Fast multicolor 3D imaging using aberration-corrected multifocus microscopy

Sara Abrahamsson1–3, Jiji Chen4,16, Bassam Haji4,16, Sjoerd Stallinga5, Alexander Y Katsov3, Jan Wisniewski4,6, Gaku Mizuguchi2,4,6, Pierre Soule7, Florian Mueller7,8, Claire Dugast Darzacq4,7,9, Xavier Darzacq4,7, Carl Wu2,4,5, Cornelia I Bargmann3,10, David A Agard11,12, Maxime Dahan4,13,14 & Mats G L Gustafsson2,15

Conventional acquisition of three-dimensional (3D) microscopy data requires sequential z scanning and is often too slow to capture biological events. We report an aberration-corrected multifocus microscopy method capable of producing an instant focal stack of nine 2D images. Appended to an epifluorescence microscope, the multifocus system enables high-resolution 3D imaging in multiple colors with single-molecule sensitivity, at speeds limited by the camera readout time of a single image.

Fast and sensitive acquisition of 3D data is one of the main challenges in modern biological microscopy. Most imaging modalities, such as wide-field, laser-scanning confocal, spinning-disk confocal and light-sheet microscopy1, record information from one focal plane at a time. 3D images are assembled from a focal stack of 2D images acquired using sequential refocusing. This process is time consuming and can yield ambiguous spatiotemporal information because the focal planes are not recorded simultaneously. Moreover, the fast movement of the microscope stage (or objective) during refocusing can mechanically perturb the sample when an immersion objective is used (though this can be avoided by remote focusing2). Fluorescent probes can also be excited and photobleached while they are out of focus, which translates the camera away from the nominal focal plane induces spherical aberration after a refocus of a few microns2. It should also be noted that in the current configuration, this approach requires one camera per focal plane.

Here we report an aberration-corrected multifocus microscopy (MFM) method, which produces an instant focal stack of high-resolution 2D images simultaneously displayed on a single camera (Fig. 1a–c). It is based on the use of a diffractive grating to form multiple focus-shifted images4,5 and on aberration-free refocusing2. Our system was designed with the following considerations: (i) sensitivity must be optimized to minimize photobleaching and phototoxicity and to enable high-speed imaging of weakly fluorescent samples such as single fluorophores; (ii) multiple focal planes must be acquired without aberrations, especially the dominating depth-induced spherical aberration, to avoid loss in resolution and contrast; (iii) the system must be corrected for the chromatic dispersion that arises when a diffractive element is used to image non-monochromatic light.

Our multifocus microscope consists of three specially designed optical elements (Fig. 1d) appended to the camera port of a standard, high-resolution epifluorescence microscope. Two relay lenses are also used, to form a secondary pupil plane (Fourier plane) and the final image plane (Fig. 1a). The diffractive multifocus grating (MFG) is placed in the Fourier plane to form the multifocus image, and it is followed by the chromatic correction grating (CCG) and prism. The MFG performs two distinct functions. First, it splits the fluorescence light emitted from the sample into separate paths, thus forming an array of $N \times N$ images of the sample on the camera. Each image corresponds to a 2D diffractive order $(m_x, m_y)$ of the grating. Here we describe an MFG with nine focal planes, which are formed by the central $3 \times 3$ diffractive orders $m_x, m_y = 0, \pm 1$. To minimize light loss, we use a phase-only grating of fused silica, with a grating function (Fig. 1d) designed to distribute the sample emission light evenly and efficiently among the nine focal planes. At the design wavelength (515 nm), the measured efficiency of our MFG (custom made by Creative Microsystems) is ~65% with even distribution between images, as illustrated in Supplementary Figure 1. This is close
to the theoretical maximum efficiency (~67%) of this type of grating, but it could be improved (theoretically to ~93%) by using a multiphase element. To implement an MFM microscope with more focal planes, one would use a different MFG to image the $m_x$, $m_y$, $m_z = 0, \pm 1, \pm 2$ diffractive orders, obtaining $5 \times 5 = 25$ planes, as shown in Supplementary Figure 1.

The second function of the MFG is to refocus the array of images so that it forms an instant focal series with a constant focus step $\Delta z$. When refocusing deep into a thick sample, the microscope objective is used at a focal distance for which it is not designed. This normally gives rise to depth-induced spherical aberration, which deteriorates the image. To avoid this problem, we have used the Abbe sine condition to calculate the defocus phase error $\delta \phi(z)$ in the Fourier plane of a point source at defocus z in the sample. We let the MFG apply an equal but opposite phase shift that entirely reverses the out-of-focus wavefront error (Online Methods). Light from the out-of-focus plane thus exits the MFG with a flat wavefront, as illustrated in Supplementary Figure 2, and is properly focused onto the camera. The phase shift is introduced by a carefully calculated geometrical distortion of the MFG pattern (Fig. 1d) and is dependent on diffractive order so that each duplicate image in the $N \times N$ array obtains a focus shift $\Delta z \times (m_x + N \times m_y)$ (Fig. 1c). The magnitude of the MFG distortion determines the step size $\Delta z$. To adapt the
microscope to a variety of samples and imaging applications, we have designed several gratings, which produce different focus shifts ranging from 250 nm to 2 μm, spanning 2.25–18 μm of sample depth per 3D image.

The MFG is in itself sufficient for imaging monochromatic light. However, even across the relatively narrow (~30-nm) wavelength spectrum of a single fluorophore, chromatic dispersion—inherent to any diffractive element—severely deteriorates resolution.

To correct the dispersion, we have designed the CCG (custom made by Tessera), which is placed after the MFG at a position where the diffractive orders are separated (Fig. 1b). The CCG panels consist of blazed transmission gratings (oriented as shown in Fig. 1d) that reverse the dispersion from the MFG (Online Methods). On its own, the CCG would not only remove the chromatic dispersion but, unfortunately, also reverse the image separation obtained by the MFG. Therefore, we have added a multifaceted refractive prism (custom made by Rocky Mountain Instruments) to direct the diffractive orders to their positions on the camera. The CCG spacing is adjusted to compensate for the additional dispersion of the prism. (The optical properties of the CCG and prism are illustrated in Supplementary Fig. 3.) We hereby obtain an essentially diffraction-limited point-spread function (PSF) for fluorophores across the visible spectrum. For an MFG with Δz = 380 nm and using a 100× Nikon oil-objective (numerical aperture (NA) = 1.4), the full width at half maximum of the PSF is 238 nm laterally and 660 nm axially (Fig. 1e, f and Supplementary Videos 1 and 2). The focus shift between planes is verified in Figure 1g, h and further discussed in Supplementary Note 1.

To evaluate the performance of our MFM in living samples, we imaged Saccharomyces cerevisiae (Fig. 2) expressing Cse4-GFP, a histone H3 variant that binds to centromeric DNA (Supplementary Note 2). We were able to track the centromeres (each labeled by 30–80 fluorescent molecules8,9) in three dimensions and observe their behavior during cell division10 with one image (covering a volume of 20 × 20 × 3.5 μm3) recorded every 3 s (exposure time = 100 ms). We observed the biphasic behavior of centromeres during cell division (Supplementary Videos 3 and 4), with a fast initial separation speed of 20 nm s–1 over ~2 min followed by a slower separation of 3 nm s–1 over ~15 min.

High sensitivity and spatiotemporal resolution are paramount in single-molecule imaging, in which the acquisition of 3D data is a major challenge11. In a single-particle tracking experiment, we imaged RNA polymerase II (labeled using HaloTag (Promega)) in the nucleus of a human osteosarcoma cell line12 (Supplementary Note 3). We were able to image the heterogeneous nuclear mobility of RNA polymerase II in three dimensions at 35 frames per s, observing bound and mobile states and transitions between them (Fig. 3 and Supplementary Videos 5 and 6). The depth (~4 μm) over which we could detect and reconstruct individual trajectories in MFM compares well to other 3D single-fluorophore localization techniques: ~3 μm for double-helix13, ~1 μm for astigmatic14 and ~2 μm for biplane15 imaging.

We also explored MFM of thicker samples with a larger imaging volume of 60 × 60 × 18 μm3 at lower magnification and coarser focal plane separation Δz = 2 μm, to visualize fluorescently labeled neurons in the developing Caenorhabditis elegans embryo (Supplementary Note 4). At nine volumes per second, we were able to image the entire late embryo moving rapidly inside the eggshell (Supplementary Videos 7 and 8), a stage previously inaccessible to full-volume imaging16.

In summary, we have implemented an aberration-corrected multifocus imaging system for fast 3D imaging. Simultaneous acquisition of all focal planes eliminates the spatiotemporal ambiguity of sequentially recorded z stacks. The resolution of the multifocus image is that of the wide-field microscope to which it is appended, and the imaging sensitivity (light efficiency) is currently ~60% of that of the wide-field fluorescence microscope. Field of view and acquisition rate are determined by camera chip size and readout speed. Thanks to its ease of use, compatibility with standard microscopes and excellent imaging performance, MFM should facilitate the rapid acquisition of 3D data from the level of single molecules up to that of small organisms.

METHODS
Methods and any associated references are available in the online version of the paper.

Note: Supplementary information is available in the online version of the paper.

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AUTHOR CONTRIBUTIONS
The optical layout was conceived by M.G.L.G. Optical design and optimizations were made by M.G.L.G. and S.A. S.A. built the system and implemented the hardware control electronics. J.C., B.H. and M.D. performed single-molecule and yeast experiments. S.A., B.H., J.C. and M.D. developed image processing tools, and B.H. and J.C. analyzed the data. S.A. and A.Y.K. acquired the C. elegans data. J.W. and G.M. constructed the yeast strain; J.W. and C.W. participated in centromere imaging. P.S., C.D.D. and X.D. provided the 3D single-emitter detection algorithm. M.G.L.G., D.A.A. and C.I.B. supervised the project. S.A. and M.D. prepared the manuscript.

COMPETING FINANCIAL INTERESTS
The authors declare no competing financial interests.

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ONLINE METHODS
Design of the MFG grating function. In a phase-only diffractive grating, the shape of the grating pattern and its etch depth constitute the grating function and determine the energy distribution between diffractive orders. To optimize light efficiency in MFM, we wished to direct the fluorescence emission light from the sample with maximum efficiency into the orders we chose to image. Furthermore, light should be distributed evenly between these orders so that one can use minimal exposure time to record each multifocus image while still getting sufficient signal in each plane and to obtain an even signal throughout the 3D image.

The amplitude point-spread function (PSF) of an imaging system can be calculated as the square of the Fourier transform of the pupil function. In MFM the pupil function is modified by the phase shift of the MFG, which we can model with a matrix $G$. The altered PSF of an aberration-free microscope in which the MFG is inserted in the Fourier plane is then given by the square of the Fourier transform of the matrix $G$. We have used this property to optimize the grating function (Fig. 1d) as described below. (Similar algorithms have been used before to tailor the PSF of imaging systems.)

We create a matrix $T$ as the target function representing the multifocus PSF we desire. For a system with nine planes, the desired PSF consists of $3 \times 3$ points of maximum brightness and evenness. A starting guess for the phase grating $G$ is made in the form of a matrix of randomly distributed black ($-1$) and white ($+1$) pixels representing phase shifts $\theta$ and $\pi$, respectively. The matrix $G$ is Fourier transformed using the command fht2 (which executes a fast 2D Fourier transform of the matrix $M$). The MFG is inserted in the Fourier plane is then given by the square of the Fourier transform of the matrix $G$. We have used this property to optimize the grating function (Fig. 1d) as described below. (Similar algorithms have been used before to tailor the PSF of imaging systems.)

We start by computing, for each point $(x_p, y_p)$ in the pupil plane, the out-of-focus phase error $\delta \phi(z)$ of the wavefront from a point source located on the optical axis in a plane at defocus $z$ from the nominal focal plane. We let $r_p = \sqrt{x_p^2 + y_p^2}$ denote the radial coordinate position in the pupil and $\rho = r_p/R_p$ the normalized radial coordinate, where $R_p = NA \times f_{obj}$ is the pupil radius and $f_{obj}$ is the focal length of the objective. The numerical aperture is defined as $NA = n \times \sin(\alpha)$, where $n$ is the refractive index of the objective immersion medium (and sample) and $\alpha$ is the highest incident-ray angle collected by the objective. We also use the free-space wave number $k = 2\pi/\lambda$ ($\lambda$ is the sample fluorescence emission wavelength). As illustrated in Supplementary Figure 2b, assuming radial symmetry and using polar coordinates, we calculate the defocus phase error of a ray entering the objective at an angle $\theta (\theta \leq \alpha)$ as

$$\delta \phi(z) = n \times k \times 2 \times \cos(\theta) + \cos(\theta) = \frac{n \times k \times 2 \times \sin^2(\theta)}{\sqrt{1 - \sin^2(\theta)}}$$

Using the Abbe sine condition, which states that $\rho = \sin(\theta)/\sin(\alpha)$, we can relate the angle $\theta$ to radial position $r_p$ in the pupil plane. We use this relation to write

$$\sin^2(\theta) = \frac{\rho^2 \times \sin^2(\alpha)}{\rho^2 = (r_p/R_p)^2} = \frac{(x_p^2 + y_p^2)/(n \times f_{obj})^2 = (x_p^2 + y_p^2)/(y_p) \times (n \times f_{obj})^2}{(x_p^2 + y_p^2)/(n \times f_{obj})^2}$$

Here we have gotten rid of the radial symmetry (to introduce the distortion in $x$ and $y$ individually) by returning to Cartesian coordinates. We can now write the equation for the defocus phase error for a plane at defocus $z$ at every point $(x_p, y_p)$ in the pupil

$$\delta \phi(z) = n \times k \times 2 \times \cos(\theta) + \cos(\theta) = \frac{n \times k \times 2 \times \sin^2(\theta)}{\sqrt{1 - \sin^2(\theta)}}$$

A geometrical distortion $\delta x$ of a periodic grating pattern (with spacing $d$) in the pupil plane introduces a phase shift $\delta \phi$ in the diffracted wavefront, which is dependent on the diffractive order $m_x$, according to

$$\delta \phi_{m_x}(\delta x) = 2\pi \times (\delta x/d) \times m_x$$

To create a multifocus image consisting of $N \times N$ planes with a constant focus step $\delta z$, we impose a local distortion of the MFG grating pattern. (The distortion is applied to a periodic pattern with spacing $d$ of the grating function in Fig. 1d.) To create a proper refocus, the distortion is applied stronger by a factor $N$ in one direction

$$\delta x(x_p, y_p) = (d/2\pi) \times n \times k \times z \times \sqrt{1 - (x_p^2 + y_p^2)/(n \times f_{obj})^2}$$

$$\delta y(x_p, y_p) = N \times \delta x(x_p, y_p)$$
This gives us a total focus shift in each diffractive order \((m_x, m_y)\) of \(\Delta z \times (m_x + N \times m_y)\). For example, with \(N = 3\), the order \((m_x, m_y) = (+1, +1)\) gets focus shifted by \(\Delta z \times (1 + 3 \times 1) = \Delta z \times 4\) and the zeroth order \((0, 0)\) gets no focus shift.

**Chromatic correction.** After the MFG, each horizontal and vertical diffractive order has a dispersion \(\delta \lambda / d\) (where \(d\) is the average grating period of the MFG pattern, and \(\delta \lambda\) is the wavelength bandwidth imaged). Each diagonal order has a dispersion \(\sqrt{2} \times \delta \lambda / d\) due to geometry. If left uncorrected the dispersion would give rise to a severe outward smear in the image (Supplementary Fig. 3a). The CCG is placed at a distance from the MFG so that each order goes through its own designated panel. In the individual blazed grating panels, >95% of the energy is distributed into the −1 (minus one) diffractive order \((m_x, m_y) = (+1, +1)\) gets focus shifted by \(\Delta z \times (1 + 3 \times 1) = \Delta z \times 4\). However, if used alone, the CCG would completely oppose the image-separating action of the MFG, and the diffractive orders would recombine to form a single image in the center of the sensor (Supplementary Fig. 3c). We have therefore added, after the CCG, a nine-faceted refractive prism, which maintains image separation by deflecting the orders while they are still separated (Supplementary Fig. 3b). To reverse the MFG dispersion, the CCG should therefore have a period equal to that of the MFG \((d_{\text{CCG}} = d)\). In summary, when used together, the CCG and the prism correct the chromatic correction module is determined by the efficiency of the blazed grating (better than 95%) and the transmittance of the (AR-coated) prism (also better than 95%).

**Data processing.** To reconstruct the 3D imaging volume from the multifocus image, the nine focal planes were aligned on top of one another using calibration data obtained with 200-nm fluorescent beads (Invitrogen) mounted on a coverslip. We recorded a focal series by scanning the bead sample along the \(z\) axis using a piezoelectric stage (nanoX-200, PiezosystemJena) (Fig. 1g,h). During this process, the beads are successively focused in each of the nine subimages. We then performed a 2D Gaussian fit on the \(z\) projection of each focal plane to locate the beads in the different subimages. Using rotation, translation and stretching of the subimages, we determined a transformation matrix enabling the focal planes to be superimposed with an accuracy of ~10 nm. The transformation matrix was subsequently used on the biological data to reconstruct the 3D volume for each time frame. The calibration data were also used to estimate and correct the small differences in transmitted intensities between images. For 3D particle tracking we used the u-track algorithm (an open-source, multiple-particle tracking software).

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