SUPERCONSISTENCY OF TESTS IN HIGH DIMENSIONS

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To assess whether there is some signal in a big database, aggregate tests for the global null hypothesis of no effect are routinely applied in practice before more specialized analysis is carried out. Although a plethora of aggregate tests is available, each test has its strengths but also its blind spots. In a Gaussian sequence model, we study whether it is possible to obtain a test with substantially better consistency properties than the likelihood ratio (LR; i.e., Euclidean norm-based) test. We establish an impossibility result, showing that in the high-dimensional framework we consider, the set of alternatives for which a test may improve upon the LR test (i.e., its superconsistency points) is always asymptotically negligible in a relative volume sense.

1. INTRODUCTION

A major challenge in the current “big-data era” is to extract signals from huge databases. Often, an applied researcher proceeds in a two-step fashion: First, in order to decide whether there is any signal in the data at all, one performs an aggregate test of the global null hypothesis of no signal. This global null hypothesis is typically formulated as the high-dimensional target parameter being the zero vector. Second, if the global null hypothesis is rejected by the test, further analysis is undertaken to uncover the precise nature of the signal. Much research has been directed to studying properties of such a sequential rejection principle (cf. Romano and Wolf, 2005, Meinshausen, 2008, Romano, Shaikh, and Wolf, 2008, Rosenbaum, 2008, Yekutieli, 2008, Goeman and Solari, 2010, Heller et al., 2018, Bogomolov et al., 2020, and the references therein).

Using a powerful test for the global null hypothesis in the first step of such a hierarchical multistep procedure is of course crucial, and the development of tests for this hypothesis has therefore attracted much research in its own right. A typical choice, employed in, e.g., Heller, Meir, and Chatterjee (2019), is to use a test based on the Euclidean norm of the estimator. This also leads to the likelihood
ratio (LR) test in the Gaussian sequence model they considered, which is also the framework in the present article. Although the LR test is a natural choice, one may ask: Do tests for the global null exist that are consistent against substantially more alternatives than the LR test? This question is practically relevant, because one can choose from a large menu of well-established tests, yet precisely which one to use is not obvious: For example, one could use tests based on other norms than the Euclidean one, a natural class of tests being based on $p$-norms (cf. the classic monograph of Ingster and Suslina (2003)). One could also use a test based on combining different $p$-norms as suggested by the power enhancement principle of Fan, Liao, and Yao (2015) and in Kock and Preinerstorfer (2021). The possibility of increasing power by combining tests has recently been applied in many types of high-dimensional testing problems (cf. Xu et al., 2016, Yang and Pan, 2017, Yu, Li, and Xue, 2020, He et al., 2021, Yu et al., 2021 [testing high-dimensional means and covariance matrices]; Zhang, Wang, and Shao, 2021 [change point detection]; Jammalamadaka, Meintanis, and Verdebout, 2020 [tests for uniformity on the sphere]; Feng et al., 2022 [tests for cross-sectional independence in high-dimensional panel data models]). Another test that has gained popularity in recent years is the Higher Criticism. This test dates back to Tukey (1976), and its strong power properties against deviations from the global null were first exhibited by Donoho and Jin (2004) and have led to much subsequent research (cf. Donoho and Jin, 2009; Hall and Jin, 2010; Arias-Castro, Candès, and Plan, 2011; Cai, Jeng, and Jin, 2011; Barnett and Lin, 2014; Li and Siegmund, 2015; Arias-Castro and Ying, 2019; Porter and Stewart, 2020). Alternatively, one could use tests based on combining $p$-values for coordinatewise zero restrictions. Important early works include Tippett (1931), Pearson (1933), Fisher (1934), Stouffer et al. (1949), and Simes (1986). For a review of the classic literature, see Cousins (2007), more recent contributions are Owen (2009), Duan et al. (2020), and Vovk and Wang (2020, 2021). It is crucial to highlight here that many of the above mentioned tests are consistent against strictly more alternatives than the LR test, i.e., they dominate the LR test in terms of their consistency properties; indeed, this is the main motivation of the power enhancement principle. Hence, the question of interest in the present article is not whether one can do better than the LR test at all, but whether one can do substantially better.

We consider the question raised in the previous paragraph from a high-dimensional perspective. In the Gaussian sequence model, we investigate whether aggregate tests can be obtained that are consistent against substantially more alternatives than the LR test. We show that relative to a uniform prior on the parameter space this is impossible: Essentially, we prove that for any given test the set of alternatives against which it is consistent, but the LR test is not, has vanishing relative Lebesgue measure. Hence, no test for the global null hypothesis can substantially improve on the LR test. From a technical perspective, our proofs are based on results by Schechtman and Schmuckenschläger (1991) concerning the asymptotic volume of intersections of $p$-norm balls and on the concentration of measure phenomenon.
Our finding is perhaps reminiscent of Le Cam (1953), who showed (in finite-dimensional settings and sufficiently regular models) that the set of possible superefficiency points of an estimator relative to the maximum likelihood estimator cannot be larger than a Lebesgue null set (cf. also van der Vaart (1997) for more discussion, Leeb and Pötscher (2006, 2008) for further elucidation, and, e.g., Han, Phillips, and Sul (2011) for superefficiency-type results in a nonregular model, namely a nonstationary autoregression). Note that our result does not imply that one should always use the LR test and not think carefully about the choice of test in high-dimensional testing problems. If, for example, one is interested in particular types of deviations from the null, e.g., sparse ones, there may be good reasons to use a test based on the supremum norm or the Higher Criticism. Furthermore, albeit very natural, the magnitude of the consistency set is merely one of many properties that can be used to compare tests. For example, tests are also frequently compared in terms of, e.g., their minimax detection properties or their local power against deviations from the null of a specific type. Nevertheless, in analogy to Le Cam (1953), regardless of how cleverly an alternative test is designed, the amount of alternatives against which one achieves an improvement as compared to the LR test cannot be substantial in terms of relative volume. This also supports basing a combination procedure, such as the power enhancement principle by Fan et al. (2015), on the Euclidean norm.

2. FRAMEWORK AND TERMINOLOGY

We consider the Gaussian sequence model

$$y_{i,d} = \theta_{i,d} + \epsilon_i, \quad i = 1, \ldots, d, \quad (1)$$

where $y_{1,d}, \ldots, y_{d,d}$ are the observations, the parameters $\theta_{i,d} \in \mathbb{R}$ are unknown, $d \in \mathbb{N}$, and where the unobserved terms $\epsilon_i$ are independent and standard normal. Writing $y_d = (y_{1,d}, \ldots, y_{d,d})'$, $\epsilon_d = (\epsilon_1, \ldots, \epsilon_d)'$, and $\theta_d = (\theta_{1,d}, \ldots, \theta_{d,d})' \in \mathbb{R}^d$, one can equivalently state the model in (1) as $y_d = \theta_d + \epsilon_d$.

In the model (1), we are interested in the testing problem

$$H_{0,d} : \theta_d = 0_d \quad \text{against} \quad H_{1,d} : \theta_d \in \mathbb{R}^d \setminus \{0_d\}, \quad (2)$$

where $0_d$ denotes the origin in $\mathbb{R}^d$. The null hypothesis $H_{0,d}$ is typically referred to as the “global null” of no effect.

The asymptotic analysis in the Gaussian sequence model (1) relies on $d \to \infty$. This is a high-dimensional regime in the sense that the number of parameters, $d$, tends to infinity. For each $d \in \mathbb{N}$, we observe a single realization of a $d$-dimensional Gaussian vector $y_d$ with mean $\theta_d$ and identity covariance matrix. In this sense, the “sample size” is one for each $d$.

**Remark 2.1.** Although the Gaussian sequence model is an idealization, many fundamental issues of high dimensionality show up already here and insights obtained within this model carry over, at least on a conceptual level, to many
other settings. It is therefore widely recognized as an important prototypical framework in high-dimensional statistics (see, for example, Ingster and Suslina (2003), Carpentier and Verzelen (2019), Johnstone (2019), or Castillo and Roquain (2020)). To make this more precise, consider a situation where an estimator \( \hat{\beta}_d \) for a target parameter \( \beta_d \in \mathbb{R}^d \) is available the distribution of which is approximately normal, that is,

\[
\hat{\beta}_d \approx \mathcal{N}(\beta_d, \Omega_d),
\]

for \( \Omega_d \) invertible. Suppose further that an invertible estimator \( \hat{\Omega}_d \approx \Omega_d \) is at one’s disposal, such that

\[
\hat{\Omega}_d^{-1/2} \hat{\beta}_d \approx \mathcal{N}(\Omega_d^{-1/2} \beta_d, I_d).
\]

Then, testing \( \beta_d = 0_d \) on the basis of \( \hat{\beta}_d \) and \( \hat{\Omega}_d \) is approximated by testing \( \theta_d : \hat{\Omega}_d^{-1/2} \beta_d = 0_d \) in a Gaussian sequence model. Precise sets of conditions under which the above approximation statements hold depend on: (i) the formal meaning of the symbol “\( \approx \)”; (ii) the interplay of the dimension of the target parameter and the sample size used for computing \( \hat{\beta}_d \); and (iii) particularities of the specific setup under consideration. This has been a topic of intense research interest, and sets of sufficient conditions for normal approximations in high-dimensional models can be found in, e.g., Portnoy (1985), Portnoy (1988), He and Shao (2000), Bentkus (2003), or in more recent work such as Chernozhukov, Chetverikov, and Kato (2017) and Giessing and Fan (2020). Working directly with a Gaussian sequence model allows us to bypass normal approximation results, and to focus on conceptual issues that already arise in a somewhat idealistic setup. We leave extensions to other models (e.g., via the above approximation heuristic) to future research.

**Remark 2.2.** To illustrate Remark 2.1 with a simple relevant model, consider a linear regression model with nonstochastic design matrix \( X \), say, of full column rank \( d \), and i.i.d. Gaussian errors with known variance, which we normalize to one for simplicity. Then the OLS estimator is Gaussian with expectation \( \hat{\beta}_d \), the regression coefficient vector, and covariance matrix \( \Omega_d := (X'X)^{-1} \), which is known and can therefore be used as \( \hat{\Omega}_d \). Note that in this situation the approximation statements in Remark 2.1 actually hold with equality.

For a given \( d \in \mathbb{N} \), a (possibly randomized) test \( \varphi_d \), say, for (2) is a (measurable) function from the sample space \( \mathbb{R}^d \) to the closed unit interval. In the asymptotic framework we consider, we are interested in properties of sequences of tests \( \{\varphi_d\} \), where \( \varphi_d \) is a test for (2) for every \( d \in \mathbb{N} \). To lighten the notation, we shall write \( \varphi_d \) instead of \( \{\varphi_d\} \) whenever there is no risk of confusion. We are particularly interested in the consistency properties of sequences of tests. As usual, we say that a sequence of tests \( \varphi_d \) is consistent against the array of parameters \( \theta = \{\theta_d : d \in \mathbb{N}\} \), where \( \theta_d \in \mathbb{R}^d \) for every \( d \in \mathbb{N} \), if and only if (as \( d \to \infty \))

\[
\mathbb{E}(\varphi_d(\theta_d + \varepsilon_d)) \to 1.
\]
To every sequence of tests $\varphi_d$, we associate its consistency set $\mathcal{C}(\varphi_d)$, say. The consistency set $\mathcal{C}(\varphi_d)$ is the set of all arrays of parameters $\vartheta$ the sequence of tests $\varphi_d$ is consistent against. By definition,

$$\mathcal{C}(\varphi_d) \subseteq \bigotimes_{d=1}^{\infty} \mathbb{R}^d =: \Theta,$$

the latter denoting the set of all possible arrays of parameters.

Recall that a sequence of tests $\varphi_d$ is said to have asymptotic size $\alpha \in [0, 1]$ if

$$\mathbb{E}(\varphi_d(\epsilon_d)) \to \alpha.$$

In this article, following the Neyman–Pearson paradigm, we focus on the case where $\alpha \in (0, 1)$, which we shall implicitly assume in the discussions throughout unless mentioned otherwise.

It is well known that the LR test for (2) rejects if the Euclidean norm $\| \cdot \|_2$ of the observation vector $y_d$ exceeds a critical value $\kappa_{d,2}$ chosen to satisfy the given size constraint. That is, the LR test is given by $\mathbb{1}\{\| \cdot \|_2 \geq \kappa_{d,2}\}$. For notational simplicity, we abbreviate the sequence of tests $\{\mathbb{1}\{\| \cdot \|_2 \geq \kappa_{d,2}\}\}$ by $\{2, \kappa_{d,2}\}$ and thus write $\mathcal{C}(\{2, \kappa_{d,2}\})$ for its consistency set. The following result is contained in Ingster and Suslina (2003) (cf. also Theorem 3.1 in Kock and Preinerstorfer (2021) for extensions).

**Theorem 2.1.** Let $\kappa_{d,2}$ be a sequence of critical values such that the asymptotic size of $\{2, \kappa_{d,2}\}$ is $\alpha \in (0, 1)$. Then

$$\vartheta \in \mathcal{C}(\{2, \kappa_{d,2}\}) \iff d^{-1/2} \|\vartheta_d\|_2^2 \to \infty. \tag{4}$$

Theorem 2.1 shows that the consistency set of the LR test is precisely characterized by the asymptotic behavior of the Euclidean norms of the array of alternatives under consideration. That the consistency set of the LR test can be completely characterized in terms of the norm its test statistic is based on seems natural, but is quite specific to the LR test (see Theorem 3.1 and the ensuing discussion in Kock and Preinerstorfer (2021)).

**3. SUPERCONSISTENCY POINTS**

**3.1. Improving on the LR Test**

Although the LR test is a canonical choice of a test for the testing problem (2), there are many other reasonable tests available. For example, classic results by Birnbaum (1955) and Stein (1956) show that any test with convex acceptance region (i.e., the complement of its rejection region) is admissible. Anderson’s (1955) theorem implies that if the acceptance region is furthermore symmetric around the origin, then the test is also unbiased. Thus, any convex symmetric (around the origin) set delivers an admissible unbiased test, which is, hence, reasonable from a nonasymptotic point of view.
One class of tests that is intimately related to the LR test consists of tests based on other $p$-norms than the Euclidean one. For $x = (x_1, \ldots, x_d)' \in \mathbb{R}^d$ and $p \in (0, \infty]$, define the $p$-norm as usual via

$$
\|x\|_p = \begin{cases} 
\left( \sum_{i=1}^{d} |x_i|^p \right)^{\frac{1}{p}}, & \text{if } p < \infty, \\
\max_{i=1, \ldots, d} |x_i|, & \text{else.}
\end{cases}
$$

In analogy to the LR test, $p$-norm-based tests reject if the $p$-norm of the observation vector exceeds a critical value $\kappa_{d,p}$. Special cases, which have an established tradition in high-dimensional inference, are the 1-norm and the supremum norm. We shall denote the sequence of tests $\{\| \cdot \|_p \geq \kappa_{d,p} \}$ by $\{p, \kappa_{d,p}\}$. Clearly, $p$-norm-based tests are unbiased and admissible for $p \in [1, \infty]$ as a consequence of the discussion in the first paragraph of this section.

Concerning the consistency sets $C(\{p, \kappa_{d,p}\})$ of general $p$-norm-based tests, it is a somewhat surprising fact that:

(i) $C(\{p, \kappa_{d,p}\}) \subset C(\{q, \kappa_{d,q}\})$, for $0 < p < q < \infty$, i.e., strictly larger exponents $p$ result in strictly larger consistency sets;

(ii) this ranking does not extend to $q = \infty$, in the sense that there are alternatives the supremum norm-based test is not consistent against but against which any $p$-norm-based test with $p \in (0, \infty)$ is consistent and vice versa

(see Kock and Preinerstorfer (2021) for formal statements). From (i), it follows that any $p$-norm-based test with $p \in (2, \infty)$ has a strictly larger consistency set than the LR test. We stress that this asymptotic strict domination of the LR test in terms of consistency sets is not in contradiction to its admissibility for each $d \in \mathbb{N}$.

Other tests that strictly dominate the LR test can be obtained, e.g., through combination procedures that enhance the LR test with a sequence of tests $\eta_d$ that is sensitive against alternatives of a different “type” than the LR test in the sense that $C(\eta_d) \setminus C(\{2, \kappa_{d,2}\}) \neq \emptyset$.

To see how this can be achieved, note that the consistency set of the sequence of tests $\psi_d$, say, where $\psi_d$ rejects if the LR test or $\eta_d$ rejects, contains $C(\{2, \kappa_{d,2}\}) \cup C(\eta_d)$, and hence dominates the LR test in terms of consistency. Essentially, this is the power enhancement principle of Fan et al. (2015) (see Kock and Preinerstorfer (2019) for related results and cf. Preinerstorfer (2021) for a nonasymptotic version of the power enhancement principle). Note that if $\eta_d$ has asymptotic size 0, which is an assumption imposed on $\eta_d$ in the context of the power enhancement principle,

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1 Strictly speaking, $\| \cdot \|_p$ defines a norm on $\mathbb{R}^d$ only for $p \in [1, \infty]$ and a quasi-norm for $p \in (0, 1)$.

2 Recall that, throughout the present article, we implicitly impose the condition that all tests have asymptotic size in $(0, 1)$ if not otherwise mentioned.
nothing is lost in terms of asymptotic size when using $\psi_d$ instead of the LR test, because both sequences of tests then have the same asymptotic size.\footnote{If $\eta_d$ has a positive asymptotic size that is smaller than the asymptotic size targeted in the final combination test, one can work with an LR test with small enough asymptotic size in the combination procedure to obtain a test that dominates the LR test in terms of consistency (recall from Theorem 2.1 that the consistency set of the LR test does not depend on the specific value of the asymptotic size).}

To clarify how much can possibly be gained in terms of consistency by using a sequence of tests $\varphi_d$ other than the LR test, we shall consider the corresponding set

$$C(\varphi_d) \setminus C([2, \kappa_{d,2}]),$$

which we refer to as the superconsistency points of the sequence of tests $\varphi_d$ (relative to the LR test). Note that the set of superconsistency points is defined for any sequence of tests, regardless of whether it dominates the LR test or not (in the sense that its consistency set includes that of the LR test).\footnote{To provide an example, for any $p \in (2, \infty)$, the set of superconsistency points of the $p$-norm-based test is fully characterized by Corollary 3.2 in Kock and Preinerstorfer (2021) (cf. also their Theorem 3.4, which essentially shows that these superconsistency points are approximately sparse and have at least one large entry).} On a conceptual level, superconsistency points are related to superefficiency points of estimators relative to the maximum likelihood estimator in classic parametric theory.

### 3.2. The Relative Volume of the Set of Superconsistency Points

The central question we consider in this article is how “large” the set of superconsistency points $C(\varphi_d) \setminus C([2, \kappa_{d,2}])$ can possibly be for a sequence of tests $\varphi_d$ with asymptotic size in $(0, 1)$. Note that the larger $C(\varphi_d) \setminus C([2, \kappa_{d,2}])$ is, the larger is the set of alternatives the sequence of tests $\varphi_d$ is consistent against, but the LR test is not consistent against. Although we already know from the examples discussed in Section 3.1 that $C(\varphi_d) \setminus C([2, \kappa_{d,2}])$ is nonempty for many $\varphi_d$, we here investigate whether one can substantially enlarge the consistency set by using another test than the LR test.

To make the above question amenable to a formal treatment, note that Theorem 2.1 implies that for any sequence of LR tests $[2, \kappa_{d,2}]$ with asymptotic size $\alpha \in (0, 1)$, the complement of $C([2, \kappa_{d,2}])$ satisfies

$$\Theta \setminus C([2, \kappa_{d,2}]) \supseteq \bigotimes_{d=1}^{\infty} B_d^2(r_d),$$

if the sequence $r_d > 0$ is such that $r_d/d^{1/4}$ is bounded and where, for every $p > 0$, we denote by $B_p^d(r)$ the closed $p$-norm ball with radius $r$ centered at the origin. That is, the LR test is inconsistent against any element of $\bigotimes_{d=1}^{\infty} B_d^2(r_d)$. We now investigate how many inconsistency points of the LR test can be removed from any such benchmark $\bigotimes_{d=1}^{\infty} B_d^2(r_d)$ by erasing all superconsistency points of a sequence of tests $\varphi_d$. 
Formally, this is to be understood in the following sense: Let $\varphi_d$ be a sequence of tests with consistency set $C(\varphi_d)$, and let $r_d$ be such that $r_d/d^{1/4}$ is bounded. Let $D_d \subseteq B_d^2(r_d)$ be such that
\[
\bigotimes_{d=1}^{\infty} D_d \subseteq C(\varphi_d).
\]
Note that all elements of $\bigotimes_{d=1}^{\infty} D_d$ are superconsistency points of $\varphi_d$ which are also contained in the benchmark $\bigotimes_{d=1}^{\infty} B_d^2(r_d)$ (cf. the illustration in Figure 1). Denoting by $\text{vol}_d$ the $d$-dimensional Lebesgue measure, we investigate the asymptotic behavior of the relative volume measure
\[
\frac{\text{vol}_d(D_d)}{\text{vol}_d(B_d^2(r_d))}. \tag{5}
\]
Obviously, the ratio in (5) is a number in $[0,1]$. On the one hand, if this ratio is asymptotically close to 1, this means that, in terms of relative volume, many elements of the benchmark $\bigotimes_{d=1}^{\infty} B_d^2(r_d)$ are superconsistency points of the sequence of tests $\varphi_d$. That is, one can substantially improve upon the LR test by using $\varphi_d$ (or by combining the LR test with $\varphi_d$ through the power enhancement principle). On the other hand, if this ratio is asymptotically close to 0, this means that in terms of relative volume only few elements of the benchmark are superconsistency points of $\varphi_d$.

**Remark 3.1.** One could also study the asymptotic behavior of the sequences $\text{vol}_d(B_d^2(r_d)) - \text{vol}_d(D_d)$ or $\text{vol}_d(D_d)$ in order to determine whether one can substantially improve upon the LR test. However, these sequences both converge to 0. To see this, just note that
\[
\text{vol}_d(B_d^2(r_d)) = \frac{\pi^{d/2}}{\Gamma(d/2 + 1)} r_d^d \rightarrow 0,
\]
in case $r_d/d^{1/4}$ is bounded as a consequence of Stirling’s approximation to the gamma function as well as $D_d \subseteq B_d^2(r_d)$. Thus, such “absolute” volume measures are uninformative, since even the absolute volume of $B_d^2(r_d)$ tends to zero.
Remark 3.2. One may argue that, rather than (5), one should study
\[
\frac{\text{vol}_d(\mathbb{D}_d)}{\text{vol}_d(\text{proj}_d[\Theta \setminus \mathcal{C}((2, \kappa_{d,2})])]},
\]
\text{proj}_d(\cdot) \text{ denoting the projection onto the } d\text{th coordinate of its argument. However, since}
\[
\prod_{d=1}^{K} \mathbb{R}^d \times \prod_{d=K+1}^{\infty} \{0\} \subseteq \Theta \setminus \mathcal{C}((2, \kappa_{d,2})),
\]
for all } K \in \mathbb{N}, \text{ it follows that } \text{vol}_d(\text{proj}_d[\Theta \setminus \mathcal{C}((2, \kappa_{d,2})])] = \infty, \text{ for all } d \in \mathbb{N}.

We emphasize that using the (normalized) Lebesgue measure to assess the asymptotic magnitude of the set of superconsistency points is one among many possible choices. Other measures would be possible too, but the uniform prior over } \mathbb{B}_d^2(r_d) \text{ is a natural choice as in many situations there is no clear guidance concerning the type of alternative one wishes to favor.\textsuperscript{5}

Note that the ratio in (5) depends on two ingredients:
1. the benchmark } \prod_{d=1}^{\infty} \mathbb{B}_2^d(r_d);
2. the sequence of superconsistency points } \prod_{d=1}^{\infty} \mathbb{D}_d \text{ which depends on the sequence of tests } \varphi_d.

Therefore, one could suspect that the asymptotic behavior of (5) depends in a complicated way on the interplay between these two components. Nevertheless, it turns out that the asymptotic behavior of (5) has a simple description that does not depend on any of the two ingredients just described. In particular, we shall prove in Section 5 that the limit of the sequence is 0 for all sequences of tests } \varphi_d. Hence, it is impossible to improve on the LR test in terms of the magnitude of its consistency set apart from a set of superconsistency points that is negligible in a relative volume sense.

In Section 4, we shall first establish this result for } \varphi_d \text{ a sequence of } p\text{-norm-based tests with } p \in (2, \infty). \text{ Note that all these tests have a strictly larger consistency set than the LR test as discussed in Section 3.1. A general result, which also provides a rate of convergence, will be presented in Section 5.

4. \textit{p-NORM-BASED TESTS}

We now consider the asymptotic behavior of the sequence (5) for the special case where } \varphi_d \text{ is a sequence of } p\text{-norm-based tests with } p \in (2, \infty) \text{ being fixed. For this class of tests, we can exploit the characterization of their consistency sets provided in Theorem 3.1 and Corollary 3.2 of Kock and Preinerstorfer (2021), together with results from asymptotic geometry developed in Schechtman and

\textsuperscript{5}Our results remain valid if, instead of measuring the magnitude of } \mathbb{D}_d \text{ w.r.t. the uniform probability measure on } \mathbb{B}_2^d(r_d), \text{ one measures its magnitude w.r.t. the uniform probability measure on the Euclidean sphere of radius } r_d. \text{ We will comment on this in Remark 5.1, but will focus on the uniform distribution on } \mathbb{B}_2^d(r_d) \text{ throughout the article.}
Schmuckenschläger (1991) based on earlier results in Schechtman and Zinn (1990). These ingredients lead to a direct proof of the limit of the sequence in (5) being 0.

**Theorem 4.1.** Let \( p \in (2, \infty) \), and let the sequence of critical values \( \kappa_{d,p} \) be such that \( [p, \kappa_{d,p}] \) has asymptotic size \( \alpha \in (0, 1) \). Then, for any sequence \( r_d > 0 \) such that \( r_d/d^{1/4} \) is bounded, and any sequence of nonempty Borel sets \( \mathbb{D}_d \subseteq B_2^d(r_d) \) such that

\[
\bigtimes_{d=1}^{\infty} \mathbb{D}_d \subseteq C([p, \kappa_{d,p}]), \tag{6}
\]

we have

\[
\lim_{d \to \infty} \frac{\text{vol}_d(\mathbb{D}_d)}{\text{vol}_d(B_2^d(r_d))} = 0.
\]

**Proof.** Let \( \{p, \kappa_{d,p}\}, r_d, \) and \( \mathbb{D}_d \) be as in the statement of the theorem. Corollary 3.2 in Kock and Preinerstorfer (2021) shows that \( \theta \in C([p, \kappa_{d,p}]) \) if and only if

\[
d^{-1/2} (\|\theta\|_2^2 + \text{vol}_{d/2}(\mathbb{D}_d)) \to \infty
\]

Together with \( r_d/d^{1/4} \) being bounded, \( \mathbb{D}_d \subseteq B_2^d(r_d) \), and (6), this guarantees that \( \tilde{s}_d/d^{(2p)/4 - 1/4} \to \infty \) for \( \tilde{s}_d := \inf \{ \|\theta\|_p : \theta \in \mathbb{D}_d \} \). The definition of \( \tilde{s}_d \) eventually implies

\[
\mathbb{G}_d := B_2^d(r_d) \setminus \mathbb{D}_d \supseteq B_2^d(r_d) \cap B_p^d(\tilde{s}_d/2).
\]

Define the sequence \( s_d := d^{(2p)/4 - 1/4} r_d > 0 \), so that \( s_d/d^{1/4} \to r_d/d^{1/4} \) is bounded. Hence, eventually \( \tilde{s}_d \geq 2s_d \) and thus \( \text{vol}_d(\mathbb{G}_d) \geq \text{vol}_d(B_2^d(r_d) \cap B_p^d(s_d)) \) holds, so that the quotient

\[
1 - \frac{\text{vol}_d(\mathbb{D}_d)}{\text{vol}_d(B_2^d(r_d))} = \frac{\text{vol}_d(\mathbb{G}_d)}{\text{vol}_d(B_2^d(r_d))}
\]

is eventually not smaller than

\[
\frac{\text{vol}_d(B_2^d(r_d) \cap B_p^d(s_d))}{\text{vol}_d(B_2^d(r_d))} = \frac{\text{vol}_d(B_2^d(e_{d,2}) \cap B_p^d(e_{d,2}s_d/r_d))}{\text{vol}_d(B_2^d(e_{d,2}))} = \frac{\text{vol}_d(B_2^d(e_{d,2}) \cap u_d B_p^d(e_{d,p}))}{\text{vol}_d(B_2^d(e_{d,2}))},
\]

where \( u_d := \frac{e_{d,2}}{e_{d,p}} d^{(2p)/4} \), \( e_{d,p} := \frac{1}{2} \Gamma(1+1/p)/(\Gamma(1+p)), \) and consequently \( \text{vol}_d(B_2^d(e_{d,2})) = 1 \).

The main result in Schechtman and Schmuckenschläger (1991) shows that for every \( r \) large enough \( \text{vol}_d(B_2^d(e_{d,2}) \cap r B_p^d(e_{d,p})) \to 1 \), as \( d \to \infty \). Therefore, we are done upon verifying that \( u_d \to \infty \). This follows from the lower bound

\[
\frac{e_{d,2}}{e_{d,p}} = \frac{\Gamma(1+2/d)}{\Gamma(1+d/p)} \frac{\Gamma(1/p + 1)}{\Gamma(1/2 + 1)} \geq \left[ \frac{d/p}{\Gamma(1/p + 1)} \frac{\Gamma(1/2 + 1)}{\Gamma(1/2 + 1)} \right].
\]
where we used the inequality for ratios involving the gamma function in equation (12) of Jameson (2013) with “$x = 1 + d/p$” (which is not smaller than 1) and “$y = d(1/2 - 1/p)$” (which is not smaller than 0).

Hence, even though $\mathcal{C}(\{p, \kappa, d\})$ contains the consistency set of the LR test as a strict subset for every $p \in (2, \infty)$ as discussed in Section 3.1, the subset of those alternatives in each benchmark $\prod_{j=1}^{\infty} \mathbb{B}_2^d(r_d)$ for which the test $\{p, \kappa, d\}$ provides an improvement over the LR test is “negligible” in (relative) volume. That this result is not specific to $p$-norm-based tests but extends to all tests will be shown next.

5. UNRESTRICTED SEQUENCES OF TESTS

The proof of Theorem 4.1 builds heavily on the particular structure of the consistency set of $p$-norm-based tests. We shall now establish that no test can improve substantially on the LR test. In the absence of any structure on the tests, one can no longer exploit specific properties of the consistency set stemming from the test being based on a $p$-norm. Instead we rely on concentration results for Lipschitz continuous functions on the sphere as exposited in Ledoux (2001) (cf. also Ledoux (1992)).

**Theorem 5.1.** For every sequence of tests $\psi_d$ with asymptotic size $\alpha \in (0, 1)$ and every sequence $r_d > 0$ such that $r_d/d^{1/4}$ is bounded, there exists an $\epsilon > 0$, such that for every sequence of nonempty Borel sets $\mathbb{D}_d \subseteq \mathbb{B}_2^d(r_d)$ satisfying

$$\prod_{d=1}^{\infty} \mathbb{D}_d \subseteq \mathcal{C}(\psi_d),$$

we have

$$\frac{\text{vol}_d(\mathbb{D}_d)}{\text{vol}_d(\mathbb{B}_2^d(r_d))} \leq \exp\left(-2\epsilon^2(d - 2)/r_d^2\right) \quad \text{for all } d \text{ large enough;}$$

in particular, $\text{vol}_d(\mathbb{D}_d)/\text{vol}_d(\mathbb{B}_2^d(r_d))$ converges to 0 as $d \to \infty$.

The proof of Theorem 5.1 can be found in Appendix A. Note that Theorem 5.1 not only shows that the magnitude of superconsistency points is asymptotically negligible for any test, but it also shows that the measure of these points converges to zero quickly in the dimension $d$.

**Remark 5.1** (Spherical measure instead of relative volume). One could ask what happens in the context of Theorem 5.1 if, instead of considering $\text{vol}_d(\mathbb{D}_d)/\text{vol}_d(\mathbb{B}_2^d(r_d))$ in (8), one considers $\rho_{d, r_d}(\mathbb{D}_d)$, where $\rho_{d, r_d}$ denotes the uniform probability measure on the sphere

$$\mathbb{S}_{d-1}(r_d) := \{\xi \in \mathbb{R}^d : \|\xi\| = r_d\}.$$
Inspection of the proof of Theorem 5.1 (cf. equation (A.2)) shows that the statement equally holds with \( \text{vol}_d(\mathbb{D}_d)/\text{vol}_d(\mathbb{B}_d^d(r_d)) \) replaced by \( \rho_{d,r_d}(\mathbb{D}_d) \). That is, also with this alternative measure, one reaches the same conclusion concerning the magnitude of the set of superconsistency points of a sequence of tests relative to the LR test.

So far, all our results concerned consistency properties of tests. We were interested in the possible magnitude of the superconsistency points of a sequence of tests relative to the LR test and have seen that the magnitude of such points cannot be substantial. Although we now know that one cannot substantially improve on the LR test in terms of consistency (in the sense of Theorem 5.1), there could in principle exist sequences of tests that have larger power than the LR test on substantial portions of the parameter space (without the power there necessarily being close to 1). A nonasymptotic question one can therefore ask is: How large can such portions of the parameter space be? To answer this question, we introduce some more notation: Let \( \alpha \in [0, 1] \) and denote for every \( r > 0 \) by \( \beta_{d,\alpha}(r) \) the power of the LR test of size \( \alpha \) against alternatives \( \theta \in \mathbb{R}^d \) such that \( \|\theta\|_2 = r \) (noting that the power of the LR test coincides for all such parameters as it is rotationally invariant).\(^6\) Denote the set of all tests \( \psi : \mathbb{R}^d \to [0, 1] \) by \( \Psi_d \), and define for every \( \alpha \in [0, 1] \), \( \epsilon > 0 \), and \( \psi \in \Psi_d \) the set \( \mathcal{F}_d(\epsilon, \psi) \) as the subset of parameters against which the power of \( \psi \) exceeds the power of the LR test of the same size as \( \psi \) by more than \( \epsilon \), i.e.,

\[
\mathcal{F}_d(\epsilon, \psi) := \left\{ \theta \in \mathbb{R}^d : \mathbb{E}(\psi(\theta + \epsilon_d)) - \beta_{d,\alpha}(\|\theta\|_2) > \epsilon \text{ for } \alpha = \mathbb{E}(\psi(\epsilon_d)) \right\}.
\]

The question is: How large can this set be made by cleverly choosing \( \psi \)? The following proposition (on which the proof of Theorem 5.1 rests) provides a nonasymptotic upper bound on its measure w.r.t. the uniform distribution \( \rho_{d,r} \) on \( \mathbb{S}^{d-1}(r) \). The upper bound decreases exponentially in \( d \).

**PROPOSITION 5.2.** For every \( \epsilon > 0 \), \( r > 0 \), \( d \in \mathbb{N} \), and \( \psi \in \Psi_d \), it holds that

\[
\rho_{d,r}(\mathcal{F}_d(\epsilon, \psi)) \leq \exp\left(-2\epsilon^2(d-2)/r^2\right).
\]

**Remark 5.2.** Given a test \( \psi \in \Psi_d \), note that \( \mathcal{F}_d(\epsilon, \psi) \cap \mathbb{S}^{d-1}(r) \) is empty if \( \beta_{d,\alpha}(r) + \epsilon \geq 1 \), where \( \alpha = \mathbb{E}(\psi(\epsilon_d)) \). For such values of \( r \) and \( \epsilon \), it obviously holds that \( \rho_{d,r}(\mathcal{F}_d(\epsilon, \psi)) = 0 \).

The proof of Proposition 5.2 is given next. It is mainly based on the observation that power functions in the model under consideration are Lipschitz continuous when restricted to spheres, and that such functions concentrate around their average.

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\(^6\)With this notation, it is worth noting that the proof of Theorem 5.1 shows that \( \epsilon \) in that theorem can be chosen as \((1 - \limsup_{d \to \infty} \beta_{d,\alpha_d}(r_d))/2\), where \( \alpha_d \) denotes the size of \( \psi_d \).
Proof. Fix $\epsilon > 0$, $r > 0$, and $d \in \mathbb{N}$. The statement in (10) is trivially true if $d \leq 2$. Hence, we only need to consider the case where $d \geq 3$ holds. Let $\psi \in \Psi_d$ and denote its size by $\alpha$. If $\alpha = 0$ or $\alpha = 1$, the inequality in (10) trivially holds as $F_d(\epsilon, \psi) = \emptyset$ then follows. Hence, we only need to verify the claim for $\alpha \in (0, 1)$. It appears to be well known (a complete proof of this statement is given in Appendix B for the convenience of the reader) that the LR test (for the testing problem (2) in the model (1)) with size $\alpha$ maximizes the “weighted average power” (WAP)

$$\psi^* \mapsto \int_{S^{d-1}(r)} \mathbb{E}(\psi^*(y + \epsilon_d)) d\rho_{d,r}(y) \quad (11)$$

among all tests $\psi^* \in \Psi_d$ of size $\alpha$. Therefore, $\int_{S^{d-1}(r)} \mathbb{E}(\psi(y + \epsilon_d)) d\rho_{d,r}(y) \leq \beta_{d,a}(r)$, and we can conclude that $\rho_{d,r}(F_d(\epsilon, \psi)) = \rho_{d,r}(F_d(\epsilon, \psi) \cap S^{d-1}(r))$ is bounded from above by

$$\rho_{d,r}\left(\left\{\theta \in S^{d-1}(r) : \mathbb{E}(\psi((\theta + \epsilon_d)) \geq \int_{S^{d-1}(r)} \mathbb{E}(\psi(y + \epsilon_d)) d\rho_{d,r}(y) + \epsilon\right\}\right). \quad (12)$$

It is well known (and easy to verify using Pinsker’s inequality as in Lemma 2.5 in Tsybakov (2009)) that the total variation distance between two Gaussian distributions with covariance matrices equal to the identity and mean vectors $\theta_1$ and $\theta_2$, respectively, is bounded from above by $\|\theta_1 - \theta_2\|_2/2$. This implies (by, e.g., Lemma 2.3 in Strasser (1985)) that the function $\theta \mapsto 2\mathbb{E}(\psi(\theta + \epsilon_d))$ is Lipschitz continuous with constant 1. Since the geodesic distance between two points in $S^{d-1}(r)$ is not smaller than the Euclidean distance between the two points, the function $\theta \mapsto 2\mathbb{E}(\psi(\theta + \epsilon_d))$ is Lipschitz continuous with constant 1 on $S^{d-1}(r)$ when the latter is equipped with the geodesic distance.

Multiplying both sides of the inequality in (12) by 2, and using the concentration inequality for Lipschitz continuous functions on spheres as given in the third display on page 222 of Ledoux (1992) (cf. also the discussion in Section 2.3 of Ledoux (2001)), we obtain

$$\rho_{d,r}(F_d(\epsilon, \psi)) \leq \exp\left(-2\epsilon^2(d-2)/r^2\right). \quad \square$$

6. CONCLUSION

In high-dimensional testing problems, the choice of a test implicitly or explicitly determines the type of alternative it prioritizes. In the Gaussian sequence model, the LR test is based on the Euclidean norm. Many tests exist that are consistent against alternatives the LR test is not consistent against (or are even consistent against strictly more alternatives than the LR test), i.e., they possess what we refer to as superconsistency points. We have shown that for any test, the corresponding set of superconsistency points is negligible in an asymptotic sense. This may be interpreted as a high-dimensional testing analog of Le Cam’s famous result that,
in sufficiently regular models, the set of superefficiency points relative to the maximum likelihood estimator is at most a Lebesgue null set (cf. Le Cam, 1953). In analogy to that classic finding, our result does not suggest that one should always use the LR test. However, it shows that there exists no test for which one can expect substantial improvements in terms of the magnitude of its set of superconsistency points.

APPENDIX A. Proof of Theorem 5.1

Let the sequence of tests $\psi_d$ and $r_d$ be as in the theorem’s statement. Denote the size of $\psi_d$ by $\alpha_d$. Since $r_d/d^{1/4}$ is bounded and $\alpha_d \to \alpha$, it follows from Theorem 2.1 that

\[ \beta := \limsup_{d \to \infty} \beta_{d, \alpha_d}(r_d) < 1. \]

Define $\epsilon = (1 - \beta)/2$. From (7), we obtain

\[ c_d := \inf_{\theta \in D_d} \mathbb{E}(\psi_d(\theta + \epsilon_d)) \to 1. \quad (A.1) \]

For all $d$ large enough, we thus obtain $c_d > \beta_{d, \alpha_d}(r_d) + \epsilon$. Together with $D_d \subseteq B^d_{2}(r_d)$ and the function $r \mapsto \beta_{d, \alpha_d}(r)$ being nondecreasing, it therefore follows that $D_d \subseteq F_d(\epsilon, \psi_d)$ for all $d$ large enough. Proposition 5.2, hence, allows us to conclude that, for all $d$ large enough, we have

\[ \rho_{d,r}(D_d) \leq \rho_{d,r}(F_d(\epsilon, \psi_d)) \leq \exp\left(-2\epsilon^2(d - 2)/r^2 \right) \quad \text{for every } r > 0. \quad (A.2) \]

For every $r > 0$, the push-forward measure of $\rho_d := \rho_{d,1}$ under the transformation $y \mapsto ry$, $y \in S^{d-1} := S^{d-1}(1)$ is $\rho_{d,r}$. Using polar coordinates (as in, e.g., Stroock (1998, Sect. 5.2)) and $D_d \subseteq B^d_{2}(r_d)$, we may express

\[ \frac{\text{vol}_d(D_d)}{\text{vol}_d(B^d_{2}(r_d))} = \frac{d}{r_d^d} \int_{(0,r_d)} r^{d-1} \int_{S^{d-1}} 1_{D_d}(ry) d\rho_d(\gamma) dr = \frac{d}{r_d^d} \int_{(0,r_d)} r^{d-1} \rho_{d,r}(D_d) dr, \]

which, for all $d$ large enough, we can upper bound by

\[ \frac{1}{r_d^d} \int_{(0,r_d)} dr^{d-1} \exp\left(-2\epsilon^2(d - 2)/r^2 \right) dr \leq \exp\left(-2\epsilon^2(d - 2)/r_d^2 \right). \]

APPENDIX B. WAP Optimality of the LR Test

In this appendix, we provide an argument showing that (for $r > 0$) the LR test (for the testing problem (2) in the model (1)) with size $\alpha$ in $(0, 1)$ maximizes the weighted average power (WAP)

\[ \psi^* \mapsto \int_{S^{d-1}} \mathbb{E}(\psi^*(y + \epsilon_d)) d\rho_{d,r}(y) \]

among all tests $\psi^* \in \Psi_d$ of size $\alpha$. To see this, denote the $d$-variate normal density with mean $y$ and identity covariance matrix by $\phi_y$ and note that (by the Neyman–Pearson lemma)

\[ \text{vol}_d(D_d) \leq \text{vol}_d(B^d_{2}(r_d)), \]

Throughout this proof, we use the notation that was introduced in the context of Proposition 5.2.
the test which maximizes WAP (i.e., which is WAP optimal) is the LR test for the simple hypothesis where (i) the density under the null equals $\phi_0$ and (ii) the density under the alternative equals $\int \phi_\gamma d\rho_{d,r}(\gamma)$. This test rejects for the observation $y$ if and only if

$$\int_{\mathbb{S}^{d-1}(r)} \phi(y)/\phi_0(y) d\rho_{d,r}(\gamma) = \exp(-r^2/2) \int_{\mathbb{S}^{d-1}(r)} \exp(y'y) d\rho_{d,r}(\gamma) \tag{B.1}$$

exceeds a critical value $C_{\alpha, r}$, say, which is chosen such that the test has size $\alpha$. Note that the measure $\rho_{d,r}$ coincides with its push-forward measure under any orthonormal linear transformation $U : \mathbb{R}^d \to \mathbb{R}^d$, i.e., $\rho_{d,r}$ is “rotationally invariant.” Choosing $U$ orthonormal and such that $Uy$ coincides with $\|y\|_2$ times the first element of the canonical basis of $\mathbb{R}^d$, it follows that the integral to the right of (B.1) coincides with

$$\int_{\mathbb{S}^{d-1}(r)} \exp(\|y\|_2 \gamma_1) d\rho_{d,r}(\gamma) = \frac{1}{2} \left( \int_{\mathbb{S}^{d-1}(r)} \left[ \exp(\|y\|_2 \gamma_1) + \exp(-\|y\|_2 \gamma_1) \right] d\rho_{d,r}(\gamma) \right).$$

Since the function $a \mapsto \exp(a\gamma_1) + \exp(-a\gamma_1)$ is nondecreasing on $[0, \infty)$ for every $\gamma_1$, it follows that the WAP optimal test rejects if and only if $\|y\|_2$ exceeds a critical value (chosen so that the test has the right size). In other words, the LR test (for the testing problem (2) in the model (1)) is WAP optimal.

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