POLARIMETRY WITH THE GEMINI PLANET IMAGER: METHODS, PERFORMANCE AT FIRST LIGHT, AND THE CIRCUMSTELLAR RING AROUND HR 4796A

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ABSTRACT

We present the first results from the polarimetry mode of the Gemini Planet Imager (GPI), which uses a new integral field polarimetry architecture to provide high contrast linear polarimetry with minimal systematic biases between the orthogonal polarizations. We describe the design, data reduction methods, and performance of polarimetry with GPI. Point-spread function (PSF) subtraction via differential polarimetry suppresses unpolarized starlight by a factor of over 100, and provides sensitivity to circumstellar dust reaching the photon noise limit for these observations. In the case of the circumstellar disk around HR 4796A, GPI’s advanced adaptive optics system reveals the disk clearly even prior to PSF subtraction. In polarized light, the disk is seen all the way in to its semi-minor axis for the first time. The disk exhibits surprisingly strong asymmetry in polarized intensity, with the west side ≳9 times brighter than the east side despite the fact that the east side is slightly brighter in total intensity. Based on a synthesis of the total and polarized intensities, we now believe that the west side is closer to us, contrary to most prior interpretations. Forward scattering by relatively large silicate dust particles leads to the strong polarized intensity on the west side, and the ring must be slightly optically thick in order to explain the lower brightness in total intensity there. These findings suggest that the ring is geometrically narrow and dynamically cold, perhaps shepherded by larger bodies in the same manner as Saturn’s F ring.

Key words: circumstellar matter – instrumentation: adaptive optics – instrumentation: high angular resolution – instrumentation: polarimeters – polarization – stars: individual (HR 4796A)

1. INTRODUCTION

In the 30 years since the pioneering coronagraphy of the disk around β Pic (Smith & Terrile 1984), imaging observations of nearby planetary systems have blossomed into a rich field of study. Young pre-main-sequence stars are now commonly seen to have optically thick gas- and dust-rich protoplanetary disks, while more tenuous debris disks have been spatially resolved around dozens of main-sequence stars (see Williams & Cieza 2011; Matthews et al. 2014, and references therein.). Disks are intimately related to planets, both giving rise to planets in young protoplanetary disks and in turn arising as second-generation debris disks from the collisional destruction of planetesimals. Indeed, β Pic itself is now seen to have a Jovian planet orbiting within and sculpting its disk (Lagrange et al. 2009, 2010), and
a correlation between the presence of planets and debris disks is increasingly supported by observational data (Raymond et al. 2012; Bryden et al. 2013; Marshall et al. 2014). Imaging studies complement spectroscopy and interferometry, and remain essential for investigating many aspects of the physics of circumstellar disks. Each new generation of instruments offers further clarity on the details of how planetary systems form and evolve.

The key challenge in imaging disks at optical and near-infrared wavelengths is achieving sufficient contrast to detect faint and extended disk-scattered light in the presence of a brighter stellar point-spread function (PSF). While a corona graph can help block direct starlight, particularly if that light is concentrated in a coherent diffraction-limited PSF, coronagraphs inevitably still leave some unblocked residual starlight. Differential measurement techniques and PSF subtraction in software are needed to remove this remnant starlight to provide a clear view of circumstellar disks.

Differential imaging polarimetry and adaptive optics (AO) have proven to be a particularly useful combination toward this goal. Randomly polarized starlight assumes a preferential polarization state after scattering off circumstellar dust; the degree of polarization and its dependence on scattering angle and wavelength are set by the nature of the scattering particles. Not only can the induced polarization be used as a diagnostic for the properties of those particles (e.g., Graham et al. 2007), it also provides a powerful discriminant of disk-scattered light from the intrinsically unpolarized stellar PSF (e.g., Kuhn et al. 2001). By measuring orthogonal polarizations simultaneously, the residual star light common to the two polarizations should vanish in their difference; modulation of the sensed polarization state after scattering off circumstellar dust; the degree of polarization, surprising given the relatively isotropic total intensity phase function. Based on our analysis of these observations, we now believe this ring to be optically thick and dominated by scattering from relatively large dust particles (Section 6). All data presented in this paper are from the 2013 December and 2014 March GPI observing runs. Subsequent multi-wavelength followup observations of HR 4796A will be presented in a future paper (M. P. Fitzgerald et al., in preparation). We conclude with some brief remarks on future prospects for circumstellar disk studies with GPI, SPHERE, and other high-contrast systems (Section 7).

2. THE IMAGING POLARIMETRY MODE FOR GPI

The design of GPI’s polarimetry mode was previously presented by Perrin et al. (2010), and builds upon concepts and lessons learned from earlier AO polarimeters (as summarized in Perrin et al. 2008). The imaging polarimetry mode is implemented primarily by a polarizing Wollaston prism beam splitter within the Integral Field Spectrograph (IFS; Larkin et al. 2014) and a rotating half-wave plate within the calibration unit, but depends on the overall instrument system to achieve its performance goals.

The GPI IFS uses a lenslet array to pixellate the field of view before dispersing the light either spirally or polarimetrically. In either mode, the field of view comprises roughly 190 × 190 lenslets at a scale of 14.14 ± 0.01 mas/lenslet (Konopacky et al. 2014) yielding a square field of view ∼2.7 arcsec on a side. This is reimaged onto a 2048 × 2048 Hawaii-2RG detector, but it is the lenslet array rather than the detector that defines the effective angular sampling. This system yields ∼36,000 spatial sample elements (“spaxels”), with the exact number varying slightly...
between bandpass filters and modes due to minor differences in which spaxels at the edge of the field are reimaged just on or off the detector.

2.1. Design Principles

Our central criterion when designing GPI’s polarimetry mode was to optimize contrast in spatially resolved coronagraphy of circumstellar disks. This led to several design choices made differently than for a typical point-source polarimeter, and differently from what we would have adopted if our goal had been the utmost performance in absolute polarimetric accuracy. GPI is designed first and foremost as an integrated starlight suppression system, only secondarily as a polarimeter.

In particular, we sought to minimize static wavefront errors prior to the coronagraphic focal plane. This is necessary because coronagraphic starlight suppression depends sensitively on image quality at the coronagraph’s focal plane—aberrations after that point have much less ability to create speckles since most starlight has been removed. The conventional wisdom for high precision polarimetry is that a modulator (e.g., waveplate) should be placed as early as possible in the optical path, to mitigate instrumental polarization. However for GPI this would have meant one or more additional pre-coronagraph optical surfaces, likely with relatively poor wavefront quality. We therefore decided to locate an achromatic waveplate retarder after the coronagraphic focal plane, specifically located in a collimated beam in the input relay to the IFS and mounted on a linear stage so that it can be removed from the light path during spectral-mode observations.

This design means that we cannot modulate out the instrumental polarization induced by off-axis reflections from GPI’s many optics, but must instead calibrate and remove this bias during data reduction (Section 4.3). However, this approach was inevitable for GPI, since Gemini instruments are required to operate at any port of the Gemini Instrument Support Structure, most of which are fed by a 45° reflection off the telescope’s tertiary mirror. This tertiary fold is likely a dominant contributor to instrumental polarization when mounted on a side port, and its effects could not possibly be mitigated by any modulator within GPI. Instrumental polarization from a 45° fold can be cancelled optically by balanced reflections from a second mirror tilted on an axis orthogonal to that of the first mirror (Cox 1976), but we did not pursue that approach because it would do more harm than good for the case in which GPI is mounted on the straight-through bottom port. Thus far GPI has only been operated at that bottom port, so currently the tertiary fold does not contribute to instrumental polarization, and as of mid-2014 it is planned that GPI will remain on the bottom port for future observing runs.

2.2. Integral Field Polarimetry

Given that the science instrument of GPI is a lenslet-based IFS, we implement the measurement of polarized light via a novel mode within that IFS that we call “integral field polarimetry.” In this mode the regular spectral dispersing prism within the IFS is replaced with a Wollaston prism, giving up spectral resolution to gain sensitivity to orthogonal linear polarizations. This swap is implemented by mounting both prisms on a linear stage within the cryogenic volume of the IFS. The polarizations are then dispersed only after the lenslet array has pixelated the field of view. Each lenslet in the array corresponds to one spatial resolution element or spaxel. Figure 1 depicts this architecture in comparison with traditional AO polarimeter.

Integral field polarimetry minimizes differential wavefront error between the two polarizations, eliminates the difficulty of precise image registration that has limited previous AO imaging polarimeters (e.g., Perrin et al. 2004; Apai et al. 2004), and does not require any reduction in field of view. It also prevents any distortion of PSFs due to lateral chromatism of the Wollaston prism, thus removing any need for exotic materials with low birefringent chromaticity such as YLF (Oliva et al. 1997; Perrin et al. 2008).

The optimal Wollaston prism design for integral field polarimetry maximizes the separation of the polarized spots by dispersing each lenslet along a ±45° axis relative to the lenslet grid. This results in two sets of dots interlaced in the same manner as the black and white squares of a chessboard. See Figure 2. In addition to maximally separating the spots, this design results in the diffraction pattern from the square lenslet grid (the dominant form of crosstalk between spots) only overlapping onto adjacent spots of the same polarization, thus minimizing contamination between channels.

Further details of the polarizing prism, waveplate, and associated mechanisms for GPI are given in Appendix A.

3. DATA REDUCTION METHODS

3.1. Key Concepts

Polarimetric observations with GPI consist of a series of exposures taken with the Wollaston and waveplate inserted into the beam, with the waveplate rotating between each subsequent exposure. The waveplate rotation angle is a free parameter that in principle can be set arbitrarily for each exposure; in practice, we generally follow the typical approach of stepping 22° per move: 0°, 22.5°, 45°, 67.5°, and so on. These images must then be combined to extract the astronomical polarization signal.

GPI always remains fixed with respect to the telescope pupil, so the sky appears to constantly rotate, allowing angular differential imaging (ADI; Marois et al. 2006a) to further reduce the residual speckle halo. The fact that GPI always observes in ADI mode complicates polarimetric data reduction because each exposure has unique sky-projected polarization axes and field rotation. Traditional double-differencing methods of polarization data reduction do not suffice. Instead, we combine each sequence of exposures based on a more generalized forward model of observations: for each individual exposure, we construct the particular Mueller matrix equation describing how sky rotation and the polarizing optics within GPI map astrophysical polarizations into orthogonal polarization signals measured on the detector. By inverting the resulting set of equations through

24 It is impractical to fabricate waveplates better than ∼50 nm peak-to-valley transmitted wavefront error, since repeated polishing to improve surface quality is incompatible with controlling the absolute thickness in order to set the retardance. Alternate modulators such as liquid crystal retarders tend to have even worse wavefront quality than waveplates, >100 nm rms. For comparison the superpolished reflective optics used in GPI typically have <1 nm rms.

25 Facility-class polarization modulators for each Gemini telescope were designed and built to avoid precisely this problem, but these GPOL systems remain uncommissioned and are unlikely to ever be used.

26 During much of commissioning, a minor software bug in the Gemini Observing Tool (OT) restricted the waveplate position to integers, so we used 22° and 68° instead of 22.5° and 67.5°. The data reduction pipeline handles any arbitrary sequence of rotation angles. The OT was subsequently updated to allow floating point values. See Appendix A for more details on the waveplate modulation mechanism.
a least-squares analysis, we derive the astrophysical polarization signal for each position in the field of view. The result is a three-dimensional (3D) Stokes datacube \([x, y, (I, Q, U, V)]\) derived from the entire observation sequence. Further details of this algorithm are provided in Appendix B.1.

One of the strengths of differential polarimetry is that modulation of the polarized signal can mitigate non-common-path biases between the orthogonal channels. For traditional imaging polarimeters, this cancellation can be obtained simply by creating double differences of images appropriately modulated to swap opposite Stokes parameters such as \(+Q\) and \(-Q\) (e.g., Kuhn et al. 2001). This, too, is complicated by the fact that GPI observations are always ADI mode. Such images cannot be added together until after a derotation step brings them to common orientation in the sky frame, but successive derotated images no longer align in the instrument frame so instrumental non-common-path biases will not cancel. Integral field polarimetry does mostly eliminate the potential for any optical non-common-path biases (i.e., light is not dispersed in polarization until after it has been optically pixelated). Detector artifacts and imperfect datacube assembly can still induce non-common-path offsets between the two channels for which we must compensate. In place of the traditional double-differencing, we have included an analysis step that estimates the bias between

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**Figure 1.** Conceptual schematics of a traditional AO polarimeter and the integral field polarimetry architecture developed for GPI, indicating the order of the various optical components. These figures are highly simplified, with many optics omitted and others shown as transmissive even though in practice most are reflective. Upper panel: in a conventional AO polarimeter, the orthogonally polarized PSFs are similar but not identical due to non-common-path wavefront errors and the wavelength dependence of the Wollaston prism’s birefringence; modulation with a rotating waveplate mitigates these differences. The data shown here for the conventional AO polarimeter are observed PSFs from the Lyot Project coronagraph at the AEOS 3.6 m (Hinkley et al. 2009). Lower panel: in an integral field polarimeter, the light is optically divided by the lenslet array prior to any dispersion, largely eliminating sensitivity to non-common-path errors and chromatic birefringence and thus producing a difference image with speckles highly suppressed.
the two orthogonal polarization channels based on the mean channel difference for all the exposures in a given observing sequence. Subtracting this mean difference from each individual difference image yields a variant of double differenced image. Empirically this method greatly reduces systematics in the final datacubes for GPI. Details of this algorithm are described further in Appendix B.2.

3.2. Steps of Data Processing

The steps involved in processing GPI polarimetry are depicted in schematic form in Figure 3. Software implementing these tasks is available as part of the GPI Data Reduction Pipeline27 (Perrin et al. 2015). Starting from raw files written by the instrument, we first subtract a dark image in the usual manner, followed by a “destriping” step to remove correlated noise due to the readout electronics and microphonics noise induced in the H2RG detector by mechanical vibration from the IFS cryocoolers (Chilcote et al. 2012; Ingraham et al. 2014a). The impact of these noise terms decreases as $1/\sqrt{N_{\text{reads}}}$, and thus is most significant for short integration times (small numbers of up-the-ramp reads); for typical science exposures of a minute or longer, the impact of correlated noise is minimal and the destriping step is often unnecessary.

To assemble a pair of polarization images from the raw data, we must know the locations of the tens of thousands of dispersed polarization spots. The spot pattern is close to but not perfectly uniform due to distortions in the spectrograph optics. A calibration map of all spot locations is made by fitting model lenslet PSFs to a high signal-to-noise (S/N) polarimetry mode observation of the GCAL flat field quartz halogen lamp. Due to internal flexure in the spectrograph as a function of elevation, the spot locations during nighttime observations will be slightly shifted relative to daytime calibration flats (typically less than one pixel, and at most a few pixels). The offset is estimated based on a subset of the brightest spots and applied to all spot positions.

Flux in each pol spot is summed over a small aperture. Currently, a fixed $5 \times 5$ pixel box is used, but future versions of the pipeline will perform optimal extraction using empirically measured microlens PSFs (Ingraham et al. 2014b); this will provide an improvement in S/N and increased robustness to bad pixels. Iterating over the whole detector and repeating for both polarizations yields a pair of orthogonally polarized images. A flat field correction for variations in lenslet throughput can then be applied. Residual bad pixels may be detected as local statistical outliers, and their values replaced through interpolation. Using the entire set of observed images, the systematic bias between the orthogonal polarization channels is estimated and subtracted following the methods in Appendix B.2.

For coronagraphy, the position of the occulted star is estimated via a Radon-transform-based algorithm (Pueyo et al. 2014; Wang et al. 2014) using the satellite spots created by a diffractive grid on the GPI apodizers (Sivaramakrishnan & Oppenheimer 2006; Marois et al. 2006b). Based on the derived centers, each exposure in the sequence is rotated to north up and aligned to a common position. The files are then combined via least squares following the methods outlined in Appendix B.1 to produce a Stokes datacube with slices $(I, Q, U, V)$. A single Stokes datacube is the result of each observation sequence. Derived quantities such as the polarized intensity, $P = (Q^2 + U^2)^{1/2}$, and polarization fraction, $p = P/I$, may then be calculated.

Differential polarimetry via the above steps yields increased contrast in polarized light, but does not do so for total intensity. If a high contrast image in total intensity is desired, it must be obtained via other methods, for instance PSF subtractions using ADI. Methods such as LOCI (Lafreriè et al. 2007) or KLIP (Soummer et al. 2012) can be effective, but require observers to carefully model the effects of these algorithms on the disk’s apparent surface brightness and morphology (e.g., Esposito et al. 2014; Rodigas et al. 2014; Milli et al. 2014).

4. PERFORMANCE

4.1. Suppression of Unpolarized Starlight

As part of the GPI commissioning program, we have measured the polarimetric suppression of residual starlight based on

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27 Software and documentation available from http://planetimager.org/datapipeline.

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Figure 3. Sketch of key steps in reducing GPI polarimetry data, from raw data to polarized intensity of scattered light. See the text in Section 3.2 for description of each step.

Table 1

| Target     | UT Date   | Obs. Mode | Int. Time (s) | No. of Coadds | No. of Exps. | Airmass   | Seeing (′) | Field Rot. (′) |
|------------|-----------|-----------|---------------|---------------|--------------|-----------|------------|---------------|
| HD 118666  | 2014 Mar 24 | J_coron  | 59.6          | 2             | 4            | 1.28–1.29 | 0.7        | 1.3           |
| HD 118666  | 2014 Mar 24 | H_coron  | 59.6          | 4             | 8            | 1.30–1.32 | 0.7        | 1.3           |
| HD 118666  | 2014 Mar 24 | K1_coron | 59.6          | 1             | 4            | 1.26      | 0.7        | 3.1           |
| Twilight Sky | 2014 Mar 24 | K1_direct | 59.6          | 1             | 12           | N/A       | N/A        | N/A           |
| Twilight Sky | 2014 Mar 24 | J_direct | 29.1          | 1             | 4            | N/A       | N/A        | N/A           |
| Twilight Sky | 2014 Mar 24 | H_direct | 59.6          | 1             | 4            | N/A       | N/A        | N/A           |
| β Pic      | 2013 Dec 12 | H_coron  | 5.8           | 10            | 60           | 1.07–1.18 | 0.5        | 91.5          |
| HD 12759   | 2013 Dec 12 | H_direct | 1.5           | 10            | 8            | 1.05      | 0.45       | 8.7           |
| HR 4796A   | 2013 Dec 12 | H_coron  | 29.1          | 2             | 11d          | 1.45–1.38 | 0.4        | 2.1           |
| HR 4796A   | 2013 Dec 12 | K1_coron | 59.6          | 1             | 11d          | 1.32–1.27 | 0.4        | 2.2           |
| HR 4796A   | 2014 Mar 25 | K1_coron | 59.6          | 1             | 12           | 1.01–1.02 | 0.4–0.7    | 33.3          |

Notes.

* GPI instrument mode corresponding to choice of filter plus corresponding apodizer, focal plane, and Lyot plane masks. “direct” modes have the coronagraphic optics removed from the light path.

b Between each exposure the half wave plate was rotated to the next position.

c Change in parallactic angle over the course of the observation sequence.

d One fewer exposure than intended was inadvertently obtained in each sequence, so there are fewer images at 68′ than the other modulator angles, but the data reduction pipeline accommodates this.

observations of unpolarized standard stars. On 2014 March 24 the unpolarized standard HD 118666 was observed with GPI in closed-loop coronagraph mode with the J, H, and K1 filters (see Table 1). HD 118666 is a bright (H = 4.8) nearby F3III-IV star with a measured polarization of 0.07% ± 0.035% (Mathewson & Ford 1970).

Each set of observations was reduced as described in the previous section to produce a Stokes data cube. We then
measured, in annuli of increasing radius from the star, the mean total intensity (Stokes $I$) and the mean polarized intensity ($P$).

The resulting radial profiles are shown in Figure 4. The ratio of these two quantities, $I/P$ as displayed in Figure 5, is a first-order measure of the suppression of unpolarized starlight. This quantity is formally the inverse of the apparent polarization fraction, but in this context is better considered as the ratio of pre- to post-differential-polarimetry total flux since the source is known to be unpolarized. In all bands, the total intensity is suppressed by factors of $>100$ at radii smaller than 0″4. The suppression ratio increases to $>200$ inside 0″2 and decreases at wider separations.

It is well known that polarized intensity is a positive definite quantity and thus biased upward by any noise (e.g., Wardle & Kronberg 1974; Simmons & Stewart 1985; Vaillancourt 2006). To assess the contributions of different noise terms, we created simulated sets of observations containing only photon and read noise, repeated for each filter with the same number of exposures as the original data sets. The simulated orthogonal polarization images were constructed to have identical mean intensity radial profiles as the observations, and appropriate photon noise was added using the nominal gain of 3 e−/ADU. For read noise, we used prior measurements for the read noise at the relevant exposure times. The simulated data sets were then run through the reduction process to produce mock Stokes cubes, and the total intensity and polarized intensity were measured as a function of radius. Simulated sets of data that only included photon noise were used to determine the photon noise limit set by the post-coronagraphic PSF.

Greater suppression of starlight may be possible once the instrumental polarization is properly considered. GPI’s differential polarimetry mode achieves sensitivities of precisely the right magnitude to explain the observed maximum suppression ratios. The instrumental polarization of $\sim 0.4\%$, as measured below in Section 4.3, is of precisely the right magnitude to explain the observed maximum suppression ratios.

The resulting mock polarized intensity profiles agree closely with the observations, confirming that photon noise is the dominant limiting factor at most separations. Figure 4 plots the $P$ profiles from the simulated data sets in red, showing the good agreement with the observed $P$ profiles in black. In all cases, the GPI data appears to be photon noise dominated at radii greater than 0″4, though the read noise is a significant secondary contributor. GPI’s differential polarimetry mode achieves sensitivities to polarized circumstellar material reaching the fundamental photon noise limit set by the post-coronagraphic PSF.

Additional descriptions and details are included in the text, with references to literature such as Harrington et al. (2011) and references therein. In the case of pure Rayleigh scattering, which we consider here, the P.A. of the observed polarization is aligned 90° from the solar azimuth.

Figure 4. Total intensity and linear polarized intensity as a function of radii for observations of the unpolarized standard star HD 118666 in GPI’s $J$, $H$, and $K1$ bands. The read noise and photon noise curves were calculated with simulated data and indicate that these observations are dominated in all three bands by photon noise at radii greater than 0″4.

Figure 5. Ratio of the total intensity to the linear polarized intensity. At angular separations smaller than $\sim 0″2$, unpolarized speckles are being suppressed by over a factor of 200. This value represents a lower limit on the performance of GPI, as instrumental polarization was not compensated for in this analysis.

4.2. Polarized Twilight Sky Tests

To validate the measurement of polarization angles it is helpful to observe a source of known polarization position angle (P.A.). The twilight sky provides a useful calibration target since it is highly polarized, predominantly due to Rayleigh scattering in the upper atmosphere. Other contributors to sky polarization include aerosol scattering, multiple scattering effects, and secondary illumination from light scattered off clouds, water, and land (Harrington et al. 2011, and references therein). In the case of pure Rayleigh scattering, which we consider here, the P.A. of the observed polarization is aligned 90° from the solar azimuth.
(i.e., the polarization is orthogonal to the great circle pointing toward the Sun). In the following analysis, we focus solely on validating the observed P.A.s and not the polarization fraction.

Zenith observations of the twilight sky were taken in the J, H, and K1 bands on 2014 March 24 (see Table 1) with the coronagraph optics out of the beam. Orthogonal polarization cubes were made using the standard pipeline recipe, and were then normalized each by its own total intensity to account for the diminishing brightness of the sky over time, before being combined into Stokes data cubes. A mean P.A. was then calculated using the mean Q and U values across the field of view for each filter.

We find the measured P.A.s are within a few degrees of the expected values as shown in Figure 6, confirming there are no sign errors in the pipeline software or instrument problems such as gross angle offsets in the optics. The measurements also reproduce the downward trend over time that is expected from the Sun’s motion. However, we find the measured P.A.s are systematically slightly offset from the expected values by 3.3–4.3. The statistical errors are small when averaged over the 36,000 lenslets; for all three filters the standard error of the mean P.A. is at or below 0.04, if each lenslet is considered to be an independent measurement. The ∼4° offset may represent an actual systematic bias to measured P.A.s, but could also be due to some aspect of the sky illumination over Cerro Pachon during these observations, for instance, secondary illumination from setting sunlight scattered by clouds on the western horizon. These data were taken between 12 and 30 minutes after sunset when such secondary illumination may be significant.

Without a larger data set spanning multiple nights, we cannot be certain yet whether this offset is a recurring systematic. We will continue investigating this issue on future observing runs. Twilight observations are somewhat difficult to obtain with GPI; given the small lenslet pixel size and the blue slope of Rayleigh scattering, the polarized near-IR sky becomes undetectably faint very shortly after sundown, making it impractical to obtain such twilight sky sequences routinely. Nonetheless these results confirm that GPI can measure P.A.s to within a few degrees. We will consider an alternate check of P.A.s based on circumstellar disk science data itself below in Section 5.6.

4.3. Instrumental Polarization

Observations of polarized and unpolarized stars have allowed us to measure the instrumental polarization induced by GPI’s optics (Wiktorowicz et al. 2014). We describe here one such measurement, using β Pic as a low polarization standard. Additional calibration data including observations of polarized standards can be found in Wiktorowicz et al. (2014).

The observed instrumental polarization depends on both the telescope itself and GPI’s internal optics; since these are fixed with respect to one another there is no need to distinguish between them and so we use “instrumental polarization” to refer to their combination. Zemax modeling of the reflections and phase retardances of the optics upstream of the GPI half-wave plate predict an instrumental linear and circular polarization of order P’ ∼ 1% and V’ ∼ 10%, respectively. The dominant effects on incident unpolarized light are expected to be crosstalk into Stokes U and V.

In the instrument reference frame, stellar polarization vectors rotate with parallactic angle. In contrast, the instrumental polarization vector is independent of parallactic angle. Therefore, a sufficiently large range in observed parallactic angle provides a modulation by which stellar and instrumental polarization may be disentangled. This holds true regardless of the level of the stellar polarization, providing a powerful technique by which any sufficiently long science sequence can be inherently self-calibrating for instrumental polarization. The largest range in parallactic angle obtained during the first night of GPI polarization was for the circumstellar disk and exoplanet host star β Pic, for which an H-band observing sequence achieved a rotation of ∼92° in parallactic angle, as indicated in Table 1. In total integrated light, the contribution from the disk is very small. (For instance, β Pic has a measured degree of linear polarization P = 0.089% ± 0.024% at P.A. 65.2 ± 8.0° east of celestial north in a 700–900 nm bandpass; Tinbergen 1982). Thus we can use this long H-band sequence to enable precise measurement of the instrumental polarization. These observations were taken in AO closed loop, coronographically occulted mode with the waveplate rotated between subsequent observations to modulate Stokes Q and U of the beam; the rotation of the pupil with parallactic angle additionally modulated at a different rate the stellar contribution to the beam’s polarization. Each frame was reduced into a data cube containing the two orthogonal linear polarizations split by the Wollaston prism analyzer. Aperture photometry was performed on the occulted PSF in each image, and the fractional polarization pfrac = (I∗ − I)/I∗ + I calculated. A model fit to these data as a function of parallactic angle yields both the instrumental and stellar polarizations.

From these observations, we determine instrumental polarization in the H band to be I → (Q’, U’, P’, V’) = (∼−0.037% ± 0.010% ± 0.0438% ± 0.0075%, 0.4354% ± 0.0075%, −6.64% ± 0.56%), where ±Q’ are referenced to the Wollaston prism axes in GPI. As expected from the Zemax modeling, the dominant terms are crosstalk into U and V, and the magnitude of these effects is broadly consistent with expectations. The stellar polarization of β Pic is measured to be (Q, U, P, Θ) = (−0.0367% ± 0.0085%, −0.0164% ± 0.0091%, 0.0402% ± 0.0087%, 102:1 ± 6:6), where +Q is 30 The analysis conducted here concentrates on measuring the apparent stellar polarization from the bright portions of the PSF, and is not particularly sensitive to disk-scattered light. The same β Pic data analyzed instead via differential polarimetry will be presented in a future work (M. Millar-Blanchaer et al., in preparation).
5. OBSERVATIONS OF THE CIRCUMSTELLAR DISK AROUND HR 4796A

5.1. Previous Studies

Jura (1991) first identified HR 4796A, an A0V main-sequence star at 72.8 ± 1.7 pc, as having significant excess emission at IRAS wavelengths. The excess emission was subsequently resolved at mid-infrared wavelengths into a belt of dust at approximately 50–100 AU radius from the star (Koerner et al. 1998; Jayawardhana et al. 1998). Near-infrared Hubble Space Telescope (HST)/NICMOS coronagraphy yielded the first images of the dust in scattered light, revealing a belt or ring inclined to the line of sight by i = 73.1 ± 0.2°, with projected semi-major axis oriented at P.A. = 26.8 ± 0.6°, and higher surface brightness along the ansae at 1′.05 ± 0.02° radius (Schneider et al. 1999). These observations delivered an angular resolution of 0′.12 (8.8 AU) at F110W, and an inner working angle of approximately 0′.065 (47.5 AU). Subsequent ground-based AO images in the H band with Subaru/HiCIAO improved the angular resolution and inner working angle to 0′.062 (4.5 AU) and 0′.4 (29.2 AU), respectively (Thalmann et al. 2011). Additional NICMOS observations at five near-infrared wavelengths (1.7–2.2 μm) contributed color information indicating that the dust particles are predominantly red scattering (Debes et al. 2008). The belt-scattered light has also been detected at optical wavelengths using HST/STIS with 0′.070 angular resolution and inner working angle ≤0′.6 (Schneider et al. 2009). Additional images of the belt in thermal emission have been obtained at L′ (Lagrange et al. 2012) and 10–25 μm (Telesco et al. 2000; Wahhaj et al. 2005; Moerchen et al. 2011). The only polarimetric detection of the belt to date has been a modest detection in the H band, where the measured fractional linear polarization of the NE ansa is >29% (Hinkley et al. 2009).

One major area of investigation has been whether or not the HR 4796A belt is geometrically offset from the star in the same manner as Fomalhaut’s belt (Kalas et al. 2005). The “pericenter glow” hypothesis was originally proposed in reference to the tentative finding of greater thermal emission from the NE ansa of HR 4796A as compared to the SW ansa (Telesco et al. 2000). One explanation is that a bound companion (not necessarily a planet and not necessarily interior to the belt) on a non-circular orbit would be responsible for a secular perturbation that creates an eccentric belt with pericenter to the NE (Wyatt et al. 1999). If the belt has an azimuthally symmetric density, then the thermal emission from the NE ansa would be greater due to closer proximity to the star. However, if the assumption of azimuthal symmetry is dropped, then the belt could be centered on the star and the excess emission could be due to a density enhancement of dust to the NE. Therefore a direct, astrometric measurement of ring geometry relative to the star was needed to distinguish between these possibilities.

The HST/STIS optical (0.2–1.0 μm) data revealed a 2.9 AU (0′.04) shift along the major axis of the belt such that the brighter NE ansa is in fact closer to the star (Schneider et al. 2009). The Subaru/HiCIAO near-IR observations give offsets of 1.23 and 1.15 AU along the major axis and projected minor axis, respectively (Thalmann et al. 2011). These Subaru observations are best fit by an inclination to the line of sight i = 76°7, which implies the deprojected minor axis offset is 5.0 AU (approximately three times smaller than the stellocentric offset of Fomalhaut’s belt; Kalas et al. 2005). These results for the geometric offset of HR 4796A are confirmed in subsequent ground-based studies (Lagrange et al. 2012; Wahhaj et al. 2014), lending empirical support to the pericenter glow or secular perturbation model. However, the magnitude of the offset may not be sufficient to explain the difference in grain scattering and thermal emission between the two ansae (Wahhaj et al. 2014).

Other key measures of the system include the radial and azimuthal profiles of the belt. The radial profiles in both thermal emission and scattered light indicate a very sharp belt inner edge and a less steep outer edge. Lagrange et al. (2012) demonstrated that the radial profile of the ring’s inner edge along the apparent projected semi-major axis is consistent with a numerical model that assumes an 8 MJ planet with a semi-major axis a = 99 AU that dynamically clears the interior region of the belt. Planet detection limits in the infrared have previously excluded the existence of planets located along the major axes greater than ~3 MJ, although in regions near the minor axes such a planet would not have been detected.

In addition to the difference in brightness between the two ansae, the ring’s surface brightness shows an asymmetry between the east and west sides which has been attributed to a scattering phase function that differs between forward and back scattering. Schneider et al. (2009) model the observed optical brightness asymmetry between the east and west sides of the belt with a Henyey–Greenstein asymmetry parameter g = 0.16 ± 0.06. Thalmann et al. (2011) find g = 0.1 based on their H-band data. It is generally assumed that the small grains that dominate the surface density of the belt preferentially forward-scatter. Therefore, the brighter east side of the belt has been thought to be the side closer to observers on Earth. The near-infrared polarimetry presented in this study now calls into question this interpretation.

5.2. Observations and Data Reduction for Polarized Intensity

HR 4796A was observed in polarization mode on the second and third GPI observing runs, in 2013 December and 2014 March, respectively, as detailed in Table 1.
The 2013 December 12 UT observations occurred just before dawn in good seeing conditions. We obtained brief sequences in both the $H$ and $K$ bands. The target was acquired via standard GPI acquisition and coronagraph alignment processes (Dunn et al. 2014; Savransky et al. 2014). Since the atmospheric dispersion compensator (ADC) was not yet in use, we manually applied position offsets to the calibration unit’s low-order wavefront sensor tip-tilt loop to center the star on the occulter at the start of each sequence. Halfway through the $H$ sequence, the IFS cryocoolers were throttled down to reduce their induced vibrations. Modifications to the IFS and AO control laws in early 2014 have mitigated the level of vibration for subsequent observations, and further mitigations are ongoing (Larkin et al. 2014; Poyneer et al. 2014; Hartung et al. 2014). The waveplate was rotated between P.A.s of $0^\circ$, $22^\circ$, $45^\circ$, $68^\circ$ for the sequence of exposures. Sky background observations in $K$ 1 were taken immediately afterward, offset $20''$ away using the same instrument settings. Given the lack of ADC, there is some slight blurring of the PSFs due to atmospheric differential refraction, but the size of this effect is small ($\sim 32$ mas in the $H$ band, $15$ mas in the $K1$ band) compared to the scale of a diffraction limited PSF. The disk around HR 4796A is easily visible in individual exposures.

On 2014 March 25 UT, a second set of observations were taken in $K1$ band with the target near transit to obtain increased field rotation. The polarimetric observations were split in two blocks, with a short series of spectral mode observations sandwiched between them. The total field rotation across the whole polarimetric data set is $33^\circ$. The observation procedures and total integration time were similar to those in December, including the acquisition of skies immediately afterward. The one significant change is that the ADC was by this time available (Hibon et al. 2014). It was used for these observations as a commissioning test, even though at airmass $\sim 1$ pointing only $10^\circ$ from zenith it was not strictly necessary. As with the December data the disk is easily seen in individual raw exposures.

All observations were reduced using the methods in Section 3. Figure 7 shows the results for the 2014 March data set, including one individual orthogonal polarization input image, the combined total intensity image resulting from a least-squares average of the input images (i.e., what the differential polarimetry reduction yields for Stokes $I$) and the polarized intensity $P = (Q^2 + U^2)^{1/2}$. In the polarized intensity image, the stellar PSF is highly suppressed and the disk appears as a bright half-ring on its western side. For the first time, the disk can be seen all the way in to its projected closest approach to the star, at least on the western side. In fact the polarized intensity is brightest at the smallest separations. In polarized light, there is no surface brightness peak at the ansae relative to the adjacent portion of the ring to the west, contrary to prior polarimetry at lower contrast and S/N (Hinkley et al. 2009). On the eastern side of the ring, the polarized surface brightness is sufficiently faint that the disk is not detected (see Section 5.3).

This polarization asymmetry is a robust result. Looking at the individual exposures in an observing sequence, it is immediately apparent that the disk’s surface brightness on the west side is modulated by the wave plate rotation and generally differs between the two orthogonal polarizations; in contrast the east side shows no such modulation. Furthermore, this result is repeatably observed in all three data sets, $H$ and $K$ 1 in December and $K1$ again in March (see Figure 8). We also note that archival VLT/NACO polarimetry of HR 4796A independently detects this asymmetry (Milli et al. 2014). Given the overall consistency of the three GPI data sets, we choose to concentrate on the March $K1$ observations for further analyses since they were observed at...
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Figure 8. Comparison of the three available data sets including two at K1 and one at H. The data set in each row is labeled at left, while the quantities displayed are shown above each column. The first column shows the total intensity images, without PSF subtraction. Comparing the two K1 data sets, it can be seen that the March data set has slightly improved contrast (due in part to observation at lower airmass.) Data are shown on linear display scales from 0 to 50 or 100 counts s\(^{-1}\) for H and K1, respectively, and the displayed field of view is 2\('\)5 across. The second column shows PSF-subtracted total intensity images following the method in Section 5.4. In the December data with small field rotation (≈2\(\circ\)), the satellite spots remain as residual systematics in the PSF-subtracted images, but the larger rotation for the March data set (33\(\circ\)) mitigates this and a cleaner PSF-subtracted total intensity image is achieved. Data are shown with linear display scale from 0 to 6 counts s\(^{-1}\). The third column shows the polarized intensity images. Here, despite the differences in wavelength and field rotation, the observations are in extremely good agreement. Data shown with linear display scale from 0 to 3.5 counts s\(^{-1}\). The fourth column shows the linear fractional polarization P/I, with overall general agreement among data sets but limited by the varying PSF subtraction qualities in the second column. Data are masked out (displayed as white) in regions where we cannot measure P/I with confidence: either P<3\(\sigma_P\), or P/I > 100\%, or I<0 in the PSF-subtracted images, or within 1\(\lambda/D\) of the occulting spot edge. Circles indicate the occulting spot sizes, 0\('\)246 and 0\('\)306 in H and K1, respectively.

lower airmass and with a much greater range of parallactic angle rotation. Note also that the overall consistency of results between the December and March K1 data confirms, as expected, that the ADC (absent in December but present in March) does not substantially change the polarization of transmitted starlight.

5.3. Polarized Intensity and Position Angle

From the Stokes Q and U maps, we construct a polarized intensity image \(P = (Q^2 + U^2)^{1/2}\) that is corrected for the inherent bias resulting from the strictly positive nature of this quantity following the approach of Vaillancourt (2006). To reduce the biasing impact of noise, the Q and U images are slightly smoothed by convolution with a Gaussian with FWHM = 2 spaxels (28 mas) prior to computing P. Uncertainties in the polarized intensity image, \(\sigma_P\), are computed based on the measured background noise in the Stokes Q and U maps, assumed to apply uniformly to all spaxels including those where the ring is located.

From the Q and U maps we also compute the polarization P.A. \(\theta = (1/2) \arctan(U/Q)\) and its associated uncertainty. Scattering off dust particles results in polarization vectors that are oriented in an either azimuthal (centrosymmetric) or radial pattern. For all spaxels where \(P > 3\sigma_P\), we find that the polarization vectors are organized in azimuthal fashion, as shown in Figure 9. In the 2014 March K1 data, the mean deviation of the P.A.s relative to the expected azimuthal pattern is 0\(\circ\)9 with a dispersion of 5\(\circ\)6, as shown in Figure 10. There is a marginal offset of 2:2 in the deviation measured from the northeast and southwest halves of the ring. This may indicate that the location of the star as estimated from the astrometric spots is slightly offset from its true position. The measured dispersion is only marginally wider than the predicted dispersion of 4\(\circ\)6 based on the distribution of uncertainties on the polarization P.A. for each spaxel where \(P > 3\sigma_P\). The P.A.s are thus consistent with single scattering illuminated by the central star.

Recent astrometric calibration measurements for GPI suggest there may be a \(\sim 1\circ\) offset between the coordinate frame of
pipeline-processed derotated datacubes and true sky coordinates (Konopacky et al. 2014). Since the Wollaston prism is located after the lenslet array, it must be affected by this offset as well, so the reference frame for Stokes parameters is likely rotated by this amount. For the purposes of checking P.A.s about the central star, the offset in lenslet position and in P.A. \( \theta \) will cancel out so the histogram should not be biased. However the above astrometric calibration of GPI is preliminary so conservatively all P.A.s should be considered uncertain to at least \( \pm 1^\circ \).

### 5.4. PSF Subtraction for Total Intensity

While the polarized intensity image \( P \) is essentially free of residual starlight, the total intensity image \( I \) of the ring is affected by significant contamination from the stellar PSF as well as by thermal background in the \( K1 \) band. In order to measure the polarization fraction, \( p = P/I \), we separately reduce the same data via different algorithms to obtain PSF-subtracted images of the disk in total intensity.

As mentioned in Section 3, ADI plus the KLIP algorithm (Soummer et al. 2011) is one effective method to remove the PSF. This requires substantial field rotation during the observations, which was only obtained in the 2014 March observations. Reducing these data using the ADI+KLIP implementation included with the GPI pipeline yields the left hand image shown in Figure 11. The ring can now be traced in total intensity almost to the projected minor axes. Several noteworthy details can be seen in this image. The ring appears brighter in total intensity on the east side by about a factor of two; this is particularly visible near the northeast ansa. The brightness does not peak at the ansae as might be expected for an optically thin ring with isotropic scatterers, but rather is brightest in diffuse arcs just to the east of either ansa. Radially outward from either ansa, a more extended surface brightness component is visible. These regions have previously been termed “streamers” by some; however, they probably do not represent unbound dust particles literally streaming away from the ring, but rather loosely bound particles on eccentric orbits after collisional production in the ring (Strubbe & Chiang 2006). This smooth component almost certainly extends azimuthally around the entire ring, and is only seen at the ansae due to a combination of the increased optical depth from the line of sight and the spatial filtering action of the PSF subtraction process.

A limitation of the KLIP algorithm is that it is not flux-preserving for either point sources or extended structures such as disks. Due to this systematic bias the apparent surface brightness in the KLIP-processed total intensity image is less than the observed polarized intensity. As a result, if we take the ratio \( P/I \) we obtain unphysical polarization fractions higher than \( 100\% \) for much of the disk. Forward modeling of the algorithm throughput is one route to mitigating this effect, but in this case since the ring can be easily seen in individual raw images we can take a simpler approach.

In order to obtain a total intensity image in which the ring’s scattered light flux is preserved, we developed an independent PSF subtraction method that takes into account the specific geometry of the HR 4796A ring, which only covers a small fraction of the spaxels within the field of view in any given exposure. First, we masked out a region defined by two concentric ellipses that bracket the ring, as well as circular spots at the location of the GPI satellite spots (in the case of the \( H \)-band data, we masked two sets of four spots, as some of the AO “waffle mode” spots at the corners of the dark zone were located close to the...
Figure 11. Two versions of PSF-subtracted total intensity images. Left: angular differential imaging (ADI) reduced using the KLIP algorithm, specifically the code implemented as part of the GPI data pipeline. Right: an alternate approach using a smooth model for the PSF halo generated after masking out the disk and interpolating across the masked region. See Section 5.4 for details. The light blue dashed circle indicates the radii inside of which we consider the data unreliable due to subtraction residuals. The inner dark circle indicates the coronagraph occulting mask, 0.306′′ in diameter. Note the different display scales as indicated by the color bars. The KLIP-processed image has a two times better inner working angle but oversubtracts about ∼75% of the flux.

We visually inspected the estimated PSF images and standard deviation maps obtained for each observing sequence to identify the optimal parameters and determine the region where the total intensity fluxes seem to be reliably recovered. Based on this inspection, we conservatively estimate that this PSF subtraction method yields good results for the $K_1$ observations beyond 50 spaxels (0.7′′) from the central star. At the $H$ band, the proximity of satellite spots and the AO PSF “waffle mode” spots significantly reduced the number of usable spaxels in the immediate vicinity of the ring to interpolate the PSF. The lack of significant field rotation during these observations further enhances this issue because systematic errors in the interpolation procedure do not average out as they do in the 2014 March observations. As a result, the final 2013 December $H$-band PSF-subtracted image is of substantially lower quality and we do not consider it further. The two $K_1$ data sets yield generally similar results to one another.

In essence, this interpolated model PSF subtraction has traded larger inner working angle for improved flux conservation. The resulting disk surface brightness is typically three to five times higher than in the KLIP-processed images. Computing polarization fractions yields physically plausible values (Section 5.6). Many of the same features can be seen as in the KLIP image, including the brighter east side, the bright diffuse arcs offset just east from each ansa, and the brightness minimum on the southwest side near P.A. = 230°. A decrease in disk surface
brightness at this location has previously been reported (Schnei-
der et al. 2009; Thalmann et al. 2011; Lagrange et al. 2012). The
“streamer” features outside of the ansae are not visible in this
reduction, which is to be expected considering that this area was
outside of the masked region and thus any disk component there
is largely subtracted away.

5.5. Ring Geometry

The geometry of the scattered-light ring is expected to trace the
locations of dust grain parent bodies and be dependent upon
the viewing angles to the system. The dynamical forces acting
on dust particles can also affect the extent of the ring, and
gravitational perturbations can induce an offset from the star.
As discussed in Section 5.1, this system has a measurable extent
and an offset from the star. Characterizing these effects can be
used to explore the underlying physics affecting the distribution
of dust around the star.

We have attempted to constrain the basic geometry of the
ring using a simple model fit to the imaging data. Our model is
constructed using an ellipse, with one focus centered on the star,
and the corresponding Euler angles describing the orientation
of the ellipse. A small but finite extent to the ring is generated by
using an ensemble of ellipses scaled from the reference ellipse.
This scaling is performed so that all ellipses share the same
geometrical center. For simplicity, we assume a flat surface
density profile; such a profile has been shown to be inadequate
to describe the full extent of the ring (e.g., Thalmann et al.
2011), but our primary aim is modeling the ring geometry and we
defer more detailed modeling for future work. We allow
for the one-dimensional brightness distribution around the ring
to vary, parameterizing the product of the volume density by
the scattering phase function with a smooth, periodic spline
function of the anomaly. The computed brightness is scaled
by the inverse square law using the distance from the star.
Separate brightness functions are used for the PSF-subtracted
total intensity and for the linearly polarized intensity, though
the geometrical parameters are shared. The resulting brightness
distribution is smoothed by a azimuthally symmetric Gaussian
to represent the unocculted PSF; the characteristic width of this
Gaussian is a fit parameter.

The model is jointly fit to the PSF-subtracted total intensity
and linearly polarized intensity K1-band images from 2014
March (second and third panels in the bottom row of Figure 8,
or equivalently the right-hand panels of Figures 7 and 11). Both
data and model are high-pass filtered prior to comparison, with
a Gaussian filter of 20 pixels (0′.28) FWHM. This mitigates
the mismatch of the true unocculted PSF to the assumed Gaussian
and filters low-spatial-frequency errors in PSF subtraction in
the total intensity image. For consistency, both total intensity
and the linearly polarized image are equally filtered. Errors are
assumed to be uncorrelated and Gaussian in each pixel. The
error level is first estimated by computing a robust estimate
of the standard deviation of the image data in 1 pixel annuli.
However, the resulting dispersion is affected by the presence of
the disk in the image data. After a trial fit, the errors are updated
using the standard deviation estimate from the residual image
data. In determining the goodness of fit, the model and data
are compared over a rectangular region encompassing the disk
emission in the high-pass filtered image. Both the total intensity
and polarized intensity images are dominated by residual stellar
speckles in the central region, so a star-centered circular region
is masked out in both images. The mask radii are 50 and 12 pixels
(0′.7 and 0′.17) in total and polarized intensity, respectively,
corresponding to the masked regions shown in Figures 11 and 7.

The residuals between the images and models are combined with
the error estimates to compute a χ² goodness of fit metric. This
is optimized with a Levenberg–Marquardt least-squares fitter.
The residuals from the least-square fit show spatial correlation
on the scale of image resolution elements, as expected given
some amount of residual unsubtracted speckle noise.

We scale the χ² metric so that it indicates the error per-
resolution-element (rather than per-pixel), and use the resulting
best-fit model to seed an ensemble Markov Chain Monte
Carlo calculation (Foreman-Mackey et al. 2013). Using the
marginal distributions of samples drawn from the ensemble
MCMC calculation, we present the mean parameters and their
standard deviations in Table 2. The marginal distributions
are Gaussian-like and do not exhibit long tails. The relatively small
error intervals suggest the model is overly constrained; this
can arise when there is a mismatch between the model and
observations. In this case, the shape of the assumed PSF and
the flat surface density profile may play significant roles.
We defer a more thorough treatment to our follow-up work (M. P.
Fitzgerald et al. in preparation), and present here these formal
statistical uncertainties while urging appropriate caution in their
interpretation.31 We have accounted for the astrometric error
in scale and orientation using the results of Konopacky et al.
(2014). Sizes in AU are computed assuming a distance of
72.8 pc, and errors do not account for distance uncertainty. The
offset of the ring is manifested in the nonzero eccentricity of
the derived Keplerian orbit. When combined with the Eulerian
viewing parameters (i, ω, Ω), the best-fit offsets of the ring
center relative to the star are 0.56 ± 0.06 AU to the west,
and 1.33 ± 0.13 AU to the south, consistent with previous
estimates (Schneider et al. 2009; Thalmann et al. 2011). The
ring is resolved at the ansae by these GPI observations, with a
radial extent of ~8 AU (0′.11). However, detailed inferences of
the radial brightness distribution are deferred to future analysis.

The fitting procedure outlined above provides a first estimate
of the ring geometry but makes several assumptions that can
affect the reliability of the ring model parameters. First, the
Keplerian description for the shape of the ring is likely incorrect.
Keplerian ellipses will describe the orbits of individual particles,
but the ensemble of particles need not follow this description.
The eccentricity controls both the shape of the ring and the offset
of the ring center from the star. Secularly perturbed disks made
of ensembles of grain orbits have different behavior (Wyatt et al.
1999), so our estimate of the offset may be biased. A proper

31 A common approach to dealing with improbably small fit uncertainties is to
rescale the uncertainties by the reduced χ², which implicitly assumes that the
model form is good but the observational uncertainties were underestimated.
That is not the appropriate course here, since we know given the intentional
simplifying assumptions that the model form is mismatched.
physical description will require a revised model. By using the ellipticity of a keplerian orbit to determine the ring offset, the estimate of inclination can differ from previous studies that relied on the ratio and projected major and minor axes. We have additionally required the star to be at the focus of our reference ellipse, but an improved description may allow an offset of the system’s center of mass. The derived parameters rely on astrometric calibration of the P.A. and pixel scale. Additionally, we may be underestimating random errors and neglecting correlations in the data that can also affect the confidence intervals of the fit and derived parameters. Finally, we have made an assumption of a flat surface density as a function of distance from the star at a given azimuth, while previous works have found steep declines at large separations; however this is partially mitigated by our high-pass filtering of the data prior to model fitting. These simplifying assumptions have additionally required the star to be at the focus of our reference ellipse, but an improved description may allow an offset of the system’s center of mass. The derived parameters rely on astrometric calibration of the P.A. and pixel scale. Additionally, we may be underestimating random errors and neglecting correlations in the data that can also affect the confidence intervals of the fit and derived parameters. Finally, we have made an assumption of a flat surface density as a function of distance from the star at a given azimuth, while previous works have found steep declines at large separations; however this is partially mitigated by our high-pass filtering of the data prior to model fitting. These simplifying assumptions reveal themselves in the relatively high chi^2 of the final fit we obtained, and as noted above we plan to continue to improve this modeling framework in a future work.

5.6. Polarimetric Scattering Properties versus Scattering Angles

We combine the debiased polarized intensity and interpolated-model-PSF-subtracted total intensity images to generate a map of polarization fraction around the ring. To enable direct comparison with predictions from dust models, we evaluate the scattering angle that characterizes each spaxel in the image based on the location of the star and under the assumptions that the ring is geometrically flat and that the star is coplanar with the ring.

Understanding which side of the ring is located closer to us, and thus is characterized by scattering angles <90°, is necessary to determine the scattering angles. Unfortunately, past observations have not allowed to unambiguously determine this. Figure 12 illustrates the two possible viewing geometries. Generally speaking, the side of a disk that is brightest in total intensity is assumed to be the front side, since scattering off dust particles typically favors forward scattering. In the case of the HR 4796A ring, the east side of the ring is brighter than the west side in the visible and near-infrared, and previous studies have taken that as evidence the east side is closer toward us (Schneider et al. 1999, 2009, see in particular Section 4.4 of the 2009 paper). Schneider et al. (2009) also found that the ansae brightness peaks are systematically displaced toward the east of the major axis (their Figure 4), which is taken as additional evidence for forward scattering on the east. Our new GPI data reproduce and confirm these features: in total intensity, the disk is brighter on its east side by a factor of up to ~2, and the brightest peaks of the ansae are east of the major axis. However, at longer wavelengths the west side becomes equal in brightness to the east side, if not slightly brighter (Lagrange et al. 2012, Milli et al. 2014), leaving unresolved the ambiguity of which side is closest to the observer.

In polarized intensity, we see a strikingly different result: the east side is much brighter in linear polarized intensity than the west side in the visible and near-infrared, and previous studies have taken that as evidence the east side is closer toward us (Schneider et al. 1999, 2009, see in particular Section 4.4 of the 2009 paper). Schneider et al. (2009) also found that the ansae brightness peaks are systematically displaced toward the east of the major axis (their Figure 4), which is taken as additional evidence for forward scattering on the east. Our new GPI data reproduce and confirm these features: in total intensity, the disk is brighter on its east side by a factor of up to ~2, and the brightest peaks of the ansae are east of the major axis. However, at longer wavelengths the west side becomes equal in brightness to the east side, if not slightly brighter (Lagrange et al. 2012, Milli et al. 2014), leaving unresolved the ambiguity of which side is closest to the observer.

Figure 12. Scattering angles around the ring for two possible orientations of the HR 4796A disk as observed from Earth. Based on the greater brightness in total intensity to the east and an assumption of predominantly forward scattering, prior works have more often favored the geometry on the left in which the east side of the ring is closer to us. However, based on the observed polarized intensities we now argue for the hypothesis at the right. The maximum and minimum scattering angles θ are 15° and 165° in either case, but flipped between minor axes.

![Figure 12. Scattering angles around the ring for two possible orientations of the HR 4796A disk as observed from Earth. Based on the greater brightness in total intensity to the east and an assumption of predominantly forward scattering, prior works have more often favored the geometry on the left in which the east side of the ring is closer to us. However, based on the observed polarized intensities we now argue for the hypothesis at the right. The maximum and minimum scattering angles θ are 15° and 165° in either case, but flipped between minor axes.](image-url)
the $[35,200]\degree$ range of P.A.s. The scattering properties of many types of astrophysical dust, across a wide range of assumed compositions and size distributions, have stronger polarized intensities on the forward scattering side, so this result appears directly to contradict the previous hypothesis that the east side is the front. The polarized intensity image yields a much stronger asymmetry than that seen in total intensity. We therefore make the assumption that the west side is closest to the observer and use this convention to determine the scattering angles. If the east side is the closest side instead, the angle we have computed is the so-called phase angle, i.e., the supplementary angle of the actual scattering angle. The reasoning behind this choice is discussed at greater length in Section 6.

We constructed total intensity and polarization fraction curves as a function of scattering angle in $5\degree$ bins (Figure 13). We limit the explored range of scattering angles to $[40,140]\degree$ to avoid the regions where substantial artifacts may be introduced by the PSF subtraction procedure. Overall, there is relatively little difference between the polarization fractions measured along the NE and SW ansae, as would be expected if the dust properties are uniform across the ring: the mean difference in polarization fraction for each $5\degree$ bin between the two ansae is $3\% \pm 5\%$. The largest differences ($10\% \pm 3\%$) are measured close to our $0\degree$ exclusion zone radius and may indicate that PSF subtraction is imperfect. Consequently, we compute total intensity and polarization fraction curves that average over the two ansae, and use the largest of the formal statistical uncertainties and the half-difference between the two ansae as the final uncertainty at each scattering angle.

On the east side of the ring for scattering angles larger than $110\degree$, too few spaxels have $P > 3\sigma_P$ and only an upper limit on the polarization fraction can reliably be estimated for this region, as illustrated in Figure 13. The observed polarization fraction rises smoothly from less than 20% on the east of the ring to up to 50% on the west side, with a possible plateau or turnover for scattering angles $\lesssim 60\degree$.

On the west side of the ring, the polarized intensity can be reliably measured at all scattering angles down to the minimum $15\degree$ allowed by the inclination of the ring. Unfortunately, the total intensity cannot be reliably estimated in the P.A. range $[230,360]\degree$ due to the strong residual PSF artifacts. Still, a lower limit to the polarization fraction can be estimated from the raw total intensity image. Directly dividing the polarized intensity map by the raw total intensity image yields a strict lower limit of about 3% along the ring semi-minor axis on the west side of the star. A more useful lower limit can be estimated by taking advantage of the azimuthal near-symmetry of the PSF. Specifically, for each narrow annulus centered on the star, we use the lowest pixel flux as a conservative estimate of the PSF flux at this stellocentric distance and subtract this value from all pixels in the annulus. In essence, the underlying assumption of this method is that the ring does not lie on top of the faintest region of the PSF. If this is true, we then obtain an upper limit on the total ring brightness at each position. From this new “PSF-subtracted” image, we can compute a polarization fraction map and use the same averaging in scattering angle bins to produce a lower limit curve for the polarization fraction along the ring. This lower limit is about twice as low as our estimated ring polarization fraction for all scattering angles where we were able to measure it. Furthermore, we find that the minimum polarization fraction along the ring semi-minor axis is about 10%. The resulting lower limit is illustrated in Figure 13.

6. ANALYSIS OF THE RING AROUND HR 4796A

6.1. Exploratory Scattered Light Models of the HR 4796A Ring

In this section, we explore possible models of the HR 4796A ring that reproduce the observed total intensity and polarization fraction maps derived from the new GPI observations. We limit our discussion to the context of Mie scattering, i.e., to spherical dust grains. We note, however, that elongated but randomly oriented dust grains have scattering properties that approach...
Figure 14. Total intensity (black) and polarization fraction (red) curves for optically thin Mie scattering models assuming astronomical silicate composition and narrow size distributions ($a_{\text{max}}/a_{\text{min}} = 2$). The four panels represent models for (a) $a_{\text{min}} = 0.1 \, \mu m$, (b) $a_{\text{min}} = 0.4 \, \mu m$, (c) $a_{\text{min}} = 1 \, \mu m$, and (d) $a_{\text{min}} = 5 \, \mu m$, respectively. Dotted portions of the red polarization curves represent the “negative polarization” regime, i.e., situations in which the polarization vectors are radial instead of azimuthal. These curves can be directly compared with the observed curves for HR 4796A, shown in Figure 13.
total intensity phase function with a sharp peak at the ansae, although it seems sharper than is actually observed in the GPI data (FWHM of about 30° and 60° for the model and observed curves, respectively). However, such a model produces a polarization curve that is in clear contradiction with observations: for such small grains, the polarization fraction is maximal around 90° scattering angle and declines symmetrically toward the front and back scattering regimes. Such a symmetric peak is characteristic of scattering by small grains ($2\pi a/\lambda < 1$, where $a$ is the grain size), irrespective of their composition within physically plausible limits. Our observations thus strongly exclude that sub-micron grains are the dominant contributors to scattering in the ring.

Increasing the grain sizes by a factor of a few results in models that simultaneously fail at reproducing the total intensity and polarization fraction curves, as illustrated in Figure 14(b). As expected for grains with size parameter $2\pi a/\lambda \approx 1$, forward scattering is heavily preferred and so one side of the ring is several times brighter than the other. This asymmetry is closer to matching the observations in some regards. However, the polarization fraction now presents two peaks, around 60° and closer to matching the observations in some regards. However, such a model produces a polarization curve that is in clear contradiction with observations: for such small grains, the polarization fraction is maximal around 90° scattering angle and declines symmetrically toward the front and back scattering regimes. Such a symmetric peak is characteristic of scattering by small grains ($2\pi a/\lambda < 1$, where $a$ is the grain size), irrespective of their composition within physically plausible limits. Our observations thus strongly exclude that sub-micron grains are the dominant contributors to scattering in the ring.

The resulting total intensity and polarization curves, shown in Figure 15, confirm the qualitative expectations set above. In particular, the shape of the polarization is a reasonable match to the observed one, with a peak at $\approx 60^\circ$ and a decline by a factor of about two between scattering angles $50^\circ$ and $120^\circ$. However, the model over-predicts the polarization fraction by $\approx 20\%$ at all scattering angles, which may indicate that the grains have small-scale surface irregularities. More simply, grain distributions extending to a somewhat smaller minimum particle size, or with a narrower distribution, would have a lower peak polarization fraction, as illustrated by the comparison between Figures 14(d) and 15. We note that a slightly smaller minimum grain size is more likely than a narrow grain size distribution. For the $5 \mu m$ minimum grain size, the total intensity curve is relatively symmetric for $\theta_{\text{scat}}$ in the range $30^\circ$–$50^\circ$, and the intensity this regime, the phase function has a shallow dependence on scattering angle. In other words, because we sample a limited range of scattering angles, the apparent phase function could be nearly isotropic even though it is intrinsically very much anisotropic. Furthermore, Fresnel scattering leads to polarization curves which peak at scattering angles much smaller than 90°, and as small as 40°. Qualitatively, both of these behaviors are consistent with the GPI observations.

To produce a physically plausible explanation for the observations, we construct a model in which grains follow a $N(a) \propto a^{-3.5}$ (Dohnanyi 1969) power law distribution and range from 5 $\mu m$ to 1 mm. The maximum grain size was selected so that even larger grains would not contribute significantly to scattering in the near-infrared or to thermal emission out to 870 $\mu m$, the longest wavelength at which fluxes are available for this source. On the other hand, the minimum grain size was chosen as an approximate match to (1) the approximate blow-out side considering the luminosity of the central star ($\approx 4 \mu m$; e.g., Wyatt et al. 1999), and (2) the minimum grain size derived from SED analyses of the system ($\approx 2 \mu m$; e.g., Li & Lunine 2003). We also tried using much larger minimum grain size (50 and 500 $\mu m$), with no significant consequence on our conclusions, as all grains larger than about 5 $\mu m$ operate in the Fresnel regime limit.

The wavelength of our observations, increasing the grain size to even larger scales results in dust particles whose scattering properties can be approximated as Fresnel scattering off macroscopic dielectric spheres. Figure 14(d) illustrates a model with grain sizes in the 5–10 $\mu m$ range, which already are in the Fresnel regime for 2 $\mu m$ observations. In this configuration, a very strong forward scattering peak in total intensity is present but limited to small scattering angles ($\le 30^\circ$), which are poorly sampled in our total intensity images at best. Beyond

![Figure 15](image-url)
enhancement at the ansae is broader than in the small grain model. This is more in line with the observed intensity profile. However, the front side is still brighter by a factor \(\approx 2\) than the back side in this model, in contradiction with our observations.

### 6.2. Interpretation

This brief exploration of parameter space reveals that the scattering properties of the HR 4796A ring are more complex than may have been expected. While the total intensity phase function is most consistent with small particles \((a \lesssim 0.5 \mu m)\), the polarization curve calls for large particles in the Fresnel regime \((a \gtrsim 5 \mu m)\). A bimodal grain distribution cannot explain this behavior since scattering off dust grains cannot contribute polarized intensity without corresponding total intensity. Therefore, this apparent dichotomy suggests that at least one of the hypotheses in our simple models is not fulfilled. Merely modifying the grain size distribution, by changing its slope for instance, is insufficient to account for the contradiction since both observations appear to be characteristic of completely different grain sizes, and yet must instead be driven by the same dust grains. Here we hypothesize on possible explanations for the shortcomings of our exploratory models.

A first interpretation of the apparent dichotomy between the total intensity and polarization curves is that the dust grains contained in the ring do not obey Mie scattering. This would happen if they depart from a compact spherical geometry. Simply increasing the porosity of the grains does not improve the situation, as the polarization curve of porous grains is similar to that of even smaller compact grains. We have computed synthetic observations of a dust model with the same 5–1000 \(\mu m\) size distribution but for a 90% porosity and found that the polarization curve matches closely that of the 0.1–0.2 \(\mu m\) grain model. Fractal grains, in which the porosity of the grain is organized in a scale-invariant structure, are an expected outcome of low-velocity collisions between small dust grains (Blum & Wurm 2008). Fractal grains, however, have scattered light polarization curves that are bell-like and centered around 90°, much like small compact grains (Hadamcik et al. 2007), and therefore do not match the HR 4796A curve.

The dust grains in the HR 4796A ring could be elongated. Their scattering properties would depart from those of compact spheres if they are larger than about half the wavelength \((a \gtrsim 1 \mu m)\) and/or if they have some degree of correlation in their orientation. For instance, it is plausible that elongated grains are aligned in preferential directions via radiation pressure effects (Hoang & Lazarian 2014, and references therein). Considering the much higher complexity of scattering in this situation, we defer a detailed study of such elongated grains to a future paper.

A second possibility is that the ring is not axisymmetric. In the optically thin regime, local density enhancements in the ring readily convert to brightness enhancements, precluding a direct estimation of the scattering phase function from brightness variations along the ring. Our total and polarized intensity images do not reveal clear small-scale asymmetries (clumps or gaps), but smooth variations along the entire ring would be harder to identify. Such global asymmetries could be induced by a planetary mass companion, whose presence is possibly indirectly revealed by the apparent eccentricity of the ring (see Section 5.5). While total intensity does not track the scattering phase function alone in this situation, the polarization fraction is a robust tracer of the dust scattering properties. The interpretation would thus be that the grains are all large enough to be in the Fresnel regime, as expected from SED analyses. The west side of the ring, where the polarization fraction is highest, would indeed be the front side, whereas the fact that the east is brighter would indicate that its surface density is larger than that of the west side by a factor of \(\approx 2.5\), making up for the weaker phase function in the back-scattering regime. Such an extreme density asymmetry may not be physically plausible, and furthermore, this explanation relies on an ad hoc coincidental alignment of the asymmetry with our line of sight. It also does not provide a clear explanation for wavelength dependence of the apparent surface brightness asymmetry. However, a non-axisymmetric ring cannot be strictly ruled out based on these data.

A third possible interpretation is that the HR 4796A ring is not optically thin, contrary to general expectations and to the assumption built in our model calculations. If the ring is radially optically thick, only the innermost region of the ring is directly illuminated by the star. Because of the high inclination of our line of sight, this region is in direct view of the observer for the back side, but the corresponding region on the front side is hidden from view. Instead, the scattered photons received by an observer must pass through an appreciable optical depth of the ring itself and thus are strongly attenuated, resulting in a significantly reduced brightness ratio between the front and back sides of the ring. On the other hand, the polarization fraction curve would not be strongly affected in this context, so long as the optical depth does not exceed \(\gtrsim 10\) to prevent multiple scattering from becoming a dominant factor. To be effective, this scenario only requires a total optical depth of a few along both the radial and vertical directions: an optical depth of \(\tau_{2\mu m} = 1\) along the line of sight is in principle sufficient to produce an intensity attenuation of a factor of \(\approx 3\). Given our viewing geometry, and depending on the surface density profile and ring thickness, this could translate in an optical depth in the disk midplane of \(\tau_{2\mu m}^{mid} \approx 2–5\). This is a plausible configuration, considering the extremely high luminosity of this debris ring. Total dust masses in the range of 1–100 \(M_\oplus\) have been inferred from SED analyses (Augereau et al. 1999; Li & Lunine 2003). If the ring is both radially narrow and vertically thin (on the order of 1 AU or less), i.e., dynamically cold, such optical depth would be achieved. We defer to a later paper a thorough exploration of this scenario, but consider this is as a plausible explanation for the apparent contradiction between the total intensity and polarization curves observed in the HR 4796A ring.

In fact, this hypothesis appears to offer a consistent explanation for several aspects of the ring’s observed morphology, as depicted in Figure 16.

1. Consider the ansae. In total intensity the brightest regions are arcs just to the east of the two ansae. Under the above hypothesis, to the west of the ansae the disk is self-shadowing while to the east we can see the directly illuminated inner surface, explaining both the sign of the asymmetry seen for HR 4796A in total intensity and the offset of the brightest regions away from the ansae.

2. Furthermore, closer to the minor axes we see different behaviors on the east and west sides. Looking at the KLIP-subtracted total intensity in Figure 11 the west side of the ring remains relatively bright as one approaches the minor axis, all the way in to or even just inside the 25 spaxel radius inner working angle. However, on the east side, even though the ring starts out brighter near the ansae the surface brightness appears to drop as one gets closer to the minor axis. For forward scattering dust we naturally expect the surface brightness to increase as one approaches the forward
Figure 16. Schematic of the geometry and scattering for the ring under the hypothesis that the ring is optically thick. Not to scale, and depicted similar to a reversed color table such that darker indicates higher surface brightness. Top panel, side view: back-scattered light on the far (eastern) side has intrinsically low scattering efficiency and polarization but we have a direct view to the optical depth $\tau = 1$ surface where most scattering occurs. Forward scattering has much higher scattering efficiency and polarization; however, because the light we observe must pass through the disk, it is attenuated by self-absorption. The portion of the disk’s rim for which light can scatter directly to the Earth without self-absorption subtends a small solid angle, also reducing the observed intensity. Bottom panel, front view: in total intensity, the less attenuated light path makes the far side appear brighter near the ansae. However closer to the minor axes the intrinsically forward scattering phase function reverses the asymmetry. The increased scattering efficiency at the smallest scattering angles is sufficient to dominate over the self absorption to make the near side minor axis peak in brightness, while the minimal scattering efficiency near back scattering causes the surface brightness to drop near the far side minor axis. In polarized intensity (not shown) the higher polarizing efficiency for forward scattering makes only the near side detectable.

3. Lastly, this model naturally explains the apparent change in the east/west flux ratio as function of wavelength: Toward longer wavelengths $\gtrsim 3 \, \mu m$ the optical depth decreases so the ring becomes less self-shadowing and more light can be scattered through on the west side, while meanwhile the size parameter $2\pi a/\lambda$ decreases. The net result is that the east side being slightly brighter at $\lambda < 2 \, \mu m$ gives way to more isotropic scattering at longer wavelengths, just as observed.

6.3. Implications

If the HR 4796A ring is indeed optically thick at wavelengths shorter than 3 $\mu m$, then the intrinsic scattering properties of the particles dominating the optical depth may be well described by Fresnel scattering. This allows us to speculate on how the surface brightness may behave in the regions for which we do not yet have high S/N detections of the disk but which may be revealed by future observations. First, the total intensity phase function for large particles has an extremely strong peak at the smallest scattering angles; such particles are very strongly forward scattering, with the total intensity increasing by a factor of $\sim 5$ between $\theta_{\text{scat}} = 40^\circ$ to $\theta_{\text{scat}} = 20^\circ$ for the 5–1000 $\mu m$ case considered earlier. Such a strong peak should be apparent even through a moderate amount of intervening optical absorption such as we hypothesize occurs from an optical depth of a few through the disk. This implies that at the smallest scattering angles—i.e., near the west side semi-minor axis—the total intensity should increase dramatically. This area cannot be investigated cleanly using the total intensity data presented here due to the PSF subtraction residuals at these smaller separations. However, we see tantalizing evidence for such a peak in the polarized intensity: the portion of the ring closest to the minor axis, corresponding to scattering angles $\lesssim 20^\circ-25^\circ$, is unambiguously the brightest location in polarized intensity. This effect is seen even more strongly in the $H$ data than the $K$ data, as shown in Figure 8.
that the polarization fraction must decrease to zero for perfect forward scattering at $\theta_{\text{scat}} = 0^\circ$, so the polarization fraction at $20^\circ$ is likely declining compared to larger scattering angles. Indeed, the measured polarization fraction for the ring peaks at $\theta_{\text{scat}} = 50^\circ$ and then decreases at smaller scattering angles in a manner that appears entirely consistent with its reaching zero at $0^\circ$ as expected for straight ahead scattering. Linearly interpolating between this boundary condition and the smallest scattering angle for which we have a reliable measurement of the polarization fraction ($\approx 40\%$ at $40^\circ$) suggests that the polarization fraction is likely no more than $10\%$–$20\%$ at the disk’s western minor axis. For the polarized intensity to peak there, the total intensity must peak even more strongly. This model predicts that future observations with higher $S/N$ and/or greater field rotation that achieve better inner working angle will find that the total intensity sharply and dramatically peaks at the smallest scattering angles. The western minor axis of the disk likely has the overall maximum surface brightness of the ring.

Secondly, we can apply similar reasoning to the opposite side of the disk at the eastern minor axis where the scattering angles are largest. Our Mie scattering model for a $5$–$1000\ \mu m$ particle distribution predicts surface brightnesses for both total and polarized intensities that are below our upper limits, i.e., in agreement with observations. If the lower bound of that distribution is instead just a bit lower (as we hypothesized might help also improve the agreement in polarization fraction), then at large scattering angles the polarization fraction may begin to exhibit a so-called negative polarization branch, i.e., a portion of parameter space for which the observed polarization is radial rather than azimuthal in orientation. Negative polarization branches are a well-known and generally seen property of dust produced by solar system comets and asteroids (e.g., Levasseur-Regourd et al. 1996; Kiselev & Chernova 1978; Lasue et al. 2009; Hines et al. 2014), seen typically for scattering angles $\theta_{\text{scat}} > 160^\circ$. It is interesting to consider whether HR 4796A’s ring might exhibit at its eastern minor axis the $90^\circ$ reversal of polarization P.A.s that would be characteristic of a negative polarization branch. The maximum scattering angle of $166^\circ$ may be just barely enough to encounter the negative branch, depending upon the exact details of the scatterers. Near-infrared observations of some but not all comets show a negative polarization branch (Kiselev et al. 2015, and references therein), reflecting a diversity of dominant particle sizes between different comets. The spectral dependence of observed polarizations is complex but typically the negative polarization branch is more shallow in the NIR than the visible. Thus, even if such a branch is present for the dust around HR 4796A the absolute value of the polarization will be low, just a few percent, and detecting such a faint signal may be beyond the reach of even the latest generation of high contrast instrumentation.

High-resolution millimeter interferometry offers a complementary view of disks in thermal continuum and molecular gas emission. As ALMA moves into full operation it is already beginning to deliver some spectacular results. However, the optical depth effect we propose here to account for the NIR scattered-light brightness and polarization does not directly lead to any particular observational signature in thermal emission at millimeter wavelengths. Using our MCFOST model corresponding to Figure 15, we computed a simulated image at ALMA resolution and $450 \ \mu m$; this yields a typical ring without a significant front/back asymmetry. The asymmetry in our model at this wavelength is dominated by the known ring geometry offset. The proposed higher optical depth around $2 \ \mu m$ leads to little to no effect at ALMA wavelengths, where the opacity will have dropped well below unity.

In comparison with other circumstellar disks for which measurements of polarized scattering are available over a large range of scattering angles, HR 4796A shows both similarities and some unique aspects. Optical imaging polarimetry of AU Mic shows both strong forward scattering ($g \approx 0.7$) and high polarizing efficiency that peaks around $90^\circ$ scattering (Graham et al. 2007). Based on these data, Graham et al. concluded that the dust must be highly porous to reconcile the high forward scattering and the linear polarizing efficiency. The overall degree of polarization is similar between AU Mic in the visible and HR 4796A at $2 \ \mu m$, $\sim 40\%$; both are significantly more highly polarized than can be explained with typical cometary dust. However, for AU Mic the observations are consistent with Rayleigh-like polarizing efficiency peaking near $90^\circ$ which seems strongly ruled out for HR 4796A. Similarly, near-infrared polarization mapping of the AB Aur circumstellar disk (Perrin et al. 2009) and the GG Tau circumbinary ring (Silber et al. 2000; Pinte et al. 2007) both reveal polarization fractions that peak at scattering angles $\sim 100^\circ$, i.e., close to the Rayleigh regime $90^\circ$ prediction and unambiguously toward the back side of the disks. These few examples confirm that the scattered light polarization properties of the HR 4796A ring are unique among circumstellar disks thus far.

Very few debris disks seen at inclinations similar to that of HR 4796A have been imaged in scattered light to date, leaving little opportunity to compare their respective scattering phase functions over similar ranges of scattering angles. The two closest examples are Fomalhaut (Kalas et al. 2005) and HD 15745 (Kalas et al. 2007), both observed at about $67^\circ$ inclination. It is interesting to note that the A-type star Fomalhaut has a belt whose front-to-back scattered light brightness is close to unity whereas the F-type star HD 15745 has a strongly marked forward scattering preference. In the latter case, Kalas et al. (2007) concluded that grains sizes in the $1$–$10 \ \mu m$ range were the primary scatterers whereas much larger grains (up to $100 \ \mu m$) have been proposed in the case of Fomalhaut. Such large grains, which operate in the Fresnel regime are consistent with our conclusion regarding the HR 4796A ring. Unfortunately, neither of these two other disks has been detected in polarized scattered light, precluding a more complete comparison with HR 4796A.

Given the known total dust mass inferred from longer wavelength observations, for the HR 4796A ring to be optically thick in the near IR as we hypothesize, it must be geometrically thin and dynamically cold. Dynamical models are beyond the scope of this current study. Thébault & Wu (2008) have previously suggested that a dynamically cold model for HR 4796A provides a good fit to the sharp outer edge of the ring. Rings are a relatively common form for debris disks, and based on the similarity of orbital radii and characteristic temperatures, the Kuiper Belt is often taken as a basis for comparison. However, the Kuiper belt is strongly dynamically stirred by its interaction with Neptune, and a substantial fraction of its constituent planetesimals are on highly inclined and/or eccentric orbits. Fully a third of currently known trans-Neptunian objects have orbital inclinations greater than $10^\circ$. A better solar system analogy might be one of the rings of Saturn, which are optically thick while having a very small scale height. The narrowest rings are shepherded
by the gravitational influence of small moonlets orbiting just inside and outside of the ring. It is tempting to speculate that a similar process is at play around HR 4796A. Previous work has found that the sharp inner and outer edges of the disk are potentially explainable using the dynamical influence of two planets, one relatively close inside the ring and the other outside (e.g., Lagrange et al. 2012). Dynamical modeling of these new observations from GPI will help test this scenario.

7. SUMMARY AND FUTURE PROSPECTS

The first light observations of HR 4796A presented here demonstrate the discovery potential of GPI. The high performance AO system and coronagraph enable the ring to be seen clearly in total intensity images both without and with PSF subtraction. Differential polarimetry not only provides dramatic starlight suppression by two orders of magnitude or better, it also is yielding new astrophysical insights into the constituents of circumstellar disks through constraints built on measurements of the scattering phase functions.

The first-of-its-kind integral field polarimetry architecture of GPI is optimized for high contrast polarimetry. While this architecture—and the fact that GPI always observes in ADI mode—does complicate some aspects of data reduction, we have developed the necessary methods and shared them with the community as part of the GPI data reduction pipeline. The calibration observations presented here for starlight suppression and instrumental polarization are part of a long-term effort to comprehensively characterize GPI’s performance as a polarimeter. These early results establish clearly that GPI is performing well in terms of polarimetric accuracy and precision.

Having a well-understood instrument is important when considering the HR 4796A observations, because the results are at odds with expectations drawn from previous studies. The side of the disk that is fainter in total intensity is ≥9 times brighter in polarized intensity. The relatively isotropic total intensity phase function suggests scattering by small particles in the Rayleigh regime, but this is strongly ruled out by our observations that show the polarized intensity does not peak at the ansae but instead at the western minor axis. We have not been able to identify any simple model that can reconcile these observations. Instead, we must consider more complex scenarios. Our favored model is that the disk is optically thick, and absorption or self-shadowing on the near side reduces its apparent brightness, making the intrinsically brighter forward scattering on the west masquerade as fainter back scattering. In this optically thick, geometrically thin scenario, only at the smallest scattering angles does the phase function’s strong forward scattering peak come to dominate over the self absorption. This effect is only hinted at in the present data, however.

Our follow-up study (M. P. Fitzgerald et al., in preparation) will present deeper multi-wavelength polarimetric data of the HR 4796A system that have a greater capacity to measure the total intensity of light around a larger range of angles, improving measurement of the dust scattering properties. The next steps in modeling the system will better constrain the geometry and consider a wider variety of potential scatterers. Additional imaging over a larger range of wavelengths with complementary instruments (e.g., SPHERE/ZIMPOL, MagAO) will also help test these models. HR 4796A has lately become somewhat of a poster child for new high contrast AO systems, and for improved reprocessing of archival data sets. This not only provides a fair test case for comparing instrument performances on spatially extended targets (akin to the diverse collection of images of HR 8799’s planetary system observed by essentially every AO-equipped large telescope), it also means that there will be an extraordinarily rich multiwavelength data set to interpret.

The data presented in this paper were obtained during the first two observing runs in which the polarimetry mode of GPI was used. Since then, polarimetry has been extensively exercised in the ongoing commissioning program, and also in the shared-risk early science observing run in April. Approximately half the observing programs during that run were polarimetry, studying not just circumstellar disks but also mass loss around massive post-main-sequence stars and accretion and outflow around FU Orionis stars. GPI will also provide a tool for spatially resolved polarimetry of solar system bodies such as asteroids and Saturn’s moon Titan. In late 2014 the GPI Exoplanet Survey key science program will commence a comprehensive survey of 600 nearby stars looking for Jovian exoplanets; a search for debris disks around a subset of these stars with known infrared excesses is a key part of the campaign.

The polarimetry mode of GPI is complementary to its planet-detection capabilities. Through imaging spectroscopy, GPI will detect and characterize the largest bodies in these planetary systems, which gravitationally dominate the dynamics of the regions outside a few AU. Conversely the polarimetry mode of GPI will provide sensitivity to the much smaller planetesimals and minor planets that populate debris disks and rings, and give rise to observable dust through collisional grinding. Correlations between the presence of planets and disks are increasingly seen; observations with GPI, SPHERE, and other high-contrast AO systems will probe these correlations in greater detail and test theories for planet-disk interactions. The proposed WFIRST/AFTA Coronagraph offers one path to extending these capabilities several more orders of magnitude in contrast, to approach the point of being able to detect solar-system-like dust levels with τ much less than that of the relatively massive and dusty HR 4796A ring. A polarimetric capability as part of the AFTA Coronagraph would be an unprecedented platform for studies of exozodiacal light arising from asteroid belts and comets around nearby stars, which would in turn inform on the astrophysical backgrounds for future terrestrial planet imaging missions. Together the sensitivity of these instruments to massive Jovian planets and ensembles of micron-sized dust particles will enable the characterization not just of individual planets, but of planetary systems overall.

M.D.P. and J.R.G. led the development of GPI’s polarimetry mode including design, implementation, and data analysis methods, and M.D.P. implemented the polarimetry reduction pipeline and led the first light observations with GPI polarimetry. G.D. led the analysis and interpretation of the HR 4796A scattering properties in collaboration with M.D.P., M.P.F., and others on the team. M.M.B. performed instrument calibrations, contributed substantially to reduction software, reduced data, and conducted the contrast and sky polarization analyses. M.P.F. performed the analysis of the ring geometry. S.J.W. analyzed instrumental polarization. P.K. and T.M. summarized previous observations of HR 4796A. B.M. provides overall scientific leadership to the GPI team. The remaining authors collaborated in the development and commissioning of GPI. R.D.R and J.P.
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APPENDIX A

POLARIMETRY HARDWARE DETAILS FOR GPI

Beam splitter. As noted in Section 2.2, the optimal design for a Wollaston prism for integral field polarimetry has the spots separated by 45° relative to the lenslet grid and interlaced like a chess board. The desired separation of the spots should be \( l / \sqrt{2} \) where \( l \) is the projected separation between lenslet centers, yielding for GPI a separation of 7.1 pixels = 126 \( \mu m \). Taking into account the 235 mm focal length of the IFS camera optics, a divergence angle of only 0.03° between polarizations is required. This is achieved using an \( \text{MgF}_2 \) Wollaston prism with a 1:4 prism angle. GPI’s lenslet array is rotated by 26.5° relative to the detector to avoid overlap of spectra in spectral mode, and therefore the polarization dispersion direction must be \(-18.5° \) or \(+71.5° \) relative to the detector. The Wollaston is therefore mounted at an angle of \(-18.5° \) on the prism exchange translation stage; this is worth emphasizing because it sets the native reference frame of GPI polarimetry which is neither aligned with the IFS lenslet array rows and columns, nor with the orientation of the AO dark hole, nor with any particular sky reference frame. That translation stage uses magnetic latches at opposite ends of its travel to ensure precise position repeatability for the spectral and Wollaston prisms. Figure 17 shows the prism and translation stage. See also Larkin et al. (2014) for further details on the GPI IFS and its mechanisms.

Modulator. An achromatic \( \text{MgF}_2 \) quartz wave plate was procured from Bernhard Halle with \( \lambda / 2 \pm 4\% \) retardance from 0.7–2.5 \( \mu m \). To achieve accurate polarimetry with GPI it is not required that the retardance of the waveplate be precisely 0.50 waves at all wavelengths, but rather that its retardance versus wavelength is accurately known. Details of the wavelength-dependent retardance may be found in Wiktorowicz et al. (2014). This waveplate was mounted in a custom rotation stage physically located in GPI’s calibration interferometer subsystem, in the collimated beam shortly before the IFS entrance window. See Figure 17, right panel. This rotation mechanism achieves angular position repeatability of 0.023 (3σ) in laboratory testing at room temperature. Temperature-dependent bias in the mechanism’s home position was tested to be \(<0.25° \) between \(-12.5°C \) and +25°C.

The wavefront error of the transmitted beam through the modulator is 47 nm peak-to-valley and 11 nm rms. For comparison the entire GPI optical path to the coronagraph focal plane was measured in the lab to achieve 13 nm rms, with individual optics \(<1 \) nm rms. The substantial wavefront error of the waveplate in this context supports our decision to place it after the coronagraph focal plane.

Bandpass filters. GPI contains five spectral bandpass filters, the details of which were motivated by the needs of exoplanet spectroscopy. Three filters correspond to the \( Y \), \( J \), and \( H \) bands, though the specific wavelength ranges do not correspond.

Figure 17. Assembled GPI hardware highlighting several key components of its polarimetry mode. Left: the IFS dewar showing the internal light path, in blue, and mechanisms. The prism slide is located inside the rectangular enclosure along with the filter wheel. The dispersed light is focused onto the Hawaii 2RG detector at lower right. Center: a view of the prism slide enclosure with the cover opened, showing the Wollaston prism mounted indicated on the right. The spectral prism has since been mounted in the other prism holder at left. Right: the waveplate insertion and rotation mechanism is the hexagonal structure shown here mounted into the calibration interferometer enclosure.
precisely to standard filter bandpasses such as the MKO filter sets. Because the spectral dispersion of the GPI IFS increase toward longer wavelengths, it was necessary to split the \( K \) band into two overlapping filters to avoid spectral overlap on the detector. Thus for polarimetry beyond 2 \( \mu m \) we have a choice between two custom filters, \( K1 \) from 1.9−2.19 \( \mu m \) and \( K2 \) from 2.12−2.38 \( \mu m \). Additional documentation on the spectral response of these filters are available on the instrument team’s Web site, and for the overall spectral response of GPI, see Maire et al. (2014).

APPENDIX B
DATA ANALYSIS METHODS FOR INTEGRAL FIELD POLARIMETRY

B.1. A Least-squares Approach to Sequence Combination

Astronomical polarimeters often adopt a data reduction method in which successive images are taken with polarization states modulated to swap e.g., the +\( Q \) and −\( Q \) polarizations between the two orthogonal polarization channels. A double-differencing image constructed from these will be relatively robust against both atmospheric speckles and instrumental polarization effects occurring after the modulator. That traditional double-differencing reduction will not suffice for GPI with its constantly rotating orientation with respect to the sky: it is not possible in general to choose a single set of waveplate rotation angles such that sums and differences of the input images would correspond to Stokes parameters in a fixed celestial frame. While specific waveplate rotation angles to achieve any desired modulation could be calculated as a function of time and telescope orientation for each target, that approach would introduce unnecessary complexity and timing dependency into GPI observations. Instead, the traditional double differencing method can be considered a special case of the more general approach in which the astronomical polarization signature is recovered by constructing the equations of condition for \( N \) measurements at arbitrary modulator positions \( \theta_1 \) to \( \theta_N \):

\[
\begin{pmatrix}
I_1' \\
Q_1' \\
U_1' \\
V_1'
\end{pmatrix} =
\begin{pmatrix}
m_{11}(\theta_1) & m_{12}(\theta_1) & m_{13}(\theta_1) & m_{14}(\theta_1) \\
m_{21}(\theta_2) & m_{22}(\theta_2) & m_{23}(\theta_2) & m_{24}(\theta_2) \\
m_{31}(\theta_N) & m_{32}(\theta_N) & m_{33}(\theta_N) & m_{34}(\theta_N)
\end{pmatrix}
\begin{pmatrix}
I_1 \\
Q_1 \\
U_1 \\
V_1
\end{pmatrix}
\]

\[
= M_{\text{meas}} \cdot S.
\]  

(B1)

If the matrix elements \( m_{ij}(\theta) \) are sufficiently well known, the input polarization vector may be solved for via the method of least squares. The double-differencing method simplifies this reduction to convenient addition and subtraction by enforcing a particular selection of the modulation angles \( \theta \), but the general approach holds even in cases where that simplification is not available.

Using the known instrumental response matrix, for every exposure in a sequence we write down the Stokes vector equation describing that measurement. We then solve this complete set of equations of condition to derive the astronomical polarization for each point in the field of view. We obtain the terms of the measurement matrix \( M_{\text{meas}} \) by modeling the instrument’s performance using the standard Mueller matrix approach. Each component in the system is described by some Mueller matrix, and the overall \( M_{\text{GPI}} \) is the product of these individual terms:

\[
M_{\text{GPI}}(\theta, \phi, \eta) = M_{\text{Woll}} M_{\text{IFS}} M_{\text{Rot}}(-\theta) M_{\text{Woll}}(\phi) M_{\text{Rot}}(\theta) M_{\text{AO}}
\times M_{\text{tertiary}} M_{\text{telescope}} M_{\text{SkyRot}}(\eta),
\]

where \( M_{\text{Woll}} \) describes the Wollaston prism (with two variants for the two output orthogonal polarizations + and −), \( M_{\text{Woll}}(\phi) \) represents a waveplate with retardance \( \phi \) at angle \( \theta \), and so on. The term \( M_{\text{SkyRot}}(\eta) \) accounts for sidereal rotation by the parallactic angle \( \eta \). All of the above may be implicitly a function of wavelength \( \lambda \). The instrumental polarization of the telescope is given by \( M_{\text{telescope}} \) for the primary and secondary, times \( M_{\text{tertiary}} \) for the contribution of the tertiary fold flat only if GPI is attached to a side port on the Gemini instrument support structure. Once each individual \( M \) is known, either by design or empirical measurement, the set of equations of condition may be derived for any given observation sequence.

The process of measurement (Equation (B1)) stated in compact matrix form is

\[
I' = M'S.
\]

The least-squares estimate of \( S \) corresponds to minimizing the norm

\[
||I' - M'S_{\text{est}}||^2,
\]

which can be found using the pseudo-inverse of the measurement matrix

\[
S_{\text{est}} = (M'^T M')^{-1} M'^T I'.
\]  

(B2)

To summarize the approach we have implemented as part of the GPI Data Reduction Pipeline: for each raw image, the two interlaced sets of polarized spots are extracted and assembled to produce a pair of images in orthogonal linear polarizations, as described in Section 3. An observing sequence yields many such pairs. These data are rotated and aligned to a common orientation, the equations of condition are computed, and the resulting set of linear equations is then solved using singular value decomposition via IDL’s \texttt{svdc} and \texttt{svsol} routines (Often \( M'^T M' \) is ill-conditioned and the use of the pseudo-inverse in Equation (B2) should be thought of as schematic only.) Because the field of view projected onto the sky changes with the parallactic angle, causing not all images in a sequence to contribute to all pixels in the final mosaic, this procedure must be repeated separately for each lenslet position. Still, the entire computation can be performed in only a few seconds on modern computers. The result is a 3D Stokes datacube \([x, y, (I, Q, U, V)]\) derived from the entire observation sequence.

B.2. A Variant on Double Differencing for ADI Polarimetry

One of the strengths of differential polarimetry as an observational technique is the ability to modulate the signal. Such modulation is not generally possible with other differential techniques; for instance one cannot simply modulate wavelengths in an integral field spectrograph. By swapping a polarized signal between different measurement channels, non-common-path biases between the two channels can be mitigated.

Let us denote the two orthogonally polarized channels in a given exposure as \( I^+ \) and \( I^- \). The traditional double differencing approach to measure a polarized signal \( Q \) would be to calculate difference images \( d_i \) as follows, assuming a modulation that swaps \( Q \) between the two channels:

\[
d_i = I^+_i - I^-_i = +Q + \epsilon
\]  

(B3)
\[ d_2 = I_2^* - I_2^- = -Q + \epsilon. \]  

(B4)

Note that the differences are contaminated by some systematic bias \( \epsilon \) between the two channels. By forming the double difference, we can recover the value of \( Q \) while cancelling that bias:

\[ d_1 - d_2 = (+Q + \epsilon) - (-Q + \epsilon) = 2Q. \]  

(B5)

But as previously noted, for GPI the continuous parallactic angle rotation for ADI means we cannot in general choose waveplate angles to swap polarizations. Because we only split the polarizations after the lenslet array, many forms of non-common-path error are minimized, but there can still be systematic biases between the two channels. In particular for GPI the dominant impact is from detector artifacts (bad pixels and assembly artifacts that do not change on short timescales, the non-common-path error are minimized, but there can still be systematic biases between the two channels, and can itself be biased depending on the angle rotation for ADI means we cannot in general choose to get a debiased difference, \( d'_i \). After doing so, we recombine the debiased differences with the sums \( s_i \) to create debiased versions of the measured orthogonal polarizations \( I' \):

\[ d'_i = d_i - \Delta \]

\[ I'_i = (s_i + d'_i)/2 \]

\[ I''_i = (s_i - d'_i)/2. \]

We then calculate the median of all the differences, \( \Delta = \text{median}(d_i) \). This is our estimate of the systematic bias \( \epsilon \) between channels, so we subtract it from each of the original differences to get a debiased difference, \( d'_i \). After doing so, we recombine the debiased differences with the sums \( s_i \) to create debiased versions of the measured orthogonal polarizations \( I' \):

\[ d'_i = d_i - \Delta \]

\[ I'_i = (s_i + d'_i)/2 \]

\[ I''_i = (s_i - d'_i)/2. \]

These debiased orthogonal polarized intensities \( I' \) are then used in place of the original measured polarized intensities when solving Equation (B2). Admittedly the median difference image, \( \Delta \) is an imperfect estimator for the systematic offset between channels, and can itself be biased depending on the presence of polarized signals in the individual difference images, so the cancellation will not be perfect. However, given that we are mostly concerned with detector calibration and cube assembly artifacts that do not change on short timescales, the median computed over many images is relatively robust. It is still worth pursuing improvements in calibration and algorithms to minimize the systematic biases between channels at their source, but empirically applying this correction is an efficient way to improve image quality and contrast in ADI polarimetry.

### B.3. Noise Propagation in GPI Stokes Datacubes

An estimate of the noise in a pixel of a final Stokes cube can be found by propagating errors through Equation (B2) using standard statistical techniques. If the covariance matrix of the measured intensities \( I' \) is \( C_{I'} \), then the covariance of the estimate of the Stokes parameters \( S_{\text{est}} \) is

\[ C_{S_{\text{est}}} = M^* C_{I'} (M^*)^T, \]  

(B8)

where \( M^* = (M'^T M')^{-1} M'^T \) is the pseudo-inverse of the measurement matrix. If the noise estimate in each element of \( I' \) is identical (as is the case when considering read-out noise or Poisson noise for an unpolarized source) then the covariance matrix \( C_{I'} \) becomes a diagonal matrix with identical entries. The Stokes covariance matrix can then be expressed as:

\[ C_{S_{\text{est}}} = \sigma^2 I (M^*)^T, \]  

(B9)

where \( \sigma \) is an estimate of the noise in a single pixel of a polarimetry data cube.

The read-out noise per spaxel can be calculated as \( \sigma_{\text{Ron}} = \sigma_{\text{Det}} \sqrt{r_{\text{pix}}}/n_{\text{coadds}} \), where \( \sigma_{\text{Det}} \) is the read-out noise for a single detector pixel and \( r_{\text{pix}} \) is the number of pixels used in the calculation of the spaxel flux. At a given annulus, the Poisson noise variance in a polarization data cube pixel can be estimated to be half of the mean intensity of a Stokes \( I' \) cube in that annulus.

If \( Q \) and \( U \) are assumed to be independent normally distributed quantities with means \( \mu \cos \theta \) and \( \mu \sin \theta \) and identical standard deviations \( \sigma \), then the polarized intensity, \( P \), can be described by a Rician distribution, \( R(\mu, \sigma) \). For a discussion on more sophisticated estimators of the linear polarized intensity, \( \mu \), and polarization angle, \( \theta \), and their confidence intervals in particular at low S/N levels, see Quinn (2012) and Plaszczynski et al. (2014), and references therein.

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