Elliptic Soliton Solutions: $\tau$ Functions, Vertex Operators and Bilinear Identities

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Abstract
We establish a bilinear framework for elliptic soliton solutions which are composed by the Lamé-type plane wave factors. $\tau$ functions in Hirota’s form are derived and vertex operators that generate such $\tau$ functions are presented. Bilinear identities are constructed and an algorithm to calculate residues and bilinear equations is formulated. These are investigated in detail for the KdV equation and sketched for the KP hierarchy. Degenerations by the periods of elliptic functions are investigated, giving rise to the bilinear framework associated with trigonometric/hyperbolic and rational functions. Reductions by dispersion relation are considered by employing the so-called elliptic $N$-th roots of the unity. $\tau$ functions, vertex operators and bilinear equations of the KdV hierarchy and Boussinesq equation are obtained from those of the KP. We also formulate two ways to calculate bilinear derivatives involved with the Lamé-type plane wave factors, which shows that such type of plane wave factors results in quasi-gauge property of bilinear equations.

Keywords Elliptic soliton solution · $\tau$ Function · Vertex operator · Bilinear identity · Weierstrass function · Lamé function

1 Introduction
The profound theory developed by Sato and his collaborators in 1980s brings a deep insight into integrable systems (Miwa et al. 1999). $\tau$ functions, vertex operators and bilinear identities together play a central role in this celebrated theory. In particular, via vertex operators, $\tau$ functions and hence soliton equations are connected to affine

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Lie algebras. These $\tau$ functions, generically, are composed by a plane wave factor (PWF) with a linear exponential function $e^{k_1 t + k_2 t^2 + k_3 t^3 + \cdots}$.

In this paper, we will develop Sato’s theory for integrable systems, aiming to establish a bilinear framework for the $\tau$ functions, vertex operators and bilinear identities that are associated with a Lamé-type PWF

$$\frac{\sigma(x + k)}{\sigma(x)\sigma(k)} e^{-\zeta(k)x + \zeta'(k)t} - \frac{1}{4} \zeta''(k)t^2 + \cdots. \quad (1.1)$$

The Lamé function, $y = \frac{\sigma(x + k)}{\sigma(x)\sigma(k)} e^{-\zeta(k)x}$, is a doubly periodic function with respect to $k$, bearing the name as it is a solution of the Lamé equation (the Schrödinger equation with an elliptic potential $\wp$)

$$y'' + (A + B\wp(x))y = 0, \quad (1.2)$$

where $A = -\wp(k)$ and $B = -2$. Here, $\sigma, \zeta$ and $\wp$ are the Weierstrass $\sigma, \zeta$ and $\wp$ functions, where $\wp(x)$ is an elliptic function, i.e., doubly periodic and meromorphic. Elliptic curves can play a role in integrable systems either as elliptic type solutions or as elliptic deformations of the equations themselves, either way brings richer insight into integrable systems than trigonometric/hyperbolic and rational cases.

Apart from the famous finite-gap integration method developed by Novikov, Matveev, Dubrovin, Its and Krichever (see Belokolos et al. 1994; Matveev 2008 and references therein), a second pioneer work is Airault et al. (1977) which extended the connection between the Korteweg–de Vries (KdV) equation and Calogero–Moser model from rational to elliptic case. Soliton solutions based on the Lamé function have emerged in Wahlquist (1976) in 1976 for the KdV equation. In 2010 Nijhoff and Atkinson (2010) developed a direct approach to obtain elliptic $N$-soliton solutions for some quadrilateral equations that are consistent-around-cube and classified in Adler and Bobenko (2003). Their approach relies on Cauchy matrix and discrete (and elliptic) Lamé-type PWFs. The obtained solutions are termed as elliptic $N$-soliton solutions (Nijhoff and Atkinson 2010). Later, their approach was applied to the lattice potential Kadomtsev–Petviashvili (KP) equation (Yoo-Kong and Nijhoff 2013). More recently, an elliptic direction linearization approach was established in Nijhoff et al. (2019), and elliptic $N$-th roots of unity were introduced to construct elliptic soliton solutions of the discrete Boussinesq-type equations and to deal with dimension reductions (Nijhoff et al. 2019).

We shall now sketch the plan of this paper and describe main results in more detail. The KdV equation will serve as our first introductory model to bear details. We will follow Nijhoff and Atkinson (2010) and still use the term elliptic soliton solutions, although in continuous case these solutions are no longer elliptic (but still doubly periodic with respect to parameters $k_j$ (see, e.g., Theorem 3.3) and expressed in terms of Weierstrass functions). We will begin with an elliptic 1-soliton solution of the lattice potential KdV (lpKdV) equation. By showing continuum limits of the equation and solution, we are able to have a full profile as well as a comparison of the Lamé-type PWFs from fully discrete to continuous. As a new feature, all these PWFs are no longer
solutions to the linear part of the corresponding nonlinear equations. This is different from the case of usual solitons composed by linear exponential functions.

Section 3 will play a role to present details that how a τ function for elliptic N-soliton solutions is obtained from a Wronskian and from vertex operators, how a bilinear identity is constructed and how explicit bilinear equations arise from the bilinear identity. The KdV equation is still the model equation of this section. We will begin by deriving its elliptic 1- and 2-soliton solutions from the bilinear KdV equation (3.1) using the standard Hirota’s procedure, but the procedure is more complicated than the usual soliton case. These two solutions are presented in Eqs. (3.6) and (3.7). Details of the derivation and some bilinear derivative formulae involved with the Lamé-type PWFs are given in Appendix B. A key and new feature is the gauge property for bilinear derivatives of the usual soliton case is not valid any longer for the Lamé-type PWFs, and instead, we have quasi-gauge property (see Proposition B.1). As a consequence, a KdV-type bilinear equation does not always admit an elliptic 2-soliton solution and even elliptic 1-soliton. This is also different from the usual soliton case where a KdV-type bilinear equation always has a 2-soliton solution (Hirota 1980, 2004). The formula of τ function in Hirota’s form for the elliptic N-soliton solution is secured from a Wronskian that satisfies the bilinear KdV equation. This formula is presented in Eq. (3.26) in Theorem 3.2. To obtain it, the quasi-gauge property and some formulae and identities of the Weierstrass functions are employed. The vertex operator to generate such a τ function is given in Theorem 3.3. After that, we will present a bilinear identity (3.43) and its residue form (3.44) in Theorem 3.4. The identity is constructed by using double-periodicity of the integrand and implementing the integration around the fundamental period parallelogram. It turns out that the integrand has 2N simple poles and an essential singularity at q = 0 (mod period lattice). Similar to the usual soliton case, the integral bilinear identity equals to the residue of the integrand at q = 0, but the way to achieve the residue is not straightforward at all. We will develop an algorithm for this matter in Sect. 3.4 and a practical formula for calculating residues as well as bilinear equations is presented in Eq. (3.55) in Theorem 3.5. After the exploration of the KdV equation with necessary details, we will move to the KP equation in Sect. 4 and sketch the main results in Theorems 4.2, 4.3, 4.4 and 4.5.

In Sect. 5, we will discuss period degenerations of the elliptic soliton solutions when the discriminant Δ = g_3^2 - 27g_2^3 = 0. This will give rise to soliton solutions of trigonometric/hyperbolic type and rational type. The degenerations are straightforward. That is to say, one can directly substitute the degenerated Weierstrass functions (see Proposition A.2) into the τ functions and bilinear equations we obtain in Sects. 3 and 4. The degenerated results for the KP hierarchy are given in Theorems 5.1 and 5.2. Three types of PWFs of the KP hierarchy are given in (4.25), (5.10) and (5.15), respectively. Note that Theorem 5.1 presents a more concise expression for the trigonometric/hyperbolic-type τ function and the associated vertex operator, which allows a direct replacement of σ(x) and ζ(x) by sin(αx) and α cot(αx), respectively. In Sect. 5, we will also investigate reductions by dispersion relations (corresponding to periodic reductions of the usual soliton case). Elliptic N-th roots of the unity (see Nijhoff et al. 2019 and Definition A.1 in this paper) will be used. However, different from the usual soliton case, when N ≥ 3, the elliptic N-th roots of the unity are not simultaneously the
elliptic \((kN)\)-th roots of the unity where \(k \in \mathbb{N}\), (see Remark A.1 in Appendix A). This means one cannot get elliptic soliton solutions for the Gel’fand–Dickey (with \(N \geq 3\)) hierarchy from those of the KP hierarchy by reduction using elliptic \(N\)-th roots of the unity.

We have introduced the plan of our paper as well as the main results and some new features associated with the Lamé-type PWFs. The paper also contains a section where we will present conclusions and mention some further topics based on the framework of this paper. In addition, there are three appendices, which include a collection of the Weierstrass functions and the related properties and identities, some calculating formulae involved with Hirota’s bilinear operator and the Lamé-type PWFs, and proofs for the elliptic \(N\)-soliton solutions in Wronskian forms that satisfy, respectively, the bilinear KdV equation and KP equation.

2 Lamé-Type Plane Wave Factors

PWF is an elementary block of \(N\)-soliton solutions. In this section, we begin by exploring PWFs and dispersion relations of elliptic solitons, for fully discrete, semi-discrete and continuous cases. We will consider usual 1-soliton solution and elliptic 1-soliton solution of the lpKdV equation and implement continuum limits of both the equation and solution, so that one can make a comparison for the usual and elliptic cases.

Recalling the KdV equation (with scaled coefficients for our convenience)

\[
  u_t = \frac{3}{2} uu_x + \frac{1}{4} u_{xxx} \tag{2.1}
\]

and its potential form \((u = v_x)\)

\[
  v_t = \frac{3}{4} v_x^2 + \frac{1}{4} v_{xxx}, \tag{2.2}
\]

which admits 1-soliton solution

\[
  v = \frac{4ke^{2kx+2k^3t}}{1 + e^{2kx+2k^3t}}, \tag{2.3}
\]

The PWF is

\[
  \rho(k) = e^{2kx+2k^3t}, \tag{2.4}
\]

which is a solution of the linear part of the (potential) KdV equation and indicates the dispersion relation of the equation.

The lpKdV equation reads (Hietarinta et al. 2016; Nijhoff and Capel 1995; Nijhoff et al. 1985)

\[
  (w - \hat{w})(\hat{w} - \bar{w}) = p^2 - q^2, \tag{2.5}
\]
where we adopt notations

\[ w = w(n, m), \quad \tilde{w} = w(n + 1, m), \quad \hat{w} = w(n, m + 1), \quad \hat{\tilde{w}} = w(n + 1, m + 1), \]

\( n, m \in \mathbb{Z}, \) \( p \) and \( q \) are spacing parameters of the \( n \)-direction and \( m \)-direction, respectively. This equation has a background solution \( w_0 = pn + qm + c \) and a usual 1-soliton solution (Hietarinta and Zhang 2009)

\[ w = w_0 + \frac{k(1 - \rho)}{1 + \rho}, \quad (2.6) \]

where

\[ \rho = \left( \frac{p + k}{p - k} \right)^n \left( \frac{q + k}{q - k} \right)^m \rho_{00} \]

(2.7)

is the PWF. Here, \( c, k \) and \( \rho_{00} \) are constants. Removing the background \( w_0 \) by introducing \( v = w - w_0 \), the lpKdV equation (2.5) is converted to

\[ (v - \tilde{v} - p - q)(\hat{v} - \tilde{v} - p + q) = p^2 - q^2. \]

(2.8)

The PWF (2.7) solves the linear part of the above equation.

With new parametrizations

\[ p^2 = \wp(\delta) - e_1, \quad q^2 = \wp(\epsilon) - e_1, \]

(2.9)

the lpKdV equation (2.5) allows a background solution

\[ w_0 = \zeta(\xi) - n\zeta(\delta) - m\zeta(\epsilon) - c_0 \]

(2.10)

where

\[ \xi = n\delta + m\epsilon, \]

(2.11)

\( e_1, c_0 \in \mathbb{C}, \) and \( \delta, \epsilon \) serve as lattice parameters. For the Weierstrass functions \( \sigma(x), \zeta(x) \) and \( \wp(x) \) and related notations and properties, please refer to Appendix A. The elliptic 1-soliton solution of the lpKdV equation is Nijhoff and Atkinson (2010)

\[ w = w_0 + \frac{\eta_{-k}(\xi) + \eta_k(\xi)\rho}{1 + \rho}, \quad (2.12) \]

where

\[ \eta_\pm(y) = \zeta(x + y) - \zeta(x) - \zeta(y), \]

(2.13)
and the PWF is
\[
\rho = \frac{\sigma(k + \xi)}{\sigma(k - \xi)} \left( \frac{\sigma(k - \delta)}{\sigma(k + \delta)} \right)^n \left( \frac{\sigma(k - \epsilon)}{\sigma(k + \epsilon)} \right)^m \rho_{00},
\] (2.14)
with \( k, \rho_{00} \in \mathbb{C} \). Again, removing the background \( w_0 \) from (2.5) by \( v = w - w_0 \) yields
\[
(v - \hat{v} + \chi_{\delta,\epsilon}(\xi))(\hat{v} - \tilde{v} - \chi_{-\delta,\epsilon}(\xi + \delta)) = \wp(\delta) - \wp(\epsilon),
\] (2.15)
where
\[
\chi_{\delta,\epsilon}(\gamma) = \xi(\delta) + \xi(\epsilon) + \xi(\gamma) - \xi(\delta + \epsilon + \gamma).
\] (2.16)
Equation (2.15) admits a solution
\[
v = \frac{\eta_{-k}(\xi) + \eta_k(\xi)\rho}{1 + \rho}
\] (2.17)
with PWF (2.14). Note that for given \( n, m \) and constant \( \rho_{00} \) that are independent of \( (k, \delta, \epsilon) \), the PWF \( \rho \) and \( \eta_{\pm k}(\xi) \) are elliptic functions of \( (k, \delta, \epsilon) \), and so is \( v \) given above. However, the PWF (2.14) is no longer a solution of the linear part of Eq. (2.15).

To show the Lamé-type PWFs in semi-discrete and continuous form, we consider continuum limits of the lpKdV equation (2.15) together with its elliptic soliton solution (2.17). Let \( m \to \infty, \epsilon \to 0 \) while \( \mu = m\epsilon \) be finite. Noticing those Laurent series listed in (A.6) and
\[
\begin{align*}
\chi_{\delta,\epsilon}(\xi) &= 1 - \eta_\delta(\mu + n\delta) + \epsilon \wp(\mu + (n + 1)\delta) + \frac{\epsilon^2}{2} \wp'(\mu + (n + 1)\delta) + O(\epsilon^3), \\
\chi_{-\delta,\epsilon}(\xi + \delta) &= 1 + \eta_\delta(\mu + n\delta) + \epsilon \wp(\mu + n\delta) + \frac{\epsilon^2}{2} \wp'(\mu + n\delta) + O(\epsilon^3),
\end{align*}
\]
in continuum limits the lpKdV equation (2.15) yields the semi-discrete pKdV equation (with a \( n \)-dependent coefficient \( \eta_\delta(\mu + n\delta) \))
\[
\partial_\mu(v + \tilde{v}) + (\tilde{v} - v)^2 + 2\eta_\delta(\mu + n\delta)(\tilde{v} - v) = 0,
\] (2.18)
which admits an elliptic 1-soliton solution
\[
v = \frac{\eta_{-k}(n\delta + \mu) + \eta_k(n\delta + \mu)\rho}{1 + \rho}
\] (2.19)
where the PWF is (with \( \rho_0 \in \mathbb{C} \))
\[
\rho = \frac{\sigma(k + n\delta + \mu)}{\sigma(k - n\delta - \mu)} \left( \frac{\sigma(k - \delta)}{\sigma(k + \delta)} \right)^n e^{-2\xi(k)\mu} \rho_0.
\] (2.20)
Strictly speaking, this PWF is doubly periodic with respect to $k$ but not elliptic as there is an essential singularity at $k = 0$ due to $e^{-2\zeta(k)\mu}$. However, we would like to inherit the term elliptic $N$-soliton solutions introduced in Nijhoff and Atkinson (2010). Note also that the PWF does not solve the linear part of Eq. (2.18) either. In the full continuum limit, first, we let $n \to \infty$, $\delta \to 0$ while $\nu = n\delta$ be finite, and then introduce $x = \mu + \nu$, $t = \frac{1}{3}\delta^2 v$. The resulting equation with coordinates $(x, t)$ is

$$v_t - \frac{3}{2}v_x^2 + 3\wp(x)v_x - \frac{1}{4}v_{xxx} = 0,$$  \hspace{1cm} (2.21)

and its elliptic 1-soliton solution takes a form

$$v = \frac{\eta_{-k}(x) + \eta_k(x)\rho}{1 + \rho},$$  \hspace{1cm} (2.22)

where the PWF for the continuous elliptic soliton solution is

$$\rho = \frac{\sigma(k + x)}{\sigma(k - x)}e^{-2\zeta(k)x + \wp'(k)t + \xi^{(0)}},$$  \hspace{1cm} (2.23)

with parameter $\xi^{(0)} \in \mathbb{C}$ independent of $k$ or being a doubly periodic function of $k$. Note that employing the transformation

$$\bar{v} = 2(v + \zeta(x) + \frac{1}{8}g_2 t)$$  \hspace{1cm} (2.24)

one can convert Eq. (2.21) into the usual pKdV equation (i.e., (2.2))

$$\bar{v}_t - \frac{3}{4}\bar{v}_x^2 - \frac{1}{4}\bar{v}_{xxx} = 0.$$  \hspace{1cm} (2.25)

Besides, the nonpotential form of Eq. (2.21) is ($u = v_x$)

$$u_t - 3uu_x + 3\wp(x)u_x + 3\wp'(x)u - \frac{1}{4}u_{xxx} = 0,$$  \hspace{1cm} (2.26)

which, by transformation $u \to \frac{1}{5}u + \wp(x)$, is written as the usual KdV equation (2.1). However, the PWF (2.23) is not a solution of the linear part of any of equations, (2.21) or (2.25) or (2.26) or (2.1). Note that the elliptic 1-soliton solution $u = v_x$ with (2.22) emerged in Wahlquist (1976).

Now let us make a comparison for the two PWFs, (2.23) and (2.4), i.e., the PWFs for elliptic solitons and usual solitons. Considering the exponential parts of them, asymptotically, it follows from (A.6) that

$$e^{-2\zeta(k)x + \wp'(k)t + \xi^{(0)}} \sim e^{-\frac{2}{3}x - \frac{2}{3}t},$$
which corresponds to the dispersion relation in (2.4). This observation motivates us to introduce a general Lamé-type PWF (the extended Lamé function)

\[
\rho = \Phi(x) \exp \left( -\xi(k)t_1 + \xi'(k)t_2 + \cdots + \frac{(-1)^{j}}{(j-1)!} \xi^{(j-1)}(k)t_j + \cdots \right),
\]

which is an elliptic analogue of the usual one

\[
\rho = \exp (kt_1 + k^2t_2 + \cdots + k^jt_j + \cdots),
\]

where \( t_1 = x \) and

\[
\Phi(x) = \frac{\sigma(k + x)}{\sigma(x)\sigma(k)}.
\]

Note that the doubly periodic feature of the PWF (2.23) can also be illustrated in its alternative form

\[
\rho = \exp \left( \xi^{(0)} + 2\wp'(k)t - \sum_{n=1}^{\infty} \frac{2}{(2n+1)!} \wp^{(2n-1)}(k)x^{2n+1} \right).
\]

For the KdV equation (2.1), its elliptic 1-soliton solution can be written as (cf. Eq. 3.6)

\[
u = -2\wp(x) + 2(\ln(1 + \Phi(x)2ke^{-2\xi(k)x + \wp'(k)x + \xi^{(0)})})_{xx},
\]

where the \(-2\wp(x)\) is a 1-gap and 1-genus solution in light of the so-called Dubrovin’s equations in finite-gap integration (Dubrovin 1975; Dubrovin and Novikov 1975) (also see Ince 1940 by Ince), but the whole solution (2.31) is a doubly periodic function of \( k \) (not periodic with respect to \( x \)).

Noting that \((\wp(k), \wp'(k)), k \in \mathbb{D}\) (see Fig. 1) are points on the elliptic curve (A.2), along the line of Airault et al. (1977), we can say that the elliptic soliton solution corresponds to the torus (A.2), while its degenerations by fixing \( g_2 = \frac{4}{3}(\frac{\pi}{2w_1})^4 \), \( g_3 = \frac{8}{27}(\frac{\pi}{2w_1})^6 \) and \( g_2 = g_3 = 0 \) (i.e., degenerations by periods) correspond to a cylinder and Riemann sphere, respectively, cf. Airault et al. (1977).

### 3 \( \tau \) Function, Vertex Operator and Bilinear Identity: KdV

We will extend the obtained elliptic 1-soliton solution of the KdV equation to its elliptic \( N \)-soliton solution and then establish a bilinear framework for such type of solutions. The framework will consist of \( \tau \) function in Hirota’s form, a vertex operator for generating the \( \tau \) function, a bilinear identity and an algorithm for calculating residues that gives rise to bilinear equations.
3.1 \( \tau \) Function of Elliptic \( N \)-Soliton Solutions

3.1.1 Bilinear Form and Elliptic 1- and 2-Soliton Solutions

We begin by exploring Hirota’s procedure to calculate elliptic 1- and 2-soliton solutions for a bilinear KdV equation. The potential KdV equation (2.25) can be converted into a bilinear form

\[
(D_x^4 - 4D_xD_t - 12\wp(x)D_x^2)\tau \cdot \tau = 0 \tag{3.1}
\]

via the transformation

\[
\bar{v} = 2\xi(x) + \frac{1}{4}g_2t + 2(\ln \tau)_x, \tag{3.2}
\]

where \( D \) is Hirota’s bilinear operator defined by Hirota (1974)

\[
D^m_t D^n_x f \cdot g = (\partial_t - \partial_{t'})^m(\partial_x - \partial_{x'})^n f(t, x)g(t', x')|_{t'=t,x'=x}, \quad m, n = 0, 1, 2 \cdots .
\]

Equation (3.1) is also a bilinear form of the KdV equation (2.1) while the transformation is

\[
u = -2\wp(x) + 2(\ln \tau)_{xx}. \tag{3.3}
\]

Both (3.2) and (3.3) have nonzero backgrounds. An alternative bilinear form for the KdV equation is

\[
(D_x^4 - 4D_xD_t - g_2)\tau' \cdot \tau' = 0, \tag{3.4}
\]

while the associated transformations are

\[
u = 2(\ln \tau')_{xx}, \quad \bar{v} = \frac{1}{4}g_2t + 2(\ln \tau')_x. \tag{3.5}
\]

By direct calculation (see Appendix B), one can find that Eq. (3.1) admits the following solutions,

\[
\tau = f_1 = 1 + \rho_1(x, t) = 1 + \Phi_x(2k_1)e^{\xi_1}, \tag{3.6}
\]

and

\[
\tau = f_2 = 1 + \rho_1(x, t) + \rho_2(x, t) + f^{(2)}(x, t)
= 1 + \Phi_x(2k_1)e^{\xi_1} + \Phi_x(2k_2)e^{\xi_2} + A_{12}\frac{\sigma(x + 2k_1 + 2k_2)}{\sigma(x)\sigma(2k_1)\sigma(2k_2)}e^{\xi_1+\xi_2}, \tag{3.7}
\]
where

$$\rho_i(x, t) = \Phi_x(2k_i)e^{ki}, \; \xi_i = -2\zeta(k_i)x + \varphi'(k_i)t + \xi^{(0)}_i, \; A_{12} = \frac{\sigma^2(k_1-k_2)}{\sigma^2(k_1+k_2)},$$

(3.8)

$k_i, \xi^{(0)}_i \in \mathbb{C}$. These are formally similar to the usual 1-soliton and 2-soliton solutions of the KdV equation but there is an essential difference in 2-soliton case: the last term $f_2$ in $f_2$ is $A_{12}e^{4\zeta(k_1)k_2}\rho_1(x+2k_2, t)\rho_2(x, t)$, rather than $A_{12}\rho_1(x, t)\rho_2(x, t)$ as in a usual two-soliton solution. In Appendix B, we provide details of deriving $f_1$ and $f_2$, as well as some formulae for higher-order bilinear derivatives and properties (e.g., the quasi-gauge property, see Proposition B.1) involved with the Lamé-type PWF $\rho_i$. We also remark that it is well known a KdV-type bilinear equation (with constant coefficients) always admits 1-soliton solution and 2-soliton solution (Hirota 1980), however, such a convention does not hold even for admitting elliptic 1-soliton solution.

A $\tau$ function in Hirota’s form for elliptic $N$-soliton solution is needed to introduce vertex operator. However, for higher-order elliptic soliton solutions, the calculation is much more complicated. Next, we will first present a $N$-soliton solution in terms of Wronskian, from which we can secure the $\tau$ function in Hirota’s form.

### 3.1.2 $\tau$ Function in Wronskian Form

Introduce a $N$-th-order column vector

$$\varphi = (\varphi_1, \varphi_2, \ldots, \varphi_N)^T,$$

(3.9)

where $\varphi_j = \varphi_j(x, t)$ are functions of $(x, t)$. A $N$-th-order Wronskian is defined as

$$f = |\varphi, \partial_x \varphi, \partial_x^2 \varphi, \cdots, \partial_x^{N-1} \varphi| = |0, 1, 2, \cdots, N - 1| = |\overline{N-1}|,$$

where we employ the conventional shorthand introduced in Freeman and Nimmo (1983). For an elliptic $N$-soliton solution of the KdV equation, we have the following.

**Theorem 3.1** The bilinear equation (3.1) admits a Wronskian solution

$$\tau = |\overline{N-1}|$$

(3.10)

composed by vector $\varphi = (\varphi_1, \varphi_2, \cdots, \varphi_N)^T$ where each element $\varphi_j$ satisfies

$$\varphi_{j,xx} = (\varphi(k_j) + 2\varphi(x))\varphi_j,$$

(3.11a)

$$\varphi_{j,t} = \varphi_{j,xxx} - 3\partial_x \varphi(x)\varphi_{j,x} - \frac{3}{2}\partial_x' \varphi(x)\varphi_j,$$

(3.11b)
for \( j = 1, 2, \cdots, N \) and \( k_j \in \mathbb{C} \). A general solution to the above equations is

\[
\varphi_j = a_j^+ \varphi_j^+ + a_j^- \varphi_j^- ,
\]

(3.12a)

where \( \varphi_j^\pm \) are Lamé functions

\[
\varphi_j^\pm = \Phi_x(\pm k_j) e^{\mp \gamma_j} , \quad \gamma_j = \xi(k_j)x - \frac{1}{2} \wp'(k_j)t + \gamma_j^{(0)} ,
\]

(3.12b)

where \( a_j^\pm, k_j, \gamma_j^{(0)} \in \mathbb{C}, \Phi_x(k) \) is defined in (2.29), and in practice, \( k_j \) takes value in the fundamental period parallelogram \( D \) of the Weierstrass \( \wp \) function (see Fig. 1).

The proof will be sketched in Appendix C. Note that such a solution in Wronskian form for the KdV equation can be alternatively obtained using the method of Darboux transformation (cf. Chapter 3.2 of Matveev and Salle (1991) for soliton solution of the KdV equation) by taking \( u = -2\wp(x) \) as a seed solution but one needs to assign a proper dispersion relation. However, we do need to have a \( \tau \) function that serves for elliptic \( N \)-soliton solutions and satisfies a definite bilinear KdV equation.\(^1\)

3.1.3 \( \tau \) Function in Hirota’s Form

To convert Wronskian (3.10) into Hirota’s form, we first investigate the Wronskian composed by \( \varphi^- = (\varphi_1^-, \varphi_2^-, \cdots, \varphi_N^-)^T \) and its derivatives, where \{\( \varphi_j^- \)\} are defined as in (3.12b). Such a Wronskian can be written as an explicit form.

Lemma 3.1 For the forementioned \( \varphi^- \), we have

\[
|\varphi^-, \partial_x \varphi^-, \partial_x^2 \varphi^-, \cdots, \partial_x^{N-1} \varphi^-| = (-1)^N \frac{\sigma(x - \sum_{i=1}^N k_i)}{\sigma(x)} \prod_{1 \leq i < j \leq N} \frac{\sigma(k_i - k_j)}{\sigma^N(k_1) \cdots \sigma^N(k_N)} \exp \left( \sum_{i=1}^N \gamma_j \right) . \tag{3.13}
\]

Proof For convenience, we introduce notations \( k = (k_1, k_2, \cdots, k_N)^T, f(k) = (f(k_1), f(k_2), \cdots, f(k_N))^T, f(k)g(k) = (f(k_1)g(k_1), f(k_2)g(k_2), \cdots, f(k_N)g(k_N))^T \), and we consider the Wronskian

\[
f^- = |\Phi_x(-k)e^{\zeta(k)x}, \partial_x(\Phi_x(-k)e^{\zeta(k)x}), \cdots, \partial_x^{N-1}(\Phi_x(-k)e^{\zeta(k)x})| , \tag{3.14}
\]

where for conciseness we have dropped off \( \wp'(k_j)t \) and \( \gamma_j^{(0)} \) in \( \gamma_j \) since the structure of the Wronskian is irrelevant to time. For each \( \varphi_j^- \) we have

\[
\partial_x \varphi_j^- = \eta_x(-k)\varphi_j^- ,
\]

\(^1\) Due to the quasi-gauge property (see Proposition B.1) of bilinear derivatives with respect to the Lamé-type PFWs, it is necessary to have some \( \tau \) function to satisfy a definite bilinear equation.
where \( \eta_x(k) \) is defined as (2.13). In addition, \( \varphi_j^- \) is a Lamé function, satisfying (3.11a), which indicates that

\[
\partial^n_x \varphi_j^- = (\varphi(k_j) + 2 \varphi(x)) \partial_{x}^{n-2} \varphi_j^- + 2 \sum_{i=1}^{n-2} \binom{n-2}{i} (\partial_x^i \varphi(x)) \partial_x^{n-2-i} \varphi_j^-, \quad (n \geq 2).
\]

Using the above relations, we can replace the column \( \partial^j_x(\Phi_x(-k)e^{\xi(x)k}) \) in (3.14), and after simplification we have

\[
f^- = \left( \exp \sum_{i=1}^{N} \zeta(k_i)x \right) \left( \prod_{j=1}^{N} \Phi_x(-k_j) \right) \\
\times |1, \eta_x(-k), \varphi(k), \varphi(k)\eta_x(-k), \varphi^2(k), \varphi^2(k)\eta_x(-k), \ldots, \varphi^{\left[\frac{N-1}{2}\right]}(k)h_1(k, x)|,
\]

where in the last column \( h_1(k, x) \) stands for

\[
h_1(k, x) = \begin{cases} 
1, & N \text{ odd}, \\
\eta_x(-k), & N \text{ even},
\end{cases}
\]

and \([x]\) is the floor function of \( x \).

Next, for the column \( \varphi^n(k)\eta_x(-k) \) in (3.15), in light of the relation (A.8), we have (for \( n \geq 1 \))

\[
\varphi^n(k)\eta_x(-k) = -\frac{1}{2} \varphi^{n-1}(k)\varphi'(k) - \frac{1}{2} \varphi^n(k)\varphi'(x) + \varphi^{n-1}(k)\eta_x(-k)\varphi(x),
\]

where the last two terms on the right hand side will be eliminated by those front columns in (3.15). We can examine all such columns in (3.15) successively from right to left. As a result, we are able to have \( f^- \) in the form

\[
f^- = \left( -\frac{1}{2} \right)^{\left[\frac{N}{2}\right]-1} \left( \exp \sum_{i=1}^{N} \zeta(k_i)x \right) \left( \prod_{j=1}^{N} \Phi_x(-k_j) \right) \\
\times |1, \eta_x(-k), \varphi(k), \varphi'(k), \varphi^2(k), \varphi(k)\varphi'(k), \varphi^3(k), \varphi^2(k)\varphi'(k), \ldots, \varphi^{\left[\frac{N-1}{2}\right]-1}(k)h_2(k)|,
\]

where in the last column \( h_2(k) \) is

\[
h_2(k) = \begin{cases} 
\varphi(k), & N \text{ odd}, \\
\varphi'(k), & N \text{ even}.
\end{cases}
\]
By virtue of the fact that \((℘(x), ℘'(x))\) is a point on the elliptic curve (A.2), i.e.,
\[
(℘'(k))^2 = 4℘^3(k) - g_2℘(k) - g_3,
\]
we know that both \(℘^{(2n-2)}(x)\) and \(℘^{(2n+1)}(x)\) can be expressed as a linear combination of \(℘^s(x)\) with \(s = n, n-2, n-3, \ldots, 2, 1, 0\). Then, we are led to
\[
f^- = \left( \exp \sum_{i=1}^{N} \zeta(k_i)x \right) \left( \prod_{j=1}^{N} \Phi_x(-k_j) \right) \frac{1}{1! \cdots (N-2)!} \times |1, \eta_x(-k), ℘(-k), ℘'(-k), ℘''(-k), \ldots, ℘^{(N-3)}(-k)|,
\]
which is further written into
\[
f^- = \left( \exp \sum_{i=1}^{N} \zeta(k_i)x \right) (-1)^{N-1} \Phi_x(-k_1 - \cdots - k_N) \frac{1}{1! \cdots (N-2)! (N-1)!} \times |1, ℘(-k), ℘'(-k), ℘''(-k), \ldots, ℘^{(N-2)}(-k)|, \tag{3.16}
\]
where use has been made of relation (A.12). Then, employing the elliptic van der Monde determinant formula (A.11), we have
\[
f^- = (-1)^N \frac{\sigma(x - \sum_{i=1}^{N} k_i)}{\sigma(x)} \prod_{1 \leq i < j \leq N} \sigma(k_i - k_j) \frac{\exp \left( \sum_{i=1}^{N} \zeta(k_i)x \right)}{\sigma(k_1)^N \cdots \sigma(k_N)^N}, \tag{3.17}
\]
which yields (3.13). \[\square\]

Next, in order to obtain the \(τ\)-function in Hirota’s form, we consider the Wronskian (3.10) composed specially by an elementary column vector (cf.(3.12a))
\[
φ_j = φ_j^+ + (-1)^{i}φ_j^-,
\]
where \(φ_j^\pm\) are defined by (3.12b). The corresponding Wronskian
\[
τ = |N-1| \tag{3.19}
\]
can be split and then written as a sum of \(2^N\) distinct Wronskians, each of which is generated by the elementary column vector of the following form,
\[
φ = (φ_1, φ_2, \ldots, φ_N)^T, \quad φ_j = (ε_j)^{i} \Phi_x(ε_j k_j) e^{-ε_j γ_j} \tag{3.20}
\]
where \(\{ε_1, ε_2, \ldots, ε_N\}\) run over \(\{1, -1\}\). Compared with \(φ_j^-\) defined in (3.12a), the above \(φ_j\) can be formally obtained from \(φ_j^-\) by multiplying \((ε_j)^i\) and replacing \(k_j\) with
\[-\varepsilon_j k_j.\text{ Thus, in light of Lemma 3.1, one can replace } k_j \text{ with } \varepsilon_j k_j \text{ in the formula (3.13) and express the Wronskian generated by (3.20) as}

\[
\tau_\varepsilon = (-1)^N \prod_{j=1}^{N} (\varepsilon_j)^j \cdot \frac{\sigma(x + \sum_{i=1}^{N} \varepsilon_i k_i)}{\sigma(x)} \cdot \prod_{1 \leq i < j \leq N} \sigma(-\varepsilon_i k_i + \varepsilon_j k_j) \sigma^{N}(-\varepsilon_1 k_1) \cdots \sigma^{N}(-\varepsilon_N k_N) \exp \left( -\sum_{i=1}^{N} \varepsilon_i \gamma_i \right)
\]

\[
= (-1)^{\frac{N(N-1)}{2}} \prod_{j=1}^{N} (\varepsilon_j)^j \cdot \frac{\sigma(x + \sum_{i=1}^{N} \varepsilon_i k_i)}{\sigma(x)} \cdot \prod_{1 \leq i < j \leq N} \sigma(\varepsilon_i k_j - \varepsilon_j k_j) \sigma^{N}(k_1) \cdots \sigma^{N}(k_N) \exp \left( -\sum_{i=1}^{N} \varepsilon_i \gamma_i \right)
\]

\[
= (-1)^{\frac{N(N-1)}{2}} \cdot \frac{\sigma(x + \sum_{i=1}^{N} \varepsilon_i k_i)}{\sigma(x)} \cdot \prod_{1 \leq i < j \leq N} \sigma(\varepsilon_i k_j - \varepsilon_j k_j) \sigma^{N}(k_1) \cdots \sigma^{N}(k_N) \exp \left( -\sum_{i=1}^{N} \varepsilon_i \gamma_i \right),
\]

(3.21)

where \( \varepsilon \) indicates cluster \( \varepsilon = \{ \varepsilon_1, \varepsilon_2, \ldots, \varepsilon_N \} \). Introduce length of \( \varepsilon \) by \( |\varepsilon| \) to denote the number of positive \( \varepsilon_j \)'s in the cluster \( \varepsilon \). Rearrange the \( 2^N \) terms in the \( \tau \) function (3.19) in terms of \( |\varepsilon| \) such that

\[
\tau = \sum_{l=0}^{N} \sum_{|\varepsilon|=l} \tau_\varepsilon = \sum_{l=0}^{N} \tau^{(l)},
\]

(3.22)

where \( \tau^{(l)} = \sum_{|\varepsilon|=l} \tau_\varepsilon \), and in particular, by \( g \) we denote \( \tau^{(0)} \), i.e.,

\[
g = \tau^{(0)} = (-1)^{\frac{N(N-1)}{2}} \cdot \frac{\sigma(x - \sum_{i=1}^{N} k_i)}{\sigma(x)} \cdot \prod_{1 \leq i < j \leq N} \sigma(k_j - k_i) \sigma^{N}(k_1) \cdots \sigma^{N}(k_N) \exp \left( \sum_{i=1}^{N} \gamma_i \right).
\]

(3.23)

Here, for convenience of this subsection, for a function \( f = f(x) \), by \( \tilde{f} \) we specially denote the \( f \) shifted in \( x \) by \( \sum_{i=1}^{N} k_i \), i.e., \( \tilde{f} = f(x + \sum_{i=1}^{N} k_i) \). Then, we have the following.

**Theorem 3.2**  Let

\[
f = \frac{\tilde{\tau}}{g},
\]

(3.24)

where \( \tau \) and \( g \) are given by (3.19) and (3.23). Then, we have

\[
(D^4_x - 4D_x D_t - 12\gamma(x) D^2_x) f \cdot f = 0.
\]

(3.25)

\( f \) is the \( \tau \) function in Hirota’s form, written as

\[
f = \sum_{\mu=0,1} \frac{\sigma(x + 2\sum_{i=1}^{N} \mu_i k_i)}{\sigma(x) \prod_{j=1}^{N} \sigma^{\mu_j}(2k_j)} \exp \left( \sum_{j=1}^{N} \mu_j \theta_j + \sum_{1 \leq i < j} \mu_i \mu_j a_{ij} \right),
\]

(3.26)
\[ f = 1 + \sum_{i=1}^{N} \Phi_x(2k_i) e^{\theta_i} + \sum_{1 \leq l < p \leq N} \frac{\sigma(x + 2k_l + 2k_p)}{\sigma(x) \sigma(2k_l) \sigma(2k_p)} A_{lp} e^{\theta_l + \theta_p} \]
\[ + \cdots + \frac{\sigma(x + 2 \sum_{i=1}^{N} k_i)}{\sigma(x) \prod_{j=1}^{N} \sigma(2k_j)} \left( \prod_{1 \leq i < j \leq N} A_{ij} \right) \prod_{i=1}^{N} e^{\theta_i}, \]

where the summation of \( \mu \) means to take all possible \( \mu_i = \{0, 1\} \) for \( i = 1, 2, \cdots, N \),

\[ \theta_i = -2\xi(k_i)x + \wp'(k_i)t + \theta_i^{(0)}, \quad \theta_i^{(0)} \in \mathbb{C}, \quad (3.27a) \]

\[ e^{\alpha_{ij}} = A_{ij} = \left( \frac{\sigma(k_i - k_j)}{\sigma(k_i + k_j)} \right)^2. \quad (3.27b) \]

**Proof** The proof consists of two parts. First, we will prove that \( f \) defined by (3.24) solves the bilinear KdV equation (3.25). In the second part, we will prove \( f \) can be written into Hirota’s form (3.26).

Noticing that \( \tilde{\tau} = \tilde{g} f \), and using formula (B.10) of the quasi-gauge property, we find

\[ D_x^4 \tilde{\tau} \cdot \tilde{\tau} = D_x^4 (\tilde{g} f) \cdot (\tilde{g} f) = \tilde{g}^2 D_x^4 f \cdot f + 6(D_x^2 \tilde{g} \cdot \tilde{g}) D_x^2 f \cdot f + f^2 D_x^4 \tilde{g} \cdot \tilde{g}, \]

\[ D_x^2 \tilde{\tau} \cdot \tilde{\tau} = D_x^2 (\tilde{g} f) \cdot (\tilde{g} f) = \tilde{g}^2 D_x^2 f \cdot f + f^2 D_x^2 \tilde{g} \cdot \tilde{g}, \]

\[ D_x D_t \tilde{\tau} \cdot \tilde{\tau} = D_x D_t (\tilde{g} f) \cdot (\tilde{g} f) = \tilde{g}^2 D_x D_t f \cdot f; \]

and meanwhile, recalling formulae (B.7) and (B.8), for the function \( g \) defined in (3.23), we have

\[ D_x^2 \tilde{g} \cdot \tilde{g} = 2 \left( \wp (x + \sum_{i=1}^{N} k_i) - \wp (x) \right) \tilde{g}^2, \]

\[ D_x^4 \tilde{g} \cdot \tilde{g} = 12 \wp (x + \sum_{i=1}^{N} k_i) D_x^2 \tilde{g} \cdot \tilde{g}. \]

These results give rise to

\[ 0 = (D_x^4 - 4D_x D_t - 12 \wp (x + \sum_{i=1}^{N} k_i) D_x^2) \tilde{\tau} \cdot \tilde{\tau} \]
\[ \quad = \tilde{g}^2 (D_x^4 - 4D_x D_t - 12 \wp (x) D_x^2) f \cdot f, \]

which indicates that \( f = \tilde{\tau}/\tilde{g} \) solves the bilinear KdV equation (3.25).
In the second part, we are going to prove \( f = \frac{\tilde{\tau}}{\tilde{g}} \) can be written as in (3.26). In light of (3.22), a generic term in \( f \) is

\[
\tilde{\tau}_g = \sigma(x + \sum_{j=1}^{N}(1 + \varepsilon_j)k_j) \cdot \left( \prod_{1 \leq i < j \leq N} \frac{\varepsilon_i\sigma(\varepsilon_i k_i - \varepsilon_j k_j)}{\sigma(k_i - k_j)} \right) 
\times \exp \left( -\sum_{j=1}^{N}(1 + \varepsilon_j)\tilde{\gamma}_j \right). \tag{3.28}
\]

In particular, when \(|\varepsilon| = 1\), e.g., only \( \varepsilon_{j_0} = 1 \) while all other \( \varepsilon_i \)'s are \(-1\), such a term is

\[
\Phi_x (2k_{j_0}) e^{\alpha_{j_0} e^{-2\tilde{\gamma}_{j_0}}},
\]

where

\[
e^{\alpha_{j_0}} = \sigma(2k_{j_0}) \prod_{1 \leq i \leq N} \frac{\sigma(k_{j_0} + k_i)}{\sigma(k_{j_0} - k_i) \cdot \text{sgn}[i - j_0]}.
\]

To proceed, we introduce

\[
S = \{1, 2, \cdots, N\}, \quad J_\varepsilon = \{n_1, n_2, \cdots, n_l\} \subset S,
\]

where \( J_\varepsilon \) is associated with \( \varepsilon \) via

\[
\varepsilon_i = \begin{cases} 
1, & i \in J_\varepsilon, \\
-1, & i \in S \setminus J_\varepsilon.
\end{cases}
\]

Equation (3.28) is then written as

\[
\frac{\tilde{\tau}_g}{\tilde{g}} = \frac{\sigma(x + 2\sum_{i \in J_\varepsilon} k_i)}{\sigma(x) \prod_{i \in J_\varepsilon} \sigma(2k_i)} \left( \prod_{i \in J_\varepsilon} e^{\beta_i} \right) \exp \left( -2 \sum_{i \in J_\varepsilon} \tilde{\gamma}_i \right), \tag{3.29}
\]

where

\[
e^{\beta_i} = \sigma(2k_i) \prod_{j \in S \setminus J_\varepsilon} \frac{\sigma(k_i + k_j)}{\sigma(k_i - k_j) \cdot \text{sgn}[j - i]}.
\]

Then, noticing that

\[
e^{\beta_i - \alpha_i} = \prod_{j \in J_\varepsilon \setminus i} \frac{\sigma(k_i - k_j)}{\sigma(k_i + k_j) \cdot \text{sgn}[j - i]},
\]

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which indicates that
\[
\prod_{i \in J_{\varepsilon}} e^{\beta_i - \alpha_i} = \prod_{i,j \in J_{\varepsilon}, i < j} \left( \frac{\sigma(k_i - k_j)}{\sigma(k_i + k_j)} \right)^2 = \prod_{i,j \in J_{\varepsilon}, i < j} A_{ij},
\] where \( A_{ij} \) is defined as in (3.27b), the term (3.29) is written as
\[
\tilde{\tau}_{\varepsilon} = \frac{\sigma(x + 2 \sum_{i \in J_{\varepsilon}} k_i)}{\sigma(x) \prod_{i \in J_{\varepsilon}} \sigma(2k_i)} \cdot \left( \prod_{i,j \in J_{\varepsilon}, i < j} A_{ij} \right) \exp \left( \sum_{i \in J_{\varepsilon}} \theta_i \right),
\] where \( \theta_i = -2\gamma_i + \alpha_i \), defined as in (3.27a). This indicates that \( f = \tilde{\tau}/\tilde{g} \) can be written into Hirota’s form (3.26) coupled with (3.27).

The proof is completed. \( \square \)

### 3.2 Vertex Operator

We look for a vertex operator that generates the \( \tau \) function (3.26) for elliptic solitons. To proceed, let us first list some notations. Let \( \mathbf{t} = (t_1 = x, t_2, \cdots, t_n, \cdots) \), \( \tilde{\eta} = (\partial_{t_1}, \frac{1}{2} \partial_{t_2}, \cdots, \frac{1}{n} \partial_{t_n}, \cdots) \), \( \tilde{\mathbf{t}} = (t_1 = x, t_3, \cdots, t_{2n+1}, \cdots) \), \( \tilde{\eta} = (\partial_{t_1}, \frac{1}{3} \partial_{t_3}, \cdots, \frac{1}{(2n+1)} \partial_{2n+1}, \cdots) \),

\[
\xi(t, k) = \sum_{n=1}^{\infty} k^n t_n, \quad \xi_{[e]}(t, k) = \sum_{n=1}^{\infty} (-1)^n \frac{\zeta^{(n-1)}(k)}{(n-1)!} t_n, \quad \xi^{(i)}(k) = \partial_k^i \zeta(k),
\] (3.30a)

\[
\theta(\tilde{\mathbf{t}}, k) = \xi(\mathbf{t}, k) - \xi(\mathbf{t}, -k) = 2 \sum_{n=0}^{\infty} k^{2n+1} t_{2n+1},
\] (3.30b)

\[
\theta_{[e]}(\tilde{\mathbf{t}}, k) = \xi_{[e]}(\mathbf{t}, k) - \xi_{[e]}(\mathbf{t}, -k) = -2 \sum_{n=0}^{\infty} \frac{\zeta^{(2n)}(k)}{(2n)!} t_{2n+1}.
\] (3.30c)

Consider the following \( \tau \) function which is equivalent to (3.26),

\[
\tau_N(\tilde{\mathbf{t}}) = \sum_{J \subset S} \left( \prod_{i \in J} c_i \right) \left( \prod_{i,j \in J, i < j} A_{ij} \right) \frac{\sigma(t_1 + 2 \sum_{i \in J} k_i)}{\sigma(t_1) \prod_{i \in J} \sigma(2k_i)} \exp \left( \sum_{i \in J} \theta_{[e]}(\tilde{\mathbf{t}}, k_i) \right),
\] (3.31)

where \( c_i \) are arbitrary constants, \( A_{ij} \) is defined as in (3.27b), \( S = \{1, 2, \cdots, N\} \), \( J \) is a subset of \( S \), and \( \sum_{J \subset S} \) means the summation runs over all subsets of \( S \). The vertex operator that generates the above \( \tau \) function is described below.
Theorem 3.3  The \( \tau \) function (3.31) can be generated by the vertex operator

\[
X(k) = \Phi_{t_1}(2k)e^{\theta_{|c|}(\bar{t},k)}e^{\theta_{\bar{c}}(\bar{t},k)}
\]

via

\[
\tau_N(\bar{t}) = e^{c_N X(k_N)} \circ \tau_{N-1}(\bar{t}), \quad \tau_0(\bar{t}) = 1,
\]

i.e.,

\[
\tau_N(\bar{t}) = e^{c_N X(k_N)} \cdots e^{c_2 X(k_2)} e^{c_1 X(k_1)} \circ 1.
\]

In addition, \( \tau_N(\bar{t}) \) is doubly periodic with respect to any \( k_i \), for \( i = 1, 2, \ldots, N \), where the two periods are those of \( \wp(k) \).

Let us prove the theorem through the following lemmas.

Lemma 3.2  For \( \theta \) and \( \theta_{|c|} \) defined in (3.30), we have

\[
e^{\theta_{|\bar{c}|}(\bar{t},k_i)} e^{\theta_{|c|}(\bar{t},k_j)} = A_{ij} e^{\theta_{|c|}(\bar{t},k_j)} e^{\theta_{|\bar{c}|}(\bar{t},k_i)},
\]

where \( A_{ij} \) is defined as (3.27b).

**Proof**  Considering the Taylor series in the neighborhood of \( q = 0 \), we have

\[
\ln \frac{\sigma(p - q)}{\sigma(p + q)} = \theta_{|c|}(\bar{e}(q), p),
\]

which indicates

\[
A_{ij} = e^{2\theta_{|c|}(\bar{e}(k_j), k_i)},
\]

where \( \bar{e}(q) = (q, \frac{q^3}{3}, \ldots, \frac{q^{2n+1}}{(2n+1)}, \ldots) \). Then, for any \( C^\infty \) function \( h(\bar{t}) \), one can directly verify that

\[
e^{\theta_{|\bar{c}|}(\bar{t},k_i)} e^{\theta_{|c|}(\bar{t},k_j)} \circ h(\bar{t}) = A_{ij} e^{\theta_{|c|}(\bar{t},k_j)} e^{\theta_{|\bar{c}|}(\bar{t},k_i)} \circ h(\bar{t}),
\]

i.e., relation (3.35) holds. \( \square \)

Note that (3.35) is formally similar to the result in the usual soliton case, cf. Date et al. (1981); Miwa et al. (1999). We are led by this lemma to the following.
Lemma 3.3  For the vertex operator $X(k)$ defined by (3.32), we have

$$X(k_i)X(k_j) = A_{ij} \frac{\sigma(t_1 + 2k_i + 2k_j)}{\sigma(t_1) \sigma(2k_i) \sigma(2k_j)} e^{\theta_{\epsilon(\tau, k_i)} + \theta_{\epsilon(\tau, k_j)}} e^{\theta(\bar{\tau}, k_i) + \theta(\bar{\tau}, k_j)},$$

(3.38a)

and hence

$$X(k) \cdot X(k) = 0, \quad e^{cX(k)} = 1 + cX(k).$$

(3.39)

With the above two lemmas in hand, we can confirm that $\tau_N(\bar{\tau})$ can be generated by the vertex operator $X(k)$ via (3.34), with (3.33) as a consequence. In addition, noticing that $\tau_1(\bar{\tau}) = e^{cX(k_1)} \circ 1$ is doubly periodic with respect to $k_1$, and $X(k_i)$ and $X(k_j)$ commute (see (3.38a) where we should consider $A_{ij}$ to be a rational function rather than a Laurent series of $k_i / k_j$ or $k_j / k_i$, cf. Date et al. (1981)), it follows that $\tau_N(\bar{\tau})$ defined by (3.34) is doubly periodic with respect to any $k_i$, for $i = 1, 2, \cdots, N$. Thus, Theorem 3.3 holds.

3.3 Bilinear Identity of the KdV Hierarchy

With the vertex operator and $\tau$ function in hand, we can construct bilinear equations for the KdV hierarchy that are adapted to the verification of the existence of elliptic soliton solutions.

To achieve that, let us first introduce a doubly periodic function.

Lemma 3.4  Consider a vertex operator

$$X(\bar{\tau}, q) = \frac{\sigma(t_1 + q)}{\sigma(q)} e^{\frac{1}{2} \theta_{\epsilon(\tau, q)}(\bar{\tau}, q)} e^{\frac{1}{2} \theta(\bar{\tau}, q)},$$

(4.0)

and introduce a function of $q$,

$$h(\bar{\tau}, q) = X(\bar{\tau}, q) \tau(\bar{\tau}),$$

(4.1)

where $\tau(\bar{\tau}) = \tau_N(\bar{\tau})$ is defined by (3.31). Then, $h(\bar{\tau}, q)$ is a doubly periodic function of $q$ with periods $2w_1$ and $2w_2$, where $w_i$ are the half periods of $\varphi(q)$. 
Proof Making use of relation (3.36), \( h(\bar{t}, q) \) can be explicitly written as
\[
\begin{align*}
  h(\bar{t}, q) &= \frac{\sigma(t_1 + q)}{\sigma(q)} e^{\frac{1}{2} \theta_q(\bar{t}, q)} \\
  &\times \sum_{J \subset S} \left[ \left( \prod_{i < j \in J} A_{ij} \right) \frac{\sigma(t_1 + 2 \sum_{i \in J} k_i + q)}{\sigma(t_1 + q)} \prod_{i \in J} \frac{\sigma(k_i - q)}{\sigma(q + k_i)} \right] \times e^{\sum_{i \in J} \theta_q(\bar{t}, k_i)}.
\end{align*}
\]

Note that in \( \frac{1}{2} \theta_q(\bar{t}, q) \), except the first term \( -\zeta(q)t_1 \), the rest part \( -\sum_{n=1}^{\infty} \frac{\zeta(2n)(q)}{(2n)!} t_{2n+1} \) is already doubly periodic with respect to \( q \). Following Proposition A.1, one can check that
\[
\frac{\sigma(t_1 + q)}{\sigma(q)} e^{-\zeta(q)t_1}, \quad \frac{\sigma(t_1 + 2 \sum_{i \in J} k_i + q)}{\sigma(t_1 + q)} \prod_{i \in J} \frac{\sigma(k_i - q)}{\sigma(q + k_i)}
\]
are doubly periodic too. This indicates \( h(\bar{t}, q) \) is a doubly periodic function of \( q \). Note that \( h(\bar{t}, q) \) is not elliptic as it has an essential singularity \( q = 0 \) (mod periodic lattice).

Then, we come up with an integral bilinear identity.

Theorem 3.4 For the function \( h(\bar{t}, q) \) defined in (3.41), we have the following bilinear identity
\[
\oint_{\Omega_1} \frac{dq}{2\pi i} h(\bar{t}, q) h(\bar{t}', -q) = 0,
\]

which gives rise to
\[
\text{Res}_{q=0} \left[ h(\bar{t}, q) h(\bar{t}', -q) \right] = 0,
\]

where the contour \( \Omega \) takes the boundary, anticlockwise, of the open fundamental period parallelogram \( \mathbb{D} \) (see Fig. 1) and all \( \{\pm k_i\} \) are distinct and belong to \( \mathbb{D} \).

Proof In light of Lemma 3.4, it is known the integrand \( h(\bar{t}, q) h(\bar{t}', -q) \) is a double-periodic function of \( q \). Meanwhile, noticing that in \( \mathbb{D} \) the integrand has only \( 2N \) isolated simple poles \( \{\pm k_i\}_{i=1}^{N} \) and one isolated essential singularity \( q = 0 \), there is a domain which contains the curve \( \Omega \) and where the integrand is continuous. Thus, since the integrand \( h(\bar{t}, q) h(\bar{t}', -q) \) is doubly periodic with respect to \( q \), if we integrate it, anticlockwise, along the boundary of the fundamental period parallelogram \( \mathbb{D} \), we will arrive at (3.43).

To prove the second identity (3.44), we examine residues of the integrand at \( q = \pm k_i \). For given \( j_0 \in S \), \( q = k_{j_0} \) is a simple pole of \( h(\bar{t}', -q) \) but \( h(\bar{t}, q) \) is analytic at
this point. Thus, we have

$$\text{Res}_{q=k_{j_0}} \left[ h(t', q) h(t', -q) \right] = h(t, k_{j_0}) \times \text{Res}_{q=k_{j_0}} \left[ h(t', -q) \right].$$  \hspace{1cm} (3.45)

$h(t', -q)$ has a similar summation expression as (3.42). For any $J$ that does not contain $j_0$, the associated terms in the summation expression of $h(t', -q)$ contribute nothing to the residue at $q = k_{j_0}$. Therefore we have

$$\text{Res}_{q=k_{j_0}} \left[ h(t', -q) \right] = \text{Res}_{q=k_{j_0}} \left[ g(t', q) \right],$$  \hspace{1cm} (3.46)

where $g(t', q)$ is a collection of all those $k_{j_0}$-related terms in $h(t', -q)$, which is

$$g(t', q) = -e^{\frac{1}{2} \theta_{t_0} \sigma(t', q)} \sum_{J \subset S \setminus \{j_0\}} \left[ \prod_{i < j \in J} A_{ij} \right] \left[ \prod_{i \in J} C_i \sigma(k_i + q) \sigma(k_i - q) \right] \prod_{i \in J} \sigma(2k_i) \times \text{Res}_{q=k_{j_0}} \left[ g(t', q) \right].$$

where

$$B_{j_0} = c_{j_0} \sigma(t'_1 + 2 \sum_{i \in J} k_i + 2k_{j_0} - q) \left( \prod_{i \in J} \sigma^2(k_i - k_{j_0}) \left( \prod_{i \in J} \sigma^2(k_i + k_{j_0}) \right) \right) \sigma(k_{j_0} + q) \sigma(k_{j_0} - q).$$

Note that $q = k_{j_0}$ is a simple pole of $B_{j_0}$. A direct calculation yields

$$\text{Res}_{q=k_{j_0}} \left[ g(t', q) \right] = \frac{c_{j_0} e^{\frac{1}{2} \theta_{t_0} \sigma(t', k_{j_0})}}{\sigma(k_{j_0})} \sum_{J \subset S \setminus \{j_0\}} \left[ \prod_{i < j \in J} A_{ij} \right] \left[ \prod_{i \in J} C_i \sigma(k_i - k_{j_0}) \sigma(k_i + k_{j_0}) \right] \sigma(t'_1 + 2 \sum_{i \in J} k_i + k_{j_0}) \sigma(2k_i).$$
where we have made use of
\[
\lim_{q \to j_0} \left( \prod_{i \in J} c_i \frac{\sigma(k_i + q)}{\sigma(k_i - q)} \right) \left( \prod_{i \in J} \frac{\sigma^2(k_i - k_j)}{\sigma^2(k_i + k_j)} \right) = \prod_{i \in J} c_i \frac{\sigma(k_i - k_j)}{\sigma(k_i + k_j)}.
\]

Recalling the expression (3.42) for \( h(\bar{q}, q) \), in the summation, such terms will vanish as they are generated by \( J \) that contains \( j_0 \). Thus, from (3.45) we have
\[
\text{Res}_{q = k_0} \left[ h(\bar{q}, q)h(\bar{q}', -q) \right] = \frac{c_{k_0} e^{\frac{i}{2} \theta_{i,j}(\bar{i}, k_{j_0}) + \frac{i}{2} \theta_{i,j'}(\bar{i}', k_{j_0})}}{\sigma^2(k_{j_0})} \times \sum_{J \subset S(\{j_0\})} \left[ \prod_{i < j \in J} A_{ij} \right] \left[ \prod_{i \in J} c_i \frac{\sigma(k_i - k_{j_0})}{\sigma(k_i + k_{j_0})} \right] \frac{\sigma(t_1 + 2 \sum_{i \in J} k_i + k_{j_0})}{\prod_{i \in J} \sigma(2k_i)} \cdot e^{\sum_{i \in J} \theta_{i,j}(\bar{i}, k_i)}
\]
\[
\times \sum_{J \subset S(\{j_0\})} \left[ \prod_{i < j \in J} A'_{ij} \right] \left[ \prod_{i \in J} c_i \frac{\sigma(k_i - k_{j_0})}{\sigma(k_i + k_{j_0})} \right] \frac{\sigma(t'_1 + 2 \sum_{i \in J} k_i + k_{j_0})}{\prod_{i \in J} \sigma(2k_i)} \cdot e^{\sum_{i \in J} \theta_{i,j'}(\bar{i}', k_i)}.
\]

In a similar way, we can calculate the residue of the integrand at \( q = -k_{j_0} \). It turns out that
\[
\text{Res}_{q = -k_{j_0}} \left[ h(\bar{q}, q)h(\bar{q}', -q) \right] = - \text{Res}_{q = k_{j_0}} \left[ h(\bar{q}, q)h(\bar{q}', -q) \right],
\]
which means finally all residues at \( q = \pm k_i \) cancel, and the remained residue at \( q = 0 \) gives rise to the bilinear identity (3.44).

The proof is completed. \( \square \)

### 3.4 Algorithm for Calculating Residues

In the following, we formulate an algorithm to calculate residues from the identity (3.44) so that the bilinear KdV hierarchy with elliptic solitons can be obtained.

Redefining \( \tau'(\bar{i}) = \sigma(t_1) \tau(\bar{i}) \), the bilinear identity (3.43) is written as
\[
\oint_{\Omega} \frac{dq}{2\pi i} \frac{1}{\sigma^2(q)} e^{\frac{i}{2} \theta_{i,j}(\bar{i} - \bar{q}, q)} \tau'(\bar{i} + \bar{\tau}(q)) \tau'(\bar{i}' - \bar{\tau}(q)) = 0. \tag{3.47}
\]

Then, introducing \( \bar{\tau} = \bar{x} + \bar{\tau} \) and \( \bar{\tau}' = \bar{x} - \bar{\tau} \), where \( \bar{x} = (x_1, x_3, \cdots) \), \( \bar{\tau} = (y_1, y_3, \cdots) \), the above equation is written as
\[
\oint_{\Omega} \frac{dq}{2\pi i} \frac{1}{\sigma^2(q)} e^{\theta_{i,j}(\bar{y}, q)} e^{(\bar{y} + \bar{\tau}(q))} D_\tau'(\bar{x}) \cdot \tau'(\bar{x}) = 0, \tag{3.48}
\]
and from (3.44) we have

\[
\text{Res}_{q=0} \left[ \frac{1}{\sigma^2(q)} e^{\theta_{(\eta)}}(\Upsilon, q) e^{(\Upsilon + \tau(q))} D_x \tau'(\mathbf{x}) \cdot \tau'(\mathbf{x}) \right] = 0, \quad (3.49)
\]

where \( D_x = (D_{x_1}, D_{x_3}, D_{x_5}, \ldots) \), and for two vectors \( \mathbf{a} = (a_1, a_2, \ldots) \) and \( \mathbf{b} = (b_1, b_2, \ldots) \) their vector product is defined as \( \mathbf{a} \cdot \mathbf{b} = \sum_{i=1}^\infty a_i b_i \). Note that in the usual soliton case, the term \( \frac{1}{\sigma^2(q)} e^{\theta_{(\eta)}}(\Upsilon, q) \) in (3.49) is \( \frac{1}{q} e^{\theta(\Upsilon, 1/q)} \) instead, cf. Jimbo and Miwa (1983); Miwa et al. (1999); \( e^{\theta(\Upsilon, 1/q)} \) has a definite expansion in terms of \( q \) but \( e^{\theta_{(\eta)}}(\Upsilon, q) \) does not. \(^2\) This is the obstacle when calculating the residue at \( q = 0 \). We need to design an algorithm to calculate the residue in (3.49).

To develop the algorithm, we write (3.49) into the following form

\[
\text{Res}_{q=0} \left[ e^{(B + D_x) \Upsilon} \frac{1}{\sigma^2(q)} e^{\xi_{(\eta)}}(\Upsilon, q) \tau'(\mathbf{x}) \cdot \tau'(\mathbf{x}) \right] = 0, \quad (3.50)
\]

where \( \xi_{(\eta)} \) is defined as in (3.30) and

\[
\overline{B} = -2(\xi(q), \xi''(q), \ldots, \xi^{(2n)}(q), \ldots), \quad \overline{D_x} = (D_{x_1}, 0, \frac{1}{3} D_{x_3}, 0, \frac{1}{5} D_{x_5}, \ldots).
\]

For convenience, we introduce polynomials \( \{ p_n(t) \} \) by Miwa et al. (1999)

\[
e^{\xi(t, k)} = \sum_{n=0}^{\infty} p_n(t) k^n, \quad (3.51)
\]

where

\[
p_n(t) = \sum_{\|\alpha\|=n} \frac{t^\alpha}{\alpha!}, \quad t = (t_1, t_2, \ldots), \quad \alpha = (\alpha_1, \alpha_2, \ldots),
\]

\[
\|\alpha\| = \sum_{j=0}^{\infty} j \alpha_j, \quad \alpha! = \alpha_1! \alpha_2! \cdots, \quad t^\alpha = t_1^{\alpha_1} t_2^{\alpha_2} \cdots.
\]

The first few \( \{ p_n(t) \} \)'s are

\[
p_0(t) = 1, \quad p_1(t) = t_1, \quad p_2(t) = \frac{1}{2} t_1^2 + t_2, \quad p_3(t) = \frac{1}{3!} t_1^3 + \frac{1}{2} t_1 t_2 + t_3, \quad p_4(t) = \frac{1}{4!} t_1^4 + \frac{1}{2} t_1^2 t_2 + \frac{1}{2} t_2^2 + t_1 t_3 + t_4.
\]

\(^2\) One can formally write \( e^{\theta_{(\eta)}}(\Upsilon, q) = \sum_{j=-\infty}^{\infty} h_j(\Upsilon) q^j \) but \( h_j(\Upsilon) \) cannot be expressed explicitly.
Meanwhile, $1/\sigma^2(q)$ is expanded as

$$\frac{1}{\sigma^2(q)} = \sum_{j=0}^{\infty} \mu_j q^{j-2} = \frac{1}{q^2} (1 + \frac{g_2}{120} q^4 + \frac{g_3}{420} q^6 + \frac{13g_2^2}{201600} q^8 + \cdots). \quad (3.52)$$

Then, the bilinear identity (3.50) is written as

$$0 = \text{Res}_{q=0} \left[ \left( \sum_{|\beta|=0}^{\infty} \frac{(\overline{B} + D_x)^\beta}{\beta!} \overline{y}^{\beta} \right) \left( \sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j (\tilde{D}_x)^x \mu_{n-j} q^{n-2} \right) \tau'(\overline{x}) \cdot \tau'(\overline{x}) \right]$$

$$= \sum_{|\beta|=0}^{\infty} \text{Res}_{q=0} \left[ \frac{(\overline{B} + D_x)^\beta}{\beta!} \left( \sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j (\tilde{D}_x)^x \mu_{n-j} q^{n-2} \right) \tau'(\overline{x}) \cdot \tau'(\overline{x}) \right] \overline{y}^{\beta}, \quad (3.53)$$

where $\overline{\beta} = (\beta_1, \beta_2, \cdots, \beta_{2j+1}, \cdots)$ and $|\overline{\beta}| = \sum_{j=0}^{\infty} \beta_{2j+1}$. Since $\{y_i\}$ are arbitrary, it then follows that

$$\text{Res}_{q=0} \left[ \frac{(\overline{B} + D_x)^\overline{\beta}}{\overline{\beta}!} \left( \sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j (\tilde{D}_x)^x \mu_{n-j} q^{n-2} \right) \tau'(\overline{x}) \cdot \tau'(\overline{x}) \right] = 0. \quad (3.54)$$

In the above equation, $\sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j (\tilde{D}_x)^x \mu_{n-j} q^{n-2}$ is a Laurent series of $q$ starting from $q^{-2}$. For another term $(\overline{B} + D_x)^\overline{\beta}$, first, given $\overline{\beta}$, contains only finite number of nonzero $\beta_j$. Thus, assume $\overline{\beta} = (\beta_1, \beta_2, \cdots, \beta_{2n+1}, 0, 0, \cdots)$ without loss of generality. Meanwhile, we shall note that the entries in $\overline{B}$ have a form $B_{2j+1} = -2 \zeta(2j)(q)$ where $\zeta(q)$ can be expanded as $\zeta(q) = (A.6b)$. Since $|\overline{\beta}|$ is finite, $(\overline{B} + D_x)^\overline{\beta}$ is a Laurent series of $q$ as well and it starts from $q^{-1}|\overline{\beta}|$ where $|\overline{\beta}| = \sum_{j=0}^{\infty} (2j+1)\beta_{2n+1}$ is finite and positive. This means, to calculate the residue (3.54), it is sufficient to consider the finite number of terms from $q^{-|\overline{\beta}|}$ to $q^1$ in $(\overline{B} + D_x)^\overline{\beta}$ and the finite number of terms from $q^{-2}$ to $q^{-|\overline{\beta}|+1}$ in $\sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j (\tilde{D}_x)^x \mu_{n-j} q^{n-2}$. Thus, we are led to the following theorem which formulates an algorithm to derive bilinear KdV hierarchy through calculating residues (3.54).

**Theorem 3.5** The bilinear KdV hierarchy are given by

$$\text{Res}_{q=0} \left[ (\overline{B} + D_x)^\overline{\beta} \right] |_{\overline{\beta} \leq 1} \left( \sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j (\tilde{D}_x)^x \mu_{n-j} q^{n-2} \right) \tau'(\overline{x}) \cdot \tau'(\overline{x}) = 0. \quad (3.55)$$

where $\overline{\beta}$ is set of nonnegative integers with finite and positive $|\overline{\beta}|$, and $(\overline{B} + D_x)^\overline{\beta} |_{\overline{\beta} \leq 1}$ means those terms of $q^j$ with $j \leq 1$ in the Laurent series of $(\overline{B} + D_x)^\overline{\beta}$.

As examples, when $\overline{\beta} = (3, 0, 0, \cdots)$, from the above theorem we find

$$(D_3^4 - 4D_{x_1}D_{x_3} - g_2) \tau' \cdot \tau' = 0,$$
which is the bilinear KdV equation (3.4). For the cases \( \tilde{\beta} = (2, 1, 0, \cdots) \) and \( \tilde{\beta} = (5, 0, 0, \cdots) \), we have, respectively,

\[
\begin{align*}
(D_1^6 + 4D_3^3 D_3 - 32D_3^2 + 3g_2D_3 - 24g_3)\tau' \cdot \tau' &= 0, \\
(D_1^6 + 40D_3^3 D_3 + 40D_3^2 - 216D_3 D_5 + 3g_2D_3 - 24g_3)\tau' \cdot \tau' &= 0.
\end{align*}
\]

(3.56a) 
(3.56b)

When \( g_2, g_3 \) are 0, these equations degenerate to those in the KdV hierarchy for the usual soliton case, cf. Jimbo and Miwa (1983).

### 4 \( \tau \) Function, Vertex Operator and Bilinear Identity: KP

Both the KdV and KP equation serve as representative models in integrable systems, while the latter plays a more fundamental role in Sato’s theory of integrable systems. Based on the exploration in the previous section for the KdV equation, in this section we will focus on the KP equation and investigate its \( \tau \) function, vertex operator and bilinear identity associated with elliptic solitons.

#### 4.1 Elliptic \( N \)-Solitons and \( \tau \) Function in Hirota’s Form

The KP equation is\(^3\)

\[
4u_t - u_{xxx} - 6uu_x - 3\partial^{-1}u_{yy} = 0,
\]

(4.1)

or in the potential form \( (u = v_x) \)

\[
4v_t - v_{xxx} - 3(v_x)^2 - 3\partial^{-1}v_{yy} = 0.
\]

(4.2)

By the transformation

\[
u = -2g\phi(x) + 2(\ln \tau)_{xx},
\]

(4.3)

or

\[
v = 2\zeta(x) + \frac{g_2}{4}t + 2(\ln \tau)_x,
\]

(4.4)

the KP equation is bilinearized as

\[
(D_4^4 - 4D_x D_t - 12\phi(x)D_x^2 + 3D_y^2)\tau \cdot \tau = 0,
\]

(4.5)

\(^3\) Usually,

\[
4u_t - u_{xxx} - 6uu_x - 3\alpha^2\partial^{-1}u_{yy} = 0
\]

is known as KP-I when \( \alpha^2 = -1 \) and KP-II when \( \alpha^2 = 1 \). We consider KP-II without loss of generality.
or
\[
(D_x^4 - 4D_xD_t + 3D_y^2 - g_2)\tau' \cdot \tau' = 0,
\]
(4.6)
where \(\tau' = \sigma(x)\tau\). The bilinear KP equation allows elliptic soliton solutions.

**Theorem 4.1** The following Wronskian
\[
\tau = |N - 1^|
\]
(4.7)
is a solution to the bilinear KP equation (4.5), where \(\tau\) is composed by vector \(\varphi = (\varphi_1, \cdots, \varphi_N)^T\) with entries
\[
\varphi_j(x, y, t) = \Phi_x(k_j)e^{-\gamma(k_j)} + \Phi_x(l_j)e^{-\gamma(l_j)},
\]
(4.8a)
where
\[
\gamma(k) = \xi(k)x + \wp(k)y - \frac{\wp'(k)}{2}t + \gamma^{(0)}(k), \quad k \in \mathbb{C}
\]
(4.8b)
with a constant \(\gamma^{(0)}(k)\) related to \(k\). Note that \(\varphi_j\) satisfies
\[
\varphi_{j,y} = -\varphi_{j,xx} + 2\wp(x)\varphi_j,
\]
\[
\varphi_{j,t} = \varphi_{j,xxx} - 3\wp(x)\varphi_{j,x} - \frac{3}{2}\wp'(x)\varphi_j.
\]
(4.9)
The proof will be given in Appendix C.

To find out a corresponding Hirota’s form of the \(\tau\) function (4.7), we consider (4.7) to be a summation of \(2N\) terms, i.e., \(\tau = \sum_{J \subset S} \tau_J\), where the generic term \(\tau_J\) is the Wronskian \(\widehat{|N - 1|}\) generated by
\[
\varphi = (\phi_1, \phi_2, \cdots, \phi_N)^T,
\]
(4.10)
where \(\phi_j = \Phi_x(k_j)e^{-\gamma(k_j)}\) for \(j \in J\) and \(\phi_j = \Phi_x(l_j)e^{-\gamma(l_j)}\) for \(j \in S \setminus J\). \(J\) is a subset of \(S = \{1, 2, \cdots, N\}\). In light of Lemma 3.1, we immediately get the following result.

**Lemma 4.1** The Wronskian \(\tau_J\) generated by vector (4.10) can be expressed as
\[
\tau_J = (-1)^{\frac{N(N-1)}{2}} \frac{\sigma(x) + \sum_{i \in J} k_i + \sum_{j \in S \setminus J} l_j}{\sigma(x)} \prod_{i \in J} \sigma(k_i - l_j) \frac{\prod_{j \in J} \sigma(k_i)}{(\prod_{i \in J} \sigma(k_i)) (\prod_{j \in S \setminus J} \sigma(l_i))} \exp \left[ -\sum_{i \in J} \gamma(k_i) - \sum_{j \in S \setminus J} \gamma(l_j) \right],
\]
(4.11)
especially, when $J$ is the empty set $\emptyset$, we have

\[
g(x, y, t) = \tau_\emptyset = (-1)^{\frac{N(N-1)}{2}} \frac{\sigma(x + \sum_{j \in S} l_j)}{\sigma(x)} \prod_{i < j \in S} \sigma(l_i - l_j) \prod_{j \in S} \sigma^N(l_j) \exp \left( -\sum_{j \in S} \gamma(l_j) \right).
\]

(4.12)

Next, for a function $f(x)$, we introduce notation $\tilde{f}(x) = f(x - \sum_{i=1}^N l_i)$. Then, similar to the KdV case, we have the following.

**Theorem 4.2** For the function $\tau$ in Wronskian form (4.7) and $g$ given by (4.12),

\[
f = \frac{\tilde{\tau}}{\tilde{g}}
\]

is a solution to the bilinear KP equation (4.5), i.e.,

\[
(D_x^4 - 4D_x D_t - 12\wp(x)D_x^2 + 3D_y^2)f \cdot \tilde{\tau} = 0,
\]

(4.14)

and $f$ is written in Hirota’s form as

\[
f = \sum_{\mu=0,1} \frac{\sigma(x + \sum_{i=1}^N \mu_i (k_i - l_i))}{\sigma(x) \prod_{i=1}^N \sigma^{\mu_i}(k_i - l_i)} \exp \left( \sum_{j=1}^N \mu_j \theta_j + \sum_{1 \leq i < j} \mu_i \mu_j a_{ij} \right),
\]

(4.15)

where the summation of $\mu$ means to take all possible $\mu_i = \{0, 1\}$ for $i = 1, 2, \cdots, N$,

\[
\theta_i = -(\zeta(k_i) - \zeta(l_i))x - (\wp(k_i) - \wp(l_i))y + \frac{1}{2} (\wp'(k_i) - \wp'(l_i))t + \theta_i^{(0)}, \quad \theta_i^{(0)} \in \mathbb{C},
\]

(4.16a)

\[
e^{a_{ij}} = A_{ij} = \frac{\sigma(k_i - k_j)\sigma(l_i - l_j)}{\sigma(k_i - l_j)\sigma(l_i - k_j)}.
\]

(4.16b)

**Proof** First, by virtue of the quasi-gauge property of bilinear equations (see Proposition B.1) and making use of identity (B.11), Eq. (4.14) can be derived from

\[
(D_x^4 - 4D_x D_t - 12\wp(x - \sum_{i=1}^N l_i)D_x^2 + 3D_y^2)\tilde{\tau} \cdot \tilde{\tau} = 0,
\]

where $\tilde{\tau} = f\tilde{g}$. 
Next, to write $\tilde{\tau}/\tilde{g}$ into an explicit form, let us look at the generic term $\tilde{\tau}_J/\tilde{g}$ in $f$. It follows from Lemma 4.1 that

$$\frac{\tilde{\tau}_J}{\tilde{g}} = \frac{\sigma(x + \sum_{i \in J}(k_i - l_i))}{\sigma(x)} \prod_{i \in J} \frac{\sigma(k_i - k_j)}{\sigma(l_i - l_j)} \left( \prod_{i \in J} e^{\beta_i} \right) \times \exp \left[ - \sum_{i \in J} (\tilde{\gamma}(k_i) - \tilde{\gamma}(l_i)) \right], \quad (4.17)$$

where $\tilde{\gamma}(k) = \gamma(k)|_{x \to x - \sum_{i=1}^N l_i}$ and

$$e^{\beta_i} = \sigma(k_i - l_i) \frac{\sigma^N(l_i)}{\sigma^N(k_i)} \prod_{j \in S \setminus J} \frac{\sigma(k_i - l_j)}{\sigma(l_i - l_j)}.$$

In particular, if $J$ contains a single element, e.g., $J = \{i\}$, we have

$$\frac{\tilde{\tau}_i}{\tilde{g}} = \Phi_i(k_i - l_i) e^{\alpha_i} e^{-\tilde{\gamma}(k_i) + \tilde{\gamma}(l_i)},$$

where

$$e^{\alpha_i} = \sigma(k_i - l_i) \frac{\sigma^N(l_i)}{\sigma^N(k_i)} \prod_{j \in S \setminus i} \frac{\sigma(k_i - l_j)}{\sigma(l_i - l_j)}.$$

Define $\theta_i^{(0)} = \alpha_i - \gamma^{(0)}(k_i) + \gamma^{(0)}(l_i) + \sum_{j=1}^N l_j(\xi(k_i) - \xi(l_i))$ such that $e^{\alpha_i} e^{-\tilde{\gamma}(k_i) + \tilde{\gamma}(l_i)} = e^{\theta_i}$ where $\theta_i$ is defined as in (4.16a). Then, the generic term (4.17) in $f$ is written into

$$\frac{\tilde{\tau}_J}{\tilde{g}} = \frac{\sigma(x + \sum_{i \in J}(k_i - l_i))}{\sigma(x)} \prod_{i \in J} \frac{\sigma(k_i - l_i)}{\sigma(l_i - l_i)} \left( \prod_{i \in J} A_{ij} \right) \exp \left( \sum_{i \in J} \theta_i \right),$$

where we have made use of

$$\prod_{i \in J} e^{\beta_i - \alpha_i} = \prod_{i,j \in J} \frac{\sigma(l_i - l_j)}{\sigma(k_i - l_j)} = \prod_{i,j \in J} \frac{\sigma^2(l_i - l_j)}{\sigma(k_i - l_j) \sigma(l_i - k_j)}$$

and $A_{ij}$ is defined as in (4.16b). It then turns out that $f = \sum_{J \subset S} \tilde{\tau}_J/\tilde{g}$ takes the explicit Hirota’s form (4.15). \qed
4.2 Vertex Operator

We now present a vertex operator that can generate $\tau$ functions for elliptic soliton solutions of the KP hierarchy. Introduce a vertex operator

$$X(k, l) = \Phi_{t_1} (k - l) e^{\xi_{[e]}(t, k) - \xi_{[e]}(t, l)} e^{\xi(\tilde{\theta}, k) - \xi(\tilde{\theta}, l)}, \quad (4.18)$$

where $\xi$ and $\xi_{[e]}$ are defined in (3.30), and $\tilde{\theta} = (\partial_{t_1}, \frac{1}{2} \partial_{t_2}, \ldots, \frac{1}{n} \partial_{t_n}, \ldots)$. Similar to the relation (3.36) and Lemma 3.2, for $A_{ij}$ defined in (4.16b), it can be proved that

$$\ln A_{ij} = \xi_{[e]}(\varepsilon(k_j) - \varepsilon(l_j), k_i) - \xi_{[e]}(\varepsilon(k_j) - \varepsilon(l_j), l_i) \quad (4.19)$$

and

$$X(k_i, l_i) X(k_j, l_j) = A_{ij} \frac{\sigma(t_1 + k_i - l_i + k_j - l_j)}{\sigma(t_1) \sigma(k_i - l_i) \sigma(k_j - l_j)} : X(k_i, l_i) X(k_j, l_j) :, \quad (4.20a)$$

where $\varepsilon(q) = (q, q^2, q^3, \ldots, q^n, \ldots)$, and by $:X:$ we denote the normalization of the exponential part of the vertex operator $X$ by moving all differential operators in $X$ to the right, e.g., here we have

$$: X(k_i, l_i) X(k_j, l_j) : = e^{\xi_{[e]}(t, k_i) - \xi_{[e]}(t, l_i)} e^{\xi_{[e]}(t, k_j) - \xi_{[e]}(t, l_j)} e^{\xi(\tilde{\theta}, k_i) - \xi(\tilde{\theta}, l_i)} e^{\xi(\tilde{\theta}, k_j) - \xi(\tilde{\theta}, l_j)}.$$

(4.20b)

A more general version of (4.20a) is

$$\prod_{i=1}^{N} X(k_i, l_i) = \left( \prod_{1 \leq i < j \leq N} A_{ij} \right) \frac{\sigma(t_1 + \sum_{i=1}^{N} (k_i - l_i))}{\sigma(t_1) \prod_{i=1}^{N} \sigma(k_i - l_i)} : \prod_{i=1}^{N} X(k_i, l_i) :, \quad (4.21)$$

It then follows that

$$X^2(k, l) = 0, \quad e^{c X(k, l)} = 1 + c X(k, l), \quad e^{c X(k, l)} \circ 1 = 1 + c \Phi_{t_1} (k - l) e^{\xi_{[e]}(t, k) - \xi_{[e]}(t, l)},$$

which leads us to the following result for elliptic $N$-soliton solution.

**Theorem 4.3** For the KP hierarchy, its $\tau$ function of elliptic $N$-soliton solution,

$$\tau_N(t) = \sum_{J \subseteq S} \left( \prod_{i \in J} c_i \right) \left( \prod_{i < j \in J} A_{ij} \right) \frac{\sigma(t_1 + \sum_{i \in J} (k_i - l_i))}{\sigma(t_1) \prod_{i \in J} \sigma(k_i - l_i)} e^{\sum_{i \in J} (\xi_{[e]}(t, k_i) - \xi_{[e]}(t, l_i))}, \quad (4.22)$$
is generated by the vertex operator (4.18) via

\[ \tau_N(t) = e^{c_N X(k_N \lambda_N)} \cdots e^{c_2 X(k_2 \lambda_2)} e^{c_1 X(k_1 \lambda_1)} \circ 1, \quad (4.23) \]

or via transformation

\[ \tau_N(t) = e^{c_N X(k_N \lambda_N)} \circ \tau_{N-1}(t), \quad \tau_0(t) = 1. \quad (4.24) \]

In addition, \( \tau_N(t) \) is a doubly periodic function with respect to any \( k_i \) and \( l_j \) for \( i, j = 1, 2, \ldots, N \).

The proof is similar to Theorem 3.3 for the KdV equation and we skip it. Note also that the single Lamé-type PWF of the KP hierarchy is

\[ \rho = X(k, l) \circ 1 = \Phi_{11}(k-l) e^{\xi_{[\epsilon]}(t, k) - \xi_{[\epsilon]}(t, l)}. \quad (4.25) \]

### 4.3 Bilinear Identity

Define two functions of \( q \),

\[
\begin{align*}
    h(t, q) &= X(t, q) \tau(t), \\
    h^*(t, q) &= X^*(t, q) \tau(t),
\end{align*}
\]

where \( \tau(t) = \tau_N(t) \) is given by (4.22), \( X(t, q) \) and \( X^*(t, q) \) are vertex operators

\[
\begin{align*}
    X(t, q) &= \frac{\sigma(t_1 + q)}{\sigma(q)} e^{\xi_{[\epsilon]}(t, q)} e^{\xi(\tilde{\lambda}, q)}, \\
    X^*(t, q) &= \frac{\sigma(t_1 - q)}{\sigma(-q)} e^{-\xi_{[\epsilon]}(t, q)} e^{-\xi(\tilde{\lambda}, q)}.
\end{align*}
\]

Similar to Lemma 3.4 for the KdV case, we can write \( h(t, q) \) and \( h^*(t, q) \) in their explicit forms,

\[
\begin{align*}
    h(t, q) &= \frac{\sigma(t_1 + q)}{\sigma(q)} e^{\xi_{[\epsilon]}(t, q)} \\
    &\quad \times \sum_{J \subset S} \left( \prod_{i \in J} A_{i,j} \right) \frac{\sigma(t_1 + \sum_{i \in J} (k_i - l_i) + q)}{\sigma(t_1 + q) \prod_{i \in J} \sigma(k_i - l_i)} \left( \prod_{i \in J} \frac{\sigma(k_i) \sigma(q - k_i)}{\sigma(l_i) \sigma(q - l_i)} e^{\theta_{[\epsilon]}(t, k_i, l_i)} \right),
\end{align*}
\]

\[
\begin{align*}
    h^*(t, q) &= \frac{\sigma(t_1 - q)}{\sigma(-q)} e^{-\xi_{[\epsilon]}(t, q)} \\
    &\quad \times \sum_{J \subset S} \left( \prod_{i \in J} A_{i,j} \right) \frac{\sigma(t_1 - \sum_{i \in J} (k_i - l_i) - q)}{\sigma(t_1 - q) \prod_{i \in J} \sigma(k_i - l_i)} \left( \prod_{i \in J} \frac{\sigma(k_i) \sigma(q - l_i)}{\sigma(l_i) \sigma(q - k_i)} e^{-\theta_{[\epsilon]}(t, k_i, l_i)} \right),
\end{align*}
\]

where \( \theta_{[\epsilon]}(t, k_i, l_i) = \xi_{[\epsilon]}(t, k_i) - \xi_{[\epsilon]}(t, l_i) \). Then, it can be verified that both functions are doubly periodic with respect to \( q \) with the same periods as \( \varphi(q) \).

Similar to the KdV case, we can construct a bilinear identity for the KP hierarchy.
Theorem 4.4  For the functions $h(t, q)$ and $h^*(t', q)$ defined in (4.26), we have

$$\oint_{\Omega} \frac{dq}{2\pi i} h(t, q) h^*(t', q) = 0,$$  \hspace{1cm} (4.28)

which gives rise to

$$\text{Res}_{q=0} \left[ h(t, q) h^*(t', q) \right] = 0,$$  \hspace{1cm} (4.29)

where the contour $\Omega$ takes the boundary, anticlockwise, of the open fundamental period parallelogram $\mathbb{D}$ (see Fig. 1) and all $\{k_i\}$ and $\{l_i\}$ are distinct and belong to $\mathbb{D}$.

Proof  The first identity (4.28) can be proved as the identity (3.43) for the KdV case.

For the second one, first, note that the integrand $h(t, q) h^*(t', q)$ has only $2N$ isolated simple poles $\{k_i\}_{i=1}^N$, $\{l_i\}_{i=1}^N$, and one isolated essential singularity $q = 0$ in $\mathbb{D}$. Then, for given $j_0 \in S$, we are going to prove the following relation,

$$\text{Res}_{q=k_{j_0}} \left[ h(t, q) h^*(t', q) \right] = - \text{Res}_{q=l_{j_0}} \left[ h(t, q) h^*(t', q) \right].$$  \hspace{1cm} (4.30)

In fact, similar to the KdV case, for given $j_0 \in S$, we have

$$\text{Res}_{q=k_{j_0}} \left[ h(t, q) h^*(t', q) \right] = - \frac{c_{j_0}}{\sigma(k_{j_0})\sigma(l_{j_0})} \epsilon[k_{j_0} - l_{j_0}](t, t', t', t_{j_0})$$

$$\times \left( \sum_{J \in S \setminus \{k_{j_0}\}} \left( \prod_{i<j \in J} A_{ij} \prod_{j \in J} l_{j} \sigma(k_{j_0} - k_{j}) \sigma(l_{j_0} - l_{j}) \frac{1}{\prod_{i \in J} \sigma(l_{j_0} - l_{j})} \right) \right)$$

$$\times \left( \sum_{J \in S \setminus \{l_{j_0}\}} \left( \prod_{i<j \in J} A_{ij} \prod_{j \in J} l_{j} \sigma(k_{j_0} - l_{j}) \sigma(l_{j_0} - k_{j}) \frac{1}{\prod_{i \in J} \sigma(l_{j_0} - k_{j})} \right) \right),$$

and $\text{Res}_{q=l_{j_0}} \left[ h(t, q) h^*(t', q) \right]$ has the same form but with “+” sign instead. Thus, (4.30) holds and then (4.29) follows.

In what follows, we derive bilinear hierarchy from the identity (4.29). We introduce $\tau'(t) = \sigma(t_1) \tau(t)$ and $t = x + y$ and $t' = x - y$, where $x = (x_1, x_2, x_3, \ldots)$, $y = (y_1, y_2, y_3, \ldots)$. Then, the bilinear identity (4.29) gives rise to

$$\text{Res}_{q=0} \left[ \frac{1}{\sigma^2(q)} e^{2\xi_t[y,q]} \tau'(x + y + \varepsilon(q)) \tau'(x - y - \varepsilon(q)) \right] = 0,$$  \hspace{1cm} (4.31)

i.e.,

$$\text{Res}_{q=0} \left[ \frac{1}{\sigma^2(q)} e^{2\xi_t[y,q]} e^{(y + \varepsilon(q))} D_x \tau'(x) \cdot \tau'(x) \right] = 0,$$  \hspace{1cm} (4.32)
which, by rearranging terms with respect to $y^\beta$, is written as

$$
\sum_{|\beta|=0}^{\infty} \text{Res}_{q=0} (B + D_x)^\beta \left( \sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j(\tilde{D}_x)\mu_{n-j} q^{n-2} \right) \tau'(x) \cdot \tau'(x) y^\beta = 0.
$$

(4.33)

Here,

$$
D_x = (D_{x_1}, D_{x_2}, D_{x_3}, \cdots), \quad \tilde{D}_x = (D_{x_1}, \frac{1}{2} D_{x_2}, \frac{1}{3} D_{x_3}, \cdots),
$$

$$
B = 2(-\xi(q), \xi'(q), \frac{e^{2\xi(q)}}{2!}, \cdots (-1)^n \frac{\xi((n-1)(q), \cdots),
$$

$$
\beta = (\beta_1, \beta_2, \beta_3, \cdots), \quad |\beta| = \sum_{j=1}^{\infty} \beta_j, \quad y^\beta = y_1^{\beta_1} y_2^{\beta_2} \cdots,
$$

\{p_j(x)\} are defined by (3.51) and \{\mu_j\} by (3.52). By a similar analysis as for the KdV case in Sect. 3.4, we can formulate an algorithm for calculating residues at $q = 0$, which gives rise to a bilinear KP hierarchy.

**Theorem 4.5** The bilinear KP hierarchy with elliptic solitons are given by

$$
\text{Res}_{q=0} (B + D_x)^\beta \left( \sum_{n=0}^{\infty} \sum_{j=0}^{n} p_j(\tilde{D}_x)\mu_{n-j} q^{n-2} \right) \tau'(x) \cdot \tau'(x) = 0, \quad (4.35)
$$

where $\beta$ stands for the set of nonnegative integers $(\beta_1, \beta_2, \cdots, \beta_n, 0, 0, \cdots)$, and $(B + D_x)^\beta|_{\leq 1}$ means those terms of $q^j$ with $j \leq 1$ in the Laurent series of $(B + D_x)^\beta$, $|\beta| = \sum_{j=1}^{n} j \beta_j$ and $p_j(t)$ are polynomials defined by (3.51).

Below are bilinear equations corresponding to $\beta = (3, 0, 0, 0, \cdots), (4, 0, 0, 0, \cdots), (5, 0, 0, 0, \cdots), (3, 1, 0, 0, \cdots)$ and $(2, 0, 1, 0, \cdots)$, respectively,

$$
(D_x^4 + 3D_{x_2}^2 - 4D_{x_1}D_{x_3} - g_2)\tau' \cdot \tau' = 0,
$$

(4.36a)

$$
(D_x^5D_{x_2} + 2D_{x_2}D_{x_3} - 3D_{x_1}D_{x_4})\tau' \cdot \tau' = 0,
$$

(4.36b)

$$
(D_x^6 + 4D_x^2D_{x_2} + 20D_{x_1}D_{x_3} + 40D_{x_2}D_{x_3} + 90D_{x_2}D_{x_4} - 216D_{x_1}D_{x_3} + 3g_2D_{x_1}^2 - 24g_3)\tau' \cdot \tau' = 0,
$$

(4.36c)

$$
(D_x^6 - 45D_x^2D_{x_2} - 20D_{x_3}D_{x_3} - 80D_{x_2}^2 + 144D_{x_1}D_{x_3} + 3g_2D_{x_1}^2 - 24g_3)\tau' \cdot \tau' = 0,
$$

(4.36d)

$$
(D_{x_1}^6 - 9D_{x_1}^2D_{x_2}^2 + 4D_{x_2}^3D_{x_3} - 32D_{x_2}^2 + 36D_{x_2}D_{x_4} + 3g_2D_{x_1}^2 - 24g_3)\tau' \cdot \tau' = 0.
$$

(4.36e)

When $g_2, g_3$ are 0, these bilinear equations degenerate to the usual soliton case, cf. Jimbo and Miwa (1983).

\( \Diamond \) Springer
5 Degenerations and Reductions

In the following we investigate deformations of $\tau$ functions and bilinear equations under the degenerations of periods and under the reductions of dispersion relations.

5.1 Degenerations by Periods

When the invariants $g_2$ and $g_3$ of the elliptic curve (A.2) take $g_2 = \frac{2}{3}(\pi \frac{w_1}{2})^4$, $g_3 = \frac{8}{27}(\pi \frac{w_1}{2})^6$ and $g_2 = g_3 = 0$, the elliptic curve degenerates to be a cylinder and Riemann sphere, respectively. These correspond to the degenerations from doubly periodic case to the singly period case and non-periodic case. The Weierstrass functions will become trigonometric/hyperbolic functions and rational functions, which we list in Proposition A.2 in Appendix A. Such deformations hold in $\tau$ functions and bilinear equations. In the following we present $\tau$ functions and bilinear equations of the trigonometric/hyperbolic case and rational case. It is worth mentioning that we will give explicit formulae for the trigonometric/hyperbolic case, which are more concise than those obtained by just formally replacing the Weierstrass functions using (A.15).

5.1.1 Trigonometric/Hyperbolic Case

One can directly replace those Weierstrass functions in the bilinear form (4.32) and $\tau$ function (4.22) using (A.15). As a result, for those explicit bilinear equations in (4.36), one needs to replace $g_2$ and $g_3$ by (A.14), and the $\tau$ function $\tau'$ is then given by

$$
\tau' = e^{\frac{1}{2}(\alpha x_1)^2} \sin(\alpha x_1) \tau_N(x),
$$

where $\tau_N(x)$ is defined as in (4.22) but in which the Weierstrass functions are replaced accordingly using (A.15).

Such a $\tau_N(x)$ for the trigonometric/hyperbolic case can have a more concise form. To achieve that, we introduce notation

$$
\xi_{[t]}(x, k) = \alpha \sum_{n=1}^{\infty} (-1)^n x_n \frac{\partial^{n-1} \cot(\alpha k)}{(n-1)!},
$$

(5.1)

where by the index $[t]$ we indicate the trigonometric/hyperbolic case. Then, similar to the formula (4.19), we can prove that

$$
\frac{\sin(\alpha(k_i - k_j))}{\sin(\alpha(k_i - l_j))} = e^{\xi_{[t]}(\epsilon(k_j) - \epsilon(l_j), k_i)}
$$

(5.2)

where $\epsilon(k) = (k, \frac{k^2}{2}, \frac{k^3}{3}, \cdots)$ defined as before. Next, we present a simple form of $\tau_N(x)$ and the related vertex operator.
Theorem 5.1 The bilinear hierarchy (4.35) with degeneration (A.14) have a solution

\[ \tau' = e^{\frac{1}{6}(\alpha x_1)^2} \sin(\alpha x_1) \tau_N(x), \quad (5.3) \]

where

\[ \tau_N(x) = \sum_{J \subset S} \left( \prod_{i \in J} c'_i \right) \left( \prod_{i < j \in J} A'_{ij} \right) \times \frac{\sin(\alpha(x_1 + \sum_{i \in J}(k_i - l_i)))}{\sin(\alpha x_1) \prod_{i \in J} \sin(\alpha(k_i - l_i))} e^{\sum_{i \in J}(\xi_{[i]}(x,k_i) - \xi_{[i]}(x,l_i))}. \quad (5.4) \]

Here, \( c'_i \in \mathbb{C} \) and

\[ A'_{ij} = \frac{\sin(\alpha(k_i - k_j)) \sin(\alpha(l_i - l_j))}{\sin(\alpha(k_i - l_j)) \sin(\alpha(l_i - k_j))}. \quad (5.5) \]

The related vertex operator is

\[ X(k, l) = \frac{\sin(\alpha(x_1 + k - l))}{\sin(\alpha x_1) \sin(\alpha(k - l))} e^{\xi_{[i]}(x,k) - \xi_{[i]}(x,l)} e^{\xi(\tilde{a}, k) - \xi(\tilde{a}, l)}. \quad (5.6) \]

The \( \tau \) function (5.4) is defined by the vertex operator via

\[ \tau_N(x) = c'_N X(k_N, l_N) \cdots c'_2 X(k_2, l_2) c'_1 X(k_1, l_1) \circ 1, \quad (5.7) \]

i.e.,

\[ \tau_N(x) = e^{c'_N X(k_N, l_N)} \circ \tau_{N-1}(x), \quad \tau_0(x) = 1. \quad (5.8) \]

Proof Let us look at the \( \tau_N(x) \) defined in (4.22) where \( t = x \). We will show that, with \( \sigma, \xi, \wp \) taking the form (A.15), the \( \tau_N(x) \) can be written as in (5.4). First, for a single PWF, we have

\[
\begin{align*}
 c'_i \frac{\sigma(x_1 + k_i - l_i)}{\sigma(x_1) \sigma(k_i - l_i)} e^{\xi_{[i]}(x,k_i) - \xi_{[i]}(x,l_i)} |_{(A.15)} \\
= c'_i \frac{\sin(\alpha(x_1 + k_i - l_i))}{\sin(\alpha x_1) \sin(\alpha(k_i - l_i))} e^{\xi_{[i]}(x,k_i) - \xi_{[i]}(x,l_i)} 
\end{align*}
\]

where we take

\[ c'_i = c_i e^{\frac{1}{6}\alpha_2^2(k_i - l_i)^2}. \quad (5.9) \]
Secondly, for the general term in \( \tau_N(x) \), we have

\[
\left( \prod_{i \in J} c_i \right) \frac{\sigma(x_1 + \sum_{i \in J} (k_i - l_i))}{\sigma(x_1)} \prod_{i \in J} \sigma(k_i - l_i) e^{\sum_{i \in J} (\xi_{i|j}(x,k_i) - \xi_{i|l}(x,l_i))} \bigg|_{(A.15)}
\]

\[
= \left( \prod_{i \in J} c_i \right) e^{\frac{1}{2}a^2(\sum_{i \in J} (k_i - l_i))^2} \frac{\sin(\alpha(x_1 + \sum_{i \in J} (k_i - l_i))}{\sin(\alpha x_1)} \prod_{i \in J} \sin(\alpha(k_i - l_i))
\]

\[
= \left( \prod_{i \in J} c_i \right) e^{\frac{1}{2}a^2(\sum_{i \in J} (k_i - l_i)(k_j - l_j))} \frac{\sin(\alpha(x_1 + \sum_{i \in J} (k_i - l_i))}{\sin(\alpha x_1)} \prod_{i \in J} \sin(\alpha(k_i - l_i)).
\]

Thirdly, for the phase factor \( A_{ij} \), we have

\[
A_{ij}|_{(A.15)} = \frac{\sigma(k_i - k_j)\sigma(l_i - l_j)}{\sigma(k_i - l_j)\sigma(l_i - k_j)}
\]

\[
eq e^{\frac{1}{2}a^2(\sum_{i \in J} (k_i - l_i)(k_j - l_j))} A'_{ij}.
\]

All these together lead us to the form (5.4) for the \( \tau \) function (4.22) with (A.15).

For the vertex operator (5.6), using relation (5.2), one can find that

\[
X(k_i, l_i)X(k_j, l_j) = A'_{i, j} \frac{\sin(\alpha(x_1 + k_i - l_i + k_j - l_j))}{\sin(\alpha(x_1))} \frac{\sin(\alpha(k_i - l_j))}{\sin(\alpha(k_j - l_j))} X(k_i, l_i)X(k_j, l_j),
\]

where

\[
: X(k_i, l_i)X(k_j, l_j) : = e^{\xi_{i|l}(x,k_i) - \xi_{i|l}(x,l_i)} e^{\xi_{i|j}(x,k_j) - \xi_{i|j}(x,l_j)} e^{\xi(\tilde{\alpha},k_i) - \xi(\tilde{\alpha},l_i)} e^{\xi(\tilde{\alpha},k_j) - \xi(\tilde{\alpha},l_j)}.
\]

Then, Eq. (5.7) follows immediately.

Compared with Theorem 4.3, it turns out that Theorem 5.1 can be obtained from Theorem 4.3 by formally replacing \( \sigma(x) \) and \( \zeta(x) \) with \( \sin(\alpha x) \) and \( \alpha \cot(\alpha x) \). This also agrees with the fully discrete case, cf. Yoo-Kong and Nijhoff (2013). The trigonometric/hyperbolic PWF of the KP hierarchy is (cf. Eq. (4.25))

\[
\rho = X(k, l) \circ 1 = \frac{\sin(\alpha(x_1 + k - l))}{\sin(\alpha(x_1))} \frac{\sin(\alpha(k - l))}{\sin(\alpha(k - l))} e^{\xi_{i|l}(x,k) - \xi_{i|l}(x,l)}.
\]

5.1.2 Rational Case

The \( \tau \) function and vertex operator of rational case are obtained from Theorem 4.3 by direct substitution of (A.16). Bilinear equations are those of doubly periodic case with degeneration \( g_2 = g_3 = 0 \), which are the same as the bilinear equations for usual solitons. We skip proof and only present main results in the following.

**Theorem 5.2** In the rational case the bilinear KP hierarchy are the same as the usual soliton case, namely, the bilinear equations derived from (4.33) with \( g_2 = g_3 = 0 \); \( \tau \) function is given by

\[
\tau' = x_1 \tau_N(x),
\]

\[
\square 
\]
where
\[
\tau_N(x) = \sum_{J \subseteq S} \left( \prod_{i \in J} c_i \right) \left( \prod_{i < j \in J} A_{ij} \right) x_1 + \sum_{i \in J} (k_i - l_i) e^{\sum_{i \in J} (\xi_{[r]}(x, k_i) - \xi_{[r]}(x, l_i))}. \tag{5.12a}
\]

Here,
\[
A_{ij} = \frac{(k_i - k_j)(l_i - l_j)}{(k_i - l_j)(l_i - k_j)}, \tag{5.12b}
\]
\[
\xi_{[r]}(x, k) = -\sum_{n=1}^{\infty} \frac{1}{kn} x_n, \tag{5.12c}
\]
and the subscript \([r]\) stands for the rational case.

The related vertex operator is
\[
X(k, l) = x_1 + k - l \frac{e^{\xi_{[r]}(x, k) - \xi_{[r]}(x, l)}}{(k - l)x_1} e^{\xi(t, k) - \xi(t, l)}, \tag{5.13}
\]
and the \(\tau\) function (5.12a) is generated via
\[
\tau_N(x) = e^{c_1 x(k_N, l_N)} \cdots e^{c_2 X(k_2, l_2)} e^{c_1 X(k_1, l_1)} \circ 1. \tag{5.14}
\]

Note that the rational-type PWF of the KP hierarchy is (cf. Eqs. (4.25) and (5.10))
\[
\rho = X(k, l) \circ 1 = \frac{x_1 + k - l}{(k - l)x_1} e^{\xi_{[r]}(x, k) - \xi_{[r]}(x, l)}. \tag{5.15}
\]

### 5.2 Reductions by Dispersion Relations

#### 5.2.1 Elliptic Case

For the KP hierarchy, the vertex operator of its usual soliton solution is
\[
X(k, l) = e^{\xi(t, k) - \xi(t, l)} e^{\xi(\tilde{a}, k) - \xi(\tilde{a}, l)}, \tag{5.16}
\]
which is governed by \(\xi(t, k)\). Reduction by dispersion relation can be implemented through imposing constraints on \(l\) such that \(l^N = k_N\), i.e., \(l = \omega k\) where \(\omega\) is some \(N\)-th root of unity and in practice we require \(\omega^s \neq 1\) for \(s = 1, 2, \ldots, N - 1\). The bilinear KP hierarchy together with its \(\tau\) function will reduce to the lower dimension for the Gel’fand–Dickey hierarchy, including the KdV for \(N = 2\), the Boussinesq for \(N = 3\), etc. To implement reduction of elliptic solitons by dispersion relation, one needs to make use of elliptic \(N\)-th roots of the unity, which is introduced in Nijhoff et al. (2019) (also see Definition A.1 in Appendix).
For the case of elliptic solitons, the vertex operator (4.18) is governed by \( \xi_{[e]}(t, k) \) and \( \xi(\tilde{\partial}, k) \) together. If we implement a reduction starting from the vertex operator, we need to consider \( \xi_{[e]}(t, k) \) and \( \xi(\tilde{\partial}, k) \) simultaneously. In this case, the vertex operator, \( \tau \) function and bilinear equations of the KP hierarchy are reduced to those of the KdV hierarchy by taking \( l_j = -k_j \). This is because when \( l = -k \) the coordinate variables \( t_{2n} \) in \( \xi_{[e]}(t, k) - \xi_{[e]}(t, l) \) and \( \partial_{t_{2n}} \) in \( \xi(\tilde{\partial}, k) - \xi(\tilde{\partial}, l) \) in the vertex operator (4.18) vanish. However, for the Boussinesq case, using the elliptic cube roots of the unity (see Definition A.1), one cannot eliminate \( \xi(\tilde{\partial}, k) - \xi(\tilde{\partial}, l) \) at the same time, unless taking \( l_j = \omega_0(k_j) \equiv k_j \). This means the vertex operator (4.18) is not applicable to the reduction for the Boussinesq equation. More than that, recalling Remark A.1 we give at the end of Appendix A, except \( \omega_0(\delta) \equiv \delta \), the other two elliptic cube roots of the unity are not the elliptic 6-th roots of the unity. This means, in principle, when \( N \geq 3 \) we cannot get elliptic multi-soliton solution for the Gel’fand–Dickey hierarchy from those of the KP hierarchy by using elliptic \( N \)-th roots of the unity.

If only for the Boussinesq equation (not the hierarchy), its \( \tau \) function and bilinear equation can be obtained from those of the KP equation (i.e., (4.14), (4.15) and (4.16)) as reduction using elliptic cube roots of the unity. We present them below. Let \( \omega_0(\delta) \equiv \delta \), \( \omega_1(\delta) \) and \( \omega_2(\delta) \) be three elliptic cube roots of the unity, then

\[
f = \sum_{\mu = 0, 1} \frac{\sigma(x + \sum_{i=1}^{N} \mu_i(k_i - \omega_1(k_i)))}{\sigma(x) \prod_{i=1}^{N} \sigma^{\mu_i}(k_i - \omega_1(k_i))} \exp \left( \sum_{j=1}^{N} \mu_j \hat{\theta}_j + \sum_{1 \leq i < j} \mu_i \mu_j a_{ij} \right) \tag{5.17}
\]

is a solution of the bilinear Boussinesq equation

\[
(D_x^4 - 12 \varphi(x) D_x^2 + 3 \varphi^2) f \cdot f = 0, \tag{5.18}
\]

where the summation of \( \mu \) means to take all possible \( \mu_i \in \{0, 1\} \) for \( i = 1, 2, \ldots, N \),

\[
\hat{\theta}_i = - (\xi(k_i) - \xi(\omega_1(k_i))) x - (\varphi(k_i) - \varphi(\omega_1(k_i))) y + \hat{\theta}_i^{(0)}, \quad \hat{\theta}_i^{(0)} \in \mathbb{C}, \tag{5.19a}
\]

\[
e^{a_{ij}} = A_{ij} = \frac{\sigma(k_i - k_j) \sigma(\omega_1(k_i) - \omega_1(k_j))}{\sigma(k_i - \omega_1(k_j)) \sigma(\omega_1(k_i) - k_j)}. \tag{5.19b}
\]

Note that it is easy to write out a vertex operator corresponding to the \( \tau \) function (5.17). We skip it.

### 5.2.2 Trigonometric/Hyperbolic Case

Similar to the elliptic case, to consider reduction, we need to introduce trigonometric/hyperbolic \( N \)-th roots of the unity. This can be done by considering period degeneration in Definition A.1. After suitable scaling of independent variables, we have the following.
Definition 5.1 There exist distinct \( \{ \omega_j(\delta) \}_{j=0}^{N-1} \), up to the periods \( k\pi \), such that the following equation holds,

\[
\prod_{j=0}^{N-1} \Psi_k(\omega_j(\delta)) = \frac{1}{(N-1)!} (\partial_k^{N-2} \csc^2(-\kappa) - \partial_k^{N-2} \csc^2(\delta)),
\]

(5.20)

where

\[
\Psi_a(b) = \frac{\sin(a + b)}{\sin(a) \sin(b)},
\]

(5.21)

\( \omega_0(\delta) = \delta \) and all \( \{ \omega_j(\delta) \} \) are independent of \( \kappa \). \( \{ \omega_j(\delta) \}_{j=0}^{N-1} \) are called trigonometric/hyperbolic \( N \)-th roots of the unity.

These roots also satisfy

\[
\sum_{j=0}^{N-1} \omega_j(\delta) = 0
\]

(5.22)

and

\[
\sum_{j=0}^{N-1} \cot^{(l)}(\omega_j(\delta)) = 0, \quad (l = 0, 1, \ldots, N - 2).
\]

(5.23)

When \( N = 2 \), i.e., reduction to the KdV, we take \( l_j = -k_j \) in the KP \( \tau \) function (5.4), and we have the trigonometric/hyperbolic \( \tau \) function of the KdV hierarchy:

\[
\tau_N(x) = \sum_{J \subseteq S} \left( \prod_{i \in J} c_i' \right) \left( \prod_{i < j \in J} A'_{ij} \right) \frac{\sin(\alpha(x_1 + 2\sum_{i \in J} k_i))}{\sin(\alpha x_1) \prod_{i \in J} \sin(2\alpha k)} \ e^{2\sum_{i \in J} \xi_{i[1]}(x,k)} e^{2\xi_{\tilde{\xi},k}},
\]

(5.24)

where

\[
A'_{ij} = \frac{\sin^2(\alpha(k_i - k_j))}{\sin^2(\alpha(k_i + k_j))},
\]

(5.25)

and by \( x \) we denote \( (x_1, 0, x_3, 0, x_5, \ldots) \) for the sake of using the results of the KP hierarchy in Sect. 5.1.1. The above \( \tau \) function is generated by vertex operator

\[
X(k) = \frac{\sin(\alpha(x_1 + 2k))}{\sin(\alpha(x_1)) \sin(2\alpha k)} e^{2\xi_{[1]}(x,k)} e^{2\tilde{\xi}_{\tilde{\xi},k}},
\]

(5.26)
where \( \tilde{\partial} = (\partial_{x_1}, 0, \frac{1}{3}\partial_{x_3}, 0, \frac{1}{5}\partial_{x_5}, \cdots) \). Bilinear equations are those derived from (4.33) by removing all \( D_{x_{2n}} \) terms and imposing \( g_2 = \frac{4}{3} \alpha^4, \ g_3 = \frac{8}{27} \alpha^6 \). These equations have solution

\[
\tau' = e^{\frac{1}{6}(\alpha x_1)^2} \sin(\alpha x_1) \tau_N(x),
\]

(5.27)

where \( \tau_N(x) \) is given by (5.24).

Same as the elliptic case, when \( N \geq 3 \) we cannot get \( \tau \) function and bilinear equations of the Gel’fand–Dickey hierarchy from those of the KP hierarchy by reduction using trigonometric/hyperbolic \( N \)-th roots of the unity. For the Boussinesq equation (not hierarchy), it allows a \( \tau \) function

\[
f = \sum_{\mu=0,1} \frac{\sin(\alpha(x_1 + \mu_i(k_i - \omega_1(k_i))))}{\sin(\alpha x_1) \prod_{i=1}^{N} \sin^{\mu_i}(\alpha(k_i - \omega_1(k_i)))} \exp \left( \sum_{j=1}^{N} \mu_j \hat{\theta}_j + \sum_{1 \leq i < j} \mu_i \mu_j a_{ij} \right),
\]

(5.28)

where the summation of \( \mu \) means to take all possible \( \mu_i = \{0, 1\} \) for \( i = 1, 2, \cdots, N \),

\[
\hat{\theta}_i = -\alpha(\cot(\alpha k_i) - \cot(\alpha \omega_1(k_i)))x - \alpha^2(\csc^2(\alpha k_i)
\]

\[
- \csc^2(\alpha \omega_1(k_i))y + \hat{\theta}_i^{(0)}, \ \hat{\theta}_i^{(0)} \in \mathbb{C},
\]

(5.29a)

\[
e^{a_{ij}} = A_{ij} = \frac{\sin(\alpha(k_i - k_j)) \sin(\alpha(\omega_1(k_i) - \omega_1(k_j)))}{\sin(\alpha(k_i - \omega_1(k_j))) \sin(\alpha(\omega_1(k_i) - k_j))},
\]

(5.29b)

\( \alpha \omega_1(k) \) is one of trigonometric/hyperbolic cube root of the unity by Definition 5.1, i.e.,

\[
\partial_\kappa \csc^2(\kappa)|_{\kappa = \alpha k} = \partial_\kappa \csc^2(\kappa)|_{\kappa = \alpha \omega_1(k)}.
\]

Such a \( \tau \) function is a solution to the bilinear Boussinesq equation

\[
(D_x^4 + 4\alpha^2 D_x^2 - 12\alpha^2 \csc^2(\alpha x) D_x^2 + 3D_y^2)\cdot f = 0.
\]

(5.30)

Note that it is easy to write out a vertex operator for the \( \tau \) function (5.29). We skip it.

### 5.2.3 Rational Case

Reduction of this case is as same as the usual soliton case. For example, reductions \( l_j = -k_j \) and \( l_j = \omega k_j \) where \( \omega^3 = 1, \ \omega \neq 1 \) reduce the results in Sect. 5.1.2 of the KP hierarchy to the KdV hierarchy and the Boussinesq hierarchy, respectively. Note that for the KdV equation its solution of this case has been obtained via the Marchenko integral equation in Ablowitz and Cornille (1979) and a direct linearization approach in Fokas and Ablowitz (1982), and now it is clear how these solutions originate from the elliptic soliton solutions.
6 Conclusions and Discussion

We have established a bilinear framework for the elliptic soliton solutions that are composed by the Lamé-type PWFs. Employing the KdV equation and KP equation as examples, we presented \( \tau \) functions for these elliptic \( N \)-soliton solutions in Hirota’s form, and the corresponding vertex operators and bilinear identities. An algorithm has been developed to calculate residues and obtain bilinear equations. Such a framework allows degenerations to the trigonometric/hyperbolic and rational cases when the invariants \( g_2 \) and \( g_3 \) are specified for one period and non-period. Reductions by dispersion relations can be implemented using elliptic \( N \)-th roots of the unity, but except the KdV hierarchy, the reductions of elliptic and trigonometric/hyperbolic soliton solutions are not applicable to the Boussinesq hierarchy and other higher-order Gel’fand–Dickey hierarchies.

We would like to address some related topics for further consideration. First, are there any algebras to characterize this type of vertex operators? In other words, are these vertex operators the representations of some algebras? Date, Date et al. (1981) found that the vertex operator related to affine Lie algebra \( \mathfrak{A}_1^{(1)} \) Lepowsky and Wilson (1978) can be used to define a symmetry group of the KdV \( \tau \) function. This then built up a beautiful connection between integrable systems and affine Lie algebras via vertex operators (Date et al. 1981, 1982; Jimbo and Miwa 1983; Miwa et al. 1999). However, so far we did not find any similar algebraic structures behind our vertex operators (excluding the rational case). The vertex operators (3.32) and (4.18) can be considered as elliptic deformations of the usual vertex operators of the KdV equation and KP equation. Without algebraic structure, one can still investigate such deformations on vertex operators of other integrable systems (e.g., Date et al. 1982; Jimbo and Miwa 1983), and in particular, of discrete integrable systems (e.g., (Date et al. 1982a, b, 1983a, b, c)). In addition, note that \( u = -2 \wp(x) \) is an initial solution in our scheme, and meanwhile it is the 1-gap and 1-genus solution in light of the finite-gap integration approach Dubrovin (1975); Dubrovin and Novikov (1975). It would be interesting to make clear the eigenvalue distribution of the corresponding spectral problem where the potential is elliptic multi-solitons, and recover these elliptic soliton solutions form some analytic approach, e.g., the inverse scattering transform. Finally, there are vertex representations for quantum affine algebras Frenkel and Jing (1988). It would be also interesting if such elliptic deformations could be extended to quantum vertex operators.

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A Weierstrass Functions

We collect some notations and properties of the Weierstrass functions that we may use in the paper. One may refer to Akhiezer (1990), Hietarinta et al. (2016) and Nijhoff et al. (2019).

Three Weierstrass functions $\zeta(z)$, $\wp(z)$ and $\sigma(z)$ are connected via

$$\zeta(z) = \frac{\sigma'(z)}{\sigma(z)}, \quad \wp(z) = -\zeta'(z).$$

Among them only $\wp(z)$ is a truly elliptic function by the definition of an elliptic function, i.e., meromorphic and doubly periodic. By $w_1$ and $w_2$, we denote two half periods of $\wp(z)$. $\zeta(z)$ and $\sigma(z)$ are quasi-periodic with respect to $w_i$, in the sense that

$$\zeta(z + 2w_i) = \zeta(z) + 2\zeta(w_i), \quad \sigma(z + 2w_i) = -\sigma(z)e^{2\zeta(w_i)(z + w_i)}, \quad i = 1, 2. \quad (A.1a)$$

It is easy to check the following holds.

**Proposition A.1** For a generalized Lamé function $\sigma^{(a+q)}e^{c\zeta(q)}$ where $a$, $b$, $c$ are constants, it is doubly periodic with respect to $q$ if $a - b + c = 0$.

Let $e_i = \wp(w_i)$ for $i = 1, 2, 3$ where $w_3 = -w_1 - w_2$. $(\wp(z), \wp'(z))$ is a point on the Weierstrass elliptic curve

$$y^2 = R(x) = 4x^3 - g_2x - g_3 = 4(x - e_1)(x - e_2)(x - e_3), \quad (A.2)$$

i.e.,

$$(\wp'(z))^2 = 4\wp^3(z) - g_2\wp(z) - g_3, \quad (A.3)$$

where $g_2 = -4(e_1e_2 + e_2e_3 + e_3e_1)$ and $g_3 = 4e_1e_2e_3$ are invariants of the curve. Differentiating (A.3) yields

$$2\wp''(z) = 12\wp^2(z) - g_2 \quad (A.4)$$

and further

$$\wp^{(3)}(z) = 12\wp(z)\wp'(z). \quad (A.5)$$

The latter is the stationary KdV equation, in other words, $u = -2\wp(x)$ is a stationary solution to the KdV equation (2.1).
\( \wp(z) \) is an even function, while \( \zeta(z) \) and \( \sigma(z) \) are odd. \( \sigma(z) \) is an entire function.

As for expansions, they have

\[
\wp(z) = \frac{1}{z^2} + \frac{g_2}{20} z^2 + \frac{g_3}{28} z^4 + O(z^6),
\]

(A.6a)

\[
\zeta(z) = \frac{1}{z} - \frac{g_2}{60} z^3 - \frac{g_3}{140} z^5 + O(z^7),
\]

(A.6b)

\[
\sigma(z) = z - \frac{g_2}{240} z^5 - \frac{g_3}{840} z^7 + O(z^9).
\]

(A.6c)

Some useful identities of the Weierstrass functions are given below.

\[
\wp(z) - \wp(u) = -\sigma(z+u)\sigma(z-u),
\]

(A.7)

\[
\eta_u(z) = \zeta(z+u) - \zeta(z) - \zeta(u) = \frac{1}{2} \frac{\wp'(z) - \wp'(u)}{\wp(z) - \wp(u)},
\]

(A.8)

\[
\wp(z) + \wp(u) + \wp(z+u) = \eta_u^2(z)
\]

(A.9)

and

\[
\chi_{u,v}(z) = \zeta(u) + \zeta(v) + \zeta(z) - \zeta(u+v+z) = \frac{\sigma(u+v)\sigma(u+z)\sigma(z+v)}{\sigma(u)\sigma(v)\sigma(z)\sigma(z+u+v)}.
\]

(A.10)

The famous Frobenius–Stickelberger determinant (also known as elliptic van der Monde determinant) is Frobenius and Stickelberger (1880)

\[
\begin{vmatrix}
1, \wp(k), \wp'(k), \wp''(k), \cdots, \wp^{(n-2)}(k)
\end{vmatrix}
= (-1)^{\frac{(n-1)(n-2)}{2}} \left( \prod_{s=1}^{n-1} s! \right) \frac{\sigma(k_1 + \cdots + k_n) \prod_{i<j} \sigma(k_i - k_j)}{\sigma^2(k_1) \sigma^2(k_2) \cdots \sigma^2(k_n)},
\]

(A.11)

where \( f(k) \) denotes a column vector with entries \( f(k_j), i.e., f(k) = (f(k_1), f(k_2), \cdots, f(k_n))^T \). One more formula is (see (C.7) in Nijhoff and Delice (2018))

\[
\prod_{j=1}^n \Phi_x(k_j) = \frac{(-1)^{n-1}}{(n-1)!} \Phi_x(k_1 + \cdots + k_n)
\]

\[
\times \begin{vmatrix}
1, \wp(k), \wp'(k), \wp''(k), \cdots, \wp^{(n-2)}(k)
\end{vmatrix}
\]

(A.12)

where \( \Phi_a(b) = \frac{\sigma(a+b)}{\sigma(a)\sigma(b)} \).

Degenerations of the Weierstrass functions take place when the discriminant is zero, i.e.,

\[
\Delta = g_2^3 - 27g_3^2 = 0.
\]

(A.13)
The degenerations are described as the following Akhiezer (1990).

**Proposition A.2** With parametrization

\[
g_2 = \frac{4}{3} \alpha^4, \quad g_3 = \frac{8}{27} \alpha^6, \quad \alpha = \frac{\pi}{2w},
\]

the Weierstrass functions degenerate to the trigonometric/hyperbolic case,

\[
\begin{align*}
\sigma(q) &= \frac{1}{\alpha} e^{\frac{1}{6}(\alpha q)^2} \sin(\alpha q), \\
\zeta(q) &= \frac{1}{3} \alpha^2 q + \alpha \cot(\alpha q), \\
\wp(q) &= -\frac{1}{3} \alpha^2 + \alpha^2 \csc^2(\alpha q).
\end{align*}
\]

And when \( g_2 = g_3 = 0 \), the Weierstrass functions degenerate to the rational case,

\[
\begin{align*}
\sigma(q) &= q, \\
\zeta(q) &= \frac{1}{q}, \\
\wp(q) &= \frac{1}{q^2}.
\end{align*}
\]

In what follows, we present the definition of elliptic \( N \)-th roots of the unity that was introduced in Nijhoff et al. (2019).

**Definition A.1** (Nijhoff et al. 2019) There exist distinct \( \{\omega_j(\delta)\}_{j=0}^{N-1} \), up to the periodicity of the periodic lattice, such that the following equation holds,

\[
\prod_{j=0}^{N-1} \Phi_\kappa(\omega_j(\delta)) = \frac{1}{(N-1)!} (\wp^{(N-2)}(-\kappa) - \wp^{(N-2)}(\delta)),
\]

where \( \omega_0(\delta) = \delta \) and all \( \{\omega_j(\delta)\} \) are independent of \( \kappa \). \( \{\omega_j(\delta)\}_{j=0}^{N-1} \) are called elliptic \( N \)-th roots of the unity.

These roots also satisfy Nijhoff et al. (2019)

\[
\sum_{j=0}^{N-1} \omega_j(\delta) = 0
\]

and

\[
\sum_{j=0}^{N-1} \zeta^{(l)}(\omega_j(\delta)) = 0, \quad (l = 0, 1, \cdots, N - 2).
\]

\(^4\) We do not discriminate between trigonometric and hyperbolic cases, as \( \alpha \) (or the period \( 2w \)) can be either real or pure imaginary, corresponding to the two cases (\( g_3 \) being positive or negative) to define the period through elliptic integrals (Akhiezer 1990).
Remark A.1 In usual case if $\omega$ is a $n$-th root of the unity, it is also a $(kn)$-th root of the unity where $k \in \mathbb{N}$. This is not true in the elliptic case. Note that the elliptic square roots of the unity are also the elliptic 2$^k$-th roots of the unity because $\wp(2nx)(x)$ is even. However, for the elliptic cube root of the unity, $\omega_1(\delta) \neq \delta$, it is not an elliptic 6-th root of the unity. Note that the elliptic square roots of the unity are also the elliptic 2$^k$-th roots of the unity because $\wp(2nx)(x)$ is even. However, for the elliptic cube root of the unity, $\omega_1(\delta) \neq \delta$, it is not an elliptic 6-th root of the unity. In other words, $\wp'(\omega_1(\delta)) = \wp'(\delta)$ holds does not guarantee that the validity of $\wp'(\omega_1(\delta)) = \wp'(\delta)$, where $\omega_1(\delta) \neq \delta$ (mod the periodic lattice). In fact, using the formulae (A.3), (A.4) and (A.5), we have

$$\wp'(\omega_1(\delta)) = \wp'(\delta),$$

In the case $\wp'(\omega_1(\delta)) = \wp'(\delta)$, it reduces to

$$\wp'(\omega_1(\delta)) = \wp'(\delta),$$

which does not vanish for arbitrary $\delta$ unless $g_2 = 0$ or $\omega_1(\delta) = \delta$.

B Elliptic 1- and 2-Soliton Solutions and Bilinear Formulae

The purpose of this section is not only to show details of deriving elliptic 1-soliton and 2-soliton solutions of the KdV equation, but also to explore some calculating formulae of the Lamé-type PWFs (cf. $e^{kx+it}$) under Hirota’s $D$ operator.

The Lamé-type PWF defined in (3.8), i.e.,

$$\rho_i(x,t) = \Phi_k(2k_i)e^{\xi_i}, \quad \xi_i = -2\zeta(k_i)x + \wp(k_i)t + \xi_i^{(0)},$$

satisfies the following relations

$$\rho_{i,x} = -\chi_{k_i,k_i}(x)\rho_i,$$  \hspace{1cm} (B.2a)

$$\rho_{i,xx} = 2\eta(k_i)\rho_{i,x},$$  \hspace{1cm} (B.2b)

$$\rho_{i,xxx} = (6\wp(x) + 2\wp(x + k_i) + 4\wp(k_i))\rho_{i,x},$$  \hspace{1cm} (B.2c)

where $\eta_x(y)$ and $\chi_{x,y}(z)$ are defined in (2.13) and (2.16). There are equivalent expressions for these derivatives. For example, noticing that

$$\chi_{k,k}(x) = \eta_{-k}(x + k) - \eta_k(x + k)$$

and making use of (A.8), we have

$$\rho_{i,x} = \frac{-\wp'(k_i)}{\wp(x + k_i) - \wp(k_i)}\rho_i.$$  \hspace{1cm} (B.3)

Using this formula to replace $\wp'(k_i)\rho_{i,x}$ in (B.2c) yields

$$\rho_{i,xxx} = 6(\wp(x + k_i) + \wp(x))\rho_{i,x} + 4\wp'(k_i)\rho_i,$$  \hspace{1cm} (B.4)
which gives another expression of $\rho_{i,xxx}$. To calculate $\rho_{i,xxxx}$, differentiating (B.4) once with respect to $x$ yields

$$\rho_{i,xxxx} = 6(\varphi'(x + k_i) - \varphi'(-x))\rho_{i,x} + 6(\varphi(x + k_i) + \varphi(x))\rho_{i,xx} + 4\varphi'(k_i)\rho_{i,x},$$

which then, by making use of (A.8) and (B.2b), gives rise to a simpler form for $\rho_{i,xxxx}$,

$$\rho_{i,xxxx} = 12\varphi(x)\rho_{i,xx} + 4\varphi'(k_i)\rho_{i,x}. \quad (B.5)$$

Hirota’s procedure for deriving usual solitons relies on the property

$$D_n^x D_m^t e^{ax+bt} \cdot e^{ax+bt} = 0, \quad a, b \in \mathbb{C},$$

but this does not hold any longer for the Lamé-type PWF $\rho_i$. For example, one can verify that

$$D_x D_t \rho_i \cdot \rho_i = 0 \quad (B.6)$$

but

$$D_x^2 \rho_i \cdot \rho_i = 2(\varphi(x) - \varphi(x + 2k_i))\rho_i^2, \quad (B.7)$$

which is not zero. In addition, using the expressions (B.2b), (B.3), (B.4), (B.5) and formula (A.9), we have

$$D_x^4 \rho_i \cdot \rho_i = 12\varphi(x)D_x^2 \rho_i \cdot \rho_i, \quad (B.8)$$

which does not vanish either. There could be a more general result. We have checked the following formula,

$$D_x^{2n} \varphi \cdot \varphi = \frac{\varphi^{(2n-1)}(x)}{\varphi'(x)}D_x^2 \varphi \cdot \varphi, \quad \varphi = \Phi_x(a)e^{bx+ct}, \quad a, b, c \in \mathbb{C}, \quad (B.9)$$

up to $n = 10$ using Mathematica. The “coefficient” $\frac{\varphi^{(2n-1)}(x)}{\varphi'(x)}$ is a linear combination of $\{\varphi^s(x)\}$ with $s = n - 1, n - 3, n - 4, \ldots, 1, 0$. In checking the above relation we made use of the following formula (see Eq.(1.188) in Hirota (2004))

$$2 \cosh(\delta \partial_x) \ln \varphi = \ln(\cosh(\delta D_x)\varphi \cdot \varphi)$$

and $(\ln \varphi)_{xx} = \varphi(x) - \varphi(x + a)$. However, a proof for arbitrary $n$ is absent. Note that Hirota’s $D$ operator allows gauge property with respect to linear exponential function, i.e.,

$$D_x^n D_t^m (e^{ax+bt} f) \cdot (e^{ax+bt} g) = e^{2(ax+bt)} D_x^n D_t^m f \cdot g,$$
but the formula (B.9) indicates that such a property no longer holds when the linear exponential function is replaced by the Lamé function. Instead of that, we have the following.

**Proposition B.1** *(Quasi-gauge property)* For the generalized Lamé-type PWF \( \varrho \) defined in (B.9) and \( C^\infty \) functions \( f(x, t) \) and \( g(x, t) \), we have

\[
D^n_x D^m_t (\varrho f) \cdot (\varrho g) = \varrho^2 D^n_x D^m_t f \cdot g + \sum_{l=1}^{[\frac{n}{2}]} \left( \frac{n}{2l} \right) (D^l_x \varrho \cdot \varrho) D^{n-2l}_x D^m_t f \cdot g.
\]

(B.10)

In light of (B.9), the term \( D^l_x \varrho \cdot \varrho \) can be replaced by \( \frac{\varrho^{(2l-1)}(x)}{\varrho'(x)} D^2_x \varrho \cdot \rho \) or \( 2(\varrho(x)-\varrho(x+a))\varrho^{(2l-1)}(x) \varrho'^2 \).

**Proof** The proof is direct by using the identity (Hirota 2004)

\[
\exp(D_1) (f \cdot h) = (\exp(D_1) h \cdot k) (\exp(D_1) f \cdot g),
\]

(B.11)

where \( f, g, h, k \) are functions of \( (x, t) \) and \( D_1 = \varepsilon D_x + \delta D_t \) with constants \( \varepsilon \) and \( \delta \).

We now look for elliptic soliton solutions in Hirota’s form. For elliptic 1-soliton solution with the form \( f_1 = 1 + \rho_1(x, t) \), thanks to (B.6) and (B.8), one only needs to verify

\[
(D_x^4 - 4D_x D_t - 12\varrho(x)D_x^2) \rho_1 = 0,
\]

(B.12)

which is nothing but (B.5) in light of

\[
\rho_{i,t} = \varrho'(k_i) \rho_i.
\]

(B.13)

Thus, the elliptic 1-soliton (3.6) is obtained.

Then, we look for 2-soliton solution of the form

\[
f_2 = 1 + \rho_1(x, t) + \rho_2(x, t) + f^{(2)}(x, t),
\]

(B.14)

subject to

\[
(D_x^4 - 4D_x D_t - 12\varrho(x)D_x^2) f_2 \cdot f_2 = 0,
\]

(B.15)

where

\[
f^{(2)}(x, t) = A_{12} e^{4k_1(k_2)k_2} \rho_1 \rho_2, \quad \rho_1(x, t) = \rho_1(x + 2k_2, t),
\]

(B.16)
and $A_{12}$ is a parameter to be fixed later. In light of relations (B.6) and (B.8), Eq. (B.15) is reduced to two equations,

$$ (D_x^4 - 4D_t D_x - 12\varphi(x) D_x^2) \rho_1 \cdot \rho_2 = -(\partial_x^4 - 4\partial_{xt} - 12\varphi(x)\partial_x^2) f^{(2)} \quad (B.17) $$

and

$$ (D_x^4 - 4D_t D_x - 12\varphi(x) D_x^2) \rho_i \cdot f^{(2)} = 0, \quad i = 1, 2. \quad (B.18) $$

Let us first work on (B.17). By virtue of the fact (B.12) which holds for $\rho_2$ as well, we have

$$ (D_x^4 - 4D_t D_x - 12\varphi(x) D_x^2) \rho_1 \cdot \rho_2 \\
= 4\rho_{1,x} \rho_{2,t} + 4\rho_{1,t} \rho_{2,x} - 4\rho_{1,xxx} \rho_{2,x} - 4\rho_{1,x} \rho_{2,xxx} \\
+ 6\rho_{1,x} \rho_{2,xx} + 24\varphi(x) \rho_{1,x} \rho_{2,x}. \quad (B.19) $$

Making use of (B.13), (B.2b) and (B.2c), we can express $\rho_{1,x}$, $\rho_{1,xxx}$ and $\rho_{1,xxx}$ in terms of $\rho_{1,x}$. After that, using formula (A.9), we arrive at

$$ (D_x^4 - 4D_t D_x - 12\varphi(x) D_x^2) \rho_1 \cdot \rho_2 = -12(\eta_1(x) - \eta_2(x))^2 \rho_{1,x} \rho_{2,x} \\
= -12\chi_{-k_1,k_2}(x + k_1) \rho_{1,x} \rho_{2,x}, \quad (B.20) $$

where use has been made of $\chi_{-k_1,k_2}(x + k_1) = \eta_1(x) - \eta_2(x)$.

For the right hand side of (B.17), by virtue of (B.12), we have

$$ - (\partial_x^4 - 4\partial_{xt} - 12\varphi(x)\partial_x^2) f^{(2)} \\
= -A_{12} e^{4\zeta(k_1)k_2} \left[ -4\tilde{\rho}_{1,x} \rho_{2,t} - 4\tilde{\rho}_{1,t} \rho_{2,x} + 4\tilde{\rho}_{1,xxx} \rho_{2,x} + 4\tilde{\rho}_{1,x} \rho_{2,xxx} \\
+ 6\tilde{\rho}_{1,x} \rho_{2,xx} + 12(\varphi(x + k_2) - \varphi(x)) \tilde{\rho}_{1,xxx} \rho_{2} - 24\varphi(x) \tilde{\rho}_{1,x} \rho_{2,x} \right], $$

in which

$$ 12(\varphi(x + k_2) - \varphi(x)) \tilde{\rho}_{1,xxx} \rho_{2} = 24(\eta_{k_2}(x + k_2) - \eta_{k_2}(x)) \eta_1(x + k_2) \tilde{\rho}_{1,x} \rho_{2,x}, $$

where use has been made of (A.9), (B.2a) and (B.2b). Then, similar to the treatment for (B.19), we have

$$ -(\partial_x^4 - 4\partial_{xt} - 12\varphi(x)\partial_x^2) f^{(2)} = -12A_{12} e^{4\zeta(k_1)k_2} \chi_{k_1,k_2}(x + k_2) \tilde{\rho}_{1,x} \rho_{2,x} \\
= -12A_{12} \chi_{k_1,k_2}^2(x + k_2) \frac{\Phi_{k_1}^2(x + 2k_2)}{\Phi_{k_1}^2(x)} \rho_{1,x} \rho_{2,x}. \quad (B.21) $$
where we have used
\[
\tilde{\rho}_{1,x} = e^{-4\xi(k_1)k_2} \frac{\Phi_1^2(x + 2k_2)}{\Phi_1^2(x)} \rho_{1,x}.
\]

Then, combining (B.20) and (B.21) together and expressing \( \chi_{a,b}(c) \) in terms of \( \sigma \) function using (A.10), we finally find
\[
A_{12} = \frac{\sigma^2(k_1 - k_2)}{\sigma^2(k_1 + k_2)},
\]
with which (B.17) holds.

Equation (B.18) can be verified straightforwardly. The idea is as same as for verifying (B.17), i.e., using (B.12) to eliminate those 4-th-order derivatives of \( \rho_i \) and \( \tilde{\rho}_1 \), and using (B.13), (B.2b) and (B.2c) to express the equation in terms of \( \rho_{i,x} \) and \( \tilde{\rho}_{1,x} \). After long and tedious calculation, we can verify (B.18) for \( i = 1, 2 \). Thus, the elliptic 2-soliton solution (3.7) in Hirota’s form is obtained.

In the above calculation, we expressed the bilinear equations in terms of \( \rho_{i,x} \) and implemented verification by evaluating coefficients of \( \rho_1, \rho_2, \) etc. There is an alternative way to calculate bilinear derivatives of \( \rho_i \) using the Bell polynomials. Let us define
\[
\varrho_i = \Phi_x(a_i)e^{b_i x + c_i t}, \quad a_i, b_i, c_i \in \mathbb{C}.
\]

Then, we have
\[
\varrho_{i,x} = \alpha_i(x) \varrho_i,
\]
where
\[
\alpha_i(x) = \zeta(x + a_i) - \zeta(x) + b_i.
\]

Introduce functions
\[
G_m(x) = \partial_x^{-m-1} \alpha_1(x) + (-1)^m \partial_x^{-m-1} \alpha_2(x).
\]

Then, it can be proved that (see Eq. (3.4) in Gilson et al. (1996) and Eq.(10) in Lambert et al. (1994))
\[
D_n^x D_i^m \varrho_1 \cdot \varrho_2 = (c_1 - c_2)^m Y_n(G_1, G_2, \ldots, G_n) \varrho_1 \varrho_2,
\]
where \( Y_n \) is the Bell polynomials defined via (see Eq.(7.2) in Bell (1934))
\[
Y_n(y_1, y_2, \ldots, y_n) = e^{-y} \partial_x^n e^y,
\]
where \( y = y(x) \) is a \( C^\infty \) function with respect to \( x \) and \( y_i \) stands for \( \partial_i^y y(x) \). \( Y_n \) can be generated by

\[
Y_n(y_1, y_2, \cdots, y_n) = \sum_{n!} \left( \prod_{s=1}^n c_s! \right) \left( \prod_{s=1}^n (s!)^{c_s} \right) \prod_{s=1}^n y_s^{c_s},
\]

where the sum is to be taken over all partitions of \( n = \sum_{s=1}^n sc_s \). The first few \( \{Y_n\} \) are

\[
Y_0 = 1, \quad Y_1 = y_1, \quad Y_2 = y_2 + y_1^2, \\
Y_3 = y_3 + 3y_1y_2 + y_1^3, \\
Y_4 = y_4 + 4y_1y_3 + 3y_2^2 + 6y_1y_2 + y_1^4.
\]

The pioneer work that associates bilinearization of soliton equations with the Bell polynomials is due to Gilson et al. (1996); Lambert et al. (1994).

For the Lamé-type function (B.22), \( Y_n(G_1, G_2, \cdots, G_n) \) is composed by functions such as \( \zeta(x+a) \) and their derivatives with respect to \( x \), which might be finally converted to the expressions in terms of \( \sigma \) function by using the formulae given in Appendix A.

### C Proof of Theorems 3.1 and 4.1

Before presenting the proof, we recall two determinantal identities which are often used when verifying bilinear equations with Wronskian solutions.

**Proposition C.1** *Freeman and Nimmo (1983)* The relation

\[
|M, a, b| |M, c, d| - |M, a, c| |M, b, d| + |M, a, d| |M, b, c| = 0 \quad (C.1)
\]

holds, where \( M \) is a \( N \times (N-2) \) matrix, \( a, b, c \) and \( d \) are \( N \)-th-order column vectors.

**Proposition C.2** *Zhang et al. (2014)* Suppose that \( \Xi = (\Xi_{i,j}) \) is a \( N \times N \) matrix with column vector set \( \{\Xi_{i,j}\} \), \( \Omega = (\Omega_{i,j}) \) is a \( N \times N \) operator matrix with column vector set \( \{\Omega_{i,j}\} \) where entries are operators. Then, we have

\[
\sum_{j=1}^N |\Omega_j \ast \Xi| = \sum_{j=1}^N |(\Omega_j^T)_j \ast \Xi^T|, \quad (C.2)
\]

where for any \( N \)-th-order column vectors \( A_j = (A_{1,j}, \cdots, A_{N,j})^T \) and \( B_j = (B_{1,j}, \cdots, B_{N,j})^T \) we define

\[
A_j \circ B_j = (A_{1,j}B_{1,j}, A_{2,j}B_{2,j}, \cdots, A_{N,j}B_{N,j})^T \quad (C.3)
\]
and

\[ |A_j * \Xi| = |\Xi_1, \ldots, \Xi_{j-1}, A_j \circ \Xi_j, \Xi_{j+1}, \ldots, \Xi_N|. \]  

(C.4)

Now we start to prove Theorem 3.1. For the \( \tau \) function given in Wronskian form (3.10), where entries \( \{\varphi_j\} \) obey relations (3.11), by direct calculation, we have

\[
\begin{align*}
\tau_x &= |N - 2, N|, \\
\tau_{xx} &= |N - 3, N - 1, N| + |N - 2, N + 1|, \\
\tau_{xxx} &= |N - 4, N - 2, N - 1, N| + 2|N - 3, N - 1, N + 1| + |N - 2, N + 2|, \\
\tau_{xxxx} &= |N - 5, N - 3, N - 2, N - 1, N| + 3|N - 4, N - 2, N - 1, N + 1| \\
&\quad + 2|N - 3, N, N + 1| + 3|N - 3, N - 1, N + 2| + |N - 2, N + 3|, \\
\tau_t &= |N - 4, N - 2, N - 1, N| - |N - 3, N - 1, N + 1| + |N - 2, N + 2| \\
&\quad - \frac{3}{2} N^2 \varphi''(x) \tau - 3 \varphi'(x) \tau_x, \\
\tau_{tx} &= |N - 2, N + 3| - |N - 3, N, N + 1| + |N - 5, N - 3, N - 2, N - 1, N| \\
&\quad - \frac{3}{2} N^2 \varphi''(x) \tau - \frac{3}{2} (N^2 + 2) \varphi'(x) \tau_x - 3 \varphi(x) \tau_{xx}.
\end{align*}
\]

Substituting them into the left hand side of (3.1) yields

\[
4 \tau_x \tau_t - 4 \tau_{tx} \tau + \tau_{xxxx} \tau - 4 \tau_{xxx} \tau_x \\
+ 3 \tau_{xx} - 12 \varphi'(x) (\tau_{xx} - \tau_x^2)
\]

\[
= \tau \left( 6 N^2 \varphi''(x) \tau + 12 \varphi'(x) \tau_x - 3 |N - 2, N + 3| + 6 |N - 3, N, N + 1| \\
+ 3 |N - 3, N - 1, N + 2| \\
+ 3 |N - 4, N - 2, N - 1, N + 1| - 3 |N - 5, N - 3, N - 2, N - 1, N| \\
- 12 |N - 2, N| |N - 3, N - 1, N + 1| + 3 (|N - 3, N - 1, N| \\
+ |N - 2, N + 1|)^2. \right) \tag{C.5}
\]

With the help of Proposition C.2 where we take \( \Omega_{j,s} = \varphi(k_j) \), from identity

\[
\left( \sum_{j=1}^N \varphi(k_j) \tau \right)^2 = \tau \sum_{j=1}^N \varphi(k_j) \left( \sum_{j=1}^N \varphi(k_j) \tau \right)
\]

we have

\[
0 = \tau \left( -2 N^2 \varphi''(x) \tau - 4 \varphi'(x) \tau_x + |N - 2, N + 3| + 2 |N - 3, N, N + 1| \\
- |N - 3, N - 1, N + 2| \\
- |N - 4, N - 2, N - 1, N + 1| + |N - 5, N - 3, N - 2, N - 1, N| \\
- (|N - 2, N + 1| - |N - 3, N - 1, N|)^2, \right) \tag{C.6}
\]

using which Eq. (C.5) is reduced to

\[
12 (|N - 3, N, N + 1| |N - 1| - |N - 2, N||N - 3, N - 1, N + 1| \\
+ |N - 3, N - 1, N||N - 2, N + 1|), \tag{C.7}
\]

which vanishes in light of Proposition C.1. Thus, Theorem 3.1 is proved.
In a similar way, we can prove Theorem 4.1 for the KP equation. In this case, the Wronskian entries \(\{\varphi_j\}\) satisfy relation (4.9). Derivatives of \(\tau\) with respect \(x\) and \(t\) are the same as those for the KdV equation. Besides them, we also have

\[
\begin{align*}
\tau_y &= 2N\varphi(x)\tau + |\overline{N-3, N-1, N-|N-2, N+1}|, \\
\tau_{yy} &= 4N^2\varphi^2(x)\tau + 4N\varphi(x)(|\overline{N-3, N-1, N-|N-2, N+1}|) \\
&\quad - 4\varphi'(x)\tau_x - 2N\varphi''(x)\tau \\
&\quad + |\overline{N-5, N-3, N-2, N-1, N+2}| + |\overline{N-3, N, N+1}| + |\overline{N-2, N+3}|.
\end{align*}
\]

For the KP equation, we do not have identity (C.6). However, \(\tau_{yy}\tau - \tau_y^2\) contributes the same terms as the right hand side of (C.6). It then follows that

\[
(D_x^4 - 4D_tD_x - 12\varphi(x)D_x^2 + 3D_y^2)\tau \cdot \tau
\]

is reduced to (C.7) as well, which is zero. Thus, we complete the proof for Theorem 4.1.

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