SHADOWS OF 4-MANIFOLDS WITH COMPLEXITY ZERO AND POLYHEDRAL COLLAPSING

HIRONOBU NAOE

Abstract. Our purpose is to classify acyclic 4-manifolds having shadow complexity zero. In this paper, we focus on simple polyhedra and discuss this problem combinatorially. We consider a shadowed polyhedron $X$ and a simple polyhedron $X_0$ that is obtained by collapsing from $X$. Then we prove that there exists a canonical way to equip internal regions of $X_0$ with gleams so that two 4-manifolds reconstructed from $X_0$ and $X$ are diffeomorphic. We also show that any acyclic simple polyhedron whose singular set is a union of circles can collapse onto a disk. As a consequence of these results, we prove that any acyclic 4-manifold having shadow complexity zero with boundary is diffeomorphic to a 4-ball.

Introduction

In 1990s Turaev introduced the notion of shadows of 3- and 4-manifolds with the intention of studying quantum invariants of knots and 3-manifolds. A simple polyhedron $X$ is called a shadow of a 4-manifold $M$ if $M$ collapses onto $X$ and $X$ is embedded properly and locally-flat in $M$. As it is well-known, $M$ can be reconstructed from $X$ and an appropriate decoration of its regions with some half-integers called gleams. It is called Turaev’s reconstruction. Shadows provide many geometric properties of 3- and 4-manifolds. We refer the reader to Costantino [3, 4] for studies of Stein structures, Spin$^c$ structures and complex structures of 4-manifolds. In [5] Costantino and Thurston established the relation between shadows and Stein factorizations of stable maps from 3-manifolds into $\mathbb{R}^2$. Consequently they observed the relation between hyperbolicity of 3-manifolds and their shadow complexities, which was strengthened by Ishikawa and Koda later [9]. Here the shadow complexity of $M$ is defined as the minimum number of true vertices of a shadow of $M$. This notion is introduced by Costantino in [2], in which he studied closed 4-manifolds with shadow complexities 0 and 1 in a special case. In [10] Martelli completely classified the closed 4-manifolds with shadow complexity 0 in the general case.

In this paper we study acyclic 4-manifolds with shadow complexity zero by observing the structure of simple polyhedra.

To state the first theorem, we introduce a canonical way to equip internal regions of a subpolyhedron of a shadowed polyhedron with gleams. Let
(X, gl) be a shadowed polyhedron, and X₀ a simple polyhedron with X₀ ⊂ X. Let R be an internal region of X₀. We observe that Sing(X₀) ⊂ Sing(X) and that R might be split by Sing(X) into some internal regions R₁, . . . Rₙ of X (n ≥ 1). Then we assign a gleam to R by

\[ \text{gl}(R) = \sum_{i=1}^{n} \text{gl}(Rᵢ). \]

Suppose that there exist a triangulation (K, K₀) of the pair (X, X₀) and a sequence of elementary simplicial collapses from K onto K₀. Then we say that X collapses X₀. Moreover, this removal is called a polyhedral collapse (or simply collapse) and denoted by X \subset X₀.

We denote by Mₓ the 4-manifold obtained from a shadowed polyhedron (X, gl) by Turaev’s reconstruction. Now we state our first theorem.

**Theorem 1.** Let (X, gl) be a shadowed polyhedron, and X₀ a simple polyhedron collapsed from X. Assign a gleam to each internal region of X₀ by formula (1). Then we have Mₓ ∼ Mₓ₀.

In the second theorem, we will study acyclic simple polyhedra and their collapsibility. Martelli introduced a way to convert a simple polyhedron whose singular set is a disjoint union of circles to a graph in [10]. We will use his notations and introduce some moves on a graph that correspond to collapsings.

**Theorem 2.** Any acyclic simple polyhedron whose singular set is a disjoint union of circles collapses onto D².

We have an important consequence of Theorem 1 and Theorem 2 as follows:

**Corollary 3.** Every acyclic 4-manifold with shadow complexity zero is diffeomorphic to D⁴.

This paper consists of 4 sections. In Section 1 we review the definitions of simple polyhedra and shadows. In Section 2 and in Section 3, we give the proofs of Theorem 1 and Theorem 2 respectively. In Section 4, we discuss some consequences of our theorems.

Throughout this paper, we work in smooth category unless otherwise mentioned.

**Acknowledgments.** The author would like to thank his supervisor, Masa-haru Ishikawa, for his useful comments and encouragement. He would also like to thank the referee for careful reading and helpful suggestions.

1. **Simple polyhedra and shadows**

A compact topological space X is called a *simple polyhedron* if any point x of X has a regular neighborhood Nbd(x; X) homeomorphic to one of the five local models shown in Figure 1. A *true vertex* is a point whose regular
neighborhood has a model of type (iii). We note that the model of type (iii) is homeomorphic to a cone over the complete graph $K_4$ with 4 vertices. The point $(p,0) \in (K_4 \times [0,1])/(K_4 \times \{0\})$ is just a true vertex. A connected component of the set of points whose regular neighborhoods are of type (ii) or (v) is called a **triple line**. The union of all true vertices and triple lines is called the *singular set* of $X$ and denoted by $\text{Sing}(X)$. The boundary $\partial X$ of $X$ is the set of points whose regular neighborhoods are of type (iv) or (v). Each component of $X \setminus \text{Sing}(X)$ is called a **region** of $X$. If a region $R$ contains points of type (iv) then $R$ is called a **boundary region**, and otherwise it is called an **internal region**.

**Definition 1.1.** Let $M$ be a compact oriented 4-manifold and let $T$ be a (possibly empty) trivalent graph in the boundary $\partial M$ of $M$. A simple polyhedron $X$ in $M$ is called a **shadow** of $(M,T)$ if the following hold:

- $M$ collapses onto $X$,
- $X$ is locally flat in $M$, that is, for each point $x$ of $X$ there exists a local chart $(U, \phi)$ of $M$ around $x$ such that $\phi(U \cap X) \subset \mathbb{R}^3 \subset \mathbb{R}^4$, and
- $X \cap \partial M = \partial X = T$.

The following theorem by Turaev is very important and is called **Turaev’s reconstruction**.

**Theorem 1.2** (Turaev [13]). Let $X$ be a shadow of a 4-manifold $M$. Then there exists a canonical way to equip each internal region of $X$ with a half-integer. Conversely, we can reconstruct $M$ uniquely from $X$ and the half-integers.

Each half-integer in the above is called a **gleam**. A simple polyhedron $X$ whose internal regions are equipped with a gleam is called a **shadowed polyhedron** and denoted by $(X, \text{gl})$ (or simply $X$).
Remark 1.3. As pointed out by Turaev [13], a gleam generalizes the Euler number of closed surfaces embedded in oriented 4-manifolds. We can interpret the gleam as follows. Let $R$ be an internal region of a shadow $X$ in a 4-manifold $M$ and let $p$ be a point of $\partial R$. By the locally flatness there exists a 3-ball $B^3$ around $p$ such that $B^3$ contains $\text{Nbd}(p; X)$. We take interval which passes through $p$ and is transverse to $R$ after giving an auxiliary Euclidean metric for $B^3$ as shown in Figure 2. By taking intervals for each point of $\partial R$ continuously, we get an interval bundle over $\partial R$. We note that the interval bundle is a subbundle of the normal bundle over $\partial R$ in $M$. Let $R'$ be a small perturbation of $R$ such that $\partial R'$ is lying in the interval bundle. If $R'$ is generically chosen, then $R$ and $R'$ have only isolated intersections. Counting them with signs, we have

$$\text{gl}(R) = \frac{1}{2} \sharp (\partial R \cap \partial R') + \sharp (R \cap R').$$

For this formula we refer the reader to Carrega and Martelli [1].

We close this section with the definition of the shadow complexity.

Definition 1.4. Let $M$ be a compact oriented 4-manifold having a shadow. We define the shadow complexity $\text{sc}(M)$ of $M$ to be the minimum number of true vertices of a shadow of $M$.

Remark 1.5. Costantino defined the shadow complexity for “closed” 4-manifolds in [2]. A shadow of a closed 4-manifold $M$ is defined as a shadow of a 4-manifold to which $M$ is obtained by attaching 3- and 4-handles.

2. Proof of Theorem [1]

In this section we introduce a proposition on PL topology and provide a lemma for the proof of Theorem [1].

Proposition 2.1. Let $M$ be an $n$-dimensional compact PL manifold and fix a triangulation $K$ of $M$. Let $L_i$ be a subcomplex of a double barycentric subdivision of $K$ for $i \in \{0, 1\}$. If $L_0 \subset L_1$, then $\text{Nbd}(|L_0|; X)$ and $\text{Nbd}(|L_1|; X)$ are PL-homeomorphic.
For the proof of this proposition we refer the reader to [11, Lemma 3.25, Theorem 3.26].

Remark 2.2. A PL manifold has a unique smoothing in dimension $n \leq 6$ [7]. In our case $n = 4$, Proposition 2.1 with “PL-homeomorphic” replaced by “diffeomorphic” also holds.

Lemma 2.3. Let $(X, \text{gl})$ be a shadowed polyhedron, and $X_0$ a simple sub-polyhedron of $X$. Assign a gleam to each internal region of $X_0$ by formula (1). Then we have $M_{X_0} \cong \text{Nbd}(X_0; M_X)$.

Proof. Let $K$ be the second barycentric subdivision of a given triangulation of $X_0$, and set

$$K' = K \setminus \{\tau \in K \mid \tau \cap \partial X_0 \neq \emptyset\}.$$ 

Then $K'$ is a subcomplex of $K$, and $K \setminus \cup K'$. We have $\text{Nbd}(X_0; M_X) \cong \text{Nbd}(X'_0; M_X)$ by Proposition 2.1, where $X'_0 = |K'|$. Note that $X_0$ is proper and locally flat in $\text{Nbd}(X'_0; M_X)$. Hence $X_0$ is a shadow of $\text{Nbd}(X'_0; M_X)$.

By Turaev’s reconstruction, there should exist gleams for the internal regions of $X_0$ so that the 4-manifold reconstructed from them is diffeomorphic to $\text{Nbd}(X'_0; M_X)$. It suffices to show that such gleams coincide with ones given by formula (1).

Let $R$ be an internal region of $X_0$, and set $S = R \cap \text{Sing}(X)$. If $S = \emptyset$, the region $R$ is also an internal region for $X$. Hence it is obvious that their gleams coincide by Remark 1.3.

We turn to the case $S \neq \emptyset$. As mentioned above, the region $R$ is split into internal regions $R_1, \ldots, R_n$ of $X$. Let $p$ be a point contained in $S$. Then $\text{Nbd}(p; X)$ can be described in either of the two right parts of Figure 3, where the colored areas indicate $\text{Nbd}(p; R)$. Note that $\text{Nbd}(p; R) = \text{Nbd}(p; X_0)$. We assume that these pictures are drawn in $\mathbb{R}^3$ and consider the regular neighborhood of $\text{Nbd}(p; X)$. Carrying out Turaev’s reconstruction with such 3-dimenional blocks, we get $M_X$ in which $R$ is smoothly embedded.

Next we consider the interval bundle over $\partial R_i$ as mentioned in Remark 1.3 for $i \in \{1, \ldots, n\}$. By the smoothness of $R$, if $\partial R_i \cap \partial R_j \neq \emptyset$, the restrictions of the interval bundles of $\partial R_i$ and $\partial R_j$ to $\partial R_i \cap \partial R_j$ coincide. Hence the union of the interval bundles is regarded as an interval bundle over $S \cup \partial R$, and we denote it by $L$. Let $S'$ be a generic small perturbation
of \( S \) in \( L \) such that the images of the true vertices of \( X \) do not lie in the zero section. Then let \( R' \) be a generic small perturbation of \( R \) such that \( S' \subset R' \) and \( \partial R' \) lies in the restriction of the interval bundle \( L \) to \( \partial R \). By restricting \( R' \) we get a small perturbation \( R'_i \) of \( R_i \) as in Remark 1.3 for \( i \in \{1, \ldots, n\} \). Note that each point \( p \in S \) except for a true vertex is sandwiched between \( R_i \) and \( R_j \) for some \( i, j \in \{1, \ldots, n\} \), in other words, the point \( p \) belongs to both \( \partial R_i \) and \( \partial R_j \). By formula (2), we have the following:

\[
\text{gl}(R) = \frac{1}{2} \# (\partial R \cap \partial R') + \# (R \cap R')
\]

\[
= \frac{1}{2} \sum_{i=1}^{n} \# ((\partial R_i \cap \partial R) \cap (\partial R'_i \cap \partial R')) + \# (S \cap S') + \sum_{i=1}^{n} \# (R_i \cap R'_i)
\]

\[
= \frac{1}{2} \sum_{i=1}^{n} \# (\partial R_i \cap \partial R'_i) + \sum_{i=1}^{n} \# (R_i \cap R'_i)
\]

\[
= \sum_{i=1}^{n} \text{gl}(R_i),
\]

and the proof is completed. \( \square \)

Proof of Theorem 1. There exist diffeomorphisms

\[
M_X \cong \text{Nbd}(X; M_X) \cong \text{Nbd}(X_0; M_X) \cong M_{X_0}
\]

by Turaev’s reconstruction, Proposition 2.1 and Lemma 2.3 \( \square \)

3. Proof of Theorem 2

In this section we study simple polyhedra and its graph notation introduced by Martelli, and give the proof of Theorem 2.

3.1. Basic lemmas for simple polyhedra. We first introduce convenient lemmas. We note that the first one was shown by Ikeda in [8, Lemma 12].

**Lemma 3.1** (Ikeda [8]). Any region of a simple polyhedron \( X \) is orientable and has no genus if \( H_1(X; \mathbb{Z}) = 0 \).

The proof of Lemma 3.1 is given by using Mayer Vietoris exact sequence. For any region \( R \) of \( X \), he considered a closed surface \( \hat{R} \) obtained from \( R \) by capping off the all boundary components of \( R \) by disks and constructed a new simple polyhedron that contains \( \hat{R} \). He checked that \( H_1(\hat{R}; \mathbb{Z}) \) must vanish.

**Lemma 3.2.** Let \( X \) be an acyclic simple polyhedron and \( \gamma \) be a simple closed curve in \( X \setminus \text{Sing}(X) \). Then \( \gamma \) splits \( X \) into two parts such that one of them is acyclic and the other is a homology-\( S^1 \). Moreover the first homology of the latter is generated by \( \gamma \).
Proof. Since any region of $X$ is orientable by Lemma 3.1, $\text{Nbd}(\gamma; X)$ is homeomorphic to an annulus. Set $\Gamma = \text{Nbd}(\gamma; X)$ and $X' = X \setminus \text{IntNbd}(\gamma; X)$. Using the Mayer Vietoris exact sequence for the decomposition $X = \Gamma \cup X'$, we have the isomorphism $H_q(\Gamma; \mathbb{Z}) \oplus H_q(X'; \mathbb{Z}) \cong H_q(\Gamma \cap X'; \mathbb{Z})$ for $q \geq 1$. Hence $H_q(X'; \mathbb{Z}) = 0$ for $q \geq 2$ and $H_1(X'; \mathbb{Z}) \cong \mathbb{Z}$. Moreover $\chi(X') = 1$ holds from the following equality
\[ \chi(X) = \chi(\Gamma) + \chi(X') - \chi(\Gamma \cap X'). \]
Hence $\text{rank} H_0(X'; \mathbb{Z}) = 2$, that is, $X'$ has two connected components: one of them is acyclic and the other is a homology-$S^1$. Let $X_0$ be the acyclic connected component of $X'$ and $X_1$ the other component. We regard $X$ as the union $X_0 \cup X_1$. From the Mayer Vietoris exact sequence for this decomposition, it follows that $\gamma$ generates $H_1(X_1; \mathbb{Z})$. $\square$

3.2. Martelli’s graph encoding a simple polyhedron. Let $X$ be a simple polyhedron whose singular set is a disjoint union of circles. In [10], Martelli introduced a graph encoded from $X$ and classified closed 4-manifolds with shadow complexity zero.

A regular neighborhood of $S^1 \subset \text{Sing}(X)$ has a structure of $Y$-bundle over $S^1$, where $Y$ is a cone of three points. There are three topological types $Y_{111}$, $Y_{12}$ and $Y_3$, and they are shown in Figure 4. Each connected component of $X \setminus \text{Nbd}(\text{Sing}(X); X)$ is a surface homeomorphic to a region of $X$. Any surface is decomposed into disks, pairs of pants and Möbius strips. Hence we have the following.

**Proposition 3.3** (Martelli [10]). *Any simple polyhedron whose singular set is a disjoint union of circles is decomposed along simple closed curves into pieces homeomorphic to $D^2$, a pair of pants, the Möbius strip, $Y_{111}$, $Y_{12}$ or $Y_3$.*

A decomposition of $X$ as in Proposition 3.3 provides a graph $G$ consisting of some edges and vertices (B), (D), (P), (2), (111), (12) or (3) as in Figure 5. The vertices of type (D), (P), (2), (111), (12) and (3) denote some portions homeomorphic to $D^2$, a pair of pants, the Möbius strip, $Y_{111}$, $Y_{12}$ and $Y_3$ respectively. A vertex of type (B) denotes a boundary component of $X$. Note that each edge encodes a simple closed curve along which $X$
decomposes except the edges adjoining a vertex of type (B). We also note that we distinguish the two edges adjoining the vertex of type (12): the edge marked with two lines corresponds to a simple closed curve winding twice along the circle in $\text{Sing}(X)$.

As Martelli said, we can uniquely reconstruct the simple polyhedron $X$ from a pair consisting of a graph $G$ and a map $\beta : H_1(G; \mathbb{Z}_2) \to \mathbb{Z}_2$. It is necessary to choose homeomorphisms that glues polyhedral pieces at each edge of $G$ since there are two self-homeomorphisms of $S^1$, orientation-preserving and -reversing, up to isotopy. It is encoded by a map from $H_1(G; \mathbb{Z}_2)$ to $\mathbb{Z}_2$.

The graph $G$ that describes $X$ is not unique since a surface decomposes into disks, pairs of pants and Möbius strips in several ways. There are some local moves as two examples shown in Figure 6 that do not change the topological type of the polyhedron. We call the two moves in Figure 6 $\text{IH-move}$ and $\text{YV-move}$.

**Definition 3.4.** If there exists an edge connecting two vertices $u$ and $v$ of a graph, then $u$ and $v$ are said to be **adjacent**.

### 3.3. Acyclic case

Let $X$ be an acyclic simple polyhedron whose singular set consists of circles. We note that we only need to consider the case $\partial X \neq \emptyset$ since there is no acyclic closed simple polyhedron without true vertices [8, Theorem 1].

Let $G$ be a graph obtained from $X$. Our goal is to transform $G$ into a 1-valent graph whose vertices are type (B) and type (D) as shown in Figure 7. It is obvious that this graph corresponds to the polyhedron $D^2$. 

---

Figure 5. A simple polyhedron without true vertices is encoded by a graph having these vertices.

Figure 6. The move in the left part of the figure, called $\text{IH-move}$, corresponds to A-move for pants-decompositions in [6]. The move in the right part of the figure, called $\text{YV-move}$, means that an annulus plays a role of connecting two polyhedral pieces.
Assertion 1. There is no embedded $Y_3$ in any acyclic simple polyhedron.

Proof. Assume that there exists $Y_3$ in an acyclic simple polyhedron $X$. By Lemma 3.2, a simple closed curve $\partial Y_3$ splits $X$ into $Y_3$ and an acyclic sub-polyhedron but does not generate $H_1(Y_3; \mathbb{Z})$. It is a contradiction. □

Assertion 2. The graph $G$ is a tree.

Proof. This follows readily from Lemma 3.2. □

If $X$ is decomposed into some pieces as in Proposition 3.3, there must be at least one piece homeomorphic to $D^2$ by applying iteratively Lemma 3.2. Choose one of such pieces and let the corresponding vertex of type (D) be the root of $G$.

We assume that $G$ has at least one vertex of type (111). We transform $G$ into a tree having no vertex of type (111).

Consider the farthest vertex of type (111) from the root. Let us denote it by $v_0$. If we remove the corresponding piece $Y_{111}$ from $X$, it is decomposed into three subpolyhedra. Let $X_1$ be one of them such that it contains $D^2$ corresponding to the root and $X_2$ and $X_3$ be the remaining two subpolyhedra. Let $G_1$, $G_2$, and $G_3$ be the subgraphs of $G$ corresponding to $X_1$, $X_2$, and $X_3$, respectively as shown in Figure 8. By Lemma 3.2, at least one of $X_2$ and $X_3$ is homologically $S^1$. Assume that $X_2$ is so. Let $\gamma$ be the simple closed curve that cuts $X_2$ off from $X$. By Lemma 3.2, $\gamma$ generates $H_1(X_2; \mathbb{Z})$. If $X_2$ has no boundary except $\gamma$, the simple polyhedron obtained from $X_2$ by capping off the boundary component by a disk is closed, acyclic and without true vertices, contrary to [8, Theorem 1]. Hence $X_2$ has some boundary components other than $\gamma$. In other words, there exists a vertex of type (B) in $G_2$.

Assertion 3. Let $v_1$ be a vertex of type (P) such that it is adjacent to a vertex of type (B). If $v_1$ is adjacent to a vertex of type (12), the edge between them is marked with two lines.
Proof. Assume that there is an edge, denoted by \( e \), adjoining \( v_1 \) and a vertex of type (12) such that the edge is not marked with two lines. Let \( v_2 \) be the vertex of type (12). Along the simple closed curve corresponding to \( e \), \( X \) is decomposed into two subpolyhedra: one contains a region \( R \) corresponding to \( v_1 \) and another contains \( Y_{12} \) corresponding to \( v_2 \). Since \( R \) has two boundary components, the former subpolyhedron has a 1-cycle. By Lemma 3.2, the latter subpolyhedron should be acyclic. However the subpolyhedron collapses so that it contains a Möbius strip in a region. This contradicts Lemma 3.1.

\[ \square \]

**Assertion 4.** The moves of \( G \) described in Figure 9 (a), (b) and (c) are realized by collapsings of \( X \).

Proof. (a) (resp. (b)) The corresponding part of \( X \) is shown in Figure 10 (a1) (resp. (b1)). It can collapse along the boundary component in the direction of the arrows described in the figure, and the resulting polyhedron is shown in Figure 10 (a2) (resp. (b2)).

(c) Figure 10 (c1) shows the corresponding part of \( X \). After we glue the two pieces, a pair of pants and \( Y_{12} \) as in Figure 10 (c1), it turns out that \( X \) can be described as in Figure 10 (c2). Let \( X \) collapse along a part of the boundary component as indicated by the arrows. Then the resulting polyhedron is shown in Figure 10 (c3).

\[ \square \]

**Assertion 5.** The graph \( G \) can change into a subgraph that does not contain \( v_0 \) and \( G_2 \) only by the moves (a),(b),(c) in Figure 9, the IH-move and the YV-move.

Proof. Let \( v \) be a vertex of type (B) in \( G_2 \). Then \( v \) is adjacent to a unique vertex \( v' \) of type (111), (12) or (P).

If \( v' \) is of type (111), that is \( v' = v_0 \), we apply the move (a) and the proof is completed.

We consider the case where \( v' \) is type (12) or (P). If \( v' \) is of type (12), the edge between \( v \) and \( v' \) must be marked with two lines as shown in Figure 11 (1) by the same reason of Assertion 3. If \( v' \) is of type (P), the two vertices adjacent to \( v' \) other than \( v \) can not be of type (B) by the acyclicity of \( X \). Therefore the possible cases are as shown in Figure 11.

Set \( H_0 = G_2 \). In each case of (1)–(7) in Figure 11 we apply some moves to \( H_k \) as follows and denote the resulting graph by \( H_{k+1} \) (\( k = 0, 1, \ldots \)).

(1) In this case we apply the move (b). Then the number of vertices in \( H_{k+1} \) is less than the one in \( H_k \).

(2)–(4) In these cases we apply the move (c). Then the number of vertices in \( H_{k+1} \) is less than the one in \( H_k \).

(5) In this case we apply YV-move. Then the number of vertices in \( H_{k+1} \) is less than the one in \( H_k \).

(6),(7) Let \( v'_k \) be the vertex adjacent to \( v \) in \( H_k \). We define a set \( V_k \) of vertices of type (P) as follows: \( u \in V_k \) if and only if there is a path
between \( v'_k \) and \( u \) in \( H_k \) such that it contains vertices only of type \( (P) \). Then there exists at least one vertex in \( V_k \) which is adjacent to a vertex different from \( v \) and of type other than \( (P) \) or \( (111) \) since \( G \) is a tree. Choose such a vertex \( u \) in \( V_k \) and a path between \( v'_k \) and \( u \) as above. We apply IH-moves along the path, and then the resulting graph \( H_{k+1} \) is as in one of the cases (1)–(5).
In all cases (1)–(7) we can decrease the number of vertices in $H_k$ but this is finite. Hence it comes down to the case where $v$ is adjacent to one of type (111), and the proof is completed.

We iterate Assertion 5 until all the vertices of type (111) in $G$ disappear and denote the resulting graph by $G'$. There still exists a vertex of type (B) in $G'$ by [8, Theorem 1]. We denote it by $v$. The vertex adjacent to $v$ is of type (D), (12) or (P). If it is of type (D), $G'$ is as in Figure 7, which corresponds to $D^2$. If the vertex adjacent to $v$ is of type (12) or (P), the possible cases are (1)–(3),(5),(7) in Figure 11. As in the proof of Assertion 5 we apply some moves to $G'$ and finally obtain a graph such that $v$ is adjacent to one of type (D). This completes the proof of Theorem 2.

4. APPLICATIONS

In this section, we discuss applications of our results.

Proof of Corollary 3 Let $M$ be an acyclic 4-manifold with shadow complexity zero, and let $X$ be a shadow of $M$ without true vertices. Then each connected component of $\text{Sing}(X)$ is $S^1$ or a closed interval. If $\text{Sing}(X)$ consists of only circles, then $X$ collapses onto $D^2$ by Theorem 2. By Theorem 11 a disk $D^2$ is a shadow of $M_X$, and then $M_X$ is diffeomorphic to $D^4$.

Assume that $\text{Sing}(X)$ has a closed interval component. We decompose $X$ into subpolyhedra $X_1, \ldots, X_n$ along all closed interval components of $\text{Sing}(X)$. From Turaev’s reconstruction [13], the boundary connected sum $M_{X_1} \# \ldots \# M_{X_n}$ and $M_X$ are diffeomorphic. For $1 \leq i \leq n$, the 4-manifold $M_{X_i}$ is diffeomorphic to $D^4$ as mentioned above since $\text{Sing}(X_i)$ consists of only circles. It follows that $M_X \cong D^4$.

We have another application to the study of 3-manifolds. Let $N$ be a closed connected 3-manifold. A shadow of $N$ is defined as a shadow of a
4-manifold whose boundary is $N$. Costantino and Thurston indicated in [5] that the Stein factorization of a stable map on $N$ to $\mathbb{R}^2$ can be seen as a shadow of $N$ with a certain modification if necessary. The notion of complexity of stable maps was introduced by Ishikawa and Koda in [9]. Especially, the complexity of a stable map is zero if and only if the map has no singular fiber of type $\text{II}^2$ and type $\text{II}^3$. See [12, 9] for the precise definitions. These observations and our results immediately yield the following:

**Corollary 4.1.** Let $N$ be a closed connected 3-manifold. Then $N$ admits a stable map with complexity zero and acyclic Stein factorization if and only if $N$ is homeomorphic to $S^3$.

**References**

[1] A. Carrega and B. Martelli, *Shadows, ribbon surfaces, and quantum invariants*, arXiv preprint arXiv:1404.5983, to appear in Quantum Topology.
[2] F. Costantino, *Complexity of 4-manifolds*, Experiment. Math. 15 (2006), 237-249.
[3] F. Costantino, *Stein domains and branched shadows of 4-manifolds*, Geom. Dedicata 121 (2006), 89-111.
[4] F. Costantino, *Branched shadows and complex structures on 4-manifolds*, J. Knot Theory Ramifications 17 (2008), 14291454.
[5] F. Costantino and D. Thurston, *3-manifolds efficiently bound 4-manifolds*, J. Topol. 1 (2008), 703745.
[6] A. Hatcher, *Pants decompositions of surfaces*, arXiv:9906084.
[7] M. Hirsch and B. Mazur, *Smoothings of piecewise linear manifolds*, Ann. Math. Studies 80, Princeton University Press, Princeton NJ 1974.
[8] H. Ikeeda, *Acyclic fake surfaces*, Topology 10 (1971), 936.
[9] M. Ishikawa and Y. Koda, *Stable maps and branched shadows of 3-manifolds*, arXiv preprint arXiv:1403.0996 to appear in Math. Ann.
[10] B. Martelli, *Four-manifolds with shadow-complexity zero*, Int. Math. Res. Not. IMRN 2011, 12681351.
[11] C. Rourke and B. Sanderson, *Introduction to piecewise-linear topology*, Ergebnisse der Mathematik, Band 69, Springer-Verlag, New York-Heidelberg, 1972.
[12] O. Saeki, *Topology of singular fibers of differentiable maps*, Lecture Notes in Mathematics 1854, Springer-Verlag, Berlin, 2004.
[13] V. G. Turaev, *Quantum invariants of knots and 3-manifolds*, de Gruyter Studies in Math., 18, Walter de Gruyter & Co., Berlin, 1994.

Tohoku University, Sendai, 980-8578, Japan
E-mail address: sb3m22@math.tohoku.ac.jp