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Pierre Martin-Dussaud  
Institute for Gravitation and the Cosmos  
https://orcid.org/0000-0002-9213-8036

Andrea Di Biagio  
La Sapienza University of Rome  
https://orcid.org/0000-0001-9646-8457

Marios Christodoulou  
University of Hong Kong

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An experiment to test the discreteness of time

Marios Christodoulou*
Department of Computer Science, The University of Hong Kong, Pokfulam Road, Hong Kong and
Clarendon Laboratory, Department of Physics, University of Oxford, Oxford, United Kingdom

Andrea Di Biagio†
Dipartimento di Fisica, La Sapienza Universita di Roma, Piazzale Aldo Moro 5, Roma, Italy and
Aix-Marseille Univ, Université de Toulon, CNRS, CPT, Marseille, France

Pierre Martin-Dussaud‡
Aix-Marseille Univ, Université de Toulon, CNRS, CPT, Marseille, France and
Basic Research Community for Physics e.V., Mariannenstraße 89, Leipzig, Germany

Time at the Planck scale ($\sim 10^{-44}$s) is an unexplored physical regime. It is widely believed that probing Planck time will remain for long an impossible task. Yet, we propose an experiment to test the discreteness of time at the Planck scale and show that it is not far removed from current technological capabilities.

I. INTRODUCTION

Optical clocks using strontium $^{87}$Sr are among the most accurate in the world. The time elapsed between two of their ticks is about $10^{-15}$s (the inverse of strontium frequency) with a precision of $10^{-19}$[1]. Physical phenomena that probe much smaller characteristic timescales have also been measured. For instance, the lifetime of the top quark is $10^{-25}$s. Such a result is obtained experimentally from a statistical analysis, where the short duration of the lifetime is compensated by a large number of events. At the theoretical level, physicists consider even shorter scales: in primordial cosmology, the inflation epoch is believed to have lasted $10^{-32}$s. Based on a cosmological model, the recent paper [2] argues that the precision of contemporary atomic clocks already sets an upper bound of $10^{-33}$s for a fundamental period of time.

Planck time is a far smaller timescale. We recall that the Planck time is defined as

$$t_P = \sqrt{\frac{\hbar G}{c^3}} \approx 10^{-44} \text{ s},$$

where $G$ is Newton’s constant, $\hbar$ the reduced Planck’s constant and $c$ the speed of light. It can seem an impossible task to probe time at the Planck scale. However, the example of the lifetime of the top quark shows that it is possible to overtake clock accuracy limitations by several orders of magnitude using statistics. Here, we examine the following question: if time behaves differently than a continuous variable at the planckian scale, how could the departure from this behaviour be inferred experimentally? To answer this question, we assume that proper time differences take discrete values in multiple steps of Planck time, and devise a low energy experiment that would detect this effect.

This work is motivated by recent experimental proposals to detect the non-classicality of the gravitational field by detecting gravity mediated entanglement (GME) [3–7] and the production of non-gaussianity [8]. Since the quantum gravity regime of particle physics may be practically impossible to probe, it is intriguing that these low energy experiments are not too far removed from current capabilities. Instead of accelerators, the suggestion in these proposals is to quantum control slow moving nanodiamonds or use a Bose-Einstein condensate.

To understand how this is possible we remark that the Planck mass is a mesoscopic quantity

$$m_P \stackrel{\text{def}}{=} \sqrt{\frac{\hbar c}{G}} \approx 2 \times 10^{-8} \text{ kg},$$

For both of the above experiments, the formula that measures the quantum gravity effect can be cast in the form [8–10]

$$Q = \frac{m}{m_P t_P} \frac{\delta \tau}{t_P},$$

with $m_P$ the Planck mass, $t_P$ the Planck time, $m$ the mass probing the gravitational field, and $\delta \tau$ a time dilation. In the case of GME, $Q$ is a quantum mechanical phase. In the case of non-gaussianity growth, it is the signal-to-noise ratio. The effects become most pronounced when $Q$ approaches order unit. We thus see an interesting interplay between the Planck mass and the Planck time: if $Q \sim 1$ and $m \sim m_P$, then $\delta \tau \sim t_P$. In the GME experiment [3], the mass is $m \sim 10^{-6} m_P$, so that it already probes a proper time difference of $\delta \tau \sim 10^6 t_P$, as was first noticed in [10]. Thus, quantum gravity phenomenology provides a further motivation to the current push to develop technologies for setting mesoscopic masses in path superposition [11–13].
The aforementioned proposals aim at demonstrating qualitative results: to witness the production of entanglement, or of non-gaussianity, i.e. $Q \neq 0$, in order to check whether the gravitational field obeys quantum mechanics. Here, we propose a quantitative method for experimentally measuring a set of values for $Q$, in order to test a hypothetical discreteness of time. We see that this requires a careful consideration of the uncertainty on $Q$. $Q$ is estimated through a probability $p_+$ of an event occurring, the uncertainty on which must satisfy

$$\Delta p_+ < \frac{m}{m_p}. \tag{4}$$

We see again that the Planck mass acts as a natural scale for the effect to become prominent: smaller masses would require higher precision in estimating the probability $p_+$. The global analysis of the experimental constraints performed in this work shows that the detection of a fundamental time discreteness may be not be too far removed from current technological capabilities.

II. RESULTS

A. Experimental setup

![Figure 1. Spacetime view of the experiment.](image)

For a time $t_{acc}$, an inhomogeneous magnetic field is applied that sets a mass $m$ with embedded spin in a superposition of two paths, at a distance $d$ and $d+l$, respectively, from another mass $M$. The masses are in free fall for a time $t$, as measured in the laboratory, after which the procedure is reversed and the superposition undone. During this time $t$, the two branches accumulate a different phase due to the gravitational interaction with $M$.

The proposed experimental setup is depicted in figure 1. A spherical nanodiamond of mass $m$ with embedded magnetic spin is dropped simultaneously with a second mass $M$. The mass $m$ is then put into a spin-dependent superposition of paths by the application of a series of electromagnetic pulses, as was proposed in [3, 14]. In the branch of closest approach, $m$ and $M$ are at a distance $d$, in the other, they are at a distance $d+l$. The superposition is held at these distances for a time $t$ as measured in the laboratory frame. While the two masses free fall, they interact gravitationally. If linearised quantum gravity holds, then the two quantum branches in the total state evolve differently, accumulating a relative phase. After the superposition has been undone, this phase is visible in the state of the spin of the mass $m$.

Let us see this in detail. The quantum state of the mass $m$ is given by its position in the apparatus and the orientation of its embedded spin. There will be three relevant position states $|L⟩$, $|C⟩$ and $|R⟩$, respectively left, centre and right. For the spin, we use the canonical basis, $|↑⟩$ and $|↓⟩$, in the $z$-direction. The mass $m$ is prepared at time $t_0$ in the central position with the spin in the positive $x$-direction:

$$|ψ_0⟩ = \frac{1}{\sqrt{2}} (|C⟩ (|↑⟩ + |↓⟩)) \cdot \tag{5}$$

An inhomogeneous magnetic field is then applied to the mass $m$, entangling its position with its spin so that at time $t_1$ the state is

$$|ψ_1⟩ = \frac{1}{\sqrt{2}} (|L⟩ ↑⟩ + |R⟩ ↓⟩). \tag{6}$$

The particle is then allowed to free-fall for a time $t$. During this time, it interacts gravitationally with the mass $M$. The displacement of the masses due to their gravitational attraction is negligible. The two states $|L⟩$ and $|R⟩$ are eigenstates of the hamiltonian and each acquires a phase proportional to the newtonian potential induced by $M$. So at time $t_2$ the state is

$$|ψ_2⟩ = \frac{1}{\sqrt{2}} (e^{iφ_L}|L⟩ ↑⟩ + e^{iφ_R}|R⟩ ↓⟩), \tag{7}$$

where

$$φ_L = \frac{G M m}{\hbar} \frac{t}{d + l} \quad \text{and} \quad φ_R = \frac{G M m}{\hbar} \frac{t}{d}. \tag{8}$$

At this point, another inhomogeneous magnetic field is applied to undo the superposition. The final state of the particle, up to a global phase, is

$$|ψ_3⟩ = \frac{1}{\sqrt{2}} (|C⟩ (|↑⟩ + e^{iδφ} |↓⟩)), \tag{9}$$

where the relative phase $δφ$ is given by

$$δφ = \frac{G M m t}{\hbar} \frac{l}{d(d+l)}. \tag{10}$$

1 It has recently been shown [15] that treating the position states as eigenstates is a valid approximation in this setup.
Information about the gravitational field is now contained in the state of the spin, which in turn can be estimated from the statistics of spin measurements.

Concretely, we consider a measurement on the spin of the particle along the y-direction
\[
|\pm\rangle = \frac{1}{\sqrt{2}} (|\uparrow\rangle \pm |\downarrow\rangle).
\]

Born’s rule gives the probability \( P_+ \) of finding the spin in the state \(|+\rangle\)
\[
P_+(m, M, d, l, t) = \frac{1}{2} + \frac{1}{2} \sin \delta \phi,
\]
where we compute \( \delta \phi \) as a function of \( m, M, d, l \) and \( t \) through equation (10). This equation for the probability is a theoretical prediction of linearised quantum gravity.

Experimentally, it can be measured by the relative frequencies in collected statistics. Keeping the experimental parameters fixed, the experiment is repeated \( N \) times, of which the outcome \(|+\rangle\) is recorded \( N_+ \) times. The frequency
\[
p_+(m, M, d, l, t) \overset{\text{def}}{=} \frac{N_+}{N},
\]
is then the experimentally measured value of the probability. This procedure can be repeated for different sets of experimental parameters to verify the functional dependence of \( p_+ \) to these. In what follows, we propose an experiment that can detect a statistically significant discrepancy between \( P_+ \) and \( p_+ \). This would signal a departure from linearised quantum gravity.

The above experimental setup is similar to that proposed to detect GME in [3], with the main difference that for our purpose we only require one mass, not two, in an interference experiment [16, 17]. However, the task we have set ourselves here and the method to achieve it, goes much beyond showing that gravity can affect a quantum mechanical phase and induce an interference pattern. To detect a potential discreteness of time, we need a more sensitive apparatus, and so the gravitational source \( M \) will need to be much weaker. In our case, \( M \) is not the Earth, but a mesoscopic particle, essentially a spec of dust.

**B. Hypothesis: Time Discreteness**

While the newtonian limit of linearised quantum gravity is sufficient to compute the phase difference \( \delta \phi \), it is also understood in general relativistic terms [9, 10]. The mass \( M \) induces a Schwarzschild metric which dilates time differently along each of the two possible trajectories of \( m \). Then, equation (10) can be recast as
\[
\delta \phi = \frac{m \delta \tau}{m_P t_P},
\]
where \( \delta \tau \) is the difference of proper time between the two trajectories, given by
\[
\delta \tau = \frac{GM}{c^2} \frac{l}{d(d + l)} t.
\]

Now, it is widely believed that the smooth geometry of general relativity should be replaced, once quantised, by some discrete structure. In particular, we may expect time to be granular in some sense. In which sense precisely we do not know. However, since \( \delta \tau \) admits a straightforward interpretation of a covariant quantum clock, it makes a good candidate to reveal discrete features of time. Thus we make the following hypothesis:

\[
\delta \tau \text{ can only take values which are integer multiples of Planck time } t_P.
\]
That is, (15) is modified to:
\[
\delta \tau = n t_P, \quad n \in \mathbb{N}.
\]

Additional motivation for the hypothesis and possible alternatives are discussed in section III D. For now, it can be taken just as the simplest implementation of the idea that time is discrete at a fundamental level, similar in philosophy to the idea that everyday-life matter is not continuous, but instead made of atoms. Devising an experiment to detect this discreteness and examining its feasibility is the task we have set ourselves in this work.

Equation (16) is still incomplete as we need to posit a functional relation between the level \( n \) and the parameters \( M, d, l, t \). We rewrite equation (15) as
\[
\delta \tau = \frac{t}{\beta} t_P,
\]
where
\[
\beta \overset{\text{def}}{=} \frac{d(d + l)c^2}{GM} t_P,
\]
and we take \( n \) to be given by the floor function
\[
n = \left\lfloor \frac{t}{\beta} \right\rfloor.
\]
That is, \( n \) is the integer part of the dimensionless quantity \( t/\beta \). The main lessons of our results do not depend on the specific choice (19) for the functional dependence between \( t/\beta \) and \( n \). Other modifications of the continuous behaviour in (15), so long as they display features of planckian size, could be probed by the experiment.

We have
\[
\delta \tau = \left\lfloor \frac{t}{\beta} \right\rfloor t_P.
\]

The consequences of this hypothesis are revealed in the measured probability \( p_+ \) of equation (13). If time behaves continuously, \( p_+ \), as a function of time \( t/\beta \), will fit the smooth (blue) curve of figure 2, given by
\[
P_+ = \frac{1}{2} + \frac{1}{2} \sin \left( \frac{m \cdot t}{m_P \beta} \right).
\]
If the hypothesis holds, the observed profile for the probability will follow that of the red step function in figure 2, given by

$$P_+^h = \frac{1}{2} + \frac{1}{2} \sin \left( \frac{m}{m_P} \frac{t}{\beta} \right). \quad (22)$$

To test the hypothesis, the strategy is thus to plot experimentally the curve $p_+(t/\beta)$. Observing plateaux would be the signature of time-discreteness.

![Figure 2](image.png)

**Figure 2. Probability of measuring spin $|+i\rangle$ as a function of $t/\beta$ under the continuous and discrete time hypotheses.** Blue line: $\delta T$ is smooth as in equation (17). Red line: $\delta T$ is discrete as in equation (20). We have taken the value of $m = 10^{-9}m_P$. The experimental parameters shown in table I would produce 100 data points scanning the range of $t/\beta$ depicted here, with a sufficient resolution to decide which of the two curves is realised in nature.

### C. Discussion

The feasibility analysis of the experiment is carried out in section III. First, we determine a set of constraints that would ensure the visibility of the plateaux in the plot of the probability $p_+(t/\beta)$ (subsection IIIA). These constraints are expressed as a set of inequalities on the experimental parameters. Second, based on current claims in the experimental physics literature, we show that there exists a reasonable range of parameters that satisfy the constraints (subsection IIIB). The obtained values are gathered in table I. In subsection IIIC, we finally determine the temperature and pressure conditions required to avoid too fast decoherence.

We surprisingly conclude that the proposed experiment is a feasible task for the foreseeable future. In particular, it is of comparable difficulty to contemporary experimental proposals for testing the non-classicality of the gravitational field. Nevertheless it remains difficult, and will require pooling expertise in adjacent experimental fields.

| Parameter | Value | Uncertainty |
|-----------|-------|-------------|
| $m$       | $3 \times 10^{-10}$ kg | $10^{-12}$ kg |
| $M$       | $3 \times 10^{-9}$ kg | $10^{-11}$ kg |
| $t$       | $10^{-1}$ s | $10^{-4}$ s |
| $l$       | $10^{-7}$ m | $10^{-9}$ m |
| $d$       | [17, 54] cm | $10^{-2}$ cm |

Table I. The experimental parameters identified in this work.

The possibility of probing Planckian time without involving extremely high energies may be a disturbing idea to many physicists. However, the history of physics shows examples where scientists have gained knowledge at a physical scale that was widely believed to be unreachable with the available technology at the time. The first example is when Einstein proposes a way to measure the size of atoms by observing the brownian motion of mesoscopic pollen grains [18]. Another example is when Millikan shows that the electric charge comes in discrete packets, and measures the charge of the smallest packet (the electron) [19, 20]. Again, such a feat was realised through the observation of the mesoscopic motion of charged drops of oil. In both cases, as in our proposal, the scale of discreteness was reached through mesoscopic observables thanks to two leverage effects: an algebraic game involving very small or very big constants and a statistical game involving the collection of many events.

The importance of realising the proposed experiment lies primarily in the groundbreaking implications of potentially discovering a granularity of time at the Planck scale. A negative result would also have significant implications, guiding fundamental theory. Finally, an easier version of the experiment with relaxed constraints would remain of profound interest, setting new bounds on the continuous behaviour of time.

### III. METHODS

#### A. Ensuring Visibility of the Effect

Each experimental data point for $p_+(t/\beta)$ is obtained from computing the statistical frequency of the outcome $|+i\rangle$. Point by point, a scatter plot of $p_+$ against $t/\beta$ will be obtained. We must choose the experimental parameters so that the difference between $P_+$ and $P_+^h$ can be resolved. This imposes requirements on the minimal precision of the experimental apparatus and on the maximal permissible gravitational noise in the environment.
The uncertainty $\Delta p_+$ for the probability $p_+$ after $N$ runs is a result of using finite statistics and is of the order

$$\Delta p_+ \sim \frac{1}{\sqrt{N}}.$$  

(23)

The vertical step $\alpha$ between the plateaux is given by

$$\alpha = \sin \left( \left( \frac{t}{\beta} \right) + 1 \right) \frac{m}{m_p} - \sin \left( \left( \frac{t}{\beta} \right) \frac{m}{m_p} \right).$$  

(24)

We assume that $m \ll m_p$, consistent with the fact that it is hard to put a large mass in a superposition. The above expression simplifies to

$$\alpha(t) \approx \frac{m}{m_p} \cos \left( \frac{t}{\beta} \frac{m}{m_p} \right).$$  

(25)

So, the steps are most visible when

$$\left| \frac{t}{\beta} \frac{m}{m_p} \right| \ll 1.$$  

(26)

Then the expression simplifies to

$$\alpha(t) \approx \frac{m}{m_p}.$$  

(27)

Requiring that the probability uncertainty is an order of magnitude smaller than the vertical step, $\Delta p_+ < 10^{-1} \alpha$, we find the constraint

$$N > 10^2 \left( \frac{m_p}{m} \right)^2.$$  

(28)

We see that a larger mass $m$ means that fewer runs $N$ per data point are required, which implies a shorter total duration $T_{\text{tot}}$ of the experiment. Indeed, since plotting $p_+(t/\beta)$ requires $N$ runs per data point, each run requiring at least a time $t$, a lower bound for the total duration of the experiment is

$$T_{\text{tot}} \sim N dp N t,$$  

(29)

where $N dp$ is the number of data points. Thus, the constraint (28) can be restated as

$$\frac{T_{\text{tot}}}{N dp t} > 10^2 \left( \frac{m_p}{m} \right)^2.$$  

(30)

This constraint imposes a trade-off between the time required to resolve the discreteness and the mass that has to put in superposition. It counter-balances the fact that it is harder to achieve quantum control of a large mass.

The uncertainty in $t/\beta$ is found via the the standard formula for the propagation of uncertainty and can be expressed as

$$\Delta(t/\beta) = U \frac{t}{\beta},$$  

(31)

where

$$U \defeq \left[ \left( \frac{\Delta t}{t} \right)^2 + \left( \frac{d}{d+1} + 1 \right) \left( \frac{\Delta d}{d} \right)^2 \right. \left. + \left( \frac{\Delta M}{M} \right)^2 + \left( \frac{d}{d+1} \right)^2 \left( \frac{\Delta l}{l} \right)^2 \right]^{\frac{1}{2}}.$$  

(32)

By assumption (19), the width of the plateaux is 1. To place several data points on each plateau, we require the typical uncertainty to be an order of magnitude smaller, i.e. $\Delta(t/\beta) < 10^{-1}$. We thus impose the constraint

$$U < 10^{-1} \frac{\beta}{t}$$  

(33)

on the experimental parameters. A given precision $U$ determines the highest value of $n = [t/\beta]$ for which the discontinuities can be resolved.

3. Gravitational Noise

There is no analog of a Faraday cage for gravitational interactions, so influences by other masses will also contribute to the accumulated phase $\phi$. Since the experiment we are considering is in a sense an extremely sensitive gravimeter, these would need to be taken carefully into account.

We distinguish between ‘predictable’ gravitational influences and ‘unpredictable’ gravitational influences, i.e. gravitational noise. The latter type will dictate the degree of isolation required for a successful realisation of the experiment, adding another visibility constraint, while the former type can be dealt with by calibration.

The presence of unexpected masses in the vicinity of the apparatus may disturb the measurement. It will contribute to the proper time dilation by an amount $\eta$, modifying (22) to

$$P^b_+(\eta) = \frac{1}{2} + \frac{1}{2} \sin \left( \frac{m}{m_p} \left( \frac{t}{\beta} + \frac{\eta}{t_p} \right) \right).$$  

(34)

Getting a single data-point requires $N$ drops, and for each drop, the perturbation $\eta$ may be a priori different. However, it should be small enough so that it does not make the probability $P^b_+$ jump to another step, i.e. $\eta$ is a negligible noise if

$$\left| \frac{t}{\beta} + \frac{\eta}{t_p} \right| = \left| \frac{t}{\beta} \right|.$$  

(35)
Of course, $\eta$ is a random variable over which the control is limited. To a first approximation, the condition (35) can be implemented over the $N$ drops by requiring
\[ \Delta \eta < 10^{-1} t_P. \] (36)
For instance, the gravitational noise induced by the presence of a mass $\mu$ at a distance $D \gg l, d$ is at most
\[ \eta_{\text{max}} = \pm \frac{G \mu t}{D^2 \hbar}. \] (37)
Thus, we get a fair idea of how isolated the apparatus should be with the condition
\[ 2G \mu \frac{t}{D^2 \hbar} < 10^{-1} t_P. \] (38)
The ratio
\[ A \overset{\text{def}}{=} \frac{\mu}{D^2} \] (39)
is a measure of the impact that a mass $\mu$ has on the visibility of the discontinuities if it is allowed to move uncontrollably as close as a distance $D$ away from the apparatus. From this, we end up with the following constraint
\[ Alt < 5 \times 10^{-2} \frac{t_{pm}}{t_P}. \] (40)
This equation is a requirement on the control of the environment necessary to resolve the discontinuities. Shorter superpositions are less sensitive to the gravitational noise.

Above, we took into account the effect of a single mass $\mu$. This is not sufficient to guarantee that there will not be a cumulative effect from several masses around. However, note that if these masses are homogeneously distributed, their contributions average out.

The ‘predictable’ type of gravitational influences are systematic errors arising for example from the gravitational field of the Earth, the Moon, and the motion of other large bodies, such as tectonic activity or sea tides, but also from small masses that will unavoidably be present in the immediate vicinity of the mass $m$, such as the experimental apparatus itself and the surrounding laboratory. Given the extreme sensitivity of the apparatus, it will likely not be possible to make all these gravitational influences satisfy (40). However, the contribution of a mass $m$ at distance $D$ can be calibrated\(^2\) for if it moves slowly with respect to the time $Nt$ that it takes to collect one data point, i.e. if
\[ Ntv \ll D \] (41)
with $v$ the speed of the mass $\mu$. Another possibility that can be calibrated for is if the mass is not moving slowly but the uncertainty in its position is small with respect to $D$ (for instance, a moving mechanical part or the Moon).

### B. Balancing act

The three experimental constraints identified in the previous subsection are repeated below.

\[ \left\{ \begin{array}{l} 10^2 \frac{N_{dp} t}{T_{\text{tot}}} < \left( \frac{m}{m_P} \right)^2 \quad \text{[Vertical]} \\ \frac{U t}{\beta} < 10^{-1} \quad \text{[Horizontal]} \\ Alt < 5 \times 10^{-2} \frac{t_P}{l_P} \frac{m_P}{l_P} \quad \text{[Noise]}, \end{array} \right. \] (42)

with
\[ \frac{t}{\beta} = \frac{M}{m_P} \frac{ctl}{d(d + l)}. \] (43)

We now proceed to identify a set of reasonable parameters that satisfy the constraints. Our series of assumptions is an educated guess based on our understanding of current technological trends.

1. Any of the parameters $M, d, l$ and $t$ could be modulated to scan a range of $t/\beta$. Since $t/\beta$ is most sensitive to changes in $d$ (quadratic dependence), we assume the modulation of $d$, keeping $M, l$ and $t$ fixed.

2. The total duration of the experiment is about a year
\[ T_{\text{tot}} \sim 10^7 \text{s}. \] (44)

3. The plot requires about a hundred of data points
\[ N_{dp} \sim 10^2, \] (45)
to be distributed over ten plateaux
\[ t/\beta \leq 10. \] (46)

4. Experimentally, the maximal distance between the two branches of the superposition cannot be very large, and so we assume
\[ d \gg l. \] (47)

\(^2\) A simple method to calibrate when the different values of $t/\beta$ are obtained by changing $d$ only while keeping $M, l$ and $t$ fixed, as considered in the following section, is the following. The mass $\mu$ will contribute a constant phase $\phi_\beta$. The state of the mass $\mu$ when the experiment is performed without $M$ present is $|0\rangle + e^{i\phi_\beta} |1\rangle/\sqrt{2}$. We can estimate the phase $\phi_\beta$ by running the experiment without $M$. So long as the masses are slow moving, it suffices to rotate the measurement basis to $|0\rangle + e^{i\phi_\beta} |1\rangle/\sqrt{2}$ rather than $\{|\pm\rangle\}$. 

From these first assumptions, the system of inequalities simplifies to

\[
\begin{cases}
  t < 10^3 \left(\frac{m_p}{m}\right)^2 \text{[Vertical]} \\
  U < 10^{-2} \text{[Horizontal]} \\
  A t < 5 \times 10^{-2} \frac{t_p m_p}{l_p} \text{[Noise]} \\
  t/\beta \leq 10 \text{[Range]},
\end{cases}
\]  

(48)

with

\[ \frac{t}{\beta} = \frac{M}{m_p} \frac{c t l}{d^2}. \]  

(49)

The uncertainty \( U \), defined by equation (32), depends on the precision in \( t, M, d \) and \( l \). With the assumption \( l \gg d \) its expression simplifies to

\[ U \approx \frac{\Delta l}{l}. \]  

(50)

5. It is reasonable to expect that the uncertainty \( U \) will be dominated by the uncertainty in the superposition size \( l \), thus,

\[ U \approx \frac{\Delta l}{l}. \]  

(51)

6. We assume possible to control the size of the superposition to the scale of a few atoms, i.e.

\[ \Delta l = 10^{-9} \text{m}. \]  

(52)

7. From the above two points we have a lower bound for the value of \( l \). Taking \( l \) larger, would only make the experiment harder because of decoherence and gravitational noise. We thus take

\[ l \sim 10^{-7} \text{m} \]  

(53)

which satisfies the horizontal constraint, allowing to resolve the first 10 steps.

8. We have now solved the horizontal constraint and fixed \( l \). The remaining constraints evaluate to

\[
\begin{cases}
  t < 10^3 \left(\frac{m}{m_p}\right)^2 \text{[Vertical]} \\
  U < 10^{-2} \text{[Horizontal]} \\
  A t < 4 \times 10^{-11} \text{kg s m}^{-2} \text{[Noise]} \\
  M t / d^2 < 7 \times 10^{-9} \text{kg s m}^{-2} \text{[Range]}.
\end{cases}
\]

(54)

All three equations suggest to take \( t \) as small as possible. Nonetheless, this cannot be too short because the superposition is created by a magnetic field \( B \) that separates the branches at a distance \( l \). This process requires some time \( t_{\text{acc}} \), which is bounded from below by the highest magnetic field \( B_{\text{max}} \) that can be created in the lab. Concretely,

\[ \mu_B \frac{B_{\text{max}}}{l} > \frac{m l}{t_{\text{acc}}^2}, \]  

(55)

where \( \mu_B \) is the Bohr magneton (\( \mu_B \approx 10^{-23} \text{J.T}^{-1} \)).

8. \( t \) should be at least as long as \( t_{\text{acc}} \), say

\[ t \sim 3 t_{\text{acc}}. \]  

(56)

9. Taking \( B_{\text{max}} \sim 10^2 \text{T} \), which is the value of the strongest pulsed non-destructive magnetic field regularly used in research [21], we get in SI units

\[ 10^{-8} t^2 > m. \]  

(57)

10. Considering the difficulty to put a heavy mass in superposition, we can minimise both \( t \) and \( m \) under the vertical constraint of (54) and equation (57). We find

\[ m = 3 \times 10^{-10} \text{kg} \sim 10^{-2} m_p, \]

\[ t = 10^{-1} \text{s}. \]  

(58)

These values are consistent with the assumptions made above that \( m \ll m_p \) and \( \Delta t / t \ll 10^{-2} \). We have thus solved the Vertical constraint too. We are left with

\[ \{ \begin{align*}
  A &< 4 \times 10^{-10} \text{kg m}^{-2} \text{[Noise]} \\
  M / d^2 &< 7 \times 10^{-8} \text{kg m}^{-2} \text{[Range]}. \end{align*} \]  

(59)

11. Considering a priori the difficulty to isolate the system from external perturbations, the noise inequality fixes the minimal upper bound for \( A \), i.e. we want to tolerate perturbations as high as

\[ A = 4 \times 10^{-10} \text{kg m}^{-2}. \]  

(60)

This threshold is very sensitive. To give an example, it corresponds to the gravity induced by a bee flying 230m away. Such a high control might only be attainable in space, where cosmic dust particles, with typical mass of \( 5 \mu g [22] \), would need to be kept 4m away from the masses.

We are thus left with one last inequality which reads, in SI units,

\[ d > 4 \times 10^3 \sqrt{M}. \]  

(61)

12. We have implicitly assumed that \( m \) is a test mass moving in the geometry defined by \( M \), so we require \( M \geq 10 \text{ m} \) for consistency. Choosing the minimal value

\[ M = 10 \text{ m}, \]  

(62)

leads to

\[ d \geq 0.17 \text{ m}. \]  

(63)
This corresponds to the lower bound for the range that \( d \) will scan, corresponding to \( t/\beta = 10 \). The value \( t/\beta = 1 \) provides an upper bound of \( d \approx 54 \) cm. Note that the assumption made above that \( \Delta d/d, \Delta M/M \ll 10^{-2} \) is indeed reasonable.

_Casimir-Polder_. So far, we have not taken into account the Casimir-Polder (CP) force between the two masses. The modification of the vacuum energy between two perfectly conducting, parallel discs of area \( a \) a distance \( d \) apart [23] results in a force \( F_{\text{CP}} = \frac{\hbar^2}{24\pi^2}a \). Taking this force as an overestimate of that between two spherically dielectric particles of cross-sectional area \( a \) a distance \( d \) apart, we see that the CP force is at most a million times weaker than the gravitational force and can thus be neglected.

**Uncertainty on \( m \).** A small shift \( \delta m \) on the mass \( m \) adds a phase difference \( \epsilon = \delta m/m \cdot [t/\beta] \), which in turn causes a shift \( \delta P \) in the probability. Since \( m \ll m_P \) and \( \beta < 10 \), then \( \epsilon \ll 1 \) and the shift is to first order \( \delta P \approx \frac{\epsilon}{\alpha} \cdot \delta m \). The uncertainty in \( m \) does not affect the visibility of the probability axis if \( \delta P \ll \alpha \), i.e. if \( \delta m/m \ll \beta/\beta \). This last condition on \( m \) means that the mass \( m \) should be known to one part in 100, which is easily reachable.

This concludes our derivation of a set of parameters that satisfy the constraints of the previous subsection and, thus, allow to probe planckian features of time. The values are summarised in table I.

### C. Maintaining Coherence

A mass in superposition of paths will interact with the ambient black body radiation and stray gas molecules in the imperfect vacuum of the device. As the photons and molecules get entangled with the position degrees of freedom of the mass, the coherence of the superposition is lost and the phase cannot be recovered by observing interference between the two paths.

These unavoidable environmental sources of decoherence are well studied both theoretically and experimentally [12, 24, 25]. Gravitational time dilation can also be a source of decoherence for thermal systems [27], but requires much stronger gravitational fields than considered in this experiment.

We assume the experiment will be performed with a nanodiamond of mass \( m = 3 \times 10^{-10} \) kg, radius \( R = 30 \) \( \mu \)m. For the formulae appearing in this section we refer the reader to [24].

#### 1. Black-Body Radiation

The typical wavelength of thermal photons (\( \approx 10^{-5} \) m at room temperature) is much larger than \( l \), thus spatial superpositions decohere exponentially in time with a characteristic time

\[
\tau_{bb} = \frac{1}{\Lambda_{bb} \ell^2},
\]

which is sensitive to the superposition size \( \ell \). The factor \( \Lambda_{bb} \) depends on the material properties of the mass as well as its temperature and that of the environment. If the environment and the mass are at the same temperature \( T \) then the factor is

\[
\Lambda_{bb} = \frac{8!8}{9\pi} \left( \frac{k_B T}{\hbar} \right)^{9} \left[ \Re \left( \frac{\epsilon - 1}{\epsilon + 2} \right)^2 \right] + \frac{32\pi^5}{189} \left( \frac{k_B T}{\hbar} \right)^{6} \left[ \Im \left( \frac{\epsilon - 1}{\epsilon + 2} \right) \right],
\]

where \( \epsilon \) is the dielectric constant of the material at the thermal frequency, which is 5.3 for diamond [28], and \( \zeta \) is the Riemann zeta function. Plugging in the the radius of 30 \( \mu \)m of the masses under consideration and the superposition size \( 10^{-17} \) \( \mu \)m, we have

\[
\tau_{bb} \approx 2 \times 10^5 \text{ s}\left( \frac{T}{K} \right)^9.
\]

A coherence time of about 1 s, one order of magnitude above \( t \) of table I, will require the temperature to be below 4 K.

#### 2. Imperfect vacuum

The thermal de Broglie wavelength of a typical gas molecule (\( \approx 10^{-10} \) m for He at 4K) is many orders of magnitude below the superposition size \( l \) considered here, thus a single collision can acquire full which-path information and entail full loss of coherence. The exponential decay rate of the superposition is in this case independent on the size \( l \) of the superposition, with a characteristic time

\[
\tau_{\text{gas}} = \frac{\sqrt{3}}{16\pi^2 \sqrt{2}} \sqrt{2m_g k_B T \left( \frac{P R^2}{PR^2} \right)}
\]

in a gas at temperature \( T \), pressure \( P \) of molecules of mass \( m_g \). Assuming the gas is entirely made of helium, and setting the highest possible value for the temperature according to the previous section, we get

\[
\tau_{\text{gas}} \approx \frac{10^{-17}}{P/\text{Pa}} \text{s}.
\]

Thus a coherence time of \( 10t = 1 \) s requires a pressure of \( 10^{-17} \text{Pa} \). This is a regime of extremely low pressure and may present the most serious challenge for any experiment that involves setting masses of this scale in path superposition. To put things in perspective, pressures of the order \( 10^{-18} \text{Pa} \) are found in nature in the warm-hot intergalactic medium [29], while the interstellar medium pressure is at the range of \( 10^{-14} \text{Pa} \) [30].
the other hand, pressures as low as $10^{-15}$ Pa at 4 K have been reported since the 1990’s in experiments employing cooling magnetic traps [31, 32]. In a similar context to ours, the contemporary GME detection proposals quoted above require pressures of $10^{-15}$ Pa at 0.15 K [3]. Finally, the cryogenic requirements found in this section can be relaxed if the path superposition can be achieved faster. From equations (55) and (56), if a stronger magnetic field can be used this will require shorter coherence times.

**D. Discussion of the hypothesis**

At first sight, the hypothesis

$$\delta \tau = n \, t_p$$

(16)

mimics the naïve picture of a tiny clock ticking at a constant rate, with a lapse $t_p$. This simple physical picture of the quantum mechanical phase as a sort of intrinsic ‘clock’ ticking at Planckian time intervals is appealing in its simplicity and does not depend on any particular model of quantum gravity. Thus, in our opinion, it is on its own right worth being looked at.

Whether this hypothesis is backed by a physical theory of time is unclear. In the well corroborated fundamental paradigms of general relativity and quantum mechanics, time is modelled as a continuous variable. However, in a more fundamental theory like quantum gravity, yet to be established, one can reasonably expect a modification of the notion of time at Planckian scale. We discuss two main avenues by which the continuous time can become discrete:

A. Instead of a smooth spacetime, consider it instead an effective description on large scales, that emerges from an underlying discrete lattice.

B. Promote time to a quantum observable with a discrete spectrum.

**A.** Most straightforwardly, (16) can be taken prima facie to arise from a kind of classical discreteness. Assuming that the notion of proper time $\tau$ of general relativity becomes discrete in a linear sense, with regular spaced Planckian time intervals, then also differences of proper time $\delta \tau$ will display a similar behaviour, from which (16) follows. This assumption is made for instance in the program of Digital Physics [33], which advocates that space may be nothing but a grid.

Of course, such a ‘classical’ discreteness would manifestly break Lorentz invariance. It might be already possible to set upper bounds on the discreteness of time from the limits set on Lorentz invariance violations by the study of the dispersion relations of light [34–37].

**B.** Turning to the quantum theory, the discreteness of time may appear as the discreteness of the spectrum of some time operator. Contrary to general belief, Pauli’s argument [41] has not ruled out the possibility of a time-operator but rather stressed the subtlety of its definition [42].

There are two main candidates for being the relevant time observable here: the proper time interval $\tau$ in each branch and the difference of proper time $\delta \tau$ between the branches. Then in both cases the question of which spectrum is to be expected should be answered.

Equation (16) can be regarded as the assumption of the linearity of the spectrum. For comparison, this is very different from the energy spectrum of the hydrogen atom $E_n \propto -1/n^2$ but it is very similar to that of the harmonic oscillator $E_n \propto n$. If the spectrum of $\tau$ is linear, then so is the spectrum of $\delta \tau$, which is what we assumed in the main analysis with equation (16). Thus, it does not really matter in this case, whether it is $\tau$ or $\delta \tau$ which is taken as the relevant quantum observable. On the contrary, for a non-linear spectrum, this question is crucial. As said earlier, the assumption of linearity is natural in the sense that it mimics the ticking of a clock, but it is not really backed so far by any theory of quantum gravity.

In Loop Quantum Gravity (LQG) the spectrum of the area operator but rather stressed the subtlety of its definition

$$A_j = 8\pi \gamma \ell_p^2 \sqrt{j(j+1)}, \quad j \in \mathbb{N}/2,$$

where $\gamma$ is a fundamental constant called the Immirzi parameter. There are indications that length has a spectrum that goes as a square root progression in $j$ [47]. Geometrically, we would expect time to behave similarly to a length. In such a case, it will make all the difference whether the square-root behaviour applies to the proper time itself

$$\tau = \sqrt{n} \, t_p,$$

(70)

or the difference of proper time

$$\delta \tau = \sqrt{n} \, t_p.$$

(71)

We first analyse the consequences of equation (70) on the visibility of the plateaux. We work in Planck units and take $l \ll d$ as in the main text, although the same result can be obtained without this assumption. The proper times $\tau_{\text{far}}$ and $\tau_{\text{close}}$ of the branch in which $M$ and $m$ are a distance $d + l$ and $d$ apart are given in terms of laboratory time according to general relativity by

$$\tau_{\text{far}} = t \sqrt{1 - \frac{2M}{d + l}}, \quad \tau_{\text{close}} = t \sqrt{1 - \frac{2M}{d}}.$$
These are very large compared to the Planck time, as we are in the weak field regime and \( t \) cannot be smaller than the period of the sharpest atomic clock. Let’s now impose the discretisation (70)

\[
\tau_{\text{far}} = \sqrt{n + k}, \quad \tau_{\text{close}} = \sqrt{n}
\]

(73)

where

\[
n + k = \left( 1 - \frac{2M}{\alpha + t} \right) t^2, \quad n = \left( 1 - \frac{2M}{\alpha} \right) t^2.
\]

(74)

Equation (16) is thus replaced by

\[
\delta \tau = \left( \sqrt{n + k} - \sqrt{n} \right) t_P.
\]

(75)

The condition \( l \ll d \) implies that \( k \ll n \), so that the equation above simplifies to

\[
\delta \tau \approx \frac{k}{2\sqrt{n}}.
\]

(76)

So in this case, a square-root behaviour for the spectrum of \( \tau \) leads to a linear behaviour for \( \delta \tau \). Unfortunately, the factor of \( \sqrt{n} \) in the denominator means that different values of \( \delta \tau \) are exceedingly close to each other, making the experiment impossible in our proposed setup.

We now consider the case (71). We have

\[
n = \left( \frac{t}{\beta} \right)^2.
\]

(77)

so that

\[
P^h = \frac{1}{2} + \frac{1}{2} \sin \left( \frac{m}{m_P} \left[ \left( \frac{t}{\beta} \right)^2 \right] \right).
\]

(78)

For small values of \( t/\beta \), the plot of \( P^h \) is the same as the one of \( P^h \), studied in the main text. For larger values of \( t/\beta \), both the width of the plateaus and the steps between them are smaller. Thus, the detection of such a discreteness is of similar difficulty so long as \( t/\beta < 10 \) (see figure 3).

Figure 3. Plot of \( P_+ \) as a function of \( t/\beta \) with an alternative hypothesis. We take \( m = 10^{-2} m_P \). Blue curve: \( \delta \tau \) takes continuous values. Red curve: \( \delta \tau = n t_P \) as considered in the main text. Green curve: \( \delta \tau = \sqrt{n} t_P \), as motivated from LQG in this section.

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Figure 1

Spacetime view of the experiment. For a time $t_{acc}$, an inhomogeneous magnetic field is applied that sets a mass $m$ with embedded spin in a superposition of two paths, at a distance $d$ and $d + l$, respectively, from another mass $M$. The masses are in free fall for a time $t$, as measured in the laboratory, after which
the procedure is reversed and the superposition undone. During this time $t$, the two branches accumulate a different phase due to the gravitational interaction with $M$.

![Graph](image)

**Figure 2**

Probability of measuring spin $|+i$ as a function of $t/\beta$ under the continuous and discrete time hypotheses. Blue line: $\delta \tau$ is smooth as in equation (17). Red line: $\delta \tau$ is discrete as in equation (20). We have taken the value of $m = 10^{-2}m_P$. The experimental parameters shown in table I would produce 100 data points scanning the range of $t/\beta$ depicted here, with a sufficient resolution to decide which of the two curves is realised in nature.
Figure 3

Plot of $P_+$ as a function of $t/\beta$ with an alternative hypothesis. We take $m = 10^{-2}m_P$. Blue curve: $\delta \tau$ takes continuous values. Red curve: $\delta \tau = \sqrt{n} t P$ as considered in the main text. Green curve: $\delta \tau = n t P$, as motivated from LQG in this section.