Ultra High Transmission Capacity of Undersea Optical Fiber Cables for Upgrading UW-WDM Submarine Systems

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Abstract

This paper has proposed ultimate optical transmission of ultra multi transmission channels huge submarine cables has been investigated under different depth conditions. Conventional forward Raman amplification technique is considered taking into account the reduction of the four wave mixing (FWM). The double impact of both ambient temperature and pressure effects are also investigated. The transmission technique is studied namely Soliton propagation technique. As well as two multiplexing methods are considered in the design namely ultra wide wavelength division multiplexing (UW-WDM) and ultra-wide space division multiplexing (UW-SDM). Based on experimental data, both the deep ocean water temperature and pressure are tailored as functions of the water depth. The product of the transmitted bit rate and the repeater spacing is processed over wide ranges of the affecting parameters.

Keywords

Four Wave Mixing, Submarine Systems, Multiplexing Techniques, Soliton Propagation and Undersea Depths

1. Introduction

To realize a long-haul high bit rate 1.5 μm undersea lightwave transmission system, the solution is to develop both a single longitudinal mode laser diode (LD) and dispersion shifted fiber to negate the effect of large chromatic dispersion in conventional fiber at 1.5 μm[1]. In developing submarine optical fiber cable for 1.5 μm operation, the increased sensitivity to bending loss during cabling and laying operations must be carefully considered. In addition a high accuracy measurement technique of optical loss and chromatic dispersion for the purpose of investigating long-length and high-bit-rate transmission potential must be established[2]. Compared with the conventional coaxial undersea cable systems, an optical fiber undersea cable system has a great technical and economical advantage. It is also suitable for digital transmission. Coaxial undersea cable systems have been used as one of the major transmission systems in international telecommunication networks over the past 25 years, and its channel capacity has rapidly been increased about ten times per decade with the growth in overseas traffic. However, this system has nearly reached a limit in its ability to increase the capacities of long-haul transoceanic systems from the standpoint of reliability and economy, although additional growth may be permitted with short-haul cable systems. On the other hand, the research and development on optical fiber communication systems progressed remarkably in the 1970’s, and a number of systems using 0.85μm wavelength have already been put into commercial services. Recently, the experimental systems using long wavelength and single-mode fibers are now actively being developed worldwide[3].

The first undersea lightwave cable system installed in the Pacific Ocean was the third trans-pacific cable (TPC-3) system. The characteristic features of the TPC-3 system were 1.3μm signal wavelength, about 50 km repeater spacing, and the transmission bit rate of 280 Mbit/sec. The second system was the fourth trans-pacific cable (TPC-4) system and the technical features of this system were 1.55 μm signal wavelength, about 120 km repeater spacing, and the transmission bit rate of 560 Mbit/sec. Both systems were using 3R optical repeaters for the optical signal transmission. This type of the optical repeater had three functions as retiming, reshaping, and regenerating of the optical signal, and these functions were realized by the monolithically integrated electrical circuit. At present there are several plans to install the lightwave cable system employing optical amplifiers[4]. Until the middle of 1990's, the fifth trans-Pacific cable network (TPC-5 CN) system was installed in the Pacific Ocean, and the twelfth and the thirteenth trans-Atlantic cable (TAT-12, 13) was installed in the...
Atlantic Ocean. These systems have the line bit rate of 5 Gbit/sec that is about eight times as much as that of the latest undersea systems using 3R repeaters[5]. The design of submarine cables is shaped by the submarine environment, which is very different than the environment for terrestrial cables. The underwater environment is very stable, very extreme, and very hard to reach. Repairs of undersea cables are difficult and expensive, so systems are designed to operate without service for long periods. Specifications usually call for no more than two underwater repairs in a cable's nominal 25 year life time, and the target is no repairs. Electrical power must be transmitted from the cable termination points on land, so power is at a premium. Early systems used repeaters, but since the mid-1990s all submarine cables have used only optical amplifiers underwater[6]. Full "three-R" regeneration, reshaping and retiming pulses as well as reamplifying them is done only at the cable termination points on shore. For intercontinental cable systems spanning thousands of kilometers, this imposes very stringent requirements on shore. For intercontinental cable systems, fully electronic components subject to failure, and because water pump lasers mark a key dividing point because they include optical amplifiers with their pump lasers in the cable, which are buried to protect them from fishing trawlers and ships' anchors—the undersea counterparts of backsplashes. If undisturbed, the cable structure should withstand intense pressures and exclude salt water for decades[7]. Optical amplifiers are mounted inside pressure-resistant cases originally developed to house repeaters. They are built into the cable but are larger in diameter, so at first glance they resemble a rabbit swallowed by a python. Submarine cable developers still call these cases "repeaters," but don't be fooled-repeaters have not been used on submarine cables for several years (although the repeaters on old cables have not been replaced). Submarine cables fall into two broad classes, unrepeatered and repeatered in the world of submarine cables, these terms define whether or not the system includes optical amplifiers with their pump lasers in the same underwater housing as the optical amplifier. Underwater pump lasers mark a key dividing point because they are electronic components subject to failure, and because they require electrical power to be transmitted through the cable. These two types can be further subdivided according to the distance they span and their configuration, but we will concentrate on the basic categories[8].

In the present study, we have investigated submarine cables to meet extremely tough requirements. Their transmission capacity should be as high as possible, because the cables are costly to make, lay, and operate. The cable, and any optical amplifiers or repeaters, must withstand harsh conditions on the bottom of the ocean for a design life of multi years. As well as we have modeled the integrated problem of optical undersea fiber cable, taking into account the effect of depth. The integrated problem is the product of the transmitted bit-rate and the repeater spacing where the following multiplexing technique is employed such as soliton propagation technique, two ultra multiplexing arrangements [ultra wide wavelength division multiplexing (UW-WDM) and ultra wide space division multiplexing (UW-SDM)], where ultra multi channels are transmitted through multi optical fiber links. Moreover forward Raman amplification method is employed, and the problem of four-wave mixing is reduced by increasing the channel spacing.

2. System Modeling Analysis

Based on reported data of[9], the pressure-dependent Sellmeier coefficients and material dispersions for silica fiber glass will be cast under the form:

\[ n^2(\lambda, T, P, x) = n_0^2(\lambda, T, x) f(\lambda, P) \]  \hspace{1cm} (1)

Where \( n \) is the core refractive index, \( \lambda \) is the optical wavelength, \( T \) is the ambient temperature, \( P \) is the pressure in Mega Newton/m², and \( x \) is the mole fraction of GeO₂, i.e. percentage of germania-doped silica fiber in Ref.[10] cast the following:

\[ n^2(\lambda, P) = A + \frac{B\lambda^2}{\lambda^2 - C} + \frac{D\lambda^2}{\lambda^2 - E} \]  \hspace{1cm} (2)

With: \( A_0 = 1.29552 + 9.86385 \times 10^{-6} P + 0.544763 \times 10^{-6} P^2 \), \( B_0 = 0.809872 + 42.0899 \times 10^{-6} P - 1.71823 \times 10^{-6} P^2 \), \( C_0 = 1.07945 \times 10^{-2} - 0.56693 \times 10^{-8} P + 0.894313 \times 10^{-10} P^2 \), \( D_0 = 0.917151 + 38.7911 \times 10^{-6} P - 1.13552 \times 10^{-6} P^2 \), and \( E_0 = 943.2 \). A special software is designed to recast \( n(\lambda, P) \) under the form to account for the thermal effects, [11] recalling again Eq. (1) as follows:

\[ n^2(\lambda, T, P, x) = n_0^2(\lambda, T, x) f(\lambda, P) \]  \hspace{1cm} (3)

Where \( f(\lambda, P) \) is found to possess the form:

\[ f(\lambda, P) = 1 + R(\lambda, P) \]  \hspace{1cm} (4)

Where:

\[ R(\lambda, P) = \alpha + \beta \lambda + \gamma \lambda^2 \]  \hspace{1cm} (5)

Where \( \alpha = 1.2 \times 10^{-1} + 1.239 \times 10^{-5} P - 5.2 \times 10^{-9} P^2 \), \( \beta = 2.47 \times 10^{-6} - 7.4 \times 10^{-7} P + 3.44 \times 10^{-9} P^2 \), \( \gamma = 6.99 \times 10^{-9} + 1.95 \times 10^{-12} P - 1.04 \times 10^{-9} P^2 \). The thermal-dependent refractive index \( n(\lambda, T, x) \) is cast on the same spirit of[12].

\[ n^2(\lambda, T, x) = 1 + \sum_{n=1}^{\infty} \frac{A_1(T, x)}{\lambda^2 - A_2^2(T, x)} \]  \hspace{1cm} (6)

Where \( A_i \) (oscillator strength) are constant related to the number of particles in the material that can oscillate with wavelength \( \lambda \). Based on the data reported by[13] both the pressure, \( P \), MN/m², and the temperature, \( T \), in K, are correlated to the depth, \( D \), in km, as \( P = 9.9342 D_0 - 0.00912 D_2^2 + 0.00707323 D_0^3 \), where \( D_0 \leq 10 \) km, and \( T = 303 - 3.048 D_0 + 392.15 D_0^2 - 542.75 D_0^3 \), where 0.0 \( \leq D_0 \), km \( \leq 0.5 \), and \( T = 283.6 - 10.313 D_0 + 4.8422 D_0^2 - 1.1622 D_0^3 \), where 0.5 \( < D_0 \), km \( \leq 5.5 \). Eq. (11) is the corner stone in the
computation of the dispersion effects and consequently the system capacity. Based on Eq. (1), on can get:

\[ n(\lambda, T, x) = n(\lambda, T, x) \sqrt{f(\lambda, T, x)} \]  

but as before \( f(\lambda, P) = 1 + R(\lambda, P) \), and \( R(\lambda, P) \) is defined by Eq. (9), then

\[ f(\lambda, P) = [1 + R(\lambda, P)]^{0.5} = 1.0 + 0.5 R(\lambda, P) \text{ for } R(\lambda, P) < 1.0. \]  

Based on the models of Refs. [13,14], the total chromatic spreading of a single mode fiber, \( D_s \), depends on \( n(\lambda, T, x) \) and its four first derivatives \( n', n'', n''', \) and \( n'''' \) w.r.t. \( \lambda \), respectively, are listed in Ref. [15].

### 2.1. Soliton Transmission Technique

Soliton transmission is an alternative to the usual methods of transmitting a series of amplitude modulated digital pulses through a fiber-optic system. A laser source can generate a series of soliton pulses, \( B_{rs} \). Thus the presence of a fiber can mean a "1" and the absence can indicate a "0". Note that solitons must be spaced a certain distance apart to keep them from interfering with each other and that their return to "0" at the end of the pulse makes this signal RZ coded. The repeater spacing "R," has no effect, as we get "\( B_{rs} \)" a distance-free quantity[15] as:

\[ P_{rs} = 0.597 \left( \frac{\sigma}{1.54} \right) \left( \frac{\lambda}{20} \right) \left( \frac{25.10^{10}}{n_{rs}} \right) \]  

Where \( P_{rs} \) is the initial pulse power of the \( i \)-th channel in Watt, \( \tau \) is the initial optical pulse broadening in psec, \( \sigma_\lambda \) is the total chromatic dispersion coefficient in psec/(km.nm), \( B_{rs} \) is the soliton bit rate of the \( i \)-th channel, \( A_e \) is the effective cross section area of the guided mode in \( \mu m^2 \), and \( n_{rs} \) is the nonlinear refractive index coefficient (the Kerr coefficient). For pure silica \( n_{rs} = 3.2 \times 10^{10} \) m²/Watt, while for Germania doped silica \( n_{rs} = 3.2 \times 10^{10} \) (1.0+81294x-16.6123x²+45.9808x³) in m²/Watt. The effective cross section area of the guided mode \( A_e \), is:

\[ A_e = \frac{\pi}{2} (R_1^2 + R_2^2) \]  

where \( R_1 \) and \( R_2 \) are the mode field radii of the two light waves with two wavelengths \( \lambda_1 \) and \( \lambda_2 \) respectively coupled with each other[16] and are given by:

\[ R_{k\lambda} = 0.21 \lambda_k^{0.5} / \sqrt{\Delta n} \]  

Where \( \Delta n \) is the relative refractive index difference. In the case of a nonlinear dispersive medium, solitary waves (unchanged propagating shape) result from the balance between nonlinearity and dispersion. These solitons represent the natural eigenstates of nonlinear pulse propagation in single mode fibers, and they can easily be excited provided the initial peak power is above certain threshold. Based on the analysis of [17] the peak power is given by

\[ P_{peak} = \frac{3.09 \lambda_0^2 A_e}{4 \pi^2 c n_{rs} \tau} \]  

For light soliton \( D_l \) must possesses positive value i.e., \( \lambda \) is above the zero-dispersion wavelength. It was suggested[17] that the predominance of soliton systems can be enhanced by using optical amplifiers as a means of in-line regeneration and pulse reshaping. Based on the analysis of [18], the minimum separation for a stream of soliton pulses to carry useful data is \( \tau_{min} = 10 \) t. This is due to the pulse broadening. The Soliton transmitted bit rate per channel \( (B_{rsch} = 1/\tau_{min}) \) then, \( \tau = 1/10 B_{rsch} \). With soliton bit rate per link \( B_{rs}=B_{rsch} N_l \).

### 2.2. Forward Raman Amplification

For forward Raman amplification over a transmission distance \( L_t \), the signal power \( P_{si} (i = 1, 2,..., N) \) and the Raman pump power \( P_R \) are injected at \( Z = 0 \) and travel in the +Z direction. The differential equations governing the signals and pump propagation are given by[65]:

\[ \frac{dP_{si}(Z)}{dZ} = \left[ -\sigma_s + \sum_{i=1}^{N} \sigma_s \frac{A_i}{A_e} P_{si}(Z) \right] P_{si}(Z) \]  

\[ \frac{dP_{R}(Z)}{dZ} = \left[ -\sigma_s + \sum_{i=1}^{N} \sigma_s \frac{A_i}{A_e} P_{si}(Z) \right] P_{R}(Z) \]  

Where \( \sigma_s \) is the scattering loss \( (0.75 + 66 \Delta n) \lambda^4 \) dB/km, \( \sigma_s \) is the intrinsic loss \( -0.03 \) dB/km, \( \sigma_{IR} \) is the infrared loss \( 49 \times 10^{10} \exp(-48\lambda) \) dB/km, and \( \sigma_{UV} \) is the ultraviolet loss \( [0.0132 x(1 + 0.733 x)] \exp(4.9/ \lambda) \) dB/km, where \( x \) is the mole fraction of GeO\(_2\), i.e. percentage of germania-doped silica fiber. Where \( \lambda_{IR} < \lambda_{UV} < < \lambda_{N} \) of the N channels are equally spaced in frequency domain with channel spacing \( \Delta \). Assuming the polarization of the fiber is maintained. The second term in Eqn. (14) denotes the coupling between the \( i \)-th signal and the pump, the third and the last terms express the cross coupling among the signal channels. To achieve high amplifier gain, the signal frequencies should be chosen so the \( g_i \) is comparable to \( g_i \) and \( \Delta \) should not be too large. Therefore \( g_i \) can be much larger than the cross coupling coefficient among the signal channels \( g_i \) to reduce cross talk. By applying an equivalent Raman gain constant approximation to all the signal channels, thus \( a \) and \( dP_{si}(Z) \) and \( dP_{R}(Z) \) are analytically solvable. The analytical expression of \( P_{si}(Z) \) and \( P_{R}(Z) \) are obtained as[21]:

\[ P_{si}(Z) = \frac{P_{R}}{1 + B \exp \left[ K \left( 1 - e^{-\alpha_{IR} Z} \right) \right]} \]  

\[ P_{R}(Z) = \frac{S_R \exp \left[ K \left( 1 - e^{-\alpha_{IR} Z} \right) \right] e^{-\alpha_s Z}}{1 + B \exp \left[ K \left( 1 - e^{-\alpha_{IR} Z} \right) \right]} \]  

Where: \( M = P_R + P_{ST} \) (Forward Raman pumping power +
Total signals power, \( P_{SF} = \sum_{i=1}^{N} \frac{\lambda_i}{\lambda_i} P_{sio} \), \( B = \frac{P_{SF}}{P_R} \),

\[
K = \frac{g M}{\sigma A_e}, \quad K_i = \frac{g_i M}{\sigma A_e}, \quad \text{and} \quad \phi = \frac{g_i}{g}.
\]

There are two approaches for the calculation of \( g \). The first one is due to[22]. The employed one is due to the work of[22] where:

\[
g_i = g_{i1} + g_{i2} (\lambda - \lambda_i)
\]

Where \( i = \{1, 2, 3, 4\} \). In this approach, the signal power is processed on the same spirit of[23] we put:

\[
P_n(Z) = U_n(Z) e^{\sigma_n Z}
\]

Thus:

\[
\frac{dP_n(Z)}{dZ} = [U_n(Z) - U_n(Z) \sigma_n] e^{\sigma_n Z}
\]

Also

\[
\frac{dP_n(Z)}{dZ} = [W_n(Z) - W_n(Z) \sigma_n] e^{\sigma_n Z}
\]

The maximum repeater spacing \( R_{sm} \) is obtained at the condition: \( P_s(R_{sm}) \cong \) minimum available detectable emission power which occur at amplified spontaneous emission (ASE)[24] as follows:

\[
P_n(Z) = \frac{-\theta e^{\sigma_n Z}}{1 + \left( \frac{\theta}{U_{sio}} \right) e^{\sigma_n (1+\sigma_n Z)}}
\]

The light signal must be amplified before its level becomes equal or less than that of the ASE thus we have[25]:

\[
\text{ASE} = h f_{si} B_{eff}
\]

With

\[
R_{sm} = 0.5 \sqrt{\pi} \Delta f \left( \frac{g M}{\sigma A_e} \right)^{0.5}
\]

Where \( \Delta f \) is the noise bandwidth, \( h \) is the Planck's constant, and \( f_{si} \) is the signal frequency. With \( \Delta f = 300 \text{GHz} \), the ASE is of order 0.01 \( \mu \text{Watt} \). Thus, \( R_{sm} \) is the solution of[26]:

\[
D_f \cdot \text{ASE} = U_n \left( R_{sm} \right) e^{\sigma_n R_{sm}}
\]

Where \( D_f \) is a designed factor \( \geq 1.0 \).

3. Simulation Results and Performance Evaluation

We have investigated the transmission characteristics of underwater optical cables to handle the product of the transmission bit rate and the repeater spacing for a cable of 36000 channel and multi optical links (40 to 360 link). Two real cases of advanced division multiplexing and advanced transmission method is processed namely soliton with forward Raman amplification technique is applied. The following items are applied in our performance analysis as follows:

a) The total number of channel \( N_{ch,t} = 36000 \) transmitted channels is divided to subgroups equal to the number of links \( N_{ch,L} \) where each link will transmit \( N_{ch,L} = N_{ch,t}/N_L \).

b) Channels of each subgroup are selected and grouped to be transmitted in each link. As the channels start from \( \lambda_1 = 1.45 \mu \text{m} \) up to \( \lambda_2 = 1.65 \mu \text{m} \), then the initial channel of subgroup is \( \lambda_1 \) and the final one is \( \lambda_f \) where reduction of four wave mixing (FWM):

\[
\lambda_i(\lambda) = \lambda_i + (J_s - 1)(\lambda_2 - \lambda_i)/(N_{ch,t} - 1)
\]

\[
\lambda_f(J_s) = \lambda_i(J_s) + N_{ch,t} (\lambda_{ch,t} - 1)/(\lambda_2 - \lambda_i)/(N_{ch,t} - 1)
\]

Where: \( J_s \) is the order of a link (40,..., 360). The central channel in each subgroup is \( \lambda_c \) and is given by the sum of Eqs. (27) and (28) as the following:

\[
\lambda_c(J_s) = 0.5 \left[ \lambda_i(J_s) + \lambda_f(J_s) \right] = \lambda_i(J_s) + 0.5 N_{ch,t} (\lambda_{ch,t} - 1)/(\lambda_2 - \lambda_i)/(N_{ch,t} - 1)
\]

c) To prevent the channel interaction the power of each channel must not exceed \( P_{sio} \) [27-29] where:

\[
P_{sio} N_{ch,t} (N_{ch,t} - 1) \Delta f \leq 500, \text{Watt.GHz}
\]

With

\[
\Delta f = \Delta \lambda \sqrt{f} / \lambda_c = \Delta \lambda \left( \frac{f}{\lambda_c^2} \right)
\]

d) The summing and the averaging over the core \( N_{ch,b} \) are process to obtain Figure to estimate the average bit rate spacing, the average bit rate/channels, and finally the average product per channel.

e) The temperature \( T_0 \) (reference one) where \( T_0 = 300 \text{K} \). Thus the cable is designed at \( T_0 \) with squeezed dispersion \( D_p \), and special design parameters, and installed under water at depth any \( D_p \).

f) Finally, if the depth \( D_p \) is changed, consequently, both the temperature \( T(D_p) \), and the pressure \( P(D_p) \), will be varied according to the previous equations are listed in the above model. Consequently, thes changes will affect both the bit rate and the repeater spacing, i.e., the product.

In the present study, the following numerical data and ranges are processed: Nonlinear coefficient \( n_2 = 3.2 \times 10^{-20} \text{m}^2/\text{W} \) of pure silica fiber, total number of transmitted channels \( N_{ch,t} = 36000 \) channels, fiber radius, \( a = 5 \mu \text{m} \), water surface temperature, \( T_0 = 300 \text{K} \), number of links, \( N_L \), 40 \( \leq N_L \) \( \leq 360 \), the order of link, \( J_s \), 1 \( \leq J_s \) \( \leq 360 \), water depth, \( D_p \), 0.0 \( \leq D_p \) \( \text{km} \), source spectral width \( \Delta f = 0.1 \text{nm} \), operating optical signal wavelength, \( \lambda_c \), 1.45 \( \leq \lambda_c \) \( \mu \text{m} \), \( \leq 1.65 \), forward Raman pumping power \( P_R = 2 \text{Watt} \), and forward Raman pumping power wavelength, \( \lambda_R = 1.45 \mu \text{m} \). The causes for investigation are: the water depth, \( D_p \) (pressure and temperature), the operating wavelength, \( \lambda_c \), and the number of link \( N_L \) in SDM. While the effects under investigation are: the soliton bit rate \( B_{sio} \), and the repeater spacing, \( R_{sm} \), to squeeze that achieve a squeezed dispersion \( D_s \) at somewhat depth. Based on the above equations analysis in the basic model, the above set of the operating parameters, the following facts are assured based on the series of the set of the Figures. (1-10) as the following:

i) As shown in the series of Figures. (1, 2) have assured that as both number of links in the fiber cable core and underwater depths increase, this results in decreasing of spectral losses for both silica-doped and plastic based submarine fiber links. Moreover plastic fiber link has presented higher spectral losses than silica-doped fiber link.
Figure 1. Variations of the spectral losses against undersea depth at the assumed set of parameters.

Figure 2. Variations of the spectral losses against undersea depth at the assumed set of parameters.

ii) Figures. (3, 4) have demonstrated that as both number of links in the fiber cable core and undersea depths increase, this leads to increase in average repeater spacing for both silica-doped and plastic based submarine fiber links. Plastic fiber link has presented lower repeater spacing than silica-doped fiber link.

Figure 3. Variations of average repeater spacing against undersea depth at the assumed set of parameters.

Figure 4. Variations of average repeater spacing against undersea depth at the assumed set of parameters.

Figure 5. Variations of average soliton bit rate per channel versus number of links at the assumed set of parameters.

Figure 6. Variations of average soliton bit rate per channel versus number of links at the assumed set of parameters.

iii) As shown in the series of Figures. (5, 6) have indicated that as both number of links in the fiber cable core and undersea depths increase, this results in increasing of soliton transmission bit rates per transmitted channel for both silica-doped and plastic based submarine fiber links. As well as plastic fiber link has presented lower transmission soliton bit rates per transmitted channels than silica-doped fiber link.
iii) Figures. (7, 8) have demonstrated that as both number of links in the fiber cable core and undersea depths increase, this leads to increase in soliton transmission bit rates per optical link for both silica-doped and plastic based submarine fiber links. As well as plastic fiber link has presented lower transmission soliton bit rates per link than silica-doped fiber link.

iv) As shown in the series of Figures. (9, 10) have indicated that as both number of links in the fiber cable core and undersea depths increase, this results in increasing of soliton transmission bit rates per core for both silica-doped and plastic based submarine fiber links. As well as plastic fiber link has presented lower transmission soliton bit rates per fiber cable core than silica-doped fiber link.

4. Conclusions

The use of single mode fibers (with a core diameter of a few micrometers) was the more promising challenge to face. In addition, further progress in fiber manufacturing (mainly through better material purification) led to evidence of the second window around 1.3 μm, with an attenuation of about 0.4 dB/km. Moreover, the bulk silica chromatic dispersion vanishes close to 1.3 μm; it was therefore possible to propagate high transmission bit rate pulses with minimum pulse broadening. As well as the problem of Ultra Wideband Wavelength Division Multiplexing plus the problem of Ultra Wide Space Division Multiplexing in nonlinear submarine optical cables with conventional Raman amplification techniques are investigated through real transmission technique. The impact of tailoring of chirped pulses of different temporal waveforms is investigated in a normal dispersion fiber. The set of multiplexed signals are tailored in a different a subset to assure approximately the same output level of power to hold the signal to noise ratio at the same level. Moreover, soliton propagation is employed with cohere successive section of alternating dispersion are used also as a technique to manage the dispersion. Distributed "Raman" amplifiers is engaged to maximize the repeater spacing. It is theoretically found that the increased number of links in the fiber cable core and undersea depths, this result in increasing average repeater spacing and then to decrease the spectral losses within silica-doped and plastic based submarine fiber link. Moreover it is evident that the increased of both number of links and undersea depths, this leads to increase in transmission bit rates either per link or per channel and
then to increase transmission bit rates per fiber cable core. It is indicated that the silica-doped based submarine fiber link has presented lower spectral losses and higher both repeater spacing and soliton transmission bit rates either per link or per channel than plastic links.

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