Linear Coding for Gaussian Two-Way Channels

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Abstract—We consider linear coding for Gaussian two-way channels (GTWCs), in which each user generates the transmit symbols by linearly encoding both its message and the past received symbols (i.e., the feedback information) from the other user. In Gaussian one-way channels (GOWCs), Butman has proposed a well-developed model for linear encoding that encapsulates feedback information into transmit signals. However, such a model for GTWCs has not been well studied since the coupling of the encoding processes at the users in GTWCs render the encoding design non-trivial and challenging. In this paper, we aim to fill this gap in the literature by extending the existing signal models in GOWCs to GTWCs. With our developed signal model for GTWCs, we formulate an optimization problem to jointly design the encoding/decoding schemes for both the users, aiming to minimize the weighted sum of their transmit powers under signal-to-noise ratio constraints. First, we derive an optimal form of the linear decoding schemes under any arbitrary encoding schemes employed at the users. Further, we provide new insights on the encoding design for GTWCs. In particular, we show that it is optimal that one of the users (i) does not transmit the feedback information to the other user at the last channel use, and (ii) transmits its message only over the last channel use. With these solution behaviors, we further simplify the problem and solve it via an iterative two-way optimization scheme. We numerically demonstrate that our proposed scheme for GTWCs achieves a better performance in terms of the transmit power compared to the existing counterparts, such as the non-feedback scheme and one-way optimization scheme.

I. INTRODUCTION

The two-way channel was first studied by Shannon [1], where two users exchange their messages with each other through their separate channels. In this paper, we consider Gaussian two-way channels (GTWCs), where Gaussian noise is added independently to each way of the channels between the users. Han in [2] showed that incorporating feedback information (i.e., the previously received symbols) into transmit symbols for encoding does not increase the capacity of GTWCs. Nevertheless, it has been shown that feedback can improve the communication reliability of Gaussian channels [3]–[9].

For Gaussian one-way channels (GOWCs), the seminal work done by Schalkwijk and Kailath (S-K) in [3] introduced a simple linear encoding that can achieve doubly exponential decay in the probability of error upon having noiseless feedback information. In [4], Chance and Love proposed a linear encoding scheme for GOWCs with noisy feedback, which is further analyzed and revealed to be the optimal linear encoding scheme by [5]. In [6], Kim et al. exploited deep learning for a non-linear coding in GOWCs and showed performance improvements in the error probability.

For GTWCs, several recent works have revealed the advantages of feedback in terms of improving communication reliability. In [7], Palacio-Baus and Devroye showed that feedback can improve the error exponent as compared to the non-feedback case. In [10], Vasal suggested a dynamic programming (DP)-based methodology for encoding in GTWCs. Although the effectiveness of the DP approach in GTWCs has not been verified, the author’s previous work [8] revealed that the DP approach is effective in GOWCs with noisy feedback.

To the best of our knowledge, a general system model for linear encoding in GTWCs has not been well studied, unlike the well-developed counterpart for GOWCs proposed by Butman [9]. Furthermore, designing the linear encoding schemes for GTWCs is a non-trivial process since the coupling of the encoding processes at the users should be encapsulated in the system model. In this paper, we aim to bridge the gaps between the two pieces of literature on GOWCs and GTWCs. To this end, we propose a general system model for linear coding in GTWCs by extending the existing formulations in GOWC literature [4], [5], [9] to GTWCs.

Furthermore, using our developed signal model for GTWCs, we define the signal-to-noise ratio (SNR) at the users, and then derive an optimal form of the linear decoding schemes by maximizing the SNRs under arbitrary encoding schemes employed at the users. We then formulate the weighted sum of transmit power minimization problem to satisfy arbitrary SNR thresholds, aiming to jointly optimize the encoding/decoding schemes of the users. To mitigate the coupling effect caused by encoding processes at the users, we assume that one of the users (i.e., User 2) feeds back only recently received signal. Under this assumption, we theoretically characterize the optimal solution for a part of the encoding schemes. In particular, we first prove that it is optimal for one of the users (i.e., User 2) not to utilize the last channel use for feeding back the previously received signals to the other user (i.e., User 1). Second, based on our conjecture, we claim that it is optimal for User 2 to transmit the message only over the last channel use. From our theoretical insights on the encoding and decoding design, we further simplify the optimization problem and propose an iterative two-way optimization scheme to solve it. Through numerical experiments, we reveal that our proposed two-way...
optimization scheme outperforms the open loop (i.e., non-feedback) and the one-way optimization schemes.

II. SYSTEM MODEL IN GAUSSIAN TWO-WAY CHANNELS

We consider a two-way channel between two users, User 1 and User 2, as shown in Fig. 1. We assume that User 1 and 2 perform linear encoding and decoding of blocklength $N$. Let $k \in \{1, \ldots, N\}$ denote the index of channel use, and $x_1[k]$ and $x_2[k]$ represent the transmit signals at User 1 and User 2, respectively, at time $k$. We consider additive white Gaussian noise (AWGN) channels between the users. Subsequently, the received signal at User 2, $y_2[k]$, and User 1, $y_1[k]$, at time $k$ are given by

$$y_2[k] = x_1[k] + n_1[k],$$

$$y_1[k] = x_2[k] + n_2[k],$$

respectively, where $n_1[k] \sim \mathcal{N}(0, \sigma_1^2)$ and $n_2[k] \sim \mathcal{N}(0, \sigma_2^2)$ are Gaussian noises. Considering signal exchange over the blocklength of $N$, we represent the received signals at User 2 and User 1 in vector form as $y_2 = [y_2[1], \ldots, y_2[N]]^\top \in \mathbb{R}^{N \times 1}$ and $y_1 = [y_1[1], \ldots, y_1[N]]^\top \in \mathbb{R}^{N \times 1}$, respectively, given by

$$y_2 = x_1 + n_1,$$

$$y_1 = x_2 + n_2,$$

where $x_i = [x_i[1], \ldots, x_i[N]]^\top$ and $n_i = [n_i[1], \ldots, n_i[N]]^\top$, $i \in \{1, 2\}$.

The goal of signal exchange among the users is to transmit the message available at each user to the other. In particular, each User $i$, $i \in \{1, 2\}$, aims to transmit a unique message $m_i \in \mathbb{R}$ to the other user where $\mathbb{E}[m_i] = 0$ and $\mathbb{E}[m_i^2] = 1$. Motivated by the advantages of incorporating the received signals into transmit signals through feedback in GOWCs, e.g., enhancing communication reliability [3]–[5], [9], we consider a linear coding framework at the users that exploits the feedback enhancing communication reliability [3]–[5], [9], we consider a two-way channel between two users, User 1 and 2, as shown in Fig. 1. We assume that User 1 and 2 transmit signals. User 1 constructs the transmit signal at time $k$, $x_1[k]$, as a function of the message $m_1$ and the received signals up to time $k-1$, $\{y_1[\tau]\}_{\tau=1}^{k-1}$.

We consider that User $i$, $i \in \{1, 2\}$, employs the message encoding vector $\bar{g}_i \in \mathbb{R}^{N \times 1}$ for encoding the message $m_i$ and the feedback encoding matrix $\bar{F}_i \in \mathbb{R}^{N \times N}$ for encoding the received signals. Note that $\bar{F}_i$, $i \in \{1, 2\}$, is strictly lower triangular (i.e., the matrix entries are zero on and above the diagonal) due to causality of the system. To avoid feeding back redundant information, we consider that each user removes the contribution of its known prior transmitted signals from the received signals to generate its future transmit signals. For the case of User 1, the transmit signal $x_1$ is encoded by User 2 with $\bar{F}_2$ and then transmitted back to User 1. Therefore, User 1 subtracts its transmit portion $x_1$ from the receive signal $y_1$ as $y_1 - \bar{F}_2 x_1$. It is obvious that using the feedback information $y_1$ is equivalent to using the modified feedback information $y_1 - \bar{F}_2 x_1$. Similarly, User 2 subtracts its transmit portion $x_2$ from $y_2$ and obtains the modified feedback information $y_2 - \bar{F}_1 x_2$. The transmit signals of the users are then given by

$$x_1 = \bar{g}_1 m_1 + \bar{F}_1 (y_1 - \bar{F}_2 x_1),$$

$$x_2 = \bar{g}_2 m_2 + \bar{F}_2 (y_2 - \bar{F}_1 x_2).$$

Since each of the users transmits the signals encapsulating the received signals from the other over the multiple channel uses, a coupling occurs between the transmit signals at the users. To mitigate the coupling effects in the signal representation, we rewrite the signal model in (5)-(6) as

$$x_1 = g_1 m_1 + \bar{F}_1 (y_1 - \bar{F}_2 x_1),$$

$$x_2 = g_2 m_2 + \bar{F}_2 (y_2 - \bar{F}_1 x_2).$$

By expressing $g_1$, $\bar{F}_1$, $g_2$, and $\bar{F}_2$ as functions of $\bar{g}_1$, $\bar{F}_1$, $\bar{g}_2$, and $\bar{F}_2$, specifically, we can reformulate the equation in (6) and obtain

$$x_2 = (I + \bar{F}_2 \bar{F}_1)^{-1} g_2 m_2 + (I + \bar{F}_2 \bar{F}_1)^{-1} \bar{F}_2 y_2.$$  

By comparing the equations in (5) and (9), we can find $g_2 = (I + \bar{F}_2 \bar{F}_1)^{-1} \bar{g}_2$ and $F_2 = (I + \bar{F}_2 \bar{F}_1)^{-1} \bar{F}_2$. Similarly, we can rewrite the equation in (5) as

$$x_1 = g_1 m_1 + \bar{F}_1 (y_1 - \bar{F}_2 x_1 - F_2 x_1 + F_2 x_1)$$

$$= (I - \bar{F}_1 (F_2 - \bar{F}_2))^{-1} g_1 m_1$$

$$+ (I - \bar{F}_1 (F_2 - \bar{F}_2))^{-1} \bar{F}_1 (y_1 - F_2 x_1).$$

By comparing the equations in (7) and (10), we can find $g_1 = A^{-1} \bar{g}_1$ and $\bar{F}_1 = A^{-1} \bar{F}_1$, where $A = I - \bar{F}_1 (F_2 - \bar{F}_2) = I - \bar{F}_1 ((I + \bar{F}_2 \bar{F}_1)^{-1} - I) \bar{F}_2$. Note that both $F_1$ and $F_2$ are strictly lower triangular.

Henceforth, we aim to design $g_1$, $\bar{F}_1$, $g_2$, and $\bar{F}_2$ and focus on the signal representation in (7)-(8). Accordingly, we rewrite the received signal expressions in (5)-(6) as

$$y_1 = g_2 m_2 + \bar{F}_2 y_2 + n_2,$$

$$y_2 = g_1 m_1 + \bar{F}_1 (y_1 - \bar{F}_2 x_1) + n_1$$

$$= g_1 m_1 + \bar{F}_1 g_2 m_2 + (I + \bar{F}_1 \bar{F}_2) n_1 + \bar{F}_1 n_2.$$  

Considering the received signals (11)-(12), the transmit signals in (7)-(8) can be written as the sum of the messages and noises as follows:

$$x_1 = g_1 m_1 + \bar{F}_1 (g_2 m_2 + \bar{F}_2 n_1 + n_2),$$

$$x_2 = g_2 m_2 + \bar{F}_2 (g_1 m_1 + F_1 g_2 m_2 + (I + \bar{F}_1 \bar{F}_2) n_1 + \bar{F}_1 n_2)$$

$$= (I + \bar{F}_2 \bar{F}_1) g_2 m_2 + F_2 g_1 m_1$$

$$+ \bar{F}_2 (I + \bar{F}_1 \bar{F}_2) n_1 + \bar{F}_2 F_1 n_2.$$  

![Fig. 1: System model for Gaussian two-way channels.](image)
Using the above two expressions, we formulate the transmit power of the users as
\[
E\left[\|x_1\|^2\right] = \|g_1\|^2 + \|F_1g_2\|^2 + \|F_1F_2\|^2 \sigma_1^2 + \|F_1\|^2 \sigma_2^2, \\
E\left[\|x_2\|^2\right] = \|(I + F_2F_1)g_2\|^2 + \|F_2g_1\|^2 + \|F_2(F_1 + F_2)\|^2 \sigma_2^2 + \|F_2F_1\|^2 \sigma_1^2,
\]
where the messages and the noises are assumed to be uncorrelated to each other. In the following section, we define SNRs of the users and obtain the optimal decoding schemes by maximizing the SNRs. We then introduce our encoding design and solution method.

III. LINEAR ENCODING AND DECODING SCHEMES IN GTWC

A. Design of Optimal Linear Decoding Schemes

Since the decoding is conducted at each of the users independently, we can use the same technique used in GOWC to find the optimal linear decoding scheme \([4, 5]\). After the \(N\) channel uses, each user aims to estimate the message of the other user. We first consider that User 1 estimates \(m_2\) with the received signal \(y_1\) by using a linear combining vector \(w_2 \in \mathbb{R}^{N \times 1}\). By plugging \(y_2\) (given by (12)) in \(y_1\) (given by (11)), we can rewrite \(y_1\) as \(y_1 = F_2g_1m_1 + (I + F_2F_1)g_2m_2 + F_2(I + F_1F_2)n_1 + (I + F_2F_1)n_2\). Through a pre-processing phase, User 1 is assumed to subtract its message contribution, \(F_2g_1m_1, \) from \(y_1\) to obtain \(z_1 = y_1 - F_2g_1m_1 = (I + F_2F_1)g_2m_2 + (I + F_2F_1)F_2n_1 + (I + F_2F_1)n_2\). For estimating \(m_1\), using \(z_1\) is equivalent to using \(\hat{y}_1 = (I + F_2F_1)^{-1}z_1 = g_2m_2 + F_2n_1 + n_2\). Using the result of pre-processing, User 1 obtains the message estimate \(\hat{m}_2 = w_2^\top \hat{y}_1\). The SNR used to estimate \(m_2\) is
\[
\text{SNR}_2 = \frac{\|w_2^\top g_2\|^2}{w_2^\top Q_2w_2}, \quad (17)
\]
where
\[
Q_2 = F_2^2 \sigma_2^2 + \sigma_2^2 I. \quad (18)
\]
Similarly, we consider that User 2 estimates \(m_1\) using the received signal \(y_2\) via a linear combining vector \(w_1 \in \mathbb{R}^{N \times 1}\). In pre-processing, User 2 is assumed to subtract its message contribution from \(y_2\) in (12), and obtains \(\hat{y}_2 = y_2 - F_1g_2m_2 = g_1m_1 + (I + F_1F_2)n_1 + F_1n_2\). User 2 then obtains the message estimate \(\hat{m}_1 = w_1^\top \hat{y}_2\) under SNR
\[
\text{SNR}_1 = \frac{\|w_1^\top g_1\|^2}{w_1^\top Q_1w_1}, \quad (19)
\]
where
\[
Q_1 = (I + F_1F_2)(I + F_1F_2)^\top \sigma_1^2 + F_1F_1^\top \sigma_1^2. \quad (20)
\]
Given \(g_1, F_1, g_2, \) and \(F_2\), the optimal combining vector (that minimizes the error probability for message estimation) is obtained by maximizing the SNRs given by (17), (19)
\[
w_i^* = \frac{Q_i^{-1}g_i}{g_i^\top Q_i^{-1}g_i}, \quad i \in \{1, 2\}. \quad (21)
\]
Plugging (21) in (17) and (19), we obtain the SNR as
\[
\text{SNR}_i = g_i^\top Q_i^{-1}g_i, \quad i \in \{1, 2\}. \quad (22)
\]

B. Optimization Formulation for Linear Encoding Schemes

The decoding schemes in (21) are represented as functions of the encoding schemes of the users. Thus, for joint encoding and decoding design, we focus on designing the encoding schemes with the derived form of SNRs in (22). In this work, we minimize the weighted sum of the users’ transmit powers under their SNR constraints. Accordingly, the optimization problem is given by
\[
(P): \min_{g_1, F_1, g_2, F_2} \alpha E[\|x_1\|^2] + (1 - \alpha) E[\|x_2\|^2] \\
\text{s.t.} \quad \text{SNR}_1 = \eta_1, \quad \text{SNR}_2 = \eta_2, \quad (23)
\]
where \(\eta_1, \eta_2 \in \mathbb{R}^+\) are the target SNRs and \(\alpha \in (0, 1)\) is a weighting coefficient.

Remark 1. The equality conditions in (23) are equivalent to inequality constraints \(\text{SNR}_1 \geq \eta_1\) and \(\text{SNR}_2 \geq \eta_2\) in terms of minimizing the objective function of \(P\). This is because if we obtain \(g_1\), such that \(\text{SNR}_1 > \eta_1\), we can always choose \(g_1 = (1 - \epsilon)g_1\) with \(\epsilon \in (0, 1)\) under which \(\text{SNR}_1 = g_1^\top Q_1^{-1}g_1 = \eta_1\).

This choice of \(g_1\) will yield a smaller transmit power of the users in (15) and (16), since \(\|g_1\|^2 < \|g_1\|^2\) and \(\|F_2g_1\|^2 < \|F_2g_1\|^2\). The same holds for the value of \(\text{SNR}_2\).

In general, at time \(k \geq 2\), User \(i\) feeds back a linear combination of the previously received signals up to time \(k - 1\), i.e., \(y_2[\tau] = \sum_{\tau = 1}^{k - 1} F_2[\tau]y_2[\tau], \) where \(i \in \{1, 2\}\). This implies that the initially received signals at the users are repetitively fed back to the other over a total of \(N\) channel uses, e.g., the information of \(y_2[1]\) at User 2 is fed back to User 1 over \(N - 1\) times.

This repetitive feedback in both ways would make the design of the encoding schemes more complicated because the encoding schemes of the users are coupled. To mitigate the complexity of designing the encoding schemes, we assume that User 2 only feeds back the recently received signal of \(y_2\) in (8), i.e., \(F_2\) is in the form of
\[
F_2 = \begin{bmatrix}
0 & 0 & 0 & \ldots & 0 \\
0 & 0 & 0 & \ldots & 0 \\
\vdots & \vdots & \ddots & \ddots & \vdots \\
0 & 0 & \ldots & 0 & 0
\end{bmatrix} \in \mathbb{R}^{N \times N}. \quad (24)
\]
First, we investigate the solution behavior for the feedback of User 2. Specifically, we reveal that it is optimal for User 2 not to utilize the last channel use for feeding back the previous received signals to User 1, i.e., \(f_{2,N} = 0\), for arbitrary encoding schemes.

Proposition 1. In the problem \(P\) with \(F_2\) in the form of (24), it is optimal that \(f_{2,N} = 0\).

Proof. We let \((g_1, F_1, g_2, F_2)\) be any feasible solution to \(P\). We also let \(F_2\) be equal to \(F_2\), except that the last entry of \(F_2\) is zero, i.e., \(f_{2,N} = 0\). We will show that (i) the solution \((g_1, \ldots, g_2, F_2, F_2, \ldots)\) is a feasible solution to \(P\) (ii) the achieved value of \(E[\|x_1\|^2] + (1 - \alpha) E[\|x_2\|^2]\) for \((g_1, F_1, g_2, F_2)\) is less than or equal to the achieved value of \(E[\|x_1\|^2] + (1 - \alpha) E[\|x_2\|^2]\) for \((g_1, F_1, g_2, F_2, F_2, \ldots)\). We will illustrate our proof with Example 1 and then generalize it for arbitrary \(F_2\).
F₁, g₂, F₂) is a feasible solution where g₂ = (1 − ε)g₂ with some ε ∈ [0, 1), and (ii) the solution (g₁, F₁, g₂, F₂) results in an objective value smaller than or equal to that with (g₁, F₁, g₂, F₂).

We will show the first statement (i). Since (g₁, F₁, g₂, F₂) is a feasible solution, it satisfies the constraints for SNR₁ and SNR₂ in (23). First, for SNR₂, using (22) and (18), we get

\[
\text{SNR}_2 = \eta_2 = g_2^T (F_2 F_2^T \sigma_1^2 + \sigma_2^2 I)^{-1} g_2 \\
\leq g_2^T (F_2 F_2^T \sigma_1^2 + \sigma_2^2 I)^{-1} g_2. \tag{25}
\]

In (25), we can always choose g₂ = (1 − ε)g₂ with ε ∈ [0, 1) that satisfies g₂^T (F₂ F₂^T σ₁^2 + σ₂^2 I)^−1 g₂ = η₂. This implies that (g₁, F₁, g₂, F₂) satisfies the constraint for SNR₂. The constraint for SNR₁ is also satisfied with (g₁, F₁, g₂, F₂) since SNR₁ relies on Q₁ in (20) and we have F₁F₂ = F₁F₂. Therefore, (g₁, F₁, g₂, F₂) is a feasible solution to \(\mathcal{P}\).

We then will show the second statement (ii). First, (g₁, F₁, g₂, F₂) yields a smaller or an equal transmit power of \(E[\|x_2\|^2]\) since

\[
E[\|x_2\|^2] = \|g_2 + (1 − \alpha)\|1 + F_2 g_2\|^2 \\
+ \|F_2 (I + F_2 F_1)\|1^2 \sigma_1^2 + \|F_2 F_1\|F^2 \sigma_2^2 \\
\geq \|g_2 + (1 − \alpha)\|1^2 \sigma_1^2 + \|F_2 g_2\|^2 \\
+ \|F_2 (I + F_2 F_1)\|F^2 \sigma_1^2 + \|F_2 F_1\|F^2 \sigma_2^2. \tag{26}
\]

Note that \(E[\|x_1\|^2]\) in (15) are not dependent on \(f_{2,N}\) since \(F₁F₂\) does not include \(f_{2,N}\). Therefore, when \(f_{2,N} = 0\), we can always obtain a smaller or an equal objective value of \(\mathcal{P}\), while satisfying the constraints in (23).

We next look into the solution behavior of the message encoding vector for User 2, g₂. To this end, we first formulate the optimization problem \(\mathcal{P}\) only with respect to g₂, given by

\[
\begin{align*}
\min_{g_2} & \quad \alpha\|F_1 g_2\|^2 + (1 − \alpha)\|I + F_2 F_1\|g_2\|^2 \\
\text{s.t.} & \quad g_2^T Q_2 g_2 = \eta_2. \tag{27}
\end{align*}
\]

Defining \(q_2 = Q_2^{-1/2} g_2\) where \(Q_2 = (Q_2^{1/2})^2\), we write an equivalent optimization problem as

\[
\begin{align*}
\min_{q_2} & \quad q_2^T B q_2 \\
\text{s.t.} & \quad \|q_2\|^2 = \eta_2, \tag{28}
\end{align*}
\]

where \(B = \alpha Q_2^{-1/2} F_1^T F_1 Q_2^{-1/2} + (1 − \alpha) Q_2^{-1/2} (I + F_2 F_1)^T (I + F_2 F_1) Q_2^{-1/2}. \tag{29}\)

We then introduce our conjecture on the objective function value of (28), based on which we find the optimal solution for g₂ in (27).

**Conjecture 1.** For any \(F_1\) and \(F_2\) (in the form of (24)),

\[
\min\{\alpha \sigma_1^2, (1 − \alpha) \sigma_2^2\} \leq \nu_{\min}[B] \leq (1 − \alpha) \sigma_2^2. \tag{30}\]

1If we conduct the singular value decomposition on \(Q_2\), we have \(Q_2 = U \Sigma U^\top\) and obtain \(Q_2^{1/2} = U \Sigma^{1/2} U^\top\).

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**Proof for \(N = 3\).** We note that \(\min\{\alpha \sigma_1^2, (1 − \alpha) \sigma_2^2\} \leq (1 − \alpha) \sigma_2^2\) for any \(\alpha \in (0, 1)\). In the special case with \(N = 3\), we will show that \(\nu_{\min}[B] = (1 − \alpha) \sigma_2^2\) for any \(F_1\) and \(F_2\) (in the form of (24)). We first rewrite \(B = (1 − \alpha) \sigma_2^2 I + C\) where \(C = (1 − \alpha) \sigma_2^2 F_2 F_1^T + Q_2^{-1/2} (\alpha F_1^T F_1 + (1 − \alpha) (F_2 F_1 + F_1^T F_2 F_2 F_1) + F_2^T F_2 F_2 F_1) Q_2^{-1/2}\). Then, showing \(\nu_{\min}[B] = (1 − \alpha) \sigma_2^2\) is equivalent to showing \(\nu_{\min}[C] = 0\). Using (i) \(Q_2^{1/2} = \text{diag}(\rho_1, \sqrt{\sigma_2^2 + f_{2,2} \sigma_1^2}, 0)/\sqrt{f_{2,2}}\) from (17) where \(f_{2,2} = 0\) from Proposition [1](ii) \(F_1^T J_i = f_{1,i} I_i\) for \(1 \leq i < 2, 3\) while other entries are zeros, and (iii) \(F_2 F_1 = 0\) due to \(f_{2,2} = 0\), we have

\[
C = \begin{bmatrix}
c_{11} & c_{12} & 0 \\
c_{21} & c_{22} & 0 \\
0 & 0 & 0
\end{bmatrix},
\]

where

\[
c_{11} = \alpha \sigma_2^2 (f_{1,2,1} + f_{1,3,1}), \tag{31}\]

\[
c_{12} = \alpha \sigma_2 \sqrt{\sigma_2^2 + f_{2,2} \sigma_1^2} f_{1,1,3}, \tag{32}\]

\[
c_{21} = \alpha \sigma_2 \sqrt{\sigma_2^2 + f_{2,2} \sigma_1^2} f_{1,3,1}, \tag{33}\]

\[
c_{22} = (1 − \alpha) \sigma_2^2 f_{2,2} + \alpha (\sigma_2^2 + f_{2,2} \sigma_1^2) f_{1,3,3}. \tag{34}\]

We can easily show that, for any \(F_1\) and \(F_2\), all the principal minors of \(C\) (i.e., the determinants of the principal matrices) are non-negative, which proves that \(C\) is positive semi-definite.

We then have \(\nu_{\min}[C] = 0\), which leads to \(\nu_{\min}[B] = (1 − \alpha) \sigma_2^2\).

We note that, for any \(N\), any example that violates the above conjecture has not been observed from the extensive numerical simulations where \(F_1\) and \(F_2\) are randomly generated.

**Proposition 2.** If Conjecture 1 is true, \(g_2 = [0, ..., 0, \sqrt{\eta_2} \sigma_2^2]^\top\) is optimal in \(\mathcal{P}\) when 
\(\alpha \geq \frac{\sigma_2^2}{\sigma_1^2 + \sigma_2^2}\).

**Proof.** We have a lower bound of the objective function in (28) as \(q_2^B q_2 \geq \nu_{\min}[B] \|q_2\|^2\). From Conjecture 1 we have \(\nu_{\min}[B] = (1 − \alpha) \sigma_2^2\) when \(\alpha \geq \frac{\sigma_2^2}{\sigma_1^2 + \sigma_2^2}\). Then, we have the lower bound as \(q_2^B q_2 \geq (1 − \alpha) \sigma_2^2 \|q_2\|^2\). Here, \(q_2 = [0, ..., 0, \sqrt{\eta_2} \sigma_2^2]^\top\) satisfies the lower bound with \(\|q_2\|^2 = \eta_2\), which can be easily shown by the fact that all the entries in the last column and row of \(B\) are zeros except the last diagonal entry is \(1 − \alpha \sigma_2^2\) due to \(f_{2,N} = 0\) from Proposition [1] in other words, \(q_2^*\) is an optimal solution of (28). We then have the optimal solution for (27) as \(g_2^* = Q_2^{1/2} q_2^* = [0, ..., 0, \sqrt{\eta_2} \sigma_2^2]^\top\), since \(f_{2,N} = 0\) from Proposition 1.

The result of Proposition 2 shows that it is optimal for User 2 to transmit the message only over the last channel use when the weight coefficient in (23) shows \(\alpha \geq \frac{\sigma_2^2}{\sigma_1^2 + \sigma_2^2}\).

Using Propositions 1 and 2, we next aim to simplify our optimization problem \(\mathcal{P}\). In our optimization, we consider the case with \(\alpha \geq \frac{\sigma_2^2}{\sigma_1^2 + \sigma_2^2}\). From Proposition 2 we have \(g_2 = [0, ..., 0, \sqrt{\eta_2} \sigma_2^2]^\top\) as an optimal solution, which always satisfies
SNR$_2 = \eta_2$ regardless of other variables. Thus, we can remove the dependency of the constraint for SNR$_2$ in $\mathcal{P}$. Further, to make $\mathcal{P}$ more tractable, we define $q_1 = Q_1^{-1/2}g_1$ where $Q_1 = (Q_1^{1/2})^2$, which implies SNR$_1 = ||q_1||^2$ and $||g_1||^2 = q_1^\top Q_1 q_1$. Consequently, we rewrite the transmit powers in $\mathcal{P}$ and $\mathcal{Q}$ as

$$
E[||x_1||^2] = q_1^\top Q_1 q_1 + ||F_1 F_2||^2_2 \sigma_1^2 + ||F_1||^2_2 \sigma_2^2
$$

$$
= q_1^2 ([I + F_1 F_2]^2 \sigma_1^2 + [I + F_1 F_2] \sigma_2^2) + ||F_2 F_1||^2_2 \sigma_1^2 + ||F_1||^2_2 \sigma_2^2
$$

Finally, we simplify our optimization $\mathcal{P}$ as

$$
(\tilde{\mathcal{P}}) : \min_{q_1 \in \mathbb{Q}_1, F_2} \quad \alpha E[||x_1||^2] + (1 - \alpha) E[||x_2||^2]
$$

s.t. \quad ||q_1||^2 = \eta_1.

IV. ITERATIVE TWO-WAY OPTIMIZATION FOR LINEAR ENCODING SCHEMES IN GTWC

To solve the optimization problem $\tilde{\mathcal{P}}$, we divide it into two sub-problems, and solve them alternately through a series of iterations. The first sub-problem is to solve $\mathcal{P}$ for $q_1$ and $F_1$ given that $F_2$ is fixed, and the second sub-problem is to solve for $F_2$ assuming $q_1$ and $F_1$ are fixed.

A. First sub-problem for obtaining $q_1$ and $F_1$

We assume a fixed value for $F_2$. We first show that $E[||x_2||^2]$ is upper bounded by sum of the scaled version of $E[||x_1||^2]$ and some constant terms as follows:

$$
E[||x_2||^2] \leq ||g_2||^2 + ||F_2 Q_1^{1/2} q_1||^2 + ||F_2||^2_2 \sigma_1^2
$$

$$
+ ||F_2 F_1||^2_2 \sigma_1^2 + ||F_1||^2_2 \sigma_2^2
$$

$$
= ||g_2||^2 + ||F_2||^2_2 \sigma_1^2 + f_2^2_{\text{max}} (||Q_1^{1/2} q_1||^2 + ||F_2||^2_2 + ||F_1||^2_2)
$$

$$
= ||g_2||^2 + ||F_2||^2_2 \sigma_1^2 + f_2^2_{\text{max}} E[||x_1||^2],
$$

where $f_2^2_{\text{max}} = \max_{i=2,\ldots,N-1} f_{2,i}^2$. We use the fact that $\text{tr}(F_2 F_1 F_2 F_1^\top) = 0$ to obtain the equality $(i)$ in (34).

In the first sub-problem, instead of solving $\tilde{\mathcal{P}}$ directly, we aim to minimize the upper bound of the objective function of $\mathcal{P}$ in (35). Since the other terms in (35) are constants except for $E[||x_1||^2]$, the first sub-problem is reduced to

$$
(\tilde{\mathcal{P}}_1) : \min_{q_1 \in \mathbb{Q}_1, F_1} \quad E[||x_1||^2]
$$

s.t. \quad ||q_1||^2 = \eta_1.

We will solve $\tilde{\mathcal{P}}_1$ via (i) first obtaining the optimal solution form of $F_1$ in terms of $q_1$, and then (ii) plugging the optimal solution form of $F_1$ in $E[||x_1||^2]$ and solving for $q_1$.

Solving for $F_1$. Note that $F_1 \in \mathbb{R}^{N \times N}$ is a strictly lower triangular matrix given by

$$
F_1 = \begin{bmatrix}
0 & 0 & \cdots & 0 \\
f_{1,2,1} & 0 & \cdots & 0 \\
\vdots & \ddots & \ddots & \vdots \\
0 & \cdots & \cdots & f_{1,N-1,1} \\
f_1 & f_2 & \cdots & 0 \\
\end{bmatrix}
$$

where $f_{1,i} = [f_{1,i+1,1}, f_{1,i+2,1}, \ldots, f_{1,N,1}]^\top \in \mathbb{R}^{(N-1) \times 1}$, $i \in \{1, \ldots, N-1\}$. Considering $q_1 = [q_{1,1}, q_{1,2}, \ldots, q_{1,N}]^\top$, we define the vector that contains a portion of the entries of $q_1$

$$
h_i = [q_{1,i+1}, q_{1,i+2}, \ldots, q_{1,N}]^\top \in \mathbb{R}^{(N-1) \times 1},
$$

where $i \in \{0, \ldots, N-1\}$. With the defined vectors $\{f_{1,i}\}$ and $\{h_i\}$, we can rewrite $E[||x_1||^2]$ in (31) as

$$
E[||x_1||^2] = \sum_{i=1}^{N-1} \Phi_i(f_{1,i}) + \sigma_1^2 ||q_{1,N-1}^i + q_{1,N}^i||^2,
$$

where $\Phi_i(f_{1,i}) = \|h_i^\top f_{1,i}^2 \sigma_1^2 + f_{1,i}^2 \sigma_1^2 + \sigma_2^2 f_{1,i}^2 + f_{1,i}^2 f_{1,i} f_{2,i}^2 ||^2 + \|f_{1,i}^2 \sigma_1^2 + \sigma_2^2 f_{1,i}^2 + f_{1,i}^2 f_{1,i} f_{2,i}^2 ||^2 + \|f_{1,i}^2 \sigma_1^2 + \sigma_2^2 f_{1,i}^2 + f_{1,i}^2 f_{1,i} f_{2,i}^2 ||^2$.

Using (38), our problem of interest (i.e., $\min E[||x_1||^2]$) can be decomposed into $N - 1$ independent problems each in the form of $\Phi_i(f_{1,i})$, $i \in \{1, \ldots, N-1\}$. Since each independent problem is convex with respect to $f_{1,i}$, we find $f_{1,i}$ optimally by solving $\frac{\partial \Phi_i(f_{1,i})}{\partial f_{1,i}} = 0^\top$. Obviously, we have $f_{1,1} = 0$. Also, for $i \in \{2, \ldots, N-1\}$, we need to solve

$$
\frac{\partial \Phi_i(f_{1,i})}{\partial f_{1,i}} = \frac{(q_{1,i-1} + f_{2,i} h_i^\top f_{1,i})^\top h_i^\top f_{2,i} \sigma_1^2 \sigma_2^2}{f_{2,i}^2 \sigma_1^2 + \sigma_2^2} + \sigma_2^2 f_{1,i}^2 (f_{2,i}^2 \sigma_1^2 + \sigma_2^2) = 0^\top.
$$

In order to satisfy the above equality, we need to have

$$
(f_{2,i}^2 \sigma_1^2 + \sigma_2^2)(h_i h_i^\top + 1)f_{1,i} = -q_{1,i-1} f_{2,i} \sigma_1^2 h_i.
$$

Finally, the optimal solution form of $f_{1,i}, i \in \{2, \ldots, N-1\}$, is given in terms of the entries of $q_1$ (encapsulated in $h_i$ according to (37)) by

$$
f_{1,i} = -\frac{q_{1,i-1} f_{2,i} \sigma_1^2}{f_{2,i}^2 \sigma_1^2 + \sigma_2^2} (h_i h_i^\top + 1)^{-1} h_i
$$

$$
= -\frac{f_{2,i} \sigma_1^2}{f_{2,i}^2 \sigma_1^2 + \sigma_2^2} \frac{q_{1,i-1}}{1 + ||h_i||^2} h_i.
$$

where the Sherman–Morrison formula is used to obtain equality (i) in (41).
Solving for $q_1$. Putting the optimal solution of $\{f_{i,1}\}_{i=1}^{N-1}$ obtained in (41) back into (38), we get

$$
\mathbb{E}[\|x_1\|^2] = \sum_{i=2}^{N-1} \left[ \frac{f_{i,1}^{2} \sigma_{1}^{2} q_{i,1-1} \|h_i\|^{2}}{f_{i,1}^{2} \sigma_{1}^{2} + \sigma_{2}^{2} (1 + \|h_i\|^{2})} \right]^{2} \sigma_{1}^{2} + \left( \frac{f_{i,1}^{2} \sigma_{1}^{2} q_{i,1-1} \|h_i\|^{2}}{f_{i,1}^{2} \sigma_{1}^{2} + \sigma_{2}^{2} (1 + \|h_i\|^{2})} \right)^{2} \sigma_{2}^{2} + \left( \frac{f_{i,1}^{2} \sigma_{1}^{2} q_{i,1-1} \|h_i\|^{2}}{f_{i,1}^{2} \sigma_{1}^{2} + \sigma_{2}^{2} (1 + \|h_i\|^{2})} \right)^{2} \|h_i\|^2 \left( f_{i,1}^{2} \sigma_{1}^{2} + \sigma_{2}^{2} \right)
+ \left( q_{i,1-N-1}^{2} + q_{i,N}^{2} \right) \sigma_{1}^{2},
$$

and the constraint in (43) as

$$
\|q_1\|^2 = \eta_1.
$$

Then, $\tilde{P}_1$ is reduced to the following optimization problem:

$$
\min_{q_1} \sum_{i=1}^{N-2} \sigma_1^2 q_{i,1} (f_{i,1}^2 \sigma_1^2 + \sigma_2^2 (1 + \|h_i+1\|^2))
+ \left( q_{i,1-N-1}^2 + q_{i,N}^2 \right) \sigma_1^2,
$$

subject to

$$
\|q_1\|^2 = \eta_1.
$$

Defining $x_i = q_{i,1}^2 \geq 0$, we rewrite the objective function in (43) as

$$
\sum_{i=1}^{N-2} \sigma_1^2 q_{i,1} (f_{i,1}^2 \sigma_1^2 + \sigma_2^2 (1 + \|h_i+1\|^2))
+ \left( q_{i,1-N-1}^2 + q_{i,N}^2 \right) \sigma_1^2
= \sigma_1^2 \sum_{i=2}^{N} f_{i,1}^2 x_i
+ \sigma_2^2 \sum_{i=2}^{N} \left( x_{i+1}^2 + \ldots + x_N \right),
$$

and the constraint in (43) as $\sum_{i=1}^{N} x_i = \eta_1$. Using the vector form of $x = [x_1, \ldots, x_N]^T \in \mathbb{R}^{N \times 1}$, we can formulate the equivalent optimization problem as

$$
\minimize_x \sum_{i=1}^{N-1} u_{i}^T x
\text{subject to } 1^T x = \eta_1, \ x \geq 0,
$$

where $1 = [1, \ldots, 1]^T \in \mathbb{R}^{N \times 1}$ and $0 = [0, \ldots, 0]^T \in \mathbb{R}^{N \times 1}$.

In (44), $u_i \in \mathbb{R}^{N \times 1}$ and $m_i \in \mathbb{R}^{N \times 1}$, $i \in \{1, \ldots, N-1\}$, are defined as

$$
u_i = \begin{bmatrix} 0, \ldots, 0, \frac{f_{i,1}^2 \sigma_1^2}{f_{i,1}^2 \sigma_1^2 + \sigma_2^2}, \ldots, 0, 0 \end{bmatrix}^T, \ i \in \{1, \ldots, N-2\},$$

$$
u_{N-1} = \begin{bmatrix} \sigma_1^2 \sigma_2^2, \ldots, \sigma_1^2 \sigma_2^2, \sigma_1^2, \sigma_2^2 \end{bmatrix}^T,$$

$$
u_{1} = \begin{bmatrix} 0, \ldots, 0, 1 \end{bmatrix}^T, \ i \in \{1, \ldots, N-2\},$$

$$
u_{N-1} = \begin{bmatrix} 0, \ldots, 0 \end{bmatrix}^T,$$

where $u_i, m_i \geq 0$. The equivalent optimization problem in (44) is a multi-objective linear fractional programming [11]. We thus can adopt commercial software [12] to solve this problem.

B. Second sub-problem for obtaining $F_2$

While fixing $q_1$ and $F_1$, we formulate the second sub-problem as

$$
(\bar{P}_2) : \min_{F_2} \alpha \mathbb{E}[\|x_1\|^2] + (1 - \alpha) \mathbb{E}[\|x_2\|^2].
$$

We aim to minimize the objective of $\bar{P}_2$ for each $f_{2,i}$, $i \in \{2, \ldots, N-1\}$ by setting the derivative with respect to $f_{2,i}$ equal to zero. Our methodology would yield a sub-optimal solution given the non-triviality of the problem $\bar{P}_2$.

Considering the expression for $\mathbb{E}[\|x_2\|^2]$ in (32), we express each of the terms including $F_2$ as a sum of entries of $F_2$, i.e., $\{f_{2,i}\}_{i=1}^{N-1}$. First, revisiting the second term in (32), we obtain

$$
\|F_2 Q_{1/2} q_1\|^2 = q_{i}^T Q_{1/2} F_2^{T} F_2 Q_{1/2} q_{i}
= p^T F_2^T F_2 p = \sum_{i=2}^{N} p_{i-1}^2 f_{2,i},
$$

where we assumed that $p \equiv Q_{1/2} q_1 = [p_1, \ldots, p_N]^T$ is fixed for tractability although $Q_{1/2}$ depends on $F_2$. We then express the third term in (32) as

$$
\|F_2 (I + F_1 F_2)\|^2 = \sigma_1^2 \sum_{i=2}^{N} f_{2,i}^2 + \sigma_2^2 \sum_{i=2}^{N} \sum_{j=i+1}^{N-1} f_{2,i} f_{2,j}^2 f_{2,j+1}.
$$

Also, the last term in (32) can be expressed as

$$
\|F_2 F_1\|^2 = \sigma_2^2 \sum_{i=3}^{N} f_{2,i}^2 \sum_{j=1}^{i-1} f_{2,j}^2.
$$

Since the derivatives, $\partial \mathbb{E}[\|x_1\|^2] / \partial f_{2,i}$, and $\partial \mathbb{E}[\|x_2\|^2] / \partial f_{2,i}$, can be readily derived from (38) and (32) using (48), respectively, we finally have

$$
\alpha \mathbb{E}[\|x_1\|^2] + (1 - \alpha) \mathbb{E}[\|x_2\|^2]
= 2 \alpha \sigma_1^2 q_{1,i-1} f_{1,i} + c_i f_{2,i},
$$

where

$$
c_i \equiv 2 \alpha \sigma_1^2 \left( \|h_i f_{1,i}\|^2 + \|f_{1,i}\|^2 \right) + 2 (1 - \alpha) \sigma_1^2 + 2 (1 - \alpha) \sigma_1^2 + \sum_{j=i+1}^{N-1} \left( f_{2,i} f_{2,j}^2 f_{2,j+1}^2 + \sum_{k=2}^{i-2} f_{2,i-1-k} f_{2,i}^2 \right)
+ 2 \sigma_2^2 (1 - \alpha) \sum_{j=1}^{i-2} f_{2,j}^2.
$$

By setting the right-hand equation in (49) to be zero, we obtain the solution for $f_{2,i}$ as

$$
f_{2,i} = -\frac{2 \alpha \sigma_1^2 q_{1,i-1} h_i f_{1,i}}{c_i}, \ i \in \{2, \ldots, N-1\}.
$$

The pseudo-code of our iterative method to solve the overall optimization problem $P$ is summarized in Algorithm 1.
Algorithm 1 Iterative Two-Way Optimization for Linear Encoding in Gaussian Two-Way Channels

1: Input. $N$, $\sigma_1^2$, $\sigma_2^2$, $\eta_1$, $\eta_2$, $\alpha$, $\epsilon$
2: Output. $g_1$, $F_1$, $g_2$, $F_2$
3: Obtain the optimal solution for $g_2$ and $f_{2,N}$ as $g_2 = [0, 0, \ldots, 0, \sqrt{\pi} \sigma_2]$ and $f_{2,N} = 0$ from Propositions 1 and 2.
4: Randomly generate $\{f_{2,i}\}_{i=2}^{N-1}$.
5: while $|s_{\text{new}} - s_{\text{old}}| > \epsilon$ do
6:   - **Sub-problem 1. Obtain $g_1$ and $F_1$**
7:      Solve the problem in (44) for $x = [x_1, \ldots, x_N]^\top$ and obtain $g_{1,i} = \sqrt{f_{2,i}}, i \in \{1, \ldots, N\}$
8:      Obtain the columns of $F_1$, $\{f_{1,i}\}_{i=1}^{N-1}$, from (41).
9:      Obtain $g_1 = Q_1^{-\frac{1}{2}} q_1$ where $Q_1$ is given in (20).
10: - **Sub-problem 2. Obtain $F_2$**
11:      while $|\nu_{\text{new}} - \nu_{\text{old}}| > \epsilon$ do
12:         Obtain $f_{2,i}$ sequentially for $i \in \{2, \ldots, N-1\}$ by (23).
13:      Calculate the objective function value $\nu_{\text{new}}$ of (23) with the updated $\{f_{2,i}\}_{i=2}^{N-1}$
14:   end while
15: - **Update values for stopping criterion**
16:     $s_{\text{old}} \leftarrow s_{\text{new}}$
17:     Calculate the objective function value $s_{\text{new}}$ of (23) with the updated $g_1$, $F_1$, and $F_2$
18: end while

V. NUMERICAL EXPERIMENTS

We next present numerical simulations to measure the performance of our proposed two-way optimization scheme. We consider $\sigma_1^2 = 1$, $\sigma_2^2 = 0.5$, and $\eta_1 = \eta_2 = 10$. For our two-way optimization scheme, we consider 30 different initializations of $\{f_{2,i}\}_{i=2}^{N-1}$ with $f_{2,i} \sim \mathcal{U}(0, 1)$, and select the best solution. The threshold for the stopping criterion in Algorithm 1 is $\epsilon = 10^{-3}$. For performance comparisons, we consider two baselines. The first baseline is the open loop scheme where each user only transmits its own message to the others without employing any feedback scheme. In this case, $F_1 = F_2 = 0$, $\|g_1\|^2 = \eta_1 \sigma_1^2$, and $\|g_2\|^2 = \eta_2 \sigma_2^2$. The second baseline is the one-way optimization method that is especially designed for one-way noisy feedback channels\(^2\) for which we consider the optimization scheme proposed in [3].

![Fig. 2: The weighted sum of transmit powers along $\alpha$.](image2)

![Fig. 3: Power profiles for blocklength $N = 7$.](image3)

\(^2\)In two-way channels, two channel uses are needed to receive back the transmit signals at each user, while only a single channel use is needed in one-way channels. Therefore, the feedback scheme for the one-way channels can be applied to the two-way channels by designing the feedback scheme for User 1 over the odd/even-numbered channel uses. For User 2, the message can be transmitted only over the last channel use while the feedback information is conveyed over the even/odd-numbered channel uses without scaling.

In this case, as $\alpha$ increases, the problem $\mathcal{P}$ is more focused on minimizing the transmit power of User 1. In this case, employing the feedback scheme will be beneficial since the feedback scheme allows User 1 to use lower transmit power for satisfying the SNR constraint, while it requires User 2 to use more power for providing the feedback information to User 1. This causes a significant performance enhancement of our method as compared to baselines in Fig. 2 upon having higher values of $\alpha$ ($0.5 \leq \alpha \leq 1$).

Fig. 3 shows the power profiles for the message transmission and the feedback at User 1 and 2 with $N = 7$ and $\alpha = 0.8$, which are obtained by our two-way optimization method. We note that $g_i[k]$ is the value of the $k$-th entry of the message encoding vector $g_i$, $i \in \{1, 2\}$. From the figure, User 1 only uses the 1, 3, 5, 7-th channel uses, while User 2 only uses the 2, 4, 6, 7-th channel uses. In other words, the channel uses do

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Fig. 2: The weighted sum of transmit powers along $\alpha$.

Fig. 3: Power profiles for blocklength $N = 7$. 

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not overlap between User 1 and 2 except the last channel use. It is interesting that we do not put any constraints on the separation of the channel usages between the two users when solving the optimization problem in (23). However, solving the optimization problem results in the separation of the channel usages. It can be also seen that the transmit power of User 1 decreases along the channel uses, which resembles the results of the optimal feedback scheme for one-way noisy feedback channels [5]. User 2 also exhibits diminishing power consumption along the channel uses.

We note that User 2 conveys its message only over the last channel based on Proposition 2. It is worth mentioning that User 2 can split its power for the message transmission over the empty channel uses, i.e., 1, 3, 5-th channel uses while maintaining the same objective function value and satisfying the SNR constraints. This implies that we have multiple optimal solutions for $g_2$ given the non-convex structure of the problem $\mathcal{P}$. Thus, although in our problem $\mathcal{P}$ we are concerned with minimizing the average transmit power over the channel block rather than imposing constraints on the instantaneous transmit powers, we may prefer to distribute the powers of $g_2$ to mitigate the instantaneous power concentration.

Fig. 4 depicts the weighted sum of transmit powers under varying number of channel uses $N$ with $\alpha = 0.8$. Once $N \geq 3$, User 1 can employ the feedback scheme, which decreases the weight sum of powers significantly. For $N \geq 5$, the weighted sum of transmit powers of our method is around 23% lower than the open loop case. Also, having larger number of channel uses, i.e., when $N \geq 5$, result in marginal performance gains. As a future work, it will be interesting to investigate the performance improvement along $N$ when instantaneous power constraints are imposed so that the users avoid to pour most of their transmit powers to a small portion of the channel uses.

VI. CONCLUSION

In this work, we presented a system model for linear coding in Gaussian two-way channels to bridge the gap between the well-developed model for Gaussian one-way channels proposed by Butman [9] and the case of Gaussian two-way channels. We then formulated an optimization problem jointly designing the encoding/decoding schemes for the users and investigated its solution behavior. We then proposed an iterative two-way optimization solver to solve our problem. Through simulations, we showed that our two-way optimization scheme performs better than the non-feedback scheme and the one-way optimization scheme. As a future work, imposing instantaneous transmit power constraints at the users is worth investigating.

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