Some old movies become classics - a case study determining the scientific value of ROV inspection footage on a platform on Australia's North West Shelf

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Abstract

The global oil and gas industry holds a vast archive of Remotely Operated Vehicle (ROV) inspection footage potentially containing useful long-term data on marine biological communities. With the upcoming era of decommissioning of oil and gas structures, it is timely to assess the usefulness of this footage for researching these communities. We used ROV inspection footage to characterize the sessile invertebrates and fishes associated with the Goodwyn Alpha Production Platform (GWA) on the North West Shelf of Australia between depths of 10 and 125 m during 2006 and 2008. Depth was a major driver of invertebrate assemblages, most likely due to specific requirements such as light, and differences between years were most likely from the physical detachment of species by cyclones and internal waves. Phototrophic species were mostly limited to the upper 50 m of the platform, including the hard coral Pocillopora sp. and the soft corals Nephthea sp. and Scleronephthya sp. In contrast, heterotrophic species including sponges, anemones, bryozoans, hydroids, bivalves such as Lopha folium and the hard coral Tubastrea spp., were distributed across all depths. We observed 1791 fish from at least 10 families and 19 species, including commercial species such as crimson seaperch (Lutjanus erythropterus), red emperor (L. sebae), saddle-tailed seaperch (L. malabaricus), mangrove jack (L. argentimaculatus) and trevally (Caranx spp.). Fish density increased significantly with depth during 2008, from a mean of 23 fish/50 m² between 10 and 25 m to 3373 fish/50 m² at 125 m, where small unidentified baitfish were abundant. The highest densities of commercial species occurred between 25 and 75 m depth, suggesting that mid-depth platform sections had high habitat value, a consideration when selecting decommissioning options. The greatest difficulties using the video were the poor lighting and resolution that inhibited our ability to identify sessile species with high taxonomic precision. However, the footage was useful for evaluating high-level biodiversity of the platform, understanding how fish and invertebrate communities changed with depth and comprehending the dynamic nature of the invertebrate community over time. Understanding the habitat value of structures will be necessary for making environmentally sound decommissioning decisions in the future.

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Some Old Movies Become Classics – A Case Study Determining the Scientific Value of ROV Inspection Footage on a Platform on Australia’s North West Shelf

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invertebrate communities changed with depth and comprehending the dynamic nature of the invertebrate community over time. Understanding the habitat value of structures will be necessary for making environmentally sound decommissioning decisions in the future.

Keywords: ROV video, sessile invertebrates, commercial fish species, fish, oil platform, rigs to reef, decommissioning

INTRODUCTION

Subsea infrastructure of the oil and gas industry (hereafter ‘oil structures’) has proliferated in continental boundaries worldwide, with reportedly more than 7,500 structures around the world (Parente et al., 2006). Over the next two decades, most oil structures will reach end of life and require decommissioning. Decommissioning has historically involved complete removal, due to the assumption that removal represents best environmental practice. However, evidence from some oil and gas-producing nations indicates structures can act as artificial reefs, providing habitat for endangered cold-water corals (Bell and Smith, 1999; Gass and Roberts, 2006) and by developing dense encrusting invertebrate communities (Forteath et al., 1982; Friedlander et al., 2014; Kolian et al., 2017) that provide habitat for other marine organisms, including commercially valuable fish species (Rooker et al., 1997; Stanley and Wilson, 1997; Love et al., 2000). These discoveries suggest that under at least some circumstances, removal of oil and gas infrastructure will result in the loss of valuable habitat for ecologically and commercially important species. In Australia, and most parts of the world, these offshore platforms are not fished and are surrounded by a 500 m exclusion zone making them quasi-marine protected areas or no-take zones. Given some of these platforms have been in place for decades, they have the potential to play a significant role in the population dynamics of key species at a local or even regional scale.

The potential for oil structures to provide important habitat has led to the development of ‘rigs-to-reefs’ (RTR) programs in some regions. RTR programs operate on a ‘win-win’ premise, whereby obsolete structures are recycled as artificial reefs, while also providing substantial cost savings to industry (Macreadie et al., 2011). RTR programs have become increasingly popular since their inception in Louisiana in 1986, and have spread to numerous other US states, as well as Southeast Asian nations (Kaiser, 2006). The phrase ‘RTR’ is now frequently used to describe any decommissioning practice that does not involve complete removal of oil structures, including leaving part of a structure in situ.

Despite growing popularity, RTR programs remain controversial. They have historically been viewed as an opportunity for oil companies to avoid their removal obligations, particularly by environmental NGOs and the general public (Jorgensen, 2012). This has resulted in strong opposition to RTR conversions in particular regions (e.g., the North Sea), and heated public debate concerning the instigation of any new RTR program. Before a new program can be established, considerable scientific evidence is required to determine whether oil structures will provide a net benefit to the marine environment (Schroeder and Love, 2004). For example, over a decade of research was required to demonstrate that oil platforms in Southern California provide important habitat for overfished rockfish populations before legislation allowing RTR conversions could be passed in that region (Assembly Bill 2503, 2010).

In Australia, the North West Shelf (NWS) Venture is supported by numerous platforms, well heads, production areas and support facilities connected by hundreds of kilometers of pipelines. Due to a dearth of research, very little is known about the environmental benefits of Australia’s offshore oil and gas infrastructure and there is little information to inform policy development or guide upcoming decommissioning decisions. Recent studies suggest that infrastructure on the NWS is well colonized, providing habitat for sessile marine invertebrates and fishes (McLean et al., 2017, 2018b). However, understanding the habitat value of these structures with respect to decommissioning decisions will require an understanding of the variability and transiency of these communities, both with depth and through time. With particular reference to platforms, understanding the distribution of the sessile invertebrate community over depth will be important when considering decommissioning options (Claisse et al., 2015). For example, one decommissioning option for platforms is ‘topping,’ that is, following the removal of the underwater supporting frame (known as the jacket) is removed down to a safe navigable depth (~30 m) and placed on the seabed alongside the structure (Macreadie et al., 2011). Would this negatively impact on the habitat value of the structure? Has the most productive and sunlit habitat been lost to greater depths? How will this affect associated fish communities and interactions with surrounding ecosystems? Answers to these questions are critical for determining the habitat value of oil structures and the relative environmental benefit of alternative decommissioning options (Fowler et al., 2014).

An inexpensive approach to assessing the habitat value of oil and gas infrastructure is to use industry inspection footage. Oil structures are regularly inspected for operational and engineering purposes using underwater video cameras mounted on Remotely Operated Vehicles (ROVs). The oil and gas industry worldwide holds a vast archive of inspection footage dating back decades (Macreadie et al., 2018). Although collected in an imperfect scientific manner, this archive contains footage of marine fauna associating with oil and
gas structures and surrounding habitats, making it a potential source of long-term data for biological observation (Macreadie et al., 2018; McLean et al., 2018a). The footage also covers a depth range rarely achieved by independent scientific investigations, spanning from the surface to beyond 1,000 m depth. Such data sources are rare in our oceans and particularly valuable, given the impacts of climate change on biological communities and the limited information available on deep sea ecosystems.

To our knowledge, we present here the first study of the biological communities associated with an offshore oil and gas platform in Australia and contribute to the few other studies carried out on NWS oil and gas infrastructure (Fowler and Booth, 2012; Pradella et al., 2014; McLean et al., 2017, 2018b). The aims of this paper are to determine: (1) the composition of the invertebrate and fish communities associated with the platform; (2) how the fish community changes with depth; and (3) how the invertebrate community changes with depth and time. While addressing these aims, we provide a preliminary evaluation of the usefulness of industry ROV footage for researching platform communities. Understanding how these communities change over depth and time will be necessary for assessing the habitat value of this and other platforms, which will be essential for making environmentally sound decommissioning decisions in the near future.

**MATERIALS AND METHODS**

The Goodwyn Alpha production platform (GWA), operated by Woodside Energy Ltd., is located 135 km north-west of Karratha, WA, Australia, on the NWS in approximately 130 m of water. The platform is located in a subtropical environment and in the path of the southward flowing Holloway Current that transports warm, low salinity water southwards into the Leeuwin Current. Seawater temperature in the upper 100 m ranges between 22 and 30°C, peaking in April each year (Bahmanpour et al., 2016). GWA was commissioned in 1995 and has a complex subsurface structure consisting of horizontal, vertical and diagonal beams or members making up the steel frame or jacket. The jacket is periodically inspected by engineers using ROV footage for structural integrity and the extent of attached invertebrates which can result in increased hydrodynamic load on the structure.

A total pool of 8.5 h of digital footage of the north face or Row G of the GWA jacket was available from 2006 and 2008 (Figure 1). This face is on the leeward side of the platform and protected from the prevailing winds and swells from the south west. The footage was collected by ROV during standard industry inspections of the infrastructure. During inspections, the ROV was positioned so that the online inspection engineer had a clear view of the member being inspected, and could determine its condition. This also provided a useful view for surveying both fishes and attached sessile invertebrates. As the quality of the footage was variable and not taken for scientific purposes, the total footage pool was pre-screened to identify footage that adhered to the following criteria: (1) between 3 and 5 m from structure; (2) water visibility ≥5 m and; (3) ROV moving at a slow, constant speed. We estimate that 24% of the video pre-screened was unsuitable for our purposes.

**Sessile Invertebrate Surveys**

Sessile invertebrate communities were surveyed from multiple, replicate quadrats taken from survey footage of the horizontal members of the jacket (Figure 1). In 2006, surveys were carried out along horizontal members at depths of 15 m, 50 m, 90 m, and 125 m. Footage was taken between midnight and 03:00 h (Western Standard Time, WST) on August 18th, 2006. In 2008, footage was taken between 15:00 h and 18:00 h on the 20th December, with the exception of footage from 90 m depth, which was taken on the 12th December at 10:00 h. There was no suitable video footage available from the horizontal member at 125 m in 2008. The horizontal members were last cleaned in December 1998, therefore the ‘age’ of the attached community was approximately 10 years by December 2008, notwithstanding changes in composition through natural disturbances (e.g., the passage of cyclones). There was no footage available from Row G between the years we surveyed.

Survey or transect lengths varied according to the length of horizontal members which increased with depth (Supplementary Table S1a). In 2006, transects ranged between 30 m and 65 m. In 2008, while there was no suitable video footage available from the horizontal member at 125 m in 2008, at least 70% of the remaining members were surveyed for sessile invertebrates, resulting in survey lengths of between 30 m and 50 m on the upper three members.

Still frames from the transects of the horizontal members were used to set quadrats within which the sessile invertebrates were identified and their coverage quantified. To optimize the number of quadrats from the footage, frames were not random but captured sequentially every 15–30 s as the previous frame of the component was cleared from the field of view. Frames were captured using VLC media player (v. 2.0.5) and then imported into Coral Point Count with Excel Extensions V4.1 (CPCe) (Kohler and Gill, 2006). Within CPCe, a square quadrat border was set for each sample to the approximate diameter of horizontal member taken from engineering diagrams of the platform. This yielded quadrats of approximately 1.25 m² at 15 m and 50 m depth, 1.5 m² at 90 m and 1.75 m² at 125 m. At least 10 replicate quadrats were examined at each depth in each year, with the exception of 125 m depth (Figure 1 and Supplementary Table S1a). Prior to the video analysis, we determined the optimal number of random points per quadrat necessary to most accurately determine sessile invertebrate cover while reducing counting effort. To do so, we chose nine quadrats from GWA with low, moderate and high cover of the easily identified coral species *Tubastrea* sp. We then scored the presence of *Tubastrea* sp. in quadrats within CPCe under an increasing number of random points that increased in 5 point steps to 50, and constructed a performance curve of score standard deviation versus random point number (Brown et al., 2004). We found that from 25 random points per quadrat, increased counting effort did not yield better estimations of *Tubastrea* coverage, thus chose this number as optimal for describing sessile invertebrate cover. To aid identification, the corresponding video was played...
concurrently when growth on the still frames was indistinct under the points. Where possible, we used still photographs of members taken during the survey and photographs of samples returned to the surface from related engineering reports from GWA in 2008 to confirm video identifications (Woodside, 2008; Surespek Iss PTY Ltd, 2009). For classifying and identifying the invertebrates, we used the Collaborative and Automated Tools for Analysis of Marine Imagery (CATAMI) system, which introduces an Australian-wide acknowledged, standardized terminology for annotating benthic substrates and biota in marine imagery (Althaus et al., 2015).

**Fish Surveys**

Video used in assessing fish density included that of horizontal, vertical, and diagonal jacket members over a greater range of depths than used for the invertebrates to increase encounter rates and to account for movement (Figure 1). Fishes were surveyed from footage taken on the August 18th, 2006 and December 20th, 2008. Footage from 2006 was taken at night (midnight – 05:30 h, WST) while footage from 2008 was taken during daylight hours (15:30–18:00 h). Transect lengths varied according to member length and the available useable footage, but at least three transects were examined within each depth category (Supplementary Table S1b). In 2006, we surveyed approximately 146 m$^2$ of platform, with transect lengths ranging between 20 and 40 m. In 2008, suitable footage was lacking from depths $>90$ m. Therefore we used frames from stationary footage taken at the base of the legs at 125 m on the northeast and northwest corners of Row G (Figure 1). This footage was taken 3 months earlier on September 12th, 2008. Consequently, in 2008, we surveyed approximately 366 m$^2$ of platform with transects of between 19 and 30 m length (Supplementary Table S1b).

**FIGURE 1** | Schematic diagram of Goodwyn Alpha (GWA) platform showing its structure including the horizontal, vertical, and diagonal cross beams surveyed for marine life. Horizontal beams or members at 15, 50, 90, and 125 m were surveyed for attached sessile invertebrates in 2006 and 2008, with the exception of the 125 m depth in 2008 when footage was not available. Fish transects are shown as blue (2006) and red bars (2008). Red squares indicate the location of fish counts from stationary images conducted at the base of the structure during 2008. Vertical arrows indicate the depth zones used for analysis in each year. The number associated with the camera icon indicates the number of quadrats per horizontal member used in the invertebrate surveys in each year. Drawing not to scale.
The depth categories differed between years due to the lack of suitable replicates required for statistical analyses in the 50–75 m category in 2006, requiring the combination of transects between the 25 and 100 m. Some footage along the horizontals used for the invertebrate surveys were reused for surveying fish where suitable.

For each transect, fish counts began from a freeze frame generally at one end of the member. We then advanced the footage frame by frame and counted additional fish as they entered the view in front of, or to the side of the member (Caselle et al., 2002). Individuals were identified to the lowest possible taxonomic level. In 2008, fish were counted from freeze frames of the seafloor infrastructure as this footage was largely stationary. To standardize the reporting of fish densities, surface areas of the members were calculated from known dimensions of the infrastructure (GWA specifications, Woodside Energy Ltd.) and densities are reported as abundance per 50 m².

Statistical Analysis
Percent cover of invertebrate species was calculated for each quadrat within CPCs and each quadrat was used as an individual sample. Invertebrate communities were compared between depths and years using the statistical packages PRIMER (v6.1.14) and PERMANOVA (v1.0.40) (Clarke, 1993; Clarke and Gorley, 2006; Anderson, 2017). Percent coverage was square-root transformed to ensure that the most abundant species did not unduly influence comparisons and a similarity matrix was constructed using the Bray–Curtis similarity coefficient. Permutational multivariate analysis of variance (PERMANOVA) was used to test the significance of differences (alpha: 0.05, 9999 permutations) between community composition at each depth within and between years. Pairwise comparisons between depths within and between years were performed using pairwise PERMANOVA tests which employ a pseudo-t statistic. A Multi-Dimensional Scaling (MDS) plot was used to visualize differences in the marine growth among depths and between years. Similarity Percentage analysis (SIMPER) within PRIMER was used to identify which species/groups contributed most to community differences between depths and years. A cut-off of 80% species contribution was used in SIMPER analyses.

As our footage in alternate years was either diurnal or nocturnal, and as time of day is known to affect fish behavior, fish communities were compared among depths within each year separately. Multivariate analyses were similar to those used for the sessile invertebrates. Fish density was log(x + 1) transformed and a Bray–Curtis similarity matrix was constructed. Community composition was compared among depths using the PERMANOVA routine and SIMPER analysis was used to identify species contributing up to 80% community differences between depths. Total fish density was compared among depths in 2008 using a one-way ANOVA, following inspection of the data for normality and homogeneity of variances. Tukey’s post hoc tests were used to identify differences between specific depth categories.

RESULTS
Sessile Invertebrates
Community Composition
We identified the invertebrate communities into broad functional and taxonomic categories, genera and species where possible (Table 1 and Figure 2). The broadest functional categories included two underlying encrusting or enveloping invertebrate and crustose algal layers. These layers were overlaid with hard and soft corals, anemones, bivalves and bryozoans and/or hydroids. Few taxa could be identified to higher taxonomic categories due to low camera resolution and lighting; however, we have included the CATAMI codes for each taxa where possible (Table 1).

The encrusting layer on the upper 50 m of the structure consisted primarily of a calcite layer of intact bivalves and bleached shells (Figure 2A). While the bivalves were not always clearly distinguishable in the footage, physical samples from industry reports in 2008–2009 supported these observations and confirmed that above approximately 60 m depth, the encrusting layer consisted primarily of living and dead bivalves, including species such as Pinctada sp. and Lopha folium of up to 190 mm diameter (Surespek Iss PTY Ltd., 2009). On the lower structure, from depths of >50 m, the enveloping layer was a colorless mat with filamentous appearance but with few other distinguishing features. Calcareous coralline algae and sponges were also distinguishable but could not be identified further.

Scleractinian stony or hard corals and octocorals (soft corals) were identified in both years (Table 1). Hard corals included two species of Tubastrea (Figure 2A) and one of Pocillopora sp. and photographs from industry samples confirm these observations (Surespek Iss PTY Ltd, 2009). Soft corals included two species of Scleronephthya and one of Nephthea (Figure 2B). The remaining cnidaria were the solitary true anemones, consisting of a fleshy stalk and a ring of tentacles surrounding a central mouth (Figure 2C). As we could not distinguish between bryozoans and hydroids with any confidence due to the poor resolution and lighting in the footage, we combined them into one category.

Community Changes With Depth and Time
Overall, we found a progressive change in the sessile invertebrate community with depth in both years, with the greatest changes evident between depths less than and greater than 50 m (Table 1 and Figures 3A,B). In 2006, coverage at 15 m depth was dominated by the calcite encrusting layer (42.0%), along with 37.7% of hard coral (mostly 24.1% of Tubastrea sp. 2 and 12.7% of Pocillopora sp.) and 15.8% soft corals (mostly 12.5% of Scleronephthya sp. 1). Coverage at 50 m was dominated by soft corals, including Scleronephthya sp. 1 and Nephthea sp. (51.4% and 7.8%, respectively), the calcite layer (22.5%) and the hard coral Tubastrea sp. 2 (10.5%). At 90 and 125 m, filamentous mat coverage was 51.8% and 65.4%, respectively, hard corals were absent and soft coral cover was 42.0% at 90 m and 28.8% at 125 m. Groups with minor coverage included unidentified hard and soft corals (0.5% and ≤8.5%, respectively), sponges at 90 m depth (1.2%) and the bryozoans/hydroids...
TABLE 1 | Invertebrate taxa and their mean percent cover on the horizontal members of Goodwyn Alpha platform in 2006 and 2008 (standard deviation shown in brackets).

| Invertebrates              | Year 2006 and depth (m) | Year 2008 and depth (m) | CAAB#    |
|----------------------------|-------------------------|-------------------------|----------|
|                            | 15                      | 50                      | 90       | 125   | 15     | 50     | 90      |         |
| Calcite encrusting layer   | 42.0 (14.9)             | 22.5 (22.8)             |          | 32.5 (15.4) | 2.8 (5.0) |          |         | 80 300034 |
| Coraline algae             | 12.6 (10.7)             | 0.4 (1.3)               |          | 80 300034 |
| Sponges                    | 1.2 (2.7)               | 5.2 (9.1)               | 50.0 (17.0) | 10 000921 |
| Filamentous mat            | 51.8 (14.0)             | 65.4 (27.9)             |          | 14.7 (21.9) |
| **Hard corals**            |                         |                         |          |         |         |         |         |         |
| **Tubastrea sp. 1**        | 0.8 (1.7)               |                         |          | 6.5 (10.0) | 11 290901 |
| **Tubastrea sp. 2**        | 24.1 (15.3)             | 10.5 (9.5)              |          | 22.2 (15.3) | 45.6 (14.3) | 11 290901 |
| **Pocillopora sp.**        | 12.7 (13.5)             |                         |          | 19.7 (13.9) | 2.4 (7.6) | 11 290912 |
| **Unidentified**           | 0.5 (1.6)               |                         |          | 6.5 (10.9) | 6.4 (14.0) | 3.7 (5.6) |
| **Soft corals**            |                         |                         |          |         |         |         |         |         |
| **Scleronephthya sp. 1**   | 12.5 (14.8)             | 51.4 (14.3)             |          | 11 168911 |
| **Scleronephthya sp. 2**   | 39.3 (14.0)             | 19.9 (30.8)             | 0.4 (1.3) | 0.3 (1.2) | 11 168911 |
| **Nephthea sp.**           | 3.3 (10.5)              | 7.8 (14.1)              | 0.8 (1.7) | 0.4 (1.3) | 19.2 (18.8) | 11 168911 |
| **Unidentified**           | 1.9 (2.7)               | 8.5 (10.1)              |          |          | 11 168909 |
| **Others**                 |                         |                         |          |         |         |         |         |         |
| True anemones              |                         |                         | 17.6 (20.3) | 30.2 (19.1) | 11 229903 |
| **Total bryozoan/hydrroids** | 4.2 (10.2)             | 7.3 (15.3)              | 5.1 (9.6) | 5.6 (7.4) | 20 000905/ 11 001000 |

Collaborative and Automated Tools for Analysis of Marine Imagery (CATAMI) CAAB codes are provided where possible.

FIGURE 2 | Attached invertebrates on Goodwyn Alpha platform and associated fishes, including (A) the white calcite encrusting layer with bleached bivalves and the hard coral Tubastrea sp. 2, (B) the soft coral Nephthea spp. with the orange hard coral Tubastrea sp. 2, (C) true anemones, sponges and the filamentous layer, (D) bannerfish (Heniochus sp.), (E) trevally (Caranx spp.) and (F) a school of unidentified juvenile fish and a red emperor (Lutjanus sebae).
FIGURE 3 | Sessile attached invertebrate coverage and changes in coverage with depth and between years illustrated by (A) mean percent cover by the major invertebrate taxa/groups and (B) multidimensional scaling plot (MDS) of the sessile invertebrate species on the horizontal members of Goodwyn Alpha platform in 2006 and 2008. In the MDS, each data point represents a replicate quadrat. The MDS is constructed from Bray–Curtis similarities based on the percent coverage of different groups/species. There was no footage available for analysis of the sessile invertebrates from 125 m in 2008.
group which were present over all depths at ≤7.3% coverage (Table 1).

The percent coverage of the sessile invertebrate community differed significantly among depths in 2006 (PERMANOVA: pseudo-$F = 31.461, P = 0.0001$). Pairwise comparisons between progressive depths indicated that the community differed between depths of 15 m, 50 m, and 90 m. The community coverage between 15 and 50 m was significantly different (pairwise PERMANOVA, pseudo-$t = 2.6, P = 0.0007$), primarily due to an increase in coverage of *Scleronephthya* sp. 1 and a decrease in the coverage of the calcite layer and the hard corals *Tubastrea* sp. 2 and *Pocillopora* sp. which together contributed 79% of the dissimilarity between depths (SIMPER, Table 2). Community coverage did not differ between 90 and 125 m (pseudo-$t = 1.2905, P = 0.2345$). However, the community at 90 m differed considerably from that at 50 m (PERMANOVA: 50 vs. 90 m, pseudo-$t = 6.2183, P = 0.0001$; 50 vs. 125 m, pseudo-$t = 5.2418, P = 0.0001$). The difference in communities between 50 and 90 m was primarily due to the increase in coverage of the filamentous mat and the decrease in coverage of the soft coral *Scleronephthya* sp. 1 at 90 m, together contributing 47% of the dissimilarity between depths (Table 2).

An increase in the cover of *Scleronephthya* sp. 2, a decrease in the cover of the calcite layer and a decrease in the hard coral *Tubastrea* sp. 2 at 90 m contributed to the remaining dissimilarity of 88%.

A similar pattern of community change across depth was observed in 2008 (Figures 3A,B and Table 1). Overall, at 15 m, coverage was dominated by hard corals at 54.9% (mostly *Tubastrea* sp. 2 and *Pocillopora* sp. at 22.2% and 19.7%, respectively) and the calcite layer (32.5%). At 50 m, the hard corals (mostly *Tubastrea* sp. 2, 45.6%), the soft coral *Nepthia* sp. (19.2%), and the anemones (17.6%) predominated. At 90 m, coverage was dominated by sponges (50.0%), anemones (30.2%) and filamentous mat (14.7%). Bryozoans/hydroids were apparently absent at any depth in 2008.

Community coverage differed significantly among depths in 2008 (PERMANOVA: pseudo-$F = 39.897, P = 0.0001$) (Figures 3A,B). Like 2006, pairwise comparisons confirmed community differences between each adjacent depth zone. The community coverage at 15 m and 50 m was significantly different (PERMANOVA: pseudo-$t = 4.6912, P = 0.0002$), due primarily to a decrease in coverage by the calcite layer which contributed most the dissimilarity between depths (18.8%; Table 2). Otherwise, a

### Table 2

Percent mean cover and Similarity Percentage results (SIMPER) for sessile invertebrates contributing up to 80% of the dissimilarity in coverage between adjacent depths on the Goodwyn Alpha platform in 2006 and 2008.

| Year       | Depth comp | Group/Taxa         | % mean cover at depth | Contribution to dissimilarity % | Cumulative % contribution |
|------------|------------|--------------------|-----------------------|---------------------------------|--------------------------|
| 2006       | 15 m       | *Scleronephthya* sp. 1 – SC | 12.5                  | 27.01                           | 27.01                    |
|            |            | Calcite encrusting layer | 42.0                  | 19.61                           | 46.62                    |
|            |            | *Tubastrea* sp. 2 – HC    | 24.1                  | 16.48                           | 63.1                     |
|            |            | *Pocillopora* sp. – HC    | 12.7                  | 16.01                           | 79.12                    |
|            |            | *Nepthia* sp. – SC        | 3.3                   | 9.39                            | 88.51                    |
|            | 50 m       | Filamentous mat          | 0                     | 24.14                           | 24.14                    |
|            |            | *Scleronephthya* sp. 1 – SC | 51.4                  | 23.1                            | 47.24                    |
|            |            | *Scleronephthya* sp. 2 – SC | 39.3                  | 19.81                           | 67.06                    |
|            |            | Calcite encrusting layer | 22.5                  | 12.29                           | 79.35                    |
|            |            | *Tubastrea* sp. 2 – HC    | 10.5                  | 8.18                            | 87.52                    |
|            | 90 m       | Filamentous mat          | 0                     | 43.57                           | 43.57                    |
|            |            | *Scleronephthya* sp. 2 – SC | 19.3                  | 23.76                           | 67.33                    |
|            |            | Unidentified – SC        | 1.9                   | 19.13                           | 86.46                    |
| 2008       | 15 m       | Calcite encrusting layer | 32.5                  | 18.83                           | 18.83                    |
|            |            | *Pocillopora* sp. – HC    | 19.7                  | 14.97                           | 33.8                     |
|            |            | *Nepthia* sp. – SC        | 0                     | 14.58                           | 48.39                    |
|            |            | True anemones             | 0                     | 11.93                           | 60.31                    |
|            |            | Coralline algae – Enc     | 12.6                  | 10.82                           | 71.14                    |
|            |            | *Tubastrea* sp. 2 – HC    | 22.2                  | 10.19                           | 81.33                    |
|            | 50 m       | *Tubastrea* sp. 2 – HC    | 45.6                  | 27.77                           | 27.77                    |
|            |            | Sponge – Enc              | 5.2                   | 22.88                           | 50.65                    |
|            |            | *Nepthia* sp. – SC        | 19.2                  | 15.4                            | 66.06                    |
|            |            | True anemones             | 17.6                  | 13.69                           | 79.74                    |

SC, soft coral; HC, hard coral.
decrease in coverage by *Pocillopora* sp. and coralline algae and an increase in coverage by *Nephthea* sp., anemones and *Tubastrea* sp. 2 at 50 m compared to 15 m contributed between 10 and 15% each of the remaining dissimilarity between the two depths. Percent coverage by groups again changed significantly between the 50 and 90 m depths (PERMANOVA: pseudo-\( t = 5.8171, P = 0.0001 \)). The decrease in *Tubastrea* sp. 2 and *Nephthea* sp. at 90 m contributed 43.2% of this dissimilarity with a further 36.6% of dissimilarity explained by an increase in cover of sponges and anemones at that depth.

We found a substantial change in the percent coverage of the attached invertebrates between years (PERMANOVA: pseudo-
\( F = 4.883, P = 0.0002 \)) ([Figures 3A,B](#fig3)). Overall, this change was evident in the decrease in soft corals and bryozoans/hyroids at all depths and a general increase in cover by hard coral, sponges and true anemones in 2008 ([Table 3](#tab3) and [Figure 3A](#fig3)). The community at 15 m differed significantly between years (PERMANOVA: pseudo-
\( t = 2.4481, P = 0.0003 \)) and was due to changes in several groups/species contributing similar percentages to the dissimilarity (between 10 and 19%, [Table 3](#tab3)). Taxa with greater coverage in 2008 at 15 m included coralline algae and the hard corals, *Pocillopora* sp. and *Tubastrea* sp. 1. Those with less coverage in 2008 included *Scleronephthya* sp. 1, *Tubastrea* sp. 2 and the calcite layer. Coverage also differed between years at 50 m depth (PERMANOVA: pseudo-
\( t = 3.9192, P = 0.0001 \)). At this depth, a large decrease in the mean coverage by the soft coral *Scleronephthya* sp. 1 (which was not observed in 2008) contributed 26.7% to the dissimilarity between years, along with a decrease in the calcite layer coverage which accounted for a further 13% of dissimilarity ([Table 3](#tab3)). Large increases in mean cover of *Tubastrea* sp. 2, *Nephthea* sp. and anemones contributed 18.2%, 14.2%, and 12.8%, respectively, to the remaining dissimilarity between years at 50 m depth. Finally, the invertebrate coverage also differed between years at 90 m (PERMANOVA: pseudo-
\( t = 9.0934, P = 0.0001 \)). The large increase in coverage of sponges and anemones during 2008 contributed 45.0% of dissimilarity between years, whilst the apparent disappearance of bryozoans/hyroids and the decrease of the filamentous mat contributed 23.3% and 19.2%, respectively.

### Fishes

We identified and counted 1791 individual fish from at least 10 families and 19 species ([Table 4](#tab4) and [Figures 2D–F](#fig2)). Where fish could not be identified to species, they were grouped into broader categories; ‘small cryptic fish’ included those fish sheltering in marine growth cover, and ‘baitfish’ were those found only at the maximum depth and in large schools. Some fish species could not be reliably distinguished from each other and were grouped together, such as the genera of the unidentified surgeonfish and unicornfish and the bluefin/bigeye trevally (*Caranx melampygus* or *C. sexfasciatus*) which at times could not be distinguished from each other due to varying light levels and speed of movement.

In 2006, abundance and diversity of fish were low, with only 119 individuals from at least six families observed ([Table 4](#tab4)). Mean fish densities ranged between 8 fish/50 m\(^2\) in the upper water column to a maximum of 14 fish/50 m\(^2\) in the 25–100 m depth category, but we found no significant difference in total fish density among depths (ANOVA, \( F_{2,7} = 0.06769, P = 0.9351 \)). Unidentified surgeonfish (*Acanthurus* spp.) and false bluefin trevally (*Carangoides orthogrannum*) were most abundant between 10 and 25 m, reaching 5.1 and 1.3 fish per

### TABLE 3 | Dissimilarity and percent mean cover of attached invertebrates between depths in 2006 and 2008.

| Depth (m) | Group/Taxa | % mean cover | Contribution to dissimilarity % | Cumulative % contribution |
|----------|------------|--------------|---------------------------------|---------------------------|
|          | 2006 | 2008 | 2006 | 2008 | 2006 | 2008 |
| 15       | Scleronephthya sp. 1 – SC | 12.5 | 0 | 18.59 | 18.59 | 18.59 |
|          | Coraline algae – Enc | 0 | 12.6 | 18.22 | 36.81 |
|          | Pocillopora sp. – HC | 12.7 | 19.7 | 16.12 | 52.93 |
|          | Tubastrea sp. 2 – HC | 24.1 | 22.1 | 13.96 | 66.89 |
|          | Tubastrea sp. 1 – HC | 0.8 | 6.5 | 10.46 | 77.35 |
|          | Calcite encrusting layer | 42.0 | 32.5 | 10.09 | 87.44 |
|          | 2006 | 2008 | 2006 | 2008 | 2006 | 2008 |
| 50       | Scleronephthya sp. 1 – SC | 51.4 | 0 | 26.71 | 26.71 |
|          | Tubastrea sp. 2 – HC | 10.5 | 45.6 | 18.18 | 44.89 |
|          | Nephthea sp. – SC | 7.8 | 19.2 | 14.19 | 59.08 |
|          | Calcite encrusting layer | 22.5 | 2.8 | 13.41 | 72.49 |
|          | Anemone | 0 | 17.6 | 12.84 | 85.33 |
|          | 2006 | 2008 | 2006 | 2008 | 2006 | 2008 |
| 90       | Sponges | 1.2 | 50.0 | 25.58 | 25.58 |
|          | Bryozoans/hyroids | 5.1 | 0 | 23.3 | 48.87 |
|          | Anemone | 0 | 30.2 | 19.31 | 68.18 |
|          | Filamentous mat | 51.8 | 14.7 | 19.24 | 87.42 |

Dissimilarity comparisons were made within depth categories using SIMPER analyses. Only taxa contributed up to 80% of the in coverage shown. SC, soft coral; HC, hard coral.
50 m², respectively. Almaco jack (Seriola rivoliana) were the most abundant fish in depths > 25 m (reaching 9.1 per 50 m²) and contributed 80% of the total fish observed in that year, although they were not observed in 2008. Other fish present in 2006 but not observed in 2008 were a unicornfish, a tall-fin batfish (Platax teira) and a giant moray (Gymnothorax javanicus) which was observed sheltering under a jacket anode.

In 2008, we observed 1671 fish from at least 8 families and 16 species (Table 4). Total fish density increased significantly with depth in 2008, from a total of 22.6 fish/50 m² at 10–25 m to 3373.6 fish/50 m² at 125 m (ANOVA, F₃,₁₂ = 56.529, P < 0.001). Density at 125 m was significantly greater than all other depths (Tukey’s tests, all P < 0.001), however, patterns among other depths were less distinct. Total fish density at 10–25 m was significantly lower than that at 25–50 m (100.8 fish/50 m², Tukey’s test, P = 0.034), but densities at 10–25 m did not differ from 50 to 75 m (87.5 fish/50 m²). Tukey’s test, P = 0.108). There was also no difference in fish density between 25–50 and 50–75 m (Tukey’s test, P = 0.881).

There were also significant differences in fish community composition across the depth categories in 2008 (PERMANOVA, pseudo-F₃,₁₂ = 5.8658, P = 0.001). Unlike fish density, we found there was no significant difference in the community composition of fishes between the 10–25 m and the 25–50 m (PERMANOVA, pseudo-t = 1.2349, P = 0.372), or between the 25–50 m and 50–75 m depth categories (PERMANOVA, pseudo-t = 1.5156, P = 0.156). However, community composition differed significantly between 10–25 m and 50–75 m (PERMANOVA, pseudo-t ≥ 2.3472, all P ≤ 0.028).

### Table 4

| Depth category (m) | 10–25 | 25–100 | 100–125 | 10–25 | 25–50 | 50–75 | 125 |
|-------------------|-------|--------|---------|-------|-------|-------|-----|
| Transect length (m) (all replicates) | 41 | 51 | 54 | 38 | 55 | 54.3 | + |
| Transect area (m²) (all replicates) | 118 | 184 | 192 | 176 | 190 | 393 | 14 |

| Family | Genus and species | Common name |
|-------|------------------|-------------|
| Carangidae | Seriola rivoliana | Almaco jack |
| Carangidae | Carangoides orthogrammus | False bluefin trevally |
| Carangidae | Caranx sexfasciatus or Caranx melampygus | Bluefin/bigeye trevally |
| Lutjanidae | Lutjanus argentimaculatus | Mangrove jack |
| Lutjanidae | Lutjanus erythopterus | Crimson sea perch |
| Lutjanidae | Lutjanus bohar | Red bass |
| Lutjanidae | Lutjanus sebae | Red emperor |
| Lutjanidae | Lutjanus malabaricus | Saddle-tailed sea perch |
| Serranidae | Cephalopholis sonnerati | Tomato cod |
| Serranidae | Pseudanthias rubronotus | Red-bar anthias |
| Chaetodontidae | Heniochus diphreutes | Schooling bannerfish |
| Acanthuridae | Acanthurus spp. | Unidentified surgeonfish |
| Acanthuridae | Acanthurus dussumieri | Ornate surgeonfish |
| Acanthuridae | Naso hexacanthus | Sleek unicornfish |
| Acanthuridae | Naso spp. | Unicornfish |
| Apogonidae | Apogon sp. | Cardinalfish |
| Pomacanthidae | Pomacanthus imperator | Emperor angelfish |
| Monacanthidae | Unknown | Filefish unidentified |
| Ephippidae | Platax teira | Tail-fin batfish |
| Muraenidae | Gymnothorax javanicus | Giant moray |

**Total density depth category (50 m²)**

| | 2006 | 2008 |
|----------------|-------|-------|
| 10–25 | 3.1 (3.2) | 31.0 (21.9) |
| 25–100 | 5.1 (4.5) | 3.2 (1.3) |
| 100–125 | 3.1 (3.2) | 0.9 (1.0) |
| 10–25 | 0.3 (0.6) | 3.2 (1.3) |
| 25–50 | 0.5 (0.8) | 3.9 (1.4) |
| 50–75 | 0.5 (0.8) | 0.6 (0.1) |
| 125 | 0.5 (0.8) | 0.7 (0.1) |

**Standard deviation shown in brackets. + indicates snapshots of infrastructure at 125 m where transect footage was unavailable.**
SIMPER analysis described the species/groups that contributed most to the similarities within depths and significant dissimilarities between depths during 2008 (Table 5a,b). The community at 0–25 m was characterized by small cryptic fish, false bluefin trevally and unidentified surgeonfish, with the former two groups having mean densities of 10.9 and 5.5 fish/50m², respectively, and accounting for 80.1% of the similarity at this depth (Table 5a). The community at 25–50

| TABLE 5 | (a) Mean densities of fish taxa that contributed to similarities of each depth category according to SIMPER analysis, and (b) fish taxa that contributed to dissimilarities between depths where significant differences were found. |
|---|---|---|---|
| (a) Species/group | Mean density (50 m²) | Contribution to similarity % | Cumulative contribution % |
| 10–25 m | | | |
| Small cryptic fish | 10.9 | 47.79 | 47.79 |
| False bluefin trevally | 5.5 | 32.26 | 80.05 |
| Surgeon (unidentified) | 3.2 | 19.95 | 100 |
| 25–50 m | | | |
| Bluefin/bigeye trevally | 49.7 | 36.38 | 36.38 |
| Schooling bannerfish | 31.0 | 23.78 | 60.16 |
| Small cryptic fish | 10.3 | 21.44 | 81.6 |
| 50–75 m | | | |
| Schooling bannerfish | 51.0 | 82.34 | 82.34 |
| Bluefin/bigeye trevally | 19.4 | 11.04 | 93.38 |
| 125 m | | | |
| Baitfish | 2554.7 | 70.56 | 70.56 |
| Red bass | 27.3 | 15.64 | 86.19 |
| (b) Species/group | Mean density (50 m²) | Contribution to dissimilarity % | Cumulative contribution % |
| 10–25 m | 50–75 m | |
| Baitfish | 0 | 2554.7 | 29.34 | 29.34 |
| Schooling bannerfish | 51.0 | 0 | 17.04 | 46.39 |
| Cardinalfish | 0 | 436.7 | 10.59 | 56.97 |
| Red bass | 0.1 | 27.3 | 10.18 | 67.15 |
| Red-bar anthias | 0 | 350.0 | 10.04 | 77.19 |
| Bluefin/bigeye trevally | 19.4 | 0 | 7.32 | 84.52 |
| 50–75 m | 125 m | |
| Baitfish | 2554.7 | 0 | 25.29 | 25.29 |
| Schooling bannerfish | 51.0 | 0 | 11.58 | 44.17 |
| Cardinalfish | 436.7 | 0 | 9.34 | 57.21 |
| Red-bar anthias | 350.0 | 0 | 8.86 | 66.07 |
| Red bass | 27.3 | 0 | 8.81 | 74.88 |
| Small cryptic fish | 0 | 10.3 | 7.75 | 82.44 |
| 125 m | 25–50 m | |
| Baitfish | 2554.7 | 0 | 32.59 | 32.59 |
| Cardinalfish | 436.7 | 0 | 11.27 | 44.17 |
| Red bass | 27.3 | 0 | 10.99 | 65.43 |
| Red-bar anthias | 350.0 | 0 | 9.38 | 75.81 |
| Small cryptic fish | 0 | 10.9 | 7.05 | 82.86 |

Only taxa contributing up to at least 80% are shown.
m was dominated by bluefin/bigeye trevally and schooling bannerfish (Heniochus diphreutes), with mean densities of 49.7 and 31.0 fish/50 m², respectively. Along with the small cryptic fish, these taxa accounted for 81.6% of the similarity at this depth. Between 50 and 75 m, schooling bannerfish reached 51.0 fish/50 m² and accounted for 82.3% similarity within the depth category and bluefin/bigeye trevally were again in high density at this depth, reaching 19.4 fish/50 m². The significant difference in the fish communities between 10–25 m and 50–75 m (reported above) was due to greater density of the schooling bannerfish and the bluefin/bigeye trevally (31.1% and 13.3% contribution to dissimilarity) (Table 5b) and lower density of the small cryptic fishes and false bluefin trevally (15.4% and 11.5%, respectively) at 50–75 m.

At 125 m, the community was typified by baitfish and red bass (Lutjanus bohar) which contributed 70.6% and 15.6%, respectively, of the similarity within the depth category (Table 5a). Baitfish were found exclusively at this depth and at a high mean density of 2554.7 fish/50 m². Red-bar anthias (Pseudanthias rubrizonatus) and cardinalfish (Apogon sp.) were also found only at this depth and in high densities (350.0 and 436.7 fish/50 m², respectively, Table 5b). SIMPER analysis indicated that the significant differences in fish composition between 125 m and all other depth categories (reported above) were largely due to these taxa that were specific to this depth (Table 5b). Baitfish contributed up to 32.6% dissimilarity while red-bar anthias (P. rubrizonatus) and cardinalfish (Apogon sp.) contributed up to 22.6% dissimilarity combined. Bluefin/bigeye trevally and schooling bannerfish were also important contributors to the differences between the 125 m category and all others, being present in relatively high densities at shallower depths but not recorded at 125 m.

**DISCUSSION**

To our knowledge, this is the first published study of attached invertebrate species and fish communities associated with an operational oil and gas platform on Australia’s North West Shelf. Furthermore, this study provides an insight into the usefulness of archival industry ROV footage for assessing marine communities associated with oil and gas structures.

Although not collected for scientific purposes, archived ROV inspection footage is a potentially valuable resource for environmental science as the footage incidentally captures flora and fauna associated with oil structures during inspections. The operator’s video archive, for example, contains footage of infrastructure since its establishment in 1995, with multiple visits to the same structures over extended time periods. Some footage dates back to the 1970s, potentially providing rare long-term datasets from an offshore environment that is challenging to study independently. Specific structures on the platform are easily identified and can be revisited over many years, allowing for fine scale studies of biological communities at specific points. Furthermore, footage is available from a range of subsea infrastructure including platforms, risers, pipelines and wellheads at a variety of depths over wide geographical ranges under the influence of different oceanographic regimes. Industry-collected footage may therefore provide an important tool for assessing the biodiversity associated with oil structures, how this diversity may change over time, how infrastructure functions as an artificial reef, and how communities on infrastructure interact with surrounding marine ecosystems. Despite some limitations using industry-collected ROV footage (outlined below), we were able to: (1) broadly identify the major elements of the invertebrate community inhabiting the GWA platform and estimate their coverage on horizontal members; (2) identify changes in the attached community with depth and time, and (3) identify differences in fish density and distribution with depth. It is important to note that our data are meant to illustrate the potential usefulness of ROV archival footage, rather than a comprehensive attempt to assess long term temporal trends on and around this platform.

**Attached Invertebrate Communities**

Sessile invertebrates could only be placed into broad taxonomic categories, mostly due to the poor resolution of the video. Despite this issue, we were able to determine patterns of community composition with depth along the platform and between the years using data obtained from the industry footage.

It appeared that at least some of the factors affecting depth zonation and community composition of sessile communities on natural reefs, including light availability, prey, competition, and habitat characteristics (Karlson and Cornell, 1998), also influenced their distribution on GWA. On the platform, we found autotrophic species mostly limited to 50 m depth, most likely reflecting light availability necessary for photosynthesis. These included the coraline algae, the hard coral Pocillopora sp. and the soft corals. The exception was the soft coral Scleronephthya sp. 2 which was unusual in its deeper distribution from 50 m depth, indicating this species requires less light and/or was an azooxanthellate species.

In contrast, heterotrophic species were distributed across all depths. The most significant heterotrophs in terms of surface cover in the upper 50 m of the platform were the bivalves within the calcite encrusting layer. Whilst indistinct in the video, this community appeared to be largely comprised of both living and bleached bivalve shells. Bivalves are common on platforms and large numbers have been previously observed on platforms in the North Sea, the Gulf of Mexico, California coastal waters and on wellheads in the North West Shelf of Western Australia (George and Thomas, 1979; Love et al., 1999; van der Stap et al., 2016; McLean et al., 2018b). The occurrence of these filter feeders on members in the upper 50 m of the platform likely mirrors the occurrence of their planktonic prey in the upper sunlit layers of water column.

Other abundant heterotrophs included the two species of Tubastrea. These hard corals lack photosynthetic zooxanthellae yet contributed much of the coral cover in the upper 50 m of the platform in both years. Tubastrea is often found attached to oil and gas platforms in the Gulf of Mexico, West Africa and in the South Atlantic (Friedlander et al., 2014; Sammarco et al., 2015; Creed et al., 2017). At depths ≥50 m, heterotrophic species such as sponges, bryozoans, hydroids and anemones with reduced
that disrupted offshore industry activities. Between August 2006 and 2008 surveys are designed to take member and jacket orientation into account. Tropical Cyclones Kara and George, were classified as category 4 and 5, respectively, by the Australian Bureau of Meteorology Tropical Cyclone Category System, with category 5 being the most severe. Cyclones cause mixing and cooling throughout the water column to 100 m depth and the generation of very strong, oscillating near-inertial internal waves, with currents reaching up to 1.5 ms$^{-1}$ at the bottom, but typically 0.5 ms$^{-1}$ throughout the entire water column for a period of up to 9 days (Rayson et al., 2015). The major difference in the attached communities between years was a decrease in soft coral cover across all depths, especially notable in the two species of Scleronephthya and the loss of other soft attached species such as the foliaceous bryozoans/hyroidans. Changes in the sessile invertebrate communities and their biomass due to environmental forcing has also been observed on platforms in the Gulf of Mexico due to seasonal flooding from coastal bays and the Mississippi River (George and Thomas, 1979). Thus, it appears that the invertebrate communities of platforms are dynamic in nature, shaped over time by environmental influences. This dynamism may have implications for the effectiveness of platforms to act as artificial reefs if susceptible invertebrates like soft corals play a functional role in the biological communities associated with platforms.

Compared to other studies on platforms (George and Thomas, 1979; Forteath et al., 1982; Friedlander et al., 2014), we did not identify a diverse invertebrate community. This is likely due at least in part to our reliance on video footage and the inability to collect physical specimens. The resolution of video footage was generally too poor to provide quality close-up images that would be required for identifications to lower taxonomic levels. The footage available for this study and our survey approach may also have some inherent biases. Spatial orientation of platform members can influence colonization and this seems particularly important to bryozoan and coral recruitment as these animals seemingly prefer vertical or diagonal surfaces (Forteath et al., 1982; Clark and Edwards, 1999; Perkol-Finkel et al., 2006). These groups may therefore have been under sampled in our study due to the focus on horizontal members. Furthermore, we surveyed only the north facing Row G surfaces of the platform, which is in the lee of the platform and the prevailing south westerly wind. It is possible that communities on this more sheltered aspect of the platform differed to those on more exposed faces. In targeted future studies, we recommend surveys are designed to take member and jacket orientation into account.

Fish Assemblages
Knowledge of the fish communities associated with Australia’s offshore oil structures is also essential for understanding their habitat value. We observed 1791 fish from at least 19 species and 10 families associated with the GWA platform during the current study. Like other studies in the region on infrastructure (Pradella et al., 2014; McLean et al., 2017, 2018b), we identified commercially important target species in the Pilbara demersal fishery, including crimson seaperch (Lutjanus erythropterus),

\[1\text{http://www.bom.gov.au/cyclone/history/wa/}\]

\[2\text{http://www.bom.gov.au/cyclone/about/intensity.shtml}\]
red emperor (L. sebae), saddle-tailed seaperch (L. malabaricus) and mangrove jack (L. argentimaculatus) (Fletcher and Santoro, 2012). Trevally (Caranx sexfasciatus and C. melampygus) were the most abundant of the commercial and recreational species at GWA and were found in the upper 75 m in 2008.

The diversity of fishes at GWA was lower than on other infrastructure within a 60 km radius. Our sampling effort and time of sampling was most similar to Pradella et al. (2014) who used ROV video to count and identify fish at three obsolete well heads at depths of 85–175 m in June and July 2008. They found 31 species from 14 families, including ten commercially important species. Similarly, McLean et al. (2017) used ROV video to study fish on pipelines between August to December over a 3-year period. This study found 37 species from 21 families on a pipeline at approximately 125 m depth and 74 species from 30 families on another pipeline at 60–80 m depth. The cause(s) of differences in fish diversity among these studies and infrastructure types is unknown. It does not appear related to habitat complexity, because the well heads, and to a lesser extent, the platform would have provided the most complex and high relief habitat and the pipelines the least. Sound and vibration from an operating oil and gas platform such as GWA may have some inhibitory effect on some fish species as underwater sound is known to affect their behavior and the abundance of catches (Engås et al., 1996; Normandeau Associates Inc., 2012). An alternative explanation for the relatively low number of taxa recorded in our study is the short duration of the footage examined, conducted over just 2 days in each year which may have underestimated the state of the fish diversity associated with GWA. Examination of footage from other seasons and years would likely result in a broader range of species being detected at the site.

The low fish abundance recorded during 2006 in the current study was most likely due to footage being taken at night. Although ROV lights illuminated the foreground of footage, low light levels in the background likely reduced detection rates of individuals relative to footage taken during the day. Furthermore, the effect of ROV lighting on fish behavior is variable, whilst some fish may be only slightly affected, others may flee the light the approaching ROV (Laidig et al., 2012), so our results may at least partially reflect this effect. Additionally, many fish species are known to exhibit reduced mobility at night, sheltering in crevices, overhangs and within the invertebrate coverage (Nagelkerken et al., 2000). This behavior makes them difficult to detect with remote survey techniques such as video. In contrast, nocturnal feeders increase mobility at night, and may move away from shelter to forage on surrounding substrata during hours of darkness. This may explain the reduced abundance of lutjanid species observed on GWA in 2006 (Table 4), many of which are known to feed at night in areas surrounding their daytime resting sites (Hobson, 1965; Colton and Alevizon, 1981). Seasonal fluctuations in abundance in the study region may also have contributed to the low abundances of fish observed in 2006. Footage in 2006 was taken during late winter (August), whereas footage in 2008 was taken during summer (December). Seasonal investigations which incorporate footage taken during both the day and night are required to identify temporal factors of greatest influence on oil structure communities.

**Habitat Value of Structures**

Determining the habitat value of oil and gas structures, and the relative value of different sections within large structures like platforms, is important for evaluating decommissioning options involving partial removal. In the case of the ‘topping’ option, where the upper steel jacket is removed from the surface to approximately 30 m depth, some habitat provided by the photosynthetic portion of the attached community will be lost. However, considering the force of waves at the ocean’s surface that minimize settlement and growth and the application of anti-biofouling strategies employed in the upper 15 m (Surespek Iss PTY Ltd, 2009), loss of this habitat over 30 m will likely be minimal. Of possibly greater importance to the habitat value of the jacket of GWA is the continual impact of the passage of cyclones and energetic internal waves on the NWS. If these forces are shaping the attached community through the semi-regular removal of weakly attached species, it may be that the community is not reaching its full habitat potential, unlike the platforms in RTR programs located in more quiescent environments where internal wave energy is quickly dissipated in shallow waters (Rayson et al., 2015). A principle difference between platforms on the NWS shelf and those elsewhere is the occurrence of the strong semidiurnal tides. When the cyclone-induced inertial waves coincide with spring tides, attached communities on structures on the NWS may suffer the additive effect of both forces. It may be that platforms on the NWS are of lower habitat value than those elsewhere because of these impacts.

Alternatively, platforms and other oil structures can be situated where biodiversity is limited and far from the nearest natural reefs. On the NWS for example, mid-shelf to deeper water bottoms are characterized by sandy sediments and muds, often with low biodiversity (McLoughlin and Young, 1985; Lyne et al., 2006). As artificial reefs can create an ‘ecological halo’ effect up to 15 times the size of the actual structure (Reeds et al., 2018), the biodiversity associated with oil structures such as the GWA platform is likely to remain very high compared to the surrounding benthos, a virtual ‘biological oasis’ independent of changes in community composition over time. Thus, isolated from the nearest reefs and coastal areas, the sessile invertebrate community we observed on GWA most likely reflects a unique assemblage compared to the diversity of the surrounding marine ecosystem. While the pelagic fish we observed may be indicative of those in the wider environment, other fish may have been recruited to the platform as larvae and will not reflect the surrounding communities. Clearly, more research elsewhere on the NWS is required to understand the habitat value of oil structures in this region.

The increase in fish density with depth on GWA in 2008 suggests deeper sections of the platform have greater habitat value than shallower sections. This result is similar to findings on seven platforms located in Southern California (Martin and Lowe, 2010), and a platform in the northern Gulf of Mexico (Rooker et al., 1997). However, patterns of fish abundance with depth have been found to vary greatly among studies and regions,
with some studies finding greatest abundance in the shallowest sections of oil structures (Stanley and Wilson, 1997; Dokken et al., 2000). The generality of our finding on GWA is therefore unclear, and further investigation is required to determine whether other platforms on the NWS share similar patterns. We also offer our conclusions concerning depth associations on GWA cautiously, due to the short duration of investigation and the different time-period of observation for the 125 m depth category (3 months earlier than other depth categories). The high densities of baitfish that drove abundance values at 125 m may represent seasonal recruitment and/or transient movement that may not represent abundance values during other periods.

Community differences between depths on GWA suggest that sections of greatest habitat value are likely to vary among taxa. Similar to findings on other platforms (Rooker et al., 1997), pelagic species (e.g., Bluefin trevally, C. melampygus) were most abundant at mid-depths sections of the structure. In contrast, depth associations of benthic species were mixed, with some taxa more abundant at mid-depths (e.g., 'small cryptic fishes'), while others were more abundant near the platform base (e.g., red-bar anthias, Pseudanthias rubrizonatus). Mixed patterns for benthic taxa are likely the result of depth preferences or tolerances, and suggest that the prediction of depth associations on other platforms will require knowledge of taxon-specific depth distributions. Depth distributions of reef-associated fishes are one of the most poorly understood ecological aspects of fish communities (Brokovich et al., 2008). Given the deep deployment depths of many oil structures, and the relatively uniform habitat they provide, oil structures may assist scientific understanding of patterns of reef fish distribution with depth.

We found high densities of baitfish in the 125 m depth category exceeding 2,500 individuals per 50 m² in three out of five surveys near the platform base, and baitfish were not observed in any other depth category. We termed these as 'baitfish' as we could not determine if they were juveniles of a larger species or the adult stages of a small species. However, this result is consistent with findings of high juvenile or sub-adult abundances on platforms in Southern California, the Gulf of Mexico and on pipelines and wellheads in the region of GWA on the NWS, suggesting that the infrastructure offers suitable habitat for some juvenile fishes (Love et al., 2000; Gallaway et al., 2009; Fowler and Booth, 2012; McLean et al., 2017). Such a conclusion would be unsubstantiated here given the short period of the study, the single platform investigated and our inability to even identify the small fish to family level. However, science-directed studies using industry ROV video on other platforms giving rise to larger datasets would provide vital life history data on fish and on the role of platforms as nurseries and in recruitment. Ideally, such studies would be followed up with direct sampling of fish using traps or nets.

Although not observed in their juvenile stage, the presence of site-attached reef taxa indicates a wide range of species recruited to GWA. Given the isolated location of GWA (outer NWS), and the apparent lack of natural reef in the immediate vicinity (100 km radius), site-attached taxa (e.g., 'small cryptic fishes') most likely settled on the platform following a pelagic larval phase. Our observations of adults of such taxa therefore indicate that GWA provided sufficient habitat for developing and sustaining populations following their recruitment (Fowler and Booth, 2012). The ability of oil structures to provide sufficient habitat for sustaining fish populations is a key aspect of their value as habitat.

**Limitations of Industry-Collected ROV Footage**

Despite the potential benefits, some challenges and limitations arose when using industry-collected footage for scientific investigation. The video archiving system used by the operator was complex and necessitated a close partnership with industry engineers and access to platform structural plans. Pre-screening to identify useful footage from structures that were repeatedly filmed through time was labor-intensive. Repeat inspections were irregular in terms of frequency and seasons. It was also difficult to find matching footage of components between years taken at similar times of the day. While time of day was largely inconsequential to the invertebrate surveys, it was likely an important factor in describing the fish community (as outlined above). Poor camera resolution and lighting often hampered our ability to identify the attached invertebrates. Similar to another study using ROV footage (van der Stap et al., 2016), our observations underestimated the biodiversity of the community on the GWA platform. For example, from the video we could not reliably distinguish bivalves in the calcite encrusting layer and we did not observe any non-attached motile invertebrates such as worms, snails, crustaceans, etc. which were likely present. Therefore, use of industry archival ROV footage will be useful as a "rapid assessment" tool for biodiversity, which could then be complemented with targeted specimen collection to ensure high levels of scientific rigor.

**CONCLUSION AND RECOMMENDATIONS**

Offshore oil structures have been identified as important habitat for marine organisms in numerous regions of the world. For example, platforms in Southern California are known to support large abundances of overfished rockfish species (Schroeder and Love, 2004; Claisse et al., 2014), and the expansion of oil infrastructure in the northern Gulf of Mexico has been linked to the establishment of a valuable red snapper (Lutjanus campechanus) fishery (Gallaway et al., 2009). These discoveries were the result of extensive research programs spanning decades, and have influenced decommissioning policy and practice in both regions. The recent policy decision to allow 'rigs-to-reefs' conversions of obsolete platforms in California (Assembly Bill 2503, 2010) was contingent on their importance to rockfish populations.

Oil structures in Australia may provide similar habitat functions to those in other regions, yet almost nothing is known about the biological communities associated with Australia’s offshore infrastructure. We have demonstrated that archival ROV
footage can be used to assess attached invertebrate and fish communities on established offshore platforms, albeit with some limitations in species identification and survey design. Our results indicate that archived ROV footage held by the oil and gas industry is a useful tool for understanding the habitat value of oil and gas infrastructure in Australia. Archival footage also provides a cost-effective means for industry to obtain environmental information on their infrastructure relative to field investigations. Information on the habitat value of oil and gas infrastructure will be essential for informing environmentally sound decommissioning policy in Australia.

Some of the limitations of using industry-collected ROV footage for scientific purposes can be overcome in the future. For example, cameras that provide high resolution video (e.g., 4k) and still frames can be easily fitted to ROVs at a small additional expense. The use of 3D video which allows for precise measurements of organisms and other objects in the field of view would also be valuable (Macreadie et al., 2018). Additionally, ROV research could be complemented by other survey techniques such as baited remote video, light traps and eDNA to help determine how these structures are used by fish (McLean et al., 2017). Finally, ROV-collected specimens would aid greatly in the identification of attached species and cryptic fish. Research using archival ROV footage must be expanded to other platforms and other types of structures (e.g., well heads, pipelines) in order to amassed a solid base of evidence for informing decommissioning policy. Research across a broad geographical range is also required to assess variability between different locations under differing environmental regimes.

**ETHICS STATEMENT**

This study was carried out in accordance with the recommendations of “Animal Welfare Act (2002)” and the requirements of the Australian Code of Practice for the Care and Use of Animals for Scientific Purposes (7th Edition 2004) ‘The Code’ and the UWA Animal Ethics Committee. The protocol was approved by the UWA Animal Ethics Committee.

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**DATA AVAILABILITY STATEMENT**

All datasets generated for this study are included in the manuscript.

**AUTHOR CONTRIBUTIONS**

DB conceived the idea and secured access to the footage. PT, AF, and DB designed the study. PT, AF, AD, and CP completed the analysis. PT compiled the data and wrote the manuscript with contributions from all other authors.

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**SUPPLEMENTARY MATERIAL**

The Supplementary Material for this article can be found online at: https://www.frontiersin.org/articles/10.3389/fmars.2018.00471/full#supplementary-material

| TABLE S1 | Transect lengths and replicate numbers (in parentheses) according to year and depth for surveys of invertebrates and fishes associated with GWA platform. Replicates for invertebrates refer to quadrats examined along the length of a transect, while replicates for fishes refer to the number of transects completed. Frames examined from 125 m during 2008 were obtained from stationary footage obtained 3 months prior to footage for other depths. Note the different depth strata examined for fishes between 2006 and 2008. | Note the different depth strata examined for fishes between 2006 and 2008. |

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**Conflict of Interest Statement:** The authors declare that the research was conducted in the absence of any commercial or financial relationships that could be construed as a potential conflict of interest.

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