PROBING BROWNSTEIN–MOFFAT GRAVITY VIA NUMERICAL SIMULATIONS

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ABSTRACT

In the standard scenario of the Newtonian gravity, a late-type galaxy (i.e., a spiral galaxy) is well described by a disk and a bulge embedded in a halo mainly composed of dark matter. In Brownstein–Moffat gravity, there is a claim that late-type galaxy systems would not need to have halos, avoiding as a result the dark matter problem, i.e., a modified gravity (non-Newtonian) would account for the galactic structure with no need of dark matter. In the present paper, we probe this claim via numerical simulations. Instead of using a "static galaxy," where the centrifugal equilibrium of a particle of mass \( M \) reads

\[
\Phi(r) = -\frac{GM}{r} \left\{ 1 + \sqrt{\frac{M_0}{M}} \left[ 1 - \exp \left( -\frac{r}{r_0} \right) \right] \right\},
\]

where \( G \) is the Newtonian constant of gravity, \( r \) is the distance to the source, \( M_0 \) is a coupling parameter, and \( r_0 \) is a characteristic length. From the BM potential, the gravitational acceleration by a particle of mass \( M \) reads

\[
a(r) = -\frac{GM}{r} \left\{ 1 + \sqrt{\frac{M_0}{M}} \left[ 1 - \exp \left( -\frac{r}{r_0} \right) \left( 1 + \frac{r}{r_0} \right) \right] \right\}.
\]

1. INTRODUCTION

Spiral galaxies are very common in the universe. When studied with spectroscopic methods, these beautiful objects usually reveal that they rotate faster than they would do if only their visible matter were taken into account. This is the missing mass problem. It is generally believed that there is a dark matter component surrounding their disks, making them rotate that way. In other words, the canonical model says that spiral galaxy rotation curves inferred from observations could be accounted for by the dark matter halos that embed the galaxies (see, e.g., Sofue & Rubin 2001; van Albada et al. 1985). Therefore, this additional distribution of mass causes an additional acceleration which can account for the rotation curves.

This picture of the understanding of the structure of late-type morphologies finds support in the present canonical physics, which considers general relativity the most reliable theory of gravitation, and, as a consequence, due to the correspondence principle, Newtonian gravitation at the weak field limit.

However, in order to avoid the dark matter problem, many authors consider modifications in Newtonian gravity at large scales, in other words, they consider that, at galactic or even cosmological scales, the law of gravity is different from the Newtonian one. In this way, contrary to the dark matter paradigm, these authors argue that there is only a disk, but due to another kind of law of gravity at large scales, it could well rotate in accord with the observed rotation curves (see, e.g., Milgrom & Sanders 2005; Milgrom 2008; Moffat & Toth 2008, 2009; Brownstein & Moffat 2006a, and references therein).

It is worth mentioning that Brownstein & Moffat (2006b) also argue that it is possible to explain the X-ray cluster masses without dark matter using this very theory.

In particular, the present work is concerned with the study made by Brownstein & Moffat (2006a, hereafter BM), who present an alternative approach to explain the rotation curves of spiral galaxies, using an alternative theory of gravitation studied by Moffat & Toth (2008, hereafter Moffatian gravity). Our main aim is to probe this theory using numerical simulations.

The Moffatian gravity is a covariant theory of gravity based on the coupling of Einsteinian gravity with a massive skew symmetric field \( F_{\mu\nu} \). Here, we do not present and discuss this alternative theory of gravity in detail, since we are only concerned with its weak field limit.

BM claim that in the weak field limit the gravitational potential of a point source of mass \( M \) reads

BM state that the above equations hold in any environment. To apply these equations to model their rotation curves, they integrate these equations for a spherically symmetric system. As a result, they obtain the following equations:

\[
\Phi(r) = -\frac{GM(r)}{r} \left\{ 1 + \sqrt{\frac{M_0}{M}} \left[ 1 - \exp \left( -\frac{r}{r_0} \right) \right] \right\},
\]

and

\[
a(r) = -\frac{GM(r)}{r} \left\{ 1 + \sqrt{\frac{M_0}{M}} \left[ 1 - \exp \left( -\frac{r}{r_0} \right) \left( 1 + \frac{r}{r_0} \right) \right] \right\}.
\]

Now, the \( M \) outside the brackets becomes \( M(r) \), but the \( M \) inside the brackets does not change. Therefore, for given values of \( r_0, M_0 \), and \( M \) (the total mass of the system), the expression inside the braces depends only on \( r \). Assuming centrifugal equilibrium and a given mass distribution, i.e., \( M(r) \), BM model their rotation curves.

Also, note that Equation (4) obeys the superposition principle, which is an essential property if one intends to make use of \( N \)-body simulations.

We note from the above equations that the Moffatian gravity can be adjusted to a large range of lengths and masses, by means of the parameters \( r_0 \) and \( M_0 \), that depend on the system under investigation. Hence, they could, in principle, explain many physical effects that the canonical theory attributes to dark matter: galaxy rotation curves, galactic cluster masses, and
so on, because the BM’s parameters depend on the total mass of the system under study.

BM apply their modified gravity to explain the rotation curves of a sample of observed spiral galaxies and yield the following set of parameters, namely, \( M_0 = 96 \times 10^{10} M_\odot \) and \( r_0 = 13.96 \) kpc (Brownstein & Moffat 2006a). As usual in this kind of study, they consider centrifugal equilibrium, which means in the end that their galaxy model is “static.”

It is well known, from the \( N \)-body simulation studies, that disks built with exponential-Spitzer laws (hereafter SdMH disks), when submitted to the Newtonian potentials, are revealed to have secular centrifugal equilibrium, maintaining their density profiles for gigayears of simulated time (Springel & White 1999; Springel et al. 2005). However, under the BM picture, we do not know how long the BM potential can maintain galactic disks in dynamical equilibrium, if in fact it really can. This is the main aim of the present paper.

In previous works (Brandao & de Araujo 2010a, 2010b, 2010c), we developed an \( N \)-body method to study alternative theories of gravity at galactic scales. In particular, we have studied an Yukawian gravitational potential and have shown that this potential is viable only if the Yukawian parameter is such that the Yukawian potential is nearly Newtonian.

In the present work, we also use \( N \)-body simulations to construct and evolve spiral galaxies now submitted to the potential and acceleration given by Equations (3) and (4), respectively. We adopted, in these simulations, the same set of fitted parameters \( (M_0 = 96 \times 10^{10} M_\odot \text{ and } r_0 = 13.96 \text{ kpc}) \) as by BM.

Our aim is to probe if the BM model is dynamically consistent, as it should be in order to be considered a realistic model. In this way, we are able to test the BM claim and verify the reliability of this kind of law of gravity, using the concepts and techniques of the galactic dynamics studies (Binney & Tremaine 2008).

In Section 2, we present the \( N \)-body code used in this work and the numerical techniques used to model spiral galaxies with the BM potential; in Section 3, the results of the numerical simulation are present; and finally, in Section 4, we discuss our main findings and conclusions.

2. NUMERICAL TECHNIQUES

2.1. The Modified Code

We performed the simulations with a modified and tested version of the Gadget-2 code (Springel 2005). As discussed in our previous papers (Brandao & de Araujo 2010a, 2010b, 2010c), this choice is based on the collisionless nature of galaxies modeled by particles and the method used by Gadget-2 to build the recursive tree in order to compute forces and potentials.

We have modified the Gadget-2 and replaced the Newtonian potential and acceleration by the expressions given by Equations (3) and (4) just in the respective code’s instructions. We have extensively tested the code efficiency to calculate potentials via the tree method, using a typical initial snapshot composed by a disk embedded in a dark matter halo.

It is worth noting that we included a halo only to test the code accuracy, since in the probes of the ability of the BM gravity to generate spiral galaxies with flat rotation curves, without dark matter, the halo is not included in the simulations.

The Newtonian and the Moffatian codes were set up with the tolerance parameter \( \theta = 0.8 \), maximizing the tree code’s performance and softening length \( l_{\text{th}} = 0.33 \) kpc for the dark halo and \( l_4 = 0.15 \) kpc for the baryonic disk. This set of softening lengths yields conservation of the total energy better than other sets. The procedure to choose the values for \( \theta, l_{\text{th}}, \text{and } l_4 \) adopted here is analogous to that used in our previous papers (Brandao & de Araujo 2010a, and references therein).

2.2. Initial Conditions

We have studied three models: model I, a typical exponential-Spitzer disk with a dark matter halo (Newtonian galaxy); model II, derived from the first one, where the system is built and the halo is removed before running the simulation with a Moffat potential (pseudo-Moffatian galaxy); and model III a pure BM disk model (pure Moffatian galaxy). Below, we give the reasons why such models are chosen.

Model I follows the prescriptions described by Springel et al. (2005, and references therein), but with the difference that we are now including neither bulges nor gas particles, because we do not need a detailed Newtonian model, since our main aim is to investigate the dynamical properties of disk galaxies under alternative potentials. The reason for this choice has to do with their dynamical stability and with computational simplicity in modeling them, as explained in detail in Springel et al. (2005). Besides, it is worth stressing that SdMH disks reproduce all observational features of late-type systems.

In one of our previous papers (Brandao & de Araujo 2010c), we described the principal recipes to model such galaxies. Besides the parameters discussed in the previous section, the models are composed by \( N_{\text{halo}} = 30,000 \) particles for the dark matter halo and \( N_{\text{disk}} = 30,000 \) for the disk. All these figures yield a conservation of energy that makes our galaxy model reliable, as the reader will find later on in this paper. Model I is then a Newtonian model for a spiral galaxy, which is consistent with observations, that we use to compare with the Moffatian model for spiral galaxies.

Model II is the same as model I but without dark halo particles. It is worth stressing that the halo potential is computed to make the rotation curve of the disk of model II as reliable as possible—like the observed ones.

After extracting the halo, the disk should be stable under the BM potential. This procedure is made to test the BM hypothesis, which claims that disks can exist under Moffat’s potential without halos, explaining rotation curves without exotic non-baryonic dark matter. In this way, we are able to test this hypothesis over the secular evolution of a disk.

Model III is similar to model II, but with the following differences: (1) we do not compute the halo’s potential and (2) we replace the Newtonian potential originated from the disk (see, e.g., Binney & Tremaine 2008, Equation (2.170)) by the BM potential originated from all the positions of the disk particles, using the BM parameters \( M_0 = 96 \times 10^{10} M_\odot \text{ and } r_0 = 13.96 \) kpc, as fitted by Brownstein & Moffat (2006a).

In other words, we first build the positions of the particles and then compute their potentials using Equation (3) over the mesh, where the velocities will be calculated (see, e.g., Brandao & de Araujo 2010c). We use these results to integrate the Jean’s equations and then calculate the velocity dispersions. With this procedure, the initial disk is put in equilibrium with the BM potential during the first snapshots of simulated time. We have set \( N_{\text{disk}} = 30,000 \) particles to this disk (hereafter Moffatian disk or BM disk for short) in order to maintain the same resolution set to the Newtonian model. Note that the disk thus modeled is
The following set of parameters is chosen for the SdMH disks (model I): the total mass $M_t = v_{200}^2/(100H_0) \approx 9.98 \times 10^{12} M_\odot$, where $v_{200} = 160$ km s$^{-1}$ is the virial velocity, $G$ is the gravitational constant, and $H_0 = 100$ km s$^{-1}$ Mpc$^{-1}$ is the Hubble constant; the total mass of the disk $M_{\text{disk}} = m_d M_t$, where $m_d = 0.041$ is a dimensionless fraction of the total mass; the disk scale length $h = 2.74$ kpc; the disk vertical scale height $z_0 \sim 0.2h$; and the spin parameter $\lambda = 0.033$. We emphasize that this model has mass comparable to the Milky Way.

For model II, we also use the same set of parameters used in model I. Recall, however, that after building the disk–halo system, we then extract the halo.

In the BM disks, we maintain the total disk mass and the exponential-Spitzer profiles. We built the disk particles from the density profiles and used the BM parameters ($M_0 = 96 \times 10^{10} M_\odot$ and $r_0 = 13.96$ kpc).

In the next section, we present the results of our simulations.

3. SIMULATIONS AND RESULTS

3.1. The Newtonian Model

Although the Newtonian model can be considered a canonical one by current theories of galactic astronomy (Binney & Merrifield 1998) and galactic dynamics (Binney & Tremaine 2008), it is important to bear in mind that here the Newtonian model is not the main focus of our work. We have run the Newtonian simulations to compare it with models II and III. As is well known from simulations of canonical late-type systems (Springel et al. 2005; Brandao & de Araujo 2010c), many observational features, such as the exponential radial density profile, the rotation curves, etc., can be accounted for by Newtonian models.

In Figures 1–3, we display the principal results of the Newtonian model we simulated. Figure 1 displays a picture with four boxes: at top left, phase space points $r \times v$ of the initial snapshot, where $r$ is the total distance from origin (0,0,0) in kpc and $v$ is the modulus of the velocity in km s$^{-1}$; at top right, the relative energy conservation is $\Delta E/E_0$, where $\Delta E = E(t) - E(0)$ and $E_0 \equiv E(0)$, where $E(t)$ denotes the total energy of the system at time $t$; at bottom left, the phase space points at final time $t = 1$ Gyr; and at bottom right, the rotation curve is $R \times v_r$, where $R$ is the radial cylindrical coordinate and $v_r$ is the rotation velocity. Note the similarity between the initial and the 1 Gyr rotation curves; one concludes that early-type galaxy structure can be accounted for by the Newtonian model quite well, as is well known. Later on we will see that the comparison between the density profiles at these same times corroborates such a conclusion.

Figures 2 and 3 show the particle’s positions in the $z$-projection at respective times indicated in the boxes. We note from these figures that the simulation follows a typical behavior with the formation of spiral arms and central bar. These features are expected from simulations of late-type morphologies, as explained by Brandao & de Araujo (2010c, and references therein). In the first 0.33 Gyr, the disk has spiral arms and the system evolves to a central bar with two spiral arms afterward. In other words, this simulation is reliable and represents a standard typical late-type system without external influences. Energy conservation is better than 0.1%.
3.2. Moffatian Models

We show above that the Newtonian disks maintain their physical properties for many crossing times. Now, when a spiral galaxy is submitted to the BM potential, an anomalous behavior occurs to the disk’s structure, as we will see in this section.

In Figure 4, we use the same format as in Figure 1. In the top right panel of Figure 4, we display the evolution of the energy violation. Note that after 1 Gyr (end of our simulation),
From this simulation, we also see that the particles in the phase space are more scattered as compared to the Newtonian simulation. This scattering is interpreted as a loss of information from the initial configuration. Note that in the bottom right panel the disk rotates slower than at its initial time, even though it still resembles a typical rotation curve. From a first glance at Figure 4, it seems that the Moffatian potential can really explain BM disks, and no dark matter is needed to maintain secularly stable exponential disks.

We display snapshots of the disk’s particles in Figures 5 and 6. Examining these snapshots, we see that at 0.08, 0.16, 0.24, and 0.32 Gyr times the system presents atypical substructures, in particular in its central region ($R \lesssim 10.0$ kpc). As the disk evolves, an annular substructure appears, and the central region becomes almost empty of particles, a void. Subsequently, the big ring collapses and fragments into three spiral unbound arms. At this stage, there is no core.

At $t = 0.66$ Gyr, the arms merge themselves and become a bar-like structure surrounded by two weak spiral arms. This bar-like structure is small when compared to the Newtonian case. This anomalous behavior is due to the fact that the particles are not in perfect initial equilibrium with the Moffatian potential.

However, it is important to bear in mind that we are testing the BM claim, which considers that the Moffatian potential can explain many observed rotation curves of galactic disks without dark matter halos. We recall that our simulated initial disk reproduces the observational features of real galaxies: exponential-Spitzer disk, velocity dispersions, rotation curves, and baryonic mass, and secular equilibrium in the Newtonian case. From this point of view, we would expect that, if BM hypotheses were reliable, our disk would be stable all the time in the simulation. We find that an equilibrium configuration is reached only after $t \gtrsim 0.66$ Gyr. After this time, the system is similar, in some dynamical aspects, to the Newtonian case, but we will see below that this similarity is only apparent.

The results of the model II simulations raise some interesting questions. One could claim that the simulations of model II need a fine tuning of the parameters $M_0$ and $r_0$ to maintain the entire disk in equilibrium. These parameters could, therefore, be changed to avoid atypical rings and central voids during the first 0.33 Gyr. To study these sub-morphology features, we have made some tests changing the parameters $M_0$ and $r_0$, but we have not found any set of parameters that left the simulations just like the Newtonian one, which, it is worth stressing again, are consistent with observations.

It was just these results of model II that led us to make a pure Moffatian disk: our model III whose simulations were made with the same parameters used in the models I and II. The results for model III can be seen in Figures 7–9.

In the top right panel of Figure 7, one finds the phase-space points. These points are distributed somewhat differently as compared to the previous models, because the rotation curve has now a different shape. Also, after 1 Gyr of simulated time, we note that the scattering in the phase-space plane is more prominent than in model II and the initial configuration is completely lost.

This effect is neither due to simulation inaccuracies nor to the resolution of the simulation, as it can be seen that the energy violation (see the top right panel of Figure 7) is small, namely, $\log \Delta E/E_0 \lesssim -2.0$. 

Figure 4. Top left: phase space for initial snapshot data. Top right: energy conservation of the simulation. Bottom left: phase space for final snapshot data at 1 Gyr. Bottom right: rotation curves for initial (solid line) and final (dashed line) snapshots.
Our results show in the end that the exponential profile is not consistent with the Moffatian potential. As occurred with model II, the rotation curve of model III is below the initial one. For $R < 10$ kpc, the rotation curve is linear and associated with the central core movement, similar to a rigid body rotation. For $R > 10$ kpc, the rotation curve is similar to a typical rotation curve of late-type systems, but, in analogy with model II, this similarity is only apparent, as we will see below.

Figures 8 and 9 display the particle’s positions at $(x,y)$ plane, where the simulated time is indicated in the respective boxes.
Figure 7. Top left: phase space for initial snapshot data. Top right: energy conservation of the simulation. Bottom left: phase space for final snapshot data at 1 Gyr. Bottom right: rotation curves for initial (solid line) and final (dashed line) snapshots.

Figure 8. BM disk at z-projection at 0, 0.33, 0.66, and 1 Gyr of simulated time (indicated in the respective boxes).

Note that, at initial times, the same atypical central void appears with its surrounding ring, which collapses and fragments in two small clumps, which evolve separately, eventually merging at \( t \sim 0.9 \) Gyr.
Figure 9. First 300 Myr of simulated time to the MB disk at $z$-projection. Time is indicated in the respective boxes.

This simulation shows that for a typical initial equilibrium configuration, BM disk systems evolve in such a way that we cannot produce models in agreement with the observed values, since atypical configurations appear.

The mixing in the phase space, for example, shows us that our BM models do not match the observational characteristics and, therefore, this model cannot be considered as a good representation of disk galaxies.

But, one could argue that the snapshot at time $t = 1$ Gyr resembles a typical late-type system, and this model could be considered reliable, since after $t \gtrsim 0.9$ Gyr this configuration seems to be stable. Later on we will consider this issue again by studying the density profile of the disk.

We now compare the rotation curve that comes from our simulations with the one that comes from the centrifugal equilibrium, i.e., $v^2(r) = r a(r)$, where $a(r)$ is given by Equation (4). This rotation curve reads

$$v(r) = \sqrt{\frac{G_0 M(r)}{r} \left(1 + \frac{M_0}{M} \left[1 - \exp(-r/r_0)(1 + r/r_0)\right]\right)^{1/2}} ,$$

where $M(r)$ is obtained from our simulation. Note that the above equation is the same one used by BM.

In Figure 10, we show the result of this comparison. Note the similarity between the rotation curves, even when considering different simulated times. The differences come from particle noise, very common in $N$-body samplings after evolving the system. This result shows the consistency between our simulations and the calculation done by BM.

An important issue is to examine the radial density profile of the simulated disks. A reliable model of a spiral galaxy must have at the end of the simulation the same initial profile.

In Figure 11, the radial density profile of the simulated disks is calculated at $t = 0$ and $t = 1$ Gyr. This figure presents the logarithmic of particle counts per unit of area, i.e., $\log(\rho)$, in the $(x, y)$ plane, that was divided in many concentric rings, in a cylindrical coordinate system. We have also estimated the initial exponential profile analytically, which is indicated by dotted lines.

Frame I indicates the Newtonian initial profile, estimated for all the particles, and analytically both profiles coincide exactly. Frame II shows the final Newtonian profile, Frame III shows the final profile of model II, and Frame IV shows the final BM profile (model III). Each frame has its initial exponential profile for comparison. Note that the Newtonian disk maintains its initial profile in spite of particle noise, which is very common in $N$-body samplings after evolving the system. This figure shows that bars and spiral arms left the exponential profile almost unchanged.

For Frame III, however, we conclude that the simulations of model II have minimized the central density and maximized the density at $R > 10$ kpc. In the phase space, this can be noted by the migration of particles to more distant regions, where their orbits are more stable, increasing the density there. The same happens with BM disks, as we can observe in Frame IV.

It is worth mentioning again that our BM disk has the same initial profile as the Newtonian model, and Frame I represents all initial profiles, due to the fact that all initial disks are modeled by the same exponential-Spitzer law. We note that, in spite of the final snapshot configurations of the model II and III mimic disks, their density profiles are very different from a canonical exponential-Spitzer law, from which they were built. In conclusion, the Moffatian potential cannot maintain exponential-Spitzer disks in dynamical equilibrium and therefore cannot be consistent with observations.
Figure 10. Moffatian rotation curves (model III). Solid lines stand for the rotation curve given by Equation (5) and dashed lines for the rotation curves obtained from the snapshots. Time is indicated in the respective boxes.

Figure 11. Radial density profiles of the simulated models. Horizontal axis: radial distance $R$ from the center of gravity. Vertical axis shows the log of the particle counts, $\log(\rho)$, where $\rho$ is the number of particles per area unit. Frame I shows the initial values of the density profile, represented by solid lines. Frame II: the final profile of the Newtonian model. Frame III: the profile of the pseudo-Moffatian disk. Frame IV: the profile of the Moffatian disk. All frames display the exponential profile in dotted lines that match with initial counts.
Figure 12. Evolution of the radial density profiles of model III. Time is indicated in the respective boxes.

Figure 13. Model III with the same initial snapshot used in Figure 8, obtained with the Gadget-2 modified code in the Newtonian limit, i.e., with $r_0 = 1000$ kpc and $M_0 = 1 \times 10^{10} M_\odot$. Top left: phase space for initial snapshot data. Top right: energy conservation of the simulation. Bottom left: phase space for final snapshot data at 1 Gyr. Bottom right: rotation curves for initial (solid line) and final (dashed line) snapshots.
Figure 14. BM disk at z-projection at 0, 0.33, 0.66, and 1 Gyr of simulated time (indicated in the respective boxes) obtained with the Gadget-2 modified code in the Newtonian limit, i.e., with $r_0 = 1000$ kpc and $M_0 = 1 \times 10^{10} M_\odot$.

In Figure 12, we present, for model III, the radial density profile for different simulated times. This figure clearly shows that, even starting from a disk in equilibrium, Moffatian gravity does not maintain the exponential-Spitzer disk with the same initial density profile. As time goes on, the profile turns gradually and is definitely different from the exponential profile. This shows that simulating models are a more robust tool than simply adjusting profiles in static models, because the evolution of the system cannot be followed in this last approach.

In conclusion, an alternative gravitational law must explain not only the rotation curves of spiral galaxies, but also their density profiles. In this way, simulations can be a powerful tool to deal with such an issue.

3.2.1. An Additional Test

Note that depending on the values of $r_0$ and $M_0$, Newtonian gravitation would naturally be recovered. Therefore, as an additional test we examine such an issue, which could help one to see how the structure of a disk galaxy would be modified by an alternative gravity law.

We start from a Moffatian disk, the one present, for example, in the first snapshot of Figure 8, whose initial rotation curve is shown in Figure 7. Then, we set $r_0 = 1000$ kpc and $M_0 = 1 \times 10^{10} M_\odot$ and follow how the disk evolves.

The results of this simulation are shown in Figures 13 and 14. For comparison, we also performed simulations using the Newtonian Gadget-2. Both calculations produce identical results. Therefore, the Newtonian calculation is recovered.

In particular, note in Figure 13 the rotation curve after 1 Gyr of simulated time; for large values of $R$, the velocity is a decreasing function of $R$, as expected for a Newtonian disk.

It is also interesting to compare the Moffatian disk snapshots and Newtonian ones. Comparing Figures 8 and 14, one clearly sees how different these configurations are.

4. CONCLUSIONS

Studies of alternative theories of gravity are usually made statically, instead of modeling “live” systems. For example, in the study of spiral galaxies centrifugal equilibrium is usually considered. The problem with this approach is that the secular evolution of these systems cannot be followed.

In the present paper, in particular, we follow the techniques used by Brandao & de Araujo (2010a, 2010b, 2010c) and probe the BM model, verifying if the Moffatian gravity is dynamically consistent to account for spiral galaxies. A dynamical study is a robust approach, since it considers the distribution functions and Jean’s equations that can maintain N-body systems in equilibrium.

We performed the simulations with a modified and tested version of the Gadget-2 code. We replaced the Newtonian potential and acceleration by the expressions given by Equations (3) and (4) in the respective code’s instructions. We have extensively tested the code efficiency to calculate potentials via the tree method, using a typical initial snapshot composed by a disk embedded in a dark matter halo.

From our simulations, it follows that the Moffatian potential cannot generate exponential disks in equilibrium, although the rotation curves are nearly flat throughout the whole simulated time. The final (stable) equilibrium configuration is very different from the exponential profile, as we have explained above. So, if we consider that exponential profiles are reliable, as seems to be the case, since they are consistent with
observations, it is hard to believe that the BM model is better than the Newtonian model (baryonic disk embedded in a dark matter halo) at accounting for the spiral galaxy structure. Recall that Brownstein & Moffat (2006a) claim that $M_0$ and $r_0$ fit very well many (observed) rotation curves, but they have only analyzed static models (centrifugal equilibrium configurations).

Finally, it is worth mentioning that it would be very interesting to simulate the BM potential for standard elliptical systems and to probe its influence over their global properties, like we have done in this work. A forthcoming paper will consider such an issue.

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