Drawings of Planar Graphs with Few Slopes and Segments

Dedicated to Godfried Toussaint on his 60th birthday.

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Abstract

We study straight-line drawings of planar graphs with few segments and few slopes. Optimal results are obtained for all trees. Tight bounds are obtained for outerplanar graphs, 2-trees, and planar 3-trees. We prove that every 3-connected plane graph on \( n \) vertices has a plane drawing with at most \( \frac{5}{2}n \) segments and at most \( 2n \) slopes. We prove that every cubic 3-connected plane graph has a plane drawing with three slopes (and three bends on the outerface). In a companion paper, drawings of non-planar graphs with few slopes are also considered.

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1 Introduction

A common requirement for an aesthetically pleasing drawing of a graph is that the edges are straight. This paper studies the following additional requirements of straight-line graph drawings:

1. minimise the number of segments in the drawing, and
2. minimise the number of distinct edge slopes in the drawing.

First we formalise these notions. Consider a mapping of the vertices of a graph to distinct points in the plane. Now represent each edge by the closed line segment between its endpoints. Such a mapping is a (straight-line) drawing if the only vertices that each edge intersects are its own endpoints. By a segment in a drawing, we mean a maximal set of edges that form a line segment. The slope of a line $L$ is the angle swept from the X-axis in an anticlockwise direction to $L$ (and is thus in $[0, \pi)$). The slope of an edge or segment is the slope of the line that extends it. Of course two edges have the same slope if and only if they are parallel. A crossing in a drawing is a pair of edges that intersect at some point other than a common endpoint. A drawing is plane if it has no crossings. A plane graph is a planar graph with a fixed combinatorial embedding and a specified outerface. We emphasise that a plane drawing of a plane graph must preserve the embedding and outerface. That every plane graph has a plane drawing is a famous result independently due to Wagner [26] and Fáry [12].

In this paper we prove lower and upper bounds on the minimum number of segments and slopes in (plane) drawings of graphs. In a companion paper [10], we consider drawings of non-planar graphs with few slopes. A summary of our results is given in Table 1. A number of comments are in order when considering these results:

- The minimum number of slopes in a drawing of (plane) graph $G$ is at most the minimum number of segments in a drawing of $G$.
- Upper bounds for plane graphs are stronger than for planar graphs, since for planar graphs one has the freedom to choose the embedding and outerface. On the other hand, lower bounds for planar graphs are stronger than for plane graphs.
- Deleting an edge in a drawing cannot increase the number of slopes, whereas it can increase the number of segments. Thus, the upper bounds for slopes are applicable to all subgraphs of the mentioned graph families, unlike the upper bounds for segments.

The paper is organised as follows. In Section 3 we consider drawings with two or three slopes, and conclude that it is $NP$-complete to determine whether a graph has a plane drawing on two slopes.

Section 4 studies plane drawings of graphs with small treewidth. In particular, we consider trees, outerplanar graphs, 2-trees, and planar 3-trees. For any tree, we construct a plane drawing with the minimum number of segments and the minimum number of slopes. For outerplanar graphs, 2-trees, and planar 3-trees, we determine bounds on the minimum number of segments and slopes that are tight in the worst-case.
Table 1: Summary of results (ignoring additive constants). Here \( n \) is the number of vertices, \( \eta \) is the number of vertices of odd degree, and \( \Delta \) is the maximum degree. The lower bounds are existential, except for trees, for which the lower bounds are universal.

| graph family          | \# segments | \# slopes |
|-----------------------|-------------|-----------|
| trees                 | \( \frac{n}{2} \) | \( \frac{\eta}{2} \) | \( \lceil \frac{\Delta}{2} \rceil \) | \( \lceil \frac{\Delta}{2} \rceil \) |
| maximal outerplanar   | \( n \)     | \( n \)   | -           | \( \eta \) |
| plane 2-trees         | \( 2n \)    | \( 2n \)  | \( 2n \)    | \( 2n \) |
| plane 3-trees         | \( 2n \)    | \( 2n \)  | \( 2n \)    | \( 2n \) |
| plane 2-connected     | \( \frac{5}{2}n \) | -       | \( 2n \)    | - |
| planar 2-connected    | \( 2n \)    | -       | \( n \)     | - |
| plane 3-connected     | \( 2n \)    | \( \frac{5}{2}n \) | \( 2n \)    | \( 2n \) |
| planar 3-connected    | \( 2n \)    | \( \frac{11}{2}n \) | \( n \)     | \( 2n \) |
| plane 3-connected cubic| -           | \( n + 2 \) | 3           | 3 |

Section 5 studies plane drawings of 3-connected plane and planar graphs. In the case of slope-minimisation for plane graphs we obtain a bound that is tight in the worst case. However, our lower bound examples have linear maximum degree. We drastically improve the upper bound in the case of cubic graphs. We prove that every 3-connected plane cubic graph has a plane drawing with three slopes, except for three edges on the outerface that have their own slope. As a corollary we prove that every 3-connected plane cubic graph has a plane ‘drawing’ with three slopes and three bends on the outerface.

We now review some related work from the literature.

Plane orthogonal drawings with two slopes (and few bends) have been extensively studied [2, 3, 19–25]. For example, Ungar [25] proved that every cyclically 4-edge-connected plane cubic graph has a plane drawing with two slopes and four bends on the outerface. Thus our result for 3-connected plane cubic graphs (Corollary 4) nicely complements this theorem of Ungar.

Contact and intersection graphs of segments in the plane with few slopes is an interesting line of research. The intersection graph of a set of segments has one vertex for each segment, and two vertices are adjacent if and only if the corresponding segments have a non-empty intersection. Hartman et al. [14] proved that every bipartite planar graph is the intersection graph of some set of horizontal and vertical segments. A contact graph is an intersection graph of segments for which no two segments have an interior point in common. Strengthening the above result, de Fraysseix et al. [7] (and later, Czyzowicz et al. [4]) proved that every bipartite planar graph is a contact graph of some set of horizontal and vertical segments. Similarly, de Castro et al. [5] proved that every triangle-free planar graph is a contact graph of some set of segments with only three distinct slopes. It is an open problem whether every planar graph is the intersection graph of a set of segments in the plane; see [6, 17] for the most recent results. It is even possible that every \( k \)-colourable planar graph (\( k \leq 4 \)) is the intersection graph of some set of segments using only \( k \) distinct slopes.
1.1 Definitions

We consider undirected, finite, and simple graphs $G$ with vertex set $V(G)$ and edge set $E(G)$. The number of vertices and edges of $G$ are respectively denoted by $n = |V(G)|$ and $m = |E(G)|$. The maximum degree of $G$ is denoted by $\Delta(G)$.

For all $S \subseteq V(G)$, the \textit{(vertex-)} induced subgraph $G[S]$ has vertex set $S$ and edge set $\{vw \in E(G) : v, w \in S\}$. For all $S \subseteq V(G)$, let $G \setminus S$ be the subgraph $G[V(G) \setminus S]$. For all $v \in V(G)$, let $G \setminus v = G \setminus \{v\}$. For all $A, B \subseteq V(G)$, let $G[A, B]$ be the bipartite subgraph of $G$ with vertex set $A \cup B$ and edge set $\{vw \in E(G) : v \in A \setminus B, w \in B \setminus A\}$.

For all $S \subseteq E(G)$, the \textit{(edge-)} induced subgraph $G[S]$ has vertex set $\{v \in V(G) : \exists vw \in S\}$ and edge set $S$. For all pairs of vertices $v, w \in V(G)$, let $G \cup vw$ be the graph with vertex set $V(G)$ and edge set $E(G) \cup \{vw\}$.

For each integer $k \geq 1$, $k$-trees are the class of graphs defined recursively as follows. The complete graph $K_{k+1}$ is a $k$-tree, and the graph obtained from a $k$-tree by adding a new vertex adjacent to each vertex of an existing $k$-clique is also a $k$-tree. The \textit{treewidth} of a graph $G$ is the minimum $k$ such that $G$ is a spanning subgraph of a $k$-tree. For example, the graphs of treewidth one are the forests. Graphs of treewidth two, called \textit{series-parallel}, are planar since in the construction of a 2-tree, each new vertex can be drawn close to the midpoint of the edge that it is added onto. Maximal outerplanar graphs are examples of 2-trees.

2 Some Special Plane Graphs

As illustrated in Figure 1, we have the following characterisation of plane drawings with a segment between every pair of vertices. In this sense, these are the plane drawings with the least number of segments.

\textbf{Theorem 1.} In a plane drawing of a planar graph $G$, every pair of vertices of $G$ is connected by a segment if and only if at least one of the following conditions hold:

(a) all the vertices of $G$ are collinear,

(b) all the vertices of $G$, except for one, are collinear,

(c) all the vertices of $G$, except for two vertices $v$ and $w$, are collinear, such that the line-segment $vw$ passes through one of the collinear vertices,

(d) all the vertices of $G$, except for two vertices $v$ and $w$, are collinear, such that the line-segment $vw$ does not intersect the line-segment containing $V(G) \setminus \{v, w\}$,

(e) $G$ is the 6-vertex octahedron graph (say $V(G) = \{1, 2, \ldots, 6\}$ and $E(G) = \{12, 13, 23, 45, 46, 56, 14, 15, 25, 26, 34, 36\}$) with the triangle $\{4, 5, 6\}$ inside the triangle $\{1, 2, 3\}$, and each of the triples $\{1, 4, 6\}, \{2, 5, 4\}, \{3, 6, 5\}$ are collinear.

\textbf{Proof.} As illustrated in Figure 1, in a plane graph that satisfies one of (a)-(e), every pair of vertices is connected by a segment. For the converse, consider a plane graph $G$ in which every pair of vertices is connected by a segment. Let $L$ be a maximum set of collinear
vertices. Let \( \hat{L} \) be the line containing \( L \). Then \(|L| \geq 2\). If \(|L| = 2\), then \( G = K_n \) for some \( n \leq 4 \), which is included in case (a), (b), or (d). Now suppose that \(|L| \geq 3\).

Without loss of generality, \( \hat{L} \) is horizontal. Let \( S \) and \( T \) be the sets of vertices respectively above and below \( \hat{L} \). Assume \(|S| \geq |T|\).

If \(|S| \leq 1\), then it is easily seen that \( G \) is in case (a), (b), (c), or (d). Otherwise \(|S| \geq 2\). Choose \( v \in S \) to be the closest vertex to \( \hat{L} \) (in terms of perpendicular distance), and choose \( w \in S \setminus \{v\} \) to be the next closest vertex. This is possible since \( G \) is finite. Let \( p \) be the point of intersection between \( \hat{L} \) and the line through \( v \) and \( w \).

Suppose on the contrary that there are at least two vertices \( x, y \in L \) on one side of \( p \). Say \( x \) is between \( p \) and \( y \). Then the segments \( vy \) and \( wx \) cross at a point closer to \( \hat{L} \) than \( v \). Since \( G \) is plane, there is a vertex in \( S \) at this point, contradicting our choice of \( v \). Hence there is at most one vertex in \( L \) on each side of \( p \). Since \(|L| \geq 3\), \( p \) is a vertex in \( L \), and \(|L| = 3\). Thus there is exactly one vertex in \( L \) on each side of \( p \). Let these vertices be \( x \) and \( y \).

Suppose on the contrary that there is a vertex \( u \in S \setminus \{v, w\} \). Then \( u \) is above \( w \), and \( u \) is not on the line containing \( v, w, p \) (as otherwise \( \hat{L} \) is not a maximum set of collinear points). Thus the segment \( uv \) crosses either \( wx \) or \( wy \) at a point closer to \( \hat{L} \) than \( w \). Since \( G \) is plane, there is a vertex in \( S \) at this point, contradicting our choice of \( w \). Thus \(|S| = 2\), which implies \(|T| \leq 2\).

Now \( V(G) = \{v, w, p, x, y\} \cup T \). We have \(|V(G)| \geq 6\), as otherwise \( G \) is in case (a), (b), (c) or (d). Hence \( T \neq \emptyset \). Consider a vertex \( q \in T \). The segment \( qv \) crosses \( \hat{L} \) at some vertex in \( L \). It cannot cross at \( p \) (as otherwise \( \hat{L} \) would not be a maximum set of collinear vertices). Thus every vertex \( q \in T \) is collinear with \( vx \) or \( vy \). Suppose there are two vertices \( q_1, q_2 \in T \) with \( q_1 \) collinear with \( vx \) and \( q_2 \) collinear with \( vy \). Then the segments \( q_1y \) and \( q_2x \) would cross at a point below \( \hat{L} \) but not collinear with \( vx \) or \( vy \), which is a contradiction.

Suppose there are two vertices \( q_1, q_2 \in T \) both collinear with \( vx \); say \( q_1 \) is closer to \( \hat{L} \) than \( q_2 \). Then the segments \( q_1y \) and \( q_2p \) would cross at a point below \( \hat{L} \) but not collinear with \( vx \) or \( vy \), which is a contradiction. We obtain a similar contradiction if there are two vertices \( q_1, q_2 \in T \) both collinear with \( vy \). Thus there is exactly one vertex \( q \in T \). Without loss of generality, \( q \) is collinear with \( vx \). Then \( \{v, w, x, y, p, q\} \) induce the octahedron in case (c) where \( 1 = q, 2 = y, 3 = w, 4 = x, 5 = p, \) and \( 6 = v \).

3 Drawings on Two or Three Slopes

For drawings on two or three slopes the choice of slopes is not important.

**Lemma 1.** A graph has a (plane) drawing on three slopes if and only if it has a (plane) drawing on any three slopes.

**Proof.** Let \( D \) be a drawing of a graph \( G \) on slopes \( s_1, s_2, s_3 \). Let \( t_1, t_2, t_3 \) be three given slopes. Let \( T \) be a triangle with slopes \( s_1, s_2, s_3 \). Let \( T' \) be a triangle with slopes \( t_1, t_2, t_3 \). It is well known that there is an affine transformation \( \alpha \) to transform \( T \) into \( T' \). Let \( D' \) be the result of applying \( \alpha \) to \( D \). Since parallel lines are preserved under \( \alpha \), every edge in \( D' \) has slope in \( \{t_1, t_2, t_3\} \). Since sets of collinear points are preserved under \( \alpha \), no edge passes through another vertex in \( D' \). Thus \( D' \) is a drawing of \( G \) with slopes \( t_1, t_2, t_3 \). Moreover,
two edges cross in $D$ if and only if they cross in $D'$. Thus $D'$ is plane whenever $D$ is plane.

**Corollary 1.** A graph has a (plane) drawing on two slopes if and only if it has a (plane) drawing on any two slopes.

Garg and Tamassia [13] proved that it is $\mathcal{NP}$-complete to decide whether a graph has a rectilinear planar drawing (that is, with vertical and horizontal edges). Thus Corollary 1 implies:

**Corollary 2.** It is $\mathcal{NP}$-complete to decide whether a graph has a plane drawing with two slopes.

Note that it is easily seen that $K_4$ has a drawing on four slopes, but does not have a drawing on slopes $\{0, \epsilon, \frac{\pi}{2}, \frac{\pi}{2} + \epsilon\}$ for small enough $\epsilon$.

### 4 Planar Graphs with Small Treewidth

#### 4.1 Trees

In this section we study drawings of trees with few slope and few segments. We start with the following universal lower bounds.

**Lemma 2.** The number of slopes in a drawing of a graph is at least half the maximum degree, and at least the minimum degree. The number of segments in a drawing of a graph is at least half the number of odd degree vertices.

**Proof.** At most two edges incident to a vertex $v$ can have the same slope. Thus the edges incident to $v$ use at least $\frac{1}{2} \deg(v)$ slopes. Hence the number of slopes is at least half the
maximum degree. For some vertex \( v \) on the convex hull, every edge incident to \( v \) has a distinct slope. Thus the number of slopes is at least the minimum degree.

If a vertex is internal on every segment then it has even degree. Thus each vertex of odd degree is an endpoint of some segment. Thus the number of vertices of odd degree is at most twice the number of segments. (The number of odd degree vertices is always even.)

We now show that the lower bounds in Lemma 2 are tight for trees. In fact, they can be simultaneously attained by the same drawing.

**Theorem 2.** Let \( T \) be a tree with maximum degree \( \Delta \), and with \( \eta \) vertices of odd degree. The minimum number of segments in a drawing of \( T \) is \( \eta \). The minimum number of slopes in a drawing of \( T \) is \( \lceil \frac{\Delta}{2} \rceil \). Moreover, \( T \) has a plane drawing with \( \frac{\eta}{2} \) segments and \( \lceil \frac{\Delta}{2} \rceil \) slopes.

**Proof.** The lower bounds are Lemma 2. The upper bound will follow from the following hypothesis, which we prove by induction on the number of vertices: “Every tree \( T \) with maximum degree \( \Delta \) has a plane drawing with \( \lceil \frac{\Delta}{2} \rceil \) slopes, in which every odd degree vertex is an endpoint of exactly one segment, and no even degree vertex is an endpoint of a segment.” The hypothesis is trivially true for a single vertex. Let \( x \) be a leaf of \( T \) incident to the edge \( xy \). Let \( T' = T \setminus x \). Suppose \( T' \) has maximum degree \( \Delta' \).

First suppose that \( y \) has even degree in \( T \), as illustrated in Figure 2(a). Thus \( y \) has odd degree in \( T' \). By induction, \( T' \) has a plane drawing with \( \lceil \frac{\Delta'}{2} \rceil \) slopes, in which \( y \) is an endpoint of exactly one segment. That segment contains some edge \( e \) incident to \( y \). Draw \( x \) on the extension of \( e \) so that there are no crossings. In the obtained drawing \( D \), the number of slopes is unchanged, \( x \) is an endpoint of one segment, and \( y \) is not an endpoint of any segment. Thus \( D \) satisfies the hypothesis.

![Figure 2: Adding a leaf \( x \) to a drawing of a tree: (a) \( \deg(y) \) even and (b) \( \deg(y) \) odd.](image)

Now suppose that \( y \) has odd degree in \( T \), as illustrated in Figure 2(b). Thus \( y \) has even degree in \( T' \). By induction, \( T' \) has a plane drawing with \( \lceil \frac{\Delta'}{2} \rceil \) slopes, in which \( y \) is not an endpoint of any segment. Thus the edges incident to \( y \) use \( \frac{1}{2} \deg_{T'}(y) \leq \lceil \frac{\Delta'}{2} \rceil - 1 \) slopes. If the drawing of \( T' \) has any other slopes, let \( s \) be one of these slopes, otherwise let \( s \) be an unused slope. Add edge \( xy \) to the drawing of \( T' \) with slope \( s \) so that there are no crossings. In the obtained drawing \( D \), there is a new segment with endpoints \( x \) and \( y \). Since both \( x \) and \( y \) have odd degree in \( T \), and since \( x \) and \( y \) were not endpoints of any segment in the drawing of \( T' \), the induction hypothesis is maintained. The number of slopes in \( D \) is \( \max\{\lceil \frac{\Delta'}{2} \rceil, \frac{1}{2} \deg_{T'}(y) + 1\} \leq \lceil \frac{\Delta}{2} \rceil \).
4.2 Outerplanar Graphs

A planar graph \( G \) is outerplanar if \( G \) admits a combinatorial embedding with all the vertices on the boundary of a single face. An outerplanar graph \( G \) is maximal if \( G \cup vw \) is not outerplanar for any pair of non-adjacent vertices \( v, w \in V(G) \). A plane graph is outerplanar if all the vertices are on the boundary of the outerface. A maximal outerplanar graph has a unique outerplanar embedding.

**Theorem 3.** Every \( n \)-vertex maximal outerplanar graph \( G \) has an outerplanar drawing with at most \( n \) segments. For all \( n \geq 3 \), there is an \( n \)-vertex maximal outerplanar graph that has at least \( n \) segments in any drawing.

**Proof.** We prove the upper bound by induction on \( n \) with the additional invariant that the drawing is star-shaped. That is, there is a point \( p \) in (the interior of) some internal face of \( D \), and every ray from \( p \) intersects the boundary of the outerface in exactly one point.

For \( n = 3 \), \( G \) is a triangle, and the invariant holds by taking \( p \) to be any point in the internal face. Now suppose \( n > 3 \). It is well known that \( G \) has a degree-2 vertex \( v \) whose neighbours \( x \) and \( y \) are adjacent, and \( G' = G \setminus v \) is maximal outerplanar. By induction, \( G' \) has a drawing \( D' \) with at most \( n - 1 \) segments, and there is a point \( p \) in some internal face of \( D' \), such that every ray from \( p \) intersects the boundary of \( D' \) in exactly one point. The edge \( xy \) lies on the boundary of the outerface and of some internal face \( F \). Without loss of generality, \( xy \) is horizontal in \( D' \), and \( F \) is below \( xy \). Since \( G' \) is maximal outerplanar, \( F \) is bounded by a triangle \( rxy \).

For three non-collinear points \( a, b, c \) in the plane, define the wedge \( (a, b, c) \) to be the infinite region that contains the interior of the triangle \( abc \), and is enclosed on two sides by the ray from \( b \) through \( a \) and the ray from \( b \) through \( c \). By induction, \( p \) is in the wedge \( (y, x, r) \) or in the wedge \( (x, y, r) \). By symmetry we can assume that \( p \) is in \( (y, x, r) \).

Let \( R \) be the region strictly above \( xy \) that is contained in the wedge \( (x, p, y) \). The line extending the edge \( xx \) intersects \( R \). As illustrated in Figure 3, place \( v \) on any point in \( R \) that is on the line extending \( xx \). Draw the two incident edges \( vx \) and \( vy \) straight. This defines our drawing \( D \) of \( G \). By induction, \( R \cap D' = \emptyset \). Thus \( vx \) and \( vy \) do not create crossings in \( D \). Every ray from \( p \) that intersects \( R \), intersects the boundary of \( D \) in exactly one point. All other rays from \( p \) intersect the same part of the boundary of \( D \) as in \( D' \). Since \( p \) remains in some internal face, \( D \) is star-shaped. By induction, \( D' \) has \( n - 1 \) segments. Since \( vx \) and \( rx \) are in the same segment, there is at most one segment in \( D \setminus D' \). Thus \( D \) is a star-shaped outerplanar drawing of \( G \) with \( n \) segments. This concludes the proof of the upper bound.

For the lower bound, let \( G_n \) be the maximal outerplanar graph on \( n \geq 3 \) vertices whose weak dual (that is, dual graph disregarding the outerface) is a path and the maximum degree of \( G_n \) is at most four, as illustrated in Figure 4.

We claim that every drawing of \( G_n \) has at least \( n \) segments (even if crossings are allowed). We proceed by induction on \( n \). The result is trivial for \( n = 3 \). Suppose that every drawing of \( G_{n-1} \) has at least \( n - 1 \) segments, but there exists a drawing \( D \) of \( G_n \) with at most \( n - 1 \) segments. Let \( v \) be a degree-2 vertex in \( G_n \) adjacent to \( x \) and \( y \). One of \( x \) and \( y \), say \( x \), has degree three in \( G_n \). Observe that \( G_n \setminus v \) is isomorphic to \( G_{n-1} \). Thus we have a drawing of \( G_n \) with exactly \( n - 1 \) segments, which contains a drawing of \( G_n \setminus v \) with \( n - 1 \)
segments. Thus the edge $vx$ shares a segment with some other edge $xr$, and the edge $vy$ shares a segment with some other edge $ys$. Since $vxy$ is a triangle, $r \neq y$, $s \neq x$ and $r \neq s$.

Since $x$ has degree three, $y$ is adjacent to $r$, as illustrated in Figure 5. That accounts for all edges incident to $y$ and $x$. Thus $xy$ is a segment in $D$.

Now construct a drawing $D'$ of $G_{n-1}$ with $x$ moved to the position of $v$ in the drawing of $G_n$. The drawing $D$ consists of $D'$ plus the edge $xy$. Since $xy$ is a segment in $D$, $D'$ has one less segment than $D$. Thus $D'$ is a drawing of $G_{n-1}$ with at most $n-2$ segments, which is the desired contradiction. □

Open Problem 1. Is there a polynomial time algorithm to compute an outerplanar drawing of a given outerplanar graph with the minimum number of segments?

4.3 2-Trees

In this section we study drawings of 2-trees with few slopes and segments. The following lower bound on the number of slopes is immediate, as illustrated in Figure 6.
Observation 1. Let $u$, $v$ and $w$ be three non-collinear vertices in a drawing $D$ of a graph $G$. Let $d(u)$ denote the number of edges incident to $u$ that intersect the interior of the triangle $uvw$, and similarly for $v$ and $w$. Then $D$ has at least $d(u) + d(v) + d(w) + |E(G) \cap \{uv, vw, uw\}|$ slopes.

Lemma 3. Every $n$-vertex 2-tree has a plane drawing with at most $2n - 3$ segments (and thus at most $2n - 3$ slopes). For all $n \geq 3$, there is an $n$-vertex plane 2-tree that has at least $2n - 3$ slopes (and thus at least $2n - 3$ segments) in every plane drawing.

**Proof.** The upper bound follows from the Fáry-Wagner theorem since every 2-tree is planar and has $2n - 3$ edges. Consider the 2-tree $G_n$ with vertex set $\{v_1, v_2, \ldots, v_n\}$ and edge set $\{v_1v_2, v_1v_i, v_2v_i : 3 \leq i \leq n\}$. Fix a plane embedding of $G_n$ with the edge $v_1v_2$ on the triangular outerface, as illustrated in Figure 7(a). The number of slopes is at least $(n - 3) + (n - 3) + 0 + 3 = 2n - 3$ by Observation 1.

**Figure 7:** The graph $G_8$ in Lemma 3.

In Lemma 3 the embedding is fixed. A better bound can be obtained if we do not fix the embedding. For example, the graph $G_n$ from Lemma 3 has a plane drawing with $\frac{3n}{2} - 2$ segments, as illustrated in Figure 7(b).

**Theorem 4.** Every $n$-vertex 2-tree $G$ has a plane drawing with at most $\frac{3}{2}n$ segments

The key idea in the proof of Theorem 4 is to position a set of vertices at each step, rather than a single vertex. The next lemma says how to partition a 2-tree appropriately. It has subsequently been generalised for $k$-trees by Dujmović and Wood [11].

**Lemma 4.** Let $G$ be a 2-tree. Then for some $k \geq 1$, $V(G)$ can be partitioned $(S_0, S_1, S_2, \ldots, S_k)$ such that:
(a) for \(1 \leq i \leq k\), the subgraph \(G_i = G[\bigcup_{j=0}^{i} S_j]\) is a 2-tree,

(b) \(S_0\) consists of two adjacent vertices,

(c) for \(1 \leq i \leq k\), \(S_i\) is an independent set of \(G\),

(d) for \(1 \leq i \leq k\), each vertex in \(S_i\) has exactly two neighbours in \(G_{i-1}\), and they are adjacent,

(e) for \(2 \leq i \leq k\), the vertices in \(S_i\) have a common neighbour \(v\) in \(G_{i-1}\), and \(v\) has degree two in \(G_{i-1}\).

Proof. We proceed by induction on \(|V(G)|\). By definition, \(|V(G)| \geq 3\). First suppose that \(|V(G)| = 3\). Let \(V(G) = \{u, v, w\}\). Then \(G = K_3\), and \((\{u, v\}, \{w\})\) is the desired partition of \(G\). Now suppose that \(|V(G)| > 3\). Let \(L\) be the set of vertices of degree two in \(G\). Then \(L\) is a nonempty independent set, the neighbours of each vertex in \(L\) are adjacent, and \(G \setminus L\) is a 2-tree. If \(G \setminus L\) is a single edge \(vw\), then \((\{v, w\}, L)\) is the desired partition of \(G\). Otherwise, \(G \setminus L\) has a vertex \(v\) of degree two. Let \(S\) be the set of neighbours of \(v\) in \(L\). Now \(S \neq \emptyset\), as otherwise \(v \in L\). By induction, there is a partition \((S_0, S_1, S_2, \ldots, S_k)\) of \(V(G \setminus S)\) that satisfies the lemma. It is easily verified that \((S_0, S_1, S_2, \ldots, S_k, S)\) is the desired partition of \(G\).

Proof of Theorem 4. Let \((S_0, S_1, S_2, \ldots, S_k)\) be the partition of \(V(G)\) from Lemma 4. First suppose that \(k = 1\). By Lemma 4(b) and (d), \(S_0 = \{v, w\}\) and \(S_1\) is an independent set of vertices, each adjacent to both \(v\) and \(w\). Let \(S_1 = \{a_1, a_2, \ldots, a_p\} \cup \{b_1, b_2, \ldots, b_q\}\), where \(q \leq p \leq q + 1\). As illustrated in Figure 8(a), \(G\) can be drawn such that \(a_i v\) and \(b_i v\) form a single segment, for all \(1 \leq i \leq q\). The number of segments is at most \(1 + |S_1| + \left\lceil \frac{1}{2} |S_1| \right\rceil \leq \frac{3}{2}(3n - 3)\).

Now suppose that \(k \geq 2\). By Lemma 4(a), \(G_{k-1}\) is a 2-tree. Thus by induction, \(G_{k-1}\) has a plane drawing with at most \(\frac{3}{2}(n - |S_k|)\) segments. By Lemma 4(d) and (e), the vertices in \(S_k\) have degree two in \(G\), and have a common neighbour \(v\) in \(G_{k-1}\) with degree two in \(G_{k-1}\). Let \(u\) and \(w\) be the neighbours of \(v\) in \(G_{k-1}\). Then the neighbourhood of each vertex in \(S_k\) is either \(\{v, u\}\) or \(\{v, w\}\). Let \(S_k^u\) and \(S_k^w\) be the sets of vertices in \(S_k\) whose neighbourhood respectively is \(\{v, u\}\) and \(\{v, w\}\). Without loss of generality, \(|S_k^u| \geq |S_k^w|\). Let \(S_k^w = \{b_1, \ldots, b_p\}\). For the time being assume that \(|S_k^u| - p\) is even. Let \(r = \frac{1}{2}(|S_k^u| - p)\). Thus \(r\) is a nonnegative integer, and \(S_k^u\) can be partitioned

\[S_k^u = \{a_1, \ldots, a_p\} \cup \{c_1, \ldots, c_r\} \cup \{d_1, \ldots, d_r\} \, .\]

As illustrated in Figure 8(b), \(G\) can be drawn such that \(a_i v\) and \(b_i v\) form a single segment for all \(1 \leq i \leq p\), and \(c_i v\) and \(d_i v\) form a single segment for all \(1 \leq i \leq r\). Clearly the vertices can be placed to avoid crossings with the existing drawing of \(G_{k-1}\). In particular, vertices \(\{b_1, \ldots, b_p, d_1, \ldots, d_r\}\) are drawn inside the triangle \((u, v, w)\). The number of new segments in the drawing is \(3p + 3r = \frac{3}{2}|S_k|\).

In the case that \(|S_k^u| - p\) is odd, a vertex \(x\) from \(S_k^u\) can be drawn so that \(x v\) and \(x w\) form a single segment; then apply the above algorithm to \(S_k \setminus \{x\}\). The number of new segments is then \(3p + 3r + 1\), where \(|S_k| = 2p + 2r + 1\). It follows that the number of new segments is at most \(\frac{1}{2}(3|S_k| - 1)\).

In both cases, the total number of segments is at most \(\frac{3}{2}(n - |S_k|) + \frac{3}{2}|S_k| = \frac{3}{2}n\). \(\square\)
4.4 Planar 3-Trees

We now turn our attention to drawings of planar 3-trees.

**Theorem 5.** Every $n$-vertex plane 3-tree has a plane drawing with at most $2n - 2$ segments (and thus at most $2n - 2$ slopes). For all $n \geq 4$, there is an $n$-vertex plane 3-tree with at least $2n - 2$ slopes (and thus at least $2n - 2$ segments) in every drawing.

**Proof.** We prove the upper bound by induction on $n$ with the hypothesis that "every plane 3-tree with $n \geq 4$ vertices has a plane drawing with at most $2n - 2$ segments, such that for every internal face $F$ there is an edge $e$ incident to exactly one vertex of $F$, and the extension of $e$ intersects the interior of $F.$" The base case is trivial since $K_4$ is the only 3-tree on four vertices, and any plane drawing of $K_4$ satisfies the hypothesis.

Suppose that the claim holds for plane 3-trees on $n - 1$ vertices. Let $G$ be a plane 3-tree on $n$ vertices. Every $k$-tree on at least $k + 2$ vertices has two non-adjacent simplicial vertices of degree exactly $k$ [9]. In particular, $G$ has two non-adjacent simplicial degree-3 vertices, one of which, say $v$, is not on the outerface. Thus $G$ can be obtained from $G \setminus v$ by adding $v$ inside some internal face $(p, q, r)$ of $G \setminus v$, adjacent to $p$, $q$ and $r$. By induction, $G \setminus v$ has a drawing with $2n - 4$ segments in which there is an edge $e$ incident to exactly one of $(p, q, r)$, and the extension of $e$ intersects the interior of the face. Position $v$ in the interior of the face anywhere on the extension of $e$, and draw segments from $v$ to each of $p$, $q$ and $r$. We obtain a plane drawing of $G$ with $2n - 2$ segments. The extension of $vp$ intersects the interior of $(v, q, r)$; the extension of $vq$ intersects the interior of $(v, p, r)$; and the extension of $vr$ intersects the interior of $(v, p, q)$. All other faces of $G$ are faces of $G \setminus v$. Thus the inductive hypothesis holds for $G$, and the proof of the upper bound is complete.

For each $n \geq 4$ we now provide a family $G_n$ of $n$-vertex plane 3-trees, each of which require at least $2n - 2$ segments in any drawing. Let $G_4 = \{K_4\}$. Obviously every plane

---

Note that this implies that the planar 3-trees are precisely those graphs that are produced by the LEDA 'random' maximal planar graph generator. This algorithm, starting from $K_3$, repeatedly adds a new vertex adjacent to the three vertices of a randomly selected internal face.
drawing of $K_4$ has six segments. For all $n \geq 5$, let $G_n$ be the family of plane 3-trees $G$ obtained from some plane 3-tree $H \in G_{n-1}$ by adding a new vertex $v$ in the outerface of $H$ adjacent to each of the three vertices of the outerface. Any drawing of $G$ contains a drawing of $H$, which contributes at least $2n - 4$ segments by induction. In addition, the two edges incident to $v$ on the triangular outerface of $G$ are each in their own segment. Thus $G$ has at least $2n - 2$ segments.

\[ \square \]

5 3-Connected Plane Graphs

The following is the main result of this section.

**Theorem 6.** Every 3-connected plane graph with $n$ vertices has a plane drawing with at most \( \frac{5}{2}n - 3 \) segments and at most $2n - 10$ slopes.

The proof of Theorem 6 is based on the canonical ordering of Kant [16], which is a generalisation of a similar structure for plane triangulations introduced by de Fraysseix et al. [8]. Let $G$ be a 3-connected plane graph. Kant [16] proved that $G$ has a canonical ordering defined as follows. Let $\sigma = \{V_1, V_2, \ldots, V_K\}$ be an ordered partition of $V(G)$. That is, $V_1 \cup V_2 \cup \cdots \cup V_K = V(G)$ and $V_i \cap V_j = \emptyset$ for all $i \neq j$. Define $G_i$ to be the plane subgraph of $G$ induced by $V_1 \cup V_2 \cup \cdots \cup V_i$. Let $C_i$ be the subgraph of $G$ induced by the edges on the boundary of the outerface of $G_i$. As illustrated in Figure 9, $\sigma$ is a canonical ordering of $G$ (also called a canonical decomposition) if:

- $V_1 = \{v_1, v_2\}$, where $v_1$ and $v_2$ lie on the outerface and $v_1v_2 \in E(G)$.
- $V_K = \{v_n\}$, where $v_n$ lies on the outerface, $v_1v_n \in E(G)$, and $v_n \neq v_2$.
- Each $C_i$ ($i > 1$) is a cycle containing $v_1v_2$.
- Each $G_i$ is biconnected and internally 3-connected; that is, removing any two interior vertices of $G_i$ does not disconnect it.
- For each $i \in \{2, 3, \ldots, K - 1\}$, one of the following conditions holds:
  1. $V_i = \{v_i\}$ where $v_i$ is a vertex of $C_i$ with at least three neighbours in $C_{i-1}$, and $v_i$ has at least one neighbour in $G \setminus G_i$.
  2. $V_i = \{s_1, s_2, \ldots, s_\ell, v_i\}$, $\ell \geq 0$, is a path in $C_i$, where each vertex in $V_i$ has at least one neighbour in $G \setminus G_i$. Furthermore, the first and the last vertex in $V_i$ have one neighbour in $C_{i-1}$, and these are the only two edges between $V_i$ and $G_{i-1}$.

The vertex $v_i$ is called the representative vertex of the set $V_i$, $2 \leq i \leq K$. The vertices $\{s_1, s_2, \ldots, s_\ell\} \subseteq V_i$ are called division vertices. Let $S \subseteq V(G)$ be the set of all division vertices. A vertex $u$ is a successor of a vertex $w \in V_i$ if $uw$ is an edge and $u \in G \setminus G_i$. A vertex $u$ is a predecessor of a vertex $w \in V_i$ if $uw$ is an edge and $u \in V_j$ for some $j < i$. We also say that $u$ is a predecessor of $V_i$. Let $P(V_i) = \{p_1, p_2, \ldots, p_q\}$ denote the set of predecessors of $V_i$ ordered by the path from $v_1$ to $v_2$ in $C_{i-1} \setminus v_1v_2$. Vertex $p_1$ and $p_q$ are the left and right predecessors of $V_i$ respectively, and vertices $p_2, p_3, \ldots, p_{q-1}$ are called middle predecessors of $V_i$. 

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Theorem 7. Let $G$ be an $n$-vertex $m$-edge plane 3-connected graph with a canonical ordering $\sigma$. Define $S$ as above (with respect to $\sigma$). Then $G$ has a plane drawing $D$ with at most

$$m - \max \left\{ \left\lfloor \frac{n}{2} \right\rfloor - |S| - 3, |S| \right\}$$

segments, and at most

$$m - \max \left\{ n - |S| - 4, |S| \right\}$$

tslopes.

Proof. We first define $D$ and then determine the upper bounds on the number of segments and slopes in $D$. For every vertex $v$, let $X(v)$ and $Y(v)$ denote the $x$ and $y$ coordinates of $v$, respectively. If a vertex $v$ has a neighbour $w$, such that $X(w) < X(v)$ and $Y(w) < Y(v)$, then we say $vw$ is a left edge of $v$. Similarly, if $v$ has a neighbour $w$, such that $X(w) > X(v)$ and $Y(w) < Y(v)$, then we say $vw$ is a right edge of $v$. If $vw$ is an edge such that $X(v) = X(w)$ and $Y(v) < Y(w)$, then we say $vw$ is a vertical edge above $v$ and below $w$.

We define $D$ inductively on $\sigma = (V_1, V_2, \ldots, V_K)$ as follows. Let $D_i$ denote a drawing of $G_i$. A vertex $v$ is a peak in $D_i$, if each neighbour $w$ of $v$ has $Y(w) \leq Y(v)$ in $D_i$. We say that a point $p$ in the plane is visible in $D_i$ from vertex $v \in D_i$, if the segment $pv$ does not intersect $D_i$ except at $v$. At the $i^{th}$ induction step, $2 \leq i \leq K$, $D_i$ will satisfy the following invariants:

**Invariant 1:** $C_i \setminus v_1v_2$ is strictly X-monotone; that is, the path from $v_1$ to $v_2$ in $C_i \setminus v_1v_2$ has increasing $X$-coordinates.

**Invariant 2:** Every peak in $D_i$, $i < K$, has a successor.

**Invariant 3:** Every representative vertex $v_j \in V_j$, $2 \leq j \leq i$ has a left and a right edge. Moreover, if $|P(V_j)| \geq 3$ then there is a vertical edge below $v_j$.

**Invariant 4:** $D_i$ has no edge crossings.
For the base case $i = 2$, position the vertices $v_1$, $v_2$ and $v_3$ at the corners of an equilateral triangle so that $X(v_1) < X(v_3) < X(v_2)$ and $Y(v_1) < Y(v_2) < Y(v_3)$. Draw the division vertices of $V_2$ on the segment $v_1v_3$. This drawing of $D_2$ satisfies all four invariants. Now suppose that we have a drawing of $D_{i-1}$ that satisfies the invariants. There are two cases to consider in the construction of $D_i$, corresponding to the two cases in the definition of the canonical ordering.

**Case 1.** $|P(V_i)| \geq 3$: If $v_i$ has a middle predecessor $v_j$ with $|P(V_j)| \geq 3$, let $w = v_j$. Otherwise let $w$ be any middle predecessor of $v_i$. Let $L$ be the open ray $\{(X(w), y) : y > Y(w)\}$. By invariant 1 for $D_{i-1}$, there is a point in $L$ that is visible in $D_{i-1}$ from every predecessor of $v_i$. Represent $v_i$ by such a point, and draw segments between $v_i$ and each of its predecessors. That the resulting drawing $D_i$ satisfies the four invariants can be immediately verified.

**Case 2.** $|P(V_i)| = 2$: Suppose that $P(V_i) = \{w, u\}$, where $w$ and $u$ are the left and the right predecessors of $V_i$, respectively. Suppose $Y(w) \geq Y(u)$. (The other case is symmetric.) Let $P$ be the path between $w$ and $u$ on $C_{i-1} \setminus v_1v_2$. As illustrated in Figure 10, let $A_i$ be the region $\{(x, y) : y > Y(w) \text{ and } X(w) \leq x \leq X(u)\}$.

![Figure 10: Illustration for Case 2.](image)

Assume, for the sake of contradiction, that $D_{i-1} \cap A_i \neq \emptyset$. By the monotonicity of $D_{i-1}$, $P \cap A_i \neq \emptyset$. Let $p \in P \cap A_i$. Since $Y(p) > Y(w) \geq Y(u)$, $P$ is $X$-monotone and thus has a vertex between $w$ and $u$ that is a peak. By the definition of the canonical ordering $\sigma$, the addition of $V_i$ creates a face of $G$, since $V_i$ is added in the outerface of $G_{i-1}$. Therefore, each vertex between $w$ and $u$ on $P$ has no successor, and is thus not a peak in $D_{i-1}$ by invariant 2, which is the desired contradiction. Therefore $D_{i-1} \cap A_i = \emptyset$.

Let $L$ be the open ray $\{(X(u), y) : y > Y(u)\}$. If $w \not\in S$, then by invariant 3, $w$ has a left and a right edge in $D_{i-1}$. Let $c$ be the point of intersection between $L$ and the line extending the left edge at $w$. If $w \in S$, then let $c$ be any point in $A_i$ on $L$. By invariant 1, there is a point $c' \not\in \{c, w\}$ on $\overline{wv}$ such that $c'$ is visible in $D_{i-1}$ from $u$. Represent $v_i$ by $c'$, and draw two segments $\overline{c'w}$ and $\overline{c'u}$. These two segments do not intersect any part of $D_{i-1}$ (and neither is horizontal). Represent any division vertices in $V_i$ by arbitrary points on the open segment $\overline{wv} \cap A_i$. Therefore, in the resulting drawing $D_i$, there are no crossings and the remaining three invariants are maintained.
This completes the construction of \( D \). The following claim will be used to bound the number of segments and slopes in \( D \). It basically says that a division vertex (and \( v_2 \)) can be the higher predecessor for at most one set \( V_i \) with \( |P(V_i)| = 2 \).

**Claim 1.** Let \( V_i, V_j \in \sigma \) with \( i < j \) and \( |P(V_i)| = |P(V_j)| = 2 \). Let \( w_i \) be the higher of the two predecessors of \( V_i \) in \( D_{i-1} \), and let \( w_j \) be the higher of the two predecessors of \( V_j \) in \( D_{j-1} \). If \( w_i \in S \) or \( w_i = v_2 \), then \( w_i \neq w_j \).

**Proof.** Suppose that \( w_i \in V_k, k < i \). First assume that \( w_i \in S \). Then each division vertex lies on some non-horizontal segment and it is not an endpoint of that segment. Thus \( w_i \) is not a peak in \( D_k \), and therefore it is not a peak in every \( D_\ell, \ell \geq k \). For all \( \epsilon > 0 \), let

\[
A'_\epsilon = \{(x, y) : y > Y(w_i), \ell X(w_i) - \epsilon \leq x < X(w_i)\}, \quad \text{and} \quad A''_\epsilon = \{(x, y) : y > Y(w_i), \ell X(w_i) < x \leq X(w_i) + \epsilon\} .
\]

Then for all small enough \( \epsilon \), either \( A'_\epsilon \cap D_k \neq \emptyset \) or \( A''_\epsilon \cap D_k \neq \emptyset \). Without loss of generality, \( A'_\epsilon \cap D_k = \emptyset \) and \( A''_\epsilon \cap D_k \neq \emptyset \). Then at iteration \( i > k \), the region \( A_i \), as defined in Case 2 of the construction of \( D_i \), contains \( A'_\epsilon \) for all small enough \( \epsilon \). Thus, \( A'_i \cap D_i \neq \emptyset \) for all small enough \( \epsilon \). Since \( j \geq i + 1, A'_j \cap D_{j-1} \neq \emptyset \) or \( A''_j \cap D_{j-1} \neq \emptyset \) for all small enough \( \epsilon \). Therefore, \( w_i \neq w_j \) (since \( V_j \) is drawn by Case 2 of the construction of \( D_j \), where it is known that \( A_j \cap D_{j-1} = \emptyset \)). The case \( w_i = v_2 \) is the same, since the region \( A''_0 \cap D_1 = \emptyset \), for every \( \epsilon \) and every \( 1 \leq i \leq K \), so only region \( A'_\epsilon \) is used, and thus the above argument applies.

For the purpose of counting the number of segments and slopes in \( D \) assume that we draw edge \( v_1v_2 \) at iteration step \( i = 1 \) and \( G_2 \setminus v_1v_2 \) at iteration \( i = 2 \). In every iteration \( i \) of the construction, \( 2 \leq i \leq K \), at most \( |P(V_i)| \) new segments and slopes are created. We call an iteration \( i \) of the construction **segment-heavy** if the difference between the number of segments in \( D_i \) and \( D_{i-1} \) is exactly \( |P(V_i)| \), and **slope-heavy** if the difference between the number of slopes in \( D_i \) and \( D_{i-1} \) is exactly \( |P(V_i)| \). Let \( h_s \) and \( h_\ell \) denote the total number of segment-heavy and slope-heavy iterations, respectively. Then \( D \) uses at most

\[
1 + \sum_{i=2}^{K} (|P(V_i)| - 1) + h_s 
\]

segments, and at most

\[
1 + \sum_{i=2}^{K} (|P(V_i)| - 1) + h_\ell
\]

slopes.

We first express \( \sum_{i=2}^{K} |P(V_i)| \) in terms of \( m \) and \( |S| \), and then establish an upper bound on \( h_s \) and \( h_\ell \). For \( i \geq 2 \), let \( E_i \) denote the set of edges of \( G_i \) with at least one endpoint in \( V_i \), and let \( \ell_i \) denote the number of division vertices in \( V_i \). Then \( m = 1 + \sum_{i=2}^{K} |E_i| = 1 + \sum_{i=2}^{K} (\ell_i + |P(V_i)|) = 1 + |S| + \sum_{i=2}^{K} |P(V_i)| \). Thus \( \sum_{i=2}^{K} |P(V_i)| = m - |S| - 1 \). Since the trivial upper bound for \( h_s \) and \( h_\ell \) is \( K - 1 \), and by (1) and (2), we have that \( D \) uses at most \( 1 + \sum_{i=2}^{K} |P(V_i)| = 1 + m - |S| - 1 = m - |S| \) segments and slopes.
We now prove a tighter bound on $h_s$. Let $R$ denote the set of representative vertices of segment-heavy steps $i$ with $|P(V_i)| \geq 3$. Consider a step $i$ such that $|P(V_i)| \geq 3$. If $v_i$ has at least one predecessor $v_j$ with $|P(V_j)| \geq 3$, then $v_i$ is drawn on the line that extends the vertical edge below $v_j$, and thus step $i$ introduces at most $|P(V_i)| - 1$ new segments and is not segment-heavy. Therefore, step $i$ is segment-heavy only if no middle predecessor $w$ of $v_i$ is in $R$. Thus for each segment-heavy step $i$ with $|P(V_i)| \geq 3$, there is a unique vertex $w \notin R$. In other words, for each vertex in $R$, there is a unique vertex in $V(G) \setminus R$. Thus $|R| \leq \left\lceil \frac{n}{3} \right\rceil$. Since the number of segment-heavy steps $i$ with $|P(V_i)| \geq 3$ is equal to $|R|$, there is at most $\left\lceil \frac{n}{3} \right\rceil$ such steps.

The remaining steps, those with $|P(V_i)| = 2$, introduce $|P(V_i)|$ segments only if the higher of the two predecessors of $V_i$ is in $S$ or is $v_2$. (It cannot be $v_1$, since $Y(v_1) < Y(v)$ for every vertex $v \neq v_1$.) By the above claim, there may be at most $|S| + 1$ such segment-heavy steps. Therefore, $h_s \leq \left\lceil \frac{n}{3} \right\rceil + |S| + 1$. By (1) and since $K = n - 1 - |S|$, $D$ has at most $m - \left\lceil \frac{n}{3} \right\rceil + |S| + 3$ segments.

Finally, we bound $h_k$. There may be at most one slope-heavy step $i$ with $|P(v_i)| \geq 3$, since there is a vertical edge below every such vertex $v_i$ by invariant 3. As in the above case for segments, there may be at most $|S| + 1$ slope-heavy steps $i$ with $|P(v_i)| = 2$. Therefore, $h_k \leq |S| + 2$. By (2) and since $K = n - 1 - |S|$, we have that $D$ has at most $m - n + |S| + 4$ slopes.

Proof of Theorem 6. Whenever a set $V_i$ is added to $G_{i-1}$, at least $|V_i| - 1$ edges that are not in $G$ can be added so that the resulting graph is planar. Thus $|S| = \sum_i (|V_i| - 1) \leq 3n - 6 - m$. Hence Theorem 7 implies that $G$ has a plane drawing with at most $m - \frac{3}{2}n + |S| + 3 \leq \frac{3}{2}n - 3$ segments, and at most $m - n + |S| - 4 \leq 2n - 10$ slopes.

We now prove that the bound on the number of segments in Theorem 6 is tight.

Lemma 5. For all $n \equiv 0 \pmod{3}$, there is an $n$-vertex planar triangulation with maximum degree six that has at least $2n - 6$ segments in every plane drawing, regardless of the choice of outerface.

Proof. Consider the planar triangulation $G_k$ with vertex set $\{x_i, y_i, z_i : 1 \leq i \leq k\}$ and edge set $\{x_iy_i, y_iz_i, z_ix_i : 1 \leq i \leq k\} \cup \{x_ix_{i+1}, y_iy_{i+1}, z_iz_{i+1} : 1 \leq i \leq k-1\} \cup \{x_iy_{i+1}, y_iz_{i+1}, z_ix_{i+1} : 1 \leq i \leq k-1\}$. $G_k$ has $n = 3k$ vertices. $G_k$ is the famous ‘nested-triangles’ graph. We say $\{(x_i, y_i, z_i) : 1 \leq i \leq k\}$ are the triangles of $G_k$. This graph has a natural plane embedding with the triangle $x_ix_iz_i$ nested inside the triangle $(x_{i+1}, y_{i+1}, z_{i+1})$ for all $1 \leq i \leq k-1$, as illustrated in Figure 11.

We first prove that if $(x_{k}, y_k, z_k)$ is the outerface then $G_k$ has at least $6k$ segments in any plane drawing. First observe that no two edges in the triangles can share a segment. Thus they contribute $3k$ segments.

We claim that the six edges between triangles $(x_i, y_i, z_i)$ and $(x_{i+1}, y_{i+1}, z_{i+1})$ contribute a further three segments. Consider the two edges $x_ix_{i+1}$ and $z_iy_{i+1}$ incident on $x_{i+1}$. We will show that at least one of them contributes a new segment. Let $R_x$ be the region bounded by the lines containing $x_1y_i$ and $x_iz_i$ that shares only $x_i$ with triangle $(x_i, y_i, z_i)$. Similarly, let $R_z$ be the region bounded by the lines containing $x_iz_i$ and $y_iz_i$ that shares only $z_i$ with the same triangle. We note that these two regions are disjoint. Furthermore,
if edge $x_ix_{i+1}$ belongs to a segment including edges contained in triangle $(x_i, y_i, z_i)$, then $x_{i+1}$ lies in region $R_x$. Similarly, if $z_{i}x_{i+1}$ belongs to a segment including edges contained in triangle $(x_i, y_i, z_i)$, then $x_{i+1}$ lies in region $R_z$. Both cases cannot be true simultaneously so either edge $x_ix_{i+1}$ or edge $z_{i}x_{i+1}$ contributes a new segment to the drawing. Symmetric arguments apply to the edges incident on $y_{i+1}$ and $z_{i+1}$ so the edges between triangles contribute at least three segments.

Thus in total we have at least $3k + 3(k - 1) = 2n - 3$ segments. Now suppose that some face, other than $(x_k, y_k, z_k)$, is the outerface. Thus the triangles are split into two nested sets. Say there are $p$ triangles in one set and $q$ in the other. By the above argument, any drawing has at least $(2p - 3) + (2q - 3) = 2n - 6$ segments.

Lemma 5 gives a tight lower bound of $2n - c$ on the number of segments in drawings of maximal planar graphs. However, there are plane drawings with as little as $O(\sqrt{n})$ segments, as illustrated in Figure 12. Note that for planar graphs without degree two vertices, if there are $k$ segments in some drawing, then the corresponding arrangement has at most $\binom{k}{2}$ vertices. Thus $n \leq \binom{k}{2}$ and $k > \sqrt{2n}$.

We now prove that the bound on the number of slopes in Theorem 6 is tight up to an additive constant.

**Lemma 6.** For all $n \geq 3$, there is an $n$-vertex planar triangulation $G_n$ that has at least $n + 2$ slopes in every plane drawing. For a particular choice of outerface, there are at least $2n - 2$ slopes in every plane drawing.

**Proof.** Let $G_n$ be the graph with vertex set $\{v_1, v_2, \ldots, v_n\}$ and edge set $\{v_1v_i, v_2v_i : 3 \leq i \leq n\} \cup \{v_iv_{i+1} : 1 \leq i \leq n - 1\}$. $G_n$ is a planar triangulation. Every 3-cycle in $G_n$ contains $v_1$ or $v_2$. Thus $v_1$ or $v_2$ is in the boundary of the outerface in every plane drawing of $G_n$. By Observation 1, the number of slopes in any plane drawing of $G_n$ is at least $(n - 3) + 1 + 1 + 3 = n + 2$. As illustrated in Figure 13(a), if we fix the outerface of $G_n$ to be $(v_1, v_2, v_n)$, then the number of slopes is at least $(n - 3) + (n - 3) + 1 + 3 = 2n - 2$ slopes by Observation 1.\qed
As illustrated in Figure 13(b), the graph $G_n$ in Lemma 6 has a plane drawing (using a different embedding) with only $\lceil \frac{3n}{2} \rceil$ slopes.

Since deleting an edge from a drawing cannot increase the number of slopes, and every plane graph can be triangulated to a 3-connected plane graph, Theorem 6 implies:

**Corollary 3.** Every $n$-vertex plane graph has a plane drawing with at most $2n - 10$ slopes.

**Open Problem 2.** Is there some $\epsilon > 0$, such that every $n$-vertex planar triangulation has a plane drawing with $(2 - \epsilon)n + \mathcal{O}(1)$ slopes?

On the other hand, Theorem 6 does not imply any upper bound on the number of
segments for all planar graphs. A natural question to ask is whether Theorem 6 can be extended to plane graphs that are not 3-connected. We have the following lower bound.

**Lemma 7.** For all even \( n \geq 4 \), there is a 2-connected plane graph with \( n \) vertices (and \( \frac{5}{2} n - 4 \) edges) that has as many segments as edges in every drawing.

**Proof.** Let \( G_n \) be the graph with vertex set \( \{v, w, x_i, y_i : 1 \leq i \leq \frac{1}{2}(n-2)\} \) and edge set \( \{vw, x_iy_i, vx_i, vy_i, wx_i, wy_i : 1 \leq i \leq \frac{1}{2}(n-2)\} \). Consider the plane embedding of \( G_n \) with the cycle \( (v, w, y_n) \) as the outerface, as illustrated in Figure 14. Since the outerface is a triangle, no two edges incident to \( v \) can share a segment, and no two edges incident to \( w \) can share a segment. Consider two edges \( e \) and \( f \) both incident to a vertex \( x_i \) or \( y_i \). The endpoints of \( e \) and \( f \) induce a triangle. Thus \( e \) and \( f \) cannot share a segment. Therefore no two edges in \( G_n \) share a segment.

![Figure 14: The graph \( G_8 \) in Lemma 7.](image)

Note that the drawing technique from Figure 7 can be used to draw the graph \( G_n \) in Lemma 7 with only \( 2n + O(1) \) segments.

**Open Problem 3.** What is the minimum \( c \) such that every \( n \)-vertex plane (or planar) graph has a plane drawing with at most \( cn + O(1) \) segments?

### 5.1 Cubic 3-Connected Plane Graphs

A graph in which every vertex has degree three is **cubic**. It is easily seen that Theorem 7 implies that every cubic plane 3-connected graph on \( n \) vertices has a plane drawing with at most \( \frac{5}{4} n + O(1) \) segments. This result can be improved as follows.

**Lemma 8.** Every cubic plane 3-connected graph \( G \) on \( n \) vertices has a plane drawing with at most \( n + 2 \) segments.

**Proof.** Let \( D \) be the plane drawing of \( G \) from Theorem 7. Recall the definitions and the arguments for counting segments in Theorem 7. By (1), the number of segments is at most

\[ 1 + h_s + \sum_{i=2}^{K} (|P(V_i)| - 1) \]

By the properties of the canonical ordering for plane cubic graphs, \( |P(V_i)| = 2 \) for all \( 2 \leq i \leq K - 1 \), and \( |P(V_K)| = 3 \). Thus \( |R| \leq 1 \). As in Theorem 7, the number of segment-heavy steps with \( |P(V_i)| = 2 \) is at most \( |S| + 1 \). Thus \( h_s \leq |S| + 2 \). Therefore the number
of segments in $D$ is at most
\[
1 + (|S| + 2) + (K - 2) + 2 = |S| + 3 + K = |S| + n - 1 - |S| = n + 2,
\]
as claimed.

Our bound on the number of slopes in a drawing of a 3-connected plane graph (Theorem 6) can be drastically improved when the graph is cubic.

**Theorem 8.** Every cubic 3-connected plane graph has a plane drawing in which every edge has slope in $\{\frac{\pi}{4}, \frac{\pi}{2}, \frac{3\pi}{4}\}$, except for three edges on the outerface.

**Proof.** Let $\sigma = (V_1, V_2, \ldots, V_K)$ be a canonical ordering of $G$. We re-use the notation from Theorem 7, except that a representative vertex of $V_i$ may be the first or last vertex in $V_i$. Since $G$ is cubic, $|P(V_i)| = 2$ for all $1 < i < K$, and every vertex not in $\{v_1, v_2, v_n\}$ has exactly one successor. We proceed by induction on $i$ with the hypothesis that $G_i$ has a plane drawing $D_i$ that satisfies the following invariants.

**Invariant 1:** $C_i \setminus v_1v_2$ is $X$-monotone; that is, the path from $v_1$ to $v_2$ in $C_i \setminus v_1v_2$ has non-decreasing $X$-coordinates.

**Invariant 2:** Every peak in $D_i$, $i < K$, has a successor.

**Invariant 3:** If there is a vertical edge above $v$ in $D_i$, then all the edges of $G$ that are incident to $v$ are in $G_i$.

**Invariant 4:** $D_i$ has no edge crossings.

Let $D_2$ be the drawing of $G_2$ constructed as follows. Draw $v_1v_2$ horizontally with $X(v_1) < X(v_2)$. This accounts for one edge whose slope is not in $\{\frac{\pi}{4}, \frac{\pi}{2}, \frac{3\pi}{4}\}$. Now draw $v_1v_3$ with slope $\frac{\pi}{4}$, and draw $v_2v_3$ with slope $\frac{3\pi}{4}$. Add any division vertices on the segment $v_1v_3$. Now $v_3$ is the only peak in $D_2$, and it has a successor by the definition of the canonical ordering. Thus all the invariants are satisfied for the base case $D_2$.

Now suppose that $2 < i < K$ and we have a drawing of $D_{i-1}$ that satisfies the invariants. Suppose that $P(V_i) = \{u, w\}$, where $u$ and $w$ are the left and the right predecessors of $V_i$, respectively. Without loss of generality, $Y(w) \leq Y(u)$. Let the representative vertex $v_i$ be the last vertex in $V_i$. Position $v_i$ at the intersection of a vertical segment above $w$, and a segment of slope $\frac{\pi}{4}$ from $u$, and add any division vertices on $uw$, as illustrated in Figure 15(a). Note that there is no vertical edge above $w$ by invariant 3 for $D_{i-1}$. (For the case in which $Y(u) < Y(w)$, we take the representative vertex $v_i$ to be the first vertex in $V_i$, and the edge $wv_i$ has slope $\frac{3\pi}{4}$, as illustrated in Figure 15(b).)

Clearly the resulting drawing $D_i$ is $X$-monotone. Thus invariant 1 is maintained. The vertex $v_i$ is the only peak in $D_i$ that is not a peak in $D_{i-1}$. Since $v_i$ has a successor by the definition of the canonical ordering, invariant 2 is maintained. The vertical edge $wv_i$ satisfies invariant 3, since $v_i$ is the sole successor of $w$. Thus invariant 3 is maintained. No vertex between $u$ and $w$ (on the path from $u$ to $w$ in $C_{i-1} \setminus v_1v_2$) is higher than the higher of $u$ and $w$. Otherwise there would be a peak, not equal to $v_n$, with no successor, and thus
violating invariant 2 for $D_{i-1}$. Thus the edges in $D_i \setminus D_{i-1}$ do not cross any edges in $D_i$. In particular, there is no edge $ux$ in $D_{i-1}$ with slope $\frac{\pi}{4}$ and $Y(x) > Y(u)$.

It remains to draw the vertex $v_n$. Suppose $v_n$ is adjacent to $v_1$, $u$, and $w$, where $X(v_1) < X(u) < X(w)$. By invariants 1 and 3 applied to $v_1$, $u$ and $w$, there is point $p$ vertically above $u$ that is visible from $v_1$ and $w$. Position $v_n$ at $p$ and draw its incident edges. We obtain the desired drawing of $G$. The edge $v_nu$ has slope $\frac{\pi}{2}$, while $v_nv_1$ and $v_nw$ are the remaining two edges whose slope is not in $\{\frac{\pi}{4}, \frac{\pi}{2}, \frac{3\pi}{4}\}$.

A number of notes regarding Theorem 8 are in order:

- By Lemma 1 we could have used any set of three slopes instead of $\{\frac{\pi}{4}, \frac{\pi}{2}, \frac{3\pi}{4}\}$ in Theorem 8.

- By Observation 1, the bound of six on the number of slopes in Theorem 8 is optimal for any 3-connected cubic plane graph whose outerface is a triangle. It is easily seen that there is such a graph on $n$ vertices for all even $n \geq 4$.

- Theorem 8 was independently obtained by Kant [15]. We believe that our proof is much simpler. Kant [15] also claimed to prove that every planar graph with maximum degree three has a 3-slope drawing (except for one bent edge). This claim is false. Consider the plane graph $G$ illustrated in Figure 16(a). It is easily seen that $G$ has no 3-slope plane (straight-line) drawing. Thus the cubic plane graph illustrated in Figure 16(b), which contains a linear number of copies of $G$, must have a linear number of bends in any plane drawing on three slopes.

Kant [15] also claimed to prove that every planar graph with maximum degree three (except $K_4$) has a drawing in which every angle (between consecutive edges incident to a vertex) is at least $\frac{\pi}{3}$, except for at most four angles. The example in Figure 16(b) is a counterexample to this claim as well. It is easily seen that every drawing of $G$ has an angle less than $\frac{\pi}{3}$. (Assume otherwise, and start from back-to-back drawings of two equilateral triangles.) Thus the cubic plane graph illustrated in Figure 16(b) has a linear number of angles less than $\frac{\pi}{3}$.

**Corollary 4.** Every cubic 3-connected plane graph has a plane ‘drawing’ with three slopes and three bends on the outerface.
Proof. Apply the proof of Theorem 8 with two exceptions. First the edge $v_1v_2$ is drawn with one bend. The segment incident to $v_1$ has slope $\frac{3\pi}{4}$, and the segment incident to $v_2$ has slope $\frac{\pi}{4}$. The second exception regards how to draw the edges incident to $v_n$. Suppose $v_n$ is adjacent to $v_1, u, w$, where $X(v_1) < X(u) < X(w)$. There is a point $s$ above $v_1$, a point $p$ above $u$, and a point $t$ above $w$, so that the slope of $sp$ is $\frac{\pi}{4}$ and the slope of $tp$ is $\frac{3\pi}{4}$. Place $v_n$ at $p$, draw the edge $v_nu$ vertical, draw the edge $v_1v_n$ with one bend through $s$ (with slopes $\{\frac{\pi}{2}, \frac{\pi}{4}\}$), and draw the edge $wv_n$ with one bend through $t$ (with slopes $\{\frac{\pi}{2}, \frac{3\pi}{4}\}$).

Open Problem 4. Does there exist a function $f$ such that every plane graph with maximum degree $\Delta$ has a plane drawing with $f(\Delta)$ slopes? This is open even for maximal outerplanar graphs. Note that there exist bounded degree (non-planar) graphs for which the number of slopes is unbounded in every drawing [1, 10, 18]. The best bounds are in our companion paper [10], in which we prove that there exists $\Delta$-regular $n$-vertex graphs with at least $n^{1-\frac{\Delta+4}{2\Delta}}$ slopes in every drawing.

Open Problem 5. In all our results, we have not studied other aesthetic criteria such as symmetry and small area (with the vertices at grid points). Many open problems remain when combining “few slopes or segments” with other aesthetic criteria. For example, can Theorem 8 be generalised to prove that every cubic 3-connected plane graph on $n$ vertices has a plane grid drawing with polynomial (in $n$) area, such that every edge has one of three slopes (except for three edges on the outerface)?

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