Influence of process parameters for sheet lamination based on laser micro-spot welding of austenitic stainless steel sheets for bone tissue applications

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Abstract
The laser micro-spot welding process was studied to implement a sheet lamination process-based methodology for the fabrication of austenitic stainless steel scaffolds. AISI 302 sheets with a thickness of 254 μm were laser cut and laser welded. Experimental tests were carried out with different values of average laser power (i.e., 180, 200, and 220 W) and different exposure times (25, 50, 75, 100, 125 ms). The micro-spot welds were visually inspected according to the ISO 13919-1 Class B requirements. Spot welds were qualitatively characterized, and weld dimensions were measured (i.e., penetration depth, top, middle, and bottom width and the heat-affected zone (HAZ)) to identify the cross-sectional shape. Furthermore, process efficiencies (i.e., coupling, melting, and process) were studied. A seam welding model was adapted to calculate the required exposure time and was used to obtain a micro-spot weld to accomplish the quality requirements of the scaffold. A scaffold prototype was designed and manufactured using the selected parameters by experimental trials and using the mathematical model (i.e., a laser power of 220 W and an exposure time of 45 ms).

Keywords Laser micro-spot welding · Stainless steel · Sheet lamination · Metallic scaffolds

1 Introduction

Scaffolds for bone tissue engineering have been developed to deal with the increased need of reconstruction procedures in orthopedics due to trauma, tumor, deformity, degeneration, and an aging population [1]. Porous metallic scaffolds for long-term replacement of bone defects provide an interfacial porosity as well as a permanent structural framework. Although there are several biocompatible metallic materials (i.e., stainless steel, magnesium alloys, titanium alloys, Ni-Ti alloys, and tantalum) frequently used in the replacement of bone in dental and orthopedic surgery, AISI 316L stainless steel alloy has been employed as a standard surgical material [2]. Additionally, AISI 302 and AISI 304 alloys are commonly used for orthodontic wires due to their high strength, elasticity, and formability additional to its low manufacturing cost. Besides, these materials achieve the biocompatibility feature in stomatognathic tissues [3].

Laser-based additive processes present high potential in the fabrication of scaffolds due to its ability to produce complex geometries that mimic the structure and mechanical properties of the human bone despite its high cost of implementation and lack of ability to produce high volumes [4]. For example, Dewidar et al. [5] fabricated austenitic AISI 316L stainless steel scaffolds with a 50% porosity, an elastic modulus, and a compression strength close to the human’s cortical bone through the selective laser sintering (SLS) process. Čapek and Vojtěch [6] explored the mechanical properties (i.e., tensile, compressive, and flexural tests) of austenitic AISI 316L stainless steel to produce highly porous cylindrical scaffolds using selective laser melting (SLM) with mechanical properties close to those of cancellous bone. According to the additive manufacturing terminology standard (ISO/ASTM 52900–15), sheet lamination processes are based on adding layers of sheets which are joined through several manufacturing methods. Xu et al. [7] proposed the micro-DLOM (double-stage layer object manufacturing) to fabricate stainless steel micro-cavity molds. These molds were produced by laser cutting metallic foils and the resistance slip spot welding...
to join the metallic foils with good surface quality (i.e., 0.07 μm of surface roughness) and good accuracy in height direction. Lie et al. [8] fabricated stainless steel micro-electrodes with ~92 μm of width using the micro-DLOM and WEDM (wire electrical discharge machining). Hung et al. [9] compared AISI 304L stainless steel parts produced by LFP (laser foil printing) and SLM to analyze the chemical composition and mechanical properties. Their results revealed that the LFP process produces solid parts through laser cutting and laser seam welding with lower oxygen content and higher tensile strength but lower ductility in comparison to the SLM parts. All studies based on sheet lamination process found in the literature were constructed from solid parts and were joined through continuous seam welds. However, to the best of our knowledge, there are no reported articles using spot welding as the joining process. Laser micro-welding is able to join all types of metallic materials and produces joints with high strength, which are consistent with those of the base material [10].

Table 1 presents several studies focused on the laser micro-welding of austenitic stainless steels (i.e., AISI 302, AISI 304, and AISI 316). These works analyze the influence of laser welding parameters on weld width and weld penetration depth. Sun et al. [11] studied the influence of different shielding gasses in pore’s formation in the laser seam welds of AISI 304 plates with 20 mm of thickness. The results demonstrated that shielding gas has a great influence in pore formation, and several pores were found in seam welds when Ar was used, but when N₂ or no gas was used, the seam welds presented almost no pores. Kumar et al. [12] performed a comparative study of the laser seam welding of AISI 304 and AISI 316 stainless steel alloys. The results demonstrated that higher linear heat input is required in the AISI 304 alloy compared to the AISI 316 alloy to obtain the maximum ultimate strength of the seam weld. Only two studies have been performed on the laser micro-spot welding of stainless steel alloys [13, 14]. Siva Shanmugam et al. [13] presented a finite element model (FEM) comparing the simulation with experimental trials for the laser micro-spot welding of austenitic AISI 304 stainless steel sheets of 2.5 mm thickness in bead on plate configuration. Cedeño-Viveros et al. [14] experimentally studied the influence of laser power and focal distances in laser micro-spot welds in austenitic AISI 302 stainless steel sheets of 0.254 mm of thickness in an overlap joint configuration.

Some mathematical models have been developed to study the influence of process parameters on the process’ efficiency and heat dissipation. Hipp et al. [15] presented a high-accuracy method for the determination of the coupling and melting efficiency based on measuring the temperature-time curves and laser seam welds conducted in AISI 304 plates of 1 mm. Patschger et al. [16] calculated the process’ efficiencies of the laser micro-welding of austenitic AISI 304 stainless steel foils to determine the amount of energy used to melt the material and the amount of energy lost in heat dissipation. Tadamalle et al. [17] studied the welding speed effect in the laser micro-welding process through a semi-empirical model which showed high process efficiency at welding speeds of 7 mm/s or above. Both models have been focused on determining the process’ efficiency of the laser micro-seam welding process using feed rate (v) in the calculations. However, no mathematical model for the laser micro-spot welding (i.e., feed rate equal to zero) melting efficiency calculation was found in literature.

According to Narayan et al. [10], the advantage of using two or more laser-based micro-fabrication processes may play an important role in the future development of the fabrication of biomaterials in different applications (i.e., neural implants, ophthalmic implants, cardiovascular devices, transdermal microneedles). Laser micro-cutting and micro-welding have shown a promising future in the medical industry. For example, laser micro-cutting has demonstrated great potential to fabricate one of the most demanding medical devices.

| Ref. | Alloy (thickness) | Welding type (configuration) | Laser mode | Laser power (W) | Weld width (μm) | Weld penetration depth (μm) |
|------|-----------------|-----------------------------|------------|----------------|----------------|-----------------------------|
| [13] | AISI 304 (2.500 mm) | Spot (bead on plate) | CW | 100–500 | 827–1696 | 554–1712 |
| [14] | AISI 302 (0.254 mm) | Spot (overlap) | CW | 100–250 | 173–3350 | 108–508 |
| [24] | AISI 304 (0.120 mm) | Seam (overlap) | Q-switch | 133–267 | 300 | 120 |
| [25] | AISI 316L (0.200 mm) | Seam (overlap) | Pulsed | 250–625 | 500–700 | 100–200 |
| [16] | AISI 304 (0.010 mm) | Seam (overlap) | CW | 50–780 | 22–74 | 15–50 |
| [17] | AISI 304L (0.500 mm) | Seam (bead on plate) | Pulsed | 1380 | 648–845 | 100–472 |
| [26] | AISI 316 (0.600 mm) | Seam (bead on plate) | Pulsed | 2000 | 318–737 | 170–600 |
coronary stents, with high accuracy and high-quality surface finish [18]. Additionally, advantages of the laser micro-welding process are high precision, due to the small size of the laser spot, non-contact to prevent contamination, and excellent weld quality with low heat input [19]. Although laser micro-cutting and micro-spot welding have not been used for to fabricate 3D metallic scaffolds, Itälä et al. [20] manufactured triangle-shaped titanium scaffolds with standard dimensions (a base of 10 mm, a height of 5 mm, and a thickness of 250 μm) and different pore sizes (i.e., 50, 75, 100, and 125 μm) with a dimensional accuracy of less than 17 μm using a laser perforation process. Geng et al. [21] produced pure Mg scaffolds by laser perforation with round pores of 500 μm and with a honeycomb distribution controlling the pore’s morphology, size, and the final scaffold porosity. Yu et al. [22] fabricated cylindrical AZ31 magnesium scaffolds with evenly distributed pores with an average 300 μm size using laser perforation. The main advantage of the fabrication of metallic scaffolds by the laser perforation method is the simplicity to control the scaffold’s structure and the pore’s shape, size, and distribution [23].

This work proposed a new related sheet lamination process to produce austenitic stainless steel AISI302 porous scaffolds through a process chain. These 3D structures were fabricated through the laser micro-cutting of thin sheets with miniature patterns stacked in an overlap configuration and joined by laser welding of discrete points. Laser micro-spot welding parameters (i.e., average laser power, exposure time, and beam diameter) were determined based on weld width and penetration depth to produce a class B laser weld based on ISO13919-1 [27] requirements. Welds were studied to analyze the influence of laser welding parameters on the spot weld dimensions, heat-affected zone (HAZ), and the process’ efficiency ($\eta_{pro}$).

### 2 Materials and methods

#### 2.1 Material characterization

The material used was cold rolled and fully hardened AISI 302 austenitic stainless steel sheets (PRECISION BRAND, IL, USA) with 0.254 mm thickness. The material selection was based on commercial availability and similar mechanical properties to AISI 316L [5] and cortical bone [28]. The chemical composition of this material is listed in Table 2. This was obtained with atomic absorption spectroscopy method (Laboratorios Fairchild, NL, Mexico) based on ASTM E-1024 [29].

#### 2.2 Stack sample laser experiments

Based on our previous results, an average laser power ($P_{AVG}$) of 175 W, an exposure time ($t$) of 250 ms, and a laser measured spot diameter ($d_t$) of 193 μm promoted well-formed micro-spot welds and enabled the overlap joint of two AISI 302 sheets of 254 μm of thickness [14]. A process parameter validation was performed before proceeding to build a porous scaffold. The aim of the study was to achieve higher penetration depth ($h$) and to assure the proper joint of the three AISI 302 sheets. The experiments were performed in a MedPro machine (Preco Inc, WI, USA). This machine has an YLR-150/1500-QCW-AC fiber laser source from IPG photonics (IPG photonics, MA, USA) adapted to a fiber core diameter of 50 μm. The beam was focused using a 60-mm collimating lens, and a 50-mm focal lens, resulting in a theoretical spot size of 42 μm. For laser cutting experiments, the laser was set in a modulated continuous wave operating mode; for laser welding, a continuous wave mode was used. A graphical view of the laser’s micro-spot welding input variables (i.e., average laser power and exposure time) and fixed conditions (i.e., laser spot diameter, shielding gas flux, shielding gas pressure, and assist gas pressure) is shown in Fig. 1. An average laser power ($P_{AVG}$) range of 180–220 W was selected, the exposure time ($t$) range was 25–125 ms, and the laser spot diameter ($d_t$) was set to 193 μm. The laser beam spot size was defocused 3 mm from the focal plane. The shielding argon gas flux ($f_x$) remained constant at 11 L/min and the pressure of the shielding gas ($P_{SG}$) and assist gas ($P_{G1}$) was near to 0 Psi. Figure 2a presents the arrangement of the three sheets stacked in an overlap setting, and welding positions ($p_1$, $p_2$) and geometrical dimensions are presented in Fig. 2b, c, respectively. The input variables of average laser power ($P_{AVG}$) and exposure time ($t$) with their respective values of total heat input ($Q_{tot}$) and laser spot diameter ($d_t$) for experimental tests are listed in Table 3.

#### 2.3 Stack sample characterization

Samples were mounted in polyester resin (Poliformas, NL, Mexico) and then were axially cut outside the laser micro-spot weld using a silicon carbide disk cutter. The sectioned samples were prepared in accordance with the specifications of the ASTM E3-11 [30] standard (Standard Guide for Preparation of Metallographic Specimens). Laser spot welds were polished with an alumina (particle size ~ 0.5 μm) and chemically etched with Marble’s reagent (50 mL HCl + 10 g CuSO$_4$ + 50 mL H$_2$O). Measurements of the laser micro-spot welds (i.e., top width ($w_{top}$), middle width ($w_{mid}$), bottom width ($w_{bot}$), and penetration depth ($h$)) were carried out using an

| Table 2: Chemical composition of the AISI 302 sheets |
| C | Cr | Ni | Mn | P | S | Si | Mo |
|---|---|---|---|---|---|---|---|
| 0.05 | 17.5 | 8.1 | 0.87 | 0.003 | 0.002 | 0.25 | 0.19 |
inverted PMG3 optical microscope (Olympus, Tokyo, Japan). Welding defects, such as pore size, lack of penetration, incompletely filled grooves, root cavity, excessive weld metal, and excessive penetration, were measured using ImageJ software (National Institute of Health, MD, USA).

There is no standard for the evaluation by visual inspection of laser micro-spot welds. However, ISO 13919-1 [27] is the current standard to evaluate the laser seam welds in steel by visual inspection. In our investigation, the total material thickness of the three AISI 302 sheets was 762 μm, which accomplishes the ISO 13919-1 standard requirement (i.e., a minimum total thickness of 500 μm). Also, the standard establishes three quality classes for the visual inspection of laser welds (i.e., B, C, and D). Considering that the final application of the laser micro-spot weld is the fabrication of metallic scaffolds for bone implants, Class B was selected as the quality level to accomplish, according to the weld defect and their failure consequences. Additionally, ISO 13919-1 [27] presented the possibility to establish limits for the visual quality evaluation according to calculations referenced by the total thickness of the laser-welded joint. This approach was extrapolated to evaluate the laser micro-spot welds of this investigation.

For the detection of incomplete filled groove, the limit was calculated and set to 38 μm (i.e., 5% of the total material thickness). For the detection of root cavity, the limit was calculated and set to 76 μm (i.e., 10% of the total material thickness) (see Fig. 3a). The limit for the maximum pore size was calculated and set to 22 μm (i.e., 3% of the total material thickness). Lack of penetration should be less than 15% of the total penetration depth (h) of the micro-spot weld (Fig. 3b). For the detection of excessive penetration defect, the limit was set to 114 μm (15% of the total material thickness) (Fig. 3c). Using the limits established for the lack of penetration and excessive penetration, two specification limits were established for the penetration depth (h) of the laser micro-spot welds. The central specification limit (CSL) is the total thickness of the three stacked sheets (i.e., 762 μm). The lower specification limit (LSL) was established adding the lack of penetration limit (0.15 h) to the penetration depth (h). This is equal to the thickness of three stacked sheets. LSL resulted in

| Average laser power, $P_{AVG}$ (W) | Exposure time, $t$ (ms) | Heat input, $Q_{in}$ (J) |
|-----------------------------------|------------------------|-------------------------|
| 180                               | 25                     | 4.5                     |
| 50                                | 9.0                    |                         |
| 75                                | 13.5                   |                         |
| 100                               | 18.0                   |                         |
| 125                               | 22.5                   |                         |
| 200                               | 25                     | 5.0                     |
| 50                                | 10.0                   |                         |
| 75                                | 15.0                   |                         |
| 100                               | 20.0                   |                         |
| 125                               | 25.0                   |                         |
| 220                               | 25                     | 5.5                     |
| 50                                | 11.0                   |                         |
| 75                                | 16.5                   |                         |
| 100                               | 22.0                   |                         |
| 125                               | 27.5                   |                         |

Fig. 1 Laser micro-spot welding process parameters

Table 3 Input variables for the laser micro-spot welding experiments

Fig. 2 a Sample arrangement, b sample assembly and spot positions, and c sectional view for the laser micro-spot welding of AISI 302 sheets

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663 μm and represented the minimum depth penetration required to avoid lack of penetration. The upper specification limit (USL) was set to 876 μm (CSL + 114 μm of excessive penetration) and it represented the maximum permitted penetration depth (Fig. 3d). Based on these specification limits, all the laser spot weld defects were visually inspected and evaluated to assure the manufacture Class B laser micro-spot welds.

### 2.4 Porous scaffold fabrication

The fixture designed for stacked experiments was modified. The top clamp consisted of a plate with holes of 3 mm in diameter. This configuration allowed the laser beam to pass through holes and perform the micro-spot welds without air gap defects. The proposed methodology was created to generate a porous structure manufactured by a new related sheet lamination process. The porous metallic scaffold was designed using NX 10 software (Siemens, USA) resulting in a theoretically calculated porosity of 47%. It was corroborated by measuring the relative density using Archimedes' principle, which resulted in an experimental porosity of around 46%. The base dimension of the designed scaffold was 10.3 mm × 10.3 mm with a height of 5.3 mm. It was composed of circular pores with a 2.54-mm diameter and 1 mm × 0.254 mm rectangular struts. According to the strut size, three metallic sheets of 254 μm of thickness were joined in an overlap joint configuration. A shape factor was defined as the penetration depth (h) divided by the spot width (w) to accomplish the spot weld dimension in the designed struts [31]. According to the scaffold design, the shape factor of the micro-spot weld must be between 1.0 (i.e., h ≥ 663 μm and w ≥ 620 μm, see Fig. 4c) and 1.4 to assure that the spot weld achieves full penetration based on the ISO 13919-1 [27]. An overview of the sheet lamination methodology used for the scaffold’s construction is illustrated in Fig. 4. Twenty-one square AISI 302 sheets (20 × 20 mm) with a 254 μm thickness were laser cut from an AISI 302 shims (Fig. 4a). A hole was pre-drilled at each cutting operation to enable a faster geometry detachment. Table 4 lists the process parameters of the laser micro-cutting and laser drilling operations. According to García-López et al. [32], these process parameters assure a pulse overlapping of over 50% which reduces considerably the surface roughness on the edge of the strut. All sheets were cleaned in an ultrasonic bath with isopropanol alcohol before the pieces were welded. Figure 4b illustrates the geometry shape and the internal patterns of the scaffold design. Three metallic sheets were stacked and aligned in a laid down orientation at 90°, 0°, and 90°, respectively (Fig. 4c). These sheets were joined with four laser spot welds. Figure 4d illustrates the position of these four laser micro-spot welds (p1–p4). The spot weld positions of the laser are alternated with the positions of the micro-spot welds (p5–p8) to avoid mechanical deformation in the sheets due to heat concentration (see Fig. 4e). After the laser micro-spot welding operations, a metallic preform was obtained. The frame was cut away using wire electrical discharge machining (WEDM). Figure 4f illustrates the porous metallic scaffold prototype manufactured.

![Figure 3](https://example.com/fig3.png)

**Fig. 3** Specification limits for a incomplete filled grooves and root cavities; b pore size and lack of penetration; c excessive weld metal and excessive penetration welding defects according to the ISO 13919-1; and d upper, central, and lower specification limits for spot weld profile
3 Mathematical model

3.1 Material’s properties

With rising temperature, density ($\rho$) is substantially constant, but electrical resistivity ($R(T)$), specific heat ($C_p(T)$), and thermal diffusivity ($\kappa(T)$) presented considerable variations over the temperature interval between ambient temperature ($T_0$) of 300 K and melting temperature ($T_m$) of 1693 K [33]. To deal with the temperature-dependent variations, average values for the thermal properties (i.e., electrical resistivity, thermal conductivity, and specific heat) were calculated [34]. Data regarding AISI 302 thermal properties (i.e., electrical resistivity, thermal conductivity, and specific heat) were collected from the Handbook of Stainless Steels [33]. Regression models were fitted to the data of the AISI 302 alloy and average values for each material property were estimated in the temperature interval from the ambient temperature ($T_0$) to the melting temperature ($T_m$) using Eqs. (1–3) [35]. The absorptance ($A$) of the materials was calculated using Eq. (4) proposed by He et al. [36] where $\lambda$ is the laser beam’s wavelength (i.e., 1074 nm for fiber laser) and $R_{AVG}$ is the average electrical resistivity aforementioned. Table 5 presents the calculated values of the average electrical resistivity ($R_{AVG}$), the average specific heat ($C_{pAVG}$), the average thermal diffusivity ($\kappa_{AVG}$), and the absorptance ($A$) for AISI 302 alloy. A density ($\rho$) of 8000 kg/m$^3$ and the latent heat of fusion ($h_f$) of 2.6 $\times$ 10$^5$ J/kg were used for the calculations [33, 37].

$$R_{AVG} = \int_{T_0}^{T_m} \frac{R(T)}{T_m-T_0} dT$$

$$C_{pAVG} = \int_{T_0}^{T_m} \frac{C_p(T)}{T_m-T_0} dT$$

$$\kappa_{AVG} = \int_{T_0}^{T_m} \frac{\kappa(T)}{T_m-T_0} dT$$

$$A = \lambda \times R_{AVG}$$

![Fig. 4](image_url) Graphical view of the proposed methodology for the manufacturing of metallic scaffolds: a laser micro-cutting of sheets, b internal geometry of AISI 302 sheets, c laid down pattern of three sheets, d intercalated positions for the laser micro-spot welds p1–p4, e alternated position for the laser micro-spot welds p5–p8, and f AISI 302 metallic scaffold

Table 4 Parameters used for laser drilling and laser micro-cutting operations

| Process parameters       | Laser drilling | Laser micro-cutting |
|--------------------------|----------------|---------------------|
| Average laser power ($P_{AVG}$) (W) | 180            | 170                 |
| Pulse frequency ($f$) (Hz) | 1500           | 1100                |
| Dwelling time ($t_D$) (ms) | 400            | –                   |
| Pulse width ($t_w$) ($\mu$s) | 160            | 218                 |
| Feed rate ($v$) (mm/min)    | –              | 200                 |
| Assist gas pressure ($P_{G1}$) (Psi) | 150            | 150                 |
\[ A = 0.365 \left( \frac{R_{\text{AVG}}}{\lambda} \right)^{1/2} - 0.0667 \left( \frac{R_{\text{AVG}}}{\lambda} \right)^{3/2} + 0.006 \left( \frac{R_{\text{AVG}}}{\lambda} \right)^{3/2} \]  

(4)

3.2 Process efficiency modeling

For laser micro-seam welding, the laser beam moves at a constant speed, while in the laser micro-spot welding process, the laser beam remains static which indicates a feed rate \(v\) equal to 0 mm/s. This model uses the final weld dimensions (i.e., penetration depth \(h\), top width \(w_T\), and bottom width \(w_B\)), the welding parameters (average laser power \(P_{\text{AVG}}\) and the exposure time \(t\)), and the thermophysical properties of the material (i.e., absorptance, average specific heat, latent fusion heat, and density) to estimate the process’ efficiency \(\eta_{\text{pro}}\). The process’ efficiency \(\eta_{\text{pro}}\) of the laser welding processes \([15, 35]\) is commonly split into two separate terms (Eq. (5)). To minimize the heat dissipation loss during the laser micro-spot welding process, the process’ efficiency \(\eta_{\text{pro}}\) should be maximized, which is of considerable interest in the fabrication of scaffolds.

\[ \eta_{\text{pro}} = \eta_{\text{C}} \eta_{\text{M}} \]  

(5)

where \(\eta_{\text{C}}\) is the coupling efficiency and \(\eta_{\text{M}}\) the melting efficiency.

3.2.1 The coupling efficiency

The coupling efficiency \(\eta_{\text{C}}\) is defined in terms of energy as the ratio between the heat input transferred \(Q_{\text{trans}}\) to the material and the total heat input \(Q_{\text{tot}}\) (see Eq. (6)) \([15, 35]\). The total heat input \(Q_{\text{tot}}\) is calculated with Eq. (7) where \(P_{\text{AVG}}\) is the average laser power in W and \(t\) is the exposure time in s. Additionally, the Gouffe-Dausinger model establishes a relationship between the coupling efficiency \(\eta_{\text{C}}\) and welding conditions using Eq. (8), where \(d_f\) is the laser spot diameter, \(h\) is the penetration depth, and \(A\) is the absorptance of the material previously calculated \([38]\).

\[ Q_{\text{tot}} = P_{\text{AVG}} t \]  

(7)

\[ \eta_{\text{C}} = \frac{Q_{\text{trans}}}{Q_{\text{tot}}} \]  

(6)

\[ \eta_{\text{C}} = A \frac{1 + (1-A) \left[ \frac{h}{2 d_f} - \left( \frac{h}{2 d_f} \right)^2 \right]}{A \left( 1 + \frac{h}{2 d_f} \right) + \frac{h}{2 d_f}} \]  

(8)

3.2.2 The melting efficiency

The melting efficiency \(\eta_{\text{M}}\) is defined by the ratio of the melting heat input \(Q_{\text{melt}}\) over the transferred heat input \(Q_{\text{trans}}\) (Eq. (9)). The melting heat input \(Q_{\text{melt}}\) (Eq. (10)) represents the amount of energy needed to heat up the material to its melting point and achieve the phase change \([39]\). Where \(V\) is the melted pool volume in \(m^3\), \(\rho\) is the density in \(kg/m^3\), \(C_{\text{AVG}}\) is the average specific heat in \(J/kg K\), \(T_m\) is the melting temperature \(K\), \(T_0\) is the ambient temperature in \(K\), and \(h_t\) is the latent heat of fusion in \(J/kg\). Melting efficiency \(\eta_{\text{M}}\) was calculated using Eq. (11) derived from the substitution of Eqs. (6), (7), and (10) in Eq. (9).

\[ \eta_{\text{M}} = \frac{Q_{\text{melt}}}{Q_{\text{trans}}} \]  

(9)

\[ Q_{\text{melt}} = V \rho \left( C_{\text{AVG}} (T_m - T_0) + h_t \right) \]  

(10)

\[ \eta_{\text{M}} = \frac{V \rho \left( C_{\text{AVG}} (T_m - T_0) + h_t \right)}{\eta_{\text{C}} P_{\text{AVG}} t} \]  

(11)

The micro-spot welds obtained in this study presented parabolic, rectangular, and trapezoidal cross-sectional shapes and from a top view, all the spots presented a circular cross-sectional shape. Considering these cross-sectional shapes, it was assumed that the spot welds presented revolution geometries (i.e., paraboloid, cylinder, and truncated cone). These revolution geometries are shown in Fig. 5. Therefore, the melted pool volume \(V\) was estimated with Eqs. (12–14), where the height of all shapes is equal to the penetration depth \(h\) and the top radius of the paraboloid, cylinder, and truncated cone is equal to half of the spot weld’s top width \(w_T\). The bottom radius of the truncated cone is equal to half of the spot weld’s bottom width \(w_B\). Equations (12–14) neglect the amount of material that is partially evaporated from the weld pool during the welding process \([37]\).

\[ V = \frac{1}{2} \pi \left( \frac{w_T}{2} \right)^2 h \]  

(12)

\[ V = \pi \left( \frac{w_T}{2} \right)^2 h \]  

(13)

| Table 5 | Results of calculations of the AISI 302 material’s properties |
|----------------------|----------------------|
| Electrical resistivity, \(R_{\text{AVG}}\) (\(\mu\Omega\) cm) | 9.98 |
| Average specific heat, \(C_{\text{AVG}}\) (J/kg K) | 544 |
| Average thermal diffusivity, \(\kappa_{\text{AVG}}\) (mm\(^2\)/s) | 4.35 |
| Absorptance, \(A\) | 0.32 |
\[
V = \frac{1}{3} \pi \left[ \left( \frac{w_f}{2} \right)^2 + \left( \frac{w_B}{2} \right)^2 + \left( \frac{w_f}{2} \right) \left( \frac{w_B}{2} \right) \right] h
\]  
(14)

### 3.3 Laser micro-spot welding modelling

For laser micro-seam welding, Dausinger et al. [40] proposed a model to estimate the required feed rate \(v\) to achieve a certain penetration depth \(h\) when the average laser power \(P_{AVG}\) and the laser spot diameter \(d_I\) are previously established. This model is based on Eq. (15), where factors \(\alpha_1\) and \(\alpha_2\) are process-dependent parameters, \(\kappa_{AVG}\) is the material’s thermal diffusivity in \(\text{mm}^2/\text{s}\), \(\eta_C\) is the coupling efficiency, and \(Hp\) is the material’s specific required melting heat in \(\text{J/mm}^3\) [16, 40]. The linear relationship presented in Eq. (15) had been used by Patschger et al. [37] to find the feed rate required for different materials (i.e., steel, nickel, aluminum, and titanium) for full penetration laser micro-seam welding. The specific required heat \(Hp\) can be calculated using Eq. (16), which is based on the material’s density \(\rho\), average specific heat \(C_{PAVG}\), latent heat of fusion \(h_f\), and melting temperature \(T_m\). A limitation of our study is the missed consideration of the temperature rise produced in the weld pool formation in Eqs. (10) and (16). Further research can be performed to include this term in our model using experimental method or numerical simulation. Experimental test to include this term is measuring the maximum temperature in the weld pool using thermocouples [41] or a thermographic camera [31]. Other methods implicate analytically calculating the temperature distribution on weld pool through numerical models and experimental validation [42, 43].

\[
v \approx \frac{\kappa_{AVG}}{d_I} + \frac{\eta_C}{Hp} \left( \frac{P_{AVG}}{h (d_I)} \right)
\]  
(15)

\[
Hp = \rho \left[ C_{PAVG}(T_m) + h_f \right]
\]  
(16)

The difference between the laser micro-seam and micro-spot welding affects mainly the way to calculate the pool volume melting rate \((\Delta V/\Delta t)\), which estimates the amount of volume that is melted per unit of time. In the laser micro-seam welding case, the pool volume melting rate \((\Delta V/\Delta t_{seam-w})\) is calculated using Eq. (17) [39], where \(A\) is the cross-sectional area of the micro-seam weld in \(\text{mm}^2\) and \(v\) is the feed rate in \(\text{mm/s}\). For the laser micro-spot welding, the pool volume melting rate \((\Delta V/\Delta t_{spot-w})\) can be calculated using Eq. (18), where \(V\) is the melted pool volume in \(\text{mm}^3\) (i.e., it is estimated with Eqs. (12–14) according to the spot weld shape) and \(t\) is the exposure time in \(s\).

\[
\frac{\Delta V}{\Delta t_{seam-w}} = v a
\]  
(17)

\[
\frac{\Delta V}{\Delta t_{spot-w}} = \frac{V}{t}
\]  
(18)

Equation (17) is solved for the feed rate \(v\) and substituted in Eq. (15) to obtain Eq. (19) that can be used in both laser micro-welding processes. The pool volume melting rate \((\Delta V/\Delta t_{spot-w})\) of Eq. (18) is substituted in Eq. (19) to obtain Eq. (20), which can be used in the laser micro-spot welding to calculate the required exposure time \(t\) to achieve the defined penetration depth \(h\), when the average laser power \(P_{AVG}\) and the laser spot diameter \(d_I\) have been previously determined.

\[
1 \left( \frac{\Delta V}{\Delta t_{spot-w}} \right) = \frac{\alpha_1}{\Phi_f} + \frac{\alpha_2}{\eta_C} \left( \frac{P_{AVG}}{h (d_I)} \right)
\]  
(19)

\[
\frac{d_I}{a} \left( \frac{V}{t} \right) = \frac{\alpha_1}{\Phi_f} + \frac{\alpha_2}{\eta_C} \left( \frac{P_{AVG}}{h} \right)
\]  
(20)

### 4 Results and discussion

#### 4.1 Process parameter validation with stacks

Figure 6 illustrates a graphical representation of heat energy dissipation of the different regimes of the laser micro-welding process. According to Simonds et al. [41], shallow and broad
cross-sections (Fig. 6a) occurred in a conduction regime. Intermediate cross-sectional shapes that share features of conduction and keyhole are classified as a transition regime (Fig. 6b). Also, Simonds observed that fluted cross-sections (Fig. 6c) are derived from a closed keyhole weld regime. Additionally, Krasnosperov et al. [45] explained that the larger rectangular cross-section (Fig. 6c) resulted from a closed keyhole weld pool while the trapezoidal cross-section arose from an open keyhole regime (see Fig. 6d).

Figure 7 shows the laser micro-spot welds obtained with the experimental parameters mentioned in Table 3. At the top left corner of each metallography is the geometrical shape of the cross-section of the weld. The vertical axis displays the average laser power ($P_{AVG}$) and the horizontal axis presents the exposure time ($t$) used for the fabrication of the micro-spot weld. Micro-spot welds fabricated with 220 W of average laser power ($P_{AVG}$) presented two shape transitions. A cross-section shape transition occurred from 50 to 75 ms (Fig. 7(b, c)) where the weld shape changed from a rectangle to a trapezoid. Besides, a second cross-section shape transition was observed from 100 to 125 ms (Fig. 7(d, e)) where the trapezoidal shape was inverted. When an average laser power of 200 W and exposure times ($t$) of 25 ms and 50 ms are used, the micro-spot welds showed rectangular cross-sections (Fig. 7(f, g)), while micro-spot welds with 75 ms, 100 ms, and 125 ms showed a trapezoidal shape (Fig. 7(i, j)). Laser micro-spot welds produced with 180 W of average laser power ($P_{AVG}$) presented a shape change from semi-circular cross-section at 25 ms (Fig. 7(k)) to a parabolic cross-section in 50, 75, 100, and 125 ms (Fig. 7(l–o)).

Only samples performed with 180 W and 25 ms (Fig. 7(k)) were identified as conduction regime with a semi-circular cross-section. Additionally, we observed that samples fabricated with heat input of 18 J, 22.5 J (Fig. 7(n, o)), 10 J (Fig. 7(g)), and 11 J (Fig. 7(b)) presented a closed keyhole with rectangular and parabolic cross-sectional shapes. Additionally, samples with open keyhole were identified in Fig. 7(c–e, h–j), which have a trapezoidal cross-section. In micro-seam welding with bead on plate configuration, the laser beam energy is not uniformly transferred along the z-direction and more energy is dissipated in the bottom region of the weld pool, which resulted in a trapezoidal cross-section causing a keyhole regimen [44].

Cedeño-Viveros et al. [14] presented micro-spot welds with semi-circular and parabolic cross-sectional shapes using a calculated intensity ($I$) between 1.8 and 2.0 kW/mm². In our study, the calculated intensity ($I$) was between 6.2 and 7.5 kW/mm², which caused semi-circular, parabolic, cylindrical, and trapezoidal cross-sectional welds. According to Ventrella et al. [25], air gaps in laser welding in overlap configuration act as barrier for heat transfer causing most of the laser beam heat input ($Q_{in}$) to be consumed on the side exposed to the laser beam. In our experiments, we observed air gaps (~24–34 μm) located between the second and third sheets (Fig. 7(a, g, h, k, m, n)). We attribute these defects to our fixture design; therefore, a new experimental setup was implemented to avoid air gaps in scaffold design.

Weld defects are showed with a red “x” at the bottom of each metallography in Fig. 7 and the respective nomenclature of the welding defects can be found in Fig. 3a–c. There were no cracks in any of the micro-spot weld samples. This indicates that no hot cracking effects due to stress generation were presented during the heat cycles (i.e., fusion and solidification) [45] and the AISI 302 sheets were properly clamped among sheets.

None of the laser micro-spot welds presented excessive penetration, melt down material, nor excess of weld metal defects. However, almost 50% of the samples showed a pore in the center of the fusion zone with an average size of 200 ± 11 μm (see Fig. 7(b–e, h–j, n)). The central pore defect was observed mainly in samples with rectangular and trapezoidal cross-sections, which indicated the tendency of pore formation in the keyhole welding. According to Sun et al. [11], pores are formed in laser seam welds due to an unstable keyhole formation. Krasnosperov et al. [44] indicated that the closed keyhole weld pool stability range is limited and the keyhole transition from closed to open causes changes in the flow of the weld pool. Furthermore, incompletely filled grooves and root cavity defects were found in samples with trapezoidal cross-sections (Fig. 7(e–i, j)). A spattering effect was produced in the center of the fusion zone (Fig. 7(b–e, h–j)), which led to high contractions at the top and bottom of the
weld pool [46]. Based on our experimental results, it is recommended to remain in the conduction regime or a closed keyhole weld pool to assure weld quality of the final micro-spot weld and to avoid the formation of pores, incompletely filled grooves, and root cavity defects which may compromise the mechanical strength and integrity of the micro-spot welds. According to the geometrical limits established in Fig. 3d, a range of samples with full penetration are highlighted in Fig. 7(b–e, h–j, n, o). These samples correspond to heat inputs ($Q_{in}$) between 11 and 27.5 J. According to Khan et al., higher values of heat input increase the surface energy density ($E_D$) irradiated on the material, which enhanced the transfer of energy in the $z$-direction [47].

Figure 8 illustrates the results for the measured penetration depth ($h$) against the exposure time ($t$). Power models were fit and coefficients of determination ($R^2$) of 0.98, 0.97, and 0.99 for 180 W, 200 W, and 220 W, respectively. The specification limits (i.e., LSL, USL, CSL) are illustrated in Fig. 8 as a geometrical constraint.

Figure 9a–c presents the measurements for the top width ($w_T$), middle width ($w_M$), and bottom width ($w_B$) of the spot welds produced with 180 W, 200 W, and 220 W, respectively. Our results show an increase of the bottom width ($w_B$) compared with the top width ($w_T$) when exposure time is increased. This tendency is observed using an average laser power of 200 W and 220 W, which corresponds to the transition from the closed to an open keyhole weld pool and indicates the formation of a trapezoidal shape (Fig. 9b, c).
case of samples produced with 180 W of average laser power (Fig. 9a), a top width \((w_T)\) value is presented higher than bottom width \((w_B)\) which corresponds to the transition of conduction regimen to close keyhole. According to Krasnosperov et al. [44], when the keyhole regime is established, there is an inherent non-uniformity caused by heat transference. In our experiments, it is observed as a change in widths reported in Fig. 9 (i.e., from 100 to 125 ms, Fig. 9c) which resulted asymmetric (see Fig. 7(b, c–e)). HAZ width \((b_{HAZ})\) is presented in Fig. 9d, and a tendency was observed: when average laser power increased, HAZ increased. According to Ventrella et al. [25], an increase in the HAZ width \((b_{HAZ})\) demonstrates a higher amount of energy dissipated in the material. The micro-spot welds obtained in this study presented heat-affected zone width \((b_{HAZ})\) between 6 and 16 \(\mu\)m. These values are lower than the results of 25 to 50 \(\mu\)m reported by Ventrella et al. [25] in the laser micro-seam welding of stainless steel. Our HAZ results are compared in range with the results reported by Siva Shanmugam et al. [13] in laser micro-spot welds of AISI 304.

The results obtained for the shape factor \((h/w_T)\) are presented in Fig. 10. This factor was considered for the scaffold design. Although top width and penetration depth were measured for all samples, Fig. 10 shows the results where full penetration of the three sheets were obtained. Our results indicate that samples that produced a heat input of 11 J \((P_{AVG} = 220 W, t = 50 ms)\), 18 J \((P_{AVG} = 180 W, t = 100 ms)\), and 22.5 J \((P_{AVG} = 180 W, t = 125 ms)\) allowed it to maintain the shape factor constraint.

### 4.2 Process efficiency modelling

The computed efficiencies (i.e., coupling efficiency \((\eta_C)\), melting efficiency \((\eta_M)\), process efficiency \((\eta_{pro})\)) were calculated using Eqs. (5), (8), and (11). The results are displayed in Fig. 11. Micro-spot welds that accomplish full penetration depth \((h)\) (i.e., 663 to 876 \(\mu\)m) presented values for the coupling efficiency \((\eta_C)\) 85–86% (11.0–27.5 J) which resulted higher in comparison to the samples that presented incomplete penetration (see Fig. 11a). Simonds et al. [41] measured the coupling efficiency by calorimetry using thermocouples and an optical sphere in micro-spot welds of AISI 316L sheets of 2 mm of thickness. They obtained results for the coupling efficiency between 80 and 90% for a heat input range of 4.6–6.3 J. These results are close in range to the coupling efficiency \((\eta_C)\) calculated in this study for the experimental trials. Hipp et al. [15] accurately measured the melting efficiency for the plasma arc, laser, and hybrid laser (i.e., laser-assisted plasma arc) welding processes in AISI 304 sheets of 1 mm of thickness using a thermographic camera. The results

![Fig. 9](image-url)  
**Fig. 9** Results for the measurements of top width \((w_T)\), middle width \((w_M)\), and bottom width \((w_B)\) for a 180 W, b 200 W, and c 220 W of average laser power \((P_{AVG})\) and d measured HAZ width \((b_{HAZ})\)
were 22.1%, 11.5%, and 35.6%, for the plasma arc, laser, and hybrid laser, respectively. In this study, the spot welds fabricated with 180 W presented a melting efficiency between 7 and 12% (Fig. 11b) which are close in range with the values reported by Hipp et al. [15] for the laser welding process. Samples performed with 200 W and 220 W showed melting efficiencies between 22 and 38% (Fig. 11b). These results indicated that laser micro-spot welding can achieve similar values for melting efficiency than plasma arc and hybrid laser welding. Additionally, the process’ efficiency for the spot welds between 5 and 10% for 180 W and between 20 and 30% for 200–220 W (Fig. 11c).

4.3 Model validation and fabrication of the porous scaffold

Samples reported in Fig. 7 do not fulfill with all Class B quality requirements in the range of full penetration, due to the presence of a macro-central pore in the weld which would compromise the mechanical integrity of the weld. However, we observed that samples near full penetration do not present the macro-pore inside the weld (Fig. 7(a, f, k, l)); therefore, we performed a new set of experiments based on previous process parameters. Samples produced with 220 W and 50 ms (i.e., a heat input of 11 J) had full penetration, and HAZ width of 12 μm had a process efficiency of 27% and a penetration depth/top width ratio value of 1.04 that complies with the required value of 1.0 mentioned above, although it has the presence of the central pore. Additionally, samples produced with 220 W and 25 ms showed lack of penetration. Our mathematical model was used to determine the required exposure time (t) using Eq. (20) (i.e., Dausinger’s adapted model for laser micro-spot welding). Through the obtained data from the experiments performed in the AISI 302 sheets and Eqs. (21) and (22), the values of x and y were calculated and displayed in Fig. 12. Then, the samples that achieved full penetration were selected. A linear model was fit to the data obtained with a coefficient of determination of 0.917 (see Fig. 12). Finally, using the results of the material properties for the AISI 302 alloy from Table 5 (Eqs. (23) and (24)), the factors α₁ and α₂ can be calculated for laser micro-spot welding. The results obtained were −1.13 and 0.24 for α₁ and α₂ respectively. Our study indicated that the adapted Dausinger’s
A mathematical model can be used for the laser micro-spot welding to find the exposure time required in the range of full penetration.

\[
y = \frac{d_f}{a} \left( \frac{V}{t} \right)
\]

(21)

\[
x = \frac{\eta C P_{\text{AVG}}}{h}
\]

(22)

\[
a = \frac{\alpha_2}{H_p}
\]

(23)

\[
b = \alpha_1 \kappa_{\text{AVG}}
\]

(24)

The average thermal diffusivity (\(\kappa_{\text{AVG}}\)) and the specific required heat (\(H_p\)) (Table 5) were used in Eq. (20) to calculate the required exposure time (\(t\)) to avoid the central pore inside the weld (see Fig. 7(b, h, n)). The results obtained for \(\alpha_1\) and \(\alpha_2\) of the keyhole welding regime (i.e., 200 to 220 W) and a cylindrical weld volume were considered to calculate the cross-sectional area (\(a\)) and the melted volume (\(V\)). For calculations, laser spot diameters (\(d_f\)) were maintained at 193 \(\mu\)m, while an average penetration depth (\(h\)) was set at 774 \(\mu\)m and top width (\(w_T\)) at 756 \(\mu\)m. According to the conceptual design, the penetration depth to top width ratio (\(d/w_T\)) must be greater than 1.0. After applying the proposed model, the exposure time (\(t\)) calculated resulted in 45 ms and 65 ms for 220 W and 200 W, respectively. Metallographic images were obtained to illustrate the cylindrical weld shape (see Fig. 13). Additionally, full penetration and the absence of internal pores were observed. Micro-spot weld produced with 200 W and 65 ms (Fig. 13a) presented a cross-sectional area greater than the weld fabricated with 220 W and 45 ms (Fig. 13b). This change in the cross-sectional area is caused by the difference in the total heat input (\(Q_{\text{in}}\)) used to perform the welds. Our results indicate that the micro-spot weld presented an average penetration depth (\(h\)) of 814 \(\mu\)m, which represents a
percentage error of around 4.9% from the estimated value of 774 μm. This result demonstrates an approximation to calculate exposure time and micro-spot welds with a cylindrical shape achieving a penetration depth to top width (h/w) ratio designed in a keyhole welding regime with a closed keyhole weld pool. Furthermore, in comparison to the samples produced with 200 W and 45 ms, the process efficiency (ηpro) was improved from 27 to 53% and the HAZ width (bHAZ) was reduced from 12 to 8 μm.

Figure 14a displays the final prototype fabricated with the selected parameters (P_{AVG} = 220, t = 45 ms). Figure 14b presents the cross-sectional view of the micro-spot welds. Figure 14a shows the micro-spot welds that correspond to the p1–p4 positions (Fig. 4d). These micro-spot welds are intercalated with the welds of the p5–p8 positions to fully join the scaffold (see Fig. 4e). Figure 14b displays the metallography of the micro-spot welds positioned in p4 and p8 (see Fig. 4d). The cross-sectional shapes of scaffold resulted in a rectangular cross-section which corresponds to the conduction welding regime. The micro-spot welds presented pores and shrinkage defects.

Pores and shrinkage (see Fig. 13) defects were not present in the three stacked experiments after using the welding parameters obtained with the proposed model. We suggest that these defects are the result of stacking more sheets. One proposal is to include in the model the heat losses caused by conduction of the sheet stacking. Further experiments can be performed to evaluate the effect of sheet number on scaffold’s quality defects. Additionally, Harooni et al. [48] used the sheets preheating before welding process as a method to avoid these defects. Future work is oriented to analyze micro-hardness and compression tests to evaluate the mechanical properties of scaffold.

5 Conclusions

The laser micro-spot welding process was studied and successfully implemented in a sheet lamination-based methodology to fabricate austenitic stainless steel scaffolds. The conclusions can be summarized as follows:

- The results for the computed coupling, melting, and process efficiency are closed in range with values experimentally measured and reported in the literature. These results prove the accuracy and the reliability of the used Eqs. (5), (8), and (11) to estimate the process efficiencies of the laser micro-spot welding process. Furthermore, the computed process efficiencies indicated that laser micro-spot welds should be produced with 200 W or 220 W to obtain the highest efficiency level.
- Dausinger’s mathematical model was successfully adapted to the laser micro-spot welding. The adapted model helped determine the required exposure time to produce micro-spot welds according to the scaffold’s conceptual design and free of welding defects.
- Based on the adapted Dausinger’s model, spot welds produced with 220 W and 45 ms presented a 5% error different from predicted. Besides, no defects were found and the spot welds achieved the Class B level according to the ISO 13919-1.
- A porous scaffold prototype was fabricated according to the conceptual design and using the process parameters selected with the help of the adapted mathematical model. This indicated the promising future of the methodology proposed to fabricate porous metallic scaffolds for bone tissue engineering applications through sheet lamination-based on micro-laser cutting and welding.

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Author contribution Not applicable.

Data availability The datasets generated and analyzed during the current study are available from the corresponding author on reasonable request.

Code availability Not applicable.

Declarations

Ethics approval Not applicable.

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Consent for publication Not applicable.

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