Tight Bounds on Subexponential Time Approximation of Set Cover and Related Problems

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Abstract
We show that Set-Cover on instances with $N$ elements cannot be approximated within $(1 - \gamma) \ln N$-factor in time $\exp(N^{\gamma - \delta})$, for any $0 < \gamma < 1$ and any $\delta > 0$, assuming the Exponential Time Hypothesis. This essentially matches the best upper bound known by Cygan et al. \cite{CyganCDK16} of $(1 - \gamma) \ln N$-factor in time $\exp(O(N^{\gamma}))$.

The lower bound is obtained by extracting a standalone reduction from Label-Cover to Set-Cover from the work of Moshkovitz \cite{Moshkovitz09}, and applying it to a different PCP theorem than done there. We also obtain a tighter lower bound when conditioning on the Projection Games Conjecture.

We also treat three problems (Directed Steiner Tree, Submodular Cover, and Connected Polymatroid) that strictly generalize Set-Cover. We give a $(1 - \gamma) \ln N$-approximation algorithm for these problems that runs in $\exp(O(N^{\gamma}))$ time, for any $1/2 \leq \gamma < 1$.

1 Introduction
We show that Set-Cover on instances with $N$ elements cannot be approximated within $(1 - \gamma) \ln N$-factor in time $\exp(N^{\gamma - \delta})$, assuming the Exponential Time Hypothesis (ETH), for any $\gamma, \delta > 0$. This essentially matches the best upper bound known by Cygan et al. \cite{CyganCDK16}. This is obtained by extracting a standalone reduction from Label-Cover to Set-Cover from the work of Moshkovitz \cite{Moshkovitz09}, and applying it to a different PCP theorem than done there. We also obtain a tighter lower bound when conditioning on the Projection Games Conjecture.

We also treat the Directed Steiner Tree (DST) problem that strictly generalizes Set-Cover. The input to DST consists of a directed graph $G$ with costs on edges, a set of terminals, and a designated root $r$. The goal is to find a subgraph of $G$ that forms an arborescence rooted at $r$ containing all the $N$ terminals and minimizing the cost. We give a
(1 − γ) ln N-approximation algorithm for DST that runs in \( \exp(\tilde{O}(N^\gamma)) \) time, for any \( \gamma \geq 1/2 \). Recall that the \( \tilde{O} \)-notation hides logarithmic factors.

This algorithm also applies to two other generalizations of SET-COVER. In the SUBMODULAR COVER problem, the input is a set system \((U, \mathcal{C})\) with a cost on each element of the universe \( U \). We are given a non-decreasing submodular function \( f : 2^U \rightarrow \mathbb{R} \) satisfying, for every \( S \subseteq T \subseteq V \) and for every \( x \in U \setminus T \), \( f(S + x) - f(S) \geq f(T + x) - f(T) \). The objective is to minimize the cost \( c(S) = \sum_{s \in S} c(s) \) subject to \( f(S) = f(U) \). In the CONNECTED POLYMATROID problem, which generalizes SUBMODULAR COVER, the elements of \( U \) are leaves of a tree and both elements and sets have cost. The goal is to select a set \( S \subseteq U \) so that \( f(S) = f(U) \) and \( c(S) + c(T(S)) \) is minimized, where \( T(S) \) is the unique tree rooted at \( r \) spanning \( S \).

1.1 Related work

Johnson \cite{johnson1974approximation} and Lovász \cite{lovasz1975tight} showed that a greedy algorithm yields a 1 + \( \lg N \)-approximation of SET-COVER, where \( N \) is the number of elements. Chvátal \cite{cvatalsubmodular} extended it to the weighted version. Slavík \cite{slavik1999tight} refined the bound to \( \ln n - \ln \ln n + O(1) \).

Lund and Yannakakis \cite{lund1994hardness} showed that logarithmic factor was essentially best possible for polynomial-time algorithms, unless \( NP \subseteq \text{DTIME}(n^{\log \log n}) \). Feige \cite{feigehardness} gave the precise lower bound that SET-COVER admits no \((1 - \epsilon)\)-approximation, for any \( \epsilon > 0 \), with a similar complexity assumption. Assuming the stronger ETH, he shows that \( \ln N - c \log \log N \)-approximation is not possible for polynomial algorithms, for some \( c > 0 \). The work of Moshkovitz \cite{moshkovitz2020approximation} and Dinur and Steurer \cite{dinur2011approximation} combined shows that \((1 - \epsilon)\ln N\)-approximation is hard modulo \( P = NP \). All the inapproximability results relate to two prover interactive proofs, via the related LABEL-COVER problem.

Recent years have seen increased interest in subexponential time algorithms, including approximation algorithms. A case in point is the maximum clique problem that has a trivial \( 2^{n/\alpha} \text{poly}(n) \)-time algorithm that gives a \( \alpha \)-approximation, for any \( 1 \leq \alpha \leq \sqrt{n} \), and Bansal et al. \cite{bansalline} improved the time to \( \exp(n/\Omega(\alpha \log^2 \alpha)) \). Chalermsook et al. \cite{chalermsookapproximation} showed that this is nearly tight, as \((1 - \epsilon)\)-approximation requires \( \exp(n^{1-\epsilon}/\alpha^{1+\epsilon}) \) time, for any \( \epsilon > 0 \), assuming ETH.

For SET-COVER, Cygan, Kowalik and Wykurz \cite{cygan2016improved} gave a \((1 - \alpha)\ln N\)-approximation algorithm that runs in time \( 2^{O(N^{\alpha})} \), for any \( 0 < \alpha < 1 \). The results of \cite{bansalline} \cite{chalermsookapproximation} imply a \( \exp(N^{\alpha/c}) \)-time lower bound for \((1 - \alpha)\ln N\)-approximation, for some constant \( c > 3 \). An unpublished report contains a conditional \( \exp(\Omega(N^\alpha)) \)-time lower bound for \((1 - \alpha)\ln N\)-approximation of SET-COVER \cite{bansalline}. In addition to ETH, this also requires the less established Projection Games Conjecture (PGC). Unfortunately, the writeup of \cite{bansalline} defies easy verification. The current paper arose from an effort to make it comprehensible.

DST can be approximated within \( N^\epsilon \)-factor, for any \( \epsilon > 0 \), in polynomial time \cite{bansalline} \cite{cygan2016improved}. In quasi-polynomial time, it can be approximated within \( O(\log^2 N / \log \log N) \)-factor \cite{cygan2017approximation}, which is also best possible in that regime \cite{bansalline} \cite{cygan2017approximation}. This was recently extended to CONNECTED POLYMATROID \cite{bansalline}. For SUBMODULAR COVER, the greedy algorithm also achieves a \( 1 + \ln N \)-approximation \cite{bansalline}.

1.2 Organization

The paper is organized so as to be accessible at different levels of detail. In Sec. \ref{sec:org}, we derive two different hardness results for subexponential time algorithms under different complexity assumptions: ETH and PGC. For this purpose, we only state (but not prove) the hardness
reduction, and introduce the Label-Cover problem with its key parameters: size, alphabet size, and degrees.

We prove the properties of the hardness reduction in Sec. 2.2, by combining two lemmas extracted from [19]. The proofs of these lemmas are given in Sec. 3.1 and 3.2. To make it easy for the reader to spot the differences with the arguments of [19], we underline the changed conditions or parameters in our presentation.

Finally, the approximation algorithm for Directed Steiner Tree is given in Sec. 4.

2 Hardness of Set Cover

We give our technical results in this section. Starting with definition of Label-Cover in Sec. 2.1, we give a reduction from Label-Cover to Set-Cover in Sec. 2.2, and derive specific approximation hardness results in Sec. 2.3. A full proof of the correctness of the reduction is given in the following section.

2.1 Label Cover

The intermediate problem in all known approximation hardness reductions for Set-Cover is the Label-Cover problem.

> Definition 2.1. In the Label-Cover problem with the projection property (a.k.a., the Projection Game), we are given a bipartite graph $G(A, B, E)$, finite alphabets (also called labels) $\Sigma_A$ and $\Sigma_B$, and a function $\pi_e : \Sigma_A \to \Sigma_B$ for each edge $e \in E$. A labeling is a pair $\varphi_A : A \to \Sigma_A$ and $\varphi_B : B \to \Sigma_B$ of assignments of labels to the vertices of $A$ and $B$, respectively. An edge $e = (a, b)$ is covered (or satisfied) by $(\varphi_A, \varphi_B)$ if $\pi_e(\varphi_A(a)) = \varphi_B(b)$. The goal in Label-Cover is to find a labeling $(\varphi_A, \varphi_B)$ that covers as many edges as possible.

The size of a label cover instance $G = (G = (A, B, E), \Sigma_A, \Sigma_B, \Pi = \{\pi_e\}_e)$ is denoted by $n_G = |A| + |B| + |E|$. The alphabet size is max$(|\Sigma_A|, |\Sigma_B|)$. The Label-Cover instances we deal with will be bi-regular, meaning that all nodes of the same bipartition have the same degree. We refer to the degree of nodes in $A$ (or $B$) as the A-degree (or B-degree), respectively.

Label-Cover is a central problem in computational complexity, corresponding to projection PCPs, or probabilistically checkable proofs that make 2 queries. A key parameter is the soundness error:

> Definition 2.2. A Label-Cover construction $G = G_\phi$, formed from a 3-SAT formula $\phi$, has soundness error $\epsilon$ if: a) whenever $\phi$ is satisfiable, there is a labeling of $G$ that covers all edges, and b) when $\phi$ is unsatisfiable, every labeling of $G$ covers at most an $\epsilon$-fraction of the edges.

We use the following PCP theorem of Moshkovitz and Raz [20].

> Theorem 2.3 ([20]). For every $\epsilon \geq 1/\text{polylog}(n)$, SAT on input of size $n$ can be reduced to Label-Cover on a bi-regular graph of degrees $\text{poly}(1/\epsilon)$, with soundness error $\epsilon$, size $n^{1+o(1)}\text{poly}(1/\epsilon) = n^{1+o(1)}$, and alphabet size that is exponential in $\text{poly}(1/\epsilon)$. The reduction can be computed in time linear in the size and alphabet size of the Label-Cover.

Dinur and Steurer [8] later gave a PCP construction whose alphabet size depends only polynomially on $1/\epsilon$. This is crucial for NP-hardness results, and combined with the reduction
of [19], implies the essentially tight bound of \((1 - \epsilon)\ln N\)-approximation of \textsc{Set-Cover} by poly-time algorithms.

### 2.2 Set Cover Reduction

We present here a reduction from a generic \textsc{Label-Cover} (a two-prover PCP theorem) to the \textsc{Set-Cover} problem. This is extracted from the work of Moshkovitz [19]. The presentation in [19] was tightly linked with the PCP construction of Dinur and Steurer [8] that was used in order to stay within polynomial time. When allowing superpolynomial time, it turns out to be more frugal to apply the older PCP construction of Moshkovitz and Raz [20]. This construction has exponential dependence on the alphabet size, which precludes its use in NP-hardness results. On the other hand, it has nearly-linear dependence on the size of the \textsc{Label Cover}, unlike Dinur-Steurer, and this becomes a dominating factor in subexponential reductions.

Our main technical contribution is then to provide a standalone reduction from \textsc{Label-Cover} to \textsc{Set-Cover} that allows specific PCP theorems to be plugged in.

We say that a reduction that originates in \textsc{Sat} achieves approximation gap \(\rho\) if there is a value \(a\) such that \textsc{Set-Cover} instances originating in satisfiable formulas have a set cover of size at most \(a\), while instances originating in unsatisfiable formulas have all set covers of size greater than \(\rho \cdot a\).

\begin{theorem}
Let \(\gamma > 0\) and \(0 < \delta < \gamma\). There is a reduction from \textsc{Label-Cover} to \textsc{Set-Cover} with the following properties. Let \(G\) be a bi-regular \textsc{Label-Cover} of almost-linear size \(n_0\), soundness error parameter \(\epsilon\), \(B\)-degree \(\text{poly}(1/\epsilon)\), and alphabet size \(\sigma_A(\epsilon)\).

Then for each \(\gamma > 0\), \(G\) is reduced to a \textsc{Set-Cover} instance \(SC = SC_G, \gamma, \delta\) with approximation gap \((1 - \gamma)\ln N\), \(N = \tilde{O}(n_0^{1/(\gamma - \delta)})\) elements, and \(M = \tilde{O}(n_0) \cdot \sigma_A(\text{polylog}(n))\) sets. The time of the reduction is linear in the size of \(SC\).
\end{theorem}

### 2.3 Approximation Hardness Results

When it comes to hardness results for subexponential time algorithms the standard assumption is the \textit{Exponential Time Hypothesis (ETH)}. ETH asserts that the 3-Sat problem on \(n\) variables and \(m\) clauses cannot be solved in \(2^{o(n)}\)-time. Impagliazzo, Paturi and Zane [14] showed that any 3-Sat instance can be sparsified in \(2^{o(n)}\)-time to an instance with \(m = O(n)\) clauses. When we refer to \textsc{Sat} input of size \(n\), we mean 3-CNF formula on \(n\) variables and \(O(n)\) clauses. Thus, ETH together with the sparsification lemma [2] implies the following:

\begin{conjecture} \textit{(ETH)} There is no \(2^{o(n)}\)-time algorithm that decides \textsc{Sat} on inputs of size \(n\).
\end{conjecture}

We need only a weaker version: There is some \(\zeta > 0\) such that there is no \(\exp(n^{1-\zeta})\)-time algorithm to decide \textsc{Sat}.

We are now ready for our main result.

\begin{theorem}
Let \(0 < \gamma < 1\) and \(0 < \delta < \gamma\). Assuming ETH, there is no \((1 - \gamma)\ln N\)-approximation algorithm of \textsc{Set-Cover} with \(N\) elements and \(M\) sets that runs in time \(\exp(N^{\gamma - \delta}) \cdot \text{poly}(M)\).
\end{theorem}

\begin{proof}
We show how such an algorithm can be used to decide \textsc{Sat} in subexponential time, contradicting ETH. Given a \textsc{Sat} instance of size \(n\), apply Thm. [2.3] with \(\epsilon = \Theta(1/\log^2 n)\), to obtain \textsc{Label-Cover} instance \(G\) of size \(n_0 = n^{1+o(1)}\) and alphabet size
\end{proof}
\[ \sigma_A(\epsilon) = \text{exp}(\text{poly}(1/\epsilon)) = \text{exp}(\text{polylog}(n)). \]

Next apply Thm. 2.4 to obtain a Set-Cover instance \( \mathcal{SC} = \mathcal{SC}_G \) with \( M = \tilde{O}(n^\epsilon) \sigma_A(\text{polylog}(n)) = \text{exp}(\text{polylog}(n)) \) sets and \( N = \tilde{O}(n^{1/\gamma+o(1)}) = n^{1/\gamma+o(1)} \) elements, and approximation gap \((1 - \gamma) \ln N\).

Suppose there is a \((1 - \gamma) \ln N\)-approximation algorithm of Set-Cover running in time \( \text{exp}(N^{\gamma-\delta}) \cdot \text{poly}(M) \). Since it achieves this approximation, it can decide the satisfiability of \( \phi \). Since \( N^{\gamma-\delta} = n^{(1/\gamma+o(1))(\gamma-\delta)} \leq n^{1-\delta'} \), for some \( \delta' > 0 \), the running time contradicts ETH.

Note: We could also allow the algorithm greater than polynomial complexity in terms of \( M \) without changing the implication. In fact, the complexity can be as high as \( \text{exp}(M^\delta) \), for some small constant \( \delta_0 \).

### 2.3.1 Still Tighter Bound Under Stronger Assumptions

Moshkovitz [19] proposed a conjecture on the parameters of possible Label Cover constructions. We require a particular version with almost linear size and low degree.

#### Definition 2.7 (The Projection Games Conjecture (PGC))

3-SAT of inputs of size \( n \) can be reduced to Label-Cover of size \( n^{1+o(1)} \), alphabet size poly\((1/\epsilon)\), and bi-regular degrees poly\((1/\epsilon)\), where \( \epsilon \) is the soundness error parameter.

The key difference of PGC from known PCP theorems is the alphabet size. PGC is considered quite plausible and has been used to prove conditional hardness results for a number of problems [19, 21].

By assuming PGC, we improve the dependence on \( M \), the number of sets.

#### Theorem 2.8

Let \( 0 < \gamma < 1 \) and \( 0 < \delta < \gamma \). Assuming PGC and ETH, there is no \((1 - \gamma) \ln N\)-approximation, nor a \( O(\log M) \)-approximation, of Set-Cover with \( N \) elements and \( M \) sets that runs in time \( \text{exp}(N^{\gamma-\delta}M^{1-\delta}) \).

Namely, both the approximation factor and the time complexity can depend more strongly on the number of sets in the Set-Cover instance. The only result known in terms of \( M \) is a folklore \( (M\ln M) \)-approximation in polynomial time.

**Proof.** We can proceed in the same way as in the proof of Thm. 2.6 but starting from the conjectured Label-Cover given by PGC, in which the alphabet size is polynomial in \( \epsilon \). We then set a cover instance \( \mathcal{SC}_G \) that differs only in that we now have \( M = |A|\Sigma_A| = n^{1+o(1)} = N^{\gamma+o(1)} \). So, a \( c \log M \)-approximation, with constant \( c > 0 \), implies a \( c\gamma \ln N \)-approximation, which is smaller than \((1 - \gamma) \ln N\)-approximation when \( c\gamma < (1 - \gamma) \) or \( \gamma < 1/(2c) \). Also, \( \text{exp}(M^{1-\delta}) = \text{exp}(n^{1-\delta'}) \), for some \( \delta' > 0 \), and hence such a running time again breaks ETH.

### 3 Proof of the Set Cover Reduction

We extract here a sequence of two reductions from the work of Moshkovitz. By untangling them from the Label-Cover construction, we can use them for our standalone Set-Cover reduction.

Moshkovitz [19] chooses some of the parameters of the lemmas so as to fit the purpose of proving NP-hardness of approximation. As a result, the size of the intermediate Label-Cover instance generated grows to be a polynomial of degree larger than 1. This leads to weaker hardness results for sub-exponential time algorithms than what we desire. We
indicate therefore how we can separate a key parameter to maintain nearly-linear size label covers.

A key tool in her argument is the concept of agreement soundness error.

**Definition 3.1** (List-agreement soundness error). Let $\mathcal{G}$ be a Label-Cover for deciding the satisfiability of a Boolean formula $\phi$. Let $\varphi_A$ assign each $A$-vertex $\ell$ alphabet symbols. We say that the $A$-vertices totally disagree on a vertex $b \in B$ if, there are no two neighbors $a_1, a_2 \in A$ of $b$ for which there exist $\sigma_1 \in \varphi_A(a_1), \sigma_2 \in \varphi_A(a_2)$ such that $\pi_{(a_1, b)}(\sigma_1) = \pi_{(a_2, b)}(\sigma_2)$.

We say that $\mathcal{G}$ has list-agreement soundness error $(\ell, \epsilon)$ if, for unsatisfiable $\phi$, for any assignment $\varphi_A : A \rightarrow (\sigma_A^\ell)$, the $A$-vertices are in total disagreement at least $1 - \epsilon$ fraction of the $B$-vertices.

The reduction of Thm. 2.4 is obtained by stringing together two reductions: from Label-Cover to a modified Label-Cover with a low agreement soundness error, and from that to Set-Cover.

The first one is laid out in the following lemma that combines Lemmas 4.4 and 4.7 of [19]. The proof is given in the upcoming subsection.

**Lemma 3.2.** Let $D \geq 2$ be a prime power, $q$ be a power of $D$, $\ell > 1$, and $\epsilon_0 > 0$. There is a polynomial reduction from a Label-Cover with list-agreement soundness error $(\ell, 2\epsilon_0 D^2, \ell^2)$ and $B$-degree $q$ to a Label-Cover with list-agreement soundness error $(\ell, 2\epsilon_0 D^2, \ell^2)$ and $B$-degree $D$. The reduction preserves alphabets, and the size is increased by $\text{poly}(q)$-factor.

Moshkovitz also gave a reduction from Label-Cover with small agreement soundness error to Set-Cover approximation. We extract a more general parameterization than is stated explicitly around Claim 4.10 in [19]. The proof, with minor changes from [19], is given for completeness in Sec. 3.2.

**Lemma 3.3** ([19], rephrased). Let $G' = (G' = (A', B', E'), \Sigma_A, \Sigma_B, \Pi')$ be a bi-regular Label-Cover instance with soundness parameter $\epsilon$ for deciding the satisfiability of a Boolean formula $\phi$. Let $D$ be the $B'$-degree. For every $\alpha$ with $2/D < \alpha < 1$ and any $u \geq (D^{O(\log D)} D \log |\Sigma_B|)^{1/\alpha}$, there is a reduction from $G'$ to a Set-Cover instance $\mathcal{SC} = \mathcal{SC}_{G'}$ with a certain choice of $\alpha$ that attains the following properties:

1. Completeness: If all edges of $G'$ can be covered, then $\mathcal{SC}$ has a set cover of size $|A'|$.
2. Soundness: If $G'$ has list-agreement soundness error $(\ell, \alpha)$, where $\ell = D(1 - \alpha) \ln u$, then every set cover of $\mathcal{SC}$ is of size more than $|A'| \cdot (1 - 2\alpha) \ln u$.
3. The number $N$ of elements of $\mathcal{SC}$ is $|B'| \cdot u$ and the number $M$ of sets is $|A'| \cdot |\Sigma_A|$.
4. The time for the reduction is polynomial in $|A'|, |B'|, |\Sigma_A|, |\Sigma_B|$ and $u$.

Given these lemmas, we can now prove Thm. 2.4 which we restate for convenience.

**Theorem 2.4** (rephrased). Let $\gamma > 0$ and $0 < \delta < \gamma$. There is a reduction from Label-Cover to Set-Cover with the following properties. Let $G$ be a bi-regular Label-Cover of almost-linear size $n_{00}$, soundness error parameter $\epsilon$, $B$-degree $\text{poly}(1/\epsilon)$, and alphabet size $\sigma_A(\epsilon)$. Then for each $\gamma > 0$, $G$ is reduced to a Set-Cover instance $\mathcal{SC} = \mathcal{SC}_{G, \gamma, \delta}$ with approximation gap $(1 - \gamma) \ln N, N = \tilde{O}(n_{00}^{(\gamma - \delta)})$ elements, and $M = \tilde{O}(n_{00} \cdot \sigma_A(\text{polylog}(n)))$ sets. The time of the reduction is linear in the size of $\mathcal{SC}$.

**Proof of Thm. 2.4** Let $\alpha = 2\delta, D$ be a prime power at least $2/\alpha$, and $\gamma' = (\gamma - \delta)/(1 - \delta)$. Let $n_1 = \tilde{O}(n_{00})$ be the size of the instance that is formed by Lemma 3.2 on $G$ with

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1 Moshkovitz doesn’t explicitly relate $\alpha$ and $D$, but indicates that $\alpha$ be small and $D$ 'sufficiently large'.
The reduction preserves alphabets, and the size is increased by \(B\) and \(B\) \(\begin{align*}
\text{We give here a full proof of Lemma 3.2, based on [19], with minor modification.}
\end{align*}\)

The proof is based on the following combinatorial lemma, whose proof we omit. We note that when labeling assigns a single label to each node, i.e., when \(\ell = 1\), the list-agreement soundness error reduces to agreement soundness error, which is otherwise defined equivalently. Moshkovitz first showed how to reduce a LABEL-COVER with small soundness error to one with a small agreement soundness error. The lemma stated here is unchanged from [19] except that Moshkovitz used the parameter name \(n\) instead of our parameter \(q\). \(\square\)

### 3.1 Proof of Lemma 3.2

We give here a full proof of Lemma 3.2 based on [19], with minor modification.

When the labeling assigns a single label to each node, i.e., when \(\ell = 1\), the list-agreement soundness error reduces to agreement soundness error, which is otherwise defined equivalently. Moshkovitz first showed how to reduce a LABEL-COVER with small soundness error to one with a small agreement soundness error. The lemma stated here is unchanged from [19] except that Moshkovitz used the parameter name \(n\) instead of our parameter \(q\). \(\square\)

▶ **Lemma 3.4 (Lemma 4.4 of [19]).** Let \(D \geq 2\) be a prime power and let \(q\) be a power of \(D\). Let \(\epsilon_0 > 0\). There is a polynomial reduction from a LABEL-COVER with soundness error \(\epsilon_0^2 D^2\) and \(B\)-degree \(q\) to a LABEL-COVER with agreement soundness error \(2\epsilon_0 D^2\) and \(B\)-degree \(D\). The reduction preserves alphabets, and the size is increased by \(\text{poly}(q)\)-factor.

We have underlined the parts that changed because of using \(q\) as parameter instead of \(n\). The proof is based on the following combinatorial lemma, whose proof we omit. We note that the set \(U\) here is different from the one used in Lemma 3.3 (but we retained the notation to remain faithful to [19]).

▶ **Lemma 3.5 (Lemma 4.3 of [19]).** For \(0 < \epsilon < 1\), for a prime power \(D\), and \(q\) that is a power of \(D\), there is an explicit construction of a regular bipartite graph \(H = (U, V, E)\) with \(|U| = q\), \(V\)-degree \(D\), and \(|V| \leq q^{O(1)}\) that satisfies the following. For every partition \(U_1, \ldots, U_\ell\) of \(U\) into sets such that \(|U_i| \leq \ell|U|\) for \(i = 1, 2, \ldots, \ell\), the fraction of vertices \(v \in V\) with more than one neighbor in any single set \(U_i\), is at most \(\epsilon D^2\).

Again, we used the parameter name \(q\), rather than \(n\) as in [19]. We show how to take a LABEL-COVER with standard soundness and convert it to a LABEL-COVER instance with total disagreement soundness, by combining it with the graph from Lemma 3.5.

**Proof of Lemma 3.4.** Let \(\mathcal{G} = (G = (A, B, E), \Sigma_A, \Sigma_B, \Pi)\) be the original LABEL-COVER. Let \(H = (U, V, E_H)\) be the graph from Lemma 3.5 where \(q\), \(D\) and \(\epsilon\) are as given in the current lemma. Let us use \(U\) to enumerate the neighbors of a \(B\)-vertex, i.e., there is a function \(E^* : B \times U \to A\) that given a vertex \(b \in B\) and \(u \in U\) gives us the \(A\)-vertex which is the \(u\) neighbor (in \(G\)) of \(b\).

\(^2\) This invited confusion, since \(n\) was also used to denote the size of the LABEL-COVER (like we do here).
We create a new Label-Cover \( \mathcal{G}' = (G = (A, B \times V, E'), \Sigma_A, \Sigma_B, \Pi') \). The intended assignment to every vertex \( a \in A \) is the same as its assignment in the original instance. The intended assignment to a vertex \( (b, v) \in B \times V \) is the same as the assignment to \( b \) in the original game. We put an edge \( e' = (a, (b, v)) \) if \( E'^-(b, u) = a \) and \( (u, v) \in E_H \). We define \( \pi e' = \pi_{(a, b)} \).

If there is an assignment to the original instance that satisfies \( \epsilon \) fraction of its edges, then the corresponding assignment to the new instance satisfies \( \epsilon \) fraction of its edges.

Suppose there is an assignment for the new instance \( \varphi_A : A \rightarrow \Sigma_A \) in which more than \( 2\epsilon D^2 \) fraction of the vertices in \( B \times V \) do not have total disagreement.

Let us say that \( b \in B \) is ‘good’ if for more than an \( \epsilon D^2 \) fraction of the vertices in \( \{b\} \times V \), the \( A \)-vertices do not totally disagree. Note that the fraction of good \( b \) in \( B \) is at least \( \epsilon D^2 \).

Focus on a good \( b \in B \). Consider the partition of \( U \) into \( |\Sigma_B| \) sets, where the set corresponding to \( \sigma \in \Sigma_B \) is:

\[
U_\sigma = \{ u \in U | a = E'^-(b, u) \land e = (a, b) \in E_G \land \pi e (\varphi_A(a)) = \sigma \}.
\]

By the goodness of \( b \) and the property of \( H \), there must be \( \sigma \in \Sigma_B \) such that \( |U_\sigma| > \epsilon |U| \).

We call \( \sigma \) the ‘champion’ for \( b \).

We define an assignment \( \varphi_B : B \rightarrow \Sigma_B \) that assigns good vertices \( b \) their champions, and other vertices \( b \) arbitrary values. The fraction of edges that \( \varphi_A, \varphi_B \) satisfy in the original instance is at least \( \epsilon^2 D^2 \).

Moshkovitz then shows that small agreement soundness error translates to the list version. The proof is unchanged from [19].

\[\textbf{Lemma 3.6 (Lemma 4.7 of [19]).} \text{ Let } \ell \geq 1, 0 < \epsilon' < 1. \text{ A Label-Cover with agreement soundness error } \epsilon' \text{ has list-agreement soundness error } (\ell, \epsilon' \ell^2).\]

\[\textbf{Proof.} \text{ Assume by the way of contradiction that the Label-Cover instance has an assignment } \hat{\varphi}_A : A \rightarrow (\Sigma_A^\ell) \text{ such that on more than } \epsilon' \ell^2 \text{-fraction of the } B \text{-vertices, the } A \text{-vertices do not totally disagree. Define an assignment } \varphi_A : A \rightarrow \Sigma_A \text{ by assigning every vertex } a \in A \text{ a symbol picked uniformly at random from the } \ell \text{ symbols in } \hat{\varphi}_A(a). \text{ If a vertex } b \in B \text{ has two neighbors } a_1, a_2 \in A \text{ that agree on } b \text{ under the list assignment } \hat{\varphi}_A, \text{ then the probability that they agree on } b \text{ under the assignment } \varphi_A \text{ is at least } 1/\ell^2. \text{ Thus, under } \varphi_A, \text{ the expected fraction of the } B \text{-vertices that have at least two neighbors that agree on them, is more than } \epsilon'. \text{ In particular, there exists an assignment to the } A \text{-vertices, such that more than } \epsilon' \text{ fraction of the } B \text{-vertices have two neighbors that agree on them. This contradicts the agreement soundness.}\]

\[\text{Lemma 3.2 follows directly from combining Lemmas 3.4 and 3.6.}\]

### 3.2 Proof of Lemma 3.3

We give here a proof of Lemma 3.3, following closely the exposition of [19], with minor modifications.

Peige [10] introduced the concept of partition systems (also known as anti-universal sets [22]) which is key to tight inapproximibility results for Set-Cover. It consists of a universe along with a collection of partitions. Each partition covers the universe, but any cover that uses at most one set out of each partition, is necessarily large. The idea is to form the reduction so that if the SAT instance is satisfiable, then one can use a single partition to
cover the universe, while if it is unsatisfiable, then one must use sets from different partitions, necessarily resulting in a large set cover.

Naor, Schulman, and Srinivasan [22] gave the following combinatorial construction (which as appears as Lemma 4.9 of [19]) that derandomizes one introduced by Feige [10].

**Lemma 3.7 ([22]).** For natural numbers $m$, $D$ and $0 < \alpha < 1$, with $\alpha \geq 2/D$, and for all $u \geq (D^O(\log D) \log m)^{1/\alpha}$, there is an explicit construction of a universe $U$ of size $u$ and partitions $P_1, \ldots, P_m$ of $U$ into $D$ sets that satisfy the following: there is no cover of $U$ with $\ell = D \ln |U|/(1-\alpha)$ sets $S_1, \ldots, S_\ell$, $1 \leq i_1 < \cdots < i_\ell \leq m$, such that set $S_{i_j}$ belongs to partition $P_{i_j}$.

Naor et al [22] state the result in terms of the relation $u \geq (D/(D-1))^{\ell O(\log \ell \log m}$. Note that for $\ell = D \ln u(1 - \alpha)$, we have $(D/(D-1))^{\ell} \approx u^{(1-\alpha)D/(D-1)} \approx u^{1-\alpha+1/D}$, and hence we need $D$ to be sufficiently large.

The following reduction follows Moshkovitz [19], which in turns is along the lines of Feige [10].

**Lemma 3.3 (restated).** Let $\mathcal{G}' = (G' = (A', B', E'), \Sigma_A, \Sigma_B, W')$ be a bi-regular Label-Cover instance with soundness parameter $\epsilon$ for deciding the satisfiability of a boolean formula $\phi$. Let $D$ be the $B'$-degree. For every $\alpha$ with $2/D < \alpha < 1$, and any $u \geq (D^O(\log D) \log |\Sigma_B|)^{1/\alpha}$, there is a reduction from $G$ to a Set-Cover instance $\mathcal{SC} = \mathcal{SC}_G$ with a certain choice of $\epsilon$ that attains the following properties:

1. Completeness: If all edges of $G$ can be covered, then $\mathcal{SC}$ has a set cover of size $|A'|$.
2. Soundness: If $G'$ has list-agreement soundness error $(\ell, \alpha)$, where $\ell = D(1-\alpha) \ln u$, then every set cover of $\mathcal{SC}$ is of size more than $|A'|(1-2\alpha) \ln u$.
3. The number $N$ of elements of $\mathcal{SC}$ is $|B'| \cdot u$ and the number $M$ of sets is $|A'| \cdot |\Sigma_A|$.
4. The time for the reduction is polynomial in $|A'|, |B'|, |\Sigma_A|, |\Sigma_B|$ and $u$.

**Proof.** Let $\alpha$ and $u$ be values satisfying the statement of the theorem. Let $m = |\Sigma_B|$ and let $D$ be the $B$-degree of $G$. Apply Lemma 3.7 with $m$, $D$ and $u$, obtaining a universe $U$ of size $u$ and partitions $P_1, \ldots, P_m$ of $U$. We index the partitions by the symbols $\sigma_1, \ldots, \sigma_m$ of $\Sigma_B$. The elements of the Set-Cover instances are $B \times U$. Equivalently, each vertex $b \in B$ has a copy of the universe $U$. Covering this universe corresponds to satisfying the edges that touch $b$. There are $m$ ways to satisfy the edges that touch $b$ — one for every possible assignment $\sigma \in \Sigma_B$ to $b$. The different partitions covering $u$ correspond to those different assignments.

For every vertex $a \in A$ and an assignment $\sigma \in \Sigma_A$ to $a$ we have a set $S_{a,\sigma}$ in the Set-Cover instance. Taking $S_{a,\sigma}$ to the cover corresponds to assigning $\sigma$ to $a$. Notice that a cover might consist of several sets of the form $S_a$, for the same $a \in A$, which is the reason we consider list agreement. The set $S_{a,\sigma}$ is a union of subsets, one for every edge $e = (a, b)$ touching $a$. If $e$ is the $i$-th edge coming into $b$ ($1 \leq i \leq D$), then the subset associated with $e$ is $\{b\} \times S_i$, where $S_i$ is the $i$-th subset of the partition $P_{e,(\sigma)}$.

Completeness follows from taking the set cover corresponding to each of the $A$-vertices and its satisfying assignments.

To prove soundness, assume by contradiction that there is a set cover $C$ of $\mathcal{SC}_G$ of size at most $|A| \ln |U|/(1-2\alpha)$. For every $a \in A$, let $s_a$ be the number of sets in $C$ of the form $S_{a,\sigma}$. Hence, $\sigma_{a \in A}s_a = |C|$. For every $b \in B$, let $s_b$ be the number of sets in $C$ that participate in

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3 Moshkovitz doesn’t explicitly relate $\alpha$ and $D$, but indicates that $\alpha$ be small and $D$ "sufficiently large".
covering \( \{b\} \times U \). Then, denoting the \( A \)-degree of \( G \) by \( D_A \),
\[
\sum_{b \in B} s_b = \sum_{a \in A} s_a D_A \leq D_A |A| \ln |U|(1 - 2\alpha) = D_B |B| \ln |U|(1 - 2\alpha) .
\]
In other words, on average over the \( b \in B \), the universe \( \{b\} \times U \) is covered by at most \( D \ln |U|(1 - 2\alpha) \) sets. Therefore, by Markov’s inequality, the fraction of \( b \in B \) whose universe \( \{b\} \times U \) is covered by at most \( D \ln |U|(1 - \alpha) = \ell \) sets is at least \( \alpha \). By the contrapositive of Lemma 3.7 and our construction, for such \( b \in B \), there are two edges \( e_1 = (a_1, b), e_2 = (a_2, b) \in E \) with \( S_{a_1, b}, S_{a_2, b} \in C \) where \( \pi_{e_1}(\sigma_1) = \pi_{e_2}(\sigma_2) \).

We define assignment \( \hat{\varphi}_A : A \rightarrow \binom{\Sigma_T}{\ell} \) to the \( A \)-vertices as follows. For every \( a \in A \), pick \( \ell \) different symbols \( \sigma \in \Sigma_A \) from those with \( S_{a, \sigma} \in C \) (add arbitrary symbols if there are not enough). As we showed, for at least \( \alpha \)-fraction of the \( b \in B \), the \( A \)-vertices will not totally disagree. Hence, the soundness property follows.

\section{Approximation Algorithm for Directed Steiner Tree}

Recall that in DST, the input consists of a directed graph \( G \) with costs \( c(e) \) on edges, a collection \( X \) of terminals, and a designated root \( r \in V \). The goal is to find a subgraph of \( G \) that forms an arborescence \( T_{opt} = T(r, X) \) rooted at \( r \) containing all the terminals and minimizing the cost \( c(T(r, X)) = \sum_{e \in T(r, X)} c(e) \). Let \( N = |X| \) denote the number of terminals and \( n \) the number of vertices.

Observe that one can model SET-COVER as a special case of DST on a 3-level acyclic digraph, with a universal root on top, nodes representing sets as internal layer, and the elements as leaves. The cost of an edge coming into a node corresponds to the cost of the corresponding element or set.

Our algorithm consists of "guessing" a set \( C \) of intermediate nodes of the optimal tree. After computing the optimal tree on top of this set, we use this set as the source of roots for a collection of trees to cover the terminals. This becomes a set cover problem, where we map each set selected to a tree of restricted size with a root in \( C \). Our algorithm then reduces to applying the classic greedy set cover algorithm on this instance induced by the "right" set \( C \). Because of the size restriction, the resulting approximation has a smaller constant factor.

We may assume each terminal is a leaf, by adding a leaf as a child of a non-leaf terminal and transfer the terminal function to that leaf. If a tree contains a terminal, we say that the tree covers the terminal.

Let \( \ell(T) \) denote the number of terminals in a tree \( T \). Let \( T_v \) denote the subtree of tree \( T \) rooted at node \( v \). For node \( v \) and child \( w \) of \( v \), let \( T_{vw} \) be the subgraph of \( T \) formed by \( T_w \cup \{vw\} \), i.e., consisting of the subtree of \( T \) rooted at \( w \) along with the edge to \( w \)'s parent \( (v) \).

\begin{definition}
A set \( C \subseteq V \) is a \( \phi \)-core of a tree \( T \) if there is a collection of edge-disjoint subtrees \( T_1, T_2, \ldots, T_l \) of \( T \) such that: a) the root of each tree \( T_i \) is in \( C \), b) every terminal in \( T \) is contained in exactly one tree \( T_i \), and c) each \( T_i \) contains at most \( \phi \) terminals, \( \ell(T_i) \leq \phi \).
\end{definition}

\begin{lemma}
Every tree \( T \) contains a \( \phi \)-core of size at most \( \lceil \ell(T)/\phi \rceil \), for any \( \phi \).
\end{lemma}

\begin{proof}
The proof is by induction on the number of terminals in the tree. The root is a core when \( \ell(T) \leq \phi \). Let \( v \) be a vertex with \( \ell(T_v) > \phi \) but whose children fail that inequality. Let \( C' \) be a \( \phi \)-core of \( T' = T \setminus T_v \) promised by the induction hypothesis, and let \( C = C' \cup \{v\} \).

For each child \( w \) of \( v \), the subtree \( T_{vw} \) contains at most \( \phi \) terminals. Together they cover uniquely the terminals in \( T_v \), and satisfy the other requirements of the definition of
a $\phi$-core for $T_v$. Thus $C$ is a $\phi$-core for $T$. Since $\ell(T') \leq \ell(T) - \phi$, the size of $C$ satisfies $|C| = |C'| + 1 \leq \lceil \ell(T')/\phi \rceil + 1 \leq \lceil (\ell(T) - \phi)/\phi \rceil + 1 = \lceil \ell(T)/\phi \rceil$. ▷

A core implicitly suggests a set cover instance, with sets of size at most $\phi$, formed by the terminals contained in each of the edge-disjoint subtrees. Our algorithm is essentially based on running a greedy set cover algorithm on that instance.

Let $R(v)$ denote the set of nodes reachable from $v$ in $G$.

- **Definition 4.3.** Let $S \subseteq V$, $U \subset X$, and let $\phi$ be a parameter. Then $S$ induces a $\phi$-bounded SET-COVER instance $(U, C(S, U))$ with $C(S, U) = \{ Y \subseteq U : |Y| \leq \phi \text{ and } \exists v \in S, Y \subseteq R(v) \}$. Namely, a subset $Y$ of at most $\phi$ terminals in $U$ is in $C(S, U)$ iff there is a $v$-rooted subtree containing $Y$.

We relate set cover solutions of $C(S, X)$ to DST solutions of $G$ with the following lemmas.

For a node $r_0$ and set $F$, let $T(r_0, F)$ be the tree of minimum cost that is rooted by $r_0$ and contains all the nodes of $F$. For sets $F$ and $S$, let $T(S, F)$ be the tree of minimum cost that contains all the nodes of $F$ and is rooted by some node in $S$.

- **Lemma 4.4.** Let $S$ be a set cover of $C(S, X)$ of cost $c(S)$. Then, we can form a valid DST solution $T_S$ by combining $T(r, S)$ with the trees $T(S, F)$, for each $F \subseteq S$. The cost of $T_S$ is at most $c(T_S) \leq c(T(r, S)) + c(S)$.

**Proof.** $T_S$ contains all the terminals since the sets in $S$ cover $X$. It contains an $r$-rooted arborescence since $T(r, S)$ contains a path from $r$ to all nodes in $S$, and the other subtrees contain a path to each terminal from some node in $S$. The cost bound follows from the definition of the weights of sets in $C(S, X)$. The actual cost could be less, if the trees share edges or have multiple paths, in which case some superfluous edges can be shed. ▷

Let $OPT_{SC}(C)$ be the weight of an optimal set cover of a set system $C$.

- **Lemma 4.5.** Let $C$ be a $\phi$-core of $T_{opt}$. The cost of an optimal DST of $G$ equals $OPT_{SC}(C(S, X))$ plus the cost of an optimal $r$-rooted tree with $C$ as terminals: $c(T_{opt}) = OPT_{SC}(C(S, X)) + c(T(r, C))$.

**Proof.** The subtree of $T_{opt}$ induced by $C$ and the root $r$ has cost $c(T(r, C))$. The rest of the tree consists of the subtrees $T_{vu}$, for each $v \in C$ and child $w$ of $v$. $T_{vu}$ contains at most $\phi$ terminals, so the corresponding set is contained in $C(S, X)$. Together, these subtrees contain all the terminals, so the corresponding set collection covers $C(S, X)$. Thus, $c(T_{opt}) \geq c(T(r, C)) + OPT_{SC}(C(S, X))$. By Lemma 4.4, the inequality is tight. ▷

The density of a set $F$ in $C(S, X)$ is $\min_{s \in S} c(T(s, F))/|F|$; the cost of the optimal tree containing $F$ averaged over the nodes in $F$.

Given a root and a fixed set $S$ of nodes as leaves, an optimal cost tree $T(r, S)$ can be computed in time $poly(n)2^{\lceil n/\phi \rceil}$ by a (non-trivial) algorithm of Dreyfus and Wagner [9].

- **Lemma 4.6.** A minimum density set in $C(S, X)$ can be found in time $n^{O(\max(\phi, N/\phi))}$.

**Proof.** There are at most $2n^\phi$ subsets of at most $\phi$ terminals and at most $N/\phi$ choices for a root from the set $C$. Given a potential root $r_0$ and candidate core $S$, the algorithm of [9] computes $T(r_0, S)$ in time $poly(n)2^{2N/\phi}$. ▷
Our algorithm for DST is based on guessing the right \( \phi \)-core \( C \), and then computing a greedy set cover of \( C^\phi_{S,X} \) by repeatedly applying Lemma 4.6. More precisely, we try all possible subsets \( S \subseteq V \) of size at most \( 2N/\phi \) as a \( \phi \)-core (of \( T_{opt} \)) and for each such set do the following. Set \( U \) initially as \( X \), representing the uncovered terminals. Find a min-density set \( Z \) of \( C^\phi_{S,U} \) and a corresponding optimal cost tree (with some root in \( S \)), remove \( Z \) from \( U \) and repeat until \( U \) is empty. We then compute \( T(r,S) \) and combine it with all the computed subtrees into a single tree \( T_S \). The solution output, \( T_{alg} \), is the \( T_S \) of smallest total cost, over all the candidate cores \( S \).

**Theorem 4.7.** Let \( \gamma \geq 1/2 \) be a parameter, \( \phi = N^{1-\gamma} \), and let \( C \) be a \( \phi \)-core of \( T_{opt} \). Then the greedy set cover algorithm applied to \( C^\phi_{S,X} \) yields a \( 1 + \ln \phi \)-approximation of DST. Namely, our algorithm is a \( (1 - \gamma) \ln n \)-approximation of DST. The running time is \( n^{O(\max(\phi,N/\phi))} = \exp(\tilde{O}(N^\gamma)) \).

**Proof.** Let \( Gr \) be the size of the greedy set cover of \( C^\phi_{C,X} \) and \( O = OPT_{SC}(C^\phi_{C,X}) \). Since the cardinality of the largest set in \( C^\phi_{C,X} \) is at most \( \phi \), it follows by the analysis of Chvátal [5] that \( Gr \leq (1 + \ln \phi)OPT_{SC}(C^\phi_{C,X}) \). Thus, letting \( t_C = c(T(r,C)) \),

\[
\begin{align*}
\phi(T_{alg}) & \leq t_C + Gr \\
& \leq t_C + (1 + \ln \phi)O \leq (1 + \ln \phi)(t_C + O) = (1 + \ln \phi)c(T_{opt}) ,
\end{align*}
\]

applying Lemma 4.4 in the first inequality and Lemma 4.5 in the (final) equality. Observe that \( \ln \phi = (1 - \gamma) \ln n \). For each candidate core \( S \) we find a min-density set at most \( n \) times. There are \( \binom{n}{N/\phi} \leq n^{N/\phi} \) candidate cores and the cost for each is \( n \cdot n^{O(\min(\phi,N/\phi))} \), by Lemma 4.6. Hence, the total cost is \( n^{N/\phi} \cdot n^{O(\max(\phi,N/\phi))} = n^{O(N/\phi)} = \exp(\tilde{O}(N^\gamma)) \) using that \( \phi = N^{1-\gamma} \leq N/\phi \).

Now we observe that the same theorem applies to the **Connected Polymatroid** problem. Since the function is both submodular and increasing, for every collection of pairwise disjoint sets \( \{S_i\}_{i=1}^k \), it holds that \( \sum_{i=1}^k f(S_i) \geq f(\bigcup_{i=1}^k S_i) \). Thus, for a given \( \gamma \geq 1/2 \), at iteration \( i \) there exists a collection \( S_i \) of terminals so that \( f(S_i)/c(S_i) \geq f(U)/c(U) \). We can guess \( S_i \) in time \( \exp(N^\gamma \cdot \log n) \) and its set of Steiner vertices \( X_i \) in time \( O(3^{N^\gamma}) \). Using the algorithm of [9], we can find a tree of density at most \( \text{opt}/N^\gamma \). The rest of the proof is identical.

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