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Abstract
We study the small mass limit of the equation describing planar motion of a charged particle of a small mass $\mu$ in a force field, containing a magnetic component, perturbed by a stochastic term. We regularize the problem by adding a small friction of intensity $\epsilon > 0$. We show that for all small but fixed frictions the small mass limit of $q_{\mu, \epsilon}$ gives the solution $q_\epsilon$ to a stochastic first order equation, containing a noise-induced drift term. Then, by using a generalization of the classical averaging theorem for Hamiltonian systems by Freidlin and Wentzell, we take the limit of the slow component of the motion $q_\epsilon$ and we prove that it converges weakly to a Markov process on the graph obtained by identifying all points in the same connected components of the level sets of the magnetic field intensity function.

Keywords
Stochastic differential equations · Smoluchowski–Kramers approximation · Averaging principle · Hamiltonian systems · Stochastic equations on graphs

1 Introduction
We are dealing with planar motion of a charged particle of a small mass $\mu$ in a force field, containing a magnetic component, perturbed by a stochastic term.
We are interested in understanding the limiting behavior of the solution $q_\mu$ to the equation (1.1), as the mass $\mu$ converges to 0. This is the so-called Smoluchowski-Kramers limit.

It is well known (see [10] for all details) that when the variable magnetic field considered in the present paper is replaced by a constant friction (that is $\lambda$ is constant and the matrix $A$ is the identity matrix), then $q_\mu(t)$ converges to the solution of the first order equation

$$dq(t) = b(q(t))\, dt + \sigma(q(t))\, dw(t), \quad q(0) = q.$$  \hspace{1cm} (1.2)

More precisely, for every fixed $T > 0$

$$\lim_{\mu \to 0} \mathbb{E} \max_{t \in [0,T]} |q_\mu(t) - q(t)|^2 = 0.$$  \hspace{1cm} (1.3)

Here $q_\mu$ can be a vector of any finite dimension. The same result can be obtained also if $\lambda$ is still constant, but $A$ is a more general matrix, whose eigenvalues have strictly positive real parts, with the limiting equation (1.2) replaced by

$$dq(t) = A^{-1}b(q(t))\, dt + A^{-1}\sigma(q(t))\, dw(t), \quad q(0) = q.$$  \hspace{1cm} (1.4)

The case of non-constant friction has been widely studied recently (see [2] and [14] for example). To summarize the relevant results, consider the system

$$\begin{cases}
\mu \ddot{q}_\mu(t) = b(q_\mu(t)) - \gamma(q_\mu(t))\dot{q}_\mu(t) + \sigma(q_\mu(t))\, \dot{w}_t, \\
q_\mu(0) = q \in \mathbb{R}^k, \quad \dot{q}_\mu(0) = p \in \mathbb{R}^k,
\end{cases}$$  \hspace{1cm} (1.5)

for an $h$-dimensional Brownian motion $w(t)$. Assume that the coefficients $b : \mathbb{R}^k \to \mathbb{R}^k$, $\gamma : \mathbb{R}^h \to \mathbb{R}^{k \times k}$ and $\sigma : \mathbb{R}^h \to \mathbb{R}^{h \times k}$ are smooth and uniformly bounded and the smallest eigenvalue $\lambda_1(q)$ of the symmetric matrix $\gamma(q) + \gamma^*(q)$ is strictly positive, uniformly in $q \in \mathbb{R}^k$,

$$\inf_{q \in \mathbb{R}^k} \lambda_1(q) =: \tilde{\lambda} > 0.$$  

In this case the relation (1.3) still holds, but now $q(t)$ is the solution of the modified equation

$$dq(t) = \left[\gamma^{-1}(q(t))b(q(t)) + S(q(t))\right]\, dt + \gamma^{-1}(q(t))\sigma(q(t))\, dw(t), \quad q(0) = q.$$  \hspace{1cm} (1.6)

Here $S(q)$ is the noise-induced drift whose $j$-th component equals

$$S_j(q) = \sum_{i,l=1}^k \frac{\partial}{\partial q_{il}} (\gamma^{-1})_{jl}(q) J_{li}(q), \quad j = 1, \ldots, k,$$

where $J$ is the matrix-valued function solving the Lyapunov equation

$$J(q)\gamma^*(q) + \gamma(q)J(q) = \sigma(q)\sigma^*(q), \quad q \in \mathbb{R}^k.$$
In [5], the case of a particle subject to a constant magnetic field orthogonal to the plane where the particle moves has been considered. In this case, the motion of the particle is governed by equation (1.1), with \( \lambda(q) \equiv \lambda \), for every \( q \in \mathbb{R}^2 \) (for simplicity of notation in what follows we shall take \( \lambda = 1 \)). In particular, since the eigenvalues of \( A \) are purely imaginary, the methods and results described above are not applicable in this case.

It is not difficult to check that if the stochastic term in (1.1) is replaced by a continuous function, then \( q_\mu \) converges uniformly in \([0, T]\) to the solution of (1.4). But for the white noise the result is different: while

\[
\lim_{\mu \to 0} \int_0^t \sin \frac{s}{\mu} \varphi(s) \, ds = 0,
\]

for every continuous function \( \varphi \), when \( w(t) \) is a Brownian motion we have

\[
\text{Var} \left( \int_0^t \sin \frac{s}{\mu} \, dw(s) \right) = \int_0^t \sin^2 \frac{s}{\mu} \, ds \to \frac{t}{2}, \quad \text{as } \mu \downarrow 0,
\]

so that

\[
\lim_{\mu \to 0} \int_0^t \sin \frac{s}{\mu} \, dw(s) \neq 0.
\]

Because of this, in [5] the problem has been regularized, in order to prove a suitable analog of the Smoluchowski-Kramers approximation. The first regularization consisted in introducing equation (1.1) a small friction proportional to the velocity. Namely, the following equation has been considered

\[
\begin{align*}
\mu \ddot{q}_{\mu, \epsilon}(t) &= b(q_{\mu, \epsilon}(t)) - A_\epsilon \dot{q}_{\mu, \epsilon}(t) + \sigma(q_{\mu, \epsilon}(t)) \dot{w}(t), \\
q_{\mu, \epsilon}(0) &= q \in \mathbb{R}^2, \quad \dot{q}_{\mu, \epsilon}(0) = p \in \mathbb{R}^2,
\end{align*}
\]

where \( A_\epsilon = A + \epsilon I \) and \( \epsilon > 0 \) is a small parameter. It has been shown that for any \( T > 0 \)

\[
\lim_{\mu \to 0} \mathbb{E} \max_{t \in [0, T]} |q_{\mu, \epsilon}(t) - q_\epsilon(t)|^2 = 0,
\]

(1.7)

where \( q_\epsilon(t) \) is the solution of the problem

\[
dq(t) = A_\epsilon^{-1} b(q(t)) \, dt + A_\epsilon^{-1} \sigma(q(t)) \, dw(t), \quad q(0) = q.
\]

Next, it has been shown that

\[
\lim_{\epsilon \to 0} \mathbb{E} \max_{t \in [0, T]} |q_\epsilon(t) - q(t)|^2 = 0,
\]

where \( q(t) \) is the solution of the problem

\[
dq(t) = -A b(q(t)) \, dt - A \sigma(q(t)) \, dw(t), \quad q(0) = q.
\]

(1.8)

Another approach to regularization (see also [16] for the case of nonconstant magnetic field) used the fact that the white noise \( \dot{w}(t) \) can be considered as an idealization of an isotropic \( \delta \)-correlated smooth mean-zero Gaussian process \( \dot{w}^\delta(t) \), with \( 0 < \delta \ll 1 \), which converges to \( \dot{w}(t) \), as \( \delta \downarrow 0 \). In this case, it has been proven that if \( q_{\mu, \delta}(t) \) is the solution of equation (1.1), with \( \dot{w}(t) \) replaced by \( \dot{w}^\delta(t) \), then

\[
\lim_{\mu \to 0} \mathbb{E} \max_{t \in [0, T]} |q_{\mu, \delta}(t) - q_\delta(t)| = 0,
\]
where $q_\delta(t)$ solves the equation
\[
\dot{q}(t) = -Ab(q(t)) - A\sigma(q(t)) \dot{w}(t), \quad q(0) = q.
\]
Next, by taking the limit as $\delta \downarrow 0$, it has been proven that $q_\delta(t)$ converges to the solution $\hat{q}(t)$ of the problem
\[
d\hat{q}(t) = -Ab(\hat{q}(t)) \, dt - A\sigma(\hat{q}(t)) \circ dw(t), \quad \hat{q}(0) = q,
\]
where the stochastic term is now interpreted in Stratonovich sense.

In the present paper we are interested in the small mass limit in the presence of a nonconstant magnetic field. To this purpose we add a small constant friction and we consider the regularized equation
\[
\begin{align*}
\mu \dot{q}_{\mu,\epsilon}(t) &= b(q_{\mu,\epsilon}(t)) - \left[\lambda(q_{\mu,\epsilon}(t))A + \epsilon I\right] \dot{q}_{\mu,\epsilon}(t) + \sigma(q_{\mu,\epsilon}(t)) \dot{w}_I, \\
q_{\mu,\epsilon}(0) &= q \in \mathbb{R}^2, \quad \dot{q}_{\mu,\epsilon}(0) = p \in \mathbb{R}^2.
\end{align*}
\] (1.9)
We show that under suitable conditions on the coefficients $b$, $\sigma$, and $\lambda$, the above problem is well posed in $L^k(\Omega; C([0,T]; \mathbb{R}^2))$, for every $T > 0$ and $k \geq 1$.

For every fixed $\epsilon > 0$, equation (1.9) is of the same type as those considered in [13] and [14], so that we can take the small mass limit as $\mu$ goes to zero, obtaining
\[
\lim_{\mu \to 0} \mathbb{E} \sup_{t \in [0,T]} |q_{\mu,\epsilon}(t) - q_\epsilon(t)| = 0,
\]
where $q_\epsilon$ is the solution of the problem
\[
\begin{align*}
dq_\epsilon(t) &= \left[(\lambda(q_\epsilon(t))A + \epsilon I)^{-1} b(q_\epsilon(t)) + S_\epsilon(q_\epsilon(t))\right] dt + (\lambda(q_\epsilon(t))A + \epsilon I)^{-1} \sigma(q_\epsilon(t)) dw(t), \\
q_\epsilon(0) &= q.
\end{align*}
\]
After some computations, we obtain
\[
dq_\epsilon(q) = \frac{1}{\epsilon} \gamma(q_\epsilon(t)) \nabla^\perp \lambda(q_\epsilon(t)) dt + B(q_\epsilon(t)) + \Sigma(q_\epsilon(t)) \, dw(t),
\]
where the mappings $\gamma : \mathbb{R}^2 \to \mathbb{R}$, $B$, $B_\epsilon : \mathbb{R}^2 \to \mathbb{R}^2$ and $\Sigma, \Sigma_\epsilon : \mathbb{R}^2 \to \mathbb{R}^{2 \times 2}$ can be explicitly computed. This means that the motion of $q_\epsilon$ is a superposition of a fast component on the level sets of $\lambda$ and a slow transversal motion. Using a suitable generalization of the classical result of Freidlin and Wentzell on averaging for Hamiltonian systems (see [12, Chapter 8] and [26]), we shall prove that the projection of $q_\epsilon$ over the graph $\Gamma$, obtained by identifying all points on the same connected component of each level set of $\lambda$, converges to a Markov process $Y$, whose generator is explicitly given.

### 2 Well-Posedness of the Regularized Problem

As mentioned in the Introduction, we are dealing here with the equation
\[
\begin{align*}
\mu \dot{q}_\mu(t) &= b(q_\mu(t)) - \lambda(q_\mu(t))A\dot{q}_\mu(t) + \sigma(q_\mu(t)) \dot{w}_I, \\
q_\mu(0) &= q \in \mathbb{R}^2, \quad \dot{q}_\mu(0) = p \in \mathbb{R}^2.
\end{align*}
\] (2.1)
where $\mu$ is a small positive constant and $w(t)$ is a standard Brownian motion in $\mathbb{R}^2$.

In this section, we shall assume that the coefficients of the equation above satisfy the following assumptions. In Sect. 4 we will impose a more restrictive growth condition on $\lambda$.

**Hypothesis 1**

1. The mappings $b : \mathbb{R}^2 \to \mathbb{R}^2$ and $\sigma : \mathbb{R}^2 \to \mathbb{R}^{2 \times 2}$ are Lipschitz-continuous.

2. The mapping $\lambda : \mathbb{R}^2 \to \mathbb{R}$ is locally Lipschitz-continuous and there exist $\gamma \geq 0$ and $c > 0$ such that

$$|\lambda(q)| \leq c (1 + |q|^{\gamma}), \quad \lambda \in \mathbb{R}^2.$$  \hspace{1cm} (2.2)

Moreover

$$\inf_{q \in \mathbb{R}^2} \lambda(q) =: \lambda_0 > 0.$$

Next, for every $\epsilon \geq 0$ we introduce the regularized problem

$$
\begin{cases}
\mu \ddot{q}_{\mu, \epsilon}(t) = b(q_{\mu, \epsilon}(t)) - \Lambda_\epsilon(q_{\mu, \epsilon}(t)) \dot{q}_{\mu, \epsilon}(t) + \sigma(q_{\mu, \epsilon}(t)) \dot{w}_t, \\
q_{\mu, \epsilon}(0) = q \in \mathbb{R}^2, \quad \dot{q}_{\mu, \epsilon}(0) = p \in \mathbb{R}^2,
\end{cases}
$$

where

$$\Lambda_\epsilon(q) = \lambda(q) A + \epsilon I = \begin{pmatrix} \frac{\epsilon}{\lambda(q)} & \lambda(q) \\ -\lambda(q) & \epsilon \end{pmatrix}, \quad q \in \mathbb{R}^2.$$  \hspace{1cm} (2.3)

Notice that for every $\epsilon > 0$ the matrix $\Lambda_\epsilon(q)$ is uniformly non-degenerate, as

$$\langle \Lambda_\epsilon(q) p, p \rangle = \epsilon |p|^2.$$  \hspace{1cm} (2.4)

Moreover, when $\epsilon = 0$, equation (2.3) coincides with equation (2.1).

**Theorem 2.1** Under Hypothesis 1, for every $\mu > 0$ and $\epsilon \geq 0$ and for every $T > 0$ and $k \geq 1$, Eq. (2.3) admits a unique adapted solution $q_{\mu, \epsilon} \in L^k(\Omega; C([0, T]; \mathbb{R}^2))$.

**Proof** For every $q, p \in \mathbb{R}^2$ and $n \in \mathbb{N}$, we define

$$\beta_n(p) = \begin{cases} p, & \text{if } |p| \leq n, \\
np/|p|, & \text{if } |p| \geq n,
\end{cases}$$

and

$$\Lambda_{\epsilon, n}(q) = \lambda_n(q) A + \epsilon I, \quad \text{where} \quad \lambda_n(q) = \begin{cases} \lambda(q), & \text{if } |q| \leq n, \\
\lambda((n + 1)q/|q|), & \text{if } |q| \geq n + 1,
\end{cases}.$$

Notice that $\lambda_n : \mathbb{R}^2 \to \mathbb{R}$ is Lipschitz-continuous and

$$|\lambda_n(q)| \leq c (1 + |q|^{\gamma}), \quad |\beta_n(p)| \leq |p|,$$  \hspace{1cm} (2.5)

for some constant $c$ independent of $n$. Moreover, since $\langle A\beta_n(p), p \rangle = 0$, and $\langle \beta_n(p), p \rangle \leq |p|^2$, for every $p \in \mathbb{R}^2$ and $n \in \mathbb{N}$, we have

$$\langle \Lambda_{\epsilon, n}(q) \beta_n(p), p \rangle = \epsilon |p|^2,$$  \hspace{1cm} (2.6)

for every $p, q \in \mathbb{R}^2, n \in \mathbb{N}$ and $\epsilon > 0$.  

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With these notations, we introduce the problem
\[
\begin{cases}
\mu \dot{q}^{n}_{\mu, \epsilon}(t) = b(q^{n}_{\mu, \epsilon}(t)) - \Lambda_{\epsilon, n}(q^{n}_{\mu, \epsilon}(t)) \beta_{n}(q^{n}_{\mu, \epsilon}(t)) + \sigma(q^{n}_{\mu, \epsilon}(t)) \tilde{w}_{t}, \\
q^{n}_{\mu, \epsilon}(0) = q \in \mathbb{R}^{2}, \quad \dot{q}^{n}_{\mu, \epsilon}(0) = p \in \mathbb{R}^{2},
\end{cases}
\]
which can be rewritten as
\[
\begin{cases}
dq^{n}_{\mu, \epsilon}(t) = p^{n}_{\mu, \epsilon}(t) \ dt, \\
\mu dp^{n}_{\mu, \epsilon}(t) = \left[ b(q^{n}_{\mu, \epsilon}(t)) - \Lambda_{\epsilon, n}(q^{n}_{\mu, \epsilon}(t)) \beta_{n}(p^{n}_{\mu, \epsilon}(t)) \right] \ dt + \sigma(q^{n}_{\mu, \epsilon}(t)) \ dw(t), \\
p^{n}_{\mu, \epsilon}(0) = p.
\end{cases}
\]
(2.7)

It is immediate to check that, for every fixed \( n \in \mathbb{N} \) and \( \epsilon > 0 \), the mapping
\[
(q, p) \in \mathbb{R}^{2} \times \mathbb{R}^{2} \mapsto \Lambda_{\epsilon, n}(q) \beta_{n}(p) \in \mathbb{R}^{2},
\]
is Lipschitz-continuous, so that equation (2.7) admits a unique adapted solution \( (q^{n}_{\mu, \epsilon}, p^{n}_{\mu, \epsilon}) \in L^{p}(\Omega; C^{1}([0, T]; \mathbb{R}^{2}) \times C([0, T]; \mathbb{R}^{2})) \).

Now, applying Itô’s formula to the function \( \Phi(q, p) = |q|^{2k} + |p|^{2k} \), for \( k \geq 2 \), we obtain
\[
\begin{align*}
|q^{n}_{\mu, \epsilon}(t)|^{2k} + |p^{n}_{\mu, \epsilon}(t)|^{2k} &= |q|^{2k} + |p|^{2k} + k \int_{0}^{t} |q^{n}_{\mu, \epsilon}(s)|^{2k-2} \langle q^{n}_{\mu, \epsilon}(s), p^{n}_{\mu, \epsilon}(s) \rangle \ ds \\
& \quad + \frac{k}{\mu} \int_{0}^{t} |p^{n}_{\mu, \epsilon}(s)|^{2k-2} \langle p^{n}_{\mu, \epsilon}(s), b(q^{n}_{\mu, \epsilon}(s)) - \Lambda_{\epsilon, n}(q^{n}_{\mu, \epsilon}(s)) \beta_{n}(p^{n}_{\mu, \epsilon}(s)) \rangle \ ds \\
& \quad + \frac{k}{2\mu^{2}} \int_{0}^{t} |p^{n}_{\mu, \epsilon}(s)|^{2k-2} \left[ \sigma \sigma^{\star}(q^{n}_{\mu, \epsilon}(s)) \right] \ ds \\
& \quad + \frac{k}{\mu} \int_{0}^{t} |p^{n}_{\mu, \epsilon}(s)|^{2k-2} \langle p^{n}_{\mu, \epsilon}(s), \sigma(q^{n}_{\mu, \epsilon}(s)) \ dw(s) \rangle.
\end{align*}
\]

Therefore, thanks to (2.6) and to the Young inequality, we have for every \( \epsilon > 0 \)
\[
|q^{n}_{\mu, \epsilon}(t)|^{2k} + |p^{n}_{\mu, \epsilon}(t)|^{2k} \leq |q|^{2k} + |p|^{2k} + c_{k, \mu} \int_{0}^{t} \left[ |q^{n}_{\mu, \epsilon}(s)|^{2k} + |p^{n}_{\mu, \epsilon}(s)|^{2k} \right] \ ds \\
+ \frac{k}{\mu} \int_{0}^{t} |p^{n}_{\mu, \epsilon}(s)|^{2k-2} \langle p^{n}_{\mu, \epsilon}(s), \sigma(q^{n}_{\mu, \epsilon}(s)) \ dw(s) \rangle.
\]

Taking expected values in values of both sides and using the Gronwall lemma, we obtain
\[
\mathbb{E}|q^{n}_{\mu, \epsilon}(t)|^{2k} + \mathbb{E}|p^{n}_{\mu, \epsilon}(t)|^{2k} \leq c_{k, \mu}(T) \left( 1 + |q|^{2k} + |p|^{2k} \right), \quad t \in [0, T].
\]
(2.8)

Therefore, since
\[
q^{n}_{\mu, \epsilon}(t) = q + \int_{0}^{t} p^{n}_{\mu, \epsilon}(s) \ ds,
\]
and
\[
p^{n}_{\mu, \epsilon}(t) = p + \frac{1}{\mu} \int_{0}^{t} \left[ b(q^{n}_{\mu, \epsilon}(s)) - \Lambda_{\epsilon, n}(q^{n}_{\mu, \epsilon}(s)) \beta_{n}(p^{n}_{\mu, \epsilon}(s)) \right] \ ds + \frac{1}{\mu} \int_{0}^{t} \sigma(q^{n}_{\mu, \epsilon}(s)) \ dw(s),
\]
using (2.5), from (2.8) we obtain

$$\sup_{n \in \mathbb{N}} \mathbb{E} \sup_{t \in [0, T]} (|q_{\mu, \epsilon}^n(t)|^{2k} + |p_{\mu, \epsilon}^n(t)|^{2k}) \leq c_{k, \mu}(T, |q|, |p|).$$

(2.9)

Now, for any $n \in \mathbb{N}$ we define

$$\tau_n = \inf \{ t \geq 0 : |q_{\mu, \epsilon}^n(t)| \lor |p_{\mu, \epsilon}^n(t)| \geq n \},$$

with the usual convention that $\inf \emptyset = +\infty$. Since

$$(q_{\mu, \epsilon}^n(t), p_{\mu, \epsilon}^n(t)) = (q_{\mu, \epsilon}^m(t), p_{\mu, \epsilon}^m(t)), \quad n < m, \quad t \leq \tau_n,$$

(2.10)

it follows that the sequence $\{\tau_n\}_{n \in \mathbb{N}}$ is non-decreasing, $\mathbb{P}$-a.s., so that we can define

$$\tau = \lim_{n \to \infty} \tau_n.$$

Due to (2.9), for every fixed $T > 0$ we have

$$\mathbb{P} \left( \sup_{t \in [0, T]} |q_{\mu, \epsilon}^n(t) \leq n, \sup_{t \in [0, T]} |p_{\mu, \epsilon}^n(t) \leq n \right) \geq 1 - \mathbb{P} \left( \sup_{t \in [0, T]} |q_{\mu, \epsilon}^n(t) > n \right) - \mathbb{P} \left( \sup_{t \in [0, T]} |p_{\mu, \epsilon}^n(t) > n \right) \geq 1 - \frac{2c_1, \mu(T, |q|, |p|)}{n}.$$

This implies

$$\lim_{n \to \infty} \mathbb{P}(\tau_n > T) = 1,$$

and then, since $T$ is arbitrary, we conclude

$$\mathbb{P}(\tau = +\infty) = 1.$$

In particular, if we set

$$(q_{\mu, \epsilon}(t), p_{\mu, \epsilon}(t)) = (q_{\mu, \epsilon}^n(t \land \tau_n), p_{\mu, \epsilon}^n(t \land \tau_n)), \quad t \leq \tau,$$

due to (2.10) we can conclude that there exists a unique solution $(q_{\mu, \epsilon}, p_{\mu, \epsilon})$ to problem (2.3), belonging to $L^k(\Omega; C^1([0, T]; \mathbb{R}^2) \times C([0, T]; \mathbb{R}^2))$, for every $k \geq 1$ and $T > 0$. □

3 The Smoluchowski–Kramers Approximation for the Regularized Problem

For every $\epsilon > 0$ and $q \in \mathbb{R}^2$, the matrix $\Lambda_\epsilon(q)$ is invertible and

$$\Lambda_\epsilon^{-1}(q) = \frac{1}{\lambda^2(q) + \epsilon^2} \begin{pmatrix} \epsilon & -\lambda(q) \\ \lambda(q) & \epsilon \end{pmatrix}.$$

(3.1)

We introduce the vector field $S_\epsilon(q)$, whose $j$-th component is defined by

$$S_\epsilon^j(q) = \sum_{i,l=1}^2 \partial_i(\Lambda_\epsilon^{-1})_{jl}(q)J_\epsilon^i(q), \quad j = 1, 2,$$

(3.2)
where \( \partial_t = \partial/\partial q_i \) and \( J^\epsilon \) is the matrix-valued function solving the Lyapunov equation
\[
J^\epsilon(q) \Lambda^*_\epsilon(q) + \Lambda_\epsilon(q) J^\epsilon(q) = \sigma(q)\sigma^*(q), \quad q \in \mathbb{R}^2.
\]

Thanks to (2.4), the equation above has a unique solution \( J^\epsilon \) which can be explicitly written as
\[
J^\epsilon(q) = \int_0^\infty e^{-\lambda(q)r} \sigma \sigma^*(q) e^{-\Lambda^*_\epsilon(q)r} dr = \int_0^\infty e^{-\lambda(q)Ar} \sigma \sigma^*(q) e^{\lambda(q)Ar} e^{-2\epsilon r} dr, \quad q \in \mathbb{R}^2. \tag{3.3}
\]

It is immediate to check that
\[
e^{-\lambda(q)Ar} = \begin{pmatrix}
\cos(\lambda(q)r) - \sin(\lambda(q)r) \\
\sin(\lambda(q)r) \cos(\lambda(q)r)
\end{pmatrix}, \quad r \geq 0.
\]

In what follows, for every \( q \in \mathbb{R}^2 \) we denote
\[
\begin{pmatrix}
a_1(q) & a_0(q) \\
a_0(q) & a_2(q)
\end{pmatrix} =: \sigma \sigma^*(q),
\]
and
\[
\beta_0(q) := \frac{a_1(q) + a_2(q)}{4}, \quad \beta_1(q) := \frac{a_1(q) - a_2(q)}{4}, \quad \beta_2(q) := \frac{a_0(q)}{2}. \tag{3.4}
\]

Lemma 3.1 Assume that \( \lambda: \mathbb{R}^2 \to \mathbb{R} \) is differentiable. Then, there exist \( M: \mathbb{R}^2 \to \mathbb{R}^{2\times 2} \) and \( R^\epsilon: \mathbb{R}^2 \to \mathbb{R}^{2\times 2} \) such that for every \( \epsilon > 0 \)
\[
S^\epsilon(q) = \frac{1}{\epsilon} \frac{\beta_0(q)}{\lambda^2(q)} \nabla^\perp \lambda(q) - M(q) \nabla \lambda(q) + R^\epsilon(q) \nabla \lambda(q), \quad q \in \mathbb{R}^2. \tag{3.5}
\]

Proof Thanks to (3.3), we have
\[
\begin{align*}
J^\epsilon_{11}(q) &= \frac{\beta_0(q)}{\epsilon} + \beta_1(q) \int_0^\infty \cos(\lambda(q)r)e^{-\epsilon r} dr - \beta_2(q) \int_0^\infty \sin(\lambda(q)r)e^{-\epsilon r} dr, \\
J^\epsilon_{22}(q) &= \frac{\beta_0(q)}{\epsilon} - \beta_1(q) \int_0^\infty \cos(\lambda(q)r)e^{-\epsilon r} dr + \beta_2(q) \int_0^\infty \sin(\lambda(q)r)e^{-\epsilon r} dr, \\
J^\epsilon_{12}(q) &= J^\epsilon_{21}(q) = \beta_1(q) \int_0^\infty \sin(\lambda(q)r)e^{-\epsilon r} dr + \beta_2(q) \int_0^\infty \cos(\lambda(q)r)e^{-\epsilon r} dr.
\end{align*}
\]

Integrating by parts, we obtain
\[
\int_0^\infty \cos(\lambda(q)r)e^{-\epsilon r} dr = \frac{\epsilon}{\lambda^2(q) + \epsilon^2},
\]
and
\[
\int_0^\infty \sin(\lambda(q)r)e^{-\epsilon r} dr = \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2}.
\]
This implies
\[
J_{11}'(q) = \frac{\beta_0(q)}{\epsilon} + \beta_1(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} - \beta_2(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2}
\]
\[
J_{22}'(q) = \frac{\beta_0(q)}{\epsilon} - \beta_1(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2}
\]
\[
J_{12}'(q) = J_{21}'(q) = \beta_1(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2}
\]
(3.6)

Now, due to (3.1), for every $\epsilon > 0$ and $q \in \mathbb{R}^2$ we have
\[
\partial_i \left( \Lambda^{-1}_\epsilon \right)_{11} (q) = \partial_i \left( \Lambda^{-1}_\epsilon \right)_{22} (q) = -\frac{2\epsilon \lambda(q)}{(\lambda^2(q) + \epsilon^2)^2} \partial_i \lambda(q), \quad i = 1, 2,
\]
\[
\partial_i \left( \Lambda^{-1}_\epsilon \right)_{12} (q) = -\partial_i \left( \Lambda^{-1}_\epsilon \right)_{21} (q) = -\frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^2} \partial_i \lambda(q), \quad i = 1, 2.
\]
(3.7)

Substituting (3.6) and (3.7) in (3.2), we obtain
\[
S_1^\epsilon(q) = -\frac{2\epsilon \lambda(q)}{(\lambda^2(q) + \epsilon^2)^2} \left[ \left( \frac{\beta_0(q)}{\epsilon} + \beta_1(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} - \beta_2(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} \right) \partial_1 \lambda(q)
\right.
\]
\[+ \left( \beta_1(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} \right) \partial_2 \lambda(q) \right]
\]
\[+ \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^2} \left[ \left( \beta_1(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} \right) \partial_1 \lambda(q)
\right.
\]
\[+ \left( \frac{\beta_0(q)}{\epsilon} - \beta_1(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} \right) \partial_2 \lambda(q) \right],
\]

and
\[
S_2^\epsilon(q) = -\frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^2} \left[ \left( \frac{\beta_0(q)}{\epsilon} + \beta_1(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} - \beta_2(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} \right) \partial_1 \lambda(q)
\right.
\]
\[+ \left( \beta_1(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} \right) \partial_2 \lambda(q) \right]
\]
\[- \frac{2\epsilon \lambda(q)}{(\lambda^2(q) + \epsilon^2)^2} \left[ \left( \beta_1(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} \right) \partial_1 \lambda(q)
\right.
\]
\[+ \left( \frac{\beta_0(q)}{\epsilon} - \beta_1(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} \right) \partial_2 \lambda(q) \right],
\]

Now, we define
\[
\Gamma_1^\epsilon(q) := \beta_1(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2} + \beta_2(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2}, \quad \Gamma_1(q) := \frac{\beta_1(q)}{\lambda(q)},
\]

and
\[
\Gamma_2^\epsilon(q) := \beta_1(q) \frac{\epsilon}{\lambda^2(q) + \epsilon^2} - \beta_2(q) \frac{\lambda(q)}{\lambda^2(q) + \epsilon^2}, \quad \Gamma_2(q) := -\frac{\beta_2(q)}{\lambda(q)}.
\]
With these notations
\[
S_1^e(q) = \frac{1}{\epsilon} \beta_0(q) \partial_2 \lambda(q) + \left[ -\frac{2\beta_0(q)}{\lambda^3(q)} + \frac{\Gamma_1(q)}{\lambda^2(q)} \right] \partial_1 \lambda(q) - \frac{\Gamma_2(q)}{\lambda^2(q)} \partial_2 \lambda(q)
\]
\[
+ R_{11}^e(q) \partial_1 \lambda(q) + R_{12}^e(q) \partial_2 \lambda(q),
\]

where
\[
R_{11}^e(q) := -\frac{2\epsilon \lambda(q)}{\epsilon(q)} \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^2} \Gamma_2(q) + \epsilon \beta_2(q) \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^3}
\]
\[
+ 2 \beta_0(q) \left[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)}{(\lambda^2(q) + \epsilon^2)^2} \right] - \beta_1(q) \left[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)(\lambda^2(q) - \epsilon^2)}{(\lambda^2(q) + \epsilon^2)^3} \right],
\]
and
\[
R_{12}^e(q) := -\frac{2\lambda(q)\epsilon}{(\lambda^2(q) + \epsilon^2)^2} \Gamma_1(q) - \epsilon \beta_2(q) \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^3}
\]
\[
- \frac{\beta_0(q)}{\epsilon} \left[ \frac{1}{\lambda^2(q)} - \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^2} \right] + \beta_1(q) \left[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)(\lambda^2(q) - \epsilon^2)}{(\lambda^2(q) + \epsilon^2)^3} \right].
\]

Similarly, we have
\[
S_2^e(q) = -\frac{1}{\epsilon} \beta_0(q) \partial_1 \lambda(q) - \frac{\Gamma_2(q)}{\lambda^2(q)} \partial_1 \lambda(q) - \left[ \frac{2\beta_0(q)}{\lambda^3(q)} + \frac{\Gamma_1(q)}{\lambda^2(q)} \right] \partial_2 \lambda(q)
\]
\[
+ R_{21}^e(q) \partial_1 \lambda(q) + R_{22}^e(q) \partial_2 \lambda(q),
\]

where
\[
R_{21}^e(q) := -\frac{2\lambda(q)\epsilon}{(\lambda^2(q) + \epsilon^2)^2} \Gamma_1(q) - \epsilon \beta_1(q) \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^3}
\]
\[
+ \beta_0(q) \left[ \frac{1}{\lambda^2(q)} - \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^2} \right] - \beta_2(q) \left[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)(\lambda^2(q) - \epsilon^2)}{(\lambda^2(q) + \epsilon^2)^3} \right],
\]
and
\[
R_{22}^e(q) := \frac{2\epsilon \lambda(q)}{(\lambda^2(q) + \epsilon^2)^2} \Gamma_2^e - \epsilon \beta_2(q) \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^3}
\]
\[
+ 2 \beta_0(q) \left[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)}{(\lambda^2(q) + \epsilon^2)^2} \right] + \beta_1(q) \left[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)(\lambda^2(q) - \epsilon^2)}{(\lambda^2(q) + \epsilon^2)^3} \right].
\]

Therefore, recalling that \( \Gamma_1(q) = \beta_1(q)/\lambda(q) \) and \( \Gamma_2(q) = -\beta_2(q)/\lambda(q) \), if we define
\[
M(q) = \frac{1}{\lambda^3(q)} \begin{pmatrix} 2\beta_0(q) - \beta_1(q) & -\beta_2(q) \\ -\beta_2(q) & 2\beta_0(q) + \beta_1(q) \end{pmatrix},
\]
and \( R^e(q) = (R_{ij}^e(q))_{i,j=1,2} \), where the components \( R_{ij}^e(q) \) are defined in (3.8), (3.9), (3.10) and (3.11), we obtain (3.5).
In what follows we shall assume that the following condition is satisfied.

**Hypothesis 2**

1. The mapping \( \lambda : \mathbb{R}^2 \to \mathbb{R} \) is continuously differentiable.
2. For every \( \epsilon > 0 \), the mapping \( \Lambda_{\epsilon}^{-1}b : \mathbb{R}^2 \to \mathbb{R}^2 \) introduced in (3.2) is locally Lipschitz-continuous and has linear growth.
3. For every \( \epsilon > 0 \) the mappings \( \Lambda_{\epsilon}^{-1}b \) and \( \Lambda_{\epsilon}^{-1}\sigma : \mathbb{R}^2 \to \mathbb{R}^2 \times \mathbb{R}^2 \) are locally Lipschitz-continuous and have linear growth.

**Remark 3.2**

1. Using the explicit expression of \( M(q) \) given in (3.12) and the expressions for the coefficients of \( R_{\epsilon}(q) \) given in (3.8), (3.9), (3.10) and (3.11), thanks to what we have already assumed in Hypothesis 1, we can check easily that Hypothesis 2 is satisfied if we assume \( \sigma \) to be bounded and \( \lambda \) to be bounded and differentiable, with \( \nabla \lambda : \mathbb{R}^2 \to \mathbb{R}^2 \) Lipschitz-continuous.
2. On the other hand, if we assume that \( \nabla \lambda : \mathbb{R}^2 \to \mathbb{R}^2 \) is locally Lipschitz-continuous and has linear growth and there exists \( c > 0 \) such that for \( |q| \) large enough

\[
|\lambda(q)| \geq c |q|, 
\]

then Hypothesis 2 is satisfied, without assuming \( \sigma \) to be bounded.

**Theorem 3.3**

For every \( \mu, \epsilon > 0 \), let \( q_{\mu,\epsilon} \) be the solution of problem (2.7). Then, under Hypotheses 1 and 2, for every \( \epsilon > 0 \) we have

\[
\lim_{\mu \to 0} \mathbb{E} \sup_{t \in [0,T]} |q_{\mu,\epsilon}(t) - q_{\epsilon}(t)| = 0, \tag{3.13}
\]

where \( q_{\epsilon} \) is the solution of the problem

\[
dq_{\epsilon}(t) = \left[ \Lambda_{\epsilon}^{-1}b(q_{\epsilon}(t)) + S_{\epsilon}(q_{\epsilon}(t)) \right] dt + \Lambda_{\epsilon}^{-1}\sigma(q_{\epsilon}(t)) dw(t), \quad q_{\epsilon}(0) = q. \tag{3.14}
\]

**Proof** Assuming Hypotheses 1 and 2, we have that for every \( \epsilon > 0 \) and for every \( k \geq 1 \) and \( T > 0 \) problem (3.14) admits a unique solution \( q_{\epsilon} \in L^k(\Omega; C([0, T]; \mathbb{R}^2)) \). As \( \langle \Lambda_{\epsilon}(q)p, p \rangle = \epsilon |p|^2 \), this allows to conclude the proof thanks to [13, Theorem 2.4]. \( \square \)

### 4 The Averaging Limit

In this section we want to investigate the limiting behavior of the slow component of \( q_{\epsilon} \), as \( \epsilon \) goes to zero. To this purpose, we need to introduce some preliminary material.

#### 4.1 Some Notations and Further Assumptions

We consider here the system

\[
\dot{X}(t) = \frac{\beta_0(X(t))}{\lambda^2(X(t))} \nabla \perp \lambda(X(t)). \tag{4.1}
\]
Clearly, for every \( t \geq 0 \), we have \( \lambda(X(t)) = \lambda(X(0)) \). Now, if we consider the perturbed system

\[
\frac{dX_\epsilon(t)}{dt} = \frac{\beta_0(X_\epsilon(t))}{\lambda^2(X_\epsilon(t))} \nabla \perp \lambda(X_\epsilon(t)) + \epsilon \left[ \frac{1}{\lambda(X_\epsilon(t))} Ab(X_\epsilon(t)) - M(X_\epsilon(t)) \nabla \lambda(X_\epsilon(t)) \right] dt + \frac{\sqrt{\epsilon}}{\lambda(X_\epsilon(t))} A \sigma(X_\epsilon(t)) dw(t) + \epsilon B_\epsilon(X_\epsilon(t)) b(X_\epsilon(t)) + \frac{\sqrt{\epsilon}}{2} H_\epsilon(X_\epsilon(t)) \sigma(X_\epsilon(t)) \frac{d}{dt} w(t),
\]

the quantity \( \lambda(X_\epsilon(t)) \) is no longer conserved. However, for any fixed time interval \([0, T]\) and for every \( k \geq 1 \), we have

\[
\lim_{\epsilon \to 0} \mathbb{E} \sup_{t \in [0, T]} |X_\epsilon(t) - X(t)|^k = 0,
\]

and, as an immediate consequence,

\[
\lim_{\epsilon \to 0} \mathbb{E} \sup_{t \in [0, T]} |\lambda(X_\epsilon(t)) - \lambda(X(0))|^k = 0.
\]

Now, with the change of time \( t \mapsto t/\epsilon \), we can check that

\[
\mathcal{L}(X_\epsilon(\cdot/\epsilon)) = \mathcal{L}(q_\epsilon(\cdot)),
\]

where \( q_\epsilon \) is the solution of equation (3.14). As mentioned above, our aim is to identify the non trivial limit for the distribution of the process \( \lambda(q_\epsilon(\cdot)) \), as \( \epsilon \downarrow 0 \). To this purpose, in addition to Hypotheses 1 and 2, we assume that \( \lambda \) satisfies the following conditions.

**Hypothesis 3**

1. If \( \beta_0 \) is the function defined in (3.4), we have

\[
\inf_{x \in \mathbb{R}^2} \beta_0(x) > 0. \tag{4.2}
\]

2. The mapping \( \lambda : \mathbb{R}^2 \to \mathbb{R} \) is four times continuously differentiable, with bounded second derivative.

3. The mapping \( \lambda \) has only a finite number of critical points \( x_1, \ldots, x_n \). The matrix of second derivative \( D^2 \lambda(x_i) \) is non degenerate, for every \( i = 1, \ldots, n \) and \( \lambda(x_i) \neq \lambda(x_j) \), if \( i \neq j \).

4. There exists a positive constant \( a \) such that \( \lambda(x) \geq a |x|^2, |\nabla \lambda(x)| \geq a |x| \) and \( \Delta \lambda(x) \geq a \), for all \( x \in \mathbb{R}^2 \), with \( |x| \) large enough.

**Remark 4.1** Remember that the function \( \beta_0 \) was defined as \( [\sigma \sigma^*]_{11}^2 + [\sigma \sigma^*]_{22}^2 ]/4 \). Therefore, condition (4.2) is a non-degeneracy condition on the noisy perturbation.

Next, for every \( z \geq \lambda_0 \), we denote by \( C(z) \) the \( z \)-level set

\[
C(z) = \{ x \in \mathbb{R}^2 : \lambda(x) = z \}.
\]

The set \( C(z) \) may consist of several connected components

\[
C(z) = \bigcup_{k=1}^{N(z)} C_k(z),
\]
and for every $x \in \mathbb{R}^2$ we have

$$X(0) = x \implies X(t) \in C_{k(x)}(\lambda(x)), \quad t \geq 0,$$

where $C_{k(x)}(x)$ is the connected component of the level set $C(\lambda(x))$, to which the point $x$ belongs. For every $z \geq 0$ and $k = 1, \ldots, N(z)$, we shall denote by $G_k(z)$ the domain of $\mathbb{R}^2$ bounded by the level set component $C_k(z)$.

If we identify all points in $\mathbb{R}^2$ belonging to the same connected component of a given level set $C(z)$ of the Hamiltonian $\lambda$, we obtain a graph $\Gamma$, given by several edges $I_1, \ldots, I_n$ and vertices $O_1, \ldots, O_m$. The vertices will be of two different types, external and internal vertices. External vertices correspond to local extrema of $\lambda$, while internal vertices correspond to saddle points of $\lambda$. Among external vertices, we will also include $O_{\infty}$, the vertex of the graph corresponding to the point at infinity.

In what follows, we shall denote by $\Pi : \mathbb{R}^2 \rightarrow \Gamma$ the identification map, that associates to every point $x \in \mathbb{R}^2$ the corresponding point $\Pi(x)$ of the graph $\Gamma$. We have $\Pi(x) = (\lambda(x), k(x))$, where $k(x)$ denotes the number of the edge on the graph $\Gamma$, containing the point $\Pi(x)$. If $O_i$ is one of the interior vertices, the second coordinate cannot be chosen in a unique way, as there are three edges having $O_i$ as their endpoint. Notice that both $k(x)$ and $H(x)$ are first integrals (a discrete and a continuous one, respectively) of system (4.1).

On the graph $\Gamma$, a distance can be introduced in the following way. If $y_1 = (z_1, k)$ and $y_2 = (z_2, k)$ belong to the same edge $I_k$, then $d(y_1, y_2) = |z_1 - z_2|$. In the case $y_1$ and $y_2$ belong to different edges, then

$$d(y_1, y_2) = \min \left\{ d(y_1, O_{i_1}) + d(O_{i_1}, O_{i_2}) + \cdots + d(O_{i_j}, y_2) \right\},$$

where the minimum is taken over all possible paths from $y_1$ to $y_2$, through every possible sequence of vertices $O_{i_1}, \ldots, O_{i_j}$, connecting $y_1$ to $y_2$.

If $z$ is not a critical value, then each $C_k(z)$ consists of one periodic trajectory of the vector field $\nabla^\perp \lambda(x)$. If $z$ is a local extremum of $\lambda(x)$, then, among the components of $C(z)$ there is a set consisting of one point, the equilibrium point of the flow. If $\lambda(x)$ has a saddle point at some point $x_0$ and $\lambda(x_0) = z$, then $C(z)$ consists of three trajectories: the equilibrium point $x_0$ and the two trajectories that have $x_0$ as their limiting point, as $t \rightarrow \pm \infty$.

Now, for every $(z, k) \in \Gamma$, we define

$$T_k(z) = \oint_{C_k(z)} \frac{\lambda^2(x)}{\beta_0(x)|\nabla \lambda(x)|} \, dl_{z,k}, \quad (4.3)$$

where $dl_{z,k}$ is the length element on $C_k(z)$. Notice that $T_k(z)$ is the period of the motion along the level set $C_k(z)$.

As is seen above, if $X(0) = x \in C_k(z)$, then $X(t) \in C_k(z)$, for every $t \geq 0$. As known, for every $(z, k) \in \Gamma$ the probability measure

$$d\mu_{z,k} := \frac{1}{T_k(z)} \frac{\lambda^2(x)}{\beta_0(x)|\nabla \lambda(x)|} \, dl_{z,k} \quad (4.4)$$

is invariant for system (4.1) on the level set $C_k(z)$.

### 4.2 The Limit of $\Pi(q_\varepsilon)$

Due to (3.1), for every $\varepsilon > 0$ we have

$$\Lambda_\varepsilon^{-1}(q) = \frac{1}{\lambda(q)} A + \varepsilon H^\varepsilon(q). \quad (4.5)$$
where

\[ H^\epsilon(q) := \frac{1}{\lambda^2(q) + \epsilon^2} \left( I - \frac{\epsilon}{\lambda(q)} A \right). \]

Notice that

\[ \sup_{\epsilon > 0} |H^\epsilon(q)| < \infty, \quad q \in \mathbb{R}^2. \]  \hspace{1cm} (4.6)

**Lemma 4.2** Let \( R^\epsilon : \mathbb{R}^2 \to \mathbb{R}^{2 \times 2} \) be the mapping introduced in Lemma 3.1. Then

\[ \sup_{\epsilon > 0} \frac{1}{\epsilon} |\tilde{R}^\epsilon(q)| < \infty, \quad q \in \mathbb{R}^2. \]  \hspace{1cm} (4.7)

**Proof** We have

\[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)}{(\lambda^2(q) + \epsilon^2)^2} = \epsilon^2 \left[ \frac{2\lambda^2(q) + \epsilon^2}{\lambda^3(q)(\lambda^2(q) + \epsilon^2)^2} \right], \]

and

\[ \frac{1}{\lambda^3(q)} - \frac{\lambda(q)(\lambda^2(q) - \epsilon^2)}{(\lambda^2(q) + \epsilon^2)^3} = \epsilon^2 \left[ \frac{4\lambda^4(q) + 3\epsilon^2\lambda^2(q) + \epsilon^4}{\lambda^3(q)(\lambda^2(q) + \epsilon^2)^3} \right], \]

and

\[ \frac{1}{\lambda^2(q)} - \frac{\lambda^2(q) - \epsilon^2}{(\lambda^2(q) + \epsilon^2)^2} = \epsilon^2 \left[ \frac{3\lambda^2(q) + \epsilon^2}{\lambda^2(q)(\lambda^2(q) + \epsilon^2)^2} \right]. \]

Therefore, in view of the definition of \( R^\epsilon(q) \) in (3.8), (3.9), (3.10) and (3.11), this concludes the proof. \( \square \)

According to (3.5), (4.5), (4.6) and (4.7), equation (3.14) can be rewritten as

\[
\begin{align*}
 dq_e(t) &= \frac{1}{\epsilon} \beta_0(q_e(t)) \nabla \lambda(q_e(t)) dt + B(q_e(t)) dt + \Sigma(q_e(t)) d\omega(t), \\
&\quad + \epsilon [B_e(q_e(t)) dt + \Sigma_e(q_e(t)) d\omega(t)], \quad q_e(0) = q, \hspace{1cm} (4.8)
\end{align*}
\]

where

\[ B(q) = \frac{1}{\lambda(q)} Ab(q) - M(q) \nabla \lambda(q), \quad \Sigma(q) = \frac{1}{\lambda(q)} A\sigma(q), \]

and

\[ B_e(q) = H^\epsilon(q) b(q) + \frac{1}{\epsilon} R^\epsilon(q) \nabla \lambda(q), \quad \Sigma_e(q) = H^\epsilon(q) \sigma(q). \]

This means that, as \( \epsilon \downarrow 0 \), some of the coefficients are of order \( O(\epsilon^{-1}) \), part of order \( O(1) \) and part of order \( O(\epsilon) \).

With the notations introduced in the previous section, in what follows, we want to investigate the limiting behavior of the \( \Gamma \)-valued process \( \Pi(q_e(\cdot)) = (\lambda(q_e(\cdot)), k(q_e(\cdot))) \), as \( \epsilon \downarrow 0 \).

Applying Itô’s formula to \( \lambda(q_e(t)) \), we get

\[
\begin{align*}
d\lambda(q_e(t)) &= \mathcal{G}_\lambda(q_e(t)) dt + A\lambda(q_e(t)) d\omega(t) + \epsilon \mathcal{G}_\lambda(q_e(t)) dt + \epsilon \mathcal{A}_\lambda(q_e(t)) d\omega(t),
\end{align*}
\]
where for every \( f \in \mathcal{C}^2(\mathbb{R}) \) and \( q \in \mathbb{R}^2 \)

\[
\mathcal{G}f(q) = \frac{1}{2} \text{Tr} \left[ \Sigma \Sigma^*(q) D^2 f(q) \right] + \langle D f(q), B(q) \rangle,
\]

\[
A_f(q) = \Sigma(q)^* D f(q),
\]

\[
\mathcal{G}_e f(q) = \frac{1}{2} \text{Tr} \left[ \epsilon \Sigma_e \Sigma^*_e(q) + \Sigma \Sigma^*_e(q) + \Sigma_e \Sigma^*(q) \right] D^2 f(q) + \langle D f(q), B_e(q) \rangle,
\]

and

\[
A_e f(q) = \Sigma^*_e(q) D f(q).
\]

We recall that the graph \( \Gamma \) is made of \( n \) edges \( I_1, \ldots, I_n \) and \( m \) vertices \( O_1, \ldots, O_m \). For every \( j = 1, \ldots, n \) and for every \( f \) that is twice differentiable in the interior of the edge \( I_j \), we denote

\[
\mathcal{L}_j f(z) = \frac{1}{2} \alpha_j(z) f''(x) + \gamma_j(z) f'(z),
\]

where

\[
\alpha_j(z) = \oint_{C_j(z)} |A \lambda(x)|^2 d\mu_{z,j}(x) = \oint_{C_j(z)} |\Sigma^* \nabla \lambda(x)|^2 d\mu_{z,j}(x),
\]

\[
\gamma_j(z) = \oint_{C_j(z)} G \lambda(x) d\mu_{z,j}(x),
\]

and \( d\mu_{z,j} \) is the probability measure introduced in (4.4).

**Definition 4.3** For each interior vertex \( O_k \) and any edge \( I_j \) adjacent to \( O_k \) (notation \( I_j \sim O_k \)), let \( \rho_{kj} \) be the positive constant defined by

\[
\rho_{kj} = \oint_{C_{kj}} \frac{\lambda^2(x)}{B_0(x)|\nabla \lambda(x)|} |\Sigma^* \nabla \lambda(x)|^2 dl(x).
\]

We denote by \( \mathcal{D}(L) \subset \mathcal{C}(\Gamma) \) the set consisting all continuously differentiable functions \( f \) defined on the graph \( \Gamma \) such that \( \mathcal{L}_j f \) is well defined in the interior of the edge \( I_j \) and for every \( I_j \sim O_k \) there exists finite

\[
\lim_{x \to O_k} \mathcal{L}_j f(x)
\]

and the limit is independent of the edge \( I_j \). Moreover, for each interior vertex \( O_k \)

\[
\sum_{j: I_j \sim O_k} \pm \rho_{kj} f'_j(\lambda(O_k)) = 0,
\]

where \( f'_j \) denotes the derivative of \( f \) with respect to the local coordinate \( z \), along the edge \( I_j \) and the sign \( \pm \) are taken if on the edge \( I_j \) it holds \( z > \lambda(O_k) \) or \( z < \lambda(O_k) \).

Next, for every \( f \in \mathcal{D}(L) \), we define

\[
Lf(x) = \begin{cases} 
\mathcal{L}_j f(x), & \text{if } x \text{ is an interior point of } I_j, \\
\lim_{x \to O_k} \mathcal{L}_j f(x), & \text{if } x \text{ is the vertex } O_k \text{ and } I_j \sim O_k.
\end{cases}
\]

As proven in [12, Theorem 8.2.1], in case \( \Sigma(q) = I \) the operator \( L \) defined on the domain \( \mathcal{D}(L) \), as described in Definition 4.3, is the generator of a strong Markov process \( Y_t \) on \( \Gamma \) with continuous trajectories. Here the same result holds, because of the non-degeneracy condition (4.2) satisfied by the diffusion coefficient \( \Sigma(q) \).
In fact, as shown in the next theorem, the Markov process $Y$ is the weak limit in $C([0, T]; \Gamma)$ of the slow motion $\Pi(q_\epsilon(\cdot))$ on $\Gamma$.

**Theorem 4.4** Under Hypotheses 1, 2 and 3, for every fixed $T > 0$ the $\Gamma$-valued process $\Pi(q_\epsilon(\cdot))$ converges weakly in $C([0, T]; \Gamma)$ to the Markov process $Y$ generated by the operator $(L, D(L))$, introduced in Definition 4.3.

**Proof** If in equation (4.8) we have $B(q) = B_\epsilon(q) = \Sigma(q) = 0$ and $\Sigma(q) = I$, the result above is what is proven in [12, Theorem 8.2.2]. In the present situation we are dealing with the more general situation in which we have a coefficient $B(q)$ of order $O(1)$ and coefficients $B_\epsilon(q)$ of order $O(\epsilon)$. Moreover we allow a non-constant diffusion coefficient $\Sigma(q) + \Sigma_\epsilon(q)$, where $\Sigma(q)$ is of order $O(1)$ and $\Sigma_\epsilon(q)$ is of order $O(\epsilon)$. As shown in [26], under these more general assumptions, an averaging principle of the same type of the one described in [12, Theorem 8.2.2] is still valid. This of course has required to introduce a suitable generalization of the operator $(L, D(L))$, that takes into account the coefficients $B$ and $\Sigma$, and to extend the limiting result in presence of the vanishing terms $B_\epsilon$ and $\Sigma_\epsilon$. \hfill $\square$

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