Finite amplitude waves under a small resonant driving force

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Abstract

We construct a special asymptotic solution for the forced Boussinesq equation. The perturbation is small and oscillates with a slowly varied frequency. The slow passage through the resonance generates waves with the finite amplitude. This phenomenon is described in details.

Introduction

The Boussinesq equation is one of fundamental equations of the mathematical physics. It naturally appears when one investigates the propagation of long waves into nonlinear media. The Boussinesq equation is the basic model for the description of surface waves [1],[2],[3]; cross-axis oscillations of the balks and rods. It describes wave phenomenons in plasma and optical fibers [4],[5].

We consider the forced Boussinesq equation

\[ U_{tt} - U_{xx} + a(U_x)^2 + bU_{xxxx} = \varepsilon^2 F. \]

The external perturbation has the different meaning for various applications: periodic influences on rods or an external pumping in optical media. The characteristic feature is the periodic nature of the external perturbation. Here we consider the such type of the perturbation

\[ U_{tt} - U_{xx} + a(U_x)^2 + \varepsilon\gamma U_{xxxx} = \varepsilon^2 f(\varepsilon x) \exp\{iS(\varepsilon^2 x, \varepsilon^2 t)/\varepsilon^2\} + \text{c.c.,} \quad (1) \]

where \( \varepsilon \) is a small positive parameter; \( a, \gamma \) are constants. The amplitude \( f(y) \) of the driving force is bounded and rapidly vanished function, when \( |y| \to \infty \).

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We investigate the simplest case $S = S(\varepsilon^2 t) = (\varepsilon^2 t)^2/2$. It allows us to avoid the complicated calculations and saves the essence of the phenomenon.

Before the resonance oscillations are realized under the perturbation. In a neighborhood of the curve $t = 0$ the driving force becomes resonant and it leads to the change of the solution behaviour. The solution contains two waves of the finite amplitude after the slow passage through the resonance. In contrast to known papers related to the slow passage through resonance [6], [7], [8] in this situation we obtain waves with the amplitude of $O(1)$. This large increase of the order of the solution follows from the resonance on the zero harmonic.

The paper has the following structure. In the first section we briefly describe the result of the article and explain the observed phenomenon. The second section presents results of numerical simulations. Then we realize analytical asymptotic constructions. The forced oscillating solution of order $\varepsilon^2$ is constructed in the third section. The forth section contains the constructions in a neighborhood of the resonant curve. The behaviour of the solution after the passage through the resonance are described in the fifth section. All constructed asymptotic expansions are matched in the manner of [9].

1 Main result

The formal asymptotic solution for (1) is constructed in the certain domain. This domain is divided on several subdomains and covers the resonant line $t = 0$. Our special solution has a different representation in each subdomain.

The forced oscillations

$$U(x, t, \varepsilon) \sim \varepsilon^2 u_2(\varepsilon x, \varepsilon^2 t) \exp\{i(\varepsilon t)^2/2\}$$

describe the solution behaviour when $t < 0$. In a neighborhood of the resonant curve $t = 0$ the asymptotic solution is represented by

$$U(x, t, \varepsilon) \sim w_0(\varepsilon x, \varepsilon t)$$

The dynamics of the leading-order term $w_0$ is described in terms of the Fresnel integral. After the passage through the resonance the solution becomes $O(1)$

$$U(x, t, \varepsilon) \sim v_0^+(\varepsilon t + \varepsilon x, \varepsilon^2 t) + v_0^-(\varepsilon t - \varepsilon x, \varepsilon^2 t).$$

This postresonant domain corresponds to $t > 0$. The leading-order terms $v_0^+, v_0^-$ of the solution are determined from the pair of the Hopf equations (29). All these representations are matched.
2 Numerical simulations

In this section we present results of numerical simulations. They completely justify our asymptotic formulas and were done under the following conditions: $\varepsilon = 0.05$ and the perturbation looks like $\frac{1}{1 + (\varepsilon x)^4} \cos \left( \frac{(\varepsilon^2 t)^2}{2\varepsilon^2} \right)$. The figure shows the generation of two waves of the finite amplitude of $O(1)$.

3 The first external expansion

In this section we construct the asymptotic solution of (1) that corresponds to forced oscillations. This solution has the order $\varepsilon^2$ and oscillates under the perturbation.

3.1 Equations for coefficients

The WKB solution has the form

$$U(x, t, \varepsilon) = \left[ \varepsilon^2 u_2(x_1, x_2, t_2) + \varepsilon^4 u_4(x_1, x_2, t_2) + \varepsilon^6 u_6(x_1, x_2, t_2) \right] \exp \left\{ iS(t_2)/\varepsilon^2 \right\} + c.c., \quad (2)$$

where $x_m = \varepsilon^m x, t_m = \varepsilon^m t$ for $m = 1, 2$. 

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Substitute this representation into (11) and gather the terms with the same order with respect to $\varepsilon$. It yields the series of the algebraic equations

$$ (S')^2 u_2 = -f, \quad (3) $$

$$ (S')^2 u_4 = 2i S' \partial_{t_2} u_2 + i S'' u_2 - \partial_{x_1}^2 u_2, \quad (4) $$

$$ (S')^2 u_6 = i S'' u_4 + 2i S'' \partial_{t_2} u_4 + \partial_{t_2}^2 u_2 - \partial_{x_1} u_4 \quad (5) $$

Note that $S' = t_2$ in our model case. It allows one to obtain the exact representation for $u_n$.

$$ u_2 = -\frac{f}{t_2^2}, \quad (6) $$

$$ u_4 = \frac{3i f + \partial_{x_1}^2 f}{t_2^4}, \quad (7) $$

$$ u_6 = \frac{15 f - 10i \partial_{x_1}^2 f - \partial_{x_1}^4 f}{t_2^6}. \quad (8) $$

### 3.2 The domain of validity for external expansion (2)

One can see that equations (3) - (5) are not solvable, when $S' = 0$. Moreover the representation (2) loses the asymptotic property in a neighborhood of the curve

$$ l[S] = S' = t_2 = 0. \quad (9) $$

Using (6) - (8) we obtain the representation of the solution in a neighborhood of the resonant curve

$$ U(x, t, \varepsilon) = \left[ \varepsilon^2 \left( -\frac{f}{t_2^2} \right) + \varepsilon^4 \left( \frac{3i f + \partial_{x_1}^2 f}{t_2^4} \right) \right. $$

$$ + \left. \varepsilon^6 \left( \frac{15 f - 10i \partial_{x_1}^2 f - \partial_{x_1}^4 f}{t_2^6} \right) \right] \exp \left\{ i \frac{t_2^2}{2} \right\} + c.c. \quad (10) $$

Representation (2) saves the asymptotic property when

$$ \varepsilon \max_{x_1, x_2, t_2} |U_{n+1}| = o \left( \max_{x_1, x_2, t_2} |U_n| \right), \quad \varepsilon \to 0. $$

It yields the domain of validity

$$ -t_2 \gg \varepsilon. $$
In this section we construct the asymptotic expansion of the solution in a neighborhood of resonant curve \( \mathbf{9} \). Here we use new scaled variables \( x_1 \) and \( t_1 \) and construct the solution of the form

\[
U(x, t, \varepsilon) = w_0(x_1, t_1) + \varepsilon w_1(x_1, t_1) + c.c. \tag{11}
\]

### 4.1 Equations for coefficients

Let us substitute (11) into (1) and gather the terms of the same order with respect to \( \varepsilon \).

The leading-order term satisfies to

\[
\partial_{t_1}^2 w_0 - \partial_{x_1}^2 w_0 = f(x_1) \exp\{it_1^2\} + c.c. \tag{12}
\]

The first-order correction term is determined from

\[
\partial_{t_1}^2 w_1 - \partial_{x_1}^2 w_1 = -2a \left[ \partial_{x_1} w_0 \partial_{x_1}^2 w_0 + \partial_{x_1} w_0^* \partial_{x_1}^2 w_0 \right] + c.c. \tag{13}
\]

### 4.2 Solutions and asymptotics

First of all we solve equation (12). The equation for characteristics is

\[
\left( \frac{\partial \omega}{\partial t_1} \right)^2 - \left( \frac{\partial \omega}{\partial x_1} \right)^2 = 0, \tag{14}
\]

Introduce new characteristic variables

\[
y = t_1 + x_1, \quad z = t_1 - x_1.
\]

Then we obtain the equation for \( v(y, z) = w_0(x_1, t_1) \)

\[
4\partial_{yz}^2 v = f\left( \frac{y - z}{2} \right) \exp \left\{ \frac{i}{2} \left( \frac{y + z}{2} \right)^2 \right\} + c.c. \tag{15}
\]

The general solution of (15) is represented by

\[
4v(y, z) = V_1(y) + V_2(z) + \int_{-\infty}^{z} \int_{-\infty}^{y} f\left( \frac{\alpha - \beta}{2} \right) \exp \left\{ \frac{i}{2} \left( \frac{\alpha + \beta}{2} \right)^2 \right\} d\alpha d\beta + c.c., \tag{16}
\]

where \( V_1(y) \) and \( V_2(z) \) are arbitrary continuously differentiable functions.
To determine these functions \( V_1(y) \) and \( V_2(z) \) we match this leading-order solution with expansion (2). Let us to return to original variables

\[
 w_0(t_1 + x_1, t_1 - x_1) = W^+_0(t_1 + x_1) + W^-_0(t_1 - x_1) + \frac{1}{4} \int_{-\infty}^{t_1-x_1} \int_{-\infty}^{t_1+x_1} f \left( \frac{\alpha - \beta}{2} \right) \exp \left\{ i \left( \frac{\alpha + \beta}{2} \right)^2 \right\} d\alpha d\beta + \text{c.c.},
\]

and construct the asymptotics of (17), when \( t_1 \to -\infty \). The desired asymptotics is obtained by integration by parts

\[
 w_0 = \exp \left\{ \frac{i t_1^2}{2} \right\} \sum_{k=1}^{\infty} w_{0,2k} t_1^{-2k} + W^+_0(t_1 + x_1) + W^-_0(t_1 - x_1), \quad (18)
\]

where \( w_{0,2} = -f(x_1), w_{0,4} = 3if + \partial^2_x f \).

Matching asymptotics (18) and (10) allows one to determine terms outside the integral in (17). It yields \( W^+_0(t_1 + x_1) = W^-_0(t_1 - x_1) = 0 \).

The solution of (13) has the form

\[
 w_1 = \frac{1}{4} \int_{-\infty}^{t_1-x_1} \int_{-\infty}^{t_1+x_1} H(\alpha, \beta) d\alpha d\beta + W^+_1(t_1 + x_1) + W^-_1(t_1 - x_1), \quad (19)
\]

where

\[
 H(\alpha, \beta) = -2a \left( \partial_x w_0 \partial^2_x w_0 + \partial_x w_0^* \partial^2_x w_0 \right).
\]

After substituting (18) into (20) we obtain

\[
 w_1 = \frac{1}{4} \int_{-\infty}^{t_1-x_1} \int_{-\infty}^{t_1+x_1} \left[ \left( \frac{A(\alpha - \beta)}{(\alpha + \beta)^2} \right)^4 + O \left( \frac{\alpha + \beta}{2} \right)^6 \right] d\alpha d\beta + W^+_1 + W^-_1 + \text{c.c.} \quad (21)
\]

Taking the integral by parts gives

\[
 w_1 = \left( \frac{A(x_1)}{t_1^6} + O(t_1^{-8}) \right) \exp \{ it_1^2 \} + \left( \frac{A(x_1)}{6t_1^2} + O(t_1^{-4}) \right) \exp \{ it_1^2 \} + W^+_1(t_1 + x_1) + W^-_1(t_1 - x_1) + \text{c.c.} \quad (22)
\]

In these formulas we keep the leading-order terms of expansions only. This rough approach is sufficient to obtain the domain of validity of (14) when \( t_1 \to -\infty \) and match the solution with representation (10).

Matching with (10) yields \( W^+_1(t_1 + x_1) = W^-_1(t_1 - x_1) = 0 \).
Formulas (18) and (22) allow us to determine the domain of validity for (11) when $t_1 \to -\infty$. The condition
\[ \varepsilon \max_{x_2, t_2} |w_{n+1}| = o \left( \max_{x_2, t_2} |w_n| \right), \quad \varepsilon \to 0 \]
is equivalent $\varepsilon \ll 1$. It means that expansion (11) is valid for $t_1 < 0$.

### 4.3 Asymptotics as $t_1 \to +\infty$

In this subsection we construct asymptotics of $w_n$ as $t_1 \to +\infty$ and determine the domain of validity for internal expansion (11).

First of all we investigate the leading-order term $w_0$. As was shown above the coefficient $w_0$ is represented by formula (16). This formula can be written as follows
\[
\begin{align*}
w_0 &= \frac{1}{4} \int_{-\infty}^{\infty} \int_{-\infty}^{\infty} f \left( \frac{\alpha - \beta}{2} \right) \exp \left\{ i \left( \frac{\alpha + \beta}{2} \right)^2 \right\} d\alpha d\beta \\
&\quad - \frac{1}{4} \int_{-\infty}^{\infty} \int_{t_1 + x_1}^{\infty} f \left( \frac{\alpha - \beta}{2} \right) \exp \left\{ i \left( \frac{\alpha + \beta}{2} \right)^2 \right\} d\alpha d\beta \\
&\quad - \frac{1}{4} \int_{t_1 - x_1}^{\infty} \int_{-\infty}^{\infty} f \left( \frac{\alpha - \beta}{2} \right) \exp \left\{ i \left( \frac{\alpha + \beta}{2} \right)^2 \right\} d\alpha d\beta \\
&\quad + \frac{1}{4} \int_{t_1 - x_1}^{\infty} \int_{t_1 + x_1}^{\infty} f \left( \frac{\alpha - \beta}{2} \right) \exp \left\{ i \left( \frac{\alpha + \beta}{2} \right)^2 \right\} d\alpha d\beta + c.c.
\end{align*}
\]
After evident denotations we obtain
\[
w_0 = C + w_0^+(t_1 + x_1) + w_0^-(t_1 - x_1) + \frac{R(x_1, t_1)}{t_1^2} \exp \left\{ i \frac{t_1^2}{2} \right\} + c.c. \quad (23)
\]
The last term of (23) decreases when $|t_1| \to \infty$. This representation is obtained after single integration by parts.

To obtain the asymptotics of $w_1$ when $t_1 \to +\infty$ let us to analyze right-hand side (20). It contains several character terms
\[
\begin{align*}
f_1 &= g^+(t_1 + x_1) + g^-(t_1 - x_1) + g(t_1 + x_1, t_1 - x_1) + \frac{F_1(x_1, t_1)}{t_1^2} \exp \left\{ i t_1^2/2 \right\} \\
&\quad + \frac{F_2(x_1, t_1)}{t_1^2} \exp \left\{ -i t_1^2/2 \right\} + \frac{F_3(x_1, t_1)}{t_1^4} \exp \left\{ i t_1^2 \right\} + \frac{F_4(x_1, t_1)}{t_1^4}, \quad (24)
\end{align*}
\]
where
\[ g^\pm(t_1 \pm x_1) = -2a \left( \partial_{x_1} w_0^\pm \partial_{x_1}^2 w_0^\pm + \partial_{x_1} w_0^\pm \partial_{x_1}^2 w_0^\pm \right), \]

\[ g(t_1 + x_1, t_1 - x_1) = -2a \left( \partial_{x_1} w_0^+ \partial_{x_1} w_0^- + \partial_{x_1} w_0^- \partial_{x_1}^2 w_0^+ \right. \]
\[ \left. + \partial_{x_1} w_0^- \partial_{x_1}^2 w_0^+ + \partial_{x_1} w_0^+ \partial_{x_1}^2 w_0^- \right), \]

\[ F_1(x_1, t_1) = -2a \left( \partial_{x_1} R \left[ \partial_{x_1}^2 w_0^+ + \partial_{x_1}^2 w_0^- \right] \right. \]
\[ \left. + \partial_{x_1} R \left[ \partial_{x_1} w_0^+ \partial_{x_1} w_0^- + \partial_{x_1} w_0^- \partial_{x_1}^2 w_0^+ \right] \right), \]

\[ F_2(x_1, t_1) = -2a \partial_{x_1} R^* \left[ \partial_{x_1}^2 w_0^+ + \partial_{x_1}^2 w_0^- \right], \]

\[ F_3(x_1, t_1) = -2a \partial_{x_1} R \partial_{x_1}^2 R, \]

\[ F_4(x_1, t_1) = -2a \partial_{x_1} R^* \partial_{x_1}^2 R. \]

After integration we obtain the following asymptotics
\[
\begin{align*}
    w_1 &= (t_1 - x_1)w_1^+ + (t_1 + x_1)w_1^- + w_1^\pm + \frac{\tilde{F}_1}{t_1^4} \exp\{it_1^2/2\} \\
    &\quad + \frac{\tilde{F}_2}{t_1^4} \exp\{-it_1^2/2\} + \frac{\tilde{F}_3}{t_1^4} \exp\{it_1^2\} + \frac{\tilde{F}_4}{t_1^4} + c.c. \quad (25)
\end{align*}
\]

Here we denote
\[
\begin{align*}
    w_1^+ &= \frac{1}{4} \int_{-\infty}^{t_1 + x_1} g^+(y)dy, \\
    w_1^- &= \frac{1}{4} \int_{-\infty}^{t_1 - x_1} g^-(y)dy, \\
    w_1^\pm &= \frac{1}{4} \int_{-\infty}^{t_1 - x_1} \int_{-\infty}^{t_1 + x_1} g(y, z)dydz,
\end{align*}
\]

\[
\begin{align*}
\frac{\tilde{F}_1(x_1, t_1)}{t_1^4} \exp\{it_1^2/2\} &= \frac{1}{4} \int_{-\infty}^{t_1 - x_1} \int_{-\infty}^{t_1 + x_1} F_1 \left( \frac{y + z}{2}, \frac{y - z}{2} \right) \\
    \times \exp \left\{ \frac{i}{2} \left( \frac{y + z}{2} \right)^2 \right\} \left( \frac{y + z}{2} \right)^{-2} dydz,
\end{align*}
\]

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\[
\tilde{F}_2(x_1, t_1) \exp\{-it_1^2/2\} = \frac{1}{4} \int_{-\infty}^{t_1-x_1} \int_{-\infty}^{t_1+x_1} F_2 \left( \frac{y + z}{2}, \frac{y - z}{2} \right) \exp \left\{ -\frac{i}{2} \left( \frac{y + z}{2} \right)^2 \right\} \left( \frac{y + z}{2} \right)^{-2} dy dz,
\]
\[
\tilde{F}_3(x_1, t_1) \exp\{it_1^2\} = \frac{1}{4} \int_{-\infty}^{t_1-x_1} \int_{-\infty}^{t_1+x_1} F_3 \left( \frac{y + z}{2}, \frac{y - z}{2} \right) \exp \left\{ i \left( \frac{y + z}{2} \right)^2 \right\} \left( \frac{y + z}{2} \right)^{-4} dy dz,
\]
\[
\tilde{F}_4(x_1, t_1) = \frac{1}{4} \int_{-\infty}^{t_1-x_1} \int_{-\infty}^{t_1+x_1} F_4 \left( \frac{y + z}{2}, \frac{y - z}{2} \right) \left( \frac{y + z}{2} \right)^{-4} dy dz.
\]
To determine the domain of validity for (11) we use the inequality
\[
\varepsilon \max_{x_1, t_1} |w_{n+1}| = o \left( \max_{x_1, t_1} |w_n| \right), \quad \varepsilon \to 0.
\]
It yields
\[
|t_1 \pm x_1| \ll \varepsilon^{-1}.
\]

5 The second external expansion

In this section we construct the second external expansion that describes the behaviour of the solution after the slow passage through the resonance.

5.1 Equations deriving

We construct the solution of the form
\[
U(x, t, \varepsilon) = C + v_0^+(t_1 + x_1, t_2) + v_0^-(t_1 - x_1, t_2) + \varepsilon \left[ v_1^+(t_1 + x_1, t_2) + v_1^- (t_1 - x_1, t_2) + v_1(t_1 + x_1, t_1 - x_1, t_2) \right] + \varepsilon^2 \left[ v_{2,S}(x_1, t_2) \exp\{iS/\varepsilon^2\} + v_2^+(t_1 + x_1, t_2) + v_2(t_1 - x_1, t_2) + v_2(t_1 + x_1, t_1 - x_1, t_2) \right] + c.c.
\]
(26)
The coefficients of (26) are determined recurrently. The function \( v_{2,S} \) is determined from the traditional algebraic equation
\[
-(S')^2 v_{2,S} = f.
\]
(27)
On the next step we obtain the differential equation
\[ 2\partial_{t_2}\zeta v_0^+ + 2a\partial_\zeta v_0^+ \partial_\zeta v_0^+ + 2\partial_{t_2}\eta v_0^- + 2a\partial_\eta v_0^- \partial_\eta v_0^- + 4\partial^2_{\zeta \eta} v_1 = 0, \quad (28) \]
where \( \zeta = t_1 + x_1 \) and \( \eta = t_1 - x_1 \). Consider this equation as equation for \( v_1 \). It is easy to see there is a special structure of the right-hand side of the equation
\[ \partial^2_{\zeta \eta} v_1 = f^+(\zeta, t_2) + f^+(\eta, t_2) \]
To avoid the secular increase of \( v_1 \) we obtain that \( \partial^2_{\zeta \eta} v_1 = 0 \). It allows us to derive equations for the leading-order terms
\[ \begin{align*}
\partial^2_{t_2^2}\zeta v_0^+ + a\partial_\zeta v_0^+ \partial_\zeta v_0^+ &= 0, \\
\partial^2_{t_2^2}\eta v_0^- + a\partial_\eta v_0^- \partial_\eta v_0^- &= 0.
\end{align*} \]
By substitution \( V^+ = \partial_\zeta v_0^+ \) and \( V^- = \partial_\eta v_0^- \) we get the pair of the Hopf equations
\[ \begin{align*}
\partial_{t_2}V^+ + aV^+ \partial_\zeta V^+ &= 0, \\
\partial_{t_2}V^- + aV^- \partial_\eta V^- &= 0. \quad (29)
\end{align*} \]
Functions \( v_1^+, v_1^-, v_2^+, v_2^- \) are determined in much the same way.

### 5.2 The domain of validity for (26)

The usual condition for validity
\[ \varepsilon \max_{x_1, t_1, x_2, t_2} |v_{n+1}| = o\left( \max_{x_1, t_1, x_2, t_2} |v_n| \right), \quad \varepsilon \to 0 \]
yields
\[ t_2 \gg \varepsilon. \]

### Concluding remarks

The realized rough analytical and numerical calculations allow one to obtain the finite amplitude waves due to the slow passage through the resonance of the small driving force. As it was mentioned above this large increase of the amplitude takes place due to the resonance on the zero harmonic. It becomes clear that this approach is evaluable for the phase \( S(x, t) \) of more general type. The construction and matching of infinite asymptotic series are possible also. The such type representation of the solution for the original
problem opens the way for a justification of the constructed asymptotics. But this is a theme for our future investigations.

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