Self-dual and Anti Self-dual Solutions of Discrete Yang-Mills Equations on a Double Complex

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Abstract. We study a discrete model of the SU(2) Yang-Mills equations on a combinatorial analog of \( \mathbb{R}^4 \). Self-dual and anti-self-dual solutions of discrete Yang-Mills equations are constructed. To obtain these solutions we use both techniques of a double complex and the quaternionic approach. Interesting analogies between instanton, anti-instanton solutions of discrete and continual self-dual, anti-self-dual equations are also discussed.

1. Introduction

It is well known that the self-dual and anti-self-dual connections are the absolute minima of the Lagrangian for a 4-dimensional non-abelian gauge theory. The first self-dual solution - the one instanton - to the SU(2) Yang-Mills equations on \( \mathbb{R}^4 \) was obtained by Belavin et al [3]. Later other more general multi-instanton solutions were described in [3,11]. Since then numerous extensions have been made. Classical references are the books by Atiyah [1], Freed and Uhlenbeck [8].

In this paper we study a discrete analog of the SU(2) Yang-Mills equations on a combinatorial analog of \( \mathbb{R}^4 \). The ideas presented here are strongly influenced by book of Dezin [6]. We develop discrete models of some objects in differential geometry, including the Hodge star operator, the differential and the covariant exterior differential operator, in such a way that they preserve the geometric structure of their continual analogs. We continue the investigations which were originated in [7, 19, 20, 21]. The purpose of this paper is to construct the self-dual and anti-self-dual solutions of discrete SU(2) Yang-Mills equations which imitate the corresponding solutions of continual theory. The geometrical discretisation techniques used here extend those introduced in [6] and [19]. A combinatorial model of \( \mathbb{R}^4 \) based on the use of the double complex construction is taken from [21].

There are many other approaches to the discretisation of Yang-Mills theories. Numerous papers have been written on this subject. See, for example, [2, 4, 9, 10, 12, 13, 15, 18, 16] and the references therein. Most of them are based on the lattice discretisation scheme. However, in the case of the lattice formulation there are difficulties in keeping geometrical properties of an origin gauge theory. An alternative geometrical discretisation scheme of a field theory can be found in [17].

The paper is organized as follows. In Section 2 we review some basic facts of the SU(2) Yang-Mills theory on \( \mathbb{R}^4 \). We begin by recalling the connection between the Lie group SU(2) and the space of quaternions. Finally, we write down the basic
instanton and anti-instanton solutions in quaternionic form. The notations here are compiled from [1] and [14].

Section 3 contains a brief summary of definitions and properties due to the double complex construction. We repeat here the relevant material from [21]. This article is also the main reference for this section. In particular, we introduce discrete matrix-valued forms (analog of differential forms) and define analogs of the main continual operations on them.

In Section 4 using the quaternionic approach we present the discrete Yang-Mills equations. We write out components of the discrete curvature 2-form in quaternionic form. The discrete self-dual and anti-self-dual equations are described. We try to be as close to continual $SU(2)$ Yang-Mills theory as possible. Hence we discuss conditions when the discrete curvature will be $su(2)$-valued.

Finally, Section 5 is devoted to self-dual and anti-self-dual solutions of the discrete Yang-Mills equations. We construct these solutions as discrete quaternionic 1-forms and discuss some analogies with continual instanton and anti-instanton solutions.

2. Quaternions and $SU(2)$-connection

In this section we briefly recall some well known settings of the smooth Yang-Mills theory in Euclidean 4-dimensional space (see, for example, [14]).

We begin with a brief review of some preliminaries about quaternions. The quaternions are formed from real numbers by adjoining three symbols $i, j, k$ and an arbitrary quaternion $x$ can be written as

$$ x = x_1 + x_2 i + x_3 j + x_4 k, $$

where $x_1, x_2, x_3, x_4 \in \mathbb{R}$. The symbols $i, j, k$ satisfy the following identities

$$ i^2 = j^2 = k^2 = -1, $$

$$ ij = -ji = k, \quad jk = -kj = i, \quad ki = -ik = j. $$

It is clear that the space of quaternions is isomorphic to $\mathbb{R}^4$. By analogy with the complex numbers $x_1$ is called the real part of $x$ and $x_2 i + x_3 j + x_4 k$ is called the imaginary part. In further we will write

$$ \text{Im} \, x = x_2 i + x_3 j + x_4 k. $$

The conjugate quaternion of $x$ is defined by

$$ \bar{x} = x_1 - x_2 i - x_3 j - x_4 k. $$

Then the norm $|x|$ of a quaternion can be introduced as follows

$$ |x|^2 = x \bar{x} = x_1^2 + x_2^2 + x_3^2 + x_4^2. $$

If $x \neq 0$, then it has a unique inverse $x^{-1}$ given by

$$ x^{-1} = \bar{x}/|x|^2. $$

The algebra of quaternions can be represented as a sub-algebra of the $2 \times 2$ complex matrices $M(2, \mathbb{C})$. We identify the quaternion $x$ with a matrix $f(x) \in M(2, \mathbb{C})$ by setting

$$ f(x) = \left( \begin{array}{cc} x_1 + x_2 i & x_3 + x_4 i \\ -x_3 + x_4 i & x_1 - x_2 i \end{array} \right). $$

Here $i$ is the imaginary unit.
It is well known that the unit quaternions, i.e., they have norm $|x| = 1$, form a group and this group is isomorphic to $SU(2)$. The following $2 \times 2$ complex matrices

\[(2.6) \quad i = \begin{pmatrix} i & 0 \\ 0 & -i \end{pmatrix}, \quad j = \begin{pmatrix} 0 & 1 \\ -1 & 0 \end{pmatrix}, \quad k = \begin{pmatrix} 0 & i \\ i & 0 \end{pmatrix}\]

realize a representation of the Lie algebra $su(2)$ of the group $SU(2)$. Note that multiplying by $-i$ these three matrices we obtain the standard Pauli matrices. Matrices (2.6) correspond to the units $i, j, k$ given by (2.2). Thus the Lie algebra $su(2)$ can be viewed as the pure imaginary quaternions with basis $i, j, k$.

Let now $A$ be an $SU(2)$-connection. This means that $A$ is an $su(2)$-valued 1-form and we can write

\[(2.7) \quad A = \sum_{\mu} A_\mu(x) dx^\mu,\]

where $A_\mu(x) \in su(2)$ and $x = (x_1, ..., x_4)$ is a point of $\mathbb{R}^4$. The connection $A$ is also called a gauge potential. Define a gauge transformation by a function $g(x)$ taking value in $SU(2)$. Then the gauge potential $A$ must transform like

\[(2.8) \quad A \to g^{-1} A g + g^{-1} d g.\]

Let us define the curvature 2-form $F$ by

\[(2.9) \quad F = dA + A \wedge A,\]

where $\wedge$ denotes the exterior multiplication.

Consider also the covariant exterior differential operator $d_A$ given by

\[(2.10) \quad d_A \Omega = d\Omega + A \wedge \Omega + (-1)^{p+1} \Omega \wedge A,\]

where $\Omega$ is a $su(2)$-valued $p$-form.

The Yang-Mills action $S$ can be expressed in terms of the 2-forms $F$ and $*F$ as

\[(2.11) \quad S = -tr \int_{\mathbb{R}^4} F \wedge *F,\]

where $*$ is the Hodge star operator. In $\mathbb{R}^4$ the operator $*^2$ is either an involution or anti-involution, i.e., $*^2 = \pm 1$. The Yang-Mills Lagrangian $L = -tr(F \wedge *F)$ is invariant under the gauge transformation (2.8). By the physical requirement it is clear that the action $S$ should be finite. Hence the curvature $F$ should be square integrable. This means that $F \to 0$ as $|x| \to \infty$. Consequently, we must describe the boundary condition at infinity for the connection $A$. By virtue of gauge freedom (2.8) we have

\[(2.12) \quad A \sim g^{-1} d g \quad \text{as} \quad |x| \to \infty,\]

where $\sim$ implies asymptotic behaviour. Here and subsequently we do not specify the rate of decay.

Written in terms of the covariant exterior differential operator $d_A$ the Euler-Lagrange equations for the extrema of (2.11) have the form

\[(2.13) \quad d_A F = 0, \quad d_A * F = 0.\]

These equations are the Yang-Mills equations. The first equation of (2.13) is known also as the Bianchi identity. In 4-dimensional Yang-Mills theories the following equations

\[(2.14) \quad F = *F, \quad F = - * F\]
are called self-dual and anti-self-dual respectively. These equations are first-order
non-linear equations for the potential $A$ which imply the second-order Yang-Mills
equations (2.13). Solutions of (2.14) – the self-dual and anti-self-dual connections –
are called also instantons and anti-instantons [8]. It is known that the self-dual
and anti-self-dual connections are the absolute minima of the action $S$.

The connection 1-form $A$ can be defined also as taking values in the space of pure
imaginary quaternions. To express $A$ in quaternion form we consider the quaternion
differential $dx = dx_1 + dx_2i + dx_3j + dx_4k$
and the conjugate quaternion of $dx$
$d\bar{x} = dx_1 - dx_2i - dx_3j - dx_4k$.

Let $f(x)$ be a function of the quaternion variable $x$ with quaternion values. Then
we can write $A$ as

\[ A = \Im(f(x)dx), \]

where

\[ f(x) = f_1(x) + f_2(x)i + f_3(x)j + f_4(x)k. \]

Using the rules of multiplication (2.2) we have

\begin{align*}
A_1(x) &= f_2(x)i + f_3(x)j + f_4(x)k, \\
A_2(x) &= f_1(x)i + f_4(x)j - f_3(x)k, \\
A_3(x) &= -f_4(x)i + f_1(x)j + f_2(x)k, \\
A_4(x) &= f_3(x)i - f_2(x)j + f_1(x)k.
\end{align*}

Using (2.15) we can rewrite (2.9) as follows

\[ F = \Im(df(x) \wedge dx + f(x)dx \wedge f(x)dx). \]

Note that calculation of the imaginary part of $f(x)dx$ and computing its curvature
commute.

Let us take the following expression for $f(x)$:

\[ f(x) = \frac{\bar{x}dx}{1 + |x|^2}. \]

Then the connection 1-form $A$ is defined by

\[ A = \Im\left\{ \frac{\bar{x}dx}{1 + |x|^2} \right\}. \]

The explicit components $A_\mu$ can be written as

\begin{align*}
A_1(x) &= -\frac{x_2i - x_3j - x_4k}{1 + |x|^2}, & A_2(x) &= \frac{x_1i - x_4j + x_3k}{1 + |x|^2}, \\
A_3(x) &= \frac{x_4i + x_1j - x_2k}{1 + |x|^2}, & A_4(x) &= \frac{-x_3i + x_2j + x_1k}{1 + |x|^2}.
\end{align*}

Putting (2.17) in (2.10) we get the pure imaginary expression

\[ F = \frac{d\bar{x} \wedge dx}{(1 + |x|^2)^2}. \]

It is easy to show that the 2-form $d\bar{x} \wedge dx$ is anti-self-dual. Hence $F$ is anti-self-dual
too and the connection (2.18) describes an anti-instanton. See for details [1].
Similarly, if we take

\begin{equation}
A = \text{Im} \left\{ \frac{x \bar{dx}}{1 + |x|^2} \right\},
\end{equation}

then we obtain the self-dual 2-form

\begin{equation}
F = \frac{dx \wedge d\bar{x}}{(1 + |x|^2)^2}.
\end{equation}

Thus the curvature is self-dual and (2.21) describes an instanton .

3. Double complex

We will need the double complex construction described in [21]. In with section for the convenience of the reader we repeat the relevant material from [21] without proofs, thus making our presentation self-contained.

Let the tensor product $C(4) = \mathbb{C} \otimes \mathbb{C} \otimes \mathbb{C} \otimes \mathbb{C}$ of an 1-dimensional complex $C$ be a combinatorial model of Euclidean space $\mathbb{R}^4$ (see for details also [3]). The 1-dimensional complex $C$ is defined in the following way. Let $C^0$ denotes the real linear space of 0-dimensional chains generated by basis elements $x_j$ (points), $j \in \mathbb{Z}$. It is convenient to introduce the shift operators $\tau, \sigma$ in the set of indices by

\begin{equation}
\tau j = j + 1, \quad \sigma j = j - 1.
\end{equation}

We denote the open interval $(x_j, x_{j+1})$ by $e_j$. We'll regards the set \{e_j\} as a set of basis elements of the real linear space $C^1$ of 1-dimensional chains. Then the 1-dimensional complex (combinatorial real line) is the direct sum of the introduced spaces $C = C^0 \oplus C^1$. The boundary operator $\partial$ on the basis elements of $C$ is given by

\begin{equation}
\partial x_j = 0, \quad \partial e_j = x_{\tau j} - x_j.
\end{equation}

The definition is extended to arbitrary chains by linearity.

Multiplying the basis elements $x_j, e_j$ in various ways we obtain basis elements of $C(4)$. Let $s_k^{(p)}$, where $k = (k_1, k_2, k_3, k_4)$ and $k_i \in \mathbb{Z}$, be an arbitrary basis element of $C(4)$. Then a $p$-dimensional chain is given by

\begin{equation}
c_p = \sum_k \sum_{p} c_k^{(p)} s_k^{(p)}, \quad c_k^{(p)} \in \mathbb{R}.
\end{equation}

We suppose that the superscript \((p)\) contains the whole requisite information about the quantity and places of 1-dimensional elements $e_j$ in $s_k^{(p)}$. For example, the 1-dimensional basis elements $c_k^{1}$ of $C(4)$ can be written as

\begin{equation}
c_k^{1} = x_{k_1} \otimes x_{k_2} \otimes x_{k_3} \otimes x_{k_4}, \quad c_k^{2} = x_{k_1} \otimes x_{k_2} \otimes x_{k_3} \otimes x_{k_4}, \quad c_k^{3} = x_{k_1} \otimes x_{k_2} \otimes x_{k_3} \otimes x_{k_4}, \quad c_k^{4} = x_{k_1} \otimes x_{k_2} \otimes x_{k_3} \otimes x_{k_4},
\end{equation}

and for the 2-dimensional basis elements $c_k^{ij}$ we have

\begin{align}
c_k^{12} &= x_{k_1} \otimes x_{k_2} \otimes x_{k_3} \otimes e_{k_4}, & c_k^{23} &= x_{k_1} \otimes x_{k_2} \otimes e_{k_3} \otimes x_{k_4}, \\
c_k^{13} &= x_{k_1} \otimes x_{k_2} \otimes e_{k_3} \otimes x_{k_4}, & c_k^{24} &= x_{k_1} \otimes e_{k_2} \otimes x_{k_3} \otimes e_{k_4}, \\
c_k^{14} &= e_{k_1} \otimes x_{k_2} \otimes x_{k_3} \otimes e_{k_4}, & c_k^{34} &= e_{k_1} \otimes x_{k_2} \otimes x_{k_3} \otimes e_{k_4}.
\end{align}
Using (3.2) we define the boundary operator $\partial$ on chains of $C(4)$ in the following way: if $c_p$, $c_q$ are chains of the indicated dimension, belonging to the complexes being multiplied, then

$$
\partial(c_p \otimes c_q) = \partial c_p \otimes c_q + (-1)^pc_p \otimes \partial c_q.
$$

For example, for the basis element $\varepsilon_k^{24}$ we have

$$
\partial \varepsilon_k^{24} = \partial(x_k^1 \otimes e_k^2) \otimes x_k^3 \otimes e_k^4 - x_k^1 \otimes e_k^2 \otimes \partial(x_k^3 \otimes e_k^4)
$$

$$
= \partial x_k^1 \otimes e_k^2 \otimes x_k^3 \otimes e_k^4 + x_k^1 \otimes \partial e_k^2 \otimes x_k^3 \otimes e_k^4
$$

$$
- x_k^1 \otimes e_k^2 \otimes \partial x_k^3 \otimes e_k^4 - x_k^1 \otimes e_k^2 \otimes x_k^3 \otimes \partial e_k^4
$$

$$
= x_k^1 \otimes x_{\tau k^2} \otimes x_k^3 \otimes e_k^4 - x_k^1 \otimes x_k^2 \otimes x_k^3 \otimes e_k^4
$$

$$
- x_k^1 \otimes x_k^2 \otimes x_k^3 \otimes x_{\tau k^4} + x_k^1 \otimes x_k^2 \otimes x_k^3 \otimes x_k^4.
$$

For convenience we also introduce the shift operators $\tau_i$ and $\sigma_i$ which act in the set of indices $k = (k_1, k_2, k_3, k_4)$, $k_i \in \mathbb{Z}$, as

$$
\tau_i k = (k_1, \ldots, \tau_{k_i}, \ldots, k_4), \quad \sigma_i k = (k_1, \ldots, \sigma_{k_i}, \ldots, k_4),
$$

where $\tau$ and $\sigma$ are given by (3.3).

Let us introduce the construction of a double complex. Together with the complex $C(4)$ we consider its double, namely the complex $\tilde{C}(4)$ of exactly the same structure. Define the one-to-one correspondence

$$
* : C(4) \rightarrow \tilde{C}(4), \quad * : \tilde{C}(4) \rightarrow C(4)
$$

in the following way. Let $s_k^{(p)}$ be an arbitrary $p$-dimensional basis element of $C(4)$, i.e., the product $s_k^{(p)} = s_{k_1} \otimes s_{k_2} \otimes s_{k_3} \otimes s_{k_4}$ contains exactly $p$ of 1-dimensional elements $e_{k_i}$ and $4 - p$ of 0-dimensional elements $x_{k_i}$, $p = 0, 1, 2, 3, 4$, $k_i \in \mathbb{Z}$. Then

$$
* : s_k^{(p)} \rightarrow \pm s_k^{(4-p)}, \quad * : s_k^{(4-p)} \rightarrow \pm s_k^{(p)},
$$

where

$$
s_k^{(4-p)} = \ast s_{k_1} \otimes \ast s_{k_2} \otimes \ast s_{k_3} \otimes \ast s_{k_4}
$$

and $\ast s_{k_i} = \tilde{e}_{k_i}$ if $s_{k_i} = x_{k_i}$ and $\ast s_{k_i} = \tilde{x}_{k_i}$ if $s_{k_i} = e_{k_i}$. In the first of mapping (3.4) we take “+” if the permutation $((p), (4 - p))$ of $(1, 2, 3, 4)$ is even and “−” if the permutation $((p), (4 - p))$ is odd. Recall that in symbol $(p)$ the number of basis element is contained. For example, for the 2-dimensional basis element $\varepsilon_k^{13} = e_k^1 \otimes x_k^2 \otimes x_k^3 \otimes e_k^4$ we have $\ast \varepsilon_k^{13} = -\varepsilon_k^{24}$ since the permutation $(1, 2, 3, 4)$ is odd. The mapping $* : s_k^{(4-p)} \rightarrow \pm s_k^{(p)}$ is defined by analogy.

**Proposition 3.1.** Let $c_r \in C(4)$ be an $r$-dimensional chain (3.3). Then we have

$$
* c_r = (-1)^{r(4-r)} c_r.
$$

**Proof.** See [21].

Now we consider a dual object of the complex $C(4)$. Let $K(4)$ be a cochain complex with $gl(2, \mathbb{C})$-valued coefficients, where $gl(2, \mathbb{C})$ is the Lie algebra of the group $GL(2, \mathbb{C})$. Recall that $gl(2, \mathbb{C})$ consists of all complex $2 \times 2$ matrices $M(2, \mathbb{C})$ with bracket operation $[\cdot, \cdot]$. We suppose that the complex $K(4)$, which is a conjugate of $C(4)$, has a similar structure: $K(4) = K \otimes K \otimes K \otimes K$, where $K$ is a conjugate of the 1-dimensional complex $C$. Basis elements of $K$ can be written as $x^j$, $e^j$. Then an arbitrary basis element of $K(4)$ is given by $s_k^{(p)} = s_{k_1}^{p_1} \otimes s_{k_2}^{p_2} \otimes s_{k_3}^{p_3} \otimes s_{k_4}^{p_4}$, where
$s^{k_i}$ is either $x^{k_i}$ or $e^{k_i}$. For example, we denote the 1-, 2-dimensional basis elements of $K(4)$ by $e_i^k$, $\varepsilon_i^k$ respectively, cf. (3.4), (3.5). For a $p$-dimensional cochain $\varphi \in K(4)$ we have

$$\varphi = \sum_k \sum_p \varphi^{(p)}_k s^{(p)}_k,$$

where $\varphi^{(p)}_k \in \text{gl}(2, \mathbb{C})$. We will call cochains forms, emphasizing their relationship with the corresponding continual objects, differential forms.

We define the pairing operation $< \cdot , \cdot >$ for arbitrary basis elements $\varepsilon_k \in C(4)$, $s^k \in K(4)$ by the rule

$$< \varepsilon_k , as^k > = \begin{cases} 0, \varepsilon_k \neq s_k \\ a, \varepsilon_k = s_k, a \in \text{gl}(2, \mathbb{C}). \end{cases}$$

Here for simplicity the superscript $(p)$ is omitted. The operation (3.12) is linearly extended to cochains.

The operation $\partial$ (3.6) induces the dual operation $d^c$ on $K(4)$ in the following way:

$$< \partial \varepsilon_k , as^k > = < \varepsilon_k , a d^c s^k > .$$

For example, if $\varphi = \sum_k \varphi_k x^k$, where $x^k = x^{k_1} \otimes x^{k_2} \otimes x^{k_3} \otimes x^{k_4}$, is a 0-form, then

$$d^c \varphi = \sum_k \sum_{i=1}^4 (\Delta_i \varphi_k) \varepsilon_i^k,$$

where $\Delta_i \varphi_k = \varphi_{r,k} - \varphi_k$ and $e^k_1$ is the 1-dimensional basis elements of $K(4)$. The coboundary operator $d^c$ is an analog of the exterior differentiation operator.

Now we describe a cochain product on the forms of $K(4)$. See [6] for details. We denote this product by $\cup$. In terms of the homology theory this is the so-called Whitney product. First we introduce the $\cup$-product on the chains of the 1-dimensional complex $K$. For the basis elements of $K$ the $\cup$-product is defined as follows

$$x^j \cup x^i = x^j, \quad e^j \cup x^i = e^j, \quad x^j \cup e^i = e^j, \quad j \in \mathbb{Z},$$

supposing the product to be zero in all other case. To arbitrary forms the $\cup$-product be extended linearly. Let us introduce an $r$-dimensional complex $K(r)$, $r = 1, 2, 3$, in an obvious notation. Let $s^{k(p)}_i$ be an arbitrary $p$-dimensional basis element of $K(r)$. It is convenient to write the basis element of $K(r+1)$ in the form $s^{k(p)}_i \otimes s^j$, where $s^{k(p)}_i$ is a basis element of $K(r)$ and $s^j$ is either $e^j$ or $x^j$, $j \in \mathbb{Z}$. Then, supposing that the $\cup$-product in $K(r)$ has been defined, we introduce it for basis elements of $K(r+1)$ by the rule

$$Q(j,q)(s^{k(p)}_i \cup s^{k(q)}_j) \otimes (s^j \cup s^p),$$

where the signum function $Q(j,q)$ is equal to $-1$ if the dimension of both elements $s^j$, $s^{k(q)}_j$ is odd and to $+1$ otherwise. The extension of the $\cup$-product to arbitrary forms of $K(r+1)$ is linear. Note that the coefficients of forms multiply as matrices.

**Proposition 3.2.** Let $\varphi$ and $\psi$ be arbitrary forms of $K(4)$. Then

$$d^c (\varphi \cup \psi) = d^c \varphi \cup (-1)^p \varphi \cup d^c \psi,$$

where $p$ is the dimension of a form $\varphi$. 


The proof of Proposition 3.2 is totally analogous to one in [6, p. 147] for the case of discrete forms with real coefficients.

The complex of the cochains $\tilde{K}(4)$ over the double complex $\tilde{C}(4)$ with the operator $d^c$ defined in it by (3.13) has the same structure as $K(4)$. The operation (3.8) induces the respective mapping

$$*: K(4) \to \tilde{K}(4), \quad *: \tilde{K}(4) \to K(4)$$

by the rule:

$$<\tilde{c}, *\varphi> = <\varphi, \tilde{c}>, \quad <c, *\tilde{\psi}> = <\tilde{\psi}, c>,$$

where $c \in C(4)$, $\tilde{c} \in \tilde{C}(4)$, $\varphi \in K(4)$, $\tilde{\psi} \in \tilde{K}(4)$. Hence for the basic elements of $K(4)$ or $\tilde{K}(4)$ we have relations (3.9). It is obviously that Proposition 3.1 is true for any $r$-dimensional cochain $c^r \in K(4)$. So we have

$$* \varphi = (-1)^{r(4-r)} \varphi$$

for any discrete $r$-form $\varphi$ on $K(4)$ and note that the same relation holds for the Hodge star operator. Thus this operator is a combinatorial analog of the Hodge star operator.

Let us introduce the following operation

$$\tilde{i}: K(4) \to \tilde{K}(4), \quad \tilde{i}: \tilde{K}(4) \to K(4)$$

by setting

$$\tilde{i}s^k_{(p)} = s^k_{(p)}, \quad \tilde{i}s^k_{(p)} = s^k_{(p)},$$

where $s^k_{(p)}$ and $\tilde{s}^k_{(p)}$ are basis elements of $K(4)$ and $\tilde{K}(4)$. Hence for a $p$-form $\varphi \in K(4)$ we have $\tilde{i}\varphi = \tilde{\varphi}$. Recall that the coefficients of $\tilde{\varphi} \in \tilde{K}(4)$ and $\varphi \in K(4)$ are the same.

**Proposition 3.3.** The following hold

$$\tilde{i}^2 = Id, \quad \tilde{i} * = * \tilde{i}, \quad \tilde{i}d^c = d^c \tilde{i},$$

$$\tilde{i}(\varphi \cup \psi) = \tilde{i}\varphi \cup \tilde{i}\psi,$$

where $\varphi, \psi \in K(4)$.

**Proposition 3.4.** Let $h$ be a discrete 0-form. Then for an arbitrary $p$-form $\varphi \in K(4)$ we have

$$\tilde{i} * (h \cup \varphi) = h \cup \tilde{i} * \varphi.$$

**Proof.** See [21].

Note that the definition of inner product in the double complex and a discrete analog of the Yang-Mills actions (2.11) can be found in [21].

### 4. Quaternions and discrete forms

Let us consider a discrete 0-form with coefficients belonging to $M(2, \mathbb{C})$. We put

$$f = \sum_k f_k x^k,$$
where \( x^k = x^{k_1} \otimes x^{k_2} \otimes x^{k_3} \otimes x^{k_4} \) is the 0-dimensional basis element of \( K(4) \), \( k = (k_1, k_2, k_3, k_4) \), \( k_i \in \mathbb{Z} \). Suppose that the matrices \( f_k \in M(2, \mathbb{C}) \) look like (2.5), i.e.

\[
(4.2) \quad f_k = \begin{pmatrix} f^1_k + f^3_k i & f^3_k + f^1_k i \\ -f^3_k + f^1_k i & f^1_k - f^3_k i \end{pmatrix},
\]

where \( f^s_k \in \mathbb{R} \), \( s = 1, 2, 3, 4 \). Then \( f_k \) in quaternionic form can be expressed as

\[
(4.3) \quad f_k = f^1_k i + f^2_k j + f^3_k k.
\]

Hence the form (4.1) can be considered as a discrete form with quaternionic coefficients. We will call it simply the quaternionic form when no confusion can arise.

Let \( f \) be a discrete 0-form and \( f \neq 0 \). Then we have

\[
(4.4) \quad f \cup f^{-1} = \sum_k f_k f_k^{-1} x^k = \sum_k x^k.
\]

**Proposition 4.1.** Let \( f \) be a discrete 0-form and \( f \neq 0 \). Then we have

\[
(4.5) \quad d^c f \cup f^{-1} = -f \cup d^c f^{-1}.
\]

**Proof.** By definition (3.14) and according to (4.4), we have

\[
(4.6) \quad d \cup f \cup f^{-1} = 0.
\]

Using (4.3) and (4.4) we write \( d^c(f \cup f^{-1}) = 0. \) Using Proposition 3.2 we immediately obtain (4.5). \( \qed \)

Let us denote by \( e \) the following quaternionic 1-form

\[
(4.6) \quad e = \sum_k e^k = \sum_k (e^1_k i + e^2_k j + e^3_k k),
\]

where \( e^s_k \) is the 1-dimensional basis elements of \( K(4) \). Let \( A \in K(4) \) be a discrete 1-form. We define the discrete \( SU(2) \)-connection \( A \) to be

\[
(4.7) \quad A = \sum_k \sum_{i=1}^4 A^i_k e^k,
\]

where \( A^i_k \in su(2) \) and \( k = (k_1, k_2, k_3, k_4) \), \( k_i \in \mathbb{Z} \). Using (4.3) and (4.6) we write (4.7) in quaternionic form as

\[
(4.8) \quad A = \text{Im}(f \cup e) = \text{Im} \left( \sum_k f_k e^k \right).
\]

Then the \( A^i_k \) are given by

\[
(4.9) \quad A^1_k = f^2_k i + f^3_k j + f^4_k k, \quad A^2_k = f^1_k i + f^3_k j - f^2_k k, \quad A^3_k = -f^3_k i + f^1_k j + f^2_k k, \quad A^4_k = f^2_k i - f^1_k j + f^3_k k.
\]

Define the quaternionic 0-form \( x \) by

\[
(4.10) \quad x = \sum_k \kappa x^k, \quad \kappa = k_1 + k_2 i + k_3 j + k_4 k,
\]

where \( k_i \in \mathbb{Z} \). It is easy to check that

\[
(4.11) \quad d^c x = e.
\]

Therefore we can rewrite (4.8) as

\[
(4.12) \quad A = \text{Im}(f \cup d^c x).
\]
Let \( g \) be a quaternionic 0-form (4.1) with the components of unit norm, i.e., \( |g_k| = 1 \) for any \( k \). It means that the corresponding discrete form is \( SU(2) \)-valued. We now define a gauge transformation for the discrete potential \( A \) which is analogous to (2.8). This is

\[
(A \rightarrow g^{-1} \cup A \cup g + g^{-1} \cup d c g,)
\]

where \( A \) is given by (4.8) or (4.12). Note that the gauge transformed discrete form \( A \) is \( su(2) \)-valued too. It is not so obviously as in the continual case but follows immediately from the definition of \( \cup \)-multiplication and formula (3.16). More generally, if we assume that the gauge transformation \( g \) is an arbitrary quaternionic 0-form, then we take the imaginary part of \( g^{-1} \cup A \cup g + g^{-1} \cup d c g \) in (4.13). For a deeper discussion of gauge invariant discrete models of the Yang-Mills theory we refer the reader to [19, 21].

An arbitrary discrete 2-form \( F \in K(4) \) can be written as follows

\[
F = \sum_k \sum_{i<j} F_{ij}^k \epsilon_{ij}^k,
\]

where \( F_{ij}^k \in gl(2, \mathbb{C}) \), \( \epsilon_{ij}^k \) is the 2-dimensional basis element of \( K(4) \) and \( 1 \leq i, j \leq 4, \ k = (k_1, k_2, k_3, k_4), \ k_i \in \mathbb{Z} \). Let \( F \) is given by

\[
F = d c A + A \cup A.
\]

Combining (4.7) and (4.15) and using (3.12), (3.13) and (3.15), we obtain

\[
F_{ij}^k = \Delta_i A_j^k - \Delta_j A_i^k + A_i^k A_{\tau j}^k - A_j^k A_{\tau i}^k,
\]

where \( \Delta_i A_j^k = A_{\tau i}^k - A_j^k \) and \( \tau j \) is given by (3.7).

Let us define a discrete analog of the exterior covariant differentiation operator (2.10) as follows

\[
dc A \Omega = dc \Omega + A \cup \Omega + (-1)^{p+1} \Omega \cup A,
\]

where \( \Omega \) is an arbitrary \( p \)-form of \( K(4) \) looking like (3.11). Then a discrete analog of Equations (2.13) can be written as

\[
dc A F = 0, \quad dc A * iF = 0,
\]

where \( i \) is given by (3.18). It is easy to check that the combinatorial Bianchi identity:

\[
dc F + A \cup F = F \cup A = 0
\]

holds for the discrete curvature form (4.16) (cf. (2.13)).

**Remark 4.2.** In the continual case the curvature form \( F \) (2.9) takes values in the algebra \( su(2) \) for any \( su(2) \)-valued connection form \( A \). Unfortunately, this is not true in the discrete case because, generally speaking, the components \( A_k^i A_{\tau j}^k - A_j^k A_{\tau i}^k \) of the form \( A \cup A \) (see (4.16)) do not belong to \( su(2) \).

To define an \( su(2) \)-valued discrete analog of the curvature 2-form we use the quaternionic form of \( A \) (4.8) and put in (4.15). Then the discrete curvature form \( F \) is given by

\[
F = \text{Im}\{dc f \cup e + (f \cup e) \cup (f \cup e)\}.
\]

It should be noted that in the discrete case calculation of the imaginary part of \( f \cup e \) and computing its curvature do not commute.
Proposition 4.3. If \( A = \text{Im}(x^{-1} \cup d^c x) \), where \( x \) is given by (4.19), then \( F = 0 \).

Proof. Using (4.20) and putting \( f = x^{-1} \) in (4.20) we get
\[
F = \text{Im}(d^c(x^{-1} \cup d^c x) + (x^{-1} \cup d^c x) \cup (x^{-1} \cup d^c x)) = \text{Im}(d^c x^{-1} \cup d^c x - d^c x^{-1} \cup x \cup x^{-1} \cup d^c x).
\]

According to (4.4) the form \( x \cup x^{-1} \) has unit components. Hence
\[
d^c x^{-1} \cup x \cup x^{-1} \cup d^c x = d^c x^{-1} \cup d^c x.
\]

We now write down the components of (4.14) using quaternions. Putting (4.9) in (4.10) we find that
\[
\begin{align*}
F_{k,1}^{12} &= (\Delta_1 f_k^1 - \Delta_2 f_k^2 - f_k^3 f_k^4 - f_k^4 f_k^3 - f_k^1 f_k^2 - f_k^2 f_k^1) i \\
&+ (\Delta_1 f_k^1 - \Delta_2 f_k^2 + f_k^3 f_k^4 + f_k^4 f_k^3 + f_k^1 f_k^2 + f_k^2 f_k^1) j \\
&+ (-\Delta_1 f_k^1 - \Delta_2 f_k^2 + f_k^3 f_k^4 - f_k^4 f_k^3 - f_k^1 f_k^2 + f_k^2 f_k^1) k \\
&- f_k^1 f_k^1 - f_k^3 f_k^3 + f_k^3 f_k^1 + f_k^1 f_k^3 + f_k^1 f_k^2 + f_k^2 f_k^1,
\end{align*}
\]
\[
\begin{align*}
F_{k,1}^{13} &= (-\Delta_1 f_k^1 - \Delta_2 f_k^2 + f_k^3 f_k^4 - f_k^4 f_k^3 + f_k^1 f_k^2 + f_k^2 f_k^1) i \\
&+ (\Delta_1 f_k^1 - \Delta_2 f_k^2 - f_k^3 f_k^4 - f_k^4 f_k^3 - f_k^1 f_k^2 + f_k^2 f_k^1) j \\
&+ (\Delta_1 f_k^1 - \Delta_2 f_k^2 + f_k^3 f_k^4 + f_k^4 f_k^3 + f_k^1 f_k^2 + f_k^2 f_k^1) k \\
&- f_k^2 f_k^1 - f_k^4 f_k^1 - f_k^4 f_k^2 - f_k^2 f_k^3 + f_k^3 f_k^3 + f_k^1 f_k^4,
\end{align*}
\]
\[
\begin{align*}
F_{k,1}^{14} &= (\Delta_1 f_k^1 - \Delta_2 f_k^2 - f_k^1 f_k^3 + f_k^4 f_k^3 + f_k^1 f_k^4 - f_k^4 f_k^1) i \\
&+ (-\Delta_1 f_k^1 - \Delta_2 f_k^2 - f_k^1 f_k^3 + f_k^4 f_k^3 + f_k^1 f_k^4 - f_k^4 f_k^1) j \\
&+ (\Delta_1 f_k^1 - \Delta_2 f_k^2 + f_k^3 f_k^4 + f_k^4 f_k^3 + f_k^1 f_k^2 + f_k^2 f_k^1) k \\
&- f_k^3 f_k^1 - f_k^1 f_k^3 - f_k^3 f_k^1 + f_k^1 f_k^3 - f_k^3 f_k^3 + f_k^1 f_k^4,
\end{align*}
\]
\[
\begin{align*}
F_{k,1}^{23} &= (-\Delta_1 f_k^1 - \Delta_2 f_k^2 + f_k^3 f_k^3 + f_k^1 f_k^4 + f_k^1 f_k^3 + f_k^4 f_k^3) i \\
&+ (\Delta_1 f_k^1 - \Delta_2 f_k^2 - f_k^3 f_k^3 - f_k^1 f_k^4 + f_k^1 f_k^3 + f_k^4 f_k^3) j \\
&+ (\Delta_1 f_k^1 - \Delta_2 f_k^2 + f_k^1 f_k^3 - f_k^4 f_k^3 + f_k^1 f_k^3 + f_k^1 f_k^4) k \\
&+ f_k^3 f_k^1 - f_k^4 f_k^1 + f_k^3 f_k^2 - f_k^3 f_k^2 - f_k^1 f_k^3 - f_k^3 f_k^3 + f_k^1 f_k^4,
\end{align*}
\]
\[
\begin{align*}
F_{k,1}^{24} &= (\Delta_2 f_k^1 - \Delta_1 f_k^2 - f_k^3 f_k^4 + f_k^4 f_k^3 - f_k^1 f_k^2 - f_k^2 f_k^1) i \\
&+ (-\Delta_2 f_k^1 - \Delta_1 f_k^2 - f_k^3 f_k^4 - f_k^4 f_k^3 + f_k^1 f_k^2 - f_k^2 f_k^1) j \\
&+ (\Delta_2 f_k^1 + \Delta_1 f_k^2 - f_k^3 f_k^4 - f_k^4 f_k^3 - f_k^1 f_k^2 + f_k^2 f_k^1) k \\
&- f_k^2 f_k^1 + f_k^1 f_k^1 + f_k^3 f_k^4 + f_k^4 f_k^3 - f_k^1 f_k^3 - f_k^3 f_k^3 + f_k^1 f_k^4,
\end{align*}
\]
\[
\begin{align*}
F_{k,1}^{34} &= (\Delta_3 f_k^1 + \Delta_4 f_k^2 + f_k^1 f_k^3 + f_k^2 f_k^4 + f_k^2 f_k^2 + f_k^1 f_k^1) i \\
&+ (-\Delta_3 f_k^1 - \Delta_4 f_k^2 + f_k^1 f_k^3 + f_k^2 f_k^4 + f_k^2 f_k^2 + f_k^1 f_k^1) j \\
&+ (\Delta_3 f_k^1 + \Delta_4 f_k^2 - f_k^1 f_k^3 + f_k^2 f_k^4 - f_k^2 f_k^2 + f_k^1 f_k^1) k \\
&+ f_k^1 f_k^1 + f_k^1 f_k^3 - f_k^4 f_k^1 - f_k^4 f_k^2 + f_k^2 f_k^3 - f_k^2 f_k^3 + f_k^1 f_k^4.
\end{align*}
\]
To obtain the components of (4.20), we must take the imaginary part of these equations.

**Proposition 4.4.** The discrete curvature 2-form \( F \) is \( su(2) \)-valued if and only if

\[
-f_k^2 i_k - f_k^4 j_k + f_k^3 l_k + f_k^1 m_k + f_k^4 l_k - f_k^3 i_k = 0,
\]

\[
f_k^4 i_k - f_k^4 j_k - f_k^2 l_k - f_k^1 m_k + f_k^2 j_k + f_k^4 l_k = 0,
\]

\[
f_k^2 i_k + f_k^2 j_k - f_k^4 l_k - f_k^4 m_k + f_k^2 j_k - f_k^4 l_k = 0,
\]

\[
f_k^4 i_k - f_k^4 j_k - f_k^2 l_k - f_k^4 m_k + f_k^2 j_k - f_k^4 l_k = 0,
\]

\[
f_k^4 i_k + f_k^4 j_k + f_k^2 l_k - f_k^4 m_k + f_k^2 j_k - f_k^4 l_k = 0.
\]

**Proof.** From the above it follows immediately. \( \square \)

**Proposition 4.5.** Let \( e \) is given by (4.19). Then the 2-form \( e \cup \bar{e} \) is self-dual, i.e.,

\[
e \cup \bar{e} = * i(e \cup \bar{e}),
\]

and \( \bar{e} \cup e \) is anti-self-dual, i.e.,

\[
\bar{e} \cup e = -* i(\bar{e} \cup e).
\]

**Proof.** Denote

\[
e_i = \sum_k e_{ik}, \quad \varepsilon_{ij} = \sum_k \varepsilon_{ij}^k.
\]

Recall that \( e_k^i \) and \( \varepsilon_{ij}^k \) are the 1-dimensional and 2-dimensional basic elements of \( K(4) \) (see also (3.3) and (3.5)). From this by (3.19) we obtain \( e_i \cup e_j = \varepsilon_{ij} \) and \( e_j \cup e_i = -\varepsilon_{ij} \) for all \( i < j \). Then we have

\[
e \cup \bar{e} = \{e_1 + e_2 i + e_4 j + e_4 k\} \cup (e_1 - e_2 i - e_4 j - e_4 k)
\]

\[
= -2\{e_1 \cup e_2 + e_4 \cup e_4\} + \{e_1 \cup e_4 + e_2 \cup e_4\} + (e_1 \cup e_4 + e_2 \cup e_4)k
\]

\[
= -2\{(e_{12} + e_{34})i + (e_{13} - e_{24})j + (e_{14} + e_{23})k\}.
\]

Using (3.17) and (3.19) we get

\[
* i(e \cup \bar{e}) = -2\{(\bar{e}_{12} + \bar{e}_{34})i + (-\bar{e}_{24} + \bar{e}_{13})j + (\bar{e}_{23} + \bar{e}_{14})k\} = e \cup \bar{e}.
\]

In the same way we obtain (4.22). \( \square \)

**Corollary 4.6.** For any quaternionic 0-form \( f \) the form \( f \cup e \cup \bar{e} \) is self-dual and \( f \cup \bar{e} \cup e \) is anti-self-dual.

**Proof.** This follows immediately from (3.20). \( \square \)

Discrete self-dual and anti-self-dual equations (discrete analogs of Equations (2.13)) are defined by

\[
F = i * F, \quad F = -\bar{i} * F,
\]

where \( F \) is the discrete curvature form (4.1). Using (4.19), by the definitions of \( i \) and \( * \), the first equation (self-dual) of (5.3) can be rewritten as follows

\[
F_k^{12} = F_k^{34}, \quad F_k^{13} = -F_k^{24}, \quad F_k^{14} = F_k^{23}.
\]

By analogy with the continual case solutions of (4.28) (or (4.24)) are called instantons and anti-instantons respectively.
5. Discrete instanton and anti-instanton

In further analogy with the continual case consider the discrete $SU(2)$-connection $A$. Let $A$ be the quaternionic 1-form (4.8), where the components of $f$ are given by

\[
\begin{align*}
\tilde{f}_k &= \frac{\kappa}{1 + |\kappa|^2},
\end{align*}
\]

where $\kappa = k_1 + k_2i + k_3j + k_4k$, $k_i \in \mathbb{Z}$. Putting the last in (4.9) we obtain

\[
\begin{align*}
A^1_k &= \frac{-k_2i - k_3j - k_4k}{1 + |\kappa|^2}, & A^2_k &= \frac{k_1i - k_4j + k_3k}{1 + |\kappa|^2}, \\
A^3_k &= \frac{k_4i + k_3j - k_2k}{1 + |\kappa|^2}, & A^4_k &= \frac{-k_3i + k_2j + k_1k}{1 + |\kappa|^2}.
\end{align*}
\]

It is convenient to denote

\[
M_i = \frac{1}{(1 + |\kappa|^2)(1 + |\tau_i\kappa|^2)}, \quad i = 1, 2, 3, 4.
\]

Recall that the shift operator $\tau_i$ is given by (4.7). Substituting (5.2) in (4.10) and using (5.3) we find that

\[
\begin{align*}
F_{k}^{12} &= \{M_1(1 + k_2^2 - k_1^2 - k_3) + M_2(1 + k_1^2 - k_2^2 - k_3)\}i \\
&+ \{M_1(k_4k_1 + k_2k_3) - M_2(k_3k_2 + k_4k_1)\}j \\
&+ \{M_1(k_2k_4 - k_3k_1) + M_2(k_1k_3 - k_2k_4)\}k \\
&+ M_1(k_1k_2 + k_2) - M_2(k_1k_2 + k_1),
\end{align*}
\]

\[
\begin{align*}
F_{k}^{13} &= \{M_1(k_2k_3 - k_3k_1) + M_3(k_1k_4 - k_2k_3)\}i \\
&+ \{M_1(1 + k_3^2 - k_1^2 - k_2) + M_3(1 + k_1^2 - k_3^2 - k_2)\}j \\
&+ \{M_1(k_2k_4 + k_3k_3) - M_3(k_3k_4 + k_1k_2)\}k \\
&+ M_1(k_1k_3 + k_3) - M_3(k_1k_3 + k_1),
\end{align*}
\]

\[
\begin{align*}
F_{k}^{14} &= \{M_1(k_4k_3 + k_2k_4) - M_4(k_2k_4 + k_1k_3)\}i \\
&+ \{M_1(k_3k_4 - k_3k_2) + M_4(k_1k_2 - k_3k_4)\}j \\
&+ \{M_1(1 + k_2^2 - k_1^2 - k_3) + M_4(1 + k_1^2 - k_2^2 - k_3)\}k \\
&+ M_1(k_1k_4 + k_4) - M_4(k_1k_4 + k_1),
\end{align*}
\]

\[
\begin{align*}
F_{k}^{23} &= \{-M_2(k_2k_4 + k_1k_3) + M_3(k_1k_4 - k_2k_3)\}i \\
&+ \{M_2(k_3k_4 - k_1k_3) + M_3(k_1k_2 - k_3k_4)\}j \\
&- \{M_2(1 + k_2^2 - k_1^2 - k_3) + M_3(1 + k_1^2 - k_2^2 - k_3)\}k \\
&+ M_2(k_2k_3 + k_3) - M_3(k_2k_3 + k_2),
\end{align*}
\]

\[
\begin{align*}
F_{k}^{24} &= \{M_2(k_2k_3 - k_4k_1) + M_4(k_1k_4 - k_2k_3)\}i \\
&+ \{M_2(1 + k_3^2 - k_2^2 - k_3) + M_4(1 + k_2^2 - k_3^2 - k_3)\}j \\
&- \{M_2(k_1k_2 + k_3k_4) + M_4(k_3k_4 + k_1k_2)\}k \\
&+ M_2(k_2k_4 + k_4) - M_4(k_2k_4 + k_2),
\end{align*}
\]
\( F^{34}_k = -\{ M_3(1 + k_4^2 - k_3^2 - k_2) + M_4(1 + k_3^2 - k_2^2 - k_1) \} i \\
+ \{ M_3(-k_2k_3 - k_1k_4) + M_4(k_1k_3 + k_2k_4) \} j \\
+ \{ M_3(k_2k_4 - k_1k_3) + M_4(k_1k_3 - k_2k_4) \} k \\
+ M_3(k_3k_4 + k_4) - M_4(k_3k_4 + k_3). \)

**Proposition 5.1.** The 2-form \( F \) with components \( F^{ij}_k \) above is \( su(2) \)-valued if and only if
\[
(5.4) \quad k_1 = k_2 = k_3 = k_4.
\]

**Proof.** From Proposition 4.4 \( F \) is \( su(2) \)-valued if and only if
\[
M_i(k_i k_j + k_j) - M_j(k_i k_j + k_i) = 0
\]
for any \( k_i \in \mathbb{Z} \), \( i, j = 1, 2, 3, 4 \) and \( i < j \). It follows immediately \( (5.4) \). \( \square \)

Thus, the \( su(2) \)-valued discrete curvature 2-form \( F \) can be written in the quaternionic form as follows
\[
(5.5) \quad F = \sum_{k_i \epsilon = \mu} M_\mu(2 - 2\mu) \{ (\epsilon_{12}^k - \epsilon_{34}^k) i + (\epsilon_{13}^k + \epsilon_{24}^k) j + (\epsilon_{14}^k - \epsilon_{23}^k) k \}.
\]

From \((5.2)\) here we have \( M_\mu = \frac{1}{2(1 + 4\mu^2)(1 + \mu + 2\mu^2)} \). Since \( k_i = \mu \), in \((5.5)\) we can write \( \epsilon_{ij}^\mu \) instead of \( \epsilon_{ij}^k \).

If we consider the 0-form
\[
(5.6) \quad \omega = \sum_{\mu} M_\mu(1 - \mu) x^\mu, \quad \mu \in \mathbb{Z}
\]
and use the following relation (see the proof of Proposition 4.5)
\[
\bar{\epsilon} \cup e = 2\{ (\epsilon_{12} - \epsilon_{34}) i + (\epsilon_{13} + \epsilon_{24}) j + (\epsilon_{14} - \epsilon_{23}) k \},
\]
then \( F \) can be written as
\[
(5.7) \quad F = \omega \cup \bar{\epsilon} \cup e.
\]

In view of Corollary 4.6 \( F \) is anti-self-dual, i.e., \( F = -\bar{i} * F \). Thus under condition \((5.4)\) \( A \) with components \((5.1)\) describes an anti-instanton.

In the same manner we can see that the following quaternionic 1-form
\[
(5.8) \quad A = \text{Im}(f \cup \bar{\epsilon}),
\]
where \( f \) has the components
\[
(5.9) \quad f_k = \frac{\kappa}{1 + |\kappa|^2},
\]
leads to an instanton solution of \((4.24)\). Indeed, substituting \((5.8)\) and \((5.9)\) in \((4.16)\) we now obtain
\[
F^{12}_k = \{ -M_1(1 + k_2^2 - k_1^2 - k_1) - M_2(1 + k_1^2 - k_2^2 - k_2) \} i \\
+ \{ M_1(k_4k_3 - k_2k_3) + M_2(k_3k_2 - k_1k_1) \} j \\
+ \{ M_1(-k_2k_4 - k_1k_3) + M_2(k_1k_3 + k_2k_4) \} k \\
+ M_1(k_1k_2 + k_2) - M_2(k_1k_2 + k_1),
\]
how the anti-instanton given by (5.1) behaves as

\[ F_{k}^{13} = \{ M_{1}(-k_{2}k_{3} - k_{1}k_{4}) + M_{3}(k_{1}k_{4} + k_{2}k_{3}) \}i \]

\[ - \{ M_{1}(1 + k_{2}^{2} - k_{1}^{2}) + M_{3}(1 + k_{1}^{2} - k_{3}^{2}) \}j \]

\[ + \{ M_{1}(k_{1}k_{2} - k_{3}k_{4}) + M_{3}(k_{3}k_{4} - k_{1}k_{2}) \}k \]

\[ + M_{1}(k_{1}k_{3} + k_{3}) - M_{3}(k_{1}k_{3} + k_{1}), \]

\[ F_{k}^{14} = \{ M_{1}(k_{1}k_{3} - k_{2}k_{4}) + M_{4}(k_{2}k_{4} - k_{1}k_{3}) \}i \]

\[ + \{ M_{1}(-k_{3}k_{4} - k_{1}k_{2}) + M_{4}(k_{1}k_{2} + k_{3}k_{4}) \}j \]

\[ - \{ M_{1}(1 + k_{2}^{2} - k_{1}^{2}) + M_{4}(1 + k_{1}^{2} - k_{3}^{2} - k_{4}) \}k \]

\[ + M_{1}(k_{1}k_{4} + k_{4}) - M_{4}(k_{1}k_{4} + k_{1}), \]

\[ F_{k}^{23} = \{ M_{2}(-k_{2}k_{4} + k_{1}k_{3}) + M_{5}(-k_{1}k_{3} + k_{2}k_{4}) \}i \]

\[ + \{ M_{2}(k_{2}k_{4} + k_{1}k_{3}) - M_{5}(k_{1}k_{2} + k_{3}k_{4}) \}j \]

\[ - \{ M_{2}(1 + k_{2}^{2} - k_{2}^{2} - k_{2}) + M_{5}(1 + k_{2}^{2} - k_{2}^{2} - k_{3}) \}k \]

\[ + M_{2}(k_{2}k_{3} + k_{3}) - M_{5}(k_{2}k_{3} + k_{2}), \]

\[ F_{k}^{24} = \{ M_{2}(k_{2}k_{3} + k_{4}k_{1}) - M_{4}(k_{1}k_{4} + k_{2}k_{3}) \}i \]

\[ + \{ M_{2}(1 + k_{2}^{2} - k_{2}^{2} - k_{2}) + M_{4}(1 + k_{2}^{2} - k_{2}^{2} - k_{4}) \}j \]

\[ + \{ M_{2}(k_{1}k_{2} - k_{3}k_{4}) + M_{4}(k_{3}k_{4} - k_{1}k_{2}) \}k \]

\[ + M_{2}(k_{2}k_{4} + k_{4}) - M_{4}(k_{2}k_{4} + k_{2}), \]

\[ F_{k}^{34} = -\{ M_{3}(1 + k_{3}^{2} - k_{3}^{2} - k_{3}) + M_{4}(1 + k_{3}^{2} - k_{3}^{2} - k_{3}) \}i \]

\[ + \{ M_{3}(-k_{2}k_{3} + k_{1}k_{4}) + M_{4}(-k_{1}k_{4} + k_{2}k_{3}) \}j \]

\[ + \{ M_{3}(k_{2}k_{4} + k_{1}k_{3}) - M_{4}(k_{1}k_{3} + k_{2}k_{4}) \}k \]

\[ + M_{3}(k_{3}k_{4} + k_{4}) - M_{4}(k_{3}k_{4} + k_{3}). \]

Again, under condition (5.4) we can write \( F \) as

\[ F = \sum_{\mu} M_{\mu}(2\mu - 2)\{ (\varepsilon_{12}^{\mu} + \varepsilon_{34}^{\mu})i + (\varepsilon_{13}^{\mu} + \varepsilon_{24}^{\mu})j + (\varepsilon_{14}^{\mu} + \varepsilon_{23}^{\mu})k \}, \]

where \( \mu \in \mathbb{Z} \). Therefore

\[ (5.10) \quad F = \omega \cup e \cup \bar{e}, \]

where \( \omega \) is given by (5.6). Thus the discrete curvature form (5.10) is self-dual and we can say that (5.8) describes an instanton.

Now to complete the analogy with the continual case we describe more precisely how the anti-instanton given by (5.1) behaves as \( |\kappa| \to \infty \). It is clear that \( f_{k} \) is asymptotically

\[ \frac{R}{|\kappa|^{r}} = \kappa^{-1}. \]

Then

\[ (5.11) \quad A \sim \text{Im}(x^{-1} \cup d^{-}x) \quad \text{as} \quad |\kappa| \to \infty. \]

Here \( x \) is given by (4.10). By virtue of Proposition 4.3 the discrete curvature \( F = 0 \) at infinity.

**Proposition 5.2.** The anti-instanton (5.7) has the same form at \( \infty \) as it has near \( \theta \).
Proof. Introduce the quaternionic 0-form
\[ y = \sum_k y_k x^k, \quad \text{where} \quad y_k = \frac{1}{\kappa}, \]
and remind \( \kappa = k_1 + k_2i + k_3j + k_4k. \) Clearly, \( y = x^{-1}. \) We first compute \( x \cup f \cup e \cup x^{-1}, \) where \( f \) is given by (5.1). To do this, take (4.10), (4.11) and use the \( \cup \)-product definition. We have
\[
x \cup f \cup e = \left( \sum_k \kappa x^k \right) \cup \left( \sum_k \frac{\bar{\kappa}}{1 + |\kappa|^2} x^k \right) \cup e
= \left( \sum_k \frac{|\kappa|^2}{1 + |\kappa|^2} x^k \right) \cup e = \left( \sum_k \frac{1}{1 + |\kappa|^2} x^k \right) \cup e
= d^c x - \left( \sum_k \frac{1}{1 + |\kappa|^2} x^k \right) \cup d^c x.
\]
From this by (4.5) we get
\[
(5.12) \quad x \cup f \cup e \cup x^{-1} = -x \cup d^c x^{-1} + \left( \sum_k \frac{\kappa}{1 + |\kappa|^2} x^k \right) \cup d^c x^{-1}.
\]

Now gauge transform the form \( f \cup e \) by the gauge transformation \( g = x^{-1}. \) We must take the imaginary part of (4.13). This yields by (5.12)
\[
\text{Im}(g^{-1} \cup f \cup e \cup g + g^{-1} \cup d^c g) = \text{Im}\left( \left( \sum_k \frac{\kappa}{1 + |\kappa|^2} x^k \right) \cup d^c x^{-1} \right)
= \text{Im}\left( \left( \sum_k \frac{\bar{\kappa}y_k}{1 + |y_k|^2} x^k \right) \cup d^c y \right).
\]
Hence the gauge transformed anti-instanton \( A \) has precisely the form (5.11) near \( y = 0. \)

The same conclusion can be drawn for the instanton (5.8).

In the continual theory Proposition 5.2 shows that the anti-instanton (or instanton) extends to the 4-sphere \( S^4. \) This follows from the fact that \( S^4 \) can be obtained from \( \mathbb{R}^4 \) by adding the point at infinity, i.e., \( S^4 \simeq \mathbb{R}^4 \cup \{\infty\}. \) To obtain the same result for our discrete model we need to construct a suitable combinatorial analog of the 4-sphere. It would be interesting to connect the above constructions with discrete model of \( S^4 \) described in [21]. This connection must be investigated and we hope to treat its further in future work.

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