FACTORIZATIONS OF BIRATIONAL EXTENSIONS OF LOCAL RINGS

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In honor of Phillip Griffith

Abstract. We give a proof of local strong factorization of a birational, monomial extension of regular local rings along a valuation of rank 1 and maximal rational rank. Our proof uses methods from linear algebra, and is in the spirit of Christensen’s proof of this result in dimension 3. This has also been proven by Karu using toric geometry.

1. Introduction

Suppose that $R$ and $S$ are regular local rings such that $S$ dominates $R$ ($R \subset S$ and the maximal ideal $m_S$ of $S$ contracts to the maximal ideal $m_R$ of $R$).

$R \to S$ is monomial if there exist regular parameters $x_1, \ldots, x_m$ in $R$, $y_1, \ldots, y_n$ in $S$, an $m \times n$ matrix $A = (a_{ij})$ of rank $m$ whose entries are nonnegative integers and units $\delta_i \in S$ such that

$$x_i = \prod_{j=1}^{n} y_{a_{ij}}^{a_{ij}} \delta_i$$

for $1 \leq i \leq m$.

Suppose that $P \subset R$ is a regular prime ($R/P$ is a regular local ring) and $0 \neq f \in P$. The regular local ring $R_1 = R[\frac{P}{f}]_m$, where $m$ is a maximal ideal of $R[\frac{P}{f}]$ containing $m_R$, is called a monoidal transform of $R$.

Suppose that $V$ is a valuation ring of the quotient field of $S$ which dominates $S$ (and thus dominates $R$). Then given a regular prime $P$ of $R$ (or of $S$) there exists a unique monoidal transform $R_1$ of $R$ (or $S_1$ of $S$) obtained from $P$ such that $V$ dominates $R_1$ (or $V$ dominates $S_1$).

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The local monomialization theorem of [C2] and [C4] shows that given an extension $R \to S \subset V$ as above such that $R, S$ are essentially of finite type over a field $k$ of characteristic zero, there exists a commutative diagram

$$
\begin{array}{ccc}
R_1 & \to & S_1 \\
\uparrow & & \uparrow \\
R & \to & S
\end{array}
$$

such that the vertical arrows are products of monoidal transforms and $R_1 \to S_1$ is monomial.

Suppose that we further have that $R \to S$ is birational (the induced homomorphism of quotient fields is an isomorphism). If $R \to S$ is monomial and birational, then we can find regular parameters $y_1, \ldots, y_n$ in $S$ such that

$$x_i = \prod_{j=1}^n y_j^{a_{ij}}$$

for $1 \leq i \leq n$ (since $B = A^{-1}$ has integral coefficients).

We may now state Abhyankar’s local factorization conjecture (page 237 of [Ab]). Suppose that $R \to S$ is a birational extension of regular local rings of dimension $n \geq 3$ and $V$ is a valuation ring of the quotient field of $S$ such that $V$ dominates $R$. The conjecture is that there exists a commutative diagram

$$
\begin{array}{ccc}
T & \subset & V \\
R & \to & S
\end{array}
$$

where the northeast and northwest arrows are products of monoidal transforms.

It is proven in [Z] and [Ab1] that there is a direct factorization of $R \to S$ by monoidal transforms if $n = 2$. However, examples of the failure of a direct factorization of $R \to S$ by monoidal transforms are given in [Sa] and [Sh] when $n \geq 3$.

The local factorization theorem is proven when $n = 3$ (and $R$ is essentially of finite type over a field of characteristic 0) in [C1, Theorem A].

In [C2, Theorem 1.9] it is proven that the local monomialization theorem ([C2, Theorem 1.1]) and “strong factorization” of birational toric morphisms of nonsingular toric varieties implies the local factorization theorem in all dimensions (in characteristic zero).

There are two published proofs of “strong factorization” of birational toric morphisms, [Mo] and [AMR]. They have both been found to have errors (as explained in the correction [AMR1] to [AMR]).

Suppose that $R$ is essentially of finite type over a field. In [C2], a strong version of local monomialization is used to reduce the proof of local factorization to the following problem, which is essentially in linear algebra.
We assume that $R \to S$ is monomial, with respect to regular parameters $x_1, \ldots, x_n$ in $R$ and $y_1, \ldots, y_n$ in $S$, the value group of $V$ is contained in $R$, and if $\nu$ is a valuation of the quotient field of $S$ whose valuation ring is $V$, then

$$\tau_1 = \nu(y_1), \ldots, \tau_n = \nu(y_n)$$

are rationally independent real numbers.

In this special case, we can assume that $R = k[x_1, \ldots, x_n](x_1, \ldots, x_n)$ and $S = k[y_1, \ldots, y_n](y_1, \ldots, y_n)$, where $k$ is a field. We have expressions $x_i = \prod_{j=1}^{n} y_j^{a_{ij}}$ for $1 \leq i \leq n$. If

$$f = \sum \alpha_{i_1, \ldots, i_n} y_1^{i_1} \cdots y_n^{i_n} \in k[y_1, \ldots, y_n],$$

we have $\nu(f) = \min\{i_1 \tau_1 + \cdots + i_n \tau_n \mid \alpha_{i_1, \ldots, i_n} \neq 0\}$. We will call the local factorization conjecture in this special case the “monomial problem”.

When $n = 3$, the monomial problem is solved by Christensen [Ch]. In [C2, Theorem 1.6], the first author extends this to prove a weaker form of the monomial problem for all $n$. By combining this with the local monomialization theorem of [C2], it was proved in [C2] that a birational extension $R \to S$ can be factored by $n - 2$ triangles of monoidal transforms.

Recently, there has been a proof by Karu [K] of this monomial problem, using toric geometry.

In this paper, we give a self-contained proof of the monomial problem. We solve the problem in the spirit of Christensen’s original theorem in dimension 3. In particular, the problem can be stated completely in the language of linear algebra, and we prove it using linear algebra. As a result, we give an explicit algorithm for the solution of the monomial problem. This theorem (Theorem 2.1) is proven in Section 2 of this paper. The solution to the monomial problem is given in Theorem 3.1.

We show in Theorem 3.3 of Section 3 of this paper how the local monomialization theorem, [C2, Theorem 1.1] and Theorem 2.1 of this paper prove the local factorization conjecture. This provides a complete proof to Theorem 1.9 of [C2].

A monoidal transform affects the coefficient matrix $A$ as a column addition. The valuation can be understood as a column vector $\vec{v}$ of positive rational numbers. To preserve the property that the valuation ring dominates the monomial transform of the local ring, we allow only those column operations on $A$ that keep both $A$ and $A^{-1}\vec{v}$ positive. We construct an algorithm here for finding a sequence of permissible column additions and interchanges to be followed by a sequence of permissible subtractions that results in the identity matrix.
2. Matrix factorization

Suppose that \( A = (a_{ij}) \) is an \( n \times n \) matrix with coefficients which are nonnegative integers and \( \det(A) = \pm 1 \). Further suppose that \( \vec{v} = (v_1, \ldots, v_n)^t \) is a \( n \times 1 \) column vector with coefficients which are positive rationally independent real numbers, and \( \vec{w} = (w_1, \ldots, w_n)^t = A^{-1} \vec{v} \) is a vector with positive coefficients (which are necessarily rationally independent). \((A, \vec{v}, \vec{w})\) satisfying these conditions will be called an \( n \)-dimensional triple.

The column addition \( C_{ij} \) of \( A \) which adds the \( j \)-th column of \( A \) to the \( i \)-th column is called permissible for \((A, \vec{v}, \vec{w})\) if \( w_j - w_i > 0 \). The triple \((A, \vec{v}, \vec{w})\) is transformed under the permissible column addition \( C_{ij} \) to the triple \((A(1), \vec{v}(1), \vec{w}(1))\), where \( A(1) = (a(1)_{ij}) \) is obtained from \( A \) by adding the \( j \)-th column of \( A \) to the \( i \)-th column, \( \vec{v}(1) = \vec{v} \) and \( \vec{w}(1) = (w(1)_1, \ldots, w(1)_n)^t = A(1)^{-1} \vec{v}(1) \). \( \vec{w}(1) \) is obtained from \( \vec{w} \) by subtracting the \( i \)-th coefficient \( w_i \) from the \( j \)-th coefficient \( w_j \) of \( \vec{w} \).

The row subtraction \( R_{j|i} \) of \( A \) which subtracts the \( i \)-th row of \( A \) from the \( j \)-th row is called permissible for \((A, \vec{v}, \vec{w})\) if \( a_{jk} \geq a_{ik} \) for \( 1 \leq k \leq n \). The triple \((A, \vec{v}, \vec{w})\) is transformed under the permissible row subtraction \( R_{j|i} \) to the triple \((A(1), \vec{v}(1), \vec{w}(1))\), where \( A(1) = (a(1)_{ij}) \) is obtained from \( A \) by subtracting the \( i \)-th row of \( A \) from the \( j \)-th row, \( \vec{v}(1) \) is obtained from \( \vec{v} \) by subtracting the \( i \)-th coefficient \( v_i \) from the \( j \)-th coefficient \( v_j \) and \( \vec{w}(1) = (w(1)_1, \ldots, w(1)_n)^t = A(1)^{-1} \vec{v}(1) \). We have that \( \vec{w}(1) = \vec{w} \).

The row interchange \( T_{ij} \) of \( A \) interchanges the \( i \)-th and \( j \)-th rows of \( A \). \( T_{ij} \) transforms the triple \((A, \vec{v}, \vec{w})\) into the triple \((A(1), \vec{v}(1), \vec{w}(1))\), where \( A(1) \) is obtained from \( A \) by interchanging the \( i \)-th and \( j \)-th row, \( \vec{w}(1) = \vec{w} \) and \( \vec{v}(1) \) is obtained from \( \vec{v} \) by interchanging the \( i \)-th and \( j \)-th row of \( \vec{v} \).

In this section, we prove the following theorem:

**Theorem 2.1.** Suppose that \( A = (a_{ij}) \) is an \( n \times n \) matrix with coefficients which are nonnegative integers and \( \det(A) = \pm 1 \). Further suppose that \( \vec{v} = (v_1, \ldots, v_n)^t \) is a \( n \times 1 \) vector with coefficients which are positive rationally independent real numbers. Then there exists a sequence of permissible column additions and row interchanges

\[
(A, \vec{v}, \vec{w}) \rightarrow (A(1), \vec{v}, \vec{w}(1)) \rightarrow \cdots \rightarrow (A(s), \vec{v}, \vec{w}(s))
\]

followed by a sequence of permissible row subtractions

\[
(A(s), \vec{v}, \vec{w}(s)) \rightarrow (A(s + 1), \vec{v}(s + 1), \vec{w}(s)) \rightarrow \cdots \rightarrow (A(t), \vec{v}(t), \vec{w}(t))
\]

such that \( A(t) \) is the \( n \times n \) identity matrix.

We will denote the inverse of a matrix \( A \) by \( B = (b_{ij}) = A^{-1} \). If a permissible column addition \( C_{ij} \) is performed by adding the \( j \)-th column of \( A \) to the \( i \)-th column, with a resulting transformation of triples \((A, \vec{v}, \vec{w}) \rightarrow (A(1), \vec{v}, \vec{w}(1))\), then \( B(1) = (b(1)_{ij}) = A(1)^{-1} \) is obtained from \( B = A^{-1} \) by


substituting the $i$-th row of $B$ from the $j$-th row, since $C_{ij}^{-1} = R_{ji}$ and
\[ B(1) = A(1)^{-1} = (AC_{ij})^{-1} = C_{ij}^{-1}A^{-1} = R_{ji}A^{-1}. \]
Similarly, if a permissible row subtraction $R_{ij}$ is performed by substituting
the $i$-th row of $A$ from the $j$-th row, with a resulting transformation of triples
$(A, \vec{v}, \vec{w}) \to (A(1), \vec{v}(1), \vec{w})$, then $B(1) = (b(1)_{ij}) = A(1)^{-1}$ is obtained from
$B = A^{-1}$ by adding the $j$-th column of $B$ to the $i$-th column.
If a permissible row interchange $T_{ij}$ is performed, then $B(1) = A(1)^{-1}$ is
obtained from $B$ by interchanging the $i$-th and $j$-th column.
Given a triple $(A, \vec{v}, \vec{w})$, we define $\beta = \max_k \{ |b_{k1}| \}$. We will write $A = (C_1, \ldots, C_n)$.
To simplify notation, we will denote the inverse of a matrix $A(t)$ by $B(t) = (b_{ij}(t))$, and define $\beta(t) = \max_k \{ |b_{k1}(t)| \}$. We will denote $A(t) = (C_1(t), \ldots, C_n(t))$.

**Remark 2.2.** Fix $i$ and $j$. Either $C_{ji}$ is permissible or $C_{ij}$ is permissible (but not both). If $C_{ij}$ is permissible, then after performing $C_{ij}$ a finite number of times, $C_{ji}$ becomes permissible. This is because $C_{ij}$ decreases $w_j$ by a positive integral multiple of $w_i$.

**Definition 2.3.** A permissible $C_{ij}$ is allowable for the triple $(A, \vec{v}, \vec{w})$ if $b_{i1}$ and $b_{j1}$ are both non-zero and have the same sign.

**Definition 2.4.** A permissible $C_{ij}$ is $\ast$-allowable for the triple $(A, \vec{v}, \vec{w})$ if either $b_{i1}b_{j1} \neq 0$, or $C_{ij}$ is allowable.

**Remark 2.5.** (1) If we perform a $\ast$-allowable $C_{ij}$ on the triple $(A, \vec{v}, \vec{w})$ to get $(A(1), \vec{v}, \vec{w}(1))$, then $b_{j1}(1) = b_{j1} - b_{i1}$, $b_{k1}(1) = b_{k1}$ if $k \neq j$ and thus
\[ \beta(1) = \max \{ |b_{k1}(1)| \} \leq \max \{ |b_{k1}| \} = \beta. \]
(2) Suppose that we fix $i$ and $j$. Then after a finite sequence consisting of allowable $C_{ij}$ and $C_{ji}$, both $C_{ij}$ and $C_{ji}$ are not allowable. If at least one of $b_{i1}$, $b_{j1}$ is nonzero, then after a finite sequence consisting of $\ast$-allowable $C_{ij}$ and $C_{ji}$, both $C_{ij}$ and $C_{ji}$ are not $\ast$-allowable.

**Proof of (2).** If $b_{i1}$ and $b_{j1}$ are nonzero of the same sign, and we perform $C_{ij}$ (or $C_{ji}$) to obtain the new triple $(A(1), \vec{v}, \vec{w}(1))$, and $b_{i1}(1)$, $b_{j1}(1)$ have the same sign, we then obtain that $(|b_{i1}|, |b_{j1}|) > (|b_{k1}(1)|, |b_{k1}(1)|)$ in the Lex order on $\mathbb{Z}^2$.
Suppose that $b_{i1} \neq 0$ and $b_{j1} = 0$. If $C_{ij}$ is $\ast$-allowable, then after performing $C_{ij}$, we obtain that both $C_{ij}$ and $C_{ji}$ are not $\ast$-allowable. If $C_{ji}$ is $\ast$-allowable, and we perform $C_{ji}$, then $b_{i1}(1) = b_{i1}$, $b_{j1}(1) = 0$. By Remark 2.2, we can only perform $C_{ji}$ a finite number of consecutive times. □
Lemma 2.6. There exists a sequence of allowable column additions
\[ (A, \vec{v}, \vec{w}) \rightarrow (A(1), \vec{v}, \vec{w}(1)) \rightarrow \cdots \rightarrow (A(t), \vec{v}, \vec{w}(t)) \]
such that at most two entries of the first column of \( B(t) \) are nonzero.

The proof of this lemma is immediate from [C2, Theorem 6.3].

Lemma 2.7. There exists a sequence of *-allowable column additions
\[ (A, \vec{v}, \vec{w}) \rightarrow (A(1), \vec{v}, \vec{w}(1)) \rightarrow \cdots \rightarrow (A(s), \vec{v}, \vec{w}(s)) \]
such that there are indices \( i \) and \( j \) with \( b_{i1} = 1 \), \( b_{j1} = -1 \) and \( b_l = 0 \) if \( l \neq i \) and \( l \neq j \).

Proof. By Lemma 2.6, there exists a sequence of allowable column additions
\[ (A, \vec{v}, \vec{w}) \rightarrow (A(t_1), \vec{v}, \vec{w}(t_1)) \rightarrow \cdots \rightarrow (A(s), \vec{v}, \vec{w}(s)) \]
such that \( \beta(s) = \max\{ |b_{11}|, |b_{21}| \} \). If \( \beta = 1 \), then we have obtained the conclusions of the theorem.

Assume that \( \beta > 1 \). We will show that we can construct a sequence of column additions in the first 3 columns which are *-allowable
\[ (A, \vec{v}, \vec{w}) \rightarrow (A(1), \vec{v}, \vec{w}(1)) \rightarrow \cdots \rightarrow (A(s_1), \vec{v}, \vec{w}(s_1)) \]
such that \( \beta(s_1) < \beta \).

Once we have established the existence of the sequence (2.1), we can apply Lemma 2.6 to construct a sequence of allowable column additions
\[ (A(s_1), \vec{v}, \vec{w}(s_1)) \rightarrow (A(s_1 + 1), \vec{v}, \vec{w}(s_1 + 1)) \rightarrow \cdots \rightarrow (A(s_2), \vec{v}, \vec{w}(s_2)) \]
such that at most two of the entries in the first column of \( B(s_2) \) are nonzero, and \( \beta(s_2) \leq \beta(s_1) < \beta \). We can thus alternate sequences (2.1) and (2.2) to eventually obtain the conclusions of the theorem.

It remains to prove that we can construct a sequence (2.1).

Since \( \text{Det}(B) = \pm 1 \), and \( \beta > 1 \), we must have that the maximum \( \beta \) is obtained by only one of \( |b_{11}| \) and \( |b_{21}| \). Without loss of generality, we may assume that
\[ \beta = |b_{11}| > |b_{21}|. \]
We now perform a finite sequence of *-allowable column additions $C_{32}$, followed by a *-allowable column addition $C_{23}$ to obtain a sequence of transformations of triples

$$(A, \vec{v}, \vec{w}) \rightarrow \cdots \rightarrow (A(t_1), \vec{v}, \vec{w}(t_1)),$$

where the first column of $B(t_1)$ is

$$(b_{11}(t_1), b_{21}(t_1), \ldots, b_{n1}(t_1))^t = (b_{11}, b_{21}, -b_{21}, 0, \ldots, 0)^t,$$

with $\beta(t_1) = |b_{11}(t_1)| = |b_{11}| = \beta$, and either $C_{13}$ or $C_{31}$ is allowable.

If $C_{31}$ is allowable on $(A(t_1), \vec{v}, \vec{w}(t_1))$, we perform it to get

$$|b_{11}(t_1 + 1)| = |b_{11}(t_1) - b_{31}(t_1)| = |b_{11} + b_{21}| < \beta(t_1) = \beta$$

and we stop.

If not, we have that $C_{13}$ is allowable and after that, $b_{11}(t_1 + 1) = b_{11}$ and

$$b_{31}(t_1 + 1) = b_{31}(t_1) - b_{11}(t_1) = -b_{21} - b_{11}$$

have opposite signs. Further, $\beta(t_1 + 1) = \beta(t_1)$ and $w_3(t_1 + 1) = w_3(t_1) - w_1 \leq w_3 - w_1$. Now, $C_{32}$ or $C_{23}$ must be allowable.

Now we perform a finite sequence of *-allowable column additions $C_{32}$, and *-allowable column additions $C_{23}$, to obtain a sequence of transformations of triples

$$(A(t_1 + 1), \vec{v}, \vec{w}(t_1 + 1)) \rightarrow \cdots \rightarrow (A(t_2), \vec{v}, \vec{w}(t_2)),$$

where $\beta(t_2) = \beta(t_1 + 1) = \beta$,

$$\max\{ |b_{21}(t_2)|, |b_{31}(t_2)| \} < |b_{11}(t_2)| = \beta(t_2) = \beta,$$

and $b_{21}(t_2)$ and $b_{31}(t_2)$ have opposite signs. One of $C_{13}, C_{31}, C_{12}$ or $C_{21}$ must now be allowable.

Performing an allowable $C_{31}$ or $C_{21}$ decreases $\beta$ and we stop. If not, we perform $C_{13}$ or $C_{12}$ to get $\beta(t_2 + 1) = \beta(t_2)$ and none of the four $C_{13}, C_{31}, C_{12}$ and $C_{21}$ are allowable.

Further, $w_2(t_2 + 1)$ or $w_3(t_2 + 1)$ is reduced by $w_1$, so that,

$$w_2(t_2 + 1) + w_3(t_2 + 1) = w_2(t_2) + w_3(t_2) - w_1 \leq w_2 + w_3 - 2w_1.$$

Now either $C_{32}$ or $C_{32}$ becomes allowable and we repeat this process. Since we can perform a $C_{13}$ or a $C_{12}$ at most $\lfloor (w_2 + w_3)/w_1 \rfloor$ times, we must achieve a reduction in $\beta$ after a finite number of steps. \hfill $\square$

**Lemma 2.8.** Let $(A, \vec{v}, \vec{w})$ be a triple such that $A = (C_1, \ldots, C_n)$ satisfies the relation

$$C_k = C_1 - e_1$$

for some $k$, where $e_1 = (1, 0, \ldots, 0)^t$. Let $A_{11}$ be the matrix obtained from $A$ be deleting the first row and column. Then

$$\text{Det}(A_{11}) = \text{Det}(A) = \pm 1.$$
Let $\tilde{v} = (v_2, \ldots, v_n)^t$ and $\tilde{w} = (\tilde{w}_2, \ldots, \tilde{w}_n) = A_{11}^{-1}\tilde{v}$. Then

$$\tilde{w}_j = w_j \text{ for } j \neq k$$

and

$$\tilde{w}_k = w_1 + w_k.$$

Proof. Set $\lambda = \text{Det}(A) = \pm 1$. Subtracting the $k$-th column of $A$ from the first column, we see that $\text{Det}(A_{11}) = \lambda$. We thus have that $B = A^{-1} = \lambda \text{adj}(A)$, and $A_{11}^{-1} = \lambda \text{adj}(A_{11})$. Let

$$A_{11}^{-1} = \lambda \text{adj}(A_{11}) = \begin{pmatrix} x_{22} & x_{23} & \cdots & x_{2n} \\ x_{32} & x_{33} & \cdots & x_{3n} \\ \vdots & \vdots & \ddots & \vdots \\ x_{n2} & x_{n3} & \cdots & x_{nn} \end{pmatrix}.$$

Since $C_k = C_1 - e_1$ and $\text{adj}(A) = \lambda A^{-1}$, the first column of $\text{adj}(A)$ is

$$(\lambda, 0, \ldots, 0, -\lambda, 0, \ldots, 0)^t,$$

where $-\lambda$ occurs in the $k$-th row.

We will compute the entry $\lambda b_{ij}$ in the $i$-th row and $j$-th column of $\text{adj}(A)$. Let $A_{ji}$ be the matrix obtained from $A$ by deleting the $j$-th row and $i$-th column.

First suppose that $i \neq 1$, $i \neq k$ and $j > 1$. Subtracting the $k$-th column of $A_{ji}$ (the $(k-1)$-st column of $A_{ji}$ if $i < k$) from the first column, and expanding the determinant along the first column, we get that the $(i, j)$-th entry of $\text{adj}(A)$ is

$$(-1)^{i+j} \text{Det}(A_{ji}) = (-1)^{i+j} \text{Det}[(A_{ji})_{11}]$$

$$= (-1)^{i+j} \text{Det}[(A_{11})_{j-1,i-1}]$$

$$= \lambda x_{i,j}.$$ 

For $j > 1$, set

$$t_j = \lambda (-1)^{1+j} \text{Det}(A_{j1}).$$

We have that the $(1, j)$-th entry of $\text{adj}(A)$ is $\lambda t_j$. We expand
\[(−1)^{1+j} \det(A_{j1}) = (−1)^{1+j} \det \begin{pmatrix} a_{12} & \cdots & a_{11} - 1 & \cdots \\ \vdots & \ddots & \ddots & \ddots \\ a_{n2} & \cdots & a_{n1} & \cdots \\ \end{pmatrix} \]

\[= (−1)^{1+j} \det \begin{pmatrix} a_{12} & \cdots & a_{11} & \cdots \\ \vdots & \ddots & \ddots & \ddots \\ a_{n2} & \cdots & a_{n1} & \cdots \\ \end{pmatrix} + (−1)^{1+j+1+k−2} \det[(A_{11})_{j−1,k−1}] \]

\[= (−1)^{1+j+k−2} \det(A_{jk}) + (−1)^{j+k−1} \det[(A_{11})_{j−1,k−1}] \]

\[= −(−1)^{j+k} \det(A_{jk}) + \lambda x_{kj}. \]

We see that, for \( j > 1 \), the \((k,j)\)-th entry of \( \text{adj}(A) \) is \( \lambda (x_{kj} - t_j) \).

In conclusion,

\[B = A^{-1} = \lambda \text{adj}(A) = \begin{pmatrix} 1 & t_2 & \cdots & t_n \\ 0 & x_{22} & \cdots & x_{2n} \\ \vdots & \ddots & \ddots & \ddots \\ −1 & x_{k2} − t_2 & \cdots & x_{kn} − t_n \\ 0 & x_{n2} & \cdots & x_{nn} \end{pmatrix}. \]

Now we see that

\[\tilde{w}_i = (x_{i2}, \ldots, x_{in})(v_2, \ldots, v_n)^t = (0, x_{i2}, \ldots, x_{in})(v_1, \ldots, v_n)^t = w_i \]

if \( i \neq k \), and

\[\tilde{w}_k = \sum_{j=2}^{n} x_{kj} v_j \]

\[= [−v_1 + \sum_{j=2}^{n} (x_{kj} − t_j)v_j] + [v_1 + \sum_{j=2}^{n} t_j v_j] \]

\[= w_k + w_1. \]

Now we prove Theorem 2.1.

A quadruple \((A, \tilde{v}, \tilde{w}, k)\) is a triple \((A, \tilde{v}, \tilde{w})\) and a number \( k \) with \( 1 < k \leq n \) such that if \( A = (C_1, \ldots, C_n) \), then \( C_k = C_1 − e_1 \). To a quadruple \((A, \tilde{v}, \tilde{w}, k)\) we associate an \((n−1)\)-dimensional triple \((\tilde{A} = A_{11}, \tilde{v}, \tilde{w})\) with the notation of Lemma 2.8.
A permissible transformation for the quadruple \((A, \vec{v}, \vec{w}, k)\) is a series of permissible column additions and row interchanges which transform the triple \((A, \vec{v}, \vec{w})\) to a triple \((A(1), \vec{v}, \vec{w}(1))\) and a number \(j\) with \(1 < j \leq n\), such that \((A(1), \vec{v}, \vec{w}(1), j)\) is a quadruple.

By Lemma 2.7, and since \(B = A^{-1}\), there exists a sequence of permissible column additions, possibly followed by some row interchanges \(T_{ij}\), \((A, \vec{v}, \vec{w}) \rightarrow (A(1), \vec{v}, \vec{w}(1))\), and a number \(k(1)\) such that \((A(1), \vec{v}, \vec{w}(1), k(1))\) is a quadruple. Without loss of generality, we may assume that there exists a number \(k\) such that \((A, \vec{v}, \vec{w}, k)\) is a quadruple.

If \(n = 3\), then after expanding the determinant of \(\tilde{A}\), we see that after possibly performing the row interchange \(T_{23}\), there is a sequence of permissible row subtractions \(R_{ji}\) which transform \(\tilde{A}\) into the identity matrix. If \(n > 3\), we assume by induction that there exists a sequence of permissible column additions and row interchanges

\[(\tilde{A}, \vec{v}, \vec{w}) \rightarrow (\tilde{A}(1), \vec{v}, \vec{w}(1)) \rightarrow \cdots \rightarrow (\tilde{A}(s), \vec{v}, \vec{w}(s))\]

followed by a sequence of permissible row subtractions

\[\tilde{A}(s), \vec{v}, \vec{w}(s)) \rightarrow (\tilde{A}(s + 1), \vec{v}(s + 1), \vec{w}(s)) \rightarrow \cdots \rightarrow (\tilde{A}(l), \vec{v}(l), \vec{w}(s))\]

such that \(\tilde{A}(l)\) is the \((n - 1) \times (n - 1)\) identity matrix.

We will first construct a sequence of permissible transformations of quadruples

\[(A, \vec{v}, \vec{w}, k) \rightarrow (A(1), \vec{v}, \vec{w}(1), k(1)) \rightarrow \cdots \rightarrow (A(s), \vec{v}, \vec{w}(s), k(s))\]

such that for \(1 \leq t \leq s\), we have \(A(t)_{11} = \tilde{A}(t)\) and \(\tilde{w}(t) = A(t)^{-1}_{11} (v_2, \ldots, v_n)^t\).

Suppose that we have constructed (2.5) out to \((A(t), \vec{v}, \vec{w}(t), k(t))\), and \(t < s\). We will construct \((A(t + 1), \vec{v}, \vec{w}(t + 1), k(t + 1))\).

First suppose that \(\tilde{A}(t + 1)\) is obtained from \(\tilde{A}(t)\) by interchanging the \(i\)-th and \(j\)-th row. Let the triple \((A(t + 1), \vec{v}(t + 1), \vec{w}(t + 1))\) be obtained from the triple \((A(t), \vec{v}, \vec{w}(t))\) by performing the row interchange \(T_{ij}\). Then the row interchange \(T_{ij}\) determines a permissible transformation of \((A(t), \vec{v}, \vec{w}(t), k(t))\) to \((A(t + 1), \vec{v}, \vec{w}(t + 1), k(t))\), such that \(A(t + 1)_{11} = \tilde{A}(t + 1)\).

Suppose that \(\tilde{A}(t + 1)\) is obtained from \(\tilde{A}(t)\) by adding the \(j\)-th column of \(\tilde{A}(t)\) to the \(i\)-th column. We necessarily have that \(\tilde{w}_j(t) > \tilde{w}_i(t)\). Set \(k = k(t)\).

If \(i \neq k\) and \(j \neq k\), then we have (by Lemma 2.8) that \(\tilde{w}_j(t) > \tilde{w}_i(t)\), and thus the column addition \(C_{ij}\) determines a permissible transformation of \((A(t), \vec{v}, \vec{w}(t), k(t))\) to \((A(t + 1), \vec{v}, \vec{w}(t + 1), k(t))\), such that \(A(t + 1)_{11} = \tilde{A}(t + 1)\).

Suppose that \(i = k\). Then \(\tilde{w}_j(t) > \tilde{w}_k(t)\). Since \(\tilde{w}_k(t) = w_1(t) + w_k(t)\) and \(\tilde{w}_j(t) = w_j(t)\) (by Lemma 2.8), we can construct a permissible transformation of quadruples \((A(t), \vec{v}, \vec{w}(t), k(t))\) to \((A(t + 1), \vec{v}, \vec{w}(t + 1), k(t))\) by first performing the permissible column addition \(C_{kj}\) followed by the permissible column addition \(C_{1j}\). We have that \(A(t + 1)_{11} = \tilde{A}(t + 1)\).

Suppose that \(j = k\). Then \(\tilde{w}_k(t) > \tilde{w}_j(t)\).
If \( w_1(t) > w_i(t) \), then we define a permissible transformation of quadruples
\[
(A(t), \vec{v}, \vec{w}(t), k(t)) \rightarrow (A(t + 1), \vec{v}, \vec{w}(t + 1), k(t))
\]
by performing the permissible column addition \( C_{11} \).

Suppose that \( w_1(t) < w_i(t) \). If \((\vec{A}, \vec{v}, \vec{w})\) is the triple obtained from \((A(t), \vec{v}, \vec{w}(t))\) by \( C_{11} \), then we have that the \( i \)-th coefficient of \( \vec{w} \) is \( \vec{w}_i = w_i(t) - w_1(t) \). Since \( \vec{w}_k(t) > \vec{w}_i(t) \), we must have that \( w_1(t) + w_k(t) > w_i(t) \), which implies that \( \vec{w}_k(t) > \vec{w}_i(t) \). Thus we can construct a permissible transformation of quadruples
\[
(A(t), \vec{v}, \vec{w}(t), k(t)) \rightarrow (A(t + 1), \vec{v}, \vec{w}(t + 1), k(t + 1) = i)
\]
by first performing the permissible column addition \( C_{11} \) followed by the permissible column addition \( C_{ik} \). We have that \( A(t + 1)_{11} = A(t + 1) \).

We can thus inductively construct the sequence (2.5). Let \( k = k(s) \). Since \( C_k(s) = C_1(s) - 1 \), where \( C_k(s), C_1(s) \) are the \( k \)-th and first columns of \( A(s) \), the sequence of permissible row subtractions of (2.4) gives a sequence of permissible row subtractions \((A(s), \vec{v}, \vec{w}(s)) \rightarrow (A(l), \vec{v}(l), \vec{w}(s)) \) such that \( A(l) \) is a matrix, where \( A(l)_{11} \) is an identity matrix, \( a_{1k}(l) = a_{11}(tl) - 1 \), \( a_{kl}(l) = 1 \), and \( a_{i1}(l) = 0 \) if \( i \neq 1 \) and \( i \neq k \).

Now we perform the successive permissible row subtractions on \( A(l) \) of subtracting \( a_{i1}(l) - 1 \) times the \( k \)-th row from the first row, subtracting \( a_{1k}(l) \) times the \( i \)-th row from the first row for all \( i \neq k \), and finally subtracting the first row from the \( k \)-th row, to transform \( A(l) \) into the identity matrix. This completes the proof of Theorem 2.1.

We say that a column subtraction is permissible on \((A, \vec{v}, \vec{w})\) if it leaves the entries of \( A \) nonnegative. If we subtract the \( i \)-th column from the \( j \)-th column, then \( \vec{v} \) is unchanged, but the coefficient \( w_i \) of \( \vec{w} \) is added to \( w_j \). So as a corollary to Theorem 2.1, or by a simple modification of the proof of Theorem 2.1, we obtain:

**Theorem 2.9.** Suppose that \((A, \vec{v}, \vec{w})\) is a triple. Then there exists a sequence of permissible column additions and interchanges, followed by a sequence of permissible column subtractions, that transforms \( A \) to the identity matrix.

### 3. Local factorization of birational extensions

Suppose that \( R \) is a regular local ring with quotient field \( K \), and \( \nu \) is a valuation of \( K \), with valuation ring \( V \), such that \( V \) dominates \( R \) (\( R \subset V \) and the maximal ideal of \( V \) intersects \( R \) in its maximal ideal). A monoidal transform of \( R \) along \( \nu \) is a regular local ring \( R(1) \) such that \( R(1) = R[\frac{P}{f}]_{m} \), where \( P \) is a regular prime of \( R \), \( f \in P \) is such that \( \nu(f) = \min\{\nu(g) \mid g \in P\} \), and \( m = \{g \in R[\frac{L}{f}] \mid \nu(g) > 0\} \). We have that \( V \) dominates \( R(1) \) and \( R(1) \) dominates \( R \).
Theorem 3.1. Suppose that $k$ is a field, $k[x_1, \ldots, x_n]$, $k[y_1, \ldots, y_n]$ are polynomial rings and there exists a matrix $(a_{ij})$ of nonnegative integers satisfying
\[x_i = \prod_{j=1}^{n} y_j^{a_{ij}}\]
for $1 \leq i \leq n$ with $\text{Det}(a_{ij}) = \pm 1$. Let $R = k[x_1, \ldots, x_n](x_1, \ldots, x_n)$ and $S = k[y_1, \ldots, y_n](y_1, \ldots, y_n)$. Suppose that $\nu$ is a rank 1 valuation of $k(y_1, \ldots, y_n)$ with valuation ring $V$ which dominates $S$, such that $\nu(y_1), \ldots, \nu(y_n)$ are rationally independent. Then there exists a commutative diagram
\[
\begin{array}{ccc}
T & \nearrow & S \\
R & \rightarrow & \downarrow \\
\end{array}
\]
such that $T$ is a regular local ring dominated by $V$, and the northeast and northwest arrows are products of monoidal transforms along $\nu$.

Proof. Let $A = (a_{ij})$, $\vec{v} = (\nu(x_1), \ldots, \nu(x_n))^t$ and $\vec{w} = (\nu(y_1), \ldots, \nu(y_n))$. By Theorem 2.1, there exists a sequence of permissible column additions and row interchanges
\[
(A, \vec{v}, \vec{w}) \rightarrow (A(1), \vec{v}, \vec{w}(1)) \rightarrow \cdots \rightarrow (A(s), \vec{v}, \vec{w}(s))
\]
followed by a sequence of permissible row subtractions
\[
(A(s), \vec{v}, \vec{w}(s)) \rightarrow (A(s + 1), \vec{v}(s + 1), \vec{w}(s)) \rightarrow \cdots \rightarrow (A(t), \vec{v}(t), \vec{w}(t))
\]
such that $A(t)$ is the $n \times n$ identity matrix.

We will construct a diagram (3.1), in which the northwest arrow is a product of monoidal transforms along $\nu$,

\[
(3.2) \quad S \rightarrow S(1) \rightarrow \cdots \rightarrow S(s) = T,
\]
and the northeast arrow is a product of monoidal transforms along $\nu$

\[
(3.3) \quad R \rightarrow R(1) \rightarrow \cdots \rightarrow R(t - s) = T.
\]

We inductively construct (3.2), with a system of regular parameters $(y_1(l), \ldots, y_n(l))$ in each $S(l)$, so that $x_i = \prod_j y_j^{a_{ij}(l)}$ for $1 \leq i \leq n$, $\vec{v}(l) = (\nu(x_1(l)), \ldots, \nu(x_n(l)))^t = \vec{v}$ and $\vec{w}(l) = (\nu(y_1(l)), \ldots, \nu(y_n(l)))^t$ for $1 \leq l \leq s$.

Suppose that $A(l + 1)$ is obtained from $A(l)$ by the row interchange $T_{ij}$. We define $S(l + 1)$ to be $S(l)$, and we interchange the regular parameters $x_i$ and $x_j$ of $R$.

Suppose that $A(l + 1)$ is obtained from $A(l)$ by the permissible column addition $C_{ij}$. We define $S(l + 1)$ to be the local ring of the blow up of the
prime ideal \((y_i(l), y_j(l))\) which is dominated by \(V\). Since \(\nu(y_j(l)) > \nu(y_i(l))\), we have that
\[
S(l + 1) = S(l) \left[ \frac{y_j(l)}{y_i(l)} \right]_{(y_1(l+1), \ldots, y_n(l+1))},
\]
where
\[
y_k(l + 1) = \begin{cases} 
y_k(l) & \text{if } k \neq j \\
y_j(l) & \text{if } k = j
\end{cases}
\]
are regular parameters in \(S(l + 1)\).

We now inductively construct (3.3), with a system of regular parameters \((x_1(l), \ldots, x_n(l))\) in each \(R(l)\), so that \(x_i(l) = \prod_j y_j(s)^{a_{ij}(l+s)}\) for \(1 \leq i \leq n\), \(v(l + s) = (\nu(x_1(l)), \ldots, \nu(x_n(l)))\) and \(w(l + s) = (\nu(y_1(s)), \ldots, \nu(y_n(s)))\) for \(1 \leq l \leq t - s\).

Suppose that \(A(l + 1 + s)\) is obtained from \(A(l + s)\) by the permissible row subtraction \(R_{ji}\). We define \(R(l + 1)\) to be the local ring of the blow up of the prime ideal \((x_i(l), x_j(l))\) which is dominated by \(V\). Since \(x_i(l)\) divides \(x_j(l)\) in \(T\), we have that
\[
R(l + 1) = R(l) \left[ \frac{x_j(l)}{x_i(l)} \right]_{(x_1(l+1), \ldots, x_n(l+1))},
\]
where
\[
x_k(l + 1) = \begin{cases} 
x_k(l) & \text{if } k \neq j \\
x_j(l) & \text{if } k = j
\end{cases}
\]
are regular parameters in \(R(l + 1)\).

Since \(A(t) = Id\), we have that \(x_i(t - s) = y_i(s)\) for \(1 \leq i \leq n\), and thus \(T\) satisfies the conclusions of the theorem. \(\square\)

**Remark 3.2.** If \(S \to S(1)\) is a monoidal transform of a regular local ring \(S\), then \(S\) is called an inverse monoidal transform of \(S(1)\) (Chapter 6 of [C2]). With the notation of Theorem 3.1, a permissible column subtraction of \(A = (a_{ij})\) induces an inverse monoidal transform \(R \to S(1) \to S\) of \(S\). We can use Theorem 2.9, instead of Theorem 2.1, to prove Theorem 3.1. Theorem 2.9 proves the equivalent statement that a diagram (3.1) can be constructed, where the northwest arrow is factored by a sequence of inverse monoidal transforms from \(T\) to \(S\).

**Theorem 3.3.** Suppose that \(R \subset S\) are regular local rings, essentially of finite type over a field \(k\) of characteristic zero, with a common quotient field \(K\), such that \(S\) dominates \(R\). Let \(V\) be a valuation ring of \(K\) which dominates \(S\). Then there exists a regular local ring \(T\), with quotient field \(K\), such that \(T\)
dominates $S$, $V$ dominates $T$, and the inclusions $R \to T$ and $S \to T$ can be factored by sequences of monoidal transforms

$$
\begin{align*}
V & \xrightarrow{\phi} T \\
R & \xrightarrow{\phi} S
\end{align*}
$$

(3.4)

Proof. Let $r = \text{rank}(V)$. We can perform monoidal transforms on $R$ and $S$ so that the assumptions of [C2, Theorem 5.5] hold. By [C2, Theorem 5.5], there exists a commutative diagram of regular local rings

$$
\begin{align*}
R' & \to S' \\
\uparrow & \uparrow \\
R & \to S
\end{align*}
$$

such that $R'$, $S'$ have respective regular parameters $(z_1, \ldots, z_n)$, $(w_1, \ldots, w_n)$ satisfying the conclusions of [C2, Theorem 5.5]. In particular, there exists a matrix $a_{ij}$ such that $z_i = \prod_j w_j^{a_{ij}}$ for $1 \leq i \leq n$, where $A = (a_{ij})$ has the block form

$$
A = \begin{pmatrix}
G_1 & 0 \\
\text{Id} & G_2 \\
0 & \text{Id} \\
& & \ddots \\
& & & \text{Id} \\
& & & & G_r
\end{pmatrix}.
$$

Here, $G_i = (g_{jk}(i))$ is an $s_i \times s_i$ matrix of determinant $\pm 1$, so that we have

$$
z_{t_1+\cdots+t_{i-1}+1} = u_{t_1+\cdots+t_{i-1}+1}^{g_{11}(i)} \cdots u_{t_1+\cdots+t_{i-1}+1}^{g_{s_i}}
$$

for $1 \leq i \leq r$. We further have that $\nu(z_{t_1+\cdots+t_{i-1}+1}), \ldots, \nu(z_{t_1+\cdots+t_{i-1}+s_i})$ are rationally independent, and if $V_i = V \cap k(z_{t_1+\cdots+t_{i-1}+1}, \ldots, z_{t_1+\cdots+t_{i-1}+s_i})$, then $V_i$ has rank 1 (and rational rank $s_i$).

Let

$$
\begin{align*}
\mathcal{R}_i &= k[z_{t_1+\cdots+t_{i-1}+1}, \ldots, z_{t_1+\cdots+t_{i-1}+s_i}], \\
\mathcal{S}_i &= k[w_{t_1+\cdots+t_{i-1}+1}, \ldots, w_{t_1+\cdots+t_{i-1}+s_i}]
\end{align*}
$$

for $1 \leq i \leq r$. We further have that $\nu(z_{t_1+\cdots+t_{i-1}+1}), \ldots, \nu(z_{t_1+\cdots+t_{i-1}+s_i})$ are rationally independent, and if $V_i = V \cap k(z_{t_1+\cdots+t_{i-1}+1}, \ldots, z_{t_1+\cdots+t_{i-1}+s_i})$, then $V_i$ has rank 1 (and rational rank $s_i$).
By Theorem 3.1, there exists a regular local ring $\overline{T}_i$ which is dominated by $V_i$ and a commutative diagram

\[
\begin{array}{ccc}
V_i & \rightarrow & S_i \\
\uparrow & & \uparrow \\
\overline{T}_i & \rightarrow & \overline{R}_i
\end{array}
\]

such that the northeast and northwest arrows are products of monoidal transforms. By performing the corresponding sequences of monoidal transforms on $R'$ and $S'$ for $1 \leq i \leq r$, we obtain the conclusions of the theorem. □

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