by now classical. It goes back to the ground breaking work on equations in divergence form by De Giorgi, Moser and Nash in the late fifties. Since then, Hölder estimates for general nonlinear elliptic and parabolic equations were derived by Krylov and Safonov. However, it became clear quite early on, after discovery of counter examples, that nonlinear elliptic and parabolic systems do not, in general, possess everywhere regularity. Instead, only partial regularity results are available \([4]\).

Despite the lack of everywhere Hölder continuity of weak solutions of general elliptic and parabolic systems, there are several nontrivial examples that do possess everywhere

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The author would like to thank his thesis advisor L. C. Evans for his continuous support and helpful advise.
regularity due to their special structure. One of the earliest such examples of a fully non-
linear elliptic system whose weak solutions are everywhere Hölder continuous is due to
Uhlenbeck [6]. She considered elliptic systems of the form
\[-(g(|\nabla u|^2)u_{x_a})_{x_a} = 0 \quad \text{for } i \in \{1 \ldots N\},\]
with some additional ellipticity and grows conditions on \(g\). Uhlenbeck’s proof of Hölder
continuity of weak solutions of these systems relies crucially on the existence of an auxil-
iary function which is subharmonic. This auxiliary function (entropy) is tied to \(|\nabla^2 u|^2\) by
an inequality, and this allows local control on the second derivatives of \(u\).

The parabolic examples of fully nonlinear systems possessing everywhere regularity
followed somewhat later. Wiegner in [7] provided an original example of such a system.
He showed everywhere Hölder continuity of weak solutions of
\[u_t - \Delta (a_{\alpha\beta}u_{x_\beta} + c_{\alpha\beta}H_{x_\beta})_{x_a} = 0,\]
with \(H := H(u)\) a strictly convex function of \(u\) and strict ellipticity conditions on the co-
efficients. His work has been followed by several others, including Dung [2], on strongly
coupled system, and Bae and Choe [11] on a parabolic analog of the example of Uhlen-
beck. Unlike Uhlenbeck’s work, however, none of the proofs of everywhere regularity for
aforementioned parabolic examples rely explicitly on the existence of entropy.

In this paper I provide new examples of parabolic systems whose weak solutions are
everywhere Hölder continuous. These systems are a type of nonlinear diffusion systems,
and are of the form
\[u_t - \Delta (\nabla \Phi(u)) = 0\]
where \(\Phi(z)\) is a strictly convex function. These systems are interesting since they general-
ize scalar nonlinear diffusion equations of the form
\[u_t - \Delta (\gamma(u)) = 0,\]
where \(\gamma\) is strictly increasing. I will show that if \(\Phi(z)\) depends only on the norm of \(z\), then,
together with some smoothness and grows conditions on \(\Phi\), weak solutions of diffusion
systems (1.2) are everywhere Hölder continuous. I will do this by exhibiting an entropy,
and showing that existence of entropy together with properties of general parabolic systems
suffices to prove everywhere regularity. In the conclusion, I will show that regularity of
bounded weak solutions to the strongly coupled systems (1.1) can also be obtained with
the help of an entropy.

Let me introduce notation that I will use throughout this paper. I consider parabolic
space to consist of space and time with space being of \(n\) dimensions and time of one
dimension. In this paper I will deal with cylindrical domains for simplicity. By elliptic
domain \(\Omega \subset \mathbb{R}^n\) I will mean space domain. Cylindrical parabolic domain \(\Omega \times (0, T) \subset \mathbb{R}^n \times \mathbb{R}_t\), where \(T > 0\), will be denoted by \(\Omega_T\). The time interval of the cylindrical domain
\(\Omega_T\), that is the interval \((0, T)\) in the case of \(\Omega_T = \Omega \times (0, T)\), will be denoted by \(I(\Omega_T)\). By \(B_r(x)\) I will mean an \(n\) dimensional ball as a subset of \(\mathbb{R}^n\) with center at \(x\) and of radius \(r\).
\(Q(x, t, r)\) will denote the cylinder
\[Q(x, t, r) := B_r(x) \times (t - r^2, t).\]
I will write \(B_r\) or \(B\) instead of \(B_r(x)\) when \(x\) or \(r\) are clear from the context. Similarly,
sometimes I will write \(Q_t\) or \(Q\) instead of \(Q(x, t, r)\). For a Lebesgue measurable set \(S\)
by $|S|$ I will mean Lebesgue measure of $S$. Finally $V(\Omega_T; \mathbb{R}^n)$ will denote the closure of $C^1(\Omega_T; \mathbb{R}^n)$ functions under the norm
\[
\|v\|_{V(\Omega_T)} = \sup_{t \in I(\Omega_T)} \int_\Omega |v(x,t)|^2 \, dx + \iint_{\Omega_T} |\nabla v(x,t)|^2 \, dx \, dt.
\]

2. PARTIAL REGULARITY OF NONLINEAR SYSTEMS

In this section we recall partial regularity results for weak solutions of quasi-linear parabolic systems of the form
\[
(2.1) \quad u'_i - (A^\alpha_{ij} (x, u) u'_{x_j})_{x_\alpha} = 0 \quad \forall i \in \{1 \ldots N\},
\]
where coefficients $A^\alpha_{ij}$ satisfy the following condition of strong ellipticity:
\[
(2.2) \quad A^\alpha_{ij} \xi^i \xi^j \geq \lambda |\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^n, \text{ for some } \lambda > 0.
\]
By a weak solution in this case I mean a function $u \in V(\Omega_T; \mathbb{R}^N)$ that satisfies
\[
\iint_{\Omega_T} -u'_i v'_i + A^\alpha_{ij} u'_{x_j} v^i_{x_\alpha} \, dx \, dt = 0, \quad \text{for all } v \in H^1_0(\Omega_T; \mathbb{R}^N).
\]
It is well known that weak solutions of systems of this type possess partial regularity under some appropriate continuity conditions on $A^\alpha_{ij}$. The important result in this area is the following local regularity result due to Giaquinta and Struwe: [4].

Theorem 2.1 (Local regularity condition). Suppose coefficients $A^\alpha_{ij}$ satisfy condition (2.2), are continuous and bounded. Also suppose $u \in V(\Omega_T)$ is a weak solution of (2.1). Then, if for some $(x_0, t_0) \in \Omega_T$
\[
(2.3) \quad \liminf_{R \to 0} \frac{1}{R^n} \iint_{Q(x_0, t_0, R)} |\nabla u|^2 \, dx \, dt = 0,
\]
then $u$ is Hölder continuous in the neighborhood of $(x_0, t_0)$.

Condition (2.3) is the basis for the proofs of everywhere regularity that we will discuss in the rest of this paper. We will, however, need one more result due to Giaquinta and Struwe [4].

Lemma 2.2 ($L^p$ estimate). Let $u$ be a weak solution of the system (2.1). Then there exists an exponent $p > 2$ such that $|\nabla u| \in L^p_{\text{loc}}(\Omega_T)$; moreover for all $Q_R \subset Q_{4R} \subset \Omega_T$ we have
\[
(2.4) \quad \left( \iint_{Q_R} |\nabla u|^p \, dx \, dt \right)^{1/p} \leq C \left( \iint_{Q_R} |\nabla u|^2 \, dx \, dt \right)^{1/2}.
\]

3. GENERALIZED DIFFUSION EQUATIONS

In this section I discuss the type of parabolic systems I will refer to as diffusion system. Let $\Phi: \mathbb{R}^N \to \mathbb{R}$ be a strictly convex, twice continuously differentiable function with
\[
(3.1) \quad \lambda |\xi|^2 \leq \Phi_{\xi^i \xi^j} \xi^i \xi^j \leq \Lambda |\xi|^2.
\]
Then we say that $u$ is a weak solution of
\[
(3.2) \quad u_t - \Delta [\nabla \Phi(u)] = 0
\]
if $u \in V(\Omega_T; \mathbb{R}^N)$ and for all $w \in H^1_0(\Omega_T; \mathbb{R}^N)$
\[
(3.3) \quad \iint_{\Omega_T} -u'_i w'_i + (\Phi_{\xi^i}(u))_{x_\alpha} w^i_{x_\alpha} \, dx \, dt = 0.
\]
This is a standard quasi-linear elliptic system of the type in (2.1), since we can rewrite it as
\[
(3.4) \quad u_i' + (\Phi_{z_i}(u)u_{i,a})_{x_a} = 0 \quad \text{for all } i \in \{1 \ldots N\}.
\]
If in addition \(u\) is bounded I say \(u\) is bounded weak solution.

As I have mentioned before this equation is a generalization of scalar nonlinear diffusion equation. It has several nice properties. First, its flow is a contraction in \(H^{-1}(\Omega)\) and its solutions are unique. Second, weak solutions of (3.2) are in \(H^1_{\text{loc}}(0,T;L^2_{\text{loc}}(\Omega))\), that is their weak derivatives in time are in \(L^2_{\text{loc}}(\Omega_T)\). Furthermore, if the solution is bounded, the gradient in \(x\) is actually in \(L^2_{\text{loc}}(\Omega_T)\).

First I show that flow is a contraction in \(H^{-1}(\Omega)\).

**Theorem 3.1 (Uniqueness).** Let \(u_0, u_1 \in V(\Omega_T;\mathbb{R}^N)\) be two weak solutions of (3.2) with the same boundary conditions, that is \(u_0(\cdot,t) \equiv u_1(\cdot,t)\) on \(\partial\Omega\) for almost all \(t \in [0,T]\). Denote by \(i : L^2(\Omega) \to H^{-1}(\Omega)\) the natural embedding of square integrable functions in \(H^{-1}\) defined by
\[
(i(f))(\phi) := \int_\Omega f\phi\,dx.
\]
Then we have for \(T \geq t_1 \geq t_0 \geq 0\)
\[
(3.5) \quad \|i(u_0(t_1) - u_1(t_1))\|_{H^{-1}(\Omega)} \leq e^{\lambda(t_1-t_0)} \|i(u_0(t_0) - u_1(t_0))\|_{H^{-1}(\Omega)},
\]
where \(\lambda\) as in (3.1).

**Proof.** Let us denote by \(f_h\) the Steklov average of \(f\) defined as
\[
f_h(x,t) := \int_{t-h}^{t} f(x,s)\,ds.
\]
Also for simplicity we will write \(v_k\) for \(\nabla \Phi(u_k)\) with \(k = 1, 2\). It is not very hard to show that \((u_k)_h\) and \((v_k)_h\) weakly satisfy
\[
(3.6) \quad ((u_k)_h) - \Delta((v_k)_h) = 0.
\]
Let us denote the solution of
\[
\Delta w = f, \quad w \equiv 0 \text{ on } \Omega
\]
by \(\Delta^{-1} f\). Then the \(H^{-1}(\Omega)\) norm of \(i(f)\) is given by
\[
\|i(f)\|_{H^{-1}(\Omega)}^2 = \int_\Omega |\nabla(\Delta^{-1} f)|^2\,dx.
\]
For simplicity for an \(f \in L^2(\Omega)\) let us write \(\|f\|_{H^{-1}(\Omega)}\) instead of \(\|i(f)\|_{H^{-1}(\Omega)}\). Now fix \(h\).

For \(t_0,t_1 \in (h,T-h)\) we compute
\[
(3.7) \quad \left( e^{2\lambda t} \|(u_1)_h - (u_0)_h\|_{H^{-1}}^2 \right)_{t_0}^{t_1} = I_1 + I_2,
\]
where
\[
I_1 = \int_{t_0}^{t_1} 2\lambda e^{2\lambda t} \|(u_1)_h - (u_0)_h\|_{H^{-1}}^2 \,dt,
\]
and
\[
I_2 = \int_{t_0}^{t_1} \int_\Omega 2e^{2\lambda t} \nabla \Delta^{-1}((u_1)_h - (u_0)_h) \cdot \nabla \Delta^{-1}((u_1)_h - (u_0)_h)\,dx\,dt.
\]
Using the equation and the fact that \(u_0\) and \(u_1\) have the same trace, for \(I_2\) we obtain
\[
I_2 = -\int_{t_0}^{t_1} \int_\Omega 2e^{2\lambda t} ((u_1)_h - (u_0)_h) \cdot ((v_1)_h - (v_0)_h)\,dx\,dt.
\]
Taking the limit of both sides of the equation (3.7) as $h \to 0$ we get

$$
(3.8) \quad \left( e^{2\lambda t} \left\| (u_1 - u_0) \right\|^2_{H^{-1}} \right) \Bigg|_{t_0}^{t_1} = I_3 + I_4,
$$

where

$$
I_3 = \int_{t_0}^{t_1} 2\lambda e^{2\lambda t} \left\| (u_1 - u_0) \right\|^2_{H^{-1}} \, dt,
$$

and

$$
I_4 = - \int_{t_0}^{t_1} \int_\Omega 2e^{2\lambda t} (u_1 - u_0) \cdot (v_1 - v_0) \, dx \, dt \\
\leq - \int_{t_0}^{t_1} \int_\Omega 2\lambda e^{2\lambda t} |u_1 - u_0|^2 \, dx \, dt \\
\leq - \int_{t_0}^{t_1} 2\lambda e^{2\lambda t} \left\| (u_1 - u_0) \right\|^2_{H^{-1}} \, dt.
$$

Thus we see that $I_3 + I_4 \leq 0$ and we establish the result for $T > t_1 \geq t_0 > 0$. We establish the Theorem by taking the limit as $t_0 \to 0$ and $t_1 \to T$. \hfill \Box \Box

Let us now derive the $H^2$ estimates for the solutions of (3.2). In general, quasi-linear parabolic systems do not have $H^2$ estimates and the fact that solutions of generalized diffusion equations do have them is the consequence of the special structure that equation (3.2) possesses.

**Theorem 3.2** ($H^2$ estimates). Let $u \in V(\Omega_T; R^N)$ be a weak solution of (3.2). Then $u_t \in L^2_{loc}(\Omega_T)$ and for $Q(x,t,r) \subseteq Q(x,t,R) \subset \Omega_T$ we have the following estimates

$$
(3.9) \quad \iint_{Q(x,t,r)} |u_t|^2 \, dx \, dt \leq \frac{C}{(R-r)^2} \iint_{Q(x,t,R)} |\nabla u|^2 \, dx \, dt,
$$

$$
(3.10) \quad \iint_{Q(x,t,r)} |\nabla^2 (\nabla \Phi(u))|^2 \, dx \, dt \leq \frac{C}{(R-r)^2} \iint_{Q(x,t,R)} |\nabla u|^2 \, dx \, dt.
$$

**Proof.** As before we will write $v$ for $\nabla \Phi(u)$ and $f_b$ for Steklov average of $f$. Denote by $\xi \in C_0^\infty(\Omega)$ a smooth bump function supported in $B_R(x) \subset \Omega$, which is identically one on $B_r(x) \subset \Omega$ with $|\nabla \xi|_\infty \leq C/(R-r)$. Also denote by $\eta \in C_0^\infty([t-R^2,t])$ a function that is identically one on $[t-r^2,t]$ and supported in $[t-R^2,t]$ with $|\eta| \leq C/(R^2-r^2)$. Then multiplying equation

$$
(u_h)_t - \Delta (v_h) = 0
$$

by $(v_h)_t \xi^2 \eta$ we obtain

$$
\int_{t-R^2}^{t} \int_\Omega (u_h)_t (v_h)_t \xi^2 \eta + \nabla (v_h) \nabla (v_h)_t \xi^2 \eta + \nabla (v_h)_t (v_h)_t 2\xi \nabla \xi \eta \, dx \, dt = 0.
$$

Using strict convexity on the first term, integrating the second term in time by parts and using Hölder inequality twice we obtain

$$
\int_{t-R^2}^{t} \int_\Omega \frac{\lambda}{2} |(u_h)|^2 \xi^2 \eta \, dx \, dt + \int_\Omega |\nabla (v_h)|^2 \xi^2 \eta \, dx \\
\leq C(|\eta|_\infty + \|\nabla \xi\|^2_2) \int_{t-R^2}^{t} \int_\Omega |\nabla (v_h)|^2 \xi^2 \, dx
$$
Thus taking a limit as \( h \to 0 \) we deduce that \( u_t \in L^2_{\text{loc}}(\Omega) \) and derive estimate (3.9) as claimed. To prove (3.10), we use \( H^2 \) estimates for the Laplacian to get the following for a fixed \( t \):

\[
\int_{B_r(x) \times \{t\}} |\nabla^2 v|^2 \, dx \leq \frac{C}{(R - r)^2} \int_{B_r(x) \times \{t\}} |\nabla v|^2 \, dx + \int_{B_r(x) \times \{t\}} |u|^2 \, dx.
\]

Integrating in time and using estimate (3.9) we get

\[
\iint_{Q(x,t,t)} |\nabla^2 v|^2 \, dxdt \leq \frac{C}{(R - r)^2} \iint_{Q(x,t,t)} |\nabla v|^2 \, dxdt.
\]

In addition to \( H^2 \) estimates for weak solutions, bounded weak solutions of equation (3.2) are actually in \( L^4_{\text{loc}} \). This is rather unusual since most quasi-linear equations do not have \( L^4 \) estimates.

**Theorem 3.3 (\( L^4 \) estimate for bounded solutions).** Let \( u \) be a weak bounded solution of the equation (3.2). Then \( \nabla u \) is locally in \( L^4 \) and for \( Q(x,t,r) \subseteq Q(x,t,t) \subseteq \Omega_T \) we have the following estimate:

\[
(3.11) \qquad \iint_{Q(x,t,t)} |\nabla^2 u|^4 \, dxdt \leq \frac{C \|u\|_{L^\infty}^4}{(R - r)^2} \iint_{Q(x,t,t)} |\nabla u|^2 \, dxdt.
\]

**Proof.** Let us again denote \( \nabla \Phi(u) \) by \( v \) and let \( \tau : \mathbb{R} \to \mathbb{R} \) be a smooth increasing function that is linear on \((-\infty, 1]\) and constant on \([2, \infty)\). For some large enough constant \( C_1 \), \( C_1 \tau(z) \geq z(\tau'(z))^2 \). Define \( \tau_\varepsilon(x) := \tau(\varepsilon x) / \varepsilon \). Notice that \( \|\tau'_\varepsilon\|_{L^\infty} \leq C_0 \) and \( C_1 \tau_\varepsilon(z) \geq z(\tau'_\varepsilon(z))^2 \) with constants independent of \( \varepsilon \). Letting \( \xi \) be a smooth bump function as in the proof of Theorem above, multiply the equation (3.2) by \( v \tau_\varepsilon(|\nabla v|^2) \xi_2 \) and integrate by parts to obtain

\[
\iint_{Q(x,t,t)} u_i v^i \tau_\varepsilon(|\nabla v|^2) \xi_2 + |\nabla v|^2 \tau_\varepsilon(|\nabla v|^2) \xi_2 \]

\[
+ 2v^i v^j \tau_\varepsilon^i (|\nabla v|^2) v^j \xi_2 \]

\[
+ 2v^i v^j \tau_\varepsilon^i (|\nabla v|^2) v^j \xi_2 \]

\[
= 0.
\]

Hence we compute

\[
\iint_{Q(x,t,t)} |\nabla v|^2 \tau_\varepsilon(|\nabla v|^2) \xi_2 \, dxdt \leq \iint_{Q(x,t,t)} C_2 \|v\|_{L^\infty}^2 \|u_t\|^2 \xi_2 + \frac{1}{2} \tau_\varepsilon^2(|\nabla v|^2) \xi_2^2
\]

\[
+C_3 \|\nabla \xi\|_{L^\infty} \|v\|_{L^\infty}^2 |\nabla v|^2 + C_4 \|v\|_{L^\infty}^2 |\nabla^2 v|^2 \xi_2^2 + \frac{1}{4C_1} |\nabla v|^4 \tau_\varepsilon^4(|\nabla v|^2)^2 \xi_2^2 \, dxdt.
\]

Simplifying and using estimates (3.9), (3.10) and \( C_1 \tau_\varepsilon(z) \geq z(\tau'_\varepsilon(z))^2 \) we deduce

\[
\iint_{Q(x,t,t)} |\nabla v|^2 \tau_\varepsilon(|\nabla v|^2) \, dxdt \leq \frac{C \|u\|_{L^\infty}^2}{(R - r)^2} \iint_{Q(x,t,t)} |\nabla u|^2 \, dxdt.
\]

Taking a limit as \( \varepsilon \to 0 \) we deduce by monotone convergence theorem that \( \nabla u \) is locally in \( L^4 \) and the estimate as claimed in the statement of the Theorem.

**Remark 3.4.** The fact that the gradient is actually locally in \( L^4 \) implies that the singular set of a bounded solution has parabolic Hausdorff dimension smaller than \( n - 2 \). As you may recall from Theorem 2.1 the singular set is contained in the set

\[
\left\{ (x,t) \in \Omega_T \mid \liminf_{R \to 0} \frac{1}{R^6} \iint_{Q(x,t,t)} |\nabla u|^2 \, dxdt > 0 \right\}.
\]
Now using the H"older inequality and the fact that $u$ locally in $L^4$ we compute
\[
\frac{1}{R^n} \int_{Q(x,t,R)} |\nabla u|^2 \, dx \, dt \leq \frac{1}{R^n} \left( \int_{Q(x,t,R)} |\nabla u|^4 \, dx \, dt \right)^{1/2} |Q(x,t,R)|^{1/2}
\leq CR^{-n} \left( \int_{Q(x,t,R)} |\nabla u|^4 \, dx \, dt \right)^{1/2}
\leq C \left( R^{2-n} \int_{Q(x,t,R)} |\nabla u|^4 \, dx \, dt \right)^{1/2}.
\]

Hence the singular set must be contained in the set
\[
\left\{ (x,t) \in \Omega_T \mid \liminf_{R \to 0} \frac{1}{R^n-2} \int_{Q(x,t,R)} |\nabla u|^4 \, dx \, dt > 0 \right\},
\]
which has $n-2$ parabolic Hausdorff measure zero.

4. The Key Lemma

In this section I discuss the parabolic version of the lemma that seems to be key in the proof of everywhere regularity of some elliptic systems. Not surprisingly, it will turn out that the parabolic lemma is crucial to proving everywhere regularity of solutions to some types of parabolic systems. The elliptic lemma, to which I refer, is well known and the proof of it can be found in [3] in Chapter 7 as part of Theorem 1.1.

Before we proceed with the discussion of this elliptic lemma let us recall that coefficients $a_{\alpha \beta}$ are called strictly elliptic if there exists $\lambda > 0$ such that
\[
a_{\alpha \beta} \xi^\alpha \xi^\beta \geq \lambda |\xi|^2 \quad \text{for all } \xi \in \mathbb{R}^n.
\]

**Lemma 4.1.** Suppose coefficients $a_{\alpha \beta}(x)$ are strictly elliptic, bounded and measurable. Let $u \in V(\Omega)$, $f \in L^1(\Omega)$ be nonnegative functions satisfying
\[
-(a_{\alpha \beta} u_{x_\beta})_{x_\alpha} + f \leq 0
\]
on $\Omega$. For any $x_0 \in \Omega$ for which $B_{R_0}(x_0) \subset \Omega$ for some $R_0$, we have the following:
\[
\liminf_{R \to 0} \frac{1}{R^n-2} \int_{B_{R_0}(x_0)} f \, dx = 0.
\]

The proof of this lemma is rather simple and follows easily from the elliptic Harnack inequality. Because of the peculiar geometry of the parabolic Harnack inequality, the elliptic proof does not translate directly into the parabolic case. Instead, by adopting proof of elliptic lemma to parabolic equations, one is able to control $f$ on the cylinders whose top centers are slightly shifted back in time. In fact it is not true that $f$ can be controlled on the cylinders whose top centers are not fixed, without additional assumptions on $f$. It turns out, however, that the assumption that one needs to impose to prove the parabolic version of the lemma is satisfied in applications to everywhere regularity of parabolic systems. What we need to assume is that for some $\alpha > 1$ the $L^\alpha$ norm of $f$ on a cylinder is controlled by the $L^1$ norm of $f$, perhaps on a larger cylinder.

**Lemma 4.2 (Key Lemma).** Suppose coefficients $a_{\alpha \beta}(x,t)$ are strictly elliptic, bounded and measurable. Let $u \in V(\Omega_T)$, $f \in L^1(\Omega_T)$ be nonnegative functions weakly satisfying
\[
u_t - (a_{\alpha \beta} u_{x_\beta})_{x_\alpha} + f \leq 0
\]
on $\Omega_T$. Further suppose that for some $\alpha > 1$ our $f$ satisfies the following:

\begin{equation}
\left( \iint_{Q_R} f^\alpha \, dx \, dt \right)^{1/\alpha} \leq C \iint_{Q_{4R}} f \, dx \, dt,
\end{equation}

for all $Q_R \subset Q_{4R} \subset \Omega_T$. Then for any $(x_0, t_0) \in \Omega_T$ for which

\[ B_{R_0}(x_0) \times (t_0 - R_0^2, t_0 + R_0^2) \subset \Omega_T, \text{ for some } R_0, \]

we have the following:

\begin{equation}
\liminf_{R \to 0} \frac{1}{R^n} \iint_{Q(x_0, t_0, R)} f \, dx \, dt = 0.
\end{equation}

**Proof.** Fix $0 < \sigma \leq 1/4$. Set

\[ R_i := \sigma^i R_0, \quad Q_i := Q(x_0, t_0, R_i), \quad M_i := \sup_{Q_i} u \]

and

\begin{align*}
Q'_i &:= Q(x_0, t_0 - 4\sigma^2 R_i^2, 1 - 8\sigma^2)^{1/2} R_i), \\
Q''_i &:= Q(x_0, t_0 - 2\sigma^2 R_i^2, 1 - 4\sigma^2)^{1/2} R_i). \\
\end{align*}

We divide the proof in three steps. In the first step we show that for any $\sigma \in (0, 1/4]$ we have

\[ \lim_{i \to \infty} \frac{1}{R^i} \iint_{Q_i'} f \, dx \, dt = 0. \]

Once we have done that, we show that we can control $f$ on $Q \setminus Q_i'$ with the help of the assumption on $f$. Finally we will put it all together to conclude the lemma.

**Step 1.** Fix $i$, and set $z := M_i - u$. We see that $z \geq 0$ on $Q_i$ and $z$ satisfies

\begin{equation}
z_t - (a_{\alpha \beta} \partial_{x\beta}) z_{\alpha} \geq f.
\end{equation}

In particular, due to parabolic Harnack inequality (see Theorem 6.24 in [5])

\begin{equation}
\iint_{Q''_i} z \, dx \, dt \leq C \inf_{Q_{i+1}} z.
\end{equation}

Let $w$ solve backward time parabolic equation

\begin{equation}
w_t - (a_{\alpha \beta} w_{\alpha \beta})_{x\beta} = \frac{1}{R_i^2} z_{x\beta}^{Q''_i}
\end{equation}

on $Q_i$, with $w \equiv 0$ on the backward time parabolic boundary, that is

\[ w \equiv 0 \text{ on } (\partial B_{R_i}(x_0) \times [t_0 - R_i^2, t_0]) \cup (B_{R_i}(x_0) \times \{t_0\}). \]

At this point if $zw$ were actually differentiable in time, we would multiply equation (4.8) by $zw$ and integrate by parts to obtain

\[ \iint_{Q''_i} z \left( \frac{w^2}{2} \right)_t + a_{\alpha \beta} \partial_{x\beta} \left( \frac{w^2}{2} \right)_{x\alpha} + a_{\alpha \beta} w_{x\alpha} w_{x\beta} z \, dx \, dt = \frac{1}{R_i^2} \iint_{Q''_i} zw \, dx \, dt, \]

and since $z$ satisfies equation (4.6) we would conclude that

\begin{equation}
\frac{1}{R_i^2} \iint_{Q''_i} f \left( \frac{w^2}{2} \right) \, dx \, dt \leq \frac{1}{R_i^2} \iint_{Q''_i} zw \, dx \, dt.
\end{equation}

In general we cannot expect $zw$ to be differentiable in time. To obtain equation (4.9) rigorously one would need to use Steklov average

\[ (zw)^h(x, t) := \frac{1}{h} \int_{t-h}^t z(x, \tau) w(x, \tau) \, d\tau \]
as a test function in (4.8). However, we will not do this here, instead I refer the reader to Lemma 6.1 in [5], where similar computation has been carried out.

Now, since \( w \) solves (4.8), by strong maximal principle \( w \geq \theta > 0 \) on \( Q \) and also \( w \leq C \) on \( Q_i \), with bounds independent of \( i \) (one can see this by scaling for example). Therefore, combining this observation with inequality (4.7), we obtain

\[
\frac{1}{R_i^n} \int_{Q_i'} f \, dx \, dt \leq C \int_{Q_i'} z \, dx \, dt \leq C \inf_Q z = C(M_i - M_{i+1}).
\]

However, since

\[
\sum_{i=0}^{\infty} M_i - M_{i+1} \leq \sup_Q u,
\]

we conclude that

\[
\frac{1}{R_i^n} \int_{Q_i'} f \, dx \, dt \to 0 \quad \text{as} \quad i \to \infty.
\]

**Step 2.** Let \( A \) be some measurable set. We will show that for all \( Q \subset Q_R \), for all \( \epsilon > 0 \), there exists \( \delta \) such that if \( |A \cap Q_R| \leq \delta |Q_R| \), then

\[
\frac{1}{(4R)^a} \int_{Q_{4R}} f \, dx \, dt \leq \epsilon.
\]

First, we can easily deduce by the argument similar to the one in part 1, that

\[
(4.10) \quad \frac{1}{(4R)^a} \int_{Q_{4R}} f \, dx \, dt \leq C,
\]

where constant is independent of \( R \).

We now use (4.4) to conclude that

\[
\int_{A \cap Q_R} f \, dx \, dt \leq \left( \frac{1}{|Q_R|^a} \int_{A \cap Q_R} f^a \, dx \, dt \right)^{1/a} |Q_R|^{1/\alpha} |A \cap Q_R|^{1-1/\alpha} \leq C |Q_R|^{1/\alpha} |A \cap Q_R|^{1-1/\alpha} \int_{Q_{4R}} f \, dx \, dt \leq C \int_{Q_{4R}} f \, dx \, dt \leq C_1 R^a \delta^{1-1/\alpha}.
\]

Above, the last inequality follows by (4.10).

**Step 3.**

Finally we put everything together. Fix \( \epsilon > 0 \). First notice that by choosing \( \sigma \) small enough we can make

\[
|Q \setminus Q'| \leq \delta |Q|,
\]

where \( C_1 \delta^{1-1/\alpha} < \epsilon/2 \). Then by first step we can find \( i > 2 \) such that

\[
\frac{1}{R_i^n} \int_{Q_i'} f \, dx \, dt \leq \epsilon/2.
\]

Finally, the above together with conclusion of second step gives us

\[
\frac{1}{R_i^n} \int_{Q_i'} f \, dx \, dt = \frac{1}{R_i^n} \int_{Q_i'} f \, dx \, dt + \frac{1}{R_i^n} \int_{Q_i \setminus Q_i'} f \, dx \, dt < \epsilon.
\]

Now we are in position to apply our key Lemma to deduce crucial importance of entropy in questions of everywhere regularity for parabolic systems.
Theorem 4.3 (Entropy condition). Let $u$ be weak solution of (2.1). Suppose there exists $\phi \in V(\Omega_T)$ that together with $u$ weakly satisfy the following inequality:

$$\phi - (a_{\alpha\beta} \phi_{\beta})_{\alpha} + \lambda |\nabla u|^2 \leq 0,$$

where $a_{\alpha\beta}$ are bounded and strictly elliptic. Then $u$ is everywhere Hölder continuous on the interior of $\Omega_T$.

Proof. Since $u$ satisfies condition (2.4), we see immediately that conditions of the key Lemma 4.2 are satisfied. Therefore, we conclude that

$$\liminf_{R \to 0} \frac{1}{R^2} \int_{Q(x_0, R)} |\nabla u|^2 \, dx \, dt = 0.$$

However, this is precisely the condition (2.3) of Theorem 2.1 Hence we conclude that $u$ is everywhere Hölder continuous on the interior of $\Omega_T$. □ □

5. EVERYWHERE REGULARITY OF CERTAIN DIFFUSION SYSTEMS

In this section we come back to the discussion of weak solutions of the diffusion system (3.2), imposing additional requirement that $\Phi(z)$ is a function of only the norm of $z$. As we will see this allows us to conclude much more about solutions of this equation. In particular solutions are bounded if they are bounded initially and at the boundary. More importantly, solutions are actually everywhere Hölder continuous and thus smooth if $\Phi$ is.

First I will show that in the case when $\Phi$ is a functions of only the norm, weak solutions of equation (3.2) that are bounded initially and bounded at the boundary will remain bounded for all time.

Theorem 5.1 (Boundedness). Let $u$ be a weak solution of the generalized diffusion equation (3.2). Also suppose that $\|u(t, \cdot)\|_{L^\infty(\Omega)} < \infty$ and $\|u(\cdot, t)\|_{L^\infty(\partial \Omega)} < \infty$ for all $t \in [0, T]$. Then $\|u\|_{L^\infty(\Omega)} < \infty$ and we have

$$\|u(t, \cdot)\|_{L^\infty(\Omega)} \leq \max \left\{ \|u(0, \cdot)\|_{L^\infty(\Omega)}, \sup_{s \in [0, T]} \|u(\cdot, s)\|_{L^\infty(\partial \Omega)} \right\}. \quad (5.1)$$

Proof. Set $B$ to

$$B = \max \left\{ \|u(0, \cdot)\|_{L^\infty(\Omega)}, \sup_{s \in [0, T]} \|u(\cdot, s)\|_{L^\infty(\partial \Omega)} \right\}.$$

Fix $\varepsilon > 0$ that is less than one. Let $\gamma : \mathbb{R}^+ \to \mathbb{R}$ be a smooth convex function which is identically zero on $[0, B + \varepsilon]$, positive and increasing otherwise, and linear on $[B + 1, \infty)$. Also set $\Gamma(z)$ to $\gamma(|z|)$. Then we compute

$$\frac{d}{dt} \int_{\Omega} \Gamma(u(x, t)) \, dx = \int_{\Omega} \Gamma_u u_t \, dx$$

$$= \int_{\Omega} (\Gamma_{\xi_i} \Phi_{\xi_i \xi_j} u_{\alpha j})_{\alpha} - \Gamma_{\xi_i \xi_j} \Phi_{\xi_i \xi_j} u_{\alpha j} u_{\alpha} \, dx$$

$$\leq \int_{\partial \Omega} \Gamma_{\xi_i} \Phi_{\xi_i \xi_j} u_{\alpha j} u_{\alpha} \, dS$$

$$= 0.$$

The inequality is true because Hessians of two functions of only the norm commute and both $\Gamma$ and $\Phi$ are convex. The last equality is true because $\gamma$ is identically zero on $[0, B + \varepsilon]$ and $|u|$ is less than or equal to $B$ on the boundary. Since $\Gamma(u)$ is positive and initially zero...
we conclude that $\Gamma$ is zero up to time $t$ and thus $\|u(\cdot, t)\|_\infty \leq B + \epsilon$. Since the inequality is true for all $\epsilon > 0$ the Theorem follows. □ □

The next Lemma will show that if we suppose that $\Phi(z)$ is a function only of the norm of $z$, then there exists an entropy that satisfies conditions of Theorem 4.3.

**Lemma 5.2.** Let $u$ be a weak bounded solution of (3.2) and suppose $\Phi$ is of the form

$$\Phi(u) = \phi(|u|).$$

Then there is a continuously differentiable, strictly increasing function $\gamma : \mathbb{R} \to \mathbb{R}$ such that $\phi$ weakly satisfies the following inequality:

$$\phi_t - \Delta(\gamma(\phi)) + \lambda^2 |\nabla u|^2 \leq 0. \quad (5.2)$$

**Proof.** First of all, without loss of generality we can suppose that $\Phi(0) = 0$. Notice that $\phi$ satisfies the following equation weakly:

$$\phi_t - (\Phi_x \Phi_{zz} u_x')_{xx} + |\nabla_x (\nabla \Phi(u))|^2 = 0.$$  

Looking at the quantity inside the divergence term we see that it is equal to

$$\Phi_x \Phi_{zz} u_x' = \left(\frac{1}{2} |\nabla \Phi(u)|^2\right)_{xx}.$$  

Since $\Phi(z) = \phi(|z|)$, we observe that

$$\frac{1}{2} |\nabla \Phi(u)|^2 = \frac{1}{2} \phi'(|u|)^2.$$  

Let $\psi$ be the continuous inverse of $\phi$. Set

$$\gamma(z) = \int_0^z \phi''(\psi(t)) \, dt.$$  

Then multiplying $\gamma'(\phi(z))$ by $\phi'(z)$ and integrating, we see that $\gamma$ and $\phi$ satisfy

$$\gamma(\phi(z)) = \frac{1}{2} \phi'(z)^2.$$  

This $\gamma$ is continuously differentiable and strictly increasing, since $\phi$ is strictly convex. Therefore we conclude that $\phi$ satisfies

$$\phi_t - \Delta(\gamma(\phi)) + |\nabla_x (\nabla \Phi(u))|^2 = 0,$$

and due to strict convexity the last term on the left hand side is greater or equal to $\lambda^2 |\nabla u|^2$. □ □

Now we are in position to use the above Lemma 5.2 together with Theorem 4.3 to deduce

**Theorem 5.3.** Weak solutions of equation (3.2) are Hölder continuous in $\Omega_T$.

**Proof.** Lemma 5.2 tells us, that for $u$ a weak bounded solution of (3.2), there exists $\phi$ satisfying

$$\phi_t - (a \phi_{xx})_{xx} + \lambda^2 |\nabla u|^2 \leq 0,$$

where $a(x,t) := \gamma'(\phi(x,t))$. However, this is precisely the condition of Theorem 4.3. Therefore, we conclude the proof. □ □
6. STRONGLY COUPLED PARABOLIC SYSTEMS

One of the earliest nontrivial examples of quasi-linear parabolic systems whose solutions have interior everywhere regularity was due to Wiegner [7]. These are the so-called strongly coupled parabolic systems of the following form:

\[ u_t^i - (a_{\alpha\beta} u^i_{x_{\beta}} + c_{\alpha\beta} H_{x_{\beta}}) x_{\alpha} = 0, \]

where

1. \( H = H(u) \) is a function of \( u \);
2. \( A_{\alpha\beta}^{ij} := a_{\alpha\beta} \delta^{ij} + c_{\alpha\beta} H_{x_{\beta}} \) and \( a_{\alpha\beta} \) are strictly elliptic in the sense that
\[ \lambda |\xi|^2 \leq A_{\alpha\beta}^{ij} \xi_i \xi_j, \quad \text{for all } \xi \in \mathbb{R}^{nN}, \xi \in \mathbb{R}^n; \]
3. \( H(z) \) is twice continuously differentiable and \( \lambda |\zeta|^2 \leq H_{zz}(\zeta) \zeta_i \zeta_i \);
4. \( a_{\alpha\beta} \) and \( c_{\alpha\beta} \) are bounded.

After Wiegner, Dung [2] also worked on these types of system. However, neither Wiegner’s nor Dung’s proofs of everywhere regularity for solutions of strongly coupled parabolic systems reduce to something analogous to the key Lemma 4.2. It is instructive to prove everywhere regularity of weak solutions to (6.1) using the key Lemma to illustrate an underlying similarity between strongly coupled parabolic systems and generalized diffusion equations (3.2). It appears that for both systems discussed in this paper the existence of an entropy is crucial for everywhere regularity of their solutions.

**Remark 6.1.** When \( \Phi \) only depends on the norm of the gradient, diffusion system (3.2) actually has the form of a strongly coupled system, except with possibly non-convex \( H \).

Indeed, if \( \Phi(z) = \phi(|z|) \), then

\[ \Phi_z(z) = \frac{\phi'(|z|)}{|z|} z_i \left( \phi''(|z|) - \frac{\phi'(|z|)}{|z|} \right) z_j, \]

therefore, with

\[ a_{\alpha\beta} = \frac{\phi'(|u|)}{|u|} \delta_{\alpha\beta}, \quad c_{\alpha\beta} = \frac{u^i}{|u|} \delta_{\alpha\beta}, \]

and

\[ H(z) = \phi'(|z|) - \int_0^{|z|} \frac{\phi'(s)}{s} \, ds, \]

system (3.2) has the form (6.1).

We can prove an interior everywhere regularity result for strongly coupled parabolic systems rather easily using Theorem 4.3. As in the previous section I will show existence of an entropy.

**Lemma 6.2.** Let \( u \in V(\Omega_T; \mathbb{R}^N) \) be a weak bounded solution of (6.1) then for some large enough \( s \) there is a positive constant \( c \) such that \( v := e^{sH} \) is a subsolution of the following equation:

\[ (e^{sH})_t = s e^{sH} H_{x_{\alpha}}(a_{\alpha\beta} u^i_{x_{\beta}} + c_{\alpha\beta} H_{x_{\beta}}) x_{\alpha} + c |\nabla u|^2 \leq 0. \]

**Proof.** We compute

\[ (e^{sH})_t = se^{sH} H_{x_{\alpha}}(a_{\alpha\beta} u^i_{x_{\beta}} + c_{\alpha\beta} H_{x_{\beta}}) x_{\alpha} \]
\[ = (A_{\alpha\beta} (e^{sH}) x_{\alpha}) + (a_{\alpha\beta} u^i_{x_{\beta}} + c_{\alpha\beta} H_{x_{\beta}}). \]
The last term on the right becomes
\[
(\varepsilon s^H H_{\zeta})_\alpha (a_{\alpha\beta}u^\beta_i + c_{\alpha\beta}H_{\gamma}) = s^2 \varepsilon s^H A_{\alpha\beta} H_{\alpha} H_{\beta} \\
+ s^2 \varepsilon s^H H_{\zeta j} a_{\alpha\beta} u^\beta_i H_{\gamma} + \varepsilon s^H H_{\zeta j} c_{\alpha\beta} H_{\gamma} u^\beta_i \\
\geq \varepsilon s^H \left( \lambda s |\nabla H|^2 + \lambda |\nabla u|^2 - C(\varepsilon) |\nabla H|^2 - \varepsilon |\nabla u|^2 \right) \geq \frac{\lambda}{2} \varepsilon s^H |\nabla u|^2.
\]

The last inequality follows by first making \( \varepsilon \) small and then \( s \) large. Since \( u \) is bounded, we have \( H \) is bounded from below. Therefore, for some \( \varepsilon, \nu \) satisfies equation (6.2) as claimed.

At this point we immediately conclude that conditions of Theorem 4.3 are satisfied. Therefore we have established

**Theorem 6.3.** Bounded weak solutions of (6.1) are Hölder continuous in \( \Omega_T \).

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