Capacity Bounds and User Identification Costs in Rayleigh-Fading Many-Access Channel

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Abstract—Many-access channel (MnAC) model allows the number of users in the system and the number of active users to scale as a function of the blocklength and as such is suited for dynamic communication systems with massive number of users such as the Internet of Things. Existing MnAC models assume a priori knowledge of channel gains which is impractical since acquiring Channel State Information (CSI) for massive number of users can overwhelm the available radio resources. This paper incorporates Rayleigh fading effects to the MnAC model and derives an upper bound on the symmetric message-length capacity of the Rayleigh-fading Gaussian MnAC. Furthermore, a lower bound on the minimum number of channel uses for discovering the active users is established. In addition, the performance of Noisy-Combinatorial Orthogonal Matching Pursuit (N-COMP) based group testing (GT) is studied as a practical strategy for active device discovery. Simulations show that, for a given SNR, as the number of users increase, the required number of channel uses for N-COMP GT scales approximately the same way as the lower bound on minimum user identification cost. Moreover, in the low SNR regime, for sufficiently large population sizes, the number of channel uses required by N-COMP GT was observed to be within a factor of two of the lower bound when the expected number of active users scales sub-linearly with the total population size.

Index Terms—Many-Access channel, Group testing, Active device discovery, multiple-access, Rayleigh-fading

I. INTRODUCTION

Recent advances in the Internet of Things (IoT) have lead to envisioning an enormous network of smart devices supporting applications in a wide range of sectors including smart health, industrial automation, smart power systems, etc. These massive networks are often composed of devices with sparse and sporadic activities. Furthermore, the number of devices that require the channel access can naturally scale as a function of the blocklength [1]. However, classical multi-user information theory [2] assumes a fixed set of users, typically small in number and thus renders itself inadequate for modeling the dynamic nature of massive wireless networks.

Recently, Chen et.al [3] proposed a novel multiple-access channel model referred to as many-access channel (MnAc) for systems with many transmitters and a single receiver in which the number of transmitters grows with the blocklength $n$. The paper introduced the notion of ‘message-length capacity’ for a Gaussian MnAc defined as the total number of information bits reliably transmitted in $n$ channel uses. While [3] assumes knowledge of each user’s channel gain in advance, in a massive wireless communication system, it is often infeasible to acquire the exact Channel State Information (CSI) a priori at the receiver owing to a large number of transmitters.

In this paper, we consider a fading-MnAc where each user experiences a Rayleigh fading channel whose gain is unknown a priori to the base station. We derive an upper bound on the message-length capacity and characterize the minimum active user identification cost defined as the minimum number of channel uses to identify the active devices such that the probability of misdetection or false alarms vanishes as the number of users increase asymptotically. We also investigate the performance gap incurred by an on-off keying based group testing (GT) approach for active device discovery in a Rayleigh-fading AWGN channel.

GT has been previously studied in the context of active device discovery in massive access when there is no noise [4], [5]. In [6], authors consider several noisy GT scenarios with additive noise as well as dilution noise models. However, these models render themselves insufficient for the Rayleigh fading MnAc we consider in this paper. A related but different problem of neighbor identification is studied in [2] under Rayleigh fading assumption for finite-user many-access.

In the GT based active device discovery we propose, each device is assigned a binary signature. During each channel use, devices with a “1” at their corresponding index in the signature transmit an ‘ON’ signal while the others remain silent. The GT based scheme only requires non-coherent energy detection at the receiver. Moreover, GT is known to be efficient in sparse vector recovery applications [8] which is the case in IoT environments with sparse and sporadic user activities. We derive closed-form expressions for upper bounds on probability of false alarm and misdetection when Noisy-Combinatorial Orthogonal Matching Pursuit based GT (N-COMP GT) is used for active device discovery.

The remainder of this paper is organized as follows. In Section II, we present the system model for Rayleigh fading MnAc. Bounds on message-length capacity and minimum user identification cost for this channel model are established in Section III. In Section IV, we describe active device discovery using GT and derive relevant bounds on probability of misdetection and false alarm for a GT based active device discovery scheme in Rayleigh fading MnAc. Section V compares the performance of GT based active device discovery with the lower bound on minimum user identification cost. Finally, we conclude our paper in Section VI.

II. SYSTEM MODEL

In [3], Chen et al. studied the symmetric message length capacity of Gaussian many-access channel without fading
where the number of users $\ell_n$ is tied to block length $n$. Here, we extend the framework to a Rayleigh fading setting. During each channel use, any user can be independently active with probability $\alpha_n$. We use $k_n = \alpha_n \ell_n$ to denote the expected number of active users. When active, each user transmits a message from its message set of cardinality $M$. The received symbols over $n$ channel uses is given by,

$$ y = \tilde{S} \tilde{H} \tilde{x} + \tilde{w} $$

(1)

where, $H = \begin{pmatrix} h_1 I_M & 0 & 0 \\ 0 & \ldots & 0 \\ 0 & 0 & h_1 I_M \end{pmatrix} \in C^{M \times n \times M \times n}$.

The $i^{th}$ diagonal block of $H$ has a value $h_i$ along its diagonal representing the channel coefficient of user $i$. We assume that $h_i$'s are i.i.d with distribution $\mathcal{CN}(0, \sigma^2)$ and unknown a priori. Each column of the matrix $\tilde{S} \in C^{n \times M \times n}$ represents the $n$-length codeword corresponding to each of the $M$ non-zero messages of the $\ell_n$ users. The codewords associated with each user satisfy the power constraint $\frac{1}{n} \sum_{i=1}^{\ell_n} s_{ji}^2 \leq P, \forall j \in \{1, 2, \ldots, \ell_n\}$. $w = [w_1, \ldots, w_{\ell_n}] \in C^{n \times 1}$ is a vector of independent circularly symmetric complex Gaussian noise with distribution $\mathcal{CN}(0, \sigma_w^2)$. For each active user, SNR per symbol ($\rho$) is defined as $\rho := \frac{P}{\sigma_w^2}$. In addition, $x$ represents whether a user is active and which one of the $M$ codewords is transmitted by the active users.

$$ x = \begin{bmatrix} [x_1]_{1 \times M} & \ldots & [x_{\ell_n}]_{1 \times M} \end{bmatrix}^T $$

(2)

where $\forall k \in \{1, 2, \ldots, \ell_n\}$, we have the following:

$$ [x_k]_{1 \times M} = \begin{cases} 0_{(1 \times M)} & \text{w.p. } 1 - \alpha_n \\ e_{m(k)_{1 \times M}} & \text{w.p. } \frac{\alpha_n}{1 - \alpha_n}, \forall m \in \{1, \ldots, M\} \end{cases} $$

(3)

Therefore, the entropy of $[x_k]_{1 \times M}$ in nats is

$$ H(x) = \ell_n H_2(\alpha_n) + \alpha_n \ln M. $$

(4)

where $H_2(.)$ denotes the binary entropy. For the MnAC channel in (6), as defined in (3), a positive non-decreasing function $B(n)$ of blocklength $n$ is said to be a symmetric message-length capacity if, for any $0 < \epsilon < 1$, there exists a sequence of $\{\exp((1 - \epsilon)B(n)), n\}$ codes such that the probability $P(\hat{x} \neq x)$ vanishes as $n \to \infty$. Moreover, $(1 + \epsilon)B(n)$ needs to be non-achievable asymptotically.

While analyzing the user identification costs, we consider $\ell$ users (instead of $\ell_n$) and let other parameters depend on $\ell$, i.e., we use $k_\ell$ and $\alpha_\ell$ instead of $k_n$ and $\alpha_n$ respectively. The binary vector $b = [b_1, b_2, \ldots, b_\ell]^T \in \{0, 1\}^{\ell \times 1}$ is used to represent the activity vector, i.e., $b_i \sim Bern(\alpha_\ell), \forall i \in \{1, 2, \ldots, \ell\}$. As defined in (3), the minimum user identification cost is said to be $n(\ell)$ if there exists a signature code of length $n_0 = (1 + \epsilon)n(\ell)$ such that the probability of erroneous identification vanishes as $\ell \to \infty$, whereas the error probability is strictly bounded away from zero if $n_0 = (1 - \epsilon)n(\ell)$.

Our aim is to understand how $B(n)$ or equivalently $\ln M$ scales in the asymptotic regime of $n$ such that the transmitted codewords are successfully decoded at the receiver. Moreover, we are interested in characterizing the minimum user identification cost associated with the Rayleigh fading MnAC.

### III. BOUNDS TO THE MESSAGE-LENGTH CAPACITY AND MINIMUM USER IDENTIFICATION COST

We start by finding an upper bound to the message-length capacity of Rayleigh fading MnAc.

**Theorem 1:** For a user set of cardinality $\ell_n$ where each user is active independently with probability $\alpha_n$, assuming $\alpha_n$ and $\ell_n$ scale such that $\ell_n e^{-\delta_0 \alpha_n \ln \sigma} \to 0$, $\forall \delta_0 > 0$, the message-length capacity of a Rayleigh-fading MnAC is upper bounded as

$$ \ln M \leq nC_{su}(\rho) - \frac{H_2(\alpha_n)}{\alpha_n} $$

(5)

where $\rho = \frac{P}{\sigma_w^2}$ and $C_{su}(\rho)$ is the non-coherency capacity of single user Rayleigh fading channel.

**Proof:** Let $C_{su}(\rho)$ denote the non-coherency capacity of a single user Rayleigh fading channel at SNR $\rho = \frac{P}{\sigma_w^2}$. Then, using cut-set upper bound, the mutual information between $x$ and $y$ can be bounded as:

$$ I(x; y) \leq n k_n C_{su}(\rho). $$

(6)

Next, we use the upper bound on $H(x \mid y)$ derived in (3). The key arguments are presented below.

Define $B_n(\delta, k) = \{x \in \mathcal{X}_n^k : 1 \leq \|x\|_0 \leq (1 + \delta)k\}$ for every $\delta \in (0, 1)$. Since $x$ is a binary vector with expected support size of $k_n$, the set $B_n^d(\delta, k_n)$ has high probability for large $n$. Let $E = 1\{\hat{x} \neq x\}$ indicate the error event, where $\hat{x}$ is the estimation of $x$ at the receiver. Thus, as established in (3), we can write

$$ H(x \mid y) \leq 2 \ln 2 + H(x \mid E, 1\{x \in B_n^d(\delta, k_n)\} \cup y). $$

(7)

Furthermore, if $\ell_n e^{-\delta k_n} \to 0$, then for large values of $n$, $H(x \mid E, 1\{x \in B_n^d(\delta, k_n)\} \cup y) \leq 4P_e^d(n)M + k_n + \ell_n H_2(\alpha_n) + \ln M. $

(8)

Where $P_e^d := P(\hat{x} \neq x)$ is the average probability of error. Thus,

$$ H(x \mid y) \leq 4P_e^d(n)M + k_n + \ell_n H_2(\alpha_n) + \ln 4M. $$

(9)

Using (6) and (8) in $H(x) = H(x \mid y) + I(x; y)$, we get

$$ \left(1 - 4P_e^d(n)\right) \ln M - 4P_e^d(n) \ln M + \left(1 - 4P_e^d(n)\right) \frac{H_2(\alpha_n)}{\alpha_n} \leq nC_{su}(\rho) + \frac{\ln 4}{k_n} + 4P_e^d(n). $$

(10)

As $k_n \to \infty$, we have

$$ \lim_{k_n \to \infty} \left(1 - 4P_e^d(n)\right) \ln M + \frac{H_2(\alpha_n)}{\alpha_n} \leq nC_{su}(\rho) + \delta + 4P_e^d(n). $$

(11)

for any arbitrarily small $\delta > 0$. Since $P_e^d(n)$ vanishes as $k_n \to \infty$, we have,

$$ \ln M + \frac{H_2(\alpha_n)}{\alpha_n} \leq (1 + \epsilon) nC_{su}(\rho) $$

(12)

Note that, for SNR values less than $10^{-2}$, it has been proven in (9) that the capacity of a single user Rayleigh fading channel without CSI is approximately given by
\( C_{su}(\rho) = \rho - \frac{\rho \ln (1 + x_1^2)}{x_1^2} - \pi \rho \csc \left( \frac{\pi}{x_1^2 + x_1} \right) \frac{1}{1 + x_1^2} \) \tag{13}

where \( x_1 \) is obtained by solving

\[ x_1^2 - (1 + x_1^2) \ln (1 + x_1^2) - \pi \left( \frac{\rho}{x_1^2 + x_1} \right) + 1 + x_1^2 - \pi \csc \left( \frac{\pi}{x_1^2} \right) + \ln \left( \frac{\rho}{x_1^2 + x_1} \right) = 0 \]  \tag{14}

Fig. 1: Upper bound on Symmetric message-length capacity of Rayleigh-fading AWGN MnAc at SNR \( 10^{-7} \). The average number of active users is assumed to be \( k_n = \sqrt{\tau_n} \).

Now, we will characterize the minimum cost of user identification in terms of the number of channel uses required.

**Theorem 2:** For a user set of cardinality \( \ell \) where each user is active independently with probability \( \alpha_\ell \), assuming \( \alpha_\ell \) and \( \ell \) scale such that \( \ell e^{-d_{\alpha_\ell}} \rightarrow 0 \), \( \forall d > 0 \), the number of channel uses \( (n(\ell)) \) required to identify the active users is lower bounded as

\[ n(\ell) \geq \frac{H_2(\alpha_\ell)}{\alpha_\ell C_{su}(\rho)} \]  \tag{15}

A. **Model for GT**

A signature matrix \( S \) is defined as a binary matrix formed by a set of \( n \)-coordinate binary signatures, \( z \in \{0,1\}^n \) where, \( i \in \{1,2,\ldots,\ell\} \), i.e.,

\[ S = \{s_1,\ldots,s_\ell\} \in \{0,1\}^{n \times \ell} \]  \tag{16}

Each entry of the signature \( s_{ij} := s_i(j) \) takes the value 1 with probability \( p \) independent of the other entries in the signature matrix indicating if the \( i^{th} \) user is a part of the \( j^{th} \) channel use. Otherwise, it takes a value 0. Note that we use \( p = \frac{1}{k_{\ell+1}} \), the optimality of which is discussed in [9].

In the active device discovery phase, users employ on-off keying to transmit the signatures in \( S \) in a time synchronized manner. During each channel use, the received signal is a superposition of the pulses transmitted by multiple active users with a 1 at the corresponding indices in their signatures. Thus, over \( n \) channel uses, the received vector \( y = \sqrt{P} \sum_{j=1}^{\ell} h_j b_j s_j + w \) where the noise vector \( (w) \), channel gains \( (h) \) and power constraint \( (P) \) are as defined in Section II. We have a non-coherent energy detector which makes a binary decision indicating the presence of energy in the received signal. Note that energy detection does not require any CSI. These decisions are represented by a binary vector \( \hat{y} = [\hat{y}_1, \hat{y}_2, \ldots, \hat{y}_n] \). The decisions are formed by setting \( \hat{y}_i \) to 1 if the received energy, \( E_r = |y_i|^2 \) during the \( i^{th} \) channel use exceeds a threshold \( \tau^2 \) determined using an appropriate probability of error criterion. During the active device discovery phase, our aim is to find an estimate of the activity vector \( \hat{b} = [\hat{b}_1, \hat{b}_2, \ldots, \hat{b}_\ell] \) using \( \hat{y} \) with a minimum number of channel uses such that \( \lim_{\ell \to \infty} \mathbb{P}(\hat{b} \neq \hat{b}) = 0 \). This can be thought of as a GT problem, with each channel use corresponding to a group test [4].

**B. Decoding strategy for GT Rayleigh-Fading MnAc**

In our analysis, we adapt the N-COMP decoding strategy proposed by Chan et al. [10] to the non-coherent fading channel. In [10], the authors assume a binary symmetric noise model where false negatives and false positives occur with the same probability which is not the case in an AWGN channel with Rayleigh fading.

Let \( q_1 \) denote the probability that during a channel use, the received energy is below the threshold \( \tau^2 \) conditioned on the event that there is at least one active user which is a part of the channel use. Mathematically, for an arbitrary channel use index \( i \in \{1,2,\ldots,n\} \),

\[ q_1 = \mathbb{P}(E_r < \tau^2 | \sum_{j=1}^{\ell} b_j s_j(i) > 0) \]  \tag{17}

Assuming, w.l.o.g. that the \( m^{th} \) user is active and is a part of the \( i^{th} \) channel use, we can rewrite \( q_1 \) in (17) as

\[ q_1 = \mathbb{P} \left( |\sqrt{P}h_m + \sqrt{P} \sum_{j=1, j \neq m}^{\ell} S_{ij} h_j b_j + W_i| \leq \tau \right) \]  \tag{18}

for any channel use \( i \in \{1,2,\ldots,n\} \).

Define \( Z = |\sqrt{P}h_m + \sqrt{P} \sum_{j=1, j \neq m}^{\ell} S_{ij} h_j b_j + W_i| \) and \( Q \sim \text{Bin}(\ell - 1, p_{\alpha_\ell}) \). Here, \( Q \) denotes the number of active users included in the \( i^{th} \) channel use other than the \( m^{th} \) user.
Thus, \( q_1 \) becomes

\[
q_1 = \sum_{g=0}^{\ell-1} P(Q = g) P\left( |Z| \leq \tau |Q = g \right).
\]  (19)

Note that conditioned on \( Q = g \), \( Z \) is distributed as \( \mathcal{CN}(0, \sigma^2 P(1+g) + \sigma_w^2) \). Thus, conditioned on \( Q = g \), \( |Z| \) follows Rayleigh distribution given by

\[
P\left( |Z| \leq \tau |Q = g \right) = 1 - \exp\left( -\frac{\tau^2}{\sigma^2 P(1+g) + \sigma_w^2} \right). \]  (20)

Combining (20) and (19), we can write

\[
q_1 = 1 - \sum_{g=0}^{\ell-1} P(Q = g) \exp\left( -\frac{\tau^2}{\sigma^2 P(1+g) + \sigma_w^2} \right) 
\geq 1 - \exp\left( -\frac{\tau^2 / \sigma_w^2}{(p_{\alpha \ell}(\ell-1)+1)\rho + 1} \right) = q_{1LB}. \]  (21)

In (21), we used Jensen’s inequality to lower-bound \( q_1 \) since the RHS in (21) is a convex function assuming its threshold, \( \tau^2 \) used in the energy detector obeys \( \sigma^2 P + \sigma_w^2 \geq \tau^2 / 2 \).

Similarly, let \( q_2 \) denote the probability that during the \( i^{th} \) channel use the received energy above the threshold \( \tau \) for any \( i \in \{1, 2, \ldots, n\} \) conditioned on the event that there is at least one inactive user. W.l.o.g. assume that the \( m^{th} \) user is inactive. Define \( \hat{Z} = \sqrt{P} \sum_{j=1,j \neq m} S_{ij} J_{ij} + w_i \) and \( Q \sim Bin(\ell-1, p\alpha \ell) \). Conditioned on \( Q = g \), \( \hat{Z} \) is distributed as \( \mathcal{CN}(0, \sigma^2 P g + \sigma_w^2) \). Thus, similar to (21), we can write

\[
q_2 = \sum_{g=0}^{\ell-1} P(Q = g) P\left(|\hat{Z}| \geq \tau |Q = g \right) \leq \exp\left( -\frac{\tau^2 / \sigma_w^2}{(p_{\alpha \ell}(\ell-1)+1)\rho + 1} \right) = q_{2LB}. \]  (22)

With N-COMP based GT, a device is declared as active, if the fraction of channel uses in which the received energy exceeds the predefined threshold is above its expected value. Precisely, let \( N_\ell = \sum_{i=1}^{n} s_\ell(i) \) denote the number of channel uses in the user \( \ell \) is included and \( S_\ell = \sum_{i=1}^{n} s_\ell(i) \hat{y}_i \) denote the number of these channel uses in which \( \hat{y}_i = 1 \). The decision rule for N-COMP [10] decoder can be written as:

\[
\text{user } \ell \text{ is active } \iff S_\ell \geq 1 - q_1(1+\Delta) \]  (23)

for a specified \( \Delta > 0 \) optimally chosen based on an appropriate probability of error criterion.

C. Probability of misdetection (\( P_{MD} \))

Consider a set of indicator random variables corresponding to a misdetection event. Specifically, \( \hat{y} \in \{1, 2, \ldots, \ell\} \),

\[
E_{miss}^j = \begin{cases} 1, & \text{if } \hat{b}_j = 0 \text{ or } \{b_j = 1\} \\ 0, & \text{otherwise} \end{cases}
\]  (24)

The probability of misdetection, \( P_{MD} \) can be expressed as

\[
P_{MD} = \mathbb{P}\left( \bigcup_{j=1}^{\ell} E_{miss}^j = 1 \right) \leq \sum_{j=1}^{\ell} \mathbb{P}(b_j = 0) \mathbb{P}(\hat{b}_j = 0 | b_j = 1)
\]  (25)

Now, using (23) and (25), \( P_{MD} \) can be bounded as:

\[
P_{MD} \leq \alpha_\ell \sum_{j=1}^{\ell} \mathbb{P}(N_j = r) \mathbb{P}(S_j < r(1-q_1(1+\Delta))).
\]  (26)

Using binomial distribution, (26) can be simplified to get

\[
P_{MD} \leq \alpha_\ell \sum_{r=0}^{\ell} \binom{n}{r} (1-p)^{n-r} \sum_{u=r}^{n} \binom{r}{u} q_1^{u}(1-q_1)^{r-u}
\]  (27)

where \( r' = r q_1(1+\Delta) \).

For a random variable \( X \sim Bin(n, q_1) \), using Chernoff bound, we have the following inequality:

\[
P(X \geq u) = \sum_{r=u}^{n} \binom{n}{r} q_1^{u}(1-q_1)^{r-u} \leq e^{-2q_1^2 \Delta^2}.
\]  (28)

Using (21) and (28) in (27) and applying binomial theorem, we get

\[
P_{MD} \leq \alpha_\ell \left( \frac{1}{1 + p - e^{-2q_1^2 \Delta^2}} \right)^n.
\]  (29)

This result is summarized in the following theorem:

Theorem 3: For a user set of cardinality \( \ell \) where each user can be active independently with probability \( p_\ell \), the probability of misdetection while using N-COMP GT across \( n \) channel uses for discovering active users in a Rayleigh fading MnAc with \( \rho \) as SNR per user is upper bounded as

\[
P_{MD} \leq \frac{p_{\alpha \ell}}{1 - \frac{1}{\alpha_\ell} \log\left(\frac{1}{1 - p_\ell}\right) \frac{1}{\ln(1/\alpha_\ell)}} \times \left( 1 + \frac{\ln(2)}{\ln(1/\alpha_\ell)} - 1 \right)
\]  (30)

where \( \beta_1 \geq \frac{1}{\alpha_\ell} \frac{1}{\rho(1-p_\ell)^2} \log\left(\frac{1}{1 - p_\ell}\right) \) and \( q_{1LB} \) is given in (21).

Corollary 1: The number of channel uses required so that the probability of misdetection will be less than \( \epsilon \) is given by

\[
n_1 = \beta_1 \times H_{2}(\alpha) \]  (31)

D. Probability of false positive (\( P_{FP} \))

We can compute the probability of false positive as follows:

\[
P_{FP} \leq \sum_{j=1}^{\ell} P(b_j = 0) P\left( \hat{b}_j = 1 | b_j = 0 \right) = (1 - \alpha_\ell) \ell \sum_{r=0}^{n} P(N_j = r) \mathbb{P}(S_j \geq r(1-q_1(1+\Delta)))
\]  (32)

where \( P(N_j = r) = \binom{n}{r} (1-p)^{n-r} \) and \( r'' = r(1-q_1(1+\Delta)) \).

For \( X \sim Bin(n, p_\ell) \), if \( m < n/2 \), then as established in [11] the distribution function can be lower bounded as

\[
P(X \leq m) \geq \frac{\exp(-nD(m/n|p_\ell))}{\sigma \sqrt{2\pi}}
\]  (33)

where \( D(\cdot) \) is the KL-Divergence between the distributions \( Bern(p_\ell) \) and \( Bern(m/n) \). Thus, we can write the following:

\[
\sum_{u=r(1-q_1(1+\Delta))}^{n} \binom{r}{u} q_2^{u}(1-q_2)^{r-u} \leq 1 - \frac{e^{-rD(q_2-q_1(1+\Delta))}}{\sqrt{2\pi r q_1 q_2}}
\]  (34)

Using (33) in (31) and invoking Binomial theorem, we get
Now, assuming $n_2 = \beta_2 \times \frac{H_2(\alpha_2)}{\alpha_2}$, we have the following results:

**Theorem 4:** For a user set of cardinality $\ell$ where each user can be active independently with probability $\alpha_2$, the probability of false alarm while using N-COMP GT across $n$ channel uses for discovering active users in a Rayleigh fading MnAc with $\rho$ as SNR per user is upper bounded as

$$P_{FP} \leq \ell(1 - \alpha_2) \left(1 - e^{-\beta_2 \log(\eta)} p(1-\eta)\right)$$

(35)

where $\eta = \exp\left(-\frac{D(q_2 - q_1) || q_2)}{\sqrt{2\log(q_2)}}\right)$ and $p = \frac{\eta}{1-\eta}$. Here $D(.)$ computes the KL-Divergence between two Bernoulli distributions. $q_1$ and $q_2$ are bounded as in (21) and (22).

**Corollary 2:** The number of channel uses required so that $P_{FP}$ will be less than $\ell^{-\delta}$ is given by $n_2 = \beta_2 \times \frac{H_2(\alpha_2)}{\alpha_2}$ where $\beta_2 \geq \frac{1}{\log(1/\alpha_2)} \log \left(\frac{1}{1-\alpha_2}\right)^{\ell+1}$.

V. COMPARISON OF N-COMP GT AND THE LOWER BOUND ON MINIMUM USER IDENTIFICATION COST

In this section, through numerical simulations, we compare the performance of N-COMP GT (in terms of number of channel uses required to have predetermined probability of misdetection and false positive) with the minimum user identification cost established in Theorem 2. Though our analysis is valid for general SNR values, in our simulations, we focus on the low-SNR regime since a numerically tractable characterization of the capacity of a single user Rayleigh fading channel without CSI is available as given in (13) for the low-SNR regime. Our analysis can be translated to arbitrary SNRs by using the non-coherent capacity expression appropriate for the SNR considered. Also note that the low-SNR results presented here are indeed a lower bound for the high SNR scenarios.

![Fig. 2: Percentage increase in channel use as a function of $\ell$ at SNR = 10^{-4}](image)

The average number of active users is assumed to be $k_\ell = \sqrt{\ell}$. For the probability of misdetection and probability of false alarm to be less than $\ell^{-\delta}$, the required minimum number of channel uses for N-COMP GT is

$$n_{GT} = \max\{\beta_1, \beta_2\} \times \ell H_2(\alpha_2)$$

(36)

where $\beta_1$ and $\beta_2$ are lower bounded in Corollary 1 and Corollary 2 respectively. Thus, the fractional increase in the number of channel uses N-COMP GT requires w.r.t the minimum user identification cost established in Theorem 2 is given by

$$G = \frac{n_{GT} - n_0}{n_0} = \max\{\beta_1, \beta_2\} \times k_\ell C_{su} \left(\frac{P \sigma^2}{\sigma_w^2}\right) - 1.$$  

(37)

In our numerical analysis, we used the decision rule for N-COMP as in (26) with $\Delta = 0.05$ and $p = \frac{1}{k_\ell+1}$. Moreover, we numerically optimized $\tau$ under the constraint $\sigma^2 + \sigma_w^2 \geq \tau^2/2$ through exhaustive search while simulating (36).

VI. CONCLUSION AND DISCUSSION

In this paper, we have derived an upper bound on the message-length capacity of a Gaussian many-access channel with Rayleigh Fading assuming no CSI at the receiver. Moreover, we have characterized a lower bound on the minimum number of channel uses required during active device discovery phase. In addition, we have investigated the performance gap incurred by a N-COMP based GT scheme for active device discovery. Through numerical simulations, it has been verified that in the low SNR regimes, the excess channel uses N-COMP requires is not too far from the lower bound. Thus, in a practical IoT setting, if the number of excess channel uses required does not overburden the system resources, our proposed N-COMP based GT strategy can be useful since it is based on a simple non-coherent energy detection which requires no CSI. Our study can be easily extended to general
SNR values by using appropriate expressions for the non-coherent capacity. As a future work, it might be interesting to study how other decoding algorithms for GT can further reduce the performance gap.

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