On the thermodynamics of moving bodies

Jorge G Russo\textsuperscript{1} and Paul K Townsend\textsuperscript{2}

\textsuperscript{1} Instituci\`o Catalana de Recerca i Estudis Avan\c{c}ats (ICREA), Departament ECM and Institut de Ciencies del Cosmos, Facultat de Física, Universitat de Barcelona, Diagonal 647, E-08028 Barcelona, Spain
\textsuperscript{2} Department of Applied Mathematics and Theoretical Physics, Centre for Mathematical Sciences, University of Cambridge, Wilberforce Road, Cambridge CB3 0WA, UK

E-mail: jruss@ub.edu and P.K.Townsend@damtp.cam.ac.uk

Received 17 December 2009, in final form 13 May 2010
Published 19 July 2010
Online at stacks.iop.org/CQG/27/175005

Abstract

We consider an Unruh–DeWitt particle detector, coupled to a massless scalar field, undergoing ‘acceleration with drift’ in a \((1+3)\)-dimensional Minkowski spacetime. We use this to model inertial motion in a \((1+2)\)-dimensional Minkowski heat bath, in particular motion within a 2-plane parallel (and near) to the horizon of a black 2-brane. We compute the angular response of the detector in its own rest frame. The response to particles arriving from within the 2-plane is isotropic and Planckian for zero drift velocity. For small drift velocities, and in the ultra-violet limit in which the excitations behave like a classical gas, the response is just Doppler shifted. However, we find discrepancies with the Doppler-shifted formula in the infrared limit, and qualitatively different behaviour when the drift velocity is not small. We discuss possible explanations for this result and potential implications for observations of the cosmic microwave background radiation.

PACS numbers: 04.60.Kz, 04.62.+v, 04.60.−m, 98.70.Vc

(Some figures in this article are in colour only in the electronic version)

1. Introduction

Inertial motions are all equivalent in a vacuum but not in a radiation heat bath because the rest frame of the radiation provides a preferred frame. Consider a Minkowski spacetime filled with a gas of massless spinless particles at temperature \(T\). We shall assume that the particles of the gas are excitations of a scalar field \(\phi\) which we may couple to a two-state Unruh–DeWitt particle detector with variable energy gap \(\hbar\omega\). If the detector is at rest with respect to an infinite heat bath, its response as a function of \(\omega\) will be Planckian. This paper is concerned with the response of such a detector to inertial motion in the heat bath.
One motivation is potential relevance to the detection of the cosmic microwave background radiation (CMBR); although the massless particles in this case are spin 1 photons, this difference is not crucial for much of the physics. There is a standard theory in this case, which goes back to Pauli [1] but was developed in the context of the CMBR by Peebles and Wilkinson [2] and others [3]: the background radiation is viewed as a classical gas of massless particles and the distribution in the moving frame is deduced from the Planck distribution in the rest frame by a Lorentz transformation of the individual particle trajectories; the result is the same (for massless particles) as one gets by an application of the relativistic Doppler shift. However, this theory is open to question because the description as a classical gas is valid only in the ultraviolet limit in which $\hbar \omega / T \gg 1$.

We leave this point here for the moment, and turn to another motivation, of a more theoretical nature. This comes from consideration of the thermal physics of black branes. As for a static black hole, a static black $p$-brane with non-zero surface gravity $\kappa$ radiates at the Hawking temperature $T_H = \hbar \kappa / (2\pi)$ and so can be in thermal equilibrium only if the temperature at transverse spatial infinity equals $T_H$. The local temperature elsewhere is then given by the Tolman relation

$$T = \frac{T_H}{\sqrt{-k^2}}, \quad (1.1)$$

where $k$ is the timelike Killing vector field such that $k^2 = 0$ on the horizon and $k^2 = -1$ at infinity. Assuming that the black $p$-brane is planar, this local temperature will be constant on the $p$-planes at a fixed distance $r$ from the event horizon, and could be measured using a particle detector. As the temperature is a function of $r$, we should expect the detector’s response to depend on the angle $\theta$ of incidence to the outward radial normal. However, if we fix $\theta = \pi/2$, the radiation will be isotropic in all other directions; in effect we have a detector in a Minkowski heat bath of dimension $(1 + p)$. We may again ask how the detector responds to inertial motion within this heat bath; in other words, how does it respond to motion parallel to the $p$-brane horizon?

If we assume that the detector is very close to the horizon then the effective spacetime geometry of a $p$-brane $d$-metric is the product of a $(d - 2)$-sphere with a $(2 + p)$-dimensional generalization of the flat Rindler metric, in which a static observer has proper acceleration $a = \kappa / \sqrt{-k^2}$. In other words, we have a detector undergoing constant proper acceleration in a $(2 + p)$-dimensional Minkowski spacetime. For $p = 0$ (i.e. a black hole), Unruh showed [4] that this acceleration causes the detector (the theory of which was subsequently clarified by DeWitt [5]) to respond as if it were in a heat bath at a temperature (the Unruh temperature) that coincides with the local temperature of the black hole:

$$T_U \equiv \frac{\hbar a}{2\pi} = \frac{T_H}{\sqrt{-k^2}} \quad (k^2 \to 0). \quad (1.2)$$

In other words, the local temperature has a purely kinematical explanation near the horizon, as might be expected from the fact that there is actually nothing at the horizon.

Unruh’s result is expected to apply for all $p > 0$, but for odd $p$ there is an apparent [6] (but spurious [7, 8]) interchange of Bose and Fermi statistics, while for $p > 2$ the interaction of an Unruh–DeWitt detector with the scalar field is non-renormalizable. For these reasons, we shall restrict ourselves here to the case of $p = 2$, although some arguments will apply more generally. We thus have an accelerating particle detector in a four-dimensional Minkowski spacetime. Because this acceleration picks out a particular direction, we should expect a direction-dependent response but the response will be isotropic in a 2-plane orthogonal to

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3 It actually turns out to be direction-independent in the detector’s rest frame but this is a special feature of scalar radiation.
the acceleration. In the context from which we extracted this picture, this 2-plane is one of the 2-planes parallel to a black 2-brane horizon, which we may conveniently think of as a (1 + 2)-dimensional braneworld at the uniform Unruh temperature implied by its acceleration in an orthogonal direction.

An obvious question that this raises is whether the model of a Minkowski heat bath as an accelerating brane can be ‘abstracted’ from the context described above and used more generally, perhaps in higher dimensions too, as a model for a Minkowski radiation heatbath [9] (where by ‘radiation’ we mean massless particles with zero chemical potential). If so, there could be implications for the detection of photons in the CMBR. The limits of applicability of this model are not clear to us, but it is interesting to note that it is an essential ingredient in the GEMS approach to black hole thermodynamics [10]: if a static black hole spacetime is embedded globally, and isometrically, in a higher dimensional flat spacetime, then a static observer anywhere, not just near the horizon, has an acceleration in the embedding spacetime that is related to the local temperature in thermal equilibrium by the Unruh formula. This is an observation, rather than a result, since it is far from clear why Unruh’s formula should apply, but it is an observation that consistently gives correct results. We shall leave further discussion of these issues until the end of the paper.

Returning to our detector at a fixed distance from a 2-brane horizon, we consider the effect on it of the inertial motion within the plane in which it is constrained to move. This leads to consideration of the motion in a four-dimensional Minkowski spacetime of a detector that undergoes constant proper acceleration in one direction along with a constant velocity ‘drift’ in an orthogonal direction. This is a stationary motion, in the sense that the extrinsic geometric invariants of the detector’s worldline (curvature, torsion and hyper-torsion) are all constant; this implies that the detector’s response is time-independent, at least in its own rest-frame. Stationary motions were classified by Letaw [11] (more recent discussions can be found in [12, 13]). Three of his six classes are inertial motion, accelerated motion and ‘acceleration with drift’; the other three all involve rotation. The response of a detector is direction dependent; in the case of acceleration with drift it will depend not only on the angle $\theta$ to the axis of the acceleration but also on the angle $\phi$ to the direction of the drift velocity in the $\theta = \pi/2$ plane. The principal technical result of this paper is a computation of the angular response of an Unruh–DeWitt detector undergoing acceleration with drift in a four-dimensional Minkowski spacetime. We thus learn, from first principles, how an Unruh–DeWitt detector at fixed distance from a black 2-brane horizon responds to inertial motion parallel to the brane.

What result should we expect? If the detector is restricted to move within a plane at a uniform temperature, and to detect only radiation that is coming from other points on this plane, then we have a situation that is very similar to that encountered by a detector moving inertially in the CMBR, except for the one lower dimension of space. So should we expect the detector to see a distribution of massless particles that is just Doppler-shifted relative to the rest-frame distribution detected by a static detector? One argument for this that applies in any dimension comes from consideration of the mode expansion for the scalar field $\phi$. It is well known that the thermal behaviour of a static detector in Rindler spacetime can be predicted from the non-trivial Bogoliubov transformation that relates the modes in the Rindler coordinates adapted to constant acceleration to those in the full Minkowski spacetime. We can similarly consider the mode expansion in coordinates adapted to acceleration with drift (adapted coordinate systems can be found explicitly for all stationary motions [14]). We shall present a version of this analysis, although the basic result is known [15]: the modes are simply Doppler-shifted relative to those of pure acceleration since the additional Bogoliubov transformation associated with the drift motion is trivial (although this is not the full story [16], as we shall explain). However, we find that the detector response reproduces the
Doppler-shifted Planck spectrum only to leading order in the drift velocity $v$ in the ultraviolet limit $\omega/T \gg 1$.

Following our presentation of this result, we make a detailed comparison with the Doppler-shifted Planck spectrum. We then discuss the related issue of scalar mode expansions in coordinates adapted to the stationary motion of ‘acceleration with drift’ and conclude with a discussion of the results, and their possible implications. We should mention here that similar issues have been addressed previously for rotational motion. Because this involves acceleration, it has been suggested that a version of the Unruh effect might be operative. However, the mode expansion analysis shows that the quantum vacuum in a rotating frame does not differ from the inertial frame, so one might expect the rotation to have no effect on a particle detector. It appears that this is indeed the case when modes of the scalar field are suitably restricted to take into account the fact that the coordinates in a rotating frame become singular at some critical radius [17]. The physics of acceleration with drift is quite different, however. What appears to be most relevant in this case is that the drift motion effectively creates an ergo-region outside the acceleration horizon.

2. Detector response

In this section we compute the response of an Unruh–DeWitt detector undergoing the stationary motion that we refer to as ‘acceleration with drift’ in a four-dimensional Minkowski spacetime with the metric

$$d\mathcal{X} \cdot d\mathcal{X} = -dX_0^2 + dX^2 + dY^2 + dZ^2.$$  \hspace{1cm} (2.1)

The worldline of the detector in this spacetime is given by

$$X_0 = a^{-1} \sinh[a\gamma \tau], \quad X = a^{-1} \cosh[a\gamma \tau], \quad Y = \gamma v \tau, \quad Z = 0,$$  \hspace{1cm} (2.2)

where $\gamma = 1/\sqrt{1 - v^2}$. The 4-acceleration $A$ is non-zero for any $v$. For $v = 0$ we have the well-known trajectory of a detector undergoing constant proper acceleration $|A| = a$. When $v \neq 0$ we have ‘acceleration with drift’ in which uniform motion with velocity $v$ in the $Y$ direction is superposed on the constant proper acceleration $|A| = \gamma^2 a$ in the $X$ direction. For pure acceleration, the worldline has non-zero curvature but zero torsion, whereas the torsion is also non-zero for acceleration with drift [11]. Equivalently, the relativistic jerk [9, 13] is zero for pure acceleration but not for acceleration with drift. We therefore expect a $v$-dependence of the detector’s response to the motion.

As we explained in the introduction, the motion of acceleration with drift is relevant to inertial motion in a heat bath if the latter is modelled as a brane at the Unruh temperature due to acceleration in an extra dimension, and we also explained how this model applies to motion near the horizon of a black 2-brane. For a 2-brane, the model is realized by the following family of embeddings of a three-dimensional worldvolume with coordinates $(\tau, y, z)$ [13]:

$$X_0 = a^{-1} \sinh[a\gamma (\tau + vy)], \quad X = a^{-1} \cosh[a\gamma (\tau + vy)],$$

$$Y = \gamma (y + \tau v), \quad Z = z, \quad (\gamma = 1/\sqrt{1 - v^2}).$$  \hspace{1cm} (2.3)

A computation of the induced metric shows that the embedded spacetime is indeed Minkowski and also that the coordinates $(\tau, y, z)$ are Cartesian. This Minkowski worldvolume can be viewed as the congruence of worldlines parametrized by position $(y, z)$ on the brane. Each such worldline defines a stationary motion of acceleration with drift, with proper time $\tau$. The embedding with non-zero $v$ is obtained from that with $v = 0$ by a worldvolume Lorentz boost in the $y$ direction. Although the induced metric is not affected by this boost, the extrinsic geometry of the worldlines of the congruence is affected by it. In particular, the torsion
(equivalently, relativistic jerk) of the worldlines of the congruence is zero only for \( v = 0 \). When account is taken of the Unruh temperature on the brane due to the acceleration, this fact can be seen as the kinematical equivalent of the fact that the rest frame of a heat bath provides a ‘preferred’ reference frame.

We begin with some generalities. We assume a ‘monopole’ detector [5] with (variable) energy gap \( \bar{\hbar}\omega \) coupled to a free quantum scalar field \( \Phi(X) \). The interaction is

\[
S_{\text{int}} = g \int d\tau m(\tau)\Phi(\tau),
\]

where \( m(\tau) \) is the detector’s monopole moment operator and \( \tau(\tau) \) is the detector’s worldline, parametrized by proper time \( \tau \). The coupling constant \( g \) is dimensionless (this is a simplifying feature of four spacetime dimensions) and may be assumed small. The probability of excitation and accompanying emission of a massless particle of 4-momentum \( P = \hbar(k, k) \) into the solid angle element \( d\omega \) may then be computed using first-order perturbation theory. Integrating over photon energy, and omitting a small dimensionless constant of proportionality, one has [18, 19]

\[
\frac{dP}{d\omega} = \int_{-\infty}^{\infty} d\tau e^{2i\hbar\omega\tau - iP \cdot \Delta\tau(\tau, \tau')},
\]

where

\[
\Delta\tau(\tau, \tau') = \tau(\tau) - \tau(\tau'), \quad \tau_\pm = \frac{1}{2}(\tau \pm \tau').
\]

Henceforth, we choose units such that \( \bar{\hbar} = 1 \), which means that all dimensionful quantities have dimensions of mass to some power.

### 2.1. Integrated response

From the braneworld perspective that we will eventually adopt, it would make no sense to integrate the detector’s response over the solid angle. However, for the general purpose of understanding the physics of detector response it is instructive to consider this integral. Setting \( \bar{\hbar} = 1 \) in (2.5) we have

\[
\int d\omega \frac{dP}{d\omega} = \int d\tau_+ \hat{P}, \quad \hat{P} = 16\pi^3 \int_{-\infty}^{\infty} d\tau_- e^{2i\omega\tau_-.G^+},
\]

where \( G^+ = [4\pi^2|\Delta\tau(\tau, \tau')|^2]^{-1} \), which is the Wightman function evaluated for points on the detector’s worldline specified by proper times \( \tau \) and \( \tau' \). The integral should vanish for inertial motion for which \( G^+ = -1/(16\pi^2\tau_+^2) \). The integrand has a pole at \( \tau_- = 0 \) but the usual ‘\( \text{i}\varepsilon \)’ prescription will push this pole below the real axis so that it does not lie within the contour completed in the upper half of the complex \( \tau_- \)-plane (we assume \( \omega > 0 \)). With this prescription, we recover the expected result that the detector remains in its ground state if it is moving inertially.

It has been proposed [20, 21] that the response of an inertial detector in a \( (1+3) \)-dimensional Minkowski spacetime at temperature \( T \) is given by

\[
P_T \propto \int_{-\infty}^{\infty} d\tau_- e^{2i\omega\tau_- G^+_T(\tau_-)},
\]

where \( G^+_T \) is the thermal Wightman function, again evaluated for points on an inertial worldline specified by proper times \( \tau \) and \( \tau' \):

\[
G^+_T = -\frac{1}{16\pi^2} \sum_{n=-\infty}^{\infty} \frac{1}{[(\tau_- - in\gamma/2T)^2 + (n\gamma v/2T)^2]}.
\]

5
Now there are poles inside the contour even for inertial motion and one gets a non-zero result that depends on the detector’s velocity with respect to the heat bath. The ‘scalar photon’ number density may be read off from this result, and one finds that

\[ n^{(3)}(\omega) \, d\omega = \frac{\omega T}{8\pi^2 \gamma v} \log \left[ \frac{1 - e^{-\omega (1 - v)/T}}{1 - e^{-\omega (1 + v)/T}} \right] \, d\omega, \]  

(2.11)

where the (3) superscript indicates that this is a 3-space number density. Note the factor of \( v \) in the denominator, which ensures that the \( v \to 0 \) limit is non-zero; naturally, this limit yields the usual Planckian distribution. For non-zero \( v \), this result is exactly what one finds by integration over the solid angle of the formula

\[ n^{(3)}_{\text{PPW}}(\omega, \mathbf{n}) \, d\omega \, d\Omega = \frac{\omega^2}{16\pi^3} \left( \frac{T}{[1 - v \cdot \mathbf{n}]} \right)^{1/2} \left( \frac{e^{\omega/T_{\text{eff}}}}{[1 - v \cdot \mathbf{n}]} - 1 \right) \, d\omega \, d\Omega, \]  

(2.12)

which is precisely the Doppler-shift result of Pauli, Peebles and Wilkinson (PPW) (after allowance is made for the fact that we here discuss ‘scalar photons’ with only one polarization state). However, the starting formula (2.9) has not been derived from first principles.

We now return to the conventional formula (2.7) for the integrated excitation rate, which is derived from first principles. This is time-independent for any stationary motion since \( G^+ \) is then a function only of \( \tau_- \). For ‘acceleration with drift’ one finds that [11]

\[ G^+ = -\frac{a^2}{16\pi^2 [\sinh^2 \xi - v^2 \xi^2]} \left( \xi = a\gamma \tau_+ \right), \]  

(2.13)

as can be shown directly using (2.2). This yields a non-zero integrated excitation rate. One can arrive at the same result by first performing the \( k \)-integral in (2.5). To this end, we choose spherical angles, \( 0 \leq \theta \leq \pi, 0 \leq \varphi \leq 2\pi \), so that

\[ P_0 = k, \quad P_X = k \cos \theta, \quad P_Y = k \sin \theta \cos \varphi, \quad P_Z = k \sin \theta \sin \varphi. \]  

(2.14)

We then find that

\[ \frac{d\mathcal{P}}{d\Omega} \bigg|_{v=0} = -\frac{a}{2\gamma} \int_0^\infty d\tau_+ \frac{e^{2\omega(\gamma \tau_+)\xi}}{[\Gamma_\theta \sinh \xi - v \xi \cos \varphi \sin \theta]^2}, \]  

(2.15)

where

\[ \Gamma_\theta = \cosh(a\gamma \tau_+) - \cos \theta \sinh(a\gamma \tau_+). \]  

(2.16)

Integrating over the solid angle, we recover the formula for the integrated excitation rate in terms of \( G^+ \).

2.2. Angular response

We now focus on formula (2.15), which gives the angular response of the detector integrated over time. Consider first the \( v = 0 \) case. We have, from (2.15) and (2.16),

\[ \frac{d\mathcal{P}}{d\Omega} \bigg|_{v=0} = \int_0^\infty d\tau_+ [\Gamma_\theta(\tau_+)]^{-2} \frac{d\mathcal{P}}{d\Omega} \bigg|_{v=0}, \]  

(2.17)

where

\[ \frac{d\mathcal{P}}{d\Omega} \bigg|_{v=0} = -\frac{a}{2\gamma} \int_0^\infty d\xi \frac{e^{2\omega(\gamma \tau_+)\xi}}{\sinh^2 \xi}. \]  

(2.18)

We would like to identify the integrand of the \( \tau_+ \) integral with an excitation rate but this rate is \( \tau_+ \)-dependent because of the \( [\Gamma_\theta]^{-2} \) factor. As shown in [19, 22], this factor arises because the detector has a time-dependent velocity \( dX/dT = \tanh(a\gamma \tau_+) \) with respect to an inertial
There is a unique pole at \( \alpha \). The angle \( \xi \) despite the step functions, \( d\dot{\xi} \). Combining both equations, we find the critical value at \( 2\alpha \). The cone closes at \( v \approx \gamma \). For non-zero \( u \equiv v \cos \varphi \sin \theta \), it encloses a finite number of poles at \( \xi = i\xi \), \( \sin x = ux \), \( x > 0 \) \( (u = v \cos \varphi \sin \theta) \). There is a unique pole at \( x = x_0(u) \) when \( u > u_1 \approx 0.13 \), and in this case the residue calculus yields \( \frac{d\bar{P}}{d\Omega} = \frac{\pi a}{\gamma} e^{-u(x_0(u))} e^{-\frac{2\pi u(x_0)}{\gamma}} \), \( \Lambda \). At \( u = u_1 \), there is an extra double pole, which splits into two poles at \( x = x_1 > x_0 \) \( x = x_1' > x_1 \) for \( u < u_1 \). As long as \( u > u_2 \), where \( u_2 < u_1 \) is a second critical value of \( u \), there will be at most three poles. As \( u \) decreases further, new pairs of poles appear at a sequence of critical values \( u_\ell \) of \( u \), and for any non-zero \( v \) one finds that \( \frac{d\bar{P}}{d\Omega} = \frac{\pi a}{\gamma} \{ c(x_0) e^{-\frac{u(x_0)}{\gamma}} + \sum_{\ell=1}^{2\ell_{\text{max}} + 1} c(x_\ell) e^{-\frac{u(x_\ell)}{\gamma}} + c(x_\ell') e^{-\frac{u(x_\ell')}{\gamma}} \} \), \( \Lambda \). The equation \( f(u) \equiv \sin x = ux = 0 \) then has no solution for \( u \) below a certain critical value \( u_x \), determined as follows. For \( u \) slightly above the critical value \( u_x \), there are two roots which become a double root at \( u = u_x \). At this point \( u = u_x \), \( f'(u) = \cos x - u = 0 \). Combining both equations, we find the critical value at \( \tan x_\ell = x_\ell \). \( x_\ell = 4.4934 \), \( u_x = \cos x_\ell \approx -0.2172 \). Since \( u = v \cos \varphi \sin \theta \), this critical point exists only at velocities \( v > v_c = |u_x| \approx 0.2172 \). At any velocity \( v > v_c \), there is no pole of the integrand of (2.19) within the contour whenever \( -\sin \theta \cos \varphi > \frac{v_c}{v} \). \( \Lambda \). In other words, there is no response from the detector in a ‘backward’ cone, with the forward axis defined by the detector velocity, \( \alpha \) such that \( \cos x = \frac{v_c}{v} \). \( \Lambda \). The angle \( \alpha \) goes to zero as \( v \to v_c \), while \( \alpha \to \arccos(v_c) \approx 0.57\pi \approx 77.5^\circ \) as \( v \to 1 \). The cone closes at \( v = v_c \), and for \( v < v_c \) the detector has a response in all directions.
\( u \) slightly above \( u_* \), the equation \( \sin x - ux = 0 \) has two roots \( x_1, x_2 \) and the detector response is of the form
\[
\frac{d\mathcal{P}}{d\Omega} = \frac{\pi a}{\gamma} \left( c(x_1) e^{\frac{2iu_1}{\gamma}} + c(x_2) e^{\frac{2iu_2}{\gamma}} \right). \tag{2.27}
\]
Again it should be noted that there is no discontinuous behaviour: the two terms give contributions of opposite signs which cancel as \( u \to u_* \).

2.3. Braneworld detector response and comparison with the Doppler-shifted spectrum

We now want to apply our results to the braneworld approach to motion in a Minkowski heat bath. We therefore consider a detector restricted to detect photons arriving from directions within the brane. Recalling that \( \theta \) is the angle that a photon’s 3-momentum makes with the \( X \)-axis, we see that we must set \( \theta = \frac{\pi}{2} \). For convenience, we define
\[
\frac{1}{8\pi^3} \frac{d\mathcal{F}}{d\varphi} \left|_{\theta=\pi/2} \right. = -\frac{a}{2\gamma} \int_{-\infty}^{\infty} d\xi \frac{e^{2i(\omega/\gamma)\xi}}{[\sinh \xi - v\xi \cos \varphi + i\epsilon]^2}. \tag{2.28}
\]
We have not been keeping track of an overall factor in the definition of the angular excitation rate of the detector, but this factor may now be fixed by considering the \( v \to 0 \) limit, in which case we find that
\[
\frac{1}{8\pi^3} \left. \frac{d\mathcal{F}}{d\varphi} \right|_{v=0} \frac{d\omega}{d\omega} = -\frac{\omega}{4\pi^2} \left( e^{\omega/T} - 1 \right), \tag{2.29}
\]
which is the Planck spectrum for the number density of ‘scalar photons’ in two space dimensions. More generally, therefore, we have
\[
n^{(2)}(\omega, \varphi) = \frac{1}{8\pi^3} \frac{d\mathcal{F}}{d\varphi} = -\frac{a}{16\pi^3\gamma} \int_{-\infty}^{\infty} d\xi \frac{e^{2i(\omega/\gamma)\xi}}{[\sinh \xi - \nu \xi \cos \varphi + i\epsilon]^2}. \tag{2.30}
\]
The integral can be evaluated as before and the result is obtained from the previous formulae (2.21) and (2.23) by setting \( \theta = \pi/2 \), so that \( u = v \cos \varphi \).

We shall be interested in comparing this result with what one finds from an application of the standard PPW theory for the distribution of massless particles in a radiation heat bath; for scalar particles in a two-dimensional space, this gives
\[
n^{(2)}_{\text{PPW}}(\omega, \varphi) = \frac{\omega}{4\pi^2(\omega/T_{\text{eff}} - 1)} \frac{T_{\text{eff}}}{1 - v \cos \varphi}, \tag{2.31}
\]
which is the 2-space dimensional analogue of (2.12). We consider in turn the case of non-relativistic and relativistic velocities.

- Non-relativistic velocities. For \( v \ll 1 \) we may expand the expression of (2.31) in powers of \( v \) to find that
\[
n^{(2)}_{\text{PPW}}(\omega, \varphi) = \frac{\omega}{4\pi^2(\omega/T - 1)} \frac{T}{1 - v \cos \varphi} + \frac{\omega^2 v \cos \varphi e^{-\omega/T}}{4\pi^2 T} \left( 1 - e^{-\omega/T} \right) + O(v^2). \tag{2.32}
\]
How does this compare with (2.30) in the same approximation? Expanding the integrand in powers of \( v \), we have
\[
n^{(2)}(\omega, \varphi) = -\frac{a}{16\pi^3\gamma} \sum_{n=0}^{\infty} (n+1) \int_{-\infty}^{\infty} d\xi \frac{e^{2i(\omega/\gamma)\xi} (v\xi \cos \varphi)^n}{[\sinh \xi + i\epsilon]^{n+2}}. \tag{2.33}
\]
We only need the \( n = 0, 1 \) terms in the sum. Using the residue calculus, and the Unruh formula \( 2\pi T = |A| = \gamma^2 a \), we find that
\begin{equation}
\begin{aligned}
n^{(2)}(\omega, \varphi) = \frac{\omega}{4\pi^2(\omega^2 - T^2)} + \frac{\omega^2 v \cos \varphi e^{-\omega/T}}{4\pi^2T(1 - e^{-\omega/T})^2} Q(\omega/T) + O(v^2),
\end{aligned}
\end{equation}

where

\begin{equation}
Q(\omega/T) = \left(1 - e^{-\omega/T}\right)^2 \left[1 - \frac{2T}{\omega} + \frac{\pi^2 T^2}{\omega^2} - \frac{2T}{\omega} e^{-\omega/T}\right].
\end{equation}

This differs from (2.32) by the additional factor \(Q\) multiplying the dipole term. This factor is a smooth monotonic function of \(\omega/T\) with the UV and IR limits

\begin{equation}
\begin{aligned}
\lim_{\omega/T \to \infty} Q = 1, \quad \lim_{\omega/T \to 0} Q = \pi^2/4.
\end{aligned}
\end{equation}

We therefore find agreement with (2.32) in the UV limit, as might be expected on the grounds that the scalar field excitations behave like a classical gas of massless particles in this limit. Otherwise, there is a discrepancy in the factor multiplying the dipole term, which increases to about a factor of 2 in the IR limit.

\begin{itemize}
  \item **Relativistic velocities.** In this case we need to return to the exact formula (2.30). The energy spectrum at \(\varphi = 0\) as compared to \(n^{(2)}_{\text{PPW}}(\omega, 0)\) is shown in figure 1(a) for \(v = 0.04\); in this case there are seven poles contributing to the sum (2.23). We see that the spectra are remarkably close at this velocity, differing slightly near the peak. The energy spectra continue to be close even for much higher velocities such as \(v = 0.15\) where only a single pole contributes to the integral and the spectrum \(n^{(2)}(\omega, 0)\) is exactly given by (2.21) divided by \(8\pi^3\). For this value of \(v\) the greatest deviation is at the peak of the spectrum and is of order 8%. At higher velocities the difference becomes substantial; for example, for \(v = 0.8\), the peak of the PPW energy spectrum is smaller by a factor of 5 and the PPW temperature (defined by the exponent of the tail) is higher by a factor of 1.8, as shown in figure 1(b).

Away from \(\varphi = 0\) there are other significant effects. We return to formulae (2.21) and (2.23) evaluated at \(\theta = \pi/2\). For \(v > |u_*| \approx 0.2172\), we find, for negative \(u_\ast\) the same ‘cone of silence’ within which the detector has no response because the integrand of (2.30) has no pole within the contour. This cone is now defined by \(\varphi > \varphi_0\), with \(\cos \varphi_0 = u_\ast/v\). The ‘cone of silence’ is obviously not a feature of the PPW formula (2.31).
Consider now $u \to 1$, which implies both $\varphi \to 0$ and $v \to 1$. In this case there is a single pole which is located at $x_0 = \sqrt{6}/\sqrt{1-v \cos \varphi} \to 0$; the leading behaviour is given by
\begin{equation}
\begin{split}
 n^{(2)}(\omega, \varphi) & \sim \frac{T}{16\pi\gamma^3} \frac{\sqrt{3}}{\sqrt{2}} \frac{\exp\left(-\frac{\sqrt{6}\omega}{\pi T} \sqrt{1-v \cos \varphi}\right)}{(1-v \cos \varphi)^{\frac{5}{2}}}.
\end{split}
\end{equation}

This is significantly different from the equivalent limit of formula (2.31).

3. Vacuum for acceleration with drift

It is well known that the thermal spectrum registered by an accelerating detector can be explained, in a detector-independent way, as a result of a difference of the Minkowski quantum vacuum to the (Fulling) vacuum of the Rindler spacetime. Specifically, the Bogoliubov transformation that relates the particle creation and annihilation operators in the two spacetimes is non-trivial, so that the Minkowski vacuum is a thermal state in the Rindler spacetime. It would be natural to suppose that our result for acceleration with drift has a similar explanation\(^4\), but the Bogoliubov transformation connecting the Fulling–Rindler vacuum with the analogous vacuum in a moving frame is trivial\(^{[15]}\). It might seem from this result that the photons available for detection at non-zero drift velocity are just the same photons that were available for detection at zero velocity, but Doppler shifted. However, there is more to this problem than just the Bogoliubov transformation; in particular, it was shown in\(^{[14,16]}\) that the stationary motion we call ‘acceleration with drift’ leads a geometry in which there is an ergo-region outside the acceleration horizon. We present here a summary of these results and then discuss the implications. This whole analysis can be carried out for arbitrary spacetime dimension $D$, in particular for the $D = 4$ case as well as for the $D = 3$ case that we have analysed from the perspective of detector response.

We begin with the $(D+1)$-dimensional Minkowski metric in the form
\begin{equation}
 ds^2 = -dt^2 + dx^2 + dy^2 + |\vec{z}|^2, \quad (3.1)
\end{equation}
where $\vec{z} = (z_1, \ldots, z_{D-2})$. The change of coordinates
\begin{equation}
 t = r \sinh \eta, \quad x = r \cosh \eta, \quad (3.2)
\end{equation}
gives the Rindler metric
\begin{equation}
 ds^2 = -r^2 d\eta^2 + dr^2 + dy^2 + |\vec{z}|^2. \quad (3.3)
\end{equation}
These coordinates cover only two portions of the Minkowski spacetime, the positive (‘right’) and negative (‘left’) Rindler wedges,
\begin{equation}
 R_+ = \{ x \mid x > |t| \}, \quad R_- = \{ x \mid x < -|t| \},
\end{equation}
which correspond, respectively, to positive and negative $r$. In these regions the Killing vector field $\partial_\eta = x \partial_t + t \partial_x$ is timelike, and a static observer at fixed $r$ has proper constant proper acceleration $a = 1/|r|$ (and proper time $\tau = a^{-1} \eta$). Rindler coordinates are thus ‘adapted’ to such observers.

To obtain the metric in coordinates adapted to an observer in the Rindler spacetime who is drifting in the $y$ direction with velocity $v$, we Lorentz boost the metric (3.3) in the $y$ direction. Note that this boost is not an isometry; this is the kinematical counterpart of the statement that a thermal bath breaks Lorentz invariance. We perform the boost by setting
\begin{equation}
 y = \gamma (\tilde{y} - v_0 \tilde{\eta}), \quad \tau = \gamma (\tau_0 - v_0 \tilde{y}), \quad v_0 = a^{-1}, \quad (3.4)
\end{equation}

\(^4\) For example, there is an Unruh-type effect associated with constant velocity motion through a medium with the refractive index $n > 1$\(^{[22]}\).
and rewriting the metric in terms of the new coordinates $(\tilde{\eta}, \tilde{y}, r, \vec{z})$:

\[
ds^2 = -r^2 \gamma^2 \left( d\tilde{\eta} - \frac{v}{r_0} d\tilde{y} \right)^2 + dr^2 + \gamma^2 (d\tilde{y} - vr_0 d\tilde{\eta})^2 + |d\vec{z}|^2
\]

\[
= -\gamma^2 (r^2 - v^2 r_0^2) d\tilde{\eta}^2 + 2\gamma^2 \frac{v}{r_0} (r^2 - r_0^2) d\tilde{y} d\tilde{\eta} + \gamma^2 \left( 1 - \frac{r^2 v^2}{r_0^2} \right) d\tilde{y}^2 + dr^2 + |d\vec{z}|^2.
\]

(3.5)

This metric is stationary, with respect to the new time variable $\tilde{\eta}$, but it is not static. There is still a coordinate singularity at $r = 0$, which is again the acceleration horizon, but there is also a ‘static limit’ surface at $r = vr_0$ [16]; the region between the horizon and this static limit surface is analogous to the ergo-region of a rotating black hole; see figure 2. The hypersurface at $r = r_0$ is $D$-dimensional Minkowski spacetime in standard coordinates

\[
ds^2|_{r=r_0} = -dt^2 + d\tilde{y}^2 + |d\vec{z}|^2,
\]

(3.6)

A static detector in this subspace has proper acceleration $\gamma^2 a$ in the larger space, where the $\gamma^2$ factor is a consequence of time dilation due to the uniform motion in the $y$ direction.

Consider now a complex massless scalar field $\phi$ in the $(D + 1)$-dimensional Minkowski spacetime, obeying the wave equation $\Box \phi = 0$. The norm of any solution $\phi$ is defined as (we follow the review article [8])

\[
\|\phi\| = -i \int d\Sigma^\mu (\phi^* \partial_{\mu} \phi - \phi \partial_{\mu} \phi^*),
\]

(3.7)

where $\Sigma$ is the volume element on an arbitrary spacelike hypersurface. A basis of solutions of positive norm is provided by the positive frequency plane parallel waves

\[
U_k = \frac{1}{[2\omega_k(2\pi)^D]^{1/2}} e^{i(-\omega_k t + k_x x + k_y y + k_z z)}, \quad \omega_k = \sqrt{k_x^2 + k_y^2 + |k|^2}.
\]

(3.8)
In Rindler coordinates, the solutions with the positive norm are again those of positive frequency, but where this is now defined with respect to the Rindler time $\eta$; these modes are

$$u_k^{(\sigma)} = \frac{\theta(\sigma r)}{[2\Omega(2\pi)^{D-1/2}]^{1/2}} h_k^{(\sigma)}(r) \exp[i(-\sigma \Omega \eta + k_y r + \vec{k} \cdot \vec{z})],$$

(3.9)

where $\sigma > 0$ for the positive Rindler wedge and $\sigma < 0$ for the negative Rindler wedge. Here we are using the fact that the timelike Killing vector $\partial_\eta$ is future directed on $\mathbb{R}^+$ and past directed on $\mathbb{R}^-$. In terms of the coordinate $r_* = \log |r|$, the equation of motion for the radial functions $h_k^{(\sigma)}(r)$ takes the form of a one-dimensional Schrödinger equation

$$-\frac{d^2}{dr_*^2} + \mu_k^2 e^{2r_*} h_k^{(\sigma)} = \Omega^2 h_k^{(\sigma)}, \quad \mu_k = \sqrt{k_y^2 + |\vec{k}|^2}.$$

(3.10)

At this point it is important to note that $\Omega$ is an arbitrary parameter that ranges from 0 to $\infty$, independent of the values of the momenta; the reason is that for any $\Omega > 0$ the solution is always oscillatory for sufficiently small $r_*$. The scalar field $\phi$ can be expanded either in terms of $U_k, U_k^*$ or in terms of $u_k^{(\sigma)}, u_k^{(\sigma)^*}, u_k^{(-\sigma)}, u_k^{(-\sigma)^*}$, as both sets constitute complete sets of modes:

$$\phi = \int d^D k \left( a_k U_k + \bar{a}_k U_k^* \right) + \int_0^\infty d\Omega \int d^{D-1} k \sum_{\sigma = \pm} \left( b_k^{(\sigma)} u_k^{(\sigma)} + \bar{b}_k^{(\sigma)} u_k^{(\sigma)^*} \right).$$

(3.11)

The linear transformation from $a_k, \bar{a}_k$ to $b_k^{(\sigma)}, \bar{b}_k^{(\sigma)}$ is a Bogoliubov transformation, which mixes modes of the positive and negative norm; it takes the form

$$b_k^{(\sigma)} = \int d^D k' \beta_k^{(\sigma)} a_k + \beta_k^{(\sigma)} \bar{a}_k.$$

(3.12)

The important implication is that the Minkowski vacuum state defined by

$$a_k(0)_M = \bar{a}_k(0)_M = 0 \quad \forall \ k$$

(3.13)

is not equivalent to the Fulling–Rindler vacuum state defined by

$$b_k^{(\sigma)}(0)_R = \bar{b}_k^{(\sigma)}(0)_R = 0 \quad \forall \sigma, k.$$

(3.14)

In particular, the expectation value of the Rindler particle number operator $N_k = h_k^{(\sigma)^\dagger} h_k^{(\sigma)}$ in the Minkowski vacuum is

$$\int d^D k' \beta_k^{(\sigma)} \beta_k^{(\sigma)^\dagger},$$

(3.15)

and as a result the Rindler observer is immersed in a thermal distribution of particles (see e.g. [8]).

We now aim to extend this analysis to the metric (3.5) adapted to the observer drifting with velocity $v$ parallel to the acceleration horizon. As $\phi$ is a scalar field, we can obtain the solutions of the wave equation in the new coordinates from those in the original Rindler coordinates by simply making the substitution (3.4):

$$\tilde{u}_k^{(\sigma)} = \frac{\theta(\sigma r)}{[2\Omega(2\pi)^{D-1/2}]^{1/2}} \tilde{h}_k^{(\sigma)}(r) \exp[i(-\sigma \tilde{\Omega} \eta + \tilde{k}_y r + \vec{\tilde{k}} \cdot \vec{z})],$$

(3.16)

where

$$\tilde{a} \tilde{\Omega} = \gamma (a \Omega + \sigma v k_y), \quad \tilde{k}_y = \gamma (k_y + \sigma v a \Omega).$$

(3.17)

5 We remind the reader that the spacetime dimension is $(D + 1)$. The integration is over the $D$ space dimensions.
The modes that were originally of the positive (negative) norm still have the positive (negative) norm, so the definition of the vacuum state is not affected by the boost [15]. This result shows that there is no change in the definition of a ‘particle’ as the drift velocity $v$ is changed, so a distribution of particles at 1 velocity can be obtained from the distribution at 0 velocity by the method of Pauli and Peebles and Wilkinson. From this perspective, it is a surprise that our explicit computation of the detector response yields a different distribution, at least for large drift velocity or, in the case of small drift velocity, away from the UV limit.

However, things are not quite so simple. As pointed out above, $\Omega_1$ and $k_y$ take independent values, $0 < \Omega < \infty$ and $-\infty < k_y < \infty$. This has the implication that a mode of positive (negative) frequency before the Lorentz boost becomes negative (positive) frequency after the boost if $vk_y < -\Omega$. This implies an instability of the vacuum [16], which can also be understood from the fact that there is an ergo-region outside the acceleration horizon. Ergo-regions of stationary rotating black holes lead to a spontaneous emission of radiation that has the effect of reducing the angular momentum and hence shrinking the ergo-region. We expect the same here, with the difference that angular momentum becomes linear momentum. This could go some way to explaining why the spectrum of particles detected by a particle detector is not simply the Doppler-shifted version of the spectrum at zero velocity.

4. Discussion

Unruh has shown how the local temperature of a static black hole may be understood kinematically near its horizon from the response of a static particle detector to the acceleration needed to maintain it at a fixed distance from the horizon. The detector effectively accelerates in a two-dimensional Minkowski space; equivalently, it is static in the two-dimensional Rindler spacetime. Applying this insight to static $p$-branes, one has the additional possibility of considering a detector in motion parallel to the horizon—in particular, motion at constant velocity. The metric ‘adapted’ to such a detector is still stationary, so one expects a time-independent response. On the other hand, the motion near the horizon can be understood as one of ‘acceleration with drift’ in a $(2 + p)$-dimensional Minkowski spacetime; as this is still a ‘stationary motion’ (in the sense that all extrinsic geometric invariants of the detector’s worldline are constant) one again expects a time-independent response. The latter interpretation allows a computation, from first principles, of the response of an Unruh–DeWitt monopole detector coupled to a massless scalar field. This is especially simple for $p = 2$, which is the case we consider. For zero drift velocity, the computation is a standard generalization of Unruh’s original computation and can be found in e.g. [18]; the excitation probability rate of the detector, as a function of its energy gap, is Planckian. For non-zero drift velocity, the excitation probability rate is direction dependent; the result after integration over angles has been considered previously [19] but our computation yields the full angular dependence.

Given this result, one can choose to consider only the response in directions orthogonal to the acceleration, equivalently in directions parallel to the 2-brane. From the perspective of a detector that is constrained to move in this plane, and to detect only particles that arrive from other points on it, it is effectively in a $(1 + 2)$-dimensional Minkowski radiation heat bath, at the Unruh temperature. We have called this the ‘braneworld’ model of a Minkowski heat bath. For low drift velocities, and in the UV limit in which the modes of the scalar field can be viewed as massless particles of a classical gas, we find that the response spectrum of the detector is just a Doppler-shifted version of the Planck spectrum, characterized by an angular-dependent ‘effective temperature’. This is just what would be predicted by the standard PPW
theory of inertial motion in a radiation heat bath. However, our computation does not agree, numerically, with the Doppler-shift formula in the IR limit, and gives a qualitatively different answer at large drift velocities.

This result raises several issues. At the very least, it provides a further example of how a particle detector in stationary motion does not always respond in the way that one might expect. In the special case of pure acceleration, the thermal response of the detector is often attributed to the different global features of Minkowski and Rindler spacetimes, and of the resulting difference between the Minkowski and Fulling–Rindler vacua. However, this cannot be the whole story because there are more distinct stationary motions than there are distinct quantum vacua, at least if two vacua are considered equivalent if the Bogoliubov transformation connecting them is trivial. We have already mentioned that the vacuum for acceleration with drift is equivalent, in this sense, to the Fulling–Rindler vacuum. It was further shown in [15] that for any stationary motion the quantum vacuum is equivalent, in this sense, to either the Minkowski vacuum or the Fulling–Rindler vacuum. In contrast, the local response of particle detectors on stationary worldlines is far more variable, being essentially different for each distinct stationary motion, and it is a challenge to understand why this is so (see e.g. [16, 17, 23]).

This issue was addressed for circular motion in [17]. The quantum vacuum for a detector undergoing uniform motion in a circle is actually equivalent to the Minkowski vacuum, despite the centripetal acceleration, so why does the detector detect particles? One may guess that the answer must have to do with the coordinate singularity at a critical radius in static co-rotating cylindrical polar coordinates, and it was shown in [17] that a co-rotating detector in the Minkowski vacuum does not detect particles if one assumes boundary conditions that remove the region of spacetime beyond the critical radius. For acceleration with drift, the resolution appears to be different. As we have mentioned, the appearance of an ergo-region outside the Rindler horizon is also expected to have an effect on a particle detector. However, it is difficult to understand how this could explain the ‘cone of silence’ that we have found above the critical velocity $v_c \sim 0.2172$.

Although we arrived at the ‘accelerating braneworld’ model of a radiation heat bath by consideration of motion near the horizon of a black brane, one may wonder whether it has a more general applicability. As we have pointed out in the introduction, this model is an essential ingredient of the GEMS approach to the thermodynamics of asymptotically flat black holes because each static observer in the asymptotic Minkowski spacetime at the Hawking temperature $T_H$ has, from the GEMS perspective, constant proper acceleration $2\pi T_H/\hbar$ in the embedding spacetime. Why the Unruh formula should ‘work’ in this context is something of a mystery: after all, the embedding spacetime is ostensibly no more than a mathematical construct, and there is no suggestion that the acceleration has any effect other than to produce a temperature. Nevertheless, the success of the GEMS program encourages the idea that the braneworld model of a radiation heat bath is of general applicability.

These considerations lead us to question the standard ‘Doppler-shift’ theory of motion in a radiation heat bath. In the first place, the assumption that the energy eigenstates, of energy $\hbar \omega$, of a quantum scalar field at temperature $T$ behave like particles of a classical gas is valid only in the UV limit in which $\hbar \omega \gg T$. One might expect angular-dependent induced emission effects to become important in the opposite, IR, limit. This is indeed what we have found from the ‘accelerating braneworld’ model, at least for small drift velocity. One may then ask what implication our results would have for the detection of photons in the CMBR if some analogous computation could be done in one higher dimension. To get some flavour of this, we conclude by exploring further the deviation of our formula (2.34) from the Doppler-shifted formula (2.31) for $v = 0.002$, which happens to be the approximate velocity of our local group.
of galaxies with respect to the CMBR rest frame. One finds that $\Delta n^{2}/n^{2} \sim 10^{-4}$, with the largest deviation occurring at $\varphi = \pi$.

However, if one focuses on the dipole term proportional to the detector velocity then one finds an appreciable discrepancy when $h\omega \sim T$ that climbs to about a factor of 2 as $h\omega/T \to 0$, although there is still agreement in the UV limit $h\omega/T \to \infty$. This is shown in figure 3.

A factor of 2 variation is fairly large, but it is possible that this factor would be found to be much smaller if we could compute the analogous result for motion in a $(1+3)$-dimensional Minkowski heat bath, in which case there would not be any obvious conflict with experimental data. One should also appreciate that since the CMBR experiment is calibrated on the dipole assuming a frequency-independent dipole factor, a small frequency dependence might get interpreted as an anomaly elsewhere. Our results suggest that it might be worthwhile to look for such frequency dependence in the CMBR data, or to analyse the implications for calibrations of assuming frequency independence.

Acknowledgments

We thank an anonymous referee of an earlier version of this paper for emphasizing the importance of the frequency dependence of the CMBR dipole moment. We also thank D Kothawala for a useful discussion. JGR acknowledges support by research grants MCYT FPA 2007-66665, 2005SGR00564. PKT thanks the EPSRC for financial support, and the University of Barcelona for hospitality.

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