DERIVATION OF LINEARISED POLYCRYSTALS FROM A 2D SYSTEM OF EDGE DISLOCATIONS

SILVIO FANZON, MARIAPIA PALOMBARO, AND MARCELLO PONSIGLIONE

ABSTRACT. In this paper we show the emergence of polycrystalline structures as a result of elastic energy minimisation. For this purpose, we introduce a variational model for two-dimensional systems of edge dislocations, within the so-called core radius approach, and we derive the $\Gamma$-limit of the elastic energy functional as the lattice space tends to zero.

In the energy regime under investigation, the symmetric and skew part of the strain become decoupled in the limit, the dislocation measure being the curl of the skew part of the strain. The limit energy is given by the sum of a plastic term, acting on the dislocation density, and an elastic term, which depends on the symmetric strains. Minimisers under suitable boundary conditions are piecewise constant antisymmetric strain fields, representing in our model a polycrystal whose grains are mutually rotated by infinitesimal angles.

Keywords: Geometric rigidity, Linearization, Polycrystals, Dislocations, Variational methods.

2000 Mathematics Subject Classification: 74B15, 74N05, 74N15, 49J45.

CONTENTS

1. Introduction 2
2. Setting of the problem 8
3. Preliminaries 10
3.1. Cell formula for the self-energy 10
3.2. Korn type inequality 12
3.3. Remarks on the distributional Curl 12
4. $\Gamma$-convergence analysis 13
4.1. Compactness 14
4.2. $\Gamma$-liminf inequality 17
4.3. $\Gamma$-limsup inequality 18
5. Relaxed Dirichlet-type boundary conditions 25
6. Linearised polycrystals as minimisers of the $\Gamma$-limit 28
7. Conclusions and perspectives 32
References 33
1. Introduction

Many solids in nature exhibit a polycrystalline structure. A single phase polycrystal is formed by many individual crystal grains, having the same underlying periodic atomic structure, but rotated with respect to each other. The region that separates two grains with different orientation is called grain boundary. Since the grains are mutually rotated, the periodic crystalline structure is disrupted at grain boundaries. As a consequence, grain boundaries are regions where dislocations occur, inducing high energy concentration.

Polycrystalline structures, which a priori may seem energetically not convenient, arise from the crystallisation of a melt. As the temperature decreases, crystallisation starts from a number of points within the melt. These single grains grow until they meet. Since their orientation is generally different, the grains are not able to arrange in a single crystal and grain boundaries appear as local minimizers of the energy, in fact as metastable configurations. After crystallisation there is a grain growth phase, when the solid tries to minimise the energy by reducing the boundary area. This process happens by atomic diffusion within the material, and it is thermally activated (see [12, Ch 5.7], [19]). On a mesoscopic scale a polycrystal resembles the structure in Figure 1.

Our purpose is to describe, and to some extent to predict, polycrystalline structures by variational principles. To this end, we first derive by $\Gamma$-convergence, as the lattice spacing tends to zero, a total energy functional depending on the strain and on the dislocation density. Then, we focus on the ground states of such energy, neglecting the fundamental mechanisms driving the formation and evolution of grain boundaries. The main feature of the model proposed in this paper is that grain boundaries and the corresponding grain orientations are not introduced as internal variables of the energy; in fact, they spontaneously arise as a result of the only energy minimisation under suitable boundary conditions.
Let us introduce our model by first discussing the case of two dimensional small angle tilt grain boundaries (from now on abbreviated to SATGB). The atomic structure of SATGBs is well understood (see, for example, [12, Ch 3.4], [17]). In fact, the lattice mismatch between two grains mutually tilted by a small angle $\theta$ is accommodated by a single array of edge dislocations at the grain boundary, evenly spaced at distance $\delta \approx \varepsilon/\theta$, where $\varepsilon$ represents the atomic lattice spacing. Therefore, the number of dislocations at a SATGB is of the order $\theta/\varepsilon$ (see Figure 2). The elastic energy of a SATGB is given by the celebrated Read-Shockley formula introduced in [17]

\begin{equation}
\text{Elastic Energy} = E_0 \theta (A + |\log \theta|),
\end{equation}

where $E_0$ and $A$ are positive constants depending only on the material. Recently Lauteri and Luckhaus in [14], starting from a nonlinear elastic energy, proved compactness properties and energy bounds in agreement with the Read-Shockley formula.

In this paper we focus on lower energy regimes, deriving by $\Gamma$-convergence, as the lattice spacing $\varepsilon \to 0$ and the number of dislocations $N_\varepsilon \to \infty$, a certain limit energy functional $\mathcal{F}$ that can be regarded as a linearised version of the Read-Shockley formula. We work in the setting of linearised planar elasticity as introduced in [10] and in particular...
we require good separation of the dislocation cores. Such good separation hypothesis will in turn imply that the number of dislocations at grain boundaries is of the order

\[ N_\varepsilon \ll \frac{\theta}{\varepsilon}. \]

As a consequence, we cannot allow a number of dislocations sufficient to accommodate small rotations \( \theta \) between grains, but rather we can have rotations by infinitesimal angles and the corresponding ground states can be seen as linearised polycrystals, whose energy is linear with respect to the number of dislocations at grain boundaries.

We now briefly introduce the setting of our problem following [10]. In linearised planar elasticity, the reference configuration is a bounded domain \( \Omega \subset \mathbb{R}^2 \), representing a horizontal section of an infinite cylindrical crystal \( \Omega \times \mathbb{R} \). A displacement is a regular map \( u : \Omega \to \mathbb{R}^2 \) and the stored energy density \( W : M^{2 \times 2} \to [0, +\infty) \) is defined by

\[ W(F) := \frac{1}{2} C F : F, \]

where \( C \) is a fourth order stress tensor that satisfies

\[ c^{-1} |F_{\text{sym}}|^2 \leq C F : F \leq c |F_{\text{sym}}|^2 \]

for every \( F \in M^{2 \times 2} \).

Here \( F_{\text{sym}} := (F + F^T)/2 \) and \( c \) is some positive constant. The energy density \( W \) acts on gradient strain fields \( \beta := \nabla u \) and the elastic energy induced by \( \beta \) is defined as

\[ \int_{\Omega} W(\beta) \, dx. \]

Following the semi-discrete dislocation model (see [3, 7, 10]), dislocations are introduced as point defects of the strain \( \beta \). More specifically, a straight dislocation line \( \gamma \) orthogonal to the cross section \( \Omega \) is identified with the point \( x_0 = \gamma \cap \Omega \). We then require

\[ \text{Curl} \beta = \xi \delta_{x_0}, \]

in the sense of distributions. Here \( \xi := (\xi_1, \xi_2, 0) \) is the Burgers vector, orthogonal to \( \gamma \), so that \( (\gamma, \xi) \) defines an edge dislocation. Therefore, with the identification above, also \( (x_0, \xi) \) represents an edge dislocation (see Figure 3). It is immediate to check that (3) implies

\[ \int_{B_\varepsilon(x_0) \setminus B_\varepsilon(x_0)} W(\beta) \, dx \geq c \log \frac{\sigma}{\varepsilon}, \quad \text{for every } \sigma > \varepsilon > 0. \]

From the above inequality we deduce that, as \( \varepsilon \to 0 \), the energy diverges logarithmically in neighbourhoods of \( x_0 \). To overcome this problem we adopt the so-called core radius approach. Namely, we remove from \( \Omega \) the ball \( B_\varepsilon(x_0) \), called the core region, where \( \varepsilon \) is proportional to the underlying lattice spacing, and we replace (3) by the circulation condition

\[ \int_{\partial B_\varepsilon(x_0)} \beta \cdot t \, ds = \xi. \]

In the above formula \( t \) is the unit tangent vector to \( \partial B_\varepsilon(x_0) \) and \( ds \) in the 1-dimensional Hausdorff measure. A generic distribution of \( N \) dislocations will therefore be identified
Figure 3. Left: cylindrical domain $\Omega \times \mathbb{R}$. The dislocation $(\gamma, \xi)$ is of edge type. The green plane represents the extra half-plane of atoms corresponding to $\gamma$. Right: section $\Omega$ of the cylindrical domain in the left picture. The red point $x_0 = \gamma \cap \Omega$ represents the section of the dislocation line, so that $(x_0, \xi)$ identifies an edge dislocation. The green line is the intersection of the extra half-plane of atoms in the left picture with $\Omega$.

with the points $\{x_i\}_{i=1}^N$. To each $x_i$ we associate a corresponding Burgers vector $\xi_i$, belonging to a finite set $\mathcal{S} \subset \mathbb{R}^2$ of admissible Burgers vectors, which depends on the underlying crystalline structure. Clearly the Burgers vector scales like $\varepsilon$; for example for a square lattice we have $\mathcal{S} = \varepsilon\{\pm e_1, \pm e_2\}$. From now on we will always renormalise the Burgers vectors, scaling them by $\varepsilon^{-1}$, so that $\mathcal{S}$ becomes a fixed set independent of the lattice spacing. The energy is in turn scaled by $\varepsilon^{-2}$, since it is quadratic with respect to the Burgers vector. Following [10], we make a technical hypothesis of good separation for the dislocation cores, by introducing a small scale $\rho_\varepsilon \gg \varepsilon$, called hard core radius. Any cluster of dislocations contained in a ball $B_{\rho_\varepsilon}(x_0) \subset \Omega$ will be identified with a multiple dislocation $\xi \delta_{x_0}$, where $\xi$ is the sum of the Burgers vectors corresponding to the dislocations in the cluster (see Figure 4 Left). Therefore $\xi \in \mathcal{S}$, where

$$\mathcal{S} := \text{Span}_\mathbb{Z} \mathcal{S}$$

is the set of multiple Burgers vectors. Under this assumption, a generic distribution of dislocations is identified with a measure

$$\mu = \sum_{i=1}^N \xi_i \delta_{x_i}, \quad \xi_i \in \mathcal{S},$$

where

$$|x_i - x_j| \geq 2\rho_\varepsilon, \quad \text{dist}(x_k, \partial \Omega) > \rho_\varepsilon, \quad \text{for every } 1 \leq i, j, k \leq N, \ i \neq j.$$
Denote by $\Omega_\varepsilon(\mu) := \Omega \setminus \bigcup B_\varepsilon(x_i)$ the drilled domain (see Figure 4 Right). The admissible strains associated to $\mu$ are matrix fields $\beta \in L^2(\Omega_\varepsilon(\mu); M_{2 \times 2})$ such that

$$\operatorname{Curl} \beta \mathbb{1}_{\Omega_\varepsilon(\mu)} = 0$$

and

$$\int_{\partial B_\varepsilon(x_i)} \beta \cdot t \, ds = \xi_i, \quad \text{for every } i = 1, \ldots, N.$$  \hfill (4)

The elastic energy corresponding to $(\mu, \beta)$ is defined by

$$E_\varepsilon(\mu, \beta) := \int_{\Omega_\varepsilon(\mu)} W(\beta) \, dx.$$  \hfill (5)

The energy induced by the dislocation distribution $\mu$ is given by minimising (5) over the set of all strains satisfying (4). From (4) it follows that the energy is always positive if $\mu \neq 0$.

The energy contribution of a single dislocation core is of order $|\log \varepsilon|$ (see Proposition 3.2). Therefore, for a system of $N_\varepsilon$ dislocations, with $N_\varepsilon \to \infty$ as $\varepsilon \to 0$, the relevant energy regime is

$$E_\varepsilon \approx N_\varepsilon |\log \varepsilon|.$$  \hfill (6)

This scaling was already studied in [6] for $N_\varepsilon \leq C$. The critical regime $N_\varepsilon \approx |\log \varepsilon|$ has been considered for Ginzburg Landau vortices in [13] and for edge dislocations in [10], where the authors, assuming that the dislocations are well separated, characterise the $\Gamma$-limit of $\frac{E_\varepsilon}{|\log \varepsilon|}$. We will later discuss how this compares to our $\Gamma$-convergence result.

For our analysis we will consider a higher energy regime corresponding to

$$\frac{1}{\varepsilon} \gg N_\varepsilon \gg |\log \varepsilon|.$$
LINEARISED POLYCRYSTALS

We will see that this energy regime will account for grain boundaries that are mutually rotated by infinitesimal angles \( \theta \approx 0 \). To be more specific, one can split the contribution of \( E_\varepsilon \) into

\[
E_\varepsilon(\mu, \beta) = E^{\text{inter}}_\varepsilon(\mu, \beta) + E^{\text{self}}_\varepsilon(\mu, \beta),
\]

where \( E^{\text{self}}_\varepsilon \) is the self-energy concentrated in the hard core region \( \cup_i B_{\rho_1}(x_i) \) while \( E^{\text{inter}}_\varepsilon \) is the interaction energy computed outside the hard core region. In Theorem 4.2 we will prove that the \( \Gamma \)-limit as \( \varepsilon \to 0 \) of the rescaled functionals \( E_\varepsilon \), with respect to the strains and the dislocation measures, is of the form

\[
F(\mu, S, A) = \int_\Omega W(S) \, dx + \int_\Omega \phi \left( \frac{d\mu}{d|\mu|} \right) \, d|\mu|.
\]

The first term of \( F \) comes from the interaction energy. It represents the elastic energy of the symmetric field \( S \), which is the weak limit of the symmetric part of the strains rescaled by \( \sqrt{N_\varepsilon \log \varepsilon} \). Instead, the antisymmetric part of the strain, rescaled by \( N_\varepsilon \), weakly converges to an antisymmetric field \( A \). Therefore, since \( N_\varepsilon \gg |\log \varepsilon| \), the symmetric part of the strain is of lower order with respect to the antisymmetric part.

The second term of \( F \) is the plastic energy. The density function \( \phi \) is positively 1-homogeneous and it can be defined as the relaxation of a cell-problem formula (see Proposition 3.2). The measure \( \mu \) in (4) is the weak-\( * \) limit of the dislocation measures rescaled by \( N_\varepsilon \), and \( d\mu/d|\mu| \) represents the Radon-Nikodym derivative of \( \mu \) with respect to \( |\mu| \). Notice that \( A \) and \( \mu \) come from the same rescaling \( N_\varepsilon \), whereas the symmetric part \( S \) is of lower order, namely \( \sqrt{N_\varepsilon \log \varepsilon} \). As a consequence, the compatibility condition (4) passes to the limit as

\[
\text{Curl} \, A = \mu.
\]

This implies that the elastic and plastic terms in \( F \) are decoupled. Indeed this is the main difference with the critical regime \( N_\varepsilon \approx |\log \varepsilon| \) studied in [10], where the contribution of the symmetric and antisymmetric part of the strain, as well as the dislocation measure, have the same order \( |\log \varepsilon| \). This results, in [10], into the coupling of the two terms of the energy, through the condition \( \text{Curl} \, \beta = \mu \) where \( \beta = S + A \).

Next we focus on the study of the \( \Gamma \)-limit \( F \). Precisely, we impose piecewise constant Dirichlet boundary conditions on \( A \), and we show that \( F \) is minimised by strains that are locally constant and take values in the set of antisymmetric matrices. More precisely, there is a Caccioppoli partition of \( \Omega \) with sets of finite perimeter where the antisymmetric strain is constant. Such sets represent the grains of the polycrystal, while the corresponding constant antisymmetric matrices represents their orientation. We call such configurations linearised polycrystals. This definition is motivated by the fact that antisymmetric matrices can be considered as infinitesimal rotations, being the linearisation about the identity of the set of rotations. The proof of this result is based on the simple observation that the variational problem is equivalent to minimise some anisotropic total variation of a scalar function, which is locally constant on \( \partial \Omega \). By the coarea formula, one can easily show that there always exists a piece-wise constant minimiser.

The paper is organised as follows. In Section 2 we introduce the rigorous mathematical setting of the problem. In Section 3 we recall some results from [10], which will be useful
for the $\Gamma$-convergence analysis of the rescaled energy $E_\varepsilon$. The main $\Gamma$-convergence result will be proved in Section 4. In Section 5 we will include Dirichlet type boundary conditions to the $\Gamma$-convergence analysis performed in the previous section. Finally, in Section 6 we will show that the plastic part of $F$ is minimised by linearised polycrystals, by prescribing piecewise constant boundary conditions on the antisymmetric part of the limit strain.

2. Setting of the problem

Let $\Omega \subset \mathbb{R}^2$ be a bounded open domain with Lipschitz continuous boundary. The set $\Omega$ represents a horizontal section of an infinite cylindrical crystal $\Omega \times \mathbb{R}$. Define as $\mathcal{S} := \{b_1, \ldots, b_s\}$ the class of Burgers vectors. We will assume that $\mathcal{S}$ contains at least two linearly independent vectors so that $\text{Span}_\mathbb{R} \mathcal{S} = \mathbb{R}^2$. We then define the set of slip directions

$$\mathcal{S} := \text{Span}_\mathbb{R} \mathcal{S},$$

that coincides with the set of Burgers vectors for multiple dislocations. An edge dislocation can be identified with a point $x \in \Omega$ and a vector $\xi \in \mathcal{S}$.

Let $\varepsilon > 0$ be a parameter representing the interatomic distance of the crystal and denote by $\{N_\varepsilon\} \subset \mathbb{N}$ the number of dislocations present in the crystal at the scale $\varepsilon$. As in [10], we introduce a hard core radius $\rho_\varepsilon \to 0$, and we assume that

(i) $\lim_{\varepsilon \to 0} \varepsilon^s \rho_\varepsilon = +\infty$ for every fixed $0 < s < 1$,
(ii) $\lim_{\varepsilon \to 0} N_\varepsilon \rho_\varepsilon^2 = 0$,
(iii) $\lim_{\varepsilon \to 0} N_\varepsilon |\log \varepsilon| = +\infty$.

The first condition implies that the hard core region contains almost all the self energy (see Proposition 3.3), the second one guarantees that the area of the hard core region tends to zero, while the third one corresponds to the supercritical regime, where the interaction energy is dominant with respect to the self energy. The above conditions are compatible if

$$\rho_\varepsilon = \varepsilon^{t(\varepsilon)}, \quad N_\varepsilon = \varepsilon^{-t(\varepsilon)}$$

for some positive $t(\varepsilon)$ converging to zero slowly enough (for instance such that $t(\varepsilon) |\log \varepsilon| < < \log(|\log \varepsilon|)$). The class of admissible dislocations is defined by

$$\mathcal{AD}_\varepsilon(\Omega) := \left\{ \mu \in \mathcal{M}(\Omega; \mathbb{R}^2) : \mu = \sum_{i=1}^M \xi_i \delta_{x_i}, \ M \in \mathbb{N}, \ \xi_i \in \mathcal{S} \right\},$$

where $\mathcal{M}(\Omega; \mathbb{R}^2)$ denotes the space of $\mathbb{R}^2$ valued Radon measures on $\Omega$ and $B_r(x)$ is the ball of radius $r$ centred at $x \in \mathbb{R}^2$.

Fix a dislocations measure $\mu = \sum_{i=1}^M \xi_i \delta_{x_i} \in \mathcal{AD}_\varepsilon(\Omega)$. For $r > 0$ define

$$\Omega_r(\mu) := \Omega \setminus \bigcup_{i=1}^M B_r(x_i).$$
The class of admissible strains associated with \( \mu \) is given by the maps \( \beta \in L^2(\Omega_\varepsilon(\mu); \mathbb{R}^2) \) such that
\[
Curl \beta \subseteq \Omega_\varepsilon(\mu) = 0, \quad \int_{\partial B_\varepsilon(x_i)} \beta \cdot t \, ds = \xi_i \quad \text{for every} \quad i = 1, \ldots, M.
\]
The identity \( Curl \beta = 0 \) is intended in the sense of distributions, where \( Curl \beta \in D'(\Omega; \mathbb{R}^2) \) is defined as
\[
(10) \quad Curl \beta := \left( \frac{\partial_1 \beta_{12} - \partial_2 \beta_{11}}{\partial_1 \beta_{22} - \partial_2 \beta_{21}} \right).
\]
The integrand \( \beta \cdot t \) is intended in the sense of traces, since \( \beta \in H(Curl, \Omega_\varepsilon(\mu)) \) (see [5, Theorem 2, p. 204]), and \( t \) is the unit tangent vector to \( \partial B_\varepsilon(x_i) \), obtained by a counterclockwise rotation of \( \pi/2 \) of the outer normal \( \nu \) to \( B_\varepsilon(x) \), that is \( t := J\nu \) with
\[
(11) \quad J := \begin{pmatrix} 0 & -1 \\ 1 & 0 \end{pmatrix}.
\]
In the following it will be useful to extend the admissible strains to the whole \( \Omega \). Therefore, for a dislocation measure \( \mu = \sum_{i=1}^M \xi_i \delta_{x_i} \in AD_\varepsilon(\Omega) \), we introduce the class \( A\mathcal{S}_\varepsilon(\mu) \) of admissible strains as
\[
(12) \quad A\mathcal{S}_\varepsilon(\mu) := \left\{ \beta \in L^2(\Omega; \mathbb{M}^{2 \times 2}) : \beta \equiv 0 \text{ in } \Omega \setminus \Omega_\varepsilon(\mu), \ C_{\varepsilon} \beta = 0 \text{ in } \Omega_\varepsilon(\mu), \int_{\partial B_\varepsilon(x_i)} \beta \cdot t \, ds = \xi_i, \int_{\Omega_\varepsilon(\mu)} \beta^{\text{skew}} \, dx = 0, \text{ for every } i = 1, \ldots, M \right\}.
\]
Here \( F^{\text{skew}} := (F - F^T)/2 \). The last condition in (12) is not restrictive and will guarantee the uniqueness of the minimising strain.

The energy associated to an admissible pair \((\mu, \beta)\) with \( \mu \in AD_\varepsilon(\Omega) \) and \( \beta \in A\mathcal{S}_\varepsilon(\mu) \) is defined by
\[
(13) \quad E_\varepsilon(\mu, \beta) := \int_{\Omega_\varepsilon(\mu)} W(\beta) \, dx = \int_{\Omega} W(\beta) \, dx,
\]
where
\[
W(F) := \frac{1}{2} C F : F = \frac{1}{2} C F^{\text{sym}} : F^{\text{sym}}
\]
is the strain energy density, where \( C \) is the elasticity tensor satisfying
\[
(14) \quad c^{-1} |F^{\text{sym}}|^2 \leq W(F) \leq c |F^{\text{sym}}|^2 \quad \text{for every} \quad F \in \mathbb{M}^{2 \times 2},
\]
for some given \( c > 0 \). Since the elasticity tensor also satisfies the symmetry properties \( C_{ijkl} = C_{klij} = C_{ijlk} = C_{jikl} \) (see [2]), it follows that
\[
\frac{1}{2} C F : F = \frac{1}{2} C F^{\text{sym}} : F^{\text{sym}}.
\]
Notice that for any \( \mu \in AD_\varepsilon(\Omega) \) the minimum problem
\[
(15) \quad \min \left\{ \int_{\Omega_\varepsilon(\mu)} W(\beta) \, dx : \beta \in A\mathcal{S}_\varepsilon(\mu) \right\}
\]
has a unique solution. This can be seen by removing a finite number of cuts \( L \) from \( \Omega_\varepsilon(\mu) \) so that \( \Omega_\varepsilon(\mu) \setminus L \) becomes simply connected and observing that there exists a displacement.
gradient such that \( \nabla u = \beta \) in \( \Omega_{\varepsilon}(\mu) \setminus L \). Then we can apply the classic Korn inequality (see, e.g., [4]) to \( \nabla u \), and conclude by using the direct method of calculus of variations.

We recall that in our analysis we assume the supercritical regime

\[
N_{\varepsilon} \gg |\log \varepsilon|.
\]

As already discussed, the relevant scaling for the asymptotic study of \( E_{\varepsilon} \) is given by \( N_{\varepsilon}|\log \varepsilon| \). Therefore we introduce the scaled energy functional defined on the space \( \mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; \mathbb{M}^{2 \times 2}) \) as

\[
F_{\varepsilon}(\mu, \beta) := \begin{cases} 
\frac{1}{N_{\varepsilon}|\log \varepsilon|} E_{\varepsilon}(\mu, \beta) & \text{if } \mu \in \mathcal{AD}_{\varepsilon}(\Omega), \beta \in \mathcal{AS}_{\varepsilon}(\mu), \\
+\infty & \text{otherwise}.
\end{cases}
\]

3. Preliminaries

In this section we will recall some results and notations from [10] that will be needed in the following \( \Gamma \)-convergence analysis.

3.1. Cell formula for the self-energy. In this section we will rigorously define the density function \( \varphi \) appearing in the \( \Gamma \)-limit \( F \) introduced in (6). In order to do so, following [10, Section 4], we will introduce the self-energy \( \psi(\xi) \) stored in the core region of a single dislocation \( \xi_{0} \) centred at the origin.

Let us start by defining, for every \( \xi \in \mathbb{R}^2 \) and \( 0 < r_1 < r_2 \), the space

\[
\mathcal{AS}_{r_1, r_2}(\xi) := \left\{ \beta \in L^2(B_{r_2} \setminus B_{r_1}; \mathbb{M}^{2 \times 2}) : \text{Curl} \beta = 0, \int_{\partial B_{r_1}} \beta \cdot t \, ds = \xi \right\},
\]

where \( B_r \) is the ball of radius \( r \) centred at the origin. For strains belonging to such class, we have the following bound from below of the energy (see [10, Remark 3]).

**Proposition 3.1.** Let \( 0 < r_1 < \frac{r_2}{2} \) and \( \xi \in \mathbb{R} \). There exists a constant \( c > 0 \) such that, for every \( \beta \in \mathcal{AS}_{r_1, r_2}(\xi) \),

\[
\int_{B_{r_2} \setminus B_{r_1}} |\beta_{\text{sym}}|^2 \, dx \geq c|\xi|^2 \log \frac{r_2}{r_1}.
\]

Let \( C_\varepsilon := B_1 \setminus B_\varepsilon \), with \( 0 < \varepsilon < 1 \), and introduce \( \psi_\varepsilon : \mathbb{R}^2 \to \mathbb{R} \) through the cell problem

\[
\psi_\varepsilon(\xi) := \frac{1}{|\log \varepsilon|} \min \left\{ \int_{C_\varepsilon} W(\beta) \, dx : \beta \in \mathcal{AS}_{\varepsilon, 1}(\xi) \right\}.
\]

It is easy to show that the minimum in (20) exists, by combining the classic Korn inequality with the direct method of the calculus of variations. It is also immediate to check that the minimiser \( \beta_\varepsilon(\xi) \) of (20) satisfies the boundary value problem

\[
\begin{cases}
\text{Div} \mathbb{C}_{\beta_\varepsilon}(\xi) = 0 & \text{in } C_\varepsilon, \\
\mathbb{C}_{\beta_\varepsilon}(\xi) \cdot \nu = 0 & \text{on } \partial C_\varepsilon,
\end{cases}
\]

where \( \nu \) is the outer normal to \( \partial C_\varepsilon \). Also, there exists a strain \( \beta_0(\xi) : \mathbb{R}^2 \to \mathbb{M}^{2 \times 2} \) with \( |\beta_0(\xi)(x)| \leq c|x|^{-1}|\xi| \) (see [2]) that is a distributional solution to
\begin{align}
\begin{cases}
\text{Div } C\beta_0(\xi) = 0 & \text{in } \mathbb{R}^2, \\
\text{Curl } \beta_0(\xi) = \xi \delta_0 & \text{in } \mathbb{R}^2.
\end{cases}
\end{align}

The following result holds true (see [10, Corollary 6]).

**Proposition 3.2** (Self-energy). There exists a constant $C > 0$ such that for every $\xi \in \mathbb{R}^2$,
\begin{equation}
\psi_\varepsilon(\xi) \leq \frac{1}{|\log \varepsilon|} \int_{C_\varepsilon} W(\beta_0(\xi)) \, dx \leq \psi(\xi) + \frac{C|\xi|^2}{|\log \varepsilon|}.
\end{equation}

In particular, for every $\xi \in \mathbb{R}^2$, we have that
\begin{equation}
\lim_{\varepsilon \to 0} \psi_\varepsilon(\xi) = \psi(\xi),
\end{equation}
pointwise, where the map $\psi : \mathbb{R}^2 \to \mathbb{R}$ is the self-energy defined by
\begin{equation}
\psi(\xi) := \lim_{\varepsilon \to 0} \frac{1}{|\log \varepsilon|} \int_{C_\varepsilon} W(\beta_0(\xi)) \, dx.
\end{equation}

Moreover, there exists a constant $c > 0$ such that, for every $\xi \in \mathbb{R}^2$,
\begin{equation}
c^{-1}|\xi|^2 \leq \psi(\xi) \leq c|\xi|^2.
\end{equation}

We now want to show that the self-energy $\psi(\xi)$ is indeed concentrated in the hardcore region $B_{\rho_\varepsilon} \setminus B_\varepsilon$ of the dislocation $\xi \delta_0$. To this end, define the map $\bar{\psi}_\varepsilon : \mathbb{R}^2 \to \mathbb{R}$ as
\begin{equation}
\bar{\psi}_\varepsilon(\xi) := \frac{1}{|\log \varepsilon|} \min \left\{ \int_{B_{\rho_\varepsilon} \setminus B_\varepsilon} W(\beta) \, dx : \beta \in \mathcal{AS}_{\varepsilon, \rho_\varepsilon}(\xi) \right\},
\end{equation}
for $\xi \in \mathbb{R}^2$. It will also be useful to introduce $\tilde{\psi}_\varepsilon : \mathbb{R}^2 \to \mathbb{R}$ as
\begin{equation}
\tilde{\psi}_\varepsilon(\xi) := \frac{1}{|\log \varepsilon|} \min \left\{ \int_{B_{\rho_\varepsilon} \setminus B_\varepsilon} W(\beta) \, dx : \beta \in \mathcal{AS}_{\varepsilon, \rho_\varepsilon}(\xi), \beta \cdot t = \tilde{\beta} \cdot t \text{ on } \partial B_\varepsilon \cup \partial B_{\rho_\varepsilon} \right\},
\end{equation}
where $\tilde{\beta} \in \mathcal{AS}_{\varepsilon, \rho_\varepsilon}(\xi)$ is a fixed given strain such that
\begin{equation}
|\tilde{\beta}(x)| \leq K \frac{|\xi|}{|x|},
\end{equation}
for some positive constant $K$. By [14], it is immediate to see that problems (25)-(26) are well posed. The following results holds (see [10, Remark 7, Proposition 8]).

**Proposition 3.3.** We have $\bar{\psi}_\varepsilon(\xi) = \psi_\varepsilon(\xi)(1 + o(\varepsilon))$ and $\tilde{\psi}_\varepsilon(\xi) = \psi_\varepsilon(\xi)(1 + o(\varepsilon))$, with $o(\varepsilon) \to 0$ as $\varepsilon \to 0$ uniformly with respect to $\xi \in \mathbb{R}^2$. In particular
\begin{equation}
\lim_{\varepsilon \to 0} \bar{\psi}_\varepsilon(\xi) = \lim_{\varepsilon \to 0} \tilde{\psi}_\varepsilon(\xi) = \psi(\xi)
\end{equation}
pointwise, where $\psi$ is the self-energy defined in (23).
Now, we can define the density $\varphi : \mathbb{R}^2 \to [0, +\infty)$ as the relaxation of the self-energy $\psi$,
\begin{equation}
\varphi(\xi) := \inf \left\{ \sum_{k=1}^{N} \lambda_k \psi(\xi_k) : \sum_{k=1}^{N} \lambda_k \xi_k = \xi, N \in \mathbb{N}, \lambda_k \geq 0, \xi_k \in \mathbb{S} \right\}.
\end{equation}

The properties of $\varphi$ are summarised in the following proposition.

**Proposition 3.4.** The function $\varphi$ defined in (28) is convex and positively 1-homogeneous, that is
\[ \varphi(\lambda \xi) = \lambda \varphi(\xi), \quad \text{for every } \xi \in \mathbb{R}^2, \lambda > 0. \]
Moreover there exists a constant $c > 0$ such that
\begin{equation}
(c^{-1} |\xi| \leq \varphi(\xi) \leq c |\xi|, \quad \text{for every } \xi \in \mathbb{R}^2. \quad \text{In particular, the infimum in (28) is actually a minimum.}
\end{equation}

### 3.2. Korn type inequality

We will now recall the generalised Korn inequality proved in [10, Theorem 11].

**Theorem 3.5** (Generalised Korn inequality). There exists a constant $C > 0$, depending only on $\Omega$, with the following property: for every $\beta \in L^1(\Omega; \mathbb{M}^{2 \times 2})$ with
\[ \text{Curl} \beta = \mu \in \mathcal{M}(\Omega; \mathbb{R}^2), \]
we have
\begin{equation}
\int_{\Omega} |\beta - A|^2 \, dx \leq C \left( \int_{\Omega} |\beta^{\text{sym}}|^2 \, dx + |\mu|(\Omega)^2 \right),
\end{equation}
where $A$ is the constant $2 \times 2$ antisymmetric matrix defined by $A := \frac{1}{|\Omega|} \int_{\Omega} \beta^{\text{skew}} \, dx$.

### 3.3. Remarks on the distributional Curl

We conclude this section with some considerations on the distributional Curl of admissible strains (see [10, Remark 1]).

**Remark 3.6** (Curl of admissible strains). Let $\mu \in \mathcal{AD}_{\epsilon}(\Omega)$ and $\beta \in \mathcal{AS}_{\epsilon}(\mu)$. Recalling definition [10], we can define the scalar distribution
\[ \text{curl} \beta(i) := \frac{\partial}{\partial x_1} \beta_{i2} - \frac{\partial}{\partial x_2} \beta_{i1}, \]
where $\beta(i)$ denotes the $i$-th row of $\beta$. This means that for any test function $\varphi$ in $C_0^\infty(\Omega)$, we can write
\begin{equation}
(\text{curl} \beta(i), \varphi) = -\int_{\Omega} \beta(i) \cdot J \nabla \varphi \, dx,
\end{equation}
where $J$ is the counter-clockwise rotation of $\pi/2$, as defined in [11]. Notice that, if $\beta(i) \in L^2(\Omega; \mathbb{R}^2)$, then (31) implies that $\text{curl} \beta(i)$ is well defined also for $\varphi \in H_0^1(\Omega)$ and acts continuously on it. Therefore
\[ \text{Curl} \beta \in H^{-1}(\Omega; \mathbb{R}^2) \quad \text{for every } \beta \in \mathcal{AS}_{\epsilon}(\mu), \]
where $H^{-1}(\Omega; \mathbb{R}^2)$ denotes the dual of the space $H_0^1(\Omega; \mathbb{R}^2)$. 

Theorem 4.2. can be written as
\[
\phi
\]
for every \( L \). We say that the family (also referred to as sequence in the following)

\[
\text{Definition 4.1. convergence result holds is given by the following definition.}
\]

\[
\text{Further, if } \mu = \sum_{i=1}^{M} \xi_{i} \delta_{x_{i}} \in \mathcal{A} \mathcal{D}_{\varepsilon}(\Omega), \text{ then the circulation condition}
\]

\[
\int_{\partial B_{\varepsilon}(x_{i})} \beta \cdot t \, ds = \xi_{i}, \quad \text{for every } i = 1, \ldots, M,
\]
can be written as
\[
\langle \text{Curl } \beta, \varphi \rangle = \sum_{i=1}^{M} \xi_{i} c_{i},
\]
for every \( \varphi \in H_{0}^{1}(\Omega) \) such that \( \varphi \equiv c_{i} \) in \( B_{\varepsilon}(x_{i}) \). If in addition \( \varphi \in C^{0}(\Omega) \cap H_{0}^{1}(\Omega) \), then
\[
\langle \text{Curl } \beta, \varphi \rangle = \int_{\Omega} \varphi \, d\mu.
\]

4. \( \Gamma \)-convergence analysis

In this section we will study, by means of \( \Gamma \)-convergence, the behaviour as \( \varepsilon \to 0 \) of the functionals \( F_{\varepsilon} : \mathcal{M}(\Omega; \mathbb{R}^{2}) \times L^{2}(\Omega; \mathbb{M}^{2 \times 2}) \to \mathbb{R} \) defined in [17], in the energy regime \( N_{\varepsilon} \gg |\log \varepsilon| \). In Theorem 4.2 we will prove that the \( \Gamma \)-limit for the sequence \( F_{\varepsilon} \) is given by the functional \( F : (\mathcal{M}(\Omega; \mathbb{R}^{2}) \cap H^{-1}(\Omega; \mathbb{R}^{2})) \times L^{2}(\Omega; \mathbb{M}_{\text{sym}}^{2 \times 2}) \times L^{2}(\Omega; \mathbb{M}_{\text{skew}}^{2 \times 2}) \to \mathbb{R} \) defined as

\[
F(\mu, S, A) := \begin{cases} 
\int_{\Omega} W(S) \, dx + \int_{\Omega} \varphi \left( \frac{d\mu}{d|\mu|} \right) \, d|\mu| & \text{if Curl } A = \mu, \\
+\infty & \text{otherwise,}
\end{cases}
\]

where \( \varphi \) is the energy density introduced in [28]. The topology under which the \( \Gamma \)-convergence result holds is given by the following definition.

\textbf{Definition 4.1.} We say that the family (also referred to as sequence in the following)

\[
(\mu_{\varepsilon}, \beta_{\varepsilon}) \in \mathcal{M}(\Omega; \mathbb{R}^{2}) \times L^{2}(\Omega; \mathbb{M}^{2 \times 2})
\]

is converging to a triplet \((\mu, S, A) \in \mathcal{M}(\Omega; \mathbb{R}^{2}) \times L^{2}(\Omega; \mathbb{M}_{\text{sym}}^{2 \times 2}) \times L^{2}(\Omega; \mathbb{M}_{\text{skew}}^{2 \times 2})\) if

\[
\begin{align*}
\mu_{\varepsilon} & \overset{\ast}{\rightharpoonup} \mu \quad \text{in} \quad \mathcal{M}(\Omega; \mathbb{R}^{2}), \\
\frac{\beta_{\varepsilon}^{\text{sym}}}{\sqrt{N_{\varepsilon}|\log \varepsilon|}} & \rightharpoonup S \quad \text{and} \quad \frac{\beta_{\varepsilon}^{\text{skew}}}{N_{\varepsilon}} \rightharpoonup A \quad \text{weakly in} \quad L^{2}(\Omega; \mathbb{M}^{2 \times 2}).
\end{align*}
\]

\textbf{Theorem 4.2.} The following \( \Gamma \)-convergence result holds true.

(i) (Compactness) Let \( \varepsilon_{n} \to 0 \) and assume that \((\mu_{n}, \beta_{n}) \in \mathcal{M}(\Omega; \mathbb{R}^{2}) \times L^{2}(\Omega; \mathbb{M}^{2 \times 2})\) is such that \( \sup_{n} \mathcal{F}_{\varepsilon}(\mu_{n}, \beta_{n}) \leq E \), for some positive constant \( E \). Then there exists

\[
(\mu, S, A) \in (\mathcal{M}(\Omega; \mathbb{R}^{2}) \cap H^{-1}(\Omega; \mathbb{R}^{2})) \times L^{2}(\Omega; \mathbb{M}_{\text{sym}}^{2 \times 2}) \times L^{2}(\Omega; \mathbb{M}_{\text{skew}}^{2 \times 2}),
\]

with \( \text{Curl } A = \mu \), such that up to subsequences (not relabelled), \((\mu_{n}, \beta_{n})\) converges to \((\mu, S, A)\) in the sense of Definition 4.1.

(ii) (\( \Gamma \)-convergence) The functionals \( F_{\varepsilon} \) defined in [17] \( \Gamma \)-converge to the functional \( F \) defined in [32], with respect to the convergence of Definition 4.1. Specifically, for every

\[
(\mu, S, A) \in (\mathcal{M}(\Omega; \mathbb{R}^{2}) \cap H^{-1}(\Omega; \mathbb{R}^{2})) \times L^{2}(\Omega; \mathbb{M}_{\text{sym}}^{2 \times 2}) \times L^{2}(\Omega; \mathbb{M}_{\text{skew}}^{2 \times 2})
\]
such that $\text{Curl} \ A = \mu$ we have:

- (\(\Gamma\)-liminf inequality) For all sequences \((\mu_\varepsilon, \beta_\varepsilon) \in \mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; \mathbb{M}^{2 \times 2})\) converging to \((\mu, S, A)\) in the sense of Definition \ref{def:weak_convergence},

\[
\mathcal{F}(\mu, S, A) \leq \liminf_{\varepsilon \to 0} \mathcal{F}_\varepsilon(\mu_\varepsilon, \beta_\varepsilon). 
\]

- (\(\Gamma\)-limsup inequality) There exists a recovery sequence \((\mu_\varepsilon, \beta_\varepsilon) \in \mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; \mathbb{M}^{2 \times 2})\), such that \((\mu_\varepsilon, \beta_\varepsilon)\) converges to \((\mu, S, A)\) in the sense of Definition \ref{def:weak_convergence} and

\[
\limsup_{\varepsilon \to 0} \mathcal{F}_\varepsilon(\mu_\varepsilon, \beta_\varepsilon) \leq \mathcal{F}(\mu, S, A). 
\]

**Remark 4.3.** Since \(A\) is antisymmetric, there exist \(u \in L^2(\Omega)\) such that

\[
A = \begin{pmatrix}
0 & u \\
-u & 0
\end{pmatrix}.
\]

Notice that $\text{Curl} \ A = Du$. Therefore, $\text{Curl} \ A \in \mathcal{M}(\Omega; \mathbb{R}^2)$ implies that $u \in BV(\Omega)$ and $\text{curl} \ \mu = 0$.

### 4.1. Compactness

We will prove the compactness statement in Theorem \ref{thm:compactness}. Assume that \((\mu_n, \beta_n)\) is a sequence in \(\mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; \mathbb{M}^{2 \times 2})\) such that

\[
\sup_n \mathcal{F}_\varepsilon(\mu_n, \beta_n) \leq E.
\]

The proof is divided into four parts.

**Part 1.** Compactness of the rescaled measures.

Let \(\mu_n := \sum_{i=1}^{M_n} \xi_{n,i} \delta_{x_{n,i}} \in AD_{\varepsilon_n}(\Omega)\). We show that the total variation of \(\mu_n/N_{\varepsilon_n}\) is uniformly bounded, i.e., there exists \(C > 0\) such that

\[
\frac{1}{N_{\varepsilon_n}} |\mu_n|(\Omega) = \frac{1}{N_{\varepsilon_n}} \sum_{i=1}^{M_n} |\xi_{n,i}| \leq C,
\]

for every \(n \in \mathbb{N}\). Since the function \(y \mapsto \beta_n(x_{n,i} + y)\) belongs to $\mathcal{AS}_{\varepsilon_n, \psi_{n}}(\xi_{n,i})$, we have

\[
E \geq \mathcal{F}_\varepsilon(\mu_n, \beta_n) \geq \frac{1}{N_{\varepsilon_n} |\log \varepsilon_n|} \sum_{i=1}^{M_n} \int_{B_{\varepsilon_n}(x_{n,i}) \setminus B_{\varepsilon_n}(x_{n,i})} W(\beta_n) \, dx
\]

\[
= \frac{1}{N_{\varepsilon_n} |\log \varepsilon_n|} \sum_{i=1}^{M_n} \int_{B_{\varepsilon_n}(0) \setminus B_{\varepsilon_n}(0)} W(\beta_n(x_{n,i} + y)) \, dy \geq \frac{1}{N_{\varepsilon_n}} \sum_{i=1}^{M_n} \bar{\psi}_{\varepsilon_n}(\xi_{n,i}),
\]

where $\bar{\psi}_\varepsilon$ is defined in \((\ref{eq:bar_psi})\). Let $\psi$ be the self-energy in \((\ref{eq:self_energy})\) and set \(c := \frac{1}{2} \min_{|\xi| = 1} \psi(\xi)\). Notice that \(c > 0\), by \((\ref{eq:psi_properties})\). By Proposition \ref{prop:psi_properties} $\bar{\psi}_\varepsilon \to \psi$ pointwise as $\varepsilon \to 0$, therefore for
sufficiently large \( n \), we have \( \bar{\psi}_{\varepsilon_n}(\xi) \geq c \) for every \( \xi \in \mathbb{R}^2 \) with \( |\xi| = 1 \). Hence,

\[
\frac{1}{N_{\varepsilon_n}} \sum_{i=1}^{M_n} \bar{\psi}_{\varepsilon_n}(\xi_{n,i}) = \frac{1}{N_{\varepsilon_n}} \sum_{i=1}^{M_n} |\xi_{n,i}|^2 \bar{\psi}_{\varepsilon_n} \left( \frac{\xi_{n,i}}{|\xi_{n,i}|} \right) \geq c \frac{1}{N_{\varepsilon_n}} \sum_{i=1}^{M_n} |\xi_{n,i}|^2 \geq \frac{c}{N_{\varepsilon_n}} \mu_n(\Omega) \cdot \frac{1}{N_{\varepsilon_n}}.
\]

The last inequality follows from the fact that the vectors \( \xi_{n,i} \) are bounded away from zero. By putting together the above estimates, we conclude that (37), and in turn (33) hold true.

**Part 2.** Compactness of the rescaled \( \beta_{n}^{\text{sym}} \).

This follows immediately by the bounds on the energy (14). Indeed by (36), (13) and (14),

\[
CN_{\varepsilon_n} \log \varepsilon_n \geq CE_{\varepsilon_n}(\mu_n, \beta_n) \geq C \int_{\Omega} |\beta_{n}^{\text{sym}}|^2 \, dx,
\]

and the weak compactness of \( \beta_{n}^{\text{sym}}/\sqrt{N_{\varepsilon_n} \log \varepsilon_n} \) in \( L^2(\Omega; \mathbb{M}^{2 \times 2}) \) follows.

**Part 3.** Compactness of the rescaled \( \beta_{n}^{\text{skew}} \).

Now that the bounds (37)-(38) are established, the idea is to apply the generalised Korn inequality of Theorem 3.5 in order to obtain a uniform upper bound for \( \beta_{n}^{\text{skew}}/N_{\varepsilon_n} \) in \( L^2(\Omega; \mathbb{M}^{2 \times 2}) \). In order to do that, we need a control over \( |\text{Curl} \beta_n(\Omega)| \). In fact, even if \( \beta_n \) is related to \( \mu_n \) by circulation compatibility conditions, the relationship between \( |\text{Curl} \beta_n(\Omega)| \) and \( |\mu_n(\Omega)| \) has to be clarified. In order to obtain a bound for \( |\text{Curl} \beta_n(\Omega)| \) in terms of \( |\mu_n(\Omega)| \), we will define new strains \( \tilde{\beta}_n \) that have the same order of energy of \( \beta_n \) and that satisfy \( |\text{Curl} \tilde{\beta}_n(\Omega)| = |\mu_n(\Omega)| \).

Recall that \( \mu_n = \sum_{i=1}^{M_n} \xi_{i,n} \delta_{x_{i,n}} \). Define the annuli \( C_{i,n} := B_{2\varepsilon_n}(x_{i,n}) \setminus B_{\varepsilon_n}(x_{i,n}) \) and the functions \( K_{i,n} : C_{i,n} \to \mathbb{M}^{2 \times 2} \) by

\[
K_{i,n}(x) := \frac{1}{2\pi} \xi_{i,n} \otimes J \frac{x - x_{i,n}}{|x - x_{i,n}|^2},
\]

where \( J \) is the counter-clockwise rotation of \( \pi/2 \). It is immediate to check that

\[
\int_{C_{i,n}} |K_{i,n}|^2 \, dx = C |\xi_{i,n}|^2,
\]

where the constant \( C > 0 \) does not depend on \( \varepsilon_n \). By Proposition 3.1, we also have

\[
\int_{C_{i,n}} |\beta_{n}^{\text{sym}}|^2 \, dx \geq C |\xi_{i,n}|^2,
\]

where, again, the constant \( C > 0 \) does not depend on \( \varepsilon_n \). Therefore

\[
\int_{C_{i,n}} |K_{i,n}|^2 \, dx \leq C \int_{C_{i,n}} |\beta_{n}^{\text{sym}}|^2 \, dx.
\]
Note that \( \text{Curl} K_{i,n} = \xi_{i,n} \delta_{x_i,n} \) in \( \mathcal{D}'(\mathbb{R}^2; \mathbb{R}^2) \), hence \( \text{Curl}(\beta_n - K_{i,n}) = 0 \) in \( C_{i,n} \). Moreover \( \int_{\partial B_{\varepsilon_n}(x_i,n)} (\beta_n - K_{i,n}) \cdot t \, ds = 0 \), therefore there exists \( u_{i,n} \in H^1(C_{i,n}; \mathbb{R}^2) \) such that \( \nabla u_{i,n} = \beta_n - K_{i,n} \) in \( C_{i,n} \). By (39),
\[
\int_{C_{i,n}} |\nabla u_{i,n}|^2 \, dx \leq C \int_{C_{i,n}} |\beta_n|^2 \, dx.
\]
By applying the classic Korn inequality we get
\[
\int_{C_{i,n}} |\nabla u_{i,n} - A_{i,n}|^2 \, dx \leq C \int_{C_{i,n}} |\nabla u_{i,n}|^2 \, dx \leq C \int_{C_{i,n}} |\beta_n|^2 \, dx,
\]
for some constant matrix \( A_{i,n} \in M^{2 \times 2} \) and some constant \( C > 0 \). By standard extension methods, there exists \( u_{i,n} \in H^1(B_{2\varepsilon_n}(x_i,n); \mathbb{R}^2) \) such that \( \nabla u_{i,n} = \nabla u_{i,n} - A_{i,n} \) in \( C_{i,n} \) and
\[
\int_{B_{2\varepsilon_n}(x_i,n)} |\nabla u_{i,n}|^2 \, dx \leq C \int_{C_{i,n}} |\nabla u_{i,n} - A_{i,n}|^2 \, dx \leq C \int_{C_{i,n}} |\beta_n|^2 \, dx.
\]
Define \( \tilde{\beta}_n : \Omega \to M^{2 \times 2} \) by setting
\[
\tilde{\beta}_n(x) := \begin{cases} 
\beta_n(x) & \text{if } x \in \Omega_{\varepsilon_n}(\mu_n), \\
\nabla u_{i,n}(x) + A_{i,n} & \text{if } x \in B_{\varepsilon_n}(x_i,n).
\end{cases}
\]
From (38) and (40), we have
\[
\int_\Omega |\tilde{\beta}_n|^2 \, dx = \int_{\Omega_{\varepsilon_n}(\mu_n)} |\beta_n|^2 \, dx + \sum_{i=1}^{M_n} \int_{B_{\varepsilon_n}(x_i,n)} |\nabla u_{i,n}|^2 \, dx
\]
\[
\leq C \int_\Omega |\beta_n|^2 \, dx \leq C N_{\varepsilon_n} \log \varepsilon_n.
\]
Moreover by construction \( \text{Curl} \tilde{\beta}_n \) is concentrated on \( \partial B_{\varepsilon_n}(x_i,n) \) and we have
\[
|\text{Curl} \tilde{\beta}_n| (\partial B_{\varepsilon_n}(x_i,n)) = |\mu_n| (\partial B_{\varepsilon_n}(x_i,n)) \text{ for all } i, \quad |\text{Curl} \tilde{\beta}_n| (\Omega) = |\mu_n| (\Omega).
\]
Therefore we can apply the generalised Korn inequality of Theorem 3.5 to get
\[
\int_\Omega |\tilde{\beta}_n - \tilde{A}_n|^2 \, dx \leq C \left( \int_\Omega |\tilde{\beta}_n|^2 \, dx + (|\mu_n| (\Omega))^2 \right)
\]
\[
\leq C \left( N_{\varepsilon_n} |\log \varepsilon_n| + N_{\varepsilon_n}^2 \right) \leq CN_{\varepsilon_n}^2,
\]
where \( \tilde{A}_n := \frac{1}{|\mu_n|} \int_\Omega \tilde{\beta}_n^{\text{skew}} \in M^{2 \times 2}_{\text{skew}} \). The last inequality follows from the assumption \( |\log \varepsilon_n| \ll N_{\varepsilon_n} \). Now recall that by hypothesis the average of \( \beta_n \) is an symmetric matrix and \( \beta_n \equiv 0 \) in \( \Omega \setminus \Omega_{\varepsilon_n}(\mu_n) \). Therefore, since symmetric and skew matrices are orthogonal, we have \( |\beta_n - \tilde{A}_n|^2 = |\beta_n|^2 + |\tilde{A}_n|^2 \), so that
\[
\int_{\Omega_{\varepsilon_n}(\mu_n)} |\beta_n|^2 \, dx \leq \int_{\Omega_{\varepsilon_n}(\mu_n)} |\beta_n - \tilde{A}_n|^2 \, dx \leq \int_\Omega |\tilde{\beta}_n - \tilde{A}_n|^2 \, dx \leq CN_{\varepsilon_n}^2,
\]
which yields the desired compactness property for \( \beta_n^{\text{skew}} / N_{\varepsilon_n} \) in \( L^2(\Omega; M^{2 \times 2}) \).

**Part 4.** \( \mu \in H^{-1}(\Omega; \mathbb{R}^2) \) and \( \text{Curl} A = \mu \).
Recall that \( \mu_n = \sum_{i=1}^{M_n} \xi_{n,i} \delta_{x_{n,i}} \in AD_{\varepsilon_n}(\Omega) \) and \( \beta_n \in \mathcal{AS}_{\varepsilon_n}(\mu_n) \). Let \( \varphi \in C_0^1(\Omega) \) and \( \varphi_n \in H_0^1(\Omega) \) be a sequence converging to \( \varphi \) uniformly and strongly in \( H_0^1(\Omega) \), and such that

\[
\varphi_n \equiv \varphi(x_{n,i}) \quad \text{in} \quad B_{\varepsilon_n}(x_{n,i}).
\]

By Remark 3.6 we then have

\[
\int_\Omega \varphi_n d\mu_n = (\text{Curl} \beta_n, \varphi_n) = \int_\Omega \beta_n \nabla \varphi_n \, dx.
\]

Hence, by invoking (16), (33) and (34), we have

\[
\int_\Omega \varphi \, d\mu = \lim_{n \to \infty} \frac{1}{N_{\varepsilon_n}} \int_\Omega \varphi_n d\mu_n = \lim_{n \to \infty} \frac{1}{N_{\varepsilon_n}}(\text{Curl} \beta_n, \varphi_n) = \lim_{n \to \infty} \frac{1}{N_{\varepsilon_n}} \int_\Omega \beta_n \nabla \varphi_n \, dx = \int_\Omega A \nabla \varphi \, dx = (\text{Curl} A, \varphi).
\]

From this we conclude that \( \text{Curl} A = \mu \). Moreover, since \( A \in L^2(\Omega; M^{2 \times 2}) \), then by definition \( \text{Curl} A \in H^{-1}(\Omega; \mathbb{R}^2) \). Hence also \( \mu \in H^{-1}(\Omega; \mathbb{R}^2) \).

4.2. \( \Gamma \)-liminf inequality. We now want to prove the \( \Gamma \)-liminf inequality of Theorem 4.2. Let \( \mu_\varepsilon \in AD_{\varepsilon}(\Omega) \), \( \beta_\varepsilon \in \mathcal{AS}_\varepsilon(\mu_\varepsilon) \) and

\[
(\mu, S, A) \in (\mathcal{M}(\Omega; \mathbb{R}^2) \cap H^{-1}(\Omega; \mathbb{R}^2)) \times L^2(\Omega; M^{2 \times 2}_\text{sym}) \times L^2(\Omega; M^{2 \times 2}_\text{skew}),
\]

such that \( \text{Curl} A = \mu \). Assume that \( (\mu_\varepsilon, \beta_\varepsilon) \) converges to \( (\mu, S, A) \) in the sense of Definition 4.1. We have to show that

\[
\liminf_{\varepsilon \to 0} \mathcal{F}_\varepsilon(\mu_\varepsilon, \beta_\varepsilon) \geq \mathcal{F}(\mu, S, A).
\]

In order to do so, we decompose the energy in

\[
\frac{1}{N_{\varepsilon} \log \varepsilon} \int_\Omega W(\beta_\varepsilon) \, dx = \frac{1}{N_{\varepsilon} \log \varepsilon} \int_{\Omega_{\rho_\varepsilon}(\mu_\varepsilon)} W(\beta_\varepsilon) \, dx + \frac{1}{N_{\varepsilon} \log \varepsilon} \int_{\Omega \setminus \Omega_{\rho_\varepsilon}(\mu_\varepsilon)} W(\beta_\varepsilon) \, dx
\]

and study the two contributions separately.

Recall that \( \mu_\varepsilon = \sum_{i=1}^{M_\varepsilon} \xi_{\varepsilon,i} \delta_{x_{\varepsilon,i}} \). Since we are assuming that \( \mu_\varepsilon/N_{\varepsilon} \xrightarrow{\ast} \mu \), this implies that \( |\mu_\varepsilon|/N_{\varepsilon} \) is uniformly bounded, hence \( M_\varepsilon \leq C N_{\varepsilon} \) for some uniform constant \( C > 0 \). Moreover \( N_{\varepsilon} \rho_\varepsilon^2 \to 0 \) by hypothesis, therefore \( \chi_{\Omega_{\rho_\varepsilon}} \to 1 \) in \( L^1(\Omega) \), as

\[
\int_\Omega |\chi_{\Omega_{\rho_\varepsilon}} - 1| \, dx = \sum_{i=1}^{M_\varepsilon} |B_{\rho_\varepsilon}(x_{\varepsilon,i})| = \pi \rho_\varepsilon^2 M_\varepsilon \leq C \rho_\varepsilon^2 N_{\varepsilon}.
\]

Since \( \beta_\varepsilon \text{sym} / \sqrt{N_{\varepsilon} \log \varepsilon} \to S \), we deduce that

\[
\frac{\beta_\varepsilon \text{sym} \chi_{\Omega_{\rho_\varepsilon}}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \to S \quad \text{weakly in} \quad L^2(\Omega; M^{2 \times 2}).
\]
Hence, by weak lower semicontinuity,
\begin{equation}
\liminf_{\varepsilon \to 0} \frac{1}{N_\varepsilon \log \varepsilon} \int_{\Omega_{\mu_\varepsilon}(\mu_\varepsilon)} W(\beta_\varepsilon) \, dx = \liminf_{\varepsilon \to 0} \int_{\Omega} W \left( \frac{\beta^{\text{sym}}_{\varepsilon} \chi_{\Omega_{\mu_\varepsilon}}}{\sqrt{N_\varepsilon \log \varepsilon}} \right) \, dx \\
\geq \int_{\Omega} W(S) \, dx.
\end{equation}

Let us consider the second integral in (44). By Proposition 3.3 we have
\begin{equation}
\frac{1}{|\log \varepsilon|} \int_{\Omega \setminus \Omega_{\mu_\varepsilon}(\mu_\varepsilon)} W(\beta_\varepsilon) \, dx = \sum_{i=1}^{M_\varepsilon} \frac{1}{|\log \varepsilon|} \int_{B_{\rho_\varepsilon}(x_{\varepsilon,i})} W(\beta_\varepsilon) \, dx \\
\geq \sum_{i=1}^{M_\varepsilon} \bar{\psi}_\varepsilon(\xi_{\varepsilon,i}) = (1 + o(\varepsilon)) \sum_{i=1}^{M_\varepsilon} \psi(\xi_{\varepsilon,i}),
\end{equation}
where $o(\varepsilon) \to 0$ as $\varepsilon \to 0$. By the properties of $\varphi$ (Proposition 3.4) and by Reshetnyak’s lower semicontinuity Theorem ([1, Theorem 2.38]),
\begin{equation}
\liminf_{\varepsilon \to 0} \frac{1}{N_\varepsilon} \sum_{i=1}^{M_\varepsilon} \psi(\xi_{\varepsilon,i}) \geq \liminf_{\varepsilon \to 0} \frac{1}{N_\varepsilon} \sum_{i=1}^{M_\varepsilon} \varphi(\xi_{\varepsilon,i}) \\
\geq \liminf_{\varepsilon \to 0} \frac{1}{N_\varepsilon} \int_{\Omega} \varphi \left( \frac{d\mu}{d|\mu|} \right) \, d|\mu|.
\end{equation}

By (46)-(47) we get
\begin{equation}
\liminf_{\varepsilon \to 0} \frac{1}{N_\varepsilon \log \varepsilon} \int_{\Omega \setminus \Omega_{\mu_\varepsilon}(\mu_\varepsilon)} W(\beta_\varepsilon) \, dx \geq \int_{\Omega} \varphi \left( \frac{d\mu}{d|\mu|} \right) \, d|\mu|,
\end{equation}
that together with (45) yields the $\Gamma$-liminf inequality (43).

4.3. $\Gamma$-limsup inequality. In this section we prove the $\Gamma$-limsup inequality of Theorem 4.2. Before proceeding, we need the following technical lemma to construct the recovery sequence for the measure $\mu$. Let us first introduce some notation. For a sequence of atomic vector valued measures of the form $\nu_\varepsilon := \sum_{i=1}^{M_\varepsilon} \alpha_{\varepsilon,i} \delta_{x_{\varepsilon,i}}$ and a sequence $r_\varepsilon \to 0$, we define the corresponding diffused measures
\begin{equation}
\bar{\nu}^{r_\varepsilon}_\varepsilon := \frac{1}{\pi r^2_\varepsilon} \sum_{i=1}^{M_\varepsilon} \alpha_{\varepsilon,i} \mathcal{H}^2 \cap B_{r_\varepsilon}(x_{\varepsilon,i}) , \quad \hat{\nu}^{r_\varepsilon}_\varepsilon := \frac{1}{2\pi r_\varepsilon} \sum_{i=1}^{M_\varepsilon} \alpha_{\varepsilon,i} \mathcal{H}^1 \cap \partial B_{r_\varepsilon}(x_{\varepsilon,i}).
\end{equation}
For $x_{\varepsilon,i} \in \text{supp} \nu_\varepsilon$, define the functions $\tilde{K}^\alpha_{\varepsilon,i}, \hat{K}^\alpha_{\varepsilon,i} : B_{r_\varepsilon}(x_{\varepsilon,i}) \to \mathbb{R}^{2 \times 2}$ as
\begin{equation}
\tilde{K}^\alpha_{\varepsilon,i}(x) := \frac{1}{2\pi r^2_\varepsilon} \alpha_{\varepsilon,i} \otimes J(x - x_{\varepsilon,i}) , \quad \hat{K}^\alpha_{\varepsilon,i}(x) := \frac{1}{2\pi} \alpha_{\varepsilon,i} \otimes J \frac{x - x_{\varepsilon,i}}{|x - x_{\varepsilon,i}|^2},
\end{equation}
where $J$ is the counter-clockwise rotation of $\pi/2$. Finally define $\tilde{K}^\nu_\varepsilon, \hat{K}^\nu_\varepsilon : \Omega \to \mathbb{R}^{2 \times 2}$ as
\begin{equation}
\tilde{K}^\nu_\varepsilon := \sum_{i=1}^{M_\varepsilon} \tilde{K}^\alpha_{\varepsilon,i} \chi_{B_{r_\varepsilon}(x_{\varepsilon,i})}, \quad \hat{K}^\nu_\varepsilon := \sum_{i=1}^{M_\varepsilon} \hat{K}^\alpha_{\varepsilon,i} \chi_{B_{r_\varepsilon}(x_{\varepsilon,i})}.
\end{equation}
It is easy to show that
\begin{equation}
\text{Curl } \tilde{K}_\varepsilon = \tilde{\nu}_\varepsilon - \tilde{\nu}_\varepsilon^s, \quad \text{Curl } \hat{K}_\varepsilon = \nu_e - \hat{\nu}_\varepsilon^s.
\end{equation}

The following easy lemma will be used in some density argument in the construction of the recovery sequence.

**Lemma 4.4.** Let $n \in \mathbb{N}$, and set
\begin{equation}
S_n := \left\{ \xi := \sum_{k=1}^{M} \lambda_k \xi_k \text{ with } M \in \mathbb{N}, \xi_k \in S, \lambda_k > 0 \text{ such that } z_j := \frac{n^2 \lambda_j}{\sum \lambda_k} \in \mathbb{N} \text{ for all } j \right\}.
\end{equation}
The union of such sets is dense in $\mathbb{R}^2$.

**Lemma 4.5.** Let conditions (i), (ii) and (iii) of Section 2 hold true. Then we have:

(A) Let $n \in \mathbb{N}$, $\xi \in S_n$ defined as in (52) and let $\mu := \xi dx$. Set $\Lambda := \sum_{k=1}^{M} \lambda_k$, $r_\varepsilon := \frac{1}{2\sqrt{\Lambda \varepsilon}}$. Then, there exists a sequence $\eta_\varepsilon = \sum_{k=1}^{M} \xi_k \eta_\varepsilon^k$, with $\eta_\varepsilon^k = \sum_{l=1}^{M_{\varepsilon}^k} \delta_{x_\varepsilon,l}$, such that $\eta_\varepsilon \in AD_\varepsilon(\Omega)$, and
\begin{equation}
\frac{|\eta_\varepsilon^k|}{N_\varepsilon} \rightarrow \lambda_k dx \quad \text{in } \mathcal{M}(\Omega; \mathbb{R}), \quad \frac{\eta_\varepsilon}{N_\varepsilon} \rightharpoonup \mu \quad \text{in } \mathcal{M}(\Omega; \mathbb{R}^2),
\end{equation}
for some constant $C$ independent of $n$, where the measure $\hat{\eta}_\varepsilon^s$ is defined according to (18).

(B) Let $\mu$, $r_\varepsilon$ as in (A), let $g \in C^0(\Omega; \mathbb{R}^2)$ and set $\sigma := g(x) dx$. Then, there exists a sequence $\eta_\varepsilon$ satisfying all the properties in (A) and a sequence $\sigma_\varepsilon = \sum \zeta_\varepsilon \delta_\varepsilon \delta_{x_\varepsilon,l}$, with $\zeta_\varepsilon, \delta_\varepsilon \in S$, such that $\text{supp}(\sigma_\varepsilon) \cap \text{supp}(\eta_\varepsilon) = \emptyset$, $\eta_\varepsilon + \sigma_\varepsilon \in AD_\varepsilon(\Omega)$ and
\begin{equation}
\frac{\sigma_\varepsilon}{\sqrt{N_\varepsilon} \log \varepsilon} \rightharpoonup \sigma \quad \text{in } \mathcal{M}(\Omega; \mathbb{R}^2), \quad \frac{\tilde{\sigma}_\varepsilon}{\sqrt{N_\varepsilon} \log \varepsilon} \rightarrow \sigma \quad \text{in } H^{-1}(\Omega; \mathbb{R}^2),
\end{equation}
where the measures $\tilde{\eta}_\varepsilon^s$ are defined according to (48).

In particular there exists a constant $C > 0$ such that
\begin{equation}
H_\varepsilon \leq C \sqrt{N_\varepsilon} \log \varepsilon, \quad M_\varepsilon \leq CN_\varepsilon,
\end{equation}
where $M_\varepsilon := \sum_{k=1}^{M} M_{\varepsilon}^k$.

**Proof.** **Step 1.** Proof of (A), the case $M = 1$ and $\mu = \xi dx$ with $\xi \in S$.

We cover $\mathbb{R}^2$ with squares of side length $2r_\varepsilon$. Divide each of them in four squares of side length $r_\varepsilon$, and plug a mass $\xi \delta_{x_\varepsilon,l}$ at the centre of one of such $r_\varepsilon$-squares, obtaining in this way a measure $\nu_\varepsilon$ on $\mathbb{R}^2$ which is $2r_\varepsilon$ periodic. We notice that we leave some free space just in order to accomplish also point (B). Then we define $\eta_\varepsilon$ as the restriction of $\nu_\varepsilon$ on all the $2r_\varepsilon$-squares contained in $\Omega$ (see Figure 5). Notice that $\eta_\varepsilon \in AD_\varepsilon(\Omega)$ since $r_\varepsilon \gg 2\rho_\varepsilon$. Also, the density of $\frac{1}{N_\varepsilon} \hat{\eta}_\varepsilon^s - \mu$ has zero average on each $2r_\varepsilon$-square, so that it converges to zero weakly in $L^2(\Omega; \mathbb{R}^2)$ and (53) is verified.
Let \( v_\varepsilon : \mathbb{R}^2 \to \mathbb{R}^2 \) be the \( 2r_\varepsilon \)-periodic solution to \( \Delta v_\varepsilon = \frac{1}{N_\varepsilon} v_\varepsilon - \mu \). By construction it is easy to see that
\[
\left\| \frac{1}{N_\varepsilon} \tilde{v}_\varepsilon - \frac{1}{N_\varepsilon} \tilde{\eta}_\varepsilon - \frac{1}{N_\varepsilon} \tilde{\nu}_\varepsilon \right\|_{H^{-1}(\Omega; \mathbb{R}^2)} \leq C r_\varepsilon.
\]
These last estimates clearly imply (54).

**Step 2.** Proof of (A), the general case \( \xi \in S_n \).

Cover \( \mathbb{R}^2 \) with squares of side length \( 2nr_\varepsilon \), and divide each of them in four squares of side length \( r_\varepsilon \). As in Step 1, pick one of these \( nr_\varepsilon \)-squares in all \( 2nr_\varepsilon \)-squares in a periodic manner. Finally, divide each of these selected \( nr_\varepsilon \)-squares in \( n^2 \) squares of side length \( r_\varepsilon \).

Now, plug at the centres of each of these \( n^2 \) squares a mass \( \xi_k \delta_{x_{\varepsilon,i}} \) with \( 1 \leq k \leq M \), in such a way that the resulting measure \( \nu_\varepsilon \) is \( 2nr_\varepsilon \)-periodic, and on each \( 2nr_\varepsilon \)-square there are exactly \( z_k \) masses with weight \( \xi_k \), where \( z_k \) is defined in (52). Then, defining \( \eta_\varepsilon \) as the restriction of \( \nu_\varepsilon \) on the union of all \( 2nr_\varepsilon \)-squares contained in \( \Omega \), and arguing as in the proof of Step 1, we have that (53) holds true, while (57) holds true with \( C \) replaced by \( nC \), so that (54) follows.

**Step 3.** Proof of (B).

We have at disposal \( CN_\varepsilon \) squares of side length \( nr_\varepsilon \), left free from the constructions in Step 2. Clearly, we can plug masses with weights in \( S \) at the centre of \( c \sqrt{N_\varepsilon \log \varepsilon} \) of such free squares, in such a way that (55) holds true.

We are now ready to prove the \( \Gamma \)-limsup inequality of Theorem 4.2.

**Proof of \( \Gamma \)-limsup inequality of Theorem 4.2.** Let
\[
(\mu, S, A) \in (\mathcal{M}(\Omega; \mathbb{R}^2) \cap H^{-1}(\Omega; \mathbb{R}^2)) \times L^2(\Omega; M_2^{2\times2}) \times L^2(\Omega; M_{2\text{skew}}^2),
\]
with \( \text{Curl} \ A = \mu \). We will construct a recovery sequence in three steps.

**Step 1.** The case \( \mu = \xi \, dx \) with \( S \in C^1(\overline{\Omega}; M_2^{2\times2}) \).
In this step we assume that \( \mu := \xi dx, A \in L^2(\Omega; M^{2 \times 2}_{\text{skew}}) \) with \( \text{Curl } A = \mu \) and \( S \in C^1(\Omega; M^{2 \times 2}_{\text{sym}}) \). We will construct a recovery sequence \( \mu_\varepsilon \in AD_{\varepsilon}(\Omega), \beta_\varepsilon \in AS_{\varepsilon}(\mu_\varepsilon) \), such that \( (\mu_\varepsilon, \beta_\varepsilon) \) converges to \( (\mu, S, A) \) in the sense of Definition 4.1 and

\[
\limsup_{\varepsilon \to 0} \frac{1}{N_\varepsilon |\log \varepsilon|} \int_\Omega W(\beta_\varepsilon) \, dx \leq \int_\Omega (W(S) + \varphi(\xi)) \, dx.
\]

By Proposition 3.4, there exist \( \lambda_k \geq 0, \xi_k \in \mathbb{S}, M \in \mathbb{N} \), such that \( \xi = \sum_{k=1}^M \lambda_k \xi_k \) and

\[
\varphi(\xi) = \sum_{k=1}^M \lambda_k \psi(\xi_k),
\]

where \( \varphi \) is the self-energy defined in (28). By standard density arguments in \( \Gamma \)-convergence, we will assume without loss of generality that \( \xi \in \mathbb{S}_n \) is as in (52) for some \( n \in \mathbb{N} \).

Set \( \sigma := \text{Curl } S \). Since \( S \in C^1(\Omega; M^{2 \times 2}_{\text{sym}}) \), then \( \sigma = g(x) \, dx \) for some continuous function \( g: \Omega \to \mathbb{R}^2 \). Let \( \eta_\varepsilon := \sum_{i=1}^M \xi \delta_{\varepsilon,i}, \sigma_\varepsilon := \sum_{i=1}^M \sigma_{\varepsilon,i}, \) and \( \varepsilon = C/\sqrt{N_\varepsilon} \) be the sequences given by Lemma 4.5 (B). Set \( \mu_\varepsilon := \eta_\varepsilon + \sigma_\varepsilon \). By (53), (55) and the hypothesis \( N_\varepsilon \gg |\log \varepsilon|, \mu_\varepsilon \) is a recovery sequence for \( \mu \).

Let \( \eta^*_\varepsilon, \eta^{**}_\varepsilon, \tilde{\sigma}_\varepsilon, \tilde{\sigma}^*_\varepsilon \) be defined according to (48). Notice that \( \hat{K}_{\varepsilon,i} \in AS_{\varepsilon,p_\varepsilon}(\xi_{\varepsilon,i}) \) and it satisfies (27). Therefore, by Proposition 3.3, there exist strains \( \hat{A}_{\varepsilon,i} \) such that

(i) \( \hat{A}_{\varepsilon,i} \in AS_{\varepsilon,p_\varepsilon}(\xi_{\varepsilon,i}) \),

(ii) \( \hat{A}_{\varepsilon,i} \cdot t = \hat{K}_{\varepsilon,i} \cdot t \) on \( \partial B_{\varepsilon}(x_{\varepsilon,i}) \cup \partial B_{p_\varepsilon}(x_{\varepsilon,i}) \),

and

\[
\frac{1}{|\log \varepsilon|} \int_{B_{p_\varepsilon}(x_{\varepsilon,i}) \setminus B_{\varepsilon}(x_{\varepsilon,i})} W(\hat{A}_{\varepsilon,i}) \, dx = \psi(\xi_{\varepsilon,i})(1 + o(\varepsilon)).
\]

Now extend \( \hat{A}_{\varepsilon,i} \) to \( \hat{K}_{\varepsilon,i} \) in \( B_{\varepsilon}(x_{\varepsilon,i}) \setminus B_{p_\varepsilon}(x_{\varepsilon,i}) \) and zero in \( \Omega \setminus (B_{\varepsilon}(x_{\varepsilon,i}) \setminus B_{\varepsilon}(x_{\varepsilon,i})) \).

Set

\[
\hat{S}_\varepsilon := \sum_{i=1}^M \hat{K}_{\varepsilon,i} \chi_{B_{\varepsilon}(y_{\varepsilon,i}) \setminus B_{\varepsilon}(y_{\varepsilon,i})}, \quad \hat{A}_\varepsilon := \sum_{i=1}^M \hat{A}_{\varepsilon,i}.
\]

Hence, recalling definition (48) we have

\[
\text{Curl } \hat{S}_\varepsilon = -\tilde{\sigma}^*_\varepsilon + \tilde{\sigma}_\varepsilon, \quad \text{Curl } \hat{A}_\varepsilon = -\eta^{**}_\varepsilon + \eta^*_\varepsilon.
\]

Define \( Q_\varepsilon := J \nabla u_\varepsilon, R_\varepsilon := J \nabla v_\varepsilon \) where \( u_\varepsilon, v_\varepsilon \) solve

\[
\begin{cases}
\Delta u_\varepsilon = \tilde{\sigma}^*_\varepsilon - \sqrt{N_\varepsilon} |\log \varepsilon| \sigma & \text{in } \Omega, \\
\frac{\partial u_\varepsilon}{\partial \nu} = C_{u,\varepsilon} & \text{on } \partial \Omega, \\
\frac{\partial v_\varepsilon}{\partial \nu} = C_{v,\varepsilon} & \text{on } \partial \Omega,
\end{cases}
\]

where the constants \( C_{u,\varepsilon}, C_{v,\varepsilon} \) satisfy the compatibility condition

\[
\int_{\partial \Omega} C_{u,\varepsilon} \, ds = \int_{\Omega} \tilde{\sigma}^*_\varepsilon - \sqrt{N_\varepsilon} |\log \varepsilon| \sigma \, dx, \quad \int_{\partial \Omega} C_{v,\varepsilon} \, ds = \int_{\Omega} \eta^{**}_\varepsilon - N_\varepsilon \mu \, dx.
\]

In this way,

\[
\text{Curl } Q_\varepsilon = \tilde{\sigma}^*_\varepsilon - \sqrt{N_\varepsilon} |\log \varepsilon| \sigma, \quad \text{Curl } R_\varepsilon = \eta^{**}_\varepsilon - N_\varepsilon \mu.
\]
Notice that by construction \( \frac{1}{\sqrt{N_{\varepsilon}}} |C_{a,\varepsilon}| + |C_{v,\varepsilon}| \to 0 \) as \( \varepsilon \to 0 \). Therefore, using also (54), (55) and standard elliptic estimates, we have

\[
\frac{Q_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \to 0, \quad \frac{R_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \to 0 \quad \text{in} \quad L^2(\Omega; \mathbb{M}^{2 \times 2}).
\]

Also notice that

\[
\frac{Q_{\varepsilon} + R_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \cdot t \to 0 \quad \text{in} \quad H^{-1/2}(\partial \Omega; \mathbb{R}^2) \cap L^1(\partial \Omega; \mathbb{R}^2).
\]

We can now define the candidate recovery sequence as

\[
\mu_{\varepsilon} = \eta_{\varepsilon} + \sigma_{\varepsilon}, \quad \beta_{\varepsilon} := (S_{\varepsilon} + A_{\varepsilon}) \chi_{\Omega_{\varepsilon}(\mu_{\varepsilon})},
\]

where

\[
S_{\varepsilon} := \sqrt{N_{\varepsilon} \log \varepsilon} S + \tilde{S}_{\varepsilon} - \tilde{K}^{\sigma_{\varepsilon}} + Q_{\varepsilon},
\]

\[
A_{\varepsilon} := N_{\varepsilon} A + \hat{A}_{\varepsilon} - \tilde{K}^{\eta_{\varepsilon}} + R_{\varepsilon}.
\]

By definition and (51), (62), (64), it is immediate to check that

\[
\text{Curl } S_{\varepsilon} = \hat{\sigma}_{\varepsilon}, \quad \text{Curl } A_{\varepsilon} = \hat{\eta}_{\varepsilon} \quad \text{in} \quad \Omega.
\]

Recalling that \( \mu_{\varepsilon} = \eta_{\varepsilon} + \sigma_{\varepsilon} \), we deduce that

\[
\text{Curl } \beta_{\varepsilon} = \hat{\eta}_{\varepsilon} + \hat{\sigma}_{\varepsilon} = \hat{\mu}_{\varepsilon} \quad \text{in} \quad \Omega, \quad \text{Curl } \beta_{\varepsilon} \subset \Omega_{\varepsilon}(\mu_{\varepsilon}) = 0.
\]

Moreover, the circulation condition \( \int_{\partial B_{\varepsilon}(x)} \beta_{\varepsilon} \cdot t \, ds = \mu_{\varepsilon}(x) \) is satisfied for every point \( x \in \text{supp } \mu_{\varepsilon} \). Hence \( \beta_{\varepsilon} \in AS_{\varepsilon}(\mu_{\varepsilon}) \).

In order for \( (\mu_{\varepsilon}, \beta_{\varepsilon}) \) to be the desired recovery sequence, we need to prove that

\[
\frac{\beta^{\text{sym}}_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \rightharpoonup S \quad \text{weakly in} \quad L^2(\Omega; \mathbb{M}^{2 \times 2}),
\]

\[
\frac{\beta^{\text{skew}}_{\varepsilon}}{N_{\varepsilon}} \rightharpoonup A \quad \text{weakly in} \quad L^2(\Omega; \mathbb{M}^{2 \times 2}),
\]

\[
\lim_{\varepsilon \to 0} \frac{1}{N_{\varepsilon} \log \varepsilon} \int_{\Omega} W(\beta_{\varepsilon}) \, dx = \int_{\Omega} (W(S) + \varphi(\xi)) \, dx.
\]

In view of (65)-(69), in order to prove (70), (71) we have to show that

\[
\frac{\hat{A}_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \to 0 \quad \text{in} \quad L^2(\Omega; \mathbb{M}^{2 \times 2}),
\]

\[
\frac{\hat{S}_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}}, \quad \frac{\tilde{K}^{\sigma_{\varepsilon}}_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}}, \quad \frac{\tilde{K}^{\eta_{\varepsilon}}_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \to 0 \quad \text{in} \quad L^2(\Omega; \mathbb{M}^{2 \times 2}).
\]
We have
\[
\int_{\Omega_{\mu_s}(\mu)} \frac{\left| \hat{A}_\varepsilon \right|^2}{N_\varepsilon \log \varepsilon} d\varepsilon = \frac{1}{N_\varepsilon \log \varepsilon} \sum_{i=1}^{M_\varepsilon} \int_{B_{r_\varepsilon}(x_{\varepsilon,i}) \setminus B_{p_\varepsilon}(x_{\varepsilon,i})} \left| \hat{K}_{\varepsilon,i}^{\varepsilon} \right|^2 d\varepsilon
\]
\[
\leq \frac{C}{N_\varepsilon \log \varepsilon} \sum_{i=1}^{M_\varepsilon} \int_{B_{r_\varepsilon}(x_{\varepsilon,i}) \setminus B_{p_\varepsilon}(x_{\varepsilon,i})} |x - x_{\varepsilon,i}|^{-2} d\varepsilon
\]
\[
\leq C \frac{M_\varepsilon (\log r_\varepsilon - \log \rho_\varepsilon)}{N_\varepsilon \log \varepsilon} \leq C \frac{\log r_\varepsilon - \log \rho_\varepsilon}{\log \varepsilon} \to 0,
\]
as \varepsilon \to 0, where the last inequality follows from (56). Moreover, by (75), (53), (60), (59), and the definition of \( \mu_\varepsilon \) given by Lemma 4.5, we have
\[
\lim_{\varepsilon \to 0} \frac{1}{N_\varepsilon \log \varepsilon} \int_{\Omega} W(\hat{A}_\varepsilon) d\varepsilon = \lim_{\varepsilon \to 0} \frac{1}{N_\varepsilon \log \varepsilon} \int_{\Omega} W(\hat{A}_\varepsilon) d\varepsilon
\]
\[
= \lim_{\varepsilon \to 0} \frac{1}{N_\varepsilon} \sum_{k=1}^{M} \psi(\xi_{\varepsilon,i})(1 + o(\varepsilon)) = \lim_{\varepsilon \to 0} \frac{1}{N_\varepsilon} \sum_{k=1}^{M} |\eta_k(\Omega) \psi(\xi_k)(1 + o(\varepsilon))|
\]
\[
= |\Omega| \sum_{k=1}^{M} \lambda_k \psi(\xi_k) = \int_{\Omega} \varphi(\xi) d\xi.
\]
From (14), (75), (76) we conclude that \( \hat{A}_\varepsilon / \sqrt{N_\varepsilon \log \varepsilon} \) is bounded in \( L^2(\Omega; M^{2 \times 2}) \) and its energy is concentrated in the hard core region. We easily deduce that (73) holds true.

We pass to the proof of (74). One can readily see that
\[
\int_{\Omega} \frac{\left| \hat{K}_\varepsilon^{\sigma_\varepsilon} \right|^2}{N_\varepsilon \log \varepsilon} d\varepsilon \leq \frac{C}{N_\varepsilon \log \varepsilon} \sum_{i=1}^{M_\varepsilon} \frac{1}{r_\varepsilon^2} \int_{B_{r_\varepsilon}(x_{\varepsilon,i})} |x - x_{\varepsilon,i}|^2 d\varepsilon = C \frac{M_\varepsilon}{N_\varepsilon \log \varepsilon} \to 0
\]
as \varepsilon \to 0. The statement for \( \hat{K}_\varepsilon^{\eta_\varepsilon} \) can be proved in a similar way. Finally, since \( H_\varepsilon \ll N_\varepsilon \) by (56), we have
\[
\int_{\Omega} \frac{\left| \hat{S}_\varepsilon \right|^2}{N_\varepsilon \log \varepsilon} d\varepsilon \leq C \frac{H_\varepsilon \log r_\varepsilon - \log \varepsilon}{N_\varepsilon \log \varepsilon} \to 0
\]
which concludes the proof of (74).

We are left to prove (72). By the symmetries of the elasticity tensor \( C \) and definition (67), we have
\[
\frac{W(\beta_\varepsilon)}{N_\varepsilon \log \varepsilon} = W\left( S + \frac{\hat{S}_\varepsilon}{\sqrt{N_\varepsilon \log \varepsilon}} - \frac{\hat{K}_\varepsilon^{\sigma_\varepsilon}}{\sqrt{N_\varepsilon \log \varepsilon}} + \frac{Q_\varepsilon}{\sqrt{N_\varepsilon \log \varepsilon}} + \frac{\hat{A}_\varepsilon}{\sqrt{N_\varepsilon \log \varepsilon}} - \frac{\hat{K}_\varepsilon^{\eta_\varepsilon}}{\sqrt{N_\varepsilon \log \varepsilon}} + \frac{R_\varepsilon}{\sqrt{N_\varepsilon \log \varepsilon}} \right)
\]
By (74) and (65), we get
\[
\lim_{\varepsilon \to 0} \frac{1}{N_{\varepsilon} \log \varepsilon} \int_{\Omega} W(\beta_{\varepsilon}) \, dx = \lim_{\varepsilon \to 0} \int_{\Omega} W \left( S + \frac{\hat{A}_{\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \right) \, dx.
\]
By recalling (73) and (76), (73), by Hölder inequality we deduce (72).

**Step 2.** The case \( \mu = \sum_{l=1}^{L} \chi_{\Omega_l} \xi_l \, dx \) and \( S \in C^{1}(\Omega; M_{\text{sym}}^{2 \times 2}) \).

In this step we assume that \( S \in C^{1}(\Omega; M_{\text{sym}}^{2 \times 2}) \) and \( A \in L^{2}(\Omega; M_{\text{skew}}^{2 \times 2}) \) with \( \mu := \text{Curl} \, A \) locally constant, i.e., \( \mu = \sum_{l=1}^{L} \chi_{\Omega_l} \xi_l \, dx \), with \( \xi_l \in \mathbb{R}^{2} \) and with \( \Omega_l \subset \Omega \) that are Lipschitz pairwise disjoint domains such that \( |\Omega \setminus \bigcup_{l=1}^{L} \Omega_l| = 0 \). We will construct the recovery sequence by combining the previous step with classical localisation arguments of \( \Gamma \)-convergence.

Let \( S_l := S \setminus \Omega_l \), \( A_l := A \setminus \Omega_l \), \( \mu_l := \mu \setminus \Omega_l = \xi_l \, dx \). Denote by \( (\mu_{l,\varepsilon}, \beta_{l,\varepsilon}) \) the recovery sequence for \( (\mu_l, S_l, A_l) \) given by Step 1. We can now define \( \mu_{\varepsilon} \in \mathcal{M}(\Omega; \mathbb{R}^{2}) \) and \( \beta_{\varepsilon}: \Omega \to M_{\text{sym}}^{2 \times 2} \) as
\[
\beta_{\varepsilon} := \sum_{l=1}^{L} \chi_{\Omega_l} \beta_{l,\varepsilon} \quad \mu_{\varepsilon} := \sum_{l=1}^{L} \mu_{l,\varepsilon}.
\]
By construction \( \mu_{\varepsilon} \in AD_{\varepsilon}(\Omega) \) and \( \beta_{\varepsilon} \) satisfies the circulation condition on every \( \partial B_{\varepsilon}(x_{\varepsilon}) \), with \( x_{\varepsilon} \in \text{supp} \, \mu_{\varepsilon} \). Also notice that on each set \( \Omega_l \) belonging to the partition of \( \Omega \), we have
\[
\text{Curl} \, \beta_{\varepsilon} \subset \Omega_l \left( \mu_{\varepsilon} \right) = 0.
\]
However \( \text{Curl} \, \beta_{\varepsilon} \) could concentrate on the intersection region between two elements of the partition \( \{ \Omega_l \}_{l=1}^{L} \). To overcome this problem, it is sufficient to notice that by construction
\[
\left\| \frac{\text{Curl} \, \beta_{\varepsilon} \subset \Omega_{\varepsilon}(\mu_{\varepsilon})}{\sqrt{N_{\varepsilon} \log \varepsilon}} \right\|_{H^{-1}(\Omega; \mathbb{R}^{2})} \leq \sum_{l=1}^{L} \left\| \beta_{l,\varepsilon} - \sqrt{N_{\varepsilon} \log \varepsilon} S - \frac{\sqrt{N_{\varepsilon} \log \varepsilon}}{t} \right\|_{H^{-1/2}(\partial \Omega; \mathbb{R}^{2})}.
\]
\[
= \sum_{l=1}^{L} \left\| \frac{Q_{l,\varepsilon} + R_{l,\varepsilon}}{\sqrt{N_{\varepsilon} \log \varepsilon}} \right\|_{H^{-1/2}(\partial \Omega; \mathbb{R}^{2})},
\]
where \( Q_{l,\varepsilon}, R_{l,\varepsilon} \) are defined according to (63), with \( \Omega \) replaced by \( \Omega_l \). Therefore by (66),
\[
\frac{\text{Curl} \, \beta_{\varepsilon} \subset \Omega_{\varepsilon}(\mu_{\varepsilon})}{\sqrt{N_{\varepsilon} \log \varepsilon}} \to 0 \quad \text{strongly in} \quad H^{-1}(\Omega; \mathbb{R}^{2}).
\]
Hence we can add a vanishing perturbation to \( \beta_{\varepsilon} \) (on the scale \( \sqrt{N_{\varepsilon} \log \varepsilon} \)), in order to obtain the desired recovery sequence in \( AD_{\varepsilon}(\mu_{\varepsilon}) \).

**Step 3.** The general case.

Let \( (\mu, S, A) \) be in the domain of the \( \Gamma \)-limit \( \mathcal{F} \). In view of Step 2 and by standard density arguments of \( \Gamma \)-convergence, it is sufficient to find sequences \( (\mu_{n}, S_{n}, A_{n}) \) such that \( \mu_{n} \) is locally constant as in Step 2,
\[
S_{n} \in C^{1}(\Omega; M_{\text{sym}}^{2 \times 2}), \quad A_{n} \in L^{2}(\Omega; M_{\text{skew}}^{2 \times 2}), \quad \text{with} \quad \text{Curl} \, A_{n} = \mu_{n},
\]
and such that
\[(79) \quad S_n \to S, \quad A_n \to A \text{ in } L^2(\Omega; M^{2 \times 2}), \quad \mu_n \rightharpoonup^* \mu \text{ in } \mathcal{M}(\Omega; \mathbb{R}^2), \quad |\mu_n|(\Omega) \to |\mu|(\Omega),\]
where \(S\) and \(A\) are the symmetric and antisymmetric part of \(\beta\), respectively. In fact, we have to show that \((79)\) implies \((80)\)
\[
\lim_{n \to \infty} F(\mu_n, \beta_n) = F(\mu, S, A).
\]
Since \(S_n \to S\) strongly in \(L^2(\Omega; M^{2 \times 2})\), then
\[
\lim_{n \to \infty} \int_{\Omega} W(S_n) \, dx = \int_{\Omega} W(S) \, dx.
\]
Also, \(|\mu_n|(\Omega) \to |\mu|(\Omega)\) implies
\[
\lim_{n \to \infty} \int_{\Omega} \varphi \left( \frac{d\mu_n}{d|\mu_n|} \right) d|\mu_n| = \int_{\Omega} \varphi \left( \frac{d\mu}{d|\mu|} \right) d|\mu|,
\]
by Reshetnyak’s Theorem ([1, Theorem 2.39]), so that \((80)\) is proved.

Let us then proceed to the construction of the sequences \(S_n, A_n\) and \(\mu_n\) satisfying properties \((78)-(79)\). Clearly, we can approximate \(S\) in \(L^2(\Omega; M^{2 \times 2})\) with a sequence \(S_n \in C^1(\Omega; M^{2 \times 2})\). Then, by Remark (4.3), writing \(A\) as in \((35)\) we have that \(u\) is in \(BV(\Omega) \cap L^2(\Omega)\). Therefore, by standard density results in \(BV\) we can find a sequence of piecewise affine functions \(u_n\) with
\[
u_n \to u \text{ in } L^2(\Omega), \quad D\nu_n \rightharpoonup D\mu = \mu, \quad |D\nu_n|(\Omega) \to |D\mu|(\Omega) = |\mu|(\Omega).
\]
Setting \(\mu_n := D\nu_n\) and \(A_n\) as in \((35)\) with \(u\) replaced by \(u_n\), it is readily seen that \(\mu_n\) is piecewise constant, and that \((78)\) and \((79)\) holds true, and this concludes the proof of the \(\Gamma\)-limsup inequality. \(\square\)

**Remark 4.6.** Recalling \((66)\) and inspecting the density arguments in Step 3 above, we notice that we can provide a recovery sequence \(\beta_\varepsilon\) for the limit strain \(\beta = S + A\) such that
\[
\frac{\beta_\varepsilon}{N_\varepsilon} \cdot t \to A \cdot t \text{ in } H^{-1/2}(\partial \Omega; \mathbb{R}^2) \cap L^1(\partial \Omega; \mathbb{R}^2).
\]

5. Relaxed Dirichlet-type boundary conditions

The aim of this section is to add a Dirichlet type boundary condition to the \(\Gamma\)-convergence statement of Theorem 4.2. Fix a boundary condition
\[
g_A \in L^2(\Omega; M^{2 \times 2}_{\text{skew}}) : \text{Curl } g_A \in H^{-1}(\Omega; \mathbb{R}^2) \cap \mathcal{M}(\Omega; \mathbb{R}^2).
\]

The rescaled energy functionals \(F^\varepsilon_{g_A} : \mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; M^{2 \times 2}) \to \mathbb{R}\), taking into account the boundary conditions, are defined by
\[
F^\varepsilon_{g_A}(\mu, \beta) := \frac{1}{N_\varepsilon |\log \varepsilon|} E_\varepsilon(\mu, \beta) + \int_{\partial \Omega} \varphi \left( \left( g_A - \frac{\beta}{N_\varepsilon} \right) \cdot t \right) ds
\]
if $\mu \in \mathcal{AD}_e(\Omega)$, $\beta \in \mathcal{AS}_e(\mu)$, and $+\infty$ otherwise, while the candidate $\Gamma$-limit is the functional

$$\mathcal{F}^{g_A} : (H^{-1}(\Omega; \mathbb{R}^2) \cap \mathcal{M}(\Omega; \mathbb{R}^2)) \times L^2(\Omega; \mathbb{M}^{2 \times 2}) \times L^2(\Omega; \mathbb{M}^{2 \times 2}_{skew}) \to \mathbb{R},$$

with

$$\mathcal{F}^{g_A}(\mu, S, A) := \int_{\Omega} W(S) \, dx + \int_{\Omega} \varphi \left( \frac{d\mu}{|d\mu|} \right) \, d|\mu| + \int_{\partial\Omega} \varphi((g_A - A) \cdot t) \, ds,$$

if $\text{Curl} \, A = \mu$ and $\mathcal{F}^{g_A}(\mu, S, A) := \infty$ otherwise. Here $ds$ coincides with $\mathcal{H}^1 \ll \partial\Omega$. The boundary term appearing in the definition of $\mathcal{F}^{g_A}$ and $\mathcal{F}^{g_A}$ are intended in the sense of traces of $BV$ functions (see [11]). Indeed, since $A$ and $g_A$ are antisymmetric, there exist $u, a \in L^2(\Omega)$ such that

$$A = \begin{pmatrix} 0 & u \\ -u & 0 \end{pmatrix}, \quad g_A = \begin{pmatrix} 0 & a \\ -a & 0 \end{pmatrix},$$

Notice that $\text{Curl} \, A = Du$ and $\text{Curl} \, g_A = Da$ in the sense of distributions. Therefore, as already observed in Remark 4.3, conditions $\text{Curl} \, A$, $\text{Curl} \, g_A \in \mathcal{M}(\Omega; \mathbb{R}^2)$ imply that $a, u \in BV(\Omega)$. Hence $a$ and $u$ admit traces on $\partial\Omega$ that belong to $L^1(\partial\Omega; \mathbb{R}^2)$. By noting that

$$\int_{\partial\Omega} \varphi((g_A - A) \cdot t) \, ds = \int_{\partial\Omega} \varphi((u - a) \nu) \, ds,$$

where $\nu$ is the inner normal to $\Omega$, we conclude that the definition of $\mathcal{F}^{g_A}$ is well-posed, as well as the definition of $\mathcal{F}^{g_A}$.

We are now ready to state the $\Gamma$-convergence result with boundary conditions.

**Theorem 5.1.** The following $\Gamma$-convergence statement holds with respect to the convergence of Definition 4.4.

(i) (Compactness) Let $\varepsilon_n \to 0$ and assume that $(\mu_n, \beta_n) \in \mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; \mathbb{M}^{2 \times 2})$ is such that $\sup_n \mathcal{F}^{g_A}_{\varepsilon_n}(\mu_n, \beta_n) \leq E$, for some positive constant $E$. Then there exists $(\mu, S, A) \in (H^{-1}(\Omega; \mathbb{R}^2) \cap \mathcal{M}(\Omega; \mathbb{R}^2)) \times L^2(\Omega; \mathbb{M}^{2 \times 2}) \times L^2(\Omega; \mathbb{M}^{2 \times 2}_{skew})$ such that $(\mu_n, \beta_n)$ converges to $(\mu, S, A)$ in the sense of Definition 4.4. Moreover $\mu \in H^{-1}(\Omega; \mathbb{R}^2)$ and $\text{Curl} \, A = \mu$.

(ii) (\(\Gamma\)-convergence) The energy functionals $\mathcal{F}^{g_A}_{\varepsilon}$ defined in (83) \(\Gamma\)-converge with respect to the convergence of Definition 4.4 to the functional $\mathcal{F}^{g_A}$ defined in (85). Specifically, for every $(\mu, S, A) \in (\mathcal{M}(\Omega; \mathbb{R}^2) \cap H^{-1}(\Omega; \mathbb{R}^2)) \times L^2(\Omega; \mathbb{M}^{2 \times 2}) \times L^2(\Omega; \mathbb{M}^{2 \times 2}_{skew})$ such that $\text{Curl} \, A = \mu$, we have:

- (\(\Gamma\)-liminf inequality) for every sequence $(\mu_\varepsilon, \beta_\varepsilon) \in (\mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; \mathbb{M}^{2 \times 2}))$ converging to $(\mu, S, A)$ in the sense of Definition 4.4, we have

  $$\mathcal{F}^{g_A}(\mu, S, A) \leq \liminf_{\varepsilon \to 0} \mathcal{F}^{g_A}_{\varepsilon}(\mu_\varepsilon, \beta_\varepsilon).$$

- (\(\Gamma\)-limsup inequality) there exists a recovery sequence $(\mu_\varepsilon, \beta_\varepsilon) \in (\mathcal{M}(\Omega; \mathbb{R}^2) \times L^2(\Omega; \mathbb{M}^{2 \times 2}))$ such that $(\mu_\varepsilon, \beta_\varepsilon)$ converges to $(\mu, S, A)$ in the sense of Definition 4.4.
The compactness statement readily follows from the compactness of Theorem 4.2, since $F_{\varepsilon}^{gA}(\mu, \beta) \geq F_{\varepsilon}(\mu, \beta)$. Let us proceed with the proof of the $\Gamma$-convergence result.

Proof of $\Gamma$-lim sup inequality of Theorem 5.1. Let $(\mu, S, A)$ be given in the domain of the $\Gamma$-limit $F^{gA}$. We will construct a recovery sequence in two steps, relying on Theorem 4.2.

Step 1. Approximation of the boundary values.

For $\delta > 0$ fixed, set $\omega_{\delta} := \{ x \in \Omega : \text{dist}(x, \partial \Omega) > \delta \}$, so that $\omega_{\delta} \subset\subset \Omega$, and assume without loss of generality that $w_{\delta}$ is Lipschitz. Define $S_{\delta} \in L^{2}(\Omega; \mathbb{M}_{2}^{2 \times 2})$ and $A_{\delta} \in L^{2}(\Omega; \mathbb{M}_{2}^{2 \times 2})$ as

$$A_{\delta} := \begin{cases} A & \text{in } \omega_{\delta}, \\ g_{A} & \text{in } \Omega \setminus \omega_{\delta}, \end{cases} \quad S_{\delta} := \begin{cases} S & \text{in } \omega_{\delta}, \\ 0 & \text{in } \Omega \setminus \omega_{\delta}. \end{cases}$$

Further, let $\mu_{\delta} \in \mathcal{M}(\Omega; \mathbb{R}^{2})$ be such that

$$\mu_{\delta} := \mu \mathbb{1}_{\omega_{\delta}} + \text{Curl } g_{A} \mathbb{1}_{\Omega \setminus \omega_{\delta}} + (g_{A} - A) \cdot t \mathcal{H}^{1} \mathbb{1}_{\partial \omega_{\delta}}.$$

Notice that

$$\text{Curl } A_{\delta} = \mu_{\delta} \quad \text{and} \quad \mu_{\delta} \in H^{-1}(\Omega; \mathbb{R}^{2}),$$

therefore $(\mu_{\delta}, S_{\delta}, A_{\delta})$ belongs to the domain of the functional $F$. Also note that

$$S_{\delta} \to S, \quad A_{\delta} \to A \text{ in } L^{2}(\Omega; \mathbb{M}_{2}^{2 \times 2}),$$

$$\mu_{\delta} \xrightarrow{\ast} \mu \text{ in } \mathcal{M}(\Omega; \mathbb{R}^{2}), \quad |\mu_{\delta}|(\Omega) \to |\mu|(\Omega) + \int_{\partial \Omega} |(g_{A} - A) \cdot t| ds,$$

as $\delta \to 0$. Therefore, by Reshetnyak’s Theorem (see [1, Theorem 2.39]), we have

$$\lim_{\delta \to 0} F(\mu_{\delta}, S_{\delta}, A_{\delta}) = F^{gA}(\mu, S, A).$$

It will now be sufficient to construct dislocation measures $\mu_{\delta, \varepsilon}$ and strains $\beta_{\delta, \varepsilon}$ such that

$$\lim_{\varepsilon \to 0} F_{\varepsilon}(\mu_{\delta, \varepsilon}, \beta_{\delta, \varepsilon}) = F(\mu_{\delta}, S_{\delta}, A_{\delta}).$$

Indeed, by taking a diagonal sequence $(\mu_{\delta_{i}, \varepsilon}, \beta_{\delta_{i}, \varepsilon})$ and using (89), (90), the thesis will follow.

Step 2. Recovery sequence for strains satisfying the boundary condition.

Let us now proceed to construct the sequence $(\mu_{\delta_{i}, \varepsilon}^{gA}, \beta_{\delta_{i}, \varepsilon}^{gA})$ as stated in the previous step.

From Theorem 4.2 there exist a sequence $(\mu_{\delta, \varepsilon}, \beta_{\delta, \varepsilon})$ converging to $(\mu, S, A)$ in the sense of Definition 4.1 and such that

$$\lim_{\varepsilon \to 0} F_{\varepsilon}(\mu_{\delta, \varepsilon}, \beta_{\delta, \varepsilon}) = F(\mu, S, A).$$

Moreover (see Remark 4.6), we can assume that $\beta_{\varepsilon}$ satisfies (81), from which it easily follows (92).
Proof of \( \Gamma \)-liminf inequality of Theorem 5.1. Let \((\mu, S, A)\) be in the domain of the \( \Gamma \)-limit \( \mathcal{F}^{g_A} \). Assume that \((\mu_\varepsilon, \beta_\varepsilon)\) converges to \((\mu, S, A)\) in the sense of Definition 4.1. By combining an extension argument with the \( \Gamma \)-liminf inequality in Theorem 4.2 we will show that

\[
\mathcal{F}^{g_A}(\mu, S, A) \leq \liminf_{\varepsilon \to 0} \mathcal{F}^{g_A}_\varepsilon(\mu_\varepsilon, \beta_\varepsilon).
\]

Fix \( \delta > 0 \) and define \( U_\delta := \{ x \in \mathbb{R}^2 : \text{dist}(x, \Omega) < \delta \} \). By standard reflexion arguments one can extend \( g_A \) to \( \tilde{g}_A \in L^2(U_\delta; \mathcal{M}^{2\times 2}_{\text{skew}}) \), in such a way that \( \tilde{\mu}_A := \text{Curl } \tilde{g}_A \) is a measure on \( U_\delta \) satisfying \( |\tilde{\mu}_A|(\partial \Omega) = 0 \). Consider now the functions \( \tilde{\beta}_\varepsilon \) defined as in (41) (with \( \varepsilon_n \) replaced by \( \varepsilon \)), and set

\[
\hat{\beta}_\varepsilon := \begin{cases} 
\tilde{\beta}_\varepsilon & \text{in } \Omega, \\
N_\varepsilon \tilde{g}_A & \text{in } U_\delta \setminus \Omega,
\end{cases}
\quad \hat{\beta} := \begin{cases} 
A & \text{in } \Omega, \\
\tilde{g}_A & \text{in } U_\delta \setminus \Omega.
\end{cases}
\]

By construction we have \( \frac{\hat{\beta}_\varepsilon}{N_\varepsilon} \rightharpoonup \hat{\beta} \) in \( L^1(U_\delta) \), so that

\[
\hat{\mu}_\varepsilon := \frac{\text{Curl } \hat{\beta}_\varepsilon}{N_\varepsilon} \rightharpoonup^* \mu + ((g_A - A) \cdot t) \mathcal{H}^1 \cap \partial \Omega + \text{Curl } \tilde{g}_A \mathcal{L} (U_\delta \setminus \Omega)
\]

Recalling (42), (46) and (47), we conclude

\[
\liminf_{\varepsilon \to 0} \mathcal{F}^{g_A}_\varepsilon(\mu_\varepsilon, \beta_\varepsilon) \geq \liminf_{\varepsilon \to 0} \frac{1}{\sqrt{N_\varepsilon \log \varepsilon}} \int_\Omega W(\beta_\varepsilon^{\text{sym}}) \, dx \\
+ \liminf_{\varepsilon \to 0} \frac{1}{N_\varepsilon} \int_\Omega \varphi \left( \frac{d\mu_\varepsilon}{d|\mu_\varepsilon|} \right) d|\mu_\varepsilon| + \int_{\partial \Omega} \varphi \left( \frac{(g_A - \frac{\beta_\varepsilon}{N_\varepsilon}) \cdot t}{\text{Curl } \tilde{g}_A} \right) ds \\
\geq \int_\Omega W(S) \, dx + \liminf_{\varepsilon \to 0} \int_{U_\delta} \varphi \left( \frac{d\hat{\mu}_\varepsilon}{d|\hat{\mu}_\varepsilon|} \right) d|\hat{\mu}_\varepsilon| - \int_{U_\delta \setminus \Omega} \varphi \left( \frac{d \text{Curl } \tilde{g}_A}{d |\text{Curl } \tilde{g}_A|} \right) d |\text{Curl } \tilde{g}_A| \\
\geq \int_\Omega W(S) \, dx + \int_{U_\delta} \varphi \left( \frac{d\mu}{d|\mu|} \right) d|\mu| + \int_{\partial \Omega} \varphi((g_A - A) \cdot t) \, ds = \mathcal{F}^{g_A}(\mu, S, A).
\]

6. LINEARISED POLYCRYSTALS AS MINIMISERS OF THE \( \Gamma \)-LIMIT

Let \( \Omega \subset \mathbb{R}^2 \) be a bounded domain with Lipschitz continuous boundary. Let \( k \in \mathbb{N} \) be fixed and let \( \{U_i\}_{i=1}^k \) be a Caccioppoli partition of \( \Omega \) (see [1, Section 4.4]). Moreover fix \( m_1, \ldots, m_k \in \mathbb{R}_+ \) with \( m_i < m_{i+1} \), and define the piecewise constant function \( a \in BV(\Omega) \) as

\[
a := \sum_{i=1}^k m_i \chi_{U_i}.
\]
In particular, (95) implies that \( a \in L^\infty(\Omega) \) and \( Da \in \mathcal{M}(\Omega; \mathbb{R}^2) \). We can now define the piecewise constant boundary condition \( g_A \in L^\infty(\Omega; \mathbb{M}^{2 \times 2}_{\text{skew}}) \) as
\[
(96) \quad g_A := \begin{pmatrix} 0 & a \\ -a & 0 \end{pmatrix}.
\]
Notice that \( g_A \in L^2(\Omega; \mathbb{M}^{2 \times 2}_{\text{skew}}) \) and \( \text{Curl} \, g_A = Da \), therefore \( \text{Curl} \, g_A \in H^{-1}(\Omega; \mathbb{R}^2) \cap \mathcal{M}(\Omega; \mathbb{R}^2) \). In this way \( g_A \) is an admissible boundary condition for \( F_{g_A} \), as required in (82).

We wish to minimise the \( \Gamma \)-limit (85) with boundary condition \( g_A \) prescribed by (95)-(96). Since the elastic energy and plastic energy are decoupled in \( F_{g_A} \), and there is no boundary condition fixed on the elastic part of the strain \( S \), we have
\[
\inf F_{g_A}(\text{Curl} \, A, S, A) = \inf F_{g_A}(\text{Curl} \, A, 0, A).
\]
Therefore it is sufficient to study
\[
\inf \left\{ \int_\Omega \varphi(\text{Curl} \, A) + \int_{\partial \Omega} \varphi((g_A - A) \cdot t) \, ds : A \in L^2(\Omega; \mathbb{M}^{2 \times 2}_{\text{skew}}), \right. \\
\left. \quad \text{Curl} \, A \in H^{-1}(\Omega; \mathbb{R}^2) \cap \mathcal{M}(\Omega; \mathbb{R}^2) \right\},
\]
where \( t \) is the unit tangent to \( \partial \Omega \) defined as the \( \pi/2 \) counter-clockwise rotation of the outer normal \( \nu \) to \( \Omega \), \( \varphi : \mathbb{R}^2 \rightarrow [0, \infty) \) is the density defined in (28), and
\[
(98) \quad \int_\Omega \varphi(\mu) := \int_\Omega \varphi \left( \frac{d\mu}{d|\mu|} \right) \, d|\mu|
\]
is the anisotropic \( \varphi \)-total variation for a measure \( \mu \in \mathcal{M}(\Omega; \mathbb{R}^2) \). Note that (98) is well-posed, since \( \varphi \) satisfies the properties given in Proposition 3.4.

For \( A \in L^2(\Omega; \mathbb{M}^{2 \times 2}_{\text{skew}}) \), we have that
\[
(99) \quad A = \begin{pmatrix} 0 & u \\ -u & 0 \end{pmatrix},
\]
for some \( u \in L^2(\Omega) \). Moreover \( \text{Curl} \, A = Du \), therefore condition \( \text{Curl} \, A \in \mathcal{M}(\Omega; \mathbb{R}^2) \) implies \( u \in BV(\Omega) \). Also notice that
\[
\int_{\partial \Omega} \varphi((g_A - A) \cdot t) \, ds = \int_{\partial \Omega} \varphi((u - a)\nu) \, ds,
\]
where \( a \) is the piecewise constant function (95). We claim that (97) is equivalent to the following minimisation problem
\[
(100) \quad \inf \left\{ \int_\Omega \varphi(Du) + \int_{\partial \Omega} \varphi((u - a)\nu) \, ds : u \in BV(\Omega) \right\}.
\]
Indeed, we already showed that if \( A \) is a competitor for (97), then the function \( u \), given by (99), belongs to \( BV(\Omega) \), and it is a competitor for (100). Conversely, assume that \( u \in BV(\Omega) \) and define \( A \) through (99). Since \( u \in BV(\Omega) \), then \( \text{Curl} \, A = Du \in \mathcal{M}(\Omega; \mathbb{R}^2) \). Moreover, recall that the immersion \( BV(\Omega) \hookrightarrow L^2(\Omega) \) is continuous, therefore \( u \in L^2(\Omega) \),
which implies $A \in L^2(\Omega; \mathbb{M}^{2 \times 2})$, so that $\text{Curl } A \in H^{-1}(\Omega; \mathbb{R}^2)$. This shows that (97) and (100) are equivalent.

The main result of this section is that, given the piecewise constant boundary condition $a$ defined in (95), there exists a piecewise constant minimiser $\tilde{u}$ to (100). In our model the function $\tilde{u}$ corresponds to a linearised polycrystal.

**Theorem 6.1.** There exists a locally constant minimiser $\tilde{u} \in BV(\Omega)$ to (100), i.e.,

$$\tilde{u} = \sum_{i=1}^{k} m_i \chi_{\Omega_i},$$

where $\{\Omega_i\}_{i=1}^{k}$ is a Caccioppoli partition of $\Omega$, and the values $m_i$ are the ones of (95).

The proof of this theorem relies on the anisotropic coarea formula. For the readers convenience we briefly recall it here. For $E \subset \Omega$ of finite perimeter, the anisotropic $\varphi$-perimeter of $E$ in $\Omega$ is defined as

$$\text{Per}_\varphi(E, \Omega) := \int_{\Omega} \varphi(D\chi_E).$$

Since $\varphi$ is convex and positively 1-homogenous, the anisotropic coarea formula holds true for every $u \in BV(\Omega)$:

$$\int_{\Omega} \varphi(Du) = \int_{-\infty}^{\infty} \text{Per}_\varphi(E_t, \Omega) \, dt,$$

where $E_t$ is the level set $E_t := \{x \in \Omega : u(x) > t\}$, defined for every $t \in \mathbb{R}$.

**Proof of Theorem 6.1.**

**Step 1.** Equivalent minimisation problem.

We start by rewriting (100) as a boundary value problem in $BV$. Let $\Omega' := \{x \in \mathbb{R}^2 : \text{dist}(x, \Omega) < 1\}$, so that $\Omega \subset \subset \Omega'$. Consider a piecewise constant extension $\tilde{a} \in BV(\Omega')$ of the function $a \in BV(\Omega)$ defined in (95), that is,

$$\tilde{a} = \sum_{i=1}^{k} m_i \chi_{U_i'},$$

where $\{U_i'\}_{i=1}^{k}$ is a Caccioppoli partition of $\Omega'$, agreeing with $\{U_i\}_{i=1}^{k}$ on $\Omega$. This is possible since the extension can be chosen such that $|D\tilde{a}|(\partial \Omega) = 0$, that is, we are not creating any jump on $\partial \Omega$. Consider the new minimisation problem

$$(102) \quad I := \inf \left\{ \int_{\Omega'} \varphi(Du) : u \in BV(\Omega'), \ u = \tilde{a} \text{ a.e. in } \Omega' \setminus \Omega \right\}.$$  

Finding a solution to (102) is equivalent to finding a solution to (100). Indeed, if $u \in BV(\Omega')$ is such that $u = \tilde{a}$ in $\Omega' \setminus \Omega$ then

$$(103) \quad Du = Du \downarrow \Omega + (u^\Omega - a^\Omega) \nu H^1 \downarrow \partial \Omega + D\tilde{a} \downarrow (\Omega' \setminus \Omega),$$

where $u^\Omega, a^\Omega \in L^1(\partial \Omega)$ are the traces of $u$ and $a$ on $\partial \Omega$. Notice that we can use $a^\Omega$ in (103) because the extension $\tilde{a}$ is such that $|D\tilde{a}|(\partial \Omega) = 0$, hence we have $\tilde{a} = a^\Omega \text{H}^{n-1}$-a.e. in $\partial \Omega$. 

Step 2. Existence of a minimiser for (102).

Let $u_j \in BV(\Omega')$ be a minimising sequence for (102), that is $u_j = \tilde{a}$ a.e. on $\Omega' \setminus \Omega$ and

$$\lim_{j \to \infty} \int_{\Omega'} \varphi(Du_j) = I. \tag{104}$$

By standard truncation arguments we can assume that $\|u_j\|_{\infty} \leq \max_i |m_i|$. In particular, from (104), we deduce that $\sup_j \|u_j\|_{BV(\Omega')} < \infty$. By compactness in $BV$, there exists $\tilde{u} \in BV(\Omega')$ such that, up to subsequences, $u_j \to \tilde{u}$ in $L^1(\Omega')$ and $Du_j \rightharpoonup D\tilde{u}$ weakly in $\mathcal{M}(\Omega' ; \mathbb{R}^2)$. Since $u_j = \tilde{a}$ a.e. on $\Omega' \setminus \Omega$, the strong convergence in $L^1$ implies that (up to subsequences) $u_j \to \tilde{u}$ a.e. in $\Omega'$, so that $\tilde{u} = \tilde{a}$ a.e. in $\Omega' \setminus \Omega$. From Reshetnyak’s lower semicontinuity Theorem we conclude that

$$\int_{\Omega'} \varphi(D\tilde{u}) \leq \liminf_{j \to \infty} \int_{\Omega'} \varphi(Du_j) = I,$$

so that $\tilde{u}$ is a minimiser for (102).

Step 3. Existence of a piecewise constant minimiser for (100).

Let $u$ be a minimiser for (102). By a standard truncation argument we can assume that $m_1 \leq u \leq m_k$ a.e. on $\Omega'$. Formula (101) then reads

$$\int_{\Omega'} \varphi(Du) = \sum_{i=1}^{k-1} \int_{m_i}^{m_{i+1}} \text{Per}_\varphi(E_t, \Omega') \, dt, \tag{105}$$

where $E_t := \{ x \in \Omega' : u(x) > t \}$ for $t \in \mathbb{R}$. By the mean value theorem, for every $i = 1, \ldots, k - 1$, there exists $t_i \in (m_i, m_{i+1})$ such that

$$\int_{m_i}^{m_{i+1}} \text{Per}_\varphi(E_t, \Omega') \, dt \geq (m_{i+1} - m_i) \text{Per}_\varphi(E_{t_i}, \Omega'). \tag{106}$$

We define the piecewise constant function

$$\tilde{u}(x) := m_i \quad \text{if} \quad x \in E_{t_{i-1}} \setminus E_{m_i},$$

for $i = 1, \ldots, k$, where we have set $E_{t_0} := \Omega'$ and we notice that $E_{m_k} = \emptyset$ set theoretically. Since the sets $E_t$ have finite perimeter in $\Omega'$, we have that $\tilde{u} \in BV(\Omega')$. Moreover, by construction, $\tilde{u} = \tilde{a}$ on $\Omega' \setminus \Omega$, so that $\tilde{u}$ is a piecewise constant competitor for (102). It is immediate to compute that

$$Du = \sum_{i=1}^{k-1} (m_{i+1} - m_i) \nu_{E_{t_i}} \mathcal{H}^1 \subset \partial^* E_{t_i},$$

so that

$$\int_{\Omega'} \varphi(D\tilde{u}) = \sum_{i=1}^{k-1} (m_{i+1} - m_i) \int_{\partial^* E_{t_i}} \varphi(\nu_{E_{t_i}}) \, d\mathcal{H}^1 = \sum_{i=1}^{k-1} (m_{i+1} - m_i) \text{Per}_\varphi(E_{t_i}, \Omega'). \tag{107}$$
By minimality of \( u \) and (105)-(107) we conclude that \( \tilde{u} \) is a locally constant minimiser for (102). Hence \( \tilde{u}|_\Omega \) is a locally constant minimiser for (100).

\[ \square \]

7. Conclusions and perspectives

The aim of this paper is to describe polycrystalline structures from a variational point of view. Grain boundaries and the corresponding grain orientations are not introduced as internal variables of the energy, but they spontaneously arise as a result of energy minimisation, under suitable boundary conditions.

We work under the hypothesis of linear planar elasticity as in [10], with the reference configuration \( \Omega \subset \mathbb{R}^2 \) representing a section of an infinite cylindrical crystal. The elastic energy functional depends on the lattice spacing \( \varepsilon \) of the crystal and we allow \( N_\varepsilon \) edge dislocations in the reference configuration, with \( N_\varepsilon \to \infty \) as \( \varepsilon \to 0 \). Each dislocation contributes by a factor \( |\log \varepsilon| \) to the elastic energy, so that the natural rescaling for the energy functional is \( N_\varepsilon |\log \varepsilon| \). We work in the energy regime

\[ \frac{1}{\varepsilon} \gg N_\varepsilon \gg |\log \varepsilon|, \]

which accounts for grain boundaries that are mutually rotated by an infinitesimal angle \( \theta \approx 0 \).

After rescaling the elastic energy of such system of dislocations and sending the lattice spacing \( \varepsilon \) to zero, in Theorem 4.2 we derive by \( \Gamma \)-convergence a macroscopic energy functional of the form

\[ F(\mu, S, A) = \int_\Omega C S : S \, dx + \int_\Omega \varphi \left( \frac{d\mu}{d|\mu|} \right) \, d|\mu|, \]

where \( C \) is the linear elasticity tensor and \( \varphi \) is a positively 1-homogeneous density function, defined through a suitable cell-problem. The elastic energy is computed on \( S \), that represents the elastic part of the macroscopic strain. The plastic energy depends only on the dislocation measure \( \mu \), which is coupled to the plastic part \( A \) of the macroscopic strain through the relation \( \mu = \text{Curl} \, A \). As a consequence, \( \mu \) is a curl-free vector Radon measure. The contributions of elastic energy and plastic energy are decoupled in the \( \Gamma \)-limit \( F \), due to the fact that \( S \) and \( A \) live on different scales: \( \sqrt{N_\varepsilon |\log \varepsilon|} \) and \( N_\varepsilon \), respectively.

Indeed this is the main difference with the energy regime \( N_\varepsilon \approx |\log \varepsilon| \) studied in [10], where \( S \) and \( A \) live on the same scale \( |\log \varepsilon| \). In [10] the authors derive a macroscopic energy that has the same structure as \( F \), but in which the contributions of elastic energy and plastic energy are coupled by the relation \( \mu = \text{Curl} \, \beta \), where \( \beta = S + A \) represents the whole macroscopic strain.

Once the \( \Gamma \)-limit \( F \) is obtained, we impose a piecewise constant Dirichlet boundary condition on \( A \), and minimise \( F \) under such constraint. In Theorem 6.1 we prove that \( F \) admits piecewise constant minimisers, of the form

\[ \hat{A} = \sum_{i=1}^k A_i \chi_{\Omega_i}, \]
where the $A_i$'s are antisymmetric matrices and $\{\Omega_i\}$ is a Caccioppoli partition of $\Omega$. We interpret $\hat{A}$ as a linearised polycrystal, with $\Omega_i$ representing a single grain having orientation $A_i$. This interpretation is motivated by the fact that antisymmetric matrices can be considered as infinitesimal rotations. The (linear) energy corresponding to $\hat{A}$ can be seen as a linearised version of the Read-Shockley formula for small angle tilt grain boundaries, i.e.,

\begin{equation}
E = E_0 \theta (1 + |\log \theta|),
\end{equation}

where $E_0 > 0$ is a constant depending only on the material and $\theta$ is the angle formed by two grains. Indeed, the Read-Shockley formula is obtained in [17] by computing the elastic energy for an evenly spaced array of $1/\varepsilon$ dislocations at the grain boundaries. Our energy regime accounts only for $N\varepsilon \ll 1/\varepsilon$ dislocations, therefore we do not have enough dislocations to create true rotations between grains. Nevertheless we still observe polycrystalline structures, but the rotation angles between grains are infinitesimal.

Recently Lauteri and Luckhaus [14] proved some compactness properties and energy bounds in agreement with the Read-Shockley formula. It would be desirable to understand if our $\Gamma$-limit can be deduced from their model as the angle $\theta$ between grains tends to zero. Moreover, it would be interesting to push our $\Gamma$-convergence analysis to energy regimes of order $\frac{|\log \varepsilon|}{\varepsilon}$, corresponding to $N\varepsilon \approx \frac{1}{\varepsilon}$. In this regime true rotations should emerge and the Read-Shockley formula could be possibly derived by $\Gamma$-convergence. At present, our technical assumption on well separation between dislocations is not compatible with such an energy regime.

Another natural question is whether the minimiser $\hat{A}$ is unique, or at least if all the minimisers are piece-wise constant. We suspect that, by enforcing piece-wise constant boundary conditions, generically all minimisers are piece-wise constant.

A further problem is to deduce our $\Gamma$-limit $F$ by starting from a nonlinear energy computed on small deformations $v = x + \varepsilon u$, in the energy regime $N\varepsilon \gg |\log \varepsilon|$. A similar analysis was already performed in [15] (see also [18]), where the authors derive the $\Gamma$-limit obtained in [10] starting from a nonlinear energy, under the assumption that $N\varepsilon \approx |\log \varepsilon|$. It seems possible to adapt the techniques used in [15] to our case. This problem is currently under investigation by the authors.

Finally, a further step forward in our analysis is the following: in this paper the formation of polycrystalline structures is driven by relaxed boundary conditions, as usual for minimisation problems in $BV$ spaces. It would be interesting to deal with true boundary conditions, which we expect to lead to the same $\Gamma$-limit $F^{94}$ defined in [84]. Moreover, it would be interesting to replace boundary conditions by forcing terms. For instance, bulk forces in competition with surface energies at grain boundaries should result in polycrystals exhibiting some intrinsic length scale. This is the case of semi-coherent interfaces, separated by periodic nets of dislocations (see [8]).

References

[1] L. Ambrosio, N. Fusco, and D. Pallara. Functions of Bounded Variation and Free Discontinuity Problems. Oxford Science Publications, 2000.
[2] D. J. Bacon, D. M. Barnett, and R. O. Scattergood. Anisotropic continuum theory of lattice defects. *Progress in Materials Science*, 23(2-4):51–262, 1978.

[3] P. Cermelli and G. Leoni. Renormalized energy and forces on dislocations. *SIAM Journal on Mathematical Analysis*, 37(4):1131–1160, 2005.

[4] P. G. Ciarlet. *Three dimensional elasticity*. North Holland, Amsterdam, 1988.

[5] R. Dautray and J.-L. Lions. *Mathematical Analysis and Numerical Methods for Science and Technology. Vol. 3*. Springer, Berlin, 1988.

[6] L. De Luca, A. Garroni, and M. Ponsiglione. Γ-convergence analysis of systems of edge dislocations: the self energy regime. *Arch. Ration. Mech. Anal.*, 206(3):885–910, 2012.

[7] V. S. Deshpande, A. Needleman, and E. Van der Giessen. Finite strain discrete dislocation plasticity. *Journal of the Mechanics and Physics of Solids*, 51:2057–2083, 2003.

[8] S. Fanzon, M. Palombaro, and M. Ponsiglione. A Variational Model for Dislocations at Semi-coherent Interfaces. *Journal of Nonlinear Science*, Feb 2017. DOI: [https://doi.org/10.1007/s00332-017-9366-5](https://doi.org/10.1007/s00332-017-9366-5).

[9] H. Foell. Defects in Crystals, Hypertext. University of Kiel. URL: [https://www.tf.uni-kiel.de/matwis/amat/def_en/](https://www.tf.uni-kiel.de/matwis/amat/def_en/).

[10] A. Garroni, G. Leoni, and M. Ponsiglione. Gradient theory for plasticity via homogenization of discrete dislocations. *J. Eur. Math. Soc. (JEMS)*, 12(5):1231–1266, 2010. DOI: [10.4171/JEMS/228](https://doi.org/10.4171/JEMS/228).

[11] J. Ginster. Plasticity as the Γ-Limit of a Nonlinear Dislocation Energy with Mixed Growth. *PAMM Proc. Appl. Math. Mech.*, 15:543–544, 2015. DOI: [https://doi.org/10.1002/pamm.201510262](https://doi.org/10.1002/pamm.201510262).

[12] G. Gottstein. *Physical foundations of materials science*. Springer, 2013.

[13] R.L. Jerrard and H.M. Soner. Limiting behavior of the ginzburg-landau functional. *Funct. Anal. 192*, 192(2):524 – 561, 1992.

[14] G. Lauteri and S. Luckhaus. An Energy Estimate for Dislocation Configurations and the Emergence of Cosserat-Type Structures in Metal Plasticity. *Preprint*, 2017. URL: [https://arxiv.org/abs/1608.06155](https://arxiv.org/abs/1608.06155).

[15] S. Muller, L. Scardia, and C. Zeppieri. Geometric rigidity for incompatible fields and an application to strain-gradient plasticity. *Indiana University Mathematics Journal*, 63(5):1365–1396, 2014.

[16] W. T. Read. Dislocations in Crystals. McGraw-Hill, 1953.

[17] W. T. Read and W. Shockley. Dislocation models of crystal grain boundaries. *Phys. Rev.*, 78:275–289, May 1950.

[18] L. Scardia and C. Zeppieri. Line-Tension Model for Plasticity as the Γ-Limit of a Nonlinear Dislocation Energy. *SIAM Journal on Mathematical Analysis*, 44(4):2372–2400, 2012.

[19] J.E. Taylor and W. Cahn. A unified approach to motion of grain boundaries, relative tangential translation along grain boundaries, and grain rotation. *Acta Materialia*, 52(16):4887–4898, 2004.

[20] Webpage. Atomic Scale Structure of Materials. DoITPoMS TLP, University of Cambridge. URL: [https://www.doitpoms.ac.uk/tlplib/atomic-scale-structure/poly.php](https://www.doitpoms.ac.uk/tlplib/atomic-scale-structure/poly.php).

(Silvio Fanzon) UNIVERSITY OF SUSSEX, DEPARTMENT OF MATHEMATICS, PEVENSEY 2 BUILDING, FALMER CAMPUS, BRIGHTON BN1 9QH, UNITED KINGDOM

E-mail address: S.Fanzon@sussex.ac.uk

(Mariapia Palombaro) UNIVERSITY OF SUSSEX, DEPARTMENT OF MATHEMATICS, PEVENSEY 2 BUILDING, FALMER CAMPUS, BRIGHTON BN1 9QH, UNITED KINGDOM

E-mail address: M.Palombaro@sussex.ac.uk

(Marcello Ponsiglione) DIPARTIMENTO DI MATEMATICA, SAPIENZA UNIVERSITÀ DI ROMA, 00185 ROME, ITALY

E-mail address: ponsigli@mat.uniroma1.it