Dependence in Propositional Logic: Formula-Formula Dependence and Formula Forgetting – Application to Belief Update and Conservative Extension

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Abstract
Dependence is an important concept in artificial intelligence. A task can be executed more efficiently by discarding something independent from the task. In this paper, we propose two novel notions of dependence in propositional logic: formula-formula dependence and formula forgetting. The first is a relation between formulas capturing whether a formula depends on another one, while the second is an operation that returns the strongest consequence independent of a formula. We also apply these two notions in two well-known issues: belief update and conservative extension. Firstly, we define a new update operator based on formula-formula dependence. Furthermore, we reduce conservative extension to formula forgetting.

Introduction
Dependence is an important concept in artificial intelligence (AI). Before performing an intelligent task (e.g., reasoning and planning), it is intuitive to first determine what are irrelevant, and discard them for better efficiency. For example, when a student takes an examination on literature, she does not need to keep the knowledge of mathematics in mind. This process of discarding irrelevant information involves two issues:

1. What is the irrelevant information in the background knowledge base (KB) for the task?
2. How to discard it in the KB?

In the context of propositional logic, various authors (Boutilier 1994; Lakemeyer 1997) studied the first issue by systematically analyzing a dependence relation between a formula and a variable, namely formula-variable dependence (FV-dependence). Loosely speaking, a formula \(\phi\) depends on a variable \(v\) if \(v\) always occur in every formula equivalent to \(\phi\). Further, Lang, Liberatore, and Marquis (2003) pointed out that, in some applications, we are concerned about not only which variable the formula depends on but also the polarity of the variable. To distinguish the case where a formula conveys some information about a literal but no information about its complement, they proposed a more fine-grained notion, namely formula-literal dependence (FL-dependence). For the second issue, variable forgetting is highly related to FV-dependence. It yields the strongest consequence independent of a variable. The intuitive meaning of literal forgetting is similar.

As mentioned in (Darwiche 1997), dependence is not only a philosophical notion but also a pragmatic notion. Over the past years, this notion has been widely used in many fields of AI, including automated reasoning (Levy, Fikes, and Sagiv 1997; Kautz, McAllester, and Selman 1997), knowledge compilation (Bryant 1992; Minato 1993; Darwiche 1997), reasoning about actions (Lin and Reiter 1997), and especially belief change (Zhang and Zhou 2009; Oveisi et al. 2017). Belief update, a type of belief change, studies how an agent modifies her belief base \(\phi\) in the presence of new information \(\psi\) in a dynamically changing environment. Herzig, Lang, and Marquis (2013) suggested that belief update should be based on the notion of dependence, and proposed the dependence-based update scheme that consists of first removing any belief on which the negation of the new information depends, and then adding the new information.

After investigating FL-dependence and literal forgetting, a natural next step is to study two more general notions: formula-formula dependence (FF-dependence) and formula forgetting. This paper is intended to fill this gap. The main contributions are as follows. First of all, we give a formal definition of FF-dependence, which is a dependence relation between formulas. We also provide a model-based characterization result and analyze some properties for FF-dependence. In addition, based on FF-dependence, we introduce formula forgetting as generalizations of literal forgetting. We give various equivalent formulations of this notion, including an axiomatic definition by four postulates, a syntactic definition via conditioning, and a model-theoretic definition. Finally, we apply these two notions in two well-known issues of AI: belief update and conservative extension. Following the dependence-based update scheme, we define an update operator \(\phi_F\) by first forgetting the negation of the new information in the initial belief base, and then conjoining the resulting belief base with the new information. We characterize \(\phi_F\) by a set of postulates and assess it against the well-known KM postulates. We compare it with
other operators from three perspectives including information preservation, computational complexity and empirical results. The comparison shows that \( \mathcal{SF} \) is a suitable alternative to belief update. We finally give the correspondence between conservative extension and formula forgetting. It turns out that the former can be reduced to the latter.

**Preliminaries**

In this section, we first recall some basic concepts of propositional logic, and then present the notions of FL-dependence and literal forgetting. Most contents of the first two subsections originate from (Lang, Liberatore, and Marquis 2003). Finally, we review some background work regarding belief update.

**Propositional logic**

We assume the propositional language \( \mathcal{L} \) is built from a finite set \( P \) of variables, the connectives \( \neg, \lor, \land \) and two logical constants \( \top \) (true) and \( \bot \) (false). We use \( \phi, \psi, \chi \) and \( \xi \) to range over formulas. The notation \( \text{Var}(\phi) \) denotes the set of variables appearing in \( \phi \). A formula is a **trivial** if it is equivalent to \( \top \) or \( \bot \). A **literal** is a variable (positive literal) or a negated one (negative literal). For a **disjunctive normal form (DNF)** is a disjunction of terms. We say that a term \( t \) is in a DNF formula \( \phi \), written \( t \in \phi \), if \( t \) is a disjunct of \( \phi \). For a subset \( X \) of \( P \), a **minterm over** \( X \) is a term where it uses only \( X \) and each variable of \( X \) appears exactly once. For simplify, we omit \( X \) if \( X = P \). We use \( \Omega_X \) to denote the set of minterms over \( X \).

A formula is in **full DNF**, if it is a disjunction of minterms. A formula is in **negation normal form (NNF)**, if \( \neg \) is only applied to variables. It is well-known that every formula can be equivalently transformed into full DNF and NNF. A full DNF formula of \( \phi \) is the disjunction of all minterms entailing \( \phi \). Throughout this paper, we take all variables of \( P \) into consideration, and assume that there is a unique full DNF formula equivalent to \( \phi \). We call it the **full DNF formula of** \( \phi \). An NNF formula of \( \phi \) can be acquired by pushing the negation inwards via De Morgan’s law and eliminating double negation. For convenience, we call the formula generated by the above process the **NNF formula of** \( \phi \).

Let \( \phi \) be an NNF formula. The variable \( x \) in \( \phi \), where \( x \) is not in the scope of \( \neg \), is called an occurrence of a positive literal \( x \) in \( \phi \). The symbols \( \neg x \) in \( \phi \) are called an occurrence of a negative literal \( \neg x \) in \( \phi \). Note that any occurrence of the negative literal \( \neg x \) cannot be considered as an occurrence of its complement \( x \). A simple example is that the formula \( \neg x \) contains no occurrence of \( x \).

A **interpretation** is a subset of \( P \). A model of \( \phi \) is an interpretation satisfying \( \phi \), and \( [\phi] \) denotes the set of models of \( \phi \). A formula \( \phi \) is **satisfiable**, if there is a model of \( \phi \). A satisfiable term is a term satisfied by at least one interpretation. In other words, it does not contain positive and negative literals of the same variable simultaneously. The following is an operation on an interpretation w.r.t. a satisfiable term.

**Definition 1.** Let \( \omega \) be an interpretation and \( t \) a satisfiable term. Forcing \( \omega \) on \( t \), written \( \omega \rightarrow t \), is defined as \( (\omega \setminus \text{Var}(t)) \cup \{ x \mid x \in P \text{ and } t \models x \} \).

Both \( \omega \) and \( \omega \rightarrow t \) agree on the valuations of all variables except those of \( \text{Var}(t) \). The latter is the model of \( t \) that is the closest to \( \omega \). For instance, let \( \omega = \{ a, b \} \) and \( t = \bar{a} \land c \), then \( \omega \rightarrow t = \{ b, c \} \).

**Formula-liter al dependence and literal forgetting**

The main intuition FL-dependence aims to capture is that the literal \( l \) is an indispensable part of the formula \( \phi \); roughly speaking, every NNF formula equivalent to \( \phi \) contains the occurrence of \( l \).

**Definition 2.** Let \( \phi \) be a formula and \( l \) a literal. We say \( \phi \) is **Lit-dependent** on \( l \), written \( l \rightarrow_{\text{FL}} \phi \), if every NNF formula equivalent to \( \phi \) contains the occurrence of \( l \). Otherwise, \( \phi \) is **Lit-independent** from \( l \), written \( l \nrightarrow_{\text{FL}} \phi \).

**Example 1.** Let \( \phi = \neg(a \land \neg b) \land (b \lor \neg b) \), and \( \psi = \neg a \lor b \). It is obvious that \( \psi \) is an NNF formula equivalent to \( \phi \), and does not contain \( \neg b \). Hence neither \( \phi \) nor \( \psi \) depends on \( \neg b \).

Although Definition 2 is a syntactic formulation of FL-dependence, it is syntax-independent.

**Proposition 1.** Let \( \phi \) and \( \phi' \) be formulas where \( \phi \equiv \phi' \), and \( l \) a literal. Then, \( l \rightarrow_{\text{FL}} \phi \) if and only if \( l \rightarrow_{\text{FL}} \phi' \).

The notion of FV-dependence can be easily defined from that of FL-dependence.

**Definition 3.** Let \( \phi \) be a formula and \( x \) a variable. We say \( \phi \) is **Var-dependent** on \( x \), written \( x \rightarrow_{V} \phi \), if \( x \rightarrow_{L} \phi \) or \( \bar{x} \rightarrow_{L} \phi \).

We also say \( x \) is a dependent variable of \( \phi \), if \( x \rightarrow_{V} \phi \). We use \( \text{DepLit}(\phi) \) (resp. \( \text{DepVar}(\phi) \)) to denote the set of dependent literals (resp. variables) of \( \phi \).

We hereafter present the notion of literal forgetting. We first introduce **term conditioning** (Darwiche 1998) that is an important syntactic operation for literal forgetting.

**Definition 4.** Let \( \phi \) be a formula and \( t \) a satisfiable term. The **conditioning** of \( \phi \) on \( t \), written \( \phi | t \), is defined by substituting each variable \( x \) of \( \phi \) by \( \top \) (resp. \( \bot \)) if \( x \) (resp. \( \bar{x} \)) is a positive (resp. negative) literal of \( t \).

For instance, conditioning \((a \land \neg b) \lor (b \land c) \) on \( \bar{a} \lor b \) gives a formula \((\bot \land \neg a) \lor (b \land \bot) \), which is equivalent to \( c \).

According to the Shannon expansion (Shannon 1938), any formula \( \phi \) can be decomposed into \((l \land \phi_l) \cup (l \land \phi_{\bar{l}})\). From the syntactic point of view, forgetting \( l \) just removes the occurrence of \( l \) from the expansion. The notion of literal forgetting can be defined in a syntactic way via conditioning.

**Definition 5.** Let \( \phi \) be a formula and \( l \) a literal. The result of forgetting \( l \) in \( \phi \), written \( \exists_{l} \phi \), is defined as \( \phi | \top \lor (l \land \phi_{\bar{l}}) \).

For example, \( \exists_{l} \phi \equiv [(a \land b) \lor (\bar{a} \land c) \lor (\bot \land \neg a) \lor (a \land (\bot \land \neg c)) \lor (a \land (\bot \land \neg c)) \lor (b \lor (a \land c)) \lor (\bot \land (a \land c)) \lor (b \lor (\neg a \land c)) \lor (b \lor (\neg a \land c)) \lor (b \lor (\neg a \land c)) \lor (b \lor (\neg a \land c)) \).

One of key propositions of literal forgetting is as follows: Forgetting a literal \( l \) generates the strongest consequence that does not depend on \( l \).

**Proposition 2.** Let \( \phi \) be a formula and \( l \) a literal. \( \exists_{l} \phi \) is the strongest consequence of \( \phi \) that is Lit-independent of \( l \).
Forgetting a single literal can be extended to a variable, a set of literals or variables. Forgetting a variable \( x \) is defined by forgetting the positive literal \( x \) and the negative one \( \bar{x} \) sequentially. As the order in which literals of \( L \) are handled does not matter, forgetting a set \( L \) of literals can be sequentially computed by forgetting a single literal \( l \) of \( L \) one by one. The operation of forgetting a set of variables is similar.

**Definition 6.** Let \( L \) be a set of literals, \( X \) a set of variables, \( l \in L \) and \( x \in X \).

- \( \exists y \forall x. \phi = \exists y \bar{x}. (\exists y x. \phi) \);  
- \( \exists l L. \phi = \exists l \{ l \}. (\exists l L. \phi) \);  
- \( \exists y X. \phi = \exists y (X \\setminus \{ x \}). (\exists y x. \phi) \).

Note that if \( L = \emptyset \) (resp. \( X = \emptyset \)), we let \( \exists L. \phi = \phi \) (resp. \( \exists X. \phi = \phi \)).

Finally, we establish the link between term conditioning and variable forgetting. The conditioning of \( \phi \) on \( t \) can be computed via forgetting all dependent variables of \( t \) in \( \phi \wedge t \).

**Proposition 3.** Let \( \phi \) be a formula and \( t \) a satisfiable term. Then, \( \phi|_t \equiv \exists y \text{DepVar}(t). (\phi \wedge t) \).

**Belief update**

Belief update focuses on the evolution of the belief base in line with the new information, reflecting the modification of the world. Based on the principle of minimal change, Katsuno and Mendelzon (1991) proposed the KM postulates to capture rational belief update operators, which map the initial belief base \( \phi \) and the new information \( \psi \) to a new belief base \( \phi \ast \psi \). The postulates are as follows:

\[
\begin{align*}
\text{U1} & \quad \phi \ast \psi \models \psi; \\
\text{U2} & \quad \text{If } \phi \models \psi, \text{ then } \phi \ast \psi \equiv \phi; \\
\text{U3} & \quad \text{If } \phi \text{ and } \psi \text{ are satisfiable, then } \phi \ast \psi \text{ is also satisfiable; } \\
\text{U4} & \quad \text{If } \phi \equiv \phi' \text{ and } \psi \equiv \psi', \text{ then } \phi \ast \psi \equiv \phi' \ast \psi'; \\
\text{U5} & \quad (\phi \ast \psi) \land \eta \models \phi \ast (\psi \land \eta); \\
\text{U6} & \quad \text{If } \phi \ast \psi \equiv \psi' \text{ and } \phi \ast \psi' \models \psi', \text{ then } \phi \ast \psi \equiv \phi \ast \psi'; \\
\text{U7} & \quad \text{If } \phi \text{ is a minterm, then } (\phi \odot \psi) \land (\phi \odot \psi') \models \phi \ast (\psi \lor \psi'); \\
\text{U8} & \quad (\phi \lor \phi') \ast \psi \equiv (\phi \ast \psi) \lor (\phi' \ast \psi).
\end{align*}
\]

According to the postulate (U8), the new belief base \( \phi \ast \psi \) collects the updates of each model of \( \phi \) by \( \psi \). More formally,

\[
[\phi \ast \psi] = \bigcup_{\omega \in [\phi]} [\omega \odot \psi].
\]

**Formula-formula dependence**

In this section, we introduce the notion of FF-dependence. We first extend the notion of occurrence of literals to that of arbitrary formulas. We then define the notion of FF-dependence in terms of occurrence. We further give a model-theoretical characterization of FF-dependence. Finally, some properties of FF-dependence are given.

Recall that the definition of FL-dependence (cf. Definition 2) says that a formula \( \phi \) is Lit-dependent on a literal \( l \) if every NNF formula equivalent to \( \phi \) contains the occurrence of \( l \). It is hard to extend this definition to FF-dependence. We therefore resort to another equivalent definition: \( \phi \) does not depend on \( l \) if substituting every occurrence of \( l \) in the NNF formula of \( \phi \) with \( \top \) leads to a logically different formula.

This definition cannot be directly transferred to the notion of FF-dependence. It is possible that \( \phi \) depends on \( \psi \) but the latter does not explicitly occur in the former even if both \( \phi \) and \( \psi \) are in NNF. For example, consider the two equivalent formulas \( \phi = \bar{a} \lor b \) and \( \psi = (\bar{a} \lor b) \land (b \lor \bar{b}) \). Because \( \phi \) appears in itself, so replacing \( \phi \) in itself by \( \top \) results in \( \top \). We get that \( \top \not\equiv \phi \), and hence \( \phi \) depends on itself. Based on the principle of syntax-independence, \( \phi \) should depend
on $\psi$. However, replacing all occurrences of $\psi$ in $\phi$ does not modify $\phi$ since $\psi$ does not explicitly occur in $\phi$. We obtain that $\phi$ does not depend on $\psi$.

To define the notion of FF-dependence, we need to solve two problems:

1. Which normal form is suitable for the notion of FF-dependence?
2. How to define the occurrence of a formula in the normal form of another formula?

For the first problem, we choose full DNF instead of NNF. In the following, we introduce the notion of occurrence of a formula in the full DNF of another formula. This notion should obey two principles: syntax-independence and self-elimination. Suppose that two formulas $\phi$ and $\phi'$ are equivalent. The former requires that “given a full DNF formula $\psi$, the occurrence of $\phi$ in $\psi$ is also that of $\phi'$ in $\psi$”. The latter means that “if $\phi'$ is in full DNF, then replacing the occurrence of $\phi$ in $\phi'$ with $T$ results in $\psi$”. To illustrate the definition of occurrence, it is necessary to define the notion of dependent minterms.

**Definition 7.** We say a term $t$ is a dependent minterm of $\phi$, if $t$ is a minterm over $\text{DepVar}(\phi)$ and $t \models \phi$.

We use $\Omega_\phi$ to denote the set of dependent minterms of $\phi$. We also let $\Omega_\phi$ be empty if $\phi \equiv \top$, and $\Omega_\phi = \{T\}$ if $\phi \equiv T$. Clearly, the disjunction of $\Omega_\phi$ is equivalent to $\phi$.

**Example 2.** Let $\psi = (a \lor b) \land (c \lor \overline{c})$. The sets of dependent variables and dependent minterms of $\psi$ are as follows:

$\text{DepVar}(\psi) = \{a, b\}$ and $\Omega_\psi = \{a \lor b, a \land b, \overline{a} \land b\}$. Neither $\overline{a} \land b \land c$ nor $a \land b$ is a dependent minterm of $\psi$ since the former contains the variable $c$ not in $\text{DepVar}(\phi)$, and the latter does not entail $\phi$.

We hereafter give a definition of occurrence. We first consider a simple case that is the occurrence of a term in a minterm.

**Definition 8.** Let $t$ be a term and $t'$ be a minterm. We say a literal $l$ of $t'$ is an occurrence of $t$ in $t'$, if $l$ is an occurrence of $t$ and $t' \models t$.

**Example 3.** Consider three terms $t_1 = a \land \overline{b}$, $t_2 = a \land b$, and $t_3 = a \land b \land c$. The literals $a$ and $b$ are occurrences of $t_1$ in $t'$. But neither of them is an occurrence of $t_2$ in $t'$ since $t' \not\models t_2$. Moreover, $t'$ contains no occurrence of $t_2$.

The notion of occurrence of a formula $\phi$ in a full DNF formula $\psi$ can be defined as that of every dependent minterm of $\psi$ in every disjunct of $\phi$.

**Definition 9.** Let $\phi$ and $\psi$ be two formulas where $\phi$ is in full DNF. Let $t'$ be a minterm of $\phi$, and $l$ a literal of $t'$. We say the occurrence of $l$ in $\phi$ is an occurrence of $\psi$ in $\phi$, if there is a dependent minterm $t$ of $\psi$ s.t. $l$ is an occurrence of $t$ in $t'$.

Since two equivalent formulas have the same set of dependent minterms, Definition 10 satisfies syntax-independence. It is easily verified that Definition 11 satisfies self-elimination.

**Example 4.** Continued with Example 1, we have $\psi = (a \lor b) \land (c \lor \overline{c})$ and $\Omega_\psi = \{a \land b, a \land \overline{b}, \overline{a} \land b\}$. Consider the full DNF formula $\phi = (a \land \overline{b} \land c) \lor (a \land b \land c) \lor (a \land \overline{b} \land c) \lor (a \land b \land c)$.

The occurrences of $a$ and $b$ in the first term $a \land \overline{b} \land c$ of $\phi$ are that of $\psi$ in $\phi$. So are the occurrences of $a$ and $b$ in the second term. However, the occurrences of $a$ and $b$ in the third and fourth disjuncts are not since no dependent minterm of $\psi$ satisfies the condition of Definition 10.

We now are ready to define the notion of FF-dependence.

**Definition 10.** We say $\phi$ is Fml-dependent on $\psi$, written $\psi \mapsto_F \phi$, if substituting every occurrence of $\psi$ in the full DNF formula of $\phi$ with $T$ leads to another formula that is not equivalent to $\phi$. Otherwise, $\phi$ is Fml-independent from $\psi$, written $\psi \not\mapsto_F \phi$.

We illustrate Definition 10 with the following example.

**Example 5.** Continued with Example 2, we have $\psi = (a \lor b) \land (c \lor \overline{c})$. Let $\psi' = (a \lor b) \land (a \land c) \lor (b \land c)$. It is easily verified that $\phi = \psi'$. Replacing every occurrence of $\psi$ in $\phi$ with $T$ results in a formula $(T \land T \land c) \land (T \land T \land b) \land (T \land \overline{b} \land c) \lor (a \land \overline{b} \land c) \lor (a \land b \land c) \lor (a \land b \land \overline{c})$. Clearly, this formula is not equivalent to $\phi$. Hence, both $\phi$ and $\psi'$ depend on $\psi$.

Definition 10 is a simple approach to define the notion of FF-dependence. To capture this notion comprehensively, we present a model-theoretic characterization.

**Proposition 4.** Let $\phi$ and $\psi$ be formulas, and $X = \text{DepVar}(\psi)$. Then, $\phi$ is Fml-dependent on $\psi$ if there exist an interpretation $\omega$ and two terms $t \in \Omega_{\phi}$ and $t' \in \Omega_{\phi} \setminus \{t\}$ s.t. $\omega \models \phi \land t$ and $\omega \models t' \not\models \phi$.

This proposition means that $\phi$ depends on $\psi$, if there exist an interpretation $\omega$ and a dependent minterm $t$ of $\psi$ such that (1) $\omega \models \phi \land t$; and (2) $t$ is essential for $\omega$ to satisfy $\phi$, i.e., there is a minterm $t'$ over $\text{DepVar}(\psi)$ such that forcing $\omega$ on $t'$ no longer satisfies $\phi$.

Next, we continue Example 5 to illustrate Proposition 4.

**Example 6.** We have $\psi' = (a \land \overline{b}) \lor (\overline{a} \land c) \lor (b \land \overline{c})$, $\psi = (a \lor b) \land (c \lor \overline{c})$, and $\Omega_{\psi} = \{a \land b, a \land \overline{b}, \overline{a} \land b\}$. Then, we let $\omega = \{a, c\}$, $t = a \land b$ and $t' = a \land \overline{b}$. Clearly, $t \in \Omega_{\phi}$, $t' \in \Omega_{\phi} \setminus \{t\}$ and $\omega \models \phi \land t$. Thus, $\omega \models t' = \{a, b, c\}$ that does not satisfy $\phi$. So $\phi$ depends on $\psi$.

Finally, we analyze some properties of FF-dependence. It is obvious that a formula is Fml-dependent on a literal if and only if the former is Lit-dependent on the latter.

**Proposition 5.** Let $\phi$ be a formula and $l$ be a literal. Then $l \mapsto_L \phi$ iff $l \mapsto_F \phi$.

FF-dependence satisfies syntax-independence, symmetry and almost reflexivity (i.e., every non-trivial formula depends on itself). Trivial formulas do not depend on any formula.

**Proposition 6.**

- Syntax-independence: $\phi \mapsto_F \psi$ iff $\phi' \mapsto_F \psi'$ when $\phi \equiv \phi'$ and $\psi \equiv \psi'$.
- Symmetry: $\phi \mapsto_F \psi$ iff $\psi \mapsto_F \phi$.
- Almost reflexivity: $\phi \mapsto_F \phi$ when $\phi$ is not trivial.
- For any formula $\phi$, $\phi \not\mapsto_F \top$ and $\phi \not\mapsto_F \bot$.

We analyze the computational complexity of FF-dependence as follows:
Proposition 7. FF-dependence is in $\Delta^0_2$ and NP-hard.

Proof. Upper bound: First, we compute $\text{DepVar}(\psi)$ by calling an NP oracle that decides whether $\psi$ depends on $v$ for each variable of $\psi$. Further, we guess an interpretation $\omega$ and two terms $t$ and $t'$, and then check whether they satisfy the condition of Proposition 4. The whole procedure calls NP oracles $n + 1$ times where $n$ is the number of $P(\psi)$. So, FF-dependence is in $\Delta^0_2$.

Lower bound: By Proposition 5, FL-dependence is a restriction of FF-dependence. The complexity of FL-dependence is NP-complete (Lang, Liberatore, and Marquis 2003). Hence, FF-dependence is NP-hard.

Formula forgetting

In the previous section, we investigate the notion of FF-dependence. Following this notion, we study the notion of formula forgetting in this section. We first propose a set of postulates that precisely characterize the notion of formula forgetting. We then discuss some properties of formula forgetting. Finally, the computation and model-theoretic characterization of formula forgetting are also studied.

Zhang and Zhou (2009) proposed four postulates (W), (IR), (PP) and (NP) for variable forgetting in modal logic S5. We extend these postulates to formula forgetting in propositional logic.

Definition 11. We say $\psi$ is a result of forgetting $\eta$ in $\phi$, if it satisfies the following postulates:

1. W Weakening: $\phi \models \psi$;
2. IR Independence: $\eta \not\models_F \psi$;
3. PP Positive Persistence: for any formula $\xi$, if $\eta \not\models_F \xi$ and $\phi \models \xi$, then $\psi \models \xi$;
4. NP Negative Persistence: for any formula $\xi$, if $\eta \not\models_F \xi$ and $\phi \not\models \xi$, then $\psi \not\models \xi$.

Postulate (W) says that forgetting weakens the original formula. Postulate (IR) requires that after forgetting, the resulting formula should be irrelevant to the formula which we have forgotten. Finally, postulates (PP) and (NP) viewed together state that forgetting $\eta$ does not affect entailment of queries that are $\text{Fml}$-independent from $\eta$.

Similarly to literal forgetting, the result of formula forgetting is unique up to logical equivalence. We use $\exists_F \psi. \phi$ to denote the result of forgetting $\psi$ in $\phi$.

The following proposition reflects strong relationships between formula forgetting and FF-dependence: Forgetting $\psi$ in $\phi$ does not change $\phi$ if and only if $\phi$ does not depend on $\psi$.

Proposition 8. Let $\phi$ and $\psi$ be two formulas. Then, $\phi \equiv \exists_F \psi. \phi$ if $\psi \not\models_F \phi$.

The following proposition further illustrates some essential properties of formula forgetting.

Proposition 9. 1. $\exists_F l. \phi \equiv \exists_l l. \phi$ for any literal $l$;
2. $\phi$ is satisfiable iff $\exists_F \psi. \phi$ is satisfiable;
3. If $\phi \equiv \phi'$ and $\psi \equiv \psi'$, then $\exists_F \psi. \phi \equiv \exists_F \psi'. \phi'$;
4. $\exists_F \psi. (\phi \lor \phi') \equiv (\exists_F \psi. \phi) \lor (\exists_F \psi. \phi')$;
5. If $\text{DepVar}(\phi) \cap \text{DepVar}(\psi) = \emptyset$, then $\exists_F \psi. (\phi \land \phi') \equiv \phi \land (\exists_F \psi. \phi')$.

Firstly, formula forgetting is a generalization of literal forgetting. Secondly, forgetting any formula preserves satisfiability of the original formula. Thirdly, it is syntax irrelevance, and distributive over disjunction. Finally, forgetting $\psi$ in a conjunction of two formulas does not affect the counterpart that shares no dependent variable of $\psi$.

We next investigate the computation of formula forgetting. Recall the definition of literal forgetting (cf. Definition 4), forgetting a literal $l$ in $\phi$ consists of two steps:

1. Transform $\phi$ into $(l \land \phi_l) \lor (\lnot l \land \phi_{\lnot l})$ via the Shannon expansion;
2. Eliminate the occurrence of $l$, i.e., $\phi_l \lor (\lnot l \land \phi_{\lnot l})$.

The Shannon expansion can be generalized to a multi-variable expansion w.r.t. a set $X$ of variables, i.e., $\phi \equiv \bigvee_{l \in \Omega} (l \land \phi_l)$. It is natural to imagine that forgetting a formula $\psi$ in $\phi$ should first decompose $\phi$ w.r.t. the set of dependent variables of $\psi$, and then remove every dependent minterm of $\psi$. We therefore obtain a brute-force computation of formula forgetting as follows.

Proposition 10. Let $X = \text{DepVar}(\psi)$. Then, $\exists_F \psi. \phi \equiv \bigvee_{l \in \Omega \setminus \text{DepVar}(\phi_l)} (l \land \phi_l)$.

The computation of formula forgetting via Proposition 10 is computationally expensive when $\text{DepVar}(\psi)$ is large. To simplify the computation, we give another approach via conditioning. It is hard to extend the definition of term conditioning (cf. Definition 4) to formula conditioning since a formula may contain a literal and its negation simultaneously and it may even be unsatisfiable. We hereafter resort to Proposition 5 and formalize the notion of formula conditioning via variable forgetting.

Definition 12. The conditioning of $\phi$ on $\psi$, written $\phi|_\psi$, is defined as $\exists_V \text{DepVar}(\psi). (\phi \land \psi)$.

Note that if $\psi \equiv \top$ (resp. $\bot$), then $\phi|_\psi \equiv \phi$ (resp. $\bot$).

From now on, we adopt Definition 12 as the definition of the notation $\phi|_\psi$ when $\psi$ is a satisfiable term $t$.

A semantic characterization of formula conditioning is as follow: the models of the conditioning of $\phi$ on $\psi$ is the union of model $\omega$ where forcing it on any dependent minterm of $\psi$ leads to a model of $\phi$.

Proposition 11. $[\phi|_\psi] = \bigcup_{t \in \text{Dom}_t} \{ \omega \mid \omega_{\lnot t} \models \phi \}$.

The following proposition states that the result of forgetting $\psi$ in $\phi$ is equivalent to the disjunction of $\phi$ and the conditioning of $\phi$ on $\psi$.

Proposition 12. $\exists_F \psi. \phi \equiv \phi \lor \phi|_\psi$.

Now, we use an example to illustrate the computation of formula forgetting.

Example 7. Continued with Example 5. We have $\phi' = (a \land b) \lor (a \land c) \lor (b \land c)$, $\psi = (a \lor b) \land (c \lor \lnot c)$, and $\text{DepVar}(\psi) = \{a, b\}$.

Firstly, the conjunction of $\phi'$ and $\psi$ is as follows:
$\phi' \land \psi = ((a \land b) \lor (a \land c) \lor (b \land c)) \land ((a \lor b) \land (c \lor \lnot c))$
$\equiv \{(a \land b) \lor (a \land b) \land c\}$.
Then, conditioning of φ’ on ψ leads to:

\[ \phi’ | \psi = \exists \psi \{ a, b \} \land ((a \land b) \lor (a \land \lnot b)) \land c \equiv c. \]

Hence, the result of forgetting ψ in φ’ is

\[ \exists \psi \psi’, \phi = \phi’ \lor \phi’ | \psi = [\lnot (a \land b) \lor (a \lor \lnot b) \lor (b \land \lnot c)] \lor c \equiv (a \land \lnot b) \lor c. \]

Theoretically, the computation of formula forgetting via Proposition[12] cause single-exponential blowup in the size of the original formula unless P = NP. But this is a practical solution by using existing techniques of knowledge compilation, e.g., binary decision diagrams (BDDs) [Bryant 1992]. BDD is a compact form of propositional formula, and supports efficient boolean operations. This will be shown in our experimental evaluation.

By Propositions[11] and [12] we get a semantic characterization of formula forgetting. Forgetting ψ in φ amounts to introduce the models of the conditioning of φ on ψ.

**Corollary 1.** \[ [\exists \psi \psi, \phi] = [\phi] \cup \bigcup_{\omega \in \Omega} \{ \omega \mid \omega_{\lnot t} \models \phi \}. \]

**Belief update based on FF-dependence**

In this section, following the dependence-based update scheme, we define a new update operator of based on FF-dependence. Then, we completely capture our update operator by identifying two extra postulates, show that the update operator satisfy the postulates (U1) - (U4) and (U8) and identify a special case in which all of the KM postulates holds. Finally, we compare of with other operators of, \( \psi \), \( \psi \), \( \psi \) from various perspectives including information preservation, computational complexity and experimental results.

**Belief update via formula forgetting**

The update operator based on FF-dependence is defined in terms of formula forgetting.

**Definition 13.** Let φ and ψ be formulas. The update operator of, is defined as \( [\psi] \psi = [\exists \psi (\lnot \eta_0) \phi \land \psi \). The following example illustrates the mechanism of the update operator of.

**Example 8.** Continued Example[5] we have \( \phi’ = (a \land b) \lor (a \land \lnot b) \lor (a \lor \lnot b) \lor (b \land c) \lor (c \lor \lnot c) \). We let \( \eta = a \land \lnot b \lor \lnot c \) that is equivalent to \( \lnot \eta \). The procedure of updating \( \phi’ \) by \( \eta \) via of consists of two steps:

1. Forget \( \eta \) in \( \phi’ = [\exists \psi (\lnot \eta_0) \phi’ \lor (a \land b) \lor (a \land \lnot b) \lor (a \lor \lnot b) \lor (b \land c) \lor (c \lor \lnot c) \)

2. Conjoin the result of formula forgetting with \( \eta_0 = [\exists \psi (\lnot \eta_0) \phi’ \lor (a \land b) \lor (a \land \lnot b) \lor (a \lor \lnot b) \lor (b \land c) \lor (c \lor \lnot c) \), \( \eta_0 = [\exists \psi (\lnot \eta_0) \phi’ \lor (a \land b) \lor (a \land \lnot b) \lor (a \lor \lnot b) \lor (b \land c) \lor (c \lor \lnot c) \equiv a \land \lnot b \land \lnot c \).

In the following, we give the model-theoretical characterization of of. We first provide the definition of the update of an interpretation by the new information.

**Definition 14.** Let \( \omega \) be an interpretation. The update \( \omega \psi \psi \) based on FF-dependence is defined as

\[ \omega \psi \psi = \left\{ \begin{array}{ll} \{ \omega \}, & \text{if } \omega \models \psi; \\ \{ \omega_{\lnot t} \mid t \in \Omega \}, & \text{otherwise.} \end{array} \right. \]

If an interpretation \( \omega \) satisfies the new information \( \psi \), then we do not modify the interpretation. Otherwise, we force \( \omega \) on each dependent minterm \( t \) of \( \psi \) such that the new interpretation \( \omega_{\lnot t} \) satisfies \( \psi \).

The FF-dependence based update of a formula \( \phi \) by \( \psi \) collects the updates of each model of \( \phi \) by \( \psi \):

**Proposition 13.** \[ [\psi \phi \psi] = \bigcup_{\omega \in \Omega} \{ \omega \psi \phi \psi \}. \]

Now, we give a representation result for the operator of.

**Theorem 1.** An operator \( \phi : \mathcal{L} \times \mathcal{L} \rightarrow \mathcal{L} \) is equal to \( \psi \) if it satisfies (U2), (U8), and

- **UP** If \( \exists \phi \cap \exists \psi = \emptyset \), then \( (\phi \land \phi’) \psi \equiv \phi \land (\phi’ \psi) \).
- **UF** If \( \exists \phi \subseteq \exists \psi \), \( \phi \neq \bot \), and \( \phi \land \psi \equiv \bot \), then \( \phi \psi \equiv \psi \).

**Proof.** (⇒): By Definition[14] and Proposition[13], \( \phi \) satisfies (U2) and (U8). Suppose that \( \exists \phi \cap \exists \psi = \emptyset \), by Proposition[2] we have \( (\phi \land \phi’) \psi \equiv [\exists \psi (\lnot \psi), (\phi \land \phi’)] \land \psi \equiv \phi \land \exists \psi (\lnot \psi), (\phi \land \phi’ \psi) \). The above implies that \( \phi \psi \) satisfies (UP). Suppose that \( \exists \phi \subseteq \exists \psi \), \( \phi \neq \bot \) and \( \phi \land \psi \equiv \bot \). It is easily verified that \( (\phi \psi) \equiv \top \). Thus, \( \phi \psi \equiv [\exists \psi (\lnot \psi), \phi \land \psi \equiv (\top \vee \phi) \land \psi \equiv \phi \land \phi \psi \).

Hence, \( \phi \psi \) satisfies (UF).

(⇐): Suppose that \( \phi \psi \equiv \top \). Let \( X = \exists \psi \psi \psi \). Based on \( \exists \psi \psi \psi \) and \( \omega \), we construct two terms \( t \) and \( t’ \) as follows:

\[ t = \bigwedge_{p \in X} \omega \models p \bigwedge_{p \in X} \omega \not\models p \rightarrow 1 \]
\[ t’ = \bigwedge_{p \in X} \omega \models p \bigwedge_{p \in X} \omega \not\models p \rightarrow 1 \]

Obviously, \( t \land t’ \) is the minterm corresponding to \( \omega \). By postulates (UP) and (UF), we get that \( (t \land t’) \psi \equiv (t \psi) \land t’ \equiv \psi \). So \( \omega \psi \equiv \{ \omega_{\lnot t} \mid t \in \Omega \} \).

Postulate (UP) is analogous to the postulate (SP) except use dependant variables instead of variables. It says that if the belief base can be divided into two disjoint compartments, then the compartment, which is not related to the new information, remains unchanged. Postulate (UP) means that if any dependent variable of \( \phi \) is also a dependant variable of \( \psi \), and \( \phi \psi \) is satisfiable and conflicts with \( \psi \), then the belief is simply replaced by the new information after updating.

By Theorem[1] and Proposition[13], it is easily verified that \( \phi \psi \) satisfies some of KM postulates.

**Theorem 2.** The operator \( \phi \psi \) satisfies (U1)-(U4) and (U8).

It is easy to construct counterexamples to show that none of (U5)-(U7) are satisfied. Due to space limitations, we do not provide the counterexamples. The reason why the operator \( \phi \psi \) fails to satisfy them is that \( \phi \psi \) does not follow the principle of minimal change to which the three postulates correspond. From the semantic perspective, this principle requires that the update of \( \omega \) by \( \psi \) should be a set of models of \( \psi \) that are the closest to \( \omega \). However, \( \phi \psi \psi \) generally involves some models that violate this condition. For example, consider \( \omega = \{ a, b, c \} \) and \( \psi = \lnot a \lor \lnot b \). Then \( \phi \psi \psi = \{ \{ a, c \}, \{ b, c \} \} \). Clearly, both \( \{ a, c \} \) and \( \{ b, c \} \) closer to \( \omega \) than \( \{ c \} \), and hence \( \{ c \} \) is not the closest model.

Interestingly, when we restrict \( \psi \) to be a satisfiable term, \( \phi \psi \psi \) contains only one model \( \omega_{\lnot t} \psi \). We take it for granted that it is the only model of \( \psi \) that is the closest to \( \omega \).
this restriction, \( \phi \) obeys the principle of minimal change, and hence satisfies (U5)-(U7).

**Theorem 3.** If any formula \( \psi \) appearing in \( \phi \circ \psi \) must be a term in the KM postulates, then the operator \( \phi \circ \psi \) satisfies (U1)-(U8).

To prove the theorem, we now give the following lemma which means that if the update of an interpretation \( \omega \) by a term \( t \) satisfies another one \( t' \), then it is the same as the update of \( \omega \) by the conjunction of \( t \) and \( t' \).

**Lemma 1.** Let \( t \) and \( t' \) be two terms. If \( \omega \circ \phi t \models t' \), then \( \omega \circ \phi t = \omega \circ \phi (t \land t') \).

We now prove Theorem 3.

**Proof.** (U5) Let \( \omega \) be a model of \( (\phi \circ \psi) \land \eta \). There is a model \( \nu \) of \( \phi \) s.t. \( \omega = \nu \circ \psi \). Thus, \( \nu \circ \psi \models \eta \). This, together with Lemma 1 imply that \( \omega = \nu \circ \psi (\psi \land \eta) \). Hence, \( (\phi \circ \psi) \land \eta \models \phi \circ \psi (\psi \land \eta) \).

(U6) Let \( \omega \) be a model of \( \phi \). By the assumption, we have \( \omega \circ \psi \models \psi' \) and \( \omega \circ \phi \psi' \models \psi' \). By Lemma 1 we get that \( \omega \circ \phi \psi' = \omega \circ \phi (\psi \land \psi') = \omega \circ \phi \psi' \). Hence, \( \phi \circ \psi \models \phi \circ \psi' \).

(U7) Let \( \omega \) be a model of \( (\phi \circ \psi) \land (\phi \circ \psi') \). Since \( \phi \) is a minterm, there is a unique model \( \nu \) of \( \phi \). Because both \( \psi \) and \( \psi' \) are terms, so \( \omega = \nu \circ \phi \psi \) and \( \omega = \nu \circ \phi \psi' \). By postulate (U1), we get that \( \omega \models \psi' \). This, together with Lemma 1 imply that \( \omega = \nu \circ \phi (\psi \land \psi') \). We construct a term \( t \) as follows:

\[
\bigwedge_{p \in P} (\psi \models \phi \circ \psi \models p \land \bigwedge_{p \in P} (\psi \not\models \phi \circ \psi \not\models p) \land (\psi \not\models \phi \circ \psi \not\models p \lor \phi \circ \psi \models p)
\]

It is easily verified that \( t \equiv \psi \land \psi' \) and \( t \) is a dependent term of \( \psi \lor \psi' \). Hence, \( \omega \circ \phi \psi (\psi \lor \psi') \subseteq \omega \circ \phi \psi \lor \psi' \), and \( (\phi \circ \psi) \land (\phi \circ \psi') \models \phi \circ \psi \lor \psi' \).

\[\square\]

From the postulational point of view, the essential difference between revision and update is as follows: revision satisfies the conjunction property (R2), proposed in (Katsuno and Mendelzon 1991): if the new information \( \psi \) does not contradict the initial base \( \phi \), then the revised belief base should be equivalent to the conjunction of \( \phi \) and \( \psi \). On the contrary, update satisfies the distribution property (U8): update is distributive over the initial base. The operator \( \phi \circ \psi \) satisfies (U8) but not (R2). Hence, we consider \( \phi \circ \psi \) as an update operator, not a revision operator.

We next give the upper and lower bounds of the inference problem of the update operator \( \phi \circ \psi \).

**Proposition 14.** Deciding whether \( \phi \circ \psi \models \eta \) is in \( \Delta^2_p \) and coNP-hard.

**Comparison with other update operators**

In this subsection, we compare our belief update operator with other operators from different perspectives.

**Information preservation** The first perspective we focus on is how much information of the initial base is preserved after updating. From the semantic perspective, the less difference between the models of the initial base and those of the updated one, the more information that the update procedure preserves.

**Definition 15.** Let \( \diamond \) and \( \diamond' \) be two update operators. We say \( \diamond \) preserves at least as much information as \( \diamond' \), written \( \diamond \leq_c \diamond' \), if \( [\phi \circ \psi \models \diamond] \subseteq [\phi \circ \psi \models \diamond'] \) for any formulas \( \phi \) and \( \psi \). The notation \( \leq_c \) is obtained as usual by taking the asymmetric parts of \( \leq_c \).

The following proposition says that update operators based on dependence preserve more information than those based on the principle of minimal change. Among three dependence-based update operators, \( \phi \circ \psi \) preserves the most information.

**Proposition 15.** \( \phi \circ \psi \models \leq_c \phi \circ \psi \models \leq_c \phi \circ \psi \models \leq_c \phi \circ \psi \models \leq_c \phi \circ \psi \models \phi \).

**Computational complexity** We next make a comparison from the perspective of the computational complexity. The complexity results of inference problems of \( \phi \circ \psi \), \( \phi \circ \psi \), and \( \phi \circ \psi \) are as follows.

**Proposition 16.** (Eiter and Gottlob 1992) Deciding whether \( \phi \circ \psi \models \eta \) is \( \Pi^2 \)-complete.

**Proposition 17.** (Herzig and Rifi 1999; Herzig, Lang, and Marquis 2013) Deciding whether \( \phi \circ \psi \models \eta \) is coNP-complete.

**Definition 16.** Let \( \diamond \) and \( \diamond' \) be two update operators. We say \( \diamond \) is at least as computationally complexity as \( \diamond' \), written \( \diamond \preceq \diamond \), iff the upper bound the complexity of \( \diamond \) is contained in the lower bound of the complexity of \( \diamond' \). The notations \( \preceq \) and \( \preceq \) are obtained by taking the asymmetric and symmetric part of \( \preceq \) respectively.

By Propositions 14, 15 and 17 we get the following corollary. Because the computational complexity of \( \phi \circ \psi \) and \( \phi \circ \psi \) are the same, so \( \phi \circ \psi \models \phi \circ \psi \) holds. Similarly, \( \phi \circ \psi \models \phi \circ \psi \) also holds. The lower bound of \( \phi \circ \psi \), which is coNP, is the same as the upper bound of \( \phi \circ \psi \). Thus, \( \phi \circ \psi \models \phi \circ \psi \) holds.

However, we cannot get that \( \phi \circ \psi \models \phi \circ \psi \) since the lower bound of \( \phi \circ \psi \) does not contain the upper bound of \( \phi \circ \psi \), which is \( \Delta^2 \). Hence, we only obtain that \( \phi \circ \psi \models \phi \circ \psi \). In addition, \( \phi \circ \psi \models \phi \circ \psi \) holds while \( \phi \circ \psi \models \phi \circ \psi \) does not. This is because the upper bound of \( \phi \circ \psi \), which is \( \Pi^2 \), is not a subset of the lower bound of \( \phi \circ \psi \) even if it is \( \Delta^2 \)-complete.

So \( \phi \circ \psi \models \phi \circ \psi \) holds. The computational complexity of \( \phi \circ \psi \) is between those of \( \phi \circ \psi \) and \( \phi \circ \psi \).

**Corollary 2.** \( \phi \circ \psi \models \phi \circ \psi \models \phi \circ \psi \models \phi \circ \psi \models \phi \circ \psi \models \phi \circ \psi \).

**Empirical results** We have shown that the computational complexity of \( \phi \circ \psi \) is higher than the other two dependence-based update operators in theory, but practice might be another matter. To assess the latter, we conduct an experiment of computing the new belief base. The benchmark used in (Marchi, Bittencourt, and Perrussel 2010) is from SATLIB that is available in http://www.cs.ubc.ca/~hoos/SATLIB/benchm.html. We test two scales of test-sets: 91 clauses with 20 variables.
Table 1: Comparison of various update operators

| Update operator | V/C | Min | Max | Avg |
|-----------------|-----|-----|-----|-----|
| $\diamond_V$    | 0.072 | 2.01 | 3.30 | 5.06 |
| $\diamond_L$    | 0.015 | 0.076 | 0.199 | 0.030 |
| $\diamond_{For}$| 9.555 | 1.350 | 857.926 | 1.225 |
| $\diamond_{PMA}$| 11.279 | 1.700 | 876.926 | 0.029 |

and 218 clauses with 50 variables. Each test-set has 1000 instances. For each instance, we use its corresponding theory as the initial belief base, and the negation of the first 4 clauses as the new contradictory information. In this experiment, we use BDDs to represent the initial KB and the new information and compute the updated KB via some operations of BDDs.

We illustrate the computation of each update operator in the following. Based on Definitions 12 and 13 and Proposition 12, computing $\diamond_V \psi$ consists of (1) generating the set $\text{DepVar}(\neg \psi)$; (2) forgetting all variables of $\text{DepVar}(\neg \psi)$ in $\phi \land \neg \psi$; (3) conjoining $\exists_t (\neg \psi). \phi$ with $\psi$. The computation of $\diamond_L \psi$ (resp. $\diamond_{For} \psi$) is similar to the above except that, it preserves less information, but it is much more efficient.

In Table 1, the update operator and the numbers of variables and clauses are reported in columns 1 and 2 respectively. Columns 3 - 5 indicate the minimum, maximum and average time (in ms) of updating the KB. We can make two observations from Table 1. Firstly, all of approaches based on dependence are much more efficient than anyone based on the principle of minimal change. Secondly, for three dependence-based update operators, the maximum updating times of three dependence-based update operators are less than 100ms while the average ones are less than 1.5ms in the benchmarks with 218 clauses and 50 variables. The difference can be negligible, and hence the updating times of them are almost the same.

We close this section by noting that $\diamond_V$ is a suitable alternative to update operator. It is the dependence-based update operator preserving the most information. In practice, the computational efficiency of $\diamond_V$ are almost the same as those via $\diamond_L$ and $\diamond_{For}$, albeit that theoretically the computational complexity of $\diamond_V$ is higher than those of them. Compared to the two operators based on the principle of minimal change, it preserves less information, but it is much more efficient.

Conservative extension via formula forgetting

Conservative extension plays a prominent role in AI and logics (Ghilardi, Lutz, and Wolter 2006; Lutz, Walther, and Wolter 2007; Jung et al. 2017). Generally speaking, a conservative extension is a supertheory of a theory that proves no new theorems about the language of the original theory. We next give a syntax-independent definition of conservative extension in terms of dependent variables.

Definition 17. We say that $\phi \land \psi$ is a syntax-independent conservative extension of $\phi$, if for every formula $\eta$ with $\text{DepVar}(\eta) \subseteq \text{DepVar}(\phi)$, $\phi \land \psi \models \eta$ implies that $\phi \models \eta$.

The above definition is slightly different from the original version that is based on variables. Each syntax-independent conservative extension also is an original one, but the converse does not hold. For example, $\phi = a \land (b \lor b)$ and $\psi = b$. The formula $\phi \land \psi$ is not a conservative extension of $\phi$ since $\phi \land \psi \models \psi$ but $\phi \not\models \psi$. However, it is a syntax-independent conservative extension of $\phi$. This difference does not impede the widespread use of syntax-independent version. In many practical applications, the background KB and query are firstly simplified, i.e., they merely contain their dependent variables (Levy, Fikes, and Sagiv 1997; Lang, Liberatore, and Marquis 2003). Based on this assumption, two definitions of conservative extension are the same.

Finally, we obtain that deciding if $\phi \land \psi$ is a syntax-independent conservative extension of $\phi$ can be reduced to determining if forgetting $\phi \land \psi$ in each dependent minterm of $\phi$ leads to a tautology.

Theorem 4. $\phi \land \psi$ is a syntax-independent conservative extension of $\phi$ iff $\exists_t (\phi \land \psi). t \models \top$ for every $t \in \Omega_{\phi}$.

Proof. ($\Rightarrow$): Suppose that there is $t \in \Omega_{\phi}$ s.t. $\exists_t (\phi \land \psi). t \not\models \top$. Let $\Omega_t$ be the set $\{ t' \mid t' \in \Omega_{\phi} \land \exists_t (\phi \land \psi). t' \not\models \top \}$. It is easy to verify that $t \land \psi \subseteq t' \models \top$ for $t \in \Omega_t$. Hence, $\phi \land \psi \equiv (t \land \psi) \models \top$. Let $\eta = \exists_t (t \land \psi). t$. Obviously, $\phi \land \psi \models \eta$ and $\phi \not\models \eta$. This contradicts the assumption.

($\Leftarrow$): Suppose that there is $t \in \Omega_{\phi}$ s.t. $\exists_t (\phi \land \psi). t \not\models \top$. Since $\text{DepVar}(\eta) \subseteq \text{DepVar}(\phi)$, $\phi \land \psi \models \eta$ and $\phi \not\models \eta$. Hence, there is $t \in \Omega_{\phi} s.t. t \not\models \eta$. Since $\text{DepVar}(\eta) \subseteq \text{DepVar}(\phi)$, we get that $t \models \neg \eta$. Because $\phi \land \psi \models \eta$, so $t \land \psi \not\models \eta$. Thus, $t \models \psi$. We get that $\exists_t (\phi \land \psi). t \not\models \top$. This contradicts the assumption. □

Example 9. Let $\phi = (a \land b) \equiv (a \land \bar{b})$ and $\psi = (a \land \bar{d}) \lor (\bar{b} \land c)$. Then, $\exists_t (\phi \land \psi). (a \land d) \equiv (a \land \bar{b} \land d) \lor (a \land \bar{b} \land c)$. Hence, $\exists_t (\phi \land \psi). (a \land d) \equiv (a \land \bar{b} \land d) \lor (a \land \bar{b} \land \bar{c} \land \bar{d}) \land (\bar{c} \land \bar{d})$. Thus, $\exists_t (\phi \land \psi). (a \land d) \equiv \top$ and $\exists_t (\phi \land \psi). (a \land \bar{b}) \equiv \top$. So $\phi \land \psi$ is a syntax-independent conservative extension of $\phi$.

Related Work

Dependence is well-known as a fundamental concept in many fields of artificial intelligence, particularly belief change. Several authors axiomatized the notion of dependence by postulates, and connected it to belief contraction. Belief contraction, a type of belief change, which is removal of existing beliefs. Del Cerro and Herzig (1996) gave postulates for a dependence relation between formulas, and established the correspondence between the dependence relation and belief contraction. In (del Cerro and Herzig 1996), a belief state is represented as a belief set, i.e., an infinite set of formulas closed under implication. Oveisi et al (2017) pointed out that a belief base, which need not be deductively closed and is often finite, is a practical alternative for
representing belief states. They also identified a similar connection between dependence and base contraction.

The main difference between our work and the above approaches to dependence relations between formulas, is that our dependence relation corresponds to formula forgetting while their relations correspond to belief contraction. Belief contraction gets rid of as little as possible from the initial belief \( \phi \) in order that the new belief state does not entail \( \psi \). By contrast, formula forgetting eliminates all parts of \( \phi \) relevant to \( \psi \) even if \( \phi \) does not entail \( \psi \).

The above works focus on axiomatizations of dependence. Besides, there are several works that define the dependence relation corresponds to formula forgetting. Parikh (1999) showed the finest splitting theorem, which says that any finite set \( \Sigma \) of formulas has a unique finest splitting (i.e., a partition \( \{ P_1, \ldots, P_n \} \) of \( P \) that refines every other splitting of \( \phi \)). \( \Sigma \) can be decomposed into a set \( \{ \phi_1, \ldots, \phi_n \} \) of formulas where every \( \phi_i \) uses only variables of \( P_i \). Based on this theorem, a formula \( \psi \) is said to be canonically cell-relevant to \( \eta \) w.r.t. \( \Sigma \), if there is a cell \( P_i \) of the finest splitting of \( \Sigma \) such that \( P_i \cap \text{DepVar}(\psi) \neq \emptyset \) and \( P_i \cap \text{DepVar}(\eta) \neq \emptyset \). Parikh (1999) also proposed a postulate (P) of relevance for belief change, and showed that the postulate (P) is consistent with the basic AGM postulates for belief revision.

Kourosias and Makinson (2007) extended the above work to the infinite case. Later, Peppas et al. (2015) demonstrated that the revision operator, proposed by Dalal (1988), satisfies all AGM postulates as well as the stronger version (SP) of postulate (P). Rodrigues (1997) proposed another definition of relevance, called path-relevance. A formula \( \psi \) is said to be path-relevant to \( \eta \) w.r.t. \( \Sigma \), if there is a finite sequence \( \xi_0, \ldots, \xi_{m+1} \) of formulas such that \( \xi_0 = \psi \), \( \xi_{m+1} = \eta \), \( \xi_i, \ldots, \xi_m \in \Sigma \), and \( \text{Var}(\xi_i) \cap \text{Var}(\xi_{i+1}) \neq \emptyset \) for \( 0 \leq i \leq m \). The notion of path-relevance is not syntax-independent. To repair this defect, Makinson (2009) proposed a new definition of path-relevance via language splitting and dependent variables, and proved that it is indeed equivalent to the notion of canonical cell-relevance. A formula \( \psi \) is said to be canonically path-relevant to \( \eta \) w.r.t. \( \Sigma \), if there is a finite sequence \( \xi_0, \ldots, \xi_{m+1} \) of formulas such that \( \xi_0 = \psi \), \( \xi_{m+1} = \eta \), \( \xi_i, \ldots, \xi_m \in \Sigma \), and \( \text{DepVar}(\xi_i) \cap \text{DepVar}(\xi_{i+1}) \neq \emptyset \) for \( 0 \leq i \leq m \).

The above works assume that the underlying logic contains classical propositional logic. Horn logic is a very useful fragment of propositional logic, whose satisfiability is tractable. For this logic, relevance-sensitive belief contraction and revision were investigated by Wu, Zhang, and Zhang (2011) and Delgrande and Peppas (2015) respectively.

In other areas of artificial intelligence, some authors proposed different definitions of dependence relation between formulas. To speed up inferences from large KBs, Levy, Fikes, and Sagiv (1997) proposed a proof-theoretic framework for analyzing which components of a KB \( \Sigma \) are irrelevant to a query \( \psi \). A formula \( \phi \) of a given KB \( \Sigma \) is irrelevant to a query \( \psi \) if \( \psi \) can be derived without exploiting \( \phi \). In the area of knowledge acquisition and machine learning, novelty is an important dependence relation between formulas given a background KB (Greiner and Genesereth 1983). It is used to decide whether a fact is new to some concepts w.r.t. the background KB. Greiner and Genesereth (1983) first formalized semantics for this relation. Later, Marquis (1991) proposed two equivalent characterizations in terms of prime implicant and abduction.

Conclusions

The focus of this paper is on dependence in propositional logic. The main contributions are as follows:

First of all, this paper sheds light on the theoretical underpinnings of dependence in propositional logic. We have generalized the notions of FL-dependence and literal forgetting to FF-dependence and formula forgetting respectively. We have provided several equivalent formulations of FF-dependence and formula forgetting. Furthermore, some properties of them have been given.

In addition, we have applied these notions in belief update and conservative extension. We have defined the update operator \( \varepsilon_F \) in terms of formula forgetting. We have completely characterized this operator by identifying some extra postulates and have assessed them against the KM postulates. Compared to the other dependence-based update operators \( \varepsilon_V \) and \( \omega_L, \omega_F \) preserves more information, and has almost the same efficiency. In contrast to the operators based on the principle of minimal change, \( \omega_F \) is much more efficient than them although it preserves less information. Finally, we show that conservative extension can be reduced to formula forgetting.

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