Symplectic geometric flows

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Abstract

Several geometric flows on symplectic manifolds are introduced which are potentially of interest in symplectic geometry and topology. They are motivated by the Type IIA flow and T-duality between flows in symplectic geometry and flows in complex geometry. Examples include the Hitchin gradient flow on symplectic manifolds, and a new flow which is called the dual Ricci flow.

1 Introduction

Geometric flows are now well-recognized as a powerful tool for geometry and topology. Major successes include the Eells-Sampson theorem on harmonic maps [ES64], Hamilton’s Ricci flow [Ham82] and Perelman’s proof of the Poincaré conjecture [Per02, Per03b, Per03a], Donaldson’s heat flow proof of the Donaldson-Uhlenbeck-Yau theorem on Hermitian-Yang-Mills connections [Don87], the differentiable sphere theorem of Brendle-Schoen [BS09], and many other developments. However, these successes were mostly in the settings of Riemannian and complex geometry, leaving the subject of symplectic geometric flows underdeveloped. In recent years, a few geometric flows adapted to symplectic geometry have been introduced, such as Lê-Wang’s anti-complexified Ricci flow [LW01], Streets-Tian’s symplectic curvature flow [ST14], and He’s flow of non-degenerate 2-forms [He21]. Although there has been much progress on these flows, applications of geometric flows in symplectic geometry and topology have remained relatively few.

In [FP21], in joint work with S. Picard and X.W. Zhang, we introduced the Type IIA flow for symplectic Calabi-Yau 6-manifolds, motivated by the Type IIA string equations proposed in e.g. [TY14]. This was further developed in [FPZa, FPPZ21, Raf21]. In particular, in [FPPZ21], we successfully applied the Type IIA flow to prove the stability of the Kähler property for Calabi-Yau 3-folds under symplectic deformations.

The goal of this paper is to introduce some new geometric flows which may potentially be of interest in symplectic geometry and topology. They are motivated by duality considerations as well as by the Type IIA flow, to which several of them are actually closely related. More specifically, in [FP21], S. Picard and the first author had introduced the dual Anomaly flow as the T-dual of the
Both the Type IIB flow and the dual Anomaly flow are flows in complex geometry, and they are only dual to each other up to lower order terms. Here we introduce instead the principle that by applying T-duality, we can derive a flow in symplectic geometry from a flow in complex geometry. In particular, we show that the Type IIA flow and the Type IIB flow are indeed related to each other by T-duality, as suggested by mirror symmetry, and the duality is now exact without lower order terms. We also derive the T-dual of the Kähler Ricci flow in the symplectic setting. In Section 3, we propose the study of the gradient flow of Hitchin’s functional in dimension six. In the presence of a compatible symplectic form, this flow takes a similar expression to that of the Type IIA flow. Moreover, it induces a flow of a pair which can be viewed as the anti-complexified Ricci flow with lower order corrections coupled to a scalar function. In Section 4 we present a few explicit examples of the gradient flow of 6D-Hitchin’s functional, showing that the flow can be used to find optimal almost complex manifolds on certain locally homogeneous symplectic half-flat manifolds. These examples naturally provide eternal and convergent solutions to the anti-complexified Ricci flow.

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2 The Type IIA and the Type IIB flows

In this section, we would like to present a general principle by which a flow in symplectic geometry should arise by T-duality from a flow in complex geometry. We illustrate this principle by establishing the duality of the Type IIA and the Type IIB flows in the semi-flat case, which is the case when T-duality can be implemented explicitly.

Let us first recall the set-up of semi-flat geometry, in the notations from [FP21]. Let $B$ be a 3-dimensional compact special integral affine manifold. We can cover $B$ by local coordinates $\{x^1, x^2, x^3\}$ such that the transition functions are valued in the group $\text{SL}(3, \mathbb{Z}) \ltimes \mathbb{R}^3$. Let $TB$ be the tangent bundle of $B$, with $\{y^1, y^2, y^3\}$ the natural coordinates of tangent directions. Clearly the fiberwise lattice

$$\hat{\Lambda} = \mathbb{Z} \frac{\partial}{\partial x^1} + \mathbb{Z} \frac{\partial}{\partial x^2} + \mathbb{Z} \frac{\partial}{\partial x^3} = \{(y^1, y^2, y^3) : y^i \in \mathbb{Z}\}$$

is well-defined, and we may form the quotient $\hat{X} = TB/\hat{\Lambda}$, which is a smooth $T^3$-fibration over $B$. Moreover, $\hat{X}$ is naturally equipped with a complex structure

\[\text{[FPZ18a, FPPZ18b]}\] with slope parameter $\alpha' = 0$, and “Type IIB flow” is a more precise name, since there is no longer a gauge field and no Green-Schwarz Anomaly cancellation mechanism [FPPZ18a].
such that \( \{ z^j = x^j + iy^j \}_{j=1}^3 \) forms a set of local holomorphic coordinates. For our purpose, we shall also assume that \( B \) is equipped with a Hessian metric \( g \) with local potential \( \phi \). In other words, there exists a local convex function \( \phi \) such that

\[
 g_{jk} = \frac{\partial^2 \phi}{\partial x^j \partial x^k}. 
\]

We shall also consider the dual affine coordinates \( \{ x_j = \frac{\partial \phi}{\partial x^j} \} \) on \( B \) under Legendre transformation. Let \( \{ y_1, y_2, y_3 \} \) be the natural coordinates for the cotangent directions associated to the local chart \( \{ x^1, x^2, x^3 \} \). It is not hard to check that the fiberwise lattice

\[
 \hat{\Lambda} = \mathbb{Z} dx^1 + \mathbb{Z} dx^2 + \mathbb{Z} dx^3 = \{ (y_1, y_2, y_3) : y_k \in \mathbb{Z} \}
\]

is well-defined, and we may form the fiberwise quotient \( \hat{X} = T^*B/\hat{\Lambda} \), which is also a smooth \( T^3 \)-fibration over \( B \). The natural symplectic form on \( T^*B \) descends to a symplectic form on \( \hat{X} \), which in local coordinates can be expressed as

\[
 \omega = dx^1 \wedge dy_1 + dx^2 \wedge dy_2 + dx^3 \wedge dy_3.
\]

Moreover, \( \hat{X} \) is equipped with a holomorphic volume form \( \Omega = \phi + i \hat{\phi} = dz_1 \wedge dz_2 \wedge dz_3 \) for \( z_j = x_j + iy_j \). In local coordinates we have

\[
 \varphi = dx_1 \wedge dx_2 \wedge dx_3 - dx_1 \wedge dy_2 \wedge dy_3 - dy_1 \wedge dx_2 \wedge dx_3 - dy_1 \wedge dy_2 \wedge dx_3,
\]

\[
 \hat{\varphi} = dx_1 \wedge dx_2 \wedge dy_3 + dx_1 \wedge dy_2 \wedge dx_3 + dy_1 \wedge dx_2 \wedge dx_3 - dy_1 \wedge dy_2 \wedge dy_3.
\]

Now we fix the affine structure on \( B \) associated to the local coordinate \( \{ x^1, x^2, x^3 \} \) and vary the Hessian metric \( g \) (or equivalently vary the potential \( \phi \)). The symplectic form \( \omega \), coming from the canonical one on \( T^*B \), does not change. However, the 3-forms \( \varphi \) and \( \hat{\varphi} \) are varying since the dual affine structure associated to \( \{ x^1, x^2, x^3 \} \) is changing.

In particular, if we run the Type IIB flow on \( \hat{X} \), by the calculation in \[FP21\], the flow reduces to the real Monge-Ampère flow of Hessian metrics

\[
 \partial_t g_{jk} = \frac{1}{4} \frac{\partial^2}{\partial x^j \partial x^k} \det g.
\]

The goal in this section is to prove the following:

**Theorem 2.1.**

Under the Type IIB flow \[1\], the associated 3-form \( \varphi \) satisfies the Type IIA flow \[FPPZc\]

\[
 \partial_t \varphi = \frac{1}{16} d\Lambda_\omega \wedge d(|\varphi|^2 \hat{\varphi}).
\]

**Proof.** By the definition of Legendre transform, we have

\[
 \frac{\partial x_j}{\partial x^k} = \frac{\partial^2 \phi}{\partial x^j \partial x^k} = g_{jk},
\]

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hence
\[ dx_1 \wedge dx_2 \wedge dx_3 = \det g \cdot dx^1 \wedge dx^2 \wedge dx^3. \]

On the other hand, as \( \varphi \wedge \dot{\varphi} = |\varphi|^2 \frac{\partial^3}{3!} \), we see that
\[ |\varphi|^2 = 4 \det g. \]

Because \( \Omega \) is holomorphic, both \( \varphi \) and \( \dot{\varphi} \) are closed. It follows that \( d(|\varphi|^2 \dot{\varphi}) = d|\varphi|^2 \wedge \dot{\varphi} \), and that
\[
\Lambda_\omega d(|\varphi|^2 \dot{\varphi}) = \sum_j \frac{\partial |\varphi|^2}{\partial x^j} \partial x^j \dot{\varphi}
\]
\[
= \frac{\partial |\varphi|^2}{\partial x^1} dx_1 \wedge dx_2 - \frac{\partial |\varphi|^2}{\partial x^1} dx_1 \wedge dx_3 + \frac{\partial |\varphi|^2}{\partial x^1} dx_2 \wedge dx_3
\]
\[- \frac{\partial |\varphi|^2}{\partial x^3} dy_1 \wedge dy_2 + \frac{\partial |\varphi|^2}{\partial x^3} dy_1 \wedge dy_3 - \frac{\partial |\varphi|^2}{\partial x^1} dy_2 \wedge dy_3.
\]

Consequently
\[
d\Lambda_\omega d(|\varphi|^2 \dot{\varphi}) = \left( \frac{\partial^2 |\varphi|^2}{\partial x_1 \partial x^1} + \frac{\partial^2 |\varphi|^2}{\partial x_2 \partial x^2} + \frac{\partial^2 |\varphi|^2}{\partial x_3 \partial x^3} \right) dx_1 \wedge dx_2 \wedge dx_3
\]
\[- d \left( \frac{\partial |\varphi|^2}{\partial x^1} \right) \wedge dy_2 \wedge dy_3 - dy_1 \wedge d \left( \frac{\partial |\varphi|^2}{\partial x^1} \right) \wedge dy_3 - dy_1 \wedge dy_2 \wedge d \left( \frac{\partial |\varphi|^2}{\partial x^3} \right).
\]

Therefore, to prove the theorem, we only need to show that
\[
\partial_t (dx_1 \wedge dx_2 \wedge dx_3) = \frac{1}{16} \left( \frac{\partial^2 |\varphi|^2}{\partial x_1 \partial x^1} + \frac{\partial^2 |\varphi|^2}{\partial x_2 \partial x^2} + \frac{\partial^2 |\varphi|^2}{\partial x_3 \partial x^3} \right) dx_1 \wedge dx_2 \wedge dx_3,
\]
\[
\partial_t (dx_j) = \frac{1}{16} \left( \frac{\partial |\varphi|^2}{\partial x^j} \right) \text{ for } j = 1, 2, 3.
\]

For the first identity above, we notice that
\[
\frac{1}{16} \sum_j \frac{\partial}{\partial x_j} \left( \frac{\partial |\varphi|^2}{\partial x^j} \right) = \frac{1}{4} \sum_{j,k} \frac{\partial}{\partial x_j} \frac{\partial^2}{\partial x_k \partial x^j} \det g = \sum_{j,k} g^{jk} \partial_t g_{jk} = \frac{\partial_t \det g}{\det g}.
\]

Therefore
\[
\partial_t (dx_1 \wedge dx_2 \wedge dx_3) = (\partial_t \det g) dx^1 \wedge dx^2 \wedge dx^3
\]
\[
= \frac{\det g}{16} \left( \frac{\partial^2 |\varphi|^2}{\partial x_1 \partial x^1} + \frac{\partial^2 |\varphi|^2}{\partial x_2 \partial x^2} + \frac{\partial^2 |\varphi|^2}{\partial x_3 \partial x^3} \right) dx_1 \wedge dx^2 \wedge dx^3
\]
\[
= \frac{1}{16} \left( \frac{\partial^2 |\varphi|^2}{\partial x_1 \partial x^1} + \frac{\partial^2 |\varphi|^2}{\partial x_2 \partial x^2} + \frac{\partial^2 |\varphi|^2}{\partial x_3 \partial x^3} \right) dx_1 \wedge dx_2 \wedge dx_3.
\]

From the evolution equation of \( g \), we know that there is an affine function \( l \) such that
\[
\partial_t \phi = \frac{1}{4} \det g + l,
\]
\[ l = \frac{1}{4} \det g. 
\]
\[ \partial_t(dx_j) = d\left( \partial_t \frac{\partial \phi}{\partial x^j} \right) = d \left( \frac{\partial}{\partial x^j} (\partial_t \phi) \right) = \frac{1}{4} d \left( \frac{\partial \det g}{\partial x^j} \right) = \frac{1}{16} d \left( \frac{\partial |\phi|^2}{\partial x^j} \right). \]

Remark 2.2. In [FP21], the dual Anomaly flow was defined as a flow of Hermitian metrics on the dual manifold. Thus the setting for both the original flow and its dual were in complex geometry, and the duality only holds modulo lower order terms. From this point of view, the symplectic and the geometric settings as described above are more naturally dual, as the duality is now exact.

Remark 2.3. In the above theorem, we made the choice of the phase angle so that \( \phi \) and \( \hat{\phi} \) have the expressions we worked with. In fact, it is well legitimate to choose \( \phi' = \phi \) and \( \hat{\phi}' = -\phi \) instead. By similar and straightforward computation, one can show that \( \phi' \) also satisfies the Type IIA flow

\[ \partial_t \phi' = \frac{1}{16} d\Lambda d(|\phi'|^2 \hat{\phi'}), \]

therefore Theorem 2.1 holds for arbitrary choice of the phase angle.

In Theorem 2.1 we showed that the Type IIA flow and Type IIB flow are related to each other by T-duality in the semi-flat limit. Following this idea, once we have a geometric flow in the complex setting, by applying T-duality, one may arrive at a natural flow in symplectic geometry. In particular, we can find the T-dual of the Kähler-Ricci flow in the symplectic world.

In [FP21], the semi-flat reduction of the Kähler-Ricci flow was shown to be given by

\[ \partial_t g_{jk} = \frac{1}{2} \frac{\partial^2}{\partial x^j \partial x^k} \log \det g. \]  

A similar calculation as in Theorem 2.1 yields the following theorem.

**Theorem 2.4.**

Under the Kähler-Ricci flow (3), the associated 3-form \( \phi \) satisfies the flow

\[ \partial_t \phi = \frac{1}{2} d\Lambda d(|\phi|^2 \hat{\phi}). \]  

By dropping the non-essential factor of \( \frac{1}{2} \), we shall call the flow

\[ \left\{ \begin{array}{l} \partial_t \phi = d\Lambda d(|\phi|^2 \hat{\phi}) \\ \phi_{t=0} = \phi_0 \end{array} \right. \]

the dual Ricci flow.

Due to the presence of the factor \( \log |\phi|^2 \) in (5), one can imagine that the short-time existence and uniqueness of (5) would be very challenging to establish, if there is such a theorem.
3 The Hitchin gradient flow on a symplectic manifold

We begin by recalling the functional introduced by Hitchin [Hit00]. Let $M$ be an oriented compact 6-manifold. Following [Hit00, Fei15], given any positive 3-form $\varphi$ on $M$, or equivalently any reduction of the structure group of $M$ to $\text{SL}(3, \mathbb{C})$, there is a naturally associated almost complex structure $J_\varphi$, and another 3-form $\hat{\varphi} = J_\varphi \varphi$, such that the form $\Omega = \varphi + \sqrt{-1} \hat{\varphi}$ is a nowhere vanishing $(3,0)$-form with respect to the almost complex structure $J_\varphi$.

The Hitchin functional is defined as

$$H(\varphi) = \frac{1}{2} \int_M \varphi \wedge \hat{\varphi}. $$

Assume now that $\varphi$ is closed. Hitchin proposed the variational problem of finding the critical points of $H(\varphi)$, subject to the constraint of $\varphi$ being in a given de Rham cohomology class. In particular, he showed in [Hit00] that

$$\delta H = \int_M \delta \varphi \wedge \hat{\varphi}. $$

Hence the critical points of $H(\varphi)$ are exactly those $\varphi$ such that $d \hat{\varphi} = 0$, or equivalently, such that $J_\varphi$ is integrable.

We would like to approach this problem by considering a gradient flow for the Hitchin functional. For this, we need to introduce a metric on $M$. A natural way to do so is to put a symplectic form $\omega$ on $M$. As shown in [FPPZc], the almost complex structure $J_\varphi$ is compatible with $\omega$ if and only if $\varphi$ is primitive with respect to $\omega$. In this way, we can rewrite Hitchin’s variational formula as

$$\delta H = \int_M (\delta \varphi, \varphi) \frac{\omega^3}{3!}. $$

Since the cohomology class of $\varphi$ is not changing, we may write $\delta \varphi = d \delta \beta$, so

$$\delta H = \int_M \langle d \delta \beta, \varphi \rangle \frac{\omega^3}{3!} = \int_M (\delta \beta, d^\dagger \varphi) \frac{\omega^3}{3!}. $$

Consequently the gradient flow of Hitchin’s functional is $\partial_t \beta = d^\dagger \varphi$, or

$$\partial_t \varphi = \partial_t d \beta = dd^\dagger \varphi. $$

In this form, the gradient flow of the Hitchin functional on a compact 6-dimensional symplectic manifold can be viewed as the 6-dimensional version of Bryant’s Laplacian flow on 7-manifolds, whose stationary points are given by manifolds with $G_2$-holonomy [Bry06].

Our first observation is that the symplectic version of the gradient flow for the Hitchin functional is actually a degenerate version of the Type IIA flow introduced in [FPPZc]:

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Theorem 3.1.
Let $M$ be a compact 6-dimensional manifold equipped with a symplectic form $\omega$. Then the gradient flow of the Hitchin functional with a closed, primitive, and positive initial 3-form can be equivalently expressed as
\[ \partial_t \varphi = d\Lambda_\omega d\hat{\varphi} \tag{6} \]

Proof. Note that, formally, the flow (6) preserves the closedness and primitiveness of $\varphi$. It suffices to prove the following identity
\[ dd^\dagger \varphi = d\Lambda_\omega d\hat{\varphi} \tag{7} \]
for any closed primitive positive 3-form $\varphi$. Since $d^\dagger \varphi = -\ast d^\ast \varphi = -\ast d\hat{\varphi}$, we only need to show that $-\ast d\hat{\varphi} = \Lambda_\omega d\hat{\varphi}$. But it follows from [FPPZc, Lemma 18] that $d\hat{\varphi}$ is the product of $\omega$ with a primitive $(1,1)$-form.

We observe that, just as the gradient flow of the 6-dimensional Hitchin functional is related to the Type IIA flow by Theorem 3.1, there is also a 7-dimensional version of Hitchin’s functional, whose gradient flow is exactly Bryant’s Laplacian flow for closed $G_2$-structures, as explained in [Lot20].

We show next that the symplectic flow (6) is weakly parabolic. For this we need to determine the eigenvalues of its principal symbol. We follow the procedure developed in [FPPZc] for the Type IIA flow. We start from the following formula derived in [FPPZc]
\[ \delta \hat{\varphi} = -J_\varphi (\delta \varphi) - 2\frac{\langle \delta \varphi, \hat{\varphi} \rangle}{|\varphi|^2} \varphi + 2\frac{\langle \delta \varphi, \varphi \rangle}{|\varphi|^2} \hat{\varphi}. \tag{7} \]
Since the symbol of the exterior differential is $\xi \wedge \cdot$, it follows that the symbol of the operator $\varphi \to d\Lambda_\omega d(\hat{\varphi})$ is given by
\[ \delta \varphi \to \xi \wedge \left\{ \Lambda_\omega \left[ \xi \wedge (-J_\varphi \delta \varphi - 2\frac{\langle \delta \varphi, \hat{\varphi} \rangle}{|\varphi|^2} \varphi + 2\frac{\langle \delta \varphi, \varphi \rangle}{|\varphi|^2} \hat{\varphi} \right] \right\}. \tag{8} \]

It is no loss of generality to assume that $\xi = e^1$, $|\varphi| = 1$, to write $J_\varphi = J$, $\Lambda_\omega = \Lambda$, and to work on an adapted frame for $\varphi$, where we have, as shown in [FPPZc]
\[ \omega = e^{12} + e^{34} + e^{56} \]
\[ \varphi = \frac{1}{2}(e^{135} - e^{146} - e^{245} - e^{236}), \quad \hat{\varphi} = \frac{1}{2}(e^{136} + e^{145} + e^{235} - e^{246}). \]

Note that in the frame $\{e_j\}$ of vectors, we have $J e_{2k-1} = e_{2k}$, $J(e_{2k}) = -e_{2k-1}$; so in this co-frame, we have $J(e_{2k-1}) = -e^{2k}$, $J(e^{2k}) = e^{2k-1}$. We need to
identify the eigenvalues of this operator, restricted to the subspace $W$ of 3-
foms $\delta \varphi$ satisfying the constraints resulting from $\varphi$ being closed and primitive

$$W = \{ \delta \varphi; \quad \xi \wedge \delta \varphi = 0, \quad \Lambda(\delta \varphi) = 0 \},$$

which can be worked out to be

$$W = e^1 \wedge W'$$

where $W'$ is the space of 2-forms $\gamma$ on the vector space $V'$ spanned by $\{e_j\}_{j=3}^6$, which satisfies the constraint $\Lambda'\gamma = 0$, where $\Lambda'$ is the Hodge contraction operator on $V'$ with respect to the symplectic form $\omega' = e^{34} + e^{56}$. Next we compute

$$\Lambda[e^1 \wedge (J\delta \varphi)] = \Lambda[e^1 \wedge (-e^2 \wedge J\varphi)] = -J\gamma$$

$$\Lambda[e^1 \wedge \hat{\varphi}] = \frac{1}{2}(e^{35} - e^{46})$$

$$\Lambda[e^1 \wedge \varphi] = -\frac{1}{2}(e^{45} + e^{36}).$$

We also work out the inner products $\langle \delta \varphi, \varphi \rangle$ and $\langle \delta \varphi, \hat{\varphi} \rangle$,

$$\langle \delta \varphi, \varphi \rangle = \frac{1}{2}(e^1 \wedge \gamma, e^{135} - e^{146}) = \frac{1}{2}(\gamma, e^{35} - e^{46})$$

$$\langle \delta \varphi, \hat{\varphi} \rangle = \frac{1}{2}(e^1 \wedge \gamma, e^{136} + e^{145}) = \frac{1}{2}(\gamma, e^{36} + e^{45}).$$

Thus the symbol map on $W'$ becomes

$$\gamma \rightarrow J\gamma + \langle \delta \varphi, \varphi \rangle(e^{45} + e^{36}) + \langle \delta \varphi, \hat{\varphi} \rangle(e^{35} - e^{46})$$

It is convenient to use the following basis for the 5-dimensional space $W'$,

$$\kappa = e^{34} - e^{56}, \quad \mu_1^+ = e^{45} \pm e^{36}, \quad \mu_2^\pm = e^{35} \pm e^{46}$$

which are all eigenvectors of $J$,

$$J(e^{34} - e^{56}) = (e^{34} - e^{56})$$

$$J(e^{45} + e^{36}) = -(e^{45} + e^{36}), \quad J(e^{45} - e^{36}) = e^{45} - e^{36}$$

$$J(e^{35} - e^{46}) = -(e^{35} - e^{46}), \quad J(e^{35} + e^{46}) = e^{35} + e^{46}.$$

The symbol becomes the following operator

$$\gamma \rightarrow J\gamma + \frac{1}{2}(\gamma, \mu_2^-)\mu_2^- + \frac{1}{2}(\gamma, \mu_1^+)\mu_1^+$$

This implies readily

**Lemma 3.2.** The above basis turns out to be all eigenvectors of the symbol map

$$\kappa \rightarrow \kappa, \quad \mu_1^+ \rightarrow 0, \quad \mu_2^+ \rightarrow \mu_2^+$$

$$\mu_1^- \rightarrow \mu_1^-, \quad \mu_2^- \rightarrow 0.$$
Thus the Hitchin gradient flow is more degenerate than the Type IIA flow, whose principal symbol only has one zero eigenvalue. This additional degeneracy prevents a proof of short-time existence for general symplectic manifolds and general data along the lines of [FPPZc]. Nevertheless, as we shall see in the next section, the Hitchin gradient flow exists on many interesting manifolds and exhibits a variety of remarkable phenomena. For the remaining part of this section, we shall just assume that the Hitchin gradient flow exists on a symplectic manifold, and derive the corresponding evolution equations for geometric quantities of interest, such as the metric $g_{ij}$ and $|\varphi|^2$.

The key point in this derivation is that the Type IIA structure is preserved under the flow (5), hence we are free to use various identities in Type IIA geometry developed in [FPPZc, FPPZa]. Otherwise, in [FPPZc] and [FPPZa], two different methods were given for deriving the evolution equations for the metric and the term $|\varphi|^2$ in the Type IIA flow. Both methods can be readily adapted to the present case of the Hitchin gradient flow. However, since the Hitchin gradient flow is given by a Laplacian, and the method of [FPPZa] gives explicit Bochner-Kodaira formulas for the Laplacian on 3-forms, it is easiest to just extract from [FPPZa] what we need.

Recall that the metric $g_\varphi$ is defined by $g_\varphi(X, Y) = \omega(X, J_\varphi Y)$. We denote it by just $g_{ij}$ for simplicity, and also consider the metric $\tilde{g}_{ij}$ defined by

$$
\tilde{g}_{ij} = |\varphi|^2 g_{ij} = \tilde{g}_{ij} = -\varphi_{j k p} \varphi_{i a b} \omega^{k a} \omega^{p b}.
$$

We consider first the flow of the metric $\tilde{g}_{ij}$, which is then given by

$$
\partial_t \tilde{g}_{ij} = -\partial_t \varphi_{j k p} \varphi_{i a b} \omega^{k a} \omega^{p b} + (i \leftrightarrow j)
$$

The contribution of $dd^\dagger$ has been worked out in [FPPZa], Lemma 14. It is given by

$$
-(dd^\dagger)_{j k p} \varphi_{i a b} \omega^{k a} \omega^{p b} + (i \leftrightarrow j)
$$

$$
= |\varphi|^2 \left\{ R g_{ij} - 2(\mathcal{D}_k N_{ij}^k + \mathcal{D}_k N_{ji}^k) + (-\nabla_\mu \nabla^\mu u + N^2) g_{ij} + 2(N_i^k j + N_j^k i) \partial_k u - 4(N^2)_{ij} + 8(N^2)_{ij} \right\}
$$

where the scalar function $u$ is defined by

$$
u = \log |\varphi|^2 \quad (15)
$$

and the quadratic expressions $N^2_+$ and $N^2_-$ in the Nijenhuis tensor are defined by

$$
(N^2_+)_ij = N^p k i N_{p k j}, \quad (N^2_-)_ij = N^k p i N_{p k j}.
$$

We can now make use of the following identities for the Nijenhuis tensor and the scalar curvature $R$ in Type IIA geometry established in [FPPZc]

$$
(N^2_+)_{ij} = 2(N^2_-)_{ij} - \frac{1}{4} |N|^2 g_{ij},
$$

$$
R = \Delta u - |N|^2 = \nabla_\mu \nabla^\mu u - |N|^2
$$

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and arrive at the following result:

**Lemma 3.3.** The flow of the metric $\tilde{g}_{ij}$ is given by

$$
\partial_t \tilde{g}_{ij} = -|\varphi|^2 \left\{ 2(\mathcal{D}_k N_{ij}^k + \mathcal{D}_k N_{ji}^k) - 2\partial_p u (N_j^p i + N_i^p j) - |N|^2 g_{ij} \right\}
$$

Here the covariant derivatives and scalar curvature are with respect to the metric $g_{ij}$.

Next, we derive the flow of $u = \log |\varphi|^2$ and of $g_{ij} = |\varphi|^{-2} \tilde{g}_{ij}$. We have

$$
\partial_t \log \det \tilde{g} = \tilde{g}^{ij} \partial_i \tilde{g}_{ij} = |\varphi|^{-2} \tilde{g}^{ij} \partial_i \tilde{g}_{ij} = -(6R - 6\nabla_\mu \nabla^\mu u) = -6(R - \Delta u).
$$

In view of the above formula relating $R$, $\Delta u$ and $|N|^2$ in Type IIA geometry, this reduces to

$$
\partial_t \log \det \tilde{g} = 6|N|^2. \tag{16}
$$

Since we also have

$$
\partial_t \log |\varphi|^2 = \frac{1}{6} \partial_t \log \det \tilde{g}
$$

we obtain the flow for $u = \log |\varphi|^2$,

$$
\partial_t \log |\varphi|^2 = |N|^2. \tag{17}
$$

The flow of $g_{ij}$ readily follows

$$
\partial_t g_{ij} = \partial_t (|\varphi|^{-2} \tilde{g}_{ij}) = |\varphi|^{-2} \partial_t \tilde{g}_{ij} - (\partial_t \log |\varphi|^2) |\varphi|^{-2} \tilde{g}_{ij}
$$

$$
= |\varphi|^{-2} \partial_t \tilde{g}_{ij} - (\partial_t \log |\varphi|^2) \tilde{g}_{ij}.
$$

We summarize the formulas in the following lemma:

**Lemma 3.4.** The flows of the metric $g_{ij}$ and of the scalar function $u = \log |\varphi|^2$ in the Hitchin gradient flow are given by

$$
\partial_t g_{ij} = -\left\{ 2(\mathcal{D}_k N_{ij}^k + \mathcal{D}_k N_{ji}^k) - 2\partial_p u (N_j^p i + N_i^p j) \right\}
$$

$$
\partial_t u = |N|^2.
$$

We note that the Hitchin functional certainly increases along its gradient flow. But the lemma implies a much stronger property, namely that the integrand in the functional is pointwise monotone increasing. Now the Ricci curvature in Type IIA geometry is given by

$$
\mathcal{D}_k N_{ij}^k + \mathcal{D}_k N_{ji}^k = R_{ij} + 2(N^2)_{ij} - (\nabla_i \nabla_j u)^J \tag{18}
$$

so that the above flows can also be rewritten as, with the notation $(\nabla_i \nabla_j u)^J = \frac{1}{2}(\nabla_i \nabla_j u + J_i^p J_j^q \nabla_p \nabla_q u)$ from FPPZ.
**Lemma 3.5.** The flows of the metric $g_{ij}$ and of the scalar function $u = \log |\varphi|^2$ in terms of the Ricci curvature are given by

$$
\partial_t g_{ij} = -\left\{2R_{ij} + 4(N^2)_{ij} - 2(\nabla_i \nabla_j u)^J - 2\partial_p u (N^i_{jp} + N^j_{pi})\right\},
$$

$$
\partial_t u = |N|^2.
$$

There is yet another natural way of rewriting this flow, using the Ricci curvature formula [FPPZc, Eq. (6.53), Eq. (6.59)]. Thus we get

**Lemma 3.6.** The flows of the metric $g_{ij}$ and of the scalar function $u = \log |\varphi|^2$ in the Hitchin gradient flow can also be written as

$$
\partial_t g_{ij} = -R_{ij} + R_{ji,jj} + 2\partial_p u (N^i_{jp} + N^j_{pi}),
$$

$$
\partial_t u = |N|^2 \tag{19}
$$

**Remark 3.7.** Formally the coupled system (19) makes sense for any compact symplectic manifold, therefore it can be viewed as a generalization of the gradient flow of Hitchin’s functional (6) to arbitrary symplectic manifolds.

**Remark 3.8.** The system (19) also shows that the gradient flow of the Hitchin functional can be viewed as a perturbation of the anti-complexified Ricci flow of Lé-Wang [LW01]. This is the gradient flow of the Blair-Ianus functional [BI86], which is the $L^2$ norm of the Nijenhuis tensor $N$. Explicitly, the gradient flow can expressed as

$$
\partial_t g_{ij} = -R_{ij} + R_{ji,jj}.
$$

We see that the first equation in (19) only differs from the anti-complexified Ricci flow by a first order term.

**Remark 3.9.** If we run the flow (6) on locally homogeneous half-flat symplectic manifolds (as in the case of [FPPZc, Section 9.3.2]), the induced flow of $g$ is exactly Lé-Wang’s anti-complexified Ricci flow because that $u$ is a constant in space. In particular, this flow can be used to find optimal compatible almost complex structures.

### 4 Examples

In this section, we present a few explicit examples of the gradient flow of 6D-Hitchin’s functional on locally homogeneous symplectic half-flat manifolds. These manifolds have been studied in [FPPZc] from the perspective of the Type IIA flow.

**Example 4.1.** Let $M$ be the nilmanifold constructed by de Bartolomeis-Tomassini [dBT06, Example 5.2]. The Lie algebra of the nilpotent Lie group is characterized by invariant 1-forms \{e^1, \ldots, e^6\} satisfying

$$
de^1 = de^2 = de^3 = de^5 = 0,
de^4 = e^{15}, \quad de^6 = e^{13}.
$$
Clearly $\omega = e^{12} + e^{34} + e^{56}$ defines an invariant symplectic structure. Moreover, this nilpotent Lie group admits co-compact lattices so all the constructions descend to compact nilmanifolds. Consider the ansatze 

$$\varphi = \varphi_{a,b} = (1 + a)e^{135} - e^{146} - e^{245} - e^{236} + b(e^{134} - e^{156}),$$

(20)

it is easy to check that $\varphi_{a,b}$ is primitive and closed for any $a, b$. The positivity condition for $\varphi_{a,b}$ is that 

$$\frac{1}{16} |\varphi|^4 = 1 + a - b^2 > 0.$$ 

By straightforward calculations, we get

$$|\varphi|^2 \dot{\varphi} = 4((1 + a - b^2)e^1 \wedge (e^{36} + e^{45}) + e^2 \wedge (be^{34} + (1 + a)e^{35} - e^{46} - be^{56})).$$

It follows that

$$d(|\varphi|^2 \dot{\varphi}) = 4e^{12}(e^{34} + 2be^{35} - e^{56}),$$

$$\Lambda_{\omega} d(|\varphi|^2 \dot{\varphi}) = 4(e^{34} + 2be^{35} - e^{56}),$$

$$d\Lambda_{\omega} d(|\varphi|^2 \dot{\varphi}) = 8e^{135}.$$

So the gradient flow of 6D-Hitchin’s functional reduces to the ODE system

$$\begin{cases} 
\dot{a} = \frac{2}{\sqrt{1 + a - b^2}}, \\
\dot{b} = 0 
\end{cases}$$

which can be solved explicitly

$$\begin{cases} 
(1 + a - b^2)^{3/2} = (1 + a_0 - b_0^2)^{3/2} + 3t, \\
b = b_0 
\end{cases}.$$

In particular the flow exists for all time and

$$|N|^2 = (1 + a - b^2)^{-3/2} = \frac{1}{(1 + a_0 - b_0^2)^{3/2} + 3t} \rightarrow 0,$$

as $t$ goes to infinity.

**Example 4.2.** Consider the symplectic half-flat structure on the solvmanifold $M$ constructed by Tomassini and Vezzoni in [TV08, Theorem 3.5]. The geometry of this solvmanifold is characterized by invariant 1-forms $\{e^j\}_{j=1}^6$ satisfying

$$\begin{align*}
\text{d}e^1 &= -\lambda e^{15}, & \text{d}e^2 &= \lambda e^{25}, & \text{d}e^3 &= -\lambda e^{36}, \\
\text{d}e^4 &= \lambda e^{46}, & \text{d}e^5 &= 0, & \text{d}e^6 &= 0,
\end{align*}$$

where $\lambda = \log \frac{3 + \sqrt{5}}{2}$. One can easily check that $\omega = e^{12} + e^{34} + e^{56}$ is an invariant symplectic form on $M$. Consider the ansatze

$$\varphi = \alpha(e^{135} + e^{136}) + \beta(e^{145} - e^{146}) + \gamma(e^{235} - e^{236}) - \delta(e^{245} + e^{246}).$$

(21)
A direct calculation gives
\[ |\varphi|^2 \dot{\varphi} = 8(-\alpha\beta\gamma(e_{135} - e_{136}) + \alpha\beta\delta(e_{145} + e_{146}) + \alpha\gamma\delta(e_{235} + e_{236}) + \beta\gamma\delta(e_{245} - e_{246})). \]

The nondegenerate condition is that
\[ |\varphi|^4 = 64\alpha\beta\gamma\delta > 0. \]
It follows that
\[ d(|\varphi|^2 \dot{\varphi}) = 16 \lambda (\alpha\beta\gamma e_{1356} + \alpha\beta\delta e_{1456} - \alpha\gamma\delta e_{2356} + \beta\gamma\delta e_{2456}), \]
\[ \Lambda_\omega d(|\varphi|^2 \dot{\varphi}) = 16 \lambda (\alpha\beta\gamma e_{13} + \alpha\beta\delta e_{14} - \alpha\gamma\delta e_{23} + \beta\gamma\delta e_{24}), \]
\[ d\Lambda_\omega d(|\varphi|^2 \dot{\varphi}) = 16 \lambda^2 (\alpha\beta\gamma(e_{135} + e_{136}) + \alpha\beta\delta(e_{145} + e_{146}) + \alpha\gamma\delta(e_{235} - e_{236}) - \beta\gamma\delta(e_{245} + e_{246})). \]

After linear time rescaling, the gradient flow of Hitchin’s functional under our ansatze reduces to
\[ \dot{\alpha} = \frac{\alpha\beta\gamma}{\sqrt{\alpha\beta\gamma\delta}}, \quad \dot{\beta} = \frac{\alpha\beta\delta}{\sqrt{\alpha\beta\gamma\delta}}, \quad \dot{\gamma} = \frac{\alpha\gamma\delta}{\sqrt{\alpha\beta\gamma\delta}}, \quad \dot{\delta} = \frac{\beta\gamma\delta}{\sqrt{\alpha\beta\gamma\delta}}. \]

For simplicity, let us assume that all of \(\alpha, \beta, \gamma, \delta\) are positive. It is easy to see that there exist positive constants \(C_1\) and \(C_2\) such that \(\alpha(t) = C_1\delta(t)\) and \(\beta(t) = C_2\gamma(t)\). The ODE system simplifies to
\[ \dot{\gamma} = \sqrt{\frac{C_1}{C_2}} \delta, \quad \dot{\delta} = \sqrt{\frac{C_2}{C_1}} \gamma. \]

Again this system can be solve explicitly as
\[ \alpha = \sqrt{\frac{C_1}{C_2}}(Ae^t + Be^{-t}), \quad \beta = \sqrt{\frac{C_2}{C_1}}(Ae^t - Be^{-t}), \quad \gamma = \frac{1}{\sqrt{C_2}}(Ae^t - Be^{-t}), \quad \delta = \frac{1}{\sqrt{C_1}}(Ae^t + Be^{-t}), \]
where \(A > 0, B\) are constants determined by initial data. In particular the flow exists for all time and \(\lim_{t\to\infty} |\varphi|^2 = \infty\). However, the limit \(\lim_{t\to\infty} J_t = J_\infty\) does exist. This is because
\[ \varphi_\infty := \lim_{t\to\infty} \frac{\varphi}{|\varphi|} = \sqrt{\frac{C_1}{8}}(e^{135} + e^{136}) + \sqrt{\frac{C_2}{8}}(e^{145} - e^{146}) + \sqrt{\frac{1}{8C_2}}(e^{235} - e^{236}) - \sqrt{\frac{1}{8C_1}}(e^{245} + e^{246}) \]
exists. In fact, \(J_\infty\) is a harmonic almost complex structure in the sense of [LW01], namely the Ricci curvature is \(J_\infty\)-invariant. In addition, \(\varphi_\infty\) satisfies
\[ d\Lambda_\omega d\varphi_\infty = 2\lambda^2 \varphi_\infty. \]

This case also provides an example of convergence of anti-complexified Ricci flow to a non-Kähler metric.
Remark 4.3. When $|\varphi|$ is a constant over space, the Hitchin gradient flow is simply a time-rescaled version of the Type IIA flow. Therefore we can use Raffero’s technique [Raf21] to produce many special solutions to the Hitchin gradient flow (6) as well.

5 Additional remarks

It may be worth considering the following $\epsilon$-regularization of the Hitchin gradient flow
\begin{equation}
\partial_t \varphi = d\Lambda_\omega d(|\varphi|^\epsilon \hat{\varphi})
\end{equation}
for each $\epsilon > 0$. The same arguments for the Type IIA flow show that the flow preserves primitiveness and should be a well-defined flow of Type IIA geometries. While we do not expect that the corresponding solutions will have a limit as $\epsilon \to 0$, it is conceivable that certain important notions may have a limit. A model situation may be Landau-Ginzburg models and renormalized energies. It is also intriguing that the dual Ricci flow can be interpreted as another limit of this regularization.

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