A PHYSICAL APPROACH TO THE IDENTIFICATION OF HIGH-Z MERGERS:
MORPHOLOGICAL CLASSIFICATION IN THE STELLAR MASS DOMAIN

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Received 2014 December 21; accepted 2015 March 18; published 2015 June 2

ABSTRACT

At $z \gtrsim 1$, the distinction between merging and “normal” star-forming galaxies based on single band morphology is often hampered by the presence of large clumps which result in a disturbed, merger-like appearance even in rotationally supported disks. In this paper we discuss how a classification based on canonical, non-parametric structural indices measured on resolved stellar mass maps, rather than on single-band images, reduces the misclassification of clumpy but not merging galaxies. We calibrate the mass-based selection of mergers using the MIRAGE hydrodynamical numerical simulations of isolated and merging galaxies which span a stellar mass range of $10^{9.8}-10^{10.6} \ M_{\odot}$ and merger ratios between 1:1–1:6.3. These simulations are processed to reproduce the typical depth and spatial resolution of observed Hubble Ultra Deep Field (HUDF) data. We test our approach on a sample of real $z \approx 2$ galaxies with kinematic classification into disks or mergers and on $\sim$100 galaxies in the HUDF field with photometric/spectroscopic redshift between $1.5 \leq z \leq 3$ and $M > 10^{10.4} \ M_{\odot}$. We find that a combination of the asymmetry $A_{\text{MASS}}$ and $M_{\text{SD}, \text{MASS}}$ indices measured on the stellar mass maps can efficiently identify major mergers with $\lesssim 20\%$ contamination from clumpy disks in the merger sample. This mass-based classification cannot be reproduced in star-forming galaxies by $H$-band measurements alone, which instead result in a contamination from clumpy galaxies which can be as high as 50%. Moreover, we find that the mass-based classification always results in a lower contamination from clumpy galaxies than an $H$-band classification, regardless of the depth of the imaging used (e.g., CANDELS versus HUDF).

Key words: galaxies: high-redshift – galaxies: interactions – galaxies: irregular – galaxies: structure

Supporting material: figure set, machine-readable table

1. INTRODUCTION

Two decades of Hubble Space Telescope (HST) optical/near-infrared (NIR) observations—and more recently also ionized or molecular gas data—have unveiled a complexity of morphologies in high-redshift star-forming galaxies. Many $z \gtrsim 1$ galaxies do not display the disk or spheroidal morphology which is observed in the majority of local galaxies but are instead characterized by giant, star-forming clumps which dominate the light profiles and result in largely asymmetric appearances (Cowie et al. 1995; Papovich et al. 2005; Elmegreen et al. 2007; law et al. 2007; Swinbank et al. 2010; Förster Schreiber et al. 2011; Guo et al. 2012; Tacconi et al. 2013). Although such irregular structure has often been associated with mergers events, e.g., Conselice et al. 2008; Lotz et al. 2008a), the use of NIR, integral-field (IFU) spectroscopy has enabled substantial progress in the classification of high-redshift galaxies (e.g., Erb et al. 2004; Shapiro et al. 2008; Epinat et al. 2009, 2012) and detailed kinematic analysis have revealed ordered rotational motion in a large number of these visually disturbed galaxies (Genzel et al. 2006; Bournaud et al. 2008; van Starkenburg et al. 2008; Förster Schreiber et al. 2009). The formation of giant clumps in “normal” disk galaxies is thought to be the outcome of violent disk instability and fragmentation (Noguchi 1999; Bournaud et al. 2007; Agertz et al. 2009; Dekel et al. 2009; Ceverino et al. 2010), developing as a consequence of the high gas fractions that are typical for distant galaxies (Daddi et al. 2010; Tacconi et al. 2010; Magdis et al. 2012; Saintonge et al. 2013; Sargent et al. 2014).

In the lack of resolved kinematic data, the distinction between merging galaxies and clumpy disks remains however an observational challenge. In this paper we show how a quantitative classification performed on resolved stellar mass maps, rather than optical or NIR single-band images, can help disentangling the population of truly merging galaxies from that of clumpy disks even without available IFU images. Our approach is motivated by a number of reasons.

Even with the currently available second-generation instruments, obtaining reliable IFU kinematic measurements still requires major telescope time investments (see e.g., the KMOS-3D campaign, Wisnioski et al. 2015). Therefore, techniques which can provide robust proxies for the full kinematic informations are necessary.

Canonical merger classification methods, however, suffer from limitations which can hamper the distinction between mergers and “normal-but-clumpy” galaxies. The selection of close pairs in the spatial and velocity domain (Barton et al. 2000; Carlberg et al. 2000; Ellis et al. 2008; de Ravel et al. 2009; Kampczyk et al. 2013; Pipino et al. 2014, among the others) for example, identifies by definition physically associated systems but it can be biased against very close galaxies (“fiber collision”) and thus late interaction stages, namely the merger phases in which the distinction between
mergers and clumpy disks becomes more hazy. Close kinematic pairs would typically have a large enough separation to allow the individual morphological classification of each galaxy.

Another common way of identifying mergers relies on the degree of irregularity in the light distribution either through non-parametric measures such as the concentration, asymmetry, clumpiness (CAS) and Gini-M$_{20}$ indices (Abraham et al. 2003; Conselice 2003; Lotz et al. 2004; Law et al. 2007; Scarlata et al. 2007; Conselice et al. 2008) or through other indicators of the presence of multiple components/ tidal interactions (Kampczyk et al. 2007; Bridge et al. 2010; Kartaltepe et al. 2012; Lackner et al. 2014). Using hydrodynamical numerical simulations, Lotz et al. (2008b) have shown that combinations of non-parametric structural estimators (G-A-M$_{20}$) are sensitive to the coalescence phase and thus can be used also for evolved mergers. As mentioned above, however, at \( z > 1 \) the light profiles are dominated by giant star-forming clumps even in regular disk galaxies and CAS-like classification schemes applied to single-band optical/NIR images typically fail in distinguishing mergers from non-interacting galaxies (e.g., Huertas-Company et al. 2014).

While the giant \( 10^7 \ M_\odot \) clumps contribute 20\%–50\% of the flux in resolved optical/UV or star formation rate (SFR) maps of \( 10^9 \ M_\odot \) star-forming galaxies, they show a lower contrast with respect to the underlying disks on stellar mass maps, contributing \( \lesssim 10\% \) of the total mass budget (Förster Schreiber et al. 2011; Guo et al. 2012; Wuys et al. 2012). This suggests a potentially lower contamination of falsely identified mergers if measuring the aforementioned non-parametric structural indicators directly on the stellar mass maps instead of the single band images: for clumpy galaxies we expect the stellar mass maps to display a regular, centrally concentrated profile, whereas for merging galaxies multiple components will be present with no clear central mass concentration.

The exploitation of resolved mass (and also SFR or age) maps has become a common method of investigating the physical properties of low and high-redshift galaxies (see e.g., Welikala et al. 2008; Zibetti et al. 2009; Wisniewski et al. 2010; Guo et al. 2012; Wuys et al. 2012; Lang et al. 2014; Tacchella et al. 2015) but have not been used so far for a quantitative merger classification. The goal of this paper is to assess the performance of such a classification. We mainly focus on the testing and calibrating the proposed mass-based selection of mergers and defer a more in depth discussion on the properties of mass-identified mergers to a forthcoming paper (A. Cibinel et al. 2015, in preparation).

We use a set of mergers and isolated galaxies from the MIRAGE simulations (Perret et al. 2014) to quantitatively determine the efficiency and timescales probed when selecting mergers with mass-based structural parameters. Although other studies have investigated the morphology of interacting galaxies in numerical simulations (e.g., Lotz et al. 2008b), the use of the MIRAGE sample enables us to make steps forward with respect to these previous analysis. The MIRAGE simulations suite includes in fact key physical processes that are paramount for the formation and regulation of the giant star-forming clumps and thus naturally reproduces the complexity of clump-dominated morphologies of high redshift galaxies. We then apply our classification scheme on a fiducial sample of \( 1.5 \leq \ z \leq 3 \) galaxies in the Hubble Ultra Deep Field (HUDF, Beckwith et al. 2006) and compare the results of our new method with the \( H \)-band classification and also with previously published kinematic analyses.

Specifically, the paper is organized as follows. We present in Section 2 the observational data utilized in our analysis, the sample basic properties and the generation of the resolved mass maps for the HUDF galaxies. Section 3 presents the MIRAGE simulations and post-processing of the simulation output. We discuss our definition of a merging galaxy and some caveats regarding the simulations in Section 4. We provide a summary of the structural measurements performed on both real and simulated galaxies in Section 5. In Section 6 we calibrate the classification performed on the mass maps using the MIRAGE simulations and ancillary data with kinematic information. We then compare in Section 7 the mass-based classification and the standard \( H \)-band classification for the real HUDF galaxies. Finally, Section 8 summarizes our findings and conclusions. Considerations about signal-to-noise ratio (S/N) effects and possible systematic biases are presented in Section 2.5 and Appendix A.

All magnitudes are in the AB system and corrected for galactic absorption using the dust maps of Schlegel et al. (1998) when necessary. Throughout the paper we use interchangeably the notation “\( H \)-band” to refer to the \( HST/ \) WFC3 F160W filter. If needed, we also use the abbreviations \( b \), \( z \) and \( Y \) when referring to the \( HST/ACS \) F435W, \( HST/Advanced Camera for Surveys (ACS) F850LP \) and \( HST/WFC3 F105W \) filters, respectively. Quoted masses assume a Chabrier initial mass function (IMF). We finally note that we will sometimes use the notation “clumpy disks” to refer those galaxies that have a clumpy appearance in the \( H \)-band/optical images but are not classified as mergers with our method. We stress however that this is not meant to be a quantification of the intrinsic strength of the bulge component in these galaxies.

2. OBSERVATIONAL DATA

We apply the new classification scheme on a sample of galaxies in the HUDF field which, thanks to the availability of extremely deep observations but also medium and shallow coverage over the same area, enables us to generate high accuracy mass maps as well as to assess the impact of S/N on the classification. We briefly summarize here the sample selection criteria and the relevant information for the public data sets utilized in this study, referring the reader to the original works for further details.

2.1. Archival \( HST \) Observations

To build the pixel-by-pixel mass maps and perform the analysis described in Section 7, we exploited the data from several public campaigns covering the HUDF area with a multi-tiered approach.

For galaxies in the original HUDF ACS field (\( 3' \times 3' \)) we generated two versions of the mass maps using either (1) the deep \( HST/ACS F435W, F606W, F775W \) and F850LP images from HUDF (Beckwith et al. 2006) combined with the \( HST/ \) WFC3 F105W, F125W and F160W images from the CANDELS-Deep survey (Grogin et al. 2011; Koekemoer et al. 2011), or (2) the F435W, F606W, F775W and F850LP observations from the GOODS survey (Giavalisco et al. 2004) plus the CANDELS-Deep NIR photometry.

For the sub-set of galaxies in the central \( 2' \times 2' \) region of HUDF (corresponding to the WFC3 field of view), we also
generated a third mass map making use of the extremely deep observations available at all wavelengths: the optical HUDF images and the HST/WFC3 F105W, F125W, F140W and F160W coverage from the HUDF09 and HUDF12 surveys (Bouwens et al. 2011; Ellis et al. 2013). We specifically employed the mosaics provided by the HUDF12 team which are combined with the HUDF09 datasets. In all cases, CANDELS observations are also used for the F814W filter.

### 2.2. Parent Catalog, Photo-z and Stellar Masses

The identification of the galaxy sample and the calculation of photometric redshifts (photo-z) are based on the H-band selected, multi-wavelength catalog published by the CANDELS team in the GOODS-S field (Guo et al. 2013, and references therein). The photometric data available in this compilation consists of imaging in 17 medium and broad-band filters ranging from the U-band to the IRAC 8 μm channel.

We derived photo-z and integrated galaxy stellar masses for all galaxies in the Guo et al. (2013) sample as described in full details in Pannella et al. (2014). Briefly, photo-z were estimated from the Guo et al. (2013) photometric catalog using the public code EAZY (Brammer et al. 2008) and a combination of the standard set of templates from Whitaker et al. (2011). These photo-z reach an accuracy of \( \Delta z = |z_{\text{phot}} - z_{\text{spec}}| / (1 + z_{\text{spec}}) = 0.03 \). Published photometric redshifts (spec-z) are available for about 30% of our final HUDF sample.\(^{\ast}\) For galaxies with a secure photometric measurement we considered the spec-z as the final redshift, whereas the photo-z was preferred in those cases in which only a tentative (or no spec-z) is given. We then obtained galaxies stellar masses through fitting of the spectral energy distribution (SED) with FAST (Kriek et al. 2009), keeping the redshift fixed and using a set of Bruzual & Charlot (2003) stellar population models with delayed exponentially declining star formation histories. Dust absorption with a maximum of \( A_V = 4 \) was allowed in the fitting (Calzetti et al. 2000).

\(^{\ast}\) In particular, we referred to the ESO compilation of GOODS/CDF-S spectroscopy, [http://www.eso.org/sci/activities/garching/projects/goods/Master_Spectroscopy.html](http://www.eso.org/sci/activities/garching/projects/goods/Master_Spectroscopy.html) which collects spec-z from several spectroscopic surveys which have covered (also) the HUDF field.

### 2.3. Sample Selection

The initial galaxy sample was extracted from the Guo et al. (2013) catalog by selecting galaxies over the HUDF area having a spectroscopic or photometric redshift between \( 1.5 \leq z \leq 3 \) and an H-band magnitude brighter than \( H \leq 26 \) mag. The redshift selection allows us to probe the rest-frame FUV to optical for all galaxies; the luminosity cut is instead applied to ensure that a minimum signal-to-noise is reached in most pass-bands and thus a reliable photo-z estimate can be obtained. The exact value of \( H \leq 26 \) mag was chosen empirically by requiring that 80% of all GOODS-S galaxies, within the same redshift bin as the one here considered, have a S/N>3 in at least 10 of the pass-bands which are used in the photo-z calculation. This magnitude threshold also ensures that the sample lies comfortably above the 50% completeness limit of the parent Guo et al. (2013) photometric catalog (\( H = 26.6 \)).

The H-band magnitude limit translates into a redshift dependent mass completeness threshold. For a clear selection of the sample, we hence apply a further cut in stellar mass to include only galaxies above the completeness value. Given that we are mostly interested in studying the properties of clump-dominated, star-forming galaxies, we consider in the following the mass completeness limit for star-forming galaxies. To derive this threshold we followed the procedure described in e.g., Pozzetti et al. (2010). For each galaxy we estimated the mass \( M_{\text{lim}} \) that it would have, keeping its mass-to-light ratio (\( M/L \)) constant, if faded to the limiting magnitude \( H = 26 \). We then calculated, at each redshift, the mass below which lie 90% of \( M_{\text{lim}} \) in the 30% faintest galaxies—considered to be representative of the typical \( M/L \) of a galaxy close to the magnitude limit. The final completeness limit is set by the highest redshift here considered (\( z = 3 \)), corresponding to a value of \( M > 10^{9.4} M_\odot \) for star-forming galaxies. The equivalent number for quiescent galaxies would be \( M > 10^{10.2} M_\odot \).

After also rejecting galaxies which fall too close to the HUDF edges for reliable measurements, our initial sample includes 132 galaxies with \( 1.5 \leq z \leq 3 \), \( H \leq 26 \), and \( M > 10^{9.4} M_\odot \). We derived structural parameters for all these galaxies and we provide them in Table 1, but the sample is further restricted for our final analysis as a result of the

### Table 1

| ID   | R.A. [J2000] | Decl. [J2000] | \( z \) | \( M_{20, \text{MASS}} \) | \( e_{\pm} M_{20, \text{MASS}} \) | \( A_{\text{MASS}} \) | \( e_{\pm} A_{\text{MASS}} \) | Class | Phot |
|------|--------------|---------------|-------|----------------|-----------------|----------------|----------------|-------|-----|
| 8740 | 53.16764     | -27.83037     | 1.88  | -1.67          | 0.06            | 0.114          | 0.010          | Not merging | H + C |
| 8750 | 53.16287     | -27.82947     | 2.04  | 1.22           | 0.12            | 0.125          | 0.040          | Unres./Faint | H + C |
| 9295 | 53.17170     | -27.82566     | 1.73  | -1.85          | 0.07            | 0.096          | 0.010          | Not merging | H + C |
| 9343 | 53.16714     | -27.82450     | 1.84  | -1.21          | 0.09            | 0.160          | 0.014          | Not merging | H + C |
| 8740 | 53.16764     | -27.82379     | 2.69* | -0.61          | 0.07            | 0.314          | 0.166          | Merger (2)   | H + C |
| 9474 | 53.16978     | -27.82394     | 2.24  | -1.26          | 0.05            | 0.112          | 0.021          | Not merging | H + C |
| 9527 | 53.15673     | -27.82306     | 1.72  | -1.95          | 0.08            | 0.036          | 0.013          | Not merging | H + C |
| 9835 | 53.17343     | -27.82028     | 2.28  | -1.32          | 0.10            | 0.036          | 0.078          | Unres./Faint | H + C |
| 9987 | 53.14894     | -27.81928     | 2.23  | -1.18          | 0.08            | 0.183          | 0.049          | Not merging | H + C |

Note. For all galaxies in the extended sample of Section 2.3 we provide: (1) the CANDELS serial number from the Guo et al. (2013) catalog; (2)–(3) R.A. and Decl. in J2000; (4) photometric or spectroscopic redshift (galaxies flagged with “s” have a spectroscopic redshift); (5)–(6) Asymmetry index \( A_{\text{MASS}} \) measured from the mass map and associated error; (7)–(8) \( M_{20, \text{MASS}} \) index measured from the mass map and associated error; (9) classification according to the structural measurements performed on the mass maps: galaxies flagged as “Merger (1)" are merger candidates selected with the criterion in Equation (1), whereas galaxies flagged as “Merger (2)" also satisfy the depth-dependent selection in Equation (2); (10) photometric data used for the generation of the mass maps: "H + C" = HUDF + CANDELS, "H + H12"=HUDF + HUDF12. Galaxies flagged as Unres./Faint are below our limits of \( r_{\text{lim}} > 5 \times \text{PSF} \) and \( H \leq 24.5 \) for a reliable mass estimate. Table 1 is published in its entirety in the electronic edition of the *Astrophysical Journal*. A portion is shown here for guidance regarding its form and content.

(This table is available in its entirety in machine-readable form.)
reliability assessment of the stellar mass maps that we present in Section 2.5 and which is based on tests performed on this initial, larger sample.

While deferring to a forthcoming paper the detailed analysis of the star formation properties of mass-selected mergers, we show in Figure 1 the position of this initial sample of 132 galaxies on the mass versus SFR plane for illustration purposes. Even above the mass completeness limit for quenched galaxies, the majority of the galaxies here considered lie on the locus of the so-called main sequence of star formation (e.g., Brinchmann et al. 2004; Daddi et al. 2007; Elbaz et al. 2007). The few galaxies with very low SFR (SFR < 1 M ☉ yr⁻¹) have been identified as quiescent based on their bH or zYF colors and the upper limits on their IR fluxes. For these galaxies no dust extinction is applied when computing the UV-based SFR and are hence imposed to lie below the main sequence. The sample considered here is mostly composed of normal (main sequence), star-forming galaxies.

![Figure 1](image_url)

**Figure 1.** Location of the galaxy sample on the mass vs. SFR plane. The dashed line shows the locus of the z = 2 main sequence of star-forming galaxies (based on literature compilation in Sargent et al. 2014) and the small gray points are all galaxies in the Guo et al. (2013) GOODS-S photometric catalog with a photometric redshift 1.5 ≤ z ≤ 3. The large green symbols correspond to the initial sample of 132 galaxies studied in the present work, prior to applying the size and magnitude selection of Section 2.5. The final sample of 87 galaxies on which reliable mass maps could be derived after applying this selection is shown with the red symbols. Triangles indicate IR-based SFR (either from a combination of NUV+monochromatic 24 μm flux density or from a fit to the mid-to-far IR SED). Circles are instead galaxies without reliable IR photometry and for which the SFR is thus estimated from the dust-corrected UV luminosity. Galaxies with very low SFR are identified as quiescent based on their bH or zYF colors and the upper limits on their IR fluxes. For these galaxies no dust extinction is applied when computing the UV-based SFR and are hence imposed to lie below the main sequence. The sample considered here is mostly composed of normal (main sequence), star-forming galaxies.

2.4. Pixel-by-pixel SED Fitting and Stellar Mass Maps

As a first step for the generation of the resolved mass maps, we registered all the ACS and WFC3 tiles to the same resolution and pixel scale of the H-band which has the worst point-spread function (PSF) among the other available filters (~0.15'). To do so, we created an individual PSF for each filter by stacking several unsaturated stars in the HUDF field and computed the convolution kernels to match the PSF of the H-band. From the matched images, we then extracted postage stamps for each galaxy in our sample with a size equal to 3 times the H-band Kron radius and, as further justified in Section 4.1, we cleaned from the stamps any nearby companion galaxy with a known spec- or photo-z.

To derive pixel-based stellar masses and the actual mass maps, we extracted pixel-by-pixel SEDs within an elliptical aperture equal to the galaxy H-band Kron semi-major axis and fitted them with stellar population models. Given the relatively low flux in each individual pixel, some degree of smoothing or binning is required to ensure a minimum S/N on most of the filters and thus obtain reliable parameters from the pixel SED fitting. Several approaches have been used in the literature to deal with S/N homogenization problems (Sanders & Fabian 2001; Cappellari & Copin 2003; Ebeling et al. 2006; Wuyts et al. 2012; Cibinel et al. 2013b). We opted here for the publicly available code ADAPTSMOOTH developed in Zibetti (2009) and Zibetti et al. (2009). Whenever the S/N falls below a given threshold, this algorithm performs an adaptive smoothing of the images by replacing the original pixel values with an average of the galaxy flux over larger and larger circular areas as the S/N decreases. ADAPTSMOOTH features two useful options: (a) the smoothing of several images on the same scale lengths—necessary to derive self-consistent SEDs—can be easily performed and (b) the pixel identity is maintained, as opposed to binning schemes in which neighboring pixels are assigned a common value, effectively grouping them together into a final “macro pixel.”

The choice of the reference band(s) defining the smoothing kernels applied by ADAPTSMOOTH is a trade-off between attaining the best S/N and maintaining spatial resolution: using the band with the lowest S/N will obviously degrade the resolution, while referring to the one with the highest S/N will likely result in noisy SEDs. Furthermore, also in light of forthcoming analyses on the comparison between the resolved mass and SFR distribution, we are interested in detecting features such as giant star-forming clumps which may be intrinsically bright in one band but have a smaller flux contrast at longer wavelengths. A too broad smoothing on the red band may completely erase these structures in the blue filters. After testing single or multiple bands smoothing, we found the optimal configuration by running ADAPTSMOOTH on stacked images of all ACS and WFC3 stamps: this ensures that the smoothing is applied on those pixels where the majority of the bands reach a low S/N while preserving the structural variations in the different filters. Specifically, we run ADAPTSMOOTH by requiring a minimum S/N = 5 on the stacked images and halting the adaptive smoothing when the averaging area reaches the maximum radius of 5 pixels. The smoothing pattern thus obtained was then applied to all available bands giving a median S/N ~ 5 also on the individual pixels for most filters. We note that we have tested that our results are not substantially affected by a different choice of the smoothing kernel (e.g., by applying the smoothing on the H-band only).
We fitted the adaptively smoothed pixel SEDs with LEPHARE (Arnouts et al. 1999; Ilbert et al. 2006) using the Bruzual & Charlot (2003) synthetic spectral library with a Chabrier (2003) IMF and a delayed exponential star formation history, \( \psi \propto (t/\tau)^{-2} \exp(-t/\tau) \). The characteristic timescale \( \tau \) was let vary between 0.01 and 10 Gyr in 22 steps and template ages were chosen between 100 Myr and the age of the universe at the given redshift. We allowed three metallicity values in the fitting (\( Z = 0.2 Z_\odot \), \( Z = 0.4 Z_\odot \) and \( Z = Z_\odot \)) and furthermore applied internal dust extinction by assuming a Calzetti law and \( E(B-V) \) ranging between 0 and 0.9 mag. We defined our fiducial pixel mass estimate as the median mass from the full probability distribution function from all templates, but our results would remain unchanged if we had used the mass from the best-fit template (i.e., minimum \( \chi^2 \)) instead. As a validation of the derived mass maps, we verified the consistency between the sum of the pixel-based masses and the integrated galaxy mass in Appendix A.1. We find an agreement at the level of \( \leq 0.1 \) dex between the two estimates.

An example of the derived mass maps is given in Figure 2, where we compare the \( bzH \) composite image, the \( H \)-band image and the mass map for a galaxy in our sample (ID 12451). We have intentionally chosen a galaxy which displays a different structure in the \( H \)-band than in the mass map to clearly illustrate how at \( z > 1 \) \( H \)-band light and mass are not equivalent tracers of morphology. This was already pointed out by Wuyts et al. (2012; see for example their Figure 2 which has two galaxies overlapping with our sample in Figure 11) and we will further demonstrate it in Section 7.

2.5. Systematic Uncertainties in the Reconstructed Mass Maps

Numerous studies have shown that the ability of recovering intrinsic galaxy properties from observed flux distributions depends strongly on the image S/N, resolution and even on the intrinsic properties of the galaxies themselves (Disney 1976; Schweizer 1979; Franx et al. 1989; Impey & Bothun 1997; Trujillo et al. 2001; Graham et al. 2005; Cameron & Driver 2007; Bailin & Harris 2008; Graham & Worley 2008; Maller et al. 2009; Carollo et al. 2013a; Cibinel et al. 2013a). Our mass-based measurements will also be affected by similar limitations. For structural measurements performed on optical images, tests on artificial galaxies have demonstrated that it is possible to derive correction schemes that can largely account for the systematic biases in the estimates of galaxy structure—e.g., galaxy radii and concentrations—for both local (see Cibinel et al. 2013a for an application to \( z \sim 0 \) galaxies from the ZENS sample in Carollo et al. 2013b) and high redshift galaxies (see Carollo et al. 2013a for an application to the COSMOS survey, Scoville et al. 2007).

We do not attempt here a derivation of similar corrections in the mass domain as this would require large suites of artificial mass maps and hence significant assumptions on the mass (and dust) distribution in merging and non-merging galaxies. We can nonetheless perform some tests which enable us to define the “boundaries of applicability” of our method, i.e., the regimes where we can obtain reliable measurements.

It is clear that for unresolved objects no meaningful mass reconstruction can be performed nor the individual galaxies participating in the merger can be identified. Likewise, the reconstruction of the mass distribution becomes more and more difficult as the flux in the pixels reaches the surface brightness limit of the observations. To derive a global magnitude and size limit below which we cannot reliably derive mass maps, we tested our SED-fitting and mass reconstruction technique on a set of artificial galaxies with known mass distribution drawn from our initial sample of \( 1.5 \leq z \leq 3 \). We describe these models in detail in Appendix A.2. For each of the toy galaxies, we compared the mass profile reconstructed following the procedure in Section 2.4 with the input model and calculated the median of the residuals as well as the typical dispersion around the input model.

The results of the comparison are presented in Figure 3 where we color code each region of the size versus magnitude plane according to the mean absolute residual value and the dispersion of all models falling in that specific area: a red/orange color indicates high residuals/scatter in the reconstructed maps, green corresponds to low residuals/scatter. The Figure illustrates how the ability of measuring reliable mass maps degrades as galaxies approach the resolution limit or reach low surface brightnesses: at sizes \( r_{Ks} \leq 5 \times \text{PSF} \) (roughly 15 pixels) and magnitudes \( H > 24.5 \) systematic shifts and/or large deviations from the input model affect the measured mass maps.\(^9\)

We thus used the thresholds \( H \leq 24.5 \) and \( r_{Ks} > 5 \times \text{PSF} \) to select galaxies with reliable mass maps, reducing the sample of \( 1.5 \leq z \leq 3 \) galaxies to 89 objects. Two of these galaxies, ID 13508 and ID 11800, are strongly contaminated by a bright neighbor and for this reason have less robust mass maps. These cases are flagged in Table 1 and excluded from the sample used for the analysis in Section 7. We show this final sample of 87 galaxies with red points in Figure 1. Note that the \( H \leq 24.5 \) selection is incidentally the same cut that has been applied for a reliable visual morphological classifications on the CANDELS fields (Kartaltepe et al. 2014).

3. THE MIRAGE SIMULATED GALAXIES

3.1. Description of the Simulations

The details on the technical aspects of the MIRAGE simulations are presented in Perret et al. (2014) and further discussions on the physics implemented in these simulations can also be found in Renaud et al. (2013) and Bournaud et al. (2014a). Briefly, three closed-box disk models with a

\(^9\) The inferred magnitude limit refers to mass maps generated from artificial images matched to the HUDF + CANDELS-Deep data, as described in Appendix A.2. For observations at a different depth this limit will scale accordingly.
bulge-to-total fraction of 8% in mass and stellar masses of $10^{10.7} M_\odot$ (simulation G3 in Perret et al. 2014), $10^{10.3} M_\odot$ (G2), and $10^{10.6} M_\odot$ (G1) were generated using an adaptive mesh refinement technique with the RAMSES code (Teyssier 2002). These simulations reach a resolution of 7.3 pc at the highest level of refinement and have initial stellar mass particles of $1.2 \times 10^4 M_\odot$ and $1.7 \times 10^4 M_\odot$ in the bulge and disk components, respectively. The disk galaxies were evolved in isolation or merged with each other, effectively probing merger ratios of 1:1, 1:2.5 and 1:6.3. In order to construct a representative sample of galaxy mergers, four different orbital parameters were explored for each merger ratio combination, resulting in a total of 20 mergers simulations (plus the 3 isolated disk models).

For each simulation configuration we utilize in the following a set of 16 snapshots separated by 40 Myr each, covering an epoch from 200 to 800 Myr from the simulations initial conditions; for the merger models, this corresponds to following the pre- and post-coalescence phases for roughly 300 Myr each (the coalescence time is visually determined in Perret et al. 2014).

The MIRAGE simulations feature several aspects which are paramount for a correct description of the ISM physics and thus for a robust comparison with the real data. First, the high level of grid refinement enables us to resolve Jeans-unstable regions within the disks, consequently we can not only model the disk fragmentation and the formation of large clumps but also properly describe outflows and heating within the giant clumps themselves.

Second, a physically motivated feedback model is implemented in the simulations by coupling standard supernovae feedback (Dubois & Teyssier 2008) with the novel recipe for photoionization and radiation pressure feedback from OB-stars developed in Renaud et al. (2013). This feedback model reproduces the typical outflows, SFR and the stellar population ages ($\lesssim$200 Myr) observed in real clumps (Bournaud et al. 2014a).

Third, the simulated disks have an initial total gas fraction of $f_g = 65\%$ which is well representative of the observed high molecular fractions in typical $z > 1$, star-forming galaxies (e.g., Daddi et al. 2010; Tacconi et al. 2010) and is essential for the onset of gravitational instability and the generation of the giant clumps.

Finally, the MIRAGE simulations were originally designed as a “numerical counterpart” for the MASSIV galaxy sample (Contini et al. 2012), and for this reason they are tailored to high-z galaxies in terms of global properties (e.g., their sizes and SFR, see Figures 6 and 9 of Perret et al. 2014).

### 3.2. Post-processing of the MIRAGE Output

To reproduce the data available for the HUDF galaxies also for the simulated MIRAGE sample, we extracted from each simulation snapshot a stellar mass density map and three stellar flux maps, in the HST/ACS F435W, F850LP, and HST/WFC3 F160W filters. We used both face-on and edge-on line of sights computed from the angular momentum of the most massive disk, at an initial resolution of 50 pc.

The mass maps were simply obtained by projecting the distribution of stellar mass particles in the simulations. We instead derived the mock observations by assigning a Starburst99 (Leitherer et al. 1999) instantaneous burst model with a Salpeter IMF and an effective metallicity $Z = 0.004$ to each star particle on the basis of its formation age. This metallicity corresponds to the integrated value that is expected for a disk galaxy with a central metallicity in agreement with observations of $z \sim 2$ galaxies by Erb et al. (2006). We note here that no dust extinction was applied to the simulated fluxes.

To produce flux and mass maps that can be directly compared with observations, we performed the following steps.

1. Generated observed-frame F435W, F850LP and F160W images by redshifting the Starburst99 SEDs and applying cosmological dimming. We assumed a reference redshift $z = 2$.

2. Matched the artificial F435W & F850LP images to the HST/ACS resolution ($\sim 0'08$) and the $H$-band and mass maps to the HST/WFC3 resolution ($\sim 0'15$). To do so, we convolved the artificial maps with the PSFs kernels constructed from stars in the HUDF field (see Section 2.4).

3. We also pixelized the simulation images to the ACS and WFC3 pixel scales ($0'03$ and $0'06$, respectively), again assuming an average $z = 2$.

4. Finally, we added noise to the flux and mass maps mimicking the typical imaging depth and the uncertainty in the reconstruction of the mass distribution for the real images. For the mock HST images, this was done by
typical of the BzK selection simulated disks and observed galaxies. The horizontal and slanted lines divide the mergers. The black points correspond to real CANDELS/GOODS-S galaxies with 1.5 evolution in mass and luminosity of the isolated disks in the MIRAGE simulation over the 600 Myrs here considered. Blue circles are the MIRAGE simulated galaxies have also the "cold-mode" parameter settings of the Guo et al. (2013) CANDELS multiwavelength catalog in the case of the mock $H$-band images. The SExtractor outputs were used for detecting/deblending the merging galaxies and to define their photometric properties, e.g., sizes or fluxes. The integrated luminosities and colors of the MIRAGE galaxies resulting from such post-processing are presented in Figure 4, where we compare the simulations with real 1.5 $\leq$ $z$ $\leq$ 3 galaxies in the CANDELS/GOODS-S field. There is a good agreement between the MIRAGE disks or mergers and the real sample of galaxies. At high masses, the MIRAGE models tend to be slightly brighter than observed galaxies, most likely as a consequence of applying no dust extinction to the simulations. Although limited by the intrinsic colors of the Starburst99 templates used to construct the flux maps, the simulated galaxies have also ($b$–$z$) and ($z$–$H$) colors that are typical of $z$ $\sim$ 2 star-forming galaxies.

We then ran SExtractor on the noisy, stellar mock images with similar configuration parameters as those employed for the construction of the GOODS ACS multi-band catalogs in the case of the artificial F435W and F850LP images, and instead using instead the "cold-mode" parameter settings of the Guo et al. (2013) CANDELS multiwavelength catalog in the case of the mock $H$-band images. The SExtractor outputs were used for detecting/deblending the merging galaxies and to define their photometric properties, e.g., sizes or fluxes.

The ability to separate two galaxies in real observations depends on several aspects, such as the intrinsic surface brightness and brightness contrast of the merging galaxies, the signal to noise of the images, the size of the galaxies, etc. Hence it is not straightforward to convert the SExtractor deblending threshold into a unique minimum distance between the two galaxies. On average, however, the closest separation at which the HUDF 1.5 $\leq$ $z$ $\leq$ 3 galaxies in the Guo et al. (2013) catalog are still deblended is $\sim$10 kpc; our merger sample will hence include galaxies at smaller separations.

4.1. Definition of Merger in Our study

As specified in the Introduction, our intent is to optimize the classification for galaxies that are close to the coalescence phase, with less interest to early merger stages which can be identified with other techniques (e.g., kinematic pair selection). For this reason, HUDF galaxies in pairs with a sufficient separation to allow distinct identification will be considered as individual objects.

Before proceeding with the analysis, we clarify here some definitions and address caveats which are relevant for the following discussion.

4. CAVEATS AND GENERAL COMMENTS

Comparison a real $z$ $\sim$ 2 galaxy extracted from the HUDF field. The simulated galaxies well reproduce the morphological/structural properties of real observed galaxies and their variation with wavelength of observation.

4.1. Definition of Merger in Our study

As specified in the Introduction, our intent is to optimize the classification for galaxies that are close to the coalescence phase, with less interest to early merger stages which can be identified with other techniques (e.g., kinematic pair selection). For this reason, HUDF galaxies in pairs with a sufficient separation to allow distinct identification will be considered as individual objects.

Practically, this means that we perform the structural measurements and classification separately for any galaxy appearing as a single entry in the parent Guo et al. (2013) catalog, even if the galaxy is in a close pair with another in the catalog. Moreover, this also implies that any galaxy displaying multiple clumps/components which do not appear as individual sources in the $H$-band catalog will be considered as a "multi-component" single system, being it either a clumpy galaxy or a merger (but see next section).

The ability to separate two galaxies in real observations depends on several aspects, such as the intrinsic surface brightness and brightness contrast of the merging galaxies, the signal to noise of the images, the size of the galaxies, etc. Hence it is not straightforward to convert the SExtractor deblending threshold into a unique minimum distance between the two galaxies. On average, however, the closest separation at which the HUDF 1.5 $\leq$ $z$ $\leq$ 3 galaxies in the Guo et al. (2013) catalog are still deblended is $\sim$10 kpc; our merger sample will hence include galaxies at smaller separations.

Following the same philosophy, we extracted from the simulations a sample of close-to-coalescence mergers which we...
refer to as "pre-coalescence" mergers/snapshots. In this sample are excluded both pre-merger (i.e., well separated) galaxies\(^{11}\) and post-merger remnants (i.e., snapshots extracted at a time after the coalescence of the two nuclei). In fact, galaxies in such phases have either to merge yet or have already completed the merger phase and have settle in their final, unperturbed state with no clear structural signatures of the past merger event. In the simulation, and possibly in the observations too, such galaxies are indistinguishable from the isolated galaxies.

Among these pre-coalescence mergers, some reach an almost unperturbed appearance already a \(\sim 20\) Myr before the coalescence time. Although these simulated galaxies are still nominally undergoing a merger, they also occupy a locus of structural parameters which is overlapping with that of "normal" galaxies. To obtain an as pure as possible merger training sample, we excluded these simulations from those employed to calibrate the classification in Section 6.2. We refer to this clean set of mergers as the "training-sample."

\(^{11}\) In order to follow for the simulation an approach as close as possible to that applied on the real galaxy sample, we relied on the SExtractor output to determine when the two simulated galaxies can be clearly deblended (see Section 3.2 for details of the SExtractor run on the simulations). Consistently with the observations, this translates into a maximum separation of about 10 kpc also for the simulated galaxies.

4.2. Keeping Projection Effects under Control

Obviously, for real data the presence of multiple components which are not deblended into individual sources does not necessarily imply that we are looking at a single clumpy galaxy.
or that the components are physically participating to a merger. Especially for those galaxies displaying extreme color gradients, one may worry about chance projections. As mentioned in Section 2.3 spectroscopic redshifts are available for only a minority of the sample, hence we cannot rely on the spectral information to confirm associations.

Another way to test this possibility is to compare the source identification/photo-z based on the H-band extraction with those obtained at shorter wavelengths to see whether the individual clumps could in principle be identified as single objects located at a different redshift and had simply passed undetected in the H-band. Of course, the advantage of an H-band extraction is precisely that—by probing the rest-frame optical for z \sim 2 galaxies—it limits the “over-deblending” of galaxies which may occur at the rest-frame UV. For this reason we keep the H-band source identification as our reference. However, we can use the short wavelength independent measurements to flag “bona-fide” multi component galaxies.

For this purpose we used the publicly available photo-z for the HUDF galaxies from the work of Coe et al. (2006) which are based on a hybrid i-band+BVIzJH detection. Specifically, for each galaxy in our sample which displayed several clumps or plausible companions we checked in the Coe et al. (2006) catalog whether these would have been identified as separate object and their photometric redshift. Whenever also the i-band extraction was consistent with only a single multi-clump galaxy or the phot-z of the individually extracted clumps/companion was consistent within errors with the redshift of the given galaxy, we considered it as a true multi-component system at best of our knowledge. Otherwise we flagged this galaxy to remind us that a chance projection cannot be excluded in this case. We highlight such galaxies with a red exclamation mark in Table 1.

4.3. Limitations of the Simulations

The MIRAGE simulations offer an ideal sample for testing our approach as we argued in Section 3. Nonetheless, there are also a number of limitations of which we must be aware when comparing with the real data.

First, in spite of being realistic models of typical high redshift galaxies, they are not statistically representative of the full galaxy population and especially of the relative frequency of normal and merging galaxies. The simulation snapshots are in fact almost equally divided between disks and mergers (with the latter dominated by major mergers) which is not necessarily reflective of reality. For this reason, we do not expect that the relative densities of simulated mergers and disks in the structural planes investigated in the following should reflect the true distribution of real galaxies. We will return to this point in Section 6.

Second, the predicted stellar fluxes for the MIRAGE simulations are not obtained with a self-consistent, full radiative transfer treatment and they do not include the effects of dust extinction and scattering which are instead known to be important in real galaxies. As discussed in detail in the work of (Lotz et al. 2008b), simulated mergers with no dust obscuration appear more concentrated, less asymmetric and have lower M20 values than simulations in which dust obscuration is included. The MIRAGE flux/H-band maps are hence likely smoother and may trace the stellar mass more closely than in real high-z galaxies. Conversely, the real mass maps may also appear noisier than the simulated maps as a consequence of the extra image processing and SED fitting which was required for the real data (see Section 2.4).

Third, the lifetimes of clumps in simulated galaxies (and hence the observed clumpiness of galaxies) are sensitive to the assumed feedback model (see e.g., Genel et al. 2012; Mandoelker et al. 2014; Moody et al. 2014). Support for the feedback recipe employed in the MIRAGE suite (Renaud et al. 2013) comes from the fact that the clumps in the simulated disks well reproduce typical stellar ages (~200 Myr) of observed clumps (Bournaud et al. 2014a). However, our still incomplete understanding of feedback processes could affect the comparison of the simulated galaxies with the real data.

Fourth, the sample of MIRAGE disks consists of purely isolated galaxies obtained from simulations that are lacking a full cosmological context. A number of processes acting on large scales could induce a higher clumpiness/ asymmetry in the galaxies, including tidal interactions with massive galaxies or nearby satellites and gas infall through intergalactic streams. Large-scale accretion would help maintaining the initial high gas fractions (60%) for longer times than in the isolated scenario, leading to more prominent instability-induced features (clumps, asymmetry, etc.). We note however that while fully cosmological simulations would overcome some of the aforementioned limitations, the lower resolution imposed by the large cosmological volumes would also most likely result in smoother galaxies than in reality.

Finally, a further complication arises from the fact that the gas fraction in the MIRAGE simulations accounts for both molecular and atomic hydrogen. The study of Bournaud et al. (2015) showed that a substantial ~20% of gas in the simulations is found in the atomic phase in moderate-density regions between the clumps and in extended reservoirs. This would lead to an underestimation of the molecular gas fraction, and consequently clumpiness, with respect to observations (e.g., Daddi et al. 2010; Tacconi et al. 2010). This is witnessed by the too weak CO excitation in these models (Daddi et al. 2014).

As a consequence of the above, it is reasonable to expect that the simulations display a somewhat smoother morphology in optical imaging than the real data. We will keep this caveat in mind.

5. STRUCTURAL MEASUREMENTS

5.1. Non-parametric Morphology

On the real as well as simulated single band images and the stellar mass maps, we calculated several non-parametric structural indicators using our own purpose built routines. We consider hereafter only two such indices.

1. The asymmetry A, which is the normalized residual flux as obtained from the difference between the original image and its 180°-rotated version (Conselice 2003; Zamojski et al. 2007). After experimenting with different methods for defining the center used in the asymmetry computation, we chose as our fiducial estimate of A the value calculated with respect to the peak of the emission/ mass distribution. We find this option to be most sensitive to multiple components in the galaxies and thus to merger features.12

12 Except for the multiplicity in Appendix A.3, all other parameters refer to the light/mass centroid.
abundance of mergers and normal galaxies which is not necessarily matched in the simulations, the MIRAGE and observed galaxies clearly span the same region of the structural parameter space. This confirms the reliability of the simulations in probing the morphology of $z \sim 2$ star-forming galaxies and enables us to use them for calibrating the classification in the next Section.

5.1.1. Uncertainties of the Structural Indices

For the real HUDF galaxies, we estimated the errors on the structural indices as follows. We resampled the mass maps and $H$-band images 101 times by replacing each pixel value with a new value randomly extracted within the mass and flux uncertainties, assuming a Gaussian distribution. We then recalculated the structural indices each time and used the median value and the 16th and 84th percentiles of all 101 realizations as our final estimates of the non-parametric indices and the associated errors. Using the median over the resampled maps rather than the directly measured indices has the advantage of down-weighting the impact of isolated extreme pixels with large uncertainties.

5.2. Visual Multiband and Mass Morphologies

As complementary information to the quantitative structural measurements, we also visually inspected all galaxies in the HUDF sample. We performed the visual classification independently on composite $bzH$ images and on the mass maps. Each galaxy was assigned to one of the following three broad classes of morphology.

1. “Compact galaxies.” These galaxies are either consistent with a spheroidal morphology with no signatures of perturbations or too compact for detecting any structural feature.
2. “Disks,” characterized by a regular, centrally symmetric light or mass profile for which an underlying disk-like morphology is discernible;
3. “Multi-component/disturbed” galaxies, which present several peaks/clumps and/or lopsided distribution of light or mass with no clear disk or spheroidal morphology.

6. CALIBRATION OF THE MASS-BASED CLASSIFICATION

We now turn to the main goal of our paper, i.e., to verify whether a mass-based classification can improve the identification of merging galaxies. We start by testing and calibrating the method on the simulated MIRAGE galaxies.

6.1. Comparison with Single-band Classification in the Simulations

For the MIRAGE mergers and the isolated disks, we show in the left panels of Figure 7 the relations between $M_{20}$ and $A$ as measured on either the three optical/NIR bands $F435W$, $F850LP$ and $F160W$ or on the mass maps (we will use the subscript “H-BAND” or “MASS” to differentiate $H$-band or mass-based indices from now on). The $F435W$ results are presented for a comprehensive comparison with the other bands and the mass maps, but a separation between mergers and disks on the artificial $F435W$ images is very difficult as in this case the two populations clearly overlap in almost the entire

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13 The choice of the Petrosian aperture is also motivated in Appendix A.3.
parameter space. Therefore, we do not consider the F435W band for the quantitative analysis described in the following.

On the F850LP, F160W and mass panels of Figure 7 we ran a support vector machine (SVM) algorithm and identified the best dividing line between simulated mergers and disks (dashed line in the figure). We remind that for this calculation we excluded from the training sample of mergers any pre-merger galaxy, merger remnants and mergers which have reached an unperturbed state (light points in Figure 7). Our method is hence optimized to select galaxies that are clearly displaying interaction features. For any given sample of snapshots falling above the dashed lines in Figure 7, we then estimated the “contamination” and the “completeness” of the selected merger sample—i.e., the fraction of misclassified isolated disks among all selected snapshots and the fraction of all pre-coalescence merger galaxies which are correctly classified. The results of these calculations are summarised in the right panels of Figure 7 where we plot contamination (uppermost panel, circles) and completeness (lower three panels, triangles). We use a red symbol when the classification is performed on the mass maps, orange when it is based on the F160W images and green for the F850LP filter.

There is a clear trend of decreasing contamination from clumpy disks going from the $z-$ to $H$-band and mass maps, supporting our approach. Although in the simulations the difference between $H$-band and mass is not statistically significant, this trend is reinforced by the results in Figure 16, showing that the contamination is minimized if the classification is performed on the mass maps also for other combinations of structural indicators. We emphasize here that as a consequence of all limitations listed in Section 4.3, the simulated $H$-band images likely trace the mass distribution more closely than in real galaxies in which, e.g., patchy dust obscuration or higher gas fractions, will increase the galaxy clumpiness and worsen the ability of separating mergers from disks. We hence expect that the differences between the mass-based and flux-based classification should be more pronounced in real data. This hypothesis is supported by the observational results discussed in Section 7.

We also note that the mass-based selection of mergers reaches a completeness level that is comparable to the $H$ band for simulated major mergers, whereas it is somewhat lower for the minor mergers. This is not surprising since, by definition, the mass-based classification identifies galaxies with large mass contrasts/asymmetries, and hence is less sensitive to minor mergers. In the simulations, some minor mergers can still be detected in the optical/NIR bands as a consequence of SFR enhancements. Again, in real observations the classification of these minor mergers will be further complicated by the effects discussed above.

### 6.2. Quantitative Definition of Mergers

We use the results of the SVM partition to define a quantitative criteria for selecting mergers based on the position in the $M_{20,\text{MASS}}$ and $A_{\text{MASS}}$ plane. We concluded in Section 4.3 that an exact one-to-one match between the relative numbers of
disks and mergers in the simulations and the real data is not expected. For this reason we have refrained from performing any fine-tuning of the coefficients in the relation between $M_{20, \text{MASS}}$ and $A_{\text{MASS}}$ such as to optimize the completeness versus contamination level. This would in fact depend on the input merger fraction in the simulations. We rather follow the conservative approach of identifying a locus in the mass-derived $M_{20, \text{MASS}}$ versus $A_{\text{MASS}}$ plane which—unless real galaxies have extreme mass distributions that are not reproduced by current models—should be populated by mergers only. This is of course still model dependent, but less affected by the specific choice of the merger fraction in the simulations.

Our simulation-justified dividing line between mergers and normal galaxies is hence given by the following relation:

$$M_{20, \text{MASS}} > -1.1 \times A_{\text{MASS}} - 1.12,$$

and it is obtained by simply applying a shift to the best SVM line in the $M_{20, \text{MASS}}$ versus $A_{\text{MASS}}$ plane of Figure 7 such to exclude the most extreme disks. This relation is shown with a solid line in Figure 7.

The completeness level over all pre-coalescence merger snapshots (including the unperturbed light-blue points in Figure 7) reached with the selection of Equation (1) is shown with a star symbol in the lower-right panel in Figure 7. As a consequence of our rather conservative choice of the dividing line in Equation (1), the mass-based classification results in a very high “purity” of the selected mergers at the expense of the completeness of the merger sample. On the MIRAGE simulated data, we estimate a completeness of up to $\sim 40\%$ for major mergers (ratios 1:1 to 1:2.5) and up to 10% completeness for the minor mergers when applying Equation (1).

When dealing with real data, it is useful to introduce, together with the binomial classification of Equation (1), also a more probabilistic description of the $M_{20, \text{MASS}}$ versus $A_{\text{MASS}}$ plane which could be used to assign a merger likelihood on individual galaxies. For this reason using the results from the simulations, we also derived a continuous parametrization of the contamination from clumpy disks over that plane. This was obtained by modeling the number densities of the mergers and disk snapshots with a Gaussian mixture approach and obtaining the number densities of the mergers and the contamination from clumpy disks over that plane. This was done with the binomial classification of Equation (1) in the disk-dominated locus and the kinematic merger/perturbed galaxy is on top of the merger locus, consistently with a transition region between disks and mergers, as shown in Figure 9.

6.3. Validation on Real Galaxies with Kinematic Classification

A kinematic classification into rotationally supported disk or merger is currently available for some $z > 1$ galaxies (e.g., Bournaud et al. 2008; Epinat et al. 2009; Förster Schreiber et al. 2009), which can thus be used to further validate the calibration of the classification in the $M_{20, \text{MASS}}$ versus $A_{\text{MASS}}$ plane obtained from the MIRAGE simulations. For this test we consider galaxies with a similar optical+NIR wavelength coverage as our HUDF sample.

In particular, a subset of the galaxies in the SINS survey (Förster Schreiber et al. 2009) are located in the GOODS-S field and thus stellar mass maps can be built using the GOODS+CANDELS data. Specifically, we refer to those SINS galaxies which have a kinemetry classification in Table 9 of Förster Schreiber et al. (2009) or as a disk displaying disturbed rotation in Tacchella et al. (2015). We label it as “perturbed/merger” to indicate that it is not a regular disk. For another galaxy that is included in our sample of galaxies with HUDF + HUDF12 coverage (CANDELS ID 15011 or UDF ID 6462) a kinematic analysis based on SINFONI data has been published in the study of Bournaud et al. (2008). As discussed in that work, in spite of its disturbed appearance this galaxy clearly displays a rotational motion in the $H_\alpha$ velocity field. We hence include this object in the sample of kinematically classified disks. We performed our mass map analysis on these galaxies and compare in Figure 8 their location with the expectations from the simulations.

Inspecting Figure 8, we find a very good agreement between our simulation-based partition of the $M_{20, \text{MASS}}$ versus $A_{\text{MASS}}$ plane and the location of the observed galaxies: all kinematically confirmed disks lie below the line defined in Equation (1) in the disk-dominated locus and the kinematic merger/perturbed galaxy is on top of the merger locus, on a region where the disk contamination is expected to be $< 20\%$ at the HUDF depth.

We note that the real kinematically confirmed disks display somewhat higher $A_{\text{MASS}}$ and $M_{20, \text{MASS}}$ values than the bulk of simulated MIRAGE disks. As mentioned in Section 4.3, a lower gas fraction in the simulations with respect to real galaxies or the lack of dust could be responsible for the difference. Furthermore, we discuss in Section 7.1 that a lower S/N causes a shift to higher $M_{20}$. Small modifications to Equation (1) should be applied when using data that is shallower than HUDF, as for the SINS galaxies. When accounting for this effect, we still find a good agreement between the kinematic and mass classification, with galaxies K20-ID6, K20-ID8, and ID 15011 falling in the disk-dominated region and the perturbed galaxy K20-ID7 on the transition region between disks and mergers, consistently with its ambiguous kinematic classification.

6.4. Probed Timescales and Merger Ratios

We can also use the simulations to convert the structural selection into a typical observability window during which mergers are identified as such by the mass-based classification. Figure 9 shows the evolution in time of the structural
parameters in the MIRAGE simulated disks and mergers. As a further illustration of the results of Section 6.1, we present the time variations for indices measured on the stellar mass maps as well as for those derived on the three optical/NIR bands. The different shades of blue illustrate the evolution of mergers with different mass ratios (increasing merger ratio for darker shades), whereas the magenta lines are for the isolated disks. For interacting galaxies we trace the parameters from an early merger phase at 50 Myr before pericenter—when the two galaxies are still separated and hence the structural indices are measured on the primary only—to after the complete fusion between the two galaxies. The peak observed in most of the indices coincides with the pre-coalescence phase that we are targeting with our selection; clearly it becomes more distinguishable from other phases when moving from the optical to the NIR and the mass maps.

The shaded gray areas in the right panels of the figure highlight the time interval over which 90% of the mergers identified by the selection in Equation (1) are found: following our classification criteria, we are able to identify mergers for about 200 Myr, i.e., between 300 and 500 Myr before coalescence. This timescale is consistent with those reported by, e.g., Lotz et al. (2008b, 2010) for optically selected mergers, even though these authors find a wide range of observability timescales (between ~0.1 and 1 Gyr) depending on the orientation, type of mergers, as well as on the structural indicators used to detect the merger features.

Finally, in the top panel of Figure 9 we show for comparison the evolution of the SFR in the simulated galaxies (see also Figure 7 of Perret et al. 2014). Interestingly, the variation in the structural parameters occurring during the merger event is not associated to a clear SFR enhancement in the simulations. Perret et al. (2014) list several plausible causes for the lack of the starburst phase, including the interplay between the high gas fractions and the feedback treatment in the simulations. A detailed study of the star formation histories in the MIRAGE simulations is beyond the scope of this paper (and is also affected by uncertainty in the models), the information is presented for completeness here but we will not further speculate on the links (or absence thereof) between the structural properties and star formation activity of the simulations.

7. MASS VERSUS LIGHT: CLASSIFICATION FOR REAL HUDF GALAXIES AT DIFFERENT DEPTHS

Building on the results from the previous section, we now apply the mass-based classification and compare the outcome with the results from the $H$-band images for the 87 galaxies with reliable mass maps in the HUDF area (i.e., the 89 galaxies with SExtractor Kron radii larger than 5× the PSF FWHM and magnitudes \( H \leq 24.5 \) minus the two galaxies with mass maps affected by strong contamination from neighboring galaxies, see Section 2.5).

For the galaxies in the HUDF area, the availability of multi-depth data allows us to verify the reliability of the mass-based classification at different S/N. Specifically, we consider mass maps derived from the three combinations of optical plus NIR imaging described in Section 2.4: (1) GOODS and CANDELS-Deep data, (2) HUDF plus CANDELS-Deep, and (3) the deepest maps obtained from the HUDF12+HUDF observations. Of the 87 galaxies here considered, 50 galaxies have coverage at all depths, while for the other 37 only the first two versions of the mass maps could be derived. For comparison with the mass maps results, we also consider structural parameters measured on the $H$-band images at the HUDF12 or CANDELS-Deep depths.

In Figure 10 we present the location of the HUDF galaxy sample in the \( M_{20} \) versus Asymmetry plane, either derived from the $H$-band images (left panels) or the stellar mass maps (right panels). From top to bottom we show measurements performed on images of increasingly shallower depths. The dotted lines in the figure indicate the dividing locus of Equation (1) and the
different symbols highlight the visual types of Section 5.2. In the following we will regard galaxies with a visual class for the mass maps that is inconsistent with the quantitative criterion on $A_{\text{MASS}}$ and $M_{20,\text{MASS}}$ as failures of the mass-based classification, i.e., as contaminants in the merger sample. In some cases such galaxies display genuine color gradients which could justify the mass asymmetries, but we will take the conservative approach of assuming they are the result of noise in the mass maps.\footnote{Note that we also implicitly assume here that there are no systematic biases in the derivation of the mass maps, which could generate artificial multi-component, merger-like features in high S/N maps.}

7.1. (Falsely) $H$-band Selected Mergers

We start the analysis on the real galaxies by identifying in Figure 10 those galaxies which would be classified as mergers based on the irregularity of their $H$-band images. For a consistent comparison with the selection based on the mass map, we consider as mergers candidates those galaxies that satisfy Equation (1) also for the $H$-band measurements, i.e., galaxies above the dotted lines in Figure 10. Other criteria are often used in the literature when using $M_{20}$ and asymmetries derived from optical images. At low redshift ($z < 1$) a cut at $A > 0.3$-0.35 is typically applied to select major mergers (Conselice 2003; Lotz et al. 2008b) but for $z > 1.5$ galaxies a value of $A \gtrsim 0.2$ is preferred to account for the effects of the morphological $k$-correction, the decrease in the image resolution and surface brightness dimming (Conselice 2003; Conselice et al. 2005). The distribution of irregular galaxies in Figure 10 of Scarlata et al. (2007) would also suggest a division at $M_{20,\text{H-band}} \gtrsim -1.7$ to identify mergers candidates. We have checked (and it can be verified by inspecting Figure 10) that the result here presented would not change if these other criteria are applied.

More than 90% of the galaxies that satisfy Equation (1) in the $H$-band were assigned to the class of “multi-component/disturbed” galaxies also by the visual $bHz$ morphological analysis. This means that these galaxies would be classified as mergers by both a multi-wavelength visual inspection and a quantitative structural analysis on the $H$-band. Conversely, it can be seen that several of the merger candidates lying above the dotted line in the $H$-band planes are visually classified as normal disk galaxies based on their mass map appearance.
These galaxies have accordingly low asymmetry and $M_{20}$ indices measured on the mass map (see right panels of Figure 10). At both the HUDF12 and CANDELS-Deep depth, about $\sim 50\%$ of those galaxies with $A_{H/BAND}$ and $M_{20, H/BAND}$ large enough to be classified as mergers in the $H$ band have a mass profile consistent with that of a normal disk galaxy and fall below Equation 1 when the mass-based indices are used. To illustrate
these differences between mass and H-band classification, we present in Figure 11 the stamp images for those galaxies with $\Delta_{H,\text{BAND}}$ and $M_{20, H\text{-BAND}}$ values, but are instead visually and quantitatively classified as normal, disk-like galaxies based on their mass distribution and the $A_{\text{MASS}}$ and $M_{20, \text{MASS}}$ indices—see filled orange triangles above the dotted line in the lower left panel of Figure 10. We mark the H-band stamps with “C” or “H12” depending on whether the galaxy satisfies the criteria for being a merger when using the CANDELS-Deep H-band photometry or the HUDF12 images (or both). A “-” sign highlights those galaxies for which only CANDELS observations are available. All images are 3″ wide. When available, the stamps and mass maps from the HUDF/HUDF12 imaging are presented; HUDF/CANDELS-Deep images are shown in the other cases.

Figure 11. Composite $b\z H$ image, H-band stamp and mass map (from left to right) for galaxies which have a sufficiently asymmetric appearance in the H-band to be classified as mergers on the basis of their $\Delta_{H,\text{BAND}}$ and $M_{20, H\text{-BAND}}$ values, but are instead visually and quantitatively classified as normal, disk-like galaxies based on their mass distribution and the $A_{\text{MASS}}$ and $M_{20, \text{MASS}}$ indices—see filled orange triangles above the dotted line in the lower left panel of Figure 10. We mark the H-band stamps with “C” or “H12” depending on whether the galaxy satisfies the criteria for being a merger when using the CANDELS-Deep H-band photometry or the HUDF12 images (or both). A “-” sign highlights those galaxies for which only CANDELS observations are available. All images are 3″ wide. When available, the stamps and mass maps from the HUDF/HUDF12 imaging are presented; HUDF/CANDELS-Deep images are shown in the other cases.

7.2. Mass-selected Mergers

Focusing on the right panels of Figure 10, we can instead study the results of the measurements performed on the mass maps. At the HUDF + HUDF12 depth—top most panel—we find an excellent agreement between the locus of mergers expected from the analysis on the simulations (see light shaded area and dotted line) and the visual classes for the real data. A comparison with the other right-hand panels, however, reveals some important facts: not surprisingly, the separation between galaxies visually classified as disks/compact and galaxies with visually disturbed morphologies becomes less clear as the S/N of the mass maps decreases. At the GOODS+CANDELS-Deep depth, the distribution of galaxies in the $A_{\text{MASS}}$ and $M_{20, \text{MASS}}$ plane is noticeably more clustered than for the structural parameters derived on the HUDF + HUDF12 mass maps.

It also appears rather clearly from Figure 10 that the bulk of real galaxies shifts toward higher $M_{20, \text{MASS}}$ values as a consequence of the decrease in S/N. This is particularly evident when comparing the data points with the shaded locus defined by the simulations. We showed in Appendix A.3 that, while the Asymmetry is almost insensitive to the image noise, some dependence of the $M_{20}$ on the S/N is expected and variations of the order of 10% are measured for $M_{20}$ indices derived at different depths. This suggests that the criterion in Equation (1), which was derived for simulations reproducing the HUDF +
HDF12 depth, should be revised as an “adaptive” threshold varying with the images S/N. Furthermore, we note that at the shallower depth a few merger candidates appear in a region of very low asymmetry ($A_{\text{M}A} < 0.1$) but very high $M_{20,\,\text{M}A}$ ($M_{20,\,\text{M}A} > -1$) where virtually no simulated mergers nor galaxy visually classified as merger are found. We suspect these galaxies to be affected by measurement errors.

We use the above empirical findings to provide refined criteria to robustly select mergers at the various depths:

$$M_{20,\,\text{M}A} > -1.1 \times A_{\text{M}A} + \begin{cases} -1.12 \, H + H12 \\ -1.00 \, H + C \\ -0.98 \, G + C \end{cases}$$

$$A_{\text{M}A} > 0.1,$$  

(2)

where “$H + H12$,” “$H + C$”, and “$G + C$” stand for the mass maps derived from the HUDF + HUDF12, HUDF + CANDELS-Deep, and GOODS+CANDELS-Deep photometry, respectively. These new relations where obtained by adding to the locus of Equation (1) the average offsets in $M_{20,\,\text{M}A}$ measured in Figure 16. The new selection limits are shown with dashed lines in Figure 10.

By selecting as merger candidates those galaxies that satisfy the generic Equations (1) we find a total of 9, 21, and 26 mergers for the HUDF + HUDF12, HUDF + CANDELS-Deep and GOODS+CANDELS-Deep combinations, respectively. Of these, 6 and 10 have a visual class that is inconsistent with the quantitative analysis on the mass maps, i.e., they have been assigned an either “compact” or “disk” class in the visual inspection of the mass maps. The use of the fixed selection of Equation (1) would hence result in an increase of the contamination from ~20% for the HUDF + HUDF12 maps to 40% for the GOODS+CANDELS-Deep combination. Conversely, using the relations in Equation (2) we find 9, 15, and 15 mergers candidates with a total of 2, 3, and 4 galaxies visually classified as non interacting, namely a roughly constant contamination of ~20%, regardless of the image depth.

What should be stressed here is that applying the “adaptive” criteria of Equation (2) also to the $H$-Band would not reduce the contamination of clumpy disks: as it is clear from the bottom left panel of Figure 10, these clumpy disks are distributed everywhere in the $M_{20,\,H\text{-BAND}}$ and $A_{H\text{-BAND}}$ plane and there is no selection that would substantially reduce the contamination.

As a validation of the latter statement we considered the 50 galaxies for which all three versions of the mass maps are available and, for each combination of the photometric data, we independently identified the samples of non-interacting galaxies and mergers, even when accounting for errors (i.e., we selected as merger candidates those galaxies that have error bars above the relations in Equation (2)). We did so for both the $H$-band and mass structural indices. We then assumed that the classification performed using the deep HUDF + HUDF12 mass maps is the “correct” one and we calculated for the mergers and disks identified at the other depths or in the $H$-band the fraction that have a consistent classification—i.e., mergers or non-interacting galaxies classified as such also on the deep mass maps—and the fraction of galaxies which are instead misclassified as a consequence of the lower S/N—i.e., galaxies classified as mergers that are identified as not-merging on the deep HUDF + HUDF12 maps or $H$-band images, vice versa.

We show the results of this calculation in Figure 12. The number of identified mergers is small and thus the error bars are relatively large, however the figure shows that by applying the relations in Equation (2) the fraction of “misclassified mergers” in the mass selected sample is consistent with being ~20% for mass maps obtained from both the HUDF + CANDELS-Deep and GOODS+CANDELS-Deep combinations. Conversely, for the structural indices $A_{H\text{-BAND}}$ and $M_{20,\,H\text{-BAND}}$, the contamination of “false mergers” remains as high as ~50% for both the HUDF and CANDELS observations, even when imposing the condition in Equation (2). As witnessed by the increase in the fraction of galaxies that are misclassified as disks in Figure 12, the drawback of the refined selection is that a larger number of mergers are missed from the selection at the shallower depths.

Summarizing the above findings, the availability of deep photometry is certainly necessary for maximizing the accuracy and completeness of the mass based classification. Nonetheless, applying small corrections to our simulation-motivated selection of mergers reliable mergers samples can be identified also
on medium depth images, albeit reaching a lower completeness. Most notably, independently of whether Equations (1) or the refined relation in (2) are applied to the $A_{H\text{-BAND}}$ and $M_{20,H\text{-BAND}}$ indices, we find the $H$-band classification results in a twice as large contamination of clumpy disks in the merger sample at any depth here considered.

We identify our final sample of merger candidates among the HUDF sample as those galaxies that satisfy the selection criteria in Equation (2) even when accounting for the error in the measurements (i.e., have error bars above those relations). The classification is performed on the deep HUDF + HUDF12 mass maps when available and on the HUDF + CANDELS-Deep maps for those galaxies with no HUDF12 coverage. We find a total of 11 such candidates over the 87 galaxies with reliable mass maps. For the latter, we show in Figure 13 the $b_2H$, $H$-band and mass stamps. Among this sample of mergers are included one galaxy with an inconsistent visual class and also one object that has been flagged as possible chance projection in Section 4.2 (ID 15844, but note that even excluding the secondary blue clump this galaxy would still be classified as a merger), suggesting again a 20% contamination level.

Figure 13. As in Figure 11, but in this case showing galaxies which satisfying the relations in Equation (2) even when accounting for errors in the measurements and hence are candidate mergers according to our definition.
7.3. Mergers Missed in the H-band

Thus far we have focused on those galaxies which are misclassified as mergers in the H-band because of the presence of bright clumps. It is however interesting to test whether the opposite also occurs, i.e., whether there are galaxies classified as mergers in the structural analysis performed on the mass maps which instead appear smooth(er) in the H-band, for example, as a result of dust lanes or intrinsically high $M/L$. Figure 12 suggests that this happens for roughly 10% of the “H-band smooth” galaxies. In our sample of 11 mass-selected merger candidates we find 5 galaxies (IDs 9704, 11388, 12624, 14533, and 15432) that fall below the dotted lines in Figure 8 when using $M_{20, H-band}$ and $A_{H-band}$, and hence would not be classified as mergers in the H-band.

To understand the origin of this discrepancy, we generated new versions of the mass maps for these galaxies obtained by applying no dust extinction during the pixel-by-pixel SED fitting. This gives us an indication of whether the mass asymmetry is driven by the dust correction applied to the templates. IDs 9704 and 14533 display significant asymmetries also in these mass maps, indicating that the classification is independent of the extinction law assumed. IDs 12624, 11388, and 15432 instead would not satisfy our selection criteria with dust-free mass maps. We note that both IDs 12624 and 15432 are detected in the far-IR with total IR luminosities $L_{\text{IR}} > 10^{12}$L$_{\odot}$, implying a substantial amount of dust in these galaxies leading us to favor the results obtained including dust corrections.

While it is clear that additional, e.g., kinematic, information is required for a complete characterization of the population of “mass-smooth and H-clumpy” galaxies, the available data suggest that most of these galaxies have distinct substructure and that dust obscuration can explain some of the differences between the H-band and mass morphology.

8. SUMMARY AND CONCLUSIONS

Using a sample of about 100 HUDF galaxies with $1.5 \leq z \leq 3$, we have compared a morphological classification of merging galaxies based on non parametric structural indices derived on resolved stellar mass maps with a canonical classification obtained from H-band measurements. We tested this approach using photometry at the different depths available on the HUDF area (GOODS, CANDELS, and HUDF/HUDF12) and, performing tests on artificial stellar mass distributions, we derived luminosity and size limits for which reliable mass maps can be obtained. The selection of mergers in the mass domain is calibrated using a sample of isolated and merging galaxies from the MIRAGE hydrodynamical simulations which have been post-processed and analyzed to closely reproduce the observational data.

We summarize our findings as follows.

1. As also discussed in previous works (Wuyts et al. 2012), the stellar mass maps morphologies cannot be reproduced by H-band data alone which often display merger-like features even for galaxies with perfectly smooth, disk-like mass profiles. Although some of these galaxies display a red nucleus indicative of a central mass concentration, even a combined visual inspection of multiple bands is still affected by the presence of star-forming clumps and does not provide a full proxy for the mass distribution. As a consequence of the above, we quantify that merger samples identified on the basis of asymmetry/irregularity in the H-band images can have a contamination from clumpy galaxies as high as 50%. Our analysis also suggests that differences between the mass- and H-band selection may originate from a population of galaxies with smoother H-band images than mass distribution, possibly as a result of dust extinction.

2. For both the data and the simulations, we find that a combination of $A_{\text{MASS}}$ and $M_{20, \text{MASS}}$ measured on the stellar mass maps is instead most cleanly separating major mergers from isolated, clumpy galaxies. We use the results from the simulations and the analysis on the real HUDF galaxies to provide in Equations (1) and (2) quantitative criteria to separate the galaxy population into mergers and disks using mass maps derived at the HUDF + HUDF12, HUDF + CANDELS-Deep and GOODS +CANDELS-Deep depths. Applying these criteria, we estimate that chance projections or the scattering of clumpy disks in the merger sample by noise in the mass maps result in a contamination of roughly 20%. When applied to galaxies with available kinematic data, our $A_{\text{MASS}}$ and $M_{20, \text{MASS}}$ based classification results in morphologies that are consistent with the kinematic classes.

3. The ability of the mass-based $A_{\text{MASS}}$ and $M_{20, \text{MASS}}$ indices to select true mergers is not significantly affected by a moderate decrease in the S/N of the parent images if the conditions in Equation (2) are used. Conversely, the H-band classification result in a twice as large contamination from clumpy disks, independently of the criteria that are applied.

4. From the analysis of the MIRAGE simulated mergers we estimate the proposed $A_{\text{MASS}}, M_{20, \text{MASS}}$ selection should be sensitive to major mergers between 300 and 50 Myr before coalescence.

Based on the above results, we thus suggest that to identify major mergers a classification in the mass domain rather than from optical/NIR images should be preferred and performed whenever possible. Obviously, our technique is only sensitive to merger phases in which the perturbation in the mass profiles...
is measurable (roughly up to 300 Myr before coalescence as specified above) and, as also a consequence of imposing a high “purity” in the resulting merger sample, is strongly biased against earlier merger stages. A combination with other techniques (e.g., close kinematic pair selection) would be hence necessary for a full census of merging systems.

Finally, it is possible that variations in the gas fraction of galaxies and the actual masses of giant clumps could introduce some redshift dependent scaling of the threshold here derived, moving the locus of clumpy disks toward slightly higher $A_{\text{MASS}}$ and/or $M_{\text{20,MASS}}$ values at higher redshift. However, we expect that these variations would be comparable to the uncertainties in the mass maps and the derived structural parameters and hence would not strongly affect the proposed classification for sufficiently large samples.

A.C. thanks P. Hurley, M. T. Sargent, and V. Strazzullo for useful discussions and suggestions. We also thank the anonymous referee for valuable comments which improved the manuscript. We acknowledge financial support from the Swiss National Science Foundation (A.C., Project PBEZP2_137312), from the Agence Nationale de la Recherche (A.C., E. l. F., contract #ANR-12-JS05-0008-01) and from the E. C. through an ERC grant (A.C., F. B., StG-257720). The simulations used in this work were performed on GENCI resources at the Tres Grand Centre de Calcul (project 04-2192) and at the LRZ SuperMUC facility under PRACE allocation number 50816. This work is based on observations taken by the CANDELS Multi-Cycle Treasury Program with the NASA/ESA HST, which is operated by the Association of Universities for Research in Astronomy, Inc., under NASA contract NAS5-26555. This work

Figure 15. As in Figure 7 but this time also considering the structural parameters $C$, Gini and $\psi$. Top panel block: relation between different structural indices for the sample of MIRAGE simulated mergers and isolated disks. From top to bottom measurements are performed on the artificial HST F435W, F850LP, F160W images and on the mass map as indicated in the labels. The dashed lines highlight the best dividing relation between mergers and disks (maximum margin classifier) obtained with a SVM approach. In the Gini-$M_{\text{20}}$ plane, we also show for reference the merger threshold of Lotz et al. (2004) with a thin dotted line. Our results remain unchanged if using this relation instead of that derived from the SVM algorithm. Lower panel block: for each of the selection criteria in the upper panels, we plot the contamination from isolated disks in the merger sample (snapshots falling above dotted line) and the completeness in the selected sample of mergers. All mergers independently of their ratio are here considered. Colors and symbols are as in Figure 7.
has made use of the adaptive smoothing code adaptsmooth, developed by Stefano Zibetti and available at the URL http://www.arcetri.astro.it/zibetti/Software/ADAPTSMOOTH.html

APPENDIX

RELIABILITY OF THE MASS MAPS AND DERIVED PARAMETERS

A.1 Comparison with Integrated Masses

As a basic consistency check of the mass maps for the sample described in Section 2.3, we show in Figure 14 the comparison between the sum of the masses in each individual pixel of the galaxy and the total galaxy mass that is obtained from the integrated photometry. Although for highly obscured or strongly star-forming galaxies differences between the two estimates can be expected on an object by object basis due to the patchy distribution of dust, strong disagreement between the resolved and integrated estimates would be an indication of biases in the pixel-by-pixel SED fits. We instead find a very good agreement between the pixel-based total mass and the whole galaxy mass, with a median difference which is less than 0.1 dex.

A.2 Description of the Models used for Testing the Mass Reconstruction

As mentioned in Section 2.5, the resolution and noise of the parent observations set major limitations for the estimate of the stellar mass maps. In order to derive the size and magnitude limits for which a reliable mass map can be obtained, we tested the pixel-based SED fitting on a sample of artificial galaxies that are representative of typical real galaxies, the models were drawn from the observed sample as follows.

For each real HUDF galaxy in the initial sample presented in Section 2.3, we generated a toy mass distribution characterized by a Sérsic profile with a total mass equal to the galaxy integrated mass and structural parameters determined by the best-fit H-band GALFIT (Peng et al. 2010) model. To densely populate the magnitude-size plane, we also generated extra models by adding random perturbations on the original galaxies parameters. We then imposed each pixel in the artificial galaxy to have an SED equal to the observed best-fit
SED for the entire galaxy (including a uniform extinction for all pixels) and used this SED to predict the pixel fluxes. From these flux maps we generated artificial HST images which we pasted into blank sky regions to mimic the typical S/N properties reached by the real galaxies with HUDF optical plus CANDELS-Deep NIR coverage. This depth is in between the two extreme combination of imaging (deep HUDF + HUDF12 or shallow GOODS+CANDELS-Deep) used for creating the mass maps (see Section 2.1). Specifically, we created stamps at the HUDF depth for the F435W, F606W, F775W, and F850LP filters, while the F814W, F105W, F125W, and F160W images were matched to the CANDELS-Deep depth. All images were degraded to the resolution of the F160W filter as in the real sample.

We finally computed “observed” mass maps form these artificial images as described in Section 2.4, i.e., by running ADAPTSMOOTH, extracting pixel-based SEDs, and fitting them with LePHARE and used these “observed” mass maps for our tests in Section 2.5. Although these simulations are undoubtedly a simplification of reality which is complicated by pixel-by-pixel variations of the SED, dust content, etc., they provide us with a measure of systematic biases in the mass estimation.

A.3 The Choice of Classification Parameters: Discriminating Power and S/N Effects

Together with the $M_{20}$ and A indices described in Section 5.1, we also evaluated the following structural indicators.

1. The concentration C defined as the logarithmic ratio of the radii containing 20% and 80% of the total flux $C = 5 \log(r_{80}/r_{20})$ (Bershady et al. 2000; Conselice 2003).
2. The Gini coefficient (Abraham et al. 2003; Lotz et al. 2004), which describes the uniformity of the flux distribution on a scale between 0 (all pixels with equal flux) and 1 (all flux in just one pixel).
3. And finally the multiplicity $\psi$ that quantifies the presence of multiple components through a comparison between the original image and a resampled version in which the pixels are re-arranged in decreasing flux order from the brightest pixel (Law et al. 2007). For this latter parameter we slightly modified the original definition proposed in Law et al. (2007) to account for ellipsoidal light/mass distribution.

We present in Figure 15 the analogous of Figure 7 but this time considering planes that include also C, Gini and $\psi$. On one hand, the figure reinforces the results of Sections 6 and 7: even for these different combinations of structural indicators, the contamination in a mass-based selection of mergers is smaller than that obtained with measurements performed on the F160W and F850LP images. On the other, it justifies the choice of $M_{20, MASS}$--$\Psi_{MASS}$ as our fiducial combination: it can be noticed in fact that these other sets of indices result in either a higher contamination or lower completeness with respect to a classification based on $M_{20, MASS}$--$\Psi_{MASS}$ (see lower panels of Figures 15 and 7). An exception is the $M_{20, MASS}$--$A_{MASS}$ combination which produces comparable results to those obtained for $M_{20, MASS}$--$\Psi_{MASS}$. We show in the following that the Gini coefficient is however more sensitive to the choice of the aperture used in the calculation and the noise in the image than the $M_{20}$ or A indices, and hence a less stable structural measurement.

This is illustrated in Figure 16 where study the variation of the structural indices with image depth and aperture size used in the calculation. We only discuss the comparison for the structural indices measured on the mass maps obtained from the combinations of HUDF + HUDF12, HUDF + CANDELS-Deep, and GOODS+CANDELS-Deep photometry. Nonetheless, we also present the results for the indices derived on the $H$-band at HUDF or CANDELS depth for completeness of information. Specifically, we considered those galaxies (50) with $r_{kron} > 5 \times $ PSF and $H \leq 24.5$ that have coverage in the HUDF, CANDELS, as well as GOODS fields and calculated the structural indices at all depths, within either a Kron or Petrosian aperture. The use of two different apertures allows us to further test the impact of the noise in the images: the Kron aperture is usually larger than the Petrosian radius16 (see Table 1) and hence includes a higher number of low flux pixels; differences between the two estimates can be used to assess the stability of the measurement. This is also the reason why we opted for a Petrosian aperture in the calculation of the parameters in Section 5.1. The points in Figure 16 show the median values of the structural indices over all the 50 galaxies here considered.

A reliable measure of structure should show as little variation as possible with both imaging depth and aperture size in Figure 16. The asymmetry $A_{MASS}$ is in this sense very robust with median values that remain almost identical at all depths and for both apertures. This should be compared, for example, with the results for the Gini coefficient in the right-most column which clearly shows a strong dependence on the aperture size with differences up to about 30%. As already pointed out in the work of Lisker (2008), this is a consequence of the fact that Gini becomes a tracer of the noise in the images rather than galactic structure for large apertures. The other parameters, $M_{20, MASS}$, $\Psi_{MASS}$, and $C_{MASS}$, all show some dependence on the depth of the images used for constructing the maps, shifting toward lower concentrations/higher clumpiness when using the GOODS+CANDELS-Deep photometry instead of the deep HUDF + HUDF12 imaging. The largest variations are measured for the multiplicity $\Psi_{MASS}$ (more than 50% change among the various cases), whereas the $M_{20, MASS}$ coefficient varies by $\lesssim 15\%$.

In combination with Figure 7, these findings justify our choice of $A_{MASS}$--$M_{20, MASS}$ in Section 6.2 as the most powerful and less noise- or aperture-dependent parameter set for the discrimination of merging and clumpy galaxies.

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16 We note that the Petrosian aperture considered here is the actual Petrosian radius, i.e., not the default SEXTRACTOR aperture equal to $2 \times R_{\text{petrosian}}$. 

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