Boundedness of Massless Scalar Waves on Reissner-Nordström Interior Backgrounds

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Abstract: We consider solutions of the scalar wave equation $\Box_g \phi = 0$, without symmetry, on fixed subextremal Reissner-Nordström backgrounds $(\mathcal{M}, g)$ with nonvanishing charge. Previously, it has been shown that for $\phi$ arising from sufficiently regular data on a two ended Cauchy hypersurface, the solution and its derivatives decay suitably fast on the event horizon $\mathcal{H}^+$. Using this, we show here that $\phi$ is in fact uniformly bounded, $|\phi| \leq C$, in the black hole interior up to and including the bifurcate Cauchy horizon $C\mathcal{H}^+$, to which $\phi$ in fact extends continuously. The proof depends on novel weighted energy estimates in the black hole interior which, in combination with commutation by angular momentum operators and application of Sobolev embedding, yield uniform pointwise estimates. In a forthcoming companion paper we will extend the result to subextremal Kerr backgrounds with nonvanishing rotation.

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1. Introduction

The Reissner-Nordström spacetime $(\mathcal{M}, g)$ is a fundamental 2-parameter family of solutions to the Einstein field equations coupled to electromagnetism, cf. Fig. 1 for the conformal representation of the subextremal case, $M > |e| \neq 0$, with $e$ the charge and $M$ the mass of the black hole. The problem of analysing the scalar wave equation

$$\Box_g \phi = 0$$

(1)

on a Reissner-Nordström background is intimately related to the stability properties of the spacetime itself and to the celebrated Strong Cosmic Censorship Conjecture. The analysis of (1) in the exterior region $J^- (I^+)$ has been accomplished already, cf. [6] and [21] for an overview and references therein for more details, as well as Sect. 3.1. The purpose of the present work is to extend the investigation to the interior of the black hole, up to and including the Cauchy horizon $\mathcal{CH}^+$.

1.1. Main result. The main result of this paper can be stated as follows.

**Theorem 1.1.** On subextremal Reissner-Nordström spacetime $(\mathcal{M}, g)$, with mass $M$ and charge $e$ and $M > |e| \neq 0$, let $\phi$ be a solution of the wave equation $\Box_g \phi = 0$
arising from smooth compactly supported Cauchy data on a two-ended asymptotically flat Cauchy surface $\Sigma$. Then

$$|\phi| \leq C$$

(2)

globally in the black hole interior, in particular up to and including the Cauchy horizon $\mathcal{CH}^+$, to which $\phi$ extends in fact continuously.

The constant $C$ is explicitly computable in terms of parameters $e$ and $M$ and a suitable norm on initial data.\(^1\) The above theorem will follow, after commuting (1) with angular momentum operators and applying Sobolev embedding, from the following theorem, expressing weighted energy boundedness.

**Theorem 1.2.** On subextremal Reissner-Nordström spacetime $(\mathcal{M}, g)$, with mass $M$ and charge $e$ and $M > |e| \neq 0$, let $\phi$ be a solution of the wave equation $\Box_g \phi = 0$ arising from smooth compactly supported Cauchy data on a two-ended asymptotically flat Cauchy surface $\Sigma$. Then

$$\int \int_{S^2} v_{\text{fix}} \left[ v^p (\partial_v \phi)^2(u, v, \theta, \varphi) + \Omega^2 |\nabla \phi|^2(u, v, \theta, \varphi) \right] r^2 dv d\sigma_{S^2} \leq E, \quad \text{for } v_{\text{fix}} \geq 1, u > -\infty$$

(3)

$$\int \int_{S^2} u_{\text{fix}} \left[ u^p (\partial_u \phi)^2(u, v, \theta, \varphi) + \Omega^2 |\nabla \phi|^2(u, v, \theta, \varphi) \right] r^2 du d\sigma_{S^2} \leq E, \quad \text{for } u_{\text{fix}} \geq 1, v > -\infty,$$

(4)

where $p > 1$ is an appropriately chosen constant, and $(u, v)$ denote Eddington-Finkelstein coordinates in the black hole interior, where by $d\sigma_{S^2}$ we denote the volume element of the unit two-sphere and $|\nabla \phi|^2 = \frac{1}{r^2} \left[ (\partial_\theta \phi)^2 + \frac{1}{\sin^2 \theta} (\partial_\varphi \phi)^2 \right]$.

\(^1\) The Theorem holds more generally for data in the weighted Sobolev space defined in this norm. We shall not explicitly give the optimal norm here, but it can be deduced from the proof of Theorem 3.1.
1.2. **Motivation and strong cosmic censorship.** Our motivation for proving Theorem 1.1 is the Strong Cosmic Censorship Conjecture. The mathematical formulation of this conjecture, here applied to electrovacuum, is given in [8] by Christodoulou as

\[ \text{“Generic asymptotically flat initial data for Einstein-Maxwell spacetimes have a maximal future development which is inextendible as a suitably regular Lorentzian manifold.”} \]  

(5)

Reissner-Nordström spacetime serves as a counterexample to the inextendibility statement, since it is (in fact smoothly) extendable beyond the Cauchy horizon \( C\mathcal{H}^+ \). Thus, for the above conjecture to be true, this property of Reissner-Nordström must in particular be unstable.

Originally it was suggested by Penrose and Simpson that small perturbations of Reissner-Nordström would lead to a spacetime whose boundary would be a spacelike singularity as in Schwarzschild and such that the spacetime would be inextendable as a \( C^0 \) metric, cf. [43]. On the other hand, a heuristic study of a spherically symmetric but fully nonlinear toy model by Israel and Poisson cf. [39], led to an alternative scenario, which suggested that spacetimes resulting from small perturbations would exist up to a Cauchy horizon, which however would be singular in a weaker sense, see also [37] by Ori. Considering the *spherically symmetric* Einstein-Maxwell-scalar field equations as a toy model, Dafermos proved that the solution indeed exists up to a Cauchy horizon and moreover is extendible as a \( C^0 \) metric but generically fails to be extendible as a \( C^1 \) metric beyond \( C\mathcal{H}^+ \), cf. [12,13]. For more recent extensions see [9–11,27].

In this work, as a first attempt towards investigation of the stability of the Cauchy horizon under perturbations **without symmetry**, we employ (1) on a fixed Reissner-Nordström background \((M, g)\) as a toy model for the full nonlinear Einstein field equations, cf. (10). The result of uniform pointwise boundedness of \( \phi \) and continuous extension to \( C\mathcal{H}^+ \) is concordant with the work of Dafermos [12]. This suggests that the non-spherically symmetric perturbations of the astrophysically more realistic Kerr spacetime may indeed exist up to \( C\mathcal{H}^+ \). See Sect. 5.4.

1.3. **A first look at the analysis.** The proof of Theorems 1.1 and 1.2 involves first considering a characteristic rectangle \( \Xi \) within the black hole interior, whose future right boundary coincides with the Cauchy horizon \( C\mathcal{H}^+ \) in the vicinity of \( i^+ \), cf. Fig. 2a).

Establishing boundedness of weighted energy norms in \( \Xi \) is the crux of the entire proof. Once that is done, analogous results hold for a characteristic rectangle \( \tilde{\Xi} \) to the left depicted in Fig. 2a). Hereafter, boundedness of the energy is easily propagated to regions \( \mathcal{R}_V, \tilde{\mathcal{R}}_V \) and \( \mathcal{R}_V I \) as depicted, giving Theorem 1.2. Commutation by angular momentum operators and application of Sobolev embedding then yields Theorem 1.1.

Let us return to the discussion of \( \Xi \) since that is the most involved part of the proof.

In order to prove Theorem 1.2 (and hence Theorem 1.1) restricted to \( \Xi \) we will begin with an upper decay bound for \( |\phi| \) and its derivatives on the event horizon \( \mathcal{H}^+ \), which can be deduced by putting together preceding work of Blue-Soffer cf. [6], Dafermos-Rodnianski cf. [15] and Schlue cf. [41]. The precise result from previous work that we shall need will be stated in Sect. 3.1.

---

2 Outside the future maximal domain of dependence \( D^+(M) \) in the future of the Cauchy horizon \( J^+(C\mathcal{H}^+) \) the spacetime shows the peculiar feature that uniqueness of the solutions of the initial value problem is lost **without loss of regularity**. It is precisely the undesirability of this feature that motivates the conjecture.
In the proof, the authors distinguish between redshift \( \mathcal{R} \), noshift \( \mathcal{N} \) and blueshift \( \mathcal{B} \) regions, as shown in Fig. 2b).

Some of these regions have appeared in previous analysis of the wave equation, especially \( \mathcal{R} = \{ r_{\text{red}} \leq r \leq r_+ \} \). Region \( \mathcal{N} = \{ r_{\text{blue}} \leq r \leq r_{\text{red}} \} \) and region \( \mathcal{B} = \{ r_- \leq r \leq r_{\text{blue}} \} \) were studied in \([13]\) in the spherically symmetric self-gravitating case, but using techniques which are very special to 1 + 1 dimensional hyperbolic equations.\(^3\) The analogous regions \( \mathcal{R} \) and \( \mathcal{N} \) were also considered by Luk \([30]\) on an interior Schwarzschild background. We will discuss this separation into \( \mathcal{R} \), \( \mathcal{N} \) and \( \mathcal{B} \) regions further in Sect. 3.2. One of the main analytic novelties of this paper is the introduction of a new vector field energy identity constructed for analyses in region \( \mathcal{B} \). In particular, the weighted vector field is given in Eddington-Finkelstein coordinates \((u, v)\) by

\[
S = |u|^p \partial_u + v^p \partial_v,
\]

for \( p > 1 \) as appearing in Theorem 1.2. This vector field associated to region \( \mathcal{B} \) will allow us to prove uniform boundedness despite the blueshift instability.

1.4. Outline of the paper. The paper is organized as follows.

In Sect. 2 we introduce the basic tools needed to derive energy estimates from the energy momentum tensor associated to (1) and an appropriate vector field. A review of the Reissner-Nordström solution and the coordinates used in this paper will be given. Moreover, we will discuss further features of Reissner-Nordström geometry.

In Sect. 3 we give a brief review of estimates obtained along \( \mathcal{H}^+ \) from previous work, \([6,15]\) and \([41]\), for \( \phi \) arising from sufficiently regular initial data on a Cauchy hypersurface. This is stated as Theorem 3.1. Further, we state our main result specialized to the rectangle \( \Xi \) in the neighbourhood of \( i^+ \) (see Theorem 3.3) and give an outline of its proof.

In Sect. 4 we prove boundedness of \( \phi \) up to and including \( \mathcal{H}^+ \). In particular, in Sect. 4.1 we first propagate the decay bound for the energy flux of \( \phi \) from \( \mathcal{H}^+ \) up to \( \mathcal{C} \mathcal{H}^+ \) in the neighbourhood of \( i^+ \). The investigation is divided into considerations within the redshift \( \mathcal{R} \), noshift \( \mathcal{N} \), and blueshift \( \mathcal{B} \) regions. Section 4.2 reveals how commutation with angular momentum operators and applying Sobolev embedding will return us pointwise boundedness for \( |\phi| \). We now must extend our result to the full interior

\(^3\) Let us note that the result of Theorem 1.1 for spherically symmetric solutions \( \phi \) can be obtained by specializing \([13–15]\) to the uncoupled case. Restricted results for fixed spherical harmonics can be in principle also inferred from \([33]\).
region. In Sect. 4.3 we propagate the energy estimates further along $\mathcal{CH}^+$ in the depicted region $\mathcal{R}_V$. Eventually, in subsection 4.4 we propagate the estimate to the region $\mathcal{R}_{VI}$ up to the bifurcation two-sphere, and thus obtain a bound for the energy flux globally in the black hole interior completing the proof of Theorem 1.2. In subsection 4.5 we prove boundedness of the weighted higher order energies. Using the conclusion of this theorem, we apply again Sobolev embedding as before and thus obtain the boundedness statement of Theorem 1.1.

An Outlook of open problems will be given in Sect. 5. We first state an analogous result to our Theorem 1.1 for general subextremal Kerr black holes (to appear as Theorem 1.1 of the follow up paper). The conjectured blow up of the transverse derivatives along the Cauchy horizon for generic solutions of (1) will also be discussed, as well as the peculiar extremal case. Finally, we will discuss what our results suggest about the nonlinear dynamics of the Einstein equations themselves.

2. Preliminaries

2.1. Energy currents and vector fields. The essential tool used throughout this work is the so called vector field method. Let $(\mathcal{M}, g)$ be a Lorentzian manifold. Let $\phi$ be a solution to the wave equation $\Box g \phi = 0$. A symmetric stress-energy tensor can be identified from variation of the massless scalar field action by

$$T_{\mu\nu}(\phi) = \partial_\mu \phi \partial_\nu \phi - \frac{1}{2} g_{\mu\nu} g^{\alpha\beta} \partial_\alpha \phi \partial_\beta \phi,$$

and this satisfies the energy-momentum conservation law

$$\nabla^\mu T_{\mu\nu} = 0. \quad (6)$$

By contracting the energy-momentum tensor with a vector field $V$, we define the current

$$J^V_\mu (\phi) = T_{\mu\nu}(\phi) V^\nu. \quad (7)$$

In this context we call $V$ a multiplier vector field. If the vector field $V$ is timelike, then the one-form $J^V_\mu$ can be interpreted as the energy-momentum density. When we integrate $J^V_\mu$ contracted with the normal vector field over an associated hypersurface we will often refer to the integral as energy flux. Note that $J^V_\mu (\phi) n^\mu_\Sigma \geq 0$ if $V$ is future directed timelike and $\Sigma$ spacelike, where $n^\mu_\Sigma$ is the future directed normal vector on the hypersurface $\Sigma$.

Since we will frequently use versions of the divergence theorem, we are interested in the divergence of the current (7). Defining

$$K^V(\phi) = T(\phi)(\nabla V) = (\pi^V)^{\mu\nu} T_{\mu\nu} (\phi), \quad (8)$$

by (6) it follows that

$$\nabla^\mu J^V_\mu (\phi) = K^V(\phi). \quad (9)$$

---

Note in contrast that the tangential derivatives of $\phi$ can be shown to be uniformly bounded up to $\mathcal{CH}^+$ (away from the bifurcation sphere) from the energy estimates proven in this paper together with commuting with angular momentum operators, cf. Theorem 1.2.
Further, \((\pi^V)_{\mu\nu} = \frac{1}{2}(\mathcal{L}_V g)_{\mu\nu}\) is the so called deformation tensor of \(V\). Therefore, \(\nabla^\mu J^V_\mu(\phi) = 0\) if \(V\) is Killing.

For a Killing vector field \(W\) we have in addition the commutation relation \([\Box_g, W] = 0\). In that context \(W\) is called a commutation vector field. In particular, we note already that in Reissner-Nordström spacetime we have \(\Box_g T\phi = 0\) and \(\Box_g J_i\phi = 0\), where \(T\) and \(J_i\) with \(i = 1, 2, 3\) are Killing vector fields that will be defined in Sects. 2.3.1 and 2.3.2, respectively.

For a more detailed discussion see [21] by Dafermos and Rodnianski [26] by Klainerman and [7] by Christodoulou.

2.2. The Reissner-Nordström solution. In the following we will briefly recall the Reissner-Nordström solution\(^5\) which is a family of solutions to the Einstein-Maxwell field equations

\[
R_{\mu\nu} - \frac{1}{2}g_{\mu\nu}R = 2T^{EM}_{\mu\nu},
\]

with \(R_{\mu\nu}\) the Ricci tensor, \(R\) the Ricci scalar and the units chosen such that \(\frac{8\pi G}{c^4} = 2\). The Maxwell equations are given by

\[
(\nabla^\alpha F_{\alpha\beta} = 0, \quad \nabla_{[\alpha} F_{\beta\gamma]} = 0, \quad (11)
\]

and the energy-momentum tensor by

\[
T^{EM}_{\mu\nu} = F_{\mu}^{\alpha} F_{\alpha\nu} - \frac{1}{4}g_{\mu\nu} F^{\alpha\beta} F_{\alpha\beta}. \quad (12)
\]

The system (10)–(12) describes the interaction of a gravitational field with a source free electromagnetic field. The Reissner-Nordström solution represents a charged black hole as an isolated system in an asymptotically Minkowski spacetime. The causal structure is similar to the structure of the astrophysically more realistic axisymmetric Kerr black holes. Since spherical symmetry can often simplify first investigations, Reissner-Nordström spacetime is a popular proxy for Kerr.

2.2.1. The metric and ambient differential structure. To set the semantic convention, whenever we refer to the Reissner-Nordström solution \((\mathcal{M}, g)\) we mean the maximal domain of dependence \(D(\Sigma) = \mathcal{M}\) of complete two-ended asymptotically flat data \(\Sigma\).

The manifold \(\mathcal{M}\) can be expressed by \(\mathcal{M} = Q \times S^2\), and \(Q = (-1, 1) \times (-1, 1)\) with coordinates \(U, V \in (-1, 1)\) and thus

\[
\mathcal{M} = (-1, 1) \times (-1, 1) \times S^2. \quad (13)
\]

The metric in global double null coordinates then takes the form

\[
g = -\Omega^2(U, V)dUdV + r^2(U, V)\left[d\theta^2 + \sin^2 \theta d\phi^2\right], \quad (14)
\]

where \(\Omega^2\) and \(r\) will be described below.

\(^5\) The reader unfamiliar with this solution may for example consult [25] for a more detailed review.
As a gauge condition we choose the hypersurface $U = 0$ and $V = 0$ to coincide with what will be the event horizons and we set
\[
\Omega^2(0, V) = \frac{1}{1 - V^2}, \quad \Omega^2(U, 0) = \frac{1}{1 - U^2},
\]
consistent with the fact that these hypersurfaces are to have infinite affine length. Fix parameters $M > |e| \neq 0$. The Reissner-Nordström metric (14) in our gauge is uniquely determined from (10) to (12) by setting
\[
r(0, V) = r|_{\mathcal{H}^+} = M + \sqrt{M^2 - e^2} = r_+ , \quad r(U, 0) = r|_{\mathcal{H}^+} = M + \sqrt{M^2 - e^2} = r_+ .
\]
(16)

Rearranging the Einstein-Maxwell equations (10) using (14) we obtain the following Hessian equation
\[
\frac{\partial_U \partial_V r}{\Omega^2} = \frac{e^2 \Omega^2}{4r^3} - \frac{\Omega^2}{4r} - \frac{\partial_U r}{r},
\]
from the $U, V$ component. From the $\theta, \theta$ or equivalently $\phi, \phi$ component we obtain
\[
\frac{\partial_U \partial_V \log \Omega^2}{\Omega^2} = \frac{2\partial_U \partial_V r}{r} \equiv - \frac{e^2 \Omega^2}{2r^4} + \frac{\Omega^2}{2r^2} + \frac{2\partial_U r \partial_V r}{r^2},
\]
(18)

In fact, all relevant information about Reissner-Nordström geometry can be understood directly from (15) to (18) without explicit expressions for $\Omega^2(U, V)$ and $r(U, V)$. In particular, one can derive the Raychaudhuri equations
\[
\partial_U \left( \frac{\partial_U r}{\Omega^2} \right) = 0 , \quad \partial_V \left( \frac{\partial_V r}{\Omega^2} \right) = 0,
\]
(19)
from the above.

We can illustrate the 2-dimensional quotient spacetime $Q$ as a subset of an ambient $\mathbb{R}^{1+1}$:

Identifying $U, V$ with ambient null coordinates of $\mathbb{R}^{1+1}$, the boundary of $Q \subset \mathbb{R}^{1+1}$ is given by $\pm 1 \times [-1, 1] \cup [-1, 1] \times \pm 1$. Let us further define the darker shaded region $II$ of Fig. 3 by $Q|_{II} = [0, 1) \times (0, 1)$. Particularly important is $\mathcal{C}H^*_A \cup \mathcal{C}H^*_B = 1 \times (0, 1] \cup (0, 1] \times 1$, which is the future boundary of the interior of region $II$. We define $\mathcal{M}|_{II} = \pi^{-1}(Q|_{II})$, where $\pi$ is the projection $\pi : \mathcal{M} \rightarrow Q$.

2.2.2. Eddington-Finkelstein coordinates. It will be convenient to rescale the global double null coordinates and define
\[
u = h(V) = \frac{2r_+}{r_+^2 - e^2} \ln \left| \frac{1 + V}{1 - V} \right|.
\]
(20)

Note that $u$ is the retarded and $v$ is the advanced Eddington-Finkelstein coordinate. These coordinates are both regular in the interior of $Q|_{II}$, cf. Fig. 3. Nonetheless, we can view the whole of $Q|_{II}$ as
\[
Q|_{II} = [-\infty, \infty) \times [-\infty, \infty),
\]
(21)
where we have formally parametrized by

\[ \mathcal{H}_A^+ = \{-\infty\} \times [-\infty, \infty), \quad \mathcal{H}_B^+ = [-\infty, \infty) \times \{-\infty\}, \]

as depicted in Fig. 4, see also (20).

In \( u, v \) coordinates the metric is given by

\[ g = -\Omega^2(u, v)du dv + r^2(u, v) \left[ d\theta^2 + \sin^2 \theta d\varphi^2 \right], \tag{22} \]

with

\[ \Omega^2(u, v) = \frac{\Omega^2(U, V)}{\partial_U f \partial_V h} = - \left( 1 - \frac{2M}{r} + \frac{e^2}{r^2} \right), \tag{23} \]

where the unfamiliar minus sign on the right hand side arises since all definitions have been made suitable for the interior. We will often make use of the fact that by the choice
of Eddington-Finkelstein coordinates \( \text{E-F} \) for the interior we have scaled our coordinates such that
\[
\frac{\partial_u r}{\Omega^2} = -\frac{1}{2}, \quad \frac{\partial_v r}{\Omega^2} = -\frac{1}{2}.
\] (24)
[The fact that the above expressions are constants follows from the Raychaudhuri equations (19) and (19)]. Taking the derivatives of (23) with respect to \( u \) and \( v \) and using (24) it follows that
\[
\frac{\partial_u \Omega}{\Omega}(u, v) = \frac{1}{2} r^2 \left( M - \frac{e^2}{r} \right), \quad \frac{\partial_v \Omega}{\Omega}(u, v) = \frac{1}{2} r^2 \left( M - \frac{e^2}{r} \right).
\] (25)

2.3. Further properties of Reissner-Nordström geometry.

2.3.1. \((t, r^*)\) and \((t, r)\) coordinates. It is useful to define the function \( t: \tilde{M}_{|I \!I} \rightarrow \mathbb{R} \) by
\[
t(u, v) = \frac{v - u^2}{2},
\] (26)
where \( M_{|I \!I} = M_{|I \!I} \setminus \partial M_{|I \!I} \) is the interior of \( M_{|I \!I} \). Moreover, we define the function \( r^*: \tilde{M}_{|I \!I} \rightarrow \mathbb{R} \) by
\[
r^*(u, v) = \frac{v + u^2}{2},
\] (27)
where \( r^* \) is usually referred to as the Regge-Wheeler coordinate. Note that for coordinates \((t, r^*, \varphi, \theta)\) defined in \( \tilde{M}_{|I \!I} \) we have that \( \frac{\partial}{\partial r^*} \) is a spacelike Killing vector field which extends to the globally defined Killing vector field \( T \) on \( M \). By \( \varphi_T \) we denote a 1-parameter group of diffeomorphisms generated by the Killing field \( T \). We can moreover relate the functions \( r \) and \( r^* \) by
\[
\frac{dr^*}{1 - \frac{2M}{r} + \frac{e^2}{r^2}} \Rightarrow r^* = r + \frac{1}{\kappa_+} \ln \left| \frac{r-r_+}{r_+} \right| + \frac{1}{\kappa_-} \ln \left| \frac{r-r_-}{r_-} \right| + C,
\] (28)
where \( C \) is constant which is implicitly fixed by previous definitions,
\[
r_- = M - \sqrt{M^2 - e^2},
\] (29)
and the surface gravities are given by
\[
\kappa_\pm = \frac{r_\pm - r_\mp}{2r_\pm^2}.
\] (30)
Note that \( \kappa_+ \) is the surface gravity at \( \mathcal{H}^+ \) and \( \kappa_- \) is the surface gravity at \( \mathcal{C H}^+ \). The function \( r(u, v) \) extends continuously and is monotonically decreasing in both \( u \) and \( v \) towards \( \mathcal{C H}^+ \) such that we have
\[
r(u, \infty) = r |_{\mathcal{C H}_A^+} = r_-, \quad r(\infty, v) = r |_{\mathcal{C H}_B^+} = r_-.
\] (31)
2.3.2. Angular momentum operators. We have already mentioned the generators of spherical symmetry $\mathcal{O}_i$, $i = 1, 2, 3$, in Sect. 2.1. They are explicitly given by

$$\mathcal{O}_1 = \sin \varphi \partial \theta + \cot \theta \cos \varphi \partial \varphi, \quad \mathcal{O}_2 = -\cos \varphi \partial \theta + \cot \theta \sin \varphi \partial \varphi, \quad \mathcal{O}_3 = -\partial \varphi,$$

which satisfy

$$\sum_{i=1}^{3} (\mathcal{O}_i \phi)^2 = r^2 |\nabla \phi|^2, \quad \sum_{i=1}^{3} \sum_{j=1}^{3} (\mathcal{O}_i \mathcal{O}_j \phi)^2 = r^4 |\nabla^2 \phi|^2,$$

where we define

$$|\nabla \phi|^2 = \frac{1}{r^2} \left[ (\partial \theta \phi)^2 + \frac{1}{\sin^2 \theta} (\partial \varphi \phi)^2 \right].$$

(32)

(33)

2.3.3. The redshift, noshift and blueshift region. As we have already mentioned in the introduction, in the interior we can distinguish

redshift $\mathcal{R} = \{r_{\text{red}} \leq r \leq r_+\}$, noshift $\mathcal{N} = \{r_{\text{blue}} \leq r \leq r_{\text{red}}\}$,

blueshift $\mathcal{B} = \{r_- \leq r \leq r_{\text{blue}}\}$

subregions, as shown in Fig. 5, for values $r_{\text{red}}, r_{\text{blue}}$ to be defined immediately below.

In the redshift region $\mathcal{R}$ we make use of the fact that the surface gravity $\kappa_+$ of the event horizon is positive. The region is then characterized by the fact that there exists a vector field $\mathcal{N}$ such that its associated current $J^\mu_{\mathcal{N}} n^v_{\mathcal{N} = \text{const}}$ on a $v = \text{const}$ hypersurface can be controlled by the related bulk term $K^\mu_{\mathcal{N}}$, cf. Proposition 4.1. This positivity of the bulk term $K^\mu_{\mathcal{N}}$ is only possible sufficiently close to $\mathcal{H}^+$. In particular we shall define

$$r_{\text{red}} = r_+ - \epsilon,$$

(34)

(35)

with $\epsilon > 0$ and small enough such that Proposition 4.1 is applicable. (Furthermore, note that the quantity $M - \frac{\epsilon^2}{r}$ is always positive in $\mathcal{R}$.)

As defined in (35) the $r$ coordinate in the noshift region $\mathcal{N}$ ranges between $r_{\text{red}}$ defined by (36) and $r_{\text{blue}}$, defined below, strictly bigger than $r_-$. In $\mathcal{N}$ we exploit the fact that $J_{-\partial r}$ and $K_{-\partial r}$ are invariant under translations along $\partial r$. For that reason we can uniformly control the bulk by the current along a constant $r$ hypersurface. This will be explained further in Sect. 4.1.2.

Fig. 5. Region II with distinction into redshift $\mathcal{R}$, noshift $\mathcal{N}$ and blueshift $\mathcal{B}$ regions
The blueshift region $\mathcal{B}$ is characterized by the fact that the bulk term $K^{S_0}$ associated to the vector field $S_0$ to be defined in (44) is positive. We define

$$r_{\text{blue}} = r_- + \tilde{\epsilon},$$

(37)

with $\tilde{\epsilon} > 0$ for an $\tilde{\epsilon}$ such that $M - \frac{\epsilon^2}{r_{\text{blue}}}$ carries a negative sign and such that (for convenience)

$$r^*(r_{\text{blue}}) > 0.$$ (38)

In particular, in view of (25) and (25) for $\tilde{\epsilon}$ sufficiently small the following lower bound holds in $\mathcal{B}$

$$0 < \beta \leq -\frac{\partial_u \Omega}{\Omega}, \quad 0 < \beta \leq -\frac{\partial_v \Omega}{\Omega},$$ (39)

with $\beta$ a positive constant.

2.4. Notation. We will describe certain regions derived from the hypersurfaces $r = r_{\text{red}}$, $r = r_{\text{blue}}$ and in addition the hypersurface $\gamma$ which will be defined in Sect. 4.1.3.1. For example given the hypersurface $r = r_{\text{red}}$ and the hypersurface $u = \tilde{u}$ we define the $v$ value at which these two hypersurfaces intersect by a function $v_{\text{red}}(\tilde{u})$ evaluated for $\tilde{u}$. Let us therefore introduce the following notation:

$$v_{\text{red}}(\tilde{u}) \text{ is determined by } r(v_{\text{red}}(\tilde{u}), \tilde{u}) = r_{\text{red}},$$

$$u_{\text{red}}(\tilde{v}) \text{ is determined by } r(u_{\text{red}}(\tilde{v}), \tilde{v}) = r_{\text{red}},$$

$$v_{\gamma}(\tilde{u}) \text{ is determined by } r(v_{\gamma}(\tilde{u}), \tilde{u}) \in \gamma,$$

$$u_{\gamma}(\tilde{v}) \text{ is determined by } r(u_{\gamma}(\tilde{v}), \tilde{v}) \in \gamma,$$

$$v_{\text{blue}}(\tilde{u}) \text{ is determined by } r(v_{\text{blue}}(\tilde{u}), \tilde{u}) = r_{\text{blue}},$$

$$u_{\text{blue}}(\tilde{v}) \text{ is determined by } r(u_{\text{blue}}(\tilde{v}), \tilde{v}) = r_{\text{blue}}.$$ (40)

For a better understanding the reader may also refer to Fig. 6.

Note that the above functions are well defined since $r = r_{\text{red}}, r = r_{\text{blue}}$ and $\gamma$ are spacelike hypersurfaces terminating at $i^+$. 

3. The Setup

3.1. Horizon estimates and Cauchy stability. Our starting point will be previously proven decay bounds for $\phi$ and its derivatives in the black hole exterior up to and including the event horizon; in particular we can state:

(a) $\text{CH}^+$

(b) $\text{CH}^+$

Fig. 6. Sketch of blueshift region $\mathcal{B}$, with quantities depicted (a) dependent on $\tilde{u}$ and (b) dependent on $\tilde{v}$
Theorem 3.1. Let \( \phi \) be a solution of the wave equation (1) on a subextremal Reissner-Nordström background \((M, g)\), with mass \( M \) and charge \( e \) and \( M > |e| \neq 0 \), arising from smooth compactly supported initial data on an arbitrary Cauchy hypersurface \( \Sigma \), cf. Fig. 1. Then, there exists \( \delta > 0 \) such that

\[
\int_{S^2} \int_v^{v+1} \left[ \left( \partial_\Omega \xi^k \phi \right)^2(-\infty, v) + \Omega^2 |\nabla_\Omega \xi^k \phi|^2(-\infty, v) \right] r^2 dv d\sigma_{S^2} \leq C_k v^{-2-2\delta}, \quad \text{for all } k \in \mathbb{N}_0, \tag{41}
\]

on \( \mathcal{H}^{+}_A \), for all \( v \) and some positive constants \( C_k \) depending on the initial data.\(^6\)

Proof. The Theorem follows by putting together work of Blue and Soffer [6] on integrated local energy decay, Dafermos and Rodnianski [15] on the redshift and Schlue [41] on improved decay using the method of [17] in the exterior region. Specifically, [6] proves integrated local energy decay with degeneration on the horizon. Adding the redshift vector field energy identity of [15] yields integrated local energy decay without degeneration on the horizon. One can then apply the black box result of [17] to obtain polynomial decay on \( \mathcal{H}^{+}_A \) of the form (41) with \( \delta = 0 \). One finally applies [41] to obtain (41) for \( \delta > 0 \). \( \square \)

The assumption of smoothness and compact support in Theorem 3.1 can be weakened. In fact, we shall only need (41) for \( k = 0, 1, 2 \). Moreover, as shown in [41], we can in fact take \( \delta \) arbitrarily close to \( \frac{1}{2} \), but \( \delta > 0 \) is sufficient for our purposes and allows in principle for a larger class of data on \( \Sigma \).

On the other hand, trivially from Cauchy stability, boundedness of the energy along the second component of the past boundary of the characteristic rectangle \( \Xi_1 \), cf. Sect. 1.3, which we have picked to be \( v = 1 \), can be derived. More generally we can state the following proposition.

Proposition 3.2. Let \( u_\diamond, v_\diamond \in (\infty, \infty) \). Under the assumption of Theorem 3.1, the energy at advanced Eddington-Finkelstein coordinate \( \{ v = v_\diamond \} \cap \{ -\infty \leq u \leq u_\diamond \} \) is bounded from the initial data

\[
\int_{S^2} \int_{-\infty}^{u_\diamond} \left[ \Omega^{-2} (\partial_\Omega \xi^k \phi)^2(u, v_\diamond) + \Omega^2 |\nabla_\Omega \xi^k \phi|^2(u, v_\diamond) \right] r^2 dv d\sigma_{S^2} \leq D_k(u_\diamond, v_\diamond), \tag{42}
\]

and further

\[
\sup_{-\infty \leq u \leq u_\diamond} \int_{S^2} (\xi^k \phi)^2(u, v_\diamond) d\sigma_{S^2} \leq D_k(u_\diamond, v_\diamond), \quad \text{for all } k \in \mathbb{N}_0, \tag{43}
\]

with \( D_k(u_\diamond, v_\diamond) \) positive constants depending on the initial data on \( \Sigma \).

Proof. This follows immediately from local energy estimates in a compact spacetime region. Note the \( \Omega^{-2} \) and \( \Omega^2 \) weights which arise since \( u \) is not regular at \( \mathcal{H}^{+}_A \). \( \square \)

---

\(^6\) The notation \( \xi^k \) denotes summation over angular momentum operators as defined in Sect. 4.2.1 by (128).
3.2. Statement of the theorem and outline of the proof in the neighbourhood of $i^+$. The most difficult result of this paper can now be stated in the following theorem.

**Theorem 3.3.** On subextremal Reissner-Nordström spacetime with $M > |e| \neq 0$, let $\phi$ be as in Theorem 3.1, then

$$|\phi| \leq C$$

locally in the black hole interior up to $\mathcal{CH}^+$ in a “small neighbourhood” of timelike infinity $i^+$, that is in $(-\infty, u_\infty) \times [1, \infty)$ for some $u_\infty > -\infty$.

**Remark.** We will see that $C$ depends only on the initial data.

We will consider a characteristic rectangle $\Xi$ extending from $\mathcal{H}^A$ as shown in Fig. 7. We pick the characteristic rectangle to be defined by $\Xi = \{(-\infty \leq u \leq u_\infty), (1 \leq v < \infty)\}$, where $u_\infty$ is sufficiently close to $-\infty$ for reasons that will become clear later on, cf. Proposition 4.11. As described in Sect. 3.1, from bounds of data on $\Sigma$ bounds on the solution on the lower segments follow according to Theorem 3.1 and Proposition 3.2.

In order to prove Theorem 3.3 we distinguish the redshift $R$, the noshift $N$ and the blueshift $B$ region, with the properties as explained in Sect. 2.3.3, cf. Fig. 7b). This distinction is made since different vector fields have to be employed in the different regions.7

In the redshift region $R$ we will make use of the redshift vector field $N$ of [21] on which we will elaborate more in Sect. 4.1.1. Proposition 4.1 gives the positivity of the bulk $K^N$ which thus bounds the current $J^N_{\mu} n^{\mu}_{r=\text{const}}$ from above. Applying the divergence theorem, decay up to $r = r_{\text{red}}$ will be proven.

In the noshift region $N$ we can simply appeal to the fact that the future directed timelike vector field $-\partial_r$ is invariant under the flow of the spacelike Killing vector field $\partial_t$. It is for that reason that the bulk term $K^{\partial_t}$ can be uniformly controlled by the energy flux $J^{\partial_t}_{\mu} n^{\mu}_{r=\text{const}}$ through the $r = \bar{r}$ hypersurface. Decay up to $r = r_{\text{blue}}$ will be proven by making use of this together with the uniform boundedness of the $v$ length of $N$.

To understand the blueshift region $B$, we will partition it by the hypersurface $\gamma$ admitting logarithmic distance in $v$ from $r = r_{\text{blue}}$, cf. Sect. 4.1.3.1. We will then separately consider the region to the past of $\gamma$, $J^- (\gamma) \cap B$ and the region to the future of $\gamma$, $J^+ (\gamma) \cap B$. The region to the future of $\gamma$ is characterized by good decay bounds on $\Omega^2$ (implying for instance that the spacetime volume is finite, $\text{Vol}(J^+ (\gamma)) < C$).

7 The reader may wonder why the noshift region $N$ is introduced instead of just separating the red- and the blueshift regions along the $r$ hypersurface whose value renders the quantity $M - \frac{e^2}{r}$ equal zero. This was to ensure strict positivity/negativity of the quantity in the redshift/blueshift region.
In $J^-(\gamma) \cap B$ we use a vector field
\[ S_0 = r^q \partial_{r^*} = r^q (\partial_u + \partial_v), \] (44)
where $q$ is sufficiently large, cf. Sect. 4.1.3. We will see that for the right choice of $q$ we can render the associated bulk term $K^{S_0}$ positive which is the “good” sign when using the divergence theorem.

In order to complete the proof, we consider finally the region $J^+(\gamma) \cap B$ and propagate the decay further from the hypersurface $\gamma$ up to the Cauchy horizon in a neighbourhood of $i^+$. For this, we introduce a new timelike vector field $S$ defined by
\[ S = |u|^p \partial_u + v^p \partial_v, \] (45)
for an arbitrary $p$ such that
\[ 1 < p \leq 1 + 2\delta, \] (46)
where $\delta$ is as in Theorem 3.1. We use pointwise estimates on $\Omega^2$ in $J^+(\gamma)$ as a crucial step, cf. Sect. 4.1.4.1.

Putting everything together, in view of the geometry and the weights of $S$, we finally obtain for all $v_* \geq 1$
\[ \int_{\mathbb{S}^2} \int_1^{v_*} v^p (\partial_v \phi)^2 r^2 dv d\sigma_{\mathbb{S}^2} \leq \text{Data}, \] (47)
for the weighted flux. Using the above, the uniform boundedness for $\phi$ stated in Theorem 3.3 then follows from an argument that can be sketched as follows.

Let us first see how we get an integrated bound on the spheres of symmetry. By the fundamental theorem of calculus and the Cauchy-Schwarz inequality one obtains
\[ \int_{\mathbb{S}^2} \phi^2 (u, v_*, \theta, \varphi) d\sigma_{\mathbb{S}^2} \leq C \left( \int_1^{v_*} (\int_1^{v_*} v^p (\partial_v \phi)^2 dv) \right) \left( \int_1^{v_*} v^{-p} dv \right) r^2 d\sigma_{\mathbb{S}^2} + \text{data}, \]
where the first factor of the first term is controlled by (47). Therefore, we further get
\[ \int_{\mathbb{S}^2} \phi^2 d\sigma_{\mathbb{S}^2} \overset{(47)}{\leq} \text{Data} \int_{\mathbb{S}^2} \int_1^{v_*} v^{-p} dv d\sigma_{\mathbb{S}^2} + \text{data} \leq \text{Data} + \text{data}, \] (48)
where we have used $\int_1^{\infty} v^{-p} dv < \infty$ which followed from the first inequality of (46).

Obtaining a pointwise statement from the above will be achieved by commuting (1) with symmetries as well as applying Sobolev embedding. As outlined in Sect. 2.1 in Reissner-Nordström geometry we have $\Box_g \omega_i \phi = 0$, where $\omega_i$ with $i = 1, 2, 3$ are the 3 spacelike Killing vector fields resulting from the spherical symmetry. Thus one obtains the analogue of (48) but with $\omega_i \phi$ and $\omega_i \omega_j \phi$ in place of $\phi$. Using Sobolev embedding on $\mathbb{S}^2$ thus leads immediately to the desired bounds. See Sect. 4.2.3. This will close the proof of Theorem 3.3.
4. Energy and Pointwise Estimates in the Interior

In this section we will derive the proof of Theorem 1.2. For this we will first state the decay bound for the energy flux of \( \phi \) given on the event horizon \( H^+ \), cf. Theorem 3.1. Using this we propagate the decay rate through the entire interior up to the Cauchy horizon. As outlined in Sect. 1.3, we first consider a characteristic rectangle \( \Xi \) in the neighbourhood of \( i^+ \). Within \( \Xi \) we need to separate the interior into different subregions. We then apply suitable vector fields according to the specific properties of the underlying subregion, which will be described further in the following subsections.

4.1. Energy estimates in the neighbourhood of \( i^+ \).

4.1.1. Propagating through \( \mathcal{R} \) from \( H^+ \) to \( r = r_{\text{red}} \). The estimates in this and the following section are motivated by work of Luk [30]. He proves that any polynomial decay estimate that holds along the event horizon of Schwarzschild black holes can be propagated to any constant \( r \) hypersurface in the black hole interior. This followed a previous spherically symmetric argument of [13]. See also Dyatlov [23].

As outlined in Sect. 3.1, we will first propagate energy decay from \( H^+ \) up to the \( r = r_{\text{red}} \) hypersurface.

The rough idea can be understood with the help of Fig. 8. By Theorem 3.1 we are given energy decay on the event horizon \( \mathcal{H}^+ \), see dash-dotted line. By using the energy identity for the vector field \( N \) in region \( \mathcal{R}_I = \{ r_{\text{red}} \leq r \leq r_+ \} \cap \{ 1 < v \leq v_* \} \), the coarea formula etc., we obtain decay of the flux through constant \( v \) hypersurfaces throughout the entire region. Using this result and considering the energy identity once again in region \( \tilde{\mathcal{R}}_I = \{ r_{\text{red}} \leq r \leq r_+ \} \cap \{ v_* \leq v \leq v_* + 1 \} \) we eventually obtain decay on the \( r = r_{\text{red}} \) hypersurface, note the dashed line.

The redshift vector field was already introduced by Dafermos and Rodnianski in [16] and elaborated on again in [21]. The existence of such a vector field in the neighbourhood of a Killing horizon \( \mathcal{H}^+ \) depends only on the positivity of the surface gravity, in this case \( \kappa_+ \). Thus by (30) the following proposition follows by Theorem 7.1 of [21].
Proposition 4.1. (Dafermos and Rodnianski). For \( r_{\red} \) sufficiently close to \( r_{+} \) there exists a \( \varphi_{\red} \)-invariant smooth future directed timelike vector field \( N \) on \( \{ r_{\red} \leq r \leq r_{+} \} \cap \{ v \geq 1 \} \) and a positive constant \( b_1 \) such that
\[
b_1 J_{\mu}^N (\phi) n^\mu_v \leq K^N (\phi),
\]
for all solutions \( \phi \) of \( \Box g \phi = 0 \).

The decay bound along \( r = r_{\red} \) can now be stated in the following proposition.

Proposition 4.2. Let \( \phi \) be as in Theorem 3.1. Then, for all \( \tilde{r} \in [r_{\red}, r_{+}) \), with \( r_{\red} \) as in Proposition 4.1 and for all \( v^* > 1 \),
\[
\int_{\{ v_0 \leq v \leq v^* + 1 \}} J_{\mu}^N (\phi) n^\mu_{\tilde{r}} d\text{Vol}_{\tilde{r} = \tilde{r}} \leq C v_*^{-2-2\delta},
\]
with \( C \) depending on \( C_0 \) of Theorem 3.1 and \( D_0 (u_{\diamond}, 1) \) of Proposition 3.2, where \( u_{\diamond} \) is defined by \( r_{\red} = r (u_{\diamond}, 1) \).

Remark 1. The decay in Proposition 4.2 matches the decay on \( \mathcal{H}^+ \) of Theorem 3.1.

Remark 2. \( n^\mu_{r=r_{\red}} \) denotes the normal to the \( r = r_{\red} \) hypersurface oriented according to Lorentzian geometry convention. \( d\text{Vol} \) denotes the volume element over the entire spacetime region and \( d\text{Vol}_{r=r_{\red}} \) denotes the volume element on the \( r = r_{\red} \) hypersurface. Similarly for all other subscripts.

Proof. Applying the divergence theorem, see e.g. [21] or [45], in region \( \mathcal{R}_I = \{ r_{\red} \leq r \leq r_{+} \} \cap \{ v_0 \leq v \leq v_* \} \), with \( v_0 \geq 1 \), we obtain
\[
\int_{\mathcal{R}_I} K^N (\phi) d\text{Vol} + \int_{\{ v_0 \leq v \leq v_* \}} J_{\mu}^N (\phi) n^\mu_{r=r_{\red}} d\text{Vol}_{r=r_{\red}} + \int_{\{ r_{\red} \leq r \leq r_{+} \}} J_{\mu}^N (\phi) n^\mu_{v=v_*} d\text{Vol}_{v=v_*} = \int_{\{ v_0 \leq v \leq v_* \}} J_{\mu}^N (\phi) n^\mu_{v=v_*} d\text{Vol}_{v=v_*} + \int_{\{ v_0 \leq v \leq v_* \}} J_{\mu}^N (\phi) n^\mu_{\mathcal{H}^+} d\text{Vol}_{\mathcal{H}^+}.
\]

We immediately see that the second term on the left hand side is positive since \( r = r_{\red} \) is a spacelike hypersurface and \( N \) is a timelike vector field. Therefore, we write
\[
\int_{\mathcal{R}_I} K^N (\phi) d\text{Vol} + \int_{\{ r_{\red} \leq r \leq r_{+} \}} J_{\mu}^N (\phi) n^\mu_{v=v_*} d\text{Vol}_{v=v_*} \leq \int_{\{ r_{\red} \leq r \leq r_{+} \}} J_{\mu}^N (\phi) n^\mu_{v=v_0} d\text{Vol}_{v=v_0} + \int_{\{ v_0 \leq v \leq v_* \}} J_{\mu}^N (\phi) n^\mu_{\mathcal{H}^+} d\text{Vol}_{\mathcal{H}^+}.
\]

By Theorem 3.1 we have
\[
\int_{\{ v_0 \leq v \leq v_* \}} J_{\mu}^N (\phi) n^\mu_{\mathcal{H}^+} d\text{Vol}_{\mathcal{H}^+} \leq C_0 \max \{ v_* - v_0, 1 \} v_0^{-2-2\delta}.
\]

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8 cf. Sect. 2.3.

9 Refer to “Appendix A” for further discussion of the volume elements.
Using that the energy current associated to the timelike vector field $N$ is controlled by the deformation $K^N$ as shown in (49) and substituting

$$E(\phi; \tilde{v}) = \int_{\{r_{\text{red}} \leq r \leq r_+\}} J^N_{\mu}(\phi)n^{\mu}_{v=\tilde{v}} \text{dVol}_{v=\tilde{v}}$$

(51)

into (50) as well as using the coarea formula

$$\int_{\mathcal{R}_t} J^N_{\mu}(\phi)n^{\mu}_{v=\tilde{v}} \text{dVol} \sim \int_{v_0}^{v_*} \int_{\{r_{\text{red}} \leq r \leq r_+\}} J^N_{\mu}(\phi)n^{\mu}_{v=\tilde{v}} \text{dVol}_{v=\tilde{v}} \text{d}\tilde{v},$$

(52)

for the bulk term,\(^{10}\) we obtain for all $v_0 \geq 1$ and $v_* > v_0$, the relation

$$E(\phi; v_0) + \tilde{b}_1 \int_{v_0}^{v_*} E(\phi; \tilde{v}) \text{d}\tilde{v} \leq E(\phi; v_0) + C_0 \max\{v_* - v_0, 1\} v_0^{-2 \beta}.$$  

(53)

Note by Proposition 3.2 with $k = 0$, applied to $u_\phi$ defined through the relation $r_{\text{red}} = r(u_\phi, 1)$, we have

$$E(\phi; 1) \leq CD_0(u_\phi, 1),$$  

(54)

since the vector field $N$ is regular at $\mathcal{H}^+$ and thus $E(\phi; 1)$ is comparable to the left hand side of (42). In order to obtain estimates from (53) we appeal to the following lemma.

\(\square\)

**Lemma 4.3.** Let $f$ be a continuous function, $f : [1, \infty) \to \mathbb{R}^+$,

$$f(t) + b \int_{\tilde{t}}^{t} f(\tilde{t}) d\tilde{t} \leq f(\tilde{t}) + C_0 (t - \tilde{t} + 1)\tilde{t}^{-\tilde{p}},$$

(55)

for all $\tilde{t} \geq 1$, where $C_0, \tilde{p}$ are positive constants. Then for any $t \geq 1$ we have

$$f(t) \leq \tilde{C} t^{-\tilde{p}},$$

(56)

where $\tilde{C}$ depends only on $f(1)$, $b$ and $C_0$.

**Proof.** For $t > t_0$, we will show (56) by a continuity (bootstrap) argument. It suffices to show that

$$f(\tilde{t}) \leq 2\tilde{C} \tilde{t}^{-\tilde{p}}, \text{ for } \tilde{t} \leq t,$$

(57)

leads to

$$\Rightarrow f(\tilde{t}) \leq \tilde{C} \tilde{t}^{-\tilde{p}}, \text{ for } \tilde{t} \leq t,$$

(58)

for some large enough constant $\tilde{C}$.

\(^{10}\) where $f \sim g$ means that there exist constants $0 < b < B$ with $bf < g < Bf$. 

We note first that given any \( t_0 \), from (55) we obtain, \( \forall \ 1 \leq t \leq t_0 \)
\[
f(t) \leq f(1) + C_0 t \leq [f(1)t_0\tilde{p} + C_0 t_0\tilde{p} + 1]t^{-\tilde{p}}. \quad (59)
\]
Given \( t \geq t_0 \), choose \( \tilde{t} = t - L \) for an \( L \) to be determined later. Moreover, \( t_0 \) will have to be chosen large enough so that \( \forall \ t \geq t_0 \),
\[
(t - L)^{-\tilde{p}} = \tilde{t}^{-\tilde{p}} < 2t^{-\tilde{p}}.
\quad (60)
\]
Given a \( t \) satisfying (57) applying (55) yields
\[
f(t) + b \int_{\tilde{t}}^{t} f(\tilde{t})d\tilde{t} \leq [2\tilde{C} + C_0(L + 1)]\tilde{t}^{-\tilde{p}} \quad (60)
\leq [4\tilde{C} + 2C_0(L + 1)]t^{-\tilde{p}}. \quad (61)
\]
Further, by the pigeonhole principle, there exists \( t_{in} \in [\tilde{t}, t] \) such that
\[
f(t_{in}) \leq \frac{1}{L} \int_{\tilde{t}}^{t} f(\tilde{t})d\tilde{t}. \quad (62)
\]
Since \( f(t) \) is a positive function (61) also leads to
\[
b \int_{\tilde{t}}^{t} f(\tilde{t})d\tilde{t} \leq [4\tilde{C} + 2C_0(L + 1)]t^{-\tilde{p}}. \quad (63)
\]
Thus, (62) and (63) yield
\[
f(t_{in}) \leq \frac{1}{bL} [4\tilde{C} + 2C_0(L + 1)]t^{-\tilde{p}}. \quad (64)
\]
Now let \( \tilde{t} = t_{in} \) and use (64) in (55), then
\[
f(t) \leq f(t) + b \int_{t_{in}}^{t} f(\tilde{t})d\tilde{t} \leq \frac{1}{bL} [4\tilde{C} + 2C_0(L + 1)]t^{-\tilde{p}} + C_0(L + 1)t_{in}^{-\tilde{p}},
\[
\leq \left[\frac{4\tilde{C}}{bL} + \frac{2C_0(L + 1)}{bL} + 2C_0(L + 1)\right]t^{-\tilde{p}}. \quad (65)
\]
If \( 1 - \frac{4}{bL} > 0 \) and
\[
\tilde{C} \geq \left(1 - \frac{4}{bL}\right)^{-1} \left[\frac{2C_0(L + 1)}{bL} + 2C_0(L + 1)\right] \quad (66)
\]
then (58) follows.

Thus picking first \( L \) such that \( 1 - \frac{4}{bL} > 0 \), and then \( t_0 \) such that \( t_0 \geq L + 1 \) and satisfying (60), and finally choosing \( \tilde{C} = \tilde{C} = \max \left\{f(1) + C_0 t_0^{-1 - \delta}, \left(1 - \frac{4}{bL}\right)^{-1} \left[\frac{2C_0(L + 1)}{bL} + 2C_0(L + 1)\right]\right\} \) (58) and thus (56) follows by continuity. \( \Box \)
By Lemma 4.3 we obtain from (53) together with (54)

$$E(\phi; v_*) = \int_{\{r_{\text{red}} \leq r \leq r_+\}} J^N_\mu(\phi)n^\mu_{v=v_*} \, d\text{Vol}_{v=v_*} \leq \tilde{C} v_*^{-2-2\delta}, \quad (67)$$

with $\tilde{C}$ depending on $\tilde{b}_1$ and $D_0(u_\circ, 1)$.

Finally, in order to close the proof of Proposition 4.2 we perform again the divergence theorem but for region $\tilde{K}_I = \{r_{\text{red}} \leq r \leq r_+\} \cap \{v_* \leq v \leq v_* + 1\}$:

$$\int_{\tilde{K}_I} K^N(\phi) \, d\text{Vol} + \int_{\{v_* \leq v \leq v_* + 1\}} J^N_\mu(\phi)n^\mu_{r=r_{\text{red}}} \, d\text{Vol}_{r=r_{\text{red}}}$$

$$+ \int_{\{r_{\text{red}} \leq r \leq r_+\}} J^N_\mu(\phi)n^\mu_{v=v_*+1} \, d\text{Vol}_{v=v_*+1} = \int_{\{r_{\text{red}} \leq r \leq r_+\}} J^N_\mu(\phi)n^\mu_{v=v_*} \, d\text{Vol}_{v=v_*}$$

$$+ \int_{\{v_* \leq v \leq v_* + 1\}} J^N_\mu(\phi)n^\mu_{\mathcal{H}^+} \, d\text{Vol}_{\mathcal{H}^+}. \quad (68)$$

In view of the signs we obtain

$$\Rightarrow \int_{\{v_* \leq v \leq v_* + 1\}} J^N_\mu(\phi)n^\mu_{r=r_{\text{red}}} \, d\text{Vol}_{r=r_{\text{red}}} \leq \int_{\{r_{\text{red}} \leq r \leq r_+\}} J^N_\mu(\phi)n^\mu_{v=v_*} \, d\text{Vol}_{v=v_*}$$

$$+ \int_{\{v_* \leq v \leq v_* + 1\}} J^N_\mu(\phi)n^\mu_{\mathcal{H}^+} \, d\text{Vol}_{\mathcal{H}^+}.$$  

Due to (67) and Theorem 3.1 we are left with the conclusion of Proposition 4.2. $\Box$

Note that the above also implies the following statement.

**Corollary 4.4.** Let $\phi$ be as in Theorem 3.1 and for $r_{\text{red}}$ as in Proposition 4.1. Then, for all $v_* \geq 1$, $v_* + 1 \leq v_{\text{red}}(\tilde{u})$ and for all $\tilde{u}$ such that $r(\tilde{u}, v_* + 1) \in [r_{\text{red}}, r_+]$, we have

$$\int_{\{v_* \leq v \leq v_* + 1\}} J^N_\mu(\phi)n^\mu_{u=\tilde{u}} \, d\text{Vol}_{u=\tilde{u}} \leq C v_*^{-2-2\delta}, \quad (69)$$

with $C$ depending on $C_0$ of Theorem 3.1 and $D_0(u_\circ, 1)$ of Proposition 3.2, where $u_\circ$ is defined by $r_{\text{red}} = r(u_\circ, 1)$ and $v_{\text{red}}(\tilde{u})$ as in (40).

**Proof.** The conclusion of the statement follows by applying again the divergence theorem and using the results of the proof of Proposition 4.2. $\Box$
4.1.2. Propagating through $\mathcal{N}$ from $r = r_{\text{red}}$ to $r = r_{\text{blue}}$. Now that we have obtained a decay bound along the $r = r_{\text{red}}$ hypersurface in the previous section, we propagate the estimate further inside the black hole through the noshift region $\mathcal{N}$ up to the $r = r_{\text{blue}}$ hypersurface. In order to do that we will use the future directed timelike vector field

$$-\partial_r = \frac{1}{\Omega^2} (\partial_u + \partial_v).$$

(70)

Using (70) in (B2) of “Appendix B” we obtain

$$K^{-\partial_r} = \frac{4}{\Omega^4} \left[ \frac{\partial_u \Omega}{\Omega} (\partial_v \phi)^2 + \frac{\partial_v \Omega}{\Omega} (\partial_u \phi)^2 \right] - \frac{4}{r \Omega^2} (\partial_u \phi \partial_v \phi),$$

for the bulk current. It has the property that it can be estimated by

$$|K^{-\partial_r} (\phi)| \leq B_1 J_\mu^{-\partial_r} (\phi) n_{\mu}^{r=r_{\tilde{r}}},$$

(72)

where $B_1$ is independent of $v_s$. Validity of the estimate can in fact be seen without computation from the fact that timelike currents, such as $J_\mu^{-\partial_r} (\phi) n_{\mu}^{r=r_{\tilde{r}}}$ contain all derivatives. The uniformity of $B_1$ is given by the fact that $K^{-\partial_r}$ and $J^{-\partial_r}$ are invariant under translations along $\partial_t$, cf. Sect. 2.3.1 for definition of the $t$ coordinate. Therefore, we can just look at the maximal deformation on a compact $\{t = \text{const}\} \cap \{r_{\text{blue}} \leq r \leq r_{\text{red}}\}$ hypersurface and get an estimate for the deformation everywhere.

**Proposition 4.5.** Let $\phi$ be as in Theorem 3.1, $r_{\text{blue}}$ as in (37) and $r_{\text{red}}$ as in Proposition 4.1. Then, for all $v_s > 1$ and $\tilde{r} \in [r_{\text{blue}}, r_{\text{red}})$, we have

$$\int_{\{v_s \leq v \leq v_s + 1\}} J_\mu^{-\partial_r} (\phi) n_{\mu}^{r=r_{\tilde{r}}} d\text{Vol}_{r=r_{\tilde{r}}} \leq C v_s^{-2 - 2\delta},$$

with $C$ depending on the initial data or more precisely depending on $C_0$ of Theorem 3.1 and $D_0 (u_\circ, 1)$ of Proposition 3.2, where $u_\circ$ is defined by $r_{\text{red}} = r (u_\circ, 1)$.

**Proof.** Given $v_s$, we define regions $\mathcal{R}_{II}$ and $\tilde{\mathcal{R}}_{II}$ as in Fig. 9, where we use (40) and

$$v(\tilde{r}, v_s) \quad \text{is determined by} \quad r (u_{\text{blue}} (v_s), v (\tilde{r}, v_s)) = \tilde{r}. \quad (73)$$

Thus the depicted regions are given by $\mathcal{R}_{II} \cup \tilde{\mathcal{R}}_{II} = \mathcal{D}^+ (\{v_1 \leq v \leq v_s + 1\} \cap \{r = r_{\text{red}}\}) \cap \mathcal{N}$, where region $\mathcal{R}_{II}$ is given by $\mathcal{R}_{II} = \mathcal{D}^+ (\{v_1 \leq v \leq v_s\} \cap \{r = r_{\text{red}}\})$.

In the following we will apply the divergence theorem in region $\mathcal{R}_{II} \cup \tilde{\mathcal{R}}_{II}$ to obtain decay on an arbitrary $r = \tilde{r}$ hypersurface, dash-dotted line, for $\tilde{r} \in [r_{\text{blue}}, r_{\text{red}})$, from the derived decay on the $r = r_{\text{red}}$ hypersurface.

$$\int_{\mathcal{R}_{II} \cup \tilde{\mathcal{R}}_{II}} K^{-\partial_r} (\phi) d\text{Vol} + \int_{\{r_{\text{blue}} \leq r \leq r_{\text{red}}\}} J_\mu^{-\partial_r} (\phi) n_{\mu}^{r=u_{\text{blue}} (v_s)} d\text{Vol}_{r=u_{\text{blue}} (v_s)}$$

$$+ \int_{\{v_s \leq v \leq v_s + 1\}} J_\mu^{-\partial_r} (\phi) n_{\mu}^{r=r_{\text{blue}}} d\text{Vol}_{r=r_{\text{blue}}} + \int_{\{r_{\text{blue}} \leq r \leq r_{\text{red}}\}} J_\mu^{-\partial_r} (\phi) n_{\mu}^{v=v_s + 1} d\text{Vol}_{v=v_s + 1}$$

$$= \int_{\{v_1 \leq v \leq v_s + 1\}} J_\mu^{-\partial_r} (\phi) n_{\mu}^{r=r_{\text{red}}} d\text{Vol}_{r=r_{\text{red}}}.$$
Fig. 9. Region $\mathcal{R}_{II} \cup \tilde{\mathcal{R}}_{II}$ represented as the hatched area

The second integral of the left hand side represents the current through the $u = u_{\text{blue}}(v_*)$ hypersurface, defined by (40). As $u = u_{\text{blue}}(v_*)$ is a null hypersurface and $-\partial r$ is timelike, the positivity of that second term is immediate. Similarly, the fourth term of the left hand side of our equation is positive and we obtain

$$\int \left\{ v_* \leq v \leq v_* + 1 \right\} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}_{r=r_{\text{blue}}} \leq \int_{\mathcal{R}_{II} \cup \tilde{\mathcal{R}}_{II}} |K^{-\partial r}(\phi)| \, d\text{Vol}$$

$$+ \int \left\{ v_{1} \leq v \leq v_* + 1 \right\} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}_{r=r_{\text{red}}}.$$  

Further, we use that the deformation $K^{-\partial r}$ is controlled by the energy associated to the timelike vector field $-\partial r$ as stated in (72). Thus we obtain

$$\int \left\{ v_* \leq v \leq v_* + 1 \right\} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}_{r=r_{\text{blue}}} \leq B_1 \int_{\mathcal{R}_{II} \cup \tilde{\mathcal{R}}_{II}} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}$$

$$+ \int \left\{ v_{1} \leq v \leq v_* + 1 \right\} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}_{r=r_{\text{red}}}.$$  

By the coarea formula we obtain

$$\int \left\{ v_* \leq v \leq v_* + 1 \right\} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}_{r=r_{\text{blue}}} \leq \tilde{B}_1 \int_{r_{\text{blue}}}^{r_{\text{red}}} \int_{r(\tilde{r}, v_* \leq v \leq v_* + 1)} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}_{r=\tilde{r}} \, d\tilde{r}$$

$$+ \int \left\{ v_{1} \leq v \leq v_* + 1 \right\} J_{\mu}^{-\partial r}(\phi)n_r^\mu \, d\text{Vol}_{r=r_{\text{red}}}.$$  

\[(74)\]
Now let
\[
E(\phi; \tilde{r}, \tilde{v}) = \int_{\{\tilde{v} \leq v \leq v_{*} + 1\}} J_{\mu}^{-\partial_{r}}(\phi) n_{r=r}^{\mu} d\text{Vol}_{r=r},
\] (76)

with \(\tilde{r} \in [r_{\text{blue}}, r_{\text{red}}]\). Replacing \(r_{\text{blue}}\) with \(\tilde{r}\) in the above, considering the future domain of dependence of \(\{v_{1} \leq v \leq v_{*} + 1\} \cap \{r = r_{\text{red}}\}\) up to the \(r = \tilde{r}\) hypersurface we obtain similarly to (75)
\[
E(\phi; \tilde{r}, v(\tilde{r}, v_{*})) \leq \tilde{B}_{1} \int_{\tilde{r}}^{r_{\text{red}}} E(\phi; \tilde{r}, v(\tilde{r}, v_{*})) d\tilde{r} + E(\phi; r_{\text{red}}, v_{1}).
\] (77)

Using Grönwall’s inequality in (77) yields
\[
E(\phi; \tilde{r}, v(\tilde{r}, v_{*})) \leq E(\phi; r_{\text{red}}, v_{1})[1 + \tilde{B}_{1}(r_{\text{red}} - \tilde{r}) e^{\tilde{B}_{1}(r_{\text{red}} - \tilde{r})}] \Rightarrow E(\phi; \tilde{r}, v(\tilde{r}, v_{*})) \leq \tilde{C} E(\phi; r_{\text{red}}, v_{1}).
\] (78)

Finally, note that
\[
[v_{*} + 1] - v(r_{\text{red}}, v_{*}) = [v_{*} + 1] - v_{1} = k < \infty,
\] (79)

where \(k = 2[r^{*}(r_{\text{blue}}) - r^{*}(r_{\text{red}})] + 1\). This can be seen since (24) and (28) yields
\[
\frac{\partial v r}{\Omega^{2}} = -\frac{\partial r^{*}}{2} \Rightarrow r^{*}(u_{\text{blue}}(v_{*}), v_{*}) - r^{*}(u_{\text{blue}}(v_{*}), v_{1}) = r^{*}(r_{\text{blue}}) - r^{*}(r_{\text{red}}) \overset{27}{=} \frac{1}{2}(v_{*} - v_{1}).
\]

Further, by using the conclusion of Proposition 4.2 and (79) we have
\[
E(\phi; r_{\text{red}}, v_{1}) = \int_{\{v_{1} \leq v \leq v_{*} + 1\}} J_{\mu}^{-\partial_{r}}(\phi) n_{r=r_{\text{red}}}^{\mu} d\text{Vol}_{r=r_{\text{red}}}
\] 
\[= \int_{\{v_{1} \leq v \leq v_{1} + k\}} J_{\mu}^{-\partial_{r}}(\phi) n_{r=r_{\text{red}}}^{\mu} d\text{Vol}_{r=r_{\text{red}}}
\] 
\[\leq C \max \{k, 1\} v_{1}^{-2 - 2\delta} \sim C v_{*}^{-2 - 2\delta}.
\] (80)

We thus infer
\[
\int_{\{v_{*} \leq v \leq v_{*} + 1\}} J_{\mu}^{-\partial_{r}}(\phi) n_{r=r}^{\mu} d\text{Vol}_{r=r} \leq \tilde{C} \int_{\{v_{1} \leq v \leq v_{*} + 1\}} J_{\mu}^{-\partial_{r}}(\phi) n_{r=r_{\text{red}}}^{\mu} d\text{Vol}_{r=r_{\text{red}}} \leq \tilde{C} C v_{*}^{-2 - 2\delta}.
\]

The above now also implies the following statement.
Corollary 4.6. Let \( \phi \) be as in Theorem 3.1, \( r_{\text{blue}} \) as in (37) and \( r_{\text{red}} \) as in Proposition 4.1. Then, for all \( v_\ast > 1 \) and all \( \tilde{u} \) such that \( r(\tilde{u}, v_\ast) \in [r_{\text{blue}}, r_{\text{red}}] \)

\[
\int_{\{v_{\text{red}}(\tilde{u}) \leq v \leq v_{\text{blue}}(\tilde{u})\}} J^N_\mu(\phi)n^\mu_{u=\tilde{u}} dVol_{u=\tilde{u}} \leq C v^*-2\cdot2^\delta, \tag{81}
\]

with \( C \) depending on \( C_0 \) of Theorem 3.1 and \( D_0(u_\ast, 1) \) of Proposition 3.2, where \( u_\ast \) is defined by \( r_{\text{red}} = r(u_\ast, 1) \) and \( v_{\text{red}}(\tilde{u}), v_{\text{blue}}(\tilde{u}) \) are as in (40).

Proof. The conclusion of the statement follows by considering the divergence theorem for a triangular region \( J^- (x) \cap N \) with \( x = (\tilde{u}, v_{\text{blue}}(\tilde{u})) \), \( x \in J^- (r = r_{\text{blue}}) \) and using the results of Proposition 4.5. Note that \( v_\ast \sim v_{\text{blue}}(\tilde{u}) \sim v_{\text{red}}(\tilde{u}) \). \( \square \)

By the previous proposition we have successfully propagated the energy estimate further inside the black hole, up to \( r = r_{\text{blue}} \). To go even further will be more difficult and we will address this in the next section.

4.1.3. Propagating through \( B \) from \( r = r_{\text{blue}} \) to the hypersurface \( \gamma \). In the following we want to propagate the estimates from the \( r = r_{\text{blue}} \) hypersurface further into the blueshift region to a hypersurface \( \gamma \) which is located a logarithmic distance in \( v \) from the \( r = r_{\text{blue}} \) hypersurface, cf. Fig. 10. We will define the hypersurface \( \gamma \) and its most basic properties in Sect. 4.1.3.1 and propagate the decay bound to \( \gamma \) in Sect. 4.1.3.2.

4.1.3.1. The hypersurface \( \gamma \). The idea of the hypersurface \( \gamma \) was already entertained in [13] by Dafermos and basically locates \( \gamma \) a logarithmic distance in \( v \) from a constant \( r \) hypersurface living in the blueshift region.

Let \( \alpha \) be a fixed constant satisfying

\[
\alpha > \frac{p + 1}{\beta}, \tag{82}
\]

with \( \beta \) as in (39) and (39). [The significance of the bound (82) will become clear later]. Let us for convenience also assume that

\[
\alpha > 1, \tag{83}
\]

and

\[
\alpha (2 - \log 2\alpha) > 2r_{\text{blue}}* + 1. \tag{84}
\]

Fig. 10. Logarithmic distance of hypersurface \( r = r_{\text{blue}} \) and hypersurface \( \gamma \) depicted in a Penrose diagram
We define the function $H(u, v)$ by
\[
H(u, v) = u + v - \alpha \log v - 2r^*(r_{\text{blue}}) = u + v - \alpha \log v - 2r_{\text{blue}}^*,
\] (85)
were $r^*(r_{\text{blue}}) = r_{\text{blue}}^*$ is the $r^*$ value evaluated at $r_{\text{blue}}$ according to (28), and $r_{\text{blue}}^* > 0$ according to the choice (38). We then define the hypersurface $\gamma$ as the levelset
\[
\gamma = \{ H(u, v) = 0 \} \cap \{ v > 2\alpha \}.
\] (86)
Since
\[
\frac{\partial H}{\partial u} = 1, \quad \frac{\partial H}{\partial v} = 1 - \frac{\alpha}{v},
\] (87)
we see that $\gamma$ is a spacelike hypersurface and terminates at $i^+$, cf. “Appendix A”. (In the notation (40), $u_\gamma(v) \to -\infty$ as $v \to \infty$.) Note that by our choices $u < -1$ and $v > |u|$ in $D^+(\gamma)$.

Recall that in Sect. 2.3.1 we have defined the Regge-Wheeler tortoise coordinate $r^*$ depending on $u, v$ by (27). Using this for $r_{\text{blue}}^*$ we have
\[
r^*(r_{\text{blue}}) = v_{\text{blue}}(u) + u^2,
\] (88)
with $v_{\text{blue}}(u)$ as in (40). Plugging this into (86) recalling $v_\gamma(u)$ defined in (40), we obtain the relation
\[
v_\gamma(u) - v_{\text{blue}}(u) = \alpha \log v_\gamma(u).
\] (89)
As we shall see in Sect. 4.1.4.1 the above properties of $\gamma$ will allow us to derive pointwise estimates of $\Omega^2$ in $J^+(\gamma) \cap B$. We first turn however to the region $J^-(\gamma) \cap B$.

4.1.3.2. Energy estimates from $r = r_{\text{blue}}$ to the hypersurface $\gamma$. Now we are ready to propagate the energy estimates further into the blueshift region $B$ up to the hypersurface $\gamma$. We will in this part of the proof use the vector field
\[
S_0 = r^q \partial_r^* = r^q (\partial_u + \partial_v),
\]
which we have defined in (44). Let us now consider the bulk term and derive positivity properties which are needed later on. Plugging (44) in (B2) of “Appendix B” yields
\[
K_{S_0} = qr^{q-1} \left[ (\partial_v \phi)^2 + (\partial_u \phi)^2 \right] - \left[ qr^{q-1} \left[ \partial_v r + \partial_u r \right] + r^q \left( \frac{\partial_u \Omega}{\Omega} + \frac{\partial_v \Omega}{\Omega} \right) \right] |\nabla \phi|^2 - 4r^{q-1} (\partial_u \phi \partial_v \phi). \tag{90}
\]
Our aim is to show that $K_{S_0}$ is positive. All terms multiplied by the angular derivatives are manifestly positive in $B$, cf. (39), (39) together with (24) to (25). Therefore, it is only left to show that the first term on the right hand side dominates the last term. Since by the Cauchy-Schwarz inequality
\[
2qr^{q-1} (\partial_u \phi \partial_v \phi) \leq qr^{q-1} [(\partial_v \phi)^2 + (\partial_u \phi)^2], \tag{91}
\]
$K_{S_0}$ is positive in $B$ for all $q \geq 2$.

We show now that at the expense of one polynomial power, we can extend the local energy estimate on $r = r_{\text{blue}}$ to an energy estimate along $\gamma$ which is valid for a dyadic length.
Proposition 4.7. Let $\phi$ be as in Theorem 3.1. Then, for all $v_*>2\alpha$

$$\int_{\{v_* \leq v \leq 2v_*\}} J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_\gamma \leq C v_*^{-1-2\delta}, \quad (92)$$

on the hypersurface $\gamma$, with $C$ depending on $C_0$ of Theorem 3.1 and $D_0(u_\circ, 1)$ of Proposition 3.2, where $u_\circ$ is defined by $r_{\text{red}} = r(u_\circ, 1)$.

Remark. $n^\mu_\gamma$ denotes the normal vector on the hypersurface $\gamma$ which is a levelset $\gamma = \{H(u, v) = 0\}$ of the function $H(u, v)$ defined in (85). For calculation of $n^\mu_\gamma$ and $J^S_\mu (\phi) n^\mu_\gamma$ refer to (A1) and (A5) of “Appendix A”.

Proof. In the following we will again make use of notation (40).

Let $v_* > 2\alpha$, such that $\gamma$ is spacelike for $v > v_*$, cf. Sect. 4.1.3.1. Define $u_3$ by $(u_3, v_*) \in \gamma$, i.e. $u_3(v_*) = u_3$ and define $v_\text{blue}$ as the intersection of $u_3$ with $r_\text{blue}$, i.e. $v_\text{blue}(u_3) = v_\text{blue}$. And similarly the hypersurfaces $u = u_1$ and $u = u_2$ as shown in Fig. 10 are given by $u_\text{blue}(2v_*) = u_1$ and $u_\gamma(2v_*) = u_2$. Having defined the relations between all these quantities we can now carry out the divergence theorem for region $\mathcal{R}_{III}$:

$$\int_{\mathcal{R}_{III}} K^S_\mu (\phi) d\text{Vol} + \int_{\{v_\text{blue} \leq v \leq v_*\}} J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_{u=\bar{u}} + \int_{\{v_* \leq v \leq 2v_*\}} J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_\gamma$$

$$+ \int_{\{u_1 \leq u \leq u_2\}} J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_{v=2v_*} = \int_{\{v_\text{blue} \leq v \leq 2v_*\}} J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_{r=r_\text{blue}}. \quad (93)$$

Positivity of the flux along the $u = u_3$ segment and the flux along the $v = 2v_*$ segment, as well as positivity of $K^S_\mu$ for the choice $q \geq 2$, which was derived in (90) and (91), leads to

$$\int_{\{v_* \leq v \leq 2v_*\}} J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_\gamma \leq \int_{\{v_\text{blue} \leq v \leq 2v_*\}} J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_{r=r_\text{blue}}$$

$$\leq C \max \{2v_* - v_\text{blue}, 1\} v_\text{blue}^{-2-2\delta} \leq C v_\delta v_*^{-1-2\delta}, \quad (89)$$

$$\leq C (v_* + \alpha \log v_*) v_\text{blue}^{-2-2\delta} \leq \tilde{C} v_*^{-1-2\delta}, \quad (94)$$

where the second step is implied by Proposition 4.5 and the last step follows from the inequality $v_* \leq C v_\text{blue}$ which is implied by (89). $\square$

We have already mentioned in the introduction that we will use the vector field $S$, cf. (45) in the region $J^S_\gamma \cap \mathcal{B}$. To control the initial flux term of $S$ we require a weighted energy estimate along the hypersurface $\gamma$.

Corollary 4.8. Let $\phi$ be as in Theorem 3.1. Then, for all $v_* > 2\alpha$

$$\int_{\{v_* \leq v < \infty\}} v^p J^S_\mu (\phi) n^\mu_\gamma d\text{Vol}_\gamma \leq C v_*^{-1-2\delta + p}, \quad (95)$$

on the hypersurface $\gamma$, with $C$ depending on $C_0$ of Theorem 3.1 and $D_0(u_\circ, 1)$ of Proposition 3.2, where $u_\circ$ is defined by $r_{\text{red}} = r(u_\circ, 1)$ and $p$ as in (46).
Proof. This follows by weighting (92) with $v_\ast^p$ and summing dyadically. ⊓⊔

Further, we can state the following.

**Corollary 4.9.** Let $\phi$ be as in Theorem 3.1, $r_{\text{blue}}$ as in (37) and $\gamma$ as in (86). Then, for all $v_\ast > 2\alpha$ and for all $\tilde{u} \in [u_{\text{blue}}(v_\ast), u_\gamma(v_\ast))$

$$
\int_{\{v_{\text{blue}}(\tilde{u}) \leq v \leq v_\gamma(\tilde{u})\}} v^p J^S_{\mu}(\phi) n_{\mu=\tilde{u}} d\text{Vol}_{u=\tilde{u}} \leq C v_\ast^{-1-2\delta+p},
$$

with $C$ depending on $C_0$ of Theorem 3.1 and $D_0(u_\omega, 1)$ of Proposition 3.2, where $u_\omega$ is defined by $r_{\text{red}} = r(u_\omega, 1)$ and $v_\gamma(\tilde{u}), v_{\text{blue}}(\tilde{u})$ as in (40).

**Proof.** The proof is similar to the proof of Corollary 4.6 by considering the divergence theorem for a triangular region $J^{-}(x) \cap B$ with $x = (\tilde{u}, v_\gamma(\tilde{u})), x \in J^{-}(\gamma)$ and using the results of the proof of Proposition 4.7. ⊓⊔

4.1.4. Propagating through $B$ from the hypersurface $\gamma$ to $\mathcal{CH}^+$ in the neighbourhood of $i^+$. In order to prove our Theorem 3.3 and close our estimates up to the Cauchy horizon in the neighbourhood of $i^+$ we are interested in considering a region $\mathcal{R}_{IV}$ within the trapped region whose boundaries are made up of the hypersurface $\gamma$, a constant $u$ and a constant $v$ segment, which can reach up to the Cauchy horizon, cf. Fig. 11.

Let $v_\ast > 2\alpha$ and let $\hat{v} > v_\ast$. We may write $\mathcal{R}_{IV} = J^+(\gamma) \cap J^-(x)$ with $x = (u_\gamma(v_\ast), \hat{v}), x \in J^+(\gamma) \cap B$. Note that $\mathcal{R}_{IV}$ lies entirely in the blueshift region, which was characterized by the fact that the quantity $M - \frac{\hat{v}^2}{r}$ takes the negative sign, cf. (39), (39) and (24) to (25).

In Sect. 4.1.4.1 we will derive pointwise estimates for $\Omega^2$ in the future of the hypersurface $\gamma$. With this estimate, the bulk term will be bounded in terms of the currents through the null hypersurfaces. Consequently, we will be able to absorb the bulk term and to show that the currents through the null hypersurfaces can be bounded by the current along the hypersurface $\gamma$, cf. Sect. 4.1.4.3.

4.1.4.1. Pointwise estimates on $\Omega^2$ in $J^+(\gamma)$. In the following we will derive pointwise estimates on $\Omega^2$ in $J^+(\gamma)$. We note that these will imply that the spacetime volume to the future of the hypersurface $\gamma$ is finite, $\text{Vol}(J^+(\gamma)) < C$.

---

**Fig. 11.** Blueshift region of Reissner-Nordström spacetime from hypersurface $\gamma$ onwards
We first derive a future decay bound along a constant \( u \) hypersurface for the function \( \Omega^2(u, v) \) for \( (u, v) \in \mathcal{B} \). Let \( x = (u_{\text{fix}}, v_{\text{fix}}), x \in \mathcal{B} \), then, from (25) we can immediately see that

\[
\log \left( \frac{\Omega^2(u_{\text{fix}}, v)}{\Omega^2(u, v)} \right) \bigg|_{v_{\text{fix}}} = \int_{v_{\text{fix}}}^{\tilde{v}} \left( M - \frac{e^2}{r} \right) dv \leq -\beta [\tilde{v} - v_{\text{fix}}]. \tag{39}
\]

It then immediately follows that

\[
\Omega^2(\bar{u}, \tilde{v}) \leq \Omega^2(\bar{u}, v_{\text{fix}}) e^{-\beta [\tilde{v} - v_{\text{fix}}]}, \quad \text{for all } (\bar{u}, v_{\text{fix}}) \in \mathcal{B} \text{ and } \tilde{v} > v_{\text{fix}}. \tag{98}
\]

Analogously, we obtain

\[
\Omega^2(\bar{u}, v_{\text{fix}}) \leq \Omega^2(u_{\text{fix}}, v_{\text{fix}}) e^{-\beta [\bar{u} - u_{\text{fix}}]}, \quad \text{for all } (\bar{u}, v_{\text{fix}}) \in J^+(x), \tag{99}
\]

and plugging (98) into (99) it yields

\[
\Omega^2(\bar{u}, \tilde{v}) \leq \Omega^2(u_{\text{fix}}, v_{\text{fix}}) e^{-\beta [\bar{u} - u_{\text{fix}} + \tilde{v} - v_{\text{fix}}]}, \quad \text{for all } (\bar{u}, \tilde{v}) \in J^+(x). \tag{100}
\]

From (98) and (89) we obtain a relation for \( \Omega^2(u, v) \) on the hypersurface \( \gamma \) as follows

\[
\Omega^2(\bar{u}, \tilde{v}) \leq \Omega^2(\bar{u}, v_{\gamma}(\bar{u})) e^{-\beta \alpha \log v_{\gamma}(\bar{u})} = \Omega^2(\bar{u}, v_{\text{blue}}(\bar{u})) v_{\gamma}(\bar{u})^{-\beta \alpha}, \quad \text{for } (\bar{u}, \tilde{v}) \in \gamma. \tag{101}
\]

For \( J^+(\gamma) \), using (98) we further get

\[
\Omega^2(\bar{u}, \tilde{v}) \leq C v_{\gamma}(\bar{u})^{-\beta \alpha} e^{-\beta [\tilde{v} - v_{\gamma}(\bar{u})]}, \quad \text{for } (\bar{u}, \tilde{v}) \in J^+(\gamma), \tag{102}
\]

where we have used \( \Omega^2(\bar{u}, v_{\text{blue}}(\bar{u})) \leq C \). Moreover, we may think of a parameter \( \tilde{v} \) which determines the associated \( u \) value via intersection with \( \gamma \), we denote this value by the evaluation the function \( u_{\gamma}(\tilde{v}) \) which was introduced in (40), cf. Fig. 6b).

Moreover, by (25) we can also state

\[
\Omega^2(\bar{u}, \tilde{v}) \leq C |u_{\gamma}(\tilde{v})|^{-\beta \alpha} e^{\beta [u_{\gamma}(\tilde{v}) - \bar{u}]} \quad \text{for } (\bar{u}, \tilde{v}) \in J^+(\gamma). \tag{103}
\]

Note that the choice (82) of \( \alpha \) implies that \( \beta \alpha > 1 \). From (103), the fact that \( |u_{\gamma}(\tilde{v})| \sim \tilde{v} \), and the extra exponential factor, finiteness of the spacetime volume to the future of \( \gamma \) follows,

\[
\text{Vol}(J^+(\gamma)) < C. \tag{104}
\]

See also [27].
4.1.4.2. Bounding the bulk term \( K^S \). To derive energy estimates in \( \mathcal{R}_{IV} \) we use the timelike vector field multiplier

\[ S = |u|^p \partial_u + v^p \partial_v, \]

which we have given before in (45). The weights of \( S \) are chosen such that they will allow us to derive pointwise estimates from energy estimates; see Sect. 4.2.3.

In order to obtain our desired estimates first of all we need a bound on the scalar current \( K^S \), in terms of \( J^S_\mu(\phi) n^\mu_{v=\bar{v}} \) and \( J^S_\mu(\phi) n^\mu_{u=\bar{u}} \). In the following we will bound the occurring \((u,v)\)-dependent weight functions by functions that depend on either \( u \) or \( v \), respectively. Plugging the vector field \( S \), cf. (45), into (B2) of “Appendix B” we obtain

\[
K^S = -\frac{2}{r} \left[ v^p + |u|^p \right] (\partial_u \Omega |u|^p + \partial_v \Omega v^p + \frac{p}{2} (v^{p-1} + |u|^{p-1}) |\nabla \phi|^2.
\]

(105)

Recall (39) and (39). For large absolute values of \( v \) and \( u \) the first two terms multiplying the angular derivatives of \( \phi \) dominate the last two terms, so in total the term multiplying the angular derivatives is always positive in \( D^+(\gamma) \). Consequently we will be able to use this property to derive an inequality by using the divergence theorem in the proof of Proposition 4.11. Let us therefore define

\[
\tilde{K}^S = -\frac{2}{r} \left[ v^p + |u|^p \right] (\partial_u \phi \partial_v \phi),
\]

and state

\[
- K^S \leq |\tilde{K}^S| \quad \text{for} \quad v > \frac{p}{\bar{z}_p} \quad \text{and} \quad |u| > \frac{p}{\bar{z}_p}, \quad \text{cf. (39)}.
\]

(107)

(Note that \( \tilde{K}^S \) coincides with the bulk term for spherically symmetric \( \phi \).) We have the following

**Lemma 4.10.** Let \( \phi \) be an arbitrary function. Then, for all \( v_* > 2\alpha \) and all \( \hat{v} > v_* \), the integral over region \( \mathcal{R}_{IV} = J^+(\gamma) \cap J^-(x) \) with \( x = (u_x(v_*), \hat{v}) \), \( x \in B \), cf. Fig. 11, of the current \( \tilde{K}^S \), defined by (106), can be estimated by

\[
\int_{\mathcal{R}_{IV}} |\tilde{K}^S| d\text{Vol} \leq \delta_1 \sup_{u_x(\hat{v}) \leq \tilde{u} \leq u_x(v_*)} \int \limits_{\{v_x(\tilde{u}) \leq v \leq \hat{v} \}} J^S_\mu(\phi) n^\mu_{u=x} d\text{Vol}_{u=x} + \delta_2 \sup_{v_* \leq \bar{v} \leq \hat{v}} \int \limits_{\{v_x(\bar{v}) \leq u \leq u_x(\bar{v}) \}} J^S_\mu(\phi) n^\mu_{v=\bar{v}} d\text{Vol}_{v=\bar{v}},
\]

where \( \delta_1 \) and \( \delta_2 \) are positive constants, with \( \delta_1 \to 0 \) and \( \delta_2 \to 0 \) as \( v_* \to \infty \).

**Remark.** In the proof of Proposition 4.11 we will see that the above proposition determines \( u_{x_0} \) of Theorem 3.3, depicted in Fig. 7b). We have to choose \( u_{x_0} = u_x(v_*) \), with \( v_* \) such that \( \delta_1 \) is small.
Proof. Using the Cauchy-Schwarz inequality twice for the remaining part of the bulk term we obtain

$$|\tilde{K}^S| \leq \frac{1}{r} \left[ \left( 1 + \frac{|u|^p}{v^p} \right) v^p (\partial_v \phi)^2 + \left( 1 + \frac{v^p}{|u|^p} \right) |u|^p (\partial_u \phi)^2 \right],$$  \hspace{1cm} (108)$$

with the related volume element

$$\text{dVol} = r^2 \frac{\Omega^2}{2} \text{d}u \text{d}v \text{d}\sigma_\Sigma^2.$$  \hspace{1cm} (109)$$

Note that the currents related to the vector field $S$ with their related volume elements are given by

$$J^S_\mu(\phi)n^\mu_{v=\bar{v}} = \frac{2}{\Omega^2} \left[ |u|^p (\partial_u \phi)^2 + \frac{\Omega^2}{4} \tilde{v}^p |\nabla \phi|^2 \right], \quad \text{dVol}_{v=\bar{v}} = r^2 \frac{\Omega^2}{2} \text{d}\sigma_\Sigma^2 \text{d}u,$$  \hspace{1cm} (110)$$

$$J^S_\mu(\phi)n^\mu_{u=\bar{u}} = \frac{2}{\Omega^2} \left[ v^p (\partial_v \phi)^2 + \frac{\Omega^2}{4} |\tilde{u}|^p |\nabla \phi|^2 \right], \quad \text{dVol}_{u=\bar{u}} = r^2 \frac{\Omega^2}{2} \text{d}\sigma_\Sigma^2 \text{d}v,$$  \hspace{1cm} (111)$$

cf. “Appendix A”. Taking the integral over the spacetime region yields

$$\int_{\mathcal{K}_{IV}} |\tilde{K}^S(\phi)| \text{dVol} \leq \int_{u_y(v_a)}^{u_y(v_u)} \int_{v_y(u \leq v \leq \bar{v})} \frac{\Omega^2(\bar{u}, \bar{v})}{2r} \left( 1 + \frac{|\tilde{u}|^p}{\bar{v}^p} \right) J^S_\mu(\phi)n^\mu_{u=\bar{u}} \text{dVol}_{u=\bar{u}} \text{d}\tilde{u}$$

$$+ \int_{v_y(u \leq u \leq u_y(v_u))} \int_{\bar{v}}^{\tilde{v}} \frac{\Omega^2(\bar{u}, \bar{v})}{2r} \left( 1 + \frac{\bar{v}^p}{|\tilde{u}|^p} \right) J^S_\mu(\phi)n^\mu_{v=\bar{v}} \text{dVol}_{v=\bar{v}} \text{d}\tilde{v},$$  \hspace{1cm} (112)$$

with $u_y(v)$ and $v_y(\bar{u})$ in the integration limits as defined in (40).

Note the following general relation for positive functions $f(\bar{u}, \bar{v})$ and $g(\bar{u}, \bar{v})$

$$\int_{u_y(v_u)}^{u_y(v_a)} \int_{\bar{u}}^{\tilde{v}} f(\bar{u}, \bar{v}) g(\bar{u}, \bar{v}) \text{d}\bar{v} \text{d}\tilde{u} \leq \int_{u_y(v_u)}^{u_y(v_a)} \int_{v_y(\bar{u} \leq \bar{v} \leq \tilde{v})} \sup_{v_y(\bar{u} \leq \bar{v} \leq \tilde{v})} f(\bar{u}, \bar{v}) \int_{\bar{u}}^{\tilde{v}} g(\bar{u}, \bar{v}) \text{d}\tilde{v} \text{d}\bar{v},$$

$$\leq \int_{u_y(v_u)}^{u_y(v_a)} \left[ \sup_{v_y(\bar{u} \leq \bar{v} \leq \tilde{v})} f(\bar{u}, \bar{v}) \right] \int_{\bar{u}}^{\tilde{v}} g(\bar{u}, \bar{v}) \text{d}\tilde{v} \text{d}\bar{v},$$

$$\leq \int_{u_y(v_u)}^{u_y(v_a)} \sup_{v_y(\bar{u} \leq \bar{v} \leq \tilde{v})} f(\bar{u}, \bar{v}) \text{d}\bar{v} \sup_{u_y(v_u) \leq u_y(v_a)} \int_{\tilde{v}}^{\tilde{v}} g(\bar{u}, \bar{v}) \text{d}\tilde{v} \text{d}\bar{v},$$

$$\leq \int_{u_y(v_u)}^{u_y(v_a)} \sup_{v_y(\bar{u} \leq \bar{v} \leq \tilde{v})} f(\bar{u}, \bar{v}) \text{d}\bar{v} \sup_{u_y(v_u) \leq u_y(v_a)} \int_{u_y(v_u) \leq u_y(v_a)} g(\bar{u}, \bar{v}) \text{d}\tilde{v} \text{d}\bar{v},$$  \hspace{1cm} (113)$$
Similarly, it immediately follows that
\[
\int_{v_*}^{u_y(v_*)} \int_{u_y(v)} f(\tilde{u}, \tilde{v}) g(\tilde{u}, \tilde{v}) d\tilde{u} d\tilde{v} \leq \int_{v_*}^{u_y(v_*)} \sup_{u_y(v) \leq \tilde{u} \leq u_y(v_*)} f(\tilde{u}, \tilde{v}) d\tilde{v} \sup_{v_* \leq \tilde{v} \leq \tilde{t}} \int g(\tilde{u}, \tilde{v}) d\tilde{u}.
\]

(113)

Using (113) and (114) in (112) we obtain
\[
\int_{\mathcal{R}_{IV}} |\tilde{K}^S(\phi)| d\mathcal{V} \leq \int_{u_y(v_*)}^{u_y(v_*)} \sup_{u_y(v) \leq \tilde{u} \leq \tilde{t}} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} \left( 1 + \frac{|\tilde{u}|^p}{\tilde{v}^p} \right) \right] d\tilde{u} \sup_{u_y(v) \leq \tilde{u} \leq u_y(v_*)} \int J_\mu^S(\phi) n^\mu_{\tilde{u} = \tilde{u}} d\mathcal{V}_{\tilde{u} = \tilde{u}}
\]
\[
\times \int_{\{u_y(v) \leq \tilde{u} \leq u_y(v_*)\}} \sup_{v_* \leq \tilde{v} \leq \tilde{t}} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} \left( 1 + \frac{\tilde{v}^p}{|\tilde{u}|^p} \right) \right] d\tilde{v} \sup_{u_y(v) \leq \tilde{u} \leq u_y(v_*)} \int J_\mu^S(\phi) n^\mu_{\tilde{v} = \tilde{v}} d\mathcal{V}_{\tilde{v} = \tilde{v}}.
\]

(114)

It remains to show finiteness and smallness of
\[
\int u_y(v_*) \sup_{v_*/u_y(v) \leq \tilde{u} \leq \tilde{v}} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} \left( 1 + \frac{|\tilde{u}|^p}{\tilde{v}^p} \right) \right] d\tilde{u}
\]
and
\[
\int v_* \sup_{u_y(v) \leq \tilde{u} \leq u_y(v_*)} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} \left( 1 + \frac{\tilde{v}^p}{|\tilde{u}|^p} \right) \right] d\tilde{v}.
\]

Earlier we obtained the relation (103) for \(\Omega^2\) in region \(\mathcal{R}_{IV}\). Therefore, we can write
\[
\int u_y(v_*) \sup_{v_*/u_y(v) \leq \tilde{u} \leq \tilde{v}} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} \left( 1 + \frac{|\tilde{u}|^p}{\tilde{v}^p} \right) \right] d\tilde{u} \leq C \int u_y(v_*) \sup_{u_y(v) \leq \tilde{u} \leq \tilde{v}} \left[ |u_y(v)|^{-\beta \alpha} e^{\beta [u_y(v) - \tilde{u}]} \left( 1 + \frac{|\tilde{u}|^p}{\tilde{v}^p} \right) \right] d\tilde{u}
\]
\[
\leq \tilde{C} \int \left[ |\tilde{u}|^{-\beta \alpha} \left( 1 + \frac{|\tilde{u}|^p}{\tilde{v}^p} \right) \right] d\tilde{u} \leq \tilde{C} \int \left[ \tilde{u}^{-\beta \alpha + p} e^\gamma \right] d\tilde{u} \leq \tilde{C} \int \left[ \tilde{u}^{-\beta \alpha + p+1} \right] d\tilde{u} \leq \delta_1,
\]

(116)

where \(\delta_1 \to 0\) for \(|u_y(v_*)| \to -\infty\) and thus for \(v_* \to \infty\). Note that we have here used (82).
For finiteness of the second term in (115) we follow the same strategy and use (102) for the second term to obtain

\[
\int \hat{v} \sup_{v_\gamma (\hat{v}) \leq \hat{u} \leq u_\gamma (v_\gamma)} \left[ \frac{\Omega^2 (\hat{u}, \hat{v})}{2r} \left( 1 + \frac{\hat{v}^p}{|\hat{u}|^p} \right) \right] d\hat{v} \leq C \int \hat{v} \sup_{v_\gamma (\hat{v}) \leq \hat{u} \leq u_\gamma (v_\gamma)} \left[ \frac{\hat{v}^{-\beta \alpha}}{1 + \frac{\hat{v}^p}{|\hat{u}|^p}} \right] d\hat{v} \leq \tilde{C} \int \hat{v} \frac{\hat{v} - \beta \alpha}{1 + \frac{\hat{v}^p}{|\hat{u}|^p}} \leq \delta_2,
\]

where \( \delta_2 \to 0 \) for \( v_* \to \infty \). Therefore, we obtain the statement of Lemma 4.10. \( \square \)

4.1.4.3. Energy estimates from \( \gamma \) up to \( \mathcal{CH}^+ \) in the neighbourhood of \( i^+ \). Now we come to the actual proof of weighted energy boundedness up to the Cauchy horizon.

**Proposition 4.11.** Let \( \phi \) be as in Theorem 3.1 and \( p \) as in (46). Then, for \( u_\infty \) sufficiently close to \( -\infty \), for all \( v_* \geq v_\gamma (u_\infty) \) and \( \hat{v} > v_* \)

\[
\int_{\{u_\gamma (\hat{v}) \leq \hat{u} \leq u_\gamma (v_\gamma)\}} J^S_\mu (\phi) n^\mu_{\gamma} d\text{Vol}_{\gamma} + \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu (\phi) n^\mu_{\gamma} d\text{Vol}_{\gamma} \leq C v_*^{-1 - 2\delta + p},
\]

where \( C \) is a positive constant depending on \( C_0 \) of Theorem 3.1 and \( D_0 (u_\infty, 1) \) of Proposition 3.2, where \( u_\infty \) is defined by \( r_{\text{red}} = r (u_\infty, 1) \).

**Remark.** Refer to (40) for the definition of \( u_\gamma (v) \) and see Fig. 6b) for further clarification.

**Proof.** In Sect. 4.1.3, Corollary 4.8, we have obtained the global estimate (95) for the weighted \( S_0 \) current which follows from Proposition 4.7. Recall that in \( D^+(\gamma) \) we have \( |u|^p \leq v^p \), cf. Sect. 4.1.3.1, which immediately leads to

\[
\int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu (\phi) n^\mu_{\gamma} d\text{Vol}_{\gamma} \leq \hat{C} \int_{\{v_* \leq v \leq \hat{v}\}} v^p J^S_\mu (\phi) n^\mu_{\gamma} d\text{Vol}_{\gamma},
\]

cf. “Appendix B” for explicit expressions of \( J^S_\mu (\phi) n^\mu_{\gamma} \) and \( J^S_\mu (\phi) n^\mu_{\gamma} \). From (119) we see that

\[
\int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu (\phi) n^\mu_{\gamma} d\text{Vol}_{\gamma} \leq C v_*^{-1 - 2\delta + p} \text{ for all } v_* > \alpha \text{ and } p \text{ as in (46)},
\]

is implied by Corollary 4.8.
Let \( v_* > 2\alpha \) and \( \hat{v} > v_* \). In order to obtain (118) we consider a region \( \mathcal{R}_{IV} = J^+(\gamma) \cap J^-(x) \) with \( x = (u_\gamma(v_\gamma), \hat{v}) \), \( x \in \mathcal{B} \), as shown in Fig. 11. Applying the divergence theorem we obtain

\[
\int_{\mathcal{R}_{IV}^V} K^S(\phi) \, d\text{Vol} + \int_{\{u_\gamma(\hat{v}) \leq u \leq u_\gamma(v_*)\}} J^S_\mu(\phi) n^\mu_{u=v=\hat{v}} \, d\text{Vol}_{u=v=\hat{v}} \]

\[+ \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{u=u_\gamma(v_*)} \, d\text{Vol}_{u=u_\gamma(v_*)} \]

\[= \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{\gamma} \, d\text{Vol}_{\gamma}. \tag{121}\]

In Sect. 4.1.4.2 we found that the angular part of \( K^S(\phi) \) is positive in \( \mathcal{R}_{IV}^V \) and we called the remaining part \( \tilde{K}^S(\phi) \) given in (106). Using (107) we can therefore write

\[
\int_{\{u_\gamma(\hat{v}) \leq u \leq u_\gamma(v_*)\}} J^S_\mu(\phi) n^\mu_{u=v=\hat{v}} \, d\text{Vol}_{u=v=\hat{v}} \]

\[+ \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{u=u_\gamma(v_*)} \, d\text{Vol}_{u=u_\gamma(v_*)} \]

\[\leq \int_{\mathcal{R}_{IV}^V} |\tilde{K}^S(\phi)| \, d\text{Vol} + \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{\gamma} \, d\text{Vol}_{\gamma}. \tag{122}\]

Using Lemma 4.10 we obtain

\[
\int_{\{u_\gamma(\hat{v}) \leq u \leq u_\gamma(v_*)\}} J^S_\mu(\phi) n^\mu_{u=v=\hat{v}} \, d\text{Vol}_{u=v=\hat{v}} \]

\[+ \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{u=u_\gamma(v_*)} \, d\text{Vol}_{u=u_\gamma(v_*)} \]

\[\leq \delta_1 \sup_{u_\gamma(\hat{v}) \leq \bar{u} \leq u_\gamma(v_*)} \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{u=\bar{u}} \, d\text{Vol}_{u=\bar{u}} \]

\[+ \delta_2 \sup_{v_* \leq \bar{v} \leq \hat{v}} \int_{\{u_\gamma(\hat{v}) \leq u \leq u_\gamma(\bar{v})\}} J^S_\mu(\phi) n^\mu_{v=v=\bar{v}} \, d\text{Vol}_{v=v=\bar{v}} + \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{\gamma} \, d\text{Vol}_{\gamma}. \tag{123}\]

Repeating estimate (123) with \( \bar{u}, \bar{v} \) in place of \( u_\gamma(v_\gamma), \hat{v} \) and taking the supremum we have

\[
\sup_{u_\gamma(\hat{v}) \leq \bar{u} \leq u_\gamma(v_*)} \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{u=\bar{u}} \, d\text{Vol}_{u=\bar{u}} \]

\[+ \sup_{v_* \leq \bar{v} \leq \hat{v}} \int_{\{u_\gamma(\hat{v}) \leq u \leq u_\gamma(\bar{v})\}} J^S_\mu(\phi) n^\mu_{v=v=\bar{v}} \, d\text{Vol}_{v=v=\bar{v}} \]

\[\leq \delta_1 \sup_{u_\gamma(\hat{v}) \leq \bar{u} \leq u_\gamma(v_*)} \int_{\{v_* \leq v \leq \hat{v}\}} J^S_\mu(\phi) n^\mu_{u=\bar{u}} \, d\text{Vol}_{u=\bar{u}} \]
Recalling \( \delta_1 \to 0, \delta_2 \to 0 \) as \( v_* \to \infty \), choose \( u \) sufficiently close to \(-\infty\), such that for \( v_* > v_\gamma(u_\infty) \), say

\[
\delta_1, \delta_2 \leq \frac{1}{2}
\] (125)

holds. The conclusion of Proposition 4.11 then follows by absorbing the first two terms of the right hand side of (124) by the two terms on the left and estimating the third from (120). \( \square \)

4.1.4.4. Energy estimates globally in the rectangle \( \Xi \) up to \( CH^+ \) in the neighbourhood of \( i^+ \). In the previous Sects. 4.1.1 to 4.1.4.3 we have proven energy estimates for each region with specific properties separately. Putting all results together we can state the following proposition.

**Proposition 4.12.** Let \( \phi \) be as in Theorem 3.1 and \( p \) as in (46). Then, for \( u_\infty \) sufficiently close to \(-\infty\), for all \( v_* > 1, \hat{v} > v_* \) and \( \tilde{u} \in (-\infty, u_\infty) \),

\[
\int_{\{v_* \leq v \leq \hat{v}\}} J^S_{\mu}(\phi)n_{\mu} u = \tilde{u} dVol_u = \tilde{u} \leq C v_*^{-1-2\delta + p},
\] (126)

where \( C \) is a positive constant depending on \( C_0 \) of Theorem 3.1 and \( D_0(u_\circ, 1) \) of Proposition 3.2, where \( u_\circ \) is defined by \( r_{\text{red}} = r(u_\circ, 1) \).

**Proof.** First of all we partition the integral of the statement into a sum of integrals of the different regions. That is to say

\[
\int_{\{v_* \leq v \leq \hat{v}\}} J^S_{\mu}(\phi)n_{\mu} u = \tilde{u} dVol_u = \tilde{u} = \int_{\{v_* \leq v \leq \hat{v}\} \cap \mathcal{R}} J^S_{\mu}(\phi)n_{\mu} u = \tilde{u} dVol_u = \tilde{u} + \int_{\{v_* \leq v \leq \hat{v}\} \cap \mathcal{N}} J^S_{\mu}(\phi)n_{\mu} u = \tilde{u} dVol_u = \tilde{u} + \int_{\{v_* \leq v \leq \hat{v}\} \cap J^-(\gamma) \cap \mathcal{B}} J^S_{\mu}(\phi)n_{\mu} u = \tilde{u} dVol_u = \tilde{u} + \int_{\{v_* \leq v \leq \hat{v}\} \cap J^+(\gamma) \cap \mathcal{B}} J^S_{\mu}(\phi)n_{\mu} u = \tilde{u} dVol_u = \tilde{u}.
\]

For the integral in \( \mathcal{R} \) and the integral in \( \mathcal{N} \) we use Corollaries 4.4 and 4.6. (Note that the former has to be summed resulting in the loss of one polynomial power). Further, for the integral in region \( J^-(\gamma) \cap \mathcal{B} \) we apply Corollary 4.9 and for the integral in region
$J^+(\gamma) \cap B$ we use Proposition 4.11. Putting all this together we arrive at the conclusion of Proposition 4.12. □

In particular, we have

**Corollary 4.13.** Let $\phi$ be as in Theorem 3.1 and $p$ as in (46). Then, for $u_\infty$ sufficiently close to $-\infty$, for all $v_{\text{fix}} \geq 1$, and $\tilde{u} \in (-\infty, u_\infty)$,

$$
\int_s^\infty \int_{v_{\text{fix}}}^{\tilde{v}} \left[ v^p (\partial_v \phi)^2 (\tilde{u}, v) + \Omega^2 |\nabla \phi|^2 (\tilde{u}, v) \right] r^2 dv d\sigma_{S^2} \leq C,
$$

where $C$ is a positive constant dependent on $C_0$ of Theorem 3.1 and $D_0(u_\circ, 1)$ of Proposition 3.2, where $u_\circ$ is defined by $r_{\text{red}} = r(u_\circ, 1)$.

**Proof.** The conclusion of the proposition follows immediately examining the weights in Proposition 4.12. □

### 4.2. Pointwise estimates from higher order energies

#### 4.2.1. The $\Box$ notation and Sobolev inequality on spheres

Recall that we had stated the expressions for the generators of spherical symmetry $\Box_i$, $i = 1, 2, 3$, in Sect. 2.3.2. They were explicitly given in (32). Further, having the expressions of (33) in mind we introduce the following notation

$$
(\Box^k_i \phi)^2 = \sum (\Box_{i_1} \cdots \Box_{i_k} \phi)^2, \quad (\Box_v \Box^k_i \phi)^2 = \sum |\nabla \Box_{i_1} \cdots \Box_{i_k} \phi|^2,
$$

with $i_j = 1, 2$ or $3$. By Sobolev embedding on the standard spheres we have in this notation

$$
\sup_{[\theta, \varphi]} |\phi(u, v, \theta, \varphi)|^2 \leq \tilde{C} \sum_{k=0}^{2} \int_{S^2} (\Box^k_i \phi)^2 (u, v, \theta, \varphi) d\sigma_{S^2},
$$

which means that we can derive a pointwise estimate from an estimate of the integrals on the spheres, see e.g. [16].

#### 4.2.2. Higher order energy estimates in the neighbourhood of $i^+$

We will need the following extension of Corollary 4.13 for higher order energies.

**Theorem 4.14.** Let $\phi$ be as in Theorem 3.1 and $p$ as in (46). Then, for $v_{\text{fix}} \geq 1$ and $u_{\text{fix}} > -\infty$

$$
\int_s^\infty \int_{v_{\text{fix}}}^{\tilde{v}} \left[ v^p (\partial_v \Box^k_i \phi)^2 (u_{\text{fix}}, v, \theta, \varphi) + \Omega^2 |\nabla \Box^k_i \phi|^2 (u_{\text{fix}}, v, \theta, \varphi) \right] r^2 dv d\sigma_{S^2} \leq E_k,
$$

for all $k \in \mathbb{N}^0$. (130)
Proof. Statement (130) with \( k = 0 \) was already derived in Corollary 4.13. Recall that \( \partial_t \phi, \partial_i \partial_j \phi \) etc. also satisfy the massless scalar wave equation, cf. Sect. 2.1. Summing over all angular momentum operators, keeping in mind notation (128), we therefore obtain (130) for all \( k \in \mathbb{N}_0 \). \( \square \)

4.2.3. Pointwise boundedness in the neighbourhood of \( i^+ \). We turn the discussion to the derivation of pointwise boundedness from energy estimates. In particular we prove Theorem 3.3 from Theorem 4.14 applied with \( k = 0, 1, 2 \).

By the fundamental theorem of calculus it follows for all \( v_* > 1, \hat{v} > v_* \) and \( u \in (-\infty, u_\infty) \) that

\[
\phi(u, \hat{v}, \theta, \varphi) = \int_{v_*}^{\hat{v}} (\partial_v \phi)(u, v, \theta, \varphi) dv + \phi(u, v_*, \theta, \varphi)
\]

\[
\leq \int_{v_*}^{\hat{v}} (\partial_v \phi)(u, v, \theta, \varphi) v^p v^{-\frac{p}{2}} dv + \phi(u, v_*, \theta, \varphi)
\]

\[
\leq \left( \int_{v_*}^{\hat{v}} v^p (\partial_v \phi)^2(u, v, \theta, \varphi) dv \right)^{\frac{1}{2}} \left( \int_{v_*}^{\hat{v}} v^{-p} dv \right)^{\frac{1}{2}} + \phi(u, v_*, \theta, \varphi),
\]

where we have used the Cauchy-Schwarz inequality in the last step. Squaring the entire expression, using Cauchy-Schwarz again and integrating over \( \mathbb{S}^2 \) we obtain the expression that we had sketched in Sect. 3.2 already

\[
\int_{\mathbb{S}^2} \phi^2(u, \hat{v}) d\sigma_{\mathbb{S}^2} \leq \tilde{C} \left[ \int_{\mathbb{S}^2} \left( \int_{v_*}^{\hat{v}} v^p (\partial_v \phi)^2(u, v, \theta, \varphi) dv \right) r^2 d\sigma_{\mathbb{S}^2} + \int_{\mathbb{S}^2} \phi^2(u, v_*) d\sigma_{\mathbb{S}^2} \right],
\]

with \( p \) as in (46) and the first term on the right hand side controlled by the flux for which we derived boundedness in Sect. 4.1.4. Therefore, by using Theorem 4.14 and applying all our estimates to \( \partial_t \phi, \partial_i \partial_j \phi \) etc. and summing, we obtain in the notation of Sect. 4.2.1 the following:

\[
\int_{\mathbb{S}^2} (\partial^k \phi)^2(u, \hat{v}) d\sigma_{\mathbb{S}^2} \leq \tilde{C} \left[ E_k \int_{\mathbb{S}^2} \int_{v_*}^{\hat{v}} v^{-p} dv d\sigma_{\mathbb{S}^2} + \int_{\mathbb{S}^2} (\partial^k \phi)^2(u, v_*) d\sigma_{\mathbb{S}^2} \right]
\]

\[
\leq \tilde{C} \left[ \tilde{C} E_k + \int_{\mathbb{S}^2} (\partial^k \phi)^2(u, v_*) d\sigma_{\mathbb{S}^2} \right],
\]

for all \( k \in \mathbb{N}_0 \). It is here that we have used the requirement \( p > 1 \) of (46).
Let us now use (43) of Proposition 3.2 to estimate the right hand side of (133) with \(v_* = 1\). Adding all equations up we derive pointwise boundedness according to (129)

\[
\sup_{\{\theta, \phi\} \in S^2} |\phi(u, \hat{v}, \theta, \phi)| \leq \tilde{C} \left[ \int_{S^2} (\phi)^2(u, \hat{v})d\sigma_{S^2} + \int_{S^2} (\tilde{\phi})^2(u, \hat{v})d\sigma_{S^2} \right. \\
\left. + \int_{S^2} (\tilde{\phi}^2\phi)^2(u, \hat{v})d\sigma_{S^2} \right],
\]

(134)

\[
\leq \tilde{C} \left[ \tilde{C} (E_0 + E_1 + E_2) + D_0(u_\phi, 1) \right. \\
\left. + D_1(u_\phi, 1) + D_2(u_\phi, 1) \right] \leq C,
\]

(135)

with \(C\) depending on the initial data on \(\Sigma_1\). We therefore arrive at the statement given in Theorem 3.3. \(\square\)

4.3. Energy along the future boundaries of \(\mathcal{R}_V\). Let \(u_\phi > u_\infty\) and \(v_* \geq v_\nu(u_\infty)\). Define \(\mathcal{R}_V = \{u_\infty \leq u \leq u_\phi\} \cap \{v_* \leq v \leq \hat{v}\}\), cf. Fig. 12, and note that \(\mathcal{R}_V \subset B\).

We will apply the vector field

\[ W = v^p \partial_v + \partial_u \]

(136)
as a multiplier. The bulk can be calculated as

\[ K^W = -\frac{2}{r} [v^p + 1](\partial_v \phi \partial_u \phi) - \left[ \frac{1}{2} p v^{p-1} + \frac{\partial_v \Omega}{\Omega} v^p + \frac{\partial_u \Omega}{\Omega} \right] |\nabla \phi|^2. \]

(137)

Let us define

\[ \tilde{K}^W = -\frac{2}{r} [v^p + 1](\partial_v \phi \partial_u \phi) \quad \text{and} \quad K^W \bar{\nabla} = -\left[ \frac{1}{2} p v^{p-1} + \frac{\partial_v \Omega}{\Omega} v^p + \frac{\partial_u \Omega}{\Omega} \right] |\bar{\nabla} \phi|^2, \]

(138)

with \(K^W \bar{\nabla}\) positive since the second term in the second equation dominates over the first for \(v_* > 2\alpha\) and \(\frac{\partial_u \Omega}{\Omega}, \frac{\partial_v \Omega}{\Omega}\) are negative in the blueshift region. We have therefore

\[ -K^W \leq |\tilde{K}^W| \]

(139)
in $\mathcal{R}_V$. We aim for estimating it via the currents along $v = \text{constant}$ and $u = \text{constant}$ hypersurfaces.

**Lemma 4.15.** Let $\phi$ be an arbitrary function. Then, for all \( v_* \geq v_\gamma(u_\infty) \), \( \hat{v} > v_* \), for \( u_\infty \geq u_2 > u_1 \geq u_\infty \) and \( \epsilon \geq u_2 - u_1 > 0 \)

\[
\int_\mathcal{R}_{V_1} |\tilde{K}^W| d\text{Vol} \leq \delta_1 \sup_{u_1 \leq \bar{u} \leq u_2} \int_{\{v_* \leq v \leq \hat{v}\}} J_{\mu}^W(\phi)n_{u=\bar{u}}^{\mu} d\text{Vol}_{u=\bar{u}} + \delta_2 \sup_{u_* \leq \bar{v} \leq \hat{v}} \int_{\{u_1 \leq u \leq u_2\}} J_{\mu}^W(\phi)n_{v=\bar{v}}^{\mu} d\text{Vol}_{v=\bar{v}},
\]

(140)

where $\mathcal{R}_{V_1} = \{u_1 \leq u \leq u_2\} \cap \mathcal{R}_V$ and $\delta_1$, $\delta_2$ are positive constants, depending only on $v_*$ and $\epsilon$ such that $\delta_1 \to 0$ for $\epsilon \to 0$ and $\delta_2 \to 0$ as $v_* \to \infty$.

**Proof.** Using the Cauchy-Schwarz inequality for the first equation of (138) we obtain

\[
|\tilde{K}^W| \leq \frac{1}{r} \left[ (1 + v^{-p}) v^p (\partial_v \phi)^2 + (1 + v^p) (\partial_u \phi)^2 \right],
\]

(141)

with the related volume element

\[
d\text{Vol} = r^2 \Omega^2 \frac{2}{\Sigma} dudvd\sigma^2_\Sigma.
\]

(142)

Note that the currents related to the vector field $W$ with their related volume elements are given by

\[
J_{\mu}^W(\phi)n_{v=\bar{v}}^{\mu} = \frac{2}{\Omega^2} \left[ (\partial_u \phi)^2 + \frac{\Omega^2}{4} \bar{v}^p |\nabla \phi|^2 \right], \quad d\text{Vol}_{v=\bar{v}} = r^2 \frac{\Omega^2}{2} d\sigma^2_\Sigma du,
\]

(143)

\[
J_{\mu}^W(\phi)n_{u=\bar{u}}^{\mu} = \frac{2}{\Omega^2} \left[ v^p (\partial_v \phi)^2 + \frac{\Omega^2}{4} |\nabla \phi|^2 \right], \quad d\text{Vol}_{u=\bar{u}} = r^2 \frac{\Omega^2}{2} d\sigma^2_\Sigma dv,
\]

(144)

cf. “Appendix A”. Taking the integral over the spacetime region therefore yields

\[
\int_{\mathcal{R}_{V_1}} |\tilde{K}^W(\phi)| d\text{Vol} \leq \int_{u_1}^{u_2} \int_{\{v_* \leq v \leq \hat{v}\}} \frac{\Omega^2(\bar{u}, \bar{v})}{2r} (1 + \bar{v}^{-p}) J_{\mu}^W(\phi)n_{u=\bar{u}}^{\mu} d\text{Vol}_{u=\bar{u}} d\bar{u} + \int_{v_*}^{\hat{v}} \int_{u_1 \leq u \leq u_2} \frac{\Omega^2(\bar{u}, \bar{v})}{2r} (1 + \bar{v}^p) J_{\mu}^W(\phi)n_{v=\bar{v}}^{\mu} d\text{Vol}_{v=\bar{v}} d\bar{u},
\]

\[
\leq \int_{u_1}^{u_2} \sup_{u_1 \leq \bar{u} \leq u_2} \left[ \frac{\Omega^2(\bar{u}, \bar{v})}{2r} (1 + \bar{v}^{-p}) \right] d\bar{u} \times \sup_{u_1 \leq \bar{u} \leq u_2} \int_{\{v_* \leq v \leq \hat{v}\}} J_{\mu}^S(\phi)n_{u=\bar{u}}^{\mu} d\text{Vol}_{u=\bar{u}}
\]
\[
+ \int_{v_+} \sup_{v_1 \leq \tilde{u} \leq v_2} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} (1 + \tilde{v}^p) \right] \, d\tilde{v}
\]

\[
\times \sup_{v_* \leq \tilde{v} \leq v_+} \left[ \int_{u_1 \leq u \leq u_2} J^S_{\mu}(\phi) n^\mu_{v_1 = v_1} d\text{Vol}_{v_1 = \tilde{v}}. \right]
\]

(145)

It remains to show finiteness and smallness of \( \int_{u_1}^{u_2} \sup_{v_* \leq \tilde{v} \leq v_+} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} (1 + \tilde{v}^p) \right] d\tilde{u} \) and

\[
\int_{v_*}^{v_+} \sup_{u_1 \leq \tilde{u} \leq u_2} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} (1 + \tilde{v}^p) \right] d\tilde{v}. \]

Recall the properties of the hypersurface \( \gamma \) shown in Sect. 4.1.3.1. Since \( v_* > v_\gamma(u_\infty) \), (103) implies that

\[
\Omega^2(\tilde{u}, \tilde{v}) \leq C \Omega^2(u_\infty, v_*), \quad \text{for any } (\tilde{u}, \tilde{v}) \in J^+(x), \quad \text{with } x = (u_\infty, v_*), \quad x \in B,
\]

so that we obtain

\[
\int_{u_1}^{u_2} \sup_{v_* \leq \tilde{v} \leq v_+} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} (1 + \tilde{v}^p) \right] d\tilde{u} \overset{(146)}{\leq} C \int_{u_1}^{u_2} \sup_{v_* \leq \tilde{v} \leq v_+} \Omega^2(u_\infty, v_*) \left(1 + \tilde{v}^p\right) d\tilde{u}
\]

\[
\leq \tilde{C} \int_{u_1}^{u_2} |u_\infty|^{-\beta_\alpha} \left(1 + v_*^{-p}\right) d\tilde{u}
\]

\[
\leq \tilde{C} |u_2 - u_1| \leq \delta_1,
\]

(147)

and moreover \( \delta_1 \to 0 \) for \( \epsilon \to 0 \).

Further, in Sect. 4.1.4.1 we derived that similarly

\[
\Omega^2(\tilde{u}, \tilde{v}) \leq C \tilde{v}^{-\beta_\alpha}, \quad \text{for any } (\tilde{u}, \tilde{v}) \in J^+(x), \quad \text{with } x = (u_\infty, v_*), \quad x \in B,
\]

(148)

where \( v_* > v_\gamma(u_\infty) \).

\[
\int_{v_*}^{v_+} \sup_{u_1 \leq \tilde{u} \leq u_2} \left[ \frac{\Omega^2(\tilde{u}, \tilde{v})}{2r} (1 + \tilde{v}^p) \right] d\tilde{v} \overset{(148)}{\leq} C \int_{v_*}^{v_+} \tilde{v}^{-\beta_\alpha} \left(1 + \tilde{v}^p\right) d\tilde{v}
\]

\[
\leq \tilde{C} \left| -\beta_\alpha + p + 1 \right| \left[ \tilde{v}^{-\beta_\alpha + p + 1}\right]_{v_*} \leq \delta_2,
\]

(149)

where \( \delta_2 \to 0 \) for \( v_* \to \infty \). Thus the conclusion of Lemma 4.15 is obtained. \( \square \)

From the above we obtain

**Proposition 4.16.** Let \( \phi \) be as in Theorem 3.1 and \( p \) as in (46). For all \( v_* > v_\gamma(u_\infty) \) sufficiently large, \( \hat{v} \in (v_*, \infty) \), for \( u_0 \geq u_2 > u_1 \geq u_\infty \) and \( \epsilon \geq u_2 - u_1 > 0 \). Then for \( \epsilon \) sufficiently small, the following is true. If

\[
\int_{\{v_* \leq v \leq \hat{v}\}} J^W_{\mu}(\phi) n^\mu_{u = u_1} d\text{Vol}_{u = u_1} \leq \tilde{C}_1,
\]

(150)
then
\[
\int_{\{v_s \leq v \leq \tilde{v}\}} J^W_\mu (\phi) n^\mu_{u=u_2} dVol_{u=u_2} + \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{v=\tilde{v}} dVol_{v=\tilde{v}} \leq \tilde{C}_2 (\tilde{C}_1, u_\diamond, v_\ast),
\]

where \(\tilde{C}_2\) depends on \(\tilde{C}_1, C_0\) of Theorem 3.1 and \(D_0(u_\diamond, v_\ast)\) of Proposition 3.2.

**Remark.** Note already that the hypothesis (150) is implied by the conclusion of Proposition 4.12 for \(u_1 = u_\diamond\).

**Proof.** By the divergence theorem and (139) we can state
\[
\int_{\{v_s \leq v \leq \tilde{v}\}} J^W_\mu (\phi) n^\mu_{u=u_2} dVol_{u=u_2} + \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{v=\tilde{v}} dVol_{v=\tilde{v}} \\
\leq \int_{\mathcal{R}_{u_1}} |\tilde{K}^W| dVol + \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{v=v_\ast} dVol_{v=v_\ast} \\
+ \int_{\{v_s \leq v \leq \tilde{v}\}} J^W_\mu (\phi) n^\mu_{u=u_1} dVol_{u=u_1}.
\]

We can replace the hypersurfaces \(u = u_2\) and \(v = \tilde{v}\) with \(u = \bar{u}\) and \(v = \bar{v}\) hypersurfaces and therefore obtain
\[
\sup_{u_1 \leq \bar{u} \leq u_2} \int_{\{v_s \leq v \leq \bar{v}\}} J^W_\mu (\phi) n^\mu_{u=\bar{u}} dVol_{u=\bar{u}} + \sup_{v_s \leq \bar{v} \leq v_\ast} \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{v=\bar{v}} dVol_{v=\bar{v}} \\
\leq \int_{\mathcal{R}_{u_1}} |\tilde{K}^W| dVol + \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{v=v_\ast} dVol_{v=v_\ast} \\
+ \int_{\{v_s \leq v \leq \bar{v}\}} J^W_\mu (\phi) n^\mu_{u=u_1} dVol_{u=u_1},
\]

Lem. 4.15
\[
\delta_1 \sup_{u_1 \leq \bar{u} \leq u_2} \int_{\{v_s \leq v \leq \bar{v}\}} J^W_\mu (\phi) n^\mu_{u=\bar{u}} dVol_{u=\bar{u}} \\
+ \delta_2 \sup_{v_s \leq \bar{v} \leq v_\ast} \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{v=\bar{v}} dVol_{v=\bar{v}} \\
+ \int_{\{u_1 \leq u \leq u_\diamond\}} J^W_\mu (\phi) n^\mu_{v=v_\ast} dVol_{v=v_\ast} + \int_{\{v_s \leq v \leq \bar{v}\}} J^W_\mu (\phi) n^\mu_{u=u_1} dVol_{u=u_1},
\]
Thus, we have

\[
\Rightarrow \sup_{u_1 \leq u \leq u_2} \int_{\{v_*=v\leq \hat{v}\}} J^W_\mu (\phi) n^\mu_{v=\hat{v}} d\text{Vol}_v = \hat{v} + \sup_{v_*=v_1 \leq v \leq \hat{v}} \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{u=\hat{u}} d\text{Vol}_u = \hat{u}
\]

\[
\leq \frac{1}{1 - \max(\delta_1, \delta_2)} \left[ \int_{\{u_1 \leq u \leq u_2\}} J^W_\mu (\phi) n^\mu_{v=v} d\text{Vol}_v + \int_{\{v_*=v \leq \hat{v}\}} J^W_\mu (\phi) n^\mu_{u=u_1} d\text{Vol}_u \right].
\]

\[
\leq \tilde{C} D_0(u_\diamond, v_*) + \tilde{C},
\]

where the last step follows by statement (42) of Proposition 3.2, with \(k=0\), and by (150). We have chosen \(\epsilon\) sufficiently small and \(v_*\) sufficiently close to \(\infty\), such that \(\delta_1\) and \(\delta_2\) satisfy say

\[
\delta_1, \delta_2 \leq \frac{1}{2}.
\]

The conclusion of Proposition 4.16 is obtained. \(\square\)

We are now ready to make a statement for the entire region \(\mathcal{R}_V\).

**Proposition 4.17.** Let \(\phi\) be as in Theorem 3.1 and \(p\) as in (46). Then, for all \(v_* > v_Y(u_\infty)\) sufficiently large, \(\hat{v} > v_*\), and \(u_\diamond > \hat{u} > u_\infty\),

\[
\int_{\{u_\infty \leq u \leq u_\diamond\}} J^W_\mu (\phi) n^\mu_{v=\hat{v}} d\text{Vol}_v \leq C(u_\diamond, v_*),
\]

where \(C\) depends on \(C_0\) of Theorem 3.1 and \(D_0(u_\diamond, v_*)\) of Proposition 3.2.

**Proof.** Let \(\epsilon\) be as in Proposition 4.16. We choose a sequence \(u_{i+1} - u_i \leq \epsilon\) and \(i = \{1, 2, \ldots, n\}\) such that \(u_1 = u_\infty\) and \(u_n = \hat{u}\). Denote \(\mathcal{R}_{V_i} = \{u_i \leq u \leq u_{i+1}\} \cap \{v_* \leq v \leq \hat{v}\}\), cf. Fig. 13. Iterating the conclusion of Proposition 4.16 from \(u_1\) up to \(u_n\) then completes the proof. Note that \(n\) depends only on the smallness condition on \(\epsilon\) from Proposition 4.16, since \(n \lesssim \frac{u_\diamond - u_\infty}{\epsilon}\). \(\square\)
4.4. Propagating the energy estimate up to the bifurcation sphere. All results stated so far, correspond to the neighbourhood of \( i^+ \) at \( u = -\infty \), which we call the right hand side of the spacetime. Analogously, we can derive all statements for the left hand side, in the neighbourhood of \( i^+ \) at \( v = -\infty \) by substituting all \( u \) parameters by \( v \) and all \( v \) parameters by \( u \). In this section we will use both results from the right and left side on \( CH^+ \).

Fix \( u_\circ = v_\circ \), such that moreover Proposition 4.17 holds with \( v_\circ = v_* \), and such that its left side analog holds with \( u_\circ = u_* \). We will consider a region \( \mathcal{R}_{VI} = \{ u_\circ \leq u \leq \hat{u}, v_\circ \leq v \leq \hat{v} \} \), with \( \hat{u} \in (u_\circ, \infty) \) and \( \hat{v} \in (v_\circ, \infty) \), cf. Fig. 14.

Recall, that in Sect. 4.1.4.2 we have defined the weighted vector field

\[
S = v^p \partial_v + u^p \partial_u, \tag{157}
\]

which we are going to use again to obtain an energy estimate up to the bifurcate two-sphere. Recall \( K^S \) given in (105), where the terms multiplying the angular derivatives are positive since \( \mathcal{R}_{VI} \) is located in the blueshift region. We further defined \( \tilde{K}^S \) in (106) and stated (107) which will be useful to state the following proposition.

**Lemma 4.18.** Let \( \phi \) be an arbitrary function. Then, for all \((u_\circ, v_\circ) \in J^+(\gamma) \cap B \) and all \( \hat{u} > u_\circ \), all \( \hat{v} > v_\circ \), the integral over \( \mathcal{R}_{VI} \), cf. Fig. 14 of the current \( \tilde{K}^S \), defined by (106), can be estimated by

\[
\int_{\mathcal{R}_{VI}} |\tilde{K}^S| dVol \leq \delta_1 \sup_{u_\circ \leq \tilde{u} \leq \hat{u}} \int_{\{v_\circ \leq v \leq \tilde{v}\}} J^S_\mu(\phi)n^{\mu}_{u=\tilde{u}} dVol_{u=\tilde{u}} + \delta_2 \sup_{v_\circ \leq \tilde{v} \leq \hat{v}} \int_{\{u_\circ \leq u \leq \tilde{u}\}} J^S_\mu(\phi)n^{\mu}_{v=\tilde{v}} dVol_{v=\tilde{v}}, \tag{158}
\]

where \( \delta_1 \) and \( \delta_2 \) are positive constants, with \( \delta_1 \to 0 \) as \( u_\circ \to \infty \) and \( \delta_2 \to 0 \) as \( v_\circ \to \infty \).

**Proof.** The proof is similar to the proof of Lemma 4.10 of Sect. 4.1.4.2 and Lemma 4.15 of Sect. 4.3.

---

11 Since \( u \) is always positive in the remaining region under consideration \( \mathcal{R}_{VI} \), we have omitted the absolute value in the \( u \)-weight.
We still need to show finiteness and smallness of \( \int \sup_{u_0} \int u_0 \leq \bar{u} \leq \hat{u} \left[ \frac{\Omega^2(\bar{u}, \hat{u})}{2r} \left( 1 + \frac{\bar{u}^p}{\hat{u}^p} \right) \right] d\bar{u} \) and \( \int \sup_{u_0} \int u_0 \leq \bar{u} \leq \hat{u} \left[ \frac{\Omega^2(\bar{u}, \hat{u})}{2r} \left( 1 + \frac{\bar{u}^p}{\hat{u}^p} \right) \right] d\bar{u} \). In Sect. 4.1.4.1 we derived (100) which we will use now for all \( \bar{u}, \hat{u} \in J^+(u_0, v_0) \). Therefore, we can write

\[
\int \sup_{u_0} \int u_0 \leq \bar{u} \leq \hat{u} \left[ \frac{\Omega^2(\bar{u}, \hat{u})}{2r} \left( 1 + \frac{\bar{u}^p}{\hat{u}^p} \right) \right] d\bar{u} \leq C \int \sup_{u_0} \left[ \Omega^2(u_0, v_0) e^{-\beta[\bar{v} - v_0 + \bar{u} - u_0]} \left( 1 + \frac{\bar{u}^p}{\hat{u}^p} \right) \right] d\bar{u},
\]

where \( \delta_1 \to 0 \) as \( u_0 = v_0 \to \infty \) (since \( \Omega^2(u_0, v_0) \to 0 \), cf. (23)). Similarly, for finiteness of the second term we obtain

\[
\int \sup_{v_0} \int v_0 \leq \bar{v} \leq \hat{v} \left[ \frac{\Omega^2(\bar{v}, \hat{v})}{2r} \left( 1 + \frac{\bar{v}^p}{\hat{v}^p} \right) \right] d\bar{v} \leq \hat{C} \int \left[ \Omega^2(u_0, v_0) e^{-\beta[\bar{v} - v_0]} \left( 1 + \frac{\bar{v}^p}{u_0^p} \right) \right] d\bar{v} \leq \delta_2,
\]

where \( \delta_2 \to 0 \) as \( u_0 = v_0 \to \infty \).

Thus we obtain the statement of Lemma 4.10 by fixing \( u_0 = v_0 \) sufficiently large.

\[ \Box \]

**Proposition 4.19.** Let \( \phi \) be as in Theorem 3.1. Then, for \( u_0 = v_0 \) sufficiently close to \( \infty \) and \( \bar{u} > u_0, \hat{u} > v_0 \)

\[
\int \left. J_\mu^S(\phi)n^\mu_{u=\bar{u}} d\text{Vol}_{u=\bar{u}} \right|_{v_0 \leq \bar{v} \leq \hat{v}} + \int \left. J_\mu^S(\phi)n^\mu_{v=\hat{v}} d\text{Vol}_{v=\hat{v}} \right|_{u_0 \leq \bar{u} \leq \hat{u}} \leq C(u_0, v_0),
\]

where \( C \) depends on \( C_0 \) of Theorems 3.1 and \( D_0(u_0, v_0) \) of Propositions 3.2 (and their left side analogs, which we obtain from interchanging \( u \) and \( v \)).

**Proof.** The proof follows from applying the divergence theorem for the current \( J_\mu^S(\phi) \) in the region \( \mathcal{R}_{\mathcal{V}^I} \). The past boundary terms are estimated by Proposition 4.17 and its left side analog. Note that the weights of \( J_\mu^S(\phi) \) are comparable to the weights of \( J_\mu^W(\phi) \) for fixed \( u_0 \), and similarly the weights of \( J_\mu^S(\phi) \) are comparable to the weights of the left analog of \( J_\mu^W(\phi) \) for fixed \( v_0 \). The bulk term is absorbed by Lemma 4.18. \[ \Box \]
Now that we have shown boundedness for different subregions of the interior we can state the following proposition for the entire interior region $\mathcal{M}_{II}$, cf. Sect. 2.3.1.

**Corollary 4.20.** Let $\phi$ be as in Theorem 3.1. Then

$$\int_{S^2}^{\infty} \int_{v_{\text{fix}}}^{\infty} \left[ (|v| + 1)^p (\partial_v \phi)^2 (u_{\text{fix}}, v, \theta, \varphi) + \Omega^2 |\nabla \phi|^2 (u_{\text{fix}}, v, \theta, \varphi) \right] r^2 dv d\sigma_{S^2}$$

$$\leq C, \quad \text{for } v_{\text{fix}} \geq v_\infty, u_{\text{fix}} > -\infty,$$

(162)

$$\int_{S^2}^{\infty} \int_{u_{\text{fix}}}^{\infty} \left[ (|u| + 1)^p (\partial_u \phi)^2 (u, v_{\text{fix}}, \theta, \varphi) + \Omega^2 |\nabla \phi|^2 (u, v_{\text{fix}}, \theta, \varphi) \right] r^2 du d\sigma_{S^2}$$

$$\leq C, \quad \text{for } u_{\text{fix}} \geq u_\infty, v_{\text{fix}} > -\infty,$$

(163)

where $p$ is as in (46) and $C$ depends on $C_0$ of Theorem 3.1 and $D_0(u_\infty, v_\infty)$ of Proposition 3.2 (and their left side analogs) where $u_\infty = v_\infty$ is as in Proposition 4.19.

**Proof.** This follows by examining the weights in Proposition 4.17 (and its left side analog) and 4.19 together with Theorem 4.14 (and its left side analog). □

4.5. Global higher order energy estimates, pointwise boundedness and continuity. To obtain pointwise bounds in analogy to Sect. 4.2 we first have to extend Corollary 4.20 to a higher order statement.

**Theorem 4.21.** Let $\phi$ be as in Theorem 3.1 and $p$ as in (46). Then, for $v_{\text{fix}} \geq v_\infty$, $u_{\text{fix}} > -\infty$

$$\int_{S^2}^{\infty} \int_{v_{\text{fix}}}^{\infty} \left[ (|v| + 1)^p (\partial_v \zeta^k \phi)^2 (u_{\text{fix}}, v, \theta, \varphi) + \Omega^2 |\nabla \zeta^k \phi|^2 (u_{\text{fix}}, v, \theta, \varphi) \right] r^2 dv d\sigma_{S^2} \leq E_k,$$

(164)

and for $u_{\text{fix}} \geq u_\infty$, $v_{\text{fix}} > -\infty$

$$\int_{S^2}^{\infty} \int_{u_{\text{fix}}}^{\infty} \left[ (|u| + 1)^p (\partial_u \zeta^k \phi)^2 (u, v_{\text{fix}}, \theta, \varphi) + \Omega^2 |\nabla \zeta^k \phi|^2 (u, v_{\text{fix}}, \theta, \varphi) \right] r^2 du d\sigma_{S^2} \leq E_k,$$

(165)

(166)

for all $k \in \mathbb{N}^0$.

**Proof.** This follows immediately from Corollary 4.20 by commutation. □

Having proven Theorem 4.21, the pointwise boundedness of $|\phi|$ in all of $\mathcal{M}_{II}$ follows analogously to Sect. 4.2.3 but by integration in $u$-direction.
We estimate
\[
\int_{S^2} (\Delta^k \phi)^2(\hat{u}, v) d\sigma_{S^2} \leq \tilde{C} \left[ \int_{S^2} \left( \int_{u_*} (|u| + 1)^p (\partial_u \Delta^k \phi)^2(u, v) du \right) r^2 d\sigma_{S^2} \right.
\]
\[
+ \int_{S^2} (\Delta^k \phi)^2(u_*, v) d\sigma_{S^2} \right],
\]
\[
\leq \tilde{C} \left[ \tilde{C} E_k + \int_{S^2} \phi^2(u_*, v) d\sigma_{S^2} \right],
\]
(167)

where \( u_* \geq u_\infty, \hat{u} \in (u_*, \infty) \) and \( v \in (1, \infty) \) and \( k \in \mathbb{N}^0 \).

By using the result (135) in (167) we derive pointwise boundedness according to (129)
\[
\sup_{(\theta, \varphi) \in S^2} |\phi(\hat{u}, v, \theta, \varphi)|^2 \leq \tilde{C} \left[ \int_{S^2} (\phi)^2(\hat{u}, v) d\sigma_{S^2} + \int_{S^2} (\Delta \phi)^2(\hat{u}, v) d\sigma_{S^2} \right]
\]
\[
+ \int_{S^2} (\Delta^2 \phi)^2(\hat{u}, v) d\sigma_{S^2} \right],
\]
\[
\leq \tilde{C} \left[ \tilde{C} (E_0 + E_1 + E_2) + C \right] \leq C,
\]
(168)

with \( C \) depending on the initial data.

Inequalities (168) and (135) gives the desired (2) for all \( v \geq 1 \). Interchanging the roles of \( u \) and \( v \), likewise (2) follows for all \( u \geq 1 \). The remaining subset of the interior has compact closure in spacetime for which (2) thus follows by Cauchy stability. We have thus shown (2) globally in the interior.

The continuity statement of Theorem 1.1 follows easily by estimating \(|\phi(u, v, \varphi, \theta) - \phi(\tilde{u}, v, \varphi, \theta)|\) via the fundamental theorem of calculus and Sobolev embedding, and similarly for \( u, \varphi \) and \( \theta \) in the role of \( u \).

5. Outlook

In the following section we give a brief overview of further related open problems.

5.1. Scalar waves on subextremal Kerr interior background. All constructions of this paper have direct generalizations to the subextremal Kerr case. The following theorem will appear in a subsequent companion paper.

---

12 We estimate as in (167) and (168) but exploiting that \( \int_{\tilde{u}}^u (|u| + 1)^{-p} \to 0 \) as \( \tilde{u}, u \to \infty \).

13 This is in contrast to the exterior region for which the analysis of the Kerr case is significantly harder than for spherically symmetric black hole spacetimes in view of the difficulties of superradiance and the more complicated trapping. See the references below.
**Theorem 5.1.** On a fixed subextremal Kerr background \( 0 \neq |a| < M \), with angular momentum per unit mass \( a \) and mass \( M \), let \( \phi \) be a solution of the wave equation arising from sufficiently regular initial data on a Cauchy hypersurface \( \Sigma \). Then

\[
|\phi| \leq C
\]
globally in the black hole interior up to \( \mathcal{C}H^+ \), to which \( \phi \) in fact extends continuously.

The above theorem of course depends on the fact that the analog of Theorem 3.1 has been proven in the full subextremal range \( |a| < M \) on Kerr backgrounds by Dafermos et al. cf. [19,22]; see also [1,18,20,21,31,35,44] for the \( |a| \ll M \) case and [42,46] for mode stability.

5.2. **Mass inflation.** In view of our stability result, what remains of the “blueshift instability”? The result of Theorem 1.1 is still compatible with the expectation that the transverse derivatives (with respect to regular coordinates on \( \mathcal{C}H^+ \)) of \( \phi \) will blow up along \( \mathcal{C}H^+ \), cf. the work of Simpson and Penrose [43]. In fact given a lower bound, say

\[
|\partial_v \phi| \geq c v^{-4},
\]
for some constant \( c > 0 \) and all sufficiently large \( v \) on \( \mathcal{H}^+ \), Dafermos has shown for the spherically symmetric Einstein-Maxwell-scalar field model that transverse derivatives blow up, cf. [13]. This blow up result of [14] would also apply to our setting here if the above lower bound (169) is assumed on the spherical mean of \( \phi \) on \( \mathcal{H}^+ \). See also [34]. Such a lower bound however has not been proven yet for solutions arising from generic data on \( \Sigma \); see also Sbierski [40]. One might therefore aim for proving the following conjecture.

**Conjecture 5.2.** Let \( \phi \) be as in Theorem 1.1 or 5.1. For generic data on \( \Sigma \), transverse derivatives of \( \phi \) blow up on \( \mathcal{C}H^+ \), in fact \( \phi \) is not \( H^1_{\text{loc}} \).

5.3. **Extremal black holes.** For a complete geometric understanding of black hole interiors one must also consider extremal black holes. Aretakis proved stability and instability properties for the evolution of a massless scalar field on a fixed extremal Reissner-Nordström exterior background. For data on a spacelike hypersurface \( \Sigma \) intersecting the event horizon and extending to infinity he has proven decay of \( \phi \) up to and including the horizon, cf. [2]. In subsequent work [3] Aretakis showed that first transverse derivatives of \( \phi \) generically do not decay along the event horizon for late times. He further proved that higher derivatives blow up along the event horizon.

The analysis of the evolution of the scalar wave in the region beyond the event horizon for the extreme case remains to be shown. Motivated by heuristics and numerics of Murata, Reall and Tanahashi [36], which suggest stronger stability results in the interior than in the subextremal case, we conjecture

**Conjecture 5.3.** (See [36]). In extremal Reissner-Nordström spacetime \((\mathcal{M}, g)\), with mass \( M \) and charge \( e \) and \( M = |e| \neq 0 \), let \( \phi \) be a solution of the wave equation

\[
\Box_g \phi = 0
\]
arising from sufficiently regular Cauchy data on \( \Sigma \). Then, for \( V_\pm \) regular at \( \mathcal{C}H^+ \)

\[
|\phi| \leq C, \quad |\partial_{V_\pm} \phi| \leq C,
\]
globally in the maximal domain of dependence \( \mathcal{D}^+(\Sigma) \) of a hypersurface \( \Sigma \).
See work of Gajic [24].

Aretakis has further considered $\Box_g \phi$ on a fixed extremal Kerr background, c.f [4]. Analogously to the extremal Reissner-Nordström case, he shows decay up to and including the event horizon for axisymmetric solutions $\phi$ and in [5] shows instability properties when considering transverse derivatives. This has been further generalised in [28,29]. In analogy with Conjecture 5.3, we thus also make the following conjecture:

**Conjecture 5.4.** In extremal Kerr spacetime $(\mathcal{M}, g)$, with mass $M$ and angular momentum per unit mass $a$ and $M = |a| \neq 0$, let $\phi$ be an axisymmetric solution of the wave equation $\Box_g \phi = 0$ arising from sufficiently regular Cauchy data on $\Sigma$. Then, for $V_-$ regular at $\mathcal{CH}^+$

$$|\phi| \leq C, \quad |\partial V_- \phi| \leq C$$

globally in the maximal domain of dependence $D^+(\Sigma)$ of the hypersurface $\Sigma$.

The case of non axisymmetric $\phi$ seems to be rather complicated and we thus do not venture a conjecture here.

**5.4. Einstein vacuum equations.** We now return to the problem that originally motivated our work, namely the dynamics of the Einstein vacuum equations. Our result and the forthcoming extension to subextremal Kerr backgrounds further support the expectation that the spherically symmetric toy models [12–14,37–39] are indeed indicative of what happens for the full nonlinear Einstein vacuum equations without symmetry. In particular our results support the following conjecture given in [14].

**Conjecture 5.5.** (Ori). Let $(\mathcal{M}, g)$ be the maximal vacuum Cauchy development of sufficiently small perturbations of asymptotically flat two-ended Kerr data corresponding to parameters $0 < |a| < M$. Then;

(a) there exist both a future and past extension $(\tilde{\mathcal{M}}, \tilde{g})$ of $\mathcal{M}$ with $C^0$ metric $\tilde{g}$ such that $\partial \mathcal{M}$ is a bifurcate null cone in $\tilde{\mathcal{M}}$ and all future (past) incomplete geodesics in $\gamma$ pass into $\tilde{\mathcal{M}}/\mathcal{M}$.

(b) Moreover, for generic such perturbations, any $C^0$ extension $\tilde{\mathcal{M}}$ will fail to have $L^2$ Christoffel symbols in a neighbourhood of any point of $\partial \mathcal{M}$.

A proof of part (a) has recently been announced by Dafermos and Luk, given the conjectured stability of Kerr exterior (i.e. given the analog of Theorem 3.1 for the full nonlinear Einstein vacuum equations). Specific examples of vacuum spacetimes with null singularities as in (b) have been constructed by Luk [32]. For a discussion of what all this means to Strong Cosmic Censorship see [14].

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Appendix A: The J-Currents and Normal Vectors

In the following we will derive the J-currents on constant \(r, u\) and \(v\) hypersurfaces as well as the hypersurface \(\gamma\), defined in (85).

We consider an arbitrary function \(F(u, v)\) independent of the angular coordinates. Let \(\zeta\) be a levelset \(\{F(u, v) = 0\}\). Then, the normal vector to the hypersurface \(\zeta\) is given by

\[
\zeta^\mu = \frac{1}{\sqrt{\Omega^2 [\partial_u F \partial_v F]}} (\partial_u F \partial_u + \partial_v F \partial_v). \quad (A1)
\]

In particular, for the future directed normal vector of an \(r(u, v) = \text{const}\) hypersurface we obtain

\[
n^\mu_r = \frac{1}{\sqrt{\Omega^2}} (\partial_u + \partial_v), \quad (A2)
\]

and on constant \(u\) and \(v\) null hypersurfaces with their related volume elements we have

\[
n^\mu_u = \frac{2}{\Omega^2} \partial_u, \quad \text{Vol}_u = r^2 \Omega^2 2 \, d\sigma_\Omega dv, \quad \text{Vol}_v = r^2 \Omega^2 2 \, d\sigma_\Omega du. \quad (A3)
\]

For (A3), note that since vectors orthogonal to null hypersurfaces cannot be normalized, their proportionality has to be chosen consistent with an associated volume form in the application of the divergence theorem.

Further, the volume element of the four dimensional spacetime is given by

\[
d\text{Vol} = r^2 \Omega^2 2 \, d\sigma_\Omega dr d\Omega. \quad (A4)
\]

According to (7), using an arbitrary vector field \(X = X^u \partial_u + X^v \partial_v\), we then obtain:

\[
J^X(\phi)n^\mu_\zeta = \frac{1}{\sqrt{\Omega^2}} \left[ X^v \left( \frac{\partial_u F}{\partial_v F} (\partial_u \phi)^2 + X^u \left( \frac{\partial_v F}{\partial_u F} (\partial_v \phi)^2 \right) \right] + \frac{\sqrt{\Omega^2}}{4} \left[ X^v \left( \frac{\partial_u F}{\partial_v F} + X^u \left( \frac{\partial_v F}{\partial_u F} \right) \right) \right] |\nabla \phi|^2, \quad (A5)
\]

\[
J^X(\phi)n^\mu_{r=\text{const}} = \frac{1}{\sqrt{\Omega^2}} \left[ X^v (\partial_u \phi)^2 + X^u (\partial_v \phi)^2 \right] + \frac{\sqrt{\Omega^2}}{4} \left[ X^v + X^u \right] |\nabla \phi|^2, \quad (A6)
\]

\[
J^X(\phi)n^\mu_{u=\text{const}} = \frac{2}{\Omega^2} X^u (\partial_u \phi)^2 + \frac{1}{2} X^v |\nabla \phi|^2, \quad (A7)
\]

Appendix B: The K-Current

In order to compute all scalar currents according to (8) in \((u, v)\) coordinates we first derive the components of the deformation tensor which is given by

\[
(\pi X)^{\mu\nu} = \frac{1}{2} (g^{\mu\lambda} \partial_\lambda X^\nu + g^{\nu\sigma} \partial_\sigma X^\mu + g^{\mu\lambda} g^{\nu\sigma} g_{\lambda\sigma} \delta X^\delta), \quad (B1)
\]

where \(X\) is an arbitrary vector field, \(X = X^u \partial_u + X^v \partial_v\) without angular components.\(^{14}\) From this we obtain

\[
(\pi X)^{\nu u} = -\frac{2}{\Omega^2} \partial_\nu X^u, \quad (\pi X)^{u u} = -\frac{2}{\Omega^2} \partial_u X^u,
\]

\[
(\pi X)^{\nu u} = -\frac{1}{\Omega^2} (\partial_\nu X^u + \partial_u X^\nu) - \frac{2}{\Omega^2} \left( \frac{\partial_\nu \Omega}{\Omega} X^u + \frac{\partial_u \Omega}{\Omega} X^\nu \right),
\]

\[
(\pi X)^{\theta \phi} = \frac{1}{r^2} \left( \frac{\partial_\nu r}{r} X^\nu + \frac{\partial_r r}{r} X^\nu \right), \quad (\pi X)^{\phi \phi} = \frac{1}{r^2 \sin^2 \theta} \left( \frac{\partial_\nu r}{r} X^\nu + \frac{\partial_r r}{r} X^\nu \right).
\]

\(^{14}\) Recall that all our multipliers \(N, -\partial_r, S_0\) and \(S_0\) only contain \(u\) and \(v\) components.
From (6) we calculate the components of the energy momentum tensor in $(u,v)$ coordinates as

\[ T_{vv} = (\partial_v \phi)^2, \quad T_{uu} = (\partial_u \phi)^2, \quad T_{uv} = T_{vu} = \frac{\Omega^2}{4} |\nabla \phi|^2, \]

\[ T_{\theta\theta} = \frac{2r^2}{\Omega^2} (\partial_u \phi \partial_v \phi) - \frac{1}{2} r^2 |\nabla \phi|^2, \]

\[ T_{\phi\phi} = \frac{2r^2 \sin^2 \theta}{\Omega^2} (\partial_u \phi \partial_v \phi) - \frac{1}{2} r^2 \sin^2 \theta |\nabla \phi|^2. \]

Multiplying the components according to (8) and using the relations (24) we obtain

\[ K^X = \frac{2}{\Omega^2} \left[ \partial_u X^v (\partial_v \phi)^2 + \partial_v X^u (\partial_u \phi)^2 \right] - \frac{2}{r} \left[ X^v + X^u \right] (\partial_u \phi \partial_v \phi) \]

\[ - \left[ \frac{1}{2} (\partial_v X^v + \partial_u X^u) + \left( \frac{\partial_v \Omega}{\Omega} X^v + \frac{\partial_u \Omega}{\Omega} X^u \right) \right] |\nabla \phi|^2. \]  

(B2)
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