A linear model of phase-dependent power correlations in neuronal oscillations

David Eriksson1*, Raul Vicente2 and Kerstin Schmidt1

1 Research Group: Cortical function and dynamics, Max-Planck-Institute for Brain Research, Frankfurt, Germany
2 Department of Neurophysiology, Max-Planck-Institute for Brain Research, Frankfurt, Germany

INTRODUCTION

Different situations may require different aspects of knowledge stored in the brain (Dayan et al., 2000). This adaptive knowledge selection can be achieved by enhancing the influence of a specific set of synapses. The selective use of certain synapses is a way to route information and to modulate communication between neurons. The communication through coherence (CTC) theory postulates that the communication between two neuronal populations is supported by the membrane potential phase difference between the oscillations in the two populations (Fries, 2005). This theory has been very influential because it confirms a role for oscillations in the neuronal code (Buschman and Miller, 2007; Knight, 2007; Saalmann et al., 2007; Womelsdorf and Fries, 2008; Fries, 2009; Tiesinga and Sejnowski, 2007; Hipp et al., 2011; Singer, 2011).

It has been tested experimentally by means of the phase difference between the multi-unit activity (MUA) from two recorded units, or between the MUA and the local field potential (LFP; Womelsdorf et al., 2007). To this end, for both recorded units, amplitude and phase of a given oscillation frequency were estimated on a trial by a trial basis. Interestingly, for those trials that had a phase difference similar to the mean phase difference ("good phase") oscillation amplitudes were more strongly correlated than for those trials that had a phase difference not corresponding to the mean ("bad phase").

Recently, it has been suggested that effective interactions between two neuronal populations are supported by the phase difference between the oscillations in these two populations, a hypothesis referred to as "communication through coherence" (CTC). Experimental work quantified effective interactions by means of the power correlations between the two populations, where power was calculated on the local field potential and/or multi-unit activity. Here, we present a linear model of interacting oscillators that accounts for the phase dependency of the power correlation between the two populations and that can be used as a reference for detecting non-linearities such as gain control. In the experimental analysis, trials were sorted according to the coupled phase difference of the oscillators while the putative interaction between oscillations was taking place. Taking advantage of the modeling, we further studied the dependency of the power correlation on the uncoupled phase difference, connection strength, and topology. Since the uncoupled phase difference, i.e., the phase relation before the effective interaction, is the causal variable in the CTC hypothesis we also describe how power correlations depend on that variable. For uni-directional connectivity we observe that the width of the uncoupled phase dependency is broader than for the coupled phase. Furthermore, the analytical results show that the characteristics of the phase dependency change when a bidirectional connection is assumed. The width of the phase dependency indicates which oscillation frequencies are optimal for a given connection delay distribution. We propose that a certain width enables a stimulus-contrast dependent extent of effective long-range lateral connections.

Keywords: communication through coherence, power correlation, phase relation, axonal delays, neuronal oscillations

MATERIALS AND METHODS

MODEL

The model consists of two interacting units represented by variables, \( O_{\alpha} \) and \( O_{\beta} \), each of which correspond to a narrow-band filtered LFP or MUA around a given frequency. We assume that the interaction is linear, and in general, described by the sum of a remote and a local oscillatory component. The governing equations are written as

\[
O_{\alpha}^k(t) = A_k^\alpha(t) \sin(2\pi ft + \Delta \phi) + w_{\alpha \beta}^k B_k^\beta(t) \sin(2\pi f t + 2\pi \tau) \tag{1}
\]

\[
O_{\beta}^k(t) = B_k^\beta(t) \sin(2\pi f t) + w_{\beta \alpha}^k A_k^\alpha(t) \sin(2\pi f t + \Delta \phi + 2\pi \tau) \tag{2}
\]

In a recent paper (Buehlmann and Deco, 2010), a biophysically plausible semi-large-scale model was built on the results of Womelsdorf et al. (2007). In the present work, we have developed a simpler linear model in order to try to understand what the main principles defining the relationship between oscillation amplitude correlations and phase differences are. We found that a linear interaction between oscillators can qualitatively fit the experimental results, which allowed us to extract several analytical predictions. These basic principles could then be applied to understand phase-dependent amplitude statistics in spiking activity and in LFP, EEG, and MEG (Wendling et al., 2009).
$A^k(t)$ and $B^k(t)$ denote the amplitude of unit $A$ and $B$ before any coupling occurs at the $k$-th trial. $O^k(t)$ and $O^k(t)$ without the trial superscript $k$ will be used to denote the output in general. $f_i$ and $f_j$ denote the frequencies of interest in unit $A$ and $B$. $t$ is the conduction delay between unit $A$ and $B$. Notice that conduction delays of cortico-cortical long-range connections have been measured to amount up to several tens of milliseconds (Swadlow and Waxman, 1975; Swadlow, 1985; Nadasdy, 2009). Therefore, it may be important to take the conduction delay into account in order to define the good phase (for a definition of the good phase see Power and Phase Estimation in the Analysis part in the Materials and Methods).

We would like to stress that the model described by Eqs 1 and 2 together with its parameter settings is not intended to represent the real brain areas. Rather it should be viewed as an abstraction of a linear and phase-dependent coupling of two oscillatory processes.

**SETTINGS FOR THE SIMULATIONS**

**Simulations with stationary parameters**

Two different cases of stationary parameters were simulated according to the distribution of the amplitudes over trials:

(i) All the variables of the model, $A(t)$, $B(t)$, and $\Delta \varphi(t)$, were constant in time during one trial and could be described by

\[ w_{\rightarrow a} = 1 \] and \[ w_{\rightarrow b} = 0 \] respectively, see (i).

For the realizations over trials $A$ and $B$ were drawn from a uniform distribution from 0 to 1. The phase difference, $\Delta \varphi$, was drawn from a $-\pi$ to $\pi$ uniform distribution. For simplicity $\tau$ was set to 0 and $w(f)$ was set to 1. These settings were also used in the section of analytical predictions.

(ii) For the variables, $A(t)$, $B(t)$, and $\Delta \varphi(t)$, $w_{\rightarrow a}$, $w_{\rightarrow b}$ see (i). The realizations $A$ and $B$ were drawn from a Gaussian distribution with a SD one and mean zero. The values for the variables in Eq. 2 were set to the following. We randomized 50,000 amplitude pairs $A^{(k)}$ and $B^{(k)}$, and 50,000 $\Delta \varphi^{(k)}$, i.e., $k = 1.50000$. The time $t$ was run from 0 to $2\pi$ in steps of 0.1, i.e., the simulation was run for one period. For simplicity $\tau$ was set to 0.

**Simulations with non-stationary parameters**

This changing parameter-set was chosen to test the timing of the establishment of a “good” phase relationship relative to the increase in power correlation. A trial of 120 time points was defined with 1 ms resolution per time point. The period of oscillations was set to 20 ms. The time resolved phase relation was calculated as $\cos(\Delta - \delta)$, where $\delta$ is the phase accumulated due to the conduction delay, and $\Delta$ is the phase difference between the coupled model variables $O^1(t)$ and $O^2(t)$ at time $t$ ($\cos(\Delta - \delta) = 1$ or $-1$ for the “good” or “bad” phase, respectively). The amplitudes for both recorded units were always kept constant during this time period, but were drawn from a Gaussian distribution for different repetitions, independently for the two units. Repeated simulations with different amplitudes were necessary in order to estimate the power correlation for every time point. The power correlation at each time point was estimated across 200 repetitions. The phase relation was always the same across repetitions.

**ANALYSIS**

**Power and phase estimation**

In simulations, the phase and amplitude were calculated using a windowed fast Fourier transform. The window was rectangular and had a duration corresponding to one period. The amplitude and phase of the signal, $y$, at time $t$ will be referred to as $\{fft(y, t)\}$ and $\varphi(fft(y, t))$, respectively, where $\|x\| = |a + ib| = \sqrt{(a^2 + b^2)}$ and $\varphi(x) = \arg(a + ib)$. The good phase was defined as the mean phase, i.e., $\langle \varphi(\sum_{i=1}^{N}x_i / |x_i|) \rangle$, where $N$ denotes the number of trials. The power was calculated as $|a + ib|^2$.

**Estimation of power correlation, mutual information, and modulation depth**

To estimate the phase-dependent power correlation (PDPC), amplitude, and phase for $O^1(t)$ and $O^2(t)$ were estimated in a $2\pi$-wide window centered around $\pi$, i.e., from 0 to $2\pi$. According to Womelsdorf et al. (2007), the phase difference was divided into six equally sized bins. The power correlation was then calculated as the Pearson coefficient for the powers of those trials that had phase differences belonging to the same bin.

Mutual information between the amplitudes of $O^1(t)$ and $O^2(t)$ was calculated using a bias-corrected “naive histogram” estimate (computed via the Matlab function “information.m,” available from http://www.cs.ru.nl/~rudy/matlab/doc/information.html). For each bin of the phase difference the mutual information was calculated on 3000 pairs (in the bad/good phase bin there were around 5000/16000 pairs) that were drawn with replacement. The mean of the information in each bin was calculated on 1000 repetitions.

The modulation depth is the peak-trough distance, where peak corresponds to the maximal power correlation and trough corresponds to the minimal power correlation.

**RESULTS**

First, using analytical derivations, we will examine the characteristics of the PDPC for oscillators interacting with uni-directional, bidirectional, and common drive connectivity. Using results from the analytical study, we predict that the width of the phase dependency will be different for the uncoupled and the coupled phase difference. This is tested with numerical simulations. Using numerical simulations we also examine if the power correlation lags the phase difference, i.e., if the phase difference plays a causal role in determining the power correlation. Finally, we summarize the results using a non-linear correlation index such as mutual information.

**ANALYTICAL DERIVATIONS AND PREDICTIONS**

In this section, we compute how power correlations between two linearly coupled oscillatory processes depend on their phase difference and coupling strength. We start by considering the case of uni-directionally coupled oscillators by setting $w_{\rightarrow b} = 0$ (see Eqs 1 and 2) and denoting $w_{\rightarrow a}$ with $w$. We set the amplitudes $A$ and $B$ fixed in time and only depending on the trial realization.
\[ O_1^t(t) = A^t \sin(2\pi f_t + \Delta \phi) \]  
\[ O_2^t(t) = B^t \sin(2\pi f_t') + wA^t \sin(2\pi f_t + \Delta \phi + 2\pi f_t') \]  

We first proceed by relating the amplitude of process \( O_2^t(\text{t}) \) (the receiver) to that of process \( O_1^t(\text{t}) \) (the emitter) and the coupling coefficient, \( w \). Once such a relation is established we can compute the Pearson correlation coefficient between the powers of the two processes. This holds, regardless of the particular distribution from which the amplitudes over trials are drawn. For simplicity, we will illustrate here the case where the amplitudes are sampled from a uniform distribution covering from 0 to 1.

We proceed by computing the amplitude of process \( O_2^t(\text{t}) \). We use the fact that process \( O_2^t(\text{t}) \) is the sum of two harmonic processes, and therefore, it is itself a harmonic process. Thus, the modified (after being coupled) amplitude \( D \) and phase \( \theta \) of process \( B \) can be obtained by solving the equation

\[ O_2^t(t) = B \sin(2\pi ft) + wA \sin(2\pi ft + \Delta \phi) = D \cos(2\pi ft + \theta) \]  

For each trial, this leads to a new amplitude \( D \) and phase difference \( \theta \) that read

\[ D = \left( B^2 + 2wAB \cos(\Delta \phi) + w^2A^2 \right)^{1/2} \]  

and

\[ \theta = \begin{cases} \arctan\left( \frac{wA \sin(\Delta \phi)}{B + wA \cos(\Delta \phi)} \right) & \text{if } B + wA \cos(\Delta \phi) < 0 \\ \arctan\left( \frac{wA \sin(\Delta \phi)}{B + wA \cos(\Delta \phi)} \right) + \pi & \text{if } B + wA \cos(\Delta \phi) \geq 0. \end{cases} \]

Eq. 7 demonstrates how the amplitude difference (\( wA/B \)) can modulate the phase difference (see Figure A1 in Appendix). Since we are interested in the power correlation between the two processes we are left to compute the Pearson coefficient between \( D^2 \) and \( A^2 \)

\[ \rho(D^2, A^2) = \frac{E\left[ (D^2 - E[D^2])(A^2 - E[A^2]) \right]}{\left( E\left[ (D^2 - E[D^2])^2 \right] E\left[ (A^2 - E[A^2])^2 \right] \right)^{1/2}}, \]  

where \( E[] \) denotes the expected value operator

\[ E[X] = \int_{-\infty}^{\infty} x p(x) \, dx, \]  

and \( p(X) \) is the probability density function of a real random variable \( X \).

In this simplified model we assume that from trial to trial the amplitudes \( A \) and \( B \) are drawn from a uniform distribution. Since \( A^2 \) and \( D^2 \) are functions of \( A \) and \( B \), it is possible, in principle, to compute the probability density functions that \( A \) and \( B \) induce on each of the powers and later compute the integrals appearing in Eq. 8. However, since we are only interested in the expected values a much more practical approach is to use the fact that

\[ E[f(X)] = \int_{-\infty}^{\infty} f(x) p(x) \, dx, \]  

and its analog version for functions of multiple random variables. After computing the integrals appearing in Eq. 8 the Pearson correlation coefficient between the powers \( A^2 \) and \( D^2 \) as a function of the coupling strength and phase difference can be obtained as

\[ \rho(D^2, A^2) = \frac{w(16w^2 + 15\cos(\Delta \phi))}{4\left(16(1 + w^2) + 5w \cos(\Delta \phi)(6 + 6w^2 + 7w \cos(\Delta \phi))\right)^{1/2}}. \]

Now, it is possible to study with more detail how power correlations are due to different coupling characteristics. For example, from the formula above it can be deduced that the maximum of the power correlation grows with the coupling strength monotonically. However, the phase difference for which this maximum arises presents a switching point for a coupling strength \( w \approx 0.95 \) (Figure 1A). Below that critical coupling strength, the maximum of the power correlation is achieved at a zero phase difference (\( \Delta \phi = 0 \)). When the
coupling strength is larger than ~0.95, there is a double maximum which in the case of large coupling strength limit occurs for phase differences of $\Delta \phi = \pm \pi$. Additionally, one can observe that negative power correlations can arise for certain phase differences only if the coupling is below the critical strength. (Note, however, that a Gaussian amplitude statistics, in contrast to a uniform amplitude statistics, in general generates a more positive correlation for the bad phase, see Figure A2 in Appendix). Beyond that limit only positive correlations arise, no matter the phase difference.

The former analysis considered a uni-directional type of interaction between units. Cortical connectivity is, however, much more often bridging areas in a bidirectional or reciprocal manner. Next, we explore therefore how power correlations arise in a bidirectional scheme of coupled oscillations. For the bidirectional case, $w_{b \rightarrow a} > 0$ (see Eqs 1 and 2), the analysis proceeds as described for the uni-directional one, except for one distinction, namely, that the phase difference between the oscillators is composed by an initial phase difference and a propagation phase due to a delay in the interaction. In the uni-directional case, these two contributions could be simply added into a single term rendering the individual contribution of each indistinguishable. In the reciprocal case, axonal delays add a factor that strongly modifies the shape of the power correlation curve. The interacting oscillators are now described by

$$O_a(t) = B \sin(2\pi f t) + w_{\rightarrow a} A \sin(2\pi f t + \Delta \phi + 2\pi f \tau)$$

$$= D \cos(2\pi f t + \theta_a)$$

$$O_b(t) = A \sin(2\pi f t + \Delta \phi) + w_{\rightarrow b} B \sin(2\pi f t + 2\pi f \tau)$$

$$= C \cos(2\pi f t + \theta_b),$$

whereby both powers depend explicitly on the phase propagation accumulated due to axonal delay in addition to the initial phase difference. They read as

$$D = \left( B^2 + 2w_{\rightarrow a} AB \cos(\Delta \phi + 2\pi f \tau) + w^2 A^2 \right)^{1/2}$$

$$C = \left( A^2 + 2w_{\rightarrow b} AB \cos(\Delta \phi - 2\pi f \tau) + w^2 B^2 \right)^{1/2}. \quad (13)$$

The power correlation can now be computed as a function of different variables from the expected values appearing in Eq. 8 once $A$ is replaced by the expression of the new power $C$. The analytical expression for the power correlation curve can be obtained even for asymmetric values of the coupling strengths $w_{b \rightarrow a} \neq w_{a \rightarrow b}$ and reads

$$\rho(C^2, D^2) = \frac{16(1 + w_{\rightarrow a}^2) O_{b \rightarrow a} + 15(1 + w_{\rightarrow b}^2) O_{a \rightarrow b} + 35O_{b \rightarrow a}O_{a \rightarrow b}}{N_{a \rightarrow a} N_{b \rightarrow b}}$$

$$N_{i \rightarrow j} = \sqrt{16(1 + w_{\rightarrow a}^i + 5O_{a \rightarrow b}(6 + 6w_{\rightarrow a}^i + 7O_{b \rightarrow j})} \quad (14)$$

$$O_{b \rightarrow a} = w_{b \rightarrow a} \cos(2\pi f \tau + \Delta \phi)$$

$$O_{a \rightarrow b} = w_{a \rightarrow b} \cos(2\pi f \tau - \Delta \phi)$$

Figure 1B displays the analytical results for the power correlation versus the uncoupled phase difference in a bidirectional interaction of oscillations. The Figure illustrates the symmetric and moderate coupling case for which we have considered different axonal delays. Clearly, the delay does not simply shift the curve but modifies its shape indicating that axonal conduction delays have to be taken into account when interpreting power correlation curves from experimental data.

Distinct neuronal units can also share power correlations without directly interacting. Common drive from a third source can create PDPCs between the driven units as it occurs described for uni-directional and bidirectional interactions. A distinction of the two scenarios is relevant to assess the origin of the phase-dependent correlations in neurophysiological recordings. In general, we observe that correlations generated by the three topologies qualitatively differ in terms of their dependency of the connection strength (see Appendix and Figure A3).

**POWER CORRELATION AS A FUNCTION OF THE COUPLED PHASE DIFFERENCE**

Overall, the phase dependency in Figure 1A is broader compared with the one for the experimental data. This could be because the experimental data exhibit a coupled phase difference ($\theta$) rather than an uncoupled one ($\Delta \phi$). In principle, Eq. 7 relates the coupled phase difference to the uncoupled one but lamentably such dependency is not one-to-one since $A$ and $B$ are not fixed from trial to trial. Therefore, one cannot translate directly from the uncoupled to the coupled phase difference. It is possible, however, to relate them in a statistical sense. To that end, we integrate $\theta$ over the random distributions of $A$ and $B$ to obtain an average coupled phase difference as a function of the uncoupled one,

$$\bar{\theta}(\Delta \phi) = \int \int \arctan \left( \frac{B + wA \cos(\Delta \phi)}{w \sin(\Delta \phi)} \right) p(A)p(B)dAdB \quad (15)$$

The numerical estimation of such integral shows that for a moderate coupling strength the average phase difference depends almost linearly on the uncoupled one (Figure 2A). Therefore, it is expected that power correlations as a function of the coupled phase look similar to Figure 1A but with the phase difference axis scaled by a numerical factor. Indeed, the power correlation curve becomes narrower when the power correlation is calculated as a function of the coupled phase difference instead of the uncoupled phase difference (Figure 2B and see Figure A4 in Appendix). A similar result is obtained when power is estimated instead of amplitude and when Spearman rank correlation is used instead of Pearson correlation (data not shown).

The shape of the PDPC was also found to be dependent on the connection strength (Figure 2C). The shape of the PDPC can be better visually inspected after dividing the PDPC by its maximal value. For large connection strengths we observe that the normalized shape stabilized (Figure 2D).
Next, we examined how the modulation depth (see Analysis subsection in the Materials and Methods) of the PDPC and the strength of the phase coherence scale with different connection strengths (Figure 3). This is of particular interest because according to Womelsdorf et al. (2007, their Figures 1 and 2), there exist cases in which the two can dissociate; a relatively high phase coherence not always predicts a PDPC. Indeed, one can observe how for low coupling strengths (~0.2) there is a regime where phase coherence can coexist with an almost flat or slightly negative peaked PDPC curve (Figure 3). However, at higher connection strengths an overall positive correlation between phase coherence and modulation depth is found.

**THE TIMING OF PHASE RELATIONS AND POWER CORRELATIONS**

The experimental results have shown that a good phase relationship precedes a strong power correlation as shown in Figure 3 of Womelsdorf et al. (2007). Such a lag could indicate a causal role for the phase relation in modulating the efficacy of the interaction as measured by power correlations. In order to examine this question we have introduced a sudden change in the phase relation (perturbing the phase in unit A) from a bad phase to a good phase at 60 ms, and back to a bad phase at 80 ms (Figure 4A). For a connection delay of 4 ms, the peak of the power correlation is delayed by approximately 4 ms relative to the maximum of the phase relation. The connection delay is correlated with the power correlation lag (Figure 4B). Since the power correlation lag is around 5 ms in the experimental data, this suggests that the average connection delay for the connection studied is in the range of 5 ms.

**EXTENDING THE LINEAR CORRELATION ANALYSIS TO A NON-LINEAR INFORMATION INDEX**

The Pearson correlation measures the degree of linearity and the Spearman rank correlation the monotonicity between two variables. However, two variables can share information by being related in a more complex manner. Mutual information will now be used to characterize the relationship between oscillatory variables since it is essentially free from any assumptions required for the above mentioned correlation measures. In Figure 5A, we have plotted the mutual information for three different cases as a function of the uncoupled phase difference. When mutual information is calculated between $O_b(\pi/(4f))$ and $O_a(\pi/(4f))$, i.e., at a fixed point in time, and therefore without the non-linear amplitude extraction, the information for the bad phase is equal to that for the good phase condition. In contrast, when the amplitude is extracted, most information for both uniform and Gaussian amplitude distributions is retrieved specifically at the good phase. This is explained by the fact that amplitude (power) extraction is a non-linear operation that averages out correlations occurring between the instantaneous outputs at a given point in time. Moreover, the Gaussian distribution gives rise to a larger relative difference between bad and good phase than the uniform distribution.
When comparing model results for the coupled phase, the most prominent change is that the phase dependency becomes bi-modal for amplitude extraction and a uniform amplitude distribution (see Figure 5B). This is related to the fact that the tails of the power correlation curve as a function of the coupled phase difference take negative values (Figure A4B in Appendix). Since positive and negative correlations contribute equally to mutual information, a double peak is present when measuring mutual information versus the coupled phase difference.

Overall, the width of the mutual information based phase dependency is narrower than that of the correlation based. Furthermore, we have seen that the width is different between uncoupled and coupled phase differences. In Figure A5 in Appendix, we present a model that illustrates that the width can be of importance in particular for contrast dependent modulation of long-range lateral connections.

**DISCUSSION**

We apply a model using a linear, albeit conduction delay dependent, neuronal interaction to examine how power correlations depend on phase differences and other parameters of oscillatory activity. Because of the simplicity of the model, the presented results are predicted to apply to generic interactions between oscillatory populations. Interestingly, the linear model leads to similar results as recently published experimental data. According to the model the influence of the connection makes one particular phase difference more frequent than other phase differences. This phase difference corresponds to the mean phase and it is referred to as the “good” phase. Since the mean phase emerges from the connection it is also a marker of the effective connectivity. Thus, it is argued that such phase might be responsible of generating the largest power correlations. In addition to explaining the experimental results the main contribution of the model has been the examination of how different parameters are influencing the shape of the phase dependency. The characteristics of the phase dependency have been investigated as a function of the correlation measure (non-linear versus linear), amplitude distribution, directionality, and of the nature of the phase difference (uncoupled or coupled).

**ASSUMPTIONS OF THE LINEAR MODEL**

Our model is approximate and makes three main assumptions, i.e., the interaction is linear, and the input is sinusoidal and spatially uncorrelated. Here, we discuss those three assumptions. First, even though a linear model might not be biophysically plausible, linearity might be included as a main component of the interaction between postsynaptic potential and membrane potential. The relative contribution of that linear component decreases, however, when neighboring synapses are activated (Polsky et al., 2004), and certain types of theoretical models do not even consider a linear component (Rabinovich et al., 2008). Thus, a future approach extending our model should demonstrate how the phase dependency changes when different types of biophysical non-linearities are taken into consideration.

Second, we used a sinusoid as the oscillatory carrier to simulate the input since the sinusoid is the eigenfunction of the Fourier transform which was used to estimate the power. Power and phase of recorded signals are typically estimated around a particular frequency by using a narrow-band-pass filter. Therefore, the processed oscillatory activity is almost sinusoidal. The exact type of oscillator, however, does not matter since the results presented here hold for any periodic random function (data not shown).

Finally, we assume that the uncoupled activities of the units are independent. Such an assumption can be expected to hold for spatially distant neuronal populations (Smith and Kohn, 2008; Ecker et al., 2010). In reality, the spatial correlation length is probably limited to the minimal distance between two
IMPLICATIONS FOR THE INVESTIGATION OF NON-LINEARITIES

Here, we have shown that a linear model can fit some recent experimental results concerning power correlation dependencies. Within a linear model information transmission can be reliably controlled if the noise amplitude is proportional to the signal, i.e., multiplicative noise. For example, if the DC level of the signal is decreased the noise would decrease too. If, on the other hand, the noise source is additive the signal would have to be amplified in order for the signal to noise ratio to increase, i.e., gain control (Haider and McCormick, 2009). Amplification, however, is a non-linear mechanism. If phase modulation is therefore proposed as a gain control mechanism it must operate in a regime that deviates from linearity. Here, we present the linear

difference in six bins. For a uniform amplitude distribution, correlations were calculated for both one time point amplitude ($r = \pi / (4/5)$) and full period amplitude. For Gaussian amplitude distribution, correlations were calculated for full period amplitude. Note that the mutual information for the good phase is equal to that of the bad phase. (B) Same as in (A) but with coupled phase. Note that the full width half maximum is narrower in (B) than in (A).

**FIGURE 5** | Mutual information for different settings of the model. (A) Uncoupled phase. The connection strength is 0.3. The x-axis (columns) denotes a phase difference in six bins. For a uniform amplitude distribution, correlations were calculated for both one time point amplitude ($r = \pi / (4/5)$) and full period amplitude. For Gaussian amplitude distribution, correlations were calculated for full period amplitude. Note that the mutual information for the good phase is equal to that of the bad phase. (B) Same as in (A) but with coupled phase. Note that the full width half maximum is narrower in (B) than in (A).

phase-independent oscillators. The upper limit of this distance has been estimated around 0.65 mm (Womelsdorf et al., 2007, their Figure 4).

**IS A HIGH POWER CORRELATION INDICATIVE OF CAUSALITY?**

Although, we have simulated here a case where – by construction – the phase has a causal role in power correlations, we would like to mention that in other scenarios, especially in more realistic setups, different interpretations of their lag are possible. First, the phase and amplitude of many oscillatory processes are intimately and mutually linked, and it is therefore not easy to assign a causal role to only one of the two variables. For instance, a perturbation in the phase of an oscillator can modify its amplitude, and vice versa. Further, the two variables can have a different inertia to perturbations, and therefore, temporal lags cannot be univocally interpreted as a sign of causality. Second, different measuring indices (e.g., phase differences and power correlations) can have different bias to detect the timing of perturbations. For example, in the presence of conduction delay $T$, it will take $T$ ms until the effect of a sudden perturbation in A can reach unit B. If both phase and amplitude have been perturbed in A, the instantaneous phase difference will pick up such a change immediately. However, it might take some time around $T$ for the variables at B to follow the change in A and build up some significant correlation with those at A. Thus, phase differences can precede power correlations even if the amplitude variable can have a causal role.

Related to the causality question is the fact that both common drive and direct interactions provide phase-dependent correlation curves. However, as we have seen there are qualitative differences between the PDPC for different topologies (Figure A3 in Appendix). For uni-directional topology and low connection strength, the correlation at zero phase difference is lower than that of the $\pi$ phase difference (Figure A3B in Appendix). In contrast, for high connection strength, the correlation at $\pi$ phase difference is lower than that of the zero phase difference. For the common drive topology, the correlation at $\pi$ phase difference is lower than that of the zero phase difference, irrespective of connection strength (Figure A3D in Appendix). Therefore, the two topologies show differences in terms of the effect of the connection strength. In an experimental condition, however, we do not know the “connection strength” between two recording points. Instead, to disambiguate between the two topologies, we

reference for such a comparison. The experimentally retrieved PDPC can be compared to a predicted PDPC. The only variable that is needed for that prediction is the connection strength, which in a strict sense can be estimated from the experimentally measured phase coherence.

A direct test for a non-linear relationship between phase and input has been done by TMS stimulation in the motor cortex while measuring the spinal input: “This enabled us to test whether the phase of the spinal beta rhythm at which the input arrived modulated the gain of this input” (van Elswijk et al., 2010). The authors describe that a naturally occurring beta rhythm is strong enough to change the gain of the spinal input. Oscillations slower than beta frequency have also been shown to modulate the cortical gain of sensory input (Lakatos et al., 2005; Lakatos et al., 2007; Rajkai et al., 2008). These studies point out the existence of some non-linear interactions at low frequencies between peripheral nerve systems and either sensory or motor cortex. However, the effect of such non-linearities on gamma power correlation statistics across cortical areas has still to be measured under physiological conditions.
can use the experimentally measurable phase coherence as a correlate of the connection strength since we show that the two are monotonically related.

**HOW A CONNECTION DELAY COULD MODULATE THE PROPORTION BETWEEN FEED-FORWARD AND LATERAL CONNECTIONS**

For firing rates, it has been observed that the influential radius of lateral connections decreases when the contrast increases (Sceniak et al., 1999; Nauhaus et al., 2009). One could argue that if the stimulus has a high-contrast it needs little interpretation and therefore only weak lateral interactions, i.e., the feed-forward pathway is sufficient. However, if the stimulus were less salient, lateral connections would be required to obtain a meaningful interpretation of the stimulus.

Could this feed-forward–lateral modulation be transmitted by neuronal oscillations?

The feed-forward pathway has, according to modeling studies, been shown to benefit from strong gamma coherence and synchrony (Tiesinga et al., 2004; Buehlmann and Deco, 2010). Long-range lateral connections could be rendered ineffective if their delay generates a bad phase relative to a globally synchronized oscillation. Experimental evidence for such a delay-mediated and possibly contrast-controlled modulation of lateral connections can be drawn from several studies that show the presence of oscillations for high-contrast stimulation together with global synchrony and suitable delayed interactions. First, stimulus-contrast has been associated with gamma oscillations because increasing the contrast, or the mere introduction of a stimulus, enhances the amplitude of gamma oscillations (Fries et al., 2001; Henrie and Shapley, 2005; Lima et al., 2010; Yu and Ferster, 2010). Second, it has been shown that distant neurons can be globally synchronized for a high-contrast stimulus (Konig et al., 1995). Finally, as the largest distance between two laterally connected neurons within one cortical area is roughly 3 mm (Fisken et al., 1975; Gilbert and Wiesel, 1979; Rockland and Lund, 1982; Luhmann et al., 1990b), and the typical conduction velocity is around 0.3 mm/ms (Luhmann et al., 1990a; Hirsch and Gilbert, 1991; Murakoshi et al., 1993; Bringuier et al., 1999; Nauhaus et al., 2009), the largest connection delay is around 10 ms. Interestingly, this delay is relatively close to half the period of a 60-Hz gamma cycle (Fries et al., 2001; Womelsdorf et al., 2007). Therefore, globally synchronized distant (2–3 mm) neurons will accumulate a propagation phase close to the bad phase.

Essential for such a mechanism would be, however, the shape of the phase difference dependency. Assuming a constant conduction velocity this shape can be directly superimposed onto the cortical surface to delineate the functional extent of horizontal connections. Therefore, a crucial parameter returned by our model is the tuning width of the phase dependency (see Figure A5 in Appendix). Preferentially, the tuning width should be such that it maximizes the dynamic range of the horizontal connections.

**AUTHOR CONTRIBUTION**

The study was conceived by David Eriksson. The numerical simulations were made by David Eriksson, Raul Vicente and Kerstin Schmidt. The analytical solutions and predictions were derived by Raul Vicente.

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APPENDIX

PHASE-DEPENDENT POWER CORRELATIONS INDUCED BY COMMON DRIVE

A common drive describes the situation where two units are driven by an external source. In this case our model reads as

\[ O_A(t) = A^t(t) \sin(2\pi ft + \Delta \phi) + wC(t) \sin(2\pi ft + \psi) \]

\[ O_B(t) = B^t(t) \sin(2\pi ft) + wC(t) \sin(2\pi ft + \psi), \]

where \( \Delta \phi \) and \( \psi \), refer to the initial phase offsets between A and B, and C, respectively.

The phase-dependent power correlation induced by common drive can be analytically estimated in a similar way as described for the uni-directional and bidirectional case. The main difference is that the integrals appearing in Eq. 8 now have to be computed over three random variables representing the amplitudes of units \( A, B, \) and \( C \) [independent and uniformly distributed in the interval \((0–1)\)]. The final expression for the power correlation between units \( A \) and \( B \) is

\[
\begin{align*}
\frac{w^2}{\sqrt{16(1 + w^4) + 5w\cos(\Delta \phi - \psi)(6 + 6w^2 + 7w\cos(\Delta \phi - \psi))}} & \left[ 16(1 + w^4) + 5w\cos(\psi)(6 + 6w^2 + 7w\cos(\psi)) \right] \\
\end{align*}
\]

(A3)

In order to examine the effects of common drive as a function of the coupled phase difference, we computed PDPC directly from numerical realizations of (A1–A2). In this case, the three amplitudes were independently drawn from the absolute value of normalized Gaussian distributions. Figure A3 compares the PDPC for the common drive, uni-directional, and bidirectional connectivity. We observe that – although the three cases are qualitatively similar – the common drive model is the only topology which generates highest correlation at the zero phase difference, irrespective of the connection strength.

OSCILLATION COHERENCY MIGHT MODULATE THE EXTENT OF EFFECTIVE LATERAL CORRELATIONS

Stimulus-contrast has been shown to increase the oscillation amplitude of the LFP and/or the phase coherence between neurons. Here, we model stimulus-contrast as the increase of a connection between two units in the “input layer” (see Figure A5A). This connection serves to increase the phase coherence and/or to increase the amplitude of the oscillations (see Figure A5B). We test if this amplitude and/or coherence increase can be used to regulate the extent of effective long-range lateral connections (see Discussion for a motivation). To quantify the extent of the communication we use mutual information or correlation. For each unit, we compute the PDPC directly from numerical realizations of (A1–A2). In this case, the three amplitudes were independently drawn from the absolute value of normalized Gaussian distributions. Figure A3 compares the PDPC for the common drive, uni-directional, and bidirectional connectivity. We observe that – although the three cases are qualitatively similar – the common drive model is the only topology which generates highest correlation at the zero phase difference, irrespective of the connection strength.

We observe two things in Figure A5. First, the long-range communication decreased and the short-range communication increased for high connection strength, \( w \). Second, the exact extent of the effective communication is dictated by the information index used, i.e., mutual information or correlation.

Unit A and B are defined by:

\[ O_A(t) = C \sin(2\pi ft + \Delta \phi_A) + A \sin(2\pi ft + \Delta \phi_A) \]

\[ O_B(t) = wC \sin(2\pi ft + \Delta \phi_A) + D \sin(2\pi ft + \Delta \phi_A) \]

(A4)

Unit C and D are defined by:

\[ O_C(t) = C \sin(2\pi ft + \Delta \phi_C) + A \sin(2\pi ft + \Delta \phi_C) \]

\[ O_D(t) = wC \sin(2\pi ft + \Delta \phi_C) + D \sin(2\pi ft + \Delta \phi_C) \]

We observe two things in Figure A5. First, the long-range communication decreased and the short-range communication increased for high connection strength, \( w \). Second, the exact extent of the effective communication is dictated by the information index used, i.e., mutual information or correlation.
A Gaussian amplitude distribution generates higher correlation than a uniform amplitude distribution. (A) Uniform amplitude distribution. (B) Distribution when the two units are connected, \( w = 1 \), for the bad coupled phase. (C,D) The same as (A) and (B) but using the superposition of multiple uniform distributions in order to approximate a Gaussian distribution. (D) In case of a Gaussian distribution, there is a correlation but, in case of a uniform distribution, there is none [see (B)].
Figure A3 | The PDPC as a function of the connection strength and three different topologies. The uni-directional model (A,B), the common drive model (C,D), and the bidirectional model (E,F) are all displayed in absolute correlation (left column) and min–max normalized correlation (right column). Note that the common drive case is the only one in which the 0 phase difference has a larger correlation than the π phase difference, irrespective of connection strength.
FIGURE A4 | The power correlation as a function of uncoupled phase difference is broader than the power correlation as a function of the coupled phase difference. (A) Uncoupled phase-dependent power correlation (top). Coupled phase difference is mapped with a pseudo color scale (bottom). The orange line indicates where the coupled phase difference is around 90°. At each uncoupled phase difference the slope of the orange line is different. If all the points representing coupled phase difference around 90° were pooled [see (B)], the resulting correlation would be less than the correlation seen for 90° of uncoupled phase difference. (B) Same as A, but with coupled phase difference. Note the relatively low correlation at a coupled phase difference of −90°. This explains why the coupled phase difference generates a narrower correlation curve than the uncoupled phase difference.
Oscillation coherency might modulate the extent of effective lateral long-range correlations. (A) The model consists of two linear units in the input layer and two linear units in the output layer. All units are defined according to the principles dictated by Eqs 3 and 4. (B) The amplitude and the phase coherency between the oscillations of the two input units increase as the connection strength between the two units increases. The “feed-forward” mutual information (see Materials and Methods) between unit A and C increases as the connection strength w increases. (C) The mutual information between the most distant units decreases as the connection strength w increases. The mapping from phase difference to cortical distance has been done by assuming a conduction velocity of 0.3 mm/ms and an oscillation frequency of 60 Hz (see Discussion). Note that the distance relationship is dependent on which information index (mutual information (black line) versus correlation (red line)) was used.