Vacuum and semiclassical gravity: a difficulty and its bewildering significance

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Abstract

We review a long-standing difficulty in some semiclassical models of vacuum and vacuum decay. Surprisingly enough these models, careless of their transparent formulation, are affected by, both, technical and conceptual issues. After proving some general results that are relevant for, both, the Euclidean and Lorentzian sectors of their dynamics, we briefly highlight their importance in connection with the issues discussed before, arguing that their solution might be interesting in our quest for quantum gravity.

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1 Introduction

The study of vacuum properties and decay is a fascinating subject, and it becomes even more interesting when its interplay with gravitation is considered. A natural context to study properties of vacuum is early universe cosmology, where vacuum energy density plays a dominant role. For this reason, early after the first studies of vacuum and vacuum decay [1], gravity entered the scene [2][3][4][5]: in most models thin relativistic shells are used to describe the dynamics of vacuum bubbles. Classical models already reveal interesting properties, but they tend to be affected by issues, in connection with stability and the presence of singularities. To avoid these problems, quantum models (mostly semiclassical) have been developed [6][7]: vacuum decay is then described in the WKB approximation as spacetime tunnelling driven by the thin shell. Despite the earliest of these works date back to more than 30 years ago, issues left open in the original formulation [6] have not yet been solved [6][8]. Here we review some of these issues from a general perspective. We also point out that, although the existing literature mostly focuses on applications relevant for early universe cosmology, the open problems are of a more general nature and can be recognized as a general difficulty in the semiclassical quantization of the (general relativistic) shell system. After a preliminary review of some background material in Sec. 2, we prove in Sec. 3 a collection of general properties of shell dynamics in spherically symmetric, but otherwise arbitrary, configurations. Then, in Sec. 4, we present in the perspective of these results some issues related with the WKB description of the tunnelling process; a concluding discussion follows in Sec. 5. Apart from the included bibliography, additional references can be also found in [9][10].

2 Background, conventions and notations

Throughout the paper curvature conventions follow [11], with Greek indices taking the values 0, 1, 2, 3, lowercase Latin indices taking the values 1, 2, 3, and uppercase latin indices the values 0, 1. We consider two parts $\mathcal{M}_{(-)}$ and $\mathcal{M}_{(+)\text{ of two spacetimes and assume that they have a common timelike part } \Sigma \text{ in their boundaries. Various quantities related to the submanifolds } \mathcal{M}_{(-)}, \mathcal{M}_{(+)} \text{ and } \Sigma \text{ are defined in the table below and in Fig. [1]} \text{ panel [a].}$

| Submanifold | Dim. | Coordinate system $x^{\pm\alpha}$ | Holonomic basis $\partial_{\alpha}$ | Metric components $(-g_{\mu\nu}(x^{\pm\alpha}))$ | Signature $\rho_{\mu\nu} \text{ or } T_{\mu\nu}$ | Covariant Derivative $\nabla_{\alpha}$ | Matter Content $\rho_{mn}(\xi^a)$ |
|-------------|------|-----------------------------------|-----------------------------------|----------------------------------|---------------------------------------|--------------------------|--------------------------|
| $\mathcal{M}_{(-)}$ | 4 | $x^{(-\alpha)}$ | $\partial_{\alpha}$ | $(-g_{\mu\nu}(x^{(-\alpha)}))$ | 2 | $(-\nabla_{\alpha} \rho_{\mu\nu})$ | $\rho_{mn}(\xi^a)$ |
| $\mathcal{M}_{(+)}$ | 4 | $x^{(+\alpha)}$ | $\partial_{\alpha}$ | $(+g_{\mu\nu}(x^{(+\alpha)}))$ | 2 | $(+\nabla_{\alpha} \rho_{\mu\nu})$ | $\rho_{mn}(\xi^a)$ |
| $\Sigma$ | 3 | $\xi^a$ | $\partial_{\alpha}$ | $g_{mn}(\xi^a)$ | 1 | $\nabla_{\alpha}$ | $\rho_{mn}(\xi^a)$ |

In the above setup, we locally define the embedding of $\Sigma$ in $\mathcal{M}_{(\pm)}$ as $x^{(\pm)\mu} = F_{(\pm)}^\mu (\xi^a)$. Moreover we assume $(-g_{\mu\nu}(x^{(-\rho)}) e^\rho_{(m)} e^\nu_{(n)}) x^\sigma = F_{(\pm)}^\mu (\xi^a) = (\pm g_{\mu\nu}(x^{(+\sigma)}) e^\sigma_{(m)} e^\nu_{(n)}) x^\rho = F_{(\pm)}^\mu (\xi^a)$, so that the metric on $\Sigma$ is well defined (by assumption, it is also non degenerate). Various geometric quantities, as for instance the normal to $\Sigma$, $\mathbf{n}$, or the extrinsic curvature of $\Sigma$, $K_{ij} \overset{\text{def}}{=} -\eta_{\alpha\beta} e^\alpha_{(j)} \nabla_{\beta} e^\beta_{(i)}$, are calculated with respect to the embedding of $\Sigma$ in $\mathcal{M}_{(-)}$ or $\mathcal{M}_{(+)}$. We specify this using $\xi^{(\pm)}$ as a sub/superscript or using ‘$|_{(\pm)}$’. The jump of quantities across $\Sigma$, is shortly denoted as ‘$|_{(\pm)}$’; consistently, square brackets are not used with any other meaning.

The dynamics of $\Sigma$ and of its energy matter content in the spacetime manifold $\mathcal{M}_{(-)} \cup \mathcal{M}_{(+)}$ (the overbar denotes the closure) is determined by Israel junction conditions [14], which relate the jump

\footnote{We assume that it points from $\mathcal{M}_{(-)}$ to $\mathcal{M}_{(+)}$; moreover, since $\Sigma$ is timelike, the normal is also transverse.}
of the extrinsic curvature of $\Sigma$ to the surface stress-energy tensor $S_{mn}$ and its trace $S$:

$$[K_{ij}] \equiv K^-_{ij} - K^+_{ij} = 8\pi \left( S_{ij} - \frac{g_{ij}}{2} S \right).$$ (1)

In particular, we are interested in the spherically symmetric reduction of the above equations, i.e. we consider the special case in which $\Sigma$ describes the spherically symmetric evolution of a sphere. A general spherically symmetric four dimensional spacetime can always be considered as a product of a two sphere $S^2$ and of another, again two dimensional, Lorentzian manifold $M_2$. Therefore, the metric $^4g$ on the four dimensional manifold can always be decomposed in the form

$$^4g = \begin{pmatrix} g_{M_2} & \mathbb{O} \\ \mathbb{O} & g_{S^2} \end{pmatrix}, \quad g_{M_2} = \begin{pmatrix} \gamma_{11}(x_1, x_2) & \gamma_{12}(x_1, x_2) \\ \gamma_{12}(x_1, x_2) & \gamma_{22}(x_1, x_2) \end{pmatrix}, \quad g_{S^2} = \rho^2(x_1, x_2) \begin{pmatrix} 1 & 0 \\ 0 & 0 \sin^2\Theta \end{pmatrix},$$

where we denote with $(x_1, x_2)$ coordinates in $M_2$ and with $(\Theta, \Phi)$ the usual coordinates in $S^2$. Thanks to general covariance, we can subject $g_{M_2}$ to two conditions so that the four dimensional metric can be locally described by only two functions: a natural choice is $\rho(x_1, x_2)$ plus another function coming from $M_2$, which can be wisely chosen to be the invariant $\Delta = \gamma^{AB} \rho_{,A} \rho_{,B}$ (the modulus square of the vector normal to the $\rho(x_1, x_2) =$ const. surfaces). If $\Delta > 0$ we are in what is called an $R$-region, whereas if $\Delta < 0$ we are in a $T$-region [13]. When we apply the above decomposition in $M_{(\pm)}$ we can conveniently use $\Delta_{(\pm)}$ to describe various properties of the dynamics of the shell in a coordinate invariant way [16].

In the following it is also useful to further specialize $(\pm)g_{\mu\nu}$ and $g_{mn}$, defined before, as follows.
We now see that \( \text{sign}(\Delta_{\pm}) = \text{sign}(f_{\pm}) \), so that if \( f_{\pm} < 0 \) we are in a \( T^{(\pm)} \)-region of \( \mathcal{M}_{(\pm)} \), whereas if \( f_{\pm} > 0 \) we are in an \( R^{(\pm)} \)-region of \( \mathcal{M}_{(\pm)} \). Moreover, after using all the freedom to fix the coordinate systems, \( R(\tau) \) is the only degree of freedom (\( \tau \) is the proper time of an observer comoving with \( \Sigma \)) describing the dynamics of the shell and only one junction condition is non-trivial:

\[
R \left[ \epsilon \sqrt{\dot{\tau}^2 + f(\tau)} \right] = M(R) \quad \text{where} \quad n^\alpha \partial_\alpha r_{(\pm)} |_{\Sigma} = \epsilon_{(\pm)} \sqrt{\dot{\tau}^2 + f_{(\pm)}(\tau)}; \tag{2}
\]

an overdot denotes a derivative with respect to \( \tau \), \( \epsilon_{(\pm)} \) are signs (we will come back later to their meaning) and \( M(R) \) describes the matter energy content of the shell, after its equation of state has been specified. The only nontrivial junction condition \( \epsilon_{(\pm)} \) can then be rewritten in the form

\[
\dot{R}^2 + V(R) = 0 \quad \text{where} \quad V(R) = - \left( \frac{R^2 f_{(\pm)}(R) + R^2 f_{(\pm)}(R) - M^2(R)^2}{4M^2(R)R^2} \right) \tag{3}
\]

A closed form expression for the \( \epsilon_{(\pm)} \) signs not involving \( \dot{R} \) can also be obtained starting from \( \epsilon_{(\pm)} \):

\[
\epsilon_{(\pm)} = \text{sign}\{M(R)(R^2 f_{(\pm)}(R) - R^2 f_{(\pm)}(R)) \mp M^2(R))\}. \tag{4}
\]

Eqs. (3) and (4) form a set of equations which is completely equivalent to \( \epsilon_{(\pm)} \) (see also Prop. 4 below). Classical solutions of the junction condition can exist only in the region \( V(R) \leq 0 \) and their turning points are solutions of the equation \( V(R) = 0 \). We call tunnelling trajectories the solutions in the inverted potential \(-V(R)\). Also notice, that the junction condition \( \epsilon_{(\pm)} \) is a first order equation, (it contains \( \dot{R} \) but not \( R \)) and it is not the equation of motion of the system but a first integral of it \( 13, 17 \). The second order equation of motion can be obtained from an effective Lagrangian, \( L_{\text{EFF}} \), that describes the dynamics of the only remaining degree of freedom \( R(\tau) \). If

\[
H_{\text{EFF}}(R, \dot{R}) = R \left[ \epsilon \sqrt{\dot{\tau}^2 + f(\tau)} \right] - M(R) \quad \text{and} \quad P_{\text{EFF}}(R, \dot{R}) = R \left[ \tanh^{-1} \left( \frac{\dot{R}}{\epsilon \sqrt{\dot{\tau}^2 + f(\tau)}} \right) \right] \tag{5}
\]

are the effective (super)hamiltonian and effective momentum, respectively, we have that the \( L_{\text{EFF}} = P_{\text{EFF}} \dot{R} - H_{\text{EFF}} \) holds and the second order equation of motion is given by

\[
\frac{d}{d\tau} \left( \frac{\partial L_{\text{EFF}}}{\partial \dot{R}} \right) - \frac{\partial L_{\text{EFF}}}{\partial R} = 0.
\]

Moreover, \( H_{\text{EFF}} \equiv 0 \) is a constraint on the system. We also anticipate that in this setup the expression for the Euclidean momentum, i.e. the momentum along a tunnelling trajectory, is

\[
P_{\text{EFF}}^{(e)}(R, R') = R \left[ \arctan \left( \frac{R'}{\epsilon \sqrt{f(R) - (R')^2}} \right) \right] = -iP_{\text{EFF}}(R, \dot{R}). \tag{6}
\]
Proposition 5

The signs of the radicals, \(\dot{\epsilon}\) about the relative positions of the zeroes of the metric functions are tangent at \(R = \bar{R}\). This can be proved deriving the Euclidean junction condition \[6\].

3 Some general results

We now prove some general results to provide toeholds for the discussion of the problems that will emerge in the Euclidean sector. Some of them appear already in the literature, but not in a systematic exposition. These results also provide simple, but useful consistency checks.

Proposition 1

The junction condition and the effective potential are invariant under the relabelling \(+ \leftrightarrow -\), whereas the signs change as \(\epsilon(\pm) \rightarrow -\epsilon(\mp)\).

Proof: the validity of the above result for \(V(R)\) and \(\epsilon(\pm)\) is manifest from \[3\] and \[1\]. Then the invariance of the junction condition \[2\] immediately follows. □

Another property directly related to the algebraic structure of \[2\], is the following.

Proposition 2

The relations \(V(R) \leq f(\pm)(R)\) always hold. Moreover, if \(V(\bar{R}) = f(\pm)(\bar{R})\), then \(V(R)\) and \(f(\pm)(R)\) are tangent at \(R = \bar{R}\).

Proof: the first result follows immediately after some algebra, since

\[
f(\pm)(R) - V(R) = \frac{(R^2 f(-) - R^2 f(+)) + M^2(R))}{4M^2(R)R^2} = a(\pm)(R) \geq 0.
\]

This, together with the first derivative of the equation above, \(f'_{(\pm)}(R) - V'(R) = 2a(R)a'(R)\) completes the proof of the second result, because \(f_{(\pm)}(\bar{R}) = V(\bar{R})\), i.e. \(a_{(\pm)}(\bar{R}) = 0\), implies \(f''_{(\pm)}(\bar{R}) = V''(\bar{R})\). □

Two immediate consequences then follow.

Proposition 3

Along a classical trajectory the signs \(\epsilon(\pm)\) vanish at the points at which the potential \(V(R)\) is tangent to the metric function \(f_{(\pm)}(R)\) and only at these points.

Proof: the result follows from \[4\] and \[7\], which show that \(\epsilon(\pm) = \text{sign}(a(\pm)(R))\). □

Proposition 4

The conditions about the well-definiteness of the two radicals in the junction condition \[2\] do not impose any restriction on the classical/tunnelling solutions.

Proof: from what we have seen above, if the effective (classical looking) equation \[5\] is satisfied, the arguments of the radicals, \(\bar{R}^2 + f_{(\pm)}(R) = f_{(\pm)}(R) - V(R)\), are always nonnegative by Prop.\[2\] □

Up to this point we have systematized some results concerning the mutual relationships of the metric functions \(f_{(\pm)}\), the potential \(V\) and the signs \(\epsilon(\pm)\). Some additional results are now obtained about the relative positions of the zeroes of \(\epsilon(\pm)\), \(V\) and the positions of the zeroes of \(f_{(\pm)}\).

Proposition 5

The signs \(\epsilon(\pm)\) can change either i) along a classical solution of \[2\] in a region in which \(f_{(\pm)} \leq 0\), or ii) along a tunnelling trajectory.
Proof: let us assume that at the point \( R = \bar{R} \) we have \( \epsilon( \pm ) ( \bar{R} ) = 0 \); this implies \( a( \pm ) ( \bar{R} ) = 0 \) by Prop. 5. If we are along a classical solution of (2) because of (3) we must have \( V( \bar{R} ) \leq 0 \), i.e. \( f( \pm ) ( \bar{R} ) \leq 0 \). If instead we have \( f( \pm ) ( \bar{R} ) > 0 \), then we also have \( V( \bar{R} ) > 0 \), i.e. we are along a tunnelling trajectory. □

An analogous result can then be proved for the turning points of the classical solutions.

Proposition 6 A turning point \( R_0 \) of (2) always satisfies \( f( \pm ) ( R_0 ) \geq 0 \).

Proof: we know that in general \( f( \pm ) ( R ) - V( R ) \geq 0 \); thus at \( R_0 \), where \( V( R_0 ) = 0 \), we have \( f( \pm ) ( R_0 ) \geq 0 \). □

Related to this result is the following one, which details the regularity properties of \( P_{\text{EFF}} \).

Proposition 7 The effective momentum \( P_{\text{EFF}} \) is always well defined on a classically allowed trajectory, with the exception of the points at which \( f( \pm ) \) vanish.

Proof: by Prop. 4 the radicals that appear in the expression of \( P_{\text{EFF}} \) are always well defined along a classical solution of the junction condition. Critical points of \( P_{\text{EFF}} \) can thus only appear either if they vanish or because of the presence of the inverse hyperbolic tangent, whose argument must be in the interval \((-1, +1)\). Two complementary subcases can be singled out.

\( f( \pm ) \neq 0 \) Under this condition we can rule out the first possibility, since along a classically allowed trajectory \( \epsilon( \pm ) \) can vanish only if \( f( \pm ) < 0 \), when the radical is in the numerator. Troubles with the inverse hyperbolic tangent are quickly excluded as well. If \( f( \pm ) > 0 \), then the exponent of its argument is +1, and we can forget about it. At the same time the absolute value of the numerator is lower than the one of the denominator, so the momentum is well defined in this case. If \( f( \pm ) < 0 \), then the absolute value of the numerator is bigger than the one of the denominator, but the ratio is raised to the power \(-1\) and still there is no problem.

\( f( \pm ) = 0 \) This case is more subtle; if the corresponding \( \epsilon( \pm ) \) sign is non vanishing, then the absolute value of the argument of the inverse hyperbolic tangent is equal to 1 and the momentum has a logarithmic, i.e. integrable, divergence. If, instead, also \( \epsilon( \pm ) = 0 \), a case by case analysis is required.

We can, thus, conclude that the momentum can be not well defined only at the points where \( f( \pm ) = 0 \); if \( \epsilon( \pm ) \neq 0 \) it has a logarithmic divergence; a case by case analysis has instead to be done if \( \epsilon( \pm ) = 0 \). □

The regularity of the Euclidean effective momentum can be analyzed in general as well.

Proposition 8 The Euclidean effective momentum \( P_{\text{EFF}}^{(e)} \) is always well defined along a tunnelling trajectory in the sense that, at most, it can have discontinuities.

Proof: from a quick inspection of (3) and from the result in Prop. 4 we see that the only trouble to the momentum can come from vanishing radicals in the denominator, i.e. from vanishing \( \epsilon( \pm ) \). This can indeed happen along a tunnelling trajectory (Prop. 5) and if this happens inside it, e.g. at \( \bar{R} \), the argument of the corresponding inverse tangent function tends to \( \pm \infty \) there. If \( \lim_{R \to \bar{R}^-} \neq \lim_{R \to \bar{R}^+} \) in the standard branch of the arctan function a discontinuity appears. This discontinuity can be eliminated by choosing another appropriate branch, although this will, in general, affect the value of \( P_{\text{EFF}}^{(e)} \) at, at least, one turning point. If \( \bar{R} \) coincides with a turning point, i.e. it occurs not inside but at the boundary of a tunnelling trajectory, a case by case analysis is again required. □

The physical content of these results can be expressed in general terms using the concepts of \( R^{(\pm)} \) and \( T^{(\pm)} \) introduced before. We have, in fact, proved that:

1. the \( \epsilon( \pm ) \) signs can only vanish either i) in the closure of a \( T^{(\pm)} \) region along a classical solution of the junction condition (2) or ii) along a tunnelling trajectory;

2. turning points can only be present in the closure of an \( R^{(\pm)} \) region; this second fact is coherent with the fact that in the Euclidean description of the manifolds \( M^{(\pm)} \), there is no region corresponding to the \( T^{(\pm)} \) ones; loosely speaking, the shell has nowhere to tunnel from one of these regions!
These results are valid for arbitrary spherically symmetric junctions, independently from the matter content of spacetime and/or of the shell. It is also noteworthy to stress the following particular case, which happens when a turning point is exactly on the boundary of an $R$-region of one of the two spacetimes (i.e. at a point where at least one of $f(\pm)$ vanishes). In this case one of the $f(\pm)$ is zero, but $V$ is also zero, so the corresponding $\epsilon(\pm)$ sign is zero too. We call this the exceptional case, but we will not consider it further here.

4 Tunnelling problems

The above results can be used to obtain general insight not only about the classical dynamics of the system, but, especially, about the semiclassical one. Here we will not discuss the interesting possibilities of using WKB methods to determine the semiclassical stationary states [18,9], but we will, instead, concentrate on the tunnelling process. In particular, it is possible to use the Euclidean momentum (6) to calculate the value of the tunnelling action (i.e of the probability)

$$S_{TUN} = \int_{R_1}^{R_2} P^{(e)}_{EFF}(R)dR \text{ where } P^{(e)}_{EFF}(R) = P^{(e)}_{EFF}(R, R') \bigg|_{R' = \sqrt{V(R)}};$$

$P^{(e)}_{EFF}(R)$ is the Euclidean Momentum evaluated along a tunnelling trajectory. This has been done for various configurations and results in agreement with other independent calculations have been obtained (for instance the results by Coleman and de Luccia [2] and by Parke [19], can be reproduced). Unfortunately things do not always work out so smoothly: problems arise when at least one of the $\epsilon(\pm)$ signs vanishes along the tunnelling trajectory. These problems relate i) to the ones connected with the difficulty to build the Euclidean manifold interpolating between the classical spacetime configuration described by the pre- and post-tunnelling solutions of the junction condition [6] and ii) to the ones connected with the difference in the tunnelling description given by canonical and path-integral methods [6]. It is convenient to summarize these issues using as a definite model, the case in which we have a de Sitter/Schwarzschild junction \( f^+(r^+) = 1 - \chi r^+_*^2, f^-(r^-) = 1 - 2m/r^-_* \) by a matter shell with equation of state \( p = -\sigma \), \( \sigma \) being the tension of the shell (i.e. \( M(R) = 4\pi\sigma R^2 \)).

To this end, in Fig. 2 we first analyze a situation free from troubles. In panels [a] and [b] we see that the normal is always transverse to the constant $r(\pm)$ surfaces. According to the definitions of $\epsilon(\pm)$, they then do not vanish, so that via Prop. 8 we know that the momentum does not have any troubles along the tunnelling trajectory, as shown in panel [c].

A different situation is, instead, shown in panel [b]. The de Sitter part of the junction in panel [a] is fine as before, but the Schwarzschild one in panel [b] has a peculiar feature: there is a point $P$ along the trajectory at which the normal is not transverse to the constant $r(\pm)$ surface, so that $\epsilon(\pm)(P) = 0$. Thus, we have some difficulty in identifying the part of the Schwarzschild spacetime participating in the junction, since the small area which is both dark-grayed and crossed-hatched is covered twice by the evolution of the Euclidean spacetime slice. This difficulty in identifying the instanton is reflect by the momentum plot in panel [c]: a discontinuity appears, as expected from Prop. 8. Notice that if we naively take the union of the grayed regions as the part of spacetime participating in the junction, a strange boundary (the $AB$ line) appears.

\[\text{There are reasonable proposals [6] to deal with this problem, but we will not discuss them here. The point we would like to stress, focusing on the problem rather than the possible solutions, is that particular care must be used when dealing with the Euclidean junction.}\]
Figure 2: A case of tunnelling where no problems appear: in [a] and [b] the Euclidean parts of spacetime participating in the junction are the grayed areas. Initial and final slices are labelled (i) and (f) respectively. The Euclidean trajectory of the shell is the solid curve. Initial and final Euclidean times and the normal are also shown.

The problem shown above is not typical of the Schwarzschild patch and can appear also in the de Sitter one, as shown in Fig. 4.

In both diagrams, at Q in panel [a] and at P in panel [b], the normal to the shell become non-transverse to the constant $r_{(±)}$ surfaces. At these points the corresponding signs $\epsilon_{(±)}$ vanish and the momentum develops a discontinuity, as shown in panel [c]. It is non trivial to build the junction and we face again a double covering with inverted normal direction in the Schwarzschild patch during the evolution of the initial slice (i) into the final one (f).

Concerning the last two cases, we notice, as we did at the end of the proof of Prop. 8, that, in view of the form of the effective momentum $P^{(e)}_{\text{EFF}}$, it is certainly possible to choose appropriate branches of the inverse tangent functions to cure the discontinuity: nevertheless, this spoils the vanishing of the momentum at one of the turning points. It would, moreover, be interesting, to understand these possibilities in connection with the structure of the Euclidean spacetime diagram.

5 Discussion and Conclusion

Remembering the results presented in Sec 3, we would like to point out that the problems discussed in the previous section under very specific settings, are in fact general ones. In our opinion this fact has not yet been properly recognized. We would also like to make clear that, although the problems with the effective momentum could be solved by arguing that it is the effective theory that has intrinsic limits, we think that this partial solution would be rather unsatisfactory. The main point we are trying to make here is that the problems of the effective formulation are closely tied to the geometric properties of the Euclidean solution to the junction condition and to the Euclidean structure of the spacetime patches that participate in the junction. Moreover, the difficulties described above can be absent, and when they are absent, perfectly consistent results are obtained. In this respect, it becomes even more suggestive to draw the following picture. The idea of bubbles/shells tunnelling has been originally developed to overcome some weak points in the description provided by purely classical models of vacuum bubbles using general relativistic shells: in particular, the problem of
initial singularity, i.e. the fact that exponentially expanding solutions giving rise to a baby universe, classically, have a singularity in their past. Tunnelling (i.e. the use of quantum effects) solves this issue: in fact, we can start with a solution regular in the past (the bounded solution, which classically would never grow enough) and have it tunnel into an infinitely expanding one (the unbounded/bounce solution) which has the late time behavior we are interested in, but cannot exist at early times. We are, thus using quantum effects to circumvent the consequences of classical singularity theorems. The same idea has been employed also in a logically opposite direction using different spacetimes to build up the junction: then the reversed tunnelling process can describe a collapsing shell of matter [20], which classically doomed to crash in a future singularity, is, instead, saved by quantum effects, again avoiding the fate prescribed by classical singularity theorems. Another fact which has not yet been appreciated is that, in view of the simple but general results of Sec.3, this kind of processes is affected by the same difficulties, again related to a hard to interpret behavior in the Euclidean sector. In this sense the more general formulation of the problems shown in Figs. 2 and 3 that can be obtained in terms of the results of Sec. 3, shows that they are very general issues which appear when we try to use semiclassical quantum effects to circumvent the consequences of classical singularity theorems. As we said, this issues are not restricted to applications to the cosmological (baby-universes) scenario, as it is often believed, but represent instead another manifestation of the intrinsic difficulty in the interplay between the properties of general relativity and those of quantum theory. It seems to us a great opportunity, given to us by the intuitive and beautiful geometric character of Israel junction conditions, that these issues can appear at a technically rather simple level, offering us the possibility to concentrate our attention on their physical/geometric significance. This study is still work in progress, which at present is focused on finding general geometric criteria i) to identify the appearance of the above issues in the junction tunnelling process and ii) to characterize the difficulties in the Euclidean sector in terms of intuitive properties of the effective theory. Additional results will be reported (hopefully soon) elsewhere.

Figure 3: A case of tunnelling when one part of the spacetime participating in the junction is problematic. If we proceed as in the case of Fig. 2, we encounter soon a point \( P \) after which, the determination of the part of spacetime participating in the junction becomes unclear (see the text for details).
Figure 4: The problem which appeared in Fig. 3 is generic and can affect both spacetimes, separately, or at once, as in this case. Now, in panel [a] some problems appear in connection with the existence of point Q, whereas in panel [b] the situation maintains the same difficulty encountered in Fig. 3. Two discontinuities of $P_{\text{EFF}}(R)$ are present (panel [c]).

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