On the algebraic classification of spacetimes

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Abstract. We briefly overview the Petrov classification in four dimensions and its generalization to higher dimensions.

1. Introduction - the Petrov classification in four dimensions

The Petrov classification, which was developed by Petrov [1] and extended e.g. in [2]-[5] (see [6]-[8] for additional references), invariantly determines algebraic type of the Weyl tensor at a given point of a spacetime. We say that a spacetime is of a given Petrov type if the type is same at all points. There are several equivalent methods of obtaining the classification. The most elegant one is probably the two component spinor approach developed by Penrose [5, 6]. In this approach the Weyl tensor is represented by a totally symmetric spinor

$$\Psi_{ABCD} = \alpha_{(A} \beta_{B} \gamma_{C} \delta_{D)}.$$ 

Petrov types now correspond to various multiplicities of principal spinors and following possibilities occur

- \(I = \{1111\} : \Psi_{ABCD} = \alpha_{(A} \beta_{B} \gamma_{C} \delta_{D)},\)
- \(II = \{211\} : \Psi_{ABCD} = \alpha_{(A} \alpha_{B} \gamma_{C} \beta_{D)},\)
- \(D = \{22\} : \Psi_{ABCD} = \alpha_{(A} \alpha_{B} \beta_{C} \beta_{D)},\)
- \(III = \{31\} : \Psi_{ABCD} = \alpha_{(A} \alpha_{B} \gamma_{C} \beta_{D)},\)
- \(N = \{4\} : \Psi_{ABCD} = \alpha_{A} \alpha_{B} \alpha_{C} \alpha_{D},\)
- \(O = \{-\} : \Psi_{ABCD} = 0\)

All Petrov types except of the type I are called algebraically special.

Null vectors corresponding to various principal spinors via \(v^A = \xi^A \bar{\xi}^A\) are called principal null vectors and corresponding directions principal null directions (PNDs). Thus there are at most four distinct PNDs at each point of a spacetime. In the tensorial form, PND corresponding to a vector \(\ell\) satisfies three equivalent conditions [6, 7] given in Table 1 for various Petrov types.

In some cases there is a close correspondence between the Petrov type and symmetries or a physical interpretation of the spacetime. For example a static spherically symmetric spacetime is of type D [9], with two double PNDs defining radially ingoing and outgoing null congruences.
\[ \ell^bC_{[a|b]e|c} = 0 \quad \ell \text{ at least simple PND (I)} \quad \Psi_0 = 0, \Psi_1 \neq 0 \]
\[ \ell^bC_{abc[e} = 0 \quad \ell \text{ at least double PND (II,D)} \quad \Psi_0 = 0, \Psi_1 = 0, \Psi_2 \neq 0 \]
\[ \ell^cC_{abc} = 0 \quad \ell \text{ at least triple PND (III)} \quad \Psi_0 = 0, \Psi_1 = 0, \Psi_2 = 0, \Psi_3 \neq 0 \]
\[ \ell^cC_{abcd} = 0 \quad \ell \text{ quadruple PND (N)} \quad \Psi_0 = 0, \Psi_1 = 0, \Psi_2 = 0, \Psi_3 = 0, \Psi_4 \neq 0 \]

Table 1. Each line contains three equivalent conditions for various Petrov types in four dimensions. \( \Psi_0 \ldots \Psi_4 \) are complex components of the Weyl tensor in the Newman-Penrose formalism [10, 6, 7]. The third condition means that it is possible to choose a frame in which given components of the Weyl tensor vanish.

Similarly one would expect that Friedmann-Robertson-Walker spacetime does not contain any preferred null direction and consequently it is of type O [6] and that the simplest gravitational waves (such as pp-waves) have only one preferred null direction and thus are of type N. (In fact gravitational waves with a longitudinal component which decays faster than transverse type N waves are of type III.)

In order to find exact solutions of the Einstein equations it is usually necessary to assume some symmetries. Another possibility is to assume a specific algebraically special type of a spacetime since then the field equations can also be considerably simplified.

In some cases the Petrov type can be distinct at some points or regions from the rest of a spacetime. An interesting example are black holes of type I with isolated or Killing horizons of type II [11, 12].

As it was mentioned above, in four dimensions there are several distinct methods leading to the Petrov classification and only some of them can be generalized to higher dimensions. Let us briefly describe the appropriate method, which can be also used in higher dimensions, at first in four dimensions:

In four dimensions in the standard complex null tetrad \((\ell, n, m, \bar{m})\) [6, 7] the Weyl tensor has five complex components \( \Psi_0 \ldots \Psi_4 \). A boost in \( \ell - n \) plane is described by \( \hat{\ell} = \lambda \ell, \hat{n} = \lambda^{-1}n \) and we say that a quantity \( q \) has a boost weight \( b \) if it transforms under boost according to \( \hat{q} = \lambda^b q \). Components of the Weyl tensor \( \Psi_0, \Psi_1, \Psi_2, \Psi_3, \Psi_4 \) have boost weight -2,-1,0,1,2, respectively. When \( \ell \) coincides with PND then \( \Psi_0 \) vanishes. Other components can be transformed away only in algebraically special cases. Namely, as can be seen from the Table 1, for types I, II, III, N one can transform away components with boost weight greater or equal to 2,1,0,-1, respectively. Type D is a special subcase of type II, all components with non-zero boost weight can be transformed away. In the next section we will use a similar approach for the classification of the Weyl tensor in higher dimensions.

2. Classification of the Weyl tensor in higher dimensions

In this section we overview the classification of the Weyl tensor in higher \((D)\) dimensions [13, 14]. In higher dimensions it is more convenient to use a real frame

\[ m^{(0)} = n, \quad m^{(1)} = \ell, \quad m^{(i)} = m^{(i)}, \quad i, j, k = 2 \ldots D - 1, \]

with two null vectors \( n, \ell \)

\[ \ell^a \ell_a = n^a n_a = 0, \quad \ell^a n_a = 1, \quad a = 0 \ldots D - 1, \]

and \( D - 2 \) spacelike vectors \( m^{(i)} \)

\[ m^{(i)} m^{(j)} = \delta_{ij}, \quad m^{(i)} \ell_a = 0 = m^{(i)} n_a, \quad i, j, k = 2 \ldots D - 1. \]
The metric has the form
\[ g_{ab} = 2\ell(a)n_b + \delta_{ij}m^{(i)}_a m^{(j)}_b, \]
which remains unchanged under null rotations
\[ \hat{\ell} = \ell + z^i z_i n, \quad \hat{n} = n, \quad \hat{m}^{(i)} = m^{(i)} - z_i n, \]
spins
\[ \hat{\ell} = \ell, \quad \hat{n} = n, \quad \hat{m}^{(i)} = X^i m^{(j)}, \]
and boosts
\[ \hat{\ell} = \lambda \ell, \quad \hat{n} = \lambda^{-1} n, \quad \hat{m}^{(i)} = m^{(i)}. \]

Let us define the boost order of a tensor \( T \) as the maximum boost weight of its frame components. It can be shown that the boost order of a tensor depends only on the choice of a null direction \( \ell \) and thus spins and boost do not affect it [13]. We will denote the boost order of a given tensor \( T \) as \( b(\ell) \) indicating the dependence on the choice of \( \ell \). We suppose that the particular choice of \( T \) is clear from the context (in our case it is the Weyl tensor).

Let us denote the maximum value of \( b(k) \) taken over all null vectors \( k \) as \( b_{\text{max}} \). Then we say that a null vector \( k \) is aligned with the tensor \( T \) whenever \( b(k) < b_{\text{max}} \). The integer \( b_{\text{max}} - b(k) - 1 \) is called order of alignment.

For the Weyl tensor aligned null vectors (or directions) represent a natural generalization of the principal null directions and we will call them WANDs (Weyl aligned null directions).

The classification of the Weyl tensor in higher dimensions can be based on the existence of WANDs of various orders of alignment. The Weyl tensor in an arbitrary dimension has in general components with boost weights \(-2 \leq b \leq 2\) and thus the order of alignment of a WAND cannot exceed 3.

We say that the primary alignment type of the Weyl tensor is G if there are no WANDs and it is 1, 2, 3, 4 if the maximally aligned null vector has order of alignment 0, 1, 2, 3, respectively.

Once we fix \( \ell \) as a WAND with maximal order of alignment, we can search for \( n \) with maximal order of alignment subject to the constraint \( n \cdot \ell = 1 \) and similarly define secondary alignment type. Alignment type is a pair consisting of primary and secondary alignment types. Possible alignment types are summarized in Table 2. We also introduce Weyl type with notation emphasizing the link with the four dimensional Petrov classification.

| Weyl type | alignment type | Petrov type |
|-----------|----------------|-------------|
| G         | G              | I           |
| I         | (1)            | I           |
| I_1       | (1,1)          | II          |
| II        | (2)            | D           |
| II_1      | (2,1)          | D           |
| III       | (3)            | III         |
| III_1     | (3,1)          | N           |
| N         | (4)            | N           |

Table 2. Classification of the Weyl tensor in four and higher dimensions. Note that in four dimensions alignment type (1) is necessarily equivalent to the type (1,1), (2) to (2,1) and (3) to (3,1) and since there is always at least one PND, type G does not exist.
In order to express the Weyl tensor in terms of its components in the $\ell$, $n$, $m^{(i)}$ frame we introduce an operation \{\}

\[ w_{\{a^2 b y c^2 z d\}} \equiv \frac{1}{2} (w_{[a^2 b y c^2 z d]} + w_{[c^2 x d y a^2 b]}). \]

Now the Weyl tensor in arbitrary dimension can be written as

\[
C_{abcd} = 4C_{001j} n_{a} m_{b} n_{c} m_{d} + 8C_{010m} n_{a} \ell_{b} n_{c} m_{d} + 4C_{0ijk} n_{a} m_{b} \ell_{b} m_{c} \ell_{b} \ell_{b} m_{d} \}

\[
+ 4C_{0101} n_{a} \ell_{b} m_{c} \ell_{d} + C_{0ij} n_{a} \ell_{b} m_{c} \ell_{d} \}

\[
+ 8C_{01ij} n_{a} m_{b} \ell_{b} m_{d} + C_{ijkl} m_{a} m_{b} \ell_{b} \ell_{b} m_{d} \}

\[
+ 8C_{10i1} \ell_{a} n_{b} \ell_{c} m_{d} + 4C_{11jk} \ell_{a} m_{b} \ell_{c} m_{d} + 4C_{11ij} \ell_{a} m_{b} \ell_{b} m_{d} \}

\]

Note that summation over $i$, $j$, $k$, $l$ indices is implicitly assumed and that boost orders of various components are also indicated.

Number of independent frame components of various boost weights, is

\[
\frac{2}{2} \left( \frac{(m + 2)(m - 1)}{2} \right) + 2 \left( \frac{(m + 1)m(m - 1)}{3} \right) + \frac{m^2(m^2 - 1)}{12} + \frac{m(m - 1)}{2},
\]

with $m = D - 2$. This is in agreement with the number of independent components of the Weyl tensor

\[
\frac{(D + 2)(D + 1)D(D - 3)}{12}.
\]

In the general case, the Weyl tensor is quite complicated, however, in some algebraically special cases it is much simpler and this can substantially simplify the field equations. The simplest case are type N spacetimes (such as pp-waves) with only $D(D - 3)/2$ independent components and the Weyl tensor of the form

\[
C_{abcd} = 4C_{11ij} \ell_{a} m_{b} \ell_{c} m_{d}.
\]

In fact type N in higher dimensions was already identified before the whole classification was worked out [15]. Similarly in [16] it was proven that static spherically symmetric spacetimes are “boost invariant” (this corresponds to the type D) in arbitrary dimension.

In [17] it was proven that in arbitrary dimension isolated horizons are locally of type II (or of more special type) similarly as in four dimensions.

The generalization of the Kerr metric for higher dimensions, the Myers-Perry solution, is also of type D in five dimensions [18] (see [19] for other type D black hole solutions in higher dimensions) while the black ring is of the type I (and of type II on the horizon) [20].

Interestingly, the peeling theorem for weakly asymptotically simple spacetimes in even dimensions can be, under certain assumptions, also demonstrated [21].

Note that in higher dimensions conditions given in the first column of Table 1 are only necessary (but not sufficient) conditions for the statements in the second column [20]. For example, a spacetime satisfying $\ell C_{abcd} = 0$ can be of the type II [20]. Such a spacetime has in principle a non-vanishing curvature invariant $C_{abcd}C^{abcd}$ and for type N and III spacetimes...
Let us at the end discuss interesting but not fully explored connection between algebraic type of the Weyl tensor and consequences following from the Bianchi and Ricci identities. In accordance with \[18\] we decompose first covariant derivatives of $\ell$ as

$$
\ell_{a;b} = L_{11} \ell_a \ell_b + L_{10} \ell_a n_b + L_{11} m_a^{(i)} \ell_b + L_{00} m_a^{(i)} n_b + L_{ij} m_a^{(i)} m_b^{(j)}
$$

and denote symmetric and antisymmetric parts of $L_{ij}$ as $S_{ij}$ and $A_{ij}$, respectively. Now we can define the expansion $\theta$ and the shear $\sigma_{ij}$ as follows:

$$
\theta \equiv \frac{1}{n-2} \ell^a_{;a} = \frac{1}{n-2} S_{kk},
$$

$$
\sigma_{ij} \equiv \left( \ell_{(ab)} - \theta \delta_{ij} m_a^{(k)} m_b^{(k)} \right) m^{(i)}a m^{(j)}b = S_{ij} - \frac{S_{kk}}{n-2} \delta_{ij}.
$$

In vacuum, where the Riemann tensor is equal to the Weyl tensor, the Bianchi identities $R_{abcd} + R_{abde} + R_{abec} = 0$ for type N spacetimes imply

$$
L_{k[i} \Psi_{j]k} = 0,
$$

$$
\Psi_{i[j} L_{k]} = 0,
$$

$$
L_{k[i} \Psi_{m]j} + L_{i[m} \Psi_{j]k} = 0,
$$

$$
\Psi_{i[k} A_{jm} + \Psi_{ij} A_{mk} + \Psi_{im} A_{kj} = 0,
$$

where $\Psi_{ij} = C_{ijkl}/2$. From these equations it follows that in arbitrary dimension the congruence corresponding to the WAND is geodesic \[18\]. This is also true in four dimensions. However, it also follows that in higher dimensions for vacuum type N spacetimes with non-vanishing expansion the matrices $S_{ij}$, $A_{ij}$ and $\Psi_{ij}$ have certain specific form \[18\] and that shear does not vanish. According to the four-dimensional Goldberg-Sachs theorem \[22, 7\] the multiple principal null vector in vacuum algebraically special spacetimes is geodesic and shearfree. From the above mentioned results we can see that the Goldberg-Sachs theorem does not have a straightforward generalization for higher dimensions (this was also pointed out in \[23\]). However, some partial steps towards the generalization can be done (see Sec. 5 in \[18\]).

Let us conclude that the algebraic classification of higher dimensional spacetimes gives us a new important tool in higher dimensional gravity. As the standard four-dimensional Petrov classification, it allows us to classify and study physical properties of spacetimes and hopefully it will also generate new algebraically special solutions.

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