Go-With-The-Winner: Client-Side Server Selection
for Content Delivery

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Abstract

Content delivery networks deliver much of the world’s web and video content by deploying a large distributed network of servers. We model and analyze a simple paradigm for client-side server selection that is commonly used in practice where each user independently measures the performance of a set of candidate servers and selects the one that performs the best. For web (resp., video) delivery, we propose and analyze a simple algorithm where each user randomly chooses two or more candidate servers and selects the server that provided the best hitrate (resp., bitrate). We prove that the algorithm converges quickly to an optimal state where all users receive the best hitrate (resp., bitrate), with high probability. We also show that if each user chose just one random server instead of two, some users receive a hitrate (resp., bitrate) that tends to zero. We simulate our algorithm and evaluate its performance with varying choices of parameters, system load, and content popularity.

1 Introduction

Modern content delivery networks (CDNs) host and deliver a large fraction of the world’s web content, video content, and application services on behalf of enterprises that include most major web portals, media outlets, social networks, application providers, and news channels [16]. CDNs deploy large numbers of servers around the world that can store content and deliver that content to users who request it. When a user requests a content item, say a web page or a video, the user is directed to one of the CDN’s servers that can serve the desired content to the user. The goal of a CDN is to maximize the performance as perceived by the user while efficiently managing its server resources.
A key functionality of a CDN is the server selection process by which client software running on the user’s computer or device, such as media player or a browser, is directed to a suitable server of a CDN [7]. The desired outcome of the server selection process is that each user is directed to a server that can provide the requested content with good performance. The metrics for performance that are optimized vary by the type of content being accessed. For instance, good performance for a user accessing a web page might mean that the web page downloads quickly. Good performance for a user watching a video might mean that the content is delivered by the server at a sufficiently high bitrate to avoid the video from freezing and rebuffering [12].

Server selection can be performed in two distinct ways that are not mutually exclusive. Network-side server selection algorithms monitor the real-time characteristics of the CDN and the Internet. Such algorithms are often complex and measure liveness and load of the CDN’s servers, as well as latency, loss, and bandwidth of the communication paths between servers and users. Using this information, the algorithm computes a good “mapping” of users to servers, such that each user is assigned a “proximal” server capable of serving that user’s content [16]. This mapping is computed periodically and is typically made available to client software running on the user’s computer or device using the domain name system (DNS). Specifically, the user’s browser or media player looks up the domain name of the content that it wants to download and receives as translation the ip address of the selected server.

A complementary approach to network-side server selection that is commonly used is client-side server selection where the client software running on the user’s computer or device embodies a server selection algorithm. The client software is typically unaware of the global state of the server infrastructure, the Internet, or other users. Rather, the client software typically makes future server selection decisions based on its own historical performance measurements from past server downloads. Client-side server selection can often be implemented as a plug-in within media players, web browsers, and web download managers [2].

While client-side server selection can be used to select servers within a single CDN, it can also be used in a multi-CDN setting. Large content providers often make the same content available to the user via multiple CDNs. In this case, the client software running on the user’s device tries out the different CDNs and chooses the “best” server from across multiple CDNs. For instance, NetFlix uses three different CDNs and the media player incorporates a client-side server selection algorithm to choose the “best”
server (and the corresponding CDN) using performance metrics such as the video bitrates achievable from the various choices \([1]\). Note also that in the typical multi-CDN case, both network-side and client-side server selection are used together, where the former is used to choose the candidate servers from each CDN and the latter is used by the user to pick the “best” among all the candidates.

1.1 The Go-With-The-Winner paradigm
A common and intuitive paradigm that is often used for client-side server selection in practice is what we call “Go-With-The-Winner” that consist of an initial trial period during which each user independently “tries out” a set of candidate servers by requesting content or services from them (cf. Figure \([1]\)). Subsequently, each user independently decides on the “best” performing server using historical performance information that the user collected for the candidate servers during the trial period. It is commonly implemented in the content delivery context that incorporate choosing a web or video content server from among a cluster of such servers.

Besides content delivery, the Go-With-The-Winner paradigm is also common for other Internet services, though we do not explicitly study such services in our work. For instance, BIND, which is the most widely deployed DNS resolver (i.e., DNS client) on the Internet, tracks performance as a smoothed value of the historical round trip times (called SRTT) from past queries for a set of candidate name servers. Then BIND chooses a particular name server to query in part based on the computed SRTT values \([13]\). It is also notable that BIND implementations incorporate randomness in the candidate selection process.

The three key characteristics of the Go-With-The-Winner paradigm are as follows.

1. **Distributed control.** Each user makes decisions in a distributed fashion using only knowledge available to it. There is no explicit information about the global state of the servers or other users, beyond what the user can infer from it’s own historical experience.

2. **Performance feedback only.** There is no explicit feedback from a server to a user who requested service beyond what can be inferred by the performance experienced by the user.

3. **Choosing the “best” performer.** The selection criteria is based on historical performance measured by the user and consists of selecting the
Figure 1: Client-side Server Selection with the Go-With-The-Winner paradigm. User $U$ makes request to two candidate servers $S_1$ and $S_2$. After a trial period of observing the performance provided by the candidate, the user selects the better performing server.

...best server according to some performance metric (i.e., go with the winner).

Besides its inherent simplicity and naturalness, the paradigm is sometimes the only feasible and robust solution. For instance, in many settings, the client software running on the user’s device that performs server selection has no detailed knowledge of the state of the server infrastructure as it is managed and owned by other business entities. In this case, the primary feedback mechanism for the client is its own historical performance measurements.

While client-side server selection is widely implemented, its theoretical foundations are not well understood. A goal of our work is to provide such a foundation in the context of web and video content delivery. It is not our intention to model a real-life client-side server selection process in its entirety which can involve other adhoc implementation-specific considerations. But rather we abstract a simple analytical model that we can explore to extract basic principles of the paradigm that are applicable in a broad context.

1.2 Our contributions

We propose a simple theoretical model for the study of client-side server selection algorithms that use the Go-With-The-Winner paradigm. Using our model, we answer foundational questions such as how does randomness help
in the trial period when selecting candidate servers? How many candidate servers should be selected in the trial phase? How long does it take for users to narrow down their choice and decide on a single server? Under what conditions does the selection algorithm converge to a state where all users have made the correct server choices, i.e., the selected servers provide good performance to their users? Some of our key results that help answer these questions follow.

(1) In Section 2, in the context of web content delivery, we analyze a simple algorithm called MaxHitRate where each user independently selects two or more random servers as candidates and decides on the server that provided the best cache hit rate. We show that with high probability, the algorithm converges quickly to a state where no cache is overloaded and all users obtain a 100% hit rate. Further, we show that two or more random choices of candidate servers are necessary, as just one random choice will result in some users (and some servers) incurring cache hit rates that tend to zero, as the number of users and servers tend to infinity. This work represents the first demonstration of the “power of two choices” phenomena in the context of client-side server selection for content delivery, akin to similar phenomena observed in balls-into-bins games [14], load balancing, circuit-switching algorithms [5], relay allocation for services like Skype [15], and multi-path communication [11].

(2) In Section 3, in the context of video content delivery, we propose a simple algorithm called MaxBitRate where each user independently selects two or more random servers as candidates and decides on the server that provided the best bitrate for the video stream. We show that with high probability, the algorithm converges quickly to a state where no server is overloaded and all users obtain the required bitrate for their video to play without freezes. Further, we show that two or more random choices of candidate servers are necessary, as just one random choice will result in some users receiving bitrates that tend to zero, as the number of users and servers tend to infinity.

(3) In Section 4, we go beyond our theoretical model and simulate algorithm MaxHitRate in more complex settings. We establish an inverse relationship between the length of the history used for hitrate computation (denoted by \( \tau \)) and the failure rate defined as the probability that the system converges to a non-optimal state. We show that as \( \tau \) increases the convergence time increases, but the failure rate decreases. We also empirically evaluate the impact of the number of choices of candidate servers. We show that two or more random choices are required for all users to receive a 100% hitrate. Though even if only 70% of the users make two choices, it
is sufficient for 95% of the users to receive a 100% hitrate. Finally, we show that the convergence time increases with system load. But, convergence time decreases when the exponent of power law distribution that describes content popularity increases.

2 Hit Rate Maximization for Web Content

The key measure of web performance is download time which is the time taken for a user to download a web object, such as a html page or an embedded image. CDNs enhance web performance by deploying a large number servers in access networks that are “close” to the users. Each server has a cache that is capable of storing web objects. When a user requests an object, such as a web page, the user is directed to a server that can serve the object (cf. Figure 1). If the server already has the object in its cache, i.e., the user’s request is a cache hit, the object is served from the cache to the user. In this case, the user experiences good performance, since the CDN’s servers are proximal to the user and the object is downloaded quickly. However, if the requested object is not in the server’s cache, i.e., the user’s request is a cache miss, then the server first fetches it from the origin, places it in its cache, and then serves the object to the user. In the case of a cache miss, the performance experienced by the user is often poor since the origin server is typically far away from the server and the user. In fact, if there is a cache miss, the user would have been better off not using the CDN at all, since downloading the content directly from the content provider’s origin would likely have been faster! Since the size of a server’s cache is bounded, cache misses are inevitable. A key goal of server selection for web content delivery is to jointly orchestrate server assignment and content placement in caches such that the cache hit rate is maximized. While server selection in CDNs is a complex process [16], we analytically model the key elements that relate to content placement and cache hit rates, leaving other factors that impact performance such as server-to-user latency for future work.

2.1 Problem Formulation

Let \( U \) be a set of \( n_u \) users who each request an object picked independently from a set \( C \) of size \( n_c \) using a power law distribution where the \( k^{th} \) most popular object in \( C \) is picked with a probability

\[
p_k \Delta \frac{1}{k\alpha \cdot H(n_c, \alpha)}, \tag{1}
\]
where $\alpha \geq 0$ is the exponent of the distribution and $H(n_c, \alpha)$ is the generalized harmonic number that is the normalizing constant, i.e., $H(n_c, \alpha) = \sum_{k=1}^{n_c} 1/k^\alpha$. Note that power law distributions (aka Zipf distributions) are commonly used to model the popularity of online content such as web pages, and videos. This family of distributions is parametrized by a Zipf rank exponent $\alpha$ with $\alpha = 0$ representing the extreme case of an uniform distribution and larger values of $\alpha$ representing a greater skew in the popularity. It has been estimated that the popularity of web content can be modeled by a power law distribution with an $\alpha$ in the range from 0.65 to 0.85 [4, 10, 9].

Let $S$ be the set of $n_s$ servers that are capable of serving content to the users. Each server can cache at most $\kappa$ objects and a cache replacement policy such as LRU is used to evict objects when the cache is full. Each server processes simultaneous user requests by batching the requests according to the object that is being accessed, i.e., requests that are for the same object are placed in the same batch. The batches are then processed in a random sequence by the server. Given that the download time of a web object is significantly different when the request is a cache hit versus a cache miss, we make the reasonable assumption that the user can reliably infer if its request to download an object from a server resulted in a cache hit or a cache miss immediately after the download completes.

The objective of client-side server selection is for each user $u \in U$ to independently select a server $s \in S$ using only the performance feedback obtained on whether each request was a hit or a miss. In the rest of the section, we describe a simple canonical “Go-With-The-Winner” algorithm for server selection and show that it converges quickly to an optimal state, with high probability.

Note: Our formulation is intentionally simple so that it could model a variety of other situations in web content delivery. For instance, a single server could in fact model a cluster of front-end servers that share a single backend object cache. A single object could in fact model a bucket of objects that cached together as is often done in a CDN context [16].

2.2 Algorithm MaxHitRate

After each user $u \in U$ has picked an object $c_u \in C$ using the power law distribution described in Equation 1, algorithm MaxHitRate described below is executed independently by each user $u \in U$ to select a server that can deliver its requested object.

1. Choose a random subset $S_u \subseteq S$ of candidate servers such that $|S_u| = \sigma$. (We call $\sigma$ the spread.)
2. At each time step $t \geq 0$, do the following:

(a) Request content $c_u$ from all servers $s \in S_u$.

(b) For each server $s \in S_u$, compute hit rate

$$H_\tau(u, s, t) \triangleq \text{percentage of the last } \tau \text{ requests from user } u \text{ to server } s \text{ that were cache hits.}$$

(c) If there exists a server $s \in S_u$ such that $H_\tau(u, s, t) = 100\%$, then decide on server $s$ by setting $S_u \leftarrow \{s\}$.

In the above algorithm, the users execute a simple “Go-With-The-Winner” strategy of trying out $\sigma$ randomly chosen candidate servers initially. Then, using the past hit rate over a time window of length $\tau$ as feedback, each user independently either chooses to continue with all the servers in $S_u$ or decides on a single server that provided the best performance. If multiple servers provided a 100% hit rate in step 2(c) of the algorithm, the user decides to use an arbitrary one.

2.3 Analysis of Algorithm MaxHitRate

Here we rigorously analyze the case where $n_u = n_c = n_s = n$ and experimentally explore other variants where $n_c$ and $n_u$ are much larger than $n_s$ in Section 4. Let $H(t)$ (called the minmax hit rate) be the best hit rate obtained by the worst user at time $t$, i.e.,

$$H(t) \triangleq \min_{u \in U} \max_{s \in S} H_\tau(u, s, t).$$

If $\sigma \geq 2$, we show that with high probability $H(t) = 100\%$, for all $t \geq T$, where $T = O(\kappa \log n \log \log n / \log(\kappa + 1))$ and $\kappa$ is the cache size. That is, the algorithm converges quickly with high probability to an optimal state where every user has decided on a single server that provides it a 100% hit rate, and every server has the objects that its users request in its cache.

Definitions. A server $s$ is said to be overloaded at some time $t$ if users request more than $\kappa$ distinct objects from server $s$, where $\kappa$ is the size of the cache. Note that a server may have more than $\kappa$ users and not be overloaded, provided the users collectively request a set of $\kappa$ or fewer objects. Also, note that a server that is overloaded at time $t$ is overloaded at every $t' \leq t$ since the number of users requesting a server can only remain the same or decrease with time. Finally, a user $u$ is said to be undecided at time $t$ if $|S_u| > 1$ when it executes step 2(a) of the algorithm, and is said to be decided if it has settled on a single server to serve its content and $|S_u| = 1$. Note that
each user starts out undecided at time zero, then decides on a server at some time \( t \) and remains decided in all future time steps larger than \( t \).

**Lemma 1.** For any time \( t > 0 \), if user \( u \) receives a cache miss from server \( s \) at some time \( t \), then server \( s \) is overloaded at time \( t - 1 \).

**Proof.** If user \( u \) requested an object \( c_u \) from server \( s \) at time \( t \), it must have also requested \( c_u \) from server \( s \) at time \( t - 1 \). As soon as the request for \( c_u \) was processed at time \( t - 1 \), it was placed in the cache of server \( s \). There must have been \( \kappa \) other requests for distinct objects that caused the LRU cache replacement policy to evict \( c_u \) from cache, resulting in the cache miss at time \( t \). Thus, at least \( \kappa + 1 \) distinct objects were requested from server \( s \) at time \( t - 1 \), i.e., server \( s \) is overloaded at time \( t - 1 \). \( \square \)

To prove convergence, we choose the *sliding window size* \( \tau = c\kappa \log n \), for a suitably large positive constant \( c \). Further, consider an initial time interval from time zero to time \( T \) that consists of \( \rho \) intervals of length \( \tau + 1 \) each, where \( \rho = 2 \log \log n / \log(\kappa + 1) \). Thus, \( T = \rho \cdot (\tau + 1) = O(\kappa \log n \log \log n / \log(\kappa + 1)) \).

**Lemma 2.** The probability that some user \( u \in U \) decides on an overloaded server \( s \in S \) at some time \( t \), \( 0 \leq t \leq T \), is at most \( 1/n^{O(1)} \).

**Proof.** Suppose user \( u \) decides on an overloaded server \( s \) at time \( t \). Then, it must be the case that \( H_\tau(u, s, t) = 100\% \). Thus, server \( s \) provided a cache hit to user \( u \) in every time \( t' \), \( t - \tau < t' \leq t \). Recall that each server serves simultaneous requests by first batching the requests according to the requested content, i.e., each batch contains requests for the same object, and then serving each batch in random order. Since server \( s \) is overloaded at time \( t \), it must have been overloaded during all the previous time steps. An overloaded server \( s \) has at least \( \kappa + 1 \) distinct objects being requested, i.e., it has at least \( \kappa + 1 \) batches of requests. The request made by user \( u \) will receive a cache miss if the batch in which it belongs to is \( \kappa + 1 \) or higher in the random ordering. Thus, the probability that user \( u \) receives a cache miss from the overloaded server \( s \) in any time step \( t' \leq t \) is at least \( 1/(\kappa + 1) \). Since \( H_\tau(u, s, t) \) is 100% only if there is no cache miss at any time \( t' \), \( t - \tau < t' \leq t \), the probability of such an occurrence is at most

\[
\left(1 - \frac{1}{\kappa + 1}\right)^\tau \leq \left(1 - \frac{1}{\kappa + 1}\right)^{c\kappa \log n} = \frac{1}{n^{O(1)}},
\]

since \( \tau = c\kappa \log n \). Using the union bound and choosing a suitably large constant \( c \), the probability that there exists a user \( u \in U \) who decides on an
overloaded server $s$ at some $t$, $0 < t < T$, is at most
\[
\frac{n \times (T + 1)}{n^{\Omega(1)}} \leq \frac{1}{n^{\Omega(1)}},
\]
since there are $n$ users, at most $n$ overloaded servers, and $T + 1 = \Omega(\kappa \log n \log \log n / \log (\kappa + 1))$ time steps.

**Theorem 3.** With probability at least $1 - 1/n\Omega(1)$, the minmax hit rate $H(t) = 100\%$, for all $t \geq T$, provided $\sigma \geq 2$ and $T = \Omega(\kappa \log n \log \log n / \log (\kappa + 1))$. That is, with high probability, algorithm MaxHitRate converges by time $T$ to an optimal state where each user $u \in U$ has decided on a server $s \in S$ that serves it content with a 100% cache hit rate.

**Proof.** For simplicity, we prove the situation where $\sigma = 2$, i.e., each user initially chooses two random candidate servers in step 1 of the algorithm. The case where $\sigma > 2$ is analogous. Wlog, we also assume $\kappa$ is at most $\Omega(\log n / \log \log n)$, which includes the practically interesting case of $\kappa$ equal to a constant. When cache size is larger, i.e., if $\kappa = \Omega(\log n / \log \log n)$, there will be no overloaded servers with high probability and the theorem holds trivially. This observation follows from a well-known result that if $n$ balls (i.e., users) uniformly and randomly select $k$ out of $n$ bins (i.e. servers), then the maximum number of users that select a server is $\Omega(\log n / \log \log n)$ with high probability, when $k$ is a fixed constant [17].

In contradiction to the theorem, suppose some user $u$ (say) has not decided on a server by time $T$. We construct a "witness tree" of degree $\kappa + 1$ and depth at least $\rho$, where $\rho = T / (\tau + 1) = 2 \log \log n / \log (\kappa + 1)$. Each node of the witness tree is a server. Each edge of the witness tree is a user whose two nodes correspond to the two servers chosen by that user. We show that the existence of an undecided user in time step $T$ is unlikely by enumerating all possible witness trees and showing that the occurrence of any such witness tree is unlikely. The proof proceeds in the following three steps.

(1) **Constructing a witness tree.** If algorithm MaxHitRate has not converged to the optimal state at time $T$, then there exists an user (say $u_1$) and a server $s$ such that $H_t(u_1, s, T - 1) < 100\%$, since user $u_1$ has not yet found a server with a 100% hit rate. We make server $s$ the root of the witness tree.

We find children for the root $s$ to extend the witness tree as follows. Since $H_t(u_1, s, T - 1) < 100\%$, there exists a time $t'$, $T - 1 - \tau < t' \leq T - 1$,\footnote{A witness tree is so called as it bears witness to the occurrence of an event such as a user being undecided.}
such that user $u_1$ received a cache miss from server $s$. By Lemma 1, server $s$ was overloaded at time $t' - 1$, i.e., there are at least $\kappa + 1$ users requesting server $s$ for $\kappa + 1$ distinct objects at time $t' - 1$. Let $u_1, \ldots, u_{\kappa + 1}$ be the users who sent requests to server $s$ at time $t' - 1$. Wlog, assume that the users $\{u_i\}$ are ordered in ascending order of their IDs. By Lemma 2 we know that the probability of a user deciding on an overloaded server is small, i.e., at most $1/n^{\Omega(1)}$. Thus, with high probability, users $u_1, \ldots, u_{\kappa + 1}$ are undecided at time $t' - 1$ since they made a request to an overloaded server $s$. Let $s_i$ be the other server choice associated with user $u_i$ (one of the choices is server $s$). We extend the witness tree by creating $\kappa + 1$ children for the root $s$, one corresponding to each server $s_i$. Note that for each of the servers $s_i$ we know that $H(u_i, s_i, t' - 2) < 100\%$, since otherwise user $u_i$ would have decided on server $s_i$ in time step $t' - 2$. Thus, analogous to how we found children for $s$, we can recursively find $\kappa + 1$ children for each of the servers $s_i$ and grow the witness tree to an additional level.

Observe that to add an additional level of the witness tree we went from server $s$ at time $T - 1$ to servers $s_i$ at time $t' - 2$, i.e., we went back in time by an amount of $T - 1 - (t' - 2) \leq \tau + 1$. If we continue the same process, we can construct a witness tree that is a $(\kappa + 1)$-ary tree of depth $T/\tau + 1 = \rho$.

(2) Pruning the witness tree. If the nodes of the witness tree are guaranteed to represent distinct servers, proving our probabilistic bound is relatively easy. The reason is that if the servers are unique then the users that represent edges of the tree are unique as well. Therefore the probabilistic choices that each user makes is independent, making it easy to evaluate the probability of occurrence of the tree. However, it may not be the case that the servers in the witness tree constructed above are unique, leading to dependent choices that are hard to resolve. Thus, we create a pruned witness tree by removing repeated servers from the original (unpruned) witness tree.

We prune the witness tree by visiting the nodes of the witness tree iteratively in breadth-first search order starting at the root. As we perform breadth-first search (BFS), we remove (i.e., prune) some nodes of the tree and the subtrees rooted at these nodes. What is left after this process is the pruned witness tree. We start by visiting the root. In each iteration, we visit the next node $v$ in BFS order that has not been pruned. Let $\beta(v)$ denote the nodes visited before $v$. If $v$ represents a server that is different from the servers represented by nodes in $\beta(v)$, we do nothing. Otherwise, prune all nodes in the subtree rooted at $v$. Then, mark the edge from $v$ to its parent as a pruning edge. (Note that the pruning edges are not part of the pruned witness tree.) The procedure continues until either no more nodes remain to be visited or there are $\kappa + 1$ pruning edges. In the latter case, we apply
a final pruning by removing all nodes that are yet to be visited, though this step does not produce any more pruning edges. This process results in a pruned witness and a set of $p$ (say) pruning edges.

Note that each pruning edge corresponds to a user who we will call a **pruned user**. We now make a pass through the pruning edges to select a set $P$ of unique pruned users. Initially, $P$ is set to $\emptyset$. We visit the pruning edges in BFS order and for each pruning edge $(u, v)$ we add the user corresponding to $(u, v)$ to $P$, if this user is distinct from all users currently in $P$ and if $|P| < \lfloor p/2 \rfloor$, where $p$ is the total number of pruning edges. We stop adding pruned users to set $P$ when we have exactly $\lceil p/2 \rceil$ users. Note that since a user who made server choices of $u$ and $v$ can appear at most twice as a pruned edge, once with $u$ in the pruned witness tree and once with $v$ in the pruned witness tree. Thus, we are guaranteed to find $\lfloor p/2 \rfloor$ distinct pruned users.

After the pruning process, we are left with a pruned witness tree with nodes representing distinct servers and edges representing distinct users. In addition, we have a set $P$ of $\lceil p/2 \rceil$ distinct pruned users, where $p$ is the number of pruning edges.

**(3) Bounding the probability of pruned witness trees.** We enumerate possible witness trees and bound their probability using the union bound. Observe that since the (unpruned) witness tree is a $(\tau + 1)$-ary tree of depth $\rho$, the number of nodes in the witness tree is

$$m = \sum_{0 \leq i \leq \rho} (\kappa + 1)^i = \frac{(\kappa + 1)^{\rho+1} - 1}{\kappa} \leq 2 \log^2 n, \quad (2)$$

since $\rho = 2 \log \log n / \log(\kappa + 1)$ and hence $(\kappa + 1)^\rho = \log^2 n$.

**Ways of choosing the shape of the pruned witness tree.** The shape of the pruned witness tree is determined by choosing the $p$ pruning edges of the tree. The number of ways of selecting the $p$ pruning edges is at most $\binom{m}{p} \leq m^p$, since there are at most $m$ edges in the (unpruned) witness tree.

**Ways of choosing users and servers for the nodes and edges of the pruned witness tree.** The enumeration proceeds by considering the nodes in BFS order. The number of ways of choosing the server associated with the root is $n$. Consider the $i^{th}$ internal node $v_i$ of the pruned witness tree whose server has already been chosen to be $s_i$. Let $v_i$ have $\delta_i$ children. There are at most $\binom{\delta_i}{\delta_i}$ ways of choosing distinct servers for each of the $\delta_i$ children of $v_i$. Also, since there are at most $n$ users in the system at any point in time, the number of ways to choose distinct users for the $\delta_i$ edges incident on $v_i$ is also at most $\binom{n}{\delta_i}$. There are $\delta_i!$ ways of pairing the users and the servers.
Further, the probability that a chosen user chooses server $s_i$ corresponding to node $v_i$ and a specific one of $\delta_i$ servers chosen above for $v_i$’s children is

$$\frac{1}{\binom{n}{2}} = \frac{2}{n(n-1)},$$

since each set of two servers is equally likely to be chosen in step 1 of the algorithm. Further, note that each of the $\delta_i$ users chose $\delta_i$ distinct objects and let the probability of occurrence of this event be $Uniq(n_c, \delta_i)$. This uniqueness probability has been studied in the context of collision-resistant hashing and it is known that $Uniq(n_c, \delta_i)$ is largest when the content popularity distribution is the uniform distribution ($\alpha = 0$) and progressively becomes smaller as $\alpha$ increases. In particular, $Uniq(n_c, \delta_i) \leq e^{-\Theta(\delta_i^2/n_c)} < 1$. Putting it together, the number of ways of choosing a distinct server for each of the $\delta_i$ children of $v_i$, choosing a distinct user for each of the $\delta_i$ edges incident on $v_i$, choosing a distinct object for each user, and multiplying by the appropriate probability is at most

$$\binom{n}{\delta_i} \cdot \binom{n}{\delta_i} \cdot \delta_i! \cdot \left( \frac{2}{n(n-1)} \right)^{\delta_i} \cdot Uniq(n_c, \delta_i) \leq \frac{2^{\delta_i}}{\delta_i!},$$

provided $\delta_i > 1$. Let $m'$ be the number of internal nodes $v_i$ in the pruned witness tree such that $\delta_i = \kappa + 1$. Using the bound in Equation 3 for only these $m'$ nodes, the number of ways of choosing the users and servers for the nodes and edges respectively of the pruned witness tree weighted by the probability that these choices occurred is at most

$$n \cdot (2^{\kappa+1}/(\kappa + 1)!)^{m'}. $$

**Ways of choosing the pruned users in $P$.** Recall that there are $\lfloor p/2 \rfloor$ distinct pruned users in $P$. The number of ways of choosing the users in $P$ is at most $n^{\lfloor p/2 \rfloor}$, since at any time step there are at most $n$ users in the system to choose from. Note that a pruned user has both of its server choices in the pruned witness tree. Therefore, the probability that a given user is a pruned user is at most $m^2/n^2$. Thus the number of choices for the $\lfloor p/2 \rfloor$ pruned users in $P$ weighted by the probability that these pruned users occurred is at most

$$n^{\lfloor p/2 \rfloor} \cdot (m^2/n^2)^{\lfloor p/2 \rfloor} \leq (m^2/n)^{\lfloor p/2 \rfloor}. $$

**Bringing it all together.** The probability that there exists a pruned witness tree with $p$ pruning edges, and $m'$ internal nodes with $(\kappa + 1)$ children each,
is at most
\[
m^p \cdot n \cdot (2^{\kappa+1}/(\kappa+1)!)^m \cdot (m^2/n)^{[p/2]} \]
\[
\leq n \cdot (2^{\kappa+1}/(\kappa+1)!)^m \cdot (m^4/n)^{[p/2]} \]
\[
\leq n \cdot (2e/(\kappa+1))^{m'(\kappa+1)} \cdot (m^4/n)^{[p/2]},
\]
(4)
since \((\kappa+1)! \geq ((\kappa+1)/e)^{\kappa+1}\). There are two possible cases depending on how the pruning process terminates. If the number of pruning edges, \(p\), equals \(\kappa+1\) then the third term of Equation (4) is
\[
(m^4/n)^{[p/2]} \leq (16 \log^8 n/n/((\kappa+1)/2)^2 \leq 1/n^{\Omega(1)},
\]
using Equation (2) and assuming that cache size \(\kappa\) is at least a suitably large constant. Alternately, if the pruning process terminates with fewer than \(\kappa+1\) pruning edges, it must be that at least one of the \(\kappa+1\) subtrees rooted at the children of the root \(s\) of the (unpruned) witness tree has no pruning edge. Thus, the number of internal nodes \(m'\) of the pruned witness tree with \((\kappa+1)\) children each is bounded as follows:
\[
m' = \sum_{0 \leq i < \rho-1} (\kappa + 1)^i \geq (\kappa + 1)^{\rho-2} \geq \log^2 n/(\kappa + 1)^2,
\]
as \((\kappa + 1)^\rho = \log^2 n\). Thus, the second term of Equation (4) is
\[
(2e/(\kappa+1))^{m'(\kappa+1)} \leq (2e/(\kappa+1))^{\log^2 n/(\kappa+1)} \leq 1/n^{\Omega(1)},
\]
assuming \(\kappa > 2e - 1\) but is at most \(O(\log n/\log \log n)\). Thus, in either case, the bound in Equation (4) is \(1/n^{\Omega(1)}\). Further, since there are at most \(m\) values for \(p\), the total probability of a pruned witness tree is at most \(m \cdot 1/n^{\Omega(1)}\) which is \(1/n^{\Omega(1)}\). This completes the proof of the theorem.

Are two or more random choices necessary for all users to receive a 100\% hit rate? Analogous to the “power of two choices” in the balls-into-bins context \([13]\), we show that two or more choices are required for good performance.

**Theorem 4.** For any fixed constants \(0 \leq \alpha < 1\) and \(\kappa \geq 1\), when algorithm MaxHitRate uses one random choice for each user (\(\sigma = 1\)), the minmax hit rate \(H(t) = o(1)\), with high probability, i.e., \(H(t)\) tends to zero as \(n\) tends to infinity, with high probability.
Proof. From the classical analysis of throwing \( n \) balls into \( n \) bins \[14\], we know that there exist a subset \( U' \subseteq U \) such that \( |U'| = \Theta(\log n / \log \log n) \) and all users in \( U' \) have chosen a single server \( s \), with high probability. Now we show that some user in \( U' \) must have a small hit rate with high probability. Let \( C' \) represent the set of all objects accessed by all users in \( S' \). The probability that \( |C'| \leq \kappa w(n) \) can be upper bounded as follows, where \( w(n) \) is an arbitrarily slowly growing function of \( n \). The number of ways of picking \( C' \) objects from a set \( C \) of \( n \) objects is at most \( n^{\left|C'\right|} \). The probability that a user in \( U' \) will pick an object in \( C' \) can be upper bounded by the probability that a user chooses one of the \( |C'| \) most popular objects. Thus the probability that a user in \( U' \) picks an object in \( C' \) is at most \( H\left(\frac{|C'|}{n}, \alpha\right) / H(n, \alpha) = \Theta\left(\left(\frac{|C'|}{n}\right)^{1-\alpha}\right) \), where \( H(i, \alpha) \) is the \( i^{th} \) generalized harmonic number and is \( \Theta(i^{1-\alpha}) \). Thus, the probability that all users in \( U' \) pick objects in \( C' \) is at most \( \Theta\left(\left(\frac{|C'|}{n}\right)^{(1-\alpha)|U'|}\right) \). Therefore, the probability that \( |C'| \leq \kappa w(n) \) is at most
\[
n^{\left|C'\right|} \cdot \Theta\left(\left(\frac{|C'|}{n}\right)^{(1-\alpha)|U'|}\right) \\
\leq n^{\kappa w(n)} \cdot \left(\frac{\kappa w(n)}{n}\right)^{\Theta(\log n / \log \log n)} = o(1)
\]
Thus, probability that \( |C'| \leq \kappa w(n) \) is small and hence \( |C'| > \kappa w(n) \), with high probability. Since the minmax hit rate \( H(t) \) is at most \( \kappa / |C'| \) which is at most \( 1/w(n) \), \( H(t) \) tends to zero with high probability. 

3 Bitrate Maximization for Video Content

In video streaming, a key performance metric is the bitrate at which an user can download the video stream. If the server is unable to provide the required bitrate to the user, the video will freeze frequently resulting in an inferior viewing experience and reduced user engagement \[12\]. For simplicity, we model the server’s bandwidth capacity that is often the critical bottleneck resource, while leaving other factors that could influence video performance such as the server-to-user connection and the server’s cache for future work.

3.1 Problem formulation

The bitrate required to play a stream without freezes is often the encoded bitrate of the stream. For simplicity, we assume that each user requires a

\[2\]Unlike the web, cache hit rate is a less critical determinant of video performance. Videos are cached in chunks by the server. The next chunk is often prefetched from origin if it is not in cache, even while the current chunk is being played by the user, so as to hide the origin-to-server latency.

15
bitrate of 1 unit for playing its video and each server has the capacity to serve $\kappa$ units in aggregate. In each time step, each server evenly divides its available bitrate capacity among all users who request videos in that time step. We make the reasonable assumption that each user can compute the bitrate that it receives from its chosen candidate servers and that this bitrate is used as the performance feedback (cf. Figure 1). The goal of each user is to find a server who can provide the required bitrate of 1 unit for viewing the video.

### 3.2 Algorithm MaxBitRate

After each user $u \in U$ has picked a video object $c_u \in C$ using the power law distribution described in Equation 1, Algorithm MaxBitRate described below is executed independently by each user $u \in U$.

1. Choose a random subset of candidate servers $S_u \subseteq S$ such that $|S_u| = \sigma$.
2. At each time step $t \geq 0$, do the following:
   
   (a) Request the video content from all servers $s \in S_u$.
   (b) For each server $s \in S_u$, compute $B(u, s, t) \triangleq$ bitrate provided by server $s$ to user $u$ in the current time step.
   (c) If there exists a server $s \in S_u$ such that $B(u, s, t) = 1$, then decide on server $s$ by setting $S_u \leftarrow \{s\}$.

Note that the users are executing a simple strategy of trying out $\sigma$ randomly chosen servers initially. Then, using the bitrate received in the current time step as feedback, each user independently narrows its choice of servers to a single server that provided the required unit bitrate. If multiple servers provided the required bitrate, the user decides to use an arbitrary one. Further, note that a user $u$ downloading from a server $s$ at time $t$ knows immediately whether or not the server is overloaded, since server $s$ is overloaded iff user $u$ received a bitrate of less than 1 unit from the server, i.e., $B(u, s, t) < 1$.

This is a point of simplification in relation to the more complex situation for hit rate maximization where any single cache hit is not indicative of a non-overloaded server and a historical average of hit rates over a large enough time window $\tau$ is required as a probabilistic indicator of server overload. As we will see, this simplification yields both faster convergence to an optimal state in $T = O(\log \log n / \log(\kappa + 1))$ steps and a much simpler proof of that convergence.
3.3 Analysis of Algorithm MaxBitRate

As before, we rigorously analyze the case where \( n_u = n_s = n \). Let the \( \text{minmax} \) bitrate \( B(t) \) be the best bitrate obtained by the worst user at time \( t \), i.e.,

\[
B(t) \triangleq \min_{u \in U} \max_{s \in S} B(u,s,t).
\]

**Theorem 5.** With probability at least \( 1 - \frac{1}{n^{\Omega(1)}} \), the \( \text{minmax} \) bitrate \( B(t) = 1 \) unit, for all \( t \geq T \), provided \( \sigma \geq 2 \) and \( T = O(\log \log n / \log(\kappa + 1)) \). That is, with high probability, algorithm MaxBitRate converges in \( T \) time steps to an optimal state where each user \( u \in U \) has decided on a server \( s \in S \) that serves it the desired bitrate of 1 unit.

**Proof.** The proof is similar to that of Theorem 3 in that we create a witness tree, prune it, and then show that a pruned witness tree is unlikely. A server \( s \) is said to be overloaded at time \( t \) if more than \( \kappa \) users want to download from server \( s \) in time step \( t \). We construct a witness tree as follows. If the algorithm MaxBitRate has not converged to the optimal state at time \( T = 4 \log \log n / \log(\kappa + 1) \), then there exists an user (say \( u_1 \)) and a server \( s \) such that \( B(u_1,s,T-1) < 1 \), since user \( u_1 \) has not yet found a server that can provide a bitrate of 1 unit. We make server \( s \) the root of the witness tree. We find children for the root \( s \) to extend the witness tree as follows. Since \( B(u_1,s,T-1) < 1 \), there exists \( \kappa + 1 \) distinct users \( u_1, \ldots, u_{\kappa+1} \) who sent a request to server \( s \) at time \( T - 1 \). We know that users \( u_1, \ldots, u_{\kappa+1} \) are undecided at time \( T - 1 \) since they made a request to a overloaded server \( s \). Let \( s_i \) be the other server choice associated with user \( u_i \) (one of the choices is server \( s \)). We extend the witness tree by creating \( \kappa + 1 \) children for each of the servers \( s \). Note that for each of the servers \( s_i \) we know that \( B(u_i,s_i,T-2) < 1 \), since otherwise user \( u_i \) would have decided on server \( s_i \) in time step \( T - 2 \). Thus, analogous to how we found children for \( s \), we can recursively find \( \kappa + 1 \) children for each of the servers \( s_i \) and grow the witness tree to an additional level. Note that going back two time steps yields an additional level of the witness tree. Thus, we get a witness tree that is a \( (\kappa + 1) \)-ary tree of depth \( \rho = T/2 = 2 \log \log n / \log(\kappa + 1) \).

The rest of the proof of pruning and enumerating such witness trees to show that the probability that any such witness tree occurs is at most \( 1/n^{\Omega(1)} \) is similar to the proof of Theorem 3.

**Theorem 6.** When algorithm MaxBitRate uses one random choice for each user (\( \sigma = 1 \)), the \( \text{minmax} \) bitrate \( B(t) = O(\kappa \log \log n / \log n) \), with high
probability. In particular, when the cache size \( \kappa \) is \( o(\log n / \log \log n) \), including the case when \( \kappa \) is a fixed constant, \( B(t) \) tends to zero as \( n \) tends to infinity, with high probability.

**Note:** When \( \kappa \) is a constant, algorithm MaxHitRate converges in time \( O(\log n \log \log n) \), where the larger factor of \( \log n \) is due to the time each user has to wait to reliably estimate the hitrate. Since estimation is not required for bitrates, the convergence of MaxBitRate is faster and occurs in time \( O(\log \log n) \).

### 4 Empirical Evaluation

We empirically study our algorithm MaxHitRate by building a simulator. The simulations allow us to go beyond the simple theoretical model and evaluate the algorithm under more complex settings. Rather than implementing the algorithm in discrete time steps as presented in Section 2, each user in the simulation generates a sequence of requests using a Poisson process with unit rate in continuous time. We use \( n_u = 1000 \) users. To simulate varying numbers of servers, users, and objects, we also varied \( n_s \) and \( n_c \) such that \( 1 \leq n_u / n_c, n_u / n_s \leq 100 \). We also simulate a range of values for the spread \( 1 \leq \sigma \leq 6 \), and sliding window size \( 1 \leq \tau \leq 20 \). Each server implements an LRU cache of size \( \kappa \geq 2 \). The objects are accessed by users using the power law distribution of Equation 1 with \( \alpha = 0.65 \) to model realistic content popularity \[4\] \[10\] \[9\]. However, we also vary \( \alpha \) from 0 (uniform distribution) to 1.5 in some of our simulations.

The system is said to have **converged** when all users have decided on a single server from their set of candidate servers. There are two complementary metrics that relate to convergence. **Failure rate** is the probability that the system converged to a non-optimal state where there exists servers that are overloaded, resulting in some users incurring cache misses after convergence occurred. The failure rate is measured by performing the simulation multiple times and assessing the goodness of the converged state. **Convergence time** is the time it takes for the system to converge provided that it converged to an optimal state.

#### 4.1 Convergence over time

Figure 2 shows how the fraction of undecided users decreases over time till it reaches zero, resulting in convergence. Note that users do not decide in the first \( \tau \) steps, since they must wait at least that long to accumulate a window
Figure 2: The figures show the percentage of undecided users for a typical power law distribution ($\alpha = 0.65$) with spread $\sigma = 2$ and $n_u = 1000$. Note that the undecided users decrease with time in all cases, but the convergence is faster when we use fewer but bigger caches by setting $n_u/n_s$ to be larger. Also, the smaller values of the look-ahead window $\tau$ result in faster convergence.

Figure 3: Generally, as $\tau$ increases, convergence time increases but failure rate decreases. However, when there are fewer but larger servers ($n_u/n_s = 20$) the failure was zero even for a smaller sliding window of $\tau = 5$.
ratio of the numbers of users in the system and total cache space that is available in the system. That is, \( l \triangleq n_u/(\kappa \cdot n_s) \). For all three setting of Figure 2 we keep load \( l = 0.5 \). The figure shows that with fewer (but larger) servers \((n_u/n_s \text{ is large})\) the convergence time is faster, because having cache capacity in a few larger servers provides a larger hit rate than having the same cache capacity in several smaller servers. The convergence times are plotted explicitly in Figure 4 for a greater range of user-to-server ratios. As \( n_u/n_s \) increases from 1 to 40, convergence time decreases. The decrease in convergence times are not significant beyond \( n_u/n_s \geq 40 \).

### 4.2 Impact of sliding window \( \tau \)

The sliding window \( \tau \) is used by algorithm MaxHitRate to estimate the hit rate. As shown in Figure 3 there is a natural tradeoff between convergence time and failure rate. When \( \tau \) increases, the users take longer to converge, as they require a 100% hit rate in a larger historical window before they make a server decision. However, waiting for a longer period also makes their decisions more robust. That is, a user is less likely to choose an overloaded server, since an overloaded server is less likely to provide a string of \( \tau \) cache hits for larger \( \tau \). In our simulations with many smaller caches \((n_u/n_s = 1)\), when \( \tau \leq 4 \), users made quick choices based on a smaller sliding window. But, this resulted in the system converging to a non-optimal state 100% of the time. As \( \tau \) further increases, the failure rate decreased. The value of \( \tau = 11 \) is a suitable sweet spot as it results in the smallest convergence time.
for a zero failure rate. However, for fewer but larger caches \((n_s/n_u = 20)\), even a smaller window of \(\tau = 5\) yielded a zero percent failure rate.

### 4.3 Impact of spread \(\sigma\)

As shown in Theorems 3 and 4, a spread of \(\sigma \geq 2\) is required for the system to converge to an optimal solution, while a spread of \(\sigma = 1\) is insufficient. As predicted by our analysis, our simulations did not converge to an optimal state with \(\sigma = 1\). Figure 5 shows the convergence time as a function of spread, for \(\sigma \geq 2\).

As \(\sigma\) increases, there are two opposing factors that impact the convergence time. The first factor is that as \(\sigma\) increases, each user has more choices and the user is more likely to find a suitable server with less load. On the other hand, an increase in \(\sigma\) also increases the total number of initial requests in the system that equals \(\sigma n_u\). Thus, the system starts out in a state where servers have greater average load when \(\sigma\) is larger. These opposing forces result in a very small incremental benefit to using \(\sigma = 3\) instead of 2, though the higher values of \(\sigma > 3\) showed no benefit as convergence time increased with increasing \(\sigma\).

We established the “power of two random choices” phenomenon where two or more random server choices yield superior results to having just one. It is intriguing to ask what percentage of users need two choices to reap the benefits of multiple choices? Consider a mix of users, some with two random choices and others with just one. Let \(\sigma_{\text{avg}}, 1 \leq \sigma_{\text{avg}} \leq 2\), denote the average value of the spread among the users. In Figure 6 we show different order statistics of the hit rate as function of \(\sigma_{\text{avg}}\). Specifically, we plot the minimum value, 1st-percentile, 5th-percentile and the median (50th-percentile) of the hit rates of the users after running the system for a long enough period of time of 200 units. As our theory predicts, when

![Figure 6](image-url)
Figure 7: Heatmap shows that convergence is faster if the cache size ($\kappa$) and/or number of servers ($n_s$) is larger for same number of users ($n_u$). ($\alpha = 0.65, \tau = 10, \sigma = 4$.)

$\sigma_{avg} = 2$, the minimum and all the order statistics converge to 100%, as all users converge to a 100% hit rate. Further, if we are interested in only the median user, any value of the spread is sufficient to guarantee that 50% of the users obtain a 100% hit rate. Perhaps the most interesting phenomena is that if $\sigma_{avg} = 1.7$, i.e., 70% of the users have two choices and the rest have one choice, the 5th-percentile converges to 100%, i.e., all but 5% of the users experience a 100% hit rate. For a higher value of $\sigma_{avg} = 1.9$, the 1st-percentile converges to 100%, i.e., all but the 1% of the users experience a 100% hit rate. This result shows that our algorithm still provides benefits even if only some users have multiple random choices of servers available to them.

4.4 Impact of load

Now we look at the performance of our algorithm under varying load conditions. Recall load $l = n_u/(\kappa \cdot n_s)$. Figure 7 shows convergence time as a heatmap with different values of cache size $\kappa$ and number of servers $n_s$. The convergence time varies from lower (blue) to higher (red) values. The figure also shows contours where the load is fixed. The white block in the bottom left corner represents high load closer to 1 where our algorithm did not converge within a reasonable amount of time. It is easy to see that convergence time is faster when either the number of servers or the cache size increases. Figure 8 shows this trend more explicitly as the convergence time increases with increasing load.

The reason for this behavior is that as load increases there is more contention for the cache resources requiring more time for the algorithm to find
Figure 8: As load increases, contention for cache resources increase, requiring more time for users to converge to a good server. ($\alpha = 0.65, \tau = 10, \sigma = 4.$)

4.5 Impact of demand distribution

We now study how hit rate changes with the exponent $\alpha$ in the power law distribution of Equation 1. Note that the distribution is uniform when $\alpha = 0$ and is the harmonic distribution when $\alpha = 1$. As $\alpha$ increases, since the tails fall as a power of $\alpha$, the distribution gets more and more skewed towards objects with a smaller rank. In Figure 9, we plot the minmax hitrate over time for different $\alpha$, where we see that a larger $\alpha$ leads to faster convergence. The reason is that as the popularity distribution gets more skewed, a larger fraction of users can share the same cached popular objects, leading to better hit rate and faster convergence. Thus, the uniform content popularity distribution ($\alpha = 0$) is the worst case and the algorithm converges faster for the distributions that tend to occur more commonly in practice. Providing theoretical support for this empirical result by analyzing the convergence time to show faster convergence for larger $\alpha$ by using a tighter bound for $Uniq(n_c, \delta_i)$ in Equation 3 is topic for future work.

5 Related work

Server selection algorithms have a rich history of both research and actual implementations over the past two decades. Several server selection algorithms have been proposed and empirically evaluated, including client-side algorithms that use historical performance feedback using probes. Server selection has also been studied in a variety of contexts, such as the
web [6, 18], video streaming [19], and cloud services [20]. Our work is distinguished from the prior literature in that we theoretically model the “Go-With-The-Winner” paradigm that is common to many proposed and implemented client-side server selection algorithms. Our work is the first formal study of the efficacy and convergence of such algorithms.

In terms of analytical techniques, our work is closely related to prior work on balls-into-bins games where the witness tree technique was first utilized [14]. Witness trees were subsequently used to analyze load balancing algorithms, and circuit-switching algorithms [5]. However, our setting involves additional complexity requiring novel analysis due to the fact that users can share a single cached copy of an object and the hitrate feedback is only a probabilistic indicator of server overload. Also, our work shows that the “power of two random choices” phenomenon applies in the context of content delivery, a phenomenon known to hold in other contexts such as balls-into-bins, load balancing, relay allocation for services like Skype [15], and circuit switching in interconnection networks [14].

There are also parallels between our work on bitrate maximization for video delivery and the recent work on throughput maximization in multipath communication [11]. Similar in spirit to our work, the work on multipath communication concludes that coordinated rate control over multiple randomly selected paths provides optimal throughput and is significantly better than uncoordinated control where rates are determined independently over each single path. However, our work also evolves techniques for determining the convergence rate that is potentially applicable in these domains.

6 Conclusion

Our work constitutes the first formal study of the simple “Go-With-The-Winner” paradigm in the context of web and video content delivery. For web (resp., video) delivery, we proposed a simple algorithm where each user randomly chooses two or more candidate servers and selects the server that provided the best hitrate (resp., bitrate). We proved that the algorithm converges quickly to an optimal state where all users receive the best hitrate (resp., bitrate) and no server is overloaded, with high probability. While we make some assumptions to simplify the theoretical analysis, our simulations evaluate a broader setting that incorporates a range of values for \( \tau \) and \( \sigma \), varying content popularity distributions, differing load conditions, and situations where only some users have multiple server choices. Taken together, our work establishes that the simple “Go-With-The-Winner” paradigm can
provide algorithms that converge quickly to an optimal solution, given a sufficient number of random choices and a sufficiently (but not perfectly) accurate performance feedback.

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