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Dual-Polarized mm-Wave Endfire Chain-Slot Antenna for Mobile Devices

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Abstract—This article describes a dual-polarized endfire antenna array for millimeter-wave (mm-wave) frequencies. The antenna consists of a chain-slot-shaped pattern on a mobile phone metal frame. The antenna is fed using a transmission line, which would cause only a negligible capacitive loading of the sub-6 GHz antenna realized on the same metal frame and, therefore, would not significantly degrade its performance. This makes colocating the sub-6 GHz and mm-wave antennas in the same, shared volume possible. Measurements indicate that a four-element array placed within a mobile phone provides a realized gain between 8 and 12.6 dBi for both polarizations across the entire band from 24.5 to 29.5 GHz. The total efficiency of a single element is better than 2 and 3 dB for the whole band for horizontal and vertical polarizations, respectively.

Index Terms—5G, antenna, beamsteering, endfire antenna array, metallic rim, millimeter-wave (mm-wave) frequencies, mobile phone.

I. INTRODUCTION

FUTURE 5G mobile devices will use millimeter-wave (mm-wave) bands (such as those at 24–80 GHz) concurrently with the currently used sub-6 GHz bands for increased data rates [1]–[3]. However, many unresolved challenges remain, especially in mobile mm-wave antennas. First, the volume reserved for all the antennas in a mobile device is very limited, and the added mm-wave antennas should be ideally accommodated in the same shared volume with the sub-6 GHz antennas. Additional volume reserved for antennas would otherwise make the mobile device larger and bulkier and, thus, less attractive to customers. Currently, known mm-wave antennas either require additional volume or, if placed in the same volume, significant changes in the design of the sub-6 GHz antennas in order to avoid major performance degradation.

The mobile device can be in almost any orientation relative to the access point in its normal use, making electrical beam-steering necessary. The mm-wave antennas should additionally be dual-polarized for increased capacity and reliability. Commonly used mm-wave antennas realized on a printed circuit board (PCB) support radiation in the broadside directions of the mobile device [4]. However, they do not easily radiate toward the edges of the phone. Dual-polarized operation can also be relatively easily achieved in broadside direction using, for instance, dual-polarized patch antennas [5], [6]. On the other hand, dual-polarized antennas radiating toward the edges are much more demanding to implement with the commonly used PCB technology. This is, in particular, because the thickness of the PCB is small compared with the wavelength. Therefore, implementing antennas, such as dipoles or other radiating structures, where the electric field is perpendicular to the PCB is challenging.

The mm-wave antennas, similar to sub-6 GHz antennas, should be compliant with the phone design, and they should not introduce changes that result in significant degradations of the visual appearance, robustness, or manufacturability of the device. The majority of mobile devices currently have a metal frame surrounding the device for robustness and esthetic reasons. The metal frame makes directing mm-waves to edge directions very demanding, as any antenna placed inside the frame is obscured by the metal in the endfire direction.

The mm-wave (endfire) antennas have attracted a lot of attention recently [7]–[21]. However, the presented antennas generally have a relatively narrowband, or they operate only with a single polarization. Furthermore, the volume reserved for the mm-wave antenna may be relatively large [22], or the metal frame, which would heavily impact the performance of the antennas, is not included.

Other prior solutions are incompatible with sub-6 GHz antennas due to the very close proximity of the antennas to the metal frame, where the sub-6 GHz antennas are realized. Due to the close distance, the mm-wave antenna significantly loads the sub-6 GHz antennas, deteriorating its operation. Moreover, the mm-wave antenna may be impractical due to multiple gaps and slots needed in the metal frame, such as in [23]. The coexistence between long-term evolution (LTE) and mm-wave antennas in different environments has recently

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been studied in some article. Kurvinen et al. [24] combined LTE and mm-wave endfire operation, but the proposed antenna array only operates at a single polarization, and beamsteering capabilities are only demonstrated in the ±25° range. In [25], excellent efficiency is achieved in the 24.75–27.5 GHz band, but the metal frame is not included, and the beamsteering capabilities are not presented. In [26], good performance is achieved in the 26–28.5 GHz band, including high realized gain, but the mm-wave antennas present only single polarized broadside operation. In [27], a dual-polarized mm-wave antenna operating at 30 GHz is presented. In this solution, the mm-wave antenna is 1 mm offset from the metal frame, and thus, it is not integrated into it. Moreover, this solution requires the addition of a fairly large rectangular window in the metal frame in order to achieve an endfire radiation pattern, which may not be visually appealing.

In comparison with the previously presented antennas, the proposed design provides the following benefits.

1) Sub-6 GHz and mm-wave antennas can coexist in a shared volume without significant performance degradation in either of the antennas.
2) Shaping of the metal frame may be similar to current microphone/speakers grill slots, such as those shown in Fig. 1. This makes the design esthetically attractive and acceptable.
3) The antenna is integrated into the metal frame, and therefore, this solution is compatible with any metal-frame phone design.
4) The presented solution supports independent beamsteering at two polarizations.
5) This solution provides a large angular coverage range in the endfire direction, making it easy to achieve full-sphere coverage with complementing broadside antennas.
6) The presented solution makes possible feeding the mm-wave antenna elements on the metal frame from the main body without short-circuiting the metal frame or significantly loading it capacitively at sub-6 GHz frequencies.
7) The feeding can be realized on a simple PCB together with the mm-wave module and the mm-wave excitation elements coupling to the aperture.

This article presents an endfire mm-wave antenna array implemented in a metal-framed mobile phone structure. The mobile phone structure resembles the one of the modern smartphones where a metal frame is generally present, and the clearance between the frame and the main body is generally 1 mm. The mm-wave module is fed using feed lines that do not short-circuit the sub-6 GHz antennas implemented in the metal frame [28]. A prototype is manufactured, and the performance of each antenna is measured and compared with the corresponding simulated results in order to validate the presented antenna concept.

In Section II, we describe the mm-wave antenna concept and its corresponding feeding structure alongside with the main antenna dimensions. Section III presents the main considerations taken into account when manufacturing the prototype. Simulation and measurement results are analyzed and compared in Section IV. Parametric sweeps and explanations for the differences between measured and simulated results are included in Section V. Finally, conclusions are given in Section VI.

II. mm-Wave Chain-Slot Antenna Concept, Feeding Structure, and Low-Band Antenna

A. Chain-Slot Antenna Concept

The chain-slot antenna array consists of two main parts: a patterned slot in the metal frame and separate coupling elements for both polarizations. The pattern in the metal frame comprises multiple slots interlaced with each other, creating an aperture structure resembling a silhouette of a chain (see Fig. 2). Therefore, the antenna is referred to as a chain-slot antenna. The chain-like slot is patterned so that it supports structural resonance modes at two different polarizations, enabling the use of the slot as a dual-polarized antenna with proper feed structures. The feed elements can be realized on a PCB and are, therefore, relatively easy and inexpensive to manufacture. The chain-like patterned slot on the metal frame can be filled with a dielectric material, such as plastic, for robustness and sealing purposes.

Figs. 3 and 4 show the surface current and E-field distribution for the chain-slot concept at 28 GHz in a simplified
structure. This structure is fed with ideal lumped ports for simplicity. As seen in the figures, both horizontally and vertically polarized fields are generated when the structure is fed. In practice, coupling elements must be included in order to excite the desired modes. Moreover, the coupling elements exhibit another resonance, which leads to a double-resonance operation. The front view of the chain-slot antenna implemented on the metal frame of a mobile phone is shown in Fig. 5. The coupling elements for exciting the horizontal and vertical (H-Pol and V-Pol, respectively) polarizations are shown in Fig. 6. The vertical polarization is excited by creating a voltage difference across the narrow part of the chain-slot pattern with an extended signal line of a coplanar waveguide, whereas the horizontal polarization is excited using a monopole-shaped planar probe. The pattern repeats periodically depending on the number of the elements in the array, and one coupling element mainly excites one period of the slot pattern. The combination of the coupling element and the chain-slot aperture in the metal frame forms a multiresonant structure, enabling a wide impedance band. This solution is based on shaping the metal frame. Modern smartphones use the metal frame as a part of the sub-6 GHz antennas. However, the proposed shaping does not introduce gaps for the currents and has a very small effect on the performance of the sub-6 GHz antennas.

Fig. 7 shows the chain-slot concept implemented in a modern smartphone. The coupling elements may be fed from an RFIC 5G transceiver module placed near it. In addition, the battery or other element already present in the phone can be used as a back-reflector behind the slot to direct energy outwards. If this is not possible due to the phone layout, an additional reflector (e.g., a thin, vertically oriented metal sheet) can be used, as shown in Fig. 8. This reflector has been hidden in the previous figures for visualization purposes.

To simplify the manufacturing process of the antenna prototype, we realize both the unibody and the metal cover of the phone on the same PCB, supplemented with one additional 3-D-shaped metal part acting as a reflector. As shown in Fig. 9, both the bent model and the prototyped planar structure follow the same operational principle. The only difference between
both models is the direction of the radiation. Section III explains the prototype structure in more detail. The dimensions and results shown in Sections III–V of this article correspond to the planar, prototyped structure.

B. Feeding Structure for mm-Wave Antennas

One common way of realizing sub-6 GHz antennas on metal-frame phones is using capacitive coupling elements (CCEs) [29], where a part or section of the metal frame is used as the antenna element. It is important that the coupling element is separated from the main conductive body (ground) of the device with a gap. Generally, the larger the gap between the metal frame and the main body, the better the sub-6 GHz antenna performance (especially below 1 GHz [30]). The main drawback with currently known mm-wave antennas for metal-frame mobile devices is that they short-circuit the metal frame or significantly load the CCE capacitively. Capacitive loading effectively decreases the gap between the CCE antenna and the main body and, thus, degrades the operation of the antenna. In other solutions, such as in [31], the metal frame is galvanically shorted, which deteriorates the performance of the sub-6 GHz antenna. In [32], an mm-wave antenna integrated with a microstrip filter is presented. However, the coupled-line filter shorts the metal frame through the ground plane, thus altering the low-band antenna performance.

An mm-wave transmission line that introduces low common-mode capacitance not degrading sub-6 GHz antenna operation is presented in [28]. This transmission line does not significantly load the sub-6 GHz antennas and is, thus, called electrically invisible. The invisibility is achieved by minimizing the common-mode capacitance of the line, i.e., the capacitive loading between the metal frame and the main conductive body. In practice, the capacitance is minimized by introducing series capacitances or gaps in the transmission line, both in the signal and ground conductors in the case of an unbalanced line and on both conductors in the case of a balanced line. The larger the gaps, the smaller the common mode capacitance, and the less the line loads the sub-6 GHz antennas. The series capacitance at mm-wave frequencies is compensated with series or parallel inductances or both so that the mm-wave signal can propagate along the line without significant attenuation. The appropriate series inductances can be realized with short transmission line sections of approximately a quarter of the wavelength. Conventionally designed high-pass or bandpass filters are not suitable to deliver the mm-wave signal to the antenna element. This is because the filter theory considers the same wave mode for the pass and stop bands. In this case, a high-pass filter causes a high reflection of the differential mode propagating in the line. However, the differential mode is not as important as the sub-6 GHz antenna only experiences the common-mode loading due to the mm-wave feed line.

In the proposed design, we use the electrically invisible feed line that is presented, in detail, in [28]. Fig. 10 shows both the feeding structure and the mm-wave antenna array. The reflector that is hidden for visualization purposes in the previous figure is shown in Fig. 11.

III. Prototype Considerations

A prototype is manufactured to verify the concepts presented in Section II. For the sake of simplicity, the prototype is manufactured on a PCB of size 156 x 75 x 0.96 mm³. The required PCB consists of six metal layers and five substrate layers with different thicknesses and relative permittivities ranging between 3.12 and 3.35, as shown in Fig. 12. The core material has tan δ = 0.003, whereas the remaining dielectrics have tan δ = 0.002. The main chain-slot dimensions in Table I are for the dimensions in Fig. 10. The prototype consists of the connectors, the feeding lines (GCPW), the invisible feed lines, and the chain-slot antenna, as shown in Fig. 13. Due to the size of the connectors, they are placed in two rows on the PCB such that the H-pol connectors are placed closer
TABLE I

| Dimension | Description                           | Value (mm) |
|-----------|---------------------------------------|------------|
| $L_1$     | Metal-frame to ground-plane clearance | 1          |
| $L_2$     | Slot height                           | 5          |
| $L_3$     | Slot width                            | 2          |
| $L_4$     | Horizontal polarization coupler length| 2.2        |
| $L_5$     | Horizontal polarization coupler width | 0.3-0.6   |
| $L_6$     | Vertical polarization slot length     | 1.5        |
| $L_7$     | Vertical polarization coupler length  | 1.75       |
| $L_8$     | Vertical polarization coupler width   | 0.4        |
| $L_9$     | Inter-element spacing                 | 6          |
| $L_{10}$  | Invisible feedline module length      | 5          |
| $L_{11}$  | mm-wave antenna array length          | 26         |
| $L_{12}$  | Metal frame height                    | 6          |
| $L_{13}$  | mm-wave cut-out                       | 30         |

Fig. 12. PCB stack-up of the manufactured prototype.

Fig. 13. Prototyped PCB.

to the antenna. As shown in Fig. 13, an aluminum reflector is screwed to the metal frame at a distance of 1.2 mm from the antenna. Fig. 14 shows a close-up of the top part of the prototype, where the invisible feed lines and the H-pol and V-pol couplers are implemented.

Since the primary goal of the prototype is to verify that the proposed concept performs as expected, a planar structure is used, which greatly simplifies the manufacturing process. As a result, the radiated energy is directed toward the broadside of the PCB. The mm-wave feed lines and significant fields are between the thin copper layers N1–N3, and by using a flexible PCB, these feed lines could be bent, making the antenna radiate toward endfire direction.

The metal-frame shaping is done in layers N3–N6 of the PCB, and the different layers are interconnected using multiple vias, making its electrical behavior similar to that of a solid metal structure.

IV. mm-WAVE MEASUREMENT RESULTS

In order to evaluate the antenna and the invisible feed line performance, the losses in the connectors and transmission lines must be compensated. Therefore, the additional test board shown in Fig. 15 is manufactured. The test board allows us to determine the insertion loss at each port with great precision via transmission measurements.

Due to the available measurement setup, each antenna port is measured individually. The four-element array results have been obtained by combining the individually measured, port-specific radiation patterns computationally in MATLAB. The beamsteered array patterns have been calculated by adding a phase shift between the individually measured antenna patterns. All the results presented in this article have been loss-compensated with the reference plane located at the beginning of the invisible feed line. This way, the invisible feed lines are part of the studied antenna structure.

The 2.4 mm female compression mount connectors are used to feed each of the eight antennas. When measuring the performance of a single antenna element, the remaining ports are terminated in 50 Ω loads.

The measured and simulated reflection coefficients for horizontally and vertically polarized antennas are shown in Figs. 16 and 17, respectively. Matching levels are mostly below −10 dB for the simulated S-parameters in the 24.5–29.5 GHz range. However, the measured S-parameters present a frequency shift, and the matching levels achieved for the vertically polarized antennas are generally higher than those predicted by simulations. The possible reasons for these differences are explained in Section V. Both horizontally and vertically polarized arrays display dual-polarized operation
corresponding to the chain-slot and feeding-element modes. The coupling between differently polarized ports is $-15$ dB at worst and, generally, well below $-20$ dB.

Figs. 18 and 19 compare the simulated and measured total efficiencies for horizontal and vertical polarizations, respectively. The simulated efficiency is generally below the measured level. A possible reason for this would be an over compensation of the used surface roughness in the simulations ($0.6 \ \mu m$).

Fig. 20 shows the measured and simulated peak realized gain for the four-element arrays. Measured realized gain is above $8$ dBi for both polarizations, and the peaks are at $12.6$ and $12.3$ dBi for the vertical and horizontal polarizations, respectively. Fig. 21 shows the measured and combined 3-D boresight radiation patterns for the four-element arrays for the horizontal and vertical polarizations. Since 3-D coverage is a key feature in mm-wave antenna arrays, beamsteering capabilities are of crucial importance. Figs. 22 and 23 show the beamsteering capabilities of the four-element array at $28$ GHz. Beamsteering up to $\pm 50^\circ$ is possible with a scan loss below $3$ dB for horizontal polarization and $\pm 40^\circ$ for
vertical polarization. For the horizontal polarization, there is an almost perfect agreement between the simulated and measured beamsteering performance. The difference between the measured and simulated patterns when steering up to ±50° is due to the measurement setup, where part of the radiation was blocked when approaching the ±75° limit. Differences between the simulated and measured patterns for the vertical polarization are slightly more noticeable. The authors believe that this could be caused by the manual placement of the vias, which is explained in detail in Section V. The measured beamsteering capability at the edges of the operation band, i.e., at 24.5 and 29.5 GHz, is comparable to that shown at 28 GHz. However, the results are not shown for conciseness.

V. Analysis of Results and Tolerance Study

This section strives to explain the differences between the simulated and measured results, as well as provides indicators on how to recover from these differences in order to achieve the desired performance.

A. Horizontally Polarized Array

The simulated and measured results are generally in good agreement for the horizontally polarized antennas. Efficiency, realized gain, and beamsteering capabilities do not differ by more than 1 dB. However, there is a systematic 700 MHz frequency shift between the measured and simulated S-parameters. The frequency shift can be explained by a small change in the relative permittivities of the dielectrics used in the PCB. Moreover, Fig. 16 shows that the simulated efficiency is slightly lower than the measured one. This may indicate that the surface roughness used in simulations was slightly too high. Furthermore, decreasing the roughness contributes to the increase in the resonant frequency of the array. Fig. 24 shows the measured and simulated S-parameters for the horizontally polarized array when the permittivity of the dielectric is modified from the original 3.35 to 3.1 and the roughness from 0.6 to 0.1 μm. An almost perfect agreement between the resonant frequencies of the simulated and measured values is observed in this figure. Simulations show that the primary dimensions affecting the two resonances are the probe length (L₄ in Fig. 9) and the aperture dimensions (L₁ and L₂ in Fig. 9). Both the feeding elements and the chain-slot structures are strongly coupled, and therefore, modifying one of the two will affect both resonances.

B. Vertically Polarized Array

Evaluating the differences between the measured and simulated S-parameters for the vertically polarized antennas clearly indicates that there are more differences than just a simple frequency shift. While the frequency shift is still apparent here, the bandwidth and resonances achieved are different.

During the last part of the simulation phase, a via critical to the performance of the vertically polarized antennas was found (see Fig. 25). The diameter of this via had to be at least 0.5 mm. However, manufacturing reasons restricted the maximum diameter to 0.2 mm. This problem was solved by replacing the 0.2 mm via with a 0.5 mm through via by drilling...
Fig. 26. (a) Prototyped chain-slot antenna. (b) Modified version with shunt via added manually.

Fig. 27. Reflection coefficient of the chain-slot antenna for port P2 of the vertically polarized antennas for two via diameters.

Fig. 28. Reflection coefficient of the chain-slot antenna for port P2 of the vertically polarized antennas.

A 0.5 mm hole and then filling it with a silver-based PDS material. This process was done manually for each of the four vias, which results in increased uncertainty in the performance. Fig. 26 shows the initially prototyped PCB on the left and the later modified PCB with the added via on the right. Fig. 27 shows different performances achieved for two via diameters.

Fig. 28 shows a parametric sweep of the via location in the vertical direction. This sweep shows that the via location has a significant effect on the reflection coefficient level. Although the sweep shows the difference in performance when the via is misplaced in the vertical axis, a horizontal misalignment is also possible in reality. From the measurement results, we believe that the via corresponding to port P1 was the one done with the highest precision, followed by the ones in ports 2, 4, and, finally, 3. On the other hand, determining precisely how accurately the manually made vias were located is very difficult. However, the authors believe that this will not be a problem in a real product since the metal frame is made out of solid metal instead of vias.

Fig. 29 shows the S-parameters for the vertically polarized antennas when the permittivity and surface roughness values are adjusted to 3.1 and 0.1 µm, respectively. A rather good agreement is achieved for ports P1 and P2. For these results, the via size and location have not been modified with respect to the reference model. For these antennas, the main dimensions determining the resonances are the distance between the two poles of the chain slot (\(L_6\) in Fig. 9), the aperture dimensions (\(L_2\) and \(L_3\) in Fig. 9), and the V-pol probe dimensions (\(L_7\) and \(L_8\) in Fig. 9). Sometimes, the two resonances are so close to each other that they add up, showing as a single resonance.

C. Tolerance Analysis

In this section, we sweep the dimensions \(L_2\) and \(L_3\) (dimensions of one subslot) since they are the most relevant for both polarizations. Figs. 30 and 31 present the reflection coefficient for the middle port P2 for horizontal and vertical polarizations, respectively, and show how it varies with different dimensions. For the horizontal polarization, small changes in \(L_2\) result in a frequency offset in the resonant frequency, while more drastic changes also result in a detuned structure, deteriorating the reflection coefficient. \(L_3\) is also very critical for the
performance of this polarization, affecting the bandwidth and resonance level achieved. For the vertical polarization, $L_2$ seems to have an effect on the resonance frequency, while $L_3$ affects its strength (matching level). The dimensions $L_2$ and $L_3$ need to be chosen to provide the best tradeoff between the operations at both polarizations.

VI. CONCLUSION

This article presents a 5G mm-wave phased-array mobile-telephone antenna that is implemented in the metal frame. The dual-polarized operation with an efficiency higher than $-3\,\text{dB}$ in the 24.5–29.5 GHz range is demonstrated. The realized gain of the mm-wave array is above $8\,\text{dBi}$ over the entire frequency band. The beamsteering range of at least $\pm 40^\circ$ is possible with a scan loss below $3\,\text{dB}$. The mm-wave design shows not only excellent dual-polarized performance but also an appealing appearance to the users since the necessary modifications to current smartphones may be tolerable.

The presented antenna type, if placed on all the edges of the phone, could alone provide the necessary angular and polarization coverage in the 28 GHz band while being able to coexist with the LTE antennas. This makes the solution a very promising candidate for future mobile devices using the mm-wave bands.

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