ON THE INVISCID BOUSSINESQ SYSTEM WITH ROUGH INITIAL DATA

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Abstract. We deal with the local well-posedness theory for the two-dimensional inviscid Boussinesq system with rough initial data of Yudovich type. The problem is in some sense critical due to some terms involving Riesz transforms in the vorticity-density formulation. We give a positive answer for a special sub-class of Yudovich data including smooth and singular vortex patches. For the latter case we assume in addition that the initial density is constant around the singular part of the patch boundary.

CONTENTS

1. Introduction 1
2. Tools and function spaces 5
3. Smooth patches 8
3.1. Proof of Theorem 1 9
3.2. A priori estimates 9
3.3. Existence 12
3.4. Uniqueness 13
4. Singular patches 13
4.1. Preliminaries 14
4.2. General statement 15
4.3. A priori estimates 16
4.4. Existence 22
4.5. Uniqueness 22
5. Appendix 24
References 25

1. Introduction

We consider the inviscid Boussinesq system describing the planar motion of a perfect incompressible fluid evolving under an external vertical force whose amplitude is proportional to the density which is in turn transported by the flow associated to the velocity field. The corresponding equations are given by,

\[
\begin{align*}
\partial_t v + v \cdot \nabla v + \nabla p &= \rho \vec{e}_2, \quad t \geq 0, x \in \mathbb{R}^2 \\
\partial_t \rho + v \cdot \nabla \rho &= 0, \\
\text{div} v &= 0, \\
v|_{t=0} &= v_0, \quad \rho|_{t=0} = \rho_0.
\end{align*}
\]

(1)

Here the vector field \( v = (v_1, v_2) \) and the scalar function \( \rho \) denote the fluid velocity and the pressure respectively. The density \( \rho \) is a passive scalar quantity and the buoyancy force \( \rho \vec{e}_2 \) in the velocity equation models the gravity effect on the fluid motion, where \( \vec{e}_2 \) stands for the unit vertical vector \((0, 1)\).

This system serves as a simplified model for the fluid dynamics of the oceans and atmosphere. It takes into account the stratification which plays a dominant role for large scales. For more details...
about this subject see for instance [4] and [33]. The derivation of the above system can be formally
done from the density dependent Euler equations through the Oberbeck-Boussinesq approximation
where the density fluctuation is neglected everywhere in the momentum equation except in the
buoyancy force. We point out that Feireisl and Novotný provide in [19] a rigorous justification of
the viscous model by means of scale analysis and singular limit of the full compressible Navier-
Stokes-Fourier system. Note that the system (1) coincides with the classical incompressible Euler
equations when the initial density \( \rho_0 \) is identically constant. Recall that Euler system is given by,
\[
\begin{align*}
\partial_t v + v \cdot \nabla v + \nabla p &= 0, \\
\text{div} v &= 0, \\
v|_{t=0} &= v_0.
\end{align*}
\]  

Before discussing some theoretical results on the well-posedness problem for the inviscid Boussinesq
equations we shall first start with the state of the art for the system (2). The local existence and
uniqueness of very smooth solutions for (2) goes back to Wolibner [37] in the thirties of the last
century. This result has been improved through the years by numerous authors and for several
functional spaces. The pioneering work in this field is accomplished by Kato and Ponce in [27]
who proved the local well-posedness in the framework of Sobolev spaces \( H^s \) with \( s > \frac{d}{2} + 1 \). This
result was later generalized for other spaces, see for instance [7, 10, 32, 36, 40] and the references
therein. Whether or not classical solutions develop singularities in finite time is still open except
some special cases as the planar motion or the axisymmetric flows without swirl. Unlike the viscous
models, the global theory for Euler equations has a geometric feature and relies crucially on the
vorticity dynamics. Historically, the concept of the vorticity \( \omega = \mathbf{rot} v \) and their basic laws were
studied by Helmholtz in his seminal work on the vortex motion theory [20]. More recently, a blow-up
vorticity criterion for Kato’s solutions was given by Beale, Kato and Majda in [3]: the lifespan \( T^* \)
is finite if and only if \( \int_0^{T^*} \| \omega(\tau) \|_{L^\infty} d\tau = +\infty \). In two dimensions the vorticity can be identified to
the scalar function \( \omega = \partial_1 v_2 - \partial_2 v_1 \) and it is transported by the flow,
\[
\partial_t \omega + v \cdot \nabla \omega = 0.
\]  

This leads to an infinite family of conservation laws. For example, we have \( \| \omega(t) \|_{L^p} = \| \omega_0 \|_{L^p} \)
for any \( p \in [1, \infty] \). Hence the global well-posedness of Kato’s solution follows from the Beale-Kato-
Majda criterion.

By using the formal \( L^p \) conservation laws it seems that we can relax the classical regularity and
construct global weak solutions in \( L^p \) spaces for \( p > 1 \). This question has been originally addressed
by Yudovich in [39], where he proved the existence and uniqueness of weak solution to 2D Euler
system only with the assumption \( \omega_0 \in L^p \cap L^\infty \). Under this pattern, the velocity is no longer in
the Lipschitz class but belongs to the log-Lipschitz functions. With a velocity being in this latter
class, it is proved that the flow map \( \psi \) defined below is uniquely defined in the class of continuous
functions in both space and time variables,
\[
\psi(t, x) = x + \int_0^t v(\tau, \psi(\tau)) d\tau.
\]

We can find more details about this subject in the book [10]. As a by-product we obtain the global
existence of the vortex patch structure. More precisely, if the initial vorticity \( \omega_0 = 1_{\Omega_0} \) is a patch,
that is, the characteristic function of a bounded domain \( \Omega_0 \) then its evolution is given \( \omega(t) = 1_{\Omega_t} \)
with \( \Omega_t \equiv \psi(t, \Omega_0) \). The regularity persistence of the boundary is very subtle and was successfully
accomplished by Chemin in [10] who showed in particular that when the boundary \( \partial \Omega_0 \) is better
than \( C^1 \), say in \( C^{1+\varepsilon} \) for \( 0 < \varepsilon < 1 \), then \( \partial \Omega_t \) will keep its initial regularity for all the time without
any loss. The proof relies heavily on the estimate of the Lipschitz norm of the velocity with the
co-normal regularity \( \partial X_\omega \) of the vorticity. The vector fields \( (X_t) \) are transported by the flow, that is,
\[
\partial_t X + v \cdot \nabla X = X \cdot \nabla v.
\]
The main advantage of this choice is the commutation of these vector fields with the transport operator $\partial_t + v \cdot \nabla$ which leads in turn to the master equation
\begin{equation}
(\partial_t + v \cdot \nabla)\partial_X \omega = 0.
\end{equation}
This means that the tangential derivative of the vorticity is also transported by the flow and this is crucial in the framework of the vortex patches. The proof given by Chemin is not restrictive to the usual patches but covers more singular data called generalized vortex patches. We point out that there is another proof in the special case of the vortex patches that can be found in [5].

In broad terms, he showed that the regular part of the initial boundary $\partial \Omega_0$ propagates with the same regularity without being affected by the singular part which by the reversibility of the problem cannot be smoothed out by the dynamics and becomes better than $C^1$. Furthermore, the velocity $v$ is Lipschitz far from the singular set and may undergo a blowup behavior near this set with a rate bounded by the logarithm of the distance from the singular set. Many similar studies have been subsequently implemented by numerous authors for bounded domains or viscous flows, see for instance [17, 12, 13, 16, 18, 21, 22, 34] and the references therein.

Now, bearing in mind that the system (1) is at a formal level a perturbation of the incompressible Euler equations, it is legitimate to see whether the known results for Euler equations work for the Boussinesq system as well. The earliest mathematical studies of the Boussinesq system and its dissipative counterpart are relatively recent and a great deal of attention has been paid to the local/global well-posedness problem, see for instance [1, 14, 15, 23, 24, 25, 26, 28, 31, 38]. Hereafter, we shall primarily restrict the discussion to the inviscid model described by (1) and recall some known facts on the classical solutions. We stress that this system can be seen as a hyperbolic one and therefore the commutator theory developed by Kato can be applied in a straightforward way. This was done by Chae and Nam in [8] who proved the local well-posedness when the initial data $(v_0, \rho_0)$ belong to the sub-critical Sobolev space $H^s$ with $s > 2$. A similar result was also established later by the same authors [9] for initial data lying in Hölderian spaces $C^r$ with $r > 1$.

Another local well-posedness result is recently obtained in [29] for the critical Besov spaces $B^{2/p+1}_{r,1}$, with $p \in ]1, +\infty[$. Furthermore, an analogous Beale-Kato-Majda criterion can be stated for the sub-critical cases. More precisely, it can be shown that Kato’s solutions cease to exist in finite time $T^*$ if and only if
\begin{equation}
\int_0^{T^*} \| \nabla \rho(t) \|_{L^\infty} dt = +\infty.
\end{equation}
For more details we refer the reader for instance to [29, 35]. Whether or not $T^*$ is finite remains an outstanding open problem.

The main scope of this paper is to deal with the local well-posedness for (1) when the initial data are rough and belong to Yudovich class. Contrary to the incompressible Euler equations the problem sounds extremely hard to solve for generic Yudovich data due to the violent coupling between the vorticity and the density. The difficulties can be illustrated from the vorticity-density formulation,
\begin{equation}
\begin{cases}
\partial_t \omega + v \cdot \nabla \omega = \partial_1 \rho, \\
\partial_t \rho + v \cdot \nabla \rho = 0,
\end{cases}
\end{equation}
According to the first equation in the above system one gets
\begin{equation}
\| \omega(t) \|_{L^\infty} \leq \| \omega_0 \|_{L^\infty} + \int_0^t \| \nabla \rho(\tau) \|_{L^\infty} d\tau.
\end{equation}
As we shall now see the estimate of the last integral requires the initial data to be more strong than what is allowed by Yudovich class. Indeed, the partial derivative $\partial_1 \rho$ obeys to the following transport model,
\begin{equation}
(\partial_t + v \cdot \nabla) \partial_j \rho = \partial_j v \cdot \nabla \rho.
\end{equation}
Consequently, the estimate of $\| \nabla \rho(t) \|_{L^\infty}$ requires the velocity field to be at least Lipschitz with respect to the space variable and unfortunately this is not necessary satisfied with a bounded vorticity. The main goal of this paper is to give a positive answer for the local well-posedness

\begin{equation}
\| \omega(t) \|_{L^\infty} \leq \| \omega_0 \|_{L^\infty} + \int_0^t \| \nabla \rho(\tau) \|_{L^\infty} d\tau.
\end{equation}
problem for a special class of Yudovich data. We shall in the first part prove the result for vortex patches with smooth boundary. In the second part we conduct the same study for patches with singular boundaries. Our first result reads as follows:

**Theorem 1.** Let $0 < \varepsilon < 1$ and $\Omega_0$ be a bounded domain of the plane with a boundary $\partial \Omega_0$ in Hölder class $C^{1+\varepsilon}$. Let $v_0$ be a divergence-free vector field of vorticity $\omega_0 = 1_{\Omega_0}$ and consider $\rho_0 \in L^2 \cap C^{1+\varepsilon}$ a real-valued function with $\nabla \rho_0 \in L^a$ and $1 < a < 2$. Then, there exists $T > 0$ such that the Boussinesq system (1) admits a unique local solution $v, \rho \in L^\infty([0,T], W^{1,\infty})$. Moreover, for all $t \in [0,T]$ the boundary of the advected domain $\Omega_t = \psi(t, \Omega_0)$ is of class $C^{1+\varepsilon}$.

Before giving some details about the proof we shall discuss few remarks.

**Remark 1.** The result of Theorem 1 will be extended in Theorem 4 to more general vortex structures. We shall get in particular a lower bound for the lifespan which is infinite for constant densities corresponding to the global result for Euler equations. More precisely we get

$$T^* \geq \frac{1}{C_0} \log \left(1 + C_0 \log \left(1 + C_0\|\nabla \rho_0\|_{L^\infty}\right)\right),$$

where $C_0 \triangleq C_0(\omega_0, \rho_0)$ depends continuously on the involved norms.

**Remark 2.** For the sake of a clear presentation we have assumed in Theorem 1 that the density $\rho_0 \in C^{1+\varepsilon}$. The persistence of such regularity is not clear and requires more than the Lipschitz norm for the velocity. However, as we shall see in Theorem 4 this condition can be relaxed to one that can be transported without loss: we replace this space by an anisotropic one.

The proof of Theorem 1 is firmly based on the formalism of vortex patches developed by Chemin in [10, 11]. The key is to estimate the tangential regularity $\partial_X \omega$ in the Hölder space of negative index $C^{\varepsilon-1}$, with respect to a suitable family of vector fields. Since this family commutes with the transport operator $\partial_t + v \cdot \nabla$ one gets easily the equation

$$(\partial_t + v \cdot \nabla)\partial_X \omega = \partial_X \partial_t \rho = \partial_1(\partial_X \rho) + [\partial_X, \partial_1] \rho.$$

By using para-differential calculus we can show that the commutator term is well-behaved and therefore the problem reduces to the estimate $\|\partial_X \rho\|_{C^\varepsilon}$. For this latter term we use anew the commutation between $\partial_X$ and the transport operator combined with the fact that the density is also conserved along the particle trajectories. Hence we find the equation

$$(\partial_t + v \cdot \nabla)\partial_X \rho = 0.$$

This structure is very important in our analysis in order to derive some crucial a priori estimates.

Let us move on to the second contribution of this paper which is concerned with the singular vortex patches. We shall assume that $\omega_0 = 1_{\Omega_0}$ but the boundary may now contain a singular subset. As the example of the square indicates, the velocity associated to a vortex patch is not in general Lipschitz and this will bring more technical difficulties. Similarly to the smooth boundary one needs to bound $\|\nabla \rho(t)\|_{L^\infty}$ and from the characteristic method we obtain

$$\|\partial_j \rho(t)\|_{L^\infty} \leq \|\nabla \rho_0\|_{L^\infty} + \int_0^t \|\partial_j v \cdot \nabla \rho(t)\|_{L^\infty}.$$

We expect the singularities initially located at the boundary to be frozen in the particle trajectories and the idea to treat the last integral term is to annihilate the effects of the velocity singularities by some specific assumptions on the density. As a possible choice we shall assume the initial density to be constant around the singularity set and from its transport structure the density will remain constant around the image by the flow of the singular set. This allows to track the singularities and kill their nasty effects by the density. Our result reads as follows:

**Theorem 2.** Let $0 < \varepsilon < 1$ and $\Omega_0$ be a bounded domain of the plane whose boundary $\partial \Omega_0$ is a curve of class $C^{1+\varepsilon}$ outside a closed set $\Sigma_0$. Let us consider a divergence-free vector field $v_0$ of vorticity $\omega_0 = 1_{\Omega_0}$ and take $\rho_0 \in L^2 \cap C^{\varepsilon+1}$ with $\nabla \rho_0 \in L^a$ for some $1 < a < 2$. Suppose that $\rho_0$ is
constant in a small neighborhood of \( \Sigma_0 \). Then the system (1) admits a unique local solution \((\omega, \rho)\) such that
\[
\omega, \rho \in L^\infty([0, T], L^2 \cap L^\infty), \quad \nabla \rho \in L^\infty([0, T], L^q \cap L^\infty).
\]
Furthermore, the velocity \( v \) is Lipschitz outside \( \Sigma_t \triangleq \psi(t, \Sigma_0) \). More precisely, we have
\[
\sup_{h \in (0, e^{-1}]} \frac{\|\nabla v(t)\|_{L^\infty((\Sigma_t)_h^c)}}{-\log h} \in L^\infty([0, T]),
\]
where the set \((\Sigma_t)^c_h\) is defined by,
\[
(\Sigma_t)^c_h \triangleq \{ x \in \mathbb{R}^2; d(x, \Sigma(t)) \geq h \}.
\]
In addition, the boundary of \( \psi(t, \Omega_0) \) is locally in \( C^{1+\varepsilon} \) outside the set \( \Sigma_t \).

**Remark 3.** Let us mention that the initial singular set is not arbitrary and should satisfy a weak condition of the following type: there exists two strictly positive real numbers \( \gamma \) and \( C \) and a neighborhood \( V_0 \) of \( \partial \Omega_0 \) such that for any point \( x \in V_0 \) we have
\[
|\nabla f(x)| \geq Cd(x, \Sigma_0)^\gamma.
\]
Here the function \( f : \mathbb{R}^2 \to \mathbb{R} \) is smooth and satisfies
\[
\Omega_0 = \{ x, f(x) > 0 \}, \partial \Omega_0 = \{ x \in \mathbb{R}^2, f(x) = 0 \}.
\]
This means that the curves defining the boundary of \( \Omega_0 \) are not tangent to one another at infinite order at the singular points.

The general outline of the paper is as follows. In the next section we recall some function spaces and give some of their useful properties, we also gather some preliminary estimates. Section 3 is devoted to the study of the regular vortex patches and the last section concerns the singular case. We close this paper with an appendix covering the proof of a technical lemma.

2. **Tools and Function Spaces**

Throughout this paper, \( C \) stands for some real positive constant which may be different in each occurrence and \( C_0 \) for a positive constant depending on the size of the initial data. We shall sometimes alternatively use the notation \( X \lesssim Y \) for an inequality of the type \( X \leq CY \).

Let us start with the dyadic partition of the unity whose proof can be found for instance in [10]. There exists a radially symmetric function \( \varphi \) in \( \mathcal{D}(\mathbb{R}^2 \setminus \{0\}) \) such that
\[
\forall \xi \in \mathbb{R}^2 \setminus \{0\}, \quad \sum_{q \in \mathbb{Z}} \varphi(2^{-q}\xi) = 1.
\]
We define the function \( \chi \in \mathcal{D}(\mathbb{R}^2) \) by
\[
\forall \xi \in \mathbb{R}^2, \quad \chi(\xi) = 1 - \sum_{q \geq 0} \varphi(2^{-q}\xi).
\]
For every \( u \in \mathcal{S}'(\mathbb{R}^2) \) one defines the non homogeneous Littlewood-Paley operators by,
\[
\Delta_{-1}v = \mathcal{F}^{-1}(\hat{\varphi} \hat{v}), \quad \forall q \in \mathbb{N} \quad \Delta_q v = \mathcal{F}^{-1}(\hat{\varphi}(2^{-q}\cdot) \hat{v}) \quad \text{and} \quad S_q v = \sum_{-1 \leq j \leq q-1} \Delta_j v.
\]
We notice that these operators map continuously \( L^p \) to itself uniformly with respect to \( q \) and \( p \). Furthermore, one can easily check that for every tempered distribution \( v \), we have
\[
v = \sum_{q \geq -1} \Delta_q v.
\]
By choosing in a suitable way the support of \( \varphi \) one can easily check the almost orthogonality properties: for any \( u, v \in \mathcal{S}'(\mathbb{R}^2) \),
\[
\Delta_p \Delta_q u = 0 \quad \text{if} \quad |p - q| \geq 2
\]
\[
\Delta_p (S_{q-1} u \Delta_q v) = 0 \quad \text{if} \quad |p - q| \geq 5.
\]
We can now give a characterization of the Hölder spaces using the Littlewood-Paley decomposition.

**Definition 1.** For all \( s \in \mathbb{R} \), we denote by \( C^s \) the space of tempered distributions \( v \) such that
\[
\|v\|_s \triangleq \sup_{q \geq -1} 2^q \|\Delta_q v\|_{L^\infty} < +\infty.
\]

**Remark 4.** We notice that for any strictly positive non integer real number \( s \) this definition coincides with the usual Hölder space \( C^s \) with equivalent norms. For example if \( s \in ]0,1[ \),
\[
\|v\|_{C^s} \triangleq \|v\|_{L^\infty} + \sup_{x \neq y} \frac{|v(x) - v(y)|}{|x - y|^s} \leq \|v\|_s.
\]

Next, we recall Bernstein inequalities, see for example [10].

**Lemma 1.** There exists a constant \( C > 0 \) such that for all \( q \in \mathbb{N}, k \in \mathbb{N}, 1 \leq a \leq b \leq \infty \) and for every tempered distribution \( u \) we have
\[
\sup_{|\alpha| \leq k} \|\partial^\alpha S_q u\|_{L^b} \leq C^{k} 2^{q(k + 2(\frac{1}{b} - \frac{1}{s}))}\|S_q u\|_{L^a},
\]
\[
C^{-k} 2^k \|\tilde{\Delta}_q u\|_{L^b} \leq \sup_{|\alpha| = k} \|\partial^\alpha \tilde{\Delta}_q u\|_{L^b} \leq C^{k} 2^{qk}\|\tilde{\Delta}_q u\|_{L^b}.
\]

Now, we introduce the Bony’s decomposition [6] which is the basic tool of the para-differential calculus. Formally the product of two tempered distributions \( u \) and \( v \) is split into three parts as follows:
\[
uv = Tu v + Tv u + R(u, v),
\]
where
\[
T_u v = \sum_q S_{q-1} u \Delta_q v \quad \text{and} \quad R(u, v) = \sum_q \Delta_q u \tilde{\Delta}_q v,
\]
with \( \tilde{\Delta}_q = \sum_{i=1}^{q+1} \Delta_q i \).

The following lemma clarifies the behavior of the paraproduct operators in the Hölder spaces.

**Lemma 2.** Let \( s \) be a real number. If \( s < 0 \) the bilinear operator \( T \) is continuous from \( L^\infty \times C^s \) in \( C^s \) and from \( C^s \times L^\infty \) in \( C^s \). Moreover, we have
\[
\|T_u v\|_s + \|T_v u\|_s \leq C \|u\|_{L^\infty} \|v\|_s.
\]
If \( s > 0 \) the remainder operator \( R \) is continuous from \( L^\infty \times C^s \) in \( C^s \). Furthermore, we have
\[
\|R(u, v)\|_s \leq C \|u\|_{L^\infty} \|v\|_s.
\]

Where \( C \) is a positive constant depending only on \( s \).

As a result, we have the following corollary.

**Corollary 1.** Let \( \varepsilon \in ]0,1] \), \( X \) be a vector field belonging to \( C^s \) as well as its divergence and \( f \) be a Lipschitz scalar function. Then for \( j \in \{1, 2\} \) we have
\[
\|\partial_j X \cdot \nabla f\|_{\varepsilon - 1} \leq C \|\nabla f\|_{L^\infty} (\|\div X\|_{\varepsilon} + \|X\|_{\varepsilon}).
\]

**Proof.** In view of Bony’s decomposition we write
\[
\|\partial_j X \cdot \nabla f\|_{\varepsilon - 1} \leq \|T_{\partial_j X, \partial_i f}\|_{\varepsilon - 1} + \|T_{\partial_i j, \partial_j X^i}\|_{\varepsilon - 1} + \|R(\partial_j X^i, \partial_i f)\|_{\varepsilon - 1},
\]
where we have adopted in the right-hand side of the last inequality the Einstein summation convention for the index \( i \). Since \( \varepsilon - 1 < 0 \) the previous lemma ensures that
\[
\|T_{\partial_j X, \partial_i f}\|_{\varepsilon - 1} + \|T_{\partial_i j, \partial_j X^i}\|_{\varepsilon - 1} \leq C \|\nabla f\|_{L^\infty} \|X\|_{\varepsilon}.
\]

For the remainder term we write
\[
R(\partial_j X^i, \partial_i f) = \partial_j R(X^i, \partial_i f) - \partial_i R(X^i, \partial_j f) + R(\div X, \partial_j f).
\]
Using once again Lemma 2 we get
\begin{align*}
\|R(\partial_j X^i, \partial_i f)\|_{\epsilon - 1} & \lesssim \|R(X^i, \partial^j f)\|_{\epsilon} + \|R(X, \partial_j f)\|_{\epsilon} + \|R(\text{div } X, \partial_j f)\|_{\epsilon} \\
& \lesssim \|\nabla f\|_{L^\infty} \|X\|_{\epsilon} + \|\nabla f\|_{L^\infty} \|\text{div } X\|_{\epsilon}.
\end{align*}

This concludes the proof of the corollary. \qed

In the next section we will need the following result dealing with the Hölderian regularity persistence for the transport equations. Its proof is given in page 66 from [10].

Lemma 3. Let \( v \) be a smooth divergence-free vector field and let \( r \in ]-1, 1[ \). Let us consider \((f, g)\) a couple of functions belonging to \( L^\infty_{\text{loc}}(\mathbb{R}) \times L^1_{\text{loc}}(\mathbb{R}) \) and such that
\[
\partial_t f + v \cdot \nabla f = g.
\]
Then we have
\[
\|f(t)\|_r \lesssim \|f(0)\|_r e^{C \int_0^t \|\nabla v(\tau)\|_{L^\infty} \, d\tau} + \int_0^t \|g(\tau)\|_r e^{C \int_0^\tau \|\nabla v(\sigma)\|_{L^\infty} \, d\sigma} \, d\tau
\]
(8)
The constant \( C \) depends only on \( r \).

Next, we notice that if \( v \) is divergence-free and decaying at infinity then it can be recovered from its vorticity \( \omega \triangleq \text{rot } v \) by means of the Biot-Savart law
\[
v(x) = \frac{1}{2\pi} \int_{\mathbb{R}^2} \frac{(x - y)^\perp}{|x - y|^2} \omega(y) \, dy.
\]
(9)
Now we briefly recall the Calderón-Zygmund estimate that will be frequently used through this paper.

Proposition 1. There exists a positive constant \( C \) satisfying the following property. For any smooth divergence-free vector field \( v \) with vorticity \( \omega \in L^p \) and \( p \in ]1, \infty[ \) one has
\[
\|\nabla v\|_{L^p} \leq C \frac{p^2}{p - 1} \|\omega\|_{L^p}.
\]
(10)

In order to extend the results stated in the introduction to various geometries, we shall introduce some useful notations and definitions. Namely, we define the anisotropic Besov spaces with respect to slight smooth vector fields. This approach has been initially developed by J.-Y. Chemin in [10] in order to treat the vortex patch problem for the incompressible Euler system.

Definition 2. Let \( \Sigma \) be a closed set of the plane and \( \varepsilon \in (0, 1) \). Let \( X = (X_\lambda)_{\lambda \in \Lambda} \) be a family of vector fields. We say that this family is admissible of class \( C^\varepsilon \) outside \( \Sigma \) if and only if :

(i) Regularity: \( X_\lambda, \text{div } X_\lambda \in C^{\varepsilon} \).

(ii) Non degeneracy:
\[
I(\Sigma, X) \triangleq \inf_{x \notin \Sigma} \sup_{\lambda \in \Lambda} |X_\lambda(x)| > 0.
\]

We set
\[
\|X_\lambda\|_\varepsilon \triangleq \|X_\lambda\|_\varepsilon + \|\text{div } X_\lambda\|_{\varepsilon - 1},
\]
and
\[
N_\varepsilon(\Sigma, X) \triangleq \sup_{\lambda \in \Lambda} \frac{\|X_\lambda\|_\varepsilon}{I(\Sigma, X)}.
\]
For each element \( X_\lambda \) of the preceding family we define its action on bounded real-valued functions \( u \) in the weak sense as follows:
\[
\partial X_\lambda u \triangleq \text{div}(u X_\lambda) - u \text{ div } X_\lambda.
\]
Definition 3. Let $\varepsilon \in (0, 1)$, $k \in \mathbb{N}$ and $\Sigma$ be a closed set of the plane. Consider a family of vector fields $X = (X_\lambda)_\lambda$ as in the Definition 2. We denote by $C^{\varepsilon+k}(\Sigma, X)$ the space of functions $u \in W^{k,\infty}$ such that
\[
\sum_{|\alpha| \leq k} \|\partial^\alpha u\|_{L^\infty} + \sup_{\lambda \in \Lambda} \|\partial X_\lambda u\|_{\varepsilon+k-1} < +\infty,
\]
and we set
\[
\|u\|_{\Sigma, X}^{\varepsilon+k} \triangleq N_\varepsilon(\Sigma, X) \sum_{|\alpha| \leq k} \|\partial^\alpha u\|_{L^\infty} + \sup_{\lambda \in \Lambda} \frac{\|\partial X_\lambda u\|_{\varepsilon+k-1}}{I(\Sigma, X)}.
\]

Remark 5. When $\Sigma$ is empty we will merely say that the set of vector fields $(X_\lambda)_{\lambda \in \Lambda}$ is admissible and to make the notation less cluttered we shall withdraw the symbol $\Sigma$ from the previous definitions. For example, we use simply $I(X)$ instead of $I(X, \Sigma)$ and $\|\cdot\|_{\Sigma, X}^{\varepsilon+k}$ instead of $\|\cdot\|_{\Sigma, X}^{\varepsilon+k}$.

The next result deals with a logarithmic estimate established in [10] which is the main key in the study of the generalized vortex patches.

Theorem 3. There exists an absolute constant $C$ such that for any $a \in (1, \infty), \varepsilon \in (0, 1)$ we have the following property. Let $\Sigma$ be a closed set of the plane and $X$ be a family of vector fields as in Definition 2. Consider a function $\omega \in C^\varepsilon(\Sigma, X) \cap L^a$. Let $v$ be the divergence-free vector field with vorticity $\omega$, then we get:
\[
\|\nabla v\|_{L^\infty(\Sigma)} \leq C_\varepsilon \|\omega\|_{L^a} + \frac{C_\varepsilon}{\varepsilon} \|\omega\|_{L^\infty} \log \left(\frac{\varepsilon + \|\omega\|_{\Sigma, X}}{\|\omega\|_{L^\infty}}\right).
\]

3. Smooth patches

In this section we shall state a local well-posedness result for the system (1) with general initial data covering the result of Theorem 1. The main result of this section is the following.

Theorem 4. Let $0 < \varepsilon < 1, a \in (1, \infty)$ and $X_0 = (X_{0,\lambda})_{\lambda \in \Lambda}$ be an admissible family of vector fields of class $C^\varepsilon$. Let $v_0$ be a divergence-free vector field whose vorticity $\omega_0$ belongs to $L^a \cap C^\varepsilon(X_0)$ and $\rho_0$ be a real-valued function belonging to $L^2 \cap C^{\varepsilon+1}(X_0)$ with $\nabla \rho_0 \in L^a$. Then there exists $T > 0$ such that the inviscid Boussinesq system (1) admits a unique solution $(v, \rho) \in L^\infty_t([0, T], \text{Lip}(\mathbb{R}^2)) \times L^\infty_{loc}([0, T], \text{Lip}(\mathbb{R}^2) \cap L^2)$ such that $\omega \in L^\infty([0, T], L^a \cap L^\infty)$. Moreover, for all $t \in [0, T]$ the transported $X_t$ of $X_0$ by the flow $\psi$, defined by
\[
X_{t,\lambda}(x) \triangleq \left(\partial X_{0,\lambda} \psi(t)\right)(\psi^{-1}(t, x)),
\]
is admissible of class $C^\varepsilon$ and
\[
\rho(t) \in C^{\varepsilon+1}(X_t) \quad \text{and} \quad \omega(t) \in C^\varepsilon(X_t).
\]
In addition,
\[
T \geq \frac{1}{C_0} \log \left(1 + C_0 \log \left(1 + C_0/\|\nabla \rho_0\|_{L^\infty}\right)\right) \triangleq T_0
\]
where $C_0 \triangleq C_0(\omega_0, \rho_0)$ depends continuously on the norms of the initial data.

Remark 6. The Theorem 4 can be applied to a larger class of initial data than the vortex patches class. For example, we may take $\omega_0 = \bar{\omega}_0 \mathbf{1}_{\Omega_0}$ with $\Omega_0$ a bounded domain of class $C^{\varepsilon+1}$ and $\bar{\omega}_0$ a function of class $C^\varepsilon(\mathbb{R}^2)$ for some $\varepsilon \in ]0, 1[$.

We shall now make precise the boundary regularity used in the main theorems.

Definition 4. Let $0 < \varepsilon < 1$ and $\Omega$ be a bounded domain in $\mathbb{R}^d$. We say that $\Omega$ is of class $C^{1+\varepsilon}$ if there exists a compactly supported function $f \in C^{1+\varepsilon}(\mathbb{R}^2)$ and a neighborhood $V$ of $\partial \Omega$ such that
\[
\partial \Omega = f^{-1}([0]) \cap V \quad \text{and} \quad \nabla f(x) \neq 0 \quad \forall x \in V.
\]
Let us see how to deduce the results of Theorem 1 from the preceding one.
3.1. Proof of Theorem 1. To begin with, we shall construct an admissible family of vector fields $X_0$ for which the initial vorticity $ω_0 = 1_{Ω_0}$ satisfies the tangential regularity property. In view of the previous definition, there exists a real function $f_0 \in C^{1+ε}$ and a neighborhood $V_0$ such that $Ω_0 = V_0 \cap f^{-1}\{(0)\}$ and $∇f_0 \neq 0$ on $V_0$. Let $\tilde{α}$ be a smooth function supported in $V_0$ and taking the value 1 in a small neighborhood of $V_1 \subset V_0$. We set

$$X_{0,0} = ∇⊥f_0, \quad X_{0,1} = (1 - \tilde{α})(\frac{1}{0})$$.

The first vector field is of class $C^ε$ with zero divergence, the second is $C^\infty$ and a simple verification shows that the family of vector fields $(X_{0,i})_{i\in\{0,1\}}$ is admissible. Besides, since the derivative of $ω_0$ along the direction $∇⊥f_0$ is zero and $1 - \tilde{α}$ vanishes on $V_0$ then we have $\partial X_{0,0}ω_0 = 0$.

Also, the fact that $ρ_0 \in C^{ε+1}$ implies that $ρ_0 \in C^ε(Ω_0)$ for all $t \leq T_0$. Therefore Theorem 1 provides a unique local solution $(v, ρ) \in L^∞_{loc}(Ω_0, L^p(\mathbb{R}^2))^2$ to (1). For the regularity of the transported initial domain $Ω_t = \psi(t,Ω_0)$, we consider $γ^0 \in C^{ε+1}(\mathbb{R}^+, \mathbb{R}^2)$ a parametrization of $∂Ω_0$ given by

$$\begin{align*}
\partial γ^0 &= ∇⊥f_0(γ^0(σ)), \\
γ^0(0) &= x_0 ∈ ∂Ω_0.
\end{align*}$$

Set $γ_t(σ) = ψ(t, γ^0(σ))$, then by differentiating with respect to the parameter $σ$ we get

$$\begin{align*}
\partial γ_t(σ) &= (∂X_{0,0}ψ)(t, γ^0(σ)), \\
γ_t(0) &= ψ(t, x_0).
\end{align*}$$

From Theorem 4, $∂X_{0,0}ψ$ belongs to $L^∞_{loc}(Ω_0, C^ε)$, then $γ_t$ belongs to $L^∞_{loc}(Ω_0, C^{ε+1})$ for all $t ≤ T_0$. Finally, as $X_{0,0}$ does not vanish on $V_0$, then it is the same for $∂X_{0,0}ψ$, therefore, $∂γ_t$ does not vanish on $\mathbb{R}$ as indicated by the estimate (15). Consequently, $γ_t$ is a regular parameterization of $∂Ω_t$.

3.2. A priori estimates. This part is the core of the proof of Theorem 4. As a matter of fact, we aim here to propagate the regularity of the initial data, namely, to bound the norms $∥ω(t)∥_{L^p∩L^∞}$ and $∥∇ρ(t)∥_{L^1∩L^∞}$. Even though these quantities seem to be less regular than $∥∇v(t)∥_{L^1L^∞}$ , it is not at all clear how to estimate them without involving the latter quantity. It comes then to show the two following propositions: The first deals with the $L^p$ estimates and the second is related on the estimate of the Lipschitz norm for the solution of the system 1.

Proposition 2. Let $(v, ρ)$ be a smooth solution of the Boussinesq system (1) defined on the time interval $[0, T]$. Then, for all $p ∈ [1, +∞]$ and $t ≤ T$ we have

$$∥ω(t)∥_{L^p} ≤ ∥ω_0∥_{L^p} + ∥∇ρ_0∥_{L^p} e^{CV(t)}t.$$ (12)

and

$$∥∇ρ(t)∥_{L^p} ≤ ∥∇ρ_0∥_{L^p} e^{CV(t)}.$$ (13)

with the notation:

$$V(t) \triangleq \int_0^t ∥∇v(τ)∥_{L^∞}dτ.$$ 

Proof. Using the vorticity equation (6) we can easily see that for all $1 ≤ p ≤ ∞$,

$$∥ω(t)∥_{L^p} ≤ ∥ω_0∥_{L^p} + ∫_0^t ∥∇ρ(τ)∥_{L^p}dτ.$$ (14)

Next, applying the partial derivative operator $∂j$ to the second equation of the system (1), we get

$$∂j∂jρ + v · ∇(∂jρ) = ∂jv · ∇ρ.$$ 

Hence, for all $1 ≤ p ≤ ∞$, we obtain

$$∥∂jρ(t)∥_{L^p} ≤ ∥∇ρ_0∥_{L^p} + ∫_0^t ∥∇ρ(τ)∥_{L^p}∥∇v(τ)∥_{L^∞}dτ.$$ 

According to the Gronwall lemma we conclude that

$$∥∇ρ(t)∥_{L^p} ≤ ∥∇ρ_0∥_{L^p} e^{CV(t)}.$$
Plugging this estimate into (14) gives,
\[ \|\omega(t)\|_{L^p} \leq \|\omega_0\|_{L^p} + \|\nabla \rho_0\|_{L^p} e^{CV(t)} t; \quad \forall 1 \leq p \leq \infty. \]

Next we shall discuss the Lipschitz norm of the velocity. This parts uses the formalism of the vortex patches. Our result reads as follows.

**Proposition 3.** Let \( 0 < \varepsilon < 1, a > 1 \) and \( X_0 \) be an admissible family of vector fields of class \( C^\varepsilon \).
Let \((v, \rho)\) be a smooth solution of the Boussinesq system (1) defined on the time interval \([0, T^\ast]\).
Then there exists \( 0 < T_0 \leq T^\ast \) such that for all time \( t \leq T_0 \) we have
\[ \|\nabla v(t)\|_{L^\infty} \leq C_0. \]
The proof of this proposition is firmly based on the following lemma.

**Lemma 4.** There exists a constant \( C \) such that for any smooth solution \((v, \rho)\) of (1) on \([0, T]\), and any time dependent family of vector field \( X_t \) transported by the flow of \( v \), we have for all \( t \in [0, T] \),
\[
I(X_t) \geq I(X_0) e^{-V(t)},
\]
\[
\|\text{div} X_{t,\lambda}\|_\varepsilon \leq \|\text{div} X_{0,\lambda}\|_\varepsilon e^{CV(t)}. \tag{15}
\]

\[
\|X_t\|_\varepsilon + \|\partial X_{t,\lambda} \omega\|_{\varepsilon-1} \leq C \left( \|X_{0,\lambda}\|_\varepsilon + \|\partial X_{0,\lambda} \omega\|_{\varepsilon-1} + \|\partial X_{0,\lambda} \rho_0\|_\varepsilon \right) e^{CV_1} e^{CV(t)}
\times \exp \left( t \|\nabla \rho_0\|_{L^\infty} e^{CV(t)} \right). \tag{16}
\]

\[
\|\partial X_{t,\lambda} \rho\|_\varepsilon \leq \|\partial X_{0,\lambda} \rho_0\|_\varepsilon e^{CV(t)}. \tag{17}
\]

where
\[ V(t) \triangleq \int_0^t \|\nabla v(\tau)\|_{L^\infty} d\tau. \]

**Proof.** Taking the derivative of term \( \partial X_{0,\lambda} \psi(t, x) \) with respect to the time \( t \) we get
\[
\begin{cases}
\partial_t \partial X_{0,\lambda} \psi(t, x) = \nabla v(t, \psi(t, x)) \partial X_{0,\lambda} \psi(t, x), \\
\partial X_{0,\lambda} \psi(0, x) = X_{0,\lambda}.
\end{cases} \tag{18}
\]

Using the time reversibility of this equation combined with Gronwall’s lemma we find
\[ |X_{0,\lambda}(x)| \leq |\partial X_{0,\lambda} \psi(t, x)| e^{V(t)}. \]
From the Definition 2 and the relation (11) we obtain the desired he estimate (15).
It is easy to check from the relation (18) that
\[ \partial_t X_{t,\lambda} + v \cdot X_{t,\lambda} = \partial X_{t,\lambda} v. \tag{19} \]
Applying the divergence operator to the equation (19) we obtain,
\[ (\partial_t + v \cdot \nabla) \text{div} X_{t,\lambda} = 0, \]
and therefore we may use Lemma 3 leading to the estimate (16).
Next, we intend to establish (17). For this goal we start with the following result whose proof is given in Lemma 3.3.2 of [10],
\[ \|\partial X_{t,\lambda} v(t)\|_\varepsilon \lessapprox \|\nabla v(t)\|_{L^\infty} \|X_{t,\lambda}\|_\varepsilon + \|\partial X_{t,\lambda} \omega(t)\|_{\varepsilon-1}. \]
Applying Lemma 3 to equation (19) we get
\[ \|X_{t,\lambda}\|_\varepsilon \leq e^{CV(t)} \left( \|X_{0,\lambda}\|_\varepsilon + C \int_0^t \|\nabla v(\tau)\|_{L^\infty} \|X_{\tau,\lambda}\|_\varepsilon + \|\partial X_{\tau,\lambda} \omega(\tau)\|_{\varepsilon-1} e^{-CV(\tau)} d\tau \right). \]
Putting this estimate with (16) yields
\[
\|X_{t,\lambda}\|_\varepsilon \leq e^{CV(t)} \left( \|X_{0,\lambda}\|_\varepsilon + C \int_0^t \|\nabla v(\tau)\|_{L^\infty} \|X_{\tau,\lambda}\|_\varepsilon + \|\partial X_{\tau,\lambda} \omega(\tau)\|_{\varepsilon-1} e^{-CV(\tau)} d\tau \right). \tag{20}
\]
Since $\partial_{Xt,\lambda}$ commutes with the transport operator $\partial_t + v \cdot \nabla$, then
\[
(\partial_t + v \cdot \nabla) \partial_{Xt,\lambda} \omega = \partial_{Xt,\lambda} \partial_t \rho
\]
and consequently we get in view of Lemma 3
\[
\|\partial_{Xt,\lambda} \omega(t)\|_{e^{-1}} \leq e^{CV(t)} \left( \|\partial_{X_{0,\lambda}} \omega_0\|_{e^{-1}} + C \int_0^t \|\partial_{X_{t,\lambda}} \partial_t \rho(\tau)\|_{e^{-1}} e^{-CV(\tau)} d\tau \right). \tag{21}
\]
Observe that
\[
\partial_{Xt,\lambda} \partial_t \rho = \partial_t (\partial_{Xt,\lambda} \rho) - \partial_{Xt,\lambda} \partial_{Xt,\lambda} \rho,
\]
and thus
\[
\|\partial_{Xt,\lambda} \partial_t \rho(\tau)\|_{e^{-1}} \lesssim \|\partial_{Xt,\lambda} \partial_{Xt,\lambda} \rho(\tau)\|_{e} + \|\partial_t \rho(\tau)\|_{e^{-1}} \lesssim \|\partial_{Xt,\lambda} \partial_{Xt,\lambda} \rho(\tau)\|_{e} + \|\nabla \rho(\tau)\|_{L^\infty} \|X_{t,\lambda}\|_{e}, \tag{23}
\]
where we have used in the last inequality Corollary 1.

To estimate the term $\|\partial_{Xt,\lambda} \rho(\tau)\|_{e}$ we use once again the commutation between $\partial_{Xt,\lambda}$ and the transport operator leading to,
\[
(\partial_t + v \cdot \nabla) \partial_{Xt,\lambda} \rho = 0. \tag{24}
\]
Applying Lemma 3 gives
\[
\|\partial_{Xt,\lambda} \rho(t)\|_{e} \lesssim \|\partial_{X_{0,\lambda}} \rho_0\|_{e} e^{CV(t)}
\]
which yields according to (23)
\[
\|\partial_{Xt,\lambda} \partial_t \rho(\tau)\|_{e^{-1}} \lesssim \|\partial_{X_{0,\lambda}} \rho_0\|_{e} e^{CV(t)} + \|\nabla \rho(\tau)\|_{L^\infty} \|X_{t,\lambda}\|_{e}.
\]
Plugging this estimate into (21) implies
\[
\|\partial_{Xt,\lambda} \omega(t)\|_{e^{-1}} \lesssim e^{CV(t)} \left( \|\partial_{X_{0,\lambda}} \omega_0\|_{e^{-1}} + \|\partial_{X_{0,\lambda}} \rho_0\|_{e} t + \int_0^t \|\nabla \rho(\tau)\|_{L^\infty} \|X_{t,\lambda}\|_{e} e^{-CV(\tau)} d\tau \right).
\]
Hence, putting together the foregoing estimate and (20) we get
\[
\Gamma(t) \lesssim \Gamma(0) + \|\partial_{X_{0,\lambda}} \rho_0\|_{e} t + \int_0^t \left( \|\nabla \rho\|_{L^\infty} + \|\nabla v\|_{L^\infty} + 1 \right) \Gamma(\tau) d\tau,
\]
with $\Gamma(t) \triangleq (\|\partial_{Xt,\lambda} \omega(t)\|_{e^{-1}} + \|X_{t,\lambda}\|_{e}) e^{-CV(t)}$. Then Gronwall’s lemma implies that
\[
\Gamma(t) \lesssim \left( \Gamma(0) + \|\partial_{X_{0,\lambda}} \rho_0\|_{e} \right) e^{C \int_0^t \left( \|\nabla \rho\|_{L^\infty} + \|\nabla v\|_{L^\infty} + 1 \right) d\tau}.
\]
Finally, Proposition 2 gives the desired result.

\[\Box\]

**Proof of the Proposition 3.** Combining the inequality (12) with the estimate (17) we find
\[
\|\partial_{Xt,\lambda} \omega(t)\|_{e^{-1}} + \|\omega(t)\|_{L^\infty} \|X_{t,\lambda}\|_{e} \leq (1 + \|\omega_0\|_{L^\infty}) \Gamma(0) + \|\partial_{X_{0,\lambda}} \rho_0\|_{e} C e^C \|\nabla \rho_0\|_{L^\infty} e^{CV(t)}.
\]
Putting together the last estimate and the inequality (15) then we get according to the Definition 3
\[
\|\omega(t)\|_{X_t} \leq C_0 e^{CV(t)} e^{C t} C e^{CV(t)} \|\nabla \rho_0\|_{L^\infty} e^{CV(t)}, \tag{25}
\]
According to the Proposition 3 and the monotonicity of the map $x \mapsto x \log (e + \frac{x}{t})$ we find
\[
\|\nabla v(t)\|_{L^\infty} \leq C \left( \|\omega_0\|_{L^\infty} + t \|\nabla \rho_0\|_{L^\infty} e^{CV(t)} \right) \log \left( e + \frac{\|\omega(t)\|_{X_t}}{\|\omega_0\|_{L^\infty}} \right).
\]
It follows from the estimate (25)
\[
\|\nabla v(t)\|_{L^\infty} \leq C \left( \|\omega_0\|_{L^\infty} + t \|\nabla \rho_0\|_{L^\infty} e^{CV(t)} \right) \times \left( C_0 + t + \|\nabla \rho_0\|_{L^\infty} e^{CV(t)} + V(t) \right), \tag{26}
\]
We shall take $T > 0$ such that
\[
T \|\nabla \rho_0\|_{L^\infty} e^{CV(T)} \leq \min \left( 1, \|\omega_0\|_{L^1 L^\infty} \right). \tag{27}
\]
Then we deuce from (26)
\[ \| \nabla v(t) \|_{L^\infty} \leq C \| \omega_0 \|_{L^8 \cap L^\infty} \left( C_0 + t + \int_0^t \| \nabla v(\tau) \|_{L^\infty} d\tau \right), \quad \forall t \in [0, T]. \]
which yields in view of Gronwall lemma
\[ \| \nabla v(t) \|_{L^\infty} \leq C \| \omega_0 \|_{L^8 \cap L^\infty} \left( C_0 + t \right) e^{C \| \omega_0 \|_{L^8 \cap L^\infty} t} \quad \text{for all } \quad t \in [0, T], \]
Therefore in order to satisfy the assumption (27), it suffices that
\[ T \| \nabla \rho_0 \|_{L^8 \cap L^\infty} \exp \left( (C_0 + T) \left( e^{C \| \omega_0 \|_{L^8 \cap L^\infty} T} - 1 \right) \right) \leq \min(1, \| \omega_0 \|_{L^1 \cap L^\infty}). \]
Hence, a possible choice for \( T \) is given by the formula
\[ T \triangleq \frac{1}{C \| \omega_0 \|_{L^8 \cap L^\infty}} \log \left( 1 + \frac{\| \omega_0 \|_{L^8 \cap L^\infty}}{\| \omega_0 \|_{L^8 \cap L^\infty} C_0 + 1} \log \left( 1 + \frac{C \min(\| \omega_0 \|_{L^8 \cap L^\infty}, \| \omega_0 \|_{L^8 \cap L^\infty}^2)}{\| \nabla \rho_0 \|_{L^\infty}} \right) \right). \quad (28) \]

3.3. Existence. The main goal of this paragraph is to answer to the local existence part mentioned in Theorem 1. For this aim we shall consider the following system
\[
\begin{cases}
\partial_t v_n + v_n \cdot \nabla v_n + \nabla p_n = \rho_n \tilde{e}_2, \\
\partial_t \rho_n + v_n \cdot \nabla \rho_n = 0, \\
\text{div } v_n = 0, \\
v_{0,n} = S_n v_n, \quad \rho_{0,n} = S_n \rho_0.
\end{cases}
\]
where \( S_n \) is the usual cut-off in frequency defined in Section 2. Since the initial data \( v_{0,n}, \rho_{0,n} \) are smooth and belong to \( C^s, s > 1 \) then we can apply Chae’s result [9] and get for each \( n \) a unique solution \( v_n, \rho_n \in C([0, T^*_n]), C^s \). The maximal time existence \( T^*_n \) obeys to the following blow-up criterion.
\[ T^*_n < \infty \implies \int_0^{T^*_n} \| \nabla v_n(\tau) \|_{L^\infty} d\tau = +\infty. \quad (29) \]
To get a uniform time existence, that is, \( \liminf_{n \to \infty} T^*_n > 0 \) it suffices to check that the time existence \( \liminf_{n \to \infty} T^*_n \geq T \), where \( T \) is given by (28) and \( T_n \) is defined by (28) with the smooth data. To do so, it suffices first to check the uniformness of the constant depending on the size of the initial data and we shall see second how to achieve the argument. First, we should bound uniformly the quantities
\[
\| \omega_{0,n} \|_{L^8 \cap L^\infty}, \| \nabla \rho_{0,n} \|_{L^8 \cap L^\infty}, \| \omega_{0,n} \|_{X^0}, \| \rho_{0,n} \|_{X^0}. \]
This follows from the uniform continuity of the operator \( S_n : L^p \to L^p \) and by the following estimates stated in pages 62, 63 from [10]
\[ \| \partial X_{0,\lambda} \omega_{0,n} \|_{\varepsilon-1} \leq C (\| \partial X_{0,\lambda} \omega_0 \|_{\varepsilon-1} + \| X_{0,\lambda} \|_{\varepsilon} \| \omega_0 \|_{L^\infty}). \]
By the same way we may prove that
\[ \| \partial X_{0,\lambda} \rho_{0,n} \|_{\varepsilon} \leq C (\| \partial X_{0,\lambda} \rho_0 \|_{\varepsilon} + \| X_{0,\lambda} \|_{\varepsilon} \| \nabla \rho_0 \|_{L^\infty}). \]
To complete the proof of the claim, we assume that for some \( n \) we have \( T^*_n \leq T_0 \) where \( T_0 \) is given by (28), then all the a priori estimates done in the preceding section are justified and therefore we obtain according to the Proposition 3
\[
\| \nabla v_n(t) \|_{L^\infty} \leq C_0, \quad \| \omega_n(t) \|_{L^8 \cap L^\infty} + \| \nabla \rho_n(t) \|_{L^8 \cap L^\infty} \leq C_0
\]
and
\[
\| \rho_n(t) \|_{X^1_{t,n}} + \| \omega_n(t) \|_{X_{t,n}} + \sup_{\lambda \in \Lambda} \| \partial X_{0,\lambda} \psi_n(t) \|_{\varepsilon} \leq C_0.
\]
Where \( \psi_n \) is the flow associated to the vector field \( v_n \). This contradicts the blow-up criterion (29) and consequently \( T^*_n > T_0 \). By standard compactness arguments we can show that this family \((v_n, \rho_n)_{n \in \mathbb{N}}\) converges to \((v, \rho)\) which satisfies our initial value problem. We omit here the details and we will next focus on the uniqueness part.
3.4. Uniqueness. We shall now focus on the uniqueness part which will be performed in the functions space $X_{T_0} = L^\infty([0, T_0], L^q \cap W^{1,\infty})$ for some $2 < q < \infty$. We point out that this space is larger than the space of the existence part and the restriction to $q > 2$ comes from the fact that the velocity associated to a vortex patch is not in $L^2$, due to its slow decay at infinity, but belongs to the spaces $L^q, q > 2$. Let $(v_1, p_1, \rho_1)$ and $(v_2, p_2, \rho_2)$ be two solutions of the system (1) belonging to the space $X_{T_0}$ and let us denote by

$$v = v_1 - v_2, \quad p = p_1 - p_2 \quad \text{and} \quad \rho = \rho_1 - \rho_2.$$ 

Then we have the system

$$\begin{align*}
\partial_t v + v_2 \cdot \nabla v &= -v_1 \cdot \nabla v - \nabla p + \rho \vec{e}_2, \\
\partial_t \rho + v_2 \cdot \nabla \rho &= -v_1 \cdot \nabla \rho_1, \\
v_{t=0} &= v_0, \quad \rho_{t=0} = \rho_0.
\end{align*}$$

The $L^q$ estimate of the density is given by

$$\|\rho(t)\|_{L^q} \leq \|\rho_0\|_{L^q} + \int_0^t \|v(\tau)\|_{L^q} \|\nabla \rho_1\|_{L^\infty} d\tau. \quad (30)$$

Similarly we estimate the velocity as follows,

$$\|v(t)\|_{L^q} \leq \|v_0\|_{L^q} + \int_0^t (\|v(\tau)\|_{L^q} \|\nabla v_1\|_{L^\infty} + \|\nabla p(\tau)\|_{L^q} + \|\rho(\tau)\|_{L^q}) d\tau. \quad (31)$$

But using the incompressibility condition we get

$$\nabla \rho = \nabla \Delta^{-1} \text{div}(v_2 \cdot \nabla v) - \nabla \Delta^{-1} \text{div}(v_2 \cdot \nabla v)$$

where we have used in the last equality the fact that $\text{div}(v_2 \cdot \nabla v) = \text{div}(v \cdot \nabla v)$. By the continuity of Riesz transform on $L^q$ we obtain

$$\|\nabla \rho\|_{L^q} \leq C \left( \|v\|_{L^q} \left( \|\nabla v_1\|_{L^\infty} + \|\nabla v_2\|_{L^\infty} \right) + \|\rho\|_{L^q} \right).$$

Inserting the last estimate into (31) and using the continuity of Riesz transforms one gets

$$\|v(t)\|_{L^q} \leq \|v_0\|_{L^q} + C \int_0^t \left( \|v(\tau)\|_{L^q} \left( \|\nabla v_1(\tau)\|_{L^\infty} + \|\nabla v_2(\tau)\|_{L^\infty} \right) + \|\rho\|_{L^q} \right) d\tau.$$ 

Combining the last estimate with (30) and using Gronwall inequality we find that for all $t \leq T_0$ we have

$$\|(v(t), \rho(t))\|_{L^q} \leq \|(v_0, \rho_0)\|_{L^q} e^{Ct} \exp \left( \int_0^t \left( \|\nabla v_1\|_{L^\infty} + \|\nabla v_2\|_{L^\infty} + \|\nabla \rho_1\|_{L^\infty} \right) d\tau \right).$$

This achieves the proof of the uniqueness part.

4. Singular patches

In this section, we move on to some results concerning singular vortex patches. Our main goal is to prove Theorem 2 and enlarge its statement for more general initial data belonging to Yudovich class. To the best of our knowledge, even for the simple case of patches with singular boundary no results on the local well-posedness are known in the literature. In this special case and as it was previously stressed in Theorem 2 we must take a density with constant magnitude around the singularity. By this assumption we wish to kill the singularity effects and reduce their violent interaction with the density which is the main obstacle of this problem.

The generalization of Theorem 2 will require some specific material that were developed by Chemin in [10]. In this new pattern we assume that the initial boundary contains a singular subset and therefore the vector fields which encode the regularity should vanish close to it. This forces us to work with degenerate vector fields and a cut-off procedure near the singular set becomes necessary. Therefore we shall deal with infinite family of vector fields parametrized by the distance.
to the singular set and the control of the blowup with respect to this parameter is mostly the main difficulty in this problem.

4.1. Preliminaries. We shall introduce and recall some basic definitions and results in connection with singular vortex patches. These tools are mostly introduced in [10] with sufficient details and for the completeness of the manuscript we shall recall them here without any proof.

Definition 5. Let $\Sigma$ be a closed set of the plane. We denote by $L(\Sigma)$ the set of the functions $v$ such that
\[ \|v\|_{L(\Sigma)} \triangleq \sup_{0<h \leq e^{-1}} \frac{\|v\|_{L^\infty}(\Sigma_h)}{-\log h} < \infty. \]
In this definition and for the remaining of the paper we shall adopt the following notation: For $h > 0$ $\Sigma_h = \{ x \in \mathbb{R}^2; \ \text{dist}(x, \Sigma) \leq h \}$ and $\Sigma_h^c = \{ x \in \mathbb{R}^2; \ \text{dist}(x, \Sigma) \geq h \}$.

Next we introduce log-Lipschitz space which is frequently used in the framework of Yudovich solutions. This space appears in a natural way thanks to the fact the velocity associated to a bounded and integrable vorticity is not in general Lipschitz but belongs to a slight bigger one called log-Lipschitz class.

Definition 6. We denote by $LL$ the space of log-Lipschitz functions, that is the set of bounded functions $v$ in $\mathbb{R}^2 \to \mathbb{R}$ satisfying
\[ \|v\|_{LL} \triangleq \|v\|_{L^\infty} + \sup_{0<|x-y|<1} \frac{|v(x) - v(y)|}{|x-y| \log \frac{e}{|x-y|}} < +\infty. \]
We have the following classical estimate which is a simple consequence of the embedding $B^1_{\infty,\infty} \subset LL$ combined with Bernstein inequality and Biot-Savart law (9).

Lemma 5. For any finite $a > 1$ we have
\[ \|v\|_{LL} \leq C \|\omega\|_{L^a \cap L^\infty}, \]
with $C$ depending only on $a$.

It is well-known, thanks to Osgood lemma, that a vector field $v$ belonging to the space $LL$ has a unique global flow map $\psi$ in the class of continuous functions on the space and time variables. This map is defined by the nonlinear integral equation,
\[ \psi(t, x) = x + \int_0^t v(\tau, \psi(\tau, x))d\tau \quad \forall (t, x) \in \mathbb{R}_+ \times \mathbb{R}^2. \]
For more details about this issue we refer the reader to Section 3.3 in [2].

The next result deals with some general aspect of the dynamics of a given set through the flow associated to a vector field in the $LL$ space. Such result was proved in [10].

Lemma 6. Let $A_0$ be a subset of $\mathbb{R}^2$ and $v$ be a vector field belonging to $L^1_{loc}(\mathbb{R}_+; LL)$. We denote by $\psi(t)$ the flow associated to this vector field. Then setting $A(t) \triangleq \psi(t, A_0)$ we get,
\[ \psi \left( t, (A_0)_h^c \right) \subset \left( A(t) \right)^e_{\delta_t(h)}, \quad \text{with} \quad \delta_t(h) \triangleq h \exp \int_0^t \|v(\tau)\|_{LL}d\tau. \]
For all $0 \leq \tau \leq t$,
\[ \psi \left( \tau, \psi^{-1} \left( (A_0)_h^c \right) \right) \subset \left( A(\tau) \right)^e_{\delta_{\tau, t}(h)}, \quad \text{with} \quad \delta_{\tau, t}(h) \triangleq h \exp \int_0^\tau \|v(\sigma)\|_{LL}d\sigma. \]
Next, we discuss the regularity persistence for a transport model and the proof can be found in [10].

Proposition 4. Let $\varepsilon \in (-1, 1)$, $a \in (1, +\infty)$ and $v$ be a smooth divergence-free vector field. Set
\[ W(t) \triangleq \left( \|\nabla v(t)\|_{L(\Sigma_t)} + \|\omega(t)\|_{L^a \cap L^\infty} \right) \exp \left( \int_0^t \|v(\tau)\|_{LL}d\tau \right), \quad \Sigma_t = \psi(t, \Sigma_0). \]
Let $f \in L^\infty_{loc}([0, T], C^\varepsilon)$ be a solution of transport model,

$$
\begin{cases}
\partial_t f + v \cdot \nabla f = g,

f(t=0) = f_0,
\end{cases}
$$

where $g = g_1 + g_2$ is given and belongs to $L^1([0, T]; C^\varepsilon)$. We assume that $\text{supp } f_0 \subset (\Sigma_0)_{\xi}^c$ and $\text{supp } g(t) \subset (\Sigma_\varepsilon)_{\delta(t, h)}$ for any $t \in [0, T]$, and for some small $h$

$$
\|g_2(t)\|_{\varepsilon} \leq -C W(t) \|f(t)\|_{\varepsilon} \log h.
$$

Then the following inequality holds true

$$
\|f(t)\|_{\varepsilon} \leq \|f_0\|_{\varepsilon} e^{-C \int_0^t W(\tau)d\tau} + \int_0^t e^{-C \int_0^\tau W(\tau')d\tau'} \|g_1(\tau)\|_{\varepsilon}d\tau.
$$

Here the constant $C$ is universal and does not depend on $h$.

Next, we recall the following definition introduced in [10].

**Definition 7.** Let $\Sigma$ be a closed subset of $\mathbb{R}^d$ and $\Xi = (\alpha, \beta, \gamma)$ be a triplet of real numbers. We consider a family $\mathcal{X} = (X_{\lambda, h})_{(\lambda, h) \in \lambda \times [0, e^{-1}]}$ of vector fields belonging to $C^\varepsilon$ as well as their divergences, with $\varepsilon \in [0, 1]$ and we denote by $X_h = (X_{\lambda, h})_{\lambda \in \Lambda}$.

The family $\mathcal{X}$ will be said $\Sigma-$admissible of order $\Xi$ if and only if the following properties are satisfied:

$$
\forall (\lambda, h) \in \Lambda \times [0, e^{-1}], \text{ supp } X_{\lambda, h} \subset \Sigma_{\lambda}^\alpha, \quad \inf_{h \in [0, e^{-1}]} h^{-\alpha} I(\Sigma_h, X_h) > 0,
$$

where we adopt the following notation: for $\eta \geq h^\alpha$,

$$
I(\Sigma_h, X_h) \triangleq \inf_{x \in \Sigma_h} \sup_{\lambda \in \Lambda} |X_{\lambda, h}(x)| \quad \text{and} \quad N_\varepsilon(\Sigma_h, X_h) \triangleq \sup_{\lambda \in \Lambda} \frac{\|X_{\lambda, h}\|_{\varepsilon}}{I(\Sigma_h, X_h)}.
$$

**Remark 7.** Concretely, the family of vector fields $\mathcal{X}$ that we shall work with vanishes near the singular set and therefore we should get $\gamma, \beta < 0$. Moreover the parameter $\alpha > 1$.

Similarly to the smooth paths we shall introduce for $\eta \geq h^\alpha$,

$$
\|u\|_{T_{\varepsilon, h}} \triangleq N_\varepsilon(\Xi, X_h) \sum_{|\alpha| \leq k} \|\partial^\alpha u\|_{L^\infty} + \sup_{\lambda \in \Lambda} \frac{\|\partial X_{\lambda, h}\|_{\varepsilon+1}}{I(\Xi, X_h)}.
$$

(32)

4.2. General statement. We intend now to extend the result of Theorem 2 and see in turn how to deduce the result of this theorem. The proof of the general statement will be carried out in multiple steps and will be postponed in the next subsections.

**Theorem 5.** Let $0 < \varepsilon < 1$, $0 < r < e^{-1}$, $1 < \alpha < 2$ and $\Sigma_0$ be a closed subset of the plane. Let $v_0$ be a divergence-free vector field with vorticity $\omega_0$ belonging to $L^\alpha \cap L^\infty$ and $\rho_0$ be a real-valued function in $W^{1, a} \cap W^{1, \infty}$ and taking constant value on $(\Sigma_0)_{\varepsilon}$. Consider $\mathcal{X}_0 = (X_{0, \lambda, h})_{(\lambda, h) \in \lambda \times [0, e^{-1}]}$ a family of vector fields of class $C^\varepsilon$ as well as their divergences and suppose that this family is $\Sigma_0$-admissible of order $\Xi_0 = (\alpha_0, \beta_0, \gamma_0)$ such that

$$
\sup_{h \in [0, e^{-1}]} h^{-\beta_0} \|\omega_0\|_{(\Sigma_0)_h, (X_h)} + \sup_{h \in [0, e^{-1}]} h^{-\beta_0} \|\omega_0\|_{(\Sigma_0)_h, (X_h)} < \infty.
$$

Then, there exists $T > 0$ such that the Boussinesq system (6) has a unique solution

$$
(\omega, \rho) \in L^\infty([0, T], L^\alpha \cap L^\infty) \times L^\infty([0, T], W^{1, a} \cap W^{1, \infty}).
$$

In addition, we have

$$
\sup_{h \in [0, e^{-1}]} \frac{\|\nabla v(t)\|_{L^\infty(\Sigma(t)_h, (X(t)_h))}}{\log h} \in L^\infty([0, T]),
$$

where $\Sigma(t) = \psi(t, \Sigma_0)$.
• **Proof of Theorem 2.** Let us briefly show how this result leads to Theorem 2 stated in the Introduction. Let \( \Omega_0 \) be a bounded open set whose boundary belongs to \( C^{\varepsilon+1} \) outside the closed singular set \( \Sigma_0 \). In view of the Definition 4 we may show the existence of a neighborhood \( V_0 \) of \( \partial \Omega_0 \) and a real function \( f_0 \in C^{\varepsilon+1} \) such that \( \partial \Omega_0 = f_0^{-1}(0) \cap V_0 \) and whose gradient does not vanish on \( V_0 \setminus \Sigma_0 \). We also assume that there exists a positive number \( \gamma_0 > 0 \) such that for all \( x \in V_0 \),
\[
|\nabla f_0(x)| \geq d(x, \Sigma_0)^{\gamma_0}.
\]
This means that the curves defining the boundary of \( \Omega_0 \) are not tangent to one another at infinite order at the singular points. Consider \((\theta_h)_{h \in (0,e^{-1})} \) a family of infinitely differentiable functions, supported in \((\Sigma_0)^c_{\varepsilon/2}\) and taking the value 1 on the set \((\Sigma_0)^c_{h}\) and satisfying for all \( h \in [0,e^{-1}] \) and any positive real number \( r \),
\[
\|\theta_h\|_r \leq C_r h^{-r}.
\]
The existence of such functions can be proved by dilation. Consider \( \bar{\alpha} \) a function of class \( C^\infty \) supported in \( V_0 \) and taking the value 1 on \( V_1 \), where \( V_1 \) is a neighborhood of \( \partial \Omega_0 \) such that \( V_1 \subset V_0 \).

We define the family \( X_0 = (X_{0,\lambda,h})_{\lambda \in \{0,1\}, h \in [0,e^{-1}]} \) of vector fields by:
\[
X_{0,0,h} = \nabla^\perp(\theta_h f_0), \quad X_{0,1,h} = (1 - \bar{\alpha}) \begin{pmatrix} 1 \\ 0 \end{pmatrix}.
\]

It comes to see if the family \( X_0 \) is \( \Sigma_0 \)-admissible of certain order \( \Xi_0 = (\alpha_0, \beta_0, \gamma_0) \). The first vector field is of class \( C^\varepsilon \) with zero divergence and the second is \( C^\infty \). On other hand, by construction, \( \text{supp} X_{0,1,h} \subset (\Sigma_0)^c_{\varepsilon/2} \subset (\Sigma_0)^c_{h} \) with \( \alpha_0 > 1 \). Moreover, thanks to the hypothesis (33) we may choose \( \gamma_0 = -\gamma_0 \). Finally, we easily show that
\[
\|X_{0,\lambda,h}\|_\varepsilon \leq C h^{-\varepsilon-1}.
\]
Hence, it suffices to take \( \beta_0 = \gamma_0 - \varepsilon - 1 \) and \( \Xi_0 = (\alpha_0, \beta_0, \gamma_0) \). Besides, we have
\[
\partial_{X_{0,\lambda,h}} \omega_0 = \theta_h \partial_{\nabla^\perp f_0} \omega_0 + f_0 \partial_{\nabla^\perp \theta_h \omega_0}.
\]
First we observe that the derivative of \( \omega_0 \) in the direction \( \nabla^\perp f_0 \) is zero and second \( \partial_{\nabla^\perp \theta_h \omega_0} \) is a distribution of order zero supported on the boundary \( \partial \Omega_0 \). As the function \( f_0 \) vanishes on \( \partial \Omega_0 \) then
\[
f_0 \partial_{\nabla^\perp \theta_h \Omega_0} = 0.
\]
Thus we deduce that \( \partial_{X_{0,\lambda,h}} \omega_0 = 0 \). For the second vector field we use that \( 1 - \bar{\alpha} \) vanishes on a small neighborhood of \( \partial \Omega_0 \) and therefore \( \partial_{X_{0,1,h}} \omega_0 = 0 \). It remains to check the regularity assumption on the density \( \rho_0 \). This function is constant in a neighborhood of \( \Sigma_0 \) and thus \( \nabla \rho_0 \nabla^\perp \theta_h = 0 \) and moreover \( \partial_{\nabla^\perp f_0} \rho_0 \in C^\varepsilon \). It is then immediate that \( \partial_{X_{0,\lambda,h}} \rho_0 \in C^\varepsilon \). Hence the hypothesis of Theorem 5 are satisfied and the local well-posedness result of Theorem 2 is now established. To infer that the boundary \( \Omega_0 \) is a curve of class \( C^{1+\varepsilon} \) outside \( \Sigma(t) \) we argue as in the case of regular vortex patches seen in the previous section.

### 4.3. A priori estimates.

This section is devoted to some a priori estimates of \( L^p \) type for both the density and the vorticity functions. As the velocity may lose regularity and becomes rough close to the singular set, our assumption to work with constant density near this set seems to be crucial and unavoidable in our analysis. Without this assumption the problem remains open and may be one should expect to propagate the regularity with some loss.

**Proposition 5.** Let \( \Sigma_0 \) be a closed set of \( \mathbb{R}^2 \) and \( (v, \rho) \) be a smooth solution of the system (1) defined on the time interval \([0,T]\). We suppose that \( \rho_0 \) is constant in the set \((\Sigma_0)^c_r = \{x \in \mathbb{R}^2; d(x, \Sigma_0) \leq r\}\) for some \( r \in (0, e^{-1}) \). Then for all \( p \in [1, +\infty) \) and for any \( t \in [0,T] \) we have
\[
\|\nabla \rho(t)\|_{L^p} \leq \|\nabla \rho_0\|_{L^p} e^{-C \int_0^t W(r) \, dr},
\]
and
\[
\|\omega(t)\|_{L^p} \leq \|\omega_0\|_{L^p} + t \|\nabla \rho_0\|_{L^p} e^{-C \int_0^t W(r) \, dr},
\]
with \( C \) an absolute constant.
Proof. In order to prove the first estimate, we apply the partial derivative $\partial_j$ to the second equation of the system (1),
\begin{equation}
\partial_t \partial_j \rho + v \cdot \nabla (\partial_j \rho) = \partial_j v \cdot \nabla \rho.
\end{equation}
Hence, for all $1 \leq p \leq \infty$ one has
\begin{equation}
\|\partial_j \rho(t)\|_{L^p} \leq \|\partial_j \rho_0\|_{L^p} + \int_0^t \|\partial_j v \cdot \nabla \rho(\tau)\|_{L^p} d\tau.
\end{equation}
Since $\rho_0$ is transported by the flow $\psi$,
$\rho(\tau, x) = \rho_0(\psi^{-1}(t, x))$,
then $\rho(\tau)$ is constant in $\psi(\tau, (\Sigma_0)_r)$ and therefore,
supp $\nabla \rho(\tau) \subset \psi(\tau, (\Sigma_0)_r)^c = \psi(\tau, (\Sigma_0)_r)^c$.
Using Lemma 6 we get easily
\begin{equation*}
supp \nabla \rho(\tau) \subset (\Sigma_{\tau})^{\delta_{\tau}(r)}, \quad \delta_{\tau}(r) = r\exp \left( \int_0^\tau \|v(\sigma)\|_{L^1} \, d\sigma \right).
\end{equation*}
Accordingly we obtain
\begin{equation*}
\|\partial_j v \cdot \nabla \rho(\tau)\|_{L^p} \leq \|\nabla v(\tau)\|_{L^\infty((\Sigma_{\tau})^{\delta_{\tau}(r)})} \|\nabla \rho(\tau)\|_{L^p}.
\end{equation*}
Thus coming back to the Definition 5 we may write
\begin{equation*}
\|\nabla v(\tau)\|_{L^\infty((\Sigma_{\tau})^{\delta_{\tau}(r)})} \leq \|\nabla v(\tau)\|_{L(\Sigma_{\tau})} \log \delta_{\tau}(r)
\leq -(\log r)\|\nabla v(\tau)\|_{L(\Sigma_{\tau})} \exp \left( \int_0^\tau \|v(\sigma)\|_{L^1} \, d\sigma \right)
\leq -W(\tau) \log r.
\end{equation*}
Recall that the function $W(t)$ was introduced in Proposition 4. It follows that
\begin{equation*}
\|\nabla \rho(t)\|_{L^p} \leq \|\nabla \rho_0\|_{L^p} - C \log r \int_0^t \|\nabla \rho(\tau)\|_{L^p} W(\tau) \, d\tau.
\end{equation*}
By Gronwall lemma we conclude that
\begin{equation*}
\|\nabla \rho(t)\|_{L^p} \leq \|\nabla \rho_0\|_{L^p} e^{-C \int_0^t W(\tau) \, d\tau}.
\end{equation*}
Therefore, in view of the vorticity equation (6) we obviously have for all $1 \leq p \leq \infty$,
\begin{equation*}
\|\omega(t)\|_{L^p} \leq \|\omega_0\|_{L^p} + \int_0^t \|\nabla \rho(\tau)\|_{L^p} d\tau \leq \|\omega_0\|_{L^p} + \|\nabla \rho_0\|_{L^p} e^{-C \int_0^t W(\tau) \, d\tau} t.
\end{equation*}
This completes the proof of the proposition. \hfill \Box

Now we shall discuss the a priori estimates which are the key of the proof of Theorem 5.

**Proposition 6.** Let $0 < \varepsilon < 1$, $a > 1$ and $\Sigma_0$ a closed set of the plane and $X_0$ be a vector field of class $C^\infty$ as well as its divergence and whose support is embedded in $(\Sigma_0)_r$. Let $(v, \rho)$ be a smooth solution of the system (1) defined on a time interval $[0, T]$ and with the initial data $(v_0, \rho_0)$ such that $\rho_0$ is constant in the set $(\Sigma_0)_r$. Let $X_t$ be the solution of :
\begin{equation}
\begin{cases}
(\partial_t + v \cdot \nabla) X_t = \partial_t v, \\
X_{t=0} = X_0.
\end{cases}
\end{equation}
then we have the estimates,
\begin{align*}
supp X_t \subset (\Sigma_{\tau})^{\delta_{\tau}(h)} \quad \text{with} \quad \delta_{\tau}(h) = h\exp \left( \int_0^\tau \|v(\sigma)\|_{L^1} \, d\sigma \right),
\end{align*}
\begin{align*}
\|\text{div} X_t\|_{C^0} \leq \|\text{div} X_0\|_{C^0} h^{-C} \int_0^\tau W(\tau) \, d\tau,
\end{align*}
\[ \|X_t\|_{\varepsilon} + \|\partial X_t, \omega(t)\|_{\varepsilon^{-1}} \leq C e^{Ct} \left( \|X_0\|_{\varepsilon} + \|\partial X_0, \omega_0\|_{\varepsilon^{-1}} + \|\partial X_0, \rho_0\|_{\varepsilon} \right) h^{-C} \int_0^t W'(\tau) d\tau \times \exp \left( C t \|\nabla \rho_0\|_{L^\infty} r^{-C} \int_0^t W'(\tau) d\tau \right). \]

where
\[ W(t) \triangleq \left( \|\nabla v(t)\|_{L^1(\Sigma_t)} + \|\omega(t)\|_{L^\infty \cap L^\infty} \right) \exp \left( \int_0^t \|v(\tau)\|_{L^2 L^1} d\tau \right). \]

**Proof.** The embedding result on the support of \( X_t \) can be deduced from Lemma 6 and the complete proof can be found in [10]. The second result concerning the estimate of \( \text{div} X_t \) follows from the equation
\[(\partial_t + v \cdot \nabla) \text{div} X_t = 0,\]
and Proposition 4. As to the estimate of \( \|X_t\|_{\varepsilon} \) we shall admit the following assertion and more details see for instance Chapter 9 from [10].
\[ \partial X_t, v(t) = g_1(t) + g_2(t), \]
with
\[ g_1(t) \leq C \|\partial X_t, \omega(t)\|_{\varepsilon^{-1}} + C \|\text{div} X_t\|_{\varepsilon} \|\omega(t)\|_{L^\infty}, \]
and
\[ g_2(t) \leq -C \|X_t\|_{\varepsilon} W(t) \log h. \]

Then applying once again Proposition 4 to the equation (36) we get
\[ \|X_t\|_{C^0} \leq \|X_0\|_{\varepsilon} h^{-C} \int_0^t W'(\tau) d\tau + \int_0^t \|\text{div} X_t\|_{\varepsilon} \|\omega(\tau)\|_{L^\infty} h^{-C} \int_0^\tau W'(\tau) d\tau d\tau \]
\[ + \int_0^t \|\partial X_t, \omega(\tau)\|_{\varepsilon^{-1}} h^{-C} \int_0^\tau W'(\tau) d\tau d\tau. \]

According to the definition of the function \( W(t) \) we may write
\[ \int_0^t \|\omega(\tau)\|_{L^\infty} d\tau \leq h^{-C} \int_0^t W'(\tau) d\tau. \]

This together with the estimate of \( \|\text{div} X_t\|_{C^0} \) yields
\[ \|X_t\|_{\varepsilon} \leq \|X_0\|_{\varepsilon} h^{-C} \int_0^t W'(\tau) d\tau + \int_0^t \|\partial X_t, \omega(\tau)\|_{\varepsilon^{-1}} h^{-C} \int_0^\tau W'(\tau) d\tau d\tau. \]

(37)

Now applying the operator \( \partial X_t \) to the vorticity equation (6) gives
\[ (\partial_t + v \cdot \nabla) \partial X_t, \omega = \partial X_t, \partial_t \rho, \]
then from Proposition 4 and taking advantage of the inequality (23) we get
\[ \|\partial X_t, \omega(t)\|_{\varepsilon^{-1}} \leq \|\partial X_0, \omega_0\|_{\varepsilon^{-1}} h^{-C} \int_0^t W'(\tau) d\tau d\tau \]
\[ + \int_0^t \|\partial X_t, \rho(\tau)\|_{\varepsilon^{-1}} h^{-C} \int_0^\tau W'(\tau) d\tau d\tau + \int_0^t \|\partial X_t, \rho(\tau)\|_{\varepsilon} h^{-C} \int_0^\tau W'(\tau) d\tau d\tau \]
\[ + \int_0^t \|\nabla \rho(\tau)\|_{L^\infty} \|X_t\|_{\varepsilon} h^{-C} \int_0^\tau W'(\tau) d\tau d\tau. \]

As it has been shown for smooth patches the scalar function \( \partial X_t, \rho(t) \) is transported by the flow,
\[(\partial_t + v \cdot \nabla) \partial X_t, \rho(t) = 0.\]

It is easy to check that \( \partial X_0, \rho_0 \) is supported in \( (\Sigma_0)^c \) and thus Proposition 4 gives
\[ \|\partial X_t, \rho(\tau)\|_{\varepsilon} \leq \|\partial X_0, \rho_0\|_{\varepsilon} r^{-C} \int_0^\tau W'(\tau) d\tau. \]
Hence, we obtain
\[
\|\partial X_t \omega(t)\|_{L^1} \lesssim (\|\partial X_0 \omega_0\|_{L^1} + \|\partial X_0 \rho_0\|_{L^1}) e^{-1} \int_0^t W(\tau) d\tau + \int_0^t \|\nabla \rho(\tau)\|_{L^\infty} \|X_t\| \delta^{-1} e^{-C \int_0^t W(\tau) d\tau} d\tau.
\]

Putting together the preceding estimate and (37) we find
\[
\Gamma(t) \lesssim \Gamma(0) + \|\partial X_0 \rho_0\|_{L^1} t + \int_0^t (\|\nabla \rho(\tau)\|_{L^\infty} + 1) \Gamma(\tau) d\tau,
\]
where
\[
\Gamma(t) \triangleq (\|\partial X_t \omega(t)\|_{L^1} + \|X_t\|_{L^1}) e^{C \int_0^t W(\tau) d\tau}.
\]

So Gronwall lemma ensures that
\[
\Gamma(t) \leq (\Gamma(0) + \|\partial X_0 \rho_0\|_{L^1}) e^{C \int_0^t \|\nabla \rho(\tau)\|_{L^\infty} d\tau} e^{C t}.
\]

Then Proposition 5 completes the proof. \(\square\)

Now, we have to control the Lipschitz norm of the velocity outside the transported of the singular set \(\Sigma_0\) by the flow.

**Proposition 7.** Let \(0 < \varepsilon < 1\), \(0 < r < e^{-1}\) and \(a > 1\) and \(\Sigma_0\) be a closed set of the plane. Let \(X_0 = (X_0, \lambda, h)\) be a family vector field which is \(\Sigma_0\)-admissible of order \(\Xi_0 = (\alpha, \beta_0, \gamma_0)\) and let \((v, \rho)\) be a smooth solution of the system (1) defined on a time interval \([0, T^*]\). We assume that the initial data satisfy \(\omega_0, \nabla \rho_0 \in L^a\), \(\rho_0\) is constant in the set \((\Sigma_0)^c\) and
\[
\sup_{h \in [0,e^{-1}]} h^{-\beta_0} \|\rho_0\|_{L^\infty(\Sigma_0,h)} + \sup_{h \in [0,e^{-1}]} h^{-\beta_0} \|\omega_0\|_{L^\infty(\Sigma_0,h)} < \infty.
\]

Then there exists \(0 < T < T^*\) such that
\[
\|\nabla v(t)\|_{L^\infty(\Sigma(t))} \in L^\infty([0, T]).
\]

**Proof.** The dynamical vector fields \(\{X_{t, \lambda, h}\}\) are nothing but the transported of the initial family by the flow. They are given by the identity
\[
Y_{t, \lambda, h}(x) \triangleq X_{t, \lambda, h}(\psi(t, x)) = \partial X_{0, \lambda, h} \psi(t, x)
\]
and clearly they satisfy
\[
\partial_t Y_{t, \lambda, h}(x) = \{\nabla v(t, \psi(t, x))\} \cdot Y_{t, \lambda, h}(x).
\]

Fix \(t > 0\) and set for \(\tau \in [0, t]\), \(Z(\tau, x) = Y_{t-\tau, \lambda, h}(x)\), then
\[
\partial_\tau Z(\tau, x) = -\{\nabla v(t-\tau, \psi(t-\tau, x))\} \cdot Z(\tau, x).
\]

Hence using Gronwall lemma we get
\[
|Z(t, x)| \leq |Z(0, x)| e^{\int_0^t \|\nabla v(t-\tau, \psi(t-\tau, x))\|_{L^\infty} d\tau} \leq |Z(0, x)| e^{\int_0^t \|\nabla v(\tau, \psi(\tau, x))\|_{L^\infty} d\tau},
\]
which is equivalent to
\[
|Y_{0, \lambda, h}(x)| \leq |Y_{t, \lambda, h}(x)| e^{\int_0^t \|\nabla v(\tau, \psi(\tau, x))\|_{L^\infty} d\tau}.
\]

This gives in turn,
\[
|X_{0, \lambda, h}(\psi^{-1}(t, x))| \leq |X_{t, \lambda, h}(x)| e^{\int_0^t \|\nabla v(\tau, \psi^{-1}(t, x))\|_{L^\infty} d\tau}.
\]

Denoting by \(\delta_t^{-1}\) the inverse function of \(\delta_t\) given by the formula,
\[
\delta_t^{-1}(h) \triangleq h \exp(-\int_0^t \|v(\tau)\|_{L^\infty} d\tau),
\]
the last estimate yields
\[
\inf_{x \in \Sigma_t^{\delta_1^{-1}}(h)} \sup_{\lambda \in \Lambda} |X_{0,\lambda,h}(\psi^{-1}(t, x))| \leq \inf_{x \in \Sigma_t^{\delta_1^{-1}}(h)} \sup_{\lambda \in \Lambda} |X_{t,\lambda,h}(x)| \times \exp \left( \int_0^t \left\| \nabla v(\tau, \psi(\tau, \psi^{-1}(t, \cdot))) \right\|_{L^\infty((\Sigma_t^{\delta_1^{-1}}(h)), d\tau)} \right),
\]
where we recall that \( \Sigma_t = \psi(t, \Sigma_0) \) and \( (\Sigma_t)_\eta = \{ x \in \mathbb{R}^2; d(x, \Sigma_t) \geq \eta \} \).
According to Lemma 6 we have
\[
\psi^{-1}(t, (\Sigma_t)_\delta^{\delta_1^{-1}}(h)) \subset (\Sigma_0)^\delta_{\delta_1^{-1}}(h) = (\Sigma_0)_h.
\]
Then we immediately deduce that
\[
\inf_{x \in \Sigma_t^{\delta_1^{-1}}(h)} \sup_{\lambda \in \Lambda} |X_{0,\lambda,h}(\psi^{-1}(t, x))| = \inf_{y \in \psi^{-1}(t, (\Sigma_t)_\delta^{\delta_1^{-1}}(h))} \sup_{\lambda \in \Lambda} |X_{0,\lambda,h}(y)| \geq \inf_{y \in (\Sigma_0)^\delta_{\delta_1^{-1}}(h)} \sup_{\lambda \in \Lambda} |X_{0,\lambda,h}(y)| \geq I((\Sigma_0)_h, (X_0)_h).
\]
Moreover, in view of the same lemma we have
\[
\psi\left( \tau, \psi^{-1}(t, (\Sigma_t)^\delta_{\delta_1^{-1}}(h)) \right) \subset (\Sigma_\tau)^\delta_{\delta_1^{-1}}(h) \subset (\Sigma_\tau)_h.
\]
Consequently, we may write
\[
\left\| \nabla v(\tau, \psi(\tau, \psi^{-1}(t, \cdot))) \right\|_{L^\infty((\Sigma_t)^\delta_{\delta_1^{-1}}(h))} \leq \left\| \nabla v(\tau) \right\|_{L^\infty((\Sigma_\tau)_h)} \leq -C \left\| v(\tau) \right\|_{L^\infty((\Sigma_\tau)_h)} \leq -C \left\| v(\tau) \right\|.
\]
Combining the last estimate with (39) and (40) we get
\[
I((\Sigma_t)^\delta_{\delta_1^{-1}}(h), (X(t))_h) \geq I((\Sigma_0)_h, (X_0)_h)^h_{C \left\| W(\tau) \right\| d\tau}
\]
We introduce
\[
\Upsilon(t) \triangleq \left\| \psi(t) \right\|_{L^\infty} \left\| X_{t,\lambda,h} \right\|_\varepsilon + \left\| \partial X_{t,\lambda,h} \right\|_{\varepsilon-1}.
\]
Then combining Proposition 6 and Proposition 5 we get
\[
\Upsilon(t) \leq C e^{Ct} \left( 1 + \left\| \psi(t) \right\|_{L^\infty} \right) \left( \left\| X_{0,\lambda,h} \right\|_\varepsilon + \left\| \partial X_{0,\lambda,h} \right\|_{\varepsilon-1} + \left\| \partial X_{0,\lambda,h} \right\|_{\varepsilon-1} \right) \times \exp \left( C t \left\| \nabla v(t) \right\|_{L^\infty} \right) \left\| v(t) \right\|_{L^\infty}.
\]
Hence in view of the Definition 7 and (41) we immediately deduce that
\[
\Upsilon(t) \leq C e^{Ct} \left( \left\| X_{\Sigma(t)}(X_0)_h \right\| + \left( 1 + \left\| \psi(t) \right\|_{L^\infty} \right) \left( \left\| \psi(t) \right\|_{(\Sigma(t))_h} \right) + \left\| \partial \right\|_{(\Sigma(t))_h} \right) \times \exp \left( C t \left\| \nabla v(t) \right\|_{L^\infty} \right) \left\| v(t) \right\|_{L^\infty}.
\]
From this estimate and the definition (32), one has
\[
\left( \left\| \psi(t) \right\|_{(\Sigma(t))_h} \right) \leq C_0 e^{Ct} \left( \left\| \psi(t) \right\|_{L^\infty} \right) \exp \left( C t \left\| \nabla v(t) \right\|_{L^\infty} \right) \left\| v(t) \right\|_{L^\infty}.
\]
Now, we shall combine Theorem 3 with the Proposition 5 and the monotonicity of the map \( x \mapsto x \log \left( e + \frac{a}{x} \right) \) to get

\[
\| \nabla v(t) \|_{L^\infty((\Sigma_t)^{\delta_t^{-1}(h)})} \leq C \left( \| \omega_0 \|_{L^\infty} + t \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau \right) \log \left( e + \frac{\| \nabla \omega \|_{L^\infty}}{\| \omega_0 \|_{L^\infty}} \right).
\]

So according to the estimate (42), we find

\[
\| \nabla v(t) \|_{L^\infty((\Sigma_t)^{\delta_t^{-1}(h)})} \leq C \left( \| \omega_0 \|_{L^1} + t \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau \right)
\times \left( C_0 + t + \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau + \left( \beta_0 - C \int_0^t W(\tau) d\tau \right) \log h \right).
\]

It follows that

\[
\frac{\| \nabla v(t) \|_{L^\infty((\Sigma_t)^{\delta_t^{-1}(h)})}}{- \log \delta_t^{-1}(h)} \leq C \left( \| \omega_0 \|_{L^1} + t \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau \right)
\times \left( C_0 + t + \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau + \int_0^t W(\tau) d\tau \right) e^{\delta_t^{-1}(h)} \| \nabla v(\tau) \|_{L^\infty} d\tau.
\]

By the definition of \( W(t) \) introduced in the Proposition 4 we have

\[
W(t) \leq C \left( \| \omega_0 \|_{L^\infty}^2 + \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau \right)
\times \left( C_0 + t + \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau + \int_0^t W(\tau) d\tau \right) e^{\delta_t^{-1}(h)} \| \nabla v(\tau) \|_{L^\infty} d\tau.
\]

We choose \( T \) such that

\[
T \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^T W(\tau) d\tau \leq \min \left( 1, \| \omega_0 \|_{L^1} \right).
\]

From Lemma 5 and Proposition 5 we get for \( t \in [0, T] \)

\[
\| v(t) \|_{L^\infty} \leq \| \omega(t) \|_{L^\infty} \leq \| \omega_0 \|_{L^\infty} + \| \nabla \rho_0 \|_{L^\infty} r^{-C} \int_0^t W(\tau) d\tau \leq 2 \| \omega_0 \|_{L^\infty}.
\]

Then,

\[
W(t) \leq C \| \omega_0 \|_{L^1} \left( C_0 + t + \int_0^t W(\tau) d\tau \right) e^{C \| \omega_0 \|_{L^\infty} t}
\]

Therefore by using to Gronwall lemma we conclude that for \( t \in [0, T] \)

\[
W(t) \leq C \| \omega_0 \|_{L^\infty} \left( C_0 + t e^{C \| \omega_0 \|_{L^\infty} t} \right) e^{C \| \omega_0 \|_{L^\infty} t} \exp \left( e^{C \| \omega_0 \|_{L^\infty} t} \right).
\]

It follows that

\[
\int_0^t W(\tau) d\tau \leq (C_0 + t) \exp \left( e^{C \| \omega_0 \|_{L^\infty} t} \right), \quad r^{-C} \int_0^t W(\tau) d\tau \leq r^{-C} \exp \left( e^{C \| \omega_0 \|_{L^\infty} t} \right).
\]

Hence in order to ensure the assumption (43) it suffices to impose,

\[
T \| \nabla \rho_0 \|_{L^\infty} r^{-C(T+T)} \exp \left( e^{C T \| \omega_0 \|_{L^\infty} t} \right) = \min \left( 1, \| \omega_0 \|_{L^1} \right).
\]

The existence of such \( T > 0 \) can be justified by a continuity argument and this ends the proof of the proposition. □
4.4. **Existence.** The existence part can be done in a similar way to the case of smooth patches by smoothing out the initial data. However we should be careful about this procedure which must preserve the imposed geometric structure. Especially we have seen in the a priori estimates that a constant density close to the singular set is a crucial fact and thereby this must be satisfied for the smooth approximation of the density. Hence we smooth the initial velocity as before by setting $v_{0,n} = S_n v_0$ but for the density we have to choose a compactly supported mollifiers. More precisely, we take $\phi \in C_0^\infty(\mathbb{R}^2)$ a positive function supported in the ball of center 0 and radius 1 and of integral 1 over $\mathbb{R}^2$. We denote by $(\phi_n)_{n \in \mathbb{N}}$ the usual mollifiers:
$$\phi_n(x) = n^2 \phi(nx)$$
and we set
$$\rho_{0,n} = \phi_n * \rho_0.$$  
Then the following uniform bounds hold true,
$$\|\rho_{0,n}\|_{L^2} \leq \|\nabla \rho_0\|_{L^2}, \quad \|\nabla \rho_{0,n}\|_{L^1 \cap L^\infty} \leq \|\nabla \rho_0\|_{L^1 \cap L^\infty}$$
and
$$\|\partial_{X_{0,\lambda}} \rho_{0,n}\|_{C^0} \leq \|\partial_{X_{0,\lambda}} \rho_0\|_{C^0} + \|X_{0,\lambda}\|_{C^0} \|\nabla \rho_0\|_{L^\infty}.$$  
The first two estimates are easy to get by using the classical properties of the convolution laws. The proof of the last estimate is obtained by writing the identity
$$\partial_{X_{0,\lambda}} \rho_{0,n} = \phi_n * (\partial_{X_{0,\lambda}} \rho_0) + [\partial_{X_{0,\lambda}}, \phi_n * \rho_0],$$
where we use the notation $[A, B \ast f] = A(B \ast f) - B \ast (Af)$. We can easily check that the first term is uniformly bound in $C^0$, as to the second one we use Proposition 8 which gives
$$\|[\partial_{X_{0,\lambda}}, \phi_n * \rho_0]\|_{C^0} \leq C\|X_{0,\lambda}\|_{C^0} \|\nabla \rho_0\|_{L^\infty}.$$  
It remains to show that $\rho_{0,n}$ is constant in small neighborhood of $\Sigma_0$. For this aim we consider the set
$$(\Sigma_0)_{r-\frac{1}{n}} \triangleq \left\{ x \in \mathbb{R}^2; d(x, \Sigma_0) \leq r - \frac{1}{n} \right\}.$$  
We can easily check according to the support property of the convolution that $\rho_{0,n}$ is constant in the set $\Sigma_{r-\frac{1}{n}}^0$ which contains $(\Sigma_0)_{r/2}$ for $n$ big enough. The remaining of the proof is similar to the one of the Theorem 1 and we omit here the details.

4.5. **Uniqueness.** It seems that the uniqueness argument performed in the smooth patches cannot be easily extended to singular patches because the velocity is not Lipschitz. To avoid this difficulty we shall use the original argument of Yudovich [39]. First let us observe according to [10] that the velocity does not necessary belong to $L^2$ but to an affine space of type $\sigma + L^2$. The vector field $\sigma$ is a stationary solution for Euler equations and can be constructed as follows: let $g$ be a radial function in $C_0^\infty$ supported away from the origin and set,
$$\sigma(x) = \frac{x}{|x|^2} \int_0^{|x|} rg(r)dr.$$  
Such $\sigma$ is a smooth stationary solutions of the incompressible Euler system,
$$\partial_\lambda \sigma = \mathbb{P}(\sigma \cdot \nabla \sigma) = 0$$
where $\mathbb{P} \triangleq \Delta^{-1} \text{div}$ is Leray’s projector onto divergence-free vector fields. It behaves like $1/|x|$ at infinity and $\nabla \sigma$ belongs to $H^s(\mathbb{R}^2)$ for all $r \in \mathbb{R}$. For a vortex patch we can show that its velocity given by Biot-Savart law belongs to some $\sigma + L^2$.
Let us state the following lemma

**Lemma 7.** Let $\sigma$ be a stationary vector field satisfying (45) and $(v_0, \rho_0)$ be a smooth initial data belonging to $(\sigma + L^2) \times L^2$. Then any local solution $(v(t), \rho(t))$ of the system (1) associated to the initial data $(v_0, \rho_0)$ belongs to $(\sigma + L^2) \times L^2.$
Proof. Setting $v = u + \sigma$ then the system (1) can be written in the form,

\[
\begin{aligned}
\begin{cases}
\partial_t u + (u + \sigma) \cdot \nabla u &= -u \cdot \nabla \sigma - \nabla p + \rho \vec{e}_2, \\
\partial_t \rho + (u + \sigma) \cdot \nabla \rho &= 0, \\
u_{|t=0} &= v_0 + \sigma, \quad \rho_{|t=0} = \rho_0.
\end{cases}
\end{aligned}
\]  

Since $\text{div} u = \text{div} \sigma = 0$, then we have the following $L^2$ estimates

\[
\|u(t)\|_{L^2} \leq \|u_0\|_{L^2} + \|\rho_0\|_{L^2} t + \|\nabla \sigma\|_{L^\infty} \int_0^t \|u(\tau)\|_{L^2} d\tau.
\]

By Gronwall inequality we conclude that

\[
\|u(t)\|_{L^2} \leq (\|u_0\|_{L^2} + \|\rho_0\|_{L^2} t) e^{\|\nabla \sigma\|_{L^\infty} t}.
\]

This conclude the proof of the lemma.

Now we shall prove the uniqueness part. As we have already seen the velocity belongs to $\sigma + L^2$ and the uniqueness in the space $L^\infty \cap L^2$ should be done by using the formulation (46). However for the clarity of the proof we shall assume that $\sigma = 0$ and the proof works for non trivial $\sigma$ as well. Let $(v_1, \rho_1, p_1)$ and $(v_2, \rho_2, p_2)$ two solutions of the system (1) with the same initial data. We notice that $(v, \rho, p) \triangleq (v_2 - v_1, \rho_2 - \rho_1, p_2 - p_1)$ satisfies

\[
\begin{aligned}
\begin{cases}
\partial_t v + v \cdot \nabla v &= -v \cdot \nabla \rho - \nabla p + \rho \vec{e}_2, \\
\partial_t \rho + v \cdot \nabla \rho &= -\nabla \sigma, \\
v_{|t=0} &= v_0, \quad \rho_{|t=0} = \rho_0.
\end{cases}
\end{aligned}
\]

A standard energy method with Hölder inequality yield for all $q \in [a, +\infty]$, \[ \frac{1}{2} \frac{d}{dt} \|v\|^2_{L^2} \leq \|\nabla v(t)\|_{L^q} \|v(t)\|_{L^{2q}}^2 + \|\rho(t)\|_{L^2} \|v(t)\|_{L^2} \]

\[
\lesssim q \|\omega_1(t)\|_{L^\infty \cap L^2} \|v(t)\|_{L^\infty}^\frac{2}{q} \|v(t)\|_{L^2} \|
\]

with $q' = \frac{q}{q-1}$ and \[ \frac{1}{2} \frac{d}{dt} \|\rho(t)\|^2_{L^2} \leq \|\nabla \rho_1(t)\|_{L^\infty} \|v(t)\|_{L^2} \|ho(t)\|_{L^2}.
\]

Let $\eta$ be a small parameter and set, \[ \Gamma_{\eta}(t) \triangleq \sqrt{\|\rho(t)\|_{L^2}^2 + \|v(t)\|_{L^2}^2 + \eta}.
\]

Then, \[ \frac{d}{dt} \Gamma_{\eta}(t) \leq C_q \|\omega_1(t)\|_{L^\infty \cap L^2} \|v(t)\|_{L^\infty}^\frac{2}{q} \Gamma_{\eta}(t)^{1-\frac{2}{q}} + (1 + \|\nabla \rho_1(t)\|_{L^\infty}) \Gamma_{\eta}(t).
\]

Setting \[ \Upsilon_{\eta}(t) \triangleq e^{-\int_0^t (1 + \|\nabla \rho_1(\tau)\|_{L^\infty}) d\tau} \Gamma_{\eta}(t),
\]

we obtain \[ \frac{d}{dt} \Upsilon_{\eta}(t) \leq C_q \|\omega_1(t)\|_{L^\infty \cap L^\infty} \|v(t)\|_{L^\infty}^\frac{2}{q} \Upsilon_{\eta}(t)^{1-\frac{2}{q}} e^{-\frac{2}{q} \int_0^t (1 + \|\nabla \rho_1(\tau)\|_{L^\infty}) d\tau}
\]

which gives \[ \frac{2}{q} \Upsilon_{\eta}(t)^{\frac{2}{q}-1} \frac{d}{dt} \Upsilon_{\eta}(t) \leq C \|\omega_1(t)\|_{L^\infty \cap L^\infty} \|v(t)\|_{L^\infty}^\frac{2}{q}.
\]

Integrating in time we get \[ \Upsilon_{\eta}(t) \leq \left( \frac{1}{q} + C \int_0^t \|\omega_1(\tau)\|_{L^\infty \cap L^\infty} \|v(\tau)\|_{L^\infty} d\tau \right)^\frac{q}{2}.
\]

Letting $\eta$ go to 0 leads \[ \|\rho(t)\|_{L^2}^2 + \|v(t)\|_{L^2}^2 \leq \|v(t)\|_{L^\infty \cap L^\infty}^2 \left( C \int_0^t \|\omega_1(\tau)\|_{L^\infty \cap L^\infty} d\tau \right)^q.
\]
Then, from the Biot-Savart law we have for \( a \in (1, 2) \)

\[
\|\rho(t)\|_{L^2}^2 + \|\nu(t)\|_{L^2}^2 \leq \|\omega(t)\|_{L^0(L^\infty)}^2 \left( C \int_0^t \|\omega_1(\tau)\|_{L^\infty(L^\infty)} \, d\tau \right)^q \\
\leq C_0 \left( C \int_0^t \|\omega_1(\tau)\|_{L^\infty(L^\infty)} \, d\tau \right)^q.
\]

Therefore, we may find \( T \) such that \( \int_0^T \|\omega_1(\tau)\|_{L^\infty(L^\infty)} \, d\tau < \frac{1}{C_0}. \) Letting first \( q \) tend to \( +\infty \) and using bootstrap arguments we can conclude that \((v, \rho) \equiv 0 \) on \([0, T_0]\).

5. APPENDIX

**Proposition 8.** Given \( 0 < \varepsilon < 1 \), \( X \) a vector field belonging to \( C^\varepsilon \) and \( f \in Lip(\mathbb{R}^2) \). Let \( \phi \in C_0^\infty(\mathbb{R}^2) \) be a positive function supported in the ball of center 0 and radius 1 and such that \( \int_{\mathbb{R}^2} \phi(x) \, dx = 1 \). For all \( n \in \mathbb{N} \) we set

\[
\phi_n(x) = n^2 \phi(nx),
\]

and we denote by \( R_n \) the convolution operator with the function \( \phi_n \). Then we have the following estimate

\[
\| [\partial_X, R_n] f \|_{C^\varepsilon} \leq C \|X\|_c \|\nabla f\|_{L^\infty}.
\]

**Proof.** By definition we write

\[
[\partial_X, R_n] f(x) = \int_{\mathbb{R}^2} \phi_n(x-y)(X(x) - X(y)) \nabla f(y) \, dy.
\]

Then for all \( x_1, x_2 \in \mathbb{R}^2 \) such that \( |x_1 - x_2| < 1 \) one has

\[
[\partial_X, R_n] f(x_1) - [\partial_X, R_n] f(x_2) = I + II,
\]

where

\[
I = \int_{\mathbb{R}^2} \phi_n(x_1-y)(X(x_1) - X(x_2)) \nabla f(y) \, dy
\]

\[
II = \int_{\mathbb{R}^2} (\phi_n(x_1-y) - \phi_n(x_2-y))(X(x_2) - X(y)) \nabla f(y) \, dy.
\]

By straightforward computations we get,

\[
|I| \leq \|\nabla f\|_{L^\infty} \|\phi\|_{L^1} |x_1-x_2|^{\varepsilon} \|X\|_{C^\varepsilon}.
\]

As \( \phi \) is supported in the ball of center 0 and radius \( \frac{1}{n} \), then we may write

\[
|II| \leq \|\nabla f\|_{L^\infty} \int_{B(x_1, \frac{1}{n}) \cup B(x_2, \frac{1}{n})} |\phi_n(x_1-y) - \phi_n(x_2-y)||X(x_2) - X(y)| \, dy
\]

\[
\leq \|\nabla f\|_{L^\infty} (II_1 + II_2 + II_3),
\]

with

\[
II_1 = \int_{B(x_1, \frac{1}{n})} |\phi_n(x_1-y) - \phi_n(x_2-y)||X(x_2) - X(x_1)| \, dy
\]

\[
II_2 = \int_{B(x_1, \frac{1}{n})} |\phi_n(x_1-y) - \phi_n(x_2-y)||X(x_1) - X(y)| \, dy
\]

and

\[
II_3 = \int_{B(x_2, \frac{1}{n})} |\phi_n(x_1-y) - \phi_n(x_2-y)||X(x_2) - X(y)| \, dy.
\]

The term \( II_1 \) can be treated by the same way as \( I \). For term \( II_2 \) we have

\[
II_2 \leq n^{2+\varepsilon} \|\phi\|_{L^1} \|X\|_c \int_{B(x_1, \frac{1}{n})} |x_1 - y|^{\varepsilon} \, dy
\]

\[
\leq \|\phi\|_{L^1} \|X\|_c.\]
The bound of and $\Pi_3$ is done similarly.

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