Modeling the nongravitational acceleration during Cassini’s gravitation experiments

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(Dated: September 4, 2014)

In this paper we present a computation of the thermally generated acceleration of the Cassini probe during its solar conjunction experiment, obtained from a model of the spacecraft. We build a thermal model of the vehicle and perform a Monte Carlo simulation to find a thermal acceleration with a main component of $(3.01 \pm 0.33) \times 10^{-9}$ m/s². This result is in close agreement with the estimates of this effect performed through Doppler data analysis.

I. INTRODUCTION

The Cassini mission was launched on October 15th 1997. Its goal was to reach Saturn and also included a set of planned experiments designed to test General Relativity. One of these experiments was carried out from June 6th to July 7th 2002, while the probe was in a solar conjunction. The results from the data harvested during this one month period allowed for constraining the $\gamma$ parameter of the PPN formalism, which quantifies the amount of curvature generated per unit mass, to within $(2.1 \pm 2.3) \times 10^{-5}$ of unity, the most accurate bound obtained so far [1].

During the solar conjunction experiment, the nongravitational acceleration had to be filtered out as well as possible and, in particular, the significant contributions from solar radiation pressure and from anisotropic thermal emission of the probe itself. Due to the unavailability of any straightforward procedure to obtain the said thermal emission from a model of the spacecraft, data from Doppler measurements was used to estimate the component of the acceleration that is constant relative to the spacecraft orientation. The obtained values for the thermally generated acceleration reveal that the largest component is aligned with the Earth-spacecraft axis and amounts to $3 \times 10^{-9}$ m/s² towards the Earth. The other two components are smaller and measured orthogonally to the orbital plane and on the orbital plane, and are found to be about $4 \times 10^{-10}$ m/s² and $1 \times 10^{-10}$ m/s², respectively. These components, however, have large error estimates associated with their determination [1].

The aim of this paper is to consider the problem of obtaining the value of the thermally generated accelerations and directly respond to the stated difficulty in extracting them from a model of the spacecraft itself. It is shown that reliable results can be obtained by using the physical and computational framework previously developed to study the acceleration generated by thermal emissions in the Pioneer 10 and 11 spacecraft, in the context of the problem that became known as the Pioneer anomaly [2–4].

II. POINTLIKE SOURCE METHOD

A. Motivation

The pointlike source method is an approach that maintains a high computational speed and a broad degree of flexibility, allowing for an easy analysis of different contributions and scenarios.

The method was designed to keep all the physical features of the problem at glance and all steps easy to scrutinize. Although it can be argued that this simplicity and transparency was achieved at the expense of accuracy, a battery of test cases can be performed to test the robustness of the results [2,3]. These test cases validate the approach, as they show that, for reasonable assumptions, the possible lack of accuracy caused by our modeling approach is much smaller than the accuracy in the characterization of the acceleration itself.

This method was also designed to consider parameters involving a large degree of uncertainty: this is related to the geometrical and material properties of the various spacecraft elements, which in most cases do not have well-known baseline (before launch) values, and have endured extended periods of degradation in space. By assigning a statistical distribution to each parameter, based on the available information, and generating a large number of random values, we have used a Monte Carlo simulation to obtain a probability distribution for the final result [4].

The fact that this method was already used to deal with spacecraft thermal emissions in the context of the Pioneer anomaly, producing results that are generally in agreement with the ones obtained through subsequent,
more detailed finite-element models \cite{5,6}, is a further indication of its reliability and robustness.

B. Radiative Momentum Transfer

Before considering the particular problem at hand, it is useful to briefly review the physical formulation behind the pointlike source method.

The key feature of this method is a distribution of a small number of carefully placed pointlike radiation sources that models the thermal radiation emissions of the spacecraft. One typically uses Lambertian radiation sources to model surface emissions, however, other types of sources may be used to model particular objects.

All the subsequent formulation of emission and reflection is made in terms of the Poynting vector-field. For instance, the time-averaged Poynting vector-field for a Lambertian source located at \( \mathbf{x}_0 \) is given by

\[
S_{\text{Lamb}}(\mathbf{x}) = \frac{W}{\pi ||\mathbf{x} - \mathbf{x}_0||^2} \left( \mathbf{n} \cdot \frac{\mathbf{x} - \mathbf{x}_0}{||\mathbf{x} - \mathbf{x}_0||}\right) \frac{\mathbf{x} - \mathbf{x}_0}{||\mathbf{x} - \mathbf{x}_0||},
\]

where \( W \) is the emissive power and \( \mathbf{n} \) is the surface normal.

In this work, we introduce a small extension to the pointlike source method to include other radiation source geometries, as long as they have a straightforward mathematical description. An especially useful example is the cylindrical source, where the emitter is a line segment instead of a point and the Poynting vector field has cylindrical symmetry. For instance, the radiation field of a cylindrical source parallel to the \( x \)-axis with coordinates \((y_0, z_0)\) in the \( yz \)-plane is given by

\[
S_{\text{cyl}}(\mathbf{x}) = \frac{W(0, y - y_0, z - z_0)}{2\pi l ((y - y_0)^2 + (z - z_0)^2)},
\]

where \( l \) is the length of the source and \( \mathbf{x} = (x, y, z) \).

The amount of power illuminating a given surface \( W_{\text{ilum}} \) can be obtained by computing the Poynting vector flux through the illuminated surface \( S \), given by the integral

\[
E_{\text{ilum}} = \int_S \mathbf{S} \cdot \mathbf{n}_{\text{ilum}} \, dA,
\]

where \( \mathbf{n}_{\text{ilum}} \) is the normal vector of the illuminated surface.

The absorbed radiation transfers its momentum to the surface yielding a radiation pressure \( p_{\text{rad}} \) given, for an opaque unit surface, by the power flux divided by the speed of light. There is also a radiation pressure on the emitting surface but with its sign reversed. If there is transmission (\( i.e. \), the surface is not opaque) the pressure is multiplied by the absorption coefficient. As to reflection, we shall see in the next two sections that it is treated as a re-emission of a part of the absorbed radiation.

Integrating the radiation pressure on a surface allows us to obtain the force and, dividing by the mass of the spacecraft, the acceleration

\[
a_{\text{ch}} = \frac{1}{m_{\text{Cassini}}} \int_S \mathbf{S} \cdot \mathbf{n}_{\text{ilum}} \frac{\mathbf{S}}{||\mathbf{S}||} \, dA.
\]

The procedure to compute this integration is not always straightforward: to determine the force exerted by the radiation on the emitting surface, the integral should be taken over a closed surface encompassing the latter; equivalently, the force exerted by the radiation on an illuminated surface requires an integration surface that encompasses it. Furthermore, considering a set of emitting and illuminated surfaces implies the proper accounting of the effect of the shadows cast by the various surfaces, which are then subtracted from the estimated force on the emitting surface. One may then read the thermally induced acceleration directly.

C. Reflection Modeling – Phong Shading

The inclusion of reflections in the model is achieved through a method known as Phong Shading, a set of techniques and algorithms commonly used to render the illumination of surfaces in 3D computer graphics \cite{7}.

This method is composed of a reflection model including diffusive and specular reflection, known as Phong reflection model, and an interpolation method for curved surfaces modeled as polygons, known as Phong interpolation.

The Phong reflection model is based on an empirical expression that gives the illumination value of a given point in a surface, \( I_p \), as

\[
I_p = k_a i_a + \sum_{m \in \text{lights}} |k_d (l_m \cdot \mathbf{n}) i_d + k_s (r_m \cdot \mathbf{v})^\alpha i_s|,
\]

where \( k_a, k_d \) and \( k_s \) are the ambient, diffusive and specular reflection constants, \( i_a, i_d \) and \( i_s \) are the respective light source intensities, \( l_m \) is the direction of the light source \( m \), \( \mathbf{n} \) is the surface normal, \( r_m \) is the direction of the reflected ray, \( \mathbf{v} \) is the direction of the observer and \( \alpha \) is a “shininess” constant (the higher it is, the more mirror-like is the surface).

In using this formulation to resolve a physics problem, there are a few constraints that should be taken into account. The ambient light parameter \( k_a \) and \( i_a \), while useful in computer graphics, are not relevant for this problem since they give the reflection behavior relative to a background radiation source. Also, the intensities \( i_d \) and \( i_s \) should be the same, since the diffusive and specular reflection are relative to the same radiation sources.

This method provides a simple and straightforward way to model the various components of reflection, as well as a more accurate accounting of the thermal radiation exchanges between the surfaces on the spacecraft. In principle, there is no difference between the treatment of
infrared radiation, in which we are interested, and visible light, for which the method was originally devised, allowing for a natural wavelength dependence of the above material constants.

Given the presentation of the thermal radiation put forward in subsection III.B, the Phong shading methodology was adapted from a formulation based on intensities (energy per unit surface of the projected emitting surface) to one based on the energy-flux per unit surface (the Poynting vector).

D. Computation of Reflection

Using the formulation outlined in section III.C, the diffuse and specular components of reflection can be separately computed in terms of the Poynting vector-field. The reflected radiation Poynting vector-field for the diffuse component of the reflection is given by

$$S_{rd}(x, x') = \frac{k_d|S(x') \cdot n|}{\pi|x - x'|^2} n \cdot (x - x') \frac{x - x'}{|x - x'|}$$

while the specular component reads

$$S_{rs}(x, x') = \frac{k_s|S(x') \cdot n|}{\pi|x - x'|^2} |\mathbf{r} \cdot (x - x')|^\alpha \frac{x - x'}{|x - x'|}$$

where $x'$ is a point on the reflecting surface. In both cases, the reflected radiation field depends on the incident radiation field $S(x')$ and on the reflection coefficients $k_d$ and $k_s$, respectively. Using Eqs. (6) and (7), one can compute the reflected radiation field by adding up these diffuse and specular components. From the emitted and reflected radiation vector fields, the irradiation of each surface is computed and, from that, a calculation of the force can be performed through Eq. (4).

In the modeling of the actual vehicle, once the radiation source distribution is put in place, the first step is to compute the emitted radiation field and the respective force exerted on the emitting surfaces. This is followed by the determination of which surfaces are illuminated and the computation of the force exerted on those surfaces by the radiation. At this stage, we get a figure for the thermal force without reflections. The reflection radiation field is then computed for each surface and subject to the same steps as the initially emitted radiation field, leading to a determination of thermal force with one reflection.

This method can, in principle, be iteratively extended to as many reflection steps as desired, considering the numerical integration algorithms and available computational power. If deemed necessary, each step can be simplified through a discretization of the reflecting surface into pointlike reflectors.

III. CASSINI THERMAL MODEL

A. Geometric Model

The first step in this analysis is to build a simplified geometric model of the spacecraft that retains only its main features. This procedure has been validated by a set of test cases performed previously in the analysis of the Pioneer space probes, which gave a good indication that the effect of smaller features does not impact the overall determination of the thermal contribution to the acceleration.

In the case of Cassini, this implies the inclusion of the main antenna dish, the spacecraft body composed by a cylindrical lower module, a conical upper module and a prismatic main bus, and the parabolic high-gain antenna.

FIG. 1. Three-dimensional model of Cassini showing the configuration of the RTGs and their covering structures (1), the spacecraft body composed by a cylindrical lower module (2), a conical upper module (3) and a prismatic main bus (4), and the parabolic high-gain antenna (5).
conditions, we get an upper bound on the force of about the thermal radiation from the equipment. Under these This scenario, albeit simplistic, maximizes the effect of do so, we assume that all the electrical power is dissipated with the estimates for the effect of the RTGs. To upper bound for its contribution, so that it can be compared to take this value and assume that 30% of the emissions from the RTG are converted into momentum, providing an order of magnitude for the force, \[ F_{\text{RTG}} \sim 0.3 \frac{W_{\text{RTG}}}{c} \sim 10^{-5} \text{ N}. \] Dividing by the spacecraft mass, which for now is assumed to be on the order of 4600 kg [1], we obtain the expected order of magnitude of the thermal acceleration generated by the RTGs \[ a_{\text{RTG}} \sim 2.2 \times 10^{-9} \text{ m/s}^2. \] When examining the spacecraft body, we can set an upper bound for its contribution, so that it can be compared with the estimates for the effect of the RTGs. To do so, we assume that all the electrical power is dissipated through the bottom wall of the lower compartment. This scenario, albeit simplistic, maximizes the effect of the thermal radiation from the equipment. Under these conditions, we get an upper bound on the force of about \[ F_{\text{equip}} \lesssim \frac{2}{3} \frac{W_{\text{elec}}}{c} \sim 2.2 \times 10^{-6} \text{ N}, \] and, at most, an acceleration of \[ a_{\text{equip}} \lesssim 4.8 \times 10^{-10} \text{ m/s}^2, \] which is below the estimated effect of the RTGs by a factor of 5. We stress that this figure clearly overestimates the effects of thermal radiation from electrical power: a more detailed computation will yield a much smaller figure. This preliminary analysis allows us to conclude that the contribution from the RTGs dominates the thermal acceleration of the Cassini space probe. The obtained order of magnitude also matches the one of the acceleration estimated from the Doppler data.

C. Thermal Radiation Model

Based on the results of the preceding section, we begin by focusing our attention on the contribution of the RTGs. A significant amount of the radiation emitted from the RTGs is illuminating their covers. The geometric model of the illuminated surface is, in this case, quite realistic, as depicted in Fig. 2. The main issue is, then, to obtain the correct distribution of radiation sources that effectively models the emissions of the RTGs.

In order to discern the sensitivity of the result, we built three different models for the RTG: (i) four isotropic sources uniformly distributed along the centerline, (ii) a cylindrical source along the centerline and (iii) 24 Lambertian sources distributed in four rings of six sources each along the lateral surface of the RTG.

The model with four isotropic sources somewhat underestimates the effect, with a deviation of around 20% relative to the other two. This is due to the fact that it has a significant amount of radiation being emitted laterally in what would still be inside the volume of the RTG. Both other models closely reproduce the cylindrical radiation field, with the results for the power illuminating the RTG cover given by both models within 5% of each other, which is clearly within the accuracy goals set for this study. After analyzing and comparing the results from these models, we decided to use the cylindrical source configuration, since it is the one that models the radiation field in a more realistic manner.

The first result to be obtained is the fraction of the power emitted that illuminates the covering structure.
This figure comes in at 28.3%, a part of which is absorbed and the remaining is reflected, depending on the optical properties of the inner surface of the RTG covers. The force computation is made leaving the diffuse and specular reflection coefficients as an open variable to be dealt with later on.

The contributions to the force are labeled according to Table I using the spacecraft part numbering from Fig. 1.

We recall that the Cassini has three RTGs positioned in an asymmetrical configuration. For that reason, we first compute the contribution of a single RTG (for simplicity, we start with the one aligned along the x-axis). Using the reflection modeling described in Section III C and performing the numerical integration, we obtain the force resulting from the emissions of that single RTG

\[
F_{11} = \frac{W_1}{c} \left[ \left( -0.0356 - 0.0204k_{d1} - 0.0466k_{s1} \right) e_x \right.
+ \left. (0.240 + 0.159k_{d1} + 0.193k_{s1})e_z \right],
\]

where \( W_1 \) is the power emitted by the RTG and \( k_{d1} \) and \( k_{s1} \) are the diffuse and specular reflection coefficients of the inner surface of the RTG cover, respectively. In order to obtain the total contribution from the 3 RTGs, we have to add this result to the contribution rotated by 120° and 180° around the spacecraft’s z-axis.

Aside from the RTG contribution, the electric power consumed by the equipment in the spacecraft body also contributes to the thermal acceleration. However, the order of magnitude analysis performed in Section III B shows that, at most, it adds up to around 20% of the contribution of the RTGs. Still, the effect of the top and bottom walls can be significant along the z-axis and deserves some effort in its determination.

When evaluating the emissions from the top wall of the spacecraft main bus, the main surface illuminated is the back of the parabolic high-gain antenna. The emissions from this surface were modeled through a total of 12 Lambertian sources, each one placed at the centroid of each triangular segment of the dodecagon shaped surface.

Integrating along the antenna, we find that 61.1% of the thermal power emitted from the top wall is hitting the antenna. Assuming that the power is evenly distributed along the surface, the radial components of the source cancels out, leaving only an axial contribution of

\[
F_{45} = \frac{W_4}{c} \left( \frac{2}{3} + 0.492 + 0.387k_{d5} + 0.236k_{s5} \right) e_z,
\]

where \( W_4 \) is the power emitted from the top wall, \( k_{d5} \) is the diffusive reflection coefficient of the antenna and \( k_{s5} \) is its specular reflection coefficient.

It should be noted that both the inner wall of the umbrellas and the lower surface of the antenna are modeled with a low shininess constant, \( \alpha = 3 \) (cf. Eq. (7)), since these are unpolished surfaces.

Any amount of power emitted from the bottom wall yields a direct contribution to the acceleration along the z-axis, since it does not illuminate any other surface. Considering that it is a Lambertian emitter, if \( W_2 \) is the power emitted from the bottom wall, then its contribution to the force is

\[
F_2 = \frac{2W_2}{3c}e_z,
\]

Given the available information, there is no way to obtain any detailed distribution of the thermal emissions on the lateral walls of the main body of the spacecraft. In any case, such contribution should be very small, since the body has an approximately cylindrical shape and the multilayer insulation blanket tends to even out the temperatures, making the radial radiation field from the spacecraft body approximately symmetric. For this reason, we focus our attention mainly on the component of the acceleration along the Earth-spacecraft axis, while attempting to get a rough estimate of the other component based entirely on the effect of the RTGs.

D. Power Supply

The amount of power available on board is of crucial importance for the outcome: the Cassini probe is powered by a set of three large plutonium RTGs; at launch, the RTGs generated around 13 kW of total thermal power, from which 878 W of electrical power were produced. Since the plutonium decays with a half-life of 87.7 years, the total thermal power \( W_{\text{Total}} \) will decrease at approximately the same rate.

The electrical power generated from the RTGs by a set of thermocouples decreases at a greater rate, due to the decay in the conversion efficiency. This rate of decay can be fitted by an exponential law with a half-life of approximately 21.2 years [8]. Taking these combined effects into account, the time evolution of the electrical power is given by

\[
W_{\text{elec}}(t) = 878e^{-\frac{t}{21.2}}e^{-\frac{t}{87.7}} \text{ W} = 878e^{-\frac{t}{21.2}} \text{ W},
\]

with \( t \) in years, thus yielding a combined half-life of 17.1 years.

In order to maintain the overall balance of the spacecraft energy, we assume that the thermal power dissipated at the RTGs results from the difference between total thermal power and the electrical power generated, since the latter will be used to power the array of equipment carried in the spacecraft body,

\[
W_{\text{RTG}}(t) = W_{\text{Total}}(t) - W_{\text{elec}}(t).
\]

In this study, we are looking at a very specific period of time, during which the gravitational experiment was performed. As mentioned in the introduction, this corresponds roughly to the month of June 2002, that is, four years and nine months after launch. Given this short time frame, Eq. (15) shows a decrease of only 0.34%, so that
we can reasonably take the power as constant. Inserting $t = 4.75$ years into Eq. (15) we obtain the reference values for the available power

$$W_{\text{Total}} = 12521 \text{ W}, \quad W_{\text{elec}} = 724 \text{ W}, \quad W_{\text{RTG}} = 11797 \text{ W}.$$ (17)

IV. RESULTS AND DISCUSSION

A. Baseline Scenarios

In order to acquire some sensitivity on the influence of the different parameters, prior to a more thorough statistical analysis, we set out a number of scenarios. We consider the spacecraft mass as $m_{\text{Cassini}} = 4591 \text{ kg}$ [9].

The simplest possible scenario, keeping in mind that the RTG contribution is expected to be the dominant one, is to simply consider their effect without reflection on the covers. This means that all power is absorbed and reemitted with the structure at a constant temperature. This means that all the power would be dissipated through the covers. This hypothesis yields an acceleration of

$$a_{\text{Scn 3}} = (-8.65e_x - 15.0e_y + 337e_z) \times 10^{-11} \text{ m/s}^2.$$ (20)

If we add to the previous conditions, the upper bound for the contribution from the electrical equipment, meaning that all the power would be dissipated through the lower wall, we get a slightly larger acceleration on the z-axis,

$$a_{\text{Scn 4}} = (-8.65e_x - 15.0e_y + 372e_z) \times 10^{-11} \text{ m/s}^2.$$ (21)

This scenario gives us the upper limit for the overall acceleration given by our model.

A more reasonable scenario, is to take the second one considered above, using the reflection coefficients of 0.4 and 0.1, and add to it a contribution from the spacecraft body that assumes that power is dissipated uniformly through all the surfaces. The MLI blanket covering the spacecraft body has the effect of evening out major temperature differences along the probe’s structure, making this hypothesis reasonable. This scenario yields a small increase in the z component of the acceleration relative to Eq. (19),

$$a_{\text{Scn 5}} = (-6.87e_x - 11.9e_y + 272e_z) \times 10^{-11} \text{ m/s}^2.$$ (22)

This last set of hypotheses represents the baseline for the parametric study that follows in the next section. Notwithstanding, we can already point out that the $z$ component is remarkably close to the value of $3 \times 10^{-9} \text{ m/s}^2$, reported through the Doppler analysis [1].

The results from all the considered scenarios are summarized in Table 1.

The off-axis components, however, remain about one order of magnitude below the values reported in Ref. [1] — although the latter are quite unreliable, as the authors themselves point out. Furthermore, those values are presented relative to the orbital plane, whereas the results of the thermal analysis correspond to the spacecraft reference frame.

One could speculate that this difference is due to the rotation between a reference with the $z$ axis along the axis of the high-gain antenna and one with the $z$ axis on the orbital plane. A simple calculation, hypothesizing that the antenna is pointing directly towards the Earth can be performed using data from the Cassini, Galileo, and Voyager ephemeris tool [11]; during the solar conjunction experiment, the angle between the two reference frames would be between $1.6^\circ$ and $1.8^\circ$. The projection of the $z$

### Table I. Labeling of the considered contributions to the Cassini thermal acceleration.

| Emitting surface | Reflecting surface | Label |
|------------------|--------------------|-------|
| RTGs            | RTG covers         | $F_{11}$ |
| Main Bus upper wall | High-gain antenna back wall | $F_{15}$ |
| Lower module bottom wall | none | $F_2$ |


TABLE II. Summary of assumptions and results from baseline scenarios, where \( W_{\text{bottom}} \) and \( W_{\text{top}} \) are the emitted powers from the bottom wall of the lower module and the top wall of the main bus, respectively; \( k_{d,\text{umb}} \) and \( k_{s,\text{umb}} \) are the RTG umbrella reflection coefficients, and \( a_x \), \( a_y \) and \( a_z \) are the components of the resulting thermal acceleration.

| Scenario                        | \( W_{\text{bottom}} \) (W) | \( W_{\text{top}} \) (W) | \( k_{d,\text{umb}} \) | \( k_{s,\text{umb}} \) | \( a_x \times 10^{-11} \text{m/s}^2 \) | \( a_y \times 10^{-11} \text{m/s}^2 \) | \( a_z \times 10^{-11} \text{m/s}^2 \) |
|--------------------------------|-----------------|-----------------|----------------|----------------|----------------|----------------|----------------|
| 1. RTGs, no reflection         | 0               | 0               | 0              | 0              | -5.09          | -8.81          | 200            |
| 2. RTGs, low reflection        | 0               | 0               | 0.4            | 0.1            | -6.87          | -11.9          | 269            |
| 3. RTGs, high reflection       | 0               | 0               | 0.8            | 0.2            | -8.65          | -15.0          | 337            |
| 4. Upper bound                 | 724             | 0               | 0.8            | 0.2            | -8.65          | -15.0          | 372            |
| 5. Scenario 2 + body uniform temp. | 47.2           | 121             | 0.4            | 0.1            | -6.87          | -11.9          | 272            |

component of the acceleration on the spacecraft frame on a direction orthogonal to the orbital plane would result in an acceleration component close to \( 10^{-10} \text{m/s}^2 \), which would agree with the order of magnitude of the Doppler measurements.

In the absence of more complete information on the methods used to obtain the Doppler estimates and the spacecraft orientation during the time of the experiment, it is not possible to make any definite assertions about the off-axis components of the acceleration.

B. Parametric Analysis

We now proceed to the statistical analysis based on a Monte Carlo simulation. We focus this analysis only on the \( z \) component of the acceleration, since there is not enough information to properly constrain the relevant parameters for the off-axis component and, as discussed above, the results would not be reliable enough to draw any conclusions.

In the Monte Carlo method, a large number of random values associated with a statistical distribution are generated for each of the relevant parameters that influence the final result. This type of analysis turned out to be quite valuable for the Pioneer anomaly problem [4].

The reflection coefficients of the RTG umbrellas can be reasonably constrained, as discussed in the preceding section, since we have some reliable data on the material and its properties [10]. This enables us to use a Normal distribution for the diffusive reflection coefficient, centered at a conservative estimate of 0.6 and with a \( \sigma \) of 0.1, allowing for a variation between 0.4 and 0.8 within 2\( \sigma \). For all other parameters, we use uniform distributions with a reasonably wide interval in order to account for the lack of accurate and reliable data. The assumptions used to generate the random values for the simulation are outline in Table III.

Running a simulation with \( 10^5 \) iterations, we obtain the probability density distribution depicted in Fig. 3. The distribution is approximately normal. The mean of the resulting distribution is \( 3.01 \times 10^{-9} \text{m/s}^2 \), with a standard deviation of \( 1.63 \times 10^{-10} \text{m/s}^2 \). The acceleration along the Earth-spacecraft axis, with an uncertainty interval of 2\( \sigma \), is

\[
(a_{\text{Cassini}})_z = (3.01 \pm 0.33) \times 10^{-9} \text{m/s}^2. \tag{23}
\]

From this analysis, we can conclude that the value for the thermal acceleration given by this model of the Cassini spacecraft is in agreement with the value obtained from the Doppler data, up to a 95% probability level.

V. CONCLUSIONS

The results found in this study for the thermally generated acceleration of the Cassini space probe during its solar conjunction experiment significantly reinforce our confidence in the method first developed to account for the Pioneer anomaly [4]. The adaptability of this approach allowed its application to an entirely new problem, with a different geometry, material properties and set of hypotheses, upholding the transparency and the simplicity of the method.

Clearly, some open questions still remain. The off-axis components of the acceleration are still poorly known. More detailed information about the internal power consumption and the attitude of the probe would be needed...
### TABLE III. Assumptions used to generate input parameter values for Monte Carlo simulation.

| Parameter                              | Symbol          | Distribution                              |
|----------------------------------------|-----------------|-------------------------------------------|
| Diffusive reflection coeff. of umbrella| $k_{d,\, umbr}$ | Normal distribution with $\mu = 0.6$ and $\sigma = 0.1$ |
| Specular reflection coeff. of umbrella  | $k_{s,\, umbr}$ | Uniform distribution with interval [0, 0.2] |
| Diffusive reflection coeff. of antenna back | $k_{d,\, ant}$ | Uniform distribution with interval [0, 0.6] |
| Specular reflection coeff. of antenna back | $k_{s,\, ant}$ | Uniform distribution with interval [0, 0.2] |
| Power emitted from top of main bus     | $W_{top}$       | Uniform distribution with interval [0, 94.4] W |
| Power emitted from bottom of lower module | $W_{bottom}$   | Uniform distribution with interval [0, 242] W |

to properly address this issue. However, the result for the main component of the acceleration, along the probe’s $z$ axis, gives a very compelling result that closely agrees with the estimates of the non-gravitational acceleration presented in Ref. [1].

The results presented in this paper significantly boost the confidence in one of the most accurate experiments ever performed to test General Relativity.

**ACKNOWLEDGMENTS**

The work of FF is sponsored by the FCT – Fundação para a Ciência e Tecnologia (Portuguese Agency), under the grant BD 66189/2009.

The work of OB and JP is partially supported by the FCT grant PTDC/FIS/111362/2009.

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