EmoBERTa: Speaker-Aware Emotion Recognition in Conversation with RoBERTa

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Abstract
We present EmoBERTa: Speaker-Aware Emotion Recognition in Conversation with RoBERTa, a simple yet expressive scheme of solving the ERC (emotion recognition in conversation) task. By simply prepending speaker names to utterances and inserting separation tokens between the utterances in a dialogue, EmoBERTa can learn intra- and inter-speaker states and context to predict the emotion of a current speaker, in an end-to-end manner. Our experiments show that we reach a new state of the art on the two popular ERC datasets using a basic and straight-forward approach. We’ve open sourced our code and models at [https://github.com/tae898/erc](https://github.com/tae898/erc).

1 Introduction
The scope of emotion recognition is very wide, ranging from stills of face images, audio data to the actual utterances or text as in tweets. In this paper, we focus on emotion recognition in conversation (ERC), which is a subfield of emotion recognition. More specifically, the task is to predict the emotion of a current speaker who’s engaging in a conversation with one person or more. Recognizing emotion is important to areas such as affective computing and human-robot communication, in which it can be an important feedback mechanism.

As humans use multiple sensory inputs to have a conversation (e.g., vision, voice, etc.) the ERC task can also include multiple modalities (e.g., visual, audio, text, etc.). Here, we report on our first experiments on the text modality, leaving using multiple modalities within our framework to future work.

Since the introduction of the Transformer (Vaswani et al., 2017), transformer-based deep neural network models have become the dominating neural network model in sequence modeling. Especially, pretrained encoder-only models such as BERT (Devlin et al., 2019) and RoBERTa (Liu et al., 2019) have shown that they can be success-fully fine-tuned for downstream tasks, such as sentence classification and question answering. ERC can be seen as a special case of sequence modeling, since emotions are expected to be triggered by a preceding event in any modality.

Our approach to ERC enriches such transformer models by including the speaker identity in the sequence information spanning multiple utterances. By adapting the RoBERTa sequence representation, we improve the SOTA on two popular benchmark datasets.

2 Related Work
Most of the existing works on ERC combine different kinds of neural network architectures (e.g., CNNs, RNNs, Transformers, GNNs, etc.) (Li et al., 2020b), (Li et al., 2020c), (Ishiwatari et al., 2020), (Wang et al., 2020), (Hazarika et al., 2021), (Sheng et al., 2020), (Ghosal et al., 2020), (Ghosal et al., 2019). The biggest downside of such approaches is that each part of the model is responsible for extracting their own features. These extracted features might not be ideal for the other parts of the model. Also, since these models are combinations of sub-models, it is hard to understand what each sub-model is contributing and how to improve the overall model. Some of the approaches try to take advantage of external knowledge bases (Ghosal et al., 2020), (Zhong et al., 2019a), which adds even more complexity to the model.

A substantial number of approaches are heavily based on RNNs (e.g., GRU) to model the sequence (Jiao et al., 2019), (Lu et al., 2020). The biggest problem with this is that it inherently decouples the word embedding extraction and the sequence modeling, whereas BERT-like models tackle them at once, often leading to a better performance. Also, they have to rely on external decontextualized word embedding extractors (e.g., GloVe (Pennington et al., 2014) or word2vec (Mikolov et al., 2013)). Furthermore, training an RNN is
The approaches that are most closely related to us are HiTrans (Li et al., 2020a) and DialogXL (Shen et al., 2020). HiTrans packs multiple utterances with [CLS] tokens prepended into one input sequence. This sequence is first fed into a BERT and then to another transformer. DialogXL is based on XLNet (Yang et al., 2019). Our approach differs in that we just use RoBERTa and encode the speaker information with multiple utterances.

3 Methodology

3.1 Problem Definition

Let’s say a dialogue of $M$ utterances is given and $I$ interlocutors are engaging in a conversation. Then the dialogue can be expressed as a list of vectors: 

$$\text{dialogue} = \{x_1, x_2, \ldots, x_M\},$$

where an utterance $x_t$ contains several words (tokens). Each utterance $x_t$ is spoken by a unique speaker $\in I$. Since this is a supervised setup, every utterance $x_t$ has one corresponding label $y_t$ that is annotated by a human.

The simplest way to solve this problem is to come up with a function $f$ that takes $x_t$ as an input and outputs the correct label $y_t$. However, this doesn’t take context into account. It’s easily conceivable that the function $f$ should also consider the past utterances $[x_1, x_2, \ldots, x_{t-1}]$ or even the future utterances $[x_{t+1}, x_{t+2}, \ldots, x_M]$ to model the context.

3.2 EmoBERTa

EmoBERTa starts from the pretrained roberta-large model (Liu et al., 2019). Since the task is basically a sequence classification task, we simply add a randomly initialized linear layer with the softmax nonlinearity to the first hidden state (this state corresponds to the [CLS] token) of the last layer of the pretrained model.

We chose RoBERTa, among the many BERT-like models, because its structure is not only relatively simple, but also it can deal with more than two segments. The original authors of RoBERTa simply used two </s> tokens consecutively as [SEP] token, which separates the first and the second segments. Although the pretrained model has not been trained on more than two segments, we show that EmoBERTa can be generalized to three segments per input sequence.

The first, second, and third segments contain the past utterances, the current utterance, and the future utterances, respectively, in a dialogue. Each utterance is prepended with the name of a speaker so that the model is aware which utterance is spoken by whom. The task is to predict the emotion of the current utterance.

RoBERTa uses <s> and </s> as [CLS] and [EOS] tokens, respectively. Building an input sequence for EmoBERTa is outlined in Algorithm 1. Example sequences can be found in Figure 1.

### Algorithm 1: Building an input sequence

Given the current utterance

$$x_t \in \{x_1, x_2, \ldots, x_M\};$$

max_tokens = 512 - 2;

sequence = [SEP] + tokenize(x_t) + [SEP];

$i = 1$;

while \(\text{len(sequence)} \leq \text{max_tokens}\) do

Prepend speaker(x_{t-i}) + “:” + x_{t-i} to sequence;

Append speaker(x_{t+i}) + “:” + x_{t+i} to sequence;

$i = i + 1$;

end

Remove the last appended / prepended utterances;

sequence = [CLS] + sequence + [EOS];

3.3 Training

The loss is calculated as the sum of cross entropy loss and $L^2$ weight decay (Krogh and Hertz, 1991). We use adaptive gradient descent (Kingma and Ba, 2015), (Loshchilov and Hutter, 2019) with gradual linear warmup learning rate scheduling (Goyal et al., 2017). The peak learning rate was determined using Optuna (Akiba et al., 2019). Mixed floating point precision was used to reduce the training time and increase the batch size (Micikevicius et al., 2017). See Appendix A.1 for the details (e.g., hyperparameters, training time, hardware, etc.). We mostly used the huggingface transformer pytorch library for training (Wolf et al., 2020).

Then the training loss function is

The pretrained RoBERTa model can have a maximum of 512 tokens in one input sequence. The while loop terminates if there are no more available past / future utterances to add in the dialogue. We empirically found that capitalizing the names of the interlocutors leads to slightly better results.
\begin{equation}
    \mathcal{L}(w) = -\frac{1}{N} \sum_{i=1}^{N} \sum_{c=0}^{C-1} y_c^{(i)} \log(\hat{y}_c^{(i)}) + \frac{\lambda}{2} \| w \|_2^2
\end{equation}

where \( y_c^{(i)} \) is a one-hot label vector, \( \hat{y}_c^{(i)} \) is the softmax output vector given the input \( x^{(i)} \), \( N \) is the number of training data samples, \( C \) is the number of classes, \( \lambda \) is a \( L^2 \) regularization rate, and \( w \) are the weights of the model. In practice, the data samples are batched, and stochastic gradient descent is used.

Although the weights \( w \) were tuned to minimize the loss value, the final model is chosen where the weighted \( f_1 \) score on the validation split is the highest, since that’s the metric that we report.

### 4 Experiments

#### 4.1 Datasets and Evaluation Metrics

| Dataset  | number of dialogues (utterances) | train | val | test |
|----------|----------------------------------|-------|-----|------|
| MELD     | 1,038 (9,989)                   | 114 (1,109) | 280 (2,610) |
| IEMOCAP  | 100 (4,778)                     | 20 (980) | 31 (1,622) |

| Dataset  | mean number of utterances per dialogue (std.) | train | val | test |
|----------|-----------------------------------------------|-------|-----|------|
| MELD     | 9.6 (5.8)                                     | 9.7 (5.4) | 9.3 (5.7) |
| IEMOCAP  | 47.78 (16.47)                                 | 49.0 (17.44) | 52.32 (17.36) |

Table 1: The upper half of the table shows the number of dialogues and utterances of the datasets. The bottom half shows the mean and the standard deviation of the number of utterances per dialogue. As shown, IEMOCAP has about 5 times more utterances per dialogue than MELD.

We test EmoBERTa on the two popular ERC datasets. MELD (Poria et al., 2019) is a multimodal (visual, audio, and text) and multi-party (more than two interlocutors in a dialogue) conversational dataset. It was collected from the TV series Friends. The seven emotions are neutral, joy, surprise, anger, sadness, disgust, and fear. Weighted \( f_1 \) score is used to evaluate the performance, as the class distribution is highly imbalanced.

IEMOCAP (Busso et al., 2008) is a multimodal (visual, audio, and text) and dyadic (only two interlocutors in a dialogue) conversational dataset. Ten actors participated in the data collection. Although the original dataset contains 11 different emotions, only six of them are used for evaluation. They are neutral, frustration, sadness, anger, excited, and happiness. As MELD, the class distribution is highly imbalanced and thus a weighted \( f_1 \) score will be used for evaluation. Unlike MELD, IEMOCAP does not officially have the names of the speakers. Therefore, we gave each actor a random name. See Appendix A.2 for the details.

Some statistics on train, val, and test splits of both datasets can be found at Table 1.

#### 4.2 Baselines

We compare our model with the models we mentioned in Section 2.

### 5 Results and Analysis

#### 5.1 Quantitative Analysis

Table 2 shows the performance of our models and the baselines. Our models outperform the other models on both MELD and IEMOCAP.

| Model    | MELD (%) | IEMOCAP (%) |
|----------|----------|-------------|
| BERT+MTL (Li et al., 2020b) | 61.90 | - |
| BiERU-ic (Li et al., 2020c) | 60.84 | 64.65 |
| DialogueGCN (Ghosal et al., 2019) | 58.1 | 64.18 |
| RGAT (Ishiwatari et al., 2020) | 60.91 | 65.22 |
| CESTa (Wang et al., 2020) | 58.36 | 67.1 |
| VHRED (Hazarika et al., 2021) | - | 58.6 |
| SumAggGIN (Sheng et al., 2020) | 58.45 | 66.61 |
| COSMIC (Ghosal et al., 2020) | 65.21 | 65.28 |
| KET (Zhong et al., 2019b) | 58.18 | 59.56 |
| BiF-AGRU (Jiao et al., 2019) | 58.1 | 63.5 |
| Iterative (Lu et al., 2020) | 60.72 | 64.37 |
| HiTrans (Li et al., 2020a) | 61.94 | 64.5 |
| DialogXL (Shen et al., 2020) | 62.41 | 65.94 |
| EmoBERTa | No past and future utterances | 65.61 | 67.42 |
| | Only past utterances | 65.55 | 68.57 |
| | Only future utterances | 64.23 | 66.56 |
| | Both past and future utterances \( \rightarrow \) without speaker names | 65.07 | 64.02 |

Table 2: All of the reported values are weighted \( f_1 \) score on the test splits. The best model and the best performance values are in bold. Since the values are stochastic in nature, we report the mean values of five random seeds.

EmoBERTa shows very good results: max weighted \( f_1 \) scores (%) of 65.61 (MELD) and 68.57 (IEMOCAP) respectively and above the best reported SOTA, especially considering that no modifications were made to the original RoBERTa model architecture. We also trained a model without the speaker names prepended, which drops the performance: weighted \( f_1 \) scores (%) of 65.07 (MELD) and 64.02 (IEMOCAP) respectively.
ROSS: I think she took it pretty well. You know Paolo’s over there right now, so... she just kind of... she didn’t really cry. ROSS: Oh, well, looks like, uh, she kicked your butt. BOB: No, she kicked our butts! ROSS: Oh, well, looks like, uh, she kicked your butt. BOB: No, she kicked our butts! ROSS: What are you still doing here? She just broke up with the guy, it’s time for butts. You could be on the Olympic standing-there team. ROSS: Come on, two on one. ROSS: You’re there for her. CHANDLER: You pick up the pieces, and then you usher in the age of Ross! CHANDLER: Okay, I gotta ask, who calls us that?!

JOEY: You’re like, like the best friend cry? MONICA: I mean we—we told Joey, he cried his eyes out! JOEY: It’s like the end of an era! JOEY: No more J-man and Channie’s! CHANDLER: Okay, I gotta ask, who calls us that?!

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A Appendix

A.1 Training Details

We used GCP (Google Cloud Platform) Compute Engine to carry out our experiments. We used an NVIDIA Tesla V100 machine (disclaimer: we are supported by neither Google nor NVIDIA). This GPU has 16 GB of memory and depending on the length of the input sequence, we were able to fit 4 to 16 samples in one batch, using mixed precision. The pretrained roberta-large model has about 355 million parameters. We found that without mixed precision, it’s very difficult to train this model, since it’s a pretty big model.

We set the value of $L^2$ regularization rate as 0.01. Training was done for five epochs. No weights were frozen during the training. The learning rate scheduler was set to linearly increase in the first 20% of training and then linearly decrease in the remaining 80%.

Since the optimal peak learning rate highly depends on the batch size and the other hyperparameters, we used Optuna (Akiba et al., 2019) to find its best value. 10% of the training data and the same amount of validation data were used to search for the best value. Optuna ran five trials and looked for the best learning rate, between $1e-6$ and $1e-4$, that minimizes the cross entropy loss on the validation data split.

The hyperparameters not mentioned here are all set to the default values.

One full five-epoch training took about 45 minutes.

A.2 IEMOCAP Speaker Names

Since the IEMOCAP dataset was created in the US, we used the top five male and female American names over the past 100 years (https://www.ssa.gov/oact/babynames/decades/century.html).

The female names used are Mary, Patricia, Jennifer, Linda, and Elizabeth. The male names used are James, John, Robert, Michael, and William.

A.3 Qualitative Analysis on IEMOCAP

Unlike MELD, only 20% of the correctly classified samples showed the behavior of the last layer $<s>$ token attending to the current target speaker. This ratio was 10% for the incorrectly classified samples. We believe this is due to the fact that the speaker names in the test split of IEMOCAP (i.e., WILLIAM and ELIZABETH) were never seen during training.)

Figure 2 gives you a visualization of the qualitative analysis on the IEMOCAP dataset.

Figure 2: Two examples from the 20 randomly selected test samples are shown. The current speaker utterance, of which the emotion that the model has to predict, is in bold. The green highlighted tokens are the top 10 most attended tokens to the current speaker (i.e., WILLIAM and ELIZABETH, for Figure 2a and 2b, respectively) in the beginning layer of the model. The yellow highlighted tokens are the top 10 most attended tokens to the [CLS] token (i.e. $<s>$) in the last layer. Unlike Figure 1, there is only one [SEP] token (i.e., $<s>/<s>$), since this model only has two segments, past and current. Best viewed when zoomed in.

We see a similar behavior as in MELD. Again, in the incorrectly classified example, the $<s>$ in the last layer does not attend to the current speaker.