Method of Restoring Parameters of Information Objects in a Unified Information Space Based on Computer Networks

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Abstract—The paper describes the organization of the unified information space which is based on the uniform principles and the general rules that ensure the informational interaction of objects.

In practice, in case when the communication with an information object of the unified information space is lost, the necessary information about this object should be collected by the analysis of previous interactions of the information object with the other information objects. The goal of this paper article is to develop a mechanism that will allow restore the missing parameters of information objects in case of communication loss with this object.

There was performed the experimental researches with the proposed mechanisms. The experiments have shown that there is an unequivocal relationship between the quality of restoration of an information object and the topology of links within an unified information space.

Index Terms—Unified information space, Information object, Parameters, Communication, Links topology.

I. INTRODUCTION

The unified information space (UIS) is an information model of a complex domain. It includes information objects, relations between them, environment of the space and processes accompanying the creation and operation of the UIS. The UIS implies a unified data entry, its storage in uniform formats and unified exchange of information between all information objects [1 - 3].

An unified information space should support the reliably store of the large volume of data of various types, update them quickly, and perform an effective search for the necessary data. Moreover, UIS should provide an unambiguous idea about the content of information and
its structure. Information in any part of the UIS should be accessible from any other point without additional conversion.

Nowadays, a number of organizations are involved in the development of the UIS, in particular: IEEE (Institute of Electrical and Electronic Engineers), NIST (National Institute of Standards and Technology), ANSI (American National Standard Institute), (all from USA) UKCEB (UK Council for Electronic Business) (UK); Tekes (Finland), etc.

II. LITERATURE REVIEW

The study of the problem of formation of the unified information space is actual now. It made by several researcher such as: Abdurakhmanov, Barishpolets, Veprintsev, Grachev, Zuev, Kopylov, Krys’ko, Manilow, Modesto and others [4 - 9].

In [5] was shown that actual is the concept of UIS as a communicative information environment at a certain organization with special feature based on the information flow. Also, there is identified the “non-electronic” information environment of organization institutions, and “electronic” one as well [4, 6].

Unified Information Space is presented in some papers as a set of data, technologies for their support, and the information and telecommunication systems and networks, which are operating on the common principles and general rules that provide information interaction between the organizations and users in order to meet their information needs [4, 5, 7].

An important component of the UIS design is an unification of information resources of unified information space, which should satisfy certain principles [4, 5, 8].

The design of UIS should be based on a holistic conception and is based on the specialized information project presented at the level of individual organizations [6, 9].

For the formation of the UIS the basic element is information objects (IO). Practically, the UIS includes a set of data, databases and data banks, technologies for their management and use, information and telecommunication systems and networks functioning on the basis of uniform principles and according to general rules providing the information interaction between objects [10 - 16].

In practice, it very often turns out that in the case of loss of communication with an information object, the information about this IO must be collected on the basis of the history of its interaction with other information objects within the framework of the UIS [17 - 22].

Unfortunately, the modern scientific publications on UIS issues are general in nature or are specified in special subject areas. Actual issues relating to the technology for restoring the UIS based on the analysis of the behavior of the IOs and the prehistory of their interaction are almost not considered.

The goal of this article is to develop the method of restoring parameters of information objects in a Unified Information Space based on computer networks. This method will allow restore the missing parameters of information objects in the case of loss of communication with this object and thereby restore the unity and integrity of the interaction of IO in the UIS.

III. THE MAIN ELEMENTS OF THE UIS, INTERACTION OF INFORMATION OBJECTS IN THE UIS

The creation of the UIS is intended to provide access to general information without limiting the space and time. The basis of the UIS is a set of computer systems, local networks, open networks (Internet), software (operating system, application programs, databases, postal services). Also during creation, the means of interfacing various computer systems with each other are formed [3, 17].

Identification of the object in the UIS allows uniquely identify an information object (IO) by its features. To define an IO, identification method can be used based on step-by-step analysis of an object's features using requests to an object in order to provide an opportunity to analyze intermediate results for making decisions on the IO identification [23 – 25].

The IO identification is performed according to certain external or internal features of the IO, taking into account IO interaction in the UIS. For this each IO is supplied with an IO image — a set of parameters that characterize the object to a certain extent. Similarly, in the form of a brief description - the image of the IO request (IR) - an information request is made to the IO. Due to this, the procedure of identification of the IO comes down to a simple comparison of the IO with the specified image of the request. If the parameters of the IO are necessary and sufficiently coincide with the IR, it is considered that IO is identified [10 – 13].

The process of placing information objects in the UIS occurs as follows: the initiating subject, as operations are completed, transmits the primary information about the information object to the UIS integrator subject through the communication network [26, 27].

Information objects of a unified information space of an enterprise are processed by integrator subjects to perform their functions in their area of responsibility. The integrator subjects, having received primary information from the initiating subjects, generalize and integrate the information objects of the UIS.

Some of the information is entered into a uniform information base for all subjects to use, and the remaining part of the information is used only by certain subjects who have corresponding access to information.

Integrated objects are used by each local subject to obtain information about the subject area in a unified information space.

The interaction of information objects in the UIS will be presented in the form of a network structure. There are several options for such structures:

1. A fully connected topology (Fig. 1) - each information object is connected with each other (IO1 – IO6). However, the number of links is redundant. This
kind of topology is used relatively rare.

2. Tree topology (Fig. 2) - there is a main information object IO1 and there are objects that are subordinate to it (IO2 – IO6).

3. Multi-tiered graph (Fig. 3) - there are only vertical links between information objects (IO1 – IO13).

IV. METHOD FOR RESTORING THE PARAMETERS OF INFORMATION OBJECTS IN A UNIFIED INFORMATION SPACE

Consider ten information objects IO1 – IO10 that interact with each other (Fig. 4).

For each information object the matrix of parameters is constructed. Let each information objects IO1 – IO10 are characterized by five parameters:

Parameter P1 - has a range of values 0.6 .. 0.9
Parameter P2 - range of values 0.02 .. 0.05
Parameter P3 - range of values 70 .. 90
Parameter P4 - range of values 0.75 .. 0.95
Parameter P5 - range of values 60 .. 80

For each information object, parameter matrices are formed (Table 1):

Table 1. Parameters matrix for each information object

| Information object IO1 | P1 | P2 | P3 | P4 | P5 |
|------------------------|----|----|----|----|----|
| IO1                    | 0.6| 0.04| 71 | 0.75| 70 |
| IO2                    | 0.9| 0.025| 89 | 0.78| 68 |
| IO3                    | 0.62| 0.03| 72 | 0.8| 62 |
| IO4                    | 0.78| 0.045| 78 | 0.92| 68 |
| IO5                    | 0.6| 0.048| 83 | 0.9| 88 |
| IO6                    | 0.65| 0.021| 82 | 0.87| 72 |
| IO7                    | 0.6| 0.028| 81 | 0.91| 74 |
| IO8                    | 0.68| 0.029| 77 | 0.93| 79 |
| IO9                    | 0.89| 0.034| 74 | 0.83| 73 |
| IO10                   | 0.74| 0.033| 86 | 0.89| 71 |

| Information object IO2 | P1 | P2 | P3 | P4 | P5 |
|------------------------|----|----|----|----|----|
| IO1                    | 0.62| 0.043| 74 | 0.77| 60 |
| IO2                    | 0.79| 0.02| 86 | 0.79| 69 |
| IO3                    | 0.6| 0.04| 72 | 0.83| 68 |
| IO4                    | 0.8| 0.04| 85 | 0.89| 79 |
| IO5                    | 0.67| 0.037| 78 | 0.75| 74 |
| IO6                    | 0.6| 0.028| 81 | 0.8| 66 |
| IO7                    | 0.69| 0.029| 85 | 0.9| 78 |
| IO8                    | 0.8| 0.039| 79 | 0.83| 74 |
| IO9                    | 0.87| 0.04| 84 | 0.89| 78 |
| IO10                   | 0.78| 0.043| 79 | 0.79| 66 |

| Information object IO3 | P1 | P2 | P3 | P4 | P5 |
|------------------------|----|----|----|----|----|
| IO1                    | 0.68| 0.035| 89 | 0.78| 68 |
| IO2                    | 0.78| 0.045| 72 | 0.8| 62 |
| IO3                    | 0.61| 0.033| 78 | 0.92| 68 |
| IO4                    | 0.87| 0.05| 74 | 0.83| 73 |
| IO5                    | 0.65| 0.047| 86 | 0.89| 71 |
| IO6                    | 0.85| 0.024| 86 | 0.79| 69 |
| IO7                    | 0.68| 0.02| 79 | 0.79| 66 |
| IO8                    | 0.84| 0.02| 78 | 0.75| 74 |
| IO9                    | 0.87| 0.04| 78 | 0.92| 68 |
| IO10                   | 0.72| 0.03| 83 | 0.9| 88 |
If there is no connection for any information objects, i.e. the table that describes the parameters of this object is not available, it is necessary to consider the tables of other information objects with which it interacted, and integrate this data taking into account the weighting factors.

Weights are factors that reflect the significance or "weight" of a given indicator compared with other indicators that influence the information object under study. Thus, with an increase in the number of intermediaries with the help of which an information object interacted with another information object, the weight coefficient value decreases accordingly. As a result, it is necessary to create a new table of parameters for information objects, and to get the parameters themselves from those tables that remain available.

For example, if there is no connection with the IO3 information object, the values of the parameters IO3 (P1), IO3 (P2), IO3 (P3), IO3 (P4) and IO3 (P5) are unknown.

We build a new table (matrix) on the basis of links with the information objects with which it interacted (Table 2).

After calculations, we obtain the vector V3 (IO3) and the values of its parameters (2):

$$V_3(IO_3) = \begin{bmatrix}
0.73 \\
0.039 \\
73.77 \\
65.73
\end{bmatrix}$$

The initial vector (with which communication was lost) V3 (IO3) had the following values (3):

$$V_3(IO_3) = \begin{bmatrix}
0.68 \\
0.035 \\
89 \\
0.78 \\
68
\end{bmatrix}$$

The deviation (the difference of values between vectors) is (4):

$$Vid(IO_3) = \begin{bmatrix}
-0.05 \\
-0.004 \\
15.23 \\
-0.01 \\
2.27
\end{bmatrix}$$

The deviations obtained for each parameter of the IO3 information object are:
IO3: P1 = 7.35%; P2 = 11.43%; P3 = 17.11%; P4 = 1.28%; P5 = 3.34%

This suggests that it is possible to accurately restore unknown parameters in the absence of communication with an information object.

We considered the case when all the parameters are known in each information object. But in practice this happens quite rarely, therefore, we will further conduct several experiments for the case when unknown information will be present in each information object.

V. THE EXPERIMENTAL RESEARCH

Let us perform an analysis of how the topology of IO interaction links affects the restoration of the parameters of information objects.

A. A fully connected topology

Let us consider a computer network that consists of 10 computers, which will be considered as information objects IO1-IO10 and which interact with each other as shown in Fig. 5.

For each information a matrix of parameters is constructed. Let each information object IO1 – IO10 be characterized by five parameters:

Parameter P1 - random access memory (range of values 1.024GB, 2.048GB, step 0.512GB);
Parameter P2 - memory on the hard drive (range of values 0.24Tb, 0.360Tb, step 0.06Tb);
Parameter P3 - performance (range of values 2.2 MHz ... 2.6 MHz, step 0.2 MHz);
Parameter P4 - bandwidth (range of values 2.048 Mbit / s, 4.096 Mbit / s, step 1.024 Mbit / s);
Parameter P5 - information transfer rate (range of values 1.024 Mbit / s ... 2.048 Mbit / s, step 1.024 Mbit / s).

Let IO3 be the information object with which communication is lost. The number of intermediaries between IO3 and other information objects is equal to one (since the fully connected network topology is used). Weighting factor for the case of one intermediary equals 0.98.

The specified information objects with parameters are presented in table 3.

| IO  | P1       | P2   | P3   | P4       | P5       |
|-----|----------|------|------|----------|----------|
| IO1 | 1.536    | 0.3  | 2.6  | 3.072    | 1.024    |
| IO2 | 1.536    | 0.3  | 2.6  | 3.072    | 1.024    |
| IO3 | 1.024    | 0.24 | 2.4  | 4.096    | 1.024    |
| IO4 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO5 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO6 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO7 | 1.024    | 0.24 | 2.4  | 4.096    | 1.024    |
| IO8 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO9 | 1.536    | 0.3  | 2.6  | 3.072    | 1.024    |
| IO10| 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |

| IO  | P1       | P2   | P3   | P4       | P5       |
|-----|----------|------|------|----------|----------|
| IO1 | 1.536    | 0.3  | 2.6  | 3.072    | 1.024    |
| IO2 | 1.536    | 0.3  | 2.6  | 3.072    | 1.024    |
| IO3 | 1.024    | 0.24 | 2.4  | 4.096    | 1.024    |
| IO4 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO5 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO6 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO7 | 1.024    | 0.24 | 2.4  | 4.096    | 1.024    |
| IO8 | 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |
| IO9 | 1.536    | 0.3  | 2.6  | 3.072    | 1.024    |
| IO10| 2.048    | 0.36 | 2.4  | 3.072    | 1.024    |

Fig. 5. Interaction of information objects with fully connected topology of links
Experiment 1.1. In each information object, all parameters are known. A new table (matrix) is built on the basis of links with those information objects with which IO3 interacted (Table 4).

| IO3 | P1 | P2 | P3 | P4 | P5 |
|-----|----|----|----|----|----|
| IO1 | 1.024 | 0.36 | 2.4 | 4.096 | 1.024 |
| IO2 | 2.048 | 0.24 | 2.4 | 2.048 | 1.024 |
| IO3 | 2.048 | 0.24 | 2.2 | 4.096 | 1.024 |
| IO4 | 2.048 | 0.24 | 2.6 | 2.048 | 1.024 |
| IO5 | 1.536 | 0.36 | 2.4 | 2.048 | 1.024 |
| IO6 | 1.536 | 0.3 | 2.2 | 3.072 | 2.048 |
| IO7 | 1.536 | 0.3 | 2.6 | 4.096 | 1.024 |
| IO8 | 1.536 | 0.24 | 2.2 | 4.096 | 1.024 |
| IO9 | 1.536 | 0.24 | 2.2 | 4.096 | 1.024 |
| IO10| 1.536 | 0.3 | 2.2 | 3.072 | 2.048 |

Get the result:
Results Vector:
IO3: P1 = 1.577; P2 = 0.2838; P3 = 2.376; P4 = 3.041; P5 = 1.239

Initial Vector:
IO3: P1 = 2.048; P2 = 0.24; P3 = 2.2; P4 = 4.096; P5 = 1.024

Deviation:
IO3: P1 = -0.471 (-23%); P2 = 0.0438 (18.25%); P3 = 0.176 (8%); P4 = -1.055 (-25.75%); P5 = 0.215 (21%)

Experiment 1.2. Each information object has up to 10 unknown parameters (how many and which are randomly generated).

Deviation:
IO3: P1 = -0.5274 (-25.75%); P2 = 0.03154 (13.14%); P3 = 0.176 (8%); P4 = -1.055 (-25.75%); P5 = 0.1165 (11.37%)

Experiment 1.3. Each information object has up to 20 unknown parameters (how many and which are randomly generated).

Deviation:
IO3: P1 = -0.4429 (-21.62%); P2 = 0.04003 (16.68%); P3 = 0.176 (8%); P4 = -1.055 (-25.75%); P5 = 1.165 (11.37%)

Experiment 1.4. Each information object has up to 30 unknown parameters (how many and which are randomly generated).

Deviation:
IO3: P1 = -0.426 (-20.8%); P2 = 0.0471 (19.63%); P3 = 2.92; P4 = -1.055 (-25.75%); P5 = 1.208

Experiment 1.5. Each information object has up to 40 unknown parameters (how many and which are randomly generated).

Deviation:
IO3: P1 = -0.426 (-20.8%); P2 = 0.0471 (19.63%); P3 = 2.92; P4 = -1.055 (-25.75%); P5 = 2.028

The graphs are built of functions of dependences of the absolute values of deviations (in%) of parameters on the number of unknown parameters in information objects (Table 5, Fig. 6).

Table 5. Value of parameters deviations (in%) from the number of unknown parameters in information objects

| Number of unknown parameters | Parameter deviation (%) |
|------------------------------|-------------------------|
|                              | P1 | P2 | P3 | P4 | P5 |
| 0                            | 23 | 18.25 | 8 | 25.75 | 21 |
| 10                           | 25.75 | 13.14 | 8 | 25.75 | 11.37 |
| 20                           | 21.62 | 16.68 | 2.6 | 28.84 |
| 30                           | 25.75 | 6.5 | 18.68 |
| 40                           | 20.8 | 19.63 | 25.75 |
| 50                           | 23.75 | 13.4 | 23.75 |

In the same way, we conducted 9 more experiments and, using the results obtained, construct graphs of the dependence functions for the absolute values of deviations (in%) of parameters in each experiment. We calculated the dependencies of absolute values of parameter deviations (in%) in each experiment for parameters P2, P3, P4 and P5 of the information object IO3.
Next, we averaged the obtained experimental values, and we construct graphs of the dependence functions of the averaged values (in %) of parameters in 6 experiments. Also, set deviation level to 15% and determine how many parameters fall into this area (Fig. 8). The value of the deviation level was taken after a detailed analysis of the data obtained, and it corresponds to the level of the data cut-off from the point of view of their reliability.

If the data obtained is below a given level of deviation, then it is considered reliable, i.e. it can be trusted; if above, the data obtained is not reliable, and it cannot be trusted.

Next, let us plot a histogram of the dependence of the parameter values up to the level of 20% - the critical number (reliability) of the parameters recovery in information objects (Fig. 9).
Fig. 9 shows that for a fully connected topology, three parameters (P1, P2 and P3) can be reconstructed with a quite high accuracy, in this case 60% parameters can be restored.

B. Tree topology

Consider a computer network, which consists of 10 information objects (computers) IO1-IO10, which interact with each other (Fig. 10).

The parameters of information objects (IO1 - IO10) are set in the same way as in the fully connected topology. Information object with which communication is lost - IO3. The number of intermediaries between IO3 and others - IO (the count starts from 1):
- IO3 and IO1 = 1;
- IO3 and IO2 = 2;
- IO3 and IO4 = 3;
- IO3 and IO5 = 3;
- IO3 and IO6 = 1;
- IO3 and IO7 = 4;
- IO3 and IO8 = 4;
- IO3 and IO9 = 2;
- IO3 and IO10 = 2

Weights:
- If there is 1 intermediary = 0.98;
- In the case of 2 intermediaries = 0.96;
- In case of presence of 3 intermediaries = 0.94;
- In case of 4 intermediaries = 0.92.

Similarly, experiments were conducted for tree topology and the following results were obtained:

The graphs of the dependence functions of the averaged values of the parameters in six experiments and the level of deviation of 15% are shown in Fig. 11.

The histogram of the dependence of the values of parameters up to the level of 20% is shown in Fig. 12.
From the histogram, it can be seen that with tree topology, two parameters (P2 and P3) can be reconstructed in this case with accuracy of 40% parameters can be restored.

C. Multi-tiered graph

Consider a computer network, which consists of 10 information objects (computers) IO1-IO10, which interact with each other (Fig. 13).

The parameters of information objects (IO1 I10) are set in the same way as in the fully connected topology. Information object with which communication is lost – is IO3. The number of intermediaries between IO3 and others - IO (the count starts from 1):

IO3 and IO1 = 4; IO3 and IO2 = 2; IO3 and IO4 = 2; IO3 and IO5 = 3; IO3 and IO6 = 1;
IO3 and IO7 = 1; IO3 and IO8 = 2; IO3 and IO9 = 2; IO3 and IO10 = 2

Weights:
If there is 1 intermediary = 0.98;
In the case of 2 intermediaries = 0.96;
In case of presence of 3 intermediaries = 0.94;
In case of 4 intermediaries = 0.92.

Similarly, experiments were conducted for multi-tiered graph and the following results were obtained:

The graphs of the functions of the dependences of the averaged values (in%) of the parameters in six experiments are presented in Fig. 14. Also, set the deviation level to 15% and determine how many parameters fall in this area.

The histogram of the dependence of the values of the parameters up to the level of 20% is shown in Fig. 15.
From the histogram (Fig. 15) it can be seen that in the multi-tiered graph one parameter (P3) can be reconstructed in this case with accuracy of 20% parameters can be restored.

VI. CONCLUSIONS

The article describes a method for calculating averaged values taking into account weights for restoring lost parameters of information objects, which was applied in turn to three network topologies: fully connected topology, tree topology and a multi-tiered graph. Using this technology, we experimentally found that when using it for a fully connected topology, we can recover (get reliable data) three parameters out of five, in tree topology two parameters out of five, and in a multilevel graph one parameter out of five. That is, we prove that here is a clear dependence of the obtained results about the parameters restoration from the selected topologies.

Thus, for the formation of the structure of relations between the information objects in a single information space, the most optimal is the topology with a fully connected links between the information objects. In the case if there is possible to form this topology, then it is most preferable. As an alternative, we may use a tree topology, but it provides the lower accuracy of parameter recovery compared to a fully connected one and can be effective, specially in the case when there are exist the formal hierarchical relationships and links between information objects in the single information space.

In order to form efficiently an unified information space and to achieve high-quality results, it is necessary to develop: algorithms and software tools to support the technology of recovery of information objects based on the results of their interaction in the unified information space; create a set of tools for the formation of the UIS on the basis of existing individual mechanisms for IO supporting; create the testing tools for the mechanisms for UIS forming.

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