Bernoulli mapping with hole and a saddle-node scenario of the birth of hyperbolic Smale–Williams attractor

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Abstract

One-dimensional Bernoulli mapping with hole is suggested to describe the regularities of the appearance of a chaotic set under the saddle-node scenario of the birth of the Smale–Williams hyperbolic attractor. In such a mapping, a non-trivial chaotic set (with non-zero Hausdorff dimension) arises in the general case as a result of a cascade of period-adding bifurcations characterized by geometric scaling both in the phase space and in the parameter space. Numerical analysis of the behavior of models demonstrating the saddle-node scenario of birth of a hyperbolic chaotic Smale–Williams attractor shows that these regularities are preserved in the case of multidimensional systems. Limits of applicability of the approximate 1D model are discussed.

1 Introduction

The saddle-node scenario of the birth/destruction of the Smale–Williams solenoid in a dynamical system under variation of its parameters [1, 2] assumes a situation where at first the hyperbolic chaotic attractor coexists with another attractor (possibly an infinitely distant one), and its destruction occurs as a result of a collision/fusion with a saddle chaotic set lying on a common boundary of their basins of attraction [3, 4]. In the extended space of phase variables and the control parameter, this scenario can be regarded as a bifurcation “return point” at which the attracting solenoid loses stability and turns into a saddle set (see scheme at Fig. 1). If we consider this scenario when moving along the control parameter from the side where the chaotic attractor does not yet exist, then we will observe the gradual simultaneous birth of two chaotic sets, which eventually become a hyperbolic attractor and a chaotic saddle. Thus, this bifurcation is prolonged and occupies a certain interval ($p_1, p_2$) over the control parameter. A numerical experiment shows that the order in which the trajectories inhabiting these sets originate depends on the parameters of the system. Which trajectories appear first, at what point the first non-trivial chaotic set of trajectories arises from virtually nothing, which trajectories complete the process of formation of the chaotic attractor – these questions need to be answered in order to reveal the laws governing this order. The study of full-size systems is complicated by the fact that one has to deal with highly unstable cycles. An important role is played here by simple low-dimensional models, which allow deep mathematical study.

In this paper, it is proposed to use the one-dimensional Bernoulli mapping with a "gap" or "hole" to describe the Smale–Williams solenoid nascence process [10, 11, 12, 13, 18, 19, 20]. The mapping is well understood, which allows us to use the results of these studies to identify the features of the saddle-node scenario.

In the first section we show how the Bernoulli map with a hole arises in our case. The second section briefly describes its main properties. The third section demonstrates how the patterns characteristic of this mapping work in the case of saddle-node scenario, and also discusses the scope of its applicability for these purposes.

2 Saddle-node scenario of the birth of chaotic attractor in the two-dimensional noninvertible model map

We start with the model complex map (1) introduced in [3, 4]:

$$z' = \frac{Rz(z + \varepsilon)}{\sqrt{1 + |z(z + \varepsilon)|^2}}.$$  (1)

For sufficiently small values of the parameter $\varepsilon$, the dynamics of the phase of the complex variable $z = \rho \exp(i\phi)$ are approximately described by the Bernoulli map, $\phi_{n+1} = 2\phi_n \pmod{2\pi}$. The map (1) has a stable fixed point
Figure 1: Scheme of the saddle-node scenario of the hyperbolic Smale–Williams attractor birth/destruction: projection of the extended space of phase variables and the control parameter is represented; structure, formed by the colliding stable solenoid and saddle chaotic set, is shown on the left panel; the same structure with cut off quarter part is shown on the right panel.

At the origin, $\rho = 0$. At values $R \approx \sqrt{2}$ and more, another attractor $A$ appears in the region $\rho \approx R$, which is chaotic. Taking into account the dynamics of the phase, it can be regarded as a two-dimensional projection of the Smale–Williams attractor.

On the common boundary of the attraction basins of both attractors there is another chaotic set $S$, which is absolutely unstable. As the parameter $R$ is decreased, the attractor $A$ collides with the set $S$ and disappears, leaving only one attractor at the origin. Thus, the mapping (1) with variation of the parameter $R$ demonstrates a transition of the same type as the Smale–Williams attractor under the saddle-nodal scenario.

It is known that the trajectories belonging to the attractor are encoded using symbolic sequences of two symbols. Periodic sequences correspond to periodic orbits. Each trajectory on the attractor corresponds to a dual trajectory on the chaotic set $S$. When two sets collide, they annihilate and disappear as a result of the saddle-node bifurcation. For different orbits, these bifurcations occur not simultaneously, but for different values of the parameter $R$. This leads to the fact that the process of collision of two chaotic sets is distributed in a certain critical range of the parameter values $R \in [R_1, R_2]$. For example, for $\varepsilon = 0.2$, the interval of destruction of the attractor $A$ is determined by the values

$$R_1 = 1.276508545718, R_2 = 1.482417271474.$$  \hspace{1cm} (2)

With increasing parameter $\varepsilon$ this interval widens.

Let us consider in more detail how the cycle of period 1 disappears. If we take a value of $R$ from the critical interval, then the phase dynamics continues to be described by a Bernoulli type map and weakly depends on the radial component over a certain range of values of $\rho$ (see Fig. 2), where the the graph of the complex phase component of the mapping (1) is presented for $\rho = 1$). As for the behavior of the radial component, depends on the value of the phase $\phi$, the map for the variable $\rho$ shows a tangent bifurcation of the birth (or disappearance) of a pair of fixed points (see Fig. 2), where the graphs of the mapping are given for different values of the phase $\phi$).

Figure 3 shows a diagram in which the white color indicates the range of phase values for which the radial dynamics demonstrates a stable fixed point, and gray – those for which there are no fixed points (except that at the origin). The domain of the mapping for the phase is split in two intervals, depending on the existence of a stable fixed point in the mapping for the radial component. A fixed point in the mapping (1) exists only if the fixed point of the Bernoulli map for the phase falls into the interval where there is a fixed point for the radial component. Otherwise, the fixed point of the map (1) disappears at the edge of the gray zone as a result of the saddle-node bifurcation.

The situation can be considered in such a way that there is a "forbidden zone" in phases, when a fixed point disappears into it. Obviously, the presence of such a zone also affects the stability of longer-period cycles – if sufficiently many points of the orbits of the Bernoulli mapping fall into a forbidden zone, then such a cycle in the map (1) also disappears. If we extremely simplify the situation and assume that any orbit disappears, at least one
Figure 2: The phase and radial components of the mapping at $R=1.35$.

Figure 3: The complex phase diagram of the mapping at $R = 1.35$. Numbers denote areas of different behavior of the radial component of the map, typical graphs for each of them are presented in Fig. 2b.
point of which falls into the forbidden band, then we arrive at the simplest one-dimensional model that describes disappearance of the trajectories under the saddle-node scenario – the Bernoulli map with a "forbidden zone" or "hole".

3 A model in the form of a Bernoulli mapping with a hole

The mapping $T$ of the Bernoulli shift with the forbidden interval of values of the variable, when hit in which the trajectory is considered impossible (in real models this corresponds to running away to another attractor, possibly at infinity)

$$x_{n+1} = \begin{cases} 2x_n \mod 1, & x_n \notin H^0, \\ \text{not defined, otherwise}, & \end{cases} \text{ where } H^0 = [a + b/2, a - b/2]. \quad (3)$$

The parameters $a$ and $b$ here are responsible for the position of the center and the width of the hole, respectively.

![Figure 4: An iterative diagram of the Bernoulli map with a "hole" $H^0$ (gray strip) with center at $a$ and width $b$. Several inverse images of the forbidden band are also depicted.](image)

From the point of view of analogy with the system \(^1\), the parameter $b$ can be associated with the value $|R_3| - |R|$, that is, the degree of deepening into the critical interval. The parameter $a$ can be in turn associated with the argument of $R$, assuming this parameter is a complex value.

The set $C$ of points whose orbits do not enter the hole, $C(a, b) : = \{x \in [0, 1] : T^n x \notin (a, b), n \geq 0\}$, can be defined as the limit

$$C = \lim_{k \to \infty} C_k, \quad C_k = [0, 1] \setminus \bigcup_{j=0}^{k} H^{-j}, \quad (4)$$

where $H^{-j}$ is the union of all the $j$th inverse images of the original hole $H^0$ with all possible encodings (see the diagram in Fig. 4, where two preimages are given).

Fig. 5 shows the arrangement of the "position – width" parameter plane. The lines correspond to the boundaries of the existence of cycles of different periods. Below each of these boundaries, there is at least one cycle of the corresponding period. Symbols above the lines denote the symbolic code of the cycle that arises first of all the cycles of a given period on this section of the boundary

\(^1\) Models in the form of mappings with a hole and leakage were investigated earlier in [10, 11, 12, 13, 14, 15, 16, 17]. It was shown that the average "lifetime" of trajectories in such systems depends in a complex manner on the position of the band gap.
We define $\mathbf{D}$ as a set of points on the plane of the parameters $(a, b)$ for which the Hausdorff dimension of the set $C$ is not zero. In Fig. 5 the numerically calculated set $\mathbf{D}$ is highlighted in gray. The picture occurs to be symmetrical and only half of it is presented.

In [18] it was proved that the boundary of this set consists of points of three types:
1. the point at which from all non-periodic trajectories the first appears an orbit with a quasi-periodic symbolic code corresponding to irrational rotations of the circle maps [21];
2. the point at which from all non-periodic trajectories the first appears an orbit with a symbolic code corresponding to tupling (doubling, tripling ...) of the period;
3. the point at which out of all the non-periodic trajectories the first appears an orbit with symbolic code $B\{\}^\infty$, where $A$ and $B$ are some combinations of $R$ and $L$'s, such an orbit is often called pre-periodic to a certain cycle.

The transition through this boundary corresponds to appearance of a nontrivial chaotic set, so that this can be considered as a transition to chaos. Theorem proved in [18], states that this transition, depending on the point at which we cross the border can be, as stated above, the one of three possible types – via "quasiperiodicity", via period tupling, and via the occurrence of the preperiodic trajectory. The codimension of the first two types of points is equal to 2, they are isolated points on the parameter plane. Codimension of the set of the third type of critical points of transition to chaos is 1, that is, there are segments of lines consisting of such points on the parameter plane. (To be precise, we may add that codimension of the critical behavior of this type may be also 2. This corresponds to points at the ends of the segments). To these lines from below the lines are accumulating of appearance of cycles, symbolic codes of which correspond to the sequence of period adding. And from all cycles of the corresponding period $N$ and less, the cycles with such symbolic codes will appear before the others. Thus, in the general case, when parameters are varied following along a certain path, a non-trivial chaotic set will arise through the sequence of occurrence of cycles, the symbolic codes of which correspond to the sequence of period adding.

Figure 5: The lines are the borders of the domains where at least one cycle exists of a given period. Encodings of the cycles which are born at the borders are shown. The domain $\mathbf{D}$ is highlighted in gray.

Figure 6 shows the set $\mathbf{D}$ whose boundary was constructed this time as the upper bound of the set of lines of
occurrence of cycles with symbolic sequences of the form $B\{\}^n$, where $n$ denotes the $n$-fold repetition of the symbol $A$, and the symbols $A$ and $B$ themselves denote all possible sequences characters $R$ and $L$ of finite length $m \leq 6$.

For some sections of the boundary, symbolic codes of the non-periodic trajectories arising on it are indicated.

In order to clarify the quantitative laws of accumulation of the lines of occurrence of cycles to the boundary of the set $D$, we consider a simple renormalization scheme presented in Fig. 7. The “inflation” rule [21] in the case of a sequence of period adding can be written in the form

\[
\begin{align*}
A & \quad \Rightarrow \quad A \\
B & \quad \Rightarrow \quad BA
\end{align*}
\]  

(5)

The symbols $A$ and $B$ correspond to segments of graphs of linear functions

\[
\begin{align*}
A(x) & = \frac{x}{K_L} - 1 \\
B(x) & = \frac{x}{K_R} + 1
\end{align*}
\]  

(6)

The origin corresponds to a cycle with a symbolic sequence $\{A\}$. The intersection point of the graph of the composite function $BA$ with the diagonal, $x_0 = \frac{K_L(1-K_R)}{K_R}$, corresponds to the cycle point with the corresponding symbolic code $BA$. Obviously, if we iterate the map $n$ times, we get as a result a point belonging to the orbit with the desired symbolic code $B\{\}^n$.

After rescaling the phase variable in $\alpha = 1/x_0$, we obtain for new functions $A'$ and $B'$

\[
\begin{align*}
A'(x) & = \frac{x}{K_L'} - 1 \\
B'(x) & = \frac{x}{K_R'} + 1
\end{align*}
\]  

(7)

where

\[
\frac{K_L'}{K_R'} = K_LK_R
\]  

(8)

For expanding maps of Bernoulli type $K_L, K_R < 1$, therefore, in the limit of a large number of iterations $K_R \to 0$, and the scale factor is $\alpha \to \frac{1}{K_L}$. It follows that the distance from the nearest element of the cycle $B\{\}^n$ to the cycle $A$ is subject to geometric scaling with the scale factor $\alpha = 1/K_L$. Hence, actually it is determined by the slope of that branch of the map to which the cycle of the adding period belongs.
It should be noted that this is simply a property of Bernoulli-type mappings, since we have not yet introduced the presence of a forbidden zone. Let us now consider the dynamics of a hole.

It can be seen from Fig. 7 that the new positions of the edges of the hole are determined from the relation $A(H_1',H_2') = H_1,H_2$. After the renormalization, we obtain

$$H_1',H_2' = H_1,H_2 \frac{(1-K_R)}{(1-K_R K_L)},$$

(9)

The parameters $a$ and $b$ are expressed in terms of $H_1,H_2$ as

$$a = \frac{H_1 + H_2}{2}, \quad b = H_2 - H_1,$$

(10)

then for them the following relations are also valid

$$a' = a \frac{(1-K_R)}{(1-K_R K_L)}, \quad b' = b \frac{(1-K_R)}{(1-K_R K_L)},$$

(11)

The factor $\frac{(1-K_R)}{(1-K_R K_L)}$ in the limit tends to 1, so the scaling factor for parameters $a$ and $b$ is the same as for the other objects in the phase space, $\delta = \alpha = 1/K_L$.

As an example, consider emergence of a chaotic set as we reduce the hole width $b$, while the position of its center (the value of parameter $b$) does not change. We take two values of the parameter $a$: $a_1 = 0.3$ and $a_2 = 0.075$, the first belongs to the longest rectilinear portion of the boundary $\Gamma$ corresponding to the addition of period 1, and the second to the section where the addition of period 2 is observed. In both cases, all values of the parameter $a$ were calculated, which correspond to the birth of cycles with periods corresponding to all possible symbolic codes of length $\leq 20$.

In the first case, at $a = 0.3$, it was found that of all cycles with periods equal to or less than $N$, the first cycle to born is that with a symbolic code of the form $LR^{N-1}$. Table 1 lists the values of the parameter $a$, for which the cycles with such codes appear, as well as the elements of these cycles closest to the cycle of period 1 with the code $\{R\}$. In Figure 5 one can see how the lines of occurrence of cycles with codes of the form $LR^{N-1}$ accumulate to the boundary $\Gamma$ of the domain $D$. The scale factors $\delta$ and $\alpha$ are set by the slope of the $R$ branch of the map and are equal to 2.

In the second case, at $a = 0.075$, it was found that out of all cycles with periods less than $2N+2$, the first appears a cycle, with a symbolic code of the form $R\{RL\}^N$. Table 2 shows the values of the parameter $b$, for which the cycles with such codes appear, as well as the elements of these cycles closest to the element of the cycle of period 2 with the code $\{RL\}$. The scaling factors $\delta$ and $\alpha$ in this case are given by the slope of the $RL$ branch of the doubly iterated map and are equal to 4.
4 Two-dimensional noninvertible mapping

In the case of two-dimensional model map \( \text{I} \), with the values of the parameters from Section 1, the numerical analysis shows that here the case of adding a cycle of period 1 is realized with the appearance on the boundary \( \Gamma \) of a non-periodic trajectory with the code \( \text{RL}^\infty \). In this case, from all cycles with periods equal to or less than \( N \), the first cycle with a symbolic code of the form \( \text{RL}^N \) occurs. Table 3 lists the corresponding bifurcation values of the parameter \( R_N \), as well as the \( x_N \) and \( y_N \) coordinates of the elements of these cycles at tangential bifurcation points closest in phase (which is defined as \( \varphi_N = \arg z_N/2\pi \)), to the cycle of period 1.

These components of the cycles accumulate in two-dimensional phase space to certain points, which in this case do not longer belong to the cycle of period 1. However, if we consider an approximate one-dimensional map for the phase, then it turns out that the point of accumulation of the phase components is the point corresponding to the phase of the cycle of period one. Table 3 gives numerical estimates for the corresponding scale factor \( \alpha \approx 1.806 \). A good approximation for the slope of the branch \( L \) at the accumulation point can be obtained from the values of the multipliers of the cycle of period one at the bifurcation point. The multiplier, which is equal to one, corresponds to the tangent bifurcation in the radial dynamics, while the value of the leading multiplier characterizes the phase component of the dynamics and gives a good estimate for the slope coefficient of the corresponding branch of the approximate one-dimensional mapping for the phase, and hence for the phase scale factor, \( \alpha = 1/K_L \approx 1.81 \).

The sequence of bifurcation points of the corresponding cycles with respect to the parameter \( R \) demonstrates geometric convergence. The numerical estimate for the scaling factor in the parameter space is \( \delta \approx 1.14 \), which differs from that predicted by the model \( \delta = 1/K_L \approx 1.81 \). The reason for this is obviously that the assumption made in the derivation of the model mapping that the cycle disappears if at least one of the elements of its orbit falls into a hole, is too strong. In fact, of course, the cycle disappears only after a sufficiently large number of its elements are in the forbidden zone, which leads to a protraction of the cascade.

Table 1: The sequence of bifurcation points of cycles with the codes \( \text{LR}^N \) of the map \( \text{II} \) at \( a=0.3 \).

| N | Code | \( b_N \) | \( x_N \) | \( (b_{N-1}-b_{N-1})/(x_{N-1}-x_{N}) \) | \( (x_0-x_{N-1})/(x_0-x_{N}) \) |
|---|------|---------|---------|------------------|------------------|
| 1 | LR   | 0.066666667 | 0.66666667 | 2.3333333 | 2.3333333 |
| 2 | LRR  | 0.25714286  | 0.85714286 | 2.1428571 | 2.1428571 |
| 3 | LRRR | 0.33333333  | 0.93333333 | 2.0322581 | 2.0322581 |
| 4 | LRRRR| 0.36774194  | 0.96774194 | 2.0122581 | 2.0122581 |
| 5 | LRRRRR| 0.38412698 | 0.98412698 | 2.0000001 | 2.0000001 |
| 6 | LRRRRRR| 0.39212598 | 0.99212598 | 2.0000001 | 2.0000001 |
| 7 | LRRRRRRR| 0.39607843 | 0.99607843 | 2.0000001 | 2.0000001 |
| 8 | LRRRRRRRR| 0.39804305 | 0.99804305 | 2.0000001 | 2.0000001 |
| 9 | LRRRRRRRRR| 0.39902248 | 0.99902248 | 2.0000001 | 2.0000001 |
| 10| LRRRRRRRRRR| 0.39951148 | 0.99951148 | 2.0000001 | 2.0000001 |
| ...| ... | ... | ... | ... | ... |
| \( \infty \) | LR\( \infty \) | 0.4 | 1.0 | 2.0 | 2.0 |

Table 2: The sequence of bifurcation points of cycles with codes \( \text{RL}^N \) of the map \( \text{II} \) at \( a=0.075 \).

| N | Code | \( b_N \) | \( x_N \) | \( (b_{N-2}-b_{N-1})/(x_{N-1}-x_{N}) \) | \( (x_0-x_{N-1})/(x_0-x_{N}) \) |
|---|------|---------|---------|------------------|------------------|
| 1 | RRL  | 0.43571428 | 0.85714286 | 4.3571428 | 4.3571428 |
| 2 | RRLRL | 0.47258065 | 0.70967742 | 4.5357143 | 4.5357143 |
| 3 | RRLRLRL | 0.48070866 | 0.67716535 | 4.5357143 | 4.5357143 |
| 4 | RRLRLRLRL | 0.48268102 | 0.66927593 | 4.1209703 | 4.1209703 |
| 5 | RRLRLRLRLRL | 0.48317049 | 0.66731803 | 4.0295260 | 4.0295260 |
| 6 | R\{RL\}^6 | 0.48329264 | 0.66682945 | 4.0073383 | 4.0073383 |
| 7 | R\{RL\}^7 | 0.48332316 | 0.66670736 | 4.0016906 | 4.0016906 |
| 8 | R\{RL\}^8 | 0.48333079 | 0.66669218 | 4.0000000 | 4.0000000 |
| 9 | R\{RL\}^9 | 0.48333270 | 0.66666918 | 4.0000000 | 4.0000000 |
| 10| R\{RL\}^{10} | 0.48333317 | 0.66666666 | 4.0 | 4.0 |
| ...| ... | ... | ... | ... | ... |
| \( \infty \) | R\{RL\}^\infty | 0.483333333 | 0.66666666 | 4.0 | 4.0 |
Table 3: The sequence of bifurcation points of cycles with codes RL$^N$ of the map (1) at $\varepsilon=0.2$.

| N | Code | Re $z_n$ | Im $z_n$ | $\alpha_N$ | $\delta_N$ |
|---|------|----------|----------|------------|------------|
| L |  | 1.2765086 | 0.8540116 | 0.0 |  |
| 1 | RL | 1.4824173 | -0.5879534 | 2.4067062 | 2.1024585 |
| 2 | RRL | 1.4429370 | 0.5069519 | 3.6591647 | 1.8377422 |
| 3 | RLLL | 1.4061755 | 0.7830113 | 4.5912542 | 2.3402559 |
| 4 | RL$^4$ | 1.3819309 | 0.8269949 | 2.4067062 | 2.1024585 |
| 5 | RL$^5$ | 1.3657408 | 0.8203300 | 1.2707420 | 1.9081841 |
| 6 | RL$^6$ | 1.3544064 | 0.8051506 | 6.7879207 | 1.8377422 |
| 7 | RL$^7$ | 1.3461006 | 0.7907497 | 3.6591647 | 1.8377422 |
| 8 | RL$^8$ | 1.3397788 | 0.7787071 | 1.9852908 | 1.8377422 |
| 9 | RL$^9$ | 1.3348195 | 0.7688770 | 1.0819726 | 1.8377422 |
| 10 | RL$^{10}$ | 1.3308354 | 0.7608308 | 5.9155441 | 1.8377422 |
| 11 | RL$^{11}$ | 1.3275739 | 0.7541788 | 3.2418203 | 1.8377422 |
| 12 | RL$^{12}$ | 1.3248635 | 0.7486189 | 1.7797216 | 1.8377422 |
| 13 | RL$^{13}$ | 1.3228383 | 0.7439251 | 9.7839089 | 1.8377422 |
| 14 | RL$^{14}$ | 1.3206743 | 0.7399280 | 5.3846671 | 1.8377422 |
| 15 | RL$^{15}$ | 1.3189892 | 0.7364994 | 2.9661763 | 1.8377422 |
| 16 | RL$^{16}$ | 1.3175610 | 0.7335402 | 1.6351765 | 1.8377422 |
| 17 | RL$^{17}$ | 1.3163215 | 0.7309729 | 9.0201188 | 1.8377422 |
| 18 | RL$^{18}$ | 1.3152432 | 0.7287362 | 4.9785269 | 1.8377422 |
| 19 | RL$^{19}$ | 1.3143010 | 0.7267806 | 2.7491549 | 1.8377422 |
| 20 | RL$^{20}$ | 1.3134753 | 0.7250658 | 1.5187344 | 1.8377422 |

5 Saddle-node scenario in the 4D invertible model map

As a second example of a system demonstrating the scenario of interest, we consider a reversible four-dimensional system with discrete time, which was introduced in [4]. Such a model is constructed on the basis of a map with a complex variable (1) in strict analogy to the construction of the Henon map:

$$z_{n+1} = \frac{Rz_n(z_n + \varepsilon)}{\sqrt{1 + |z_n(z_n + \varepsilon)|^2}} - bz_{n-1},$$

(12)

The attractor is now located in the four-dimensional space and is a full-fledged Smale–Williams solenoid. We consider the dynamics of this mapping for the values of the parameter $\varepsilon = 0, b = 0.3$. The saddle-node scenario of disappearance of the chaotic attractor is still observed with decreasing the parameter $R$.

Numerical analysis shows that here the case of cycle of period 2 adding is realized with the appearance on the boundary of a nonperiodic trajectory with the code RL$\{RL\}$.$^\infty$. Of all cycles with periods less than 2N+2, the first cycle appears, with symbolic code of the form RL$\{RL\}$.$^N$. Table 4 shows the bifurcation values of the parameter $R_N$ and the phase $\phi_N$ of the closest (in phase) cycle components to one of the elements of the cycle of period 2.

An estimate of the average rate of convergence in phase can be obtained from the largest multiplier of the cycle of period 2 at the point of its disappearance $\alpha=1/K_L \approx 2.5$. The numerical value of the scale factor over the parameter $K$ is again significantly lower than the value assumed by the model.

Table 4: The sequence of bifurcation points of cycles with codes RRL$^N$ of the map (12) at $\varepsilon=0, b = 0.3$.

| N | code | $\phi_N$ | $R_N$ | $\alpha_N$ | $\delta_N$ |
|---|------|----------|-------|------------|------------|
| 2 | RL | 0.3333333 | 0.9899494 | 2.8918343 | 2.2027843 |
| 3 | RRL | 0.4635776 | 1.5162512 | 1.9081841 | 1.8377422 |
| 5 | RRLRL | 0.3789271 | 1.3678263 | 1.8377422 | 1.8377422 |
| 7 | RRLRLRL | 0.3497154 | 1.3004457 | 2.8918343 | 2.2027843 |
| 9 | RRLRLRLRL | 0.3384539 | 1.2657087 | 2.5979340 | 1.9081841 |
| 11 | RRLRLRLRLRL | 0.3339073 | 1.2461442 | 2.4769408 | 1.8377422 |
| 13 | R(RL)$^6$ | 0.3319775 | 1.2345261 | 2.3559391 | 1.8062930 | 1.4045353 |
6 The model of two coupled Van der Pol oscillators

It was shown in [3] that the considered scenario is realized in the system of two coupled van der Pol oscillators [5]

\[
\begin{align*}
\dot{x} &= \omega_0 u, \\
\dot{u} &= (h + a \cos 2\pi t/T - x^2)u - \omega_0 x + (\varepsilon y/\omega_0) \cos \omega_0 t, \\
\dot{y} &= 2\omega_0 v, \\
\dot{v} &= (h - a \cos 2\pi t/T - y^2)v - 2\omega_0 y + (\varepsilon/2\omega_0)x^2,
\end{align*}
\]

(13)

The hyperbolicity of the attracting set at the values of the parameters \(h=0, \omega_0=2\pi, T=6, A=5, \varepsilon=0.5\) was tested numerically using the cone criterion [6,7], and it was verified using the computer-assisted proof framework [8]. On the parameter plane \((h, A)\), for negative \(h\), the region of existence of the hyperbolic chaotic attractor is bounded by the line on which this attractor arises as a result of the saddle-node scenario.

In [3], the creation of a chaotic attractor with variation of the parameter \(h\) for a constant \(A = 6.5\) was considered. Along this path, the cycle of period 3 with code LLR appears first. The code of the cycle was determined from the variable change in the original equation (13), made in order that in the new coordinates the attractor was close to the circle, and \(\dot{\phi} = nT\), where \(\phi = \arg[x_0(t_n) + ix_1(t_n)]/2\pi\), with \(\{x_0, x_1\} = \{x, u/0.9 - x/2\}\) is the variable change in the original equation (13), made in order that in the new coordinates the attractor was close to the circle, and \(t_n = nT\), which corresponds to the mapping in the stroboscopic section. As the parameter \(h\) is increased, cycles with a period less than or equal 10 start with cycles LRLLR and LRLLRLRLR, indicating that there is a sequence of addition of period 3. However, finding out the bifurcation points of cycles of a larger period is more difficult because of the fact that they quickly become strongly unstable.

If one moves up the parameter \(A\), then at \(A = 7.1\), the cycle of period 2 is the first to appear with increase of the parameter \(h\), which allows us to hope that there will be a scenario of adding this period. Indeed, numerical analysis shows that of all cycles with periods less than 2\(N\)+2, the first cycle appears with a symbolic code of the form \(L\{LR\}^N\). Table 5 shows values of the parameter \(h_N\), for which cycles with such codes arise as a result of the tangent bifurcation, as well as phase values \(\varphi_N\) for the elements of these cycles are closest to one of the elements of the cycle of period 2. The estimate for the scaling factor determining the accumulation rate for the phases \(\varphi_N\) can be obtained from the value of the largest multiplier of the cycle of period 2 at the moment of disappearance as a result of tangent bifurcation, \(1/K_L \approx \mu_n=3.99\).

Table 5: The sequence of bifurcation points of cycles with codes \(L\{LR\}^N\) of the system (13) at \(A = 7.1\).

| \(N\) | code | \(h_N\) | \(\varphi_N\) | \(\alpha_N = \frac{\varphi_{N-2} - \varphi_{N-1}}{\varphi_{N-1} - \varphi_N}\) | \(\delta_N = \frac{\varphi_{N-2} - \varphi_{N-1}}{\alpha_N} - \varphi_N\) |
|------|------|--------|-------|------------------|------------------|
| 1    | LR   | -1.5784956 | 0.30920170 |
| 1    | LRLR | -1.5782312 | 0.30643015 |
| 2    | LRLRLR | -1.5784217 | 0.29818979 |
| 3    | LRLRLRLR | -1.5784563 | 0.3043015 |
| 4    | LRLRLRLRLR | -1.5784680 | 0.30840628 |

On the other hand, if we consider the boundary of the region of existence of a chaotic attractor for small negative constant \(h\) and vary the parameter \(A\), then at least for cycles of a not very long period, the addition of period 1 may be observed, see Table 6. However, we should pay attention to that circumstance that the cycle of period one arises here only after the cycle of period 9 have already appeared, that is, it does not exist at a possible point of accumulation of bifurcation points. Moreover, the cycle of period one, in contrast to all other cycles, becomes stable at the bifurcation point.

Table 6: The sequence of bifurcation points of cycles with codes \(RL^N\) of the system (13) at \(h = -0.05\).

| \(N\) | code | \(A_N\) | \(\varphi_N\) | \(\alpha_N = \frac{\varphi_{N-2} - \varphi_{N-1}}{\varphi_{N-1} - \varphi_N}\) | \(\delta_N = \frac{\varphi_{N-2} - \varphi_{N-1}}{\alpha_N} - \varphi_N\) |
|------|------|--------|-------|------------------|------------------|
| 1    | R    | 3.9307609 | 0.0    | 1.1910364        | 1.5069537        |
| 2    | RL   | 4.6171255 | 0.73543964 |
| 3    | RLL  | 4.3823556 | 0.4995719 |
| 3    | RLLL | 4.2265313 | 0.30150912 |
| 4    | RL\(^4\) | 4.1254594 | 0.22563264 |
| 5    | RL\(^5\) | 4.0516771 | 0.26073326 |
| 6    | RL\(^6\) | 3.9909290 | 0.29818979 |
| 7    | RL\(^7\) | 3.9379366 | 0.3043015 |
| 8    | RL\(^8\) | 3.8929254 | 0.30840628 |
| 9    | RL\(^9\) | 3.8616612 | 0.30920170 |

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An estimate of the phase scale factor is of the order of 1 (see Table 6), and if we take into account that its value is directly related to the corresponding slope of the branch of the map for the phase, then obviously it is no longer a Bernoulli type map. This is clearly seen in Fig. 8b, which shows a map for the phase on the cycle of period 10 at the point of the tangent bifurcation from the Table 6. This looks more like a phase map for a resonant cycle on a torus. For comparison, Fig. 8a shows a graph of the mapping for the phase on the cycle of period 9 from Table 5. Here you can see how the elements of the cycle of period 9 accumulate to the elements of the cycle of period 2, which are indicated by triangles.

Figure 8: The phase map for the cycles of the system (13) at the saddle-node bifurcation points: a) a cycle of period 9 with the code L{RL}⁴ at the point $A_1=7.1$, $h=-1.5784680$; b) a cycle of period 10 with the code RL⁹ at the point $A_1=3.8616612$, $h=-0.05$.

Obviously, for small $h$, the model of a one-dimensional mapping with a hole loses its applicability here, which is connected with the fact that at the moment of destruction of the chaotic attractor the phase dynamics is no longer described by the Bernoulli map. This is due to the fact that a stable cycle, which for $h>0$ coexists with a chaotic attractor, loses stability at $h=0$ via the Neimark-Sacker bifurcation and a stable torus is produced instead. In this case, the scenario of birth/destroiy of the hyperbolic chaotic attractor also changes. For $h<0$, it arises when a quasiperiodic behavior is destroyed, and this transition is already not catastrophic, but gradual (see [9]). But this is a completely different story and will be discussed elsewhere.

7 Conclusions

To describe the regularities of the chaotic set appearance under the saddle-node scenario of the birth of the Smale–Williams hyperbolic attractor, it is suggested using the one-dimensional Bernoulli mapping with the “forbidden zone”. In such mapping, a non-trivial chaotic set (with non-zero Hausdorff dimension) arises in the general case as a result of cascade of period-adding bifurcations characterized by geometric scaling both in the phase space and in the parameter space.

Numerical analysis of behavior of models demonstrating the saddle-node scenario of the birth of chaotic attractor shows that these regularities are preserved qualitatively as we pass from 1D model to multidimensional systems. Numerical scale exponents characterizing the average rate of accumulation of critical cycle elements to characteristic points in the phase space also correspond to those determined by the model. It should be noted that these regularities are reproduced only as long as the phase component of the dynamics continues to be described by a Bernoulli type map at the time of the disappearance of the chaotic attractor.

The scale factor in the parameter space in all the examples considered was significantly smaller than the values predicted by the one-dimensional model. Apparently, this is a consequence of the assumptions made in the derivation of the approximate mapping. Nevertheless, the nature of the convergence of the points of bifurcations of cycles remains geometric.
Acknowledgements

The work was supported by the grant of the Russian Scientific Foundation No 17-12-01008. Authors acknowledge Prof. S.P. Kuznetsov and Prof. A. Pikovsky for useful discussion.

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