A Computational Procedure for solving a Non-Convex Multi-Objective Quadratic Programming under Fuzzy Environment

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The purpose of this paper is to study a non-convex fuzzy multi-objective quadratic programming problem, in which both the technological coefficients and resources are fuzzy with nonlinear membership function. A computational procedure to find a fuzzy efficient solution of this problem is developed. A numerical example is given to illustrate the procedure.

Keywords: Non-convex, Fuzzy multi-objective quadratic programming, nonlinear membership function, Fuzzy efficient solution.

1. Introduction
This paper studies the problem of maximizing a number of quadratic objective functions subject to linear and bound constraints under fuzzy environment:

\[(\text{NFMOQPP}) \quad \text{Max} \quad Z_1 = c_1^T x + \frac{1}{2} x^T Q_1 x \]
\[\text{Max} \quad Z_2 = c_2^T x + \frac{1}{2} x^T Q_2 x \]
\[\vdots \]
\[\text{Max} \quad Z_k = c_k^T x + \frac{1}{2} x^T Q_k x \]

Subject to \[x \in X = \{x \in \mathbb{R}^n : \tilde{A} x \leq \tilde{b}, \tilde{l} \leq x \leq \tilde{u}, x \geq 0\},\]

where \(c_q, q = 1, 2, \ldots k\) are n-dimensional cost vectors; \(Q_q, q = 1, 2, \ldots k\) are n \times n symmetric positive semi-definite matrices; \(\tilde{A}\) is the m \times n constraint fuzzy matrix of technological coefficients; \(\tilde{b}\) is the m-dimensional fuzzy resource vector, n-dimensional fuzzy vectors \(\tilde{l}\) and \(\tilde{u}\) are lower and upper bounds respectively on n-dimensional decision vector \(x\).

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Remark 1.1.  The problem (NFMOQPP) is a non-convex programming problem because $Q_q$, $q = 1, 2 \ldots k$ are assumed to be $n \times n$ symmetric positive semi-definite matrices and our problem is maximization.

In the literature section, a greater part of the study focused on convex programming problem; as in convex programming local optima is global optima but in case of non-convex programming local optima may not be global optima. Orden (1963) was the first one who considered the maximization of a non-concave quadratic programming. He derived the necessary and sufficient conditions for the maximization of non-concave quadratic programming. Ritter (1966) extended Orden’s work and gave a different approach to find the maximization of non-concave quadratic programming. Murty and Kabadi (1987) discussed that non-convex problem is an N-P Hard problem and it is very hard to get the global maxima. They have conferred that descent algorithms are quite practical algorithms for dealing with non-convex nonlinear problem. Hanson (1990) used generalized invexity to derive the necessary and sufficient conditions in non-convex quadratic programming for global minima. Ye (1992) applied the affine scaling algorithm to find the optimal solution for the non-convex quadratic programming. Burer and Vandenberguesche (2008) has developed a finite branch and bound algorithm for non-convex quadratic programming via semi definite relaxation. Chen and Burer (2011) extended the work of Burer and Vandenberguesche to get the global optima of non-convex problem with linear and bound constraints.

The purpose of this paper is to develop a computational procedure for more general non-convex quadratic problem similar to that of Chen and Burer (2011) and Orden (1963). They have focused on the single objective non-convex quadratic programming problem. But here in this paper, we have concentrated on the problem (NFMOQPP) in which instead of single objective we have taken multiple objectives which are fuzzified during the procedure in order to obtain the bounds on them; the crisp linear and bound constraints have been replaced by fuzzy linear and bound constraints.

In real world, the concept of decision-making takes place in an environment in which the objectives and constraints are not known precisely. Such situations can be tackled efficiently with the help of fuzzy set theory. Fuzzy sets were first introduced by Zadeh (1965). These sets were used to introduce the concept of decision-making in a fuzzy environment by Bellman and Zadeh (1970). They have defined appropriate aggregation of fuzzy sets for the fuzzy decision. Zimmermann (1978) has used fuzzy decision concept in the fuzzy linear programming for several objectives. Guu and Wu (1997) extended the Zimmermann’s approach to two-phase approach for solving the multi-objective linear programming in the fuzzy environment. Several authors have studied linear programming in the fuzzy environment and applied to real world problems like transportation, production planning etc. A fuzzy decision is based on the intersection of membership functions of the goals and constraints. Most of the authors have used linear membership functions as they are easy to tackle. Leberling (1981) has defined the hyperbolic membership function. Li and Lee (1991) have defined the exponential membership function and Yang, Ignizio and Kim (1991) have defined piecewise nonlinear membership function. In our paper, we have used trigonometric membership function in terms of sin, for objective functions and some of the constraints and used LINGO 9.0 to find the fuzzy efficient solution of (NFMOQPP).

The paper is organized as follows: Section 2 consists of preliminaries, which contain a useful definition and some basic membership functions of fuzzy technological coefficients and fuzzy resource vector; fuzzy efficient solution and nonlinear membership functions are described in Section 3; in Section 4, we have discussed the solution methodology for solving non-convex fuzzy multi-objective quadratic programming problem; and illustrative numerical example to explain the solution methodology is given in Section 5.
2. Preliminaries

In this section, we give a basic definition and membership functions corresponding to (NFMOQPP).

General form of Non-convex Multi-objective Quadratic Programming problem is given by

\[(\text{NMOQPP}) \quad \text{Max} \quad Z_1 \ x = c_1'x + \frac{1}{2} x'Q_1x
\]

\[\text{Max} \quad Z_2 \ x = c_2'x + \frac{1}{2} x'Q_2x
\]

\[\vdots
\]

\[\text{Max} \quad Z_k \ x = c_k'x + \frac{1}{2} x'Q_kx
\]

Subject to \( x \in X = \{x \in \mathbb{R}^n : Ax \leq b, x \geq 0\} \),

where \( c_q, q = 1, 2, \ldots k \) are \( n \)-dimensional cost vectors; \( Q_q, q = 1, 2, \ldots k \) are \( n \times n \) symmetric positive semi-definite matrices; \( A \) is the \( m \times n \) constraint matrix of technological coefficients; \( b \) is the \( m \)-dimensional resource vector and \( x \) is \( n \)-dimensional decision vector.

**Definition 2.1.** A point \( x^* \in X \) is said to be Pareto optimal solution of (NMOQPP) if there does not exist any \( x \in X \) such that

\[Z_q(x) \geq Z_q(x^*) \quad \forall \quad q = 1, 2, \ldots k \quad \text{and} \quad Z_r(x) > Z_r(x^*) \quad \text{for at least one} \quad r = 1, 2, \ldots k.
\]

In the problem (NFMOQPP), \( \tilde{A} \) is the \( m \times n \) constraint fuzzy matrix of technological coefficients; \( \tilde{b} \) is the \( m \)-dimensional fuzzy resource vector, \( \tilde{l} \) and \( \tilde{u} \) are \( n \)-dimensional fuzzy vectors and \( x \) is \( n \)-dimensional decision vector. Their membership functions are given as below:

1. **The membership function of \( \tilde{b} \):**

\[
\mu_{\tilde{b}}(y) = \begin{cases} 
1, & y \leq b_i \\
\frac{b_i + \rho_i - y}{\rho_i}, & b_i \leq y \leq b_i + \rho_i \\
0, & y \geq b_i + \rho_i 
\end{cases}
\]

where \( y \in \mathbb{R} \) and \( \rho_i > 0 \) is the tolerance level of \( b_i \) for all \( i = 1, 2 \ldots m \).

2. **The membership function of the fuzzy matrix \( \tilde{A} \):**

\[
\mu_{\tilde{A}}(y) = \begin{cases} 
1, & y \leq a_{ij} \\
\frac{a_{ij} + d_{ij} - y}{d_{ij}}, & a_{ij} \leq y \leq a_{ij} + d_{ij} \\
0, & y \geq a_{ij} + d_{ij} 
\end{cases}
\]

where \( y \in \mathbb{R} \) and \( d_{ij} > 0 \) is the tolerance level of \( a_{ij} \) for \( i = 1, 2 \ldots m \) and \( j = 1, 2 \ldots n \).
3. The membership function of $\tilde{u}$:

$$
\mu_{u}(y) = \begin{cases} 
1, & y \leq u_j \\
\frac{u_j + t_j - y}{t_j}, & u_j \leq y \leq u_j + t_j \\
0, & y \geq u_j + t_j 
\end{cases}
$$

(4)

where $y \in \mathbb{R}$ and $t_j > 0$ is the tolerance level of $u_j$ for all $j=1,2,\ldots,n$.

4. The membership function of $\tilde{l}$:

$$
\mu_{l}(y) = \begin{cases} 
1, & l_j \leq y \\
\frac{y - l_j + r_j}{r_j}, & l_j - r_j \leq y \leq l_j \\
0, & y \leq l_j - r_j 
\end{cases}
$$

(5)

where $y \in \mathbb{R}$ and $r_j > 0$ is the tolerance level of $l_j$ for all $j=1,2,\ldots,n$.

3. Fuzzy Efficient Solution

Werners (1987) has given a definition of fuzzy efficient solution for fuzzy multi-objective linear programming problem. As in our problem (NFMOQPP), the constraint set $X$ is described exclusively by fuzzy constraints, the varying degree of feasibility should be taken into account by consideration of efficient solutions, for additional dependencies between the individual goal values and the degree of membership to the region of feasible solutions can arise. That means we want to emphasize not only the achievement of maximum value of objective functions, but also the highest membership grade of fuzzy constraints in a flexible region. In order to take care of fuzzy concept, we will extend the definition of Werners to (NFMOQPP).

Let the constraint sets of (NFMOQPP) be denoted by

$C_i(x) = \{ x \in \mathbb{R}^n : \tilde{A}_i x \leq \tilde{b}_i \}, \quad i=1,2,\ldots,m$

$B_j(x) = \{ x \in \mathbb{R}^n : x_j \leq \tilde{u}_j \}, \quad j=1,2,\ldots,n$

$B'_j(x) = \{ x \in \mathbb{R}^n : x_j \geq \tilde{l}_j \}, \quad j=1,2,\ldots,n$

Define the trigonometric membership function of $i^{th}$ constraint $C_i(x)$ as:

$$
\mu_{C_i}(x) = \begin{cases} 
0, & b_i \leq \sum_{j=1}^{n} d_{ij} x_j \\
\sin \left( \frac{\left[ b_i - \sum_{j=1}^{n} a_{ij} x_j \right]}{\left[ \sum_{j=1}^{n} d_{ij} x_j + p_i \right]} \frac{\pi}{2} \right), & \sum_{j=1}^{n} a_{ij} x_j \leq b_i \leq \sum_{j=1}^{n} (a_{ij} + d_{ij}) x_j + p_i \\
1, & b_i \geq \sum_{j=1}^{n} (a_{ij} + d_{ij}) x_j + p_i 
\end{cases}
$$

(6)

where $x \in \mathbb{R}^n$ and $d_{ij} > 0$ and $p_i > 0$ are respectively the tolerance level of the technological coefficients and resources for $i=1,2,\ldots,m$ and $j=1,2,\ldots,n$. 



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This trigonometric membership function has the following properties:

1. \( \mu(C_i(x)) \) is a nonlinear and monotonically decreasing function.
2. \( 0 \leq \mu(C_i(x)) \leq 1 \ \forall \ x \in \mathbb{R}^n. \)
3. \( \mu(C_i(x)) \) is a concave function on the set \( \left\{ x \in \mathbb{R}^n : \sum_{j=1}^{n} a_{ij} x_j \leq b_i \right\}. \)

We define the linear membership function of the constraint \( B_j(x), j=1,2,...n \) as:

\[
\mu(B_j(x)) = \begin{cases} 
1 & x_j \leq u_j \\
\frac{u_j + t_j - x_j}{t_j} & u_j \leq x_j \leq u_j + t_j \\
0 & x_j \geq u_j + t_j 
\end{cases}
\]

(7)

where \( x \in \mathbb{R}^n \) and \( t_j > 0 \) is the tolerance level of \( u_j \).

Define the linear membership function of the constraint \( B'_j(x), j=1,2,...n \) as:

\[
\mu(B'_j(x)) = \begin{cases} 
1 & l_j \leq x_j \\
\frac{x_j - l_j + r_j}{r_j} & l_j - r_j \leq x_j \leq l_j \\
0 & l_j - r_j \geq x_j 
\end{cases}
\]

(8)

where \( x \in \mathbb{R}^n \) and \( r_j > 0 \) is the tolerance level of \( l_j \).

**Definition 3.1.** The point \( x^* \in X \) is said to be fuzzy efficient solution for the (NFMOQPP) if there does not exist any \( x \in X \) such that

\[
\begin{align*}
Z_q \ x & \geq Z_q(x^*) \ \forall \ q = 1,2,...k \ \text{and} \ \ C_i \ x & \geq C_i(x^*) \ \forall \ i = 1,2,...m \ \text{and} \\
B_j \ x & \geq B_j(x^*) \ \forall \ j = 1,2,...n \ \text{and} \ \ B'_j \ x & \geq B'_j(x^*) \ \forall \ j = 1,2,...n 
\end{align*}
\]

and

\[
\begin{align*}
\left[ Z_q \ x & > Z_q(x^*) \right. \ \text{for at least one} \ q = 1,2,...k \ \text{or} \ C_i \ x & > C_i(x^*) \ \text{for at least one} \ i = 1,2,...m \ \text{or} \\
\left. B_j \ x & > B_j(x^*) \right. \ \text{for at least one} \ j = 1,2,...n \ \text{or} \ B'_j \ x & > B'_j(x^*) \ \text{for at least one} \ j = 1,2,...n 
\end{align*}
\]

As mentioned in Werners (1987), similarly here, this definition takes into account that for a fuzzy efficient solution an improvement concerning an objective function can only be reached either at the expense of an additional objective function or at the expense of the membership into the constraints. In fact, we can easily see that the fuzzy efficiency defined above comprises the classical efficiency as special case if each of the \( \mu(C_i(x)), \mu(B_j(x)) \) and \( \mu(B'_j(x)) \) is 1 for each \( x \in C_i(x), x \in B_j(x) \) and \( x \in B'_j(x) \) respectively.

4. **Procedure to find a Fuzzy Efficient Solution**

Our objective functions are crisp and constraints are fuzzy in nature in (NFMOQPP). To defuzzificate the problem, we will first fuzzify the objective functions, which can be done by solving the following four quadratic programming problems
We have now four non-convex quadratic problems corresponding to the objective function $q^{th}$ ($q = 1, 2, \ldots, k$). They can be solved by using LINGO 9.0 to get the aspiration level for the $q^{th}$ objective function.

Now we take the best and worst value of the optimal solutions of the four non-convex quadratic programming problems.

Let $Z^L_q = \text{Min} (Z^1_q, Z^2_q, Z^3_q, Z^4_q)$ and $Z^U_q = \text{Max} (Z^1_q, Z^2_q, Z^3_q, Z^4_q)$, $q = 1, 2, \ldots, k$. (9)

Now taking the interval $[Z^L_q, Z^U_q]$ as the tolerance level interval for the $q^{th}$ objective ($q = 1, 2, \ldots, k$) in (NFMOQPP), we define the trigonometric membership function of the $q^{th}$ objective ($q = 1, 2, \ldots, k$) as:
\[ \mu_{Z_q}(x) = \begin{cases} 
0, & Z_q x \leq Z_q^L \\
n\left(\frac{Z_q x - Z_q^L}{Z_q^U - Z_q^L}\right)\frac{\pi}{2}, & Z_q^L < Z_q x \leq Z_q^U \\
1, & Z_q x > Z_q^U 
\end{cases} \] (10)

This trigonometric membership function has the following properties:

1. \( \mu(Z_q(x)) \) is a nonlinear and monotonically increasing function.
2. \( 0 \leq \mu(Z_q(x)) \leq 1 \) in \( [Z_q^L, Z_q^U] \).
3. \( \mu(Z_q(x)) \) is concave function in \( [Z_q^L, \infty) \).

Now, by using max-min fuzzy decision making approach given by Bellman and Zadeh (1970), we have

\[ \mu_D(x) = \min_{q,i,j} \mu_{Z_q}(x) \cdot \mu_{C_i}(x) \cdot \mu_{B_j}(x) \cdot \mu(B_j'(x)) \] (11)

Then, the optimal fuzzy decision is a solution of the problem

\[ \max_{x \geq 0} \mu_D(x) = \max_{x \geq 0} \left( \min_{q,i,j} (\mu(Z_q(x)) \cdot \mu(C_i(x)) \cdot \mu(B_j(x)) \cdot \mu(B_j'(x))) \right). \] (12)

The problem (12) is equivalent to the following problem as discussed by Zimmermann (1978)

\[ \text{(NPP)} \]

\begin{align*}
\text{Max} & \quad \lambda \\
\text{Subject to} \quad & \mu(Z_q(x)) \geq \lambda, \quad q = 1,2,\ldots,k \\
& \mu(C_i(x)) \geq \lambda, \quad i = 1,2,\ldots,m \\
& \mu(B_j(x)) \geq \lambda, \quad j = 1,2,\ldots,n \\
& \mu(B_j'(x)) \geq \lambda, \quad j = 1,2,\ldots,n \\
& 0 \leq \lambda \leq 1, \\
& x \geq 0.
\end{align*}

Now, the above problem is a nonlinear convex programming problem which can be solved by LINGO 9.0. Let \( (x^*, \lambda^*) \) be the optimal solution of the problem \( \text{(NPP)} \).

Now, by two phase method proposed by Guu and Wu (1997), we will solve the following nonlinear problem:

\[ \text{(NPP1)} \]

\begin{align*}
\text{Max} & \quad \sum_{q=1}^{k} \lambda_q + \sum_{i=1}^{m} \delta_i + \sum_{j=1}^{n} \theta_j + \sum_{j=1}^{n} \gamma_j \\
\text{Subject to} \quad & \mu_{Z_q}(x) \geq \lambda_q \geq \lambda^*, \quad q = 1,2,\ldots,k \\
& \mu_{C_i}(x) \geq \delta_i \geq \lambda^*, \quad i = 1,2,\ldots,m \\
& \mu_{B_j}(x) \geq \theta_j \geq \lambda^*, \quad j = 1,2,\ldots,n \\
& \mu_{B_j'}(x) \geq \gamma_j \geq \lambda^*, \\
& \lambda^* \leq \lambda_q, \delta_i, \theta_j, \gamma_j \leq 1, \\
& x \geq 0.
\end{align*}

We solve the above problem by LINGO 9.0. Let \( (x^*, \lambda^*, \delta^*, \theta^*, \gamma^*) \) where \( \lambda^* = (\lambda_1^*, \lambda_2^*, \ldots, \lambda_k^*) \), \( \delta^* = (\delta_1^*, \delta_2^*, \ldots, \delta_m^*) \), \( \theta^* = \theta_1^*, \theta_2^*, \ldots, \theta_n^* \) and \( \gamma^* = \gamma_1^*, \gamma_2^*, \ldots, \gamma_n^* \) be the optimal solution of \( \text{(NPP1)} \). Now we will prove that this optimal solution \( (x^*, \lambda^*, \delta^*, \theta^*, \gamma^*) \) gives the fuzzy efficient solution of \( \text{(NFMOQPP)} \).
Theorem 4.1. Let \((x^*, \lambda^*, \delta^*, \theta^*, \gamma^*)\) where \(\lambda^* = (\lambda_1^*, \lambda_2^*, \ldots, \lambda_k^*)\), \(\delta^* = (\delta_1^*, \delta_2^*, \ldots, \delta_m^*)\), \(\theta^* = (\theta_1^*, \theta_2^*, \ldots, \theta_n^*)\) and \(\gamma^* = (\gamma_1^*, \gamma_2^*, \ldots, \gamma_n^*)\) be the optimal solution of the problem \((NPP1)\), then \(x^*\) is the fuzzy efficient solution of the problem \((NFFMOQPP)\).

Proof: Let if possible, \(x^*\) be not a fuzzy efficient solution of \((NFFMOQPP)\), then there exist a \(y \in X\) such that

\[
\begin{align*}
Z_q y &\geq Z_q(x^*) \quad \forall q = 1, 2, \ldots, k \quad \text{and} \quad C_i y \geq C_i(x^*) \quad \forall i = 1, 2, \ldots, m \quad \text{and} \\
B_j y &\geq B_j(x^*) \quad \forall j = 1, 2, \ldots, n \\
\text{and} \quad Z_q y &> Z_q(x^*) \quad \text{for at least one } q = 1, 2, \ldots, k \\
\text{or} \quad C_i y &> C_i(x^*) \quad \text{for at least one } i = 1, 2, \ldots, m \\
\text{or} \quad B_j y &> B_j(x^*) \quad \text{for at least one } j = 1, 2, \ldots, n
\end{align*}
\]

As \(\mu(Z_q(.))\) is the increasing function

\[Z_q(y) \geq Z_q(x^*) \quad \Rightarrow \quad \mu(Z_q(y)) \geq \mu(Z_q(x^*)) \quad \text{for all } q = 1, 2, \ldots, k.\]

Since \((x^*, \lambda^*, \delta^*, \theta^*, \gamma^*)\) is the optimal solution and the coefficients in the objective function are positive in problem \((NPP1)\)

So, we have

\[
\begin{align*}
\lambda_q^* &= \mu Z_q x^* \quad q = 1, 2, \ldots, k \\
\delta_i^* &= \mu C_i x^* \quad i = 1, 2, \ldots, m \\
\theta_j^* &= \mu B_j(x^*) \quad j = 1, 2, \ldots, n \\
\gamma_j^* &= \mu B_j'(x^*) \quad j = 1, 2, \ldots, n
\end{align*}
\]

Now choosing,

\[
\lambda_q^* = \mu Z_q y \quad q = 1, 2, \ldots, k \\
\delta_i^* = \mu C_i y \quad i = 1, 2, \ldots, m \\
\theta_j^* = \mu B_j(y) \quad j = 1, 2, \ldots, n \\
\gamma_j^* = \mu B_j'(y) \quad j = 1, 2, \ldots, n
\]

As \((x^*, \lambda^*, \delta^*, \theta^*, \gamma^*)\) is the feasible solution of \((NPP1)\) so using inequalities (13) and property of \(\mu(Z_q(.))\), we get

\[
\begin{align*}
\mu Z_q y &\geq \mu Z_q x^* \quad \geq \lambda_q \geq \lambda^* \quad \text{q=1, 2, \ldots, k} \\
\mu C_i y &\geq \mu C_i x^* \quad \geq \delta_i \geq \delta^* \quad \text{i=1, 2, \ldots, m} \\
\mu(B_j(y)) &\geq \mu(B_j(x^*)) \quad \geq \theta_j \geq \theta^* \quad \text{j=1, 2, \ldots, n} \\
\mu(B_j'(y)) &\geq \mu(B_j'(x^*)) \quad \geq \gamma_j \geq \gamma^* \quad \text{j=1, 2, \ldots, n}
\end{align*}
\]

So, we can easily see that \((y, \lambda^*, \delta^*, \theta^*, \gamma^*)\), where \(\lambda^* = (\lambda_1^*, \lambda_2^*, \ldots, \lambda_k^*)\), \(\delta^* = (\delta_1^*, \delta_2^*, \ldots, \delta_m^*)\), \(\theta^* = (\theta_1^*, \theta_2^*, \ldots, \theta_n^*)\) \(\gamma^* = (\gamma_1^*, \gamma_2^*, \ldots, \gamma_n^*)\) is the feasible solution of \((NPP1)\).

As \((y, \lambda^*, \delta^*, \theta^*, \gamma^*)\) and \((x^*, \lambda^*, \delta^*, \theta^*, \lambda^*)\) are solutions of the problem \((NPP1)\) and using (13), we get
\[ \sum_{q=1}^{k} \lambda_q^y + \sum_{i=1}^{m} \delta_i^y + \sum_{j=1}^{n} \theta_j^y + \sum_{j=1}^{n} \gamma_j^y = \sum_{q=1}^{k} \mu(Z_q(y)) + \sum_{i=1}^{m} \mu(C_i(y)) + \sum_{j=1}^{n} \mu B_j(y) + \sum_{j=1}^{n} \mu B'_j(y) \]

\[ > \sum_{q=1}^{k} \mu(Z_q(x^o)) + \sum_{i=1}^{m} \mu(C_i(x^o)) + \sum_{j=1}^{n} \mu B_j x^o + \sum_{j=1}^{n} \mu B'_j x^o \]

\[ = \sum_{q=1}^{k} \lambda_q^x + \sum_{i=1}^{m} \delta_i^x + \sum_{j=1}^{n} \theta_j^x + \sum_{j=1}^{n} \gamma_j^x \]

This is a contradiction as \((x^o, \lambda^o, \delta^o, \theta^o, \lambda^o)\) is optimal solution of the problem (NPP1).

So \(x^o\) is the fuzzy efficient solution of (NFMOQPP).

\[ \Box \]

4.1 Computational Procedure

The ideas discussed above for finding fuzzy efficient solution of (NFMOQPP) can be summarized in the form of algorithm as given below.

**Step 1:**

Construct the four problems of the form (NQPP) \((j=1, 2, 3, 4)\) corresponding to \(q^{th}\) (q=1, 2, …, k) objective.

**Step 2:**

Solve them to get the aspiration level for the \(q^{th}\) (q=1, 2, …, k) objective.

**Step 3:**

Determine the aspiration level of the \(q^{th}\) (q = 1, 2, ….., k) objective by

\[ Z_q^u = \text{Max} \ Z_q^1, Z_q^2, Z_q^3, Z_q^4 \text{ and } Z_q^l = \text{Min} \ Z_q^1, Z_q^2, Z_q^3, Z_q^4 \quad \forall \ q = 1,2,....k. \]

**Step 4:**

Construct the trigonometric membership functions of the form (6) and (10) for the constraints and the objectives respectively. Also linear membership functions of the form (7) and (8) respectively for upper and lower values of \(x\).

**Step 5:**

Construct the problem (NPP) and solve it. Let \((X^*, \lambda^*)\) be the solution and \(\lambda^*\) be the optimal value.

**Step 6:**

Construct the problem (NPP1) and solve it. Let \((x^*, \lambda^*, \delta^*, \theta^*, \gamma^*)\) where \(\lambda^* = (\lambda_1^*, \lambda_2^*, ..., \lambda_m^*)\), \(\delta^* = (\delta_1^*, \delta_2^*, ..., \delta_m^*)\), \(\theta^* = \theta_1^*, \theta_2^*, ..., \theta_n^*\) and \(\gamma^* = \gamma_1^*, \gamma_2^*, ..., \gamma_n^*\) be the optimal solution. Then \(x^*\) is the fuzzy efficient solution of problem (NFMOQPP).

5. Illustrative Example

(NFMOQPP)

Max \(Z_1(x) = x_1 + 2x_2 + x_1^2 + 2x_2^2\)

Max \(Z_2 x = 4x_1 + 7x_2 + 2x_1^2 + 3x_2^2\)

Subject to \(\begin{align*}
\tilde{1}x_1 + \tilde{1}x_2 & \leq \tilde{10}, \\
\tilde{2}x_1 + \tilde{3}x_2 & \leq \tilde{25}, \\
\tilde{2} & \leq x_1 \leq \tilde{9}, \\
\tilde{2} & \leq x_2 \leq \tilde{8}, \\
x_1, x_2 & \geq 0.
\end{align*}\)
Here, \( A = (a_{ij}) = \begin{pmatrix} 1 & 1 \\ 2 & 3 \end{pmatrix}, \quad (d_{ij}) = \begin{pmatrix} 1 & 1 \\ 1 & 2 \end{pmatrix}, \quad (a_{ij} + d_{ij}) = \begin{pmatrix} 2 & 2 \\ 3 & 5 \end{pmatrix} \)

\( b = \begin{pmatrix} 10 \\ 25 \end{pmatrix}, \quad p = \begin{pmatrix} 5 \\ 10 \end{pmatrix}, \quad (b + p) = \begin{pmatrix} 15 \\ 35 \end{pmatrix}, \quad u = \begin{pmatrix} 9 \\ 8 \end{pmatrix}, \quad t = \begin{pmatrix} 3 \\ 2 \end{pmatrix}, \quad u + t = \begin{pmatrix} 12 \\ 10 \end{pmatrix}, \quad l = \begin{pmatrix} 2 \\ 2 \end{pmatrix}, \quad r = \begin{pmatrix} 1 \\ 1 \end{pmatrix}, \quad 1 - r = \begin{pmatrix} 1 \\ 1 \end{pmatrix} \)

**Computational Procedure:**

**Step1:**

Construction of the four problems of the form \((NQPP^q_j)\) (j = 1, 2, 3, 4) corresponding to \(q^{th}\) (q = 1, 2) objective as follows:

| \((NQPP^1_1)\) | \((NQPP^1_2)\) |
| --- | --- |
| \[ Z^1_1 = \text{Max} \ x_1 + 2x_2 + x_1^2 + 2x_2^2 \] | \[ Z^1_2 = \text{Max} \ 4x_1 + 7x_2 + 2x_1^2 + 3x_2^2 \] |
| Subject to \[ x_1 + x_2 \leq 10 \] | Subject to \[ x_1 + x_2 \leq 10 \] |
| \[ 2x_1 + 3x_2 \leq 25 \] | \[ 2x_1 + 3x_2 \leq 25 \] |
| \[ 2 \leq x_1 \leq 9 \] | \[ 2 \leq x_1 \leq 9 \] |
| \[ 2 \leq x_2 \leq 8 \] | \[ 2 \leq x_2 \leq 8 \] |
| \[ x_1, x_2 \geq 0 \] | \[ x_1, x_2 \geq 0 \] |

| \((NQPP^2_1)\) | \((NQPP^2_2)\) |
| --- | --- |
| \[ Z^2_1 = \text{Max} \ x_1 + 2x_2 + x_1^2 + 2x_2^2 \] | \[ Z^2_2 = \text{Max} \ 4x_1 + 7x_2 + 2x_1^2 + 3x_2^2 \] |
| Subject to \[ 2x_1 + 2x_2 \leq 10 \] | Subject to \[ 2x_1 + 2x_2 \leq 10 \] |
| \[ 3x_1 + 5x_2 \leq 25 \] | \[ 3x_1 + 5x_2 \leq 25 \] |
| \[ 1 \leq x_1 \leq 9 \] | \[ 1 \leq x_1 \leq 9 \] |
| \[ 1 \leq x_2 \leq 8 \] | \[ 1 \leq x_2 \leq 8 \] |
| \[ x_1, x_2 \geq 0 \] | \[ x_1, x_2 \geq 0 \] |

| \((NQPP^3_1)\) | \((NQPP^3_2)\) |
| --- | --- |
| \[ Z^3_1 = \text{Max} \ x_1 + 2x_2 + x_1^2 + 2x_2^2 \] | \[ Z^3_2 = \text{Max} \ 4x_1 + 7x_2 + 2x_1^2 + 3x_2^2 \] |
| Subject to \[ 2x_1 + 2x_2 \leq 15 \] | Subject to \[ 2x_1 + 2x_2 \leq 15 \] |
| \[ 3x_1 + 5x_2 \leq 35 \] | \[ 3x_1 + 5x_2 \leq 35 \] |
| \[ 1 \leq x_1 \leq 12 \] | \[ 1 \leq x_1 \leq 12 \] |
| \[ 1 \leq x_2 \leq 10 \] | \[ 1 \leq x_2 \leq 10 \] |
| \[ x_1, x_2 \geq 0 \] | \[ x_1, x_2 \geq 0 \] |

| \((NQPP^4_1)\) | \((NQPP^4_2)\) |
| --- | --- |
| \[ Z^4_1 = \text{Max} \ x_1 + 2x_2 + x_1^2 + 2x_2^2 \] | \[ Z^4_2 = \text{Max} \ 4x_1 + 7x_2 + 2x_1^2 + 3x_2^2 \] |
| Subject to \[ x_1 + x_2 \leq 15 \] | Subject to \[ x_1 + x_2 \leq 15 \] |
| \[ 2x_1 + 3x_2 \leq 35 \] | \[ 2x_1 + 3x_2 \leq 35 \] |
| \[ 2 \leq x_1 \leq 12 \] | \[ 2 \leq x_1 \leq 12 \] |
| \[ 2 \leq x_2 \leq 10 \] | \[ 2 \leq x_2 \leq 10 \] |
| \[ x_1, x_2 \geq 0 \] | \[ x_1, x_2 \geq 0 \] |

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Step 2:
Now by solving the above quadratic programming problems using LINGO 9.0, we get
\[ Z_1 = (Z_1^1, Z_1^2, Z_1^3, Z_1^4) = (118, 42, 96.72 \text{ and } 228.75) \]
\[ Z_2 = (Z_2^1, Z_2^2, Z_2^3, Z_2^4) = (212, 82, 173.68 \text{ and } 392.5) \]

Step 3:
Now using (9) for \( q = 1, 2 \), we get the interval \([Z^L_q, Z^U_q]\) as the aspiration level interval for the \( q^{th} \) objective \((q=1, 2)\) in \((NFMQQP)\) as
\[ [Z^L_1, Z^U_1] = [42, 228.75] \text{ and } [Z^L_2, Z^U_2] = [82, 392.5] \]

Step 4:
Construction of the membership functions of the form (6) to (8) and (10) for the constraints and objectives, as follows:

\[ \mu(C_1(x)) = \begin{cases} 0, & 10 \leq x_1 + x_2 \\ \sin \left( \frac{10 - x_1 - x_2}{x_1 + x_2 + 5} \right), & x_1 + x_2 \leq 10 \leq 2x_1 + 2x_2 + 5 \\ 1, & 10 \geq 2x_1 + 2x_2 + 5 \end{cases} \]

\[ \mu(C_2(x)) = \begin{cases} 0, & 25 \leq 2x_1 + 3x_2 \\ \sin \left( \frac{25 - 2x_1 - 3x_2}{x_1 + 2x_2 + 10} \right), & 2x_1 + 3x_2 \leq 25 \leq 3x_1 + 5x_2 + 10 \\ 1, & 25 \geq 3x_1 + 5x_2 + 10 \end{cases} \]

\[ \mu(B_1(x)) = \begin{cases} 1, & x_1 \leq 9 \\ \frac{12 - x_1}{3}, & 9 \leq x_1 \leq 12 \\ 0, & x_1 \geq 12 \end{cases} \]

\[ \mu(B_2(x)) = \begin{cases} 1, & x_2 \leq 8 \\ \frac{10 - x_2}{2}, & 8 \leq x_2 \leq 10 \\ 0, & x_2 \geq 10 \end{cases} \]

\[ \mu(B_1'(x)) = \begin{cases} 0, & x_1 \leq 1 \\ \frac{(x_1 - 1)}{1}, & 1 \leq x_1 \leq 2 \\ 1, & x_1 \geq 2 \end{cases} \]

\[ \mu(B_2'(x)) = \begin{cases} 0, & x_2 \leq 1 \\ \frac{(x_2 - 1)}{1}, & 1 \leq x_2 \leq 2 \\ 1, & x_2 \geq 2 \end{cases} \]
\[
\begin{align*}
\mu_{Z_1}(x) &= \begin{cases} 
0, & Z_1 \cdot x \leq 42 \\
\sin \left( \frac{Z_1 \cdot x - 42}{186.75} \pi \right), & 42 \leq Z_1 \cdot x \leq 228.75 \\
1, & Z_1 \cdot x \geq 228.75
\end{cases}, \\
\mu_{Z_2}(x) &= \begin{cases} 
0, & Z_2 \cdot x \leq 82 \\
\sin \left( \frac{Z_2 \cdot x - 82}{310.5} \pi \right), & 82 \leq Z_2 \cdot x \leq 392.5 \\
1, & Z_2 \cdot x \geq 392.5
\end{cases}.
\end{align*}
\]

From the graph drawn in figure 1 corresponding to the membership function \(\mu(C_1(x))\) we can observe that

1. \(\mu(C_1(x))\) is a nonlinear and monotonically decreasing function.
2. \(0 \leq \mu(C_1(x)) \leq 1 \ \forall \ x \in \mathbb{R}^n\).
3. \(\mu(C_1(x))\) is a concave function on the set \(x \in \mathbb{R}^n : x_1 \cdot x_2 \leq 10\).

Also from the graph drawn in figure 2 corresponding to the membership function \(\mu(Z_1(x))\) we can observe that

1. \(\mu(Z_1(x))\) is a nonlinear and monotonic increasing function.
2. \(0 \leq \mu(Z_1(x)) \leq 1 \ \forall \ x \in \mathbb{R}^n\).
3. \(\mu(Z_1(x))\) is concave function on the interval \(42, \infty\).

Similar properties can be observed for all other membership functions with the help of the graphs.

**Step 5:**

Now the problem (NPP) becomes
Max $\lambda$

Subject to
\[
\sin \left( \frac{x_1 + 2x_2 + x_1^2 + 2x_2^2 - 42}{186.75} \right) \geq \lambda,
\]
\[
\sin \left( \frac{4x_1 + 7x_2 + 2x_1^2 + 3x_2^2 - 82}{310.5} \right) \geq \lambda,
\]
\[
\sin \left( \frac{10 - x_1 - x_2}{x_1 + x_2 + 5} \right) \geq \lambda,
\]
\[
\sin \left( \frac{25 - 2x_1 - 3x_2}{x_1 + 2x_2 + 10} \right) \geq \lambda,
\]
\[
\left( \frac{12 - x_1}{3} \right) \geq \lambda,
\]
\[
\left( \frac{10 - x_2}{2} \right) \geq \lambda,
\]
\[
(x_1 - 1) \geq \lambda,
\]
\[
(x_2 - 1) \geq \lambda,
\]
\[
0 \leq \lambda \leq 1,
\]
\[
x_1, x_2 \geq 0.
\]

We solve the above nonlinear problem by LINGO 9.0. We get the optimal solution as ($\lambda^* = 0.3310024$, $x_1^* = 1.331002$, $x_2^* = 5.804374$).

**Step 6:**

Now construct the problem (NPP1) as follows:

Max $\lambda_1 + \lambda_2 + \delta_1 + \delta_2 + \theta_1 + \theta_2 + \gamma_1 + \gamma_2$

Subject to
\[
\sin \left( \frac{x_1 + 2x_2 + x_1^2 + 2x_2^2 - 42}{186.75} \right) \geq \lambda_1 \geq 0.3310024,
\]
\[
\sin \left( \frac{4x_1 + 7x_2 + 2x_1^2 + 3x_2^2 - 82}{310.5} \right) \geq \lambda_2 \geq 0.3310024,
\]
\[
\sin \left( \frac{10 - x_1 - x_2}{x_1 + x_2 + 5} \right) \geq \delta_1 \geq 0.3310024,
\]
\[
\sin \left( \frac{25 - 2x_1 - 3x_2}{x_1 + 2x_2 + 10} \right) \geq \delta_2 \geq 0.3310024,
\]
\[
\left( \frac{12 - x_1}{3} \right) \geq \theta_1 \geq 0.3310024,
\]
\[
\left( \frac{10 - x_2}{2} \right) \geq \theta_2 \geq 0.3310024,
\]
\[
(x_1 - 1) \geq \gamma_1 \geq 0.3310024.
\]
\[(x_2 - 1) \geq y_2 \geq 0.3310024, \]
\[0.3310024 \leq \lambda_1, \lambda_2, \delta_1, \delta_2, \theta_1, \theta_2, \gamma_1, \gamma_2 \leq 1, \]
\[x_1, x_2 \geq 0. \]

We solve the above problem (NPP1) by LINGO 9.0 and get the optimal values as \((\lambda_1^* = 0.3310024, \lambda_2^* = 0.3401065, \delta_1^* = 0.362496, \delta_2^* = 0.3310024, \theta_1^* = 1, \theta_2^* = 1, \gamma_1^* = 0.3310024, \gamma_2^* = 1)\). Hence the fuzzy efficient solution of the problem (NFMOQPP) is \(x_1^* = 1.3310024, \) and \(x_2^* = 5.804373\). The corresponding values of the objectives are \(Z_1(x^*) = 82.092806\) and \(Z_2(x^*) = 150.569993\).

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