Slowly evolving geometry in recurrent neural networks I: the extreme dilution regime

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Abstract. We study extremely diluted spin models of neural networks in which the connectivity evolves in time, although adiabatically slowly compared to the neurons, according to stochastic equations which on average aim to reduce frustration. The (fast) neurons and (slow) connectivity variables equilibrate separately, but at different temperatures. Our model is exactly solvable in equilibrium. We obtain phase diagrams upon making the condensed ansatz (i.e. recall of one pattern). These show that, as the connectivity temperature is lowered, the volume of the retrieval phase diverges and the fraction of mis-aligned spins is reduced. Still one always retains a region in the retrieval phase where recall states other than the one corresponding to the ‘condensed’ pattern are locally stable, so the associative memory character of our model is preserved.

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1. Introduction

Most statistical mechanical studies of recurrent neural networks have traditionally been concerned with systems in which the dynamical variables are either the neurons (see e.g. [1 2 3 4] or the reviews [5 6] and references therein), or their interactions (or synapses, see e.g. [7 8 9 10] or the reviews [12 13 14] and references therein). The first type of processes describe network operation, whereas the second correspond to learning. These areas have by now been investigated quite extensively. In contrast, only a modest number of studies involved coupled dynamical laws for both neurons and interactions [15 16 17 18 19 20 21 22], to reflect the complex dynamical interplay between synapses and neurons found in the real brain. The approach usually adopted in the latter studies, to obtain analytically solvable models, is the introduction of a hierarchy of adiabatically separated time-scales, such that the fast variables (taken to be the neurons) are in equilibrium on the time-scales where the slow variables (the interactions, taken to be symmetric) evolve. One can also introduce further levels in
the hierarchy by introducing different classes of interactions, each evolving on different characteristic time-scales [22]. The resulting formalism involves nested replica theories, with Parisi matrices [23] in which the number of blocks at each level is the ratio of temperatures of subsequent levels in the hierarchy of equilibrating degrees of freedom. Such models can also serve to derive Parisi’s replica symmetry breaking scheme [24]. In neural network studies the dynamics of the interactions have usually been governed by Langevin equations in which the deterministic forces are proportional to expectation values of neuronal pair correlations (with the neuron state statistics corresponding to Boltzmann equilibrium, given the instantaneous values of the interactions), potentially biased to reflect the possibility of recall of a pattern. In [18, 19] the interactions were taken to evolve away from an initial state given by Hopfield’s [11] interaction matrix, with an extensive number of stored patterns. There it was found that for low interaction temperatures the network collapsed into an undesirable so-called ‘super-ferromagnetic’ state, whereas for negative replica dimension (corresponding to anti-Hebbian learning) the storage capacity of the network was found to be enhanced.

All papers dealing with the theory of coupled neuronal and interaction dynamics published so far assumed full connectivity: each neuron interacted with each other neuron, with the magnitude and sign of the interactions evolving in time. Here we propose and study a model of a symmetrically diluted recurrent neural network in which the geometry (or connectivity) is allowed to change slowly. On time-scales where the neuron variables are in thermodynamic equilibrium, the microscopic realization of the (discrete) dilution variables (reflecting the connectivity) is allowed to evolve slowly and stochastically, driven by forces aiming at a reduction of global frustration, without however changing the actual values of the bonds (the latter are frozen, given by Hopfield’s [11] recipe). It has been known that one may store information in recurrent neural networks solely by eliminating frustrated bonds, but this has always been done by hand (see e.g. [25] and references therein). Here the system is allowed to adapt its geometry autonomously. It should be emphasized that there is a important difference between having dynamic bonds with Hebbian type dynamical laws, as in [15, 16, 17, 20, 21, 22], and the present situation of having dynamic geometry with fixed Hebbian values for active bonds. The former definitions imply irreversible modification or even elimination of stored information, whereas in the present paper, since the values assigned to the active bonds are not modified, the slow adaptation is fully reversible (one can always return to random dilution) and all stored information is retained.

The scaling with the system size $N$ chosen for the average connectivity $c$ in the system (the average number of bonds per spin) will have a strong influence on the structure of the resulting theory. In this first paper we consider the so-called ‘extreme dilution’ regime [26], defined by $\lim_{N \to \infty} c^{-1} = \lim_{N \to \infty} c/N = 0$ (a second paper will be devoted to the finite connectivity regime, where $c = \mathcal{O}(N^0)$ as $N \to \infty$). We solve our coupled spin and geometry dynamics model analytically, in replica symmetric ansatz. We find that, as a result of the connectivity adaptation, the network geometry becomes more ordered to boost retrieval of condensed patterns, as a result of which
the system’s retrieval phase is enhanced compared to that of the corresponding network with a quenched random connectivity matrix as studied in [26], and that the fraction of ‘misaligned spins’ is reduced as the temperature of the connectivity variables is lowered. Yet one still retains regions in the phase diagram where the alternative (presently non-condensed) pure retrieval states remain locally stable, so that the system continues to function as an associative memory.

2. Definitions

We study diluted Hopfield [1] type recurrent neural networks, with (fast) binary neurons \( \sigma_i \in \{-1, 1\} \) (denoting quiet versus firing states) and \( i = 1, \ldots, N \). The geometry of the system is defined by connectivity variables \( c_{ij} \in \{0, 1\} \), with \( c_{ji} = c_{ij} \) and \( c_{ii} = 0 \). Our neurons evolve according to Glauber-type local field alignment at temperature \( T = \beta^{-1} \), with the fields defined by \( h_i = \sum_j \frac{c_{ij}}{c} \sum_{\mu=1}^{p} \xi_{\mu} \xi_{j}^\mu \sigma_j \), i.e. with Hebbian interactions whenever \( c_{ij} = 1 \) (when a bond \((i, j)\) is present). For frozen geometry \( \{c_{ij}\} \) our Ising spin neurons would equilibrate to a Boltzmann state characterized by the Hamiltonian:

\[
H_f(\sigma, c) = -\sum_{i<j} \frac{c_{ij}}{c} \sum_{\mu=1}^{p} \xi_{\mu} \xi_{j}^\mu \sigma_i \sigma_j
\]

Here \( \sigma = (\sigma_1, \ldots, \sigma_N) \) and \( c = \{c_{ij}\} \). The \( \{\xi_{\mu}^\mu\} \in \{-1, 1\} \) with \( \mu = 1, \ldots, p \) represent \( p \) fixed patterns \( \xi^\mu = (\xi_{1}^\mu, \ldots, \xi_{N}^\mu) \) to be stored and hopefully recalled. Instead of frozen, we now take our geometry to also evolve in time, albeit on time-scales much larger than those of the neuronal relaxation (so the neurons can always be assumed in equilibrium, given the instantaneous geometry). This slow process is again taken to be of a Glauber type, but at temperature \( \tilde{T} = \tilde{\beta}^{-1} \) and with the connectivity Hamiltonian:

\[
H_s(c) = -\frac{1}{\beta} \log Z_f(c) + \frac{1}{\tilde{\beta}} \log \left( \frac{N}{c} \right) \sum_{i<j} c_{ij}
\]

\[
Z_f(c) = \sum_{\sigma} e^{-\beta H_f(\sigma, c)}
\]

The second term in (2) acts as a chemical potential, ensuring an average number of \( c \) connections per neuron. The pre-factor \( 1/\tilde{\beta} \) will be found helpful later.

The properties of our system at the largest time-scales, where also the geometry has equilibrated, are characterized by the partition sum of the slow variables:

\[
Z_s = \sum_c e^{-\tilde{\beta} H_s(c)} = \sum_c [Z_f(c)]^{\tilde{\beta}/\beta} e^{-\log(\xi) \sum_{i<j} c_{ij}}
\]

This sum is interpreted as describing \( n = \tilde{\beta}/\beta \) replicated copies of the fast system, leading to a replica theory with finite replica dimension \( n \). Minimization of \( H_s(c) \) should give a ‘smart’ arrangement of the geometry \( \{c_{ij}\} \), tailored to the realization of the patterns, but constrained to give an average connectivity \( c \). In the remainder of this paper we calculate phase diagrams and the fraction of mis-aligned spins. Phases are characterized by the values of the replicated overlap and spin glass order parameters:

\[
m^\mu_\alpha = \lim_{N \to \infty} N^{-1} \sum_i \langle \xi_{i}^\mu \sigma_{i}^\alpha \rangle \quad q_{\alpha\beta} = \lim_{N \to \infty} N^{-1} \sum_i \langle \sigma_{i}^\alpha \sigma_{i}^\beta \rangle
\]
Here \( \langle \ldots \rangle \) denotes averaging over all geometries \( \{c_{ij}\} \) and all spin-configurations \( \sigma^\alpha \) in each of the replicas \( \alpha = 1, \ldots, n \), with the Boltzmann measure associated with (4): 
\[
\langle G(\{\sigma^\alpha\}, c) \rangle = Z_s^{-1} \sum_{\{\sigma^\alpha\}} \sum_c G(\{\sigma^\alpha\}, c)
\]
\[
\times \exp \left\{ \beta \sum_{i<j} c_{ij} \sum_\mu \xi_i^\mu \xi_j^\mu \sum_{\alpha=1}^n \sigma_i^\alpha \sigma_j^\alpha - \log \left( \frac{N}{c} \right) \sum_{i<j} c_{ij} \right\}
\]
(6)

3. Equilibrium analysis

3.1. Calculation of the RS free energy

The thermodynamic properties of the stationary state, with equilibrated geometry, are derived from the asymptotic free energy per spin \( f = -\lim_{N \to \infty} (\beta N)^{-1} \log Z_s \). Upon performing the trace over all geometries in (4) one obtains, with \( \sigma_i = (\sigma_1^i, \ldots, \sigma_n^i) \):
\[
Z_s = \sum_{\sigma_1^i \ldots \sigma_n^i} \prod_{i<j} \left[ 1 + \frac{c}{N} e^{\frac{\beta}{2} \sum_{i,j} (\sigma_i \cdot \sigma_j) + \frac{\beta^2}{4n} \sum_{i,j} (\sigma_i \cdot \sigma_j)^2 + O(\frac{1}{N})} \right]
\]
(7)

In evaluating the free energy we make the usual ‘condensed’ ansatz: only a finite number \( r \) of patterns will be structurally correlated with the system state. The remaining \( n - r \) patterns can be treated as frozen disorder, over which the free energy may be averaged. For the result we write \( [f]_{\text{dis}} \). In this paper we work within the connectivity scaling regime of extreme dilution, where \( \lim_{N \to \infty} \frac{c}{N} = \lim_{N \to \infty} c^{-1} = 0 \). Now one obtains
\[
-\beta [f]_{\text{dis}} = \lim_{N \to \infty} \frac{1}{N} \log \sum_{\sigma^1 \ldots \sigma^n} e^{\frac{\beta}{2n} \sum_{i,j} (\sigma_i \cdot \sigma_j) + \frac{\beta^2}{4n} \sum_{i,j} (\sigma_i \cdot \sigma_j)^2 + O(\frac{1}{N})}
\]
(8)

(modulo irrelevant additive constants). We define the familiar pattern and state overlaps \( m_{\alpha \mu}(\sigma) = N^{-1} \sum_i \xi_i^\alpha \sigma_i \) and \( q_{\alpha \beta}(\{\sigma\}) = N^{-1} \sum_i \sigma_i^\alpha \sigma_i^\beta \). They are introduced via appropriate \( \delta \)-distributions, so that the spin traces can be carried out. This results in the usual type of steepest descent expression for \([f]_{\text{dis}}\) (again modulo constants):
\[
[f]_{\text{dis}} = \text{extr}_{(m_{\alpha \mu}, q_{\alpha \beta})} \left\{ \frac{\alpha \beta}{4n} \sum_{\alpha \neq \beta} q_{\alpha \beta}^2 + \frac{1}{2n} \sum_{\alpha \mu \leq r} m_{\alpha \mu}^2 \right. \]
\[
- \frac{1}{n \beta} \left\langle \log \sum_{\sigma_1 \ldots \sigma_n} e^{\beta \sum_{\alpha \leq r} m_{\alpha \mu} \xi_\alpha \sigma_\alpha + \frac{\alpha \beta}{4} \sum_{\alpha \neq \beta} q_{\alpha \beta} \xi_\alpha \sigma_\beta} \right\rangle \right\}
\]
(9)

where \( \langle g(\xi) \rangle = 2^{-r} \sum_{\xi \in \{-1,1\}^r} g(\xi) \). The parameter \( c \) represents the ensemble averaged connectivity. This follows upon adding suitable generating fields to the slow Hamiltonian: \( H_s(c) \rightarrow H_s(c) + \frac{\Delta c}{c} \sum_{i<j} c_{ij} \). Repeating the above calculation with the added fields shows that \( \lim_{N \to \infty} \frac{2}{N c} \sum_{i<j} c_{ij} = \lim_{\lambda \to 0} \frac{\partial [f]_{\text{dis}}}{\partial \lambda} = 1 \), which proves our claim.

We next make the replica-symmetric (RS) ansatz for the physical saddle-point:
\[
m_{\alpha \mu} = m_{\mu} \quad \text{for all} \quad (\alpha, \mu) \quad \text{and} \quad q_{\alpha \beta} = q + \delta_{\alpha \beta}(1 - q) \quad \text{for all} \quad (\alpha, \beta),
\]
keeping in mind that the replica dimension \( n \) can take any non-negative value:
\[
[f]_{\text{dis}}^{\text{RS}} = \text{extr}_{(m_{\mu}, q)} \left\{ \frac{1}{2} \sum_{\mu \leq r} m_{\mu}^2 + \frac{1}{4} \alpha \beta [2q + (n - 1)q^2] \right\}
\]
Variation of \( \{ m_\mu, q \} \) gives the saddle-point equations for our RS order parameters, with the short-hand \( \Xi = \beta (\sum_{\mu \leq r} m_\mu \xi_\mu + z \sqrt{\alpha q}) \), which are of the familiar form

\[
\begin{align*}
m_\mu &= \left< \xi_\mu \frac{\int Dz \: \tanh(\Xi) \cosh^n(\Xi)}{\int Dz \: \cosh^n(\Xi)} \right>/\xi \\
qu &= \left< \frac{\int Dz \: \tanh^2(\Xi) \cosh^n(\Xi)}{\int Dz \: \cosh^n(\Xi)} \right>/\xi
\end{align*}
\]

(12) (13)

The physical meaning of the RS order parameters is

\[
m_\mu = \lim_{N \to \infty} N^{-1} \sum_i \langle \xi_\mu \sigma_i \rangle \quad \text{and} \quad q = \lim_{N \to \infty} N^{-1} \sum_i \langle \sigma_i^2 \rangle,
\]

as usual.

3.2. Phase transitions and phase diagrams

If one simplifies matters further by assuming only one pattern to be condensed, i.e. \( m_\mu = m\delta_{\mu,1} \), then equations (12,13) reduce to

\[
\begin{align*}
m &= \frac{\int Dz \: \tanh[\beta (m + z \sqrt{\alpha q})] \cosh^n[\beta (m + z \sqrt{\alpha q})]}{\int Dz \: \cosh^n[\beta (m + z \sqrt{\alpha q})]} \\
q &= \frac{\int Dz \: \tanh^2[\beta (m + z \sqrt{\alpha q})] \cosh^n[\beta (m + z \sqrt{\alpha q})]}{\int Dz \: \cosh^n[\beta (m + z \sqrt{\alpha q})]}
\end{align*}
\]

(14) (15)

These are recognized to be identical to those of the finite \( n \) model studied in [27] if we re-define the parameters in the latter according to

\[
J^{(1)}(1) m/k \to m \quad J^{(2)} q/k \to \alpha \beta q
\]

(16)

This makes sense, since the \( n \to 0 \) limit of our present model (i.e. the symmetrically extremely diluted Hopfield model with quenched random connectivity [26]) is known to map onto the \( n \to 0 \) limit of [27] (i.e. the SK model [28]). Clearly one finds simplified equations for the special dimension values \( n = 1 \) (equivalent to having annealed geometry) and \( n = 2 \), where the Gaussian integrals can be done. For instance, at \( n = 1 \) the equation for \( m \) reduces to \( m = \tanh(\beta m) \), whereas for \( n = 2 \) one finds

\[
\begin{align*}
n = 2 : \quad m &= \frac{\sinh(2\beta m)}{\cosh(2\beta m) + e^{-2\alpha \beta^2 q}} \\
q &= \frac{\cosh(2\beta m) - e^{-2\alpha \beta^2 q}}{\cosh(2\beta m) + e^{-2\alpha \beta^2 q}}
\end{align*}
\]

(17)

Our RS equations admit three phases: a paramagnetic phase (P) with \( m = q = 0 \), a recall phase (R) where \( m \neq 0 \) and \( q > 0 \), and a spin-glass phase (SG) where \( m = 0 \) but \( q > 0 \). Since deriving the RS phase transitions has been reduced to appropriate translation of the results found in [27], we will here simply mention the outcome:

- For sufficiently small \( \alpha \) one will find a P \( \to \) R transition at a finite temperature. For \( \alpha < \alpha_c = \frac{1}{3n-2} \) this transition is second order, and occurs at \( T_R = 1 \).
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Figure 1. RS phase diagram in the space of control parameters. We show the critical temperature(s) as surface(s) over the \((\alpha, n)\) plane. The high temperature phase is paramagnetic (P). At low temperature we find the retrieval phase R. For \((\alpha, n)\) values with two critical temperatures, the latter define the boundaries of a spin-glass phase SG. The P\(\rightarrow\)R transitions are second order for \(\alpha < \frac{1}{3n-2}\), and first order elsewhere. The P\(\rightarrow\)SG transitions are second order for \(n < 2\) and first order elsewhere. For large \(\alpha\) the SG\(\rightarrow\)R transitions become second order, but for small \(\alpha\) they are first order.

- For larger \(\alpha\), lowering temperature will lead first to a P\(\rightarrow\)SG transition, followed at some yet lower temperature by a SG\(\rightarrow\)R transition\(\dagger\). For \(n \leq 2\) the P\(\rightarrow\)SG transition is second order, and occurs for \(T_{SG} = \sqrt{\alpha}\).
- The SG\(\rightarrow\)R transition is second order for \(\alpha \rightarrow \infty\), where its transition temperature tends to \(T_c = n\), but first order for sufficiently small \(\alpha\).
- The effects of increasing the replica dimension \(n\) are (i) a reduction of the size in the phase diagram of the SG phase, and (ii) a change of the orders of the P\(\rightarrow\)R and P\(\rightarrow\)SG transitions, from second order (for small \(n\)) to first order (for large \(n\)).

Numerical solution of equations (14,15) leads to the RS phase diagram drawn in figure 1. Figure 2 shows intersections of this diagram in the planes of constant replica dimension \(n = 0.1\) and \(n = 2\). All transitions discussed and drawn above refer to bifurcations of locally stable solutions, since for recurrent neural networks the time-scales where thermodynamic stability would become an issue are in practice never reached.

We finally turn to replica symmetry breaking (RSB). The location in our phase diagram of second order RSB phase transition follow upon inspection of the eigenvalues of the Hessian. Since our model can be mapped onto the nonzero-\(n\) SK-model [27], we can read off the eigenvalues from [29]. The dangerous eigenvalue \(\lambda_{RSB}\) is the one

\(\dagger\) For small values of \(n\), the latter SG\(\rightarrow\)R transition is expected to disappear when replica symmetry breaking is taken into account.
Figure 2. Intersections of the phase diagram shown in figure 1 at $n = 0.1$ (left) and $n = 2$ (right). We have paramagnetic (P), recall (R) and spin-glass (SG) phases. We note that there is no critical value for $\alpha$ above which recall is no longer possible. Instead the SG→R transition line will approach the line $T = n$ for large $\alpha$. Since RSB phenomena appear to be confined to $n < 1$ (see below), this is not an artifact of the RS assumption. For large $n$ all phase transitions ultimately become first order.

Figure 3. Location of the AT instability $n_c$, shown as a function of the inverse temperature $\beta = T^{-1}$, and for a number of different storage ratios $\alpha$. Replica symmetry breaking is seen to be limited to values of $n$ below 0.32. We also note the non-monotonic dependence on temperature of the critical dimension $n_c$ for fixed $\alpha$.

associated with the so-called replicon mode:

$$\lambda_{\text{RSB}} = \alpha \beta^2 \left[ 1 - \alpha \beta^2 [1 - 2q + h(m, q)] \right]$$

$$h(m, q) = \frac{\int Dz \, \tanh^{4}[\beta(m + z \sqrt{\alpha q})] \cosh^n[\beta(m + z \sqrt{\alpha q})]}{\int Dz \, \cosh^n[\beta(m + z \sqrt{\alpha q})]}$$
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Replica symmetry is stable only if $\lambda_{RSB} > 0$. For each combination $(\alpha, T)$ one finds a critical value $n_c(\alpha, T)$ (the AT line) below which replica symmetry is unstable. Examples of the behaviour of $n_c(\alpha, T)$ are shown in figure 3. Replica symmetry breaking is found to occur only for $n < 0.32$.

Compared to diluted neural network models with static random geometry, the main effect of introducing dynamic geometry (with the present Glauber dynamics, aimed at reducing frustration) is to reduce the spin-glass phase in favour of the recall phase. The geometry adjusts itself autonomously in order to retrieve the condensed pattern optimally, to such an extent that for sufficiently low temperature there is no upper limit on the storage ratio (provided we do not leave the ‘extreme dilution’ scaling regime $\lim_{N \to \infty} c/N = \lim_{N \to \infty} c^{-1} = 0$). This then raises the question of whether the other (non-condensed) patterns can be retrieved at all after the geometry has been tailored to the recall of one specific condensed pattern. This is investigated in section 5.

4. Fraction of misaligned spins

We expect the observed improvement of retrieval performance due to the slow geometry dynamics to be reflected in a reduction with increasing $n$ of the fraction of frustrated bonds in the system. To verify this we calculate a different but similar quantity: the fraction $\phi$ of misaligned spins, i.e. those where $\sigma_i$ and local field $h_i$ have opposite sign:

$$\phi = \lim_{N \to \infty} \frac{1}{N} \sum_i \left[ \langle \theta[-\sigma_i \sum_j \frac{\xi_j}{c} \sum_{\mu} \xi_{\mu i}^p \sigma_j] \rangle \right]_{\text{dis}}$$

To calculate this object one could introduce further replicas, but here we follow an alternative route: we solve our model first for finite $c$, in which case joint replicated spin-field distributions (in terms of which $\phi$ can be expressed) become the natural order parameters, followed by taking the limit $c \to \infty$.

4.1. Calculation of the joint spin-field distribution

To do so we have to adapt and generalize the calculation in e.g. \cite{30} by first introducing the $2^p$ so-called sub-lattices \cite{31}, with $\xi_i = (\xi_i^1, \ldots, \xi_i^p)$:

$$I_{\xi} = \{ i | \xi_i = \xi \} \quad p_{\xi} = |I_{\xi}|/N$$

Since $c$ is assumed finite, so is $p = \alpha c$. We write $\sum_{\xi} p_{\xi} \Phi(\xi) = \langle \Phi(\xi) \rangle_{\xi}$; for randomly drawn patterns $\lim_{N \to \infty} p_{\xi} = 2^{-p}$. For finite $c$ our analysis will start to resemble that in e.g. \cite{32}. In each sublattice we may define a joint distribution for replicated spins and fields, and (with a modest amount of foresight) conjugate fields:

$$P_{\xi}(\sigma, h, \hat{h}) = |I_{\xi}|^{-1} \sum_{i \in I_{\xi}} \delta_{\sigma_i \sigma} \delta[h - h_i(\{\sigma\})] \delta[\hat{h} - \hat{h}_i(\{\sigma\})]$$

where $\sigma \in \{-1, 1\}^n$, $h, \hat{h} \in \mathbb{R}^n$, and $h_i^\alpha(\{\sigma\}) = \sum_j \frac{\xi_j}{c} (\xi_i \cdot \xi_j) \sigma_j^\alpha$. In evaluating the free energy per spin we write the fast Hamiltonian in terms of replicated fields, and introduce \cite{22} by inserting suitable integrals over $\delta$-functions. This is done first
only for discrete values of \( h \), with the continuum limit (converting integrals into path integrals) to be taken after the thermodynamic limit. We abbreviate \( \{dPd\hat{P}\} = \prod_{\xi, \sigma, h, \tilde{h}}[dP\xi(\sigma, h) d\hat{P}\xi(\sigma, h)] \) and find

\[
-\beta f = \lim_{N \to \infty} \frac{1}{N} \log \sum_{\sigma} \sum_{\sigma' \ldots \sigma^n} c_i \sum_{i < j} \xi_{i,j}(\{\xi\})^{-\log(\lambda)} \sum_{i \in \mathcal{I}} \xi_i \]

\[
= \lim_{N \to \infty} \frac{1}{N} \log \int \{dPd\hat{P}\} e^{N(\sum_{\sigma} \int dh \hat{h} P\xi(\sigma, h) \left[ i\hat{P}\xi(\sigma, h) + \frac{1}{2} \beta(\sigma \cdot h) \right] \xi)}
\]

\[
\times \prod_i \left[ \frac{dh_i d\hat{h}_i e^{i\hat{h}_i h_i}}{(2\pi)^n} \right] \sum_{\sigma_1 \ldots \sigma^n} e^{-i\sum_i \sum_{i \in \mathcal{I}} \xi_i \hat{P}\xi(\sigma, h, \hat{h})} \sum_{i \in \mathcal{I}} \xi_i \hat{P}\xi(\sigma, h, \hat{h})
\]

\[
= \lim_{N \to \infty} \frac{1}{N} \log \int \{dPd\hat{P}\} e^{N(\sum_{\sigma} \int dh \hat{h} P\xi(\sigma, h) \left[ i\hat{P}\xi(\sigma, h) + \frac{1}{2} \beta(\sigma \cdot h) \right] \xi)}
\]

\[
\times e^{\frac{N}{2}(\sum_{\sigma} \int dh \hat{h} P\xi(\sigma, h) \left[ i\hat{P}\xi(\sigma, h) + \frac{1}{2} \beta(\sigma \cdot h) \right] \xi)}
\]

\[
\times \prod_i \left[ \frac{dh_i d\hat{h}_i e^{i\hat{h}_i h_i}}{(2\pi)^n} \right] \sum_{\sigma_1 \ldots \sigma^n} e^{\left\{ \sum_{i \in \mathcal{I}} \xi_i \hat{P}\xi(\sigma, h, \hat{h}) \right\}}
\]

\[
= \text{extr}_{\{P, \hat{P}\}} \left\{ \left\langle \sum_{\sigma} \int dh \hat{h} P\xi(\sigma, h, \hat{h}) \left[ i\hat{P}\xi(\sigma, h, \hat{h}) + \frac{1}{2} \beta(\sigma \cdot h) \right] \xi) \xi' \right\rangleight.
\]

\[
+ \frac{1}{2} c \left\langle \sum_{\sigma} \int dh \hat{h} P\xi(\sigma, h, \hat{h}) \left[ i\hat{P}\xi(\sigma, h, \hat{h}) + \frac{1}{2} \beta(\sigma \cdot h) \right] \xi) \xi' \right\rangleight.
\]

\[
\left. + \langle \log \left\{ \int \left[ \frac{dh \hat{h}}{(2\pi)^n} e^{i\hat{h} h} \right] \sum_{\sigma \in (-1,1)^n} e^{-i\hat{P}\xi(\sigma, h, \hat{h})} \right\} \xi) \xi' \right\rangle \right( \right) (23)
\]

Extremization with respect to \( P\xi(\sigma, h, \hat{h}) \) and \( \hat{P}\xi(\sigma, h, \hat{h}) \) gives the following two saddle-point equations:

\[
\hat{P}\xi(\sigma, h, \hat{h}) = ic \left\langle \sum_{\sigma} \int dh' P\xi(\sigma', h') e^{\frac{1}{2}(\xi(\sigma') + (h' \cdot \sigma))} \xi' \right\rangle e^{-\frac{1}{2} \beta(\sigma \cdot h)} \right) (24)
\]

\[
P\xi(\sigma, h, \hat{h}) = e^{i\hat{h} h - i\hat{P}\xi(\sigma, h, \hat{h})} \int \frac{dh' \hat{h}' e^{i\hat{h}' h'}}{\sigma \in (-1,1)^n} e^{-i\hat{P}\xi(\sigma', \hat{h}', \sigma')} \right) (25)
\]

Insertion of (21) into (24) gives a saddle-point equation in terms of \( P \) only:

\[
P\xi(\sigma, h, \hat{h}) = \frac{Z_\xi Z e^{-\frac{1}{2} \beta(\sigma \cdot h)}}{\int dh' \hat{h}' e^{i\hat{h}' h'} \sum_{\sigma \in (-1,1)^n} e^{-i\hat{P}\xi(\sigma', \hat{h}', \sigma')} \right) (26)
\]
with $Z_{\xi}$ denoting a normalization constant. According to (22), the physical meaning of the saddle-point is

$$P_{\xi}(\sigma, h, \hat{h}) = \lim_{N\to\infty} \frac{1}{|I_\xi|} \sum_{\{\sigma\}} \frac{\langle \delta\sigma, \delta[h - h_i(\{\sigma\})] \delta[h - \hat{h}_i(\{\sigma\})] \rangle}{\langle \delta\sigma, \delta[h - h_i(\{\sigma\})] \delta[h - \hat{h}_i(\{\sigma\})] \rangle}$$  \hspace{1cm} (27)

We next make the one pattern condensed ansatz (this is not essential for being able to proceed, but will simplify and compactify our derivation significantly), which here implies $P_{\xi}(\sigma, h, \hat{h}) = P_{\xi_1}(\sigma, h, \hat{h})$, and we send $c \to \infty$. As a result $(\xi \cdot \xi')/\sqrt{c} = \xi_1 \xi_1'/\sqrt{c} + \sqrt{\alpha z}$ where $z$ is a zero-average unit-variance Gaussian variable, and

$$P_{\xi}(\sigma, h, \hat{h}) = Z_{\xi}^{-1} e^{-\hat{h} \cdot h + \frac{1}{2}(\sigma \cdot h) - \sum_{\{\sigma, h\}} \int dh' P_{\xi'}(\sigma', h') \left[ i(\xi \cdot h') + (\sigma' \cdot h') + \frac{1}{2} (\sigma' \cdot h')^2 \right]}_{\xi'}$$  \hspace{1cm} (28)

In the right-hand side of (28) we are seen to need only the following moments of our distributions (which include the previously encountered $\{m_\alpha, q_{\alpha\beta}\}$):

$$m_\alpha = \langle \xi \sum_{\sigma} \int dh \ P_{\sigma}(\sigma, h) \rangle_{\xi} \quad q_{\alpha\beta} = \langle \sum_{\sigma} \int dh \ P_{\sigma}(\sigma, h) \rangle_{\xi}$$

$$k_\alpha = i \langle \xi \sum_{\sigma} \int dh \ P_{\sigma}(\sigma, h) \rangle_{\xi} \quad L_{\alpha\beta} = \langle \sum_{\sigma} \int dh \ P_{\sigma}(\sigma, h) \rangle_{\xi}$$

$$K_{\alpha\beta} = i \langle \sum_{\sigma} \int dh \ P_{\sigma}(\sigma, h) \rangle_{\xi}$$

Integration by parts over the fields in (28) shows that $k_\alpha = -\frac{1}{2} \beta m_\alpha$, $K_{\alpha\beta} = -\frac{1}{2} \beta q_{\alpha\beta}$, and $L_{\alpha\beta} = -\frac{1}{4} \beta^2 q_{\alpha\beta}$. The replicated joint spin-field distributions can now be written as

$$P_{\xi}(\sigma, h) = e^{\xi \cdot \sigma + \frac{1}{2} \beta \sigma \cdot h - \frac{1}{2} \sum_{\{\sigma, h\}} \int dh' P_{\xi'}(\sigma', h') \left[ i(\xi \cdot h') + (\sigma' \cdot h') + \frac{1}{2} (\sigma' \cdot h')^2 \right]}_{\xi}$$  \hspace{1cm} (29)

with $m = \{m_\alpha\}$ and $q = \{q_{\alpha\beta}\}$. The latter obey the following familiar closed equations which in RS ansatz lead one back to (12), as they should:

$$m_\alpha = \left\langle \xi \sum_{\sigma} \sigma_\alpha e^{\xi \cdot \sigma + \frac{1}{2} \beta \sigma \cdot q} \right\rangle_{\xi}$$  \hspace{1cm} (30)

$$q_{\alpha\beta} = \left\langle \xi \sum_{\sigma} \sigma_\alpha \sigma_\beta e^{\xi \cdot \sigma + \frac{1}{2} \beta \sigma \cdot q} \right\rangle_{\xi}$$  \hspace{1cm} (31)

4.2. Fraction of mis-aligned spins in RS ansatz

The fraction $\phi$ defined in (20) can be written as $\phi = \langle \phi_{\xi} \rangle_{\xi}$, where the sublattice fractions $\phi_{\xi}$ are expressed in terms of the replicated distributions (29) in the following way:

$$\phi_{\xi} = \frac{1}{2} - \frac{1}{2} \sum_{\sigma} \int dh \ P_{\xi}(\sigma, h) \frac{1}{n} \sum_{\gamma} \sigma_{\gamma} \text{sgn}[h_{\gamma}]$$

$$= \frac{1}{2} - \frac{1}{2n} \sum_{\gamma} \frac{\sigma_{\gamma} e^{\xi \cdot \sigma + \frac{1}{2} \beta \sigma \cdot q} \int dx \text{sgn}[m_\alpha + \alpha \beta q_{\beta\gamma} \sigma_{\gamma} + \sqrt{\alpha x_{\gamma}}] e^{-\frac{1}{2} x q^{-1} x}}{\sum_{\sigma} \sigma e^{\xi \cdot \sigma + \frac{1}{2} \beta \sigma \cdot q} \int dx e^{-\frac{1}{2} x q^{-1} x}}$$  \hspace{1cm} (32)
We see that the $\phi_1 = \phi_{-1}$. At this stage we make the RS ansatz, putting $m_\alpha = m$ and $q_{\alpha\beta} = q + \delta_{\alpha\beta}(1 - q)$, which results in

$$\phi_{RS} = \frac{1}{2} - \frac{1}{2} \int_D z \int \sigma_1 e^{\beta \int \sigma_2 \sigma_\alpha(m + z \sqrt{\alpha q}) + \sqrt{\alpha x}} \int_D z \int \sigma_1 e^{\beta \int \sigma_2 \sigma_\alpha(m + z \sqrt{\alpha q}) + \sqrt{\alpha x}}$$

We carry out the spin summations over $\sigma_\alpha$ with $\alpha > 1$. A shift in the complex plane for the variable $z$ in the numerator, $z \rightarrow z - \sqrt{q}(x - iy)$, followed by integration over $y$ and some simple manipulations, converts this expression into

$$\phi_{RS} = \frac{1}{2} - \frac{1}{4} \int_D z \int \sigma_1 e^{\beta \int \sigma_2 \sigma_\alpha(m + z \sqrt{\alpha q}) + \sqrt{\alpha x}} \int_D z \int \sigma_1 e^{\beta \int \sigma_2 \sigma_\alpha(m + z \sqrt{\alpha q}) + \sqrt{\alpha x}}$$

In the paramagnetic state, where $m = q = 0$, this simplifies further to

$$\phi_{RS} = \frac{1}{2} - \frac{1}{2} \text{Erf}[\beta \sqrt{\frac{1}{2}}]$$
In the recall and spin-glass states the evaluation of (33) requires the (numerical) solution of the RS order parameters \( \{m, q\} \) from (14). Examples of the resulting curves as functions of temperature are shown in figure 4, for \( \alpha \in \{0.1, 0.5, 1.0\} \) and \( n \in \{1, 2, 3, 4, 5\} \). We note that for these values of \( n \) replica symmetry should be stable. The fraction of misaligned spins is seen to decrease with increasing \( n \) (i.e. with decreasing connectivity temperature), as expected. This effect becomes more pronounced for larger \( \alpha \), where the amount of frustration to be reduced by the geometry dynamics should indeed be largest. In the paramagnetic phase (large \( T \)) we see that \( \phi_{RS} \) is independent of \( n \), in accordance with (34).

4.3. Comparison with numerical simulations

In order to perform numerical simulations, we need an explicit stochastic dynamical equation for updating of the network geometry variables \( \mathbf{c} = \{c_{ij}\} \), which must approach the appropriate Boltzmann equilibrium state characterized by the slow Hamiltonian (2). Here we used a Glauber type Markov process, where candidate bonds \( c_{ij} \) are drawn randomly at each iteration step and then flipped with probability \( W[F_{ij}\mathbf{c}; \mathbf{c}] \), where \( F_{ij} \) denotes the bond switch operator defined by \( F_{ij}c_{ij} = 1 - c_{ij}, F_{ij}c_{k\ell} = c_{k\ell} \) if \((i, j) \neq (k, \ell)\):

\[
W[F_{ij}\mathbf{c}; \mathbf{c}] = \frac{1}{2} \left\{ 1 - \tanh\left( \frac{\beta}{2} [H_s(F_{ij}\mathbf{c}) - H_s(\mathbf{c})]\right) \right\}
\]  

(35)

Detailed balance is built in. Upon inserting the slow Hamiltonian (2) and using the scaling property \( \lim_{N \to \infty} c/N = 0 \) of our present extreme dilution regime, one can for large \( N \) rewrite our transition probabilities as

\[
W[F_{ij}\mathbf{c}; \mathbf{c}] = \frac{1}{2} \left\{ 1 - \tanh\left[ \frac{1}{2} (2c_{ij} - 1) \log\left( \frac{c}{N}\right) + \frac{\beta}{c} \sum_\mu \xi_\mu^i \xi_\mu^j \langle \sigma_i \sigma_j \rangle \right] \right\}
\]  

(36)

where, as before, \( \langle \ldots \rangle \) indicates an equilibrium average for the fast system, in Boltzmann equilibrium with Hamiltonian (1), for a given connectivity matrix \( \mathbf{c} \).

In the present type of systems with multiple adiabatically separated time-scales and nested equilibrations, the verification of theoretical results by numerical simulations is known to be a highly demanding task. Even without the evolving geometry, full equilibration of the spins requires relaxation times which diverge with \( N \) faster than polynomially. If on top of this one aims to also approach geometry equilibrium, which involves \( O(N^2) \) stochastic degrees of freedom, the system sizes accessible in practice for numerical experimentation are small. Thus profound finite size effects are unavoidable. It turns out that, when simulating the process (36), geometry equilibration times are indeed extremely long, especially close to phase transitions. This limits our ambitions regarding size, with the standard CPU resources at our disposal, to the order of \( N \sim 10^2 \) spins. Since in our chosen scaling regime of extreme dilution we have to simultaneously minimize \( c^{-1} \) and \( cN^{-1} \), we have in our numerical experiments chosen \( c = \sqrt{N} \).

Different macroscopic quantities could in principle be used for testing our theory against experiments. The advantage of observables such as \( m \) and \( \phi \) is that they can
be measured instantaneously, in contrast to the spin-glass order parameter \( q \). Here we have opted for the fraction of misaligned spins \( \phi = N^{-1} \sum_i [\theta(-\sigma_i h_i)] \) (where \( h_i \) is the local field at site \( i \)), as functions of temperature. The data shown refer to \( \alpha = 0.5 \) with \( n = 2 \) (simulations: connected squares; theory: dashed lines) or \( n = 3 \) (simulations: connected circles; theory: dotted-dashed lines). Due to the need to equilibrate two nested disordered processes, conventional computer resources limit experimentation to modest values of \( N \). In spite of the resulting finite size effects, the graph does show satisfactory qualitative agreement between theory and experiment.

Figure 5. Comparison between simulation measurements (all with \( N = 200 \)) and RS theoretical predictions for the fraction of misaligned spins \( \phi = N^{-1} \sum_i [\theta(-\sigma_i h_i)] \) as functions of temperature. The data shown refer to \( \alpha = 0.5 \) with \( n = 2 \) (simulations: connected squares; theory: dashed lines) or \( n = 3 \) (simulations: connected circles; theory: dotted-dashed lines). Due to the need to equilibrate two nested disordered processes, conventional computer resources limit experimentation to modest values of \( N \). In spite of the resulting finite size effects, the graph does show satisfactory qualitative agreement between theory and experiment.

5. Stability of non-condensed retrieval states

The significant enlargement of the retrieval phase caused by our geometry adaptation (see e.g. figures 1 and 2) could have as a drawback that retrieval of patterns other than the condensed one becomes impossible. Here we address the question of whether the present ‘tayloring’ of the geometry variables \( \{c_{ij}\} \) to one condensed state will leave a finite basin of attraction for the non-condensed patterns, or whether recalling the latter requires a rewiring of the system (e.g. by temporarily raising the temperature \( \tilde{T} \)) to undo the established geometry. For large \( \alpha \) most retrieval states must be unstable for any given geometry in the extreme dilution scaling regime, since optimal capacity calculations a la Gardner for diluted networks predict a finite storage capacity \( [33] \).

To answer our question we will study a second (fast) spin system of \( N \) spins \( \tau = \{\tau_i\} \), governed again by the fast Hamiltonian \( [11] \), with patterns and geometry identical to that of the first. In particular, the connectivity statistics are again given by

\[
P(c) = Z_s^{-1} e^{-\beta H_s(c)}
\]
The slow Hamiltonian $H_s(c)$ continues to be defined in terms of the original spins $\sigma$, assumed in a condensed state characterized by a finite overlap with the first pattern, and will therefore be tailored towards the recall of that particular pattern. By studying in the $\tau$ system the properties of states which are condensed in patterns two or higher, we gain access to the stability of non-condensed retrieval states in the original $\sigma$ system.

The geometry-averaged free energy per spin of our new system is calculated by using the replica trick in its conventional form, i.e. via

$$\left[f^\tau\right] = -\lim_{\hat{n} \to 0} \lim_{N \to \infty} \frac{1}{\hat{n}N} \log \left\{ \sum_c P(c) \left[ \sum_{\tau} e^{-\beta H_l(\tau, c)} \right]^{\hat{n}} \right\}$$

$$= -\lim_{\hat{n} \to 0} \lim_{N \to \infty} \frac{1}{\hat{n}N} \log \left\{ Z_s^{-1} \sum_{\{\sigma^\alpha\}} \sum_c e^{-\beta \log(\hat{n}) \sum_{i<j} c_{ij}} \right.$$  

$$\times e^{\hat{n} \sum_{i<j} c_{ij} (\xi_i \cdot \xi_j)} \left[ \sum_{\alpha=1}^n \sigma^\alpha_i \sigma^\alpha_j + \sum_{\gamma=1}^\hat{n} \tau^\gamma_i \tau^\gamma_j \right] \right\}$$

The next stages of analysis are sufficiently similar to those followed earlier to justify limiting ourselves to giving the final result in RS approximation. If again we assume at most $r$ patterns to be condensed we find:

$$\left[f^\tau\right]^{RS} = \text{extr}_{\{\hat{m}_\mu, \hat{q}, a\}} \left\{ \frac{1}{2} \sum_{\mu \leq r} \hat{m}_\mu^2 - \frac{1}{4} \alpha (\hat{q} - 1)^2 + \frac{1}{2} \hat{m}_\mu \hat{m}_\mu + \frac{1}{\beta} \log 2 \right.$$  

$$- \frac{1}{\beta} \left\langle \int DyDz \cosh^n(\Xi_1) \log \cosh(\Xi_2) \right\rangle \xi \right\}$$

$$\Xi_1 = \beta (\hat{m} \cdot \xi + y\sqrt{\alpha q})$$

$$\Xi_2 = \beta \left( \hat{m} \cdot \xi + \frac{a}{\hat{q}} \sqrt{\alpha q} y + z\sqrt{\hat{q}q/a^2 - 1} \right)$$

In addition to the previously encountered order parameters $\{m, q\}$, which relate to the $\sigma$ system (and continue to be defined as the solution of the earlier saddle-point equations), we now have new order parameters $\{\hat{m}, \hat{q}, a\}$, whose physical meaning is found to be

$$\hat{m}_\mu = \lim_{N \to \infty} \frac{1}{N} \sum_i \langle \xi_i^\mu \tau_i \rangle$$  

$$\hat{q} = \lim_{N \to \infty} \frac{1}{N} \sum_i \langle \tau_i \rangle^2$$  

$$a = \lim_{N \to \infty} \frac{1}{N} \sum_i \langle \sigma_i \tau_i \rangle$$

The new order parameters are to be solved from the saddle-point equations

$$\hat{m}_\mu = \left\langle \xi_i^\mu \frac{\int DyDz \tanh(\Xi_2) \cosh^n(\Xi_1)}{\int Dy \cosh^n(\Xi_1)} \right\rangle \xi$$  

$$\hat{q} = \left\langle \frac{\int DyDz \tanh^2(\Xi_2) \cosh^n(\Xi_1)}{\int Dy \cosh^n(\Xi_1)} \right\rangle \xi$$  

$$a = \left\langle \frac{\int DyDz \tanh(\Xi_1) \tanh(\Xi_2) \cosh^n(\Xi_1)}{\int Dy \cosh^n(\Xi_1)} \right\rangle \xi \right.$$  

(42)

It can be shown that solutions of these equations will obey $a^2 \leq \hat{q} q$ (to be expected in view of the square root in $\Xi_2$).
Figure 6. Cross-sections for fixed \( n \) of the expanded phase diagram, in which the previous retrieval phase \( R \) has been separated into two sub-regions: \( R_1 \) defines the phase where only the nominated pattern can be recalled to which the geometry has been tailored, and \( R_2 \) defines the phase where, in spite of the biased geometry, all stored patterns can still be recovered. From left to right: \( n = 1, 2, 3 \).

We now adopt a condensed ansatz which corresponds to the \( \tau \) system being in a condensed state which differs from that of the \( \sigma \) system (where the latter drives the geometry evolution): \( m_\mu = m_\delta \mu_1, \hat{m}_\mu = \hat{m}_\delta \mu_2 \). Solutions of this type must have \( a = 0 \), which is reasonable considering that any finite correlation between the \( \tau \) and \( \sigma \) systems makes \( \hat{m}_1 = 0 \) highly improbable. For \( a = 0 \) our two systems decouple, with the equations for \( \hat{m} \) and \( \hat{q} \) reducing to

\[
\hat{m} = \int Dz \tanh(\beta [\hat{m} + z\sqrt{\alpha \hat{q}}]) \tag{43}
\]

\[
\hat{q} = \int Dz \tanh^2(\beta [\hat{m} + z\sqrt{\alpha \hat{q}}]) \tag{44}
\]

These are exactly the RS equations of the model with frozen random dilution \[26\]. The \( \hat{m}_1 = a = 0 \) solutions of our saddle point equations could be unstable against perturbations in \( \hat{m}_1 \) and \( a \). In the paramagnetic phase, an expansion of the free energy up to second order in the order parameters gives

\[
[f_T]^{RS} = \text{extr}_{\{\hat{m}, \hat{q}, a\}} \left\{ \frac{1}{2} (1 - \beta) \sum_\mu \hat{m}_\mu^2 - \frac{1}{4} \alpha \beta \hat{q}^2 + \frac{1}{2} \alpha \beta a^2 + \text{higher orders} \right\}
\]

indicating that the physical solution of the saddle-point equations is the one which minimizes the free energy with respect to \( \hat{m} \) and \( a \), and maximizes it with respect to \( \hat{q} \), as is usual in the limit \( \hat{n} \to 0 \) \[23\]. Expansion around \( \hat{m}_1 = a = 0 \), with nonzero \( \hat{m}_2 \) and \( \hat{q} \), reveals that a second order instability in \( a \) occurs at the temperature

\[
T_c = \sqrt{\alpha(1 - \hat{q})[1 + (n - 1)\hat{q}]} \tag{45}
\]

Below \( T_c \) the \( \tau \) system will be captured in the \( \hat{m}_\mu = \hat{m}_\delta \mu_1 \) state, with \( \hat{m}_1 = m \) (so retrieval of states other than that to which the geometry has adapted is impossible), whereas above \( T_c \) the \( \tau \) system can be in a locally stable condensed state different from
that in which the $\sigma$ system is found. The free energy of the $\hat{m}_\mu = m\delta_{\mu 1}$ state is, however, always lower than that of other retrieval states, at any temperature. This implies that in the latter states the $\tau$ system can be at most locally stable. The line (45) has been calculated in RS ansatz; this seems reasonable, since in the model of [26] RSB does not occur for $n \geq 1$. In figure 6 we show for $n \in \{1, 2, 3\}$ the line (45) which separates the previous retrieval phase $R$ into two sub-regions, one $R_1$ where only recall of one single pattern is possible (the one to which the geometry is taylored), and a second region $R_2$ where, in spite of the biased geometry, multiple patterns can be recalled. As expected, increasing $n$ (i.e. reducing the connectivity temperature, so the ‘tayloring’ of the geometry becomes more effective) reduces the size of the $R_2$ region.

6. Conclusion

We have studied extremely diluted recurrent neural networks in which the geometry is allowed to evolve on time-scales which are adiabatically slower than the equilibration time of the (fast) neurons. In contrast to earlier studies, the actual values of the bonds remain frozen (they are here given by Hopfield’s [1] recipe) and only the connectivity is dynamic, which implies that the slow adaptation is reversible and will not wipe out any stored information. Our motivation was to investigate whether, by having a geometry dynamics which aims to reduce frustration, the information retrieval properties of the system can be improved. As in earlier models with slow bond dynamics [16, 17, 20, 21, 22, 18, 19] the equilibrium properties of our model are described by a replica theory with nonzero replica dimension $n$, where $n = \tilde{\beta}/\beta$ is the ratio between the temperature of the (fast) neurons and the temperature of the (slow) connectivity.

We have calculated phase diagrams, reflecting the stationary state of the slowest stochastic system (i.e. the geometry). They reveal a boosting of the retrieval phase, compared to the frozen connectivity case, as soon as $n > 0$. In fact, for nonzero $n$ the storage capacity diverges at low temperatures, as long as $p \ll N$. This at first sight somewhat surprising result is explained by the observation that, in tayloring the geometry to the recall of a single condensed pattern, the system sacrifices the recall quality of an infinite number of non-nominated patterns. RSB effects are as always confined to small values of $n$ (below approx. 0.32). In order to measure the expected reduction in frustration as a result of the geometry dynamics we have calculated the fraction of mis-aligned spins (where spin and local field are of opposite sign). This fraction is indeed found to decrease with decreasing temperature of the connectivity. In order to examine in which region of the phase diagram retrieval states other than the condensed pattern are still locally stable, we studied a pair of identical diluted networks, both with the same Boltzmann type connectivity distribution. The connectivity is taylored to reduce frustration in only the first of the two copies. This allows one to study scenarios corresponding to the recall of patterns (in the second copy) which are not the one to which the geometry is adapted. Such recall is seen to be possible, but only in a sub-region of the recall phase, whose size decreases with increasing $n$. 

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It would appear an interesting question to examine to what extent the properties of our model with slowly evolving geometry persist in more (biologically) realistic scenarios, e.g. when the average number of connections $c$ per neuron remains finite when $N \to \infty$. Such studies will involve order-parameter functions, see e.g. [32, 34], and require finite $n$ generalizations of finite connectivity replica theory.

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