CONFORMAL PERTURBATIONS AND LOCAL SMOOTHING

HANS CHRISTIANSON AND DYLAN MUCKERMAN

Abstract. The purpose of this paper is to study the effect of conformal perturbations on the local smoothing effect for the Schrödinger equation on surfaces of revolution. The paper [CW13] studied the Schrödinger equation on surfaces of revolution with one trapped orbit. The dynamics near this trapping were unstable, but degenerately so. Beginning from the metric $g$ from this paper, we consider the perturbed metric $g_s = e^{sf}g$, where $f$ is a smooth, compactly supported function. If $s$ is small enough and finitely many derivatives of $f$ satisfy appropriate symbolic estimates, then we show that a local smoothing estimate still holds.

1. Introduction and Statement of Results

Local smoothing estimates for solutions to the Schrödinger equation are estimates that use the infinite propagation speed to see high-frequency wave packets leave a compact region faster than low-frequency wave packets. In Euclidean space, the local smoothing result for the Schrödinger equation states that on average in time, and locally in space, solutions to the Schrödinger equation gain half a derivative compared to their initial data. More precisely, for every $T > 0$ there exists $C_T > 0$ such that if $u$ solves

$$\begin{cases}
(D_t - \Delta)u = 0 \\
u|_{t=0} = u_0,
\end{cases}$$

then

$$\int_0^T \| \langle r \rangle^{-3/2} \partial_r u \|^2 + \| \langle r \rangle^{-1/2} r^{-1} \nabla_{S^{n-1}} u \|^2 \, dt \leq C_T \| u_0 \|^2_{H^{1/2}},$$

for all $u_0 \in H^{1/2}$. Here we have used polar coordinates with $r$ the radial variable. Note that the spatial weights are not sharp.

The idea of local smoothing was first studied by Kato [Kat83] in the context of the KdV equation. Local smoothing for the linear Schrödinger equation and other dispersive type equations was studied by Constantin-Saut [CS88], Sjölin [Sjö87], Vega [Veg88], and Kato-Yajima [KY89]. Both [Sjö87] and [Veg88] made use of this inequality to prove that solutions of the Schrödinger equation converge pointwise almost everywhere to their initial data as $t \to 0$. We refer to [Tao06] and [CW13] for simple proofs of this estimate.

1.1. Local smoothing in the presence of trapping. One perspective on the local smoothing effect is that it arises from the dispersive nature of the Schrödinger equation. In particular, high frequency parts of solutions to the Schrödinger equation have higher velocity. By looking locally at solutions, we see “less” of the high frequency part of our solution, and this is what is responsible for the local smoothing. In Euclidean space,
where the geodesics are straight lines, this is easy to visualize, and the $1/2$ derivative gain in the local smoothing estimate makes this idea rigorous. On the other hand, on a compact manifold, wave packets have no where to escape so no local smoothing is expected.

But many possibilities exist between Euclidean space and compact manifolds. According to our heuristic argument, the important property of Euclidean space is that every geodesic goes to infinity. In other words, there are no \textit{trapped} geodesics, where a trapped geodesic is a complete geodesic that remains in a compact set for all time.

The relationship between trapping and local smoothing was explored in \cite{Doi96}: On asymptotically Euclidean manifolds, solutions to the Schrödinger equation exhibit $1/2$ of a derivative of local smoothing if and only if the manifold has no trapped geodesics.

The next question which arises is to what degree the local smoothing effect still holds when a trapped set exists.

The results in \cite{Bur04}, \cite{Chr07}, \cite{Chr08}, \cite{Chr11}, and \cite{Dat09} showed that in the presence of non-degenerate hyperbolic trapping, for any $\epsilon > 0$, there is local smoothing of $1/2 - \epsilon$ derivatives for the Schrödinger equation.

\subsection*{Surfaces of Revolution.}

In \cite{CW13}, local smoothing is studied on a family of surfaces of revolution that have periodic geodesics which are unstable, but degenerately so. In other words, the curvature vanishes to some degree at the geodesic. The family of surfaces studied are given by rotating the curve

$$A(x) = (1 + x^{2m})^{1/2m},$$

where $m \geq 2$ is an integer. The local smoothing effect is then

$$\int_0^T \| \langle x \rangle^{-3/2} u \|^2_{H^1} dt \leq C(\| \langle D_\theta \rangle^{m/(m+1)} u_0 \|^2_{L^2} + \| \langle D_x \rangle^{1/2} u_0 \|^2_{L^2}).$$

In other words, we gain the full $1/2$ of a derivative of local smoothing in the $x$ direction, but we only gain $1/(m+1)$ derivatives of local smoothing in the $\theta$ direction. Note that as the trapping becomes more stable, the local smoothing gained in the $\theta$ direction goes to 0.

In \cite{CM14}, a similar result is proven for a related class of surfaces of revolution with inflection-transmission type trapping. It should be noted that the results of \cite{CW13} and \cite{CM14} are sharp and show that no better (lower) power of $\langle D_\theta \rangle$ is possible.

Finally, \cite{Chr18} gives details of the connection between resolvent estimates for the Laplacian and local smoothing, and a detailed exposition of how the results obtained in \cite{CW13} and \cite{CM14} can be combined via “gluing” to prove local smoothing results for a wide variety of warped product manifolds.

Similar results are also available for localized energy estimates for the wave equation on surfaces of revolution with degenerate trapping in \cite{BCM19}.

\subsection*{Conformal perturbations of surfaces of revolution.}

The previous results mentioned above essentially complete the study of local smoothing for the Schrödinger equation on surfaces of revolution (and warped product manifolds in general). All of these results are essentially 1 dimensional, thanks to the decomposition into Fourier modes. We study local smoothing on a family of surfaces which are conformal perturbations of the surfaces studied in \cite{CW13}. 
Recall that a surface of revolution is the manifold $M = \mathbb{R}_x \times \mathbb{R}_\theta / 2\pi \mathbb{Z}$ endowed with the metric 

$$g_0 = dx^2 + A^2(x)d\theta^2,$$

where $A > 0$. We consider conformal perturbations of this metric in which the metric is of the form 

$$g_s = e^{sf(x,\theta)}g_0,$$

where $f(x,\theta)$ is a smooth function, compactly supported in $x$. Note that 

$$\Delta g_s = e^{-sf}\Delta g_0.$$

We will work with the function $A$ given in [CW13]. Note that if $f$ depends only on $x$, then after the perturbation our surface retains its rotational symmetry and so is still a surface of revolution, though it is impractical to write down its metric explicitly in the standard form for surfaces of revolution.

If our perturbation function $f$ has appropriate conditions placed on it, one expects that it will have little effect on the dynamics near the trapped set and thus little effect on the local smoothing. In fact, it is reasonable to expect that the perturbation could make the dynamics less stable and thus lead to greater local smoothing, though this is beyond our scope.

**Theorem 1.1.** Let $\epsilon > 0$ and let $M = \mathbb{R}_x \times \mathbb{R}_\theta / 2\pi \mathbb{Z}$ endowed with the metric 

$$g = e^{sf(x,\theta)}(dx^2 + A^2(x)d\theta^2),$$

where 

$$A(x) = (1 + x^{2m})^{1/2m},$$
$m \in \mathbb{Z}$, $m \geq 2$, and $f \in C^\infty(M)$ is compactly supported in $x$ and satisfies
\[ |\partial_x^j \partial_\theta^k f| \leq C|x|^{2m-1} \]
for $x$ small and $j, k \leq N$ for sufficiently large $N = N(m, \epsilon)$ where $j + k \geq 1$. Let
\[ r = \frac{m}{m+1} + \epsilon. \]

Then for $s > 0$ sufficiently small, there exists $C_T > 0$ such that
\[ \int_0^T (\| \langle x \rangle^{-1} \partial_x u \|^2 + \| \langle x \rangle^{-3/2} \partial_\theta u \|^2) \, dt \leq C_T \| u_0 \|_{H^r}^2 \]
for all $u$ solving the Schrödinger equation
\[ \begin{cases} (D_t - \Delta_g) u = 0 \\ u|_{t=0} = u_0 \in S. \end{cases} \]

Remark. We have assumed that the initial data $u_0 \in S$ is Schwartz class to avoid any issues with integration by parts.

In the unperturbed case, there is a gain of
\[ \frac{1}{m+1} \]
derivatives, whereas in our case there is the gain of
\[ \frac{1}{m+1} - \epsilon \]
derivatives. This is because we have chosen to avoid the marginal calculus used in [CW13], in order to ensure gains (in terms of $\theta$ derivatives) in symbol expansions, so that the many extra terms introduced by the factor $e^{-sf}$ are easier to control.

Remark. Note that we do not require any bound on $f$ itself, only on its derivatives. We have stated the theorem in terms of $s > 0$, which is a convenience just to avoid excessive notation of $|s|$ every time we estimate. We have made no assumptions on the sign of the function $f$.

Remark. The intuitive reason for our condition on derivatives of $f$ is that in general the degenerate trapping found in the unperturbed manifold is unstable under perturbation, and could potentially be perturbed into much worse trapping, for which the result would not hold.

We also note that non-degenerate hyperbolic trapping is stable under perturbation, so there is no corresponding issue in that situation.

2. Notation and Preliminary Material

2.1. Notations and Conventions. We will use $C$ to denote a large constant which may change from line to line. We will similarly use $c$ to denote a small positive constant which may change from line to line. We use the bracket notation:
\[ \langle x \rangle^s = (1 + x^2)^{s/2}, \]
for any $s \in \mathbb{R}$, which is a smooth positive function and $\langle x \rangle^s \sim |x|^s$ at infinity.
2.1.1. Pseudodifferential Operators. Our outline of pseudodifferential operators will follow the presentation of [Zwo12], [Tay81], and [Tay13]. For the use of pseudodifferential operators on a circle with discrete frequency parameter, we follow [RT10].

We will work with the symbol classes $\mathcal{S}_\rho^m$, $\rho \geq 0$ originally defined in [Hör66], given by

$$\mathcal{S}_\rho^m = \{a \in C^\infty(\mathbb{R} \times \mathbb{R} \times S^1 \times \mathbb{Z}) : |\partial^\alpha_x \partial^\beta_y \partial^\gamma_\eta \partial^\delta_\theta a| \leq C_{\alpha,\beta,\gamma,\delta} \langle \xi \rangle^m - |\alpha| \rho \langle \eta \rangle - |\delta| \rho \},$$

where $\partial_\eta$ denotes a difference operator in $\eta$, defined by

$$\partial_\eta a(\cdot,\eta) = a(\cdot,\eta + 1) - a(\cdot,\eta).$$

In particular, we will work with a symbol supported only where $|\xi| \leq C|\eta|$, allowing us to transfer decay in $|\eta|$ to decay in $|\xi|$. We also point out that $\rho = 0$ is the “marginal case” where derivatives gain nothing. The marginal calculus was used in [CW13] to obtain a sharp result, but in this paper we will always have $\rho > 0$. It is unclear if this is necessary, or if the marginal calculus can be used in the present context.

Define

$$a^w u = \frac{1}{(2\pi)^2} \int_{\mathbb{R}^2} \int_{S^1} \sum_\eta e^{i(x-\tilde{x},\xi)+i(\theta-\tilde{\theta},\eta)} a \left( \frac{x + \tilde{x}}{2}, \frac{\theta + \tilde{\theta}}{2}, \xi, \eta \right) u(\tilde{x}, \tilde{\theta}) d\tilde{\theta} d\tilde{x} d\xi$$

The operator $a^w$ is a pseudodifferential operator obtained from taking the Weyl quantization of $a$. It should be noted that the Weyl quantization is just one choice of many quantizations. The function $a$ is said to be the symbol of the operator.

2.1.2. Symbol calculus. We review a few essential theorems of the symbol calculus.

**Theorem 2.1** (Calderon-Vaillancourt Theorem). If $a \in \mathcal{S}_0^0$ then the operator $a^w$ is bounded as an operator from $L^2$ to $L^2$.

This theorem is originally due to [CV71]. See Theorem 4.23 in [Zwo12] for another proof.

In fact, a more general theorem holds.

**Theorem 2.2.** If $a \in \mathcal{S}_0^m$ then the operator $a^w(x, D)$ is bounded as an operator from $H^{s+m}$ to $H^s$.

Quantization does not commute with composition. That is to say, the composition of two pseudodifferential operators is not the quantization of the product of their symbols. In fact, it is not immediately obvious that the composition of two pseudodifferential operators is a pseudodifferential operator. In fact, the following theorem holds.

**Theorem 2.3** (Theorem 4.18 in [Zwo12]). Let $a \in \mathcal{S}_\rho^m$, $b \in \mathcal{S}_\rho^\eta$. Let

$$A(D) = \frac{1}{2} (\langle D_\xi, D_y \rangle - \langle D_x, D_\eta \rangle).$$

Then

$$a^w(x, D) \circ b^w(x, D) = c^w(x, D)$$

for

$$c = a \# b := \sum_{k=0}^N \frac{k!}{k!} A(D)^k a(x, \xi) b(y, \eta) \bigg|_{x=y, \xi=\eta} + r,$$
where \( r \) is a symbol in \( S^{m+m-N}\rho \). Furthermore, the symbol \( c \) is in the class \( S^m + \tilde{m} - N\rho \).

In particular, we have the following Corollary.

**Corollary 2.4.** Let \( a \in S^m_\rho \), \( b \in S^{\tilde{m}}_\rho \). Then
\[
a \# b = ab + \frac{1}{2i} \{a, b\} + r,
\]
where \( r \in S^{m+\tilde{m}-2\rho} \).

This can be seen from the symbol expansion for the commutator of \( a^w \) and \( b^w \) using Theorem 2.3. Due to the symmetry of the Weyl quantization, the following holds.

**Corollary 2.5.** Let \( a \in S^m_\rho \), \( b \in S^{\tilde{m}}_\rho \). Then the commutator
\[
[a^w(x, D), b^w(x, D)] = c^w(x, D),
\]
where
\[
c = \frac{1}{i} \{a, b\} + r,
\]
and \( r \in S^{m+\tilde{m}-3\rho} \).

Note that we gain 3 in the symbol class of the remainder term, rather than the gain of 2 we may naively expect. See Theorem 4.12 in [Zwo12].

Another useful feature of the Weyl quantization is the following theorem.

**Theorem 2.6.** Let \( a \) be a real symbol. Then the operator \( a^w \) is essentially self-adjoint.

A final result we require is the Gårding inequality.

**Theorem 2.7.** Let \( a \in S^m_\rho \) with \( 0 \leq \rho \leq 1 \) and suppose
\[
\text{Re } a \geq C|\langle \xi, \eta \rangle|^m
\]
for \( |\langle \xi, \eta \rangle| \) large. Then for any \( m \in \mathbb{R} \) there exist \( C_1, C_2 \) such that for all \( u \in H^{m/2} \),
\[
\text{Re } \langle a^w u, u \rangle \geq C_1 \|u\|_{H^{m/2}}^2 - C_2 \|u\|_{H^{(m-\rho)/2}}^2.
\]

See Chapter 7, Theorem 6.1 in [Tay13] for a proof.

3. Positive Commutator

The Laplacian \( \Delta_{g_0} \) on the unperturbed metric is given by
\[
\Delta_{g_0} = \partial_x^2 + A^{-2}(x)\partial_\eta^2 + A^{-1}(x)A'(x)\partial_x.
\]

Define
\[
L_1 : L^2(X, dVol) \rightarrow L^2(X, dx d\theta)
\]
by
\[
L_1 u(x, \theta) = A^{1/2}(x)u(x, \theta)
\]
and define
\[
L_2 : L^2(e^{sf} dx d\theta) \rightarrow L^2(dx d\theta)
\]
by
\[
L_2 u(x, \theta) = e^{sf/2}u.
\]
Let \( \tilde{\Delta} = L_2 L_1 \Delta_g L_1^{-1} L_2^{-1} \). Let
\[
V_1(x) = \frac{1}{2} A''(x) A^{-1}(x) - \frac{1}{4} (A'(x))^2 A^{-2}(x)
\]
We compute \( \tilde{\Delta} \) explicitly and find
\[ R \text{ and } L \]
then
\[ Q \]
Let \( \tilde{\Delta} = B \) so that
\[ \| x \] are able to prove the local smoothing estimate away from
\[ Q \]
commuting the operator we are interested in,
\[ Q \]
Below we will commute with an operator
\[ B \]
we begin by making the same positive commutator argument as in [CW13]. By
\[ B \]

We begin by commuting the two operators to find
\[
\tilde{\Delta} u = e^{-sf/2} (\partial_x^2 + A^{-2} \partial_\theta^2) - V_1(x) \right) e^{-sf/2}
= e^{-sf} (\partial_x^2 + A^{-2} \partial_\theta^2)
+ e^{-sf} (-sf_x \partial_x - A^{-2} sf_\theta \partial_\theta - (s/2) f_{xx} + ((s/2) f_x)^2)
+ e^{-sf} (-A^{-2} (s/2) f_{\theta \theta} + A^{-2} (s/2) f_\theta)^2)
- e^{-sf} V_1(x).
\]
We note that
\[
(e^{-sf}(\xi^2 + A^{-2}(x) \eta^2 + V_1(x)))^w = -\tilde{\Delta}
\]
Let
\[
Q = (e^{-sf}(\xi^2 + A^{-2} \eta^2))^w
\]
and
\[
R = -e^{-sf} (-sf_x \partial_x - A^{-2} sf_\theta \partial_\theta - (s/2) f_{xx} + ((s/2) f_x)^2 - A^{-2} (s/2) f_{\theta \theta} + A^{-2} (s/2) f_\theta)^2)
\]
so that
\[
Q = -e^{-sf} (\partial_x^2 + A^{-2} \partial_\theta^2) + R.
\]
Then \( Q \) is essentially self-adjoint and \( R \) consists of the lower order parts of the operator.
Below we will commute with an operator \( B \) involving only 1 derivative. Commuting
\[ B \] and \( e^{-sf} V_1(x) \) will produce a bounded function and no derivatives, or in other words
an \( L^2 \) bounded operator. This can then easily be absorbed into the upper bound of
\[ \| u_0 \|_{H^{1/2}}^2 \], as will be done with many other remainder terms below. Thus proving the
result for \( Q \) will prove the result for \( \tilde{\Delta} \). Conjugating back then proves the result for
\( \Delta_g \). For this reason, we will leave out \( V_1(x) \) in the computations below and work with
\( Q \).

We begin by making the same positive commutator argument as in [CW13]. By
commuting the operator we are interested in, \( Q \), with an appropriate operator \( B \) we
are able to prove the local smoothing estimate away from \( x = 0 \).

For our commutant we choose
\[
B = \arctan(x) \partial_x.
\]
We begin by commuting the two operators to find
\[
[Q, B] = -e^{-sf} (\partial_x^2 + A^{-2} \partial_\theta^2)[\arctan(x) \partial_x]
+ \arctan(x) \partial_x [e^{-sf} (\partial_x^2 + A^{-2} \partial_\theta^2)] + [R, B]
= -e^{-sf} \left[ 2 \langle x \rangle^{-2} \partial_x^2 - \frac{2x}{(1 + x^2)^2} \partial_x + sf_x \arctan(x) (\partial_x^2 + A^{-2} \partial_\theta^2) \right]
+ \arctan(x) 2A' A^{-3} \partial_\theta^2 \right] + [R, B].
\]
Now that we are done with the preliminary computations, we begin the argument proper by assuming that $u$ satisfies the Schrödinger equation
\[
\begin{cases}
(D_t + Q)u = 0, \\
u(0, x, \theta) = u_0 \in S.
\end{cases}
\]

Using that, we write down the following expression which equals 0:
\[
0 = \int_0^T \langle B(D_t + Q)u, u \rangle - \langle Bu, (D_t + Q)u \rangle \, dt.
\]

In order to make our commutator term appear, we next need to integrate by parts in the second term and obtain
\[
0 = \int_0^T \langle B(D_t + Q)u, u \rangle - \langle (D_t + Q)Bu, u \rangle \, dt + i \langle Bu, u \rangle|_0^T.
\]

We combine the terms involving $D_t$, $Q$, and $B$. This results in
\[
0 = \int_0^T \langle B(D_t + Q) - (D_t + Q)Bu, u \rangle \, dt + i \langle Bu, u \rangle|_0^T.
\]

Finally, we note that these combined terms are precisely the commutator we computed above, and we end up with the equation
\[
\int_0^T \langle [Q, B]u, u \rangle = i \langle Bu, u \rangle|_0^T.
\]

Next we write out the commutator in (2) and move the largest, highest order terms to the left hand side. That is, we move the terms with zero or one derivative to the right hand side, as well as terms multiplied by $s$. This results in the equation
\[
\int_0^T \left\langle -e^{-sf} \langle x \rangle^{-2} \partial_x^2 u, u \right\rangle - \left\langle e^{-sf} \arctan(x)2A^\prime A^{-3} \partial_\theta^2 u, u \right\rangle dt
\]
\[
= -\int_0^T \left\langle e^{-sf} \frac{2x}{(1 + x^2)^2} \partial_x + sf \arctan(x)(\partial_x^2 + A^{-2} \partial_\theta^2) + [R, B] \right\rangle u, u \right\rangle dt
\]
\[
+ i \langle Bu, u \rangle|_0^T.
\]

We begin by working on the left hand side of (3). Starting with the first term on the left hand side of (3) involving derivatives of $x$, we first integrate by parts to find
\[
- \left\langle e^{-sf} 2 \langle x \rangle^{-2} \partial_x^2 u, u \right\rangle = \left\langle \partial_x u, \left\langle 2e^{-sf} \langle x \rangle^{-2} u \right\rangle \right\rangle.
\]

Next we use the product rule to find that (4) equals
\[
\|e^{-sf/2} \langle x \rangle^{-1} \partial_x u\|^2 + \left\langle \partial_x u, \left( -2sf e^{-sf} \langle x \rangle^{-2} - \frac{4xe^{-sf}}{(1 + x^2)^2} \right) u \right\rangle.
\]

The first term here is the highest order giving an $H^1$ norm. We move the second term to the right hand side of (3) and bound it above. First we note that the function
\[
-2sf e^{-sf} \langle x \rangle^{-2} - \frac{4xe^{-sf}}{(1 + x^2)^2}
\]
Using the Cauchy-Schwarz inequality we are able to bound (5) from above by
\[ \langle \partial_x u, \left( -2sf_x e^{-sf} \langle x \rangle^{-2} - \frac{4xe^{-sf}}{(1 + x^2)^2} \right) u \rangle \]
\[ = \left( \langle D_x \rangle^{-1/2} \partial_x u, \left( \langle D_x \rangle^{1/2} \left( -2sf_x e^{-sf} \langle x \rangle^{-2} - \frac{4xe^{-sf}}{(1 + x^2)^2} \right) u \right) \right). \] (5)

Using the Cauchy-Schwarz inequality we are able to bound (5) from above by
\[ C \| \langle D_x \rangle^{-1/2} \partial_x u \|_{L^2} \left\| \left( \langle D_x \rangle^{1/2} \left( -2sf_x e^{-sf} \langle x \rangle^{-2} - \frac{4xe^{-sf}}{(1 + x^2)^2} \right) u \right) \right\|_{L^2} \leq C \| u \|_{H^{1/2}}^2. \]

Next we move on to the term in (3) involving derivatives of \( \theta \) and proceed similarly. We have
\[ - \left( e^{-sf} \arctan(x) A' A^{-3} \partial^2 \theta, u \right) \]
\[ = e^{-sf} \arctan(x) x^{2m-1} (1 + x^{2m})^{-1/m-1} \partial \theta, \partial \theta u \]
\[ + s \left( \partial e^{-sf} \arctan(x) x^{2m-1} (1 + x^{2m})^{-1/m-1} \partial \theta, u \right). \] (6)

The last term in (6) involving only a single \( \theta \) derivative is controlled by \( C \| u \|_{H^{1/2}}^2 \), just as we did for the terms involving only a single \( x \) derivative in (5). In fact, returning to (3), we can use energy estimates to similarly estimate each first order term on the right hand side by \( C_T \| u_0 \|_{H^{1/2}}^2 \). Here we emphasize that the constant \( C_T \) does depend on \( T \).

Thus far we have proven the inequality
\[ \int_0^T \| e^{-sf/2} \langle x \rangle^{-1} \partial_x u \|_{L^2} + \left\langle e^{-sf} \arctan(x) x^{2m-1} (1 + x^{2m})^{-1/m-1} \partial \theta, \partial \theta u \right\rangle dt \] \[ \leq \int_0^T \left\| s f_x \arctan(x) (\partial^2 \theta + A^{-2} \partial \theta) u, u \right\| dt + C_T \| u_0 \|_{H^{1/2}}^2. \] (7)

The first term on the left hand side of (7) is already written as a norm. For the second term, we need to do a bit of work before it can be bounded below by a norm. Note that
\[ \left\langle e^{-sf} x^{2m} \langle x \rangle^{-2m-3} \partial \theta, \partial \theta u \right\rangle \leq C \left\langle e^{-sf} \arctan(x) x^{2m-1} (1 + x^{2m})^{-1/m-1} \partial \theta, \partial \theta u \right\rangle, \]

So we may bound the left hand side of (7) below by
\[ c \int_0^T \| e^{-sf} \langle x \rangle^{-1} \partial_x u \|_{L^2} + \| e^{-sf} x^m \langle x \rangle^{-m-3/2} \partial \theta \|_{L^2}^2 dt, \] (8)
for some \( c > 0 \). Finally, we can drop the factors of \( e^{-sf} \) by using the fact that \( f \) is compactly supported and hence \( e^{-sf} \) is bounded below by some \( c > 0 \). Thus the lower
bound of the left hand side of (7) is

\[ c \int_0^T \| \langle x \rangle^{-1} \partial_x u \|^2_{L^2} + \| \langle x \rangle^m \langle x \rangle^{-m-3/2} \partial_{\theta} u \|^2_{L^2} \, dt. \] (9)

So far we have shown

\[ c \int_0^T \| \langle x \rangle^{-1} \partial_x u \|^2_{L^2} + \| \langle x \rangle^m \langle x \rangle^{-m-3/2} \partial_{\theta} u \|^2_{L^2} \, dt \]

\[ \leq C_T \| u_0 \|^2_{H^{1/2}} + \int_0^T \left| \langle s f_x \arctan(x) \partial_x^2 u, u \rangle \right| \, dt. \] (10)

The strategy for dealing with the terms with two derivatives on the right hand side of (10) is to make use of the fact that \( s \) is small to absorb them into the left hand side of (10). Integrating by parts and using energy estimates on the lower order terms, we have

\[ \int_0^T \left| \langle s f_x \arctan(x) \partial_x^2 u, u \rangle \right| \, dt \]

\[ = \int_0^T \left| \langle s e^{-sf} (-s f_x)^2 \arctan(x) + f_{xx} \arctan(x) \rangle \partial_x u, u \partial_x \rangle \right| \, dt \]

\[ + \int_0^T \left| \langle s e^{-sf} (f_x \langle x \rangle^{-2} + f_x \arctan(x) \partial_x \rangle \partial_x u, \partial_x u \rangle \right| \, dt \]

\[ \leq C_T \| u_0 \|^2_{H^{1/2}} + \int_0^T \left| \langle s e^{-sf} f_x \arctan(x) \partial_x^2 u, \partial_x^2 u \rangle \right| \, dt. \] (11)

By making use of the fact that \( f \) is compactly supported, we can then bound (11) above by

\[ C_T \| u_0 \|^2_{H^{1/2}} + C s \int_0^T \| \langle x \rangle^{-1} \partial_x u \|^2_{L^2} \]

The second of these terms may be moved to the left hand side of (10), provided that \( s \) is sufficiently small.

Similarly, for the term with two \( \theta \) derivatives on the right hand side of (10), we compute

\[ \int_0^T \left| \langle e^{-sf} s f_x \arctan(x) A^{-2} \partial_{\theta}^2 u, u \rangle \right| \, dt \]

\[ = s \int_0^T \left| \langle \partial_{\theta} (e^{-sf} f_x \arctan(x) A^{-2} u), \partial_{\theta} u \rangle \right| \, dt \]

\[ = s \int_0^T \left| \langle e^{-sf} \arctan(x) A^{-2} (-s f_{\theta} f_x + f_x \partial_x u) \partial_{\theta} u, \partial_{\theta} u \rangle \right| \, dt \]

\[ \leq C_T \| u_0 \|^2_{H^{1/2}} + \int_0^T s \left| \langle e^{-sf} f_x \arctan(x) A^{-2} \partial_{\theta} u, \partial_{\theta} u \rangle \right| \, dt. \]

Recall we have assumed that

\[ |f_x| \leq C |x|^{2m-1} \]
in a neighborhood of $x = 0$. Then using also the fact that $f$ is compactly supported and $\arctan(0) = 0$, we have
\[ |s f_x \arctan(x)| \leq Cs |x|^{2m} \langle x \rangle^{-2m-3}, \]
and thus
\[ \int_0^T s \left| \left< e^{-s f_x \arctan(x)} A^2 \partial_\theta u, \partial_\theta u \right> \right| dt \leq Cs \int_0^T \| |x|^{m} \langle x \rangle^{-m-3/2} \partial_\theta u \|_{L^2}^2 dt. \]
By choosing $s$ sufficiently small we may absorb this into the left hand side of (10). We thus have the estimate
\[ \int_0^T \| \langle x \rangle^{-1} \partial_x u \|_{L^2}^2 + \| |x|^m \langle x \rangle^{-m-3/2} \partial_\theta u \|_{L^2}^2 dt \leq C_T \| u_0 \|_{H^{1/2}}^2 \]
(12)
This estimate shows that the local smoothing is perfect away from $x = 0$, and that we have perfect local smoothing in the $x$ direction. Next we will work on the local smoothing in the $\theta$ direction and near $x = 0$.

4. Estimating in the Frequency Domain

Our plan is to split the function $u$ up based on whether $|D_x|$ or $\langle D_\theta \rangle$ is larger, writing $u = u_1 + u_2$, so that $u_2$ satisfies the estimate
\[ \| \langle D_\theta \rangle u_2 \|_{L^2} \lesssim \| \partial_x u_2 \|_{L^2}. \]
We give an outline of the proof before proceeding with the proof. First we repeat the above argument using $u_2$ in place of $u$. Because $u_2$ is only approximately a solution to the Schrödinger equation, there will be additional error terms. The lower bound of
\[ \int_0^T \| \langle x \rangle^{-1} \partial_x u_2 \|_{L^2}^2 dt. \]
can be bounded from below by
\[ \int_0^T \| \langle x \rangle^{-1} \langle D_\theta \rangle u_2 \|_{L^2}^2 dt \]
This gives us a lower bound in the $\theta$ direction away from $x = 0$. However, it is only for $u_2$, and the upper bound will involve a term other than $\| u_0 \|_{H^{1/2}}^2$, due to the fact that $u_2$ does not solve the Schrödinger equation. We will reduce the problem to finding an appropriate estimate for $u_1$, which will be the subject of the remaining sections.

Let $\psi(\tau)$ be a bump function with $\psi(\tau) = 0$ for $|\tau| > 2$ and $\psi(\tau) = 1$ for $|\tau| < 1$. We define the operator $\psi(D_x/\langle D_\theta \rangle)$ as a Fourier multiplier. Let $\hat{u}(t, \xi, \eta)$ denote the Fourier transform of $u$ in $x$ and $\theta$. Because $\theta \in S^1$, $\eta$ takes integer values. Let $\mathcal{F}$ denote also this Fourier transform:
\[ (\mathcal{F} u)(\xi, \eta) = \int_{\mathbb{R}} \int_{\mathbb{R}} e^{-ix\xi} e^{-i\theta \eta} u(x, \theta) \ d\theta \ dx. \]
Let $\mathcal{F}^{-1}$ denote the inverse. Note that $\mathcal{F}^{-1}$ involves an integral in $\xi$ but a sum in $\eta$:
\[ (\mathcal{F}^{-1} v)(x, \theta) = \frac{1}{4\pi^2} \int_{\mathbb{R}} \sum_{\eta \in \mathbb{Z}} e^{ix\xi} e^{i\theta \eta} v(\xi, \eta) \ d\xi \]
We then define
\[ \psi(D_x/\langle D_\theta \rangle) u = F^{-1}(\psi(\xi/\langle \eta \rangle) \hat{u}). \]

Again suppose \( u \) solves
\[ \begin{cases} (D_t + Q)u = 0, \\ u(0, x, \theta) = u_0 \in \mathcal{S}. \end{cases} \]

We will consider \( u_1 = \psi(D_x/\langle D_\theta \rangle) u \) and \( u_2 = (1 - \psi(D_x/\langle D_\theta \rangle)) u \). While \( u_2 \) is not a solution to the Schrödinger equation, we will show that it is close enough to a solution for our purposes. We have
\[
(D_t + Q)u_2 = (D_t + Q)[(1 - \psi(D_x/\langle D_\theta \rangle))] u \\
= (1 - \psi(D_x/\langle D_\theta \rangle))(D_t + Q)u - [Q, \psi(D_x/\langle D_\theta \rangle)]u \\
= -(Q, \psi(D_x/\langle D_\theta \rangle)) u.
\] (13)

We pause briefly to point out at this point that the commutator with \( \psi \) above gains both regularity and decay in the radial variable \( x \). We use that shortly.

Letting \( B = \arctan(x) \partial_x \) as above we repeat the positive commutator argument from above. We begin by simply expanding the commutator to find
\[
\int_0^T \langle [Q, B]u_2, u_2 \rangle \, dt = \int_0^T \langle QBu_2, u_2 \rangle - \langle BQu_2, u_2 \rangle \, dt.
\]

Next we want to have both \( Q \)'s be applied to \( u_2 \) so that we can use what we know about \( u_2 \) and the Schrödinger equation. We then proceed as in the calculations following (11) to find
\[
\int_0^T \langle [Q, B]u_2, u_2 \rangle \, dt = \int_0^T \left[ \langle Bu_2, (D_t + Q)u_2 \rangle - \langle B(D_t + Q)u_2, u_2 \rangle \right] \, dt \\
+ i \langle Bu_2, u_2 \rangle \bigg|_{t=0}^T.
\] (14)

Our lower bound will come from the left hand side of the equality, while the right hand side will need to be bounded from above, in a manner similar to the preceding section.

Next we consider
\[
\int_0^T \langle Bu_2, (D_t + Q)u_2 \rangle \, dt.
\]

We write this as
\[
\left| \int_0^T \langle (x)^{-1} Bu_2, (x) (D_t + Q)u_2 \rangle \, dt \right| \\
\leq C \int_0^T (\| (x)^{-1} Bu_2 \|_{L^2}^2 + \| (x) (D_t + Q)u_2 \|_{L^2}^2) \, dt.
\]
Note that \([\psi(D_x/ \langle D_\theta \rangle), \partial_x] = 0\). Using the inequality (12) we proved in the previous section, we then know
\[
\int_0^T \| \langle x \rangle^{-1} Bu_2 \|^2 \, dt \\
\leq C \int_0^T \| \langle x \rangle^{-1} \partial_x u \|^2 \, dt + C \| u \|_{L^2}^2 \leq C_T \| u_0 \|_{H^{1/2}}^2.
\]
Recall that \(u_2\) satisfies (13), so that

\[
\begin{align*}
(D_t + Q)u_2 &= -[Q, \psi(D_x/ \langle D_\theta \rangle)]u \\
&= -[e^{-s\partial} (D_x^2 + A^{-2}D_\theta^2) + R, \psi(D_x/ \langle D_\theta \rangle)]u \\
&= -[e^{-s\partial} \psi(D_x/ \langle D_\theta \rangle)](D_x^2 + A^{-2}D_\theta^2)u - e^{-s\partial} [D_x^2 + A^{-2}D_\theta^2, \psi(D_x/ \langle D_\theta \rangle)]u \\
&\quad + [R, \psi(D_x/ \langle D_\theta \rangle)]u.
\end{align*}
\]

(15)

To estimate the first term on the right hand side of (15), we make note of the commutator terms. Because \(f\) has compact support in \(x\), we have decay in \(x\) as quickly as we like. Because of the \(\psi'\) appearing in the commutator, we will be working in the region where \(D_x \sim \langle D_\theta \rangle\), and we will gain a power of \(D_x\) or \(\langle D_\theta \rangle\), whichever is more useful. Thus
\[
\| \langle x \rangle \left[ e^{-s\partial} \psi(D_x/ \langle D_\theta \rangle)](D_x^2 + A^{-2}D_\theta^2)u \right] \| \leq C \| \langle x \rangle^{-1} D_x u \|.
\]

We may then bound \(\int_0^T \| \langle x \rangle^{-1} D_x u \|^2 \, dt\) by \(C_T \| u_0 \|_{H^{1/2}}^2\) as we did before.

Next we note that
\[
[D_x^2 + A^{-2}D_\theta^2, \psi(D_x/ \langle D_\theta \rangle)] = [A^{-2}(x), \psi(D_x/ \langle D_\theta \rangle)]D_\theta^2.
\]

We then have
\[
\langle x \rangle \left[ A^{-2}(x), \psi(D_x/ \langle D_\theta \rangle)]D_\theta^2 = L \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x/ \langle D_\theta \rangle),
\]

where \(L\) is \(L^2\)-bounded and \(\tilde{\psi} \in C_0^\infty\) equals 1 on \(\text{supp} \, \psi\). Then
\[
\int_0^T \| \langle x \rangle \left[ A^{-2}(x), \psi(D_x/ \langle D_\theta \rangle)]D_\theta^2 u \|^2 \, dt = \int_0^T \| L \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x/ \langle D_\theta \rangle)u \|^2 \, dt \\
\leq C \int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x/ \langle D_\theta \rangle)u \|^2 \, dt.
\]

Controlling this will be the subject of the next section.

The term
\[
\int_0^T \langle B(D_t + Q)u_2, u_2 \rangle \, dt = \int_0^T \langle (D_t + Q)u_2, B^*u_2 \rangle \, dt
\]
from (14) is controlled in exactly the same fashion. Thus far we have shown
\[
\int_0^T \langle [Q, B]u_2, u_2 \rangle \, dt \leq CT \| u_0 \|_{H^{1/2}}^2 + \int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x/ \langle D_\theta \rangle)u \|^2 \, dt.
\]
Next we use our expansion of \([Q, B]\) given in (1) above:

\[
[Q, B] = -e^{-sf} \left[ 2 \langle x \rangle^{-2} \partial_x^2 - \frac{2x}{(1 + x^2)^2} \partial_x - sf_x \arctan(x)(\partial_x^2 + A^{-2}(x)\partial_\theta^2) \\
+ \arctan(x)2A' A^{-3} \partial_\theta^2 \right] + [R, B].
\]

We will examine

\[
\int_0^T \langle [Q, B]u_2, u_2 \rangle \, dt
\]

\[
= \int_0^T \langle -e^{-sf} (2 \langle x \rangle^{-2} \partial_x^2 u_2, u_2) \rangle \, dt \\
+ \int_0^T \langle e^{-sf} \frac{2x}{(1 + x^2)^2} \partial_x u_2, u_2 \rangle \, dt \\
+ \int_0^T \langle e^{-sf} sf_x \arctan(x)(\partial_x^2 + A^{-2}(x)\partial_\theta^2) u_2, u_2 \rangle \, dt \\
- \int_0^T \langle e^{-sf} \arctan(x)2A' A^{-3} \partial_\theta^2 u_2, u_2 \rangle \, dt \\
+ \int_0^T \langle [R, B]u_2, u_2 \rangle \, dt
\]

(16)

term by term. As in the previous section we have

\[
\int_0^T \| [R, B]u_2, u_2 \| \, dt \leq CT \| u_0 \|_{H^{1/2}}^2,
\]

so we move on to the next computation. Next we write

\[
\int_0^T \langle -2e^{-sf} \langle x \rangle^{-2} \partial_x^2 u_2, u_2 \rangle \, dt \\
= 2 \int_0^T \langle e^{-sf/2} \langle x \rangle^{-1} \partial_x u_2, \partial_x (e^{-sf/2} \langle x \rangle^{-1} u_2) \rangle \, dt \\
= 2 \int_0^T \|e^{-sf/2} \langle x \rangle^{-1} \partial_x u_2\|^2 \, dt \\
+ \int_0^T \langle e^{-sf/2} \langle x \rangle^{-1} \partial_x u_2, \partial_x (e^{-sf/2} \langle x \rangle^{-1} u_2) \rangle \, dt.
\]
Note that
\[
\int_0^T \left| \left\langle e^{-sf/2} \langle x \rangle^2 \partial_x u_2, \partial_x(e^{-sf/2} \langle x \rangle^{-1})u_2 \right\rangle \right| dt 
\leq C \int_0^T \| D_x \|^{-1/2} \| e^{-sf/2} \langle x \rangle^{-1} \partial_x u_2 \| \| \langle D_x \rangle \|^{1/2} \| \langle D_x \rangle \| \| [\partial_x e^{-sf/2} \langle x \rangle^{-1}]u_2 \| dt 
\leq C \int_0^T \| u_2 \|_{H^{1/2}}^2 dt 
\leq C T \| u_0 \|_{H^{1/2}}^2.
\]

The \( \partial_\theta^2 \) term in (16) is taken care of similarly:
\[
\int_0^T \left\langle e^{-sf} \arctan(x) 2A'A^{-3} \partial_\theta^2 u_2, u_2 \right\rangle dt 
= \int_0^T \left\langle \arctan(x) 2A'A^{-3} \partial_\theta u_2, \partial_\theta(e^{-sf}u_2) \right\rangle dt 
= \int_0^T \left\langle e^{-sf} \arctan(x) 2A'A^{-3} \partial_\theta u_2, (-sf_\theta + \partial_\theta)u_2 \right\rangle dt. \tag{17}
\]

Then for the term from (17) involving only one derivative we may again bound it from above by \( C_T \| u_0 \|_{H^{1/2}}^2 \). The other term is
\[
\int_0^T \left\langle e^{-sf} \arctan(x) 2A'A^{-3} \partial_\theta u_2, \partial_\theta u_2 \right\rangle dt 
\geq c \int_0^T \| |x|^m \langle x \rangle^{-m-3/2} \partial_\theta u_2 \| dt.
\]

The next term from (16) we estimate is
\[
\left| \int_0^T \left\langle 2x \langle x \rangle^{-4} \partial_x u_2, u_2 \right\rangle dt \right| \leq C_T \| u_0 \|_{H^{1/2}}^2,
\]
just as in the previous sections.

The remaining terms can be controlled by using our estimates from the previous section and again that \( s \) is small and \( |f_\theta| = O(|x|^{2m-1}) \). Collecting terms, we end up with \( u_2 \) satisfying the estimate
\[
\int_0^T \| \langle x \rangle^{-1} \partial_x u_2 \|_{L^2}^2 + \| |x|^m \langle x \rangle^{-m-3/2} \partial_\theta u_2 \|_{L^2}^2 dt 
\leq C_T \| u_0 \|_{H^{1/2}}^2 + C \int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x/\langle D_\theta \rangle)u \|_{L^2}^2 dt. \tag{18}
\]

Finally we make use of the micro-support property of \( \tilde{\psi}(D_x/\langle D_\theta \rangle)u \). This function cuts \( u_2 = (1 - \tilde{\psi}(D_x/\langle D_\theta \rangle)u \) off to where \( \langle D_\theta \rangle \lesssim |\partial_x| \), so we have from the Gårding inequality
\[
\| \langle x \rangle^{-1} \langle D_\theta \rangle u_2 \| \leq C \| \langle x \rangle^{-1} \partial_x u_2 \| + C \| u_2 \|_{H^{1/2}}^2.
\]

Using this, we see that
\[
\int_0^T \| \langle x \rangle^{-1} \langle D_\theta \rangle u_2 \|_{L^2}^2 dt \leq C_T \| u_0 \|_{H^{1/2}}^2 + \int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x/\langle D_\theta \rangle)u \|_{L^2}^2 dt.
\]
Now let $\chi(x) \equiv 1$ near 0 and have compact support. Then
\[
\int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x / \langle D_\theta \rangle) u \|_{L^2_x}^2 \, dt \\
\leq C \int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x / \langle D_\theta \rangle) \chi(x) u \|_{L^2_x}^2 \, dt \\
\leq C \int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x / \langle D_\theta \rangle)(1 - \chi(x)) u \|_{L^2_x}^2 \, dt
\]
The second term on the right hand side has integrand with support away from $x = 0$, so can then be bounded using the estimate from the previous section:
\[
\int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x / \langle D_\theta \rangle)(1 - \chi(x)) u \|_{L^2_x}^2 \, dt \\
\leq \int_0^T \| |x|^m \langle x \rangle^{m-3/2} \partial_{\theta} u \|_{L^2_x}^2 \, dt \\
\leq C_T \| u_0 \|_{H^{1/2}}^2.
\]
Thus to finish this part of our estimate we need only bound
\[
\int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x / \langle D_\theta \rangle) \chi(x) u \|_{L^2_x}^2 \, dt,
\]
for $\tilde{\psi}$ with compact support, $\tilde{\psi} \equiv 1$ on the support of $\psi$. Note that by estimating this with $\tilde{\psi}$, we will also bound
\[
\int_0^T \| \langle x \rangle^{-2} D_\theta \chi(x) u \|_{L^2_x}^2 \, dt = \int_0^T \| \langle x \rangle^{-2} D_\theta \chi(x) \psi(D_x / \langle D_\theta \rangle) u \|_{L^2_x}^2 \, dt,
\]
which will then complete the local smoothing estimate. We begin this process in the next section.

5. High Frequency Estimate

We have proven our local smoothing estimate outside of a region that is “small” in both space and frequency. This suggests that it will be profitable to work microlocally.

To that end, we wish to show that estimating
\[
\int_0^T \| \langle x \rangle^{-2} D_\theta \tilde{\psi}(D_x / \langle D_\theta \rangle) \chi(x) u \|_{L^2_x}^2 \, dt
\]
follows from proving an estimate of the form
\[
\| (Q + \tau) \psi \chi u \| \geq \| (D_\theta)^r \psi \chi u \|
\]
for some $r \in \mathbb{R}$, where $u$ is microlocalized near $(x, \xi/\langle \eta \rangle) = 0$. We do this by using a “$TT^*$” argument.

The operator to which we apply the argument will be $F(t)$. Define the operator $F(t)$ by
\[
F(t)g = \chi(x) \psi(D_x / \langle D_\theta \rangle) e^{-itQ} g(x, \theta).
\]
We need to determine for which values of $r$, with $0 \leq r \leq 1$, we have a bounded map $F : L^2 L^r_\theta \to L^2([0, T]) L^2 \mathcal{H}$. 
We have
\[ F^* g = \int_0^T e^{i\tilde{Q}} \psi(D_x/\langle D_\theta \rangle) \chi(x) \tilde{g} \, dt \]
and we need to show
\[ F^* : L^2([0, T])L^2_xH^r_\theta \to L^2_xL^2_\theta. \]
Then
\[ FF^* \tilde{g} = \chi(x) \psi(D_x/\langle D_\theta \rangle) \int_0^T e^{i(\tilde{t}-t)Q} \psi(D_x/\langle D_\theta \rangle) \chi(x) \tilde{g} \, d\tilde{t} \]
and we need to show
\[ FF^* : L^2([0, T])L^2_xH^r_\theta \to L^2([0, T])L^2_xH^r_\theta. \]
We split this expression into two. Let
\[ v_1 = \int_0^t e^{i(\tilde{t}-t)Q} \psi(D_x/\langle D_\theta \rangle) \chi(x) \tilde{g} \, d\tilde{t} \]
and
\[ v_2 = \int_t^T e^{i(\tilde{t}-t)Q} \psi(D_x/\langle D_\theta \rangle) \chi(x) \tilde{g} \, d\tilde{t}. \]
Then
\[ FF^* \tilde{g} = \chi(x) \psi(D_x/\langle D_\theta \rangle)(v_1 + v_2). \]
We need to show
\[ \| \chi(x) \psi(D_x/\langle D_\theta \rangle)v_j \|_{L^2_xL^2_\theta H^r_\theta} \leq C\| \tilde{g} \|_{L^2_xL^2_\theta H^r_\theta} \]
for \( j = 1, 2 \), where we require some assumptions on \( \tilde{g} \) which will be included in the statement of our theorem below.

Note that
\[ (D_t + Q)v_1 = -i\psi(D_x/\langle D_\theta \rangle)\chi(x) \tilde{g} \]
and
\[ (D_t + Q)v_2 = i\psi(D_x/\langle D_\theta \rangle)\chi(x) \tilde{g}. \]
Let \( \hat{\cdot} \) denote the Fourier transform in time. Then
\[ (\tau + Q)\hat{v}_j = (-1)^j i\chi \hat{\psi}\hat{\tilde{g}}, \]
If we can prove the bound
\[ \| \chi \hat{\psi} \hat{v}_j \|_{L^2_xL^2_\theta H^r_\theta} \leq C\| \hat{\tilde{g}} \|_{L^2_xL^2_\theta H^r_\theta}, \]
we will have shown that \( FF^* : L^2_xL^2_\theta H^r_\theta \to L^2_xL^2_\theta H^r_\theta \) (and thus \( F : L^2_xL^2_\theta \to L^2_xL^2_\theta H^r_\theta \)) is a bounded operator. To that end, we need to bound the operator
\[ \chi(x) \psi(D_x/\langle D_\theta \rangle)(Q + \tau)^{-1} \psi(D_x/\langle D_\theta \rangle) \chi(x) \]
in the \( L^2_xH^r_\theta \to L^2_xH^r_\theta \) operator norm, uniformly in \( \tau \).
This is equivalent to showing that there exists \( C \) such that
\[ \| \langle D_\theta \rangle^{2r} u \|_{L^2_{x,\theta}} \leq C\| (Q + \tau)u \|_{L^2_xH^r_\theta}. \]
Proving this estimate will be the subject of the next section. Proving it will bound \( \chi(x) \psi(D_x/\langle D_\theta \rangle)e^{i\tilde{Q}} \tilde{g} \) in \( L^2_xL^2_\theta H^r_\theta \), but we are ultimately interested in bounding it in
\( L_x^2 L_x^2 H_0^1 \). To do so, we apply the bound to \( \langle D_\theta \rangle^{1-r} g \), so we will ultimately end up with the bound

\[
\int_0^T \| \langle D_\theta \rangle \chi(x) \psi(D_x / \langle D_\theta \rangle) u \|_{L_x^2}^2 \, dt \leq C \| u_0 \|_{H^{1-r}}^2.
\]

6. Microlocal Resolvent Estimate

We state and prove the aforementioned resolvent estimate in order to finish the proof of the main theorem.

**Theorem 6.1.** Let \( \epsilon > 0 \) and let \( p = \xi^2 + \eta^2 A^{-2} \). Suppose \( f(x, \theta) \) is a compactly supported, smooth function such that

\[
|\partial_x^j \partial_\theta^k f| \leq C|x|^{2m-1}
\]

for \( x \) small and \( j, k \leq N \) for sufficiently large \( N = N(m, \epsilon) \) and \( j + k \geq 1 \). For \( s \) sufficiently small, there exists \( c > 0 \) such that

\[
\| (e^{x f} p + \tau) u \|_{L_x^2} \geq c \| \langle D_\theta \rangle^{2/(m+1)-\epsilon} u \|_{L_x^2},
\]

for all \( \tau \), provided that \( u \) satisfies the following microlocal support properties: We require that \( u \) be of the form

\[
u = b^w \tilde{u},
\]

where \( b \) has (classical) symbol supported in the region where \( |(x, \xi/\eta)| \leq \delta/2 \) for some small \( \delta \) and \( |\eta| \geq M \) for sufficiently large \( M \).

Broadly speaking, our proof uses a commutator argument. The basic structure is to make use of the fact that to highest order, the symbol of the commutator of two pseudodifferential operators is given by applying the Hamiltonian vector field of the one symbol to the other symbol. Recall that \( Q = (e^{-sf} p)^w \) denotes the operator we are interested in. We define a symbol \( a \in S^0 \) such that \( H_{e^{-sf} p} a \) has the required lower bound. Ignoring the issues of error terms coming from the pseudodifferential calculus for the moment, we will consider the quantity

\[
\langle [Q + \tau, a^w] u, u \rangle,
\]

where \( a \) is yet to be determined, following [CW13].

As we stated above, the lower bound makes use of the fact that to highest order, \( [Q, a^w] = i^{-1} (H_{e^{-sf} p} a)^w \), where \( p = \xi^2 + A^{-2} \eta^2 \). We seek \( a \) such that the resulting symbol \( H_{e^{-sf} p} a \) is of the form \( |\eta|^{-\epsilon} (\xi^2 + \eta^2 x^{2m}) \) at least where \( x \) and \( \xi \eta^{-1} \) are small and \( \eta \) is large. We may then use a lower bound on this operator to achieve a lower bound of

\[
\| \langle D_\theta \rangle^{2/(m+1)-\epsilon/2} u \| \leq \| a^w u, (Q + \tau) u \|.
\]

The operator we require a lower bound on is \( (e^{-sf} q)^w + \tau \). To define the symbol of our commutant \( a \), we first define

\[
\Lambda(t) = \int_0^t \langle \tilde{\tau} \rangle^{-1-\epsilon_0} \, d\tilde{t},
\]

where \( \epsilon_0 > 0 \) is a small fixed number so that the integral is bounded. The important facts about \( \Lambda(t) \) is that it is a symbol of order 0, and \( \Lambda(t) \sim t \) near 0.
We will also make use of cutoff functions $\chi(t)$ and $\tilde{\chi}(t)$. For $\delta > 0$ small, let $\chi(t)$ be a smooth, compactly supported function such that $\chi(t) \equiv 1$ for $|t| \leq \delta/2$ and $\chi(t) \equiv 0$ for $|t| \geq \delta$. Let $\tilde{\chi}(t)$ be a smooth function such that $\tilde{\chi}(t) \equiv 0$ for $|t| \leq M$ and $\tilde{\chi}(t) \equiv 1$ for $|t| \geq 2M$.

Let

$$a = \chi(x)\chi(\xi \eta^{-1})\Lambda(x)\Lambda(\xi |\eta|^{-\epsilon})\tilde{\chi}(\eta)$$

and note that

$$|\partial_x^\alpha \partial_\xi^\beta \partial_\eta^\gamma a| \leq C_{\alpha,\beta,\gamma,\delta} \langle \xi \rangle^{-\epsilon \beta} \langle \eta \rangle^{-\epsilon \delta},$$

where we have used the fact that $\chi(\xi \eta^{-1})$ cuts off to zero where $|\xi| \leq |\eta|$. Because of this inequality, $a \in S^0$.

**Theorem 6.2.** Let $p, a$ be as above. Then for any $\epsilon > 0$ there exists $c > 0$ such that

$$\langle e^{-s f} (H_{e^{-s f}})^w u, u \rangle \geq c \langle (D_\theta)^{-\epsilon} (D_x^2 + D_\theta^2 x^{2m}) u, u \rangle - O(\| (D_\theta)^{-\epsilon / 2} u \|^2).$$

for all $u$ microsupported where $|x| \leq \delta$, $|\xi \eta^{-1}| \leq \delta$, and $|\eta| \geq M$ for some large $M$.

**Proof.** We begin by computing $H_{e^{-s f}} p a$. First recall that

$$p(x, \xi, \theta, \eta) = \xi^2 + A^{-2}(x) \eta^2$$

and

$$a(x, \xi, \theta, \eta) = \chi(x)\chi(\xi \eta^{-1})\Lambda(x)\Lambda(\xi |\eta|^{-\epsilon})\tilde{\chi}(\eta).$$

Note that $a$ does not depend on $\theta$, so no $(e^{-s f} p)_\eta a_\theta$ term will appear in the symbol expansion for the commutator. We next compute the necessary derivatives for the symbol expansion of the commutator. Recall that the notation for the $\eta$ derivative actually refers to a difference operator in $\eta$.

$$\begin{align*}
(e^{-s f} p)_x &= -2 e^{-s f} A^{-3} A' \eta^2 - s f_x e^{-s f} p, \\
(e^{-s f} p)_\xi &= 2 e^{-s f} \xi, \\
(e^{-s f} p)_\theta &= -s f_\theta e^{-s f} p, \\
_{\alpha} a_x &= [\chi'(x)\chi(\xi \eta^{-1})\Lambda(x)\Lambda(\xi |\eta|^{-\epsilon}) + \chi(x)\chi(\xi \eta^{-1})\Lambda'(x)\Lambda(\xi |\eta|^{-\epsilon})] \tilde{\chi}(\eta), \\
_{\alpha} a_\xi &= [\eta^{-1} \chi(x)\chi'(\xi \eta^{-1})\Lambda(x)\Lambda(\xi |\eta|^{-\epsilon}) + |\eta|^{-\epsilon} \chi(x)\chi(\xi \eta^{-1})\Lambda(x)\Lambda'(\xi |\eta|^{-\epsilon})] \tilde{\chi}(\eta), \\
_{\alpha} a_\eta &= \Lambda(x)\Lambda(\xi |(\eta + 1) |^{-\epsilon}) - \Lambda(\xi |\eta|^{-\epsilon})] \chi(x) \chi(\xi \eta^{-1}) \tilde{\chi}(\eta), \\
&+ \Lambda(x)\Lambda(\xi |(\eta + 1) |^{-\epsilon}) \chi(x) \chi(\xi (\eta + 1)^{-1}) \tilde{\chi}(\eta) - \chi(\xi \eta^{-1}) \tilde{\chi}(\eta) \\
&+ \Lambda(x)\Lambda(\xi |\eta|^{-\epsilon}) \chi(x) \chi(\xi \eta^{-1}) \tilde{\chi}(\eta) \\
&+ \Lambda(x)\Lambda(\xi |\eta|^{-\epsilon}) \chi(x) \chi(\xi \eta^{-1}) \tilde{\chi}(\eta) - \chi(\xi \eta^{-1}) \tilde{\chi}(\eta).
\end{align*}$$

Using this computation we write down $H_{e^{-s f}} p a$ and split it into two parts. We are only interested in the behavior of $H_{e^{-s f}} p a$ where $x$ is small, $\xi \eta^{-1}$ is small, and $\eta$ is large, so we separate out the terms of $H_{e^{-s f}} p a$ where derivatives or difference operators hit $\chi$. These terms are supported where $x$ is large, $\xi$ is large relative to $\eta$, or $\eta$ is small. Because we have already proven our local smoothing estimate in these regions, there is no need to apply our resolvent estimate there.
We collect the terms involving derivatives of $\chi$ where $|\eta| = 2$.

We have

$$H_{e^{-sf_p}} a = \left[ 2e^{-sf} \xi' \chi(\xi \eta^{-1}) \Lambda(x) \Lambda(\xi|\eta|^{-\epsilon}) + \chi(x) \chi(\xi \eta^{-1}) \Lambda'(x) \Lambda(\xi|\eta|^{-\epsilon}) \right]$$

$$- (-2e^{-sf} A^{-3} A'|\eta|^2 - s f_p e^{-sf} p) \chi(x) \chi'(\xi \eta^{-1}) \eta^{-1} \Lambda(x) \Lambda(\xi|\eta|^{-\epsilon})$$

$$+ |\eta|^{-\epsilon} \chi(x) \chi(\xi \eta^{-1}) \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon})$$

$$- (-s f_p e^{-sf} p) \Lambda(x) \left( \Lambda(\xi|\eta+1|^{-\epsilon}) - \Lambda(\xi|\eta|^{-\epsilon}) \right) \chi(x) \chi(\xi \eta^{-1}) \right] \tilde{\chi}(\eta))$$

$$+ s f_p e^{-sf} p \Lambda(x) \Lambda(\xi|\eta+1|^{-\epsilon}) \chi(x) \left[ \chi(\xi \eta^{-1}) \tilde{\chi}(\eta + 1) - \chi(\xi \eta^{-1}) \tilde{\chi}(\eta) \right].$$

We collect the terms involving derivatives of $\chi$ or $\tilde{\chi}$ and write

$$H_{e^{-sf_p}} a = \left[ 2 \xi' \Lambda(x) \Lambda(\xi|\eta|^{-\epsilon}) + 2 A^{-3} A'|\eta|^2 \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon}) \right]$$

$$+ s f_p |\eta|^{-\epsilon} \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon}) + s f_p \Lambda(x) \left( \Lambda(\xi|\eta+1|^{-\epsilon}) - \Lambda(\xi|\eta|^{-\epsilon}) \right)$$

$$\times e^{-sf} \chi(x) \chi(\xi \eta^{-1}) (\tilde{\chi}(\eta))$$

$$+ r,$$

where

$$\text{supp} r \subset \{ |x| \geq \delta/2 \} \cup \{ |\xi| \geq \delta|\eta|/2 \} \cup \{ |\eta| \leq 2M \}.$$

We use $g$ to denote the part of $H_{e^{-sf_p}} a$ to which we devote most of our efforts. Let

$$g = \left( 2 \xi' \Lambda(x) \Lambda(\xi|\eta|^{-\epsilon}) + 2 |\eta|^{-\epsilon} A^{-3}(x) A'(x) \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon}) \right) e^{-sf} \chi(x) \chi(\xi \eta^{-1}) \tilde{\chi}(\eta).$$

We use $\tilde{g}$ to denote the terms in which derivatives have hit $e^{-sf}$:

$$\tilde{g} = \left[ s f_p |\eta|^{-\epsilon} \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon}) \right]$$

$$+ s f_p \Lambda(x) \left( \Lambda(\xi|\eta+1|^{-\epsilon}) - \Lambda(\xi|\eta|^{-\epsilon}) \right) e^{-sf} \chi(x) \chi(\xi \eta^{-1}) \tilde{\chi}(\eta),$$

so

$$H_{e^{-sf_p}} a = g + \tilde{g} + r.$$

Our goal is, roughly, to show that $\tilde{g}$ can be absorbed into $g$ and that $g$ is bounded below by a small multiple of $|\eta|^{-\epsilon} (\xi^2 + \eta^2 A x^{2m})$.

We begin by bounding $\tilde{g}$ from above. Because we will only apply this result to functions which are microlocally supported in the region where $\chi(x) = 1$, $\chi(\xi \eta^{-1}) = 1$, and $\tilde{\chi}(\eta) = 1$, we omit the $\chi$ and $\tilde{\chi}$ factors. We start with the first term in (19):

$$|sf_p |\eta|^{-\epsilon} \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon}) e^{-sf}| \leq C |sf_p |\eta|^{-\epsilon} (\xi^2 + \eta^2 A^{-2}(x) \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon})$$

$$\leq C |sf_p |\eta|^{-\epsilon} \Lambda(x) \Lambda'(\xi|\eta|^{-\epsilon}),$$

where we have used the fact that $|\xi| \leq C|\eta|$. 

For the next term in (19) we first use the mean value theorem to note that
\[ |\Lambda(\xi(|\eta + 1|^{-\epsilon}) - \Lambda(\xi|\eta|^{-\epsilon})| = \left| \int_{\xi|\eta|^{-\epsilon}}^{\xi(|\eta + 1|^{-\epsilon})} \langle t \rangle^{-1-\epsilon_0} \, dt \right| \]
\[ \leq C|\xi|\langle (\eta + 1)\rangle^{-\epsilon} - |\eta|^{-\epsilon}\langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0} \]
\[ \leq C|\xi|||\eta|^{-\epsilon}|\langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0}. \]

Thus
\[ \left| - s f_\theta \Lambda(x) \left( \Lambda(\xi(|\eta + 1|^{-\epsilon}) - \Lambda(\xi|\eta|^{-\epsilon}) \right) e^{-sf} \right| \]
\[ \leq C |sf_\theta|\eta^{-1-\epsilon}(\xi^2 + \eta^2 A^{-2}(x))\Lambda(x) \langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0} \]
\[ \leq C |sf_\theta|\eta^{2-\epsilon}\Lambda(x) \langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0}, \]
so
\[ |\tilde{g}| \leq |s||\langle f_x \rangle + |f_\theta|||\eta|^{2-\epsilon}\Lambda(x) \langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0}. \]

We need to write \( g \) in a more useful form. To get started, we recall that the definition of \( \Lambda \) is
\[ \Lambda(t) = \int_0^t \langle \tilde{t} \rangle^{-1-\epsilon_0} \, d\tilde{t}, \]
so \( \Lambda'(t) = \langle t \rangle^{-1-\epsilon_0} \), and
\[ g = (2\xi \langle x \rangle^{-1-\epsilon_0} \Lambda(\xi|\eta|^{-\epsilon}) + 2|\eta|^{2-\epsilon}A^{-3}(x)\Lambda'(x) \langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0}) \]
\[ \times e^{-sf} \chi(x)\chi(\xi\eta^{-1})\tilde{\chi}(\eta). \]

We will assume throughout that \(|x| \leq \delta/2, |\xi\eta^{-1}| \leq \delta/2, \) and \(|\eta| \geq M \) because we will be applying our operators to functions microlocally cutoff near here. In this region, \( \chi(x) = 1, \chi(\xi\eta^{-1}) = 1, \) and \( \tilde{\chi}(\eta) = 1. \)

We first break \( g \) up into two parts:
\[ g = (2\xi \langle x \rangle^{-1-\epsilon_0} \Lambda(\xi|\eta|^{-\epsilon}) + 2|\eta|^{2-\epsilon}A^{-3}(x)\Lambda'(x) \Lambda(x) \langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0}) e^{-sf} \]
\[ = g_1 + g_2, \]
where
\[ g_1 = 2\xi \langle x \rangle^{-1-\epsilon_0} \Lambda(\xi|\eta|^{-\epsilon}) e^{-sf}, \]
\[ g_2 = 2|\eta|^{2-\epsilon}A^{-3}(x)\Lambda'(x) \Lambda(x) \langle \xi|\eta|^{-\epsilon}\rangle^{-1-\epsilon_0} e^{-sf}. \]

Before bounding \( g \) from below, we note how \( \tilde{g} \) may be absorbed into \( g \). From (20) we see that
\[ \tilde{g} \leq C|s|g_2 \]
as long as \(|f_x| \leq CA'(x) \) and \(|f_\theta| \leq CA'(x) \). This is satisfied as long as \(|f_x| \leq C|x|^{2m-1} \) and \(|f_\theta| \leq C|x|^{2m-1} \). We will consider two cases.

**Case 1:** In the first case we make the assumption that \(|\xi|\eta|^{-\epsilon}| \leq \delta. \) We are working where \( \Lambda \) is only applied to small quantities, and for \(|t| \) small \( \Lambda(t) = t + O(t^3) \) and \( \langle t \rangle^{-1-\epsilon} = 1 + O(t^2). \)
We write out $g_1$. Because $|\eta|$ is relatively large and $\xi$ is relatively small, the most important term will end up being $2|\eta|^{-e} \xi^2 e^{-sf}$. Below we will show how the other terms may be absorbed. We separate out this term by writing

\[
g_1 = (2\xi(1 + O(x^2))(\xi|\eta|^{-\epsilon} + O((\xi|\eta|^{-\epsilon})^2)e^{-sf}
\]
\[
= 2\xi^2|\eta|^{-\epsilon}(1 + O(x^2))(1 + O((\xi|\eta|^{-\epsilon})^2))e^{-sf}
\]
\[
= 2|\eta|^{-\epsilon}\xi^2 e^{-sf} + O(x^2\xi^2|\eta|^{-\epsilon}) + O(\xi^4|\eta|^{-3\epsilon}) + O(\xi^4|\eta|^{-3\epsilon}x^2)
\]
\[
= 2|\eta|^{-\epsilon}\xi^2 e^{-sf} + \xi^2|\eta|^{-\epsilon} (O(x^2) + O((\xi|\eta|^{-\epsilon})^2))
\]

where we have used the fact that there exists $C$ such that $e^{-sf(x, \theta)} \leq C$.

Because $|x| \leq \delta$ and $|\xi| |\eta|^{-\epsilon} \leq \delta$, we then have

\[
g_1 = 2|\eta|^{-\epsilon}\xi^2 e^{-sf}(1 + O(\delta^2)).
\]

Along the same lines, for $g_2$, the most important term in the expansion will be $2|\eta|^{-\epsilon}(|\eta|x^m)^2 e^{-sf}$. Recall that $A(x) = (1 + x^{2m})^{1/2m}$. Here we use Taylor’s theorem to expand $A^{-3}(x)A'(x)$ and write

\[
g_2 = 2|\eta|^{-\epsilon} A^{-3}(x)A'(x)(x + O(x^3))(1 + O((\xi|\eta|^{-\epsilon})^2))e^{-sf}
\]
\[
= 2|\eta|^{-\epsilon}(x^{2m-1} + O(x^{4m-1}))(x + O(x^2))(1 + (O((\xi|\eta|^{-\epsilon})^2))e^{-sf}
\]
\[
= 2|\eta|^{-\epsilon}(|\eta|x^m)^2 e^{-sf} + 2|\eta|^{-\epsilon} x^{2m} ((O(x^{4m}) + O((x^m|\eta|^{-\epsilon})^2)).
\]

Again using that $|x| \leq \delta$ and $|\xi| |\eta|^{-\epsilon} \leq \delta$, we have

\[
g_2 = 2|\eta|^{-\epsilon}(|\eta|x^m)^2 e^{-sf}(1 + O(\delta^2)).
\]

Because $|\tilde{g}| \leq C|s|g_2$, we then have $g_2 + \tilde{g} = g_2(1 + O(s))$, hence

\[
g_2 + \tilde{g} = 2|\eta|^{-\epsilon}(|\eta|x^m)^2 e^{-sf}(1 + O(\delta^2) + O(s)).
\]

We can thus write

\[
g + \tilde{g} = 2e^{-sf}|\eta|^{-\epsilon}(2\xi^2 + |\eta|^2 x^{2m})(1 + O(\delta^2) + O(s))
\]

as long as $|\xi| |\eta|^{-\epsilon} \leq \delta$.

**Case 2:** We move on to our other case, where $|\xi| |\eta|^{-\epsilon} \geq \delta$. Our cutoff functions still allow us to assume that $|x| \leq \delta$, $|\xi|^{-\epsilon} \leq \delta$, and $|\eta|$ is large.

In this region, we will show that $g + \tilde{g}$ is elliptic. We will consider two sub-cases, based on the size of $x$ relative to the size of $\xi |\eta|^{-\epsilon}$.

We first note that $g_1, g_2 \geq 0$. Also note using the bound on $\tilde{g}$ given by (20) that, for $s$ sufficiently small,

\[
g_1 + g_2 + \tilde{g} = g_1 + g_2(1 + O(s)) \geq g_1 + (1 - C|s|)g_2 \geq c(g_1 + g_2).
\]

Hence showing that $g$ is elliptic will show that $g + \tilde{g}$ is elliptic.
For our first sub-case, suppose $|x|^{1+\epsilon_0} \geq |\xi\eta|^{-\epsilon} \geq \delta$. Then
\[
g_2 = 2e^{-sf}\langle \eta \rangle^{-2\epsilon} A^{-3}(x)A'(x)A(x) \langle \xi\eta \rangle^{-\epsilon-1-\epsilon_0} = 2e^{-sf}\langle \eta \rangle^{-2\epsilon} x^{2m}(1 + O(x^{2m}))(1 + O(x^2)) \langle \xi\eta \rangle^{-\epsilon-1-\epsilon_0} \geq c\langle \eta \rangle^{-2\epsilon} x^{2m}(1 + O(x^2)) \langle \xi\eta \rangle^{-\epsilon-1-\epsilon_0} \geq c|\eta|^{-2\epsilon} x^{2m} |x|^{-(1+\epsilon_0)^2} \geq c|\eta|^{-\epsilon}.
\]

For our second sub-case, if $|\xi\eta|^{-\epsilon} \geq |x|^{1+\epsilon_0}$, but still $|\xi\eta|^{-\epsilon} \geq \delta$, then
\[
g_1 = 2e^{-sf}\langle \eta \rangle^{-1-\epsilon_0} \Lambda(|\xi\eta|^{-\epsilon}) \geq c\frac{\xi}{\langle \xi \rangle} |\eta| \Lambda(|\xi\eta|^{-\epsilon}) \geq c|\eta|^{\epsilon}
\]
since $\xi$ and $\Lambda(|\xi\eta|^{-\epsilon})$ have the same sign. Hence $g \geq c|\eta|^{\epsilon}$. In either sub-case, we find that in this region $g \geq c|\eta|^{\epsilon}$ and hence $\tilde{g} + g \geq c|\eta|^{\epsilon}$.

Considering both cases, there thus exists a $\sigma > 0$ such that if $u$ is microlocally supported only in the region where $|\xi\eta|^{-\epsilon} \leq \delta$,
\[
\langle (g + \tilde{g})^w u, u \rangle \geq \sigma \| (D_0)^{\epsilon/2} u \|^2.
\]
We have shown that there exists $c > 0$ such that here we may write
\[
g + \tilde{g} \geq c|\eta|^{-\epsilon}(\xi^2 + \eta^2 x^{2m})(1 + O(\delta^2) + O(s)).
\]
For $s > 0$ sufficiently small, this then allows us to write
\[
g + \tilde{g} = |\eta|^{-\epsilon}(\xi^2 + \eta^2 x^{2m}) K^2,
\]
where $K$ is a strictly positive symbol. Because we are using the Weyl quantization here, this quantizes as
\[
\text{Op}^w(K)^* (D_\theta)^{-\epsilon}(D_x^2 + D_\theta^2 x^{2m}) \text{Op}^w(K) + O((\langle D_\theta \rangle)^{-\epsilon} u
\]
so that
\[
\langle (g + \tilde{g})^w u, u \rangle \geq \langle (D_\theta)^{-\epsilon}(D_x^2 + D_\theta^2 x^{2m}) u, u \rangle - O(\| (D_\theta)^{-\epsilon/2} u \|^2)
\]
We thus have
\[
\langle (H_{e^{-sf}} a)^w u, u \rangle \geq \langle (D_\theta)^{-\epsilon}(D_x^2 + D_\theta^2 x^{2m}) u, u \rangle - O(\| (D_\theta)^{-\epsilon/2} u \|^2).
\]

**Proof of Theorem 6.2.** In the symbol calculus, the commutator $[(e^{-sf})^w, a^w]$ has principal symbol $H_{e^{-sf}}^w a$, but we will still need to control the remaining terms. Let
\[
R_1 = [(e^{-sf})^w, a^w] - (H_{e^{-sf}}^w a)^w.
\]
Then we have
\[
[(e^{-sf})^w + \tau, a^w] = (H_{e^{-sf}}^w a)^w + R_1.
\]
Applying this to \( u \) and taking an inner product with \( u \) we find the equality
\[
\left\langle [(e^{-s}f)p]u + \tau, a^w \right\rangle u, u = \left\langle (H_{e^{-s}f}a)^w u, u \right\rangle + \langle R_1 u, u \rangle.
\]
We can then apply the above Theorem 6.2 to find
\[
\left| \left\langle [(e^{-s}f)p]u + \tau, a^w \right\rangle u, u \right| \geq c \left| \left\langle (D_\theta)^-\epsilon (D_x^2 + D_\theta^2 x^{2m}) u, u \right\rangle - C \| (D_\theta)^{-\epsilon/2} u \|^2 \right.
\]
\[
- \left| \langle R_1 u, u \rangle \right|.
\]

Our goal is to bound \( \langle R_1 u, u \rangle \) from above in such a way that it can be absorbed into the term \( c \langle (D_\theta)^{-\epsilon} (D_x^2 + D_\theta^2 x^{2m}) u, u \rangle \).

The commutator \([(e^{-s}f)p]u, a^w] \) has symbol given by
\[
\sum_{k=0}^N \frac{j^k}{k!} \sigma(D)^k \left[ p(x, \xi, \theta, \eta) a(\tilde{x}, \tilde{\xi}, \tilde{\theta}, \tilde{\eta}) - (e^{-s}f)(\tilde{x}, \tilde{\xi}, \tilde{\theta}, \tilde{\eta}) a(x, \xi, \theta, \eta) \right]_{\text{diag}} + O(\langle \eta \rangle^{-\epsilon N}),
\]
where \( \mid \text{diag} \mid \) denotes evaluation along the diagonal, i.e. \( x = \tilde{x}, \xi = \tilde{\xi}, \theta = \tilde{\theta}, \) and \( \eta = \tilde{\eta}. \)

The bound on the error term is a result of the symbol class we are working in. Recall also from Theorem 2.3 that
\[
A(D) = \frac{1}{2} \left[ \langle (D_\xi, D_\eta), (D_\tilde{\xi}, D_\tilde{\eta}) \rangle - \langle (D_x, D_\theta), (D_\tilde{x}, D_\tilde{\theta}) \rangle \right].
\]

The first non-zero term in this expansion is \( H_{e^{-s}f}a. \) Because we are using the Weyl calculus, there are no even terms. Therefore, when applying this symbol expansion to write down \( R_1, \) the first term is
\[
\frac{r^3}{3!} A(D)^3 \left[ (e^{-s}f)p(x, \xi, \theta, \eta) a(\tilde{x}, \tilde{\xi}, \tilde{\eta}) - (e^{-s}f)(\tilde{x}, \tilde{\xi}, \tilde{\theta}, \tilde{\eta}) a(x, \xi, \theta, \eta) \right]_{\text{diag}}. \tag{22}
\]

Before expanding \( A(D)^3 \), we note that \( a \) does not depend on \( \theta, \) so there will be no terms involving \( \theta \) derivatives of \( a, \) and thus no terms involving \( \eta \) differences of \( e^{-s}f/p. \) We have to consider every combination of \( x, \xi, \) and \( \theta \) as the derivative we will be applying to \( e^{-s}f/p \) in \( \tag{22}. \) Because of the symbol class of \( a \) and \( p \) we know that we will gain 3 powers of \( \langle \eta \rangle^{-\epsilon}. \) We also know that if any derivative hits the term \( e^{-s}f \) then we will have gained a derivative of \( f \) and a factor of \( s. \) When this is the case, we can bound these above by
\[
C |s f_s| \langle \eta \rangle^{2-\epsilon} \Lambda(x), \tag{23}
\]
where \( f_s \) denotes some (first, second, or third) derivative of \( f. \) As long as we require \( |f_s| \leq C |x|^{2m-1} \) we find that \( \tag{23} \) is bounded above by \( C |s| \langle \eta \rangle^{2-\epsilon} |x|^{2m}. \)

The remaining term occurs when three \( x \) derivatives all hit \( p. \) This term is
\[
Ce^{-s}f(D_x^3 p)(D_x^3 a) = Ce^{-s}f(A^{-2})''(x) |\eta|^{2-3\epsilon} \Lambda(x) \Lambda''(\xi |\eta|^{-\epsilon}) \chi(x) \chi((\xi |\eta|^{-1}) \chi(\eta)) + r_2,
\]
where
\[
\text{supp} r_2 \subset \{|x| \geq \delta\} \cup \{|\xi| \geq \delta |\eta|\} \cup \{|\eta| \geq \delta\}.
\]
Because we will be applying our estimate only on functions microlocally supported away from the support of \( r_2, \) it will pose no problem to absorb this term. For now, we simply carry this term along.
We first note that
\[ |(A^{-2})''| \leq C|x|^{2m-3}. \]
Next note that
\[ |\Lambda(x)| \leq |x|. \]
Hence
\[ C|(A^{-2})''(x)|\eta|^{-2+3\epsilon}|\Lambda(x)\Lambda''(\xi\eta^{-1})\chi(x)(\xi\eta^{-1})(\chi(\eta))| \leq Cx^{2m-2}|\eta|^{2-3\epsilon}. \]
Next we need to control the symbol \( Cx^{2m-2}|\eta|^{2-3\epsilon} \).
When \(|x|^{-1} \leq c_0||\eta||^{\epsilon} \), we have
\[ |Cx^{2m-2}|\eta|^{2-3\epsilon}| \leq Cc_0x^{2m}|\eta|^{2-\epsilon}, \]
which can be absorbed into (21) as long as \( c_0 \) is small enough.
On the other hand, if \(|x| \leq (c_0)^{-1}|\eta|^{-\epsilon} \) then
\[ |Cx^{2m-2}|\eta|^{2-3\epsilon}| \leq C(c_0)^{-2m+2}|\eta|^{(1-2m)\epsilon}. \]
Because \( m \geq 2 \) and \(|\eta| \) is large, \(|\eta|^{(1-2m)} \) is small, so we may then absorb this term into \( \|D_\theta\|^{-\epsilon/2} u\|_{L^2}^2 \).
We may similarly bound \( A(D)^k p a \) for higher powers. Note that for every further term we write down in the expansion, the power of \(|\eta| \) in the remainder term is improved. This follows from the symbol class of \( e^{-sf} p \) and \( a \).
Before bounding the remainder term in this symbol expansion, we make a couple of notes. We know that \( e^{-sf} p \) satisfies the inequalities
\[ |\partial^\alpha_x \partial^\beta_\xi \partial^\gamma_\theta \partial^\delta_\eta (e^{-sf} p)| \leq C_{\alpha,\beta,\gamma,\delta} \langle \eta \rangle^{2-\epsilon(\beta+\delta)}. \]
As we stated before, \( a \) satisfies the inequalities for \( \langle \xi \rangle \lesssim \langle \eta \rangle \)
\[ |\partial^\alpha_x \partial^\beta_\xi \partial^\gamma_\theta \partial^\delta_\eta a| \leq C_{\alpha,\beta,\gamma,\delta} \langle \eta \rangle^{-\epsilon(\beta+\delta)}. \]
Let \( E_N \) denote the remainder term obtained after expanding the first \( N \) terms of the commutator \([P,a^w]\). Using our hybrid calculus, we know that \( E_N \) has symbol in the class \( S^0_{\epsilon-N\epsilon} \), hence
\[ \|E_N u\|_{L^2_{x,\theta}} \leq \|D_\theta\|^{2-\epsilon N} u\|_{L^2_{x,\theta}}. \]
By taking \( N \) large enough we will be able to absorb this term into our final lower bound.
Combining all this, we have shown
\[ |\left< e^{-sf} R_1 u, u \right>| \leq C\|u\|^2 + C(c_0 + |s|)(\langle D_\theta \rangle^{1-\epsilon/2} x^m)\|u\|^2, \]
where \( c_0 \) is small. Note that
\[ c\langle D_\theta \rangle^{-\epsilon} (D_x^2 + D_\theta^2 x^{2m})u, u \rangle - C(c_0 + |s|)\|(\langle D_\theta \rangle^{1-\epsilon/2} x^m)\|u\|^2 \]
\[ \geq \tilde{c}\langle D_\theta \rangle^{-\epsilon} (D_x^2 + D_\theta^2 x^{2m})u, u \rangle, \]
where \( \tilde{c} > 0 \) is smaller than \( c \).
In total we have found
\[ \left| \langle ((e^{-sf} p)^w + \tau), a^w \rangle \right| \geq c\langle D_\theta \rangle^{-\epsilon} (D_x^2 + D_\theta^2 x^{2m})u, u \rangle - C\|u\|^2. \]
We will now bound the left hand side from above. We expand the commutator to find
\[
\left| \left\langle \left( (e^{-sf}p)^w + \tau, a^w \right) u, u \right\rangle \right| \leq \left| \left\langle \left( (e^{-sf}p)^w + \tau \right) a^w u, u \right\rangle \right| + \left| \left\langle a^w (e^{-sf}p)^w + \tau) u, u \right\rangle \right|.
\]
Because \( a^w \) and \((e^{-sf}p)^w + \tau \) are self-adjoint, we can combine these terms and obtain the bound
\[
\left| \left\langle \left( (e^{-sf}p)^w + \tau, a^w \right) u, u \right\rangle \right| \leq 2 \left| \left\langle \left( (e^{-sf}p)^w + \tau \right) u, a^w u \right\rangle \right|.
\]
We now apply the identity operator, in the form \( \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} \langle D_\theta \rangle^{1/(m+1) + \epsilon/2} \), to the right hand side:
\[
\left| \left\langle \left( (e^{-sf}p)^w + \tau, a^w \right) u, u \right\rangle \right| \leq 2 \left| \langle D_\theta \rangle^{1/(m+1) + \epsilon/2} \left( (e^{-sf}p)^w + \tau \right) u, \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} a^w u \right| \leq C \| \langle D_\theta \rangle^{1/(m+1) + \epsilon/2} \left( (e^{-sf}p)^w + \tau \right) u \|_{L^2} \| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} a^w u \|_{L^2}.
\]
We compute:
\[
C \| \langle D_\theta \rangle^{1/(m+1) + \epsilon/2} \left( (e^{-sf}p)^w + \tau \right) u \|_{L^2} \| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} a^w u \|_{L^2} \leq C \| \langle D_\theta \rangle^{1/(m+1) + \epsilon/2} \left( (e^{-sf}p)^w + \tau \right) u \|_{L^2}^2 + \| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} a^w u \|_{L^2}^2.
\]
To estimate (24) we note that
\[
\| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} a^w u \|_{L^2} \leq C \| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} u \|_{L^2}.
\]
Furthermore if we expand the commutator \( \langle [\langle D_\theta \rangle^{1/(m+1) + \epsilon/2}, (e^{-sf}p)^w + \tau] \rangle \) using the symbol calculus and the condition on derivatives of \( f \) we find that we can bound the first \( N \) terms by
\[
C |s| |x|^m (\eta)^{1-\epsilon/2},
\]
and thanks to the gains in powers of \( |\eta|^{-\epsilon} \) we can guarantee that the remainder term has bounded symbol.

Thus we can bound (24) from above by
\[
C \left( \| (e^{-sf}p)^w + \tau \| \langle D_\theta \rangle^{1/(m+1) + \epsilon/2} u \| + |s| \| |x|^m \langle D_\theta \rangle^{1-\epsilon/2} u \| + \| u \| \right) \times \| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} u \|
\]
\[
\leq \| (e^{-sf}p)^w + \tau \| \langle D_\theta \rangle^{1/(m+1) + \epsilon/2} u \| \| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} u \|
\]
\[
+ c_1 \| \langle D_\theta \rangle^{1/(m+1) - \epsilon/2} u \|^2 + C c_1 (|u|^2 + (C c_1 |s|) |x|^m \langle D_\theta \rangle^{1-\epsilon/2} u \|, \]
where \( c_1 > 0 \) is very small. Note similarly to before that
\[
c \left( \| (e^{-sf}p)^w + \tau \| \langle D_\theta \rangle^{2} u \| + (C c_1 |s|) |x|^m \langle D_\theta \rangle^{1-\epsilon/2} u \| \right.
\]
\[
\geq c_0 \langle [\langle D_\theta \rangle^{2} (D^2 + D^2 x^{2m}) u] u \|,
\]
where \( c_0 > 0 \) is slightly smaller than \( c \), as long as \( s \) is sufficiently small.
Also note that since we are working microlocally where \(|\eta|\) is large,
\[ \|u\|^2 \ll c_1 \| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u \|^2. \]
We thus have the estimate
\[
\|((e^{-sf})^w + \tau) \langle D_\theta \rangle^{-1/(m+1)+\epsilon/2} u\| \| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u \|
\geq c \langle \langle D_\theta \rangle^{-\epsilon} (D_\theta^2 + D_\theta^2 x^{2m})u, u \rangle - 2c_1 \| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u \|^2.
\]
Applying Lemma 6.3 we then find
\[
\|((e^{-sf})^w + \tau) \langle D_\theta \rangle^{-1/(m+1)+\epsilon/2} u\| \| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u \|
\geq c\| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u\|^2 - 2c_1 \| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u \|^2
\geq c\| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u\|^2,
\]
as long as \(c_1\) is sufficiently small. Dividing through by \(\| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u\|\) we have the inequality
\[
\|((e^{-sf})^w + \tau) \langle D_\theta \rangle^{-1/(m+1)+\epsilon/2} u\| \geq c\| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u\|.
\]
Finally, plugging in \(\langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u\) we end up with the inequality
\[
\|((e^{-sf})^w + \tau)u\| \geq c\| \langle D_\theta \rangle^{1/2/(m+1)-\epsilon/2} u\|,
\]
which proves the theorem.

The following Lemma and its proof follows Lemma A.2 in [CW13].

**Lemma 6.3.** There exists \(c > 0\) such that
\[
\langle \langle D_\theta \rangle^{-\epsilon} (-\partial_x^2 - \partial_\theta^2 x^{2m})u, u \rangle \geq c\| \langle D_\theta \rangle^{1/(m+1)-\epsilon/2} u\|^2
\]
for all \(u \in S\) with microlocal support where \(\eta > 0\).

This lemma depends on the following result on the anharmonic oscillator (See [RS78]).

**Theorem 6.4.** Let \(P = -\partial_x^2 + x^{2m}\) with \(m \in \mathbb{Z}_{\geq 2}\). Then as an operator on \(L^2\) with domain \(S\), \(P\) is essentially self-adjoint and has pure point spectrum with eigenvalues \(\lambda_j \to \infty\). Every eigenfunction is in \(S\) and furthermore \(\lambda_0 > 0\).

**Proof of Lemma 6.3.** Letting \(\hat{u}\) denote the Fourier transform in only \(\theta\), we note
\[
\langle \langle -\partial_x^2 - \partial_\theta^2 x^{2m} \rangle u, u \rangle = \langle \langle -\partial_x^2 + \eta^2 x^{2m} \rangle \hat{u}, \hat{u} \rangle.
\]
This inner product is
\[
\sum_{\eta \in \mathbb{Z}} \left( \int ((-\partial_x^2 + \eta^2 x^{2m}) \hat{u}) \overline{\hat{u}} \, dx \right).
\]
We make the change of variables \(x = |\eta|^{-1/(m+1)} \tilde{x}\) to obtain
\[
\sum_{\eta \in \mathbb{Z}} |\eta|^{-1/(m+1)} \left( \int ((-|\eta|^{2/(m+1)} \partial_x^2 + |\eta|^{2-2m/(m+1)} x^{2m}) \hat{u}) \overline{\hat{u}} \, d\tilde{x} \right)
\geq c \sum_{\eta \in \mathbb{Z}} |\eta|^{1/(m+1)} \left( \int (-\partial_x^2 + \tilde{x}^{2m}) \hat{u} \overline{\hat{u}} \, d\tilde{x} \right).
\]
We then apply Lemma A.1 from [CW13] to find
\[
\sum_{\eta \in \mathbb{Z}} |\eta|^{1/(m+1)} \left( \int (-\partial_x^2 + \tilde{x}^{2m}) \hat{u} \, d\tilde{x} \right) \geq c \sum_{\eta \in \mathbb{Z}} |\eta|^{1/(m+1)} \hat{u} \, d\tilde{x} \\
= c \sum_{\eta \in \mathbb{Z}} |\eta|^{2/(m+1)} \hat{u} \, d\tilde{x} \\
\geq c \left< \langle D_\theta \rangle^{2/(m+1)} u, u \right>,
\]
where we have used the fact that this will only be applied to \( \hat{u} \) supported away from \( \eta = 0 \).

To achieve the result with \( \langle D_\theta \rangle^{-\epsilon} \) in front of the operator, we apply the inequality we have just proven to the function \( \langle D_\theta \rangle^{-\epsilon/2} \). Because \( \langle D_\theta \rangle^{-\epsilon/2} \) is self-adjoint and commutes with the operator \( \langle D_\theta \rangle^{-\epsilon} (-\partial_x^2 - \partial_\theta^2 \tilde{x}^{2m}) \), this proves the lemma. \( \Box \)

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