The Approximate Variation of Univariate Uniform Space Valued Functions and Pointwise Selection Principles

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Abstract—Given a Hausdorff uniform space $X$ with the countable gage of pseudometrics of the uniformity of $X$, we introduce a concept of the approximate variation of a function $f$ mapping a subset $T$ of the reals into $X$: this is the infimum of the family of Jordan-type variations of all functions $g : T \rightarrow X$ which differ from $f$ in each uniform pseudometric, generated by a pseudometric from the gage, not greater than $\varepsilon > 0$. We prove the following compactness theorem in the topology of pointwise convergence: if a pointwise relatively sequentially compact sequence of functions is such that the limit superior of its approximate variations is finite for all pseudometrics in the gage and all $\varepsilon > 0$, then it contains a subsequence which converges pointwise on the domain $T$ to a bounded regulated function (in a generalized sense). We illustrate this result by appropriate sharp examples and present a new characterization of uniform space valued regulated functions in terms of the approximate variation.

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1. INTRODUCTION

The historically first extensions of Bolzano–Weierstrass' theorem (viz., a bounded sequence in $\mathbb{R}$ admits a convergent subsequence) are two theorems of Helly [23] (cf. also [24, II.8.9–10], [28, VIII.4.2]) for real monotone functions and for functions of bounded (Jordan) variation on $I = [a, b]$, conventionally called Helly's selection principles. Their significant role in analysis and topology is well-known ([18], [24], [26], [28], [31]). A vast literature already exists concerning generalizations of Helly's principles for various classes of functions ([5–8], [11], [14–16], [21], [27], and references therein, mostly for metric space valued functions) as well as their applications in the theory of convergence of Fourier series, stochastic processes, Riemann- and Lebesgue–Stieltjes integrals, optimization, set-valued analysis, generalized ODEs, modular analysis ([2], [3], [5], [7], [11], [12], [17], [25], [30]).

The latter series of references above exhibits also an important role played by regulated functions in various areas of mathematics. Classically, a function $f : I = [a, b] \rightarrow \mathbb{R}$ is said to be regulated provided the left limit $f(t - 0) \in \mathbb{R}$ exists at each point $a < t \leq b$ and the right limit $f(t + 0) \in \mathbb{R}$ exists at each point $a \leq t < b$. It is well known that each regulated function on $I$ is bounded, has at most a countable set of discontinuity points, and is the uniform limit of a sequence of step functions on $I$. Furthermore, there are different descriptions of regulated real and metric space valued functions ([2], [5], [8], [9], [11], [14], [16], [18], [19], [21], [22], [25], [27], [29], [32], [33]).

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1) We recall Helly's selection principle for monotone functions in Section 4.
2) In Section 2, we adopt a more general definition of regulated functions.
There is an explicit indication in the literature (e.g., [13], [16]) of a certain conjunction of ‘characterizations of regulated functions’ and ‘pointwise selection principles’. It can be formulated (heuristically, at present) as follows: if we have a characterization of regulated functions in certain terms, then, in the same terms, we may obtain a (Helly-type) pointwise selection principle, possibly outside the scope of regulated functions. This is demonstrated by the main results of this paper, Theorems 1 and 2, as well.

The class of uniform spaces is ‘situated’ properly between the class of metric spaces and the class of topological spaces ([4], [26]). Applications of uniform spaces outside topology seem to be not numerous (e.g., [9], [10], [32], [33]), and the most important of them being to topological groups ([1], [4]). However, since uniform spaces can be described in terms of their gages of pseudometrics (see [26] and Section 2), they form natural codomains (= ranges) for regulated functions and sequences of functions in selection principles. In fact, we may define oscillations of functions, uniform pseudometrics, bounded functions, functions of bounded (Jordan) variation and regulated functions with respect to pseudometrics from the gage, pointwise and uniform convergences of sequences of functions valued in a uniform space.

The purpose of this paper is to present a new characterization of a uniform space valued univariate regulated functions and, on the basis of it, establish a pointwise selection principle in terms of the (new notion of) approximate variation for uniform space valued sequences of univariate functions. Further comments on the novelty of our results can be found in Section 2.

The paper is organized as follows. In Section 2, we present necessary definitions and our main results, Theorems 1 and 2. In Section 3, we establish essential properties of the approximate variation (Lemmas 1 and 2), prove Theorem 1, and present illustrating examples including Dirichlet’s function. In Section 4, we prove Theorem 2, show that its main assumption (2.2) is necessary for the uniform convergence, but not necessary for the pointwise convergence of sequences of functions, and comment on the applicability of Theorem 2 to sequences of non-regulated functions.

2. DEFINITIONS AND MAIN RESULTS

We begin by reviewing certain definitions and facts needed for our results.

Throughout the paper we assume (if not stated otherwise) that the pair \((X, \mathcal{U})\) is a Hausdorff uniform space with the gage of pseudometrics \(\{d_p\}_{p \in \mathcal{P}}\) (on \(X\)) of the uniformity \(\mathcal{U}\) for some index set \(\mathcal{P}\) (cf. [26, Chapter 6]). For the reader’s convenience, we describe this assumption in more detail (see (I)–(IV) below).

(I) Given \(p \in \mathcal{P}\), the function \(d_p : X \times X \to [0, \infty)\) is a pseudometric on \(X\), i.e., for all \(x, y, z \in X\), it satisfies the three conditions: \(d_p(x, x) = 0\), \(d_p(y, x) = d_p(y, x)\), and \(d_p(x, y) \leq d_p(x, z) + d_p(z, y)\) (triangle inequality).

(II) The family \(\{d_p\}_{p \in \mathcal{P}}\) of pseudometrics on \(X\) is the gage of the uniformity \(\mathcal{U}\) for \(X\) if \(\{d_p\}_{p \in \mathcal{P}}\) is the family of all pseudometrics which are uniformly continuous on \(X \times X\) relative to the product uniformity derived from \(\mathcal{U}\). Recall ([26, Theorem 6.11]) that a pseudometric \(d\) on \(X\) is uniformly continuous on \(X \times X\) relative to the product uniformity if and only if the set \(\{(x, y) \in X \times X : d(x, y) < \varepsilon\}\) belongs to \(\mathcal{U}\) for all \(\varepsilon > 0\). The uniform space \((X, \mathcal{U})\) is said to be Hausdorff if conditions \(x, y \in X\) and \(d_p(x, y) = 0\) for all \(p \in \mathcal{P}\) imply \(x = y\).

(III) Every family \(\mathcal{F}\) of pseudometrics on \(X\) generates a uniformity \(\mathcal{U}\) (by [26, Theorem 6.15]). A direct description of the gage \(\{d_p\}_{p \in \mathcal{P}}\) of \(\mathcal{U}\) generated by \(\mathcal{F}\) is as follows ([26, Theorem 6.18]): the family \(\{U(d, \varepsilon) : d \in \mathcal{F}\) and \(\varepsilon > 0\}\) is a subbase for the uniformity \(\mathcal{U}\); thus, given a pseudometric \(d\) on \(X\), \(d \in \{d_p\}_{p \in \mathcal{P}}\) if and only if, for each \(\varepsilon > 0\), there are \(\delta > 0\), \(n \in \mathbb{N}\) and \(p_1, \ldots, p_n \in \mathcal{P}\) such that \(\bigcap_{i=1}^{n} U(d_p, \delta) \subset U(d, \varepsilon)\). Furthermore ([26, Theorem 6.19]), if \(\{d_p\}_{p \in \mathcal{P}}\) is the gage of \(\mathcal{U}\), then the family \(\{U(d_p, \varepsilon) : p \in \mathcal{P}\) and \(\varepsilon > 0\}\) is a base for the uniformity \(\mathcal{U}\) (i.e., for every \(U \in \mathcal{U}\) there are \(p \in \mathcal{P}\) and \(\varepsilon > 0\) such that \(U(d_p, \varepsilon) \subset U\)).

(IV) “Each concept which is based on the notion of a uniformity can be described in terms of a gage because each uniformity is completely determined by its gage” (cf. [26, Theorem 6.19]).

A particular case of a uniform space is a metric space \((X, d)\) with metric \(d\). The standard base of the uniformity \(\mathcal{U}\) for \(X\) is the family \(\{U(d, \varepsilon) : \varepsilon > 0\}\), where \(U(d, \varepsilon)\) is as in (II). The uniformity \(\mathcal{U}\) has a countable base, e.g., the family \(\{U(d, 1/k) : k \in \mathbb{N}\}\). Two more examples are in order. First, the family \(\{U_\alpha : \alpha \in \mathbb{R}\}\) with \(U_\alpha = \{(x, y) \in \mathbb{R} \times \mathbb{R} : x = y\) or \(x > \alpha, y > \alpha\}\) is a base of a uniformity on...
for all quantity (e.g., [6], [10], [31], [32]) the family of all $f$ of all $f$ with the convention that $p$ where the supremum is taken over all partitions on $X$. For more examples, we refer to [4, 20, 26, 34].

For the sake of brevity, we often write $X$ in place of $(X, \mathcal{U})$.

Given a nonempty set $T$ (in what follows, $T \subset \mathbb{R}$), we denote by $X^T$ the family of all functions $f : T \to X$ mapping $T$ into $X$ and equip it with (extended-valued) uniform pseudometrics

$$d_{T,p}(f,g) = \sup_{t \in T} d_p(f(t), g(t)), \quad f, g \in X^T, \quad p \in \mathcal{P}.$$ 

For $p \in \mathcal{P}$, the oscillation of $f \in X^T$ with respect to pseudometric $d_p$ is the quantity

$$|f(T)|_p = \sup_{s,t \in T} d_p(f(s), f(t)) \in [0, \infty],$$

also known as the $d_p$-diameter of the image $f(T) = \{f(t) : t \in T\} \subset X$. We denote by $B_p(T; X) = \{f \in X^T : |f(T)|_p < \infty\}$ the family of all $d_p$-bounded functions, and by $B(T; X) = \bigcap_{p \in \mathcal{P}} B_p(T; X)$ — the family of all bounded functions mapping $T$ into $X$.

Recall that a sequence of points $\{x_j\} = \{x_j\}_{j=1}^\infty \subset X$ converges in the uniform space $X$ to an element $x \in X$ (as $j \to \infty$) if and only if $d_p(x_j, x) \to 0$ as $j \to \infty$ for all $p \in \mathcal{P}$. Since $X$ is Hausdorff, the limit $x$ is determined uniquely. A subset $Y$ of the uniform space $X$ is said to be sequentially compact (relatively sequentially compact) if each sequence of points from $Y$ has a subsequence which converges in $X$ to an element of $Y$ (to an element of $X$, respectively).

Suppose we have a sequence of functions $\{f_j\} \equiv \{f_j\}_{j=1}^\infty \subset X^T$ and $f \in X^T$. If $p \in \mathcal{P}$, we write: (a) $f_j \to_p f$ on $T$ if $d_p(f_j(t), f(t)) \to 0$ as $j \to \infty$ for all $t \in T$, and (b) $f_j \Rightarrow_p f$ on $T$ if $d_{T,p}(f_j, f) \to 0$ as $j \to \infty$. We denote by: (c) $f_j \to f$ on $T$ the pointwise (or everywhere) convergence of $\{f_j\}$ to $f$, i.e., $f_j \to f$ on $T$ for all $p \in \mathcal{P}$, and (d) $f_j \Rightarrow f$ on $T$ the uniform convergence of $\{f_j\}$ to $f$, i.e., $f_j \Rightarrow f$ on $T$ for all $p \in \mathcal{P}$. Clearly, (d) implies (c), but not vice versa.

A sequence of functions $\{f_j\} \subset X^T$ is said to be pointwise relatively sequentially compact on $T$ if the set $Y = \{f_j(t) : j \in \mathbb{N}\}$ is relatively sequentially compact in $X$ for all $t \in T$.

From now on, we assume that $T$ is a nonempty subset of the reals $\mathbb{R}$.

Given $f \in X^T$ and $p \in \mathcal{P}$, the (Jordan-type) variation of $f$ with respect to pseudometric $d_p$ is the quantity (e.g., [6], [10], [31], [32])

$$V_p(f, T) = \sup_\pi \sum_{i=1}^m d_p(f(t_i), f(t_{i-1})) \in [0, \infty],$$

where the supremum is taken over all partitions $\pi$ of $T$, i.e., $m \in \mathbb{N}$ and $\pi = \{t_i\}_{i=0}^m \subset T$ such that $t_{i-1} \leq t_i$ for all $i = 1, 2, \ldots, m$. We denote by $BV_p(T; X) = \{f \in X^T : V_p(f, T) < \infty\}$ the family of all functions from $T$ into $X$ of bounded $d_p$-variation, and by $BV(T; X) = \bigcap_{p \in \mathcal{P}} BV_p(T; X)$ — the family of all functions of bounded variation (or BV functions, for short).

The following definition is crucial for the whole subsequent material.

**Definition 1.** The approximate variation of a function $f \in X^T$ is the two-parameter family $\{V_{\varepsilon}(f, T) : \varepsilon > 0, p \in \mathcal{P}\} \subset [0, \infty]$ of $\varepsilon$-$d_p$-variations $V_{\varepsilon,p}(f, T)$ of $f$, given for $\varepsilon > 0$ and $p \in \mathcal{P}$, by

$$V_{\varepsilon,p}(f, T) = \inf \{V_p(g, T) : g \in BV_p(T; X) \text{ and } d_{T,p}(f, g) \leq \varepsilon\} \quad (2.1)$$

with the convention that $\inf \emptyset = \infty$.

The notion of $\varepsilon$-variation $V_\varepsilon(f, T)$ of a function $f \in X^T$ with $T = [a, b]$ a closed interval in $\mathbb{R}$ and $X = \mathbb{R}^N$ was introduced by Fraňková [21, Definition 3.2]. For any $T \subset \mathbb{R}$ and a metric space $(X, d)$, this notion was considered and extended by the authors in [14, Sections 4 and 6], and the corresponding approximate variation was thoroughly studied by the first author in [13] (in particular, Example 3.10 from [13] shows that the infimum in (2.1) is in general not attained). The notion of $\varepsilon$-variation was also generalized by the authors for metric space valued bivariate functions in [15].
The notion of the approximate variation is useful in characterizing regulated metric space valued functions in the usual sense ([13], [14], [21]). For our purposes, we adopt the following more general definition.

Given \( p \in \mathcal{P} \), a function \( f \in X^T \) is said to be \( d_p \)-regulated on \( T \) (in symbols, \( f \in \text{Reg}_p(T; X) \)) if it satisfies the \( d_p \)-Cauchy conditions at every left limit point of \( T \) and every right limit point of \( T \). More explicitly, given \( \tau \in T \), which is a left limit point for \( T \) (i.e., \( T \cap (\tau - \delta, \tau) \neq \emptyset \) for all \( \delta > 0 \)), we have \( d_p(f(s), f(t)) \to 0 \) as \( T \ni s, t \to \tau \to 0 \), and similarly, given \( \tau' \in T \), which is a right limit point for \( T \) (i.e., \( T \cap (\tau', \tau' + \delta) \neq \emptyset \) for all \( \delta > 0 \)), we have \( d_p(f(s), f(t)) \to 0 \) as \( T \ni s, t \to \tau' \to 0 \).

A function \( f \in X^T \) is said to be regulated on \( T \) if it is \( d_p \)-regulated on \( T \) for all \( p \in \mathcal{P} \). We set \( \text{Reg}(T; X) = \bigcap_{p \in \mathcal{P}} \text{Reg}_p(T; X) \). It is to be noted that a regulated function need not be bounded in general (for instance, the function \( f \in \mathbb{R}^T \), given on the set \( T = [0, 1] \cup \{2 - (1/n) : n = 2, 3, \ldots \} \) by \( f(t) = t \) for \( 0 \leq t \leq 1 \) and \( f(2 - (1/n)) = n \) for \( n = 2, 3, \ldots \), is regulated on \( T \) in the above sense, but not bounded).

In the case when \( T = I = [a, b] \) is a closed interval in \( \mathbb{R} \) and \( X \) is complete we have: \( f \in \text{Reg}(I; X) \) if and only if the (left) limit of \( f(t) \) as \( t \to \tau - 0 \) exists in \( X \) at each point \( \tau \in (a, b) \) and the (right) limit of \( f(t) \) as \( t \to \tau' + 0 \) exists in \( X \) at each point \( \tau' \in [a, b) \) (cf. [10, Section 4]).

Our first result is a characterization of regulated functions in terms of the approximate variation (containing similar results from [14, equality (4.2)] and [21, Proposition 3.4] as particular cases):

**Theorem 1.** Suppose \( \emptyset \neq T \subset \mathbb{R} \) and \((X, \mathcal{U})\) is a Hausdorff uniform space. Given \( p \in \mathcal{P} \),

\[
\{f \in X^T : V_{\varepsilon, p}(f, T) < \infty \text{ for all } \varepsilon > 0\} \subset \text{Reg}_p(T; X),
\]

and this inclusion turns into the equality for \( T = I = [a, b] \). Consequently,

\[
\text{Reg}(I; X) = \{f \in X^I : V_{\varepsilon, p}(f, I) < \infty \text{ for all } \varepsilon > 0 \text{ and } p \in \mathcal{P}\}.
\]

As it was already mentioned in the Introduction, there is a relationship between ‘characterizations of regulated functions’ and ‘pointwise selection principles’. The second main result is a pointwise selection principle for uniform space valued functions in terms of the approximate variation:

**Theorem 2.** Suppose \( \emptyset \neq T \subset \mathbb{R} \) and \((X, \mathcal{U})\) is a Hausdorff uniform space with the at most countable gage of pseudometrics \( \{d_p\}_{p \in \mathcal{P}} \) of the uniformity \( \mathcal{U} \). If \( \{f_j\} \subset X^T \) is a pointwise relatively sequentially compact sequence of functions on \( T \) such that

\[
\limsup_{j \to \infty} V_{\varepsilon, p}(f_j, T) < \infty \text{ for all } \varepsilon > 0 \text{ and } p \in \mathcal{P},
\]

then there is a subsequence of \( \{f_j\} \) which converges pointwise on \( T \) to a function \( f \in X^T \) belonging to \( \text{B}(T; X) \cap \text{Reg}(T; X) \).

The novelty of this theorem is threefold. First, functions \( f_j \) take their values in a uniform space, which (as it was seen earlier) is more general than a metric space. Second, condition (2.2) is necessary for uniformly convergent sequences \( \{f_j\} \) (but not for pointwise convergent sequences \( \{f_j\} \)). Third, Theorem 2 may be applied to sequences \( \{f_j\} \) of non-regulated functions. These issues are addressed in Section 4.

3. **PROPERTIES OF THE APPROXIMATE VARIATION**

3.1. **Bounded functions and functions of bounded variation**

Given \( f, g \in X^T \), \( s, t \in T \), and \( p \in \mathcal{P} \), by the triangle inequality for \( d_p \), we find

\[
d_{T, p}(f, g) \leq |f(T)|_p + d_p(f(t), g(t)) + |g(T)|_p
\]

and

\[
d_p(f(s), f(t)) \leq d_p(g(s), g(t)) + 2d_{T, p}(f, g)
\]

and so, the definition of the \( d_p \)-oscillation and (3.2) imply

\[
|f(T)|_p \leq |g(T)|_p + 2d_{T, p}(f, g).
\]
By (3.1) and (3.3), we have $d_{T,p}(f,g) < \infty$ for all $f, g \in B_p(T; X)$ with $p \in P$ and, given a constant function $c \in X^T$, $B_p(T; X) = \{ f \in X^T : d_{T,p}(f,c) < \infty \}$ for all $p \in P$, and so, the family of bounded functions is equal to $B(T; X) = \{ f \in X^T : d_{T,p}(f,c) < \infty \}$ for all $p \in P$. Clearly,

$$|f(T)|_p \leq V_p(f,T) \quad \text{for all } f \in X^T \text{ and } p \in P, \quad (3.4)$$

and so, $BV_{p}(T; X) \subset B_{p}(T; X)$ and $BV(T; X) \subset B(T; X)$.

Given $f \in X^T$ and $p \in P$, the functional $V_p(\cdot, \cdot)$ has the following two properties: (i) additivity of $V_p(f, \cdot)$ in the second variable (cf. [6], [12]):

$$V_p(f,T) = V_p(f,T \cap (-\infty, t]) + V_p(f,T \cap [t, \infty)) \quad \text{for all } t \in T; \quad (3.5)$$

(ii) sequential lower semicontinuity of $V_p(\cdot, T)$ in the first variable (cf. [10]):

$$\text{if } \{f_j\} \subset X^T \text{ and } f_j \to f \text{ on } T, \text{ then } V_p(f,T) \leq \liminf_{j \to \infty} V_p(f_j,T). \quad (3.6)$$

### 3.2. The approximate variation

The essential properties of the approximate variation are gathered in

**Lemma 1** Given $f \in X^T$ and $p \in P$, we have:

(a) the function $\varepsilon \mapsto V_{\varepsilon,p}(f,T)$, mapping $(0, \infty)$ into $[0, \infty]$, is nonincreasing on $(0, \infty)$, and so,

$$V_{\varepsilon+0,p}(f,T) \leq V_{\varepsilon,p}(f,T) \leq V_{\varepsilon-0,p}(f,T) \quad \text{for all } \varepsilon > 0; \quad (3.4)^3$$

(b) if $\varnothing \neq T_1 \subset T_2 \subset T$ and $\varepsilon > 0$, then $V_{\varepsilon,p}(f,T_1) \leq V_{\varepsilon,p}(f,T_2)$;

(c) $\lim_{\varepsilon \to 0} V_{\varepsilon,p}(f,T) = \sup_{\varepsilon > 0} V_{\varepsilon,p}(f,T) = V_p(f,T)$$;

(d) $|f(T)|_p \leq V_{\varepsilon,p}(f,T) + 2\varepsilon$ for all $\varepsilon > 0$;

(e) if $\varepsilon > 0$, $t \in T$, $T^-_t = T \cap (-\infty, t]$ and $T^+_t = T \cap [t, \infty)$, then

$$V_{\varepsilon,p}(f,T^-_t) + V_{\varepsilon,p}(f,T^+_t) \leq V_{\varepsilon,p}(f,T) \leq V_{\varepsilon,p}(f,T^-_t) + V_{\varepsilon,p}(f,T^+_t) + 2\varepsilon.$$

**Proof.** (a) Suppose $0 < \varepsilon_1 < \varepsilon_2$. If $g \in X^T$ and $d_{T,p}(f,g) \leq \varepsilon_1$, then $d_{T,p}(f,g) \leq \varepsilon_2$, and so, Definition 1 implies $V_{\varepsilon_2,p}(f,T) \leq V_{\varepsilon_1,p}(f,T)$.

(b) Since $T_1 \subset T_2$, we have $d_{T_1,p}(f,g) \leq d_{T_2,p}(f,g)$ for all $g \in X^T$, whence, by Definition 1, $V_{\varepsilon,p}(f,T_1) \leq V_{\varepsilon,p}(f,T_2)$.

(c) By (a), the quantity $C_p = \lim_{\varepsilon \to 0} V_{\varepsilon,p}(f,T)$, which actually is equal to $\sup_{\varepsilon > 0} V_{\varepsilon,p}(f,T)$, is well-defined in $[0, \infty]$. Assume first that $f \in BV_{p}(T; X)$. By (2.1), $V_{\varepsilon,p}(f,T) \leq V_p(f,T)$ for all $\varepsilon > 0$, and so, $C_p \leq V_p(f,T) < \infty$. To prove the reverse inequality, we apply the definition of $C_p$: for every $\eta > 0$ there is $\delta = \delta(\eta) > 0$ such that $V_{\varepsilon,p}(f,T) \leq C_p + \eta$ for all $\varepsilon \in (0, \delta)$. If $\{\varepsilon_k\}_{k=1}^{\infty}$ is a sequence in $(0, \delta)$ such that $\varepsilon_k \to 0$ as $k \to \infty$, then, for every $k \in \mathbb{N}$, the definition of $V_{\varepsilon_k,p}(f,T)$ yields the existence of $g_k \in BV_{p}(T; X)$ such that $d_{T,p}(f,g_k) \leq \varepsilon_k$ and $V_p(g_k,T) \leq C_p + \eta$. Since $\varepsilon_k \to 0$, $g_k \equiv f$ on $T$, hence $g_k \to f$ on $T$, and so, by (3.6),

$$V_p(f,T) \leq \liminf_{k \to \infty} V_p(g_k,T) \leq C_p + \eta.$$

By the arbitrariness of $\eta > 0$, $V_p(f,T) \leq C_p$. Thus, $C_p$ and $V_p(f,T)$ are finite or not finite simultaneously, and $C_p = V_p(f,T)$, which proves (c).

(d) We may assume that $\varepsilon > 0$ is such that $V_{\varepsilon,p}(f,T)$ is finite. By definition (2.1), given $\eta > 0$, there is $g = g_\eta \in BV_{p}(T; X)$ such that $d_{T,p}(f,g) \leq \varepsilon$ and $V_p(g,T) \leq V_{\varepsilon,p}(f,T) + \eta$. Now, (3.3) and (3.4) imply

$$|f(T)|_p \leq |g(T)|_p + 2d_{T,p}(f,g) \leq V_p(g,T) + 2\varepsilon \leq V_{\varepsilon,p}(f,T) + \eta + 2\varepsilon.$$  

3\footnote{As usual, $V_{\varepsilon+0,p}(f,T)$ and $V_{\varepsilon-0,p}(f,T)$ are the limits from the right and from the left of the function $\varepsilon \mapsto V_{\varepsilon,p}(f,T)$, respectively.}
and the inequality in (d) follows due to the arbitrariness of $\eta > 0$.

(e) First, we prove the left-hand side inequality, in which we may assume that $V_{\varepsilon, p}(f, T)$ is finite. By definition (2.1), for every $\eta > 0$ there is $g = g_\eta \in BV_p(T; X)$ such that $d_{T, p}(f, g) \leq \varepsilon$ and $V_p(g, T) \leq V_{\varepsilon, p}(f, T) + \eta$. We set $g^-(s) = g(s)$ for $s \in T^-$ and $g^+(s) = g(s)$ for $s \in T^+$, and note that $g^-(t) = g^+(t)$. Since $g^- \in BV_p(T^-; X)$, $g^+ \in BV_p(T^+; X)$,

$$d_{T^-}(f, g^-) \leq d_{T, p}(f, g) \leq \varepsilon \quad \text{and} \quad d_{T^+}(f, g^+) \leq d_{T, p}(f, g) \leq \varepsilon,$$

definition (2.1) implies $V_{\varepsilon, p}(f, T^-) \leq V_p(g^-, T^-)$ and $V_{\varepsilon, p}(f, T^+) \leq V_p(g^+, T^+)$, and so, by the additivity property (3.5), we find

$$V_{\varepsilon, p}(f, T^-) + V_{\varepsilon, p}(f, T^+) \leq V_p(g^-, T^-) + V_p(g^+, T^+) = V_p(g, T^-) + V_p(g, T^+)$$

$$= V_p(g, T) \leq V_{\varepsilon, p}(f, T) + \eta \quad \text{for all} \ \eta > 0.$$

This establishes the left-hand side inequality.

In order to prove the right-hand side inequality, we may assume that $V_{\varepsilon, p}(f, T^-)$ and $V_{\varepsilon, p}(f, T^+)$ are finite. Note that if $T^- = \{ t \}$, then $T^+ = T$, and if $T^+ = \{ t \}$, then $T^- = T$; in both these cases the inequality is clear. Assume that $T^- \neq \{ t \}$ and $T^+ \neq \{ t \}$, so that $T \cap (-\infty, t) \cap (t, \infty)$ are nonempty. By definition (2.1), for every $\eta^- > 0$ and $\eta^+ > 0$ there are $g^- \in BV_p(T^-; X)$ and $g^+ \in BV_p(T^+; X)$ with properties: $d_{T^-}(f, g^-) \leq \varepsilon$, $d_{T^+}(f, g^+) \leq \varepsilon$, $V_p(g^-, T^-) \leq V_{\varepsilon, p}(f, T^-) + \eta^-$, and $V_p(g^+, T^+) \leq V_{\varepsilon, p}(f, T^+) + \eta^+$. Given $x \in X$ (to be specified below), we define $g \in BV_p(T; X)$ by

$$g(s) = \begin{cases} 
g^-(s) & \text{if} \ s \in T \cap (-\infty, t), \\
x & \text{if} \ s = t, \\
g^+(s) & \text{if} \ s \in T \cap (t, \infty). \end{cases}$$

Suppose that the following two inequalities are already established:

$$V_p(g, T^-) \leq V_p(g^-, T^-) + d_p(g(t), g^-(t)) \quad (3.7)$$

and

$$V_p(g, T^+) \leq V_p(g^+, T^+) + d_p(g(t), g^+(t)). \quad (3.8)$$

By the additivity property (3.5) of $V_p(\cdot, \cdot)$, these inequalities imply

$$V_p(g, T) = V_p(g, T^-) + V_p(g, T^+)$$

$$\leq V_{\varepsilon, p}(f, T^-) + \eta^- + d_p(x, g^-(t)) + V_{\varepsilon, p}(f, T^+) + \eta^+ + d_p(x, g^+(t)).$$

Now, we put $x = g^-(t)$ (by symmetry, we may have put $x = g^+(t)$ as well). Since $g = g^-$ on $T^-$ and $g = g^+$ on $T \cap (t, \infty) \subset T^+$, we get

$$d_{T, p}(f, g) \leq \max\{d_{T^-}(f, g^-), d_{T^+}(f, g^+)\} \leq \varepsilon. \quad (3.10)$$

Noting that (cf. (3.9))

$$d_p(x, g^+(t)) = d_p(g^-(t), g^+(t)) \leq d_p(g^-(t), f(t)) + d_p(f(t), g^+(t))$$

$$\leq d_{T^-}(f, g^-) + d_{T^+}(f, g^+) \leq \varepsilon + \varepsilon = 2\varepsilon,$$

we conclude from (2.1), (3.9), and (3.10) that

$$V_{\varepsilon, p}(f, T) \leq V_p(g, T) \leq V_{\varepsilon, p}(f, T^-) + \eta^- + V_{\varepsilon, p}(f, T^+) + \eta^+ + 2\varepsilon,$$

and the inequality in (e) follows due to the arbitrariness of $\eta^- > 0$ and $\eta^+ > 0$. 

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It remains to establish (3.7) (since (3.8) is similar). Let \( \{t_i\}_{i=0}^m \subset T_t^- \) be a partition of \( T_t^- \), i.e., \( t_0 \leq t_1 \leq \ldots \leq t_{m-1} < t_m = t \). Since \( g(s) = g^-(s) \) for all \( s \in T \) with \( s < t \), we have
\[
\sum_{i=1}^m d_p(g(t_i), g(t_{i-1})) = \sum_{i=1}^{m-1} d_p(g(t_i), g(t_{i-1})) + d_p(g(t_m), g(t_{m-1}))
\]
\[
= \sum_{i=1}^{m-1} d_p(g^-(t_i), g^-(t_{i-1})) + d_p(g^-(t_m), g^-(t_{m-1}))
\]
\[
+ d_p(g^+(t_m), g^+(t_{m-1})),
\]
where the last inequality is due to the triangle inequality for \( d_p \). Taking the supremum over all partitions of \( T_t^- \), we obtain inequality (3.7).

**Remark 1.** Inequalities in Lemma 1(e) are sharp (cf. [13, Example 3.2]).

### 3.3. Regulated functions and Dirichlet’s function

Now, we are in a position to prove Theorem 1.

**Proof of Theorem 1.** Suppose \( p \in {\mathcal{P}} \), and \( f \in {\mathcal{X}}^T \) is such that \( V_{\epsilon, p}(f, T) \) is finite for all \( \epsilon > 0 \). Given \( \tau \in T \), which is a left limit point for \( T \), let us show that \( d_p(f(s), f(t)) \to 0 \) as \( T \ni s, t \to \tau - 0 \) (the arguments for \( \tau' \in T \) being a right limit point for \( T \) are similar). For any \( \epsilon > 0 \), we define the \( \epsilon \)-\( d_p \)-variation function by \( \varphi_{\epsilon, p}(t) = V_{\epsilon, p}(f, T_t^-) \), \( t \in T \), where \( T_t^- = T \cap (-\infty, t] \). By Lemma 1(b), given \( s, t \in T \) with \( s \leq t \) (and so, \( T_s^- \subset T_t^- \)), we find
\[
0 \leq \varphi_{\epsilon, p}(s) \leq \varphi_{\epsilon, p}(t) \leq V_{\epsilon, p}(f, T) < \infty,
\]
i.e., \( \varphi_{\epsilon, p} : T \to [0, \infty) \) is a bounded and nondecreasing function. Consequently, the left limit
\[
\lim_{T \ni t \to \tau - 0} \varphi_{\epsilon, p}(t) = \sup_{t \in T \cap (-\infty, \tau)} \varphi_{\epsilon, p}(t)
\]
exists in \( [0, \infty) \). It follows that there is \( \delta = \delta(\epsilon) > 0 \) such that
\[
|\varphi_{\epsilon, p}(t) - \varphi_{\epsilon, p}(s)| < \epsilon
\]
for all \( s, t \in T \cap (\tau - \delta, \tau) \). Now, assume that \( s, t \in T \cap (\tau - \delta, \tau) \) are arbitrary such that \( s < t \). Lemma 1(e) (in which \( T \) is replaced by \( T_t^- \), so that \( (T_t^-)_s^- = T_s^- \) and \( (T_t^-)_t^+ = T_t^+ \)) for \( s \in T_t^- \) implies
\[
V_{\epsilon, p}(f, T \cap [s, t]) \leq V_{\epsilon, p}(f, T_t^-) - V_{\epsilon, p}(f, T_s^-) = \varphi_{\epsilon, p}(t) - \varphi_{\epsilon, p}(s) < \epsilon.
\]
By the definition of \( V_{\epsilon, p}(f, T \cap [s, t]) \), there is \( g = g_{\epsilon, p} \in BV_p(T \cap [s, t] ; X) \) such that \( d_{T \cap [s, t], p}(f, g) \leq \epsilon \) and \( V_p(g, T \cap [s, t]) \leq \epsilon \), and so, (3.2) yields
\[
d_p(f(s), f(t)) \leq d_p(g(s), g(t)) + 2d_{T \cap [s, t], p}(f, g) \leq V_p(g, T \cap [s, t]) + 2\epsilon \leq 3\epsilon.
\]
This completes the proof of the equality \( \lim_{T \ni t \to \tau - 0} d_p(f(s), f(t)) = 0 \).

Suppose now that \( f \in \text{Reg}_p(I; X) \) with \( I = [a, b] \). By virtue of [10, Lemma 4], there is a sequence of step functions \( \{g_j\} \subset X^I \) such that \( g_j \Rightarrow_p f \) on \( I \), and so, given \( \epsilon > 0 \), there is \( j(\epsilon) \in \mathbb{N} \) such that \( d_{I, p}(f, g_{j(\epsilon)}) \leq \epsilon \). Since \( g_{j(\epsilon)} \in BV_p(I; X) \), definition (2.1) yields \( V_{\epsilon, p}(f, I) \leq V_{\epsilon, p}(g_{j(\epsilon)}, I) < \infty \), which was to be proved.

As an illustration of Theorem 1, we present an example.

**Example 1.** Let \( I = [a, b], x, y \in X, x \neq y \), and \( \mathbb{Q} \) be the set of all rational numbers. We denote by \( f = D_{x, y} \in X^I \) the *Dirichlet function* given by
\[
D_{x, y}(t) = x \text{ if } t \in I \cap \mathbb{Q}, \text{ and } D_{x, y}(t) = y \text{ if } t \in I \setminus \mathbb{Q}.
\]
\(^{4}\text{Recall that } g \in X^I \text{ is a step function if, for some partition } a = t_0 < t_1 < t_2 < \ldots < t_{m-1} < t_m = b \text{ of } I = [a, b], g \text{ takes a constant value on each open interval } (t_{i-1}, t_i), i = 1, 2, \ldots, m. \text{ Clearly, } g \in BV_p(I; X) \text{ for all } p \in {\mathcal{P}}.\)
It is clearly seen that $f \not\in \text{Reg}(I; M)$: in fact, since $X$ is Hausdorff and $x \neq y$, there is $p_0 \in \mathcal{P}$ such that $d_{p_0}(x, y) > 0$, and so, if, say, $a < \tau < b$, then for all $\delta \in (0, \tau - a)$, $s \in (\tau - \delta, \tau) \cap \mathbb{Q}$ and $t \in (\tau - \delta, \tau) \setminus \mathbb{Q}$, we have $d_{p_0}(f(s), f(t)) = d_{p_0}(x, y) > 0$, so that the limit of $d_{p_0}(f(s), f(t))$ as $I \ni s, t \to \tau - 0$ does not exist.

We claim that, for $\varepsilon > 0$ and all $p \in \mathcal{P}$ with $d_p(x, y) > 0$, we have

$$V_{\varepsilon, p}(f, I) = \begin{cases} \infty & \text{if } \varepsilon < d_p(x, y)/2, \\ 0 & \text{if } \varepsilon \geq d_p(x, y) \end{cases}$$

(3.12)

(the value $V_{\varepsilon, p}(f, I)$ for $d_p(x, y)/2 \leq \varepsilon < d_p(x, y)$ depends on the structure of $X$ such as generalized convexity, cf. [14, Example 1]). In fact, if $\varepsilon \geq d_p(x, y)$, we may set $g(t) = x$ (or $g(t) = y$) for all $t \in I$, so that $d_{p, g}(x, y) \leq \varepsilon$ and, by (2.1), $0 \leq V_{\varepsilon, p}(f, I) \leq V_p(g, I) = 0$. Suppose $0 < \varepsilon < d_p(x, y)/2$. We are going to show that $V_p(g, I) = \infty$ for all $g \in \mathcal{X}$ with $d_{p, g}(x, y) \leq \varepsilon$, which, in accordance with (2.1), will imply $V_{\varepsilon, p}(f, I) = \inf \varnothing = \infty$. Let $m \in \mathbb{N}$ and $a \leq t_0 < t_1 < t_2 < \ldots < t_{m-1} < t_m \leq b$ be a partition of $I = [a, b]$ such that $\{t_{2i}\}_{i=0}^m \subset I \cap \mathbb{Q}$ and $\{t_{2i-1}\}_{i=1}^m \subset I \setminus \mathbb{Q}$. Given $i \in \{1, 2, \ldots, m\}$, (3.2) implies

$$d_p(x, y) = d_p(f(t_{2i}), f(t_{2i-1})) \leq d_p(g(t_{2i}), g(t_{2i-1})) + 2\varepsilon,$$

whence, by the definition of $V_p(g, I)$,

$$V_p(g, I) \geq \sum_{i=1}^m d_p(g(t_{2i}), g(t_{2i-1})) \geq (d_p(x, y) - 2\varepsilon)m \quad \text{for all } m \in \mathbb{N}.$$

### 3.4. Uniform convergence vs. pointwise convergence

The next lemma shows the interplay of the approximate variation and the uniform convergence.

**Lemma 2.** Let $\varnothing \neq T \subset \mathbb{R}$ and $(X, \mathcal{U})$ be a Hausdorff uniform space. Suppose $p \in \mathcal{P}$, $f \in \mathcal{X}$, and $f_j \Rightarrow_p f$ on $T$. We have:

(a) $V_{\varepsilon, p}(f, T) \leq \liminf_{j \to \infty} V_{\varepsilon, p}(f_j, T) \leq \limsup_{j \to \infty} V_{\varepsilon, p}(f_j, T) \leq V_{\varepsilon, p}(f, T), \varepsilon > 0$;

(b) if $V_{\varepsilon, p}(f_j, T) < \infty$ for all $\varepsilon > 0$ and $j \in \mathbb{N}$, then $V_{\varepsilon, p}(f, T) < \infty$ for all $\varepsilon > 0$.

**Remark 2.** (a) Only the first and the last inequalities are to be established.

1. In order to prove the first inequality, we may assume (passing to a suitable subsequence of $\{f_j\}$ if necessary) that its right-hand side is equal to $C_p = \lim_{j \to \infty} V_{\varepsilon, p}(f_j, T) < \infty$. Let $\eta > 0$ be given arbitrarily. Then, there is $j_0 = j_0(\eta) \in \mathbb{N}$ such that $V_{\varepsilon, p}(f_j, T) \leq C_p + \eta$ for all $j \geq j_0$. By the definition of $V_{\varepsilon, p}(f_j, T)$, for every $j \geq j_0$ there is $g_j \in \text{BV}_p(T; X)$ (also depending on $\eta$ and $p$) such that $d_{T, p}(f_j, g_j) \leq \varepsilon$ and $V_{\varepsilon, p}(g_j, T) \leq V_{\varepsilon, p}(f_j, T) + \eta$. Since $f_j \Rightarrow_p f$ on $T$, we find $d_{T, p}(f_j, f) \to 0$ as $j \to \infty$, and so, there is $j_1 = j_1(\eta) \in \mathbb{N}$ such that $d_{T, p}(f_j, f) \leq \eta$ for all $j \geq j_1$. Taking into account that

$$d_{T, p}(f, g_j) \leq d_{T, p}(f, f_j) + d_{T, p}(f_j, g_j) \leq \eta + \varepsilon \quad \text{for all } j \geq \max\{j_0, j_1\},$$

and making use of definition (2.1), we get

$$V_{\eta + \varepsilon, p}(f, T) \leq V_p(g_j, T) \leq V_{\varepsilon, p}(f_j, T) + \eta \leq (C_p + \eta) + \eta = C_p + 2\eta.$$ 

Passing to the limit as $\eta \to +0$, we arrive at $V_{\varepsilon, p}(f, T) \leq C_p$, which was to be proved.

2. To establish the third inequality in (a), we may assume (with no loss of generality) that $V_{\varepsilon, p}(f, T) < \infty$. Given $\eta > 0$, there is $\delta = \delta(\eta, \varepsilon) \in (0, \varepsilon)$ such that $V_{\varepsilon', p}(f, T) \leq V_{\varepsilon, p}(f, T) + \eta$ for all $\varepsilon' \in (\varepsilon - \delta, \varepsilon)$. Since $f_j \Rightarrow_p f$ on $T$, for every $\varepsilon' \in (\varepsilon - \delta, \varepsilon)$ there is $j_0 = j_0(\varepsilon', \varepsilon) \in \mathbb{N}$ such that $d_{T, p}(f_j, f) \leq \varepsilon - \varepsilon'$ for all $j \geq j_0$. By the definition of $V_{\varepsilon', p}(f, T)$, given $j \in \mathbb{N}$, there is $g_j \in \text{BV}_p(T; X)$ (also depending on $\varepsilon'$ and $p$) such that $d_{T, p}(f, g_j) \leq \varepsilon'$ and

$$V_{\varepsilon, p}(f, T) \leq V_p(g_j, T) \leq V_{\varepsilon', p}(f, T) + (1/j).$$
Hence, \( \lim_{j \to \infty} V_p(g_j, T) = V_{\varepsilon_p}(f, T) \). Noting that, for all \( j \geq j_0 \),
\[
d_{T,p}(f_j, g_j) \leq d_{T,p}(f_j, f) + d_{T,p}(f, g_j) \leq (\varepsilon - \varepsilon') + \varepsilon' = \varepsilon,
\]
we find from (2.1) that \( V_{\varepsilon_p}(f_j, T) \leq V_p(g_j, T) \) for all \( j \geq j_0 \). Thus,
\[
\limsup_{j \to \infty} V_{\varepsilon_p}(f_j, T) \leq \lim_{j \to \infty} V_p(g_j, T) = V_{\varepsilon_p}(f, T) \leq V_{\varepsilon-0,p}(f, T) + \eta.
\]
It remains to take into account the arbitrariness of \( \eta > 0 \).

(b) Let \( \varepsilon > 0 \) and \( 0 < \varepsilon' < \varepsilon \). Given \( j \in \mathbb{N} \), since \( V_{\varepsilon_p}(f_j, T) < \infty \), definition (2.1) implies the existence of \( g_j \in BV_p(T; X) \) such that \( d_{T,p}(f_j, g_j) \leq \varepsilon' \) and \( V_p(g_j, T) \leq V_{\varepsilon_p}(f_j, T) + 1 \). Since \( f_j \Rightarrow_p f \) on \( T \), there is \( j_0 = j_0(\varepsilon, \varepsilon') \in \mathbb{N} \) such that \( d_{T,p}(f_{j_0}, f) \leq \varepsilon - \varepsilon' \). Now, it follows from
\[
d_{T,p}(f, g_{j_0}) \leq d_{T,p}(f, f_{j_0}) + d_{T,p}(f_{j_0}, g_{j_0}) \leq (\varepsilon - \varepsilon') + \varepsilon' = \varepsilon
\]
and definition (2.1) that \( V_{\varepsilon_p}(f, T) \leq V_p(g_{j_0}, T) \leq V_{\varepsilon_p}(f_{j_0}, T) + 1 < \infty \).

A few comments and examples concerning Lemma 2 are in order.

**Example 2.** The left limit \( V_{-0,p}(f, T) \) in Lemma 2 (a) cannot in general be replaced by \( V_{\varepsilon,p}(f, T) \). We demonstrate this in the case of a normed linear space \( (X, \| \cdot \|) \) equipped with the canonical metric \( d(x, y) = \| x - y \|, \ x, y \in X \) (here we omit the subscript \( p \) in the notations \( d_T = d_{T,p}, V = V_p \) and \( V_{\varepsilon} = V_{\varepsilon,p} \)). Let \( T = I = [a, b] \) and \( \{x_j\}, \{y_j\} \subset X \) be two sequences such that \( \|x_j - x\| \to 0 \) and \( \|y_j - y\| \to 0 \) as \( j \to \infty \), where \( x, y \in X \), \( x \neq y \). If \( f_j = D_{x_j, y_j}, \ j \in \mathbb{N}, \) and \( f = D_{x,y} \) are Dirichlet functions (3.11) on \( T \), then \( f_j \Rightarrow f \) on \( T \), because
\[
d_{T}(f_j, f) = \sup_{t \in T} \| f_j(t) - f(t) \| = \max \{\|x_j - x\|, \|y_j - y\|\} \to 0 \quad \text{as} \quad j \to \infty.
\]
According to (3.12), the values \( V_{\varepsilon}(f, I) \) are given for \( \varepsilon > 0 \) by
\[
V_{\varepsilon}(f, I) = \infty \quad \text{if} \quad \varepsilon < \|x - y\|/2, \quad \text{and} \quad V_{\varepsilon}(f, I) = 0 \quad \text{if} \quad \varepsilon \geq \|x - y\|/2
\]
(note that if \( \|x - y\|/2 \leq \varepsilon < \|x - y\| \), we may set \( g(t) = (x + y)/2 \) for all \( t \in I \), which implies \( d_{T}(f, g) = \|x - y\|/2 \leq \varepsilon \), and so, \( 0 \leq V_{\varepsilon}(f, I) \leq V_{\varepsilon}(g, I) = 0 \)). Similarly, for (large) \( j \in \mathbb{N} \),
\[
V_{\varepsilon}(f_j, I) = \infty \quad \text{if} \quad \varepsilon < \|x_j - y_j\|/2, \quad \text{and} \quad V_{\varepsilon}(f_j, I) = 0 \quad \text{if} \quad \varepsilon \geq \|x_j - y_j\|/2.
\]
Setting \( \varepsilon = \|x - y\|/2 \), we find
\[
V_{\varepsilon-0}(f, I) = V_{\varepsilon}(f, I) = 0 < \infty = V_{\varepsilon-0}(f, I),
\]
whereas, if \( x_j = \alpha jx \) and \( y_j = \alpha jy \) with \( \alpha = 1 + (1/j), \ j \in \mathbb{N} \), we get \( \varepsilon < \alpha j\|x - y\|/2 = \|x_j - y_j\|/2 \), which implies \( V_{\varepsilon}(f_j, I) = \infty \) for all \( j \in \mathbb{N} \), and so, \( \lim_{j \to \infty} V_{\varepsilon}(f_j, I) = \infty \).

**Example 3.** In this example, we show that the right-hand side inequality in Lemma 2 (a) does not hold in general if \( \{f_j\} \subset X^T \) converges to \( f \in X^T \) only pointwise on \( T \). Suppose \( p_0 \in \mathcal{P} \) is such that \( C_{p_0} = \inf_{j \in \mathbb{N}} |f_j(T)|_{p_0} > 0 \) and \( f = c \) is a constant function on \( T \). Given \( 0 < \varepsilon < C_{p_0}/2 \) and \( j \in \mathbb{N} \), Lemma 1 (d) implies
\[
V_{\varepsilon-0}(f_j, T) \geq |f_j(T)|_{p_0} - 2\varepsilon \geq C_{p_0} - 2\varepsilon > 0 = V_{\varepsilon-0}(c, T) = V_{\varepsilon-0}(f, T).
\]
More specifically, let \( x, y \in X, \ x \neq y, \ p_0 \in \mathcal{P} \) be such that \( d_{p_0}(x, y) > 0 \), and \( \{\tau_j\}_{j \in \mathbb{N}} \subset (a, b) \subset T = [a, b] \) be such that \( \tau_j \to a \) as \( j \to \infty \). Defining \( f_j \in X^T \) by \( f_j(\tau_j) = x \) and \( f_j(t) = y \) if \( t \in T \setminus \{\tau_j\} \), we get \( C_{p_0} = d_{p_0}(x, y) > 0 \) and \( f_j \Rightarrow_p c \equiv y \) on \( T \) for all \( p \in \mathcal{P} \).

Note that the arguments above are not valid for the uniform convergence: in fact, if \( p \in \mathcal{P} \) and \( f_j \Rightarrow_p f = c \) on \( T \), then, by (3.3), \( |f_j(T)|_{p} \leq 2d_{T,p}(f_j, c) \to 0 \) as \( j \to \infty \), and so, \( C_p = \inf_{j \in \mathbb{N}} |f_j(T)|_{p} = 0 \).

**Example 4.** Lemma 2 (b) is wrong for the pointwise convergence of \( \{f_j\} \) to \( f \). To see this, let \( T = I = [a, b], \ x, y \in X, \ x \neq y \), and, given \( j \in \mathbb{N} \), define \( f_j \in X^I \) at \( t \in I \) by: \( f_j(t) = x \) if \( j \cdot t \) is an integer, and \( f_j(t) = y \) otherwise. Each \( f_j \) is a step function on \( I \), so \( f_j \in \text{Reg}(I; X) \) and, hence, by Theorem 1, \( V_{\varepsilon_p}(f_j, I) < \infty \) for all \( \varepsilon > 0 \) and \( p \in \mathcal{P} \). Clearly, \( f_j \) converges (only) pointwise on \( I \) to the Dirichlet function \( f = D_{x,y} \) from (3.11), and so, by (3.12), \( V_{\varepsilon_p}(f, I) = \infty \) for all \( p \in \mathcal{P} \) with \( d_{p}(x, y) > 0 \) and \( 0 < \varepsilon < d_{p}(x, y)/2 \).
4. PROOF OF THE MAIN RESULT

We denote by \( \text{Mon}(T; \mathbb{R}^+) \) the family of all bounded nondecreasing functions mapping \( T \) into \( \mathbb{R}^+ = [0, \infty) \) (where \( \mathbb{R}^+ \) may be replaced by \( \mathbb{R} \)). We recall the classical Helly selection principle for an arbitrary set \( T \subset \mathbb{R} \) (cf. [7, Proof of Theorem 1.3]): a uniformly bounded sequence of functions from \( \text{Mon}(T; \mathbb{R}) \) contains a subsequence which converges pointwise on \( T \) to a function from \( \text{Mon}(T; \mathbb{R}) \).

**Proof of Theorem 2.** By Lemma 1 (b), given \( \varepsilon > 0 \) and \( j \in \mathbb{N} \), the \( \varepsilon - d_p \)-variation function \( t \mapsto V_{\varepsilon, p}(f_j, T_t^-) \) is nondecreasing on \( T \) (recall that \( T_t^- = T \cap (-\infty, t] \) for \( t \in T \)). By assumption (2.2), for every \( \varepsilon > 0 \) and \( p \in \mathcal{P} \) there are \( j^*(\varepsilon, p) \in \mathbb{N} \) and \( C(\varepsilon, p) > 0 \) such that \( V_{\varepsilon, p}(f_j, T) \leq C(\varepsilon, p) \) for all natural \( j \geq j^*(\varepsilon, p) \). Again by Lemma 1 (b),

\[
V_{\varepsilon, p}(f_j, T_t^-) \leq V_{\varepsilon, p}(f_j, T) \leq C(\varepsilon, p) \quad \text{for all } t \in T \text{ and } j \geq j^*(\varepsilon, p),
\]

and so, the sequence of nondecreasing functions \( \{ t \mapsto V_{\varepsilon, p}(f_j, T_t^-) \}_{j=j^*(\varepsilon, p)}^{\infty} \) is uniformly bounded in \( t \in T \) by constant \( C(\varepsilon, p) \).

We divide the rest of the proof into four steps. With no loss of generality we assume that \( \mathcal{P} = \mathbb{N} \).

1. Making use of the Cantor diagonal process, let us show that for each decreasing sequence \( \{ \varepsilon_k \}_{k=1}^{\infty} \) of positive numbers \( \varepsilon_k \to 0 \) (as \( k \to \infty \)) there is a subsequence of \( \{ f_j \} \), again denoted by \( \{ f_j \} \), and for every \( p \in \mathcal{P} \) there is a sequence of functions \( \{ \varphi_{k, p}\}_{k=1}^{\infty} \subset \text{Mon}(T; \mathbb{R}^+) \) such that

\[
\lim_{j \to \infty} V_{\varepsilon_k, p}(f_j, T_t^-) = \varphi_{k, p}(t) \quad \text{for all } t \in T \text{ and } k \in \mathbb{N}.
\]

We begin with \( p = 1 \). The sequence \( \{ t \mapsto V_{\varepsilon_1, 1}(f_j, T_t^-) \}_{j=j^*(\varepsilon_1, 1)}^{\infty} \) from \( \text{Mon}(T; \mathbb{R}^+) \) is uniformly bounded in \( t \in T \) by \( C(\varepsilon_1, 1) \), and so, by the Helly selection principle, there are a subsequence \( \{ J_{1, 1}(\epsilon) \}_{j=1}^{\infty} \) of \( \{ j \}_{j=j^*(\varepsilon_1, 1)}^{\infty} \) and a function \( \varphi_{1, 1} \in \text{Mon}(T; \mathbb{R}^+) \) such that

\[
\lim_{j \to \infty} V_{\varepsilon_1, 1}(f_{J_{1, 1}(\epsilon)}, T_t^-) = \varphi_{1, 1}(t) \quad \text{for all } t \in T.
\]

Now, choose the least number \( j_{1, 1} \in \mathbb{N} \) such that \( J_{1, 1}(j_{1, 1}) \geq j^*(\varepsilon_2, 1) \).

Inductively, assume that \( k \geq 2 \) and a subsequence \( \{ J_{k-1, 1}(\epsilon) \}_{j=1}^{\infty} \) of \( \{ j \}_{j=j^*(\varepsilon_1, 1)}^{\infty} \) and the number \( j_{k-1, 1} \in \mathbb{N} \) such that \( J_{k-1, 1}(j_{k-1, 1}) \geq j^*(\varepsilon_k, 1) \) have already been constructed. Since \( \{ t \mapsto V_{\varepsilon_k, 1}(f_{J_{k-1, 1}(\epsilon)}, T_t^-) \}_{j=j_{k-1, 1}}^{\infty} \) is a sequence from \( \text{Mon}(T; \mathbb{R}^+) \), uniformly bounded in \( t \in T \) by \( C(\varepsilon_k, 1) \), the Helly selection principle implies the existence of a subsequence \( \{ J_{k, 1}(\epsilon) \}_{j=1}^{\infty} \) of \( \{ J_{k-1, 1}(\epsilon) \}_{j=j_{k-1, 1}}^{\infty} \) and a function \( \varphi_{k, 1} \in \text{Mon}(T; \mathbb{R}^+) \) such that

\[
\lim_{j \to \infty} V_{\varepsilon_k, 1}(f_{J_{k, 1}(\epsilon)}, T_t^-) = \varphi_{k, 1}(t) \quad \text{for all } t \in T.
\]

Given \( k \in \mathbb{N} \), \( \{ J_{k, 1}(\epsilon) \}_{j=1}^{\infty} \) is a subsequence of \( \{ J_{k-1, 1}(\epsilon) \}_{j=1}^{\infty} \), and so, the diagonal subsequence \( \{ f^{(1)}_j \}_{j=1}^{\infty} \equiv \{ f_{J_{k, 1}(\epsilon)} \}_{j=1}^{\infty} \) of the original sequence \( \{ f_j \}_{j=1}^{\infty} \) satisfies the condition

\[
\lim_{j \to \infty} V_{\varepsilon_k, 1}(f^{(1)}_j, T_t^-) = \varphi_{k, 1}(t) \quad \text{for all } t \in T \text{ and } k \in \mathbb{N}.
\]

Taking into account (4.2), again inductively, assume that \( p \in \mathcal{P} \), \( p \geq 2 \), and a subsequence \( \{ f^{(p-1)}_j \}_{j=1}^{\infty} \) of \( \{ f^{(1)}_j \}_{j=1}^{\infty} \) (and, hence, of \( \{ f_j \} \)) satisfying

\[
\lim_{j \to \infty} V_{\varepsilon_k, p-1}(f^{(p-1)}_j, T_t^-) = \varphi_{k, p-1}(t) \quad \text{for all } t \in T \text{ and } k \in \mathbb{N}
\]

is already chosen. The sequence \( \{ t \mapsto V_{\varepsilon_1, p}(f^{(p-1)}_j, T_t^-) \}_{j=j^*(\varepsilon_1, p)}^{\infty} \) of nondecreasing functions on \( T \) is uniformly bounded in \( t \in T \) by \( C(\varepsilon_1, p) \), and so, by the Helly selection principle, there are a
subsequence \( \{f_{j,p}^{(p-1)}\}_{j=1}^{\infty} \) of \( \{f_{j}^{(p-1)}\}_{j=j^*(\varepsilon_1,p)}^{\infty} \) (where \( J_{1,p} : \mathbb{N} \to \mathbb{N} \) is a strictly increasing subsequence of \( \{j\}_{j=j^*(\varepsilon_1,p)}^{\infty} \)) and a function \( \varphi_{1,p} \in \text{Mon}(T;\mathbb{R}^+) \) such that

\[
\lim_{j \to \infty} V_{\varepsilon_1,p}(f_{j,p}^{(p-1)}, T^-_t) = \varphi_{1,p}(t) \quad \text{for all } t \in T.
\]

Pick the least number \( j_{1,p} \in \mathbb{N} \) such that \( J_{1,p}(j_{1,p}) \geq j^*(\varepsilon_2,p) \). Inductively, assume now that \( k \geq 2 \) and a subsequence \( \{J_{k-1,p}(j)\}_{j=1}^{\infty} \) of \( \{j\}_{j=j^*(\varepsilon_1,p)}^{\infty} \) and the (least) number \( j_{k-1,p} \in \mathbb{N} \) such that \( J_{k-1,p}(j_{k-1,p}) \geq j^*(\varepsilon_k,p) \) are already chosen. Since \( \{t \mapsto V_{\varepsilon_k,p}(f_{j_{k-1,p}}^{(p-1)}, T^-_t)\}_{j=j_{k-1,p}}^{\infty} \) is a sequence from \( \text{Mon}(T;\mathbb{R}^+) \), uniformly bounded in \( t \in T \) by \( C(\varepsilon_k,p) \), the Helly selection principle implies the existence of a subsequence \( \{J_{k,p}(j)\}_{j=1}^{\infty} \) of \( \{J_{k-1,p}(j)\}_{j=1}^{\infty} \) and a function \( \varphi_{k,p} \in \text{Mon}(T;\mathbb{R}^+) \) such that

\[
\lim_{j \to \infty} V_{\varepsilon_k,p}(f_{J_{k,p}(j)}^{(p-1)}, T^-_t) = \varphi_{k,p}(t) \quad \text{for all } t \in T.
\]

Given \( k \in \mathbb{N} \), \( \{J_{k,p}(j)\}_{j=1}^{\infty} \) is a subsequence of \( \{J_{k-1,p}(j)\}_{j=1}^{\infty} \), and so, the diagonal subsequence \( \{f_{j,p}^{(p)}\}_{j=1}^{\infty} = \{f_{J_{k,p}(j)}^{(p-1)}\}_{j=1}^{\infty} \) of \( \{f_{j_{k-1,p}}^{(p-1)}\}_{j=1}^{\infty} \) satisfies the equality

\[
\lim_{j \to \infty} V_{\varepsilon_k,p}(f_{J_{k,p}(j)}^{(p)}, T^-_t) = \varphi_{k,p}(t) \quad \text{for all } t \in T \text{ and } k \in \mathbb{N}.
\]

Finally, the diagonal sequence \( \{f_{j,p}^{(p)}\}_{j=1}^{\infty} \), again denoted by \( \{f_j\}_{j=1}^{\infty} \), satisfies (4.1).

2. Let \( Q \) be an at most countable dense subset of \( T \). Note that any point \( t \in T \), which is not a limit point for \( T \) (i.e., \( T \cap (t - \delta, t + \delta) = \{t\} \) for some \( \delta > 0 \)), belongs to \( Q \). Since, for any \( k \in \mathbb{N} \) and \( p \in \mathcal{P} \), \( \varphi_{k,p} \in \text{Mon}(T;\mathbb{R}^+) \), the set \( Q_{k,p} \subset T \) of points of discontinuity of \( \varphi_{k,p} \) is at most countable. Setting \( S = Q \cup \bigcup_{k \in \mathbb{N}} \bigcup_{p \in \mathcal{P}} Q_{k,p} \), we find that \( S \) is an at most countable dense subset of \( T \). Furthermore, if \( S \neq T \), then every point \( t \in T \setminus S \) is a limit point for \( T \) and \( \varphi_{k,p} \) is continuous on \( T \setminus S \) for all \( k \in \mathbb{N} \) and \( p \in \mathcal{P} \).

(4.3)

Since \( S \) is at most countable and \( \{f_j(s) : j \in \mathbb{N}\} \) is a relatively sequentially compact subset of \( X \) for all \( s \in S \), with no loss of generality we may assume (applying the Cantor diagonal process and passing to a subsequence of \( \{f_j\} \) if necessary) that, for each \( s \in S \), \( f_j(s) \) converges in \( X \) as \( j \to \infty \) to a unique point denoted by \( f(s) \in X \), so that \( f : S \to X \) and \( \lim_{j \to \infty} d_p(f_j(s), f(s)) = 0 \) for all \( p \in \mathcal{P} \).

If \( S = T \), we turn to step 4 below which completes the proof.

3. Assume that \( S \neq T \) and \( t \in T \setminus S \) is arbitrary. Let us prove that \( \{f_j(t)\}_{j=1}^{\infty} \) is a Cauchy sequence in \( X \), i.e., \( \lim_{j,j' \to \infty} d_p(f_j(t), f_{j'}(t)) = 0 \) for all \( p \in \mathcal{P} \). Let us fix \( p \in \mathcal{P} \). Since \( \varepsilon_k \to 0 \) as \( k \to \infty \), given \( \eta > 0 \), choose and fix \( k = k(\eta) \in \mathbb{N} \) such that \( \varepsilon_k \leq \eta \). By (4.3), \( \varphi_{k,p} \) is continuous at \( t \), and so, by the density of \( S \) in \( T \), there is \( s = s(\eta,k,t,p) \in S \) such that \( |\varphi_{k,p}(t) - \varphi_{k,p}(s)| \leq \eta \). Property (4.1) implies the existence of \( j^1(\eta,k,t,s,p) \in \mathbb{N} \) such that, for all \( j \geq j^1 \), we have

\[
|V_{\varepsilon_k,p}(f_j, T^-_t) - \varphi_{k,p}(t)| \leq \eta \quad \text{and} \quad |V_{\varepsilon_k,p}(f_j, T^-_s) - \varphi_{k,p}(s)| \leq \eta.
\]

(4.4)

Supposing (with no loss of generality) that \( s < t \) and applying Lemma 1 (e) (in which \( T \) is replaced by \( T^-_t \), so that \( (T^-_t)^{-} = T^-_s \) and \( (T^-_t)^{+} = T \cap [s,t] \)), we get

\[
V_{\varepsilon_k,p}(f_j, T \cap [s,t]) \leq V_{\varepsilon_k,p}(f_j, T^-_s) - V_{\varepsilon_k,p}(f_j, T^-_t)
\]

\[
\leq |V_{\varepsilon_k,p}(f_j, T^-_s) - \varphi_{k,p}(t)| + |\varphi_{k,p}(t) - \varphi_{k,p}(s)|
\]

\[
+ |\varphi_{k,p}(s) - V_{\varepsilon_k,p}(f_j, T^-_s)| \leq \eta + \eta + \eta = 3\eta \quad \text{for all } j \geq j^1.
\]

By the definition of \( V_{\varepsilon_k,p}(f_j, T \cap [s,t]) \), for each \( j \geq j^1 \) there is a function \( g_j \in \text{BV}_p(T \cap [s,t];X) \), also depending on \( \eta,k,t,s,p \), such that

\[
d_{T \cap [s,t],p}(f_j, g_j) \leq \varepsilon_k \quad \text{and} \quad V_p(g_j, T \cap [s,t]) \leq V_{\varepsilon_k,p}(f_j, T \cap [s,t]) + \eta.
\]
These inequalities, (3.2) and the definition of $V_p(\cdot, \cdot)$ imply, for all $j \geq j^1$,
\[
d_p(f_j(s), f_j(t)) \leq d_p(g_j(s), g_j(t)) + 2d_{T \cap [s, t], p}(f_j, g_j) \\
\leq V_p(g_j, T \cap [s, t]) + 2\varepsilon_k \leq (3\eta + \eta) + 2\eta = 6\eta.
\]
Being convergent in the uniform space $X$, the sequence $\{f_j(s)\}_{j=1}^\infty$ is Cauchy (cf. [26, Theorem 6.21]), and so, there is $j^3 = j^3(\eta, s, t, p) \in \mathbb{N}$ such that $d_p(f_j(s), f_{j'}(s)) \leq \eta$ for all $j, j' \geq j^3$. The number $j^3 = \max\{j^1, j^2\}$ depends only on $\eta, t$ and $p$, and we find, by the triangle inequality for $d_p$,
\[
d_p(f_j(t), f_{j'}(t)) \leq d_p(f_j(t), f_j(s)) + d_p(f_j(s), f_{j'}(s)) + d_p(f_{j'}(s), f_{j'}(t)) \\
\leq 6\eta + \eta + 6\eta = 13\eta \quad \text{for all} \quad j, j' \geq j^3.
\]
Due to the arbitrariness of $p \in \mathcal{P}$, this proves that $\{f_j(t)\}_{j=1}^\infty$ is a Cauchy sequence in $X$. Taking into account that the set $\{f_j(t) : j \in \mathbb{N}\}$ is relatively sequentially compact in $X$, we conclude that the sequence $\{f_j(t)\}_{j=1}^\infty$ has a limit point in $X$, which we denote by $f(t) \in X$. By [26, Theorem 6.21], a Cauchy sequence in a uniform space converges to its limit point, and so, $\lim_{j \to \infty} d_p(f_j(t), f(t)) = 0$ for all $p \in \mathcal{P}$.

4. Since the uniform space $X$ is Hausdorff, we have shown at the end of steps 2 and 3 that the function $f : T = S \cup (T \setminus S) \to X$ is well-defined, and it is the pointwise limit on $T$ of a subsequence $\{f_{j_k}\}_{k=1}^\infty$ of the original sequence $\{f_j\}_{j=1}^\infty$. It follows from Lemma 1(d) that, given $p \in \mathcal{P}$ and $\varepsilon_0 > 0$,
\[
|f(T)|_p \leq \liminf_{k \to \infty} |f_{j_k}(T)|_p \leq \liminf_{k \to \infty} V_{\varepsilon_0, p}(f_{j_k}, T) + 2\varepsilon_0 \\
\leq \limsup_{j \to \infty} V_{\varepsilon_0, p}(f_j, T) + 2\varepsilon_0 < \infty,
\]
and so, $f$ is a bounded function on $T$ (i.e., $f \in B(T; X)$).

Now, we prove that $f$ is regulated on $T$. Given $\tau \in T$, which is a left limit point for $T$, let us show that $d_p(f(s), f(t)) \to 0$ as $T \ni s, t \to \tau - 0$ for all $p \in \mathcal{P}$ (similar arguments apply in the case when $\tau' \in T$ is a right limit point for $T$). Given $p \in \mathcal{P}$, this is equivalent to showing that for every $\eta > 0$ there is $\delta = \delta(\eta, p) > 0$ such that $d_p(f(s), f(t)) \leq 7\eta$ for all $s, t \in T \cap (\tau - \delta, \tau)$ with $s < t$. Recall that the (finally) extracted subsequence of the original sequence $\{f_j\}$, again denoted by $\{f_j\}$ here, satisfies condition (4.1), and $f_j \to f$ pointwise on $T$.

Let $p \in \mathcal{P}$ and $\eta > 0$ be arbitrarily fixed. Since $\varepsilon_k \to 0$ as $k \to \infty$, pick and fix natural $k = k(\eta)$ such that $\varepsilon_k \leq \eta$, and since $\varphi_{k, p} \in \text{Mon}(T, \mathbb{R}^+)$ and $\tau \in T$ is a left limit point for $T$, the left limit $\lim_{t \searrow \tau - 0} \varphi_{k, p}(t) \in \mathbb{R}^+$ exists. Hence, there is $\delta = \delta(\eta, k, p) > 0$ such that $|\varphi_{k, p}(t) - \varphi_{k, p}(s)| \leq \eta$ for all $s, t \in T \cap (\tau - \delta, \tau)$. By virtue of (4.1), for any $s, t \in T \cap (\tau - \delta, \tau)$ there is $j^1 = j^1(\eta, k, s, t, p) \in \mathbb{N}$ such that, if $j \geq j^1$, then the inequalities (4.4) hold. Arguing exactly the same way as in between the lines (4.4) and (4.5), we find that $d_p(f(s), f(t)) \leq 6\eta$ for all $j \geq j^1$. Noting that $f_j(s) \to f(s)$ and $f_j(t) \to f(t)$ in $X$ as $j \to \infty$, by the triangle inequality for $d_p$, we get
\[
|d_p(f_j(s), f_j(t)) - d_p(f(s), f(t))| \leq d_p(f_j(s), f(s)) + d_p(f_j(t), f(t)) \to 0
\]
as $j \to \infty$. So, there is $j^2 = j^2(\eta, s, t, p) \in \mathbb{N}$ such that $d_p(f(s), f(t)) \leq d_p(f_j(s), f_j(t)) + \eta$ for all $j \geq j^2$. Thus, choosing $j \geq \max\{j^1, j^2\}$, we obtain $d_p(f(s), f(t)) \leq 6\eta + \eta = 7\eta$.

This completes the proof of Theorem 2. \hfill \Box

**Remark 1.** Theorem 2 is an extension of the Helly-type selection principles from [21, Theorem 3.8] (for $T = [a, b]$ and $X = \mathbb{R}^N$) and [14, Theorem 3] (for any $T \subset \mathbb{R}$ and a metric space $X$). It also extends Theorem 8 from [10], in which, under the assumptions of Theorem 2, condition (2.2) is replaced by a more stringent one: $C_p \equiv \sup_{j \in \mathbb{N}} V_p(f_j, T) < \infty$ for all $p \in \mathcal{P}$. In fact, by Lemma 1(c), $V_{\varepsilon, p}(f_j, T) \leq C_p$ for all $j \in \mathbb{N}, \varepsilon > 0$ and $p \in \mathcal{P}$, and so, (2.2) is fulfilled. Now, if, according to Theorem 2, a subsequence of $\{f_j\}$ converges pointwise on $T$ to a function $f \in X^T$, then property (3.6) implies $V_p(f, T) \leq C_p$ for all $p \in \mathcal{P}$, i.e., $f \in BV(T; X)$. 

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Remark 2. Condition (2.2) in Theorem 2 is necessary for the uniformly convergent sequence \( \{f_j\} \subset X^T \) in the following sense: if \( f_j \Rightarrow f \) on \( T \), where \( f \in X^T \) is such that \( V_{\varepsilon,p}(f,T) < \infty \) for all \( \varepsilon > 0 \) and \( p \in \mathcal{P} \), then, by virtue of Lemma 2(a), for all \( 0 < \varepsilon' < \varepsilon \) and \( p \in \mathcal{P} \), we have
\[
\limsup_{j \to \infty} V_{\varepsilon,p}(f_j,T) \leq V_{\varepsilon-0,p}(f,T) \leq V_{\varepsilon',p}(f,T) < \infty.
\]

Example 5. Condition (2.2) in Theorem 2 is not necessary for the pointwise convergent sequence \( \{f_j\} \subset X^T \) (cf. also Examples 4.7, 4.10 and 4.11 in [13]). This can be illustrated by the sequence \( \{f_j\} \) from Example 4, where \( I = [0,1] \). We assert that if \( p \in \mathcal{P} \) is such that \( d_p(x,y) > 0 \), and \( 0 < \varepsilon < d_p(x,y)/2 \), then \( \lim_{j \to \infty} V_{\varepsilon,p}(f_j,I) = \infty \). In fact, given \( j \in \mathbb{N} \), we set \( t_k = k/j! \) (so that \( f_j(t_k) = x \)) for \( k = 0,1,\ldots,j! \), and \( s_k = (t_{k-1} + t_k)/2 = (k - 1/2)/j! \) (so that \( f_j(s_k) = y \)) for \( k = 1,2,\ldots,j! \). This induces a partition of \( I = [0,1] \):
\[
0 = t_0 < s_1 < t_1 < s_2 < t_2 < \ldots < s_{j!-1} < t_{j!-1} < s_{j!} < t_{j!} = 1.
\]

Supposing \( g \in X^I \) is arbitrary such that \( d_{I,p}(f_j,g) \leq \varepsilon \), by virtue of the definition of \( V_{\varepsilon}(g,I) \) and (3.2), we find
\[
V_{\varepsilon,p}(g,I) \geq j! \sum_{k=1}^{j!} d_p(g(t_k),g(s_k)) \geq j! \sum_{k=1}^{j!} (d_p(f(t_k),f(s_k)) - 2\varepsilon) = j! \cdot (d_p(x,y) - 2\varepsilon).
\]

By definition (2.1), \( V_{\varepsilon,p}(f_j,I) \geq j! \cdot (d_p(x,y) - 2\varepsilon) \), which proves our assertion.

Example 6. Theorem 2 is inapplicable to the sequence \( \{f_j\} \) from Example 2, because (although \( f_j \Rightarrow f \equiv D_{x,y} \) on \( I \)) \( \lim_{j \to \infty} V_{\varepsilon}(f_j,I) = \infty \) for \( \varepsilon = \|x-y\|/2 \). The reason here is that the limit function \( D_{x,y} \) is not regulated if \( x \neq y \).

Nevertheless, Theorem 2 can be applied to sequences of non-regulated functions. Let \( \{x_j\} \) and \( \{y_j\} \) be two sequences in the uniform space \( X \) such that \( x_j \neq y_j \) for all \( j \in \mathbb{N} \), \( x_j \to x \) and \( y_j \to x \) in \( X \) as \( j \to \infty \) for some \( x \in X \). The sequence \( f_j = D_{x_j,y_j} \) converges uniformly on \( I = [a,b] \) to the constant function \( f(t) \equiv x \) on \( I \):
\[
d_{I,p}(f_j,f) = \max\{d_p(x_j,x),d_p(y_j,x)\} \to 0 \quad \text{as } j \to \infty \text{ for all } p \in \mathcal{P}.
\]

Given \( p \in \mathcal{P} \) and \( \varepsilon > 0 \), there is \( j_0 = j_0(p,\varepsilon) \in \mathbb{N} \) such that \( d_p(x_j,y_j) \leq \varepsilon \) for all \( j \geq j_0 \), and so, by (3.12), \( V_{\varepsilon,p}(f_j,I) = 0 \) for all \( j \geq j_0 \). This implies condition (2.2):
\[
\limsup_{j \to \infty} V_{\varepsilon,p}(f_j,I) \leq \sup_{j \geq j_0} V_{\varepsilon,p}(f_j,I) = 0.
\]

Applying Theorem 2 and the diagonal process over expanding intervals, we get the following local version of Theorem 2:

**Theorem 3.** Under the assumptions of Theorem 2, suppose that condition (2.2) is replaced by (the local one)
\[
\limsup_{j \to \infty} V_{\varepsilon,p}(f_j,T \cap [a,b]) < \infty \quad \text{for all } a, b \in T, \ a \leq b, \ \varepsilon > 0, \text{ and } p \in \mathcal{P}.
\]

Then, there is a subsequence of \( \{f_j\} \) which converges pointwise on \( T \) to a function \( f \in \text{Reg}(T;X) \) such that \( f \in B(T \cap [a,b];X) \) for all \( a, b \in T, \ a \leq b \).
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