SMOOTH GLOBAL SOLUTIONS FOR THE TWO DIMENSIONAL EULER POISSON SYSTEM

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Abstract. The Euler-Poisson system is a fundamental two-fluid model to describe the dynamics of the plasma consisting of compressible electrons and a uniform ion background. By using the dispersive Klein-Gordon effect, Guo first constructed a global smooth irrotational solution in the three-dimensional case. It has been conjectured that same results should hold in the two-dimensional case. The main difficulty in 2D comes from the slow dispersion of the linear flow and certain nonlocal resonant obstructions in the nonlinearity. In this paper we develop a new method to overcome these difficulties and construct smooth global solutions for the 2D Euler-Poisson system.

1. Introduction

The Euler-Poisson system is a fundamental two-fluid model used to describe the dynamics of a plasma consisting of moving electrons and ions. Since the heavy ions move much more slowly than the light electrons, one can treat them as two independent compressible fluids which only interact through their self-consistent electromagnetic fields. In the simplest approximation, the ions are immobile and uniformly distributed in space, providing only a background of positive charge for the electrons. Neglecting magnetic effects, the equations of motion describing the dynamics of the compressible electron fluid is then given by the following Euler-Poisson system in $(t,x) \in [0,\infty) \times \mathbb{R}^d$,

$$
\begin{align*}
\frac{\partial n}{\partial t} + \nabla \cdot (nu) &= 0, \\
m_e n (\partial_t u + (u \cdot \nabla) u) + \nabla p(n) &= en \nabla \phi, \\
\Delta \phi &= 4\pi e (n - n_0).
\end{align*}
$$

(1.1)

Here $n = n(t,x)$ and $u = u(t,x)$ denote the density and average velocities of the electrons respectively. The dimension $d$ will mostly be either $d = 3$ or $d = 2$ and we shall state clearly the dimensional dependence of the results. The state of the plasma is completely specified once the density and average velocities are known. It is useful to keep in mind that such a fluid model description is only accurate when the plasma velocity distribution is close to the Maxwell-Boltzmann distribution so that the microscopic details of each individual particles are averaged out. The symbol $e$ and $m_e$ denote the unit charge and mass of electrons. The first equation in (1.1) is simply the mass conservation law, while the second equation comes from the momentum balance. The pressure term $p(n)$ is assumed to obey the polytropic $\gamma$-law, i.e.

$$
p(n) = An^\gamma,
$$

(1.2)

where $A$ is a constant and $\gamma \geq 1$ is usually called the adiabatic index. The last equation in (1.1) is the Poisson equation (or Gauss law) which computes the electric
field self-consistently through the charge distribution. We assume here that at the
equilibrium the density of ions and electrons are both a constant denoted by \( n_0 \).
The dependence on ions only enter through the term \( 4\pi e(n - n_0) \) which is the net
charge generating the electric field. It is in this sense that the system (1.1) is the
simplest two-fluid model for plasmas since the ions are merely treated as constant
uniform sources. The natural boundary condition for the electric potential is a
decaying condition at infinity, i.e.
\[
\lim_{|x| \to \infty} \phi(t, x) = 0.
\] (1.3)
Throughout the rest of this paper, we shall consider an irrotational flow\(^1\) i.e.
\[
\nabla \times \mathbf{u} \equiv 0.
\] (1.4)
By a simple computation, it is easy to check that the irrotational condition is pre-
served for all time. The system (1.1)–(1.4) describes the dynamics of an irrotational
compressible Eulerian electronic fluid moving against the ionic forces.

Our main objective is to construct global in time smooth solutions for the Euler-
Poisson system. This is not an easy task since this is a hyperbolic conserva-
tion law with zero dissipation which has remain largely unsolved and no general theory is
available. The Euler-Poisson system has close connection with the well-known compres-
sible Euler equations. Indeed in (1.1) if the electric field term \( \nabla \phi \) is dropped,
one recovers the usual Euler equations for compressible fluids. In [14], Sideris con-
sidered the 3D compressible Euler equation for a classical polytropic ideal gas with
adiabatic index \( \gamma > 1 \). For a class of initial data which coincide with a constant
state outside a ball, he proved that the lifespan of the corresponding \( C^1 \) solution
must be finite. In [12] Rammaha extended this result to the 2D case. For
the Euler-Poisson system, Guo and Tahvildar-Zadeh [6] established a "Siderian"
blowup result for spherically symmetric initial data. Recently Chae and Tadmor
[2] proved finite-time blow-up for \( C^1 \) solutions of a class of pressureless attractive
Euler-Poisson equations in \( \mathbb{R}^n, n \geq 1 \). These negative results showed the abundance
of shock waves for large solutions.

The point of departure in the analysis of (1.1) from that of the compressible
Euler equations begins with understanding the small irrotational perturbations of
the equilibrium state \( n \equiv n_0, \mathbf{u} \equiv 0 \). For the 3D compressible Euler equation with
irrotational initial data \( (n, \mathbf{u}) = (\rho + n_0, \mathbf{v}), \) where \( \rho \in S(\mathbb{R}^3), \mathbf{v} \in S(\mathbb{R}^3) \)\( ^3 \ S(\mathbb{R}^3) \) is the usual Schwartz
space), Sideris [14] proved that the lifespan of the classical solution \( T_\epsilon > \exp(C/\epsilon) \). For the upper bound it follows from his previous paper
[14] that \( T_\epsilon < \exp(C/\epsilon^2) \) under some mild conditions on the initial data. Sharper
results are also available. For initial data which is spherically symmetric and is
smooth compact \( \epsilon \)-perturbation of the constant state, Godin [4] obtained by using
a suitable approximation solution the precise asymptotic of the lifespan \( T_\epsilon \) as
\[
\lim_{\epsilon \to 0} \epsilon \log T_\epsilon = T^*,
\]
where \( T^* \) is a constant. These results rely crucially on the observation that after
some simple manipulations, the compressible Euler equation in rescaled variables
is given by a vectorial nonlinear wave equation with pure quadratic nonlinearities.
The linear part of the wave equation decays at most at the speed \( t^{-(d-1)/2} \) which in

\(^1\)In the two dimensional case, one can regard in the usual fashi on \( \mathbf{u} = (u_1, u_2, 0) \), for which
the condition \( \nabla \times \mathbf{u} \equiv 0 \) simplifies to \( \partial_{x_1} u_2 - \partial_{x_2} u_1 \).
3D case is not integrable. Unless some additional structure e.g. the null condition \[ [1, 9] \] is imposed on the nonlinearity, one cannot in general expect global existence of small solutions. For the Euler-Poisson system \([1.1] \), the situation for small irrotational perturbations of the equilibrium state is quite different. By a straightforward computation, the linear part of the Euler-Poisson system for irrotational flows has the form

\[
\begin{align*}
\partial_{tt} n - \frac{1}{m_e} p'(n_0) \Delta n + \omega_p^2 n &= 0, \\
\partial_{tt} u - \frac{1}{m_e} p'(n_0) \Delta u + \omega_p^2 u &= 0.
\end{align*}
\]

Here \( \omega_p = \sqrt{4\pi e^2 n_0/m_e} \) is so called plasma frequency. This new term \( \omega_p^2 \) which is absent in the pure Euler case makes the linear part of the Euler-Poisson system into a Klein-Gordon system for which the linear solutions have an enhanced decay of \( (1 + t)^{-d/2} \). This is in sharp contrast with the pure Euler case for which the decay is only \( t^{-(d-1)/2} \). Note that in \( d = 3 \), \( (1 + t)^{-d/2} = (1 + t)^{-3/2} \) which is integrable in \( t \). In a remarkable paper \([5]\), by exploiting the crucial decay property of the Klein-Gordon flow in 3D, Guo \([5]\) modified Shatah’s normal form method \([13]\) and constructed a smooth irrotational global solution to \([1.1]\) around the equilibrium state \((n_0, 0)\) for which the perturbations decay at a rate \( C_p (1 + t)^{-p} \) for any \( 1 < p < 3/2 \) (here \( C_p \) denotes a constant depending on the parameter \( p \)). Note in particular that the sharp decay \( t^{-3/2} \) is marginally missed here due to a technical complication, namely in employing one of the \( L^p \to L^\infty \) decay estimates, the nonlinear term has a Riesz-type singular operator in the front and one is forced to take \( p > 1 \) in bounding the corresponding part.

As was already mentioned, the purpose of this paper is to construct smooth global solutions to \([1.1]\) for the two-dimensional case. One can already sense a bit that this situation is more challenging than the \( d = 3 \) case since the linear solutions to the Klein-Gordon system in \( d = 2 \) decays only at \( (1 + t)^{-1} \) which is not integrable, in particular making the strategy in \([5]\) difficult to apply. As we shall see shortly, the Euler-Poisson system after writing in terms of the perturbed variables can be recast into a quasi-linear Klein-Gordon system with nonlocal nonlinearities. To understand and spell out the main difficulties associated with the analysis of this nonlocal quasi-linear Klein-Gordon system, we first review some known results on nonlinear Klein-Gordon equations. For general scalar quasi-linear Klein-Gordon equations in 3D with quadratic type nonlinearities, global small smooth solutions were constructed independently by Klainerman \([8]\) using the invariant vector field method and Shatah \([13]\) using a normal form method. There are essential technical difficulties to employ Klainerman’s invariant vector field method to the Klein-Gordon system associated with \([1.1]\). Namely after reformulating in terms of perturbed the variables, the nonlinear part of the system \([1.1]\) has a Riesz type nonlocal term which comes from solving the Poisson equation for the electric field in \([1.1]\), i.e. a term of the form

\[ (-\Delta)^{-1} \partial_x \partial_x (\text{quadratic terms}). \]

The Klainerman invariant vector fields consist of infinitesimal generators which commute well with the linear operator \( \partial_{tt} - \Delta + 1 \). The most problematic part comes from the Lorentz boost \( \Omega_{ij} = t \partial_x - x \partial_t \). Whilst the first part \( t \partial_x \) commutes naturally with the Riesz operator \( R_{ij} = (-\Delta)^{-1} \partial_x \partial_x \), the second part \( x \partial_t \)
interacts rather badly with $R_{ij}$ and produces a commutator which scales as

$$[x_j \partial_t, R_{ij}] \sim \partial_t |\nabla|^{-1}.$$ 

After repeated commutation of these operators one obtain in general terms of the form $|\nabla|^{-N}$ which makes the low frequency part of the solution out of control. It is for this reason that in 3D case Guo [5] adopted Shatah’s method of normal form in $L^p$ ($p > 1$) setting for which the Riesz term $R_{ij}$ causes no trouble. We turn now to the 2D Klein-Gordon equations with pure quadratic nonlinearities. In this case, direct applications of either Klainerman’s invariant vector field method or Shatah’s normal form method are not possible since the linear solutions only decay at a speed of $(1 + t)^{-1}$ which is not integrable and makes the quadratic nonlinearity quite resonant. In [16], Simon and Taflin constructed wave operators for the 2D semilinear Klein-Gordon system with quadratic nonlinearities. In [11], Ozawa, Tsutaya and Tsutsumi considered the Cauchy problem and constructed smooth global solutions by first transforming the quadratic nonlinearity into a cubic one using Shatah’s normal form method and then applying Klainerman’s invariant vector field method to obtain decay of intermediate norms. Due to the nonlocal complication with the Lorentz boost which we explained earlier, this approach seems difficult to apply in the 2D Euler-Poisson system.

Our approach in this paper is inspired by the recent work of Gustafson, Nakanishi and Tsai [3] on the Gross-Pitaevskii equation of the form

$$i\partial_t \psi = -\Delta \psi + (|\psi|^2 - 1) \psi,$$

where $\psi : \mathbb{R}^{1+d} \to \mathbb{C}$ is solved with the boundary condition

$$|\psi(t,x)| \to 1, \quad \text{as} \quad |x| \to \infty.$$ 

The main objective in [3] is to investigate large time behavior of solutions $\psi = 1 + \text{“small”}$. It is then natural to look at the perturbation $u = \psi - 1$ which satisfies the equation

$$i\partial_t u + \Delta u - 2Re(u) = F(u), \quad F(u) := u^2 + 2|u|^2 + |u|^2 u. \quad (1.5)$$

To make the problem complex linear, introduce change of variable

$$v = Ku := \sqrt{(-\Delta)^{-1}(2 - \Delta)}Re(u) + iIm(u).$$

Then for $v$ the equation takes the form

$$i\partial_t v - \sqrt{(-\Delta)(2 - \Delta)}v = -iK_iF(K^{-1}v). \quad (1.6)$$

In [3], Gustafson, Nakanishi and Tsai considered the final data problem for (1.6) (i.e. Cauchy data at $t = \infty$),

$$v(t) = e^{-i\sqrt{-\Delta(2 - \Delta)}t} \phi + \int_0^\infty e^{-i\sqrt{-\Delta(2 - \Delta)(t-s)}}K_iF(K^{-1}v(s))ds,$$

where $\phi$ is the final data. Under some decay and smallness assumptions on $\phi$, they constructed a unique global solution for (1.6) in dimensions $d = 2, 3$. In particular for $d = 2$, the solutions has a decay

$$\|v(t) - e^{-i\sqrt{-\Delta(2 - \Delta)t}} \phi\|_{\dot{H}^1} \leq C_* t^{-1+\epsilon}, \quad (1.7)$$
for any \( \epsilon \in (0, 1) \) and \( C_\epsilon \) is a constant depending on \( \epsilon \). Note that this marginally misses the sharp decay \( t^{-1} \) due to some technical issues which we explain now. The first step in \([4]\) is to estimate the first nonlinear iterate, i.e.

\[
z_1(t) = \int_t^\infty e^{-i\sqrt{-\Delta(2-\Delta)}}(t-s)K_1 F(K^{-1}_1 v_1(s))ds,
\]

where

\[
v_1(t) = e^{-i\sqrt{-\Delta(2-\Delta)}}t\phi
\]

is simply the linear solution. By a careful space-time phase estimate (see Lemma 4.1 in \([3]\)), the authors showed that

\[
\|z_1(t)\|_{\dot{H}^1} \lesssim t^{-1} (\log t)^2, \quad t \geq 2,
\]

here we suppressed the dependence on the final data \( \phi \). The logarithm part of \( t \) comes mainly from certainly degeneracies of the phase near \( \xi = 0 \). Since the nonlinearity is quadratic, one immediately observe that due to this logarithm loss we cannot close the simple \( \dot{H}^1 \) estimates for further iterates (in fact there also some problems with low frequencies which we shall not dwell further here). To remedy this problem, Gustafson, Nakanishi and Tsai then introduced a novel normal form for the original equation written in the function \( u \) (see \((1.5)\))

\[
w = u + P_{\leq 1}(\|u\|^2/2),
\]

where \( P_{\leq 1} \) is the usual Littlewood-Paley projector localized to frequency \( |\xi| \leq 1 \). After this transformation and using Strichartz estimates together with a fixed point argument, the authors were able to settle for this logarithmic loss and obtain the existence of global solutions, in particular establishing \((1.7)\).

Our analysis of the Euler-Poisson system starts with sharpening the analysis of the Gross-Pitaevskii equation in 2D. In \([10]\), the second author of this paper observed that provided with some suitable transform and choosing a good working space, one can remove the epsilon in \((1.7)\), in particular obtaining the sharp decay \( 1/t \) in 2D. A key observation in this work is that one should obtain the critical \( 1/t \) decay in the energy estimates of the first nonlinear estimate, and after that only energy estimates are needed (in particular, no Strichartz estimates are needed!). This intuition is further arrested in our subsequent work \([7]\), where we revisited the classical semilinear Klein-Gordon equations in 2D with quadratic nonlinearity and also semilinear wave equations in 3D with a quadratic nonlinearity satisfying the null condition. Note that in both cases the linear solution decay at the critical speed \( 1/t \) for which the quadratic nonlinearity is resonant. In that work we constructed wave operators for the final data problem and obtain the sharp decay of the nonlinear part of the solution. As a byproduct of our analysis in \([7]\), one can reinforce the notion of the null condition as an annihilation condition on the quadratic interaction of linear solutions.

In this work, we take the point of view that the Euler-Poisson system is a quasi-linear Klein-Gordon system with nonlocal quadratic nonlinearities. We shall construct smooth global solutions to this system by solving the final data problem (i.e constructing the wave operators). As is well-known with quasilinear systems, the Strichartz estimates will suffer loss of derivatives unless one considers energy estimates. We shall resolve this difficulty by performing a delicate localization in time argument. This localization is only carried out for the part of the solution which has no resonances and only for the corresponding quasi-linear part of the
nonlinearity. We then introduce a new iteration scheme to construct the solution as a uniform limit of iterates. The crucial point in the iteration step is to obtain a priori uniform sharp decay estimates of $H^m$ norms of the nonresonant part of the solution. This is done by a delicate bootstrap argument. We should stress that our new iteration scheme is quite robust and should have applications to many other systems for which the nonlinearity is resonant. To better illustrate our technique, we summarize below the main steps of the proof.

**Step 1.** Reformulation. For simplicity set all physical constants $e, m_e, 4\pi$ and $A$ to be one. To simplify the presentation, we also set $\gamma = 3$. Define the rescaled functions

\[
\begin{align*}
    u(t, x) &= n(t/c_0, x) - n_0, \\
    v(t, x) &= \frac{1}{c_0} u(t/c_0, x),
\end{align*}
\]

where the sound speed is $c_0 = \sqrt{3}n_0$. For simplicity we shall set $n_0 = 1/3$ so that the characteristic wave speed is unity. Then in terms of the new functions $(u, v)$, the Euler-Poisson system (1.1)–(1.4) takes the form

\[
\begin{cases}
    (\Box + 1)u = \nabla \cdot \left( (v \cdot \nabla)v + u \nabla u \right) - \partial_t \left( v \cdot \nabla u + u \nabla v \right) \\
    (\Box + 1)v = \nabla \cdot \left( (v \cdot \nabla)u + u \nabla v \right) - \partial_t \left( v \cdot \nabla v + u \nabla u \right) - \nabla \Delta^{-1} \nabla \cdot (uv),
\end{cases}
\]

or in a more compact notation

\[
\begin{cases}
    (\Box + 1)u = G_1(u, v) \\
    (\Box + 1)v = G_2(u, v).
\end{cases}
\]

**Step 2.** Remove resonances and fine decomposition of the solution. Define linear solutions according to (3.1)–(3.2). We then identify the resonant part of the solution corresponding to the quadratic interaction of the linear solutions. This is done by solving the system (see (3.5)–(3.6))

\[
\begin{cases}
    (\Box + 1)\Phi_1 = G_1(h_1, h_2), \\
    (\Box + 1)\Phi_2 = G_2(h_1, h_2)
\end{cases}
\]

with a decaying condition at $t = \infty$. We then decompose the solution as

\[
\begin{align*}
    u &= \bar{u} + h_1 + \Phi_1, \\
    v &= \bar{v} + h_2 + \Phi_2.
\end{align*}
\]

The new variable $(\bar{u}, \bar{v})$ no longer contains resonances and satisfy

\[
\begin{cases}
    (\Box + 1)\bar{u} = \tilde{G}_1(\bar{u}, \bar{v}, h, \Phi), \\
    (\Box + 1)\bar{v} = \tilde{G}_2(\bar{u}, \bar{v}, h, \Phi),
\end{cases}
\]

where $\tilde{G}_1, \tilde{G}_2$ are corresponding new nonlinearities.

**Step 3.** Sharp decay estimates for $h_1, h_2$ and the resonances $\Phi_1, \Phi_2$. In this step we perform a careful space-time analysis of the bilinear integral for $\Phi_1, \Phi_2$. Note that the $L^\infty$ norms of the source terms $h_1, h_2$ decay as $1/t$ which is a standard $L^1 - L^\infty$ estimate. The crucial point in our analysis is to establish sharp $1/t$ decay of $H^m$ norms of $\Phi_1, \Phi_2$. This is needed later for the iteration step.
Step 4. Localization in time and definition of the iteration scheme. Let \( \chi \in C^\infty_c(\mathbb{R}) \) be such that \( \chi(t) = 1 \) for \( 0 \leq t \leq 1 \) and \( \chi(t) = 0 \) for \( t \geq 2 \). For integers \( n \geq 0 \), define
\[
\chi_n(t) = \chi(2^{-n} t).
\]
Observe that \( \chi_n \) is localized to the regime \( t \lesssim 2^n \). Let \( \bar{u}^{(0)} = 0 \), \( \bar{v}^{(0)} = 0 \). For \( n \geq 1 \) inductively define
\[
\begin{aligned}
(\Box + 1)\bar{u}^{(n)} &= \chi_n(t)(\tilde{G}_{11}(\bar{u}^{(n)}, \cdot) + \tilde{G}_{12}(\bar{v}^{(n)}, \cdot)) + \tilde{G}_{13}(\bar{u}^{(n-1)}, \bar{v}^{(n-1)}, h, \Phi), \\
(\Box + 1)\bar{v}^{(n)} &= \chi_n(t)(\tilde{G}_{21}(\bar{v}^{(n)}, \cdot) + \tilde{G}_{22}(\bar{v}^{(n)}, \cdot)) + \tilde{G}_{23}(\bar{u}^{(n-1)}, \bar{v}^{(n-1)}, h, \Phi).
\end{aligned}
\]
Here \( \tilde{G}_{11}, \tilde{G}_{12} \) denote the quasi-linear part of the nonlinearity in \( \tilde{G}_1 \). Similar convention applies to \( \tilde{G}_2 \) (see (3.10)–(3.11) for more details). Note that the time localization is only applied in the quasi-linear part of the nonlinearity containing only the interactions of the non-resonant part of the solution.

Step 5. Solvability of the iteration system and non-uniform energy estimates. The solvability of the iteration system is not immediately obvious, due to the quasi-linear nature of the problem. In this respect our strategy is to take advantage of the smooth time cutoff function \( \chi_n(t) \) which vanishes for \( t \geq 2^{n+1} \). In the large time regime \( t \geq 2^{n+1} \), the nonlinearity of the iteration system does not contain \( (\bar{u}^{(n)}, \bar{v}^{(n)}) \) and we can solve for all \( t \geq 2^{n+1} \) by using the fundamental solution with source term depending only on the previous iteration \( (\bar{u}^{(n-1)}, \bar{v}^{(n-1)}) \). After this is done we solve backwards the same system for \( t \leq 2^{n+1} \) with initial data \( (\bar{u}^{(n)}(2^n), \bar{v}^{(n)}(2^n)) \). We then perform an energy estimate. Denote
\[
A_k(t) = \|\bar{u}^{(k)}(t)\|_{H^m} + \|\bar{u}^{(k)}(t)'\|_{H^m} + \|\bar{v}^{(k)}(t)\|_{H^m} + \|\bar{v}^{(k)}(t)'\|_{H^m}, \quad \forall k \geq 0.
\]
Our inductive hypothesis is that
\[
A_{n-1}(t) \leq \frac{\epsilon}{\langle t \rangle}, \quad \forall t \geq 0.
\]
Here \( \langle t \rangle = \sqrt{1 + t^2} \) is the usual Japanese bracket notation. We then use a crude energy estimate to obtain
\[
A_n(t) \leq \frac{K_n \epsilon}{\langle t \rangle},
\]
where \( K_n \) is a constant depending on the iteration \( n \). This dependence on the iteration number \( n \) comes from the part where we solve the iteration system backwards for \( t \leq 2^{n+1} \).

Step 6. Bootstrap and contraction. In this step we upgrade the estimate on \( A_n \) and remove the dependence on \( n \). This is done by an infinite-time Gronwall argument (see Lemma 6.4.1), which rests on the intuition that nonlinear decay is dictated by the sharp decay of the source terms. After obtaining the uniform energy estimate and closing the induction hypothesis, we perform the usual contraction argument. There is one more small twist in the argument, namely we have to first show the strong contraction with a weak time decay \( \langle t \rangle^{-1/2} \), but this is enough to extract the limiting solution since the true decay \( \langle t \rangle^{-1} \) from the iterates can be passed to the limit for any finite \( t \).
Organization of the paper. In section 2 we give the reformulation of the 2D Euler-Poisson system and state the main results. In section 3 we extract the non-resonant part of the solution and introduce the iteration scheme. Section 4 is devoted to the estimates of the resonant part of the solution. In section 5 we prove solvability of the iteration system and establish some non-uniform energy decay estimates. In section 6 we upgrade the decay estimate of the iterates and establish uniform in time energy estimates. In the last section 7 we perform a contraction argument and prove the existence and uniqueness of the desired classical solution.

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2. Reformulation and main results

We first transform the system (1.1)–(1.4) in terms of certain perturbed variables. For simplicity set all physical constants $e, m_e, 4\pi$ and $A$ to be one. To simplify the presentation, we also set $\gamma = 3$ although other cases of $\gamma$ can be easily included in the discussion. Define the rescaled functions

$$u(t, x) = \frac{n(t/c_0, x) - n_0}{n_0},$$
$$v(t, x) = \frac{1}{c_0} u(t/c_0, x),$$
$$\psi(t, x) = \phi(t/c_0, x),$$

where the sound speed is $c_0 = \sqrt{3}n_0$. For simplicity we shall set $n_0 = 1/3$ so that the characteristic wave speed is unity. The Euler-poisson system (1.1)–(1.4) in new variables take the form

$$\begin{align*}
\partial_t u + \nabla \cdot v + v \cdot \nabla u + u \nabla \cdot v &= 0, \\
\partial_t v + \nabla u + (v \cdot \nabla) v + u \nabla u &= 3 \nabla \psi, \\
\partial_t \nabla \psi &= -\frac{1}{2} v - \frac{1}{3} \nabla \Delta^{-1} \nabla \cdot (u v), \\
\Delta \psi &= \frac{1}{3} u.
\end{align*}$$

(2.1)

To simplify the discussion later, it is useful to denote the system as

$$\begin{align*}
(\Box + 1) u &= G_1(u, v) \\
(\Box + 1) v &= G_2(u, v).
\end{align*}$$

(2.2)
In Duhamel formulation, we write
\[
\begin{align*}
(\vec{u}(t) & ) \\
(\vec{v}(t) & )
\end{align*}
& = \cos(t-T)\langle \nabla \rangle \begin{pmatrix} u(T) \\ v(T) \end{pmatrix} + \sin(t-T)\langle \nabla \rangle \begin{pmatrix} u_t(T) \\ v_t(T) \end{pmatrix} \\
& + \int_T^t \sin(t-s)\langle \nabla \rangle \begin{pmatrix} G_1(u, v)(s) \\ G_2(u, v)(s) \end{pmatrix} ds.
\]

Note that
\[
\begin{align*}
\cos(t-T)\langle \nabla \rangle & = \cos t\langle \nabla \rangle \cos T\langle \nabla \rangle + \sin t\langle \nabla \rangle \sin T\langle \nabla \rangle \\
\sin(t-T)\langle \nabla \rangle & = \sin t\langle \nabla \rangle \cos T\langle \nabla \rangle - \cos t\langle \nabla \rangle \sin T\langle \nabla \rangle.
\end{align*}
\]

Therefore
\[
\begin{align*}
\begin{pmatrix} u(t) \\ v(t) \end{pmatrix} & = \cos t\langle \nabla \rangle \begin{pmatrix} u(T) \\ v(T) \end{pmatrix} - \sin T\langle \nabla \rangle \begin{pmatrix} u_t(T) \\ v_t(T) \end{pmatrix} \end{align*}
\]
(2.3)

\[
\begin{align*}
\begin{pmatrix} u(t) \\ v(t) \end{pmatrix} & + \frac{\sin t\langle \nabla \rangle}{\langle \nabla \rangle} \begin{pmatrix} \langle \nabla \rangle \sin T\langle \nabla \rangle \begin{pmatrix} u(T) \\ v(T) \end{pmatrix} + \cos T\langle \nabla \rangle \begin{pmatrix} u_t(T) \\ v_t(T) \end{pmatrix} \end{pmatrix} \\
& + \int_T^t \frac{\sin(t-s)\langle \nabla \rangle}{\langle \nabla \rangle} \begin{pmatrix} G_1(u, v)(s) \\ G_2(u, v)(s) \end{pmatrix} ds.
\end{align*}
\]
(2.5)

Consider the linear flow generated by the homogeneous equation
\[
\begin{align*}
\begin{cases}
(\square + 1)\vec{u} = 0 \\
(\square + 1)\vec{v} = 0
\end{cases}
\end{align*}
\]
with initial data
\[
\begin{align*}
\begin{pmatrix} \vec{u}(0) \\ \vec{v}(0) \end{pmatrix} & = \begin{pmatrix} \vec{u}_0 \\ \vec{v}_0 \end{pmatrix}, \quad \begin{pmatrix} \vec{u}_t(0) \\ \vec{v}_t(0) \end{pmatrix} = \begin{pmatrix} \vec{u}_1 \\ \vec{v}_1 \end{pmatrix}.
\end{align*}
\]

It is not difficult to check that
\[
\begin{align*}
\begin{pmatrix} \vec{u}(t) \\ \vec{u}_t(t) \end{pmatrix} & = \begin{pmatrix} \cos t\langle \nabla \rangle & \sin t\langle \nabla \rangle \\ -\langle \nabla \rangle \sin t\langle \nabla \rangle & \cos t\langle \nabla \rangle \end{pmatrix} \begin{pmatrix} \vec{u}_0 \\ \vec{u}_1 \end{pmatrix}
\end{align*}
\]
and similarly
\[
\begin{align*}
\begin{pmatrix} \vec{v}(t) \\ \vec{v}_t(t) \end{pmatrix} & = \begin{pmatrix} \cos t\langle \nabla \rangle & \sin t\langle \nabla \rangle \\ -\langle \nabla \rangle \sin t\langle \nabla \rangle & \cos t\langle \nabla \rangle \end{pmatrix} \begin{pmatrix} \vec{v}_0 \\ \vec{v}_1 \end{pmatrix}.
\end{align*}
\]

Write the linear flow propagator
\[
S(t) = \begin{pmatrix} \cos t\langle \nabla \rangle & \sin t\langle \nabla \rangle \\ -\langle \nabla \rangle \sin t\langle \nabla \rangle & \cos t\langle \nabla \rangle \end{pmatrix}.
\]

For given data \((f_1, g_1), (f_2, g_2)\), the wave operator problem for (2.1) amounts to finding the nonlinear solution \((\vec{u}(t), \vec{v}(t))\) such that
\[
\begin{align*}
S(-T) \begin{pmatrix} u(T) \\ u_t(T) \end{pmatrix} & \rightarrow \begin{pmatrix} f_1 \\ g_1 \end{pmatrix}, \\
S(-T) \begin{pmatrix} \vec{v}(T) \\ \vec{v}_t(T) \end{pmatrix} & \rightarrow \begin{pmatrix} f_2 \\ g_2 \end{pmatrix}, \quad \text{as } T \rightarrow \infty.
\end{align*}
\]
The convergence here takes place in some Sobolev space $H^m$ which will become clear later. Plugging (2.6), (2.7) into (2.3), (2.4), we get
\[
\left( u(t) \right)_{v(t)} = \cos t \langle \nabla \rangle \left( f_1 f_2 \right) + \sin t \langle \nabla \rangle \left( g_1 g_2 \right) + \int_{t}^{\infty} \sin(t - s) \langle \nabla \rangle \left( G_1(u,v)(s) \right) G_2(u,v)(s) ds. \tag{2.8}
\]

The system (2.8) will be our main object of study. Here is our theorem.

**Theorem 2.1.** Let $m \geq 0$ be an integer. Let $(f_0^1, f_0^2), (g_0^1, g_0^2)$ be given functions such that
\[
\sup_{\xi \in \mathbb{R}^2} \langle \xi \rangle^{m + 24} \sum_{|\alpha| \leq 2}^{2} |\partial_\xi^\alpha f_0^i(\xi)| + \sum_{|\alpha| \leq 2}^{2} |\partial_\xi^\alpha g_0^i(\xi)| < \infty, \tag{2.9}
\]
where $\hat{f}_0^i, \hat{g}_0^i$ are their Fourier transforms. Let
\[
\left( f_1 f_2 \right) = \epsilon \left( f_0^1 f_0^2 \right), \quad \left( g_1 g_2 \right) = \epsilon \left( g_0^1 g_0^2 \right). \]

Then there exists $\epsilon_0 > 0$, such that for any $0 < \epsilon < \epsilon_0$, there exists a unique global solution to (2.8) written in the form
\[
\left( u(t) \right)_{v(t)} = \cos t \langle \nabla \rangle \left( f_1 f_2 \right) + \sin t \langle \nabla \rangle \left( g_1 g_2 \right) + \left( z_1(t) \right)_{z_2(t)}, \]
where $(z_1(t), z_2(t)) \in H^m$, and
\[
\sup_{t \geq 0} (\|z_1(t)\|_{H^m} + \|z_2(t)\|_{H^m}) \lesssim \epsilon.
\]

**Remark 2.2.** Certainly the global solution for (2.8) is also a global solution for (2.1). Our constructed solutions scatters in the $H^m$ space at the optimal speed $1/t$, i.e.
\[
\left\| \left( u(t) \right)_{v(t)} - \cos t \langle \nabla \rangle \left( f_1 f_2 \right) + \sin t \langle \nabla \rangle \left( g_1 g_2 \right) \right\|_{H^m} \lesssim \frac{1}{t}, \quad \forall t \geq 0.
\]

Our method of proof also works for the 3D case. In that case we can obtain optimal decay $t^{-3/2}$.

**Remark 2.3.** To simplify the presentation, we do not make attempt to optimize the decay assumption (2.9) on the final data $(f_1, g_1, f_2, g_2)$. More refined estimates can weaken the assumption (2.9) significantly. However we shall not pursue this matter here.

### 3. Reduction of the Problem and the Iteration Scheme

Define the linear solutions
\[
h_1(t) = \cos t \langle \nabla \rangle f_1 + \sin t \langle \nabla \rangle g_1, \tag{3.1}
\]
\[
h_2(t) = \cos t \langle \nabla \rangle f_2 + \sin t \langle \nabla \rangle g_2. \tag{3.2}
\]
Let
\[
\begin{align*}
u^{(1)} &= u - h_1, \\
v^{(1)} &= v - h_2.
\end{align*}
\]
For \((u^{(1)}, v^{(1)})\) we have the system
\[
(\Box + 1)u^{(1)} = \nabla \cdot \left( (v \cdot \nabla)(v^{(1)} + h_2) + u \nabla (u^{(1)} + h_1) \right) \\
- \partial_t \left( (v \cdot \nabla)(u^{(1)} + h_1) + u \nabla \cdot (v^{(1)} + h_2) \right) 
\]  
(3.3)
\[
(\Box + 1)v^{(1)} = \nabla \left( (v \cdot \nabla)(u^{(1)} + h_1) + u \nabla \cdot (v^{(1)} + h_2) \right) \\
- \partial_t \left( (v \cdot \nabla)(v^{(1)} + h_2) + u \nabla (u^{(1)} + h_1) \right) \\
- \nabla \Delta^{-1} \nabla (uv). 
\]  
(3.4)
The RHS of (3.3)–(3.4) still contains quadratic source terms due to the self interaction of the linear solution \((h_1, h_2)\). To remove resonances created by these sources, we further define
\[
\Phi_1 = \int_t^\infty \frac{\sin(t-s)(\nabla)}{\langle \nabla \rangle} G_1(h_1, h_2)(s) ds, 
\]  
(3.5)
\[
\Phi_2 = \int_t^\infty \frac{\sin(t-s)(\nabla)}{\langle \nabla \rangle} G_2(h_1, h_2)(s) ds. 
\]  
(3.6)
It is clear that
\[
(\Box + 1)\Phi_1 = G_1(h_1, h_2), 
\]
\[
(\Box + 1)\Phi_2 = G_2(h_1, h_2). 
\]
Also we have the estimate
\[
\|\Phi_1(t)\|_{H^k} + \|\Phi_1(t)\|_{H^k} + \|\Phi_2(t)\|_{H^k} + \|\Phi_2(t)\|_{H^k} \lesssim \frac{2}{\langle t \rangle}. 
\]
We then introduce one more change of variables and define
\[
\bar{u} = u^{(1)} - \Phi_1 = u - h_1 - \Phi_1, 
\]
\[
\bar{v} = v^{(1)} - \Phi_2 = v - h_2 - \Phi_2. 
\]
For the new variables \((\bar{u}, \bar{v})\), we have the system
\[
(\Box + 1)\bar{u} = \nabla \cdot \left( (v \cdot \nabla)(\bar{v} + \Phi_2) + u \nabla (\bar{u} + \Phi_1) \right) \\
- \partial_t \left( (v \cdot \nabla)(\bar{u} + \Phi_1) + u \nabla \cdot (\bar{v} + \Phi_2) \right) \\
+ \nabla \cdot \left( ((\bar{v} + \Phi_2) \cdot \nabla)h_2 + (\bar{u} + \Phi_1) \nabla h_1 \right) \\
- \partial_t \left( ((\bar{v} + \Phi_2) \cdot \nabla)h_1 + (\bar{u} + \Phi_1) \nabla \cdot h_2 \right), 
\]  
(3.7)
\[
(\Box + 1)\bar{v} = \nabla \left( (v \cdot \nabla)(\bar{u} + \Phi_1) + u \nabla \cdot (\bar{v} + \Phi_2) \right) \\
- \partial_t \left( (v \cdot \nabla)(\bar{v} + \Phi_2) + u \nabla (\bar{u} + \Phi_1) \right) \\
+ \nabla \left( (\bar{v} + \Phi_2) \cdot \nabla h_1 + (\bar{u} + \Phi_1) \nabla h_2 \right) \\
- \partial_t \left( ((\bar{v} + \Phi_2) \cdot \nabla)h_2 + (\bar{u} + \Phi_1) \nabla h_1 \right) \\
- \nabla \Delta^{-1} \nabla (uv), 
\]  
(3.8)
and

\[ u = \bar{u} + \Phi_1 + h_1, \]
\[ \mathbf{v} = \bar{\mathbf{v}} + \Phi_2 + h_2. \]

(3.9)

The system (3.7)–(3.9) in the variables \((\bar{u}, \bar{v})\) no longer contains resonant terms. We will construct a smooth global solution to this system.

Let \(\chi \in C^\infty_c(\mathbb{R})\) be such that \(\chi(t) = 1\) for \(0 \leq t \leq 1\) and \(\chi(t) = 0\) for \(t \geq 2\). For integers \(n \geq 0\), define

\[ \chi_n(t) = \chi(2^{-n}t). \]

It is clear that \(\chi_n\) is localized to the regime \(t \lesssim 2^n\).

Let \(\bar{u}^{(0)} = 0\), \(\bar{\mathbf{v}}^{(0)} = 0\). For \(n \geq 1\) we inductively define

\[ \Box + 1 \bar{u}^{(n)} = \chi_n(t) \nabla \cdot \left( (\mathbf{v}^{(n-1)} \cdot \nabla)(\bar{u}^{(n)}) + u^{(n-1)} \nabla \bar{u}^{(n)} \right) - \chi_n(t) \partial_t \left( (\mathbf{v}^{(n-1)} \cdot \nabla)(\bar{u}^{(n)}) + u^{(n-1)} \nabla \cdot (\bar{\mathbf{v}}^{(n)}) \right) + \nabla \left( (\mathbf{v}^{(n-1)} \cdot \nabla)\Phi_2 + u^{(n-1)} \nabla \Phi_1 \right) - \partial_t \left( (\mathbf{v}^{(n-1)} \cdot \nabla)\Phi_1 + u^{(n-1)} \nabla \cdot \Phi_2 \right) + \partial_t \left( ((\bar{u}^{(n-1)} + \Phi_1) \cdot \nabla)h_1 + (\bar{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2 \right), \]

(3.10)

and

\[ \Box + 1 \bar{\mathbf{v}}^{(n)} = \chi_n(t) \nabla \cdot \left( (\mathbf{v}^{(n-1)} \cdot \nabla)(\bar{u}^{(n)}) + u^{(n-1)} \nabla \cdot \bar{u}^{(n)} \right) - \chi_n(t) \partial_t \left( (\mathbf{v}^{(n-1)} \cdot \nabla)(\bar{u}^{(n)}) + u^{(n-1)} \nabla \bar{u}^{(n)} \right) + \nabla \left( (\mathbf{v}^{(n-1)} \cdot \nabla)\Phi_2 + u^{(n-1)} \nabla \cdot \Phi_2 \right) - \partial_t \left( (\mathbf{v}^{(n-1)} \cdot \nabla)\Phi_1 + u^{(n-1)} \nabla \cdot \Phi_1 \right) + \partial_t \left( ((\bar{\mathbf{v}}^{(n-1)} + \Phi_2) \cdot \nabla)\Phi_1 + u^{(n-1)} \nabla \cdot \Phi_2 \right) - \partial_t \left( ((\bar{\mathbf{v}}^{(n-1)} + \Phi_2) \cdot \nabla)h_2 + (\bar{\mathbf{v}}^{(n-1)} + \Phi_2) \nabla \cdot h_1 \right) - \nabla \Delta^{-1} \nabla \cdot (u^{(n-1)} \mathbf{v}^{(n-1)}). \]

(3.11)

Here

\[ u^{(n-1)} = \bar{u}^{(n-1)} + h_1 + \Phi_1, \]
\[ \mathbf{v}^{(n-1)} = \bar{\mathbf{v}}^{(n-1)} + h_2 + \Phi_2. \]

In Section 5 we will study the system (3.10)–(3.11) and its solvability.
4. SHARP PHASE ESTIMATES FOR \( \Phi_1, \Phi_2 \)

In this section we estimate \((\Phi_1, \Phi_2)\). By \((3.5) - (3.6), (3.1) - (3.2)\) and \((2.2)\), we have

\[
\Phi_1 = \int_{-\infty}^{t} \sin(t-s) \langle \nabla \rangle \left( \nabla \cdot ((h_2(s) \cdot \nabla)h_2(s) + h_1(s) \nabla h_1(s)) \\
- \partial_s (h_2(s) \cdot \nabla h_1(s) + h_1(s) \nabla h_2(s)) \right) ds,
\]

where we recall

\[
h_1(s) = \cos s \langle \nabla \rangle f_1 + \sin s \langle \nabla \rangle g_1,
\]
\[
h_2(s) = \cos s \langle \nabla \rangle f_2 + \sin s \langle \nabla \rangle g_2.
\]

By Fourier transform, one can write down the explicit form of \( \Phi_1 \) in terms of the sum of several bilinear integrals involving the functions \((f_1, g_1, f_2, g_2)\). There are altogether sixteen such terms. To simplify the notations, we shall only write

\[
\Phi_1(t, \xi) \sim e^{\pm i \xi \cdot \eta} |\xi|^{-1} \int_{-\infty}^{t} \int_{\mathbb{R}^2} e^{-is(\xi \cdot \eta)} \hat{f}(\xi - \eta) \hat{g}(\eta) d\eta ds,
\]

where

\[
\hat{f}(\xi) = (C_1 \xi^{\alpha_1} + C_2 \xi^{\alpha_2}) \hat{f}(\xi),
\]
\[
\hat{g}(\xi) = (C_3 \xi^{\alpha_3} + C_4 \xi^{\alpha_4}) \hat{g}(\xi),
\]

and \(|\alpha_1| \leq 2, |\alpha_2| \leq 2, \alpha_1, \alpha_2\) are multi-indices, also \(r_1 = \pm 1, r_2 = \pm 1, C_1, \cdots, C_4\) are constants, \(\hat{f}, \hat{g}\) can be any one choice from \((\hat{f}_1, \hat{g}_1, \hat{f}_2, \hat{g}_2)\).

Let \(m \geq 0\) be any integer. We compute

\[
\| \langle \xi \rangle \Phi_1(t) \|_{H_{m+2}} + \| \langle \xi \rangle \partial_t \Phi_1(t) \|_{H_{m+2}} \\
\lesssim \| \langle \xi \rangle^{m+2} \langle \xi \rangle \int_{-\infty}^{t} \int_{\mathbb{R}^2} e^{is(\xi \cdot \eta)} \hat{f}(\xi) \hat{g}(\eta) d\eta ds \|_{L^2_{\xi}}
\]
\[
\lesssim \| \langle \xi \rangle^{m+2} \langle \xi \rangle \int_{-\infty}^{t} \int_{\mathbb{R}^2} e^{is(\xi \cdot \eta)} \hat{f}(\xi) \hat{g}(\eta) d\eta ds \|_{L^2_{\xi}},
\]

where in the last step we made a change of variable \(\eta \rightarrow \frac{\xi}{2} + \eta\).

The main result of this section is the following

**Theorem 4.1.** For any integer \(m \geq 0\), we have the estimate

\[
\| \langle \xi \rangle \Phi_1(t) \|_{H_{m+2}} + \| \langle \xi \rangle \partial_t \Phi_1(t) \|_{H_{m+2}} \leq C \sup_{\xi \in \mathbb{R}^2} \| \langle \xi \rangle^{m+24} \left( \sum_{|\alpha| \leq 2} |\partial_\alpha \hat{f}_1(\xi)| + \sum_{|\alpha| \leq 2} |\partial_\alpha \hat{g}_1(\xi)| \right),
\]

where \(C\) is an absolute constant. \((\hat{f}_1, \hat{g}_1, \hat{f}_2, \hat{g}_2)\) are Fourier transforms of the final data \((f_1, g_1, f_2, g_2)\) respectively. Same estimates also hold for \(\Phi_2\).

Theorem 4.1 will follow from the following
Proposition 4.2. For any integer $m \geq 0$, we have

$$\| (\xi)^{m+2}(t) \int_{-\infty}^{t} \int_{\mathbb{R}^2} e^{is\xi(\xi \pm \eta \pm (\xi - \eta))} h(\xi, \eta) d\eta ds \|_{L^2_{\xi}} \lesssim \sup_{\tilde{\xi}, \tilde{\eta} \in \mathbb{R}^2} \langle |\tilde{\xi}| + |\tilde{\eta}| \rangle^{m+2} (|h(\tilde{\xi}, \tilde{\eta})| + |(\partial_\eta h)(\tilde{\xi}, \tilde{\eta})| + |(\partial_\xi^2 h)(\tilde{\xi}, \tilde{\eta})|) \quad (4.1)$$

Note that it is enough to prove Proposition 4.2 for the case $m = 0$. We defer the proof of Proposition 4.2 to the end of this section. For now we assume Proposition 4.2 holds and complete the proof of Theorem 4.1.

It suffices to show the case $m = 0$. By Proposition 4.2 and the brief computation preceding Theorem 4.1, we only need to bound the quantity

$$\sup_{\tilde{\xi}, \tilde{\eta} \in \mathbb{R}^2} \langle |\tilde{\xi}| + |\tilde{\eta}| \rangle^{21} (|h(\tilde{\xi}, \tilde{\eta})| + |(\partial_\eta h)(\tilde{\xi}, \tilde{\eta})| + |(\partial_\xi^2 h)(\tilde{\xi}, \tilde{\eta})|),$$

where $h(\xi, \eta) \sim \hat{f}(\xi + \eta) \hat{g}(\xi - \eta)$, and $\hat{f}(\xi), \hat{g}(\xi)$ depends only on the final data $(f_1, g_1, f_2, g_2)$. An elementary case by case analysis then yields the result. □

The rest of this section is devoted to the proof of Proposition 4.2. We begin by establishing some elementary lemmas.

Lemma 4.3. For any $a, b \in \mathbb{R}^2$, we have

$$\left| \frac{a + b}{\langle a + b \rangle} + \frac{a - b}{\langle a - b \rangle} \right| \gtrsim \frac{|a|}{\langle |a| + |b| \rangle^3}. \quad (4.2)$$

Proof. If $a = 0$ or $b = 0$ then (4.2) holds trivially. Now assume both $a$ and $b$ are nonzero vectors. Denote the vector on the LHS of (4.2) as $X$. We consider several cases. WLOG we may assume $a \cdot b \geq 0$.

Case 1: $|a| \geq |b|$. Then $(a + b) \cdot (a - b) \geq 0$. Therefore we have

$$|X| \gtrsim \frac{|a|}{\langle |a| + |b| \rangle} \gtrsim \frac{|a|}{\langle |a| + |b| \rangle^3}.$$

Case 2: $|a| \leq |b|$. We decompose the vector $a$ as

$$a = a_1 + a_2, \quad \text{where } a_1 \parallel b, a_2 \perp b.$$

Then we have

$$|X| = \sqrt{\frac{|a_1 + b|}{\langle a + b \rangle} + \frac{|a_1 - b|}{\langle a - b \rangle} + |a_2| \left( \frac{1}{\langle a + b \rangle} + \frac{1}{\langle a - b \rangle} \right)^2}. \quad (4.3)$$

Consider two subcases.

Subcase 2a: $|a_2| \geq \frac{1}{2}|a|$. Clearly by (4.3), we get

$$|X| \gtrsim |a_2| \cdot \frac{1}{\langle |a| + |b| \rangle} \gtrsim \frac{|a|}{\langle |a| + |b| \rangle^3}.$$
Subcase 2b: $|a_1| \geq \frac{1}{3} |a|$. Since $a \cdot b \geq 0$, we can write $a_1 = \lambda b$, with $\frac{1}{3} \cdot \frac{|a|}{|b|} \leq \lambda \leq \frac{|a|}{|b|}$. By (4.3) and the fact $a_1 \parallel b$, we obtain

\[
|X| \gtrsim \left| \frac{(\lambda + 1)b}{\langle a_2 + (\lambda + 1)b \rangle} + \frac{(\lambda - 1)b}{\langle a_2 + (\lambda - 1)b \rangle} \right|
\]

\[
\gtrsim \sqrt{\frac{(\lambda + 1)^2 |b|^2}{1 + |a_2|^2 + (\lambda + 1)^2 |b|^2} - \frac{(\lambda - 1)^2 |b|^2}{1 + |a_2|^2 + (\lambda - 1)^2 |b|^2}}
\]

\[
\gtrsim \frac{|a|}{(\langle |a| + |b| \rangle)^3} \cdot (a \cdot b)
\]

The lemma is proved. \qed

**Lemma 4.4.** For any $A, B \in \mathbb{R}$, we have

\[
\sqrt{1 + A^2} + \sqrt{1 + B^2} - \sqrt{1 + (A + B)^2} \gtrsim \frac{1}{\sqrt{1 + A^2} + \sqrt{1 + B^2}} \quad (4.4)
\]

**Proof.** This is almost trivial. We compute

\[
\text{LHS of (4.4)} = \frac{2 + A^2 + B^2 + 2\sqrt{1 + A^2} \cdot \sqrt{1 + B^2} - (1 + A^2 + B^2 + 2AB)}{\sqrt{1 + A^2} + \sqrt{1 + B^2} + \sqrt{1 + (A + B)^2}}
\]

\[
\gtrsim \frac{1}{\sqrt{1 + A^2} + \sqrt{1 + B^2}}.
\]

Now define

\[
a_1(\xi, \eta) = \langle \xi \rangle - \frac{\xi}{2} + \eta - \frac{\eta}{2},
\]

\[
a_2(\xi, \eta) = \langle \xi \rangle + \frac{\xi}{2} + \eta + \frac{\eta}{2},
\]

\[
a_3(\xi, \eta) = \langle \xi \rangle - \frac{\xi}{2} + \eta + \frac{\eta}{2},
\]

\[
a_4(\xi, \eta) = \langle \xi \rangle + \frac{\xi}{2} + \eta - \frac{\eta}{2}.
\]

**Lemma 4.5.** For any $\xi, \eta \in \mathbb{R}^2$, we have
\[
\frac{1}{\langle |\xi| + |\eta| \rangle} \lesssim |a_i(\xi, \eta)| \lesssim \langle |\xi| + |\eta| \rangle, \quad \forall 1 \leq i \leq 4. \tag{4.5}
\]
\[
|\nabla_\eta a_i(\xi, \eta)| \gtrsim \begin{cases} 
\frac{|\eta|}{\langle |\xi| + |\eta| \rangle^2}, & i = 1, 2 \\
\frac{|\xi|}{\langle |\xi| + |\eta| \rangle^2}, & i = 3, 4
\end{cases} \tag{4.6}
\]
\[
|\partial_\eta^k a_i(\xi, \eta)| \lesssim 1, \quad \forall 1 \leq i \leq 4, k \geq 1. \tag{4.7}
\]

If \(i = 3, 4\), then
\[
|\partial_\eta^k a_i(\xi, \eta)| \lesssim |\xi|, \quad \forall 1 \leq k \leq 4. \tag{4.8}
\]
\[
\left| \partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla a_i(\xi, \eta)|^2} \right) \right| \lesssim \frac{\langle |\xi| + |\eta| \rangle^6}{|\xi|}, \quad \forall \xi \neq 0, \tag{4.9}
\]
\[
\left| \partial_\eta^2 \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla a_i(\xi, \eta)|^2} \right) \right| \lesssim \frac{\langle |\xi| + |\eta| \rangle^9}{|\xi|}, \quad \forall \xi \neq 0. \tag{4.10}
\]

Proof: The lower bound in (4.5) follows from Lemma 4.4. The upper bound in (4.5) is trivial. If \(i = 1, 2\), then (4.6) follows from Lemma 4.3 with \(a = \eta, b = \frac{\xi}{2}\). Similarly the case \(i = 3, 4\) follows from Lemma 4.3 with \(a = \frac{\xi}{2}, b = \eta\). Next observe that \(|\partial_\eta^k(\langle x \rangle)| \lesssim \langle x \rangle^{-(k-1)}\) for any \(k \geq 1\). Therefore (4.7) holds. Next we show (4.8). This is a matter of direct calculation. Define \(a(x) = \langle x \rangle\). Then for \(i = 3, 4, 1 \leq k \leq 4\),
\[
|\partial_\eta^k a_i(\xi, \eta)| = |(\partial_\eta^k a)(\eta + \frac{\xi}{2}) - (\partial_\eta^k a)(\eta - \frac{\xi}{2})|
\lesssim \|\partial_\eta^{k+1} a\|_\infty \cdot |\xi|
\lesssim |\xi|,
\]
where in the last inequality we have used again the fact that \(|\partial_\eta^k(\langle x \rangle)| \lesssim \langle x \rangle^{-(k-1)}\). This finishes the proof of (4.8). Finally we show (4.9) and (4.10). By direct differentiation, disregarding inessential coefficients and keeping only the main terms, we have
\[
\partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla a_i(\xi, \eta)|^2} \right) \sim \frac{(\partial_{\eta\eta} a_i(\xi, \eta))^2 \partial_\eta^2 a_i(\xi, \eta)}{|\nabla a_i(\xi, \eta)|^4},
\]
\[
\partial_\eta^2 \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla a_i(\xi, \eta)|^2} \right) \sim \frac{\partial_\eta^3 a_i(\xi, \eta) \cdot (\partial_{\eta a_i(\xi, \eta)})^2 + (\partial_\eta^2 a_i(\xi, \eta))^2 \cdot \partial_{\eta a_i(\xi, \eta)}}{|\nabla a_i(\xi, \eta)|^4}
+ \frac{(\partial_{\eta a_i(\xi, \eta)})^3 \cdot (\partial_\eta^2 a_i(\xi, \eta))^2}{|\nabla a_i(\xi, \eta)|^6}.
\]
Therefore by (4.6) and (4.8), we obtain
\[
\left| \partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla a_i(\xi, \eta)|^2} \right) \right| \lesssim \frac{|\partial_\eta^2 a_i(\xi, \eta)|}{|\nabla a_i(\xi, \eta)|^2} \lesssim \frac{\langle |\xi| + |\eta| \rangle^6}{|\xi|^2}
\lesssim \frac{\langle |\xi| + |\eta| \rangle^6}{|\xi|},
\]
Lemma 4.6. Let $a_{ij}(\xi, \eta)$ be as defined as above. Define

$$F_i(s, \xi) = \int_{\mathbb{R}^2} e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} h(\eta) d\eta.$$  

Then we have

$$|F_i(s, \xi)| \lesssim \frac{1}{s^2} (|\xi|)^{12} (1 + |\xi|^{-2})$$

$$+ \left( \sum_{|\alpha| \leq 2} \int |\eta|^{12} |\partial^\alpha h(\eta)| d\eta + \sum_{|\alpha| \leq 2} \sup_{|\eta| \leq 2} |\partial^\alpha h(\eta)| \right)$$

$$|\partial_i F_i(s, \xi)| \lesssim \frac{1}{s^2} (|\xi|)^{12} (1 + |\xi|^{-2})$$

$$+ \left( \sum_{|\alpha| \leq 2} \int |\eta|^{12} |\partial^\alpha h(\eta)| d\eta + \sum_{|\alpha| \leq 2} \sup_{|\eta| \leq 2} |\partial^\alpha h(\eta)| \right)$$

Proof. We first estimate $\partial_i F_i$. Without loss of generality, we also assume $s > 1$.

We first consider $\partial_i F_1$, $\partial_i F_2$, where we shall use the following bound for $a_i$, $i = 1, 2$,

$$\begin{cases}
|\nabla a_i| \gtrsim \frac{|\eta|}{(|\eta| + |\xi|)^2} \\
|\partial^k a_i| \lesssim 1, \text{ for } k \geq 1, \\
|a_i(\xi, \eta) - a_i(\xi, 0)| \lesssim |\eta|^2.
\end{cases} \quad (4.11)$$

Since for the phase function $a_i(\xi, \eta) - a_i(\xi, 0)$, the stationary phase point occurs at $\eta = 0$, we introduce the cutoff function separate the near-origin regime and others.

Let $\psi(\eta)$ be a smooth cutoff function such that

$$\psi(\eta) = \begin{cases}
1, & |\eta| \leq 1, \\
0, & |\eta| > 2
\end{cases} \quad (4.12)$$

We split $\partial_i F_i$, $i = 1, 2$ as follows

$$\partial_i F_i(s, \xi) = \int_{\mathbb{R}^2} (a_i(\xi, \eta) - a_i(\xi, 0)) e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} h(\eta) d\eta$$

$$= \int_{\mathbb{R}^2} (a_i(\xi, \eta) - a_i(\xi, 0)) e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} h(\eta) \psi(\eta) d\eta$$

$$+ \int_{\mathbb{R}^2} (a_i(\xi, \eta) - a_i(\xi, 0)) e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} h(\eta) (1 - \psi(\eta)) d\eta \quad (4.13)$$

For (4.13), we do integration by parts twice. This gives

$$\frac{1}{s^2} \int_{\mathbb{R}^2} \nabla \cdot \left( \frac{\nabla a_i}{|\nabla a_i|^2} \right) \cdot \left( \frac{\nabla a_i}{|\nabla a_i|^2} (a_i(\xi, \eta) - a_i(\xi, 0)) h(\eta) (1 - \psi(\eta)) \right)$$

$$e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} d\eta.$$
Using the product rule and the estimates (4.11), we obtain

\[
\left| \frac{\xi}{\eta} \right| \lesssim \frac{1}{s^2} \int_{|\eta| \geq 1} (1 + |\eta|^{-4}) (|\xi| + |\eta|)^{12} \left( \sum_{|\alpha| \leq 2} |\partial^\alpha h(\eta)| \right) d\eta \\
\lesssim \frac{1}{s^2} \int_{|\eta| \geq 1} (|\xi| + |\eta|)^{12} \left( \sum_{|\alpha| \leq 2} |\partial^\alpha h(\eta)| \right) d\eta \\
\lesssim \frac{1}{s^2} (|\xi|)^{12} \sum_{|\alpha| \leq 2} \int_{\mathbb{R}^2} (|\eta|)^{12} |\partial^\alpha h(\eta)| d\eta.
\]

We now turn to estimating (4.13). To this end, we further write it into the following

\[
4.13 = \int (a_i(\xi, \eta) - a_i(\xi, 0)) e^{i\pi(\xi, \eta)} h(\eta) \psi(\eta) \psi(\eta) d\eta \\
+ \int (a_i(\xi, \eta) - a_i(\xi, 0)) e^{i\pi(\xi, \eta)} h(\eta) \psi(\eta)(1 - \psi(\eta)) d\eta. 
\]

For (4.13), we simply use (4.11) to get

\[
4.15 \lesssim \int_{|\eta| \leq 2s^{-10}} |\eta| |h(\eta)| \psi(\eta) |d\eta| \\
\lesssim s^{-10} \int |h(\eta)| |d\eta|.
\]

For (4.16), we use integration by parts twice and (4.11) to get

\[
|4.16| \lesssim \frac{1}{s^2} \int \left| \nabla \cdot \left( \frac{\nabla a_i}{|\nabla a_i|^2} \right) \right| \left| \nabla \cdot \left( \frac{\nabla a_i}{|\nabla a_i|^2} (a_i(\xi, \eta) - a_i(\xi, 0)) h(\eta) \psi(\eta) (1 - \psi(\eta) \eta) \right) \right| |d\eta| \\
\lesssim \frac{1}{s^2} \left\{ \int |a_i(\xi, \eta) - a_i(\xi, 0)| |\nabla a_i|^{-4} |h(\eta)| \psi(\eta) (1 - \psi(\eta) \eta) |d\eta| \\
+ \int_{|\eta| \leq 2} |a_i(\xi, \eta) - a_i(\xi, 0)| |\nabla a_i|^{-3} \left( \sum_{|\alpha| \leq 1} |\partial^\alpha h(\eta)| \right) (1 - \psi(\eta) \eta) + s^{10} |\nabla \psi(\eta) \eta) |d\eta| \\
+ \int_{|\eta| \leq 2} |a_i(\xi, \eta) - a_i(\xi, 0)| |\nabla a_i|^{-2} \left( \sum_{|\alpha| \leq 2} |\partial^\alpha h(\eta)| \right) \\
\times \left( (1 - \psi(\eta) \eta) + s^{10} |\nabla \psi(\eta) \eta) | + s^{20} |\nabla \psi(\eta) \eta) |d\eta| \\
+ \int_{|\eta| \leq 2} |\nabla a_i| |\nabla a_i|^{-3} |h(\eta)| |d\eta| \\
+ \int_{|\eta| \leq 2} |\nabla a_i| |\nabla a_i|^{-2} \left( \sum_{|\alpha| \leq 1} |\partial^\alpha h(\eta)| \right) (1 - \psi(\eta) \eta) + s^{10} |\nabla \psi(\eta) \eta) |d\eta| \right\}.
\]
Using estimates (4.11), we further bound (4.16) as

\[
\|4.16\| \lesssim \frac{1}{s^2} \left\{ \int_{s^{-10} \leq |\eta| \leq 2} |\eta|^{-2} (|\eta| + |\xi|)^{12} |h(\eta)| d\eta \\
+ \int_{s^{-10} \leq |\eta| \leq 2} |\eta|^{-1} (|\eta| + |\xi|)^9 \left( \sum_{|\alpha| \leq 1} |\partial^\alpha h(\eta)| \right) d\eta \\
+ \int_{|\eta| \sim s^{-10}} (|\eta| + |\xi|)^6 s^{10} \left( \sum_{|\alpha| \leq 2} |\partial^\alpha h(\eta)| \right) d\eta \\
+ \int_{|\eta| \sim s^{-10}} (|\eta| + |\xi|)^6 \left( \sum_{|\alpha| \leq 2} |\partial^\alpha h(\eta)| \right) s^{20} d\eta \right\} \lesssim \frac{1}{s^2} \log s \langle |\xi| \rangle^{12} \sum_{|\alpha| \leq 2} \sup_{|\eta| \leq 2} |\partial^\alpha h(\eta)| \\
\lesssim \frac{\langle |\xi| \rangle^{12}}{s^2} \sum_{|\alpha| \leq 2} \sup_{|\eta| \leq 2} |\partial^\alpha h(\eta)|.
\]

Collecting the estimates above we obtain

\[
|\partial_s F_i(s, \xi)| \lesssim \frac{1}{s^2} \langle |\xi| \rangle^{12} \sum_{|\alpha| \leq 2} \left( \int (|\eta| + |\xi|)^{12} |\partial^\alpha h(\eta)| d\eta + \sup_{|\eta| \leq 2} |\partial^\alpha h(\eta)| \right).
\]  

(4.18)

for \( i = 1, 2. \)

Now it remains to obtain the estimates for \( F_i, \) \( i = 3, 4. \) We will use the following estimates for \( a_i, \)

\[
\begin{align*}
|\nabla a_i| &\gtrsim \frac{|\xi|}{(|\eta| + |\xi|)^2} \\
|\partial^k a_i| &\lesssim 1, \; k \geq 1, \\
|a_i(\xi, \eta) - a_i(\xi, 0)| &\lesssim |\eta|.
\end{align*}
\]  

(4.19)
We will estimate $\partial_s F_i$, simply by integration by parts twice. We have

$$|\partial_s F_i(s, \xi)| = \left| \int (a_i(\xi, \eta) - a_i(\xi, 0)) e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} h(\eta) d\eta \right|$$

$$= \frac{1}{s^2} \left| \int \nabla \cdot \left( \frac{\nabla a_i}{|\nabla a_i|^2} \nabla \cdot \left( \frac{\nabla a_i}{|\nabla a_i|^2} (h(\eta)(a_i(\xi, \eta) - a_i(\xi, 0))) \right) \right) e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} d\eta \right|$$

$$\lesssim \frac{1}{s^2} \left\{ \int |\nabla a_i|^{-4} h(\eta)|\eta|d\eta 
+ \int |\nabla a_i|^{-3} \sum_{|\alpha| \leq 1} |\partial^\alpha h(\eta)|(|\eta| + |\nabla a_i|) d\eta 
+ \int |\nabla a_i|^{-2} \sum_{|\alpha| \leq 2} |\partial^\alpha h(\eta)||\eta|d\eta \right\}$$

$$\lesssim \frac{1}{s^2} \int |\xi|^{-2}(|\eta| + |\xi|)^{12} \sum_{|\alpha| \leq 2} |\partial^\alpha h(\eta)| d\eta$$

$$\lesssim \frac{1}{s^2} |\xi|^{-2}(|\xi|)^{12} \sum_{|\alpha| \leq 2} \int |\partial^\alpha h(\eta)||\eta|^{12} d\eta.$$

This finishes the estimates for $\partial_s F_i$, $i = 3, 4$. Finally we make a remark about the decay of $F_i$. Indeed, the decay of $F_i$ can be obtained by slightly modifying the above computation, namely, replacing the integration by parts twice with IBP once. We omit the details. The proof of this lemma is completed.

$\square$

As a consequence of this lemma, we have

**Lemma 4.7.** Assume the function $h = h(\xi, \eta)$ is such that

$$\sum_{|\alpha| \leq 2} \int_{\mathbb{R}^2} (\eta)^{12} |\partial^\alpha h(\xi, \eta)| d\eta + \|\partial^\alpha h(\xi, \eta)\|_\infty < \infty.$$

Then for $i = 1, 2, 3, 4$ and any $\xi \neq 0$, we have

$$\int_t^\infty \int_{\mathbb{R}^2} e^{is a_i(\xi, \eta)} h(\xi, \eta) d\eta ds = -\int_{\mathbb{R}^2} \int_t^\infty i a_i(\xi, \eta) h(\xi, \eta) d\eta ds.$$  \hspace{1cm} (4.20)

**Proof.** Define

$$F(s, \xi) = \int e^{is(a_i(\xi, \eta) - a_i(\xi, 0))} h(\xi, \eta) d\eta.$$

We write

$$\int_t^\infty \int_{\mathbb{R}^2} e^{is a_i(\xi, \eta)} h(\xi, \eta) d\eta ds = \int_t^\infty e^{is a_i(\xi, 0)} F_i(s, \xi) ds$$

$$= \int_t^\infty \frac{1}{ia_i(\xi, 0)} \int_t^\infty \partial_s (e^{is a_i(\xi, 0)} F_i(s, \xi)) ds - \frac{1}{ia_i(\xi, 0)} \int_t^\infty e^{is a_i(\xi, 0)} \partial_s F_i(s, \xi) ds$$

$$= -\frac{1}{ia_i(\xi, 0)} e^{ia_i(\xi, 0)} F_i(t, \xi) - \frac{1}{ia_i(\xi, 0)} \int_t^\infty e^{is a_i(\xi, 0)} \partial_s F_i(s, \xi) ds.$$
Now due to the decay of $\partial_s F_i$, the integral in the above is absolutely convergent. Therefore we have

$$\int_0^\infty \int e^{ita_i(\xi,\eta)} h(\xi,\eta) d\eta ds$$

$\lim_{\varepsilon \to 0^+} \int_0^\infty e^{ita_i(\xi,0) - \varepsilon t} F_i(t,\xi) - \frac{1}{ia(\xi,0) - \varepsilon} \int_0^\infty e^{ita_i(\xi,0) - \varepsilon s} \partial_s F_i(s,\xi) ds$

$$= \lim_{\varepsilon \to 0^+} \int_0^\infty e^{ita_i(\xi,0) - \varepsilon t} F_i(s,\xi) ds$$

$$= \lim_{\varepsilon \to 0^+} \int_0^\infty \int e^{ita_i(\xi,\eta) - \varepsilon t} h(\xi,\eta) d\eta ds$$

$$= \lim_{\varepsilon \to 0^+} \int_0^\infty \int \frac{e^{ita_i(\xi,\eta) - \varepsilon t}}{ia(\xi,\eta) - \varepsilon} h(\xi,\eta) d\eta$$

$$= \int \frac{e^{ita_i(\xi,\eta)}}{ia(\xi,\eta)} h(\xi,\eta) d\eta.$$

□

Lemma 4.8. Let $0 < \delta \leq \frac{1}{100}$. Then for $i = 1, 2$,

$$\left| \int_{|\eta| \leq \frac{2d(\xi)}{(\xi \cdot t)^2}} e^{ita_i(\xi,\eta)} d\eta \right| \lesssim \frac{1}{(\xi \cdot t)} \cdot \langle \xi \rangle^7. \quad (4.21)$$

Proof. This is a stationary phase calculation. The main point is to get the explicit dependence on the parameter $\xi$. WOLOG we can assume $t \geq 1$. Define $\lambda = \frac{1}{2}|\xi|$. By rotation invariance, we may assume $\xi = 2\lambda \hat{e}_1 = (2\lambda, 0)$. Let $\eta = \lambda \tilde{\eta}$. Then

$$\langle \eta + \frac{\xi}{2} \rangle + \langle \eta - \frac{\xi}{2} \rangle = \sqrt{1 + \lambda^2(|\tilde{\eta}|^2 + 2\lambda_1 + 1) + \sqrt{1 + \lambda^2(|\tilde{\eta}|^2 - 2\lambda_1 + 1)}.$$ Here $\hat{\eta}_1$ is the first component of the vector $\tilde{\eta}$. Passing to radial coordinates, we obtain

$$\text{LHS of (4.21)} \lesssim \left| \int_{0}^{2\pi} \int_{0}^{\pi/4} \sqrt{1 + \lambda^2} e^{itg(\rho,\theta) \lambda^2 \rho d\rho d\theta} \right|,$$

where

$$g(\rho, \theta) = \sqrt{1 + \lambda^2(\rho^2 + 2\rho \cos \theta + 1)} \sqrt{1 + \lambda^2(\rho^2 - 2\rho \cos \theta + 1)}.$$ Now set $r = \sqrt{\rho}$. Then we get

$$\text{LHS of (4.21)} \lesssim \left| \int_{0}^{2\pi} \int_{0}^{\pi/4} \sqrt{1 + \lambda^2} e^{it\tilde{g}(r,\theta) \lambda^2 r d\theta} \right|. \quad (4.22)$$

Here

$$\tilde{g}(r, \theta) = \sqrt{1 + \lambda^2(r + 2\sqrt{r} \cos \theta + 1)} \sqrt{1 + \lambda^2(r - 2\sqrt{r} \cos \theta + 1)} =: \sqrt{A_+} + \sqrt{A_-}.$$ Observe that for $r \leq \frac{16\lambda^2}{1+4\lambda^2}$,

$$1 \lesssim A_+, \ A_- \lesssim \lambda + 1.$$
On the other hand
\[
\frac{\partial}{\partial r}\tilde{g}(r, \theta) = \lambda^2 \cdot \frac{A_+ + A_- + 2\sqrt{A_+ \cdot A_-} - 4\lambda^2 \cos^2 \theta}{\sqrt{A_+ \cdot A_-} \cdot (\sqrt{A_+} + \sqrt{A_-})}
\]
\[
= \lambda^2 \cdot \frac{2 + 2\lambda^2(r + 1) + 2\sqrt{(1 + \lambda^2)(r + 1)^2} - 4\lambda^4 r \cos^2 \theta - 4\lambda^2 \cos^2 \theta}{\sqrt{A_+ \cdot A_-} \cdot (\sqrt{A_+} + \sqrt{A_-})}.
\]

For \( r \leq \frac{16\lambda^2}{1+4\lambda^2} \), we have
\[
4\lambda^4 r \cos^2 \theta \leq 2\lambda^2 \leq 2\lambda^2(r + 1).
\]
This gives
\[
2 + 2\lambda^2(r + 1) + 2\sqrt{(1 + \lambda^2)(r + 1)^2} - 4\lambda^4 r \cos^2 \theta - 4\lambda^2 \cos^2 \theta \geq 2 + 2\lambda^2 + 2\lambda^2(r + 1) - 4\lambda^2 \geq 2.
\]
Therefore we get for \( 0 \leq r \leq \frac{16\lambda^2}{1+4\lambda^2} \),
\[
\left| \frac{\partial}{\partial r}\tilde{g}(r, \theta) \right| \geq \frac{\lambda^2}{(1 + \lambda)^2}.
\] (4.23)

Next we need to bound the second order derivative \( \frac{\partial^2}{\partial r^2}\tilde{g}(r, \theta) \). We first rewrite \( \tilde{g}(r, \theta) \) as
\[
\tilde{g}(r, \theta) = \sqrt{(\sqrt{A_+} + \sqrt{A_-})^2}
\]
\[
= \sqrt{2 + 2\lambda^2(r + 1) + 2\sqrt{(1 + \lambda^2)(r + 1)^2} - 4\lambda^4 r \cos^2 \theta}
\]
\[
=: \sqrt{B_1 + 2\sqrt{B_2}}.
\]
By direct differentiation, we have
\[
\frac{\partial^2}{\partial r^2}\tilde{g} = -\frac{1}{4} \cdot (B_1 + 2\sqrt{B_2})^{-\frac{3}{2}} \cdot \left( \frac{\partial B_1}{\partial r} + B_2^{-\frac{3}{2}} \cdot \frac{\partial B_2}{\partial r} \right)^2
\]
\[
+ \frac{1}{2} \cdot (B_1 + 2\sqrt{B_2})^{-\frac{1}{2}} \cdot \left( -\frac{1}{2} B_2^{-\frac{3}{2}} \cdot \left( \frac{\partial B_2}{\partial r} \right)^2 + B_2^{-\frac{1}{2}} \cdot \frac{\partial^2 B_2}{\partial r^2} \right).
\]
It is not difficult to check that for \( 0 < r \leq \frac{16\lambda^2}{1+4\lambda^2} \),
\[
B_1 + 2\sqrt{B_2} \geq 1, \quad \text{and} \quad B_2 \geq 1,
\]
\[
\left| \frac{\partial B_1}{\partial r} \right| \lesssim \lambda^2, \quad \text{and} \quad \left| \frac{\partial B_2}{\partial r} \right| \lesssim \lambda^2 + \lambda^4.
\]
Also
\[
\left| \frac{\partial^2 B_2}{\partial r^2} \right| \lesssim \lambda^4.
\]
Therefore
\[
\left| \frac{\partial^2}{\partial r^2}\tilde{g} \right| \lesssim (\lambda^2 + \lambda^4)^2 + \lambda^4 \lesssim \lambda^4 + \lambda^8.
\] (4.24)
By (4.23) and (4.24), we obtain
\[
\left| \int_{0}^{16 \xi^{2}} e^{i \theta (r, \theta)} \, dr \right| \lesssim \frac{1}{t^{2}} \cdot \left( \frac{(1 + \lambda)^{2}}{\lambda^{2}} + \frac{(1 + \lambda)^{3}}{\lambda^{2}} \cdot (\lambda^{4} + \lambda^{8}) \cdot \frac{1}{1 + \lambda^{2}} \right).
\]

Therefore by (4.22), we get
\[
\text{LHS of (4.21)} \lesssim \frac{1}{t} \cdot (1 + \lambda)^{7}.
\]

The lemma is proved. \qed

**Lemma 4.9.** Let \( \psi \in C_{c}^{\infty} (\mathbb{R}^{2}) \) be such that
\[
\psi (x) = \begin{cases} 
1, & |x| \leq 1, \\
0, & |x| \geq 2.
\end{cases}
\]

Then for any \( i = 1, 2 \), we have
\[
\left| \int_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} \left( \frac{h(\xi, \eta)}{a_{i}(\xi, \eta)} \psi (\eta (\xi) \frac{2}{|\xi|}) - \frac{h(\xi, 0)}{a_{i}(\xi, 0)} \right) \cdot e^{ita_{i}(\xi, \eta)} \, d\eta \right| 
\leq \frac{1}{\langle \xi \rangle} \cdot \langle \xi \rangle^{3} \cdot \sup_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} (|h(\xi, \eta)| + |\nabla_{\eta} h(\xi, \eta)|).
\]

**Proof.** If \( t \leq 1 \), then (4.25) holds trivially. Now assume \( t \geq 1 \). Define
\[
G_{i}(\xi, \eta) = \frac{h(\xi, \eta)}{a_{i}(\xi, \eta)} \psi (\eta (\xi) \frac{2}{|\xi|}) - \frac{h(\xi, 0)}{a_{i}(\xi, 0)}.
\]

Note that \( \psi (0) = 1 \) and
\[
\left| \nabla_{\eta} \psi (\eta (\xi) \frac{2}{|\xi|}) \right| \lesssim \frac{\langle \xi \rangle^{2}}{|\xi|}.
\]

By Lemma 4.5 we have for \( i = 1, 2 \)
\[
\sup_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} |G_{i}(\xi, \eta)| \lesssim \langle \xi \rangle \cdot \sup_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} |h(\xi, \eta)|.
\]

Since \( G_{i}(\xi, 0) = 0 \), we get
\[
\sup_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} \frac{|G_{i}(\xi, \eta)|}{|\eta|} \lesssim \sup_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} \left| \nabla_{\eta} G_{i}(\xi, \eta) \right|
\geq \sup_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} \left\{ \left| \nabla_{\eta} h(\xi, \eta) \right| + \left| h(\xi, \eta) \cdot |\nabla_{\eta} a_{i}(\xi, \eta)| \right|^{2} \right\}^{3/2}
\leq \frac{\langle \xi \rangle^{3}}{|\xi|} \cdot \sup_{|\eta| \leq \frac{2|\xi|}{(\xi, \eta)}} (|h(\xi, \eta)| + |\nabla_{\eta} h(\xi, \eta)|).
\]
Using integration by parts together with (4.20), (4.27), we then obtain or $i = 1, 2$

\[
\text{LHS of (4.26)} = \frac{1}{t} \int_{|\eta| \leq \frac{2t|\xi|}{|\xi|^2}} G_1(\xi, \eta) \frac{\nabla_a \eta |a_i(\xi, \eta)|^2}{|\nabla_a \eta|} \eta e^{ita_i(\xi, \eta)} d\sigma(\eta)
\]
\[
- \int_{|\eta| \leq \frac{2t|\xi|}{|\xi|^2}} \nabla_\eta \cdot (G_1(\xi, \eta) \frac{\nabla_a \eta a_i(\xi, \eta)}{|\nabla_a \eta|} |a_i(\xi, \eta)|^2) e^{ita_i(\xi, \eta)} d\eta
\]
\[
\lesssim \frac{1}{t} \int_{|\eta| \leq \frac{2t|\xi|}{|\xi|^2}} \langle \xi \rangle \cdot \sup_{|\eta| \leq \frac{2t|\xi|}{|\xi|^2}} |h(\xi, \eta)| \cdot \frac{\langle |\eta| + |\xi|^3 \rangle}{|\eta|} d\sigma(\eta)
\]
\[
+ \frac{1}{t} \cdot \langle \xi \rangle^3 \cdot \sup_{|\eta| \leq \frac{2t|\xi|}{|\xi|^2}} (|h(\xi, \eta)| + |\nabla_\eta h(\xi, \eta)|) \cdot \int_{|\eta| \leq \frac{2t|\xi|}{|\xi|^2}} \frac{\langle |\eta| + |\xi|^6 \rangle}{|\eta|} d\eta
\]
\[
\lesssim \frac{1}{t} \cdot \langle \xi \rangle^9 \cdot \sup_{|\eta| \leq \frac{2t|\xi|}{|\xi|^2}} (|h(\xi, \eta)| + |\nabla_\eta h(\xi, \eta)|).
\]

\[\square\]

**Lemma 4.10.** For $i = 1, 2$, we have

\[
\left| \int_{\mathbb{R}^2} \frac{h(\xi, \eta)}{a_i(\xi, \eta)} (1 - \psi(\frac{\eta(\xi)^2}{\delta|\xi|})) \cdot e^{ita_i(\xi, \eta)} d\eta \right|
\]
\[
\lesssim \frac{1}{|\xi|} \cdot (1 + |\log |\xi||) \cdot \langle \xi \rangle^{-5} \cdot \sup_{\xi, \eta \in \mathbb{R}^2} (|\xi| + |\eta|)^{12} \cdot (|h(\xi, \eta)| + |\nabla_\eta h(\xi, \eta)|). \quad (4.28)
\]

**Proof.** WLOG we may assume $t \geq 1$. Since the function $1 - \psi(\frac{\eta(\xi)^2}{\delta|\xi|})$ is localized to the region $\{|\eta| \geq \frac{\delta|\xi|}{|\xi|^2}\}$ and vanishes on the boundary, a simple integration by parts gives us

\[
\text{LHS of (4.28)} = -\frac{1}{it} \int_{\mathbb{R}^2} \nabla_\eta \cdot \left( \frac{\nabla_a \eta a_i(\xi, \eta)}{|\nabla_a \eta|} \cdot \frac{h(\xi, \eta)}{a_i(\xi, \eta)} \cdot (1 - \psi(\frac{\eta(\xi)^2}{\delta|\xi|})) \right) e^{ita_i(\xi, \eta)} d\eta
\]
\[
=: -\frac{1}{it} \int_{\mathbb{R}^2} \frac{\Delta_\eta a_i(\xi, \eta)}{|\nabla_a \eta|} \cdot \frac{|h(\xi, \eta)|}{|a_i(\xi, \eta)|} \cdot \left| 1 - \psi(\frac{\eta(\xi)^2}{\delta|\xi|}) \right| e^{ita_i(\xi, \eta)} d\eta.
\]

It only remains for us to bound $G_1(\xi, \eta)$.

By direct differentiation, we get

\[
|G_1(\xi, \eta)| \lesssim \frac{|\Delta_\eta a_i(\xi, \eta)|}{|\nabla_a \eta|} \cdot \frac{|h(\xi, \eta)|}{|a_i(\xi, \eta)|} \cdot \left| 1 - \psi(\frac{\eta(\xi)^2}{\delta|\xi|}) \right| \quad (4.30)
\]
\[
+ \frac{1}{|\nabla_a \eta h(\xi, \eta)|} \cdot \frac{|h(\xi, \eta)|}{|a_i(\xi, \eta)|} \cdot \left| 1 - \psi(\frac{\eta(\xi)^2}{\delta|\xi|}) \right| \quad (4.31)
\]
\[
+ \frac{|h(\xi, \eta)|}{|a_i(\xi, \eta)|} \cdot \left| 1 - \psi(\frac{\eta(\xi)^2}{\delta|\xi|}) \right| \quad (4.32)
\]
\[
+ \frac{1}{|\nabla_a \eta h(\xi, \eta)|} \cdot \frac{|h(\xi, \eta)|}{|a_i(\xi, \eta)|} \cdot \left| (\nabla h)(\eta(\xi)^2) \right| \cdot \left| (\nabla \psi)(\eta(\xi)^2) \right| \quad (4.33)
\]
By Lemma 4.10 we have

\[ \int_{\mathbb{R}^2} \frac{h(\xi, \eta)}{\alpha_t(\xi, \eta)} e^{it\alpha_t(\xi, \eta)} d\eta \leq \frac{1}{t^2} \frac{1}{|\xi|^2} \cdot \frac{1}{|\xi|^3} \cdot \sup_{\xi, \eta \in \mathbb{R}^2} |\xi| + |\eta|^{21}(|h(\xi, \eta)| + |(\partial_\eta h(\xi, \eta)| + |(\partial_\eta^2 h)(\xi, \eta)|). \] (4.34)

**Proof.** By using integration by parts twice, we get

\[
\int_{\mathbb{R}^2} \frac{h(\xi, \eta)}{\alpha_t(\xi, \eta)} e^{it\alpha_t(\xi, \eta)} d\eta \\
= - \frac{1}{t^2} \int_{\mathbb{R}^2} \nabla_\eta \cdot \left( \frac{\nabla_\eta a_t(\xi, \eta)}{\nabla_\eta a_t(\xi, \eta)} \right) \nabla_\eta \cdot \left( \frac{h(\xi, \eta)}{|\nabla_\eta a_t(\xi, \eta)|^2} \right) e^{it\alpha_t(\xi, \eta)} d\eta \\
= - \frac{1}{t^2} \int_{\mathbb{R}^2} G_2(\xi, \eta) e^{it\alpha_t(\xi, \eta)} d\eta. \] (4.35)
It only remains for us to bound \( G_2(\xi, \eta) \). By direct differentiation and discarding inessential constants, we have

\[
|G_2(\xi, \eta)| \lesssim \left| \partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla_\eta a_i(\xi, \eta)|^2} \right) \right| \cdot \left| \partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla_\eta a_i(\xi, \eta)|^2} \right) \right| \cdot \frac{|h(\xi, \eta)|}{a_i(\xi, \eta)} \tag{4.36}
\]

\[
+ \left| \partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla_\eta a_i(\xi, \eta)|^2} \right) \right| \cdot \frac{1}{|\nabla_\eta a_i(\xi, \eta)|} \cdot \left| \partial_\eta \left( \frac{h(\xi, \eta)}{a_i(\xi, \eta)} \right) \right| \tag{4.37}
\]

\[
+ \frac{1}{|\nabla_\eta a_i(\xi, \eta)|} \cdot \left| \partial^2_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla_\eta a_i(\xi, \eta)|^2} \right) \right| \cdot \frac{|h(\xi, \eta)|}{a_i(\xi, \eta)} \tag{4.38}
\]

\[
+ \frac{1}{|\nabla_\eta a_i(\xi, \eta)|} \cdot \left| \partial^3_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla_\eta a_i(\xi, \eta)|^2} \right) \right| \cdot \frac{1}{|\partial^2_\eta a_i(\xi, \eta)|} \cdot \frac{1}{a_i(\xi, \eta)} \tag{4.39}
\]

\[
+ \frac{1}{|\nabla_\eta a_i(\xi, \eta)|} \cdot \left| \partial^2_\eta \left( \frac{h(\xi, \eta)}{a_i(\xi, \eta)} \right) \right| \cdot \frac{1}{|\nabla_\eta a_i(\xi, \eta)|} \cdot \left| \partial^2_\eta \left( \frac{h(\xi, \eta)}{a_i(\xi, \eta)} \right) \right| \cdot \frac{1}{|\nabla_\eta a_i(\xi, \eta)|} \tag{4.40}
\]

For \( 4.36 \), we use Lemma 4.5 to bound it as

\[
4.36 \lesssim \frac{\langle |\xi| + |\eta| \rangle^{13}}{|\xi|^2} \cdot |h(\xi, \eta)|
\]

\[
\lesssim \frac{1}{|\xi|^2} \cdot \frac{1}{|\eta|^5} \cdot \sup_{\xi, \eta \in \mathbb{R}^2} \langle |\xi| + |\eta| \rangle^{21} |h(\xi, \eta)|.
\]

Similarly

\[
4.37 \lesssim \left| \partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla_\eta a_i(\xi, \eta)|^2} \right) \right| \cdot \frac{1}{|a_i(\xi, \eta)|^2} \cdot |h(\xi, \eta)|
\]

\[
+ \left| \partial_\eta \left( \frac{\nabla_\eta a_i(\xi, \eta)}{|\nabla_\eta a_i(\xi, \eta)|^2} \right) \right| \cdot \frac{1}{|a_i(\xi, \eta)|} \cdot \frac{1}{|\nabla_\eta a_i(\xi, \eta)|} \cdot |\partial_\eta h(\xi, \eta)|
\]

\[
\lesssim \frac{\langle |\xi| + |\eta| \rangle^8}{|\xi|} |h(\xi, \eta)| + \frac{\langle |\xi| + |\eta| \rangle^6}{|\xi|} \cdot \langle |\xi| + |\eta| \rangle \cdot \langle |\xi| + |\eta| \rangle^3 \cdot |\partial_\eta h(\xi, \eta)|
\]

\[
\lesssim \frac{1}{|\xi|^2} \cdot \frac{1}{|\eta|^5} \cdot \sup_{\xi, \eta \in \mathbb{R}^2} \langle |\xi| + |\eta| \rangle^{21} (|h(\xi, \eta)| + |(\partial_\eta h)(\xi, \eta)|)
\]

The computation of \( 4.38 - 4.39 \) is similar to \( 4.37 \), and we have

\[
4.38 + 4.39 \lesssim \frac{1}{|\xi|^2} \cdot \frac{1}{|\eta|^5} \cdot \frac{1}{|\eta|^3} \cdot \sup_{\xi, \eta \in \mathbb{R}^2} \langle |\xi| + |\eta| \rangle^{21} (|h(\xi, \eta)| + |(\partial_\eta h)(\xi, \eta)|)
\]

Finally for \( 4.40 \), we note that by Lemma 4.5

\[
\left| \partial^2_\eta \left( h(\xi, \eta) a_i(\xi, \eta) \right) \right| \lesssim |(\partial^3_\eta h)(\xi, \eta)| + \frac{|(\partial_\eta h)(\xi, \eta)| \cdot |(\partial^2_\eta a_i)(\xi, \eta)|}{a_i(\xi, \eta)^2}
\]

\[
+ |h(\xi, \eta)| \cdot \frac{|(\partial^2_\eta a_i)(\xi, \eta)|}{a_i(\xi, \eta)^2} + \frac{|(\partial_\eta h)(\xi, \eta)|^2}{a_i(\xi, \eta)^3}
\]

\[
\lesssim \langle |\xi| + |\eta| \rangle^3 (|h(\xi, \eta)| + |(\partial_\eta h)(\xi, \eta)| + |(\partial^2_\eta h)(\xi, \eta)|)
\]

Therefore

\[
4.40 \lesssim \frac{\langle |\xi| + |\eta| \rangle^9}{|\xi|^2} \cdot (|h(\xi, \eta)| + |(\partial_\eta h)(\xi, \eta)| + |(\partial^2_\eta h)(\xi, \eta)|)
\]

\[
\lesssim \frac{1}{|\xi|^2} \cdot \frac{1}{|\eta|^5} \cdot \frac{1}{|\eta|^3} \cdot \sup_{\xi, \eta \in \mathbb{R}^2} \langle |\xi| + |\eta| \rangle^{21} (|h(\xi, \eta)| + |(\partial_\eta h)(\xi, \eta)| + |(\partial^2_\eta h)(\xi, \eta)|).\]
Collecting all the estimates, we obtain

\[ |G_2(\xi, \eta)| \lesssim \frac{1}{|\xi|^2} \cdot \frac{1}{|\xi|^2} \cdot \frac{1}{|\eta|^3} \cdot \sup_{\xi, \eta \in \mathbb{R}^2} \langle \xi \rangle + \langle \eta \rangle^2 (|h(\xi, \eta)| + |(\partial_{\xi} h)(\xi, \eta)| + |(\partial_{\eta} h)(\xi, \eta)|). \]

Plugging this last estimate into RHS of (4.35) and integrating out \( \eta \), we obtain (4.34). The lemma is proved. \( \square \)

We are now ready to complete the proof of Proposition 4.2. Assume \( h = h(\xi, \eta) \) is such that the RHS of (4.1) is finite. By Lemma 4.7, we have for all \( 1 \leq i \leq 4 \),

\[ \left\| \langle \xi \rangle^2 \int_1^\infty \int_{\mathbb{R}^2} e^{ita_i(\xi, \eta)} h(\xi, \eta) d\eta ds \right\|_{L^2_t} = \left\| \langle \xi \rangle^2 \int_{\mathbb{R}^2} e^{ita_i(\xi, \eta)} h(\xi, \eta) d\eta \right\|_{L^2_t}. \]

Consider first \( i = 1, 2 \). Let \( \psi \in C_c^\infty(\mathbb{R}^2) \) be such that

\[ \psi(x) = \begin{cases} 1, & |x| \leq 1, \\ 0, & |x| \geq 2. \end{cases} \]

Let \( 0 < \delta < \frac{1}{\|a_1\|} \). Then we decompose

\[ \int_{\mathbb{R}^2} e^{ita_i(\xi, \eta)} h(\xi, \eta) d\eta = \int_{\mathbb{R}^2} \frac{h(\xi, \eta)}{a_1(\xi, \eta)} (1 - \psi(\eta \xi^2) e^{ita_i(\xi, \eta)} d\eta \]

(4.41)

\[ + \int_{|\eta| \leq \frac{2|\xi|}{\delta|\xi|}} \left( \frac{h(\xi, \eta)}{a_1(\xi, \eta)} \psi(\eta \xi^2) - \frac{h(\xi, 0)}{a_1(\xi, 0)} \right) e^{ita_i(\xi, \eta)} d\eta \]

(4.42)

\[ + \int_{|\eta| \leq \frac{2|\xi|}{\delta|\xi|}} e^{ita_i(\xi, \eta)} d\eta \cdot \frac{h(\xi, 0)}{a_1(\xi, 0)}. \]

(4.43)

For (4.41), we use Lemma 4.10 and this gives us

\[ \left\| \langle \xi \rangle^2 \int_{\mathbb{R}^2} h(\xi, \eta) \left(1 - \psi(\eta \xi^2) \right) e^{ita_i(\xi, \eta)} d\eta \right\|_{L^2_t} \lesssim \sup_{\xi, \eta \in \mathbb{R}^2} \langle \xi \rangle + \langle \eta \rangle^{12} \cdot (|h(\xi, \eta)| + |\nabla \eta h(\xi, \eta)|) \cdot \|1 + \log |\xi| \cdot |\xi|^{-3}\|_{L^2_t} \]

\[ \lesssim \sup_{\xi, \eta \in \mathbb{R}^2} \langle \xi \rangle + \langle \eta \rangle^{12} \cdot (|h(\xi, \eta)| + |\nabla \eta h(\xi, \eta)|). \]
Similarly for (4.12), we use Lemma 4.9 to compute

\[
\left\| \left(\xi^2(t) \int_{|\eta| \leq 2 |\xi|^{1/2}} \frac{h(\xi, \eta)}{a_i(\xi, \eta)} \mathcal{V}_{(\eta, 0)} - \frac{h(\xi, 0)}{a_i(\xi, 0)} \right) e^{i t a_i(\xi, \eta)} d\eta \right\|_{L^2_\xi}
\]

\[
\lesssim \left\| \left(\xi^2 \sup_{|\delta| \leq 2 |\xi|^{1/2}} \left( |h(\xi, \delta) + |\nabla h(\xi, \delta)| \right) \right) \right\|_{L^2_\xi}
\]

\[
\lesssim \sup_{\xi, \eta \in \mathbb{R}^2} \left( |\xi| + |\eta| \right)^{14} \cdot \left( |h(\xi, \eta) + |\nabla h(\xi, \eta)| \right) \cdot \| (\xi)^{-3} \|_{L^2_\xi}
\]

\[
\lesssim \sup_{\xi, \eta \in \mathbb{R}^2} \left( |\xi| + |\eta| \right)^{14} \cdot \left( |h(\xi, \eta) + |\nabla h(\xi, \eta)| \right).
\]

For (4.43), we apply Lemma 4.8 Lemma 4.9 and obtain

\[
\left\| \left(\xi^2(t) \int_{|\eta| \leq 2 |\xi|^{1/2}} \frac{h(\xi, 0)}{a_i(\xi, 0)} e^{i t a_i(\xi, \eta)} d\eta \right) \right\|_{L^2_\xi}
\]

\[
\lesssim \left\| \left(\xi^9 \frac{h(\xi, 0)}{a_i(\xi, 0)} \right) \right\|_{L^2_\xi}
\]

\[
\lesssim \left\| \left(\xi^{10} h(\xi, 0) \right) \right\|_{L^2_\xi}
\]

\[
\lesssim \sup_{\xi, \eta \in \mathbb{R}^2} \left( |\xi| + |\eta| \right)^{14} \cdot \left( |h(\xi, \eta) + |\nabla h(\xi, \eta)| \right).
\]

Therefore we have shown that in the case \( i = 1, 2 \), the contribution of \( a_i \) is bounded by the RHS of (4.11). Next we consider \( i = 3, 4 \). If \( t \leq 1 \), then by Lemma 4.5 we have

\[
\left\| \left(\xi^2(t) \int_{\mathbb{R}^2} \frac{h(\xi, \eta)}{a_i(\xi, \eta)} e^{i t a_i(\xi, \eta)} d\eta \right) \right\|_{L^2_\xi}
\]

\[
\lesssim \left\| \left(\xi^2 \int_{\mathbb{R}^2} (|\xi| + |\eta|) |h(\xi, \eta)| d\eta \right) \right\|_{L^2_\xi}
\]

\[
\lesssim \sup_{\xi, \eta \in \mathbb{R}^2} \left( |\xi| + |\eta| \right)^{12} |h(\xi, \eta)|
\]

which is acceptable. If \( t \geq 1 \) and \( |\xi| \leq \frac{1}{4} \), then we also have

\[
\left\| \left(\xi^2(t) \int_{\mathbb{R}^2} \frac{h(\xi, \eta)}{a_i(\xi, \eta)} e^{i t a_i(\xi, \eta)} d\eta \right) \right\|_{L^2_\xi(|\xi| \leq \frac{1}{4})}
\]

\[
\lesssim \left\| \int_{\mathbb{R}^2} (|\xi| + |\eta|) |h(\xi, \eta)| d\eta \right\|_{L^2_\xi}
\]

\[
\lesssim \sup_{\xi, \eta \in \mathbb{R}^2} \left( |\xi| + |\eta| \right)^{12} |h(\xi, \eta)|.
\]
It remains for us to consider the case \( t \geq 1 \) and \(|\xi| \geq \frac{1}{t}\). By Lemma 4.11 we compute

\[
\left\| \langle \xi \rangle^2 \langle t \rangle \int_{\mathbb{R}^2} h(\xi, \eta) a_i(\xi, \eta) e^{ia \cdot (\xi, \eta)} d\eta \right\|_{L^2_t}
\leq \sup_{\xi, \eta \in \mathbb{R}^2} \langle |\xi| + |\eta| \rangle^{21} (|h(\xi, \eta)| + |(\partial_\eta h)(\xi, \eta)| + |(\partial^2_\eta h)(\xi, \eta)|)
\leq \frac{1}{t} \cdot \frac{1}{|\xi|^2} \left\| \tilde{\eta} \right\|_{L^2_t(|\xi| \geq \frac{1}{4})}
\leq \sup_{\xi, \eta \in \mathbb{R}^2} \langle |\xi| + |\eta| \rangle^{21} (|h(\xi, \eta)| + |(\partial_\eta h)(\xi, \eta)| + |(\partial^2_\eta h)(\xi, \eta)|).
\]

This finishes the case \( i = 3, 4 \).

\[
5. \text{ Solvability of the iteration system (3.10)–(3.11)}
\]

Since the RHS of (3.10)–(3.11) generally contains second order derivatives of \((\bar{u}^{(n)}, \bar{v}^{(n)})\), the solvability of the system is not immediately a trivial matter. However, due to the time cutoff function \( \chi_n(t) \) which vanishes for \( t \geq 2^{n+1} \), these troublesome terms involving \((\bar{u}^{(n)}, \bar{v}^{(n)})\) also drop out for \( t \geq 2^{n+1} \). Our strategy then is to solve first (3.10)–(3.11) for \( t \geq 2^{n+1} \). In this regime we can make use of the explicit representation of the solution in terms of the RHS of (3.10)–(3.11) which only involve \((\Phi_1, \Phi_2, h_2, \bar{u}^{(n-1)}, \bar{v}^{(n-1)})\). We then solve backwards the same system for \( t \leq 2^{n+1} \) with initial data \((\bar{u}^{(n)}(2^{n+1}), \bar{v}^{(n)}(2^{n+1}))\). In the latter case, the time interval is of finite length and the solvability is rather obvious since it is a linear equation for \((\bar{u}^{(n)}, \bar{v}^{(n)})\).

More precisely, we inductively assume that

\[
\|\bar{u}^{(n-1)}(t)\|_{H^m} + \|\bar{v}^{(n-1)}(t)\|_{H^m} + \|\bar{v}^{(n-1)}(t)\|_{H^m} 
\leq \frac{c}{t}. \tag{5.1}
\]

Then for \( t \geq 2^{n+1} \), we get

\[
(\Box + 1) \bar{u}^{(n)} = \nabla \cdot \left( (\bar{v}^{(n-1)} \cdot \nabla) \Phi_2 + u^{(n-1)} \nabla \Phi_1 \right) 
- \partial_t \left( (\bar{v}^{(n-1)} \cdot \nabla) \Phi_1 + u^{(n-1)} \nabla \cdot \Phi_2 \right) 
+ \nabla \cdot \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_2 + (\bar{u}^{(n-1)} + \Phi_1) \nabla h_1 
- \partial_t \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_1 + (\bar{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2, \tag{5.2}
\]

\[
(\Box + 1) \bar{v}^{(n)} = \nabla \cdot \left( (\bar{v}^{(n-1)} \cdot \nabla) \Phi_2 + u^{(n-1)} \nabla \Phi_1 \right) 
- \partial_t \left( (\bar{v}^{(n-1)} \cdot \nabla) \Phi_1 + u^{(n-1)} \nabla \cdot \Phi_2 \right) 
+ \nabla \cdot \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_2 + (\bar{u}^{(n-1)} + \Phi_1) \nabla h_1 
- \partial_t \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_1 + (\bar{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2, \tag{5.3}
\]

\[
(\Box + 1) \bar{u}^{(n)} = \nabla \cdot \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_2 + (\bar{u}^{(n-1)} + \Phi_1) \nabla h_1 
- \partial_t \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_1 + (\bar{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2. \tag{5.4}
\]

\[
(\Box + 1) \bar{v}^{(n)} = \nabla \cdot \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_2 + (\bar{u}^{(n-1)} + \Phi_1) \nabla h_1 
- \partial_t \left( \left( \bar{v}^{(n-1)} + \Phi_2 \right) \cdot \nabla \right) h_1 + (\bar{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2. \tag{5.5}
\]
and
\[
(\Box + 1)\tilde{v}^{(n)} = \nabla \left( (v^{(n-1)} \cdot \nabla)\Phi_1 + u^{(n-1)}\nabla \cdot \Phi_2 \right) \\
- \partial_t \left( (v^{(n-1)} \cdot \nabla)\Phi_2 + u^{(n-1)}\nabla \Phi_1 \right) \\
+ \nabla \left( (v^{(n-1)} + \Phi_2) \cdot \nabla h_1 + (\tilde{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2 \right) \\
- \partial_t \left( ((\tilde{v}^{(n-1)} + \Phi_2) \cdot \nabla) h_2 + (\tilde{u}^{(n-1)} + \Phi_1) \nabla h_1 \right) \\
- \nabla \Delta^{-1} \nabla \cdot (u^{(n-1)} \Phi^{(n-1)}). \tag{5.3}
\]

Observe that the RHS of (5.2) does not contain \(\tilde{u}^{(n)}\), therefore we have the explicit representation
\[
\tilde{u}^{(n)}(t) = \int_0^t \frac{\sin(t-s)}{\langle \nabla \rangle} \tilde{G}_1(\Phi_1, \Phi_2, h_1, h_2, \tilde{u}^{(n-1)}; \tilde{v}^{(n-1)})(s) ds, \tag{5.4}
\]
for \(t \geq 2^{n+1},\)

where
\[
\tilde{G}_1(\Phi_1, \Phi_2, h_1, h_2, \tilde{u}^{(n-1)}; \tilde{v}^{(n-1)}) \\
= \nabla \cdot \left( (v^{(n-1)} \cdot \nabla)\Phi_2 + u^{(n-1)}\nabla \Phi_1 \right) \tag{5.5}
- \partial_t \left( (v^{(n-1)} \cdot \nabla)\Phi_1 + u^{(n-1)}\nabla \cdot \Phi_2 \right) \tag{5.6}
+ \nabla \cdot \left( ((\tilde{v}^{(n-1)} + \Phi_2) \cdot \nabla) h_2 + (\tilde{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2 \right) \tag{5.7}
- \partial_t \left( ((\tilde{v}^{(n-1)} + \Phi_2) \cdot \nabla) h_1 + (\tilde{u}^{(n-1)} + \Phi_1) \nabla \cdot h_1 \right). \tag{5.8}
\]

Similarly for \(\tilde{v}^{(n)}(t)\) we have
\[
\tilde{v}^{(n)}(t) = \int_0^t \frac{\sin(t-s)}{\langle \nabla \rangle} \tilde{G}_2(\Phi_1, \Phi_2, h_1, h_2, \tilde{u}^{(n-1)}; \tilde{v}^{(n-1)})(s) ds, \tag{5.9}
\]
for \(t \geq 2^{n+1},\)

where
\[
\tilde{G}_2(\Phi_1, \Phi_2, h_1, h_2, \tilde{u}^{(n-1)}; \tilde{v}^{(n-1)}) \\
= \nabla \left( (v^{(n-1)} \cdot \nabla)\Phi_1 + u^{(n-1)}\nabla \cdot \Phi_2 \right) \\
- \partial_t \left( (v^{(n-1)} \cdot \nabla)\Phi_2 + u^{(n-1)}\nabla \Phi_1 \right) \\
+ \nabla \left( ((\tilde{v}^{(n-1)} + \Phi_2) \cdot \nabla) h_1 + (\tilde{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2 \right) \\
- \partial_t \left( ((\tilde{v}^{(n-1)} + \Phi_2) \cdot \nabla) h_2 + (\tilde{u}^{(n-1)} + \Phi_1) \nabla h_1 \right) \\
- \nabla \Delta^{-1} \nabla \cdot (u^{(n-1)} \Phi^{(n-1)}). \tag{5.10}
\]

For the function \((\Phi_1, \Phi_2)\), we have
\[
\|\Phi_1(s)\|_{H^{m+2}} + \|\Phi_2(s)\|_{H^{m+2}} + \|(\Phi_1(s))'\|_{H^{m+1}} \\
+ \|(\Phi_2(s))'\|_{H^{m+1}} \lesssim \frac{\epsilon}{\langle s \rangle}, \quad \forall s \geq 0. \tag{5.11}
\]
Also for \((h_1, h_2)\), we have the estimate
\[
\|h_1(s)\|_{L^\infty_x} + \|\partial_s h_1(s)\|_{L^\infty_x} + \|D^{m+2} h_1(s)\|_{L^\infty_x}
+ \|\partial_s D^{m+1} h_1(s)\|_{L^\infty_x} \lesssim \frac{\epsilon}{(s)^{1/2}} \quad \forall s \geq 0.
\] (5.12)

\[
\|h_2(s)\|_{L^\infty_x} + \|\partial_s h_2(s)\|_{L^\infty_x} + \|D^{m+2} h_2(s)\|_{L^\infty_x}
+ \|\partial_s D^{m+1} h_2(s)\|_{L^\infty_x} \lesssim \frac{\epsilon}{(s)^{1/2}} \quad \forall s \geq 0.
\] (5.13)

Recall that
\[
\tilde{u}^{(n-1)} = \bar{u}^{(n-1)} + \Phi_1 + h_1,
\]
\[
\tilde{v}^{(n-1)} = \bar{v}^{(n-1)} + \Phi_2 + h_2.
\]

Therefore by (5.1), (5.11) - (5.13), we have
\[
\|\nabla \cdot \left((v^{(n-1)}(s) \cdot \nabla) \Phi_2(s) + \bar{u}^{(n-1)}(s) \nabla \Phi_1(s)\right)\|_{H^m}
\lesssim \|\nabla \cdot \left(h_2(s) \cdot \nabla \Phi_2(s)\right)\|_{H^m} + \|\nabla \cdot \left(h_1(s) \nabla \Phi_1(s)\right)\|_{H^m}
+ \|\nabla \cdot \left(\Phi_2(s) \cdot \nabla \Phi_2(s)\right)\|_{H^m} + \|\nabla \cdot \left(\Phi_1(s) \nabla \Phi_1(s)\right)\|_{H^m}
\lesssim \|v^{(n-1)}(s)\|_{H^m} \cdot \|\Phi_2(s)\|_{H^{m+2}} + \|\bar{u}^{(n-1)}(s)\|_{H^m} \cdot \|\Phi_1(s)\|_{H^{m+2}}
+ \left(\|h_2(s)\|_{L^\infty_x} + \|D^{m+2} h_2(s)\|_{L^\infty_x}\right) \cdot \|\Phi_2(s)\|_{H^{m+2}}
+ \left(\|h_1(s)\|_{L^\infty_x} + \|D^{m+1} h_1(s)\|_{L^\infty_x}\right) \cdot \|\Phi_1(s)\|_{H^{m+2}}
+ \|\Phi_2(s)\|_{H^m}^2 + \|\Phi_1(s)\|_{H^m}^2
\lesssim \frac{\epsilon^2}{(s)^2}.
\]

The remaining terms (5.6) - (5.8) can be estimated in a similar fashion. Collecting the estimates, we get
\[
\|\tilde{G}_1(\Phi_1, \Phi_2, h_1, h_2, \bar{u}^{(n-1)}, \bar{v}^{(n-1)})(s)\|_{H^m} \lesssim \frac{\epsilon^2}{(s)^{1/2}}.
\]

By (5.4), we then compute
\[
\|\partial_t \tilde{u}^{(n)}(t)\|_{H^m} \lesssim \int_t^{\infty} \|\tilde{G}_1(\Phi_1, \Phi_2, h_1, h_2, \bar{u}^{(n-1)}, \bar{v}^{(n-1)})(s)\|_{H^m} ds
\lesssim \int_t^{\infty} \frac{\epsilon^2}{(s)^2} ds
\lesssim \frac{\epsilon^2}{(t)}, \quad \forall t \geq 2^{n+1}.
\]

Similarly
\[
\|\tilde{u}^{(n)}(t)\|_{H^m} + \|\partial_x \tilde{u}^{(n)}(t)\|_{H^m} \lesssim \frac{\epsilon^2}{(t)}, \quad \forall t \geq 2^{n+1}.
\]
Therefore
\[ \| \tilde{u}^{(n)}(t) \|_{H^m} + \|(\tilde{u}^{(n)}(t))' \|_{H^m} \lesssim \frac{\epsilon^2}{(\ell)}, \quad \forall t \geq 2^{n+1}. \]  
(5.14)

By using similar estimates, we obtain from
\[ \| \tilde{v}^{(n)}(t) \|_{H^m} + \|(\tilde{v}^{(n)}(t))' \|_{H^m} \lesssim \frac{\epsilon^2}{(\ell)}, \quad \forall t \geq 2^{n+1}. \]  
(5.15)

The estimates (5.14)–(5.15) are consistent with the inductive assumption (5.1) on the time interval \([2^{n+1}, \infty)\). However, we still have to solve (3.10)–(3.11) for \(0 \leq t \leq 2^{n+1}\). Since we have obtained the solution on the time interval \([2^{n+1}, \infty)\), we can use \((\tilde{u}^{(n)}(2^{n+1}), \tilde{v}^{(n)}(2^{n+1}))\) as initial data which is explicitly given by (5.4)–(5.9), i.e.
\[ \tilde{u}^{(n)}(2^{n+1}) = \int_{\infty}^{2^{n+1}} \sin(2^{n+1} - s) \langle \nabla \rangle G_1(\Phi_1, \Phi_2, h_1, h_2, \tilde{u}^{(n-1)}(s) ds, \]
\[ \tilde{v}^{(n)}(2^{n+1}) = \int_{\infty}^{2^{n+1}} \sin(2^{n+1} - s) \langle \nabla \rangle G_2(\Phi_1, \Phi_2, h_1, h_2, \tilde{v}^{(n-1)}(s) ds. \]

Using this information, we then solve backwards (3.10)–(3.11) until \(t = 0\). This way we have obtained the solution \((\tilde{u}^{(n)}(t), \tilde{v}^{(n)}(t))\) well defined for all \(t \geq 0\). Furthermore, since \([0, 2^{n+1}]\) is a finite time interval and \((\tilde{u}^{(n)}(t), \tilde{v}^{(n)}(t))\) enjoys the decay estimate (6.2), we have
\[ \| \tilde{u}^{(n)}(t) \|_{H^m} + \| \tilde{v}^{(n)}(t) \|_{H^m} + \|(\tilde{u}^{(n)}(t))' \|_{H^m} \]
\[ + \| (\tilde{v}^{(n)}(t))' \|_{H^m} \lesssim \frac{K_n}{(\ell)}, \quad \forall t \geq 0, \]  
(5.16)

where \(K_n\) is a constant depending on the iteration step \(n\). Because of the dependence on \(n\), the estimate (5.16) is certainly not good for us since we have to justify the inductive assumption (5.1) for step \(n\). Nevertheless it is an important a priori estimate for our argument later. In the next section we shall upgrade the estimate (5.16) to the true decay estimate (5.1).

6. A PRIORI ENERGY ESTIMATES OF THE ITERATION SYSTEM (3.10)–(3.11)

In this section we carry out basic energy estimates for the iteration system (3.10)–(3.11). Our standing inductive assumption is
\[ \| \tilde{u}^{(n-1)}(t) \|_{H^m} + \|(\tilde{u}^{(n-1)}(t))' \|_{H^m} + \| \psi^{(n-1)}(t) \|_{H^m} \]
\[ + \| (\psi^{(n-1)}(t))' \|_{H^m} \lesssim \frac{\epsilon}{(\ell)}. \]  
(6.1)

For the functions \((\Phi_1, \Phi_2)\), recall the estimate
\[ \| \Phi_1(t) \|_{H^{m+2}} + \| \Phi_2(t) \|_{H^{m+2}} + \| (\Phi_1(t))' \|_{H^{m+1}} \]
\[ + \| (\Phi_2(t))' \|_{H^{m+1}} \lesssim \frac{\epsilon}{(\ell)}, \quad \forall t \geq 0. \]  
(6.2)
Also for \((h_1, h_2)\), we shall use the estimate

\[
\|h_1(t)\|_{L^\infty} + \|\partial_t h_1(t)\|_{L^\infty} + \|D^{m+2}h_1(t)\|_{L^\infty} + \|\partial_t D^{m+1}h_1(t)\|_{L^\infty} \lesssim \frac{\epsilon}{(t)^{1/2}}, \quad \forall \ t \geq 0. \tag{6.3}
\]

\[
\|h_2(t)\|_{L^\infty} + \|\partial_t h_2(t)\|_{L^\infty} + \|D^{m+2}h_2(t)\|_{L^\infty} + \|\partial_t D^{m+1}h_2(t)\|_{L^\infty} \lesssim \frac{\epsilon}{(t)^{1/2}}, \quad \forall \ t \geq 0. \tag{6.4}
\]

Our task is to justify the estimate \([6.1]\) for \((\bar{u}^{(n)}, \bar{v}^{(n)})\). For the convenience of notations, we introduce

\[
A_n(t) = \|\bar{u}^{(n)}(t)\|_{H^m} + \|\bar{u}^{(n)}(t)'\|_{H^m} + \|\bar{v}^{(n)}(t)\|_{H^m} + \|\bar{v}^{(n)}(t)'\|_{H^m}, \quad \forall \ n \geq 0.
\]

Take \(D^\alpha\) derivative on both sides of \([6.10]\) and multiply by the factor \(\partial_t D^\alpha \bar{u}^{(n)}\). Integrating by parts and summing over \(|\alpha| \leq m\), we obtain

\[
\frac{1}{2} \frac{d}{dt} \left( \sum_{|\alpha| \leq m} \|D^\alpha \bar{u}^{(n)}(t)\|_{L^2}^2 + \|D^\alpha \bar{u}^{(n)}(t)'\|_{L^2}^2 \right) = \chi_n(t) \sum_{|\alpha| \leq m} \int_{\mathbb{R}^2} D^\alpha \left( \nabla \cdot \left( (\bar{v}^{(n-1)} \cdot \nabla) (\bar{v}^{(n)} + u^{(n-1)} \nabla \bar{u}^{(n)}) \right) \right) \partial_t D^\alpha \bar{u}^{(n)}(t) dx \tag{6.5}
\]

\[
- \chi_n(t) \sum_{|\alpha| \leq m} \int_{\mathbb{R}^2} D^\alpha \partial_t \left( (\bar{v}^{(n-1)} \cdot \nabla) (\bar{u}^{(n)} + u^{(n-1)} \nabla \bar{v}^{(n)} \cdot \bar{v}^{(n)}) \right) \partial_t D^\alpha \bar{u}^{(n)}(t) dx \tag{6.6}
\]

\[
+ \sum_{|\alpha| \leq m} \int_{\mathbb{R}^2} D^\alpha \nabla \cdot \left( (\bar{v}^{(n-1)} \cdot \nabla) \Phi_2 + u^{(n-1)} \nabla \Phi_1 \right) \partial_t D^\alpha \bar{u}^{(n)}(t) dx \tag{6.7}
\]

\[
- \sum_{|\alpha| \leq m} \int_{\mathbb{R}^2} D^\alpha \partial_t \left( (\bar{v}^{(n-1)} \cdot \nabla) \Phi_1 + u^{(n-1)} \nabla \cdot \Phi_2 \right) \partial_t D^\alpha \bar{u}^{(n)}(t) dx \tag{6.8}
\]

\[
+ \sum_{|\alpha| \leq m} \int_{\mathbb{R}^2} D^\alpha \nabla \cdot \left( (\bar{v}^{(n-1)} + \Phi_2) \cdot \nabla \right) h_2 + (\bar{u}^{(n-1)} + \Phi_1) \nabla h_1 \partial_t D^\alpha \bar{u}^{(n)}(t) dx \tag{6.9}
\]

\[
- \sum_{|\alpha| \leq m} \int_{\mathbb{R}^2} D^\alpha \partial_t \left( (\bar{v}^{(n-1)} + \Phi_2) \cdot \nabla \right) h_1 + (\bar{u}^{(n-1)} + \Phi_1) \nabla \cdot h_2 \partial_t D^\alpha \bar{u}^{(n)}(t) dx. \tag{6.10}
\]
We first deal with (6.5). By using integration by parts and Leibniz in time, we write

\[ (6.11) = \chi_n(t) \sum_{|\alpha| \leq m-1} \int_{\mathbb{R}^2} D^\alpha \nabla \cdot \left( (\psi^{(n-1)} \cdot \nabla)(\tilde{v}^{(n)}) + u^{(n-1)} \nabla \tilde{u}^{(n)} \right) \partial_t D^\alpha \tilde{u}^{(n)} \, dx \]

\[ + \frac{d}{dt} \left( \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} v^{(n-1)}_j D^\alpha \partial_{x_j} \partial_{x_i} v^{(n)}_i D^\alpha \tilde{u}^{(n)} \, dx \right) \]  

\[ - \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} \partial_t v^{(n-1)}_j D^\alpha \partial_{x_j} \partial_{x_i} \tilde{v}^{(n)}_i D^\alpha \tilde{u}^{(n)} \, dx \]

\[ - \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} v^{(n-1)}_j \partial_t D^\alpha \partial_{x_j} \partial_{x_i} \tilde{v}^{(n)}_i D^\alpha \tilde{u}^{(n)} \, dx. \]  

By using (6.1), (6.2)–(6.4) and Sobolev embedding, we compute the absolute value of (6.11) as follows

\[ |(6.11)| \lesssim \sum_{|\alpha| \leq m-1} \sum_{|\beta| \leq |\alpha| + 1} \int_{\mathbb{R}^2} |D^\beta \psi^{(n-1)}| \cdot |D^{\alpha+2-\beta} \tilde{v}^{(n)}| \cdot |\partial_t D^\alpha \tilde{u}^{(n)}| \, dx \]

\[ + \int_{\mathbb{R}^2} |D^\beta \tilde{u}^{(n-1)}| \cdot |D^{\alpha+2-\beta} \tilde{u}^{(n)}| \cdot |\partial_t D^\alpha \tilde{u}^{(n)}| \, dx \]

\[ \lesssim \sum_{|\alpha| \leq m-1} \sum_{|\beta| \leq |\alpha| + 1} \|D^\beta \psi^{(n-1)}(t)\|_{L^\infty} \cdot \|D^{\alpha+2-\beta} \tilde{v}^{(n)}(t)\|_{L^2} \cdot \|\partial_t D^\alpha \tilde{u}^{(n)}(t)\|_{L^2} \]

\[ + \|D^\beta h_1(t)\|_{L^\infty} \cdot \|D^{\alpha+2-\beta} \tilde{u}^{(n)}(t)\|_{L^2} \cdot \|\partial_t D^\alpha \tilde{u}^{(n)}(t)\|_{L^2} \]

\[ + \sum_{|\alpha| \leq m-1} \sum_{|\beta| \leq |\alpha| + 1} \|D^\beta \psi^{(n-1)}(t)\|_{L^\infty} \cdot \|D^{\alpha+2-\beta} \tilde{v}^{(n)}(t)\|_{L^2} \cdot \|\partial_t D^\alpha \tilde{u}^{(n)}(t)\|_{L^2} \]

\[ + \sum_{|\alpha| \leq m-1} \sum_{|\beta| > |\alpha| + 1} \|D^\beta \tilde{u}^{(n-1)}(t)\|_{L^\infty} \cdot \|D^{\alpha+2-\beta} \tilde{u}^{(n)}(t)\|_{L^2} \cdot \|\partial_t D^\alpha \tilde{u}^{(n)}(t)\|_{L^2} \]

\[ + \frac{c}{t} A_n(t)^2. \]

The term (6.12) will be absorbed into the LHS of (6.5). To bound (6.13), note that

\[ |\chi_n'(t)| \leq 2^{-n} |\chi'(2^{-n} t)| \lesssim 1, \quad \forall n \geq 0, \quad t \geq 0. \]
By using integration by parts, (6.1)–(6.4) and Sobolev embedding, we obtain

\[ |(6.13)| \lesssim \sum_{|\alpha| = m, 1 \leq i, j \leq 1} \left( \| v_j^{(n-1)}(t) \|_{L^\infty_x} + \| \partial_{x_j} v_j^{(n-1)}(t) \|_{L^\infty_x} \right) A_n(t)^2 \]

\[ \lesssim (\| h_2(t) \|_{L^\infty_x} + \| Dh_2(t) \|_{L^\infty_x} + \| \Phi_2(t) \|_{H^m} + \| \bar{v}^{(n-1)}(t) \|_{H^m}) A_n(t)^2 \]

\[ \lesssim \frac{\epsilon}{(t)} A_n(t)^2. \]

Proceeding in a similar manner, we also obtain

\[ |(6.14)| \lesssim \frac{\epsilon}{(t)} A_n(t)^2. \]

For (6.15) we shall integrate by parts twice and this gives us

\[ |(6.15)| = -\chi_n(t) \sum_{|\alpha| = m, 1 \leq i, j \leq 2} \int_{\mathbb{R}^2} v_j^{(n-1)}(x) \partial_i D^\alpha \bar{v}_i^{(n)}(x) \partial_{x_j} D^\alpha \bar{u}^{(n)}(x) dx \] (6.16)

\[ + \chi_n(t) \sum_{|\alpha| = m, 1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_{x_j} v_j^{(n-1)}(x) \partial_i D^\alpha \bar{v}_i^{(n)}(x) D^\alpha \bar{u}^{(n)}(x) dx \] (6.17)

\[ - \chi_n(t) \sum_{|\alpha| = m, 1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_i v_i^{(n-1)}(x) \partial_{x_j} D^\alpha \bar{v}_i^{(n)}(x) \partial_{x_j} D^\alpha \bar{u}^{(n)}(x) dx \] (6.18)

We shall keep the term (6.16) since it will cancel with the corresponding term obtained in the calculation of \( \bar{v}^{(n)} \) later. The term (6.17) can be bounded after one more integration by parts in \( \partial_{x_i} \) and this will give us

\[ |(6.17)| \lesssim \frac{\epsilon}{(t)} A_n(t)^2. \]

The term (6.18) can be bounded in a similar way as (6.13) and we get

\[ |(6.18)| \lesssim \frac{\epsilon}{(t)} A_n(t)^2. \]

Collecting all the estimates, we obtain

\[ |(6.5)| = \frac{d}{dt} \left( \chi_n(t) \sum_{|\alpha| = m, 1 \leq i, j \leq 2} \int_{\mathbb{R}^2} v_j^{(n-1)}(x) \partial_i D^\alpha \bar{v}_i^{(n)}(x) \partial_{x_j} D^\alpha \bar{u}^{(n)}(x) dx \right) \]

\[ - \chi_n(t) \sum_{|\alpha| = m, 1 \leq i, j \leq 2} \int_{\mathbb{R}^2} v_j^{(n-1)}(x) \partial_i D^\alpha \bar{v}_i^{(n)}(x) \partial_{x_j} D^\alpha \bar{u}^{(n)}(x) dx \]

\[ + E_1, \]

where

\[ |E_1| \lesssim \frac{\epsilon}{(t)} A_n(t)^2. \]
Next we consider \(6.6\) and write it as
\[
6.6 = -\chi_n(t) \sum_{|\alpha| \leq m-1} \int_{\mathbb{R}^2} \partial_t D^\alpha \left( (\psi^{(n-1)} \cdot \nabla) \bar{u}^{(n)} + u^{(n-1)} \nabla \cdot (\bar{\psi}^{(n)}) \right) \partial_t D^\alpha \bar{u}^{(n)} dx \tag{6.19}
\]
\[
- \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} D^\alpha \partial_t \left( (\psi^{(n-1)} \cdot \nabla) \bar{u}^{(n)} \right) \partial_t D^\alpha \bar{u}^{(n)} dx \tag{6.20}
\]
\[
- \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} D^\alpha \partial_t \left( u^{(n-1)} \nabla \cdot (\bar{\psi}^{(n)}) \right) \partial_t D^\alpha \bar{u}^{(n)} dx. \tag{6.21}
\]

The term \(6.19\) can be easily bounded by
\[
\left| 6.19 \right| \lesssim \frac{\epsilon}{t} A_n(t)^2.
\]

For \(6.20\), by using integration by parts, \(6.1\)–\(6.4\), Sobolev embedding and proceeding in the similar way as in the estimate of \(6.5\), we obtain
\[
\left| 6.20 \right| \lesssim \sum_{|\alpha| = m} \int_{\mathbb{R}^2} D^\alpha \left( (\partial_t \psi^{(n-1)} \cdot \nabla) \bar{u}^{(n)} \right) \partial_t D^\alpha \bar{u}^{(n)} dx + \sum_{|\alpha| = m} \int_{\mathbb{R}^2} D^\alpha \left( \psi^{(n-1)} \cdot \nabla \partial_t \bar{u}^{(n)} \right) \partial_t D^\alpha \bar{u}^{(n)} dx
\]
\[
\lesssim \sum_{|\alpha| = m} \sum_{|\beta| \leq |\alpha|} \int_{\mathbb{R}^2} |\partial_t D^{\alpha-\beta} \psi^{(n-1)}| \cdot |\nabla D^\beta \bar{u}^{(n)}| \cdot |\partial_t D^\alpha \bar{u}^{(n)}| dx + \sum_{|\alpha| = m} \sum_{|\beta| < |\alpha|} \int_{\mathbb{R}^2} |D^{\alpha-\beta} \psi^{(n-1)}| \cdot |\nabla D^\beta \partial_t \bar{u}^{(n)}| \cdot |\partial_t D^\alpha \bar{u}^{(n)}| dx
\]
\[
+ \sum_{|\alpha| = m} \int_{\mathbb{R}^2} \left( \psi^{(n-1)} \cdot \nabla \right) D^\alpha \partial_t \bar{u}^{(n)} \cdot \partial_t D^\alpha \bar{u}^{(n)} dx \lesssim \frac{\epsilon}{t} A_n(t)^2.
\]

For \(6.21\), we use Leibniz in time and write it as
\[
6.21 = - \sum_{|\alpha| = m} \int_{\mathbb{R}^2} D^\alpha \left( \partial_t u^{(n-1)} \nabla \cdot \bar{\psi}^{(n)} \right) \partial_t D^\alpha \bar{u}^{(n)} dx \tag{6.22}
\]
\[
- \sum_{|\alpha| = m} \int_{\mathbb{R}^2} D^\alpha \left( u^{(n-1)} \partial_t \nabla \cdot \bar{\psi}^{(n)} \right) \partial_t D^\alpha \bar{u}^{(n)} dx. \tag{6.23}
\]

We can easily bound \(6.22\) as
\[
\left| 6.22 \right| \lesssim \sum_{|\alpha| = m} \sum_{|\beta| \leq |\alpha|} \int_{\mathbb{R}^2} |D^{\beta} \partial_t u^{(n-1)}| \cdot |D^{\alpha-\beta} \nabla \cdot \bar{\psi}^{(n)}| \cdot |\partial_t D^\alpha \bar{u}^{(n)}| dx \lesssim \frac{\epsilon}{t} A_n(t)^2.
\]
On the other hand for (6.23), we further decompose it into

\[
(6.23) = - \sum_{|\alpha|=m} \int_{\mathbb{R}^2} u^{(n-1)} D^n \nabla \cdot \bar{v}^{(n)} \partial_i D^n \bar{u}^{(n)} dx
\]

\[
- \sum_{|\alpha|=m} \sum_{0<|\beta| \leq |\alpha|} \left( \frac{\alpha}{\beta} \right) \int_{\mathbb{R}^2} D^\beta u^{(n-1)} D^{\alpha-\beta} \partial_i \nabla \cdot \bar{v}^{(n)} \partial_i D^n \bar{u}^{(n)} dx
\]

\[
= \sum_{|\alpha|=m} \int_{\mathbb{R}^2} u^{(n-1)} \partial_i D^n \bar{v}^{(n)} \cdot \nabla \partial_i D^n \bar{u}^{(n)} dx \quad (6.24)
\]

\[
+ \sum_{|\alpha|=m} \int_{\mathbb{R}^2} \left( \nabla u^{(n-1)} \cdot \partial_i D^n \bar{v}^{(n)} \right) \partial_i D^n \bar{u}^{(n)} dx \quad (6.25)
\]

\[
- \sum_{|\alpha|=m} \sum_{0<|\beta| \leq |\alpha|} \left( \frac{\alpha}{\beta} \right) \int_{\mathbb{R}^2} D^\beta u^{(n-1)} D^{\alpha-\beta} \partial_i \nabla \cdot \bar{v}^{(n)} \partial_i D^n \bar{u}^{(n)} dx. \quad (6.26)
\]

We shall keep the term (6.24) since it will cancel with a corresponding term arising from the calculation of $\bar{v}^{(n)}$ later. The terms (6.25), (6.26) can be bounded in the same way as the calculation of (6.5) and this gives us

\[
| (6.24) | + | (6.26) | \lesssim \frac{\epsilon A_n(t)^2}{(t)}.
\]

Collecting all the estimates, we obtain

\[
(6.6) = \sum_{|\alpha|=m} \int_{\mathbb{R}^2} u^{(n-1)} \partial_i D^n \varphi^{(n)} \cdot \nabla \partial_i D^n \bar{u}^{(n)} dx + E_2,
\]

where

\[
|E_2| \lesssim \frac{\epsilon}{(t)} A_n(t)^2.
\]

We still have to bound the terms (6.7)–(6.10). The estimates of these terms can be done in a similar manner as that of (6.5). We omit the tedious computations and write the final result as

\[
| (6.7) | + | (6.8) | + | (6.9) | + | (6.10) | \lesssim \frac{\epsilon^2}{(t)^2} A_n(t).
\]
Putting together all the estimates, we have the expression

\[
\frac{1}{2} \frac{d}{dt} \left( \sum_{|\alpha| \leq m} \| D^\alpha \bar{u}^{(n)}(t) \|_{L^2_x}^2 + \| \left( D^\alpha \bar{u}^{(n)}(t) \right)' \|_{L^2_x}^2 \right) = \frac{d}{dt} \left( \chi_n(t) \right) \sum_{|\alpha| = m} \left( \int_{\mathbb{R}^2} v_j^{(n-1)} D^\alpha \partial_x \partial_x \bar{v}_i^{(n)} D^\alpha \bar{u}^{(n)}(x) dx \right) \\
- \chi_n(t) \sum_{|\alpha| = m} \left( \int_{\mathbb{R}^2} v_j^{(n-1)} D^\alpha \bar{v}_i^{(n)} \partial_x \partial_x D^\alpha \bar{u}^{(n)}(x) dx \right) \\
+ \sum_{|\alpha| = m} \int_{\mathbb{R}^2} u^{(n-1)} D^\alpha v^{(n)} \cdot \nabla \partial_t D^\alpha \bar{u}^{(n)}(x) dx \\
+ F_1 + F_2,
\]

where

\[
|F_1(t)| \lesssim \frac{\epsilon}{(t)} A_n(t)^2, \\
|F_2(t)| \lesssim \frac{\epsilon^2}{(t)^2} A_n(t).
\]

Next we consider the bounds on \( \bar{v}^{(n)} \) by using (3.11). Proceeding in a similar fashion as in the computation of \( \bar{u}^{(n)} \), we obtain

\[
\frac{1}{2} \frac{d}{dt} \left( \sum_{|\alpha| \leq m} \| D^\alpha \bar{v}^{(n)}(t) \|_{L^2_x}^2 + \| \left( D^\alpha \bar{v}^{(n)}(t) \right)' \|_{L^2_x}^2 \right) = \frac{d}{dt} \left( \chi_n(t) \right) \sum_{|\alpha| = m} \left( \int_{\mathbb{R}^2} v_j^{(n-1)} D^\alpha \partial_x \partial_x \bar{v}_i^{(n)} D^\alpha \bar{u}^{(n)}(x) dx \right) \\
- \chi_n(t) \sum_{|\alpha| = m} \left( \int_{\mathbb{R}^2} v_j^{(n-1)} D^\alpha \bar{v}_i^{(n)} \partial_x \partial_x D^\alpha \bar{u}^{(n)}(x) dx \right) \\
+ \sum_{|\alpha| = m} \int_{\mathbb{R}^2} u^{(n-1)} D^\alpha \nabla \cdot \nabla \partial_t D^\alpha \bar{u}^{(n)}(x) \partial_t \bar{v}^{(n)} dx \\
+ F_3 + F_4,
\]

where

\[
|F_3(t)| \lesssim \frac{\epsilon}{(t)} A_n(t)^2, \\
|F_4(t)| \lesssim \frac{\epsilon^2}{(t)^2} A_n(t).
\]
Denote
\[ B_n(t)^2 = \frac{1}{2} \left( \sum_{|\alpha| \leq m} \left\| D^\alpha \bar{u}^{(n)}(t) \right\|_{L^2_x}^2 + \left\| \left( D^\alpha \bar{u}^{(n)}(t) \right)' \right\|_{L^2_x}^2 \right. \]
\[ + \sum_{|\alpha| \leq m} \left\| D^\alpha \bar{v}^{(n)}(t) \right\|_{L^2_x}^2 + \left\| \left( D^\alpha \bar{v}^{(n)}(t) \right)' \right\|_{L^2_x}^2 \]
\[ + \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} \partial_{x_i} \bar{v}^{(n-1)}(x) D^\alpha \partial_{x_i} \bar{u}^{(n)}(x) dx \] (6.29)
\[ + \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} \bar{v}^{(n-1)}(x) D^\alpha \partial_{x_i} \bar{v}^{(n)}(x) \partial_{x_j} \partial_{x_i} \bar{u}^{(n)}(x) dx \] (6.30)
\[ - \chi_n(t) \sum_{|\alpha| = m} \int_{\mathbb{R}^2} u^{(n-1)}(x) D^\alpha \nabla \cdot \bar{v}^{(n)}(x) dx. \] (6.31)

By using (6.1)–(6.4), we have
\[ \left| (6.29) \right| + \left| (6.30) \right| + \left| (6.31) \right| \lesssim \epsilon \cdot \frac{1}{t} \left( \sum_{|\alpha| \leq m} \left\| D^\alpha \bar{u}^{(n)}(t) \right\|_{L^2_x}^2 + \left\| \left( D^\alpha \bar{u}^{(n)}(t) \right)' \right\|_{L^2_x}^2 \right. \]
\[ + \sum_{|\alpha| \leq m} \left\| D^\alpha \bar{v}^{(n)}(t) \right\|_{L^2_x}^2 + \left\| \left( D^\alpha \bar{v}^{(n)}(t) \right)' \right\|_{L^2_x}^2 \right). \]

Therefore for \( \epsilon \) sufficiently small (depending only on an absolute constant), we have
\[ \frac{1}{C} B_n(t) \leq A_n(t) \leq C B_n(t), \] (6.32)
where \( C \) is some absolute constant. Adding together (6.27) and (6.28) and using (6.32), we have
\[ \left| \frac{d}{dt} B_n(t) \right| \lesssim \epsilon \cdot \frac{1}{t} B_n(t) + \frac{\epsilon^2}{(t^2)^2}, \quad t \geq 0, \] (6.33)
where we have canceled a factor of \( B_n(t) \) on both sides of the inequality.

By (5.16) and (6.32), we have the rough estimate
\[ |B_n(t)| \lesssim \frac{K_n}{t}, \quad \forall t \geq 0, \] (6.34)
where \( K_n \) is a constant depending on the iteration number \( n \).

We now need the following

**Lemma 6.1** (Infinite time Gronwall lemma). Let \( B(t) \) be a nonnegative smooth function on \([1, \infty)\) satisfying
\[ \left| \frac{d}{dt} B(t) \right| \leq \frac{\epsilon}{t} B(t) + \frac{\delta}{t^2} \] (6.35)
and
\[ B(t) \leq \frac{K}{t}, \quad \forall t \geq 1. \] (6.36)
Here $0 < \epsilon < 1$, $\delta > 0$, $K > 0$ are constants. Then

$$B(t) \leq \frac{\delta \cdot 1}{1 - \epsilon} \cdot \frac{1}{t}, \quad \forall t \geq 1. \quad (6.37)$$

**Remark 6.2.** The crucial point here is that the final bound on $B(t)$ is independent of the constant $K$.

**Proof.** By Fundamental Theorem of Calculus and plugging the estimate (6.36) into (6.35), we obtain

$$B(t) \leq \int_{t}^{\infty} \left( \frac{\epsilon \cdot K}{\tau} + \frac{\delta}{\tau^2} \right) d\tau \leq \frac{K \epsilon + \delta}{t}.$$ We inductively assume $j \geq 0$,

$$B(t) \leq \frac{K \epsilon^{j+1} + \delta(1 + \cdots + \epsilon^j)}{t}.$$ Then for $j + 1$, using (6.35) we have

$$\left| \frac{d}{dt} B(t) \right| \leq \frac{1}{t^2} \cdot \left( \epsilon (K \epsilon^{j+1} + \delta (1 + \cdots + \epsilon^j)) + \delta \right) \leq \frac{1}{t^2} \left( K \epsilon^{j+2} + \delta (1 + \cdots + \epsilon^{j+1}) \right).$$

Using again the fundamental theorem of calculus we conclude that the inductive estimate holds for all $j$. Taking $j \to \infty$ we obtain (6.37). □

By Lemma 6.1 and (6.33), (6.34), we obtain for $\epsilon$ sufficiently small

$$B_n(t) \lesssim \frac{\epsilon}{t}. \quad (6.38)$$

The extra power of $\epsilon$ can be used to kill the underlying implied constants. Therefore the inductive assumption (6.1) also holds for step $n$ with the same underlying constant. Hence we obtain the following: there exists a constant $C > 0$, such that for all $n \geq 0$,

$$\| \tilde{u}^{(n)}(t) \|_{H^m} + \| (\hat{a}^{(n)}(t))' \|_{H^m} + \| \tilde{v}^{(n)}(t) \|_{H^m} + \| (\hat{v}^{(n)}(t))' \|_{H^m} \leq C \frac{\epsilon}{t}, \quad \forall t \geq 0. \quad (6.39)$$

**Remark 6.3.** Since the bound (6.38) is slightly stronger than the inductive bound (6.1), one may wonder whether the bound (6.1) is optimal in terms of the power of $\epsilon$. Indeed by revisiting the inequality (6.33) and Lemma 6.1, one can easily derive the bound

$$B_n(t) \lesssim \frac{\epsilon}{t}, \quad \forall n \geq 0,$$
from which it follows that

$$
\|\bar{u}^{(n)}(t)\|_{H^m} + \|\bar{v}^{(n)}(t)\|_{H^m} + \|\bar{v}^{(n)}(t)\|_{H^m}
$$

$$
+ \|\bar{v}^{(n)}(t)\|_{H^m} \leq C \frac{\epsilon^2}{(t)} \quad \forall \ t \geq 0, \ n \geq 0.
$$

7. Contraction estimates and existence of the smooth solution

In this section we shall show that the sequence \((\bar{u}^{(n)}, \bar{v}^{(n)})\) forms a Cauchy sequence in some suitable metric. Define

$$
U^{(n)} = \bar{u}^{(n)} - \bar{u}^{(n-1)}
$$

$$
V^{(n)} = \bar{v}^{(n)} - \bar{v}^{(n-1)}.
$$

From (3.10), (3.11), we get

$$
(\Box + 1)U^{(n)} = \chi_n(t) \nabla \cdot \left( (V^{(n-1)} \cdot \nabla)\bar{v}^{(n)} + U^{(n-1)} \nabla \bar{v}^{(n)} \right)
$$

$$
+ \chi_n(t) \nabla \cdot \left( (V^{(n-2)} \cdot \nabla)\bar{v}^{(n)} + u^{(n-2)} \nabla U^{(n)} \right)
$$

$$
+ (\chi_n(t) - \chi_{n-1}(t)) \nabla \cdot \left( (V^{(n-2)} \cdot \nabla)\bar{v}^{(n-1)} + u^{(n-2)} \nabla \bar{v}^{(n-1)} \right)
$$

$$
- \chi_n(t) \partial_t \left( (V^{(n-1)} \cdot \nabla)\bar{u}^{(n)} + U^{(n-1)} \nabla \bar{v}^{(n)} \right)
$$

$$
- \chi_n(t) \partial_t \left( (V^{(n-2)} \cdot \nabla)U^{(n)} + u^{(n-2)} \nabla \bar{v}^{(n)} \right)
$$

$$
- (\chi_n(t) - \chi_{n-1}(t)) \partial_t \left( (V^{(n-2)} \cdot \nabla)\bar{u}^{(n-1)} + u^{(n-2)} \nabla \bar{v}^{(n-1)} \right)
$$

$$
+ \nabla \cdot \left( (V^{(n-1)} \cdot \nabla) \Phi_2 + U^{(n-1)} \nabla \Phi_1 \right)
$$

$$
- \partial_t \left( (V^{(n-1)} \cdot \nabla) \Phi_1 + U^{(n-1)} \nabla \Phi_2 \right)
$$

$$
+ \nabla \cdot \left( (V^{(n-1)} \cdot \nabla) h_2 + U^{(n-1)} \nabla h_1 \right)
$$

$$
- \partial_t \left( (V^{(n-1)} \cdot \nabla) h_1 + U^{(n-1)} \nabla h_2 \right),
$$

(7.1)
\[(\square + 1)V^{(n)} = \chi_n(t)\nabla \left( (V^{(n-1)} \cdot \nabla)\tilde{u}^{(n)} + U^{(n-1)} \nabla \cdot \tilde{v}^{(n)} \right)
+ \chi_n(t)\nabla \left( (v^{(n-2)} \cdot \nabla)(U^{(n)}) + u^{(n-2)} \nabla \cdot V^{(n)} \right)
+ (\chi_n(t) - \chi_{n-1}(t))\nabla \left( (v^{(n-2)} \cdot \nabla)(u^{(n-1)}) + U^{(n-2)} \nabla \cdot \tilde{v}^{(n-1)} \right)
- \chi_n(t)\partial_t \left( (V^{(n-1)} \cdot \nabla)(\tilde{v}^{(n)}) + U^{(n-1)} \nabla (u^{(n)}) \right)
- \chi_n(t)\partial_t \left( (v^{(n-2)} \cdot \nabla)(V^{(n)}) + u^{(n-2)} \nabla (U^{(n)}) \right)
- (\chi_n(t) - \chi_{n-1}(t))\partial_t \left( (v^{(n-2)} \cdot \nabla)(\tilde{v}^{(n-1)}) + u^{(n-2)} \nabla (\tilde{u}^{(n-1)}) \right)
+ \nabla \left( (V^{(n-1)} \cdot \nabla)\Phi_1 + U^{(n-1)} \nabla \cdot \Phi_2 \right)
- \partial_t \left( (V^{(n-1)} \cdot \nabla)\Phi_2 + U^{(n-1)} \nabla \Phi_1 \right)
+ \nabla \left( V^{(n-1)} \cdot \nabla h_1 + U^{(n-1)} \nabla \cdot h_2 \right)
- \partial_t \left( (V^{(n-1)} \cdot \nabla)h_2 + U^{(n-1)} \nabla h_1 \right)
- \nabla \Delta^{-1} \nabla \cdot (U^{(n-1)} v^{(n-1)})
- \nabla \Delta^{-1} \nabla \cdot (u^{(n-2)} V^{(n-1)}) \quad (7.2)\]

For the convenience of notations, we define

\[w_n(t)^2 = \|U^{(n)}(t)\|_{L_x^2}^2 + \|(U^{(n)}(t))'\|_{L_x^2}^2 + \|V^{(n)}(t)\|_{L_x^2}^2 + \|(V^{(n)}(t))'\|_{L_x^2}^2 \quad n \geq 0. \quad (7.3)\]

We shall derive some recursive inequalities for \(w_n(t)\) from which it will follow that the sequence \((\tilde{u}^{(n)}, \tilde{v}^{(n)})\) is a contraction.
By using (6.39), (6.2)–(6.4) and (7.3), we have

\[
\frac{d}{dt} \left( \frac{1}{2} \| U^{(n)}(t) \|_{L^2}^2 + \frac{1}{2} \| (U^{(n)}(t))' \|_{L^2}^2 \right) = \int_{\mathbb{R}^2} \chi_n(t) \nabla \cdot \left( (V^{(n-1)} \cdot \nabla) \bar{v}^{(n)} + U^{(n-1)} \nabla \bar{w}^{(n)} \right) \cdot \partial_t U^{(n)} \, dx \tag{7.4}
\]

\[
+ \chi_n(t) \int_{\mathbb{R}^2} \nabla \cdot \left( (V^{(n-2)} \cdot \nabla) V^{(n)} + u^{(n-2)} \nabla U^{(n)} \right) \cdot \partial_t U^{(n)} \, dx \tag{7.5}
\]

\[
+ (\chi_n(t) - \chi_{n-1}(t)) \int_{\mathbb{R}^2} \nabla \cdot \left( (V^{(n-2)} \cdot \nabla) \bar{v}^{(n-1)} + u^{(n-2)} \nabla \bar{w}^{(n-1)} \right) \partial_t U^{(n)} \, dx \tag{7.6}
\]

\[
- \chi_n(t) \int_{\mathbb{R}^2} \partial_t \left( (V^{(n-1)} \cdot \nabla) \bar{u}^{(n-1)} + U^{(n-1)} \nabla \bar{v}^{(n)} \right) \partial_t U^{(n)} \, dx \tag{7.7}
\]

\[
- \chi_n(t) \int_{\mathbb{R}^2} \partial_t \left( (V^{(n-2)} \cdot \nabla) U^{(n)} + u^{(n-2)} \nabla V^{(n)} \right) \partial_t U^{(n)} \, dx \tag{7.8}
\]

\[
- (\chi_n(t) - \chi_{n-1}(t)) \int_{\mathbb{R}^2} \partial_t \left( (V^{(n-2)} \cdot \nabla) \bar{u}^{(n-1)} + u^{(n-2)} \nabla \bar{v}^{(n-1)} \right) \partial_t U^{(n)} \, dx \tag{7.9}
\]

\[
+ \int_{\mathbb{R}^2} \nabla \cdot \left( (V^{(n-1)} \cdot \nabla) \Phi_2 + U^{(n-1)} \nabla \Phi_1 \right) \partial_t U^{(n)} \, dx \tag{7.10}
\]

\[
- \int_{\mathbb{R}^2} \partial_t \left( (V^{(n-1)} \cdot \nabla) \Phi_1 + U^{(n-1)} \nabla \Phi_2 \right) \partial_t U^{(n)} \, dx \tag{7.11}
\]

\[
+ \int_{\mathbb{R}^2} \nabla \cdot \left( (V^{(n-1)} \cdot \nabla) h_2 + U^{(n-1)} \nabla h_1 \right) \partial_t U^{(n)} \, dx \tag{7.12}
\]

\[
- \int_{\mathbb{R}^2} \partial_t \left( (V^{(n-1)} \cdot \nabla) h_1 + U^{(n-1)} \nabla \cdot h_2 \right) \partial_t U^{(n)} \, dx \tag{7.13}
\]

By using (6.39), (6.2)–(6.3) and (7.4), we have

\[
\sum_{7.4} + \sum_{7.7} + \sum_{7.10} + \sum_{7.11} + \sum_{7.12} + \sum_{7.13} \lesssim \frac{\epsilon}{\langle t \rangle} w_{n-1}(t) \cdot w_n(t).
\]

Also we have

\[
\sum_{7.9} \lesssim | \chi_n(t) - \chi_{n-1}(t) | \cdot \frac{\epsilon^2}{\langle t \rangle^2} \cdot w_n(t).
\]

By using integration by parts, we write (7.3) as

\[
\sum_{7.5} = -\chi_n(t) \int_{\mathbb{R}^2} u^{(n-2)} \nabla U^{(n)} \cdot \partial_t \nabla U^{(n)} \, dx \tag{7.14}
\]

\[
- \chi_n(t) \sum_{1 \leq i,j \leq 4} \int_{\mathbb{R}^2} \chi_i^{(n-2)} \partial_{x_i} V_j^{(n)} \partial_t \partial_{x_j} U^{(n)} \, dx. \tag{7.15}
\]
For (7.14), we use Leibniz in time and this gives
\[
(7.14) = \frac{d}{dt} \left( \frac{1}{2} \chi_n(t) \int_{\mathbb{R}^2} u^{(n-2)} |\nabla U^{(n)}|^2 \, dx \right) \tag{7.16}
\]
\[+ \frac{1}{2} \chi'_n(t) \int_{\mathbb{R}^2} u^{(n-2)} |\nabla U^{(n)}|^2 \, dx \tag{7.17}
\]
\[+ \frac{1}{2} \chi_n(t) \int_{\mathbb{R}^2} \partial_t u^{(n-2)} |\nabla U^{(n)}|^2 \, dx. \tag{7.18}
\]

The first term (7.16) will be absorbed into the LHS of (6.39). By using (6.39), (6.29), (6.30), (6.31), the other two terms (7.17), (7.18) can be easily bounded as
\[
|7.17| + |7.18| \lesssim \frac{\epsilon}{t} w_n(t)^2.
\]

Next we consider the term (7.15). By using repeatedly integration by parts, we have
\[
(7.15) = \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_{x_i} v_i^{(n-2)} v_j^{(n)} \partial_t \partial_{x_j} U^{(n)} \, dx
\]
\[+ \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} v_i^{(n-2)} v_j^{(n)} \partial_t \partial_{x_i} \partial_{x_j} U^{(n)} \, dx \tag{7.19}
\]
\[= -\chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_{x_i} v_i^{(n-2)} \partial_{x_j} v_j^{(n)} \partial_t U^{(n)} \, dx \tag{7.20}
\]
\[- \frac{d}{dt} \left( \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_{x_j} v_i^{(n-2)} v_j^{(n)} \partial_{x_i} U^{(n)} \, dx \right)
\]
\[+ \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} v_i^{(n-2)} \partial_{x_j} v_j^{(n)} \partial_{x_i} U^{(n)} \, dx \tag{7.21}
\]
\[+ \chi'_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_{x_j} v_i^{(n-2)} v_j^{(n)} \partial_{x_i} U^{(n)} \, dx \tag{7.22}
\]
\[+ \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_{x_j} v_i^{(n-2)} v_j^{(n)} \partial_{x_i} U^{(n)} \, dx \tag{7.23}
\]
\[+ \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_{x_j} \partial_t v_i^{(n-2)} v_j^{(n)} \partial_{x_i} U^{(n)} \, dx \tag{7.24}
\]
\[+ \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_t v_i^{(n-2)} \partial_{x_j} v_j^{(n)} \partial_{x_i} U^{(n)} \, dx \tag{7.25}
\]
\[- \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_t v_i^{(n)} \partial_{x_j} \left( \partial_{x_i} U^{(n)} \cdot v_i^{(n-2)} \right) \, dx \tag{7.26}
\]
\[+ \chi_n(t) \sum_{1 \leq i, j \leq 2} \int_{\mathbb{R}^2} \partial_t v_i^{(n)} \partial_{x_j} U^{(n)} \partial_{x_i} v_i^{(n-2)} \, dx \tag{7.27}
\]

We shall absorb (7.21) into the LHS of (6.39). We will make no changes to the term (7.20) since it will cancel with a corresponding term in the calculation of $V^{(n)}$. 
For the rest of the terms, we use again (6.39), (6.2)–(6.4) to bound them as
\[ |(7.19)| + |(7.20)| + |(7.22)| + |(7.23)| + |(7.24)| + |(7.25)| + |(7.27)| \leq \frac{\epsilon}{(t)} w_n(t)^2. \]

This ends the estimate of (7.15) and (7.5). By a similar but tedious calculation, we also have
\[ (7.25) = \chi_n(t) \int_{\mathbb{R}^2} \partial_t \left( u^{(n-2)} \nabla U^{(n)} \right) \cdot \partial_t V^{(n)} \, dx + \tilde{E}_1, \]

where
\[ |\tilde{E}_1| \leq \frac{\epsilon}{(t)} w_n(t)^2. \]

Collecting all the estimates, we obtain
\[
\frac{d}{dt} \left( \frac{1}{2} \| U^{(n)}(t) \|^2_{L^2_x} + \frac{1}{2} \| (U^{(n)}(t))' \|^2_{L^2_x} \right) = - \frac{d}{dt} \left( \frac{1}{2} \chi_n(t) \int_{\mathbb{R}^2} u^{(n-2)} |\nabla U^{(n)}|^2 \, dx \right) \\
- \frac{d}{dt} \left( \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_{x_i} U^{(n)} \partial_{x_j} V^{(n)} \, dx \right) \\
+ \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_{x_i} V^{(n)} \partial_{x_j} U^{(n)} \, dx \\
- \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_t V^{(n)} \partial_{x_j} \left( \partial_{x_i} U^{(n)} \cdot v_i^{(n-2)} \right) \, dx \\
+ \chi_n(t) \int_{\mathbb{R}^2} \partial_t \left( u^{(n-2)} \nabla U^{(n)} \right) \cdot \partial_t V^{(n)} \, dx + \tilde{E}_2, \quad (7.28)
\]

where
\[ |\tilde{E}_2| \leq \frac{\epsilon}{(t)} \left( w_n(t)^2 + w_n(t) \cdot w_{n-1}(t) \right) \\
+ |\chi_n(t) - \chi_{n-1}(t)| \cdot \frac{\epsilon^2}{(t)^2} w_n(t). \]

Next we deal with the estimate of $V^{(n)}$. This time we need to take the inner product of both sides of (7.22) with $\partial_t V^{(n)}$ integrate by parts. Proceeding in a similar manner as in the calculation of $U^{(n)}$ and after a long and tedious calculation, we
\begin{align*}
\frac{d}{dt} \left( \frac{1}{2} \| V^{(n)}(t) \|^2_{L^2} + \frac{1}{2} \| (V^{(n)}(t))' \|^2_{L^2} \right) \\
= & \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_i V_i^{(n)} \partial_j \left( \partial_x U^{(n)} \cdot \nabla V_i^{(n-2)} \right) dx \\
& \quad - \chi_n(t) \int_{\mathbb{R}^2} \partial_t \left( u^{(n-2)} \nabla U^{(n)} \right) \cdot \partial_t V^{(n)} dx \\
& \quad + \tilde{E}_3, 
\end{align*}
(7.29)

where
\[
|\tilde{E}_3| \lesssim \frac{\epsilon}{\langle t \rangle} \left( w_n(t)^2 + w_n(t) \cdot w_{n-1}(t) \right) \\
+ |\chi_n(t) - \chi_{n-1}(t)| \cdot \frac{\epsilon^2}{\langle t \rangle^2} w_n(t).
\]

Adding together (7.28), (7.29) and rearranging terms, we obtain
\begin{align*}
\frac{d}{dt} \left( \frac{1}{2} \| U^{(n)}(t) \|^2_{L^2} + \frac{1}{2} \| (U^{(n)}(t))' \|^2_{L^2} \right) \\
& \quad + \frac{1}{2} \| V^{(n)}(t) \|^2_{L^2} + \frac{1}{2} \| (V^{(n)}(t))' \|^2_{L^2} \\
& \quad + \frac{1}{2} \chi_n(t) \int_{\mathbb{R}^2} u^{(n-2)} \nabla U^{(n)} \|^2 dx \\
& \quad + \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_x \nabla V_i^{(n-2)} \partial_x U \partial_i V_j^{(n)} dx \\
& \quad + \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_i V_i^{(n-2)} \partial_x U \partial_j V_j^{(n)} dx 
= \tilde{E}_4,
\end{align*}
(7.30)

where
\[
|\tilde{E}_4| \lesssim \frac{\epsilon}{\langle t \rangle} \left( w_n(t)^2 + w_n(t) \cdot w_{n-1}(t) \right) \\
+ |\chi_n(t) - \chi_{n-1}(t)| \cdot \frac{\epsilon^2}{\langle t \rangle^2} w_n(t).
\]

Now denote
\begin{align*}
W_n(t) &= \frac{1}{2} \| U^{(n)}(t) \|^2_{L^2} + \frac{1}{2} \| (U^{(n)}(t))' \|^2_{L^2} \\
& \quad + \frac{1}{2} \| V^{(n)}(t) \|^2_{L^2} + \frac{1}{2} \| (V^{(n)}(t))' \|^2_{L^2} \\
& \quad + \frac{1}{2} \chi_n(t) \int_{\mathbb{R}^2} u^{(n-2)} \nabla U^{(n)} \|^2 dx \\
& \quad + \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_x \nabla V_i^{(n-2)} \partial_x U \partial_i V_j^{(n)} dx \\
& \quad + \chi_n(t) \sum_{1 \leq i,j \leq 2} \int_{\mathbb{R}^2} \partial_i V_i^{(n-2)} \partial_x U \partial_j V_j^{(n)} dx.
\end{align*}
(7.32)
By using (6.39), (6.2)–(6.4), it is clear that for \( \varepsilon \) sufficiently small (depending on an absolute constant), we have

\[
\frac{1}{10} \|U^{(n)}(t)\|_{L^2}^2 + \frac{1}{2} \|U^{(n)}(t)'\|_{L^2}^2 + \frac{1}{10} \|V^{(n)}(t)\|_{L^2}^2 + \frac{1}{2} \|V^{(n)}(t)'\|_{L^2}^2.
\]

Therefore for some absolute constant \( C > 0 \), we have

\[
\frac{1}{C} W_n(t) \leq w_n(t) \leq CW_n(t).
\]

The inequalities (7.30) and (7.31) now give us

\[
\left| \frac{d}{dt} W_n(t) \right| \lesssim \varepsilon \langle t \rangle (W_n(t) + W_{n-1}(t)) + |\chi_n(t) - \chi_{n-1}(t)| \cdot \frac{\varepsilon^2}{\langle t \rangle^2}, \quad \forall t \geq 0,
\]

where we have canceled a factor of \( W_n(t) \) on both sides of the inequality.

We then inductively assume

\[
W_n(t) \leq \frac{\delta_n}{\langle t \rangle^2}.
\]

Therefore

\[
\left| \frac{d}{dt} W_{n+1}(t) \right| \lesssim \frac{1}{\langle t \rangle^2} + \frac{\varepsilon}{\langle t \rangle^2} \cdot W_{n+1}(t) \cdot \frac{\varepsilon}{\langle t \rangle^2} + \frac{\varepsilon^2}{\langle t \rangle^2} \cdot |\chi(t) - \chi_{2n-1}(t)|
\]

\[
\lesssim \frac{\delta_n \cdot \varepsilon}{\langle t \rangle^2} + \frac{\varepsilon^2 \cdot 2^{-\frac{2n}{\sigma}}}{\langle t \rangle^2} + W_{n+1}(t) \cdot \frac{\varepsilon}{\langle t \rangle^2},
\]

where in the last inequality we have used the fact that the function \( |\chi(t) - \chi_{2n-1}(t)| \) is localized to the region \( t \sim 2^n \). By (6.39), we have the a priori estimate

\[
W_{n+1}(t) \lesssim \frac{\varepsilon}{\langle t \rangle^2}.
\]

We need the following Gronwall lemma

**Lemma 7.1** (Infinite time Gronwall, version 2). Let \( B(t) \) be a nonnegative smooth function on \([1, \infty)\) satisfying

\[
\left| \frac{d}{dt} B(t) \right| \leq \frac{\varepsilon}{t} B(t) + \frac{\delta}{t^{1+\sigma}}
\]

and

\[
B(t) \leq \frac{K}{t^\sigma}, \quad \forall t \geq 1.
\]

Here \( 0 < \varepsilon < 1, \sigma > 0, \delta > 0, K > 0 \) are constants. Then for \( \varepsilon < \sigma \),

\[
B(t) \leq \frac{\delta}{\sigma - \varepsilon} \cdot \frac{1}{t^{\sigma}}, \quad \forall t \geq 1,
\]
where \(C_1(\sigma)\) is a constant depending only on \(\sigma\).

**Proof.** The proof of Lemma 7.1 is similar to that of Lemma 6.1. We omit the details here. \(\square\)

By using Lemma 7.1 and taking \(\epsilon\) sufficiently small, we get

\[
W_{n+1}(t) \leq \frac{\delta_{n+1}}{(t)^{\frac{\theta}{2}}},
\]

where \(\delta_{n+1} = \theta \cdot (\delta_n + 2^{-\frac{n}{2}})\), where \(0 < \theta < 1\) is some constant. It is obvious that \(\delta_n \leq \text{const} \cdot \alpha^n\) for some \(0 < \alpha < 1\). Hence the sequence \((\bar{u}^{(n+1)}(t), \bar{v}^{(n+1)}(t))\) is Cauchy and converges to a nontrivial limiting function in \(H^1\). By interpolation inequalities \((\bar{u}^{(n+1)}(t), \bar{v}^{(n+1)}(t))\) converges strongly in \(H^{m-1}\) for every \(t\). For the highest norm \(H^m\), upon passing to a subsequence if necessary, we have \((\bar{u}^{(n+1)}(t), \bar{v}^{(n+1)}(t))\) tends to the limiting solution \((\bar{u}(t), \bar{v}(t))\) weakly for each \(t\). Hence

\[
\|\bar{u}(t)\|_{H^m} + \|\bar{v}(t)\|_{H^m} + \|(\bar{u}(t))'\|_{H^m} + \|(\bar{v}(t))'\|_{H^m} \lesssim \frac{\epsilon}{(t)}.
\]

We have obtained the desired classical solution.

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