Phase-noise Reduction Through an External High-Q Network Using a Black-Box Oscillator Model

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Abstract — A method is presented to minimize the phase noise of an existing oscillator when connected to an external high-Q network. It relies on the experimental extraction of a reduced-order model of the original free-running oscillator, which involves a characterization of its pulling effects. With this model it is possible to predict the solution curves, stability properties and phase-noise of the augmented oscillator. It enables the optimization of the high-Q network to maximize the phase-noise reduction at a stable operation point in a single valued section of the solution curve. The method has been applied to (VCO) Mini-Circuits ROS-3000-819+ (2-3GHz) obtaining a phase-noise reduction of about 10 dB with respect to the free-running values.

Keywords — oscillator, phase noise, dielectric resonator.

I. INTRODUCTION

Several works demonstrate the possibility to reduce the phase noise of an existing oscillator through the connection of a high-quality-factor (Q) network to its output port or as an additional feedback loop [1]-[4]. The advantage of this procedure is that no modification of the original oscillator design is needed since the high-Q network is introduced externally. However, the parameters of the added network must be designed judiciously. Otherwise, it can give rise to unstable behaviour, as demonstrated in [1]-[2]. Under the high Q required to achieve a significant phase-noise reduction, the added network exhibits a high frequency sensitivity and, as a result, is susceptible to give rise to multivalued curves when varying a parameter. Thus, the behaviour of the augmented oscillator must be accurately predicted to achieve a significant phase-noise reduction in a stable single-valued section of the solution curve. The method in [4] enables an optimization of the network parameters using a formulation based on a reduced-order model of the oscillator circuit. The external network should not significantly perturb the amplitude and frequency of this original oscillator, so the model is constituted by the derivatives of the admittance function of the oscillator circuit, calculated at its original free-running operation point. In [4], this oscillator model is extracted from harmonic-balance (HB) simulations at circuit level, applying finite differences to an auxiliary generator. However, if the oscillator is a commercial one, it will not be possible to simulate it in HB. On the other hand, if the oscillator is home-made but the models of its components are not reliable, the model extracted from HB will not be accurate enough.

In [5], a method was presented for the empirical extraction of an oscillator model using an injection-locking procedure. However, this model does not contain all the parameters required to predict the behavior of the oscillator augmented with a high-Q network. Here a different modelling procedure, based on the characterization of the oscillator pulling, is presented. This model will be applied to predict the solution curves, stability and phase noise of a commercial oscillator loaded with a high-Q network. The external networks in [4] contain slow-wave structures. Here the investigation will be extended to a high-Q network containing a dielectric resonator. This will enable a theoretical analysis of the effect of the Q factor, as well as a validation of the solution curves versus the continuous variation of a network parameter. The network will be tested on a Mini-Circuits ROS-3000-819+ VCO (2–3GHz). A second network containing a slow-wave structure [4], easier to integrate, will also be considered. Variations in the VCO frequency will be carried out, which will require the calculation of the oscillator model at different bias voltages.

II. AUGMENTED OSCILLATOR WITH AN EMPIRICAL MODEL

Let us consider an existing oscillator terminated in the load \( Y_o = 1/50 \text{ Ohm}^{-1} \). This load will be replaced with a one-port high-Q network having the input admittance \( Y_i(\omega) \) (Fig. 1). Then, the total admittance of the oscillator is [4]:

\[
Y_i(V, \omega) + (Y_i(\omega) - Y_o) = Y_i(V, \omega) + Y_o(\omega) = 0
\]

where \( Y_i(V, \omega) \) is the total admittance function of the original oscillator, fulfilling \( Y_i(V_o, \omega_o) = 0 \) at the free-running amplitude \( V_o \) and frequency \( \omega_o \), and \( Y_o(\omega) \) is the increment in the load admittance (with respect to \( Y_o \)), due to the introduction of the one-port network. This network should not significantly affect the original oscillation amplitude and frequency, so it will be possible to expand \( Y_i(V, \omega) \) in (1) in a first-order Taylor series about \( V_o, \omega_o \). Note that \( Y_o(\omega) \) is not expanded since, due to the high Q, a high frequency sensitivity is expected. Splitting (1) into real and imaginary parts, one obtains [4]:

\[
E(\omega) = \omega - \omega_o - \frac{\partial Y}{\partial \omega} \frac{Y_i'(\omega)}{\det_o} + \frac{\partial Y}{\partial V} \frac{Y_o(\omega)}{\det_o} = 0
\]

\[
V = V_o - \frac{\partial Y}{\partial \omega} \frac{Y_i'(\omega)}{\det_o} + \frac{\partial Y}{\partial V} \frac{Y_o(\omega)}{\det_o} \tag{2}
\]

where the derivatives are calculated at the free-running solution of the original oscillator circuit, \( r \) and \( i \) indicate real and imaginary parts, \( E(\omega) \) is an error function and \( \det_o \) is:
\[ \det \omega = \frac{\partial Y_o}{\partial \omega} \frac{\partial Y_L}{\partial \omega} - \frac{\partial Y_o}{\partial \omega} \frac{\partial Y_L}{\partial \omega} \]  

(3)

To predict the solution curves, one will need a reduced-order model constituted by the following quantities:

\[ \text{Osc model} = \left\{ \omega_o, V_o, \frac{\partial Y_L}{\partial \omega}, \frac{\partial Y_o}{\partial \omega} \right\} \]  

(4)

To solve (2) both the amplitude and phase of the two derivatives in (4) are required, unlike the situation in [5]. Once the numerical model is available, it will be introduced into (2) (a). Then, the solution curve can be easily obtained by (i) performing a linear simulation of the high-Q network (which can be an electromagnetic one) to calculate \( Y_2(\omega) \) and (ii) tracing the zero-error contour \( E(\omega) = 0 \).

\[ Y_4(\omega) = \frac{1}{\Delta} \left[ \begin{array}{c} \frac{\partial Y_o}{\partial \omega} \\ \frac{\partial Y_L}{\partial \omega} \\ \frac{\partial Y_o}{\partial \omega} \\ \frac{\partial Y_L}{\partial \omega} \end{array} \right] \]  

\[ \Delta = Y_4(\omega_o)Y_2(\omega_o) - Y_2(\omega_o)Y_4(\omega_o) \]  

The above procedure is automated with a load-pull measurement [6]. A sufficiently large number of points enables an evaluation of the consistency of the experimental results. To calculate \( \det \omega \), one can injection-lock the oscillator circuit, introducing an independent locking signal at the output port, where the high-Q network will be connected. For a small injection-current amplitude \( I_o \), the oscillator can be linearized about its steady-state solution [5]. The magnitude of the frequency derivative \( \frac{\partial Y}{\partial \omega} \) can be obtained from the locking bandwidth \( \Delta \omega_{\text{max}} \) as:

\[ \frac{\partial Y}{\partial \omega} = \frac{2I_o}{\varepsilon \Delta \omega_{\text{max}} \sin \alpha_{\omega}} \]  

(6)

where \( \alpha_{\omega} \) is the difference between the angle of \( \partial Y / \partial \omega \) and that of \( \partial Y / \partial V \), easily obtained from (5). Then, the quantity \( \det \omega \), which should be a positive scalar in a well behaved oscillator, is directly calculated combining (2) and (6). The procedure allows obtaining an empirical model of the standalone oscillator, shown in (4), which will be used to calculate the steady-state solution of the augmented oscillator [from (2)], as well as its stability and phase noise. The method has been applied to the (VCO) Mini-Circuits ROS-3000-819+ (2-3GHz). This particular oscillator is very convenient because, as reported in [7], it is unbuffered. Table I shows the model obtained when biasing the VCO at \( V_t = 2.45 \text{ V} \), which provides the free-running frequency \( f_o = 2.151 \text{ GHz} \).

| Parameter | Value |
|-----------|-------|
| \( V_o \) | 0.6 V |
| \( f_o \) | 2.15 GHz |
| \( \partial Y / \partial \omega \) | 7.69E-11 + 3.82E-10 i |
| \( \partial Y / \partial V \) | 0.1538 - 0.1995 i |

In the following, two different types of output network will be considered. The first one, containing a dielectric resonator coupled to a transmission line [Fig. 1(b)], will allow a simple experimental validation of the solution curves obtained when varying a network parameter in a continuous manner. Even though, in practice, other configurations may be more convenient, this one will allow getting analytical insight into the whole circuit behaviour. The second one [Fig. 1(c)] is based on a slow-wave structure, as in [4], where a home-made oscillator circuit and a model extracted from HB simulations are used.

### III. STRUCTURE WITH A DIELECTRIC RESONATOR

Initially, an analytical derivation of the oscillation frequency in the presence of a high-Q resonator will be carried out. For simplicity of this analytical derivation, the structure is made up of just dielectric resonator coupled to a transmission line [8]-[9]. From [8] the input reflection coefficient is:

\[ \Gamma = \frac{k\omega_o}{(k + 1)\omega_o + 2jQ(\omega - \omega_o)} e^{-j\phi/I} \]  

(7)

where \( k \) is the coupling factor, \( Q \) is the quality factor, \( \omega_o \) is the resonance frequency and \( I \) is the length of the transmission line from the input reference plane to the coupling point [8]. Using (7) to calculate \( Y_4 \) and replacing the resulting expression into (2) (a), the oscillation frequency can be calculated from:

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Table I. Oscillator model

| Parameter | Value |
|-----------|-------|
| \( V_o \) | 0.6 V |
| \( f_o \) | 2.15 GHz |
| \( \partial Y / \partial \omega \) | 7.69E-11 + 3.82E-10 i |
| \( \partial Y / \partial V \) | 0.1538 - 0.1995 i |
\[
\alpha (\omega - \omega_0) + 4Q^2 (\omega - \omega_0)^3 + \\
2Y_L \left( \frac{\partial Y_L}{\partial V} \gamma - \frac{\partial Y_L}{\partial V} \xi Q(\omega - \omega_0) \right) \sin \left( \frac{2\omega_l}{v} \right) = 0 \quad (8)
\]

where \( \gamma = (k+1)k\omega_0^2, \xi = 2k\omega_0, \alpha = (k+1)^2\omega_0^2, v = c/\sqrt{\varepsilon_{eff}} \).

As gathered from (8), when increasing Q, multivalued solutions in terms of the oscillation frequency \( \omega \) versus the length \( l \) can arise, and the frequency excursion decreases. The frequency \( \omega \) agrees with the free-running one at the \( l \) values (\( l_p \)) fulfilling:

\[
\tan \left( 2\omega_l / p / v \right) = -\frac{\partial Y_L}{\partial V} / \frac{\partial Y_L}{\partial V} \quad (9)
\]

Fig. 2 presents the variation of the oscillation frequency versus the length \( l \). The results of the approximate model are compared with those obtained with the numerical technique in (2)(a), based on a linear simulation of the output network (providing \( Y_L \)) with very good agreement. Fulfillment of (9) can be noted. Length values \( l_p \) in single- and multi-valued regions alternate Experimental measurements are also superimposed in Fig. 2. Note that in the theoretical curves \( Y_L \) is calculated either from (7) or through a linear simulation. It is not empirical, which justifies the small discrepancies.

Fig. 3. Detailed characterization of the discontinuous jump predicted in Fig. 2.

A detailed characterization of the first predicted discontinuous jump, with a much finer variation of the length \( l \), is presented in Fig. 3. The measurement has been performed by holding the spectral-line peak, while sliding the dielectric resonator along the transmission line.

Fig. 4. Stability and noise properties, using the empirical model. (a) Stability analysis versus \( l \). (b) Variation of the phase-noise spectral density at 10 kHz.

IV. PHASE-NOISE REDUCTION WITH SLOW-WAVE STRUCTURE

In a second experiment, the oscillator has been loaded with a one-port network containing a slow-wave structure in a reflection configuration [4]. The structure is based on a simple distributed implementation of the inductors and capacitors in a discrete transmission line [Fig. 1(c)] and provides a group delay of 3.1 ns at 2.45 GHz. Unlike the case in Section III (when using the dielectric resonator) it is not possible to vary any parameters of the slow-wave structure. Thus, the external network must be properly optimized to enable the phase-noise reduction at the desired oscillation frequency. Otherwise, the phase noise can even increase. Variations in the VCO bias voltage between desired oscillation frequency. Otherwise, the phase-noise reductions of about 10 dB have been achieved.

![Phase-noise spectrum at I = 83 mm. The spectrum is compared with the one obtained in free-running conditions.](image)

**CONCLUSIONS**

A method has been proposed to predict the phase-noise reduction of an existing oscillator, modeled as a black box, when connected to a high Q output network. The model is easily obtained from a characterization of the oscillator pulling effects. The capability to predict the solution curves versus a parameter of the external network has been tested using a dielectric resonator coupled to a transmission line. The relative simplicity of this load network has allowed an analytical derivation of the solution curves, which become multivalued for some parameter intervals. Then, a slow-wave structure has been used, considering variations in the oscillator bias voltage.

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