A NOTE ON THE BAR-NATAN SKEIN MODULE

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Abstract. We introduce a new skein module for three manifolds based on properly embedded surfaces and their relations introduced by D.Bar-Natan in [1], and modified by M.Khovanov [3]. We compute the structure of the modules for some manifolds, including Seifert fibred manifolds.

1. Introduction

This paper explores a new kind of skein module of three-manifolds that comes from Bar-Natan’s study of the Khovanov homology of tangles and cobordisms [1]. The module is a quotient of the free module on isotopy classes of marked surfaces in the underlying three-manifold. If the three-manifold is small in the sense that it has no incompressible surfaces, then the module is one dimensional on the empty surface. For sufficiently large manifolds its structure is more interesting.

The paper is organized as follows. In the next section we state the definitions and prove some propositions that will help to work examples. In section 3, we look at two simple examples. Section 4 explores other normalizations for the module. Finally, we compute the Bar-Natan skein module for Seifert fibered spaces.

2. The Basics

Let $S$ be a surface. A simple closed curve $C$ embedded in $S$ is essential if it does not bound a disk on $S$. A simple arc $A$ properly embedded in $S$ is essential if it does not cut a disk out of $S$.

If $S$ is embedded in the three-manifold $M$ a compressing disk for $S$ is a disk $D$ embedded in $M$ so that $D \cap S = \partial D$ and $\partial D$ is essential on $S$. We say the surface $S$ is incompressible if no component is a sphere bounding a ball and it has no compressing disks.

A three-manifold $M$ is irreducible if every sphere bounds a ball. We say the manifold $M$ is prime if every separating sphere in $M$ bounds a ball.

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Definition 2.1. (Bar-Natan skein relations)

\begin{align*}
\text{(1)} & \quad \begin{array}{c}
\includegraphics[width=0.1\textwidth]{dot_dot} \\
\end{array} = 0, \\
\text{(2)} & \quad \begin{array}{c}
\includegraphics[width=0.1\textwidth]{dot_circle} \\
\end{array} = 0, \\
\text{(3)} & \quad \begin{array}{c}
\includegraphics[width=0.1\textwidth]{dot_ball} \\
\end{array} = 0, \\
\text{(4)} & \quad \begin{array}{c}
\includegraphics[width=0.1\textwidth]{dot_ball} \\
\end{array} = 0.
\end{align*}

In the last two diagrams we intend that the spheres bound balls.

Any surface with more than one dot is zero under these relations. It is convenient to note that the relation (2) implies

\[ 2\begin{array}{c}
\includegraphics[width=0.1\textwidth]{dot_circle} \\
\end{array} = 0. \]

For later convenience, by "a dotted surface" we mean a surface with a dot on it, and "a white surface" we mean a surface without a dot.

Definition 2.2. (Bar-Natan skein modules)

Let \( M \) be a 3-manifold, and \( R \) be a commutative unital ring. A surface is marked if in addition to the surface we indicate which components carry dots. Let \( \mathcal{F}(M) \) be the set of isotopy classes of orientable marked surfaces, including the empty surface. Denote the free \( R \)-module with basis \( \mathcal{F} \) by \( R\mathcal{F}(M) \). Let \( S(M) \) denote the submodule of \( R\mathcal{F}(M) \) spanned by the Bar-Natan skein relations. Let \( BN(M, R) \) denote the quotient of \( R\mathcal{F}(M) \) by \( S(M) \). We call this the Bar-Natan module of \( M \).
There are many variations on this definition depending on how we deal with orientations of surfaces. Note that one may define BN modules for a manifolds with boundary, using properly embedded surfaces. There are some variations for that as well, but we do not elaborate in that direction.

A pure state is an element of the Bar-Natan skein module that is represented by a single marked surface. It is worth noting that a pure state can have impure descriptions. We call a marked surface incompressible if the underlying surface is incompressible.

**Proposition 2.3.** \( BN(M; R) \) is spanned by the pure incompressible states.

**Proof.** Starting with a representation of an element \( BN(M, R) \) as a linear combination of pure states. If one of the diagrams is compressible, then apply the second skein relation to replace it by the sum of two diagrams after doing the compression. We also eliminate spheres bounding balls using the fourth and fifth relations. After finitely many steps, the skein will be written as a sum of incompressible pure states. \( \Box \)

It is evident that \( BN(S^3) = R\phi \), that is, it is the free module of rank 1 over \( R \) with basis the empty surface. How does a given surface in the three-sphere evaluate? The skein relations tell us how to deal with a sphere. Suppose that the surface is a torus. A torus embedded in the three-sphere always has a compressing disk. Suppose we have a simple state consisting of the torus with no dots. After one compression, we have written as a sum of two states consisting of a sphere with one dot, so the torus evaluates as \( 2\emptyset \). If the torus has a dot, then after an application of the second skein relation we have a sum of two spheres with two dots, which evaluates to zero. Using these rules it is easy to evaluate any surface in the three-sphere.

We say two disjoint \( S_0 \) and \( S_1 \) in \( M \) are parallel, if there is an embedding of \( S \times [0,1] \) into \( M \) so \( S \times \{0\} \) is \( S_0 \) and \( S_1 \) is \( S \times \{1\} \). We call image of the embedding of \( S \times [0,1] \) the region between them.

**Proposition 2.4.** Suppose a surface \( F \) contains two parallel connected surfaces \( S_0, S_1 \) so that no other surface in the state touches the region between them. Let \( P_0 \) be a pure state based on \( F \) so that \( S_0 \) carries a dot and \( S_1 \) does not carry a dot. Let \( P_1 \) be the pure state that is the same away from \( S_0 \) and \( S_1 \), but now \( S_1 \) carries a dot and \( S_0 \) does not carry a dot. Then \( P_0 = -P_1 \).

Suppose that \( T \) is a pure state so that both \( S_0 \) and \( S_1 \) carry a dot then \( T \). If \( S_0 \) is a sphere, then \( T \) is equivalent to the pure state obtained by deleting \( S_0 \cup S_1 \). If \( S_0 \) has genus greater than zero then \( T = 0 \).
Proof. First we assume that $F = S_0 \cup S_1$. By $A^\bullet$ we denote a connected surface $A$ carrying a dot. Then we may have an expression of the pure state $P_0 = S_0^\bullet \cup S_1$, $P_1 = S_0 \cup S_1^\bullet$, respectively. By the second skein relation we have $S_0^\bullet \cup S_1 + S_0 \cup S_1^\bullet = S_0 \sharp S_1$, where the connected sum is taken through the region between $S_i$'s. Note that the right hand side bounds a handle body $S \backslash \{disk\} \times [0,1]$, which has the genus 0 or greater than 1. Therefore it determines zero state, thus we obtain $P_0 = -P_1$. Similarly $T = S_0^\bullet \cup S_1^\bullet = (S_0 \sharp S_1)^\bullet - S_0 \cup S_1^\bullet = (S_0 \sharp S_1)^\bullet$. If $S$ is sphere $S_0 \sharp S_1$ is a sphere bounding a ball, thus we obtain $T = 1$, otherwise $T = 0$. Since all the procedures are done within the region between $S_i$'s, the general case where $F$ has more components than $S_i$'s is proved in the same way.

In general you cannot move dots around so fluidly. To this end we can define a filtration of $BN(M,R)$. We say a surface has level $m$ if it has $m$ connected components. Let $F_m$ be the span in $BN(M,R)$ of all surfaces having level less than or equal to $m$. It is clear that $\cup_m F_m = BN(M,R)$. Let $G_m = F_m / F_{m-1}$ where $F_{-1} = \{0\}$. By the graded object we mean $\sum_m G_m$.

An important property of the graded object is:

**Proposition 2.5.** If $P_0$ and $P_1$ are pure states as above of level $m$, then $P_0 = -P_1$ in $G_m$. If a pure state of level $m$ has more than one dot, and $M$ is connected then that state is zero in $G_m$.

**Proof.** If you tube $S_0$ to $S_1$ you get a state of level $m - 1$ so it is zero in the quotient. That proves the first statement. To prove the second statement use the first relation to shift dots till they are on the same component.

There is one more final proposition we would like to make here about the relations.

**Proposition 2.6.** Suppose that $M$ is prime. If $P_i$ is a collection of distinct pure incompressible states without dots then they are linearly independent.

**Proof.** To prove this result we construct a family of linear functionals on $F(M)$ that is dual to the elements induced by the $P_i$ and vanishes on $S(M)$. Let $F_i : BN(M,R) \to R$ be defined as follows. Given a marked surface $S$, if it is a surface isotopic to $P_i$ along with a disjoint union of spheres bounding balls carrying a dot, and compressible tori that don’t have a dot, so that compressing any torus yields a sphere bounding a ball, then let $F_i(S) = (1/2)^k$ where $k$ is the number of compressible tori without a dot. Otherwise, let $F_i(S) = 0$. 

If this map were not well defined it would be because there are two ways to compress a particular torus. One that yields a sphere bounding a ball, and one that yields a sphere that does not bound a ball. If this happens the two compressing disks must lie on opposite sides of the torus, which is separating. The side containing the disk, so that compressing along the disk yields a ball, is a solid torus. The other side can be seen as the connect sum of a solid torus with a 3-manifold that is not a sphere. Hence if the two disks like this exist, \( M \) is the connected sum of a nontrivial manifold with a lens space, and is not prime. Therefore \( F_i \) is well defined. It is easy to check that \( F \) sends all the relations in \( BN(M, R) \) to zero, so it induces a linear functional on \( BN(M) \). The family of linear functionals \( F_i \) is dual to the \( P_i \) in the sense that \( F_i(P_j) = \delta^i_j \). Therefore the \( P_i \) are independent.

3. Two Examples

From the results of the last section it is evident that if \( M \) has no incompressible surfaces, \( BN(M, R) \) is free of rank one on the empty surface. To get an interesting answer, you need to have plenty of incompressible surfaces in your three-manifold. In this section we will discuss two examples. The first is \( S^1 \times S^2 \). The only incompressible surfaces in \( S^1 \times S^2 \) are surfaces whose connected components are all isotopic to \( \{*\} \times S^2 \). Hence the collection is nonempty but has a really simple structure. The second example we discuss is \( S^1 \times S^1 \times S^1 \). The answer turns out to be very similar to the first example.

Let \( M \) be \( S^1 \times S^2 \). We compute \( BN(M, R) \). Assume that 2 is invertible in \( R \).

**Theorem 3.1.** By \( z^k \) we denote a disjoint union of \( k \) parallel spheres in \( M \) that are homologically non-trivial. Let \( e_m \) be a disjoint union of \( z^m \) and a dotted non-trivial sphere (i.e. \( m + 1 \) parallel non-trivial spheres with a dot on one of them). Then

\[
BN(M, R) = R[z] \oplus Re_0.
\]

**Proof.** There are two statements that need to be proved. The surfaces span, and the surfaces are independent. in the following we only consider pure states based on parallel copies of essential \( S^2 \) unless otherwise is specified.

The lemmata below follow from Proposition 2.4.

**Lemma 3.2.** *(Shifting)* Let \( \alpha \) be a dotted sphere in \( e \) and \( \beta \) be a white sphere parallel to \( \alpha \). Then \( e = -e'' \), where \( e'' \) is obtained from \( e \) by moving the dot from \( \alpha \) to \( \beta \).
Lemma 3.3. (reduction) If \( e \) contains two parallel dotted spheres \( \alpha_1, \alpha_2 \), then \( e = e' \), where \( e' = e - \{\alpha_1, \alpha_2\} \).

Using these lemmata we may shift dots and reduce parallel dotted spheres. Thus one may describe a pure state with more than one dots as a linear combination of the states with no dot, or a dot on some component. However, a pure state with a dot is zero if the number of component is greater than one: while shifting of a dot from a sphere to an adjacent sphere causes sign change, it is on the other hand isotopic to the original state, thus the same element in the module.

Next we need to see that our skeins are independent. By Proposition 2.4 the skeins \( z^k \) are all independent. We just need to show that \( e_0 \) is independent from the \( z^k \). To this end we define a linear functional \( E : R\mathcal{F}(S^1 \times S^2) \to R \). If a surface is the result of taking the disjoint union a family of spheres with dots bounding balls and compressible tori without a dot that are nullhomologous in \( H_2(S^1 \times S^2; \mathbb{Z}_2) \), with \( e_0 \) or a torus without a dot that represents something nonzero in \( H_2(S^1 \times S^2; \mathbb{Z}_2) \) send it to \((1/2)^k \) where \( k \) is the number of torus components. Send any other surface to 0. Once again it is easy to check that this linear functional vanishes on all the relations so descends to \( BN(S^1 \times S^2; R) \). Furthermore, it sends \( e_0 \) to 1 and all \( z^k \) to zero. Ergo the surface \( e_0 \) is independent from the surfaces \( z^k \).

The case of \( T^3 = S^1 \times S^1 \times S^1 \) is so similar we will just posit the answer without proof. The nonempty connected orientable surfaces in \( T^3 \) are all tori. Up to isotopy they are in one to one correspondence with the pairs of triples of integers \( \pm (p, q, r) \) that are relatively prime and not all zero. The module \( BN(T^3) \) has a basis consisting of the empty surface, parallel copies of the tori paramatrized above without a dot, and single copies of the tori above carrying one dot.

4. An exploration of normalization

In this section we investigate if there is any other choice for the constants in Bar-Natan skein relations as in Definition 2. First let

\[
\begin{align*}
\begin{array}{c}
\includegraphics{circle_with_dot} \\
\end{array} &= y,
\end{align*}
\]

\[
\begin{align*}
\begin{array}{c}
\includegraphics{circle_with_double_dot} \\
\end{array} &= z,
\end{align*}
\]

\[
\begin{align*}
\begin{array}{c}
\includegraphics{circle_with_three_dots} \\
\end{array} &= x.
\end{align*}
\]
By using the relation (2) in Definition 2 we have
\[ \circledast = y = \circledast \circledast + \bullet \circledast = 2yz \]
and
\[ \circledast \bullet = \circledast \circledast + \bullet \circledast . \]
we need 2, y to be invertible in \( R \) if \( y \neq 0 \), then we have \( z = 1/2 \),
and \( xy = 1/4 \). In the case \( y = 0 \), we have \( z = z^2 \), then \( z = 0 \) or 1.
For \( z = 0 \) we have totally trivial theory where everything is zero, and
the latter case we have the relation identical to the Bar-Natan skein
relation. Thus we have the following new possible skein relations:

**Definition 4.1. (modified Bar-Natan skein relations)**

\[(1) \quad - \circledast - \bullet - \bullet = 0, \]

\[(2) \quad \circledast - \circledast = 0 \]

\[(3) \quad \bullet - 1/2 = 0 \]

\[(4) \quad \bullet \bullet - x = 0, \]

where \( y = \frac{1}{4x} \).

These relations turn out to imply that the distribution of the dots in
fact do not matter as demonstrated next. Let \( \alpha_k \) be a pure state with
\( k \) dots. Then
\[ \alpha_k = \circledast \bullet = \circledast \bullet \bullet + \bullet \circledast \circledast \]
\[ = x\alpha_{k-1} + \frac{1}{2}\alpha_k, \]
thus we have \( \alpha_k = 2x\alpha_{k-1} = \ldots (2x)^k S_0 \). Thus the first relation is sim-
plified as
By scaling $\alpha_k \rightarrow 1/2^k \alpha_k =: \alpha'_k$, we get the following equivalent definition.

**Definition 4.2.** (doubly modified Bar-Natan (MBN) skein relations)

1. \[= \] (the dot may go with the upper component or the lower one.)
2. \[= x^{-1}\]
3. \[= 1\]
4. \[= x\]

Let $MBN(M, R) := \text{span}_R \{\text{closed dotted or white surfaces in } M\}/\text{MBN relations}$. Note that in this definition we do not limit the surfaces to be orientable. It is easy to check that $\alpha'_k = x\alpha'_{k-1}$ for a pure state $\alpha'_k$ with $k$ dots in $MBN(M, R)$, i.e. a dot corresponds to multiplication by $x$. Thus a compression also gives rise to multiplication by $x$. Taking the contribution of dots and white spheres bounding balls into account, we have

$$MBN(M, R) \cong R[[x^\pm]]H_2(M, \mathbb{Z}_2) \cong R[[x^\pm]] \otimes H_2(M, \mathbb{Z}_2)$$

with the identification of the elements given by $F \in MBN(M, R) \rightarrow x^{g(F)-|F|}F \in R[[x^\pm]]H_2(M, \mathbb{Z}_2)$, where $F$ is a surface without dots, $g(F)$ is the genus of $F$, and $|F|$ is the number of the connected components of $F$. Note that $MBN(M, R)$ has an algebra structure, equipped with the product induced by the double curve sum on the homology group.

5. **Seifert fibred spaces**

A Seifert fibered space is a compact three-manifold $M$ that is the disjoint union of circles, so that every circle has a neighborhood that is a union of circles, and the decomposition of the neighborhood is modeled on a standard $(p, q)$ decomposition of a solid torus into circles (see [2]), or if the circle lies in the boundary of $M$, the neighborhood
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looks like half a solid torus fibered by longitudes. The decomposition space obtained by identifying two points if they lie on the same circle is a surface $F$. The quotient map $\psi : M \to F$ has the property that its restriction to the complement of finitely many fibers is an $S^1$ bundle. The fibers that must be deleted are called the singular fibers. These correspond to points where the local model is built on $(p,q)$ where $|p| > 1$. A surface $S$ in a Seifert fibered space is called vertical if it is a union of fibers. It is called horizontal if it is transverse to all the fibers. If $S$ is horizontal in $M$ then the result of cutting $M$ along $S$ is homeomorphic to $S \times [0,1]$. We will restrict our attention to Seifert fibered spaces where the total space is orientable as is the decomposition space. In this case it is a theorem of Waldhausen [5] that every two-sided incompressible surface is isotopic to a vertical surface or a horizontal surface.

In the following we study the structure of $BN(M, R)$ where $M$ is a Seifert fibered space, $F$ is its orbifold, with $l$ singularities $p_1, ..., p_l$, and $\psi : M \to F$ be the fibration map always. We assume that $F$ is closed, connected, and orientable for simplicity. By Waldhausen’s theorem we immediately obtain the following decomposition:

$$BN(M, R) = BN_v(M, R) \oplus BN_h(M, R),$$

where $BN_v(M, R)$ is generated by vertical surfaces with dots, and $BN_h(M, R)$ is generated by horizontal surfaces with dots.

For now we focus on $BN_v(M, R)$. A vertical surface is a pre-image of simple closed curves on $F$. Connected sums of simple closed curves on $F$ correspond to ”annular sums” of vertical surfaces along longitudes:

**Definition 5.1.** (annular sum) Let $N$ be a three manifold. Let $S_1, S_2$ be connected components of a surface properly embedded in $N$, and $A$ be an annulus embedded in $N$ so that each of two boundary component $c_i$ lies in $S_i$ respectively, and that $c_i$ is orientation preserving on $S_i$. We define the annular sum of $S_1$ and $S_2$ along with $A$ by

$$S_1 \#_A S_2 = S_1 \setminus N(c_1) \cup S_2 \setminus N(c_2) \cup A' \cup A'' ,$$

where $A'$ and $A''$ are parallel copies of $A$ so that for their boundary components $\partial A' = c'_1 \cup c'_2$ and $\partial A'' = c''_1 \cup c''_2$, $c'_1 \cup c'_2 = \partial N(c_1)$ holds.

The above definition is illustrated as follows:

![Diagram](image-url)
Note that the annular sum depends on choice of $A$. One may also consider the case $S_1 = S_2$ in the same way.

We have the following skein relation associated with annular sum, derived from B-N skein relation.

**Proposition 5.2.** For the above setting, let $S_1'$, $S_2'$ be the components of $S_1 \#_A S_2$ that contain components of $\partial A$ each. Then we have

$$S_1^* \cup S_2 + S_1 \cup S_2^* = S_1 \# S_2 = S_1^* \cup S_2' + S_1' \cup S_2^*,$$

where by $S^*$ we mean a singly dotted component $S$.

This is easy to observe by the fact that both $S_1 \cup S_2$ and $S_1' \cup S_2'$ are obtained by applying the relation 2 in BN relations to $S_1 \# S_2$ in different directions. Note that it is possible that $S_1 = S_2$, or $S_1' = S_2'$, in those cases we have just twice of the same term in each formula. Indeed by our condition that the boundary components of $A$ need to be orientation preserving, if $S_1$ and $S_2$ are distinct components, $S_i'$ are in fact one component, and vice versa.

Now we come back to our Seifert fibred manifold $M$. In the following we consider the case where the surfaces are all vertical surfaces of $M$, and the annuli used for annular sum are also vertical. In the following we define a skein module on $F$ based on the curves corresponding to vertical surfaces, with relation induced by BN relations along with the relation given by Proposition 5.2.

**Lemma 5.3.** A vertical surface is separating (resp. non-separating) in $M$ if and only if the corresponding simple closed curve on $F$ is separating (resp. non-separating). An annular sum of two vertical surfaces along the longitude corresponds to a band sum of corresponding s.s.c’s in $F$.

**Definition 5.4.** For a surface $F$ we define

$$SBN(F,R) := \text{span}_R\{\text{properly embedded curves with or without dots}\}/\text{relations},$$

where the relations are given by the following:

**SBN relations**

\[
(1) \quad S^* = 0,
\]
where the circles bound a disk, possibly with one singular point.

By construction it is clear that $BN_v(M, R) \hookrightarrow SBN(F, R)$. In the following we study the structure of $SBN(F, R)$.

5.1. **Structure of $SBN(F, R)$**.

The SBN relation 2 is typically realized as the following situation for closed curves:

$$
\begin{align*}
\bigcirc \cdot \bigcirc + \bigcirc \cdot \bigcirc = 2 \bigcirc \cdot \bigcirc
\end{align*}
$$

We call an element $\alpha \in SBN(F, R)$ pure state if it determines a pure state in $BN(M, R)$. All notions, such as levels, introduced for states in $BN(M, R)$ are used for corresponding states in $SBN(F, R)$ without explanation.

Our goal is to find a basis for $SBN(F, R)$. Since we know from the earlier section that all the white pure states are linearly independent, we focus on describing the relations between dotted pure states. Since our focus is mainly on pure states, we will simply use the word "state" to mean a pure state unless otherwise is stated. We provide some tools in the following.

**Proposition 5.5.** $2c^* = 0$ if $c$ is a separating curve in $F$.

This is from the following lemmas.

**Lemma 5.6.** Let $c$ be a simple closed curve in $F$. $2c^* = 0$ if $c$ bounds a blank disk with more than one singular point, where by a blank disk we mean a disk that has no curve on it.

**Proof.** easy.

**Lemma 5.7.** $2c^* = 0$ if $c$ is a separating simple closed curve in $F$ cutting a genus $k$ empty surface $S$ without a boundary other than $c$ itself.
Proof. First we may assume that \( S \) does not contain any singular point: if it does, get rid of it by the following relation:

\[
2 \begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array} = \begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright + \\
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array} = 2 \begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array}.
\]

Apply the annular skein relation to the following series of pictures appropriately.

\[
\begin{array}{c}
\begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array} \\
\rightarrow \\
\begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array} \\
\rightarrow \\
\begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array}
\end{array}
\]

Repeating the process \( k \) times one obtains \( 2c^* = 2c'^* \), where \( c' \) bounds a disk, and thus the right hand side is zero. \( \square \).

Lemma 5.8. Let \( \alpha \) and \( \alpha' \) be states with a dotted circle \( c^* \), \( c'^* \) respectively. Assume all the other components are the same, and that \( c \) and \( c' \) bound a surface which is blank in both states. Then \( 2\alpha = 2\alpha' \).

Proof. similar to the previous lemma.

Lemma 5.9. Let \( \alpha, \alpha' \in SBN(F, R) \) be states consisting of the same curves, with a dot in each of two circles cobounding an blank surface without other boundaries. Then \( \alpha = -\alpha' \).

Proof. Using the previous lemma, we have

\[
\begin{array}{c}
\begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array} \\
+ \\
\begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array} = 2 \begin{array}{c}
\circlearrowleft \\
\bullet \\
\circlearrowright
\end{array} = 0,
\end{array}
\]

where the ”clouds” in the circles signify that there may be something there, such as boundaries, singularities, genus, rather than blank disk. \( \square \)

Lemma 5.10. A state \( \alpha \) with more than one dot is zero if there is a pair of dotted circles that are connected by a path of circles.

Proof. Let \( c, c' \) be circles in \( \alpha \) that have a dot on each, and let \( \{c_1...c_n\} \) be a ”path” of circles connecting \( c \) and \( c' \), namely \( c \) and \( c_1 \) are adjacent, \( c_i \) and \( c_{i+1} \) are adjacent, \( c_n \) and \( c' \) are adjacent. WLOG one may assume that \( \{c_i\} \) and \( c, c' \) are all distinct, and that \( \{c_i\} \) are all
white. Let us call \( n = d(c, c') \) the distance between the dotted circles \( c \) and \( c' \) along the path. We show by induction in \( n \) that \( \alpha = 0 \). When \( n = 1 \), we have
\[
c^\bullet \cup c_1 \cup c^\bullet = -c \cup c_1 \cup c^\bullet + 2(c^\bullet c_1)^\bullet \cup c^\bullet = -\{ -c \cup c_1 \cup c^\bullet + 2(c^\bullet c_1)^\bullet \cup c^\bullet \} + 2\{ -(c^\bullet c_1)^\bullet \cup c^\bullet + 2(c^\bullet c_1)^\bullet c')^\bullet \} = 0.
\]
For general \( n \), we have
\[
c^\bullet \cup c_1 \cup c_2 \cup \cdots \cup c_n \cup c^\bullet = -c \cup c_1 \cup c_2 \cup \cdots \cup c_n \cup c^\bullet + 2(c^\bullet c_1)^\bullet \cup c_2 \cup \cdots \cup c_n \cup c^\bullet = 0,
\]
noting that \( d(c_1, c') = d((c^\bullet c_1), c') = n - 1 \) and applying induction. \( \square \).

For a state \( \alpha \in SBN(M, R) \), we denote by \( |\alpha| \) the number of circles contained in \( \alpha \). We introduce the filtration and grading for \( \alpha \in SBN(M, R) \) as in section 2. Let
\[
S_i := \text{span}_R\{ \text{state } \in SBN(F, R) \mid |\alpha| \leq i, \text{a component is dotted} \}
\]
Then we have
\[
S_0 \subset S_1 \subset S_2 \subset \cdots .
\]
Clearly \( \lim_{i \to \infty} = SBN(F, R) \).

Let \( G_i = S_i/S_{i-1} \). Since \( R \) is a direct product of simple rings, a basis of \( G_i \)'s give a basis for \( SBN(F, R) \). Note that in \( G_i \) we have the following relation between dotted circles.

Thus it is easy to see that a state with more than one dot is zero: one may bring one dot to another dotted circle with sign change. Thus from now on we only consider "dotted states" as those that have a single dot. For a dotted state, any choice of the dotted circle would give rise to the same state up to sign.

For a better description of states, we define the following notion:

**Definition 5.11.** For a dotted state \( \alpha \), we define a stack \( e \) to be a non-empty collection of circles \( \{ c_i \} \) in \( \alpha \) defined inductively: a circle \( c \) is in \( e \) if there is a circle \( c' \in e \) that cobounds a blank surface with \( c \). Clearly every circle in \( \alpha \) belong to some stack. All the circles in a stack are homologous, thus a stack determines an element of \( H_1(F, \mathbb{Z}_2) \), which we also denote by \( e \), abusing the notation. By \( w_e \) we denote the number of the circles \( |e| \) in a stack \( e \), and call it weight. Note that two distinct stacks may determine the same element of \( H_1(F, \mathbb{Z}_2) \).

We define a "band" \( N(e) \) for a stack \( e \) as follows: let us order the circles in \( e \) as \( c_0, c_2, \ldots, c_n \), where \( n = |e| \), \( c_i \) and \( c_{i+1} \) are adjacent for \( i = 0, \ldots, n \). We define \( N(e) \) to be a connected surface in \( F \) so that
$\partial N(e) = c_0 \cup c_n$, and $c_i \subset N(e)$ for all $i$. All $N(e)$’s are disjoint, regardless of choice of $N(e)$ for each $e$: $N(e)$ depends on the ordering of the circles in $e$.

It is easy to see, by using Lemma 5.8 and the fact that one may shift the dot by sign change, that one may move the circles within each stack without changing the state, as long as they do not interfere with circles in other stack.

Further, we have the following lemmas:

**Lemma 5.12.** A dotted state $\alpha$ is zero if there is a connected component $F' \subset F \setminus \bigcup_e N(e)$ that contains more than two distinct circles in $\alpha$ among its boundary components.

**Proof.** Let $c_1, c_2, c_3$ be distinct circles in $\alpha$ that are among the boundary component of $F'$, and by $\alpha_i$ I denote the state with a dot on $c_i$ and has identical circles as $\alpha$. Then, using the formula 5.1 we have $\alpha_1 = -\alpha_2 = \alpha_3 = -\alpha_1$, thus $\alpha = 0$. \hfill \Box

**Lemma 5.13.** A state $\alpha$ is zero if there is a connected component $F'' \subset F \setminus \bigcup_e N(e)$ and a stack $e$ with $w_e > 1$ odd, so that $\partial N(e) \subset F''$.

**Proof.** This is easily checked, considering the sign changes caused by the moves of the dot. \hfill \Box

These lemmas give a strong restriction on the possible non-zero dotted states. In order to enumerate them better, we introduce the following diagram along with some data for each state.

**Definition 5.14.** (diagram) For a state $\alpha \in SBN(F, R)$, the diagram $\Gamma$ of $\alpha$ consists of the following:

- $\Gamma^{(1)} = \{\text{edges}\}$. Each edge $e$ corresponds to a stack $e$.
- $\Gamma^{(0)} = \{\text{vertices}\}$. Each vertex $v$ corresponds to a connected component $F_v$ of $F^\circ$, where $F^\circ = F \setminus \bigcup_e N(e)$.

An edge $e$ is connected to a vertex $v$ by one end if $\partial F_v \cap N(e)$ is a circle in $e$. $e$ forms a loop around $v$ if $\partial F_v \cap N(e)$ is two circles in $e$. For $e \in \Gamma^{(1)}$, we have
• the weight $w_e = |e|$ is the number of circles that belong to $e$.
• the $\mathbb{Z}_2$ homology class that each element in $e$ determines. We denote it by $e$, abusing the notation. Note however that it is possible that distinct edges determine the same $\mathbb{Z}_2$-homology class.

An example of a pure state and the corresponding graph is illustrated below: a pure state $\alpha$ (the dot is omitted):

\begin{center}
\includegraphics[width=0.5\textwidth]{example_graph}
\end{center}

the graph $\Gamma$ of $\alpha$:

\begin{center}
\includegraphics[width=0.5\textwidth]{example_graph}
\end{center}

Lemma 5.15. For a given surface $F$, the graph along with the data for each edge determines a pure state in $SBN(F,R)$ if for each $v \in \Gamma^{(0)}$ \[\sum_{e \in v \neq \text{loop}} e = 0 \in H_1(F, \mathbb{Z}_2)\] holds.

We call a graph that corresponds to a pure state admissible.

Proof. First, a graph corresponding to a pure state is admissible since a vertex $v \in \Gamma^{(0)}$ corresponds to a surface with boundary components specified by the edges that connect to $v$, where a loop will give two circles, thus the contribution is zero in $\mathbb{Z}_2$-homology. On the other hand, for a given admissible graph with the data, the circles corresponding to the edges attached to a vertex must bound a surface in $F$ by the admissibility condition. One many randomly choose circles for each edge as many as the weights. \qed

Lemma 5.16. For an admissible graph, we have the following reduction rule:

\begin{center}
\includegraphics[width=0.5\textwidth]{reduction_rule}
\end{center}

Proof. The relation (1) is given by the fact that, by admissibility $e_1 = e_2$ in $\mathbb{Z}_2$ homology, and thus the circles in $e_1$ and $e_2$ belong to the same edge. \qed

We call an admissible graph reduced if there is no divalent vertex connecting two edges.
An admissible graph $\Gamma$ determines a pure state in the filtration $S_n$ if $|\Gamma| := \sum_{e \in \text{Gr}(1, n, 2)} w_e \leq n$. For the sake of notation economy, we consider admissible graphs as if they are pure states in $SBN(F, R)$. The Lemmas 5.12, 5.13 lead to the following formulas for the graphs.

**Lemma 5.17.** A reduced admissible graph $\Gamma \in G_n = S_n / S_{n-1}$ if:

1. $|\Gamma| \leq n - 1$
2. $\bigcirc \subset \Gamma$
3. for some $v \in \text{Gr}(0, n)$, the number of edges connected to $v$ is more than two.
4. $\bigcirc \subset \Gamma$, $n > 1$, $n$ is odd.
5. $\bigcirc \subset \Gamma$, $n$ even, $m \neq 0$

where dotted line may or may not exist.

Using the previous lemmata we obtain the following classification.

**Theorem 5.18.** A reduced admissible graph $\Gamma$ in $G_n$ for some $n$ is one of the following graphs.

1. $\bigcirc \bigcirc$, $n = 1$ or even, $e \in H_1(F, \mathbb{Z}_2)$
2. $\bigcirc \bigcirc$, $e \neq f \in H_1(F, \mathbb{Z}_2)$
3. $\bigcirc \bigcirc$, $e \neq f \in H_1(F, \mathbb{Z}_2)$.

Note that the graph (b) is the case $n = 0$ of the graph (c).
Corollary 5.19. Let $H_1 := H_1(F, \mathbb{Z}_2)$ and $\Delta = \{(e, e) | e \in H_1\}$.

$$G_1 = RH_1 = \text{span}_R\{1, e | e \in H_1\},$$

$$G_n = \begin{cases} \text{span}_R\{\begin{array}{c} \includegraphics[width=1cm]{fig1} \end{array}| e \neq f \in H_1\} \\
R(H_1 \times H_1 \setminus \Delta) & \text{if } n \text{ is odd } > 1, \\
\text{span}_R\{\begin{array}{c} \includegraphics[width=1cm]{fig2} \end{array}| e \in H_1\} \oplus \text{span}_R\{\begin{array}{c} \includegraphics[width=1cm]{fig3} \end{array}| e \neq f \in H_1\} \\
R(H_1 \oplus R(H_1 \times H_1 \setminus \Delta) & \text{if } n \text{ is even } > 0 \end{cases}$$

5.2. The structure of $BN_v(M, R)$ and $BN_h(M, R)$.

In the previous subsection we clarified the structure of $SBN(F, R)$, which was known to contain $BN_v(M, R)$. In fact we have the following:

Proposition 5.20.

$$BN_v(M, R) = SBN(F, R).$$

Proof

We maintain the notation used in the previous subsection regarding $SBN(F, R)$. Let $F'_n := \text{span}_R\{\text{states } \alpha \in BN_v(M, R)| |\alpha| \leq i\}$, and $G'_n = F'_n/F'_{n-1}$. Since we already know that states consisting of incompressible surfaces without dots are linearly independent, we show that the preimages of the basis $\{\alpha_i\}$ of $G_n$ with respect to the fibration map $\psi$ are linearly independent in $G'_n$. Assume that the component that the dot in each $\alpha_i$ is placed is arbitrarily chosen and fixed for all. We show that the states $\{\alpha'_i\}$, where $\alpha'_i = \psi^{-1}(\alpha_i) \cong \alpha_i \times S^1$ are linearly independent in $G'_n$. We proceed in a similar way to Proposition 2.6. Let $\varphi_i : BN_v(M, R) \to \mathbb{R}$ be defined as follows: For a state $\beta$, if it is a disjoint union of $\alpha'_i$ possibly with the dot dislocated, and singly dotted spheres bounding balls, and $k$ compressible white tori, let $\varphi_i(\beta) = (-1)^l(1/2)^k$, where $l$ is the number of shifts that the dot in $\beta$ makes to arrive to the default position of the dot in $\alpha'_i$ within the
Note that shifting of a dot among the components of the surface $\alpha'_i$ is fully expressed in terms of components of the curve in $\alpha_i$, which has been discussed earlier. Since $\alpha_i$ is not zero, $l$ is well-defined modulo 2. Now we check that $\varphi_i$ is compatible with the BN relations modulo grading. The only non-trivial relation to check is (2). Let

$$\alpha'_\infty = \circ \, , \quad \alpha'_+ = \circ \circ \, , \quad \alpha'_- = \circ \circ \circ \, ,$$

where by these equalities we denote pure states with local modifications illustrated by the right hand sides. We need to show that $\varphi_i(\alpha'_\infty) = \varphi_i(\alpha'_+) + \varphi_i(\alpha'_-)$. We may assume that $\alpha'_\pm$ does not have any spheres bounding balls, or tori bounding solid tori. If the underlining surface $s$ of $\alpha'_\pm$ is compressible, or incompressible but not isotopic to that of $\alpha'_i$, both side of the equality is zero. Otherwise $\alpha'_+ = \pm \alpha_i = \pm \alpha'_i$, thus we have

$$\varphi_i(\alpha'_+) + \varphi_i(\alpha'_-) = (-1)^l\varphi_i(\alpha'_i) + (-1)^{l+1}\varphi_i(\alpha'_i) = 0.$$

The number of the components of $\alpha'_\infty$ is $n - 1$, thus $\varphi_i(\alpha'_\infty) = 0$ in $G'_n$. Thus we proved the independence of $\{\alpha'_i\}$ in $G'_n$, which implies $BN_v(M, R) \cong SBN(F, R)$.

Next we want to understand the horizontal surfaces. If $M$ has a horizontal surface, let $H$ be a connected horizontal surface so that $\psi|_H : H \to F$. Orienting the fibers of $M$ we can define a map $\phi : H \to H$ by following the fibers in the positive direction. The map $\phi$ has finite order and $H \times [0, 1]/\sim$, where we identify $(x, 1)$ with $(\phi(x), 0)$, is homeomorphic to $M$. Let $H_1(H)^\phi$ denote the invariant part of $H_1(H)$ under the action of $\phi$. For the sake of computation we orient $H$ and $M$ and $F$. If $H'$ is any horizontal surface the degree of $\psi_{H'}$ is an integer $d(H')$. Making $H'$ transverse to $H$ we can take their oriented intersection and view it as defining an element $z(H')$ of $H_1(H)^\phi$. Hence we can assign to any connected oriented horizontal surface the ordered pair $(z(H'), d(H')) \in H_1(H)^\phi \oplus \mathbb{Z}$. The image of this map is all indivisible elements, which we denote $I(H)$. Two connected oriented surfaces are isotopic if and only if they have the same image in $I(H)$. Let $P(I(H))$ be all elements of $I(H)$ with $d(H') > 0$, these points are in one to one correspondence with the isotopy classes of unoriented horizontal surfaces in $M$. If $f \in P(I(H))$, let $f^k$ denote $k$ parallel copies of $f$ without dots. Let $d_f$ denote on copy of $f$ with a dot.
Theorem 5.21. $BN_h(M, R) = \oplus_{f \in P(I(H))} \{f^k \}_k \oplus \{d_f \}$.

The proof is just like the example $S^1 \times S^2$, noting that two nonparallel horizontal surfaces cannot be disjoint.

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