Research Article

3D Modeling Design of Multirole Virtual Character Based on Visual Communication in Wireless Sensor Networks

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In order to solve the problems of poor design effect and time consumption of traditional virtual character modeling design methods, a three-dimensional (3D) modeling design method of multirole virtual characters based on visual communication is studied. Firstly, the wireless sensor network is used to locate, scan, and collect the human body structure information and convert the coordinates to bind the 3D skeleton. Secondly, according to different human postures, we switch the linear hybrid skin algorithm, spherical hybrid skin algorithm, and double quaternion hybrid skin algorithm; design the geometric surface; and attach it to the 3D skeleton to generate 3D modeling. Finally, based on the influence of visual communication on human eye observation and psychological feeling, the geometric surface is divided twice, and the virtual character is rendered in the way of display, coating, and splicing to obtain a complete 3D modeling of the virtual character. The results show that the positioning coverage of this method is higher, the rendering effect of the hand and head is better, the design time is significantly shortened, and the maximum time is no more than 35 min.

1. Introduction

With the advent of the digital information society and the continuous innovation of technologies, virtual reality technology has been born and has been widely applied to various fields [1, 2]. Furthermore, thanks to the increased speed of wireless sensor’s network transmission speed coupled with the guidance of the virtual reality technology [3], virtual communication technology has become more applicable and is able to better adapt to the processing of virtual images. With virtual communication technology, real and 3D images can be perceived virtually, thus meeting people’s demands for interactive images. In recent years, the booming development of the digital information technology has brought prosperity to the animation industry which has become an integral part of China’s cultural sector, and the digital animation industry is also developing rapidly. In addition, with their increasing demands for virtual animation, people are no longer satisfied with the simple modeling of virtual characters in animation, which has led to the continuously increasing demands for modeling design of animation characters [4, 5]. In order to make virtual character 3D modeling more real and interactive [6], it is necessary to explore different design methods of virtual character 3D modeling, upgrade tools used for the production of 3D animation and assisted teaching system, and thus provide more reliable technical support. At present, 3D modeling design has been widely used and has achieved relatively good application effect in 3D landscape design and the interactive gesture system of the Greenland system [7].

Literature [8] proposed a character virtual modeling design method based on the VR technology, in which virtual reality technology is used for the diagrammatic virtual modeling of characters integrated with the 3D virtual modeling technology, so that interactive modeling design of various characters can be realizing just by clicking the mouse. Literature [9] proposed character virtual modeling design methods based on the parameter modeling SMPL, in which the facial characteristics and contours of various characters are used, and the collected data are inputted into the
parameter modeling SMPL to complete the 3D projection of facial modeling. Literature [10] proposed a character virtual modeling design method based on the mobile platform, in which virtual integration processing is conducted according to the modeling of various characters, thus constructing the facial modeling target functions of various characters. Restrictions are set for different characters, and the target function is solved under different restrictions, thus completing the character modeling design. Literature [11] proposed a character virtual modeling design method based on the computer diagram, in which the real-time computer diagrammatic technology, 3D modeling technology, and double-eyed 3D virtual technology are used for the modeling design of various virtual characters in virtual reality technology. Literature [12] proposed a character virtual modeling design method based on deep and enhanced target parameter learning, in which the maximum rewarding function of character virtual modeling design is constructed, and the mapping relationship between different kinds and various characters is studied. Besides, the agent learning method is used to complete the character virtual modeling design.

The current wireless sensor networks are optimized from the perspective of metaheuristics, and the new clustering protocol is used to improve the setting of network nodes. As a new design method proposed in recent years, visual communication, with the help of advanced technologies such as cloud computing and the Internet of Things, better applies visual elements to different art designs and strengthens the visual effect. On the whole, wireless sensor networks and virtual communication means having a wide range of application at this stage. In this study, under the application of wireless sensor networks, a new multirole virtual character 3D modeling design method is proposed based on virtual communication.

The main contributions of this paper are as follows:

1. In this paper, wireless sensor networks are proposed to locate human structure information, including different structural plane information and contour information.
2. Based on the collected human body information, this paper constructs a 3D skeleton and attaches it to the geometric surface to generate a 3D modeling that can be split.
3. Based on virtual communication, this paper renders the overall modeling structure to realize local texture and color enhancement.

2. 3D Modeling Design of Multicharacter Virtual Character Based on Visual Communication

2.1. Locating Human Structure Information in Wireless Sensor Network. To design the 3D modeling of virtual characters, it is necessary to scan the human body structure and locate the information and activity state information of various parts of the human body according to the scanning. It is assumed that the location of the signal transmitting source node in wireless sensor network is \( p_0 \), the signal transmission time is \( t_0 \), and there are \( n \) nodes in the wireless sensor network. According to the above information [13, 14], set the source node’s location as \( p_n \), and then, the corresponding transmission time is

\[
t_n = t_0 + \frac{1}{\alpha} \sum \| p_0 - p_n \| O_n,
\]

where \( \alpha \) refers to the signal transmission speed and \( O_n \) refers to the number of paths. We linearize the above formula, adjust the calculation order of parameters in the formula, and square both sides of the formula at the same time.

\[
\| p_0 - p_n \|^2 = a^2 ( t_0 - t_n + O_n )^2.
\]

The above formula is further transformed to obtain new calculation results:

\[
\| p_n \|^2 - a^2 t_n^2 = 2 p_n^T p_0 - 2 a^2 t_n t_0 - ( \| p_0 \|^2 - a^2 t_0^2 ) + 2 a^2 ( t_0 - t_n ) O_n + a^2 O_n^2.
\]

We regard \( \| p_n \|^2 - a^2 t_n^2 \) in formula (3) as an unknown variable \( \lambda \), i.e., \( \lambda = \| p_n \|^2 - a^2 t_n^2 \). At this point, this formula becomes a linear observation equation, in which the values of \( p_0 \), \( t_0 \), and \( \lambda \) are all estimated values. Coordinate system transformation is performed on the estimated value to obtain

\[
\begin{align*}
  p_i' &= p_i - p_j, \\
  t_j' &= t_i - t_j,
\end{align*}
\]

where \( p_i \) and \( t_i \) mean the coordinate parameters before transformation, while \( p_j \) and \( t_j \) refer to the coordinate transformation parameters.

The parameters after coordinate system transformation are substituted into formula (3) to obtain the following calculation formula:

\[
\| p_i' \|^2 - a^2 t_i'^2 = 2 p_n^T p_i' - 2 a^2 t_i' t_0' - ( \| p_0 \|^2 - a^2 t_0'^2 ) + 2 a^2 ( t_0' - t_n') O_n + a^2 O_n^2,
\]

where \( p_n' \), \( p_i' \), \( t_i' \) and \( t_0' \) are the source node position, transmitting node position, node transmission time, and signal transmission time after coordinate system transformation, respectively.

According to the above calculation, when \( n = j \), \( t_0' + (1/\alpha) \| p_0' \| + O_j = 0 \). Therefore, it is deduced that

\[
\| p_i' \|^2 - a^2 t_i'^2 = 2 a^2 ( t_i' O_j + \frac{1}{2} O_j^2 ).
\]

As can be seen from the above formula, the right side of
the formula contains the measurement error, so the actual value of the parameter is derived according to the coordinate system transformation. According to this value, the positioning parameters of the wireless sensor network are set to realize the positioning of human structure information and provide structural data for the design of virtual character 3D modeling [15].

2.2. Draw 2D Outline of Characters and Bind the 3D Skeleton. The 3D modeling of characters is obtained by averaging multiple human body data, and the 2D contour and 3D skeleton are the support of 3D modeling. Therefore, the 2D contour of characters is drawn according to the positioning data of wireless sensor networks, and the 3D skeleton is bound. It is known that the posture of the human body is determined by bone motion, so starting from 78 joint points of the human body, 20 of them are used to design the 2D contour and 3D skeleton. It is shown in Figure 1.

According to Figure 1, the human skeleton is obtained by scanning mapping, which needs normalization. We set the skeleton in a plane coordinate system [16]; the axes X and Y are used to describe the column and line of a specific pixel in the digital image, respectively; and axis Z is used to describe the deep information. We convert the coordinate system into the world coordinate system and obtain 3D coordinates according to the following conversion relationship:

\[ x = h \frac{X_A}{Z_A}, \]

\[ y = h \frac{Y_A}{Z_A}, \]

\[ z = Z_A, \]

where \((x, y, z)\) refer to the coordinate positions in different directions; \(X_A, Y_A,\) and \(Z_A\) refer to the transformation parameters in the direction of three coordinate axes; and \(h\) refers to the focus [17]. The world coordinate system is obtained according to the coordinate transformation, and the human body structure information obtained by the wireless sensor network through the handheld 3D scanner is transformed. The transformation generates the corresponding transformation relationship according to the following formula:

\[ U \begin{bmatrix} x \\ y \\ 1 \end{bmatrix} = V \begin{bmatrix} x' \\ y' \\ z' \end{bmatrix}, \]

\[ \begin{bmatrix} x \\ y \\ z \end{bmatrix} = UV \begin{bmatrix} x' \\ y' \\ z' \end{bmatrix}, \]

where \(U\) and \(V\) are the internal parameter and external parameter generated by 3D modeling and \((x', y', z')\) refers to the coordinate position parameters after human body structure information transformation. The above formula is used to convert the coordinates to realize the binding of the 3D skeleton.

2.3. Create and Attach Geometric Surfaces for Virtual Character 3D Modeling Design. Virtual character 3D modeling has many geometric surfaces and irregular edges. The geometric surface is attached to the 3D skeleton by a skin algorithm to create virtual character 3D modeling. When designing the geometric surface with influence relationship between the bone and the skin, the skin algorithm designs the edge of the geometric surface by linear calculation. The formula is

\[ R_1 = \sum_{i=1}^{m-1} \omega_i S_i R_0, \]

where \(\omega_i\) refers to the weight of bone \(i\) in affecting the skin surface, \(S_i\) refers to the coordinate transmission result under formula (10), \(R_0\) refers to the original location of the skin vertex, and \(R_1\) refers to the final position of the skin vertex. When a part of the human body moves, formula (11) is no longer used to design the geometric surface edge, but the skin algorithm with a spherical hybrid calculation function is used to obtain the final position of the skin vertex. The formula is

\[ R_1 = S_i K T_i^{-1} R_0, \]

where \(K\) refers to the interpolation rotation matrix calculated according to the weight value \(\omega_i\) when the bone \(i\) rotates; \(T_i^{-1}\) refers to rotation matrix of the skin vertex affected by local actions.

When the human body performs complex movements and the designed 3D modeling of characters needs to be displayed synchronously, the skin algorithm with dual quaternion hybrid computing ability is used. According to the value of the quaternion \(\mu\), we determine the final position of the skin vertex, and the calculation formula of the
The above formula uses the double quaternion hybrid skin algorithm. We convert the bone rotation matrix $S_i$ into unit quaternion $\mu_i$ and get the quaternion $\mu$ by calculating the weight value $\omega$ of all bones. According to this parameter, the final spatial coordinates of the skin vertex are obtained to realize the design of the virtual character 3D modeling geometric surface under a complex action posture [18].

\[
\mu = DLB(\omega, \mu_1, \mu_2, \cdots, \mu_n) = \frac{\omega_1\mu_1 + \omega_2\mu_2 + \cdots + \omega_n\mu_n}{\|\omega_1\mu_1 + \omega_2\mu_2 + \cdots + \omega_n\mu_n\|}.
\] (13)

The above formula uses the double quaternion hybrid skin algorithm. We convert the bone rotation matrix $S_i$ into unit quaternion $\mu_i$ and get the quaternion $\mu$ by calculating the weight value $\omega$ of all bones. According to this parameter, the final spatial coordinates of the skin vertex are obtained to realize the design of the virtual character 3D modeling geometric surface under a complex action posture [18].

2.4. Render Virtual Characters Based on Virtual Communication. After the basic structure of the virtual character 3D modeling is designed, different body parts need to be rendered. In order to enhance the realism of 3D modeling, this design integrates the basic concept of virtual communication and renders virtual characters on the basis of the best view. Virtual communication is a design concept. It is proposed that different location information will make people have different psychological feelings for the information transmitted by different visual planes. It is shown in Figure 2.

![Figure 2: Effect of visual communication.](image)

![Figure 3: Geometric surface splitting.](image)

According to Figure 2, different location matching and color matching will have different psychological effects. Therefore, based on the concept of virtual communication, visual association is established to render the appearance of virtual characters.
of virtual characters through showing, covering, and splicing. Among them, showing is to cover the skin at different positions according to the light, covering is to wrap the body structure and cover the lines, and splicing is to render human skin or decoration in the way of grain splicing [19]. On the premise of the above means, the geometric surface is divided twice, and the color and texture are rendered according to the local structure. It is shown in Figure 3.

We use the split method to avoid the lines and seams visible on the 3D modeling surface and hide the redundant lines and seams under the rendering lines of other body structures, so that the whole 3D model has no redundant lines. So far, the design of multicharacter virtual character 3D modeling is realized based on virtual communication in wireless sensor networks [20].

Through the above process, the 3D modeling design of multirole virtual characters is completed, and the overall design process is shown in Figure 4.

3. Experimental Analysis and Results

3.1. Experimental Environment and Data Set. The experimental environment parameters are shown in Table 1.

The data sets used in this experiment include the iCartoonFace data set and the Danbooru2018 data set. Among them, iCartoonFace contains more than 5000 cartoon characters and more than 400,000 high-quality animation virtual character images. Danbooru2018’s animation picture library contains 140,000 images of 512 × 512 px size HD animation face map. 12000 images were randomly selected from the above data set, and the above images were randomly divided into 120 groups according to a group of 100 images for comparison experiments.

3.2. Experimental Standards. In order to fully verify the performance of this method, the experimental indexes are selected as follows.

Figure 5: Comparison of positioning and coverage effects.
3.2.1. Sensor Coverage. Based on the known coverage and coverage efficiency, a coverage evaluation index is proposed, the basic definition and calculation method of the index are given, and the positioning functions of different design methods are analyzed by using the index. There are two key links in scanning human body information, namely, data acquisition and data positioning. Therefore, the requirements for scanning and positioning are set to two categories: full coverage of one static acquisition target and full coverage of multiple dynamic acquisition targets. We set the coverage rate as $G$. According to the above setting, i.e., $G = 1$ and $G > 1$. In order to evaluate the two kinds of coverage, the body coordinates of the scanned person are set. When the node is within the normal communication range of $G$ referential nodes, the node is covered by $G$. When the coverage of the scanned human body coordinate meets $G$, the region is covered by $G$. When all the points in the scanned region are covered by at least $G$ nodes, it is hereby referred to $G$ coverage, and the formula used to calculate the variance between the average coverage times and the actual coverage times is

$$g_{eve} = \frac{\sum_{i=1}^{n} g_i}{n},$$

where $g_{eve}$ refers to the average coverage times, $\delta_{eve}$ refers to the variance of coverage times, $g_i$ refers to the scanned point $i$, and $n$ refers to all the points in the scanned region. According to the average coverage weight, the scanning data coverage times that can be achieved by different positioning methods can be evaluated; the uniformity of coverage can be tested according to the variance of coverage times.

3.2.2. Hand Modeling Design Effect. The effect of human body data positioning affects the 3D modeling of characters. We install the unified Maya animation software in the design system of 6 groups of methods to open the animation running scene. We open the script editor on the script editing control panel, import the scanning and positioning results of human body structure information obtained by

![Figure 6: 3D modeling structure of human hand.](image)
different methods, and click start to run. We build an experimental test environment, and different test groups design the virtual character 3D modeling according to the obtained positioning data. According to the 3D effect of the character modeling structure and skin material rendering effect of different test groups, the differences of different design methods are compared.

### 3.2.3. Head Modeling Design Effect
The verification process of the head modeling design effect is basically the same as that of the hand modeling design effect, but the verification parts are different.

### 3.2.4. Time-Consuming Verification of Modeling Design
Due to the large demand for multirole virtual character modeling, there are strict requirements on the design time, so the verification time of various methods is compared.

### 3.2.5. Modeling Design Score
According to the design results of different methods, ten experts of relevant disciplines are invited to score the design results for 10 times, and the average value of the results of 10 times is taken. The scoring method is the percentage system.

The comparison methods used include the character virtual modeling design method based on VR technology proposed in Literature [8], the character virtual modeling design method based on parameter mode SMPL proposed in Literature [9], the character virtual modeling design method based on the mobile platform proposed in Literature [10], the character virtual modeling design method based on a computer diagram proposed in Literature [11], and the character virtual modeling design method based on deep and enhanced target parameter learning proposed in Literature [12].

### 3.3. Results and Discussion

#### 3.3.1. Positioning Coverage Effect Test
The positioning coverage effect test results of the six methods are shown in Figure 5.

According to Figure 5, there are different degrees of gaps in the data coverage of the five traditional design methods, which shows that there are data leakage points in these methods when scanning and positioning human structure.
information, which affects the subsequent generation effect of virtual character 3D modeling. The data coverage of this method is not blank, which shows that the scanning data obtained under the support of a wireless sensor network positioning algorithm is complete and can cover the whole scanning area, which provides more data support for generating virtual character 3D modeling.

3.3.2. Comparison of the 3D Hand Structure Effect. The structure of human fingers is the most complex, because each human hand is composed of five fingers and one palm. In addition, human fingers have many joints and are very flexible. Therefore, there are some difficulties in 3D modeling design. Figure 6 shows the design effect of 3D modeling of human hands.

According to Figure 6, for the hand 3D modeling designed under 5 groups of traditional positioning technologies, there are problems such as adhesion and truncation between finger structures, which corresponds to the positioning coverage of the human body structure in Figure 5. Only with the help of wireless sensor network positioning, the method in this paper matches the different position information of the hand to the corresponding position according to the more comprehensive positioning information, so as to obtain the 3D design effect similar to the real hand.

3.3.3. Comparison of Hand Modeling Rendering Effect. Considering the design concept of virtual communication, on the basis of completing the overall 3D modeling design, the skin material rendering effects of six groups of methods on virtual character modeling are compared. It is shown in Figure 7.

According to the test results shown in Figure 7, when rendering 3D modeling of the human head in the first two methods, 3D collapse occurs in human eyes and nose. The third, fourth, and fifth groups of methods have some problems, such as missing eyebrows, too thin eyebrows, lack of facial lines, lack of spots, and wrong color matching. Based on the design of virtual communication, the head shape is complete, the color matching is correct, and the spots and wrinkles are obvious. From the above test results, the 3D modeling rendering effect based on the design of virtual communication is the best.

3.3.4. Comparison of Time-Consuming Comparison of Modeling Design. The comparison results of modeling design time consumption of the six methods are shown in Figure 8. It can be seen from the design results shown in Figure 8 that under multiple experiments, the modeling design time of this method is always lower than that of the literature comparison method in 5, and the maximum time is no more than 35 min.

3.3.5. Comparison Results of Modeling Design Scores. The scoring results of the six methods are shown in Table 2.

As can be seen from the scoring results shown in Table 2, the expert scores of this method are higher than those of the other five comparison methods, and the average score is 99.6. Therefore, it shows that the 3D modeling design effect designed by this method can be recognized more.

4. Conclusions

The 3D modeling design method in this study gives full play to the technical characteristics of wireless sensor networks and virtual communication and generates 3D modeling of people with different poses through mode switching of different skin algorithms. The performance of the method is verified from both theoretical and experimental aspects. In the modeling design of multirole virtual characters, the coverage of human data acquisition is enhanced through wireless sensor networks. Virtual communication technology is used to effectively render the human body modeling, which can improve the design effect, shorten the design time, and better meet the requirements of a multirole virtual character modeling design. However, there are a lot of calculation steps in this design, so the overall design efficiency may not be high, affecting the design speed of modeling. In the future, we can optimize the positioning of wireless sensor networks, strengthen the adaptability of positioning and scanning, and speed up the overall progress of modeling design.

Data Availability

The data used to support the findings of this study are included within the article. Readers can access the data supporting the conclusions of the study from iCartoonFace and the Danbooru2018 data set.

Conflicts of Interest

The authors declare that there is no conflict of interest with any financial organizations regarding the material reported in this manuscript.

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