ONLINE OPTO-THERMO-MECHANICAL STUDIES OF ISOTACTIC POLYPROPYLENE FIBRES USING MODIFIED MULTI-MODE OPTO-THERMO-MECHANICAL STRETCHING DEVICE.

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Abstract

The hot-stage multi-mode opto-thermal stretching device attached to Pluta polarising interference microscopes used to study the online variations of the optical parameters of isotactic Polypropylene fibre as a function of the surrounding temperature. Also the variations of the birefringence profiles of isotactic Polypropylene at different stretching conditions is studied. This device allows the online examination of the chains orientation in more details at different draw ratios and surrounding temperatures. The influence of temperature on the stretched samples and necking phenomenon was investigated using the hot-stage stretching device presented in this paper. The experimental results are supported with the microinterferograms, which are given for illustration.

Introduction:

Isotactic polypropylene (iPP) is an outstanding thermoplastic polymer concerning its excellent cost/ performance ratio and high stiffness[1]. Polypropylene (PP) fibres and filaments are used in making many of products, such as ropes, cords, nets, woven bags, tents, geotextile components, nonwoven fabrics and reinforcing materials for various composites[2].

Structural deformation behaviour over a wide range of strain and temperature has been actively studied from scientific and industrial aspects for many years, i.e. spherulite deformation [3], necking behaviour [4] and ultradrawability [5]. Temperature is an effective parameter, which controls the drawing process of the polymeric fibres. During the stretching, there is a balance between two parameters: temperature and strain rate. A low drawing temperature implies little chain relaxation but, in this case, the strain rate takes low values, leading, on the contrary, to a larger chain relaxation [6]. Undrawn synthetic fibres are almost isotropic in their physical properties. Mechanical drawing enhances different properties of textile fibres. This results stronger, more birefringence fibres that are highly anisotropic [6]. Necking phenomenon is observed during the mechanical drawing of textile fibres at room temperature, which is observed to as cold-drawing.

Based on a thermo-mechanical coupling at the neck, Barenblatt proposed the modelling of a nonlinear dynamical system. Thermo-mechanical coupling means that the work done on drawing is converted into heat. Since the deformation occurs locally at the neck, the heat increases the temperature at the neck [7]. This model based on an empirical differential equation. This equation describes the relationship between the applied stress, the necking propagation velocity and the temperature at the neck.

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Faust [8] designed an Optothermal device to study the variation of the refractive index of the fibre with the variation of that of the surrounding liquid via changes in the temperature of the interferometric system. Hamza et al. [9] studied the effect of temperature (within 15-31 C) on the optical properties of Wool fibre. Hamza et al.[10] designed a hot stage attached to a multiple-beam Fizeau interferometric system to study the optical and structural properties of fibres. These studies carried out with static condition. Belal et al. [11] studied the influence of temperature on the spectral dispersion curves of refractive indices for polypropylene fibres. Hamza et al. [12] studied the influence of temperature on the mean cross-sectional area and the refractive indices of acrylic fibres. Recently, El-Dessouky [13] studied the variation of the optical and structural properties of high density polyethylene (HDPE) fibres at different temperatures.

The main task of this work is to present the online studies on the effect of temperature on the optical and structural properties of fibres. In this paper we designed and fabricated the hot-stage multi-mode opto-thermal stretching device [14] attached to Pluta polarising interference microscope. This device is used to study the online variations of the optical properties of isotactic Polypropylene fibre during the change of temperature and at different stretching conditions. This system enables the researcher to investigate the variations of the macroscopic structural properties during the stretching and/or increasing the temperature. This system also enables the researcher to investigate the effect of temperature on the necking phenomenon.

**Experimental technique:**

Sokkar et al. [14] designed a multi-mode opto-thermo mechanical stretching system to determine dynamically the mechanical, optical and structural properties of fibres. This system is designed to be coupled with the well-known Pluta polarising interference microscope. The setup of this system used in this work is shown in figure (1). This system had four action modes: longitudinal testing mode, dynamic stretching mode, one point stretching mode [14] and thermo-mechanical mode.

In this paper we are concerning with the last mode. This mode of operation helps to detect the structural variations of fibres at elevated temperature. This is done with the help of a heater attached to the stretching device. A temperature controller is connected to the heater to allow controlling the surrounding temperature. At this mode of operation, the multi-mode opto-thermo-mechanical stretching device [14] is configured to study the effect of varying the temperature on the optical and structural properties during different stretching processes. This allowed us to investigate the effect of increasing the temperature on polymeric fibres and also on the necking phenomenon formed during the stretching of these fibres.

**Software configuration:**

To carry out the above two targets, put both motors $W_1$ and $W_2$ to the same frequency and same total number of steps but let them to run in opposite directions as illustrated in operation of one point stretching mode. With no motion of motors while the thin heater is switched on and the CCD camera too, the camera will record changes of fringe shift of particular section through the continuous increase of temperature. In order to detect the stretching behaviour of certain fibre section at higher temperatures, connect the heater to a thermostatic controller and set the temperature to a selected value, as the temperature reaches this value and fixed then let motors to run as well as the camera. The recorded clip represents the stretching behaviour of the fibre's material at the selected temperature. This process can be repeated at another selected temperature and another fibre sample.

**Calculations:**

The main task, in the case of detecting the refractive index profile at elevated temperature, is the matching between recorded temperature and the recorded video frames. To do this match, the temperature rising as function of time should recorded initially and then presented graphically. The recorded video clip is then decomposed into frames; each frame is characterized by the moment of capture. The time of certain frame can be dropped onto the temperature time curve to determine the temperature that corresponds to the capture time of the frame. On the other hand, the following equation is hold for this mode of operation as long as the temperature is fixed at a selected value.

$$R_e = 4\pi r \left( \frac{f_0}{m} \right)$$  \hspace{1cm} (1)

Where: $R_e$ is the elongation speed, $r$ is the radius of the cylinder that is rotating by the two motors $f_0$ is the rotational speed of two motors in step/sec and $m$ is the number of steps per one complete revolution.
Cases of use:-
This mode is useful for studying opto-thermo-mechanical of polymeric fibres. It helps to detect the structural variations of fibres at higher temperature.

Experimental Results and Discussion:-
In this work a hot-stage multi-mode opto-thermo-mechanical device was designed to study the online influence of increasing the temperature on the optical properties of iPP samples. The designed multi-mode opto-thermo mechanical stretching system was attached to Pluta polarising interference microscope to allow the observation of the changes on the optical parameters during increasing the temperature of the fibre and during the stretching process of the samples and finally during the necking phenomenon.

Online investigation of optical properties during temperature increasing:-
The used sample in this work is isotactic as-spun undrawn monofilaments of polypropylene textile fibres, manufactured at spinneret take up speed = 250 m/min and pump speed = 10 rpm. Samples of iPP fibres were fixed on the hot-stage and brought into the focus of the objective of the Pluta polarising interference microscope. During the optical investigation, iPP sample was immersed in a liquid with a suitable refractive index value (n_L=1.499) at room temperature (T=25°C). The wavelength of the monochromatic light used was 546.1 nm. The hot-stage heater is turned on to allow the heating of the fixed samples. Variations of the refractive index values were monitored by the online recording of the interference patterns.

The microinterferograms were analysed using the subfringe integration technique, which reduces the effect of noise [15]. The main idea of subfringe integration method is that the period of the sinusoidal signal, is divided into at least three or more buckets and integrates each bucket. Four integrating buckets, given by I_1, I_2, I_3 and I_4 (cf. [15]) in the spatial domain are used. The phase (φ) is giving by applying the equation:

$$\varphi = \tan^{-1} \left( \frac{I_1 + I_2}{I_1 - I_2} \right)$$

Figure (2) shows the flowchart of the designed software used in determining the refractive index profile and/or the birefringence profile in three dimensions. The measuring accuracy of the refractive index profile and/or birefringence profile using this model is (0.003-0.001) [16, 17].

The patterns were analysed to extract the phase distribution during the heated process from which the refractive index values for light vibrating parallel and perpendicular along the fibre axis are determined. The refractive index profile is calculated according to the following relation [18], it was considered that, the graded index fibre is divided into number (m) of very thin layers (Q) with thickness a=R/m, where R is the fibre radius. If the thickness of each layer is small enough, the variation of the value of the refractive index of the layer is negligible, and hence each layer has a constant refractive index value n(Q). The layer thickness plays an important role in accuracy of measurement. In other words, the thinner is the layer, the higher is the accuracy of calculation. Let X_Q and d_Q be the emerged and incidedntrays distance, where Q is the layer number. h is the interference spacing and λ is the wavelength:
Where $k$ denotes parallel and perpendicular.

This deduced expression [18] is used to determine the refractive index value for each layer $n(Q)$, by means of iteration. In this mathematical model, the refractive index values are determined with taking into account the transverse refraction of the incident rays, as well as, the longitudinal refraction. Transverse refraction may be neglected by setting $d_Q = X_Q$ to simplify the calculations and to avoid the iteration process when determining the refractive index profile.

Figure (3A) illustrates the calculated phase map of the captured interference patterns during the heating process at different temperatures for the case where the incident light is polarized parallel to the undrawn fibre axis. On the other hand, figure (3B) illustrates the phase map for the case of light vibrating perpendicular to the undrawn fibre axis. Figure (4) shows the 3D refractive index profile of the thermally treated filaments in case of light vibrating parallel to the fibre axis. This figure clarifies that increasing the temperature causes an increment in the refractive index values across the fibre layers which indicates a rise in the refractive index distribution along the fibre axis, while figure (5) shows the 3D refractive index profile in case of light vibrating perpendicular to the fibre axis. According to this figure, a decrease in the refractive index distribution along the fibre axis, which reached a matching value at temperature = 70 °C.

The optical orientation function $f_\Delta$ is obtained using the following equations (cf. [19]):

$$f_\Delta = \frac{\Delta n}{\Delta n_{\text{max}}}$$(4)

Where, $\Delta n_{\text{max}}$ is the maximum birefringence, and it was found to equal 0.03 for iPP fibres [20]. Figure (6) represents the effect of increasing the temperature on the orientation function of the different layers of iPP fibres, a noticeable increase in the molecular orientation is noticed for the layers on increasing the temperature.

Effect of temperature on the drawing process:

The influence of the surrounding temperature on the distribution of the birefringence values at different position of the fibre during drawing process was investigated. The used sample in this work is isotactic as-spun undrawn monofilaments of polypropylene textile fibres, manufactured at spinneret take up speed = 150 m/sec with temperature zone equal to 350-450 °C. The sample is fixed from its ends on the two motors ($W_1$, $W_2$) passing through the hot-stage, (figure 1), to carry out the thermal treatment during the stretching process. The sample was immersed in a liquid with a suitable refractive index value ($n_L = 1.500$ at room temperature $T=25^\circ C$). The wavelength of the monochromatic light used was 546.1 nm. The hot-stage multi-mode stretching device was attached to Pluta polarising interference microscope, and the fibre sample was brought to be in the focus of the objective lens. The speed of stretching was adjusted to be 4step/sec, which was fixed during the different stretching processes. First, the sample was heated until it reaches a certain temperature ranges at (25, 50, 60, and 70 °C) respectively, then a temperature controller was used to fix every mentioned temperature during the stretching process in the range ($Dr = 1.2-1.7$). During the stretching process, the interferograms were recorded continuously,
which allows the online study of the variations of the optical parameters that are determined from the interferograms.

The patterns were analysed to extract the phase distribution during the heating process from which the birefringence values are determined. The birefringence profile is calculated according to the following relation, which considers the transverse refraction of the incident beam [21]:

$$\Delta n_0 = \left[ \frac{1}{R - (Q - 1)\alpha} \right] \lambda \Delta Z_0 - a \sum_{j=1}^{j=q-1} \Delta n_j$$

Where; \( \Delta n \): birefringence, \( Q \): layer number, \( j \): integer number (\( j=1: Q-1 \)), \( \lambda \): wavelength of monochromatic light used, \( Z \): fringe shift, \( b \): interfringe spacing, \( R \): the radius of the fibre, \( \alpha \): layer thickness.

Figure (7) shows the 3D birefringence profile at different draw ratios ranged from (DR = 1.2 – 1.7) at temperature \( T = 25 \, ^\circ \text{C} \). This figure shows an increase in the birefringence during the stretching process as the draw ratios increase. Also for different temperatures i.e. 50, 60 and 70 \, ^\circ \text{C}, the increase in the birefringence was observed during the stretching process as shown in figures (8, 9 and 10). Moreover, for the same draw ratio DR=1.6, for example, it was noticed that, the birefringence values were higher at higher temperature. According to this behaviour, either increasing the temperature or increasing the draw ratio induces more orientation of the molecular chains observed as an increase in the birefringence value. The distribution of the birefringence values helps in detecting different geometrical deformations during the stretching process. This is shown in figure (8) for DR = 1.3 when the surrounding temperature is 50 \, ^\circ \text{C}. In this figure a necking phenomenon takes place at this draw ratio causing deformed distribution of the birefringence values having the shape of the neck. Also, for the surrounding temperature equal 60 \, ^\circ \text{C}, the neck deformation is detected at draw ratio DR=1.4 as shown in figure (9). And another neck is shown in figure (10), when the temperature is 70 \, ^\circ \text{C} and draw ratio is Dr=1.6. So, it can be concluded that the creation of necking deformation depending on the surrounding temperature and draw ratio for the constant stretching velocity.

The determined 3D birefringence profile presents accurate measurements of the birefringence values at different positions of the stretched samples. It may noted that, in all of the following birefringence profiles, the birefringence scale was not fixed for all graphs, this was done to allow more details to be observed rather than fixing the scale of the birefringence axis which may suppress the details of the distribution of the birefringence for the inner layers of the investigated samples.

**Effect of temperature on the necking phenomenon:**

One of the main features of the multi-mode stretching device is its ability to investigate the effect of increasing the temperature on the necking phenomenon observed during the stretching process of iPP fibres. The used sample in this work is isotactic as-spun undrawn monofilaments of polypropylene textile fibres, manufactured at spinneret take up speed = 150 m/sec with temperature zone equal to 350-450 \, ^\circ \text{C}. The iPP fibre sample was fixed from its ends on the two motors (W1 & W2), (figure 1), passing through the hot-stage. The used device was attached to Pluta polarising interference microscope. The fibre was immersed in a liquid with refractive index value \( n_l=1.5 \). The wavelength of the light used was 546.1 nm. The fixed iPP fibre sample was stretched until the necking region is observed in the field of view. Once the necking is observed, the stretching process is stopped and the heater is turned on. The online recording of the interference pattern for iPP fibre with necking deformation during heating processes allowed us to investigate the effect of heating on the necked sample.

The necking phenomenon usually occurs when a homogeneous polymeric fibre is stretched uniaxially. In this case the fibre is deformed into three microscopic regions according to the morphological model of Shimizu et al. [22] and the molecular model of Peterlin [23]. These regions are: i) The as spun, part of fibre (before neck). ii) The neck shoulder (neck zone as super drawing), and iii) The drawn fibre part (after neck).

Figure (11) represents the acquired phase maps of two-beam interference patterns captured during the heating process. In addition, figure (12) represents the unwrapped phase distribution in 3D along necked iPP fibres at different temperatures. The necking regions were noticed as localised phase changes along the fibre's axis. From the observed phase maps and the 3D unwrapped phase distribution (figures 11&12), necking propagation can be noticed as the temperature increases. To clarify this phenomenon the phase maps (figure 11) are remarked to be easy for identification the propagation of the necking.
along the fibre axis during the increasing of temperature. At temperature (27°C), the neck shoulder was observed at fringe number 5, at (28°C), the neck shoulder became between fringe number 5 and 6, at (29°C), the neck shoulder was detected near to fringe number 6, at (30°C), the neck shoulder was located at fringe number 6, at (32°C), the neck shoulder was between fringe number 6 and 7, at (33°C), the neck shoulder was noticed near to fringe number 7, finally, at (34°C), the neck shoulder was observed at fringe number 7. It was noticed that, increasing the temperatures may cause the localised necking to transfer to another position. In this case, we can conclude that increasing temperature causes the necking to propagate along the fibre axis.

To calculate the speed of necking propagation interferometrically from the fringe shift profile, the neck profile is noticed when changes passes between two points along the fibre axis, the spacing distance between the two points(Δx), during the interval time (Δt). The speed of propagation is given from the equation $V_p = \frac{\Delta x}{\Delta t}$. This process is carried out at different positions along fibre axis to determine the mean speed of propagation. It was noticed that the speed of propagation is nearly constant along fibre axis during the propagation process. The mean speed of propagation is $V_p = 1.0635 \, \mu\text{m/sec}$.

**Figure 1:** A schematic diagram of multi-mode opto-thermo mechanical stretching system. Where, M: Microscope stage, G1, G2: glass slides, H: flat heater (at 20w, 110v), F: fibre under test, W1, W2 : rotating wheels attached to stepper motors, E: microscope eyepiece, L: collimating lens, S: white light source, TC: tip of K-type thermocouple and it's terminals, RL : variable load resistance, P: power terminals for heater.
Figure 2: Flowchart of the used software for fringe analysis.

| A | B |
|---|---|
| ![Image](image1.png) | ![Image](image2.png) |
| $T = 20 ^\circ C$ | $T = 20 ^\circ C$ |
| ![Image](image3.png) | ![Image](image4.png) |
| $T = 30 ^\circ C$ | $T = 30 ^\circ C$ |
Figure 3:- (A) Phase map obtained from the recorded interferograms during the heating process at different temperatures (20, 30, 40, 50, 60 and 70 °C) for the case where the incident light is polarised parallel to the fibre axis. (B) Phase map for the case where the incident light is polarised perpendicular to the fibre axis.
Figure 4: The 3D refractive index profile during the heating process at different temperatures (20, 30, 40, 50, 60 and 70 °C) for the case where the incident light is polarised parallel to the fibre axis.
Figure 5: The 3D refractive index profile during the heating process at different temperatures (20, 30, 40, 50, 60 and 70 °C) for the case where the incident light is polarized perpendicular to the fibre axis.
Figure 6: - Therelation betweenthe orientation function and different layers of iPP fibres.
Figure 7: The 3D birefringence profile during stretching fibre at temperature 25°C and stretching speed=4step/sec, at draw ratios (1.2, 1.3, 1.4, 1.5, 1.6 and 1.7).

- DR = 1.4 at T=25°C
- DR = 1.7 at T=25°C
- DR = 1.2 at T=50°C
- DR = 1.5 at T=50°C
- DR = 1.3 at T=50°C
- DR = 1.6 at T=50°C
Figure 8: The 3D birefringence profile during stretching fibre at temperature 50°C and stretching speed=4step/sec, at draw ratios (1.2, 1.3, 1.4, 1.5, 1.6 and 1.7).
Figure 9: The 3D birefringence profile during stretching fibre at temperature 60 °C and stretching speed=4step/sec, at draw ratios (1.2, 1.3, 1.4, 1.5, 1.6 and 1.7).

DR = 1.4 at T=60°C

DR = 1.7 at T=60°C

DR = 1.2 at T=70°C

DR = 1.5 at T=70°C

DR = 1.3 at T=70°C

DR = 1.6 at T=70°C
Figure 10: The 3D birefringence profile during stretching fibre at temperature 70 °C and stretching speed=4step/sec, at draw ratios (1.2, 1.3, 1.4, 1.5, 1.6 and 1.7).

DR = 1.4 at T=70°C

DR = 1.7 at T=70°C

T = 27 °C

T = 28 °C

T = 29 °C

T = 31 °C

T = 32 °C

T = 33 °C
Figure 11: Phase map obtained from the recorded interferograms during the heating process of necking phenomenon at different temperatures (27, 28, 29, 30, 31, 32, 33 and 34 °C).
Conclusion:
A multi-mode opto-thermo mechanical stretching device attached to Pluta polarising interference microscope is constructed. The advantage of this device is the online determination of the optical parameter of heated fibres at different temperatures. Using this device for iPP fibre clarified that; temperature increment resulted higher orientation of heated fibres. Also it is concluded that the surrounding temperature of the fibre is an effective parameter, as well as the draw ratio and stretching velocity, for the creation of necking deformation. Also using this device allowed us to investigate the effect of varying the surrounding temperature on the necking phenomenon. In this study, upon increasing the temperature, necking region began to propagate.

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