On the environmental dependence of halo formation

Ravi K. Sheth\textsuperscript{1} & Giuseppe Tormen\textsuperscript{2}

\textsuperscript{1} Department of Physics & Astronomy, University of Pittsburgh, 3941 O’Hara Street, PA 15260, USA
\textsuperscript{2} Dipartimento di Astronomia, Vicolo dell’Osservatorio 2, 35122 Padova, Italy
Email: rks12@pitt.edu, tormen@pd.astro.it

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\section{INTRODUCTION}

The excursion set model of hierarchical clustering (Epstein 1983; Bond et al. 1991) has been remarkably successful. It provides useful analytic approximations for the abundance of haloes of mass $m$ at time $t$ (Bond et al. 1991; Sheth, Mo & Tormen 2001), for the conditional mass function of $m$ haloes at $t$ which are later (at $T > t$) in more massive haloes $M > m$ (Bond et al. 1991; Lacey & Cole 1993; Sheth & Tormen 2002), for the abundance of haloes as a function of the larger scale environment (Mo & White 1996; Lemson & Kauffmann 1999; Sheth & Tormen 2002) for the distribution of halo formation times (Lacey & Cole 1993) and masses (Nusser & Sheth 1999; Sheth & Tormen 2004). Here, formation is typically defined as that time when the most massive progenitor contains at least half the final mass.

In the simplest and most used approximation, this approach ignores most correlations between different spatial scales. In this approximation, the approach predicts that there should be no correlation between halo formation and the large scale environment in which the halo sits (White 1996). This is because, in the model, formation refers to a smaller mass than the final virial mass, and hence to a smaller spatial scale than that associated with the Lagrangian radius of an object, whereas the larger scale environment, by definition, refers to scales which are larger than that of the halo.

Lemson & Kauffmann (1999) presented evidence from measurements in numerical simulations of clustering that halo formation times were indeed independent of environment. They interpreted this as evidence that the excursion set neglect of correlations was justified. (Lemson & Kauffmann also presented evidence that a number of other physical properties of haloes were also independent of environment, and this evidence has been used to justify an assumption which enormously simplifies semi-analytic models of galaxy formation: that the properties of galaxies are determined by the haloes in which they form, and not by the surrounding larger-scale environment.) Their conclusion is somewhat surprising for the following reason. It is quite well established that the ratio of massive to low mass haloes is larger in dense regions, and that the excursion set model is able to quantify this dependence quite well (see the references given earlier). It is also well established that, on average, low mass haloes form at higher redshifts (see references given earlier). Together, these suggest that if one averages over the entire range of halo masses in any given region, then the mean formation time in dense regions should be shifted to lower redshifts, simply because these regions contain more massive haloes which, on average, form later. In Figure 4 of their paper, Lemson & Kauffmann averaged over the entire range of halo masses accessible to them in their simulations, and found no dependence of formation time on environment; at face value, this is inconsistent with the simplest excursion set prediction!

The main goal of this paper is to repeat the test for environmental effects on halo formation. Section 2 shows that a simple plot of formation time versus local density does not show strong trends, suggesting that the excursion set approximation is rather accurate. But then, Section 3 presents
2 FORMATION TIMES AND ENVIRONMENT

We have identified the formation times of all haloes which contain more than two hundred particles in the GIF simulations of Kauffmann et al. (1999). These simulations are a subset of those made available to the public by the Virgo consortium (Frenk et al. 2000). Particle positions and velocities from the simulations were output at a range of redshifts, approximately evenly spaced in logarithmic expansion factor: \( \Delta \ln (1+z) \approx 0.0596 \). For each output time, we identified haloes using the spherical overdensity method (e.g., Lacey & Cole 1994; Tormen, Moscardini & Yoshida 2003) which contained at least twenty particles. The required overdensity is a cosmology dependent factor times the background density, as specified by the spherical collapse model. For the SCDM model, this factor is 178, and it is independent of redshift; for the ΛCDM model, it is 323 at \( z = 0 \), and is smaller at higher redshifts (e.g., Peebles 1993). At any given output time \( z_1 \), we selected the haloes which were composed of more than two hundred particles, and studied the formation times and masses at formation of these haloes as follows. (For reference, an \( M_\ast \) halo at \( z = 0, 0.5 \) and 1.0 has 1289, 170 and 31 particles in the SCDM run, and 807, 185 and 40 particles in the ΛCDM run, so the high redshift runs mainly probe the formation times and masses of objects much larger than \( M_\ast \).

Given a halo of mass \( M_1 \) (i.e., containing \( N_1 \) particles) at \( z_1 \), we go to the previous output step \( (z_1 + d_{z_2}, \text{say}) \), identify the object which contributes the most number of particles to \( N_1 \), and call it the most massive progenitor at \( z_1 + d_{z_2} \). Suppose this most massive progenitor had \( N_2 \) particles. We then go to the preceding output step \( (z_1 + d_{z_2} + d_{z_3}, \text{say}) \) and identify the most massive progenitor, \( N_3, \) of \( N_2 \). We continue in this way until the number of particles in the most massive progenitor first falls below \( N_1/2 \). If the mass just

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**Figure 1.** Joint distribution of halo formation times and environments. Crosses and dots represent massive and low mass haloes respectively. Histograms show the cumulative distribution of formation redshifts, averaged over the entire halo population, for two bins in density (dotted/solid curves show results for low/high densities). Although the symbols appear to show that low mass haloes in dense regions tend to have formation times which extend to higher redshifts, when averaged over the entire population of high- and low-mass haloes, there are no significant trends with environment.

**Figure 2.** Same as previous figure, but now with scaled formation redshifts. Note that, in these scaled units, all haloes span the same range along the x-axis, whatever their mass. Histograms show the cumulative distribution of \( \omega_{0.5} \), averaged over the entire halo population, for different bins in density (dotted/solid line is for lower/higher density environments). Comparison of the dotted and solid lines indicates that haloes in dense regions tend to have formation times which extend to higher redshifts compared to their counterparts in less dense regions.
their local density, and then choosing those whose local density was in the lowest ten percent to make the dotted curves, and haloes whose local density was in the highest ten percent to make the solid curves. The similarity of the cumulative distributions suggests that there is little evidence for dependence of formation time on local density. This is essentially what Lemson & Kauffmann (1999) found, using a similar technique. (In fact, Lemson & Kauffmann defined the environment of a halo slightly differently—they use the density in a shell within $2h^{-1}$ and $5h^{-1}$ Mpc of each halo, whereas we include the central region as well. Since most halos are smaller than $2h^{-1}$ Mpc, our definition of local density places massive haloes in denser regions than does theirs.) Note, however, that as a result of the average over masses, this plot is difficult to interpret.

A slightly more straightforward plot to interpret is shown in Figure 2, were we have scaled all the formation times to $\omega_{0.5} = (\delta_{0.5}(z) - \delta_{0.1}(z))/[\sigma^2(M/2) - \sigma^2(M)]^{1/2}$; in this variable, the dependence of formation time on mass has been removed (Lacey & Cole 1993). Comparison with the previous figure shows that, indeed, haloes of all masses now span the same range along the x-axis. Figure 3 shows this explicitly: the different symbols show the scaled formation time distribution for different halo populations in the simulations. The solid curves in each panel all show the same functional form, $p(\omega) = 2\omega \text{erf}(\omega/\sqrt{2})$. Notice that this functional form provides a reasonably good description of the scaled halo formation times over a wide range of masses and times. This rescaling allows us to look for a dependence on environment in the following sense: do haloes of a given mass in dense regions form at different times relative to their counterparts of the same mass in the field? The slight separation between the cumulative histograms indicates that there is marginal evidence for higher formation redshifts in dense regions.

Rather than quantifying this with a KS test, we have chosen to present the results of a different test which we believe is to be preferred, as it does not depend on the vagueries of what scale one chooses to define the local density (what is special about $10h^{-1}$ Mpc? why make a spherical average? what if one excises the region occupied by the halo itself when estimating the local density?), or on how the choice of density threshold affects the result (how do the cumulative histograms change if we simply split the sample into two equal-sized halves, rather than compare only the extreme ends of the density distribution?).

3 A MARKED CORRELATION FUNCTION ANALYSIS

This section describes the results of a novel test of environmental effects on halo formation times: an analysis of the ‘marked’ correlations of the halo population, with formation time as the ‘mark’. Let $m_i$ and $m_j$ denote the values of the marks associated with objects $i$ and $j$, and let $\bar{m}$ denote the mean value of the mark, when averaged over all objects. The marked correlation function with objects $i$ and $j$, denoted by the product of the marks $m_i m_j$, divided by the sum over the same pairs (i.e., those separated by $r$), but this time weighted by $\bar{m}^2$. In essence, $M(r)$ tests if pairs separated by
We use the formation redshift as the mark, then a plot \( r \) tends to have larger or smaller values than the mean mark. If we use the formation redshift as the mark, then a plot of \( M(r) \) versus \( r \) shows if close pairs tend to have smaller \( (M(r) < 1) \) or larger \( (M(r) > 1) \) formation redshifts than average.

The previous section showed that halo formation times depend on mass. Since the clustering of haloes depends on their mass, an analysis which averages over a large range in halo masses will be difficult to interpret. Therefore, the different panels in Figure 4 show the marked correlation functions for a number of small bins in mass in the ΛCDM simulation at \( z_1 = 0 \). Results for other \( z_1 \) and for the SCDM model are qualitatively similar. The symbols show that, in all but the bottom right panel, \( M(r) > 1 \) on small scales. To estimate the statistical significance of the difference from unity, we have randomized the marks and measured \( M(r) \), and then repeated this procedure one hundred times. The solid curve which is close to unity on all scales shows the mean \( M(r) \), averaged over these random realizations. The standard deviation around this mean is shown as the dotted line; comparison of the symbols with the shape of this curve suggests that we have weak evidence that close pairs have larger formation redshifts than average. The bottom right panel appears to behave differently from the others, so a word on why this happens is in order. Notice that this bin contains a much larger range of halo masses. Massive haloes cluster more strongly than low mass ones, so it is plausible that each of the closest pairs in this bin is either a pair of massive haloes, or has one of these massive haloes as one member of the pair. Since massive haloes have, on average, the smallest formation redshifts, \( M(r) \) drops on small scales. This again illustrates the complexities of interpreting plots which average over a range of masses.

We have repeated this analysis but using the recalced formation times \( \omega_{0.5} \) defined in the previous section. Since this rescaling removes the dependence of formation redshift on mass, we are now allowed to average over the entire range of halo masses when computing the marked correlation function, thus allowing us to increase the signal-to-noise of our measurement. The results are shown in Figure 5; now there is clear evidence that close pairs tend to form earlier than do more distant pairs. At \( 1 h^{-1}\text{Mpc} \), for instance, \( M_\omega(r) \sim 1.2 \) because \( M_\omega(r) \) depends on the product of the marks, this suggests that haloes with neighbours on this scale tend to have values of \( \omega_{0.5} \) which are typically \( \sim 1.20.5 \) times the mean value, but that on scales of order \( 10h^{-1}\text{Mpc} \), this excess is considerably smaller.

The signal appears to be stronger at \( z = 0 \) than at \( z = 0.5 \). Some of this is because, as a consequence of the finite mass resolution of the simulations, we do not sample haloes with small values of \( M/M_\ast \) at higher redshifts. It will be interesting to repeat this analysis on simulations with better mass resolution, so as to quantify how the trend with environment depends on \( M/M_\ast \), and how it depends on redshift (e.g., one might wonder if the signal is clearer at \( z = 0 \) than at \( z = 0.5 \) because the correlation with environment shifts to smaller scales at higher redshifts).

4 ALTERNATIVE DEFINITION OF FORMATION

In the previous sections, formation was defined as the first time that at least half the mass of a halo is contained in one progenitor. To illustrate that the trend with environment we find does not depend on this precise definition of formation,
we have modified the definition as follows: here formation is defined as the first time that at least half the mass of a halo is contained in progenitors each containing at least one percent of the mass of their parent halo. The previous definition corresponds to requiring that the minimum mass of a progenitor be one-half that of the parent. If $z_{0.01}$ denotes this formation time, then $z_{0.01} > z_{0.5}$, but the two formation times depend similarly on halo mass: in both cases, massive haloes form later.

Figure 6 shows the result of rescaling $z_{0.01}$ to $\omega_{0.01}$, similarly to how we rescaled $z_{0.5}$ to $\omega_{0.5}$, and then measuring $p(<\omega_{0.01})$ in different environments, similarly to what was done in Figure 2. (Figure 7, the analogue of Figure 3, shows that this rescaling removes most of the dependence on the mass of the parent halo mass and the redshift when it virialized.) Figure 6 shows that $p(<\omega_{0.01})$ is shifted towards higher redshifts for the haloes in denser regions (solid curve), indicating that for this definition of formation also, haloes in dense regions form slightly earlier.

In the previous section, we argued that the marked correlation function analysis is a simple and powerful technique for detecting and quantifying environmental dependence. To emphasize this point, Figure 8 shows a marked correlation function analysis using $\omega_{0.01}$ as the mark. Notice how similar this signal is to that shown in Figure 5, in which $\omega_{0.5}$ was used as the mark, and also how much easier it is to see the environmental dependence here, than in Figure 6.

Although we will not pursue this further here, we think it is worth discussing briefly what information we think the shape of the $M(r)$ contains. Suppose we write the weighted correlation function as a bias factor times the unweighted correlation function: $W(r) \approx B^2(r)\xi(r)$. In models where environmental effects only matter on small scales, one might reasonably expect this bias factor to become independent of scale on sufficiently large scales. Since $\xi(r)$ typically decreases with increasing separation, the rate at which $M(r) = [1 + B^2\xi(r)]/[1 + \xi(r)] \rightarrow 1$ on large scales...
Figure 9. Scaled distribution of halo concentrations at $z = 0$. Bars, squares and hexagons show results for halos with masses in the range $1 < M/M_* < 2$, $4 < M/M_* < 8$, and $16 < M/M_* < 32$. In this scaled variable, the distribution of halo concentrations is approximately independent of mass. Solid line shows that this shape is well approximated by a Lognormal with rms $\sigma_{\ln c} = 0.3$.

![Diagram showing scaled distribution of halo concentrations at $z = 0$. Bars, squares, and hexagons represent results for different mass ranges, with the solid line indicating a Lognormal distribution with $\sigma_{\ln c} = 0.3$.]

is determined by the bias factor. This suggests a generalization of the test we have performed: smooth the marked field (e.g., compute the mean formation time in spheres of radius $R$), compute the correlation function of the smoothed marked field, and normalize by the correlation function of the smoothed density field. If the mark is determined by local effects, then a measurement of the shape of the marked correlation function on large smoothing scales is a measurement of the bias associated with the mark.

Figure 10. Similar to Figures 5 and 8, but now with scaled concentration $C$ as the mark. There is no evidence that, once mass dependent trends have been removed, halo concentrations depend on environment. It will be interesting to see if this conclusion remains when this analysis is repeated with higher resolution simulations.

![Diagram showing the dependence of halo concentrations on environment. The scaled distribution is shown for different mass ranges, with the solid line indicating a Lognormal distribution with $\sigma_{\ln c} = 0.3$.]

depends on environment, it is plausible that the structural properties of haloes will also depend on environment.

As a first step, we have attempted a measurement which uses the halo concentration as the mark. This is not entirely straightforward, because the GIF simulations we have used in this paper do not have particularly good mass-resolution, so they are not well suited to estimating the density run around halo centres; as a result, the halo concentrations we estimate are rather noisy. Nevertheless, if we select a sample for which the Navarro et al. formula is a better fit, then we find reasonable agreement with previous higher resolution studies (e.g. Jing 2000) which were restricted to considerably smaller halo samples. Specifically, we find that on average, massive halos have slightly smaller concentration parameters: $\langle \ln c \rangle = \ln[c_* (M/M_*)^{-0.1}]$, with $c_* = 8$ and $9$ at $z = 0$ in the SCDM and ΛCDM runs. More importantly, the distribution around the mean concentration is approximately independent of halo mass, and is well approximated by a lognormal with $\sigma_{\ln c} = 0.3$. This is shown in Figure 9.

Because the same lognormal shape provides a good description of the distribution of concentrations at all masses, we can use it to remove mass-dependent trends, as we did in our study of halo formation in main text. Figure 10 shows a marked correlation function in which this scaled concentration was used as the mark. There is no evidence that the concentrations of close pairs are any different than those of more widely separated pairs, suggesting that, once mass-dependent trends have been removed, halo concentrations do not depend on environment. Since this strongly suggests that the connection between halo formation and concentration is not as straightforward as is generally assumed, it will be interesting to see if this conclusion remains when the analysis is repeated on higher resolution simulations.

Although we believe a marked correlation analysis of halo concentrations, spins, shapes and alignments will yield interesting results, we think that there is one measurement which is more interesting still. Recent studies of pure dark-matter simulations suggest that galaxies are likely associated with the substructure components of dark matter haloes (Kravtsov et al. 2003). A marked correlation correlation analysis which uses the number of subclumps as the mark would be extremely interesting, because one of the crucial assumptions in current interpretations of the galaxy corre-
lation function is that the number of galaxies which form in a halo depends on halo mass, but does not depend on halo environment. For similar reasons, a marked correlation analysis of the sites in which gas cools in dark-matter plus hydro- simulations will be very interesting, particularly in view of the fact that conventional tests find little evidence for environmental trends (Berlind et al. 2003).

Finally, it is worth mentioning that models based on the work of Efstathiou & Rees (1988) which relate the formation of massive black holes to halo formation assume that, at fixed mass, the clustering of halos is independent of whether or not they formed recently. Measurements in simulations of the large-scale clustering of merger sites indicate that, on scales larger than a few Mpc, this assumption is accurate (Percival et al. 2003). Similarly, simulations show that the large-scale cross-correlation between halos that formed recently and the entire halo population is similar to the auto-correlation function of the entire halo population (Kauffmann & Haehnelt 2002). Both measurements indicate that, at least on large scales, the only trends with environment are those which arise from the correlation between mass and environment, consistent with the simplest excursion set prediction.

Although they emphasized what they saw on large scales, on smaller scales both Kauffmann & Haehnelt (2002) and Percival et al. (2003) do see weak evidence for small additional trends with environment. Their measurements can be reconciled with the excursion set approach if we recall that the excursion set prediction is based on the assumption that different scales are uncorrelated—in the jargon, this comes from using a smoothing filter which is sharp in $k$-space. The predictions of the excursion set approach do depend on the choice of filter. However, the precise choice of filter cannot matter on scales larger than the correlation length. Thus, the predicted importance of halo mass rather than environment on large scales, although it is derived from consideration of the sharp $k$-space filter, is a generic prediction of the approach. On the other hand, one does expect filter-dependent environmental trends on smaller scales. Since the sharp $k$-space filter is not expected to be a reasonable choice on small scales, one generically expects to find correlations with environment on small scales (over and above those associated with halo mass). Presumably, it is these correlations which our analysis is well-suited to detecting.

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