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Deciphering solar turbulence from sunspots records

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ABSTRACT

It is generally believed that sunspots are the emergent part of magnetic flux tubes in the solar interior. These tubes are created at the base of the convection zone and rise to the surface due to their magnetic buoyancy. The motion of plasma in the convection zone being highly turbulent, the surface manifestation of sunspots may retain the signature of this turbulence, including its intermittency. From direct observations of sunspots, and indirect observations of the concentration of cosmogenic isotopes $^{14}$C in tree rings or $^{10}$Be in polar ice, power spectral densities in frequency are plotted. Two different frequency scalings emerge, depending on whether the Sun is quiescent or active. From direct observations we can also calculate scaling exponents. These testify to a strong intermittency, comparable with that observed in the solar wind.

Key words: magnetic fields – MHD – plasmas – turbulence – sunspots.

1 INTRODUCTION

Sunspots observed at the surface of the convection zone of the Sun are usually understood as the manifestation of solar magnetic activity. Naked-eye and telescope observations of sunspots are available from AD 1610, providing reliable records of sunspot numbers (SSN). Several sets of data exist, varying in how they have been sampled, averaged (daily or monthly), whether they concern sunspots or sunspot groups and on the scientific societies who have compiled the records. Here we consider the American daily SSN (D),1 the American daily group SSN (G)2 and the International monthly averaged SSN (M)3 (Fig. 1). In addition SSN at earlier times have been reconstructed from proxies, based on the concentration of cosmogenic isotopes $^{14}$C in tree rings4 or $^{10}$Be in ice core bubbles. The production rate of such isotopes increases with the cosmic ray flux, which is higher when the solar magnetic activity is low. Plotting the SSN versus time reveals a cycle of about 11 yr known as the Schwabe cycle. This cyclical solar magnetic activity is sufficiently robust to be detected in $^{10}$Be concentration records, even during some long periods with almost no visible sunspots, like the Maunder minimum (1645–1715) (Beer, Tobias & Weiss 1998). Analysing long time series of $^{14}$C and $^{10}$Be, it has been shown that the solar activity of the last 70 yr has been exceptionally high (Usoskin et al. 2003; Solanki et al. 2004), and that a decline is expected within the next two or three cycles (Abreu et al. 2008).

The occurrence of sunspots is of course an important diagnostic that must be reproduced by any solar dynamo model. The fact that it is irregular (in spite of the Schwabe cycle) reflects the complexity inherent in the non-linear coupling between the turbulent flow and the magnetic field in the solar convection zone (Browning et al. 2006). With the long time series of direct SSN observations and $^{14}$C and $^{10}$Be data available, it is tempting to calculate the corresponding frequency spectra, to infer some signature of the underlying turbulence in the convection zone. Similar attempts have been made for the Earth (Courtillot & Le Mouel 1988; Constable & Johnson 2005; Sakuraba & Hamano 2007); the frequency spectrum of the geomagnetic dipole moment obtained from paleomagnetic data is consistent with an inertial range of $f^{-5/3}$ scaling, and a dissipation range of $f^{-11/3}$ as expected in magnetohydrodynamic turbulence (Alemany et al. 2000). For the Sun, analysis of International daily SSN have led to a $f^{-2/3}$ scaling (Moffet et al. 1991; Lawrence, Cadavid & Ruzmaikin 1995), and this has been attributed to some sequential sampling of the field upon arrival at the photosphere on top of a Kolmogorov spatial scaling due to the underlying turbulence. Here we extend this analysis to the other SSN records mentioned above and test how robust the $f^{-2/3}$ scaling is, in particular during minima and maxima of sunspot activity. In addition, for time-scales smaller than 2 yr, the stochastic character of the SSN records suggests strong intermittency (Lawrence et al. 1995), as opposed to a low-dimensional chaotic interpretation. We shall characterize this intermittency by calculating the corresponding scaling exponents.

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3 http://solarscience.msfc.nasa.gov/greenwch/spot_num.txt
4 ftp://ftp.ncdc.noaa.gov/pub/data/paleo/climate_forcing/solar_variability/solanki2004-ssn.txt

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In order to filter out the noise, we use a wavelet decomposition of the signal. In Fig. 2, the wavelet coefficients are plotted versus time (in years) and frequency (in month$^{-1}$). The light (resp. dark) colours correspond to low (resp. high) values of these coefficients. For a given year, the curve giving the wavelet coefficient versus frequency corresponds to a power spectral density (PSD) of the signal. The dark horizontal stripe for $f \sim 0.01$ month$^{-1}$ corresponds to the Schwabe cycle. It is not visible in the $^{14}$C data set due to the coarse sampling of this data (averaged over 10 yr). On the other hand a clear dark stripe is visible for $f \sim 3.5 \times 10^{-3}$ month$^{-1}$, corresponding to a $\sim 2400$ yr cycle. In the figure for $M$ data the dark stripe of the Schwabe cycle almost disappears during the Dalton minimum (1790–1820) (Frick et al. 1997). In the $G$ and $D$ data figures we identify another horizontal stripe at $f \sim 1$ month$^{-1}$, corresponding to the solar mean rotation rate. This indicates that the latitudinal repartition of sunspots is not homogeneous.
Finally, the vertical light stripes correspond to minima of magnetic activity.

The time average of the wavelet coefficients is shown in Fig. 3 (top) for the five data sets. As mentioned earlier the two peaks around 0.01 and 1 month$^{-1}$ correspond to the Schwabe cycle and solar mean rotation rate. Between them the three spectra of the directly observed SSN (M, G, D) present a common scaling in $f^{-2/3}$. The other data sets $^{14}$C and $^{10}$Be are compatible with a $f^{-2/3}$ scaling as well, although the $^{14}$C PSD is overestimated by roughly a factor of 10, probably due to the proxy used in the reconstruction of the SSN from the $^{14}$C data.

For the three data sets (M), (G) and (D), instead of averaging on all times, we now average on periods corresponding to either maximum or minimum magnetic activity as shown in Fig. 4. For the maximum (resp. minimum) activity subset, the excluded data are that centred around the times of the Schwabe minima (resp. maxima). The corresponding spectral densities are plotted in Fig. 3 (bottom).

The slopes for minima are systematically steeper than those for maxima, indicating two different regimes. To estimate these slopes we vary both the range of frequency $[f_{\text{min}}, f_{\text{max}}]$ on which they are calculated, and the way the data sets are split into subsets of maximum and minimum activity. For the former we take $f_{\text{max}} = 0.7$ month$^{-1}$ for the data sets (G) and (D) in order to escape from the influence of the peak $f = 1$ month$^{-1}$, and $f_{\text{max}} = 0.5$ month$^{-1}$ for the data set (M). When changing $f_{\text{min}}$ the slopes change. We vary $f_{\text{min}}$ such that the ratio $f_{\text{max}} / f_{\text{min}}$ is about 10, and the standard deviation of the slope remains 10 per cent or less of its average value. This leads to $f_{\text{min}} \in [0.05, 0.07]$ for (G), $f_{\text{min}} \in [0.06, 0.08]$ for (D) and $f_{\text{min}} \in [0.03, 0.05]$ for (M). In addition we consider at least three different degrees of splitting for each data set, this splitting degree being related to the time length of the subsets of maximum and minimum activity. The choices of this splitting degree are made such that both subsets are long enough to provide good statistics, but remain separated by sufficient time lags that the SSN values falling into each subset do not overlap too much. Then for both the maximum and minimum subsets, we calculate the mean slope and the standard deviation obtained when varying both the frequency range and the degree of splitting of each data set (into the two subsets of maximum and minimum magnetic activity).

The corresponding spectral densities are plotted in Fig. 3 (bottom).

The slopes for minima are systematically steeper than those for maxima, indicating two different regimes. To estimate these slopes we vary both the range of frequency $[f_{\text{min}}, f_{\text{max}}]$ on which they are calculated, and the way the data sets are split into subsets of maximum and minimum activity. For the former we take $f_{\text{max}} = 0.7$ month$^{-1}$ for the data sets (G) and (D) in order to escape from the influence of the peak $f = 1$ month$^{-1}$, and $f_{\text{max}} = 0.5$ month$^{-1}$ for the data set (M). When changing $f_{\text{min}}$ the slopes change. We vary $f_{\text{min}}$ such that the ratio $f_{\text{max}} / f_{\text{min}}$ is about 10, and the standard deviation of the slope remains 10 per cent or less of its average value. This leads to $f_{\text{min}} \in [0.05, 0.07]$ for (G), $f_{\text{min}} \in [0.06, 0.08]$ for (D) and $f_{\text{min}} \in [0.03, 0.05]$ for (M). In addition we consider at least three different degrees of splitting for each data set, this splitting degree being related to the time length of the subsets of maximum and minimum activity. The choices of this splitting degree are made such that both subsets are long enough to provide good statistics, but remain separated by sufficient time lags that the SSN values falling into each subset do not overlap too much. Then for both the maximum and minimum subsets, we calculate the mean slope and the standard deviation obtained when varying both the frequency range and the degree of splitting of each data set (into the two subsets of maximum and minimum magnetic activity).

Table 1. Slope estimates for the PSD curves plotted in Fig. 3 (bottom). They correspond to average values plus standard deviation errors when varying both the frequency range and the degree of splitting of each data set (into the two subsets of maximum and minimum magnetic activity).

| Activity | (M) | (G) | (D) |
|----------|-----|-----|-----|
| Max.     | $-0.61 \pm 0.05$ | $-0.69 \pm 0.05$ | $-0.63 \pm 0.05$ |
| Min.     | $-1.03 \pm 0.03$ | $-0.94 \pm 0.07$ | $-0.98 \pm 0.02$ |
formal standard errors from each of the individual regressions (for specific frequency ranges and degrees of splitting) are of comparable magnitude.

As noted by Lawrence et al. (1995), the question of causality complicates the interpretation of such temporal data. The difference of spectral slopes between minima and maxima can be attributed to two different effects: a change of the underlying turbulence, affecting the spatial structure the magnetic field; or a change in the frequency of the sequential sampling of the magnetic field, as suggested by Lawrence et al. (1995). Although the latter effect cannot be excluded, there is a simple argument in favour of the former. It is generally accepted that the occurrence of sunspots at the photosphere is due to the magnetic buoyancy force $\nabla B^2$, where $B$ is some magnetic induction intensity in the convection zone (Tobias et al. 2001). It is then tempting to interpret the two spectral slopes as the signatures of this buoyancy, assuming that the frequency of sunspot occurrence at the photosphere is proportional to this force. Then the $f^{-2/3}$ and $f^{-1}$ SSN spectra would correspond to buoyancy spectra of $k^{-2/3}$ and $k^{-1}$, where $k$ is the spatial wavenumber. During maxima this implies a Kolmogorov magnetic energy spectrum of $k^{-5/3}$, compatible with inertia-driven turbulence in the convection zone. During minima it implies a magnetic energy spectrum of $k^{-2}$, compatible with turbulence dominated by the solar rotation (Zhou 1995). In the transport scenario proposed by Tobias et al. (2001), the field which arises at the surface is the strongest part of a poloidal field generated by cyclonic turbulence in the convection zone. Our interpretation then suggests two different regimes for such cyclonic turbulence, controlled by either inertia or rotation.

3 INTERMITTENCY

The stochastic nature of SSN occurrence for times scales smaller than 2 yr has been shown by Lawrence et al. (1995), suggesting an intermittent turbulence. Here our goal is to quantify this intermittency for the three sets (M, G, D), calculating the corresponding scaling exponents. For that we first calculate the associated generalized structure function (GSF) and look for its scaling exponents, as usually done in turbulence. We define the SSN increment by

$$ \delta y(t, \tau) = S(t+\tau) - S(t), $$

where $S(t)$ denotes the SSN at time $t$. Assuming statistical stationarity in the frequency range of interest, the $\tau$ dependence in $\delta y(t, \tau)$ can be dropped and the GSF is then given by (Nicol, Chapman & Dendy 2008)

$$ S_m(\tau) = \langle |\delta y|^m \rangle = \int_{-\infty}^{\infty} |\delta y|^m P(\delta y, \tau) d(\delta y), $$

where $P$ is the probability density function (PDF) of $\delta y$, the angle brackets $\langle \cdot \rangle$ denote time averaging and $m$ is a positive integer.

In Fig. 5, PDFs for the three data sets (M, G, D) are plotted for selected values of $\tau$. The PDFs of the $^{14}$C data are poorly defined, and so we drop this data set for the rest of the study. The PDFs of the other data sets show peaks at $\tau = 11/2/yr$, corresponding to the Schwabe cycle. For other values of $\tau$ they exhibit tails containing a higher number of rare events than for a Gaussian distribution, suggesting intermittency. Similar results were shown in Lawrence et al. (1995).

To quantify this intermittency we first check whether the GSF obey a scaling law in the form

$$ S_m(\tau) \sim \tau^{m/3}. $$

We find (not shown) that this is clearly the case. In homogeneous and isotropic fully developed turbulence, intermittency corresponds to $\xi(m) < \xi(3)/3$. The ratio $\xi(m)/\xi(3)$ is calculated, estimating the scaling power of $S_m(\tau)/S(3)$. Plotting the ratio $\xi(m)/\xi(3)$ versus $m$ for the three data sets (Fig. 6) we see a clear departure from the Kolmogorov straight line $\xi(m)/\xi(3) = m/3$, and clear indications of intermittency. It is remarkable that the (D) set, which has the best sampling, leads to the largest intermittency. It is also remarkable that the (M) and (G) sets lead to similar scaling exponents, supporting the equivalence between averaging over space and time.
The exponents can be fitted to the standard $p$-model derived for hydrodynamic (Meneveau & Sreenivasan 1987) and magnetohydrodynamic turbulence (Carbone 1993). This model is defined by

$$\zeta(m) = 1 - \log_2\left[p^{m/3} + (1 - p)^{m/3}\right]. \quad (4)$$

We find $p(G) = 0.68$, $p(M) = 0.68$ and $p(D) = 0.83$. The last value compares surprisingly well with those for the solar wind measured by the Ulysses spacecraft (Pagel & Balogh 2002; Nicol et al. 2008), and for the magnetospheric cusp measured by the Polar satellite (Yordanova et al. 2004), even though the frequencies differ by several orders of magnitude.

4 SUMMARY

In conclusion, the wavelet spectral analysis of sunspot records has revealed two different behaviors, depending on whether the Sun is quiescent or active. This suggests two different kinds of turbulence in the convection zone, controlled either by inertia or by rotation. The signature of such fully developed turbulence is confirmed by the calculation of the GSF scaling exponents, which indicate strong intermittency.

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