Two Empirical Regimes of the Planetary Mass-Radius Relation

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Abstract

Today, with the large number of detected exoplanets and improved measurements, we can reach the next step of planetary characterization. Classifying different populations of planets is not only important for our understanding of the demographics of various planetary types in the galaxy, but also for our understanding of planet formation. We explore the nature of two regimes in the planetary mass-radius (M-R) relation. We suggest that the transition between the two regimes of "small" and "large" planets, occurs at a mass of 124 ± 7, \(M_\oplus\) and a radius of 12.1 ± 0.5, \(R_\oplus\). Furthermore, the M-R relation is \(R \propto M^{0.55 \pm 0.02}\) and \(R \propto M^{0.01 \pm 0.02}\) for small and large planets, respectively. We suggest that the location of the breakpoint is linked to the onset of electron degeneracy in hydrogen, and therefore, to the planetary bulk composition. Specifically, it is the characteristic minimal mass of a planet which consists of mostly hydrogen and helium, and therefore its M-R relation is determined by the equation of state of these materials. We compare the M-R relation from observational data with the one derived by population synthesis calculations and show that there is a good qualitative agreement between the two samples.

1 Introduction

Exoplanet studies have now reached the level at which planet characterization is possible. There are hundreds of planets with measured masses and radii. Knowledge of these two
physical properties provides valuable clues about the planetary composition, through the mass-radius (hereafter M-R) relationship. Traditionally, planets have been divided into two main groups. The first includes the massive, gas-dominated planets, while the second consists of the small, terrestrial planets (e.g., Weidenschilling 1977). In part, this division is inspired by the Solar System, where massive planets are composed of volatile materials (e.g., Jupiter) while the terrestrial planets are small and consist of refractory materials. However, the diversity in masses and radii of exoplanets\(^\text{1}\) has taught us that this separation is somewhat arbitrary and may be over-simplistic (see review by Baraffe et al. 2014 and references therein).

While the first detected exoplanets had relatively large masses and radii, in the recent few years the number of small exoplanets increased dramatically, due to improvements in technology and detections from space (e.g., CoRoT (Baglin et al. 2006) and Kepler (Borucki et al. 2010)). Of course, since most exoplanets have been detected via radial velocity measurements or transits, there is a difference when defining a "small planet" by mass or by radius. In terms of mass, it is customary to define small planets as planets whose masses are less than \(\sim 30M_\oplus\) (Mayor et al. 2011, Howard et al. 2010), while in terms of radius, small exoplanets are often those whose radii are smaller than \(4R_\oplus\) (e.g., Marcy et al. 2014, Weiss & Marcy 2014). These divisions are partially based on the behavior of the planetary mass function of exoplanets.

Previous studies that examined the M-R relation have suggested a transition in the M-R relation between 'small' planets (Neptune-like) and 'large' planets (Jovian). Based on visual estimates of the M-R and mass-density relations, Weiss et al. (2013) suggested that the transition point occurs at a mass of \(\sim 150M_\oplus\). The derived slopes of the M-R relations in the different regimes turned out to be \(R \propto M^{0.54}\) for \(M_p < 150M_\oplus\) and \(R \propto M^{-0.039}\) for massive planets \((M_p > 150M_\oplus)\). Hatzes & Rauer (2015) have analyzed changes in the slope of the mass-density relation. Using a similar slope criterion, they locate the breakpoint at a mass of \(\sim 0.3M_J \approx 95M_\oplus\). In a recent study, Chen & Kipping (2017) presented a detailed forecasting model built upon a probabilistic M-R relation using MCMC. According to their classification the transition between small and large planets occurs at \(0.41 \pm 0.07M_J \approx 130 \pm 22M_\oplus\), corresponding to the transition between Neptunians and Jovians, with slopes of \(R \propto M^{0.59}\) and \(R \propto M^{-0.04}\) for the low-mass and high-mass planets, respectively. Interestingly, although the studies do not agree exactly on the transition mass between the two regimes, they do agree that it is significantly higher than the traditional cutoff at \(20-30M_\oplus\). This essentially suggests that the change in the occurrence rate as seen in the mass function of exoplanets (at

\(^\text{1}\)See \url{http://exoplanets.org} for exoplanet properties.
∼ 30M⊕), i.e., the frequency of planets is not the same as the behavior of the M-R relation, which is linked to the planetary composition.

In this paper we present the results of a study we performed in order to empirically characterize the transition point between small and large planets based on their M-R relation. On the one hand our aim was to perform a quantitative straightforward study, that will come up with simple numerical information – the two M-R power law indices, and the transition mass.  On the other hand, we opted for a kind of least-square fit, and not an elaborate probabilistic recipe. Our hope was that this would allow a more intuitive yet rigorous characterization of the planetary M-R relation. Finally, we also compare the exoplanet population to formation models and find a qualitative good agreement.

2 Sample

The data we use include only planets with masses and radii that are based directly on the observations, as opposed to being inferred from planetary physics models. Our sample consists of 274 exoplanets queried from http://exoplanets.org on March 2016. The lowest mass planet in our sample is Kepler-138b, with a mass of 0.0667 ± 0.0604M⊕, well below Earth mass. The highest planet mass in our sample is that of CoRoT-3b, with a mass of 6945 ± 315M⊕ (= 21.85 ± 0.99MJ) – a brown dwarf. For all the planets our sample must include measured masses, radii, and their uncertainties. Thus, we exclude planets with reported masses estimated based on a theoretical M-R relation. All planets in the sample are transiting planets, whose masses have been measured either by RV (238 through RV follow-up, and 9 were first detected by RV), or using TTVs (e.g. Nesvorný & Morbidelli 2008; 27 planets)\textsuperscript{2} The top panel of Fig. 1 shows the resulting M-R diagram\textsuperscript{3}.

3 Analysis

The model we assume is that of two mass regimes that differ by the M-R power law. In the log-log plane, this translates into a continuous piecewise linear function, with two segments, that we had to fit to the data points. In spite of our ambition to apply the most basic techniques of simple regression to perform this fit, several problems conspire to turn this into a somewhat more complicated problem.

\textsuperscript{2}It should be noted that almost all the TTV planets are of low mass

\textsuperscript{3}The list of the planets we use is summarized in Table 2 in the online version.
First, the two variables – the planetary mass and radius – are both measured with non-negligible errors. If we could assume that only one of them (e.g. the mass) had errors, the problem could have been treated as a standard regression problem. The fact that uncertainties exist for both variables, takes us to the field of ‘errors-in-variables’ (EIV) problems, which are surprisingly more difficult than standard regression problems (e.g. Durbin 1954), and there is not one agreed approach to analyze them.

As difficult as EIV problems are, in our case the complexity is even exacerbated by the fact that we aim to fit not a linear function, but a continuous piecewise-linear function, rendering futile any hope to solve the problem analytically. Even under the assumptions of standard regression, where the so-called explanatory variable has no uncertainty, the problem (dubbed ‘segmented regression’) is not trivial (e.g. Hinkley 1969).

Another difficulty arises because of the nature of our specific sample. A glance at the top panel of Figure 1 reveals that the data points are not scattered evenly across the logarithmic mass range. The points corresponding to the smaller planets seem to be much more sparse than those of the Jovian planets. The same is true for the very large planets, with masses of a few Jupiter’s mass. One may say that there seem to be three mass intervals with varying density of sample points. The origin of this differentiation lies beyond the scope of this study, and in any case it may very well be a combination of observational bias and astrophysical processes of formation and evolution. The smaller number of massive planets (above a Jupiter-mass) is a result of the low occurrence rate of such planets (e.g., Cumming et al. 2008), while the clustering of small is probably a result of the massive efforts to detect low-mass planets and their high occurrence rate (e.g., Howard et al. 2012).

There are various reasons for this sampling variability, ranging from observational biases to physical effects related to planet formation and evolution. However, the fact remains that for the purposes of regression analysis, the mass affects the sampling. In regression theory this amounts to ‘endogenous sampling’. While fitting a simple straight line might be affected only slightly by this imbalanced sampling, it is not guaranteed for a piecewise-linear function. Any fitting procedure should take this imbalance into consideration.

To streamline the discussion, let us denote:

\[ x = \log M_p \]
\[ y = \log R_p \]

The choice of logarithm base is irrelevant as long as it consistent throughout the calculation. Eventually the values in linear scale are the important ones, not in logarithm scale. Now our sample, in the log-log plane, consists of a set of ordered pairs \((x_i, y_i)\). Let us further denote
by $\Delta x_i$ and $\Delta y_i$ the corresponding logarithmic uncertainties derived from the uncertainties in the linear scale using the standard transformation. In cases where the transformation led to asymmetric uncertainties, we still assigned symmetric errors, by taking the more conservative (larger error) of the two error estimates.

In our quest for the best-fit piecewise-linear function, we chose what is probably the most intuitive approach to EIV: Total Least Squares – TLS (e.g. Markovsky et al. 2010). Similarly to standard regression, in TLS the problem is represented as a minimization problem of a sum of squares. Each data point contributes to the total sum-of-squares its orthogonal distance from the fitted line, measured in units of the two uncertainties. In the simple case where we fit a simple linear function, if we denote the slope and intercept of the line by $a$ and $b$, the contribution of the point $(x_i, y_i)$ would be:

$$\frac{(y_i - ax_i - b)^2}{a^2(\Delta x_i)^2 + (\Delta y_i)^2},$$

where $\Delta x_i$ and $\Delta y_i$ are the errors of $x_i$ and $y_i$. Golub (1973), and Golub & Van Loan (1980) were the first to introduce an algorithm to solve this basic TLS problem, using singular value decomposition. They have also shown that even in this simple linear case a solution is not guaranteed to exist.

In our case, where the function we seek consists of two straight lines, we simply calculate, for each point, its weighted orthogonal distances from the two lines, and include the smaller one in the total sum-of-squares:

$$S(a_1, b_1, a_2, b_2) = \sum_{i=1}^{N} \min\left\{ \frac{(y_i - a_1x_i - b_1)^2}{a_1^2(\Delta x_i)^2 + (\Delta y_i)^2}, \frac{(y_i - a_2x_i - b_2)^2}{a_2^2(\Delta x_i)^2 + (\Delta y_i)^2} \right\},$$

where $N$ is the total number of points and $a_1, b_1, a_2$ and $b_2$ are the slopes and intercepts of the two straight lines. $S$ is parameterized by four numbers whose meaning is somewhat arbitrary. This is true especially for the two intercepts $b_1$ and $b_2$, which are functions of the arbitrary location of the zero point of $x$. We can instead parameterize $S$ by an alternative, physically more meaningful, quadruple: the two coordinates of the breakpoint (breakpoint mass and corresponding radius), and the two slopes of the separate mass regimes.

When we set out to minimize $S$, it turned out that the solution was numerically unstable. Using different starting points for the optimization algorithm (Nelder-Mead simplex algorithm, see Nelder & Mead 1965) resulted in different solutions. That meant that around the global minimum of $S(a_1, b_1, a_2, b_2)$ there were many local minima. We suspect that this instability resulted from the endogenous sampling problem to which we alluded above (the mass-distribution shown in Fig. 2). In order to rectify this problem we have decided to
introduce weights to the definition of $S$, that will balance the effect each mass range has on the final solution. As is clear from the top panel of Figure 1, there are apparently three intervals: $M_p < 69M_\oplus$, $69M_\oplus \leq M_p < 1660M_\oplus$, and $1660M_\oplus \leq M_p$. Fig. 2 further demonstrates the differentiation in mass by portraying a histogram of the mass, together with the borders we chose among the three mass ranges.

The weighting scheme we applied is known in statistics as Inverse Probability Weighting, which is designed in order to alleviate the implications of endogenous sampling (e.g., Wooldridge 1999). We thus multiplied the contribution of each data point by a weight that was supposed to compensate for the effect of the size of the mass-range set to which the data point belonged to. The weight we assigned was simply proportional to the inverse of the size of the set: $N/N_c$, where $N$ is the total number of planets and $N_c$ is the size of the set. Table 1 details the three mass-range sets, their sizes and the corresponding weights. The final expression for $S$ is thus:

$$S(a_1, b_1, a_2, b_2) = \sum_{i=1}^{N} w_i \min \left\{ \frac{(y_i - a_1x_i - b_1)^2}{a_1^2(\Delta x_i)^2 + (\Delta y_i)^2}, \frac{(y_i - a_2x_i - b_2)^2}{a_2^2(\Delta x_i)^2 + (\Delta y_i)^2} \right\},$$

where $w_i$ is the weight of each point.

After optimizing $S$, we went on to obtain error estimates for the four variables, using a Monte-Carlo resampling approach. We randomly drew new data points from a Gaussian distribution. The expected values of the Gaussian distribution were the nominal values of $x$ and $y$, and we used the error bars as the widths (standard deviations) of the Gaussian distribution. We repeated the resampling procedure for 100,000 such random realizations of the data. The resulting random sample yielded the error estimates.

4 Results

Using the approach we outlined in the previous section, we obtained estimates for the two slopes, and the breakpoint. We found the breakpoint at a mass of $124 \pm 7M_\oplus$, and a radius of $12.1 \pm 0.5R_\oplus$. The resulting power laws of the two regimes (based on the two slopes in the $x$-$y$ plane) are: $R \propto M^{0.55 \pm 0.02}$ for small planets, and $R \propto M^{0.01 \pm 0.02}$ for large planets. The bottom panel of Figure 1 shows the derived relation.

4We have decided it is beyond the scope of this study to perform a rigorous clustering analysis. There seems to be a consensus in data-mining literature that at this stage there is not a single clustering algorithm or criterion that is guaranteed to be the best one. Thus, an intuitive division at this stage is completely acceptable (e.g., Estivill-Castro 2002).
It is interesting to note also according to our analysis, Saturn is "a small planet" (e.g., Chen & Kipping 2017; Weiss et al. 2013). Indeed, based on internal structure models, the heavy element fraction is Saturn is estimated to be between $\sim 20\%$ and $40\%$ (e.g., Guillot 2005). Thus, Saturn’s mass is not very far from the transition point, and it is important to note that the transition mass at $\sim 120 \ M_\oplus$ must be understood as a statistical quantity. As can be seen in Fig. 1, there is a region near the breakpoint in the fit at $120 \ M_\oplus$ that could either be considered as the continuation of the regime where the radius increases with mass to even higher masses, or as an continuation of the high-mass regime (with approximately constant radius) to even lower masses. This transition regime approximately covers a mass range larger than the one derived in the analysis, somewhere between about 80 and 120 $M_\oplus$. Thus, according to the data, the actual transition occurs at the higher end of this mass range. Another point that should be taken into account is that the apparent transition is also affected by stellar irradiation, while Saturn experiences a much lower irradiation than most of the planets that were used in our statistical analysis.

Our results are in good agreement with previous studies. The analysis we used to obtain was simple and intuitive and did not rely on subjective estimates. The fact that the transition occurs at a planetary mass larger than that of Saturn’s supports the idea that the change in the M-R relation for large planets is due to the dominating composition – in the case of massive planets, a mixture of hydrogen and helium. The data suggest that for planets larger than $\sim 120 M_\oplus$, the planetary radius is determined by the equation of state of these light elements (e.g., Zapolsky & Salpeter 1969; Fortney et al. 2007). The dominating H-He composition and the compression due to the large mass also naturally explains the weak dependence of the radius on mass for giant planets that consists of mostly hydrogen and helium (e.g., Guillot 2005). Lower-mass planets are less compressed and therefore, have a radius that increases in mass. The relatively large spread of the low-mass planets around the line suggests that in this mass regime, the planets can have various compositions.

### 4.1 Comparison with theoretical calculations

In this section we briefly compare the observational data with theoretical results from planet population syntheses based on the core accretion paradigm (Mordasini et al. 2012). These calculations yield the planetary bulk composition (solids and H/He) and the post-formation entropy based on the planets’ formation track. Here we use two sets of cores (heavy-element) compositions: silicates and iron or water. These two sets are chosen to assess the impact of various compositions of the solid core on the predicted radii of the synthetic planets. The first core is differentiated, and its composition is assumed to consists in mass of $1/3$ iron.
(inner core) and 2/3 perovskite (outer core), similar to Earth and several low-mass extrasolar planets (e.g., Santos et al. 2015). The second composition corresponds to cores consisting exclusively of water ice. While pure water core are unlikely to exist, these cores represent the limiting case of low-density cores. In all cases, the modified polytropic equation of state is used to derive the core radius, taking into account the pressure exerted by the surrounding envelope (see Mordasini et al. 2012). The star is assumed to be 1\(M_\odot\). Planets with semi-major axes of 0.01 to 0.5 AU are included in order to have a better comparison with the measurements. The formation model includes the effect of type I and II orbital migration. During the evolutionary phase, no mechanisms that can lead to inflation of the planetary radius (bloating) are included, whereas the effect of atmospheric escape is considered as described in Jin et al. (2014). The planetary opacity used in the formation models is the combination of the ISM opacities (Bell & Lin 1994) reduced by a factor 0.003 plus the grain-free opacities of Freedman et al. (2014). The reduction factor was determined in Mordasini et al. (2014) by comparison with detailed simulations of the grain dynamics by Movshovitz et al. (2010). During the planetary evolution, we assume a grain-free opacity because grains are expected to grow and settle to deeper regions after gas accretion is terminated accretion stops (e.g., Movshovitz & Podolak 2008).

The observations and the theoretical data are compared in Figure 3. As can be seen from the figure, the general M-R relation is similar, but there are also important differences. Both data sets show two different regimes. In the low-mass regime, both the observational and synthetic data show a large scatter in the M-R relation, which stems in the synthetic population from different envelope-core mass ratios, which in turn reflect different formation histories. For giant planets, the simulated planets follow a narrow M-R relation, which is clearly a consequence of neglecting bloating, assuming solar opacity, and an internal structure consisting of a pure H/He envelope surrounding a core made of pure heavy elements (i.e., a core+envelope internal structure). This is in contrast to the observations that also contain planets that have significantly larger radii, and probably different compositions and/or internal structures. In addition, the theoretical data correspond to a given age (5 \(\times\) 10\(^9\) years), while the observed population includes various ages. However, since most of the detected planets are observed around relatively old stars we do not expect a large impact on the goodness of fit to the observed M-R relation.

In the giant planet regime, one sees that in the observed exoplanet population, there are both giant planets with significantly larger, but also smaller radii. The large radii can be attributed to bloating, while the smaller planets suggest that there are some planets that contain significantly higher amounts of heavy elements than in the synthetic population.
This could be the result of a more efficient accretion of solids during formation, or giant impacts at later times. The effect of bloating on the population of small planets still needs to be studied in detailed although some work on this topic has already been presented (e.g., Lopez et al. 2012; Owen & Wu 2013). At the moment, it is still unclear whether an inflation mechanism is required in order to explain some of the small exoplanets with very low mean densities, since the existence of an (H-He) atmosphere can significantly increase the planetary radius. In addition, unlike massive planets which are expected to be H-He dominated, small planets have a large spread of heavy-elements and various fractions of H-He. This introduces a degeneracy with inflation mechanisms for low-mass planets: an observed M-R relation can probably either be caused by the existence of a more massive H-He envelope without inflation, or alternatively by a physical mechanism that causes the planet to be large, i.e., inflation. A better understanding of inflation and atmospheric loss in small- and intermediate- mass planets is clearly desirable.

Clearly, the two data sets should be compared only qualitatively. This is because the observed planets have a variety of ages, atmospheric opacities, and of course, possibly mixed compositions. As a result, the partially strong and tight correlations in the theoretical M-R should not be considered realistic, as they simply represent the composition of pure ice/rock planets (in the case of the bare cores), or the artificially narrow M-R relation of giant planets having all the same atmospheric opacity and lacking bloating mechanism. Nevertheless, there is a rather good agreement in terms of the transition between ”small” and ”large” planets in the M-R diagram.

5 Discussion and Conclusions

Our analysis suggests that the transition between large and small planets occurs at a mass (radius) of 124 ± 7M⊕ (12.1 ± 0.5R⊕). As expected, we establish two mass-radius relations for exoplanets. For low-mass planets, the radius is increasing with increasing mass, and the M-R relation we derive is: \( R \propto M^{0.55\pm0.02} \), whereas for the large planets, the radius is almost independent of the mass, and the M-R relation is \( R \propto M^{0.01\pm0.02} \).

Planetary mass and heavy element content almost exclusively determine the radius of low-mass planets < 124M⊕. The turnover point at this mass is probably due to the characteristic boundary between planets that are mostly gaseous (H-He dominated) and planets that consist of varying compositions, and therefore, do not have a single M-R relation. When the planet mass reaches > 124M⊕ the relation is flattened and is even consistent with a small negative slope, since we are approaching a slope of a compressed hydrogen-helium-dominated
planet.

This work identifies the transition point between small and large planets based on the M-R relation. This transition point is not the same as the one derived from studies of measured frequency of planets (occurrence rate), although the two might be linked. From standard planet formation models point of view, the transition from a heavy-element-dominated composition to a hydrogen-helium-dominated composition occurs at a mass where the core and envelope mass are similar (crossover mass). Statistical simulations of planet formation have shown (e.g., Mordasini et al. 2015) that this leads to a break in the planetary occurrence rate at about $30 \, M_\oplus$, but the actual value can vary significantly depending on the assumed solid-surface density, opacity, accretion rates, etc. Thus, it is interesting to note that there are not many observed planets with masses between $30$ and $120 \, M_\oplus$ (see Fig. 1; see also Mayor et al. 2011). This may suggest that the two transitions are linked. Finding the link between the two transition points can reveal crucial information on planetary formation and characteristics, and we hope to address this topic in the future.

As mentioned earlier, thinking about planetary characterization in terms of M-R relation is useful, but it should be noted that in reality, there is a M-R-flux, or even M-R-flux-time relation for planets. This is because the stellar flux and the time evolution are expected to affect the radius of the planet at a given time. These relations will be better understood in the future when exoplanet detections will include larger radial distances and various ages of stars, as expected from the PLATO mission.

Acknowledgments

We thank the anonymous referee for valuable comments and suggestions. R. H. acknowledges support from the Israel Space Agency under grant 3-11485 and from the United States - Israel Binational Science Foundation (BSF) grant 2014112. C. M. acknowledges support from the Swiss National Science Foundation under grant BSSGI0_155816 “PlanetsInTime’. Parts of this work have been carried out within the frame of the National Centre for Competence in Research PlanetS supported by the SNSF.
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Table 1: The details of the three mass-range sets, and the resulting weights used in the analysis.

|          | Group A | Group B                        | Group C                        |
|----------|---------|--------------------------------|--------------------------------|
| $M$      | $M < 69M_{\oplus}$ | $69M_{\oplus} < M < 1660M_{\oplus}$ | $M > 1660M_{\oplus}$ |
| $N_K$    | $N_A = 54$ | $N_B = 207$                   | $N_C = 13$ |
| $W_K$    | $W_A = 5.0741$ | $W_B = 1.3237$                | $W_C = 21.0769$ |

Table 2: The M-R relations derived for small and large planets.

|          | Weiss et al. 2013 | Chen & Kipping 2017 | This work |
|----------|-------------------|---------------------|-----------|
| Small planets | $R \propto M^{0.53\pm0.05}$ | $R \propto M^{0.59^{+0.04}_{-0.03}}$ | $R \propto M^{0.55\pm0.02}$ |
| Large planets | $R \propto M^{-0.04\pm0.01}$ | $R \propto M^{-0.04\pm0.02}$ | $R \propto M^{0.01\pm0.02}$ |
Figure 1: **Top:** The M-R relation of the exoplanets considered in the analysis. The dashed lines identify the three different regimes we consider for the weighting (see text) **Bottom:** The M-R relation and the derived best-fit curves, and M-R relations.
Figure 2: Histogram of planetary mass, showing clearly the three empirical mass ranges. The division into three intervals was performed in order to improve the quality of the statistical analysis (see text for details).
Figure 3: The M-R relation: observations vs. theoretical data. The circles correspond to the observations while the shaded area represents the results from planet population synthesis models.