Comparison of Type I Error of some Non-Parametric Tests on Multiple Regression Models Coefficients

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Abstract
Various non-parametric methods have been used to perform hypothesis test on multiple regression coefficients. In this article, at first the most important methods which has been introduced from other statisticians as proper methods, such as Kennedy, Freedman and Lane, and modified Kennedy, are explained and then, Freedman and Lane (Huh-John) method will be modified in the form of Kennedy method; finally, all aforementioned methods will be compared as simulating. At last, we look for a method that done best. So, Huh-John (2001) modify the method of Kennedy which was proposed in 1995 and showed by simulation that is called modified Huh-John method; and it has less type I error. On the other hand, Anderson as simulation (1991) and Schadrehk as theory (2011) had shown that Freedman& Lane method has lower type I error in comparison with Kennedy method. We did some modification on Freedman and Lane method that Huh-John had done on Kennedy method and compared this modified method with Freedman and Lane and Huh-John method. We conclude that Freedman and Lane modified method often has lower type I error estimation and higher power than Freedman& Lane and Huh-John method.

Keywords: Permutation tests; type I permutation error; changeability; multiple regression coefficient.
1. INTRODUCTION

When fundamental hypotheses to perform hypothesis test are not true on linear models regression coefficients, doing classic tests on regression coefficients will not give a reliable answer, so we should use non-parametric methods. One group of these tests is resampling tests including Jacknife, Botstape, and permutation tests. Since most of the time, fundamental hypotheses are not true on real data, so permutation tests attain significant place. There is an agreement among statisticians about linear simple regression for hypothesis test, but different methods have been proposed for multiple regression. Important methods that are based on Permutability principle include: Freedman and Lane (1983), Kennedy (1995), Manly (1991), Ter Bruak (1992). In 1999, Anderson and Legendr investigated four above methods by doing extensive simulation and showed that Freedman and Lane method and Kennedy method perform better than other. In 2010, Schaderch theoretically showed that Freedman and Lane method can perform better than Kennedy’s. Huh and John modified Kennedy method in 2001 and showed that Kennedy modified method has better performance than Kennedy. Schaderch in 2010 also showed that Freedman and Lane method is better than Huh and John. Now, our goal is to modify the method of Freedman Lane as the way that Huh and John has modified Kennedy method, as well as compare it by Freedman and Lane and Kennedy method as simulation.

2. Permutation test methods

In this section, we neglect the presence of missing data and we investigate only the modes have one dependant variable, and expand its results to multi-variable modes. The method that is identified appropriate for this mode will be proper to permutation methods with models having several dependant models. Here, for the ease of problem, we survey linear multiple regression model with two independent variables. We consider the following model for studying with two variables,

\[ y = \beta_0 + \beta_1 x_1 + \beta_2 x_2 + \varepsilon \]  

We use the following statistic for testing the hypothesis,

\[
\begin{align*}
H_0 : \beta_2 &= 0 \\
H_1 : \beta_2 &\neq 0
\end{align*}
\]

where \( S_{(b_2)} \) is the standard deviation of \( b_2 \).

2.1 Permutation of remaining under reduced model

Freedman and Lane utilized a model in which the value of remaining are used as permutable units. Assume a model in which \( H_0 : \beta_2 = 0 \) is true, so we can write model (1) under the title of “reduced model” as below:

\[ y = \beta_0 + \beta_1 x_1 + \varepsilon' \]  

It is evident that \( \beta_1' \) and \( \varepsilon' \) used in reduced model are different from \( \beta_1 \) and \( \varepsilon \) in complete model. There are two different methods for the use of remaining permutation in regression coefficient estimation. First method was proposed in 1983 by Freedman & Lane and the second one was in 1995 by Kennedy; we explain both here:

I) Proposed model by Freedman and Lane:

Make \( Y \) regression on \( X_1 \) and \( X_2 \), and estimate the value of \( b_2 \) for \( \beta_2 \) coefficient using minimum squares method. And by use of it, we obtain statistic \( t \) value for primary data. We call this statistic \( t_{Ref} \)

\[ t_{ref} = \frac{b_2}{S_{(b_2)}} \]

1) Make \( Y \) regression on \( X_1 \) variable as model (3), and obtain the estimation of \( b_0 \) for \( \beta_0 \) and \( b_1 \) for \( \beta_1 \); then we calculate \( \hat{Y} \):

2) Obtain the remaining as follow:

\[ R_{Y|X_1} = Y - \hat{Y} = Y - (b_0 + b_1 x_1) \]
Now we permute these remaining, and show them by \( R_{Y|X_1}^* \).

1) Add Permutated remaining to \( \hat{Y} \) in order to obtain new values of \( Y^* \). A considerable note here is, \( Y^* \) are not permutated values of \( Y \), but indicate the \( Y \) that are obtained from permutation of remaining.

\[
Y^* = \hat{Y} + R_{Y|X_1}^* \tag{5}
\]

2) Make the \( Y^* \) obtained from step 4 regression as the model below on both variables of \( X_1 \) and \( X_2 \).

\[
Y^* = \beta_0^* + \beta_1^* x_1 + \beta_2^* x_2 + \epsilon^* \tag{6}
\]

Finally obtain an estimation \( b_2^* \) for \( \beta_2^* \) and \( t^* \) for permutation data in the form of \( t_{ref}^* = \frac{b_2^*}{S(b_2^*)} \) with \( (n-2) \) freedom degree by using it.

1) Repeat steps 3 to 5 for \( n! \) Possible permutation in order to obtain value distribution of \( t^* \) under permutations.

2) Calculate absolute value of Ref as the method that was explained at the first of this chapter, and decide to accept or omit zero hypotheses.

II) Proposed method by Kennedy:

The steps of Kennedy method are as follow:

1) First 3 steps are done like Freedman and Lane method.

2) Calculate regression equation of \( X_2 \) variable on \( X_1 \) as the model below

\[
x_2 = \tau_0 + \tau_1 x_1 + \epsilon''
\]

and obtain remaining of \( R_{x_2|x_1} \) from estimation of \( X_2 \).

3) Make \( R_{Y|x_1}^* \) vector regression on variable of \( R_{x_2|x_1} \) under the following model

\[
R_{Y|x_1}^* = \beta_0 + \beta_1 R_{x_2|x_1} + \tilde{\epsilon}''
\]

and calculate \( b_1 \) estimation for \( \beta_1 \), and obtain \( t^* \) values from it by different permutation.

4) Repeat Steps 3 until 5 to obtain \( t^* \) value under permutation. (note that \( R_{x_2|x_1} \) obtained in Step 4 should be fixed.)

5) \( P \)-value is obtained like methods described.

3. Freedman and Lane method in multiple mode:

Consider the following regression model:

\[
Y = \beta_0 + \beta_1 x_{11} + \beta_2 x_{12} + \ldots + \beta_k x_{1k} + \epsilon_i
\]

Where errors are came from an independent random sample uni-distributed by zero mean and \( \sigma^2 \) variance. Explain individual test of regression coefficients. A regression coefficient which is considered for test is \( \beta_k \), and the goal of performing this test is Freedman and Lane method.

\[
\begin{aligned}
H_0: & \beta_k = 0 \\
H_1: & \beta_k \neq 0
\end{aligned}
\]

Rewrite equation (8) as matrix form:

\[
Y = X_1 \tilde{\beta}_1 + \tilde{X}_k \beta_k + \tilde{\epsilon} \sim F(0, \sigma^2 I_n)
\]

Where error terms have unspecified distribution \( F \) as above:
Indeed, separate the coefficient is considered for test from others, and assumes other coefficients as a vector. Now, we perform Freedman and Lane method as follow:

**Step 1)** We first obtain \( \hat{\beta}_k \) value and also \( t_{ref} \) statistic value from main data (non-permuted) of equation (11).

**Step 2)** Multiply both sides of the equation (11) by the following matrix:

\[
M_{X_k} = I_n - M_{X_k} (X_k^T X_k)^{-1} X_k^T
\]

The following relation is achieved from above operation:

\[
\hat{Y} = \hat{X}_k \hat{\beta}_k + \hat{e}_r
\]

Where

\[
\hat{X}_k = (I_n - H_k) X_k = M_{X_k} X_k \quad \text{and} \quad \hat{e}_r = (I_n - H_k) \hat{e} = M_{X_k} \hat{e}
\]

We know that \( M_{X_k} = I - H_k \) matrix is a symmetric and idempotent matrix. Furthermore, the matrix has the following feature:

\[
M_{X_k} X_k = 0
\]

By the use of minimum squares method, we estimate \( \beta_k \) coefficient as below:

\[
\hat{\beta}_k = \frac{\hat{X}_k^T \hat{Y}}{\hat{X}_k^T \hat{X}_k}
\]

By simplifying this term and regarding the symmetry and idempotency of \( M_{X_k} \), we have:

\[
\hat{\beta}_k = \frac{(M_{X_k} X_k)^T (M_{X_k} X_k) X_k M_{X_k} Y}{(M_{X_k} X_k)^T M_{X_k} X_k X_k} = \frac{X_k^T M_{X_k} Y}{X_k^T M_{X_k} X_k}
\]

Using \( \hat{\beta}_k \) estimation, \( \hat{Y} \) estimation is calculated and is called \( \bar{Y} \).

**Step 3)** Calculate the remaining of subtracting \( \bar{Y} \) from \( \hat{Y} \) and call it \( R_{\bar{Y} | X_k} \). Then, we permute these remaining and sowed them by \( R_{\bar{Y} | X_k} \).

**Step 4)** Add permuted remaining to \( \bar{Y} \) in order to obtain new values of \( \bar{Y}^* \). Then, we make them regress on \( X_1 \) and \( X_{k'} \), regression equation is in the form of below:

\[
\bar{Y}^* = \beta_1^* X_1 + \beta_k^* X_{k'} + \hat{e}^*
\]

We obtain estimator \( \beta_k^* \) by permuted data \( \bar{Y}^* \):

\[
\tilde{\beta}_k^* = \frac{\hat{\beta}_k^*}{\hat{e}^*}
\]

and by using it we obtain \( t^* = \tilde{\beta}_k^*/s(\tilde{\beta}_k^*) \).

**Step 5)** we repeat steps 3 and 4 and by using values of \( t^* \)s we obtain the distribution of permutation of \( t \)s and then \( p \)-value.

### 3.1 Criticism of the Freedman and Lane method
In Friedman and Lane’s approach from the reduced regression equation based on residuals about the null hypothesis, we
decided that we need to know the distribution of \( \tilde{e} \). This is a point that \( \tilde{e} \) in model (11) has an equal distribution with \( \tilde{e}^* \) but
the distribution of \( \tilde{e}^* \) in model (14) with the distribution of \( \tilde{e}^* \) is different.

### 3.2 Distribution of Errors and Compare them:

In multiple Friedman and Lane’s approach mean and variance of the error is as follows:

\[
E(\tilde{e}) = E((I_n H_1) \tilde{e}) = E(I_n H_1) E(\tilde{e}) = 0
\]

\[
V(\tilde{e}) = \text{Var}(I_n H_1) \tilde{e}) = (I_n H_1) \text{Var}(\tilde{e}) (I_n H_1) = \sigma^2 (I_n H_1) (I_n H_1) = \sigma^2 (I_n H_1)
\]

\[
\tilde{e} \sim F(0, \sigma^2 (I_n - H_1))
\]

Also in equation (14) we express the mean and variance of the error, now if we consider \( P \) as a permutation matrix, we have:

\[
\tilde{e}^* = P \tilde{e} \quad E(\tilde{e}^*) = E(P \tilde{e}) = PE(\tilde{e}) = 0
\]

\[
V(\tilde{e}^*) = V(P \tilde{e}) = p V(\tilde{e}) p^T = \sigma^2 I_n p^T = \sigma^2 I_n
\]

Therefore \( \tilde{e} \) and \( \tilde{e}^* \) are identically distribution. For comparing the distribution of \( \tilde{e} \) and \( \tilde{e}^* \) by using the permutation matrix we have:

\[
\tilde{e}^* = P \tilde{e} \quad E(\tilde{e}^*) = E(P \tilde{e}) = p E(\tilde{e}) = 0
\]

\[
V(\tilde{e}^*) = V(P \tilde{e}) = p V(\tilde{e}) p^T = p (\sigma^2 (I_n - H_1)) p^T = \sigma^2 p I_n p^T - p H_1 p^T = \sigma^2 (I_n - H_1^*)
\]

Considering the above term, we find that the variance of \( \tilde{e}^* \) is affiliated \( H_1^* \) so that by any permutation of \( H_1 \), \( \sigma^2 \) would
be multiply the new number and the variance would be change. Mean and variance \( \tilde{e} \) with \( \tilde{e}^* \) are not the same; as a result, their distribution is not equal. In view of the hypothesis \( \beta_k = 0 \) the distribution of \( \tilde{Y}^2 \) will be different from the
distribution of \( \tilde{Y} \). This is due to Friedman and Lane’s approach that is under doubt.

### 3.3 Modified Friedman and Lane method:

Error expressed in Friedman and Lane method was first in the Kennedy method that Huh and John gave a way to resolve
this problem; similarly we used this method to improve Friedman and Lane method. Considering that the matrix \( (I_n - H_1) \) is
an idempotent matrix with rank \( n^2 - n \) (where \( k \) is the number of independent variables in the model.) For Correcting
Friedman and Lane method the following steps will apply:

Step 1) Calculate eigenvectors of matrix \((I_n - H_1)\) and its rank.

Step 2) Consider eigenvectors corresponding to the eigenvalues of one that their number with rank \((I_n - H_1)\) is equivalent,
as a matrix.

Step 3) Using Gram-Schmidt method the above matrix is converted to a orthogonal matrix.

Step 4) Dividing each column by norm of that column it goes to a unit vector and resulting matrix will be represented by
\( W_1 \) that is an \((n \times n)\) orthogonal matrix so that has the following features:

\[
W_1^T W_1 = I_n
\]

Step 5) Since the eigenvalue of matrix \( W_1 \) is one and by using theory of Spectral Decomposition presented in index,
matrix \((I_n - H_1)\) is obtained

\[
(I_n - H_1) = W_1 W_1^T - W_1 W_1^T = W_1 W_1^T
\]

Step 6) Product \( W_1 \) in \( \tilde{Y} \) are \( \beta_k \) and \( \tilde{e} \) equation:

\[
\tilde{Y}_{n \times 1} = X_{n \times k} \beta_{k \times 1} \tilde{e}_{n \times 1}
\]
Where \( \tilde{Y} = W^T_1 \tilde{Y} \) \( \tilde{X}_k = W^T_1 \tilde{X}_k \) \( \tilde{e} = W^T_1 \tilde{e} \)

For mean and variance \( \tilde{e} \) we have:

\[
\begin{align*}
E(\tilde{e}) &= E(W^T_1 \tilde{e}) = W^T_1 E(\tilde{e}) = 0 \\
V(\tilde{e}) &= V(W^T_1 \tilde{e}) = W^T_1 V(\tilde{e}) W_1 = \sigma^2 W^T_1 (W_1 W^T_1) W_1 = \sigma^2 I_n \Rightarrow \tilde{e} \sim \mathcal{N}(0, \sigma^2 I_n)
\end{align*}
\]

(26)

To consider the distribution of permutated vector \( \tilde{e} \) namely \( \tilde{e}^* \), we use permutater matrix \( \rho \), therefore

\[
\begin{align*}
\tilde{e}^* &= \rho \tilde{e} \\
E(\tilde{e}^*) &= E(\rho \tilde{e}) = \rho E(\tilde{e}) = \rho E(\tilde{e}) = 0 \\
V(\tilde{e}) &= V(\rho \tilde{e}) = \rho V(\tilde{e}) \rho^T = \sigma^2 I_n \Rightarrow \tilde{e}^* \sim \mathcal{N}(0, \sigma^2 I_n)
\end{align*}
\]

(27)

So, \( \tilde{e} \) and \( \tilde{e}^* \) are identically distribution, in fact with this method distribution of the error terms after the permutation also are fixed, so by using new regression equation in the Freedman and Lane algorithm, this problem will disappear.

By using Sum Least Squares Error we obtain \( \tilde{\beta}_k \):

\[
\tilde{\beta}_k = (\tilde{X}_k^T \tilde{X}_k)^{-1} \tilde{X}_k^T \tilde{Y}
\]

(28)

Now we explain how we obtained the above estimation

\[
\tilde{X}_k^T \tilde{Y} = (W^T_1 \tilde{X}_k)^T \tilde{Y} = \tilde{X}_k^T W_1^T \tilde{Y} = \tilde{X}_k^T (I_n \tilde{H}_1) \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y}
\]

Where \( H_1 \tilde{Y} = H_1 Y - H_1 Y = 0 \)

Since \( H_1 \) is self-power we have

\[
\tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y} = \tilde{X}_k^T \tilde{Y}
\]

(29)

And also

\[
H_1 \tilde{X}_k = H_1 (I_n \tilde{H}_1) \tilde{X}_k = H_1 \tilde{X}_k = H_1 \tilde{X}_k = H_1 \tilde{X}_k = H_1 \tilde{X}_k = H_1 \tilde{X}_k = 0
\]

Therefore

\[
\tilde{\beta}_k = \frac{\tilde{X}_k^T \tilde{Y}}{\tilde{X}_k^T \tilde{X}_k} = \frac{\tilde{X}_k^T \tilde{Y}}{\tilde{X}_k^T \tilde{X}_k} = \tilde{\beta}_k
\]

(30)

\[
\tilde{Y}^* = \tilde{X}_k^T \tilde{\beta}_k + \tilde{e}^*
\]

(31)

So estimate \( \tilde{\beta}_k^* \) by least squares method is as follow

\[
\tilde{\beta}_k^* = \frac{\tilde{X}_k^T \tilde{Y}^*}{\tilde{X}_k^T \tilde{X}_k}
\]

(32)

Where \( \tilde{Y}^* \) is a \((n \times 1)\) vector that has obtained by random permutation \( \tilde{Y} \). Because of testing of null hypothesis we obtained all \( \tilde{\beta}_k^* \) s and \( t^* \) and then \( p \)-value, and decision whether hypothesis should be rejected or not.

4. Simulation
In this section we want to compare three methods: modified Kennedy (Huh and John), Freedman and Lane and modified Freedman and Lane. We investigate the result of simulation by using figures and programs exist in index written by S-PLUS software.

4.1. Simulation way:

For this purpose, we compute the estimation of type I error for all three permutation methods (Huh and John, Freedman and Lane, and modified Freedman and Lane) in terms of following 4 factors:

1- Sample size (n)
2- Correlation between two variables of $X_1$ and $X_2$ which is demonstrated by $\rho$
3- $\beta_k$ regression coefficient value which is not tested.
4- Error variable distribution

To perform simulation, we consider the values of random variable of $X_1$ and $X_2$ from three uniform distributions (-3, 3), exponential distribution with parameter 2, and Gama distribution with parameters 1 and 2 so that one of them is symmetric and two others are skew to the right. $Y$ vector is also generated through $Y=X\beta+\varepsilon$ where $X$ is a matrix that its columns are $X_1$ and $X_2$, and $\beta$ vector consist of the values of ($\beta_1$ and $\beta_2$). Since the goal of the test is the hypothesis of $H_0: \beta_2=0$, and regarding to the fact that, type I error is possible to deny zero hypothesis when it is true, thus we must assume zero hypothesis of $H_0: \beta_2=0$ true, then $\beta_1$ will adopt selective values of (0, 0.5, 1, 1.5, 2, 2.5).

The values of error term are also generated by three distribution of standard normal distribution, exponential distribution with parameter 2 (skew to the right), and uniform distribution (-3, 3). The correlation between two variables of $X_1$ and $X_2$ is obtained by using Choleski decomposition of correlation matrix $R_{2\times2}$, whose values on main diagonal are 1 and values on minor diagonal are $\rho$, which are here (0, 0.1 and 0.9). Therefore,

$$X_R=X\times R_C$$ (33)

Where $R_C$ is matrix that is achieved by Choleski decomposition of $R$, $X_R$ is also a matrix whose columns are consisted of $X_{1R}$ and $X_{2R}$ vectors, which are correlated to each other by $R$ and consistent with correlation coefficient of $\rho$. Finally, $Y$ vector is regenerated by using this matrix based on $Y=X_R\beta+\varepsilon$ model.

The estimation of type I errors at significance level of 0.05 is calculated by 1000 replication for 3 methods namely, Freedman and Lane, Huh and John, and modified Freedman and Lane. Calculation method of type I error for every type and every combination that is called experimental or permutation error is such that, we obtain the proportion of times that p- values are less than significance level of $\alpha=0.05$, and consider it as type I error estimation.

At the end, we compare the power of all three methods considering values of (0.5, 1, and 1.5) for parameter $\beta_2$. We prepare and simulate these programs in S-PLUS. Some of figures from simulation are in the below. It is sufficient to compare type I error and power of three methods in the following examples.
For investigating power of three mentioned methods we present some figures for $n=20$ and $30$:

I. $n=20$
II. \( n=30 \)
In total, every method that its type I error is close to $\alpha=0.05$ identified have been done better. Also, by using simulation we showed under reduced models, modified Freedman and Lane due to lower type I error and higher power is first choice and Freedman and Lane and Huh and John will be our next choice.

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INDEX (Simulation Programs)

These three algorithms for a bivariate regression model with the hypothesis test $\beta_2=0$ have been regulated and they have the capacity that for different values of sample size and correlation coefficient ($r$) can change. To determine these values we marked them by (*).

A. Kennedy's Algorithm

```r
alpha_matrix(nrow=1000,ncol=1)
for(i in 1:1000)
    x1_runif(n*,3,3)
x1_matrix(c(x1),ncol=1)
x2_runif(n*,3,3)
x2_matrix(c(x2),ncol=1)
x_matrix(c(x1,x2),ncol=2)
beta_matrix(c(beta*,0))
e_rexp(n*,2)
e_matrix(c(e),ncol=1)
r_matrix(c(1,r*,r*,1),ncol=2)
sr_chol(r)
xr_x%*%sr
y_(x)x%*%beta+e
reg_lm(y~x1+x2)
h_summary(reg)$coefficient
bref_h[3,1]
tref_h[3,3]
reg2_lm(y~x1)
x0_matrix(c(rep(1,n*),ncol=1))
x_matrix(c(x0,x1),ncol=2)
xt_t(x)
z_xt%*%x
zv_solve(z)
e_x%*%zv
h_e%*%xt
i_diag(n*)
mx_i
k_matrix(nrow=n*+1,ncol=1)
for(i in 1:1000)
    mxy_mx%*%y
    mxys_sample(mxy)
    mxx2_mx%*%x2
    reg3_lm(mxys~mxx2)
s_summary(reg2)$coefficient
```
t_s[2,3]
k[i]_t
k
}
kplus_abs(k)
k1_kplus[kplus>=tref]
k1_length(k1)
pvalue_k1/\textbf{1000}
pvalue
}
alpha_alpha[pvalue<0.05]
halpha_length(alpha)/1000
halpha

\textbf{B. Huh and John's Algorithm}

alpha_matrix(nrow=1000,ncol=1)
for(i in 1:1000){
x1_runif(n^*,3,3)
x1_matrix(c(x1),ncol=1)
x2_runif(n^*,3,3)
x2_matrix(c(x2),ncol=1)
x_matrix(c(x1,x2),ncol=2)
beta_matrix(c(\textbf{beta}^*,0))
e_rexp(n,2)
e_matrix(c(e),ncol=1)
r_matrix(c(1,r^*,r^*,1),ncol=2)
sr_chol(r)
\textbf{y}_x(e^{\textbf{beta}+e})
reg_lm(y~x1+x2)
h_summary(reg)$\text{coefficient}
bref_h[3,1]
tref_h[3,3]
reg2_lm(y~ x1)
x0_matrix(c(rep(1, n^*-1)),ncol=1)
x_matrix(c(x0,x1),ncol=2)
xt_t() x
z_xt%*%x
zv_solve(z)
e_x%*%zv
h_e%*%xt
i_diag(N)
m_x_i-h
m_matrix(c(mx),nrow=N)
d_eigen(m)$vectors
c_qr(d)$rank
c_d[1:k]
td_t(d)
v_matrix(nrow=N,nrow=k)
v[1:k]_d[1:k]
  for(i in 2:k){
    s_matrix(0, N, 1)
    for(j in 1:(k-1)){
      s_s+(t(v[j])%*%v[j])/((t(v[j])%*%v[j])*v[j])
    }
    v[,k]_d[k]=s
  }
  v
}
vn_matrix(nrow=N,nrow=k)
  for(i in 1:k){
    vn[i]_v[i]/sqrt(t(v[i])%*%v[i])
  }
  vn
  tvn_t(vn)
mxy_mx%*%y
ytildes_tvnn%*%mxy
mxx2_mx%*%x2
xtildes_tvnn%*%mxx2
k_matrix(nrow=N-1,nrow=1)
  for(i in 1:1000){
    ytildes_sample(ytildes)
    reg3_lm(ytildes~xtildes)
    s_summary(reg3)$coefficient
    t_s[2,3]
    k[i]_t
    k}
kplus_abs(k)
  k1_kplus[kplus>=tref]
  k2_length(k1)
pvalue_k2/1000
  pvalue}
C. Freedman and Lane’s Algorithm

alpha_matrix(nrow=1000,ncol=1)
for(i in 1:1000){
    x1_runif(n^*,-3,3)
    x1_matrix(c(x1),ncol=1)
    x2_runif(n^*,-3,3)
    x2_matrix(c(x2),ncol=1)
    x_matrix(c(x1,x2),ncol=2)
    beta_matrix(c(Beta^*,0))
    e_rexp(n^*,2)
    e_matrix(c(e),ncol=1)
    r_matrix(c(1,r^*,r^*,1),ncol=2)
    sr_chol(r)
    x_r=x%*%sr
    y_(x_r%*%beta)+e
    reg_lm(y~x1+x2)
    h_summary(reg)$coefficient
    bref_h[3,1]
    tref_h[3,3]
    reg2_lm(y~x1)
    x0_matrix(c(rep(1,n^*-1)),ncol=1)
    x_matrix(c(x0,x1),ncol=2)
    h1_summary(reg2)$coefficients
    b_h1[1,1]
    yhat_x=x%*%b
    k_matrix(nrow=,ncol=1)
    for(i in 2:1000){
        R_y-yhat
        Rs_sample(R)
        ys_yhat+Rs
        reg3_lm(ys~x1+x2)
        h2_summary(reg3)$coefficients
        t_h2[2,3]
        k[i]=t
    }
    kplus_abs(k)
    k1_kplus[kplus>=tref]
    k1i_length(k)
    pvaluei_k1i/1000
    pvalue
D. Modified Freedman and Lane’s Algorithm

```r
alpha_matrix(nrow=1000, ncol=1)
for(i in 1:1000){
x1_matrix(c(x1), ncol=1)
x2_matrix(c(x2), ncol=1)
x_matrix(c(x1, x2), ncol=2)
}

beta_matrix(c(Beta, 0))
e_norm(n^*, 0, 1)
e_matrix(c(e), ncol=1)
r_matrix(c(1, r^*, r^*, 1), ncol=2)
sr_chol(r)
xr_x%*%sr
y_(xr%*%beta)+e
reg_lm(y~x1+x2)
h_summary(reg)$coefficient
bref_h[3, 1]
tref_h[3, 1]
x0_matrix(c(rep(1, n^*−1)), ncol=1)
1
x_matrix(c(x0, x1), ncol=2)
x_t(x)
z_xt%*%x
zv_solve(z)
e_x%*%zv
h_e%*%xt
i_diag(n^*)
mx_i-h
m_matrix(c(mx), nrow=n^*)
d_eigen(m)$vector
k_qr(d)$rank
d_d[1:k]
td_t(d)
v_matrix(nrow=n^*, ncol=k)
v[1:k], d[1:k]
for(i in 1:k){
s_matrix(0, n^*, 1)
for(j in 1:(k-1)){
s_s+((v[j]%*%v[j])/(v[j]^2))^1/2
}
v[k, d[1:k]]=s
}
```

alpha_alpha[pvalue<0.05]
alpha_length(alpha)/1000
alpha_length

vn_matrix(nrow=N, ncol=k)
for(i in 1:k){
    vn[i]_v[i]/sqrt(t(v[i])%*%v[i])
}

tvn_t(vn)

mx = mx*y
ytilde = mv*x
mxx2 = mx*x2
xtilde2 = mv*x2
mxx1 = mx*x1
xtilde1 = mv*x1
reg2 = lm(ytilde ~ mxx1)

h1_summary(reg2)$coefficient
b = h1[,1]
yhat = x*b
k = matrix(nrow=1000, ncol=1)
for(i in 1:1000){
    R = ytilde-yhat
    Rtilde = sample(R)
    y = yhat+Rtilde
    reg3 = lm(y ~ xtilde1+xtilde2)
    h2_summary(reg3)$coefficients
    t = h2[3,3]
    k[i] = t
}
kplus = abs(k)
kplus[kplus>=t]
k_length(k)
pvalue = k/1000

alpha = pvalue<0.05
halpha = length(alpha)/1000
halpha