1. Introduction

In just-in-time (JIT) scheduling, the decision maker intends to find a rational scheduling scheme so that all jobs will not be completed either too early or too late. In general, it is assumed that there are job due dates in the JIT scheduling model, and both earliness and tardiness are penalized. This paper tackles a scheduling model involving earliness and tardiness penalties in both quadratic and fixed form, that is, these penalties contain not only the variable charges hinging upon the quadratic earliness/tardiness of the jobs but also the fixed charges generated once the job is not punctually finished no matter how much the earliness/tardiness is. Hence, in order to avoid these penalties as much as possible, it is of great importance for decision maker to allocate the job due dates.

The single machine environment plays a crucial role in scheduling theory. The performance of complex systems such as parallel machines generally depends on the schedule quality of a single bottleneck machine. Also, some results and insights obtained from the research of the single machine problems can be regarded to be valuable for solving the scheduling problems on more complex systems. The deterministic models related to single machine JIT scheduling problem have become an extensive research topic discussed since the later 1970s. Sidney [1] was one of the pioneers to study this class of scheduling problem. Kanet [2] proposed a constructive algorithm to find an optimal solution in polynomial time for the scheduling problem, where earliness and tardiness penalties are unit weights. Lann and Mosheiov [3], firstly, investigated the problem with the number of early and tardy jobs related to several cost structures by some heuristic algorithms. Later, there were many scheduling problems with earliness and tardiness
penalties which have been studied in [4–6] by different algorithms, whilst this type of scheduling problem with controllable processing times was discussed in [7, 8], and the notion of job preemption in this type of scheduling problem was also examined in [9, 10]. The problems of minimizing the quadratic earliness and tardiness have also been considered. In [11–13], researchers, under different assumptions, considered the problem in which all quadratic earliness and tardiness penalties are equal, and this problem with symmetric weighted quadratic penalty function was also studied in [14, 15], while the asymmetric weighted version of this problem was investigated in [16–18]. The relevant scheduling problems with quadratic cost function have also been studied in [19, 20]. For the problems with more than two types of penalties, Lee et al. [21] developed a dynamic programming algorithm to solve two instances of the problem which includes a combination of three types of penalties, namely, earliness, tardiness, and tardy jobs. Shabtay [22] considered a case with the objective function \[ \sum_{i=1}^{n} (f(d_i) + g(E_i) + h(T_i)) \], where \( f(\cdot) \), \( g(\cdot) \), and \( h(\cdot) \) are nondecreasing functions. Koulamas [23] presented an algorithm for the \( \{d_i = d\sum_{i=1}^{n} (a d + \beta T_i + \gamma E_i + \delta V_i + \theta U_i)\} \) problem. Baker and Scudder [24] presented an excellent survey for the initial research situations on both linear E-T and quadratic E-T scheduling problems, whilst a brilliant review of scheduling problems with multiple types of penalties was also provided in [25]. In [26, 27], the concept of batch in JIT scheduling problems with different objectives was investigated by several authors.

Although there are most of JIT problems in which processing times and due dates are certain, jobs usually have random processing times and due dates in many practical situations. Surprisingly, there is little literature studied on scheduling problems in stochastic environments. Sorosh and Fredendall [28] analyzed the single machine scheduling problem with normally distributed processing times and deterministic due dates to minimize the total expected earliness and tardiness penalties. Baker [29] studied the same case and obtained optimal solutions by designing a branch and bound algorithm. However, this problem was also considered in [30] when both processing times and due dates follow exponential distributions, and they derived the optimal V-shaped schedule by giving a dynamic programming algorithm. Liu and Liu [31] dealt with this type of problem in which release times and processing times are random variables. Cai and Zhou [32] investigated a problem with the three types of penalties, namely, earliness, tardiness, and flow time under normally distributed processing times and identically distributed due dates. Soroush [33] firstly explored the problem whose goal is to minimize the total expected weighted number of early and tardy jobs, where processing times are arbitrarily distributed, due dates are certain and jobs are penalized by fixed earliness weights and tardiness weights. The majority of the corresponding problems with E-T penalties have also been studied in [34–36] under distinct constraint conditions and assumptions. The stochastic version of problems with a relevant quadratic cost function has also been studied by several authors. Mittenthal and Raghavachari [37] analyzed a problem with quadratic earliness and tardiness penalties and stochastic machine breakdowns, whilst processing times are deterministic and due dates are common with certainty, and their objective is to minimize the expected value of the weighted sum of symmetric quadratic earliness and tardiness penalties of all jobs. Cai and Zhou [38] considered a similar case with uncertain uptimes and downtimes, but where both processing times and due dates are exponentially distributed. The problem of stochastically minimizing maximum lateness was analyzed in [39], where processing times and due dates follow exponential distribution. In [40], Soroush and Alqallaf investigated the stochastic problem of finding an optimal sequence that minimizes the total expected costs with weight quadratic tardiness penalties on a single machine, where idle time is not allowed, whilst the extending problem with initial idle time was examined in [41].

In this paper, we, under stochastic scenario, address a static single machine JIT scheduling problem with the objective of minimizing the expected total penalties for quadratic earliness, quadratic tardiness, and early and tardy jobs. In this scheduling problem, it is assumed that processing times follow geometric distributions with distinct parameters and due dates follow geometric distributions with a common parameter. Geometric distribution is a commonly used discrete distribution, where there is only one parameter which represents the probability of success of the event, and the value range of geometric random variable is all positive integers. It is also one of the simplest forms in processing time distributions. Moreover, the jobs are penalized by variable weights depending on quadratic earliness/tardiness and fixed earliness/tardiness weights. These weights are distinct and job-dependent. We show that the optimal solution of this problem has V-shaped characteristic with respect to the ratio of mean processing time to unit tardiness penalty, that is, the schedule will first arrange jobs in nonincreasing order of the ratio of mean processing time to unit tardiness penalty and then arrange jobs in nondecreasing order of the ratio of mean processing time to unit tardiness penalty. To the best of the author’s knowledge, no other research, under geometrically distributed processing times and due dates, has studied this objective function which simultaneously incorporated the four types of penalty.

This paper is structured as follows. Section 2 defines and formulates a static single machine stochastic JIT scheduling problem. In Section 3, we obtain the V-shaped property of the optimal schedule for this problem and show a special case and two theorems related to this problem under specific situations where the optimal solutions exist. The designed dynamic programming is presented to obtain an optimal V-shaped schedule in Section 4. Section 5 is the conclusions.

2. Problem Definition and Formulation

Consider stochastic JIT scheduling problem that a set \( J = \{1, 2, \ldots, n\} \) of \( n \) jobs are to be scheduled on a single machine. Assume that all jobs prepare for processing at time zero, and job preemption is not allowed that, as soon as a job starts to process on a single machine, it can not be disrupted.
until the process is finished. In addition, it is assumed that the machine which is always available can handle at most one job at a time, no machine breakdown occurs, and the machine inserted idle time are not allowed. In this problem, the processing time $P_i$ of each job $i$ is assumed to be independent random variable which follows geometric distribution with parameter $(1/\theta)$. Each job $i$ has a due date $D_i$ which has geometric distribution with common parameter $(1/\delta)$, and $D_i$ is independent of $P_i$.

The objective is to determine a schedule $\pi$ that minimizes the expected total penalties for quadratic earliness, quadratic tardiness, and early and tardy jobs which can be formulated as follows:

$$
ETP(\pi) = E\left[\sum_{i=1}^{n} (\alpha_i E_i^2 + \beta_i T_i + \tau_i V_i + \phi_i U_i)\right],
$$

where

- $\pi$ determines the order of processing the $n$ jobs is a sequence.
- $C_i(\pi)$ denotes the completion time of job $i$ under $\pi$.
- $D_i$ denotes the due date of job $i$.

$$
ETP(\pi) = \sum_{i=1}^{n} (\tau_i - \phi_i) Pr(D_i > C_i) + \sum_{i=1}^{n} (\alpha_i - \beta_i) E\left[(D_i - C_i)^2 I_{[D_i > C_i]}\right] + \sum_{i=1}^{n} \beta_i E\left[(C_i - D_i)^2\right] + \sum_{i=1}^{n} \phi_i
$$

where $I_A$ is an indicative function, which takes value 1 when event $A$ occurs; otherwise, it takes 0, and $ETP_i(\pi)$, $i = 1, 2, 3$, are defined by

$$
ETP_1(\pi) = \sum_{i=1}^{n} (\tau_i - \phi_i) Pr(D_i > C_i),
$$

$$
ETP_2(\pi) = \sum_{i=1}^{n} (\alpha_i - \beta_i) E\left[(D_i - C_i)^2 I_{[D_i > C_i]}\right],
$$

$$
ETP_3(\pi) = \sum_{i=1}^{n} \beta_i E\left[(C_i - D_i)^2\right].
$$

In order to tackle this scheduling problem, we first present a lemma below.

**Lemma 1.** If the processing times $\{P_i, i = 1, 2, \ldots, n\}$ are stochastically independent and geometrically distributed random variables with the mean $\{\theta_i, i = 1, 2, \ldots, n\}$, the due dates follow geometric distributions with a common mean $\delta$, independent of $\{P_i\}$. Then, given an arbitrary schedule $\pi = \ldots, i, j, \ldots$, let $\pi' = \ldots, j, i, \ldots$ denote the schedule that interchanges order of job $i$ and job $j$ in $\pi$. Hence,

$$
ETP(\pi) - ETP(\pi') = \frac{y_i y_j}{(\delta - 1)} \prod_{h \in Z^*} y_h,
$$

$$
ETP_1(\pi) - ETP_1(\pi') = (\pi E_i^2 - \phi_j^2) \frac{y_i y_j}{(\delta - 1)} \prod_{h \in Z^*} y_h,
$$

$$
ETP_2(\pi) - ETP_2(\pi') = (2\pi^2 - \delta)(\beta_j^2 - \phi_j^2) \frac{y_i y_j}{(\delta - 1)} \prod_{h \in Z^*} y_h,
$$

$$
ETP_3(\pi) - ETP_3(\pi') = (\beta_j^2 - \phi_j^2) \left(2 \sum_{h \in Z^*} \theta_j + 2\delta - 2\delta - 1\right).
$$
Proof. Due to the geometrically distributed of \{P_i\} and \{D_i\}, we have \( EP_i = \theta_i \), \( \text{Var} P_i = \theta_i^2 = \theta_i^2 - \theta_i \), \( ED_j = \delta_i \) and \( ED_j^2 = 2\delta^2 - \delta \). Therefore, we have the expected completion time of job \( i \) under \( \pi \):

\[
EC_i = \sum_{h \in Z_i} EP_h = \sum_{h \in Z_i} \theta_h,
\]

(9)

where \( Z_i = Z_i(\pi) = \{ \ldots, i \} \) is the set of jobs which is to be processed before job \( i + 1 \) in \( \pi \). Since \( \{ D_i \} \) and \( \{ P_i \} \) are geometrically distributed, which are stochastically independent, we have

\[
Pr(D_i > P_i) = E(Pr(D_i > P_i|P_i = p_i))
\]

\[
= E\left( \sum_{n=1}^{+\infty} \frac{1}{\delta} \left( 1 - \frac{1}{\delta} \right)^{n-1} \right) = E\left( \frac{1}{\delta} \right)^{P_i}
\]

\[
= \sum_{n=1}^{+\infty} \left( 1 - \frac{1}{\delta} \right)^{\frac{n-1}{\delta}} = \frac{\delta - 1}{\delta + \delta - 1} = \gamma_i,
\]

(10)

and

\[
Pr(D_i > C_i) = E \left( \frac{1}{\delta} \right)^{C_i} = E \left( \frac{1}{\delta} \right)^{\sum_{h \in Z_i} P_h}
\]

\[
= \prod_{h \in Z_i} E \left( \frac{1}{\delta} \right)^{y_h},
\]

(11)

where \( y_h = ((\delta - 1)/(\theta_i + \delta - 1)) \), which implies

\[
1 - y_i = \frac{\theta_i}{\theta_i + \delta - 1} = \frac{\theta_i y_i}{\delta - 1}.
\]

(12)

Subsequently, by simple calculation, we have

\[
E(D_i - C_i)^2 I_{\{D_i > C_i\}} = E \left( \left( (D_i - C_i)^2 I_{\{D_i > C_i\}} \right| C_i = c_i \right)
\]

\[
= E \sum_{n=c_i+1}^{+\infty} \left( n - c_i \right) \left( 1 - \frac{1}{\delta} \right)^{n-1} = E \sum_{x=1}^{+\infty} x \left( 1 - \frac{1}{\delta} \right)^{x-1}
\]

\[
= \frac{1}{\delta} \sum_{x=1}^{+\infty} x \left( 1 - \frac{1}{\delta} \right)^{x-1} E \left( \frac{1}{\delta} \right)^y
\]

\[
= ED^2 \prod_{h \in Z_i} y_h = (2\delta^2 - \delta) \prod_{h \in Z_i} y_h,
\]

(13)

and then, by (11) and (13), we can define

\[
M_1(\pi) = \sum_{i=1}^{n} (\tau_i - \varphi_i) \prod_{h \in Z_i} y_h,
\]

(14a)

and

\[
M_2(\pi) = (2\delta^2 - \delta) \sum_{i=1}^{n} (\alpha_i - \beta_i) \prod_{h \in Z_i} y_h.
\]

(14b)

Hence, according to (14a) and (14b), the objective in (3) and (4) can, respectively, be rewritten by

\[
\text{ETP}_1(\pi) = M_1(\pi),
\]

(15)

and

\[
\text{ETP}_2(\pi) = M_2(\pi).
\]

(16)

Following expectation and variance of \{P_i\}, we have

\[
EC^2_i = E \left( \sum_{h \in Z_i} P_h^2 + \sum_{h \in Z_i, k \neq l} P_h P_l \right) = \sum_{h \in Z_i} EP_h^2 + \sum_{h \in Z_i, h \neq l} EP_h EP_l
\]

\[
= \sum_{h \in Z_i} \sigma_h^2 + \left( \sum_{h \in Z_i} \theta_h \right)^2.
\]

(17)
and by (9), (17), and \( \{ P_i \} \) being independent of \( \{ D_i \} \), the objective in (5) can be further written as

\[
\text{ETP}_3(\pi) = \sum_{i=1}^{n} \beta_i \left( \text{EC}_i^2 - 2\text{ED}_i^2 \right)
\]

\[
= \sum_{i=1}^{n} \beta_i \sum_{h \in Z_i} \sigma_h^2 + \sum_{i=1}^{n} \beta_i \left( \sum_{h \in Z_i} \theta_h \right)^2 - 2\delta \sum_{i=1}^{n} \beta_i \sum_{h \in Z_i} \theta_h + (2\delta^2 - \delta) \sum_{i=1}^{n} \beta_i
\]

\[
= M_3(\pi) + M_4(\pi) - 2\delta M_5(\pi) + (2\delta^2 - \delta) \sum_{i=1}^{n} \beta_i,
\]

where \( M_i(\pi), i = 3, 4, 5, \) are similarly defined by

\[
M_3(\pi) = \sum_{i=1}^{n} \beta_i \sum_{h \in Z_i} \sigma_h^2,
\]

\[
M_4(\pi) = \sum_{i=1}^{n} \beta_i \left( \sum_{h \in Z_i} \theta_h \right)^2,
\]

\[
M_5(\pi) = \sum_{i=1}^{n} \beta_i \sum_{h \in Z_i} \theta_h.
\]

Thus, due to (15), (16), and (18) and (2) can be rewritten by

\[
\text{ETP}(\pi) = \sum_{i=1}^{n} \left( \tau_i - \varphi_i \right) \prod_{h \in Z_i} y_h + 2\delta^2 \sum_{i=1}^{n} \left( \alpha_i - \beta_i \right) \prod_{h \in Z_i} y_h + \sum_{i=1}^{n} \beta_i \sum_{h \in Z_i} \theta_h^2
\]

\[
+ \sum_{i=1}^{n} \beta_i \left( \sum_{h \in Z_i} \theta_h \right)^2 - (2\delta + 1) \sum_{i=1}^{n} \beta_i \sum_{h \in Z_i} \theta_h + (2\delta^2 - \delta) \sum_{i=1}^{n} \beta_i + \sum_{i=1}^{n} \varphi_i.
\]

Let \( Z^* = Z_i(\pi) - \{ i \} = Z_j(\pi') - \{ j \} \) denote the set of jobs scheduled before job \( i \) in \( \pi \) (or before job \( j \) in \( \pi' \)). Therefore, by (12) and (14a), under \( \pi \) and \( \pi' \), we have

\[
M_1(\pi) - M_1(\pi') = (\tau_i - \varphi_i) y_i \prod_{h \in Z^*} y_h + (\tau_j - \varphi_j) y_j \prod_{h \in Z^*} y_h
\]

\[
- (\tau_j - \varphi_j) y_j \prod_{h \in Z^*} y_h - (\tau_i - \varphi_i) y_i \prod_{h \in Z^*} y_h
\]

\[
= ((\tau_i - \varphi_i) y_i (1 - y_j) - (\tau_j - \varphi_j) y_j (1 - y_i)) \prod_{h \in Z^*} y_h
\]

\[
= \left( (\tau_i - \varphi_i) y_i \frac{\theta_i y_j}{\delta - 1} - (\tau_j - \varphi_j) y_j \frac{\theta_j y_i}{\delta - 1} \right) \prod_{h \in Z^*} y_h
\]

\[
= (\varphi_i \theta_i - \varphi_j \theta_j - (\tau_i \theta_i - \tau_j \theta_j)) \frac{y_i y_j}{\delta - 1} \prod_{h \in Z^*} y_h.
\]
and according to (12), (14b), and similar process with (21),

\[
M_2(\pi) - M_2(\pi') = (2\delta - \delta) \left[ (a_i - \beta_i) y_i \prod_{h \in Z^*} y_h + (a_j - \beta_j) y_j \prod_{h \in Z^*} y_h \right] - (a_j - \beta_j) y_j \prod_{h \in Z^*} y_h + (a_i - \beta_i) y_i \prod_{h \in Z^*} y_h
\]

\[
= (2\delta - \delta) \left( (\beta_j \theta_i - \beta_j \theta_j) - (a_j \theta_j - a_i \theta_i) \right) y_j y_i \frac{1}{\delta - \delta} \prod_{h \in Z^*} y_h. \tag{22}
\]

Substituting (21) into (15), (6) can be obtained, and substituting (22) into (16), (7) can be obtained.

Similarly, by (19a) and (19b),

\[
M_3(\pi) - M_3(\pi') = \beta_1 \left( \sum_{h \in Z^*} \theta_h^i + \theta_i \right) + \beta_1 \left( \sum_{h \in Z^*} \theta_h^j + \theta_j \right) - \beta_j \left( \sum_{h \in Z^*} \theta_h^j + \theta_j \right) - \beta_i \left( \sum_{h \in Z^*} \theta_h^i + \theta_i \right)
\]

\[
= \beta_1 \theta_i^2 - \beta_1 \theta_j^2 = \beta_1 \theta_i^2 - \beta_1 \theta_j^2 + \beta_1 \theta_j - \beta_1 \theta_i. \tag{23}
\]

\[
M_4(\pi) - M_4(\pi') = \beta_1 \left( \sum_{h \in Z^*} \theta_h + \theta_i \right)^2 + \beta_1 \left( \sum_{h \in Z^*} \theta_h + \theta_j \right)^2 - \beta_j \left( \sum_{h \in Z^*} \theta_h + \theta_j \right)^2 - \beta_i \left( \sum_{h \in Z^*} \theta_h + \theta_i \right)^2
\]

\[
= \beta_1 \theta_i^2 - \beta_1 \theta_j^2 \left( 2 \sum_{h \in Z^*} \theta_h + 2 \theta_i + \theta_j \right) - \beta_1 \theta_j^2 \left( 2 \sum_{h \in Z^*} \theta_h + 2 \theta_j + \theta_i \right) + \beta_1 \theta_i^2 - \beta_1 \theta_j^2, \tag{24}
\]

and

\[
M_5(\pi) - M_5(\pi') = \beta_1 \left( \sum_{h \in Z^*} \theta_h + \theta_i \right) + \beta_1 \left( \sum_{h \in Z^*} \theta_h + \theta_j \right) - \beta_j \left( \sum_{h \in Z^*} \theta_h + \theta_j \right) - \beta_i \left( \sum_{h \in Z^*} \theta_h + \theta_i \right)
\]

\[
= \beta_1 \theta_i - \beta_1 \theta_j. \tag{25}
\]

Substituting (23), (24), and (25) into (18), (8) can be obtained.

According to Lemma 1, when both the processing times \(P_i\) and the due dates \(D_i\) are geometrically distributed, we
have the main result on the expected penalties of quadratic earliness, quadratic tardiness, and early and tardy jobs below.

**Theorem 1.** Assume that the processing times $P_1, \ldots, P_n$ are stochastically independent and geometrically distributed random variables with means $\theta_1, \ldots, \theta_n$, individually, and the due dates $D_1, \ldots, D_n$ follow geometric distributions with a common mean $\delta$, independent of $\{P_i\}$. Define

$$R_{ij} = \left(\frac{\varphi_j}{\theta_j} - \frac{\varphi_i}{\theta_i}\right)^{-1} \left(\frac{\tau_j - \tau_i}{\theta_j - \theta_i}\right),$$

(26a)

$$S_{ij} = \left(\frac{\beta_j}{\theta_j} - \frac{\beta_i}{\theta_i}\right)^{-1} \left(\frac{\alpha_j - \alpha_i}{\theta_j - \theta_i}\right),$$

(26b)

$$T_{ij} = \left(\frac{\varphi_j}{\theta_j} - \frac{\varphi_i}{\theta_i}\right)^{-1} \left(\frac{\beta_j - \beta_i}{\theta_j - \theta_i}\right),$$

where $R_{ij}$, $S_{ij}$, and $T_{ij}$ are defined unless $\varphi_i/\theta_i = \varphi_j/\theta_j$ or $\beta_j/\theta_j = \beta_i/\theta_i$. If $\{R_{ij}\}$, $\{S_{ij}\}$, and $\{T_{ij}\}$ satisfy the following condition,

$$[T_{ij}(1 - R_{ij}) - y_k T_{jk}(1 - R_{jk}) + (2\theta^2 - \delta)(1 - S_{ij}) - y_k (1 - S_{jk})] < 2\theta_k(\delta - 1)$$

for all different, $i, j, k \in \{1, 2, \ldots, n\}$, and the jobs are firstly arranged such that in nonincreasing order of $[(\theta_i/\beta_i), i = 1, 2, \ldots, j]$, then they are arranged such that, in nondecreasing order of $[(\theta_i/\beta_i), i = j, j + 1, \ldots, n]$, for $\exists j \in \{1, 2, \ldots, n\}$, the schedule minimizes $ETP(\pi)$. In other words, the optimal solutions given by the schedule are $V$-shaped with respect to the order of $[\theta_i/\beta_i]$.

**Proof.** By combining (6), (7), and (8) with (26a) and (26b), we obtain

$$ETP(\pi) - ETP(\pi') = \sum_{i=1}^{n} \left(ETP_i(\pi) - ETP_i(\pi')\right)$$

$$= \theta_1 \theta_2 \left[T_{ij}\left(\frac{\beta_j}{\theta_j} - \frac{\beta_i}{\theta_i}\right) - R_{ij}T_{ij}\left(\frac{\beta_j}{\theta_j} - \frac{\beta_i}{\theta_i}\right)\right] y_i y_j \prod_{h \in Z^*} y_h$$

$$+ \theta_1 \theta_2 \left[S_{ij}\left(\frac{\beta_j}{\theta_j} - \frac{\beta_i}{\theta_i}\right) - S_{ij}\left(\frac{\beta_j}{\theta_j} - \frac{\beta_i}{\theta_i}\right)\right] \frac{2\theta^2 - \delta}{\delta - 1} y_i y_j \prod_{h \in Z^*} y_h$$

$$+ \theta_1 \theta_2 \left[T_{ij}\left(\frac{\beta_j}{\theta_j} - \frac{\beta_i}{\theta_i}\right)\right] \left[2 \sum_{h \in Z^*} \theta_h + 2\theta_i + 2\theta_j - 2\delta - 1\right].$$

Then, by extracting common factor,

$$ETP(\pi) - ETP(\pi') = \theta_1 \theta_2 \left(\frac{\beta_j}{\theta_j} - \frac{\beta_i}{\theta_i}\right) \times \left[\sum_{h \in Z^*} 2\theta_h + 2\theta_i + 2\theta_j + T_{ij}(1 - R_{ij}) \frac{y_i y_j}{\delta - 1} \prod_{h \in Z^*} y_h$$

$$+ (2\theta^2 - \delta)(1 - S_{ij}) \frac{y_i y_j}{\delta - 1} \prod_{h \in Z^*} y_h - 2\delta - 1\right].$$

(29)
Now, given a sequence \( \pi = (\ldots, i, j, k, \ldots) \), then we denote the sequence \( \pi' = (\ldots, i, k, j, \ldots) \) which interchanges the order of job \( i \) and job \( j \) in \( \pi \) and the sequence \( \pi'' = (\ldots, i, k, j, \ldots) \) which interchanges the order of job \( j \) and job \( k \) in \( \pi \). Define

\[
G_j = 2 \sum_{h \in \mathbb{Z}^*} \theta_h + 2\theta_{j-1} + 2\theta_j + T_{j-1,i}(1 - R_{j-1,i}) \frac{y_{j-1,y_j}}{\delta - 1} \prod_{h \in \mathbb{Z}^*} y_h
\]

\[
+ (1 - S_{j-1,i}) \frac{2\delta^2 - \delta}{\delta - 1} y_{j-1,y_j} \prod_{h \in \mathbb{Z}^*} y_h,
\]

where \( \theta_j \geq \frac{\beta_j}{\beta_j} = \frac{\beta_k}{\beta_k} = \frac{\beta_j}{\beta_j} \geq \frac{\beta_j}{\beta_j} \geq \frac{\beta_j}{\beta_j} \). Then, (31) implies

\[
\text{ETP}(\pi) - \text{ETP}(\pi') = \theta_i \theta_j (\beta_j - \beta_j)(G_j + H) \leq 0.
\]

If \( G_j + H < 0 \) and according to the assumption of Theorem 1, the jobs are firstly handled such that

\[
G_k - G_j = 2\theta_k + y_k T_{j,k}(1 - R_{j,k}) \frac{y_{j,y_j}}{\delta - 1} \prod_{h \in \mathbb{Z}^*} y_h + y_k (2\delta^2 - \delta)(1 - S_{j,k}) \frac{y_{j,y_j}}{\delta - 1} \prod_{h \in \mathbb{Z}^*} y_h
\]

\[
- T_{ij}(1 - R_{i,j}) \frac{y_{i,y_j}}{\delta - 1} \prod_{h \in \mathbb{Z}^*} y_h - (2\delta^2 - \delta)(1 - S_{i,j}) \frac{y_{i,y_j}}{\delta - 1} \prod_{h \in \mathbb{Z}^*} y_h
\]

\[
= 2\theta_k \left(1 - \frac{q}{2\theta_k (\delta - 1)} y_j \prod_{h \in \mathbb{Z}^*} y_h \right) > 0,
\]

where \( q = T_{ij}(1 - R_{i,j}) - y_k T_{j,k}(1 - R_{j,k}) + (2\delta^2 - \delta)(1 - S_{j,k}) - y_k (1 - S_{j,k}) \). Hence, we obtain \( G_k - H > G_j - H \geq 0 \). Due to the assumption of Theorem 1, the jobs are secondly handled such that

\[
\frac{\theta_{j+1}}{\beta_{j+1}} \geq \frac{\theta_j}{\beta_j} = \frac{\beta_k}{\beta_k} = \frac{\beta_j}{\beta_j} \geq \frac{\beta_j}{\beta_j} \geq \frac{\beta_j}{\beta_j} \]

Then, (32) implies

\[
\text{ETP}(\pi) - \text{ETP}(\pi'') = \theta_j \theta_k (\beta_k - \beta_k)(G_k + H) \leq 0.
\]

Thus, the result of Theorem 1 is proved that an optimal sequence to minimize ETP(\( \pi \)) is \( V \)-shaped with respect to \( \{\theta_i/\beta_i\} \). For distinct \( \alpha_i, \beta_i, \tau_i \), and \( \phi_i \), a large quantity of cases are covered by Theorem 1. When the four weights are some constants, we discuss a special case below.

A special case: assume that \( R_{ij} = R, S_{ij} = S \), and \( T_{ij} = T \) are some constants, then condition (27) is rewritten by

\[
T (1 - R)(1 - y_k) + (2\delta^2 - \delta)(1 - S)(1 - y_k) < 2\theta_k (\delta - 1).
\]

If \( R > 1, S > 1, \) and \( T > 0 \), the above condition evidently holds. Therefore, \( \{\theta_i/\alpha_i\}, \{\theta_i/\beta_i\}, \{\theta_i/\tau_i\}, \) and \( \{\theta_i/\phi_i\} \) have the same order. Hence, by Theorem 1, the optimal schedule is \( V \)-shaped with respect to \( \{\theta_i/\alpha_i\}, \{\theta_i/\beta_i\}, \{\theta_i/\tau_i\}, \) or \( \{\theta_i/\phi_i\} \).

In addition, we, under different assumptions, show two theorems related to this ETP(\( \pi \)) problem where the optimal solutions exist.

**Theorem 2.** Assume that \( \min_{i < j \leq n} \theta_i > \delta \), and \( R_{ij} = R \), \( S_{ij} = S \), and \( T_{ij} = T \) are some constants.

(1) If \( R < 1, 0 < S < 1, \) and \( T > 0 \), that is, \( \{\theta_i/\alpha_i\}, \{\theta_i/\beta_i\}, \{\theta_i/\tau_i\}, \) and \( \{\theta_i/\phi_i\} \) have same orders, then
Theorem 3. Assume that \( \sum_{i=1}^{n} \theta_i < \delta \), and \( R_{ij} \equiv R, S_{ij} \equiv S \), and \( T_{ij} \equiv T \) are some constants.

(i) If \( R > 0, S > 0 \), and \( T > 0 \), that is, \( \{\theta_i/\alpha_i\} \), \( \{\theta_i/\beta_i\} \), \( \{\theta_i/\tau_i\} \), and \( \{\theta_i/\varphi_i\} \) have the same orders, then \( \text{ETP}(\pi) \) is minimized by the schedule in nondecreasing order of \( \{\theta_i/\beta_i\} \) or \( \{\theta_i/\varphi_i\} \), or, equivalently, in nonincreasing order of \( \{\theta_i/\alpha_i\} \) or \( \{\theta_i/\tau_i\} \).

(ii) If \( R > 0, S > 0, \) and \( T > 0 \), that is, \( \{\theta_i/\alpha_i\} \), \( \{\theta_i/\beta_i\} \), \( \{\theta_i/\tau_i\} \), and \( \{\theta_i/\varphi_i\} \) have opposite orders, then \( \text{ETP}(\pi) \) is minimized by the schedule in nondecreasing order of \( \{\theta_i/\beta_i\} \) or \( \{\theta_i/\varphi_i\} \), or, equivalently, in nonincreasing order of \( \{\theta_i/\alpha_i\} \), \( \{\theta_i/\tau_i\} \), or \( \{\theta_i/\varphi_i\} \).

Proof. Let \( \{\theta_i/\alpha_i\} \leq \{\theta_i/\beta_i\} \leq \{\theta_i/\tau_i\} \leq \{\theta_i/\varphi_i\} \); according to the assumption that \( \min_{i \in I} \theta_i > \delta \) and the conditions of Part (i), we have \( T_i \geq R_i > 0 \) and \( 1 - S_i > 0 \). It follows from (29) that \( \text{ETP}(\pi) - \text{ETP}(\pi) \leq 0 \). This proves that \( \text{ETP}(\pi) - \text{ETP}(\pi) \leq 0 \) if and only if \( \{\theta_i/\alpha_i\} \leq \{\theta_i/\beta_i\} \leq \{\theta_i/\tau_i\} \leq \{\theta_i/\varphi_i\} \).

According to the similar proof procedure of Part (i), we can prove Part (ii), Part (iii), Part (iv), Part (v), and Part (vi).

4. Dynamic Programming Algorithm

In this section, in order to obtain the optimal solution of this stochastic problem \( \text{ETP}(\pi) \) among all \( V \)-shaped schedules, we propose dynamic programming algorithm based on Theorem 1 for the objective function (20). In general, it is necessary for the jobs to be numbered in nondecreasing order of \( \{\theta_i/\beta_i\} \), that is, \( \{\theta_i/\beta_i\} \leq \{\theta_i/\beta_i\} \leq \cdots \leq \{\theta_i/\beta_i\} \). Then, think about a set of the jobs \( A_i = \{1, 2, \ldots, n\} \) for \( i \in [1, 2, \ldots, n] \). Hence, job can be scheduled as the first or the last in this schedule for all the jobs in \( A_i \), if a schedule has a \( V \)-shaped characteristic. Suppose that \( \pi^* \) denotes the optimal \( V \)-shaped schedule for the objective function (20) and \( A_i \) represents a set of the jobs is scheduled before the jobs in \( A_i \) under \( \pi^* \). Let \( \Psi_i = \prod_{h \in A_i} \eta_i \), \( Y_i = \sum_{h \in A_i} \eta_i \), and \( \Omega_i = \sum_{h \in A_i} \eta_i \). Then, provided \( \Psi_i \), \( Y_i \), and \( \Omega_i = f_j(\Psi_i, Y_i, \Omega_i) \) is defined as the contribution of all the jobs in \( A_i \) to the objective function (20). Afterwards, it is obvious that the contribution of the jobs if job \( i \) is the first and last job scheduled among all jobs in \( A_i \) is, respectively,

\[
 f_i^{\pi}(\Psi_i, Y_i, \Omega_i) = f_{i-1}(\Psi'_i, Y'_i, \Omega'_i + \theta_i, \Omega'_i + \theta_i, \Omega'_i + \theta_i) + \left( (\tau_i - \varphi_i) + (2 \delta^2 - \delta) (\alpha_i - \beta_i) \right) \Psi'_i Y_i + \beta_i (\Omega'_i + \theta_i) + (Y_i + \theta_i) - (2 \delta + 1) \beta_i (Y_i + \theta_i)
\]

and

\[
 f_i^{\phi}(\Psi_i, Y_i, \Omega_i) = f_{i-1}(\Psi'_i, Y'_i, \Omega'_i) + \left( (\tau_i - \varphi_i) + (2 \delta^2 - \delta) (\alpha_i - \beta_i) \right) \Psi'_i Y_i + \beta_i (\Omega'_i + \Omega_i) + (Y_i + Y_i) - (2 \delta + 1) \beta_i (Y_i + Y_i)
\]

where \( \Psi_i = \prod_{h \in A_i} \eta_i \), \( Y_i = \sum_{h \in A_i} \eta_i \), and \( \Omega_i = \sum_{h \in A_i} \eta_i \).

On the basis of the optimal principle of dynamic programming, and \( f_i^{\pi}(\Psi_i, Y_i, \Omega_i) \) and \( f_i^{\phi}(\Psi_i, Y_i, \Omega_i) \) are expressed in (39a) and (39b), respectively, hence the jobs are handled by the optimal \( V \)-shaped schedule such that

\[
 f_i(\Psi_i, Y_i, \Omega_i) = \min\{ f_i^{\pi}(\Psi_i, Y_i, \Omega_i), f_i^{\phi}(\Psi_i, Y_i, \Omega_i) \} + (2 \delta^2 - \delta) \sum_{h \in A_i} \beta_i + \sum_{h \in A_i} \varphi_i
\]
Thus, we can summarize the dynamic programming algorithm designed to achieve the optimal V-shaped schedule for this stochastic JIT problem.

Since this is a dynamic programming algorithm, we can obtain \( \pi^* \) according to its standard procedure, and the detailed process of the backward tracking is omitted. The algorithm is used to calculate all \( f_i(\Psi^i, Y^i, \Omega^i) \), at most \( \mathcal{O}(\Psi Y \Omega) \) steps, for each \( i \). Thus, Algorithm 1 can derive the optimal schedule in \( \mathcal{O}(n \Psi Y \Omega) \) pseudopolynomial time for the stochastic single machine JIT problem.

Step 1: for \( i = 1, 2, \ldots, n \), we can calculate \( f_i(\Psi^i, Y^i, \Omega^i) \) by (39a), (39b), and (40) for all possible values \( \Psi^i, Y^i, \) and \( \Omega^i \).

Step 2: define \( F^*_n = \min_{\Psi^i Y^i \Omega^i} (f_i(\Psi^i, Y^i, \Omega^i)) \)

Step 3: structure the optimal V-shaped schedule \( \pi^* \) that obtains \( F^*_n \) due to the backward tracking process

Algorithm 1: Dynamic programming.

Data Availability
No data were used to support the findings of the study.

Conflicts of Interest
The author declares that there are no conflicts of interest reported in this paper.

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