A NEW SET OF TOOLS FOR GOODNESS-OF-FIT VALIDATION

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Abstract. We introduce two new tools to assess the validity of statistical distributions. These are based on components derived from a new statistical quantity, the comparison curve, which can provide a detailed appraisal of validity. The first tool is a graphical representation of these components on a bar plot (B-plot). The knowledge such gained could suggest an existing goodness-of-fit test to supplement this assessment with a control of the type I error. Otherwise, an adaptive test may be preferable and the second tool is the combination of these components to produce a powerful \( \chi^2 \)-type goodness-of-fit test. Because the number of these components can be large, we introduce a new selection rule to decide on their number. In a simulation, our goodness-of-fit tests are powerwise competitive with the best solutions recommended. Practical examples show how to use these tools to derive principled information about where the model departs from the data.

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1. Introduction

Let $X$ be a random variable with unknown cumulative distribution function (CDF) $F(\cdot)$. Statistical models are entertained approximations to $F(\cdot)$ which serve to produce inferential statements about the behaviour of $X$. Constructing a good approximation is an iterative process where at any given step, a contemplated model based on previously acquired knowledge is assessed by confrontation with data. When the current proposal is invalidated, its defects must be learned to explore a better model at the next iteration. When a model is tentatively validated, useful inference can be drawn by exploiting its characteristics, allowing the accumulation of subject matter knowledge.

In the present work, the entertained statistical model for $X$ is the CDF $F_0(\cdot; \beta)$ where the parameter $\beta$ may be unknown. The data is a sample of independent copies $X_1, \ldots, X_n$ of $X$.

Two main routes exist for statistical model validation. A first one focusses on graphical representations, such as PP (percentile-percentile) or QQ (quantile-quantile) plots (Thas, 2010, Section 3.2). When the model is valid, these plots should closely follow the 45-degree line through the origin. Deviations can provide insights about where the data do not conform to the entertained model. These visual appreciations can be supplemented with confidence regions about such representations (Aldor-Noiman et al., 2013; Gan, Koehler & Thompson, 1991) or test statistics measuring departure from this straight line (Gan & Koehler, 1990) to control the type I error (i.e. falsely considering a model is invalid). This route can clearly be a cog in the modelling process.

A second route focusses mainly on error risks by testing, via formal goodness-of-fit (GoF) procedures, the null hypothesis that the model holds. A large number of test statistics have been derived for such problems (for testing the GoF to the Gaussian distribution, Arnastauskaitė, Ruzgas & Brazėnas (2021) list 40 such tests) which allow controlling the type I error risk. Regarding the type II error (i.e. not rejecting an invalid model and thus stopping prematurely the modelling process), an enormous amount of work has been accomplished, both theoretically and empirically, to understand the respective power of the various proposals and to derive a generally good solution for specific problems. In particular, regarding the Gaussian distribution again, a long series of simulation experiments have been conducted (see Arnastauskaitė, Ruzgas & Brazėnas, 2021 and references therein) to characterize the effectiveness of popular proposals. A first drawback is that it is not easy to decide, in view of the data at hand, upon an appropriate GoF test among this plethora of solutions. Another drawback is that when the chosen test rejects, the user is often left with little information about the defects of the model. This makes it difficult to pursue the modelling.

A few exceptions are the well-known Pearson $\chi^2$-test and the smooth test introduced by Neyman (1937), to which sets of components can be associated. Each component reacts to specific departures and if these can be discerned, their inspection can help a user gain some insights about where the model is at fault. Below, we discuss some problems arising with these tests when $\beta$ is known. Both approaches have been extended to unknown $\beta$ but then more serious difficulties occur.

There are two main problems with such tests. The first one arises from the standard order of the argument leading to these components, which is first to get from external considerations a GoF test, then try to extract meaningful components. For
Pearson’s $\chi^2$-test. Anderson (1994) has made such an attempt but Boero, Smith & Wallis (2004a) have shown that his approach was not completely successful; for similar efforts, see Voinov (2010) and references therein. When $\beta$ is known, the components of the classical Pearson’s $\chi^2$-square test are not easy to interpret as they heavily depend on the selected partition. Regarding Neyman’s smooth tests, meaning depends on the orthogonal system used in the test. With classical orthogonal polynomials, the first few components will typically be associated with central moments (Thas, 2010, p. 84), but beyond the third (skewness) they become difficult to relate to telling departures.

The second problem concerns the number of components to be used in the test: too few or too many negatively affect the power of the test. For some historical notes and recommendations about choosing the partitions, see Boero, Smith & Wallis (2004b) and Rolke & Gongora (2021). Bogdan (1995) and Inglot & Janic-Wróblewska (2003) contain some useful proposals regarding data driven selections of the partition in classical $\chi^2$-test. Some data driven GoF tests based on partitions have also been derived in Section 5.5 of Thas (2001). In turn, Ledwina (1994) has proposed an effective way of selecting the number of components in the classical Neyman’s smooth test.

In the present work, we try to solve these problems by introducing easily interpretable components, different from those in the original $\chi^2$-test and several variants of Neyman’s test, which can be graphically depicted on what we call a bar plot (B-plot) to give a detailed appraisal of the validity of a model. This may help in selecting an appropriate GoF test to assess the global fit between the data and the model. When, likely, none naturally emerges, the components can be combined to produce a powerful new data driven $\chi^2$-type GoF test, (see Section 2.4 for an explanation of the label “-type”), supplementing the visual assessment with a control of the type I error. When the chosen test rejects, acceptance regions for subsets of components under the null model can be plotted and analyzed to sharpen the insight gained from the B-plot about where and why departures seem to occur.

We start by introducing a function, referred to as the comparison curve (CC), which is related to existing statistical objects such as PP and QQ plots. Its evaluation yields components whose statistical properties offer richer insights, when depicted on the B-plot, than these plots. In particular, this first new tool allows gaining some ideas about where (in terms of ranges of quantiles of the model $F_0(\cdot; \beta)$) and to which extent the data contradict the model. These components are then shown to be estimated successive Fourier coefficients of the comparison density (see Section 2.3). The number of such components can in principle be as large as one chooses. Hence a second important task is to derive a way of selecting, in a data driven fashion, their number. We introduce a new selection rule to decide on a proper number of components to include in our second tool, a data driven $\chi^2$-type GoF test statistic. Finally, we show how the B-plot can be supplemented with acceptance regions for subsets of components to provide richer indications regarding the compatibility of the data with the null model in some regions of interest.

We first consider the context where the null model $F_0(\cdot; \beta)$ is entirely specified, i.e. $\beta$ is known. A carefully balanced simulation experiment shows that our procedure competes with some best tests in this context. Then we move to the context where the parameter $\beta$ in $F_0(\cdot; \beta)$ must be estimated. Particular attention is given to the location-scale model, i.e. $F_0((x - \beta_1)/\beta_2)$, and to the important sub-case of a Gaussian model. Again the results of a balanced simulation experiment show that our procedure competes with some best tests for this set-up. In both contexts, we apply our tools to real data to show how useful insights can be derived. The appendices contain details about more examples showing the useful information that
can derive from the tools of the paper, some practical recommendations regarding the application of our test strategies, the results of a simulation study regarding the power of the test statistic of Section 3 along with some more general discussion and the proofs of various technical results.

2. The case of a simple null hypothesis

2.1. Comparison curve (CC) and B-plot. Let \( X_1, \ldots, X_n \) be a sample of i.i.d. observations from an unknown continuous CDF \( F(\cdot) \). We start by considering the case where the parameter \( \beta \) in the continuous model \( F_0(\cdot; \beta) \) is known and write for simplicity \( F_0(\cdot) \) for this CDF. The simple null hypothesis of interest is \( H_0 : F(\cdot) = F_0(\cdot) \).

Consider the random variable \( Z = F_0(X) \). By the probability integral transformation, when \( X \sim F(\cdot) \), \( Z \) has CDF \( H(p) = F(F_0^{-1}(p)) \), \( p \in (0, 1) \), which is referred to by Parzen (2004) as the comparison CDF, because when some auxiliary random variable \( X_0 \sim F_0(\cdot) \), then \( H(\cdot) \) is the CDF of \( X \) expressed on a scale in which \( X_0 \sim U(0, 1) \). \( H(\cdot) \) is also referred to in the literature as the relative distribution (Handcock & Morris, 1999, Chapter 2, p. 21) as \( Z \) measures the relative ranks of \( X \) compared to \( X_0 \sim F_0(\cdot) \). Such relative ranks are also known as the grade transformation following a statistical tradition that goes back to Galton; cf. Kendall & Buckland (1957, p. 121). The function \( H(\cdot) \) is also the population version of the PP plot of \( F(\cdot) \) against \( F_0(\cdot) \) which, in this context, is sometimes called the reference distribution.

The approach of the present work is based on a standardized version of the comparison CDF, which we call the comparison curve (CC) and define as

\[
CC(p) = \frac{p - F(F_0^{-1}(p))}{(p(1 - p))^{1/2}}, \quad p \in (0, 1).
\]

When \( H_0 \) holds, \( CC(\cdot) \equiv 0 \) and otherwise captures weighted vertical discrepancies between the population PP plot and the 45-degree line. As with PP plots, \( CC(\cdot) \) is invariant under strictly increasing and continuous transformations of the scale of measurement. But in contrast with PP plots which are always 0 as \( p \to 0 \) and 1 as \( p \to 1 \), \( CC(\cdot) \) can be unbounded at the boundaries, see the Lehmann contamination and the Anderson kurtotic alternatives in Figure 2.2. As a result, due to the meaningful weighting in \( CC(\cdot) \), CC(·) can better exhibit differences between \( F(\cdot) \) and \( F_0(\cdot) \) appearing in tails. The equality \( CC(p) = 0 \) for all \( p \in (0, 1) \) is equivalent to \( F(x) = F_0(x) \) for all \( x \), while \( CC(p) \geq 0 \) for all \( p \) is equivalent to \( F(\cdot) \) being stochastically larger than \( F_0(\cdot) \). These properties are well known with PP plots.

However, we can say more on both PP and CC plots in terms of probability mass allocation between \( F(\cdot) \) and \( F_0(\cdot) \) in relation with their stochastic ordering. Namely, if there is only one point \( p_0 \in (0, 1) \) such that \( CC(p_0) = 0 \), then \( F^{-1}(p_0) = F_0^{-1}(p_0) \) and consequently the set \( (-\infty, F_0^{-1}(p_0)] \) has the same probability under both \( F(\cdot) \) and \( F_0(\cdot) \). Obviously, the same conclusion holds for the set \( (F_0^{-1}(p_0), +\infty) \). The relation \( CC(p) > 0 \) on \((0, p_0)\) defines the region where \( F_0(\cdot) > F(\cdot) \). Hence, when restricted to this interval, observations generated from the conditional distribution of \( F(\cdot) \) are stochastically larger than under the respective conditional variant of \( F_0(\cdot) \). Otherwise stated, the probability mass associated with \( F(\cdot) \) accumulates more intensively toward \( F_0^{-1}(p_0) \) than the mass of \( F_0(\cdot) \). In terms of quantiles, we get \( F_0^{-1}(\cdot) < F^{-1}(\cdot) \) and the quantiles of \( F(\cdot) \) are more concentrated toward the \( p_0 \)-quantile of the reference CDF \( F_0(\cdot) \) than those of \( F_0(\cdot) \) itself. The reverse holds when \( CC(\cdot) < 0 \) on \((0, p_0)\). The magnitude of \( CC(\cdot) \) reflects the rate at which the mass allocation between the two CDFs changes. If there are more than one point \( p \) such that \( CC(p) = 0 \), these interpretations apply to each resulting region in

\[\text{G.R. Ducharme and T. Ledwina}\]
(0, 1). The above, along with the comments in Section 3.3, essentially strengthens the interpretation of PP plots discussed in Thas (2010), Sections 7.6 and 8.1.1.2, and lead to the view that CC plots can be seen as upgraded variants of PP plots.

Replacing in (2.1) the unknown \( F(\cdot) \) by \( \hat{F}_n(x) = n^{-1} \sum_{i=1}^{n} I(X_i \leq x) \), where \( I(\omega) \) is the indicator function of event \( \omega \), leads to the \textit{empirical CC}

\[
(2.2) \quad \hat{CC}(p) = \frac{p - \hat{F}_n(F_0^{-1}(p))}{(p(1-p))^{1/2}}, \quad p \in (0, 1).
\]

Formally, \( \hat{CC}(p) \) is a consistent estimator of \( CC(p) \) in the sense that, for any \( \epsilon \in (0, 1) \), \( \sup_{\epsilon \leq p \leq 1 - \epsilon} |\hat{CC}(p) - CC(p)| \to 0 \) in probability. More importantly, \( n^{1/2} \hat{CC}(p) \) is asymptotically \( N(0, 1) \) under \( H_0 \) for each \( p \). Thus, in contrast with empirical PP and QQ plots, \( n^{1/2} \hat{CC}(\cdot) \) captures discrepancies between the postulated model under \( H_0 \) and the data with equal precision over the whole range of \( p \).

Evaluating \( n^{1/2} \hat{CC}(\cdot) \) at points on a grid in \( (0, 1) \) and representing these as bars over the grid points yields a \textit{bar plot} (B-plot), as introduced by Ledwina and Wyłupek (2012a, b) in a related problem. Obviously, the \( n^{1/2} \hat{CC}(\cdot) \) are noisy but being correlated, their visual inspection can allow to approximately identify regions where the null model puts more probability mass, via a clustering of its quantiles, than the data seems to suggest, and reversely.

As an example of the usefulness of a \( CC(\cdot) \), consider the smiling baby data set (Bhattacharjee & Mukhopadhyay, 2013). The data (\( n = 55 \)) are the smiling times (in seconds) of an eight-week-old baby. According to various authors, the data could realistically be uniformly distributed over the interval \([0, \theta]\). Here, we take \( \theta = 23.5 \), a value close to the estimators investigated by Bhattacharjee & Mukhopadhyay (2013) and transform the data onto [0, 1]. Panel 1) of Figure 2.1 shows the empirical PP plot against the reference \( U[0, 1] \) distribution (the 45-degree line) while Panel 2) represents the B-plot of \( n^{1/2} \hat{CC}(p) \) for \( p \in \{1/32, \ldots, 31/32\} \). Inspection of these bars shows a coincidence of the null and empirical quantiles in the neighbourhood of \( p = 0.45 \) (\( \approx 10.6 \) in the original units), slightly to the left of the median under \( H_0 \). The shape of the sets of positive bars to the left and negative bars to the right of \( p \approx 0.45 \) suggests that the central quantiles of the true distribution could be more clustered about this point than those of the null uniform. Thus the true distribution is perhaps less dispersed than the uniform and slightly shifted toward 0. Similar insight can be derived from the empirical PP plot (Panel 1) and QQ plot (not shown) of this data set. However, by making use of the null expectation and approximate homoscedasticity of \( CC(\cdot) \) under \( H_0 \), the B-plot allows an enhanced appraisal of these main features of the data. In particular, this B-plot allows seeing for which quantiles of the null CDF \( F_0(\cdot) \), the discrepancy with the data is unexpectedly large (positive or negative). The approach is developed in Section 3.3 for the null and composite case and discussed for the present case in Section 3.5.4, where we revisit this data set.

Such visual insights about the discordance of data with a null model is interesting, but should be supported by a GoF test for error control. Here we exploit the asymptotic behaviour of \( n^{1/2} \hat{CC}(\cdot) \) under \( H_0 \) to obtain inferential statements about the overall validity of the model. Hence, we now consider the problem of creating a GoF test based on the empirical CC. Here, we proceed in a simple and traditional way by considering \( \hat{CC}(p) \) evaluated at points \( p \) in a finite set associated with a B-plot of interest. These points are described in the next subsection. Then, from the values of the related bars, we build a \( \chi^2 \)-type test statistic. Finally, we
introduce a selection rule to decide about the most useful subset of points, which is a highly non-trivial problem in the case of statistics of the present type.

![Graphical representations for the smiling baby data](image)

Figure 2.1. Graphical representations for the smiling baby data ($n = 55$) in Bhattacharjee & Mukhopadhyay (2013). Panel 1: PP plot against the $U[0,1]$ distribution (45-degree solid line); Panel 2: B-plot of the $n^{1/2} \overline{C}(\cdot)$ of eq. (2.2) evaluated over the grid $p \in \{1/32, \ldots, 31/32\}$.

2.2. Nested partition of (0,1) and projected Haar function $\{h_{s,j}(\cdot)\}$. Let $a_{s,k} = (2k-1)/2^{s+1}, (s = 0, 1, \ldots; k = 1, 2, \ldots, 2^s)$. Associated with a sequence of sample sizes $n$, let $S(n)$ be a user-defined increasing sequence of integers. With $s$ ranging in $\{0, 1, \ldots, S(n)\}$ and $k \in \{1, 2, \ldots, 2^s\}$, introduce in turn the sequence of nested sets of points in (0,1) corresponding to those $a_{s,k}$’s with $\{s = 0\}, \{s = 0, 1\}, \{s = 0, 1, 2\}, \ldots$, sorted from smallest to largest to create the increasingly finer sets of points

$$\{p_{0,1}\}, \{p_{1,1}, p_{1,2}, p_{1,3}\}, \ldots, \{p_{s,1}, \ldots, p_{s,d(s)}\}, \ldots$$

$d(s) = 2^{s+1} - 1$.

For example, if $S(n) = 2$ the nested sets of ordered points are $\{4/8\}, \{2/8, 4/8, 6/8\}$ and $\{1/8, 2/8, 3/8, 4/8, 5/8, 6/8, 7/8\}$. Also define $D(n) = \{d(s) : s = 0, \ldots, S(n)\}$ and $D(n) = d(S(n))$.

Now for a given $s$ and corresponding $d(s)$, introduce the $d(s)$-dimensional vector of functions $(h_{s,1}(p), \ldots, h_{s,d(s)}(p))$ with $0 \leq p \leq 1$, where for $j \in \{1, \ldots, d(s)\}$

$$h_{s,j}(p) = (1 - p_{s,j})^{1/2} \times I(0 \leq p \leq p_{s,j}) + \left(\frac{p_{s,j}}{1 - p_{s,j}}\right)^{1/2} \times I(p_{s,j} < p \leq 1)$$

$$= \frac{p_{s,j} - I(0 \leq p \leq p_{s,j})}{(p_{s,j}(1 - p_{s,j}))^{1/2}}.$$  

These functions arise as normalized orthogonal projections of the Haar functions onto the cone of nondecreasing functions (cf. Ledwina & Wylupek, 2012b) and constitute the building blocks of our tools. Obviously, the functions in this system are normalized but not orthogonal. The explicit form of the inner product matrix of the $h_{s,j}(\cdot)$ and its inverse have been derived in Ledwina & Wylupek (2012b) under $\mathbb{H}_0$. Note that Pearson’s $\chi^2$ is also related to a set of points $0 = \pi_0 < \pi_1 < \ldots < \pi_k = 1$ defining a normalized but not orthogonal system of functions given by

$$l_j(p) = I(\pi_{j-1} < p < \pi_j) - (\pi_j - \pi_{j-1})/\pi_j - \pi_{j-1}} \right)^{1/2}. \quad \text{Indeed, Pearson’s } \chi^2 = \sum_{j=1}^{k} \left(\sum_{i=1}^{n} l_j(X_i)\right)^2. \text{ Here, a single } l_j(\cdot) \text{ corresponds to two neighbouring points, so Pearson’s system is naturally adapted to histograms. This is to be contrasted with the system } \{h_{s,j}(\cdot)\}, \text{ where each point } p_{s,j} \text{ corresponds to the single function } h_{s,j}(\cdot) \text{ and is thus adapted to CDFs.}
2.3. Fourier coefficient of the comparison density in the system \( \{h_{s,j}(\cdot)\} \).

Write \( f_0(\cdot) \) and \( f(\cdot) \) for the densities of \( F_0(\cdot) \) and \( F(\cdot) \) respectively. Assume further that \( f_0(x) = 0 \implies f(x) = 0 \). Then the function \( H(\cdot) = F(F_0^{-1}(\cdot)) \) satisfies \( H(0) = 0, H(1) = 1 \) and possesses a density, called the comparison density (Parzen, 2004) or the relative density (Handcock & Morris, 1999, Chapter 2, p. 22) given by \( \kappa(p) = f(F_0^{-1}(p))/f_0(F_0^{-1}(p)), \ p \in (0,1) \). Obviously, \( \kappa(\cdot) \equiv 1 \) if and only if \( H_0 \) holds. Now, consider the Fourier coefficients (FC) of \( \kappa(\cdot) \) in the system \( \{h_{s,j}(\cdot)\} \). The \((s,j)\)-th Fourier coefficient, noted \( \gamma_{s,j} \), takes the form

\[
(2.3) \quad \gamma_{s,j} = \gamma_{s,j}(p_{s,j}) = \int_0^1 \kappa(p) h_{s,j}(p) \, dp = \frac{p_{s,j} - F(F_0^{-1}(p_{s,j}))}{(p_{s,j}(1 - p_{s,j}))^{1/2}}.
\]

Then, \( H_0 \) can be equivalently reformulated as \( \gamma_{s,j} = 0, (s = 0, 1, \ldots; j = 1, \ldots, d(s)) \).

Expression (2.3) leads to the empirical FC : \( \hat{\gamma}_{s,j} = n^{-1} \sum_{i=1}^n h_{s,j}(F_0(X_i)) \). A little algebra shows that \( \gamma_{s,j} = \hat{\chi}(p_{s,j}) \) and \( \hat{\gamma}_{s,j} = \hat{\chi}(p_{s,j}) \). Observe that, in view of our nested partition, increasing \( s \) allows for more and more careful checks of the discrepancies between \( F(\cdot) \) and \( F_0(\cdot) \). More precisely, we start by considering the deviation at the median of \( F_0(\cdot) \), then check the fit at its quartiles and so on. Also, \( \hat{\gamma}_{s,j} \) can be seen as a statistic for testing \( \gamma_{s,j} = 0 \).

For \( S(n) \) large enough corresponding to \( n \geq n_0 \) say, if \( F(\cdot) \neq F_0(\cdot) \), there exist \( s_0 \in \{0, 1, \ldots, S(n)\} \) and \( j_0 \in \{1, \ldots, d(s_0)\} \) such that

\[
(2.4) \quad \gamma_{s_0,j_0} = 0.
\]

Because we are considering nested partitions, for \( n \geq n_0 \) and \( s \geq s_0 \), there is a corresponding \( j_0 \) such that (2.4) remains valid; hence we might as well assume that \( n_0, s_0, j_0 \) are the smallest values for which (2.4) holds.

2.4. \( \chi^2 \)-type test statistic and selection rule for its number of components \( d(s) \).

Set

\[
(2.5) \quad \kappa(d(s)) = n^{1/2} \left( \hat{\chi}(p_{s,1}), \ldots, \hat{\chi}(p_{s,d(s)}) \right) = n^{1/2} \left( \hat{\gamma}_{s,1}, \ldots, \hat{\gamma}_{s,d(s)} \right).
\]

This vector can be seen as the score vector of an auxiliary parametric model associated with \( (h_{s,1}(\cdot), \ldots, h_{s,d(s)}(\cdot)) \) modelling an alternative to \( F_0(\cdot) \). Consider the \( \chi^2 \)-type test statistic for the GoF problem of testing \( H_0 \):

\[
(2.6) \quad \mathcal{P}_{d(s)} = \kappa^\prime(d(s))\kappa(d(s)) = n \sum_{j=1}^{d(s)} \left[ \hat{\chi}(p_{s,j}) \right]^2.
\]

Note that here and in the sequel, the term “\( \chi^2 \)-type” refers to the structure of the test statistic, which as in Pearson’s standard \( \chi^2 \) test, is a sum of squares of asymptotically \( N(0,1) \) components under \( H_0 \), but not to its asymptotic distribution. Indeed, under \( H_0 \), the null asymptotic distribution of \( \mathcal{P}_{d(s)} \) is a sum of weighted \( \chi^2 \). The covariance matrix \( \Lambda_{d(s)}(\kappa(d(s))) \) and the related score statistic, namely \( \kappa^\prime(d(s))\left(\Lambda_{d(s)}^{-1}\kappa(d(s))\right) \), could be used to obtain a quadratic form with an asymptotic \( \chi^2 \) distribution. We do not pursue this further because \( \Lambda_{d(s)} \) being non-diagonal, the components of the score statistic are linear combinations of the \( \hat{\chi}(p_{s,j}) \)'s and thus difficult to interpret. Furthermore, the convenience of a \( \chi^2(d(s)) \) reference distribution vanishes in view of the upcoming enhancements to (2.6).

An important question with GoF test statistic (2.6) is the proper choice for the number of components \( d(s) \) to include. Here we adapt a data driven selection rule inspired by Ledwina & Wylupek (2012a, 2015) that is defined as follows. First, consider the auxiliary selection rule with AIC-type penalty

\[
(2.7) \quad A(a) = \min \left\{ d(s) \in D(n) : \mathcal{P}_{d(s)} - a \cdot d(s) \geq \mathcal{P}_{d(t)} - a \cdot d(t), \ d(t) \in D(n) \right\}.
\]
Now, given \( n \) and significance level \( \alpha \), find by the Monte Carlo method a value \( a = a(n, \alpha) \) such that, under \( \mathbb{H}_0 \), \( \Pr(A(a) = 1) \geq 1 - \alpha \). Such a value exists because \( \Pr(A(a) = 1) \) is a nondecreasing function of \( a \in [0, \infty) \). Then introduce the auxiliary statistic
\[
M_{D(n)} = \max_{1 \leq j \leq D(n)} \left| n^{1/2} \bar{C}(p_{S(n),j}) \right|
\]
and denote by \( m(n, \alpha) \) the critical value of the \( \alpha \)-level test rejecting \( \mathbb{H}_0 \) for large values of \( M_{D(n)} \). Finally, set
\[
R(\alpha) = \begin{cases} 
A(a(n, \alpha)), & M_{D(n)} \leq m(n, \alpha), \\
A(0), & M_{D(n)} > m(n, \alpha).
\end{cases}
\]

With these notations, our data driven GoF \( \chi^2 \)-type test statistic takes the form \( P_{R(\alpha)} \). Its critical values are obtained via Monte Carlo simulations (see Appendix B for some recommendations).

In (2.9), test statistic \( M_{D(n)} \) acts like an oracle. When the oracle rejects \( \mathbb{H}_0 \), i.e. when \( M_{D(n)} > m(n, \alpha) \), then \( R(\alpha) = A(0) = D(n) \) because the \( p_{d(s)} \) are increasingly ordered. In such cases, \( P_{R(\alpha)} = P_{D(n)} \) and our procedure seeks confirmation of the oracle’s rejection by using the comprehensive test statistic \( P_{D(n)} \).

Now consider the case where \( M_{D(n)} \) accepts the null hypothesis \( \mathbb{H}_0 \), i.e. \( M_{D(n)} \leq m(n, \alpha) \). This means that after examining the large number \( (D(n)) \) of components in \( M_{D(n)} \), the oracle sees no reason to reject \( \mathbb{H}_0 \) at level \( \alpha \). Then our procedure \( P_{R(\alpha)} \) proceeds to look at a smaller number of components by using the auxiliary selection rule \( A(\alpha) \). More precisely, under \( \mathbb{H}_0 \), it holds that \( \Pr(A(a(n, \alpha)) = 1) \geq 1 - \alpha \). Hence, the resulting penalty \( a(n, \alpha) \) in the selection rule is relatively large. It follows that the (implied) basic selection rule \( R(\alpha) \) will tend to choose a relatively small dimension \( d(s) \). This results in moderately large critical values for \( P_{R(\alpha)} \), in comparison with the corresponding critical values for \( P_{D(n)} \). In turn, this leads to more frequent rejections under the alternatives than would produce \( P_{D(n)} \) and thus, results in higher power.

The following proposition is proved in Appendix D.1.

**Proposition 1.** Assume that \( S(n) \rightarrow \infty \) and \( D(n) = o(n^{\delta}) \) for some \( \delta \in (0, 1/2) \). Then the test rejecting for large values of \( P_{R(\alpha)} \) is consistent under any alternative \( F(\cdot) \neq F_0(\cdot) \).

In closing this section, note that from the proof of this proposition, it follows that under \( \mathbb{H}_0 \), the first line in (2.9) plays the main role in controlling \( R(\alpha) \) while under alternatives, the value of \( R(\alpha) \) is mainly decided by the second line.

### 2.5. A simulation experiment.
In order to assess the properties of our test based on \( P_{R(\alpha)} \), a simulation experiment was performed. The goal was to compare the power of \( P_{R(\alpha)} \) with some of its competitors. The null hypothesis considered is \( F_0(x) = \Phi(x) \), the CDF of the \( N(0, 1) \) distribution. The alternatives were carefully selected to cover a fair range of shapes of \( \text{CC}(-) \), see Figure 2.2 and the discussion in Section 4. They are:

- \( A_0^0(\theta) \), a normal location model with CDF \( \Phi(x - \theta) \), \( \theta \in \mathbb{R} \);
- \( A_0^0(\theta) \), a normal scale model with CDF \( \Phi(x/(1 + \theta)) \), \( \theta > -1 \);
- \( A_0^2(\theta) \), the two-piece normal distribution with density \( C \{ I(x < 0) \exp(-x^2/2) + I(x \geq 0) \exp(-x^2/2(1 + \theta)^2) \} \) with \( C = ((2\pi)^{1/2}(2 + \theta/2))^{-1} \) and \( \theta > -1 \);
- \( A_0^2(\theta) \), a model of Fan with local departure around 0 and density \( \phi(x)[1 + \{ 4x(\theta - 2) - |z| \} I(|z| < \theta)] \), where \( z = 2\Phi(x) - 1 \) and \( \theta \in [0, 1] \);
• $A^0_0(\theta)$, a normal contamination model with CDF $(1-\theta)\Phi(x) + \theta \Phi(x-2)\),
  $\theta \in [0, 1]$;
• $A^0_1(\theta)$, Anderson’s skewed distribution with stochastic representation $I(Z < 0)Z/(1-\theta) + I(Z \geq 0)Z(1-\theta)$ where $Z \sim N(0, 1)$ and $\theta \in [0, 1]$;
• $A^0_2(\theta)$, the Mason & Schuenemeyer tail alternative with CDF $J(\Phi(x), q, \theta)$
  where $\theta > -1$, $J(x, q, \theta) = (q^{\theta/(\theta+1)}x^{1/(\theta+1)})I(0 \leq x < q) + xI(q \leq x \leq 1 - q) + ((1-q^{\theta/(\theta+1)}(1-x)^{1/(\theta+1)})I(1 - q < x \leq 1)$ and here $q = 0.25$;
• $A^0_3(\theta)$, Anderson’s kurtotic distribution generated as $X = Z \cdot |Z|^\theta$, where $Z \sim N(0, 1)$ and $\theta \geq 0$;
• $A^0_4(\theta)$, a Lehmann contamination model with CDF $(1-\theta)\Phi(x) + \theta \Phi(x))^{0.175}$,
  $\theta \in [0, 1]$ with $(\Phi(x))^\delta$ being the Lehmann distribution.

For more details about these alternatives, see Appendix C. They all reduce to the $N(0, 1)$ when $\theta = 0$ and thus embed the null model. Our choice for $H_0$ offers the convenience of easily defined embedding families of alternatives and allows some comparisons with the simulations in Appendix C. No loss of generality ensues from this choice as the probability integral transformation translates the GoF problem for any continuous $F_0(\cdot)$ into a null $U(0,1)$ distribution, for which many good tests have been derived. In particular, we have considered the following two competitors: the Anderson-Darling statistic (AD) and the Berk & Jones (1979) statistic (BJ).

Taking $\alpha = 0.05$ and $n = 100$, we investigated $P_{R(\alpha)}$ with $S(n) = 6$ and computed $m(n, \alpha) = 3.30$ and $a(n, \alpha) = 3.31$ (see Appendix B for some practical considerations regarding these choices and values). The power functions for the nine alternatives were simulated in their $\theta$ range for each of AD, BJ and $P_{R(\alpha)}$. The 5% critical values were obtained from 100 000 replications under the null distribution, while the powers were computed from 10 000 Monte Carlo runs. We extracted from each power curve a representative value of $\theta$ which provided intermediate powers, e.g. not too close to 0.05 and 1.0 and where the powers of the various tests could be distinguished. As a result of these choices, the powers presented below offer a broad view of the comparative behaviour of the tests over a fair range of situations.

The results are reported in Table 3. None of the tests dominates and $P_{R(\alpha)}$ emerges as very competitive. In most cases, AD is less powerful and simulations results in Čmiel, Inglot & Ledwina (2020) show that for larger sample sizes and heavy tails, the power differences between AD and $M_{D(n)}$ can be even more pronounced. Thus powerwise, we conclude that our test could be included among the best solutions for this problem.

We close this section by noting that when any of AD, BJ rejects $H_0$, the user is left with little clues to what aspects of the null model must be corrected. In contrast, when the competitive $P_{R(\alpha)}$ rejects, a B-plot as in Panel 2) of Figure 3.1 can be produced to help the user see where the, now statistically established, discrepancies are located. The B-plot could be further supplemented with acceptance regions to separate in a reasonable way the large components from those more consonant with a local agreement to the model. This will be discussed in Section 3.3 and illustrated in Section 3.5 (see also Appendix A). Hence the pair (B-plot, $P_{R(\alpha)}$) can be a useful tool for statistical modelling.

We now consider the case where the parameter $\beta$ in model $F_0(\cdot; \beta)$ is unknown.
In the case of a composite null hypothesis, we proceed in a reversed order than under $H_0$. We start with a counterpart to the empirical Fourier coefficients (FC) associated with an adjusted variant of $\gamma_{s,j}$ to motivate our definition of an analogue to CC($\cdot$) in the present setting. Next, we define the related $\chi^2$-type test and its data driven version. We focus on the important case of location-scale families and illustrate our approach by testing GoF to the Gaussian distribution. A simulation experiment, reported in Appendix C, confirms that our test is competitive in a broad spectrum of situations. Finally, we produce the B-plots of four real data sets (more are worked out in Appendix A) to show their usefulness in obtaining

\[ \text{Figure 2.2. CC}(p) \text{ (solid black curve) for the alternative distributions in Table 1 for testing the simple null hypothesis } H_0 : \Phi(x). \]
insights about the aspects of the model that could have caused rejection or led to an erroneous conclusion because of the application of an inadequate GoF test.

3.1. Fourier coefficient, empirical CC and B-plot. Let $X_1, \ldots, X_n$ be i.i.d. observations from a continuous CDF $F(\cdot)$ and consider the family of null models $F_0(\cdot; \beta)$ where the Euclidean parameter $\beta \in \mathcal{B}$ is unknown. The null hypothesis of interest is composite and takes the form $H : F(\cdot) = F_0(\cdot; \beta)$ for some unknown $\beta \in \mathcal{B}$.

As in Section 2.3, the $(s, j)$-th empirical FC of the comparison density associated with $F(\cdot)$ and $F_0(\cdot; \beta)$ can be defined as

$$\hat{\gamma}_{s,j}(\beta) = \frac{\hat{p}_{s,j} - \hat{F}_n(p_{s,j}; \tilde{\beta})}{(p_{s,j}(1 - p_{s,j}))^{1/2}}, \quad \hat{F}_n(p; \tilde{\beta}) = n^{-1} \sum_{i=1}^{n} I(F_0(X_i; \tilde{\beta}) \leq p).$$

Plugging into this expression the value $\tilde{\beta}$ of an estimator of $\beta$, elementary calculations yield

$$\hat{\gamma}_{s,j}(\tilde{\beta}) = \frac{\hat{p}_{s,j} - \hat{F}_n(p_{s,j}; \tilde{\beta})}{(p_{s,j}(1 - p_{s,j}))^{1/2}}, \quad \hat{F}_n(p; \tilde{\beta}) = n^{-1} \sum_{i=1}^{n} I(F_0(X_i; \tilde{\beta}) \leq p).$$

It is tempting to define the empirical CC as $\hat{C}(\cdot, \cdot)$, but the use of $\tilde{\beta}$ must be taken into account. Consider the empirical process $\hat{e}_n(p; \tilde{\beta}) = n^{1/2}(\hat{F}_n(p; \tilde{\beta}) - p)$, $p \in [0, 1]$. Durbin (1973) has studied this process and shown that under mild smoothness assumptions on $F_0(\cdot; \cdot)$ (his assumption A.2) and if $\tilde{\beta}$ satisfies

$$n^{1/2}(\tilde{\beta} - \beta) = n^{-1/2} \sum_{i=1}^{n} B(X_i, \beta) + o_P(1),$$

where $B(X, \beta)$ has mean 0 and a finite covariance matrix under $H$ (a variant of his assumption A.1 adapted to our context), this process converges under $H$ to some Gaussian process on $[0, 1]$ with 0 mean function. The covariance function $\rho(\cdot, \cdot)$ of the limiting process is also given in Durbin (1973). We assume throughout that Durbin’s assumptions hold true. Hence, putting $\sigma_{s,j} = (\rho(p_{s,j}, p_{s,j}))^{1/2}$, we get that $\hat{e}_n(p_{s,j}; \tilde{\beta})/\sigma_{s,j}$ is asymptotically $N(0, 1)$ under $H$. We also refer to Neuhaus (1979) for a thorough discussion of Durbin’s (1973) paper.

The above leads to defining the empirical CC in the present context as

$$\hat{C}(p; \tilde{\beta}) = \frac{p - \hat{F}_n(p; \tilde{\beta})}{\rho^{1/2}(p, p)}.$$

The graph of $\hat{C}(\cdot; \tilde{\beta})$ evaluated on the points $p_{s,j}$’s of a grid defines the B-plot when the nuisance parameter $\beta$ is present.

3.2. CC and alternative in the case of location-scale models. Let $F(\cdot)$ be the true CDF of the data and suppose the null model is location-scale with $\beta$ estimated by $\tilde{\beta}$, a $n^{1/2}$-consistent estimator under $F_0(\cdot; \cdot)$. Suppose that under $F(\cdot)$, $\tilde{\beta} \to \beta(F) = (\beta_1(F), \beta_2(F))'$ where the convergence is in probability with respect to $F(\cdot)$. The population version of $CC(p; \tilde{\beta})$ is

$$CC(p; \beta(F)) = \frac{p - F(\beta_2(F) \cdot F_0^{-1}(p) + \beta_1(F))}{\rho^{1/2}(p, p)}.$$

We call $F(\cdot)$ an alternative when $F(x) \neq F_0((x - \beta_1(F))/\beta_2(F))$ for some $x \in \mathbb{R}$. By continuity of $F(\cdot)$ and the fact that the partition of Section 2.2 is dense, there exists $n_0, s_0 \in \{0, \ldots, S(n_0)\}$ and $j_0 \in \{1, \ldots, d(s_0)\}$, such that $CC(p_{n_0,j_0}; \beta(F)) \neq 0$. Without loss of generality we may, as in Section 2.3, assume that $n_0, s_0, j_0$ are the smallest such indices. Thus for sufficiently large $n$ and under $F(\cdot)$, there will be at least one non-zero component among the $CC(p_{s,j}; \beta(F))$’s.
3.3. Acceptance region for subset of bars. Similarly to the case of Section 2.1 where \( \beta(F) \) is known, \( \mathcal{C}(p; \beta(F)) \) inherits its interpretation from its local sign and possible zeroes. Now \( F_0(; \beta(F)) \) is the reference CDF. Therefore, it is important to discriminate those bars that seem compatible with \( H \) from more surprisingly large ones, positive or negative. This suggests, as a first step, supplementing the B-plot with one-sided \((1 - \alpha)\)-th acceptance intervals for the height of an individual bar expected under the null model. Here, this is done by drawing on the B-plot horizontal lines at \( \pm 1.645 \), if one considers \( \alpha = 0.05 \). We use asymptotic critical levels because they approximate well the finite sample distribution of single bars; see Section 3.5.1. Note that to ensure the statistical rigor in a classical sense of knowledge, not from looking at the B-plot arising from a given sample.

Insight deriving from a single bar may be rather limited and, in view of the interpretation of B-plots as explained below equation (2.1), instead of a single bar, one may be interested in subsets of adjacent bars and there simultaneous acceptance regions. Of course the same caveat as above applies about their uses in practice. Now for such subsets, recall from Durbin’s (1973) result that the joint asymptotic distribution of a subset of bars is multivariate normal with means 0, unit variances and associated covariance function. Thus the correlation between the bars must be taken into account. When a subset of bars, say \( n^{1/2} \mathcal{C}(p_{S(n), j}; \hat{\beta}) \) for all \( j \in J \), are expected to be jointly positive, one approach to flag their significance is to compute a one-sided simultaneous \( 1 - \alpha \) level acceptance region. This consists in computing by Monte Carlo and under \( \mathbb{H} \) an approximation to \( u(n, \alpha; J) \) in

\[
\text{pr}\left(\max_{j \in J} n^{1/2} \mathcal{C}(p_{S(n), j}; \hat{\beta}) \leq u(n, \alpha; J)\right) \geq 1 - \alpha.
\]

If the bars under consideration should be negative, (3.3) must be adapted to obtain the lower bound \( \ell(n, \alpha; J) \) via

\[
\text{pr}\left(\min_{j \in J} n^{1/2} \mathcal{C}(p_{S(n), j}; \hat{\beta}) \geq \ell(n, \alpha; J)\right) \geq 1 - \alpha.
\]

If desired, a two-sided simultaneous \( 1 - \alpha \) level acceptance region for all \( j \in J \) can be defined as follows. With \( u(n, \alpha; J) \) and \( \ell(n, \alpha; J) \) as defined above, it holds that

\[
\text{pr}\left(\min_{j \in J} \sqrt{n} \mathcal{C}(p_{S(n), j}) \geq \ell(n, \alpha; J), \max_{j \in J} \sqrt{n} \mathcal{C}(p_{S(n), j}) \leq u(n, \alpha; J)\right) \geq 1 - 2\alpha.
\]

Hence \( \ell(n, \alpha/2; J), u(n, \alpha/2; J) \) forms a two-sided \( 1 - \alpha \) level acceptance regions for bars in \( J \).

Such computations are easily done because with a location-scale null model and a \( \hat{\beta} \) invariant to location-scale transformations, the distribution of \( \mathcal{C}(p_{S(n), j}; \hat{\beta}) \) does not depend on \( \beta \), so sampling can be made from e.g. \( F_0(; (0, 1)) \). When \( \hat{\beta} \) is known, a variant of \( u(n, \alpha; J) \) can be computed by approximating under the null hypothesis expression (3.3) using \( \mathcal{C}(p_{S(n), j}) \), and similarly for \( \ell(n, \alpha; J) \). When at least one of the bars related to an element of \( j \in J \) is above the computed \( u(n, \alpha; J) \) or below \( \ell(n, \alpha; J) \), the heuristic suggests that the data seems incompatible with the null model in the related region. We represent these simultaneous acceptance regions by shaded grey stripes on the B-plot, see Section 3.5 or Appendix A for illustrations and Appendix C for some information about the required computational effort. Also, in these computations the question of choosing appropriately the simultaneous level \( \alpha \) of such acceptance regions arises. See Section 3.5 for some discussion about this point.
3.4. $\chi^2$-type test statistic and a selection rule for $d(s)$ for testing Gaussianity. Consider as in (2.5), $K(\hat{\beta},d(s)) = n^{1/2} \left( \hat{C}(p_{s,1}; \hat{\beta}), \ldots, \hat{C}(p_{s,d(s)}; \hat{\beta}) \right)'$. Inspired by (2.6), a GoF test statistic for $\mathbb{H}$ is

$$
(3.4) \quad \mathcal{P}_{d(s)}(\hat{\beta}) = K'(\hat{\beta},d(s))K(\hat{\beta},d(s)) = n \sum_{j=1}^{d(s)} \left[ \hat{C}(p_{s,j}; \hat{\beta}) \right]^2.
$$

Remark 1. When $F_0(\cdot; \beta)$ is a location-scale family, i.e. $F_0(x; \beta) = F_0((x - \beta_1)/\beta_2)$ with $\beta = (\beta_1, \beta_2)' \in \mathcal{B} \subseteq \mathbb{R} \times \mathbb{R}_+$, we have $F_n(p; \hat{\beta}) = \hat{F}_n(\beta_2 F_0^{-1}(p) + \hat{\beta}_1)$, where $\hat{F}_n(\cdot)$ is the ordinary empirical CDF of the sample. Under Durbin’s assumptions, the process $e_n(p; \hat{\beta})$ has a limiting distribution that does not depend on $\beta$. Test statistic (3.4) becomes

$$
(3.5) \quad \mathcal{P}_{d(s)}(\hat{\beta}) = n \sum_{j=1}^{d(s)} \left[ \frac{p_{s,j} - \hat{F}_n(\beta_2 F_0^{-1}(p_{s,j}) + \hat{\beta}_1)}{\hat{\sigma}_{s,j}} \right]^2.
$$

To reduce technicalities, consider from now on the important sub-case where $F_0(x; \beta) = F_0((x - \beta_1)/\beta_2)$ is the Gaussian CDF with unknown expectation $\beta_1$ and variance $\beta_2^2$, i.e. $F_0(\cdot) = \Phi(\cdot)$ with density $f_0(\cdot) = \varphi(\cdot)$. To estimate $\beta_1$ and $\beta_2^2$, we consider the maximum likelihood estimators (MLE), i.e. $\hat{\beta}_1 = \hat{X}$ and $\hat{\beta}_2^2 = S^2 = n^{-1} \sum_{i=1}^n (X_i - \hat{X})^2$. This model and these estimates satisfy all assumptions in Durbin’s theorem. Hence we have $\rho(t,v) = \min\{t,v\} - tv - \rho_1(t)\rho_1(v) - \rho_2(t)\rho_2(v)$, $t, v \in [0,1]$, where $\rho_1(t) = \varphi(\Phi^{-1}(t))$ and $\rho_2(t) = 2^{-1/2} \varphi(\Phi^{-1}(t))\Phi^{-1}(t)$. In this case, the quantity $\sigma_{s,j} = (p_{s,j} - \rho_1^2(p_{s,j}) - p_2^2(p_{s,j}))/2$ is smaller than the value $(p_{s,j} - p_2^2(p_{s,j}))/2$ adequate for $\mathbb{H}_0$. To be specific, $\rho(t,t)$ is symmetric about $1/2$, $\cap$ shaped but much smaller than $t(1-t)$ in $(0,1)$, while $\lim_{t \to \infty} \rho(t,t)/t(1-t) = \lim_{t \to 1^-} \rho(t,t)/(t(1-t)) = 1$.

To define a selection rule for $d(s)$ in (3.5), we proceed similarly as in Section 2.4. First, we seek an oracle test whose task is to provide some reliable preliminary information on the situation. The results of Section 2 suggest considering the following version of the oracle test (2.8), namely...
Remark 2. Estimated by MLE. For this problem, several solutions exist (see Arnastauskaité, 2003). The null hypothesis is \( H_0 \). Experiment was performed. The structure of the experiment mimics closely that in Section 2.5. The null hypothesis is \( H \): \( F(x) = \Phi((x - \beta_1)/\beta_2) \) where \((\beta_1, \beta_2)\) are estimated by MLE. For this problem, several solutions exist (see Arnastauskaité, 2003). For this problem, several solutions exist (see Arnastauskaité, 2003).

Proposition 2. Let \( F(\cdot) \) be an alternative in the sense of Section 3.2 to the Gaussian null model. Assume that the fourth moment of \( F(\cdot) \) exists and is finite. Moreover, assume that \( F(\cdot) \) possesses a bounded density \( f(\cdot) \) with respect to the Lebesgue measure on \( \mathbb{R} \). Further assume that \( \tilde{\beta} \) is the MLE for \( \beta \). Finally, let \( S(n) \to \infty \) and \( D(n) = o(n^{1/2}) \) as \( n \to \infty \). Then, the test rejecting for large values of \( P_{Q(\alpha)}(\tilde{\beta}) \) is consistent under \( F(\cdot) \).

Remark 2. Under the assumptions on \( F(\cdot) \) and \( \tilde{\beta} \) in Proposition 2, it holds that, as \( n \to \infty \), \( \sup_{\epsilon \leq p \leq 1-\epsilon} |\overline{C}(p; \tilde{\beta}) - \overline{C}(p; \beta(F))| \to 0 \) in probability for any \( \epsilon \in (0, 1) \).

In order to assess the properties of the test based on \( P_{Q(\alpha)}(\tilde{\beta}) \), a simulation experiment was performed. The structure of the experiment mimics closely that in Section 2.5. The null hypothesis is \( H : F(x) = \Phi((x - \beta_1)/\beta_2) \) where \((\beta_1, \beta_2)\) are estimated by MLE. For this problem, several solutions exist (see Arnastauskaité, 2003).
Ruzgas & Brazėnas, 2021), notably the Anderson-Darling (AD), the Shapiro-Wilks (SW) and the BCMR tests.

Our main interest is to see how our approach compares with these. The details and results of the simulation appear in Appendix C, which pertains to a set of carefully selected alternatives according to the form of their CC(·; β(F)) partly inspired by those in Section 2.5. It emerges from this experiment that, as an oracle, $M_{D(n)}(\beta)$ generally does poorly. Otherwise, and similarly to the context of Section 2, none of the other tests dominates and $P_{Q(n)}(\beta)$ turns out to be a good competitor, being powerwise on par with the oracle test it is based upon. Recall that a main advantage of our approach is the possibility of deriving information from the B-plot about where the null model could be at fault and an overall measure of fit based on this plot. Note however that regarding the tests of $H_0$ and $H_1$, this common approach allows to exhibit some essential differences between the two problems. See the discussion in Appendix C.

3.5. Real data examples. The results of the previous sections are now applied to some real data sets to show how useful insights can be derived from the components $n^{1/2} \overline{C}(\cdot; \beta)$ when using the methods of the paper. More examples are worked out in Appendix A. Programs in the Mathematica language (Wolfram Research, Inc., Mathematica, Version 12.1, Champaign, IL, 2020) to compute the new data-driven test statistic, the B-plots and the acceptance regions can be found in the GITHUB repository gilles-ducharme/GoF.Validation.

3.5.1 The wave records data. We consider a data set in Bickel and Doksum (1977, p. 384, Table 9.6.3) measuring the time spent above a high level of $n = 66$ wave records in the San Francisco bay. Their analysis does not reject the null Gaussian hypothesis at level 10%. The data were later considered by Rosenkranz (2000) whose simultaneous 90% confidence band approach indicates some inconsistency with the postulated Gaussian model in the left tail of the distribution. They were reexamined by Aldor-Noiman et al. (2013) using simultaneous confidence bands about the QQ plot. Their approach detects, at the 5% level, a significant departure from normality in the right tail, while another approach, based on Kolmogorov-Smirnov bands, nearly rejects, at the same level, relying solely on points at the centre of the data.

For this data set, we have $\tilde{\beta}_1 = \overline{X} = 3.79$ and $\tilde{\beta}_2 = S = 2.39$. We apply the test based on $P_{Q(n)}(\beta)$ with $\alpha = 0.05$, $S(n) = 4$, $t(n, \alpha) = 2.60$ and compute $a(n, \alpha; \tilde{\beta}) = 3.18$. The observed value of $T_n$ is 4.52, leading to $\hat{Q}(\alpha) = 31$ and $P_{Q(n)}(\beta) = 92.40$ to be compared to the 5% critical level of 10.46 obtained from 100 000 Monte Carlo replications. Thus we reject the null hypothesis of Gaussianity at the 5% level. The tests AD, SW and BCMR also reject at the 5% level with $p$-values of 0.004 for AD, 0.002 for SW and 0.002 for BCMR. Figure 3.1 shows the B-plot of $n^{1/2} \overline{C}(p_{4,j}; \beta)$ with $j \in \{1, \ldots, 31\}$ along with the $\pm 1.645$ lines delimiting the one-sided upper and lower 0.05-level asymptotic individual acceptance regions (dashed horizontal lines in Figure 3.1).

The value of $n^{1/2} \overline{C}(p_{31}; \beta)$ above the dashed line is consonant with the finding of Aldor-Noiman et al. (2013) of a fatter right tail than a Gaussian distribution. Assuming that the meaning of their term “right tail” relates to quantiles such that $p \geq 29/32 \approx 0.9$, we can substantiate this by computing from (3.3) $u(66, 0.05; \{29, 30, 31\}) = 2.21$. From Figure 3.1 because the bar at $p = 31/32$ is above 2.21, this further supports the claim of Aldor-Noiman et al. (2013). If we define similarly the left tail as below the first decile, i.e. $p \leq 3/32$, we get $u(66, 0.05; \{1, 2, 3\}) = 1.96$. Again from Figure 3.1 all three bars in $\{1, 2, 3\}$ are
above this value, in agreement with the finding in Rosenkranz (2000) regarding a thinner than Gaussian left tail.

Finally, Aldor-Noiman et al. (2013) do not define the meaning of “centre of the data” but, in view of the above findings of a thinner left and fatter right tail, suggesting some asymmetry to the right, we have decided to consider a slightly shifted centre ranging from $0.45 \approx 15/32 \leq p \leq 21/32 \approx 0.65$. This yields $\ell(66, 0.05; \{15, \ldots, 21\}) = -2.07$. The fact that three bars are below this value is consonant with the claim that, in this area, observations tend to be stochastically smaller than expected under Gaussianity.

Note that in computing the above acceptance regions, we have used the same level $\alpha$ (= 5\% here) as in the global test procedure. The main goal at this stage of the analysis is to derive heuristic, but principled, informations as to whether the departures are located where we believe they could be. Therefore, it seems reasonable to use for each subset of bars the initial level $\alpha$. This is in accordance with similar work in extracting diagnostic information following the rejection of a null model, as in Thas (2010, Sections 4.2.1.2 and 4.2.1.3). Thus in the sequel, all acceptance regions have been computed at level 5\% for each subset of bars considered.

To better appreciate the structure of the data, Figure 3.1 presents the B-plot associated with the denser partition $S(n) = 6$. This figure shows that the overall shape of the B-plot is retained, while evidence of departures in the tails are better manifested. The question arises whether the conclusions regarding sets of bars hold for this new B-plot. We have recomputed $u(66, 0.05, \{1, \ldots, 12\}) = 2.27$, $u(66, 0.05, \{116, \ldots, 127\}) = 2.57$ and $\ell(66, 0.05, \{58, \ldots, 84\}) = -2.43$ and represented the related simultaneous acceptance regions as shaded grey stripes. This shows that increasing $S(n)$ slightly changes the bounds, as should be expected, but that the previous observations remain unchanged.
By construction, the simultaneous acceptance regions are accurate up to the number of Monte Carlo replications, taken here as 100 000. However, one may inquire about the preciseness of the asymptotic ±1.645 individual bounds. In Figure 3.2 we added (the dotted red lines) the bounds obtained, again from 100 000 Monte Carlo replications. For finite samples, the $n^{1/2} \hat{C}C(p_{n,j}; \hat{\beta})$ have a discrete distribution. But interestingly, even with the small sample considered here ($n = 66$), the asymptotic 5% bounds are sufficiently close to the exact values to be useful throughout the range $p \in (0, 1)$, except perhaps near the outmost boundaries.

Figure 3.2. B-plot of $n^{1/2} \hat{C}C(p_{n,j}; \hat{\beta})$, with $j \in \{1, \ldots, 127\}$, for the wave records data ($n = 66$) in Bickel & Doksum (1977). The dashed grey lines are located at ±1.645 to identify the individual bars where some dissonance with $H$: Gaussianity occurs at one-sided level 5%. The shaded grey stripes are the simultaneous 95% one-sided acceptance regions for subsets of bars $\{1, \ldots, 12\}$, $\{58, \ldots, 84\}$ and $\{116, \ldots, 127\}$. The dotted red lines are the one-sided (upper and lower) 95% acceptance intervals for an individual bar, as obtained by the Monte Carlo method.

A B-plot can also provide useful information regarding which test statistic could be more profitably applied to assess overall compatibility between the data and the model. For example, the above analysis exhibits substantial disagreements between the data and the model in the tails. Now, much evidence (see Milbrodt & Strasser, 1990; Ćmiel, Inglot & Ledwina, 2020; Inglot, 2020 and references therein) have been unearthed showing that in such circumstances, the classical Kolmogorov-Smirnov (KS) test is weak: for the wave data we get a $p-$value of 0.06. B-plots present weighted distances between an estimated empirical process and the model CDF. This weighting rescales the differences appearing in the KS statistic, thus creating a comparable scale, under $H$, over the whole range of $p$. In particular, test statistic $M_{127}(\hat{\beta})$, which can be considered as a weighted variant of the KS statistic, leads to a $p-$value of 0.004, comparable with AD, SW and BCMR, thus removing the weakness of the classical KS solution. In contrast, in situations where the B-plot shows that most of the discrepancies occur in the central range of quantiles, such classical tests can be adequate tools, see the next section.

The above ranges for $p_{S(n),j}$ can be translated into the original scale of the data via $\hat{\beta}_2 \Phi^{-1}(p_{S(n),j}) + \hat{\beta}_1$; see Appendix A.1.
3.5.2 The tephra data. We consider the tephra data \( (n = 59) \) analyzed in Bowman & Azzalini (1997, Section 2.5). We apply the transformation to the logistic scale (i.e. \( X = \log(Y/(100 - Y)) \)) as done by these authors. For this data, we find \( \hat{\beta}_1 = \bar{X} = -1.77, \hat{\beta}_2 = S = 0.056 \). Here we reverse the order in which our tools were applied in the previous example and first look at the B-plot for this data set, which appears in Figure 3.3 for \( S(n) = 4 \) and \( S(n) = 6 \). A few bars are unexpectedly large in case \( H \) is true, in the central region \( p \in (13/32, 19/32) \). This is substantiated by computing (for \( S(n) = 4 \)) \( u(59, 0.05; \{13, \ldots, 19\}) = 2.10 \).

The tephra data:

\[
\begin{array}{cccccccccc}
S(n) = 4 & 8 & 8 & 32 & 32 & 32 & 32 & 32 & 32 & 32 \\
S(n) = 6 & 12 & 128 & 24 & 128 & 52 & 128 & 76 & 126 & 96 & 128 & 116 & 128
\end{array}
\]

Figure 3.3. B-plot of the values of \( n^{1/2} \hat{C}(p_{S(n)}; \tilde{\beta}) \), with \( S(n) = 4 \) and \( S(n) = 6 \) for the tephra data \( (n = 59) \) from Bowman & Azzalini (1997). The dashed grey lines are located at \( \pm 1.645 \) to identify the bars where dissonance with \( H \): Gaussianity occurs. The shaded grey stripe is the simultaneous 95\% one-sided acceptance region for bars in the indicated deciles.

As stated in Section 3.5.1, there is a vast amount of literature providing some indications as to which test is more efficient in some given situations. In particular, when relatively large departures occur near the centre of the data, the classical solutions, e.g. KS, CvM and AD, have been shown to be efficient. In particular, the AD test works well as it can also detect allocations of moderate portions of mass towards the tails. For related discussions, see Janssen (2000), Inglot, Kallenberg & Ledwina (2000), Cmiel, Inglot & Ledwina (2020) along with its Supplementary Information and references therein. To substantiate this evidence here, we have applied the tests SW and BCMR which do not reject, with \( p \)-values for 0.13 of SW and 0.12 for BCMR. The test based on \( P Q_{Q(\alpha)}(\tilde{\beta}) \), with \( S(n) = 4 \) and using the same constants as previously, yields an observed value of \( T_n \) of 1.79, leading to \( \hat{Q}(\alpha) = 1 \) with \( P Q_{Q(\alpha)}(\tilde{\beta}) = 3.78 \), to be compared to a 5\% critical level of 10.47. Thus the null hypothesis of Gaussianity is also not rejected at the 5\% level. However, with the KS test, we get a \( p \)-value of 0.051 while the AD test yields a \( p \)-value of 0.03. This shows that the observation of the B-plot can provide some clues as to what test, here one of the classical solutions, should be subsequently applied to formally detect global departures between the data and the model.

3.5.3 The PCB data. We consider the PCB data set of Risenbrough \( (n = 65) \) recalled in Thas (2010, p. 5) and pertaining to the concentration of the chemical PCB (polychlorinated biphenyl) in the yolk lipids of Anacapa (pelican) birds. The data has been thoroughly studied by the author using several graphical methods and one of his conclusions, based on an estimated comparison density, is (Thas, 2010, p. 73) “the plot suggests weakly that the frequency of PCB concentrations is smaller than expected under the hypothesis of normality”.

\[
\begin{array}{cccccccccc}
& 32 & 32 & 32 & 32 & 32 & 32 & 32 & 32 & 32 \\
& 12 & 128 & 24 & 128 & 52 & 128 & 76 & 126 & 96 & 128 & 116 & 128
\end{array}
\]
For this data, we have $\tilde{\beta}_1 = \bar{X} = 210.0$ and $\tilde{\beta}_2 = S = 72.26$. Here again, we first look at the B-plot for this data set, which appear in Figure 3.4 and is plotted using both $S(n) = 4$ (with $\ell(65, 0.05; \{16, \ldots, 25\}) = -2.27$) and $S(n) = 6$ (with $\ell(65, 0.05; \{64, \ldots, 100\}) = -2.49$).

![Figure 3.4](image.png)

**Figure 3.4.** B-plot of the values of $n^{1/2} \hat{G}(p_{S(n),j}; \hat{\beta})$, with $S(n) = 4$ and $S(n) = 6$ for the PCB data ($n = 65$). The dashed grey lines are located at $\pm 1.645$ to identify the bars where dissonance with $H$: Gaussianity occurs. The shaded grey stripes are the simultaneous 95% one-sided acceptance region for bars $\{16, \ldots, 25\}$ and $\{64, \ldots, 100\}$.

The left half of the distribution appears concordant with the Gaussian hypothesis while the data seems more concentrated toward the centre on the right side. In contrast to previous examples, there seems to be little guidance formulated in the literature suggesting that one of the classical tests for this problem may be preferable in this case. In particular, we get for KS a $p$-value of 0.057, 0.056 for SW, and 0.057 for AD, all near but above the 0.05 threshold. The BCMR test barely rejects Gaussianity with a $p$-value of 0.049. This is a situation where an adaptive approach such as Thas’s (2010, p. 120) data driven smooth test based on Hermite polynomials could be useful. Such a test yields a $p$-value of 0.0325, which leads to rejection of the Gaussian hypothesis. However, the author is unable to derive from the test’s components any insight about what may have caused rejection. Our data driven test based on $P_{\hat{Q}(\alpha)}(\hat{\beta})$, with $S(n) = 4$ and using the same constants as previously, yields an observed value of $T_n$ of 2.64, leading to $\hat{Q}(\alpha) = 31$ with $P_{\hat{Q}(\alpha)}(\hat{\beta}) = 56.74$, to be compared to a 5% critical level of 10.47. Thus the null hypothesis of Gaussianity is here rejected at the 5% level, a conclusion enhanced by the above knowledge derived from the B-plot about the discrepancies with the model.

3.5.4 The smiling baby data revisited. Here, we revisit the smiling baby data set of Section 2.1, normalized to $[0, 1]$. The B-plot for this data with $S(n) = 4$ appears in Panel 2) of Figure 1. The B-plot associated with $S(n) = 6$ appears in Figure 3.5. To obtain more precise insights regarding some sets of adjacent bars in the B-plot, the variants of $u(n, \alpha, \{r, \ldots, s\})$ and $\ell(n, \alpha, \{r, \ldots, s\})$ adapted to a simple null hypothesis, with $\hat{C}(p_{S(n),j})$ in place of $\hat{C}(p_{S(n),j}, \hat{\beta})$ as explained in Section 3.3, could be computed. However, this is unnecessary here because all individual bars are well within $\pm 1.645$ and no reason emerges to reject uniformity anywhere.

To validate this visual assessment, we apply the test based on $P_{R(\alpha)}$ with $S(n) = 6$ and $\alpha = 0.05$. The observed value of $M_n$ is 1.59, leading to $R(\alpha) = 1$ with $P_{R(\alpha)} = 0.16$, to be compared to a 5% critical level of 133.9. Thus we clearly do not reject
the null hypothesis of uniformity at the 5\% level. This is in agreement with the AD ($p$-value $= 0.63$) and BJ ($p$-value $= 0.85$) tests.

For these data, we have $\tilde{\beta}_1 = \bar{X} = 0.50$, the median is 0.47 and $\tilde{\beta}_2 = S = 0.26$. From these values, one may wonder whether tests tailored to detect a shift to the left of the median or a smaller dispersion would improve on the above general-purpose GoF procedures, i.e. AD and BJ. The one-sided signed rank test yields a $p$-value of 0.45 while the one-sided Brown-Forsythe test has a $p$-value of 0.15. These extra results further support the claim of previous authors (see Bhattacharjee & Mukhopadhyay, 2013) that this data could well be uniformly distributed.

4. Discussion

The present work proposes an approach for model validation based on the pair (B-plot, $P_{R(\alpha)}$) or (B-plot, $P_{Q(\alpha)}(\tilde{\beta})$) that appears to be a good compromise to the two routes presented in the Introduction. In the case of a Gaussian null model, with known as well as unknown parameters, our test statistics are powerwise competitive with some of the best solutions proposed in the literature, while the B-plot and related acceptance regions offer an enhanced assessment, with respect to PP or QQ plots, as to where the data deviate from the contemplated model. The technical details here are confined to the Gaussian null model. But existing evidence and earlier experience allows to expect that our approach can be extended to other nonparametric problems, general location-scale families and several more complex models. In particular, other $\sqrt{n}$-consistent estimators than the MLE could be covered by adjusting the CC curve, the test statistic and the data driven selection procedure. For illustration of different situations where data driven smooth tests, using other systems of functions than the present $\{h_{s,j}(\cdot)\}$, work well see Kallenberg & Ledwina (1999), Peña (2003), Ducharme & Fontez (2004), Ducharme & Lafaye de Micheaux (2004, 2020), Inglot & Ledwina (2006), Bissantz, Claeskens, Holzmann & Munk (2009), Escanciano & Lobato (2009), Janic & Ledwina (2009), Wang & Qu (2009), Wyłupek (2010, 2021) and Thas, Rayner & de Neve (2015). However, it should be noted that in such situations, the constructions are more involved as a rule and additional technical work is needed. In return, both empirical and theoretical
studies show that well-calibrated data driven tests are only slightly less powerful
than classical solutions applied in their most favourable situations, while otherwise
having unrivalled sensitivity to a large spectrum of important alternatives.

We emphasize that the main motivation for this work is to propose an approach
that can help in understanding the structure of the data at hand, to allow investigat-
ing why a null hypothesis has been rejected, to detect and describe some local
discrepancies, and to provide some evidence in which sense and how reliable such
an approach can be. In particular, we consider such endeavors as useful additions
that better enshrine the modeling process in a more constructive iterative loop,
as pointed out in the first paragraph of the present Introduction. We confine our
work here to the case of classical goodness of fit testing but note that questions of
this kind are increasingly discussed in recent literature on several different testing
problems. For an illustration see Kim et al. (2019), Zhang (2019), Algeri (2021),
Xiang et al. (2023) and the references therein.

In Sections 2.5 and 3, we have qualified our alternatives, comprising a range of
shape of CC’s, as “carefully” selected. In many simulation studies about the empir-
ical power of GoF tests, the alternatives are taken among broad categories such as
symmetric, asymmetric, etc., often building up on previous simulations by adding
some new “interesting” alternatives. In addition, in summarizing their results, many
authors base their final recommendations on some averaging of the obtained powers
over the alternatives investigated. However, such categories are mostly related to
shape of densities, which may not be well adapted to departures related to other
characteristics that some GoF tests can detect with greater power than density dif-
ferences. Thus such averaging can introduce bias in these recommendations, which
are often of the form “this test is good at detecting such type of departures” with, in
many cases, departures pertaining to asymmetry and large or short tails. However,
at the beginning of the modelling process, a user has often limited knowledge about
the plausible alternatives to the null model. Hence such recommendations are of
little help in choosing a GoF test appropriate to his problem and this will often
lead to the use of a test based solely on its popularity. This is not good science.
Here, examination of the B-plot, as in the examples of Section 3.5, allows acquiring
such knowledge and decide whether one can use with some confidence a classical
solution or would be better off going through the trouble of considering a much
more computationally expensive data driven test, as the ones of the present work.

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Appendix A. More real data examples

This appendix contains details regarding three examples that show the information that can derive from the tools of the paper.

A.1. The wave record data revisited. The B-plots in Section 3.5 are expressed as functions of the quantiles \( p \). A variant B-plot can be produced that relates more directly to the original data. To this end, set

\[
\tilde{q}_{s,j} = \tilde{q}_{s,j}(p_{s,j}) = \beta_2 \Phi^{-1}(p_{s,j}) + \beta_1,
\]

which represents the estimated \( p_{s,j} \) quantile of the null distribution. With this notation, set

\[
\tilde{F}_n(\tilde{q}_{s,j}) = \frac{\Phi((\tilde{q}_{s,j} - \tilde{\beta}_1)/\beta_2) - \hat{F}_n(\tilde{q}_{s,j})}{\sigma_{s,j}} = \frac{p_{s,j} - \hat{F}_n(\beta_2 \Phi^{-1}(p_{s,j}) + \beta_1)}{\sigma_{s,j}},
\]

where \( \hat{F}_n(\cdot) \) is the ordinary empirical CDF of the sample. Given \( s \), this variant of the B-plot, noted \( B_{\tilde{q}} \)-plot, is obtained by plotting the \( \tilde{C}\tilde{C}(\tilde{q}_{s,j}; \tilde{\beta}) \) against the estimated quantiles \( \tilde{q}_{s,j} \) with \( j \in \{1, \ldots, d(s)\} \). Figure A.1 shows such a graph for the wave data of Section 3.5.1 with \( S(n) = 5 \) and the related acceptance regions. In particular, one can see that the seven data points greater than \( \tilde{q}_{5,58} = 6.9 \) are more dispersed to the right than expected under the null hypothesis.

![B\_q-plot for Wave data : S(n) = 5](image)

**Figure A.1.** \( B_{\tilde{q}} \)-plot of the values of \( n^{1/2} \tilde{C}\tilde{C}(\tilde{q}_{6,j}; \tilde{\beta}) \) plotted against the estimated quantiles \( \tilde{q}_{6,j} \) with \( j \in \{1, \ldots, 63\} \), for the wave records data \( (n = 66) \) in Bickel & Doksum (1977). The dashed grey lines are located at \( \pm 1.645 \) to identify an individual bar where some dissonance with H: Gaussianity occurs at one-sided level 5%. The shaded grey stripes are the simultaneous 95% one-sided acceptance regions for subsets of bars \( \{1, \ldots, 6\}, \{30, \ldots, 42\} \) and \( \{58, \ldots, 63\} \).
A.2. **The open/closed book examination data.** Consider the open book/closed book examination data set in Mardia, Kent & Bibby (1979) pp. 3–4, which gives the marks of a group of $n = 88$ students in Mechanics, Vectors, Algebra, Analysis, and Statistics. The marks in Statistics, Vectors and Analysis were analyzed in Ducharme & Lafaye de Micheaux (2020) who rejected a trivariate multinormal distribution. Here we revisit the marks for Analysis.

For this data set, we have $\tilde{\beta}_1 = \bar{X} = 46.68$ and $\tilde{\beta}_2 = S = 14.76$. We have applied the test based on $P_{Q(\alpha)}(\tilde{\beta})$ with $S(n) = 4$ and $\alpha = 0.05$. The observed value of $T_n$ is 5.15, leading to $Q(\alpha) = 31$ with $P_{Q(\alpha)}(\tilde{\beta}) = 155.12$, to be compared to a 5% critical level of 10.44, interpolated from Table B.3 in Appendix B. Thus we reject the null hypothesis of Gaussianity at the 5% level. The $p$-values for AD, SW, BCMR are 0.0001 for AD, 0.0001 for SW and 0.001 for BCMR. Thus these tests also reject the Gaussian model at level 5%.

![Figure A.2. B-plot of $n^{1/2} \bar{C}(p_{S(n), j}; \tilde{\beta})$ with $S(n) = 4$ and $S(n) = 6$ for the marks in analysis in the open/closed book data ($n = 88$) from Mardia, Kent & Bibby (1979). The dashed grey lines are located at $\pm 1.645$ to identify a bar where dissonance with $H_0$: Gaussianity occurs. The shaded grey stripes are the simultaneous 95% one-sided acceptance regions for subsets of bars in the first and last deciles and the slightly decentred central part $p \in (0.38, 0.56)$.](image-url)

On the B-plot of Figure A.2, the left tail of the distribution seems heavier than the Gaussian, while the right one could be thinner, thus indicating some asymmetry to the right of the distribution with less mass at the centre. We find for $S(n) = 4$, $\ell(88, 0.05; \{1, 2, 3\}) = -2.21$, $\ell(88, 0.05; \{29, 30, 31\}) = -1.92$ and, for similar reasons as in Section 3.5, the slightly decentred (to the left) $u(88, 0.05; \{12, \ldots, 18\}) = 2.21$. After drawing the related acceptance regions, we can observe that, in all regions, at least one bar goes beyond these acceptance regions, thus supporting the above claims.
A.3. The cystine data. Consider the cystine content of grade 5 yellow corn. The data \(n = 106\) appear in Gan, Koehler & Thompson (1991). In their work they use graphical methods to infer, from the shape of the PP plot, that the Gaussian distribution does not provide an adequate model. However after several attempts, they conclude that no other model they have investigated leads to a clearly better alternative to the Gaussian.

For this data set, we have \(\hat{\beta}_1 = \bar{X} = 0.09\) and \(\hat{\beta}_2 = S = 0.014\). We apply the test based on \(P_{\overline{Q}(\alpha)}(\hat{\beta})\) with \(S(n) = 4\) and \(\alpha = 0.05\). The observed value of \(T_n\) is 4.20, leading to \(\overline{Q}(\alpha) = 31\) with \(P_{\overline{Q}(\alpha)}(\hat{\beta}) = 118.52\) to be compared to a 5% critical level of 10.42. Thus the null hypothesis of Gaussianity is rejected at the 5% level. The tests AD, SW and BCMR similarly reject at the level of 10.42. Thus the null hypothesis of Gaussianity is rejected at the level of 0.0001, SW : 0.003 and BCMR : 0.005.

\[Cystine : S(n) = 4\]

\[Cystine : S(n) = 6\]

Figure A.3. B-plot of the values of \(n^{1/2}\widehat{CC}(P_{S(n); j} ; \hat{\beta})\) with \(S(n) = 4\) and \(S(n) = 6\) for the cystine data \(n = 106\) from Gan, Koehler & Thompson (1991). The dashed grey lines are located at \(\pm 1.645\) to identify a bar where dissonance with \(H_0: \text{Gaussianity}\) occurs. The shaded grey rectangles are the two-sided acceptance regions for the subsets of bars in the first and last decile and the middle tier of the distribution.

In view of the limited previous information regarding this data set, and to obtain some insights about the type of departures from Gaussianity suggested by the data, it may appear appropriate to consider two-sided acceptance regions for a few subsets of bars in the B-plots. Here we consider the subsets of bars in the first and last decile (the tails) and the middle tier of the distribution. B-plots of the \(n^{1/2}\widehat{CC}(P_{S(n); j} ; \hat{\beta})\) for \(S(n) = 4\) and \(S(n) = 6\), along with the \(\pm 1.645\) critical values (see Figure A.3) suggest a left tail thinner than the Gaussian but a right tail more consonant with the Gaussian. For \(S(n) = 4\) (resp. \(S(n) = 6\)) we get \(\ell(106, 0.025; \{1, 2, 3\}) = -2.65\) (resp. \(-2.70\) using \(J = \{1, \ldots, 12\}\)) and \(u(106, 0.025; \{1, 2, 3\}) = 2.20\) (resp. \(-2.49\)), supporting the claim about the left tail. For the right tail, we find \(\ell(106, 0.025; \{29, 30, 31\}) = -2.19\) (resp. \(-2.48\) using \(J = \{116, \ldots, 127\}\)) and \(u(106, 0.025; \{29, 30, 31\}) = 2.65\) (resp. \(2.77\)) and no discrepancy seems to occur there. As for the central tier part, we consider the quantiles in the range \(0.33 \approx 11/32 \leq p \leq 21/32 \approx 0.66\) and compute \(\ell(106, 0.025; \{11, \ldots, 21\}) = -2.66\) (resp. \(-2.82\) using \(J = \{44, \ldots, 84\}\)), \(u(106, 0.025; \{11, \ldots, 21\}) = 2.65\) (resp. \(2.81\)). The data seems indeed more abundant in this region.
Appendix B. Details and recommendations on the implementation of our tools

The practical implementation of our tests requires the choice of $S(n)$ and, depending on whether $\beta$ is known (the case of $H_0$ of Section 2) or must be estimated (the case of $H : \Phi((x - \beta_1)/\beta_2)$ of Section 3.4), the computation of $a(n, \alpha)$ or $a(n, \alpha; \tilde{\beta})$. In addition, our tests require the values $m(n, \alpha)$ or $t(n, \alpha)$ for the oracles $M_{D(n)}$ or $T_n$ as well as the critical values $c(n, \alpha)$ for $P_{R(\alpha)}$ or $c(n, \alpha)$ for $P_{Q(\alpha)}(\tilde{\beta})$.

Here we give some details about these values for the cases where $4 \leq S(n) \leq 6$ and for values of $n$ in the range $50, \ldots, 500$, which should cover many situations encountered in practice. Linear interpolations can be used in between entries of the tables.

The values of $a(n, \alpha)$ and $a(n, \alpha; \tilde{\beta})$ are rather stable as functions of $n$. In particular, one can take $a(n, 0.1) = 2.59$, $a(n, 0.05) = 3.31$ while $a(n, 0.10; \tilde{\beta}) = 2.53$ and $a(n, 0.05; \tilde{\beta}) = 3.18$. Some values of $m(n, \alpha)$ and $t(n, \alpha)$ appear in Tables B.1 and B.2.

| $n$ | $\alpha$ | $S(n)$ |
|-----|---------|--------|
|     |         | 4      | 5      | 6      |
| 50  | 10%     | 2.77   | 2.79   | 2.93   |
|     | 5%      | 2.89   | 3.14   | 3.43   |
| 100 | 10%     | 2.64   | 2.79   | 2.88   |
|     | 5%      | 2.92   | 3.14   | 3.30   |
| 150 | 10%     | 2.61   | 2.78   | 2.92   |
|     | 5%      | 2.96   | 3.07   | 3.20   |
| 300 | 10%     | 2.78   | 2.97   | 3.04   |
|     | 5%      | 3.04   | 3.19   | 3.32   |
| 500 | 10%     | 2.83   | 2.93   | 3.05   |
|     | 5%      | 3.04   | 3.18   | 3.29   |

Table B.1. Some critical values $m(n, \alpha)$ of $M_{D(n)}$ in computing $P_{R(\alpha)}$ for $H_0 : \Phi(\cdot)$ (simple null hypothesis)

| $\alpha/n$ | 50   | 100  | 150  | 300  | 500  |
|------------|-----|------|------|------|------|
| 0.10       | 2.15| 2.33 | 2.42 | 2.57 | 2.67 |
| 0.05       | 2.52| 2.73 | 2.83 | 3.00 | 3.10 |

Table B.2. Some critical values of test statistic $T_n$ for $H : \Phi((x - \beta_1)/\beta_2)$ (unknown parameters)

The computation of critical values $c(n, \alpha)$ for $P_{R(\alpha)}$ is rather straightforward and one can get a good approximation with 25 000 Monte Carlo replications. Such a number is required because this test statistic has a distribution with a discrete component. Table B.3 lists some critical values $c(n, \alpha)$ for $P_{Q(\alpha)}(\tilde{\beta})$. Using these leads to probabilities of a type 1 error very close to the nominal 5% and 10%.
Table B.3. Some critical values of $\tilde{c}(n, \alpha)$ for testing $H_0 : \Phi((x - \beta_1)/\beta_2)$ (unknown parameters) with test statistic $P_{R(\alpha)}(\tilde{\beta})$

| $n$ | $\alpha$ | 4   | 5   | 6   |
|-----|----------|-----|-----|-----|
| 50  | 10%      | 7.96| 8.43| 8.43|
|     | 5%       | 10.48| 10.79| 10.86|
| 100 | 10%      | 8.10| 8.29| 8.31|
|     | 5%       | 10.43| 10.67| 10.70|
| 150 | 10%      | 8.11| 8.32| 8.39|
|     | 5%       | 10.33| 10.46| 10.57|
| 300 | 10%      | 7.88| 8.07| 8.15|
|     | 5%       | 10.01| 10.18| 10.24|
| 500 | 10%      | 7.78| 7.94| 7.95|
|     | 5%       | 9.71| 9.88| 9.92|

One must generally be careful when using GoF tests involving an oracle. Such a construction creates a null distribution which is a complex mixture of two components: one when the oracle accepts and another one when it rejects. Regarding statistic $P_{R(\alpha)}$, this mixture distribution is steep enough so that no difficulty occurs in computing its $\alpha$-th critical values in the range of conditions we have investigated.

However, the null CDF of the counterpart $P_{\tilde{R}(\alpha)}(\tilde{\beta})$ of $P_{R(\alpha)}$ is approximately $1 - \alpha$ for a large set of values. This creates instability in computing its $\alpha$-th critical value, which must be resolved by using over two million MC replications, a serious defect of the procedure. The use here of $P_{\tilde{Q}(\alpha)}(\tilde{\beta})$, with the penalty $A(1.5; \tilde{\beta})$, slightly less than the Akaike $A(2; \tilde{\beta})$, provides a null distribution where the required critical values are easier to approximate: if necessary, these can be obtained with as little as 25,000 replications for $\alpha = 0.10$ and 0.05.

With a simple null hypothesis as in Section 2, the power of the oracle $\mathcal{M}_{D(n)}$ increases with $S(n)$ and this in turn affects favourably the power of $P_{R(\alpha)}$. As a consequence, we recommend using a large value, e.g. $S(n) = 6$, as in the simulations of Section 2.5 and the smiling baby data of Section 3.5.4. However, in the context of a composite null hypothesis, the oracle BCMR is not affected by this choice, and this reflects on the powers of $P_{\tilde{Q}(\alpha)}(\tilde{\beta})$ which are rather stable as a function of $S(n)$. Hence a small value can be used for the GoF test and here we have taken $S(n) = 4$. However, to extract useful insight from a B-plot, we recommend first computing the simultaneous acceptance regions with $S(n) = 4$ and, if necessary, use $S(n) = 6$ to get a richer picture, as we have done in the examples of Section 3.5 and Appendix A.

Appendix C. The simulation experiment for a composite Gaussian null hypothesis and related comments

In this appendix, we describe the setting and results of the simulation experiment discussed in Section 3.4. Note beforehand that all computations and simulations in the present paper, both in the previous sections and the present appendices, were performed using the Mathematica language (Wolfram Research, Inc., Mathematica, Version 12.1, Champaign, IL, 2020) and the random number generators in the program. Note also that the calculation of test statistic $P_{R(\alpha)}$ and $P_{\tilde{Q}(\alpha)}(\tilde{\beta})$ is rather quick. For example, with $S(n) = 6$ and $n = 500$, our test statistics are computed in about 0.10 second on a MacBook Pro M2 running MacOS Ventura.
13.2.1. Associated computational efforts are necessary in the computation of \( \beta \)
for example, the approximation of any \( u(n,\alpha;\{r,\ldots,s\}) \) or \( \ell(n,\alpha;\{r,\ldots,s\}) \) when \( S(n) = 4 \) and \( n = 100 \), based on a reasonable 10 000 replications, requires less than two minutes. Thus the computational effort to use the statistics of the paper in practice can be considered marginal.

We recall that the null hypothesis is the composite \( H : F(x) = \Phi((x - \beta_1)/\beta_2) \), i.e. we consider testing GoF to the Gaussian distribution. We estimate \( \beta \) by the MLE \( \hat{\beta} = (X, S^2) \), so that \( \beta_1(F), \beta_2(F) \) are the mean and variance of \( F(\cdot) \).

The alternatives were selected from some extensive simulation studies and chosen with care to cover a fair range of shapes (see Figure C.1) of CC(\( \cdot; \beta(F) \)) while embedding, either exactly or approximately, the Gaussian distribution. They are:

- \( A_3(\theta) \), the Tukey distributions with quantile function \( \theta^{-1}(q - (1 - q)^\theta) \) if \( \theta \neq 0 \) and \( \log(q/(1 - q)) \) when \( \theta = 0 \); these are symmetric about 0 unimodal distributions having support \([-1/\theta, 1/\theta]\), if \( \theta > 0 \) and \( \mathbb{R} \) otherwise; \( A_3(0.14) \) is close to a \( N(0,2.142) \), see Pearson, D’agostino & Bowman (1977);
- \( A_2(\theta) \), normal distributions perturbed by cosine functions with densities \( \phi(x) \{1 + \theta \cos(4\pi \Phi(x))\} \), \( \theta \in [0,1] \) on \( \mathbb{R} \) which for \( \theta > 0.3 \) are visually clearly trimodal, see Inglo, Jurlewicz & Ledwina (1990); the case \( \theta = 0 \) yields the \( N(0,1) \);
- \( A_3(\theta) = A_3^\circ(\theta) \), the two-piece normal distributions of Section 2.5; these asymmetric distributions have a left tail proportional to a Gaussian, a fat right tail when \( \theta > 1 \) and a short one otherwise (see Experiment \( C_2 \) in Boero, Smith & Wallis (2004); for some history about this distribution, see Wallis (2014));
- \( A_4(\theta) = A_4^\circ(\theta) \), the Fan local model defined in Section 2.5; these densities are asymmetric, bimodal and their tails coincide with those of the \( N(0,1) \) which is \( A_4(0) \) (see Example 5 in Fan, 1996);
- \( A_5(\theta) = A_5^\circ(\theta) \), the normal contamination model defined in Section 2.5; the case \( \theta = 0 \) yields the \( N(0,1) \); see Pearson, D’agostino & Bowman (1977);
- \( A_6(\theta) = A_6^\circ(\theta) \), Anderson’s skewed distribution of Section 2.5 the case \( \theta = 0 \) yields the \( N(0,1) \) (see Experiment \( C_3 \) in Boero, Smith & Wallis, 2004);
- \( A_7(\theta) = A_7^\circ(\theta) \), the Mason & Schuenemeyer (1983) symmetric about zero distribution with CDF \( J(\Phi(x),0.15,\theta) \); the case \( \theta = 0 \) yields the \( N(0,1) \) (see Ćmiel, Inglo & Ledwina, 2020);
- \( A_8(\theta) \), Johnson’s SU distributions, with \( X = \sinh(Z/\theta) \), \( \theta > 0 \) and \( Z \sim N(0,1) \), yielding symmetric about zero and unimodal densities; \( A_8(3.5) \) is approximately \( N(0,0.22) \), see Pearson, D’agostino & Bowman (1977);
- \( A_9(\theta) = A_9^\circ(\theta) \), the Lehmann contamination model from Section 2.5, a contamination model skewed to the left with \( A_9(0) = N(0,1) \) (see Ćmiel, Inglo & Ledwina, 2020);
- \( A_{10}(\theta) \), the Lehmann model with CDF \( (\Phi(x))^{\theta} \); of course the case \( \theta = 1 \) yields the \( N(0,1) \) and here we take \( 0 < \theta \leq 1 \);
- \( A_{11}(\theta) \), the generalized error distribution (GED) with density proportional to \( \exp(-|x|^\theta/\theta) \); the case \( \theta = 2 \) yields the \( N(0,1) \) and here we consider \( \theta \leq 2 \);
- \( A_{12}(\theta) \), a symmetric Pareto contamination model with CDF given by \( (1 - \theta)N(0,1) + \theta \Pi(5) \), where \( \Pi(\delta) \) is the symmetric Pareto distribution (see model \( M_2^\circ \) in Ćmiel, Inglo & Ledwina, 2020).

Additionally, alternative \( A_6^\circ(\theta) \) in the simulation of Section 2.5 has been extensively used in Experiment \( D_2 \) of Boero, Smith & Wallis (2004).

As competitors to \( \mathcal{P}_{Q(x)}(\hat{\beta}) \), we have considered the following tests:

- the Anderson-Darling (AD) test adjusted for unknown parameters;
• the Shapiro-Wilk (SW) test;
• the del Barrio, Cuesta-Albertos, Matran & Rodríguez (1999) test BCMR.
• at the reviewer’s request, the data driven smooth test of Janic & Ledwina
  (2009) with test statistic $W_{S1}(\tilde{\beta}[ns])$.

We recall that our main focus here pertains to the interpretation of the new
components, provided the related test statistic $P_{Q(1)}(\tilde{\beta})$ exhibits a generally good
behavior, as we now show.

---

**Figure C.1.** 
$CC(\cdot; \beta(F))$ (solid red) for the alternative distributions in Table C.2 for testing the composite null hypothesis
$\Phi((x - \beta_1)/\beta_2)$ with $(\beta_1, \beta_2)$ unknown. The black dotted curve represents $CC(\cdot)$ of (2.1) corresponding to the simple null model $\Phi(x)$.

Taking $\alpha = 0.05$ and $n = 100$, we have investigated $P_{Q(1)}(\tilde{\beta})$ with the del Barrio,
Cuesta-Albertos, Matran & Rodríguez (1999) BCMR oracle test using $S(n) = 4$;
this yields $a(n, 0.05; \beta) = 3.18$, see Appendix B. The power functions for the twelve
alternatives were simulated in their $\theta$ range for each of the tests $M_{D(n)}(\tilde{\beta})$ of (15)
with $D(n) = 31$ and $D(n) = 127$, AD, SW, BCMR, $W_{S1}(\tilde{\beta}[ns])$ and $P_{Q(1)}(\tilde{\beta})$. The
5% critical value for each test was obtained from 100 000 replications under the null
distribution, while the powers were computed from 10 000 Monte Carlo runs. As in
Section 2.5, we extracted from each power curve one representative value of $\theta$ which
provided interesting powers. As a result of these choices, the obtained powers give
a comprehensive view of the comparative behaviour of the above tests in a wide
range of situations. The results are reported in Table C.2 along the selected value of $\theta$ and roughly sorted from thin to fat-tailed. As can be seen, none of the other
is the case for the Fan alternative (forms of the CC are sometimes almost imperceptible at the level of densities. This having finite fourth moment. Also, it should be stated that large differences in the impact the estimation process has on the CC going from a simple to a composite null model. It is interesting to see the strong impact the estimation process has on the CC is modified from (1) to (11) in which the denominator is different while additionally, is composite, the reference CDF for the same cases where CC is difficult to predict without such additional insight. Figure C.1 exhibits more that the required √n-consistency of the MLE of β implies a substantial restriction on the allowable class of alternatives F(·) to those having finite fourth moment. Also, it should be stated that large differences in the forms of the CC are sometimes almost imperceptible at the level of densities. This is the case for the Fan alternative (A2(0.4) and A4(0.4)). Finally, going from the

| Alternative | $\mathcal{M}_{127}(\beta)$ | $\mathcal{M}_{127}(\tilde{\beta})$ | AD | SW | BCMR | $W^*_3(\tilde{\beta}[ns])$ | $P_{Q(\alpha)}(\tilde{\beta})$ |
|-------------|-----------------------------|-------------------------------|----|----|------|------------------------------|------------------|
| A1(3.0)     | 42                          | 38                            | 47 | 74 | 70   | 59                           | 68               |
| A2(0.7)     | 64                          | 60                            | 75 | 40 | 41   | 57                           | 57               |
| A3(-0.5)    | 27                          | 29                            | 43 | 46 | 47   | 46                           | 45               |
| A4(0.4)     | 82                          | 80                            | 78 | 43 | 45   | 39                           | 65               |
| A5(0.15)    | 17                          | 17                            | 28 | 29 | 30   | 26                           | 28               |
| A6(0.3)     | 58                          | 58                            | 73 | 68 | 70   | 64                           | 69               |
| A7(2.0)     | 47                          | 44                            | 56 | 47 | 51   | 60                           | 56               |
| A8(1.6)     | 34                          | 34                            | 47 | 55 | 58   | 61                           | 53               |
| A9(0.1)     | 53                          | 55                            | 68 | 80 | 82   | 80                           | 75               |
| A10(0.025)  | 27                          | 28                            | 43 | 57 | 55   | 47                           | 50               |
| A11(1.2)    | 39                          | 37                            | 54 | 54 | 56   | 60                           | 56               |
| A12(0.25)   | 77                          | 74                            | 71 | 58 | 56   | 63                           | 66               |

Table C.2. Powers (n = 100, α = 0.05) of $\mathcal{M}_{D(n)}(\tilde{\beta})$ of (15) with $D(n) = 31$ and $D(n) = 127$, the Anderson-Darling (AD), the Shapiro-Wilks (SW), the oracle BCMR, the Janic&Ledwina (2009) test ($W^*_3(\tilde{\beta}[ns])$) and our $P_{Q(\alpha)}(\tilde{\beta})$ tests for H: $\Phi((x - \beta_1)/\beta_2)$ with $(\beta_1, \beta_2)$ unknown, against the set of alternatives $A_{11}(\theta)$ to $A_{12}(\theta)$.

tests dominates $P_{Q(\alpha)}(\tilde{\beta})$, which emerges as a good competitor over our range of alternatives.

Power comparisons between the case where $F_0(\cdot; \beta)$ is fully specified and those where $\beta$ is estimated seldom appear in the literature. Here, in addition to our concern regarding well-balanced set of alternatives, we have made the deliberate choice of selecting three alternatives in common in Tables 1 and [C.2] namely the Fan local alternative ($A_3^0$ and $A_4$), the normal contamination ($A_5^0$ and $A_5$) and the Lehmann contamination ($A_9^0$ and $A_9$). This was done to explore the difficulties in going from a simple to a composite null model. It is interesting to see the strong impact the estimation process has on the CC(·). Basically, the expression for CC(·) is modified from (1) to (11) in which the denominator is different while additionally, in (11), $\beta(F)$ plays a role. More precisely, in the case of a simple null hypothesis, $\Phi(\cdot)$ is the reference distribution to an alternative $F(\cdot)$. When the null hypothesis is composite, the reference CDF for the same $F(\cdot)$ is $\Phi((x - \beta_1(F))/\beta_2(F))$ which is now adjusted to $F(\cdot)$. The new denominator in (11) plays a strong role in the central region of (0, 1) while the standardization of $\Phi(\cdot)$ via the use of $\beta(F)$ affects the tails of the reference distribution and thus plays an essential role for $p$ close to 0 and 1.

For the three alternatives in common, Figure C.1 shows that pairs of CC(·) and CC(·; $\beta(F)$) can be very different and this affects the powers in a way that is difficult to predict without such additional insight. Figure C.1 exhibits more cases where CC(·) and the associated CC(·; $\beta(F)$) are rather different, e.g. $A_1$, $A_3$, $A_7$ and $A_{10}$, with the selected parameter $\theta$. In particular, it can be noticed that the estimation of $\beta$ strongly affects the related shape of CC(·; $\beta(F)$) in the case of relatively heavy-tailed alternatives, as then the pertaining $\beta_2(F)$ is often large. It should also be remembered that the required √n-consistency of the MLE of $\beta$ implies a substantial restriction on the allowable class of alternatives $F(\cdot)$ to those having finite fourth moment. Also, it should be stated that large differences in the forms of the CC are sometimes almost imperceptible at the level of densities. This is the case for the Fan alternative ($A_4^0(0.4)$ and $A_4(0.4)$). Finally, going from the
simple null hypothesis to a composite one, the selection rule had to be adapted in an intricate way to preserve the good properties of our procedures.

Hence, it can be concluded that the case of unknown parameters is a problem whose complexity is of an order of magnitude above the fully specified case.

APPENDIX D. PROOFS

D.1. Proof of Proposition 1. We have that \( \hat{F}_n(F_0^{-1}(p_{s,j})) = n^{-1} \sum_{i=1}^n I(F_0(X_i) \leq p_{s,j}) \) where \( F_0(X_i) \) are i.i.d. \( U(0,1) \) under \( \mathbb{H}_0 \). Let \( \alpha_n(t), \ t \in [0,1] \), denote the uniform empirical process. Then it holds that

\[
\mathcal{M}_{D(n)} = \max_{1 \leq j \leq D(n)} \left| \alpha_n(p_{S(n),j}) \right| \bigg/ (p_{S(n),j}(1 - p_{S(n),j}))^{1/2}.
\]

Because \( D(n) = o(n^{2\delta}), \ \delta \in (0,1/2) \), for sufficiently large \( n \) we get \( p_{S(n),1} \geq \epsilon_n = [\log n]^3/n \). Moreover, for the quantity

\[
\sup_{\epsilon_n \leq t \leq 1 - \epsilon_n} \frac{|\alpha_n(t)|}{(t(1-t))^{1/2}},
\]

the Darling-Erdős theorem holds, see Jaeschke (1979). This implies that

\[
(MD(n)) = O_P((\log \log n)^{1/2}).
\]

Let \( c(n, \alpha) \) denote the \( \alpha \)-th critical value of \( \mathcal{P}_{R(\alpha)} \). On the set \{ \( \mathcal{M}_{D(n)} > m(n, \alpha) \) \}, the value of \( \mathcal{P}_{R(\alpha)} \) is equal to \( \mathcal{P}_{D(n)} \). Moreover, it holds that

\[
\text{pr}(\mathcal{P}_{R(\alpha)} \geq c(n, \alpha)) = \text{pr}(\mathcal{P}_{R(\alpha)} \geq c(n, \alpha) \mid \mathcal{M}_{D(n)} \leq m(n, \alpha))
\]

\[
\times \text{pr}(\mathcal{M}_{D(n)} \leq m(n, \alpha)) + \text{pr}(\mathcal{P}_{D(n)} \geq c(n, \alpha))
\]

\[
- \text{pr}(\mathcal{P}_{D(n)} \geq c(n, \alpha), \mathcal{M}_{D(n)} \leq m(n, \alpha)).
\]

Hence, it is enough to show that, under \( F(\cdot) \), the test rejecting for large values of \( \mathcal{M}_{D(n)} \) is consistent and \( \text{pr}(\mathcal{P}_{D(n)} \geq c(n, \alpha)) \rightarrow 1 \) as \( n \rightarrow \infty \).

We start by showing that, under \( F(\cdot) \), the test rejecting for large values of \( \mathcal{M}_{D(n)} \) is consistent. By \( D(n) \), \( m(n, \alpha) \) cannot grow faster than \( O((\log \log n)^{1/2}) \). On the other hand, using the definition of \( (s_0, j_0) \), we have for \( n \) large enough

\[
\text{pr}(\mathcal{M}_{D(n)} > m(n, \alpha)) = \text{pr}(\max_{1 \leq j \leq D(n)} |n^{1/2} \gamma_{j,n}(p_{s,j})| > m(n, \alpha))
\]

\[
\geq \text{pr}(n^{1/2} \gamma_{j,n}(p_{s_0,j_0}) > m(n, \alpha))
\]

\[
= \text{pr}\left(\left|\frac{n^{1/2}(\gamma_{j,n}(p_{s_0,j_0}) - V_n)}{V_n}\right| > m(n, \alpha)\right).
\]

where

\[
V_n = \frac{n^{1/2}F_n(F_0^{-1}(p_{s_0,j_0})) - F_0^{-1}(p_{s_0,j_0}))^{1/2}}{(1 - p_{s_0,j_0})^{1/2}}.
\]

while \( \gamma_{j,n}(p_{s_0,j_0}) = \gamma_{s_0,j_0} \) is defined in (4). The numerator in the formula for \( V_n \) is \( O_P(1) \) while the denominator’s impact onto \( V_n \) is at most of the order \((D(n))^{-1/2} \).

Due to the assumption on \( D(n) \), the term \( V_n \) is \( o_P(n^{\delta}) \), \( \delta \in (0,1/2) \). Hence, in view of (D.2) and the range of \( m(n, \alpha) \), we conclude that under \( F(\cdot) \), \( \text{pr}(\mathcal{M}_{D(n)} > m(n, \alpha)) \rightarrow 1 \).

Now we show convergence of \( \text{pr}(\mathcal{P}_{D(n)} \geq c(n, \alpha)) \rightarrow 1 \). Because \( \mathcal{P}_{R(n)} \leq \mathcal{P}_{D(n)} \leq D(n) \times O_P(\log \log n) \), then \( c(n, \alpha) = o(n^{2\delta} \times \log \log n) \). Similarly as in the case of \( \mathcal{M}_{D(n)} \), we can write

\[
\text{pr}(\mathcal{P}_{D(n)} \geq c(n, \alpha)) \geq \text{pr}(n^{1/2} |\gamma_{j,n}(p_{s_0,j_0})| \geq c(n, \alpha)^{1/2})
\]

\[
= \text{pr}\left(\left|\frac{n^{1/2}(\gamma_{j,n}(p_{s_0,j_0}) - V_n)}{V_n}\right| \geq c(n, \alpha)^{1/2}\right).
\]
D.2. Proof of Proposition 2. We start by reducing the consistency problem. Let $\tilde{c}(n, \alpha)$ denote the $\alpha$–th critical value of $\mathcal{P}_{Q(\alpha)}(\tilde{\beta})$. In the sequel, all probabilities are computed under $F(\cdot)$. Then,

$$\Pr(\mathcal{P}_{Q(\alpha)}(\tilde{\beta}) \geq \tilde{c}(n, \alpha)) = \Pr(\mathcal{P}_{Q(\alpha)}(\tilde{\beta}) \geq \tilde{c}(n, \alpha) | T_n \leq t(n, \alpha))$$

$$\times \Pr(T_n \leq t(n, \alpha))$$

$$+ \Pr(\mathcal{P}_{Q(\alpha)}(\tilde{\beta}) \geq \tilde{c}(n, \alpha) | T_n > t(n, \alpha))$$

$$\times \Pr(T_n > t(n, \alpha)).$$

From pp.1-2 of the Supplementary Material to Ledwina and Wlupak (2015), $T_n$ is consistent under the assumption that $F(\cdot)$ possesses a finite second moment. Hence $\Pr(T_n > t(n, \alpha)) \to 1$. In view of the above, to prove that $\Pr(\mathcal{P}_{Q(\alpha)}(\tilde{\beta}) \geq \tilde{c}(n, \alpha)) \to 1$, it is enough to show that

$$\Pr(\mathcal{P}_{Q(\alpha)}(\tilde{\beta}) < \tilde{c}(n, \alpha) | T_n > t(n, \alpha)) \to 0.$$  

The next step is to get the rate of growth of $\tilde{c}(n, \alpha)$. $\mathcal{P}_{Q(\alpha)}(\tilde{\beta}) \leq \mathcal{P}_{D(n)}(\tilde{\beta}) \leq U_n$, where

$$U_n = D(n)[\max_{0 \leq p \leq 1} |p - \tilde{F}_n(\tilde{\beta}_2 F_0^{-1}(p) + \tilde{\beta}_1)|^2] \times \left[ \min_{1 \leq j \leq D(n)} \sigma^2_S(n,j) \right]^{-1}.$$ 

Under $\mathbb{H}$, the first expression in squared brackets is $O_P(1)$ by Durbin’s (1973) theorem. The second expression is $O(D(n))$. As a consequence, $U_n = O_P(D^2(n))$ and $\tilde{c}(n, \alpha)$ does not grow faster than $D^2(n)$. Hence, in view of the assumption on $D(n)$, $\tilde{c}(n, \alpha) = o(n)$.

Recall from Section 3.2 the indices $s_0$ and $j_0$ such that $\text{CC}(p_{s_0,j_0}; \beta(F)) \neq 0$. We have from (13), (14)

$$\mathcal{P}_{d(s_0)}(\tilde{\beta}) = \sum_{j=1}^{d(s_0)} \frac{p_{s_0,j} - \tilde{F}_n(\tilde{\beta}_2 F_0^{-1}(p_{s_0,j}) + \tilde{\beta}_1)}{(p_{s_0,j}(1 - p_{s_0,j}))^{1/2}} = \sum_{j=1}^{d(s_0)} \tilde{\text{CC}}(p_{s_0,j}; \tilde{\beta})^2.$$ 

Now, we show that

$$\Pr(n^{1/2}\tilde{\text{CC}}(p_{s_0,j_0}; \tilde{\beta}) \geq (\tilde{c}(n, \alpha))^{1/2}) \to 1, \quad n \to \infty.$$ 

To this end, observe that

$$n^{1/2}\tilde{\text{CC}}(p_{s_0,j_0}; \tilde{\beta}) = n^{1/2}\text{CC}(p_{s_0,j_0}; \beta(F))$$

$$+ \{W_n^{(1)}(s_0, j_0; \tilde{\beta}) + W_n^{(2)}(s_0, j_0; \tilde{\beta})\} \times [\sigma_{s_0,j_0}]^{-1},$$

where

$$W_n^{(1)}(s_0, j_0; \tilde{\beta}) = n^{1/2}\{F(\tilde{\beta}_2 F_0^{-1}(p_{s_0,j_0}) + \tilde{\beta}_1) - \tilde{F}_n(\tilde{\beta}_2 F_0^{-1}(p_{s_0,j_0}) + \tilde{\beta}_1)\},$$

while

$$W_n^{(2)}(s_0, j_0; \tilde{\beta}) = n^{1/2}\{F(\tilde{\beta}_2 F_0^{-1}(p_{s_0,j_0}) + \beta_1(F)) - F(\tilde{\beta}_2 F_0^{-1}(p_{s_0,j_0}) + \tilde{\beta}_1)\}.$$ 

The deterministic term in (D. 6) is $O(n^{1/2})$. The term $W_n^{(1)}(s_0, j_0; \tilde{\beta})$ can be majorized by $n^{1/2}\sup_{x \in \mathbb{R}} |F(x) - \tilde{F}_n(x)|$ and is thus $O_P(1)$. Using the equality

Taking into account the rate of growth of $c(n, \alpha)$, the same argument as above finishes the proof. $\square$
By boundedness of \((D. 10)\), the expression \([D. 7]\) is \(O_P(1)\). Thus, by the above, \(n^{1/2} \overline{C}(p_{s_0,j}; \beta) = O_P(n^{1/2})\). Because \(\bar{c}(n, \alpha) = o(n)\), we get \(\mathcal{P}_{d(s_0)}(\tilde{\beta}) \to \infty\).

Now,

\[
\Pr(\tilde{Q}(\alpha) < d(s_0), T_n > t(n, \alpha)) \leq \sum_{s=s_0}^{s_0-1} \Pr(\mathcal{P}_{d(s)}(\tilde{\beta}) - 1.5 \times d(s) \geq \mathcal{P}_{d(s_0)}(\tilde{\beta}) - 1.5 \times d(s_0)).
\]

For \(s < s_0\) it holds that \(\overline{C}(p_{s_0,j}; \beta(F)) = 0, (j = 1, \ldots, d(s))\). Therefore, by \([D. 5]\) to \([D. 8]\) applied to such \(s\) and related \(p_{s,j}\), we have \(\mathcal{P}_{d(s)}(\tilde{\beta}) = O_P(1)\). But it was earlier shown that \(\mathcal{P}_{d(s_0)}(\tilde{\beta}) \to \infty\) as \(n \to \infty\). It follows that \(\Pr(\tilde{Q}(\alpha) < d(s_0)) \to 0\) on the set \(\{T_n > t(n, \alpha)\}\), as \(n \to \infty\).

Getting back to \((D.3)\), we have

\[
\Pr(\mathcal{P}_{\tilde{Q}(\alpha)}(\tilde{\beta}) < \tilde{c}(n, \alpha)) = \Pr(\mathcal{P}_{\tilde{Q}(\alpha)}(\tilde{\beta}) < \tilde{c}(n, \alpha), \tilde{Q}(\alpha) < d(s_0))
\]

\[+ \sum_{s=s_0}^{D(n)} \Pr(\mathcal{P}_{\tilde{Q}(\alpha)}(\tilde{\beta}) < \tilde{c}(n, \alpha), \tilde{Q}(\alpha) = d(s)).\]

If \(\tilde{Q}(\alpha) \geq d(s_0)\), then \(\mathcal{P}_{\tilde{Q}(\alpha)}(\tilde{\beta}) \geq \mathcal{P}_{d(s_0)}(\tilde{\beta})\). Moreover, on the set \(\{T_n > t(n, \alpha)\}\), the first summand in \([D. 10]\) is \(o(1)\). By the above

\[
\Pr(\mathcal{P}_{\tilde{Q}(\alpha)}(\tilde{\beta}) < \tilde{c}(n, \alpha)) \leq o(1) + D(n) \Pr(\mathcal{P}_{d(s_0)}(\tilde{\beta}) < \tilde{c}(n, \alpha))
\]

\[
\leq o(1) + D(n) \Pr(n^{1/2} |\overline{C}(p_{s_0,j}; \beta)| \leq (\tilde{c}(n, \alpha))^{1/2}).
\]

This shows that we need to sharpen \((D.4)\) by studying the rate at which the probability appearing in \([D. 11]\) tends to 0. But in view of \([D. 5]\) to \([D. 8]\) the event \(E_n = \{n^{1/2} |\overline{C}(p_{s_0,j}; \beta)| \leq (\tilde{c}(n, \alpha))^{1/2}\}\) reads as

\[
E_n = \{n^{1/2} l_n < W_n^{(1)}(s_0, j_0, \tilde{\beta}) + W_n^{(2)}(s_0, j_0, \tilde{\beta}) < n^{1/2} u_n\},
\]

where

\[
l_n = \sigma_{s_0,j_0} \left\{-(n^{-1} \tilde{c}(n, \alpha))^{1/2} - \overline{C}(p_{s_0,j_0}; \beta(F))\right\},
\]

\[
u_n = \sigma_{s_0,j_0} \left\{(n^{-1} \tilde{c}(n, \alpha))^{1/2} - \overline{C}(p_{s_0,j_0}; \beta(F))\right\}.
\]

Because \(\tilde{c}(n, \alpha) = o(n)\), we get \(l_n = O(1)\) and \(u_n = O(1)\). If \(\overline{C}(p_{s_0,j_0}; \beta(F)) < 0\), then we can write \(\Pr(E_n) \leq \Pr(W_n^{(1)}(s_0, j_0, \tilde{\beta}) + W_n^{(2)}(s_0, j_0, \tilde{\beta}) > n^{1/2} l_n)\). Otherwise, we can consider \(\Pr(E_n) \leq \Pr(- W_n^{(1)}(s_0, j_0, \tilde{\beta}) + W_n^{(2)}(s_0, j_0, \tilde{\beta}) > n^{1/2} (-u_n))\).

Hence, the triangle inequality, the DKW inequality applied to \(W_n^{(1)}(s_0, j_0, \tilde{\beta})\) and Markov’s inequality applied to both terms of \(W_n^{(2)}(s_0, j_0, \tilde{\beta})\) appearing in \([D. 8]\) show that \(\Pr(E_n) = O(n^{-1})\). In view of the assumption \(D(n) = o(n^{1/2})\) we have \(D(n) \Pr(E_n) = o(1)\) and by \([D. 11]\), the proof is complete. \(\square\)
D.3. Proof of Remark 2. The relations (D.5)–(D.8), expressed in terms of an arbitrary $p \in [\epsilon, 1 - \epsilon]$, imply that

$$\sup_{\epsilon \leq p \leq 1 - \epsilon} n^{1/2} | \overline{CC}(p; \hat{\beta}) - CC(p; \beta(F)) | = O_P(1).$$

Hence the statement of Remark 2 follows. □

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