Characterization of initial fluctuations for the hydrodynamical description of heavy ion collisions

Stefan Floerchinger* and Urs Achim Wiedemann†

Physics Department, Theory Unit, CERN, CH-1211 Genève 23, Switzerland

(Received 31 July 2013; published 10 October 2013)

Event-by-event fluctuations in the initial conditions for a hydrodynamical description of heavy ion collisions are characterized. We propose a Bessel-Fourier decomposition with respect to the azimuthal angle, the radius in the transverse plane, and rapidity. This allows for a complete characterization of fluctuations in all hydrodynamical fields including energy density, pressure, fluid velocity, shear stress, and bulk viscous pressure. It has the advantage that fluctuations can be ordered with respect to their wavelength and that they can be propagated mode by mode within the hydrodynamical formalism. Event ensembles can then be characterized in terms of a functional probability distribution. For the event ensemble of a Monte Carlo Glauber model, we provide evidence that the latter is close to Gaussian form, thus allowing for a particularly simple characterization of the event distribution.

DOI: 10.1103/PhysRevC.88.044906
PACS number(s): 12.38.Mh, 25.75.Nq, 25.75.Gz

I. INTRODUCTION

In recent years, data from ultrarelativistic nucleus-nucleus collisions at the CERN Large Hadron Collider [1–4] and at BNL Relativistic Heavy Ion Collider [5–7] have been understood as giving strong support to a dynamical picture according to which the produced soft hadronic distributions in transverse momentum, azimuthal orientation, centrality, and particle species are determined by the fluid dynamic response to fluctuating initial conditions [8–12]. A detailed dynamical exploration of this picture has the potential of addressing central questions in the study of hot and dense QCD matter with nucleus-nucleus collisions. In particular, one expects that fundamental transport properties of dense QCD matter, such as the ratio of shear viscosity to entropy density [13–16], can be constrained with unprecedented accuracy from the fluid dynamic propagation of fluctuations [17,18]. Moreover, to the extent to which the fluid is almost perfect and therefore almost transparent to the propagation of fluid dynamic perturbations, fluctuation analyses may provide information about the initial conditions of ultrarelativistic nucleus-nucleus collisions and their evolution towards equilibrium [19,20]. As we shall shortly recall below, and as summarized in several recent reviews [21–23], a large number of recent works address this program or parts of it.

To fully exploit these physics opportunities of fluctuation analyses, one may require that a fluid dynamic formulation of ultrarelativistic nucleus-nucleus collisions should be as complete and as differential as possible with respect to the characterization of fluctuating initial conditions, their fluid dynamic propagation, and their decoupling at freeze-out. In the present work, we propose to decompose fluctuating initial conditions in a complete, orthonormal basis of fluctuating modes that can be propagated individually, mode by mode, as fluid dynamic perturbations on a smooth event-averaged background. To this end, we employ in the following a Bessel-Fourier expansion that—with the exception of one remarkable work [24]—has not been explored for the characterization of initial conditions so far.

On the level of single events, this can provide, for instance, a more differential understanding of how fluctuating modes that differ, e.g., with respect to wavelength are attenuated or enhanced differently during the evolution, thus providing input to the question of whether structures arising on some spatial scales in the initial conditions can leave signatures in experimental observables or whether they will remain experimentally inaccessible because they are washed out in the course of the evolution.

On the level of event ensembles, the orthonormal basis makes it possible to determine a functional probability distribution that characterizes weights and eventwise correlations of all fluctuating modes in the initial conditions. This probability distribution can actually be evolved fluid dynamically by evolving each mode. The additional control we gain by this program can help, for example, to relate subclasses of events defined by cuts on experimental data [25] to subclasses of initial conditions, thus opening further possibilities for testing the dynamical relation in between.

The present paper is devoted to a detailed discussion of the Bessel-Fourier expansion for scalar, vector, and tensor fields, the ensuing characterization of event ensembles by probability distributions formulated in this basis, and the relation of this approach to other characterizations of initial conditions for individual events and event samples. As emphasized above, one important motivation for the choice of a Bessel-Fourier expansion is that its basis modes can be propagated individually as fluid dynamic perturbations. A detailed discussion of this fluid dynamic propagation will be left to a subsequent publication, but some first results are given already in a recent letter [26], and we comment in the following on properties that make the Bessel-Fourier expansion particularly suited for such a mode-by-mode fluid dynamic propagation of fluctuations.

By far the most common characterization of fluctuating initial conditions is in terms of a cumulant expansion of the initial (entropy) density distribution [27] that underlies the characterization of spatial azimuthal anisotropies in terms of...
eccentricities. We discuss in Sec. II how the coefficients in a Bessel-Fourier expansion of initial conditions are related to eccentricities. Eccentricities have been determined for initial conditions from simple model distributions [17,20,28–34], as well as for full dynamical models of ultrarelativistic heavy ion collisions (such as the UQMD [35], BAMPS [36], and AMPT codes [37]). Eccentricities and closely related cumulant-based formulations have also been used to characterize angular correlations between different harmonics [38–40], and they play currently an important role in discussing the specific initial geometry and expected fluid dynamic response of collisions between deformed nuclei (e.g., U + U) and nonidentical nuclei (e.g., Cu + Au) and of p-Pb collisions [41–45]. The fluid dynamic responses that result from initial conditions with characteristic eccentricities have been studied in much detail both on the level of single events or event averages [17,29,32,35], as well as on the level of event ensembles characterized by their probability distributions [18,28,30,33,36,37,46]. By demonstrating that data on soft hadronic spectra and correlations can be reproduced in viscous relativistic fluid dynamic simulations supplemented by realistic freeze-out and by constraining the transport properties of matter, these studies have established and are now further exploiting the paradigm that heavy ion collisions produce an almost perfect fluid.

Despite the obvious use and success of a dynamic framework that relates via fluid dynamic simulations a cumulant expansion of initial conditions to hadronic observables, there are questions that one may want to address within a fluid dynamic treatment of fluctuations and for which a cumulant expansion may not provide an optimal parametrization of initial conditions. In particular, any given (positive) transverse density can, in principle, be determined fully by the infinite set of its moments or cumulants. However, given a finite set of cumulants beyond the ones that determine a Gaussian, it is not possible to find a positive transverse density corresponding to them such that higher cumulants vanish. In particular, one cannot find positive transverse density configurations that correspond to a single cumulant only, as one may want to do if one is interested in studying the propagation and attenuation of single modes. Reference [27] had understood this problem and had devised a pragmatic approach to work around it by regulating the reconstructed densities to avoid negative values. However, introducing a regulator introduces further nonzero cumulants, and therefore, in principle, one still cannot formulate initial positive transverse densities to correspond to one cumulant only. Nevertheless, this approach has been very useful for understanding how specific structures in the initial conditions propagate fluid dynamically, in particular when applied to small deviations from a Gaussian transverse density distribution [27]. However, the Bessel-Fourier expansion of initial conditions that we discuss here (see Sec. IV) may be better suited for studying the fluid dynamic propagation of fluctuations individually mode by mode, because it avoids this problem. For a dynamical treatment of individual fluctuations, it is also advantageous that this is an expansion in an orthonormal basis, while the cumulant expansion is not. Moreover, as we discuss in Sec. V, the Bessel-Fourier expansion is easily extended to the characterization of initial fluctuations in vector and tensor fields and to their fluid dynamic propagation.

To the best of our knowledge, an extension of the cumulant expansion to vector and tensor fields has not been attempted so far. While essentially all currently used models of initial conditions neglect fluctuations in the initial fluid velocity and shear viscous tensor, they seem to be a natural possibility, and we regard it as an advantage to set up a formulation that treats them on an equal footing with fluctuations in the transverse density.

We have mentioned above that it can be useful to decompose initial fluctuations in an orthonormal basis. Such formulations have been explored so far, in particular, in studies that formulate fluid dynamic perturbations on top of simple, analytically given background fields [47–50]. For these special choices of the background field, the orthogonality of the basis modes is then preserved by the fluid dynamic evolution. However, such a simplification of mode-by-mode fluid dynamics can be expected only in the presence of additional symmetries. In particular, for the case of conformal symmetry, the basis functions used in Ref. [49] do not mix in the fluid dynamic evolution. For the case of translational invariance in the transverse plane as it is realized for a background field with Bjorken flow, a two-dimensional Fourier expansion of modes has this property [50]. We note that also the orthonormal modes of the Bessel-Fourier expansion discussed here will not mix during fluid dynamic evolution if embedded as fluctuations of a Bjorken background field with transverse translational invariance. This feature may be helpful, for instance, if one plans to check the numerical accuracy of the fluid dynamic simulation of fluctuations against simple analytically known limiting cases. In general, however, we want to characterize fluctuations in all fluid dynamic fields as eventwise perturbations of smooth realistic background fields that do not share such special symmetries. For this realistic case, the modes of fluid dynamic fields will mix under time evolution, and a differential understanding of how this mixing occurs may provide additional physics insights.

The present paper is organized as follows. In Sec. II we introduce the Bessel-Fourier transform for scalar fields, we explain how the coefficients of an expansion in this basis can be determined in a CPU-inexpensive way via Lemoine’s method of discrete Bessel transformation, and we explain how these coefficients are related to eccentricities. In Sec. III, we illustrate first the accuracy and use of this expansion by applying it to a simple model of fluctuating initial conditions. We then turn to the question of how event ensembles can be characterized in terms of probability distributions, and we show that the latter take a particularly simple and explicit form if expressed in the expansion coefficients of the Bessel-Fourier transform. In particular, we emphasize that a Gaussian ansatz for the probability distribution, specified in terms of event-averaged two-mode correlations only, can account with high accuracy for the event distributions in a model of initial conditions that is currently used in phenomenological studies.

In this sense, realistic event ensembles of initial conditions are very well approximated by simple, analytically known expressions depending on a finite number of event-averaged input data. While the Bessel-Fourier expansion of initial densities, discussed in Sec. III, does not remain positive everywhere if truncated after a finite number of modes, we...
show in Sec. IV that this problem does not exist if the expansion is applied to normalized density fluctuations. Because this approach underlies our dynamical treatment of fluctuations in Ref. [26], we discuss it here in some detail. Section V is finally discussing the extension of the Bessel-Fourier expansion to vector and tensor fields. Some general properties of Bessel transformations in continuous and discrete form are given in Appendixes A and B, while Appendix C discusses some properties of functional probability distributions for event samples.

II. CHARACTERIZING FLUCTUATING INITIAL CONDITIONS

The hydrodynamical description of heavy ion collisions is normally initialized on some space-time hypersurface shortly after the collision, at the end of a regime with nonequilibrium dynamics. In Bjorken coordinates $\tau, r, \phi, \text{ and } \eta$, related to the laboratory coordinates $x, y, z$ by $t = \tau \cosh \eta, \quad x = r \cos \phi, \quad y = r \sin \phi, \quad z = \tau \sinh \eta$, the initialization hypersurface is usually taken to correspond to fixed $\tau = \tau_0$. In this section, we consider the initial transverse enthalpy density $w(r, \phi)$ that characterizes the matter distribution at $\tau = \tau_0$. To keep notation simple, we do not denote explicitly the dependence of $w$ on time or its possible dependence on the longitudinal position along the beam direction (see Sec. V for a generalization). In practice, one might want to replace $w$ with the initial transverse energy density $\epsilon$, entropy density $s$, pressure $p$, or some charge density associated to a single event. Our discussion focuses first on how to characterize the fluctuating density $w$ of single arbitrary events in terms of a Bessel-Fourier transformation, and we turn to the discussion of event averages and event distributions later.

A. Radial decomposition of $w$: Motivation and Lemoine’s method

Our starting point is the harmonic Fourier decomposition of the azimuthal dependence of $w(r, \phi)$ in terms of the harmonics

$$w^{(m)}(r) = \frac{1}{2\pi} \int_0^{2\pi} d\phi e^{im\phi} w(r, \phi).$$

(1)

We recall that the commonly used event eccentricities $\epsilon_{n,m}$ can be defined [51] as the normalized moduli

$$\epsilon_{n,m} = |\bar{\epsilon}_{n,m}|/|\bar{\epsilon}_{n,0}|$$

(2)

of the radial moments of $w^{(m)}(r)$,

$$\bar{\epsilon}_{n,m} = 2\pi \int dr r^{n+1} w^{(m)}(r) = |\bar{\epsilon}_{n,m}| e^{im\psi_{n,m}}.$$  

(3)

In recent phenomenological studies, one often focusses on one radial moment per harmonic, selecting, for instance, the subset of eccentricities $\{\bar{\epsilon}_{2,m}\}$ or $\{\epsilon_{m,m}\}$ that is then denoted by the shorthand $\{\epsilon_{m}\}$. As we see in the following, this practice may be justified to some extent by the observation that the eccentricities $\epsilon_{n,m}$ for phenomenologically relevant density profiles tend to change only gradually and smoothly with increasing $n$. However, while the subset of eccentricities $\{\epsilon_{n}\}$ provides an incomplete characterization of $w$, the set of all $|\bar{\epsilon}_{n,m}|$ supplemented by the angular orientations $\psi_{n,m}$ is complete: The shape of the transverse density $w(r, \phi)$ of a single event can, in principle, be reconstructed unambiguously from the complete set of complex-valued $\epsilon_{n,m}$’s.

The azimuthal decomposition (1) of $w(r, \phi)$ provides a natural ordering of the azimuthal dependence that characterizes increasingly finer azimuthal structures with increasing azimuthal wave number $m$. In comparison, the connection between the $n$th moments $\epsilon_{n,m}$ of $w^{(m)}(r)$ and fluctuating modes of particular radial wavelength is arguably less direct. Here we ask how to write an alternative decomposition of the radial dependence of $w(r, \phi)$ that orders fluctuating radial modes more explicitly in terms of functions of increasingly smaller radial resolution scale. Because we expect that dynamics changes the wavelength of a fluctuation only gradually and over a sufficiently long time scale, we may hope that the modes of such an alternative expansion will mix only weakly under dynamical evolution, thus facilitating studies of the relation between modes of characteristic radial wavelength in the initial distribution and measurements that are differential in transverse momenta.

A Fourier transformation of $w$ provides arguably the simplest decomposition of a function in terms of modes of increasing resolution scale. However, in the neighborhood of $r = 0$, an expansion of $w$ in Fourier modes $e^{ikr}$ is not possible, because these do not satisfy the boundary condition $w^{(m)}(r) \propto r^m$ for small $r$. In radial coordinates, a two-dimensional Fourier transformation is an expansion in modes $\propto e^{ikr} \cos \phi$ and the $m$th harmonic moment of this Fourier mode is a Bessel function, $J_l(k r) = \int_0^{2\pi} d\phi e^{ikr} \cos \phi \propto r^l J_l(k r)$. The Bessel functions $J_l$ do have the desired limiting behavior $\propto r^m$ for $r \to 0$. These considerations prompt us to seek an expansion of the $m$th moment $w^{(m)}(r)$ in a series of Bessel functions $J_l(z)$ [24],

$$w^{(m)}(r) = \int dk k w^{(m)}(k) J_m(k r).$$

(4)

This continuous expansion becomes discrete if restricted to a finite region $r \in [0, R]$ with boundary condition

$$w^{(m)}(r) = 0 \quad \text{for } r > R \quad \text{and all } m.$$  

(5)

One can write then

$$w^{(m)}(r) = \sum_{l=1}^{\infty} w^{(m)}_l J_l(k_l r),$$

(6)

with the complex coefficients $w^{(m)}_l$ given by the integral expressions

$$w^{(m)}_l = \frac{2}{R^2 [J_{m+1}(k_l R)]^2} \int_0^R drr w^{(m)}(r) J_m(k_l r).$$

(7)

To minimize notation, we distinguish here the moment $w^{(m)}(r)$ from its Bessel transform $w^{(m)}(k)$ by its argument only. No confusion should arise because most of the following discussion is in terms of the coefficients $w^{(m)}_l$ instead of $w^{(m)}(k)$; see Eq. (6).
The discrete set of wave numbers \( k_{l}^{(m)} \) is defined in terms of the \( l \)th zero crossings \( z_{l}^{(m)} \) of the Bessel function \( J_{m}(z) \),

\[
k_{l}^{(m)} = z_{l}^{(m)} \frac{1}{R}.
\]  

(8)

By construction, the expansion (6) satisfies the boundary condition (5), and the terms with increasing \( l \) correspond to modes of smaller and smaller radial resolution \( 1/k_{l}^{(m)} \).

In this way, the characterization of the azimuthal dependence of \( w(r, \phi) \) in terms of a discrete set of azimuthal harmonics (labeled by \( m \)) can be paralleled by a characterization of its radial dependence in terms of a discrete set of radial modes labeled by \( l \).\(^{2}\)

Lemoine’s method [52] of discrete Bessel transformation simplifies the determination of the weights \( w_{l}^{(m)} \) of the Bessel expansion because it allows one to replace the integral in Eq. (7) with a finite sum,

\[
w^{(m)}(r) \approx \sum_{l=1}^{N_{l}} w_{l}^{(m)} J_{m}(k_{l}^{(m)} r).
\]  

(9)

Here, \( w_{l}^{(m)} \) are complex-valued expansion coefficients, and the approximation (9) can be improved systematically by including a larger number of terms \( N_{l} \). Remarkably, according to Lemoine’s method [52], the determination of the coefficients \( w_{l}^{(m)} \) does not involve integrations but can be done by matrix multiplication of the function \( w^{(m)}(r) \) evaluated at a discrete set of radii

\[
\rho_{a}^{(m)} = R z_{l}^{(m)} \frac{1}{\zeta_{N_{l}}},
\]  

(10)

The coefficients \( w_{l}^{(m)} \) take then the form

\[
w_{l}^{(m)} \approx \sum_{a=1}^{N_{l}} M_{l a} w(\rho_{a}^{(m)}, m),
\]  

(11)

where the matrix \( M_{l a}^{(m)} \) is independent of the properties of \( w^{(m)}(r) \) and reads

\[
M_{l a}^{(m)} = 4 J_{m}(k_{l}^{(m)} \rho_{a}^{(m)}) \left( \zeta_{N_{l}}^{-1} \right)^{2} J_{m+1}^{2}(z_{l}^{(m)}) J_{m+1}^{2}(\zeta_{a}^{(m)}).
\]  

(12)

The value of \( R \) is a parameter in the analysis that can be chosen freely as long as Eq. (5) is satisfied. In practice, it is useful to choose \( R \) as small as possible to ensure that the expansion (9) does not need to account for regions of \( r \) in which the function \( w \) vanishes. In the numerical studies for Pb-Pb collisions, discussed in later sections, we choose \( R = 8 \) fm. Once \( R \) is fixed, one can tabulate the matrix (12) and determine the complex expansion coefficients \( w_{l}^{(m)} \). If one wants to change the number \( N_{l} \) of terms in the expansion, both the matrix \( M \) in Eq. (12) and all the coefficients \( w_{l}^{(m)} \) need to be reevaluated.

From the expansion coefficients \( w_{l}^{(m)} \), the spatial density distribution can then be reconstructed,

\[
w_{\text{rec}(N_{a}, N_{l})}(r, \phi) = \sum_{l=1}^{N_{l}} w_{l}^{(m=0)} J_{0}(\zeta_{l}^{(m=0)} r/R) + 2 \sum_{m=1}^{N_{m}} \sum_{l=1}^{N_{l}} |w_{l}^{(m)}| J_{m}(\zeta_{l}^{(m)} r/R) \times \cos [m(\phi - \varphi_{l}^{(m)})].
\]  

(13)

Here we have made the phase dependence of the complex-valued Bessel coefficients explicit,

\[
w_{l}^{(m)} = |w_{l}^{(m)}| \exp \left[ im \phi_{l}^{(m)} \right].
\]  

(14)

As we illustrate with examples in the next section, the reconstructed spatial transverse density becomes an increasingly better approximation of \( w(r, \phi) \) if one increases the numbers \( N_{m} \) and \( N_{l} \) of azimuthal and radial modes included in Eq. (13).

We finally note that by inserting Eq. (9) into Eq. (3), one can express the eccentricities \( \tilde{e}_{n,m} \) in terms of a complete set of coefficients \( w_{l}^{(m)} \),

\[
\tilde{e}_{n,m} \approx R^{n+2} \sum_{l=1}^{N_{l}} K_{n}^{l} w_{l}^{(m)}(r),
\]  

(15)

where

\[
K_{n}^{l} w_{l}^{(m)} = \frac{2\pi}{(\zeta_{l}^{(m)})^{n+1}} \int_{0}^{\zeta_{l}^{(m)}} d\tilde{r} \tilde{r}^{n+1} J_{m}(\tilde{r}).
\]  

(16)

For finite \( N_{l} \), relation (15) is approximate and can be viewed as including all contributions to \( \tilde{e}_{n,m} \) that result from fluctuating modes of wavelength \( 1/k_{l}^{(m)} \) and larger. With increasing \( N_{l} \), this expression becomes more and more accurate.

### III. CHARACTERIZING INITIAL CONDITIONS WITH LEMOINE’S METHOD: A NUMERICAL EXAMPLE

The relations (15) and (16) illustrate that the information about \( w \) contained in the Bessel coefficients \( w_{l}^{(m)} \) and in the eccentricities \( \tilde{e}_{n,m} \) is complete and mathematically equivalent. It then depends on the physics problem under consideration to decide which of these two equivalent characterizations is better suited. In particular, the relation (15) makes it explicit that for any given \( n \)th moment, the \( n \)th radial moments \( \tilde{e}_{n,m} \) receive, in general, contributions from fluctuating modes of various different radial wavelengths \( 1/k_{l}^{(m)} \), \( l \in [1, N_{l}] \). In contrast, the expansion (9) of the fluctuations in Bessel functions is explicitly an expansion in modes of increasing radial resolution, and it is an expansion in an orthonormal basis. This can be helpful. To illustrate the use of organizing fluctuating modes of \( w \) with the help of a discrete Bessel transformation, we turn now to an explicit numerical example.

\(^{2}\)We remark that instead of using a Bessel expansion as in Eq. (1) directly for the transverse density \( w^{(m)}(r) \), it may be advantageous for some questions to expand a normalized version,

\[
\tilde{w}^{(m)}(r) = w^{(m)}(r)/w_{\text{back}}(r).
\]

Here, \( w_{\text{back}}(r) \) denotes an appropriately normalized “background function” that depends only on the radius \( r \) and that can be defined, e.g., as the event-averaged density \( \langle w(r, \phi) \rangle \). The motivations for this formulation and some properties are discussed in Sec. IV.
A. A simple wounded nucleon model for the initial transverse density

For illustrative purposes, we consider a simple MC Glauber model for the initial conditions in Pb-Pb collisions, similar to the one described in Ref. [34]. In the simplest version, this model determines the enthalpy density $w(r, \phi)$ as proportional to the number of wounded nucleons. Nucleons in the incoming projectiles are distributed by event randomly in the transverse plane according to the two-dimensional projection of a standard spherically symmetric two-parameter Woods-Saxon nuclear density profile. Nucleon-nucleon correlations in the incoming projectiles are neglected. The condition for collision between nucleons $i$ and $j$ of different nuclei is the simple geometric one, namely that the transverse positions $(x_i, y_i)$ of both nucleons are closer than $(x_i - x_j)^2 + (y_i - y_j)^2 \leq \sigma_{NN}/\pi$. Here we choose for the inelastic nucleon-nucleon cross section a value corresponding to $\sqrt{\sigma_{NN}} = 2.76$ TeV, namely, $\sigma_{NN} = 63$ mb. The transverse enthalpy density in this model is then obtained by centering at the transverse position of each participating nucleon an enthalpy contribution of Gaussian shape and with width $\sigma_B$, 

$$w(x, y) = N \sum_{i=1}^{N_{part}} c_i \exp\left(-\frac{(x-x_i)^2 + (y-y_i)^2}{2\sigma_B^2}\right).$$

(17)

Here the factors $c_i$ give weights to the contributions from individual participating nucleons $i$. In the model of Ref. [34], $c_i = 1$. Instead, we use a MC Glauber model that determines for each participating nucleon the number of collisions that this nucleon undergoes. The prefactors $c_i$ are then chosen such that the total entropy of the system scales with $[(1-x)N_{part}/2 + x N_{coll}]$, where $x = 0.118$. This model extension is consistent with the initial conditions used in recent fluid dynamic simulations of flow [17]. It is unimportant for the arguments made in the present paper, but because the present paper serves us also to further document the input in our recent fluid dynamic study [26], and because this study is based on state-of-the-art initial conditions, we adhere to it here. The normalization $N$ in Eq. (17) is then fixed by the total enthalpy of the system. For numerical studies, we associate to the position of each participating nucleon a Gaussian of width $\sigma_B = 0.4$ fm, except where stated otherwise. We position the center of mass (the center of enthalpy) of each event at the origin of the coordinate system.

B. Reconstructing transverse density of a single event from Bessel data

We first establish the efficiency of Lemoine’s method in reconstructing the transverse enthalpy $w$ of a single event from its Bessel coefficients $w_{l,m}^{(i)}$. To this end, we have chosen one particular Pb-Pb collision simulated with the wounded nucleon model of Sec. III A for impact parameter $b = 0$. The corresponding density distribution is shown in the top left plot in Fig. 1; it is nonvanishing in a transverse extension of radius $\sim 6$ fm, characteristic of a Pb-Pb collision, and it shows significant fluctuations. We have determined the Bessel coefficients $w_{l,m}^{(m)}$ of this distribution as discussed in Sec. II, and we have reconstructed the density distribution $w_{\text{reco}}(N_m, N_l)(r, \phi)$, including a varying number of modes $N_m$, $N_l$ in the azimuthal and radial direction. As one sees clearly from the various plots in Fig. 1, with increasing number of modes, $w_{\text{reco}}(N_m, N_l)$ reconstructs increasingly finer details of the transverse density of this single event. A larger number of modes is needed to resolve smaller scales. In general, we observe that for a relatively small number of expansion coefficients, the main features of the transverse density can be characterized and that the approximation of the true $w$ in terms of the reconstructed density (13) improves rapidly in accuracy with increasing number of modes $N_m$, $N_l$.

C. Characterizing event averages of single fluctuating modes

As seen from Fig. 1, the MC Glauber model for the initial density distribution $w$ generates spatial distributions with significant eventwise variations. We aim at quantifying these as fluctuations around an event-averaged density distribution. To this end, we first determine the event-averaged density distribution by averaging over the densities $w_i$ of a large number of events, $i \in [1, N_{\text{events}}]$. 

$$w_{\text{average}}(x, y) \equiv \langle w(x, y) \rangle \equiv \lim_{N_{\text{events}} \to \infty} \frac{1}{N_{\text{events}}} \sum_{i=1}^{N_{\text{events}}} w_i(x, y).$$

(18)

Here and in the following, the brackets $\langle \cdots \rangle$ define the event average. The event-averaged density $w_{\text{average}}$ of a Pb-Pb collisions at impact parameter $b = 0$ is shown in Fig. 2. At $b = 0$, this average is azimuthally symmetric. As a consequence, all eccentricities of $w_{\text{average}}$ with $m \neq 0$ vanish and, similarly, the event-averaged Bessel coefficients satisfy

$$\langle w_{l,m}^{(i)} \rangle = w_{l,m}^{(0)} \delta_{m0}. \quad (19)$$

The coefficients $w_{l,m}^{(0)}$ average quantify the shape of $w_{\text{average}}$ completely. As seen from Fig. 2, $w_{l,m}^{(0)}$ has significant nonzero entries only for the first few radial modes $l = 1, 2, 3, 4$. This reflects the fact that the shape of $w_{\text{average}}$ is smooth and hence only long radial wavelengths (i.e., modes with small $l$) are needed to characterize its radial dependence.

As a first step towards quantifying fluctuations on top of the event-averaged background distribution $w_{\text{average}}$, we display in Fig. 2 the dispersion $D(w_i^{(m)})$ of the event distribution of $w_i^{(m)}$ around its average,

$$D^2(w_i^{(m)}) = \langle w_i^{(m)} w_i^{(m)\ast} \rangle - \langle w_i^{(m)} \rangle \langle w_i^{(m)\ast} \rangle.$$  

(20)

Because fluctuations around $w_{\text{average}}$ break the azimuthal symmetry, one finds nonvanishing values for $\langle w_i^{(m)} w_i^{(m)\ast} \rangle$, even for $m \neq 0$, when the event average $\langle w_i^{(m)} \rangle$ vanishes. Because fluctuations vary on smaller scales than the variation of $w_{\text{average}}$, this dispersion has nonzero entries also for larger mode number $l$. For a physical understanding of the dispersion $D(w_i^{(m)})$ shown in Fig. 2, it is useful to relate the mode number $l$ to the physical scale of the corresponding radial wavelength $1/k_l^{(m)}$. For $R = 8$ fm, used in Fig. 2, and for $m = 2$, one finds, for instance, the following radial wavelengths associated with
FIG. 1. (Color online) (Top left plot) Transverse enthalpy density distribution $w(x, y)$ for one randomly chosen central Pb-Pb collision, simulated according to the model described in Sec. III A. (Remaining five plots) Reconstruction $w_{\text{reco}}(N_m, N_l)$ of this particular density distribution from the data of a discrete Bessel transformation of $w(x, y)$, involving an increasing number of modes in the azimuthal ($N_m$) and in the radial ($N_l$) direction. The point-by-point differences between the truth $w(x, y)$ and the reconstruction $w_{\text{reco}}(N_m, N_l)$ are less than 1% of the maximal density for a reconstruction with $N_m = N_l = 30$.

some modes $l$: $1/k_{l_1}^{(2)} = 1.56$ fm, $R/k_{l_2}^{(2)} = 0.45$ fm, $R/k_{l_15}^{(2)} = 0.16$ fm. The fact that for $l > 15$, the dispersions $D(w_l^{(m)})$ around $\langle w_l^{(2)} \rangle = 0$ are very small translates then directly into a statement that within the present model, event-by-event fluctuations do not induce significant variations at radial scales below 0.16 fm. In the present case, we know this, of course, because the calculation of Bessel coefficients in Fig. 2 was done for a MC Glauber model with smearing factor $\sigma_R = 0.4$ fm; see Eq. (17). We further note that in physical units, the radial wavelengths $1/k_l^{(m)} = R/z_l^{(m)}$ decrease for increasing $m$ at fixed $l$. This is a consequence of the dependence of the Bessel zero crossings $z_l^{(m)}$ on $m$ and $l$, and it explains why with increasing $m$, less and less modes $l$ give numerically significant contributions to $w_l^{(m)}$. In this way, the model discussed here
FIG. 2. (Color online) (Top row) The event-averaged density distribution \( w_{\text{average}} \) for Pb-Pb collision at impact parameter \( b = 0 \) fm and the Bessel coefficients \( w_{l}^{(m=0)} \) characterizing it. (Bottom row) Left-hand side, the dispersion of the eventwise distribution of \( w_{l}^{(m)} \) around the mean \( \langle w_{l}^{(m)} \rangle \) characterizes event-by-event fluctuations in the initial density. Right-hand side, characterization of the average event-by-event fluctuations by the event-averaged eccentricities \( \langle \epsilon_{n,m} \rangle \). Data are simulated with the wounded model of Sec. III A for a sample of \( O(1000) \) Pb-Pb collision at \( b = 0 \) fm.

illustrates the generic fact that higher modes \( m \) correspond to increasingly finer azimuthal resolution and higher Bessel modes \( l \) correspond to increasingly finer radial resolution.

Figure 2 shows also the average eccentricities \( \langle \epsilon_{n,m} \rangle \) calculated for the same sample of 1000 central Pb-Pb events. One sees that \( \epsilon_{n,m} \) tends to increase smoothly with increasing \( n \). In principle, if one would know precisely the \( n \)-dependence of \( \epsilon_{n,m} \) for all infinitely many \( n \)’s, then one could reconstruct from this information the radial dependence of \( w_{l}^{(m)}(r) \) analogously to the reconstruction given from the Bessel coefficients in Fig. 1. However, the radial dependence of \( w_{l}^{(m)}(r) \) is arguably much less directly characterized by the \( \epsilon_{n,m} \) than by the \( w_{l}^{(m)} \). This is so, because a mode characterized by \( w_{l}^{(m)} \) can be associated with a characteristic radial wavelength \( 1/k_{l}^{(m)} \), while a mode \( \epsilon_{n,m} \) will, in general, receive contributions from vastly different length scales.

D. Characterizing correlations between two fluctuating modes

The Bessel coefficients \( w_{l}^{(m)} \) that characterize the transverse density distribution \( w \) of a single event are complex valued.

In principle, a complete characterization of event samples amounts to knowing all \( n \)-mode correlators \( \langle w_{l_{1}}^{(m_{1})} \cdots w_{l_{n}}^{(m_{n})} \rangle \). As we argue in Sec. III E, knowledge of the two-mode correlators \( \langle w_{l_{1}}^{(m_{1})} w_{l_{2}}^{(m_{2})} \rangle \) can provide a satisfactory characterization for practical purposes. For the model studied here, we have checked numerically that correlations between different azimuthal harmonics \( m_{1}, m_{2} \) vanish.\(^3\) Therefore, we focus in the following discussion on two-mode correlators that are diagonal in the azimuthal mode \( m \),

\[
\{ w_{l_{1}}^{(m)} w_{l_{2}}^{(m)^*} \} = \langle |w_{l_{1}}^{(m)}|^2 \rangle \exp \left[ i m (\varphi_{l_{1}}^{(m)} - \varphi_{l_{2}}^{(m)}) \right].
\]

(21)

Histograms of the event distribution of \( w_{l}^{(m)} w_{l}^{(m)^*} \) are shown for \( m = 2 \) and \( l = 1, 2 \) in the top row of Fig. 3. One observes a distribution that does not peak at the event average, but that is of approximately exponential shape. We discuss this shape in the following section.

\(^3\)This feature is actually related to a statistical azimuthal rotation invariance; see Appendix C.
For individual events, two fluctuations characterized by the modes \((l_1, m)\) and \((l_2, m)\) can be oriented along different azimuthal directions \(\varphi_{l_1}^{(m)} \neq \varphi_{l_2}^{(m)}\). This shows up in the complex phase \(\exp[im(\varphi_{l_1}^{(m)} - \varphi_{l_2}^{(m)})]\) of the product \(w_{l_1}^{(m)} w_{l_2}^{(m)*}\) between different radial modes \(l_1 \neq l_2\); see Fig. 3. If on average two radial modes are completely decorrelated in azimuth, then the event distribution shows statistical azimuthal symmetry around the origin in the complex \(w_{l_1}^{(m)} w_{l_2}^{(m)*}\)-plane, and the event average \(\langle w_{l_1}^{(m)} w_{l_2}^{(m)*}\rangle\) vanishes. This case of azimuthal decorrelation is (approximately) realized for the distribution \((w_{l_1}^{(m)} w_{l_2}^{(m)*})\) displayed in Fig. 3. However, for second azimuthal harmonics \(m = 2\), the radial modes \(l_1 = 1\), \(l_2 = 2\) show a significant positive correlation, characterized by a nonvanishing real value of \(\langle w_{l_1}^{(m)} w_{l_2}^{(m)*}\rangle\). The plot illustrates also that there is a significant dispersion in phase and norm around this nonvanishing event-averaged correlation.

We have inspected the event distributions of off-diagonal two-mode products \(w_{l_1}^{(m)} w_{l_2}^{(m)*}\) for azimuthal modes \(1 \leq m \leq 5\) and for a large number of radial modes \(1 \leq l_1 \leq l_2 \leq 9\). Some results for the event-averaged mean \(\langle w_{l_1}^{(m)} w_{l_2}^{(m)*}\rangle\) are shown in Fig. 4. We observe a simple and generic pattern: For fixed \(m\), there is a significant azimuthal correlation between fluctuations of neighboring radial resolution, \(l_1, l_2 = l_1 \pm 1\). As the difference between radial resolutions increases a bit (next-to-neighboring modes, \(l_2 = l_1 \pm 2\)), the azimuthal correlation decreases, and modes with even larger differences in radial resolution \(l_2 = l_1 \pm n\), \(n \geq 3\) show essentially no azimuthal correlation. We have observed the same pattern for \(m = 1, 4, 5\) and for higher radial modes \(l_1, l_2\) (data not shown). The observed pattern is characteristic of the nature of the fluctuations in the Glauber model of Sec. III A. In fact, all fluctuations of this model are built up of elementary uncorrelated Gaussian-shaped building blocks of transverse spatial width \(\sigma_T = 0.4\) fm. Event by event, this generates fluctuations with a variety of different radial wavelengths, but the model does not introduce correlations between widely separated radial scales. For instance, for \(m = 2\), radial wavelengths \(1/k_2^{(2)} = R/z_2^{(2)} = 0.95\) fm and \(1/k_{2+1}^{(2)} = R/z_{2+1}^{(2)} = 0.68\) fm may be expected to show correlations because the model will result in some fluctuations of transverse scale around 0.8 fm and because fluctuations of this scale will contribute to modes of both radial wavelengths \(1/k_2^{(2)} = 0.95\) fm and \(1/k_{2+1}^{(2)} = 0.68\) fm, thus leading to an azimuthal correlation between them. However, modes of higher wave number \(l\) receive contributions from structures on smaller scales, and because the model of Sec. III A does not implement correlations among fluctuations of different scale, the pattern observed in Fig. 4 appears to be a natural consequence. We expect that a similar pattern emerges also for alternative models of initial state fluctuations that do not implement correlations among fluctuations of very different scale.

E. Characterizing event ensembles via functional probability distributions

Event samples can be characterized fully via the probability distribution \(\mathcal{P}[w]\) of their initial transverse densities, where \(\mathcal{P}[w]\) is a functional over the space of all functions \(w\). Here we discuss what can be said about the structure of \(\mathcal{P}\). In the previous sections, we have seen that the initial transverse density \(w\) of each event can be characterized completely in terms of the set of complex-valued Bessel coefficients \(\{w_{l_1}^{(m)}\}\). Therefore, one can characterize an event sample also by a
Figure 4. (Color online) The two-mode correlator $\langle w_i^{(m)} w_j^{(m_0)} \rangle$ for $m = 2$ (top plot) and $m = 3$ (bottom plot). The position of the brackets $\langle l_1 l_2 \rangle$ in these plots indicates the value taken by $\langle w_i^{(m)} w_j^{(m_0)} \rangle$.

probability distribution $\mathcal{P}[\{w_i^{(m)}\}]$ that is a function of the set of all $\{w_i^{(m)}\}$. Event averages of the coefficients $w_i^{(m)}$ and its correlators are then defined by

$$
\left\langle w_i^{(m_1)} \ldots w_i^{(m)} \right\rangle = \int \mathcal{D}[\{w_i^{(m)}\}] \prod_{m=0}^{N_m} \prod_{i=1}^{N_i} w_i^{(m)} \mathcal{P}[\{w_i^{(m)}\}],
$$

where $\mathcal{D}[\{w_i^{(m)}\}]$ defines the integration measure

$$
\mathcal{D}[\{w_i^{(m)}\}] = \prod_{m=-N_m}^{N_m} \prod_{i=1}^{N_i} w_i^{(m)}.
$$

### 1. Gaussian probability distribution

For the case of a Gaussian distribution $\mathcal{P}[w]$, one has (see also Appendix C)

$$
P[\{w_i^{(m)}\}] = \mathcal{N} \exp \left[ -\frac{1}{2} \sum_{m_1,m_2=-N_m}^{N_m} \sum_{l_1,l_2=1}^{N_i} \left( w_i^{(m_1)} - \langle w_i^{(m_1)} \rangle \right) \left( w_i^{(m_2)} - \langle w_i^{(m_2)} \rangle \right) \right] \times \mathcal{T}_{l_1,l_2} \left( w_i^{(m_1)} - \langle w_i^{(m_1)} \rangle \right) \left( w_i^{(m_2)} - \langle w_i^{(m_2)} \rangle \right).
$$

Here, $\mathcal{N}$ is an appropriate normalization factor. The matrix $T$ and the averages $\langle w_i^{(m_1)} \rangle$ in (24) are determined by

$$
\{w_i^{(m_1)}\} = \int \mathcal{D}[\{w_i^{(m)}\}] \prod_{m=0}^{N_m} \prod_{i=1}^{N_i} w_i^{(m)} \mathcal{P}[\{w_i^{(m)}\}],
$$

$$
\{w_i^{(m_1)} w_i^{(m_2)} \} = \int \mathcal{D}[\{w_i^{(m)}\}] \prod_{m=0}^{N_m} \prod_{i=1}^{N_i} w_i^{(m)} \mathcal{P}[\{w_i^{(m)}\}] = (T^{-1})^{(m_1)(m_2)} \{w_i^{(m_1)} \} \{w_i^{(m_2)} \}.
$$

For collisions at vanishing impact parameter, the azimuthal symmetry of event averages implies that

$$
\{w_i^{(m)}\} = \delta_{m0} \{w_i^{(0)}\}.
$$

At finite impact parameter, also nontrivial azimuthal modes can have nonvanishing event averages, $\langle w_i^{(m)} \rangle \neq 0$ for $m \neq 0$. However, because event-averaged distributions do not display structures at small wavelength, one expects generically that $\langle w_i^{(m)} \rangle$ is non-negligible only for very small $l$.

In general, because $\mathcal{P}$ is real, the matrix $T$ in Eq. (24) is Hermitian, and a nonvanishing complex phase of off-diagonal elements $(T^{-1})^{(m_1)(m_2)}$ measures the difference $\phi^{(m_1)} - \phi^{(m_2)}$ between the azimuthal orientations of different modes. However, the matrix $T$ is real and symmetric if the ensemble is symmetric with respect to the transformation $\psi \rightarrow -\psi$. The statistical azimuthal rotation symmetry for $b = 0$ implies further that the matrix $T$ is diagonal in the azimuthal modes $m$,

$$
(T^{-1})^{(m_1)(m_2)} = \delta_{m_1,m_2} (T^{-1})^{(m_1)(m_1)}.
$$

Within the MC Glauber model we observe in Fig. 4 that two-mode correlations decrease quickly with increasing difference in the radial wavelengths of the two modes, that is,

$$
|\langle T^{-1} \rangle_{l,j}^{(m_1)(m_2)}| > |\langle T^{-1} \rangle_{l,j+1}^{(m_1)(m_2)}| > |\langle T^{-1} \rangle_{l,j+2}^{(m_1)(m_2)}| > \ldots,
$$

and we expect that this feature is shared by other models as well.

### 2. Testing the validity of the Gaussian approximation of $\mathcal{P}$

The Gaussian probability distribution (24) is fully specified in terms of the event averages $\langle w_i^{(m_1)} \rangle$, $\langle w_i^{(m_1)} w_i^{(m_2)} \rangle$, and it provides a simple ansatz for the eventwise distribution of arbitrary products $w_i^{(m_1)} \ldots w_i^{(m)}$. Here we derive within the Gaussian approximation explicit expressions for some of these eventwise distributions, and we establish for the model of Sec. III A that these eventwise distributions are correctly described by the ansatz (24). The practical interest in this statement is that to the extent to which the Gaussian approximation (24) holds, the small set of numbers $\langle w_i^{(m_1)} \rangle$ and $\langle w_i^{(m_1)} w_i^{(m_2)} \rangle$ provides then complete information not only about all event averages, but also about the functional shapes of all event distributions.

In the recent letter [26], we have shown that experimentally measurable flow coefficients in nucleus-nucleus collisions can be written as the fluid dynamic response to diagonal and
off-diagonal products of two modes,
\[\xi_a \equiv w_{la}^{(m)} w_{lb}^{(m)a}, \quad \chi_{ab} \equiv w_{la}^{(m)} w_{lb}^{(m)a},\]
and their event averages. We are therefore particularly interested in the event distributions of \(\xi_a\) and \(\chi_{ab}\) around the averages \(\langle w_{la}^{(m)} w_{lb}^{(m)} \rangle\) and \(\langle w_{la}^{(m)} w_{lb}^{(m)} \rangle\). Here \(l_a\) and \(l_b\) denote arbitrary but fixed radial wave numbers. For an arbitrary probability distribution \(P([w_1^{(m)})]\), the distribution in \(\xi_a\) and \(\chi_{ab}\) can be calculated from
\[P_\xi(\xi_a) = \int D\{[w_1^{(m)}]\} P\{[w_1^{(m)}]\} \delta(\xi_a - w_{la}^{(m)} w_{lb}^{(m)a}), \quad (30)\]
\[P_\chi(\chi_{ab}) = \int D\{[w_1^{(m)}]\} P\{[w_1^{(m)}]\} \delta^2(\chi_{ab} - w_{la}^{(m)} w_{lb}^{(m)a}). \quad (31)\]

These are probability distributions in the real variable \(\xi_a\) and the complex variable \(\chi_{ab}\), respectively. For the Gaussian ansatz (24), the integrals in (30) and (31) can be done analytically. For the diagonal product \(\xi_a\), one finds
\[P_\xi(\xi_a) = \sigma w e^{-\sigma w \xi_a} f_0(2\sqrt{\xi} \sigma w (w_{la}^{(m)})^2) e^{-\sigma w (w_{la}^{(m)})^2} \Theta(\xi_a), \quad (32)\]
where the inverse width \(\sigma w\) is given by
\[\sigma w = \frac{1}{\langle w_{la}^{(m)} w_{lb}^{(m)a} \rangle} = \frac{1}{\langle \xi_a \rangle}. \quad (33)\]

In this section, we focus on the case of vanishing impact parameter, for which all averages \(\langle w_{l}^{(m=2)} \rangle\) vanish, and Eq. (32) reduces to an exponential \(P_\xi(\xi_a) = \sigma w \exp(-\sigma w \xi_a) \Theta(\xi_a)\). In Fig. 3, we demonstrate that once the event average \(\langle w_{la}^{(m)} w_{lb}^{(m)a} \rangle\) is specified, this provides a parameter-free and accurate description of the eventwise distribution of \(\xi_a\) in the model of Sec. III A.

For the event distribution in the complex variable \(\chi_{ab} = \chi_{ab}^r + i \chi_{ab}^i\), we find for vanishing impact parameter (i.e., for \(\langle w_{l}^{(m=2)} \rangle = 0\),
\[P_{\chi_{ab}}(\chi_{ab}^r, \chi_{ab}^i) = \frac{\det T}{2\pi} K_0(\sqrt{T_{la} T_{lb} \chi_{ab}^* \chi_{ab}}) \exp[-T_{la} T_{lb} \chi_{ab}], \quad (34)\]

Here, \(T\) denotes the two-dimensional submatrix obtained from \(T_{1a}, l_1, l_2 = l_a, l_b\). In this way, both distributions (33) and (34) are specified completely in terms of the one-mode and two-mode correlators Eqs. (25) and (26). For the model studied here, the finite number of relevant event averages is shown in Fig. 4.

To visualize the comparison of (34) to event distributions simulated in the model of Sec. III A, we show in Fig. 5 histograms of one-dimensional projections of the off-diagonal two-mode event distributions plotted in Fig. 3. These are compared to the corresponding projection of Eq. (34). We find that the Gaussian approximation (24) accounts very satisfactorily for the shape of event distributions of off-diagonal two-point correlators \(\chi_{ab}\), too. For the case of vanishing impact parameter, these studies indicate that, in practice, a small number of two-mode correlations is sufficient to specify fully the shape of event distributions of all products of two modes around these averages.

F. Lemoine’s mode decomposition at finite impact parameter:
A numerical study for \(b = 6\) fm

So far, we have focused on heavy ion collisions at vanishing impact parameter, for which event averages are azimuthally symmetric. In this section, we show that Lemoine’s method applies equally well to characterizing initial conditions at finite impact parameter. To demonstrate this, we repeat in the following the study of Secs. III C–III E for Pb-Pb collisions at impact parameter \(b = 6\) fm. Our discussion is brief, and
we focus only on those points that arise anew at finite impact parameter.

In Fig. 6, we show the density distribution of a randomly chosen Pb-Pb collision at $b = 6$ fm. In comparison to the collision at vanishing impact parameter, seen in Fig. 1, the active transverse area is clearly smaller. We have checked that Lemoine’s method characterizes the simulated densities with comparable accuracy irrespective of impact parameter. In particular, the point-by-point differences between the true enthalpy density $w(x, y)$ and the reconstruction $w_{\text{reco}(N_m, N_l)}$ are less than 1% of the maximal density for a reconstruction with $N_m = N_l = 30$.

Figure 7 shows some elementary characterizations of event averages at finite impact parameter when the event-averaged density $w_{\text{average}}$ has an approximately ellipsoidal shape that breaks azimuthal symmetry. As a consequence, there are...
nonvanishing one-mode event averages \( \langle w_l^{(m)} \rangle \) also for even integers \( m \neq 0 \). The elliptic variation of the average involves only long wavelengths, and therefore \( \langle w_l^{(m)} \rangle \) takes nonvanishing values only for small \( l \). The event-averaged eccentricities \( \langle \epsilon_{n,m} \rangle \) can be understood as being composed of a fluctuating component that is comparable to the one shown for \( b = 0 \) in Fig. 2, and an event-averaged nonfluctuating component that contributes to \( m = 2 \) (and slightly to \( m = 4 \)) for all values of \( n \) and that increases these coefficients significantly.

In the dispersion
\[
\sqrt{\langle w_l^{(m)} w_l^{(m)*} \rangle - \langle w_l^{(m)} \rangle^2},
\]
the nonfluctuating contribution is subtracted by construction. Comparing this plot to the corresponding one in Fig. 2, one see that the fluctuations around \( \langle w_l^{(m)} \rangle \) are similar at vanishing and nonvanishing impact parameter, although the event averages \( \langle w_l^{(m)} \rangle \) are characteristically different.

Also the two-mode correlators \( \langle w_{l_1}^{(m_1)} w_{l_2}^{(m_2)*} \rangle \) show remarkable similarities between collisions at finite impact parameter (see Fig. 8) and collisions at vanishing impact parameter (see Fig. 3). The overall normalization of all \( \langle w_{l_1}^{(m_1)} w_{l_2}^{(m_2)*} \rangle \) increases with the total enthalpy of the distribution, and it is thus larger for the case \( b = 0 \). Compared to the case for \( b = 0 \), however, the relative weight of \( \langle w_{l_1}^{(m=2)} w_{l_2}^{(m=2)*} \rangle \) is significantly increased in the longest wavelength modes \( l_1, l_2 = 1, 2 \) that characterize the event-averaged azimuthal anisotropy of \( w_{\text{average}} \).

At finite impact parameter, there can be nonvanishing event-averaged two-mode correlators \( \langle w_{l_1}^{(m_1)} w_{l_2}^{(m_2)*} \rangle \) also for modes corresponding to different azimuthal harmonics \( m_1 \neq m_2 \). In particular, the event-averaged shape of \( w_{\text{average}} \) at finite impact parameter contributes not only to the second but also to the fourth azimuthal harmonics and this leads to nonvanishing correlations \( \langle w_{l_1}^{(2)} w_{l_2}^{(4)*} \rangle \). As seen in Fig. 9, such correlations vanish for \( b = 0 \) within statistical uncertainties, but they are found at finite impact parameter in the model studied here. The strength of these correlations is weak if compared to correlations for modes at the same azimuthal harmonics.

Figure 10 shows event distributions for diagonal and nondiagonal two-mode products of the types
\[
\xi_a = w_{l_1}^{(m)} w_{l_2}^{(m)*} \quad \text{and} \quad \chi_{ab} = w_{l_1}^{(m)} w_{l_2}^{(m)*},
\]
respectively. In the top part of Fig. 10, we compare the simulated event distribution \( P_k(\xi_a) \) to the analytical expectation (32) for a Gaussian probability distribution (24). This comparison is analogous to the one shown in Fig. 3 for vanishing impact parameter, but it involves now a nonvanishing expectation value \( \langle w_{l_1}^{(m)} \rangle \).

Figure 10 then illustrates that while the event distributions
Fig. 8. (Color online) Same as Fig. 3 but for finite impact parameter \( b = 6 \) fm.

\( \mathcal{P}_\xi \) of different modes can have rather different shapes, they are all satisfactorily accounted for in a Gaussian probability distribution (24) that is determined by a small number of easily accessible event-averaged values, \( \langle w_{l_1}^{(m_1)} \rangle \) and \( \langle w_{l_1}^{(m_1)} w_{l_1}^{(m_1)*} \rangle \).

Figure 10 also shows examples of event distributions for off-diagonal two-mode correlators \( \chi_{ab} = w_{l_1}^{(m_1)} w_{l_2}^{(m_2)*} \). In Fig. 11, we compare one-dimensional projections of these to analytical expectations for a Gaussian probability distribution (24). For finite impact parameter, when the expectations values \( \langle w_{l_1}^{(m_1)} \rangle \) do not vanish, one finds from Eq. (31)

\[
\mathcal{P}_\chi(\chi_{ab}, \chi_{ab}) = \frac{\text{Det}[T]}{4\pi} \int dx \frac{d^2x}{x_0} \left[ \sqrt{A^2 \chi_{ab}^2 + B^2 x + 2\Re \chi_{ab} A B} \right] \times \exp \left[ -\frac{1}{2} \left( T_{l_1 l_1} x + T_{l_2 l_2} \chi_{ab} / x + 2 T_{l_1 l_2} \Re \chi_{ab} + \sum_{i,j} \langle w_{l_1}^{(m_1)} \rangle T_{ij} \langle w_{l_2}^{(m_2)} \rangle \right) \right],
\]

(35)

where

\[
A \equiv T_{l_1 l_1} \langle w_{l_1}^{(m_1)} \rangle + T_{l_2 l_2} \langle w_{l_2}^{(m_2)} \rangle,
\]

(36)

\[
B \equiv T_{l_1 l_1} \langle w_{l_1}^{(m_1)} \rangle + T_{l_2 l_2} \langle w_{l_2}^{(m_2)} \rangle.
\]

(37)

For \( \langle w_{l_1}^{(m_1)} \rangle = \langle w_{l_2}^{(m_2)} \rangle = 0 \), expression (35) reduces to the simple analytical form (34). In general, however, the event distribution \( \mathcal{P}_\chi \) depends on the two event averages \( \langle w_{l_1}^{(m_1)} \rangle \), \( \langle w_{l_2}^{(m_2)} \rangle \), and on the three independent matrix elements \( T_{ij} \). Determining the latter from (26), we confirm also at finite impact parameter that the Gaussian approximation (24) accounts very satisfactorily for the shape of event distributions of off-diagonal products \( \chi_{ab} \). At finite, as well as at vanishing impact parameter, a very small set of event averages (25) and (26) is therefore sufficient to specify fully the shape of all two-mode event distributions.

IV. NORMALIZED DENSITY FLUCTUATION

So far, we have discussed in Sec. II general properties of the Bessel-Fourier expansion (8) for transverse scalar densities, and we have studied in Sec. III applications of this expansion to a simple model of the transverse enthalpy density at vanishing and at finite impact parameter. The full enthalpy density \( w \) is, of course, positive everywhere and for each event. However, each fluctuating mode \( w_{l_1}^{(m_1)} J_m(k l_1 r) \) in the Bessel-Fourier expansion will take negative values in some spatial regions. Moreover, at large radial distance \( r \), the maximal amplitudes of the oscillating modes falls off with the root of the radial distance \( \propto \sqrt{1/r} \) only, while the enthalpy density of each
event is expected to fall off exponentially. Therefore, after truncation at a finite number of modes, the Bessel-Fourier expansion \( w \) is not guaranteed to be positive, and it may show locally negative entries, in particular, at large \( r \). As we have seen in Sec. III, this is not a problem for characterizing the initial conditions. However, it becomes an unwanted feature if one wants to propagate single modes \( w^{(m)}_l J_m(\ell^{(m)}_l r) \) fluid dynamically. The propagation of locally negative densities poses certainly problems in fluid dynamics, and irrespective of whether one deals with those by "ad hoc" regularizations of locally negative contributions or in another way, the effort to ensure that the physical results depend only sufficiently weakly on a chosen prescription will be an unwanted complication. One way to bypass this problem is to seek a Fourier-Bessel expansion of the enthalpy density normalized by some conveniently chosen background enthalpy \( w_{BG}(r) \), such that for sufficiently small fluctuations the truncated expansion remains positive by construction. Here, we explore the ansatz

\[
w^{(m)}(r) = \delta_{m0} w_{BG}(r) + w_{BG}(r) \sum_{l=1}^{\infty} \tilde{w}^{(m)}_l J_m(\ell^{(m)}_l r),
\]

where \( \tilde{w}^{(m)}_l \) are the Bessel coefficients of the normalized density \( [w^{(m)}(r) - \delta_{m0} w_{BG}(r)]/w_{BG}(r) \). We chose the background

![FIG. 10. (Color online) Event distributions of several two-mode correlators. Same as Fig. 4 but for finite impact parameter \( b = 6 \) fm.](image1)

![FIG. 11. (Color online) One-dimensional projections of the event distributions shown in Fig. 10 (blue histograms) compared to the analytical expectation (35). Without any adjustment of parameters, the Gaussian ansatz (24) fixed in terms of event averages only can account for the shapes of all event distributions \( \mathcal{P}_x \).](image2)
fluctuations at large radius $r$ take much larger values than for the un-normalized case. The Bessel-Fourier expansion tends to reproduce such structures at large $r$ and the nonvanishing values of $w(r, \phi)/w_{BG}(r)$ at the boundary $r = R$ by alternating the sign of neighboring Bessel coefficients; see Fig. 12. In general, we find that the structure of $(\tilde{u}_{l_1}^{(m)} \tilde{u}_{l_2}^{(m)\ast})$ in Fig. 12 still follows for each $m$ a simple pattern: The sign of the two-mode correlator alternates, and its norm decreases for fixed $m$ with increasing $l_2 - l_1$, as expected for a density in which radial modes decorrelate with increasing difference in wavelength. Let us mention as an aside that we have illustrated already in a first dynamical study [26] how to propagate fluid dynamically event ensembles of small fluctuations characterized by the two-point correlators $(\tilde{u}_{l_1}^{(m)} \tilde{u}_{l_2}^{(m)\ast})$ or single fluctuating modes of weight $\tilde{u}_{l_1}^{(m)}$, and we have shown how to calculate the contributions of these fluctuating modes to measured hadron spectra; see also Ref. [53].

As we have seen in Sec. III, establishing that the probability distribution of event samples of initial conditions is approximately Gaussian provides a significant simplification for the characterization of event samples. Here we note that this simplification holds also for the probability distribution $P((\tilde{u}^{(m)})_l)$ of the Bessel coefficients of the normalized density distribution $w(r, \phi)/w_{BG}(r)$: The information displayed in Fig. 11 provides an almost complete characterization of $P((\tilde{u}^{(m)})_l)$. In particular, as discussed in Sec. III D already, a Gaussian probability distribution is fully specified by the two-mode correlators $(\tilde{u}_{l_1}^{(m)} \tilde{u}_{l_2}^{(m)\ast})$, but it makes nontrivial statements about the event distributions of $\tilde{u}_{l_1}^{(m)}$, $\tilde{u}_{l_2}^{(m)\ast}$ (and higher order products) around these averages. In Eqs. (32) and (34), we have derived explicit expressions for the relevant event distributions of two-mode products. As we show in Fig. 13 for the distributions of different products of two modes, and in Fig. 14 for projections of complex-valued products $\tilde{u}_{l_1}^{(m)} \tilde{u}_{l_2}^{(m)\ast}$ on the real and imaginary axis, these distributions around event averages indicate that $P((\tilde{u}^{(m)})_l)$ is a close to Gaussian probability distribution of the form of Eq. (24).

In both the Bessel-Fourier expansion (8) and the scheme (38), the radius $R$ must be chosen sufficiently large, so that the area of radius $R$ encompasses the entire physically relevant range. However, $R$ should not be chosen too large, because the expansion scheme determines the Bessel-Fourier coefficients with respect to the entire radial range $r \in [0, R]$ without giving more weight to the high-density region at small $r$ that is physically most relevant. Also, the Bessel-Fourier expansion coefficients depend on the choice of $R$. One may wonder whether it is possible to eliminate this unwanted $R$ dependence and to give in the expansion more weight to the physically most relevant region of small and intermediate radii that contain most of the enthalpy density. One idea in this context might be to use a mapping of the complete range of radii $r \in [0, \infty]$ to a compact interval. The outer boundary condition corresponds

\begin{equation}
\langle \tilde{w}_{l_1}^{(m)} \tilde{w}_{l_2}^{(m)\ast} \rangle \equiv \langle w^{(0)}(r) \rangle,
\end{equation}

but other choices may be possible as well. By construction, as long as the coefficients $\tilde{w}_{l}^{(m)}$ of fluctuations are sufficiently small, the density (38) is positive everywhere even if truncated. Mainly for this reason, we have based a first recent study [26] of the fluid dynamic propagation of single modes on the expansion (38). Because of the interesting properties of (38), and to fully document the starting point of the dynamical study [26], we discuss this expansion now in some detail.

We first note that the Bessel-Fourier expansion (8) and the expansion (38) of the normalized enthalpy density share significant commonalities. In particular, we have checked numerically that both expansions account with comparable accuracy for a given true density distribution if truncated at the same number of modes (data not shown). This indicates that it is not problematic for a good approximation in the physical region $r < R$ that the normalized enthalpy density [in contrast to the un-normalized one; see Eq. (5)] does not vanish at the boundary $r = R$. However, as seen in Fig. 12, the two-mode correlators $(\tilde{u}_{l_1}^{(m)} \tilde{u}_{l_2}^{(m)\ast})$ of the normalized density show an oscillating structure that is rather different from that seen in Figs. 4 and 8. Technically, this oscillation arises because, for the normalized density $w(r, \phi)/w_{BG}(r)$,
then to $r = \infty$, and artificial boundary effects would disappear. A natural mapping of this kind is induced, for instance, by the background enthalpy density $w_{BG}(r)$ chosen such that it agrees with an appropriate event average, $w_{BG}(r) = \langle w(r, \phi) \rangle$. Because $w_{BG}(r)$ is positive, monotonously decreasing with $r$ and integrable in the transverse plane (the total enthalpy is finite), one can define the transformed radial coordinate such that

$$\rho(r) = \sqrt{\int_0^r dr' r' w_{BG}(r') \int_0^\infty dr'' r'' w_{BG}(r'')}.$$  
(40)

The coordinate $\rho$ is proportional to $r$ for small $r$ and it maps the interval $r \in [0, \infty]$ onto $\rho \in [0, 1]$. A reformulation of the expansion (38) in this new radial coordinate is straightforward, but we do not further explore this point in the present work.

V. VECTOR AND TENSOR FLUCTUATIONS

In this section we extend the Bessel-Fourier representation of the previous section to hydrodynamical fields that transform as vectors and tensors under rotations. We also make the dependence of these fields on spatial rapidity $\eta$ and time $\tau$ explicit, which has been omitted for notational simplicity so far. Again we design the expansion such that in a situation where the background field is independent of the coordinates in the transverse plane the evolution equations for different Bessel modes decouple. We discuss here fluctuations in fluid velocity; the extension to other vector fields is then straightforward.

In coordinates $\tau, r, \phi, \eta$ it is sensible to choose the independent components of the fluid velocity as $u^r, u^\phi$, and $u^\eta$. The

FIG. 13. (Color online) Event distributions of products of two modes $\tilde{w}_1^{(m)} \tilde{w}_2^{(m)*}$ for $b = 0$. Same as Fig. 3, but for the normalized enthalpy density $w(r, \phi)/w_{BG}(r)$.

FIG. 14. (Color online) The distribution of real and imaginary values taken by complex-valued two-mode correlators $\langle \tilde{w}_1^{(m)} \tilde{w}_2^{(m)*} \rangle$, $l_1 \neq l_2$. Same as Fig. 3, but for the normalized enthalpy density $w(r, \phi)/w_{BG}(r)$.
fourth component follows from the normalization condition as $u' = \sqrt{1 + (u^\phi)^2 + r^2(u^\theta)^2 + \tau^2(u^\eta)^2}$. For a background fluid field that satisfies rotational symmetry in the transverse plane as well as Bjorken boost invariance, the background components $u^\phi$ and $u^\eta$ vanish, but the radial background component $u'_\text{BG}$ can be nonvanishing. We denote the fluctuating part of the velocity fields with a tilde, and we rescale all field components such that they are dimensionless in units with $c = 1$. Expressed with the help of transverse Cartesian coordinates $\vec{v} = (v_x, v_y), \tilde{r} = (x, y), \tilde{z} = (-y, x)$, the fluctuating part of the velocity components takes then the form
\begin{align}
\tilde{u}' &= \tilde{s} \cdot \tilde{\nu}/|\tilde{s}| - u'_\text{BG} = u' - u'_\text{BG}, \\
\tilde{u}^\phi &= \tilde{s}_\perp \cdot \tilde{\nu}/|\tilde{s}_\perp| = r u^\phi, \\
\tilde{u}^\eta &= \tau u^\eta.
\end{align}

We now discuss how to set up the Bessel-Fourier representation of these fields. Naively, one might think that an expansion as in Eq. (9) would do for vector valued quantities as well. However, this leads to problems, as can be seen, for example, for the $m = 0$ modes. At $r = 0$ the Bessel functions are nonzero, $J_0(0) = 1$, and an expansion of $\tilde{u}'$ as in Eq. (9) would thus contain parts that do not vanish for $r \to 0$. This is unphysical because the divergence of the fluid velocity would have a $1/r$ singularity; the zeroth harmonic moment of $\tilde{u}'$ must vanish at $r = 0$. However, the first harmonic moments of $\tilde{u}'$ and $\tilde{u}^\phi$ can take finite values at $r = 0$, while the expansion (9) does not allow for that. Instead of Eq. (9), one can expand the $m$th moments of the velocity fields $\tilde{u}'$ and $\tilde{u}^\phi$ as linear combinations of the Bessel functions $J_{m-1}(k_{i(m)} r)$ and $J_{m+1}(k_{i(m)} r)$ that satisfy physical boundary conditions at $r = 0$. Here the wave numbers $k_{i(m)}$ are the same as in Eq. (8). The functions $J_{m-1}(k_{i(m)} r)$ and $J_{m+1}(k_{i(m)} r)$ form an appropriate orthogonal set of functions; see Appendix A. Closer inspection shows then that physical boundary conditions are realized for the linear combinations
\begin{align}
\tilde{u}' &= \frac{1}{\sqrt{2}} (\tilde{u}^- + \tilde{u}^+), \\
\tilde{u}^\phi &= \frac{i}{\sqrt{2}} (\tilde{u}^- - \tilde{u}^+),
\end{align}
where
\begin{align}
\tilde{u}^- (t_0, r, \phi, \eta) &= \sum_{i = 1}^\infty \sum_{m = -\infty}^\infty \int_{-\infty}^\infty \frac{d k_{i(m)}}{2\pi} \tilde{a}^-_{i(m)} (t_0, k_{i}) e^{i(m\phi + k_{i} \eta)} J_{m-1}(k_{i(m)} r), \\
\tilde{u}^+ (t_0, r, \phi, \eta) &= \sum_{i = 1}^\infty \sum_{m = -\infty}^\infty \int_{-\infty}^\infty \frac{d k_{i(m)}}{2\pi} \tilde{a}^+_{i(m)} (t_0, k_{i}) e^{i(m\phi + k_{i} \eta)} J_{m+1}(k_{i(m)} r).
\end{align}

For $\tilde{u}^\eta$ one can use the same expansion as in the scalar case,
\begin{align}
\tilde{u}^\eta (t_0, r, \phi, \eta) &= \sum_{i = 1}^\infty \sum_{m = -\infty}^\infty \int_{-\infty}^\infty \frac{d k_{i(m)}}{2\pi} \tilde{a}^\eta_{i(m)} (t_0, k_{i}) e^{i(m\phi + k_{i} \eta)} J_{m}(k_{i(m)} r).
\end{align}

Note that in Eqs. (45) and (46) we also expand the dependence on rapidity $\eta$ into an appropriate Fourier transform. In this sense Eqs. (45) and (46) provide generalizations of Eqs. (1) and (6).

To shortly illustrate properties of the Bessel-Fourier expansion of vector fields, we have generated initial conditions with nonvanishing velocity fluctuations according to a model described in Ref. [50]. This model supplements the MC Glauber initial conditions of Sec. III with a velocity field by associating a small random transverse velocity component $v$ to each of the participants and their individual enthalpy density distributions. For the examples considered here, we draw the random velocity components from a Gaussian distribution of width $|v| = 0.1c$. Figure 15 shows the fluctuations in the radial (\tilde{u}') and azimuthal (\tilde{u}^\phi) velocity components, generated in such a model for a single event. We mention as an aside that the initial velocity fluctuations of this model have divergent and rotational (a.k.a. vorticity) components of similar size [50]. It is an open question whether such initial velocity fluctuations leave characteristic signatures in relativistic heavy ion collisions, but at least some conceivable scenarios are being explored [54,55]. However, even if velocity fluctuations should turn out to be negligible at initial time $t_0$, they will be generated at $r > t_0$ in response to fluctuations in the enthalpy density. Understanding how the Bessel-Fourier expansion extends to vector and tensor fields is therefore relevant for studying how single-density modes propagate. In particular, our first exploratory study of the dynamical evolution of single modes of the enthalpy density [26] was based on a Bessel-Fourier expansion of all vector and tensor fields at times $r > t_0$.

Here we do not further discuss the physics of initial velocity fluctuation, but we limit our discussion to the properties of characterizing vector fields with the ansatz (44) and (45). It is a general feature of vector fields that in the limit $r \to 0$ their first harmonic moments can take nonvanishing values, while all other harmonic moments vanish. Figure 16 shows the harmonic moments $\tilde{u}'_{i(m)}, \tilde{u}^\phi_{i(m)}$ for the velocity fluctuations of Fig. 15 and illustrates this point.

To determine the Bessel-Fourier coefficients of the expansion (45) of vector fields, one can apply again Lemoine’s method of discrete Bessel transformation. The only difference to the scalar case is now that $a_{i(m)}$ in (12) gets replaced by $J_{m-1}(k_{i(m)} r), J_{m+1}(k_{i(m)} r)$, respectively, so that
\begin{align}
\tilde{u}^\pm_{i(m)} &= \sum_{\alpha = 1}^{N_i} M^\pm_{i(m)} \tilde{u}^\pm(m) (r_{\alpha} (m)),
\end{align}
FIG. 15. (Color online) Fluctuations in the initial radial (left) and angular (right) velocity fields \(u_r\) and \(u_\phi\) of a single event. The event was generated from MC Glauber initial conditions in which the enthalpy density attributed to each participant is associated with a small random transverse velocity component, drawn from a Gaussian distribution of width \(\langle |v| \rangle = 0.1c\).

where the matrix \(M^{\pm(m)}_{l\alpha}\) is independent of the properties of \(u^{\pm(m)}_{l\alpha}(r)\) and reads

\[
M^{\pm(m)}_{l\alpha} = \frac{4 J^{(m)}_{l\pm1} J^{(m)}_{l\alpha}}{(z^{(m)}_N)^2 j^{(m)}_{l+m+1}(\zeta^{(m)}_l) j^{(m)}_{l+m+1}(\zeta^{(m)}_r)}. \tag{48}
\]

Let us now turn to tensor-valued fields. The prime example for this is the shear stress tensor \(\pi_{\mu\nu}\). If the event-averaged background of this shear tensor has rotational symmetry in the transverse plane and Bjorken boost invariance, then it depends only on \(r\) and the only nonzero components are \(\pi_{\tau\tau}\), \(\pi_{\tau\phi}\), \(\pi_{\phi\tau}\), \(\pi_{\phi\phi}\), \(\pi_{\phi\eta}\), and \(\pi_{\eta\phi}\). We note that only two of these components are independent; the other are constrained by

\[
\pi^{\mu\nu} = \pi^{\nu\mu}, \quad \pi^{\mu}_{\mu} = 0, \quad u_{\mu}\pi^{\mu\nu} = 0. \tag{49}
\]

Here, the last constraint is nonlinear in the fluid dynamical fields. It is therefore not necessarily true for expectation values. It may still be reasonable, however, to assume that the relation (49) holds when \(u_{\mu}\) and \(\pi^{\mu\nu}\) are replaced by their background values \(u^{BG}_{\mu}\) and \(\pi^{BG}_{\mu\nu}\).

We now rescale again the components of the shear viscous tensor so that they are dimensionless, and we denote their fluctuating parts with a tilde:

\[
\tilde{\pi}_{\tau\tau} = \frac{1}{w_{BG}} (\pi^{\tau\tau} - \pi^{BG}_{\tau\tau}), \quad \tilde{\pi}_{\tau\phi} = \tilde{\pi}_{\phi\tau} = \frac{r}{w_{BG}} (\pi^{\tau\phi} - \pi^{BG}_{\tau\phi}), \\
\tilde{\pi}_{\phi\phi} = \frac{r^2}{w_{BG}} (\pi^{\phi\phi} - \pi^{BG}_{\phi\phi}), \quad \tilde{\pi}_{\phi\eta} = \tilde{\pi}_{\eta\phi} = \frac{r}{w_{BG}} (\pi^{\phi\eta} - \pi^{BG}_{\phi\eta}). \tag{50}
\]

The components involving the temporal direction \(\tau\) can be inferred from these using \(u_{\mu}\pi^{\mu\nu} = 0\). We note also that one of the components in Eq. (50) can be expressed in terms of the others owing to the traceless constraint \(\pi^{\mu}_{\mu} = 0\).

For the Bessel-Fourier expansion it is furthermore useful to make the following change of variables:

\[
\tilde{\pi}^{\tau\eta} = \frac{1}{\sqrt{2}} (\tilde{\pi}^{\eta\tau} + \tilde{\pi}^{+\eta}), \\
\tilde{\pi}^{\phi\eta} = \frac{i}{\sqrt{2}} (\tilde{\pi}^{\eta\phi} - \tilde{\pi}^{+\eta}), \\
\tilde{\pi}^{\phi\phi} = \frac{1}{\sqrt{2}} (\tilde{\pi}^{-\phi} + \tilde{\pi}^{+\phi}), \\
\tilde{\pi}^{\phi\eta} + \frac{1}{2} \tilde{\pi}^{\eta\phi} = \frac{i}{\sqrt{2}} (\tilde{\pi}^{-\phi} - \tilde{\pi}^{+\phi}). \tag{51}
\]
As a fifth independent component we take $\tilde{\mathcal{F}}^{\eta\eta}$. One can then use the expansion scheme

\[\tilde{\mathcal{F}}^{\eta\eta}(\tau_0, r, \phi, \eta) = \sum_{l=1}^{\infty} \sum_{m=-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{dk_{\eta}}{2\pi} \tilde{\mathcal{F}}^{\eta\eta(m)}(\tau_0, k_{\eta}) e^{i(m\phi + k_\eta \eta)} J_m(k_{\eta} r),\]

\[\tilde{\mathcal{F}}^{-\eta}(\tau_0, r, \phi, \eta) = \sum_{l=1}^{\infty} \sum_{m=-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{dk_{\eta}}{2\pi} \tilde{\mathcal{F}}^{-\eta(m)}(\tau_0, k_{\eta}) e^{i(m\phi + k_\eta \eta)} J_{m-1}(k_{\eta} r),\]

\[\tilde{\mathcal{F}}^{+\eta}(\tau_0, r, \phi, \eta) = \sum_{l=1}^{\infty} \sum_{m=-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{dk_{\eta}}{2\pi} \tilde{\mathcal{F}}^{+\eta(m)}(\tau_0, k_{\eta}) e^{i(m\phi + k_\eta \eta)} J_{m+1}(k_{\eta} r),\]

\[\tilde{\mathcal{F}}^{-+}(\tau_0, r, \phi, \eta) = \sum_{l=1}^{\infty} \sum_{m=-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{dk_{\eta}}{2\pi} \tilde{\mathcal{F}}^{-+}(\tau_0, k_{\eta}, \eta) e^{i(m\phi + k_\eta \eta)} J_{m-2}(k_{\eta} r),\]

\[\tilde{\mathcal{F}}^{++}(\tau_0, r, \phi, \eta) = \sum_{l=1}^{\infty} \sum_{m=-\infty}^{\infty} \int_{-\infty}^{\infty} \frac{dk_{\eta}}{2\pi} \tilde{\mathcal{F}}^{++}(\tau_0, k_{\eta}, \eta) e^{i(m\phi + k_\eta \eta)} J_{m+2}(k_{\eta} r).\]

The inverse relations for $\tilde{\mathcal{F}}^{\eta\eta}$, $\tilde{\mathcal{F}}^{-\eta}$, and $\tilde{\mathcal{F}}^{+\eta}$ are analogous to the vector case (48). For the components $\tilde{\mathcal{F}}^{-\eta}$ and $\tilde{\mathcal{F}}^{++}$ one has additional boundary terms,

\[\tilde{\mathcal{F}}^{-\eta}(\tau_0, l, m, k_{\eta}) = \frac{1}{2\pi} \frac{2}{R^2 J_{m+1}(\zeta_{l})(\zeta_{l})} \int_{0}^{R} r dr \int_{0}^{2\pi} d\phi \int_{-\infty}^{\infty} d\eta \tilde{\mathcal{F}}^{-\eta}(\tau_0, r, \phi, \eta) e^{-i(m\phi + k_\eta \eta)} J_{m-2}(k_{\eta} r),\]

\[\tilde{\mathcal{F}}^{++}(\tau_0, l, m, k_{\eta}) = \frac{1}{2\pi} \frac{2}{R^2 J_{m+1}(\zeta_{l})(\zeta_{l})} \int_{0}^{R} r dr \int_{0}^{2\pi} d\phi \int_{-\infty}^{\infty} d\eta \tilde{\mathcal{F}}^{++}(\tau_0, r, \phi, \eta) e^{-i(m\phi + k_\eta \eta)} J_{m+2}(k_{\eta} r).\]

The reason is the modified orthogonality relation for the functions $J_{m-2}$ and $J_{m+2}$ in Eq. (A4). Again, these relations can be inverted with Lemoine’s method. We emphasize that the expressions given in this section are of practical use. In particular, the calculation of the fluid dynamical propagation of single fluctuating modes presented in Ref. [26] involves a Bessel-Fourier decomposition of all scalar, vector, and tensor fluid dynamic fields at each time step of the simulation.

**VI. SUMMARY AND OUTLOOK**

In summary, we have shown in the present work that a Bessel-Fourier expansion provides a convenient orthonormal basis for the characterization of fluctuating initial conditions in all fluid dynamic fields. The form of the Bessel-Fourier expansion explored in Sec. III was proposed for scalar fields already in Ref. [24], where, in particular, results closely related to Figs. 1 and 2 of the present work were presented. Here we have extended these studies to the characterization of vector and tensor fields, we have extended it to the characterization of correlations between fluctuating modes, and we have explained how the weights of these modes can be determined in practice in a CPU-inexpensive way based on Lemoine’s method. Moreover, in Sec. IV, we have introduced a variant of the Bessel-Fourier expansion for normalized densities that remains by construction positive definite if truncated after a finite number of modes. As we have argued here on general grounds, and as we have demonstrated in a first fluid dynamical study of fluctuations recently [26], this property allows one to propagate single modes fluid dynamically. The Bessel-Fourier expansion, in the form given in Sec. IV is therefore a suitable starting point for the program of mode-by-mode hydrodynamics that we plan to pursue in future work.

We have also shown that the orthonormal Bessel-Fourier expansion provides for a simple and efficient characterization of the functional event-by-event probability distribution $\mathcal{P}$. To illustrate this point, we have characterized $\mathcal{P}$ in Secs. III and IV for the MC Glauber model of fluctuating initial conditions. We have shown for this model in particular that event distributions of single modes and distributions of products of two modes are described by a Gaussian ansatz for $\mathcal{P}$ with high accuracy. This is important because it allows for the discussion of event distributions in terms of simple analytic expressions that depend on a finite number of event-averaged quantities only.

For a general classification of the initial conditions of ultra-relativistic nucleus-nucleus collisions, it would be interesting to understand in the future to what extent the event probability distributions $\mathcal{P}$ that characterize other models of fluctuating initial conditions are also well approximated by a Gaussian ansatz. We note in this context that the framework presented...
in Secs. III and IV need not be limited to the analysis of event-distributions of single modes and of products of two modes. In close analogy to our discussion of Eqs. (30) and (31), one can also compare for event distributions of three or more modes the true model distributions to the results of a Gaussian ansatz. One can test, of course, whether higher-mode correlators of the form (22) factorize into products of two-point correlators, as expected for a Gaussian distribution. This would establish to what extent non-Gaussianities arise in different models of fluctuating initial conditions, and it could thus contribute to a general classification of these initial conditions.

ACKNOWLEDGMENTS

We thank U. Heinz, M. Luzum, J. Y. Ollitrault, and H. Petersen for useful discussions at various stages of this work.

APPENDIX A: BESSSEL FUNCTIONS AND BESSSEL TRANSFORMATION

In this Appendix we gather some properties of Bessel functions that we found useful in manipulating the representation of fluctuating initial conditions proposed in the main text.

Denoting by \( z_{l}^{(m)} \) the \( l \)th zero of the Bessel function of the first kind \( J_{m}(z) \), one can write the standard orthogonality property as

\[
\int_{0}^{R} dr \ r \ J_{m}\left(\frac{z_{l}^{(m)}}{R}\right) J_{m}\left(\frac{z_{l}^{(m)}}{R}\right) = \frac{R^{2}}{2} \left[ J_{m+1}\left(z_{l}^{(m)}\right)\right]^{2} \delta_{ll}'.
\]  

(A1)

In essence this relation states that for given \( m \) one can use the functions \( f_{l} = J_{m}\left(\frac{z_{l}^{(m)}}{R}\right) \), with \( l = 1, \ldots, \infty \) as an orthogonal set of functions on the interval \( 0, \ldots, R \) when the integration measure is \( r \, dr \).

Particularly useful are also the following expressions for derivatives and for multiplying with \( m/R \):

\[
J'\left(\frac{z_{l}^{(m)}}{R}\right) = \frac{1}{2} \left[ J_{m-1}\left(\frac{z_{l}^{(m)}}{R}\right) - J_{m+1}\left(\frac{z_{l}^{(m)}}{R}\right) \right],
\]

\[
mR J\left(\frac{z_{l}^{(m)}}{R}\right) = \frac{1}{2} \left[ J_{m-1}\left(\frac{z_{l}^{(m)}}{R}\right) + J_{m+1}\left(\frac{z_{l}^{(m)}}{R}\right) \right].
\]

(A2)

From the Bessel differential equation one can also derive the following relations:

\[
\int_{0}^{R} dr \ r \ J_{m-1}\left(\frac{z_{l}^{(m)}}{R}\right) J_{m-1}\left(\frac{z_{l}^{(m)}}{R}\right) = \frac{R^{2}}{2} \left[ J_{m+1}\left(z_{l}^{(m)}\right)\right]^{2} \delta_{ll}'.
\]

\[
\int_{0}^{R} dr \ r \ J_{m+1}\left(\frac{z_{l}^{(m)}}{R}\right) J_{m+1}\left(\frac{z_{l}^{(m)}}{R}\right) = \frac{R^{2}}{2} \left[ J_{m+1}\left(z_{l}^{(m)}\right)\right]^{2} \delta_{ll}'.
\]

(A3)

Note that \( z_{l}^{(m)} \) is here still the \( l \)th zero of \( J_{m}(z) \). The significance of Eq. (A3) is that, in addition to \( J_{m}\left(\frac{z_{l}^{(m)}}{R}\right) \), also the set of functions \( J_{m-1}\left(\frac{z_{l}^{(m)}}{R}\right) \) or \( J_{m+1}\left(\frac{z_{l}^{(m)}}{R}\right) \) for \( l = 1, \ldots, \infty \) constitute orthogonal sets of functions on the interval \( 0, \ldots, R \). This feature is important for the Bessel expansion of vector valued functions such as the fluctuations in the fluid velocity.

Finally, we note a related property for the sets of functions \( J_{m-2}\left(\frac{z_{l}^{(m)}}{R}\right) \) and \( J_{m+2}\left(\frac{z_{l}^{(m)}}{R}\right) \). The orthogonality relations are now slightly more complicated,

\[
\int_{0}^{R} dr \ r \ J_{m-2}\left(\frac{z_{l}^{(m)}}{R}\right) J_{m-2}\left(\frac{z_{l}^{(m)}}{R}\right) = \frac{R^{2}}{2} \left[ J_{m+1}\left(z_{l}^{(m)}\right)\right]^{2} \delta_{ll}'.
\]

\[
\int_{0}^{R} dr \ r \ J_{m+2}\left(\frac{z_{l}^{(m)}}{R}\right) J_{m+2}\left(\frac{z_{l}^{(m)}}{R}\right) = \frac{R^{2}}{2} \left[ J_{m+1}\left(z_{l}^{(m)}\right)\right]^{2} \delta_{ll}'.
\]

(A4)

These relations can still be used for an expansion of tensor valued fluctuations in terms of the set of functions \( J_{m-2}\left(\frac{z_{l}^{(m)}}{R}\right) \) or \( J_{m+2}\left(\frac{z_{l}^{(m)}}{R}\right) \), \( l = 1, \ldots, \infty \) although some expressions contain additional boundary terms, as discussed in Sec. V.

APPENDIX B: DISCRETE BESSSEL TRANSFORMATION

In this Appendix we discuss an efficient numerical scheme owing to Lemoine [52] to do Bessel transformations by converting integrals into finite numerical sums. In this scheme \( r \)-dependent functions \( h \) are represented in position space by their value on \( N \) discretization points,

\[
h\left(\frac{z_{\alpha}^{(m)}}{R}\right), \quad \alpha = 1, \ldots, N, \quad (B1)
\]

where

\[
h\left(\frac{z_{\alpha}^{(m)}}{R}\right) = \frac{z_{\alpha}^{(m)}}{z_{N}^{(m)}} R. \quad (B2)
\]

and \( z_{\alpha}^{(m)} \) is the \( \alpha \)th zero crossing of the Bessel function \( J_{m}(z) \). Note that \( r_{N}^{(m)} = R \) is on the boundary where one assumes \( h(R) = 0 \).

Consider now the Bessel function expansion

\[
h(r) = \sum_{l=1}^{\infty} h_{l} J_{m}\left(\frac{k_{l}^{(m)}}{R}\right). \quad (B3)
\]

with

\[
k_{l}^{(m)} = \frac{z_{l}^{(m)}}{R}. \quad (B4)
\]

We truncate this expansion at \( l = N \) or for \( k_{l}^{(m)} = k_{N}^{(m)} = z_{N}^{(m)}/R \). Restricting also to the points \( r_{\alpha}^{(m)} \),

\[
h\left(\frac{z_{\alpha}^{(m)}}{R}\right) \approx \sum_{l=1}^{N} h_{l} J_{m}\left(\frac{k_{l}^{(m)}}{r_{\alpha}^{(m)}}\right). \quad (B5)
\]
thereby possibly cutting off the very fine structures of the function \( h(r) \). The virtue of the spatial discretization [Eqs. (B1) and (B2)] is now that one can efficiently approximate the inverse relation

\[
\hat{h}_l = \frac{2}{R^2 \left[ J_{m+1}(k_l^{(m)} R) \right]^2} \int_0^R dr \ r \ h(r) \ J_m(k_l^{(m)} r) \quad (B6)
\]

by a finite sum

\[
\hat{h}_l \approx \sum_{\alpha=1}^N \left[ \frac{4}{\left[ J_{m+1}(\zeta_l^{(m)} \alpha) \right]^2} \right] \times h(r_\alpha^{(m)}) J_m(k_l^{(m)} r_\alpha^{(m)}). \quad (B7)
\]

Note that the last term with \( \alpha = N \) vanishes so that the sum goes effectively over the range \( \alpha = 1, \ldots, N - 1 \). Note that Eqs. (B5) and (B7) constitute matrix relations between the two representations of the function \( h \) in position space (B1) and in Bessel space represented by \( h_1, l = 1, \ldots, N \).

We emphasize at this point that even in a situation where \( h_1 = 0 \) for \( l > N \) so that Eq. (B5) is exact, this is not necessarily the case for a discrete version of the inverse relation (B7). This is in contrast to other relations of similar kind such as the discrete Fourier transforms. Equation (B6) is exact and Eq. (B7) is getting better and better as \( N \to \infty \).

**APPENDIX C: PROBABILITY DISTRIBUTION OF ENTHALPY DENSITIES**

In this Appendix we discuss some general properties of the event-by-event probability distribution of enthalpy density in the transverse plane at time \( \tau_0 \) where hydrodynamics is initialized. For notational simplicity we neglect the dependence on the longitudinal rapidity coordinate.

Because the initial transverse enthalpy density \( w(r, \phi) \) is a function of radius \( r \) and azimuthal angle \( \phi \), the probability distribution that describes an ensemble of events is a functional,

\[
\mathcal{P}[w]. \quad (C1)
\]

It can be characterized in different ways, for example by the expectation value

\[
\langle w(r, \phi) \rangle \quad (C2)
\]

and the set of \( n \)-point correlation functions,

\[
\langle w(r_1, \phi_1) \cdots w(r_n, \phi_n) \rangle. \quad (C3)
\]

Note that the enthalpy density is real and positive definite, which therefore has to be the case for the expectation values and correlation functions as well.

If the event ensemble in question consists of events with arbitrary orientation in the transverse plane, azimuthal rotation invariance \( \phi \to \phi + \Delta \phi \) and invariance under reflections \( \phi \to -\phi \) are realized as statistical symmetries. This means that the transverse enthalpy distribution of a single event is not invariant under these transformations but appropriate event averages are. In particular, the expectation value in Eq. (C2) is then independent of \( \phi \) and the correlation functions in Eq. (C3) depend only on differences between the azimuthal angles. The statistical symmetry must also be realized for the probability distribution (C1).

Let us now discuss the particularly simple and important case of a functional probability distribution of Gaussian form \((N)\) is an appropriate normalization factor,

\[
\mathcal{P}[w] = \mathcal{N} \exp \left[ -\frac{1}{2} \int dr_1 dr_2 d\phi_1 d\phi_2 r_1 r_2 \times (w(r_1, \phi_1) - \langle w(r_1, \phi_1) \rangle) M(r_1, r_2, \phi_1, \phi_2) \times (w(r_2, \phi_2) - \langle w(r_2, \phi_2) \rangle) \right]. \quad (C4)
\]

The statistical azimuthal rotation and reflection symmetry would imply that \( M \in \mathbb{R} \) depends on \( \phi_1 \) and \( \phi_2 \) only via the difference \( |\phi_1 - \phi_2| \). We expand now \( w(r, \phi) \) in terms of the Bessel-Fourier decomposition proposed in Sec. II,

\[
w(r, \phi) = \sum_{m=-N}^N \sum_{l=1}^N w_l^{(m)} e^{im\phi} J_m(k_l^{(m)} r). \quad (C5)
\]

The coefficients \( w_l^{(m)} \) are complex but fulfill \( w_l^{(m)} = w_l^{(-m)} \) because \( w(r, \phi) \in \mathbb{R} \). The Gaussian distribution (C4) becomes in this basis

\[
\mathcal{P}[w] = \mathcal{N} \exp \left[ -\frac{1}{2} \sum_{m_1, m_2 = -N}^N \sum_{l_1, l_2 = 1}^N \sum_{m_1, m_2 = -N}^N \sum_{l_1, l_2 = 1}^N \right.
\]

\[
\times (w_{l_1}^{(m_1)} - \langle w_{l_1}^{(m_1)} \rangle)^2 \left[ T_{l_1 l_2}^{(m_1, m_2)} (w_{l_2}^{(m_2)} - \langle w_{l_2}^{(m_2)} \rangle) \right], \quad (C6)
\]

with

\[
T_{l_1 l_2}^{(m_1, m_2)} = \int dr_1 dr_2 d\phi_1 d\phi_2 r_1 r_2 e^{-i m_2 \phi_2} \times J_{m_1}(k_{l_1}^{(m_1)} r_1) J_{m_2}(k_{l_2}^{(m_2)} r_2) M(r_1, r_2, \phi_1, \phi_2). \quad (C7)
\]

The matrix \( T_{l_1 l_2}^{(m_1, m_2)} \) is Hermitian because \( \mathcal{P} \) is real. It also fulfills

\[
T_{l_1 l_2}^{(m_1, m_2)*} = T_{l_1 l_2}^{(m_1, -m_2)}. \quad (C8)
\]

For statistical rotation symmetry it is diagonal with respect to the indices \( m_1 \) and \( m_2 \),

\[
T_{l_1 l_2}^{(m_1, m_2)} = \delta_{m_1, m_2} T_{l_1 l_2}^{(m_1, m_2)}. \quad (C9)
\]

Statistical azimuthal reflection symmetry implies

\[
T_{l_1 l_2}^{(m_1, m_2)} = T_{l_1 l_2}^{(-m_1, -m_2)} \in \mathbb{R}. \quad (C10)
\]

We finally note that general properties of Gaussian distributions imply

\[
(T^{-1})_{l_1 l_2}^{(m_1, m_2)} = (w_{l_1}^{(m_1)} w_{l_2}^{(m_2)*}) - \langle w_{l_1}^{(m_1)} \rangle \langle w_{l_2}^{(m_2)*} \rangle. \quad (C11)
\]

The functional probability distribution (C6) is therefore completely determined by the expectation values and two-mode correlators.

PHYSICAL REVIEW C 88, 044906 (2013)
