JOINT EXCITATION PROBABILITY FOR TWO HARMONIC OSCILLATORS IN DIMENSION ONE AND THE MOTT PROBLEM

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ABSTRACT. We analyze a one dimensional quantum system consisting of a test particle interacting with two harmonic oscillators placed at the positions $a_1$, $a_2$, with $a_1 > 0$, $|a_2| > a_1$, in the two possible situations: $a_2 > 0$ and $a_2 < 0$. At time zero the harmonic oscillators are in their ground state and the test particle is in a superposition state of two wave packets centered in the origin with opposite mean momentum. Under suitable assumptions on the physical parameters of the model, we consider the time evolution of the wave function and we compute the probability $P_{n_1 n_2}^{-}(t)$ (resp. $P_{n_1 n_2}^{+}(t)$) that both oscillators are in the excited states labelled by $n_1, n_2 > 0$ at time $t > |a_2| v^{-1}_0$, when $a_2 < 0$ (resp. $a_2 > 0$).

We prove that $P_{n_1 n_2}^{-}(t)$ is negligible with respect to $P_{n_1 n_2}^{+}(t)$, up to second order in time dependent perturbation theory.

The system we consider is a simplified, one dimensional version of the original model of a cloud chamber introduced by Mott in [M], where the result was argued using heuristic arguments in the framework of the time independent perturbation theory for the stationary Schrödinger equation.

The method of the proof is entirely elementary and it is essentially based on a stationary phase argument. We also remark that all the computations refer to the Schrödinger equation for the three-particle system, with no reference to the wave packet collapse postulate.

1. INTRODUCTION, NOTATION AND RESULT

In his paper of 1929 Mott ([M]) analyzes the dynamics of formation of tracks left an $\alpha$-particle emitted by a radioactive source inside the supersaturated vapour in a cloud chamber. He notices the difficulty to understand intuitively how a spherical wave function, describing the particle isotropically emitted by the source, might manifest itself as a straight track in the cloud chamber.

Without referring to any wave packet collapse, he proposes an explanation based on the analysis of the whole quantum system made up of the $\alpha$-particle and of the atoms of the vapour. Using a simplified model with only two atoms and making use of time independent perturbation arguments, he concludes that each ionization process focuses the probability of presence of the $\alpha$-particle on narrower and narrower cones, around the straight line connecting the source to the ionized atoms.
In this way Mott suggests a quantum dynamical mechanism responsible of the transition between an initial superposition of outgoing waves heading isotropically in all directions toward an incoherent (classical) sum of those same waves. We mention that the same problem is also discussed in [H] and later in [Be], where the above approach is compared with the explanation based on the wave packet collapse. We refer to [Br], [HA], [CL], [BPT] for some further elaborations on the subject and to [LR] for a description of the original experimental apparatus.

The aim of our work is to provide a detailed time dependent analysis of a one dimensional version of the system investigated by Mott. The system we consider consists of a test particle and two harmonic oscillators. In our model a superposition of two wave packets centered in the origin with opposite momentum plays the role of the spherical wave of the $\alpha$-particle and the oscillators replace the atoms to be ionized. Under suitable assumptions on the physical parameters of the model, we perform a detailed time analysis of the evolution of the system wave function using time dependent perturbation theory and we give a quantitative estimate of the joint excitation probability of the oscillators. Roughly speaking, our main result is that such probability is essentially zero if the oscillators are placed on opposite sides of the origin, while it has a finite, non-zero value in the other case. Following the line of reasoning of Mott, the result can be interpreted saying that before the interaction the test particle is delocalized while after the interaction it is either on the left (if there is an excited oscillator on the left) or on the right (if there is an excited oscillator on the right). In any case one can say that the test particle propagates along an almost classical trajectory, without making any reference to the wave packet collapse postulate.

In [CCF] the authors consider a similar problem in three dimensions where a particle interacts via zero range forces with localized two level quantum systems. A non perturbative analysis of the model is carried out but results are valid only in the scattering regime.

Let us introduce the model. We consider a three-particle non relativistic quantum system in dimension one, made of one test particle with mass $M$ interacting with two harmonic oscillators with the identical mass $m$. We denote by $R$ the position coordinate of the test particle and by $r_1, r_2$ the position coordinates of the two oscillators. The Hamiltonian of the system in $L^2(\mathbb{R}^3)$ is

\begin{align}
H &= H_0 + \lambda H_1 \\
H_0 &= -\frac{\hbar^2}{2M} \Delta_R - \frac{\hbar^2}{2m} \Delta_{r_1} + \frac{1}{2} m \omega^2 (r_1 - a_1)^2 - \frac{\hbar^2}{2m} \Delta_{r_2} + \frac{1}{2} m \omega^2 (r_2 - a_2)^2 \\
H_1 &= V(\delta^{-1}(R - r_1)) + V(\delta^{-1}(R - r_2))
\end{align}

where $\lambda > 0$, $\omega > 0$, $a_1 > 0$, $a_2 \in \mathbb{R}$, with $a_1 < |a_2|$, $\delta > 0$ and $V$ is a smooth interaction potential. The assumptions on $V$ will guarantee that the Hamiltonian $H$ is self-adjoint with the same domain of $H_0$ and then the evolution problem corresponding to the Hamiltonian $H$ is well posed. For the test particle we choose an initial state $\psi$ in the form of a superposition
state

\[ \psi(R) = \psi^+(R) + \psi^-(R) \]  
\[ \psi^\pm(R) = \mathcal{N} e^{-\frac{a_1^2}{2\sigma}} e^{\pm i\frac{P_0}{\hbar} R}, \quad P_0 = M v_0 \]  

where \( \sigma > 0, \mathcal{N} = \left[2\sqrt{\pi}(1 + e^{-\frac{(P_0^2)^2}{\sigma^2}})\right]^{-1/2} \) is the normalization factor and \( P_0, v_0 \) denote the absolute value of the initial mean momentum and velocity of the test particle.

For the harmonic oscillator centered in \( a_j, j = 1, 2 \), the initial state \( \phi_0^{a_j} \) is the corresponding ground state. Moreover we define

\[ \phi_{n_j}^{a_j}(r_j) = \frac{1}{\sqrt{\gamma}} \phi_{n_j}(\gamma^{-1}(r_j - a_j)) \]  
\[ \gamma = \sqrt{\frac{\hbar}{m\omega}} \]  

where \( \phi_m \) is the normalized Hermite function of order \( m \in \mathbb{N} \). We notice that the parameter \( \gamma \) has the dimension of a length and gives a measure of the spatial localization of the oscillators.

Let us denote by \( \Psi(R, r_1, r_2, t) \) the wave function of the system; \( \Psi(t) \equiv \Psi(\cdot, \cdot, \cdot, t) \) is the solution of the Cauchy problem

\[ i\hbar \frac{\partial}{\partial t} \Psi(t) = H \Psi(t) \]  
\[ \Psi(0) = \psi \phi_0^{a_1} \phi_0^{a_2} \]  

We are interested in the probability that both harmonic oscillators are in an excited state at a given time \( t > 0 \). The solution of the three-body problem (1.8), (1.9) is not known in closed form; we shall limit ourselves to a perturbative computation. It is worth mentioning that, in order to get a non trivial result, we are forced to compute the second order approximation of the solution of the Cauchy problem (1.8), (1.9), which we denote by \( \Psi_2(R, r_1, r_2, t) \). Therefore the object of our analysis is the quantity

\[ \mathcal{P}_{n_1, n_2}^\pm(t) = \int dR \left| \int dr_1 dr_2 \phi_{n_1}^{a_1}(r_1) \phi_{n_2}^{a_2}(r_2) \Psi_2(R, r_1, r_2, t) \right|^2 \]  

for \( n_1 \neq 0 \) and \( n_2 \neq 0 \), where \( \pm \) refers to the cases \( a_2 > 0 \) and \( a_2 < 0 \) respectively. Formula (1.10) represents the probability that both oscillators are in an excited state at time \( t \), up to second order in perturbation theory.

The explicit computation of (1.10) will be performed exploiting some further assumptions on the physical parameters of the model. More precisely the complete set of assumptions required for our analysis is the following
The quantities $\delta m \equiv \frac{m}{M}$, $\delta E \equiv \frac{\hbar \omega}{M v_0}$, $\delta R \equiv \frac{\sigma}{|a_j|}$, $\delta L \equiv \frac{\delta}{|a_j|}$, $\delta \tau_j \equiv \frac{v_0}{\omega |a_j|}$, for $j = 1, 2$, are all $O(\varepsilon)$ where

$$\lambda_0 \ll \varepsilon \ll 1 \quad (1.12)$$

The interaction potential $V : \mathbb{R} \to \mathbb{R}$ is a continuous, positive and compactly supported function.

Let us briefly comment on the above assumptions. In $(A_0)$ we ensure that the dimensionless coupling constant $\lambda_0$ is small. In $(A_1)$ we assume that the mass and the kinetic energy of the test particle are much larger than the mass and the spacing of the energy levels of the oscillators; moreover the initial wave packets of the test particle are assumed to be well localized and the interaction is required to be short range; finally the characteristic time of the oscillators $\omega^{-1}$ is assumed to be much smaller than the flight times $\tau_1, \tau_2$ of the test particle, which are defined by

$$\tau_1 = \frac{a_1}{v_0}, \quad \tau_2 = \frac{|a_2|}{v_0} \quad (1.13)$$

Condition $(1.12)$ guarantees that the first and second order corrections in perturbation theory remain small compared with the unperturbed wave function, in fact of order $\lambda_0^2 \varepsilon^{-2}$ and $\lambda_0^3 \varepsilon^{-3}$ respectively.

In order to understand the meaning of $(A_1)$, let us consider the parameters $M, v_0, a_1, a_2$ all of order one. Then we obtain $m = O(\varepsilon), \omega = O(\varepsilon^{-1}), \hbar \omega = O(\varepsilon), \sigma = O(\varepsilon), \delta = O(\varepsilon)$.

We observe that the length $\gamma$ introduced in $(1.7)$ can be written as

$$\gamma = a_1 \delta \tau_1 \sqrt{\frac{\delta E}{\delta m}} \quad (1.14)$$

and this means that $\gamma$ is of the same order of $\delta$ and $\sigma$. In particular this guarantees that the transit time of the test particle on the region where the oscillators are localized is of the same order of the characteristic time of the oscillators. To simplify the notation, from now on we shall fix

$$\delta = \gamma \quad (1.15)$$

We also introduce here a (large) parameter which is useful to express the various estimates in the proof.
\[ \Lambda_j \equiv \frac{|a_j|}{\gamma} = O(\varepsilon^{-1}), \quad j = 1, 2 \] (1.16)

Our main result is the following.

**Theorem 1.** Let us assume \((A_0), (A_1), (A_2)\) and fix \(t > \tau_2, n_1 \neq 0, n_2 \neq 0\). Then for any \(k \in \mathbb{N}, \) with \(k > 2\), we have

\[
\mathcal{P}^-_{n_1n_2}(t) \leq \frac{1}{\Lambda_1^{2k-4}} \left( \frac{\lambda_0}{\varepsilon} \right)^4 C_{n_1n_2}^{(k)}(t) \tag{1.17}
\]

\[
\mathcal{P}^+_{n_1n_2}(t) = 16\pi^4 \sqrt{\pi} \left( \frac{\lambda_0}{\varepsilon} \right)^4 N^2 \left( \prod_{j=1,2} V(q_j)\widetilde{(\phi_{n_j}\phi_0)}(q_j) \right)^2 + S_{n_1n_2}(t) \tag{1.18}
\]

\[
q_j = -n_j \sqrt{\frac{\delta E}{\delta m}} \tag{1.19}
\]

\[
|S_{n_1n_2}(t)| \leq \frac{1}{\Lambda_1} \left( \frac{\lambda_0}{\varepsilon} \right)^4 D_{n_1n_2}(t) \tag{1.20}
\]

where the symbol \(\sim\) denotes Fourier transform and \(C_{n_1n_2}^{(k)}(t), D_{n_1n_2}(t)\) are functions of the physical parameters of the model which will be explicitly given during the proof (see (4.16), (4.19) below).

We remark that the estimates (1.17), (1.18), (1.20) are not optimal; in particular \(C_{n_1n_2}^{(k)}(t), D_{n_1n_2}(t)\) diverge for \(t \to \infty\). From (1.16), (1.19) it will be clear that \(C_{n_1n_2}^{(k)}(t), D_{n_1n_2}(t)\) are of order one, and then the estimates are meaningful only for \(t\) larger but of the same order of \(\tau_2\). Let us briefly outline the strategy of the proof and give a heuristic argument which, at least at a qualitative level, justifies the result stated in theorem 1. We find convenient to represent the solution of (1.8), (1.9) in the form

\[
\Psi(R, r_1, r_2, t) = \sum_{n_1, n_2} f_{n_1n_2}(R, t)\phi_{n_1}^{a_1}(r_1)\phi_{n_2}^{a_2}(r_2) \tag{1.21}
\]

where \(f_{n_1n_2}(\cdot, t) = f_{n_1n_2}(t)\) belongs to \(L^2(\mathbb{R})\) for any \(n_1, n_2 \in \mathbb{N}\) and \(t \geq 0\), and it is explicitly given by

\[
f_{n_1n_2}(R, t) = \int d r_1 d r_2 \phi_{n_1}^{a_1}(r_1)\phi_{n_2}^{a_2}(r_2)\Psi(R, r_1, r_2, t) \tag{1.22}
\]

We notice that the coefficients of the expansion \(f_{n_1n_2}(R, t)\) have a precise physical meaning; in fact the quantity

\[
\int_{\Omega} d R |f_{n_1n_2}(R, t)|^2 \tag{1.23}
\]
The result is

Iterating twice equation (1.25) we obtain

\[ \Psi(t) = e^{-\frac{i}{\hbar}tH_0}\Psi_0 - i\frac{\lambda}{\hbar} \int_0^t ds \ e^{-\frac{i}{\hbar}(t-s)H_0} H_1 \Psi(s) \]  

(1.24)

multiplying by \( \phi_{n_1}^a \phi_{n_2}^a \) and then integrating with respect to the coordinates of the oscillators. The result is

\[ f_{n_1n_2}(t) = f_{n_1n_2}^{(0)}(t) - \int_0^t ds \ \Gamma_{n_1n_2}(t - s) \left( \sum_{j_1} V_{n_1j_1}^{a_1} f_{j_1n_2}^{(0)}(s) + \sum_{j_2} V_{n_2j_2}^{a_2} f_{n_1j_2}^{(0)}(s) \right) \]  

(1.25)

where in the above formula we have introduced the notation

\[ f_{n_1n_2}^{(0)}(t) = \delta_{n_10} \delta_{n_20} e^{-2\frac{i}{\hbar}tE_0} e^{-\frac{i}{\hbar}tK_0} \psi \]  

(1.26)

\[ K_0 = -\frac{\hbar^2}{2M} \Delta R \]  

(1.27)

\[ \Gamma_{n_1n_2}(t) = i\frac{\lambda}{\hbar} e^{-\frac{i}{\hbar}(E_{n_1} + E_{n_2})} e^{-\frac{i}{\hbar}tK_0} \]  

(1.28)

\[ V_{mn}(x) = \int dy \ \phi_{m}^{i_a}(y) \phi_{n}^{i_a}(y) V(\gamma^{-1}(x - y)), \quad m, n \in \mathbb{N}, \ i = 1, 2 \]  

(1.29)

We want to give an estimate of the solution of (1.25) up to second order in perturbation theory. Iterating twice equation (1.25) we obtain

\[ f_{n_1n_2}(t) = f_{n_1n_2}^{(0)}(t) + f_{n_1n_2}^{(1)}(t) + f_{n_1n_2}^{(2)}(t) + \mathcal{E}_{n_1n_2}(t) \]  

(1.30)

where

\[ f_{n_1n_2}^{(1)}(t) = -\int_0^t ds \ \Gamma_{n_1n_2}(t - s) \left( \sum_{j_1} V_{n_1j_1}^{a_1} f_{j_1n_2}^{(0)}(s) + \sum_{j_2} V_{n_2j_2}^{a_2} f_{n_1j_2}^{(0)}(s) \right) \]  

(1.31)

\[ f_{n_1n_2}^{(2)}(t) = -\int_0^t ds \ \Gamma_{n_1n_2}(t - s) \left( \sum_{j_1} V_{n_1j_1}^{a_1} f_{j_1n_2}^{(1)}(s) + \sum_{j_2} V_{n_2j_2}^{a_2} f_{n_1j_2}^{(1)}(s) \right) \]  

(1.32)

and \( \mathcal{E}_{n_1n_2}(t) \) is the error term which we shall neglect in the sequel. Obviously we have

\[ \Psi_2(R, r_1, r_2, t) = \sum_{n_1, n_2} \left( f_{n_1n_2}^{(0)}(R, t) + f_{n_1n_2}^{(1)}(R, t) + f_{n_1n_2}^{(2)}(R, t) \right) \phi_{n_1}^{a_1}(r_1) \phi_{n_2}^{a_2}(r_2) \]  

(1.33)

Exploiting the explicit expression (1.26) of \( f_{n_1n_2}^{(0)}(t) \), we can write \( f_{n_1n_2}^{(1)}(t) \) in the form
From formula (1.34) it is clear that \( f_{n_{1}n_{2}}^{(1)}(t) = 0 \) if \( n_{1} \neq 0 \) and \( n_{2} \neq 0 \). As expected, this means that the probability that both oscillators are in an excited state is zero up to first order in perturbation theory. As a consequence, from (1.10) we get

\[
P_{n_{1}n_{2}}^{\pm}(t) = \int dR |f_{n_{1}n_{2}}^{(2)}(R, t)|^2, \quad n_{1} \neq 0, n_{2} \neq 0
\]

(1.35)

Following the original strategy of Mott, a crucial point of the analysis is the explicit evaluation of \( f_{n_{1}0}^{(1)}(t) \) and \( f_{n_{2}0}^{(1)}(t) \). We notice that \( V_{n_{1}0}^{a_{1}}(x) \) and \( (e^{-\frac{i}{\hbar}K_{0}\psi^{\pm}})(x) \) are essentially different from zero only for \( x \simeq a_{1} \) and \( x \simeq \pm v_{0}s \) respectively. This means that the only non zero contribution to the time integral defining \( f_{n_{1}0}^{(1)}(t) \) comes from \( \psi^{+} \) and such contribution is essentially concentrated around \( s = \frac{a_{1}}{v_{0}} = \tau_{1} \). Hence we can argue that \( f_{n_{1}0}^{(1)}(t) \) is approximately given by a wave packet starting at time \( \tau_{1} \) from the position \( a_{1} \) of the first oscillator, with a velocity close to \( v_{0} \). In particular it is essentially different from zero only in a neighborhood of \( a_{1} + v_{0}(t - \tau_{1}) \), for \( t > \tau_{1} \).

Analogously, \( f_{n_{2}0}^{(1)}(t) \) is approximately given by a wave packet starting at time \( \tau_{2} \) from the position \( a_{2} \) of the second oscillator, with a velocity close to \( v_{0} \) if \( a_{2} > 0 \), and to \( -v_{0} \) if \( a_{2} < 0 \). Then \( f_{n_{2}0}^{(1)}(t) \) is essentially different from zero only in a neighborhood of \( a_{2} + v_{0}(t - \tau_{2}) \), for \( t > \tau_{2} \), \( a_{2} > 0 \), and in a neighborhood of \( a_{2} - v_{0}(t - \tau_{2}) \), for \( t > \tau_{2} \), \( a_{2} < 0 \).

Let us now consider the second order term \( f_{n_{1}n_{2}}^{(2)}(t) \); exploiting expression (1.34), we have

\[
f_{n_{1}n_{2}}^{(2)}(t) = -\delta_{n_{2}0} \int_{0}^{t} ds \Gamma_{n_{1}0}(t - s) \sum_{j_{1}} V_{n_{1}j_{1}}^{a_{1}} f_{j_{1}0}^{(1)}(s) - \delta_{n_{1}0} \int_{0}^{t} ds \Gamma_{0n_{2}}(t - s) \sum_{j_{2}} V_{n_{2}j_{2}}^{a_{2}} f_{0j_{2}}^{(1)}(s)
\]

\[
- \int_{0}^{t} ds \Gamma_{n_{1}n_{2}}(t - s) V_{n_{1}0}^{a_{1}} f_{0n_{2}}^{(1)}(s) - \int_{0}^{t} ds \Gamma_{n_{1}n_{2}}(t - s) V_{n_{2}0}^{a_{2}} f_{n_{1}0}^{(1)}(s)
\]

(1.36)

Since we are interested in the probability that both oscillators are excited, only the last two terms of (1.36) are relevant.

We notice that the supports of \( V_{n_{1}0}^{a_{1}} \) and \( f_{n_{2}0}^{(1)}(s) \) are essentially disjoint for any \( s \geq 0 \) and this implies that the third term in the r.h.s. of (1.36) gives a negligible contribution.

For the same reason, the fourth term in the r.h.s. of (1.36) is also approximately zero if \( a_{2} < 0 \). This explains why we expect that an estimate like (1.17) holds.
On the other hand, in the case \( a_2 > 0 \) the product \( V_{n_2}^{a_2} f_{n_1 0}^{(1)}(s) \) is different from zero for \( s \approx \tau_2 \). In such case the fourth term in the r.h.s. of (1.36) gives a non zero contribution and this explains why we can expect that a formula like (1.18) holds.

We collect here some further notation which will be used in the paper:
- \( \langle x \rangle \) denotes \((1 + x^2)^{1/2}\);
- \( d^k_x f \) is the derivative of order \( k \) with respect to \( x_l \) of a smooth function \( f(x_1, \ldots, x_n) \), for \( n \in \mathbb{N} \) and \( l = 1, \ldots, n \);
- \( \| f \|_{W^k_1} = \sum_{l=1}^{n} \sum_{m=0}^{k} \int dx \langle x \rangle^s |(d^m_x f)(x)| \), \( k \in \mathbb{N} \), \( s \geq 0 \);
- \( \| f \|_{L^1} = \| f \|_{W^0_1} \);
- \( c \) is a generic positive numerical constant.

The paper is organized as follows. In section 2 we study the first order approximation step. In section 3 we analyze the second order approximation, distinguishing the two cases \( a_2 > 0 \) and \( a_2 < 0 \). In section 4 we compute the joint excitation probability of the two oscillators concluding the proof of theorem 1. Finally in the appendix we give a proof of a technical lemma.

2. FIRST ORDER APPROXIMATION

In this section we fix \( t > \tau_j, j = 1, 2 \), and we give an estimate of the first order terms \( f_{n_j 0}^{(1)}(t) \). We only give the details for the case \( a_2 > 0 \) since the opposite case can be treated similarly. We rewrite \( f_{n_j 0}^{(1)}(t) \) as follows

\[
f_{n_j 0}^{(1)}(t) = f_{n_j 0}^{(1)+}(t) + f_{n_j 0}^{(1)-}(t)
\]

Moreover let us define for \( j = 1, 2 \) and \( s, t \geq 0 \)

\[
\mathcal{I}_j(s) = e^{\frac{i}{\hbar} s K_0} V^{a_j}_{n_j 0} e^{-\frac{i}{\hbar} s K_0}
\]

\[
h_j^{\pm}(t) = \int_0^t ds e^{i n_j \omega s} \mathcal{I}_j(s) \psi^{\pm}
\]

As a first step the operator (2.3) will be written in a more convenient form.

**Lemma 2.1.** For any \( f \in L^2(\mathbb{R}) \) and \( s \geq 0 \) the following identity holds

\[
(\mathcal{I}_j(s)f)(R) = \int d\xi \ g_j(\xi) f(R + (M\gamma)^{-1} \hbar s \xi) e^{\frac{i}{\hbar} \frac{s}{2M\gamma} \xi^2} e^{i\frac{\xi}{\hbar} R} e^{-i\Lambda_j \xi}
\]
where
\[ g_j(\xi) = \tilde{V}(\xi) \langle \phi_n, \phi_0 \rangle(\xi) \] (2.6)

**Proof.** Exploiting the explicit expression of the free propagator we have

\[
\left( e^{\frac{sK_0}{\hbar}} V_{n,j}^{a_j} e^{-\frac{sK_0}{\hbar} f} \right)(R)
\]
\[
= \frac{M}{2\pi\hbar s} e^{-i\frac{M}{\hbar s} R^2} \int dx e^{i\frac{M}{\hbar s} R x} V_{n,j}^{a_j}(x) \int dy f(y) e^{i\frac{M}{\hbar s} y^2 - i\frac{M}{\hbar s} xy}
\]
\[
= \frac{M}{2\pi\hbar s} e^{-i\frac{M}{\hbar s} R^2} \int dy f(y) e^{i\frac{M}{\hbar s} y^2} \int dx V_{n,j}^{a_j}(x) e^{-i\left(\frac{M}{\hbar s} - \frac{M R}{\hbar s}\right)x}
\]
\[
= \frac{M}{\sqrt{2\pi\hbar s}} e^{-i\frac{M}{\hbar s} R^2} \int dy f(y) e^{i\frac{M}{\hbar s} y^2} V_{n,j}^{a_j}(M h s)^{-1}(y - R)
\]
\[
= \frac{1}{\sqrt{2\pi\gamma}} \int d\xi f(R + (M\gamma)^{-1} h s \xi) e^{i\frac{R}{\gamma} \xi + i\frac{h}{2\pi\gamma}\xi^2} \tilde{V}^{a_j}_{n,j}(\gamma^{-1}\xi)
\] (2.7)

where in the last line we have introduced the new integration variable \( \xi = M\gamma(h s)^{-1}(y - R) \).

Using the convolution property of Fourier transform we have

\[
V_{n,j}^{a_j}(x) = \frac{1}{\gamma} \int dy \phi_n(\gamma^{-1}(y - a_j)) \phi_0(\gamma^{-1}(y - a_j)) V(\gamma^{-1}(x - y))
\]
\[
= \int dz V(z) \left( \phi_n, \phi_0 \right)(\gamma^{-1}(x - a_j - \gamma z))
\]
\[
= \gamma \int dk \tilde{V}(\gamma k) \left( \phi_n, \phi_0 \right)(\gamma k) e^{i(x - a_j)k}
\] (2.8)

Hence
\[
\tilde{V}^{a_j}_{n,j}(k) = \sqrt{2\pi\gamma} \tilde{V}(\gamma k) \left( \phi_n, \phi_0 \right)(\gamma k) e^{-i a_j k}
\] (2.9)

Using (2.9) in (2.7) and introducing the large parameter \( \Lambda_j = \frac{a_j}{\gamma} \) we conclude the proof.

□

Using the above lemma we can rewrite also the integral in (2.4).

**Lemma 2.2.**

\[
h_j^\pm(t) = \int_0^t ds \int d\xi F_j^\pm(\cdot, \xi, s) e^{i\Lambda_j \theta_j^\pm(\xi, s)}
\] (2.10)
where

\[
F_j^\pm (R, \xi, s) = g_j(\xi) e^{i\frac{\hbar s}{2Mr^2} \xi^2} \hat{\psi}_1^\pm (R, \xi, s)
\]  \hspace{1cm} (2.11)

\[
\hat{\psi}_1^\pm (R, \xi, s) = \frac{N}{\sqrt{\sigma}} e^{i \frac{(R-R_1)^2}{2\sigma^2} \pm i \frac{\hbar}{R}}
\]  \hspace{1cm} (2.12)

\[
\hat{R}_1 = -\frac{\hbar}{M\gamma} \xi, \quad \hat{P}^{\pm}_1 = P_0 \pm \frac{\hbar}{\gamma} \xi
\]  \hspace{1cm} (2.13)

\[
\theta_j^\pm (\xi, s) = (\pm \frac{s}{\tau_j} - 1) \xi - q_j \frac{s}{\tau_j}
\]  \hspace{1cm} (2.14)

and \(q_j\) has been defined in (1.19).

**Proof.** The proof is trivial if we notice that

\[
\psi^\pm (R + (M\gamma)^{-1}\hbar s \xi) e^{i \hat{R}_1} = \hat{\psi}_1^\pm (R, \xi, s) e^{\pm i \Lambda_j \xi^{\pm}}
\]  \hspace{1cm} (2.15)

and use lemma 2.1.

\[\square\]

The next step is to estimate (2.10), i.e. an integral containing the rapidly oscillating phase \(\Lambda_j \theta_j^\pm (\xi, s)\). The standard stationary (or non-stationary) phase methods can be used to obtain the estimate.

It is worth mentioning that the integral in (2.10) contains also other phase factors depending on \((\xi, s)\) which, however, are slowly varying under our assumptions on the physical parameters of the model.

The asymptotic analysis for \(\Lambda_j \to \infty\) is simplified by the fact that \(\theta_j^\pm (\xi, s)\) is a quadratic function. The only critical points of the phase are \((\pm q_j, \pm \tau_j)\) and, moreover, the hessian matrix is non degenerate, with eigenvalues \(\pm \tau_j^{-1}\). This means that the behaviour of (2.10) for \(\Lambda_j \to \infty\) in the case with \(\theta_j^-\) is radically different from the case with \(\theta_j^+\), due to the fact that in the first case the critical point never belongs to the domain of integration while in the second case this happens for \(t > \tau_j\).

For the analysis of this second case it will be useful the following elementary lemma. For the convenience of the reader a proof of the lemma will be given in the appendix.

**Lemma 2.3.** Let us consider for any \(\Lambda > 0\)

\[
\mathcal{J}(\Lambda) = \int dx \int_{\mu}^{\nu} dy \ f(x, y) e^{i\Lambda xy}
\]  \hspace{1cm} (2.16)

where \(\mu, \nu\) are positive parameters, \(f\) is a complex-valued, sufficiently smooth function. Then
\[ J(\Lambda) = \frac{1}{\Lambda} K_1(\Lambda) \]  
\[ = \frac{1}{\Lambda} 2\pi f(0,0) + \frac{1}{\Lambda^2} K_2(\Lambda) \]  
\[ = \frac{1}{\Lambda} 2\pi f(0,0) + \frac{1}{\Lambda^2} 2\pi i d_x d_y f(0,0) + \frac{1}{\Lambda^3} K_3(\Lambda) \]

where \( K_l(\Lambda), \ l = 1, 2, 3, \) are explicitly given (see the appendix) and satisfy the estimates

\[ |K_1(\Lambda)| \leq c_1 \left( \| f(\cdot,0) \|_{L^1} + \int dx \| d_x d_y f(\cdot,\cdot) \|_{L^2} \right) \]  
\[ |K_2(\Lambda)| \leq c_2 \left( \| d_x^2 f(\cdot,0) \|_{L^1} + \| d_x d_y f(\cdot,0) \|_{L^1} + \int dx \| d_x^2 d_y^2 f(\cdot,\cdot) \|_{L^2} \right) \]  
\[ |K_3(\Lambda)| \leq c_3 \left( \| d_x^3 f(\cdot,0) \|_{L^1} + \| d_x^2 d_y f(\cdot,0) \|_{L^1} + \| d_x^2 d_y^2 f(\cdot,\cdot) \|_{L^1} + \int dx \| d_x^3 d_y^3 f(\cdot,\cdot) \|_{L^2} \right) \]

and the constants \( c_1, c_2, c_3 \) depend only on \( \mu, \nu. \)

Exploiting lemma 2.3 we obtain the following asymptotic behaviour of (2.10) for \( t > \tau_j \) when the phase is \( \theta_j^+ \).

**Proposition 2.4.** For any \( t > \tau_j \) we have

\[ h_j^+(t) = \frac{2\pi \tau_j}{\Lambda_j} e^{-i\Lambda_j \theta_j} F_j^+(\cdot, q_j, \tau_j) + \frac{1}{\Lambda_j^2} R_j^+(\cdot, t, \Lambda_j) \]

where

\[ |R_j^+(R, t, \Lambda_j)| \leq C_j \left[ \int d\xi |d_\xi^2 F_j^+(R, \xi, \tau_j)| + \int d\xi |d_\xi d_s F_j^+(R, \xi, \tau_j)| \right. \]

\[ + \left. \int d\xi \left( \int_0^t ds |d_\xi^2 d_s^2 F_j^+(R, \xi, s)|^2 \right)^{1/2} \right] \]

and \( C_j \) depends on \( t \) and \( \tau_j \).

**Proof.** Let us introduce the change of coordinates \( x = \xi - q_j, \ y = s - \tau_j \) in (2.10) and the shorthand notation \( F(x, y) = e^{-i\Lambda_j \theta_j} F_j^+(R, x + q_j, y + \tau_j) \). Then
\[ h_j^+(t) = \int dx \int_{t-\tau_j}^{t} dy \ F(x,y) \ e^{i\Lambda_j xy} \] (2.25)

The integral in (2.25) has the same form as the integral (2.16) analysed in lemma 2.3, if we identify \( \nu, \mu, f, \Lambda \) with \( \tau_j, t - \tau_j, F, \Lambda \) respectively. Then, exploiting formula (2.18), we obtain the r.h.s. of (2.23) with

\[ R_j^+(R, t, \Lambda_j) = -\tau_j^2 \int dx \frac{F(x,0) - F(0,0) - d_x F(x,0)x}{x^2} \left( \frac{e^{i\Lambda_j (t-\tau_j)x}}{t - \tau_j} + \frac{e^{-i\Lambda_j x}}{\tau_j} \right) \]

\[ + \tau_j^2 \int dx \int d_x d_y F(x,0) \left( \frac{e^{i\Lambda_j (t-\tau_j)x}}{x} - e^{-i\Lambda_j x} \right) \]

\[ - \tau_j^2 \int_{t-\tau_j}^{t} dy \int dx \frac{d_x^2 F(x,y) - d_x^2 F(x,0) - d_x^2 d_y F(x,0)y}{y^2} e^{i\Lambda_j xy} \] (2.26)

Using (2.24) we immediately get the estimate (2.24) and this concludes the proof.

In the next proposition we shall analyze the asymptotic behaviour of (2.10) when the phase is \( \theta_j^- \). Taking into account the error term in (2.23), it is sufficient to show that \( h_j^-(t) = O(\Lambda_j^{-2}) \); on the other hand we remark that, following the same line, it is easy to extend the result to \( h_j^-(t) = O(\Lambda_j^{-k}) \), for any integer \( k \).

**Proposition 2.5.** For any \( t > 0 \) we have

\[ h_j^-(t) = \frac{1}{\Lambda_j^2} \mathcal{R}_j^-(\cdot, t, \Lambda_j) \] (2.27)

where

\[ |\mathcal{R}_j^-(R, t, \Lambda_j)| \leq \int_0^t ds \int d\xi |d_x^2 F_j^-(R, \xi, s)| \] (2.28)

**Proof.** If we notice that

\[ e^{i\Lambda_j \theta_j^- (\xi, s)} = \frac{1}{\left[ -i\Lambda_j \left( \frac{s}{\tau_j} + 1 \right) \right]^2} d_x^2 e^{i\Lambda_j \theta_j^- (\xi, s)} \] (2.29)
and integrate by parts two times in the r.h.s. of (2.10) we easily obtain the r.h.s. of (2.27) with

\[ R_j^{-}(R, t, \Lambda_j) = -\frac{\tau_j^2}{2} \int_0^t ds \frac{1}{(s + \tau_j)^2} \int d\xi \left( d^2 F^-_j(R, \xi, s) \right) e^{i\Lambda_j \theta_j^-(\xi, s)} \] (2.30)

Then by a trivial estimate we conclude the proof.

\[ \square \]

Collecting together the results of propositions 2.4 and 2.5 we finally obtain an asymptotic expression for \( t > \tau_j \) of the first order terms when \( \Lambda_j \to \infty \)

\[ f^{(1)}_{n_0}(t) = \frac{\mathcal{A}^{(1)}_j}{\Lambda_j} e^{-i K_0 \psi_j^+} + \frac{1}{\Lambda_j^2} \mathcal{R}^{(1)}_j(\cdot, t, \Lambda_j) \] (2.31)

\[ \mathcal{A}^{(1)}_j = -2\pi i \frac{\lambda \tau_j}{\hbar} e^{-i(n_j + 1)\omega t - i\Lambda_j q_j + i \frac{b \tau_j^2}{2M \gamma} q_j^2} g_j(q_j) \] (2.32)

\[ \psi_j^+ = \hat{\psi}_j^+(\cdot, q_j, \tau_j) \] (2.33)

\[ \mathcal{R}^{(1)}_j(\cdot, t, \Lambda_j) = -\Gamma_{n_0}(t) \left( \mathcal{R}_j^-(\cdot, t, \Lambda_j) + \mathcal{R}_j^+(\cdot, t, \Lambda_j) \right) \] (2.34)

We observe that the leading term in the r.h.s. of (2.31) can be more conveniently written in the form

\[ \frac{\mathcal{A}^{(1)}_j}{\Lambda_j} e^{-i K_0 \psi_j^+} = -2\pi i \frac{\lambda_0}{\sqrt{\delta m \delta E}} e^{i \eta_j(t) \tilde{V}(q_j) \tilde{\phi}_n(q_j)} e^{-i K_0 \psi_j^+} \] (2.35)

\[ \eta_j(t) = \frac{n_j^2 \delta E}{2 \delta \tau_j} - (n_j + 1)\omega t + \frac{n_j}{\delta \tau_j} \] (2.36)

\[ \psi_j^+(R) = \frac{b}{\sqrt{\sigma}} e^{-\frac{(R - R_j)^2}{2\sigma^2} + i R_j - R_j} \quad R_j = n_j a_j \delta E, \quad P_j = P_0(1 - n_j \delta E) \] (2.37)

Then it is clear that the leading term has the form of a free evolution of a wave packet which starts at \( t = \tau_j \) from the position \( a_j \) of \( j^{th} \) oscillator, with mean momentum \( P_j \). Notice that under our assumptions \( P_j \simeq P_0 > 0 \).

In particular (2.31) gives a precise meaning to the qualitative statement concerning the approximate behavior of \( f^{(1)}_{n_j0}(t) \) made in section 1.
3. Second order approximation

In this section we fix \( t > \tau_2 \) and consider the second order terms corresponding to both oscillators in some exited states, i.e. terms of the type (see formula (1.36))

\[
- \int_0^t ds \, \Gamma_{n_jn_l}(t - s) \, V_{n_0}^{\alpha_1} f_{n_0}^{(1)}(s)
\]

\[
= i \frac{\lambda}{\hbar} \Gamma_{n_jn_l}(t) \int_0^t ds \, e^{i\eta s} \int_0^s ds' \, e^{inj_s' \mathcal{I}_j(s') \mathcal{I}_j(s') \psi^+} (3.1)
\]

\[
\equiv i \frac{\lambda}{\hbar} \Gamma_{n_jn_l}(t) \, h_{jl}^\pm(t) (3.2)
\]

for \( j, l = 1, 2, \, l \neq j \). Proceeding as in lemmas 2.1 and 2.2, a straightforward computation in the case \( a_2 > 0 \) yields

\[
h_{jl}^\pm(t) = \int_0^t ds \int_0^s ds' \int d\xi \int d\eta \, G_{jl}^\pm(\xi, \xi', \eta, \eta) \, e^{i\Lambda_j \theta_j^\pm(\xi, \eta') + i\Lambda_1 \theta_1^\pm(\eta, \eta)} (3.3)
\]

\[
G_{jl}^\pm(R, \xi, \xi', \eta, \eta) = g_j(\xi)g_l(\eta) \, e^{i\frac{\hbar}{2M\gamma}(s'\xi^2 + m^2 \eta^2 + 2s\xi \eta)} \psi^\pm_{2}(R, \xi, \xi', \eta, \eta) (3.4)
\]

\[
\hat{\psi}_2^\pm(R, \xi, \xi', \eta, \eta) = \frac{N}{\sqrt{\sigma}} e^{-\frac{(R - R_2\gamma)}{2s^2} + i\frac{\hbar}{\gamma} - R} (3.5)
\]

\[
\hat{R}_2 = -\frac{\hbar}{M\gamma}(\xi\xi' + \eta\eta), \quad \hat{P}_2^\pm = P_0 \pm \frac{\hbar}{\gamma}(\xi + \eta) (3.6)
\]

where \( g_j \) and \( \theta_j^\pm \) have been defined in (2.10) and (2.11) respectively. In the case \( a_2 < 0 \) the same representation formula (3.3) holds if we replace \( \Lambda_2, \, \tau_2 \) with \(-\Lambda_2, \, -\tau_2 \), where \( \Lambda_2 = |a_2|\gamma^{-1}, \, \tau_2 = |a_2|\tau_0^{-1} \). In both cases, we shall discuss the asymptotic behaviour of \( h_{jl}^\pm(t) \) for \( \Lambda_1, \, \Lambda_2 \to \infty \).

The integral (3.3) contains a rapidly oscillating phase and moreover the phase has exactly one critical point. Therefore the behaviour strongly depends on whether or not the critical point lies in the integration domain. We shall analyze separately the two cases \( a_2 > 0 \) and \( a_2 < 0 \).

3.1. The case \( a_2 > 0 \).

We distinguish the four possible cases: i) \( h_{21}^\pm(t) \), ii) \( h_{21}^\pm(t) \), iii) \( h_{12}^\pm(t) \), iv) \( h_{12}^\pm(t) \). It is easily seen that the point \((\xi_0, s_0', \eta_0, s_0) \) where the phase is stationary is: \((q_2, \tau_2, q_1, \tau_1) \) for i), \((-q_2, -\tau_2, -q_1, -\tau_1) \) for ii) and \((-q_1, -\tau_1, -q_2, -\tau_2) \) for iii). In all three cases the stationary point of the phase does not belong to the domain of integration and then the integral rapidly decreases to zero for \( \Lambda_1, \, \Lambda_2 \to \infty \). On the other hand in the case iv) the stationary point is \((q_1, \tau_1, q_2, \tau_2) \), i.e. it belongs to the domain of integration and therefore there is a leading term.
of order \((\Lambda_1\Lambda_2)^{-1}\) which we shall compute. In the next proposition we study the cases iv) following the same line of the proof of proposition 2.4.

**Proposition 3.1.** For \(a_2 > 0\) and \(t > \tau_2\) we have

\[
h_{12}^+(t) = \frac{4\pi^2 \tau_1 \tau_2}{\Lambda_1 \Lambda_2} e^{-i\Lambda_1 q_1 - i\Lambda_2 q_2} G_{12}^+(\cdot, q_1, \tau_1, q_2, \tau_2) + \frac{1}{\Lambda_1^3} R^+_{12}(\cdot, t, \Lambda_1, \Lambda_2)
\]

(3.7)

where \(R^+_{12}(R, t, \Lambda_1, \Lambda_2)\) is a bounded function of \(\Lambda_1, \Lambda_2\), whose estimate will be given during the proof.

**Proof.** Let us introduce the change of coordinates \(x = \xi - q_1\), \(y = \eta - q_2\), \(z = s - \tau_2\) in (3.3) and the shorthand notation \(G(x, y, w, z) = e^{-i\Lambda_1 q_1 - i\Lambda_2 q_2} G_{12}^+(R, x + q_1, y + \tau_1, w + q_2, z + \tau_2)\). Then

\[
h_{12}^+(t) = \int_{-\tau_2}^{t-\tau_2} dz \int_{-\tau_1}^{\tau_1} dy \int_{-\tau_2}^{t-\tau_2} dx \int_{-\tau_2}^{t-\tau_2} dw G(x, y, w, z) e^{i\Lambda_1 xy + i\Lambda_2 wz} \]

(3.8)

\[
= G(0, 0, 0, 0) \lim_{a, b \to \infty} \int_{-\tau_2}^{t-\tau_2} dx \int_{-\tau_1}^{\tau_1} dy \int_{-\tau_2}^{t-\tau_2} dx \int_{-\tau_2}^{t-\tau_2} dw (G(x, y, 0, 0) - G(0, 0, 0, 0)) e^{i\Lambda_1 xy + i\Lambda_2 wz}
\]

\[
+ \lim_{a, b \to \infty} \int_{-\tau_2}^{t-\tau_2} dx \int_{-\tau_1}^{\tau_1} dy \int_{-\tau_2}^{t-\tau_2} dx \int_{-\tau_2}^{t-\tau_2} dw (G(x, y, w, z) - G(x, y, 0, 0)) e^{i\Lambda_1 xy + i\Lambda_2 wz}
\]

\[
\equiv (I) + (II) + (III)
\]

(3.9)

The term \((I)\) is the leading term and it can be easily computed

\[
(I) = \frac{4\pi^2 \tau_1 \tau_2}{\Lambda_1 \Lambda_2} G(0, 0, 0, 0) \lim_{a, b \to \infty} \int_{-\tau_2}^{t-\tau_2} dz \int_{-\tau_1}^{\tau_1} dy \sin \frac{\Delta z}{\tau_2} \sin \frac{\Delta y}{\gamma}
\]

\[
= \frac{4\pi^2 \tau_1 \tau_2}{\Lambda_1 \Lambda_2} G(0, 0, 0, 0)
\]

\[
= \frac{4\pi^2 \tau_1 \tau_2}{\Lambda_1 \Lambda_2} e^{-i\Lambda_1 q_1 - i\Lambda_2 q_2} G_{12}^+(R, q_1, \tau_1, q_2, \tau_2)
\]

(3.10)

Concerning the term \((II)\) we have

\[
(II) = \frac{2\pi \tau_2}{\Lambda_2} \lim_{a, b \to \infty} \int_{-\tau_2}^{t-\tau_2} dz \int_{-\tau_1}^{\tau_1} dy \int_{-\tau_2}^{t-\tau_2} dx (G(x, y, 0, 0) - G(0, 0, 0, 0)) e^{i\Lambda_1 xy}
\]

\[
= \frac{2\pi \tau_2}{\Lambda_2} \int dx \int_{-\tau_1}^{\tau_1} dy (G(x, y, 0, 0) - G(0, 0, 0, 0)) e^{i\Lambda_1 xy}
\]

(3.11)
The r.h.s. of (3.11) can be estimated using (2.18), (2.21) and the result is

$$\|(II)\| \leq \frac{C_2}{\Lambda_2 A_1^2} \left( \|d_x^2 G(\cdot, 0, 0, 0)\|_{L^1} + \|d_x d_y G(\cdot, 0, 0, 0)\|_{L^1} + \int dx \|d_x^2 d_y^2 G(x, \cdot, 0, 0)\|_{L^2} \right)$$

$$= \frac{C_2}{\Lambda_2 A_1^2} \left[ \int d\xi |d_\xi^2 G_{12}^+(R, \xi, \tau_1, q_2, \tau_2)| + \int d\xi |d_\xi d_\eta G_{12}^+(R, \xi, \tau_1, q_2, \tau_2)|$$

$$+ \int d\xi \left( \int_0^t ds |d_\xi d_\eta d_s G_{12}^+(R, \xi, s', q_2, \tau_2)|^2 \right)^{1/2} \right] (3.12)$$

where $C_2$ is a constant depending on $\tau_1$, $\tau_2$. The term (III) can be more conveniently written as

$$(III) = \int dw \int_0^t dw \int_{-\tau_2}^{T - \tau_2} dz L(w, z)e^{i\tau_2 w z} (3.13)$$

$L(w, z) \equiv \int dx \int_{-\tau_1}^{T + \tau_2 - \tau_1} dy (G(x, y, w, z) - G(x, y, 0, 0)) e^{i\tau_1 x y} (3.14)$

where $L(0, 0) = 0$. Using (2.19), (2.22) we have

$$(III) = (IV) + (V) (3.15)$$

where

$$(IV) = \frac{2\pi i\tau_2^2}{\Lambda_2^2} d_w d_z L(0, 0) (3.16)$$

$$\|(V)\| \leq \frac{C_3}{\Lambda_2^2} \left( \|d_w^3 L(\cdot, 0)\|_{L^1} + \|d_w^3 d_z L(\cdot, 0)\|_{L^1} + \|d_w^2 d_z^2 L(\cdot, 0)\|_{L^1} + \int dw \|d_w^3 d_z^2 L(w, \cdot)\|_{L^2} \right) (3.17)$$

and $C_3$ depends on $t$, $\tau_1$, $\tau_2$. Taking into account (3.14) we also obtain

$$\|(V)\| \leq \frac{C_3}{\Lambda_2^2} \left( \|d_w^3 G(\cdot, \cdot, \cdot, 0)\|_{L^1} + \|d_w^3 d_z G(\cdot, \cdot, \cdot, 0)\|_{L^1} + \|d_w^2 d_z^2 G(\cdot, \cdot, \cdot, 0)\|_{L^1}$$

$$+ \int dw \int dx \int_{-\tau_2}^{t - \tau_2} dy \|d_w^3 d_z^2 G(x, y, w, \cdot)\|_{L^2} \right)$$

$$= \frac{C_3}{\Lambda_2^2} \left[ \int_0^{\tau_2} ds' \int d\xi \int d\eta |d_\eta^3 G_{12}^+(R, \xi, \eta, \tau_2)| + \int_0^{\tau_2} ds' \int d\xi \int d\eta |d_\eta^3 d_s G_{12}^+(R, \xi, \eta, \tau_2)|$$

$$+ \int_0^{\tau_2} ds' \int d\xi \int d\eta |d_\eta^2 d_s^2 G_{12}^+(R, \xi, s', \eta, \tau_2)| + \int_0^{\tau_2} ds' \int d\xi \int d\eta \left( \int_0^{\tau_2} ds |d_\eta^3 d_s G_{12}^+(R, \xi, s', \eta, s)|^2 \right)^{1/2} \right] (3.18)$$
Concerning $dw dz L(0,0)$, a straightforward computation gives

\[ dw dz L(0,0) = \int dx dw G(x, \tau_2 - \tau_1, 0, 0) e^{i \frac{\Lambda_1}{\tau_1} (\tau_2 - \tau_1)x} + \int dx \int_{-\tau_1}^{\tau_2 - \tau_1} dy dw dz G(x, y, 0, 0) e^{i \frac{\Lambda_1}{\tau_1} xy} \]

\[ \equiv (IV_1) + (IV_2) \]  

(3.19)

In (3.19) we integrate by parts in the first integral and use (2.17), (2.20) in the second integral. Then

\[ |(IV_1)| \leq \frac{1}{\Lambda_1} \frac{\tau_1}{\tau_2 - \tau_1} \|dx dw G(\cdot, \tau_2 - \tau_1, 0, 0)\|_{L^1} \]

(3.20)

\[ |(IV_2)| \leq \frac{C_1}{\Lambda_1} \left( \|dw dz G(0, 0, 0, 0)\|_{L^1} + \|dx dw dz G(x, \cdot, 0, 0)\|_{L^2} \right) \]

\[ = \frac{C_1}{\Lambda_1} \left[ \int d\xi |d\eta d\eta G^{ij}_{12} (\xi, \tau_1, q_2, \tau_2)| + \int d\xi \left( \int_0^{\tau_2} ds |d\eta d\eta d\eta d\eta G_{12} (\xi, s, q_2, \tau_2)|^2 \right)^{1/2} \right] \]  

(3.21)

and $C_1$ depends on $\tau_1, \tau_2$. Taking into account (3.12), (3.18), (3.20), (3.21) we get (3.7), with an explicit estimate of $R_{+1}^a (R, t, \Lambda_1, \Lambda_2)$, and this concludes the proof.

Let us consider the cases i), ii), iii) where the stationary point of the phase lies out of the integration region. In such cases, exploiting repeated integration by parts, one can show that (3.3) is $O(\Lambda_1^k)$, for any integer $k$, for $\Lambda_1 \to \infty$. Since the error term in (3.7) is $O(\Lambda_1^{-3})$, in the next proposition we shall limit to $k = 3$.

**Proposition 3.2.** For $a_2 > 0$, $t > \tau_2$ we have

\[ h_{+1}^a (t) = \frac{1}{\Lambda_1^3} R_{+ij}^a (\cdot, t, \Lambda_1, \Lambda_2) \]  

(3.22)

for $a = \pm, j = 2, l = 1$ and $a = -, j = 1, l = 2$, where

\[ |R_{+ij}^a (R, t, \Lambda_1, \Lambda_2)| \leq C \int_0^t ds \int_0^s ds' \int d\xi \int d\eta \left( |d\eta d\eta G_{ij}^a (R, \xi, s', q_2, \eta, \tau_2)| + d\frac{d}{\tau_1} G_{ij}^a (R, \xi, s', q_2, \eta) | \right) \]  

(3.23)

and $C$ depends on $\tau_1, \tau_2$.

**Proof.** Let us define $\tau_0 = \frac{\tau_1 + \tau_2}{2}$ and write...
\[ h_{21}^+ (t) = \int_0^{\tau_0} ds \int_0^s ds' \int d\xi \int d\eta \, G_{21}^+(\cdot, \xi, s', \eta, s) e^{i\Lambda_2 \theta_2^+ (\xi, s')} e^{i\Lambda_1 \theta_1^+(\eta, s)} \]
\[ + \int_{\tau_0}^{t} ds \int_0^s ds' \int d\xi \int d\eta \, G_{21}^+(\cdot, \xi, s', \eta, s) e^{i\Lambda_2 \theta_2^+ (\xi, s')} e^{i\Lambda_1 \theta_1^+(\eta, s)} \]
\[ \equiv (A) + (B) \] (3.24)

In (A) we integrate by parts three times with respect to the variable \( \xi \) and we obtain

\[ |(A)| = \left| \frac{\tau_0^3}{i^3 \Lambda_2^3} \int_0^{\tau_0} ds \int_0^s ds' \int d\xi \int d\eta \left( \frac{1}{(s - \tau_1)^3} \right) \, G_{21}^+(\cdot, \xi, s', \eta, s) e^{i\Lambda_2 \theta_2^+ (\xi, s')} e^{i\Lambda_1 \theta_1^+(\eta, s)} \right| \]
\[ \leq \frac{1}{\Lambda_2^3} \left( \frac{\tau_0^3}{(s - \tau_1)^3} \right) \int_0^{\tau_0} ds \int_0^s ds' \int d\xi \int d\eta \left| G_{21}^+(\cdot, \xi, s', \eta, s) \right| \] (3.25)

Integrating by parts with respect to \( \eta \) in (B) we have

\[ |(B)| = \left| \frac{(-\tau_1)^3}{i^3 \Lambda_1^3} \int_0^{\tau_0} ds \int_0^s ds' \int d\xi \int d\eta \left( \frac{1}{(s - \tau_1)^3} \right) \, G_{21}^+(\cdot, \xi, s', \eta, s) e^{i\Lambda_2 \theta_2^+ (\xi, s')} e^{i\Lambda_1 \theta_1^+(\eta, s)} \right| \]
\[ \leq \frac{1}{\Lambda_1^3} \left( \frac{\tau_0^3}{(s - \tau_1)^3} \right) \int_0^{\tau_0} ds \int_0^s ds' \int d\xi \int d\eta \left| G_{21}^+(\cdot, \xi, s', \eta, s) \right| \] (3.26)

From (3.25) and (3.26) we get the estimate for \( h_{21}^+ (t) \).

For the estimate of \( h_{21}^- (t) \) it is sufficient to notice that

\[ e^{i\Lambda_2 \theta_2^+ (\xi, s')} = \frac{1}{\left[ -i\Lambda_1 \left( \frac{s}{\tau_1} + 1 \right) \right]^3} e^{i\Lambda_2 \theta_2^+ (\xi, s')} d_3^3 e^{i\Lambda_1 \theta_1^- (\eta, s)} \] (3.27)

and to integrate by parts three times. The estimate of \( h_{12}^- (t) \) is analogous and then the proof is complete.

\[ \square \]

Taking into account (3.2), (3.7), (3.22), we obtain for \( n_1, n_2 \neq 0, a_2 > 0 \) and \( t > \tau_2 \)
\[ f_{n_1n_2}(t) = \frac{A^{(2)}}{\Lambda_1\Lambda_2} e^{-\frac{\pi t K_0}{2}} \psi_{12}^+ + \frac{1}{\Lambda_1^2} \mathcal{R}^{(2)}(\cdot, t, \Lambda_1, \Lambda_2) \] (3.28)

\[ A^{(2)} = -4\pi^2 \frac{\lambda^2}{\hbar^2} e^{-i(n_1+n_2+1)\omega t - i\Lambda_1 q_1 - i\Lambda_2 q_2} e^{i\frac{\hbar}{2m\tau_2^2}(\tau_1 q_1^2 + \tau_2 q_2^2 + 2\tau_1\tau_2 q_1 q_2)} g_1(q_1)g_2(q_2) \] (3.29)

\[ \psi_{12}^+ = \hat{\psi}_2^+(\cdot, q_1, \tau_1, q_2, \tau_2) \]

\[ \mathcal{R}^{(2)}(\cdot, t, \Lambda_1, \Lambda_2) = i\frac{\lambda}{\hbar} \Gamma_{n_1n_2}(t) \sum_{a=\pm} \mathcal{R}_{jl}^a(\cdot, t, \Lambda_1, \Lambda_2) \] (3.31)

Notice that the leading term in (3.28) can also be written as

\[ \frac{A^{(2)}}{\Lambda_1\Lambda_2} e^{-\frac{\pi t K_0}{2}} \psi_{12}^+ = -4\pi^2 \frac{\lambda^2}{\hbar^2} e^{i\eta_{12}(t)} \prod_{j=1,2} \tilde{V}(q_j)(\phi_{n_j}\phi_0)(q_j) e^{-\frac{\pi t K_0}{2}} \psi_{12}^+ \] (3.32)

\[ \eta_{12}(t) = \frac{n_1^2}{2} \frac{\delta E}{\delta \tau_1} + \frac{n_2^2}{2} \frac{\delta E}{\delta \tau_2} + n_1n_2 \frac{\delta E}{\delta \tau_2} - (n_1 + n_2 + 1)\omega t + \frac{n_1}{\delta \tau_1} + \frac{n_2}{\delta \tau_2} \] (3.33)

\[ \psi_{12}(R) = \frac{N}{\sqrt{\delta}} e^{\frac{(R-R_0)^2}{2\delta \tau^2}} e^{iP_1\tau}, \quad R_{12} = (n_1a_1 + n_2a_2)\delta E, \quad P_{12} = P_0[1 - (n_1 + n_2)\delta E] \] (3.34)

### 3.2. The case \( a_2 < 0 \).

Here the two oscillators are on the opposite sides with respect to the origin and one can easily check that the point \((\xi_0, s_0, \eta_0, s_0)\) where the phase in (3.3) is stationary is: \((q_1, \tau_1, q_2, -\tau_2)\) for \(h_{12}^+(t), (q_2, -\tau_2, \tau_1, q_1)\) for \(h_{12}^-(t), (q_2, -\tau_2, q_1, -\tau_1)\) for \(h_{21}^+(t), (-q_2, -\tau_2, q_1, -\tau_1)\) for \(h_{21}^-(t)\).

Since none of these points belongs to the domain of integration we can show that \(h_{jl}^\pm(t)\) is always rapidly decreasing to zero for \(\Lambda_1, \Lambda_2 \to \infty\).

### Proposition 3.3.

For \( a_2 < 0, t > \tau_2 \) and any integer \( k > 2 \) we have

\[ h_{jl}^\pm(t) = \frac{1}{\Lambda_1^2} Q_{jl}^\pm(\cdot, t, \Lambda_1, \Lambda_2), \quad j, l = 1, 2 \] (3.35)

where

\[ |Q_{jl}^\pm(R, t, \Lambda_1, \Lambda_2)| \leq \int_0^t ds \int_0^s ds' \int d\xi \int d\eta \left( |d_{q_0}^k G_{jl}^\pm(R, \xi, s', \eta, s)| + |d_{\xi}^k G_{jl}^\pm(R, \xi, s', \eta, s)| \right) \] (3.36)
Proof. The proof is an immediate consequence of $k$ integration by parts and a trivial estimate.

From the above proposition we conclude that for $n_1, n_2 \neq 0$, $a_2 < 0$, $t > \tau_2$ and any integer $k > 2$ we have

$$f_{n_1n_2}^{(2)}(t) = \frac{1}{\Lambda_1^k} Q_{n_1n_2}^{(2)}(\cdot, t, \Lambda_1, \Lambda_2)$$

$$Q_{n_1n_2}^{(2)}(\cdot, t, \Lambda_1, \Lambda_2) = \frac{1}{\tilde{h}} \Gamma_{n_1n_2}^a(t) \sum_{a=\pm, j,l=1,2, j \neq l} Q_{jl}^a(\cdot, t, \Lambda_1, \Lambda_2)$$

4. Joint excitation probability

We are now in position to compute the joint excitation probability of the two oscillators in the two cases $a_2 < 0$ and $a_2 > 0$. As a preliminary step, we need a pointwise estimate of the derivatives of $G_{jl}^\pm$ with respect to the variables $\xi, \eta$.

It is convenient to introduce the following notation

$$a = \frac{\hbar t}{M \gamma^2}, \quad b = \frac{\hbar t}{M \gamma^\sigma}, \quad c = \frac{\sigma}{\gamma}$$

$$s = t\alpha, \quad s' = t\beta,$$

$$x = \sigma^{-1} R, \quad z = x + b(\beta \xi + \alpha \eta)$$

We notice that, for $t$ of the same order of magnitude of $\tau_2$, the constants in (4.1) are of order one; moreover the rescaled variables $\alpha, \beta$ satisfy $0 \leq \alpha, \beta \leq 1$.

Lemma 4.1. We have

$$|d_{\eta}^k G_{jl}^\pm(R, \xi, t\beta, \eta, t\alpha)| + |d_{\xi}^k G_{jl}^\pm(R, \xi, t\beta, \eta, t\alpha)|$$

$$\leq c \mathfrak{A}_k(t) \frac{\mathcal{N}}{\sqrt{\sigma}} \langle \tilde{z} \rangle^k e^{-\frac{x^2}{2}} \langle \xi \rangle^k \sum_{m=0}^k |d_{\eta}^m g_j(\xi)| \langle \eta \rangle^k \sum_{m=0}^k |d_{\eta}^m g_l(\eta)|$$

where

$$\mathfrak{A}_k(t) = (1 + a^2 + b^4)^{k/2} (1 + b^2 + c^2)^{k/2} (1 + a)^k$$
Proof. Exploiting the above notation we can write
\[ G^\pm_{jl} = \psi^\pm g_j g_l e^\phi \] (4.6)
where \( \psi^\pm = \psi^\pm(R) \), \( g_j = g_j(\xi) \), \( g_l = g_l(\eta) \) and
\[ \phi = ia\left(\frac{\beta^2}{2} \xi^2 + \frac{\alpha}{2} \eta^2 + \alpha \xi \eta\right) - b^2\left(\frac{\beta^2}{2} \xi^2 + \frac{\alpha^2}{2} \eta^2 + \alpha \beta \xi \eta\right) - bx(\beta \xi + \alpha \eta) + icx(\xi + \eta) \] (4.7)
Let us compute the derivative of order \( k \) with respect to \( \eta \).
\[ d^k_\eta G^\pm_{jl} = \psi^\pm g_j \sum_{m=0}^k \binom{m}{k} d^m_\eta g_l d^m_\eta e^\phi \]
\[ = \psi^\pm e^\phi g_j \sum_{m=0}^k \binom{m}{k} d^m_\eta g_l \sum_{n+p=m} \frac{m!}{n! p!} (d^2_\eta \phi)^n (d^2_\eta \phi)^p \] (4.8)
A straightforward computation yields
\[ |d_\eta \phi|^n \leq \left[ \sqrt{b^2 + c^2} |z| + (a + bc)(|\xi| + |\eta|) \right]^n \]
\[ = \sum_{q=0}^n \binom{n}{q} (b^2 + c^2)^{\frac{n-q}{2}} |z|^{n-q} (2a)^q (|\xi| + |\eta|)^q \]
\[ \leq c(1 + b^2 + c^2)^{k/2}(1 + a)^k |z|^k (|\xi|)^k (|\eta|)^k \] (4.9)
\[ |d^2_\eta \phi|^p \leq (1 + a^2 + b^4)^{k/2} \] (4.10)
\[ |\psi^\pm e^\phi| = \frac{N}{\sqrt{\sigma}} e^{-\frac{z^2}{\sigma}} \] (4.11)
Using (4.9), (4.11), (4.11) in (4.8) we obtain the estimate
\[ |d^k_\eta G^\pm_{jl}| \leq c 2^k k! \frac{N}{\sqrt{\sigma}} (z)^k e^{-\frac{z^2}{\sigma}} (|\xi|)^k |g_j(\xi)| (|\eta|)^k \sum_{m=0}^k |d^m_\eta g_l(\eta)| \] (4.12)
Following exactly the same line we also find the corresponding estimate of \( |d^k_\xi G^\pm_{jl}| \) and this concludes the proof of the lemma.

□

Finally we can prove our main result.
Proof of theorem 1. We start with a detailed estimate of $\mathcal{P}_{n_1 n_2}(t)$. Taking into account (3.37), (3.38), (3.36) we have

$$\mathcal{P}_{n_1 n_2}(t) \leq \frac{1}{\Lambda_1^2} \int dR \left| Q^{(2)}(R, t, \Lambda_1, \Lambda_2) \right|^2$$

$$\leq \frac{4\lambda^4}{h^4 \Lambda_1^{2k}} \sum_{a=\pm} \sum_{j, l=1, 2, j \neq l} \int dR \left| Q_{j,l}^a(R, t, \Lambda_1, \Lambda_2) \right|^2$$

$$\leq \frac{16\lambda^4}{h^4 \Lambda_1^{2k}} \sup_{a, j, l} \left\{ \int_0^t \int_0^s \int d\xi \int d\eta \left[ \int dR \left( |d_{\eta}^k G_j^a| + |d_{\xi}^k G_j^a| \right) \right]^2 \right\}^{1/2}$$

(4.13)

where in the last line we have interchanged the order of integration and used the Schwartz inequality. Exploiting the estimate (4.14) we find

$$\mathcal{P}_{n_1 n_2}(t) \leq \frac{c}{\Lambda_1^{2k} - 4} \frac{\lambda^4}{h^4 \Lambda_1^4} \mathcal{A}_k^2(t) N^2 \|g_1\|_{W_{k,1}}^2 \|g_2\|_{W_{k,1}}^2 \left[ \int_0^t \int_0^{s'} \left( \frac{1}{\sigma} \int dR \langle z \rangle^{2k} e^{-z^2} \right)^{1/2} \right]^2$$

$$\leq \frac{c}{\Lambda_1^{2k} - 4} \frac{\lambda^4}{h^4 \Lambda_1^4} \mathcal{A}_k^2(t) N^2 \|g_1\|_{W_{k,1}}^2 \|g_2\|_{W_{k,1}}^2$$

It remains to evaluate the two norms in (4.14). Recalling the definition of $g_j(\xi)$ (see (2.6)) we have

$$\|g_j\|_{W_{k,1}} \leq \frac{k}{m=0} \sum_{m=0}^k \frac{m!}{p!} \int d\xi |\langle \xi \rangle|^k \left| d_{\xi}^{m-p} \tilde{V}(\xi) d_{\xi}^p (\tilde{\phi}_{n_j} \tilde{\phi}_0)(\xi) \right|$$

$$\leq \frac{k}{m=0} \sum_{m=0}^k \frac{m!}{p!} \left( \frac{1}{\sqrt{2\pi}} \int dx |x|^{m-p} |V(x)| \right) \left[ \int d\xi |\langle \xi \rangle|^k \left| d_{\xi}^{p} (\tilde{\phi}_{n_j} \tilde{\phi}_0)(\xi) \right| \right]$$

$$\leq c \|V\|_{L_k^1} \|\tilde{\phi}_{n_j} \tilde{\phi}_0\|_{W_{k,1}}$$

(4.15)

Inserting (4.15) in (4.14) we finally get the estimate (1.17) with

$$C_{n_1 n_2}^{(k)}(t) \equiv \frac{c}{\sqrt{m \delta V}} \left( \frac{t}{\tau_2} \right)^4 \left( \frac{a_2}{a_1} \right)^4 \mathcal{A}_k^2(t) N^2 \|V\|_{L_k^1} \|\tilde{\phi}_{n_1} \tilde{\phi}_0\|_{W_{k,1}}^2 \|\tilde{\phi}_{n_2} \tilde{\phi}_0\|_{W_{k,1}}^2$$

(4.16)

Let us consider $\mathcal{P}_{n_1 n_2}^+(t)$. From (3.28), (3.31), (3.32), (3.34) we have
\[ P_{n_1 n_2}(t) = 16 \pi^4 \sqrt{\pi} \left( \frac{\lambda_0}{\sqrt{\delta m \delta E}} \right)^4 N^2 |g_1(q_1)g_2(q_2)|^2 + S_{n_1 n_2}(t) \] (4.17)

where \( S_{n_1 n_2}(t) \) is a correction term of order \( \Lambda_1^{-1} \). In fact

\[
|S_{n_1 n_2}(t)| \leq \frac{c}{\Lambda_1^4} \left( \frac{\lambda_0^2}{\delta m \delta E} \right) N^2 |g_1(q_1)g_2(q_2)| \left( \int dR |R^{(2)}(R, t, \Lambda_1, \Lambda_2)|^2 \right)^{1/2} + \frac{1}{\Lambda_1^4} \int dR |R^{(2)}(R, t, \Lambda_1, \Lambda_2)|^2
\]

\[
\leq \frac{c}{\Lambda_1^4} \left( \frac{\lambda_0^2}{\delta m \delta E} \right) \frac{\lambda^2}{\hbar^2 \Lambda_1^2} N^2 |g_1(q_1)g_2(q_2)| \left( \sup_{a,j,l} \int dR |R_{s}^{a}(R, t, \Lambda_1, \Lambda_2)|^2 \right)^{1/2} + \frac{c}{\Lambda_1^4} \frac{\lambda^4}{\hbar^4 \Lambda_1^4} \sup_{a,j,l} \int dR |R_{s}^{a}(R, t, \Lambda_1, \Lambda_2)|^2
\]

\[
= \frac{1}{\Lambda_1^4} \left( \frac{\lambda_0}{\varepsilon} \right)^4 D_{n_1 n_2}(t) \] (4.18)

where

\[
D_{n_1 n_2}(t) \equiv c \left( \frac{\varepsilon}{\sqrt{\delta m \delta E}} \right)^4 \left( \frac{t}{\tau_2} \right)^2 \left( \frac{a_2}{a_1} \right)^2 \left[ N^2 |g_1(q_1)g_2(q_2)| \left( \frac{1}{t^4} \sup_{a,j,l} \int dR |R_{s}^{a}(R, t, \Lambda_1, \Lambda_2)|^2 \right)^{1/2} \right.
\]

\[
+ \frac{1}{\Lambda_1} \left( \frac{t}{\tau_2} \right)^2 \left( \frac{a_2}{a_1} \right)^2 \frac{1}{t^4} \sup_{a,j,l} \int dR |R_{s}^{a}(R, t, \Lambda_1, \Lambda_2)|^2 \left] \right.
\]

(4.19)

The proof of (1.18), (1.20) is complete if we notice that the quantity

\[
\frac{1}{t^4} \sup_{a,j,l} \int dR |R_{s}^{a}(R, t, \Lambda_1, \Lambda_2)|^2
\]

can be estimated following the line of the previous case. The explicit computation is straightforward but rather long and tedious and we omit the details.

\[ \square \]

5. Appendix

Here we give a proof of lemma 2.3 (see e.g. [BH] for analogous computations).

**Proof of lemma 2.3.** Let us decompose \( \mathcal{J}(\Lambda) \) in the following form
\[ \mathcal{J}(\Lambda) = \int dx \int_{-\nu}^\mu dy f(x,0) e^{i\Lambda xy} + \int dx \int_{-\nu}^\mu dy (f(x,y) - f(x,0)) e^{i\Lambda xy} \]

\[ = -\frac{i}{\Lambda} \int dx f(x,0) \frac{e^{i\Lambda\mu x} - e^{-i\Lambda\nu x}}{x} + \frac{i}{\Lambda} \int dx \int_{-\nu}^\mu dy \frac{dx f(x,y) - dx f(x,0)}{y} e^{i\Lambda xy} \]

\[ \equiv \frac{1}{\Lambda} (\mathcal{K}_{11}(\Lambda) + \mathcal{K}_{12}(\Lambda)) \tag{5.1} \]

where an explicit integration in the first integral and an integration by parts in the second integral has been performed. Thus we have (2.17) with \( \mathcal{K}_1(\Lambda) = \sum_{j=1}^2 \mathcal{K}_{1j}(\Lambda) \). The estimate of \( \mathcal{K}_1(\Lambda) \) is easily obtained if we write

\[ dx f(x,y) - dx f(x,0) = y \int_0^1 d\theta dx dy f(x,\theta y) \tag{5.2} \]

and then use the Schwartz inequality.

In order to prove (2.18) we reconsider \( \mathcal{K}_{11}(\Lambda) \) and \( \mathcal{K}_{12}(\Lambda) \). In particular we have

\[ \mathcal{K}_{11}(\Lambda) = -if(0,0) \int dx \frac{e^{i\Lambda\mu x} - e^{-i\Lambda\nu x}}{x} - i \int dx (f(x,0) - f(0,0)) \frac{e^{i\Lambda\mu x} - e^{-i\Lambda\nu x}}{x} \]

\[ = 2\pi f(0,0) - \frac{1}{\Lambda} \int dx f(x,0) - f(0,0) - dx f(x,0) x \left( \frac{e^{i\Lambda\mu x}}{\mu} + \frac{e^{-i\Lambda\nu x}}{\nu} \right) \]

\[ \equiv 2\pi f(0,0) + \frac{1}{\Lambda} \mathcal{K}_{21}(\Lambda) \tag{5.3} \]

where we have explicitly computed the first integral and we have integrated by parts in the second integral. Concerning \( \mathcal{K}_{12}(\Lambda) \), we observe that it is of the same form as \( \mathcal{J}(\Lambda) \) and then we can repeat the procedure. Denoting \( \eta(x,y) \equiv \frac{dx f(x,y) - dx f(x,0)}{y} e^{i\Lambda xy} \), with \( \eta(x,0) = dx dy f(x,0) \), we obtain

\[ \mathcal{K}_{12}(\Lambda) = \frac{1}{\Lambda} \int dx \int dy \frac{e^{i\Lambda\mu x} - e^{-i\Lambda\nu x}}{x} - \frac{1}{\Lambda} \int dx \int_{-\nu}^\mu dy \frac{dx \eta(x,y) - dx \eta(x,0)}{y} e^{i\Lambda xy} \]

\[ = \frac{1}{\Lambda} \int dx \int dy f(x,y) \frac{e^{i\Lambda\mu x} - e^{-i\Lambda\nu x}}{x} - \frac{1}{\Lambda} \int dx \int_{-\nu}^\mu dy \frac{dx^2 f(x,y) - dx^2 f(x,0) - dx^2 f(x,0) y}{y^2} e^{i\Lambda xy} \]

\[ \equiv \frac{1}{\Lambda} (\mathcal{K}_{22}(\Lambda) + \mathcal{K}_{23}(\Lambda)) \tag{5.4} \]

and the asymptotic formula (2.18) follows, with \( \mathcal{K}_2(\Lambda) = \sum_{j=1}^3 \mathcal{K}_{2j}(\Lambda) \).

The estimate of \( \mathcal{K}_{21}(\Lambda) \) is obtained if we write

\[ f(x,0) - f(0,0) - dx f(x,0) x = -x^2 \int_0^1 d\theta \theta dx^2 f(x\theta,0), \tag{5.5} \]
the estimate of $\mathcal{K}_{22}(\Lambda)$ is trivial and for $\mathcal{K}_{23}(\Lambda)$ it is sufficient to notice that
\begin{equation}
\frac{d^2_x f(x,y) - d^2_x f(x,0) - d^2_y d_y f(x,0)y}{y^2} = y^2 \int_0^1 d\theta \theta \int_0^1 d\zeta d^2_x d^2_y f(x, y\theta\zeta) (5.6)
\end{equation}
and to use the Schwartz inequality. Then the estimate (2.21) for $\mathcal{K}_{2}(\Lambda)$ is proved.

Finally we shall prove (2.19). An integration by parts in $\mathcal{K}_{21}(\Lambda)$ yields
\begin{align*}
\mathcal{K}_{21}(\Lambda) &= \frac{2i}{\Lambda} \int dx \left( f(x,0) - f(0,0) - d_x f(x,0) x + d^2_x f(x,0) \right) \frac{e^{i\Lambda x}}{\mu^2} - \frac{e^{-i\Lambda x}}{\nu^2} \\
&\equiv \frac{1}{\Lambda} \mathcal{K}_{31}(\Lambda) (5.7)
\end{align*}
For $\mathcal{K}_{22}(\Lambda)$ we proceed as in (5.3) and we obtain
\begin{align*}
\mathcal{K}_{22}(\Lambda) &= d_x d_y f(0,0) \int dx \frac{e^{i\Lambda x} - e^{-i\Lambda x}}{x} + \int dx \left( d_x d_y f(x,0) - d_x d_y f(0,0) \right) \frac{e^{i\Lambda x} - e^{-i\Lambda x}}{x} \\
&= 2\pi i d_x d_y f(0,0) - \frac{i}{\Lambda} \int dx d_x d_y f(x,0) - d_x d_y f(0,0) - d^2_x d_y f(x,0) x \frac{e^{i\Lambda x} + e^{-i\Lambda x}}{\mu^2} + \frac{e^{-i\Lambda x}}{\nu^2} \\
&\equiv 2\pi i d_x d_y f(0,0) + \frac{1}{\Lambda} \mathcal{K}_{32}(\Lambda) (5.8)
\end{align*}
The last term $\mathcal{K}_{23}(\Lambda)$ has the same form as $\mathcal{J}(\Lambda)$ and then following the same argument we get
\begin{align*}
\mathcal{K}_{23}(\Lambda) &= \frac{i}{2\Lambda} \int dx d_x^2 d_y f(x,0) \frac{e^{i\Lambda x} - e^{-i\Lambda x}}{x} \\
&- \frac{i}{\Lambda} \int dx \int dy \left( f(x,y) - d^2_x f(x,0) - d^2_y d_y f(x,0)y - d^3_x d_y d_y f(x,0) \frac{y^2}{2} \right) e^{i\Lambda x} \\
&\equiv \frac{1}{\Lambda} (\mathcal{K}_{33}(\Lambda) + \mathcal{K}_{34}(\Lambda)) (5.9)
\end{align*}
and (2.19) is proved with $\mathcal{K}_{3}(\Lambda) = \sum_{j=1}^{4} \mathcal{K}_{3j}(\Lambda)$.

The estimate (2.22) for $\mathcal{K}_{3}(\Lambda)$ is easily obtained following the same line as before and we omit the details.

□

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