ON RUNGE PAIRS AND TOPOLOGY OF AXIALLY
SYMMETRIC DOMAINS

CINZIA BISI & JÖRG WINKELMANN

ABSTRACT. We prove a Runge theorem for and describe the ho-
monology of axially symmetric open subsets of $\mathbb{H}$.

1. Introduction

Approximation theory plays a fundamental role in complex analy-
sis, holomorphic dynamics, the theory of minimal surfaces in Euclidean
spaces and in many other related fields of mathematics. In this paper,
our goal is to study quaternionic analogs of the classical complex Runge
theory, in particular analogs of the classical topological characteriza-
tion of domains in the complex plane on which holomorphic functions
may be approximated by entire functions. We recall that the classi-
cal theory of holomorphic approximation started in 19th century with
the amazing results of Runge and Weierstrass (1885) and continued in
the 20th century with the work of Oka and Weil, Mergelyan, Vituskin
and others: here we prove the analog of Behnke and Stein theorem
in the more modern quaternionic setting, hoping that this paper will
bring a new stimulus for future developments in this important area of
mathematics.

Throughout this paper the integers, real, complex and quaternionic
numbers are denoted by $\mathbb{Z}$, $\mathbb{R}$, $\mathbb{C}$ and $\mathbb{H}$ respectively. We recall that
$\mathbb{H}$ is a skew field, a four-dimensional associative $\mathbb{R}$-algebra with basis
1, $I$, $J$, $K$ subject to the rules $I^2 = J^2 = K^2 = -1$, $IJ +JI = IK +$ $KI = KJ + JK = 0$, $IJK = -1$.

The set of imaginary units $\mathbb{S} = \{q \in \mathbb{H} : q^2 = -1\}$ is a real two-
dimensional sphere, because

$$\mathbb{S} = \{xI + yJ + zK : x^2 + y^2 + z^2 = 1\}.$$  

Our goal is to study (slice) regular functions on domains in $\mathbb{H}$ which
are the analog of holomorphic functions on $\mathbb{C}$.

2020 Mathematics Subject Classification. 30G35.

The two authors were partially supported by GNSAGA of INdAM. C. Bisi was
also partially supported by PRIN Varietà reali e complesse: geometria, topologia e
analisi armonica.
Definition 1.1. Let $\Omega$ be an open subset of $\mathbb{H}$ with $\Omega \cap \mathbb{R} \neq \{\}$. A real differentiable function $f : \Omega \to \mathbb{H}$ is said to be (slice) regular if, $\forall I \in S$, its restriction $f_I$ to the complex line $C_I = \mathbb{R} + \mathbb{R}I$ passing through the origin and containing 1 and $I$ is holomorphic on $\Omega \cap C_I$.

This notion was introduced by Gentili and Struppa [17, 18].

For a ball in $\mathbb{H}$ centered at the origin regularity is the same as the condition that the function can be represented by a convergent power series

$$f(q) = \sum_{k=0}^{\infty} q^k a_k.$$ 

In the last decade the theory of slice regular functions has been investigated in many directions, see, as samples, the papers [4], [5], [6], [7], [8], [9], [2], [1], [10], [11].

In this article, we call an open subset $D \subset \mathbb{C}$ symmetric if it is invariant under complex conjugation. An open subset $\Omega \subset \mathbb{H}$ is called axially symmetric if it is invariant under all $\mathbb{R}$-algebra automorphisms of $\mathbb{H}$. This is equivalent to the condition that for any $x, y \in \mathbb{R}$, $I, J \in S$ the condition $x + yI \in \Omega$ holds if and only if $x + yJ \in \Omega$.

There is a one-to-one correspondence between symmetric open subsets $D \subset \mathbb{C}$ and axially symmetric open subsets $\Omega_D \subset \mathbb{H}$ which may be described as follows.

Given an axially symmetric open subset $\Omega \subset \mathbb{H}$, we may choose an element $I \in S$ and define $D \subset \mathbb{C}$ as

$$D = \{x + yi : x + yI \in \Omega, x, y \in \mathbb{R}\}.$$ 

Conversely, given a symmetric open subset $D \subset \mathbb{C}$, we define the corresponding axially symmetric subset $\Omega \subset \mathbb{H}$ (which we often denote as $\Omega_D$) via

$$\Omega = \{x + yI : I \in S, x, y \in \mathbb{R}, x + yi \in D\}.$$ 

Let $D$ be a symmetric open subset of $\mathbb{C}$. Then a “stem function” on $D$ is a holomorphic function $F : D \to \mathbb{H} \otimes_{\mathbb{R}} \mathbb{C}$ such that $F(z) = \overline{F(z)}$ for all $z \in D$. Here “holomorphic” is to be understood with respect to the complex structure on $\mathbb{H} \otimes_{\mathbb{R}} \mathbb{C}$ induced by the complex structure on the second factor of the tensor product.

Given a symmetric open subset $D \subset \mathbb{C}$ with $D \cap \mathbb{R} \neq \{\}$ and its associated axially symmetric open subset $\Omega_D$ we have a one-to-one correspondence between slice regular functions on $\Omega_D$ and “stem functions on $D$”.

Given a stem function $F : D \to \mathbb{H} \otimes_{\mathbb{R}} \mathbb{C}$, we write $F$ as

$$F(z) = F_1(z) \otimes 1 + F_2(z) \otimes i.$$
with $F_i : D \to \mathbb{H}$ and define

$$f(x + yI) = F_1(x + yi) + IF_2(x + yi) \quad (x, y \in \mathbb{R}, I \in \mathbb{S})$$

Conversely, given $f : \Omega \to \mathbb{H}$, we fix an element $I \in \mathbb{S}$ and define

$$F_1(x + yi) = \frac{1}{2} (f(x + yI) + f(x - yI))$$

$$F_2(x + yi) = -I\frac{1}{2} (f(x + yI) - f(x - yI))$$

It can be shown (using the “representation formula”) that the $F_i$ are independent of the choice of $I$, see [16].

For arbitrary axially symmetric domains in $\mathbb{H}$ (for which the intersection with the real axis may be empty) we use the definition below.

**Definition 1.2.** Let $D$ be a symmetric domain in $\mathbb{C}$ and let $\Omega_D$ be its associated axially symmetric domain in $\mathbb{H}$, i.e.,

$$\Omega_D = \{ x + yJ : x, y \in \mathbb{R}, J \in \mathbb{S}, x + yI \in D \}$$

A function $f : \Omega_D \to \mathbb{H}$ is regular if it is induced by a holomorphic stem function $F : D \to \mathbb{H} \otimes \mathbb{R} \mathbb{C}$.

Our main result is the following:

**Theorem 1.3.** Let $D \subset D_1$ be symmetric open subsets of $\mathbb{C}$ and let $\Omega_D \subset \Omega_{D_1}$ be the corresponding axially symmetric open subsets in $\mathbb{H}$.

Then the following are equivalent:

(i) $D \subset D_1$ is a Runge pair, i.e., every holomorphic function on $D$ can be approximated by holomorphic functions on $D_1$ (uniformly on compact sets).

(ii) $\Omega_D$ is Runge in $\Omega_{D_1}$ in the sense that every regular function on $\Omega_D$ can be approximated (uniformly on compact sets) by regular functions on $\Omega_{D_1}$.

(iii) $i_* : H_1(D) \to H_1(D_1)$ is injective, where $i_*$ denotes the homology group homomorphism induced by the inclusion map $i : D \to D_1$.

(iv) $i_* : H_k(\Omega_D) \to H_k(\Omega_{D_1})$ is injective for $k \in \{1, 3\}$ where $i_*$ is the homomorphism induced by the inclusion map $i : \Omega_D \to \Omega_{D_1}$.

(v) Every bounded connected component of $\mathbb{C} \setminus D$ intersects $\mathbb{C} \setminus D_1$.

(vi) Every bounded connected component of $\mathbb{H} \setminus \Omega_D$ intersects $\mathbb{H} \setminus \Omega_{D_1}$.

The equivalences (i) $\iff$ (iii) $\iff$ (v) are classical (see Proposition 2.1 below). The implication (vi) $\Rightarrow$ (ii) has been proven before by Colombo, Sabadini and Struppa (Theorem 4.13 of [12]).
The equivalence \((i) \iff (ii)\) is Proposition 2.4. The equivalence \((iii) \iff (iv)\) is Proposition 2.15.

The equivalence \((v) \iff (vi)\) is an easy consequence of the fact that each bounded connected component \(C\) of \(D\), resp. \(D_1\), corresponds to a bounded connected component \(\Omega_C\) of \(\Omega_D\), resp. \(\Omega_{D_1}\), via

\[
\Omega_C = \{x + yi; x, y, \in \mathbb{R}, x + yi \in C, I \in \mathbb{S}\}.
\]

In the context of proving our results on Runge pairs we obtain a precise description of the homology of \(\Omega_D\) in terms of the topology of \(D\). (see Proposition 2.5.)

1.1. Examples.

**Example 1.4.** \(\mathbb{C}^*\) is a symmetric domain with corresponding axially symmetric domain \(\mathbb{H}^*\).

\(\mathbb{H}^*\) is simply-connected, but not Runge in \(\mathbb{H}\), because \(i_* : H_3(\mathbb{H}^*) \simeq \mathbb{Z} \to H_3(\mathbb{H}) = \{0\}\) is not injective.

**Example 1.5.** \(\mathbb{C}\backslash \mathbb{R}\) is a symmetric domain with corresponding axially symmetric domain \(\Omega = \mathbb{H}\backslash \mathbb{R}\). The domain \(\Omega\) is homotopic to the 2-sphere, thus simply-connected but not contractible. However, \(\Omega\) is Runge in \(\mathbb{H}\): \(H_1(\Omega)\) and \(H_3(\Omega)\) vanish both, hence \(H_k(\Omega) \to H_k(\mathbb{H})\) is injective for \(k = 1, 3\). Thus we have a Runge pair although \(\mathbb{Z} \simeq H_2(\Omega) \to H_2(\mathbb{H}) = \{0\}\) is not injective.

**Example 1.6.** Let \(D = \{z \in \mathbb{C} : |z| > 1\}\) and \(D_1 = D \cup \{z \in \mathbb{C} : -1/2 < \Re m(z) < 1/2\}\).

Then \(\Omega_D\) is Runge in \(\Omega_{D_1}\).

Evidently \(\Omega_D\) is the complement of the closed unit ball in \(\mathbb{H}\) and therefore homotopic to the 3-sphere. Now \(D_1 \neq \mathbb{C}\), hence \(\exists\ p \not\in \Omega_{D_1}\) and we have inclusion maps

\[
\Omega_D \overset{i}{\hookrightarrow} \Omega_{D_1} \overset{j}{\to} \mathbb{H} \backslash \{p\}.
\]

Since the composition map \(j \circ i\) is a homotopy equivalence, all the homology group homomorphisms \(i_*\) induced by \(i\) must be injective. Hence our results imply that \(D\) is Runge in \(D_1\).

2. Runge

2.1. The complex situation. In the complex case one has the following well-known result.

**Proposition 2.1.** Let \(D \subset D_1\) be open subsets of \(\mathbb{C}\). Then the following properties are equivalent:
(i) The inclusion map induces an injective group homomorphism $H_1(D) \to H_1(D_1)$.

(ii) Every bounded connected component of $\mathbb{C} \setminus D$ intersects $\mathbb{C} \setminus D_1$.

(iii) For every holomorphic function $f$ on $D$, every $\epsilon > 0$ and every compact subset $K \subset D$ there exists a holomorphic function $F$ on $D_1$ with $\sup_{p \in K} |f(p) - F(p)| < \epsilon$.

If one (hence all) of these properties are fulfilled, then $D \subset D_1$ is called a Runge pair, or we say that $D$ is Runge in $D_1$.

See [3] and [20] §13.2.1.

2.2. Symmetric complex situation. We recall (see §1) that a subset $D \subset \mathbb{C}$ is “symmetric” if it is invariant under complex conjugation.

Lemma 2.2. Let $D \subset D_1$ be symmetric open subsets of $\mathbb{C}$.

Then the following are equivalent:

(i) Every holomorphic function $f$ on $D$ can be approximated (locally uniformly) by holomorphic functions on $D_1$ (i.e., $D \subset D_1$ is a Runge pair)

(ii) Every holomorphic function $f$ on $D$ which is symmetric, i.e., for which $f(z) = \overline{f(\bar{z})}$ holds, can be approximated (locally uniformly) by symmetric holomorphic functions on $D_1$.

Proof. (i) $\implies$ (ii). Assume that $D$ is Runge in $D_1$ and that $f : D \to \mathbb{C}$ is holomorphic with $f(z) = \overline{f(\bar{z})}$. If $f_n$ is a sequence of holomorphic functions on $D_1$ converging to $f$, then also

$$g_n(z) = \frac{1}{2} \left( f_n(z) + \overline{f_n(\bar{z})} \right)$$

converges to $f$ and in addition fulfills $g_n(z) = \overline{g_n(\bar{z})}$

(ii) $\implies$ (i). Let $f : D \to \mathbb{C}$ be an arbitrary holomorphic function. We define

$$g(z) = \frac{1}{2} \left( f(z) + \overline{f(\bar{z})} \right)$$

$$h(z) = \frac{1}{2i} \left( f(z) - \overline{f(\bar{z})} \right)$$

Then $g$ and $h$ are both symmetric holomorphic functions and $f(z) = g(z) + ih(z)$. By assumption the functions $g$ and $h$ may be approximated by holomorphic functions on $D_1$. It follows that $f = g + ih$ can be approximated, too. \qed
2.3. **Passing from** $D$ **to** $\Omega_D$. Let a symmetric open subset $D \subset \mathbb{C}$ be given. The associated axially symmetric subset $\Omega_D$ in $\mathbb{H}$ has been defined in §1 as:

$$\Omega_D = \{x + yI : x, y \in \mathbb{R}, I \in S, x + yi \in D\}$$

(with $S = \{q \in \mathbb{H} : q^2 = -1\}$).

This construction may be reformulated as follows.

Define $D^+ = D \cap \{z \in \mathbb{C} : \Im m(z) \geq 0\}$, $D_R = D \cap \mathbb{R}$.

Let $Z = D^+ \times S$. Then $\Omega_D \simeq Z/\sim$ where $(p, I) \sim (q, J)$ iff $p = q$ and one of the following conditions is fulfilled:

(i) $I = J$, or
(ii) $p = q \in \mathbb{R}$.

In other words, for each $p \in D_R$, the subset $\{p\} \times S$ of $Z$ is collapsed to one point.

2.4. **Quaternionic situation.**

**Lemma 2.3.** Let $f : \mathbb{H} \to \mathbb{H}$ be a slice function induced by a stem function $F$. Then

$$\frac{1}{\sqrt{2}} ||F(x + yi)|| \leq \max\{|f(x + yI)|, |f(x - yI)|\} \leq \sqrt{2} ||F(x + yi)||$$

for every $x, y \in \mathbb{R}, I \in S$.

**Proof.** From $f(x + yI) = F_1(x + yI) + IF_2(x + yi)$ one deduces

$$|f(x + yI)| \leq ||F_1(x + yi)|| + ||F_2(x + yi)||$$

$$\Rightarrow |f(x + yI)|^2 \leq (||F_1(x + yi)|| + ||F_2(x + yi)||)^2$$

$$\Rightarrow |f(x + yI)|^2 \leq ||F(x + yi)||^2 + 2||F_1(x + yi)|| \cdot ||F_2(x + yi)||$$

$$\leq 2||F(x + yi)||^2$$

$$\Rightarrow |f(x + yI)| \leq \sqrt{2} ||F(x + yi)||.$$

On the other hand, $F_1(x + yi) = \frac{1}{2} (f(x + yI) + f(x - yI))$ implying

$$||F_1(x+yi)|| \leq \max\{|f(x+yI)|, |f(x-yI)|\}.$$ Similarly: $||F_2(x+yi)|| \leq \max\{|f(x+yI)|, |f(x-yI)|\}$. Combining these bounds we obtain:

$$||F(x+yi)||^2 \leq 2 \max\{|f(x+yI)|^2, |f(x-yI)|^2\}$$

which implies the first inequality of the lemma. 

**Proposition 2.4.** Let $D \subset D_1$ be a symmetric open subsets of $\mathbb{C}$ with corresponding axially symmetric open subsets $\Omega_D \subset \Omega_{D_1}$ in $\mathbb{H}$. 


Then every regular function on $\Omega_D$ may be approximated locally uniformly by regular functions on $\Omega_{D_1}$ if and only if $D$ is Runge in $D_1$.

Proof. For any symmetric subset $C \subset D$ the corresponding subset

$$\Omega_C = \{x + yI : \exists x + yi \in C, I \in S\}$$

of $\mathbb{H}$ is compact if and only if $C$ is compact. We measure the size of a function by using the sup-norm. From the euclidean scalar product on $\mathbb{C} \simeq \mathbb{R}^2$ and $\mathbb{H} \simeq \mathbb{C} \simeq \mathbb{R}^4$ we deduce a scalar product on $\mathbb{H} \otimes \mathbb{C} \simeq \mathbb{R}^8$. The norm induced by this scalar product is denoted by $|| \cdot ||$. From the preceding lemma we deduce that

$$\frac{1}{\sqrt{2}} ||F||_C \leq ||f||_{\Omega_C} \leq \sqrt{2} ||F||_C$$

for any compact symmetric subset $C \subset D$ (where $||F||_C = \sup_{z \in C} ||F(z)||$).

Therefore the space of slice functions $C \subset D$ (where $||F||_C = \sup_{z \in C} ||F(z)||$) is isomorphic as a topological vector space to the space of stem functions on $D$ (both spaces endowed with topology of locally uniform convergence). This implies the assertion. \qed

2.5. Homology of axially symmetric domains. In this paragraph we show that and how the homology of an axially symmetric domain in $\mathbb{H}$ is determined by that of the corresponding symmetric open set in $\mathbb{C}$.

We will study the topology of this procedure aided by the Mayer-Vietoris sequence.

We introduce some notation which we will keep throughout this section.

Convention. Let $D$ be a symmetric open subset of $\mathbb{C}$ (i.e. a domain such that $z \in D$ if and only if $\bar{z} \in D$), $D^+ = \{z \in D : \Im m(z) \geq 0\}$, $D^- = \{z \in D : \Im m(z) \leq 0\}$, $D_\mathbb{R} = D \cap \mathbb{R}$, $D^* = D^+ \setminus \mathbb{R}$. For any subset $A \subset \mathbb{C}$ a subset $\Omega_A$ of $\mathbb{H}$ is defined as

$$\Omega_A = \{x + yI : x, y \in \mathbb{R}, x + yi \in A, I \in S\}$$

Let the boundary of $D$ in $\mathbb{C}$ be denoted by $\partial D$. Define a real positive function $h$ on $D_\mathbb{R}$ by

$$h(x) = \text{dist}(x, \partial D) = \inf_{z \in \partial D} |z - x|.$$ 

Using the triangle inequality, it is easy to check that $h$ is continuous. Furthermore, we define $W = \{x + yi \in \mathbb{C} : x \in D_\mathbb{R} : 0 \leq y < h(x)\}$, $W^* = W \setminus D_\mathbb{R}$. 

We observe that
\[ W = \{ x + rh(x)i : x \in D_R, r \in [0, 1] \} \]
\[ W^* = \{ x + rh(x)i : x \in D_R, r \in ]0, 1[ \} \]
\[ D_R = \{ x + rh(x)i : x \in D_R, r = 0 \} \].

Since \([0, 1[, ]0, 1[\) and \(\{0\}\) are all contractible, it is clear that the natural inclusion maps \(W^* \to W\) and \(D_R \to W\) are homotopy equivalences. The inclusion map \(D^+ \to D^+\) is likewise a homotopy equivalence.

We recall the definition of \(\tilde{H}_0\): An element \(\alpha\) in \(H_0(X)\) is a formal finite \(\mathbb{Z}\)-linear combination of points \(\alpha = \sum n_i p_i\) \((p_i \in X)\) and therefore admits a natural degree function by \(deg(\alpha) = \sum n_i\). The “reduced homology group” \(\tilde{H}_0\) is defined as the kernel of the degree map \(H_0 \to \mathbb{Z}\).

**Proposition 2.5.** Let \(D\) be a symmetric open subset of \(\mathbb{C}\). We assume that the corresponding axially symmetric set \(\Omega_D\) is connected.

Then \(H_2(\Omega_D) = \{0\}\) if \(D_R \neq \{\}\) and \(H_2(\Omega_D) \cong \mathbb{Z}\) if \(D_R\) is empty.

There are natural exact sequences
\begin{align*}
0 & \to H_1(D^+) \to H_3(\Omega_D) \to \tilde{H}_0(D_R) \to 0 
\end{align*}
and
\begin{align*}
0 & \to H_1(D^+) \to H_1(\Omega_D) \to 0.
\end{align*}

**Proof.** Observe that \(\Omega_D = \Omega_{D^*} \cup \Omega_W\) and \(\Omega_{D^*} \cap \Omega_W = \Omega_{W^*}\). This yields a Mayer-Vietoris sequence for homology:
\[ \ldots \to H_{k+1}(\Omega_D) \to H_k(\Omega_{W^*}) \to H_k(\Omega_{D^*}) \oplus H_k(\Omega_W) \to H_k(\Omega_D) \to \ldots \]
We claim that there are homotopy equivalences
\[ \Omega_{W^*} \sim S \times D_R, \quad \Omega_W \sim D_R, \quad \Omega_{D^*} \sim S \times D^* \sim S \times D^+. \]
The first of these homotopy equivalences holds because
\[ \Omega_{W^*} = \{ x + yI : x \in D_R, 0 < y < h(x), I \in S \}. \]
We observe that \(D_R\) is a deformation retract of \(\Omega_W\). Indeed
\[ \Omega_W = \{ x + yI : x \in D_R, 0 \leq y < h(x), I \in \mathbb{S} \} \]
may be retracted to \(D_R\) via
\[ \Phi_s : (x + yI) \mapsto (x + syI) \quad (0 \leq s \leq 1). \]
Thus \(\Omega_W\) is homotopy equivalent to \(D_R\).

Finally \(\Omega_{D^*} \sim S \times D^+\) follows from
\[ \Omega_{D^*} = \{ x + yI, x + yi \in D^*, I \in \mathbb{S} \} \sim D^* \times \mathbb{S} \]
and the fact that \(D^+\) and \(D^*\) are homotopy equivalent.
Thus our Mayer-Vietoris sequence yields this exact sequence:

$$\ldots \rightarrow H_{k+1}(\Omega_D) \rightarrow H_k(S \times D_{\mathbb{R}}) \rightarrow H_{k}(S \times D^+) \oplus H_{k}(D_{\mathbb{R}}) \rightarrow H_{k}(\Omega_D) \rightarrow \ldots$$

Since the homology groups of the sphere $S$ are torsion-free, the Künneth formula tells us that

$$H^*(S \times X) \simeq H^*(S) \otimes_{\mathbb{Z}} H^*(X) \simeq (H_0(S) \otimes_{\mathbb{Z}} H^*(X)) \oplus (H_2(S) \otimes_{\mathbb{Z}} H^*(X)) \simeq H^*(X) \oplus [S] \cdot H^*(X)$$

where $[S] \in H_2(S)$ is the fundamental class.

Hence

$$\ldots \rightarrow H_{k+1}(\Omega_D) \rightarrow (H_0(S) \otimes H_k(D_{\mathbb{R}})) \oplus (H_2(S) \otimes H_{k-2}(D_{\mathbb{R}})) \rightarrow (H_0(S) \otimes H_k(D^+)) \oplus (H_2(S) \otimes H_{k-2}(D^+)) \oplus H_k(D_{\mathbb{R}}) \rightarrow H_k(\Omega_D) \rightarrow \ldots$$

We know that $H_k(D_{\mathbb{R}}) = \{0\}$ for $k > 0$ and $H_k(D^+) = \{0\}$ for $k > 1$ for dimension reasons.

Therefore our long exact Mayer-Vietoris sequences yield the following two exact sequences:

(2.3) \quad $0 \rightarrow H_2(S) \otimes H_1(D^+) \rightarrow H_3(\Omega_D) \rightarrow H_2(S) \otimes H_0(D_{\mathbb{R}}) \rightarrow H_2(S) \otimes H_0(D^+) \rightarrow H_2(\Omega_D) \rightarrow 0$

and

(2.4) \quad $0 \rightarrow H_0(S) \otimes H_1(D^+) \rightarrow H_1(\Omega_D) \rightarrow H_0(D_{\mathbb{R}}) \rightarrow H_0(D^+) \oplus H_0(D_{\mathbb{R}}) \rightarrow H_0(\Omega_D) \rightarrow 0$

Case (1). Assume now that $D_{\mathbb{R}}$ is not empty. Then inclusion map from $D_{\mathbb{R}}$ into $D^+$ yields a surjective group homomorphism $H_0(D_{\mathbb{R}}) \rightarrow H_0(D^+)$ with $H_0(D_{\mathbb{R}})$ as kernel. Let $\alpha$ denote the homomorphism $H_2(S) \otimes H_0(D_{\mathbb{R}}) \rightarrow H_2(S) \otimes H_0(D^+)$ in (2.3). Then the exact sequence (2.3) can be split into two parts

(2.5) \quad $0 \rightarrow H_2(S) \otimes H_1(D^+) \rightarrow H_3(\Omega_D) \rightarrow \ker \alpha \rightarrow 0$

and

(2.6) \quad $0 \rightarrow (H_2(S) \otimes H_0(D_{\mathbb{R}})) / \ker \alpha \rightarrow H_2(S) \otimes H_0(D^+) \rightarrow H_2(\Omega_D) \rightarrow 0$. 


Since $\ker \alpha \simeq \tilde{H}_0(D_\mathbb{R})$, (2.5) now implies (2.1).
Furthermore (2.6) implies that $H_2(\Omega_D)$ is zero, because $\alpha$ is surjective.

Case (2). Now let us discuss the case where $D_\mathbb{R}$ is empty. Then $H_0(D_\mathbb{R}) = \{0\}$ and consequently from (2.3) we obtain two sequences

$$0 \to H_2(S) \otimes H_1(D_\mathbb{R}) \to H_3(\Omega_D) \to 0 = H_2(S) \otimes H_0(D_\mathbb{R})$$

and

$$0 = H_2(S) \otimes H_0(D_\mathbb{R}) \to \mathbb{Z} \simeq H_2(S) \otimes H_0(D^+) \to H_2(\Omega_D) \to 0$$

Using $H_2(S) \simeq \mathbb{Z} \simeq H_0(S)$ we get (2.1) and $H_2(\Omega_D) = \{\mathbb{Z}\}$.

It remains to show (2.2). For this purpose we return to (2.4). The map $H_0(D_\mathbb{R}) \to H_0(D^+) \oplus H_0(D_\mathbb{R})$ in (2.4) is obviously injective, therefore (due to exactness of the sequence) the preceding map is zero and $H_1(\Omega_D)$ is isomorphic to $H_0(S) \otimes H_1(D^+)$. However, $H_0(S) \simeq \mathbb{Z}$ and therefore $H_0(S) \otimes H_1(D^*) \simeq H_1(D^*)$. Hence $H_1(\Omega_D) \simeq H_1(D^*)$. □

**Corollary 2.6.** Assume in addition that $D$ is a bounded domain with smooth boundary. Then all the homology groups are finitely generated and Proposition 2.5 implies the following description of the Betti numbers $b_k = \dim_\mathbb{R} H_k(\Omega_D) \otimes \mathbb{R}$: Let $r = b_0(D_\mathbb{R}) - 1$ if $D_\mathbb{R}$ is not empty and set $r = 0$ if $D_\mathbb{R}$ is empty. Then

$$b_1(\Omega_D) = \frac{1}{2} (b_1(D) - r)$$

$$b_3(\Omega_D) = \frac{1}{2} (b_1(D) + r)$$

and

$$b_2(\Omega_D) = \begin{cases} 1 & \text{if } D_\mathbb{R} \text{ is empty} \\ 0 & \text{if } D_\mathbb{R} \text{ is not empty} \end{cases}$$

**Corollary 2.7.** Let $D$ be a symmetric open subset and let $\Omega_D$ denote the corresponding axially symmetric set (not necessarily connected).

Then $\hat{H}_2(\Omega_D) \simeq \mathbb{Z}^k$ where $k$ denote the number of connected components of $D^+$ which do not intersect $\mathbb{R}$.

Let $\tilde{H}_0(D_\mathbb{R})$ denote the kernel of the homomorphism $i_* : H_0(D_\mathbb{R}) \to H_0(D^+)$. There are natural exact sequences

$$0 \to H_1(D^+) \to H_3(\Omega_D) \to \tilde{H}_0(D_\mathbb{R}) \to 0$$
and

\[(2.8)\quad 0 \to H_1(D^+) \to H_1(\Omega_D) \to 0.\]

**Proof.** This is an easy consequence of Proposition 2.5, since the homology of a disconnected space is isomorphic to the direct sum of the homology of its connected components. \qed

**Corollary 2.8.** For an axially symmetric open subset \(\Omega \subset \mathbb{H}\) all homology groups are torsion-free.

**Proof.** First observe that there is no loss in generality in assuming that \(\Omega_D\) is connected, because the homology groups of \(\Omega_D\) are isomorphic to the direct sum of the homology groups of its connected components. For connected \(\Omega_D\) the assertion follows from the preceding proposition, because the homology groups of open sets in \(\mathbb{R}\) and \(\mathbb{R}^2\) are known to be always torsion-free and \(D_{\mathbb{R}}\), resp. \(D^*\), is an open subset in \(\mathbb{R}\) resp. \(\mathbb{R}^2\). \qed

We now explain the geometric meaning of the short exact sequence (2.1). Given an element \(\alpha \in H_1(D^+)\) we may represent \(\alpha\) as a finite formal \(\mathbb{Z}\)-linear combination of closed curves \(\gamma_j : S^1 \to D^+\). Each such curve \(\gamma_j\) defines a map \(\eta\) from \(S^1 \times \mathbb{S}\) to \(\Omega_D\) via

\[\eta(t, I) = Re(\gamma_j(t)) + I Im(\gamma_j(t)).\]

The fundamental class of the real three-dimensional manifold \(S^1 \times \mathbb{S}\) then defines the corresponding element in \(H_3(\Omega_D)\).

An element \(\beta \in H_0(D_{\mathbb{R}})\) may be represented as a formal \(\mathbb{Z}\)-linear combination of points \(\sum n_i \{p_i\}\). Assume that \(\beta\) is in the kernel of the natural map to \(\mathbb{Z}\) which is given by \(\sum n_i \{p_i\} \mapsto \sum n_i\). Then \(\beta\) is the sum of elements of the form \(+1\{p_i\} - 1\{q_i\}\). Given such an element, we choose a curve \(\gamma : [0, 1] \to D^+\) with \(\gamma(0) = p_i\), \(\gamma(1) = q_i\), \(\gamma(t) \in D^+ \setminus \mathbb{R}\) for \(0 < t < 1\). Then \(\Omega_{\gamma([0,1])}\) is a 3-sphere defining an element in \(H_3(\Omega_D)\). Note that this construction depends on the choice of the curve \(\gamma\). Therefore the sequence (2.1) has no natural splitting.

**Lemma 2.9.** Let \(D \subset \mathbb{C}\) be a symmetric open subset.

With \(D^+, D_{\mathbb{R}}\) and \(\hat{H}_0(D_{\mathbb{R}})\) defined as in Corollary 2.7 there is natural exact sequence

\[(2.9)\quad 0 \to H_1(D^+) \oplus H_1(D^-) \to H_1(D) \to \hat{H}_0(D_{\mathbb{R}}) \to 0\]

**Proof.** Let \(W\) be as above in the proof of Proposition 2.5 and define

\[V = \{z \in \mathbb{C} : z \in W \text{ or } \bar{z} \in W\}\]

\[U^+ = D^+ \cup V, \quad U^- = D^- \cup V.\]
Observe that we have homotopy equivalences
\[ U^+ \sim D^+, \quad U^- \sim D^-, \quad (U^+ \cap U^-) = V \sim D_R \]
We use the Mayer-Vietoris sequence associated to \( D = U^+ \cup U^- \):
\[ \ldots \rightarrow H_{k+1}(D) \rightarrow H_k(D_R) \rightarrow H_k(D^+) \oplus H_k(D^-) \rightarrow H_k(D) \rightarrow \ldots \]
The details (which we omit) are very much similar to the proof of Proposition \ref{prop:homotopy-equivalences}.

**Corollary 2.10.** Let \( D \subset D_1 \) be symmetric open subsets in \( \mathbb{C} \). Assume that \( H_1(D) \rightarrow H_1(D_1) \) is injective. Then \( H_1(D^+) \rightarrow H_1(D_1^+) \) is injective, too.

**Proof.** The inclusion map from \( D \) to \( D_1 \) combined with \eqref{eq:mayer-vietoris-sequence} yields the following commutative diagram
\[
\begin{array}{cccccc}
0 & \rightarrow & H_1(D^+) \oplus H_1(D^-) & \rightarrow & H_1(D) & \rightarrow & \hat{H}_0(D_R) & \rightarrow & 0 \\
& & \downarrow & & \downarrow & & \downarrow & & \downarrow \\
0 & \rightarrow & H_1(D_1^+) \oplus H_1(D_1^-) & \rightarrow & H_1(D_1) & \rightarrow & \hat{H}_0(D_1, \mathbb{R}) & \rightarrow & 0
\end{array}
\]
Now the assertion follows from the snake lemma (see e.g. \cite{book:19},III.§9).

**Proposition 2.11.** Let \( D \) be a symmetric open subset of \( \mathbb{C} \).
Then there is a natural exact sequence
\[
(2.10) \quad 0 \longrightarrow H_1(D^+) \overset{\alpha}{\longrightarrow} H_1(D) \overset{\beta}{\longrightarrow} H_3(\Omega_D) \longrightarrow 0.
\]
Here \( \alpha, \beta \) are as follows: Let \( \tau : \mathbb{C} \rightarrow \mathbb{C} \) denote complex conjugation on \( \mathbb{C} \) and let \( \zeta : D \times S \rightarrow \Omega_D \) be the map given by
\[
\zeta(x + yi, J) = x + yJ.
\]
Then \( \alpha(\gamma) = \gamma - \tau^* \gamma \) and \( \beta(\gamma) = \zeta^*(\gamma \times [S]) \) where \([S] \in H_2(S)\) denotes the fundamental class.

**Proof.** There is no loss in generality in assuming that \( D^+ \) is connected (and therefore \( \Omega_D \), too).
We cover \( D^+ \) by the two open subsets \( D^* \) and \( W \) as in the proof of Proposition \ref{prop:homotopy-equivalences}.
This induces corresponding coverings of \( D \), \( D \times S \) and \( \Omega_D \):
\[
D = (D \setminus D_R) \cup V \text{ with } V = \{ z \in \mathbb{C} : z \in W \text{ or } \bar{z} \in W \} \\
D \times S = ((D \setminus D_R) \times S) \cup (V \times S). \\
\Omega_D = \Omega_{D^*} \cup \Omega_W.
\]
For each of these coverings we obtain a Mayer–Vietoris sequence for homology.

We utilize the map $\zeta : D \times S \to \Omega_D$ given by

$$(x + y; J) \mapsto x + yJ.$$

This yields a morphism between the respective Mayer–Vietoris sequences:

$$\cdots \to H_k((V \setminus D_R) \times S) \to H_k((D \setminus D_R) \times S) \oplus H_k(V \times S) \to H_k(D \times S) \to \cdots$$

$$\downarrow \quad \downarrow \quad \downarrow \quad \downarrow$$

$$\cdots \to H_k(\Omega_{W^*}) \to H_k(\Omega_{D^*}) \oplus H_k(\Omega_W) \to H_k(\Omega_D) \to \cdots$$

In particular, we get

$$H^3((V \setminus D_R) \times S) \to H^3((D \setminus D_R) \times S) \oplus H^3(V \times S) \to H^3(D \times S) \to C \to 0$$

$$\downarrow \quad \downarrow \quad \downarrow \quad \downarrow$$

$$H^3(\Omega_{W^*}) \to H^3(\Omega_{D^*}) \oplus H^3(\Omega_W) \to H^3(\Omega_D) \to C' \to 0$$

with

$$C = \ker[H^2((V \setminus D_R) \times S) \to H^2((D \setminus D_R) \times S) \oplus H^2(V \times S)]$$

and

$$C' = \ker[H^2(\Omega_{W^*}) \to H^2(\Omega_{D^*}) \oplus H^2(\Omega_W)]$$

Recall that $H^3(M \times S) \simeq H_1(M)$ and $H^2(M \times S) \simeq H_0(M)$ for any $M \subset \mathbb{C}$ due to Künneth formula and dimension reasons. Observe also that $V \setminus D_R$ is the disjoint union of two open subsets (namely $D^+ \cap (V \setminus D_R)$ and $D^- \cap (V \setminus D_R)$) both of which are homotopic to $D_R$. Recall moreover that $V$ and $D_R$ are homotopy equivalent.

Hence

$$C \simeq \ker[H_0(V \setminus D_R) \to H_0(D \setminus D_R) \oplus H_0(V)].$$

and consequently

$$H_0(D_R) \sim \ker[H_0(V \setminus D_R) \to H_0(V)].$$
where the isomorphism may be describe as
\[ H_0(D_R) \ni \xi = \sum_j n_j \{p_j\} \]
\[ \mapsto \sum_j n_j (\{p_j - \epsilon\} - \{p_j + \epsilon\}) \in \ker[H_0(V \setminus D_R) \to H_0(V)] \]
\[ (p_j \in D_R) \]

for a sufficiently small \( \epsilon \).

Let \( \eta = \sum_j n_j (\{p_j - \epsilon\} - \{p_j + \epsilon\}) \in \ker[H_0(V \setminus D_R) \to H_0(V)]. \)

Then the homomorphism to \( H_0(D \setminus D_R) \) may be described as \( \eta \mapsto (\sum_j n_j, -\sum_j n_j) \in \mathbb{Z}^2 \cong H_0(D \setminus D_R). \)

It follows that
\[ C \cong \tilde{H}_0(D_R). \]

Now
\[ C' = \ker[H_2(\Omega W^\ast) \to H_2(\Omega D^\ast) \oplus H_2(\Omega W)] \]
\[ \cong \ker[H_2(D_R \times S) \to H_2(D^+ \times S) \oplus H_2(D_R)] \]

due to the homotopy equivalences (which were verified in the proof of Proposition 2.5)
\[ \Omega W^\ast \cong D_R \times S, \quad \Omega D^\ast \cong D^+ \times S, \quad \Omega W \cong D_R. \]

It follows that
\[ C' \cong \ker[H_0(D_R) \to H_0(D^+) \oplus \{0\}] \cong \ker[H_0(D_R) \to H_0(D^+)] \cong \tilde{H}_0(D_R). \]

The aforementioned homotopy equivalences also imply \( H_3(\Omega D^\ast) \cong H_1(D^+) \) and \( H_3(\Omega W) = \{0\} \). Combining all these facts, the above commutative diagram turns into the following commutative diagram:

\[
\begin{array}{ccccccccc}
0 & \longrightarrow & H_1(D^+) & \oplus & H_1(D^-) & \longrightarrow & H_1(D) & \longrightarrow & \tilde{H}_0(D_R) & \longrightarrow & 0 \\
\downarrow & & \rho_1 \downarrow & & \rho_2 \downarrow & & \downarrow \rho_3 = \text{id} & & \\
0 & \longrightarrow & H_1(D^+) & \longrightarrow & H_3(\Omega D) & \longrightarrow & \tilde{H}_0(D_R) & \longrightarrow & 0 \\
\end{array}
\]

The homomorphism \( \rho_1 \) is induced by the embedding
\[ D \setminus D_R = D^+ \cup D^- \longrightarrow \Omega D^\ast \]
and

\[ H_3(\Omega_{D^*}) \simeq H_3(D^+ \times \mathbb{S}) \simeq H_1(D^+). \]

Hence \( \rho_1(c_1, c_2) = c_1 + \tau_s c_2 \) if \( c_1 \) is a 1-cycle in \( D^+ \) and \( c_2 \) a 1-cycle in \( D^- \). In particular, \( \rho_1 \) is surjective with kernel

\[ \ker \rho_1 = \{(c, -\tau_s c) : c \in H_1(D^+)\} \]

\( \rho_2 \) is defined by

\[ H_1(D) \simeq H_3(D \times \mathbb{S}) \xrightarrow{\zeta} H_3(\Omega_D). \]

We set \( \beta = \rho_2 \) and define \( \alpha \) via \( \alpha(c) = \eta_1(c, -\tau_s c) \). Injectivity of \( \alpha \) is implied by injectivity of \( \eta_1 \). To check surjectivity of \( \beta \), let \( s \in H_3(\Omega_D) \). Since \( \rho_3 \) is an isomorphism, we find an element \( c \in H_1(D) \) with \( \eta_2(c) = \mu_2(s) \). Then \( s - \rho_2(c) \in \ker \mu_2 = \text{image}(\mu_1) \). Now \( \rho_1 \) is surjective. Therefore there exists \( a \in H_1(D^+) \oplus H_1(D^-) \) with

\[ s - \rho_2(c) = \mu_1(\rho_1(a)) = \rho_2(\eta_1(a)) \Rightarrow s = \rho_2(c + \eta_1(a)). \]

Let us check that \( \beta \circ \alpha = 0 \):

\[ \beta(\alpha(c)) = \rho_2(\alpha(c)) = \rho_2(\eta_1(c, -\tau_s c)) = \mu_1(\rho_1(c, -\tau_s c)) = \mu_1(0) = 0 \]

Finally, assume \( b \in \ker \beta \). We have to show that \( b \) is in the image of \( \alpha \). Now \( \beta(b) = \rho_2(b) = 0 \) implies

\[ \mu_2(\rho_2(b)) = \rho_3(\eta_2(b)) = \eta_2(b) = 0. \]

Thus \( b \in \ker(\eta_2) = \text{image}(\eta_1) \), i.e., there is an element \((c', c'') \in H_1(D^+) \oplus H_1(D^-) \) with \( \eta_1(c', c'') = b \). Since \( \mu_1 \) is injective, and \( \rho_2(b) = 0 \), we know that

\[ 0 = \rho_1(c', c'') = c' + \tau_s c''. \]

Hence \( c'' = -\tau_s c' \). It follows that \( b = \alpha(c') \). \qed

**Corollary 2.12.** Let \( D \subset D_1 \) be symmetric open subsets in \( \mathbb{C} \) such that \( H_1(\Omega_D) \to H_1(\Omega_{D_1}) \) and \( H_3(\Omega_D) \to H_3(\Omega_{D_1}) \) are both injective. Then \( H_1(D) \to H_1(D_1) \) is injective, too.

**Proof.** First recall that \( H_1(\Omega_D) \simeq H_1(D^+) \) (and \( H_1(\Omega_{D_1}) \simeq H_1(D_1^+) \)) due to \([3.2]\).

Second, we consider the following commutative diagram induced from \([2.10]\) via the map \( D \leftrightarrow D_1 \).

\[
\begin{array}{cccccc}
0 & \longrightarrow & H_1(D^+) & \longrightarrow & H_1(D) & \longrightarrow & H_3(\Omega_D) & \longrightarrow & 0 \\
\downarrow & & \downarrow & & \downarrow & & \downarrow & & \\
0 & \longrightarrow & H_1(D_1^+) & \longrightarrow & H_1(D_1) & \longrightarrow & H_3(\Omega_{D_1}) & \longrightarrow & 0.
\end{array}
\]

Now the snake lemma (see e.g. \([19]\),III.§9) yields the statement. \qed
Lemma 2.13. Let $P$ be a symmetric compact connected subset of $\mathbb{C}$ such that $P \cap \mathbb{R}$ is non-empty and connected. Let $P'$ be a non-empty symmetric closed subset of $P$ and define

$$
D = \mathbb{C} \setminus P, \\
D_1 = \mathbb{C} \setminus P'.
$$

Then $H_3(\Omega_D) \to H_3(\Omega_{D_1})$ is injective.

Proof. By construction we have

$$H_1(D) \simeq \mathbb{Z}, \quad \hat{H}_0(D_{\mathbb{R}}) \simeq \mathbb{Z}.$$

Using (2.9) it follows that $H_1(D^+) = \{0\}$. Then we may apply (2.1) to conclude that $H_3(\Omega_D) \simeq \mathbb{Z}$.

Let $R > \max\{|z| : z \in P\}$. Regard the 3-sphere $S$ with center 0 and radius $R$ in $\mathbb{H}$. Because $P$ is contained in the interior of the sphere, $S$ defines a non-trivial homology class in $H_3(\Omega_D)$. Since $P'$ is also non-empty and in the interior of the sphere, the homology class of $S$ in $H_3(\Omega_{D_1})$ is likewise non-zero. Thus the homomorphism $i_* : H_3(\Omega_D) \to H_3(\Omega_{D_1})$ maps a non-trivial element of $H_3(\Omega_D)$ to a non-trivial element of $H_3(\Omega_{D_1})$. This implies the statement because $H_3(\Omega_D) \simeq \mathbb{Z}$. \hfill $\square$

Proposition 2.14. Let $D \subset D_1$ be symmetric open subsets of $\mathbb{C}$ such that the natural homomorphism $H_1(D) \to H_1(D_1)$ is injective.

Then $H_3(\Omega_D) \to H_3(\Omega_{D_1})$ is injective, too.

Proof. Assume the contrary. Let

$$\alpha \in \ker (H_3(\Omega_D) \to H_3(\Omega_{D_1})) , \alpha \neq 0.$$

The injectivity of $H_1(D) \to H_1(D_1)$ implies that $H_1(D^+) \to H_1(D_1^+)$ is injective too (Corollary 2.10). The inclusion map $D \to D_1$ applied to (2.1) yields the following commutative diagram

$$
\begin{array}{cccccc}
0 & \longrightarrow & H_1(D^+) & \longrightarrow & H_3(\Omega_D) & \longrightarrow & \hat{H}_0(D_{\mathbb{R}}) & \longrightarrow & 0 \\
\downarrow & & \downarrow & & \downarrow & & \downarrow & & \downarrow \\
0 & \longrightarrow & H_1(D_1^+) & \longrightarrow & H_3(\Omega_{D_1}) & \longrightarrow & \hat{H}_0(D_{1,\mathbb{R}}) & \longrightarrow & 0.
\end{array}
$$

Let $\alpha_0$ denote the image of $\alpha$ in $\hat{H}_0(D_{\mathbb{R}})$. First, we claim that $\alpha_0$ cannot vanish. Indeed, if $\alpha_0 = 0$, then $\alpha$ is induced by an element $\beta \in H_1(D^+)$. Evidently $\alpha \neq 0$ implies $\beta \neq 0$. But now we obtain a contradiction, since $H_1(D^+) \to H_1(D_1^+)$ and $H_1(D_1^+) \to H_3(\Omega_{D_1})$ are both injective, but $\alpha$ is mapped to zero in $H_3(\Omega_{D_1})$. Hence $\alpha_0 \neq 0$. 
Second, by assumption the image of $\alpha$ in $H_3(\Omega_{D_1})$ vanishes, implying that the image in $\tilde{H}_0(D_{1,\mathbb{R}})$ also vanishes. Thus $\alpha_0$ is in the kernel of $\tilde{H}_0(D_{\mathbb{R}}) \rightarrow \tilde{H}_0(D_{1,\mathbb{R}})$. Let $\alpha_0$ be represented by the formal $\mathbb{Z}$-linear combination $\sum_{x \in I} n_x \{x\}$ where $I$ is a finite subset of $D_{\mathbb{R}}$. Since $\alpha_0 \neq 0$, but $\sum n_k = 0$ (because $\alpha$ is in the kernel of the morphism from $H_0(D_{\mathbb{R}})$ to $H_0(D)$), we can find a point $q \in \mathbb{R} \setminus D$ such that

$$\sum_{p \in I, p > q} n_p \neq 0.$$ 

Fix such a point $q$. Let $B$ denote the connected component of $D^c = \mathbb{C} \setminus D$ containing $q$.

Fix $p_1, p_2 \in I$ with $p_1 < q < p_2$ and such that $I \cap [p_1, p_2] = \emptyset$.

Note that $\alpha_0$ is mapped onto zero in $\tilde{H}_0(D_{1,\mathbb{R}})$ which implies that $[p_1, p_2]$ is contained in $D_{1,\mathbb{R}}$.

Because $\alpha$ is mapped to zero in $H_0(D^+)$, we know that $p_1$ and $p_2$ are contained in the same connected component of $D^+$. Therefore $p_1$ and $p_2$ can be connected by a path $\gamma$ in $D^+$. This path, combined with its image under conjugation, yields a closed curve inside $D$ which surrounds $q$. Therefore $B$ must be bounded, and $B \cap \mathbb{R} \subset [p_1, p_2]$.

Combining the latter fact with $[p_1, p_2] \subset D_{1,\mathbb{R}}$ implies that $\mathbb{R} \cap (B \setminus D_1) = \emptyset$.

Since we assumed that $H_1(D) \rightarrow H_1(D_1)$ is injective, boundedness of $B$ implies $B \cap D^c_1 \neq \emptyset$.

We choose a path $\zeta : [0, 1] \rightarrow B$ such that $\zeta(0) = q$, $\zeta(1) \notin D_1$ and $\zeta(t) \notin \mathbb{R}$ for $t > 0$. Define

$$P = \{ z \in \mathbb{C} : \exists t \in [0, 1], z = \zeta(t) \text{ or } \overline{\zeta(t)} \}.$$ 

Observe that $P \cap \mathbb{R} = \{q\}$.

Now we consider the following diagram of inclusion maps

$$
\begin{array}{ccc}
D & \longrightarrow & D_1 \\
\downarrow & & \downarrow \\
\mathbb{C} \setminus P & \longrightarrow & \mathbb{C} \setminus (P \cap D_1^c).
\end{array}
$$

From Lemma 2.13 we obtain injectivity of $H_3(\Omega_{\mathbb{C} \setminus P}) \rightarrow H_3(\Omega_{\mathbb{C} \setminus (P \cap D_1^c)})$ which leads to a contradiction: First, by construction $\alpha_0$ is mapped to a non-zero element of $\tilde{H}_0(\mathbb{R} \setminus P)$. Due to (2.1) it follows that $\alpha$ is mapped to a non-zero element of $H_3(\Omega_{\mathbb{C} \setminus P})$. Second, its image in $H_3(\Omega_{D_1})$ is zero, which forces its image in $H_3(\Omega_{\mathbb{C} \setminus (P \cap D_1^c)})$ to be zero, because $D_1 \subset \mathbb{C} \setminus (P \cap D_1^c)$. □
Proposition 2.15. Let $D \subset D_1$ be symmetric open subsets of $\mathbb{C}$ with corresponding axially symmetric subsets $\Omega_D \subset \Omega_{D_1}$ in $\mathbb{H}$.

Then $H_1(D) \to H_1(D_1)$ is injective if and only if both $H_1(\Omega_D) \to H_1(\Omega_{D_1})$ and $H_3(\Omega_D) \to H_3(\Omega_{D_1})$ are injective.

Proof. First we recall that the homology of a disjoint union $X = A \cup B$ is simply the direct sum of the homology of $A$ and $B$. For this reason there is no loss in generality in assuming that $\Omega_D$ is connected.

If both $H_1(\Omega_D) \to H_1(\Omega_{D_1})$ and $H_3(\Omega_D) \to H_3(\Omega_{D_1})$ are injective, injectivity of $H_1(D) \to H_1(D_1)$ follows from Corollary 2.12.

Now assume $H_1(D) \to H_1(D_1)$ is injective. Then $H_3(\Omega_D) \to H_3(\Omega_{D_1})$ is injective due to Proposition 2.14. Furthermore injectivity of $H_1(\Omega_D) \to H_1(\Omega_{D_1})$ follows from Corollary 2.10 combined with (2.2). □

3. Appendix

3.1. Some planar topology. Here we show that for a pair of domains $G \subset H$ in $\mathbb{C}$ the group homomorphism $i_* : H_1(G) \to H_1(H)$ induced by the inclusion map $i$ is injective if and only if every bounded connected component of $G^c = \mathbb{C} \setminus G$ hits a bounded connected component of $H^c$. This is well-known, but we provide a new proof based on an identification of $H_1(G)$ with a certain function space, namely $C_c(G^c, \mathbb{Z})$. 
Proposition 3.1. Let $G$ be an open subset of $\mathbb{C}$ and denote its complement by $G^c$.

Then there is a natural isomorphism $\xi$ between $H_1(G, \mathbb{Z})$ and $\mathcal{C}_c(G^c, \mathbb{Z})$ (i.e. the space of $\mathbb{Z}$-valued continuous (locally constant) functions with compact support on $G^c$).

Proof. A cycle $\gamma \in H_1(G, \mathbb{Z})$ defines a function $n_\gamma$ on $\mathbb{C} \setminus \text{supp}(\gamma)$ by the winding number

$$n_\gamma(z) = \int_\gamma \frac{dw}{w - z}.$$ 

The winding number $n_\gamma$ is locally constant on $\mathbb{C} \setminus |\gamma|$, therefore $n_\gamma$ is continuous on $G^c$. It is compactly supported, because $n_\gamma(z) = 0$ for all $z$ with $|z| > \max\{|w| : w \in |\gamma|\}$.

Now assume that $\gamma$ is in the kernel of this map $\xi : \gamma \mapsto n_\gamma$. For each $k \in \mathbb{Z}$ let $Z_k$ denote the cycle defined by the open set $\{z \in G : n_\gamma(z) = k\}$. Then the homology class of $\gamma$ in $H_1(G, \mathbb{Z})$ vanishes, because $\gamma = \partial(\sum_k kZ_k)$ (here $\partial$ denotes the boundary operator in homology). This proves injectivity of the group homomorphism $\xi : H_1(G, \mathbb{Z}) \to \mathcal{C}_c(G^c, \mathbb{Z})$.

Conversely let $f \in \mathcal{C}_c(G^c, \mathbb{Z})$. Since $f$ has compact support and takes values in $\mathbb{Z}$, $f$ is a finite sum of functions $\pm f_i$ with $f_i \in \mathcal{C}_c(G^c, \mathbb{Z})$ and $f_i(z) \in \{0, 1\}$ for all $z, i$. We may therefore without loss of generality assume that $f(G^c) = \{0, 1\}$. Let $R > \sup\{|z| : f(z) \neq 0\}$. Now we define a function $g$ on $G^c \cup \{z : |z| \geq R\}$ as follows

$$g(z) = \begin{cases} f(z) & \text{if } z \in G^c, \\ 0 & \text{if } |z| \geq R. \end{cases}$$

We extend $g$ to a (real-valued) smooth function $F$ defined on all of $\mathbb{C}$. Sard’s theorem implies that $\{z : F(z) = c\}$ is a smooth submanifold of $\mathbb{C}$ for almost all $c \in [0, 1]$. Each level set $\{z : F(z) = c\}$ ($0 < c < 1$) is compact, because $F(z) = 0$ if $|z| \geq R$. Therefore almost every $c \in [0, 1]$ defines a finite union of disjoint closed smooth real curves in $\mathbb{C}$ which circumscribe $F = 1$. The homology class of this curve defines the element of $H_1(G, \mathbb{Z})$ corresponding to the function $f$. \hfill \Box

Lemma 3.2. Let $A$ be a closed subset of $\mathbb{C}$ and let $B$ be a bounded connected component of $A$. Assume that $B \neq A$ and let $q \in A \setminus B$. Then there exists a function $f \in \mathcal{C}_c(A, \mathbb{Z})$ which is identically 1 on $B$ such that $f(q) = 0$.

Proof. Connected components are closed. Hence $B$ is compact. Let $R > \max\{|z| : z \in B\}$. 


Define \( C = \{ z \in A : |z| = R \} \) and for each \( w \in C \) choose disjoint open subsets \( U_w, V_w \) of \( A \) with \( A = U_w \cup V_w \), \( B \subset U_w \) and \( w \in V_w \). Define \( f_w \) as the indicator function of \( U_w \), i.e.,

\[
f_w(z) = \begin{cases} 1 & \text{if } z \in U_w \\ 0 & \text{if } z \in A \setminus U_w = V_w. \end{cases}
\]

Now \( C \) is a compact set covered by the open sets \( V_w \) \((w \in C)\). Hence there is a finite set \( S \subset C \) with \( C \subset \bigcup_{w \in S} V_w \).

We define \( g(z) = \prod_{w \in S} f_w(z) \) observing that \( g \equiv 1 \) on \( B \) and \( g \equiv 0 \) on \( C \).

We choose a continuous function \( h : A \to \{0,1\} \) such that \( h \) equals 1 on \( B \) and \( h(q) = 0 \) (which is possible, since \( q \) lies in a connected component of \( A \) different from \( B \)).

Now we can define the function \( f \) we are looking for as

\[
f(z) = \begin{cases} g(z)h(z) & \text{if } z \in A \text{ and } |z| \leq R \\ 0 & \text{if } z \in A \text{ and } |z| > R. \end{cases}
\]

The function \( f \) is continuous on \( A \), because \( g(z) = 0 \) for all \( z \in A \) with \( |z| = R \), which implies that \( g(z)h(z) = 0 \) for \( |z| = R \). By construction its support is contained in the closed disc of radius \( R \) (and therefore compact) and we have \( f \equiv 1 \) on \( B \) and \( f(q) = 0 \).

**Proposition 3.3.** Let \( G \subset H \subset \mathbb{C} \) be open subsets. Then the following properties are equivalent:

(i) \( H^c = \mathbb{C} \setminus H \) intersects each bounded connected component of \( G^c \).

(ii) The restriction map from \( \mathcal{C}_c(G^c, \mathbb{Z}) \) to \( \mathcal{C}_c(H^c, \mathbb{Z}) \) is injective.

(iii) \( H_1(G, \mathbb{Z}) \to H_1(H, \mathbb{Z}) \) is injective.

**Proof.** The equivalence of properties (ii) and (iii) has been shown above.

We prove the equivalence of (i) and (ii). Let \( B \) be a bounded connected component of \( G^c \) with \( B \subset H \). Let \( f \in \mathcal{C}_c(G^c, \mathbb{Z}) \) be a function which equals 1 on \( B \) and assumes only 0 and 1 as values. (Such a function exists due to Lemma 3.2). Let \( K = \text{supp}(f) = \{ z : f(z) \neq 0 \} \) be its support and define \( C = K \setminus H \). For every \( x \in C \) we choose a function \( g_x \in \mathcal{C}_c(G^c, \mathbb{Z}) \) with \( g_x(x) = 0 \) and \( g_x \equiv 1 \) on \( B \). (This is
possible by Lemma 3.2, since $B$ is compact). Due to compactness of $C$ we may choose a finite subset $S$ of $C$ such that

$$C \subset \bigcup_{x \in S} \{ z \in G^c : g_x(z) = 0 \}.$$  

Define

$$g(z) = f(z) \cdot \Pi_{x \in S} g_x(z).$$

Then $g$ equals one on $B$ and vanishes identically on $C$. Since $\text{supp}(g) \subset \text{supp}(f) \subset K$, $C = K \setminus H$ and $g|_C \equiv 0$, it is clear that $g$ vanishes identically on $H^c$. Thus we have found a non-zero function $g \in \mathcal{C}_c(G^c, \{0, 1\})$ whose restriction to $H^c$ is zero. Therefore the existence of a bounded connected component $B$ of $G^c$ with $B \subset H$ implies that the restriction homomorphism $\mathcal{C}_c(G^c, \mathbb{Z}) \to \mathcal{C}_c(H^c, \mathbb{Z})$ is not injective.

To prove the opposite direction, let us assume that $B \cap H^c \neq \emptyset$ for every bounded connected component $B$ of $G^c$. Let $f \in \mathcal{C}_c(G^c, \mathbb{Z})$. Since $f$ is locally constant and has compact support, it must vanish identically on every unbounded connected component of $G^c$. Thus, if $f \neq 0$, there must be a bounded connected component $B$ of $G^c$ on which $f$ is not zero. Since by assumption $B \cap H^c$ is not empty, it follows that the restriction of $f$ to $H^c$ is not everywhere zero. This proves injectivity. 

$\square$

References

[1] Altavilla, A.; Bisi, C.: Log-biharmonicity and a Jensen formula in the space of quaternions, Ann. Acad. Sci. Fenn. Math., 44, n.2, (2019), 805-839. DOI: 10.5186/aasfm.2019.4447

[2] Angella, D.; Bisi, C.: Slice-quaternionic Hopf surfaces, Journal of Geom. Anal., 29, n.3, (2019), 1837-1858. https://doi.org/10.1007/s12220-018-0064-9

[3] Behnke, H.; Stein, K.: Entwicklung analytischer Funktionen auf Riemannschen Flächen, Math. Ann., 120, 430-461 (1949).

[4] Bisi, C.; Gentili, G.: M"obius transformations and the Poincaré distance in the quaternionic setting, Indiana Univ. Math. J., 58, (6) : 2729–2764, (2009).

[5] Bisi, C.; Gentili, G. : On the geometry of the quaternionic unit disc, Hypercomplex analysis and applications, 1-11, Trends Math., Birkhäuser/Springer Basel AG, Basel, (2011).

[6] Bisi, C.; Stoppato, C. : The Schwarz-Pick lemma for slice regular functions, Indiana Univ. Math. J., 61, (2012), no. 1, 297–317.

[7] Bisi, C.; Stoppato, C. : Regular vs. classical M"obius transformations of the quaternionic unit ball, Advances in hypercomplex analysis, 1-13, Springer INdAM Ser., 1, Springer, Milan, (2013).

[8] Bisi, C.; Stoppato, C. : Landau’s theorem for slice regular functions on the quaternionic unit ball, Internat. J. Math., 28, (2017), no. 3, 1750017, 21 pp.

[9] Bisi, C.; Gentili, G. : On quaternionic tori and their moduli space, Journal of Noncommutative Geometry, 12, Issue 2, (2018), 473-510.
[10] Bisi, C.; Winkelmann, J.: The harmonicity of slice regular functions, ArXiv: 1902.08165, To appear on Journal of Geometric Analysis.

[11] Bisi, C.; Winkelmann, J.: On a quaternionic Picard theorem, Proc. Amer. Math. Soc., Ser. B, 7, p. 106-117, (2020).

[12] Colombo, F.; Sabadini, I.; Struppa, D.: The Runge Theorem for slice hyperholomorphic functions. Proc. A.M.S., 139, no. 5, 1787-1803, (2011).

[13] Fornaess, J.E.; Forstneric, F.; Fornaess Wold, E.: Holomorphic approximation: the legacy of Weierstrass, Runge, Oka-Weil, and Mergelyan. ArXiv: 1802.03924. To appear as Chapter 5 in the volume Advancements in Complex Analysis, Springer-Verlag, (2020).

[14] Gal, S.G.; Sabadini, I.: Arakelian’s approximation theorem of Runge type in the hypercomplex setting. Indag. Math. (N.S.), 26, (2015), no. 2, 337–345.

[15] Gal, S.G.; Sabadini, I.: Approximation by polynomials on quaternionic compact sets. Math. Meth. Appl. Sci., (2015), 38, 3063–3074.

[16] Ghiloni, R.; Perotti, A.: Slice regular functions on real alternative algebras. Adv. Math., 226, (2), 1662–1691, (2011).

[17] Gentili, G.; Struppa, D.: A new approach to Cullen-regular functions of a quaternionic variable. C. R. Math. Acad. Sci. Paris, 342, no. 10, 741-744, (2006).

[18] Gentili, G.; Struppa, D.: A new theory of regular functions of a quaternionic variable. Adv. Math., 216, no. 1, 279-301, (2007).

[19] Lang, S.: Algebra. Springer Graduate texts in Mathematics, 211, (2002). Revised Third Edition.

[20] Remmert, R.: Classical Topics in Complex Function Theory. Springer, (1997).

Cinzia Bisi, Department of Mathematics and Computer Sciences, Ferrara University, Via Machiavelli 30, 44121 Ferrara, Italy
Email address: bsicnz@unife.it
ORCID: 0000-0002-4973-1053

Jörg Winkelmann, Lehrstuhl Analysis II, Fakultät für Mathematik, Ruhr-Universität Bochum, 44780 Bochum, Germany
Email address: joerg.winkelmann@rub.de
ORCID: 0000-0002-1781-5842