Absolute Continuity of the Laws of Perturbed Diffusion Processes and Perturbed Reflected Diffusion Processes

Wen Yue, Tusheng Zhang

Department of Mathematics, University of Manchester, Oxford Road, Manchester M13 9PL, England, UK

Abstract

In this paper, we prove that the laws of perturbed diffusion processes and perturbed reflected diffusion processes are absolutely continuous with respect to the Lebesgue measure. The main tool we use is the Malliavin calculus.

Keywords: Perturbed diffusion processes; Perturbed reflected diffusion processes; Malliavin differentiability; Absolute continuity; Comparison theorem.

1 Introduction

Let \((\Omega, \mathcal{F}, \{\mathcal{F}_t\}_{t \geq 0}, P)\) be a filtered probability space with filtration \(\{\mathcal{F}_t\}_{t \geq 0}\) satisfying the usual conditions. \(\{B_t\}_{t \geq 0}\) is a one-dimensional standard \(\{\mathcal{F}_t\}_{t \geq 0}\)-Brownian Motion. Suppose that \(\sigma(x), b(x)\) are Lipschitz continuous functions on \(\mathbb{R}\). There now exists a considerable body of literature devoted to the study of perturbed stochastic differential equations (SDEs), see e.g. [1-4], [6-8], [11], [13]. It was proved in [5] that the following perturbed SDE:

\[
Y_t = y_0 + \int_0^t \sigma(Y_s) dB_s + \int_0^t b(Y_s) ds + \alpha \max_{0 \leq s \leq t} Y_s. \tag{1.1}
\]

and the perturbed reflected SDE:

\[
\begin{align*}
X_t &= \int_0^t \sigma(X_s) dB_s + \int_0^t b(X_s) ds + \alpha \max_{0 \leq s \leq t} X_s + L_t \\
X_t &\geq 0 \\
\int_0^t X(X_s=0) dL_s &= L_t.
\end{align*}
\tag{1.2}
\]

admit unique solutions. Perturbed Brownian motion arose in a study of the windings of planar Brownian motion, see [8]. Perturbed diffusion processes are also continuous versions of self-interacting random walks.

The purpose of this paper is to establish the absolute continuity of the laws of perturbed diffusion processes as well as perturbed reflected diffusion processes under appropriate conditions. The absolute continuity of the laws of the solutions is of fundamental importance both theoretically and numerically. The absolute continuity of the laws of the solutions to stochastic differential equations has been studied by many people. We refer the reader to the books [11], [13] and references therein.

The tool we use is naturally Malliavin Calculus. Because the extra terms in equation (1.1) and (1.2) involve the maximum of the solution itself, the Malliavin differentiability of the solutions becomes very delicate. For the absolute continuity of the laws of the solutions, we
need a careful analysis of the time points where the solution $X$ reaches its maximum. The local property of the Malliavin derivative and a comparison theorem for stochastic differential equations play a crucial role.

This paper is organized as follows. In Section 2, we collect some results of Malliavin calculus to be used later in the paper. In Section 3, we prove that the perturbed diffusion process is Malliavin differentiable and establish the absolute continuity of the laws of the perturbed diffusion processes. In Section 4, we study the reflected perturbed diffusion processes. The Malliavin differentiability and the absolute continuity of the solutions are obtained.

2 Preliminaries

In this section, we collect some results on Malliavin calculus which will be used in the paper. Let $\Omega = C_0(R_+)$ be the space of continuous functions on $R_+$ which are zero at zero. Denote by $\mathcal{F}$ the Borel $\sigma$-field on $\Omega$ and $P$ the Wiener measure. Then the canonical coordinate process $\{B_t, t \in R_+\}$ on $\Omega$ is a Brownian motion. Define $\mathcal{F}_t^0 = \sigma(B_s, s \leq t)$. Denote by $\mathcal{F}_t$ the completion of $\mathcal{F}_t^0$ with respect to the $P$-null sets of $\mathcal{F}$.

Let $h \in L^2(R_+)$. $W(h)$ will stand for the Wiener integral as follows:

$$W(h) = \int_0^\infty h(t)dB_t. \tag{2.1}$$

\{W(h), h \in H\} is a Gaussian Process on $H := L^2(R_+, \mathcal{B}, \mu)$, where $(R_+, \mathcal{B})$ is a measurable space, $\mathcal{B}$ is the Borel sigma field of $R_+$ and $\mu$ is the Lebesgue measure on $R_+$.

We denote by $C^\infty_p(R^n)$ the set of all infinitely continuously differentiable functions $f : R^n \rightarrow R$ such that $f$ and all of its partial derivatives have polynomial growth. Let $S$ be the set of smooth random variables defined by

$$S = \{F = f(W(h_1), W(h_2), ..., W(h_n)); \ h_1, ..., h_n \in L^2(R_+), n \geq 1, f \in C^\infty_p(R^n)\}. \tag{2.2}$$

Let $F \in S$. Define its Malliavin derivative $D_tF$ by

$$D_tF = \sum_{i=1}^n \partial_i f(W(h_1), W(h_2), ..., W(h_n))h_i(t), \tag{2.3}$$

and its norm by

$$||F||_{1,2} = \left[ E(||F||^2) + E(||DF||^2_H) \right]^\frac{1}{2}. \tag{2.4}$$

Let $D^{1,2}$ be the completion of $S$ under the norm $||.||_{1,2}$. The following result is from [11].

**Theorem 2.1** Let $F \in D^{1,2}$. If $||DF||_H > 0$ a.s., then the law of the random variable $F$ is absolutely continuous with respect to Lebesgue measure.

3 Absolute continuity of the laws of perturbed diffusion processes

Let $\sigma(x), b(x)$ be Lipschitz continuous functions on $R$, i.e., there exists a constant $C$ such that

$$|\sigma(x) - \sigma(y)| \leq C|x - y|, \tag{3.1}$$

...
\[ |b(x) - b(y)| \leq C|x - y|. \] \hspace{1cm} (3.2)

For \( \alpha < 1 \), \( y_0 \in R \), consider the following stochastic differential equation:

\[
Y_t = y_0 + \int_0^t \sigma(Y_s)dB_s + \int_0^t b(Y_s)ds + \alpha \max_{0 \leq s \leq t} Y_s.
\] \hspace{1cm} (3.3)

It was shown in [5] that equation \((3.3)\) admits a unique, continuous, adapted solution. We have the following result.

**Theorem 3.1** Let \( Y_t \) be the unique solution to equation \((3.3)\). Then \( Y_t \in D^{1,2} \) for any \( t \geq 0 \).

**Proof.** Consider Picard approximations given by

\[
Y_t^0 = \frac{y_0}{1 - \alpha}, \hspace{0.5cm} 0 \leq t < \infty.
\] \hspace{1cm} (3.4)

For \( n \geq 0 \), define \( Y_{t}^{n+1} \) to be the unique, continuous, adapted solution to the following equation:

\[
Y_{t}^{n+1} = y_0 + \int_0^t \sigma(Y^n_s)dB_s + \int_0^t b(Y^n_s)ds + \alpha \max_{0 \leq s \leq t} Y_{s}^{n+1}.
\] \hspace{1cm} (3.5)

Such a solution exists and can be expressed explicitly as

\[
Y_{t}^{n+1} = \frac{y_0}{1 - \alpha} + \int_0^t \sigma(Y^n_s)dB_s + \int_0^t b(Y^n_s)ds + \frac{\alpha}{1 - \alpha} \max_{0 \leq s \leq t} \left( \int_0^s \sigma(Y^n_u)dB_u + \int_0^s b(Y^n_u)du \right).
\] \hspace{1cm} (3.6)

It was shown in [5] that the solution \( Y_t \) is the limit of \( Y^n_t \) in \( L^2(\Omega) \).

We will prove the following property by induction on \( n \):

\((P)\) \hspace{0.5cm} \( Y^n_t \in D^{1,2} \), \( E[\int_0^t ||DY^n_u||_H^2 du] < \infty, t \geq 0 \).

Clearly, \((P)\) holds for \( n=0 \). Suppose \( Y^n_t \in D^{1,2} \) and \( E[\int_0^t ||DY^n_u||_H^2 du] < \infty \). Applying Proposition 1.2.4 in [11] to the random variable \( Y^n_s \) and to \( \sigma \) and \( b \), we deduce that the random variables \( \sigma(Y^n_s) \) and \( b(Y^n_s) \) belong to \( D^{1,2} \) and that there exist adapted processes \( \tilde{\sigma}(s) \) and \( \tilde{b}(s) \), which are uniformly bounded by some constant \( K \), such that:

\[
D_r(\sigma(Y^n_s)) = \tilde{\sigma}(s)D_r(Y^n_s)I\{r \leq s\},
\] \hspace{1cm} (3.7)

and

\[
D_r(b(Y^n_s)) = \tilde{b}(s)D_r(Y^n_s)I\{r \leq s\}.
\] \hspace{1cm} (3.8)

From (3.7) and (3.8) we get

\[
|D_r(\sigma(Y^n_s))| \leq K|D_r(Y^n_s)|,
\] \hspace{1cm} (3.9)

and

\[
|D_r(b(Y^n_s))| \leq K|D_r(Y^n_s)|.
\] \hspace{1cm} (3.10)

By Lemma 1.3.4 in [11], we conclude that

\[
\int_0^t \sigma(Y^n_s)dB_s \in D^{1,2}.
\] \hspace{1cm} (3.11)
For $r \leq t$, by Proposition 1.3.8 in [11],

$$ D_r\left[ \int_0^t \sigma(Y^n_s)dB_s \right] = \sigma(Y^n_r) + \int_r^t D_r(\sigma(Y^n_u))dB_u $$  \hspace{1cm} (3.12) 

Similarly, we have

$$ \int_0^t b(Y^n_s)ds \in \mathbb{D}^{1,2}, $$  \hspace{1cm} (3.13) 

$$ D_r\left[ \int_0^t b(Y^n_s)ds \right] = \int_r^t D_r(b(Y^n_u))ds. $$  \hspace{1cm} (3.14) 

Let $Z^n_s = \int_0^s \sigma(Y^n_u)dB_u$, $X^n_s = \int_0^s b(Y^n_u)du$. Then

$$ Z^n_s + X^n_s \in \mathbb{D}^{1,2}, $$  \hspace{1cm} (3.15) 

and

$$ E[ \sup_{0 \leq s \leq t} (Z^n_s + X^n_s)^2 ] \leq E[ \sup_{0 \leq s \leq t} 2((Z^n_s)^2 + (X^n_s)^2) ] \leq 2E[ \sup_{0 \leq s \leq t} (Z^n_s)^2 ] + 2E[ \sup_{0 \leq s \leq t} (X^n_s)^2 ] < \infty. $$  \hspace{1cm} (3.16) 

Next we show that

$$ E[ \sup_{0 \leq s \leq t} ||D(Z^n_s + X^n_s)||^2_H ] < \infty. $$  \hspace{1cm} (3.17) 

Now

$$ E[ \sup_{0 \leq s \leq t} ||D(Z^n_s + X^n_s)||^2_H ] = E[ \sup_{0 \leq s \leq t} \int_0^s |D_r(Z^n_s + X^n_s)|^2 dr ] $$

$$ \leq 3E\{ \sup_{0 \leq s \leq t} \int_0^s [\sigma(Y^n_r)^2 + | \int_r^s D_r(\sigma(Y^n_u))dB_u|^2 $$

$$ + | \int_r^s D_r(b(Y^n_u))du|^2 ] dr \} $$

$$ \leq 3E \int_0^t \sigma(Y^n_r)^2 dr + 3 \int_0^t E[ \sup_{r \leq s \leq t} | \int_r^s D_r(\sigma(Y^n_u))dB_u|^2 ] dr $$

$$ + 3E \int_0^t | \int_r^s |D_r(b(Y^n_u))|^2 du|^2 ] dr $$

$$ \leq 3 \int_0^t E[\sigma(Y^n_r)^2] dr + 3C \int_0^t \int_r^t E[D_r(\sigma(Y^n_u))]^2 du dr $$

$$ + 3 \int_0^t \int_r^t E[D_r(b(Y^n_u))^2] du(t - r) dr $$

$$ \leq 3 \int_0^t E[\sigma(Y^n_r)^2] dr + 3CK^2 \int_0^t \int_r^t E[D_r(Y^n_u)^2] du dr $$

$$ + 3K^2 \int_0^t \int_r^t E[D_r(Y^n_u)^2] du(t - r) dr $$

$$ \leq 3 \int_0^t E[\sigma(Y^n_r)^2] dr + (3CK^2 + 3K^2t) \int_0^t \int_r^t E[D_r(Y^n_u)^2] du dr $$
It follows from (3.6) that
\[
\max_{0 \leq s \leq t} (Z^u_s + X^u_s) \in \mathbb{D}^{1,2},
\] (3.19)
and
\[
E[||D(\max_{0 \leq s \leq t} (Z^u_s + X^u_s))||^2_H] \leq E[\max_{0 \leq s \leq t} ||D(Z^u_s + X^u_s)||^2_H].
\] (3.20)

So we have proved (3.17). From (3.15), (3.16) and (3.17), and by Proposition 2.1.10 in [11], we conclude
\[
\max_{0 \leq s \leq t} (Z^u_s + X^u_s) \in \mathbb{D}^{1,2},
\]

and
\[
E[||D(\max_{0 \leq s \leq t} (Z^u_s + X^u_s))||^2_H] \leq E[\max_{0 \leq s \leq t} ||D(Z^u_s + X^u_s)||^2_H].
\]

It follows from (3.6) that \(Y_{t+1}^n \in \mathbb{D}^{1,2}\). Moreover,
\[
E \int_0^t ||D(Y_{u+1}^n)||^2_H du \leq 4 \int_0^t \int_0^u E[\sigma(Y^u_r)^2] dr du + 4 \int_0^t \int_0^u E(\int_r^u D_r(\sigma(Y^u_v)) dB_v)^2 dr du + 4 \int_0^t \int_0^u E(\int_r^u D_r(b(Y^u_v)) dv)^2 dr du + 4 \int_0^t \int_0^u E[D_r(\sup_{0 \leq v \leq u} (Z^u_v + X^u_v))^2] dv dr du 
\]
\[
 \leq 4t \int_0^t E[\sigma(Y^u_r)^2] dr + 4K^2(t + 1) \int_0^t \int_0^u E(D_r(Y^u_v))^2 dv dr du + 4 \int_0^t \int_0^u E[D_r(\sup_{0 \leq v \leq u} (Z^u_v + X^u_v))^2] dv dr du 
\]
\[
 \leq 4t \int_0^t E[\sigma(Y^u_r)^2] dr + 4K^2(t + 1) \int_0^t \int_0^u E(||D(Y^u_v)||^2_H dv) du + 4 \int_0^t \int_0^u E[D_r(\sup_{0 \leq v \leq u} (Z^u_v + X^u_v))^2] dv dr du 
\]
\[
 \leq 4t \int_0^t E[\sigma(Y^u_r)^2] dr + 4K^2(t + 1) \int_0^t \int_0^u E(||D(Y^u_v)||^2_H dv) du + 4 \int_0^t \int_0^u E[D_r(\sup_{0 \leq v \leq u} (Z^u_v + X^u_v))^2] dv dr du 
\]
\[
 \leq 4t \int_0^t E[\sigma(Y^u_r)^2] dr + 4K^2(t + 1) \int_0^t \int_0^u E(||D(Y^u_v)||^2_H dv) du + 4 \int_0^t \int_0^u E[D_r(\sup_{0 \leq v \leq u} (Z^u_v + X^u_v))^2] dv dr du < \infty,
\] (3.21)

where (3.17) has been used. Property (P) is proved.

Now we prove
\[
\sup_n E(||DY^n_t||^2_H) < \infty.
\] (3.22)

Note that
\[
D_r(Y^n_t) = \sigma(Y^n_{t-r}) + \int_r^t D_r(\sigma(Y^n_{s-r})) dB_s + \int_r^t D_r(b(Y^n_{s-r})) ds + \frac{\alpha}{1 - \alpha} D_r[\max_{0 \leq s \leq t} (Z^n_{s-r} + X^n_{s-r})].
\]
\[ E(||DY_t^n||_H^2) = E \int_0^t |D_rY_t^n|^2dr \]
\[ \leq 4 \{ E[\int_0^t |\sigma(Y_{r-1}^n)|^2dr] + E[\int_0^t |D_r(\sigma(Y_{r-1}^n))dB_r|^2dr] \]
\[ + E[\int_0^t |D_r(b(Y_{r-1}^n))ds|^2dr] \]
\[ + (\frac{\alpha}{1-\alpha})^2 E \int_0^t |D_r\max_{0 \leq s \leq t} [\int_0^s \sigma(Y_{r-1}^n)dB_u + \int_0^s b(Y_{r-1}^n)du]|^2dr \}\]
\[ \leq 4 \int_0^t E|\sigma(Y_{r-1}^n)|^2dr + 4 \int_0^t E(\int_0^t |D_r(\sigma(Y_{r-1}^n))|^2ds)dr \]
\[ + 4t \int_0^t E[\int_0^t |D_r(b(Y_{r-1}^n))|^2ds]dr \]
\[ + 4(\frac{\alpha}{1-\alpha})^2 E[\sup_{0 \leq s \leq t} ||D(\int_0^s \sigma(Y_{r-1}^n)dB_u + \int_0^s b(Y_{r-1}^n)du)||_H^2] \]
\[ \leq 4E[\int_0^t |\sigma(Y_{r-1}^n)|^2dr] + 4K^2 \int_0^t E[\int_0^t |D_r(Y_{r-1}^n)|^2ds]dr \]
\[ + 4K^2t \int_0^t E[\int_0^t |D_r(Y_{r-1}^n)|^2ds]dr \]
\[ + 4(\frac{\alpha}{1-\alpha})^2 \{3 \int_0^t E(\sigma(Y_{r-1}^n))^2dr \}
\[ + (3CK^2 + 3K^2t) \int_0^t \int_0^t E(D_r(Y_{r-1}^n))^2dudr \}
\[ \leq C_1 \int_0^t E|\sigma(Y_{r-1}^n)|^2dr + C_2 \int_0^t E||DY_{r-1}^n||_H^2du. \] (3.23)

Where (3.17) and (3.20) were used.

Note that \( A = \sup_n \int_0^t E|\sigma(Y_{r-1}^n)|^2dr \leq C \sup_n \int_0^t E(1 + |Y_{r-1}^n|^2)dr < \infty, \) because \( Y_n \) converges to \( Y \) uniformly w.r.t time parameter from \( n \).

Iterating (3.23) gives \( \sup_n E||DY_t^n||_H^2 < \infty. \)

Thus by Lemma 1.2.3 in \([11]\), we deduce that \( Y_t \in D^{1,2} \) and \( DY_t^n \rightarrow DY_t \) weakly in \( L^2(\Omega;H). \)

\[ \square \]

**Theorem 3.2** Assume that \( \sigma(\cdot) \) and \( b(\cdot) \) are Lipschitz continuous, and \(|\sigma(x)| > 0, \) for all \( x \in \mathbb{R}. \) Then, for \( t > 0, \) the law of \( Y_t \) is absolutely continuous with respect to Lebesgue measure.

**Proof.** According to Theorem 2.1, we just need to show that \( ||DY_t||_H^2 > 0 \) a.s.

Note that,

\[ D_rY_t = \sigma(Y_r) + \int_r^t D_r(\sigma(Y_s))dB_s + \int_r^t D_r(b(Y_s))ds + \alpha D_r(\max_{0 \leq s \leq t} Y_s), \quad r \leq t \] (3.24)
We have,

\[ (D_t Y_t)^2 \geq \frac{1}{2} \sigma(Y_t)^2 - \int_r^t D_r(\sigma(Y_s))dB_s + \int_r^t D_r(b(Y_s))ds + \alpha D_r(\max_{0 \leq s \leq t} Y_s)^2 \]

\[ \geq \frac{1}{2} \sigma(Y_t)^2 - 3\{\int_r^t D_r(\sigma(Y_s))dB_s^2 + \int_r^t D_r(b(Y_s))ds^2 + \alpha^2 D_r(\max_{0 \leq s \leq t} Y_s)^2\}. \]

Since \( \sigma(Y_t)^2 \) is continuous w.r.t \( r \), it follows that

\[ \lim_{\epsilon \to 0} \frac{1}{\epsilon} \int_{t-\epsilon}^t \sigma(Y_r)^2dr = \sigma(Y_t)^2. \]  

(3.25)

Now,

\[ E\{\int_{t-\epsilon}^t [\int_r^t D_r(b(Y_s))ds]^2 dr\} \]

\[ \leq \int_{t-\epsilon}^t E[\int_r^t |D_r(b(Y_s))|^2ds(t - r)]dr \]

\[ \leq K^2 \int_{t-\epsilon}^t \int_r^t E|D_r(Y_s)|^2(t - r)dsdr \]

\[ \leq K^2 \epsilon \int_{t-\epsilon}^t \int_r^t E|D_r Y_s|^2dsdr \]

\[ = K^2 \epsilon \int_{t-\epsilon}^t \int_r^s E|D_r Y_s|^2drds \]

\[ \leq K^2 M \epsilon^2. \]

\[ E\int_{t-\epsilon}^t [\int_r^t D_r(\sigma(Y_s))dB_s]^2 dr \leq \int_{t-\epsilon}^t E[\int_r^t D_r(\sigma(Y_s))^2ds]dr \]

\[ \leq K^2 \int_{t-\epsilon}^t E[\int_r^t (D_r Y_s)^2 ds]dr \]

\[ \leq K^2 \int_{t-\epsilon}^t \int_r^s E(D_r Y_s)^2 drds \]

\[ \leq K^2 \int_{t-\epsilon}^t \int_r^s E(D_r Y_s)^2 drds. \]

Next we show that \( \int_{s-\epsilon}^s E[(D_r Y_s)]^2 dr \leq C\epsilon \), where \( C \) is independent of \( s \). Because

\[ D_s Y_s^n = \sigma(Y_s^{n-1}) + \int_r^s D_r(\sigma(Y_u^{n-1}))dB_u + \int_r^s D_r(b(Y_u^{n-1}))du + \frac{\alpha}{1 - \alpha} D_{\max_{0 \leq u \leq s}(Z_u^{n-1} + X_u^{n-1})}, \]

we have,

\[ E\int_{s-\epsilon}^s (D_s Y_s^n)^2 dr \leq 4E\int_{s-\epsilon}^s \sigma(Y_s^{n-1})^2 dr + 4E\int_{s-\epsilon}^s [\int_r^s D_r(\sigma(Y_u^{n-1}))dB_u]^2 dr \]
\[\begin{align*}
  &+4E \int_{s-\epsilon}^{s} \int_{r}^{s} D_{r} b(Y_{u}^{n-1})du]^{2}dr \\
  &+4(\frac{\alpha}{1-\alpha})^{2}E \int_{s-\epsilon}^{s} (D_{r}(\max_{0\leq u\leq s} (Z_{u}^{n-1} + X_{u}^{n-1}))dr \\
  \leq &\begin{align*}
  &4 \int_{s-\epsilon}^{s} E[\sigma(Y_{r}^{n-1})^{2}]dr + 4 \int_{s-\epsilon}^{s} E \int_{r}^{s} D_{r}(\sigma(Y_{u}^{n-1}))^{2}dudr \\
  &+4E \int_{s-\epsilon}^{s} \int_{r}^{s} D_{r}(b(Y_{u}^{n-1}))^{2}du(s-r)]dr \\
  &+4(\frac{\alpha}{1-\alpha})^{2}E \sup_{0\leq u\leq s} \int_{s-\epsilon}^{s} [D_{r}(Z_{u}^{n-1} + X_{u}^{n-1})]^{2}dr \\
  \end{align*}
\end{align*}\]

\[\begin{align*}
  \leq &\begin{align*}
  &4 \int_{s-\epsilon}^{s} E[\sigma(Y_{r}^{n-1})^{2}]dr + 4K^{2} \int_{s-\epsilon}^{s} \int_{r}^{s} E(D_{r}(Y_{u}^{n-1}))^{2}dudr \\
  &+4K^{2}\epsilon \int_{s-\epsilon}^{s} \int_{r}^{s} E[D_{r}(Y_{u}^{n-1})]^{2}dudr \\
  &+4(\frac{\alpha}{1-\alpha})^{2}E \sup_{0\leq u\leq s} \int_{s-\epsilon}^{s} [D_{r}(\int_{0}^{u} \sigma(Y_{v}^{n-1})dB_{v} + \int_{0}^{u} b(Y_{v}^{n-1})dv)]^{2}dr \\
  \leq &\begin{align*}
  &4 \int_{s-\epsilon}^{s} E[\sigma(Y_{r}^{n-1})^{2}]dr + (4K^{2} + 4K^{2}\epsilon) \int_{s-\epsilon}^{s} \int_{r}^{s} E(D_{r}Y_{v}^{n-1})^{2}dudr \\
  &+4(\frac{\alpha}{1-\alpha})^{2}(3 \int_{s-\epsilon}^{s} E[\sigma(Y_{r}^{n-1})^{2}]dr + (3C_{1}K^{2} + 3K^{2}\epsilon) \int_{s-\epsilon}^{s} \int_{r}^{s} E(D_{r}Y_{v}^{n-1})^{2}dudr \\
  = &\begin{align*}
  &4 + 12(\frac{\alpha}{1-\alpha})^{2} \int_{s-\epsilon}^{s} E[\sigma(Y_{r}^{n-1})^{2}]dr \\
  &+4K^{2} + 4K^{2}\epsilon + 4(\frac{\alpha}{1-\alpha})^{2}(3C_{1}K^{2} + 3K^{2}\epsilon) \int_{s-\epsilon}^{s} \int_{r}^{s} E(D_{r}Y_{v}^{n-1})^{2}dudr \\
  \end{align*}
\end{align*}
\end{align*}\]

where we have used Proposition 2.1.10 in [11] from (3.26) to (3.27).

Let \(\phi_{n}(s) = E \int_{s-\epsilon}^{s} (D_{r}Y_{s}^{n})^{2}dr\), and \(\phi(s) = E \int_{s-\epsilon}^{s} (D_{r}Y_{s})^{2}dr\), then \(\phi_{n}(s) \leq C^{*}\epsilon + C^{*} \int_{s-\epsilon}^{s} \phi_{n-1}(v)dv\). Iterating it, we get

\[\begin{align*}
  \phi_{n}(s) &\leq C^{*}\epsilon(1 + C^{*}\epsilon + (C^{*}\epsilon)^{2} + \ldots + (C^{*}\epsilon)^{n}) \\
  &= C^{*}\epsilon \frac{1}{1 - C^{*}\epsilon} \\
  &\leq 2C^{*}\epsilon,
\end{align*}\]

when \(\epsilon\) is sufficiently small. Then

\[\begin{align*}
  \phi(s) &\leq \liminf_{n\to\infty} \phi_{n}(s) \leq 2C^{*}\epsilon.
\end{align*}\]
So
\[
E \int_{t-\epsilon}^{t} \left[ \int_{t}^{r} D_r(\sigma(Y_s)) dB_s \right]^2 dr \leq K^2 \int_{t-\epsilon}^{t} \phi(s) ds \leq 2C^*K^2\epsilon^2. \tag{3.32}
\]

Therefore
\[
\lim_{\epsilon \to 0} \frac{1}{\epsilon} E\{ \int_{t-\epsilon}^{t} \left[ \int_{t}^{r} D_r(\sigma(Y_s)) dB_s \right]^2 + \int_{t-\epsilon}^{t} D_r(b(Y_s)) ds \} = 0.
\]

Hence, there exists \( \epsilon_n \downarrow 0 \), such that
\[
\lim_{\epsilon_n \to 0} \frac{1}{\epsilon_n} \int_{t-\epsilon_n}^{t} \left[ \int_{t}^{r} D_r(\sigma(Y_s)) dB_s \right]^2 + \int_{t-\epsilon_n}^{t} D_r(b(Y_s)) ds \} = 0 \text{ a.s..} \tag{3.33}
\]

Set
\[
A_n = \{ \omega : \max_{0 \leq s \leq t} Y_s(w) = \max_{0 \leq s \leq t-\epsilon_n} Y_s(\omega) \},
\]
and
\[
A = \{ \max_{0 \leq s \leq t} Y_s = Y_t \}.
\]

It is clear that \( \Omega = \bigcup_{m=1}^{\infty} A_m \bigcup A \).

For \( \omega \in A_m, \forall n > m \), we have
\[
\int_{t-\epsilon_n}^{t} \alpha^2 D_r(\max_{0 \leq s \leq t-\epsilon_m} Y_s(\omega))^2 dr = 0.
\]

By the local property of the Malliavin derivative (Proposition 1.3.16 in [11]) on \( A_m \), we have
\[
\lim_{n \to \infty} \frac{1}{\epsilon_n} \int_{t-\epsilon_n}^{t} \alpha^2 D_r(\max_{0 \leq s \leq t} Y_s(\omega))^2 dr
\]
\[
= \lim_{n \to \infty} \frac{1}{\epsilon_n} \int_{t-\epsilon_n}^{t} \alpha^2(D_r(\max_{0 \leq s \leq t-\epsilon_m} Y_s(\omega))^2 dr
\]
\[
= 0. \tag{3.34}
\]

Since \( m \) is arbitrary, by (3.33) and (3.34), we conclude that
\[
\lim_{\epsilon_n \to 0} \frac{1}{\epsilon_n} \int_{t-\epsilon_n}^{t} (D_rY_t)^2 dr \geq \frac{1}{2} \sigma(Y_t)^2 > 0 \text{ a.s. on } \bigcup_{m=1}^{\infty} A_m.
\]

For \( \omega \in A \), according to (3.24), we have
\[
(1-\alpha)D_rY_t = \sigma(Y_r) + \int_{t}^{r} D_r(\sigma(Y_s)) dB_s + \int_{t}^{r} D_r(b(Y_s)) ds,
\]
\[(1 - \alpha)^2(D_rY_t)^2 \geq \frac{1}{2}\sigma(Y_r)^2 - \left[ \int_r^t D_r(\sigma(Y_s))dB_s + \int_r^t D_r(b(Y_s))ds \right]^2,\]

Since \(\alpha < 1\),
\[
(D_rY_t)^2 \geq \frac{1}{2(1 - \alpha)^2}\sigma(Y_r)^2 - \frac{1}{(1 - \alpha)^2}\left[ \int_r^t D_r(\sigma(Y_s))dB_s + \int_r^t D_r(b(Y_s))ds \right]^2.
\]

Here on \(A\),
\[
\lim_{\epsilon_n \to 0} \frac{1}{\epsilon_n} \int_{t-\epsilon_n}^t (D_rY_t)^2 dr \geq \frac{1}{2(1 - \alpha)^2} \lim_{\epsilon_n \to 0} \frac{1}{\epsilon_n} \int_{t-\epsilon_n}^t \sigma(Y_r)^2 dr = \frac{\sigma(Y_t)^2}{2(1 - \alpha)^2} > 0. \tag{3.35}
\]

Therefore
\[
\|DY_t\|_H^2 = \int_0^t (D_rY_t)^2 dr > 0 \text{ a.s.}. \tag{3.36}
\]

By Theorem 2.1, we conclude that the law of \(Y_t\) is absolutely continuous with respect to Lebesgue measure. \(\square\)

### 4 Absolute continuity of the laws of perturbed reflected diffusion processes

Consider the reflected, perturbed stochastic differential equation:
\[
X_t = \int_0^t \sigma(X_s)dB_s + \int_0^t b(X_s)ds + \alpha \max_{0 \leq s \leq t} X_s + L_t. \tag{4.1}
\]

**Definition 4.1** We say that \((X_t, L_t, t \geq 0)\) is a solution to the equation (4.1) if
(i) \(X_0 = 0, X_t \geq 0\) for \(t \geq 0\),
(ii) \(X_t, L_t\) are continuous and adapted to the filtration of \(B\),
(iii) \(L_t\) is non-decreasing with \(L_0 = 0\) and \(\int_0^t \chi\{X_s = 0\}dL_s = L_t\),
(iv) \((X_t, L_t, t \geq 0)\) satisfies the equation (4.1) almost surely for every \(t > 0\).

we need the following lemma which strengthens the result of Proposition 2.1.10 in [1].

**Lemma 4.1** Let \(X = \{X_s, 0 \leq s \leq t\}\) be a continuous process. Suppose that
(i) \(E(\sup_{0 \leq s \leq t} X_s^2) < \infty\),
(ii) for any \(0 \leq s \leq t, X_s \in \mathbb{D}^{1,2}\) and \(E(\sup_{0 \leq s \leq t} \|DX_s\|^2_H) < \infty\),

Then the random variable \(M_t = \sup_{0 \leq s \leq t} X_s\) belongs to \(\mathbb{D}^{1,2}\) and moreover,
\[
\|DM_t\|_H^2 \leq \sup_{0 \leq s \leq t} \|DX_s\|_H^2 \text{ a.s.}.
\]
Proof. Consider a countable and dense subset $S_0 = \{t_n, n \geq 1\}$ of $[0, t]$. Define $M_n = \sup\{X_{t_1}, \ldots, X_{t_n}\}$. The function $\varphi_n : \mathbb{R}^n \to \mathbb{R}$ defined by $\varphi_n(x_1, \ldots, x_n) = \max\{x_1, \ldots, x_n\}$ is Lipschitz. Therefore, we deduce that $M_n$ belongs to $\mathbb{D}^{1,2}$. Moreover, the sequence $M_n$ converges in $L^2(\Omega)$ to $M$. In order to evaluate the Malliavin derivative of $M_n$, we introduce the following sets:

\begin{align*}
A_1 &= \{M_n = X_{t_1}\}, \\
\ldots \\
A_k &= \{M_n \neq X_{t_1}, \ldots, M_n \neq X_{t_{k-1}}, M_n = X_{t_k}\}, \quad 2 \leq k \leq n.
\end{align*}

By the local property of the operator $D$, on the set $A_k$ the derivatives of the random variables $M_n$ and $X_{t_k}$ coincide. Hence, we can write

$$DM_n = \sum_{k=1}^n I_{A_k} DX_{t_k}$$

Consequently,

$$E(||DM_n||_H^2) \leq E(\sup_{0 \leq s \leq t} ||DX_s||_H^2) < \infty \quad (4.4)$$

Then, $M_t = \sup_{0 \leq s \leq t} X_s$ belongs to $\mathbb{D}^{1,2}$ and $DM_n$ weakly converges to $DM_t$ in $L^2(\Omega, P; H)$.

Now we want to show that

$$||DM_t||_H^2 \leq \sup_{0 \leq s \leq t} ||DX_s||_H^2 \quad \text{a.e..} \quad (4.5)$$

It is equivalent to prove that for every non-negative bounded random variable $\xi$,

$$E(||DM_t||_H^2 \xi) \leq E[\sup_{0 \leq s \leq t} ||DX_s||_H^2 \xi], \quad (4.6)$$

i.e.

$$\int_{\Omega} ||DM_t||_H^2 \xi dP \leq \int_{\Omega} \sup_{0 \leq s \leq t} ||DX_s||_H^2 \xi dP. \quad (4.7)$$

Define $\mu(A) = \int_A \xi dP, \quad \forall A \in \mathcal{F}$, then (4.6) is equivalent to

$$\int_{\Omega} [||DM_t||_H^2] d\mu \leq \int_{\Omega} [\sup_{0 \leq s \leq t} ||DX_s||_H^2] d\mu. \quad (4.8)$$

For $h \in L^2(\Omega, \mu; H)$, because $\xi$ is bounded, $\xi h \in L^2(\Omega, P; H)$.

Consequently, by the weak convergence of $DM_n$,

$$\int_{\Omega} [(DM_n, h)_H] d\mu = \int_{\Omega} (DM_n, \xi h)_H dP \quad \rightarrow \quad \int_{\Omega} (DM_t, \xi h)_H dP \quad = \quad \int_{\Omega} (DM_t, h)d\mu$$
This shows that $DM_n \to DM_t$ weakly in $L^2(\Omega, \mu; H)$.

Hence, we have

$$\int_\Omega (||DM_t||_H^2) d\mu \leq \liminf_{n \to \infty} \int_\Omega (||DM_n||_H^2) d\mu \leq \int_\Omega (\sup_{0 \leq s \leq t} ||DX_s||_H^2) d\mu < \infty.$$  \[ \square \]

**Theorem 4.1** Assume $0 \leq \alpha < \frac{1}{2}$. Let $(X_t, L_t, t \geq 0)$ be the unique solution to the equation (4.1). Then $X_t$ belongs to $D^{1, 2}$ for any $t \geq 0$.

**Proof.** Consider the Picard iteration, $X^0_t = 0$, $\forall t \in [0, T]$, $T \geq 0$, and let $(X^{n+1}_t, L^{n+1}_t)$ be the unique solution to the following reflected equation:

$$X^{n+1}_t = \int_0^t \sigma(X^n_s) dB_s + \int_0^t b(X^n_s) ds + \alpha \max_{0 \leq s \leq t} X^n_s + L^{n+1}_t. \quad (4.9)$$

By the reflection principle,

$$L^{n+1}_t = -\inf_{s \leq t} \{ (\int_0^s \sigma(X^n_u) dB_u + \int_0^s b(X^n_u) du + \alpha \max_{0 \leq u \leq s} X^n_u) \wedge 0 \}. \quad (4.10)$$

It was shown in [5], there exists a unique solution $X_t$ to (4.1). Next we are going to show that

$$\lim_{n \to \infty} E[\sup_{0 \leq s \leq t} |X^n_s - X^1_s|^2] = 0. \quad (4.11)$$

Now Eq(4.11) and Eq(4.9) imply that:

$$|X^{n+1}_t - X_t| \leq |\int_0^t (\sigma(X^n_s) - \sigma(X_s)) dB_s| + 2\alpha \max_{0 \leq s \leq t} |X^n_s - X_s|.$$

$$+ |\int_0^t (b(X^n_s) - b(X_s)) ds| + \max_{0 \leq s \leq t} |\int_0^s (\sigma(X^n_u) - \sigma(X_u)) dB_u|$$

$$+ \max_{0 \leq s \leq t} |\int_0^s (b(X^n_u) - b(X_u)) du|,$$

where we have used the fact:

$$L_t = -\inf_{0 \leq s \leq t} \{ (\int_0^s \sigma(X_u) dB_u + \int_0^s b(X_u) du + \alpha \max_{0 \leq u \leq s} X_u) \wedge 0 \}. \quad (4.12)$$

Consequently,

$$\max_{0 \leq s \leq t} |X^{n+1}_s - X_s| \leq 2 \max_{0 \leq s \leq t} |\int_0^s (\sigma(X^n_u) - \sigma(X_u)) dB_u|$$

$$+ 2 \max_{0 \leq s \leq t} |\int_0^s (b(X^n_u) - b(X_u)) du| + 2\alpha \max_{0 \leq s \leq t} |X^n_s - X_s|. \quad (4.13)$$
For any $\epsilon > 0$, using the elementary inequality, $(a + b)^2 \leq (1 + C_\epsilon)a^2 + (1 + \epsilon)b^2$, we obtain

\[
\max_{0 \leq s \leq t} |X_{s+1}^n - X_s|^2 \leq 4(1 + C_\epsilon)\max_{0 \leq s \leq t} \left| \int_0^s (\sigma(X_u^n) - \sigma(X_u))dB_u \right| + \max_{0 \leq s \leq t} \left| \int_0^s (b(X_u^n) - b(X_u))du \right|^2 + (1 + \epsilon)(2\alpha)^2 \max_{0 \leq s \leq t} |X_s^n - X_s|^2
\]

\[
\leq 8(1 + C_\epsilon)\max_{0 \leq s \leq t} \left| \int_0^s (\sigma(X_u^n) - \sigma(X_u))dB_u \right|^2 + \max_{0 \leq s \leq t} \left| \int_0^s (b(X_u^n) - b(X_u))du \right|^2 + (1 + \epsilon)(2\alpha)^2 \max_{0 \leq s \leq t} |X_s^n - X_s|^2.
\]

By Burkhölder inequality,

\[
E[\max_{0 \leq s \leq t} |X_{s+1}^n - X_s|^2] \leq 8(1 + C_\epsilon)\{E[\max_{0 \leq s \leq t} \left| \int_0^s (\sigma(X_u^n) - \sigma(X_u))dB_u \right|^2] + E[\max_{0 \leq s \leq t} \left| \int_0^s (b(X_u^n) - b(X_u))du \right|^2]\} + (1 + \epsilon)(2\alpha)^2 E[\max_{0 \leq s \leq t} |X_s^n - X_s|^2]
\]

\[
\leq 8(1 + C_\epsilon)(K_1C^2 + TC^2)E[\int_0^t |X_t^n - X_t|^2 du] + (1 + \epsilon)(2\alpha)^2 E[\max_{0 \leq s \leq t} |X_s^n - X_s|^2].
\]

Let $g_{n+1}(t) = E[\max_{0 \leq s \leq t} |X_{s+1}^n - X_s|^2]$. The above inequality implies

\[
g_{n+1}(t) \leq 8(K_1C^2 + TC^2)(1 + C_\epsilon) \int_0^t g_n(s) ds + (1 + \epsilon)(2\alpha)^2 g_n(t). \quad (4.14)
\]

Summing the above equations from 1 to $M$:

\[
\sum_{n=1}^M g_{n+1}(t) \leq 8(K_1C^2 + TC^2)(1 + C_\epsilon) \int_0^t \sum_{n=1}^M g_n(s) ds + (1 + \epsilon)(2\alpha)^2 \sum_{n=1}^M g_n(t). \quad (4.15)
\]

And then,

\[
\sum_{n=1}^M g_n(t) - g_1(t) \leq \sum_{n=1}^M g_{n+1}(t) \quad (4.16)
\]

\[
\leq C^* \int_0^t \sum_{n=1}^M g_n(s) ds + \beta \sum_{n=1}^M g_n(t), \quad (4.17)
\]

where $\beta = (1 + \epsilon)(2\alpha)^2$, $C^*$ is a constant. Choose $\epsilon > 0$ sufficiently small so that $\beta = (1 + \epsilon)(2\alpha)^2 < 1$. 

13
It follows from (4.17) that
\[
(1 - \beta) \sum_{n=1}^{M} g_n(t) \leq g_1(t) + C^* \int_{0}^{t} \sum_{n=1}^{M} g_n(s) ds. \tag{4.18}
\]

By Gronwall inequality,
\[
\sum_{n=1}^{M} g_n(t) \leq \frac{g_1(T)}{1 - \beta} e^{\frac{c^*}{1 - \beta} \sigma T}. \tag{4.19}
\]

Let \( M \to \infty \) to get
\[
\sum_{n=1}^{\infty} E[\max_{0 \leq s \leq t} |X^n_s - X_s|^2] < \infty. \tag{4.20}
\]

which yields that \( X^n_t \) converges to \( X_t \) in \( L^2(\Omega) \).

Let \( Y^n_s = \max_{0 \leq s \leq t} X^n_u \). We will prove the following property by induction on \( n \).

\( \mathbf{(P)} \). \( X^n_t \in \mathbb{D}^{1,2}, E(\max_{0 \leq s \leq t} ||DX^n_s||^2_{H}) < \infty, E(\max_{0 \leq s \leq t} ||DY^n_s||^2_{H}) < \infty. \)

Clearly, \( \mathbf{(P)} \) holds for \( n = 0 \).

Suppose \( \mathbf{(P)} \) holds for \( n \). We prove that it is valid for \( n + 1 \).

Now we note that
\[
\int_{0}^{t} \sigma(X^n_s) dB_s \in \mathbb{D}^{1,2}, \int_{0}^{t} b(X^n_s) ds \in \mathbb{D}^{1,2}, \tag{4.21}
\]

and
\[
D_r(\int_{0}^{t} \sigma(X^n_s) dB_s) = \sigma(X^n_r) + \int_{r}^{t} D_r(\sigma(X^n_s)) dB_s, \quad D_r(\int_{0}^{t} b(X^n_s) ds) = \int_{r}^{t} D_r(b(X^n_s)) ds.
\]

Next we prove \( \max_{0 \leq s \leq t} X^n_s \in \mathbb{D}^{1,2} \).

As
\[
\max_{0 \leq s \leq t} |X^n_s| \leq 2 \max_{0 \leq s \leq t} |\int_{0}^{s} \sigma(X^{n-1}_u) dB_u| + 2 \alpha \max_{0 \leq s \leq t} |X^{n-1}_s| + 2 \max_{0 \leq s \leq t} |\int_{0}^{s} b(X^{n-1}_u) du|,
\]

we get
\[
E(\max_{0 \leq s \leq t} |X^n_s|^2) \leq 2E[\max_{0 \leq s \leq t} |\int_{0}^{s} \sigma(X^{n-1}_u) dB_u|^2] + 12\alpha^2 E(\max_{0 \leq s \leq t} |X^{n-1}_s|^2) + 12 \int_{0}^{s} b(X^{n-1}_u)^2 du] \]
\[
+ 12 \int_{0}^{s} b(X^{n-1}_u)^2 du] \]
\[
\leq 12K_1 E[\int_{0}^{t} \sigma(X^{n-1})^2 du] + 12E(\max_{0 \leq s \leq t} |X^{n-1}_s|^2) + 12T E[\int_{0}^{t} b(X^{n-1}_u)^2 du] \]

\[14\]
\[ \leq 12(K_1 + T)C^2 E \int_0^t (1 + (X_u^{n-1})^2) du + 12\alpha^2 E(\max_{0 \leq s \leq t} |X_s^{n-1}|^2) \]
\[ \leq 12(K_1 + T)C^2 t + [12(K_1 + T)C^2 T + 12\alpha^2] E(\max_{0 \leq s \leq t} |X_s^{n-1}|^2). \]

By iteration, we see that
\[ E(\max_{0 \leq s \leq t} |X_s^n|^2) < \infty. \quad (4.22) \]

By the induction hypothesis \( E(\max_{0 \leq s \leq t} \|DX_s^n\|_H^2) < \infty \) and Proposition 2.1.10 in [11], it follows that
\[ \max_{0 \leq s \leq t} X_s^n \in \mathbb{D}^{1,2}. \quad (4.23) \]

Now we want to show
\[ L_t^{n+1} = \max_{0 \leq s \leq t} \{-(\int_0^s \sigma(X_u^n) dB_u + \int_0^s b(X_u^n) du + \alpha \max_{0 \leq u \leq s} X_u^n) \vee 0 \} \in \mathbb{D}^{1,2}. \quad (4.24) \]

Let
\[ V_s^n := -(\int_0^s \sigma(X_u^n) dB_u + \int_0^s b(X_u^n) du + \alpha \max_{0 \leq u \leq s} X_u^n) \vee 0. \quad (4.25) \]

Firstly, \( V_s^n \in \mathbb{D}^{1,2} \) by (4.21) and (4.23). Secondly,
\[ E(\max_{0 \leq s \leq t} (V_s^n)^2) \leq 3E[\max_{0 \leq s \leq t} (\int_0^s \sigma(X_u^n) dB_u)^2] + 3\alpha^2 E[\max_{0 \leq s \leq t} (X_s^n)^2] + 3E[\max_{0 \leq s \leq t} (\int_0^s b(X_u^n) du)^2] \]
\[ = 3K_1 E[\int_0^t \sigma(X_u^n)^2 du] + 3\alpha^2 E[\max_{0 \leq s \leq t} (X_s^n)^2] + 3T E[\int_0^t b(X_u^n)^2 ds] \]
\[ \leq 3(K_1 + T)C^2 E \int_0^t (1 + (X_u^n)^2) du + 3\alpha^2 E[\max_{0 \leq s \leq t} (X_s^n)^2] \]
\[ \leq 3C^2 (K_1 + T)(T + T E[\max_{0 \leq s \leq t} (X_s^n)^2]) + 3\alpha^2 E[\max_{0 \leq s \leq t} (X_s^n)^2] \]
\[ = 3C^2 T(K_1 + T) + [3C^2 (K_1 + T) T + 3\alpha^2] E[\max_{0 \leq s \leq t} (X_s^n)^2] < \infty. \quad (4.26) \]

Thirdly,
\[ E(\max_{0 \leq s \leq t} \|DV_s^n\|_H^2) = E(\max_{0 \leq s \leq t} \int_0^s (D_r(V_s^n))^2 dr) \]
\[ \leq 3(1 + C_\epsilon) E \int_0^t \sigma(X_r^n)^2 dr + 3(1 + C_\epsilon) E[\max_{0 \leq s \leq t} \int_0^s (\int_r^s D_r(\sigma(X_u^n)) dB_u)^2 dr] \]
\[ + 3(1 + C_\epsilon) E[\max_{0 \leq s \leq t} \int_0^s \int_r^s (D_r(b(X_u^n))) du)^2 dr \]
\[ + (1 + \epsilon) \alpha^2 E[\max_{0 \leq s \leq t} \int_0^s (D_r(Y_s^n))^2 dr] \]
\[ \leq 3(1 + C_\epsilon) E \int_0^t \sigma(X_r^n)^2 dr + 3(1 + C_\epsilon) \int_0^t [E \int_r^t (D_r(\sigma(X_u^n)))^2 du] dr \]
To prove we only need to prove

\[+3(1 + C_\epsilon)t \int_0^t E \int_r^t \sigma(X_u^n)2dr - (1 + \epsilon)\alpha^2 E\max_{0 \leq s \leq t} ||DY_s^n||_H^2\]

\[\leq (1 + C_\epsilon)E^t \sigma(X_u^n)^2dr + 3(1 + C_\epsilon)(1 + t)K^2 \int_0^t E||DX_u^n||_H^2du\]

\[+ (1 + \epsilon)\alpha^2 E\max_{0 \leq s \leq t} ||DY_s^n||_H^2\]

\[< \infty. \tag{4.27}\]

By Proposition 2.1.10 in [11], (4.26) and (4.27) yield that \(L_{t+1}^n \in \mathbb{D}^{1,2}\). Thus, we conclude \(X_{t+1}^n \in \mathbb{D}^{1,2}\).

Moreover,

\[D_r(X_{s+1}^n) = \sigma(X_r^n) + \int_r^s D_r(\sigma(X_u^n))dB_u + \int_r^s D_r(b(X_u^n))du + \alpha D_r\max_{0 \leq u \leq s} X_u^n + D_r(L_{s+1}^n),\]

and

\[||D(X_{s+1}^n)||_H^2 = \int_0^s (D_r(X_{s+1}^n))^2dr\]

\[\leq 5 \int_0^t \sigma(X_u^n)^2dr + 5 \int_0^s [\int_r^s D_r(\sigma(X_u^n))dB_u]^2dr + 5 \int_0^s [\int_r^s D_r(b(X_u^n))du]^2dr\]

\[+ 5 \alpha^2 ||DY_s^n||_H^2 + 5 ||DL_{s+1}^n||_H^2. \tag{4.28}\]

So

\[E\max_{0 \leq s \leq t} ||DX_{s+1}^n||_H^2 \leq 5E\int_0^t \sigma(X_u^n)^2dr + 5E\int_0^t \max_{0 \leq s \leq t} [\int_r^s D_r(\sigma(X_u^n))dB_u]^2dr\]

\[+ 5TE\int_0^t \int_r^s (D_r(b(X_u^n)))^2dudr + 5\alpha^2 E\max_{0 \leq s \leq t} ||DY_s^n||_H^2\]

\[+ 5 \alpha^2 ||DY_s^n||_H^2 + 5 ||DL_{s+1}^n||_H^2\]

\[\leq 5E\int_0^t \sigma(X_u^n)^2dr + 5K_1 \int_0^t E\int_r^t (D_r(\sigma(X_u^n)))^2dudr\]

\[+ 5TE\int_0^t \int_r^s (D_r(b(X_u^n)))^2dudr + 5\alpha^2 E\max_{0 \leq s \leq t} ||DY_s^n||_H^2\]

\[+ 5 \alpha^2 ||DY_s^n||_H^2 + 5 ||DL_{s+1}^n||_H^2\]

\[\leq 5E\int_0^t \sigma(X_u^n)^2dr + (5K_1 K_2 + 5TK^2) \int_0^t E||DX_u^n||_H^2du\]

\[+ 5\alpha^2 E\max_{0 \leq s \leq t} ||DY_s^n||_H^2 + 5 \alpha^2 ||DL_{s+1}^n||_H^2.\]

To prove

\[E\max_{0 \leq s \leq t} ||DX_{s+1}^n||_H^2 < \infty, \tag{4.29}\]

we only need to prove

\[E\max_{0 \leq s \leq t} ||DL_{s+1}^n||_H^2 < \infty. \tag{4.30}\]
According to Lemma 4.1,
\[ \|DL_s^{n+1}\|_H^2 \leq \sup_{0 \leq u \leq s} \|DV_u^n\|_H^2. \] (4.31)

Thus we have
\[ \max_{0 \leq s \leq t} \|DL_s^{n+1}\|_H^2 \leq \max_{0 \leq s \leq t} (\sup_{0 \leq u \leq s} \|DV_u^n\|_H^2) = \max_{0 \leq s \leq t} \|DV_s^n\|_H^2, \] (4.32)

and by (4.27),
\[ E[\max_{0 \leq s \leq t} \|DL_s^{n+1}\|_H^2] \leq E[\sup_{0 \leq s \leq t} \|DV_s^n\|_H^2] < \infty. \] (4.33)

Again by Lemma 4.1,
\[ \|DY_s^{n+1}\|_H^2 \leq \sup_{0 \leq u \leq s} \|DX_u^{n+1}\|_H^2. \] (4.34)

Hence,
\[ E[\max_{0 \leq s \leq t} \|DY_s^{n+1}\|_H^2] \leq E[\sup_{0 \leq s \leq t} \|DX_s^{n+1}\|_H^2] < \infty. \] (4.35)

We’ve proved property (P).

Next we prove
\[ \sup_n E[\|DX_t^{n+1}\|_H^2] < \infty. \] (4.36)

Because, for any \( \epsilon > 0 \),
\[ |D_s X_s^{n+1}|^2 \leq (1 + C_\epsilon)[3 \sigma(X_s^n)^2 + 3(\int_r^s D_r(\sigma(X_u^n))dB_u)^2 + 3(\int_r^s D_r(b(X_u^n))du)^2] + (1 + \epsilon)[2 \alpha^2 D_r(\max_{0 \leq u \leq s} X_s^n)^2 + 2 D_r(L_s^{n+1})^2]. \]

We have
\[ \|DX_s^{n+1}\|_H^2 \leq 3(1 + C_\epsilon) \int_0^s \sigma(X_u^n)^2 dr + 3(1 + C_\epsilon) \int_0^s [\int_r^s D_r(\sigma(X_u^n))dB_u]^2 dr + 3(1 + C_\epsilon) \int_0^s [\int_r^s D_r(b(X_u^n))du]^2 dr + 2(1 + \epsilon) \int_0^s D_r(\max_{0 \leq u \leq s} X_u^n)^2 dr + (1 + \epsilon) \int_0^s D_r(L_s^{n+1})^2 dr = 3(1 + C_\epsilon) \int_0^s \sigma(X_u^n)^2 dr + 3(1 + C_\epsilon) \int_0^s [\int_r^s D_r(\sigma(X_u^n))dB_u]^2 dr + 3(1 + C_\epsilon) \int_0^s [\int_r^s D_r(b(X_u^n))du]^2 dr + 2(1 + \epsilon) \int_0^s \|DY_s^n\|_H^2 + (1 + \epsilon) \|DL_s^{n+1}\|_H^2 \leq 3(1 + C_\epsilon) \int_0^s \sigma(X_u^n)^2 dr + 3(1 + C_\epsilon) \int_0^s [\int_r^s D_r(\sigma(X_u^n))dB_u]^2 dr \]
where Lemma 4.1 was used in the last step. Hence, using Ito’s Isometry we have

\[ E(\sup_{0 \leq s \leq t} ||DX_s^{n+1}||_H^2) \leq 3(1 + C_\epsilon) \int_0^t \sigma(X_r^n)^2 dr + 3K_1K^2(1 + C_\epsilon) \int_0^t (D_r(X_u^n))^2 dr
\]

\[ + 3TK^2(1 + C_\epsilon) \int_0^t (D_r(X_u^n))^2 dr u du
\]

\[ + 2(1 + \epsilon)\alpha^2 E[\sup_{0 \leq u \leq t} ||DX_u^n||_H^2] + 2(1 + \epsilon)E[\sup_{0 \leq u \leq t} ||DV_u^n||_H^2]
\]

\[ = 3(1 + C_\epsilon)E \int_0^t \sigma(X_r^n)^2 dr + 3(K_1 + T)K^2(1 + C_\epsilon) \int_0^t E\|DX_u^n\|_H^2 du
\]

\[ + 2(1 + \epsilon)\alpha^2 E\sup_{0 \leq s \leq t} ||DX_s^n||_H^2 + 2(1 + \epsilon)\{3(1 + C_\epsilon)E \int_0^t \sigma(X_r^n)^2 dr
\]

\[ + 6(1 + C_\epsilon)K^2 \int_0^t E\|DX_u^n\|_H^2 du + (1 + \epsilon)\alpha^2 E[\sup_{0 \leq s \leq t} ||DY_s^n||_H^2]\}

\[ \leq 3(1 + C_\epsilon) \int_0^t E[\sigma(X_r^n)^2] dr + 3(K_1 + T)K^2(1 + C_\epsilon) \int_0^t E\|DX_u^n\|_H^2 du
\]

\[ + 2(1 + \epsilon)\alpha^2 E[\sup_{0 \leq s \leq t} ||DX_s^n||_H^2] + 6(1 + \epsilon)(1 + C_\epsilon)E \int_0^t \sigma(X_r^n)^2 dr
\]

\[ + 12(1 + \epsilon)(1 + C_\epsilon)K^2 \int_0^t E\|DX_u^n\|_H^2 du + (1 + \epsilon)\alpha^2 E[\sup_{0 \leq s \leq t} ||DX_s^n||_H^2]
\]

\[ = (9 + 6\epsilon)(1 + C_\epsilon) \int_0^t E[\sigma(X_r^n)^2] dr + 2(2 + \epsilon)(1 + \epsilon)\alpha^2 E[\sup_{0 \leq s \leq t} ||DX_s^n||_H^2)
\]

\[ + [12K^2(1 + \epsilon)(1 + C_\epsilon) + 3K^2(K_1 + T)(1 + C_\epsilon)] \int_0^t E\|DX_u^n\|_H^2 du(4.37)
\]

Note that \(\sup_n \int_0^t E[\sigma(X_r^n)^2] dr \leq C \sup_n \int_0^t E(1 + |X_r^n|^2) dr < \infty\).

Let

\[ \psi_n(t) = E(\sup_{0 \leq s \leq t} ||DX_s^n||_H^2).
\]

Then from (4.37), we have

\[ \psi_{n+1}(t) \leq c_1 + c_2 \psi_n(t) + c_3 \int_0^t \psi_n(u) du,
\]

where \(c_2 = 2(2 + \epsilon)(1 + \epsilon)\alpha^2 < 1\) when \(\epsilon > 0\) is sufficiently small, according to \(\alpha < \frac{1}{2}\).

Iterating this inequality, we obtain

\[ \sup_n \psi_{n+1}(t) < \infty, \text{ i.e. } \sup_n E(\max_{0 \leq s \leq t} ||DX_s^{n+1}||_H^2) < \infty.
\]
According to Lemma 1.2.3 in [11], \( X_t \in \mathbb{D}^{1,2} \).

To study the absolute continuity of the law, we need the following comparison theorem.

**Lemma 4.2** Assume \( 0 \leq \alpha < \frac{1}{2} \). Let \( X_t \) be the solution to the perturbed, reflected stochastic differential equation

\[
X_t = \int_0^t \sigma(X_s)dB_s + \int_0^t b(X_s)ds + \alpha \max_{0 \leq s \leq t} X_s + L_t.
\]

Let \( Y_t \) be the solution to the reflected stochastic equation \( Y_t = \int_0^t \sigma(Y_s)dB_s + \int_0^t b(Y_s)ds + \tilde{L}_t \).

Then, we have that \( Y_t \leq X_t \) a.e.

**Proof.**

Let \( \Delta_t = Y_t - X_t = \tilde{L}_t - L_t + \int_0^t (b(Y_s) - b(X_s))ds + \int_0^t (\sigma(Y_s) - \sigma(X_s))dB_s - \alpha \max_{0 \leq s \leq t} X_s. \)

There exists a strictly decreasing sequence \( \{a_n\}_{n=0}^{\infty} \subseteq (0,1) \) with \( a_0 = 1, \lim_{n \to \infty} a_n = 0 \) and \( \int_0^{a_n-1} \frac{1}{c \alpha} dc = n, \) for every \( n \geq 1. \) For each \( n \geq 1, \) there exists a continuous function \( \rho_n \) on \( R \) with support in \((a_n, a_n-1)\) so that \( 0 \leq \rho_n(x) \leq \frac{2}{n \alpha x^2} \) holds for every \( x > 0, \) and \( \int_{a_n}^{a_n-1} \rho_n(x)dx = 1. \) Then the function

\[
\phi_n(x) = \int_0^{[x]} \int_0^y \rho_n(u)dudyI_{(0,\infty)}(x), x \in R.
\]

is twice continuously differentiable, with \( 0 \leq \phi_n'(x) \leq 1 \) and \( \lim_{n \to \infty} \phi_n(x) = x^+ \) for \( x \in R. \)

By the Ito rule:

\[
\phi_n(\Delta_t) = \int_0^t \phi_n'(\Delta_s)d\tilde{L}_s - \int_0^t \phi_n'(\Delta_s)dL_s - \alpha \int_0^t \phi_n'(\Delta_s)d(\max_{0 \leq u \leq s} X_u)
\]
\[+ \int_0^t \phi_n'(\Delta_s)(b(Y_s) - b(X_s))ds + \int_0^t \phi_n'(\Delta_s)(\sigma(Y_s) - \sigma(X_s))dB_s
\]
\[+ \frac{1}{2} \int_0^t \phi_n''(\Delta_s)(\sigma(Y_s) - \sigma(X_s))^2 ds
\]
\[
\leq \int_0^t \phi_n'(\Delta_s)d\tilde{L}_s + C \int_0^t \phi_n'(\Delta_s)I_{\{Y_s > X_s\}}|Y_s - X_s|ds
\]
\[+ \int_0^t \phi_n'(\Delta_s)(\sigma(Y_s) - \sigma(X_s))dB_s
\]
\[+ \frac{1}{2} \int_0^t \phi_n''(\Delta_s)(\sigma(Y_s) - \sigma(X_s))^2 ds
\]

Hence,

\[
E[\phi_n(\Delta_t)] \leq E \int_0^t \phi_n'(\Delta_s)X_{\{Y_s > 0\}}d\tilde{L}_s + CE \int_0^t (Y_s - X_s)^+ ds
\]
\[+ \frac{1}{2} E \int_0^t \phi_n''(\Delta_s)(\sigma(Y_s) - \sigma(X_s))^2 ds
\]
Then, by reflection principle,

Let

Now,

Proof. It is sufficient to prove \(||DX_t||_{H^2}^2 > 0\) a.s. according to Theorem 2.1.

Now,

Let

Then, by reflection principle,

\[ L_t = \max_{0 \leq s \leq t} -\{ \int_0^s \sigma(X_u)dB_u + \int_0^s b(X_u)du + \alpha \max_{0 \leq u \leq s} X_u \} \] \[ D_r X_t = \sigma(X_r) + \int_r^t D_r(\sigma(X_s))dB_s + \int_r^t D_r(b(X_s))ds + \alpha D_r(\max_{0 \leq s \leq t} X_s) + D_r(\max_{0 \leq s \leq t} V_s). \] \[ (D_r X_t)^2 \geq \frac{1}{2} \sigma(X_r)^2 - \left[ \int_r^t D_r(\sigma(X_s))dB_s + \int_r^t D_r(b(X_s))ds + \alpha D_r(\max_{0 \leq s \leq t} X_s) + D_r(\max_{0 \leq s \leq t} V_s) \right]^2 \]

Similar as in Section 3, we have

\[ \lim_{\epsilon \to 0} \frac{1}{\epsilon} E \left\{ \int_{t-\epsilon}^t \left[ \int_r^t D_r(\sigma(X_s))dB_s \right]^2 + \left[ \int_r^t D_r(b(X_s))ds \right]^2 \right\} dr = 0. \]

Hence, there exists \( \epsilon_n \downarrow 0 \), such that

\[ \lim_{\epsilon_n \to 0} \frac{1}{\epsilon_n} \int_{t-\epsilon_n}^t \left[ \int_r^t D_r(\sigma(X_s))dB_s \right]^2 + \left[ \int_r^t D_r(b(X_s))ds \right]^2 dr = 0 \text{ a.s..} \] (4.38)

Let

\[ A_n = \{ \omega : \max_{0 \leq s \leq t} X_s = \max_{0 \leq s \leq t-\epsilon_n} X_s \}, \]

\[ A = \{ \omega : \max_{0 \leq s \leq t} X_s = X_t \}. \]

Then,

\[ \Omega = \cup_{m=1}^\infty A_m \cup A. \] (4.39)
Let

\[ B_n = \{ \omega : \max_{0 \leq t \leq T_n} V_s = \max_{0 \leq s \leq t-\epsilon_n} V_s \}, \]

\[ B = \{ \omega : \max_{0 \leq s \leq t} V_s = V_t \}. \]

We have,

\[ \Omega = \bigcup_{n=1}^{\infty} B_n \cup B. \]  (4.40)

Firstly, if \( \omega \in A_m \cap B_n \), for \( l > m, n \), we have

\[ \int_{t-\epsilon_l}^{t} (D_r(\max_{0 \leq s \leq t-\epsilon_m} X_s))^2 dr = 0, \]

\[ \int_{t-\epsilon_l}^{t} (D_r(\max_{0 \leq s \leq t} V_s))^2 dr = 0. \]

This gives

\[ \lim_{l \to \infty} \frac{1}{\epsilon_l} \int_{t-\epsilon_l}^{t} \alpha^2 (D_r(\max_{0 \leq s \leq t} X_s))^2 dr = 0, \]

\[ \lim_{l \to \infty} \frac{1}{\epsilon_l} \int_{t-\epsilon_l}^{t} (D_r(\max_{0 \leq s \leq t} V_s))^2 dr = 0, \]

a.e. on \( A_m \cap B_n \).

Hence,

\[ \lim_{l \to \infty} \frac{1}{\epsilon_l} \int_{t-\epsilon_l}^{t} (D_r(X_t))^2 dr \geq \frac{1}{2} \sigma(X_t)^2 > 0, \]  (4.41)

on \( A_m \cap B_n \).

Secondly, if \( \omega \in A_m \cap B \), for fixed \( m \geq 1 \),

\[ X_t = \int_0^t \sigma(X_s) dB_s + \int_0^t b(X_s) ds + \alpha \max_{0 \leq s \leq t} X_s + \left[ - \left( \int_0^t \sigma(X_s) dB_s + \int_0^t b(X_s) ds + \alpha \max_{0 \leq s \leq t} X_s \right) \big|_0^t \right]. \]

If \( \int_0^t \sigma(X_s) dB_s + \int_0^t b(X_s) ds + \alpha \max_{0 \leq s \leq t} X_s > 0 \), then \( X_t = \int_0^t \sigma(X_s) dB_s + \int_0^t b(X_s) ds + \alpha \max_{0 \leq s \leq t} X_s \).

In this case, we can see from the proof in Section 3 that \( ||DX_t||^2_H > 0 \).

If \( \int_0^t \sigma(X_s) dB_s + \int_0^t b(X_s) ds + \alpha \max_{0 \leq s \leq t} X_s < 0 \), then \( X_t = 0 \).

But \( \{X_t = 0\} \) is an event with probability zero. Indeed, according to Lemma 4.2, \( 0 \leq Y_t \leq X_t \).

According to Proposition 4.1 in [9], the law of \( Y_t \) is absolutely continuous with respect to the Lebesgue measure, and then we have \( P(Y_t = 0) = 0 \). Therefore, \( P(X_t = 0) \leq P(Y_t = 0) = 0 \).

Thirdly, if \( \omega \in A \cap B_n \), for fixed \( n \geq 1 \),

\[ D_r X_t = \sigma(X_r) + \int_r^t D_r(\sigma(X_s)) dB_s + \int_r^t D_r(b(X_s)) ds + \alpha D_r(X_t) + D_r(\max_{0 \leq s \leq t-\epsilon_n} V_s). \]

Hence,

\[ (1-\alpha)D_r X_t = \sigma(X_r) + \int_r^t D_r(\sigma(X_s)) dB_s + \int_r^t D_r(b(X_s)) ds + D_r(\max_{0 \leq s \leq t-\epsilon_n} V_s). \]
Thus, for \( l > n \),
\[
\frac{1}{\epsilon_l} \int_{t-\epsilon_l}^{t} (1 - \alpha)^2 (D_r X_t)^2 \, dr \geq \frac{1}{2} \sigma(X_t)^2 - \frac{3}{\epsilon_l} \int_{t-\epsilon_l}^{t} \left[ \int_{r}^{t} D_r(\sigma(X_s)) \, dB_s \right]^2 \, dr \\
\quad - \frac{3}{\epsilon_l} \int_{t-\epsilon_l}^{t} \left[ \int_{r}^{t} D_r(b(X_s)) \, ds \right]^2 \, dr - \frac{3}{\epsilon_l} \int_{t-\epsilon_l}^{t} [D_r(\max_{0 \leq s \leq t-\epsilon_n} V_s)]^2 \, dr.
\]
This implies,
\[
\lim_{l \to \infty} \frac{1}{\epsilon_l} \int_{t-\epsilon_l}^{t} (1 - \alpha)^2 (D_r X_t)^2 \, dr \geq \frac{1}{2} \sigma(X_t)^2 > 0 \quad \text{on a.e. } A \cap B_n. \quad (4.42)
\]
Finally, let \( \omega \in A \cap B \). Then
\[
X_t = \int_{0}^{t} \sigma(X_s) \, dB_s + \int_{0}^{t} b(X_s) \, ds + \alpha X_t + L_t, \quad (4.43)
\]
\[
L_t = -(\int_{0}^{t} \sigma(X_s) \, dB_s + \int_{0}^{t} b(X_s) \, ds + \alpha X_t) \vee 0. \quad (4.44)
\]
If \( \int_{0}^{t} \sigma(X_s) \, dB_s + \int_{0}^{t} b(X_s) \, ds + \alpha X_t \geq 0 \), then \( L_t = 0 \), and \( X_t = \int_{0}^{t} \sigma(X_s) \, dB_s + \int_{0}^{t} b(X_s) \, ds + \alpha X_t \).
In this case we see that \( ||DX_t||_H^2 > 0 \) from the proof in section 3.
If \( \int_{0}^{t} \sigma(X_s) \, dB_s + \int_{0}^{t} b(X_s) \, ds + \alpha X_t \ < 0 \), then \( L_t = -(\int_{0}^{t} \sigma(X_s) \, dB_s + \int_{0}^{t} b(X_s) \, ds + \alpha X_t) \), and \( X_t = 0 \). But \( X_s \leq X_t \) for \( 0 \leq s \leq t \) on \( A \). Therefore we deduce that \( X_s = 0 \), for \( 0 \leq s \leq t \).
Note that
\[
X_s = \int_{0}^{s} \sigma(X_u) \, dB_u + \int_{0}^{s} b(X_u) \, du + \alpha X_s + L_s. \quad (4.45)
\]
Thus we have
\[
- \int_{0}^{s} \sigma(X_u) \, dB_u = \max_{0 \leq u \leq s} \left\{ -(\int_{0}^{u} \sigma(X_v) \, dB_v + \int_{0}^{u} b(X_v) \, dv + \alpha X_u) \vee 0 \right\} + \int_{0}^{s} b(X_u) \, du, \quad s \leq t. \quad (4.46)
\]
Notice that the right side is a process of bounded variation, so the equation \((4.46)\) is not possible. Combining all the cases, we get \( ||DX_t||_H^2 > 0 \). a.s. \( \Box \)

**References**

[1] Ph.Carmona, F.Petit, M. Yor, Beta variables as times spent in \([0, \infty)\) by certain perturbed Brownian motions, J.London Math. Soc. 58(1998)239-256.

[2] L. Chaumont, R.A. Doney, Pathwise uniqueness for perturbed versions of Brownian motion and reflected Brownian motion, Probab. Theory Related Fields 113(1999)519-534.

[3] B.Davis, Brownian motion and random walk perturbed at extrema, Probab. Theory Related Fields 113(1999)501-518.
[4] R.A. Doney, Some calculations for perturbed Brownian motion, in: Séminaire de Probabilités XXXII, in: Lecture Notes in Mathematics, 1998, pp.231-236.

[5] R.A. Doney, Tusheng Zhang, Perturbed Skorohod equations and perturbed reflected diffusion processes, Ann.I.H.Poincare-PR41(2005)107-121.

[6] N. Ikeda, S. Watanabe, Stochastic Differential Equations and Diffusion Processes, Second ed., North-Holland/Kodansha, 1989.

[7] J.F. Le Gall, M. Yor, Excursions browniennes et carrés de processus de Bessel, C.R. Acad. Sci. Paris Sér. I 303(1986)73-76.

[8] J.F. Le Gall, M. Yor, Enlacements du mouvement brownien autour des courbes de l’espace, Trans. Amer. Math. Soc. 317(1990)687-7722.

[9] D. Lépingle, D. Nualart, M. Sanz, Dérivation stochastique de diffusions réfléchies. Annales de l’Institut Henri Poincaré, Probabilités et Statistiques, Vol.25, 1983,p. 283-305.

[10] P.L. Lions, A.S. Sznitman, Stochastic differential equations with reflecting boundary conditions, Comm. Pure Appl. Math. 37(1984)511-537.

[11] D. Nualart, The Malliavin Calculus and Related Topics, Second edition, Springer 2006.

[12] M. Perman, W. Werner, Perturbed Brownian motions, Probability Theory and Related Fields 108(1997)357-383.

[13] M. Sanz-Sole, Malliavin Calculus with Applications to Stochastic Partial Differential Equations, EPFL-Press 2005.

[14] W. Werner, Some remarks on perturbed Brownian motion, in: Séminaire de Probabilités XXIX, in:Lecture Notes in Mathematics, Vol.1613, 1995, pp.37-43.

[15] T.S. Zhang, On the strong solutions of one-dimensional stochastic differential equations with reflecting boundary, Stochastic Process. Appl. 50(1994)135-147.

[16] T.S. Zhang and W.A. Zheng, SPDEs Driven by Space-time white noise in high dimensions: absolute continuity of the law and convergence of solutions, Stochastics and Stochastic Reports, Vol.75, No.3, June 2003, pp.103-128.