Acoustic location of conspecifics in a nocturnal bird: the corncrake *Crex crex*

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**Abstract** Although the use of sounds in spatial orientation is widespread among animals, only a few groups advanced such specific adaptations as echolocation. In contrast, practically all animals and night-active species in particular, must occasionally orient themselves relative to invisible but audible objects such as a hidden rival or predator. In this study, I would like to determine the impact of locating which involves the use of acoustic parameters of sender’s vocalisations by receivers and changes of positions and triangulation of sender’s vocalisations by receivers in estimating the distance to the sender during night-time territorial interactions of the corncrake (*Crex crex*). Males were subjected to two kinds of stimuli: approaching one, imitating the change of the distance of the calling intruder toward the focal male while keeping the direction constant, or stationary stimuli, involving acoustic stimulation with no motion. Although males subjected to approaching stimulation moved longer distances, in both stimuli groups, males moved predominantly toward or out of the playback speaker, and only occasionally made sideway movements. However, the results gave no evidence of corncrakes moving specifically in order to locate the source of the sound; they suggest that males moved toward or away from the already located sound. The fact that males moved longer distances in response to approaching than stationary stimuli indicates that they were able to perceive the change of the distance to the playback speaker based only on structural parameters or amplitude of the calls played.

**Keywords** Sound location · Triangulation · Distance assessment · Corncrake · *Crex crex*

**Introduction**

Spatial orientation is based on integration of information collected from the surrounding environment with the use of senses. In birds, vision is of primary importance; however, other senses can also play important role (Ioalé et al. 1990; Walcott 1996; Witten et al. 2010), and the actual hierarchy of cues appears to depend strongly on the spatial scale. Generally, birds are not well adapted to conditions of zero visibility and except for some cave-dwelling oilbirds and swiftlets, which have evolved some rudimentary echolocation (Jordan Price et al. 2004), and owls, which position acoustic signals with great accuracy (Knudsen et al. 1979; Konishi 2003), the ability of birds to use sounds to locate objects does not rival that of the bats or dolphins. Nevertheless, birds must sometimes orient relative to invisible acoustic objects such as a hidden rival or predator.

There are many mechanisms enabling the listener to estimate both the direction and distance to the source of the sound. The direction is relatively easy to assess by the listener having two ears because the sound intensity difference and arrival time or sound wave phase difference that occur at two ears act as cues that enable the listener to perceive the direction of the source of the sound (Makita 1962). Many bird species mastered passive acoustic location to perfection, with owls being the most specialised birds for hearing (Coles and Guppy 1988). By contrast, the estimation of the distance to the source of the sound is more complicated, mostly because it is strongly affected by local conditions and the acoustic structure of sounds transmitted through the environment (Brumm and Naguib 2009). The most obvious distance cue appears to be the sound amplitude; however, except for the distance, amplitude depends strongly on the degree of sender’s arousal (Brumm and Ritschard 2011), the so-called Lombard effect (Brumm and Zollinger 2011) and the directionality of the sound (i.e. direction towards which the singer is facing). Hence, it is questionable that birds actually use...
amplitude as the principal ranging cue. But birds can use other cues that change predictably with transmission distance, particularly the accumulation of reverberations and frequency-dependent attenuation (Waas 1991; Naguib 1995; Naguib et al. 2000; Naguib and Wiley 2001; Marler 2004; Slabbekoorn 2004). Finally, it is possible for birds to measure the distance to the auditory stimuli actively by triangulation, that is by measuring the direction to the stimuli from at least two different locations and when the distance is too long for triangulation only based on the simultaneous use of two ears. Nevertheless, this possibility has not been tested so far. The main objective of this study is to determine the impact of passive (with the use acoustic parameters of vocalisations) and active (involving movements and triangulation) sound location in estimating the distance to the sender in light- limited conditions. This objective was achieved with the experiment based on social interactions of the corncrake (*Crex crex*) males.

The corncrake is a typical cryptic rale species, active mostly during the night. Males communicate intensively using repetitious cracking calls, characterised by high amplitude and long range. They interact vocally with each other in communication networks consisting of several individuals (1–20). Such system appears to be an example of an exploded lek (Alonso et al. 2012), in which information exchange among males is almost restricted to the auditory channel. At the same time, such interactions are almost two dimensional because males inhabit low vegetation and fly with reluctance. Therefore, the corncrake is a very suitable subject for studying the location of a sound source based solely on acoustic cues.

The concept of the experiment was based on testing the impact of the distance and direction cues on the movements of birds separately with the use of either approaching or stationary stimuli. The function of the approaching stimulation was to imitate the change of the distance of the intruder male to the focal male (movement toward the male) while keeping the direction to the intruder constant (no sideways movements), whereas trials with stationary stimuli functioned as control group in which both the distance and angle were constant. Generally, intrusion by itself initiates aggressive responses or retreats by territory owners but the nature of the response depends on the risk assessment. Distance to the intruder is a crucial risk assessment factor (Waas 1991). Consequently, I assumed that the first reaction of the focal male is the assessment of the distance to the playback speaker (risk assessment). This could be achieved either by the assessment of structural parameters of calls, which could change only with distance (calling samples were homogenous with this respect), or by active movements by the focal male. Approaching stimulation manipulated the distance and so it must have affected the structural parameters of calls, which could be useful in the distance assessment. However, approaching stimulation did not affect the direction to the sound source. Therefore, if subjects respond with forward or backward movements (proxies of attack and retreat), it might suggest that they assessed the distance primarily based on structural parameters of calls or the change in the call amplitude. In contrast, if subjects respond with sideways movements, it might suggest that males required several independent measurements of different angles to the speaker to assess the distance reliably, and that the information from structural parameters of calls or the change in the call amplitude is insufficient.

**Materials and methods**

**Study site and species**

Experiments were conducted in the Upper Nurzec River Valley in Northeast Poland (centre of the study area: 23°14′ E and 52°36′ N) May 21 and June 6, 2012, between 2200 and 0215 hours local times. The test subjects were 70 territorial corncrake males randomly selected from larger populations.

**Call stimuli, stimuli groups and experimental protocol**

To prepare call stimuli, I used a total of \( n = 70 \) 20-s-long samples of corncrake’s natural broadcast calls recorded from different males in 2007–2008 in Kampinoski NP in Poland and digitised using the Avisoft SASLab Pro 4.52 sound analysis package (48 kHz/16 bit PCM files). All calls were digitally prepared to match a 96±5-dB signal pressure level (sound pressure level [SPL] at 1 m) (natural level: mean: 96 dB, range 80–101 dB) and randomly assigned to two stimuli groups: with approaching and stationary stimuli. SPL(A) was measured with a CHY 650 (Ningbo, China) sound pressure level meter. For recording of samples, Sennheiser ME 62 microphones (frequency response: 150–15,000 Hz, ±2 dB) recording to an Edirol R-4 Pro Portable Recorder and Wave Editor (Hamamatsu, Japan) were used. Call samples used in both stimuli groups were recorded from similar distances (stationary stimuli: mean ± SE = 13.3±1.1 m; approaching stimuli: mean ± SE = 14.4±0.9 m; test: \( t = 0.48, df = 68, P = 0.634 \)) and in similar field and weather conditions. Therefore, although experimental males listened to sounds affected to some degree by transmission through environment, sound transmission could not have differential effect on males’ responses in both stimuli groups.

Before each trial, the loudspeaker was placed < 0.5 m above the ground, within the subject male’s territory. During trials with approaching stimuli, the playback speaker was carried by the researcher toward the male. The approaching stimulation started immediately after the beginning of the
playback and continued slowly directly toward the focal male until the end of the playback. The change of the distance was set not to exceed 4 m. Such a change made a considerable though a small fraction of the initial distance of a male to the speaker (see “Results”), and it was chosen because of two reasons. Firstly, to minimise the deterrent effect of the intrusion itself. Because after the stimulation the speaker was still far away from a male, the movement itself could increase the concentration of a male rather that to threaten it. Secondly, to provide listeners with a considerable change in sound amplitude. During stationary trials, playback speaker was motionless throughout the trials; however, the person was standing close by. Because corncrakes call from within dense vegetation during the night, it was very unlikely for the males to see the researcher.

Data collection and analysis

For the playback experiments, I used a Creative ZEN player (quality of files: PCM, 48,000 Hz, 16 bits) with a wireless SEKAKU WA-320 (Taichung, ROC Taiwan) loudspeaker with 20 W amplifier and 50–15,000 Hz frequency range. All of the experiments were conducted within an Acoustic Location System, which consisted of an array of four omnidirectional microphones (Sennheiser K6/ME 62) recording to an Edirol R-4 Pro 4-channel Portable Recorder and Wave Editor (Hamamatsu, Japan). I used the acoustic locator algorithm in XBAT (v. 0.6.1, Cornell Lab of Ornithology) to determine the position of focal subjects within the microphone array. Microphones were fixed at 1.5 m above the ground.

I measured the position of the focal male relative to the playback speaker continuously, having started right before the playback started and finished 10 s after the playback finished (30 s altogether). From this data set, I chose two positions defining the first movement of each male: the first one from before the playback started and the second one collected right after a male moved and stopped. Because corncrakes stop calling while moving, the choice of the second position was straightforward. Consequently, the change of the position between the first and second measurements was always the first movement, regardless of the number of movement recorded and the total distance covered by a male during the mentioned 30 s.

Considering these positions, I calculated the angle of the first movement relative to the speaker (0°). Next, I categorised the angles into three classes: forward (between 315° and 45°), backward (between 135° and 225°) and sideways (between 45° and 135° or 225° and 315°) movements. However, for simplicity, I transformed the angles 180°–360° into the corresponding 0°–180° angles.

For statistical analyses, I used both parametric (t test and F test (ANOVA)) and nonparametric (Mann–Whitney test, Kruskal–Wallis test and χ² test with Yates correction for continuity) tests when data deviated from normality. I tested each variable for normality of distribution using the Shapiro–Wilk test. The variables distance of first reaction and initial distance of a male to the speaker were log-transformed. All P values are two tailed.

Results

Although males from both stimuli groups had similar distances to the speaker before the experiment (stationary stimuli: mean ± SE = 33.96±2.24 m; approaching stimuli: mean ± SE = 31.78±2.64 m; t = −1.24, df = 68, P = 0.219), males subjected to approaching stimuli moved longer distances than males subjected to stationary stimuli (Fig. 1; t = 2.36, df = 68, P = 0.021). Nevertheless, the angle between the initial position and the position after the first reaction was small in both groups (stationary stimuli: Q25/median/Q75=0.18/0.44/1.92°; approaching stimuli: Q25/median/Q75=0.19/0.64/2.23°; Mann–Whitney test: U=503.0, P=0.544). Consequently, a majority of males either moved toward or away from the playback speaker and only 11 % of males in both stimuli groups moved sideways (Fig. 2). Assuming equal likelihood of moving sideways and forward or backward (0.5 vs. 0.5), this difference was very unlikely to happen by chance (<0.001).

Fig. 1 Responses of focal males to two types of stimuli: with both acoustic and moving stimuli (approaching stimuli) and only with acoustic stimuli (stationary stimuli). The boxes show mean (±SE) distances. In this graph, movements were included independent of their direction. Distance of first reaction was calculated measuring the distance between the position from before the playback started and the position measured right after a male moved for the first time and stopped (see “Materials and methods” for more details)
Males categorised as responding with forward, backward and sideway movements had similar initial distances to the speaker (forward: mean±SE = 32.99±2.56 m, backward: mean±SE = 31.41±3.34 m, sideways: mean ± SE = 33.45±5.56 m; Kruskal–Wallis test: $H=1.29$, $P=0.526$), and the difference between the numbers of males with forward or backward and sideway responses in both stimuli groups was not significant (Fig. 2; $\chi^2=0.36$, $df=1$, $P=0.549$). Therefore, the significantly lower number of males moving sideways neither could result from initial conditions nor from the effect of the stimuli themselves.

**Discussion**

Relatively small number of males making sideway movements compared with predominating forward and backward movements suggests that corncrakes did not move specifically in order to locate the source of the sound but that they moved toward or away from the already located sound. Because such an effect was independent of the stimulus, it might be concluded that corncrakes were not able to estimate or did not pay attention to the distance to the speaker. Nevertheless, the fact that males moved longer distances in response to approaching than stationary stimuli indicates they were able to perceive the change of the distance to the playback speaker based only on structural parameters or the amplitude of the calls played. This proves that males did pay attention to the distance per se. At the same time, the results gave no evidence for the active localisation. To justify these conclusions, they should be referred to both the general mechanisms of spatial imagination in birds as well as the specificity of the mating system of the corncrake.

Many types of birds’ vocalisations appear to have acoustic structures adjusted specifically to the positioning of the sender (McGregor and Falls 1984; McGregor and Krebs 1984; Holland et al. 1998, 2001). Such a function is relatively well fulfilled by, so-called, broadcast signals, i.e. all kinds of territorial songs or calls directed to both males and females. Various parameters of broadcast signals change predictably during transmission through environment, providing receivers with better or worse estimates of the distance to the sender. Vocalisations characterised by wide frequency spectra and strong modulation of amplitude or frequency provide receivers with the best distance assessment cues (Naguib and Wiley 2001). Because higher frequencies are attenuated faster than lower ones, vocalisations received after longer transmission have narrower and lower frequency spectra than those received after shorter transmission. Similarly, modulated signals are prone to smear and extend with distance, which modify their structure: creates energy tails, fill in pauses and selectively attenuates or amplifies some frequencies (Slabbekoorn 2004). All these changes can provide listeners with relatively accurate information about the distance to the sender. At the other extreme, there are alarm calls with acoustic structures making them hard to locate (Klump et al. 1986; McGregor and Dabelsteen 1996). Such vocalisations, as might be predicted, have narrow frequency spectra and lack modulation (Kumar 2004; Marler 2004). Territorial call of the corncrake looks like a textbook example of the sound from the first group: it has wide-frequency spectrum and pulsating amplitude-modulated structure (Ręk and Osiejuk 2011). Besides, it is produced in long series, which minimises the error of measurements. Consequently, it appears that the structure of corncrake’s broadcast calls provides listeners with a satisfactory set of distance assessment cues, without the need to fall back on the more time-consuming techniques of active localisation.

The acoustic communication of the corncrake takes place in complex communication networks, consisting of several to even 20 simultaneously singing males. As in all territorial animals, it is crucial for corncrake males to keep at bay, and
the distances among males are seldom smaller than 100 m. Therefore, the precision of localisation seems not to be of the highest importance. Nevertheless, in conditions of extremely low visibility, vocalisations of the corncrake must play an especially important social role, limiting the frequency of territorial conflicts and facilitating mutual localisation. A male surrounded by a group of singing and known rivals should have satisfactory spatial information to orientate himself relative to other males and to detect potential reshuffles. It cannot be excluded, however, that corncrakes facilitate this process using calls of neighbours with known location as the acoustic background with points of reference for measuring changes in the distances. Such a process would be based on the assessment of quantitative relationships between the same acoustic parameters coming from different sources. Nevertheless, except for the studies on owls that evolved some anatomic adaptations (Moiseff 1989), we still know very little about mechanisms of sound location in nocturnal birds.

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