A Folding Algorithm for Extended RNA Secondary Structures

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ABSTRACT

Motivation: RNA secondary structure contains many non-canonical base pairs of different pair families. Successful prediction of these structural features leads to improved secondary structures with applications in tertiary structure prediction and simultaneous folding and alignment.

Results: We present a theoretical model capturing both RNA pair families and extended secondary structure motifs with shared nucleotides using 2-diagrams. We accompany this model with a number of programs for parameter optimization and structure prediction.

Availability: All sources (optimization routines, RNA folding, RNA evaluation, extended secondary structure visualization) are published under the GPLv3 and available at www.tbi.univie.ac.at/~choener/segfold/.

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1 INTRODUCTION

The classical RNA secondary structure model considers only the Watson-Crick AU and GC base pairs as well as the GU wobble pair. A detailed analysis of RNA 3D structures, however, reveals that there are 12 basic families of interactions between the bases, all of which appear in nature (Leontis and Westhof, 2001; Leontis et al., 2002). This has led to the development of an extended presentation of RNA contact structures with edges labelled by their pairing type. This extended description of base pairing is commonly termed after its inventors the Leontis-Westhof (LW) representation.

The LW representation has proved to be a particularly useful means of analyzing three-dimensional structures of RNA as determined by X-ray crystallography and NMR spectroscopy (Leontis and Lescoute, 2006). In particular, it has led to the discovery of recurrent structural motifs, such as kink-turns and C-loops, that act as distinctive building blocks of 3D structures. The sequence variation in these structural motifs follows combinatorial rules that can be understood by the necessity to maintain the overall geometry when base pairs are exchanged. These isostericity rules are discussed in detail by Lescoute et al. (2005); Stombaugh et al. (2009).

Since many additional interactions beyond the standard base pairs are represented in the LW formalism, loops of the classical secondary structures now appear as complex structures of non-standard base pairs. Effectively, long loops are therefore subdivided into much shorter ones. Parisien and Major (2008) proposed a model that contains loops with no more than 4 unpaired bases. For unbranched structures, it is parameterized by a statistical potential estimated from the available 3D structures by counting the relative frequencies of base pairs, short unbranched loops of particular shapes in dependence of their sequences, and combinations of loops with a common base pair. An accompanying folding procedure, MC-Fold (Parisien and Major, 2008), which exhaustively enumerates stem-loop components, is available and has been used very successfully as a first step towards the de novo prediction of RNA 3D structures using MC-Sym (Parisien and Major, 2008) which takes as input the proposed secondary structure from MC-Fold.

2 MC-FOLD REVISITED

2.1 Algorithm

Like ordinary secondary structure prediction tools, MC-Fold is based on a decomposition of the RNA structure into “loops”. In contrast to the standard energy model, however, it considers the full set of base types available in the LW representation. Each base pair, therefore, corresponds to a triple \((i, j; \theta)\) where \(\theta\) is one of the 12 types of pairs. Ordinary secondary structures, thus, can be thought of as the subset of pairs where the type \(\theta = \text{WC}\).
and the two nucleotides form one of the 6 canonical combinations \{AU, UA, CG, GC, GU, UG\}. This extension of the structure model also calls for a more sophisticated energy model. While the standard model assumes that the contributions of the loops are additive, MC-Fold also considers interactions between adjacent unbranched loops (hairpins, stacked pairs, bulges, and general interior loops). Dispensing with details of the parameterization, the scoring function of MC-Fold for a structure \( S \) on sequence \( x \) can be paraphrased as follows:

\[
E(S|x) = \sum_{\mathcal{G}} E_c(\mathcal{G}|x|\mathcal{G}) + \sum_{(k,l)\in\mathcal{E},(\mathcal{G}',\mathcal{G}'')} E_{j+h}(\mathcal{G}',\mathcal{G}'',\theta;x[k],x[l])
\]  

(2.1)

where \( \mathcal{G}', \mathcal{G}'', \mathcal{G}''' \) are the loops of \( \mathcal{G} \), \( E_c \) tabulates the sequence-dependent contributions of the loops, and \( E_{j+h} \) accounts for the “junction” and “hinge” terms in stem-loop regions that depend on the type of the adjacent loops, and the type \( \theta \) and sequence \((x[k],x[l])\) of the base pair that connects them. For multiloops only the loop-term is considered.

Let us ignore multiloops for the moment. A basepair \((i,j)\) then encloses a loop of type \( L \) which is either a hairpin or connected to a single enclosed loop \( \mathcal{L} \) by a base pair \((k,l,\psi)\) with \( i < k < l < j \). Let \( B_{ij}(\theta; L) \) be the minimal energy of a structure on \( x[i,j] \) enclosed by a base pair \((i,j)\) with outermost loop of type \( L \). Note that, in our notation, the loop type \( L \) also specifies its length and hence implicitly determines the coordinates of the inner base pair of an interior loop: \((k,l) = (i + \ell_1(L),j - \ell_2(L))\). For simplicity we write \((k(L),l(L))\). If \( L \) is a hairpin, then

\[
B_{ij}(\theta; L) = \mathcal{H}[i,j;\theta;\text{hairpin}], \text{ a tabulated energy parameter.}
\]

Otherwise, we have the recursion

\[
B_{ij}(\theta; L; \psi, \chi) = \min_{\psi,\chi} \left( B_{ij}(\theta; L; \psi, \chi) + B_{k,l}(\mathcal{L};l(L);\psi,\chi) \right)
\]  

(2.2)

If desired, this could even be expanded to a full “next-nearest-neighbor” model by enforcing an explicit dependence on the type of the inner base pair:

\[
B_{ij}(\theta; L; \psi) = \min_{\psi,\chi,\phi} \left( \beta[i,j;\theta;L;\psi,\chi,\phi] + B_{k,l}(\mathcal{L};l(L);\psi,\chi,\phi) \right)
\]  

(2.3)

The effort to evaluate this recursion equation for a fixed base pair \((i,j)\) is \( L^3T^3 \), where \( L \) is the number of loop types and \( T \) is the number of base pair types. While this prefactor is inconveniently large, we nevertheless obtain an \( O(n^2) \) folding algorithm instead of the exponential run-time of MC-Fold.

The problem with this general form of energy parameterization is the unmanageable number of parameters that need to be measured, estimated, or learned from a rather limited set of experiments and known RNA structures.

### 2.2 Parameterization and Implementation

Since the folding problem for the MC-Fold model can be solved in polynomial time, the associated parameter estimation problem also becomes amenable to advanced parameter optimization techniques (Do et al., 2008; Andronescu et al., 2007). At present, however, we have opted to extend the original MC-Fold parameters only by simple sparse data corrections that can be applied on top of the original MC-Fold database. This also has the advantage of allowing a direct comparison between the original version of MC-Fold and our dynamic programming version MC-Fold-DP. In contrast to the original version, large data sets and long sequences (33s for 250nt, about 100s for 500nt, compared to 660s for 100nt) become tractable with MC-Fold-DP. 1

1 Note that the implementation has not been aggressively optimized apart from using the polynomial-time algorithm.
3 BEYOND 1-DIAGRAMS

3.1 Base Triplets

An important restriction of secondary structures is that each nucleotide interacts with at most one partner. In combinatorial terms, secondary structures are 1-diagrams. A closer analysis of the available 3D structures, however, reveals that many nucleotides form specific base pairs with two other nucleotides, forming “base triplets” or, more generally, “multi-pairings”. Cross-free b-diagrams with maximal number b of interaction partners for each nucleotide can be treated combinatorially in complete analogy with (pseudoknot-free) secondary structures by conceptually splitting each node into as many vertices as there are incident arcs. As in the case of secondary structures, we say that (i, j) and (k, l) cross if i < k < j < l or k < i < l < j. A b-diagram is non-crossing if no two arcs cross. Base pairs can then be well-ordered also in this extended setting: Two distinct arcs (i, j) \( \neq (k, l) \) are either nested \( (i < k < l < j) \) or juxtaposed \( (i < j < k < l) \). This observation is used in RNAfotifScan (Zhong et al., 2010) to devise a dynamic programming algorithm for sequence-structure alignments along the lines of RNAsc (Bafna et al., 2006) or Locarna (Will et al., 2007), which in turn are restricted variants of the Sankoff algorithm (Sankoff, 1985).

Here we consider only structures with at most two base pairs involving the same nucleotide, i.e., 2-diagrams. In this case there is a convenient string representation generalizing the Vienna (dot-parentheses) notation for secondary structures by introducing three additional symbols \(<, >, X\) for position in which two arcs meet: \((i < k < j < l) = >, (i < j < k < l) = <, (i = j) = X, (i = k) = \). For general \( b \), the number of necessary symbols grows quadratically, \( s_b = (b + 1)(b + 2)/2 \), since each must encode \( b \) opening and \( b \) closing pairs with \( b_1, b_2 \geq 0 \) and \( b_1 + b_2 \leq b \).

3.2 A Grammar with Base Triples

In order to design a dynamic programming folding algorithm for cross-free 2-structures we need a decomposition, i.e., a grammar for 2-structures. For practical applications it is desirable to have not only a minimization algorithm but also a partition function version.

To this end, an unambiguous grammar is required (Dowell and Eddy, 2004; Reeder et al., 2005). A simple version, treating base pairs as the elementary entities is shown in Fig. 2. It translates into an extension of either a Nussinov-style algorithm for maximizing the number of base pairs or a recursion for counting the number of non-crossing two-diagrams. Let \( F_{ij} \) denote the minimum energy of a structure on the sequence interval \( x[i..j] \). We have

\[
F_{ij} = \min \left\{ C_{ij}, \epsilon_{ij} + U_{i,j-1}, \epsilon_{ij} + V_{i+1,j}, \epsilon_{ij} + W_{i,j} \right\}
\]

and analogous recursion for \( U_{ij} \) and \( W_{ij} \). Denoting the minimum energies over all structures whose left, right, or both ends, are involved in a triplet. The symbol \( C_{ij} \) refers to structures enclosed by a non-triplet base pair. In the simplest case \( C_{ij} = \)
Fig. 3. Decomposition of one non-terminal in the full loop-based model with triples. The l.h.s. of the production rule denotes a structure enclosed by a base pair where the base at the 3’ end is part of a triple. The second base pair of this triple ends within the structure. The structural element is either bulge-like (1st column) or multi-loop like. In the first case, we have to distinguish whether the enclosed structure has a normal pair or a triple at its 5’ side. In the multi-loop case we use the linear decomposition into components familiar from the Turner model with a non-terminal denoting a partial multi-loop containing at least one base pair. Here we need to distinguish whether the 5’ end of the rightmost component and 3’ end of the left components are triples or not. As the multi-loop part is not implemented in our current version, it is grayed out.

\[ \epsilon_{ij} + F_{i+1,j-1} \] (lower right corner of Fig. 2). The terminal symbols are the unpaired base \( \bullet \), the ordinary base pairs, and the three types of base pairs involved in triples, contributing \( \epsilon_{ij} = 0 \), sequence-dependent energy increment \( \epsilon_{ij} \), and sequence-dependent energy increments \( \epsilon_{ij}^{c}, \epsilon_{ij}^{t} \), and \( \epsilon_{ij}^{e} \), respectively. The recursion is initialized with \( F_{ii} = 0 \).

Only certain combinations of types of base-pairs can occur in triples. Thus in a refined model we need to replace \( U_{ij}, V_{ij} \) and \( W_{ij} \) by \( U_{ij}[\nu], U_{ij}[\mu], \) and \( W_{ij}[\xi] \) explicitly referring to the base pair type(s) of the triplet. Furthermore, the energy parameters also become type-dependent \( \epsilon_{ij}^{c} \rightarrow \epsilon_{ij}^{c}[\nu] \), or even \( \epsilon_{ij}^{c}[\nu, \mu] \) where \( \rho \) is the type of the pair itself and \( \nu \) is type of the second pair of the triplet. The first variant is chosen for Nussinov variants, where each individual basepair is evaluated, splitting triples, and the second variant is more fitting for Turner-like nearest-neighbor models. In that case, recursion on \( W \) changes to \( W_{ij}[\nu, \mu] \) to reflect the pairing choice being made.

### 3.3 Full Loop-Based Model

The grammar of Fig. 2 can be extended to incorporate the standard loop-based Turner energy model (Turner and Mathews, 2010) (which distinguishes hairpin loops, stacks of two basepairs, bulges, interior loops, and multibranched loops). The modification of the grammar is tedious but rather straightforward, Fig. 3. Instead of treating the base pairs themselves as terminal symbols (as in Fig. 2) this role is taken over by entire loops. Note that as in the case of ordinary secondary secondary structures, each loop in a given structure is uniquely determined by its closing pair. The energy contributions now depends, in a more complex way, on the characteristics of the loop, hence we also need additional non-terminals to describe e.g. the components of multiloops.

We use a decomposition that is similar to that of MC-Fold and in addition encompasses 2-diagrams. A \( p \times q \)-loop, \( p \leq q \), consists of \( p \) nucleotides on one strand and \( q \) nucleotides on the other one. In particular, \( 2 \times 2 \)-loops correspond to stacked base pairs, \( 1 \times q \)-loops, \( q > 1 \) are triples, and \( 2 \times 3 \)-loops are stacks with a bulged-out nucleotide. In addition to hairpin loops and these \( p \times q \)-loops, we consider generic bulges with and without a shared nucleotide, interior loops of larger sizes and multibranched loops, again possibly with shared nucleotides. Fig. 3 gives an example for the full loop-based decomposition of one particular non-terminal.

In our current implementation we use several simplifications in particular for multi-loops that involve triples. Some information on the complete grammar used in our implementation can be found in the appendix, other information is available on the Segfold homepage.

### 4 IMPLEMENTATION

#### 4.1 Folding Software

The implementation available on the Segfold homepage is written in the high-level functional programming language Haskell. While this leads to an increase in running times (by a constant factor), the high-level notation and a library of special functions lead to very concise programs, and enable, e.g., the use of multiple cores.

Currently, the following algorithms are implemented: (i) An optimizer which takes a set of melting experiments and the PDB database as input and produces a parameter file optimized as described below. (ii) A folding program which expects a sequence of nucleotides as input and produces an extended secondary structure prediction which includes nucleotide pairs of non-canonical types. Furthermore it can contain motifs with base triples. (iii) An evaluation program which expects both, a sequence and a secondary structure. The input is then evaluated to return the score of said structure and, if requested, tries to fill the given (canonical) structure with additional pairs. This allows to turn a classical secondary structure into an extended secondary structure by filling large loops with non-canonical pairs.

At the moment, base triples have been restricted slightly in that shared nucleotides are only possible in stem structures, not within a multibranched loop motif. Allowing shared nucleotides between two helices of a multiloop would slow down multi-loops by a significant factor. Nevertheless, we will lift this restriction for the full nearest-neighbor model we plan to implement. In the full model, we will be able to use data gathered from our current model to reduce the combinatorial complexity of the algorithm within multibranched loops.

#### 4.2 Parameter Estimation

In contrast to the Turner model, which considers only canonical basepairs (i.e., Watson-Crick and GU (wobble) pairs), we include all types of base pairs. Thus, we also have to derive parameters for all possible basepair families in our motifs of choice. To this end we need to find sufficient evidence for each parameter and we need an efficient numerical algorithm for optimizing the parameters.

(i) Even if a large body of sequence/structure pairs is available to train the parameters, it is still highly unlikely that each parameter is witnessed. A simple calculation for canonical stacked pairs already produces \( 4^3 \times 12^2 = 36864 \) (ignoring symmetries) parameters to be trained. While symmetries reduce the number of distinct parameters, canonical stacks still require \( \sim 10000 \) independent parameters. In total, the number of parameters easily reaches \( 10^5 \), which means that only a very small set of parameters will actually be observed in experimentally verified structures.

(ii) The second problem is of numerical nature in that it gets hard to estimate a solution in \( \mathbb{R}^{100000} \) even under ideal circumstances. In addition, the computational effort for the computation of the solution vector is rather high. There are two different types of approaches to this problem, described in some detail by Andronescu et al. (2007). In max-margin formulations, parameters are optimized such as to drive them away from wrongly determined structures and toward correctly determined ones. Alternatively, the conditional likelihood of known structures is maximized. Andronescu et al. (2010) described an extension of the algorithm that can deal with un-observed configurations by employing a hierarchical statistical model.
We have selected yet another way of dealing with the immense number of features. Instead of optimizing the full set of parameters directly we first optimize the parameters for a restricted model closely following the simple unambiguous grammar given in Fig. 2. In short a loop of type \( r_1 \) (e.g. stacked pair, bulge, etc) enclosed by two pairs \( p_1, p_2 \) is assigned an energy \( \epsilon (m) + \epsilon ^m (p_1) + \epsilon ^m (p_2) \), where \( \epsilon (m) \) depends on the type and size of the loop but is independent of sequence, and the pair energies depend on the identity of the nucleotides as well as the LW type (e.g. GC,cWW).

We call our model enhanced Nussinov as it distinguishes between loops of different types (say bulges of different lengths are assigned different scores) but assumes that pair energies are independent as in the Nussinov model.

This approach has several advantages. First, the resulting algorithm is an "toy-model" that can be employed to test different hypotheses. Second, the estimated parameters provide a useful set of priors for the full model. This is important since, in contrast to the work of Andronescu et al. (2007), we cannot derive a complete set of priors from known data. Finally, the computational requirements are significantly lower. Training a full Boltzmann model for conditional likelihood maximization might easily have taken months of CPU time (Andronescu et al., 2010).

Here, we utilize both melting experiments and PDB data for parameter estimation. Melting experiments yield a small set of sequences, structures and corresponding free energies. The structural data, unfortunately, provides almost exclusively canonical Turner features and no information regarding the basepair family, although it can be assumed that all pairs are of the Watson-Crick (cWW) style. The PDB data, on the other hand, contain not only non-canonical base pairs, but also provide information on the basepair family. In addition, PDB entries typically refer to structures that are much larger than those used in melting experiments.

Together, both sets provide data required for the estimation of an extended set of parameters. In order to keep computation times short, we employ the original no-max-margin constraint-generation approach used by (Andronescu et al., 2007). While not providing the most accurate parameters in the original paper, the relatively short runtimes of approximately one CPU day are convenient for experimental purposes. In addition, since we are training an enhanced Nussinov-style model, we can assume that the prediction accuracy is limited by the structure of the model. More advanced, and hence computationally more expensive, training methods are therefore unlikely to lead to substantial improvements of the prediction accuracy.

### 4.3 Optimization

Our task is to estimate the energy contributions \( x_j \) for a given collection of features \( j \). In this context, a feature corresponds to a terminal symbol in our grammar with a fixed underlying sequence, such as GC/GC stacked pair or a 1 × 3-loop with sequence (G—AUC) where GA is a Hoogsteen pair and GC is a Watson-Crick pair. We are given the following types of data: (1) a matrix \( A \) whose entries \( A_{ij} \) encode how often feature \( j \) occurs in sequence/structure pair \( i \), and (2) a vector \( y \) containing measured melting temperatures \( y_i \) for experiment \( i \).

Constraints are now generated as follows. For each entry \( k \) of the PDB we extract the (extended) secondary structure features. This means that neither pseudoknots nor intermolecular interactions (which require more complicated grammars) are considered. The entry \( f^j \) of the row vector \( f^j \) counts how often feature \( j \) is observed in the structure. Using the current parameter values \( x \) (see below), the sequence of PDB entry \( k \) is folded and the corresponding feature vector \( g^k \) is constructed. If the predicted fold has a lower free energy than the known structure, a new constraint \( (f - g)^T x \leq 0 \) is introduced. Note that \( f^j x \) and \( g^j x \) are, by construction, the free energies of the known and the predicted structure evaluated with the current parameters \( x \). Since the true structure is expected to be the thermodynamic ground state, its free energy must be smaller than that of any other structure. The constraint matrix \( D \) contains all currently active constraints where \( D_{kj} \) is the \( k \)th active constraint.

Following Andronescu et al. (2007), we use a slack variable \( \delta_k \) for each constraint so that \( D_k x \leq \delta_k \). This guarantees that the problem remains feasible as otherwise conflicting constraints could reduce the feasible set for \( x \) to the empty set. The slack variables \( \delta_k \) are bounded from below by \( 0 \leq \delta_k \) because \((f - g)^T x \geq 0\), with equality for co-optimal structures. Norm minimization problems can drive individual variables \( x_i \) to extreme values. We therefore constrain the energy contribution of individual features to \( |x_i| < 5 \) kcal/mol. A subset \( S \) of features that act as penalties are constrained to positive values, \( x_i \geq 0 \) for \( j \in S \). The set \( S \) is defined along the following principles: unpaired loop regions destabilize the structure relative to a random coil and hence should be penalized. Hairpins, bulges and interior loops fall into this category. In addition, 1 × 2 and 2 × 3 stems, which are otherwise modelled as 2 × 2 stems, are penalized. Hence, for e.g. the 2 × 3 loop CAUGG with A unpaired, we have \( \epsilon (CG) + \epsilon (UG) + \epsilon (2 \times 3) \) where \( \epsilon (2 \times 3) \) is the penalty term.

Parameter estimation is thus reduced to the constrained norm optimization problem

\[
\frac{1}{2} \left\langle A \begin{pmatrix} 0 \\ D \end{pmatrix} \begin{pmatrix} x \\ y \end{pmatrix} - \begin{pmatrix} y \\ d \end{pmatrix} \right\rangle_2^2
\]

with the linear constraints

\[
-5 \leq x_j \leq 5, \quad 0 \leq x_i, \quad l \in S, \quad 0 \leq \delta_k.
\]

Since this optimization problem is convex it can be solved efficiently.

The parameter vector \( x \) is optimized iteratively. Initially, \( D \) is empty and no slack variables \( d \) are used. After the first step, all PDB sequences have been folded and those for which the predicted structure is different from the known structure are included as a row in \( D \) as described above. The slack variables are initialized as \( d_k = D_k x + \gamma \) for each constraint \( k \), where \( \gamma \in \mathbb{R}_+ \) is a small constant. Iterations of the optimization procedure continue until no more constraints have to be added.

The computational effort required, both to estimate the parameters and to fold a single sequence, is higher than what is required for the Turner model. The additional computational effort required by the folding algorithm is mainly a result of the inclusion of the pair family information. In the case of 2-loops (stacks, bulges, interior loops), we incur an additional factor of 12 since each possible pair family has to be considered. More problematic are multibranchied loops in the case of shared nucleotides as now there are up to 12 × 11 possibilities to connect a shared nucleotide with its pairing partners.

### 4.4 Comparison with Turner Parameters

A comparison with the parameter sets by Turner (Turner and Mathews, 2010) shows that individual contributions are similar enough to make the the "enhanced Nussinov"-model a useful prior in the parameter optimization for the full model. Consider, for example, canonical 2 × 2 stacks, where one pair is of type GC, cWW style and the other pair is of type XY, eWW. In the Turner-2004 model, energy contributions range from \(-1.5\) to \(-3.4\) kcal/mol, while the base-pair contribution for the GC, eWW pair is \(-1.36\) kcal/mol in the optimized "enhanced Nussinov"-model. Depending on the second pair, we observe discrepancies of \( \approx 0.5 \) when comparing the sum of individual pair energies to the total stacking energy. This level of agreement is expected and suggests that it makes sense in later iterations of parameter estimation to constrain features to tighter intervals than the current setting of \( |x| \leq 5 \).

### 5 RESULTS AND DISCUSSION

We compared our enhanced Nussinov algorithm to three state-of-the-art thermodynamic folding algorithms (RNAfold (Hofacker et al., 1994), UNAFold (Markham and Zuker, 2008), and RNAstructure (Reuter and Mathews, 2010)) to assess the prediction quality of our model. We folded a subset of 550 randomly chosen structures from RNAstrad (Andronescu et al., 2008) and compared the F-measure of our results with those of the other programs. The results in Fig. 4(top) show that, not unexpectedly, the "enhanced Nussinov" algorithm cannot compete with state-of-the-art tools due to its simplified energy model.
Fig. 4. Top: Histogram of F-measures for different folding algorithms, given 550 random RNAstrand entries. Bottom: F-measures, given 155 PDB entries from the RNAstrand, which are a subset of the 550 random RNAstrand entries.

Interestingly, once we focused on data gathered from the PDB database (Fig. 4(bottom)), the results showed a remarkable improvement. This could suggest that the PDB structures used for training do not sufficiently cover the RNA structure space and that additional RNAs (for which only secondary structure information is available) should be included in the training.

Because of the large number of base pair types, the “enhanced Nussinov-algorithm”, has to perform more work than classical secondary structure prediction programs when filling the dynamic programming matrices. This is reflected by rather high runtimes (25s for 100nt, 110s for 200nt). However, the asymptotic time complexity is still in $O(n^3)$.

A constrained folding variant of the “enhanced-Nussinov” algorithm can be used, for example, to predict non-canonical basepairs in large interior loops of structures. As an example, Fig. 5, shows that Segfold is able to correctly predict the non-canonical basepairs in a situation where the canonical base pair bases are already given, i.e., where the input consists of both the sequence and a dot-bracket string representing canonical Watson-Crick base pairs. Only the zig-zag motif (upper part of the interior loop) was not predicted, presumably due to the large penalty of +3.89 for each of the two 1x2 stacks.

Fig. 5. Prediction of non-canonical base pairs with Segfold. Left: Known structure of PDB entry 1dul. Right: Constrained prediction (canonical basepairs were given) of 1dul. Only the central part of the structure is shown. The outer part of the stem contains only canonical base pairs and is not shown.

6 CONCLUSION

Large experimentally verified RNA structures contain a sizeable number of non-canonical base pairs (Stombaugh et al., 2009). However, only a few RNA folding programs predict non-canonical pairs (Do et al., 2006; Parisien and Major, 2008). With the exception of MC-Fold, the pair families are not explicitly taken into account. Here, we have shown that the prediction of non-canonical pairs together with the corresponding pair families and their possible interactions in base triples is feasible by efficient dynamic programming approaches. Although direct thermodynamic measurements are not available to cover all aspects of such an extended and refined model of RNA structures, meaningful parameter sets can nevertheless be constructed. To this end, the information of the thermodynamic measurements is combined with a feature analysis of 3D structures using one of several approaches to large-scale parameter optimization. The extended combinatorial model, which in essence covers the Leontis-Westhof representations (LW) of RNA structures, allows a much more detailed modelling of the intrinsic structures in particular of hairpins, interior loops, and bulges.

We emphasize that our contribution does not yet provide a full-fledged loop-based LW-style energy model. In essence, we still lack an implementation for the full model of multi-loops. As the example of Fig. 5 suggests, interactions of adjacent loops as in the MC-Fold model may also be required to obtain satisfactory prediction accuracies for practical applications. Due to the computational cost it will also make sense to investigate the trade-off between further refinements of the model and speed-ups resulting from additive approximations. Another facet that naturally should be taken into account is co-axial stacking, in particular in the context of multi-loops (Tyagi and Mathews, 2007). We have demonstrated here that the goal of an accurate, practically applicable folding algorithm for LW-structures is meaningful and reachable: The
work of Parisien and Major (2008) shows that major improvements of prediction accuracy can be obtained by employing LW-based folding algorithms. Although Segfold does not yet reach the desired levels of accuracy, it allows us to explore the missing components of the energy model in a systematic manner, and it demonstrates that this can be achieved without leaving the realm of fast, efficient, and exact dynamic programming approaches. The next step, therefore, is a toolkit for optimizing parameters in the full loop-based model.

An interesting possibility for further extensions of the model is the explicit incorporation of recurring RNA structural motifs with non-canonical pairs, such as Kink-Turns (Klein et al., 2001), into the grammar and the energy model. This may be particularly useful in those cases where motifs are not crossing-free and hence would require a pseudoknot version of the folding algorithm. While the inclusion of various types of pseudoknots is conceptually not more difficult than for ordinary secondary structures, the parameterization of such models will be even more plagued by the lack of training data in the LW framework.

The folding algorithm introduced here, furthermore, sets the stage for a complete suite of bioinformatics tools for LW structures. Simple extension can cover the co-folding of two or more RNAs along the lines of (Dimitrov and Zuker, 2004; Bernhart et al., 2006; Dirks et al., 2007). Consensus structures can be predicted from given sequence alignments using the same recursions. As in RNAalifold (Bernhart et al., 2008), it suffices to re-define the energy parameters for alignment columns instead of individual nucleotides. Instead of RIBOSUM-like scores as measures of conservation (Klein and Eddy, 2003), one naturally would employ the isostericity rules for the individual base pair types (Leontis et al., 2002; Lescoute et al., 2005). Inverse folding algorithms (Hofacker et al., 1994; Andronescu et al., 2004; Busch and Backofen, 2006) design RNA sequences that fold into prescribed structures by iteratively modifying and folding sequences to optimize their fit to substructures of the target. This strategy can immediately be generalized to LW structures; in fact, it is just as easy to replace secondary structure folding by LW-style folding. Combining the algorithmic ideas of this contribution with the Sankoff-style alignment approach of Zhong et al. (2010) and the progressive multiple alignment scheme of mlocarna (Will et al., 2007) directly leads to an LW-variant of structural alignment algorithms.

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APPENDIX

A Pairfamily-Aware Grammar

Here we discuss in some more detail how the base pair types affect the grammar and, hence, the folding algorithm. We start from Fig. 2 and the corresponding recursion in eqn.(3.1). Each base pair is now colored by its LW family. In particular, therefore, base pairs have type-dependent energy contributions $\epsilon_{ij}[\theta]$ for pairs not involved in base triples and energy contributions depending on the type of the pair and on the type of the incident pairs: $\epsilon_i^{\theta}(i,j)$ if the 5' nucleotide i is a triplet, $\epsilon_i^{\theta}(i,j)$ if the 3' nucleotide i is a triplet, and $\epsilon_i^{\theta}(i,j)$ if both nucleotides are triplets. Similarly, therefore, non-terminals delimited by triplets must be colored by the base pair types to allow the evaluation of the energy of the enclosing base pair. In the simplest case, as implemented in Segfold, we may assume that $\epsilon_i^\theta$ only depends on the pair type $\theta$ for permitted combinations of pair types and is $+\infty$ otherwise. With explicit representation of the pair family types, eqn.(3.1) becomes

$$ F_{ij} = \min_{i \leq k < j} \left\{ F_{i+1,j}, C_{ij}, U_{ij}, V_{ij}, W_{ij} \right\} $$

where $F_{ij}$ is a matrix where

$$ F_{ij}^{ij} = \min_{\theta, \psi} \left( \begin{array}{c} F_{i+1,j-1} + \min_{\phi} \{ U_{i,j-1}[\theta] + c_i^{\theta}(i,j) \} \\ V_{i+1,j}^{ij} + \min_{\phi} \{ V_{i,j}[\theta] + c_i^{\theta}(i,j) \} \\ W_{i+1,j}^{ij} + \min_{\phi} \{ W_{i,j}[\theta] + c_i^{\theta}(i,j) \} \end{array} \right) $$

which are obtained by carrying out the optimization over the combinations of base pairing types at all triples.

The non-terminal $C_{ij}$, designating a structure enclosed by an ordinary base pair remains unchanged since the minimization $C_{ij} = F_{i+1,j-1} + \min_{\theta} \epsilon_{ij}[\theta]$ can be carried out in the simplified energy model. The triplet-terms however, are now conditioned on the pair type $\theta$.

$$ W_{ij}^{\theta}[\theta, \psi] = \min_{\phi} \{ W_{i,j}[\theta, \phi] + c_i^{\theta}(i,j) \} $$

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