HOLOGRAPHIC ALGORITHMS WITHOUT MATCHGATES

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Abstract. The theory of holographic algorithms, which are polynomial time algorithms for certain combinatorial counting problems, yields insight into the hierarchy of complexity classes. In particular, the theory produces algebraic tests for a problem to be in the class $P$. In this article we streamline the implementation of holographic algorithms by eliminating one of the steps in the construction procedure, and generalize their applicability to new signatures. Instead of matchgates, which are weighted graph fragments that replace vertices of a natural bipartite graph $\Gamma_P$ associated to a problem $P$, our approach uses only a natural number-of-edges by number-of-edges matrix associated to $\Gamma_P$. An easy-to-compute multiple of its Pfaffian is the number of solutions to the counting problem. This simplification improves our understanding of the applicability of holographic algorithms, indicates a more geometric approach to complexity classes, and facilitates practical implementations. The generalized applicability arises because our approach allows for new algebraic tests that are different from the “Grassmann-Plücker identities” used up until now. Natural problems treatable by these new methods have been previously considered in a different context, and we present one such example.

1. Introduction

In [18][19][20][21][22][23] L. Valiant introduced matchgates and holographic algorithms, in order to prove the existence of polynomial time algorithms for counting and sum-of-products problems that naïvely appear to have exponential complexity. Such algorithms have been studied in depth and further developed by J. Cai et al. [1][2][3][4][5][6][7][8].

The algorithms work as follows: suppose the problem $P$ is to count the number of satisfying assignments to a collection of Boolean variables $x_1, \ldots, x_m$ subject to clauses $c_1, \ldots, c_p$. The problem $P$ defines a bipartite graph $\Gamma_P = (V, U, E)$, with vertex sets $V = \{x_1, \ldots, x_m\} = \{x_i\}$ and $U = \{c_1, \ldots, c_p\} = \{c_s\}$ and there is an edge $(i, s) \in E$ iff $x_i$ appears in $c_s$. Holographic algorithms apply if the coordinates of the clauses and variables, expressed as tensors, satisfy a collection of polynomial equations called matchgate identities, possibly, in fact usually, after a change of basis. In the matchgate approach each vertex of $\Gamma_P$ is replaced by a weighted graph fragment called a matchgate to form a new weighted graph $\Gamma_\Omega(P)$, such that the weighted sum of perfect matchings of $\Gamma_\Omega(P)$ equals the number of satisfying assignments to $P$. If $\Gamma_\Omega(P)$ is planar, or more generally Pfaffian, the weighted sum of perfect matchings of $\Gamma_\Omega(P)$ can be computed in time polynomial in $|E|$ using the FKT algorithm [13][17]. FKT defines a sign-altered skew-symmetric adjacency matrix $X$ of $\Gamma_\Omega(P)$ whose Pfaffian equals the weighted sum of matchings of $\Gamma_\Omega(P)$. Our approach is related directly to the graph $\Gamma_P$, computing the Pfaffian of a natural $|E| \times |E|$ matrix associated to $\Gamma_P$. We replace FKT with an edge ordering defined by a plane curve as described in Section 6. Evaluating the Pfaffian takes polynomial time.

Equivalently, the number of satisfying assignments to $P$ is the result of the pairing of a vector $G \in \mathbb{C}^{2^{|E|}}$ formed as the tensor product of “local” data representing the variables and a vector $R$ in the dual vector space, the tensor product of “local” data concerning the clauses (see Section 4.1). The Valiant-Cai formulation of holographic algorithms can be summarized as

(1) $\#$satisfying assignments of $P = \langle G, R \rangle =$ weighted sum of perfect matchings of $\Gamma_\Omega(P)$.
In this article we give a new construction which eliminates the need to construct matchgates. We associate constants \( \alpha = \alpha_G, \beta = \beta_R \) (depending only on the number of each type of vertex) and \(|E| \times |E|\)-skew symmetric matrices \( \tilde{z} = \tilde{z}_G, y = y_R \) directly to \( G, R \), without the construction of matchgates, to obtain the equality:

\[
\# \text{satisfying assignments of } P = \langle G, R \rangle = \alpha \beta \text{Pfaff}(\tilde{z} + y);
\]

see Examples 1.2.4 and 4.2.5. The constants and matrices are essentially just components of the vectors \( G, R \). The algorithm complexity is dominated by evaluating the Pfaffian.

The key to our approach is that a vector satisfies the matchgate identities iff it is a vector of sub-Pfaffians of some skew-symmetric matrix, and that the pairing of two such vectors can be reduced to calculating a Pfaffian of a new matrix constructed from the original two. A similar phenomenon holds in great generality discussed in Appendix [7]. A simple example is the set of vectors of sub-minors of an arbitrary rectangular matrix. We describe an example of such an implementation in Section 3.

The starting point of our investigations was the observation that the matchgate identities come from classical geometric objects called spinors. The results in this article do not require any reference to spinors to either state or prove, and for the convenience of the reader not familiar with them we have eliminated all mention of them except for this paragraph and an Appendix (§7), included for the interested reader. However further results, such as our characterization of 1-realizable signatures [14], do require use of the representation theory of the spin groups.

2. Counting problems as tensor contractions

For brevity we continue to restrict to problems \( P \) counting the number of satisfying assignments of Boolean variables \( x_i \) subject to clauses \( c_s \) (such as \#PI-Mon-NAE-SAT in Example 3.1). Following e.g., [2] express \( P \) in terms of a tensor contraction diagrammed by a planar bipartite graph \( \Gamma_P = (V, U, E) \) as above (see Figure 1), together with the data of tensors \( G_i = G_{x_i} \) and \( R_s = R_{c_s} \) attached at each vertex \( x_i \in V \) and \( c_s \in U \). \( G_i \) will record that \( x_i \) is 0 or 1 and \( R_s \) will record that the clause \( c_s \) is satisfied. Let \( n = |E| \) be the number of edges in \( \Gamma_P \).

For each edge \( e = (i, s) \in E \) define a 2-dimensional vector space \( A_e \) with basis \( a_e|0, a_e|1 \). Say \( x_i \) has degree \( d_i \) and is joined to \( c_{j_1}, \ldots, c_{j_{d_i}} \). Let \( E_i \) denote the set of edges incident to \( x_i \) and associate to each \( x_i \) the tensor

\[
G_i := a_{i,s_{j_1}}|0 \otimes \cdots a_{i,s_{j_{d_i}}}|0 + a_{i,s_{j_1}}|1 \otimes \cdots a_{i,s_{j_{d_i}}}|1 \in A_i := A_{i,s_{j_1}} \otimes \cdots A_{i,s_{j_{d_i}}}
\]

The tensor \( G_i \) represents that either \( x_i \) is true (all 1’s) or false (all 0’s). It is called a generator and in the matchgates literature is denoted by the vector \((1,0,\ldots,0,1)\) corresponding to a lexicographic basis of \( A_i = \otimes_{e \in E_i} A_e \). This vector is called its signature. We use notation emphasizing the tensor product structure of the vector space \( A_i = \mathbb{C}^{2^{d_i}} \), and will use the word signature to refer to the tensor expression of \( G_i \).

Next define a tensor associated to each clause \( c_s \) representing that \( c_s \) is satisfied. Let \( A^*_e \) be the dual space to \( A_e \) with dual basis \( \alpha_{e,0, \alpha_{e,1}} \). Let \( E_s \) denote the set of edges incident to \( c_s \). For example, if \( c_s \) has degree \( d_s \) and is “not all equal” (NAE), then the corresponding tensor (called a recognizer) associated to it is

\[
R_s := \sum_{(\epsilon_1,\ldots,\epsilon_{d_s}) \neq (0,0,0)} \alpha_{i,s_1,\epsilon_1} \otimes \cdots \otimes \alpha_{i,s_{d_s},\epsilon_{d_s}} = \sum_{(\epsilon_1,\ldots,\epsilon_{d_s}) \neq (0,0,0)} \otimes_{e \in E_s} \alpha_{e,\epsilon_e}
\]

Now consider \( G := \otimes_i G_i \) and \( R := \otimes_s R_s \) respectively elements of the vector spaces \( A := \otimes_e A_e \) and \( A^* := \otimes_e A^*_e \). Then the number of satisfying assignments to \( P \) is \( \langle G, R \rangle \) where \( \langle \cdot , \cdot \rangle : \)
$A \times A^* \rightarrow \mathbb{C}$ is the pairing of dual vector spaces. At this point we have merely exchanged our original counting problem for the computation of a pairing in vector spaces of dimension $2^{|E|}$.

![Figure 1](image-url)

**Figure 1.** A bipartite graph $\Gamma$ diagrams a tensor contraction, representing an exponential sum of products such as counting the satisfying assignments of a satisfiability problem. Boxes denote clauses, circles denote variables. Each clause or variable corresponds to a tensor lying in the indicated vector space; e.g. $R_1 \in A_1^* \otimes A_2^* \otimes A_3^*$. Instead of replacing each vertex with a matchgate, our construction defines an $n \times n$ matrix, where $n$ is the number of edges in the problem graph. The Pfaffian of this matrix, times a constant depending on the number of each type of variable and clause, is the number of satisfying assignments.

### 3. Local conditions and change of basis

In order to be able to construct the matchgates corresponding to the $x_i, c_s$, there are local conditions that need to be satisfied; the algebraic equations placed on the $G_i, R_s$ are called the Grassmann-Plücker identities (or Matchgate Identities in this context). See, e.g., Theorem 7.2 of [4] for an explicit expression of the equations, which are originally due to Chevalley in the 1950’s [9]. These identities ensure that a tensor $T$ representing a variable or clause can be written as a vector of sub-Pfaffians of some matrix. From the matchgates point of view, these equations are necessary and sufficient conditions for the existence of graph fragments that can replace the vertices of $\Gamma_P$ to form a new weighted graph $\Gamma_{\Omega(P)}$ such that the weighted perfect matching polynomial of $\Gamma_{\Omega(P)}$ equals $\langle G, R \rangle$.

Expressed in the basis most natural for a problem, a clause or variable tensor may fail to satisfy the Grassmann-Plücker identities. However it may do so under a change of basis; e.g. in Example 3.1 we replace the basis (True, False) with (True+False, False−True). Such a change of basis will not change the value of the pairing $A \times A^* \rightarrow \mathbb{C}$ as long as we make the corresponding dual change of basis in the dual vector space—but of course this may cause the tensors in the dual space to fail to satisfy the identities. Thus one needs a change of basis that works for both generators and recognizers. In this article, as in almost all existing applications of the theory, we only consider changes of bases in the individual $A_e$’s, and we will perform the exact same change of basis in each such, although neither restriction is a priori necessary for the theory.

#### 3.1. Example

In #Mon-3-NAE-SAT, we are given a Boolean formula in conjunctive normal form where each clause has exactly three literals, and all are either positive or negative (no mixed negations). A clause is satisfied if it contains at least one true and one false literal. The counting problem asks how many satisfying truth assignments to the variables exist. The generator tensor $G_i$ corresponding to a variable vertex $x_i$ is $[\text{3}]$. The recognizer tensor corresponding to a NAE clause $R_s$ is $[\text{4}]$ and in our case we will have $d_s = 3$ for all $s$. 
Let $T_0$ be the basis change, the same in each $A_e$, sending $a_{e0} \mapsto a_e|0 + a_e|1$ and $a_{e1} \mapsto a_e|0 - a_e|1$ which induces the basis change $\alpha_{e|0} \mapsto \frac{1}{2}(\alpha_{e|0} + \alpha_{e|1})$ and $\alpha_{e|1} \mapsto \frac{1}{2}(\alpha_{e|0} - \alpha_{e|1})$ in $A_e^*$. This basis is denoted $b_2$ in [23]. Applying $T_0$, we obtain

$$T_0(a_{i,s_1}|0 \otimes \cdots \otimes a_{i,s_{d_i}}|0 + a_{i,s_1}|1 \otimes \cdots \otimes a_{i,s_{d_i}}|1) = 2 \sum_{\{s_1, \ldots, s_{d_i}\} \sum_{t=0}^{(mod 2)}} a_{i,s_1}|s_1 \otimes \cdots \otimes a_{i,s_{d_i}}|s_{d_i}.$$

In the matchgates literature this tensor is denoted by the vector $(2, 0, 0, 0, \ldots, 2, 0, 2)$ (assuming the number of incident edges is even). We also have

$$T_0 \left( \sum_{(s_1, s_2, s_3) \neq (0,0,0),(1,1,1)} \alpha_{i,s_1}|s_1 \otimes \alpha_{i,s_2}|s_2 \otimes \alpha_{i,s_3}|s_3 \right) = 6\alpha_{i,s_1}|0 \otimes \alpha_{i,s_2}|0 \otimes \alpha_{i,s_3}|0 - 2(\alpha_{i,s_1}|0 \otimes \alpha_{i,s_2}|1 \otimes \alpha_{i,s_3}|1 + \alpha_{i,s_1}|1 \otimes \alpha_{i,s_2}|0 \otimes \alpha_{i,s_3}|1 + \alpha_{i,s_1}|1 \otimes \alpha_{i,s_2}|1 \otimes \alpha_{i,s_3}|0)$$

or denoted by its coefficients, $(6, 0, 0, 0, -2, -2, -2, 0)$.

4. Holographic algorithms without matchgates

Though we do not use matchgates, in our approach the matchgate identities still must be satisfied under a change of basis as above. Our purpose is to make $G, R$ expressible as vectors of sub-Pfaffians of some skew-symmetric matrices. While this appears to be a global condition, it can be accomplished locally. Let $u, v$ be $s \times s$ and $t \times t$ matrices, and form a block diagonal $(s + t) \times (s + t)$ matrix from them. The vector of sub-Pfaffians of the new block diagonal matrix in $\mathbb{C}^{2s+t}$ can be obtained by taking the $2s \times 2t$ matrix corresponding to the product of the (column) vector of sub-Pfaffians of $u$ with the (row) vector of sub-Pfaffians of $v$, and writing the matrix as a vector in $\mathbb{C}^{2s+t}$. The analogous statement holds for block diagonal matrices built out of an arbitrary number of smaller matrices. Thus if each $G_i, R_i$ is a vector of Pfaffians, the corresponding $G, R$ will be so too; see Proposition [4.1.2]. Theorem [4.2.2] below shows how realizing $G, R$ as vectors of sub-Pfaffians aids one in computing the pairing $\langle G, R \rangle$ indicated by [2].

In all this there is a problem of signs that we have not yet discussed. The problem arises because if we order the $x_i$ and $e_s$, there are two natural types of orders of the vector spaces in the tensor products of the $A_i$, one grouping $i$’s and one grouping $s$’s. The block-diagonal discussion above cannot be simultaneously applied to both orderings at once. We explain this problem in detail and how to overcome it in [6].

4.1. The complement pairing and representing $G$ and $R$ as vectors of sub-Pfaffians

Assume we have a problem expressed as above and have constructed tensors $G, R$ such that in some change of basis their component tensors $G_i, R_i$ satisfy the Grassmann-Plücker identities. For the purposes of exposition, we will assume the total number of edges is even. See the discussion in the Appendix § for the case of an odd number of edges.

To compute $\langle G, R \rangle$, we will represent $G$ and $R$ as vectors of sub-Pfaffians. For an $n \times n$ skew-symmetric matrix $z$, the vector of sub-Pfaffians $\text{sPf}(z)$ lies in a vector space of dimension $\mathbb{C}^{2^n}$, where the coordinates are labeled by subsets $I \subset [n]$, and

$$(\text{sPf}(z))_I = \text{Pfaff}(z_I)$$

where $z_I$ is the submatrix of $z$ including only the rows and columns in the set $I$. Letting $I^c = [n] \setminus I$, similarly define $\text{sPf}^c \in \mathbb{C}^{2^n}$ by

$$(\text{sPf}^c(z))_I = \text{Pfaff}(z_{I^c}).$$
Lemma 4.2.1. Let following lemma can be found in [16, p. 110] and [11, p. 141]. A of identification for \(A \), \(A^*\) of the edges has been chosen we obtain ordered bases of \(A \), \(A^*\). To obtain the convenient choice of identification for \(A \), identify the vector corresponding to \(I \) with 1’s in the \(i_1, \ldots, i_{2p}\) slots and zeros elsewhere, so, e.g. \(I = \emptyset\) corresponds to \((0, \ldots, 0)\), \(I = (1, \ldots, 2n)\) corresponds to \((1, \ldots, 1)\). Reverse the correspondence for \(A^*\).

For later use, we remark that with these identifications, as long as the first (resp. last) entry of \(G\) (resp. \(R\)) is non-zero, we may rescale to normalize them to be one. (If say, e.g., the first entry of \(G\) is zero but the last is not, and last entry of \(R\) is non-zero, we can just reverse the identifications and proceed.) Note that the first and last choices of entries are independent of the edge ordering, but if necessary, to get the first and last entries non-zero, we simply take a less convenient choice of identification. (See [7] for an explanation of this freedom.) As long as this is done consistently it will not produce any problems.

In the rest of this section we assume that the local problem has been solved, i.e., that Grassmann-Plücker identities hold for all the \(G_i, R_i \) possibly after a change of basis. We also assume for brevity that the \(G_i\) and \(R_i\) are symmetric, i.e. that \(G_i = sPf(x_i) = sPf(\pi(x_i))\) for any permutation \(\pi\) on the edges incident on \(G_i\); this covers most problems of interest. For the more general case when the variables or clauses are not symmetric, and we need to be more careful about defining \(E_G\) and \(E_R\), see Section 6 and the Appendix.

**Definition 4.1.1.** Call an edge order such that edges incident on each \(x_i \in V\) (resp. \(c_s \in U\)) are adjacent a generator order (resp. recognizer order) and denote such by \(\bar{E}_G\) (resp. \(\bar{E}_R\)).

**Proposition 4.1.2.** Suppose \(P\) is a counting problem as above, \(E_G\) and \(E_R\) are respectively generator and recognizer orders. If for all \(x_i \in V\) there exists \(z_i \in \text{Mat}_{d_i \times d_i}\) such that \(sPf(z_i) = G_i\) under the \(\bar{E}_G\) identification, and similarly, there exists \(y_s \in \text{Mat}_{d_s \times d_s}\) for \(c_s\) and \(R_s\) with \(sPf^\vee(y_s) = R_s\), then there exists \(z, y \in \text{Mat}_{|E| \times |E|}\) such that

\[ sPf(z) = G \quad \text{under the } \bar{E}_G \text{ identification and} \]

\[ sPf^\vee(y) = R \quad \text{under the } \bar{E}_R \text{ identification}; \]

\(z, y\) are just given by stacking the component matrices \(z_i, y_s\) block-diagonally.

As the proposition suggests, a difficulty appears when we try to find an order \(\bar{E}\) that works for both generators and recognizers.

**Definition 4.1.3.** An order \(\bar{E}\) is valid if there exists skew-symmetric matrices \(z, y\) such that \(sPf(z) = G\) and \(sPf^\vee(y) = R\) under the \(\bar{E}\) identification.

Thus if an order is valid

\[ \langle G, R \rangle = \sum_I sPf_I(z) sPf_{I^c}(y) \]

and in the next subsection we will see how to evaluate the right hand side in polynomial time. Then in [8] we prove that if \(\Gamma_P\) is planar, there is always a valid ordering.

4.2. Evaluating the complementary pairing of vectors of sub-Pfaffians. Let \(n\) be even. For an even set \(I \subseteq [n]\), define \(\sigma(I) = \sum_{i \in I} i\), and define \(\text{sgn}(I) = (-1)^{\sigma(I) + |I|/2}\). Proofs of the following lemma can be found in [16] p. 110 and [11] p. 141.

**Lemma 4.2.1.** Let \(z\) and \(y\) be skew-symmetric \(n \times n\) matrices. Then

\[ \text{Pfaff}(z + y) = \sum_{p=0}^{n} \sum_{I \subseteq [n], |I| = 2p} \text{sgn}(I) \text{Pfaff}_I(z) \text{Pfaff}_{I^c}(y) \]
To use Lemma 4.2.1 to compute inner products we need to adjust one of the matrices to correct the signs. For a matrix $z$ define a matrix $\tilde{z}$ by setting $\tilde{z}_{ij} = (-1)^{i+j+1}z_{ij}$. Let $z$ be an $n \times n$ skew-symmetric matrix. Then for every even $I \subseteq [n]$, 
\[
Pfaff_I(\tilde{z}) = \text{sgn}(I)Pfaff_I(z).
\]
This is because for odd $|I|$, both sides are zero. For $|I| = 2p$, $p = 1, \ldots, \left\lfloor \frac{n}{2} \right\rfloor$, 
\[
Pfaff_I(\tilde{z}) = (-1)^{i_1+i_2+1}\cdots(-1)^{i_{2p-1}+i_{2p}+1}Pfaff_I(z) = \text{sgn}(I)Pfaff_I(z).
\]
Thus we have the following Theorem.

**Theorem 4.2.2.** Let $z, y$ be skew-symmetric $n \times n$ matrices. Then 
\[
\langle sPf(z), sPf^\vee(y) \rangle = Pfaff(\tilde{z} + y).
\]

In Section 6 we show that if $\Gamma_P$ is planar there is an easily computable valid edge ordering $\tilde{E}$. Our result may be summarized as follows:

**Theorem 4.2.3.** Let $P$ be a problem admitting a matchgate formulation $\Gamma = (V,U,E)$ (e.g., a satisfiability problem as in the first paragraph) such that

1. There exists a change of basis in $\mathbb{C}^2$ such that all the $G_i, R_s$ satisfy the Grassmann–Plücker identities (i.e., all $G_i$ and $R_s$ are simultaneously realizable) with complementary indexing.

2. There exists a valid edge order (e.g. if $\Gamma$ is any planar bipartite graph)

Normalize $\pi(G)$ (resp. $\tau(R)$) so that the first (resp. last) entry is one, say we need to divide by $\alpha, \beta$ respectively (i.e. $\alpha = \prod_i \alpha_i$ where $G_i = \alpha_i sPf(x_i)$ and similarly for $\beta$). Consider skew symmetric matrices $x, y$ where $x_{ij}$ is the entry of (the normalized) $\pi(G)$ corresponding to $I = (i,j)$ and $y_{ji}$ is the entry of (the normalized) $\tau(R)$ corresponding to $I^c = (i,j)$. Then the number of satisfying assignments to $P$ is given by $\alpha \beta Pfaff(\tilde{x} + y)$.

**Example 4.2.4.** Figure 2 shows an example of #Pl-Mon-3-NAE-SAT, with an edge order given by a path through the graph. The corresponding matrix, $\tilde{z} + y$ is below. In a generator order,
for each variable, so $\alpha = 2^6$, $\beta = \left(\frac{6}{21}\right)^4$, and $\alpha \beta \text{Pfaff}(\tilde{z} + y) = 26$ satisfying assignments.

$$\begin{pmatrix}
0 & 1 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1/3 & -1/3 \\
-1 & 0 & -1/3 & -1/3 & 0 & 0 & 0 & 0 & 0 & 0 \\
0 & 1/3 & 0 & -1/3 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1/3 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 1/3 & 0 & -1 & 0 & 0 & 0 \\
0 & 0 & 0 & 0 & 0 & 1/3 & 0 & -1/3 & 0 & 0 \\
0 & 0 & 0 & 0 & 1/3 & 0 & 1 & 0 & 0 & 0 \\
1/3 & 0 & 0 & 0 & 0 & 0 & 0 & 0 & -1 & 0 \\
1/3 & 0 & 0 & 0 & 1/3 & 0 & 0 & 0 & 0 & 0 \\
\end{pmatrix}$$

\[\tilde{z} + y = \begin{pmatrix}0 & 1 & -1 & 1 & 0 & 0 & 0 & 0 & 0 & -1/3 & -1/3 \\
-1 & 0 & 1 & -1 & 0 & 0 & 0 & 0 & -1/3 & -1/3 & 0 \\
1 & -1 & 0 & -1 & 0 & 1/3 & -1/3 & 0 & 0 & 0 & 0 \\
-1 & 1 & -1 & 0 & -1/3 & -1/3 & 0 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1/3 & 0 & -1/3 & 0 & 0 & 0 & 0 & 1 \\
0 & 0 & 0 & 1/3 & 1/3 & 0 & 1 & 0 & 0 & 0 & 0 \\
0 & 0 & 0 & 1/3 & 0 & -1 & 0 & -1/3 & 0 & 0 & 0 \\
0 & 0 & 0 & 1/3 & 0 & 0 & 0 & 1/3 & 0 & 1 & 0 \\
0 & 1/3 & 0 & 0 & 0 & 0 & -1 & 0 & -1/3 & 0 & 0 \\
0 & 1/3 & 0 & 0 & 0 & 0 & 0 & 1/3 & 0 & 1 & 0 \\
1/3 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 0 & -1 & 0 \\
1/3 & 0 & 0 & 0 & -1 & 0 & 0 & 0 & 1/3 & 0 & 0 \\
\end{pmatrix}\]

**Example 4.2.5.** Another #Pl-Mon-3-NAE-SAT example which is not read-twice and its \(\tilde{z} + y\) matrix are shown in Figure 3. The central variable has a submatrix which is again ones above the diagonal and also contributes 2 to \(\alpha\), so \(\alpha = 2^5\), \(\beta = \left(\frac{6}{21}\right)^4\). Four sign changes are necessary in \(\tilde{z}\). The result is \(\alpha \beta \text{Pfaff}(\tilde{z} + y) = 14\) satisfying assignments.

$$(G, R) = \det(\text{Id} + z^T y).$$

Here is an example that exploits this situation.

**Example 5.0.6.** Given a graph $G$ and an arbitrary orientation of $E(G)$, the incidence matrix $B = (b_v^e)_{v \in V(G), e \in E(G)}$ is a $|V(G)| \times |E(G)|$ matrix defined by

$$b_v^e = \begin{cases} 
1 & \text{if } v \text{ is the initial vertex of } e, \\
-1 & \text{if } v \text{ is the terminal vertex of } e, \\
0 & \text{otherwise.}
\end{cases}$$

For $W \subseteq V(G)$ and $F \subseteq E(G)$, with $|W| = |F|$, let $\Delta_{W,F}(B)$ denote the corresponding minor of $B$. Let $s \text{Det}(B) = (1, \Delta_{v,e}B, \ldots, \Delta_{W,F}(B), \ldots)$ denote the vector of minors of $B$. 

**5. Beyond Pfaffians**

As mentioned in the introduction, the key to our approach is that the pairing of a vector in a vector space of dimension $2^n$ with a vector in its dual space can be accomplished by evaluating a Pfaffian if both vectors are vectors of Pfaffians of some skew-symmetric matrix. This type of simplification occurs in many other situations as explained in the Appendix 7. One simple such is that if the vector space is of dimension $\binom{n}{k}$ and the vectors that are to be paired are vectors of minors of some $k \times (n-k)$ matrix. Then the pairing can be done by computing the determinant of an easily constructed auxiliary $(n-k \times n-k)$ or $(k \times k)$-matrix, so if $k$ is on the order of $\frac{n}{2}$, there is a spectacular savings. Explicitly, for $k \times \ell$ matrices $z$ and $y$, with $G = s \text{Det}(z)$ and $R = s \text{Det}(y)$,

$$\langle G, R \rangle = \det(\text{Id} + z^T y).$$
A rooted spanning forest of $G$ is a pair $(H,W)$, where $W \subseteq V(G)$, $H$ is a spanning acyclic subgraph of $G$, and every component of $H$ contains exactly one vertex of $W$. The minor $\Delta_{W,F}(B)$ equals to $\pm 1$ if $(G|_F, V(G) - W)$ is a rooted spanning forest, and $\Delta_{W,F}(B) = 0$, otherwise. (See [10] for a proof of a generalization of this statement to weighted graphs.) Therefore, the value of the pairing

$$ \langle \text{sDet}(B^I), \text{sDet}(B) \rangle = \sum_{W \subseteq V(G)} \sum_{F \subseteq V(G)} (\Delta_{W,F}(B))^2 $$

is equal to the number of rooted spanning forests of $G$. It is shown [10] that this value can be computed efficiently by the Cauchy-Binet formula:

$$ \sum_{W \subseteq V(G)} \sum_{F \subseteq V(G)} (\Delta_{W,F}(B))^2 = \det(\text{Id} + B^I B), $$

where $\text{Id}$ is a $|E(G)| \times |E(G)|$ identity matrix.

From our point of view the result outlined in this example is an instance of the above fact that the pairing of vectors in the Grassmannian and its dual can be computed efficiently. (The Grassmannian can be locally parametrized by vectors of minors of matrices.) The above efficient algorithm for enumerating rooted spanning forests is surprising in the same sense as many holographic algorithms are: A closely related problem of enumerating spanning forests of a graph is $\#P$-hard [12].

6. Edge ordering and sign

Throughout this section we assume the local problem has been solved and we only need a valid edge order. We do not require symmetric signatures.

Given an order $\bar{E}$ we would like to know if it is valid. Say $\bar{E}_G$, $\bar{E}_R$ are generator and recognizer orders so that there exist skew-symmetric matrices $z,y$ such that with respect to these orders $G = \text{sPf}(z)$, $R = \text{sPf}(y)$. Let $\pi, \tau \in \mathfrak{S}_{|E|}$ respectively be the permutations such that $\pi(\bar{E}_G) = \bar{E}$ and $\tau(\bar{E}_R) = \bar{E}$. Then for all $J \subset [n]$, Pfaff $\pi(J)(\tau(z)) = \text{sgn}(\pi|_J) \text{Pfaff}_J(z)$ and similarly for $\tau$, so up to signs we have what we want. Valid orderings yield $\pi, \tau$ which preserve sub-Pfaffian signs.

We now describe one type of valid ordering for planar graphs, called a $C$-ordering. For any planar bipartite graph $\Gamma_P$, a plane curve $C$ intersecting every edge once corresponds to a non-self-intersecting Eulerian cycle in the dual of $\Gamma_P$ and can be computed in $O(|E|)$ time. Fix such a $C$, an orientation and a starting point for $C$, and let $\bar{E}_C$ be the order in which the resulting path crosses the edges of $\Gamma_P$. Define $\bar{E}_G'$ to be the generator order chosen so that the permutation $\pi : \bar{E}_G' \to \bar{E}_C$ is lexicographically minimal. In particular, $\bar{E}_G'$ agrees with $\bar{E}_G$ on the edges incident to any fixed generator in $V$. For example, the generator order on Figure 2 is $1, 2, 3, 6, 4, 5, 7, 8, 9, 12, 10, 11$. Define $\bar{E}_R'$ similarly.

To show that $\bar{E}_C$ is valid we will need another characterization of the sub-Pfaffians and the notion of crossing number. Let $S = \{(e_1, e'_1), \ldots, (e_k, e'_k)\}$ be a partition of an ordered set $I$, with $|I| = 2k$, into unordered pairs. Assume, for convenience, that $e_r < e'_r$ for $1 \leq r \leq k$. Define the crossing number $\text{cr}(S)$ of $S$ as

$$ \text{cr}(S) = \# \{(r,s) \mid e_r < e_s < e'_r < e'_s\}. $$

Note that $\text{cr}(S)$ can be interpreted geometrically as follows. If the elements of $I$ are arranged on a circle in order and the pairs of elements corresponding to pairs in $S$ are joined by straight-line edges, then $\text{cr}(S)$ is the number of crossings in the resulting geometric graph (see Figure 2(b)). When the order $\bar{E}$ on $I$ is unclear from context we write $\text{cr}(S, \bar{E})$, instead of $\text{cr}(S)$.

For $I \subseteq E(\Gamma)$, denote by $\Gamma_I$ the subgraph of $\Gamma$ induced by $I$. Let $\mathcal{S}(\Gamma_I)$ be the set of pairings $S = \{(e_1, e'_1), \ldots, (e_k, e'_k)\}$ of $I$ such that edges in each pair share a vertex in the set
Let \( \sigma(S) \) denote the permutation
\[
\sigma(S) = ( e_1 \ e_1' \ e_2 \ e_2' \ldots \ e_k \ e_k').
\]
By \cite[p. 91]{15} or direct verification, \( \text{sgn}(\sigma(S)) = (-1)^{\text{cr}(S)}. \) Therefore, for a skew-symmetric matrix \( z \) one has
\[
\text{Pfaff}_I(z) = \sum_{S \in \mathcal{S}} (-1)^{\text{cr}(S)} z_S,
\]
where \( z_S := z_{e_1 e_1'} \ldots z_{e_k e_k'} \) and the sum is taken over the set \( \mathcal{S} \) of all partitions of \( I \) into pairs.

We need to show that the terms \( z_S, S \in \mathcal{S} \setminus \mathcal{S}(\Gamma_I) \) are zero. Note that for a nonzero term, there must be an even number of edges in the restriction to each variable. If \( S \) contains a pair with split ends \( (x_i e_s, x_k e_t), i \neq k \), then \( z_S = 0. \) \( \square \)

The analogous statement to Proposition \ref{lem607} holds for recognizers. We can now prove the following Lemma.

**Lemma 6.0.8.** Let \( P \) be a problem as above such that all the associated \( G_i, R_s \) satisfy the Grassmann-Plücker relations under some change of basis, \( \Gamma_P \) is planar and let \( \bar{E}^C \) be a \( C \)-ordering. If \( \pi, z \) are defined as above, then \( \text{sPf}(\pi(z)) = \pi(\text{sPf}(z)). \)

**Proof.** It suffices to show that for any \( I \subseteq E(\Gamma) \) and any partition \( S \in \mathcal{S}(\Gamma_I) \) of \( I \), the signs of the term corresponding to \( S \) in \( \text{Pfaff}_I(z) \) and \( \text{Pfaff}_{\pi(I)}(\pi(z)) \) are identical. By Proposition \ref{lem607} this is equivalent to showing that
\[
(5) \quad (-1)^{\text{cr}(S, \bar{E}^C)} = \prod_{x \in V} (-1)^{\text{cr}(S_{|x}, \bar{E}^C_{G})},
\]
where the left hand side of \ref{5} is the sign of the term corresponding to \( S \) appearing in \( \text{Pfaff}_{\pi(I)}(\pi(z)) \), and the right hand side is the sign of the term corresponding to \( S \) in \( \text{Pfaff}_I(z) \), as
\[
\text{Pfaff}_I(z) = \prod_{x \in V} \text{Pfaff}_{I_{|x}}(z).
\]

Here \( S_{|x} \) and \( I_{|x} \) denote the restriction to the edges incident to \( x \) of \( S \) and \( I \), respectively.

A stronger equality, namely \( \text{cr}(S, \bar{E}^C) = \sum_{x \in V} \text{cr}(S_{|x}, \bar{E}^C_{G}) \), holds. The curve \( C \) determining \( \bar{E}^C \) separates \( V \) from \( U \). To exploit the geometric intuition presented above, we replace each vertex in \( x \in V \) by a small circle and join the ends of edges in \( I \) on this circle by line segments corresponding to pairs in \( S_{|x} \). The total number of crossings in the resulting graph is \( \sum_{x \in V} \text{cr}(S_{|x}, \bar{E}^C_{G}) = \sum_{x \in V} \text{cr}(S_{|x}, \bar{E}^C) \), as \( \bar{E}^C_{G} \) and \( \bar{E}^C \) coincide on the set of edges incident to a fixed \( x \in V \). On the other hand, a pair \( \{r, s\} \) is counted in \( \text{cr}(S_{|x}, \bar{E}^C) \), if and only if the curves with ends on \( C \) corresponding to \( e_r \cup e'_r \) and \( e_s \cup e'_s \) cross.

In other words, we are considering restrictions of (the union of \( e_r \) and \( e'_r \)) and (the union \( e_s \) and \( e'_s \)) to the region of the plane bounded by \( C \) containing \( V \). \( \square \)
Figure 4. $x, x'$ are two generators, the oval is $C$ and the numbers indicate the ordering of the edges determined by $C$.

It follows from Lemma 6.0.8 and a symmetric statement for $\tau$ that $\tilde{E}^C$ is valid.

**Example 6.0.9.** An example is given in Figure 4. There, the curves composed of edges (3 and 5), and (4 and 6) cross, and that shows that the permutation $(3\ 5\ 4\ 6)$ is odd. The edges corresponding to, say, (3 and 5) and (2 and 7) don’t cross, and the permutation $(3\ 5\ 2\ 7)$ is even. In the example,

$$S = \{\{1, 9\}, \{2, 7\}, \{3, 5\}, \{4, 6\}, \{8, 10\}\}.$$ 

The term corresponding to $S$ in $\text{Pfaff}_{\pi(I)}(\pi(x))$ is $(-1)^2 x_{1,9} x_{2,7} x_{3,5} x_{4,6} x_{8,10}$, as $cr(S, \tilde{E}^C) = 2$. The term in $\text{Pfaff}(x)$ is a product of $-x_{3,5} x_{4,6}$ and $-x_{1,9} x_{2,7} x_{8,10}$, which are the terms in Pfaffians of blocks corresponding to $x$ and $x'$, respectively.

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7. Appendix: Spinors and holographic algorithms

The Grassmann-Plücker identities are the defining equations for the spinor varieties (set of pure spinors). These equations date back at least to Chevalley in the 1950’s [9]. The spinor varieties, of which there are two (isomorphic to each other) for each $n$, $\mathcal{S}_+, \mathcal{S}_-$, respectively live in $\Lambda^{even} \mathbb{C}^n =: \mathcal{S}_+$, and $\Lambda^{odd} \mathbb{C}^n =: \mathcal{S}_-$. The parity condition corresponds to requiring that $G, R$ both be either in $\mathcal{S}_+$ or $\mathcal{S}_-$. If $n$ is odd then $\mathcal{S}_+, \mathcal{S}_-$ are dual vector spaces to one another, and if $n$ is even, each is self-dual. It is this self-duality that leads to the simplification of the exposition with $n$ is even - the discussion for $n$ odd is given below.
They admit a cover by Zariski open subsets where each subset in e.g. \( \hat{S}_+ \) is covered by a map of the form

\[
\phi : \Lambda^2 \mathcal{C}^n \to \bigoplus_j \Lambda^{2j} \mathcal{C}^n = \Lambda^{\text{even}} \mathcal{C}^n
\]

\[
x \mapsto (\text{Pfaff}_I(x))
\]

as \( I \subseteq (1, \ldots , 2n) \) runs over the subsets of even cardinality (and by convention \( \text{Pfaff}_\emptyset(x) = 1 \)).

The identification \( S_+ \simeq \Lambda^{\text{even}} \mathcal{C}^{2n} \) is not canonical. We can get different identifications by composing \( \phi \) with the action of the Weyl group. The Weyl group action assures that some “less convenient” map will have first entry nonzero for \( G, R \) as mentioned in §4.1.

The map (6) is a special case of a natural map to the “big cell” in a rational homogeneous variety and the potential generalizations to holographic algorithms mentioned to in the introduction would correspond to replacing \( \hat{S}_+ \) by a Lagrangian Grassmannian or an ordinary Grassmannian of \( k \)-planes in a \( n \)-dimensional space. More generally, if \( V \) is a generalized \( G(n) \)-cominuscule module, where \( n \) denotes the rank of the semi-simple group \( G \), then the pairing \( V \times V^* \to \mathbb{C} \), when restricted to the cone over the closed orbits in \( V, V^* \) can be computed with \( O(n^4) \) arithmetic operations, even though the dimension of \( V \) is generally exponential in \( n \).

Much of the exposition could be rephrased more concisely using the language of representation theory. For example, the fact that if each \( G_i \) lies in a small spinor variety then \( G = \otimes G_i \) lies in a spinor variety as well, is a consequence that the tensor product of highest weight vectors subgroups with compatible Weyl chambers will be a highest weight vector for the larger group. Similarly the map \( z \mapsto \tilde{z} \) has a natural interpretation in terms of an involution on the Clifford module structure that \( S_+ \) comes equipped with.

On the other hand \( \mathcal{C}^{2n} \) may be viewed as \( (\mathcal{C}^2)^\otimes n \) and as such, inherits an \( SL_2 \mathcal{C} \)-action. The \( SL_2(\mathcal{C}) \) action corresponds to our change of basis, and what we are trying to do is determine which pairs of points can by simultaneously be moved into the spinor varieties in \( (\mathcal{C}^2)^\otimes n \) and the dual space \( (\mathcal{C}^{2*})^\otimes n \). The convenient basis referred to in the text corresponds to an identification that embeds the torus of \( SL_2 \) diagonally into the torus of \( Spin_{2n} \) so weight vectors map to weight vectors.

To continue the group perspective in complexity theory more generally, one can also view the ability to compute the determinant quickly via Gaussian elimination as the consequence of the robustness of the action of the group preserving the determinant: whereas above there is a subvariety of a huge space (the spinor variety) on which the pairing can be computed quickly, and a group \( SL_2 \) that preserves the pairing - a holographic algorithm can be exploited if the pair \( (G, R) \) can be moved into the subvariety \( \hat{S}_+ \times \hat{S}_+ \) under the action of \( SL_2 \). In Gaussian elimination, for the corresponding subvariety one takes, e.g., the set of upper-triangular matrices, and the group preserving the determinant acts on the space of matrices sufficiently robustly that any matrix can be moved into this subvariety (and in polynomial time). Contrast this with the permanent which is also easy to evaluate on upper-triangular matrices, but the group preserving the permanent is not sufficiently robust to send an arbitrary matrix to an upper-triangular one. This difference in robustness of group actions might explain the difference between the determinant and permanent, as well as why only solutions to certain SAT problems can (so far) be counted quickly.

8. Appendix: Non-symmetric signatures

Most of the natural examples of holographic algorithms, and, in particular, the examples given in this paper, correspond to generator and recognizer signatures \( G_i \) and \( R_s \) which are symmetric, that is invariant under permutations of edges incident to the corresponding vertex. The assumption that the signatures are symmetric is also convenient for our arguments. If the signatures are symmetric, then the generator tensor \( G \) can be represented as a vector of
sub-Pfaffians in some generator order if and only if it can be represented as such a vector in every generator order, and the same holds for recognizer orders. This does not hold for general, non-symmetric signatures. We now explain how to deal with non-symmetric signatures.

It is shown in Section 6 that given a planar curve $C$, an edge order $\bar{E}_C$ and a generator order $\bar{E}_G$, the tensor $G$ can be represented as a vector of sub-Pfaffians in $\bar{E}_C$ if and only if it can be represented as one in $\bar{E}_G$. A similar statement holds for $\bar{E}_C$ and the recognizer order $\bar{E}_R$. The edges incident to a given generator are ordered in a clockwise cyclic order in $\bar{E}_G$. It is easy to verify that only a cyclic, not linear, ordering enters Grassmann-Plücker identities. Thus for non-symmetric signatures the following statement holds.

**Theorem 8.0.10.** Let $P$ be a problem admitting a matchgate formulation $\Gamma_P = (V,U,E)$ with $\Gamma_P$ planar. Let the edges incident to every vertex of $\Gamma_P$ be ordered in a clockwise order. Assume that there exists a change of basis such that all the $G_i, R_s$ satisfy the Grassmann-Plücker identities with complementary indexing. Then there exists a valid order, and the number of satisfying assignments of $P$ can be found in polynomial time.

Note that the assumption that the edges (or “wires”) are ordered in a way that agrees with a planar embedding is also used in the matchgate formulation, as the matchgates must be inserted in such a way that the resulting graph remains planar.