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STRESS-STRAIN STATE OF THICK-WALLED ANISOTROPIC CYLINDRICAL SHELLS UNDER THERMAL POWER LOAD, PROTECTED BY THE FUNCTIONALLY GRADED MATERIAL

M.P. Semenyuk¹, Dr. Eng.
V.M. Trach², Dr. Eng.
A.V. Podvornyï², PhD (Engineering)

¹Institute of Mechanics of the National Academy of Sciences of Ukraine, Kyiv, Petra Nesterova str., 3, 02000
²National University of Water and Environmental Engineering, Rivne, Soborna str., 11, 33028

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In the article the stress-strain state of thick-walled structurally anisotropic composite cylindrical shells under thermal power load, which are protected by a functionally graded material, are analysed. Based on the interrelations of the spatial theory of elasticity, a system of inhomogeneous differential equations in three-dimensional formulation, which describes the stress-strain state of thick-walled anisotropic cylindrical shells, was obtained. To reduce the dimensionality of this system, the Bubnov-Galerkin analytical method was used. Thus, the obtained one-dimensional system of twelve equations of normal Cauchy form was implemented using the numerical method of discrete orthogonalization. To represent the possibilities of the proposed approach, there were used stress-strain states of two, four and five-layered anisotropic cylindrical shells of fibrous composites, protected from temperature by a layer of transversely isotropic functionally graded material.

Key words: thick-walled anisotropic cylindrical shell, stress-strain state, three-dimensional formulation, functionally graded material.

1. Introduction

Thin-walled structures made of composite materials are widely used in a variety of elements of up-to-date equipment. For example, the aerospace and rocket industries require the use of shells made of lightweight, high-strength composite materials. Unfortunately, traditional composite materials are not always able to be used in high temperatures, because their load-bearing capacity can be significantly reduced. Heat-resistant ceramics can be used to protect thin-walled composites from temperatures, but it is well known that this material has brittle properties and does not bend and twist.

Relatively recently, a new class of composite materials known as functionally graded materials (FGMs) has emerged [16]. Typical FGMs is an inhomogeneous composite made of different phases of material components (usually ceramics and metal). FGMs ceramic components are able to withstand high-temperature environments due to the better heat resistance characteristics, and metal components provide higher mechanical properties and reduce the...
possibility of destruction. Thus, the use of FGMs can help to protect the shell structure from the effects of variable temperature fields, which will allow the structure to absorb the load without reducing its strength, for instance.

At present, a sufficiently detailed analysis of the stress-strain state of thin-walled and thick-walled cylindrical shells of both conventional composites and FGMs in the calculations of two-dimensional systems under the thermal power load [1, 3, 12, 15, 16, 17] is made. In this paper, the change of the characteristics of the stress-strain state in the thickness of the structure is modeled by hypotheses of varying degrees of accuracy. It is generally known that to calculate the stress-strain state of thick-walled cylindrical shells it should be applied an approach [2, 6, 7, 10, 11, 13], based on the use of equations of the spatial theory of elasticity and which allows you to correctly analyze changes of parameters such as stress-strain state of the construction by the thickness.

The authors propose an approach to the establishment of the stress-strain state of a thick layered anisotropic cylindrical shell made of a fibrous composite, which is made at an angle to the generatrix, and a layer of FGMs. It is also necessary to take into account the effect of anisotropy caused by the discrepancy between the directions of reinforcement and the shell axes (Fig. 1) [1, 2, 3, 6, 7, 10, 11, 13, 14], and to assess the impact of temperature on such a combined structure thickness.

In this paper a three-dimensional theory of elasticity is used to solve the problem of the stress-strain state of a thick-walled anisotropic cylindrical shell made of fibrous composites [5]. The obtained solutions can serve as references in the calculations of stress-strain states of thin-walled structures of more complex geometry established, for example, when using the finite element method.

2. Formulation of the problem
Linear equilibrium equations in non-axisymmetric stress-strain state for each i-th layer are as follows [5]:

\[
\frac{\partial \sigma_{rr}^i}{\partial r} = -\frac{1}{r} \left[ \sigma_{rr}^i + r \frac{\partial}{\partial r} (\tau_{r\theta}^i) + \frac{\partial}{\partial \theta} (\tau_{\theta r}^i) \right] - \sigma_{00}^i + r F_r^i;
\]
\[
\frac{\partial \tau_{rz}^i}{\partial r} = -\frac{1}{r} \left[ \tau_{rz}^i + r \frac{\partial}{\partial z} \left( \sigma_{zz}^i \right) + \frac{\partial}{\partial \theta} \left( \tau_{r\theta}^i \right) + r F_{z}^i \right]; \\
\frac{\partial \tau_{r\theta}^i}{\partial r} = -\frac{1}{r} \left[ \tau_{r\theta}^i + \tau_{r\theta}^i + r \frac{\partial}{\partial z} \left( \tau_{z\theta}^i \right) + \frac{\partial}{\partial \theta} \left( \sigma_{\theta\theta}^i \right) + r F_{\theta}^i \right], 
\]
(1)

where \( r_i \) (i=1,2) – radius of the cylinder, which does not depend on the coordinates \( z \) and \( \theta \); \( \sigma_{zz}^i, \sigma_{rr}^i, \sigma_{\theta\theta}^i, \tau_{rz}^i, \tau_{r\theta}^i, \tau_{z\theta}^i \) – components of the stress tensor, \( F_r, F_z, F_\theta \) – vector projections of specific volume forces on the directions tangent to the coordinate lines \( r, z, \theta \).

The relationship between the components of deformation and displacement will take the form:

\[
e_{zz}^i = \frac{\partial u_{zz}^i}{\partial z}; \quad e_{r\theta}^i = \frac{1}{r} \frac{\partial u_{r\theta}^i}{\partial \theta} + \frac{1}{r} u_{r \theta}^i; \quad e_{rr}^i = \frac{\partial u_{r\theta}^i}{\partial r}; \\
e_{z\theta}^i = \frac{\partial u_{z\theta}^i}{\partial z}; \quad e_{rz}^i = \frac{1}{r} \frac{\partial u_{rz}^i}{\partial r} + \frac{1}{r} u_{r z}^i; \quad e_{r\theta}^i = \frac{\partial u_{r\theta}^i}{\partial \theta} - \frac{1}{r} u_{\theta \theta}^i + \frac{1}{r} \frac{\partial u_{r \theta}^i}{\partial \theta}.
\]
(2)

And \( u_{z}^i, u_{\theta}^i, u_{r}^i \) – displacement in the direction of the axes \( z, \theta, r \) respectively; \( e_{zz}^i, e_{r\theta}^i, e_{rr}^i \) – relative linear deformations in the directions of the coordinate axes \( z, \theta, r \); \( e_{z\theta}^i, e_{rz}^i, e_{r\theta}^i \) – relative tangential displacements at the point to the corresponding coordinate surfaces.

The ratios of the generalized Hooke's law, which connect the components of deformations and stresses, when the axes of orthotropy with the coordinate axes are coincident:

\[
e_{zz}^i = a_{11}^i \sigma_{zz}^i + a_{12}^i \sigma_{\theta\theta}^i + a_{13}^i \sigma_{rr}^i; \\
e_{r\theta}^i = a_{12}^i \sigma_{zz}^i + a_{22}^i \sigma_{\theta\theta}^i + a_{23}^i \sigma_{rr}^i; \\
e_{rr}^i = a_{13}^i \sigma_{zz}^i + a_{33}^i \sigma_{\theta\theta}^i + a_{33}^i \sigma_{rr}^i; \\
e_{r\theta}^i = a_{44}^i \tau_{r\theta}^i; \\
e_{rz}^i = a_{55}^i \tau_{r\theta}^i; \\
e_{z\theta}^i = a_{66}^i \tau_{z\theta}^i.
\]
(3)

When rotating the axes of orthotropy relative to the \( z \) axis, these dependencies take the form:

\[
e_{zz}^i = a_{11}^i \sigma_{zz}^i + a_{12}^i \sigma_{\theta\theta}^i + a_{13}^i \sigma_{rr}^i + a_{16}^i \tau_{z\theta}^i; \\
e_{r\theta}^i = a_{12}^i \sigma_{zz}^i + a_{22}^i \sigma_{\theta\theta}^i + a_{23}^i \sigma_{rr}^i + a_{26}^i \tau_{z\theta}^i; \\
e_{rr}^i = a_{13}^i \sigma_{zz}^i + a_{33}^i \sigma_{\theta\theta}^i + a_{33}^i \sigma_{rr}^i + a_{36}^i \tau_{z\theta}^i; \\
e_{r\theta}^i = a_{44}^i \tau_{r\theta}^i + a_{45}^i \tau_{r\theta}^i; \\
e_{rz}^i = a_{45}^i \tau_{r\theta}^i + a_{55}^i \tau_{r\theta}^i; \\
e_{z\theta}^i = a_{66}^i \tau_{r\theta}^i; \\
e_{z\theta}^i = a_{66}^i \tau_{z\theta}^i.
\]
(4)

In the equations (3, 4) \( a_{kl}^i \) and \( a_{kl}^i \) – are mechanical constants of the \( i \)-th layer of orthotropic material and material with one plane of elastic symmetry, the relationship between which is established in [4].
3. Research methodology

The relation of the generalized Hooke's law for a material with one plane of elastic symmetry (4) takes the form [2], which is used in the solution of the system (1):

\[ \sigma_{zz}^i = b_{11}^i \epsilon_{zz}^i + b_{12}^i \epsilon_{\theta\theta}^i + b_{16}^i \epsilon_{\varphi\varphi}^i + c_1^i \sigma_{rr}^i + \beta_{11}^i T ; \]

\[ \sigma_{\theta\theta}^i = b_{12}^i \epsilon_{zz}^i + b_{22}^i \epsilon_{\theta\theta}^i + b_{26}^i \epsilon_{\varphi\varphi}^i + c_2^i \sigma_{rr}^i + \beta_{22}^i T ; \]

\[ \tau_{z\theta}^i = b_{16}^i \epsilon_{zz}^i + b_{26}^i \epsilon_{\theta\theta}^i + b_{66}^i \epsilon_{\varphi\varphi}^i + c_1^i \sigma_{rr}^i + \beta_{12}^i T ; \]

\[ e_{rr}^i = c_1^i \epsilon_{zz}^i - c_2^i \epsilon_{\theta\theta}^i - c_4^i \epsilon_{\varphi\varphi}^i + c_4^i \sigma_{rr}^i + \alpha_{33}^i T + a_{13}^i \beta_{11}^i T + a_{23}^i \beta_{22}^i T + a_{36}^i \beta_{12}^i T ; \]

\[ e_{z\theta}^i = a_{45}^i \tau_{z\theta}^i + a_{55}^i \tau_{z\theta}^i + \alpha_{13}^i T ; \]

\[ e_{\theta\theta}^i = a_{44}^i \tau_{\theta\theta}^i + a_{45}^i \tau_{\theta\theta}^i + \alpha_{23}^i T ; \]

where \( b_{kl}^i \) (\( k,l=1,2,6 \)), \( c_k^i \) (\( k = 1 + 4 \)) – are the characteristics of the \( i \)-th layer that are determined by the mechanical constants \( a_{kl}^i \) of the shell material; \( \beta_{11}^i \), \( \beta_{22}^i \), \( \beta_{12}^i \) – are the components of the stress-strain state of the \( i \)-th layer, related with the temperature dependences \( T(0)\):

\[ \beta_{11}^i T = -(b_{11}^i \alpha_{11}^i + b_{12}^i \alpha_{22}^i + b_{16}^i \alpha_{12}^i) T ; \]

\[ \beta_{22}^i T = -(b_{12}^i \alpha_{11}^i + b_{22}^i \alpha_{22}^i + b_{26}^i \alpha_{12}^i) T ; \]

\[ \beta_{12}^i T = -(b_{16}^i \alpha_{11}^i + b_{26}^i \alpha_{22}^i + b_{66}^i \alpha_{12}^i) T . \]

In this system of equations and in (5) \( \alpha_{ij}^i (i,j=1+3) \) – are the coefficients of linear thermal expansion of the material of the \( i \)-th shell layer.

Replacing in (5) the deformations \( \epsilon_{zz}^i \), \( \epsilon_{\theta\theta}^i \), \( \epsilon_{z\theta}^i \) by their expressions from (2) and substituting the obtained dependences for \( \sigma_{zz}^i \), \( \sigma_{\theta\theta}^i \), \( \tau_{z\theta}^i \) in (1), and for \( e_{rr}^i \), \( e_{z\theta}^i \), \( e_{\theta\theta}^i \) in (2) we obtain for each \( i \)-th layer a complete system of differential equations in partial derivatives, in which we take into account that the shell is deformed according to the axial symmetry:

\[ \frac{\partial \sigma_{rr}^i}{\partial r} = c_2^i \frac{1}{r} \sigma_{rr}^i - \frac{\partial \tau_{z\theta}^i}{\partial z} + \frac{b_{12}^i}{r} u_r^i + \frac{b_{12}^i}{r} \frac{\partial u_r^i}{\partial z} + \frac{b_{26}^i}{r} \frac{\partial u_\theta^i}{\partial z} - \frac{b_{12}^i}{r} \alpha_{11}^i T - \frac{b_{26}^i}{r} \alpha_{22}^i T - \frac{b_{26}^i}{r} \alpha_{12}^i T ; \]

\[ \frac{\partial \tau_{z\theta}^i}{\partial r} = -c_1^i \frac{\partial \sigma_{rr}^i}{\partial z} - \frac{1}{r} \tau_{z\theta}^i - \frac{b_{12}^i}{r} \frac{\partial u_r^i}{\partial z} - \frac{b_{11}^i}{r} \frac{\partial^2 u_r^i}{\partial z^2} - \frac{b_{16}^i}{r} \frac{\partial^2 u_\theta^i}{\partial z^2} + \frac{b_{11}^i}{r} \alpha_{11}^i \frac{dT}{dz} + \]

\[ + \frac{b_{12}^i}{r} \alpha_{22}^i \frac{dT}{dz} + \frac{b_{16}^i}{r} \alpha_{12}^i \frac{dT}{dz} ; \]
The solution of the system (7) must correspond to the conditions on the side surfaces at \( r = \eta_1 \), \( r = \eta_2 \):

\[
\begin{align*}
\sigma_{rr}^1 (\eta_1, z) &= \pm q_1^1 (z) ; & \tau_{rz}^1 (\eta_1, z) &= 0 ; & \tau_{r\theta}^1 (\eta_1, z) &= 0 ; \\
\sigma_{rr}^2 (\eta_2, z) &= \pm q_2^1 (z) ; & \tau_{rz}^2 (\eta_2, z) &= 0 ; & \tau_{r\theta}^2 (\eta_2, z) &= 0 ,
\end{align*}
\]

conditions at the ends are \( z = 0 \), \( z = L \).
\[ \sigma_{zz}^i = u_r^i = u_\theta^i = 0 \]  
\( (9) \)

and the conditions of hard contact of the layers:

\[ \sigma_{rr}^i (r_i) = \sigma_{rr}^{i+1} (r_i); \quad \tau_{rz}^i (r_i) = \tau_{rz}^{i+1} (r_i); \quad \tau_{r\theta}^i (r_i) = \tau_{r\theta}^{i+1} (r_i); \]
\[ u_r^i (r_i) = u_r^{i+1} (r_i); \quad u_z^i (r_i) = u_z^{i+1} (r_i); \quad u_\theta^i (r_i) = u_\theta^{i+1} (r_i). \]  
\( (10) \)

There is a diaphragm, which is absolutely rigid in its plane and flexible, at the edges of the cylinder in conditions (9). In (8) \( q_r (z), q_r^2 (z) \) - an internal and external pressure is distributed on the side surfaces of the shell, respectively.

To solve the three-dimensional problem (7) and (8-9), we use the Bubnov-Galerkin methodology. According to it, we decompose all functions into trigonometric series on the coordinate along the cylinder generatrix \( z \), so that they would satisfy the boundary conditions (9):

\[ \sigma_{rr}^i (r,z) = \sum_{m=1}^{\infty} \left[ y_{1,p}^i (r) + y_{1,m}^i (r) \right] \sin m z; \]
\[ \tau_{rz}^i (r,z) = \sum_{m=0}^{\infty} \left[ y_{2,p}^i (r) + y_{2,m}^i (r) \right] \cos m z; \]
\[ \tau_{r\theta}^i (r,z) = \sum_{m=1}^{\infty} \left[ y_{3,p}^i (r) + y_{3,m}^i (r) \right] \sin m z; \]
\[ u_r^i (r,z) = \sum_{m=1}^{\infty} \left[ y_{4,p}^i (r) + y_{4,m}^i (r) \right] \sin m z; \]
\[ u_z^i (r,z) = \sum_{m=0}^{\infty} \left[ y_{5,p}^i (r) + y_{5,m}^i (r) \right] \cos m z; \]
\[ u_\theta^i (r,z) = \sum_{m=1}^{\infty} \left[ y_{6,p}^i (r) + y_{6,m}^i (r) \right] \sin m z, \]
\( (11) \)

where \( y_{i,pk}, y_{i,mk} \ (i = 1,6) \) – are the components of expansion into trigonometric Fourier series of components of the stress-strain state of shell, \( p, m \) – are the wave numbers in the series.

After some mathematical transformations and separation of variables in equations (7) using the ratios (11), we obtain for each \( i \)-th layer a system of differential equations of the twelfth order in the normal Cauchy form

\[ \frac{d y^i}{d r} = T^i (r) \bar{y}^i + f^i, \quad T^i (r) = t_{n,i}^l (r), \quad n,l = 1 + 12, \]  
\( (12) \)

where

\[ \bar{y}^i = \left[ y_{1,p}, y_2, y_{3,p}, y_{3,m}, y_{4,p}, y_{4,m}, y_{5,p}, y_{5,m}, y_{6,p}, y_{6,m} \right] - \text{solving vector function. Non-zero elements of which are written in accordance with } [6,11], t_{n,i}^l (r) - \text{coefficients for unknown systems (7), } f^i - \text{the components of the stress-strain state related to the temperature in the system (7) and are determined as:} \]
Implementation of the obtained one-dimensional problem on the stress-strain state of a thick-walled cylinder was carried out using the numerical method of discrete orthogonalization [3]. After solving the system (12) taking into account the boundary conditions (8), ratios (11) were used for the transition from the obtained functions to the components of the stress-strain state.

4. Results of the numerical calculations and their analysis

The object of the study is a cylindrical shell made of layers of fibrous boroplastic material and a layer of functionally graded material [16] under the distributed external pressure and external constant temperature. Silicone nitride was chosen as the ceramic component of FGMs, and titanium (Ti-6Al-4V) was chosen as the metal component. The temperature distribution along thickness of the cylinder was determined according to [9, 16]. Physical and mechanical properties of the functionally graded component of the cylinder dependent on the temperature were determined in the tables 1–4 [12] and according to the dependences [18]:

\[
E = P_{0E} \cdot \left( P_{-1E} T^{-1} + 1 + P_{1E} T + P_{2E} T^2 + P_{3E} T^3 \right); \\
\nu = P_{0\nu} \cdot \left( P_{-1\nu} T^{-1} + 1 + P_{1\nu} T + P_{2\nu} T^2 + P_{3\nu} T^3 \right), \\
\alpha = P_{0\alpha} \cdot \left( P_{-1\alpha} T^{-1} + 1 + P_{1\alpha} T + P_{2\alpha} T^2 + P_{3\alpha} T^3 \right); \\
\kappa = P_{0\kappa} \cdot \left( P_{-1\kappa} T^{-1} + 1 + P_{1\kappa} T + P_{2\kappa} T^2 + P_{3\kappa} T^3 \right),
\]

where \( E \) – the desired modulus of elasticity, \( \nu \) – Poisson's ratio, \( \alpha \) – coefficient of linear thermal expansion and \( \kappa \) – thermal conductivity, the given temperature \( T(0) \), and \( P_{0E}, P_{0\nu}, P_{0\alpha}, P_{0\kappa} \) – the desired characteristics of the material, when \( T=0(0) \), \( P_{iE}, P_{i\nu}, P_{i\alpha}, P_{i\kappa} \) – are given in the tables 1–4.

### Table 1

Modulus of elasticity of ceramics and metal, Pa

| Material                  | \( P_{0E} \)        | \( P_{-1E} \)      | \( P_{1E} \) | \( P_{2E} \) | \( P_{3E} \) |
|---------------------------|---------------------|--------------------|--------------|--------------|--------------|
| Silicone nitride          | 348.43*10^9         | 0                  | -3.070*10^{-4}| 2.160*10^{-7}| -8.946*10^{-11}|
| Titanium alloy (Ti-6Al-4V)| 122.56*10^9         | 0                  | -4.586*10^{-4}| 0            | 0            |
Table 2

Poisson's ratios of ceramics and metal

| Material                      | $P_{0v}$ | $P_{1v}$ | $P_{2v}$ | $P_{3v}$ |
|-------------------------------|----------|----------|----------|----------|
| Silicone nitride              | 0.24     | 0        | 0        | 0        |
| Titanium alloy (Ti-6Al-4V)    | 0.2884   | 0        | 1.121*10^{-4} | 0        |

Table 3

Coefficient of linear thermal expansion of ceramics and metal, $\alpha^0 K^{-1}$

| Material                      | $P_{0a}$ | $P_{1a}$ | $P_{2a}$ | $P_{3a}$ |
|-------------------------------|----------|----------|----------|----------|
| Silicone nitride              | 5.8723*10^{-6} | 0        | 9.095*10^{-4} | 0        |
| Titanium alloy (Ti-6Al-4V)    | 7.5788*10^{-6} | 0        | 6.638*10^{-4} | -3.147*10^{-6} |

Table 4

Thermal conductivity of ceramics and metal, $W / (m^0K)$

| Material                      | $P_{0k}$ | $P_{1k}$ | $P_{2k}$ | $P_{3k}$ |
|-------------------------------|----------|----------|----------|----------|
| Silicone nitride              | 13.723   | 0        | -1.032*10^{-3} | 5.466*10^{-7} |
| Titanium alloy (Ti-6Al-4V)    | 1.000    | 0        | 1.704*10^{-2} | 0        |

Boroplastics has the following mechanical characteristics:

$E_{11}=28*10^5$ MPa, $E_{22}=E_{33}=3.1*10^5$ MPa, $G_{12}=G_{23}=1.05*10^5$ MPa,

$G_{13}=2.12*10^5$ MPa, $v_{21}=0.25$, $v_{12}=0.0277$.

Common characteristics of the functionally graded materials were determined in accordance with [8]:

$$E(\xi) = (E_c - E_m)(\xi/h)^N + E_m;$$

$$\nu(\xi) = (\nu_c - \nu_m)(\xi/h)^N + \nu_m;$$

$$\alpha(\xi) = (\alpha_c - \alpha_m)(\xi/h)^N + \alpha_m;$$

$$\kappa(\xi) = (\kappa_c - \kappa_m)(\xi/h)^N + \kappa_m,$$

(14)

where $E(\xi), \nu(\xi), \alpha(\xi), \kappa(\xi)$ – physical and mechanical characteristics of the common material by thickness, $E_m, \nu_m, \alpha_m, \kappa_m$ – mechanical characteristics of metal (titanium alloy), $E_c, \nu_c, \alpha_c, \kappa_c$ – mechanical characteristics of ceramics (zirconium), $h$ – the thickness of the functionally graded component of the shell material, $\xi$ – thickness coordinate $\xi = r - r_1$, $r$ – the coordinate of an arbitrary point in the shell general coordinate system, fig. 1, $r_1$ – the
coordinate of the cylinder inner surface, $N$ – volume fraction of mixed materials [16].

A cylindrical shell with the following geometric parameters was considered (fig. 1): $L=1.2$ m, $r_1=0.57$ m, $r_2=0.63$ cm, $h=0.06$ m. Three variants of a thick-walled cylindrical shell were calculated. The first one took into the consideration only power load, and then combined power and thermal load. In this case, the temperature field changed only according to the thickness of the layer of functionally graded material.

In the first variant of this structure, it was assumed that the cylinder consists of two layers: the inner $r_1=0.57$ m, $r_1=0.6$ m – made of boroplastic material with reinforcement angle $\psi=70^0$ to the axes $z$ and the external $r_0=0.6$ m, $r_2=0.63$ m – made of functionally graded material, when $N=1$ (titanium alloy Ti-6Al-4V($r_{02}$) – silicone nitride ($r_2$)).

In the second variant, the shell was consisted of three layers: two internal cross-enclosed with reinforcement angles $\psi=\pm 70^0$ to the axis $z$, made of boroplastic material $r_1=0.57$ m, $r_{11}=0.585$ m ($\psi=70^0$) and $r_{21}=0.585$ m, $r_{22}=0.6$ m ($\psi=-70^0$) and external layer $r_{02}=0.6$ m, $r_2=0.63$ m – made of functionally graded material, when $N=1$ (titanium alloy Ti-6Al-4V($r_{02}$) – silicone nitride ($r_2$)).

In the third variant, the shell was consisted of five layers: four internal cross-enclosed with reinforcement angles $\psi=\pm 70^0$ to the axis $z$, made of boroplastic material $r_1=0.57$ m, $r_{11}=0.5775$ m ($\psi=70^0$) and $r_{21}=0.5775$ m, $r_{22}=0.585$ m ($\psi=-70^0$), $r_{31}=0.585$ m, $r_{32}=0.5925$ m ($\psi=70^0$) and $r_{41}=0.5925$ m, $r_{42}=0.6$ m ($\psi=-70^0$) and the external layer $r_{02}=0.6$ m, $r_2=0.63$ m – made of functionally graded material, when $N=1$ (titanium alloy Ti-6Al-4V($r_{02}$) – silicone nitride ($r_2$)).

All presented variants of shell structures were under pressure load that was distributed on the external surface $q=-q_0 \sin (\pi z/L)$, where $q_0=100$ MPa. In the case of joint power and thermal load, the temperature field changed only by the thickness of the functionally graded component of the material from $T=293^0K$ ($20^0C$), when $r_{02}=0.6$ m, to $T=373^0K$ ($100^0C$), when $r_2=0.63$ m for all three variants of the cylindrical shell, and distributed by thickness according to the law presented in [9].

Fig. 2-4 show the change of stress-strain components of the shells with one layer of boroplastic, that is curve 1 (solid), with two and four layers, i.e curve 2 (dashed) and curve 3 (dotted), respectively. The calculation results are given by the coordinate $r$ for the cross-section that is on the middle of generatrix, i.e, when $z=0.5L$. 
The analysis results of calculations in Fig. 2-4 describe the stress-strain state of the layered thick-walled anisotropic composite shells and show that the variable temperature field of the functionally graded component of the shell material within the studied temperatures ranges from $T=293^0K (20^0C)$, when $r=0.6$ m to $T=373^0K (100^0C)$, when $r=0.63$ m and does not significantly affect...
the stress-strain state of a thick-walled anisotropic cylinder. However, it should be noted that variable temperature field and distributed lateral pressure (fig. 2b) effects that the values of normal stresses are slightly, up to 5%, higher compared with those, which are under power load only (fig. 2a).

The graphs presented in figs. 3a and 3b indicate that the cross-laying of fibrous material allows reducing the value of the tangential stresses \( \tau_{rz} \) compared to one layered of the composite. This is especially evident in the example of the thickness distribution of the tangential stresses \( \tau_{r\theta} \) in figs. 4a and 4b, which appear only in anisotropic material. There are anisotropic components of the stress-strain state \( \tau_{r\theta} \) for one composite layer in the transversely isotropic FGMs. However, for cross-ply composites having two and four layers the effect is almost absent.

5. Conclusions

In the article the numerical calculations of the stress-strain state of a thick-walled cylindrical anisotropic shell of fibrous composite material that is protected by a functionally graded material under power and thermal load, were conducted based on three-dimensional theory of elasticity. Variants of increasing the number of layers stacked so that their axes of orthotropy of fiber composites do not coincide with the axes of the cylinder coordinate system, creating the effect of a material with one plane of elastic symmetry, are analyzed. It is taken into account that the physical and mechanical properties of FGMs are dependent on temperature. It was found that the stress-strain state of a thick-walled anisotropic cylinder does not change significantly due to the action of high temperature, which is the effect of using FGMs to protect the cylindrical shell.

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Семенюк М.П., Трач В.М., Подворний А.В.
НАПРУЖЕНИЙ СТАН ТОВСТИХ АНІЗОТРОПНИХ ЦИЛІНДРИЧНИХ ОБОЛОНОК, ЗАХИЩЕННИХ ФУНКЦІОНАЛЬНО-ГРАДІЄНТНИМ МАТЕРІАЛОМ, ПІД ТЕРМОСИЛОВОЮ ДІЄЮ

В роботі приведений напружений стан товстих конструктивно-анізотропних композитних циліндричних оболонок, що захищені функціонально-градієнтним матеріалом, і знаходяться в полі термосильної дії. На основі співвідношень просторової теорії пружності отримана система неоднорідних диференціальних рівнянь в тривимірній постановці, що описує напружений стан товстих анізотропних циліндрів. Для понижения розмірності зазначеної системи, використано аналітичний метод Бубнова-Гальоркіна. Отриману, таким чином, одновимірну систему з дванадцяти рівнянь нормального виду Коші реалізовано за використанням чисельного методу дискретної ортогоналізації. В якості представлення можливостей запропонованого підходу приведені напружени стани дво, чотири і п’яті шаруватих анізотропних циліндричних оболонок, утворених з волокнистих композитів, що захищені, від дії температури, шаром трансверсально-ізотропного функціонально-градієнтного матеріалу.

Ключові слова: товстая анізотропна циліндрична оболонка, напружений стан, тривимірна постановка, функціонально-градієнтний матеріал.
In the article the stress-strain state of thick-walled structurally anisotropic composite cylindrical shells under thermal power load, which are protected by a functionally graded material, are analysed. Based on the interrelations of the spatial theory of elasticity, a system of inhomogeneous differential equations in three-dimensional formulation, which describes the stress-strain state of thick-walled anisotropic cylindrical shells, was obtained. To reduce the dimensionality of this system, the Bubnov-Galerkin analytical method was used. Thus, the obtained one-dimensional system of twelve equations of normal Cauchy form was implemented using the numerical method of discrete orthogonalization. To represent the possibilities of the proposed approach, there were used stress-strain states of two, four and five-layered anisotropic cylindrical shells of fibrous composites, protected from temperature by a layer of transversely-isotropic functionally-graded material.

Tabl. 4. Fig. 1. Ref. 18.
Автор (науковий ступінь, вчене звання, посада): доктор технічний наук, професор, провідний науковий співробітник СЕМЕНЮК Микола Павлович

Адреса робоча: 02000 Україна, м. Київ, вул. Петра Нестерова, 3, Інститут механіки НАН України, СЕМЕНЮКУ Миколі Павловичу

Контактний тел. +38098-106-06-49
E-mail: mikolasem@ukr.net
ORCID ID: http://orcid.org/0000-0001-5711-4277

Автор (науковий ступінь, вчене звання, посада): доктор технічний наук, професор, завідувач кафедри мостів і тунелів, опору матеріалів і будівельної механіки ТРАЧ Володимир Мирославович

Адреса робоча: 33028 Україна, м. Рівне, вул. Соборна, 11, Національний університет водного господарства та природокористування, ТРАЧУ Володимиру Мирославовичу

Контактний тел. +38097-289-15-80
E-mail: trach-vm@ukr.net
ORCID ID: http://orcid.org/0000-0001-9500-2743

Автор (науковий ступінь, вчене звання, посада): кандидат технічний наук, доцент кафедри мостів і тунелів, опору матеріалів і будівельної механіки ПОДВОРНИЙ Андрій Володимирович

Адреса робоча: 33028 Україна, м. Рівне, вул. Соборна, 11, Національний університет водного господарства та природокористування, ПОДВОРНОМУ Андрію Володимировичу

Контактний тел. +38096-411-12-87
E-mail: andrei_podvornyi@ukr.net
ORCID ID: http://orcid.org/0000-0001-8518-4395