A Two Warehouse Inventory Model for Perishable Items with Ramp Type Demand and Partial Backlogging

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Abstract: In this paper, a two warehouse inventory model for perishable items with ramp type demand has been developed in which shortages are allowed and partially backlogged. The model so developed has been discussed for two scenarios: i) demand rate becomes constant before the time at which the inventory level reaches zero in rented warehouse ii) demand rate becomes constant when rented warehouse is empty and demand is fulfilled from own warehouse. Numerical example for each scenario has been solved to maximize the total profit and obtain optimal order quantity. Finally, sensitivity analysis has been carried out to analyze the behavior of presented model.

Keywords: Inventory, Two warehouse, Perishable, Ramp type, Partial Backlogging

1. INTRODUCTION
Perishable or deteriorating items are those, which have finite or limited shelf life. In inventory systems, decay or deterioration of physical goods (such as seasonal products, medicines, volatile liquids, etc.) with time is a natural phenomenon. Deterioration of goods during their normal storage period is major and realistic problem in any inventory system. Inventory models with deteriorating items have been progressively modified by various researchers in few decades to make them more practicable and realistic. The analysis of deteriorating inventory begun with Ghare and Schrader (1963), they established the classical inventory model without shortage and with a constant rate of decay. Goyal and Giri (2001) presented an excellent review in the field of inventory control of deteriorating items. Yang & Wee (2002) presented a production-inventory policy for deteriorating items with a constant production & demand rate. Ghosh and Chaudhuri (2004) developed an order level inventory model for deteriorating items considering two parameter Weibull distribution deterioration, and demand as a quadratic function of time. They solved model analytically and obtain optimal solution with a numerical example. He et al. (2010) developed an optimal production inventory model for deteriorating items, where manufacturers sold the goods to multiple markets with varying demands. An up-to-date review of published work about deteriorating inventory models for the period 2012-2015 was presented by Janssen et al. (2016). Sharma et al. (2018) analyzed an inventory model for deteriorating items assuming constant deterioration rate with expiry date and time varying cost. Khakzad and Gholamian (2020) introduced an inventory models for deteriorating items with advanced payment. In this model, they studied the effect of deteriorated items on deterioration rate of adjacent items and established a relationship between number of inspections and deterioration rate.

It is observed that demand of some useful newly launched products such as electronic goods and fashionable goods increases at the beginning and ultimately stabilizes and become constant. This kind of demand pattern seems to be quite realistic and is termed as “ramp type”. Thus, in case of ramp type demand, the demand increases linearly at the beginning and then the market grows into a stable stage such that the demand becomes a constant till the end of the inventory cycle. Hill (1995) first considered the inventory models for increasing demand followed by a constant demand and termed it as “ramp type” demand pattern. Wu (2001) developed an EOQ model with ramp type demand and partial backlogging. They assumed that partial backlogging rate depends on waiting time and next replenishment. Giri et al. (2003) extended the ramp type demand inventory model with a more generalized Weibull deterioration distribution. Manna & Chaudhuri (2006) analyzed an inventory models for deteriorating items considering ramp type demand rate, wherein the production rate is function of demand rate and deterioration rate is time proportional. Panda et al. (2008) developed an inventory model for perishable seasonal products with ramp-type demand. Skouri et al (2009) presented inventory models with ramp type demand rate, partial backlogging & Weibull deterioration rate. Sanni and Chukwu (2013) proposed an EOQ model with three parameter Weibull distribution deterioration, shortages and ramp type demand, and established necessary and sufficient conditions for the optimal replenishment policy. Wang and Huang (2014) studied a production inventory model for a seasonal deteriorating product. In this model, demand has been considered as price and ramp type dependent. Chandra (2017) discussed an inventory model with ramp type demand, price discount and backorders in which holding cost has been expressed as linearly increasing function of time. Saha et al. (2018) analyzed an inventory model for deteriorating items with ramp type demand and price discount under the effect of partial backlogging. Yadav et al. (2020) explained an inventory model for deteriorating items with stock dependent and ramp type demand considering reserve money and carbon emission.
The classical inventory models are mainly developed with the single storage facility. It implies that the available warehouse has unlimited capacity in those models. But in practice, the capacity of any warehouse is limited. When management has to purchase (or produce) large amount of units of an item that cannot be store in the existing warehouse (i.e. own warehouse, OW) at the market place due to its limited capacity then in such a situation excess units are stored in a rented warehouse (RW) which is located at some distance away from OW. Normally inventory managers decide to hold more items than that can be stored in OW when the replenishment cost is higher than the other related costs or the demand of items is very high or the managers are obtaining a attractive price discount on bulk purchase and so on. Here it is assumed that RW is sufficiently large i.e. it can be made large as per situation. Inventories are first stored in OW with excess going to RW. But while retrieving goods for consumption, it is always from RW first and when RW is empty then the goods are retrieved from OW as the storage conditions in RW are poor than in OW and holding cost is more in RW than in OW. A two warehouse inventory model was first developed by Hartley (1976). He considered the model in which holding cost of RW is greater than that in OW. Sarma (1983) extended Hartley’s model by introducing the transportation cost. Goswami & Chaudhuri (1992) developed the model with or without shortages by considering a linear demand, the equal shipment cycle. Zhou (1998) presented a two-warehouse model for deteriorating items with time-varying demand and shortages during the finite planning horizon. Dye et al. (2007) developed an inventory model for deteriorating items with capacity constraint and time-proportional backlogging rate. Rong et al. (2008) presented an optimization inventory policy for a deteriorating item with partially/fullbacklogged shortages and price dependent demand under two-warehouse system. Dey et al. (2008) proposed a two storage inventory problem with dynamic demand under inflation and time value of money over finite time horizon. Maity (2011) developed a two-warehouse production inventory problem under fuzzy inequality constraints. Sharma et al. (2013) presented a two-warehouse inventory model in which they evaluated impact of reduction rate in selling price with volume flexibility. Ranjan and Uthayakumar (2015) studied a two-warehouse inventory model for deteriorating items having time proportional backlogging rate. Dye (2007) formulated a joint pricing and ordering policy for deteriorating inventory. Shortages were allowed and partially backlogged. San-Jose and Garcia-Laguna (2009) presented an inventory model with full backlogging and all units quantity discounts. Hsieh & Dye (2010) developed an inventory lot size model for deteriorating items under inflation with partial backlogging over a finite planning horizon. Sharma and Singh (2013) proposed an inventory model for deteriorating items with partial backlogging considering stock and selling price dependent demand rate in fuzzy environment. Dutta and Kumar (2015) presented an inventory model having time dependent demand and holding cost under partial backlogging. Singh et al. (2016) analyzed an inventory model with multivariate demands in different phases and partial backlogging. In this model, effects of customer returns and inflation have been taken in to account. Singh et al. (2017) proposed a production inventory model for deteriorating items with time dependent demand rate and demand dependent production rate considering that shortages are allowed and partially backlogged. Singh et al. (2019) developed an inventory model for deteriorating items with partial backlogging assuming incremental holding cost.

Furthermore, Shortages occur in the system when the product required by the customers is not available. In this situation, the customer either waits for next replenishment or moves to other places to buy product. The length of the waiting time for the next replenishment would determine whether the backlogging will be accepted or not. Therefore, the backlogging rate should be variable and depends on the waiting time for the next replenishment. Many researchers such as Park (1982), Hollier and Mark (1983) and Wee (1995) considered the constant partial backlogging rate whereas researchers such as Abad (2000), Chang and Dye (2001), Wang (2002), Papachristos & Skouri (2003) have modified inventory policy by considering the time proportional partial backlogging rate. Dye (2007) formulated a joint pricing and ordering policy for deteriorating inventory. Shortages were allowed and partially backlogged. San-Jose and Garcia-Laguna (2009) presented an inventory model with full backlogging and all units quantity discounts. Hsieh & Dye (2010) developed an inventory lot size model for deteriorating items under inflation with partial backlogging over a finite planning horizon. Sharma and Singh (2013) proposed an inventory model for deteriorating items with partial backlogging considering stock and selling price dependent demand rate in fuzzy environment. Dutta and Kumar (2015) presented an inventory model having time dependent demand and holding cost under partial backlogging. Singh et al. (2016) analyzed an inventory model with multivariate demands in different phases and partial backlogging. In this model, effects of customer returns and inflation have been taken in to account. Singh et al. (2017) proposed a production inventory model for deteriorating items with time dependent demand rate and demand dependent production rate considering that shortages are allowed and partially backlogged. Singh et al. (2019) developed an inventory model for deteriorating items with partial backlogging assuming incremental holding cost.

The structure of presented article is as follows. Notations and assumptions used throughout the paper have been given in Section 2. In section 3, a two ware house inventory model for perishable items with ramp type demand and partial backlogging has been formulated. In this section model is developed for two realistic scenarios. Also, numerical example has been solved (to maximize total profit and obtained optimal ordering quantity) and sensitivity analysis is carried out with respect to parameters to show the behavior of model in each scenario. The paper has been closed with conclusion in section 4.

2. ASSUMPTIONS AND NOTATION

To develop the present mathematical model the assumptions and notations adopted are as follows:

ASSUMPTIONS
1. Replenishment is instantaneous, and lead time is zero.
2. A single item is considered over a prescribed period of time.
3. The time horizon of the inventory system is finite.
4. The owned warehouse (OW) has a fixed capacity of W units; the rented warehouse (RW) has unlimited capacity.
5. The goods of OW are consumed only after consuming the goods kept in RW.

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6. To guarantee the optimal solution exists, it is assumed that the maximum deteriorating quantity for items in OW, \( \theta_2 W \), is less than the demand rate \( D(t) \); that is, \( \theta_2 W < D(t) \).

7. The unit inventory costs (including holding cost and deterioration cost) per unit time in RW are higher than those in OW; that is, \( C_{11} + \theta_1 c > C_{12} + \theta_2 c \).

8. Shortages are allowed. Unsatisfied demand is backlogged, and the fraction of shortages backordered is \( \frac{1}{1 + \delta x} \), where \( x \) is the waiting time up to the next replenishment and \( \delta \) is a positive constant.

**NOTATIONS**

1. \( D(t) = B_0 - \frac{B_t}{a + t}, B_0, B_t > 0, a > 0 \) and \( B_0 > \frac{B_t}{a} \) be the deterministic demand rate per unit time, which increases with time at a decreasing rate.
2. \( A \) is the replenishment cost per order
3. \( c \) is the purchasing cost per unit
4. \( s \) is the selling price per unit, where \( s > c \)
5. \( W \) is the capacity of the owned warehouse
6. \( Q \) is the ordering quantity per cycle
7. \( I_m \) is the maximum inventory level per cycle
8. \( C_{11} \) is the holding cost per unit per unit time in RW
9. \( C_{12} \) is the holding cost per unit per unit time in OW, where \( C_{11} > C_{12} \)
10. \( C_2 \) is the shortage cost per unit per unit time
11. \( C_3 \) is the opportunity cost due to lost sales per unit per unit time
12. \( \theta_1 \) is the deterioration rate in RW, where \( 0 < \theta_1 < 1 \)
13. \( \theta_2 \) is the deterioration rate in OW, where \( 0 < \theta_2 < 1 \)
14. \( T \) is the length of the replenishment cycle
15. \( t_1 \) is the time at which the inventory level reaches zero in RW
16. \( t_2 = kT \) is the length of period during which the inventory level depletes in OW due to both demand and deterioration where \( 0 < k < 1 \)
17. \( I_{RW}(t) \) is the level of positive inventory in RW at time \( t \)
18. \( I_{OW}(t) \) is the level of positive inventory in OW at time \( t \)
19. \( I_B(t) \) is the level of negative inventory at time \( t \)
20. \( \psi = k_1 T \) is the known time at which demand \( D(t) \) becomes constant where \( 0 < k_1 < 1 \)

3. **FORMULATION AND SOLUTION OF THE MODEL**

There may be two scenarios in the discussion of formulation of the present model according to the position of time \( \psi \) when demand rate becomes constant.

3.1. **Scenario-1: When \( 0 \leq \psi \leq t_1 \)**

In this scenario the demand rate becomes constant during the period when demand is fulfilled from RW only. Therefore the following time intervals \([0, \psi], [\psi, t_1], [0, t_1] \) and \([t_1 + t_2, T]\) are considered separately. During the interval \([0, \psi]\), the inventory levels are depleted from RW and OW. In RW, the inventory is depleted due to the combined effects of demand and deterioration and in OW, the inventory is depleted only by the effect of deterioration. During the interval \([\psi, t_1]\), the only change in the equation of formulation is that the demand becomes \( D(\psi)(a \text{ constant}) \) at RW and the inventory level reaches...
zero at time \( t_1 \) in RW. During the interval \([0, t_2]\), the inventory level in RW is zero and thus the inventory is depleted due to the combined effects of demand \( D(\psi) \) and deterioration in OW. Furthermore, at time \( t_1 + t_2 \), the inventory level reaches zero in OW. Period \([t_1 + t_2, T]\) is stock-out period and some demand is lost while a fraction \( \frac{1}{1+\delta(T-t)} \) of the demand is backlogged. The graphical representation of the model is shown in Figure 3.1.

Thus during the cycle \((0, T)\) the inventory levels \( I_{RW}(t), I_{OW}(t) \) and \( I_{B}(t) \) at RW and OW are governed by the following differential equations:

\[
\frac{dI_{RW}(t)}{dt} + \theta I_{RW}(t) = -\left( B_0 - \frac{B_1}{a+t} \right), \quad 0 \leq t \leq \psi, \quad (3.1.1)
\]

\[
\frac{dI_{RW}(t)}{dt} + \theta I_{RW}(t) = -D(\psi), \quad \psi \leq t \leq t_1, \quad (3.1.2)
\]

\[
\frac{dI_{OW}(t)}{dt} + \theta_2 I_{OW}(t) = 0, \quad 0 \leq t \leq t_1, \quad (3.1.3)
\]

\[
\frac{dI_{OW}(t)}{dt} + \theta_2 I_{OW}(t) = -D(\psi), \quad t_1 \leq t \leq t_2, \quad (3.1.4)
\]

\[
\frac{dI_{B}(t)}{dt} = \frac{D(\psi)}{1+\delta(T-t)}, \quad t_1 + t_2 \leq t \leq T, \quad (3.1.5)
\]

with boundary conditions \( I_{RW}(0) = I_m - W, \quad I_{RW}(t_1) = 0, \quad I_{OW}(0) = W, \quad I_{OW}(t_2) = 0 \) and \( I_{B}(t_1 + t_2) = 0 \).

The solutions of above first order ordinary differential equations (3.1.1-3.1.5) are given as follows:
\[ I_{ RW}(t) = (I_m - W)(1 - \theta t) - B_0 \left( t - \frac{\theta t^2}{2} \right) + B_1 \left( \theta t + (1 - a \theta_i - \theta t)(\log(a + t) - \log a) \right), \]
\[ 0 \leq t \leq \psi, \quad (3.1.6) \]
\[ I_{ RW}(t) = \left( t_1 - t - \theta t_1 t + \frac{\theta t_1^2}{2} + \frac{\theta t_2^2}{2} \right) D(\psi), \quad \psi \leq t \leq t_1, \quad (3.1.7) \]
\[ I_{ OW}(t) = W(1 - \theta t), \quad 0 \leq t \leq t_1, \quad (3.1.8) \]
\[ I_{ OW}(t) = \left( t_2 - t - \theta t_2 t + \frac{\theta t_2^2}{2} + \frac{\theta t_2^2}{2} \right) D(\psi), \quad t_1 \leq t \leq t_2, \quad (3.1.9) \]
\[ I_B(t) = -\frac{D(\psi)}{\delta} \left\{ \log \left[ 1 + \delta (T - t_1 - t_2) \right] - \log \left[ 1 + \delta (T - t) \right] \right\}, \quad t_1 + t_2 \leq t \leq T. \quad (3.1.10) \]

Due to continuity of \( I_{ OW}(t) \) at point \( t = t_1 \), it follows from equations (3.1.8) and (3.1.9),
\[ W(1 - \theta t_1) = \left( t_2 + \frac{\theta t_2^2}{2} \right) D(\psi) \]

This implies that
\[ t_1 = \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta t_2^2}{2} \right) \quad (3.1.11) \]

It notes that \( t_1 \) is a function of \( t_2 \). Then taking the first-order derivative of \( t_1 \) with respect to \( t_2 \), gives
\[ \frac{dt_1}{dt_2} = \frac{D(\psi)}{W \theta W} (1 + \theta_2 t_2) < 1 \]

Thus \( \frac{dt_1}{dt_2} - 1 < 0 \) holds.

The ordering quantity over the replenishment cycle is determined as
\[ Q = I_{ RW}(0) + I_{ OW}(0) - I_B(T) = I_m + \frac{D(\psi)}{\delta} \log (1 + \delta (T - t_1 - t_2)) \quad (3.1.12) \]

Due to the continuity of \( I_{ RW}(t) \) at point \( t = \psi \), the maximum inventory level is obtained from equations (3.1.6) and (3.1.7)
\[ I_m = W + \frac{1}{1 - \theta \psi} \left[ \left( t_1 - \psi - \theta t_1 \psi + \frac{\theta t_1^2}{2} + \frac{\theta \psi^2}{2} \right) D(\psi) + B_0 \left( \psi - \frac{\theta \psi^2}{2} \right) - B_1 \left( \theta \psi + (1 - a \theta - \theta \psi) \log \frac{a + \psi}{a} \right) \right] \quad (3.1.13) \]

Based on above equations, profit per replenishment cycle consists of the following elements:

Ordering cost is \( C_r = A \).

(3.1.14)

Holding cost in RW is
\[ C_{ RW} = C_{11} \left[ \int_0^\psi I_{ RW}(t) dt + \int_\psi^\infty I_{ RW}(t) dt \right] \]
\[ = C_{11} \psi \left( 1 - \theta \psi \right) \left[ \frac{1}{1 - \theta \psi} \left( \frac{D(\psi)}{\theta^2} \left( t_2 + \frac{\theta t_2^2}{2} \right) - \psi \right) - \frac{1}{\theta} \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta t_2^2}{2} \right) \right] \]
\[ + \frac{\theta}{2} \left( \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta t_2^2}{2} \right) \right) \]
\[ + B_0 \left( \psi - \frac{\theta \psi^2}{2} \right) - B_1 \left( \theta \psi + (1 - a \theta - \theta \psi) \log \frac{a + \psi}{a} \right) \]
\[ + \frac{\theta}{2} \left( \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta t_2^2}{2} \right) \right) + B_0 \left( \psi - \frac{\theta \psi^2}{2} \right) - B_1 \left( \theta \psi + (1 - a \theta - \theta \psi) \log \frac{a + \psi}{a} \right) \]
\[-B_0 C_{11} \left\{ \frac{\psi^2}{2} - \frac{\theta_0 \psi^3}{6} \right\} + B_1 C_{11} \left\{ -\psi + \frac{a \theta_0 \psi}{2} \right\} + B_2 C_{11} \left\{ \psi - a \theta_0 \psi - \frac{\theta_0 \psi^2}{2} + a - \frac{a^2 \theta_0}{2} \right\} \log \left( \frac{a + \psi}{a} \right) \]

\[+ C_{11} D(\psi) \left\{ \frac{1}{2} \frac{1 - D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - \psi \right\}^2 + \frac{1}{6} \left\{ \frac{1 - D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - \psi \right\}^3 \right\}. \] (3.1.15)

Holding cost in OW is

\[C_{\text{H}} = C_{12} \int_0^{t_2} I_{\text{OW}}(t) dt + \int_0^{t_2} I_{\text{OW}}(t) dt \]

\[= C_{12} W \left\{ \left( \frac{1}{2} \frac{1 - D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - \psi \right) + \frac{1}{6} \left( \frac{1 - D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - \psi \right) \right\}. \] (3.1.16)

Shortage cost is

\[C_S = -C_2 \int_0^{T} I_B(t) dt \]

\[= C_2 D(\psi) \left[ \delta (T - t_1 - t_2) - \log \left\{ 1 + \delta (T - t_1 - t_2) \right\} \right] = \frac{C_2 D(\psi)}{\delta} \left[ \delta \left( T - \frac{1}{2} \frac{D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - t_2 \right) \right. \]

\[\left. - \log \left\{ 1 + \delta \left( T - \frac{1}{2} \frac{D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - t_2 \right) \right\} \right]. \] (3.1.17)

Opportunity cost due to lost sales is

\[C_{\text{OR}} = C_2 \int_{t_2}^{T} D(\psi) \left[ 1 - \frac{1}{1 + \delta (T - t)} \right] dt \]

\[= C_2 D(\psi) \left[ \delta (T - t_1 - t_2) - \log \left\{ 1 + \delta (T - t_1 - t_2) \right\} \right] = \frac{C_2 D(\psi)}{\delta} \left[ \delta \left( T - \frac{1}{2} \frac{D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - t_2 \right) \right. \]

\[\left. - \log \left\{ 1 + \delta \left( T - \frac{1}{2} \frac{D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - t_2 \right) \right\} \right]. \] (3.1.18)

Purchase cost is

\[C_p = cQ \]

\[= c \left[ I_m + \frac{D(\psi)}{\delta} \log \left\{ 1 + \delta (T - t_1 - t_2) \right\} \right] \]

\[= c W + \frac{c D(\psi)}{1 - \theta_0 \psi} \left[ \frac{1}{2} \frac{D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) - \psi - \theta_0 \psi \left( \frac{1}{2} \frac{D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) \right) \right] \]

\[+ \frac{\theta_0 \psi}{2} \left[ \frac{1}{2} \frac{D(\psi)}{W \theta_0} \left( t_2 + \frac{\theta_0 \psi^2}{2} \right) \right] + \frac{c B_0}{(1 - \theta_0 \psi)} \left( \frac{\psi}{2} - \frac{\theta_0 \psi^2}{2} \right) - \frac{c B_1}{(1 - \theta_0 \psi)} \left( \psi + (1 - a \theta_1 - \theta_0 \psi) \log \left( \frac{a + \psi}{a} \right) \right) \]
\[ \frac{cD(\psi)}{\delta} \log \left\{ 1 + \delta \left\{ T - \frac{1}{\theta_2} + D(\psi) \left( \frac{t_2 + \frac{\theta_2 t_2^2}{2}}{2} \right) \right\} \right\}. \]

(3.1.19)

Sales revenue is

\[ SR = s \left[ D(\psi) dt + \frac{t_1}{\psi} D(\psi) dt + \frac{t_1}{\theta_1} D(\psi) dt + \frac{T}{1 + \delta(T - t)} dt \right] = s \left\{ B_0 \psi - B_1 \log \left( \frac{a + \psi}{a} \right) + D_1 \log a \right\} \]

\[ + sD(\psi) t_2 + sD(\psi) \left\{ \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right\} + \frac{sD(\psi)}{\delta} \log \left\{ 1 + \delta \left\{ T - \frac{1}{\theta_2} + D(\psi) \left( \frac{t_2 + \frac{\theta_2 t_2^2}{2}}{2} \right) \right\} \right\}. \]

(3.1.20)

Consequently, the total profit of the system per replenishment cycle can be formulated as:

\[ P(t_2) = SR - C_p - C_c - C_{D_{aRW}} - C_{D_{aOW}} - C_S - C_{OOP} \]

\[ = s \left\{ B_0 \psi - B_1 \log \left( \frac{a + \psi}{a} \right) \right\} + sD(\psi) t_2 + sD(\psi) \left\{ \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right\} \]

\[ + \frac{D(\psi)}{\delta} \left( s + \frac{C_2}{\delta} + C_3 - c \right) \log \left\{ 1 + \delta \left\{ T - \frac{1}{\theta_2} + D(\psi) \left( \frac{t_2 + \frac{\theta_2 t_2^2}{2}}{2} \right) \right\} \right\} \]

\[ - \frac{A}{2} \left( 1 + \frac{C_1 \psi (1 - \theta_2)}{(1 - \theta_2) \psi} \right) \left\{ D(\psi) \left( \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right) \right\} \]

\[ - B_1 \left( \theta_2 \psi + (1 - a) \theta_2 \log \left( \frac{a + \psi}{a} \right) \right) \]

\[ = s \left\{ B_0 \psi - B_1 \log \left( \frac{a + \psi}{a} \right) \right\} + sD(\psi) t_2 + sD(\psi) \left\{ \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right\} \]

\[ + \frac{D(\psi)}{\delta} \left( s + \frac{C_2}{\delta} + C_3 - c \right) \log \left\{ 1 + \delta \left\{ T - \frac{1}{\theta_2} + D(\psi) \left( \frac{t_2 + \frac{\theta_2 t_2^2}{2}}{2} \right) \right\} \right\} \]

\[ - \frac{A}{2} \left( 1 + \frac{C_1 \psi (1 - \theta_2)}{(1 - \theta_2) \psi} \right) \left\{ D(\psi) \left( \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right) \right\} \]

\[ - B_1 \left( \theta_2 \psi + (1 - a) \theta_2 \log \left( \frac{a + \psi}{a} \right) \right) \]

\[ - B_1 \left( \theta_2 \psi + (1 - a) \theta_2 \log \left( \frac{a + \psi}{a} \right) \right) \]

\[ + \frac{1}{3} \left\{ 1 - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right\} \left\{ \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right\} \left\{ \frac{1}{\theta_2} - \frac{D(\psi)}{W \theta_2} \left( t_2 + \frac{\theta_2 t_2^2}{2} \right) \right\} \]

\[ - \frac{C_2}{\delta} \left\{ \frac{t_2^2}{2} + \frac{\theta_2 t_2^3}{6} \right\}. \]

(3.1.21)

Using \( t_2 = kT, \psi = kT \)

\[ P(k) = s \left\{ B_0 kT - B_1 \log \left( \frac{a + kT}{a} \right) \right\} + sD(kT) kT + sD(kT) \left\{ \frac{1}{\theta_2} - \frac{D(kT)}{W \theta_2} \left( kT + \frac{\theta_2 kT^2}{2} \right) \right\} - kT \]

\[ + \frac{D(kT)}{\delta} \left( s + \frac{C_2}{\delta} + C_3 - c \right) \log \left\{ 1 + \delta \left\{ T - \frac{1}{\theta_2} + D(kT) \left( kT + \frac{\theta_2 kT^2}{2} \right) \right\} \right\}. \]
\[-A - \left( \frac{c + C_1 kT (1 - \theta_1 kT)}{(1 - \theta_1 kT)} \right) \left[ D(k,T) \left( \frac{1}{\theta_2} - \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) \right) - kT \right] \]
\[-\theta_1 kT \left( \frac{1}{\theta_2} - \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) \right) + \theta_1 \left( \frac{1}{\theta_2} - \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) \right)^2 + \frac{\theta_1 kT}{2} \]
\[+B_0 \left( kT - \frac{\theta_1 k^2 T^2}{2} \right) - B_1 \left( \theta_1 kT + (1 - a\theta_1 - kT\theta_1) \log \frac{a + kT}{a} \right) \]
\[- \left( \frac{C_2}{\delta} + C_3 \right) D(k,T) \left[ T - \frac{1}{\theta_2} + \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) - kT \right] - \frac{2}{3} \left( \frac{C_2}{\delta} + C_3 \right) \left( T - \frac{1}{\theta_2} + \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) - kT \right)^2 \]
\[-B_1 C_{11} \left( kT + a\theta_1 kT \right) - B_1 C_{11} \left( kT - a\theta_1 kT - \frac{\theta_1 k^2 T^2}{2} \right) + a - \frac{\theta_1 k^2 T^2}{2} \log \frac{a + kT}{a} \]
\[- \frac{C_{11} D(k,T)}{2} \left[ \frac{1}{\theta_2} - \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) \right] - \frac{\theta_1}{\theta_2} \left( \frac{1}{\theta_2} - \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) \right)^2 \]
\[-C_{12} D(k,T) \left\{ \frac{k_2 T^2}{2} + \frac{\theta_1 k_3 T^3}{6} \right\} \]

(3.1.22)

### 3.1.2. Solution Procedure

The profit \( P(k) \) is a function of single variable \( k \) where \( k \) is a continuous variable. The necessary condition for \( P(k) \) to be maximized is

\[
\frac{dP(k)}{dk} = 0 \quad (3.1.23)
\]

Provided \( \frac{d^2 P(k)}{dk^2} < 0 \)

Equation (3.1.23) is equivalent to

\[
sD(k,T)T - sD^2(k,T)T + D(k,T) + s + \frac{C_2}{\delta} + C_3 - c \left\{ \frac{D(k,T)}{W\theta_2} (T + \theta_2 kT^2) \right\} - T
\]

\[
\left\{ 1 + \delta \left\{ T - \frac{1}{\theta_2} + \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) - kT \right\} \right\}
\]

\[
- \frac{C_{11} D(k,T)}{2} \left( 1 - \theta_1 kT \right) \left\{ D(k,T) \left( 1 - \theta_1 kT \right) - \frac{D(k,T)}{W\theta_2} \left( T + \theta_2 kT^2 \right) \right\}
\]

\[
- \frac{\theta_1 D(k,T)}{W\theta_2} \left( T + \theta_2 kT^2 \right) \left\{ \frac{1}{\theta_2} - \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) \right\} \left\{ \frac{C_2}{\delta} + C_3 \right\} D(k,T) \left( \frac{D(k,T)}{W\theta_2} (T + \theta_2 kT^2) \right) - T
\]

\[
- \frac{C_{12} D(k,T)}{2} \left\{ \frac{2D(k,T)}{W\theta_2} (T + \theta_2 kT^2) \left\{ \frac{1}{\theta_2} - \frac{D(k,T)}{W\theta_2} \left( kT + \frac{\theta_2 k^2 T^2}{2} \right) \right\} \right\}
\]
Furthermore, the total profit \( P = 74 \) is highly sensitive with respect to model parameter \( B_0 \), whereas it is slightly sensitive with respect to model parameters \( B_1, a, \delta, W \) and \( \psi \). Furthermore, the total profit \( P \) is highly sensitive with respect to model parameter \( B_0 \), while it is slightly sensitive with respect to model parameters \( B_1, a, \delta, W \) and \( \psi \).
3.2. **Scenario-2: When** \( t_1 \leq \psi \leq t_1 + t_2 \)

This is the scenario where the demand becomes constant \( D(\psi) \) when rented warehouse is empty and demand is fulfilled from OW. Therefore the following time intervals \([0,t_1],[0,\psi],[\psi,t_2] \) and \([t_1 + t_2,T]\) are considered separately. During the interval \([0,t_1]\), the inventory is depleted due to the combined effects of demand and deterioration from RW and the inventory is depleted only by the effect of deterioration from OW. During the interval \([0,\psi]\), the inventory level in RW is zero and thus the inventory level at OW is depleted due to the combined effects of variable demand and deterioration. During the interval \([\psi,t_2]\), the only change in the equation formulation in OW is that the demand becomes \( D(\psi) \), a constant at OW. Furthermore, at time \( t_1 + t_2 \), the inventory level reaches zero in OW and shortage starts to occur. During \([t_1 + t_2,T]\), some demand is lost while a fraction \( \frac{1}{1+\delta(T-t)} \) of the demand is backlogged. A graphical representation of this scenario of the model is shown below in figure 3.2.

![Figure 3.2](image-url)

Thus during the cycle \([0,T]\) the inventory levels \( I_{\text{RW}}(t), I_{\text{OW}}(t) \) and \( I_b(t) \) at RW and OW are governed by the following differential equations:

\[
\frac{dI_{\text{RW}}(t)}{dt} + \theta_1 I_{\text{RW}}(t) = -\left( B_0 - \frac{B_1}{a+t} \right), \quad 0 \leq t \leq t_1, \quad (3.2.1)
\]

\[
\frac{dI_{\text{OW}}(t)}{dt} + \theta_2 I_{\text{OW}}(t) = 0, \quad 0 \leq t \leq t_1, \quad (3.2.2)
\]

\[
\frac{dI_{\text{OW}}(t)}{dt} + \theta_2 I_{\text{OW}}(t) = -\left[ B_0 - \frac{B_1}{a+t} \right], \quad t_1 \leq t \leq \psi, \quad (3.2.3)
\]

\[
\frac{dI_{\text{OW}}(t)}{dt} + \theta_2 I_{\text{OW}}(t) = -D(\psi), \quad \psi \leq t \leq t_2, \quad (3.2.4)
\]
\[
\frac{dI_B(t)}{dt} = \frac{D(\psi)}{1+\delta(T-t)}, \quad t_1+t_2 \leq t \leq T,
\] (3.2.5)

with boundary conditions, \( I_{RW}(t_1) = 0, \ I_{ow}(0) = W, \ I_{ow}(t_1) = W(1-a_1t_1). \ I_{ow}(t_2) = 0 \) and \( I_B(t_1+t_2) = 0. \)

The solutions of above ordinary differential equations (3.2.1-3.2.5) have been given below:

\[
I_{RW}(t) = B_0 \left[ (t_1-t)+\frac{\theta_1}{2}(t_1-t)^2 \right] - B_1 \left[ \theta_1(t_1-t) + (1-a\theta_1-\theta_1) \left\{ \log (a+t_1) - \log (a+t) \right\} \right],
\]

\[0 \leq t \leq t_1, \quad (3.2.6)\]

\[
I_{ow}(t) = W(1-\theta_2t), \quad 0 \leq t \leq t_1,
\] (3.2.7)

\[
I_{ow}(t) = W(1-\theta_2t-\theta_2t_1) - B_0 \left[ t-\frac{\theta_1^2}{2} \right] - B_1 \left[ \theta_1t+(1-a\theta_2-\theta_2)t \left\{ \log (a+t) - \log a \right\} \right], \quad t_1 \leq t \leq \psi,
\] (3.2.8)

\[
I_{ow}(t) = D(\psi) \left[ t_2-t + \frac{\theta_2t_2^2}{2} + \frac{\theta_2^2t_2^3}{2} - \theta_2t_2\psi \right], \quad \psi \leq t \leq t_2,
\] (3.2.9)

\[
I_B(t) = -\frac{D(\psi)}{\delta} \left[ \log \left\{ 1+\delta(T-t_1-t_2) \right\} - \log \left\{ 1+\delta(T-t) \right\} \right], \quad t_2 \leq t \leq T.
\] (3.2.10)

Due to continuity of \( I_{ow}(t) \) at point \( t = \psi \), it follows from equations (3.2.8) and (3.2.9),

\[
W(1-\theta_2\psi-\theta_2t_1) - B_0 \left[ \psi - \frac{\theta_1^2}{2} \right] - B_1 \left[ \theta_2\psi + (1-a\theta_2-\theta_2) \left\{ \log (a+\psi) - \log a \right\} \right]
\]

\[
= D(\psi) \left\{ t_2-\psi + \frac{\theta_2t_2^2}{2} + \frac{\theta_2^2t_2^3}{2} - \theta_2t_2\psi \right\}.
\]

This implies that

\[
t_1 = E - \frac{D(\psi)}{W\theta_2} \left\{ t_2-\psi + \frac{\theta_2t_2^2}{2} + \frac{\theta_2^2t_2^3}{2} - \theta_2t_2\psi \right\},
\] (3.2.11)

Where \( E = -\frac{B_0}{W\theta_2} \left[ \psi - \frac{\theta_1^2}{2} \right] - \left( 1-\theta_2\psi \right) \frac{\theta_1}{\theta_2} + \frac{B_1}{W\theta_2} \left[ \theta_2\psi + (1-a\theta_2-\theta_2) \log \left( \frac{a+\psi}{a} \right) \right] \).

It notes that \( t_1 \) is a function of \( t_2 \). Then taking the first-order derivative of \( t_1 \) with respect to \( t_2 \), gives

\[
\frac{dt_1}{dt_2} = -\frac{D(\psi)}{W\theta_2} \left\{ 1+\theta_2t_2-\theta_2\psi \right\} < 1
\]

Thus \( \frac{dt_2}{dt_1} - 1 < 0 \) holds

The ordering quantity over the replenishment cycle can be determined as

\[
Q = I_{RW}(0) + I_{ow}(0) - I_B(T)
\]

\[
= I_m + \frac{D(\psi)}{\delta} \log \left\{ 1+\delta(T-t_1-t_2) \right\}.
\] (3.2.12)

And the maximum inventory level per cycle \( I_m \) is given by

\[
I_m = I_{RW}(0) + I_{ow}(0)
\]

\[
= B_0 \left[ t_1 + \frac{\theta_1t_1^2}{2} \right] - B_1 \left[ \theta_1t_1 + (1-a\theta_1) \left\{ \log (a+t_1) - \log a \right\} \right] + W.
\] (3.2.13)
Based on above equations, profit per replenishment cycle consists of the following elements:

Ordering cost per cycle is \( C_r = A \). (3.2.14)

Holding cost in RW is

\[
C_{hRW} = C_{11} \int_0^t I_{RW}(t) \, dt \\
= B_0 C_{11} \left[ \frac{1}{2} \left( E - \frac{D(\psi)}{W \theta_2} \left\{ t_2 - \psi + \frac{\theta_2 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right)^2 + \frac{\theta}{6} \left( E - \frac{D(\psi)}{W \theta_2} \left\{ t_2 - \psi + \frac{\theta_2 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right)^2 \right] + B_1 C_{11} \left( a - a^2 \theta_1 \right)
\]

Holding cost in OW is

\[
C_{hOW} = C_{12} \left[ \int_0^t I_{OW}(t) \, dt + \int_0^t I_{OW}(t) \, dt + \int_0^t I_{OW}(t) \, dt \right] = WC_{12} \left[ \left( E - \frac{D(\psi)}{W \theta_2} \left\{ t_2 - \psi + \frac{\theta_2 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right)^2 + \frac{\theta}{2} \left( E - \frac{D(\psi)}{W \theta_2} \left\{ t_2 - \psi + \frac{\theta_2 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right)^2 \right] + C_{12} W \left( \psi - \frac{\theta_2 \psi^2}{2} - \theta_2 \psi \right)
\]

Shortage cost is

\[
C_s = -C_{12} \int_{t_1}^{t_2} I_s(t) \, dt
\]

\[
= \frac{C_{12} D(\psi)}{\delta^2} \left[ \delta (T - t_2 - t_1) - \log \left\{ 1 + \delta (T - t_2 - t_1) \right\} \right]
\]
\[ C_p = c \cdot Q \]
\[
= c \left[ I_m + \frac{D(\psi)}{\delta} \log \left\{ 1 + \delta(T - t_i - t_f) \right\} \right] = cB_0 \left\{ E - \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} \right\}
\]
\[
+ \theta_1 \left\{ E - \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} \right\}^2 \right\} - cB_1 \left\{ E - \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} \right\}
\]
\[
+ (1 - a\theta) \left\{ \log \left\{ a + E - \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} \right\} \log a \right\} + cW
\]
\[
+ \frac{cD(\psi)}{\delta} \log \left\{ 1 + \delta \left( T - E + \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} - t_2 \right) \right\}. \] (3.2.19)

Sales revenue is
\[ SR = s \left[ \int_0^{t_i} D(t) dt + \int_{t_i}^{t_2} t_i \cdot t_2 \cdot D(t) dt + \int_{t_i}^{t_2} D(\psi) dt + \int_{t_i}^{t_2} \frac{D(\psi)}{1 + \delta(T - t)} dt \right]
\]
\[
= sB_0 \left\{ \psi + E - \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} \right\} - sB_1 \log \left\{ a + \psi + E \right\}
\]
\[
- \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} + \alpha \left\{ a + sD(\psi)(t_2 - \psi) \right\}
\]
\[
+ \frac{sD(\psi)}{\delta} \log \left\{ 1 + \delta \left( T - E + \frac{D(\psi)}{\theta_2} \left\{ t_2 - \psi + \frac{\theta t_2^2}{2} + \frac{\theta \psi^2}{2} - \theta t_2 \psi \right\} - t_2 \right) \right\}. \] (3.2.20)

Consequently, the total profit of the system per replenishment cycle can be formulated as:
\[ P(t_2) = SR - C_P - C_r - C_{\text{KRW}} - C_{\text{COW}} - C_S - C_{\text{OP}} \]
\[ = sB_0 \left\{ \psi + E - \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right\} - sB_1 \log \left\{ a + \psi + E \right\} \]
\[ - \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \]
\[ + \frac{(s-c)D(\psi)}{\delta} \log \left\{ 1 + \delta - \frac{T - E + \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} - t_2 \right\} - A \]
\[ + \left\{ -cB_0 + cB_1 \theta_1 - C_{12} W + C_{11} B_1 (1 - a\theta_1) \right\} \left\{ E - \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right\} \]
\[ + \left\{ -cB_0 + cB_1 \theta_1 + C_{12} W \theta_2 + C_{11} B_1 \theta_1 \right\} \left\{ E - \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right\} \]
\[ + \left\{ -C_{12} W \psi - \frac{\theta_1 \psi^2}{2} - \theta_2 \psi \right\} \left\{ E - \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right\} \]
\[ + \left\{ -C_{11} B_1 \left\{ \psi + a\theta_1 \psi - \frac{\theta_2 \psi^2}{2} + a - \frac{\theta_1 \psi}{2} \right\} \right\} \log \left\{ a + \frac{\psi}{a} \right\} \]
\[ - \left\{ -C_{12} D(\psi) \left\{ t_2^2 + \frac{\psi^2}{2} - \frac{\theta_2 t_2^3}{2} + \frac{\theta_1 \psi^2}{2} + \frac{\theta_1 \theta_2 \psi^3}{6} - \frac{\theta_2 t_2 \psi^3}{6} \right\} - B_0 C_{11} \left\{ \frac{1}{2} - \frac{E - \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right\} \right\} \]
\[ \left\{ -C_{12} D(\psi) \left\{ t_2^2 + \frac{\psi^2}{2} - \frac{\theta_2 t_2^3}{2} + \frac{\theta_1 \psi^2}{2} + \frac{\theta_1 \theta_2 \psi^3}{6} - \frac{\theta_2 t_2 \psi^3}{6} \right\} - B_0 C_{11} \left\{ \frac{1}{2} - \frac{E - \frac{D(\psi)}{W^2} \left\{ t_2 - \psi + \frac{\theta_1 t_2^2}{2} + \frac{\theta_2 \psi^2}{2} - \theta_2 t_2 \psi \right\} \right\} \right\} \right\} - A \]
\[
\left\{ \begin{array}{l}
\frac{dP(k)}{dk} = 0
\end{array} \right.
\]

Provided \(\frac{d^2P(k)}{dk^2} < 0\)

Equation (3.2.23) is equivalent to

\[
\begin{align*}
&\sum B_k \left\{ -\frac{D(k,T)}{W\theta_2} \left[ T + \theta_1kT^2 - \theta_2kT^2 \right] - sB_k \left\{ \frac{D(k,T)}{W\theta_2} \left[ T + \theta_1kT^2 - \theta_2kT^2 \right] \right\} \right\} + sTD(k,T) \\
&\quad + \left( \frac{s-c}{\delta} \right) D(k,T) \left\{ \frac{D(k,T)}{W\theta_2} \left[ T + \theta_1kT^2 - \theta_2kT^2 \right] - T \right\} \\
&= 0
\end{align*}
\]
\[
\left\{ 1 + \delta \left( T - \frac{D(k^i_T)}{W_{\theta_2}} \left( k^i - k_T + \frac{\theta_1 k^2 T^2}{2} + \frac{\theta_1 k^2 T^2}{2} - \theta_2 k k_T T^2 \right) - k_T \right) \right\} \\
+ \left\{ -cB_0 + cB_1 \theta_1 - C_{12} W + C_{11} B_i (1 - a \theta_1) \right\} \left\{ -\frac{D(k^i_T)}{W_{\theta_2}} \left( k^i T + \theta_2 k^2 T^2 - \theta_2 k T^2 \right) \right\} \\
+ \left\{ -cB_0 \theta_1 + C_{12} W \theta_2 + \frac{C_{11} B_i \theta_1}{2} \right\} \left\{ -\frac{D(k^i_T)}{W_{\theta_2}} \left( k^i T + \theta_2 k^2 T^2 - \theta_2 k T^2 \right) \right\} \\
E - \frac{D(k^i_T)}{W_{\theta_2}} \left( \theta_2 k^2 T^2 - \theta_2 k T^2 \right) \right\} \\
\left\{ -\frac{D(k^i_T)}{\delta} \left( C_{2} \theta_1 + C_{3} \right) \left\{ -\frac{D(k^i_T)}{W_{\theta_2}} \left( k^i T + \theta_2 k^2 T^2 - \theta_2 k T^2 \right) \right\} \right\} \\
\left\{ -\frac{D(k^i_T)}{W_{\theta_2}} \left( k^i T + \theta_2 k^2 T^2 - \theta_2 k T^2 \right) \right\} \right\} \\
\left\{ a + \frac{D(k^i_T)}{W_{\theta_2}} \left( k^i T + \frac{\theta_2 k^2 T^2}{2} \right) + \frac{\theta_1 k^2 T^2}{2} - \frac{\theta_2 k k_T T^2}{2} \right\} \\
\left\{ C_{12} \theta_1 D(k^i_T) \left( T + \theta_2 k^2 T^2 - \theta_2 k T^2 \right) \right\} \left\{ C_{12} D(k^i_T) \left( k^2 - k T^2 \right) \right\} \\
\left\{ -\frac{D(k^i_T)}{W_{\theta_2}} \right\} \left\{ T + \theta_2 k^2 T^2 - \theta_2 k T^2 \right\} \\
\left\{ -\frac{D(k^i_T)}{W_{\theta_2}} \right\} \left\{ \theta_2 k^2 T^2 - \theta_2 k T^2 \right\} \right\} \right\} \\
\left\{ 0 \right\}.
\]

(3.2.24)

### 3.2.2 Numerical Example

A practical model is considered taking the following values for different parameters: \( a = 0.6, B_0 = 15, \theta_1 = 0.8, \theta_2 = 0.12, \theta_3 = 0.11, T = 15 \) months, \( k_1 = 0.7, D(k^i_T) = 14.9279, \) Capacity of the owned warehouse \( W = 1000, A = Rs. \) 200/order, \( c = Rs. \) 2.5 per unit, \( C_{11} = Rs. \) 0.50 per unit, \( C_{12} = Rs. \) 0.20 per unit, \( C_{2} = Rs. \) 0.10 per unit, \( C_{3} = Rs. \) 0.10, \( \delta = 0.9, s = Rs. \) 25 per unit

Using the solution procedure described in the model the optimal results obtained are, \( k^* = 0.704732, t_1^* = 0.798188, P(k^*) = Rs. \) 1076.28 and \( Q^* = 1035.91. \) Thus the RW is emptied in \( t_1 = 0.798188 \) months, after which demand is fulfilled from OW, where the demand becomes constant at \( \psi = k^i T = 10.5 \) months, the inventory in OW lasts for \( t_2 = kT = 10.57098 \) months of the replenishment cycle thereby giving the maximum profit \( P(k^*) = Rs. \) 1076.28 on optimal order quantity \( Q^* = 1035.91. \)

### 3.2.3 Sensitivity Analysis

In scenario-2 (when \( t_1 \leq \psi \leq t_1 + t_2 \)), the sensitivity analysis is performed in a similar manner as for scenario-1 (when \( 0 \leq \psi \leq t_1 \)) with respect to changes in model parameters and have been presented in Table 3.2.
The present study can be future extended for some other characteristics above.

In this paper, an inventory model is developed for two-warehouse storage problem with ramp type demand and partial backlogging to maximize the total profit and optimal ordering quantity. The presented model is discussed for two scenario: i) demand rate becomes constant before the time at which the inventory level reaches zero in RW ii) demand rate becomes constant when RW is empty and demand is fulfilled from OW. This model could be very useful in retail business where the storage capacity in OW (which is at a busy market place) is limited. An analytic formulation of the problem on the frame work satisfying the assumptions of the model and optimal solution procedure to find optimal profit is presented. Numerical example for each scenario has been solved to illustrate the model. Sensitivity analysis with respect to parameters has been carried out.

The proposed model incorporates some realistic features that are likely to be associated with some kind of inventory. It can be used for electronic components, fashionable goods, cloths, foodstuff and other products which have more likely the characteristics above.

The present study can be future extended for some other factors involved in the inventory system.

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(Table 3.2)

| Parameter | % change in Ψ | % change in Q | % change in P |
|-----------|---------------|---------------|---------------|
| B₀        | -50           | -50.00        | -52.17        |
|           | -20           | -20.00        | -20.86        |
|           | 20            | 20.00         | 20.86         |
|           | 50            | 49.99         | 52.16         |
| B₁        | -50           | 0.005         | 0.005         |
|           | -20           | 0.003         | 0.003         |
|           | 20            | -0.003        | -0.003        |
|           | 50            | -0.005        | -0.005        |
| α         | -50           | -0.007        | -0.007        |
|           | -20           | -0.002        | -0.002        |
|           | 20            | 0.001         | 0.002         |
|           | 50            | 0.003         | 0.003         |
| δ         | -50           | -0.00.57      | 0.00.40       |
|           | -20           | -0.00.16      | 0.01.11       |
|           | 20            | 0.00.11       | 0.00.07       |
|           | 50            | 0.00.23       | 0.00.15       |
| W         | -50           | -0.00.06      | -0.00.06      |
|           | -20           | -0.00.02      | -0.00.02      |
|           | 20            | 0.00.02       | 0.00.02       |
|           | 50            | 0.00.06       | 0.00.05       |
| ψ         | -50           | -0.00.08      | 0.00.36       |
|           | -20           | -0.00.10      | 0.00.02       |
|           | 20            | 0.00.28       | -0.01.15      |
|           | 50            | 0.01.03       | -0.00.72      |
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