The rotating Navier–Stokes–Fourier–Poisson system on thin domains

Bernard Ducomet\textsuperscript{1}, Matteo Caggio\textsuperscript{2}, Šárka Nečasová\textsuperscript{2}, and Milan Pokorný\textsuperscript{3}

\textsuperscript{1} CEA, DAM, DIF, F-91297 Arpajon, France
e-mail: bernard.ducomet@cea.cz

\textsuperscript{2} Institute of Mathematics of the Academy of Sciences of the Czech Republic
Žitná 25, 115 67 Praha 1, Czech Republic
e-mails: caggio@math.cas.cz, matus@math.cas.cz

\textsuperscript{3} Charles University in Prague, Faculty of Mathematics and Physics
Mathematical Inst. of Charles University, Sokolovská 83, 186 75 Prague 8, Czech Republic
e-mail: pokorny@karlin.mff.cuni.cz

Abstract

We consider the compressible Navier–Stokes–Fourier–Poisson system describing the motion of a viscous heat conducting rotating fluid confined to a straight layer \( \Omega_\epsilon = \omega \times (0, \epsilon) \), where \( \omega \) is a 2-D domain. The aim of this paper is to show that the weak solutions in the 3D domain converge to the strong solution of the 2-D Navier–Stokes–Fourier–Poisson system on \( \omega \) as \( \epsilon \to 0 \) on the time interval, where the strong solution exists. We consider two different regimes in dependence on the asymptotic behaviour of the Froude number.

Keywords: Navier–Stokes–Fourier–Poisson system, weak solution, entropy, rotation, accretion disk, thin domains, dimension reduction, strong solution.

2010 MSC Classification: 76N10, 76U05

1 Introduction

Our motivation for this work is a rigorous derivation of the equations describing astrophysical objects called “accretion disk” which are thin structures observed in various places in the universe, as e.g. Saturn’s rings, protoplanetary disks, or disks found in close binary stars in which one star captures matter lost by its companion through a stellar wind\textsuperscript{18,20,22}. In fact accretion disks are among the most important objects in astronomy as they accompany the stellar formation and they are the main sites for planetary formation. Namely physicists realized already in the sixties that in a binary system (composed of two massive
objects) mass transfer from a neutron star to its companion takes the form of an accretion disk.

In this context, the hydrodynamical disk structure \[2\], \[24\] comes from a subtle competition between rotation, gravitational attraction and viscosity, and self-gravitation seems also to play an important role in the disk evolution \[21\].

Even though, strictly speaking, these disks are indeed three-dimensional, their size in the “third” dimension is usually very small and therefore they are often modelled as two-dimensional. Our aim is to study mathematically rigorously the limit when the thickness tends to zero, hence the object is in the limit described as two-dimensional.

We start from the compressible Navier–Stokes–Fourier–Poisson system describing the motion of a viscous heat conducting rotating fluid confined to a straight layer \(\Omega_\varepsilon = \omega \times (0, \varepsilon)\), where \(\omega\) is a 2-D domain.

The motion of the fluid is described by standard fluid mechanics equations giving the evolution of the mass density \(\sigma = \sigma(t, z)\), the velocity field \(\vec{W} = \vec{W}(t, z)\), and the temperature \(\varsigma = \varsigma(t, z)\) as functions of the time \(t\) and the spatial coordinate \(z \in \Omega_\varepsilon \subset \mathbb{R}^3\). We also assume that the flow is influenced by the gravitational force due to the fluid itself. More precisely, the system of equations to be studied in \((0, T) \times \Omega_\varepsilon\) reads as follows:

\[
\begin{align*}
\partial_t \sigma + \text{div}_z(\sigma \vec{W}) &= 0, \quad (1.1) \\
\partial_t (\sigma \vec{W}) + \text{div}_z(\sigma \vec{W} \otimes \vec{W}) + \sigma(\vec{\chi} \times \vec{W}) + \nabla_z p &= \text{div}_z S + \sigma \nabla_z \Phi + \sigma \nabla_z |\vec{\chi} \times \vec{z}|^2, \quad (1.2) \\
&= \sigma \nabla_z \Phi \cdot \vec{W} + \sigma \nabla_z |\vec{\chi} \times \vec{z}|^2 \cdot \vec{W}, \quad (1.3)
\end{align*}
\]

where the body forces are represented by the gravitational force \(\sigma \nabla_z \Phi\), and the centrifugal force \(\sigma \nabla_z |\vec{\chi} \times \vec{z}|^2\). We namely suppose that the system is globally rotating at uniform velocity \(\vec{\chi}\) around the vertical direction \(\vec{e}_3\) and we denote \(\vec{\chi} = \chi \vec{e}_3\). Therefore (see e.g. \[2\]) the Coriolis acceleration \(\sigma \vec{\chi} \times \vec{u}\) and the centrifugal force term \(\sigma \nabla_z |\vec{\chi} \times \vec{z}|^2\), must be included into the momentum equation.

The potential \(\Phi\) obeys Poisson’s equation,

\[
- \Delta \Phi = 4\pi G (\alpha \sigma + (1 - \alpha)g) \quad \text{in} \quad (0, T) \times \Omega_\varepsilon, \quad (1.4)
\]

where \(G\) is the Newton constant and \(\alpha\) is a positive parameter (see below). The first contribution in the right-hand side corresponds to self-gravitation while in the second one \(g\) is a given function, modelling the external gravitational effect of a central massive object (or, possibly, also of all other objects which are important to consider) attracting the system. Physically this may correspond to the gravitational attraction by a black hole (in the classical limit) or by a central star in the case of circumstellar disks \[24\].

Here and hereafter, we assume that the function \(\sigma\) is extended by zero outside of \(\Omega_\varepsilon\). Supposing further that \(g\) is such that the integral below converges, we have

\[
\Phi(t, z) = G \int_{\mathbb{R}^3} K(z - y)(\alpha \sigma(t, y) + (1 - \alpha)g(y)) \, dy,
\]

where \(K\) is a suitable kernel.
where \( K(z) = \frac{1}{|z|} \), and the parameter \( \alpha \) may take the values 0 or 1: for \( \alpha = 1 \) the self-gravitation is present and for \( \alpha = 0 \) the gravitation only acts as an external field (astrophysicists often consider self-gravitation of accretion disks as small compared to the external attraction described by \( g \), see e.g. \[22\]). We will explain the choice of the gravitational potential later. Since we also work with \( \nabla_z \Phi \), we have further to assume that

\[ \int_{\mathbb{R}^3} |\nabla K(z - y)| (\alpha \sigma(t, y) + (1 - \alpha)g(y))| \, dy < \infty. \]

We consider the no slip boundary condition holds on the boundary \( \partial \omega \times (0, \epsilon) \) (on the lateral part of the domain)

\[ \vec{W} |_{\partial \omega \times (0, \epsilon)} = 0, \quad (1.5) \]

and the slip boundary condition on the other parts of the boundary \( \omega \times \{0, \epsilon\} \) (the top and bottom part of the layer)

\[ \vec{W} \cdot \vec{n} |_{\omega \times \{0, \epsilon\}} = 0, \quad [\Sigma \vec{n}] \times \vec{n} |_{\omega \times \{0, \epsilon\}} = \vec{0}. \quad (1.6) \]

Note that we have on \( \omega \times \{0, \epsilon\} \) \( \vec{n} = \pm \vec{e}_3 \), hence the first condition in \(1.6 \) can be rewritten as

\[ W_3 = 0 \text{ on } \omega \times \{0, \epsilon\}. \quad (1.7) \]

Let us emphasize that we imposed a slip condition on the boundary \( \omega \times \{0, \epsilon\} \) in order to avoid difficulties in passing to the “infinitely thin” disk limit.

We suppose finally that the no heat flux condition holds on \( \partial \Omega \)

\[ \vec{q} \cdot \vec{n} |_{\partial \Omega} = 0. \quad (1.8) \]

Equations are completed with the initial conditions

\[ \sigma(0, z) = \tilde{\sigma}_{0, \epsilon}(z), \quad \vec{W}(0, z) = \vec{W}_{0, \epsilon}, \quad \varsigma(0, z) = \tilde{\varsigma}_{0, \epsilon}(z) \text{ for } z \in \Omega_{\epsilon}. \quad (1.9) \]

The thermodynamic pressure \( p \) and the specific internal energy \( e \) are given functions of the density \( \sigma \) and the temperature \( \varsigma \). They are interrelated through Maxwell’s relation

\[ \frac{\partial e(\sigma, \varsigma)}{\partial \sigma} = \frac{1}{\sigma^2} \left( p(\sigma, \varsigma) - \varsigma \frac{\partial p(\sigma, \varsigma)}{\partial \varsigma} \right). \quad (1.10) \]

Furthermore, \( S \) is the viscous part of the stress tensor determined by

\[ S = S(\varsigma, \nabla_z \vec{W}) = \mu \left( \nabla_z \vec{W} + (\nabla_z \vec{W})^T - \frac{2}{3} \text{div}_z \vec{W} \right) + \eta \text{div}_z \vec{W} \, \mathbb{I}, \]

where the shear viscosity coefficient \( \mu = \mu(\varsigma) > 0 \) and the bulk viscosity coefficient \( \eta = \eta(\varsigma) \geq 0 \) are effective functions of the temperature, and the upper index \( T \) denotes the transposed matrix.

Similarly, the heat flux \( \vec{q} \) is given by Fourier’s law

\[ \vec{q} = \vec{q}(\varsigma, \nabla_z \varsigma) = -\kappa(\varsigma) \nabla_z \varsigma, \quad (1.12) \]
with the heat conductivity coefficient $\kappa(\zeta) > 0$.

Using standard tools and methods from the mathematical compressible fluid dynamics (see [9]) it is possible to establish the existence of a weak solution to our system (1.1–1.12) under physically reasonable assumptions on the form of the pressure $p(\sigma, \zeta)$ and the functions $\mu(\zeta)$, $\eta(\zeta)$ and $\kappa(\zeta)$. Our aim is to verify that under reasonable assumptions on the data of the problem, for $\epsilon \to 0^+$, the solution tends to the strong solution of the corresponding two-dimensional system (presented below). The essential tool in this paper will be the relative entropy inequality as developed by E. Feireisl, A. Novotný and co-workers in [8], [10] and [11] (for utilisation of relative entropy inequalities in other contexts we refer to works of C. Dafermos [3], P. Germain [13], A. Mellet and A. Vasseur [17] and L. Saint-Raymond [23]).

The aim of this paper is to extend recent results of E. Feireisl, A. Novotný and co-workers (see [1], [15]) to the rotating Navier–Stokes–Fourier system in presence of the gravitational forces.

The paper is organized as follows. In Section 2, we collect our main assumptions on the form of the pressure $p(\sigma, \zeta)$, the viscosity coefficients and the heat conductivity and introduce the concept of weak solution to our original problem. We also introduce the two-dimensional target system and present the main result of the paper which claims that the weak solution to the original system converge for $\epsilon \to 0^+$ to the strong solution of the target system (on the life span of this solution). Section 3 contains the derivation of the relative entropy inequality and Section 4 the proof of the convergence result.

## 2 Hypotheses and the target system

### 2.1 Thermodynamic concept

As mentioned above, we use the temperature and the density as the main thermodynamic quantities and assume that the thermodynamic potentials are given functions of them. Hypotheses imposed on constitutive relations and transport coefficients are motivated by the general existence theory for the Navier–Stokes–Fourier system developed in [9, Chapter 3]. As we cannot handle the monoatomic gas model when the self-gravitation is included, we use the generalization of the model as considered e.g. in [19]; see also [14].

We consider the pressure and the internal energy in the form

$$p(\sigma, \zeta) = p_1(\sigma, \zeta) + \frac{a}{3} \zeta^4,$$

$$e(\sigma, \zeta) = e_1(\sigma, \zeta) + a \frac{\zeta^4}{\sigma},$$

where

$$p_1(\sigma, \zeta) = (\gamma - 1) \sigma e(\sigma, \zeta)$$

with $\gamma > 1$. Note that $\gamma = \frac{5}{3}$ corresponds exactly to the model of the monoatomic gas, as considered in [9]. Recalling the Maxwell relation (1.10), it follows under some regularity assumptions on the functions $p_1$ and $e_1$ that

$$p_1(\sigma, \zeta) = \zeta^{\gamma - 1} P \left( \frac{\sigma}{\zeta^{\gamma - 1}} \right),$$

where $P$ is a polynomial of degree $\gamma - 1$. This form of the pressure is consistent with the classical form of the monoatomic gas model. 

The aim of this paper is to extend recent results of E. Feireisl, A. Novotný and co-workers (see [1], [15]) to the rotating Navier–Stokes–Fourier system in presence of the gravitational forces.
where \( P : [0, \infty) \to [0, \infty) \) is a given function with the following properties:

\[
P \in C^1([0, \infty)) \cap C^2((0, \infty)), \ P(0) = 0, \ P'(Z) > 0 \text{ for all } Z \geq 0,
\]

\[
0 < \frac{\gamma P(Z) - P'(Z)Z}{Z} \leq c < \infty \text{ for all } Z > 0,
\]

\[
\lim_{Z \to \infty} \frac{P(Z)}{Z^\gamma} = p_\infty > 0.
\]

The component \( \frac{2}{3} \varsigma^4 \) represents the effect of “equilibrium” radiation pressure (see [5] for the motivations).

Using the Maxwell relation (1.10), the corresponding non-radiative part of the internal energy \( e \) is

\[
e_1(\sigma, \varsigma) = \frac{1}{\gamma - 1} \frac{\varsigma^\gamma - 1}{\sigma} P(\frac{\sigma}{\varsigma^\gamma - 1}).
\]

(2.8)

Note also that the Maxwell relation is equivalent with the Gibbs relation

\[
\frac{1}{\theta} \left(De(\sigma, \varsigma) + p(\sigma, \varsigma) D\left(\frac{1}{\sigma}\right)\right) = Ds(\sigma, \varsigma)
\]

(2.9)

which defines a new quantity, the specific entropy. Due to the form of the pressure and the internal energy the specific entropy is given by

\[
s(\sigma, \varsigma) = s_1(\sigma, \varsigma) + \frac{4\theta}{3} \varsigma^3,
\]

(2.10)

with

\[
s_1(\sigma, \varsigma) = M\left(\frac{\sigma}{\varsigma^\gamma - 1}\right), \quad M'(Z) = -\frac{1}{\gamma - 1} \frac{\gamma P(Z) - P'(Z)Z}{Z^2} < 0, \quad \lim_{Z \to +\infty} M(Z) = 0.
\]

(2.11)

Note that it is possible to show that

\[
s_1(\sigma, \varsigma) \leq C(1 + |\ln \sigma|)
\]

(2.12)

in the set \( \sigma \in (0, \infty), \ \varsigma \in (0, 1) \), and

\[
s_1(\sigma, \varsigma) \leq C(1 + |\ln \sigma| + \ln \varsigma)
\]

(2.13)

in the set \( \sigma \in (0, \infty) \) and \( \varsigma \in (1, \infty) \).

The transport coefficients \( \mu, \eta, \) and \( \kappa \) are continuously differentiable functions of the absolute temperature such that

\[
0 < c_1(1 + \varsigma) \leq \mu(\varsigma), \quad \mu'(\varsigma) < c_2, \quad 0 \leq \eta(\varsigma) \leq c_3(1 + \varsigma),
\]

\[
0 < c_4(1 + \varsigma^3) \leq \kappa(\varsigma) \leq c_5(1 + \varsigma^3)
\]

(2.14)

(2.15)

for any \( \varsigma > 0 \). For the sake of simplicity, we consider the particular case

\[
\mu(\varsigma) = \mu_0 + \mu_1 \varsigma, \quad \mu_0, \mu_1 > 0, \quad \eta \equiv 0,
\]

(2.16)
and

\[ \kappa(\varsigma) = \kappa_0 + \kappa_2 \varsigma^2 + \kappa_3 \varsigma^3, \quad \kappa_i > 0, i = 0, 2, 3. \] (2.17)

As a matter of fact, the total energy balance (1.3) is not suitable for the weak formulation since, at least according to the recent state-of-art, the term \( \mathbf{SW} \) is not controlled on the (hypothetical) vacuum zones of vanishing density. Following [9], we replace (1.3) by the internal energy balance (it is possible at least formally, for smooth solutions, by subtracting the balance of the kinetic energy, i.e. the momentum equation tested by \( \mathbf{W} \))

\[ \partial_t(\sigma e) + \text{div}_z(\sigma e \mathbf{W}) + \text{div}_z \mathbf{q} = \mathbf{S}(\varsigma, \nabla_z \mathbf{W}) : \nabla_z \mathbf{W} - p \text{div}_z \mathbf{W}. \] (2.18)

Furthermore, dividing (2.18) by \( \varsigma \) and using Gibbs’ relation (2.9), we may rewrite (2.18) as the entropy equation

\[ \partial_t(\varsigma s) + \text{div}_z(\varsigma s \mathbf{W}) + \text{div}_z \left( \frac{\mathbf{q}}{\varsigma} \right) = \frac{1}{\varsigma} \left( \mathbf{S}(\varsigma, \nabla_z \mathbf{W}) : \nabla_z \mathbf{W} - \frac{\mathbf{q} \cdot \nabla \varsigma}{\varsigma} \right). \] (2.19)

### 2.2 Formal scaling analysis

We introduce the change of variables

\[ (z_h, z_3) \in \Omega_e \mapsto (x_h, x_3) \in \Omega_1 = \Omega, \text{ where } x_h = (x_1, x_2), z_h = (z_1, z_2). \] (2.20)

Note that for \( z \in \Omega_e \) we have \( x \in \Omega_1 =: \Omega \). For \( z \) and \( x \) interrelated by (2.20) we introduce new unknowns defined as follows: the density \( \varrho(t, x) = \sigma(t, z) \), the velocity \( \mathbf{u}(t, x) = \mathbf{W}(t, z) \) and the thermodynamic temperature \( \theta(t, x) = \varsigma(t, z) \). Similarly we set \( \phi(t, x) = \Phi(t, z) \).

In order to identify the appropriate limit regime, we perform a general scaling, denoting by \( L_{ref}, \ell_{ref}, T_{ref}, U_{ref}, \varrho_{ref}, \rho_{ref}, \mu_{ref}, \nu_{ref} \), the reference hydrodynamical quantities (horizontal and vertical lengths, time, velocity, density, pressure, viscosity) and by \( \chi_{ref} \) the reference rotation velocity.

We denote by \( S_r := \frac{L_{ref}}{T_{ref} U_{ref}}, \quad M_a := \frac{U_{ref}}{\rho_{ref} \ell_{ref}}, \quad R_e := \frac{U_{ref} \rho_{ref} L_{ref}}{\mu_{ref}}, \quad F_r := \frac{U_{ref}}{\sqrt{\rho_{ref} L_{ref}}}, \quad R_o := \frac{U_{ref}}{\chi_{ref} L_{ref}}, \quad P_e := \frac{U_{ref} \rho_{ref} L_{ref}}{\theta_{ref} \ell_{ref}} \), the Strouhal, Mach, Reynolds, Froude, Rossby and Péclet numbers. We set

\[ \epsilon := \frac{\ell_{ref}}{L_{ref}}. \]

We also denote

\[ \nabla_\epsilon = (\nabla_h, \frac{1}{\epsilon} \partial_{z_3}), \quad \nabla_h = (\partial_{x_1}, \partial_{x_2}), \]

\[ \text{div}_z \mathbf{u} = \text{div}_h \mathbf{u}_h + \frac{1}{\epsilon} \partial_{x_3} u_3, \quad \mathbf{u}_h = (u_1, u_2), \quad \text{div}_h \mathbf{u}_h = \partial_{x_1} u_1 + \partial_{x_2} u_2, \]

\[ \Delta_\epsilon = \partial_{x_1}^2 + \partial_{x_2}^2 + \frac{1}{\epsilon^2} \partial_{x_3}^2. \]

Note also that

\[ \nabla_\epsilon \phi(t, x) = \epsilon G \int_{\Omega} \alpha(t, x) \frac{(x_1 - \xi_1, x_2 - \xi_2, \epsilon(x_3 - \xi_3))}{(|x_h - \xi_h|^2 + \epsilon^2 |x_3 - \xi_3|^2)^\frac{3}{2}} d\xi. \]
\[ + G \int_{\mathbb{R}^3} (1 - \alpha) g(y) \frac{(x_1 - y_1, x_2 - y_2, \epsilon x_3 - y_3)}{(|x_1 - y_1|^2 + (\epsilon x_3 - y_3)^2)^{3/2}} \, dy =: \epsilon \alpha \vec{E}_1 + (1 - \alpha) \vec{E}_2 =: \vec{E}, \quad (2.21) \]

and
\[ \nabla_\epsilon |\vec{\chi} \times \vec{x}|^2 = (\nabla_\epsilon |\vec{\chi} \times \vec{x}|^2, 0) = \frac{\chi}{\sqrt{x_1^2 + x_2^2}}(x_1, x_2, 0). \quad (2.22) \]

Performing the scaling the continuity equation reads now
\[ Sr \partial_t \varrho + \text{div}_\epsilon (\varrho \vec{u}) = 0, \quad (2.23) \]

the momentum equation
\[ Sr \partial_t (g \vec{u}) + \text{div}_\epsilon (g \vec{u} \otimes \vec{u}) + \frac{1}{Ma^2} \nabla_\epsilon p(\varrho, \vartheta) + \frac{1}{Ro} g(\vec{\chi} \times \vec{u}) = \frac{1}{Re} \text{div}_\epsilon S(\nabla_\epsilon \vec{u}) + \frac{1}{Fr^2} g \vec{E} + \frac{1}{Ro} g \nabla_\epsilon |\vec{\chi} \times \vec{x}|^2, \quad (2.24) \]

and the entropy balance
\[ Sr \partial_t (g s) + \text{div}_\epsilon (g s \vec{u}) + \frac{1}{Pe} \text{div}_\epsilon \left( \frac{g(\vartheta, \nabla_\epsilon \vartheta)}{\vartheta} \right) = \Sigma, \quad (2.25) \]

with
\[ \Sigma = \frac{1}{\vartheta} \left( \frac{Ma^2}{Re} \nabla_\epsilon (\vartheta, \nabla_\epsilon \vec{u}) : \nabla_\epsilon \vec{u} - \frac{1}{Pe} g(\vartheta, \nabla_\epsilon \vartheta) \cdot \nabla_\epsilon \vartheta \right). \]

We take \( Fr = \epsilon^\beta \) and set all other numbers equal to 1. We consider in fact only two (the most interesting limit) cases: \( \beta = \frac{1}{2} \) and \( \beta = 0 \). If \( \beta = \frac{1}{2} \), we take \( \alpha = 1 \), i.e. we assume only the self-gravitation and neglect the gravity due to the other objects, and if \( \beta = 0 \), we take \( \alpha = 0 \), i.e. we neglect the self-gravitation effects of the fluid and consider only the gravitational force due to the other objects. Indeed, if \( \beta = 0 \), we could also include into the primitive system the self-gravitation of the fluid, however, in the limit \( \epsilon \to 0^+ \) the corresponding part of the gravitational potential would disappear. We comment on this case below Theorem 2.1.

We obtain the new (rescaled) system of equations
\[ \partial_t \varrho + \text{div}_\epsilon (g \vec{u}) = 0, \quad (2.26) \]
\[ \partial_t (g \vec{u}) + \text{div}_\epsilon (g \vec{u} \otimes \vec{u}) + \nabla_\epsilon p(\varrho, \vartheta) + g(\vec{\chi} \times \vec{u}) = \text{div}_\epsilon S(\vartheta, \nabla_\epsilon \vec{u}) + \epsilon^{-2\beta} g \vec{E} + g \nabla_\epsilon |\vec{\chi} \times \vec{x}|^2, \quad (2.27) \]
\[ \partial_t (g s) + \text{div}_\epsilon (g s \vec{u}) + \text{div}_\epsilon \left( \frac{g(\vartheta, \nabla_\epsilon \vartheta)}{\vartheta} \right) = \frac{1}{Pe} \left( S(\vartheta, \nabla_\epsilon \vec{u}) : \nabla_\epsilon \vec{u} - \frac{1}{Pe} g(\vartheta, \nabla_\epsilon \vartheta) \cdot \nabla_\epsilon \vartheta \right), \quad (2.28) \]

with initial conditions
\[ \varrho(0, x) = \varrho_{0,\epsilon}(x), \quad \vec{u}(0, x) = \vec{u}_{0,\epsilon}, \quad \vartheta(0, x) = \vartheta_{0,\epsilon}(x), \quad x \in \Omega, \quad (2.29) \]

where
\[ \varrho_{0,\epsilon}(x) = \overline{\varrho}_{0,\epsilon}(z), \quad \vec{u}_{0,\epsilon}(x) = \overline{\vec{W}}_{0,\epsilon}(z), \quad \vartheta_{0,\epsilon}(x) = \overline{\vartheta}_{0,\epsilon}(z), \quad (2.29) \]
and where $\vec{E}$ is given by (2.21).

The rescaled problem (2.26–2.29) is completed with the boundary conditions

\begin{align}
\vec{u}|_{\partial \omega \times (0,1)} &= \vec{0}, \\
\vec{u} \cdot \vec{n}|_{\omega \times \{0,1\}} &= \vec{0}, \tag{2.30}
\end{align}

and

\begin{align}
\nabla \cdot \vec{n}|_{\omega \times (0,1)} &= 0. \tag{2.31}
\end{align}

Recall that due to the shape of $\Omega$ we have

\begin{align}
\varrho|_{\omega \times \{0,1\}} = 0. \tag{2.32}
\end{align}

\section{2.3 Weak formulation}

To present the weak formulation of our problem, we consider the functional space

\begin{align*}
W_{0,n}^{1,2}(\Omega; \mathbb{R}^3) = \{ \vec{u} \in W^{1,2}(\Omega; \mathbb{R}^3); \vec{u} \cdot \vec{n}|_{\omega \times \{0,1\}} = 0, \vec{u}|_{\partial \omega \times (0,1)} = \vec{0} \}.
\end{align*}

In the weak formulation of the Navier–Stokes–Fourier system the equation of continuity (2.26) is replaced by its (weak) renormalized version (cf. [4]) represented by the family of integral identities

\begin{align}
\int_0^T \int_\Omega \left( (\varrho + b(\varrho)) \partial_t \varphi + (\varrho + b(\varrho)) \vec{u} \cdot \nabla \varphi + (b(\varrho) - b'(\varrho)) \varrho \text{div} \vec{u} \varphi \right) \, dx \, dt \tag{2.34}
\end{align}

\begin{align}
= - \int_\Omega \left( \varrho \varrho + b(\varrho) \right) \varphi(0, \cdot) \, dx
\end{align}

satisfied for any $\varphi \in C_\infty^\infty([0, T] \times \Omega)$, and any $b \in C^\infty([0, \infty)), b' \in C^\infty([0, \infty))$, where (2.34) includes as well the initial condition $\varrho(0, \cdot) = \varrho_0$.

Similarly, the momentum equation (2.27) is replaced by

\begin{align}
\int_0^T \int_\Omega \left( \varrho \varrho \vec{u} \cdot \partial_t \vec{u} + (\varrho \varrho \odot \vec{u}) : \nabla \varphi - \varrho \vec{u} \times \varphi + p(\varrho, \vartheta) \text{div} \vec{u} \varphi \right) \, dx \, dt
\end{align}

\begin{align}
- \int_0^T \int_\Omega \left( S(\vartheta, \nabla \varrho) : \nabla \varphi - \epsilon^{-2\beta} \varrho \vec{E} \cdot \varphi - \varrho \vartheta |\vec{v}|^2 \cdot \varphi \right) \, dx \, dt \tag{2.35}
\end{align}

\begin{align}
= - \int_\Omega \varrho \varrho \vec{u}_0 \vec{u}(0, \cdot) \cdot \varphi(0, \cdot) \, dx
\end{align}

for any $\vec{\varphi} \in C_c^\infty([0, T] \times \Omega; \mathbb{R}^3)$ such that $\vec{\varphi}|_{[0, T] \times \partial \omega \times (0,1)} = \vec{0}$ and $\varrho(0, \cdot) = \varrho_0 |_{[0, T] \times \omega \times \{0,1\}} = 0$, where (2.35) includes the initial condition $\varrho(0, \cdot) = \varrho_0, \vec{u}_0, \vec{\varphi}$. The entropy equation must be replaced by the entropy inequality. Its weak formulation is the following

\begin{align}
\int_0^T \int_\Omega \left( \varrho s(\varrho, \vartheta) \partial_t \varphi + \varrho s(\varrho, \vartheta) \vec{u} \cdot \nabla \varphi + \frac{\varrho(\vartheta, \nabla \varrho)}{\varrho} \cdot \nabla \varphi \right) \, dx \, dt \tag{2.36}
\end{align}
\[
\leq - \int_{\Omega} \phi_{0,e}(\phi_{0,e}, \partial_{0,e}) \varphi(0, \cdot) \, dx - \int_{0}^{T} \int_{\Omega} \frac{1}{\theta} \left( \mathbf{S}(\partial, \nabla \varphi) : \nabla \varphi - \frac{1}{2} \left( \mathbf{D}(\partial, \nabla \varphi) \cdot \nabla \varphi \right) \right) \varphi \, dx \, dt,
\]
for any \( \varphi \in C_{c}^{\infty}((0, T) \times \Omega) \), \( \varphi \geq 0 \). Since we replace the entropy equation by the inequality, the system must be supplemented with the total energy balance
\[
\int_{\Omega} \left( \frac{1}{2} \theta |\vec{u}|^2 + \varphi \varphi(\theta, \varphi) \right) (\tau, \cdot) \, dx
\]  
\[
= \int_{\Omega} \left( \frac{1}{2} \varphi_{0,e} |\phi_{0,e} \vec{u}|^2 + \varphi_{0,e} \varphi(\phi_{0,e}, \varphi_{0,e}) \right) \, dx + \int_{0}^{T} \int_{\Omega} \left[ \varepsilon^{-2\beta} \theta \vec{E} \cdot \vec{u} + \theta \varphi_{e}(\varphi_{e} \vec{v}) \right] \, dx \, dt.
\]
Finally, the gravitational force is given by (2.21).

**Definition 2.1** We say that \((\varphi, \vec{u}, \varphi)\) is a weak solution of problem (2.26–2.29) if
\[ \varphi \geq 0, \quad \varphi > 0 \quad \text{for a.a.} \quad (t, x) \in (0, T) \times \Omega, \]
\[ \varphi \in C_{\text{weak}}([0, T]; L^{\infty}(\Omega)), \quad \varphi \varphi \in C_{\text{weak}}([0, T]; L^{\frac{2n}{n+1}}(\Omega; \mathbb{R}^{3})), \]
\[ \vec{u} \in L^{2}(0, T; W_{0,n}^{1,2}(\Omega; \mathbb{R}^{3})), \]
\[ \varphi \in L^{\infty}(0, T; L^{4}(\Omega)) \cap L^{2}(0, T; W^{1,2}(\Omega), \]
and if \( \varphi, \vec{u}, \varphi \) satisfy the integral identities (2.34), (2.35), (2.36), together with the total energy balance (2.37), and integral representation of the gravitational force (2.21).

We denote for fixed \( \epsilon > 0 \) by the lower index \( e \) the solution to our problem on \( \Omega \) (i.e., after rescaling). Recall that if \( \alpha = 0 \), we neglect the self-gravitation.

**Proposition 2.1** Suppose the thermodynamic functions \( p, \epsilon, s \) satisfy hypotheses (2.1), (2.11), the transport coefficients \( \mu, \lambda, \kappa \) comply with (2.10)–(2.14) and the stress tensor is given by (2.11). Let \( \gamma > \frac{3}{2} \) if \( \alpha = 0 \) or \( \gamma > \frac{12}{11} \) if \( \alpha = 1 \). Let \( g \) be such that \( g \in L^{p}(\mathbb{R}^{3}) \) for \( p = 1 \) if \( \gamma > 6 \) and \( p = \frac{12}{7 - 2\gamma} \) for \( \frac{3}{2} < \gamma \leq 6 \).

Suppose the initial data satisfy
\[
\int_{\Omega} \left( \frac{1}{2} \varphi_{0,e} |\phi_{0,e} \vec{u}|^2 + \varphi_{0,e} \varphi(\phi_{0,e}, \varphi_{0,e}) \right) (0, \cdot) \, dx (2.38)
\]
\[
\equiv \int_{\Omega} \left( \frac{1}{2} \varphi_{0,e} |\phi_{0,e} \vec{u}|^2 + \varphi_{0,e} \varphi(\phi_{0,e}, \varphi_{0,e}) \right) \, dx \leq E_{0},
\]
\[
\int_{\Omega} \varphi_{0,e} \varphi(\varphi_{0,e}, \varphi_{0,e}) (0, \cdot) \, dx \equiv \int_{\Omega} \varphi_{0,e} \varphi(\varphi_{0,e}, \varphi_{0,e}) \, dx \geq S_{0}.
\]

Then problem (2.26)–(2.29) with boundary conditions (2.30)–(2.33) admits at least one weak solution in the sense of Definition 2.1.

**Proof.** The existence of weak solutions to the above problem can be deduced from the works of Feireisl et al. [10], [11], [13] and [14]. In fact, we fix \( \epsilon > 0 \), construct a weak solution in \( \Omega_{e} \), and then rescale the solution. Note that due to the form of the total energy inequality (2.38) we need stronger assumptions on \( \gamma \) and \( g \) than in [6]. However, this form will be important in Section 4. Note that in real situations we may assume that \( g \) is compactly supported, which removes the fact that the assumptions on the integrability of \( g \) are in a certain sense more restrictive for large \( \gamma \).
2.4 Target system

The aim of our paper is to investigate the limit process $\epsilon \to 0^+$ in the system of equations (2.26–2.28) under the assumptions that initial data $(\rho_{0,\epsilon}, \vec{u}_{0,\epsilon}, \vartheta_{0,\epsilon})(x)$ converge in a certain sense to $(\rho_0, \vec{U}_0, \Theta_0)(x)$, where $\vec{U}_0 = (\vec{V}_0, 0)$ and all quantities are independent of $x_3$.

We therefore expect that the sequence $(\rho_{\epsilon}, \vec{u}_{\epsilon}, \vartheta_{\epsilon})$ of weak solutions to (2.26–2.28) converge to $(\rho, \vec{U}, \Theta)$, $\vec{U} = [\vec{V}, 0]$ has zero third component and all quantities are independent of $x_3$.

Then the triple $(r(t, x_h), \vec{V}(t, x_h), \Theta(t, x_h))$ solves the 2D compressible heat conducting rotating fluid in the domain $(0, T) \times \omega$. However, the target system depends on the gravitational potential, i.e., on the choice of $\beta$ (and $\alpha$).

\[
\partial_t r + \text{div}_h(r\vec{V}) = 0, \quad (2.39)
\]

\[
r\partial_t \vec{V} + r\vec{V} \cdot \nabla_h \vec{V} + \nabla_h p(r, \Theta) + r(\vec{\chi} \times \vec{V}) = \text{div}_h S_h(\Theta, \nabla_h \vec{V}) + r\nabla_h \phi_h + r\nabla_h |\vec{\chi} \times \vec{x}|^2, \quad (2.40)
\]

\[
r\partial_t s + r\vec{V} \cdot \nabla_h s + \text{div}_h \left( \frac{g_h(\Theta, \nabla_h \Theta)}{\Theta} \right) = \frac{1}{\Theta} \left( S_h(\Theta, \nabla_h \vec{V}) : \nabla_h \vec{V} - \frac{g_h(\Theta, \nabla_h \Theta) \cdot \nabla_h \Theta}{\Theta} \right), \quad (2.41)
\]

Above,

\[
\phi_h(t, x_h) = G \int_\omega \frac{r(t, y_h)}{|x_h - y_h|} \, dy_h \quad (2.42)
\]

if $\alpha = 1$ and $\beta = \frac{1}{2}$, and

\[
\phi_h(t, x_h) = G \int_{\mathbb{R}^3} \frac{g(y)}{\sqrt{|x_h - y|^2 + y_3^2}} \, dy \quad (2.43)
\]

if $\alpha = 0$ (and $\beta = 0$). Moreover, $\vec{g}_h(\Theta, \nabla_h \Theta) = -\kappa(\Theta)\nabla_h \Theta$. Further, we have $\vec{V}|_{\partial \omega \times (0, T)} = \bar{\vec{V}}$, $\vec{g}_h \cdot \vec{n}|_{\partial \omega \times (0, T)} = 0$, and

\[
S_h(\Theta, \nabla_h \vec{V}) = \mu \left( \nabla_h \vec{V} + (\nabla_h \vec{V})^T - \text{div}_h \vec{V} \right) + \left( \eta + \frac{\mu}{3} \right) \text{div}_h \vec{V} I_h, \quad (2.44)
\]

where $I_h$ is the unit tensor in $\mathbb{R}^{2\times 2}$.

Note that since we consider only smooth solutions to (2.39–2.44), the entropy balance is in fact expressed as equality and it is equivalent with either the internal or the total energy balance (in the sense of (1.3)).

Our aim now is to prove that solutions of (2.26–2.28) converge in a certain sense to the unique strong solution of (2.39–2.44) as explained below.

From classical results of Matsumura and Nishida [16] we know that the target system admits a unique global strong solution provided the initial data are close to a stationary solution.

Another possible result is the existence of local in time smooth solution, i.e. a smooth solution on possibly short time interval $(0, T_*)$, see e.g. [25] for such a type of result. More precisely
Proposition 2.2 Let $E$ be a given positive constant. Suppose that the functions $p \in C^2((0, \infty)^2)$, $\mu, \eta, \kappa \in C^1(0, \infty)$ and that
\[ r_0 \in W^{2,2}(\omega), \inf_{\omega} r_0 > 0, \bar{V}_0 \in W^{3,2}(\omega; \mathbb{R}^2) \cap W_0^{1,2}(\omega; \mathbb{R}^2), \Theta_0 \in W^{3,2}(\omega), \inf_{\omega} \Theta_0 > 0. \] (2.45)
Assume that the compatibility condition
\[ \frac{1}{r_0} \left( \nabla_h p(r_0, \Theta_0) + r_0 (\chi \times \bar{V}_0) - \nabla_h \nabla_h \nabla_h \Theta_0 - r_0 \nabla_h \phi_h - r_0 \nabla_h (|\chi \times \vec{x}|^2) \right)_{\partial \omega} = \vec{0}, \] (2.46)
holds. Then:
1. (Local solution) There exists a positive constant $T^*$ such that $(r, \bar{V}, \Theta)$ is the unique classical solution to problem (2.39–2.44) with the boundary conditions
\[ \bar{V} |_{\partial \omega} = \vec{0}, \] (2.47)
\[ \frac{\partial \Theta}{\partial n} |_{\partial \omega} = 0. \] (2.48)
and the initial conditions $(r_0, \bar{V}_0, \Theta_0)$ in $(0, T) \times \Omega$ for any $T < T^*$ such that
\[ r \in C([0, T]; W^{3,2}(\omega)) \cap C^1([0, T]; W^{2,2}(\omega)), \] (2.49)
\[ \bar{V} \in C([0, T]; W^{3,2}(\omega; \mathbb{R}^2)) \cap C^1([0, T]; W^{1,2}(\omega; \mathbb{R}^2)), \] (2.50)
\[ \Theta \in C([0, T]; W^{3,2}(\omega)) \cap C^1([0, T]; W^{1,2}(\omega)). \] (2.51)
2. (Global solution) Let $r_0, \bar{V}_0, \Theta_0, \chi$ be such that for a sufficiently small $\varepsilon > 0$
\[ \|r_0 - \vec{r}, \bar{V}_0, \Theta_0 - \vec{\Theta}\|_{3,2} + |\chi| \leq \varepsilon, \] (2.52)
where $(\vec{r}, \vec{V}_0, \vec{\Theta})$ is a stationary solution to (2.39–2.44) with the boundary condition
\[ \frac{\partial \vec{\Theta}}{\partial n} |_{\partial \omega} = 0. \] (2.53)
Then for any $T^* < +\infty$ there exists a global unique strong solution to problem (2.39–2.44) with the boundary conditions (2.47–2.48) and the initial conditions $(r_0, \bar{V}_0, \Theta_0)$ in the class (2.49–2.51).

Proof. It follows from [16, Theorem 1.1] and [23] with slight modifications due to the rotation and the self-gravitation. Moreover, in the former case, we also use that the potential part of the external force does not need to be small.

\[ \square \]

11
2.5 Main result

We introduce the relative entropy functional

\[ I(\varrho_\epsilon, \vec{u}_\epsilon, \vartheta_\epsilon | r, \vec{U}, \Theta) = \int_{\Omega} \left( \frac{1}{2} \varrho_\epsilon |\vec{u}_\epsilon - \vec{U}|^2 + \mathcal{E}(\varrho_\epsilon, \partial_\epsilon | r, \Theta) \right) (r, \cdot) \, dx, \]  

where for

\[ H_{\tilde{\vartheta}}(\varrho, \vartheta) = \varrho c(\varrho, \vartheta) - \tilde{\vartheta} s(\varrho, \vartheta) \]

we define

\[ \mathcal{E}(\varrho, \vartheta | \tilde{\varrho}, \tilde{\vartheta}) := H_{\tilde{\vartheta}}(\varrho, \vartheta) - \partial_\varrho H_{\tilde{\vartheta}}(\tilde{\varrho}, \tilde{\vartheta})(\varrho - \tilde{\varrho}) - H_{\tilde{\vartheta}}(\tilde{\varrho}, \tilde{\vartheta}). \]

Our main result reads

**Theorem 2.1** Suppose the thermodynamic functions \( p, e, s \) satisfy hypotheses (2.1 - 2.11), the transport coefficients \( \mu, \lambda, \kappa \) comply with (2.16–2.17) and the stress tensor is given by (1.11).

Suppose that \( (\varrho_0, \vec{V}_0, \Theta_0) \) satisfy assumptions of Proposition 2.2 and let \( T^* > 0 \) be the time interval of existence of the strong solution to problem (2.39-2.44) corresponding to \( r_0, \vec{V}_0, \Theta_0 \) determined in Proposition 2.2. Let either \( \beta = 0, \alpha = 0, \gamma > \frac{3}{2} \) and \( g \in L^p(\mathbb{R}^3) \) with \( p = 1 \) for \( \gamma > 6 \) and \( p = \frac{5\gamma}{\gamma - 6} \) for \( \gamma \in \left( \frac{3}{2}, 6 \right) \), or \( \beta = \frac{1}{2}, \alpha = 1 \) and \( \gamma \geq \frac{12}{5} \).

Let \( (\varrho_\epsilon, \vec{u}_\epsilon, \vartheta_\epsilon) \) be a sequence of weak solutions to the 3-D compressible Navier–Stokes–Fourier(–Poisson) system (2.34–2.37) with (2.21), emanating from the initial data \( (\varrho_0, \vec{V}_0, \Theta_0) \).

Suppose that

\[ I(\varrho_0, \vec{V}_0, \Theta_0) \to 0, \]

where \( \vec{U}_0 = (\vec{V}_0, 0) \). Then

\[ \text{ess sup}_{t \in [0, T_{\max}]} I(\varrho_\epsilon, \vec{u}_\epsilon, \vartheta_\epsilon | r, \vec{U}, \Theta) \to 0, \]

\[ \varrho_\epsilon \to \Theta \quad \text{strongly in } L^2(0, T; W^{1,2}(\Omega)), \]

\[ \vartheta_\epsilon \to \Theta \quad \text{strongly in } L^2(0, T; W^{1,2}(\Omega)) \]

where the triple \((r, \vec{V}, \Theta)\) satisfies the 2-D compressible Navier–Stokes–Fourier(–Poisson) system (2.33, 2.43) with the boundary conditions (2.30) and (2.32) on the time interval \([0, T]\) for any \( 0 < T < T_\star \).

**Remark 2.1** Indeed, we may also include for \( \beta = 0 \) in the primitive system the part corresponding to the self-gravitation of the fluid. However, passing with \( \epsilon \to 0^+ \), this term tends to zero, therefore we do not consider it here, as it would lead to an additional restriction for \( \gamma \).
Remark 2.2 Condition (2.55) is the necessary condition for the validity of the 2-D system, as it means that the gravitational force in the $x_3$-direction in $\omega$ is zero. Indeed, we may replace this condition by adding another force term to the right-hand side of (2.40) which would compensate this gravitational force. The proof is the same as in our case.

Remark 2.3 From (2.57) it follows, in addition to Theorem 2.1, $\rho_\varepsilon \to \rho$ in $C_{\text{weak}}([0,T];L^r(\Omega))$, $\rho_\varepsilon \to \rho$ a.a. in $(0,T) \times \Omega$. (2.61)

Remark 2.4 Let us mention that we assume more stronger assumptions in Theorem 2.1 in the case $\alpha = 1$, $\beta = \frac{1}{2}$ than in Proposition 2.1 since we need estimates independent of $\varepsilon$ see (4.7).

Corollary 2.1 Suppose that the thermodynamic functions $p$, $e$, $s$ satisfy hypotheses (2.1–2.11), that the transport coefficients $\mu$, $\lambda$, $\kappa$ comply with (2.16–2.17) and the stress tensor is given by (1.11). Assume that $(\rho_\varepsilon,0,\vec{u}_\varepsilon,\vartheta_\varepsilon)$, $\rho_\varepsilon,0,\vec{u}_\varepsilon,\vartheta_\varepsilon \geq 0$, $\vartheta_\varepsilon,0 \geq 0$ satisfy

$$\int_0^1 \rho_{0,\varepsilon}(x) \, dx_3 \to r_0 \quad \text{weakly in } L^1(\omega),$$

(2.62)

$$\int_0^1 \rho_{0,\varepsilon}(x) \vec{u}_{0,\varepsilon} \, dx_3 \to \vec{V}_0 \quad \text{weakly in } L^1(\omega;\mathbb{R}^2),$$

(2.63)

$$\int_0^1 \vartheta_{0,\varepsilon}(x) \, dx_3 \to \Theta_0 \quad \text{weakly in } L^1(\omega),$$

(2.64)

where $r_0, \vec{w}_0, \Theta_0$ belong to the regularity class (2.49), and

$$\int_{\Omega} \left( \frac{1}{2} \rho_{0,\varepsilon} |\vec{u}_{0,\varepsilon}|^2 + \rho_{0,\varepsilon} e(\rho_{0,\varepsilon}, \vartheta_{0,\varepsilon}) \right) \, dx \\
\to \int_{\Omega} \left( \frac{1}{2} r_0 |\vec{V}_0|^2 + r_0 e(r_0, \Theta_0) \right) \, dx_k.$$

(2.65)

Let $(\rho_\varepsilon, \vec{u}_\varepsilon, \vartheta_\varepsilon)$ be a sequence of weak solutions to the 3-D compressible Navier–Stokes–Fourier system (2.26–2.29) emanating from the initial data $(\rho_{0,\varepsilon}, \vec{u}_{0,\varepsilon}, \vartheta_{0,\varepsilon})$. Then (2.57–2.60) hold.

3 Relative entropy inequality

We introduce the relative entropy inequality which is satisfied by any weak solution of the Navier–Stokes–Fourier–Poisson system. We follow here the ideas from the paper [10]. Let us consider a triple $\{r, \vec{U}, \Theta\}$, smooth functions such that $r$ and $\Theta$ are bounded below away from zero in $[0,T] \times \Omega$, $\vec{U} \mid_{\partial \omega \times (0,1)} = \vec{0}$, and $U_3 \mid_{\omega \times (0,1)} = 0$.

We call ballistic free energy the thermodynamic potential given by

$$H_3(r, \Theta) = re(r, \Theta) - \bar{\vartheta} s(r, \Theta),$$

(2.66)
where \((r, \Theta, \tilde{v})\) are sufficiently regular function so that the definition as well as the computations below are meaningful. We denote \((\rho_\epsilon, \bar{u}_\epsilon, \vartheta_\epsilon)\) the weak solution to (2.34)-(2.37) with (2.21) for a fixed \(\epsilon > 0\). The \textit{relative entropy} is then defined by

\[
\mathcal{E}(\rho, \vartheta|\tilde{\rho}, \tilde{\vartheta}) := H_{\tilde{\rho}}(\rho, \vartheta) - \partial_\rho H_{\tilde{\rho}}(\tilde{\rho}, \tilde{\vartheta})(\rho - \tilde{\rho}) - H_{\tilde{\rho}}(\tilde{\rho}, \tilde{\vartheta}).
\]

Using as a test function in (2.34) with \(b \equiv 0\) the function \(\varphi = \frac{1}{2} |\bar{U}|^2\) and using that \(\bar{U}\) is sufficiently smooth, we arrive after standard manipulations at

\[
\int_\Omega \frac{1}{2} (\varphi_\epsilon |\bar{U}|^2)(\tau) \, dx - \int_\Omega \frac{1}{2} \rho_0 \epsilon |\bar{U}(0, \cdot)|^2 \, dx
\]

\[
= \int_0^\tau \int_\Omega \varphi_\epsilon \left( \bar{U} \cdot \partial_\tau \bar{U} + \bar{u}_\epsilon \cdot \nabla_\tau \bar{U} \right) \, dx \, dt. \tag{3.1}
\]

Next, using as test function in (2.35) \(\phi = \bar{U}\), we get similarly as above

\[
\int_\Omega \varphi_\epsilon \bar{u}_\epsilon (\tau, \cdot) \cdot \bar{U} (\tau, \cdot) \, dx - \int_\Omega \varphi_\epsilon \bar{u}_0 \cdot \bar{U}(0, \cdot) \, dx
\]

\[
= \int_0^\tau \int_\Omega \left( \varphi_\epsilon \bar{u}_\epsilon \cdot \partial_\tau \bar{U} + \varphi_\epsilon \bar{u}_\epsilon \otimes \bar{u}_\epsilon : \nabla \bar{U} + p(\varphi_\epsilon, \vartheta_\epsilon) \text{div}_\epsilon \bar{U} - \mathbb{S}(\varphi_\epsilon, \nabla_\epsilon \bar{u}_\epsilon) : \nabla_\epsilon \bar{U} \right) \, dx \, dt
\]

\[
- \int_0^\tau \int_\Omega \left( \varphi_\epsilon (\bar{x} \times \bar{u}_\epsilon) \cdot \bar{U} - \epsilon^{-2\beta} \varphi_\epsilon \bar{E} \cdot \bar{U} - \varphi_\epsilon \nabla_\epsilon |\bar{x}|^2 \cdot \bar{U} \right) \, dx \, dt. \tag{3.2}
\]

Combining (3.1), (3.2) and (2.37), we get

\[
\int_\Omega \left( \frac{1}{2} \varphi_\epsilon |\bar{u}_\epsilon - \bar{U}|^2 + \varphi_\epsilon c(\varphi_\epsilon, \vartheta_\epsilon) \right) \, dx
\]

\[
= \int_\Omega \left( \frac{1}{2} \rho_0 \epsilon |\bar{u}_0 \epsilon - \bar{U}(0, \cdot)|^2 + \rho_0 \epsilon c(\rho_0 \epsilon, \vartheta_\epsilon) \right) \, dx
\]

\[
+ \int_0^\tau \int_\Omega \left( \epsilon^{-2\beta} \varphi_\epsilon \bar{E} \cdot (\bar{u}_\epsilon - \bar{U}) - \varphi_\epsilon (\bar{x} \times \bar{u}_\epsilon) \cdot (\bar{u}_\epsilon - \bar{U}) + \varphi_\epsilon \nabla_\epsilon |\bar{x}|^2 \cdot (\bar{u}_\epsilon - \bar{U}) \right) \, dx \, dt
\]

\[
+ \int_0^\tau \int_\Omega \left( \left( \varphi_\epsilon \partial_\tau \bar{U} + \varphi_\epsilon \bar{u}_\epsilon \cdot \nabla_\epsilon \bar{U} \right) \cdot (\bar{U} - \bar{u}_\epsilon) - p(\varphi_\epsilon, \vartheta_\epsilon) \text{div}_\epsilon \bar{U} + \mathbb{S}(\varphi_\epsilon, \nabla_\epsilon \bar{u}_\epsilon) : \nabla_\epsilon \bar{U} \right) \, dx \, dt. \tag{3.3}
\]

Using finally as test function in (2.36) \(\varphi = \Theta\), we get

\[
\int_\Omega \rho_0 \epsilon s(\rho_0 \epsilon, \vartheta_\epsilon) \Theta (0, \cdot) \, dx - \int_\Omega \rho_\epsilon s(\varphi_\epsilon, \vartheta_\epsilon) \Theta (\tau, \cdot) \, dx
\]

\[
+ \int_0^\tau \int_\Omega \frac{\Theta}{\varphi_\epsilon} \left( \mathbb{S}(\varphi_\epsilon, \nabla_\epsilon \bar{u}_\epsilon) : \nabla_\epsilon \bar{u}_\epsilon - \frac{\bar{q}(\partial_\varphi \vartheta_\epsilon, \nabla_\epsilon \vartheta_\epsilon) \cdot \nabla_\epsilon \vartheta_\epsilon}{\varphi_\epsilon} \right) \, dx \, dt
\]

\[
\leq - \int_0^\tau \int_\Omega \left( \varphi_\epsilon s(\varphi_\epsilon, \vartheta_\epsilon) \partial_\tau \Theta + \varphi_\epsilon s(\varphi_\epsilon, \vartheta_\epsilon) \bar{u}_\epsilon \cdot \nabla_\Theta \right) \, dx \, dt
\]
\[ - \int_0^T \int_\Omega \frac{q(\partial_\tau, \nabla_\tau \partial_\tau)}{\partial_\tau} \cdot \nabla_\tau \Theta \, dx \, dt. \]  

From (3.3) and (3.4) we get

\[ \int_\Omega \left( \frac{1}{2} \varrho_\varepsilon |\tilde{u}_\varepsilon - \tilde{U}|^2 + \varrho_\varepsilon c(\varrho_\varepsilon, \varrho_\varepsilon) - \varrho_\varepsilon s(\varrho_\varepsilon, \varrho_\varepsilon) \right) (\tau, \cdot) \, dx \]

\[ + \int_0^T \int_\Omega \frac{\Theta}{\partial_\tau} \left( S(\partial_\tau, \nabla_\tau \tilde{u}_\varepsilon) : \nabla_\tau \tilde{u}_\varepsilon - \tilde{q}(\partial_\tau, \nabla_\tau \partial_\tau) \cdot \nabla_\tau \partial_\tau \right) \, dx \, dt \]

\[ \leq \int_\Omega \left( \frac{1}{2} \varrho_0, \varepsilon |\tilde{u}_0, \varepsilon - \tilde{U}(0, \cdot)|^2 + \varrho_0, \varepsilon c(\varrho_0, \varepsilon, \varrho_0, \varepsilon) - \varrho_0, \varepsilon s(\varrho_0, \varepsilon, \varrho_0, \varepsilon) \Theta(0, \cdot) \right) \, dx \]

\[ + \int_0^T \int_\Omega \left( \varrho_\varepsilon \partial_\tau \tilde{U} + \varrho_\varepsilon \tilde{u}_\varepsilon \cdot \nabla_\tau \tilde{U} \right) \cdot \left( \tilde{U} - \tilde{u}_\varepsilon \right) \, dx \, dt \]

\[ - \int_0^T \int_\Omega \left( \varrho_\varepsilon s(\varrho_\varepsilon, \varrho_\varepsilon) \partial_\tau \Theta + \varrho_\varepsilon s(\varrho_\varepsilon, \varrho_\varepsilon) \tilde{u}_\varepsilon \cdot \nabla_\tau \Theta + \frac{\tilde{q}_\varepsilon}{\partial_\tau} \cdot \nabla_\tau \Theta \right) \, dx \, dt \]

\[ + \int_0^T \int_\Omega \left( \epsilon^{-2\beta} \varrho_\varepsilon \tilde{E} \cdot (\tilde{u}_\varepsilon - \tilde{U}) - \varrho_\varepsilon (\Theta r \times \tilde{u}_\varepsilon) \cdot (\tilde{u}_\varepsilon - \tilde{U}) + \varrho_\varepsilon \nabla r \cdot \tilde{E} \right) \, dx \, dt. \]

Using as test function in (2.34) with \( b \equiv 0 \) the function \( \phi = \partial_\tau H_\Theta(r, \Theta) \), we get

\[ \int_\Omega \varrho_\varepsilon \partial_\tau H_\Theta(r, \Theta)(\tau, \cdot) \, dx - \int_\Omega \varrho_0, \varepsilon \partial_\tau H_\Theta(0, \cdot) (r(0, \cdot), \Theta(0, \cdot)) \, dx \]

\[ = \int_0^T \int_\Omega \left( \varrho_\varepsilon \partial_\tau \left( \partial_\tau H_\Theta(r, \Theta) \right) + \varrho_\varepsilon \tilde{u}_\varepsilon \cdot \nabla_\tau \left( \partial_\tau H_\Theta(r, \Theta) \right) \right) \, dx \, dt. \]

Formulas (3.5) and (3.6) yield

\[ \int_\Omega \left( \frac{1}{2} \varrho_\varepsilon |\tilde{u}_\varepsilon - \tilde{U}|^2 + H_\Theta(\varrho_\varepsilon, \varrho_\varepsilon) - H_\Theta(r, \Theta) - \partial_\tau H_\Theta(r, \Theta)(\varrho_\varepsilon - r) \right) (\tau, \cdot) \, dx \]

\[ + \int_0^T \int_\Omega \frac{\Theta}{\partial_\tau} \left( S(\partial_\tau, \nabla_\tau \tilde{u}_\varepsilon) : \nabla_\tau \tilde{u}_\varepsilon - \tilde{q}(\partial_\tau, \nabla_\tau \partial_\tau) \cdot \nabla_\tau \partial_\tau \right) \, dx \, dt \]

\[ \leq \int_\Omega \frac{1}{2} \varrho_0, \varepsilon |\tilde{u}_0, \varepsilon - \tilde{U}(0, \cdot)|^2 \, dx \]

\[ + \int_\Omega \left( H_\Theta(0, \cdot) (\varrho_0, \varepsilon, \varrho_0, \varepsilon) - H_\Theta(0, \cdot) (r(0, \cdot), \Theta(0, \cdot)) \right) \, dx \]

\[ - \partial_\tau H_\Theta(0, \cdot) (r(0, \cdot), \Theta(0, \cdot))(\varrho_0, \varepsilon - r(0, \cdot)) \, dx \]

\[ + \int_0^T \int_\Omega \left( \varrho_\varepsilon \partial_\tau \tilde{U} + \varrho_\varepsilon \tilde{u}_\varepsilon \cdot \nabla_\tau \tilde{U} \right) \cdot \left( \tilde{U} - \tilde{u}_\varepsilon \right) \, dx \, dt \]

\[ - \int_0^T \int_\Omega \left( \varrho_\varepsilon s(\varrho_\varepsilon, \varrho_\varepsilon) \partial_\tau \Theta + \varrho_\varepsilon s(\varrho_\varepsilon, \varrho_\varepsilon) \tilde{u}_\varepsilon \cdot \nabla_\tau \Theta + \frac{\tilde{q}(\partial_\tau, \nabla_\tau \partial_\tau)}{\partial_\tau} \cdot \nabla_\tau \Theta \right) \, dx \, dt \]
\[ - \int_{0}^{T} \int_{\Omega} \left( \varrho \partial_t \left( \partial_r H_{\Theta}(r, \Theta) \right) + \varrho \vec{u}_e \cdot \nabla \left( \partial_r H_{\Theta}(r, \Theta) \right) \right) \, dx \, dt \]
\[ + \int_{0}^{T} \int_{\Omega} \left( \varrho \vec{E} \cdot \left( \vec{u}_e - \vec{U} \right) - \varrho \vec{E} \times \vec{u}_e \cdot \left( \vec{u}_e - \vec{U} \right) + \varrho \nabla \vec{E} \cdot \left( \vec{u}_e - \vec{U} \right) \right) \, dx \, dt \]
\[ + \int_{0}^{T} \int_{\Omega} \partial_t \left( r \partial_r H_{\Theta}(r, \Theta) - H_{\Theta}(r, \Theta) \right) \, dx \, dt. \]  

(3.7)

Observing finally that for \( D = \partial_t \) or \( D = \nabla \) one has

\[ D \partial_r H_{\Theta}(r, \Theta) = -s(r, \Theta) D \Theta - r \partial_r s(r, \Theta) D \Theta + \partial_{rr} H_{\Theta}(r, \Theta) Dr + \partial_{\Theta \Theta} H_{\Theta}(r, \Theta) D \Theta, \]

and using the thermodynamic relations \((\ref{1.10})\) (Maxwell’s relation) and \((\ref{2.9})\) (Gibbs’ relation), the following relative entropy inequality holds

\[ \int_{\Omega} \left( \frac{1}{2} \varrho |\vec{u}_e - \vec{U}|^2 + \mathcal{E}(\varrho, \varrho_e |r, \Theta) \right) (\tau, \cdot) \, dx \]
\[ + \int_{0}^{T} \int_{\Omega} \frac{\Theta}{\varrho_e} \left( \mathcal{S}(\varrho_e, \nabla \vec{u}_e) : \nabla \vec{u}_e - \frac{\varrho_e}{\varrho_e} \nabla \vec{u}_e \right) \, dx \, dt \]
\[ \leq \int_{\Omega} \left( \frac{1}{2} \varrho_0 |\vec{u}_0, \vec{U} (0, \cdot)|^2 + \mathcal{E}(\varrho_0, \varrho_0, \Theta (0, \cdot)) \right) \, dx \]
\[ + \int_{0}^{T} \int_{\Omega} \varrho_e (\vec{u}_e - \vec{U}) \cdot \nabla \vec{U} \cdot (\vec{U} - \vec{u}_e) \, dx \, dt \]
\[ + \int_{0}^{T} \int_{\Omega} \varrho_e (s(\varrho_e, \varrho_e) - s(r, \Theta)) (\vec{U} - \vec{u}_e) \cdot \nabla \vec{U} \, dx \, dt \]
\[ + \int_{0}^{T} \int_{\Omega} \left( \varrho_e \left( \partial_t \vec{U} + \vec{U} \cdot \nabla \vec{U} \right) \cdot (\vec{U} - \vec{u}_e) \right) \, dx \, dt \]
\[ - \int_{0}^{T} \int_{\Omega} \left( \vec{E} \cdot \vec{u}_e \, dx \right) \right) \, dx \, dt \]
\[ - \int_{0}^{T} \int_{\Omega} \left( \varrho_e (s(\varrho_e, \varrho_e) - s(r, \Theta)) \partial_t \Theta \right) \, dx \, dt \]
\[ - \int_{0}^{T} \int_{\Omega} \varrho_e (s(\varrho_e, \varrho_e) - s(r, \Theta)) \vec{U} \cdot \nabla \Theta \, dx \, dt \]
\[ - \int_{0}^{T} \int_{\Omega} \varrho_e \vec{E} \cdot \nabla \Theta \, dx \, dt \]
\[ + \int_{0}^{T} \int_{\Omega} \left( \left( 1 - \varrho_e \frac{\varrho_e}{r} \right) \partial_r p(r, \Theta) - \frac{\varrho_e}{r} \vec{u}_e \cdot \nabla p(r, \Theta) \right) \, dx \, dt \]
\[ + \int_{0}^{T} \int_{\Omega} \left( \varrho_e \vec{E} \cdot (\vec{u}_e - \vec{U}) - \varrho_e \vec{E} \times (\vec{u}_e - \vec{U}) + \varrho_e \nabla \vec{E} \cdot (\vec{u}_e - \vec{U}) \right) \, dx \, dt. \]
4 Proof of Theorem 2.1

4.1 Preliminaries

It is easy to verify that

\[ S(\vartheta, \nabla \vartheta) : \nabla \vartheta = \left( \eta(\vartheta) - \frac{2}{3} \mu(\vartheta) \right) |\text{div} \vartheta|^2 + \mu(\vartheta) (|\nabla \vartheta|^2 + \nabla \vartheta : (\nabla \vartheta)^T) \tag{4.1} \]

for any \( \vartheta \in W^{1,2}(\Omega; \mathbb{R}^3) \). As for any \( \vartheta \in W^{1,2}_{0,\alpha}(\Omega; \mathbb{R}^3) \)

\[ \int_{\Omega} \nabla \vartheta : (\nabla \vartheta)^T \, dx = \int_{\Omega} (\text{div} \vartheta)^2 \, dx, \]

we have for \( \vartheta \in W^{1,2}_{0,\alpha}(\Omega; \mathbb{R}^3) \)

\[ \int_{\Omega} S(\vartheta, \nabla \vartheta) : \nabla \vartheta \, dx \geq C\| \vartheta \|_{W^{1,2}(\Omega; \mathbb{R}^3)}^2, \tag{4.2} \]

\[ \int_{\Omega} \frac{1}{\vartheta} S(\vartheta, \nabla \vartheta) : \nabla \vartheta \, dx \geq C\| \vartheta \|_{W^{1,2}(\Omega; \mathbb{R}^3)}^2, \tag{4.3} \]

provided \( \mu \) fulfills (2.10), \( \eta \equiv 0, \epsilon \leq 1 \) and \( \vartheta > 0 \) in \((0, T) \times \Omega \). Indeed, easily

\[ \int_{\Omega} S_h(\Theta, \nabla \Theta) : \nabla \Theta \, dx \geq C\| \Theta \|_{W^{1,2}(\omega; \mathbb{R}^2)}^2, \tag{4.4} \]

\[ \int_{\Omega} \frac{1}{\Theta} S_h(\Theta, \nabla \Theta) : \nabla \Theta \, dx \geq C\| \Theta \|_{W^{1,2}(\omega; \mathbb{R}^2)}^2 \tag{4.5} \]

for any \( \Theta \in W^{1,2}_0(\omega; \mathbb{R}^2) \) and \( \Theta > 0 \) in \((0, T) \times \omega \).

Moreover, note that we also have the Poincaré inequality in the form

\[ \| \nabla \Theta \|_{L^2(\omega; \mathbb{R}^2)} \leq c\| \nabla \Theta \|_{L^2(\omega; \mathbb{R}^{2 \times 2})} \tag{4.6} \]

for any \( \Theta \in W^{1,2}_0(\omega; \mathbb{R}^2) \).

Due to the energy equality (2.37) combined with the entropy inequality (2.36) and Korn’s inequality in the form (4.3), we have that the sequence \( (\vartheta_\epsilon, \tilde{u}_\epsilon, \tilde{\vartheta}_\epsilon) \) is bounded in the following spaces

\[ \| \vartheta_\epsilon \|_{L^\infty(0, T; L^\gamma(\Omega))} + \| \sqrt{\vartheta_\epsilon} \tilde{u}_\epsilon \|_{L^\infty(0, T; L^2(\Omega; \mathbb{R}^3))} + \| \tilde{u}_\epsilon \|_{L^2(0, T; W^{1,2}(\Omega; \mathbb{R}^3))} + \| \nabla \vartheta_\epsilon \|_{L^2(0, T; L^2(\Omega; \mathbb{R}^3))} \tag{4.7} \]

with the constant \( C \) independent of \( \epsilon \). These estimates hold if \( \gamma \geq \frac{12}{5} \) (if \( \alpha = 1 \)) or under the assumptions on \( g \) from Theorem 2.1 (if \( \alpha = 0 \), for any \( \gamma > \frac{3}{2} \)). Note that the limit on \( \gamma \) comes from the gravitational potential, as

\[ \| \nabla \epsilon \int_{\Omega} \frac{\vartheta(y)}{\sqrt{(x_3 - y_3)^2 + \epsilon^2(x_2 - y_2)^2 + (x_1 - y_1)^2}} \, dy \|_{L^p(\Omega; \mathbb{R}^3)} \leq C\| \vartheta \|_{L^p(\Omega)} \]
for \( 1 < p < \infty \), with \( C \) independent of \( \epsilon \).

We recall the necessary definitions of essential and residual sets from [9]. We take four positive numbers \( 0 < \varrho \leq \vartheta < \infty \), \( 0 < \underline{\vartheta} \leq \overline{\vartheta} < \infty \). The essential and residual subsets of \( \Omega \) are defined for a.e. \( t \in (0, T) \) as follows:

\[
O_{\text{ess}}^\epsilon(t) = \left\{ x \in \Omega \mid \frac{1}{2} \varrho \leq \varrho_e(t, x) \leq 2\overline{\vartheta}, \frac{1}{2} \underline{\vartheta} \leq \vartheta_e(t, x) \leq 2\overline{\vartheta} \right\}, \quad O_{\text{res}}(t) = \Omega \setminus O_{\text{ess}}^\epsilon(t). \quad (4.8)
\]

For any function \( h \) defined for a.e. \( (t, x) \in (0, T) \times \Omega \), we write

\[
[h]_{\text{ess}}(t, x) = h(t, x)1_{O_{\text{ess}}^\epsilon(t)}(x), \quad [h]_{\text{res}}(t, x) = h(t, x)1_{O_{\text{res}}(t)}(x). \quad (4.9)
\]

Now, using [9], we have the following properties of the Helmholtz function.

**Lemma 4.1** Let \( \overline{\vartheta} > 0 \) and \( \overline{\vartheta} > 0 \) be two given constants and let \( H_{\varrho}(\varrho, \vartheta) = \varrho e - \overline{\vartheta} s \).

Let \( O_{\text{ess}}(t) \) be defined as above with \( \varrho = \overline{\varrho} \) and \( \vartheta = \overline{\vartheta} \). Then there exist positive constants \( C_j = C_j(\varrho, \vartheta) \) for \( j = 1, \ldots, 4 \) such that

\[
C_1 \left( |\varrho - \overline{\varrho}|^2 + |\vartheta - \overline{\vartheta}|^2 \right) \leq H_{\varrho}(\varrho, \vartheta) - (\varrho - \overline{\vartheta}) \varrho e H_{\varrho}(\varrho, \vartheta) - H_{\varrho}(\varrho, \vartheta)
\]
\[
\leq C_2 \left( |\varrho - \overline{\varrho}|^2 + |\vartheta - \overline{\vartheta}|^2 \right), \quad (4.10)
\]

for all \( (\varrho, \vartheta) \in O_{\text{ess}}(t) \),

\[
H_{\varrho}(\varrho, \vartheta) - (\varrho - \overline{\vartheta}) \vartheta e H_{\varrho}(\varrho, \vartheta) - H_{\varrho}(\varrho, \vartheta)
\]
\[
\geq \inf_{(\tilde{\varrho}, \tilde{\vartheta}) \in \partial O_{\text{ess}}} \left\{ H_{\varrho}(\tilde{\varrho}, \tilde{\vartheta}) - (\tilde{\varrho} - \overline{\vartheta}) \tilde{\vartheta} e H_{\varrho}(\tilde{\varrho}, \tilde{\vartheta}) - H_{\varrho}(\tilde{\varrho}, \tilde{\vartheta}) \right\} = C_3, \quad (4.11)
\]

for all \( (\varrho, \vartheta) \in O_{\text{res}}(t) \),

\[
H_{\varrho}(\varrho, \vartheta) - (\varrho - \overline{\vartheta}) \vartheta e H_{\varrho}(\varrho, \vartheta) - H_{\varrho}(\varrho, \vartheta) \geq C_4 (\varrho e(\varrho, \vartheta) + \varrho s(\varrho, \vartheta)), \quad (4.12)
\]

for all \( (\varrho, \vartheta) \in O_{\text{res}}(t) \),

**Proof.** See [9] Lemma 5.1. \( \square \)

As a consequence we get the following lemma.

**Lemma 4.2** There exists a constant \( C = C(\varrho, \overline{\varrho}, \overline{\vartheta}, \overline{\vartheta}) > 0 \) such that for all \( \varrho \in [0, \infty) \), \( r \in [\varrho/2, 2\overline{\vartheta}] \), \( \vartheta \in (0, \infty) \) and \( \Theta \in [\overline{\vartheta}/2, 2\overline{\vartheta}] \)

\[
\mathcal{E}(\varrho, \vartheta; r, \Theta)(\tau, \cdot) \geq C(\varrho, \overline{\varrho}, \overline{\vartheta}, \overline{\vartheta})(1_{O_{\text{res}}} + \varrho^2 1_{O_{\text{res}}} + \vartheta^2 1_{O_{\text{res}}} + (\varrho - r)^2 1_{O_{\text{res}}} + (\vartheta - \Theta)^2 1_{O_{\text{res}}}).
\]

The lemma yields the lower bound of the relative entropy functional

\[
\mathcal{I}(\varrho_e, \vartheta_e; r, \tilde{U}, \Theta) \geq C(\varrho, \overline{\varrho}, \overline{\vartheta}, \overline{\vartheta}) \int_{\Omega} \left( \varrho_e |\tilde{U} - \overline{U}|^2 + 1_{\text{res}} + [\varrho_e]_{\text{res}} + [\varrho_e - r]_{\text{res}}^2 + [\vartheta_e]_{\text{res}}^2 + [\vartheta_e - \Theta]_{\text{ess}}^2 \right) \, dx. \quad (4.13)
\]
4.2 Estimates of the remainder

We now return back to (3.8), where we assume that \((r, \tilde{U}, \Theta)\), \(\tilde{U} = (\tilde{V}, 0)\), is such that \((r, \tilde{V}, \Theta)\) solves the 2-D Navier–Stokes–Fourier–Poisson system \((2.39) \text{–} (2.44)\) in \((0, T) \times \omega\), see Proposition 2.2. We further use the following. In order to integrate over \(\Omega\), we assume that the functions defined only on \(\omega\) are extended being constant in \(x_3\) for \(0 \leq x_3 \leq 1\). Moreover, we write \(\tilde{U}\) instead of \(\tilde{V}\) in the situations, when we need to use a vector field with three components. Similarly, we write \(\vec{u}\) instead of \(\vec{E}\) in the situations, when we need to use a vector field with three components. Similarly, we write \(\vec{u}\) instead of \(\vec{E}\) in the situations, when we need to use a vector field with three components.

Recall that these functions are sufficiently regular and fulfill the corresponding boundary conditions, therefore they can be used as test functions in \((2.34) \text{–} (2.36)\). Similarly, we write in such situations \(S(\Theta, \nabla_x U)\) instead of \(S_h(\Theta, \nabla_h \tilde{V})\).

We denote \(\underline{q} = \inf_{(0,T) \times \Omega} r, \quad \overline{q} = \sup_{(0,T) \times \Omega} r\) and \(\underline{q} = \inf_{(0,T) \times \Omega} \Theta\) and \(\overline{q} = \sup_{(0,T) \times \Omega} \Theta\) and use these numbers in order to define the essential and residual sets in \((18)\). As above, \((\varrho_e, \vec{u}_e, \vartheta_e)\) denotes the solution to the primitive system. We now rearrange the remainder, i.e. the terms on the right-hand side of \((3.8)\) which are integrated over time and space, as follows

\[
\int_0^T R(q_e, \vec{u}_e, \vartheta_e, r, \tilde{V}, \Theta) \, dt
\]

\[
= \int_0^T \int_{\Omega} q_e (\vec{u}_e - \tilde{U}) \cdot \nabla_x \tilde{U} \cdot (\vec{U} - \vec{u}_e) \, dx \, dt \\
+ \int_0^T \int_{\Omega} q_e (s(q_e, \vartheta_e) - s(r, \Theta)) (\vec{u}_e - \vec{U}) \cdot \nabla_x \Theta \, dx \, dt \\
+ \int_0^T \int_{\Omega} q_e (\partial_t \vec{U} + \vec{U} \cdot \nabla_x \tilde{U}) \cdot (\vec{U} - \vec{u}_e) \, dx \, dt \\
- \int_0^T \int_{\Omega} q_e (s(q_e, \vartheta_e) - s(r, \Theta)) \partial_t \Theta \, dx \, dt \\
- \int_0^T \int_{\Omega} q_e (s(q_e, \vartheta_e) - s(r, \Theta)) \tilde{V} \cdot \nabla_h \Theta \, dx \, dt \\
+ \int_0^T \int_{\Omega} \left( 1 - \frac{\varrho_e}{r} \right) \partial_t p(r, \Theta) - \frac{\varrho_e}{r} \vec{u}_e \cdot \nabla_x p(r, \Theta) \right) \, dx \, dt \\
+ \int_0^T \int_{\Omega} q_e (\vec{X} \times \vec{u}_e) \cdot (\vec{U} - \vec{u}_e) \, dx \, dt - \int_0^T \int_{\Omega} q_e \nabla_x |\vec{X} \times \vec{x}|^2 \cdot (\vec{U} - \vec{u}_e) \, dx \, dt \\
- \int_0^T \int_{\Omega} e^{-2\vartheta} \varrho_e \vec{E} \cdot (\vec{U} - \vec{u}_e) \, dx \, dt - \int_0^T \int_{\Omega} \left( \frac{\varrho_e (\vartheta_e, \nabla \vartheta_e)}{\varrho_e} \right) \cdot \nabla_x \Theta \, dx \, dt \\
- \int_0^T \int_{\Omega} \left( p(q_e, \vartheta_e) \right) \nabla_h \tilde{V} - S(\vartheta_e, \nabla \vartheta_e) : \nabla \tilde{V} \right) \, dx \, dt =: \int_0^T \left( \sum_{j=1}^{11} R_j \right) \, dt.
\]

Let us now estimate all terms in \(R(q_e, \vec{u}_e, \vartheta_e, r, \tilde{V}, \Theta)\).

We have

\[
R_1 = \int_{\Omega} q_e (\vec{u}_e - \vec{U}) \cdot \nabla_x \vec{U} \cdot (\vec{U} - \vec{u}_e) \, dx \leq CD(t) I(q_e, \vec{u}_e, \vartheta_e; r, \vec{U}, \Theta)
\]

\[
\|\nabla_x \vec{u}_e\|_\infty \leq C \|\nabla_x \vec{U}\|_\infty \quad \text{and} \quad \|\vec{U}\|_\infty \leq C \|\vec{U}\|_\infty.
\]

Let us now estimate all terms in \(R(q_e, \vec{u}_e, \vartheta_e, r, \tilde{V}, \Theta)\).
with

$$ D = \|\nabla_h \tilde{V}\|_{L^\infty(\Omega;\mathbb{R}^{2\times 2})} \in L^1(0,T), $$

due to the assumption on the smoothness of $\tilde{V}$. Next

$$ |R_2| \leq \left| \int_{\Omega} \varrho e (s(\varrho e, \vartheta e) - s(r, \Theta)) (\tilde{U} - \tilde{u}_e) \cdot \nabla \Theta \, dx \right| $$

$$ \leq \|\nabla_h \Theta\|_{L^\infty(\Omega;\mathbb{R}^2)} \left[ 2\varphi \int_{\Omega} \|s(\varrho e, \vartheta e) - s(r, \Theta)\|_{\text{ess}} \|\tilde{U} - \tilde{u}_e\| \, dx \right] $$

$$ + \int_{\Omega} \|s(\varrho e(s(\varrho e, \vartheta e) - s(r, \Theta))\|_{\text{res}} \|\tilde{U} - \tilde{u}_e\| \, dx \right]. $$

Lemma 4.2 together with the properties of the entropy (2.12–2.13) yields

$$ \int_{\Omega} \|s(\varrho e, \vartheta e) - s(r, \Theta)\|_{\text{ess}} \|\tilde{U} - \tilde{u}_e\| \, dx \leq \delta \|\tilde{U} - \tilde{u}_e\|_{L^2(\Omega;\mathbb{R}^3)}^2 + C(\delta) \int_{\Omega} \mathcal{E}(\varrho e, \vartheta e | r, \Theta) \, dx, $$

for $\delta > 0$, and

$$ \int_{\Omega} \|s(\varrho e(s(\varrho e, \vartheta e) - s(r, \Theta))\|_{\text{res}} \|\tilde{U} - \tilde{u}_e\| \, dx \leq \delta \|\tilde{U} - \tilde{u}_e\|_{L^2(\Omega;\mathbb{R}^3)}^2 + C(\delta) \|s(\varrho e(s(\varrho e, \vartheta e) - s(r, \Theta))\|_{\text{res}} \|\tilde{U} - \tilde{u}_e\|_{L^{6/5}(\Omega)}, $$

Using again properties of the entropy (2.12–2.13) together with the fact that the mapping $t \mapsto \int_{\Omega} \mathcal{E}(\varrho e, \vartheta e | r, \Theta) \, dx \in L^\infty(0,T)$, we conclude that

$$ \|s(\varrho e(s(\varrho e, \vartheta e) - s(r, \Theta))\|_{\text{res}} \|\tilde{U} - \tilde{u}_e\|_{L^{6/5}(\Omega)} \leq C \int_{\Omega} \mathcal{E}(\varrho e, \vartheta e | r, \Theta) \, dx. $$

So finally, we end up with

$$ |R_2| \leq \delta \|\tilde{U} - \tilde{u}_e\|_{L^2(\Omega;\mathbb{R}^3)}^2 + C(\delta; r, \tilde{V}, \Theta) \int_{\Omega} \mathcal{E}(\varrho e, \vartheta e | r, \Theta) \, dx. $$

Next, using the fact that $(r, \tilde{V}, \Theta)$ solve the 2-D Navier–Stokes–Fourier–Poisson system,

$$ R_3 = \int_{\Omega} \varrho e (\partial_t \tilde{U} + \tilde{U} \cdot \nabla_h \tilde{U}) \cdot (\tilde{U} - \tilde{u}_e) \, dx = R_{3, 1} + R_{3, 2}, $$

where

$$ R_{3, 1} = \int_{\Omega} \varrho \left( \frac{\varrho e}{r} (\tilde{U} - \tilde{u}_e) \cdot (\text{div}\, S(\Theta, \nabla, \tilde{U}) - \nabla p(r, \Theta)) \right) \, dx, $$

$$ R_{3, 2} = \int_{\Omega} \varrho e (\tilde{U} - \tilde{u}_e) \cdot (-(\chi \times \tilde{U}) + \nabla |\chi| x \times \tilde{x}|^2 + \nabla_h \phi_h) \, dx = \sum_{i=1}^3 K_i. $$

We write

$$ R_{3, 1} = \int_{\Omega} \varrho \left( \frac{\varrho e}{r} (\tilde{U} - \tilde{u}_e) \cdot (\text{div}\, S(\Theta, \nabla, \tilde{U}) - \nabla p(r, \Theta)) \right) \, dx $$

20
Finally, \( \delta > 0 \) for any \( H \). Hence we conclude

\[
R_{3,1} \leq \int_{\Omega} \left( \sum_{\varepsilon} \left( \text{div}(\Theta, \nabla \varepsilon U) - \nabla \varepsilon p(r, \Theta) \right) \right) \, dx + \delta \| \bar{U} - \bar{u}_\varepsilon \|^2_{L^2(\Omega; R^3)}
\]

Integrating by parts in the second integral of \( R_{3,1} \), we have

\[
\int_{\Omega} (\bar{U} - \bar{u}_\varepsilon) \cdot (\text{div}(\Theta, \nabla \varepsilon U) - \nabla \varepsilon p(r, \Theta)) \, dx = -\int_{\Omega} \left( \sum_{\varepsilon} (\text{div}(\Theta, \nabla \varepsilon U) : \nabla \varepsilon (\bar{U} - \bar{u}_\varepsilon) - p(r, \Theta) \text{div}(\bar{U} - \bar{u}_\varepsilon)) \right) \, dx.
\]

Hence we conclude

\[
R_{3,1} \leq \int_{\Omega} \left( p(r, \Theta) \text{div}(\varepsilon - \varepsilon \Theta) - s(\varepsilon, \varepsilon \Theta) \right) \, dx + \delta \| \bar{U} - \bar{u}_\varepsilon \|^2_{L^2(\Omega; R^3)}
\]

for any \( \delta > 0 \).

The terms \( K_1-K_3 \) will be treated below, in combination with \( R_7-R_9 \).

\[
R_4 = -\int_{\Omega} \sum_{\varepsilon} \left( s(\varepsilon, \varepsilon \Theta) - s(\varepsilon, \Theta) \right) \, dx - \int_{\Omega} \left( \sum_{\varepsilon} \left( s(\varepsilon, \varepsilon \Theta) - s(\varepsilon, \Theta) \right) \right) \, dx - \int_{\Omega} \left( \sum_{\varepsilon} \left( s(\varepsilon, \varepsilon \Theta) - s(\varepsilon, \Theta) \right) \right) \, dx.
\]

We rewrite the first term as above, using the essential and residual parts, and estimate them

\[
-\int_{\Omega} \sum_{\varepsilon} \left( s(\varepsilon, \varepsilon \Theta) - s(\varepsilon, \Theta) \right) \, dx
\]

\[
= -\int_{\Omega} \left( s(\varepsilon, \Theta) - s(\varepsilon, \Theta) \right) \text{ess} \, dx - \int_{\Omega} \left( \sum_{\varepsilon} \left( s(\varepsilon, \varepsilon \Theta) - s(\varepsilon, \Theta) \right) \right) \, dx
\]

\[
\leq C(\delta; \varepsilon, \varepsilon \Theta) \int_{\Omega} \sum_{\varepsilon} \left( s(\varepsilon, \Theta) \right) \, dx.
\]

Finally

\[
-\int_{\Omega} \sum_{\varepsilon} \left( s(\varepsilon, \varepsilon \Theta) - s(\varepsilon, \Theta) \right) \, dx
\]
\[ R_4 \leq C(\delta; r, \vec{V}, \Theta) \int_\Omega \mathcal{E}(\varrho_\varepsilon, \partial_\varepsilon; \varrho, \Theta) \, dx - \int_\Omega r(\partial_\varrho s(r, \Theta)(\varrho_\varepsilon - r) + \partial_\Theta s(r, \Theta)(\varrho_\varepsilon - \Theta)) \partial_\Theta \, dx. \]

The first integral on the right-hand side can be estimated in the same way as before, using the essential and the residual parts, and we end with

\[ R_4 \leq C(\delta; r, \vec{V}, \Theta) \int_\Omega \mathcal{E}(\varrho_\varepsilon, \partial_\varepsilon; \varrho, \Theta) \, dx - \int_\Omega r(\partial_\varrho s(r, \Theta)(\varrho_\varepsilon - r) + \partial_\Theta s(r, \Theta)(\varrho_\varepsilon - \Theta)) \partial_\Theta \, dx. \]

In the estimate of the next term we use exactly the same procedure as for \( R_4 \) and end up with

\[ R_5 = - \int_\Omega \varrho_\varepsilon(s(\varrho_\varepsilon, \partial_\varepsilon) - s(r, \Theta)) \vec{V} \cdot \nabla h \Theta \, dx \leq C(\delta; r, \vec{V}, \Theta) \int_\Omega \mathcal{E}(\varrho_\varepsilon, \partial_\varepsilon; r, \Theta) \, dx - \int_\Omega r(\partial_\varrho s(r, \Theta)(\varrho_\varepsilon - r) + \partial_\Theta s(r, \Theta)(\varrho_\varepsilon - \Theta)) \partial_\Theta \, dx. \]

Furthermore

\[ R_6 = \int_\Omega \left( 1 - \frac{\varrho_\varepsilon}{r} \right) \partial_\varrho p(r, \Theta) - \frac{\varrho_\varepsilon}{r} \vec{u}_\varepsilon \cdot \nabla \varrho \, dx \]

\[ = \int_\Omega \left( 1 - \frac{\varrho_\varepsilon}{r} \right) \left( \partial_\varrho p(r, \Theta) + \vec{V} \cdot \nabla \varrho \right) \, dx + \int_\Omega p(r, \Theta) \text{div} \vec{u}_\varepsilon \, dx \]

and using the same argument as used for \( R_2 \), we get

\[ \left| \int_\Omega \left( 1 - \frac{\varrho_\varepsilon}{r} \right) \nabla \varrho \cdot (\vec{u}_\varepsilon - \vec{U}) \, dx \right| \]

\[ \leq C(\delta; r, \vec{V}, \Theta) \left( \delta \| \vec{U} - \vec{u}_\varepsilon \|_{W^{1,2}(\Omega; \mathbb{R}^3)^3} + \int_\Omega \mathcal{E}(\varrho_\varepsilon, \partial_\varepsilon; r, \Theta) \, dx \right) \]

for any \( \delta > 0 \). Hence we end with

\[ R_6 \leq \int_\Omega \left( 1 - \frac{\varrho_\varepsilon}{r} \right) \left( \partial_\varrho p(r, \Theta) + \vec{V} \cdot \nabla \varrho \right) \, dx + \int_\Omega p(r, \Theta) \text{div} \vec{u}_\varepsilon \, dx \]

\[ + \delta \| \vec{U} - \vec{u}_\varepsilon \|_{W^{1,2}(\Omega; \mathbb{R}^3)}^2 + C(\delta; r, \vec{V}, \Theta) \int_\Omega \mathcal{E}(\varrho_\varepsilon, \partial_\varepsilon; r, \Theta) \, dx. \]

We can rewrite \( R_7 \) and \( K_1 \) as follows (note that \( (\vec{\chi} \times (\vec{U} - \vec{u}_\varepsilon)) \cdot (\vec{U} - \vec{u}_\varepsilon) = 0) \)

\[ R_7 + K_1 = \int_\Omega \varrho_\varepsilon (\vec{\chi} \times \vec{U}) \cdot (\vec{U} - \vec{u}_\varepsilon) \, dx - \int_\Omega \varrho_\varepsilon (\vec{\chi} \times \vec{U}) \cdot (\vec{U} - \vec{u}_\varepsilon) \, dx = 0. \]

Similarly, we have

\[ R_8 + K_2 = 0. \]
Next we consider the gravitational potential. The case \( \alpha = 0 \) (i.e. only the gravitational effect of other objects than the fluid itself is taken into account) is relatively easy. Recall that we assume

\[
\int_{\mathbb{R}^3} \frac{\rho(y) y_3}{(\sqrt{|x_h - y_h|}^2 + y_3^2)^3} = 0.
\]

Therefore we have to show that

\[
\lim_{\epsilon \to 0^+} \int_{\Omega} \rho \epsilon (\tilde{U} - \tilde{u}_\epsilon) \cdot \left( \int_{\mathbb{R}^3} \rho(y) \right) dy \, dx = 0.
\]

First of all, due to the estimates presented above, it is not difficult to see that (note that to get estimates independent of \( \epsilon \) of the integral over \( \mathbb{R}^3 \) is easy) it is enough to verify

\[
\lim_{\epsilon \to 0^+} \int_{\mathbb{R}^3} \rho(y) \left[ \frac{(x_h - y_h, y_3)}{(\sqrt{|x_h - y_h|}^2 + y_3^2)^3} - \frac{(x_h - y_h, \epsilon x_3 - y_3)}{(\sqrt{|x_h - y_h|}^2 + (\epsilon x_3 - y_3)^2)^3} \right] dy = 0
\]

for all \( x_h \in \omega, x_3 \in (0, 1) \) and \( \overline{\rho} \in C^\infty_c(\mathbb{R}^3) \). As

\[
\lim_{\epsilon \to 0^+} \left( \frac{(x_h - y_h, \epsilon x_3 - y_3)}{(\sqrt{|x_h - y_h|}^2 + (\epsilon x_3 - y_3)^2)^3} \right) = 0
\]

for a.a. \( (x_h, x_3) \in \Omega, (y_h, y_3) \in \mathbb{R}^3 \), and

\[
\left| \frac{(x_h - y_h, \epsilon x_3 - y_3)}{(\sqrt{|x_h - y_h|}^2 + (\epsilon x_3 - y_3)^2)^3} \right| \leq \frac{1}{\sqrt{|x_h - y_h|}^2 + (\epsilon x_3 - y_3)^2} \in L^1_{\text{loc}}(\mathbb{R}^3) \quad \forall \epsilon \in [0, 1],
\]

the Lebesgue dominated convergence theorem yields the required identity

\[
(4.16)
\]

The case of the self-gravitation (\( \alpha = 1 \)) is more complex. Here, we have to show that

\[
\int_{\Omega} \rho \epsilon (\tilde{U} - \tilde{u}_\epsilon) \cdot \left[ \int_{\Omega} \frac{\rho \epsilon(t, y)(x_h - y_h, \epsilon(x_3 - y_3))}{(\sqrt{|x_h - y_h|}^2 + \epsilon^2(x_3 - y_3)^2)^3} \, dy + \nabla \epsilon \int_{\omega} \frac{r(t, y_h)}{|x_h - y_h|} \, dy_h \right] \, dx.
\]

\[
\leq \delta \|\tilde{U} - \tilde{u}_\epsilon\|_{L^1(\Omega; \mathbb{R}^3)} + C(\delta; r, \hat{V}, \Theta) \int_{\Omega} \mathcal{E}(\rho \epsilon, \nabla \epsilon, r, \Theta) \, dx + H_\epsilon,
\]

where \( H_\epsilon = o(\epsilon) \) as \( \epsilon \to 0^+ \). The derivative of the integral over \( \omega \) with respect to \( x_3 \) is indeed zero. First of all, for \( \gamma \geq \frac{1}{2} \), as in \((4.7)\), using the decomposition to the essential and the residual set and proceeding as in the estimates of the remainder above, we can show that it is enough to verify that

\[
\lim_{\epsilon \to 0^+} \int_{\Omega} \epsilon \tilde{U} \cdot \left[ \int_{\Omega} \frac{r(t, y_h)(x_h - y_h, \epsilon^2(x_3 - y_3))}{(\sqrt{|x_h - y_h|}^2 + \epsilon^2(x_3 - y_3)^2)^3} \, dy + \nabla \epsilon \int_{\omega} \frac{r(t, y_h)}{|x_h - y_h|} \, dy_h \right] \, dx = 0.
\]

Again, it is not difficult to verify that (e.g. using the change of the variables to integrate over \( \Omega_\epsilon \)) it is enough to show

\[
\lim_{\epsilon \to 0^+} \left[ \int_{\Omega} \frac{r(t, y_h)(x_h - y_h, \epsilon(x_3 - y_3))}{(\sqrt{|x_h - y_h|}^2 + \epsilon^2(x_3 - y_3)^2)^3} \, dy + \nabla \epsilon \int_{\omega} \frac{r(t, y_h)}{|x_h - y_h|} \, dy_h \right] = 0.
\]
First, note that
\[
\nabla_{t} \int_{\omega} \frac{r(t, y_{h})}{|x_{h} - y_{h}|} \, dy_{h} = -v.p. \int_{\omega} \frac{r(t, y_{h})(x_{h} - y_{h})}{|x_{h} - y_{h}|^{2}} \, dy_{h},
\]
where v.p. denotes the integral in the principal value sense. Therefore, we have to verify that
\[
\lim_{\epsilon \to 0^{+}} \int_{\Omega} \frac{\epsilon r(t, y_{h})(x_{3} - y_{3})}{\sqrt{|x_{h} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}} \, dy = 0, \tag{4.18}
\]
and
\[
\lim_{\epsilon \to 0^{+}} \int_{\Omega} \frac{\epsilon r(t, y_{h})(x_{h} - y_{h})}{\sqrt{|x_{h} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}} \, dy = v.p. \int_{\omega} \frac{r(t, y_{h})(x_{h} - y_{h})}{|x_{h} - y_{h}|^{3}} \, dy_{h}. \tag{4.19}
\]
Let us fix \(x_{0} \in \omega, \Delta > 0\), sufficiently small, and denote \(B_{\Delta}(x_{0}) = \{ x \in \omega; |x - x_{0}| < \Delta \}\) and \(C_{\Delta}(x_{0}) = \{ x \in \Omega; |x_{h} - x_{0}| < \Delta, 0 < x_{3} < 1 \}\).

We first consider (4.18). Let us fix \(\delta > 0\). Using the change of variables (from \(\Omega\) back to \(\Omega_{t}\)) it is not difficult to see that there exists \(\Delta > 0\) such that for any \(0 < \epsilon \leq 1, 0 < x_{3} < 1\) we have
\[
\left| \int_{C_{\Delta}(x_{0})} \frac{\epsilon r(t, y_{h})(x_{3} - y_{3})}{\sqrt{|x_{0} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}} \, dy \right| < \delta
\]
and for this \(\Delta > 0\) there exists \(\epsilon_{0} > 0\) such that for any \(0 < \epsilon \leq \epsilon_{0}\)
\[
\left| \int_{\Omega \setminus C_{\Delta}(x_{0})} \frac{\epsilon r(t, y_{h})(x_{3} - y_{3})}{\sqrt{|x_{0} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}} \, dy \right| < \delta.
\]
Whence (4.18).

In order to prove (4.19), we proceed similarly. Since \(\frac{\epsilon r(t, y_{h})}{\sqrt{|x_{h} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}}\) is a singular integral kernel in the sense of the Calderón–Zygmund theory, as above, for a fixed \(x_{0} \in \omega, 0 < x_{3} < 1\) and \(\delta > 0\) that there there exists \(\Delta > 0\) such that
\[
\left| \int_{C_{\Delta}(x_{0})} \frac{r(t, y_{h})(x_{0} - y_{h})}{\sqrt{|x_{0} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}} \, dy \right| < \delta,
\]
and
\[
v.p. \int_{B_{\Delta}(x_{0})} \frac{r(t, y_{h})(x_{h} - y_{h})}{|x_{h} - y_{h}|^{3}} \, dy_{h} < \delta.
\]
For this \(\Delta > 0\), using that
\[
\frac{1}{\sqrt{|x_{0} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}} - \frac{1}{|x_{0} - y_{h}|} \to 0 \quad \text{as} \quad \epsilon \to 0^{+}
\]
for any \(y_{h} \in \omega, 0 < x_{3}, y_{3} < 1\), except \(x_{0} = y_{h}\), we see that for above given \(\Delta > 0\), there exists \(\epsilon_{0} > 0\) such that for any \(0 < \epsilon \leq \epsilon_{0}\)
\[
\left| \int_{\Omega \setminus C_{\Delta}(x_{0})} \frac{\epsilon r(t, y_{h})(x_{h} - y_{h})}{\sqrt{|x_{h} - y_{h}|^{2} + \epsilon^{2}(x_{3} - y_{3})^{2}}} \, dy \right| < \delta - v.p. \int_{\omega \setminus B_{\Delta}(x_{0})} \frac{r(t, y_{h})(x_{h} - y_{h})}{|x_{h} - y_{h}|^{3}} \, dy_{h} < \delta.
\]
Whence (4.19).
Therefore we proved that

\[ |K_3 + R_9| \leq \delta \| \bar{U} - \bar{u}_\varepsilon \|_{L^\infty(\Omega;\mathbb{R}^3)} + C(\delta; r, \bar{V}, \Theta) \int_\Omega \mathcal{E}(\varphi_\varepsilon, \vartheta_\varepsilon | r, \Theta) \, dx + H_\varepsilon, \]

where \( H_\varepsilon = o(\varepsilon) \) as \( \varepsilon \to 0^+ \).

Plugging all the previous estimates into (3.8) we get

\[
\int_\Omega \left( \frac{1}{2} \varphi_\varepsilon |\bar{u}_\varepsilon - \bar{U}|^2 + \mathcal{E}(\varphi_\varepsilon, \vartheta_\varepsilon | r, \Theta) \right) \, dx
dt
\]

\[
+ \int_0^T \int_\Omega \left( \frac{\Theta}{\varphi_\varepsilon} \mathcal{S}(\varphi_\varepsilon, \nabla_\varepsilon \bar{u}_\varepsilon) : \nabla_\varepsilon \bar{u}_\varepsilon - \mathcal{S}(\Theta, \nabla_\varepsilon \bar{U}) : (\nabla_\varepsilon \bar{u}_\varepsilon - \nabla_\varepsilon \bar{U}) - \mathcal{S}(\varphi_\varepsilon, \nabla_\varepsilon \bar{u}_\varepsilon) : \nabla_\varepsilon \bar{U} \right) \, dx \, dt
\]

\[
\leq \int_0^T \left( \frac{1}{2} (\varphi_{0,\varepsilon} |\bar{u}_{0,\varepsilon} - \bar{U}(0, \cdot)|^2 + \mathcal{E}(\varphi_{0,\varepsilon}, \vartheta_{0,\varepsilon} | r(0, \cdot), \Theta(0, \cdot))) \right) \, dx + H_\varepsilon
\]

\[
+ \int_0^T \left[ \delta \| \bar{V} - \bar{u}_\varepsilon \|_{W^{1,2}(\Omega;\mathbb{R}^3)}^2 + C(\delta; r, \bar{V}, \Theta) \int_\Omega \left( \frac{1}{2} \varphi_\varepsilon |\bar{u}_\varepsilon - \bar{U}|^2 + \mathcal{E}(\varphi_\varepsilon, \vartheta_\varepsilon | r, \Theta) \right) \, dx \right] \, dt
\]

\[
+ \int_0^T \int_\Omega \left( \left( 1 - \frac{\Theta}{r} \right) (\partial_\varphi p(r, \Theta) + \bar{V} \cdot \nabla_\varepsilon p(r, \Theta)) \right) \, dx \, dt
\]

\[
- \int_0^T \int_\Omega \left( \partial_\varphi s(r, \Theta)(\varphi_\varepsilon - \Theta) + \partial_\varphi s(r, \Theta)(\vartheta_\varepsilon - \Theta) \right) \left( \partial_\varphi \Theta + \bar{V} \cdot \nabla_\varepsilon \Theta \right) \, dx \, dt,
\]

where \( H_\varepsilon \) is as above. We denote

\[ A := \int_\Omega (p(r, \Theta) - p(\varphi_\varepsilon, \vartheta_\varepsilon)) \text{div}_h \bar{V} \, dx + \int_\Omega \left( 1 - \frac{\Theta}{r} \right) \left( \partial_\varphi p(r, \Theta) + \bar{V} \cdot \nabla_\varepsilon p(r, \Theta) \right) \, dx
\]

\[
- \int_\Omega \left( \partial_\varphi s(r, \Theta)(\varphi_\varepsilon - \Theta) + \partial_\varphi s(r, \Theta)(\vartheta_\varepsilon - \Theta) \right) \left( \partial_\varphi \Theta + \bar{V} \cdot \nabla_\varepsilon \Theta \right) \, dx
\]

\[
= \int_\Omega (p(r, \Theta) - p(\varphi_\varepsilon, \vartheta_\varepsilon)) \text{div}_h \bar{V} \, dx + \int_\Omega \left( \Theta - \varphi_\varepsilon \right) \partial_\varphi s(r, \Theta)(\vartheta_\varepsilon - \Theta) \left( \partial_\varphi \Theta + \bar{V} \cdot \nabla_\varepsilon \Theta \right) \, dx
\]

\[
- \int_\Omega \left( r - \varphi_\varepsilon \right) \partial_\varphi p(r, \Theta) \text{div}_h \bar{V} \, dx,
\]

where we used the Gibbs (2.21) and Maxwell (1.10) relations and the continuity equation (2.39). The second term in the right-hand side rewrites as follows

\[
\int_\Omega \left( \Theta - \varphi_\varepsilon \right) \partial_\varphi s(r, \Theta)(\vartheta_\varepsilon - \Theta) \left( \partial_\varphi \Theta + \bar{V} \cdot \nabla_\varepsilon \Theta \right) \, dx
\]
In order to finish the proof, it remains to study carefully the terms in the left-hand side.

\[ \int_{\Omega} (\Theta - \vartheta) \left( \partial_x s(r, \Theta) + \vec{V} \cdot \nabla_h s(r, \Theta) \right) \, dx - \int_{\Omega} (\Theta - \vartheta) \partial_x p(r, \Theta) \text{div}_h \vec{V} \, dx \]

\[ = \int_{\Omega} (\Theta - \vartheta) \left[ \frac{1}{\Theta} \left( \bar{S}_h(\Theta, \nabla_h \vec{V}) : \nabla_h \vec{V} - \bar{\theta}_h(\Theta, \nabla_h \Theta) \cdot \nabla \Theta \right) \right] \, dx \]

\[- \int_{\Omega} (\Theta - \vartheta) \partial_x p(r, \Theta) \text{div}_h \vec{V} \, dx, \]

where we used the same identities as above, together with the entropy balance \[\text{(2.41)}.\] Hence

\[ A = \int_{\Omega} \left( p(\vartheta) - p(\vartheta_r, \vartheta) + \partial_x p(r, \Theta)(\vartheta_r - r) + \partial_x p(r, \Theta)(\vartheta - \Theta) \right) \text{div}_h \vec{V} \, dx \]

\[+ \int_{\Omega} (\Theta - \vartheta) \left[ \frac{1}{\Theta} \left( \bar{S}_h(\Theta, \nabla_h \vec{V}) : \nabla_h \vec{V} - \bar{\theta}_h(\Theta, \nabla_h \Theta) \cdot \nabla \Theta \right) \right] \, dx. \]

Observing that

\[ \left| \int_{\Omega} \left( p(r, \Theta) - p(\vartheta, \vartheta_r) + \partial_x p(r, \Theta)(\vartheta_r - r) + \partial_x p(r, \Theta)(\vartheta - \Theta) \right) \text{div}_h \vec{V} \, dx \right| \]

\[ \leq C \| \text{div}_h \vec{V} \|_{L^\infty(\Omega)} \int_{\Omega} \mathcal{E}(\vartheta, \vartheta; r, \Theta) \, dx, \]

we see that \[\text{(3.8)}\] reduces finally to

\[ \int_{\Omega} \left( \frac{1}{2} \vartheta_r |\vec{u}_r - \vec{U}|^2 + \mathcal{E}(\vartheta, \vartheta; r, \Theta) \right) (\tau, \cdot) \, dx \]

\[+ \int_0^\tau \int_{\Omega} \left( \frac{\Theta}{\vartheta_r} S(\vartheta_r, \nabla \vec{u}_r) : \nabla \vec{u}_r - S(\Theta, \nabla \vec{U}) : (\nabla \vec{u}_r - \nabla \vec{U}) - S(\vartheta, \nabla \vec{u}_r) : \nabla \vec{U} \right) \, dx \, dt \]

\[+ \int_0^\tau \int_{\Omega} \left( \frac{\Theta - \vartheta_r}{\Theta} \bar{S}_h(\Theta, \nabla_h \vec{V}) : \nabla_h \vec{V} \right) \, dx \, dt \]

\[+ \int_0^\tau \int_{\Omega} \left( \frac{\bar{\theta}_h(\Theta, \nabla_h \vartheta_r) \cdot \nabla \Theta}{\vartheta_r} - \frac{\Theta}{\vartheta_r} \bar{\theta}_h(\vartheta_r, \nabla \vartheta_r) \cdot \nabla \vartheta_r \right) \, dx \, dt \]

\[+ \int_0^\tau \int_{\Omega} \left( \left( \Theta - \vartheta_r \right) \frac{\bar{\theta}_h(\Theta, \nabla_h \vartheta_r) \cdot \nabla \Theta}{\Theta} + \frac{\bar{\theta}_h(\Theta, \vartheta_r) \cdot \nabla \vartheta_r \left( \vartheta - \Theta \right)}{\Theta} \right) \, dx \, dt \]

\[\leq \int_{\Omega} \left( \frac{1}{2} \vartheta_r |\vec{u}_r - \vec{U}(0, \cdot)|^2 + \mathcal{E}(\vartheta_0, \vartheta; r(0, \cdot), \Theta(0, \cdot)) \right) \, dx + H \]

\[+ \int_0^\tau \left[ \delta \| \vec{U} - \vec{u}_r \|^2_{W^{1,2}(\Omega; \mathbb{R}^3)} + C(\delta; r, \vec{V}, \Theta) \int_{\Omega} \mathcal{E}(\vartheta, \vartheta; r, \Theta) \, dx \right] \, dt. \]  

(4.20)

In order to finish the proof, it remains to study carefully the terms in the left-hand side.
4.3 Dissipative terms

We will consider more carefully only the terms with the stress tensor, referring to [10] for more details, especially in the case of the terms with the heat flux. In the spirit of [10], using the special structure of the stress tensor (see (2.16)), we can write

\[ S(\vartheta, \nabla \varepsilon \bar{u}) = S^0(\nabla \varepsilon \bar{u}) + S^1(\vartheta, \nabla \varepsilon \bar{u}), \]  
(4.21)

where

\[ S^0(\nabla \varepsilon \bar{u}) = \mu_0 \left( \nabla \varepsilon \bar{u} + (\nabla \varepsilon \bar{u})^T - \frac{2}{3} \text{div} \varepsilon \bar{u} I \right), \]

\[ S^1(\vartheta, \nabla \varepsilon \bar{u}) = \mu_1 \vartheta \left( \nabla \varepsilon \bar{u} + (\nabla \varepsilon \bar{u})^T - \frac{2}{3} \text{div} \varepsilon \bar{u} I \right). \]

Then

\[ \frac{\Theta}{\vartheta} S^1(\vartheta, \nabla \varepsilon \bar{u}) : \nabla \varepsilon \bar{u} - S^1(\Theta, \nabla \bar{U}) : (\nabla \varepsilon \bar{u} - \nabla \bar{U}) - S^1(\vartheta, \nabla \varepsilon \bar{u}) : \nabla \bar{U} \]

\[ + \left( \frac{\vartheta - \Theta}{\Theta} S^1(\vartheta, \nabla \bar{V}) : \nabla \bar{V} \right) \]

\[ = \Theta \left( \frac{S^1(\vartheta, \nabla \varepsilon \bar{u})}{\vartheta} - \frac{S^1(\Theta, \nabla \bar{U})}{\Theta} \right) : (\nabla \varepsilon \bar{u} - \nabla \bar{U}) \]

\[ + (\Theta - \vartheta) \left( \frac{S^1(\vartheta, \nabla \varepsilon \bar{u})}{\vartheta} - \frac{S^1(\Theta, \nabla \bar{U})}{\Theta} \right) : \nabla \varepsilon \bar{U}. \]

In the first term we use the Korn inequality and we split the second term to the essential and the residual parts. As above, we get bounds

\[ \left| \int_\Omega (\Theta - \vartheta) \left( \frac{S^1(\vartheta, \nabla \varepsilon \bar{u})}{\vartheta} - \frac{S^1(\Theta, \nabla \bar{U})}{\Theta} \right) : \nabla \varepsilon \bar{U} \, dx \right| \]

\[ \leq \delta \|\bar{u} - \bar{U}\|_{W^{1,2}(\Omega;\mathbb{R}^3)}^2 + C(\delta) \int_\Omega E(\vartheta, \vartheta| r, \Theta) \, dx. \]

The part of the stress tensor containing \( S^0 \) can be rewritten in the following way. First, for \( 0 < \Theta \leq \vartheta \)

\[ \frac{\Theta}{\vartheta} S^0(\nabla \varepsilon \bar{u}) : \nabla \varepsilon \bar{u} - S^0(\nabla \bar{U}) : (\nabla \varepsilon \bar{u} - \nabla \bar{U}) - S^0(\nabla \varepsilon \bar{u}) : \nabla \bar{U} \]

\[ + \frac{\vartheta - \Theta}{\Theta} S^0(\nabla \bar{V}) : \nabla \bar{V} \]

\[ \geq \frac{\Theta}{\vartheta} \left( S^0(\nabla \varepsilon \bar{u}) - S^0(\nabla \bar{U}) \right) : \nabla \varepsilon \bar{u} - \bar{U} + \Theta \left( \frac{1}{\vartheta} - \frac{1}{\Theta} \right) S^0(\nabla \bar{U}) : \nabla \varepsilon \bar{u} - \bar{U} \]

\[ + \frac{\vartheta - \Theta}{\vartheta} \left( S^0(\nabla \bar{U}) - S^0(\nabla \varepsilon \bar{u}) \right) : \nabla \varepsilon \bar{U}. \]
As $\frac{1}{2} \leq \frac{1}{3}$, the last two terms can be, after integrating over $\Omega$, estimated by

$$\delta \| \vec{u}_e - \vec{U} \|^2_{W^{1,2}(\Omega; \mathbb{R}^3)} + C(\delta) \int_\Omega \mathcal{E}(\varrho_e, \vartheta_e | r, \Theta) \, dx.$$ 

Next, for $0 < \vartheta_e \leq \Theta$,

$$\frac{\Theta}{\vartheta_e} S^0(\nabla_e \vec{u}_e) : \nabla_e \vec{u}_e - S^0(\nabla_e \vec{U}) : (\nabla_e \vec{u}_e - \nabla_e \vec{U}) - S^0(\nabla_e \vec{u}_e) : \nabla_e \vec{U}$$

$$+ \frac{\theta_e - \Theta}{\Theta} S^0(\nabla_h \vec{V}) : \nabla_h \vec{V}$$

$$\geq (S^0(\nabla_e \vec{u}_e) - S^0(\nabla_e \vec{U})) : \nabla_e (\vec{u}_e - \vec{U}) + \frac{\theta_e - \Theta}{\Theta} (S^0(\nabla_e \vec{u}_e) : \nabla_e \vec{u}_e - S^0(\nabla_h \vec{V}) : \nabla_h \vec{V}).$$

As $\nabla_e \vec{u}_e \mapsto S^0(\nabla_e \vec{u}_e) : \nabla_e \vec{u}_e$ is convex, we have

$$\frac{\Theta}{\vartheta_e} S^0(\nabla_e \vec{u}_e) : \nabla_e \vec{u}_e - S^0(\nabla_e \vec{V}) : \nabla_e \vec{V} \geq \frac{\Theta}{\Theta} S^0(\nabla_e \vec{U}) \geq \frac{\Theta}{\Theta} S^0(\nabla_e \vec{U}) \geq \nabla_e (\vec{u}_e - \vec{U}).$$

After integration over $\Omega$, this term can be controlled on the right-hand side by

$$\delta \| \vec{u}_e - \vec{U} \|^2_{W^{1,2}(\Omega; \mathbb{R}^3)} + C(\delta) \int_\Omega \mathcal{E}(\varrho_e, \vartheta_e | r, \Theta) \, dx.$$ 

Therefore, summing up,

$$\int_\Omega \left( \frac{1}{2} \varrho_e | \vec{u}_e - \vec{U} |^2 + \mathcal{E}(\varrho_e, \vartheta_e | r, \Theta) \right) (\tau, \cdot) \, dx + k_1 \int_0^T \int_\Omega | \nabla_e \vec{u}_e - \nabla_e \vec{U} |^2 \, dx \, dt$$

$$+ \int_0^T \int_\Omega \left( \frac{\bar{q}(\varrho_e, \vartheta_e)}{\varrho_e} \nabla \Theta : \nabla \varrho_e + \bar{q}_h(\Theta, \nabla \Theta) \cdot \nabla h + \bar{q}_h(\Theta, \nabla \Theta) \cdot \nabla (\varrho_e - \Theta) \right) \, dx \, dt$$

$$\leq \int_0^T \int \left( \frac{1}{2} \left( \varrho_0 | \vec{u}_0 - \vec{U} |(0, \cdot) |^2 + \mathcal{E}(\varrho_0, \vartheta_e | r(0, \cdot), \Theta(0, \cdot)) \right) \, dx \right. +$$

$$+ \int_0^T \left[ \delta \| \vec{U} - \vec{u}_e \|^2_{W^{1,2}(\Omega; \mathbb{R}^3)} + C(\delta; r, \vec{V}, \Theta) \int_\Omega \mathcal{E}(\varrho_e, \vartheta_e | r, \Theta) \, dx \right] \, dt.$$

For the terms connected with the heat conductivity, we proceed exactly as in [10]. We arrive at the following inequality

$$\int_\Omega \left( \frac{1}{2} \varrho_e | \vec{u}_e - \vec{U} |^2 + \mathcal{E}(\varrho_e, \vartheta_e | r, \Theta) \right) (\tau, \cdot) \, dx + k_1 \int_0^T \int_\Omega | \nabla_e \vec{u}_e - \nabla_e \vec{U} |^2 \, dx \, dt$$

$$+ k_2 \int_0^T \int_\Omega | \nabla \varrho_e - \nabla \Theta |^2 \, dx \, dt + k_3 \int_0^T \int_\Omega | \nabla \log \varrho_e - \nabla \log \Theta |^2 \, dx \, dt$$

$$\leq \int_\Omega \left( \frac{1}{2} \left( \varrho_0 | \vec{u}_0 - \vec{U} |(0, \cdot) |^2 + \mathcal{E}(\varrho_0, \vartheta_e | r(0, \cdot), \Theta(0, \cdot)) \right) \, dx \right) + H_e.$$
\[ + k_j \int_0^T \int_{\Omega} \left( \frac{1}{2} \rho_\varepsilon |\vec{u}_\varepsilon - \vec{U}|^2 + \mathcal{E}(\rho_\varepsilon, \vartheta_\varepsilon |r, \Theta) \right) \, dx \, dt, \quad (4.23) \]

where the positive constants \( k_j \) depend on \((r, \vec{V}, \Theta)\) through the norms involved in Theorem 2.1, and \( H_\varepsilon \to 0 \) as \( \varepsilon \to 0^+ \). This inequality, after application of the Gronwall lemma, finishes the proof of Theorem 2.1.

**Acknowledgement:** Bernard Ducomet is partially supported by the ANR project IN-FAMIE (ANR-15-CE40-0011). Šárka Nečasová and Matteo Caggio acknowledge the support of the GAČR (Czech Science Foundation) project No. 16-03230S in the framework of RVO: 67985840. Part of article was written during stay of Šárka Nečasová at CEA. She would like to thank to Prof. Ducomet for his hospitality. The work of Milan Pokorný was supported by the GAČR (Czech Science Foundation) project No. 16-03230S.

**References**

[1] P. Bella, E. Feireisl, A. Novotný, Dimensional reduction for compressible viscous fluids. Acta Appl. Math., 134 (2014) 111–121.

[2] A. R. Choudhuri, *The physics of fluids and plasmas, an introduction for astrophysicists*. Cambridge University Press, 1998.

[3] C. M. Dafermos, The second law of thermodynamics and stability. *Arch. Rational Mech. Anal.*, 70 (1979) 167–179.

[4] R. J. DiPerna, P.-L. Lions, Ordinary differential equations, transport theory and Sobolev spaces. *Invent. Math.*, 98 (1989) 511–547.

[5] B. Ducomet, E. Feireisl, Š. Nečasová. On a model of radiation hydrodynamics. *Ann. I. H. Poincaré-AN*, 28 (2011) 797–812.

[6] B. Ducomet, E. Feireisl, H. Petzeltová, I. Straškraba, Global in time weak solutions for compressible barotropic self-gravitating fluids. *Discrete and Continuous Dynamical Systems*, 11 (2004) 113–130.

[7] E. Feireisl, *Dynamics of viscous compressible fluids*. Oxford, Oxford University Press, 2001.

[8] E. Feireisl, B. J. Jin, A. Novotný, Relative entropies, suitable weak solutions, and weak-strong uniqueness for the compressible Navier-Stokes system. *J. Math. Fluid Mech.*, 14 (2012) 717–730

[9] E. Feireisl, A. Novotný, *Singular limits in thermodynamics of viscous fluids*. Birkhäuser, Basel, 2009.

[10] E. Feireisl, A. Novotný, Weak Strong Uniqueness Property for the Full Navier Stokes Fourier System. *Arch. Rational Mech. Anal.*, 204 (2012) 683–706.

[11] E. Feireisl, A. Novotný, Y. Sun, Suitable weak solutions to the Navier-Stokes system of compressible viscous fluids. *Indiana Univ. Math. J.*, 60 (2011) 611–631.
[12] E. Feireisl. On the motion of a viscous, compressible, and heat conducting fluid. Indiana Univ. Math. J., 53 (2004) 1707–1740.

[13] P. Germain, Weak-strong uniqueness for the isentropic compressible Navier-Stokes system. J. Math. Fluid Mech., 13 (2011) 137–146.

[14] O. Kreml, Š. Nečasová, M. Pokorný, On the steady equations for compressible radiative gas. Z. Angew. Math. Phys., 64 (2013) 539–571.

[15] D. Maltese, A. Novotný, Compressible Navier-Stokes equations in thin domains. J. Math. Fluid Mech., 16 (2014) 571–594.

[16] D. Matsumura, T. Nishida, Initial boundary value problems for the equations of motion of compressible viscous and heat-conductive fluid. Commun. Math. Phys., 89 (1983) 445–464.

[17] A. Mellet, A. Vasseur, Existence and uniqueness of global strong solutions for one-dimensional compressible Navier-Stokes equations. SIAM J. Math. Anal., 39 (2007) 1344–1365.

[18] A. Montesinos Armijo, Review: Accretion disk theory, ArXiv:1203.685v1 [astro-ph.HE] 30 Mar 2012.

[19] A. Novotný, M. Pokorný, Steady compressible Navier-Stokes-Fourier system for monoatomic gas and its generalizations, J. Differential Equations, 251 (2011) 270–315.

[20] G. I. Ogilvie, Accretion disks, In: Fluid dynamics and dynamos in astrophysics and geophysics, A.M. Soward, C.A. Jones, D.W. Hughes, N.O. Weiss Eds., pp.1–28, CRC Press, 2005.

[21] A. Pierens, L’autogravité dans les disques astrophysiques, PhD. Dissertation, Université Pierre et Marie Curie-Paris VI, 2005.

[22] J. E. Pringle, Accretion disks in astrophysics. Ann. Rev. Astron. Astrophys., 19 (1981) 137–162.

[23] L. Saint-Raymond, Hydrodynamic limits: some improvements of the relative entropy method. Ann. I. H. Poincaré-AN, 26 (2009) 705–744.

[24] S.N. Shore, An introduction to astrophysical hydrodynamics. Academic Press, 1992.

[25] A. Tani, On the first initial-boundary value problem of compressible viscous fluid motion, Publ. RIMS. Kyoto Univ. 13, (1977) 193–253.