MHD on Convective Mass Transfer in Annular Flow: Catheter Based Drug Release

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Abstract: In the present study, convective diffusive mass transfer is considered, along with effects of particle drag under the influence of a magnetic field concerning drug delivery in the presence of the catheter. A concentric annular region is created by the presence of a catheter, and the effects of which on mass transfer are considered. A model on the hydrodynamics of the fluid, blood flow, and convective diffusive mass transfer of the species is presented. Here, an attempt is made to analyze a drug delivery method for delivering a drug to a specific site in the body and for this analysis, considered a channel bounded by the tissue region where the drug is targeted. The magnetic field induces pulsatile flow, which affects the mass transfer. The graphs predict that the mass transfer increases from the lumen region to the tissue region. Peclet number and magnetic parameter are the parameters that significantly affect carrying drug towards the tissue. The results are well agreed with the physical phenomena of the problem as well as many biomedical applications.

Keywords: generalized dispersion model; Newtonian fluid; magnetic field; dispersion coefficient; interphase mass transfer.

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1. Introduction

A catheter is a tube that can be inserted into a body cavity, duct, or vessel. It is a thin, flexible tube. A catheter left inside the body either temporarily or permanently is referred to as an indwelling catheter. A catheter can be used for different medicinal applications. It is used to drain urine from the kidney, angioplasty, angiography, measuring blood pressure, etc. It can also be used for the administration of intravenous fluids, medication, or providing nutrition.

The study of convective diffusive mass transfer has an important role in understanding the administration of drugs, transport of LDL, which is the cause of Atherosclerosis, transport of oxygen and nutrients, etc. The intravenous fluid injected gets dispersed and is carried to the tissue region surrounding it. The dispersion of mass in blood vessels is influenced by conductive blood vessel walls examined by Sarkar and Jayaraman et al. [1]. Shankarasubramanian and Gill [2] have analyzed solute dispersion through a circular tube, developing a generalized dispersion model. Mazumdar and Das [3] have studied the effect of wall conductance on the axial dispersion in the pulsatile tube flow.

Jiang and Grotberg [4] studied the dispersion of bolus contaminant in a straight tube with the oscillatory flow and weak conductive walls. Balasubramanian et al. [5] have studied
the combined effect of secondary flows and shown that secondary flow has a negligible effect. Pedley and Kamm [6] studied axial mass transport in an annular region by asymptotic analysis to limit a small annular gap. Srivastava et al. [7] has studied the particle fluid suspension model of blood flow through a stenotic blood vessel. Recently, Umadevi et al. [8] have studied the effect of particle drag using the Gill and Shankarasubramanian model. A similar analysis is done in studying the behavior of dispersion in the case of oscillatory flows in uniform conduits. Also, it is shown that diffusion of heat and other diffusible properties through the interior of the fluid by turbulent motion [9-11]. Pedram and Ehasan [12] have been developed to study nano fluid transportation in bio tissue in the case of magnetic hyperthermia. Kumar et al. [13] studied the magnetic targeting of the drug numerically under the effect of the applied magnetic field. Shah et al. [14] considered an innovative model that has been developed to study the electro-osmotic flow of Couette nanofluids. Kumaresan et al. [15] studied the effect of stenosis on magneto nanoparticles distributions in the presence of the magnetic field. Nadja and Nadji [16] have examined the heat transfer characteristics of various parameters of ferrofluids. Shah et al. [17] used an implicit method (Keller Box) to analyze the nanofluid flow in the case of stretching sheets considering the heat transfer through convection. They concluded that heat transfer varies for different classes of nanofluids. Ibrahim and Gadisa [18] examined the heat transfer rate decreases when the nanoparticle volume fraction increases for cu-water. Naveed Khan et al. [19] considered nanofluid flow in the case of the vertical plate to study the heat generation effects due to natural convection. They proved that as the volume concentration increases, the temperature and heat transfer rate also increases. Meanwhile, Sulochana et al. [20] and Rafique et al. [21] worked on the free convection flow of nanofluids in the case of the vertical plate of infinite length and studied the effects of magnetic field on it. The solution to the problem is obtained using a numerical method.

Many researchers have done extensive work on new manufacturing methods, and new models for non-Newtonian fluids are proposed [22-24]. It is observed that the application of boundary layer theory for the flows is relevant for the flow analysis through annulus in the engineering domain. They are applied in biological fluid movement, manufacturing of glass fiber, and wire drawing.

In the present study, convective diffusive mass transfer is considered, along with the effects of particle drag under the influence of a magnetic field with reference to drug delivery in the presence of a catheter. A concentric annular region is created by the presence of a catheter and the effects on mass transfer.

2. Mathematical Formulation

Consider the physical configuration of the catheterized artery shown in Figure 1. In this diagram, we consider the concentric annular geometry with $R_0$ as the radius of the artery representing the outer tube and $KR_0$ is the radius of the catheter representing the inner tube ($K < 1$). Let us consider the axi symmetric flow in the concentric annulus where the following fluid is a dusty viscous fluid.

We know that diffusive and advective processes govern the mass transport through the artery wall. The most important aspect of drug transport through the wall is the metabolic consumption of drugs by the wall tissue. To avoid the decay of the drug, we apply a first-order reaction and incorporate the external magnetic effect.
The governing equations in cylindrical coordinates \((R, \theta, Z)\) for the above-explained configuration are given by

\[
\rho \frac{\partial w}{\partial t} = -\frac{\partial p}{\partial Z} + \mu \left[ \frac{\partial^2 w}{\partial r^2} + \frac{1}{r} \frac{\partial w}{\partial r} \right] + KN (v - w) - \sigma_0 B^2 w \tag{1}
\]

\[
Nm \frac{\partial w}{\partial t} = KN (w - v) \tag{2}
\]

Where \(\mu\) is the viscosity of the fluid, \(m\) is the Brinkman viscosity of the fluid, \(v\) is the velocity of the dusty particle, \(N\) is the number density of the particle, \(K = 3\mu_d d\) is the stokes drag term, \(d\) is the diameter of the dusty particle, \(Nm\) is the mass of the dusty particle, \(\sigma_0\) is the stress tensor, \(B^2\) is the magnetic effect on the flow, \(w\) is the velocity of the fluid phase, \(p\) is the pressure, and \(\rho\) is the density of the fluid.

To solve (1) and (2) the no-slip boundary conditions are

\[
w = 0 \quad \text{at} \quad R = kR_0 \quad \text{and} \quad R = R_0 \tag{3}
\]

Assuming \(r = \frac{R}{R_0}, w = W(r)e^{-nt}, v = V(r)e^{-nt}, \frac{\partial p}{\partial Z} = -P e^{-nt}\) and eliminating \(v\) from (2), we get

\[
d^2 W \frac{1}{dr^2} + \frac{1}{r} \frac{dW}{dr} + \lambda^2 W = P \tag{4}
\]

Where \(P = -\frac{p}{\mu}, \lambda^2 = \left[ \frac{KN}{\rho} \frac{n\Gamma}{1-n\Gamma} - \frac{\sigma_0 B^2}{\mu} + \frac{\rho n}{\mu} \right], \Gamma = \frac{m}{k}, \lambda\) is the drag parameter, \(\Gamma\) is the relaxation time, \(\rho\) is the pressure gradient, and \(W\) is the non-dimensional velocity of the fluid phase.

Equation (3) in non-dimensional form is

\[
W = 0 \quad \text{at} \quad r = K \tag{5}
\]

\[
\frac{\partial W}{\partial r} = -\alpha W \quad \text{at} \quad r = 1 \tag{6}
\]

The solution of (4) using (5) and (6) is

\[
W(r) = A\text{f}_0(\lambda r) + B\text{Y}_0(\lambda r) \tag{7}
\]

Where \(A = \frac{p}{\lambda^2} \left[ \frac{a(Y_0(\lambda k) - Y_0(\lambda)) - \lambda Y_0(\lambda)}{a\{(Y_0(\lambda k) - Y_0(\lambda)) - \lambda Y_0(\lambda)\} + \lambda \{(Y_1(\lambda k) - Y_1(\lambda)) - \lambda Y_1(\lambda)\}} \right] \tag{8a}\)
3. Dispersion Model

To develop a convective-diffusion model for the physical configuration under study, we consider the convective-diffusion equation in the cylindrical coordinate system \((R, \theta, Z)\) given by

\[
\frac{\partial c}{\partial t} + w(t, R) \frac{\partial c}{\partial z} = D_m \left\{ \left( \frac{\partial^2 c}{\partial R^2} + \frac{1}{R} \frac{\partial c}{\partial R} \right) + \frac{1}{R} \frac{\partial^2 c}{\partial z^2} \right\}
\]

(9)

Where \(t\) is the time, \(c\) is the concentration of the solute, \(R\) is the radial coordinate, \(z\) is the axial coordinate, and \(w\) is the axial velocity.

To solve (9), we define initial and boundary conditions as:

\[
c(0, R, \theta, z) = c_0 \psi_2(z) \zeta_1(R),
\]

(10)

where \(\psi_2(z)\) is a function of \(z\),

\[
\zeta_1(R) = \begin{cases} R_0 & , \quad kR_0 < R \leq aR_0 \\ 0 & , \quad aR_0 < R \leq R_0 \end{cases}.
\]

(11)

\[
\frac{\partial c}{\partial R} = -kc \quad \text{at} \quad R = R_0
\]

(12a)

\[
\frac{\partial c}{\partial R} = 0 \quad \text{at} \quad R = kR_0
\]

(12b)

Non-dimensionalising (9) to (12b) using the following:

\[
c^* = \frac{c}{c_0}, \quad z^* = \frac{z}{D_m R_0 w_0}, \quad r^* = \frac{r}{R_0}, \quad w^* = \frac{w}{W_0}, \quad t^* = \frac{t}{R_0^2/D_m}, \quad P_e = \frac{R_0 w_0}{D_m},
\]

we get

\[
\frac{\partial c^*}{\partial t^*} + w(r, \tau) \frac{\partial c^*}{\partial z^*} = \frac{\partial^2 c^*}{\partial r^2} + \frac{1}{r} \frac{\partial c^*}{\partial r} + \frac{1}{P_e^2} \frac{\partial^2 c^*}{\partial z^2}
\]

(13)

\[
c(0, r, \theta, z) = B_2(z)B_1(r),
\]

(13a)

\[
\frac{\partial c^*}{\partial r^*} = -\beta c \quad \text{at} \quad r = 1
\]

(13b)

\[
\frac{\partial c^*}{\partial r^*} = 0 \quad \text{at} \quad r = k
\]

(13c)

where \(B_1(r) = \begin{cases} 1 & , \quad k < r \leq a \\ 0 & , \quad a < r \leq 1 \end{cases}\)

\(B_2(z) = \frac{\delta(z)}{a^2 P_e}\), \(\tau\) is the non-dimensional time, \(c_0\) is the reference concentration, \(D_m\) is the molecular diffusivity, \(W_0\) is the mean axial velocity, \(R_0\) is the radius of the tube, \(P_e\) is the Peclet number, \(w(r, \tau)\) is the non-dimensional axial velocity, \(\beta\) is the non-dimensional wall reaction parameter.

By using the generalized dispersion model proposed by Gill and Sankarasubramanian (1970) and solving (13) using (13a) to (13c), we get

\[
c(\tau, r, z) = \sum_{n=0}^{\infty} f_n (\tau, r) \frac{\partial c_m}{\partial z^m}
\]

(14)

where the mean concentration ‘\(c_m\)’ is expressed as
\[ c_m = \int_0^{2\pi} \int_0^1 r c \, dr \, d\theta = \frac{2}{(1-k^2)} \int_0^1 r c \, dr \]  

Equation (13) using (14) takes the form

\[ \frac{\partial c_m}{\partial \tau} = \frac{1}{p_e^2} \frac{\partial^2 c_m}{\partial r^2} + \frac{\partial c_m}{\partial r} \int_0^1 U c \, dr \]  

Let us introduce the dispersion coefficient in the model as

\[ \frac{\partial c_m}{\partial \tau} = \sum_{i=0}^\infty M_i(\tau) \frac{\partial c_m}{\partial r^i} \]  

The values of \( M_i(\tau) \)'s can be obtained from the following result:

\[ M_i(\tau) = \frac{2}{(1-k^2)} \frac{\partial}{\partial r} f_i(\tau_1) + \frac{\delta_{i/2}}{p_e^2} - \frac{2}{(1-k^2)} \int_0^1 r w(\tau, r) f_{i-1} \, dr \quad i = 0, 1, 2, \ldots, \]  

Where \( f_{-1} = f_{-2} = 0 \), \( \delta_{i,2} \) is the kronecker delta, \( \frac{2}{(1-k^2)} \frac{\partial}{\partial r} f_i(\tau_1) \) is due to the first-order heterogeneous reaction at the outer wall of the tube.

Truncating higher terms in (17), we get

\[ \frac{\partial c_m}{\partial \tau} = M_0(\tau) c_m + M_1(\tau) \frac{\partial c_m}{\partial r} + M_2(\tau) \frac{\partial^2 c_m}{\partial r^2} \]  

Where \( M_0(\tau) \) is the absorption parameter, \( M_1(\tau) \) is the velocity of the reactive tracer and \( M_2(\tau) \) is a modification in the convective dispersion because of absorption. \( M_1(\tau) \) and \( M_2(\tau) \) are convective and dispersion coefficients respectively. The values of \( M_i(\tau) \) and \( f_k(k = 1, 2, 3, \ldots) \) are required to solve (19).

Substituting (14) in (13) and using (19), we obtain a set of differential equations for \( f_k \) as shown below:

\[ \frac{\partial f_k}{\partial \tau} = \frac{\partial^2 f_k}{\partial r^2} + \frac{1}{r} \frac{\partial f_k}{\partial r} - w(\tau, r) f_{k-1} + \frac{1}{p_e^2} f_{k-2} + \sum_{m=0}^\infty f_{m-i} M_i \quad k = 0, 1, 2, \ldots \]  

To find \( c_m \) and \( f_k \) the required initial and boundary conditions are

\[ c_m(0, z) = \frac{2}{(1-k^2)} \int_0^1 r B_1(\tau) \, dr \]  

\[ c(0, r, z) = f_0(0, r) c_m(0, z) \]  

\[ f_k(0, r) = 0 \quad \text{for} \quad k = 1, 2, 3, \ldots \ldots \]  

\[ f_k(0, r) = \begin{cases} \frac{(1-k^2)}{2} \frac{B_1(r)}{\int_0^1 r B_1(\tau) \, d\tau}, & k = 0 \\ 0, & k \neq 0 \end{cases} \]  

\[ \frac{\partial f_k}{\partial r}(\tau, 1) = -\beta f_k(\tau, 1) \]  

\[ \frac{\partial f_k}{\partial r}(r, n) = 0 \quad \text{for} \quad k = 0, 1, 2, 3, \ldots \]  

Using (15) into (14), we get

\[ \int_0^1 r f_n(\tau, r) \, dr = \frac{(1-k^2)}{2} \delta_{n,0} \]
Since the equations are coupled to find $M_2(\tau)$, we need to find $(f_n, M_n)$ for $n = 0, 1, 2$ in pairs. The functions $f_0$ and exchange coefficient $M_0$ are independent of velocity field and can be solved directly.

From (18), we get

$$M_0(\tau) = \frac{2}{(1-k^2)} \frac{\partial f_0}{\partial \tau}(\tau, 1)$$

(23)

The coefficient $M_0(\tau)$ is decoupled with the equation obtained from (20) given by

$$\frac{\partial f_0}{\partial \tau} = \frac{\partial^2 f_0}{\partial \tau^2} + \frac{1}{r} \frac{\partial f_0}{\partial r} - M_0 f_0$$

(24)

The solution of (24) may be formulated as

$$f_0(\tau, r) = e^{-\int_0^\tau M_0(\eta) d\eta} g_0(\tau, r)$$

(25)

Where $g_0(\tau, r)$ must satisfy $\frac{\partial g_0}{\partial \tau} = \frac{\partial^2 g_0}{\partial \tau^2} + \frac{1}{r} \frac{\partial g_0}{\partial r}$

(26a)

With boundary conditions

$$g_0(0, r) = \frac{(1-k^2)}{2} \frac{B_1(r)}{\int_0^1 r B_1(r) dr},$$

(26b)

$$\frac{\partial g_0}{\partial r}(\tau, 1) = -\beta g_0(\tau, 1),$$

(26c)

$$\frac{\partial g_0}{\partial r}(\tau, k) = 0.$$  

(26d)

The solution of (26a) using (26b) to (26d) is

$$g_0(\tau, r) = \sum_{n=0}^{\infty} \frac{A_n}{J_1(\mu_n r)} E_n(\mu_n r) e^{-\mu_0^2 \tau}$$

(27a)

where

$$A_n = \frac{\mu_n^2 (1-k^2) J_1(\mu_n r) \int_0^1 r B_1(r) E_n(\mu_n r) dr}{\left(\mu_n^2 + \beta^2 E_n(\mu_n r)^2 - k^2 \mu_n^2 (E_n(\mu_n r))^2 \int_0^1 r B_1(r) dr \right)}$$

(27b)

$$E_n(\mu_n r) = Y_0(\mu_n r) J_1(\mu_n r) - Y_1(\mu_n r) J_0(\mu_n r)$$

(27c)

And $\mu_n$'s are eigenvalues satisfying the following equation:

$$\mu_n \left( Y_1(\mu_n r) J_1(\mu_n) - J_1(\mu_n r) Y_1(\mu_n) \right) + \beta \left( Y_0(\mu_n r) J_1(\mu_n k) - Y_1(\mu_n r) J_0(\mu_n r) \right) = 0$$

(27d)

In the above equation $J_0, Y_0$ are Bessel functions of order ZERO and $J_1, Y_1$ are Bessel functions of order ONE.

From (22), we have

$$\int_0^1 r f_0(\tau, r) dr = \frac{(1-k^2)}{2}$$

(28)

Using (25) in (28), we get

$$e^{-\int_0^\tau M_0(\tau) d\tau} = \frac{(1-k^2)}{2} \frac{1}{\int_0^1 r g_0(\tau, r) dr}$$

(29)

From (25) and (29), we obtain $f_0(\tau, r)$ as

$$f_0(\tau, r) = \frac{(1-k^2)}{2} \frac{g_0(\tau, r)}{\int_0^1 r g_0(\tau, r) dr}$$

(30)

From (23) and (30), we obtain
\[ M_0(\tau) = - \frac{\sum_{n=0}^{\infty} A_n e^{-\mu_n^2 \tau}}{\sum_{n=0}^{\infty} A_n e^{-\mu_n^2 \tau}} (\mu_n Y_1(\mu_n) J_1(\mu_n k) - J_1(\mu_n) Y_1(\mu_n k)) e^{-\mu_n^2 \tau} \]  
\hspace{1cm} (31)

During the process of finding the remaining functions \( f_n, M_n \) for \( n = 1, 2, 3, \ldots \), the computation becomes complex. Hence we consider larger time solutions w.r.t steady flow conditions. By this consideration, the defined model represents the asymptotic results under steady flow conditions.

As \( \tau \to \infty \), Equations (30) and (31) give the following asymptotic representations for \( f_0 \) and \( M_0 \).

\[ f_0(\infty, r) = \frac{1-k^2}{2} \frac{\mu_0 [Y_1(\mu_0 r) J_1(\mu_0 k) - J_1(\mu_0) Y_1(\mu_0 k)]}{Y_1(\mu_0) J_1(\mu_0 k) - J_1(\mu_0) Y_1(\mu_0 k)} \]  
\hspace{1cm} (32)

\[ M_0(\infty) = - \mu_0^2 , \]  
\hspace{1cm} (33)

where \( \mu_0 \) is the first (lowest in magnitude) root of equation (27d).

From (20), we have \( f_1(r) \) satisfying the following equation

\[ \frac{\partial^2 f_1}{\partial r^2} + \frac{1}{r} \frac{\partial f_1}{\partial r} + \mu_0 f_1 = w(r) f_0 + M_1 f_0 . \]  
\hspace{1cm} (34)

With boundary conditions

\[ \frac{\partial f_1}{\partial r}(1) = - \beta f_1(1) , \]  
\hspace{1cm} (35a)

\[ \frac{\partial f_1}{\partial r}(k) = 0 , \]  
\hspace{1cm} (35b)

From (18) and (35a) we have

\[ M_1 = - \frac{2}{(1-k^2)} \left[ \beta f_1(1) + \int_k^1 r w(r) f_0 dr \right] \]  
\hspace{1cm} (36)

Equations (34) and (36) are coupled, and equation (36) is not known explicitly as \( f_1(1) \) is unknown at this stage. By multiplying equation (34) with \( r E_0(\mu_0 r) \), and integrating from \( k \) to 1 with respect to \( r \), it is observed that the left-hand side becomes zero leaving the nonzero right-hand side as

\[ M_1(\tau) = - \frac{\int_k^1 r w(r) E_0(\mu_0 r) f_0(r) dr}{\int_k^1 r E_0(\mu_0 r) f_0(r) dr} \]  
\hspace{1cm} giving

\[ M_1(\tau) = \frac{-4 \mu_0 [Y_1(\mu_0) J_1(\mu_0 k) - J_1(\mu_0) Y_1(\mu_0 k)] \int_k^1 r w(r) E_0(\mu_0 r) f_0(r) dr}{(1-k^2) \left[ \mu_0^2 + k^2 \right] E_0(\mu_0 k)^2 - k^2 \mu_0^2 E_0(\mu_0 k)^2} \]  
\hspace{1cm} (37)

Using (34) and (37), we get \( f_1 \) satisfying the boundary conditions (35a) and (35b) as

\[ f_1(r) = \sum_{n=0}^{\infty} \frac{A_{1n} E_n(\mu_0 r)}{J_1(\mu_n k)} \]  
\hspace{1cm} (38)

where

\[ A_{1n} = \left\{ \begin{array}{ll}
\int_k^1 r w(r) + M_0 f_0(r) E_n(\mu_0 r) dr & , \quad \text{for } n \geq 1 \\
\int_k^1 r E_0(\mu_0 r) f_0(r) \sum_{n=1}^{\infty} \frac{A_{1n}}{J_1(\mu_n k)} \int_k^1 r E_n(\mu_0 r) dr & , \quad \text{for } n = 0
\end{array} \right. \]  
\hspace{1cm} (39)

For \( n = 0 \), the expression for \( A_{1n} \) is obtained from equation (22), i.e \( \int_k^1 r f_1 dr = 0 \).
By applying the same procedure used to find $M_1(\tau)$, we obtain $M_2(\tau)$ as

$$M_2(\tau) = \frac{1}{Pe^2} + \frac{-\int_{\Gamma}^1 r[w(r)+M_1(r)] E_0(\mu_0 r) \, dr}{\int_{\Gamma}^1 r E_0(\mu_0 r) f_0(r) \, dr}$$  \hspace{1cm} (40)

### 3. Results and Discussion

A catheter is used for different purposes. The presence of a catheter causes variations in the presence and amount of blood flowing inside, affecting the solute transfer process. The absorption by a wall is enhanced by the presence of a magnetic field which causes more solute to get convected to the wall. Wall absorption parameter $\beta$ affects the exchange coefficient, asymptotic convection, and diffusion coefficients.

Figures 2-4 show the plot of a radial velocity profile for different catheter radius magnetic parameters $M$ and permeability $\alpha$. Increases in catheter radius increase the velocity. This is due to the fact that the area of the cross-section decreases with an increase in catheter radius. But it is necessary to maintain the same amount of fluid flow to facilitate tissue needs around. Hence velocity increases.

As the permeability increases, velocity near the center of the annular region (created by the catheter) increases but closer to the wall of the tissue region (where the drug is targeted), velocity reduces. This is due to the loss of fluid at a permeable wall. The increase in magnetic field causes a pulsatile flow which can be seen in Figure 3. Figures 5 and 6 show convection coefficient versus absorption parameters for different magnetic drag and different permeability. As magnetic field increases, $-M_1$ increases showing more solute gets convected with the fluid, thereby decreasing absorption at the wall. As absorption increases, $-M_1$ decreases showing convection coefficient affects inversely to the solute of absorption.

As permeability increases, convection decreases due to the loss of fluid. Hence increase in the permeability parameter results in a decrease in convection coefficient. Figures 5-6 show a plot of diffusion coefficient versus absorption parameter $\beta$ for different values of a magnetic parameter, permeability, and Peclet number. Diffusion increases with increasing absorption parameters. The diffusion coefficient increases with increased permeability due to enhancement in fluid convection of fluid towards the wall, thereby increasing absorption.

Increase in magnetic field decreases $M_2$ due to the fact that the magnetic field increases the velocity of the fluid, thereby increasing the convection. An increase in Peclet number shows a decrease in diffusion hence decrease in $M_2$. Peclet number and magnetic field influence diffusion significantly. The effect of an increase in a magnetic field is to create pulsatile motion.
5. Conclusions

This paper presents mass transfer in the presence of a catheter and magnetic field. Induced catheter creates an annual region in which mass transfer is studied using modified Gill and Sankarasubramanian model. Magnetic field influences in increasing absorption and convection. An increase in catheter radius increases the velocity. The absorption by a wall is enhanced by the presence of a magnetic field which causes more solute to get convected to the wall. Permeability increases velocity near the center increases but closer to the wall, velocity decreases. Diffusion coefficient increases with an increase in permeability due to enhancement in convection of fluid towards the wall thereby increasing absorption. Peclet number and magnetic field influence diffusion significantly. The effect of an increase in a magnetic field is to create pulsatile motion.

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Conflicts of Interest

The authors declare no conflict of interest.

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