Nmbr9 as a Constraint Programming Challenge

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1 Introduction

Modern board games are a rich source of interesting and new challenges for combinatorial problems. The game Nmbr9 is a solitaire style puzzle game using polyominoes. The rules of the game are simple to explain, but modelling the game effectively using constraint programming is hard.

This abstract presents the game, contributes new generalized variants of the game suitable for benchmarking and testing, and describes a model for the presented variants. The question of the top possible score in the standard game is an open challenge.

2 Nmbr9

Nmbr9 (Wichmannm 2017) is a solitaire puzzle game using polyominoes that can be played by multiple people at the same time. The goal of the game is to build layers of the polyominoes in Figure 1 according to a pre-defined but unknown shuffle, and to place polyominoes representing larger numbers higher up to score points.

Rules

The game consists of polyominoes representing the numbers 0 to 9, two copies per number for each player. A common deck of 20 cards with the polyominoes are shuffled.

When a card is drawn, each player takes the corresponding part and places it in their own area. Placements are done in levels, where the first level (level 1) is directly on the table, and level n is on top of level n − 1.

Placement must always be done fully supported (level 1 is always fully supported, level n is supported by previously placed parts in level n − 1). Each level must be fully 4-connected (i.e., not diagonally) after placement. The final requirement on placements is that when placing a part on top of other parts, it must be on top of at least two different parts. For example, if a 9-part is in level n, then an 8-part can not be placed in level n + 1 resting solely on the 9-part.

When all cards have been drawn, the score is computed as the the sum of the value for parts times their level minus one. For example, an 8-part on level 3 is worth 16, while it is worth 0 on level 1.

Variants

We define variants of Nmbr9 to get a larger sampling of problems to solve, from small trivial problems to larger intractable problems. Let \( T − m − c − n \) be the scheme, where \( T \in U, F, K \). Whether the draft is unknown, free to choose, or known. The first corresponds to a quantified problem, where the draft is \( \forall \)-quantified. The second models the question of the max possible score, while the last models the max possible score given a specific known shuffle.

\( m \) The maximum value to use, from 0-9.

\( c \) The number of available copies of each polyomino.

\( k \) The number of cards in the deck to use, \( k \leq m \cdot c \) must hold.

With this taxonomy of variants, the standard game is \( U−9−2−20 \), where all available parts are used. Reducing \( m, c, or k \) are all effective ways to make the model smaller. \( F \) variants are interesting for answering the question of the top-score possible. \( K \) variants are interesting computationally because they represent a much simpler but still hard problem, and are also interesting recreationally given a finished game, where participants wonder how they compare to the best possible result for that particular shuffle.

At Board Game Geek, a forum thread on solving the standard \( F−9−2−20 \) instance has a top score of 229 points, using a total of 7 layers (Kuenzler 2018).

3 Constraint programming model

In this section, a constraint programming model is described for Nmbr9 in the \( F \) and \( K \) variants; a quantified model for the \( U \) variant could be built as an extension on top of this. The model is based on the models in Lagerkvist and Pesant 2008 Lagerkvist 2019, where regular constraints are used for placement of polyominoes in grids.

![Figure 1: Parts to place representing the numbers 0-9.](image-url)
Nmbr9 is played on a conceptually infinite grid, with as many layers as needed available. The model used here requires a fixed grid. In practice, placements very seldom surpass 20 squares wide, and more than 7 layers is unlikely. The width/height size s and the number of layers $l_T$ are parameters for the model. A core problem is keeping levels connected. This is accomplished using the technique of defining an area around parts, here as a new value. Also, parts may not be placed, which is controlled using reification of the regular expression. As an example, the regular expression for part 0 (called $R_0$) in its two rotations, where the value 0 is an empty square. 1 is a square occupied by the part, and 2 is an area surrounding the part becomes (including initial control variable for reified placement)

$$10^7 (2^{19}0^{-5}213^{20}0^{-5})(2101200^{-5})213^{20}0^{-4}23 \mid 24^{0^{-5}}214^{20}0^{-6}2102^{1200^{-6}}24^{20}0^{-5}24)0^* \mid 00^*$$

Let $P = \{p_1, \ldots, p_n\}$ be the set of parts, and $v(p) \in P \to 0..m$ the value of each part. Variables $D = (d_1, \ldots, d_k) \in P$ represent the deck of polyominoes, and $O = (o_1, \ldots, o_n) \in \{1..n\}$ the order of the polyominoes as they occur in the deck, with values above $k$ representing not used. The matrix $G_l$ is the grid for level $l$ for all parts on that level (of size $s \times s$, domain 0..$n$, border is 0), and $G_{lp}$ the grid for a part $p$ on level $l$ (of similar size, domain 0..2). Variables $G_{lp}$ and $G_{lp}^\ell$ are Boolean matrices representing when $G_{lp}$ is 1 and 2 respectively. Boolean variables $L_{lp}$ represent $p$ being placed on level $l$, integer variable $L_{lp} \in 0..l_T$ the level of $p$ (if any, 0 if not), and $Y_p$ a Boolean variable representing that $p$ is placed with $N_p$ the inverse. The following defines the constraints of the model, where $p, p'$ is implicitly assumed to range over $P$ with $p \neq p'$, $l \in 1..l_T$, $l' \in 2..l_T$, and $i, j \in 1..s$. Operators $\lor$ and $\land$ are used for point-wise logical operations. The notation $|M|$ is used to indicate true iff any element in the matrix $M$ is true.

$$\text{global_cardinality}(D, \{Y_1, \ldots, Y_n\}) \quad (1)$$
$$\text{regular}(R_p, L_{lp}G_{lp}) \quad (2)$$
$$\text{inverse}(O, \{D_1, \ldots, D_k, E_{k+1}, \ldots, E_{n}\}), E \in P \quad (3)$$
$$B(p, p') \leftrightarrow (O(p) < O(p'), O(p) \leq k \leftrightarrow Y_p) \quad (4)$$
$$\text{int_to_bool}(L_{lp}, \{N_p, L_{lp}, \ldots, L_{lp}^\ell\}), \quad (5)$$
$$Y_p = 1 - N_p, \quad (6)$$
$$G_{lp}(i, j) = 1 \leftrightarrow G_{lp}^\ell(i, j), G_{lp}(i, j) = 2 \leftrightarrow G_{lp}^\ell(i, j) \quad (7)$$
$$G_l(i, j) = p \leftrightarrow G_{lp}(i, j) = 1 \quad (8)$$
$$(L_{lp} \land \exists p'[B(p', p) \iff \rightarrow G_{lp}^\ell \land \forall p'[B(p', p)G_{lp}^\ell]) \quad (9)$$
$$G_{lp}^\ell(i, j) \rightarrow \forall p'[B(p', p)G_{lp}^\ell(i, j)] \quad (10)$$
$$L_{lp' \lor} \rightarrow \left(2 \leq \sum_{p'[B(p', p)G_{lp}^\ell(i, j)} \right) \quad (11)$$
$$S = \sum_{p \in P}(L_p - Y_p) \cdot v(p) \quad (12)$$

Constraint [1] checks that the deck is a shuffle of parts. Constraint [2] is the core placement constraints, with $l_T \cdot n$ regular constraints in total. Constraints [3] to [8] channel information between variables. Constraints [9] to [11] implement the requirements for connectedness and being placed supported and on top of at least two different parts. When $k = n$, then constraint [1] is equivalent to an all different, and in constraint [3] there are no extra E variables representing fake deck placement for non-used parts.

Finally, constraint [12] sums up the score of the solution, where $L_{p} - Y_{p}$ is 0 for non-used parts ($L_{p} = 0$ and $Y_{p} = 0$), and also for parts in the first layer ($L_{p} = 1$ and $Y_{p} = 1$).

### 4 Implementation

The described model has been implemented using Gecode (Gecode team 2019) version 6.2.0 and C++17, and can be accessed at github.com/zayenz/cp-2019-nmbr9.

Choices are made on the deck, then the levels of parts, then the placements. A static variable order is used spiralling out from the centre to keep placement centered in the grid for as long as possible. Extra implied constraints that the first card is on the first level, and that the area for each level is at most the area for the level above are added. The latter improves performance significantly.

It is intractable to find a max score for the standard game approaching the score found manually using this model and search strategy; the model has more than 2.5 million propagators, and setting up the root node takes 5 seconds. A small problem like $F-6-1-5$ with 3 levels and grid size 8 takes more than 30 seconds and 80k failures to solve.

### 5 Conclusions

As seen, modelling Nmbr9 is surprisingly complex, mainly due to the connectedness and support requirements. This leads to a large model with not much propagation. Finding the maximum score for the standard game is a computationally hard open challenge.

Future work include: exploring how large problems can be solved with the current model; investigating better models for stronger propagation; and finding effective heuristics for the search. For search heuristics, the propagation guided global regret in (Lagerkvist 2019) might be very interesting.

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### References

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