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Generalized $N = 1$ and $N = 2$ structures
in M-theory and type II orientifolds

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ABSTRACT

We consider M-theory and type IIA reductions to four dimensions with $N = 2$ and $N = 1$ supersymmetry and discuss their interconnection. Our work is based on the framework of Exceptional Generalized Geometry (EGG), which extends the tangent bundle to include all symmetries in M-theory and type II string theory, covariantizing the local U-duality group $E_7(7)$. We describe general $N = 1$ and $N = 2$ reductions in terms of $SU(7)$ and $SU(6)$ structures on this bundle and thereby derive the effective four-dimensional $N = 1$ and $N = 2$ couplings, in particular we compute the Kähler and hyper-Kähler potentials as well as the triplet of Killing prepotentials (or the superpotential in the $N = 1$ case). These structures and couplings can be described in terms of forms on an eight-dimensional tangent space where $SL(8) \subset E_7$ acts, which might indicate a description in terms of an eight-dimensional internal space, similar to F-theory. We finally discuss an orbifold action in M-theory and its reduction to O6 orientifolds, and show how the projection on the $N = 2$ structures selects the $N = 1$ ones. We briefly comment on new orientifold projections, U-dual to the standard ones.
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1 Introduction

It has been a long-standing problem to understand more general flux backgrounds in string theory. The most successful tool for this task has been supersymmetry, since it reduces the second-order equations of motion to first-order supersymmetry equations that are much simpler to solve and provides non-renormalization theorems for certain sets of couplings. The simplest string backgrounds are Ricci-flat geometries that admit a number of covariantly constant spinors. However, in the presence of fluxes, the first-order supersymmetry equations become more involved, as all bosonic fields of string theory appear in these equations. The global bosonic symmetries of the massless string spectrum then can help to write these first-order equations in a simpler form. This is the approach of generalized geometry. The introduction of a generalized tangent bundle covariantizes these symmetries by combining the diffeomorphisms and gauge transformations of the gauge fields into a single vector bundle. The metric on this bundle then includes, besides the metric, the other massless bosonic fields. The idea was first applied to the T-duality group that transforms the metric and the B-field into each other. This description goes by the name of Generalized Complex Geometry [1].

More recently, the formalism was extended to the U-duality group of type II string theory to also include its Ramond-Ramond fields and to M-theory, covariantizing its three-form gauge field [2–5]. In both cases the covariantized symmetry group relevant to compactify to four dimensions is $E_7(7)$, and the generalized tangent bundle of type IIA is recovered from the one of M-theory by dimensional reduction. All possible supersymmetric backgrounds of type II and M-theory can then be understood as (generalized) $G$-structure backgrounds, where $G$ is, depending on the number of supercharges, a subgroup of $SU(8)$ (the maximal compact subgroup of $E_7(7)$) [1]. The first-order supersymmetry equations can then be written in a covariant way [6–8]. Furthermore, $G$-structure backgrounds that solve the equations of motion but not the first-order supersymmetry conditions can usually be understood as backgrounds with spontaneously broken supersymmetry. In this sense, generalized geometry serves as an off-shell supersymmetric formulation for general $G$-structure backgrounds.

Generalized $G$ structures are characterized by fundamental objects (defined by bi-spinors) in certain representations of $E_7(7)$ such that their common stabilizer is exactly $G$. These fundamental objects determine the generalized metric (which is stabilized by $SU(8)$) and thereby the entire bosonic supergravity background. The first-order supersymmetry conditions are resembled by first-order differential equations on them. Moreover, the couplings of the off-shell supersymmetric formulations are given in terms of tensorial combinations of these fundamental objects into $E_7(7)$ singlets.

A major aim of this work is to understand $SU(7)$ and $SU(6)$ structures in M-theory and type II, as they correspond to backgrounds with the off-shell structure of four-dimensional $N = 1$ and $N = 2$ supergravity. $SU(7)$ structures in M-theory have already been discussed to some extend in [3], $SU(6)$ structures in type IIA have already been discussed in [4]. Of particular interest in our discussion will be the existence of an eight-dimensional intermediate bundle between the tangent and the generalized tangent bundle that admits the action of $SL(8) \subset E_7(7)$. This might indicate the existence of

\[1\] Often these are called generalized $G$-structures as they are structures on the generalized tangent space, as opposed to usual $G$-structures on the tangent space.

\[2\]
a twelve-dimensional theory (similar to F-theory) in which some of the charges will be
geometrized. \(SU(7)\) and \(SU(6)\) structures are related to \(Spin(7)\) and \(SU(4)\) structures
in \(SL(8)\).

After we briefly review the \(E_{7(7)}\)-covariant formalism of exceptional generalized geometry
in Section 2, we will discuss \(SU(7)\) and \(SU(6)\) structures in M-theory in Section 3. In
particular, we will discuss all classical couplings in these backgrounds. Subsequently, we
will relate these results to the equivalent structures in type IIA string theory in Section 4.
While \(SU(6)\) structures descend in a straight-forward way, \(SU(7)\)-structures are related
to O6-orientifold backgrounds in type IIA. Moreover, \(SU(6)\) and \(SU(7)\) structures should
be related by involutions that project out half of the supersymmetry, such as orbifolding
and orientifolding in M-theory and type II string theory. In Section 5 we will show how an
\(SU(7)\) structure is obtained from an \(SU(6)\) structure via such involutions. In particular,
we will determine the \(N = 1\) couplings in terms of the \(N = 2\) parent theory. Finally, we
will identify the involutions given by standard orbifolding and orientifolding in M-theory
and type II string theory and discuss a few new involutions, for instance an involution
creating objects with tension and charge opposite to those of NS5-branes. We conclude
with a summary of the results and some outlook. Appendix A contains all the relevant
formuli concerning \(E_{7(7)}\) representations, and Appendix B presents the details of some of
the calculations done along the paper.

2 Exceptional Generalized Geometry (EGG)

In this section we review the basic concepts of Exceptional Generalized Geometry (EGG),
emphasizing the role of the eight-dimensional intermediate tangent bundle \(T_8\). The idea
of EGG is to covariantize the U-duality group \(E_{7(7)}\) in M-theory and type II compactifica-
tions to four dimensions. Though only torus compactifications admit globally the action
of the U-duality group, locally any background admits it, as the tangent space is isomor-
phic to \(\mathbb{R}^7\) (\(\mathbb{R}^6\)). In EGG the internal seven- (or six-)dimensional tangent bundle of an
M-theory (type II) compactification to four dimensions is enlarged to a 56-dimensional
exceptional generalized tangent bundle such that the U-duality symmetry group \(E_{7(7)}\)
acts linearly on it. Thereby, the U-duality group promotes to a geometric action on this
bundle. As the U-duality group maps all bosonic supergravity degrees of freedom into
each other, EGG gathers them all in a metric on this exceptional generalized tangent
bundle. The patching of the exceptional generalized tangent bundle \(T_8\) resembles the
global aspects of the compactification. More details can be found in [2–5].

2.1 An eight-dimensional tangent space \(T_8\)

In the case of compactifications of type II, the exceptional tangent bundle combines the
string internal momentum and winding charges (6+6 elements), their magnetic duals
(another 6+6) as well as all the D-brane charges (32 elements). These together form the
fundamental 56 representation of \(E_7\). In M-theory, it is a result of combining momentum
and its dual (Kaluza-Klein monopole charge) (7+7) together with M2 and M5-brane
charges (21+21). These charges can be combined into \(SL(8, \mathbb{R})\) representations. We can
think of this group as acting on an 8-dimensional tangent bundle \(T_8\), which will be split
into $7 + 1$ for M-theory, and further split into $6 + 1 + 1$ for type IIA. Of course there is a
priori no eight-dimensional manifold with a tangent bundle $T_8$ appearing in M-theory or
type IIA. Therefore, $T_8$ should be seen as some kind of generalized tangent bundle. In
terms of $SL(8, \mathbb{R})$ representations, the fundamental of $E_7$ decomposes as

$$E = \Lambda^2 T_8 \oplus \Lambda^2 T_8^* ,$$

$$56 = 28 \oplus 28'.$$

Similarly, for the adjoint we have

$$A = (T_8 \otimes T_8^*)_0 \oplus \Lambda^4 T_8^* ,$$

$$133 = 63 \oplus 70 ,$$

where the subscript 0 denotes traceless. We will also need the 912 representation, which
splits according to

$$N = S^2 T_8 \oplus (\Lambda^3 T_8 \otimes T_8^*)_0 \oplus S^2 T_8^* \oplus (\Lambda^3 T_8^* \otimes T_8)_0 ,$$

$$912 = 36 \oplus 420 \oplus 36' \oplus 420' ,$$

where $S^2$ denotes symmetric two-tensors.

When we later consider spinors it is also useful to use the maximal compact subgroups
of the groups that are involved. The maximal compact subgroup of $E_7$ is $SU(8)$, and the
group-theoretical decompositions are completely analogous to the $SL(8, \mathbb{R})$ case and are
given by (2.1-2.3). Note though that the $SU(8)$ that transforms the spinors is not the
compact subgroup $SU(8)$ of $SL(8)$ that acts on $T_8$. Nevertheless the two $SU(8)$ subgroups
are related by some $E_7(7)$ transformation and the decomposition of $E_7(7)$ representations
is the same in both cases. More details can be found in Appendix A.2. When we then
consider $SL(8, \mathbb{R})$, spinors transform under the corresponding spin group $Spin(8)$ and its
maximal compact subgroup $SO(8)$. Note that for $Spin(8)$, we can impose a Majorana-
Weyl condition on the spinor. The Weyl-spinors are in one-to-one correspondence to
$Spin(7)$ spinors that are considered in the M-theory compactification.

### 2.2 M-theory and $GL(7)$ decompositions

For compactifications of M-theory on seven-dimensional manifolds, we should decompose
further the $SL(8)$ into $GL(7)$ representations, or in other words split the 8-dimensional
dual vector bundle $T_8^*$ into a 7-dimensional one $T_7^*$, plus a scalar piece. Choosing an
overall power of the 7-dimensional volume form to get the correct embedding in $SL(8)$
(see more details in [3]), we get

$$T_8^* = (\Lambda^7 T_7^*)^{-1/4} \otimes (T_7^* \oplus \Lambda^7 T_7^*)$$

$$8 = 7 \oplus 1$$

$$\rho_a = (\rho_m, \rho_8)$$

where $\rho$ is some one-form, and $a = 1, \ldots, 8$, $m = 1, \ldots, 7$. Note that the eight-form
$\rho_1 \wedge \cdots \wedge \rho_8$ is just one on $T_8$. This fits nicely with the fact that only $SL(8)$ acts on this
bundle. This implies that the fundamental 56 representation \((2.1)\) decomposes as
\[
E_M = (\Lambda^7 T_7) \frac{1}{12} \otimes (T_7 \oplus \Lambda^2 T_7^* \oplus \Lambda^5 T_7^* \oplus (T_7^* \otimes \Lambda^7 T_7^*)) ,
\]
\[
56 = 7 \oplus 21 \oplus 21 \oplus 7
\]
corresponding respectively to momentum, M2- and M5-brane charge, and KK monopole charge.

In turn, the adjoint \((2.2)\) decomposes into
\[
A = T_7 \otimes T_7^* \oplus \Lambda^6 T_7 \oplus \Lambda^6 T_7^* \oplus \Lambda^3 T_7 \oplus \Lambda^3 T_7^* ,
\]
\[
133 = 48 \oplus 1 \oplus 7 \oplus 7 \oplus 35 \oplus 35
\]
We recognize here the \(GL(7)\) adjoint (first term), and the shifts of the M-theory 3-form potential \(A_3\) (last term) and its 6-form dual \(A_6\) (fourth term). These build up the geometric subgroup of transformations that are used to patch the exceptional tangent bundle. The other pieces correspond to “hidden symmetries”, very much like the \(\beta\)-transformations in generalized geometry. Note that \(A_3\) and \(A_6\) come respectively from the 70 and 63 representations of \(SL(8)\) in \((2.2)\), i.e. they embed into the \(SL(8)\) representations in \((2.2)\) as
\[
A_{\text{shifts}} = \left( \hat{A} \otimes \rho_8, A_4 \right),
\]
where we defined the four-form
\[
A_4 \equiv A_3 \wedge \rho_8 ,
\]
and the vector
\[
\hat{A} \equiv (\text{vol}_7)^{-1} \l A_6 ,
\]
with \(\l\) meaning the full contraction of \(A_6\) with \((\text{vol}_7)^{-1}\).

3 Supersymmetric reductions of M-theory in EGG

In this section we review reductions of M-theory preserving \(N = 2\) and \(N = 1\) supersymmetry in the language of Exceptional Generalized Geometry following [3,4]. In the \(N = 2\) case, we show how an \(SU(4)\) structure on \(T_8\) emerges, and write the EGG structures in terms of the complex and symplectic structures on this space.

To get a supersymmetric effective four-dimensional theory, there should exist nowhere-vanishing spinors \(\eta_i\) on the seven-dimensional internal space such that the eleven-dimensional spinor can be decomposed as (for spinor conventions, see [3])
\[
\epsilon = \xi_+^i \otimes \eta_i^c + \xi_-^i \otimes \eta_i ,
\]
where \(\xi_{\pm}^i\) are four-dimensional Weyl spinors, \(\eta_i\) are complex \(Spin(7)\) spinor and \(i = 1, \ldots, N\) determines the amount of 4D supersymmetry. When we embed \(Spin(7)\) into \(Spin(8)\), we can choose \(\eta_i\) to be of positive chirality with respect to \(Spin(8)\), which means that we can take \(\eta_i\) to transform in the 8 of \(SU(8)\). Note that there exists a Majorana condition for \(Spin(7)\) (and also for \(Spin(8)\)) so that actually the real and imaginary parts of \(\eta_i\) are independent spinors. Both the real and imaginary part of \(\eta_i\) are stabilized by a
Spin(7) subgroup in $SL(8, \mathbb{R})$, respectively. Therefore, inside $SL(8, \mathbb{R})$ each complex spinor $\eta_i$ defines a pair of Spin(7) structures. Inside $E_{7(7)}$ though, each $\eta$ transforms in the fundamental of $SU(8)$ and its real and imaginary parts are not independent any more, as they transform into each other under $SU(8)$. Consequently, a single $\eta$ defines an $SU(7)$ structure [3], and in general $N$ non-mutually parallel spinors define an $SU(8-N) \subset E_{7(7)}$ structure.

### 3.1 $N = 2$ reductions and $SU(6) \times SU(6)$ structures

For reductions with $N = 2$ supersymmetry in four-dimensions, there should be a pair of globally defined no-where vanishing (and nowhere parallel) $SU(8)$ spinors $\eta_1, \eta_2$. As explained above, each of these spinors can be complex so that $\text{Re} \, \eta_i$ and $\text{Im} \, \eta_i$ each define an $SU(6)$ structure. Without loss of generality, we can take them to be orthogonal and having the same norm, namely

$$\bar{\eta}_i \eta_j = e^{-K_L/2} \delta_{ij}, \quad (3.2)$$

where $i, j = 1, 2$ is an $SU(2)_R$ index, and we introduced an arbitrary normalization factor $e^{-K_L/2}$ which we will further discuss below. On the other hand, we have in general the following inner products

$$\eta_i^T \eta_j = c_{ij}, \quad (3.3)$$

for some complex $2 \times 2$ matrix $C = (c_{ij})[2]$. The scalar degrees of freedom of $N = 2$ theories, coming from vector and hypermultiplets, are encoded respectively in an $SU(2)_R$ singlet and an $SU(2)_R$ triplet of bispinors [4]. The former embeds in the 28 representation of $SU(8)$, which appears in the fundamental 56 representation of $E_7$, and in terms of the decomposition (2.1) reads

$$\hat{L}^{(0)} = \frac{1}{2}(\epsilon^{ij} \eta_i \otimes \eta_j, \epsilon^{ij} \bar{\eta}_i \otimes \bar{\eta}_j), \quad \tilde{L}^{(0)} = \frac{1}{2}(-i \epsilon^{ij} \eta_i \otimes \eta_j, i \epsilon^{ij} \bar{\eta}_i \otimes \bar{\eta}_j), \quad (3.4)$$

where for later convenience we have defined two real bispinors in the 28 and $\bar{28}$ that are related to $L$ by $L = \hat{L}^{(0)} + i \tilde{L}^{(0)}$. From $\hat{L}^{(0)}$ we can define also the almost complex structure $J_L$ that relates real and imaginary parts of $L$, given by

$$J_L = 2 \hat{L} \times \tilde{L} = L \times \bar{L} = (e^{-K_L/2} \delta_{ij} \eta_i \otimes \bar{\eta}_j - \frac{1}{4} e^{-K_L} 1, 0). \quad (3.5)$$

where 1 is the identity matrix with $Spin(8)$ spinorial indices, $\delta^a_{ij}$.

Furthermore, the $SU(2)_R$ triplet transforms in the 63 adjoint representation of $SU(8)$, which is embedded in the 133 adjoint representation of $E_7$, and reads in terms of the decomposition (2.2)

$$K_{a}^{(0)} = (\kappa e^{K_L/2} \sigma^i_a \delta_{ij} \eta_i \otimes \bar{\eta}_j, 0) \quad (3.6)$$

where $\sigma_a$ are the Pauli sigma matrices and we introduced another normalization factor $\kappa$. Note that the product of $L$ and $K$ in the 56 vanishes, i.e.

$$K_{a}^{(0)} \cdot L^{(0)} = 0, \quad (3.7)$$

---

2The matrix $C$ is complex symmetric and in general not diagonalizable.
which means that the stabilizers of $L^{(0)}$ ($E_6(2) \subset E_7(7)$) and $K_a^{(0)}$ ($SO^*(12) \subset E_7(7)$) intersect in $SU(6)$. General $L$ and $K_a$ are then constructed by acting with the shift matrix $A_{\text{shifts}}$ in the adjoint of $E_7(7)$ on them, i.e.

$$L = e^{A_{\text{shifts}}} L^{(0)} , \quad J_L = e^{A_{\text{shifts}}} J_L^{(0)} , \quad K_a = e^{A_{\text{shifts}}} K_a^{(0)} .$$

(3.8)

The Kähler potential for the space of structures $L$ and the hyper-Kähler potential hyper-Kähler cone over the space of $K_a$ has been given in [4]. The Kähler potential for $L$ is given by the moment map for the rotation of $L$ by a phase (generated by $J_L$) and can be expressed by the logarithm of the quartic invariant of $\hat{L}$ [4]

$$K_L = -\log \sqrt{-\frac{1}{4}(J_L, J_L) = -\log \sqrt{-q(\hat{L})} = -\log \left(-\frac{i}{8} \langle L^{(0)}, \bar{L}^{(0)} \rangle \right) .$$

(3.9)

where $(\cdot, \cdot)$ refers to the trace in the adjoint, given in (A.7). The hyper-Kähler potential of the hyper-Kähler cone over the moduli space of $K_a$ is determined by [4]

$$\kappa = \sqrt{-\frac{1}{4}(K_a, K_a)} .$$

(3.10)

It determines the normalization of the $K_a$ by

$$K_a \cdot (K_b \cdot \nu) = -\frac{1}{2} \kappa^2 \delta_{ab} \nu + \kappa \epsilon_{abc} K_c \cdot \nu ,$$

(3.11)

where $\nu$ is an arbitrary element in the 56 representation.

The supersymmetric couplings between the two objects $L$ and $K_a$ are given by the Killing prepotentials [4,8]

$$P^a = \epsilon^{abc}(D_L K_b, K_c) ,$$

(3.12)

and $D_L = \langle L, D \rangle - L \times D$ is the Dorfman derivative [5] along $L$, with $D$ being the standard differential operator. Inserting this, we get [8]

$$P^a = \epsilon^{abc}(\langle L, D \rangle K_b, K_c) + 4\kappa \langle L, DK_a \rangle .$$

(3.13)

### 3.2 $N = 2$ reductions and $SU(4)$ structure on $T_8$

In the last section we defined a general $SU(6)$ structure with an arbitrary product (3.3). Note that in general, the spinors $\eta_i$ are complex, and real and imaginary part of each spinor, if they are never parallel, already define an $SU(6)$ structure, so in general we would have “$SU(6) \times SU(6)$” structures (and secretly, a theory with more supersymmetries). In such a generic case, it is difficult to be more explicit as typically all $SL(8)$ components are present in $L$ and $K_a$. The case of real (i.e. Majorana) spinors $\eta_i$ simplifies the form of $L$ and $K_a$ and gives rise to a natural interpretation in terms of the bundle $T_8$. The relation (3.3) reduces for real spinors to the normalization condition (3.2) so that

$$c_{ij} = e^{-K \epsilon_i/2 \delta_{ij}} .$$

(3.14)

$\langle L, D \rangle$ is the symplectic invariant (A.6), and $(L \times D)$ is the projection onto the adjoint in the product of two 56 elements, given in (A.8).
We will express now both $L^{(0)}$ and $K_8^{(0)}$ in (3.4) and (3.6) in terms of objects in $SL(8, \mathbb{R})$ representations. For this we define a pure spinor
\[ \chi = \eta_1 + i \eta_2 \] out of the real spinors $\eta_i$. We then find for $L^{(0)}$ and $K_8^{(0)}$ that
\[
K_8^{(0)} = (\chi \otimes \chi^T, 0), \quad J_8^{(0)} = (\chi \otimes \chi - \frac{1}{4} e^{K_L/2} 1, 0). \]
On the other hand, the bispinors $\Phi_1 = \chi \otimes \bar{\chi}$ and $\Phi_2 = \chi \otimes \chi^T$ are a pair of compatible $O(8, 8)$ pure spinors that define an $SU(4)$ structure on $T_8$, given by
\[
\Phi_1 = \frac{1}{4} e^{-K_L/2}\exp(-i e^{K_L/2} J_8^{(0)}), \quad \Phi_2 = \Omega_4^{(0)},
\]
where we made the following definitions
\[
J_8^{(0)} = -i \bar{\chi} \gamma_{ab} \chi dx^a \wedge dx^b = \epsilon^{ij} \bar{\eta}_i \gamma_{ab} \eta_j dx^a \wedge dx^b,
\]
\[
\Omega_4^{(0)} = -\frac{1}{4} \epsilon \gamma_{abcd} \gamma_{efgh} \gamma_{mn} \eta_j dx^a \wedge dx^b \wedge dx^c \wedge dx^d
\]
\[= -\frac{1}{4} \epsilon \gamma_{abcd} (\eta_1 + i \eta_2) \gamma_{efgh} (\eta_1 + i \eta_2) dx^a \wedge dx^b \wedge dx^c \wedge dx^d.
\]
In terms of the $x^m$ we find
\[
J_8^{(0)} = J + v^{(0)} \wedge \rho_8, \quad J = \epsilon^{ij} \bar{\eta}_i \gamma_{mn} \eta_j dx^m \wedge dx^n,
\]
\[
\Omega_4^{(0)} = (\rho_8 + i v^{(0)}) \wedge \Omega, \quad \Omega = \tau_8 \Omega_4^{(0)},
\]
where the one-form $v^{(0)}$ is defined by
\[
v^{(0)} = \tau_8 \epsilon^{ij} \bar{\eta}_i \gamma_{ab} \eta_j dx^a \wedge dx^b.
\]
The four-form $\Omega_4^{(0)}$ defines a complex structure $T_8^{(0)}$ by
\[
(l_8^{(0)})_{mn} = \frac{1}{\kappa^2} (\ast_8 \text{Im} \Omega_4^{(0)})_{mpq} (\text{Re} \Omega_4^{(0)})_{npq}
\]
\[= \frac{1}{2\kappa^2} ((\bar{\ast} v^{(0)})^m (\rho_8)_n - \rho_8^m v_n^{(0)} + (\text{Im} \Omega)^{mpq} (\text{Re} \Omega)_{npq} - (\text{Re} \Omega)^{mpq} (\text{Im} \Omega)_{npq}).
\]
In terms of these objects, the structure $L^{(0)}$ has the following $SL(8, \mathbb{R})$ decomposition (cf. [2.1])
\[
L^{(0)} = \tilde{L}^{(0)} + i \tilde{J}^{(0)} = (\tilde{\rho}_8 \wedge \tilde{v}) + e^{K_L} \text{vol}_8^{-1} (\frac{1}{2} \rho_8 \wedge v^{(0)} \wedge J \wedge J), \ i(\rho_8 \wedge v^{(0)} - J)
\]
\[= (e^{K_L} \text{vol}_8^{-1} \frac{1}{2} J_8^{(0)} \wedge J_8^{(0)} \wedge J_8^{(0)}), \ -i J_8^{(0)}
\]
\[= e^{i \rho_8 \wedge v^{(0)} \wedge J} (\tilde{\rho}_8 \wedge \tilde{v}^{(0)}, 0),
\]
\[= \exp(-i \rho_8 \wedge v^{(0)} \wedge J).
\]

\[4\] A complex $\text{Spin}(8)$ spinor $\chi$ is called pure if $\chi^T \chi = 0$.

\[5\] The hat denotes the vector dual to a one-form. In the special case that $v$ is the one-form $dy$ of a circle, one can reduce the theory to type IIA, where $v_m \gamma^{mab}$ then plays the role of chirality.

\[6\] For the generic case of complex spinors $\eta_i$, the form of $L^{(0)}$ is also given by Eq. (3.23), but in this case $J_8^{(0)}$ is complex, given by
\[
J_8^{(0)} = \epsilon^{ij} \eta_i \gamma_{ab} \eta_j dx^a \wedge dx^b,
\]
and similarly for $J$ and $v^{(0)}$. 

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where we have used (A.20) and $\text{vol}_8^{-1}$ means contraction with the eight-dimensional volume form, i.e. with the numeric epsilon tensor (the 8-dimensional space has no volume modulus). We see that $L^{(0)}$ can be understood as the shift of the bi-vector $-\hat{\rho}_8 \wedge \hat{v}$ by some imaginary four-form $i \rho_8 \wedge v^{(0)} \wedge J^7$. The almost complex structure relating real and imaginary part of $L^{(0)}$ given in (3.5) can be computed to be

$$J_{L^{(0)}} = (0, J_8 \wedge J_8) .$$

(3.24)

Similarly, using (3.16) and (A.21), we can determine $K^{(0)}_a$ for the decomposition (2.2) to be

$$K^{(0)}_1 = (0, \text{Im} \Omega^{(0)}_4) ,$$

$$K^{(0)}_2 = (\kappa J^{(0)}_8, 0) ,$$

$$K^{(0)}_3 = (0, \text{Re} \Omega^{(0)}_4) .$$

(3.25)

From the Fierz identities (or from the $SU(2)$ algebra) it follows that $\Omega^{(0)}_4$ transforms holomorphically under $I^{(0)}_8$, and obeys

$$\Omega^{(0)}_4 \wedge \Omega^{(0)}_4 = 0 , \quad \Omega^{(0)}_4 \wedge \bar{\Omega}^{(0)}_4 = 2\kappa^2 \text{vol}_8 .$$

(3.26)

We also have $\iota^{\hat{v}(0)} J = \iota^{\hat{\rho}_8} J = 0$, and $\frac{1}{3!} v \wedge J \wedge J \wedge J = e^{-2K_L \text{vol}_7}$ or in other words

$$\frac{1}{3!} J^{(0)}_8 \wedge J^{(0)}_8 \wedge J^{(0)}_8 \wedge J^{(0)}_8 = \frac{1}{3!} J \wedge J \wedge J \wedge v \wedge \rho_8 = e^{-2K_L \text{vol}_8} .$$

(3.27)

Furthermore, the compatibility condition (3.7) of $L^{(0)}$ and $K^{(0)}_a$ implies $\iota^{\hat{v}(0)} \Omega = 0$ and $J \wedge \Omega = 0$, or in other words

$$J^{(0)}_8 \wedge \Omega^{(0)}_4 = 0 .$$

(3.28)

Therefore $J^{(0)}_8$ and $\Omega^{(0)}_4$ define an $SU(4)$ structure on the eight-dimensional space $T_8$, i.e. inside $SL(8, \mathbb{R})$\(^7\). From the compatibility condition (3.7) it also follows that $g^{(0)}_8$ defined by

$$g^{(0)}_8 = e^{K_L/2} J^{(0)}_8 \cdot J^{(0)}_8 ,$$

(3.29)

is a symmetric object. Furthermore, explicit computation shows that $g^{(0)}_8$ is of the form

$$g^{(0)}_8 = (\det g_7)^{-1/4} \begin{pmatrix} g_7 & 0 \\ 0 & \det g_7 \end{pmatrix} .$$

(3.30)

Similar to (3.29) we also find for the inverse metric $g^{(0)-1}_8$ the expression

$$g^{(0)-1}_8 = e^{3K_L/2} I^{(0)}_8 \cdot (\text{vol}_8^{-1})_L \left( \frac{1}{3!} J^{(0)}_8 \wedge J^{(0)}_8 \wedge J^{(0)}_8 \right) .$$

(3.31)

General elements $L, K_a$ in the orbit can be achieved from $L^{(0)}, K^{(0)}_a$ by the action of $E_{7(7)}$, cf. (3.8). The degrees of freedom that can modify the above embeddings are the remaining massless fields of M-theory, namely the three-form gauge field $A_3$ and its

---

\(^7\)Note that this shift is not an $E_{7(7)}$ transformation because the four-form is not real.

\(^8\)As stated above, these objects define an $SU(6)$ structure inside $E_{7(7)}$. 
magnetic dual six-form field $A_6$. Their action in $SL(8)$ language is shown in (2.7). This gives
\begin{equation}
L = e^{A_4} \left( \text{vol}_8^{-1} \left( \text{vol}_8 \vee J_8 \wedge J_8 \right), \ -i J_8 \right), \tag{3.32}
\end{equation}
and
\begin{equation}
J_L = - e^{A_4} \left( 0, \ J_8 \wedge J_8 \right),
\end{equation}
where $A_4$ is defined in (2.8) and the shifted $J$ and $\Omega_4$ are
\begin{equation}
J_8 = J + v \wedge \rho_8, \quad \Omega_4 = \left( (1 + i a_6^v) \rho_8 + i v^{(0)} \right) \wedge \Omega - i \rho_8 \wedge v^{(0)} \wedge \iota_{\hat{A}} \Omega \tag{3.34}
\end{equation}
with $\hat{A}$ defined in (2.9), and
\begin{equation}
v = v^{(0)} - \iota_{\hat{A}} J, \quad a_6^v = \text{vol}_7^{-1} \cdot (v^{(0)} \wedge A_6). \tag{3.35}
\end{equation}
The symplectic and complex structure $J_8$ and $\Omega_4$ are also compatible, which means $J_8 \wedge \Omega_4 = 0$. Finally, the almost complex structure $I_8^{(0)}$ is shifted so that $\Omega_4^{(0)}$ is replaced by $\Omega_4$ in (3.22).

We see that the description of an $SU(6) \subset E_7$ structure in M-theory is completely analogous to the type II case discussed in [4], namely given by one object in the fundamental representation and a triplet in the adjoint. These are in turn described respectively by $J_8$ and $\Omega_4$, which define an $SU(4) \subset SL(8)$ structure, in a form that very much resembles the pure spinors $e^{-i J_8}$, $\Omega_4$ of two generalized almost complex structures. We will come back to this in Section 4.

We turn now to the Kähler potentials and prepotentials for the space of structures $L$ and (the hyper-Kähler cone over) $K_a$. They both have the expected form in terms of the $SU(4)$ structure objects $J_8$ and $\Omega_4$. The Kähler potential for $L$ can be easily computed from (3.9) to be
\begin{equation}
K_L = - \frac{1}{2} \log \left( \frac{1}{4} J_8 \wedge J_8 \wedge J_8 \wedge J_8 \right). \tag{3.36}
\end{equation}
The hyper-Kähler potential of the hyper-Kähler cone over the moduli space of $K_a$ is given by (3.10) and reads in terms of $\Omega_4$ as
\begin{equation}
\kappa = \sqrt{\frac{1}{2} \Omega_4 \wedge \bar{\Omega}_4}. \tag{3.37}
\end{equation}
Finally, the Killing prepotentials (3.13) are computed in Appendix B.2 using the differential operator $D$ in the 56 representation that is given by the embedding
\begin{equation}
D = (0, \rho_8 \wedge d). \tag{3.38}
\end{equation}
The result of the computation is given by
\begin{equation}
P^3 + iP^1 = - 4 \kappa \left( i J \wedge \rho_8 \wedge d\Omega_4^{(0)} + \iota_v \Omega_4^{(0)} \wedge \rho_8 \wedge dA_3 \right),
\end{equation}
\begin{equation}
P^2 = e^{-K_L} \text{Im} \left( \mathcal{L}_v \Omega_4^{(0)} \right) - 2\kappa^2 e^{K_L} \rho_8 \wedge J \wedge J \wedge v^{(0)} \wedge dv^{(0)} \tag{3.39}
\end{equation}
\begin{equation}
+ 4 \kappa \rho_8 \wedge \left( dA_6 - (A_3 + i \kappa v^{(0)} \wedge J) \wedge dA_3 \right),
\end{equation}
where $\mathcal{L}_v$ is the Lie derivative along $v$. 

10
3.3 $N = 1$ reductions

For reductions with $N = 1$ supersymmetry, there is a single $Spin(8)$ internal spinor $\eta$, which defines an $SU(7)$ structure in $E_7(7)$. This structure can be encoded in a nowhere-vanishing object $\phi$ in the $912$ representation of $E_7(7)$. The $912$ decomposes in $SU(8)$ representations in the same way as for $SL(8)$, given in (2.3). In terms of this decomposition, we have

$$\phi^{(0)} = (2\eta \otimes \eta, 0, 0, 0), \quad \bar{\phi}^{(0)} = (0, 0, 2\bar{\eta} \otimes \bar{\eta}, 0),$$

with the normalization

$$\bar{\eta} \eta = e^{-K_\phi/2}.$$  (3.41)

Using (A.22) we can write this in terms of $SL(8)$ representations (2.3)

$$\phi^{(0)} = -\left(c(g_8^{(0)})^{-1}, g_8^{(0)} \cdot (\text{vol}_{8}^{-1} \wedge \phi_4^{(0)}), ig_8^{(0)}, ig_8^{(0)} \cdot \phi_4^{(0)}\right)$$

where $g_8^{(0)}$ is the metric on $T_8$ (3.30), the complex constant $c$ is defined by

$$\eta^T \eta = c,$$  (3.43)

and

$$\phi_4^{(0)} = 3/8 \eta^T \gamma_{abcd} \eta.$$  (3.44)

Note that at points where $|c| \neq e^{K_\phi/2}$ real and imaginary part of $\eta$ actually define a (local) $SU(6)$-structure. In terms of the split into $7+1$ in (2.4), this can be written as

$$\phi_4^{(0)} = \rho_8 \wedge \alpha_3 + \ast_7 \alpha_3,$$  (3.45)

where $\alpha_3$ is a complex three-form that defines a $G_2 \times G_2$-structure which reduces to a real three-form in the $G_2$-structure case (i.e. when $\eta$ is Majorana). Note that $\phi_4^{(0)}$ is self-dual as $\eta$ is of positive chirality in $Spin(8)$.

A general element $\phi$ is obtained by

$$\phi = e^{A_4 \text{shifts}} \phi^{(0)} = -e^{A_4}(cg_8^{-1}, g_8 \cdot (\text{vol}_{8}^{-1} \wedge \phi_4), ig_8, ig_8^{-1} \cdot \phi_4),$$

where $A_4$, defined in (2.8), acts by the $E_7$ adjoint action (A.11), while $A_6$ shifts the metric (3.30) by

$$g_8 = (\text{det}_7)^{-1/4}\left(\begin{array}{cc}
g_7 + (*)_{7} A_6^2 & (\text{det}_7)^{1/2} (*)_{7} A_6 \\
(\text{det}_7)^{1/2} (*)_{7} A_6 & \text{det}_7
\end{array}\right),$$

and the 4-form

$$\phi_4 = \phi_4^{(0)} + \rho_8 \wedge \iota_A (*)_{7} \alpha_3.$$

Note that the volume form $\text{vol}_8$ of the metric $g_8$ in (3.47) is still given by the eight-dimensional epsilon tensor (with entries $\pm 1$ and 0), as there is no $R_+$ factor in $E_7(7)$ corresponding to the eight-dimensional volume. We will therefore sometimes abuse notation and make no distinction between an eight-form and a scalar.

The stabilizer of $\phi$ turns out to be indeed $SU(7)$ [3]. Therefore, the existence of $\phi$ is completely equivalent to $\eta$. We will denote the real and imaginary parts of $\phi$ by $\hat{\phi}$ and

---

This spinor can have a real and imaginary part and thereby actually defines an $SU(7) \times SU(7)$ structure.
\[ \mathcal{J}_\phi = 2\hat{\phi} \times \hat{\phi}, \quad (3.49) \]

which in terms of the \( SL(8) \) decomposition \((2.2)\) is

\[ \mathcal{J}_\phi = e^{A_4} \cdot (I_{\phi}, \phi^r_4) , \quad (3.50) \]

with

\[ (I_\phi)^a_b = -\frac{4}{3} (\text{vol}_8 \text{Re} \phi_4)^{acde} (\text{Im} \phi_4)_{bced} \quad (3.51) \]

and

\[ \phi^r_4 = 14 \text{Re}(\bar{c}\phi_4) = \frac{1}{2} e^{K_\phi/2} \bar{\eta}_{abcd} \eta \, dx^a \wedge dx^b \wedge dx^c \wedge dx^d . \quad (3.52) \]

The Kähler potential \( K_\phi \) in the orbit of \( \phi \) is given by the quartic invariant in the \( 912 \) and turns out to be

\[ K_\phi = -\log \sqrt{-q(\phi)} = -\log \sqrt{-\frac{1}{4} \mathcal{J}_\phi \cdot \mathcal{J}_\phi} = -\log \sqrt{-\frac{1}{4} \text{tr}(T^2_\phi)} - \frac{1}{2} \log \frac{1}{4!} \phi^*_4 \wedge \phi^r_4 \quad (3.53) \]

where in the last step we used \( (\iota_{A_3} * \gamma \alpha_3) \wedge * \gamma \alpha_3 = 0 \). Therefore, the Kähler potential does not depend on \( A_6 \) and \( A_4 \), in agreement with \( E_{7(7)} \) invariance. Note that this expression reduces to the known one in the \( G_2 \)-structure case.

As has been derived in \cite{3}, the superpotential \( W \) is given through the eigenvalue equation

\[ (D\phi) \cdot \phi = (e^{K_\phi/2}W)\phi , \quad (3.54) \]

where \( D \) is defined in \((3.38)\). We present the detailed computation of the superpotential in Appendix \( B.1 \). We get

\[ e^{K_\phi/2}W = \iota_{\rho_8} \phi^{(0)}_4 \wedge d\phi^{(0)}_4 + \rho_8 \wedge dA_6 - 2i \phi_4 \wedge \iota_{\rho_8} dA_4 + \iota_{\rho_8} A_4 \wedge dA_4 . \quad (3.55) \]

which is exactly the result of \cite{3}. A similar result for manifolds of \( G_2 \) structure has been obtained in \cite{10}.

### 3.4 \( N = 2 \) in the language of \( N = 1 \)

To finish this section, we note that the \( SU(6) \) structure of \( N = 2 \) reductions can also be understood as a triple of \( SU(7) \) structures, by using the product \( 133 \times 56 \to 912 \) given in \((A.10)\). We find the objects

\[ \tilde{\phi}^{(0)}_a = \tilde{L}^{(0)} \otimes K_a^{(0)} = 2\kappa (\epsilon_{ik}(\sigma_a)^k_j \eta_i \otimes \eta_j, 0, \epsilon_{ik}(\sigma_a)^k_j \bar{\eta}_i \otimes \bar{\eta}_j, 0) , \quad (3.56) \]

which are non-zero and define an \( SU(2) \) triplet of \( SU(7) \) structures of the form given in \((3.40)\). The index \( a \) here labels the various symmetric combinations of the \( \eta_i \). A spinor
Choosing $T_5$ decomposes as one-dimensional pieces, i.e. $4.1$ Type IIA and $4$ Type IIA reductions of these $SU(4)\text{ winding, their magnetic duals and the p-brane charges.}$

where from the last expression we recognize the type IIA charges, namely momentum, winding, their magnetic duals and the p-brane charges.

For an $SU(6)$ structure the $\phi_a^{(0)}$ can be computed in terms of the $SU(4)$ forms $J_8$ and $\Omega_4$ on the 8-dimensional bundle. For this, we use $(3.29)$ and $(3.31)$. In terms of the decomposition $(2.3)$, we then find

$$
\phi_1^{(0)} = -2e^{-K_L/2}(0, i g_8^{(0)} \cdot (\text{vol}_8^{-1} \cdot \text{Re} \Omega_4^{(0)}), 0, (g_8^{(0)})^{-1} \cdot \text{Re} \Omega_4^{(0)}), \\
\phi_2^{(0)} = -2e^{-K_L/2}K((g_8^{(0)})^{-1}, e^{K_L}g_8^{(0)} \cdot (\text{vol}_8^{-1}(J_8^{(0)} \wedge J_8^{(0)})), i g_8^{(0)}, i e^{K_L}(g_8^{(0)})^{-1} \cdot (J_8^{(0)} \wedge J_8^{(0)}), \\
\phi_3^{(0)} = -2e^{-K_L/2}(0, -i g_8^{(0)} \cdot (\text{vol}_8^{-1} \cdot \text{Im} \Omega_4^{(0)}), 0, (g_8^{(0)})^{-1} \cdot \text{Im} \Omega_4^{(0)}),
$$

where $g_8^{(0)}$ is given in $(3.30)$. As before, the general form of $\phi_a$ is obtained by acting with $A_6$ and $A_3$ on the above expressions. The action of $A_6$ turns $g_8^{(0)}$ into $g_8$ (cf. Eq. $(3.47)$), $J_8^{(0)}$ into $J_8$ and $\Omega_4^{(0)}$ into $\Omega_4$ (see $(3.34)$), while $A_3$ acts as usual by the 4-form shift $e^{g_8 \wedge A_3}$.

One can therefore understand the $SU(6)$ structure in $E_7$ relevant for $N = 2$ compactifications as a triple of $SU(7)$ structures. When we perform a projection on the $SU(6)$ structure, for instance by orbifolding or orientifolding, a single combination of these $SU(7)$ structures will survive, giving the $N = 1$ description one expects. We will discuss such projections in Section 5.

4 Type IIA reductions

4.1 Type IIA and $GL(6)$ decompositions

To descend to type IIA, we further split the 7-dimensional tangent space into six plus one-dimensional pieces, i.e.

$$
T^*_7 = T^*_6 \oplus T^*_y \\
\rho_m = (\rho_m, \rho_y)
$$

Choosing $T_y$ to have no $GL(6)$ weight, we get that the exceptional tangent bundle $(2.5)$ decomposes as $56 = 6 \oplus 6 \oplus 6 \oplus 6 \oplus 32$, i.e.

$$
E_{\text{IIA}} = (\Lambda^6 T_6)^{1/2} \otimes ((T_6 \oplus \Lambda^2 T^*_6 \oplus \Lambda^2 T^*_6 \oplus T^*_6 \oplus \Lambda^4 T^*_6 \oplus \Lambda^4 T^*_6 \oplus (T^*_6 \otimes \Lambda^6 T^*) \oplus \Lambda^6 T^*) \\
= (\Lambda^6 T_6)^{1/2} \otimes ((T_6 \oplus T^*_6 \oplus \Lambda^5 T^*_6 \oplus (T^*_6 \otimes \Lambda^6 T^*) \oplus \Lambda^\text{even} T^*_6), \\
$$

where from the last expression we recognize the type IIA charges, namely momentum, winding, their magnetic duals and the p-brane charges.
The adjoint decomposes as

\[
A_{\text{IIA}} = [\lambda \oplus (T_6 \otimes T_6^*)_0] \oplus (T_y \otimes \Lambda^2 T_6) \oplus (T_y^* \otimes \Lambda^2 T_6^*)] \oplus [\varphi \oplus \Lambda^6 T_6 \oplus \Lambda^6 T_6^*]
\]

\[
\oplus [(T_y \otimes T_6^* \oplus \Lambda^3 T_6^* \oplus (T_y^* \otimes \Lambda^5 T_6^*)] \oplus [(T_y^* \otimes T_6 \oplus \Lambda^3 T_6 \oplus (T_y \otimes \Lambda^5 T_6)]
\]

\[
= (T_6 \otimes T_6^*) \oplus \Lambda^2 T_6 \oplus \Lambda^2 T_6^* \oplus \varphi \oplus \Lambda^6 T_6 \oplus \Lambda^6 T_6^* \oplus \Lambda^{\text{odd}} T_6^* \oplus \Lambda^{\text{odd}} T_6
\]

where

\[
\lambda = dy \otimes \partial_y , \quad \varphi = 2dy \otimes \partial_y + dx^\hat{m} \otimes \partial_{\hat{m}},
\]

are linear combinations of the generators for shifts in the volumes of the six-dimensional part and the eleventh dimension. From the last equality we recognize the \(O(6,6)\) adjoint, where the \(GL(6)\) and \(B_2\)-field transformations live, the \(SL(2)\) adjoint where the dual \(B_6\) of \(B_2\) is, and the sum of odd forms corresponding to the shifts of the RR potentials.

More precisely, under the breaking of the U-duality group \(E_{7(7)}\) into the product of T-duality and S-duality group \(SO(6,6) \times SL(2)\), the fundamental representation splits according to\(^{10}\)

\[
56 = (12, 2) \oplus (32, 1),
\]

\[
L^A = (L^{A^i}, L^\pm)
\]

where \(A = 1, \ldots, 12\) \((i = 1, 2)\) is a fundamental \(O(6,6)\) \((SL(2))\) index, and \(\pm\) represents a positive or negative chirality \(O(6,6)\) spinor (the plus is relevant for type IIA and M-theory, while for type IIB we need the negative chirality representation). The adjoint decomposes as the adjoint of each group, plus a spinor contribution

\[
133 = (66, 1) \oplus (1, 3) \oplus (32', 2),
\]

\[
K = (K^A_B, K^i_j, K^{\pm i}).
\]

The embedding of the gauge fields \(B_2, B_6\) and \(C^\mp\) (that we will call collectively \(A_{\text{shifts}}\)) in type IIA and type IIB is the following\(^4\)

\[
A_{\text{shifts}} = \left(\begin{pmatrix} 0 & B_2 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & B_6 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} C^\mp \\ 0 \end{pmatrix}\right).
\]

We can now write explicitly the one-form \(v\) and gauge fields \(A_3\) (or \(A_4\)), \(A_6\) of the previous sections in terms of their type IIA counterparts

\[
v^{(0)} = dy + C_1, \quad C_5 = \iota_{\partial_y} A_6, \quad A_4 = \rho_8 \wedge (C_3 - dy \wedge B_2), \quad \iota_{\partial_y} C_3 = 0.
\]

Inspecting (2.7), we can write the \(E_{7(7)}\) embedding of the gauge fields in \(SL(8, R)\) decomposition (cf. (2.2)) as follows

\[
A_{\text{shifts}} = (C_1 \otimes \partial_y + \rho_8 \otimes \hat{C}_5, \rho_8 \wedge C_3 - \rho_8 \wedge dy \wedge B)
\]

where \(\hat{C}_5\) is the vector associated to \(C_5\), i.e.

\[
\hat{C}_5 = \text{vol}^{-1}_6 \cdot C_5.
\]

\(^{10}\)S-duality here does not refer to the type IIB S-duality, but as the group that acts by fractional linear transformations on \(\tau = B_6 + 1e^{-\varphi} \).
\section*{4.2 \( N = 2 \) and \( N = 1 \) reductions}

As in M-theory, reductions to 4D with \( N = n \) supersymmetry require \( n \) internal \( SU(8) \) spinors \( \eta^i \), which show up in the decomposition of the two ten-dimensional spinors \( \epsilon^{1,2} \) as follows

\[
\begin{pmatrix}
\epsilon^1 \\
\epsilon^2
\end{pmatrix} = \xi^- \otimes \eta_i + \text{c.c.}
\]

(4.11)

where \( \eta_i \) are \( SU(8) \) spinors that combine the \( SU(4) \cong O(6) \) spinors that build up \( \epsilon_1 \) and \( \epsilon_2 \).

Given \( \eta_{1,2} \) and \( \eta \) for the case of \( N = 2 \) and \( N = 1 \), the reductions work exactly as in M-theory, namely one builds the structures \( L^{(0)}, K_3^{(0)} \) as in (3.4), (3.6) in the case of \( N = 2 \) \cite{4}, and \( \phi^{(0)} \) as in (3.10) in the case of \( N = 1 \). Their full orbit is obtained by the \( E_{7(7)} \) action of the gauge fields (4.9).

Let us concentrate on the \( N = 2 \) case now. The form of \( L \) resembles very much the pure spinor counterpart \( e^{B+iJ} \) for an \( SU(3) \) structure. Indeed, we get

\[
L = e^{(C_1 \otimes \theta_3 + \rho_8 \otimes C_5, \rho_8 \wedge C_3)} e^{\rho_8 \wedge dy \wedge (-B-iJ)}. \quad (\hat{\rho}_8 \wedge \hat{v}, 0)
\]

(4.12)

Note however that \( J \) here is a 2-form constructed as a bilinear of two different \( SU(8) \) spinors, and furthermore it is complex. To make the comparison with GCG more straightforward, one can parameterize them as \footnote{In standard Calabi-Yau compactifications, one takes \( \theta^1 = \theta^2 = \theta, \hat{\theta}^i = 0 \). Note that in this case \( \eta_i \) as defined in (4.13) are not Majorana, but the combinations \( \eta_1 + \eta_2 \) and \( i(\eta_1 - \eta_2) \) are.}

\[
\eta_1 = \begin{pmatrix} \theta_1^1 \\ \bar{\theta}_1^-
\end{pmatrix}, \quad \eta_2 = \begin{pmatrix} \theta_2^2 \\ \bar{\theta}_2^-
\end{pmatrix}
\]

(4.13)

For the special ansatz \( \bar{\theta}^i = 0 \), \( L \) and \( K \) have particularly nice forms in terms of the \( O(6,6) \) pure spinors\footnote{Note that for this ansatz, \( J (\Omega) \) contains the bilinears between the two \( \theta \)'s involving two (three) \( \text{Spin}(6) \) gamma matrices.}

\[
\Phi^\pm = e^{B(\theta_1^1 \otimes \bar{\theta}_2^-)}
\]

(4.14)

the \( SL(2, R) \) vielbein \( u^i \) related to the four-dimensional axiodilaton, \( i = 1, 2 \), and the RR-spinor \( C = C_1 + C_3 + C_5 \) as \footnote{Note that for this ansatz, \( J (\Omega) \) contains the bilinears between the two \( \theta \)'s involving two (three) \( \text{Spin}(6) \) gamma matrices.}

\[
L = e^{C(0, \Phi^+)} \, , \quad K_3 + iK_1 = e^{C(0, 0, u^i\Phi^-)} \, ,
\]

(4.15)

where this is written in the \( O(6,6) \times SL(2, R) \) decomposition of \( E_{7(7)} \), given explicitly below in (4.5), (4.6), and \( K_2 \) is just the commutator of \( K_3 \) and \( K_1 \).

\section*{5 \ From \( N = 2 \) to \( N = 1 \): Orientifolding and orbifolding in EGG}

As we will show in detail in Section \footnote{In standard Calabi-Yau compactifications, one takes \( \theta^1 = \theta^2 = \theta, \hat{\theta}^i = 0 \). Note that in this case \( \eta_i \) as defined in (4.13) are not Majorana, but the combinations \( \eta_1 + \eta_2 \) and \( i(\eta_1 - \eta_2) \) are.} 5.2.4, orientifolds break the \( E_{7(7)} \) covariance into that of the subgroup \( O(6,6) \times SL(2, R)_O \), where the “\( O \)” makes it explicit that this is a different subgroup from that of \( T \) and \( S \)-duality. Furthermore, as we will see, each orientifold projection gives rise to a different \( O(6,6) \times SL(2, R) \) subgroup. The splitting of the fundamental and adjoint representations of \( E_{7(7)} \) has been given in (4.5) and (4.6).
5.1 Orbifold action on $T_8$ and its reduction to M-theory

The M-theory uplift of type IIA O6-orientifolds are a geometric involution on the 7-dimensional space. Such an involution can in turn be uplifted to an orbifold action $\tilde{\sigma}^*$ on the 8-dimensional space $T_8$ such that the $SL(8)$ bundle decomposes at the locus of the action into a positive and a negative eigenbundle

$$T_8 = T_8^+ \oplus T_8^-,$$  \hspace{1cm} (5.1)

and such that both subspaces are four-dimensional. The adjoint of $E_{7(7)}$ decomposes under (5.1) as

$$E = (T_8^+ \otimes T_8^{*+})_0 \oplus (T_8^- \otimes T_8^{*-})_0 \oplus (\Lambda^2 T_8^+ \otimes \Lambda^2 T_8^{*-}) \oplus T_0 \oplus \Lambda^4 T_8^{**+} \oplus \Lambda^4 T_8^{*-} \oplus (T_8^+ \otimes T_8^-) \oplus (T_8^- \otimes T_8^{**+}) \oplus (\Lambda^3 T_8^{**+} \otimes \Lambda^3 T_8^{*-}) \oplus (\Lambda^1 T_8^{**+} \otimes \Lambda^3 T_8^{*-}),$$  \hspace{1cm} (5.2)

where $T_0$ is the element of the adjoint that acts as $\pm 1$ on $T_8^\pm$. By comparing to (4.6), we can see how $E_7$ is broken into $O(6,6) \times SL(2,\mathbb{R})$, the first line builds up the adjoint of $O(6,6) \times SL(2,\mathbb{R})_\sigma$, which is even under the orbifold action, while the terms in the second line are odd and form the $(2,32')$ representation. Similarly, the fundamental of $E_{7(7)}$, given in (2.1) in terms of $SL(8)$ representations, decomposes as

$$A = \Lambda^2 T_8^+ \oplus \Lambda T_8^+ \oplus \Lambda^2 T_8^- \oplus \Lambda^2 T_8^{*-} \oplus (T_8^+ \otimes T_8^-) \oplus (T_8^- \otimes T_8^{**+}) \oplus (T_8^- \otimes T_8^{**+}),$$  \hspace{1cm} (5.3)

where the first four terms are even and form the $(12,2)$ representation of $O(6,6) \times SL(2,\mathbb{R})_\sigma$ (see Eq. (4.5)), while the last two, odd terms, form the $(32,1)$.

To descend to M-theory, we require the orbifold action to have positive eigenvalue when acting on $\hat{\rho}_s$. Eq. (2.4) tells us then that $T_7^+$ is three-dimensional, while $T_7^-$ is four-dimensional. Finally, to recover the type IIA orbifold action that gives rise to O6 planes, we require $\hat{v}$ to have negative eigenvalue. In summary

$$T_8 = T_8^+ \oplus T_8^- = (T_7^+ \oplus T_7^{**}) \oplus T_7^- = (T_6^+ \oplus T_6^{**}) \oplus (T_6^- \oplus T_6^-).$$  \hspace{1cm} (5.4)

We will come back to the full orientifold projection later in Section 5.2.1.

Now let us see how the orbifold acts on the $N = 2$ structures defined in the previous sections. In type IIA, an involutive symmetry $\sigma$ that can be used to mod out the theory should be anti-holomorphic if $N = 1$ supersymmetry is to be preserved [11]. This means that for an $SU(3)$ structure defined by $J$ and $\Omega$, it should act as $\sigma^* J = - J, \sigma^* \Omega = \Omega$. This is easy to uplift to an action on $J_8, \Omega_4$ defining the $SU(4)$ structure on $T_8$, namely we require $\sigma$ to act as

$$\tilde{\sigma}^* J_8 = - J_8, \quad \tilde{\sigma}^* \Omega_4 = - \Omega_4.$$  \hspace{1cm} (5.5)

This implies that the action induced by $\tilde{\sigma}^*$ on $K_a$ and $L$ in the $133$ and the $56$ representation, which define an $SU(6) \subset E_7$ structure, should be

$$\tilde{\sigma}^* L = - L, \quad \tilde{\sigma}^* K_1 = K_1, \quad \tilde{\sigma}^* K_{2/3} = - K_{2/3}.$$  \hspace{1cm} (5.6)

Therefore, $L$ and $K_{2/3}$ are not well-defined any more in the presence of fixed points. However, their products are well-defined under the orbifold action. More precisely, their
product in the $912$ representation is defined by

$$L \otimes (K_2 + i K_3) = \sqrt{\kappa} \phi ,$$

(5.7)

where the pre-factor $\sqrt{\kappa}$ appears due to the different normalizations in (3.2) and (3.41). This $\phi$ in the $912$ defines in turn an $SU(7)$ structure following Section 3.3, corresponding to the single spinor that survives the orbifolding. $\phi$ defines the metric $g$ and a four-form $\phi^4$, cf. (3.46). From (5.7) we find

$$\phi^4 = \sqrt{\kappa} e^{-K_L/2} \Im \Omega_4 + \sqrt{\kappa} e^{K_L/2} J_8 \wedge J_8 ,$$

$$\phi^*_4 = e^{-K_L} \Im \Omega_4 + \kappa J_8 \wedge J_8 .$$

(5.8)

We find the second expression using $c = \sqrt{\kappa} e^{-K_L/2}$.

The orbifold projection selects an $N = 1$ special Kähler subspace inside the $N = 2$ Kähler and quaternionic spaces. The generator of its complex structure is given in (3.50), which can in turn be written in terms of the $SU(4)$-structure objects $J_8$ and $\Omega_4$ in $L$ and $K$ respectively as

$$J_\phi = e^{A_4} \cdot (0, e^{-K_L} \Im \Omega_4 + \kappa J_8 \wedge J_8) = e^{-K_L} K_1 + \kappa J^L .$$

(5.9)

Therefore, the complex structure on the $N = 1$ Kähler space $e^{J_\phi}$ is the tensor product of the complex structures $e^{K_1}$ with $e^{J^L}$. If the orbifold singularities were blown-up (see comments below), $e^{J_\phi}$ would not be block-diagonal any more. As long as the singularities are not blown up, the Kähler potential (3.53) simplifies to the sum the two Kähler potentials for $L$ and $K$, i.e.

$$K_\phi = -\frac{1}{2} \log \kappa + K_L + \frac{1}{2} \log 2 ,$$

(5.10)

The superpotential is given in (3.55). On the other hand, we have the Killing prepotentials (3.39) that should descend to the $N = 1$ description. Comparing both expressions we find the relation

$$e^{K_\phi/2} W = \frac{1}{2} \kappa^{-1} (P^2 + i P^3) .$$

(5.11)

The above formulas are valid for the orbifold of an $SU(6)$ structure. If we blow-up the singularities resulting from the orbifolding, we switch on additional modes in $\phi$ that alter its form from the one given in (5.7). More precisely, the objects $K_{2/3}$ and $L$ are not well-defined on the blown-up manifold, while $\phi$ still defines the geometry. The blow-up should lead to new modes that enter $\phi^4$ as extra four-forms.

## 5.2 Further descent to type IIA

### 5.2.1 O6 orientifolds

To recover O6-orientifolds, the orbifold involution $\tilde{\sigma}$ should have negative eigenvalue on $T_y$, i.e. act on $T_7$ as $\text{diag}(\sigma, -1)$ where $\sigma$ is an involution on the 6-dimensional space $T_T$.

\footnote{Note that the 56 component of their tensor product is forced to be zero by the compatibility condition.}
whose action is given above [5.5]. Furthermore, the O6 projection mods out by the action of $\sigma \Omega_p (-1)^F_L$, where $\Omega_p$ is the worldsheet parity, and $(-1)^F_L$ gives an additional minus sign on the RR sector. The uplift of this combination is the purely geometric involution $\bar{\sigma}$.

The combined operation $\Omega_p (-1)^F_L$ has a different action on the different $O(6,6) \times SL(2, \mathbb{R})$ components of $L$ and $K_a$. On $O(6,6)$ bispinors, such as the RR potentials or the pure spinors of generalized complex geometry $\Phi^\pm$, which are tensor products of a left and a right-moving spinor, it acts in the following way [12]

$$(-1)^F_L \Omega_p \Phi^+ = \lambda(\Phi^+) \ , \ \ (-1)^F_L \Omega_p \Phi^- = - \lambda(\Phi^-) \ , \ \ (-1)^F_L \Omega_p C = \lambda(C) \ (5.12)$$

where $\lambda$ is the following action on forms

$$\lambda(\alpha_{2p}) = (-1)^p \alpha_{2p} \ , \ \ \lambda(\alpha_{2p-1}) = (-1)^p \alpha_{2p-1} \ . \ (5.13)$$

This can be understood since worldsheet parity exchanges the left and right-moving sectors, and on the bispinors, which are tensor products of left and right moving spinors, it acts by transposition. Since the orientifold projection keeps states which are even under the action of $\sigma (-1)^F_L \Omega_p$, one requires the involution to satisfy

$$\sigma^* \Phi^+ = \lambda(\Phi^+) \ , \ \ \sigma^* \Phi^- = - \lambda(\Phi^-) \ , \ \ \sigma^* C = \lambda(C) \ . \ (5.14)$$

We want to define an analogous “$\lambda$-operation” as an action on fundamental $SL(2)$ and $O(6,6)$ indices. The following operator acting respectively on the 12 of $O(6,6)$, 2 of $SL(2, \mathbb{R})$ and 32 of $O(6,6)$ does the job

$$\tilde{\lambda} = \left( \begin{array}{cc} 1_{6 \times 6} & 0 \\ 0 & -1_{6 \times 6} \end{array} \right) \otimes \left( \begin{array}{cc} 1 & 0 \\ 0 & -1 \end{array} \right) \otimes (-\lambda) \ . \ (5.15)$$

For higher representations $\tilde{\lambda}$ just acts on all indices [14]. Therefore, on the fundamental 56 representation, which decomposes into $O(6,6) \times SL(2, \mathbb{R})$ as in (4.5), this action reads

$$\tilde{\lambda}(L) = \left( \begin{array}{cc} L^\dagger_{\dot{m}1} & -L_{\dot{m}1} \\ -L_{\dot{m}2} & L^\dagger_{\dot{m}2} \end{array} \right) , \ -\lambda(L^+) \ . \ (5.16)$$

On the adjoint representation, whose $O(6,6) \times SL(2, \mathbb{R})$ decomposition is given in (4.6), we get

$$\tilde{\lambda}(K) = \left( \begin{array}{cc} K^\dagger_{\dot{m}1} & -K_{\dot{m}1} \\ -K^\dagger_{\dot{m}2} & K_{\dot{m}2} \end{array} \right) , \ -\lambda(K^+) \ . \ (5.17)$$

(\text{where by construction } K^2_1 = -K^1_1 \text{ and } K^2_2 = -K^1_2)\).  

The claim is that $\tilde{\lambda}$ acts like $\Omega_p (-1)^F_L$ on $K_1$, while on $L$ and $K_{2/3}$ it is $-\tilde{\lambda}$ that does the job. The fields that will survive the orientifold projection are therefore those for which $\sigma$ acts in the following way

$$\sigma^* L = -\tilde{\lambda}(L) \ , \ \ \sigma^* K_1 = \tilde{\lambda}(K_1) \ , \ \ \sigma^* K_{2/3} = -\tilde{\lambda}(K_{2/3}) \ . \ (5.18)$$

\footnote{Note that the action on $T \oplus T^*$ then induces the action $\lambda$ in (5.13) on the spinor representation (isomorphic to a sum of forms).}
In the language of (4.13), we see from (3.4)-(3.6) that the action of $\tilde{\lambda}$ corresponds to the exchange of the two spinors $\eta^j$.

For the corresponding vector fields $L_\mu = (L_\mu^A, L_\mu^+)$ in the 56 representation we have

$$\sigma^* L_\mu = \tilde{\lambda}(L_\mu) \ . \quad (5.19)$$

Here, $L_\mu^A$ are the electric and dual magnetic vectors coming from the off-diagonal components of the metric and the B-field, while $L_\mu^+$ collects the Ramond-Ramond fields with one external leg, i.e. $L_\mu^+ = (C_1)_\mu + (C_3)_\mu + (C_5)_\mu + (C_7)_\mu$.

### 5.2.2 Type IIB orientifolds

For completeness (and because we will use later O9 as an illustration) we give the action for type IIB orientifolds.\(^\text{15}\) There, the theory is modded out by $\sigma \Omega_p (-1)^{F_L}$ for O3/O7 projection, and $\sigma \Omega_p$ for O5/O9. This means that the latter projection has an extra minus sign on the $O(6,6)$ spinors with respect to the type IIA case, i.e. we define

$$\tilde{\lambda}_{\text{IIB}} = \begin{pmatrix} 1_{6\times 6} & 0 \\ 0 & -1_{6\times 6} \end{pmatrix} \otimes \begin{pmatrix} 1 & 0 \\ 0 & -1 \end{pmatrix} \otimes \pm \lambda , \quad (5.20)$$

where the plus sign is for O3/O7 projections, while the minus applies to O5/O9. This contributes to a $\pm$ sign in the last components of (5.16) and (5.17). We then require (5.18) and (5.19), with $\tilde{\lambda}$ replaced by $\tilde{\lambda}_{\text{IIB}}$.

### 5.2.3 New $\mathbb{Z}_2$ projections

In general, new orientifold actions can be found by conjugating known orientifold actions with elements in $E_7(7)$($\mathbb{Z}$). For all these new orientifolds our discussion applies. A simple example of a new $\mathbb{Z}_2$ action is the NS5-projection that is related to O5-orientifolding in type IIB by S-duality in ten dimensions. Concerning the involution, S-duality only exchanges the roles of the $B$ field and the field $C_2$. Therefore, the NS-NS (R-R) sector is even (odd) under the resulting involution, which thus can be written as $(-1)^{F_L} \sigma$, where $F_L$ is the left-moving fermion number on the world-sheet and $\sigma$ is an involution of the internal space that inverts four of the internal directions, satisfying the following on the pure spinors of GCG and the RR fields

$$\sigma^* \Phi^\pm = \Phi^\pm , \quad \sigma^* C = -C . \quad (5.21)$$

Correspondingly, the involution $\tilde{\lambda}_{\text{NS5}}$ is

$$\tilde{\lambda}_{\text{NS5}} = 1_{12 \times 12} \otimes 1_{2 \times 2} \otimes (-1)^{32} . \quad (5.22)$$

Subsequently, the roles of $K_1$ and $K_3$ are exchanged with respect to (5.6). S-duality implies that the fixed points of this action are negative tension objects with negative NS5-brane charge.

\(^{15}\)Note that in type IIB the roles of $\Phi^+$ and $\Phi^-$ are exchanged.
Note that this action can be defined in a completely analogous way in type IIA, and it can be uplifted to M-theory to find the orientifolding for M5-branes, with
\[
\tilde{\sigma}_M^* dy = -dy , \quad \tilde{\sigma}_M^* \rho_8 = -\rho_8 .
\] (5.23)
The analogous D4-orientifolding lifts to the same expression, but without any involution of \(dy\). Though we can uplift these involutions to M-theory, even with these assignments for \(\tilde{\sigma}_M\), the M5-involution does not become an orbifold action. More precisely, it acts on the adjoint representation as \(\sigma_M^*\) but on the exceptional generalized tangent bundle with an extra minus sign, i.e. with \(-\sigma_M^*\). Therefore, the projection on \(L\) and \(K_a\) is given by
\[
\tilde{\sigma}_M^* L = L , \quad \tilde{\sigma}_M^* K_1 = K_1 , \quad \tilde{\sigma}_M^* K_{2/3} = -K_{2/3} ,
\] (5.24)
in contrast to the orbifold action given in (5.6). Thus, no \(SU(7)\) structure surviving the involution can be defined. As a consequence the fixed points of \(\sigma_M\) cannot be resolved in a geometric way within M-theory, in contrast to the orbifold fixed points of Section 5.1.

### 5.2.4 Kähler subspaces

Here we show how the orientifold projection selects the \(N = 1\) special Kähler subspaces inside the \(N = 2\) Kähler and quaternionic ones. Before we analyze how a Kähler space emerges from the projection on the hypermultiplets, we first want to understand the reduction of \(E_{7(7)}\) under the orientifolding. Let us first start with an orientifolding to O9-planes, i.e. \(\sigma\) is the identity (and we are modding out the theory just by the action of \(\Omega_p\)). As the representations of \(E_{7(7)}\) split into the even and odd parts under \(\tilde{\lambda}\), they form representations of a subgroup of \(E_{7(7)}\) that is the subgroup of even transformations. Therefore, we analyze the action of \(\tilde{\lambda}\) on the adjoint of \(E_{7(7)}\), split into representations of the subgroup \(O(6,6) \times SL(2,\mathbb{R})\) corresponding to T- and S-duality subgroups, cf. Eq. (4.6). \(^{16}\)

On the adjoint of \(O(6,6)\), \(\tilde{\lambda}\) acts as in the first component of (5.17). The 66 representation therefore gets projected to
\[
66 \rightarrow 35_0 \oplus 1_0 , \quad (5.25)
\]
\[
\mu^A_B \rightarrow \mu^\hat{m}_{\hat{n}}
\]
Thus we find \(O(6,6) \rightarrow GL(6,\mathbb{R}) = SL(6,\mathbb{R}) \times \mathbb{R}_+\) (and the subindex denotes the charge under this \(\mathbb{R}_+\), corresponding to the volume). Similarly
\[
3 \rightarrow 1_0 , \quad (5.26)
\]
\[
\mu^i_j \rightarrow \mu^1_1
\]
and thus \(SL(2,\mathbb{R}) \rightarrow \mathbb{R}_+\) (and the subindex denotes the charge under this \(\mathbb{R}\), corresponding to the dilaton). Finally, on the \((32',2)\) representation we get (recall that for O9, \(\tilde{\lambda}_{\text{IIB}}\) acts as \(-\lambda\) on the spinor)
\[
(32',2) \rightarrow 1_{(+1,+1)} \oplus 15_{(+1,-1)} \oplus 1_{(-1,-1)} \oplus 15'_{(-1,+1)} , \quad (5.27)
\]
\[
\mu^{+i} \rightarrow \mu_0^{+i} + \mu_1^{+i} + \mu_2^{+i} + \mu_3^{+i} .
\]
\(^{16}\)Here S-duality does not refer to the type IIB S-duality acting on the RR axion \(C_0\) and the dilaton, but the S-duality within the NS sector, that acts on \(\tau = B_6 + i e^{-\phi}\).
On the first line we stated the \( SL(6, \mathbb{R}) \) representations and denoted the charges under the two \( R_+ \) factors coming from the volume and the dilaton, and on the second line the superscript denotes the \( SL(2) \) component, while the number in parenthesis in the subscript denotes the degree of the form.

We see that the diagonal \( R_+ \) factor together with the two scalars in (5.27) forms an \( SL(2, \mathbb{R}) \) group, while the two \( 15 \)s together with the non-diagonal \( R_+ \) factor enhance the \( SL(6, \mathbb{R}) \) to \( O(6, 6) \). Thus, the new covariance group is \( O(6, 6) \times SL(2, \mathbb{R}) \). Since this is a different \( O(6, 6) \times SL(2, \mathbb{R}) \) from the original one associated with S- and T-duality (see Footnote 16), we call this \( O(6, 6) \times SL(2, \mathbb{R})_O \). Thus we get

\[
E_7 \rightarrow O(6, 6) \times SL(2, \mathbb{R})_{O_0},
\]

\[
\mu \rightarrow \left( \begin{pmatrix} \mu_1 & \mu_{1(2)} \\ \mu_{2(4)} & \mu_{\tilde{m}} \end{pmatrix}, \begin{pmatrix} \mu_1 & \mu_{1(6)} \\ \mu_{2(0)} & -\mu_{1(1)} \end{pmatrix}, 0 \right),
\]

\[
A_{\text{shifts}} \rightarrow \left( \begin{pmatrix} 0 & C_2 \\ 0 & 0 \end{pmatrix}, \begin{pmatrix} 0 & C_6 \\ 0 & 0 \end{pmatrix}, 0 \right)
\]

where in the last line we have used the \( O(6, 6) \times SL(2, \mathbb{R}) \) embedding of the \( B \) and \( C \)-fields given in (4.17).

If \( \sigma \) is not the identity, the situation is slightly more involved. The orientifolding in general maps different points onto each other. Only at the locus of the \( O \)-planes the covariance group can be really projected to a subgroup. Let us consider the case of an \( O(3 + p) \)-plane. At the \( O(3 + p) \)-plane we can split the tangent space

\[
T \rightarrow T^{(p)}_\parallel \oplus T^{(6-p)}_\perp,
\]

(5.28)

where the supraindex in parenthesis indicates the dimensions of each space. The involution \( \sigma^* \) acts as \(+1\) on \( T^{(p)}_\parallel \) and as \(-1\) on \( T^{(6-p)}_\perp \). Therefore, the combination \( \sigma^* \lambda \) projects the geometric group

\[
Gl(6, \mathbb{R}) \rightarrow Gl^{(p, \mathbb{R})}_\parallel \times Gl^{(6-p, \mathbb{R})}_\perp.
\]

(5.29)

Furthermore, \( \sigma^* \lambda \) projects

\[
\Lambda^2 T^* \rightarrow T^{(p)}_\parallel \otimes T^{(6-p)}_\perp, \quad \Lambda^2 T \rightarrow T^{(p, \mathbb{R})}_\parallel \times T^{(6-p, \mathbb{R})}_\perp,
\]

(5.30)

and these give each the \( (p, 6 - p) \) representations that enhance \( Gl^{(p, \mathbb{R})}_\parallel \times Gl^{(6-p, \mathbb{R})}_\perp \) to \( Gl(6, \mathbb{R})_{O(3+p)} \). Thus, as for the case of O9-planes, we find \( O(6, 6) \rightarrow Gl(6, \mathbb{R})_{O(3+p)} \), but now to a different \( Gl(6, \mathbb{R}) \) indicated by the subindex. Under the breaking \( O(6, 6) \rightarrow Gl(6, \mathbb{R})_{O(3+p)} \), the \( (2, 32') \) representation projects as in (5.27). Here, the two surviving singlets are \( \Lambda^p T^* \parallel \) and \( \Lambda^{(6-p)} T^* \parallel \), which form singlets under the emerging \( Gl(6, \mathbb{R})_{O(3+p)} \). Hence, we see that for all orientifold actions, the covariance group projects to \( O(6, 6) \times SL(2, \mathbb{R})_{O(p-3)} \) (as we saw this subgroup is different for each type of orientifold).

Now let us consider the projection (5.18) on the vector and hypermultiplet sectors. The vector fields that survive the orientifold projection are those that are even under \( \sigma^* \lambda \) (see (5.19)). For O9, where \( \sigma \) is the identity and \( \lambda \) acts as \(-\lambda \) in the spinor part, we get that the surviving vector fields are the Kaluza-Klein vectors as well as the vectors associated with the internal one-form \( (C_2)_\mu \) (and their magnetic duals). As for the \( N = 1 \)
chiral fields that descend from $N = 2$ vector multiplets, we keep from $L$ only the pieces that are invariant under $-\sigma^* \tilde{\lambda}$. Again, for an O9 and an SU(3) structure, we have that the projection onto states that are invariant under $\tilde{\lambda}$ gives that all degrees of freedom in the three-form $\Omega$ is kept.

In the hypermultiplet sector, since $E_7(7)$ is projected onto $O(6,6) \times SL(2,\mathbb{R})_{O(p+3)}$, we know from (5.18) that both $K_2$ and $K_3$ will be in the $(32',2)$ representation of $O(6,6) \times SL(2,\mathbb{R})_{O(p+3)}$, which is odd under the projection. Since $[K_2, K_3] \sim K_1$ and each $K_2$ and $K_3$ determines each other, $K_2 + i K_3$ defines a pure $O(6,6)$ spinor tensored with a doublet of $SL(2,\mathbb{R})$. Therefore, $K_2 + i K_3$ parametrizes a special Kähler space. On the other hand, $K_1$ is in the $(66,1) \oplus (1,3)$ of $O(6,6) \times SL(2,\mathbb{R})_{O(p+3)}$. It can be understood as a generalized almost complex structure on the orbit of $K_2 + i K_3$.

6 Discussion

In this work we derived the form of the couplings for general SU(7) and SU(6) structures in M-theory and type IIA, which correspond to (off-shell) $N = 1$ and $N = 2$ supersymmetric compactifications to four dimensions, building on and extending the work of [3,4]. Using EGG we could reformulate all degrees of freedom in such backgrounds by a set of fundamental objects in $E_7(7)$ representations. Moreover, the effective couplings are easily determined as singlets that are tensor products of the fundamental objects and their first derivatives in $E_7(7)$. In particular, $N = 1$ backgrounds are determined by an SU(7) structure $\phi$ in the 912 representation. Its quartic invariant gives the Kähler potential, while the superpotential is determined by an eigenvalue equation. In contrast, $N = 2$ backgrounds admit two sectors: vector- and hyper-multiplets. The former is described by one object $L$ in the (fundamental) 56 representation whose quartic invariant gives the Kähler potential. The hypermultiplets are described by an SU(2) subalgebra spanned by a triplet of structures $K_a$ in the adjoint representation. The normalization of the SU(2) commutator relations gives the hyper-Kähler potential of the hyper-Kähler cone over this quaternionic Kähler space. $L$ and $K_a$ together define an SU(6) structure. The couplings of the two sectors, i.e. the prepotentials, are given by a triple tensor product of these two objects with the derivative operator.

Furthermore, we discussed involutions in EGG that are supposed to project an $N = 2$ background to an $N = 1$ one. Examples of these involutions are orbifoldings in M-theory or orientifoldings in type II. We found the explicit map between the original SU(6) structure and its SU(7) descendant. In particular, while $L$ as well as $K_2 + i K_3$ are projected out, their tensor product produces $\phi$, which defines the SU(7) structure and survives the blow-up to a smooth geometry. The $N = 1$ Kähler potential and superpotential are then naturally determined by the $N = 2$ Kähler and hyper-Kähler potentials, and the prepotentials. We also determined the projection that creates negative tension objects with negative M5-brane charge in M-theory and observed that no SU(7) structure can be defined in that case, i.e. one cannot describe the resolution of singularities from involutions other than orbifoldings in EGG. In particular, the orientifold singularities related to D6-branes in type IIA cannot be resolved, but the corresponding M-theory orbifold fixed points can. In other words, the pure existence of an extra coordinate enables to resolve the singularities of D6-branes and O6-planes. It seems in order to describe D-branes in
EGG one needs to introduce extra coordinates. For instance, while NS5-branes cannot be described in generalized geometry, they could in principle be described in doubled geometry. It would be interesting to understand the resulting doubled geometries in the presence of NS5-branes and their negative tension counterparts further. Even more challenging would be the realization of a 56-dimensional space that covariantizes $E_7(7)$ and could describe all branes in type II string theory or M-theory.

We pointed moreover out that there exists an intermediate generalized tangent bundle $T_8$ in M-theory that transforms under an $SL(8)$ subgroup of $E_7(7)$. From the type IIA point of view, this $SL(8)$ group contains the geometric transformations $SL(6)$ and the group $SL(2)$ transforming the four-dimensional axiodilaton $\tau = B_6 + i e^{-\phi}$. In this language, $N = 1$ backgrounds are described by a four-form on $T_8$, $N = 2$ backgrounds by a real two-form and a complex four-form, i.e. they correspond to $Spin(7)$ and $SU(4)$ structures in eight dimensions. This suggests that there should exist a lift to an eight-dimensional space $M_8$ on which $T_8$ is the tangent bundle, similar to F-theory, whose volume is normalized everywhere. In the fashion described above, $M_8$ would not only geometrize D6-branes, but also some kind of exotic branes (as described in [13, 14]) that form a set of $(p, q)$-branes for the four-dimensional axiodilaton, similar to F-theory. It would be very interesting to understand such geometries further.

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Appendix

A $E_7(7)$ group theory

In the following we give relevant formulas for products of representations in the $SL(8)$ decomposition and their translation into the $SU(8)$ decomposition of spinors, following and extending [6].

A.1 $E_7(7)$ group theory in terms of $SL(8)$ representations

The $E_7(7)$ representations of interest are the fundamental 56, the adjoint 133 and the 912, whose decompositions under $SL(8)$ are given in (2.1), (2.2) and (2.3), respectively. In the following we denote objects in the fundamental representation by $\alpha, \beta, \text{etc.}$ and write them in terms of $SL(8)$ representations as

$$\alpha = (\alpha^{ab}, \alpha_{ab}) \ . \quad (A.1)$$
Similarly, the adjoint representation decomposes as
\[
\mu = (\mu^a_b, \mu_{abcd}) .
\] (A.2)
The 912 representation finally is given by
\[
\phi = (\phi^{ab}_{cd}, \phi_{ab}, \phi_{abc}^d) .
\] (A.3)

We will use the following notation for the product of representations:
\[
(, ) : [\text{rep} \otimes \text{rep}]_1 , \quad x : [\text{rep} \otimes \text{rep}]_{133} , \quad \cdot : [133 \otimes \text{rep}]_{\text{rep}} , \quad \otimes : [56 \otimes 133]_{912} , \quad \odot : [912 \otimes 133]_{56} , \quad \odot : [912 \otimes 56]_{133} ,
\] (A.4)
where \text{rep} is any representation of \(E_7(7)\).

The action of the adjoint on the fundamental representation, in other words the product \(133 \times 56 \to 56\), is given by
\[
(\mu \cdot \alpha)^{ab} = \mu^a_c \alpha_c^{\, ab} + \mu^b_c \alpha^{ac} + (\text{vol}_8^{-1} \mu)_{abcd} \alpha_{cd} ,
\] (A.5)
\[
(\mu \cdot \alpha)_{ab} = - \mu^c_d \alpha_{cb} - \mu^c_b \alpha_{ac} - \mu_{abcd} \alpha_{cd} .
\]
The symplectic invariant on the 56 reads
\[
\langle \alpha, \beta \rangle = \alpha^{ab} \beta_{ab} - \alpha_{ab} \beta^{ab} .
\] (A.6)
The trace in the adjoint is
\[
(\mu, \nu) = \mu^a_b \nu^b_a = \frac{1}{6} (\text{vol}_8^{-1} \mu)_{abcd} \nu_{abcd} .
\] (A.7)
The 56 \times 56 \to 133 reads
\[
(\alpha \otimes \beta)^{a}_{b} = \alpha^{ca} \beta_{cb} - \frac{1}{5} \delta^0_a \alpha^{cd} \beta_{cd} + \alpha_{cb} \beta^{ca} - \frac{1}{5} \delta^0_a \alpha_{cd} \beta^{cd} ,
\] (A.8)
\[
(\alpha \otimes \beta)_{abcd} = - 3 \alpha_{[ab]cd} + \frac{1}{4} \epsilon_{abcd} \epsilon_{efgh} \alpha^{ef} \beta^{gh} .
\]
The action of the adjoint onto itself, i.e. the 133 \times 133 \to 133 is given by
\[
(\mu \otimes \nu)^{a}_{b} = - (\mu^c_a \nu^d_c - \mu^d_a \nu^c) - \frac{1}{5} \epsilon_{acde} \nu_{bcde} - \mu_{bcde} \nu_{acde} ,
\] (A.9)
\[
(\mu \otimes \nu)_{abcd} = 4 (\mu^e_{[a} \nu_{bcd]} - \nu^e_{[a} \mu_{bcd]} ) .
\]
The product 56 \times 133 \to 912 is given by
\[
(\alpha \otimes \mu)^{ab} = \mu^a_c \alpha^{cb} + \mu^b_c \alpha^{ca} ,
\]
\[
(\alpha \otimes \mu)^{abc}_{d} = - 3 \alpha_{[ab]c} \delta^d_c + 2 (\text{vol}_8^{-1} \mu)^{abcd} \alpha_{ed} + 2 \alpha_{ef} \text{vol}_8^{-1} \mu^{[ab]} \delta^e_d ) ,
\]
\[
(\alpha \otimes \mu)_{ab} = - 3 \alpha_{[ab]c} \delta^d_c + 2 \alpha_{ef} \mu^{[ab]} \delta^e_d ) ,
\]
\[
(\alpha \otimes \mu)_{abc}^d = - 3 \alpha_{[ab]c} \delta^d_c + 2 (\text{vol}_8^{-1} \mu)^{abcd} \alpha_{ed} + 2 \alpha_{ef} \mu^{[ab]} \delta^e_d ) .
\] (A.10)
The adjoint action $133 \times 912 \rightarrow 912$ on the $912$ is given by

\[
(\mu \cdot \phi)^{ab} = \mu^a \phi^{cb} + \mu^b \phi^{ac} + \frac{2}{3}((\text{vol}_8^{-1} \cdot \mu)^{cde}(\phi^{abc})_{cde}),
\]

\[
(\mu \cdot \phi)^{abc}_d = 3 \mu^a \epsilon^{bc}_d - \mu^c \phi^{abc}_d + \epsilon^{abc}_d \phi_{ed} + \epsilon^{abc}_d \phi_{efd} - \epsilon^{abc}_d \phi_{edf} + \frac{2}{3}((\text{vol}_8^{-1} \cdot \mu)^{bef}(\phi^{abc})_{efd}),
\]

\[
(\mu \cdot \phi)_a = -\mu^a \phi_{cb} - \mu^c \phi_{ab} + \frac{2}{3}((\text{vol}_8^{-1} \cdot \mu)^{cde}(\phi^{bud})_{cde}),
\]

\[
(\mu \cdot \phi)_{abc}^d = -3 \epsilon^{a} \phi_{abc}^d + \epsilon^{d} \phi_{abc} + \epsilon^{d} \phi_{abc} + \epsilon^{d} \phi_{abc} + \epsilon^{d} \phi_{abc} - \epsilon^{d} \phi_{abc} - \epsilon^{d} \phi_{abc} - \epsilon^{d} \phi_{abc}.
\]

The product $912 \times 56 \rightarrow 133$ reads

\[
(\phi \odot \mu)^{ab} = -(\phi^{ac} \mu^b - \phi^{bc} \mu^a) - 2 \phi^{abc} \mu^d
\]

\[
+ \frac{2}{3}(\phi^{a} \epsilon^{bc}_d - \phi^{b} \epsilon^{ac}_d) + \frac{2}{3}(\text{vol}_8^{-1} \cdot \mu)^{cde}(\phi^{bud})_{cde},
\]

\[
(\phi \odot \mu)_{ab} = (\phi_{abc} \mu^e - \phi_{abc} \mu^e) - 2 \phi_{abc} \mu^e
\]

\[
- \frac{2}{3}(\phi^{cde} \epsilon_{abcde} - \phi^{cde} \epsilon_{abcde}),
\]

Similarly, the product $912 \times 56 \rightarrow 133$ reads

\[
(\phi \odot \alpha)^{ab} = \alpha^{ac} \phi_{cb} + \alpha_{cb} \phi^{ac} + \alpha_{cd} \phi^{cde} b - \alpha^{cd} \phi_{cde}^a,
\]

\[
(\phi \odot \alpha)_{abcd} = -(\phi_{abc} \epsilon_{d}^e - \frac{1}{4} \epsilon_{abcd} \phi^{efg} \alpha^{ghi})
\]

The product $912 \times 912 \rightarrow 133$ reads in the $SL(8)$ decomposition

\[
(\phi \times \psi)^{ab} = \phi^{ac} \psi_{cb} + \phi_{cb} \psi^{ca} + \frac{1}{3}(\phi_{cde} \psi^{cde} b + \phi^{cde} \phi_{cde}^a)
\]

\[
- (\phi^{acd} \epsilon_{bcd} + \phi_{bcd} \epsilon^{acd})
\]

\[
- \frac{1}{8} \delta^{ab} \phi^{cde} \psi_{cd} - \phi_{cd} \epsilon^{cde} f \psi^{e} \phi_{cde} f - \frac{2}{3} \phi^{cde} \phi_{cde} f \psi_{cde} f,
\]

\[
(\phi \times \psi)_{abcd} = 4(\phi_{a} \epsilon_{bcd} \psi_{e} + \phi_{b} \epsilon_{cd} \psi_{a} \epsilon_{e} + \frac{1}{4} \epsilon_{abcdefg} \phi^{efg} \psi_{a} \epsilon_{e} + \phi^{fg} \psi_{a} \epsilon_{e})
\]

\[
+ 2 (\phi_{ab} \epsilon_{cde} \psi_{efg} + \frac{1}{4} \epsilon_{abcdefg} \phi^{efg} \psi_{a} \epsilon_{e})
\]

A.2 The relation to $SU(8)$ representations

The $SU(8)$ representation is spanned by anti-symmetric products $\gamma_{ab}$ of the matrices $\gamma_a$ that obey the Clifford algebra

\[
\{\gamma_a, \gamma_b\}^{\alpha}_{\beta} = 2 g_{ab} \delta^{\alpha}_{\beta}.
\]

Furthermore, the gamma matrices $\gamma_a$ fulfill

\[
(\gamma^{a})^{\alpha}_{\beta}(\gamma_{a})^{\gamma}_{\delta} = \delta^{\alpha}_{\beta} \delta^{\gamma}_{\delta}.
\]

Under $SU(8)$, the $56$ decomposes according to

\[
\alpha = (\alpha^{\alpha\beta}, \tilde{\alpha}^{\alpha\beta}),
\]

\[
56 = 28 \oplus 28.
\]
while for the adjoint $133$ we have

$$
\mu = (\mu^\alpha_{\beta}, \mu^\alpha_{\beta\gamma\delta}, \bar{\mu}_{\alpha\beta\gamma\delta}) ,
$$

(A.18)

$$
133 = 63 \oplus 35 \oplus 35 .
$$

where $\mu^\alpha_{\beta} = 0$ and $\bar{\mu}_{\alpha\beta\gamma\delta} = *_8 \mu_{\alpha\beta\gamma\delta}$. Furthermore, we have for the $912$ the $SU(8)$ decomposition

$$
\phi = (\phi^{\alpha\beta}, \phi^{\alpha\beta\gamma\delta}, \bar{\alpha}_{\alpha\beta\gamma\delta}) ,
$$

(A.19)

$$
912 = 36 \oplus 420 \oplus 36 \oplus 420 ,
$$

Note that these are very similar to the $SL(8, \mathbb{R})$ decompositions (2.1), (2.2) and (2.3). To go from one to the other, we use for the $56$ \[ \alpha_{ab} = (\alpha_{\alpha\beta} + \bar{\alpha}_{\alpha\beta})\gamma_{ab}^{\alpha\beta} , \]

(A.20)

$$
\bar{\alpha}_{ab} = -i(\alpha_{\alpha\beta} - \bar{\alpha}_{\alpha\beta})\gamma_{ab}^{\alpha\beta} ,
$$

where we defined $\gamma_{ab}^{\alpha\beta} = C_{\gamma\alpha}(\gamma_{ab}^{\alpha\beta})_{\gamma\beta}$ and $C_{\alpha\beta}$ is the matrix that induces transposition on spinors. In the $133$, if only the $63$ adjoint representation of $SU(8)$ is nonzero, i.e. if $\mu_{\alpha\beta\gamma\delta} = 0$, one recovers the following $SL(8, \mathbb{R})$ components

$$
\mu_{ab} = \frac{1}{2}\mu_{ab}^{\alpha\beta}g_{ab}^{\alpha\beta} ,
$$

(A.21)

$$
\mu_{abcd} = \frac{1}{4}\mu_{abcd}^{\alpha\beta\gamma\delta}g_{abcd}^{\alpha\beta\gamma\delta} ,
$$

where $\mu_{ba} = -\mu_{ab}$ and $*_8 \mu_{abcd} = \mu_{abcd}$ (the symmetric and anti-self-dual pieces are obtained from the $70$ representation $\mu_{\alpha\beta\gamma\delta}$) and $\mu_{ab} = g_{ac}C^{cb}$. Similarly, if only the $36$ and the $\bar{36}$ components are non-zero in the $SU(8)$ decomposition of the $912$, we get the $SL(8, \mathbb{R})$ components $36$ and $420$ in the following way

$$
\phi^{ab} = -\frac{1}{2}(\phi^{\alpha\beta} + \bar{\phi}^{\alpha\beta})C_{\alpha\beta}^{ab} ,
$$

$$
\phi^{abc}_{\enspace d} = -\frac{3}{16}(\phi^{\alpha\beta} + \bar{\phi}^{\alpha\beta})(\gamma^{abc}_{\enspace d})_{\alpha\beta} ,
$$

$$
\phi_{ab} = \frac{1}{2}(\phi^{\alpha\beta} - \bar{\phi}^{\alpha\beta})C_{\alpha\beta}g_{ab} ,
$$

$$
\phi^{abc}_{\enspace d} = \frac{3}{16}(\phi^{\alpha\beta} - \bar{\phi}^{\alpha\beta})(\gamma^{abc}_{\enspace d})_{\alpha\beta} .
$$

(B.22)

**B Technical computations**

**B.1 The $N = 1$ superpotential**

In this appendix we give the computation of the superpotential given in (3.55). We start from (3.54) where the differential operator is given by (3.38). The form of $\phi$ is given in (3.46 – 3.48). In order to compute (3.54), we consider first

$$
D^C(A^D_{1B}\phi^A_{DC} + A^D_{1C}\phi^A_{BD} - A^A_{1D}\phi^D_{BC}) = A^D_{1B}D^C\phi^A_{DC} - A^A_{1D}D^C\phi^D_{BC}
$$

$$
+ (D^C A^D_{1B})\phi^A_{DC} - (D^C A^A_{1B})\phi^D_{BC}
$$

$$
+ (D^C A^D_{1C})\phi^A_{BD} + A^D_{1C}D^C\phi^A_{BD} ,
$$

(B.1)
where we used $Sp(56)$ indices\footnote{Note that $E_{7(7)} \subset Sp(56)$.} Now we can translate this back into $E_{7(7)}$ indices, rewriting the above equation as

$$D \circ (A_4 \cdot \phi) = A_4 \cdot (D \circ \phi) + (D \otimes A_4) \times \phi + (D \cdot A_4) \circ \phi + (A_4 \cdot D) \circ \phi ,$$

where we used the notation of Eq. (A.4) and in the last term the differential operator $D$ acts on $\phi$. If we use the form $A_4 = (0, \rho_8 \wedge A_3)$ and the form of the differential operator (3.38), we find that

$$D \cdot A_4 = 0 , \quad A_4 \cdot D = 0 .$$

Now we can use a variant of the Hadamard formula to find

$$D \phi = e^{A_4} D(e^{-A_4} \phi) - e^{A_4} \left( [D \otimes A_4] \times (e^{-A_4} \phi) \right) + \frac{1}{2} e^{A_4} \left( (A_4 \cdot [D \otimes A_4]) \times (e^{-A_4} \phi) \right) + \ldots ,$$

where we can compute the coefficients to be

$$[D \otimes A_4] = (0, 2(\epsilon \cdot (\rho_8 \wedge dA_3)) \otimes (\rho_8), 0, 0) ,$$

$$A_4 \cdot [D \otimes A_4] = (0, 0, -2 \ast_8 (A_3 \wedge \rho_8 \wedge dA_3)(\rho_8) \otimes (\rho_8), 0) ,$$

$$A_4 \cdot (A_4 \cdot [D \otimes A_4]) = 0 .$$

The last equation actually puts all further terms in (B.4) to zero. From this together with (3.54), the superpotential can be computed to be

$$e^{K_{\phi}/2} W = \frac{1}{2} \rho_8 \phi_4 \wedge d\phi_4 + \frac{1}{2} \rho_8 \wedge \phi_4^c \wedge d^\dagger \phi_4 - 2 i \phi_4 \wedge t_{\rho_8} dA_4 + (t_{\rho_8} A_4) \wedge dA_4 .$$

In order to make the dependence on $A_6$ explicit, we use Formula (B.1) but now for $\hat{A} = (\rho_8 \otimes \hat{A}, 0)$ and note that $D_B \hat{A}_A = 0$ and $D_C D_D = 0$. Therefore, we find

$$D \cdot (\hat{A} \cdot \phi) = \hat{A} \cdot (D \circ \phi) + [D \otimes \hat{A}] \times \phi .$$

Furthermore, we compute

$$D \otimes \hat{A} = (0, 0, (\rho_8 \wedge dA_6)\rho_8 \otimes \rho_8, 0) ,$$

giving

$$e^{K_{\phi}/2} W = \frac{1}{2} \rho_8 \phi_4^{(0)} \wedge d\phi_4^{(0)} + \frac{1}{2} \rho_8 \wedge \phi_4^{(0)} \wedge d^\dagger \phi_4^{(0)} + \rho_8 \wedge dA_6 - 2 i \phi_4^{(0)} \wedge t_{\rho_8} dA_4 + (t_{\rho_8} A_4) \wedge dA_4 .$$

From self-duality of $\phi_4^{(0)}$ we find that the first two terms actually agree. This means that we finally have

$$e^{K_{\phi}/2} W = t_{\rho_8} \phi_4^{(0)} \wedge d\phi_4^{(0)} + \rho_8 \wedge dA_6 - 2 i \phi_4^{(0)} \wedge t_{\rho_8} dA_4 + (t_{\rho_8} A_4) \wedge dA_4 .$$
B.2 The $N = 2$ prepotentials

In this appendix we compute the Killing prepotentials of the $N = 2$ theory given in (3.39). This computation is very similar to the one in Appendix B.1. We start with the second term in (3.13) where the differential operator is given by (3.38). The objects $K_a$ and $L$ defining the $SU(6)$ structure are given in (3.33) and (3.32), respectively. In order to compute (3.13), we consider first

$$D^B(A^A_{4D}K^D_B - A^D_{4B}K^A_D) = A^A_{4D}D^B K^D_B + (D^B A^A_{4D})K^D_B - A^D_{4B}D^B K^A_D$$

(B.11)

where we again used $Sp(56)$ indices. Translating this back into $E_7(7)$ indices, we find

$$D(A_1 \cdot K) = A_1 \cdot (DK) + [D \otimes A_4] \otimes K + [D \cdot A_4] \cdot K + (A_1 \cdot D) \cdot K,$$

(B.12)

where in the last term the differential operator $D$ acts on $K$. The last two terms vanish due to $A_4 = (0, \rho_8 \wedge A_3)$, cf. (3.3). From the Hadamard formula we find

$$DK = e^{A_1} D(e^{-A_1} K) - e^{A_1} ([D \otimes A_4] \otimes (e^{-A_1} K)) + \frac{1}{2} e^{A_1} (A_1 \cdot [D \otimes A_4]) \cdot (e^{-A_1} K),$$

(B.13)

where the coefficients are given in (B.3). We can treat the transformations $\hat{A} = (\rho_8 \otimes \hat{A}, 0)$ using the same equations and (B.8), so that

$$DK = e^{A_{\text{shifts}}} D(e^{-A_{\text{shifts}}} K) - e^{A_{\text{shifts}}} ([D \otimes A_4] \otimes (e^{-A_{\text{shifts}}} K)) + \frac{1}{2} e^{A_{\text{shifts}}} (A_1 \cdot [D \otimes A_4]) \cdot (e^{-A_{\text{shifts}}} K)$$

(B.14)

For the first term in (3.13) we have essentially to determine the scalar derivative $(L, D)$. From (3.32) and (3.38), we get

$$(L^{(0)}, D) = -e^{K_L} \text{vol}_8^{-1} \frac{1}{3} (\frac{1}{3} J^3 \wedge \rho_8 \wedge d) = e^{-K_L} L_{(0)}.$$
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