Finite-time Stückelberg interferometry with nanomechanical modes

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Abstract

Stückelberg interferometry describes the interference of two strongly coupled modes during a double passage through an avoided energy level crossing. In this work, we investigate finite-time effects in Stückelberg interferometry and discuss the exact analytical solution of the double passage Stückelberg problem by expanding the finite-time solution of the Landau–Zener problem. Approximating the return probability amplitudes of the double passage in distinct limits reveals uncharted parameter regimes of Stückelberg interferometry where finite-time effects affect the coherent exchange of energy. We find the long-time limit of the exact solution to formally coincide with the well-established adiabatic impulse model which is, to the best of our knowledge, the only regime of Stückelberg interferometry reported so far. Experimentally, we study all predicted regimes using a purely classical, strongly coupled nanomechanical two-mode system of high quality factor. The classical two-mode system consists of the in-plane and out-of-plane fundamental flexural mode of a high stress silicon nitride string resonator, coupled via electric gradient fields. We exploit our experimental and theoretical findings by studying the onset of Stückelberg interference in dependence of the characteristic system control parameters and obtain characteristic excitation oscillations between the two modes even without the explicit need of traversing the avoided crossing. The presented findings are not limited to classical mechanical two-mode systems but can be applied to every strongly coupled (quantum) two-level system, for example a spin-1/2 system or superconducting qubit.

1. Introduction

Strongly coupled nanomechanical resonators have proven themselves as prominent testbed for the investigation of various fundamental physical concepts. The recent studies of, for example, non-classical correlations [1, 2], quantum back-action [3], quantum squeezing [4] and topological effects [5] in different nanomechanical systems demonstrate an outstanding way the scientific impact of hybrid-mechanical systems. In addition, the high level of control over such coupled resonators allows for the realization of ultrasensitive vectorial force sensors [6, 7] and A-type three level systems [8].

Recently, this high level of control led to the demonstration of classical Stückelberg interference of two strongly coupled nanomechanical resonator modes [9]. This coherent transfer of energy has originally been studied in a broad range of quantum systems including, e.g., spin-1/2 systems [10–12] and superconducting qubits [13–17], amongst many others. Typically, the coherent dynamics of a two-level system in the configuration proposed by Stückelberg [18] is theoretically modeled by an infinite-time approach, the so-called adiabatic impulse model [16]. Following this model, the interference of two quantum states during a double passage through an avoided level crossing solely relies on the mutual coupling and is independent of the exact time evolution of the two states in the vicinity of the avoided crossing. In this work, we go well beyond this simple approximation and show that the adiabatic impulse model represents just one particular limit, the infinite-time limit, of the full Stückelberg problem [18]. We employ the exact analytical finite-time solution [19] of the...
Landau–Zener problem [20, 21] to derive an exact solution for the double passage Stückelberg problem [18]. Our solution captures the importance of finite-time effects. By means of asymptotic approximations of the exact finite-time return amplitudes, we identify up to six different parameter regimes of Stückelberg interferometry. Experimentally, we demonstrate that a classical strongly coupled nanomechanical two-mode system [9, 22] allows for the investigation of all discussed asymptotic regimes due to high mechanical quality factors and hence lifetimes of the coherent mechanical modes in the millisecond regime [9, 22].

The manuscript is organized as follows. Following this introduction (section 1), we discuss in sections 2.1 and 2.2 an exact analytical solution of the Stückelberg problem, taking advantage of the conformity of classical and quantum interference in this particular problem [9]. Additionally, the asymptotic limits of the exact solution are derived (appendices A and B) which allows for a quantification of characteristic parameter regimes in Stückelberg interferometry. In section 2.3, we explicitly derive the long-time limit of the analytical solution. Section 2.4 provides a brief summary of an established, approximative theoretical approach of Stückelberg interferometry and establishes the link to the long-time limit of the presented exact analytical solution. Section 3 introduces the nanoelectromechanical system as well as the experimental techniques. Section 4 compares the different theories to the experimentally observed classical Stückelberg oscillations of a strongly coupled nanomechanical system. In the last part (section 5), we summarize the results.

2. Finite-time theory

In this work, we study the effects of finite times in classical Stückelberg interferometry. In general, Stückelberg interferometry [18] occurs during a double passage through an avoided energy level crossing within the coherence time of the strongly coupled system. Both energy branches accumulate phase during the double passage, giving rise to self-interference. This brings about interference fringes depending on the difference in the coherence time of the strongly coupled system. Both energy branches accumulate phase during the double passage oscillates in dependence of the level splitting, the traversal time as well as the initialization and turning point [16, 18].

2.1. Theory of strongly coupled modes

The double passage Stückelberg problem is solved by considering two strongly coupled nanomechanical modes forming a classical two-mode system [9]. We follow the work of Novotny [28] and describe the coupled modes with the system of differential equations:

\[
\begin{align*}
\dot{m}u_i(t) + m\omega_i^2 u_i(t) + \kappa [u_i(t) - u_j(t)] &= 0 \\
\dot{m}u_j(t) + m\omega_j^2 u_j(t) + \kappa [u_j(t) - u_i(t)] &= 0,
\end{align*}
\]

where \(m = m_0/2\) denotes the effective mass of the resonator with physical mass \(m_0\), \(u_j (j = 1, 2)\) the displacement of mode \(j\), \(\omega_j = \sqrt{k_j/m}\) the respective angular resonance frequency of the two modes under investigation, in our case the out-of-plane \((j = 1)\) and in-plane \((j = 2)\) resonator mode, \(k_j\) the spring constant of mode \(j\), and \(\kappa\) the coupling constant between the two modes. Using the ansatz \(u_j(t) = u_{j0} \exp(-i\omega t)\) in equation (1) yields the resonance frequencies of the two normal modes in the coupled system:

\[
\omega_{\pm}^2 = \omega_+^2 + \omega_-^2 + 2\omega_+ \omega_- + \frac{1}{2} \left( (\omega_+ + \omega_-)^2 + 4\omega_0^2 \right),
\]

Here, we have defined \(\omega_0 = \sqrt{\kappa/m}\). The minimal level splitting, i.e. the frequency splitting for \(\omega_1 = \omega_2\), is given by

\[
\Delta = \omega_+ - \omega_- = \frac{2\omega_+ \omega_-}{\omega_+ + \omega_-} \approx \frac{\omega_+^2}{\omega_1} = \frac{\kappa}{m\omega_1} \equiv |\lambda|,
\]

where \(\kappa/k \ll 1\). The coupling \(\lambda\), in general, can be complex valued. In this work, \(\lambda\) is a real value since the presented experimental system exhibits a spring-like coupling [26].

If the level splitting exceeds the dissipation in the system, namely the linewidth of the mechanical resonances, the modes can coherently exchange energy on a faster timescale than the energy decay. This strong coupling regime allows for the investigation of time dependent phenomena, like non-adiabatic Landau–Zener tunneling [26, 28] in the classical regime, coherent dynamics of classical two-mode systems [22, 29, 30] and classical state interferometry [9].

2.2. Finite-time Stückelberg interferometry

We look for a solution of equation (1) in the experimentally relevant limit where \(\kappa/k_j \ll 1, j \in \{1, 2\}\). This suggests to look for solutions of the form \(u_j(t) = c_j(t) \exp[i\omega_j t]\) with \(c_j(t)\) a normalized amplitude, i.e.
\[|\psi(t)|^2 + |\psi(t)|^2 = 1, \text{ and we define } \tilde{\omega}_j = \sqrt{(k_j + \kappa)/m}. \text{ By replacing our ansatz for } u_j(t) \text{ in equation (1), we find}
\]
\[
\begin{align*}
\tilde{c}_j(t) + 2i\tilde{\omega}_j \tilde{c}_j(t) - \frac{\kappa}{m} \tilde{c}_j(t) &= 0, \quad \text{where } j = 1, 2, \\
\tilde{c}_j(t) + 2i\tilde{\omega}_j \tilde{c}_j(t) + (\tilde{\omega}_j^2 - \tilde{\omega}_j^2) \tilde{c}_j(t) - \frac{\kappa}{m} \tilde{c}_j(t) &= 0,
\end{align*}
\]
(4)

Since the amplitudes \( c_j(t) \) are slowly varying in time compared to the oscillatory function \( \exp[i\tilde{\omega}_j t] \) (see for instance [31]), one can neglect the second derivatives \( \tilde{c}_j(t) \) in equation (4). Thus, the evolution of the normalized amplitudes is described by

\[
i\dot{c}(t) = H(t)c(t),
\]
(5)

where we have defined \( c(t) = (\tilde{c}_1(t)\tilde{c}_2(t))^T \) and

\[
H(t) = \begin{pmatrix}
0 & \frac{\lambda}{2} \\
\frac{\lambda}{2} & \gamma - \alpha t
\end{pmatrix},
\]
(6)

with \( \lambda = \kappa/(m\tilde{\omega}_1) \). To obtain equation (6), we have used that in the vicinity of the avoided crossing \( \tilde{\omega}_2 \approx \tilde{\omega}_1 \). This yields \( (\tilde{\omega}_2^2 - \tilde{\omega}_1^2)/(2\tilde{\omega}_1) \approx \tilde{\omega}_2 - \tilde{\omega}_1 \) and we assume that the difference in frequency is changed in time such that \( \tilde{\omega}_2 - \tilde{\omega}_1 \approx \alpha t \), where \( \alpha \) denotes the frequency sweep rate.

By applying the time-dependent unitary transformation

\[
S(t) = \exp\left[-\frac{\lambda}{4} t^2\right],
\]
(7)

to equation (5), with \( I_2 \) the two-dimensional identity operator, we find that the transformed amplitudes obey the differential equation

\[
i\dot{c}_{LZ}(t) = H_{LZ}(t)c_{LZ}(t),
\]
(8)

where the dynamical matrix

\[
H_{LZ}(t) = \frac{1}{2} \begin{pmatrix}
\alpha t & \lambda \\
\lambda & \gamma - \alpha t
\end{pmatrix}
\]
(9)

is analog to the representation of the Landau–Zener Hamiltonian in the basis of diabatic states. Thus, the finite-time solution of the Landau–Zener problem [19] is also a solution of equation (8). By analogy with the quantum mechanical case, we express the solution using a classical flow \( \varphi_{LZ} \) (see for instance Hamiltonian flow in [32])

\[
\psi_{LZ}(t) = \varphi_{LZ}(t, t_i)\psi_{LZ}(t_i),
\]
(10)

with \( \psi_{LZ}(t_i) \) the initial condition of the system and

\[
\varphi_{LZ}(t, t_i) = \begin{pmatrix}
\varphi_{LZ,11}(t, t_i) & \varphi_{LZ,12}(t, t_i) \\
-\varphi_{LZ,12}^*(t, t_i) & \varphi_{LZ,11}^*(t, t_i)
\end{pmatrix}
\]
(11)

We have

\[
\varphi_{LZ,11}(t, t_i) = \frac{\Gamma(1 + i\frac{\theta}{4})}{\sqrt{2\pi}} D_{1-1}^z(e^{-i\frac{\theta}{4}}) D_{1-1}^z(e^{i\frac{\theta}{4}})
\]
\[+ D_{1-1}^z(e^{i\frac{\theta}{4}}) D_{1-1}^z(e^{-i\frac{\theta}{4}})\]
(12)

and

\[
\varphi_{LZ,12}(t, t_i) = \frac{\Gamma(1 + i\frac{\theta}{4})}{\sqrt{2\pi}} D_{1-1}^z(e^{i\frac{\theta}{4}}) D_{1-1}^z(e^{-i\frac{\theta}{4}})
\]
\[+ D_{1-1}^z(e^{-i\frac{\theta}{4}}) D_{1-1}^z(e^{i\frac{\theta}{4}})\]
(13)

where we have introduced dimensionless quantities by defining \( \tau = \sqrt{\alpha} t \) and \( \eta = \lambda/\sqrt{\alpha} \). Finally, the flow describing the evolution of \( \psi(t) \) and \( \psi(t) \) is given by

\[
\varphi(t, t_i) = \exp\left[i\frac{1}{4}(\tau^2 - \tau_i^2)\right] \psi_{LZ}(t, t_i).
\]
(14)
The flow \( \varphi(t,t_i) \) allows us to write in a simple way the state of the system after multiple passages through the avoided crossing. In particular, for a double passage we have

\[
e(t) = \varphi_b(t, t_p) \varphi(t_p, t_i) c(t_i),
\]

with \( \varphi_b(t, t_i) = \sigma_x \varphi(t, t_i) \sigma_x \), describing the evolution of the system during the back sweep, \( \sigma_x \) denotes the Pauli matrix in \( x \)-direction, and \( t_p \) labels the time at which the forward (backward) sweep stops (starts). The fact that \( \varphi_b(t, t_i) = \sigma_x \varphi(t, t_i) \sigma_x \) can be understood by noticing that during the back sweep the frequency of mode 1 (2) decreases (increases) while it increases (decreases) during the forward sweep (see figure 2(a)).

From equation (15), one obtains the return probability to mode 1

\[
P_{1\rightarrow 1} = |\varphi_{11}(t_p, t_i) \varphi^*_{11}(t, t_p) + \varphi^*_{12}(t_p, t_i) \varphi_{12}(t, t_p)|^2.
\]

### 2.3. Asymptotic solution for the long-time limit

#### 2.3.1. Long-time limit

In this section, we show how to obtain an approximate form of equation (16) in the long-time limit, i.e. \( \tau, |\tau_i|, \tau_p \gg 1 \). While asymptotic finite-time Landau–Zener probabilities have been derived in [19], here, we derive asymptotic finite-time expressions for the double passage Stückelberg problem. Note that our formalism would allow one to derive similar expressions for the case of \( N \) passages. We find

\[
\varphi_{LZ,11}(t, t_i) \approx \sqrt{1 - e^{-\pi^2 \tau}} \left[ \sin[\theta(|\tau_i|)] \cos[\theta(\tau)] e^{i\left(\theta(|\tau_i|)+\theta(\tau) + \frac{\pi}{4} - \arg\left[\Gamma\left(1 + \frac{\eta_i^2}{\tau}\right)\right]\right]} \right]
\]

and

\[
\varphi_{LZ,12}(t, t_i) \approx \sqrt{1 - e^{-\pi^2 \tau}} \left[ -\sin[\theta(|\tau_i|)] \sin[\theta(\tau)] e^{i\left(\theta(|\tau_i|)+\theta(\tau) + \frac{\pi}{4} - \arg\left[\Gamma\left(1 + \frac{\eta_i^2}{\tau}\right)\right]\right]} \right]
\]

The functions \( \cos[\theta(\tau)], \sin[\theta(\tau)], \) and \( \xi(\tau) \) are defined in appendix A and \( \Gamma(z) \) is the gamma function.

Substituting these expressions in equation (16) yields an expression for the return probability that is valid in the long-time limit. Note that the expansions in equations (17) and (18) are also valid for the softer criteria \( \tau^2 + \eta^2/4 > 1, \tau_1^2 + \eta^2/4 > 1, \) and \( \tau_p^2 + \eta^2/4 > 1 \).

#### 2.3.2. Infinite-time limit

If one further assumes that \( \eta/\tau, \eta/|\tau_i|, \eta/\tau_p \ll 1 \), then \( \cos[\theta(\tau)] \) and \( \sin[\theta(\tau)] \) can be expanded in powers of \( \eta/\tau \). We find \( \cos[\theta(\tau)] = 1 + \mathcal{O}(\eta^2/\tau^2) \) and \( \sin[\theta(\tau)] = \mathcal{O}(\eta/\tau) \). In this limit, which we refer to as the infinite-time limit, the return probability becomes

\[
P_{1\rightarrow 1}^{\text{inf}} = 1 - 4P_{LZ}(1 - P_{LZ}) \cos^2[\chi_{dp}(\tau_p)] + \mathcal{O}\left(\frac{\eta}{\tau}, \frac{\eta}{|\tau_i|}, \frac{\eta}{\tau_p}\right),
\]

where \( P_{LZ} = \lim_{\tau \to -\infty} |\varphi_{11}(t, t_i)|^2 = \exp(-\pi \eta^2/2) \) is the Landau–Zener(-Stückelberg–Majorana) non-adiabatic transition probability [18, 20, 21, 33] and we have defined the phase acquired during the double passage

\[
\chi_{dp}(\tau) = -\frac{\eta^2}{4} + \frac{\eta^2}{2} \log\left[\frac{1}{2}(\tau + \sqrt{\tau^2 + \eta^2})\right] + \frac{\tau}{2} \sqrt{\tau^2 + \eta^2} - \arg\left[\Gamma\left(1 + \frac{\eta^2}{4}\right)\right] - \frac{\pi}{4}.
\]
Another drawback of the adiabatic impulse model is that the leading order corrections to equation (19) cannot be found. In appendix B, we give an expression for the leading order correction to equation (19), which demonstrates that even in the infinite-time limit the return probability depends explicitly on $\tau_i$ and $\tau_f$.

### 2.4. Adiabatic impulse model

In this section, we briefly recapitulate an established theoretical approach to Stückelberg interferometry known as the adiabatic impulse model [16]. The main assumptions of the adiabatic impulse model are that all non-adiabatic transitions happen at $\tau = 0$ and that the system follows perfect adiabatic evolution from $\tau_i \rightarrow 0$ and from $0 \rightarrow \tau_f$, where $|\tau_i| \gg \eta$ with $\tau_i < 0$ and $\tau_f \gg \eta$. Given the assumptions of the model, it is convenient to work in the basis of instantaneous eigenstates of equation (9).

The non-adiabatic part of the evolution is described with a scattering matrix that relates the probability amplitudes right before the avoided crossing at $t = 0_-$ and right after the avoided crossing at $t = 0_+$. The scattering matrix (in the basis of instantaneous eigenstates) reads [16]

\[
N = \left( \sqrt{1 - P_{LZ}} e^{-i(\chi - \frac{\eta}{2})} \right) - \sqrt{P_{LZ}} \left( \sqrt{1 - P_{LZ}} e^{i(\chi - \frac{\eta}{2})} \right).
\]

Here, $\chi = \pi/4 + (\eta^2/4) \log(\eta^2/4) - 1 - \arg \left[ \Gamma(1 + i\eta^2/4) \right]$ is the so-called Stokes phase [34].

The adiabatic part of the evolution is described by the unitary evolution operator

\[
U_{ad}(\tau_i, \tau_f) = \exp \left[ -i\chi_{dyn}(\tau_i, \tau_f) \sigma_z \right],
\]

with $\sigma_z$ the Pauli matrix in the $z$-direction and we have defined the dynamical phase

\[
\chi_{dyn}(\tau_i, \tau_f) = \frac{1}{2} \int_{\tau_i}^{\tau_f} d\tau \sqrt{\tau^2 + \eta^2},
\]

\[
= \frac{1}{4} \left( \tau \sqrt{\tau^2 + \eta^2} + \eta^2 \log[\tau + \sqrt{\tau^2 + \eta^2}] - \tau_i \sqrt{\tau_i^2 + \eta^2} - \eta^2 \log[\tau_i + \sqrt{\tau_i^2 + \eta^2}] \right). \tag{23}
\]

Within this formalism, the state of the system after a double passage is given by

\[
\psi_{LZ}(\tau) \approx U_{ad}(\tau, \tau_0) U_{ad}(-\tau_0, \tau) U_{ad}(\tau_f, 0) U_{ad}(0, \tau_f) \psi_{LZ}(\tau_f) \psi_{LZ}(\tau_0).
\]

Here, we have chosen $0_-$ and $0_+$ to represent fixed times along the time axis. Note that we employ the scattering matrix $N$ instead of its Hermitian conjugate in the back sweep. Since the scattering matrix is expressed in the basis of instantaneous eigenstates, there is no difference in which direction the non-adiabatic transition is performed.

In general, all four adiabatic evolution operators in equation (24) contribute to the acquired dynamical phase of the system. For the particular case of the presented experiment, we initialize the system in an eigenstate of the coupled system. In this scenario, the first and the last adiabatic evolution operators in equation (24) turn into global phases, which do not contribute to the two-mode interference. Hence, the interference of the two modes is solely governed by the phase evolution in between the two scattering events. Finally, the adiabatic impulse model yields the return probability

\[
P_{\text{imp}}^{1\rightarrow 1} = 1 - 4P_{LZ} (1 - P_{LZ}) \cos^2[\chi_{dyn}(\tau)],
\]

where we have used the fact that in the infinite-time limit ($\eta/\tau \ll 1$) the instantaneous eigenstates and diabatic states of equation (9) coincide with each other.

As mentioned earlier, we have $P_{\text{imp}}^{1\rightarrow 1} = P_{\text{imp}}^{2\rightarrow 1}$. The main difficulty in using the adiabatic impulse model to get the return probability in regimes other than $\eta/\tau \ll 1$ lies in finding an appropriate scattering matrix $N$ that explicitly depends on time.

### 3. The nanoelectromechanical system

#### 3.1. Experimental set-up

We study self-interference of a classical nanomechanical two-mode system situated in a vacuum chamber at room temperature. The nanomechanical resonator operates deeply in the classical regime and does not exhibit quantum mechanical properties [9, 22]. The sample consists of a freely suspended and doubly clamped silicon nitride (SiN) string resonator, fabricated in a top-down approach from a high-stress silicon nitride film on a fused silica substrate. The 55 μm long, 270 nm wide and 100 nm thick silicon nitride string exhibits a high tensile pre-stress of 1.46 GPa resulting from the LPCVD deposition process of the SiN atop the fused silica wafer. The high tensile pre-stress translates into high mechanical quality factors up to $Q \approx 500,000$ at mechanical resonance frequencies of $\omega_m/2\pi \approx 6.5$ MHz at room temperature. Note that the experiments are conducted on the same sample as in a previous work (sample B in [9]) using the same experimental set-up. As depicted in
figures 1(a) and (b) the string resonator exhibits two fundamental flexural vibration modes with orthogonal mode polarizations, namely one perpendicular to the sample plane (out-of-plane) and one parallel to the sample plane (in-plane). For dielectric control and transduction of the string resonator (see figure 1(c)) we process two gold electrodes adjacent to the SiN string, which form a capacitor and are connected to a microwave cavity [23] via a bond wire. The oscillation of the dielectric silicon nitride string between the gold electrodes periodically modulates the capacitance. This change in capacitance in turn modulates the \( \lambda /4 \) microstrip cavity signal with resonance frequency at approximately \( \Omega_c / 2\pi \approx 3.6 \) GHz by producing sidebands on the cavity signal at \( \Omega_{\pm} = \Omega_c \pm \omega_m \), where \( \omega_m / 2\pi \approx 6.5 \) MHz denotes the mechanical resonance frequency. The modulation induced sidebands are not resolved but can be demodulated via a heterodyne in-phase-quadrature mixing technique [23] before subsequent low-pass filtering and amplification. Finally, the demodulated signal is captured using a spectrum analyzer. In addition to the described microwave cavity enhanced heterodyne dielectric detection, the gold electrodes are used at the same time for dielectric actuation and control of the mechanical resonance [24]. Applying a DC bias to one of the electrodes induces an electric polarization in the dielectric silicon nitride string, which, in turn, couples to the gradient of the inhomogeneous electric field, generating a gradient force. Adding a resonant sinusoidal RF drive tone with frequency \( \omega_m / 2\pi \) to the DC voltage at a bias tee results in a periodic force which drives the vibrational resonance of the nanomechanical silicon nitride string resonator [25]. Approximating the induced electrical polarization by a dipole moment [24, 25], its magnitude scales linearly with the applied DC voltage. Since the electric field gradient is also directly proportional to the DC voltage, the resonance frequency of the nanomechanical string resonator shifts quadratically with the applied DC bias [24]. By means of careful sample design, the in-plane polarized vibration mode can be engineered to shift downwards in resonance frequency with increasing DC bias, whereas the out-of-plane polarized resonance tunes towards higher resonance frequencies [24]. Thereby, the inherent resonant frequency off-set between the two orthogonally polarized vibration modes, which arises from the rectangular cross-section of the nanomechanical string, can be compensated. Near resonance, the two modes hybridize into normal modes [6, 7, 26] of the strongly coupled system, diagonally polarized along \( \pm 45^\circ \) with respect to the sample plane. The strong coupling, mediated by the inhomogeneous electric field [22, 26], is reflected by the pronounced avoided crossing of the two mechanical modes with level splitting \( \Delta/2\pi \) as depicted in figure 2(a).

**Figure 1.** Schematic experimental set-up. (a) False color scanning electron micrograph of a 50 \( \mu \)m long, 270 nm wide and 100 nm thick silicon nitride string resonator (green) in oblique view. The mechanical resonator is flanked by two 1 \( \mu \)m wide gold electrodes (yellow), which are processed on top of the silicon nitride and form a capacitor providing dielectric drive, tuning and detection as well as mode coupling. (b) Schematic illustration of the two orthogonally polarized fundamental flexural vibration modes of the silicon nitride string resonator. The oscillation in z-direction, perpendicular to the sample plane, is referred to as out-of-plane oscillation, whereas the oscillation in y-direction, parallel to the sample plane, is referred to as in-plane oscillation. (c) Schematic equivalent circuit diagram of the electrical drive, tuning and heterodyne detection scheme. The voltage ramp is added to the DC tuning voltage by a summation amplifier and combined with the resonant sinusoidal RF drive tone at a bias tee. The combined voltages are applied to one of the gold electrodes versus the ground of the microwave cavity. The bypass capacitor acts as a ground for the microwave cavity. The microwave cavity is driven on resonance and the signal is read-out via a heterodyne IQ-mixing technique, demodulating the sidebands induced by the oscillation of the nanomechanical resonator.
The experiment is repeated for a set of different voltage sweep rates at a fixed peak voltage. Consequently, we use the term measurement scheme instead of return probability. For each particular measurement, the voltage ramp has a fixed voltage sweep rate $\beta$ and fixed peak voltage $U_p$. The experiment is repeated for a set of different voltage sweep rates at a fixed peak voltage. Subsequently, the peak voltage is changed and the measurement procedure is repeated. In this way, we investigate classical St"uckelberg interferometry as a function of sweep speed and sweep distance which can be absorbed into a single variable, namely time.

Figure 2. Avoided crossing and voltage ramp sequence. (a) Avoided energy level crossing of the two frequency branches (mode 1: blue, mode 2: red) which stem from the two orthogonally polarized flexural modes. Gray dashed lines indicate the initialization voltage $U_i$ at which the two modes exhibit a frequency splitting of $\Delta/2\pi$. (b) Temporal evolution of the voltage ramps (blue solid line) defined by the sweep voltage. The ramp starts at $t = t_{\text{start}}$. The sweep voltage is increased from zero to peak voltage $U_F$ at sweep rate $\beta$, which increases the sweep voltage from $U_i$ to $U_F$. At the apex of the triangular voltage ramp (peak voltage $U_p$), the sweep voltage is decreased at the same rate to the read-out voltage $U_r$ which is approached at time $t = t_\phi$. Hence, the complete triangular voltage ramp has a duration of $\phi$. Note that the read-out voltage $U_r$ is off-set from the initialization voltage $U_i$, as explained in the text. As a consequence, the sweep voltage does not return to zero. The ring-down of the mechanical signal power (green dashed line) is measured after a delay $\varepsilon$ (at time $t = t_{\phi+\varepsilon}$), and a fit (black dotted line) is used to extract its magnitude at time $t = t_\phi$. The measured return signal is normalized to the mechanical signal power at $t = t_{\text{start}}$. 

3.2. Measurement scheme

Experimentally, we realize the double passage of the avoided crossing using fast triangular voltage ramps [9]. The voltage ramps are provided by an arbitrary function generator (AFG) and combined with the fixed DC tuning voltage at a summation amplifier. A detailed description of the ramps can be found in appendix C. In the following, we focus solely on the measurement principle. Note that the presented voltage ramp sequence [9] is analogous to the one employed by Sun et al [27] and differs from the frequently performed periodic driving schemes in St"uckelberg interferometry experiments [16]. The schematic sequence of the applied voltage ramp is depicted in figure 2(b). The system is initialized in the lower frequency branch at $\omega_i(U_i)/2\pi$ by the application of a resonant sinusoidal RF drive tone. Hereby, $U_i$ denotes the initialization voltage to which the DC tuning voltage is set during a St"uckelberg experiment. Note that this voltage corresponds to a sweep voltage of zero. The sweep voltage defines the additional ramp voltage provided by the AFG. At $t = t_{\text{start}}$, the fast voltage ramp is turned on and detunes the system from the resonant drive at $\omega_i(U_i)/2\pi$. From this time on, the mechanical resonator is not driven any more and its oscillation decays exponentially (green dashed line in figure 2(b)). Note that the mechanical energy decays on a larger timescale than the duration of the fast voltage ramp. The sweep voltage ramps the system from $U_i$ through the avoided crossing at voltage $U_a$, up to the absolute peak voltage $U_F = U_a + U_p$ and back to the read-out voltage $U_r$ during time $\phi$. At time $t = t_{\phi+\varepsilon}$, we start to measure the exponential decay of the mechanical oscillation at frequency $\omega_i(U_i)/2\pi$ in the lower branch at the read-out voltage $U_r$. The return signal needs to be measured at $U_i$ since the drive at $\omega_i(U_i)/2\pi$ cannot be turned off during the experiment. Hence, a measurement at $U_i$ would lead to another excitation of the mode and therefore destroy the interference. Additionally, the exponential decay of the return signal power needs to be measured with a temporal off-set $\varepsilon$ to avoid transient effects. The exponential decay is extrapolated back to the time $t_\phi$ where the voltage ramp ended via a fit and the resulting return signal power is normalized to the signal power at the time of initialization of the resonance ($t = t_{\text{start}}$). This normalization process can lead to return probabilities exceeding a value of unity due to experimental scatter and different characteristic signal power heights at the initialization and read-out voltage. Consequently, we use the term normalized squared return amplitude for the experimental data instead of return probability.

For each particular measurement, the voltage ramp has a fixed voltage sweep rate $\beta$ and fixed peak voltage $U_p$. The experiment is repeated for a set of different voltage sweep rates at a fixed peak voltage. Subsequently, the peak voltage is changed and the measurement procedure is repeated. In this way, we investigate classical St"uckelberg interferometry as a function of sweep speed and sweep distance which can be absorbed into a single variable, namely time.
In previous approaches [16], Stückelberg interferometry has been investigated in the limit of infinite times. This means the initialization and turning point on the left and the right-hand side of the avoided crossing are far away from its center, which is at voltage $U_c$. This infinite-time approximation is referred to as the adiabatic impulse model [16] and is summarized in section 2.4. In this work, we go beyond this approximation via the investigation of finite-time effects. We describe the interference of the two modes by the exact finite-time evolution of the system along the two frequency branches depicted in figure 2(a). Since each particular mode acquires a certain phase during the temporal evolution along its respective frequency branch, interference occurs as soon as the modes start to hybridize. Hence, finite-time dynamics of the nanomechanical two-mode system results in characteristic Stückelberg oscillations without the explicit need of traversing the avoided crossing. Experimentally, we access this regime by turning points, i.e. peak voltages, close to or even before the avoided crossing.

4. Comparison of experiment and theories

4.1. Stückelberg oscillations

In this chapter, we compare the experimental results with the theoretical models from section 2. The measurements are performed at room temperature in a vacuum chamber with pressure $\leq 10^{-4}$ mbar to avoid damping of the mechanical resonator by surrounding gas molecules. The 55 $\mu$m long nanomechanical string resonator exhibits a linewidth of the mechanical resonance $\Gamma/2\pi \approx 25$ Hz at the out-of-plane resonance frequency $\omega_\ell(U_l)/2\pi = 6.561$ MHz and hence a mechanical lifetime of 6.21 ms. Here, $U_l = 10.4$ V is the initialization voltage. The two strongly coupled mechanical modes exhibit a frequency splitting of $\Delta/2\pi = 6.3$ kHz at the avoided crossing voltage $U_a = U_l + 1.96$ V = 12.36 V.

The system is initialized in the lower frequency branch at $U_l$ before a fast triangular voltage ramp with peak voltage $U_p$ sweeps the system to $\tilde{U}_p$ and back to the read-out voltage $U_f = U_l + 0.5$ V = 10.9 V at a constant voltage sweep rate $\beta$. Note that we employ the frequency sweep rate $\alpha$ in the theory which is converted to the experimentally accessible voltage sweep rate $\beta$ using the conversion factor $\zeta$ from frequency to voltage (see [9]):

$$\alpha = 2\pi \times \zeta \times \beta.\quad (26)$$

The conversion factor from frequency sweep rate $\alpha$ to voltage sweep rate $\beta$ is determined from the avoided crossing via a linear fit [9] as $\zeta = 19$ kHz V$^{-1}$.

The accumulation of phase and hence the state interference is determined by the exact evolution of the two frequency branches in time in combination with the coupling of the modes. This dependence can be absorbed in characteristic times and an effective coupling $\eta$, determined by the sweep rate and the voltages of initialization, avoided crossing, turning-point and read-out:

$$t_i = -\frac{1}{\beta}(U_a - U_l) = \frac{\tau_i}{\sqrt{\alpha}}$$

$$t_p = \frac{1}{\beta}(\tilde{U}_p - U_a) = \frac{\tau_p}{\sqrt{\alpha}}$$

$$t_f = \frac{1}{\beta}(U_a - U_f) = \frac{\tau_i}{\sqrt{\alpha}}$$

$$\eta = \frac{\Delta}{\sqrt{2\pi\zeta\beta}} = \frac{\Delta}{\sqrt{\alpha}}.\quad (27)$$

Note that in the definition of $t_p$, the absolute peak voltage $\tilde{U}_p$ appears instead of the peak voltage of the applied voltage ramp $U_p$ (see figure 2(b)).

In order to investigate the validity of the different theoretical approaches, we perform Stückelberg interferometry experiments for a large set of peak voltages $U_p$ and voltage sweep rates $\beta$. In particular, we study the finite-time dynamics of the system for absolute peak voltages, i.e. turning points, close to the avoided crossing and even observe interference without traversing the latter. Figure 3(a) depicts a color-coded two-dimensional map of the normalized squared return amplitude in dependence of the inverse voltage sweep rate $1/\beta$ and the peak voltage $U_p$. The experimental data in figure 3(a) is smoothed by a moving average of 10 points in each horizontal line for reasons of illustration. The original non-averaged data is presented in appendix D together with further information on the averaging. The gray dotted line indicates the avoided crossing voltage $U_a$. We observe clear interference fringes in the normalized squared return amplitude. The lowest destructive interference fringe extends beyond the line of the avoided crossing and we find a reduced normalized squared return amplitude even for absolute peak voltages near or smaller than the avoided crossing voltage ($\tilde{U}_p \leq U_a$). This fact shows that the two modes interfere without the explicit need of traversing the avoided crossing and hence underlines the existence of finite-time dynamics in Stückelberg interferometry. Furthermore, this result
flaws the assumptions of the adiabatic impulse model that all non-adiabatic transitions occur at the avoided crossing and that phase is only accumulated between the two transitions. Explicitly, phase is accumulated along both frequency branches and the interference is determined from finite-time effects. Calculating the theoretical return probability using the exact finite-time solution from equation (16) with no free parameters yields good qualitative agreement between experiment and theory as displayed in figure 3(b). Similar to the experimental data, the self-interference of the two-mode system extends beyond the gray dotted line which represents the position of the avoided crossing at voltage $U_a$. Because of the long duration ramps applied to the sample (up to $\beta = 1.0$ ms), the mechanical damping needs to be taken into account. Modeling the mechanical damping by an exponential decay with average energy decay time $\tau_0 = 5.7$ ms, the evolution of the modes after the double sweep through the avoided crossing is given by
\[
|c_j(t)|^2 = \exp[-t/\tau_0]P_{1 \rightarrow j},
\]
(28)
with $P_{1 \rightarrow j}$ the return probability to mode $j = 1$ or $j = 2$. Note that equation (28) is applied to all three different theoretical approaches in figures 3(b)–(d).

The theory exhibits distinct features in the interference pattern, e.g., the plateau in the theoretical return probability in the region of $1/\beta \approx 65$ $\mu$s $V^{-1}$, which are not reproduced by the experiment. In order to experimentally resolve these features, the system needs to interfere precisely with the same set of constant experimental device parameters in every particular measurement pixel from figure 3(a). Since the experiments are performed at room temperature, the system parameters vary strongly from measurement to measurement due to temperature fluctuations. Experimentally, we partially account for this effect by the implementation of an initialization voltage feedback loop [9], which ensures the initialization of the system at the same resonance frequency, at least within one horizontal line from figure 3(a). Nevertheless, the fluctuations and uncertainties

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**Figure 3.** Comparison of experiment and different theoretical models on Stückelberg interferometry. (a) Color-coded (left colorbar) normalized squared return amplitude versus peak voltage $U_p$ and inverse sweep rate $1/\beta$. The experimental data is smoothed by a moving average of 10 points in each horizontal line for illustration reasons. Details on the averaging and the non-avedaged data can be found in appendix D. Gray dotted line indicates the position of the avoided crossing at voltage $U_a = 1.96$ V in all sub-panels. (b)–(d) Color-coded theoretical return probability (right colorbar) calculated from a single set of parameters, extracted from the experimental data, for the exact finite-time solution (b) the asymptotic theory (c) and the adiabatic impulse model (d). The mechanical damping is modeled according to equation (28) in all theory plots (b)–(d). Note that the adiabatic impulse model (d) is plotted for the same parameter range without respect to the physical validity in certain ranges. The black dashed line indicates the regime where $\tau_0 > \tau_{cut}$ (see section 4.3 and appendix A). Above this line, the adiabatic impulse model (infinite-time limit) applies. The region for absolute peak voltages $U_p < U_a$ is manually grayed out as explained in the text.
prevent the system from interfering with the precise same parameters in every particular measurement. Further information on the experimental uncertainties is provided elsewhere [9]. Note that the experimental data in figure 3(a) is taken in a non-consecutive way over a timespan of approximately 6 months which clearly demonstrates the validity of the data.

The results for the asymptotic theory (appendix A) are depicted in figure 3(c). The asymptotic theory reproduces the exact finite-time solution with excellent agreement over the full displayed parameter range. Consequently, one can exploit the piecewise definition of the asymptotic theory in appendix A to deduce the characteristic dynamics of the system in each particular parameter regime. A detailed discussion of the different regimes will be given in section 4.3.

Figure 3(d) depicts the return probability calculated from the adiabatic impulse model (equation (25)) using the same parameters as for the exact solution (equation (16)). The model is depicted for the complete experimentally investigated parameter regime. However, certain displayed parameter ranges violate the basic assumptions of the adiabatic impulse model that the dynamics of the system is fully adiabatic and governed by ‘infinite times’ as described in section 2.4. In principle, there is no sharp transition for the validity of the model since it applies for $\eta/\tau \ll 1$. As a guide to the eye, the black dashed line indicates the limit of long times where $\tau_p > \tau_{\text{cin}}$ as will be explained in section 4.3 and appendix A. Above this line, the system operates in the long-time limit from which the infinite-time limit and hence the adiabatic impulse model can be recovered. Below this line, the system dynamics is governed by finite times and the adiabatic impulse model is not defined. Additionally, the region below the avoided crossing voltage (gray dotted line) in figure 3(d) is grayed out manually. The reason is that the result of equation (25) is unphysical for the region where $U_p > U_s$ since the definition of the adiabatic impulse model requires traversing the avoided crossing.

In general, we observe a clear deviation between the adiabatic impulse model and both, the experimental data and the exact solution. In particular, the interference fringes of figure 3(d) vanish for peak voltages in the region of the avoided crossing, when the dimensionless time of the phase evolution $\tau_p$ becomes comparable to the dimensionless level splitting $\eta$. This discrepancy clearly demonstrates that the dynamics of the system cannot be generally described by an infinite-time approach where the two-mode interference is solely governed by the coupling of the system. However, for peak voltages, i.e., turning points far away from the avoided crossing above the black dashed line, the result of the adiabatic impulse model qualitatively resembles the result obtained by the exact solution and the experimental data. The characteristic features which appear in the exact solution and the asymptotic theory, e.g., the plateau in the theoretical return probability, are not recovered from the adiabatic impulse model. As detailed in appendix B, the adiabatic impulse model corresponds to the zeroth order series expansion of $\cos(\theta(\tau))$ and $\sin(\theta(\tau))$ in the long-time limit of the asymptotic solution. Taking into account higher order corrections to the return probability would result in the appearance of the distinct features of the exact solution in the extended adiabatic impulse model.

4.2. Interference visibility

In order to study the crossover from the infinite-time limit to the finite-time domain in more detail, we extract the interference visibility in dependence of the peak voltage from the experimental data and the different theoretical approaches. Note that by interference visibility we refer to the original definition of interference contrast [35] and not to the single-shot read-out-visibility as frequently referred to in, e.g., spin systems [36]. The interference visibility from the experimental data for a given peak voltage is calculated from the corresponding horizontal line-cut in figure 3(a) by the difference of the maximum and minimum normalized squared return amplitude divided by their sum [35]. Figure 4 depicts the interference visibility as a function of peak voltage for the experimental data (blue dots) and the different theoretical models. Since the theoretical models represent real probabilities, we associate the interference visibility with the interference contrast, which is the difference of the maximum and the minimum return probability without a normalization to their sum. The exact solution (red solid line, equation (16)) clearly exhibits a non-zero interference visibility for a set of peak voltages smaller than the avoided crossing voltage $U_s$ (gray dotted vertical line) in good agreement with the experimental data. The interference visibility obtained from the return probability in the asymptotic theory (green dashed line) nearly coincides with the result of the exact finite-time solution. The underlying agreement clearly demonstrates that the exact solution of the double passage Stueckelberg problem can be well-approximated by taking the asymptotic limit of the parabolic cylinder functions in the appropriate parameter regime. Furthermore, the analysis confirms the appearance of interference for peak voltages before the avoided crossing. In contrast, the adiabatic impulse model (black dotted line, equation (25)) interference visibility drops down close to zero for peak voltages smaller than $U_p \approx 2.0$ V, such that $\tilde{U}_p \approx U_s$. Again, one has to note that the adiabatic impulse model is not valid for the entire displayed parameter space and hence its interference visibility in the finite-time regime is just an extrapolation of equation (25).

To obtain a more intuitive understanding of the interference visibility in terms of finite times, we replace the parameter $U_p$ by introducing the ratio between two characteristic dimensionless scales, which are the
dimensionless time $\tau_p$ and the dimensionless coupling $\eta$ (see top x-axis in figure 4). As explained above (equation (27)), $\tau_p$ corresponds to the distance from the avoided crossing to the turning point of the double sweep and hence becomes negative for sweeps where the avoided crossing is not passed (see top axis in figure 4). The dimensionless coupling $\eta$ represents the effective level splitting between the two modes and is itself independent of the turning point in the double sweep (see equation (27)). Consequently, a characteristic dimensionless ratio of $\tau_p/\eta = 1$ would correspond to a population transfer from the lower to the upper mode with fidelity of 100% using the generic picture of the Bloch sphere [37, 38] in the classical two-mode system [22].

Losely speaking, the system has enough 'time' to perform a complete population transfer to the upper mechanical mode when initialized in the lower mode. In principle, this characteristic behavior can be extracted from the interference visibility depicted in figure 4. For $\tau_p/\eta = 1$ the interference visibility of the experimental data (blue dots) and the exact theoretical finite-time solution (red solid line) reaches a maximum which is close to unity. At this point, we recover the full interference contrast since the two modes have the ability to interfere fully destructive due to the possibility of a complete population transfer. However, the interference visibility extracted from the theory saturates to a value of approximately 94% whereas the experimental data converges to 100% visibility. The origin of this discrepancy in the theory is attributed to the fact that the interference pattern in figure 3(b) is calculated for the parameter range in which the experiment is conducted. The fastest voltage sweeps are performed at an inverse sweep rate of $1/\beta = 3 \text{ } \mu\text{s}^{-1}$. Whereas experimental scatter of the data allows for a visibility of 100%, the theory does not incorporate sufficiently fast sweeps to return to the same mode with a probability of unity. The sweeps are not non-adiabatic enough. In the limit $1/\beta \rightarrow 0$, the theory would simultaneously exhibit a 100% visibility at $\tau_p/\eta = 1$. For $\tau_p/\eta \gg 1$ the theory curve also converges to 100% visibility since the horizontal line-cuts from figure 3 intersect at least one constructive and one destructive interference fringe. Furthermore, we observe a reduced interference visibility in certain regions, where the return probability does not completely drop down to zero. We attribute this to the hyperbolic shape of the observed interference fringes in the displayed parameter space representation of the return probability as a function of inverse sweep rate and peak voltage. One could easily find horizontal line-cuts in figure 3 where the return probability does not completely drop down to zero, which translates into a reduced interference visibility. The distinct physical origin of this reduction in interference visibility remains subject of further experimental and theoretical investigations.

In contrast to the above findings, the interference visibility extracted from the adiabatic impulse model (black dotted line) peaks for a larger ratio of $\tau_p/\eta \approx 1.5$, which clearly demonstrates that this model is only valid if the turning point is far away from the avoided crossing, i.e., $\eta/\tau_p \ll 1$. However, we recover qualitatively similar dips in the interference visibility as in the exact finite-time solution and the experimental data.

For larger ratios of $\tau_p/\eta$, i.e. $\eta/\tau_p \ll 1$, the interference visibility extracted from the adiabatic impulse model coincides with the exact finite-time solution. This result is in excellent agreement with the definition of the adiabatic impulse model as the infinite-time limit of the finite-time Stückelberg theory (see section 2.3.2). As a consequence, the results obtained from the interference visibility allow for an estimation where finite-time effects become important in Stückelberg interferometry, which is for $\tau_p/\eta \lesssim 2$. 

**Figure 4.** Interference visibility. Interference visibility as a function of peak voltage $U_p$ (bottom axis) and characteristic dimensionless ratio $\tau_p/\eta$ (top axis) extracted from horizontal line-cuts of figures 3(b)–(d) for the exact theoretical solution (red solid line), asymptotic theory (green dashed line) and adiabatic impulse model (black dotted line). Blue dots depict the interference visibility calculated from the averaged experimental data in figure 3(a) as described in the text and appendix D.
4.3. Parameter regimes

In this section, we exploit the piecewise definition of the asymptotic limit of the exact theoretical finite-time solution given in appendices A and B to quantify specific parameter regimes of Stückelberg interferometry. Depending on the specific regime, the characteristic times (equation (27)) are limited to certain boundaries. These boundaries, in turn, allow for the quantification of the underlying physics governing the coupled system dynamics and hence the role of finite-time dynamics in the respective regime.

In order to asymptotically expand the parabolic cylinder functions, we define a critical dimensionless time $t_{\text{crit}}$. This critical dimensionless time serves as a measure for the employed dimensionless times $t_i$, $t_p$, and $t_f$ in the theory. Those parameters can either be bound by $t_{\text{crit}}$ ($-t_{\text{crit}} \leq \tau \leq t_{\text{crit}}$) or unbound ($|\tau| > t_{\text{crit}}$). Here, one should keep in mind that $t_i$ is defined as smaller than zero. If the parameters are bound, the system undergoes finite-time dynamics whereas it can be approximated by the adiabatic impulse model in the unbound case. As further discussed in appendix A, the parabolic cylinder functions can mathematically be approximated by a power series. Hereby, the magnitude of $t_{\text{crit}}$ specifies up to which order the power series is expanded. For the following calculations we defined $t_{\text{crit}} = 2$.

Figure 5 depicts the theoretical return probability calculated from the asymptotic theory as in figure 3(c) for an extended peak voltage range. The layover in figure 5 displays the boundary lines of the different parameter regimes in the asymptotic theory. The different parameter regimes are labeled by roman numerals which are elucidated in table 1.

![Figure 5](image-url)  
Figure 5. Phase space of the parameter regimes in the asymptotic theory. Color-coded theoretical return probability as calculated from the asymptotic theory (see figure 3(c)) for an extended peak voltage range. Black dashed lines indicate the border-lines of the different parameter regimes in the asymptotic theory. The different parameter regimes are labeled by roman numerals which are elucidated in table 1.

| Regime | $t_i$ | $t_p$ | $t_f$ |
|-------|------|------|------|
| I     | $-t_{\text{crit}} \leq t_i \leq t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_p \leq t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_f \leq t_{\text{crit}}$ |
| II    | $t_i < -t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_p \leq t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_f \leq t_{\text{crit}}$ |
| III   | $t_i < -t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_p \leq t_{\text{crit}}$ | $t_f > t_{\text{crit}}$ |
| IV    | $t_i < -t_{\text{crit}}$ | $t_p > t_{\text{crit}}$ | $t_f > t_{\text{crit}}$ |
| V     | $t_i < -t_{\text{crit}}$ | $t_p > t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_f \leq t_{\text{crit}}$ |
| VI    | $-t_{\text{crit}} \leq t_i \leq t_{\text{crit}}$ | $t_p > t_{\text{crit}}$ | $t_f > t_{\text{crit}}$ |

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| Table 1. Summary of the different asymptotic regimes. |
|--------|--------|--------|--------|--------|
| Regime | $t_i$ | $t_p$ | $t_f$ |
| I      | $-t_{\text{crit}} \leq t_i \leq t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_p \leq t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_f \leq t_{\text{crit}}$ |
| II     | $t_i < -t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_p \leq t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_f \leq t_{\text{crit}}$ |
| III    | $t_i < -t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_p \leq t_{\text{crit}}$ | $t_f > t_{\text{crit}}$ |
| IV     | $t_i < -t_{\text{crit}}$ | $t_p > t_{\text{crit}}$ | $t_f > t_{\text{crit}}$ |
| V      | $t_i < -t_{\text{crit}}$ | $t_p > t_{\text{crit}}$ | $-t_{\text{crit}} \leq t_f \leq t_{\text{crit}}$ |
| VI     | $-t_{\text{crit}} \leq t_i \leq t_{\text{crit}}$ | $t_p > t_{\text{crit}}$ | $t_f > t_{\text{crit}}$ |
interferometry [16], except for the work of Vitanov et al [19] and [12, 39]. Nevertheless and as one can easily
deduce from figure 5, a complete solution of the double passage Stückelberg problem is in crucial need of
additional parameter regimes, where the finite durations of the sweeps play a major role.

The transition from the long-time limit to the finite-time domain is represented by the hyperbolic black
dashed line in figure 5. Associating a threshold peak voltage $U_{p, \text{crit}}$ with this transition, one can easily calculate
the border-line as a function of inverse sweep rate via the definition of $\tau_\text{f}$ (see equations (27)) and $\tau_{\text{crit}} = 2$

$$U_{p, \text{crit}} = \sqrt{\frac{2}{\pi \zeta}} \frac{1}{\sqrt{1/\beta}} + (U_h - U_i)$$

$$\approx \sqrt{\frac{2}{\pi \zeta}} \frac{1}{\sqrt{1/\beta}} + 1.96 \text{ V.} \quad (29)$$

Accordingly, the two vertical border-lines in figure 5, which are independent of the peak voltage
$$(1/\beta)_h = 8.64 \mu \text{s V}^{-1}, (1/\beta)_l = 15.58 \mu \text{s V}^{-1},$$
can be calculated straightforwardly from equation (27). Note
that for $\tau_i = -\tau_\text{f}$, i.e., if the system could be read-out at the initialization point after a symmetric voltage ramp,
the right vertical border-line in figure 5 would vanish. Even though regime II and regime V are exclusively
observed in our particular measurement scheme, the importance of finite-time effects in Stückelberg
interferometry is definitely pointed out by the presence of regimes I, III and VI. Especially regime I and III are of
great interest since they reveal the dynamics of Stückelberg interferometry between two strongly coupled modes
without the explicit need of traversing the avoided energy level crossing.

Since the dynamics of the strongly coupled classical two-mode system can be mapped onto the dynamics of
a quantum mechanical two-level system in Stückelberg interferometry [9], the same regimes are existent in every
quantum mechanical two-level system such as e.g. superconducting qubits [13–15, 17] or spin-1/2 systems [10–
12]. To the best of our knowledge, such regimes have so far not been investigated in the framework of
Stückelberg interferometry and might be a prominent candidate for future investigations of quantum two-level
systems.

5. Conclusion

In conclusion, we have demonstrated the importance of finite times in Stückelberg interferometry. Discussing a
complete and exact theoretical solution to the double passage Stückelberg problem, we have shown that the
commonly employed adiabatic impulse model [16] does not address the full complexity of the problem [18]. In
particular, the adiabatic impulse model solely describes one single parameter regime, where the dynamics of the
system is completely governed by the coupling of the two modes corresponding to an infinite-time limit. By
asymptotically expanding the exact finite-time Stückelberg return amplitudes, we have classified previously
undiscovered parameter regimes in Stückelberg interferometry. The theoretical findings have been confirmed in
good qualitative agreement by a detailed experimental study of the dynamics of a classical two mode system
[22, 29] realized by two strongly coupled high quality factor nanomechanical string resonator modes. All
theoretically predicted parameter regimes have been demonstrated experimentally by a thorough investigation
of classical Stückelberg interferometry [9]. We observed clear oscillations in the experimentally accessible
normalized squared return amplitude, even without traversing the avoided crossing in good agreement with the
exact theory. These findings have been supported by a detailed study of the interference visibility over a huge
parameter range. Interestingly, the dynamics of the investigated classical two-mode system can be mapped to the
dynamics of quantum mechanical two-level systems, as has recently been demonstrated by the authors [9]. As a
consequence, the above theoretical findings can be applied one-to-one to quantum mechanical two-level
systems.

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Appendix A. Asymptotic expansion of the parabolic cylinder function

In this section we list the asymptotic expansions used to produce figures 3(c) and 5.
A.1. Short-time expansion
When $-\tau_{\text{crit}} < \tau < \tau_{\text{crit}}$, one can approximate parabolic cylinder functions by a power series. In this work we used one of the power series derived in [40]

$$D_n(\tau) = \sqrt{2\pi} \exp \left( \frac{\tau^2}{4} \right) \sum_{n=0}^{\infty} \frac{(-\sqrt{2} \tau)^n}{n! \Gamma \left( \frac{1}{2} (1 - \nu - n) \right)}.$$ (A.1)

This expansion is particularly useful when $|\tau_{\text{crit}}| < 1$ since the series can be truncated after a few terms.

Here, we are going to choose $|\tau_{\text{crit}}| = 2$. While we will not be able to truncate the series to only one or two terms, we will be able to approximate the parabolic cylinder functions with only two different functions. The special values $|\tau_{\text{crit}}| = 2$ correspond then to the point where the functions are matched.

A.2. Long-time expansion
When $\tau > 1$, one can use the results of [41] to find asymptotic expansions for the relevant parabolic cylinder functions involved in equations (12) and (13). The asymptotic expansions are

$$D_{i\frac{1}{4} - i\frac{1}{2} \tau}^\downarrow (e^{i\frac{1}{2} \tau}) \simeq \frac{2}{\eta} \sin[\theta(\tau)] \exp \left[ -\frac{\pi \eta^2}{16} - i \left( \xi(\tau) + \frac{\pi}{4} \right) \right],$$

$$D_{i\frac{1}{4} - i\frac{1}{2} \tau}^\uparrow (e^{-i\frac{1}{2} \tau}) \simeq \frac{2}{\eta} \sin[\theta(\tau)] \exp \left[ -\frac{3 \pi \eta^2}{16} - i \left( \xi(\tau) - \frac{3 \pi}{4} \right) \right],$$

$$D_{i\frac{1}{4} - i\frac{1}{2} \tau}^\downarrow (e^{-i\frac{1}{2} \tau}) \simeq \cos[\theta(\tau)] \exp \left[ -\frac{3 \pi \eta^2}{16} - i \xi(\tau) \right],$$

$$D_{i\frac{1}{4} - i\frac{1}{2} \tau}^\uparrow (e^{i\frac{1}{2} \tau}) \simeq \cos[\theta(\tau)] \exp \left[ \frac{\pi \eta^2}{16} - i \xi(\tau) \right],$$ (A.2)

where we have defined

$$\sin[\theta(\tau)] = \sqrt{\frac{1}{2} \left( 1 - \frac{\tau}{\sqrt{\tau^2 + \eta^2}} \right)},$$

$$\cos[\theta(\tau)] = \sqrt{\frac{1}{2} \left( 1 + \frac{\tau}{\sqrt{\tau^2 + \eta^2}} \right)},$$

$$\xi(\tau) = -\frac{\eta^2}{8} + \frac{\eta^2}{4} \log \left[ \frac{1}{2} (\tau + \sqrt{\tau^2 + \eta^2}) \right] + \frac{\tau}{4} \sqrt{\tau^2 + \eta^2}. \quad \text{(A.3)}$$

Note that this expansion is employed for $\tau \gg \tau_{\text{crit}}$.

A.2.1. ‘Negative’ long-time expansion. To obtain the asymptotic expansions for negative arguments, $\tau < 0$ and $|\tau| > 1$, one substitutes $\tau \rightarrow e^{i\pi} |\tau|$ in the argument of the functions to be expanded. With this substitution, the problem is reduced to the cases presented in equation (A.2).

A.2.2. Expansion of $[D_n(\tau)]^*$. Since the parabolic functions are analytic, we have $[D_n(\tau)]^* = D_n^*(e^{i\theta})$. As a consequence, the asymptotic expansion of $D_n(\tau)$ is the complex conjugate of the asymptotic expansion of $D_n(\tau)$.

Appendix B. Leading order correction to the return probability in the infinite-time limit

As explained in the main text, we have defined the infinite-time limit as $\eta/\tau$, $\eta/|\tau|$, $\eta/\overline{\tau} \ll 1$. To obtain the first-order correction to equation (19), we use equations (17) and (18) and expand $\cos[\theta(\tau)]$ and $\sin[\theta(\tau)]$ in powers of $\eta/\tau$. In contrast to what has been presented in the main text, we keep the lowest contribution in $\eta/\tau$. 

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We find
\[ \cos[\theta(\tau)] = 1 - \frac{1}{8} \frac{\eta^2}{\tau^2} + \mathcal{O}\left(\frac{\eta^3}{\tau^4}\right) \] (B.1)

and
\[ \sin[\theta(\tau)] = \frac{1}{2} \frac{\eta}{\tau} + \mathcal{O}\left(\frac{\eta^3}{\tau^4}\right). \] (B.2)

We find that the leading order correction is given by
\[
P_{1\rightarrow 1}^{(1)} = \frac{\eta}{\sqrt{2}} \sqrt{P_{LZ} \sqrt{1 - P_{LZ}}}
\times \left\{-2 \cos[\xi(\tau) - \xi(\tau_i)] \left[ P_{LZ} (\sin[\chi_1(\tau, \tau_i)] - \cos[\chi_1(\tau, \tau_i)]) + (1 - P_{LZ})(\cos[\chi_2(\tau, \tau_p, \tau_i)] + \sin[\chi_2(\tau, \tau_p, \tau_i)]) \right]
+ 2 \cos[\xi(\tau) - \xi(\tau_p)] \left[ P_{LZ} (\sin[\chi_3(\tau, \tau_p)] + \cos[\chi_3(\tau, \tau_p)]) + (1 - P_{LZ})(\cos[\chi_4(\tau, \tau_p)] - \sin[\chi_4(\tau, \tau_p)]) \right]
- 2 \sin[\xi(\tau) - \xi(\tau_p)] \left[ 2 \cos[\xi(\tau) - \xi(\tau_p)] (\cos[\chi_5(\tau_p)] + \sin[\chi_5(\tau_p)]) \right.
- \left. \cos[\chi_6(\tau, \tau_p)] + \sin[\chi_6(\tau, \tau_p)] \right] \right\}, \] (B.3)

where we have defined
\[
\chi_1(\tau, \tau_i) = \xi(\tau) + \xi(\tau_i) - \arg\left[ \Gamma\left(1 + i \frac{\eta^2}{4}\right) \right],
\chi_2(\tau, \tau_p, \tau_i) = \xi(\tau) + \xi(\tau_i) + 4 \xi(\tau_p) - 3 \arg\left[ \Gamma\left(1 + i \frac{\eta^2}{4}\right) \right],
\chi_3(\tau, \tau_p) = \xi(\tau) - 3 \xi(\tau_p) + \arg\left[ \Gamma\left(1 + i \frac{\eta^2}{4}\right) \right],
\chi_4(\tau, \tau_p) = \xi(\tau) + \xi(\tau_p) - \arg\left[ \Gamma\left(1 + i \frac{\eta^2}{4}\right) \right],
\chi_5(\tau_p) = 2 \xi(\tau_p) - \arg\left[ \Gamma\left(1 + i \frac{\eta^2}{4}\right) \right],
\chi_6(\tau_i, \tau_p) = \xi(\tau_i) + \xi(\tau_p) - \arg\left[ \Gamma\left(1 + i \frac{\eta^2}{4}\right) \right]. \] (B.4)

and \(\xi(\tau)\) is defined in equation (A.3).

If we define (see equation (19) in the main text)
\[
P_{1\rightarrow 1}^{(0)} = 1 - 4 P_{LZ} (1 - P_{LZ}) \cos^2[\chi_{dp}(\tau_p)] = P_{1\rightarrow 1}^{inf}, \] (B.5)

then the return probability to leading order in \(\eta/\tau, \eta/\tau_i, \eta/\tau_p\) is given by
\[
P_{1\rightarrow 1} = P_{1\rightarrow 1}^{(0)} + P_{1\rightarrow 1}^{(1)} + \mathcal{O}\left(\frac{\eta^2}{\tau^2}, \frac{\eta^2}{\tau_p}, \frac{\eta^2}{\tau_i}\right). \] (B.6)

Appendix C. Voltage ramps

The experimentally applied triangular voltage ramps are created numerically and fed to an arbitrary function generator (AFG). A schematic of the applied ramps is depicted in figure C1. The ramps consist of a total of 500 000 samples (500 kSa) divided into four basic regions. The first region is a \(t_{\text{trigger}} = 5\) ms long window in which a trigger command is sent from to the AFG to the spectrum analyzer to start the measurement, during which the additional ramp voltage is kept at zero and hence the absolute voltage is at base level \(U_i\) of the initialization voltage. The triangular voltage ramp itself (region two) consists in total of 1000 samples (1 kSa),
with 500 Sa per ramp flank. The sweep voltage is ramped up from zero to the peak voltage $U_p$ with sample rate

$$\text{Sample rate} = \frac{500 \text{ Sa}}{U_p \times 1/\beta},$$

(C.1)

from which we deduce the inverse sweep rate $1/\beta$. The corresponding ramp time is hence given by

$$t_{\text{ramp}} = \frac{500 \text{ Sa}}{\text{Sample rate}} = U_p \times 1/\beta.$$

(C.2)

The right-hand side flank of the triangular voltage ramp decreases the absolute voltage from $\tilde{U}_p$ to the read-out voltage $U_i$ which is off-set from the initialization voltage $U_i$ by $U_{\text{offset}} = 0.5$ V. As described in the main text, the exponential decay of the returning excitation has to be measured at a different read-out frequency since the resonant sinusoidal drive tone at fixed frequency $\omega_i(U_i)/2\pi$ cannot be turned off during the voltage ramp. Hence, the above introduced voltage off-set is employed. It is important to note that the voltage off-set has to be adjusted in such a way, that the mechanical resonance at the read-out voltage $\omega_i(U_i)/2\pi$ is not excited by the resonant drive tone at $\omega_i(U_i)/2\pi$. The exponential decay of the mechanical resonance after the triangular voltage ramp is measured in region three using a spectrum analyzer in a timespan of

$$t_{\text{readout}} = t_{\text{ramp}} \times \frac{\text{Total Samples}}{500 \text{ Sa}} = U_p \times 1/\beta \left( \frac{500 \text{ kSa}}{500 \text{ Sa}} - 2 \right).$$

(C.3)

After the measurement, the absolute voltage is ramped back from $U_i$ to the initialization voltage $U_i$ (region four) by decreasing the sweep voltage from $U_{\text{offset}}$ to zero, which takes 100 samples of the total sample number of 500 kSa.

**Appendix D. Moving average of the experimental data**

A moving average, also referred to as sliding average, is a statistical tool for the smoothing of datasets. Consider a dataset of $N$ elements. Then, a moving average of $M$ points creates $N - M$ subsets of elements, which are averaged individually. For each element $n \geq M$ of dataset $N$, the moving average yields the mean of the subset which consists of element $n$ and the preceding $M - 1$ elements in the dataset:

$$\bar{p}_n = \frac{1}{M} \sum_{i=0}^{M-1} p_{n-i}.$$  

(D.1)

Figure D1(a) depicts the non-averaged experimental raw data from which figure 3(a) has been produced. The gray dotted line indicates again the position of the avoided crossing at $U_p = 1.96$ V. As in figure 3(a) of the main text, we find the destructive interference to extend beyond the avoided crossing. However, experimental scatter and outliers stretch the color scale of the normalized squared return amplitude which affects the readability of the figure. Hence, a moving average over 10 points is applied to the experimental data. The effect of a moving average of 10 points on the experimental data is exemplarily depicted in figure D1(b). The dataset corresponds to the line-cut along the gray dotted line in figure D1(a) where $\tilde{U}_p \approx U_i$. 

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**Figure C1.** Illustration of the applied voltage ramps. The time axis is truncated as a guide to the eye since the read-out time $t_{\text{readout}}$ is much longer than the ramp time $t_{\text{ramp}}$. 

**Figure D1.** (a) Illustration of the applied voltage ramps. The time axis is truncated as a guide to the eye since the read-out time $t_{\text{readout}}$ is much longer than the ramp time $t_{\text{ramp}}$. (b) Moving average of the experimental data. A moving average, also referred to as sliding average, is a statistical tool for the smoothing of datasets. Consider a dataset of $N$ elements. Then, a moving average of $M$ points creates $N-M$ subsets of elements, which are averaged individually. For each element $n \geq M$ of dataset $N$, the moving average yields the mean of the subset which consists of element $n$ and the preceding $M-1$ elements in the dataset: $\bar{p}_n = \frac{1}{M} \sum_{i=0}^{M-1} p_{n-i}$. (D.1)
Figure D1. Non-averaged experimental data and illustration of the averaging. (a) Color-coded normalized squared return amplitude without averaging routine (see figure 3(a) of the main text) versus peak voltage $U_p$ and inverse sweep rate $1/\beta$. Gray dotted line indicates the position of the avoided crossing at voltage $U_p = 1.96$ V. (b) Exemplary line-cut taken along the gray dotted line in panel (a) for illustration of the averaging of the experimental data. Blue dots represent the experimentally determined normalized squared return amplitude versus inverse sweep rate $1/\beta$ for peak voltage $U_p \approx U_p'$. Yellow triangles correspond to the averaged data using a moving average of 10 points.

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