Role of Cellulose in Determining the Mechanical and Optical Properties of Two Soft Paper Roll Samples and Application in the Mechanics of the System of the Fourth Order Improved Runge-Kutta Method

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Abstract

White soft paper sample rolls from Glass Cleaning SA. were tested for their tensile and optical properties as well as the fibre component of their pulps using the optical microscope. Also, other substrate properties of the two soft paper roll samples were determined i.e., ash content on ignition at 900 °C, brightness, basis weight, the band gap energy, and finally application in the mechanics of the system of the 4th order Runge-Kutta method of two different step sizes was implemented on the two wet paper strips used for determining their wet tensile strength.

Keywords: Cellulose; Optical microscope; Tensile strength; Absorption spectra; Kubelka-Munk K/S value; Band gap energy; Fourth order Runge-Kutta method.

Introduction

In this work a fibre furnish analysis was carried out under the optical microscope to determine the fibre component of the pulps of two soft paper roll samples quantitatively. The physico-chemical characteristics of the paper roll sheets were connected to the chemical composition of the obtained pulps [1]. The Herzberg staining test was applicable to the qualitative and quantitative differentiation between chemical, mechanical and rag pulps [2-4]. Here the pulp of the paper samples was identified as chemical, i.e., cellulose.

With the development of micro-electro-mechanical systems technology, more thin materials have been used in this field. A method is proposed to measure the mechanical properties of thin sheets of soft paper. The tensile properties of the dry and wet soft paper samples were carried out using a Zwick-Roell Z.2.5 machine with a 50N load cell [5-7]. The tensile-testing apparatus stretched the soft paper test pieces strips at a constant rate of elongation of 50 ± 2mm/min. The paper test specimens strips were conditioned at (23 ±1) °C and (50 ±2)% relative humidity (r.h.) before and during the testing. With the rapid development of electro-mechanical systems more thin materials including paper and plastics products have been widely used. The mechanical properties such as tensile strength and elongation at rupture are necessary for producing soft paper products and plastic products and evaluating their reliability [6]. Of all the methods proposed to measure the properties of soft paper products the uniaxial tensile test has been generally considered as the most reliable way. The difficulty of the uniaxial tensile test is how to fabricate a thin, undamaged, straight, smooth and with parallel edges strip, align the paper strip, and measure the strain. A micro-tensile method has been implemented for measuring the mechanical properties of micro-electro-mechanical systems materials and measure the strain [6]. The mechanical behavior of paper samples and polymers is also temperature dependent. Many models have been proposed for the determination of the relationship between temperature, relative humidity, strength, stress and strain. The high tensile strength appearing lengthwise for both paper samples rolls was caused by the grain-boundary strengthening and grain preferred orientation [6]. Also, in this work a tensile test system was presented to measure the tensile strength of the soft paper strips in their dry and wet state.
Generally cellulose fibres are used in the production of paper pulp and they impart mechanical strength properties [8]. In cellulose, a polymer of glucopyranose units (β-D) linked together by the association of β-glycosidic bond to be a long chain and are connected with other hydrogen bond chains [8]. The tensile strength was calculated using the formula $\sigma = \frac{F_{\text{max}}}{A}$ (1), where $F_{\text{max}}$ was the maximum force and $A$ was the cross-sectional area of the paper 50mm strip of the two soft paper roll samples [8,9]. The inference from the data from this work was that cellulose was the key mechanical component contributing to mechanical strength [9,10]. The mechanical properties of soft paper rolls mainly depended on the structure and strength of cellulosic fibers [11,12] which bear the exterior loads. Cellulose was behaving as a mechanical element. It behaved as a mat of individual fibrils. The assessment of the cellulosic fiber for the two soft paper samples was conducted with the determination of strength and strain to failure using paper strip tensile tests [8,9]. The mean tensile strength and the standard deviation were calculated also.

The cellulose fibre pulp of the two paper sample rolls in this work was separated from the other biomass components by pulping and by the bleaching process [10,11]. Finally, this paper deals with a special ordinary differential equation. The purpose of this work was to propose a mathematical model. Fourth order improved Runge-Kutta method for directly solving a special third-order ordinary differential equation was constructed by Hussain et al. [13]. Numerical comparisons were performed using the existing Runge-Kutta method after reducing the problems into a system of first-order equations and solving them, and direct RKD (Runge-Kutta) method for solving special third-order ordinary differential equations. Numerical examples were presented to illustrate the efficiency and the accuracy of the method in terms of a number of function evaluations and the max absolute error. In this work the 4th order Runge-Kutta method of two different step sizes $h=0.5$ and $h/2=0.25$ was implemented for both of two soft paper samples in the Matlab computing environment. A Runge-Kutta 4th order method for solving an ordinary differential equation was developed and implemented [13].

**Experimental**

**Reagents**

All the chemicals used were of analytical reagent grade quality and they were used without further purification. Solutions were prepared using deionized water of conductivity <1μS/cm. Zinc chloride for analysis (250g) was procured from M ESMURE (M.W.136.30g/mol). Potassium Iodide for analysis (250g) was procured from M ESMURE (M.W. 166.00g/mol). Iodine, IODIO BISUBLIMATO (100g) was procured from Carlo Erba (Cod. 455959). Calcium chloride anhydrous (M.W. 110.99g/mol) QP desiccant was procured from Panreac (1000g) (Code 211221.12 11).

**Apparatus**

Ordinary laboratory equipment such as beakers of capacity 100ml, and glass cylinders of capacity 100ml were used. The Reagents

Experimental

**Absorption spectra were obtained also by means of a Spectrophotometer CM-3630, BCMTS M Type 40605, S.N. 43029, TouchScreen-M V 2.0, Frank-PTI. The spectrophotometer CM-3630, Model BCMTS M Type 40605, had a software Touchscreen M. The apparatus was connected with a computer Asus with windows 7 Pro. The computer had a display Hanns. G and a keyboard Logitech K120, a mouse Logitech RX250, and a printer HP Laserjet P1102. The spectrophotometer also had a black cavity made in Japan with a reflectance factor which did not differ from its nominal value by more than 0.2% at all wavelengths. It also had a white calibration plate Konica Minolta with number 20286101. It also used for calibration a paper non-fluorescent reference standard for adjusting the UV-content of the radiation incident upon the sample with number CNF-082, and a paper fluorescent reference standard for adjusting the UV-content of the radiation incident upon the sample with number CF-082, 1R 3 Ct。”

Weighings were carried out on an electronic balance Sartorius Basicplus, AGGöttingen Germany BP 221S, with maximum capacity 220g, precision of four decimal places, and accuracy to 0.1mg and it was accredited every three years. A Bunsen burner with a flame with a reducing internal cone was used where the dishes with the paper sample specimens of size approximately 1cmx1cm, were heated slowly in such a manner that the paper sample specimens were burned and did not burst into flames. Also, no material was lost in the form of flying particles. The intensity of the flame was such that its internal cone was not into contact with the porcelain of

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the dish. Glass containers were procured from NS ISOLAB Germany, and were used with a diameter of 80mm, a height of 30mm, and a capacity of 80ml, inside which the soft paper test pieces were kept and weighed. A glass desiccator, with a plate from porcelain with holes, and with CaCl₂ as desiccant, was used for the transferring of the porcelain dishes, inside which were kept the test pieces of the two soft paper samples, and finally the dishes with the ash content. Dishes of porcelain with an even bottom with a diameter of 5cm, a height of 4.5cm, and a capacity of 50ml were used for the incineration of the paper sample specimens. The dishes did not lose and did not gain mass on ignition. Before their use the dishes were rinsed with distilled water and then they were heated at 900 °C±25 °C inside the furnace for 60min. After the passage of two hours their temperature diminished at 400 °C and the dishes were kept for two hours into the desiccator before they were used.

A muffle furnace Carbolite of maintaining a temperature of 900 °C was used. The muffle furnace Carbolite type OAF 11/1 S/N 9/99/2080, with max temperature 1100 °C was used, of maintaining a temperature of 900 °C±25°C, i.e. 918 °C. It constituted from thermal plates which made the roof and its floor. The furnace had a built in pre-heated stream of air which passed through its chamber. It was also provided with a chimney to evacuate smoke and steam and fumes. The furnace was accredited every three years. An Oven Memmert Gmbh UNE 400 was used, which maintained air temperature at 105 °C±2 °C and it was ventilated in order to maintain uniform temperature and extracted the moisture from the two soft paper test pieces [14] and it was accredited every three years. An Oven Memmert direkt, was used capable of being controlled at 1030°C, where the soft paper test pieces were heated and dried. The cutting device used was a guillotine IDEAL 1043 GS DP 02050 made in Germany which produced paper test pieces strips of 50mm wide and 100mm in length with undamaged, straight smooth and parallel edges.

An accredited ruler for measuring the width of the soft paper test pieces strips and also of measuring the rate of elongation was used. The metallic ruler was accredited from an external accredited body every five years. The tensile properties of the soft paper roll samples vary at different temperatures and relative humidities. Therefore, a conditioning room where each test piece was positioned vertically. The tensile-testing apparatus was stretching the test piece of the soft tissue paper sample at a constant rate of elongation of 50mm/min and recording the tensile strength as a function of elongation on the computer LG. The elongation was recorded to an accuracy of ±0.01mm. The tensile-testing apparatus was cut using a guillotine. The type of tensile-strength tester was used where each test piece was positioned vertically. The tensile-testing apparatus was stretching the test piece of the soft tissue paper sample at a constant rate of elongation of 50mm/min and recording the tensile strength as a function of elongation on the computer LG. The elongation was recorded to an accuracy of ±0.1mm. The measurement of the elongation started at a tension of 5N/m. The force measuring system measured the loads with an accuracy of ±0.05N. The tensile testing apparatus had two clamps with glass rods until dissolved and we transferred the two solutions to a glass cylinder of 100ml capacity and we stoppered the cylinder. We shaked the cylinder well to mix the solutions and finally left it overnight away from light and air, in the dark, so that the precipitate formed settled. After 24 hours we decanted the clear solution into a brown dropper bottle with a ground-glass stopper and we kept it away from air and light in the dark.

Preparation of the paper fiber suspension

The paper fiber suspensions were prepared in the ultra-sonic disperser by putting the test paper pieces of each of the two soft paper samples, of size approximately 1cmx1cm and adding 400ml deionized water. The paper pulp was homogenized in a Waring commercial blender (mixer) setting low and high for 3 minutes.

Staining and preparation of fibre slides for optical microscopy

We put 1ml of the paper fiber suspension on to the microscope slide and we dried the slide with the suspension onto it, for 10min in the oven Memmert direct controlled at 103 °C±2 °C. As the slide with the suspension was hot from the oven, we stained the slides with each of the two paper samples by applying 3 drops of the Herzberg stain onto the fibre slide. We then put three (3) rectangular microscope cover glasses onto the glass microscope slides with each of the paper fiber suspensions on them. We placed the stained fibre slides under the optical microscope and we examined them using a magnification of x10/0.2 to x20/0.4. The microscope was equipped with a mechanical stage and crosshair and a central dot. For the illumination we used a normal vacuum lamp with daylight filter, namely a Halostar UV-stop OSRAM lamp (>500 °C) with barcode 4050300324432 made in Germany. We identified the fibres as chemical pulp, and we counted the fibres on the basis of the bluish violet colour developed by the Herzberg stain. The morphology of the paper pulp was observed using the optical microscope. The microscope was a useful tool to help us see the objects that were smaller than 0.1mm. With the optical projection microscope with a round screen and no binoculars we saw small the objects of size 0.1μm i.e., 0.0001mm. For the smaller objects to see we may have used other types of microscopes. The two soft paper samples consisted of chemical pulp i.e., cellulose, since the color of the stained specimens in the optical microscope was bluish violet.

Determination of dry conditioned state tensile strength

Rectangular strips of paper (their geometry 100x50x1mm) were cut using a guillotine. The type of tensile-strength tester was used where each test piece was positioned vertically. The tensile-testing apparatus was stretching the test piece of the soft tissue paper sample at a constant rate of elongation of 50mm/min and recording the tensile strength as a function of elongation on the computer LG. The elongation was recorded to an accuracy of ±0.1mm. The measurement of the elongation started at a tension of 5N/m. The force measuring system measured the loads with an accuracy of ±0.05N.
of 50mm width. Each clamp grabbed the soft paper test piece strip firmly without damaging it along a straight line across the full width of the test piece. The clamping lines were parallel to each other. They were also perpendicular to the direction of the applied tensile force and to the long dimension of the test piece. The distance between the clamping lines was 90mm.

The two ends of the dry paper test pieces strips were placed directly between the metallic pneumatic grabs in the Zwick-Roell Z.2.5KN tensile machine [16-18] and the grabs moved apart at a constant speed of 50mm.min⁻¹. The load cell was 50N. The extensometer was a long stroke with code number 320109. We took ten (10) specimens from each of the two paper samples of the two soft paper products. From each specimen we cut ten (10) test pieces in the Machine Direction (MD) and ten (10) test pieces in the Cross Direction (CD) making a total of twenty (20) test pieces from each sample of soft paper sample product. We placed the test pieces of the two paper samples, one at a time, in the clamps so that no observable slack appeared and that the test pieces were not placed under any significant strain. We did not touch the test area of the test pieces between the clamps with our fingers. We aligned and tightly clamped the paper test pieces and carried out the tests. We have tested twenty (20) test pieces from each soft paper sample. The elongation rate between the clamps was kept constant at 50mm/min. We recorded all the readings except for the test pieces that broke within 5mm from the clamping line. Ten tests were carried out along the Machine Direction (MD) of the dry soft paper samples and another ten tests were carried out along the Counter Machine Direction (CD) of the dry soft paper samples. The samples which had broken near the edge of the clamps were excluded from the analysis. The test specimen strips for the tensile testing were conditioned at 23 °C ±1 °C and at 50% ±2% relative humidity before the testing, as well as during the tensile testing.

Determination of wet state tensile strength

Rectangular strips of paper (of typical geometry 100x50x1mm) were cut using the guillotine IDEAL 1043 GS DP 02050. The paper samples were conditioned and tested in a standard atmosphere at 23 °C and 50% relative humidity. A type of tensile-strength tester was used where the test piece was positioned vertically. The tensile-testing apparatus was stretching the test pieces of the soft paper samples at a constant rate of elongation of 50mm/min and was recording the tensile force as a function of elongation on the computer. The elongation was recorded to an accuracy of ±0.1mm. The measurement of the elongation started at a tension of 0.025N (pre-load). The force measuring system was measuring the loads with an accuracy of ±0.1N. The tensile testing apparatus had an upper clamp of 50mm width for holding both ends of the soft paper test pieces firmly and without slippage.

The lower clamp was made to grip the Finch Cup soaking device firmly. During the test, the upper clamping line and the Finch cup soaking device rod were parallel to each other. They were also perpendicular to the direction of the applied tensile force and to the length axis of the test pieces. The test span length, which was the distance between the clamping line and the top surface line of the cylindrical rod of the Finch Cup soaking device was adjusted to 86mm. The Finch Cup soaking device consisted of a support system that held a horizontal cylindrical rod of 5mm diameter and 60mm length and the water container. The water container was constructed such that it moved vertically and locked in the raised position. In the locked raised position, the water in the container completely surrounded the cylindrical rod, which was immersed in the liquid (deionized water) to a depth of 20mm. Projecting downwards from the bottom of the device was a rigid metal tongue by means of which the device was held in the lower clamp of the tensile-strength-testing apparatus. The water in the soaking vessel was adjusted to a constant level between the measurements. Rectangular strips of paper (of typical geometry 100x50x1mm) were cut using the guillotine. The guillotine was cutting the test pieces 50mm wide and 100mm in length with undamaged, straight, smooth and parallel edges. The paper samples were conditioned in a standard atmosphere at 23 °C and 50% relative humidity. The paper specimens were conditioned in this standard atmosphere and were kept in this conditioning atmosphere throughout the tests. The type of tensile-strength tester was used where the test piece was positioned vertically. Each clamp grabbed the soft paper test piece strips firmly without damaging them along a straight line across the full width of the test pieces. The clamping lines were parallel to each other during the testing within an angle of 1°. They were also perpendicular to the direction of the applied tensile force and to the longest dimension of the test pieces. The distance between the clamping lines was 86.5mm.

We have placed the water container (Finch Cup soaking device) in its bottom position, and we filled it up to the mark with deionized water at 23 °C. We inserted the dry test pieces horizontally under the dry rod, we bent them around the rod creating a loop and we clamped the two ends of the test pieces in the upper clamp of the tensile-strength-testing apparatus. We ensured that both ends of the looped test pieces were held by the clamp and that were tightened without causing damage, while avoiding slippage during the tests. We raised the water container until it locked in its upper position thereby immersing the looped end of each test piece to a depth of 20mm below the initial water level. We then immediately have started the stopwatch. After soaking for 15s, we lowered the water container to its lowest position.

Then we immediately initiated the tensile tests. The wet tensile strength of the immersed test pieces was determined at an elongation rate of 50mm/min. In order to obtain the wet tensile strength of each single test piece we divided the recorded wet tensile strength by two (2). When the paper test pieces broke on the rod of the Finch Cup soaking device and in the upper clamp, we rejected the reading of the test and we repeated it with an additional test piece. After each test we wiped dry the horizontal rod of the Finch Cup soaking device, before attaching the next test piece.
after each test, we topped up the water container with deionized water. Also, after each set of ten (10) tests of the two samples we cleaned and refilled the water container. Ten tests were carried out along the Machine Direction (MD) of the wet soft paper samples and another ten tests were carried out along the Counter Machine Direction (CD) of the wet soft paper samples. The test specimen strips for the wet tensile testing were conditioned at 23 °C±2% and 50%±2% relative humidity before the testing as well as during the wet tensile testing. **Determination of residue (ash) on ignition at 900 °C**

The residue on ignition was the mass of the residue left after incineration of each of the two samples of soft paper in the furnace at 900 °C. The samples of soft paper were weighed in the porcelain heat-resistant dish and were incinerated at 900 °C in the muffle furnace. The masses of the residues were determined by weighing the dishes after incineration of the soft paper samples. The procedure was carried out in duplicate for each of the two soft paper samples. The yield was 0.41%w/w for soft paper roll 1. The yield was 0.37%w/w for the soft paper roll 2. The yield was calculated as the following formula:

\[
\text{Yield} = \frac{\text{mass of the residue on ignition at 900 °C}}{\text{massing of the paper sample test pieces}}
\]

For the determination of the ash content, the test pieces of 50g total weight were prepared, that were cut from different points of each of the two soft paper sample rolls and were kept into the two separate glass containers. The paper test specimens consisted of a number of small pieces having dimensions of 10mmx10mm, and of size 1cm². The test pieces of the two paper samples and their weighing containers were put into the drying oven Memmert GmbH UNE 400, for 24 hours approximately with a temperature of 105 °C±2 °C. Then the paper small pieces were allowed to attain room temperature in the desiccator for 40min.

Firstly, for the determination of the ash content of the two paper samples the button of the muffle furnace Carbolite was pressed to being operative in place 1. The button to adjust the temperature was then on and the furnace made a short, test cycle. The light of heating of the furnace was on and was blinking as the furnace reached the temperature that was put at 900 °C±25 °C, namely 918 °C. The procedure of calculating the ash content in the two paper samples was carried out in duplicate. The ash content was weighed 0.0042g for the soft paper sample 1. The ash content was also weighed 0.0040g for the soft paper sample 2. The portions to be incinerated consisted of a number of small paper test pieces and had a total mass of 1.0310g for the soft paper sample 1. The dishes with the samples were heated first in the Bunsen burner slowly in a manner that the sample burned but did not burst into flames, until the residue in the dish did not release fumes (soot). When the combustion was complete, so that only the small amounts of carbon were visible, the dish was exposed to full heat (900 °C±25 °C) in the muffle furnace for 1hour. When the heating was complete the operation of the furnace was stopped, and we have waited until the temperature in its interior reached 400 °C. Then the dishes with the ash were removed from the furnace and were allowed to attain room temperature in the desiccator for 3 hours. The dishes with the ash content were weighed in the electronic balance with an accuracy of 0.1mg. The furnace was placed in a hood and was provided with a chimney for evacuating the smoke and fumes.

**Result and Discussion**

Tensile properties (Figure 1-4). The tensile strength was the maximum stress until the fiber network of the paper samples broke, and it was dependent on the degree of fiber-fiber bonding. The inter fiber bonding was the most important factor contributing to the tensile strength property [16]. The soft paper samples were as usual stronger in the Machine Direction (MD) than Counter Machine Direction (CD) direction in tension. The soft papers manufactured on a paper machine, had more fibers oriented in the machine direction than in the cross direction. In general papers have different properties in the machine and the cross direction. The tensile strengths were the maximum stress until the paper fiber network broke. This paper property was dependent on the degree of fiber-fiber bonding. Usually, the soft paper is stronger in MD (Machine Direction) than CD (Cross Direction) in tension. Of all the properties that explained the tensile strength of the cellulose material i.e., the chemical pulp by far the most important was the intermolecular bonding forces. The second soft paper sample tested had a higher tensile strength than the first because of the effect of its extended hydrogen bonding. The -OH and -O-groups in cellulose provided sites for hydrogen bonding governing the tensile properties of the paper samples [19]. The nature of the inter fiber bonds in the soft paper samples were the same as that of the intermolecular bonds in cellulose. The tensile properties in this work were carried out according to ISO 12625-4 [20] and ISO 12625-5 [21]. Ten specimens were tested lengthwise (MD) and ten specimens were tested crosswise (CD) and the median value was taken for each dimension [22]. The soft paper sample 1 had the tensile index [1] 6.67KN.m/Kg lengthwise (MD) and 2.68KN.m/Kg crosswise (CD). The soft paper sample 2 had the tensile index [1] 6.82KN.m/Kg lengthwise (MD) and 2.79KN.m/Kg crosswise (CD). The elongation at rupture [23] of the dry soft paper sample 1 was 14.0% lengthwise (MD) and 9.3% crosswise (CD). The elongation at rupture of the dry soft paper sample 2 was 13.3% lengthwise (MD) and 8.2% crosswise (CD). The elongation at rupture [23-28] of the wet soft paper sample 1 was 8.2% lengthwise (MD) and 7.1% crosswise (CD). The elongation at rupture of the wet soft paper sample 2 was 6.3% lengthwise (MD) and 5.4% crosswise (CD).
**Figure 1:** Tensile force of the dry soft paper sample 1 as a function of the strain of its paper specimens.

**Figure 2:** Tensile force of the wet soft paper sample 1 as a function of strain of its paper specimens.

**Figure 3:** Tensile force of the dry soft paper sample 2 as a function of strain of its paper specimens.
In Table 1 the tensile strengths for the two soft paper samples in the dry conditioned state are presented as well as their uncertainties which were calculated as the following formula: \( \text{tensile strength} = \frac{\overline{y} \pm t_{(n-1), 0.05} \frac{s}{\sqrt{n}}}{10^5} \) (5), where \( \overline{y} \) the mean value of the ten measurements and \( s \) is the standard deviation and \( n \) the number of tests made. The theoretical is from tables for student's t-distribution for 95% confidence level and \( n-1 \) degrees of freedom, of two ends. In Table 2 the tensile strengths for the two soft paper samples in dry conditioned state are presented as well as their uncertainties which were calculated as the following formula: \( \text{tensile strength} = \frac{\overline{y} \pm t_{(n-1), 0.05} \frac{s}{\sqrt{n}}}{10^5} \) (6), where \( \overline{y} \) the mean value of the ten measurements, and \( s \) is the standard deviation and \( n \) the number of tests made. The theoretical is from tables for student's t-distribution for 95% confidence level and \( n-1 \) degrees of freedom, of two ends. In Table 3 the tensile strengths for the two soft paper samples in wet conditioned state are presented as well as their uncertainties which were calculated as the following formula: \( \text{tensile strength} = \frac{\overline{y} \pm t_{(n-1), 0.05} \frac{s}{\sqrt{n}}}{10^5} \) (7), where \( \overline{y} \) the mean value of the ten measurements, and \( s \) is the standard deviation and \( n \) the number of tests made. The theoretical is from tables for student's t-distribution for 95% confidence level and \( n-1 \) degrees of freedom, of two ends. In Table 4 the tensile strengths for the two soft paper samples in wet conditioned state are presented as well as their uncertainties which were calculated as the following formula: \( \text{tensile strength} = \frac{\overline{y} \pm t_{(n-1), 0.05} \frac{s}{\sqrt{n}}}{10^5} \) (8) where \( \overline{y} \) the mean value of the ten measurements and \( s \) is the standard deviation and \( n \) the number of tests made. The theoretical is from tables for student's t-distribution for 95% confidence level and \( n-1 \) degrees of freedom, of two ends. In Table 5 various properties for the two soft paper samples are presented as well as their ash on ignition content and their extended uncertainties at 95% confidence level.

### Table 1

| Dry Conditioned Soft Paper 1 | Dry Conditioned Soft Paper 2 |
|------------------------------|------------------------------|
| Tensile strength lengthwise MD=107.4N/m±14.1N/m | Tensile strength lengthwise MD=111.9N/m±11.5N/m |
| Tensile strength crosswise CD=43.1N/m±4.5N/m | Tensile strength crosswise CD=45.8N/m±6.7N/m |

### Table 2

| Dry Conditioned Soft Paper 1 | Dry Conditioned Soft Paper 2 |
|------------------------------|------------------------------|
| Tensile strength lengthwise MD=2.148KPa±0.28KPa | Tensile strength lengthwise MD=2.238KPa±0.229KPa |
| Tensile strength crosswise CD=0.862KPa±0.09KPa | Tensile strength crosswise CD=0.916KPa±0.135KPa |
Table 3: The tensile strengths for the two soft paper samples in wet conditioned state are presented as well as their uncertainties which were calculated as the following formula: \( \text{result} = \bar{y} \pm \frac{s}{\sqrt{n}} (N/m) (95\%) \) (7), where \( \bar{y} \) the mean value of the ten measurements, and \( s \) is the standard deviation and \( n \) the number of tests made. The \( t_{\text{theoretical}} \) is from tables for student’s t-distribution for 95% confidence level and \( n - 1 \) degrees of freedom, of two ends.

| Wet Conditioned Soft Paper 1 | Wet Conditioned Soft Paper 2 |
|------------------------------|------------------------------|
| Tensile strength lengthwise MD=(4.50/2)N/m±0.4N/m | Tensile strength lengthwise MD=(4.84/2)N/m±0.6N/m |
| Tensile strength crosswise CD=(2.14/2)N/m±0.08N/m | Tensile strength crosswise CD=(1.88/2)N/m±0.2N/m |

Table 4: The tensile strengths for the two soft paper samples in wet conditioned state are presented as well as their uncertainties which were calculated as the following formula: \( \text{result} = \bar{y} \pm \frac{s}{\sqrt{n}} (\text{Pa}) (95\%) \) (8) where \( \bar{y} \) the mean value of the ten measurements and \( s \) is the standard deviation and \( n \) the number of tests made. The \( t_{\text{theoretical}} \) is from tables for student’s t-distribution for 95% confidence level and \( n - 1 \) degrees of freedom, of two ends.

| Wet Conditioned Soft Paper 1 | Wet Conditioned Soft Paper 2 |
|------------------------------|------------------------------|
| Tensile strength lengthwise MD=(90/2)Pa±8.6Pa | Tensile strength lengthwise MD=(96.8/2)Pa±12.5Pa |
| Tensile strength crosswise CD=(42.8/2)Pa±1.6Pa | Tensile strength crosswise CD=(37.6/2)Pa±4.7Pa |

Table 5: Substrate details.

| Property | Soft Paper Sample 1 | Soft Paper Sample 2 |
|----------|---------------------|---------------------|
| ISO Brightness (ISO 2470-1)[24] | 88.30% | 88.32% |
| Opacity (ISO 2471)[25] | 60.96% | 61.81% |
| Ash on ignition (ISO 2144)[26] | 0.41%w/w±0.04%w/w | 0.37%w/w±0.04%w/w |
| Basis weight (ISO 536)[27] | 16.1g/sq.m | 16.4g/sq.m |
| Water absorbency (Tappi 432 om-87)[28] | 7s | 7s |

Calculation of Kubelka-Munk K/S values for the soft paper sample 1 and for the soft paper sample 2 (absorption coefficient/scattering coefficient ratio). The optical properties of the soft paper samples were examined using a UV-visible Spectrophotometer [29] at room temperature [30]. The K/S ratio for the soft paper sample 1 was found K/S=43.16 and the reflectance ISO brightness used was measured 88.30%. The ISO brightness measured was the numerical value of the reflectance of the soft paper sample 1 at 457nm, blue light reflectance.

The K/S ratio for the second soft paper sample 2 was found K/S=43.17 and the reflectance ISO brightness used was measured 88.32%. The ISO brightness measured was the numerical value of the reflectance of the soft paper sample 2 at 457nm, blue light reflectance.

In this work the Kubelka-Munk theory was used for predicting the optical properties for the two soft paper samples. The appearance of the soft papers in the rolls was the result of their optical properties. As known the Kubelka-Munk theory is based on the assumption that the interaction between the diffuse light and the paper material can be described in terms of two fundamental optical constants. The specific scattering coefficient (S) and the specific absorption coefficient (K). The Kubelka-Munk theory holds strictly for homogeneous materials only, and it works well here for the two paper samples containing chemical pulp [30]. The equation of Kubelka-Munk used above is: \( K/S = (1-R)^2/2R \) (9) where K is the absorption coefficient of reflectivity and S is the coefficient of light scattering; \( R \) is the observed reflectivity for monochromatic light.

Estimation of the band gap energy \( E_g \) from the DRS studies of the soft paper sample 1

A graph was plotted of \((K/s \cdot h\nu)^2 \) versus \( h\nu \). The extrapolation of straight line to \((K/s \cdot h\nu)^2=0\) axis (Tauc Plot) gave the value of the band gap energy \( E_g \) [31]. The estimation of the band gap energy was performed from the DRS (Diffuse reflectance spectra) study. The band gap energy \( E_g \) [32,33] of the chromophores, i.e., colored compounds, present in the cellulose matrix [34] was estimated as 1.169845eV for permitted indirect transitions, or 1.874091193540620E-19Joules, for the soft paper sample 1. The band gap energy was calculated from the function trend in the excel spreadsheet with the data calculated for the whole range of wavelengths 400-700nm [35,36]; (Figure 5 & 6). The band gap energy \( E_g \) [33] of the chromophores, i.e., colored compounds, present in the cellulose matrix [34] of the soft paper sample 2 was estimated as 1.169845eV for the permitted indirect transitions, or 1.874091193540630E-19Joules.
Application in the mechanics of the system of the Runge-Kutta method [37-39] for finding the position and velocity of the body bound in the wet strip of the two soft roll paper samples. Suppose we have accepted that the body of mass \( m = 2N \) was attached to the spring constrained to oscillate along the x-axis, i.e., horizontally, here the wet soft paper sample strip of dimensions 90x50mm, and with constant \( k = \frac{4.50}{2} = 2.25 \text{N/m} \) lengthwise, which was the tensile force of the wet tissue paper sample 1, then this body may have felt not only the spring’s force but also the damping force proportional to the square of its velocity and with a ratio of proportion four (4). The weight force of the body was ignored in the supposition. Also, for the wet soft paper sample 2 the constant was \( k = \frac{4.84}{2} = 2.42 \text{N/m} \) lengthwise. When this body was prevented from the equilibrium position to the position \( x = 2m \) and was released at the time \( t = 0 \) then its position and its velocity at the time \( t = 5s \) could have been calculated with the fourth order improved Runge-Kutta method with pace \( h = 0.5s \). Then the graphical representation of its position and velocity for \( 0 < t < 5s \) had to be drawn. Because the damping power of the spring was proportional to the square of the velocity of the body then from the fundamental law of dynamics, we wrote the equations below

\[
mx'' = F_e - b|x'|
\]

where \( m \) was the mass of the body tied to the wet paper sample strip 1, \( F_e \) was the spring’s force and \(-b|x'|\) was the damping force. Then replacing with numbers, we had

\[
2x'' = -4.50x - 4|x'|
\]

for wet tissue paper strip 1 or

\[
x'' = -2.25x - 2|x'|
\]

for wet tissue paper strip 2, and analogously.
2x''=-4.84x-4|x'|x' (14) for wet tissue paper strip 2 or
x''=-2.42x-2|x'|x' (15) for wet tissue paper strip 2.

Then we set y=x' and the above equations became
y''=-2.25x-2y|y| (16) for wet tissue paper strip 1 and
y''=-2.42x-2y|y| (17) for wet tissue paper strip 2.

For the solution of the above system, we applied the method of Runge-Kutta fourth class with
f(t, x, y)=y (18)

And for each wet soft paper strip we had the equations
g(t,x,y)=-2.25x-2y|y| (19) and pace h=0.5 in Matlab program for wet soft paper strip 1 and
g(t,x,y)=-2.42x-2y|y| (20) and pace h=0.5 in Matlab program for wet soft paper strip 2.

Application in the mechanics of the system of the Runge-Kutta method for finding the position x and the velocity y of the body bound in the wet strip of soft roll paper sample 1 with pace h=0.5s. From the execution in MATLAB program, the solution for the wet soft paper strip 1 of Figure 7a resulted. The solution also for the position x and the velocity y of the body at the time t=5s for paper sample strip 1 was:

x(5)=0.1496m=14.96cm and
u(5)=y(5)=0.0791m/s

Figure 7a: The blue line is the position x in m of the wet paper sample strip 1, and u in m/s the red line is the velocity of the wet paper sample 1 with pace h=0.5s.

Figure 7b: The blue line is the position x in m of the wet paper sample strip 1, and u in m/s the red line is the velocity of the wet paper sample 1, and the grey line is the energy E in Joules for the wet paper sample strip 1, where K=2.25N/m was the spring’s force, with time interval t=0.25s, and pace h=0.5s.
Also, the graph with the solution of Figure 7b resulted where the Energy in Joules for the wet paper strip 1 is also presented. The graph with the grey line for the Energy in Joules of the system was constructed for all the solutions for the position and the velocity of the body for time 0s to 5s. The code in MATLAB for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class is presented in Figure 8. The solution of the code in MATLAB for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class is also presented with pace h=0.5s in Figure 9. Application in the mechanics of the system of the Runge-Kutta method for finding the position and the velocity of the body bound in the wet strip of the soft roll paper sample 2 with pace h=0.5s. From the execution in MATLAB program the solution for the wet soft paper strip 2 of Figure 10a resulted.

```
>> clear x y t;
>> h=0.25;
>> N=20;
>> t(1)=0;
>> x(1)=2;
>> y(1)=0;
>> for i=1:N
   a1=h*y(i);
   b1=h*(-2.25*x(i)-2*y(i)*abs(y(i)));
   tq=t(i)+0.5*h;
   xq=x(i)+0.5*a1;
   yq=y(i)+0.5*b1;
   a2=h*yq;
   b2=h*(-2.25*xq-2*yq*abs(yq));
   xq=x(i)+0.5*a2;
   yq=y(i)+0.5*b2;
   a3=h*yq;
   b3=h*(-2.25*xq-2*yq*abs(yq));
   yq=y(i)+a3;
   yq=y(i)+b3;
   a4=h*yq;
   b4=h*(-2.25*xq-2*yq*abs(yq));
   x(i+1)=x(i)+1/6*(a1+2*a2+2*a3+a4);
   tq=t(i)+h;
   y(i+1)=y(i)+1/6*(b1+2*b2+2*b3+b4);
   t(i+1)=t(i)+h;
end
```

**Figure 8:** The code in matlab for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class is presented above.
The solution is in matlab

```
x = 2.0000 1.8725
y = 0 -0.9354
x = 2.0000 1.8725 1.5864
y = 0 -0.9354 -1.2577
x = 2.0000 1.8725 1.5864 1.2682
y = 0 -0.9354 -1.2577 -1.1681
x = 2.0000 1.8725 1.5864 1.2682 0.9649
y = 0 -0.9354 -1.2577 -1.1681 -1.0408
x = 2.0000 1.8725 1.5864 1.2682 0.9649 0.6903
y = 0 -0.9354 -1.2577 -1.1681 -1.0408 -0.9034
x = 2.0000 1.8725 1.5864 1.2682 0.9649 0.6903 0.4488
y = 0 -0.9354 -1.2577 -1.1681 -1.0408 -0.9034 -0.7623
x = 2.0000 1.8725 1.5864 1.2682 0.9649 0.6903 0.4488 0.2419
y = 0 -0.9354 -1.2577 -1.1681 -1.0408 -0.9034 -0.7623 -0.6198
x = 2.0000 1.8725 1.5864 1.2682 0.9649 0.6903 0.4488 0.2419 0.0702
y = 0 -0.9354 -1.2577 -1.1681 -1.0408 -0.9034 -0.7623 -0.6198 -0.4765
x = 2.0000 1.8725 1.5864 1.2682 0.9649 0.6903 0.4488 0.2419 0.0702 -0.0659
y = 0 -0.9354 -1.2577 -1.1681 -1.0408 -0.9034 -0.7623 -0.6198 -0.4765 -0.1564
x = 2.0000 1.8725 1.5864 1.2682 0.9649 0.6903 0.4488 0.2419 0.0702 -0.0659 -0.1564 -0.2310
y = 0 -0.9354 -1.2577 -1.1681 -1.0408 -0.9034 -0.7623 -0.6198 -0.4765 -0.3325 -0.1877
```

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Figure 9: The solution of the code in matlab for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class is also presented above with pace h=0.5s.
**Figure 10a:** The blue line is the position $x$ in m of the wet paper sample strip 2 and $u$ in m/s, the red line, is the velocity of the wet paper sample 2 with pace $h=0.5s$.

**Figure 10b:** The blue line is the position $x$ in m of the wet paper sample strip 2 and $u$ in m/s, the red line, is the velocity of the wet paper sample 2, and the grey line is the energy $E$ in Joules for the wet paper sample 2 where $K=2.42N/m$ was the spring's force, with time interval $t=0.25s$, and pace $h=0.5s$. Also the graph with the solution of Figure 10b resulted where the energy in Joules for the wet paper strip 2 was also presented. The graph for the energy with the grey line was constructed for all the solutions for the position and the velocity of the body from time $0s$ to $5s$. The code in MATLAB for the solving of the system for wet paper sample 2 with the method Runge-Kutta fourth class was as in Figure 11. The solution of the code in MATLAB for the solving of the system for wet paper sample 2 with the method Runge-Kutta fourth class is also presented in Figure 12.

From the execution the solution of Figure 10a resulted, as well as and that for the position and the velocity of the body at the time $t=5s$ which were for paper sample strip 2:

- $x(5)=0.1585m=15.85cm$ and
- $u(5)=y(5)=0.0147m/s$
Figure 11: The code in matlab for the solving of the system for wet paper sample 2 with the method Runge-Kutta fourth class and pace h=0.5s is presented above.
The solution in matlab is:

```matlab
x =
   2.0000  1.8638
   0.9934
   2.0000  1.8638  1.5628
   0.9934  1.5100
   2.0000  1.8638  1.5628  1.2334
   0.9934  1.5100  -1.3022
   2.0000  1.5600  1.5628  1.2334  0.9223
   0.9934  1.5100  -1.3022  -1.1936
   2.0000  1.8638  1.5628  1.2334  0.9223  0.6430
   0.9934  1.5100  -1.3022  -1.1936  -1.0544
   2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997
   0.9934  1.5100  -1.3022  -1.1936  -1.0544  -0.9055
   2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938
   0.9934  1.5100  -1.3022  -1.1936  -1.0544  -0.9055  -0.7532
   2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938  0.0259
   0.9934  1.5100  -1.3022  -1.1936  -1.0544  -0.9055  -0.7532  -0.5995
   2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938  0.0259  -0.1038
   0.9934  1.5100  -1.3022  -1.1936  -1.0544  -0.9055  -0.7532  -0.5995  -0.4450
   2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938  0.0259  -0.1038  -0.1950
   0.9934  1.5100  -1.3022  -1.1936  -1.0544  -0.9055  -0.7532  -0.5995  -0.4450  -0.2096
   2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938  0.0259  -0.1038  -0.1950  -0.2475
   0.9934  1.5100  -1.3022  -1.1936  -1.0544  -0.9055  -0.7532  -0.5995  -0.4450  -0.2896  -0.1334

x = Columns 1 through 12
2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938  0.0259  -0.1038  -0.1950  -0.2475
Column 13
-0.2610

y = Columns 1 through 12
0.9934  -1.3100  -1.3022  -1.1936  -1.0544  -0.9055  -0.7532  -0.5995  -0.4450  -0.2096  -0.1334
Column 13
0.0242

x = Columns 1 through 12
2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938  0.0259  -0.1038  -0.1950  -0.2475
Columns 13 through 14
-0.2610  0.3561

y = Columns 1 through 12
0.9934  -1.3100  -1.3022  -1.1936  -1.0544  -0.9055  -0.7532  -0.5995  -0.4450  -0.2096  -0.1334
Columns 13 through 14
0.0242  0.1717

x = Columns 1 through 12
2.0000  1.8638  1.5628  1.2334  0.9223  0.6430  0.3997  0.1938  0.0259  -0.1038  -0.1950  -0.2475
```
Figure 12: The solution of the code in matlab for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class is also presented above.
Application in the mechanics of the system of the Runge-Kutta method for finding the position and velocity of the body bound in the wet strip of the soft roll paper sample 1 with pace 0.25s. From the execution in MATLAB program the solution for the wet soft paper strip 1 with pace h 0.25s of Figure 13a resulted. Also, the graph with the solution of Figure 13b resulted where the energy in Joules for the wet paper strip 1 was also presented. The graph for the energy with the grey line was constructed for all the solutions for the position and the velocity of the body from time 0s to 5s.

For the solution of this system, we have applied the method of Runge-Kutta fourth class with pace h=0.25s

\[ f(t, x, y) = y \] (18)

\[ g(t, x, y) = -2.25x - 2y|y| \] (19) and with pace h=0.25s in the Matlab program

\[ g(t, x, y) = -2.42x - 2y|y| \] (20) and with pace h=0.25s in the Matlab program

Then the graphical representation of its position and velocity for 0\( t \)\(<5s\) was drawn.

From the execution the solution of Figure 13a resulted, as well as and that for the position and the velocity of the body at the time \( t = 5s \) which were for paper sample strip 1

\[ x(5) = 0.1927m = 19.27cm \] and

\[ u(5) = y(5) = 0.0548m/s \]

**Figure 13a:** The blue line \( x \) in m is the position of the wet paper sample strip 1 and \( u \) in m/s the red line is the velocity of the wet paper sample 1 with pace h=0.25s.

**Figure 13b:** The blue line is the position \( x \) in m of the wet paper sample strip 1, and \( u \) in m/s the red line is the velocity of the wet paper sample 1, and the grey line is the energy \( E \) in Joules for the wet paper sample strip 1, where \( K=2.25N/m \) is the spring’s force, with time interval \( t=0.25s \), and pace h=0.25s.
Figure 14: The code in MATLAB for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class and with pace $h=0.25s$ is presented above.

The code in MATLAB for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class and with pace $h=0.25s$ was as presented in Figure 14.

The solution of the code in MATLAB for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class with pace $h=0.25s$ is also presented in Figure 15.
| x      | y      |
|--------|--------|
| 2.0000 | 1.9990 |
| 0      | -0.9977|
| 2.0000 | 1.9990 |
| 1.6014 | 0      | -1.9309|
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 |
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 |
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173|
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412|
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|-0.2633|
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|-0.2633| Column 13
| 0.2886|
| y      | Column 1 through 12
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|-0.2633|
| Column 13|
| -0.2886|
| x      | Column 1 through 12
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|-0.2633|
| Column 13 through 14
| -0.2886| -0.2740|
| y      | Column 1 through 12
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|-0.2633|
| Column 13 through 14
| 0.0046| 0.1632|
| x      | Column 1 through 12
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|-0.2633|
| Column 13 through 15
| -0.2886| -0.2740| -0.2223|
| y      | Column 1 through 12
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0      | -0.9977|-1.3255|-1.9360| -1.0527
| 2.0000 | 1.9990 |
| 1.6014 | 1.2832 |
| 0.9646 | 0.6795 | 0.4302 | 0.2173 | 0.0412 | -0.0990|-0.1997|-0.2633|
| Column 13 through 15
| 0.0046| 0.1632| 0.2897|
Figure 15: The solution of the code in matlab for the solving of the system for wet paper sample 1 with the method Runge-Kutta fourth class with pace h=0.25s is also presented above.
Application in the mechanics of the system of the Runge-Kutta method for finding the position and velocity of the body bound in the wet strip of the soft roll paper sample 2 with pace $h=0.25s$. From the execution in MATLAB program the solution for the wet soft paper strip 2 of Figure 16a resulted. Also, the graph with the solution of Figure 16b resulted where the energy in Joules for the wet paper strip 2 was also presented. The graph for the energy with the grey line was constructed for all the solutions for the position and the velocity of the body from time $0s$ to $5s$.

$$g(t,x,y)=-2.42x-2y|y| \ (20)$$

and with pace $h=0.25$ in Matlab program

From the execution the solution of Figure 16a resulted, as well as and that for the position and the velocity of the body at the time $t=5s$ which are for paper sample strip 2

$x(5)=0.2008m=20.08cm$ and

$u(5)=y(5)=-0.0284m/s$

The code in MATLAB for the solving of the system for wet paper sample 2 with the method Runge-Kutta fourth class was as presented in Figure 17. The solution of the code in MATLAB for the solving of the system for the wet paper sample 2 with the method Runge-Kutta fourth class with pace $h=0.25s$ is also presented in Figure 18.
Figure 17: The code in matlab for the solving of the system for wet paper sample 2 with pace h=0.25s with the method Runge-Kutta fourth class is presented above.
Figure 18: The solution of the code in matlab for the solving of the system for the wet paper sample 2 with the method Runge-Kutta fourth class with pace h=0.25s is also presented above.
Finally, the benefit of having the above two approximations to the results was the extrapolation calculated below which was used to obtain the best estimate of the solutions we had obtained for the position of the body attached to the wet soft paper strips. Since the Runge-Kutta method was accurate through $h^5$, the two solutions were combined to eliminate the first term of the error ($\sim h^5$) and $x(h)$ and $x(h/2)$ were the two solutions for the position of the body at the time $t=5s$, with $paxeh=0.5s$ and $h/2=0.25s$ respectively. The extrapolated values were found as the formula:

$$x_{\text{extrapolated}} = \frac{1}{2} (x(h) + x(h/2)).$$

where $h$ was the size of the step. To verify the accuracy of the method we used Richardson’s extrapolation \[40\] and we obtained the below approximations and a better estimate of the respective derivatives. For the soft paper sample 1 the position of the body $x_{\text{extrapolated}}$ was then found \[23,25,26\]

$$x_{\text{extrapolated}} = \frac{15}{16} (19.27 - 14.96 - 19.615 - 20.08).$$

For the soft paper sample 2 the position of the body $x_{\text{extrapolated}}$ was then found \[23,25,26\]

$$x_{\text{extrapolated}} = \frac{15}{16} (16.20 - 15.85 - 20.08).$$

Conclusion

In this work we used an optical microscope to examine the cellulose contents of two soft paper samples which were identified as chemical pulps using the Herzberg staining test. The role of cellulose was to impart the mechanical properties of the two papers which were tested with a tensile-strength machine of 50N. The micro-tensile system used was well suited for measuring the mechanical properties of thin paper samples with large strain (>5%). Then we calculated above the solution of the system of the two wet paper sample strips with a body attached to them, an oscillating horizontally problem, involving two ordinary differential equations (16) and (17), and with two different step sizes $h$ and $h/2$. We have compared the results for the velocity of the body tied to the two wet soft paper strips made from cellulose which were tested for their tensile strength. The easiest way to accomplish the comparison of the accuracy of that solution was to use the step sizes $h$ and $h/2$. As a check on the accuracy, the calculations were repeated for the two different step sizes and the results were compared. We also have calculated the Richardson’s extrapolated values of the derivatives.

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