Data Article

Experimental datasets of networks of nonlinear oscillators: Structure and dynamics during the path to synchronization

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A B S T R A C T

The analysis of the interplay between structural and functional networks require experiments where both the specific structure of the connections between nodes and the time series of the underlying dynamical units are known at the same time. However, real datasets typically contain only one of the two ways (structural or functional) a network can be observed. Here, we provide experimental recordings of the dynamics of 28 nonlinear electronic circuits coupled in 20 different network configurations. For each network, we modify the coupling strength between circuits, going from an incoherent state of the system to a complete synchronization scenario. Time series containing 30000 points are recorded using a data-acquisition card capturing the analogic output of each circuit. The experiment is repeated three times for each network structure allowing to track the path to the synchronized state both at the level of the nodes (with its direct neighbours) and at the whole network. These datasets can be useful to test new metrics to evaluate the coordination between dynamical systems and to investigate to what extent the coupling

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strength is related to the correlation between functional and structural networks.

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Specifications Table

| Subject | Physics |
|---------|---------|
| Specific subject area | Nonlinear dynamics, complex networks, synchronization. |
| Type of data | - Tables  
- Graphs  
- Figures  
- Times series in text file |
| How data were acquired | - We used a Data Acquisition Card (DAQ), NI USB-6363 to acquire the voltage of $N = 28$ nonlinear electronic oscillators connected through a complex network.  
- 20 different network structures were implemented.  
- For each structure, the time series (30000 points) corresponding to 100 different coupling strengths are recorded.  
- The full experiment is repeated three times for each network structure |
| Data format | - Raw Data. |
| Parameters for data collection | - Time series are given in a plain text file.  
- Sampling frequency of 30K/S  
- Filtered using a Butterworth order 3 low-pass filter with a cut-off frequency of 1500 Hz.  
- 30000 points for each time series  
- Resolution of 16 bits  
- Range of the ADC: Form $-5V$--$5V$ |
| Description of data collection | Datasets consists of the structure and dynamics of electronic arrays of $N = 28$ Rössler circuits operating at the chaotic regime. The configuration of the coupling variables make the circuits to be class II system in the classification given by the Master Stability Function. Using a multichannel DAQ, the voltage corresponding to one of the variables of each Rössler oscillator was acquired using the analogue ports (AI-0, AI-1, ..., AI-27). An in-house electronic coupler was the responsible of defining the structure and strength of the coupling between the oscillators. 20 different network structures were implemented and recorded. A digital potentiometer was used to change the coupling strength between the nodes, which was controlled by means of the digital ports (P0.0 P0.1) of the DAQ card. In this way, we were able to turn the dynamics of the network from an incoherent behaviour (low coupling strength) to a fully synchronized state (high coupling strength). |
| Data source location | Institution: Centro Universitario de los Lagos (Universidad de Guadalajara)  
City/Town/Region: Lagos de Moreno, Jalisco.  
Country: Mexico |
| Data accessibility | With the article  
Repository name: [Zenodo]  
Data identification number: [10.5281/zenodo.3521009]  
Direct URL to data: https://doi.org/10.5281/zenodo.3521009 |

Value of the Data

- We provide the time series of a $N = 28$ networked system in its path to synchronization for 20 different network structures. Datasets allow investigating the interplay between the dynamics of a set of nonlinear dynamical systems with the specific underlying structure and the coupling needed by the network to synchronize.  
- Datasets can be used to develop new metrics to evaluate synchronization between nonlinear systems. However, the main merit of the datasets is having at the same time the structure and dynamics of 20 different networks. This is not so common since, in most real cases, we have datasets concerning only the structure of the networks (e.g., road networks, power grids, cortical networks, ...) or only the dynamics (e.g., electroencephalography, functional magnetic resonance). Therefore, studies about the interplay between structural and functional networks could benefit from the current datasets.  
- It is one of the very few cases where the structure and dynamics of a networked system is known (with precision) at the same time. In addition, the existence of the intrinsic noise and tolerance of the electronic components can be used as an evidence of the robustness of the eventual analysis.
1. Data

The datasets contain the structure of 20 networks composed of 28 Rössler electronic oscillators, with each network having a different structure. The number of oscillators is limited by the analogue ports of the data acquisition card (DAQ), however, it is fully scalable as long as a DAQ with higher number of analogue ports is used. We also include the dynamics of the 28 nodes for 100 different values of the coupling strength, which allows tracking the path to synchronization in all structural networks. Fig. 1 describes the network structure and the degree distribution for all the experiments, the latter being maintained for all network structures. Fig. 2 shows the eigenvector centrality of each node for all network structures. Fig. 3 describes the evolution of the time series when the coupling strength between nodes is increased. Fig. 4 shows the Rössler oscillators placed at the nodes of the networks. Fig. 5 describes the coupling circuit between nodes. Figs. 6 and 7 show a photograph of the experimental array and the corresponding schematic representation.

![Schematic representation of the structural networks.](image1)

**Fig. 1.** Schematic representation of the structural networks. (Left) Example of one network structure used for the experiment; the size of the nodes is proportional to their degree (number of neighbours). (Right) Degree distribution of the nodes, which was maintained for the 20 network structures.

![Eigenvector centrality](image2)

**Fig. 2.** Eigenvector centrality. Node centrality for each of the 20 network structures. Warm colors correspond to nodes with high centrality.
2. Experimental design, materials, and methods

We provide the times series of $N = 28$ Rössler electronic oscillators for 20 different network configurations (compressed file with tags from R1 to R20). For each network structure, we recorded the times series for 101 different coupling strengths between oscillators. Each one of the 101 corresponding files is labelled as $\text{ST}_X_Y.dat$ where $X$ is a value between $X = 0$ and $X = 100$ that corresponds to the minimum ($\kappa = 0$) and maximum coupling strength ($\kappa = 1$), respectively. The value of $Y$ indicates the

Fig. 3. Time series of the second variable $v_2$ (see Eqs (1)–(3)) of the oscillators of Network 1 at different coupling values for: a) File ST_1_1 ($\kappa = 0$), b) File ST_10_1 ($\kappa = 0.1$), c) File ST_50_1 ($\kappa = 0.5$), and d) File ST_100_1 ($\kappa = 1$).

Fig. 4. Electronic representation of the Rössler-like system. See the specific values of the resistances and capacitors at Table 1.
number of repetition, which can be 1, 2 or 3 (i.e., we repeated the same experiment three times). Data files contain the second variable of the 28 nodes (see variable $v_2$ of Eqs. 1-3) arranged in columns with a length of 30000 points. In a second file named Structure.zip, all network structures are given, each file having a name Net_R.dat, where $R = 1, 2, ..., 20$. The degree of each node (i.e., number of output connections) is the same for all network configurations (see Fig. 1, right plot). However, the specific neighbours of each node are re-arranged randomly at each network structure.

2.1. Network properties

The structure of the 20 different network configurations is random. First, we assigned the degree of the nodes in order to have a high heterogeneity, i.e., we fixed the degree distribution. The reason is that

Fig. 5. Electronic representation of the coupler circuit responsible of the diffusive coupling between an electronic oscillator and its neighbours. We use an operational amplifier (Op-Amp) for the output of oscillator $i$ and each of its $j$ neighbours. Finally, we sum the input of all incoming neighbours. In the coupler circuit, all resistances are set to 1 kΩ.

Fig. 6. Photograph of the experimental array using 28 nonlinear oscillators and their corresponding electronic couplers. The voltage of each oscillator was acquired by a DAQ card (NI USB 6363), shown at the top right corner of the photograph.
we wanted to have hubs and also nodes with a low degree, with the aim of promoting further works relating the degree of the nodes with their synchronization properties. Next, for each structural network, we re-arranged the connection between nodes maintaining their degree. In this way, we generated a group of datasets where the structure of the networks, and not the degree distribution, induced changes in the dynamics. As a consequence, the centrality of the nodes (i.e., its importance in the network) changed from network to network. To show this point, we computed the eigenvector centrality [4] of each node. In Fig. 2 we can observe the change of the node’s centrality for each network structure.

In Fig. 3 there is an example of the transition to synchronization, we can see the time series of the second variable of the electronic oscillator. In Fig. 3(a) we can see how when the coupling is zero (κ=0), the oscillators evolve independently. However, when the coupling increases (κ=0.1 in b and κ=0.5 in c); oscillators begin to evolve together, until they reach complete synchronization (κ=1 in d). The value of the coupling strength κ is proportional to the incoming impedance to each oscillator of the network [see Eq. (2)].

2.2. The dynamical system

Each node of the network contains a Rössler-like nonlinear oscillator. The detailed components and connections are shown in Fig. 4. The dynamics of an oscillator i is given by the following equations [2,3]:

\[ \dot{v}_{1i} = - \frac{1}{R_1 C_1} \left( \frac{v_{1i} + R_1}{R_2} \frac{v_{2i} + R_1}{R_4} + \frac{v_{3i}}{R_3} \right) \]  \hspace{1cm} (1)

\[ \dot{v}_{2i} = - \frac{1}{R_5 C_2} \left( \frac{R_6 R_8}{R_7} v_{1i} + \left[ 1 - \frac{R_6 R_8}{R_5 C_7} \right] v_{2i} - \kappa \frac{R_5}{R_{15}} \sum_{j=1}^{N} A_{ij} (v_{2j} - v_{2i}) \right) \]  \hspace{1cm} (2)

\[ \dot{v}_{3i} = - \frac{1}{R_{10} C_3} \left( - \frac{R_{10}}{R_{11}} G(v_{1i}) + v_{3i} \right) \]  \hspace{1cm} (3)
where \( v_1, v_2 \) and \( v_3 \) correspond to the three voltages describing the dynamical state of each electronic oscillator, is the adjacency matrix containing the specific structure of the network (\( a_{ij} = 1 \) if circuit \( i \) is connected to circuit \( j \), and 0 otherwise), \( R_i \) are resistances, \( C_i \) are capacitors (see Table 1) and \( G_{v_1} \) is a piecewise nonlinear function given by:

\[
G_{v_1} = \begin{cases} 
0, & v_1 \leq V_d + V_d \frac{R_{14}}{R_{13}} + V_e \frac{R_{14}}{R_{13}} \\
 \frac{R_{12}}{R_{14}} v_1 - V_e \frac{R_{12}}{R_{13}} - V_d \left( \frac{R_{12}}{R_{13}} + \frac{R_{12}}{R_{14}} \right), & v_1 > V_d + V_d \frac{R_{14}}{R_{13}} + V_e \frac{R_{14}}{R_{13}} 
\end{cases}
\]

The output voltage \( v_2 \) of each nonlinear oscillator is sent to an electronic coupler to introduce the diffusive coupling \( (v_2 - v_2) \) between oscillator \( i \) and each of its neighbours (see Fig. 5).

In the case of the Rössler oscillator the coupling through variable \( v_2 \) ensures that the system is class II, following the classification of the Master Stability Function, and therefore the ensemble will be able of synchronizing above a threshold value of \( \kappa \) for any topological configuration [1].

2.3. The experimental setup

The coupling strength between the nonlinear electronic circuits was controlled by means of digital potentiometers (model X9C103), which acted as voltage divisors with a maximum resistance of 10 kΩ corresponding to a zero coupling. These potentiometers were controlled through the digital ports (P0.0, P0.1) of a DAQ card. First, we set the coupling value of all circuits to zero and then, after a transitory of 500 ms, we recorded the time series of each network: All variables \( v_2 \) of each oscillator \( i \) were acquired by the DAQ card through the analogue ports (AI0, AI1, ..., AI27) and saved into the computer. Next, the coupling strength between all nodes was increased one step (0.01) by means of digital pulses that were sent to the potentiometers, decreasing the coupling resistance 100Ω each step, until the maximum value of \( \kappa \) was reached (i.e., when digital potentiometers are set to 0 Ω). All the experiment was controlled from a computer using the LabVIEW software (see Figs. 6 and 7).

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Conflict of Interest

The authors declare that they have no known competing financial interests or personal relationships that could have appeared to influence the work reported in this paper.
Appendix A. Supplementary data

Supplementary data to this article can be found online at https://doi.org/10.1016/j.dib.2019.105012.

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