Semidefinite code bounds based on quadruple distances

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Abstract. Let $A(n,d)$ be the maximum number of 0,1 words of length $n$, any two having Hamming distance at least $d$. We prove $A(20,8) = 256$, which implies that the quadruply shortened Golay code is optimal. Moreover, we show $A(20,6) \leq 2279$, $A(23,6) \leq 13674$, $A(19,8) \leq 135$, $A(25,8) \leq 5421$, $A(26,8) \leq 9275$, $A(21,10) \leq 47$, $A(22,10) \leq 84$, $A(24,10) \leq 268$, $A(25,10) \leq 466$, $A(26,10) \leq 1237$, $A(27,10) \leq 1585$, $A(25,12) \leq 55$, and $A(26,12) \leq 96$.

The method is based on the positive semidefiniteness of matrices derived from quadruples of words. This can be put as constraint in a semidefinite program, whose optimum value is an upper bound for $A(n,d)$. The order of the matrices involved is huge. However, the semidefinite program is highly symmetric, by which its feasible region can be restricted to the algebra of matrices invariant under this symmetry. By block diagonalizing this algebra, the order of the matrices will be reduced so as to make the program solvable with semidefinite programming software in the above range of values of $n$ and $d$.

Key words: error-correcting, code, semidefinite, programming, algebra

1. Introduction

For any $k$, we will identify elements $\{0,1\}^k$ with 0,1 words of length $k$. The Hamming distance $d_H(v,w)$ between two words $v,w$ is the number of $i$ with $v_i \neq w_i$.

Throughout we denote

$$N := \{0,1\}^n.$$ (1)

A code of length $n$ is any subset $C$ of $N$. The minimum distance of a code $C$ is the minimum Hamming distance between any two distinct elements of $C$. Then $A(n,d)$ denotes the maximum size (= cardinality) of a code of length $n$ with minimum distance at least $d$.

Computing $A(n,d)$ and finding upper and lower bounds for it have been long-time focuses in combinatorial coding theory (cf. MacWilliams and Sloane [11]). Classical is Delsarte’s bound [3]. Its value can be described as the maximum $A_2(n,d)$ of $\sum_{u,v \in N} X_{u,v}$, where $X$ is a symmetric, nonnegative, positive semidefinite $N \times N$ matrix with trace 1 and with $X_{u,v} = 0$ if $u,v \in N$ are distinct and have distance less than $d$. Then $A(n,d) \leq A_2(n,d)$, since for any nonempty code $C$ of minimum distance at least $d$, the matrix $X$ with $X_{u,v} = |C|^{-1}$ if $u,v \in C$ and $X_{u,v} = 0$ otherwise, is a feasible solution with objective value $|C|$.

This is the analytic definition of the Delsarte bound (in the vein of Lovász [9], cf. [12], [16]). It is a semidefinite programming problem, but of huge dimensions ($2^n$), which makes it hard to compute in this form.
However, the problem is highly symmetric. The group $G$ of distance preserving permutations of the set $N$ acts on the set of optimum solutions: if $(X_{u, v})$ is an optimum solution, then also $(X_{\pi(u), \pi(v)})$ is an optimum solution for any $\pi \in G$. Hence, as the set of optimum solutions is convex, by averaging we obtain a $G$-invariant optimum solution $X$. That is, $X_{\pi(u), \pi(v)} = X_{u, v}$ for all $u, v$ and all $\pi \in G$. So $X_{u, v}$ depends only on the Hamming distance of $u$ and $v$, hence there are in fact at most $n + 1$ variables. Since (in this case) the algebra of $G$-invariant matrices is commutative, it implies that there is a unitary matrix $U$ such that $U^* X U$ is a diagonal matrix for each $G$-invariant $X$. It reduces the semidefinite constraints of order $2^n$ to $2^n$ linear constraints, namely the nonnegativity of the diagonal elements. As the space of $G$-invariant matrices is $n + 1$-dimensional, there are in fact only $n + 1$ different linear constraints, hence it reduces to a small linear programming problem.

So the Delsarte bound is initially a huge semidefinite program in variables associated with pairs and singletons of words in $N$, that can be reduced to a small linear program, with a small number of variables. In [17] this method was generalized to semidefinite programs in variables associated with sets of words of size at most 3. In that case, the programs can be reduced by block diagonalization to a small semidefinite program, with a small number of variables. A reduction to a linear program does not work here, as in this case the corresponding algebra is not commutative. This however is not a real bottleneck, as like for linear programming there are efficient (polynomial-time) algorithms for semidefinite programming.

In the present paper we extend this method to quadruples of words. Again, by a block diagonalization, the order of the size of the semidefinite programs is reduced from exponential size to polynomial size. We will give a more precise description of the method in Section 2.

The reduced semidefinite programs still tend to get rather large, but yet for $n$ up to 28 and several values of $d$, we were able to solve the associated semidefinite programming up to (more than) enough precision, using the semidefinite programming algorithm SDPA. It gives the new upper bounds $A_4(n, d)$ for $A(n, d)$ displayed in Table 1. One exact value follows, namely $A(20, 8) = 256$. It means that the quadruply shortened Golay code is optimum. In the table we give also the values of the new bound where it does not improve the currently best known bound, as in many of such cases the new bound confirms or is very close to this best known bound.

Since $A(n, d) = A(n + 1, d + 1)$ if $d$ is odd, we can restrict ourselves to $d$ even. We refer to the websites maintained by Erik Agrell [1] and Andries Brouwer [2] for more background on the known upper and lower bounds displayed in the table.

In the computations, the accuracy of the standard double precision version of SDPA (already considered in the comparison [13]) was insufficient for several of the cases solved here. The semidefinite programs generated appear to have rather thin feasible regions so that SDPA and the other high-quality but double precision codes terminate prematurely with large infeasibilities. We have used the multiple precision versions of SDPA developed by M. Nakata for quantum chemistry computations in [15]. Fortunately, the quadruple precision version was sufficient in all cases tabulated. The even higher precision versions as also implemented by the second author for interactive use at the NEOS Server [14] would have needed excessive computing times. Still, the times needed in Table 1 below varied from a few hours for the small cases to $1\frac{1}{2}$ days for $A_4(20, 4)$, 13 days for $A_4(23, 6)$, 22
Table 1. Bounds for $A(n, d)$

| $n$ | $d$ | known lower bound | known upper bound | new upper bound | $A_4(n, d)$ |
|-----|-----|-------------------|-------------------|----------------|------------|
| 17  | 4   | 2720              | 3276              | 3276.800       |
| 18  | 4   | 5312              | 6552              | 6553.600       |
| 19  | 4   | 10496             | 13104             | 13107.200      |
| 20  | 4   | 20480             | 26168             | 26214.400      |
| 21  | 4   | 36864             | 43688             | 43690.667      |
| 17  | 6   | 256               | 340               | 351.506        |
| 18  | 6   | 512               | 680               | 673.005        |
| 19  | 6   | 1024              | 1280              | 1237.939       |
| 20  | 6   | 2048              | 2372              | 2279.758       |
| 21  | 6   | 2560              | 4096              | 4096.000       |
| 22  | 6   | 4096              | 6941              | 6943.696       |
| 23  | 6   | 8192              | 13766             | 13674.962      |
| 17  | 8   | 36                | 37                | 38.192         |
| 18  | 8   | 64                | 72                | 72.998         |
| 19  | 8   | 128               | 142               | 135.710        |
| 20  | 8   | 256               | 274               | 256.000        |
| 21  | 8   | 4096              | 5477              | 5421.499       |
| 22  | 8   | 4096              | 9672              | 9275.544       |
| 23  | 8   | 4096              | 13766             | 13674.962      |
| 24  | 8   | 4096              | 9672              | 9275.544       |
| 21  | 10  | 42                | 48                | 47.007         |
| 22  | 10  | 64                | 87                | 84.421         |
| 23  | 10  | 80                | 150               | 151.324        |
| 24  | 10  | 128               | 280               | 268.812        |
| 25  | 10  | 192               | 503               | 466.809        |
| 26  | 10  | 384               | 886               | 836.669        |
| 27  | 10  | 512               | 1764              | 1585.071       |
| 25  | 12  | 52                | 56                | 55.595         |
| 26  | 12  | 64                | 98                | 96.892         |
| 27  | 12  | 128               | 169               | 170.667        |
| 28  | 12  | 178               | 288               | 288.001        |

days for $A_4(25, 8)$, 30 days for $A_4(27, 10)$, and 43 days for $A_4(26, 8)$.

The approach outlined above of course suggests a hierarchy of upper bounds by considering sets of words of size at most $k$, for $k = 2, 3, 4, \ldots$. This connects to hierarchies of bounds for 0.1 programming problems developed by Lasserre [7], Laurent [8], Lovász and Schrijver [10], and Sherali and Adams [19]. The novelty of the present paper lies in exploiting the symmetry and giving an explicit block diagonalization that will enable us to calculate the bounds.

In fact, the relevance of the present paper might be three-fold. First, it may lie in coding
and design theory, as we give new upper bounds for codes and show that the quadruply shortened Golay code is optimal. Second, the results may be of interest for algebraic combinatorics (representations of the symmetric group and extensions), as we give an explicit block diagonalization of the centralizer algebra of groups acting on pairs of words from \( N \).

Third, the relevance may come from semidefinite programming theory and practice, by exploiting symmetry and reducing sizes of programs, and by gaining insight into the border of what is possible with current-state semidefinite programming software, both as to problem size, precision, and computing time.

We do not give explicitly all formulas in our description of the method, as they are sometimes quite involved, rather it may serve as a manual to obtain an explicit implementation, which should be straightforward to derive.

2. The bound \( A_k(n, d) \)

For any \( n, d, k \in \mathbb{Z}_+ \), we define the number \( A_k(n, d) \) as follows. Let \( \mathcal{N} \) be the collection of codes \( S \subseteq N \) of minimum distance at least \( d \). (Recall that \( N = \{0, 1\}^n \).) For any \( t \), let \( N_t \) be the collection of \( S \in \mathcal{N} \) with \( |S| \leq t \).

For \( S \in \mathcal{N}_k \), define

\[
\mathcal{N}(S) := \{ S' \in \mathcal{N} \mid S \subseteq S', |S| + 2|S' \setminus S| \leq k \}.
\]

The rationale of this definition is that \( |S' \cup S''| \leq k \) for all \( S', S'' \in \mathcal{N}(S) \).

For \( x : \mathcal{N}_k \to \mathbb{R} \) and \( S \in \mathcal{N}_k \), let \( M_S(x) \) be the \( \mathcal{N}(S) \times \mathcal{N}(S) \) matrix given by

\[
M_S(x)_{S', S''} := \begin{cases} 
  x(S' \cup S'') & \text{if } S' \cup S'' \in \mathcal{N}, \\
  0 & \text{otherwise},
\end{cases}
\]

for \( S', S'' \in \mathcal{N}(S) \). Define

\[
A_k(n, d) := \max \left\{ \sum_{v \in N} x\{v\} \mid x : \mathcal{N}_k \to \mathbb{R}, x(\emptyset) = 1, M_S(x) \text{ positive semidefinite for each } S \in \mathcal{N}_k \right\}.
\]

Note that, as \( x(S) \) occurs on the diagonal of \( M_S(x) \), \( x \) has nonnegative values only.

**Proposition 1.** \( A(n, d) \leq A_k(n, d) \).

**Proof.** Let \( C \) be a maximum-size code of length \( n \) and minimum distance at least \( d \). Define \( x(S) := 1 \) if \( S \subseteq C \) and \( x(S) := 0 \) otherwise. Then \( M_S(x) \) is positive semidefinite for each \( S \in \mathcal{N}_k \). Moreover, \( A(n, d) = |C| = \sum_{v \in N} x\{v\} \).

The upper bound \( A_2(n, d) \) can be proved to be equal to the Delsarte bound \([3]\) (see \([5]\)).

The bound given in \([17]\) is a slight sharpening of \( A_3(n, d) \).

Now to make the problem computationally tractable, let again \( G \) be the group of permutations of \( N \) that maintain distances. Then, if \( x \) is an optimum solution of \([3]\) and
\( \pi \in G \), also \( x^\pi \) is an optimum solution. (We refer to Section 3.2 for notation.) As the feasible region in (4) is convex, by averaging over all \( \pi \in G \) we obtain a \( G \)-invariant optimum solution. So we can reduce the feasible region to those \( x \) that are \( G \)-invariant. Then \( M_S(x) \) is \( G_S \)-invariant, where \( G_S \) is the \( G \)-stabilizer of \( S \) (set of \( \pi \in G \) with \( \pi(S) = S \)). This allows us to block diagonalize \( M_S(x) \), and to make the problems tractable for larger \( n \). In the coming sections we will discuss how to obtain an explicit block diagonalization.

It is of interest to remark that the equality \( A(20, 8) = 256 \) in fact follows if we take \( k = 4 \) and require in (4) only that \( M_S(x) \) is positive semidefinite for all \( S \) with \(|S| = 0 \) or \(|S| = 4 \).

An observation useful to note (but not used in the sequel) is the following. A well-known relation is \( A(n+1, d) \leq 2 A(n,d) \). The same relation holds for \( A_k(n,d) \):

**Proposition 2.** For all \( n,d \): \( A_k(n+1,d) \leq 2 A_k(n,d) \).

**Proof.** Let \( x \) attain the maximum (4) for \( A_k(n+1,d) \). For each \( S \subseteq \{0,1\}^n \), let \( S' := \{w0 \mid w \in S\} \) and \( S'' := \{w1 \mid w \in S\} \). Define \( x'(S) := x(S') \) and \( x''(S) := x(S'') \) for all \( S \in N \). Then \( x' \) and \( x'' \) are feasible solutions of (4) for \( A_k(n,d) \). Moreover \( \sum_{w \in \{0,1\}^n} (x'(\{v\}) + x''(\{v\})) = \sum_{w \in \{0,1\}^{n+1}} x(\{v\}) \). Thus \( 2 A_k(n,d) \geq A_k(n+1,d) \).

This implies, using \( A(20, 8) = 256 \) and \( A(24, 8) = 4096 \) (the extended Golay code), that \( A_4(21, 8) = 512 \), \( A_4(22, 8) = 1024 \), \( A_4(23, 8) = 2048 \), and \( A_4(24, 8) = 4096 \). We did not display these values in the table, and we do not need to solve the corresponding semidefinite programming problems.

From now on we will fix \( k = 4 \), and we will use the name \( k \) for other purposes. In Section 6 we will discuss how to find a further reduction by considering words of even weights only, which is enough to obtain the bounds.

### 3. Preliminaries

In this section we fix some notation and recall a few basic facts. Underlying mathematical disciplines are representation theory and C*-algebra, but because the potential readership of this paper might possess diverse background, we give a brief elementary exposition.

#### 3.1. Notation

We denote

\begin{equation}
[s, t] := \{i \in \mathbb{Z} \mid s \leq i \leq t\} \quad \text{and} \quad [s, t]_{\text{even}} := \{i \in \mathbb{Z} \mid s \leq i \leq t; i \text{ even}\}.
\end{equation}

Throughout this paper, \( P \), \( T \), and \( N \) denote the sets of ordered pairs, triples, and \( n \)-tuples of elements of \( \{0,1\} \), i.e.,

\begin{equation}
P := \{0,1\}^2, \ T := \{0,1\}^3, \ \text{and} \ \ N := \{0,1\}^n.
\end{equation}
As mentioned, we identify elements of \(\{0,1\}^t\) with 0, 1 words of length \(t\). We will view \(\{0,1\}\) as the field of two elements and add elements of \(P, T,\) and \(N\) modulo 2.

For \(\alpha : P \rightarrow \mathbb{Z}_+\), we denote

\[
\begin{align*}
i_\alpha &:= \alpha(10) + \alpha(11), j_\alpha := \alpha(01) + \alpha(11), n_\alpha := \alpha(00) + \alpha(10) + \alpha(01) + \alpha(11). 
\end{align*}
\]

For any finite set \(V\) and \(n \in \mathbb{Z}_+\), let

\[
\Lambda^n_V := \{\lambda : V \rightarrow \mathbb{Z}_+ \mid \sum_{v \in V} \lambda(v) = n\}.
\]

For any element \(\lambda \in \Lambda^n_V\), let

\[
\Omega_\lambda := \{\rho : \{1, \ldots, n\} \rightarrow V \mid |\rho^{-1}(v)| = \lambda(v) \text{ for each } v \in V\}.
\]

So \(\{\Omega_\lambda \mid \lambda \in \Lambda^n_V\}\) is the collection of orbits on \(V^n\) under the natural action of the symmetric group \(S_n\) on \(V^n\) (cf. Section 3.2).

Throughout, \(G\) denotes the group of distance preserving permutations of \(N\). The group consists of all permutations of coordinates followed by swapping 0 and 1 in a subset of the coordinates.

### 3.2. Group actions

An *action* of a group \(H\) on a set \(Z\) is a group homomorphism from \(H\) into the group of permutations of \(Z\). One then says that \(H\) *acts on* \(Z\). An action of \(H\) on \(Z\) induces in a natural way actions of \(H\) on derived sets like \(Z \times Z, \mathcal{P}(Z), \{0,1\}^Z,\) and \(\mathbb{C}^Z\).

If \(\pi \in H\) and \(z \in Z\), then \(z^\pi\) denotes the image of \(z\) under the permutation associated with \(\pi\). If \(H\) acts on \(Z\), an element \(z \in Z\) is called *\(H\)-invariant* if \(z^\pi = z\) for each \(\pi \in H\). The set of \(H\)-invariant elements of \(Z\) is denoted by \(Z^H\).

A function \(\phi : Z \rightarrow Z\) is *\(H\)-equivariant* if \(\phi(z^\pi) = \phi(z)^\pi\) for each \(z \in Z\) and each \(\pi \in H\). If \(Z\) is a vector space, the collection of \(H\)-equivariant endomorphisms \(Z \rightarrow Z\) is denoted by \(\text{End}_H(Z)\). It is called the *centralizer algebra* of the action of \(H\) on \(Z\).

If \(Z\) is a finite set and \(H\) acts on \(Z\), then there is a natural isomorphism

\[
\text{End}_H(\mathbb{C}^Z) \cong (\mathbb{C}^Z \times Z)^H.
\]

If \(Z\) is a linear space, the symmetric group \(S_n\) acts naturally on the \(n\)-th tensor power \(Z^\otimes n\). As usual, we denote the subspace of symmetric tensors by

\[
\text{Sym}^n(Z) := (Z^\otimes n)^{S_n}.
\]

### 3.3. Matrix *-algebras

A *matrix *-algebra* is a set of matrices (all of the same order) that is a \(\mathbb{C}\)-linear space and is closed under multiplication and under taking conjugate transpose \((X \mapsto X^*)\). If a group...
If \( A \) and \( B \) are matrix \(*\)-algebras, a function \( \phi : A \to B \) is an \textit{algebra \(*\)-homomorphism} if \( \phi \) is linear and maintains multiplication and taking conjugate transpose. It is an \textit{algebra \(*\)-isomorphism} if \( \phi \) is moreover a bijection.

If \( \phi : A \to B \) is an algebra \(*\)-homomorphism and \( A \in A \) is positive semidefinite, then also \( \phi(A) \) is positive semidefinite. (This follows from the fact that any matrix \( X \) is positive semidefinite if and only if \( X = YY^* \) for some linear combination \( Y \) of \( X, X^2, \ldots \). This last statement can be proved by diagonalizing \( X \).)

The sets \( \mathbb{C}^{m \times m} \), for \( m \in \mathbb{Z}_+ \), are the \textit{full matrix \(*\)-algebras}. An algebra \(*\)-isomorphism \( A \to B \) is called a \textit{full block diagonalization} of \( A \) if \( B \) is a direct sum of full matrix \(*\)-algebras.

Each matrix \(*\)-algebra has a full block diagonalization — we need them explicitly in order to perform the calculations for determining \( A_4(n, d) \). (A full block diagonalization is in fact unique, up to obvious transformations: reordering the terms in the sum, and resetting \( X \mapsto U^*XU \), for some fixed unitary matrix \( U \), applied to some full matrix \(*\)-algebra.)

### 3.4. Actions of \( S_2 \)

Let \( Z \) be a finite set on which the symmetric group \( S_2 \) acts. This action induces an action of \( S_2 \) on \( \mathbb{C}^Z \). For \( \pm \in \{+, -\} \), let \( L_\pm := \{ x \in \mathbb{R}^Z \mid x^\sigma = \pm x \} \), where \( \sigma \) is the non-identity element of \( S_2 \). Then \( L_+ \) and \( L_- \) are the eigenspaces of \( \sigma \).

Let \( U_\pm \) be a matrix whose columns form an orthonormal basis of \( L_\pm \). The matrices \( U_\pm \) are easily obtained from the \( S_2 \)-orbits on \( Z \). Then the matrix \( [U_+ \ U_-] \) is unitary. Moreover, \( U_+^*XU_- = 0 \) for each \( X \) in \( (\mathbb{C}^Z \times Z)^{S_2} \). As \( L_+ \) and \( L_- \) are the eigenspaces of \( \sigma \), the function \( X \mapsto U_+^*XU_+ \oplus U_-^*XU_- \) defines a full block diagonalization of \( (\mathbb{C}^Z \times Z)^{S_2} \).

### 3.5. Fully block diagonalizing \( \text{Sym}^n(\mathbb{C}^{2 \times 2}) \)

We describe a full block diagonalization

\[
\chi : \text{Sym}^n(\mathbb{C}^{2 \times 2}) \to \bigoplus_{k=0}^{\lfloor \frac{n}{2} \rfloor} \mathbb{C}^{[k, n-k] \times [k, n-k]},
\]

as can be derived from the work of Dunkl [4] (cf. Vallentin [20], Schrijver [17]).

To this end, let, for any \( \alpha \in \Lambda^n_p \),

\[
M_\alpha := \sum_{\rho \in \Omega_{\alpha}} \bigotimes_{i=1}^n E_{\rho(i)} \in \text{Sym}^n(\mathbb{C}^{2 \times 2}).
\]

Here, for \( c = (c_1, c_2) \in P, E_c \) denotes the \( \{0, 1\} \times \{0, 1\} \) matrix with 1 in position \( c_1, c_2 \) and 0 elsewhere. Then \( \{M_\alpha \mid \alpha \in \Lambda^n_p \} \) is a basis of \( \text{Sym}^n(\mathbb{C}^{2 \times 2}) \). (Throughout, we identify \( \mathbb{C}^{2 \times 2} \) with \( \mathbb{C}^{\{0, 1\} \times \{0, 1\}} \).)

For any \( \alpha : P \to \mathbb{Z}_+ \) and \( k \in \mathbb{Z}_+ \), define the following number:
\[ \gamma_{\alpha,k} := \sum_{p=0}^{k} (-1)^p \binom{k}{p} \left( \binom{\alpha(0)+\alpha(01)-k}{\alpha(01)-p} \binom{\alpha(0)+\alpha(11)-k}{\alpha(01)-p} \binom{\alpha(10)+\alpha(00)-k}{\alpha(01)-p} \binom{\alpha(10)+\alpha(11)-k}{\alpha(01)-p} \right)^{1/2}, \]

and the following \([k, n-k] \times [k, n-k]\) matrix \(\Gamma_{\alpha,k}\), where \(n := n_\alpha\):

\[ (\Gamma_{\alpha,k})_{i,j} := \begin{cases} \gamma_{\alpha,k} & \text{if } i = i_\alpha \text{ and } j = j_\alpha, \\ 0 & \text{otherwise,} \end{cases} \]

for \(i, j \in [k, n-k]\). Now \(\chi\) is given by

\[ \chi(M_\alpha) = \bigoplus_{k=0}^{\lfloor \frac{1}{2}n \rfloor} \Gamma_{\alpha,k} \]

for \(\alpha \in \Lambda^p\).

4. Fully block diagonalizing the matrices \(M_S(x)\)

Recall that \(\mathcal{N}_t\) consists of all codes of length \(n\), of minimum distance at least \(d\), and size at most \(t\). Let \(x : \mathcal{N}_4 \to \mathbb{R}\) be \(G\)-invariant. For any \(S \in \mathcal{N}_4\) and any \(\pi \in G\), we have that \(M_S(x)\) is equal to \(M_{\pi(S)}(x)\), up to renaming row and column indices. So we need to check positive semidefiniteness of \(M_S(x)\) for only one set \(S\) from any \(G\)-orbit on \(\mathcal{N}_4\). Moreover, \(M_S(x)\) belongs to the centralizer algebra of the \(G\)-stabilizer \(G_S\) of \(S\) (the set of all \(\pi \in G\) with \(\pi(S) = S\)).

Consider any \(S \in \mathcal{N}_4\). If \(|S| = 4\), then \(M_S(x)\) is a \(1 \times 1\) matrix with entry \(x(S)\). So \(M_S(x)\) is positive semidefinite if and only if \(x(S) \geq 0\).

Moreover, if \(|S|\) is odd and \(|S| \leq 3\), then \(M_S(x)\) is a principal submatrix of \(M_R(x)\), where \(R\) is any subset of \(S\) with \(|R| = |S| - 1\). (This because if \(S' \supseteq S\) and \(|S| + 2|S' \setminus S| \leq 4\), then \(|R| + 2|S' \setminus R| \leq 4\).)

Concluding it remains to consider checking positive semidefiniteness of \(M_S(x)\) only for \(S = \emptyset\) and for one element from each \(G\)-orbit of codes \(S\) in \(\mathcal{N}\) with \(|S| = 2\). We first consider the case \(|S| = 2\).

Note that the \(G\)-orbit of any \(S \in \mathcal{N}\) with \(|S| = 2\) is determined by the distance \(m\) between the two elements of \(S\). Hence we can assume \(S := \{0, u\}\), where \(u\) is the element of \(N\) with precisely \(m\) 1's, in positions 1, \ldots, \(m\). Then there is a one-to-one relation between

\[ N' := \{ v \in N \mid d_H(0, v) \in [d, n] \text{ and } d_H(u, v) \in \{0\} \cup \{d, n\} \} \]

and \(\mathcal{N}(S)\), given by \(v \mapsto S \cup \{v\}\).

For any \(v, w \in N\), let \(\rho_{v, w} : \{1, \ldots, n\} \to P\) be defined by \(\rho_{v, w}(i) := (v_i, w_i)\) for \(i = 1, \ldots, n\). This gives an embedding
\( \Phi : \text{End}_{GS}(\mathbb{C}^{N(S)}) \to \text{Sym}^m(\mathbb{C}^{2 \times 2}) \otimes \text{Sym}^{n-m}(\mathbb{C}^{2 \times 2}) \)

defined by

\[
\Phi(X) := \sum_{v,w \in N'} X_{S \cup \{v\}, S \cup \{w\}} M_{\rho_{v,w}}
\]

for \( X \in \text{End}_{GS}(\mathbb{C}^{N(S)}) \).

The image of \( \Phi \) is equal to the linear hull of those \( M_\alpha \otimes M_\beta \) with \( \alpha \in \Lambda_P^m \) and \( \beta \in \Lambda_P^{n-m} \) such that \( i_\alpha + i_\beta \in [d, n] \), \( j_\alpha + j_\beta \in [d, n] \), \( m - i_\alpha + i_\beta \in \{0\} \cup [d, n] \), \( m - j_\alpha + j_\beta \in \{0\} \cup [d, n] \).

With the full block diagonalization (15) this gives that the image is equal to the direct sum over \( k,l \) of the linear hull of the submatrices of \( \Gamma_\alpha,k \otimes \Gamma_\beta,l \) induced by the rows and columns indexed by \( (i,i') \) with \( i + i' \in [d, n] \) and \( m - i + i' \in \{0\} \cup [d, n] \).

The stabilizer \( GS \) contains a further symmetry, replacing any \( c \in N \) by \( c + u \) (mod 2). This leaves \( S = \{0, u\} \) invariant. It means an action of \( S_2 \), and the corresponding reduction can be obtained with the method of Section 3.4.

5. Fully block diagonalizing \( M_\emptyset(x) \)

In this section we consider \( S = \emptyset \). Then \( N(S) = N_2 \), which is the set of all codes of length \( n \), minimum distance at least \( d \), and size at most 2. We are out for a full block diagonalization of the centralizer algebra \( \text{End}_G(\mathbb{C}^{N_2}) \) of the action of \( G \) on \( \mathbb{C}^{N_2} \). This will be obtained in a number of steps.

5.1. The algebra \( \mathcal{A} \)

We first consider an algebra \( \mathcal{A} \) consisting of (essentially) \( 4 \times 4 \) matrices. For any \( c \in P = \{0, 1\}^2 \), let \( \overline{c} := c + (1, 1) \) (mod 2). Let \( \mathcal{A} \) be the centralizer algebra of the action of \( S_2 \) on \( P \) generated by \( c \mapsto \overline{c} \) on \( c \in P \). We can find a full block diagonalization with the method of Section 3.4. We need it explicitly. Note that

\[
\mathcal{A} = \{ A \in \mathbb{C}^{P \times P} \mid A_{\overline{c},\overline{d}} = A_{c,d} \text{ for all } c, d \in P \}
\]

and that \( \mathcal{A} \) is a matrix \( * \)-algebra of dimension 8.

For \( c, d \in P \), let \( E_{c,d} \) be the 0,1 matrix in \( \mathbb{C}^{P \times P} \) with precisely one 1, in position \( (c, d) \). Recall \( T = \{0, 1\}^3 \), and define for \( t \in T \):

\[
B_t := E_{c,d} + E_{t,d}
\]

where \( (c,d) \) is any of the two pairs in \( P^2 \) satisfying

\[
c_1 + c_2 = t_1, d_1 + d_2 = t_2, c_2 + d_2 = t_3.
\]

Then \( \{B_t \mid t \in T\} \) is a basis of \( \mathcal{A} \).
For \( i \in \{0, 1\}, \) let \( U_i \in \mathbb{C}^{P \times \{0, 1\}} \) be defined by

\[
(23) \quad (U_i)_{c,a} = \frac{1}{2}\sqrt{2}(-1)^{ic_2}\delta_{a,c_1+c_2}
\]

for \( c \in P \) and \( a \in \{0, 1\} \). Then one directly checks that the matrix \( U := [U_0 \ U_1] \) is unitary, i.e., \( U^*U = I \). Moreover, for all \( c, d \in P \) and \( a, b, i, j \in \{0, 1\} \) we have

\[
(24) \quad (U_i^*E_{c,d}U_j)_{a,b} = (U_i)_{c,a}(U_j)_{d,b} = \frac{1}{2}(-1)^{ic_2+jd_2}\delta_{a,c_1+c_2}\delta_{b,d_1+d_2}.
\]

Hence, if \( t \in T \) and \( c, d \) satisfy (22), then

\[
(25) \quad (U_i^*B_tU_j)_{a,b} = \frac{1}{2}((-1)^{ic_2+jd_2} + (-1)^{ic_2+jd_2+i+j})\delta_{a,c_1+c_2}\delta_{b,d_1+d_2} = \frac{1}{2}(-1)^{ic_2+jd_2}(1 + (-1)^{i+j})\delta_{a,c_1+c_2}\delta_{b,d_1+d_2} = (-1)^{it_3}\delta_{i,j}\delta_{a,t_1}\delta_{b,t_2}.
\]

So \( U_0^*AU_1 = 0 \), and hence, as \( \dim A = 8 \), \( U^*AU \) gives a full block diagonalization of \( A \). Moreover

\[
(26) \quad U_i^*B_tU_i = (-1)^{it_3}E_{t_1,t_2}.
\]

### 5.2. The algebra \( \text{Sym}^n(A) \)

Our next step is to find a full block diagonalization of \( \text{End}_G(\mathbb{C}^{N^2}) \), where \( N^2 \) is (as usual) the collection of ordered pairs from \( N = \{0, 1\}^n \).

There is a natural algebra isomorphism

\[
(27) \quad \text{End}_G(\mathbb{C}^{N^2}) \to \text{Sym}^n(A)
\]

by the natural isomorphisms

\[
(28) \quad \mathbb{C}^{\{0,1\}^2} \cong \mathbb{C}^{\{0,1\}^2} \cong (\mathbb{C}^{\{0,1\}^2})^\otimes n,
\]

using the fact that \( G \) consists of all permutations of \( N \) given by a permutation of the indices in \( \{0, \ldots, n\} \) followed by swapping 0 and 1 on a subset of it.

Let \( U_0 \) and \( U_1 \) the \( P \times \{0, 1\} \) matrices given in Section 5.1. Define

\[
(29) \quad \phi : \text{Sym}^n(A) \to \bigoplus_{m=0}^n \text{Sym}^m(\mathbb{C}^{\{0,1\} \times \{0,1\}}) \otimes \text{Sym}^{n-m}(\mathbb{C}^{\{0,1\} \times \{0,1\}})
\]

by

\[
(30) \quad \phi(A) := \bigoplus_{m=0}^n (U_0^\otimes m \otimes U_1^\otimes n-m)^* A (U_0^\otimes m \otimes U_1^\otimes n-m)
\]

for \( A \in \text{Sym}^n(A) \). Trivially, \( \phi \) is linear, and as \( U^*AU = U_0^*AU_0 \oplus U_1^*AU_1 \), \( \phi \) is a bijection.
(cf. Lang [6], Chapter XVI, Proposition 8.2). Moreover, it is an algebra ∗-isomorphism, since $U_i^* U_i = I$ for $i = 0, 1$ and hence $U_0^{⊗ m} \otimes U_1^{⊗ n-m}$ is unitary.

Since a full block diagonalization of $\text{Sym}^n(C^{2×2})$, expressed in the standard basis of $\text{Sym}^m(C^{2×2})$, is known for any $m$ (Section 3.5), and since the tensor product of full block diagonalizations is again a full block diagonalization, we readily obtain with $\phi$ a full block diagonalization of $\text{Sym}^n(A)$. To use it in computations, we need to describe it in terms of the standard basis of $\text{Sym}^m(A)$. First we express $\phi$ in terms of the standard bases of $\text{Sym}^n(A)$ and of $\text{Sym}^m(C^{2×2})$ and $\text{Sym}^{n-m}(C^{2×2})$.

Let $\Lambda^n_T$ and $\Omega$ be as in (8) and (9). For $\lambda \in \Lambda^n_T$, define

$$B_\lambda := \sum_{\rho \in \Omega(\lambda)} B^{(i)}.$$  

Then $\{B_\lambda \mid \lambda \in \Lambda^n_T\}$ is a basis of $\text{Sym}^n(A)$.

We need the ‘Krawtchouk polynomial’: for $n, k, t \in \mathbb{Z}_+$,

$$K_n^k(t) := \sum_{i=0}^{k} (-1)^i \binom{t}{i} \binom{n-t}{k-i}.$$  

For later purposes we note here that for all $n, k, t$:

$$K_{n-k}^n(t) = (-1)^t K_k^n(t).$$  

For $\lambda \in \Lambda^n_T$, $\alpha \in \Lambda^m_P$, $\beta \in \Lambda^{n-m}_P$, define

$$\vartheta_{\lambda, \alpha, \beta} := \delta_{\lambda', \alpha + \beta} \prod_{c \in P} K_{\lambda(c1)}(\beta(c)),$$

where for $\lambda \in \Lambda^n_T$, $\lambda' \in \Lambda^m_T$ is defined by

$$\lambda'(c) := \lambda(c0) + \lambda(c1)$$  

for $c \in P$.

We now express $\phi$ in the standard bases (31) and (13).

**Proposition 3.** For any $\lambda \in \Lambda^n_T$,

$$\phi(B_\lambda) = \bigoplus_{m=0}^{n} \sum_{\alpha \in \Lambda^m_P, \beta \in \Lambda^{n-m}_P} \vartheta_{\lambda, \alpha, \beta} M_\alpha \otimes M_\beta.$$  

**Proof.** By (20), the $m$-th component of $\phi(B_\lambda)$ is equal to

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\[
\sum_{\rho \in \Omega} \left( \bigotimes_{i=1}^{m} E_{\rho_1(i), \rho_2(i)} \right) \otimes \left( \bigotimes_{i=m+1}^{n} (-1)^{\rho_3(i)} E_{\rho_1(i), \rho_2(i)} \right) = \\
\sum_{\mu \in \Lambda^m, \nu \in \Lambda^{n-m}} \left( \prod_{c \in C} (\mu(c)_1) \right) M_{\mu} \otimes \left( \prod_{c \in C} (-1)^{\nu(c)} (\nu(c)) \right) M_{\nu}.
\]

If we sum over \( \alpha := \mu' \) and \( \beta := \nu' \), we can next, for each \( c \in C \), sum over \( j \) and set \( \nu(c1) := j \), and \( \mu(c1) := \lambda(c1) - j \). In this way we get that the last expression in (37) is equal to

\[
\sum_{\alpha \in \Lambda^m, \beta \in \Lambda^{n-m}} \vartheta_{\lambda, \alpha, \beta} M_{\alpha} \otimes M_{\beta}.
\]

This describes the algebra isomorphism \( \phi \) in (29). With the results given in Section 3.5, it implies a full block diagonalization

\[
\psi : \text{Sym}^n(A) \to \bigoplus_{m=0}^{n} \bigoplus_{k=0}^{\left\lfloor \frac{m}{2} \right\rfloor} \bigoplus_{l=0}^{\left\lfloor \frac{n-m}{2} \right\rfloor} \mathbb{C}^{[k,m-k] \times [k,m-k]} \otimes \mathbb{C}^{[l,n-m-k] \times [l,n-m-k]},
\]

described by

\[
\psi(B_\lambda) = \bigoplus_{m=0}^{n} \bigoplus_{k=0}^{\left\lfloor \frac{m}{2} \right\rfloor} \bigoplus_{l=0}^{\left\lfloor \frac{n-m}{2} \right\rfloor} \psi_{m,k,l}(B_\lambda)
\]

where

\[
\psi_{m,k,l}(B_\lambda) := \sum_{\alpha \in \Lambda^m, \beta \in \Lambda^{n-m}} \vartheta_{\lambda, \alpha, \beta} \Gamma_{\alpha, k} \otimes \Gamma_{\beta, l}
\]

for \( \lambda \in \Lambda^r \). Inserting (14) and (15) in (41) makes the block diagonalization explicit, and it can readily be programmed. Note that \( \alpha, \beta \) in the summation can be restricted to those with \( \alpha + \beta = \lambda' \). Note also that at most one entry of the matrix \( \Gamma_{\alpha, k} \otimes \Gamma_{\beta, l} \) is nonzero.

### 5.3. Deleting distances

For \( m, k, l \), we will use the natural isomorphism
\[(42)\quad \mathbb{C}^{[k,m-k] \times [l,n-m-l]} \times ([k,m-k] \times [l,n-m-l]) \cong \mathbb{C}^{[k,m-k]} \otimes \mathbb{C}^{[l,n-m-l]} \times [l,n-m-l].\]

**Proposition 4.** Let \( D \subseteq [0,n] \). Then the linear hull of
\[(43)\quad \{\psi_{m,k,l}(B_\lambda) \mid \lambda \in \Lambda^n_\varphi, i_\lambda, j_\lambda \in D\}\]

is equal to the subspace \( \mathbb{C}^F \times F \) of \( (42) \), where
\[(44)\quad F := \{(i, i') \in [k, m-k] \times [l, n-m-l] \mid i + i' \in D\}.

**Proof.** For any \( \lambda \in \Lambda^n_\varphi \), if \( \psi_{m,k,l}(B_\lambda)_{(i,i'),(j,j')} \) is nonzero, then \( i + i' = i_\lambda \) and \( j + j' = j_\lambda \).

This follows from \( (40) \) and from the definition of the matrices \( \Gamma_{\alpha,k} \) (cf. \( (15) \)).

Hence, for any fixed \( a, b \in \mathbb{Z}_+ \), the linear hull of the \( \psi_{m,k,l}(B_\lambda) \) with \( i_\lambda = a \) and \( j_\lambda = b \)

is equal to the set of matrices in \( (42) \) that are nonzero only in positions \((i, i'), (j, j')\) with \( i + i' = a \) and \( j + j' = b \).

So if distances are restricted to \( D \subseteq [0,n] \), we can reduce the block diagonalization to those rows and columns with index in \( F \).

### 5.4. Unordered pairs

We now go over from ordered pairs to unordered pairs. First, let \( \Lambda^n_\varphi := \Lambda_2 \setminus \{\emptyset\} \), and consider \( \text{End}_G(\mathbb{C}^{\Lambda^n_\varphi}) \). Let \( \tau \) be the permutation of \( N^2 \) swapping \((c, d)\) and \((d, c)\) in \( N^2 \). Let \( Q_\tau \) be the corresponding permutation matrix in \( \mathbb{C}^{N^2 \times N^2} \). Note that \( N^2 \) corresponds to the set of row indices of the matrices \( B_\lambda \) (cf. \( (25) \)).

For any \( \lambda \in \Lambda^n_\varphi \), let \( \lambda := \Lambda_2 \setminus \{\emptyset\} \) be given by \( \lambda(t_1, t_2, t_3) := \lambda(t_1, t_2, t_3 + t_1) \) for \( t \in T \). So for any \( c \in P \), \( \lambda(c1) = \lambda(c) \) if \( c_1 = 0 \) and \( \lambda(c1) = \lambda(c) - \lambda(c1) \) if \( c_1 = 1 \). Then \( B_\lambda = Q_\tau B_\lambda \).

Now \( (33) \) gives that for any \( m \) and \( \alpha \in \Lambda^n_\varphi, \beta \in \Lambda^n_{P^{-m}} \) one has
\[(45)\quad \hat{\vartheta}_{\lambda,\alpha,\beta} = (-1)^{ij} \hat{\vartheta}_{\lambda,\alpha,\beta}.

This implies that the matrix 
\( \psi_{m,k,l}(B_\lambda + B_\lambda) \)

has only 0’s in rows whose index \((i, i')\) has \( i' \) odd. Similarly, the matrix 
\( \psi_{m,k,l}(B_\lambda - B_\lambda) \)

has only 0’s in rows whose index \((i, i')\) has \( i' \) even. As the space of matrices invariant under permuting the rows by \( \tau \) is spanned by the matrices \( B_\lambda + B_\lambda \), this space corresponds under \( \psi_{m,k,l} \) to those matrices that have 0’s in rows whose index \((i, i')\) has \( i' \) odd.

A similar argument holds for columns if we consider \( \lambda(t_1, t_2, t_3) := \lambda(t_1, t_2, t_3 + t_2) \). Hence the image of \( \psi_{m,k,l} \) of the set of elements of \( \text{Sym}^n(A) \) that are invariant under the operations \( \lambda \mapsto \lambda \) and \( \lambda \mapsto \lambda \) is precisely equal to
\[(46)\quad \mathbb{C}^{[k,m-k]} \otimes \mathbb{C}^{[l,n-m-l]}_{\text{even}} \times [l,n-m-l]_{\text{even}}.

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5.5. Adding $\emptyset$

So far we have a full block decomposition of $\text{End}_G(\mathbb{C}^N_2)$, We need to incorporate $\emptyset$ in it. It is a basic fact from representation theory that if $V_1, \ldots , V_t$ is the canonical decomposition of $\mathbb{C}^N_2$ into isotypic components (cf. Serre [18]), then $\text{End}_G(\mathbb{C}^N_2) = \bigoplus_{i=1}^t \text{End}_G(V_i)$, and each $\text{End}_G(V_i)$ is $*$-isomorphic to a full matrix algebra.

We can assume that $V_1$ is the set of $H$-invariant elements of $\mathbb{C}^N_2$. Hence, as $\emptyset$ is $G$-invariant, $V'_1 := \mathbb{C}^0 \oplus V_1$ is the set of $G$-invariant elements of $\mathbb{C}^N_2$. One may check that the block indexed by $(m,k,l) = (n,0,0)$ corresponds to $V_1$. So replacing block $(n,0,0)$ by $\text{End}_G(V'_1)$ gives a full block diagonalization of $\text{End}_G(\mathbb{C}^N_2)$. Note that $\text{End}_G(V'_1) = \text{End}(V'_1)$.

We can easily determine a basis for $V'_1$, namely the set of characteristic vectors of the $G$-orbits of $N_2$. Then for any $B \in \text{End}_G(\mathbb{C}^N_2)$, we can directly calculate its projection in $\text{End}(V'_1)$. This gives the required new component of the full block diagonalization.

6. Restriction to even words

We can obtain a further reduction by restriction to the collection $E$ of words in $\{0,1\}^n$ of even weight. (The weight of a word is the number of $1$’s in it.) By a parity check argument one knows that for even $d$ the bound $A(n,d)$ is attained by a code $C \subseteq E$. A similar phenomenon applies to $A_k(n,d)$:

**Proposition 5.** For even $d \geq 2$, the maximum value in (4) does not change if $x(S)$ is required to be zero if $S \not\subseteq E$.

**Proof.** Let $\varepsilon : N \rightarrow E$ be defined by $\varepsilon(w) = w$ if $w$ has even weight and $\varepsilon(w) = w + e_n$ if $w$ has odd weight. Here $e_n$ is the $n$-th unit basis vector, and addition is modulo 2. If $d$ is even, then for all $v, w \in N$: $d_H(v,w) \geq d$ if and only if $d_H(\varepsilon(v),\varepsilon(w)) \geq d$. Now $\varepsilon$ induces a projection $p : \mathbb{R}^N \rightarrow \mathbb{R}^E$, where $E$ is the collection of codes in $N$ with all words having even weight.

One easily checks that if $M_S(x)$ is positive semidefinite for all $S$, then $M_S(p(x))$ is positive semidefinite for all $S$. Moreover, $\sum_{v \in N} p(x)(\{v\}) = \sum_{v \in N} x(\{v\})$. 

This implies that restricting $x$ to be nonzero only on subsets $S$ of $E$ does not change the value of the upper bound. However, it gives a computational reduction. This can be obtained by using Proposition 4 and by observing that the restriction amounts to an invariance under an action of $S_2$, for which we can use Section 3.4. The latter essentially implies that in (46) we can restrict the left hand side factor to rows and columns with index in $[k,m-k]_{\text{even}}$. As it means a reduction of the program size by only a linear factor, we leave the details to the reader.

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