Dynamic of the three dimensional viscous primitive equations of large-scale atmosphere

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Abstract
The main objective of this paper is to study the existence of a finite dimension global attractor for the three dimensional viscous primitive equations of large-scale atmosphere. Thanks to the shortage of the uniqueness of weak solutions, we prove the existence of a global attractor with finite fractal dimension for the three dimensional viscous primitive equations of large-scale atmosphere by using the method of ℓ-trajectories.

Keywords: Primitive equation, Global attractor, The method of ℓ-trajectories, Fractal dimension.

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1. Introduction
In this paper, we consider the long-time behavior of solutions for the following three dimensional viscous primitive equations of large-scale atmosphere (see [22, 23]):

\[
\begin{aligned}
\frac{\partial \mathbf{v}}{\partial t} + (\mathbf{v} \cdot \nabla) \mathbf{v} + w \frac{\partial \mathbf{v}}{\partial z} + f_0 \vec{k} \times \mathbf{v} + \nabla p + L_1 \mathbf{v} &= 0, \\
\frac{\partial p}{\partial z} &= T, \\
\nabla \cdot \mathbf{v} + \frac{\partial w}{\partial z} &= 0, \\
\frac{\partial T}{\partial t} + \mathbf{v} \cdot \nabla T + w \frac{\partial T}{\partial z} + L_2 T &= Q,
\end{aligned}
\]

in the domain
\[
\Omega = M \times (-h, 0) \subset \mathbb{R}^3,
\]

where \( M \subset \mathbb{R}^2 \) is a bounded domain with smooth boundary. Here \( \mathbf{v} = (v_1, v_2), \) \((v_1, v_2, w)\) is the velocity field, \( T \) is the temperature, \( p \) is the pressure, \( f_0 = 2\Omega_1 \sin v_0 \) is the Coriolis parameter, \( \vec{k} = (0, 0, 1) \) is vertical unit vector and \( Q \) is a heat source. The operators \( L_1 \) and \( L_2 \) are given by

\[
L_1 = -\frac{1}{Re_1} \Delta - \frac{1}{Re_2} \frac{\partial^2}{\partial z^2}, \quad L_2 = -\frac{1}{Rt_1} \Delta - \frac{1}{Rt_2} \frac{\partial^2}{\partial z^2},
\]

where \( Re_1, Re_2 \) are positive constants representing the horizontal and vertical Reynolds numbers, respectively, and \( Rt_1, Rt_2 \) are positive constants which stand for the horizontal and vertical heat diffusivity, respectively. For the sake

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of simplicity, let $\nabla = (\partial_x, \partial_y)$ be the horizontal gradient operator and let $\Delta = \partial_x^2 + \partial_y^2$ be the horizontal Laplacian. We denote the different parts of the boundary of $\bar{\Omega}$ by

$$\Gamma_a = \{(x, y, z) \in \bar{\Omega} : z = 0\},$$
$$\Gamma_b = \{(x, y, z) \in \bar{\Omega} : z = -h\},$$
$$\Gamma_l = \{(x, y, z) \in \bar{\Omega} : (x, y) \in \partial M, -h \leq z \leq 0\}.$$  

Equations (1.1) is equipped with the following boundary conditions, with non-slip and non-flux on the side walls and bottom (see [3])

$$\begin{aligned}
\frac{\partial \bar{v}}{\partial n}|_{\Gamma_a} &= 0, w|_{\Gamma_a} = 0, \left(\frac{1}{\alpha} \frac{\partial \bar{T}}{\partial n} + aT\right)|_{\Gamma_a} = 0, \\
\frac{\partial \bar{r}}{\partial n}|_{\Gamma_b} &= 0, w|_{\Gamma_b} = 0, \frac{\partial \bar{r}}{\partial n}|_{\Gamma_b} = 0, \\
v \cdot \bar{n}|_{\Gamma_l} &= 0, \frac{\partial \bar{T}}{\partial n}|_{\Gamma_l} = 0, \frac{\partial \bar{r}}{\partial n}|_{\Gamma_l} = 0.
\end{aligned}$$  

Equations (1.1) with the following initial datum

$$\begin{aligned}
v(x, y, z, 0) &= v_0(x, y, z), \\
T(x, y, z, 0) &= T_0(x, y, z).
\end{aligned}$$  

In the past several decades, the primitive equations of the atmosphere, the ocean and the coupled atmosphere-ocean have been extensively studied from the mathematical point of view (see [3, 8, 10, 11, 12, 16, 17, 22, 23, 26, 27] etc). By introducing $p$-coordinate system and using some technical treatments, Lions, Temam and Wang in [22] obtained a new formulation for the primitive equations of large-scale dry atmosphere which is a little similar with Navier-Stokes equations of incompressible fluid, and they proved the existence of weak solutions for the primitive equations of the atmosphere. In [23], Lions, Temam and Wang introduced the primitive equations of large-scale ocean and proved the existence of weak solutions and the well-posedness of local in time strong solutions for the primitive equations of large-scale ocean, and estimated the dimension of the universal attractor. Based on the works of Lions, Temam and Wang in [22, 23], many authors continued to consider the well-posedness of solutions for the primitive equations of large-scale ocean and atmosphere dynamics with any initial datum remain unresolved. Until 2007, Cao and Titi [3] decomposed the three dimensional primitive equations of large-scale ocean and atmosphere dynamics into two systems by using the idea of the decomposition of semigroup, one is similar with the two dimensional incompressible Navier-Stokes equations, the other is the reaction-convection-diffusion equations. As we known, the solutions of each system were fairly regular. Cao and Titi performed some a priori estimates about the solutions of each system by which they obtained some a priori estimates of strong solutions for the three dimensional primitive equations of large-scale ocean and atmosphere dynamics, which implies the well-posedness of strong solutions for the three dimensional primitive equations of large-scale ocean and atmosphere dynamics, they resolved the open question posed in [22, 23]. Meanwhile, the long-time behavior of solutions for the three dimensional primitive equations of large-scale ocean and atmosphere dynamics has been considered extensively (see [6, 7, 10, 11, 12, 13, 14, 15, 18, 19, 20, 21, 22, 27, 32]). In particular, in [11], Guo and Huang obtained a weakly compact global attractor $\mathcal{A}$ for the primitive equations of large-scale atmosphere which captures all the trajectories. The existence of a global attractor in $V$ for the primitive equations of large-scale atmosphere and ocean dynamics was proved by Ning Ju in [18] by using the Aubin-Lions compactness theorem under the assumption $Q \in L^2(\Omega)$. In [19, 20], the authors have proved the finite dimensional global attractor for the 3D viscous primitive equations by using the squeezing property.

To the best of our knowledge, the method of $t$-trajectories is based on an observation that the limit behavior of solutions to a dynamical system in an original phase space can be equivalently captured by the limit behavior of $t$-trajectories which are continuous parts of solution trajectories that are parametrized by time from an interval of the length $\ell$ with $\ell > 0$ and it can weaken the requirements on the regularity of the solution. In this paper, thanks to the shortage of the regularity of weak solutions for the three dimensional viscous primitive equations of large-scale atmosphere, we can not obtain the uniqueness of weak solutions such that we are not able to define the semigroup on $H$. Therefore, the existence of a global attractor in $H$ can not be obtained by the classical theory of dynamical systems. Fortunately, we know that any weak solutions of equations (1.1)-(1.3) will be unique for any $t > 0$. To overcome this
Therefore, equations (1.1) can be reformulated as follows which is the pressure of the atmosphere on \( z \). Define an unknown function on \( z \) and \( A \) as follows:

\[
\begin{align*}
A &= \text{the pressure of the atmosphere on } z = 0, \\
A &= \text{Define an unknown function on } z = 0, \text{ say } p_t : M \to \mathbb{R},
\end{align*}
\]

which is the pressure of the atmosphere on \( z = 0 \). Then

\[
p(x, y, z, t) = p_t(x, y, t) + \int_0^\infty T(x, y, r, t)dr.
\]

Therefore, equations (1.1) can be reformulated as follows

\[
\begin{align*}
&\frac{\partial v}{\partial t} + (v \cdot \nabla)v - (\int_h \nabla \cdot v(x, y, s, t)ds)\frac{\partial h}{\partial t} + \nabla p_t(x, y, t) + \int_0^t \nabla T(x, y, s, t)ds + L_1v = 0, \\
&\frac{\partial T}{\partial t} + v \cdot \nabla T - (\int_h \nabla \cdot v(x, y, s, t)ds)\frac{\partial T}{\partial t} + L_2T = Q
\end{align*}
\]

subject to the following boundary conditions

\[
\begin{align*}
&\frac{\partial v}{\partial n}|_{\Gamma_0} = 0, \frac{\partial v}{\partial n}|_{\Gamma_1} = 0, v \cdot \vec{n}|_{\Gamma_1} = 0, \frac{\partial v}{\partial n} \times \vec{n}|_{\Gamma_1} = 0, \\
&\frac{\partial T}{\partial n}|_{\Gamma_1} = 0, (\frac{1}{R_0} \frac{\partial T}{\partial n} + \alpha T)|_{\Gamma_1} = 0, \frac{\partial T}{\partial n} |_{\Gamma_1} = 0
\end{align*}
\]

and the initial datum

\[
\begin{align*}
&v(x, y, z, 0) = v_0(x, y, z), \\
&T(x, y, z, 0) = T_0(x, y, z).
\end{align*}
\]

2.2. Some function spaces

In this subsection, we first introduce the notations for some standard function spaces on \( \Omega \) as follows

\[
\begin{align*}
\mathcal{V}_1 = \left\{v \in (C^\infty(\tilde{\Omega}))^2 : \frac{\partial v}{\partial z}|_{\Gamma_0} = 0, \frac{\partial v}{\partial z}|_{\Gamma_1} = 0, v \cdot \vec{n}|_{\Gamma_1} = 0, \frac{\partial v}{\partial n} \times \vec{n}|_{\Gamma_1} = 0, \int_0^t \nabla \cdot v(x, y, z) dz = 0 \right\}, \\
\mathcal{V}_2 = \left\{T \in C^\infty(\tilde{\Omega}) : \frac{\partial T}{\partial z}|_{\Gamma_0} = 0, \frac{1}{R_0} \frac{\partial T}{\partial z} + \alpha T)|_{\Gamma_1} = 0, \frac{\partial T}{\partial n} |_{\Gamma_1} = 0 \right\}.
\end{align*}
\]
Denote the norm in $L^p(\Omega)(1 \leq p < \infty)$ by the notation $\| \cdot \|_p$ given by

$$\|f\|_p = \left( \int_\Omega |f|^p dxdydz \right)^{\frac{1}{p}}$$

for any $f \in L^p(\Omega)$, and let $H_1$ be the closure of $\mathcal{V}_1$ with respect to the $(L^2(\Omega))^2$-norm. Similarly, we let $V_1$, $V_2$ be the closure of $\mathcal{V}_1$, $\mathcal{V}_2$ with respect to the following norms

$$\|v\| = \left( \frac{1}{Re_1} \int_\Omega |\nabla v|^2 dxdydz + \frac{1}{Re_2} \int_\Omega |\frac{\partial v}{\partial z}|^2 dxdydz \right)^{\frac{1}{2}},$$

$$\|T\| = \left( \frac{1}{Rr} \int_\Omega |\nabla T|^2 dxdydz + \frac{1}{Rr} \int_\Omega |\frac{\partial T}{\partial z}|^2 dxdydz + \alpha \int_\Omega |T|^2 dxdy \right)^{\frac{1}{2}}$$

for any $v \in \mathcal{V}_1$ and $T \in \mathcal{V}_2$, respectively, let $V = V_1 \times V_2$ and $H = H_1 \times L^2(\Omega)$ with the norm defined by $\|(v, T)\|_2 = \left( \|v\|_1^2 + \|T\|_2^2 \right)^{\frac{1}{2}}$ for any $(v, T) \in H$, and denote by $V'$ the dual space of $V$.

Next, we recall some results used to prove the existence of a finite dimensional global attractor for problem (2.3)-(2.5).

**Lemma 2.1.** (3) There exists a positive constant $K_1$ such that

$$\frac{1}{K_1} \|T\|_1^2 \leq \|T\|_H^2 \leq K_1 \|T\|_2^2$$

for any $T \in V_2$. Moreover, we have

$$\|T\|_2^2 \leq K_2 \|T\|_1^2$$

for any $T \in V_2$, where

$$K_2 = \max\{\frac{2h}{\alpha}, 2Rr\epsilon^2\}.$$

**Lemma 2.2.** (3, 18, 22, 23, 24) Assume that $p_1 \in (1, \infty]$, $p_2 \in [1, \infty)$. Let $X$ be a Banach space and let $X_0$, $X_1$ be separable and reflexive Banach spaces such that $X_0 \subset X \subset X_1$. Then

$$Y = \{ u \in L^{p_1}(0, \tau; X_0) : u' \in L^{p_2}(0, \tau; X_1) \} \subset \subset L^{p_1}(0, \tau; X),$$

where $\tau$ is a fixed positive constant.

**Definition 2.1.** (23, 33) Let $(S(t))_{t \geq 0}$ be a semigroup on a Banach space $X$. A set $\mathcal{A} \subset X$ is said to be a global attractor if the following conditions hold:

(i) $\mathcal{A}$ is compact in $X$.

(ii) $\mathcal{A}$ is strictly invariant, i.e., $S(t)\mathcal{A} = \mathcal{A}$ for any $t \geq 0$.

(iii) For any bounded subset $B \subset X$ and for any neighborhood $\mathcal{O} = \mathcal{O}(\mathcal{A})$ of $\mathcal{A}$ in $X$, there exists a time $\tau_0 = \tau_0(B)$ such that $S(t)B \subset \mathcal{O}(\mathcal{A})$ for any $t \geq \tau_0$.

**Lemma 2.3.** (23) Let $X$ be a (subset of) Banach space and $(S(t), X)$ be a dynamical system. Assume that there exists a compact set $K \subset X$ which is uniformly absorbing and positively invariant with respect to $S(t)$. Let moreover $S(t)$ be continuous on $K$. Then $(S(t), X)$ has a global attractor.

**Definition 2.2.** (23, 33) Let $H$ be a separable real Hilbert space. For any non-empty compact subset $K \subset H$, the fractal dimension of $K$ is the number

$$d_f(K) = \limsup_{\epsilon \to 0} \frac{\log(N_\epsilon(K))}{\log(\frac{1}{\epsilon})}$$

where $N_\epsilon(K)$ denotes the minimum number of open balls in $H$ with radii $\epsilon > 0$ that are necessary to cover $K$. 

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Lemma 2.4. \((\text{[2.3]}))\) Let \(X, Y\) be norm spaces such that \(X \subset\subset Y\) and \(\mathcal{A} \subset Y\) be bounded. Assume that there exists a mapping \(L\) such that \(L\mathcal{A} = \mathcal{A}\) and \(L : Y \to X\) is Lipschitz continuous on \(\mathcal{A}\). Then \(d_L(\mathcal{A})\) is finite.

Lemma 2.5. \((\text{[2.3]}))\) Let \(X\) and \(Y\) be two metric spaces and \(f : X \to Y\) be \(\alpha\)-Hölder continuous on the subset \(A \subset X\). Then
\[
d_F(f(A), Y) \leq \frac{1}{\alpha}d_F(A, X).
\]
In particular, the fractal dimension does not increase under a Lipschitz continuous mapping.

3. The existence of a global attractor

We start with the following general existence of weak solutions which can be obtained by the standard Faedo-Galerkin methods (see \([3, 30]\)). Here we only state the result as follows.

Theorem 3.1. Assume that \(Q \in L^2(\Omega)\). Then for any \((v_0, T_0) \in H\), there exists at least one solution \((v(t), T(t)) \in C(\mathbb{R}^+; H_0) \cap L^2(\mathbb{R}^+; V)\) of problem \((2.3)-(2.5)\).

Lemma 3.1. \((\text{[3, 18]}))\) Assume that \(Q \in L^2(\Omega)\). Then for any \((v_0, T_0) \in V\), there exists a unique strong solution \((v(t), T(t)) \in C(\mathbb{R}^+; V)\) of problem \((2.3)-(2.5)\), which depends continuously on the initial data with respect to the topology of \(H\) and the topology of \(V\).

Corollary 3.1. Assume that \(Q \in L^2(\Omega)\) and \((v_{0m}, T_{0m}) \to (v_0, T_0)\) in \(H\), let \((v_{m}(t), T_{m}(t)) \to (v_0, T_0)\) in \(V\). For any \(S > 0\), if there exists a subsequence converging \((\ast)\) weakly in spaces \(\{(v, T) \in L^\infty(0, S; H) \cap L^2(0, S; V) : (v_1, T_1) \in L^1(0, S; ((H^2(\Omega))^3 \cap V'))\}\) to a certain function \((v(t), T(t))\). Then \((v(t), T(t))\) is a weak solution on \([0, S]\) with \((v(0), T(0)) = (v_0, T_0)\).

3.1. The existence of a global attractor in \(X_t\)

In this subsection, we will consider the existence of global attractors for problem \((2.3)-(2.5)\) by using the \(\ell\)-trajectory method. From Theorem 3.1 we deduce that for any \(t > 0\), there exists some \(t_0 \in (0, t)\) such that \((v(t_0), T(t_0)) \in V\). Therefore, we infer from Remark 2.1 in \([18]\) that there exists a unique solution of problem \((2.3)-(2.5)\) with smoother initial data \((v(t_0), T(t_0))\). Therefore, many trajectories may start from the same initial data \((v_0, T_0) \in H\).

Denote by \(\{e^\beta(t, (v_0, T_0))\}_{t \in (0, T)}\), for short \(e^\beta(t, (v_0, T_0))\), \(\beta \in \Gamma_{(v_0, T_0)}\), \(\Gamma_{(v_0, T_0)}\) is the set of indices marking trajectories starting from \((v_0, T_0)\). In the following, we first give the mathematical framework of attractor.

**Definition 3.1.** Let \(\ell\) be a fixed positive constant. Define
\[
X_\ell = \bigcup_{(v_0, T_0) \in H} \bigcup_{\beta \in \Gamma_{v_0, T_0}} X^\beta(t, (v_0, T_0))
\]
equipped with the topology of \(L^2(0, \ell; H)\).

Since \(X_\ell \subset C([0, \ell]; H_0)\), it makes sense to talk about the point values of trajectories. On the other hand, it is not clear whether \(X_\ell\) is closed in \(L^2(0, \ell; H)\) and hence \(X_\ell\) in general is not a complete metric space. In what follows, we first give the definition of some operators.

For any \(t \in [0, 1]\), we define the mapping \(e_t : X_\ell \to H \times V_t\) by
\[
e_t(\chi) = \chi(t\ell)
\]
for any \(\chi \in X_\ell\).

The operators \(L_t : X_\ell \to X_\ell\) are given by the relation
\[
L_t(\chi(t, (v_0, T_0))) = (v, T)(t + \tau, (v_0, T_0)), \quad \tau \in [0, \ell]
\]
for any \(\chi(t, (v_0, T_0)) \in X_\ell\), where \((v, T)\) is the unique solution of problem \((2.3)-(2.5)\) on \([0, \ell + t]\) such that \((v, T)|_{[0, \ell]} = \chi(t, (v_0, T_0))\), we can easily prove the operators \([L_t]_{t \geq 0}\) is a semigroup on \(X_\ell\).

From the proof of absorbing balls in \([18]\), we immediately obtain the following result.
**Theorem 3.2.** Assume that $Q \in L^2(\Omega)$. Then there exists a positive constant $\rho_1$ satisfying for any bounded subset $B \subset H$, there exists a time $\tau_1 = \tau_1(B) > 0$ such that for any weak solutions of problem (2.3)-(2.5) with initial data $(v_0, T_0) \in B$, we have

$$
\|v(t)\|^2 + \|T(t)\|^2 \leq \rho_1
$$

for any $t \geq \tau_1$.

Let

$$
B_0 = \{(v, T) \in V : \|v\|^2 + \|T\|^2 \leq \rho_1\},
$$

we infer from Theorem 3.2 that there exists a time $t_0 = t_0(B_0) \geq 0$ such that for any $(v_0, T_0) \in B_0$ and any $t \geq t_0$, we have

$$
(v(t), T(t)) \in B_0,
$$

where $(v(t), T(t))$ is the solution of problem (2.3)-(2.5) with initial data $(v_0, T_0) \in B_0$.

Define

$$
A(t, (v_0, T_0)) = \{(v(t), T(t)) : (v(t), T(t)) \text{ is the solution of problem (2.3)-(2.5) with initial data} (v_0, T_0)\},
$$

$$
B_1 = \bigcup_{t \in [0, t_0]} \{A(t, (v_0, T_0)) : (v_0, T_0) \in B_0\},
$$

and

$$
B_2 = \overline{B_1}
$$

from the proof of absorbing balls in [18] and Theorem 3.2, we deduce

$$
\{A(t, (v_0, T_0)) : (v_0, T_0) \in B_1\} \subset B_1
$$

for any $t \geq 0$ and $B_1$ is a bounded subset of $V$. Moreover, we have the following conclusion.

**Proposition 3.1.** Assume that $B_1$ is a bounded subset of $V$. Then $B_2 = \overline{B_1}$ is also a positively invariant, bounded subset of $V$.

**Proof.** From the definition of $B_2$, we infer that for any $x \in B_2$, there exists a sequence $(x_n)_{n=1}^\infty \subset B_1$ such that

$$
x_n \to x \text{ in } H, \text{ as } n \to \infty.
$$

Since $x_n$ is uniformly bounded in $V$ and $V$ is a reflexive Hilbert space, we deduce that there exist some $y \in V$ and a subsequence $(x_{n_j})_{j=1}^\infty$ of $(x_n)_{n=1}^\infty$ such that

$$
x_{n_j} \to y \text{ in } V, \text{ as } j \to \infty.
$$

From the compactness of $V \subset H$ and the lower semi-continuity of $\| \cdot \|$, we obtain

$$
x = y
$$

and

$$
\|y\| \leq \liminf_{n \to +\infty} \|x_n\|.
$$

Therefore, $B_2$ is a bounded subset of $V$. 

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For any \( x \in B_2 \) and any fixed \( t > 0 \), there exists a sequence \( \{x_n\}_{n=1}^\infty \subset B_1 \) such that \( x_n \to x \) in \( H \) as \( n \to \infty \), we infer from Lemma 3.1 that \( A(t, x_n) \to A(t, x) \) in \( H \) as \( n \to \infty \). Notice that \( A(t, x_n) \in B_1 \) for any \( n \in \mathbb{Z}^+ \), we obtain \( A(t, x) \in B_2 \). Therefore, we obtain

\[
[A(t, (v_0, T_0)) : (v_0, T_0) \in B_2] \subset B_2
\]

for any \( t \geq 0 \).

From Theorem 3.2, we immediately obtain the following result.

**Corollary 3.2.** Assume that \( Q \in L^2(\Omega) \). Then for any bounded subset \( B_\ell \subset X_\ell \), there exists a time \( \tau_2 = \tau_2(B_\ell) > 0 \) such that for any weak solutions of problem (2.3)-(2.5) with short trajectory \( \chi \in B_\ell \), we have

\[
\|v(t)\|^2 + \|T(t)\|^2 \leq \rho_1
\]

for any \( t \geq \tau_2 \).

Next, we prove the existence of absorbing sets in \( X_\ell \) for the three dimensional viscous primitive equations of large-scale atmosphere.

**Theorem 3.3.** Assume that \( Q \in L^2(\Omega) \). Then there exists a positive constant \( \rho_2 \) satisfying for the \( B_0 \), there exists a time \( \tau_3 = \tau_3(B_0) > 0 \) such that for any weak solutions of equations (2.3)-(2.5) with short trajectory \( \chi(\tau, (v_0, T_0)) \in B_0 \), we have

\[
\int_0^\ell \|v(T(t+\tau))\|^2 d\tau + \left( \int_0^\ell \|v(T(t+\tau))\|_{(W^2(\Omega) \cap V)^\prime} d\tau \right)^2 \leq \rho_2
\]

for any \( t \geq \tau_3 \).

**Proof.** Taking the \( L^2(\Omega) \) inner product of the second equation of (2.3) with \( T \) and combining Lemma 2.1 with Young inequality, we obtain

\[
\frac{1}{2} \frac{d}{dt} \|T\|^2 + \|T\|^2 = \int_\Omega QT\, dxdydz \leq \|Q\|_2 \|T\|_2 \leq \frac{1}{2} \|T\|^2 + \frac{1}{2} K_2 \|Q\|^2_2,
\]

which implies that

\[
\frac{d}{dt} \|T\|^2_2 + \frac{1}{K_2} \|T\|^2_2 \leq K_2 \|Q\|^2_2
\]

and

\[
\frac{d}{dt} \|T\|^2 + \|T\|^2 \leq K_2 \|Q\|^2_2. \tag{3.1}
\]

It follows from the classical Gronwall inequality that

\[
\|T(t)\|^2_2 \leq \|T_0\|^2_2 e^{-\frac{t}{K_2}} + K_2 \|Q\|^2_2. \tag{3.2}
\]

Thanks to

\[
\frac{d}{ds} \left( \|T(s)\|^2_2 e^{\frac{t}{K_2}} \right) \leq K_2 \|Q\|^2_2 e^{\frac{t}{K_2}}, \tag{3.3}
\]

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for any \( \tau \in (0, \ell) \), integrating (3.3) with respect to \( s \) from \( \tau \) to \( t + \tau \) and integrating the resulting inequality over \((0, \ell)\) with respect to \( \tau \), we obtain

\[
\int_0^\ell \|T(t + \tau)\|_2^2 \, d\tau \leq e^{-\frac{\tau}{2}} \int_0^\ell \|T(\tau)\|_2^2 \, d\tau + C K_2^2 \|Q\|_2^2 \ell.
\]

Multiplying the first equation of (2.3) by \( v \) and integrating over \( \Omega \), we find

\[
\frac{1}{2} \frac{d}{dt} \|v\|_2^2 + \|v\|_2^2 = - \int_\Omega \nabla T(x, y, s, t) ds \cdot v(x, y, z, t) \leq C \|T\|_{L^2} \|\nabla v\|_2.
\]

Let \( \lambda = \sup \{ \lambda \in \mathbb{R} : \lambda \|v\|_2^2 \leq \|v\|_2^2, \forall v \in V_1 \} \), we infer from Young inequality and Poincaré inequality that

\[
\frac{d}{dt} \|v\|_2^2 + \|v\|_2^2 \leq \frac{C}{\lambda} \|T\|_2^2.
\]

We infer from the classical Gronwall inequality and (3.2) that

\[
\|v(t)\|_2^2 \leq \|v(0)\|_2^2 e^{-2\lambda t} + \frac{C}{\lambda} \int_0^t \|T(s)\|_2^2 e^{2\lambda(s-t)} \, ds
\]

\[
\leq \|v(0)\|_2^2 e^{-2\lambda t} + \frac{C}{\lambda} \int_0^\infty \|T_0\|_2^2 e^{-\frac{\tau}{2} + \lambda(\tau-t)} + K_2^2 \|Q\|_2^2 e^{-\frac{\tau}{2}} \, d\tau
\]

\[
\leq \|v(0)\|_2^2 e^{-2\lambda t} + \frac{C K_2}{\lambda(1 - K_2\lambda)} \|T_0\|_2^2 e^{-2\lambda t} + \frac{C}{\lambda^2} K_2^2 \|Q\|_2^2.
\]

Thanks to

\[
\frac{d}{ds}(\|v(s)\|_2^2 e^{2\lambda s}) \leq \frac{C}{\lambda} \|T(s)\|_2^2 e^{2\lambda s}.
\]

Integrating (3.8) with respect to \( s \) between \( \tau \) and \( t + \tau \) and integrating the resulting inequality with respect to \( \tau \) over \((0, \ell)\), using (3.2) and (3.7), we know

\[
\int_0^\ell \|v(t + \tau)\|_2^2 \, d\tau \leq \left( \frac{1}{\lambda} \|v(0)\|_2^2 + \frac{C K_2}{\lambda(1 - K_2\lambda)} \|T_0\|_2^2 + \frac{K_2}{\lambda(1 - K_2\lambda)} \|T_0\|_2^2 + \frac{C}{\lambda^2} K_2^2 \|Q\|_2^2 \right) e^{-2\lambda t} + \frac{C}{\lambda^2} K_2^2 \|Q\|_2^2 \ell.
\]

From Proposition 3.1, (3.4) and (3.5), we deduce that there exists some time \( t_0 = t_0(B_0') \) such that

\[
\int_0^\ell \|v(t + \tau)\|_2^2 + \|T(t + \tau)\|_2^2 \, d\tau \leq \phi_1
\]

for any \( t \geq t_0 \), where

\[
\phi_1 = 2(1 + \frac{C}{\lambda^2}) K_2^2 \|Q\|_2^2 \ell.
\]

Integrating (3.1) and (3.5) between \( t - s \) and \( t + \ell \) with \( \ell \geq t_0 + \frac{1}{4} \ell \), \( s \in (0, \frac{1}{2} \ell) \) and combining (3.10), we obtain

\[
\int_0^\ell \|v(t + \tau)\|_2^2 + \|T(t + \tau)\|_2^2 \, d\tau \leq 2K_2 \|Q\|_2^2 \ell + \|v(t - s)\|_2^2 + \|T(t - s)\|_2^2 + \frac{2C}{\lambda} \int_0^\ell \|T(t + \tau)\|_2^2 \, d\tau
\]

\[
\leq 2K_2 \|Q\|_2^2 \ell + \|v(t - s)\|_2^2 + \|T(t - s)\|_2^2 + \frac{2C}{\lambda} \frac{\lambda^2}{2} \phi_1.
\]
Integrating (3.11) with respect to $s$ over $(0, \frac{t}{2})$ and using (3.10), we find
\[
\frac{\ell}{2} \int_0^\ell \|v(t + \tau)\|^2 + \|T(t + \tau)\|^2 \, d\tau \leq K_2 \|Q\|^2 \ell^2 + \int_0^\ell \|v(t - s)\|^2_2 + \|T(t - s)\|^2_2 \, ds + \frac{C}{A} q_1 \ell
\]
\[
= K_2 \|Q\|^2 \ell^2 + \int_0^\ell \|v(t - \frac{\ell}{2} + s)\|^2_2 + \|T(t - \frac{\ell}{2} + s)\|^2_2 \, ds + \frac{C}{A} q_1 \ell
\]
\[
\leq K_2 \|Q\|^2 \ell^2 + q_1 + \frac{C}{A} q_1 \ell
\]
which implies that
\[
\int_0^\ell \|v(t + \tau)\|^2 + \|T(t + \tau)\|^2 \, d\tau \leq q_2
\]
for any $t \geq t_0 + \frac{\ell}{2}$, where
\[
q_2 = 2K_2 \|Q\| \ell^2 + \left(\frac{2C}{A} + \frac{2}{\ell}\right) q_1.
\]
For any $(\phi, \psi) \in V \cap (H^2(\Omega))^2$, from Hölder inequality, we deduce
\[
\langle v, \phi \rangle \leq \|v_1\|_2 \|\phi\|_2 + C \|v\|_2 \|\phi\|_6 + C \|v\|_2 \|\phi\|_2 + \|T\|_2 \|\phi\|_2 + \|\phi\|_2
\]
\[
\leq C (\|v\|^2 + 1 + \|T\|^2 + \|\phi\|^2)
\]
and
\[
\langle T, \psi \rangle \leq \|v_1\|_2 \|T\|_6 \|\psi\|_2 + C \|v\|_2 \|T\|_3 \|\psi\|_6 + \|T\| \|\psi\| + \|Q\|_2 \|\psi\|_2
\]
\[
\leq C (\|T\|^2 + \|v\|^2 + \|Q\|_2 \|\psi\|_2)
\]
which implies that
\[
\|v, T\|_{(V \cap (H^2(\Omega))^2)} \leq C (\|v\|^2 + \|T\|^2 + 1 + \|Q\|_2)
\]
Integrating (3.13) over $(t, t + \ell)$ and combining (3.12), we find
\[
\int_0^\ell \|v(t + \tau), T(t + \tau)\|_{(V \cap (H^2(\Omega))^2)} \, d\tau \leq C (q_2 + \ell + \ell \|Q\|_2)
\]
for any $t \geq t_0 + \frac{\ell}{2}$.

Let
\[
Y = \{ \chi \in X : \chi \in L^2(0, \ell; V), \chi_t \in L^1(0, \ell; (V \cap (H^2(\Omega))^3')) \}
\]
equipped with the following norm
\[
\|\chi\|_Y = \left( \int_0^\ell \|\chi(t)\|^2 \, dt + \left( \int_0^\ell \|\chi(t)\|_{(V \cap (H^2(\Omega))^3')} \, dt \right)^\frac{2}{3} \right)\frac{3}{2}.
\]
Define
\[
B' = \{ \chi \in X : \|\chi\|_Y \leq \rho_2 \}
\]
From Proposition 3.1 and Theorem 3.3 we know that $L_t B'_t \subset B'_0$ for any $t \geq 0$ as well as $L_t B'_t \subset B'_t$ for any $t \geq \tau_3$. 

Lemma 3.2. Assume that $Q \in L^2(\Omega)$. Then $L_tB^0_0 \subset B^0_t$ for any $t \geq 0$.

Proof. Thanks to $L_tB^0_t \subset B^0_t$ for any $t \geq 0$, it is enough to prove that

$$L_tB^2_0 \subset B^2_t$$

For any $\chi_0 \in B^2_0$, there exists a sequence of trajectories $\chi_n \in B^1_0$ such that $\chi_n \to \chi_0$ in $L^2(0, t; H)$, which implies that $e_t(\chi_n) \to e_t(\chi_0)$ in $H$ for almost all $t \in [0, 1]$. Since $e_t(\chi_n) \in B^2_t$ for any $n \in \mathbb{N}$, there exists a subsequence $\{e_t(\chi_n)\}_{n=1}^{\infty}$ of $\{e_t(\chi_n)\}_{n=1}^{\infty}$ and $(u_0, \phi_0) \in V$ such that $e_t(\chi_n) \to (u_0, \phi_0)$ in $V$. From the proof of the existence of weak solutions for problem (2.3)-(2.5), we deduce that for any $S > 0$, there exists a subsequence converging weakly in spaces $L^2(0, S; H) \cap L^2(0, S; V) : (v_1, T) \in L^2(0, S; ((H^2(\Omega))^d \cap V'))$ to a certain function $(v(t), T(t))$ with $(v(0), T(0)) = (v_0, T_0)$. Therefore, we obtain $\chi_0 \in X_T$ from Corollary 3.1. It remains to show that $e_t(\chi) \in B^2_t$. Since $B_2$ is weakly closed in $V$, we deduce from the proof of Proposition 3.1 that $e_t(\chi_0) \in B^2_t$ for almost all $t \in [0, 1]$. In particular, $e_t(\chi_0) \in B^2_t$ for any sequence $\ell_0$ with $\ell_0 \to 0$. From the weak continuity of $\chi_0 : [0, \ell] \to H$ and the weak closedness of $B_2$, we deduce that $e_t(\chi_0) \in B_2$. Therefore, we obtain $\chi_0 \in B^2_0$.

Lemma 3.3. Assume that $Q \in L^2(\Omega)$. Then the mapping $L_t : X_T \to X_T$ is locally Lipschitz continuous on $B^1_t$ for all $t \geq 0$.

Proof. For any fixed $t > 0$, let $(v_1, T_1, p_1), (v_2, T_2, p_2)$ be two solutions for problem (2.3)-(2.5) with the initial data $(v_{i0}, T_{i0}), (v_{20}, T_{20})$, respectively. Let $v = v_1 - v_2, T = T_1 - T_2, p = p_1 - p_2$, from the proof of Theorem 2 in [3], we conclude

$$\frac{d}{dt}||v(t)||^2 + ||T(t)||^2 \leq L(t)||v(t)||^2 + ||T(t)||^2, \quad (3.15)$$

where

$$L(t) = C(||\nabla v_1^2||^2 + ||\nabla T_2||^2 + ||\nabla \partial v_2||^2 ||\nabla \partial v_2||^2 + ||\nabla \partial T_2||^2 ||\nabla \partial T_2||^2).$$

Let $s \in (0, \ell)$ and integrating (3.15) from $s$ to $t + s$, we obtain

$$||v(t + s)||^2 + ||T(t + s)||^2 \leq \int_s^{t + s} L(r)||v(r)||^2 + ||T(r)||^2 dr + ||v(s)||^2 + ||T(s)||^2. \quad (3.16)$$

From the classical Gronwall inequality, we deduce

$$||v(t + s)||^2 + ||T(t + s)||^2 \leq ||v(s)||^2 + ||T(s)||^2 \exp \int_s^{t + s} L(r) dr$$

$$\leq M(t)||v(s)||^2 + ||T(s)||^2, \quad (3.17)$$

where

$$M(t) = \exp \int_0^{t + \ell} L(r) dr \quad (3.18)$$

is a finite number depending on $(v_{20}, T_{20}) \in B_2$ for any fixed $t > 0$ from Remark 2.1 in [18] and the proof of a priori estimates in [3].

Integrating (3.17) with respect to $s$ for $0$ to $\ell$, we obtain

$$\int_0^\ell ||v(t + s)||^2 + ||T(t + s)||^2 ds \leq M(t) \int_0^\ell ||v(s)||^2 + ||T(s)||^2 ds, \quad (3.19)$$

which implies the mapping $L_t : X_T \to X_T$ is locally Lipschitz continuous on $B^1_t$ for all $t \geq 0$.

We can immediately obtain the existence of a global attractor in $X_T$ from Lemma 2.3 stated as follows.
Theorem 3.4. Assume that \( Q \in L^2(\Omega) \). Then the semigroup \( \{L_t\}_{t \geq 0} \) generated by problem (2.3) possesses a global attractor \( \mathcal{A}_t \) in \( X_t \) and \( e_t(\mathcal{A}_t) \) is uniformly bounded in \( V \) with respect to \( t \in [0, 1] \), where

\[
e_t(\mathcal{A}_t) = \{e_t(\chi) : \chi \in \mathcal{A}_t\}
\]

for any \( t \in [0, 1] \).

In what follows, we prove the smooth property of the semigroup \( \{L_t\}_{t \geq 0} \) to estimate the fractal dimension of the global attractor \( \mathcal{A}_t \).

Theorem 3.5. Assume that \( Q \in L^2(\Omega) \), let \( \chi^1 \) and \( \chi^2 \) be two short trajectories belonging to \( \mathcal{A}_t \). Then there exists a positive constant \( \kappa \) independent of \( t \) such that for arbitrary \( t \geq \ell \), we have

\[
\|L_t\chi^1 - L_t\chi^2\|_V^2 \leq \kappa M_\ell(t) \int_0^\ell \|\chi^1(r) - \chi^2(r)\|_V^2 \, dr,
\]

where \( M_\ell(t) \) is given in (3.13).

Proof. For any \( \chi^1, \chi^2 \in \mathcal{A}_\ell \), let \( (v_1(t + \tau), T_1(t + \tau)) = L_t\chi^1 \), \( (v_2(t + \tau), T_2(t + \tau)) = L_t\chi^2 \) and let \( v = v_1 - v_2, T = T_1 - T_2 \). Since \( e_t(\chi^1) \) and \( e_t(\chi^2) \) is uniformly bounded in \( V \) with respect to \( t \in [0, 1] \) for any \( \chi^1, \chi^2 \in \mathcal{A}_\ell \), from the proof of Theorem 2 in [3], we conclude

\[
\frac{d}{dt}(\|v(t)\|_2^2 + \|T(t)\|_2^2) \leq \mathbb{L}(t)(\|v(t)\|_2^2 + \|T(t)\|_2^2),
\]

(3.20)

where

\[
\mathbb{L}(t) = C(\|\nabla v_1\|_2^2 + \|\nabla T_2\|_2^2 + \|\partial_\tau v_1\|_2^2\|\nabla \partial_\tau v_2\|_2^2 + \|\partial_\tau T_2\|_2^2\|\nabla \partial_\tau T_2\|_2^2).
\]

For any \( t \geq \ell \), integrating (3.20) from \( t - s \) to \( t + \ell \) with \( s \in [0, \frac{\ell}{2}] \), we conclude

\[
\|v(t + \ell)\|_2^2 + \|T(t + \ell)\|_2^2 + \int_{t-s}^{t+\ell} \|v(\xi)\|_2^2 + \|T(\xi)\|_2^2 \, d\xi \\
\leq \int_{t-s}^{t+\ell} \mathbb{L}(\xi)(\|v(\xi)\|_2^2 + \|T(\xi)\|_2^2) \, d\xi + \|v(t-s)\|_2^2 + \|T(t-s)\|_2^2.
\]

It follows from the classical Gronwall inequality that

\[
\|v(t + \ell)\|_2^2 + \|T(t + \ell)\|_2^2 + \int_{t-s}^{t+\ell} \|v(\xi)\|_2^2 + \|T(\xi)\|_2^2 \, d\xi \\
\leq \exp(\int_{t-s}^{t+\ell} \mathbb{L}(\xi) \, d\xi)(\|v(t-s)\|_2^2 + \|T(t-s)\|_2^2).
\]

(3.21)

For any \( t \geq \ell \) and any \( s \in [0, \frac{\ell}{2}] \), integrating (3.20) from \( s \) to \( t - s \), we obtain

\[
\|v(t-s)\|_2^2 + \|T(t-s)\|_2^2 \leq \int_{s}^{t-s} \mathbb{L}(r)(\|v(r)\|_2^2 + \|T(r)\|_2^2) \, dr + (\|v(s)\|_2^2 + \|T(s)\|_2^2).
\]

We deduce from the classical Gronwall inequality that

\[
\|v(t-s)\|_2^2 + \|T(t-s)\|_2^2 \leq (\|v(s)\|_2^2 + \|T(s)\|_2^2) \exp(\int_{0}^{t-s} \mathbb{L}(r) \, dr) \\
\leq (\|v(s)\|_2^2 + \|T(s)\|_2^2) \exp(\int_{0}^{t-s} \mathbb{L}(r) \, dr).
\]

(3.22)
Combining (3.21) with (3.22), we obtain
\[
\int_0^\ell \|v(t + \zeta)\|^2 + \|T(t + \zeta)\|^2 \, d\zeta \leq \exp(\int_0^{\ell + t} L(\zeta) \, d\zeta) (\|v(s)\|^2 + \|T(s)\|^2) = M_e(t)(\|v(s)\|^2 + \|T(s)\|^2).
\]
Integrating the above inequality over \((0, \ell)\) with respect to \(s\), we obtain
\[
\int_0^\ell \|v(t + \zeta)\|^2 + \|T(t + \zeta)\|^2 \, d\zeta \leq \frac{2M_e(t)}{\ell} \int_0^\ell \|v(s)\|^2 + \|T(s)\|^2 \, ds.
\]
Thanks to \(M_e(t)\) is bounded for any fixed \(t \in [\ell, S]\), we obtain
\[
\int_0^\ell \|v(t + \zeta)\|^2 + \|T(t + \zeta)\|^2 \, d\zeta \leq \frac{2M_e(t)}{\ell} \int_0^\ell \|v(s)\|^2 + \|T(s)\|^2 \, ds.
\]
Thanks to
\[
\|v\|_{(H^2(\Omega) \cap V^1)} \leq \|v\| + C\|v\|_1 + \|v\|_6 + C\|\nabla v\|_3 + C\|\nabla v\|_3 + C\|v\|_3 + C\|v\|_3 + C\|\nabla v\|_2 + C\|v\|_2
\]
and
\[
\|T\|_{(H^2(\Omega) \cap V^1)} \leq \|T\| + C\|v\|_1 + \|T\|_6 + C\|\nabla v\|_3 + C\|\nabla v\|_3 + C\|T\|_3 + C\|T\|_3 + C\|\nabla v\|_2 + C\|v\|_2
\]
we infer from Theorem 3.4, 3.24 + 3.26 that
\[
\left( \int_0^\ell (\|v(t + r), T(t + r)\|_{(H^2(\Omega) \cap V^1)} \, dr \right)^2 \leq \kappa_2 M_e(t) \int_0^\ell \|v(s)\|^2 + \|T(s)\|^2 \, ds.
\]
The proof of Theorem 3.5 is completed.

From Lemma 2.4, Theorem 3.4 and Theorem 3.5, we immediately obtain the following result.

**Theorem 3.6.** Assume that \(Q \in L^2(\Omega)\). Then the fractal dimension of the global attractor \(\mathcal{A}_t\) in \(X_t\) of the semigroup \(L_{t \geq 0}\) generated by problem (2.3)–(2.5) established in Theorem 3.4 is finite.

### 3.2. The existence of a global attractor in \(H\)

In this subsection, we prove the existence of a finite dimensional global attractor in \(H\) of problem (2.3)–(2.5). From Lemma 3.1, we deduce that for any given initial condition \((v_0, T_0) \in B_2 \subset V\), there exists a unique solution of problem (2.3)–(2.5), hence solution operators \(S(t)\) is a semigroup on \(B_2\). Moreover, \(B_2\) is positively invariant with respect to \(S(t)\).

**Theorem 3.7.** Assume that \(Q \in L^2(\Omega)\). Then the mapping \(e_1 : \mathcal{A}_t \to \mathcal{A} = e_1(\mathcal{A}_t)\) is Lipschitz continuous. That is, for any two short trajectories \(\chi^1, \chi^2 \in \mathcal{A}_t\), there exists a positive constant \(\theta\) dependent on \(t\) such that
\[
\|e_1(\chi^1) - e_1(\chi^2)\|_2^2 \leq \theta \int_0^\ell \|\chi^1(r) - \chi^2(r)\|_2^2 \, dr.
\]

**Proof.** For any \(\chi^1, \chi^2 \in \mathcal{A}_t\), let \((v_1(t + r), T_1(t + r) = L_0\chi^1, (v_2(t + r), T_2(t + r) = L_0\chi^2)\) and let \(v = v_1 - v_2, T = T_1 - T_2\). Thanks to \(e_0(\chi^1)\) and \(e_0(\chi^2)\) is uniformly bounded in \(V\) for any \(\chi^1, \chi^2 \in \mathcal{A}_t\), from (3.20), we obtain
\[
\frac{d}{dt}(\|v(t)\|^2 + \|T(t)\|^2) + \|v(t)\|^2 + \|T(t)\|^2 \leq \|L(t)(v(t))\|^2 + \|T(t)\|^2.
\]
For $s \in (0, \ell)$, we infer from the classical Gronwall inequality that
\[
\|v(t)\|_{L^2}^2 + \|T(t)\|_{L^2}^2 \leq (\|v(s)\|_{L^2}^2 + \|T(s)\|_{L^2}^2) \exp(\int_s^\ell \|L(r)\| \, dr)
\]
\[
\leq (\|v(s)\|_{L^2}^2 + \|T(s)\|_{L^2}^2) \exp(\int_0^\ell \|L(r)\| \, dr).
\]  
(3.28)

Integrating (3.28) over $(0, \ell)$, we obtain
\[
\|v(t)\|_{L^2}^2 + \|T(t)\|_{L^2}^2 \leq \frac{1}{\ell} \exp\left(\int_0^\ell \|L(r)\| \, dr\right) \int_0^\ell (\|v(s)\|_{L^2}^2 + \|T(s)\|_{L^2}^2) \, ds.
\]

Thanks to (3.18), we know that
\[
\mathcal{M}_L = \exp(\int_0^\ell \|L(r)\| \, dr) < +\infty,
\]
which implies that the mapping $e_1 : \mathcal{A}_\ell \to \mathcal{A}$ is Lipschitz continuous.

\[\Box\]

**Theorem 3.8.** Assume that $Q \in L^2(\Omega)$. Then dynamical system $(S(t), B_2)$ possesses a global attractor $\mathcal{A} = e_1(\mathcal{A}_\ell)$ in $H$, which is compact, invariant in $H$ and attracts every bounded subset in $H$ with respect to the topology of $H$. Furthermore, $\mathcal{A}$ is bounded in $V$ and its fractal dimension is finite.

**Proof.** From Lemma 2.5, Theorem 3.6 and Theorem 3.7, we know that $L$ is finite. As a result of (2.3)-(2.5), there exist a subsequence $\{n_j\} \subset \mathbb{N}$ and some positive constant $C$ such that for any $t \geq 0$ and any $\ell \in (0, \ell)$, we have
\[
\mathcal{S}(t') = \mathcal{S}(t e_1(\mathcal{A}_{\ell}) = e_1(L_n \mathcal{A}_{\ell}) = e_1(\mathcal{A}_\ell) = \mathcal{A}
\]
for any $t \geq 0$. From the definition of $B_2$, we deduce that for any bounded subset of $H$, there exists some time $\bar{t} = \bar{t}(B)$ such that for any $t \geq \bar{t}$, we have
\[
\mathcal{A}(t, (v_0, T_0)) : (v_0, T_0) \in B \subset B_2.
\]

Therefore, we only need to prove that
\[
\lim_{t \to +\infty} \text{dist}_H(S(t)B_2, \mathcal{A}) = 0.
\]

Otherwise, there exist some positive constant $\epsilon_0$, some sequence $\{(v_n, T_n)\}_{n=1}^\infty \subset B_2$ and some $\{t_n\}_{n=1}^\infty$ with $t_n \to +\infty$ as $n \to +\infty$ such that
\[
\text{dist}_H(S(t_n)(v_n, T_n), \mathcal{A}) \geq \epsilon_0.
\]
(3.29)

From the definition of $B_2$, we deduce that there exists $\chi_n \in B_2$ such that
\[
(v_n, T_n) = e_0(\chi_n).
\]

Since $\{\chi_n\}_{n=1}^\infty$ is bounded in $X_{\ell}$ and $\mathcal{A}_{\ell}$ is a global attractor in $X_{\ell}$ of the semigroup $\{L_n\}_{n=1}^\infty$ generated by problem (2.3)-(2.5), there exist a subsequence $\{\chi_{n_j}\}_{j=1}^\infty$ of $\{\chi_n\}_{n=1}^\infty$ and a subsequence $\{t_{n_j}\}_{j=1}^\infty$ of $\{t_n\}_{n=1}^\infty$ such that
\[
L_{n_j}^{-t_{n_j}} \chi_{n_j} \to \chi \in \mathcal{A}_{\ell} \in X_{\ell} \text{ for as } j \to +\infty.
\]

Thanks to the continuity of $e_1$, we have
\[
S(t_{n_j})(v_{n_j}, T_{n_j}) = e_1(L_{n_j}^{-t_{n_j}} \chi_{n_j}) \to e_1(\chi) \in \mathcal{A} \in H \text{ as } j \to +\infty,
\]
which contradicts with (3.29).

\[\Box\]

Since $\mathcal{A}$ is bounded in $V$, we immediately obtain the following result.

**Theorem 3.9.** Assume that $Q \in L^2(\Omega)$ and $\mathcal{A}_1$ is the global attractor established in [18]. Then
\[
\mathcal{A}_1 = \mathcal{A}.
\]  
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