Learning to Win Lottery Tickets in BERT Transfer via Task-agnostic Mask Training

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Abstract

Recent studies on the lottery ticket hypothesis (LTH) show that pre-trained language models (PLMs) like BERT contain matching subnetworks that have similar transfer learning performance as the original PLM. These subnetworks are found using magnitude-based pruning. In this paper, we find that the BERT subnetworks have even more potential than these studies have shown. Firstly, we discover that the success of magnitude pruning can be attributed to the preserved pre-training performance, which correlates with the downstream transferability. Inspired by this, we propose to directly optimize the subnetwork structure towards the pre-training objectives, which can better preserve the pre-training performance. Specifically, we train binary masks over model weights on the pre-training tasks, with the aim of preserving the universal transferability of the subnetwork, which is agnostic to any specific downstream tasks. We then fine-tune the subnetworks on the GLUE benchmark and the SQuAD dataset. The results show that, compared with magnitude pruning, mask training can effectively find BERT subnetworks with improved overall performance on downstream tasks. Moreover, our method is also more efficient in searching subnetworks and more advantageous when fine-tuning within a certain range of data scarcity. Our code will be released upon publication.

1 Introduction

The NLP community has witnessed a remarkable success of pre-trained language models (PLMs). After being pre-trained on unlabelled corpus in a self-supervised manner, PLMs like BERT (Devlin et al., 2019) can be fine-tuned as a universal text encoder on a wide range of downstream tasks. However, the growing performance of BERT is driven, to a large extent, by scaling up the model size, which hinders the fine-tuning and deployment of BERT in resource-constrained scenarios.
ing. We find that there is a correlation, to certain extent, between the performance of a BERT subnetwork on the pre-training task (right after pruning), and its downstream performance (after fine-tuning). As shown by Fig. 1, the OMP subnetworks significantly outperform random subnetworks at 50% sparsity in terms of both MLM loss and downstream score. However, with the increase of model sparsity, the downstream performance and pre-training performance degrade simultaneously. This phenomenon suggests that we might be able to further improve the transferability of BERT subnetworks by discovering the structures that better preserve the pre-training performance.

To this end, we propose to search transferable BERT subnetworks via Task-Agnostic Mask Training (TAMT), which learns selective binary masks over the model weights on pre-training tasks. In this way, the structure of a subnetwork is directly optimized towards the pre-training objectives, which can preserve the pre-training performance better than heuristically retaining the weights with large magnitudes. The training objective of the masks is a free choice, which can be designed as any loss functions that are agnostic to the downstream tasks. In particular, we investigate the use of MLM loss and a loss based on knowledge distillation (KD) (Hinton et al., 2015).

To examine the effectiveness of the proposal, we train the masks on the WikiText dataset (Merity et al., 2017) for language modeling and then fine-tune the searched subnetworks on a wide variety of downstream tasks, including the GLUE benchmark (Wang et al., 2019) for natural language understanding (NLU) and the SQuAD dataset (Rajpurkar et al., 2016) for question answering (QA). The empirical results show that, through mask training, we can indeed find subnetworks with lower pre-training loss and better downstream transferability than OMP and IMP. Compared with IMP, which also involves training (the weights) on the pre-training task, mask training requires much fewer training iterations to reach the same performance. Moreover, the subnetworks found by mask training is generally more robust when being fine-tuned with reduced data, as long as the training data is not extremely scarce.

In summary, our contributions are:

- We find that the pre-training performance of a BERT subnetwork correlates with its downstream transferability, which provides a useful insight for the design of searching methods to find transferable BERT subnetworks.
- Based on the above finding, we propose to search subnetworks by learning binary masks over the weights of BERT, which can directly optimize the subnetwork structure towards the given pre-training objective.
- Experiments on a variety of NLP tasks show that subnetworks found by mask training have better downstream performance than magnitude pruning. This suggests that BERT subnetworks have more potential, in terms of universal downstream transferability, than existing work has shown, which can facilitate our understanding and application of LTH on BERT.

2 Related Work

The lottery ticket hypothesis (Frankle and Carbin, 2019) suggests the existence of matching subnetworks, at random initialization, that can be trained in isolation to reach the performance of the original network. However, the matching subnetworks are found using IMP, which typically requires more training cost than the full network. To overcome this problem, Morcos et al. (2019) proposed to transfer the WT structure from source tasks to related tasks in the computer vision (CV) field.

Some recent works extend the LTH from random initialization to pre-trained initialization. There are two typical setups. The first one searches WTs for each downstream task separately (Prasanna et al., 2020; Chen et al., 2020; Liang et al., 2021). Like the conventional LTH, this setting may suffer from additional searching cost for every new task. The second setup investigates the transfer of WTs between tasks (Chen et al., 2020; Liang et al., 2021). Particularly, Chen et al. (2020) find that WTs obtained in downstream tasks generally underperform WTs derived from the pre-training tasks of MLM, which is universally transferable to other tasks. The same question of transferring WTs found using IMP, which typically requires more training cost than the full network. To overcome this problem, Morcos et al. (2019) proposed to transfer the WT structure from source tasks to related tasks in the computer vision (CV) field.

In the literature of BERT compression, pruning (LeCun et al., 1989; Han et al., 2015) and KD (Hinton et al., 2015) are two widely-studied techniques. BERT can be pruned in either unstructured (Gordon et al., 2020; Sanh et al., 2020; Mao et al., 2020) or structured (Michel et al., 2019; Hou et al., 2020) ways.
2020) ways. Although unstructured pruning is not hardware-friendly for speedup purpose, it is a common setup in LTH, and some recent efforts have been made to support sparse tensor acceleration (Elsen et al., 2020; Xu et al., 2021). In BERT KD, an important question is the selection of knowledge, which includes the soft-labels (Sanh et al., 2019), the hidden state knowledge (Sun et al., 2019; Hou et al., 2020; Liu et al., 2021) and the attention relations (Jiao et al., 2020), among others. In this paper, the hidden state knowledge is used in TAMT.

Binary mask training was first proposed by Mallya et al. (2018) to adapt a learned model to multiple tasks. For each new task the binary masks are trained and stored instead of the weights, so as to save the memory footprint. Recently, Zhao et al. (2020) extend this idea to BERT fine-tuning. The difference between our work and these works is two-fold. First, they learn masks at low sparsity, since their focus is not on model pruning. In comparison, we specially focus on the subnetworks at high sparsities. Moreover, their goal is to save storage through task-specific mask training on every new task, while we perform task-agnostic mask training to search subnetworks with universal transferability to multiple downstream tasks.

Another way to obtain more efficient BERT with the same transferability as the original one is to pretrain a compact model from scratch. This model can be trained either with the MLM objective (Turc et al., 2019) or using pre-trained BERT as the teacher to perform KD (Wang et al., 2020; Sun et al., 2020; Jiao et al., 2020). By contrast, the LTH extracts subnetworks from BERT, which is about exposing the knowledge already learned by BERT, rather than learning new knowledge from scratch. Compared with training a new PLM, the LTH in BERT is still underexplored in the literature.

3 Methodology

3.1 BERT Architecture

BERT consists of an embedding layer and L Transformer layers (Vaswani et al., 2017). Each Transformer layer has two sub-layers: the self-attention layer and the feed-forward network (FFN).

The self-attention layer contains $N_h$ parallel attention heads and each head can be formulated as:

$$\text{Self-Att}_h(H) = \text{softmax} \left( \frac{HW_{Qh} (HW_{Kh})^T}{\sqrt{d_h}} \right) HW_{Vh}$$  

where $H \in \mathbb{R}^{N \times d_H}$ is the input; $d_H$ and $|x|$ are the hidden size and the length of input $x$, respectively. $W_{Qh}, W_{Kh}, W_{Vh} \in \mathbb{R}^{d_H \times d_h}$ are the query, key and value matrices, and $d_h = \frac{d_H}{N_h}$. In practice, the matrices for different heads will be combined into three large matrices $W_{Q,K,V} \in \mathbb{R}^{d_H \times d_H}$. The outputs of the $N_h$ heads are then concatenated and linearly projected by $W_{AO} \in \mathbb{R}^{d_H \times d_H}$ to obtain the final output of the self-attention layer.

The FFN consists of two weight matrices $W_{FI} \in \mathbb{R}^{d_H \times d_f}$, $W_{FO} \in \mathbb{R}^{d_f \times d_H}$ with a ReLU activation in between, where $d_f$ is the hidden dimension of FFN. Dropout (Srivastava et al., 2014), residual connection (He et al., 2016) and layer normalization (Ba et al., 2016) are also applied following each sub-layer. Eventually, for each downstream task, a classifier is used to give the final prediction based on the output of the Transformer module.

3.2 Subnetwork and Magnitude Pruning

Consider a model $f(\cdot; \theta)$ with weights $\theta$, we can obtain its subnetwork $f(\cdot; M \odot \theta)$ by applying a binary mask $M \in \{0, 1\}^{|\theta|}$ to $\theta$, where $\odot$ denotes element-wise multiplication. In terms of BERT, we extract the subnetwork from the pre-trained weights $\theta_0$. Specifically, we consider the matrices of the Transformer sub-layers and the word embedding matrix, i.e., $\theta_0 = \{W_{Emb}\} \cup \{W_{Q}, W_{K}, W_{V}, W_{AO}, W_{FI}, W_{FO}\}_{l=1}^L$.

Magnitude pruning (Han et al., 2015) is initially used to compress a trained neural network by setting the low-magnitude weights to zero. It can be conducted in two different ways: 1) Oneshot magnitude pruning (OMP) directly prunes the trained weights to target sparsity while 2) iterative magnitude pruning (IMP) performs pruning and retraining iteratively until reaching the target sparsity. OMP and IMP are also widely studied in the literature of LTH as the method to find the matching subnetworks, with an additional operation of resetting the weights to initialization.

3.3 Problem Formulation: Transfer BERT Subnetwork

As depicted in Fig. 2, given $N_T$ downstream tasks $T = \{T_i\}_{i=1}^{N_T}$, the subnetwork $f(\cdot; M \odot \theta_0, C_0^T)$ is fine-tuned on each task, together with the randomly initialized task-specific linear classifier $C_i^T$. We formulate the training algorithm for task $T_i$ as a
function $\mathcal{A}_T^t \left( f \left( \cdot ; M \odot \theta_t, C^T_0 \right) \right)$ (e.g., Adam or SGD), which trains the model for $t$ steps and produces $f \left( \cdot ; M \odot \theta_t, C^T_t \right)$. After fine-tuning, the model is evaluated against the metric $\mathcal{E}^T_t \left( f \left( \cdot ; M \odot \theta_t, C^T_t \right) \right)$ (e.g., Accuracy or F1) for task $T_i$.

In this work, we focus on finding a BERT subnetwork, that maximally preserves the overall downstream performance given a particular sparsity $S$, especially at the sparsity that magnitude pruning performs poorly. This can be formalized as:

$$\max_M \left( \frac{1}{N_T} \sum_{t=1}^{N_T} \mathcal{E}^T_t \left( \mathcal{A}_T^t \left( f \left( \cdot ; M \cdot \theta_0, C^T_0 \right) \right) \right) \right)$$

subject to $\left\| M \right\|_0 \left/ \left| \theta_0 \right| \right. = (1 - S)$

where $\left. \left\| M \right\|_0 \right\|$ and $\left| \theta_0 \right|$ are the $L_0$ norm of the mask and the total number of model weights respectively.

### 3.4 Task-agnostic Mask Training

#### 3.4.1 Mask Training with Binarization and Gradient Estimation

In order to learn the binary masks, we adopt the technique for training binarized neural networks (Hubara et al., 2016), following Zhao et al. (2020); Mallya et al. (2018). This technique involves mask binarization in the forward pass and gradient estimation in the backward pass.

As shown in Fig. 2, each weight matrix $W \in \mathbb{R}^{d_{in} \times d_{out}}$ is associated with a binary mask $M \in \{0, 1\}^{d_{in} \times d_{out}}$, which is derived from a real-valued matrix $\widetilde{M} \in \mathbb{R}^{d_{in} \times d_{out}}$ via binarization:

$$M_{i,j} = \begin{cases} 1 & \text{if } \tilde{M}_{i,j} \geq \phi \\ 0 & \text{otherwise} \end{cases}$$

where $\phi$ is the threshold that controls the sparsity. In the forward pass of a subnetwork, $W \odot M$ is used in replacement of the original weights $W$.

Since $M_{i,j}$ are discrete variables, the gradient signals cannot be back-propagated through the binary mask. We therefore use the straight-through estimator (Bengio et al., 2013) to approximate the gradients and update the real-valued mask:

$$\widetilde{M} \leftarrow \widetilde{M} - \eta \frac{\partial \mathcal{L}}{\partial \widetilde{M}}$$

where $\mathcal{L}$ is the loss function and $\eta$ is the learning rate. In other words, the gradients of $\widetilde{M}$ is estimated using the gradients of $M$. In the process of mask training, all the original weights are frozen.

### 3.4.2 Mask Initialization and Sparsity Control

The real-valued masks can be initialized in various forms, e.g., random initialization. Considering that magnitude pruning can preserve the pre-training knowledge to some extent, and OMP is easy to implement with almost zero computation cost, we directly initialize $\widetilde{M}$ using OMP:

$$M_{i,j} = \begin{cases} \alpha \times \phi & \text{if } \widetilde{M}_{i,j}^{OMP} = 1 \\ 0 & \text{otherwise} \end{cases}$$
where $\mathbf{M}^{\text{OMP}}$ is the binary mask derived from OMP and $\alpha \geq 1$ is a hyper-parameter. In this way, the weights with large magnitudes will be retained at initialization according to Eq. 3, because the corresponding $\overline{\mathbf{M}}_{l,j} = \alpha \times \phi \geq \phi$. In practice, we perform OMP over the weights locally based on the given sparsity, which means the magnitudes are ranked inside each weight matrix.

As $\mathbf{M}$ being updated, some of its entries with zero initialization will gradually surpass the threshold, and vice versa. If the threshold $\phi$ is fixed throughout training, there is no guarantee that the binary mask will always satisfy the given sparsity. Therefore, we rank $\overline{\mathbf{M}}_{l,j}$ according to their absolute values during mask training, and dynamically adjust the threshold to satisfy the sparsity constraint.

### 3.4.3 Mask Training Objectives

We explore the use of two objectives for mask training, namely the MLM loss and the KD loss.

The MLM is the original task used in BERT pre-training. It randomly replaces a portion of the input tokens with the [MASK] token, and requires the model to reconstruct the original tokens based on the entire masked sequence. Concretely, the MLM objective is computed as cross-entropy loss on the predicted masked tokens. During MLM learning, we allow the token classifier (i.e., the $C^{\text{mlm}}$ in Fig. 2) to be trainable, in addition to the masks.

In KD, the compressed model (student) is trained with supervision from the original model (teacher). Under our framework of mask training, the training signal can also be derived from the unpruned BERT. To this end, we design the KD objective by encouraging the subnetwork to mimic the representations of the original BERT, which is shown to be a useful source of knowledge in BERT KD (Sun et al., 2019; Hou et al., 2020). Specifically, the distillation loss is formulated as the cosine similarity between the teacher’s and student’s representations:

$$L_{\text{distill}} = \frac{1}{L|x|} \sum_{l=1}^{L} \sum_{i=1}^{|x|} (1 - \cos (\mathbf{H}_{t,i}^T, \mathbf{H}_{s,i}^S))$$

where $\mathbf{H}_{t,i}$ is the hidden state of the $i^{th}$ token at the $l^{th}$ layer; $T$ and $S$ denote the teacher and student respectively; $\cos(\cdot, \cdot)$ is the cosine similarity.

### 4 Experiments

#### 4.1 Experimental Setups

#### 4.1.1 Models

We examine two PLMs from the BERT family, i.e., BERT$_{\text{BASE}}$ (Devlin et al., 2019) and RoBERTa$_{\text{BASE}}$ (Liu et al., 2019). They have basically the same structure, while differ in the vocabulary size, which results in approximately 110M and 125M parameters respectively. The main results of Section 4.2.1 study both two models. For the analytical studies, we only use BERT$_{\text{BASE}}$.

#### 4.1.2 Baselines, Datasets and Evaluation

We compare our mask training method with IMP, OMP as well as subnetworks with random structures. Following Chen et al. (2020), we use the MLM loss during IMP training.

We build our pre-training set using the WikiText-103 dataset (Merity et al., 2017) for language modeling. For downstream fine-tuning, we use six datasets, i.e., CoLA, SST-2, RTE, MNLI, MRPC and STS-B from the GLUE benchmark for NLU and the SQuAD v1.1 dataset for QA.

Evaluations are conducted on the dev sets. For the downstream tasks, we follow the standard evaluation metrics (Wang et al., 2019). For the pre-training tasks, we calculate the dev loss of MLM/KD for the subnetworks $f(\cdot, \mathbf{M} \odot \theta_0)$. More information about the datasets and evaluation metrics can be found in Appendix B.

#### 4.1.3 Implementation Details

Both TAMT and IMP are conducted on the pre-training dataset. For mask training, we initialize the mask using OMP as described in Section 3.4.2. The threshold $\phi$ and $\alpha$ are set to $1e-2$ and 2 respectively, which work well in our experiments. For IMP, we increase the sparsity by 10% every 1/10 of total training iterations, until reaching the target sparsity, following Chen et al. (2020). Every pruning operation in IMP is followed by resetting the remaining weights to $\theta_0$. In the fine-tuning stage, all the subnetworks and the full PLMs are trained using the same set of hyper-parameters unless otherwise specified.

For TAMT, IMP and random pruning, we generate three subnetworks with different seeds, and the result of each subnetwork is also averaged across three runs, i.e., the result of every method is the average of nine runs in total. For OMP, we can only generate one subnetwork, which is fine-tuned.
across three runs. More implementation details and computing budgets can be found in Appendix C.

4.2 Results and Analysis

4.2.1 Main Results

Fig. 3 presents the downstream performance of BERT and RoBERTa subnetworks across sparsities. We can derive the following observations:

There is a clear gap between random subnetworks and the other ones found with certain inductive bias. At 50% sparsity for BERT and 20% for RoBERTa, all the methods, except for “Rand”, maintain 90% of the full model’s overall performance. As sparsity grows, the OMP subnetworks degrade significantly. IMP, which is also based on magnitude, exhibits relatively mild declines.

TAMT further outperforms IMP with perceivable margin. At 60% ~ 70% sparsity for BERT and 40% ~ 60% for RoBERTa, both TAMT-MLM and TAMT-KD have advantage over IMP. At higher sparsity level (e.g., 80%), the performance of TAMT-KD is undesirable, which is only comparable with IMP. In comparison, TAMT-MLM consistently surpasses the other methods.

At 90% sparsity, all the methods perform poorly, with average scores approximately half of the full model. On certain tasks like RTE and MRPC, such failure of all methods can even be observed at lower sparsity (e.g., 60% ~ 80%). This is probably because the number of training data is too scarce in RTE and MRPC for sparse PLMs to perform well. However, we find that the strength of TAMT is more significant within a range of data scarcity, which will be discussed in Section 4.2.5.

We also note that RoBERTa, although outperforms BERT as a full model, is more sensitive to task-agnostic pruning. A direct comparison between the two PLMs is provided in Appendix D.

4.2.2 The Effect of Pre-training Performance

As we discussed in Section 1, our motivation of mask training is to improve downstream transferability by preserving the pre-training performance. To examine whether the effectiveness of TAMT, is indeed derived from the improvement on pre-training tasks, we calculate the MLM/KD dev loss for the subnetworks obtained from the mask training process, and associate it with the downstream performance. The results of TAMT, IMP, OMP, random pruning and the full BERT, are shown in Fig. 4, from which we can see that:
There is a positive correlation between the pre-training and downstream performance, and this trend can be observed for subnetworks across different sparsities. Compared with random pruning, the magnitude pruning subnetworks and TAMT subnetworks reside in an area with lower MLM/KD loss and higher downstream score at 50% sparsity. As sparsity increases, OMP subnetworks gradually move from the upper-left to the lower-right area of the plots. In comparison, IMP is better at preserving the pre-training performance, even though it is not deliberately designed for this purpose. For this reason, hypothetically, the downstream performance of IMP is also better than OMP.

TAMT-MLM and TAMT-KD have the lowest MLM and KD loss respectively, which demonstrates that the masks are successfully optimized towards the given objectives. As a result, the downstream performance is also elevated from the OMP initialization, which justifies our motivation. Moreover, training the mask with KD loss can also optimize the performance on MLM, and vice versa, suggesting that there exists some consistency between the objectives of MLM and KD.

It is also worth noting that the correlation between pre-training and fine-tuning performance is not ubiquitous. For example, among the subnetworks of OMP, IMP and TAMT at 50% sparsity, the decrease in KD/MLM loss produces little or no downstream improvement; at 60% ~ 80% sparsity, OMP underperforms random pruning in MLM, while its downstream performance is better. These phenomena suggest that some properties about the BERT winning tickets are still not well-understood by us.

4.2.3 The Effect of Pre-training Cost

We have shown that mask training is more effective than magnitude pruning. Now let us take a closer look at the results of TAMT and IMP with different iterations of pre-training, to evaluate their efficiency in subnetwork searching. For TAMT, we directly obtain the subnetworks from varied pre-training iterations. For IMP, we change the pruning frequency to control the number of training iterations before reaching the target sparsity.

Fig. 5 presents the downstream results with increased pre-training cost. The training time is computed excluding evaluation. Shadowed areas denote standard deviations. Results for each task and more sparsities are shown in Appendix F.
4.2.4 Similarity between Subnetworks

The above results show that the subnetworks found by different methods perform differently. We are therefore interested to see how they differ in the mask structure. To this end, we compute the similarity between OMP mask and the masks derived during the training of TAMT and IMP. Following Chen et al. (2020), we define the similarity between two binary masks $M_i$ and $M_j$ as $\frac{M_i \cap M_j}{M_i \cup M_j}$, and the mask distance as $1 - \frac{M_i \cap M_j}{M_i \cup M_j}$.

From the results of Fig. 6, we can find that: 1) With different objectives, TAMT produces different mask structures. The KD loss results in masks in the close proximity of OMP initialization, while the MLM masks deviate away from OMP. 2) Among the four methods, IMP and TAMT-MLM have the highest degree of dissimilarity, despite the fact that they both involve MLM training. 3) Although IMP, TAMT-KD and TAMT-MLM are different from each other in terms of subnetwork structure, all of them clearly improves over the OMP baseline. Therefore, we hypothesize that the high-dimensional binary space $\{0, 1\}^\theta$ might contain multiple regions of winning tickets that are disjoint with each other. Searching methods with different inductive biases (e.g., mask training versus pruning and KD loss versus MLM loss) are inclined to find different regions of interest.

4.2.5 Results of Reducing Fine-tuning Data

To test the fine-tuning results with reduced data, we select four tasks (CoLA, SST-2, MNLI and SQuAD) with the largest data sizes and shrink them from original training set to 1,000 samples.

Fig. 7 summarizes the results. We can see that the four datasets present different patterns. For MNLI and SQuAD, the advantage of TAMT first increases and then decreases with the reduction of data size. The turning point appears at around 10,000 samples, after which the performance of all methods degrade drastically. For SST-2, the performance gap is enlarged continuously until we have only 1,000 data. With regard to CoLA, the performance of TAMT is not desirable as we reduce the data size. This is in part because the Mcc of IMP is already quite low with the full dataset, and thus the performance decrease of IMP is limited compared with TAMT. However, as we discussed in the main results, the fundamental reason of the results on CoLA, as well as the results on MNLI and SQuAD under extreme data scarcity, is probably the inherent difficulty of learning with limited data for subnetworks at high sparsity.

5 Conclusions

In this paper, we address the problem of searching transferable BERT subnetworks. We first show that there exist correlations between the pre-training performance and downstream transferability of a subnetwork. Motivated by this, we devise a subnetwork searching method based on task-agnostic mask training (TAMT). We empirically show that TAMT with MLM loss or KD loss achieve better pre-training and downstream performance than the magnitude pruning, which is recently shown to be successful in finding universal BERT subnetworks. TAMT is also more efficient in mask searching and produces more robust subnetworks when being fine-tuned within a certain range of data scarcity.
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A Single Task Downstream Performance of OMP and Random Pruning

In Fig. 1 of the main body of paper, we show that the pre-training and overall downstream performance of OMP, as well as the gap between “OMP” and “Rand”, degrade simultaneously as sparsity increases. The detailed results of each downstream task are presented in Fig. 8. As we can see, the general pattern for every task is similar, with the exception that the gap between “OMP” and “Rand” slightly Increases before high sparsity on tasks RTE, MNLI and SQuAD.

B More Information about Datasets and Evaluation

For pre-training, we adopt the WikiText-103 dataset 1 for language modeling. WikiText-103 is a collection of articles on Wikipedia and has over 100M tokens. Such data scale is relatively small for PLM pre-training. However, we find that it is sufficient for mask training and IMP to discover subnetworks with perceivable downstream improvement.

For the downstream tasks, we use six datasets from the GLUE benchmark and the SQuAD v1.1 dataset 2. The GLUE benchmark is intended to train, evaluate, and analyze NLU systems. Our experiments include the tasks of CoLA for linguistic acceptability, SST-2 for sentiment analysis, RTE and MNLI for natural language inference, MRPC and STS-B for semantic matching/similarity. The

1WikiText-103 is available under the Creative Commons Attribution-ShareAlike 4.0 License (https://en.wikipedia.org/wiki/Wikipedia:Text_of_Creative_Commons_Attribution-ShareAlike_4.0_Unported_License)

2SQuAD is available under the CC BY-SA 4.0 license.
The hyper-parameters for pre-training and fine-tuning are shown in Tab. 1. The pre-training setups of IMP basically follow (Chen et al., 2020), except for the number of training epochs, because we set the maximum number of pre-training epochs to 10% every 2 iterations of TAMT accordingly. Specifically, we control the number of pre-training iterations (i.e., the number of gradient descent steps) to be the same. Considering that the IMP subnetworks of different sparsities are obtained from different pre-training iterations, we adjust the pre-training iterations of TAMT accordingly. Specifically, we control the number of pre-training iterations to 2 for IMP, which equals to 27.92K training iterations. Thus, the sparsity is increased by 10% every 2.792K iterations. Tab. 2 shows the number of pre-training iterations for IMP and TAMT subnetworks at 20% ~ 90% sparsity. Note that the final training iteration does not equal to 27.92K at 100% sparsity according to Tab. 2. This is because we prune to 10% sparsity at the 0th iteration, which follows the implementation of Chen et al. (2020).

The hyper-parameters for downstream fine-tuning follow the standard setups of (Wolf et al., 2020; Chen et al., 2020). We use the same set of hyper-parameters for all the subnetworks, as well as the full models. We perform evaluations dur-
### Table 2: Pre-training iterations for IMP and TAMT subnetworks at 20% ~ 90% sparsity.

| Sparsity | IMP | TAMT-MLM | TAMT-KD |
|----------|-----|----------|---------|
| 20%      | 2.79K | 3K       | 3K      |
| 30%      | 5.58K | 6K       | 6K      |
| 40%      | 8.38K | 8K       | 8K      |
| 50%      | 11.17K| 11K      | 11K     |
| 60%      | 13.96K| 14K      | 14K     |
| 70%      | 16.75K| 17K      | 17K     |
| 80%      | 19.54K| 20K      | 20K     |
| 90%      | 22.34K| 22K      |         |

### Table 3: Pre-training time (w/o evaluation during training) of IMP and TAMT on a single 32GB Nvidia V100 GPU. “h”, “m” and “s” denote hour, minute and second, respectively. The pre-training iterations are 22.34K and 22K for IMP and TAMT respectively, which correspond to the 90% sparsity in Tab. 2.

| PLM         | IMP Time | TAMT-MLM Time | TAMT-KD Time |
|-------------|----------|---------------|--------------|
| BERT_BASE   | 4h6m26s  | 3h54m58s      | 4h46m46s     |
| RoBERTa_BASE| 4h33m9s  | 4h17m15s      | 4h51m55s     |

D **Comparison Between BERT and RoBERTa Subnetworks**

In the main results of Fig. 3, we compare the fine-tuning performance of subnetworks of the same PLM but found using different methods. In this section, we give a comparison between subnetworks of BERT<sub>BAS</sub>E and RoBERTa<sub>BAS</sub>E. As shown in Fig. 9, RoBERTa consistently outperforms BERT as a full model. However, as we prune the pre-trained weights according to the magnitudes, the performance of RoBERTa declines more sharply than BERT, leading to worse results of RoBERTa subnetworks when crossing a certain sparsity threshold. This phenomenon suggests that, compared with BERT, RoBERTa is less robust to task-agnostic magnitude pruning. More empirical and theoretical analysis are required to understand the underlying reasons.

E **Pre-training Performance and Single Task Downstream Performance**

The relation between pre-training performance and overall downstream performance is illustrated in Fig. 4. Here in this appendix, we provide the detailed results about each single downstream task, as shown in Fig. 10 and Fig. 11. As we can see, the pattern in each single task is general the same as we discussed in Section 4.2.2. When the model sparsity is higher than 50%, TAMT promotes the performance of OMP in terms of both pre-training tasks and downstream tasks, and improves over IMP with perceivable margin. As shown in Fig. 3 of the main paper, both IMP and TAMT display no obvious improvement over OMP on MRPC and RTE (but no degradation as well). Therefore, we do not report the comparison on these two datasets.

F **Pre-training Iteration and Single Task Downstream Performance**

In Fig. 5, we show the overall downstream performance at 70% sparsity with the increase of mask training iterations. Here, we report the results of each single downstream task from 60% ~ 80% sparsities, which are shown in Fig. 12, Fig. 13 and Fig. 14. We can see that: 1) The single task performance of both TAMT-MLM and TAMT-KD grows faster than IMP at 60% and 70% sparsity, with the only exception of STS-B, where the three methods are comparable. 2) The MLM and KD objectives are good at different sparsity levels and different tasks. TAMT-KD performs the best at 60% sparsity, surpassing TAMT-MLM on CoLA, SST-2 and MNLI. In contrast, TAMT-MLM is better at higher sparsities. 3) At 80% sparsity, the searching efficiency of the KD objective is not desirable, which requires more pre-training steps to outperform IMP on CoLA and SQuAD and lags behind on STS-B. However, the advantage of TAMT-MLM is consistent across the five tasks at 80% sparsity.

G **Subnetwork Similarity at Different Sparsities**

In Section 4.2.4, we analyse the similarity between subnetworks at 70% sparsity. In Fig. 15, we...
present additional results of subnetworks at different sparsities. We can see that the general pattern, as discussed in Section 4.2.4, is the same across 60%, 70% and 80% sparsities. However, as sparsity grows, different searching methods becomes more distinct from each other. For instance, the similarity between TAMT-MLM and IMP subnetworks decreases from 0.75 at 60% sparsity to less than 0.6 at 80% sparsity. This is understandable because the higher the sparsity, the lower the probability that two subnetworks will share the same weight.
Figure 9: Downstream performance of BERT and RoBERTa subnetworks found using OMP. Shadowed areas denote standard deviations.

Figure 10: MLM dev loss and single task downstream performance of BERT\textsubscript{BASE} subnetworks. The results of TAMT are obtained from the masks along the training process, and the results of IMP and Rand are from different seeds.
Figure 11: KD dev loss and single task downstream performance of BERT\textsubscript{BASE} subnetworks. The results of TAMT are obtained from the masks along the training process, and the results of IMP and Rand are from different seeds.

Figure 12: The downstream performance of 60% sparse BERT\textsubscript{BASE} subnetworks on each single task, with increased pre-training iterations.
Figure 13: The downstream performance of 70% sparse BERT\textsubscript{BASE} subnetworks on each single task, with increased pre-training iterations.

Figure 14: The downstream performance of 80% sparse BERT\textsubscript{BASE} subnetworks on each single task, with increased pre-training iterations.
Figure 15: Upper: The downstream performance of masks with varying distances from the OMP mask. Shadowed areas denote standard deviations. Lower: The similarity between masks searched using different methods. The masks are the same as those used to report the main results. The suffix numbers indicate different seeds. The masks are from BERT_{BASE}. 