Towards Consistent Document-level Entity Linking: Joint Models for Entity Linking and Coreference Resolution

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Abstract

We consider the task of document-level entity linking (EL), where it is important to make consistent decisions for entity mentions over the full document jointly. We aim to leverage explicit “connections” among mentions within the document itself: we propose to join EL and coreference resolution (coref) in a single structured prediction task over directed trees and use a globally normalized model to solve it. This contrasts with related works where two separate models are trained for each of the tasks and additional logic is required to merge the outputs. Experimental results on two datasets show a boost of up to +5% F1-score on both coref and EL tasks, compared to their standalone counterparts. For a subset of hard cases, with individual mentions lacking the correct EL in their candidate entity list, we obtain a +50% increase in accuracy.\footnote{Our code, models and AIDA+ dataset will be released on https://github.com/klimzaporojets/consistent-EL}

1 Introduction

In this paper we explore a principled approach to solve entity linking (EL) jointly with coreference resolution (coref). Concretely, we formulate coref+EL as a single structured task over directed trees that conceives EL and coref as two complementary components: a coreferenced cluster can only be linked to a single entity or NIL (i.e., a non-linkable entity), and all mentions linking to the same entity are coreferent. This contrasts with previous attempts to join coref+EL (Hajishirzi et al., 2013; Dutta and Weikum, 2015; Angell et al., 2021) where coref and EL models are trained separately and additional logic is required to merge the predictions of both tasks.

Our first approach (Local in Fig. 1(a)) is motivated by current state-of-the-art coreference resolution models (Joshi et al., 2019; Wu et al., 2020) that predict a single antecedent for each span to resolve.

We extend this architecture by also considering entity links as potential antecedents: in the example of Fig. 1, the mention “Alliance” can be either connected to its antecedent mention “NATO” or to any of its candidate links (Alliance or Alliance,_Ohio). While straightforward, this approach cannot solve cases where the first coreferenced mention does not include the correct entity in its candidate list (e.g., if the order of “NATO” and “Alliance” mentions in Fig. 1 would be reversed). We therefore propose a second approach, Global, which by construction overcomes this inherent limitation by using bidirectional connections between mentions. Because that implies cycles could be formed, we resort to solving a maximum spanning tree problem. Mentions that refer to the same entity form a cluster, represented as a subtree rooted by the single entity they link to. To encode the overall document’s clusters in a single spanning tree, we introduce a virtual root node (see Fig. 1(b)).\footnote{Coreference clusters without a linked entity, i.e., a NIL cluster, have a link of a mention directly to the root.}

This paper contributes: (i) 2 architectures (Local and Global) for joint entity linking (EL) and...
coreference resolution, (ii) an extended AIDA dataset (Hoffart et al., 2011), adding new annotations of linked and NIL coreference clusters, (iii) experimental analysis on 2 datasets where our joint coref+EL models achieve up to +5% F1-score on both tasks compared to standalone models. We also show up to +50% in accuracy for hard cases of EL where entity mentions lack the correct entity in their candidate list.

2 Architecture

Our model takes as input (i) the full document text, and (ii) an alias table with entity candidates for each of the possible spans. Our end-to-end approach allows to jointly predict the mentions, entity links and coreference relations between them.

2.1 Span and Entity Representations

We use SpanBERT (base) from Joshi et al. (2020) to obtain span representations \( g_i \) for a particular span \( s_i \). Similarly to Luan et al. (2019); Xu and Choi (2020), we apply an additional pruning step to keep only the top-\( N \) spans based on the pruning score \( \Phi_p \) from a feed-forward neural net (FFNN):

\[
\Phi_p(s_i) = \text{FFNN}_P(g_i). \tag{1}
\]

For a candidate entity \( e_j \) of span \( s_i \) we will obtain representation as \( e_j \) (which is further detailed in §3).

2.2 Joint Approaches

We propose two methods for joint coreference and EL. The first, Local, is motivated by end-to-end span-based coreference resolution models (Lee et al., 2017, 2018) that optimize the marginalized probability of the correct antecedents for each given span. We extend this local marginalization to include the span’s candidate entity links. Formally, the modeled probability of \( y \) (text span or candidate entity) being the antecedent of span \( s_i \) is:

\[
P_{cl}(y|s_i) = \frac{\exp \left( \Phi_{cl}(s_i, y) \right)}{\sum_{y' \in \mathcal{Y}(s_i)} \exp \left( \Phi_{cl}(s_i, y') \right)}, \tag{2}
\]

where \( \mathcal{Y}(s_i) \) is the set of antecedent spans unified with the candidate entities for \( s_i \). For antecedent spans \( \{ s_j : j < i \} \) the score \( \Phi_{cl} \) is defined as:

\[
\Phi_{cl}(s_i, s_j) = \Phi_p(s_i) + \Phi_p(s_j) + \Phi_c(s_i, s_j), \tag{3}
\]

\[
\Phi_c(s_i, s_j) = \text{FFNN}_C([g_i; g_j; g_i \odot g_j; \varphi_{i,j}]), \tag{4}
\]

where \( \varphi_{i,j} \) is an embedding encoding the distance\(^3\) between spans \( s_i \) and \( s_j \). Similarly, for a particular candidate entity \( e_j \), the score \( \Phi_{cl} \) is:

\[
\Phi_{cl}(s_i, e_j) = \Phi_p(s_i) + \Phi_c(s_i, e_j), \tag{5}
\]

\[
\Phi_c(s_i, e_j) = \text{FFNN}_C([g_i; e_j]). \tag{6}
\]

An example graph of mentions and entities with edges for which aforementioned scores \( \Phi_{cl} \) would be calculated is sketched in Fig. 1(a). While simple, this approach fails to correctly solve EL when the correct entity is only present in the candidate lists of mention spans occurring later in the text (since earlier mentions have no access to it).

To solve EL in the general case, even when the first mention does not have the correct entity, we propose bidirectional connections between mentions, thus leading to a maximum spanning tree problem in our Global approach. Here we define a score for a (sub)tree \( t \), noted as \( \Phi_{tr}(t) \):

\[
\Phi_{tr}(t) = \sum_{(u_i, u_j) \in t} \Phi_{cl}(u_i, u_j), \tag{7}
\]

where \( u_i \) and \( u_j \) are two connected nodes (i.e., root, candidate entities or spans) in \( t \). For a ground truth cluster \( c \in C \) (with \( C \) being the set of all such clusters), with its set\(^4\) of correct subtree representations \( T_c \), we model the cluster’s likelihood with its subtree scores. We minimize the negative log-likelihood \( \mathcal{L} \) of all clusters:

\[
\mathcal{L} = -\log \frac{\prod_{c \in C} \sum_{t \in T_c} \exp \left( \Phi_{tr}(t) \right)}{\sum_{t \in T_{all}} \exp \left( \Phi_{tr}(t) \right)}. \tag{8}
\]

Naively enumerating all possible spanning trees (\( T_{all} \) or \( T_c \)) implied by this equation is infeasible, since their number is exponentially large. We use the adapted Kirchoff’s Matrix Tree Theorem (MTT; Koo et al. (2007); Tutte (1984)) to solve this: the sum of the weights of the spanning trees in a directed graph rooted in \( r \) is equal to the determinant of the Laplacian matrix of the graph with the row and column corresponding to \( r \) removed (i.e., the minor of the Laplacian with respect to \( r \)). This way, eq. (8) can be rewritten as

\[
\mathcal{L} = -\log \frac{\prod_{c \in C} \det \left( \mathbf{L}_c(\Phi_{cl}) \right)}{\det \left( \mathbf{L}_r(\Phi_{cl}) \right)} \tag{9}
\]

\(^3\)Measured in number of spans, after pruning.

\(^4\)For a single cluster annotation, indeed it is possible that multiple correct trees can be drawn.
where $\Phi_{cl}$ is the weighted adjacency matrix of the graph, and $L_r$ is the minor of the Laplacian with respect to the root node $r$. An entry in the Laplacian matrix is calculated as

$$L_{i,j} = \begin{cases} \sum_k \exp(\Phi_{cl}(u_k, u_j)) & \text{if } i = j \\ -\exp(\Phi_{cl}(u_i, u_j)) & \text{otherwise} \end{cases}$$

Similarly, $\hat{L}$ is a modified Laplacian matrix where the first row is replaced with the root $r$ selection scores $\Phi_{cl}(r, u_j)$. For clarity, Appendix A presents a toy example with detailed steps to calculate the loss in eq. (9).

To calculate the scores of each of the entries $\Phi_{cl}(u_i, u_j)$ to $\Phi_{cl}$ matrix in eqs. (7) and (9) for Global, we use the same approach as in Local for edges between two mention spans, or between a mention and entity. For the directed edges between the root $r$ and a candidate entity $e_j$ we choose $\Phi_{cl}(r, e_j) = 0$. Since we represent NIL clusters by edges from the mention spans directly to the root, we also need scores for them: we use eq. (3) with $\Phi_{cl}(r) = 0$. We use Edmonds’ algorithm (Edmonds, 1967) for decoding the maximum spanning tree.

### 3 Experimental Setup

We considered two datasets to evaluate our proposed models: DWIE (Zaporojets et al., 2021) and AIDA (Hoffart et al., 2011). Since AIDA essentially does not contain coreference information, we had to extend it by (i) adding missing mention links in order to make annotations consistent on the coreference cluster level, and (ii) annotating NIL coreference clusters. We note this extended dataset as AIDA$^+$. See Table 1 for the details.

As input to our models, for DWIE we generate spans of up to 5 tokens. For each mention span $s_i$, we find candidates from a dictionary of entity surface forms used for hyperlinks in Wikipedia. We then keep the top-16 candidates based on the prior for that surface form, as per Yamada et al. (2016, §3). Each of those candidates $e_j$ is represented using a Wikipedia2Vec embedding $e_j$ (Yamada et al., 2016).5 For AIDA$^+$, we use the spans, entity candidates, and entity representations from Kolitsas et al. (2018).6

To assess the performance of our joint coref+EL models Local and Global, we also provide standalone implementations for coref and EL tasks. The Standalone coref model is trained using only the coreference component of our joint architecture (eq. (2)–(4)), while the EL model is based only on the linking component (eq. (6)).

### 4 Results

Table 2 shows the results of our compared models for EL and coreference resolution tasks. Answering (Q1), we observe a general improvement in performance of our coref+EL joint models (Local and Global) compared to Standalone models? (Q2) Does jointly solving coreference resolution and EL enable more coherent EL predictions? (Q3) How do our joint models perform on hard cases where some individual entity mentions do not have the correct candidate?

| Dataset | # Linked clusters | # NIL clusters | Linked mentions | # NIL mentions |
|---------|------------------|----------------|----------------|---------------|
| DWIE    | 11,967           | 9,935          | 28,482         | 14,891        |
| AIDA    | 16,673           | -              | 27,817         | 7,112         |
| AIDA$^+$| 16,775           | 4,284          | 28,813         | 6,116         |

Table 1: Datasets statistics.
Further analysis reveals that this boost in performance is driven by more coherent predictions on our joint architectures compared to the standalone counterparts. We observe that the difference in performance between our joint models and Standalone is bigger on $M$ clusters (with a consistent superiority of Global), indicating that our approach indeed produces more coherent predictions for mentions that refer to the same concept. Further analysis reveals that this difference in performance is even higher for a more complex scenario where the clusters contain mentions with different surface forms (not shown in the table).

In order to tackle research question (Q3), we study the accuracy of our models on the important corner case that involves mentions without correct entity in their candidate lists. This is illustrated in Table 4, which focuses on such mentions in clusters where at least one mention contains the correct entity in its candidate list. As expected, the Standalone model cannot link such mentions, as it is limited to the local candidate list. In contrast, both our joint approaches can solve some of these cases by using the correct candidates from other mentions in the cluster, with a superior performance of our Global model compared to the Local one.

Table 2: Experimental results (F1 scores defined in §3) using the Standalone coreference and EL models compared to our joint architectures (Local and Global), on DWIE and AIDA$^+$ datasets.

| Setup   | DWIE | AIDA$^+$ | AIDA$_b^+$ |
|---------|------|----------|------------|
|         | EL$_m$ | EL$_h$ | Coref | EL$_m$ | EL$_h$ | Coref | EL$_m$ | EL$_h$ | Coref |
| Standalone | 88.7±0.1 | 78.4±0.2 | 94.5±0.1 | 86.2±0.4 | 80.7±0.5 | 93.8±0.1 | 79.1±0.3 | 74.0±0.3 | 91.5±0.3 |
| Local    | 90.5±0.4 | 83.4±0.4 | 94.4±0.2 | 87.5±0.2 | 83.1±0.2 | 94.7±0.1 | 79.9±0.4 | 75.8±0.3 | 92.3±0.1 |
| Global   | 90.7±0.3 | 83.9±0.5 | 94.7±0.2 | 87.6±0.2 | 83.7±0.3 | 95.1±0.1 | 79.6±0.4 | 76.0±0.4 | 92.2±0.2 |

Table 3: Cluster-based accuracy of link prediction on singletons ($S$) and clusters of multiple mentions ($M$).

| Setup | DWIE | AIDA$^+$ | AIDA$_b^+$ |
|-------|------|----------|------------|
| Standalone | 80.4 | 69.5 | 82.9 | 70.7 | 77.0 | 57.0 |
| Local | 82.6 | 78.6 | 84.9 | 74.8 | 79.8 | 61.4 |
| Global | 82.6 | 80.0 | 85.1 | 76.8 | 79.3 | 63.0 |

Table 4: EL accuracy for corner case mentions where the correct entity is not in the mention’s candidate list.

5 Related Work

Entity Linking: Related work in entity linking (EL) tackles the document-level linking coherence by exploring relations between entities (Kolitsas et al., 2018; Yang et al., 2019; Le and Titov, 2019), or entities and mentions (Le and Titov, 2018). More recently, contextual BERT-driven (Devlin et al., 2019) language models have been used for the EL task (Broscheit, 2019; De Cao et al., 2020, 2021; Yamada et al., 2020) by jointly embedding mentions and entities. In contrast, we explore a cluster-based EL approach where the coherence is achieved on coreferent entity mentions level.

Coreference Resolution: Span-based antecedent-ranking coreference resolution (Lee et al., 2017, 2018) has seen a recent boost by using SpanBERT representations (Xu and Choi, 2020; Joshi et al., 2020; Wu et al., 2020). We extend this approach in our Local joint coref+EL architecture. Furthermore, we rely on Kirchhoff’s Matrix Tree Theorem (Koo et al., 2007; Tutte, 1984) to efficiently train a more expressive spanning tree-based Global method.

Joint EL+Coref: Fahrni and Strube (2012) introduce a more expensive rule-based Integer Linear Programming component to jointly predict coref and EL. Durrett and Klein (2014) jointly train coreference and entity linking without enforcing single-entity per cluster consistency. More recently, Angell et al. (2021); Agarwal et al. (2021) use additional logic to achieve consistent cluster-level entity linking. In contrast, our proposed approach constrains the space of the predicted spanning trees on a structural level (see Fig. 1).

6 Conclusion

We propose two end-to-end models to solve entity linking and coreference resolution tasks in a joint setting. Our joint architectures achieve superior performance compared to the standalone counterparts. Further analysis reveals that this boost in performance is driven by more coherent predictions on
the level of mention clusters (linking to the same entity) and extended candidate entity coverage.

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Figure 2: Illustrative graph example of Global model. The weights of the edges correspond to \(\exp(\Phi_{cl})\) (see eq. (11)).

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A Step by Step Example of MTT Theorem

In this appendix we will provide a clarifying artificial example in order to walk the reader step by step through MTT (eq. (9)–(10)) applied in our Global approach. The graph of the example is illustrated in Fig. 2 and is composed by nodes representing \(root\) \((r)\), entities \(e_1\) and \(e_2\), and spans \(s_1\), \(s_2\) and \(s_3\). The span \(s_2\) is associated with candidate entity set \(\{e_1, e_2\}\) (i.e., represented by edges from \(s_2\) to \(e_1\) and \(e_2\)), and \(s_3\) with \(\{e_2\}\) (i.e., represented by the edge from \(s_3\) to \(e_2\)). The candidate entity set of \(s_1\) is empty. The nodes are grouped in two ground truth clusters: NIL cluster \(c_1 = \{s_1, s_2\}\), and linked cluster \(c_2 = \{e_2, s_2\}\).

The exponential of weighted adjacency matrix\(^7\) \(\Phi_{cl}\) of the presented example is:

\[
\exp(\Phi_{cl}) = \\
\begin{bmatrix}
0 & 1 & 1 & 5 & 3 & 7 \\
1 & 0 & 0 & 0 & 1 & 0 \\
1 & 0 & 0 & 0 & 4 & 2 \\
5 & 0 & 0 & 0 & 5 & 9 \\
3 & 0 & 0 & 0 & 3 & 0 \\
8 & 0 & 0 & 0 & 8 & 0 \\
\end{bmatrix},
\]

\(^7\)For simplicity, the weights are small integers.
where the weights of incorrect edges are represented in red (i.e., red dashed edges in Fig. 2), the weights of the correct edges in green (i.e., green edges in Fig. 2), and the weights between disconnected nodes are set to 0.

In order to compute the denominator of the loss function in eq. (9), the Laplacian of the matrix in eq. (11) is calculated as described in eq. (10), and the row and column corresponding to root \( r \) removed (i.e., the minor \( L_r \) with respect to the root):

\[
L_r = \begin{bmatrix}
e_1 & e_2 & s_1 & s_2 & s_3 \\
e_1 & 1 & 0 & 0 & -1 & 0 \\
e_2 & 0 & 1 & 0 & -4 & -2 \\
s_1 & 0 & 0 & 16 & -5 & -9 \\
s_2 & 0 & 0 & -3 & 17 & -2 \\
s_3 & 0 & 0 & -8 & -4 & 20
\end{bmatrix}.
\] (12)

Following Kirchhoff’s Matrix Tree Theorem (Koo et al., 2007; Tutte, 1984), the determinant of \( L_r \) equals to the sum of the weights of all possible spanning trees of the graph represented in Fig. 2:

\[
det(L_r) = 3600 = \sum_{t \in T_{\text{all}}} \exp(\Phi_{tr}(t)).
\] (13)

In order to compute the numerator of the loss function in eq. (9) (i.e., the sum of the weights of the spanning trees of ground truth clusters), we first mask out (set to zero) all the weights assigned to incorrect edges:

\[
\exp(\Phi_{cl})' = \begin{bmatrix}
r & c_1 & c_2 & s_1 & s_2 & s_3 \\
r & 0 & 1 & 1 & 5 & 0 & 7 \\
c_1 & 0 & 0 & 0 & 0 & 0 & 0 \\
c_2 & 0 & 0 & 0 & 0 & 4 & 0 \\
s_1 & 0 & 0 & 0 & 0 & 0 & 9 \\
s_2 & 0 & 0 & 0 & 0 & 0 & 0 \\
s_3 & 0 & 0 & 0 & 8 & 0 & 0
\end{bmatrix}
\] (14)

Next, the modified Laplacian (i.e., Laplacian with the first row replaced by root \( r \) selection weights) \( \hat{L} \) is calculated for both clusters \( c_1 \) and \( c_2 \):

\[
\hat{L}_{c_1} = \begin{bmatrix}
s_1 & s_3 \\
s_1 & 5 & 7 \\
s_3 & -8 & 9
\end{bmatrix},
\] (15)

\[
\hat{L}_{c_2} = \begin{bmatrix}
e_2 & s_2 \\
e_2 & 1 & 0 \\
s_2 & 0 & 4
\end{bmatrix},
\] (16)

The determinants of \( \hat{L}_{c_1} \) and \( \hat{L}_{c_2} \) equal to the sum of the weights of all spanning trees connecting the nodes in clusters \( c_1 \) and \( c_2 \) respectively:

\[
det(\hat{L}_{c_1}) = 101 = \sum_{t \in T_{c_1}} \exp(\Phi_{tr}(t))
\] (17)

Finally, in order to calculate the final loss, we replace the obtained results in eqs. (13), (17), and (18) in the loss function of eq. (9):

\[
L = -\log \frac{101 \ast 4}{3600}.
\] (19)

Note: strictly speaking, there are three clusters rooted in root in the graph of Fig. 2, the third one being \( c_3 = \{e_1\} \), whose exponential weight is 1 by definition of \( \Phi_{cl}(r, e_j) = 0 \) (see §2.2), and has no impact in calculation of the loss function in eq. (19).