Off-shell renormalization in the presence of dimension 6 derivative operators. II. Ultraviolet coefficients

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Abstract The full off-shell one loop renormalization for all divergent amplitudes up to dimension 6 in the Abelian Higgs-Kibble model, supplemented with a maximally power counting violating dimension 6 gauge-invariant derivative interaction $\sim g \phi^\dagger \phi (D^\mu \phi)^\dagger D_\mu \phi$, is presented. This allows one to perform the complete renormalization of radiatively generated dimension 6 operators in the model at hand. We describe in details the technical tools required in order to disentangle the contribution to ultraviolet divergences parameterized by (generalized) non-polynomial field redefinitions. We also discuss how to extract the dependence of the $\beta$-function coefficients on the non-renormalizable coupling $g$ in one loop approximation, as well as the cohomological techniques (contractible pairs) required to efficiently separate the mixing of contributions associated to different higher-dimensional operators in a spontaneously broken effective field theory.

1 Introduction

In this paper we continue the study of the off-shell renormalization of the Abelian Higgs-Kibble model supplemented by the maximally power counting violating dimension 6 operator $\phi^\dagger \phi (D^\mu \phi)^\dagger D_\mu \phi$. In particular, we will show here how to evaluate the one-loop divergent coefficients associated to all dimension 6 operators which are radiatively generated, and without limiting ourselves to: (i) on-shell quantities that are customarily assumed in the Standard Model Effective Field Theories (SMEFT) literature, where the cancellations between one-loop anomalous dimensions of dimension 6 operators were originally discovered [1–3]; and (ii) the linearized approximation in the higher dimensional couplings. Consequently, we will be able to compute the Generalized Field Redefinitions (GFRs) at one-loop order in closed form, which will give ultimately access to the explicit evaluation of the $\beta$-function of the higher dimensional couplings (and not only the anomalous dimensions of the operators).

The purpose of the present paper is to achieve the off-shell renormalization of the theory by imposing the Slavnov–Taylor (ST) identity [4,5] order by order in the loop expansion. The latter identity encodes at the quantum level the classical BRST invariance [6–8] of the gauge-fixed classical action and ensures the fulfillment order by order in the $\hbar$-expansion of physical unitarity [9–12] (i.e., the cancellation of unphysical ghost modes).

The appropriate perturbative expansion for this program is the loop expansion, since locality properties of quantum field theory are intimately tied to the $\hbar$-expansion by the so-called Quantum Action Principle [13–16]: if, for a non-anomalous model, the ST identity is fulfilled up to order $n−1$ in the loop expansion, then the ST identity at order $n$ can be fulfilled by a suitable choice of local counter-terms.

Indeed, the procedure presented below provides a concrete way on how the order $n$ ST identity can be constructed for spontaneously broken effective gauge theories. More specifically, the $X$-formalism allows to deal in a simplified way (in comparison with the ordinary treatment) with such local counter-terms by making certain hidden relations between them explicit.

To be sure, at fixed loop order, 1-PI amplitudes can further be expanded in powers of the coupling constants. In the present model, an infinite number of UV divergent amplitudes with arbitrarily high powers of $g/\Lambda$, with $g$ the dimension 6 coupling constant and $\Lambda$ an energy scale much higher than the electroweak scale $v$, is obtained already at one-loop order via the resummation of certain insertions of suitably
chosen external sources.\(^1\) Yet these infinite towers of counterterms are controlled by just one parameter, as we will explain.

The general aspects of the formalism needed to achieve these results have been explained in details in Ref. [17], to which we refer the reader for a thorough exposition of the technical tools required within the Algebraic Renormalization approach to the problem we use [18–31].

Instead, the present paper describes in a self-contained way the procedure developed in Ref. [17] from an operational point of view. In particular, we show how to disentangle the contributions to ultraviolet (UV) divergences parametrized by unphysical (generalized) non-polynomial field redefinitions from those associated to the renormalization of physical gauge-invariant operators in the evaluation of one-loop \(\beta\)-functions.

To systematically compute the (one-loop) UV coefficients in spontaneously broken effective field theories possessing (dimension 6) derivative operators, it is convenient to first renormalize an associated auxiliary model, the so-called \(X\)-\(2\)-theory, which is obtained by describing the scalar physical degree of freedom in terms of the gauge-invariant field coordinate

\[
vX_2 \sim \phi^\dagger \phi - \frac{v^2}{2}, \tag{1.1}
\]

\(v\) being the vacuum expectation value of the Higgs scalar \(\phi\).

Then, in the \(X\)-theory all higher dimensional operators in the classical action are required to vanish at \(X_2 = 0\). Thus, the operator

\[
\frac{g}{v\Lambda} \phi^\dagger (D^\mu \phi)^\dagger D_\mu \phi \tag{1.2}
\]

will be expressed as \(\frac{g}{\Lambda} X_2 (D^\mu \phi)^\dagger D_\mu \phi\); going on-shell with the field \(X_2\) and an additional Lagrange multiplier \(X_1\) enforcing algebraically the constraint in Eq. (1.1), we get back the original operator in Eq. (1.2).

The latter contains tri- and quadri-linear interaction vertices of the type \(\sim \sigma \partial^\mu \sigma \partial^\nu \sigma\) and \(\sim \sigma^2 \partial^\mu \sigma \partial_\mu \sigma\), that give rise to an infinite number of UV divergent amplitudes already at one-loop order, as shown in Fig. 1. Hence, the problem of the complete renormalization of the model might seem practically intractable already in the one-loop approximation (although it has been known since a long time that, in principle, UV divergences can indeed be subtracted in a symmetric way order by order in the loop expansion, as proven in a seminal paper by Weinberg and Gomis [32]). Nevertheless, there are relations between the UV divergent parts of the one-loop amplitudes that significantly simplify the problem; but they become transparent only after one uses as a dynamical variable the gauge invariant combination \(X_2\) in Eq. (1.1). This is the main virtue of the \(X\)-formalism. It happens because the dependence of the vertex functional \(\Gamma\) on the field \(X_2\) can be strongly restricted by a set of functional identities that involve external sources with a better UV behaviour, thus reducing the number of independent UV divergences [17,33,34].

In particular, two external sources are required in order to formulate in a mathematically consistent way the \(X\)-theory [17] when the operator (1.2) is added to the power-counting renormalizable action: one is coupled to the constraint \(vX_2 - \phi^\dagger \phi - \frac{v^2}{2}\) and is denoted by \(\phi^*\); the second, called \(T_1\), is required to close the algebra of operators, implementing the \(X\)-theory equation of motion at the quantum level.

The important point is that, unlike in the ordinary formalism, in the \(X\)-theory all 1-PI amplitudes, with the exception of those involving insertions of the \(T_1\) source, exhibit a manifest weak power-counting [35]: only a finite number of divergent amplitudes exist at each loop order (although increasing with the loop number, as expected in a general effective field theory setting). As for \(T_1\)-dependent amplitudes, they can be recovered by resumming the \(T_1\)-insertions on the Green’s functions at \(T_1 = 0\), which, sometimes, can be even done in a closed form.

Once the renormalization of the \(X\)-theory is achieved, one goes on-shell with the \(X_1\) and \(X_2\) fields, which amounts to a suitable mapping of the sources \(\phi^*\) and \(T_1\) onto operators depending on \(\phi\) and its covariant derivatives. Then, one can immediately read off the UV coefficients of the higher dimensional gauge-invariant operators in the target theory, as now everything is expressed in terms of the original \(\phi\) field.

We hasten to emphasize that since we are working off-shell the effects of generalized field redefinitions, that are present already at one-loop order, and are not even polynomial for the model at hand [17], need to be correctly accounted for. This is automatically done through the cohomologically trivial invariants of the \(X\)-theory. In fact, as we will show, the associated coefficients are gauge-dependent (as we will explicitly

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\]
check by evaluating all the coefficients both in Feynman and Landau gauge), being instrumental in ensuring crucial cancellations leading to the gauge-independence of the coefficients associated to gauge-invariant operators. Notice in fact that since the ensuing analysis is based on cohomological results valid for anomaly-free gauge theories, the computational approach presented here can be readily extended to the electroweak gauge group $SU(2) \times U(1)$ and, more generally, to any non-anomalous non-Abelian gauge group.

The paper is organized as follows. Our notations and conventions are described in Sect. 2. After providing in Sect. 3 a brief reminder on the structure of the mapping to the target theory, we proceed to evaluate the coefficients of the cohomologically trivial invariants relevant for dimension 6 operators in Sect. 4. Section 5 is then devoted to the evaluation of the coefficients of the three classes of gauge invariant operators appearing in the theory: those only depending on the external sources, those mixing external sources and fields and those that only depend on the fields. We finally apply the mapping to the target theory in Sect. 6.1 thereby computing the coefficients of all the UV divergent operators up to dimension 6 in the original (target) theory. This allows us to construct (Sect. 6.3) the full $\beta$ functions of the theory. Our conclusions and outlook are presented in Sect. 7. The paper ends with two appendices: Appendix A contains the list of all the independent invariants needed for renormalization of the theory, while the relevant $X$-theory divergent one-loop amplitudes up to dimension 6 are given in Appendix B.

2 Notations and setup

The tree-level vertex functional in the $X$-formalism can be written as [17]

$$\Gamma^{(0)} = \int \! d^4 x \left[ - \frac{1}{4} F_{\mu \nu}^a F_{\mu \nu}^a + (D^\mu \phi)^\dagger (D_\mu \phi) - \frac{M^2 - m^2}{2} X_2^2 - \frac{m^2}{2 v^2} \left( \phi^\dagger \phi - \frac{v^2}{2} \right)^2 \right. \right.$$ \begin{equation}
\left. - \bar{c} (\square + m^2) c + \frac{1}{v} (X_1 + X_2) (\square + m^2) \right] \times \left( \phi^\dagger \phi - \frac{v^2}{2} - v X_2 \right) + \frac{8}{\Lambda} X_2 (D^\mu \phi)^\dagger (D_\mu \phi) + T_1 (D^\mu \phi)^\dagger (D_\mu \phi) + \frac{\xi}{2} b^2 - b \left( \partial A + \xi e v \chi \right) + \bar{\omega} \left( \square + \xi e v (\sigma + v) \omega \right) + \bar{\sigma} \left( \phi^\dagger \phi - \frac{v^2}{2} - v X_2 \right) + \sigma^* (-e \omega \chi) + \chi^* e \omega (\sigma + v) \right]. \tag{2.1}
\end{equation}

The first line is the action of the Abelian Higgs-Kibble model in the $X$-formalism. Besides the usual scalar field $\phi \equiv \frac{1}{\sqrt{2}} (\sigma + v + i \chi)$, with $v$ its vacuum expectation value (v.e.v.), one also adds a singlet field $X_2$ that provides a gauge-invariant parameterization of the physical scalar mode.

When going on-shell with the field $X_1$, that plays the role of a Lagrange multiplier, one recovers the constraint $X_2 \sim \frac{1}{2} (\phi^\dagger \phi - \frac{v^2}{2})$. Inserting the latter back into the first line of Eq. (2.1), the $m^2$-term cancels out and one is left with the usual Higgs quartic potential with coefficient $\sim M^2/2v^2$.

Hence, Green’s functions in the target theory have to be $m^2$-independent, a fact that provides a very strong check of the computations, due to the ubiquitous presence of $m^2$ both in Feynman amplitudes and invariants.

We notice that in the limit $v \rightarrow 0$ (unbroken phase) the $X$-formalism is ill-defined, since in this limit the $X_1$-equation of motion yields

$$v X_2 = \phi^\dagger \phi - \frac{v^2}{2} = 0 \Rightarrow_{v \rightarrow 0} \phi^\dagger \phi = 0.$$ \tag{2.2}

The $X_{1,2}$-system comes together with a constraint BRST symmetry, ensuring that the number of physical degrees of freedom in the scalar sector remains unchanged in the $X$-formalism w.r.t. the standard formulation relying only on the field $\phi$ [33,36]. More precisely, the vertex functional (2.1) is invariant under the following BRST symmetry:

$$\delta X_1 = \omega c; \quad \delta \phi = \delta X_2 = \delta c = 0; \quad \delta \bar{c} = \phi^\dagger \phi - \frac{v^2}{2} - v X_2.$$ \tag{2.3}

The associated ghost and antighost fields $c, \bar{c}$ are free. The constraint BRST differential $\delta$ anticommutes with the gauge group BRST symmetry of the classical action after the gauge-fixing introduced in the fourth line of Eq. (2.1):

$$s A_\mu = \partial_\mu \omega; \quad s v = 0; \quad s \bar{\omega} = b; \quad s b = 0; \quad s \phi = i e \omega \phi.$$ \tag{2.4}

Here $\omega (\bar{\omega})$ is the U(1) ghost (antighost); the latter field is paired into a BRST doublet with the Lagrange multiplier field $b$, enforcing the $R_\xi$ gauge-fixing condition

$$\mathcal{F}_\xi = \partial A + \xi e v \chi.$$ \tag{2.5}

\[ \text{Going on-shell with } X_1 \text{ yields the condition} \]

$$\left( \square + m^2 \right) (\phi^\dagger \phi - \frac{v^2}{2} - v X_2) = 0,$$ \tag{2.2}

so that the most general solution is $X_2 = \frac{1}{2} \left( \phi^\dagger \phi - \frac{v^2}{2} \right) + \eta$, $\eta$ being a scalar field of mass $m$. However in perturbation theory the correlators of the mode $\eta$ with any gauge-invariant operators vanish [34], so that one can safely set $\eta = 0$. 

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The two BRST symmetries can both be lifted to the corresponding Slavnov-Taylor identities at the quantum level, provided one introduces the antifields, i.e., the external sources coupled to the relevant BRST transformation that are non-linear in the quantized fields. The antifield couplings are displayed in the last line of Eq. (2.1). Then the ST identity for the constraint BRST symmetry is

$$\delta_c(\Gamma) \equiv \int d^4x \left[ v_c \frac{\delta \Gamma}{\delta X^1} + \frac{\delta \Gamma}{\delta \bar{c}^*} \right] = \int d^4x \left[ v_c \frac{\delta \Gamma}{\delta X^1} - (\Box + m^2)c \frac{\delta \Gamma}{\delta c} \right] = 0, \quad (2.6)$$

where in the latter equality we have used the fact that both the ghost $c$ and the antighost $\bar{c}$ are free:

$$\frac{\delta \Gamma}{\delta c} = -(\Box + m^2)c, \quad \frac{\delta \Gamma}{\delta \bar{c}^*} = (\Box + m^2)\bar{c}. \quad (2.7)$$

Hence Eq. (2.6) reduces to the $X_1$-equation of motion

$$\frac{\delta \Gamma}{\delta X^1} = \frac{1}{v}(\Box + m^2)\frac{\delta \Gamma}{\delta \bar{c}^*}. \quad (2.8)$$

Finally, the ST identity (equivalently the BV master equation) associated to the gauge group BRST symmetry reads

$$\delta(\Gamma) = \int d^4x \left[ \partial_{\mu} \omega \frac{\delta \Gamma}{\delta A_{\mu}} + \frac{\delta \Gamma}{\delta \sigma^*} \frac{\delta \Gamma}{\delta \sigma} + \frac{\delta \Gamma}{\delta \bar{c}} \frac{\delta \Gamma}{\delta c} + b \frac{\delta \Gamma}{\delta \bar{\omega}} \right] = 0. \quad (2.9)$$

The third line of Eq. (2.1) contains the derivative dim.6 operator

$$X_2(D^4\phi)^\dagger D_{\mu}\phi \sim (\phi^3 - \frac{v^2}{2})(D^4\phi)^\dagger D_{\mu}\phi$$

together with the source $T_1$ required to define the $X_2$-equation at the quantum level in the presence of such an additional non-power-counting renormalizable interaction:

$$\frac{\delta \Gamma}{\delta X^2} = \frac{1}{v}(\Box + m^2)\frac{\delta \Gamma}{\delta \bar{c}^*} + \frac{g}{\Lambda} \frac{\delta \Gamma}{\delta T_1} - (\Box + m^2)X^1 - (\Box + M^2)X^2 - v\bar{c}^*. \quad (2.10)$$

Notice that the terms in the third line of Eq. (2.1) respect both BRST symmetries and thus they do not violate either the $X_1$-equation (2.8) or the ST identity (2.9).

The set of the functional identities holding in this theory is completed by:

- The $b$-equation:

$$\frac{\delta \Gamma^{(0)}}{\delta b} = \xi b - \partial A - \xi ev\chi; \quad (2.11)$$

- The antighost equation:

$$\frac{\delta \Gamma^{(0)}}{\delta \bar{\omega}} = \Box \omega + \xi e v^* \chi. \quad (2.12)$$

In what follows subscripts denote functional differentiation w.r.t. fields and external sources. Moreover, if not otherwise stated, amplitudes will be denoted as, e.g., $\Gamma^{(1)}_{XX}$, meaning

$$\Gamma^{(1)}_{XX} \equiv \left. \frac{\delta^2 \Gamma^{(1)}}{\delta \chi(-p)\delta \chi(p)} \right|_{p=0}. \quad (2.13)$$

A bar denotes the UV divergent part of the corresponding amplitude in the Laurent expansion around $\epsilon = 4 - D$, with $D$ the space-time dimension. Dimensional regularization is always implied, with amplitudes evaluated by means of the packages FeynArts and FormCalc [37,38]. As already remarked, all amplitudes will be evaluated in the Feynman ($\xi = 1$, with $\xi$ the gauge fixing parameter) and Landau ($\xi = 0$) gauge; this will allow to explicitly check the gauge cancellations in gauge invariant operators.

The UV divergent contributions to one-loop amplitudes form a local functional (in the sense of formal power series) aptly denoted by $\bar{\Gamma}^{(1)}$. In particular, $\bar{\Gamma}^{(1)}$ belongs to the kernel of $\delta_0$ i.e.

$$\delta_0(\bar{\Gamma}^{(1)}) = 0, \quad (2.14)$$

where $\delta_0$ is the linearized ST operator

$$\delta_0(\bar{\Gamma}^{(1)}) = \int d^4x \left[ \partial_{\mu} \omega \frac{\delta \bar{\Gamma}^{(1)}}{\delta A_{\mu}} + ev(\sigma + v) \frac{\delta \bar{\Gamma}^{(1)}}{\delta \chi} + \frac{\delta \bar{\Gamma}^{(0)}}{\delta \sigma} \frac{\delta \Gamma^{(0)}}{\delta \sigma} \right]$$

$$+ \frac{\delta \Gamma^{(0)}}{\delta \bar{\omega}} \frac{\delta \Gamma^{(0)}}{\delta \omega} + (\Box + m^2) \frac{\delta \Gamma^{(1)}}{\delta \bar{c}^*} + (\Box + m^2) \frac{\delta \Gamma^{(1)}}{\delta c}$$

$$= s\bar{\Gamma}^{(1)} + \int d^4x \left[ \frac{\delta \Gamma^{(0)}}{\delta \sigma} \frac{\delta \Gamma^{(1)}}{\delta \sigma} + \frac{\delta \Gamma^{(0)}}{\delta \bar{c}} \frac{\delta \Gamma^{(1)}}{\delta \bar{c}^*} + \frac{\delta \Gamma^{(0)}}{\delta \bar{\omega}} \frac{\delta \Gamma^{(1)}}{\delta \bar{\omega}} \right], \quad (2.15)$$

which acts as the BRST differential $s$ on the fields of the theory while mapping the antifields into the classical equations of motion of their corresponding fields. Then, the nilpotency of $\delta_0$ ensures that $\bar{\Gamma}^{(1)}$ is the sum of a gauge-invariant functional $\bar{\mathcal{F}}^{(1)}$ and a cohomologically trivial contribution $\delta_0(\bar{\mathcal{F}}^{(1)})$:

$$\bar{\Gamma}^{(1)} = \bar{\mathcal{F}}^{(1)} + \delta_0(\bar{\mathcal{F}}^{(1)}). \quad (2.16)$$

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3 Mapping on the external sources

As a result of the previous Section, we only need to determine the invariants contributing to $\mathcal{F}_{\bar{y}}^{(1)}$ and $\overline{\mathcal{Y}}^{(1)}$ that will induce in the target theory operators of dimension less or equal to 6.

To that end we first need to consider how the mapping affects the external sources $\bar{c}^a$, $T_1$.

The $X_1$- and $X_2$-equations (2.8) and (2.10) at loop order $n \geq 1$ for $\Gamma^{(n)}$ read

$$\begin{align*}
\frac{\delta \Gamma^{(n)}}{\delta X_1} &= \frac{1}{v} (\Box + m^2) \frac{\delta \Gamma^{(n)}}{\delta \bar{c}^a} - \int d^4 x \bar{c}^a (\bar{c}^* \phi - \frac{v^2}{2}) \\
\frac{\delta \Gamma^{(n)}}{\delta X_2} &= \frac{1}{v} (\Box + m^2) \frac{\delta \Gamma^{(n)}}{\delta \bar{c}^a} + \frac{g}{\Lambda} \frac{\delta \Gamma^{(n)}}{\delta T_1},
\end{align*}$$

(3.1)

thus implying that the whole dependence on $X_1$ and $X_2$ can only arise through the combinations

$$\bar{c}^* = \bar{c}^a + \frac{1}{v} (\Box + m^2) (X_1 + X_2); \quad \mathcal{T}_1 = T_1 + \frac{g}{\Lambda} X_2. \tag{3.2}$$

In particular, Eq. (3.1) states that the 1-PI amplitudes involving at least one $X_1$ or $X_2$ external legs are uniquely fixed in terms of amplitudes involving neither $X_1$ or $X_2$.

We now turn to the analysis of how the right-hand side of Eq. (3.2) is transformed under the mapping. For that purpose we need to impose the equations of motion for $X_1, X_2$. At the one-loop level, we can restrict to tree-level equations of motion for these fields. As already discussed, the $X_1$-equation of motion enforces the constraint $X_2 = \frac{1}{v} (\phi^* \phi - \frac{v^2}{2})$. Once one takes into account this constraint, the $X_2$-equation of motion in turn yields

$$(\Box + m^2) (X_1 + X_2) = - (M^2 - m^2) X_2 + \frac{g}{\Lambda} (D^\mu \phi)^\dagger D_\mu \phi - v \bar{c}^a . \tag{3.3}$$

By substituting the above expressions for $X_{1,2}$ into the replacement rules (3.2) we arrive at the sought-for mapping transformation (at zero external sources):

$$\begin{align*}
\bar{c}^* &\rightarrow - \frac{(M^2 - m^2)}{v^2} (\phi^* \phi - \frac{v^2}{2}) + \frac{g}{v \Lambda} (D^\mu \phi)^\dagger D_\mu \phi; \\
\mathcal{T}_1 &\rightarrow \frac{g}{v \Lambda} (\phi^* \phi - \frac{v^2}{2}). \tag{3.4}
\end{align*}$$

Since the right-hand side of the above equation contains operators of dimension at least 2, in order to obtain target operators of up to dimension 6 it is clear that we need to consider amplitudes with up to 3 external sources $\bar{c}^a$ and $T_1$. Equivalently, we can assign dimension 2 to both $\bar{c}^a$ and $T_1$ and use it in order to identify the mixed fields-external sources invariants that will contribute to target operators of up to dimension 6. For instance $\int d^4 x \bar{c}^a (\phi^* \phi - \frac{v^2}{2})$ would project onto

$$\begin{align*}
\int d^4 x \bar{c}^a (\phi^* \phi - \frac{v^2}{2}) &\rightarrow - \frac{(M^2 - m^2)}{v^2} \int d^4 x \left( \phi^* \phi - \frac{v^2}{2} \right)^2 \\
&\quad + \frac{g}{v \Lambda} \int d^4 x (D^\mu \phi)^\dagger D_\mu \phi \left( \phi^* \phi - \frac{v^2}{2} \right), \tag{3.5}
\end{align*}$$

whereas $\int d^4 x \bar{c}^a (\phi^* \phi - \frac{v^2}{2})^2$ would give rise to

$$\begin{align*}
\int d^4 x \bar{c}^a (\phi^* \phi - \frac{v^2}{2})^2 &\rightarrow - \frac{(M^2 - m^2)}{v^2} \int d^4 x \left( \phi^* \phi - \frac{v^2}{2} \right)^3, \tag{3.6}
\end{align*}$$

where we have neglected the covariant kinetic term in the first term of Eq. (3.4) since it would generate a dimension 8 operator.

Finally, the coefficients of the three possible types of invariants contributing to the $X$-theory functional $\mathcal{F}_{\bar{y}}^{(1)}$ will be indicated with $\lambda_i$ (combinations of the field strength, its derivatives and $\phi$ and its covariant derivatives of up to dimension 6), $\theta_i$ (combinations of external sources and fields) or $\theta_i$ (combinations of external sources only). The complete list of invariants is reported in Appendix A.

4 Cohomologically trivial invariants

Before addressing the evaluation of the coefficients of the gauge invariants, it is necessary to fix the coefficients $\rho_i$ of the cohomologically trivial invariants contributing to $\delta_0 (\overline{\mathcal{Y}}^{(1)})$. Their knowledge is crucial in the renormalization procedure, since these invariants will allow us to obtain in closed form the generalized field redefinitions present in the original $\phi$-theory (once the mapping is applied).

Taking into account the bounds on the dimensions, this requires to consider two invariants at $T_1 = 0$, namely

$$\begin{align*}
\rho_0 \delta_0 &\int d^4 x [\sigma (\sigma + v) + \chi^* \chi]; \\
\rho_1 \delta_0 &\int d^4 x (\sigma^* \sigma + \chi^* \chi). \tag{4.1}
\end{align*}$$
4.1 Generalized field redefinitions

To begin with let us observe that Eq. (2.15) implies
\[ \rho_1 \delta_0 \int d^4x \ (\sigma^*\sigma + \chi^*\chi) \ni -ev \rho_1 \int d^4x \ \chi^* \omega. \] (4.2)

Therefore, the coefficient \( \rho_1 \) associated to this invariant is controlled by the single amplitude \( \Gamma^{(1)}_{\chi^* \omega} \). Indeed, Eq. (4.2) demands that
\[ ev \rho_1 = -\Gamma^{(1)}_{\chi^* \omega}, \] (4.3)
or, using the result (B2a),
\[ \rho_1 = \frac{M^2_A}{8\pi^2} \frac{1}{v^2 - \epsilon} (1 - \delta_{\xi 0}). \] (4.4)

with \( \delta_{\xi 0} = \delta_{00} = 1 \) in the Landau gauge and \( \delta_{\xi 0} = \delta_{10} = 0 \) in the Feynman gauge. Notice that this result implies that there are no pure field redefinitions in Landau gauge, i.e., the v.e.v. renormalizes in the same way as the fields, as we will soon show.

Finally, repeated insertions of the source \( T_1 \) resum to
\[ \rho_1 \delta_0 \int d^4x \ \frac{1}{1 + T_1} (\sigma^*\sigma + \chi^*\chi). \] (4.5)

A comment is in order here. In the standard formalism one should consider the effect of the generalized field redefinitions in the target theory, which, as explained in Ref. [17], is the one induced by Eq. (4.5). This implies that the fields \( \sigma \) and \( \chi \) undergo the transformation
\[ \sigma \rightarrow \sigma + \frac{\rho_1}{1 + \frac{\epsilon}{M^2_A} (\phi^\dagger \phi - \frac{v^2}{2})} \sigma; \]
\[ \chi \rightarrow \chi + \frac{\rho_1}{1 + \frac{\epsilon}{M^2_A} (\phi^\dagger \phi - \frac{v^2}{2})} \chi. \] (4.6)

This would be a rather involved task, which is however simplified in the approach developed here, since all the combinatorics is automatically taken into account via the renormalization of the \( X \)-theory, through the cohomologically trivial invariant Eq. (4.5).

4.2 Tadpoles

The tadpoles \( \Gamma^{(1)}_{\sigma} \), \( \Gamma^{(1)}_{\chi^*} \) allow to fix the coefficients of three invariants:
\[ \rho_0 \delta_0 \int d^4x \ [\sigma^*(\sigma + v) + \chi^*\chi] 
\]
\[ + \lambda_1 \int d^4x \ (\phi^\dagger \phi - \frac{v^2}{2}) + \vartheta_1 \int d^4x \ \overline{\epsilon}^* \]
\[ \ni \int d^4x \ [(-m^2 v \rho_0 + v \lambda_1)\sigma + (\rho_0 v^2 + \vartheta_1)\overline{\epsilon}^*]. \] (4.7)

Indeed, Eq. (4.7) gives rise to the equations
\[ -m^2 v \rho_0 + v \lambda_1 = \Gamma^{(1)}_{\sigma}; \] (4.8a)
\[ \rho_0 v^2 + \vartheta_1 = \Gamma^{(1)}_{\overline{\epsilon}^*}. \] (4.8b)

Direct inspection of the one-loop results (B1a) and (B1c) shows that, in the Feynman gauge, it is consistent to set \( \rho_0|_{\xi = 1} = 0 \), thus yielding the results
\[ \lambda_1|_{\xi = 1} = \frac{1}{v} \Gamma^{(1)}_{\sigma}|_{\xi = 1} = \frac{1}{16\pi^2} \frac{1}{v^2 - \epsilon} \left[ m^2 (M^2 + M^2_A) + \frac{2}{3} (M^2 + 3M^2_A) \right], \] (4.9a)
\[ \vartheta_1|_{\xi = 1} = \Gamma^{(1)}_{\overline{\epsilon}^*}|_{\xi = 1} = -\frac{M^2 + M^2_A}{16\pi^2} \frac{1}{v^2 - \epsilon}. \] (4.9b)

On the other hand, since \( \lambda_1 \) must be gauge invariant, Eq. (4.8a) implies
\[ \rho_0 = \frac{1}{m^2 v} (v \lambda_1 - \Gamma^{(1)}_{\sigma}|_{\xi = 1}) = \frac{M^2_A}{16v^2 \pi^2} \frac{1}{v^2 - \epsilon} \delta_{\xi 0}, \] (4.10)
whereas Eq. (4.8b) furnishes a consistency condition that can be easily checked. Notice in particular that Eq. (4.8b) shows that \( \vartheta_1 \) is gauge independent (as it should) since the gauge dependence in \( \Gamma^{(1)}_{\overline{\epsilon}^*} \) is cancelled by the one in \( \rho_0 \). Finally, using Eq. (4.10) and the gauge independence of \( \vartheta_1 \), Eq. (4.8b) can be recast in the form
\[ -\frac{m^2}{v} \left( \Gamma^{(1)}_{\overline{\epsilon}^*}|_{\xi = 0} - \Gamma^{(1)}_{\overline{\epsilon}^*}|_{\xi = 1} \right) = \Gamma^{(1)}_{\overline{\epsilon}^*}|_{\xi = 0} - \Gamma^{(1)}_{\overline{\epsilon}^*}|_{\xi = 1}. \] (4.11)

Next, we need to consider the insertion of one and two sources \( T_1 \) on tadpole amplitudes. Starting from a single insertion, the relevant projection equation becomes
\[ \rho_0 \delta_0 \int d^4x \ T_1 [\sigma^*(\sigma + v) + \chi^*\chi] 
\]
\[ + \vartheta_2 \int d^4x \ T_1 (\phi^\dagger \phi - \frac{v^2}{2}) + \vartheta_7 \int d^4x \ \overline{\epsilon}^* T_1 
\]
\[ \ni \int d^4x \ [(-m^2 v \rho_0 + v \lambda_1)\sigma + (\rho_0 v^2 + \vartheta_1)\overline{\epsilon}^*]. \] (4.12)
As before, one obtains two equations

\[ -m^2 v \rho_0 T_1 + v \theta_2 = \Gamma^{(1)}_{T_1\sigma}, \]  
\[ v^2 \rho_0 T_1 + \theta_7 = \overline{\Gamma}^{(1)}_{C^* T_1}, \]  
(4.13a)

which is most easily solved in the Feynman gauge in which \( \rho_0 T_1 \big|_{\xi=1} = 0 \), and therefore, using the results (B2h) and (B2f),

\[ \theta_2|_{\xi=1} = \frac{1}{v} \Gamma^{(1)}_{T_1\sigma} \big|_{\xi=1} = \frac{m^2 (M^2 + M_A^2)}{8 \pi^2 v^2} \frac{1}{\epsilon}, \]  
(4.14a)

\[ \theta_7|_{\xi=1} = \overline{\Gamma}^{(1)}_{c^* T_1} \big|_{\xi=1} = \frac{(M^2 + M_A^2)}{8 \pi^2} \frac{1}{\epsilon}. \]  
(4.14b)

Then, using the fact that \( \theta_2 \) is gauge invariant, Eq. (4.13a) can be used to fix the coefficient \( \rho_0 T_1 \), obtaining

\[ \rho_0 T_1 = \frac{1}{m^2 v} \left( v \theta_2 - \Gamma^{(1)}_{T_1\sigma} \right) = -\frac{M_A^2}{8 \pi^2 v^2} \frac{1}{\epsilon} \delta_{\xi 0}, \]  
(4.15)

which, once inserted in Eq. (4.13b) shows that \( \theta_7 \) is gauge invariant, thus allowing to recast the condition (4.13b) in the form

\[ -\frac{m^2}{v} \left( \Gamma^{(1)}_{c^* T_1} \big|_{\xi=0} - \Gamma^{(1)}_{c^* T_1} \big|_{\xi=1} \right) = \Gamma^{(1)}_{T_1\sigma} \big|_{\xi=0} - \Gamma^{(1)}_{T_1\sigma} \big|_{\xi=1}, \]  
(4.16)

in complete analogy with Eq. (4.11).

Finally, for the case of two \( T_1 \)-insertions, the relevant projection equation reads

\[ \rho_0 \overline{T}_1 \int d^4 x \overline{T}_1^2 \delta_0 \int d^4 x \left[ \sigma^* (\sigma + v) + \chi^* \chi \right] \]

\[ + \theta_{12} \int d^4 x \overline{T}_1^2 \left( \phi^* \phi - \frac{v^2}{2} \right) + \frac{\theta_{11} }{2} \int d^4 x \overline{c}^* T_1^2 \]

\[ \supset \int d^4 x \left[ \left( -m^2 v \rho_0 \overline{T}_1^2 + v \theta_{12} \right) \sigma T_1^2 + (v^2 \rho_0 \overline{T}_1^2 + \frac{\theta_{11} }{2}) \overline{c} c^* T_1^2 \right], \]  
(4.17)

giving rise to the conditions

\[ 2(-m^2 v \rho_0 \overline{T}_1^2 + v \theta_{12}) = \Gamma^{(1)}_{\sigma T_1 T_1}, \]  
(4.18a)

\[ 2v^2 \rho_0 \overline{T}_1^2 + \theta_{11} = \overline{\Gamma}^{(1)}_{c^* T_1 T_1}. \]  
(4.18b)

In the Feynman gauge \( \rho_0 \overline{T}_1 \big|_{\xi=1} = 0 \), so that, using Eqs. (B3) and (B3b)

\[ \theta_{12}|_{\xi=1} = \frac{1}{2v} \Gamma^{(1)}_{\sigma T_1 T_1} \big|_{\xi=1} = \frac{1}{16 \pi^2 v^2} \left[ m^2 (2M^2 + 2M_A^2) + 6(M^4 + M_A^4) \right] \frac{1}{\epsilon}, \]  
(4.19a)

\[ \theta_{11}|_{\xi=1} = \overline{\Gamma}^{(1)}_{c^* T_1 T_1} \big|_{\xi=1} = -\frac{3M^2 + 2M_A^2}{8 \pi^2} \frac{1}{\epsilon}. \]  
(4.19b)

Using then the gauge independence of \( \theta_{12} \) we obtain, from Eq. (4.18a)

\[ \rho_0 \overline{T}_1^2 = \frac{1}{2m^2 v} \left( 2v \theta_{12} - \Gamma^{(1)}_{\sigma T_1 T_1} \right) = \frac{M_A^2}{8 \pi^2 v^2} \frac{1}{\epsilon} \delta_{\xi 0}. \]  
(4.20)

which, once inserted in Eq. (4.18b) shows that \( \theta_{11} \) is also gauge invariant, so that the condition (4.18b) reads

\[ -\frac{m^2}{v} \left( \Gamma^{(1)}_{\overline{T}_1 T_1} \big|_{\xi=0} - \Gamma^{(1)}_{c^* T_1 T_1} \big|_{\xi=1} \right) = \Gamma^{(1)}_{\sigma T_1 T_1} \big|_{\xi=0} - \Gamma^{(1)}_{\sigma T_1 T_1} \big|_{\xi=1}. \]  
(4.21)

We remark that resummation of the \( T_1 \)-insertions is not at work for the tadpoles in the Landau gauge since the loop with a massless Goldstone field in \( \Gamma^{(1)}_{c^*} \) and \( \Gamma^{(1)}_{\sigma} \) happens to be zero in dimensional regularization.

In the Landau gauge there is no pure field redefinition since \( \rho_1 \big|_{\xi=0} = 0 \). On the other hand the invariant

\[ \rho_0 \delta_0 \int d^4 x \left[ \sigma^* (\sigma + v) + \chi^* \chi \right]. \]  
(4.22)

shows that in Landau gauge also the v.e.v. \( v \) renormalizes in the same way as the field \( \phi \). This is a well-known fact in spontaneously broken gauge theories [39].

5 The gauge invariant sector

Having fixed the relevant invariants in the cohomologically trivial sector, we can now extract from the one-loop UV divergent 1-PI amplitudes the contributions to the gauge invariants up to dimension 6. In the X-theory this requires to consider three classes of operators: (i) those only dependent on the external sources; (ii) those mixing external sources and fields; and (iii) those only dependent on the fields. These invariants cannot depend on the gauge, as we will explicitly show.

Once the mapping in Eq. (3.4) is applied, these invariants will contribute to the dimension 6 operators in the target theory. The tadpole operators that mix with the cohomologically
trivial sector have already been determined in the previous Section.

5.1 The pure external sources sector

The invariants in the pure external sources sector are reported in Eq. (A1),

5.1.1 Linear terms

\( \vartheta_1 \) has been already fixed in Eq. (4.8b). \( \vartheta_2 \) can be fixed by looking at the \( T_1 \)-tadpole (B1b):

\[
\vartheta_2 = \Gamma^{(1)}_{T_1} = - \frac{(M^4 - 3M_A^4)}{16\pi^2} \frac{1}{\epsilon}.
\]

(5.1)

Notice that there are no contributions from cohomologically trivial invariants since there are no linear couplings for \( T_1 \) at tree-level. Consequently \( \Gamma_{T_1}^{(1)} \) is the same both in Landau and in Feynman gauge.

5.1.2 Bilinears

\( \vartheta_3 \) is fixed by the 2-point \( \bar{c}^* \)-amplitude Eq. (B2e):

\[
\vartheta_3 = \Gamma_{c^*c^*}^{(1)} = \frac{1}{8\pi^2} \frac{1}{\epsilon}.
\]

(5.2)

Notice that \( \Gamma_{c^*c^*}^{(1)} \) does not develop momentum-dependent divergences and that it does not depend on the gauge.

This is clearly not the case for \( \Gamma_{T_1T_1}^{(1)} \) as Eq. (B2g) shows; we can then read off the coefficients of the different bilinear invariants, obtaining

\[
\vartheta_4 = \Gamma_{T_1T_1}^{(1)} = \frac{3}{16\pi^2} (M^4 + M_A^4) \frac{1}{\epsilon},
\]

\[
\vartheta_5 = - \frac{\partial \Gamma_{T_1T_1}^{(1)}}{\partial p^4} \bigg|_{p=0} = \frac{3}{32\pi^2} (M^2 + M_A^2) \frac{1}{\epsilon},
\]

\[
\vartheta_6 = \frac{\partial \Gamma_{T_1T_1}^{(1)}}{\partial p^4} \bigg|_{p=0} = \frac{1}{32\pi^2} \frac{1}{\epsilon}.
\]

(5.3)

We notice that \( \vartheta_6 \) has been included for completeness but does not contribute to operators of dim. \( \leq 6 \) in the target theory, rather to dim.8 operators.

Finally, \( \vartheta_7 \) has been fixed in Eq. (4.14b), while the \( p^2 \)-coefficient of the amplitude \( \Gamma_{c^*T_1}^{(1)} \), see (B2f), is gauge independent and implies

\[
\vartheta_8 = - \frac{\partial \Gamma_{T_1c^*}^{(1)}}{\partial p^2} \bigg|_{p=0} = \frac{1}{16\pi^2} \frac{1}{\epsilon}.
\]

(5.4)

5.1.3 Trilinears

While \( \vartheta_{11} \) has been fixed in Eq. (4.19b), it turns out that the remaining trilinears do not receive contributions from cohomologically trivial invariants. In particular we find

\( \vartheta_9 = 0 \)

(5.5)

since \( \Gamma_{c^*c^*c^*}^{(1)} \) is UV finite, and, using the results (B3a) and (B3c)

\[
\vartheta_{10} = \Gamma_{c^*c^*T_1}^{(1)} = - \frac{1}{4\pi^2} \frac{1}{\epsilon}; \quad \vartheta_{12} = \Gamma_{T_1T_1T_1}^{(1)} = - \frac{3M^4}{4\pi^2} \frac{1}{\epsilon}.
\]

(5.6)

5.2 The mixed external sources-field sector

5.2.1 The \( \vartheta_1 \) and \( \vartheta_2 \) coefficients

The coefficients \( \vartheta_1 \) and \( \vartheta_2 \) can be fixed by evaluating the three-point functions \( \Gamma_{c^*c^*c^*}^{(1)} \) and \( \Gamma_{T_1T_1c^*}^{(1)} \) at zero momentum. Since

\[
\rho_0 \delta_0 \int d^4x \left[ \sigma^*(\sigma + v + \chi^* \chi) + \rho_1 \delta_0 \int d^4x (\sigma^* \sigma + \chi^* \chi) + \vartheta_1 \int d^4x \bar{c}^* (\phi^* \phi - \frac{v^2}{2}) + \vartheta_2 \int d^4x (\rho_0 + \rho_1 + \vartheta_1) \bar{c}^* \chi^2 \right]
\]

(5.7)

one arrives at the relation

\[
2\rho_0 + 2\rho_1 + \vartheta_1 = \Gamma_{c^*c^*c^*}^{(1)}.
\]

(5.8)

Then, using Eqs. (4.4), (4.10) and (B3h), we immediately obtain the result

\[
\vartheta_1 = \Gamma_{c^*c^*c^*}^{(1)} - 2(\rho_0 + \rho_1) = - \frac{m^2 + M^2 + M_A^2}{8\pi^2 v^2} \frac{1}{\epsilon},
\]

(5.9)

which, due to the compensation of the gauge parameter dependence between the amplitude and the coefficients \( \rho_0 \) and \( \rho_1 \) turns out to be gauge independent, as it should. In a similar fashion, considering the combination

\[
\rho_0 T_1 \delta_0 \int d^4x T_1 \left[ \sigma^* (\sigma + v + \chi^* \chi) + \rho_2 \int d^4x T_1 (\phi^* \phi - \frac{v^2}{2}) + \vartheta_2 \int d^4x \left( - \rho_0 T_1 \frac{m^2}{2} + \vartheta_2 \right) T_1 \chi^2 \right],
\]

(5.10)
we get
\[ -\rho_0 \Gamma_1 m^2 + \theta_2 = \Gamma^{(1)}_{T_1XX}, \]  
(5.11)
or, using the result (B3i)
\[ \theta_2 = -\frac{m^2(M^2 + M^2_A) + 2(M^4 - 3M^4_A)}{8\pi^2 v^2} \frac{1}{\epsilon}, \]  
(5.12)
and again one obtains the gauge independence of this parameter as a result of the cancellation of the gauge-dependence between the 1-PI amplitude and the coefficient \( \rho_0 \Gamma_1 \).

The validity of these results can be checked against the relations provided by 1-PI amplitudes involving one source and one external \( \sigma \)-field. For example considering the \( \tilde{c}\sigma \) case, we find
\[ \rho_0 \delta_0 \int d^4x \left[ \sigma^*(\sigma + v) + \chi^*\chi \right] \]
+ \( \rho_1 \delta_0 \left( \int d^4x \left( \sigma^*\sigma + \chi^*\chi \right) \right) \]
+ \( \theta_1 \int d^4x \tilde{c}^* \left( \phi^*\phi - \frac{v^2}{2} \right) \]
\[ \supset \int d^4x v \left( 2\rho_0 + \rho_1 + \theta_1 \right) \tilde{c}^*\sigma, \]  
(5.13)
yielding the relation
\[ v(2\rho_0 + \rho_1 + \theta_1) = \Gamma^{(1)}_{\tilde{c}\sigma}, \]  
(5.14)
which can be checked directly using Eqs. (4.4), (4.10) and (5.9). Notice that \( \Gamma^{(1)}_{\tilde{c}\sigma} \) is the same in Feynman and Landau gauge, see Eq. (B21); therefore, since \( \theta_1 \) is gauge independent, so must be the combination \( 2\rho_0 + \rho_1 \), as can be easily verified.

Considering the \( T_1\sigma \) amplitudes, we find instead
\[ \rho_0 \delta_0 \left( \int d^4x T_1 \left( \sigma^*(\sigma + v) + \chi^*\chi \right) \right) \]
+ \( \theta_2 \left( \int d^4x T_1 \left( \phi^*\phi - \frac{v^2}{2} \right) \right) \]
\[ \supset \int d^4x \left( -vm^2 \rho_0 T_1 + v\theta_2 \right) T_1\sigma. \]  
(5.15)
Thus we get
\[ -vm^2 \rho_0 T_1 + v\theta_2 = \Gamma^{(1)}_{T_1\sigma}, \]  
(5.16)
which can be immediately verified using the one-loop result (B2h).

5.2.2 The \( \theta_3 \) and \( \theta_5 \) coefficients

In order to fix \( \theta_3 \) and \( \theta_5 \), we need the amplitude \( \Gamma^{(1)}_{\tilde{c}\mu\mu\nu} \), which can be decomposed in form factors according to
\[ \Gamma^{(1)}_{\tilde{c}\mu\mu\nu}(p_1, p_2) = \gamma^0_{\tilde{c}\mu\mu\nu}(p_1^2 + p_2^2) + \gamma^2_{\tilde{c}\mu\mu\nu}(p_1, p_2). \]  
(5.17)
We find
\[ \theta_3 \int d^4x \tilde{c}^*(D^\mu \phi)^\dagger D_\mu \phi \supset \theta_3 \int d^4x \tilde{c}^* \frac{D^\mu \chi}{2} \hat{\sigma}_\mu \chi, \]  
(5.18a)
\[ \theta_5 \int d^4x \tilde{c}^* \left( (D^2 \phi)^\dagger \phi + h.c. \right) \supset \theta_5 \int d^4x \tilde{c}^* \chi \chi, \]  
(5.18b)
which, using the result Eq. (B3b), implies the following identifications
\[ \theta_3 = -\gamma^2_{\tilde{c}\mu\mu\nu} = -\frac{1}{16\pi^2} \frac{g}{\Lambda} \left( 2 + \frac{gv}{\Lambda} \right) \frac{1}{\epsilon}; \]
\[ \theta_5 = -\gamma^1_{\tilde{c}\mu\mu\nu} = -\frac{1}{16\pi^2} \frac{g}{\Lambda} \frac{1}{\epsilon}. \]  
(5.19)
Notice that both coefficients are the same in Landau and Feynman gauge, as expected.

In this case a consistency check is provided by the three-point function \( \Gamma^{(1)}_{\tilde{c}\phi A_\mu A_\nu} \), since one has
\[ \theta_3 \int d^4x \tilde{c}^* \left( (D^\mu \phi)^\dagger D_\mu \phi + \theta_5 \int d^4x \tilde{c}^* \left( (D^2 \phi)^\dagger \phi + h.c. \right) \right) \]
\[ \supset \int d^4x \frac{M^2_A}{2} \left( \theta_3 - 2\theta_5 \right) \tilde{c}^* A^2, \]  
(5.20)
so that
\[ M^2_A \left( \theta_3 - 2\theta_5 \right) g_{\mu\nu} = \left. \Gamma^{(1)}_{\tilde{c}\phi A_\mu A_\nu}(p_1, p_2) \right|_{p_1 = p_2 = 0}, \]  
(5.21)
as can be easily verified with the help of Eq. (B3e).

5.2.3 The \( \theta_4 \) and \( \theta_6 \) coefficients

In order to fix \( \theta_4 \) and \( \theta_6 \), we need the amplitude \( \Gamma^{(1)}_{T_1XX} \), which we decompose as before according to
\[ \Gamma^{(1)}_{T_1XX}(p_1, p_2) = \gamma^0_{T_1XX}(p_1^2 + p_2^2) \]
\[ + \gamma^2_{T_1XX}(p_1, p_2) + \theta_4(p^4), \]  
(5.22)
and the dots denote terms of order \( p^4 \), which are not needed.
There are two projections to be considered, namely $T_1 \partial^\mu \chi \partial_\mu \chi$ and $T_1 \chi \square \chi$, to which the cohomological trivial invariants can also contribute. To begin with, observe that

$$
\rho_1 \delta_0 \int d^4 x \frac{1}{1 + T_1} (\sigma^* \sigma + \chi^* \chi) \\
= \rho_1 \delta_0 \int d^4 x (1 - T_1 + \cdots) (\sigma^* \sigma + \chi^* \chi) \\
\supset \rho_1 \int d^4 x \left( T_1 \partial^\mu \chi \partial_\mu \chi + T_1 \chi \square \chi \right). 
$$

(5.23)

On the other hand we have

$$
\rho_0 \delta_0 \int d^4 x (\sigma^* (\sigma + v) + \chi^* \chi) \\
+ \rho_0 \gamma_1 \delta_0 \int d^4 x T_1 [\sigma^* (\sigma + v) + \chi^* \chi] \\
\supset \int d^4 x \left[ \rho_0 T_1 \partial^\mu \chi \partial_\mu \chi - \rho_0 \gamma_1 T_1 \chi \square \chi \right]. 
$$

(5.24)

Therefore we obtain

$$
\rho_1 - \rho_0 \gamma_1 + \theta_4 = -\gamma_1 T_1 \chi \chi; \\
2 (\rho_1 + \rho_0) + \theta_6 = -\gamma_1 T_1 \chi \chi, 
$$

(5.25)

from which, using Eq. (B3i), we finally get the values

$$
\theta_4 = -\frac{1}{32 \pi^2 v^2} \\
\times \left[ 4m^2 + M_A^2 \left( 4 - 3 \frac{g^2 v^2}{\Lambda^2} \right) + M^2 \left( 4 + 3 \frac{g^2 v^2}{\Lambda^2} \right) \right] \frac{1}{\epsilon}, \\
\theta_6 = -\frac{1}{16 \pi^2 v^2} \left[ m^2 - M_A^2 + M^2 \left( 1 + 2 \frac{g^2 v^2}{\Lambda} \right) \right] \frac{1}{\epsilon}. 
$$

(5.26a)

Similarly to what we have done in the previous case, we can check the results above using the three-point function $\Gamma^{(1)}_{T_1 A_\mu A_\nu}$. Indeed we have

$$
\theta_4 \int d^4 x T_1 (D^\mu \phi)^\dagger D_\mu \phi + \theta_6 \int d^4 x T_1 \left[ (D^2 \phi)^\dagger \phi + \text{h.c.} \right] \\
+ \rho_0 \delta_0 \int d^4 x [\sigma^* (\sigma + v) + \chi^* \chi] \\
+ \rho_0 \gamma_1 \delta_0 \int d^4 x T_1 [\sigma^* (\sigma + v) + \chi^* \chi] \\
\supset \int d^4 x \frac{M_A^2}{2} \left[ \theta_4 - 2 \theta_6 + 2 (\rho_0 + \rho_0 \gamma_1) \right] T_1 A^2, 
$$

(5.27)

implying the consistency condition

$$
M_A^2 \left[ \theta_4 - 2 \theta_6 + 2 (\rho_0 + \rho_0 \gamma_1) \right] g_{\mu \nu} \\
= \Gamma^{(1)}_{T_1 A_\mu A_\nu} (p_1, p_2) \big|_{p_1 = p_2 = 0}. 
$$

(5.28)

5.2.4 The $\theta_7$ and $\theta_8$ coefficients

In this sector the relevant projections are

$$
\rho_0 \delta_0 \int d^4 x [\sigma^* (\sigma + v) + \chi^* \chi] \\
+ \rho_1 \delta_0 \int d^4 x (\sigma^* \sigma + \chi^* \chi) \\
+ \theta_1 \int d^4 x \bar{c}^* (\bar{\phi}^\dagger \phi - \frac{v^2}{2}) \\
+ \theta_1 \int d^4 x \bar{c}^* (\bar{\phi}^\dagger \phi - \frac{v^2}{2})^2 \\
\supset \int d^4 x \left( \rho_0 + \rho_1 + \frac{\theta_1}{2} + v^2 \theta_7 \right) \bar{c}^* \sigma^2, 
$$

(5.29a)

$$
\rho_0 \gamma_1 \delta_0 \int d^4 x T_1 [\sigma^* (\sigma + v) + \chi^* \chi] \\
- \rho_1 \delta_0 \int d^4 x T_1 (\sigma^* \sigma + \chi^* \chi) \\
+ \theta_2 \int d^4 x T_1 (\bar{\phi}^\dagger \phi - \frac{v^2}{2}) \\
+ \theta_2 \int d^4 x T_1 (\bar{\phi}^\dagger \phi - \frac{v^2}{2})^2 \\
\supset \int d^4 x \left( m^2 \rho_1 - \frac{5}{2} \rho_0 T_1 m^2 + \frac{\theta_2}{2} + v^2 \theta_8 \right) T_1 \sigma^2, 
$$

(5.29b)

yielding the relations

$$
2 (\rho_0 + \rho_1) + \theta_1 + 2 v^2 \theta_7 = \bar{\Gamma}^{(1)}_{\sigma^* \sigma}; \\
2 m^2 \rho_1 - 5 \rho_0 T_1 m^2 + \theta_2 + 2 v^2 \theta_8 = \bar{\Gamma}^{(1)}_{T_1 \sigma \sigma}, 
$$

(5.30)

and, finally, the values

$$
\theta_7 = 0; \\
\theta_8 = -\frac{1}{8 \pi^2 v^4} \\
\times \left[ m^4 + 2 m^2 (M^2 + M_A^2) + 2 (M^4 - 3 M_A^4) \right] \frac{1}{\epsilon}, 
$$

(5.31)

see Eqs. (B3j) and (B3m).

5.2.5 The $\theta_9$ and $\theta_{10}$ coefficients

The fact that the function $\bar{\Gamma}^{(1)}_{\sigma^* \sigma}$ turns out to be momentum independent, see Eq. (B3e), implies immediately that

$$
\theta_9 = 0. 
$$

(5.32)
Next, in order to extract the coefficient \( \theta_{10} \) one needs first to change the variables to the contractible pairs basis, as explained in Ref. [17]. To this end, one replaces the derivatives of the gauge field with a linear combination of the complete symmetrization over the Lorentz indices and a contribution depending on the field strength:

\[
\partial_{v_1 \ldots v_l} A_\mu = \partial_{(v_1 \ldots v_l)} A_\mu + \frac{1}{l+1} \partial_{(v_1 \ldots v_{l-1})} F_{\nu_1 \mu},
\]

where \((\ldots)\) denote complete symmetrization. In the present case it is therefore sufficient to consider the monomial \( T_1 \partial^{\mu} A^\nu \partial_\mu A_\nu \) since, due to Eq. (5.33)

\[
T_1 \partial^{\mu} A^\nu \partial_\mu A_\nu = T_1 \partial^{(\mu} A^{\nu)} \partial_{\mu} A_{\nu} + \frac{T_1}{4} F^{\mu \nu} F_{\mu \nu}.
\]

Then, after we decompose the amplitude \( \Gamma^{(1)}_{T_1 A_\mu A_\nu} \), according to

\[
\Gamma^{(1)}_{T_1 A_\mu A_\nu} = [\gamma^0_{T_1 A A} - 2\gamma^1_{T_1 A A}(p_1 - p_2) + \gamma^2_{T_1 A A}(p_1^2 + p_2^2)] g^{\mu \nu} + \gamma^3_{T_1 A A} p_1^\mu p_2^\nu + \gamma^4_{T_1 A A} p_1^\mu p_2^\nu,
\]

Eq. (B3f) gives

\[
\theta_{10} = \frac{\gamma^0_{T_1 A A}}{4} = - \frac{M^2_F}{128 \pi^2 v^2 A^2} \frac{1}{\epsilon}.
\]

### 5.2.6 The \( \theta_{11}, \theta_{12} \) and \( \theta_{13} \) coefficients

The coefficient \( \theta_{12} \) has been fixed already, see Eq. (4.19a); on the other hand, \( \theta_{11} \) is determined by the projection of

\[
\theta_{11} \int d^4 x \bar{c}^* T_1 \left( \phi^\dagger \phi - \frac{v^2}{2} \right)
- \rho_1 \delta_0 \int d^4 x T_1 \left( \sigma^* \sigma + \chi^* \chi \right)
+ \rho_2 \delta_0 \int d^4 x T_1 \left( \sigma^* \sigma + \chi^* \chi \right)
\supset \int d^4 x \left( \varphi_1 - 2 \varphi_0 \right) \bar{c}^* T_1 \sigma.
\]

yielding

\[
\theta_{11} = \frac{1}{v} \left( \Gamma^{(1)}_{c^* T \sigma} + \varphi_1 - 2 \varphi_0 \right)
= \frac{1}{4 \pi^2 v^2} \frac{1}{m^2 + M^2 + M^2_A} \frac{1}{\epsilon},
\]

where the one-loop result (B3d) has been used. Finally,

\[
\theta_{13} \int d^4 x (\bar{c}^*)^2 \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \supset \int d^4 x \theta_{13} v \sigma (\bar{c}^*)^2,
\]

which implies

\[
\theta_{13} = \frac{1}{2v} \Gamma^{(1)}_{c^* \bar{c}^* \sigma} = 0,
\]

as this amplitude turns out to be UV finite.

### 5.3 The gauge-invariant field sector

The last sector we need to consider is finally the one of gauge invariants containing only the fields.

#### 5.3.1 The \( \lambda_2 \) and \( \lambda_3 \) coefficients

While the coefficient \( \lambda_1 \) has been already fixed, see Eq. (4.7), \( \lambda_2 \) and \( \lambda_3 \) can be determined by considering the two- and three-point \( \sigma \) amplitudes. The relevant projection equation are

\[
\rho_0 \delta_0 \int d^4 x [\sigma^* (\sigma + v) + \chi^* \chi]
+ \rho_1 \delta_0 \int d^4 x (\sigma^* \sigma + \chi^* \chi)
+ \lambda_1 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right)^2
+ \lambda_2 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right)^2
\supset \int d^4 x \left( \varphi_2 - \frac{1}{2} \lambda_1 - m^2 \rho_1 - \frac{5}{2} m^2 \rho_0 \right) \sigma^2,
\]

\[
\rho_0 \delta_0 \int d^4 x [\sigma^* (\sigma + v) + \chi^* \chi]
+ \rho_1 \delta_0 \int d^4 x (\sigma^* \sigma + \chi^* \chi)
+ \lambda_2 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right)^2
+ \lambda_3 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right)^3
\supset \int d^4 x \left( 2 v^2 \lambda_3 + 2 v \lambda_2 - \frac{3m^2}{v} \rho_1 - \frac{4m^2}{v} \rho_0 \right) \sigma^3,
\]

yielding

\[
2 v^2 \lambda_2 + \lambda_1 - 2 m^2 \rho_1 - 5 m^2 \rho_0 = \Gamma^{(1)}_{\sigma \sigma \sigma},
\]

\[
6 v^2 \lambda_3 + 6 v \lambda_2 - \frac{9 m^2}{v} \rho_1 - \frac{12 m^2}{v} \rho_0 = \Gamma^{(1)}_{\sigma \sigma \sigma}.
\]
Eqs. (B2c) and (B3n) implies then the following results

$$\lambda_2 = \frac{1}{16\pi^2 v^4} \left[ m^4 + 2m^2(M^2 + M_A^2) + 2(M^4 + 3M_A^2) \right] \frac{1}{\epsilon},$$

$$\lambda_3 = 0.$$  \hspace{1cm} (5.43a)

The values of these coefficients can be checked by looking at the $\Gamma^{(1)}_{\sigma X X}$ and $\Gamma^{(1)}_{\sigma \sigma X X}$ amplitudes, for which the projection equation

$$\rho_0 \delta_0 \int d^4x \left[ \sigma^*(\sigma + v) + \chi^* \chi \right]$$

$$+ \rho_1 \delta_0 \int d^4x \left( \sigma^* \sigma + \chi^* \chi \right)$$

$$+ \lambda_2 \int d^4x \left( \phi^* \phi - \frac{v^2}{2} \right)^2$$

$$\subseteq \int d^4x \left( \rho_0 \phi - \frac{v^2}{2} \right)^2$$

$$+ \rho_0 \delta_0 \int d^4x \left[ \sigma^* \sigma + \chi^* \chi \right]$$

$$+ \rho_1 \delta_0 \int d^4x \left( \sigma^* \sigma + \chi^* \chi \right)$$

$$+ \lambda_2 \int d^4x \left( \phi^* \phi - \frac{v^2}{2} \right)^2$$

$$\subseteq \int d^4x \left( \rho_0 \phi - \frac{v^2}{2} \right)^2$$

which gives rise to the following projections

$$\lambda_1 - m^2 \rho_0 = \Gamma^{(1)}_{\sigma X X} \left|_{p^2 = 0} \right.$$  \hspace{1cm} (5.47)

$$2(\rho_0 + \rho_1) + \lambda_4 = \frac{\partial \Gamma^{(1)}_{\sigma X X}}{\partial p^2} \left|_{p^2 = 0} \right.$$  \hspace{1cm} (5.48b)

From the one-loop expression reported in (B2b), we then obtain the gauge-independent coefficients

$$\lambda_4 = \frac{1}{32\pi^2 v^2}$$

$$\times \left[ \frac{g v}{\Lambda} \left( 4 - \frac{g v}{\Lambda} \right) M^2 + M_A^2 \left( 16 + \frac{g v}{\Lambda} + 3 \frac{g^2 v^2}{\Lambda^2} \right) \right] \frac{1}{\epsilon},$$

$$\lambda_5 = \frac{g^2}{96\pi^2 \Lambda^2} \frac{1}{\epsilon}.$$  \hspace{1cm} (5.48a)

5.3.3 The $\lambda_6$ and $\lambda_7$ coefficients

The relevant Green’s function for fixing these coefficients is the four-point Goldstone amplitude since

$$\rho_0 \delta_0 \int d^4x \left[ \sigma^* (\sigma + v) + \chi^* \chi \right]$$

$$+ \rho_1 \delta_0 \int d^4x \left( \sigma^* \sigma + \chi^* \chi \right)$$

$$+ \lambda_2 \int d^4x \left( \phi^* \phi - \frac{v^2}{2} \right)^2$$

$$\subseteq \int d^4x \left( \rho_0 \phi - \frac{v^2}{2} \right)^2$$

$$\subseteq \int d^4x \left( \rho_0 \phi - \frac{v^2}{2} \right)^2$$

yielding

$$6\lambda_2 - \frac{12m^2}{v^2} (\rho_0 + \rho_1) - 3\lambda_6 \sum_{i=1}^{4} p_i^2 - \lambda_7 \sum_{i < j} p_i p_j$$

$$= \Gamma^{(1)}_{X X X X}(p_1).$$  \hspace{1cm} (5.50)

Notice that we keep the momentum dependence of the four point $\chi$ amplitude on the right-hand side. A remark is in order here. Before attempting to extract the coefficients of
the momenta polynomial on the left-hand side of Eq. (5.50), we need to take into account the fact that \texttt{FeynArts} and \texttt{FormCalc} internally implement momentum conservation, so the amplitude is only known on the hyperplane \( \sum p_i = 0 \). Hence we eliminate \( p_4 \) in favor of the remaining momenta, \( p_4 = - \sum_{i=1}^3 p_i \), so that Eq. (5.50) becomes

\[
6\lambda_2 = \frac{12m^2}{v^2} (\rho_0 + \rho_1) - (6\lambda_6 - \lambda_7) \left( \sum_{i=1}^3 p_i^2 + \sum_{i<j} p_i p_j \right)
= \Gamma_{XXX}^{(1)} (p_1, p_2, p_3).
\]  

(5.51)

Then the condition

\[
6\lambda_2 = \frac{12m^2}{v^2} (\rho_0 + \rho_1) = \Gamma_{XXX}^{(1)} |_{p_4=0},
\]

(5.52)

is easily verified, see Eq. (B4b). On the other hand, we notice that the restriction of \( \Gamma_{XXX}^{(1)} \) on the momentum conservation hyperplane only fixes the combination \( 6\lambda_6 - \lambda_7 \), and an additional amplitude needs to be considered to fix the two coefficients separately.

To this end, let us consider the two point \( \sigma \)-amplitude, with the following projection on the derivative-dependent sector

\[
\rho_0 \delta_0 \int d^4 x \left[ (\sigma^* \sigma + v^*) \chi + \chi^* \chi \right]
+ \rho_1 \delta_0 \int d^4 x \left( \sigma^* \chi + \chi^* \sigma \right)
+ \lambda_3 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \left( \phi^\dagger D^2 \phi + (D^2 \phi)^\dagger \phi \right)
+ \lambda_6 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \left( \phi^\dagger D^2 \phi + (D^2 \phi)^\dagger \phi \right)
\supset \int d^4 x \left[ \left( \frac{\lambda_4}{2} + \rho_0 + \rho_1 \right) \partial^\mu \sigma \partial_\mu \sigma + v^2 \lambda_6 \sigma \Box \sigma \right].
\]

(5.53)

leading to the condition

\[
2v^2 \lambda_6 - \lambda_4 - 2(\rho_0 + \rho_1) = - \frac{\partial \Gamma_{XXX}^{(1)}}{\partial p^2} \bigg|_{p^2=0}.
\]

(5.54)

This gives then the result, see Eq. (B2c)

\[
\lambda_6 = \frac{1}{64\pi^2 v^3} \frac{g}{\Lambda} \left[ 4m^2 + \left( \frac{M^2 - 3M_A^2}{4} + \frac{g^2 v}{\Lambda} \right) \right] \frac{1}{\epsilon},
\]

(5.55)

which in combination with Eqs. (5.51) and (B4b) yields finally

\[
\lambda_7 = \frac{1}{32\pi^2 v^3} \frac{g}{\Lambda} \left[ \frac{2m^2}{2 + \frac{g^2 v}{\Lambda}} - M^2 \left( 4 + \frac{5g^2 v}{\Lambda} \right) - 3M_A^2 \left( 12 + \frac{5g^2 v}{\Lambda} \right) \right] \frac{1}{\epsilon}.
\]

(5.56)

We can check this result against the projections on the monomials \( \sigma \chi \Box \chi, \sigma \partial^\mu \chi \partial_\mu \chi \), namely (we use integration by parts in the last line)

\[
\lambda_6 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \left( \phi^\dagger D^2 \phi + (D^2 \phi)^\dagger \phi \right)
+ \lambda_7 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \left( D^\mu \phi \right)^\dagger D_\mu \phi
\supset \int d^4 x \left( v\lambda_6 \sigma \Box \chi + \frac{\lambda_7}{2} \sigma \partial^\mu \chi \partial_\mu \chi + \frac{\lambda_6}{2} \chi^2 \Box \sigma \right)
= \int d^4 x \left[ 2v\lambda_6 \sigma \Box \chi + (v\lambda_6 + \frac{\lambda_7}{2}) \sigma \partial^\mu \chi \partial_\mu \chi \right].
\]

(5.57)

After eliminating the \( \sigma \)-momentum in favour of the remaining two by using momentum conservation, the resulting amplitude can be expanded as

\[
\Gamma_{\sigma XX}^{(1)} (p_1, p_2) = \gamma_{\sigma XX} + \gamma_{\sigma XX}^1 (p_1^2 + p_2^2)
+ \gamma_{\sigma XX}^2 p_1 \cdot p_2 + O(p^4)
\]

(5.58)

Eq. (5.57) then implies the consistency conditions

\[
2v\lambda_6 + \gamma_{\sigma XX}^1 = 0; \quad 2v\lambda_6 + v\lambda_7 + \gamma_{\sigma XX}^2 = 0,
\]

(5.59)

which can be easily verified using the result Eq. (B3o).

\subsection{5.3.4 The \( \lambda_s \) and \( \lambda_g \) coefficients}

These coefficients are controlled by the \( AA \) amplitude which also provides a non-trivial example of the contractible pairs technique. Indeed, the two-point function of the Goldstone field fixes the coefficient \( \lambda_5 \) via the projection on the monomial \( \int d^4 x \chi \Box^2 \chi \); on the other hand, the \( \lambda_5 \) invariant admits also a non-trivial expansion in power of the gauge field, precisely accounting for the non-transverse form factors of \( \Gamma_{AA AA}^{(1)} \).

To see this in detail, observe that the relevant invariants are

\[
\rho_0 \delta_0 \int d^4 x \left[ (\sigma^* \sigma + v^*) \chi + \chi^* \chi \right]
+ \rho_1 \delta_0 \int d^4 x \left( \sigma^* \chi + \chi^* \sigma \right)
+ \lambda_5 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \left( \phi^\dagger D^2 \phi + (D^2 \phi)^\dagger \phi \right)
+ \frac{\lambda_8}{2} \int d^4 x \left( F_{\mu \nu}^2 + \lambda_9 \int d^4 x \partial^\mu F_{\mu \nu} \partial_\nu F^{\mu \nu} \right)
\]

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\[ \int d^4x \left[ (\rho_0 + \frac{\lambda_A}{2}) e^{2 v^2 A^2} - \frac{\lambda_A}{2} e^{2 v^2 (2 A^\mu \partial_\mu A + A^\mu \Box A^\mu)} + \frac{\lambda_8}{2} (\partial^\nu A^\mu - \partial^\mu A^\nu)^2 + \lambda_9 (\Box A^\mu - \partial^\mu (\partial A))^2 \right] \]

(5.60)

There are no contribution of order \( p^4 \) in \( \Gamma^{\text{(2)}}_{A^\mu A^\nu} \), see Eq. (B2d), so

\[ \lambda_9 = 0. \]

(5.61)

The remaining terms give the projection equation

\[ \left[ e^{2 v^2 (2 \rho_0 + \lambda_A)} + (2 \lambda_8 + e^{2 v^2 \lambda_A}) p^2 \right] g^{\mu \nu} + 2 \left( e^{2 v^2 \lambda_8} \right) p^{\mu} p^{\nu} = \Gamma^{\text{(1)}}_{A^\mu A^\nu} (p). \]

(5.62)

Notice that in the right-hand side of the above equation we keep the momentum dependence of the two point gauge amplitude. From Eqs. (4.10), (5.48a), (5.48b) and (B2d), we see that the above equation is verified with

\[ \lambda_8 = - \frac{M_A^2}{96 \pi^2 v^2} \left( 2 + \frac{2 g_v}{\Lambda} + \frac{g_v^2 v^2}{\Lambda^2} \right) \frac{1}{\epsilon}, \]

(5.63)

which implies that \( \lambda_8 \) is gauge-independent, as it should.

5.3.5 The \( \lambda_{10} \) coefficient

This coefficient can be obtained in much the same way as \( \theta_{10} \), i.e., by the contractible pair method. Parameterize the amplitude \( \Gamma^{\text{(1)}}_{A^A_{\rho A} A^v} \) according to

\[ \Gamma^{\text{(1)}}_{A^\mu A^\nu} (p_1, p_2) = [\gamma^{1}_{A A} - 2 \gamma^{1}_{A A} p_1 \cdot p_2 + \gamma^{1}_{A A} (p_1^2 + p_2^2)] g^{\mu \nu} + \gamma^{2}_{A A} p_1^\mu p_2^\nu + \gamma^{2}_{A A} p_1^\nu p_2^\mu, \]

(5.64)

and extract \( \lambda_{10} \) through the form factor \( \gamma^{1}_{A A} \):

\[ \lambda_{10} = \int d^4x \ F^{2}_{\mu \nu} (\phi^\dagger \phi - \frac{v^2}{2}) \]

\[ \ni \lambda_{10} \int d^4x \ 2 \sigma \partial^\mu A^\nu \partial_\mu A^\nu. \]

(5.65)

We obtain, see Eq. (B3g),

\[ \lambda_{10} = \frac{\gamma^{1}_{A A}}{4 v} = \frac{M_A^2}{128 \pi^2 v^2 \Lambda^2} \left( -4 + \frac{g_v}{\Lambda} \right) \frac{1}{\epsilon}. \]

(5.66)

Notice in particular that the combination

\[ \lambda_{10} + \frac{g_v}{v \Lambda} \theta_{10} = - \frac{M_A^2}{32 \pi^2} \frac{g_v^2}{\Lambda^2 v^2} \frac{1}{\epsilon}, \]

(5.67)

correctly reproduces the coefficient \( c^{(1)}_{\phi} \) of [17].

6 Mapping

6.1 Renormalization coefficients

We are now in a position to evaluate the renormalization coefficients of the operators of dimension less or equal to 6 in the target theory. For that purpose one simply needs to map the invariants depending on the external sources by applying the substitution rules (3.4) and collecting the contributions to the operator one is interested in.

Notice that all the coefficients obtained must be gauge-invariant (as a consequence of the gauge-invariance of the \( \theta_i \), \( \theta_i \) and \( \lambda_i \) coefficients); in addition they must not depend on \( m^2 \). The latter is a highly non-trivial check of the computations, due to the ubiquitous presence of \( m^2 \) in the projections as well as in the amplitudes.

In what follows, we list here the results for all possible operators, reinstating the correct \( D \)-dimensional dependence on the 't Hooft mass \( \mu \).

- \( \phi^\dagger \phi - \frac{v^2}{2} \)

\[ \lambda_1 = \frac{1}{v^2} \left( (M^2 - m^2) \theta_1 + \frac{g_v}{\Lambda} \theta_2 + v^2 \lambda_1 \right) \]

\[ = \frac{\mu^{-\epsilon}}{16 \pi^2 v^2} \left( M^4 \left( 3 - \frac{g_v}{\Lambda} \right) \right. \]

\[ + \left. M_A^2 \left( M^2 + 3 M_A^2 \left( 2 + \frac{g_v}{\Lambda} \right) \right) \right) \frac{1}{\epsilon}. \]

(6.1)

- \( \left( \phi^\dagger \phi - \frac{v^2}{2} \right)^2 \)

\[ \lambda_2 = \frac{(m^2 - M^2)^2}{2 v^4} \theta_3 + \frac{g^2}{2 \Lambda^2 v^2} \theta_4 \]

\[ + \frac{g_v}{\Lambda v} (m^2 - M^2) \theta_7 + \frac{m^2 - M^2}{v^2} \theta_1 \]

\[ + \frac{g_v}{\Lambda v} \theta_2 + \lambda_2 \]

\[ = \frac{\mu^{-\epsilon}}{32 \pi^2 v^4} \]

\[ \times \left( 4 M_A^2 M^2 \left( 1 - \frac{g_v}{\Lambda} \right) \right. \]

\[ + 3 M_A^4 \left( 4 + 8 \frac{g_v}{\Lambda} + \frac{g_v^2 v^2}{\Lambda^2} \right) \]

\[ + M^4 \left( 10 - 12 \frac{g_v}{\Lambda} + 3 \frac{g_v^2 v^2}{\Lambda^2} \right) \right) \frac{1}{\epsilon}. \]

(6.2)
\[ \bar{\lambda}_3 = \frac{(m^2 - M^2)^3}{6v^6} \theta_0 + \frac{g(m^2 - M^2)^2}{2\Lambda v^4} \theta_{10} \\
+ \frac{g^2(m^2 - M^2)}{2\Lambda v^4} \theta_{11} + \frac{g^3}{6\Lambda^3 v^3} \theta_{12} \\
+ \frac{m^2 - M^2}{v^2} \theta_1 + \frac{g}{v\Lambda} \theta_8 \\
+ \frac{g(m^2 - M^2)}{\Lambda v^4} \theta_{11} + \frac{g^2}{\Lambda^2 v^2} \theta_{12} \\
+ \frac{(m^2 - M^2)^2}{v^4} \theta_{13} + \lambda_3 \\
= -\frac{\mu^-}{16\pi^2 v^2} \frac{g}{\Lambda} \\
\times \left[ 2M^2M_A^2 \left( 2 - \frac{g v}{\Lambda} \right) - 6M_A^4 \left( 2 + \frac{g v}{\Lambda} \right) \right] \frac{1}{\epsilon}. \] (6.3a)

\[ \bar{\lambda}_4 = \frac{g}{\Lambda v} \theta_1 + \lambda_4 \\
= -\frac{\mu^-}{32\pi^2 v^2} \frac{g}{\Lambda^2} \\
\times \left[ M^2 \frac{g v}{\Lambda} \left( 6 - \frac{g v}{\Lambda} \right) \right] \frac{1}{\epsilon}. \] (6.3b)

\[ \bar{\lambda}_5 \equiv \lambda_5 = \frac{\mu^-}{96\pi^2} \frac{g^2}{\Lambda^2} \frac{1}{\epsilon}. \] (6.3c)

\[ \bar{\lambda}_6 = \frac{g^2}{2\Lambda^2 v^2} \theta_5 + \frac{g}{\Lambda v^3} (m^2 - M^2) \theta_8 \\
+ \frac{m^2 - M^2}{v^2} \theta_5 + \frac{g}{\Lambda v} \theta_6 + \lambda_6 \\
= -\frac{\mu^-}{16\pi^2 v^2} \frac{g^2 M^2}{\Lambda^2} \frac{1}{\epsilon}. \] (6.6)

\[ \bar{\lambda}_7 = \frac{g(m^2 - M^2)}{\Lambda v^3} \theta_3 + \frac{g^2}{\Lambda v^2} (\theta_5 + \theta_7) \\
+ \frac{2g}{\Lambda v^3} (m^2 - M^2) \theta_8 + \frac{g}{\Lambda v} (\theta_1 + \theta_4) \\
+ \frac{m^2 - M^2}{v^2} \theta_3 + \lambda_7 \\
= -\frac{\mu^-}{32\pi^2 v^2} \frac{g}{\Lambda^2} \\
\times \left[ M^2 \left( 16 - 14 \frac{g v}{\Lambda} + \frac{3g^2 v^2}{\Lambda^2} \right) \right] \frac{1}{\epsilon}. \] (6.7)

\[ \bar{\lambda}_8 \equiv \lambda_8 = -\frac{\mu^-}{96\pi^2 v^2} M_A^2 \left( 2 + \frac{g v}{\Lambda} + \frac{g^2 v^2}{\Lambda^2} \right) \frac{1}{\epsilon}. \] (6.8)

\[ \bar{\lambda}_9 \equiv \lambda_9 = 0. \] (6.9)

\[ \bar{\lambda}_{10} = -\frac{M^2 - m^2}{v^2} \theta_9 + \frac{g}{v\Lambda} \theta_{10} + \lambda_{10} \\
= -\frac{\mu^-}{32\pi^2} \frac{g^2 M_A^2}{\Lambda^2 v^2} \frac{1}{\epsilon}. \] (6.10)

### 6.2 \( v/\Lambda \) expansion

In order to match our results with standard conventions used in the EFT literature (see e.g. [40]), it is convenient to rescale the coupling according to

\[ g' = \frac{g}{v\Lambda} \rightarrow \frac{g'}{\Lambda^2}, \] (6.11)

with \( g' \) dimensionless. This constitutes then the dimension 6 coupling in the target theory, namely one has

\[ \frac{g'}{\Lambda^2} \left( \phi^+ \phi - \frac{v^2}{2} \right) (D^\mu \phi)^\dagger D_\mu \phi. \] (6.12)

Then, all the target theory coefficients in Eqs. (6.1)–(6.10) are polynomials in the coupling constants \( e = \frac{M_A}{v}, \lambda = \frac{M^2}{v^2}, g' = \frac{g}{v^2} \) as well as the ratio \( \frac{v^2}{\Lambda^2} \), as one would expect. The only exception is the tadpole \( \lambda_1 \), that still exhibits a \( v^2 \)-dependence not suppressed by \( \Lambda \) but which is anyhow present already in the power-counting renormalizable limit \( g' \to 0 \).

Moreover it should be noticed that not all the invariants parameterized by the \( \lambda \)'s are on-shell independent. Therefore the question arises of whether the same \( v/\Lambda \) behaviour holds true once the on-shell reduction is carried out.

In Appendix A4 we provide the relevant linear combinations of the invariants that are on-shell independent and contain the minimum number of covariant derivatives. As the coefficients of those linear combinations are analytical...
in $v, e^2 = M_A^2/v^2, \lambda = M^2/v^2$, also the on-shell independent projections can be expanded in powers of $v/\Lambda$ and the remaining coupling constants of the model.

As a final remark, it is instructive to compare these on-shell invariants with those of the Warsaw basis [41]. This is done in Appendix A5. In particular we notice that the change of variables is still analytic in the coupling constants and $v^2$. However, since in the Warsaw basis the v.e.v. is unsubtracted, the tower of invariants contributing to a given amplitude is in general infinite. For instance, in the simplest case (the tadpole) each invariant

$$\langle \phi^3 \phi \rangle^n = \left[ \frac{1}{2} (\sigma + v)^2 + \chi^2 \right]^n \sim \frac{v^{2n}}{2^n} + \frac{n!2^{n-1}}{2^{n-1}} \sigma + \cdots$$

(6.13)

contributes to the 1-point $\sigma$-amplitude. This is not the case for the choice of the contractible pairs basis, since by subtracting the v.e.v. in the combination $\phi^3 \phi - v^2 \phi$, the linear system to be solved is truncated and only a finite number of amplitudes has to be evaluated in order to fix the invariant coefficients.

6.3 $\beta$-functions

It is now immediate to construct the $\beta$-functions of the theory. Renormalization implies that the running of the coupling $\tilde{\lambda}_i$ in the target theory is determined by the corresponding $\beta$-function $\beta_i$

$$\beta_i = (4\pi)^2 \frac{d}{d \log \mu} \tilde{\lambda}_i.$$  

(6.14)

Then, taking into accounts only terms proportional to the beyond the SM coupling $g$ we can write

$$\beta_i \supset - (4\pi)^2 C_i,$$  

(6.15)

where the coefficients $C_i$ are obtained from the corresponding $\tilde{\lambda}_i$ dropping terms proportional to the power counting renormalizable couplings and replacing $g/\Lambda$ with $\tilde{\lambda}_7$ as dictated by Eqs. (2.1) and (A6).

In the linear approximation we finally obtain

$$\beta_i \supset c_i \tilde{\lambda}_7,$$  

(6.16)

with

$$c_1 = \frac{1}{v} (M_A^4 - 3M_A^2),$$

$$c_2 = \frac{2}{v^3} (3M_A^4 + M^2M_A^2 - 6M_A^2),$$

$$c_3 = \frac{2}{v^3} (5M_A^4 + 2M^2M_A^2 - 6M_A^4);$$

$$c_4 = \frac{1}{v} (3M_A^2 + 7M_A^2),$$

$$c_5 = 0;$$

$$c_6 = 0,$$

$$c_7 = \frac{2}{v^3} (4M_A^2 + 9M_A^2);$$

$$c_8 = \frac{1}{3v} M_A^2,$$

$$c_9 = 0;$$

$$c_{10} = 0.$$  

(6.17)

7 Conclusions

We have presented the explicit evaluation of all the UV coefficients of dimension less or equal to 6 operators in an Abelian spontaneously broken gauge theory supplemented with a maximally power counting violating derivative interaction of dimension 6. This has been possible by following the methodology put forward in a companion paper [17], in which one constructs an auxiliary theory based on the $X$-formalism in which a power-counting can be established (thus limiting the number of divergent diagrams one has to consider at each loop order) together with a mapping onto the original theory.

In particular, a separation of the gauge-dependent contributions, associated to the cohomologically trivial invariants, from the genuine physical renormalizations of gauge invariant operators has been achieved, and we have explicitly checked in two different gauges (Feynman and Landau) our results in order to explicitly verify the gauge independence of the coefficients of gauge invariant operators. In this respect it should be clear the pivotal role played by the field redefinitions for the correct identification of the gauge dependent coefficients of the cohomologically trivial invariants and, consequently, of the coefficients of the gauge invariant operators. Purely gauge fixed on-shell calculations will completely miss their contributions, running the risk of obtaining gauge dependent results even in the case of ostensibly gauge invariant quantities. As an example we have derived the complete set of one-loop $\beta$-functions of the model which, after the field renormalization is carried out, can be read immediately from the renormalization coefficient of the corresponding operator.

The techniques presented here and in Ref. [17] are suitable to be generalized to: the inclusion of the complete set of dimension 6 operators; the extension of higher orders in the loop expansion; the extension of non-Abelian case, and, in particular, to the Standard Model effective field theory in which dimension 6 operators are added to the usual $SU(2) \times U(1)$ action. This latter generalization would be especially interesting, as it would allow to better understand the remarkable cancellations and regularities discovered when evaluating the one-loop anomalous dimensions for this model, and which have been linked to holomorphy [42], and/or remnants of embedding supersymmetry [3]. Work in this direc-
tion is currently underway and we hope to report soon on this and related issues.

**Data Availability Statement** This manuscript has no associated data or the data will not be deposited. [Authors’ comment: No data are associated with the present theory paper. Mathematica notebooks are available upon request to the corresponding author.]

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**Appendix A: List of invariants**

1. Pure external sources invariants

The invariants in this sector are

\[ \theta_1 \int d^4x \bar{c}^*; \quad \theta_2 \int d^4x \bar{T}_1, \]
\[ \theta_3 \int d^4x \frac{1}{2} (\bar{c}^*)^2; \quad \theta_4 \int d^4x \frac{1}{2} T_1^2, \]
\[ \theta_5 \int d^4x \frac{1}{2} T_1 \Box T_1; \quad \theta_6 \int d^4x \frac{1}{2} T_1 \Box^2 T_1 \]
\[ \theta_7 \int d^4x \bar{c}^* T_1; \quad \theta_8 \int d^4x \bar{c}^* \Box T_1, \]
\[ \theta_9 \int d^4x \frac{1}{3!} (\bar{c}^*)^3; \quad \theta_{10} \int d^4x \frac{1}{2} (\bar{c}^*)^2 T_1, \]
\[ \theta_{11} \int d^4x \frac{1}{2} (\bar{c}^*)^2 T_1^2; \quad \theta_{12} \int d^4x \frac{1}{3!} T_1^3. \]  (A1)

Notice that \( \theta_6 \) has been inserted for completeness but does not contribute to dim. 6 operators in the target theory.

2. Mixed field-external sources invariants

The invariants in this sector are

\[ \theta_4 \int d^4x T_1 \left( D^\mu \phi \right)^{\dagger} D_\mu \phi, \]
\[ \theta_5 \int d^4x \bar{c}^* \left( (D^2 \phi)^{\dagger} \phi + \text{h.c.} \right); \]
\[ \theta_6 \int d^4x T_1 \left( (D^2 \phi)^{\dagger} \phi + \text{h.c.} \right), \]
\[ \theta_7 \int d^4x \bar{c}^* \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right) ; \]
\[ \theta_8 \int d^4x T_1 \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right), \]
\[ \theta_9 \int d^4x \bar{c}^* F^2_{\mu \nu}, \quad \theta_{10} \int d^4x T_1 F^2_{\mu \nu}, \]
\[ \theta_{11} \int d^4x \bar{c}^* T_1 \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right), \]
\[ \theta_{12} \int d^4x T_1 \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right), \]
\[ \theta_{13} \int d^4x (\bar{c}^*)^2 \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right). \]  (A2)

Notice that the use of the contractible pair basis allows us to re-express the (otherwise present) invariants

\[ \theta_{14} \int d^4x \bar{c}^* \Box \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right); \quad \theta_{15} \int d^4x T_1 \Box \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right). \]  (A3)

in terms of the above, since one has

\[ \Box \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right) = (D^2 \phi)^{\dagger} \phi + \phi^{\dagger} (D^2 \phi) + 2 (D^\mu \phi)^{\dagger} D_\mu \phi, \]  (A4)

and therefore

\[ \theta_{14} = 2 \theta_3 + \theta_5; \quad \theta_{15} = 2 \theta_4 + \theta_6. \]  (A5)

3. Gauge invariants depending only on the fields

The invariants in this sector are

\[ \lambda_1 \int d^4x \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right); \]
\[ \lambda_2 \int d^4x \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right)^2; \]
\[ \lambda_3 \int d^4x \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right)^3; \]
\[ \lambda_4 \int d^4x \left( D^\mu \phi \right)^{\dagger} D_\mu \phi, \]
\[ \lambda_5 \int d^4x \phi^{\dagger} [(D^2)^2 + D^\mu D_\nu D^\sigma D_\mu + D^\mu D^2 D_\mu] \phi; \]
\[ \lambda_6 \int d^4x \left( \phi^{\dagger} \phi - \frac{v^2}{2} \right) \left( \phi^{\dagger} D^2 \phi + (D^2 \phi)^{\dagger} \phi \right). \]
\[ \lambda_7 \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) (D^\mu \phi)^\dagger D_\mu \phi; \]
\[ \frac{\lambda_8}{2} \int d^4 x F_{\mu \nu}^2; \]
\[ \lambda_9 \int d^4 x \partial^\mu F_{\mu \nu} \partial^\nu F_{\rho \nu}; \]
\[ \lambda_{10} \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) F_{\mu \nu}^2. \] (A6)

These invariants are the only ones appearing also in the target theory; in that case the associated coefficient will be indicated as \( \tilde{\lambda}_i \) (with \( i = 1, \ldots, 10 \)).

4. On-shell reduction

Let us denote by \( \mathcal{J}_j \) the gauge invariant of coefficient \( \tilde{\lambda}_j \) and by \( S \) the classical gauge-invariant action in the target theory, namely

\[ S = \int d^4 x \left[ -\frac{1}{4} F_{\mu \nu} F_{\mu \nu} + (D^\mu \phi)^\dagger (D_\mu \phi) - \frac{M^2}{2v^2} \left( \phi^\dagger \phi - \frac{v^2}{2} \right)^2 \right]. \] (A7)

The \( \mathcal{J}_j \)'s are not all independent if one imposes the tree-level equations of motion

\[ \frac{\delta S}{\delta \phi^\dagger} = -D^2 \phi - \frac{M^2}{v^2} \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \phi = 0, \]
\[ \frac{\delta S}{\delta \phi} = -(D^2 \phi)^\dagger - \frac{M^2}{v^2} \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \phi^\dagger = 0, \]
\[ \frac{\delta S}{\delta A^\mu} = \partial^\nu F_{\nu \mu} - i e [(D_\mu \phi)^\dagger \phi - \phi^\dagger D_\mu \phi] = 0. \] (A8)

We use this freedom in order to select as an on-shell basis the independent invariants with a minimum number of covariant derivatives, which are: \( \mathcal{J}_1, \mathcal{J}_2, \mathcal{J}_3, \mathcal{J}_7, \mathcal{J}_8, \mathcal{J}_{10} \).

Indeed, consider for instance \( \mathcal{J}_1 \); integrating by parts and using the first of Eq. (A8) we get

\[ \mathcal{J}_1 = \int d^4 x \phi^\dagger D^2 \phi = \int d^4 x \frac{M^2}{v^2} \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \phi^\dagger \phi = \frac{M^2}{2v^2} \mathcal{J}_1 + \frac{M^2}{v^2} \mathcal{J}_2. \] (A9)

Next, let us consider

\[ \mathcal{J}_5 = \int d^4 x \phi^\dagger \left[ (D^2)^2 + D^\mu D^\nu D_\mu D_\nu \right] \phi. \] (A10)

The first term can be reduced by using again the first of Eq. (A8) and integration by parts:

\[ \int d^4 x \phi^\dagger (D^2)^2 \phi = \frac{M^4}{v^2} \int d^4 x \left( \phi^\dagger \phi - \frac{v^2}{2} \right) \phi^\dagger \phi = \frac{M^4}{2v^2} \mathcal{J}_2 + \frac{M^4}{v^4} \mathcal{J}_3. \] (A11)

The second term of Eq. (A10) reads instead

\[ \int d^4 x \phi^\dagger D^\mu D^\nu D_\mu D_\nu \phi = \int d^4 x \phi^\dagger D^\mu D^\rho D_\mu D_\rho \phi + \int d^4 x D^\mu D^\rho [D_\mu, D_\rho] \phi = \int d^4 x \phi^\dagger D^\mu D^\rho D_\mu D_\rho \phi - ie \int \phi^\dagger D^\mu D^\rho F_{\rho \mu} \phi, \] (A12)

where in the last line we have used the relation

\[ [D_\mu, D_\nu] = -ieF_{\mu \nu}. \] (A13)

By further anti-symmetrizing the last term of Eq. (A12) we finally obtain

\[ \int d^4 x \phi^\dagger D^\mu D^\nu D_\mu D_\nu \phi = \int d^4 x \phi^\dagger D^\mu D^\rho D_\mu D_\rho \phi + \int d^4 x F_{\mu \nu} \phi^\dagger \phi = \int d^4 x \phi^\dagger D^\mu D^\rho D_\mu D_\rho \phi + \frac{e^2}{2} \mathcal{J}_8 + \frac{e^2 v^2}{4} \mathcal{J}_{10}. \] (A14)

The third term of Eq. (A10) can be finally treated in a similar way:

\[ \int d^4 x \phi^\dagger D^\mu D^\rho D_\mu D_\rho \phi = \int d^4 x \phi^\dagger (D^2)^2 \phi + \int d^4 x \phi^\dagger D^\mu [D^\rho, D_\mu] D_\rho \phi = \int d^4 x (D^2 \phi)^\dagger D^2 \phi - ie \int d^4 x F_{\mu \nu} (D^\mu \phi)^\dagger D^\rho \phi. \] (A15)
The second term in the above Equation can be reduced by using the equation of motion as follows:

\[-ie \int d^4x \, F_{\mu\nu} (D^\mu \phi)^\dagger D^\nu \phi\]
\[= -\frac{ie}{2} \int d^4x \, F_{\mu\nu} \left[ (D^\mu \phi)^\dagger D^\nu \phi + (D^\nu \phi)^\dagger D^\mu \phi \right]\]
\[= -\frac{ie}{2} \int d^4x \left[ -\partial^\mu F_{\mu\rho} (D^\rho \phi)^\dagger D^\nu \phi - F_{\mu\rho} (D^\rho D^\mu \phi)^\dagger + \partial^\mu F_{\mu\rho} (D^\rho \phi)^\dagger - F_{\mu\rho} (D^\rho D^\mu \phi)^\dagger \right] \quad (A16)\]

where in the r.h.s. in the first line of the above equation we have integrated by parts w.r.t. \((D^\mu \phi)^\dagger\) (respectively \(D^\mu \phi\)) in the first (respectively second) term.

By anti-symmetrizing the terms containing the field strength and by using Eq. (A13) we eventually obtain

\[-ie \int d^4x \, F_{\mu\nu} (D^\mu \phi)^\dagger D^\nu \phi\]
\[= \int d^4x \left\{ i e \partial^\mu F_{\mu\rho} \left[ (D^\rho \phi)^\dagger D^\nu \phi - (D^\nu \phi)^\dagger D^\rho \phi \right] + \frac{e^2}{2} F_{\mu\rho}^2 \phi^\dagger \phi \right\}. \quad (A17)\]

Use of the \(A_{\mu}\)-equation of motion Eq. (A8) then yields

\[-ie \int d^4x \, F_{\mu\nu} (D^\mu \phi)^\dagger D^\nu \phi\]
\[= -\frac{e^2}{2} \int d^4x \left\{ 2 \phi^\dagger D^\mu \phi (D^\mu \phi)^\dagger - (D^\mu \phi)^\dagger \phi^\dagger (D^\mu \phi)^\dagger \phi + \frac{e^2}{2} F_{\mu\rho}^2 \phi^\dagger \phi \right\} \quad \text{A23}\]

By direct computation and after a certain number of integrations by parts one can check that

\[\int d^4x \left[ (D^\mu \phi)^\dagger \phi (D^\mu \phi)^\dagger + \phi^\dagger D^\mu \phi \phi^\dagger D^\mu \phi \right] \]
\[= -e^2 \int d^4x \times \left\{ 4 \phi^\dagger \phi (D^\mu \phi)^\dagger D^\mu \phi + \phi^\dagger \phi \left[ \phi^\dagger D^2 \phi + (D^2 \phi)^\dagger \phi \right] \right\}. \quad (A19)\]

By plugging Eqs. (A19) and (A18) into (A15) we arrive at the following result:

\[\int d^4x \, \phi^\dagger D^\mu D^\nu D^\rho D^\sigma \phi\]
\[= \int d^4x \, \phi^\dagger (D^2)^\dagger \phi + \frac{e^2 v^2 M^2}{4} \mathcal{J}_1 + e^2 M^2 \mathcal{J}_2 + \frac{e^2 M^2}{v^2} \mathcal{J}_3\]
\[= \frac{3}{2} e^2 v^2 \mathcal{J}_4 - 3 e^2 \mathcal{J}_5 + \frac{e^2 v^2}{4} \mathcal{J}_6 + e^2 \mathcal{J}_{10}. \quad (A20)\]

Putting everything together we arrive at the on-shell reduction (recall that \(M_A = ev\)):

\[\mathcal{J}_5 = -M_A^2 M^2 \mathcal{J}_1 + \frac{M_A^2}{2} \left( \frac{3 M_A^2}{v^2} - \frac{2 M_A^2}{v^2} \right) \mathcal{J}_2\]
\[+ \frac{M_A^2}{2} \left( \frac{3 M_A^2}{v^2} + \frac{M_A^2}{v^2} \right) \mathcal{J}_3\]
\[= \frac{6 M_A^2}{v^2} \mathcal{J}_7 + \frac{3}{4} M_A^2 \mathcal{J}_3 + \frac{3}{2} M_A^2 \mathcal{J}_{10}. \quad (A21)\]

By using the \(\phi, \phi^\dagger\)-equations of motion \(\mathcal{J}_6\) can be reduced as

\[\mathcal{J}_6 = -M_A^2 \mathcal{J}_2 - \frac{2 M_A^2}{v^2} \mathcal{J}_3 \quad (A22)\]

while by using the \(A_{\mu}\)-equation of motion and Eq. (A19) \(\mathcal{J}_9\) can be expressed as

\[\mathcal{J}_9 = -\frac{M_A^2 M^2}{2} \mathcal{J}_1 - \frac{2 M_A^2 M^2}{v^2} \mathcal{J}_2 - \frac{2 M_A^2 M^2}{v^2} \mathcal{J}_3\]
\[+ 3 M_A^2 \mathcal{J}_4 + \frac{6 M_A^2}{v^2} \mathcal{J}_7\]
\[= M_A^2 M^2 \mathcal{J}_1 + \frac{M_A^2 M^2}{v^2} \mathcal{J}_2 - \frac{2 M_A^2 M^2}{v^2} \mathcal{J}_3 + \frac{6 M_A^2}{v^2} \mathcal{J}_7, \quad (A23)\]

where in the second line we have eliminated \(\mathcal{J}_3\) via Eq. (A9).

By direct inspection we see that the coefficients of the linear combinations of the on-shell reduction are polynomials in \(e^2 = M_A^2/v^2, \lambda = M^2/v^2\) and \(v^2\).

5. Comparison with the Warsaw basis

The Warsaw basis invariants [41] in the dimension 6 sector of the Abelian theory are

\[\mathcal{W}_{R,1} = \int d^4x \, (\phi^\dagger \phi)^3, \quad \mathcal{W}_{R,2} = \int d^4x \, \phi^\dagger \phi \Box \phi^\dagger \phi, \quad \mathcal{W}_{R,3} = \int d^4x \, (\phi^\dagger D^\mu \phi)^\dagger \phi^\dagger D^\mu \phi, \quad \mathcal{W}_{R,4} = \int d^4x \, \phi^\dagger \phi F_{\mu\nu}^2. \quad (A24)\]
These are not on-shell independent, since by using the equation of motion for \(\phi, \phi^\dagger\) one gets the relation

\[
\mathcal{W}_{B,2} = \int d^4x \phi^\dagger \phi \Box \phi^\dagger \phi \\
= \int d^4x \phi^\dagger \phi \left\{ (D^2 \phi)^\dagger \phi + \phi^\dagger (D^2 \phi) + 2(D^\mu \phi)^\dagger D_\mu \phi \right\} \\
= -\frac{2M^2}{v^2} \int d^4x (\phi^\dagger \phi)^3 + M^2 \int d^4x (\phi^\dagger \phi)^2 \\
+ 2 \int d^4x \phi^\dagger (D^\mu \phi)^\dagger D_\mu \phi \\
= M^2 \int d^4x (\phi^\dagger \phi)^2 - \frac{2M^2}{v^2} \mathcal{W}_{B,1} + 2 \mathcal{W}_{B,3} \\
= -M^2 \mathcal{J}_6 - \frac{2M^2}{v^2} \mathcal{J}_3 + 2 \mathcal{J}_7. \tag{A25}
\]

Then one can straightforwardly obtain the decomposition for the \(\mathcal{W}_{B,j} \ j = 1, 3, 4\) in terms of the \(\mathcal{J}'s:\)

\[
\begin{align*}
\mathcal{W}_{B,1} &= \frac{\delta^3}{8} + \frac{3}{4} v^4 \mathcal{J}_1 + \frac{3}{2} v^2 \mathcal{J}_2 + \mathcal{J}_3, \\
\mathcal{W}_{B,3} &= \frac{M^2 v^2}{4} \mathcal{J}_1 + \frac{M^2}{2} \mathcal{J}_2 + \mathcal{J}_7, \\
\mathcal{W}_{B,4} &= \frac{v^2}{2} \mathcal{J}_8 + \mathcal{J}_{10}. \tag{A26}
\end{align*}
\]

Notice the consistency condition

\[
\mathcal{W}_{B,2} = \mathcal{J}_6 + 2 \mathcal{J}_7 \tag{A27}
\]

which holds true since on-shell

\[
\mathcal{J}_6 + M^2 \mathcal{J}_2 + \frac{2M^2}{v^2} \mathcal{J}_3 = 0. \tag{A28}
\]

Appendix B: UV divergent ancestor amplitudes

1. Tadpoles

\[
\begin{align*}
\Gamma_{\phi^\dagger \phi^\dagger}^{(1)} &= -\frac{M^2 + (1 - \delta_{\xi 0}) M_A^2}{16\pi^2 \epsilon}, \tag{B1a} \\
\Gamma_{\mathcal{T}_1}^{(1)} &= -\frac{(M^4 - 3M_A^4)}{16\pi^2 \epsilon}, \tag{B1b} \\
\Gamma_{\sigma}^{(1)} &= \frac{1}{16\pi^2 v} \\
&\times \left[ m^2 M^2 + (1 - \delta_{\xi 0}) m^2 M_A^2 + 2(M^4 + 3M_A^4) \right] \frac{1}{\epsilon}. \tag{B1c}
\end{align*}
\]

2. Two-point functions

\[
\begin{align*}
\Gamma_{\chi^\dagger \chi}^{(1)} &= \frac{cM_A^2 1}{8\pi^2 \epsilon} \left( \delta_{\xi 0} - 1 \right), \tag{B2a} \\
\Gamma_{\chi \chi}^{(1)} &= \frac{1}{32\pi^2 \epsilon^2} \\
&\times \left\{ 2m^2(M^2 + M_A^2) + 4(M^4 + 3M_A^4) \\
&- \frac{1}{16\pi^2 v^2} M_A^2 (m^2 + 2p^2) \frac{\delta_{\xi 0}}{\epsilon} \\
&- \left[ \frac{g^2 v}{\Lambda} M_A^2 (4 - \frac{g^2 v}{\Lambda}) \\
&+ (\frac{M^2 (m^2 + 2p^2) \delta_{\xi 0}}{16\pi^2 v^2}) \frac{1}{\epsilon^2} \right] p^2 \\
&+ \frac{g^2 v^2}{\Lambda^2} p^4 \right\} \frac{1}{\epsilon^2}, \tag{B2b} \\
\Gamma_{\sigma \sigma}^{(1)} &= \frac{1}{16\pi^2 v^2} \\
&\times \left\{ 2m^2(M^2 + M_A^2) + 6(M^4 + 3M_A^4) \\
&- \left[ 4M_A^2 + 2 \frac{g^2 v}{\Lambda} (m^2 + 2M^2) \right] p^2 \\
&+ \frac{g^2 v^2}{\Lambda^2} p^4 \right\} \frac{1}{\epsilon}, \tag{B2c} \\
\Gamma_{\phi^\dagger \phi}^{(1)} &= \frac{-M_A^2}{32\pi^2 v^2} \\
&\times \left\{ M_A^2 \frac{g^2 v}{\Lambda} (4 - \frac{g^2 v}{\Lambda}) \\
&+ M_A^2 \left[ 4(4 - \delta_{\xi 0}) + 12 \frac{g^2 v}{\Lambda} + 3 \frac{g^2 v^2}{\Lambda^2} \right] p^2 \\
&+ \frac{1}{3} \left[ (4 + \frac{g^2 v}{\Lambda})^2 \right] \frac{2}{\epsilon} \\
&+ \left[ \frac{M_A^2}{24\pi^2 v} \left( 1 + \frac{g^2 v}{\Lambda} + \frac{g^2 v^2}{\Lambda^2} \right) \right] p^2 \frac{1}{\epsilon} \right\} \frac{1}{\epsilon} \tag{B2d} \\
\Gamma_{\phi^\dagger \phi}^{(1)} &= \frac{1}{16\pi^2} \left[ 2M^2 + 2M_A^2 (1 - \delta_{\xi 0}) - p^2 \right] \frac{1}{\epsilon}, \tag{B2f} \\
\Gamma_{\mathcal{T}_1 \mathcal{T}_1}^{(1)} (p^2) &= \frac{1}{32\pi^2} \\
&\times \left\{ 6(M^4 + M_A^4) - 3(M^2 + M_A^2) p^2 + p^4 \right\} \frac{1}{\epsilon}, \tag{B2g} \\
\Gamma_{\mathcal{T}_1 \sigma}^{(1)} (p^2) &= \frac{-1}{32\pi^2 v} \\
&\times \left\{ 4m^2(M^2 + M_A^2) + 8(M^4 - 3M_A^4) \\
&- 2 \left( m^2 + M^2 - M_A^2 + 2M_A^2 \frac{g^2 v}{\Lambda} \right) p^2 \right\}. \tag{B2c}
\end{align*}
\]
\[
\Gamma^{(1)}_{\bar{c}^{\ast}c\sigma}(p^2) = \frac{1}{16\pi^2 v} \left[ -2(m^2 + M^2) + \frac{g v}{\Lambda} \frac{m}{v} \right], \quad (B2i)
\]

3. Three-point functions

\[\Gamma^{(1)}_{\bar{c}^{\ast}T_1} = -\frac{1}{4\pi^2 v} \epsilon, \quad (B3a)\]

\[\Gamma^{(1)}_{\bar{c}^{\ast}T_1} \mid_{p_1=p_2=0} = -\frac{3M^2 + 2M^2_{A}}{8\pi^2} \frac{1}{\epsilon} + \frac{M^2_{A}}{4\pi^2} \frac{\delta_{\theta_0}}{\epsilon}, \quad (B3b)\]

\[\Gamma^{(1)}_{T_1T_1} = -\frac{3M^4}{4\pi^2} \frac{1}{\epsilon}, \quad (B3c)\]

\[\Gamma^{(1)}_{\bar{c}^{\ast}T_1\sigma} = \frac{m^2 + M^2 + \frac{M^2}{\Lambda}}{4\pi^2 v} \frac{1}{\epsilon} - \frac{M^2_{A}}{8\pi^2 v^2} \frac{\delta_{\theta_0}}{\epsilon}, \quad (B3d)\]

\[\Gamma^{(1)}_{\bar{c}^{\ast}A_{\mu}A_{\nu}}(p_1, p_2) = -\frac{M^2_{A}}{16\pi^2 v^2} \frac{g^2}{\Lambda^2} \frac{g_{\mu\nu}}{v} \frac{1}{\epsilon}, \quad (B3e)\]

\[\Gamma^{(1)}_{T_1A_{\mu}A_{\nu}}(p_1, p_2) = \frac{M^2_{A}}{32\pi^2 v^2} \times \left[ \frac{g v}{\Lambda} \left( 8 - 3 \frac{g v}{\Lambda} \right) M^2 
- \left( 8 + 4\delta_{\theta_0} - 3 \frac{g^2 v^2}{\Lambda^2} \right) M^2_{A} 
+ \frac{2}{3} \frac{g v}{\Lambda} \left( 1 + 2 \frac{g v}{\Lambda} \right) (p_1^2 + p_2^2) 
+ \frac{2}{3} \frac{g^2 v^2}{\Lambda^2} p_1 \cdot p_2 \frac{1}{\epsilon}, 
- \frac{1}{96\pi v} \frac{g}{\Lambda} M^2_{A} \left( 2 + \frac{g v}{\Lambda} \right) 
\right] (p_1\mu p_1\nu + p_2\mu p_2\nu) \frac{1}{\epsilon} + \frac{M^2}{16\pi^2 v^2} \frac{g^2}{\Lambda^2} p_1 \cdot p_2, \quad (B3f)\]

\[\Gamma^{(1)}_{A_{\mu}A_{\nu}}(p_1, p_2) = -\frac{M^2_{A}}{16\pi^2 v^5} \times \left[ 3 \left( 4 + 8 \frac{g v}{\Lambda} + 3 \frac{g^2 v^2}{\Lambda^2} \right) M^2_{A} 
- \frac{g^2 v^2}{\Lambda^2} m^2 + \frac{g v}{\Lambda} \left( 8 - 3 \frac{g v}{\Lambda} \right) M^2_{A} 
+ \frac{1}{6} \frac{g v}{\Lambda} \left( 4 - 10 \frac{g v}{\Lambda} + 3 \frac{g^2 v^2}{\Lambda^2} \right) (p_1^2 + p_2^2) 
\right] (p_1\mu p_1\nu + p_2\mu p_2\nu) \frac{1}{\epsilon} + \frac{1}{4\pi^2 v^2} \frac{g}{\Lambda} M^2_{A} \left( 2 + 7 \frac{g v}{\Lambda} \right) \times (p_1\mu p_1\nu + p_2\mu p_2\nu) \frac{1}{\epsilon} + \frac{M^2}{8\pi^2 v^2} \frac{\delta_{\theta_0}}{\epsilon}, \quad (B3g)\]

\[\Gamma^{(1)}_{\bar{c}^{\ast}c\sigma}\mid_{p_1=p_2=0} = -\frac{1}{8\pi^2 v^2} (m^2 + M^2 - M^2_{A}) \frac{1}{\epsilon} - \frac{M^2_{A}}{8\pi^2 v^2} \frac{\delta_{\theta_0}}{\epsilon}, \quad (B3h)\]

\[\Gamma^{(1)}_{T_1A_{\mu}A_{\nu}}\mid_{p_1=p_2=0} = -\frac{1}{8\pi^2 v^2} (m^2 + M^2 - M^2_{A}) \frac{1}{\epsilon} - \frac{M^2_{A}}{8\pi^2 v^2} \frac{\delta_{\theta_0}}{\epsilon}, \quad (B3i)\]

\[\Gamma^{(1)}_{\bar{c}^{\ast}c\sigma}\mid_{p_1=p_2=0} = -\frac{1}{8\pi^2 v^2} (m^2 + M^2 - M^2_{A}) \frac{1}{\epsilon} - \frac{M^2_{A}}{8\pi^2 v^2} \frac{\delta_{\theta_0}}{\epsilon}, \quad (B3j)\]

\[\Gamma^{(1)}_{T_1\sigma}\mid_{p_1=p_2=0} = -\frac{1}{8\pi^2 v^2} (2m^2 + 5m^2 M^2 + 6M^4 + 3m^2 M^2 - 18M^4_{A}) \frac{1}{\epsilon} + \frac{3m^2 M^2_{A}}{8\pi^2 v^2} \frac{\delta_{\theta_0}}{\epsilon}, \quad (B3k)\]

\[\Gamma^{(1)}_{T_1T_1}\mid_{p_1=p_2=0} = \frac{1}{8\pi^2 v^2} \times \left[ m^2 (3M^2 + 2(1 - \delta_{\theta_0})M^2_{A}) + 6(M^4 + M^4_{A}) \right] \frac{1}{\epsilon}, \quad (B3l)\]

\[\Gamma^{(1)}_{\bar{c}^{\ast}c\sigma} = 0, \quad (B3m)\]

\[\Gamma^{(1)}_{\sigma\sigma}\mid_{p_1=p_2=0} = \frac{3}{8\pi^2 v^5} \times \left( m^4 + 2m^2 M^2 + 2M^4 - m^2 M^2_{A}(1 - \delta_{\theta_0}) + 6M^4_{A} \right) \frac{1}{\epsilon}, \quad (B3n)\]
