Frequency Response of Uncertain Systems: Strong Kharitonov-Like Results*

Long Wang
Center for Systems and Control, Department of Mechanics and Engineering Science
Peking University, Beijing 100871, China

Abstract

In this paper, we study the frequency response of uncertain systems using Kharitonov stability theory on first order complex polynomial set. For an interval transfer function, we show that the minimal real part of the frequency response at any fixed frequency is attained at some prescribed vertex transfer functions. By further geometric and algebraic analysis, we identify an index for strict positive realness of interval transfer functions. Some extensions and applications in positivity verification and robust absolute stability of feedback control systems are also presented.

Keywords: Uncertain Control Systems, Frequency Response, Kharitonov Theorem, Interval Transfer Functions, Strict Positive Realness, Absolute Stability.

1 Introduction

Motivated by the seminal theorem of Kharitonov on robust stability of interval polynomials[1, 2], a number of papers on robustness analysis of uncertain systems have been published in the past few years[3, 4, 5, 6, 7, 8, 9, 10, 11, 12, 13, 14]. Kharitonov’s theorem states that the Hurwitz stability of a real (or complex) interval polynomial family can be guaranteed by the Hurwitz stability of four (or eight) prescribed critical vertex polynomials in this family. This result is significant since it reduces checking stability of infinitely many polynomials to checking stability of finitely many polynomials, and the number of critical vertex polynomials need to be checked is independent of the order of the polynomial family. An important extension of Kharitonov’s theorem is the edge theorem discovered by Bartlett, Hollot and Huang[3]. The edge theorem states that the stability of a polytope of polynomials can be guaranteed by the stability of its one-dimensional exposed edge polynomials. The significance of the edge theorem is that it allows some (affine) dependency among polynomial coefficients, and applies to more general stability regions, e.g., unit circle, left sector, shifted half plane, hyperbola region, etc. When the dependency among polynomial coefficients is nonlinear, however, Ackermann shows that

*Supported by National Natural Science Foundation (69925307) and National Key Project of China.
checking a subset of a polynomial family generally can not guarantee the stability of the entire family\cite{6, 8}.

In this paper, we study the frequency response of uncertain systems using Kharitonov stability theory on first order complex polynomial set. For an interval transfer function, we show that the minimal real part of the frequency response at any fixed frequency is attained at some prescribed vertex transfer functions. By further geometric and algebraic analysis, we identify an index for strict positive realness of interval transfer functions. Some extensions and applications in positivity verification and robust absolute stability of feedback control systems are also presented.

2 Preliminaries

Denote the $m$-th, $n$-th ($m \leq n$) order real interval polynomials $K^m(s), K^n(s)$ as

$$K^m(s) = \{g(s) | g(s) = \Sigma_{i=0}^{m} a_i s^i, a_i \in [a_i^{-}, a_i^{+}], i = 0, 1, \ldots, m\} \quad (1)$$

$$K^n(s) = \{f(s) | f(s) = \Sigma_{j=0}^{n} b_j s^j, b_j \in [b_j^{-}, b_j^{+}], j = 0, 1, \ldots, n\} \quad (2)$$

For any $g(s) \in K^m(s)$, we have

$$g(s) = \alpha_g(s^2) + s \beta_g(s^2) \quad (3)$$

where

$$\alpha_g(s^2) = a_0 + a_2 s^2 + a_4 s^4 + a_6 s^6 + \ldots \quad (4)$$

$$\beta_g(s^2) = a_1 + a_3 s^2 + a_5 s^4 + a_7 s^6 + \ldots \quad (5)$$

For the interval polynomial $K^m(s)$, denote

$$\alpha_g^{(1)}(s^2) = a_0^+ + a_2^+ s^2 + a_4^+ s^4 + a_6^+ s^6 + \ldots \quad (6)$$

$$\alpha_g^{(2)}(s^2) = a_0^{-} + a_2^{-} s^2 + a_4^{-} s^4 + a_6^{-} s^6 + \ldots \quad (7)$$

$$\beta_g^{(1)}(s^2) = a_1^+ + a_3^+ s^2 + a_5^+ s^4 + a_7^+ s^6 + \ldots \quad (8)$$

$$\beta_g^{(2)}(s^2) = a_1^{-} + a_3^{-} s^2 + a_5^{-} s^4 + a_7^{-} s^6 + \ldots \quad (9)$$

and denote $g_{ij}(s) \in K^m(s)$ as

$$g_{ij}(s) = \alpha_g^{(i)}(s^2) + s \beta_g^{(j)}(s^2), \quad i, j = 1, 2 \quad (10)$$

For the interval polynomial $K^n(s)$, the corresponding $\alpha_f^{(i)}(s^2), \beta_f^{(j)}(s^2)$ and $f_{ij}(s) \in K^n(s)$ can be defined analogously.

Denote the set of all Hurwitz stable polynomials as $H$.

A transfer function $\frac{g(s)}{f(s)}$ is said to be strictly positive real (SPR), denoted as $\frac{g(s)}{f(s)} \in SPR$, if

1) $f(s) \in H$
A transfer function set \( J \) is said to be SPR, denoted as \( J \in \text{SPR} \), if every member in \( J \) is SPR.

Lemma 1

For any fixed \( \omega \in \mathbb{R} \) and any \( g(s) \in K^m(s), f(s) \in K^n(s) \)

\[
\alpha_g^{(1)}(-\omega^2) \leq g(-\omega^2) \leq \alpha_g^{(2)}(-\omega^2) \tag{11}
\]

\[
\alpha_f^{(1)}(-\omega^2) \leq f(-\omega^2) \leq \alpha_f^{(2)}(-\omega^2) \tag{12}
\]

\[
\beta_g^{(1)}(-\omega^2) \leq g(-\omega^2) \leq \beta_g^{(2)}(-\omega^2) \tag{13}
\]

\[
\beta_f^{(1)}(-\omega^2) \leq f(-\omega^2) \leq \beta_f^{(2)}(-\omega^2) \tag{14}
\]

Lemma 2

For any fixed \( \omega, \beta \in \mathbb{R} \), if \( f(j\omega) \neq 0 \), then

\[
\Re \left( \frac{g(j\omega) - \beta f(j\omega)}{f(j\omega)} \right) > 0 \tag{15}
\]

if and only if

\[
f(j\omega)s + g(j\omega) - \beta f(j\omega) \in H \tag{16}
\]

Proof: For any fixed \( \omega, \beta \in \mathbb{R} \), \( g(j\omega) - \beta f(j\omega) \) and \( f(j\omega) \) are fixed complex numbers. Thus \( f(j\omega)s + [g(j\omega) - \beta f(j\omega)] \) is a first order complex polynomial, and

\[
f(j\omega)s + g(j\omega) - \beta f(j\omega) \in H
\]

\[\iff \Re \left( \frac{g(j\omega) - \beta f(j\omega)}{f(j\omega)} \right) < 0 \tag{17}\]

\[\iff \Re \left( \frac{g(j\omega) - \beta f(j\omega)}{f(j\omega)} \right) > 0 \tag{17}\]

This completes the proof.

Consider the interval complex numbers \( c_0 + jd_0, c_1 + jd_1 \), where \( c_i \in [c_i^-, c_i^+] \), \( d_i \in [d_i^-, d_i^+] \), \( i = 1, 2 \). Define the sign functions

\[
\text{sgn}[c_i] = \begin{cases} 
1 & c_i = c_i^- \\
2 & c_i = c_i^+
\end{cases} \tag{18}
\]

\[
\text{sgn}[d_i] = \begin{cases} 
1 & d_i = d_i^- \\
2 & d_i = d_i^+
\end{cases} \tag{19}
\]

and define the index sets \( I_1, I_2, I_3 \) as
\[ I_1 = \{(1222), (1221), (2221), (2111), (2112), (1112), (1211), (2212), (2122), (1122)\} \]

\[ I_2 = \{(1112), (1222), (2111), (2121), (1211), (2221), (2112), (1122)\} \]

\[ I_3 = \{(1111), (1212), (2222), (2121), (1222), (2221), (2212), (1212), (2112), (1122)\} \]

For any two polynomials \( h^{(1)}(s), h^{(2)}(s) \), denote their convex combination as

\[ L[h^{(1)}, h^{(2)}] = \{\lambda h^{(1)}(s) + (1 - \lambda)h^{(2)}(s) | \lambda \in [0, 1]\} \]

**Lemma 3**

For any fixed \( \beta > 0 \), the first order complex polynomial set

\[ W_1(s) := \{(c_1 + jd_1)(s - \beta) + (c_0 + jd_0) | c_i \in [c_i^-, c_i^+], d_i \in [d_i^-, d_i^+], i = 1, 2\} \subset H \]

if and only if

\[ \{(c_1 + jd_1)(s - \beta) + (c_0 + jd_0) | \text{sgn}[c_0], \text{sgn}[d_0], \text{sgn}[c_1], \text{sgn}[d_1]\} \subset I_1 \subset H \]

Proof: Necessity is obvious, to prove sufficiency, by Zero Exclusion Principle\(^1\), we only need to prove

\[ 0 \notin W_1(j\omega), \forall \omega \in \mathbb{R} \]  \hspace{1cm} (24)

Since \( W_1(s) \) has a fixed order, for sufficiently large \( \omega_\infty \)

\[ 0 \notin W_1(j\omega_\infty) \]  \hspace{1cm} (25)

Hence, by continuity, we only need to prove

\[ 0 \notin \partial W_1(j\omega), \forall \omega \in \mathbb{R} \]  \hspace{1cm} (26)

where \( \partial W_1(j\omega) \) stands for the boundary set of \( W_1(j\omega) \) in the complex plane.

Apparently, the interval complex numbers \( c_0 + jd_0, c_1 + jd_1 \) are two rectangles in the complex plane, with edges parallel to the coordinate axes (Fig. 1). When \( \omega \geq 0, (j\omega - \beta)(c_1 + jd_1) \) is a rotated rectangle (Fig. 2). Hence, \( W_1(j\omega) \) is a octagon, produced by addition of two rectangles in the complex plane (Fig. 3).

To prove \( 0 \notin \partial W_1(j\omega), \forall \omega \geq 0 \), suppose on the contrary that there exists \( \omega_0 \geq 0 \) such that \( 0 \in \partial W_1(j\omega_0) \).

Let

\[ h_1(s) = (c_1^+ + jd_1^+)(s - \beta) + (c_0^- + jd_0^-) \]  \hspace{1cm} (27)

\[ h_2(s) = (c_1^+ + jd_1^-)(s - \beta) + (c_0^- + jd_0^+) \]  \hspace{1cm} (28)

Without loss of generality, suppose

\[ 0 \in L[h_1, h_2](j\omega_0) \]  \hspace{1cm} (29)
Namely, there exists $\lambda_0 \in (0, 1)$ such that
\[
\lambda_0 h_1(j\omega_0) + (1 - \lambda_0)h_2(j\omega_0) = 0 \tag{30}
\]
Since $h_1(s), h_2(s) \in H$, we have
\[
\frac{d}{d\omega} \arg h_i(j\omega) > 0, \quad \forall \omega \in \mathbb{R}, \quad i = 1, 2 \tag{31}
\]
Thus, we have
\[
\frac{d}{d\omega} \arg[h_2 - h_1](j\omega)|_{\omega_0} = (1 - \lambda_0)\frac{d}{d\omega} \arg h_1(j\omega)|_{\omega_0} + \lambda_0 \frac{d}{d\omega} \arg h_2(j\omega)|_{\omega_0} > 0 \tag{32}
\]
On the other hand, since
\[
h_2(s) - h_1(s) = j(d_1^- - d_1^+)(s - \beta) \tag{33}
\]
and $\beta > 0$, obviously we have
\[
\frac{d}{d\omega} \arg[h_2 - h_1](j\omega) < 0, \quad \forall \omega \in \mathbb{R} \tag{34}
\]
Hence, a contradiction arises, which means that $0 \in \partial W_1(j\omega_0)$ is impossible.
When $\omega < 0$, $W_1(j\omega)$ is still a octagon in the complex plane (Fig. 4). However, four of the eight vertices are different from the previous ones. By similar analysis, we have
\[
0 \not\in \partial W_1(j\omega), \quad \forall \omega < 0 \tag{35}
\]
This completes the proof.

The following result is a direct consequence of Kharitonov Theorem for interval complex polynomials.

**Lemma 4**

The first order interval complex polynomial set
\[
W_2(s) := \{(c_1 + jd_1)s + (c_0 + jd_0)|c_i \in [c_i^-, c_i^+], d_i \in [d_i^-, d_i^+], i = 1, 2\} \subset H \tag{36}
\]
if and only if
\[
\{(c_1 + jd_1)s + (c_0 + jd_0)|(\text{sgn}[c_0] \quad \text{sgn}[d_0] \quad \text{sgn}[c_1] \quad \text{sgn}[d_1]) \in I_2\} \subset H \tag{37}
\]

### 3 Pointwise Strict Positive Realness

**Theorem 1**

For any fixed $\omega \in \mathbb{R}$, if $0 \not\in K^n(j\omega)$ and
\[
\min\{\text{Re} g_{i_1 j_1}(j\omega) f_{i_2 j_2}(j\omega) | (i_1 j_1 i_2 j_2) \in I_1\} := \beta_0 > 0 \tag{38}
\]
Then
By Lemma 2, we have
\[
\min\{\Re \frac{g(j\omega)}{f(j\omega)}|g(s) \in K^m(s), f(s) \in K^n(s)\} = \beta_0
\] (39)

Proof: Since \( g_{ij}(s) \in K^m(s), f_{ij}(s) \in K^n(s), i,j = 1,2 \), we have
\[
\min\{\Re \frac{g(j\omega)}{f(j\omega)}|g(s) \in K^m(s), f(s) \in K^n(s)\} \leq \beta_0
\] (40)

Suppose
\[
\min\{\Re \frac{g(j\omega)}{f(j\omega)}|g(s) \in K^m(s), f(s) \in K^n(s)\} := \beta_1 < \beta_0
\] (41)

Since \( \beta_0 > 0 \), there exists \( \beta_2 > 0 \) such that \( \beta_1 < \beta_2 < \beta_0 \). Hence, for any \((i_1 j_1 i_2 j_2) \in I_1\), we have
\[
\Re \frac{g_{i_1j_1}(j\omega)}{f_{i_2j_2}(j\omega)} \geq \beta_0 > \beta_2 > 0
\] (42)

Namely
\[
\Re \frac{g_{i_1j_1}(j\omega) - \beta_2 f_{i_2j_2}(j\omega)}{f_{i_2j_2}(j\omega)} > 0
\] (43)

By Lemma 2, we have
\[
f_{i_2j_2}(j\omega) s + g_{i_1j_1}(j\omega) - \beta_2 f_{i_2j_2}(j\omega) \in H, \quad \forall (i_1 j_1 i_2 j_2) \in I_1
\] (44)

Consider the first order complex polynomial set
\[
W_3(s) := \{f(j\omega)s + g(j\omega) - \beta_2 f(j\omega)|g(s) \in K^m(s), f(s) \in K^n(s)\}
\] (45)

By Lemma 1, when \( \omega \geq 0 \), we have
\[
\alpha_f^{(1)}(-\omega^2) \leq \Re f(j\omega) \leq \alpha_f^{(2)}(-\omega^2)
\] (46)
\[
\omega \beta_f^{(1)}(-\omega^2) \leq \Im f(j\omega) \leq \omega \beta_f^{(2)}(-\omega^2)
\] (47)
\[
\alpha_g^{(1)}(-\omega^2) \leq \Re g(j\omega) \leq \alpha_g^{(2)}(-\omega^2)
\] (48)
\[
\omega \beta_g^{(1)}(-\omega^2) \leq \Im g(j\omega) \leq \omega \beta_g^{(2)}(-\omega^2)
\] (49)

By Lemma 3, \( W_3(s) \subset H \). When \( \omega < 0 \), the two inequalities on the imaginary parts of \( f(j\omega), g(j\omega) \) above will be reversed. By Lemma 3, \( W_3(s) \subset H \). Hence, for any fixed \( \omega \in \mathbb{R}, f(s) \in K^n(s), g(s) \in K^m(s) \), we have
\[
f(j\omega)s + g(j\omega) - \beta_2 f(j\omega) \in H
\] (50)

By Lemma 2, we have
\[
\Re \frac{g(j\omega) - \beta_2 f(j\omega)}{f(j\omega)} > 0, \quad \forall f(s) \in K^n(s), g(s) \in K^m(s)
\] (51)
Namely
\[ \Re \frac{g(j\omega)}{f(j\omega)} > \beta_2, \quad \forall f(s) \in K^n(s), g(s) \in K^m(s) \] (52)

Namely
\[ \min \{ \Re \frac{g(j\omega)}{f(j\omega)} \mid g(s) \in K^m(s), f(s) \in K^n(s) \} = \beta_1 > \beta_2 \] (53)
which contradicts \( \beta_1 < \beta_2 < \beta_0 \). This completes the proof.

**Corollary 1a**

If \( f_{ij}(s) \in H, i, j = 1, 2 \) and
\[ \min \{ \inf_{\omega \in R} \Re \frac{g_{ij}(j\omega)}{f_{ij}(j\omega)} \mid (i_1, j_1, i_2, j_2) \in I_1 \} := \gamma_0 > 0 \] (54)

Then
\[ \min \{ \inf_{\omega \in R} \Re \frac{g(j\omega)}{f(j\omega)} \mid g(s) \in K^m(s), f(s) \in K^n(s) \} = \gamma_0 \] (55)

Proof: Since \( f_{ij}(s) \in H, i, j = 1, 2 \), by Kharitonov Theorem[1, 2], \( K^n(s) \subset H \). Hence
\[ 0 \notin K^n(j\omega), \quad \forall \omega \in R \] (56)
Moreover, since \( g_{ij}(s) \in K^m(s), f_{ij}(s) \in K^n(s), i, j = 1, 2 \), we have
\[ \min \{ \inf_{\omega \in R} \Re \frac{g(j\omega)}{f(j\omega)} \mid g(s) \in K^m(s), f(s) \in K^n(s) \} := \gamma_1 \leq \gamma_0 \] (57)
Suppose \( \gamma_1 < \gamma_0 \), since \( \gamma_0 > 0 \), there exists \( \gamma_2 > 0 \) such that \( \gamma_1 < \gamma_2 < \gamma_0 \). Since \( \gamma_0 > \gamma_2 > 0 \), for any fixed \( \omega \in R \), we have
\[ \Re \frac{g_{ij}(j\omega)}{f_{ij}(j\omega)} > \gamma_2 > 0, \quad \forall (i_1, j_1, i_2, j_2) \in I_1 \] (58)
By Theorem 1, we have
\[ \Re \frac{g(j\omega)}{f(j\omega)} > \gamma_2 > 0, \quad \forall f(s) \in K^n(s), g(s) \in K^m(s) \] (59)
Hence, we have
\[ \inf_{\omega \in R} \Re \frac{g(j\omega)}{f(j\omega)} \geq \gamma_2 \] (60)
Namely
\[ \min \{ \inf_{\omega \in R} \Re \frac{g(j\omega)}{f(j\omega)} \mid g(s) \in K^m(s), f(s) \in K^n(s) \} = \gamma_1 \geq \gamma_2 \] (61)
which contradicts \( \gamma_1 < \gamma_2 < \gamma_0 \). This completes the proof.

By similar analysis, we have

**Corollary 1b**
If $\forall \omega \in [\omega_1, \omega_2], 0 \notin K^n(j\omega)$ and

$$\min\{\inf_{\omega \in [\omega_1,\omega_2]} \Re \frac{g_{i_1j_1}(j\omega)}{f_{i_2j_2}(j\omega)} | (i_1 \ j_1 \ i_2 \ j_2) \in I_1\} := \gamma_0 > 0$$

(62)

Then

$$\min\{\inf_{\omega \in [\omega_1,\omega_2]} \Re \frac{g(j\omega)}{f(j\omega)} | g(s) \in K^m(s), f(s) \in K^n(s)\} = \gamma_0$$

(63)

**Theorem 2**

For any fixed $\omega \in R$, if $0 \notin K^n(j\omega)$, then

$$\min\{\Re \frac{g(j\omega)}{f(j\omega)} | g(s) \in K^m(s), f(s) \in K^n(s)\} > 0$$

(64)

if and only if

$$\min\{\Re \frac{g_{i_1j_1}(j\omega)}{f_{i_2j_2}(j\omega)} | (i_1 \ j_1 \ i_2 \ j_2) \in I_2\} > 0$$

(65)

Proof: Necessity: Obvious.

Sufficiency: Since

$$\min\{\Re \frac{g_{i_1j_1}(j\omega)}{f_{i_2j_2}(j\omega)} | (i_1 \ j_1 \ i_2 \ j_2) \in I_2\} > 0$$

(66)

By Lemma 2, for any fixed $\omega \in R$

$$f_{i_2j_2}(j\omega)s + g_{i_1j_1}(j\omega) \in H, \ \forall (i_1 \ j_1 \ i_2 \ j_2) \in I_2$$

(67)

Consider the first order interval complex polynomial set

$$W_4(s) := \{f(j\omega)s + g(j\omega) | g(s) \in K^m(s), f(s) \in K^n(s)\}$$

(68)

By the proof of Theorem 1 and by Lemma 4, $W_4(s) \subset H$. Hence, for any fixed $\omega \in R, f(s) \in K^n(s), g(s) \in K^m(s)$, we have

$$f(j\omega)s + g(j\omega) \in H$$

(69)

By Lemma 2, we have

$$\Re \frac{g(j\omega)}{f(j\omega)} > 0, \ \forall f(s) \in K^n(s), g(s) \in K^m(s)$$

(70)

This completes the proof.

**Corollary 2**

$$\{\frac{g(s)}{f(s)} | g(s) \in K^m(s), f(s) \in K^n(s)\} \subset SPR$$

(71)

if and only if
Proof: Necessity: Obvious.
Sufficiency: Since
\[
\left\{ \frac{g_{i_1 j_1}(s)}{f_{i_2 j_2}(s)} \right\}(i_1 \ j_1 \ i_2 \ j_2) \in I_2 \subset \text{SPR} \tag{72}
\]
We have
\[
f_{i_2 j_2}(s) \in H, \ i_2, j_2 = 1, 2 \tag{74}
\]
and
\[
\min\left\{ \Re \frac{g_{i_1 j_1}(j\omega)}{f_{i_2 j_2}(j\omega)} \right\}|(i_1 \ j_1 \ i_2 \ j_2) \in I_2 > 0 \tag{75}
\]
By Kharitonov Theorem\cite{1, 2}, \(K^n(s) \subset H\). Hence, \(0 \not\in K^n(j\omega)\). By Theorem 2, we have
\[
\min\left\{ \Re \frac{g(j\omega)}{f(j\omega)} \right\}|(s) \in K^n(s), f(s) \in K^n(s) > 0 \tag{76}
\]
This completes the proof.

Theorem 2 is stronger than Corollary 2, since Theorem 2 reveals a pointwise property of the frequency response. This can be illustrated in the following example.

**Example 1**

Consider the interval transfer function
\[
\frac{[3, 5]s + [-7, 9]}{[5, 8]s + [1, 2]} \tag{77}
\]
and suppose \(\omega = 1\). Then it is easy to verify that all of the eight vertex transfer functions in Theorem 2 have positive real parts at this frequency. Hence by Theorem 2, all of the transfer functions in this interval family have positive real parts at this frequency. However, Corollary 2 does not apply in this case, since some transfer functions in this family, like \(\frac{-2, 5}{4s + 2}\), are not strictly positive real. Similar results can be shown for the following interval transfer functions
\[
\frac{[-2, 5]s^2 + [3, 5]s + [-2, 7]}{[2, 4]s^5 + [3, 4]s + [1, 2]} \tag{78}
\]
\[
\frac{[2, 3]s^9 + [1, 2]s + [-7, 9]}{[-3, -2]s^3 + [3, 5]s + [1, 2]} \tag{79}
\]

## 4 Further Extensions and Applications

### 4.1 Index of Strict Positive Realness

**Lemma 5**

Consider the real polynomial
\[ h(s, \lambda) = h^{(0)}(s) + \lambda(\alpha s + \beta), \quad \lambda \in [0, 1] \quad (80) \]

with constant order. Then

\[ h(s, \lambda) \in H, \quad \forall \lambda \in [0, 1] \quad (81) \]

if and only if

\[ h(s, 0), h(s, 1) \in H \quad (82) \]

\textbf{Lemma 6}

For any fixed \( \beta > 0 \), the first order real polynomial set

\[ W_5(s) := \{ c_1(s + \beta) + c_0 | c_i \in [c_i^-, c_i^+], i = 1, 2 \} \subset H \quad (83) \]

if and only if

\[ \{ c_1(s + \beta) + c_0 | c_i \in \{c_i^-, c_i^+\}, i = 1, 2 \} \subset H \quad (84) \]

Proof: Necessity: Obvious.

Sufficiency: Suppose \( c_1 \in [c_1^-, c_1^+] \) is fixed, if

\[ c_1(s + \beta) + c_0^- \in H \quad (85) \]

\[ c_1(s + \beta) + c_0^+ \in H \quad (86) \]

Then, by Lemma 5, we have

\[ c_1(s + \beta) + c_0 \in H, \quad \forall c_0 \in [c_0^-, c_0^+] \quad (87) \]

Suppose \( c_0 \in [c_0^-, c_0^+] \) is fixed, if

\[ c_1^-(s + \beta) + c_0 \in H \quad (88) \]

\[ c_1^+(s + \beta) + c_0 \in H \quad (89) \]

Then, by Lemma 5, we have

\[ c_1(s + \beta) + c_0 \in H, \quad \forall c_1 \in [c_1^-, c_1^+] \quad (90) \]

This completes the proof.

\textbf{Lemma 7} \[9\]

Suppose \( f(s) \in H \), then \( \frac{g(s)}{f(s)} \in SPR \) if and only if

1) \[ \Re \frac{g(0)}{f(0)} > 0 \]

2) \[ g(s) \in H \quad (91) \]

3) \[ f(s) + j\alpha g(s) \in H, \quad \forall \alpha \in R \]
Lemma 8
For any fixed $\beta > 0, \gamma \in R \setminus \{0\}$, the complex polynomial set

$$W_6(s) := \{g(s) + (\beta + j\gamma)f(s)|g(s) \in K^m(s), f(s) \in K^n(s)\} \subset H$$

(92)

if and only if

$$\{g_{i_1j_1}(s) + (\beta + j\gamma)f_{i_2j_2}(s)|(i_1 j_1 i_2 j_2) \in I_3\} \subset H$$

(93)

Proof: Necessity: Obvious.

Sufficiency: When $\gamma > 0, \arg(\beta + j\gamma) \in (0, \frac{\pi}{2})$. When $\omega \geq 0$, by Lemma 1, $K^m(j\omega), K^n(j\omega)$ are rectangles in the complex plane, with edges parallel to the coordinate axes (Fig. 5). The four vertices of $K^m(j\omega)$ are $g_{11}(j\omega), g_{12}(j\omega), g_{22}(j\omega), g_{21}(j\omega)$. $(\beta + j\gamma)K^n(j\omega)$ is produced by rotating the rectangle $K^n(j\omega)$ counterclockwisely by $\arg(\beta + j\gamma)$ with respect to the origin of the coordinate axes, and then scaling by $|\beta + j\gamma|$ (Fig. 6). Hence, $W_6(j\omega) = K^m(j\omega) + (\beta + j\gamma)K^n(j\omega)$ is a octagon in the complex plane (Fig. 7), with edges parallel to either the edges of $K^m(j\omega)$ or the edges of $(\beta + j\gamma)K^n(j\omega)$. Hence, the slopes of the edges of $W_6(j\omega)$ are invariant with respect to $\omega$. Moreover,

since $\{g_{i_1j_1}(s) + (\beta + j\gamma)f_{i_2j_2}(s)|(i_1 j_1 i_2 j_2) \in I_3\} \subset H$, by similar analysis as in the proof of Lemma 3, we have

$$0 \notin \partial W_6(j\omega), \forall \omega \geq 0$$

(94)

The other three cases $(\gamma > 0, \omega < 0; \gamma < 0, \omega \geq 0; \gamma < 0, \omega < 0)$ can be analyzed analogously. Henceforth, for any fixed $\omega \in R, \beta > 0, \gamma \in R \setminus \{0\}$, we have

$$0 \notin \partial W_6(j\omega)$$

(95)

Moreover, since $\gamma \neq 0$, $W_6(s)$ has a constant order. Hence

$$0 \notin W_6(j\omega)$$

(96)

By Zero Exclusion Principle [1], $W_6(s) \subset H$. This completes the proof.

Theorem 3
If $f_{ij}(s) \in H, i, j = 1, 2$ and

$$\min\{\inf_{\omega \in R} \Re \left(\frac{g_{i_1j_1}(j\omega)}{f_{i_2j_2}(j\omega)}\right)|(i_1 j_1 i_2 j_2) \in I_3\} := \gamma_0 < 0$$

(97)

Then

$$\min\{\inf_{\omega \in R} \Re \left(\frac{g(j\omega)}{f(j\omega)}\right)|g(s) \in K^m(s), f(s) \in K^n(s)\} = \gamma_0$$

(98)

Proof: Since $f_{ij}(s) \in H, i, j = 1, 2$, by Kharitonov Theorem [1, 2], $K^n(s) \subset H$. Moreover, since $g_{ij}(s) \in K^m(s), f_{ij}(s) \in K^n(s), i, j = 1, 2$, we have

$$\min\{\inf_{\omega \in R} \Re \left(\frac{g(j\omega)}{f(j\omega)}\right)|g(s) \in K^m(s), f(s) \in K^n(s)\} := \gamma_1 \leq \gamma_0$$

(99)
Suppose $\gamma_1 < \gamma_0 < 0$, then there exists $\gamma_2$ such that $\gamma_1 < \gamma_2 < \gamma_0 < 0$. Since $\gamma_0 > \gamma_2$, for any fixed $\omega \in R$, we have
\[
\Re \frac{g_{i_1j_1}(j\omega) - \gamma_2 f_{i_2j_2}(j\omega)}{f_{i_2j_2}(j\omega)} > 0, \quad \forall (i_1, j_1, i_2, j_2) \in I_3
\] (100)
Namely
\[
\frac{g_{i_1j_1}(s) - \gamma_2 f_{i_2j_2}(s)}{f_{i_2j_2}(s)} \in SPR, \quad \forall (i_1, j_1, i_2, j_2) \in I_3
\] (101)
By Lemma 7, for any $(i_1, j_1, i_2, j_2) \in I_3$, we have
\[
11) \quad \Re \frac{g_{i_1j_1}(0) - \gamma_2 f_{i_2j_2}(0)}{f_{i_2j_2}(0)} > 0
\]
\[
12) \quad g_{i_1j_1}(s) - \gamma_2 f_{i_2j_2}(s) \in H
\]
\[
13) \quad f_{i_2j_2}(s) + j\alpha[g_{i_1j_1}(s) - \gamma_2 f_{i_2j_2}(s)] \in H, \quad \forall \alpha \in R
\]
We will prove that, for any $g(s) \in K^m(s), f(s) \in K^n(s)$, we have
\[
\frac{g(s) - \gamma_2 f(s)}{f(s)} \in SPR
\] (103)
By Lemma 7, we only need to prove that, for any $g(s) \in K^m(s), f(s) \in K^n(s)$, we have
\[
21) \quad \Re \frac{g(0) - \gamma_2 f(0)}{f(0)} > 0
\]
\[
22) \quad g(s) - \gamma_2 f(s) \in H
\] (104)
\[
23) \quad f(s) + j\alpha[g(s) - \gamma_2 f(s)] \in H, \quad \forall \alpha \in R
\]
Proof of 21): By 11) and Lemma 2, we have
\[
f_{i_2j_2}(0)s + g_{i_1j_1}(0) - \gamma_2 f_{i_2j_2}(0) \in H
\] (105)
Namely
\[
f_{i_2j_2}(0)(s - \gamma_2) + g_{i_1j_1}(0) \in H, \quad \forall (i_1, j_1, i_2, j_2) \in I_3
\] (106)
By Lemma 6, for any $g(s) \in K^m(s), f(s) \in K^n(s)$, we have
\[
f(0)(s - \gamma_2) + g(0) \in H
\] (107)
By Lemma 2, 21) is proved.
Proof of 22): By 12), we have
\[
g_{ij}(s) - \gamma_2 f_{ij}(s) \in H, \quad \forall i, j = 1, 2
\] (108)
Since $\gamma_2 < 0$, by Kharitonov Theorem\cite{[1, 2]}, 22) is proved.
Proof of 23): When $\alpha = 0$, 13) becomes $f_{i_2j_2}(s) \in H, \forall i_2, j_2 = 1, 2$. By Kharitonov Theorem\cite{[1, 2], 3, 23} is proved. When $\alpha \neq 0$, 13) becomes
\[ g_{i_1j_1}(s) + (-\gamma_2 + \frac{1}{j\alpha})f_{i_2j_2}(s) \in H, \quad \forall (i_1 \ j_1 \ i_2 \ j_2) \in I_3 \]  

(109)

By Lemma 8, for any \( g(s) \in K^m(s), f(s) \in K^n(s) \), we have

\[ g(s) + (-\gamma_2 + \frac{1}{j\alpha})f(s) \in H \]  

(110)

Thus, (23) is proved. Henceforth, for any \( g(s) \in K^m(s), f(s) \in K^n(s) \), we have

\[ \frac{g(s) - \gamma_2 f(s)}{f(s)} \in SPR \]  

(111)

Namely

\[ \Re \frac{g(j\omega)}{f(j\omega)} > \gamma_2, \quad \forall \omega \in R \]  

(112)

Hence

\[ \inf_{\omega \in R} \frac{\Re g(j\omega)}{f(j\omega)} \geq \gamma_2 \]  

(113)

Henceforth

\[ \gamma_1 = \min \{ \inf_{\omega \in R} \frac{\Re g(j\omega)}{f(j\omega)} | g(s) \in K^m(s), f(s) \in K^n(s) \} \]  

(114)

which contradicts \( \gamma_1 < \gamma_2 < \gamma_0 < 0 \). This completes the proof.

Let

\[ \gamma_0 = \min \{ \inf_{\omega \in R} \frac{\Re g_{i_1j_1}(j\omega)}{f_{i_2j_2}(j\omega)} | (i_1 \ j_1 \ i_2 \ j_2) \in I_3 \} \]  

(115)

\[ \gamma_1 = \min \{ \inf_{\omega \in R} \frac{\Re g(j\omega)}{f(j\omega)} | g(s) \in K^m(s), f(s) \in K^n(s) \} \]  

(116)

Then, obviously, \( \gamma_1 \leq \gamma_0 \). The following result shows that \( \gamma_0 \) can be regarded as an index of strict positive realness.

**Theorem 4**

If \( f_{ij}(s) \in H, i, j = 1, 2 \), then

1) if \( \gamma_0 < 0 \), then \( \gamma_1 = \gamma_0 < 0 \).

2) if \( \gamma_0 = 0 \), then \( \gamma_1 = 0 \).

3) if \( \gamma_0 > 0 \), then \( \gamma_1 \geq 0 \).

Proof: 1) is a direct consequence of Theorem 3. To prove 2) and 3), suppose on the contrary that \( \gamma_1 < 0 \), then there exists \( \gamma_2 \) such that \( \gamma_1 < \gamma_2 < 0 \). By similar analysis as in the proof of Theorem 3, we have \( \gamma_1 \geq \gamma_2 \), which contradicts \( \gamma_1 < \gamma_2 < 0 \). This completes the proof.
4.2 Closed Loop Systems

Consider the open loop transfer function \( \frac{g(s)}{f(s)} \). Under negative unity feedback, the closed loop transfer function is \( \frac{g(s)}{f(s) + g(s)} \).

**Theorem 5**

\[
\{ \frac{g(s)}{f(s) + g(s)} | g(s) \in K^m(s), f(s) \in K^n(s) \} \subset SPR
\]

if and only if

\[
\{ \frac{g_{ijj_2}(s)}{f_{i_1j_1}(s) + g_{ijj_2}(s)} | (i_1, j_1, i_2, j_2) \in I_3 \} \subset SPR
\]

Proof: Necessity: Obvious.

Sufficiency: Since \( f_{ij}(s) + g_{ij}(s) \in H, \forall i, j = 1, 2 \), by Kharitonov Theorem [1, 2], we have

\[ f(s) + g(s) \in H, \quad \forall g(s) \in K^m(s), f(s) \in K^n(s) \]

By Lemma 7, we only need to prove that, for any \( g(s) \in K^m(s), f(s) \in K^n(s) \), we have

1) \( \Re \frac{g(0)}{f(0) + g(0)} > 0 \)

2) \( g(s) \in H \)

3) \( f(s) + g(s) + j\omega g(s) \in H, \quad \forall \alpha \in R \)

Proof of 1): we only need to prove

\[ \Re \frac{f(0) + g(0)}{g(0)} > 0 \]

By Lemma 2, this is equivalent to

\[ g(0)(s + 1) + f(0) \in H \]

By Lemma 6, this is obvious.

Proof of 2): Since \( g_{ij}(s) \in H, i, j = 1, 2 \), by Kharitonov Theorem [1, 2], we have

\[ g(s) \in H, \quad \forall g(s) \in K^m(s) \]

Proof of 3): When \( \alpha = 0, 3) \) is obvious. When \( \alpha \neq 0 \), by Lemma 8, 3) is true. This completes the proof.

From the analysis in the proof of Theorem 5, we have

**Theorem 6**

For any fixed \( \gamma > 0 \), we have

\[
\{ \frac{g(s)}{f(s) + \gamma g(s)} | g(s) \in K^m(s), f(s) \in K^n(s) \} \subset SPR
\]

if and only if
\{ \frac{g_{i_2j_2}(s)}{f_{i_1j_1}(s) + \gamma g_{i_2j_2}(s)} | (i_1, j_1, i_2, j_2) \in I_3 \} \subset \text{SPR} \quad (125)

4.3 Robust Absolute Stability

Consider the classical Lur'e problem: the forward path is a linear time-invariant stable component, the feedback path is a memoryless nonlinear time-varying component (Fig. 8).

The nonlinear component \( \Phi(t, \sigma) \) satisfies

\[
\Phi(t, 0) = 0, \quad \forall t \geq 0 \quad (126)
\]

\[
0 \leq \sigma \Phi(t, \sigma) \leq k\sigma^2 \quad (127)
\]

Such class of nonlinearities is said to belong to the sector \([0, k]\), denoted as \( \Phi \in \text{sect}[0, k] \). If the closed loop system is stable for all nonlinearities in the sector \([0, k]\), then we say the system is absolutely stable.

**Lemma 9**\[15\]

Suppose \( f(s) \in H, \Phi \in \text{sect}[0, k] \). If

\[
\Re\left( \frac{1}{k} + \frac{g(j\omega)}{f(j\omega)} \right) > 0, \quad \forall \omega \in R \quad (128)
\]

Then the closed loop system is absolutely stable.

Suppose the transfer function of the forward path is an interval transfer function \( \frac{g(s)}{f(s)} \), \( g(s) \in K^m(s), f(s) \in K^n(s) \). Then we have

**Theorem 7**

Suppose

\[
\begin{cases}
0 < k < -\frac{1}{\gamma_0} & \text{if } \gamma_0 < 0 \\
0 < k < +\infty & \text{if } \gamma_0 \geq 0
\end{cases} \quad (129)
\]

Then, for any \( g(s) \in K^m(s), f(s) \in K^n(s), \Phi \in \text{sect}[0, k] \), the closed loop system is absolutely stable.

Proof: By Theorem 4, we have

\[
\begin{cases}
\gamma_1 = \gamma_0 & \text{if } \gamma_0 < 0 \\
\gamma_1 \geq 0 & \text{if } \gamma_0 \geq 0
\end{cases} \quad (130)
\]

Hence, for any fixed \( \omega \in R, g(s) \in K^m(s), f(s) \in K^n(s) \), we have

\[
\Re\left( \frac{1}{k} + \frac{g(j\omega)}{f(j\omega)} \right) > \frac{1}{k} + \gamma_1 > 0 \quad (131)
\]

By Lemma 9, the theorem is proved.
5 Conclusions

We have studied the frequency response of uncertain systems using Kharitonov stability theory on first order complex polynomial set. For an interval transfer function, we have shown that the minimal real part of the frequency response at any fixed frequency is attained at some prescribed vertex transfer functions. By further geometric and algebraic analysis, we have identified an index for strict positive realness of interval transfer functions. Some extensions and applications in positivity verification and robust absolute stability of feedback control systems have also been presented. Our results can be easily extended to the study of maximal real part, minimal (or maximal) imaginary part of the frequency response. One salient feature of this paper is that we transform the pointwise strict positive realness problem into the stability problem of a first order complex polynomial set, thereby simplifying the analysis of the original problem. This idea is also useful in the study of maximal pointwise or bounded-bandwidth $H_\infty$ norm of an interval transfer function, which can be transformed into Schur stability problem of a first order complex polynomial set. For instance, $\left\| \frac{g(s)}{f(s)} \right\|_\infty < \gamma$ if and only if, for all $\omega \in \mathbb{R}$, $f(j\omega)z + \frac{1}{\gamma}g(j\omega)$ is Schur stable. The established extreme point results will be published elsewhere.

References

[1] J. Ackermann, Robust Control: Systems with Uncertain Physical Parameters, Springer-Verlag, London, 1993.
[2] V. L. Kharitonov, Asymptotic Stability of an Equilibrium Position of a Family of Systems of Linear Differential Equations, Differential’nye Uravneniya, vol.14, No.11, 2086-2088, 1978.
[3] A. C. Bartlett, C. V. Hollot and L. Huang, Root Location of an Entire Polytope of Polynomials: It Suffices to Check the Edges, Mathematics of Control, Signals and Systems, vol.1, No.1, 61-71, 1988.
[4] Y. Tsypkin and B. Polyak, Frequency Domain Criteria for Robust Stability of Polytope of Polynomials, IEEE Trans. on Automatic Control, vol.36, No.12, 1464-1469, 1991.
[5] B. R. Barmish, C. V. Hollot, F. J. Kraus and R. Tempo. Extreme point results for robust stabilization of interval plants with first order compensators, IEEE Trans. on Automatic Control, vol.37, 707-714, 1992.
[6] L. Wang and L. Huang. Finite verification of strict positive realness of interval rational functions, Chinese Science Bulletin, vol.36, 262-264, 1991.
[7] J. Ackermann. Uncertainty structures and robust stability analysis, Proc. of European Control Conference, 2318-2327, 1991.
[8] J. Ackermann. Does it suffice to check a subset of multilinear parameters in robustness analysis? IEEE Trans. on Automatic Control, vol.37, 487-488, 1992.
[9] H. Chapellat, M. Dahleh and S. P. Bhattacharyya, On Robust Nonlinear Stability of Interval Control Systems, IEEE Trans. on Automatic Control, vol.36, No.1, 59-67, 1991.
[10] S. Dasgupta. Kharitonov’s theorem revisited, Systems and Control Letters, vol.11, No.4, 381-384, 1988.
[11] A.Rantzer. Stability conditions for polytopes of polynomials, IEEE Trans. on Automatic Control, vol.37, 79-89, 1992.

[12] C.V.Hollot and R.Tempo. On the Nyquist envelope of an interval plant family, IEEE Trans. on Automatic Control, vol.39, 391-396, 1994.

[13] L. Wang, Robust Strict Positive Realness of Transfer Function Families, Systems Science and Mathematical Sciences, vol.7, No.4, 371-378, 1994.

[14] L. Wang, On strict positive realness of multilinearly parametrized interval systems, Proceedings of the 1st Chinese Control Conference, Taiyuan, China, 1994.

[15] M. Vidyasagar, Nonlinear Systems Analysis, Prentice-Hall, Englewood Cliffs, New Jersey, 1978.