Enabling data-limited chemical bioactivity predictions through deep neural network transfer learning

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Abstract
The main limitation in developing deep neural network (DNN) models to predict bioactivity properties of chemicals is the lack of sufficient assay data to train the network’s classification layers. Focusing on feedforward DNNs that use atom- and bond-based structural fingerprints as input, we examined whether layers of a fully trained DNN based on large amounts of data to predict one property could be used to develop DNNs to predict other related or unrelated properties based on limited amounts of data. Hence, we assessed if and under what conditions the dense layers of a pre-trained DNN could be transferred and used for the development of another DNN associated with limited training data. We carried out a quantitative study employing more than 400 pairs of assay datasets, where we used fully trained layers from a large dataset to augment the training of a small dataset. We found that the higher the correlation \( r \) between two assay datasets, the more efficient the transfer learning is in reducing prediction errors associated with the smaller dataset DNN predictions. The reduction in mean squared prediction errors ranged from 10 to 20% for every 0.1 increase in \( r^2 \) between the datasets, with the bulk of the error reductions associated with transfers of the first dense layer. Transfer of other dense layers did not result in additional benefits, suggesting that deeper, dense layers conveyed more specialized and assay-specific information. Importantly, depending on the dataset correlation, training sample size could be reduced by up to tenfold without any loss of prediction accuracy.

Graphical abstract

Keywords Machine learning · Deep neural networks · Transfer learning · QSAR

Introduction
Numerous computational methodologies and applications have been developed to predict diverse properties of chemicals, such as their physiochemical characteristics, pharmacological effects, or biomedical activities [1–4]. The use of in silico modeling methods to develop quantitative structure–activity relationship (QSAR) play an important role in a
range of disciplines such as rational drug discovery, toxicity predictions, and exposure risk assessments [5–8]. The fundamental steps in developing such model predictions require (1) acquiring training and validation data to build and evaluate the prediction model (data), (2) specifying a molecular description method to capture the relevant chemical features to build the model on (feature extraction), and (3) choosing a machine learning approach for modeling regression or classification (model) [9, 10].

Although these steps are interconnected, the main limiting factor in creating any accurate data driven machine-learning model is the availability of sufficient data to train the model, a problem that is especially acute when deploying deep neural network (DNN) techniques and models to QSAR-based chemical and bioactivity property predictions [11, 12]. This is in stark contrast to applications in image recognition where convolutional neural networks (CNNs) pre-trained on images belonging to a large number of readily available images can be re-used [13], effectively reducing the amount of training samples needed as there is no need to re-learn image feature extraction from scratch [14–16]. The ability to circumvent the need to re-learn the basics of image recognition is a powerful concept and, similarly, we would like to avoid re-learning all of chemistry and biology when developing machine-learning models that predict bioactivities of chemicals. Indeed, this transfer learning strategy was recently implemented and evaluated as a means to overcome the challenge of lack of data for deep learning in biomedical research [17–19], with an overview of deep transfer learning and related applications to drug discovery published in 2020 [20]. These studies show that deploying transfer learning to predict molecular bioactivity are likely to be successful, but the degree of success appeared to be dataset-dependent [18, 19]. None of the studies published so far systematically examined or determined the conditions under which transfer learning would be successful or quantified the potential benefits. Yamada et al. [19] examined a shotgun transfer learning method developed on 140,000 models pre-trained with large amount of training data. To developed a model with limited training data, they transferred a fraction of model parameters from one of their pre-trained models and optimized the rest of the model parameters using available limited training data. This process was repeated, each time with parameters transferred from a different pre-trained model. The resulting models were then evaluated, and the one that gave the best performance was chosen as the final transfer learnt model. This represents a trial and error approach and requires a certain amount of test data for a reliable evaluation of model performance, which may not be available if there is insufficient training data. Hence, the goal of our study was to develop and quantify a methodology that can be used to transfer learnt knowledge from one dataset to another prediction problem with a priori confidence.

Whereas image recognition techniques per se have not been widely adopted for bioactivity prediction problems [8, 21], the development of efficient molecular feature extraction methods can roughly be divided into a static, structure-based descriptor method that encodes atom and bond features [22–26] and a dynamic graph neural network (GNN) approach that learns molecular features within the context of the data to be modeled [27–30]. This latter method represents an efficient end-to-end deep learning method as the learnt, extracted features capture all features important to the modeled data, but may not be applicable for other datasets [31]. As a result, GNN-based transfer learning may instead lead to a degradation in model performance and learning [28]. Instead, here we are examining how and under what conditions the dense layers of one feedforward neural network can be used to augment training of a different DNN, i.e., transfer “knowledge” between networks, to classify a different bioactivity property.

The premise for this study is the application of the quantitative structure–activity relationship (QSAR) principle, which states that the chemical structure of a compound contains sufficient information to predict the outcome of a specific bioactivity assay. We fixed the representation of the chemical structures using extended-connectivity fingerprints (ECFP) to generate a one-dimensional fingerprint of each chemical structure—encoding atoms, bonds, and chemical environments—as molecular input features [26]. The choice of using ECFPs instead of graph neural networks (GNNs) to create molecular input features allowed us to focus on assessing the use of dense layers in applying transfer learning [32, 33]. We collected data for pairs of assays comprising one “large” and one “small” dataset, but with sufficient overlap between the chemicals to allow us to gauge the correlations between the two datasets. We then examined under what conditions (different network architectures, number of training samples, and degree of correlation between different assays) pre-trained layers from a “large” dataset could be used to develop a DNN model for a “small” dataset. In particular, we examined predictions of the 50% growth inhibition concentration (pGI50) of compounds tested in the U.S. National Cancer Institute’s NCI-60 Human Tumor Cell Lines Screening project [34]. These datasets comprise a varying number of overlapping compounds tested for their pGI50 in multiple cell lines [35]. We used these as well as other bioassay and physiochemical datasets to examine the reduction in mean squared prediction errors when transferring dense layers with frozen parameters from one fully trained DNN model based on a large dataset to train another DNN associated with fewer data.

The aim here is not to make accurate pGI50 or property predictions per se, but rather to examine under what conditions transfer learning is appropriate and what can be gained by transferring dense DNN layers. This paves the way for
using similar transfer-learning techniques to overcome the challenge of limited data when implementing DNNs in drug design efforts, toxicity evaluations, and assessment of biological activity of chemicals.

Materials and methods

Molecular activity datasets

One of the challenges of evaluating deep learning is the lack of large high-quality datasets. Our study surveyed a total of 52 datasets with partially overlapping compound sets, ranging from a high of over 50,000 data points for the 50% growth inhibition of the A549 (a lung cancer) cell line to a low of 1266 data points for cytochrome P450 inhibition (Cyp2C9). The bulk of the data comprise 29 datasets from the U.S. National Cancer Institute’s NCI-60 Human Tumor Cell Lines Screen project, examining growth-inhibition data for more than 60 human cancer cell lines of different tissues of origin for a large number of chemicals. For many cell lines, pGI50 spans 17 orders of magnitude, with a pGI50 uncertainty of about 0.45, estimated from multiple measurements of the same compounds that serve as plate controls. We also used 16 datasets ranging in size from 5923 to 2407 molecules each, comprising measured binding affinities of drug-like molecules to proteins as collected in the publicly available BindingDB database [36], and four datasets ranging from 3413 to 1266 molecules each, tested against different isoforms of cytochrome P450 inhibition from PubChem [37]. In addition, we used a publicly available acute rat oral toxicity dataset consisting of 6,320 tested chemicals [38] as well as a molecular lipophilicity dataset of 10,130 molecules, quantified by the n-octanol/water partition coefficient P and presented in a logarithmic form (logP), and an aqueous solubility dataset of 8,665 molecules, given in logarithmic form (logS) [39]. Details of these datasets, including the number of compounds in each dataset, molecular property/activity, measurement units, and source of the dataset, are summarized in Table S1 of the Supplementary Information.

DNN architecture, software, and hyperparameters

DNNs use a number of hyperparameters, some for defining the neural network architecture, such as number of hidden layers (depth of network) and number of hidden neurons in a hidden layer (width of layer), and others for controlling training behavior, such as gradient descent optimizer, learning rate, batch size, and number of epochs. We used networks with up to three hidden layers with different number of hidden nodes. For the single-hidden layer architecture, we used 100, 500, 1000, 2000, 4000, or 6000 hidden neurons. For the two-hidden layer architecture, we used all combinations of the first hidden layer containing 1000, 2000, or 4000 neurons and the second layer contained 100, 500, 1000, or 2000 neurons. We limited the three-hidden layer architecture to all combinations of 1000 or 2000 neurons in the first layer, 500 or 1000 in the second layer, and 100 or 500 neurons in the third layer.

To develop a best performing DNN for a specific dataset, a common practice is to first select a specific set of hyperparameters that works best for the dataset, which usually requires costly grid searches for large datasets [40]. As this procedure is dataset dependent, the optimal hyperparameters for one dataset may not be appropriate for another, and as transfer learning involves at least two different datasets (a data-rich and a data-limited dataset), we did not optimize hyperparameters for individual datasets. Instead, we used generally recommended or commonly used hyperparameters for molecular activity modelling [41, 42], and we deliberately constructed the above networks with different depths and widths to ensure that our findings regarding transfer learning were not dependent on a specific network architecture.

We performed all DNN calculations using the Keras API in TensorFlow 2.1.0 in a Python 3.7.6 environment. To prepare input data into training, validation, and test sets, we used the train_test_split function of scikit-learn 0.22.1. We used Adam optimizer [43] to minimize the mean squared error (MSE) loss function, with a learning rate of 0.001, a batch size of 50, and a maximum number of epochs of 2000. However, our DNN optimizations always stopped well before reaching the maximum number of epochs, as we applied the early stopping with a patience of 50, i.e., when the MSE of the validation set ceased to improve with 50 additional epochs, the training stopped and the network weights and biases that yielded the smallest validation MSE were selected as the final optimized model parameters. In an overwhelming majority of the cases, the smallest validation MSE were achieved in 10 to 30 epochs only. In order to reduce overfitting, we used dropout regularization with a fixed dropout rate of 25% on all input, output, and hidden layers. We used Keras’ default selection/values for all other hyperparameters, i.e., the activation function was set to the ReLU function, the weight kernel initializer was set to “glorot_uniform” [44] and the bias initializer was set to “zero.”

Input features

In this study, we used the counts of ECFP [26] features present in a molecule calculated using a bond diameter of two as the input features of the molecule. The fingerprint features were folded to a fixed length of 1024. That is, the input features of each molecule were stored in a vector of 1024 integers, where each integer represents a count of a molecular fragment present in the molecule. We generated the input
features using Pipeline Pilot software using the Molecular Fingerprints and Convert Fingerprint components (Dassault Systèmes, Vélizy-Villacoublay, France).

**Transfer-learning efficiency**

To assess transfer learning quantitatively, we defined transfer-learning efficiency (TLE) as the percentage reduction of MSE due to transfer learning, as follows:

\[
    TLE = \frac{\text{MSE}_0 - \text{MSE}_{\text{TL}}}{\text{MSE}_0} \times 100\%
\]

where \( \text{MSE}_0 \) represents the MSE of test-set compounds by a model trained without transfer learning and \( \text{MSE}_{\text{TL}} \) denotes the MSE of test-set compounds by a model trained with transfer learning.

**Results and discussion**

**Impact of neural network architecture and training set size**

To evaluate the effect of network architecture and training set size, we used the largest NCI-60 dataset—the growth inhibition data of 50,606 compounds against A549 cell line. We randomly selected 1000 compounds as the test set for DNN model performance evaluation. From the remaining compounds, we randomly selected subsets, ranging in number from 500 to 40,000, as the training sets and used the leftover compounds as validation sets. Although this introduced variability of the size of the validation set used to determine the training stopping point, the final test set used to evaluate the results remained fixed for these calculations.

For single-hidden layer networks, we evaluated networks of different width, with the number of hidden neurons ranging from 100 to 6000. For each network architecture and training-set size, we repeated model optimization five times using different initializing conditions, with the average MSE of the test set from the five resulting models considered as the MSE of the network architecture. Table 1 summarizes the numerical evaluation as a function of hidden neurons and number of compounds in the training sets, showing that with a large number of training samples (i.e., \( \geq 10,000 \)), the number of hidden neurons did not have an impact on model performance. However, when the training set was smaller, models with too few (i.e., 100) or too many (i.e., 4000 and 6000) hidden neurons appeared to perform worse than models with 500–2000 hidden neurons. Overall, the results are in line with the well-known observation that the larger the number of training samples, the better the model. The model improvement resulting from increasing the training-set size is roughly constant at 10% when doubling the training set size. Given that the absolute error is the largest of the smallest dataset, we can note that the largest absolute benefit in reducing prediction errors using transfer learning will occur for the smallest training sets.

Figures 1 and 2 show the corresponding numerical results for DNNs with two and three hidden layers, with the complete datasets presented in Tables S2 and S3, respectively, of the Supplementary Information. Similar to the results of one-hidden layer networks in Table 1, these results show that the most important determinant of model quality was the training sample size. Compared to variations in training-set size, the depth and width of the neural networks had a much smaller impact on model performance, especially when there were more than ~4000 compounds in the training set.

### Table 1 Mean squared error (standard deviation) of test-set compounds for predicting A549 cell inhibition using a single-hidden layer neural network trained as a function of increasing training-set size and with a variable number of neurons in the hidden layer. The data show that models with too few (e.g., 100) or too many (e.g., 6000) hidden neurons do not perform well when trained by small training sets. Doubling the number of compounds in the training set roughly reduced the relative error by 10%. The units of the errors are given in \((\text{log}_{10}(\text{mol/l}))^2\), and the smallest error for each set of training compounds are indicated in boldface font

| Number of hidden neurons | Number of training compounds | 500 | 1000 | 2000 | 3000 | 4000 | 10,000 | 20,000 | 30,000 | 40,000 |
|--------------------------|-----------------------------|-----|------|------|------|------|--------|--------|--------|--------|
| 100                      | 0.82 (0.04)                 | 0.74 (0.02) | 0.65 (0.02) | 0.62 (0.03) | 0.59 (0.02) | 0.47 (0.02) | 0.43 (0.02) | 0.40 (0.01) | 0.38 (0.01) |
| 500                      | 0.73 (0.03)                 | 0.67 (0.03) | 0.61 (0.03) | 0.58 (0.03) | 0.55 (0.02) | 0.47 (0.01) | 0.42 (0.03) | **0.38 (0.01)** | **0.37 (0.01)** |
| 1000                     | 0.73 (0.04)                 | 0.67 (0.02) | **0.60 (0.02)** | **0.57 (0.03)** | **0.54 (0.03)** | 0.46 (0.01) | 0.42 (0.02) | **0.38 (0.01)** | **0.38 (0.01)** |
| 2000                     | 0.73 (0.04)                 | 0.67 (0.02) | 0.61 (0.02) | **0.57 (0.03)** | 0.55 (0.03) | **0.45 (0.02)** | **0.41 (0.02)** | 0.39 (0.01) | **0.37 (0.01)** |
| 4000                     | 0.74 (0.03)                 | 0.69 (0.02) | 0.62 (0.02) | 0.58 (0.02) | 0.55 (0.02) | 0.46 (0.02) | 0.42 (0.02) | 0.39 (0.01) | **0.37 (0.01)** |
| 6000                     | 0.77 (0.04)                 | 0.70 (0.02) | 0.63 (0.02) | 0.59 (0.02) | 0.56 (0.02) | 0.46 (0.01) | **0.41 (0.02)** | 0.39 (0.01) | 0.38 (0.02) |

The smallest error for each set of training compounds are indicated in boldface font

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Effect of transferring parameters from a data-rich model to develop a model with limited training data: a proof-of-concept study

To evaluate the effect of transferring parameters from a model trained with a large number of compounds to develop a model with limited experimental data, we initially used A549 data as a data-rich dataset. We first developed a number of different DNN models for predicting pGI50 by randomly splitting the dataset into a 90% training set and a 10% validation set to train A549 prediction models with an increasing number of hidden layers. For these...
models, we used network architectures sized as 1024:1000:1, 1024:1000:1000:1, and 1024:1000:1000:500:1, where the initial nodes of size 1024 correspond to the number of input features, and the final single output node represents the predicted pGI50 value. The other integers correspond to the number of hidden neurons in the first, second, and third hidden layers.

Next, we designated the HTB132 (a breast cancer cell line) pGI50 data (total number of compounds 5612) to serve as a data-limited dataset. Figure 3 schematically shows the steps executed in evaluating the transfer-learning approach. We randomly selected 10% of the HTB132 data as a test set for evaluating the DNN model performance. From the remaining HTB132 data, we randomly selected 10% as a validation set. We then trained a series of HTB132 models of the same architecture as that of the A549 model using 500, 1000, and 2000 compounds to simulate models trained with small datasets. We also trained a HTB132 model with ~80% of the HTB132 dataset (4546 compounds), with the remaining 20% as the validation and test sets, to establish a reference of the best model one could derive from the HTB132 data only (without transfer learning). We used the MSE of the DNN models for the test-set compounds as a performance measure. Finally, we repeated the previous step of training the HTB132 DNN model, but with one to three hidden layers of the A549 models transferred while freezing the values of the weights and biases, and optimizing the rest of the model parameters using the HTB132 training sets. We then calculated the MSE of the test-set compounds using the resulting HTB132 models. Due to the stochastic nature of gradient descent optimization and random assignment of the initial weights and biases, each optimization ended up with a different set of model parameters. We repeated all model training 10 times with randomly selected training and validation compounds to derive statistically reliable results.

Figure 4 shows the results of our evaluation where each data point represents an average of the MSE over the 10 models trained with the same number of randomly selected training samples, where the vertical bar represents ±2 standard deviations. The three panels show the results as a function of the number of hidden layers in the networks, i.e., N = 1, 2, or 3. The complete datasets are given in Table S4 of the Supplementary Information. Figure 4 (top) shows that, for each network architecture, without transfer learning, model performance depended strongly on the number of compounds in the training set, with the variability decreasing with increasing training-set size, as expected. The range of minimum MSE achievable using the complete HTB132 data could not be reached with the limited-compound training set. However, using the frozen parameters transferred from the A549 model, optimization of the remaining parameters using the same HTB132 training sets resulted in a marked performance improvement, both in terms of considerably smaller average MSEs and their variability. Even with the smallest training set of 500 compounds, transfer learning resulted in considerably better models than training

![Diagram](image-url)
with all HTB132 compounds without transfer learning. For networks with two or three hidden layers, we transferred parameters for up to three hidden layers, with the results consistently indicating that transfer of the first hidden layer parameters was the most effective. Transferring parameters from additional layers resulted in slightly worse models as judged by the MSE of the test-set compounds. This is most likely due to the presence of more specialized, A549-specific parameters from the A549 growth inhibition DNN model appearing in the second and third hidden layers. Transferring these parameters would not provide any additional benefits to a non-A549-specific model, and could instead degrade the prediction performance of the HTB132 model.

**Conditions for transfer-learning success and expected benefits**

The results of transferring parameters from the A549 model to develop an HTB132 model are promising, yielding results that were better than what could be achieved by using the entire HTB132 dataset itself. The benefits can be partially explained by the high correlation and similarity of the assays themselves, i.e., by measuring chemically induced growth inhibition in cell-line cultures. In fact, the pGI50 values of A549 and HTB132 cells were highly correlated with a squared Pearson’s correlation coefficient ($r^2$) of 0.60, as calculated from the 5532 common compounds tested in both growth inhibition assays. As suggested by Xu et al. that assay correlation might be the key to success of multi-task DNN molecular activity models [45], we hypothesized that assay correlation may also be an important contributing factor to the success of transfer learning. Trivially, given an assay correlation of 1.0, transfer learning is by definition the optimal choice of weights. To non-trivially test this hypothesis, we need to assess transfer learning across many pairs of datasets with a broad range of inter-assay $r^2$ values. Consequently, we selected a number of NCI-60 growth inhibition dataset pairs that included cell lines from different tissue origins and complemented them with additional chemical activity data covering a broad range of inter-assay correlations.
We examined the NCI-60 MALME-3M (a human skin cancer) cell line dataset paired with 28 other cell lines, providing a range of inter-assay pGI50 correlations \( r^2 \) between 0.45 and 0.87. Similarly, we included the MDA-MB-435 (a human breast cancer) cell line paired with 18 other cell lines, with a range of inter-assay pGI50 correlations \( r^2 \) between 0.47 and 0.95. Given the nature of the NCI-60 assays and their relatively high correlations \( r^2 > 0.4 \), we complemented the NCI-60 dataset pairs with other chemical activity data, such as chemical binding affinity to drug targets, potency to inhibit enzyme functions, as well as physicochemical properties, including lipophilicity and aqueous solubility. Details of these datasets and their pairings are provided in Tables S1 and S5 of the Supplementary Information.

We evaluated transferability of the hidden layers of pre-trained neural networks across the dataset pairs using the 1024:2000:1, 1024:2000:100:1, and 1024:1000:1000:100:1 network architectures, where evaluation procedure followed the steps outlined in Fig. 3.

Thus, for each dataset pair, we designated the larger dataset as the data-rich dataset and the smaller one as the data-limited set. We used a random 90 to 10% split for training and validation of the data-rich models to create the weights and biases of the hidden layers so that they could be transferred for the development of the data-limited models. From each of the data-limited datasets, we first randomly selected 10% of the compounds as a test set. From the remaining compounds, we randomly selected 10% as the validation set. We then randomly selected 500 and 1,000 compounds from the remaining compounds as our data-limited training sets to train neural network models with and without transfer learning. We calculated the MSEs of the test sets using the resulting models and calculated TLE from the MSEs of models trained without and with transfer learning. Figure 5 shows the results for training sets consisting of 500 compounds, and Fig. 6 shows the corresponding data using 1,000-compound training sets. The numerical results are given in Tables S5 and S6 of the Supplementary Information. Figures 5 and 6 are similar, with both showing that when \( r^2 \) of a dataset pair was 0.4 or higher, the TLE was larger than zero, and the higher the \( r^2 \), the larger the TLE. When \( r^2 \) was lower than 0.4, the results were less clear-cut and depended on network architecture. Using the shallow network with a single hidden layer, in a little over 50% of the cases (19 out of 35 with a training set of 500 compounds and 21 out of 35 with a training set of 1000 compounds), transfer learning was able to lower the MSE, as indicated by a TLE > 0. However, using a deeper network with two or three hidden layers, in a majority of the cases, transfer learning resulted in a positive TLE even when \( r^2 \) was lower than 0.4.

Figure 7 shows the mean TLE values as a function of \( r^2 \) and illustrates that the higher the \( r^2 \), the better the transfer learning, the larger the benefit of transfer learning. The increase in TLE and consequent reduction in prediction error ranged from 10 to 20% for every 0.10 increase in \( r^2 \) between the datasets. In the cases where the inter-assay correlations \( r^2 \) were lower than 0.4, there was no benefit of using transfer learning for a one-hidden layer network, whereas two- or three-hidden layer network could still benefit.

![Fig. 5](image)

**Fig. 5** Transfer-learning efficiency (TLE) vs. squared correlation coefficient \( (r^2) \) between datasets. We trained all data-limited models with 500 compounds with or without transferring the first hidden layer from a corresponding data-rich model. The notation \( F^{\text{TLE}>0}_{r^2<0.4} \) represents the fraction of cases when \( r^2 < 0.4 \) and TLE was >0.
Fig. 6 Transfer-learning efficiency (TLE) vs. squared correlation coefficient ($r^2$) between datasets. We trained all data-limited models with 1000 compounds with or without transferring the first hidden layer from a corresponding data-rich model. The notation $F_{r^2<0.4}^{TLE>0}$ represents the fraction of cases when $r^2 < 0.4$ and TLE was $> 0$.

Fig. 7 Mean transfer-learning efficiency vs. squared correlation coefficient ($r^2$) between datasets for neural network models consisting of 1, 2, or 3 hidden layers. We trained the models with either (A) 500 or (B) 1000 compounds.
Limitations

We introduced the concept of dataset similarity as a metric for deciding when transfer learning could be beneficial to the augment training of DNNs associated with small-size datasets. Currently, we used Pearson’s correlation coefficient as a purely numerical evaluation of data similarity, and this may not capture all considerations for evaluating transfer learning. Furthermore, we do not know the correlation metric a priori, as it has to be estimated from the datasets themselves based on a potentially limited number of compounds tested in both datasets. Although this can be a practical limitation when confronted with narrow chemical diversity among the data, for chemical property applications based on minima; datasets of ~ 10^5 compound, the transfer learning approach described here might be the only practical way forward to implement a data-driven prediction model.

Summary

The goal of this study was to evaluate if and under what conditions the dense layers of a pre-trained DNN can be transferred and used for the development of another DNN associated with limited training data. Our results derived from molecular activity data indicated that, unlike the convolutional layers of a DNN for image recognition where all layers are considered transferrable, the bulk of error reduction in developing a network using a small dataset was associated with transfers from the first dense layer. Transfer of other dense layers did not result in additional benefit, suggesting that deeper, dense layers conveyed more specialized and assay-specific information. In addition, the benefits of transferring the first dense layer were related to the extent of inter-assay dataset correlation. The larger the correlation, the higher the transfer-learning efficiency. Interestingly, even when there was no apparent correlation, or when there was very low correlation between two datasets, transfer learning of DNNs with two or three hidden layers was still beneficial, albeit with a lower reduction of model error.

Note that in this study we used training sets of 500 and 1,000 compounds to simulate small training sets. Results of our evaluation of the impact of training-set size indicated that the larger the training set, the better the resulting model regardless of network architecture. Thus, we can reasonably expect that transfer-learning efficiency will decrease with increasing training-set size. On the other hand, with an increasing amount of training data, there is a decreasing need for transfer learning. Therefore, the transfer-learning strategy evaluated in this study may be useful for partially overcoming the challenge of deep learning with “small” datasets, when only a limited number of compounds have been tested for their potency at a drug target, or for in vivo studies where only a limited number of compounds can be assayed.

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Authors’ contributions All authors contributed to the study conception and design. Material preparation, data collection, computation, and analysis were performed by Ruifeng Liu and Srinivas Laxminarayan. The first draft of the manuscript was written by Anders Wallqvist and Ruifeng Liu. All authors commented on previous versions of the manuscript. All authors read and approved the final manuscript.

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Availability of data and materials All the data used in this study were downloaded from public repositories as described in the Molecular Activity Datasets Section. The web links to specific datasets are given in Table S1 in the Supplemental Materials. We generated the input features using Pipeline Pilot 18.1.100.11 (Dassault Systèmes, Vélizy-Villacoublay, France, an evaluation license is available from https://www.3ds.com/how-to-buy/contact-sales). For anyone interested in repeating the computations but having no access to Pipeline Pilot, we provided the input data generated from Pipeline Pilot in Supplementary Information. We performed all DNN studies using the open source Keras API in Tensorflow 2.1.0 available from https://www.tensorflow.org/. Our python code for transfer learning using a two-hidden layer neural network is provided in the Supplementary Information.

Declarations

Competing interests The authors declare no competing interests.

Consent for publication All authors have given consent for publication of the article. The opinions and assertions contained herein are the private views of the authors and are not to be construed as official or as reflecting the views of the U.S. Army, the U.S. Department of Defense, or The Henry M. Jackson Foundation for the Advancement of Military Medicine, Inc. This paper has been approved for public release with unlimited distribution.

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