Solving Bethe-Salpeter scattering state equation in Minkowski space

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We present a method to directly solving the Bethe-Salpeter equation in Minkowski space, both for bound and scattering states. It is based on a proper treatment of the singularities which appear in the kernel, propagators and Bethe-Salpeter amplitude itself. The off-mass shell scattering amplitude for spinless particles interacting by a one boson exchange is computed for the first time.

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I. INTRODUCTION

The interest in solving the Bethe-Salpeter (BS) equation [1] in its natural Minkowski-space formulation has increased in the recent years [2–18]. There are several reasons for dealing with Minkowski solutions. One of them is the fact that the Wick rotation is not directly applicable for computing electromagnetic form factors due to the singularities in the complex momentum plane [6,8]. The Euclidean solutions are still used in the context of BS-Schwinger-Dyson equations for computing bound-state form factors but this requires a huge numerical effort [19–26]. They can also be used to obtain on-shell observables like binding energies or phase shifts [27,28], whereas the computation of the off-shell BS scattering amplitude – mandatory for computing e.g. the transition e.m. form factor or for solving the three- and many-body BS equations – is possible only using a full Minkowski solution.

A method for computing these solutions based on the Nakanishi representation [29] of the BS amplitude was first developed in [2,3]. A similar approach combined with the light-front projection was proposed in [4,5]. It led to a different integral equation which involved only smooth functions and was numerically easy to treat. The bound state Minkowski amplitude and later on [6,8] the corresponding form factors were in this way computed for the first time. A modified method to the one developed in [4,5] aimed to compute the scattering states was proposed in [9]. It has already been successfully tested for the bound states [15].

Although our approach [4,5] could also be naturally extended to the scattering states, we have developed a new method [10,13] which allows to solve the Minkowski BS equation in a simplest and more straightforward way. It consists in a direct solution of the equation which takes properly into account the many singularities and without making use of the Nakanishi integral representation. The aim of this paper is to present this method in detail with applications to the problem of two scalar particles interacting by a one-boson exchange kernel.

Some of the results have been presented in the short publications [10,12] and reviewed in [13] without a detailed explanation of the method. Until now, the off-shell BS amplitude has been computed only for a separable kernel [30].

In Sec. II we transform the Bethe-Salpeter equation to the form which does not contain the pole singularities. In Sec. III we analyze the kernel singularities. Section IV is devoted to the extraction of the phase shifts from the computed Minkowski amplitude. We derive in Sec. V the system of equations which couples the Euclidean amplitude with the Minkowski one for a particular value of its arguments. The comparison between the direct solution in Minkowski space and the one found using this system of equations constitutes a strong test for our approach. The numerical results are presented in Sec. VI. They concern the half-off-shell BS amplitude, the scattering length and the elastic and inelastic phase shifts. Sec. VII contains some concluding remarks. Technical details are given in appendices A, B and C.

II. TRANSFORMING THE BS EQUATION

Let us consider the scattering of two equal mass (m) particles with initial (k_{1s}) and final (k_{1f}) four-momenta respectively

\[ k_{1s} + k_{2s} \rightarrow k_1 + k_2 \]

The corresponding BS amplitude \( F \) is parametrized in terms of the total

\[ p = k_1 + k_2 = k_{1s} + k_{2s} \] (1)
and relative momenta

\[ \begin{align*}
2k &= k_1 - k_2 \\
2k_s &= k_{1s} - k_{2s}
\end{align*} \]  

(2)

The subscript \( s \) means "scattering" (on-mass-shell) momenta. For a scattering process, \( F \) obeys the inhomogeneous integral equation graphically represented in Fig. 1.

\[ \begin{align*}
F(k, k_s; p) &= K(k, k_s; p) - i \int \frac{d^4k'}{(2\pi)^4} \frac{K(k, k'; p)F(k', k_s; p)}{\left( \frac{p}{2} + k' \right)^2 - m^2 + i\epsilon} \left[ \left( \frac{p}{2} - k' \right)^2 - m^2 + i\epsilon \right] 
\end{align*} \]  

(3)

We will consider all along this article the case of spinless particles interacting by the one-boson exchange kernel \( K \):

\[ K(k, k'; p) = -\frac{16\pi m^2\alpha}{(k - k')^2 - \mu^2 + i\epsilon}, \]  

(4)

where \( \alpha = g^2/(16\pi m^2) \) is the dimensionless coupling constant. In the non relativistic limit, this kernel leads to the Yukawa potential \( V(r) = -\alpha \exp(-\mu r)/r \). We denote by \( M^2 = p^2 \), the squared total invariant mass of the system.

The amplitude \( F \) depends on the three four-momenta \( k, k_s, p \). In the center of mass frame, defined by \( \vec{p} = 0 \), one has \( k_s = (0, \vec{k}_s) \) and \( p_0 = M = 2\varepsilon k_s = 2\sqrt{m^2 + k_s^2} \). For a given incident momentum \( \vec{k}_s \), \( F \) depends on the three scalar variables \( k_0, \vec{k} \) and \( z = \cos(\vec{k}, \vec{k}_s) \). It will be hereafter denoted by \( F(k_0, k, z) \), setting abusively \( k = |\vec{k}|, k_s = |\vec{k}_s| \).

Notice that the solution thus obtained is the half-off-mass shell amplitude. It is a particular case of the so called full off-shell amplitude \( F(k_0, k, z; k_0s, k_s; M) \). The latter, in addition to the variables \( k_0, k, z, \) de-
pends also on the off-shell independent variables \( k_0, k_s \), now with \( k_0 \neq 0 \) and \( k_0 \neq \varepsilon_{k_s} \) and the total mass \( M \) which is an independent parameter neither equal to \( 2\varepsilon_{k_s} \) nor related to \( k_0 \). By "off-shell amplitude" we will hereafter mean the half-off-shell amplitude. The method we have developed can also be applied to the full off-shell amplitude, though the dependence of the latter on two extra variables \( k_0, k_s \) requires much more extensive numerical calculations and will not be considered here.

The difficulty in computing the off-shell amplitude \( F(k_0, k, z) \) in the entire domain of its arguments is due to the singular character of the inhomogeneous term \( K \) and as well as of each of the factors in the integrand of equation (3). In particular the singular character of the amplitude \( F \) itself makes it hardly representable in terms of smooth functions. These singularities are integrable in the mathematical sense, due to \( i\epsilon \) in the denominators of propagators, but their integration is a quite delicate task and requires the use of appropriate analytical as well as numerical methods.

To avoid these problems, equation (3) was first solved on-shell \(^{[27]}\) by rotating the integration contour \( k_0 \rightarrow ik_4 \) and taking into account the contributions of the crossed singularities. These singularities are absent in the bound state case but exist for the scattering states. A similar method will be developed in Sec. \( \text{V} \) as a test of our approach.

The off-shell amplitude \( F(k_0, k, z) \) can be obtained by directly solving the corresponding three-dimensional equation derived from (3) after integrating over the azimuthal variable. However we prefer to present in what follows its partial wave solution. This procedure, apart from the much smaller numerical cost, has the advantage of smoothing the kernel singularities in particular in the inhomogeneous term. The partial wave amplitude \( F_L(k_0, k) \) is defined as \(^{[31]}\):

\[
F(k_0, k, z) = 16\pi \sum_{L=0}^{\infty} (2L + 1) F_L(k_0, k) P_L(z)
\]

where \( P_L(z) \) is the Legendre polynomial and

\[
F_L(k_0, k) = \frac{1}{32\pi} \int_{-1}^{1} dz \, P_L(z) F(k_0, k, z)
\]

By inserting (5) into (3) we obtain a set of uncoupled two dimensional equations for the partial amplitudes \( F_L \).

\[
F_L(k_0, k) = F^B_L(k_0, k) - i \int_0^\infty k'^2 \, dk' \int_{-\infty}^{\infty} dk'_0 \epsilon \left( k'_0 - a_\epsilon + i\epsilon \right) \left( k'_0 + a_\epsilon - i\epsilon \right) \left( k'_0 - a_\epsilon + i\epsilon \right) \left( k'_0 + a_\epsilon - i\epsilon \right)
\]

with

\[
W_L(k_0, k, k'_0, k') = \frac{1}{(2\pi)^3} \int_{-1}^{1} dz \, P_L(z) K(k, k'; p)
\]

and the inhomogeneous (Born) term \( F^B_L \) is given in terms of \( W_L \) by:

\[
F^B_L(k_0, k) = \frac{\pi^2}{4} W_L(k_0, k, k'_0 = 0, k' = k_s)
\]

The denominator of (3) has been factorized by writing (in the c.m. frame).

\[
\begin{align*}
\left( \frac{p}{2} + k' \right)^2 - m^2 + i\epsilon &= (\varepsilon_{k_s} + k'_0)^2 - (\varepsilon_{k'} - i\epsilon)^2 \\
\left( \frac{p}{2} - k' \right)^2 - m^2 + i\epsilon &= (\varepsilon_{k_s} - k'_0)^2 - (\varepsilon_{k'} - i\epsilon)^2
\end{align*}
\]

and making the replacement \(-\varepsilon_{k'}^2 + i\epsilon \rightarrow -(\varepsilon_{k'} - i\epsilon)^2\), valid since it does not change the sign of imaginary contribution. This leads to the expression displayed in (7) where the four propagator poles are made explicit. They are symmetric with respect the origin in the complex \( k'_0 \)-plane and are given by

\[
\begin{align*}
k'_0^{(1)} &= \varepsilon_{k_s} + \varepsilon_{k'} - i\epsilon = +a_+ - i\epsilon \\
k'_0^{(2)} &= \varepsilon_{k_s} - \varepsilon_{k'} + i\epsilon = -a_- + i\epsilon \\
k'_0^{(3)} &= -\varepsilon_{k_s} + \varepsilon_{k'} - i\epsilon = +a_- - i\epsilon \\
k'_0^{(4)} &= -\varepsilon_{k_s} - \varepsilon_{k'} + i\epsilon = -a_+ + i\epsilon
\end{align*}
\]

with

\[
a_\pm = \varepsilon_{k'} \pm \varepsilon_{k_s}
\]
Notice that \( a_+ > 0 \) while for the scattering process \( a_- \) vs. \( k' \) changes sign and \( a_-(k' = k_s) = 0 \).

We will be hereafter restricted the Bethe-Salpeter solutions for S-wave. The corresponding kernel \( W_0 \) is given by:

\[
W_0(k_0, k, k', k'_0) \equiv \frac{1}{kk'}w_0(\eta) = -\frac{\alpha m^2}{\pi kk'} \left\{ \frac{1}{\pi} \log \left| \frac{\eta + 1}{\eta - 1} \right| - iI(\eta) \right\} \tag{11}
\]

with

\[
I(\eta) = \begin{cases} 
1 & \text{if } |\eta| \leq 1 \\
0 & \text{if } |\eta| > 1 
\end{cases}
\]

\[
\eta = \frac{(k_0 - k'_0)^2 - k^2 - k'^2 - \mu^2}{2kk'} \tag{12}
\]

The solution of (7) faces three kind of problems, all related to the unavoidable singularities when working in Minkowski metric, and must be properly treated before a numerical solution can be tried.

First are the four propagator poles in the right hand side of (7) which are explicitly given by (9).

Second are the logarithmic singularities of the kernel \( W_0 \) which make difficult its numerical integration both in \( k'_0 \) and \( k' \) variables.

Third, are the singularities of the inhomogeneous term \( F_B^0 \). They are related to the previous ones, i.e. \( W_0 \), but generate a different type of problems: they imply the singular character of the amplitude \( F_0 \) we are interested in, and thus a difficulty in being represented in terms of smooth functions when solving numerically equation (7).

In the following subsections we will examine separately each of these points and detail our approach to circumvent the related difficulties.

**A. Removing the pole singularities**

Let us first represent the pole contributions in the integrand of (7) in the usual form:

\[
\frac{1}{k'_0 - a_\pm + i\epsilon} = PV \left( \frac{1}{k'_0 - a_\pm} \right) - i\pi\delta(k'_0 - a_\pm),
\]

\[
\frac{1}{k'_0 + a_\pm - i\epsilon} = PV \left( \frac{1}{k'_0 + a_\pm} \right) + i\pi\delta(k'_0 + a_\pm)
\]

where PV denotes the principal value. The integrand in the r.h.-side of Eq. (7) takes the form
\[
\frac{f(k_0, k, k'_0, k')}{(k'_0 - a_+ + i\epsilon)(k'_0 + a_+ - i\epsilon)(k'_0 + a_- - i\epsilon)(k'_0 - a_- + i\epsilon)} = \left[ -i\pi \delta(k'_0 - a_+) + PV \frac{1}{k'_0 - a_+} \right] \\
\times \left[ i\pi \delta(k'_0 + a_+) + PV \frac{1}{k'_0 + a_+} \right] \\
\times \left[ -i\pi \delta(k'_0 - a_-) + PV \frac{1}{k'_0 - a_-} \right] \\
\times \left[ i\pi \delta(k'_0 + a_-) + PV \frac{1}{k'_0 + a_-} \right] f(k_0, k, k'_0, k')
\]  
(13)

with the notation
\[
f(k_0, k, k'_0, k') \equiv W_0(k_0, k, k'_0, k')F_0(k'_0, k')
\]  
(14)

By expanding this expression we obtain the integral term on the r.h.-side of (7) as a sum of terms containing respectively products of 4, 3, 2, 1 and 0 delta-functions to be integrated over \( k'_0 \) and \( k' \) variables:
\[
I = I_4 + I_3 + I_2 + I_1 + I_0
\]

The terms \( I_4 \) and \( I_3 \) containing a products of four and three delta-functions are always zero since the arguments of \( \delta \)'s cannot vanish simultaneously.

Among the terms \( I_2 \) containing the product of two delta-functions, and for the same reasons than in the previous case, only the one containing \( \delta(k'_0 - a_-)\delta(k'_0 + a_-) \) gives a non zero contribution to the integral when \( k'_0 = \pm a_- = 0 \), that is when \( \varepsilon_{k'} = \varepsilon_{k} \). This contribution reads:

\[
I_2 = -i\pi^2 \int_0^\infty k'^2 \, dk' \int_{-\infty}^{+\infty} dk'_0 \delta(k'_0 - a_-)\delta(k'_0 + a_-) \frac{f(k_0, k, k'_0, k')}{k'_0 - a_+} \\
= +i\pi^2 \int_0^\infty dk' \delta[2(\varepsilon_{k'} - \varepsilon_{k})] \frac{1}{4\varepsilon_{k'}\varepsilon_{k}} \frac{1}{k'_0 - a_+} f(k_0, k, 0, k') = \frac{i\pi^2 k}{8\varepsilon_{k}} W_0(k_0, k, 0, k')F_0(0, k')
\]  
(15)

where we have used
\[
\frac{1}{a_-^2 - a_+^2} = -\frac{1}{4\varepsilon_{k'}\varepsilon_{k}}
\]  
(16)

\[
\delta[\varepsilon_{k'} - \varepsilon_{k}] = \frac{\varepsilon_{k}}{k} \delta(k' - k)
\]  
(17)

The sum of the four terms from (13) containing one delta-function reads:

\[
I_1 = -i \int_0^\infty k'^2 \, dk' \int_{-\infty}^{+\infty} dk'_0 f(k_0, k, k'_0, k') \\
\times \left[ -i\pi \delta(k'_0 - a_+) \frac{1}{k'_0^2 - a_-^2} PV \frac{1}{k'_0 + a_+} + i\pi \delta(k'_0 + a_+) \frac{1}{k'_0^2 - a_+^2} PV \frac{1}{k'_0 - a_+} \\
- i\pi \delta(k'_0 - a_-) \frac{1}{k'_0^2 - a_+^2} PV \frac{1}{k'_0 + a_-} + i\pi \delta(k'_0 + a_-) \frac{1}{k'_0^2 - a_-^2} PV \frac{1}{k'_0 - a_-} \right]
\]  
(18)
After integrating over $dk'_0$, the two integrals over $dk'$ remain:

$$I_1 = \frac{\pi}{4\varepsilon_{k_s}} PV \int_0^\infty \frac{k'^2dk'}{2\varepsilon_{k'}a_-} [f(k_0, k, k'_0 = a_-, k') + f(k_0, k, k'_0 = -a_-, k')]$$

$$- \frac{\pi}{4\varepsilon_{k_s}} \int_0^\infty \frac{k'^2dk'}{2\varepsilon_{k'}a_+} [f(k_0, k, k'_0 = a_+, k') + f(k_0, k, k'_0 = -a_+, k')]$$

(19)

Since the $W_0$ kernel is symmetric with respect to the change of sign of variables $k_0, k'_0$

$$W_0(-k_0, k, -k'_0, k') = W_0(k_0, k, k'_0, k')$$

the solution $F_0(k_0, k)$ is also symmetric, that is: $F_0(-k_0, k) = F_0(k_0, k)$. By inserting this relation in (19), one can see that the symmetrized value of the kernel $W_0$ with respect to the variable $k'_0$

$$W_0^S(k_0, k, k'_0, k') = W_0(k_0, k, k'_0, k') + W_0(k_0, k, -k'_0, k')$$

(20)

appears naturally in the formulation. After substituting (14) and (20) in (19) one gets:

$$I_1 = \frac{\pi}{4\varepsilon_{k_s}} PV \int_0^\infty \frac{k'^2dk'}{2\varepsilon_{k'}a_-} W_0^S(k_0, k, a_-, k')F_0(a_-, k') - \frac{\pi}{4\varepsilon_{k_s}} \int_0^\infty \frac{k'^2dk'}{2\varepsilon_{k'}a_+} W_0^S(k_0, k, a_+, k')F_0(a_+, k')$$

(21)

The first integrand in (21) is singular due to the factor $a_- = \varepsilon_{k'} - \varepsilon_{k_s}$ in the denominator which vanishes at $k' = k_s$. It must be understood in the sense of principal value. The integral is well defined but, because of the singularity of the integrand at $k' = k_s$, explicitly manifested in the form:

$$\frac{1}{a_-} = \frac{1}{\varepsilon_{k'} - \varepsilon_{k_s}} = \frac{\varepsilon_{k'} + \varepsilon_{k_s}}{k'^2 - k_s^2}$$

it requires an additional treatment to be transformed in a non-singular form. The singularity is eliminated using the subtraction technique, that is

$$PV \int_0^\infty \frac{h(k')}{{k'}^2 - a^2} = \int_0^\infty dk' \left[ \frac{h(k') - h(a)}{{k'}^2 - a^2} \right]$$

(22)

based on the identity:

$$PV \int_0^\infty \frac{1}{{k'}^2 - a^2} = 0, \quad \text{if} \quad a \neq 0.$$  

(23)

The condition $a \neq 0$ prevent us from setting $k_s = 0$ in our equation.

The second integrand in (21) is non-singular and it does not require any additional treatment.

Let us finally consider in (13) the term which does not contain any delta-function. Its contribution to r.h.-side of the equation can be represented as:
\[ I_0 = -i \int_0^\infty k'^2 dk' \operatorname{PV} \int_{-\infty}^{\infty} \frac{f(k_0, k, k'_0, k')}{(k'_0 - a_-)(k'_0 + a_+)(k'_0 - a_+)(k'_0 + a_+)} dk'_0 \]
\[ = -i \int_0^\infty \frac{k'^2 dk'}{4\varepsilon_{k_s} \varepsilon_{k'}} \operatorname{PV} \int_{-\infty}^{\infty} dk'_0 f(k_0, k, k'_0, k') \left[ \frac{1}{(k'_0 - a_-^2)} - \frac{1}{(k'_0 - a_+^2)} \right] = I_0^+ + I_0^- \]

The singularity \( \frac{1}{(k'_0 - a_-^2)} \) in \( I_0^+ \) is regularized by using the same subtraction technique \((22)\) than previously.

\[ I_0^+ = -i \int_0^\infty \frac{k'^2 dk'}{4\varepsilon_{k_s} \varepsilon_{k'}} \operatorname{PV} \int_{-\infty}^{\infty} \frac{f(k_0, k, k'_0, k')}{(k'_0 - a_-^2)} \]
\[ = -i \int_0^\infty \frac{k'^2 dk'}{4\varepsilon_{k_s} \varepsilon_{k'}} \operatorname{PV} \int_{-\infty}^{\infty} dk'_0 \left[ \frac{f(k_0, k, k'_0, k')}{(k'_0 - a_-^2)} - \frac{f(k_0, k, a_+, k')}{(k'_0 - a_+^2)} \right] \]

which has been derived in appendix \((13)\). For \( a = a_- = \varepsilon_{k'} - \varepsilon_{k_s} \), it takes the form:

\[ \operatorname{PV} \int_{-\infty}^{\infty} \frac{dk'_0}{[k'_0^2 - (\varepsilon_{k'} - \varepsilon_{k_s})^2]} = \frac{\pi^2}{2} \delta(\varepsilon_{k'} - \varepsilon_{k_s}) \quad (25) \]

The subtraction formula \((22)\) must now be replaced by

The integrand of the first term in \((26)\) – inside the square brackets – is again regular.

\[ I_0^- = i \int_0^\infty \frac{k'^2 dk'}{4\varepsilon_{k_s} \varepsilon_{k'}} \operatorname{PV} \int_{-\infty}^{\infty} \frac{f(k_0, k, k'_0, k')}{k'_0^2 - a_-^2} \]
\[ = i \int_0^\infty \frac{k'^2 dk'}{4\varepsilon_{k_s} \varepsilon_{k'}} \int_{-\infty}^{\infty} dk'_0 \left[ \frac{f(k_0, k, k'_0, k'_0)}{k'_0^2 - a_-^2} - \frac{f(k_0, k, a_-, k'_0)}{k'_0^2 - a_+^2} \right] + \frac{i\pi^2}{2} \int_0^\infty \frac{k'^2 dk'}{4\varepsilon_{k_s} \varepsilon_{k'}} \delta(\varepsilon_{k'} - \varepsilon_{k_s}) f(k_0, k, a_-, k') \quad (26) \]

The last term is transformed using relation \((17)\) and performing the integral over \( k' \) into:

\[ \frac{i\pi^2}{2} \int_0^\infty \frac{k'^2 dk'}{4\varepsilon_{k_s} \varepsilon_{k'}} \delta(\varepsilon_{k'} - \varepsilon_{k_s}) f(k_0, k, a_-, k') = \frac{i\pi^2 k_s^2}{8\varepsilon_{k_s}} f(k_0, k, a_-, k_s) = \frac{i k_s^2}{8\varepsilon_{k_s}^2} W_0(k_0, k, 0, k_s) F_0(0, k_s) \quad (27) \]

It gives exactly the same contribution as the two-delta term \((15)\). The sum of these two contributions results into multiplying the coefficient in \((15)\) by a factor 2. Since, as noticed above, the solution \( F_0(k_0, k) \) is symmetric with respect to \( k_0 \to -k_0 \), the equation \((7)\) can be reduced to the interval \( k_0 \in [0, \infty] \). After
reducing the integral term to the same interval in $k'_0$ and introducing the symmetric kernel $W_S$ given by (20), we finally obtain the S-wave equation that we aimed to solve and that does not contain the pole singularities:

\[
F_0(k_0, k) = F_0^B(k_0, k) + \frac{i\pi^2 k_s}{8\varepsilon_{k_s}} W_0^S(k_0, k, 0, \varepsilon_s) F_0(0, \varepsilon_s) \\
+ \frac{\pi}{2M} \int_0^\infty \frac{dk'}{2\varepsilon_{k'}(2\varepsilon_{k'} - M)} \left[ k'^2 W_0^S(k_0, k, a_-, k') F_0(|a_-|, k') - \frac{2k_s^2 \varepsilon_{k'}}{\varepsilon_{k'} + \varepsilon_{k_s}} W_0^S(k_0, k, 0, k_s) F_0(0, k_s) \right] \\
- \frac{\pi}{2M} \int_0^\infty \frac{k'^2 dk'}{2\varepsilon_{k'}} W_0^S(k_0, k, a_+, k') F_0(a_+, k') \\
+ \frac{i}{2M} \int_0^\infty \frac{k'^2 dk'}{2\varepsilon_{k'}} \int_0^{\infty} dk'_0 \left[ W_0^S(k_0, k, k', k'_0) F_0(k'_0, k') - W_0^S(k_0, k, a_-, k') F_0(|a_-|, k') \right] \\
- \frac{i}{2M} \int_0^\infty \frac{k'^2 dk'}{2\varepsilon_{k'}} \int_0^{\infty} dk'_0 \left[ W_0^S(k_0, k, k', k'_0) - W_0^S(k_0, k, a_+, k') F_0(a_+, k') \right]
\]

(28)

Notice the appearance of the absolute value in the argument $|a_-|$ and that the relation $W_0^S(k_0, k, 0, k_s) = 2W_0(k_0, k, 0, k_s)$ accounts for the factor 8 in the denominator of the non-integral term. We remind also that $M = 2\varepsilon_{k_s}$.

The origin of the different terms appearing in (25) is quite clear:

- The non-integral term (second term in the first line) is a sum of two equal contributions in (13): the first one comes from the two $\delta$-functions term $I_2$, Eq. (15), and the second one comes from the term without $\delta$-functions, precisely the last term in the subtraction (26) given by Eq. (27).

- The one-dimensional integral terms (second and third lines) result from the contribution $I_1$, Eq. (21), i.e., from the four contributions of one $\delta$-function terms – $\delta(k'_0 + a_-)$ in second line and $\delta(k'_0 - a_+)$ in third line – after integration over $k'_0$.

- The last two lines come from the product of four principal values (no $\delta$-function), the contribution $I_0$, Eq. (24), however without the term (27), which is incorporated in the non-integral term in the first line of the equation (28).

The differences appearing in squared brackets (2nd, 4th and 5th lines) correspond to the subtractions (22) and (20) used to remove the pole singularities: $2\varepsilon_{k'} = M$ in second line, $k'_0 = a_-$ in forth and $k'_0 = a_+$ in fifth lines respectively.

## III. KERNEL SINGULARITIES

In view of the numerical integration of (28), it is useful to know the precise positions of the singularities both in the kernel and in the Born term.

The above considerations were devoted to treat the poles of the free constituent propagators. However these singularities are not the only ones. The propagator of the exchanged particle, i.e. the kernel (4), also has two poles which, after partial wave decomposition, turn into the logarithmic singularities of the $W_0$ kernel (11). Though the log-singularities can be integrated numerically by "brut force", to improve precision, it is useful to treat them too. Their positions are found analytically, both in $k'_0$ and $k'$ variables.

Let us first consider the singularities on $k'_0$. It follows from (11), that $W_0$ is singular when $|\eta(k_0, k, k'_0)| = 1$, where $\eta$ is defined by (12). Solving two equations $\eta = \pm 1$ relative to $k'_0$ we find the four singularities of $W_0$:

\[
k'_0 = k_0 + \sqrt{\mu^2 + (k \pm k')^2}, \quad k'_0 = k_0 - \sqrt{\mu^2 + (k \pm k')^2},
\]

(29)
The symmetric kernel $W_0^S$ has four additional singularities when $| \eta(k_0, k, -k_0', k') | = 1$. Together with (29), it means that $W_0^S$ is singular at the eight points:

\[
\begin{align*}
    k_0' &= k_0 + \sqrt{\mu^2 + (k' \pm k)^2}, \\
    k_0' &= k_0 - \sqrt{\mu^2 + (k' \pm k)^2}, \\
    k_0' &= -k_0 + \sqrt{\mu^2 + (k' \pm k)^2}, \\
    k_0' &= -k_0 - \sqrt{\mu^2 + (k' \pm k)^2}. \\
\end{align*}
\]  

(30)

However, since the equation (28) was reduced to the interval $0 < k_0' < \infty$, one should take into account only the singularities on the positive axis $k_0' > 0$. This is equivalent to take the absolute value of $k_0'$, that is $W_S$ is singular at the four $k_0'$ values:

\[
\begin{align*}
    k_0' &= | k_0 + \sqrt{\mu^2 + (k' \pm k)^2} |, \\
    k_0' &= | k_0 - \sqrt{\mu^2 + (k' \pm k)^2} |.
\end{align*}
\]

Their positions depend on the integration variable $k'$ (moving singularities) as well on the external momenta $k_0$ and $k$.

The numerical integration over $k_0'$ is split into as many intervals as needed in order to contain a single singularity in only one of its borders. The integral over each of these intervals is made safely by choosing an appropriate change of variable.

The kernel singularities in the $k'$-variable manifest themselves only in the 2nd and 3rd lines of equation (28). They are also given by the solutions, with respect to $k'$, of $\eta(k_0, k, k_0', k') = \pm 1$ and $\eta(k_0, k, -k_0', k') = \pm 1$ for the particular values $k_0' = a_\pm$. For the symmetrized $W_0^S$ kernel, this gives the positions detailed in what follows.

The term with $k_0' = a_-$, written in the second line of Eq. (28), is singular at:

\[
\begin{align*}
    k_{-,-} &= \frac{\epsilon kQ_+ - d_+ \sqrt{Q_+^2 - 4m^2(d_+^2 - k^2)}}{2(d_+^2 - k^2)}, \quad \epsilon = \pm 1
\end{align*}
\]

where

\[
Q_+ = d_+^2 - k^2 + m^2 - \mu^2, \quad d_+ = k_0 + \frac{M}{2}, \quad M = 2 \varepsilon k_+.
\]

That is, the integrand of the second term vs. $k'$ has the four singularities denoted by $k_{-,-1,2,3,4}$:

\[
\begin{align*}
    k_{-,-1} &= \frac{\epsilon kQ_+ + d_+ \sqrt{Q_+^2 - 4m^2(d_+^2 - k^2)}}{2(d_+^2 - k^2)}, \\
    k_{-,-2} &= \frac{+kQ_+ - d_+ \sqrt{Q_+^2 - 4m^2(d_+^2 - k^2)}}{2(d_+^2 - k^2)}, \\
    k_{-,-3} &= \frac{-kQ_+ + d_+ \sqrt{Q_+^2 - 4m^2(d_+^2 - k^2)}}{2(d_+^2 - k^2)}, \\
    k_{-,-4} &= \frac{-kQ_+ - d_+ \sqrt{Q_+^2 - 4m^2(d_+^2 - k^2)}}{2(d_+^2 - k^2)}.
\end{align*}
\]

(31)

The term with $k_0' = a_+$, written in the third line of Eq. (28), is singular at:

\[
\begin{align*}
    k_{+} &= \frac{\epsilon kQ_- + d_- \sqrt{Q_-^2 - 4m^2(d_-^2 - k^2)}}{2(d_-^2 - k^2)}, \quad \epsilon = \pm 1
\end{align*}
\]

where

\[
Q_- = d_-^2 - k^2 + m^2 - \mu^2, \quad d_- = k_0 - \frac{M}{2}.
\]

That is the integrand has the four singularities $k_{+,1,2,3,4}$. Their positions are obtained from Eqs. (31) by the replacement $Q_+ \to Q_-, d_+ \to d_-$. Since the integration domain of the $k'$ variable is positive, one should take into account only the real and positive values of the above singularities.

A. Born term

The S-wave Born term (8) is singular both in $k_0$ and $k$ variables. The singularities are logarithmic in its real part and Heaviside-like discontinuities in the imaginary one. Their positions can be found from the condition $| \eta(k_0, k, k_0', k'/k_s) | = 1$, where $\eta$ is defined in (12).

In $k_0$-variable (see Fig. 3 upper part), there are two singularities at the points

\[
k_0(k) = \sqrt{(k \pm k_s)^2 + \mu^2}
\]

for any value of $k$.

In the variable $k$ (see Fig. 3 bottom) the singularities (in its definition domain $k > 0$) are given by the same equation rewritten in the form:

\[
k(k_0) = \left| k_0 \pm \sqrt{k_0^2 - \mu^2} \right|
\]

and exist only for $k_0 > \mu$. 

The Minkowski BS amplitude $F_0$ has many non-analyticities due to its Born term $F_0^B$ and to the interaction kernel, including inelastic threshold effects. However, the only singularities (infinite values and discontinuities) in the physical domain of its arguments are those originated by the Born term $F_0^B$ itself. Their existence makes difficult representing $F_0$ on a basis of regular functions in view of a numerical solution of Eq. (31). To circumvent this problem we factorize out the Born amplitude by making the replacement

$$F_0 = F_0^B \chi f_0$$

(32)

where $f_0$ is a smoother function obeying the BS transformed equation

$$F_0 = F_0^B + KF_0 \Rightarrow f_0 = \frac{1}{\chi} f_0 [K F_0^B \chi f_0]$$

$\chi$ is an arbitrary but suitable function introduced to provide a convenient inhomogeneous term. After that, the singularities of the $F_0$ are casted into the kernel and integrated using the same procedure as above. We obtain in this way a non-singular equation for a non-singular function $f_0$ which can be solved by standard methods.

The off-mass shell BS amplitude $F_0$ in Minkowski space can be thus safely computed.

**IV. EXTRACTING SCATTERING OBSERVABLES**

The amplitude $F(k, k_s; p)$ satisfying the BS equation (3) is related to the $S$-matrix by:

$$S = 1 + i(2\pi)^4 \delta^{(4)}(p - p_f) F(k, k_s; p)$$

The unitarity condition for $S$-matrix $S^\dagger S = 1$ is rewritten in terms of the amplitude $F^{on}(k, k_s; p)$ (which is on the mass-shell $k_1^2 = k_2^2 = k_{1s}^2 = k_{2s}^2 = m^2$) as follows:

$$i(F^{on} - F^{on}) = \int F^{on} F^{on} (2\pi)^4 \delta^{(4)}(p - k_1 - k_2) \frac{d^3k_1}{(2\pi)^3 2 \varepsilon_1} \frac{d^3k_2}{(2\pi)^3 2 \varepsilon_2}$$

(33)

The sum over intermediate states in the product $S^\dagger S$ is understood as integration with the measure given in (33). After substituting the partial waves decomposition (5) in the equation (33) the latter obtains the form:

$$i(F^{on}_L - F^{on}_L) = \frac{2k_s}{\varepsilon_{k_s}} |F^{on}_L|^2$$

(34)
where \( F_L^{on} \equiv F_L(k_0 = 0, k = k_s) \) is the on-shell amplitude. The function satisfying Eq. (34) is represented as:

\[
F_L^{on} = \frac{\varepsilon_{k_s}}{k_s} \exp(i\delta_l) \sin\delta_l
\]

with arbitrary real \( \delta_l \). Solving Eq. (35) relative to \( \delta_l \) we find that the on-shell amplitude determines the phase shift according to:

\[
\delta_L(k_s) = \frac{1}{2i} \log \left( 1 + \frac{2ik_s}{\varepsilon_{k_s}} \right)
\]

V. EUCLIDEAN SCATTERING AMPLITUDE

Equation (28), is free from the poles of the constituent propagators and after the appropriate treatment of the logarithmic singularities provides the desired solution for the off-shell amplitude in Minkowski space. This equation is however rather cumbersome, even in the simplest case of two scalar particles in S-wave we are considering, and looks rather different from the initial BS equation (3). It would thus be of the highest interest to have at our disposal an independent test of the numerical solutions.

The test we have performed is based on an Euclidean version of the initial BS equation for the scattering amplitude in Minkowski space (37) by

\[
F^E(k_4, k) = F^M(k_0 = ik_4, k)
\]

By applying the Wick rotation \( k_0 = ik_4 \) to (3) we will derive in what follows the equation satisfied by \( F^E \). We will introduce all along this section the index M or E to distinguish between both amplitudes quantities.

Some preliminary remarks are in order:

1. Contrary to the Minkowski case, the off-shell Euclidean amplitude cannot be used to compute physical observables like e.m. form factors even in the bound state case. The reason is the impossibility to make the Wick rotation in the form factor integral [6, 8].

2. The on-mass-shell condition for \( k_0 = 0 \) corresponds to \( k_4 = 0 \). Therefore both amplitudes, although obeying different equations, should coincide on the mass shell: \( F^M(k_0 = 0, k_s) = F^E(k_4 = 0, k_s) \) and should thus provide the same phase shifts. This property will be used to check our Minkowski results.

3. In the case of the scattering states, the Wick rotation cannot be performed in a naive way to the equation (37) by simply replacing \( k_0 \rightarrow k_4 = -ik_0 \). This important point will be developed below.

A. Rotating the integration contour

Let us consider the pole positions appearing in the equation (7) and given by (9). The integration domain \( k' < k_s \) corresponds to \( \varepsilon_{k'} < \varepsilon_{k_s} \) and hence to \( \text{Re}[k'(2)] > 0 \) and \( \text{Re}[k'(3)] < 0 \). The positions of these singularities are illustrated in Fig. 5. The contour cannot be anti-clock-wise rotated without taking into account the residues at these poles \( k'^{(2)} \cdot k'^{(3)} \). Notice that for the bound state problem, the value \( \varepsilon_{k_s} \) is replaced by \( \frac{M^2}{2} \). Since for any \( k' \) we have \( \varepsilon_{k'} > \frac{M^2}{2} \), when performing the Wick rotation in the bound state equation there is no any crossed singularity and so no any additional contribution.
A Rotating the integration contour

FIG. 5: Singularities of the propagators for scattering state and the integration contour after rotation in the complex plane $k_0$, if $k' < k_s$.

Therefore, for the bound state case, the positions of singularities allows to safely rotate the contour as it is shown in Fig. 4. In this way, one gets equation for the Euclidean BS amplitude $F^E$.

On the contrary, for the scattering state case, the rotated contour in the complex plane of $k'_0$ (see Fig. 5) crosses two of the four pole singularities $k^{(2)}_0, k^{(3)}_0$ displayed in the integrand of Eq. (38). They are on the real axes $k'_0$ at the points $k'_0 = \pm(\varepsilon_{k_s} - \varepsilon_{k'})$. The residues in these poles (to be added to the integral terms) are still expressed in terms of the Minkowski off-shell amplitude:

$$F_M^L(k') \equiv F_M^L(k'_0 = \varepsilon_{k_s} - \varepsilon_{k'}, k').$$

(38)

Thus, when transforming Eq. (37) into Euclidean, we obtain not an Euclidean equation, but a non-singular equation which indeed contains in l.h.-side the Euclidean BS amplitude $F^E$, however, in r.h.-side, under the integrals, both Euclidean amplitude $F^E$ and the particular Minkowski amplitude $F_M^L(k)$ defined in (38). One can similarly derive another non-singular equation which contains in l.h.-side the particular Minkowski amplitude $F_M^L(k')$, and in r.h.-side, under the integrals, again both Euclidean amplitude $F^E$ and the particular Minkowski amplitude $F_M^L(k)$. In this way, we derive the system of two equations which couples the Euclidean amplitude $F^E_{M}(k_4, k)$ to the particular Minkowski off-shell amplitude $F_M^L(k)$. A similar derivation is described in [27].

An additional test is to check that the off-shell Minkowski amplitude $F_M^L(k_0, k)$ obtained by solving equation (7) coincides, for the particular value $k_0 = \pm(\varepsilon_{k_s} - \varepsilon_{k})$, with the independent solution $F_M^L(k)$ of the system of equations. Furthermore, we can check that all three on-mass amplitudes (for the S-waves, in particular) coincide with each other:

$$F_M^L(k_0 = 0, k_0 = k_s) = F_M^E(k_4 = 0, k = k_s) = F_M^L(k_0)$$

and therefore give the same phase shifts.

Below in this section we sketch the derivation of this system of two equations which couples the amplitudes $F^E(k_4, k, z)$ and $F^M(k, z)$. In this derivation we will consider the case when the amplitudes are not decomposed in the partial waves. The two equations for the S-wave amplitudes $F^E_M(k_4, k)$ and $F^M_M(k)$ solved numerically will be given in appendix [C].

We should also analyze the position of singularities in the kernel (41). They are at the points:

$$k'_0 = k_0 \pm \sqrt((\bar{k}' - k')^2 + \mu^2 \mp i \epsilon)$$

When we rotate the contour around $k'_0 = 0$ we must distinguish two cases. If $|k_0| < \sqrt((\bar{k}' - k')^2 + \mu^2)$, the singularity

$$k'_0 = k_0 + \sqrt((\bar{k}' - k')^2 + \mu^2 - i \epsilon)$$

(39)

is in the 4th quadrant and

$$k'_0 = k_0 + \sqrt((\bar{k}' - k')^2 + \mu^2 + i \epsilon)$$

(40)

in the 2nd one. In this case the contour can be rotated anti-clockwise without crossing the singularities. If $|k_0| > \sqrt((\bar{k}' - k')^2 + \mu^2)$, both singularities are in the same half-plane (e.g., at the right half-plane, if $k_0 > 0$) and the contour cannot be rotated.

However, Wick rotation must be performed in both $k_0'$ and $k_0$ variables simultaneously. That is, rotating the integration contour in $k_0'$ by an angle $\phi$, we change also the variable $k_0 \to k_0 \exp(i \phi)$. Then the positions of singularities (39) and (40) are also rotated. As it can be easily checked, $k_0'$ is rotated faster than the contour and $k_0''$ is rotated slower; therefore they move away from the contour and the contour rotation can be safely done. Its final position, after rotation by $\phi = \pi/2$, is $-i \infty < k_0' < i \infty$, whereas the final value of $k_0$ turns into $ik_0$. The singularities of the propagator (41) do not prevent from the Wick rotation in both variables.
A Rotating the integration contour

For the amplitude $F(k', k_0 = \varepsilon_{k_s} - \varepsilon_k; \vec{k}_s)$ the condition $|k_0| < \sqrt{(k - \vec{k})^2 + \mu^2}$ turns into

$$\varepsilon_{k_s} - \varepsilon_{k'} < \sqrt{(k - \vec{k})^2 + \mu^2}$$

Since we integrate over $\vec{k}'$, the maximal value of l.h.-side is $\varepsilon_{k_s} - m$ and the minimal value of r.h.-side is $\mu$. Hence, this inequality is violated if $\varepsilon_{k_s} - m > \mu$, that is when $\varepsilon_{k_s} > m + \mu \rightarrow \sqrt{s} > 2m + 2\mu$, i.e. above the two-meson creation threshold. The singularities of the one-boson exchange kernel allow the contour rotation only in this kinematical domain. Above that, additional contributions should be taken into account. The same conclusion was found in [27]. In our solution of the Euclidean equation, we will not exceed the two-meson creation threshold.

B. Euclidean equation

We start with performing the Wick rotation shown in Fig. 5 to the equation (3). In the c.m.-frame $\vec{p} = 0$, it is transformed into:

$$F^E(k_4, \vec{k}; \vec{k}_s) = V^B(k_4, \vec{k}; \vec{k}_s) + \int \frac{d^4k'}{(2\pi)^4} \frac{V(k_4, \vec{k}'; k_4', \vec{k}') F^E(k_4', \vec{k}'; \vec{k}_s)}{(k_4'^2 + a_+^2)(k_4^2 + a_+^2)} + S$$

where

$$V(k_4, \vec{k}; k_4', \vec{k}') = \frac{16\pi m^2 \alpha}{(k_4 - k_4')^2 + (\vec{k} - \vec{k}')^2 + \mu^2}, \quad (42)$$

$$V^B(k_4, \vec{k}; \vec{k}_s) = V(k_4, \vec{k}; k_4' = 0, \vec{k}' = \vec{k}_s)$$

and $S$ denotes the contribution due to the two singularities shown in Fig. 5. This contribution, existing only if $\varepsilon_{k_s} - \varepsilon_{k'} > 0$, is given by the sum of two residues $S = S_1 + S_2$; $S_1$ is the contribution from $k_0' = (\varepsilon_{k_s} - \varepsilon_{k'}) + i\epsilon$ multiplied by $(2\pi i)$ and $S_2$ the one from $k_0' = -(\varepsilon_{k_s} - \varepsilon_{k'}) - i\epsilon$ multiplied by $(-2\pi i)$.

Contribution $S_1$ has the form:

$$S_1(k_0) = \frac{\pi g^2}{4(2\pi)^4} \frac{\hat{F}^M(k', z')}{\varepsilon_{k_s} \varepsilon_{k'} [-a_- + i\epsilon][-a_- + \sqrt{(\vec{k}' - \vec{k})^2 + \mu^2 - k_0]}}$$

whereas $S_2$ is given by $S_2(k_0) = S_1(-k_0)$. The sum $S_1 + S_2$ is symmetric relative to $k_0 \rightarrow -k_0$, as should be. At this point it is interesting to keep these expressions for $S_{1,2}$ with $k_0$ not replaced by $ik_4$. The reason will become clear later, when deriving another equation, we will substitute $k_0 = \varepsilon_{k_s} - \varepsilon_k$. Above the $2m + \mu$ inelastic threshold these factors give an imaginary contribution making the elastic phase shift complex. The above form of $S_{1,2}$ is convenient to find this imaginary part.

Setting $k_0 = ik_4$ the preceding expression reads:
Equation (41) is not singular. The factor \( 1/[k'_4^2 + a_2^2(k')] \) in the integrand of (41) is singular when \( k'_4 = 0 \) and \( k' = k_s \) simultaneously, but this singularity is in fact canceled by a similar term in the singular part of \( S \) given by (42). It is however convenient to cancel these two singularities explicitly and analytically and obtain a regular resulting expression. The transformations are elementary but lengthy and will not be carried out in detail. Below are indicated the main steps.

We make subtraction in the integrand and add the subtracted term:

\[
S(i k_4) = \frac{g^2 \pi}{(2\pi)^4} \int_{k' < k_s} d^4 k' \frac{\hat{F}^M(k', z')}{2\epsilon_k \epsilon_{k'} (a_+ - i\epsilon)} \left[ k_4^2 - \left( a_- - \sqrt{(k'^2 - \tilde{k})^2 + \mu^2} \right) \left( a_- + \sqrt{(k'^2 - \tilde{k})^2 + \mu^2} \right) \right] \]

(45)

There is no any singularity in the difference. The subtracted term is not unique. Our choice was motivated in order to obtain an analytic result for the integral over \( dk'_4 \) in the last line of Eq. (46).

The term which we add is singular \( k' = k_s \). We perform an additional subtraction to eliminate this singularity and again add the subtracted term. This additional term is, of course, again singular but analytic. Its contribution, after integration in the limits \( 0 < k' < k_s - \delta, \ k_s + \delta < k' < \infty \) and at \( \delta \to 0 \), is \( \sim \log(\delta/m) \). It is exactly cancelled analytically by a similar term in the singular part of \( S \). The resulting S-wave equation is regular and given in appendix C, Eq. (47).

The equation (46) and, equivalently (after cancellation of singularities), Eq. (47) relate the Euclidean amplitude \( F^E(k_4, k, z) \) and the Minkowski one \( \tilde{F}^M(k, z) \) appearing in \( S \). To determine both amplitudes, we should obtain an additional equation.

This new equation is still obtained by performing a Wick rotation \( k'_0 = i k_4 \) to (43). However, instead of taking \( k_0 = i k_4 \) we set \( k_0 = \epsilon_{k_4} - \epsilon_k \) for \( k < k_s \). As discussed at the end of the subsection (43) for this particular value of \( k_0 \) the kernel singularities do not prevent from the Wick rotation below the two meson creation threshold. In this way we get the following equation (symbolically):

\[
\tilde{F}^M_0(k, z) = \text{r.h.-side Eq. (46) at } [k_4 = i(\epsilon_{k_4} - \epsilon_k)], \]

(47)

that is the right-hand side term of the equation (46) taken at the value \( k_4 = i(\epsilon_{k_4} - \epsilon_k) \). The corresponding explicit S-wave equation is given in appendix C, Eq. (48).

VI. RESULTS

We present in this section the results of solving the BS equation in Minkowski space (28) and the coupled Euclidean–Minkowski system of equations (41) and (42). Some details of the numerical methods used are given in the Appendix A.

We have first computed the bound state solutions, denoted \( \Gamma_0(k_0, k) \), by dropping the inhomogeneous term \( F^B_0(k_0, k) \) in (28) and setting \( M = 2m - B \). The binding energies \( B \) thus obtained coincides, within four-digit accuracy, with the ones calculated in our previous work (48).
An interesting issue is the appearance of an imaginary part in \( \Gamma_0(k_0, k) \) when normalized for instance by \( \Gamma(0, 0) = 1 \). In spite of this real normalization condition, \( \Gamma_0(k_0, k) \) will become imaginary depending on the kinematical domain of its arguments corresponding to the virtual meson creation. Written in terms of variables \( k_i \), defined in (1), they read:

\[
\begin{align*}
k_1^2 &> (m + \mu)^2 \quad \text{or} \quad k_2^2 > (m + \mu)^2
\end{align*}
\]

which in terms of variables \((k_0, k)\) in the center of mass frame, become:

\[
\begin{align*}
\left( \frac{M}{2} + k_0 \right)^2 - k^2 > (m + \mu)^2 \\
\left( \frac{M}{2} - k_0 \right)^2 - k^2 > (m + \mu)^2
\end{align*}
\]

\( \Gamma \) obtains an imaginary part if one of these two preceding conditions is fulfilled. In the \((k_0, k)\) plane and for positive values of \( k_0 \) this gives the locus

\[
k_0(k) = -\frac{M}{2} + \sqrt{k^2 + (m + \mu)^2}
\]

Above this curve (represented in Fig. 3) the imaginary part of \( \Gamma \) is not 0.

We display in Fig. 4 the \( k_0 \)-dependence of the imaginary part of amplitude \( \Gamma(k_0, k) \) obtained in our calculations for different values of \( k \). It corresponds to the parameters \( \alpha = 1.44, \mu = 0.50, B = 0.01 \). We can thus check that the a vanishing imaginary part of \( \Gamma \) appears at the \( k_0 \) values given by equation (49). Note also the difficulty in reproducing a sharp non-analytic threshold behavior in terms of smooth functions even if they are as flexible as splines. The small oscillations in the vicinity of the threshold are artefacts of our spline basis. They can be reduced by increasing the number of basis elements.

The scattering amplitude \( F_0(k_0, k) \) in Minkowski space has been calculated for \( L = 0 \) states and the corresponding phase shifts have been extracted according to (36). The BS relativistic formalism accounts naturally for the meson creation in the scattering process, when the available kinetic energy allows it. The inelasticity threshold corresponding to \( n \)-particle creation is given by

\[
k_s^{(n)} = m \sqrt{\left( \frac{\mu}{m} \right) n + \frac{1}{4} \left( \frac{\mu}{m} \right)^2 n^2}
\]

Below the first inelastic threshold, \( k_s^{(1)} \), the phase shifts are real. This unitarity condition is not automatically fulfilled in our approach, but appears as a consequence of handling the correct solution and provides a stringent test of the numerical method. Above \( k_s^{(1)} \), the phase shift obtains an imaginary part which behaves like

\[
\text{Im}[\delta_0] \sim (k_s - k_s^{(1)})^2
\]
in the threshold vicinity. Higher inelasticity thresholds, corresponding to creation of 2, 3, etc. intermediate mesons at $k_s^{(n)}$, are also taken into account in our calculations.

Some selected results corresponding to $\alpha = 1.2$ and $\mu = 0.5$ are listed in Table I. We have also solved the system of equations, derived in Sec. V and Appendix C (eqs. [C1] and [C8]), coupling the Euclidean amplitude to the Minkowski one at the particular value $k_0 = \varepsilon_{k_s} - \varepsilon_k$. The phase shifts found by these two independent methods are consistent to each other within the accuracy given in this table. They are also rather close to ones found in [27].

TABLE I: Real and imaginary parts of the phase shift (degrees) calculated by solving the equation (28) vs. incident momentum $k_s$ for $\alpha = 1.2$ and $\mu = 0.5$. Corresponding first inelastic threshold is $k_s^{(1)} = 0.75$.

| $k_s$ | 0.05 | 0.1 | 0.2 | 0.3 | 0.4 | 0.5 | 0.6 | 0.7 | 0.8 | 0.9 | 1.0 | 1.3 | 1.5 | 2.0 | 2.5 | 3.0 |
|-------|------|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|-----|
| $Re[\delta_0]$ | 124 | 99.9 | 77.8 | 65.1 | 56.2 | 49.3 | 43.9 | 39.4 | 35.7 | 32.5 | 29.7 | 19.3 | 13.3 | 7.78 | 7.78 |
| $Im[\delta_0]$ | 0.033 | 0.221 | 0.453 | 0.848 | 0.852 | 0.578 | 0.333 | 0.203 |

The low energy parameters were computed directly at $k_s = 0$ and found to be consistent with a quadratic fit to the effective range function $k \cot \delta_0(k) = -\frac{1}{a_0} + \frac{1}{2} r_0 k^2$. The BS scattering length $a_0$ as a function of the coupling constant $\alpha$ is given in Fig. 9 for $\mu = 0.50$. It is compared to the non-relativistic (NR) values. The singularities correspond to the appearance of the first bound state at $\alpha_0 = 1.02$ for BS and $\alpha_0 = 0.840$ for NR. One can see that the differences between relativistic and non-relativistic treatments of the same problem are not of kinematical origin since even for processes involving zero energy they can be substantially large, especially in presence of bound state. It is worth noticing that only in the limit $\alpha \to 0$ the two curves are tangent to each other and in this region the results are given by the Born approximation

$$a_0^B = -\frac{1}{\mu} \frac{m}{\mu} \alpha$$

which is the same for the NR and the BS equation. Beyond this region both dynamics are not compatible. This non matching between NR and relativistic equations was already pointed out in [32, 33] when computing the binding energies $B$ of a two scalar and two fermion system in the limit $B \to 0$ with different relativistic approaches. A recent work [16] devoted to this problem proposes the construction of equivalent
non relativistic potential using the technique of geometrical spectral inversion. It would be interesting to check the robustness of this equivalence by extend it to the scattering states and to form factors.

Some numerical values of the scattering length for different values of the exchanged mass $\mu$ were given in Ref. [10], Table I. It can be checked by direct inspection, that the scaling properties of the non relativistic equation [34], in particular the relation between the scattering length corresponding to different values of $\mu$ and coupling constants

$$a_0 \left( \frac{\mu}{m}, \alpha \right) = \frac{1}{\mu} a_0 \left( 1, \frac{\alpha}{\mu} \right)$$

are no longer valid except in the Born approximation region.

We display in Fig. 10 the factorized part of the off-shell scattering amplitude $f_0$, defined in [32], as a function $k_0$ for different values of $k$. It corresponds to the parameters $\alpha = 1.2$, $\mu = 0.5$ and $k_s = 1.0$. The upper panel displays its real part and lower panel the imaginary one. Its $k$-dependence is shown in Fig. 11 for different values of $k$. The regular amplitudes $f_0$ are those effectively computed in our approach. As one can see, these functions are no longer singular, although they present several sharp structures and cusps both on its real and imaginary parts. The corresponding three-dimensional plots $F_0(k_0, k)$ for the values $\alpha = 0.5$, $\mu = 0.5$ and $k_s = 0.5$ are given in Fig. 4 of [10].

The off-shell scattering amplitudes $F_0$ computed using our direct method in Minkowski space have been tested using also the results of the coupled Euclidean-Minkowski equation derived in Sec. V. As it was explained in Sec. V these equations couple the Euclidean amplitude to the Minkowski one for the particular off-shell value $k_0 = \varepsilon_{k_s} - \varepsilon_k$, denoted $F_0(k)$. The comparison of the off-shell amplitude $F_0(k)$ found by this method with the solution of Eq. (28) $F_0(k) = F^M(k_0 = \varepsilon_{k_s} - \varepsilon_k, k)$ for the same argument $k_0$ pro-
FIG. 10: Real (upper panel) and imaginary (lower panel) parts of the factorized off-shell scattering amplitude $f_0$ defined in Eq. (32) for $\alpha = 1.2$ and $\mu = 0.50$ vs. $k_0$ for different fixed values of $k$.

Figures 10 and 11 provide an independent test of our direct method based on Eq. (28).

Two illustrative examples are shown in Fig. 12 for different values of the parameters $\alpha, \mu$ and $k_s$. Solid line denotes the real parts of the amplitudes $F_0(k)$ (in black) and $\tilde{F}_0(k)$ (red color), whereas the dashed line denotes their imaginary part.

Upper panel corresponds to $\alpha = 0.5$, $\mu = 0.50$ and $k_s = 0.5$. The results of $F_0(k)$ and $\tilde{F}_0(k)$ are not distinguishable by eyes, their relative difference being at the level of $10^{-3} - 10^{-4}$.

Lower panel corresponds to the parameters $\alpha = 1.2$, $\mu = 0.50$ and $k_s = 1.0$. In these case, a cusp-like structure develops around $k \approx 0.65$. The Euclidean-Minkowski formulation shed some light on the origin of this cusp, which comes actually from the last term $\tilde{g}_i$ in equation (C8). According to its definition in Eq. (C9), this term does not contribute below the first meson creation threshold, that is if $\sqrt{s} = 2\varepsilon k_s < 2m + \mu$, since in this case the argument of the $\theta$-function is always negative.

Above the threshold, the amplitude $\tilde{g}(k)$ is also zero for $k > k_c$ where $k_c$ is a critical value given by

$$k_c = \frac{1}{2\sqrt{s}} \sqrt{(s - \mu^2)(s - (2m + \mu)^2)} \quad (54)$$

When $k < k_c$, the argument of the $\theta$-function vs. the integration variable $k'$ can be positive that allows a non-zero value of $\tilde{g}_i$. If $k \rightarrow k_c$ from below, the integration domain over $k'$ due the $\theta$-function shrinks...
FIG. 12: Comparison between the Minkowski amplitude \( F_0 \) (in black) and \( \tilde{F}_0 \) (in red) obtained by solving the Euclidean-Minkowski coupled equations for the particular off shell value \( k_0 = \varepsilon - \varepsilon k \) (see Sec. V). Solid line denotes the real parts of the amplitudes and dashed line denotes their imaginary part. Upper panel corresponds to \( \alpha = 0.5 \), \( \mu = 0.5 \), and \( k_s = 0.5 \). Lower panel corresponds to \( \alpha = 1.2 \), \( \mu = 0.5 \), and \( k_s = 1.0 \).

\[
k_0' - c\sqrt{k_c - k} \leq k' \leq k_0' + c\sqrt{k_c - k}
\]

where \( k_c' \) and \( c \) are independent of \( k \) and \( k' \). One then has, in this limit,

\[
\tilde{g}_s(k) \propto \sqrt{k_c - k}
\]

This is the reason of the cusp behavior, with an infinite derivative at \( k = k_c \), which manifests itself in the lower panel of Fig. 12. For \( m = 1, \mu = 0.5 \), and \( k_s = 1 \) the critical value, given by Eq. (54), is \( k_c = 0.651 \), in agreement with the position of the cusp seen in our results. We have also checked from our numerical solutions, that the cusp position moves as function of \( k_s \) according to Eq. (54). It is interesting to point out that from the analysis of our purely Minkowski BS equation the origin of this cusp is not evident at all. It is however remarkably manifested in the corresponding numerical solution seen in Fig. 12. We would like to emphasize that this cusp-like structure described analytically above, is only one example of the many structures seen in the results displayed in Figs. 10 and 11, though their analysis was beyond the scope of the present work.

The small differences near the cusp between the real parts of \( F_0(k) \) and \( \tilde{F}_0(k) \) are purely numerical and indicate the difficulty in reproducing sharp behaviors in terms of smooth functions. They can be reduced by increasing the number of grid points.

The results presented in Fig. 12 confirm the validity and accuracy of our direct Minkowski space calculations.

VII. CONCLUSION

We present a new method to solve the Bethe-Salpeter equation in Minkowski space. Contrary to the preceding approaches devoted to this problem, this method does not make use of the Nakanishi integral representation of the amplitude but it is based on a direct solution of the equation taking properly into account the many singularities. A regular equation is finally obtained and solved numerically by standard methods.

It has been successfully applied to bound and scattering states. The Bethe-Salpeter off-shell scattering amplitude in Minkowski space has been computed for the first time.

Applying the Wick rotation to the original Bethe-Salpeter equation, an independent system of equations coupling the Euclidean amplitude to the Minkowski one for a particular off-shell value has been derived. It provides an independent test for our approach.

Coming on mass shell, the elastic phase shifts and low energy parameters where accurately computed. They considerably differ, even at zero energy, from the non-relativistic ones. Above the meson creation threshold, an imaginary part of the phase shift appears and has also been calculated.

The results presented here were limited to S-wave in the spinless case and the ladder kernel but they can be extended to any partial wave.
The off-shell Bethe-Salpeter scattering amplitude thus obtained has been further used to calculate the transition form factor \[14\]. In its full off-shell form, it can be used as input in the three-body Bethe-Salpeter Faddeev equations.

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Appendix A: Numerical methods

We consider a generic two-dimensional integral equation

\[
 f(x, y) = f^B(x, y) + \int_0^\infty dy' V(x, y, a_{y'}, y') f(a_{y'}, y') + \int_0^\infty dy' V(x, y, b_{y'}, y') f(b_{y'}, y') \\
 + \int_0^\infty dy' \int_0^\infty dx' \frac{V(x, y, x', y') f(x', y') - V(x, y, a_{y'}, y') f(a_{y'}, y')}{x'^2 - a_{y'}^2} \\
 + \int_0^\infty dy' \int_0^\infty dx' \frac{V(x, y, x', y') f(x', y') - V(x, y, b_{y'}, y') f(b_{y'}, y')}{x'^2 - b_{y'}^2} \tag{A1}
\]

The solution \(f\) is searched in the compact domain \([0, x_m] \times [0, y_m]\) in the form

\[
 f(x, y) = \sum_{ij} c_{ij} S_i(x) S_j(y) \tag{A2}
\]

where \(c_{ij}\) are unknown coefficients to be determined and \(S_i\) is a basis of spline functions (see for instance \[6\]). They are defined respectively in \([0, x_m]\) and \([0, y_m]\) and are cubic piecewise in each of the \(N_x\) (\(N_y\)) intervals in which \([0, x_m]\) (\([0, y_m]\)) is divided.

The expansion \(A2\) is supposed to be valid on a set of selected point \(\{x_i\} \times \{y_j\}\) with \(i = 0, 2N_x + 1\) and \(j = 0, 2N_y + 1\) suitably chosen in order to maximize the accuracy of the solution.

By inserting \(A2\) in \(A1\) one is led with a linear system of equations

\[
 \sum_{i' j'} U_{ij, i' j'} c_{i' j'} = f^B_{ij} + \sum_{i' j'} A_{ij, i' j'} c_{i' j'} \tag{A3}
\]

with an inhomogeneous term given by

\[
 f^B_{ij} = f^B(\bar{x}_i, \bar{y}_j) \tag{A4}
\]

and the matrices \(U\) and \(A\) are

\[
 U_{ij, i' j'} = S_{i'}(\bar{x}_i) S_{j'}(\bar{y}_j) \tag{A5}
\]

and

\[
 A_{ij, i' j'} = \int_{0}^{y_{\text{max}}} dy' V(\bar{x}_i, \bar{y}_j, a, y') S_{i'}(a_{y'}) S_{j'}(y') \\
 + \int_{0}^{y_{\text{max}}} dy' V(\bar{x}_i, \bar{y}_j, b, y') S_{i'}(b_{y'}) S_{j'}(y') \\
 + \int_{0}^{x_{\text{max}}} dx' \frac{V(\bar{x}_i, \bar{y}_j, x', y') S_{i'}(x') - V(\bar{x}_i, \bar{y}_j, a_{y'}, y') S_{i'}(a_{y'})}{x'^2 - a_{y'}^2} \\
 + \int_{0}^{y_{\text{max}}} dy' S_{j'}(y') \int_{0}^{x_{\text{max}}} dx' \frac{V(\bar{x}_i, \bar{y}_j, x', y') S_{i'}(x')}{x'^2 - b_{y'}^2}
\]
An interesting property of the splines used is the fact that the functions \( S_{2i}(x) \) and \( S_{2i+1}(x) \) have a support limited to the two consecutive intervals \([x_i-1, x_i] \cup [x_i, x_{i+1}]\) and vanish elsewhere. This reduces considerably the computation of the matrix elements.

After removing the many singularities following the techniques explained in Sec. II all integrands appearing in (A6) are regular functions and the integrations can be performed using the standard Gauss quadrature methods. The number collocation points on each dimension equals the number of spline basis and the validation procedure allows to determine the coefficients \( c_{ij} \) of the expansion (A2). One is finally led to solve a complex linear system denoted symbolically

\[
(U - A)c = f^b
\]

with dimension \( d = (2N_x + 1)(2N_y + 1) \)

When dealing with a finite integration domain in both variables \( k', k_0' \) some care must be taken to use the subtraction technique (22). Indeed this relation – used for \( k' \) as well as for \( k_0' \) integrations – it is based on the identity (23) which is valid only in an infinite domain and that must be properly adapted. Thus, for a generic variable \( z = x, y \) integrated over a finite domain \( z \in [0, L] \), the relation

\[
\int_0^\infty \frac{dz}{z^2 - a^2} = 0
\]

must be replaced by

\[
\int_0^L \frac{dz}{z^2 - a^2} + \frac{1}{2a} \log \left| \frac{L + a}{L - a} \right| = 0 \quad (A7)
\]

The integral term in (A7) is used to eliminates the singularities on the finite interval \([0, L]\) whereas the logarithmic term represents a finite volume correction.

**Appendix B: Deriving equation (25)**

Let us consider the integral:

\[
I(y) = PV \int_{-\infty}^{\infty} \frac{dx}{x^2 - y^2} = \frac{\pi^2}{2} \delta(y) \quad (B1)
\]

appearing in (25). Since it is zero if \( y \neq 0 \) (see Eq. 23) and diverges if \( y = 0 \), we expect it to be proportional to the delta-function \( \delta(y) \). We replace it by the regularized integral

\[
I_\epsilon(y) = \int_{-\infty}^{\infty} \frac{(x^2 - y^2)dx}{(x^2 - y^2)^2 + \epsilon^2} \quad (B2)
\]

which tends to \( I(y) \) when \( \epsilon \to 0 \). Calculating this integral, we find:

\[
I_\epsilon(y) = \frac{\pi \sqrt{\sqrt{y^4 + \epsilon^4} - y^2}}{\sqrt{2} \sqrt{y^4 + \epsilon^4}}
\]

When \( \epsilon \to 0 \), this is a very sharp function in the vicinity of \( y = 0 \) with the value \( I_\epsilon(0) = \pi/(\sqrt{2}\epsilon) \to \infty \). It represents a delta-function. The integral

\[
\int_{-\infty}^{\infty} I_\epsilon(y)dy = \frac{\pi^2}{2}
\]

gives the normalization coefficient. We conclude that

\[
I(y) = PV \int_{-\infty}^{\infty} \frac{dx}{x^2 - y^2} = \frac{\pi^2}{2} \delta(y) \quad (B3)
\]

**Appendix C: Coupled Euclidean-Minkowski system of equations for the S-wave amplitudes**

In Sec. IV making a Wick rotation in the BS equation, we derived the system of equations coupling the Euclidean amplitude \( F^E(k_4, k, z) \) and the Minkowski one for the particular off-shell \( k_0 \) value \( F^M(k, z) = F^M(k_0 = \varepsilon_k, -\varepsilon_k, k, z) \) with \( k \in [0, k_0] \). To underline the main steps, this was done without partial waves decomposition. Here we give the equations for the S-wave, which we solved numerically. We remind that the partial waves \( F^E_L \) and \( F^M_L \) are defined by eq. (6).

The first equation reads:
\[
F_0^{E}(k_4, k) = \frac{1}{16\pi} V_0^B(k_4, k) + \frac{1}{4\pi^3} \int_0^\infty k'^2 dk' \int_0^\infty \frac{dk'}{k'^2 + a_-^2} \left\{ F_0^E(k', k') \left( \frac{F_0^E(k'_4 = 0, k'_4)}{(k'_4^2 + a_+^2)} - \frac{F_0^E(k'_4 = 0, k'_4)}{a_+^2} \right) \right\} \\
+ \frac{1}{4\pi^3} \int_0^\infty k'^2 dk' \pi \left\{ F_0^E(k'_4 = 0, k'_4) \left( \frac{F_0^E(k'_4 = 0, k'_4)}{|a_-| a_+^2} V_0^B(k_4, k) - \frac{k_s \varepsilon_{k'_s} V_0^B(k'_4 = 0, k'_s)}{2 \varepsilon_{k'_s} |a_-| a_+} V_0^B(k_4, k) \right) \right\} \\
+ h + g
\]

where the kernels

\[
V_0^B(k_4, k) = \frac{4\pi m^2 \alpha}{kk'} \log \left( \frac{k_s^2 + \mu^2 + (k + k_s)^2}{k_s^2 + \mu^2 + (k - k_s)^2} \right)
\]

\[
V_s(k_4, k; k'_4, k'_4) = \frac{4\pi m^2 \alpha}{kk'} \log \left( \frac{k_s^2 + k'_s^2 + \mu^2 + (k + k'_s)^2}{k_s^2 + k'_s^2 + \mu^2 + (k - k'_s)^2} - 4k_s^2 k'_s^2 \right)
\]

\[
V_1(k_4, k, k') = \frac{4\pi m^2 \alpha}{kk'} \log \left( \frac{|a_-| + \sqrt{(k + k')^2 + \mu^2}}{|a_-| + \sqrt{(k - k')^2 + \mu^2}} \right)^2 + k_s^2
\]

The amplitude \( \tilde{F}_0^M(k) \) enters in the terms \( h \) and \( h \).

The term \( h \) is given by:

\[
h(k_4, k) = \frac{1}{16\pi^2} F_0^E(k'_4 = 0, k = k_s) V_0^B(k_4, k) \frac{k_s \varepsilon_{k_s}}{\varepsilon_{k_s}} \left( \frac{\varepsilon_{k_s}^2}{m^2} + 4 \log \frac{\varepsilon_{k_s}}{m} - 2 - \log 4 \right) \\
+ \frac{1}{8\pi^2} \tilde{F}_0^M(k = k_s) V_0^B(k_4, k) \frac{1}{\varepsilon_{k_s}} \left( 2m \arctan \frac{k_s}{m} - k_s \log \frac{2k_s}{m} \right)
\]

It does not contain the integrals and it contains the on-shell Minkowski and Euclidean amplitudes which coincide with each other.

The term \( g \) is given by:

\[
g(k_4, k) = \frac{1}{8\pi^2} \int_0^{k_s} k'^2 dk' \left\{ \tilde{F}_0^M(k') \left( \frac{\varepsilon_{k_s}}{\varepsilon_{k'_s}} V_2(k_4, k, k') - \frac{k_s 2 \varepsilon_{k_s} \tilde{F}_0^M(k = k_s)}{\varepsilon_{k'_s} a_+ a_-} V_0^B(k_4, k) \right) \right\} \\
+ \frac{i}{16\pi \varepsilon_{k_s}} \tilde{F}_0^M(k = k_s) V_0^B(k_4, k)
\]

It contains on the kernel \( V_2(k_4, k, k') \):

\[
V_2(k_4, k, k') = \frac{2\pi m^2 \alpha}{kk'} \log \left| \frac{k_s^2 + a_+^2 + \mu^2 + (k + k')^2}{k_s^2 + a_+^2 + \mu^2 + (k - k')^2} - 4a_+^2 |\mu^2 + (k + k')^2| \right|
\]

Notice that:

\[ V_1(k_4, k, k' = k_s) = V_2(k_4, k, k' = k_s) = V_0^B(k_4, k) \]
This completes the full definition of the equation [C1]. Due to subtraction which we have under any integral, these integrals are non-singular. The second equation has the following form:

$$\tilde{F}_0^M(k) = \frac{1}{16\pi} V_0 B \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k \right)$$

$$+ \frac{1}{4\pi^3} \int_0^\infty k'^2 dk' \int_0^\infty dk' \frac{V_s \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k; k', k' \right)}{(k_4^2 + \mu^2)} \left\{ \frac{F_0^E(k'_4, k')}{(k'_4 + \mu^2)} - \frac{F_0^E(k'_4 = 0, k')}{\mu^2} \right\}$$

$$+ \frac{\pi}{4\pi^3} \int_0^\infty k'^2 dk' \left\{ \frac{F_0^E(k'_4 = 0, k')}{|a_-|a_+} V_1 \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k, k' \right) \frac{k_s \varepsilon'_k}{2k'^2 |a_-|a_+} V_0^B \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k \right) \right\} \tag{C8}$$

$$+ \tilde{h} + \tilde{g} + \tilde{g}_i$$

In contrast to Eq. [C1], the equation [C8] contains the term

$$\tilde{g}_i(k) = \frac{ig^2}{64\pi} \int_0^{k_s} \frac{k'^2 dk'}{kk'\varepsilon_k \varepsilon_{k'} a_-} \tilde{F}_0^M(k') \theta \left( 1 - \frac{\left(2\varepsilon_{k_s} - \varepsilon_{k'} - \varepsilon_k \right)^2 - k'^2 - k^2 - \mu^2}{2kk'} \right) \tag{C9}$$

Due to restriction given by the theta-function, one can show that this term is identically zero below the one meson creation threshold $2m + \mu$. Namely it provides the value $\text{Im}[\delta]$ above the threshold: if we omit it we find always $\text{Im}[\delta] = 0$. The denominator $a_- = \varepsilon_{k'} - \varepsilon_k$, never crosses zero since the theta-function does not allow that (it restricts the domain where $a_- \neq 0$). Kernels $V_0^B$, $V_s$, $V_1$ and $V_2$ are correspondingly defined by eqs. [C2], [C3], [C4] and [C7] above.

The quantity $\tilde{h}$ reads:

$$\tilde{h}(k) = \frac{1}{16\pi^2} F_0^E(k_4 = 0, k = k_s) V_0^B \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k \right) \frac{k_s}{\varepsilon_{k_s}} \frac{\varepsilon_{k_s}^2}{m^2} + 4 \log \frac{\varepsilon_{k_s}}{m} - 2 - \log 4 \right)$$

$$+ \frac{1}{8\pi^2} \tilde{F}_0^M(k = k_s) V_0^B \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k \right) \frac{1}{2} \frac{2m \arctan \frac{k_s}{m} - k_s \log \frac{2k_s}{m}}{m} \tag{C10}$$

The term $\tilde{g}$ has the form:

$$\tilde{g}(k) = \frac{1}{16\pi^2} \int_0^{k_s} k'^2 dk' \left\{ \frac{F_0^M(k')}{\varepsilon_k \varepsilon_{k'} a_-} V_2 \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k, k' \right) - \frac{k_s}{k} \frac{2\varepsilon_{k_s}}{\varepsilon_k a_- a_+} \tilde{F}_0^M(k = k_s) V_0^B \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k \right) \right\}$$

$$+ \frac{i}{16\pi} \frac{k_s}{\varepsilon_{k_s}} \tilde{F}_0^M(k = k_s) V_0^B \left( k_4 = i(\varepsilon_{k_s} - \varepsilon_k), k \right) \tag{C11}$$
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