A Critical Examination of RESCAL for Completion of Knowledge Bases with Transitive Relations

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Abstract
Link prediction in large knowledge graphs has received a lot of attention recently because of its importance for inferring missing relations and for completing and improving noisily extracted knowledge graphs. Over the years a number of machine learning researchers have presented various models for predicting the presence of missing relations in a knowledge base. Although all the previous methods are presented with empirical results that show high performance on select datasets, there is almost no previous work on understanding the connection between properties of a knowledge base and the performance of a model. In this paper we analyze the RESCAL method (Nickel et al., 2011) and show that it cannot encode asymmetric transitive relations in knowledge bases.

1 Introduction
Large-scale and highly accurate knowledge bases (KB) such as Freebase (Bollacker et al., 2008) and YAGO2 (Hoffart et al., 2013), have come to be recognized as essential for high performance on various Natural Language Processing (NLP) tasks. Relation extraction, Question Answering (Dalton et al., 2014; Fader et al., 2014; Yao and Van Durme, 2014) and Entity Recognition/Disambiguation in informal domains (Ritter et al., 2011) [Zheng et al., 2012] are a few examples of tasks where KBs have proved to be invaluable. As these examples demonstrate, increasing the recall of knowledge bases without compromising on the precision has a direct impact on several tasks that are the focus of NLP research. Because of this importance of high recall in knowledge bases and because the recall of even Freebase, the largest open source KB, is still quite low, a number of researchers have published heuristics with their empirical performance on automatically inferring the information that is missing in knowledge bases. Unfortunately the literature on theoretical analysis for these methods is still scarce.

In this paper we analyze RESCAL (Nickel et al., 2011) which is a widely cited method for inferring missing relations in KBs. The RESCAL method embeds entities and relations in a KB using vectors and matrices respectively and it predicts the true status of an edge between two nodes using these representations. Although RESCAL was introduced in 2011 and has been shown to be effective on a variety of datasets (Toutanova et al., 2015; Nickel et al., 2011; Nickel et al., 2012) there has been no theoretical analysis of the failure modes of this method. We show, both theoretically and experimentally (Sections 2 and 3), that RESCAL is not suitable for predicting missing relations in a KB that contains transitive and asymmetric relations such as the “type of” relation which is very important in Freebase (Guha, 2015) and the “hypernym” relation which is important in WordNet (Miller, 1995).

2 Analysis of RESCAL

Notation: A knowledge base contains, but is not equal to, a collection of (subject, relation, object) triples. Each triple encodes the fact that a subject entity is related to an object through a particular type of relation. Let \( V \) and \( R \) denote the finite set of entities and relationships. We assume that \( R \) includes a type for the null relation or no relation. Let \( V = |V| \) and \( R = |R| \) denote the number of entities and relations. We use \( v \) and \( r \) to denote a
generic entity and relation respectively. The shorthand \([n]\) denotes \(\{x|1 \leq x \leq n, x \in \mathbb{N}\}\). Let \(E\) be the number of triples known to us and let \(e\) denote a generic triple. We denote the subject, object and relation of \(e\) through \(e^{\text{sub}} \in \mathcal{V}, e^{\text{obj}} \in \mathcal{V}\) and \(e^{\text{rel}} \in \mathcal{R}\) respectively and we denote the entire collection of facts as \(E = \{e_k|k \in [E]\}\).

**RESCAL:** The RESCAL model associates each entity \(v\) with the vector \(a_v \in \mathbb{R}^d\) and it represents the relation \(r\) through the matrix \(M_r \in \mathbb{R}^{d \times d}\). Let \(v\) and \(v'\) denote two entities whose relationship is unknown, the RESCAL model predicts the relation between \(v\) and \(v'\) to be:

\[
\hat{r} = \arg\max_{r \in \mathcal{R}} s(v, r, v') \\
s(v, r, v') = a_v^T M_r a_{v'}
\]

Note that in general if the matrix \(M_r\) is asymmetric then the score function \(s\) would also be asymmetric, i.e., \(s(v, r, v') \neq s(v', r, v)\). Let \(\Theta = \{a_v|v \in \mathcal{V}\} \cup \{M_r|r \in \mathcal{R}\}\). Clearly \(\Theta\) parameterizes RESCAL. Therefore even though the same embedding is used to represent an entity regardless of whether it is the first or the second entity in a relation, the RESCAL model could still handle asymmetric relations if the matrix \(M_r\) is asymmetric.

**Transitive Relations and RESCAL:** In addition to relational information about the binary connections between entities, many KBs contain information about the relations themselves. For example, consider the toy knowledge base depicted in Figure 1. Based on the information that Fluffy is-a Dog and that a Dog is-a Animal and that is-a is a transitive relations we can infer missing relations such as Fluffy is-a Animal.

Let us now analyze what happens when we encode a transitive, asymmetric relation with RESCAL. Consider the situation where the set \(\mathcal{R}\) only contains two relations \(\{r_0, r_1\}\). \(r_1\) denotes the presence of the is-a relation and \(r_0\) denotes the absence of that relation. The RESCAL model can only follow the chain of transitive relations and infer missing edges using existing information in the graph if for all triples of vertices \(v, v', v''\) in \(\mathcal{V}\) for which we have observed \((v, is-a, v')\) and \((v', is-a, v'')\) the following holds true:

\[
s(v, r_1, v') \land s(v', r_1, v'') \land s(v, r_0, v''') \Rightarrow s(v, r_1, v'') > s(v, r_0, v''')
\]

This can be rewritten as:

\[
a_v^T (M_{r_1} - M_{r_0}) a_{v'} > 0 \land a_v^T (M_{r_1} - M_{r_0}) a_{v'''} > 0 \\
\implies a_v^T (M_{r_1} - M_{r_0}) a_{v'''} > 0
\]

We now define a transitive matrix and and state a theorem that we prove in the Appendix.

**Definition** We say that a matrix \(M \in \mathbb{R}^{d \times d}\) is transitive if every triple of vectors \(a, b, c \in \mathbb{R}^d\) that satisfy \(a^T Mb > 0\) and \(b^T Mc > 0\) also satisfy \(a^T Mc > 0\).

**Theorem 1.** Every transitive matrix is symmetric.

If we enforce the constraint in Equation 3 to hold for all possible vectors and not just a finite number of vectors then \(M_{r_1} - M_{r_0}\) is a transitive matrix. By Theorem 1 \(M_{r_1} - M_{r_0}\) must be symmetric. This implies that if the RESCAL model predicts that \(s(v, r_1, v') > s(v, r_0, v')\) then it would also predict that \(s(v', r_1, v') > s(v', r_0, v')\). In terms of the toy KB shown in Figure 1 if the RESCAL model predicts that Fluffy is-a Animal then it would also predict that Animal is-a Fluffy. Therefore the RESCAL model is not suitable for encoding asymmetric, transitive relations.

### 3 Experiments

During our analysis in Section 2 we made assumption that the constraint of equation 3 held over all vectors in \(\mathbb{R}^d\) instead of just a finite number of vector triples. This assumption was used to make conclusions about RESCAL using Theorem 1.

A fair criticism of our analysis is that practically the RESCAL model only needs to encode a finite number of vertices into vector space and it is possible that there exists an asymmetric matrix that can correctly make the finite number of deductions that are possible inside a finite KB. This could be
especially true when the dimensionality $d$ of the RESCAL embeddings is high. On the other hand, it is intuitive that as the number of entities inside a KB increases our assumptions and analysis would become increasingly better approximations of reality. Therefore the performance of the RESCAL model should degrade as the number of entities inside the KB increases and the dimensionality of the embeddings remains constant.

### 3.1 On Simulated Data

In order to test the applicability of our analysis we performed the following experiment: We started with a complete, balanced, rooted, directed binary tree $\mathcal{T}$, with edges directed from the root to its children. We then augmented $\mathcal{T}$ as follows: For every tuple of distinct vertices $v, v'$ we added a new edge to $\mathcal{T}$ if there already existed a directed path starting at $v$ and ending at $v'$ in $\mathcal{T}$. We stopped when we could not add any more edges without creating multi-edges. For the rest of the paper we denote this resulting set of ordered pairs of vertices as $\mathcal{E}$ and those pairs of vertices that are not in $\mathcal{E}$ as $\mathcal{E}^c$. For example $\mathcal{E}$ contains an edge from the root vertex to every other vertex and $\mathcal{E}^c$ contains an edge from every vertex to the root vertex. For a tree of depth 11, $V = 2047$, $|\mathcal{E}| = 18,434$ and $|\mathcal{E}^c| = 4,171,775$.

We trained the RESCAL model under two settings: In the first setting we used entire $\mathcal{E}$ and $\mathcal{E}^c$ as training inputs to the RESCAL model. We denote this setup as FullSet. In the second setting we randomly sample $\mathcal{E}^c$ and select only $E = |\mathcal{E}|$ edges from $\mathcal{E}^c$. We denote this training setup as SubSet. Note however, that all in the edges in $\mathcal{E}$ including all the edges in the original tree are always used during both FullSet and SubSet.

For both the settings of FullSet and SubSet we trained the RESCAL model 5 times and evaluated the models’ predictions on the following three subsets of the edges: $\mathcal{E}$, $\mathcal{E}^c$ and $\mathcal{E}^{rev}$. $\mathcal{E}$ and $\mathcal{E}^c$ were introduced earlier. To recall, $\mathcal{E}$ contains all ordered pairs of vertices that are in the transitive relation of being connected, $\mathcal{E}^c$ contains pairs of vertices that are not connected and not in a relation. $\mathcal{E}^{rev}$ denotes the set of ordered pairs whose reverse pair exists in $\mathcal{E}$. I.e., $\mathcal{E}^{rev} = \{(u, v) | (v, u) \in \mathcal{E}\}$. For every edge in each of these subsets we evaluate the model’s performance under $0 - 1$ loss. For example, when we evaluate the performance of RESCAL on an edge $(v, v') \in \mathcal{E}$ we evaluate whether the model assigns a higher score to $(v, r_1, v')$ than $(v, r_0, v')$ and reward the model by 1 point if it makes the right prediction and 0 otherwise. As before, $r_1$ and $r_0$ denote the presence and absence of relationship between $v$ and $v'$.

We note that low Performance on $\mathcal{E}^{rev}$ and high performance on $\mathcal{E}$ would indicate exactly the kind of failure that we predicted from our analysis.

As explained earlier, the dimensionality of the RESCAL embedding, $d$, and the number of entities, $V$ significantly influence the performance of RESCAL therefore we vary them and tabulate the results in Table 1 and upload_to_arxiv.

| $d$ | $V = 2047$ | 4095 | 8191 |
|-----|------------|------|------|
| 50  | 66 100 100 | 60 100 100 | 54 100 100 |
| 100 | 76 100 100 | 69 100 100 | 63 100 100 |
| 200 | 86 100 100 | 79 100 100 | 72 100 100 |
| 400 | 94 100 100 | 88 100 100 | 81 100 100 |

Table 1: Percentage accuracy of RESCAL with FullSet. Every table element is a triple of numbers measuring the performance of RESCAL on $\mathcal{E}$, $\mathcal{E}^c$, $\mathcal{E}^{rev}$ respectively. $V$ denotes the number of nodes in the tree and $d$ denotes the number of dimensions used to parameterize the entities.

| $d$ | $V = 2047$ | 4095 | 8191 |
|-----|------------|------|------|
| 50  | 100 93 52  | 100 91 48 | 100 89 44 |
| 100 | 100 78 58  | 100 92 56 | 100 89 52 |
| 200 | 100 60 72  | 100 71 61 | 100 90 59 |
| 400 | 100 54 67  | 100 57 70 | 100 65 62 |

Table 2: Accuracy of RESCAL trained with SubSet.

### 3.2 On WordNet

In order to test our analysis on real data we performed experiments on the WordNet dataset. WordNet contains vertices called synsets that are arranged in a tree like hierarchy under the relation of hyponymy. For example, a dog is a hyponym of animal and an animal is a hyponym of living_thing therefore a dog is a hyponym of living_thing. To conduct our experiments we extracted all the hyponyms of the living_thing synset as a tree and edges to that tree to form a transitive closure under the hyponym relation. The living_thing synset contained 16255 hyponyms which were connected with 16489 edges and after performing the transitive closure the number of edges became 128241, i.e., $V = 16,255$ and $E = 128,241$. We performed two experiments under the FullSet and SubSet protocols in exactly the same way as described
in Section 3.1 with the new graph. The results, shown in Table 3, exhibit the same trends as seen in Table 1 and 2. See the following section for a more thorough discussion of results.

\begin{table}[ht]
\centering
\begin{tabular}{|c|c|c|}
\hline
\textbf{d} & \textbf{FullSet} & \textbf{SubSet} \\
\hline
50 & 71 100 100 & 100 93 58 \\
100 & 79 100 100 & 100 94 60 \\
200 & 84 100 100 & 100 93 63 \\
400 & 89 100 100 & 100 68 69 \\
\hline
\end{tabular}
\caption{Results from experiments on WordNet. Specifically we chose to use the subtree rooted at the \textit{living things} synset from the WordNet hierarchy. Every synset in the subtree corresponds to a vertex. Consequently, for all our experiments \( V = 16413 \).}
\end{table}

4 Related Work

Most previous works for inferring the missing information in knowledge bases assumes that a knowledge base is just a graph with labeled vertices and labeled edges (Nickel et al., 2016; Toutanova et al., 2015) and they either focus on inferring which labeled edge, if any, should be used to connect two previously unconnected vertices or they try to learn what vertex label/entity type, if any, should be used to annotate an unlabeled entity.

The task of predicting missing edges in a KB, which we focus on, has previously been called Link Prediction (Liben-Nowell and Kleinberg, 2007; Nickel et al., 2011), Knowledge Base Completion (KBC) (Socher et al., 2013; West et al., 2014) or more broadly Relational Machine Learning (Nickel et al., 2016). Besides the before-mentioned papers the following publications also present models for KBC which we list without comments (Bordes et al., 2011; Lao et al., 2011; Gardner and Mitchell, 2015; Lin et al., 2015; Zhao et al., 2015; Wang et al., 2015; He et al., 2015; Wei et al., 2015).

5 Results and Discussion

Table 1 and 2 show the performance of the RESCAL model, for encoding three subsets of relational information, \( \mathcal{E}, \mathcal{E}^c \) and \( \mathcal{E}^{rev} \) in increasingly large KBs with a single transitive relation under a broad range of settings.

The results in Table 1 were obtained by feeding RESCAL \( \mathcal{E} \cup \mathcal{E}^c \) as training data. Note that RESCAL received all possible information during training so we are evaluating the training accuracy of the model at this point. Low accuracy under this setting implies that the model does not have the capacity to learn the rules in the knowledge base. We observe that the accuracy of RESCAL decreases as the number of entities, \( V \) increases and it increases as the dimensionality, \( d \) increases which in line with our predictions. We also note that since \( \mathcal{E}^c \) is much larger than \( \mathcal{E} \) therefore the training objective of RESCAL favors good performance on \( \mathcal{E}^c \) and accordingly the accuracy of RESCAL on edges in \( \mathcal{E}^c \) remains high but the performance on \( \mathcal{E} \) suffers. The high accuracy of RESCAL with \( V = 2047 \) and \( d = 400 \) suggests that with a high enough dimensionality of the embeddings it is possible to embed a finite database with high accuracy. But increasing the dimensionality of RESCAL embeddings can become infeasible for an extremely large knowledge base. Also we can observe that the performance of RESCAL degrades as the number of entities inside the KB increases and the dimensionality of the embeddings remains constant.

The results in Table 2 were obtained by training RESCAL with \( \mathcal{E} \) and a subset of \( \mathcal{E}^c \). This training method is closer to the way such embedding based methods for KBC are usually trained (Nickel et al., 2016). We observe that the accuracy of the RESCAL model on \( \mathcal{E}^{rev} \) is substantially lower than its performance on either \( \mathcal{E} \) or \( \mathcal{E}^c \), especially in the upper triangle region of the table where \( V \) is high and \( d \) is low. This result is in accordance with our analysis that under the RESCAL mode if \( s(v, r_1, v') > s(v, r_0, v') \) then \( s(v', r_1, v) > s(v', r_0, v) \) as well. Our results also highlight a problem with the commonly employed KBC evaluation protocol of randomly dividing the edge set of a graph into train and test sets for measuring knowledge base completion accuracy. For example with \( d = 50 \) the average accuracy on both \( \mathcal{E} \) and \( \mathcal{E}^c \) is quite high but on \( \mathcal{E}^{rev} \) accuracy is low even though \( \mathcal{E}^{rev} \) is a subset of \( \mathcal{E}^c \). Such a failure would stay undetected with existing evaluation methods.

6 Conclusions

In this paper we investigated a popular KBC algorithm named RESCAL and through our analysis...
We note that Theorem 1 was first proven by Grinberg (2015). Here we give an alternative proof.

Proof. Consider the triplet of vectors \( c := x, b := Mc, a := Mb \). Then \( a^T (Mb) = \|Mb\|^2 \geq 0 \) and \( b^T (Mc) = \|b\|^2 \geq 0 \) and \( a^T Mc = b^T Mb \). Either \( b = 0 \) or \( b \neq 0 \) and \( Mb = 0 \), or both \( Mb \neq 0 \) and \( b \neq 0 \) which implies \( b^T Mb > 0 \) (by transitivity).

In all three cases \( b^T Mb \geq 0 \).

\[ \lambda > 0 = \frac{\|b\|^2}{\|Mb\|^2} \] for some \( \lambda > 0 \).

We defer the proof of this technical lemma to the supplementary material submitted with the paper.

Lemma 4. If there exists \( x, y \) such that \( x^T My > 0 \) and \( x^T MT y < 0 \) then \( M \) is not transitive.

Proof. Let \( x, y \) be two vectors that satisfy \( x^T My > 0 \) and \( x^T MT y < 0 \). Since \( x^T MT y = y^T Mx \) therefore \( y^T M(-x) > 0 \). If we assume \( M \) is transitive, then \( x^T M(-x) > 0 \) by transitivity, but Lemma 2 shows such an \( x \) cannot exist.

Theorem 1. Every transitive matrix is symmetric.

Proof. By Lemma 4 \( x^T My > 0 \) \( \Rightarrow x^T MT y > 0 \). Using Lemma 3 we get \( M = \lambda M^T \) for some \( \lambda > 0 \). Clearly \( \lambda = 1 \).

\[ \lambda > 0 = \frac{\|b\|^2}{\|Mb\|^2} \]

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Acknowledgments

One of the key ideas underlying our work was that knowledge bases should be considered as more than just graphs since KBs also contain logical structure amongst the predicates. By taking such logical structure, e.g., the constraint that if vertex \( v \) connects to \( v' \) and \( v' \) connects to \( v'' \) then \( v \) connects to \( v'' \), to a logical extreme we came up with a well founded argument about the performance of RESCAL in encoding knowledge bases with transitive relations. We believe that this idea can be gainfully used to analyze other KBC methods as well.

A Proof of Theorem 1

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Before proving Lemma 3 let us present its analogue for vectors.

**Lemma 5.** Let \(x, y \in \mathbb{R}^d \setminus \{0\}\). If \(\exists z \in \mathbb{R}^d\) such that \(x^T z > 0\) and \(y^T z < 0\) then \(x = \lambda y\) for some \(\lambda > 0\).

**Proof.** If \(x = \lambda y\) then \(x^T y = \lambda y^T y\). Since \(y^T y > 0\) therefore \(\lambda > 0\). In the case that \(x \neq \lambda y\) then by Cauchy Schwartz inequality \(D := (x^T y)^2 - (x^T x)(y^T y) \neq 0\). Consider the vector \(\alpha x + \beta y\) with \(\alpha = -\frac{x^T y + y^T x}{D}\) and \(\beta = \frac{x^T y + x^T x}{D}\). It is easy to check that \((\alpha x + \beta y)^T x\) and \((\alpha x + \beta y)^T y\) equal 1 and -1, which contradicts the hypothesis. \(\square\)

**Lemma 3.** Let \(M_1, M_2 \in \mathbb{R}^{d \times d} \setminus \{0\}\). If \(\forall x, y:\ x^T M_1 y > 0 \implies x^T M_2 y > 0\) then \(M_1 = \lambda M_2\) for some \(\lambda > 0\).

**Proof.** Choose an \(x \in \mathbb{R}^d\) for which \(x^T M_1 \neq 0\). If such an \(x\) does not exist then \(M_1 = 0\) in contradiction to the hypothesis. Note that if \(x^T M_1 y \neq 0\) then either \(x^T M_1 y\) or \(x^T M_1 - y\) would be positive. Since \((x^T M_1)y > 0 \implies (x^T M_2)y > 0\) there exists \(\exists y\) for which \((x^T M_1)y > 0\) but \((x^T M_2)y < 0\). By Lemma 5 \(x^T M_1 = \lambda_x x^T M_2\). Further from the proof of Lemma 5 \(\lambda_x = \frac{x^T M_1, M_2 x}{x^T M_2 x}\) therefore \(\lambda_x\) is continuous with respect to \(x\). Now we prove that \(\lambda_x\) is constant. Consider vectors \(x\) and \(\alpha x\). As shown earlier, \((\alpha x)^T M_1 = \lambda_{\alpha x} (\alpha x)^T M_2\). But \((\alpha x)^T M_1 = \alpha (x^T M_1) = \alpha \lambda_x x^T M_2\). Therefore \(\lambda_{\alpha x} = \lambda_x\). Since \(\lambda_x\) is continuous at \(0\) therefore \(\lambda_{\alpha x}\) equals the constant \(\lambda_0\). This implies \(x^T (M_1 - \lambda_0 M_2) = 0\). Clearly \(\lambda = \lambda_0 > 0\). \(\square\)