Asymptotic Synchronization for Finite-State Sources

Nicholas F. Travers$^{1,2}$ and James P. Crutchfield$^{1,2,3,4}$

$^1$ Complexity Sciences Center
$^2$ Mathematics Department
$^3$ Physics Department
University of California at Davis,
One Shields Avenue, Davis, CA 95616
$^4$ Santa Fe Institute
1399 Hyde Park Road, Santa Fe, NM 87501

(Dated: January 5, 2011)

We extend a recent synchronization analysis of exact finite-state sources to nonexact sources for which synchronization occurs only asymptotically. Although the proof methods are quite different, the primary results remain the same. We find that an observer’s average uncertainty in the source state vanishes exponentially fast and, as a consequence, an observer’s average uncertainty in predicting future output converges exponentially fast to the source entropy rate.

PACS numbers: 02.50.-r 89.70.+c 05.45.Tp 02.50.Ey

I. INTRODUCTION

In Ref. [1] we analyzed the synchronization process for exact $\epsilon$-machines, where the observer may come to know the internal state of the machine with certainty after only a finite number of measurements. Here, we examine the case of nonexact $\epsilon$-machines, where the observer may only synchronize to the machine’s state asymptotically. Although the analysis differs, the behavior is qualitatively similar to the exact case in the sense that an observer (on average) synchronizes to a nonexact machine exponentially fast. That is, there exist constants $K > 0$ and $0 < \alpha < 1$ such that the average state entropy $H(L) \leq K\alpha^L$, for all $L \in \mathbb{N}$.

Our development is organized as follows. Section II briefly reviews the synchronization problem and provides the essential definitions for our results. Section III presents an intuitive picture of the synchronization process, using it to derive a formula for $\phi(w)$, the conditional state distribution induced by a word $w$. Section IV establishes a formula for the entropy rate of a finite-state $\epsilon$-machine. Section V uses the entropy-rate formula to prove the existence of averaged asymptotic synchronization. Section VI builds on this result to prove our main theorem—the Nonexact Machine Synchronization Theorem. Section VII uses this theorem to show that, for any nonexact $\epsilon$-machine, the state entropy $H(L)$ vanishes exponentially fast and the length-$L$ entropy-rate approximation $h_L(L)$ converges exponentially fast to the machine’s entropy rate. Finally, Sec. VIII summarizes our results and examines possible extensions.

II. BACKGROUND

This section lays out the necessary definitions and background for our results. For a more thorough introduction the reader is referred to Ref. [1], where a similar but more detailed presentation is given.

A. Machines

Definition 1. Hidden Markov machine: A finite-state edge-label hidden Markov machine (HMM) consists of

1. a finite set of states $S = \{\sigma_1, \ldots, \sigma_N\}$,
2. a finite alphabet of symbols $A$, and
3. a set of $N$ by $N$ symbol-labeled transition matrices $T^{(x)}$, $x \in A$, where $T^{(x)}_{ij}$ is the probability of transitioning from state $\sigma_i$ to state $\sigma_j$ on symbol $x$. The corresponding internal state-to-state transition matrix is denoted $T = \sum_{x \in A} T^{(x)}$.

A hidden Markov machine can be depicted as a directed graph with labeled edges. The nodes are the states $\{\sigma_1, \ldots, \sigma_N\}$ and for all $x, i, j$ with $T^{(x)}_{ij} > 0$, there is an edge from state $\sigma_i$ to state $\sigma_j$ labeled $p|x$ for the symbol $x$ and transition probability $p = T^{(x)}_{ij}$. We require that the transition matrices $T^{(x)}$ be such that this graph is strongly connected.

A hidden Markov machine $M$ generates a stationary process $P = (X_L)_{L \geq 0}$ as follows. Initially, $M$ starts in some state $\sigma_i$ chosen according to the stationary distribution $\pi$ over machine states—the distribution satisfying $\pi T = \pi$. It then picks an outgoing edge according to their relative transition probabilities $T^{(x)}_{ij}$, emits the symbol $x^*$ labeling this edge, and follows the edge to a new state $\sigma_{j^*}$. The next output symbol and state are consequently chosen in a similar fashion, and this procedure is repeated indefinitely.

We denote by $S_0, S_1, S_2, \ldots$ the random variables (RVs) for the sequence of machine states visited and...
by $X_0, X_1, X_2, \ldots$ the RVs for the associated sequence of output symbols generated. The sequence of states $(S_L)_{L \geq 0}$ is a Markov chain with transition kernel $T$. However, the stochastic process we consider is not the sequence of states, but rather the associated sequence of outputs $(X_L)_{L \geq 0}$, which is not normally Markov. We assume that an observer of the process sees the sequence of outputs, but does not have direct access to the machine’s “hidden” internal states.

**Example: Even Process Machine** Figure 1 gives an HMM for the Even Process, a machine that has been studied extensively [2]. Its name derives from the feature that in its output there are always an even number of 1s in its output sequence of states, but rather the associated sequence of outputs, but does not have direct access to the machine’s “hidden” internal states.

**Definition 2.** Given above is also an output RVs: the states are probabilistically distinct.

**FIG. 1:** A hidden Markov machine (the $\epsilon$-machine) for the Even Process. The transitions denote the probability $p$ by $X$ sequence of states, but rather the associated sequence of outputs, but does not have direct access to the machine’s “hidden” internal states.

The following notation will be used for sequences of output RVs:

1. $\overrightarrow{X} = X_0X_1 \ldots$,
2. $\overrightarrow{X}^L = X_0X_1 \ldots X_{L-1}$, and
3. $\overrightarrow{X}_L^L = X_1X_2 \ldots X_{L+1}$.

**Definition 2.** A finite-state $\epsilon$-machine is a finite-state edge-label hidden Markov machine with the following properties:

1. **Unifilarity:** For each state $\sigma_k \in S$ and each symbol $x \in A$ there is at most one outgoing edge from state $\sigma_k$ labeled with symbol $x$.
2. **Probabilistically distinct states:** For each pair of distinct states $\sigma_k, \sigma_j \in S$ there exists some finite word $w = x_0x_1 \ldots x_{L-1}$ such that:
   \[
   \Pr(\overrightarrow{X}^L = w | S_0 = \sigma_k) \neq \Pr(\overrightarrow{X}^L = w | S_0 = \sigma_j).
   \]

**Example (continued)** The Even Process machine given above is also an $\epsilon$-machine. It is clearly unifilar, and $\sigma_1$ can generate the symbol 0 whereas $\sigma_2$ cannot, so the states are probabilistically distinct.

**Remark.** $\epsilon$-Machines were originally defined in Ref. [3] as hidden Markov machines whose states, known as causal states, were the equivalence classes of infinite pasts $\overrightarrow{x}$ with the same probability distribution over futures $\overrightarrow{x}$. This “history machine” definition is, in fact, equivalent to the “generating machine” definition presented above in the finite-state case. Although, this is not immediately apparent. Formally, it follows from the synchronization results established here and in Ref. [1].

We now provide the definitions for two extensions of an $\epsilon$-machine $M$ that are necessary for our proofs later on: the edge machine $M_{edge}$ and the power machine $M^n$.

In what follows:

1. $\Pr(x|\sigma_k) \equiv \Pr(X_0 = x | S_0 = \sigma_k),$
2. $\Pr(w|\sigma_k) \equiv \Pr(\overrightarrow{X}^{|w|} = w | S_0 = \sigma_k),$
3. $I(x, k, j)$ denotes the indicator function of the transition from state $\sigma_k$ to state $\sigma_j$ on symbol $x$, and
4. $I(w, k, j)$ denotes the indicator function of the transition from state $\sigma_k$ to state $\sigma_j$ on the word $w$.

That is, $I(x, k, j) = 1$ if $\sigma_k \overrightarrow{x} \sigma_j$ and 0 otherwise; $I(w, k, j) = 1$ if $\sigma_k \overrightarrow{w} \sigma_j$ and 0 otherwise.

**Definition 3.** For an $\epsilon$-machine $M$, the corresponding edge machine $M_{edge}$ is the Markov chain whose states are the outgoing edges of $M$. That is, the states are the pairs $(x, \sigma_k)$ such that $\Pr(x|\sigma_k) > 0$, and the transition probabilities are defined as:

\[
\Pr((x, \sigma_k) \rightarrow (y, \sigma_j)) = \Pr(y|\sigma_j)I(x, k, j).
\]

A sequence of $M_{edge}$ states visited by the Markov chain corresponds to a sequence of edges visited by the original machine $M$. The process $P_{edge}$ generated by $M_{edge}$ can be thought of as the bi-process $(X_L, S_L)_{L \geq 0}$ generated by the original machine $M$ as it moves from state to state generating symbols. Note that since $M$’s graph is strongly connected, $M_{edge}$’s graph is as well. Hence, the edge-label Markov chain is irreducible and has a unique stationary distribution $\pi_{edge}$. See Fig. 2 (top).

**Definition 4.** Let $M$ be an $\epsilon$-machine, and let $n$ be relatively prime to the period $p$ of $M$’s graph. The power machine $M^n$ is defined to be the $\epsilon$-machine with the states of $M$, output symbols which are length-$n$ words generated by $M$, and transition probabilities given by:

\[
\Pr(\sigma_k \overrightarrow{w} \sigma_j) = \Pr(w|\sigma_k)I(w, k, j).
\]

The power machine $M^n$ generates the same process as the original machine $M$, but over length-$n$ blocks.

Note that since $M$ is by definition unifilar with probabilistically distinct states, $M^n$ is also necessarily unifilar with probabilistically distinct states. Furthermore, it can be shown that for $n$ relatively prime to $p = \text{period}(M)$ the graph of $M^n$ is strongly connected. Therefore, for $n$ relatively prime to $p$, $M^n$ is indeed an $\epsilon$-machine for the process $P^n$. See Fig. 2 (bottom).
As to the current state of the machine after observing \( w \) let \( \phi \) has knowledge of this fact.

by the machine is stationary, and also that the observer synchronizes to the machine’s state through observations of the output. Due to unifilarity, we know that if the observer synchronizes to the machine’s state through observations, we are interested in studying the procedure by which the observer synchronizes to the machine’s state through these observations. Due to unifilarity, we know that if an observer is able to completely synchronize to the machine’s internal state at some time \( T > 0 \), it remains synchronized for all future times \( T' \geq T \). For simplicity, we assume that the initial state is chosen according to the stationary distribution \( \pi \), so that the process generated by the machine is stationary, and also that the observer has knowledge of this fact.

For a word \( w \) of length \( L \) generated by the machine let \( \phi(w) = \Pr(S|w) \) be the observer’s belief distribution as to the current state of the machine after observing \( w \). That is,

\[
\phi(w)_k = \Pr(S_L = \sigma_k | X^L = w) \\
= \Pr(S_L = \sigma_k | X^L = w, S_0 \sim \pi).
\]

And, define the observer’s uncertainty in the machine state after observing \( w \) as:

\[
u(w) = H(\phi(w)) = H(S_L | X^L = w).
\]

Let \( \mathcal{L}(M) \) denote the set of all finite words that \( M \) can generate, \( \mathcal{L}_L(M) \) the set of all length-\( L \) words it can generate, and \( \mathcal{L}_\infty(M) \) the set of all infinite sequences \( \overrightarrow{x} = x_0x_1... \) that it can generate.

**Definition 6.** A word \( w \in \mathcal{L}(M) \) is a synchronizing word (or sync word) for \( M \) if \( u(w) = 0 \); that is, if the observer knows the current state of the machine with certainty after observing \( w \).

We denote the set of \( M \)'s infinite synchronizing sequences as SYN(M) and the set of \( M \)'s infinite weakly synchronizing sequences as WSYN(M):

\[
\text{SYN}(M) = \{ \overrightarrow{x} \in \mathcal{L}_\infty(M) : u(\overrightarrow{x}^L) = 0 \text{ for some } L \}, \quad \text{and}
\text{WSYN}(M) = \{ \overrightarrow{x} \in \mathcal{L}_\infty(M) : u(\overrightarrow{x}^L) \to 0 \text{ as } L \to \infty \}.
\]

**Definition 7.** An \( \epsilon \)-machine \( M \) is exactly synchronizable (or simply exact) if \( \Pr(\text{SYN}(M)) = 1 \); that is, if the observer synchronizes to almost every (a.e.) sequence the machine generates in finite time.

**Definition 8.** An \( \epsilon \)-machine \( M \) is asymptotically synchronizable if \( \Pr(\text{WSYN}(M)) = 1 \); that is, if the observer’s uncertainty in the machine state vanishes asymptotically for a.e. sequence the machine generates.

**Examples:**

- The Even Process \( \epsilon \)-machine is an exact machine. Any word containing a 0 is a sync word for this machine, and almost every \( \overrightarrow{x} \) generated by this machine contains at least one 0.
- The ABC machine (Fig. 3) is not exactly synchronizable, but it is asymptotically synchronizable.

\[
p|1, \ 1 - p|0
\]

**FIG. 2:** Examples of \( M_{\text{edge}} \) (top) and \( M^2 \) (bottom) for the Even Process \( \epsilon \)-machine \( M \).

**B. Synchronization**

Although we assume that our observer is not able to directly see the \( \epsilon \)-machine’s internal state (\( S_L \)), it is able to see the output symbols generated by the machine (the \( X_L \)’s). Thus, the observer may attempt to infer the internal machine state through observations of the output. We are interested in studying the procedure by which the observer synchronizes to the machine’s state through these observations. Due to unifilarity, we know that if an observer is able to completely synchronize to the machine’s internal state at some time \( T > 0 \), it remains synchronized for all future times \( T' \geq T \). For simplicity, we assume that the initial state is chosen according to the stationary distribution \( \pi \), so that the process generated by the machine is stationary, and also that the observer has knowledge of this fact.

For a word \( w \) of length \( L \) generated by the machine let \( \phi(w) = \Pr(S|w) \) be the observer’s belief distribution as to the current state of the machine after observing \( w \). That is,

\[
\phi(w)_k = \Pr(S_L = \sigma_k | X^L = w) \\
= \Pr(S_L = \sigma_k | X^L = w, S_0 \sim \pi).
\]

And, define the observer’s uncertainty in the machine state after observing \( w \) as:

\[
u(w) = H(\phi(w)) = H(S_L | X^L = w).
\]

Let \( \mathcal{L}(M) \) denote the set of all finite words that \( M \) can generate, \( \mathcal{L}_L(M) \) the set of all length-\( L \) words it can generate, and \( \mathcal{L}_\infty(M) \) the set of all infinite sequences \( \overrightarrow{x} = x_0x_1... \) that it can generate.

**Definition 6.** A word \( w \in \mathcal{L}(M) \) is a synchronizing word (or sync word) for \( M \) if \( u(w) = 0 \); that is, if the observer knows the current state of the machine with certainty after observing \( w \).

We denote the set of \( M \)'s infinite synchronizing sequences as SYN(M) and the set of \( M \)'s infinite weakly synchronizing sequences as WSYN(M):

\[
\text{SYN}(M) = \{ \overrightarrow{x} \in \mathcal{L}_\infty(M) : u(\overrightarrow{x}^L) = 0 \text{ for some } L \}, \quad \text{and}
\text{WSYN}(M) = \{ \overrightarrow{x} \in \mathcal{L}_\infty(M) : u(\overrightarrow{x}^L) \to 0 \text{ as } L \to \infty \}.
\]

**Definition 7.** An \( \epsilon \)-machine \( M \) is exactly synchronizable (or simply exact) if \( \Pr(\text{SYN}(M)) = 1 \); that is, if the observer synchronizes to almost every (a.e.) sequence the machine generates in finite time.

**Definition 8.** An \( \epsilon \)-machine \( M \) is asymptotically synchronizable if \( \Pr(\text{WSYN}(M)) = 1 \); that is, if the observer’s uncertainty in the machine state vanishes asymptotically for a.e. sequence the machine generates.

**Examples:**

- The Even Process \( \epsilon \)-machine is an exact machine. Any word containing a 0 is a sync word for this machine, and almost every \( \overrightarrow{x} \) generated by this machine contains at least one 0.
- The ABC machine (Fig. 3) is not exactly synchronizable, but it is asymptotically synchronizable.
that a machine $M$ is exact if (and only if) it has some sync word $w$ of finite length.

One important quantity to monitor during synchronization is the observer’s average uncertainty in the machine state after seeing a length-$L$ block of output.

**Definition 9.** The observer’s average state uncertainty at time $L$ is:

$$U(L) = H[S_L|X^L] = \sum_{\{x^L\}} \Pr(\overrightarrow{x^L}) U(\overrightarrow{x^L}).$$

**C. Prediction**

A process’s intrinsic randomness is measured by its entropy rate and that, in turn, determines how well an observer can predict its behavior.

**Definition 10.** The block entropy $H(L)$ for a stationary process $\mathcal{P}$ is:

$$H(L) = H[\overrightarrow{x^L}] = -\sum_{\{x^L\}} \Pr(\overrightarrow{x^L}) \log_2 \Pr(\overrightarrow{x^L}).$$

**Definition 11.** The entropy rate $h_\mu$ is the asymptotic average entropy per symbol:

$$h_\mu = \lim_{L \to \infty} \frac{H(L)}{L} = \lim_{L \to \infty} H[X_{L-1}|\overrightarrow{x^{L-1}}].$$

**Definition 12.** Its length-$L$ approximation is:

$$h_\mu(L) = H(L) - H(L - 1) = H[X_{L-1}|\overrightarrow{x^{L-1}}].$$

That is, $h_\mu(L)$ is the observer’s average uncertainty in the next symbol to be generated after observing the first $L - 1$ symbols.

For any stationary process, $h_\mu(L)$ monotonically decreases to the limit $h_\mu$. However, the form of convergence depends on the process. The lower the value of $h_\mu$ a process has, the better an observer’s predictions of the process will be asymptotically. The faster $h_\mu(L)$ converges to $h_\mu$, the faster an observer’s predictions will reach this optimal asymptotic level. Since we are often interested in making predictions after only a finite sequence of observations, the source’s true entropy rate $h_\mu$, as well as the rate of convergence of $h_\mu(L)$ to $h_\mu$, are both important properties.

Now, for an $\epsilon$-machine, an observer’s prediction of the next output symbol is a direct function of the probability distribution over machine states induced by the previously observed symbols. That is,

$$\Pr(X_L = x|\overrightarrow{x^L} = \overrightarrow{x^L}) = \sum_k \Pr(x|\sigma_k) \Pr(S_L = \sigma_k|\overrightarrow{x^L} = \overrightarrow{x^L}).$$

Hence, the better an observer knows the machine state at the current time, the better it can predict the next symbol the machine generates. And, on average, the closer $U(L)$ is to 0, the closer $h_\mu(L)$ is to $h_\mu$. Therefore, the rate of convergence of $h_\mu(L)$ to $h_\mu$ for an $\epsilon$-machine is closely related to the average rate of synchronization. This is one of the primary motivations for studying the synchronization problem.

### III. An Intuitive Picture

In this section we present an intuitive picture of the synchronization process and use it to derive a formula for the conditional state distribution $\phi(w)$. The basic idea is illustrated schematically in Fig. 4 for a hypothetical 5-state machine.

![Synchronization diagram](image)

**FIG. 4:** Synchronization illustrated for a 5-state machine.

Initially, the observer does not know the machine state $S_0$, so all five states $\{\sigma_1, \sigma_2, \sigma_3, \sigma_4, \sigma_5\}$ are possible. After seeing the first symbol $x_0$, there are only four possibilities for $S_1 = \{\sigma_1, \sigma_2, \sigma_3, \sigma_5\}$—since only four of the five states may generate this symbol. After seeing the second symbol $x_1$, a different set of four states is possible—$\{\sigma_1, \sigma_2, \sigma_3, \sigma_4\}$. After seeing the third symbol $x_2$, there are only three possibilities $\{\sigma_1, \sigma_2, \sigma_3\}$ for $S_3$, since two of the state paths merge on seeing the third symbol. Finally, after seeing the fourth symbol $x_3$, two more state paths merge and another dies, so there is only one possibility $\{\sigma_3\}$ for $S_4$. The observer has synchronized.

The transition function $\delta(\sigma_k, x)$ is defined by the relation $\sigma_k \xrightarrow{x} \delta(\sigma_k, x)$ and the word transition function $\delta(\sigma_k, w)$ by the relation $\sigma_k \xrightarrow{w} \delta(\sigma_k, w)$. In general, for each possible initial state $\sigma_k$ and each $\overrightarrow{x^L}$ there is a state path $p^k$ following $\sigma_k$ under $\overrightarrow{x^L}$. That is, $p^k = \rho_0^k, \rho_1^k, \ldots, \rho_L^k$, where $\rho_0^k = \sigma_k$, $\rho_1^k = \delta(\rho_0^k, x_0)$, $\rho_2^k = \delta(\rho_1^k, x_1)$, and so on. An observer synchronizes exactly once all, but one, of these paths have either merged or died.
If a machine is not exactly synchronizable, then it is impossible for all paths to merge or die and, at any finite time $L$, there are at least two possible nonmerged paths remaining. However, it is still possible for an observer to synchronize to such a machine asymptotically. To understand how this happens we need to know the relative probabilities of being in each of the possible remaining states at a given time. In general, the probability of starting in state $\sigma_k$ and generating the word $\mathcal{X}^L$ is:

$$\Pr(p^k) = \Pr(S_0 = \sigma_k, \mathcal{X}^L = \mathcal{X}^L) = \pi_k \cdot \Pr(\mathcal{X}^L | \sigma_k).$$

These probabilities will be exactly 0 if and only if the path $p^k$ dies by the $L_{th}$ symbol. Typically, however, all these probabilities decay—in fact, decay exponentially fast—as $L \to \infty$. For nonexact synchronization, we are concerned not with absolute path probabilities, but with their relative or normalized probabilities. The probability of ending up in state $\sigma_j$ at time $L$ is simply the sum of the normalized probabilities of all paths ending up in state $\sigma_j$. That is, for any word $w = \mathcal{X}^L$ we have:

$$\phi(w)_j \equiv \Pr(S_L = \sigma_j \mathcal{X}^L = w) = \frac{\Pr(S_L = \sigma_j, \mathcal{X}^L = w)}{\Pr(\mathcal{X}^L = w)} = \sum_k \frac{\pi_k \cdot \Pr(w | \sigma_k) \cdot I(w, k, j)}{\sum_i \pi_i \cdot \Pr(w | \sigma_i)} = \sum_k \frac{\Pr(p^k) \cdot I(w, k, j)}{\sum_i \Pr(p^i)}.$$

For nonexact asymptotic synchronization, then, the important quantities to consider are the relative probabilities of all paths that never merge or die. If a nonexact machine is asymptotically synchronizable, then for a.e. $\mathcal{X}$ there must be some state $\sigma_k$ such that the ratio of the path probabilities:

$$\frac{\Pr(p^k(\mathcal{X}^L))}{\Pr(p^i(\mathcal{X}^L))} \to \infty,$$

as $L \to \infty$, for any path $p^j$ which does not eventually merge with $p^k$ or die. Since $\pi_k/\pi_j$ is bounded for all states $\sigma_k$ and $\sigma_j$, the initial state is unimportant for asymptotic synchronization. The question is whether, on average, the transition probabilities for one path are greater than those of the other. If, on average, the transition probabilities for path $p^k$ are $c$ ($>1$) times as likely as the transition probabilities for path $p^i$ then, for large $L$, $\Pr(p^k)/\Pr(p^i) \sim c^L$. Intuitively, this is why synchronization occurs exponentially fast. Establishing this, as we will see, requires some care, however.

IV. THE ENTROPY RATE FORMULA

In this section we derive a formula for the entropy rate of a finite-state $\epsilon$-machine. Although an analogous expression has been previously established in similar contexts (see, e.g., Ref. [5]), we provide a derivation as well for completeness. The proof presented here is also somewhat simpler than the original in Ref. [5]. A proof quite similar to ours for unifilar Moore hidden Markov models (as opposed to the edge-label or Mealy models we use) is given in Ref. [6].

**Proposition 1.** For any $\epsilon$-machine $M$,

$$h_\mu = H[X_0 | S_0] = \sum_k \pi_k h_k,$$

where $h_k = H[X_0 | S_0 = \sigma_k]$.

**Proof.** We establish the bounds from above and below separately.

**Upper bound:** $h_\mu \leq H[X_0 | S_0]$. We calculate directly:

$$h_\mu = \lim_{L \to \infty} \frac{H[\mathcal{X}^L]}{L} \leq \lim_{L \to \infty} \frac{H[S_0] + \sum_{i=0}^{L-1} H[X_i | S_0, \mathcal{X}^i]}{L}$$

(a) $\lim_{L \to \infty} \frac{H[S_0] + \sum_{i=0}^{L-1} H[X_i | S_0]}{L} = \lim_{L \to \infty} \frac{H[S_0] + H[X_0 | S_0] \cdot L}{L} = H[X_0 | S_0],$

where step (a) follows from the chain rule, step (b) from unifilarity, and step (c) from stationarity.

**Lower bound:** $h_\mu \geq H[X_0 | S_0]$. We have:

$$h_\mu = \lim_{L \to \infty} \frac{H[\mathcal{X}^L]}{L} \geq \lim_{L \to \infty} \frac{H[\mathcal{X}^L | S_0]}{L}$$

(a) $\lim_{L \to \infty} \frac{\sum_{i=0}^{L-1} H[X_i | S_0, \mathcal{X}^i]}{L} = \lim_{L \to \infty} \frac{H[X_0 | S_0]}{L} = H[X_0 | S_0],$

where again step (a) follows from the chain rule, step (b) from unifilarity, and step (c) from stationarity.

V. AVERAGED ASYMPTOTIC SYNCHRONIZATION

The entropy rate formula says that (on average) an observer predicts asymptotically just as well as if it knew...
the machine state exactly:
\[
 h_{\mu} = \lim_{L \to \infty} H[X_L | \tilde{X}^L ]
\]
\[
 = H[X_0 | S_0] .
\]
Intuitively, this suggests that an observer’s average uncertainty \(U(L)\) in the machine state must vanish asymptotically. That is, we should have:
\[
 \lim_{L \to \infty} U(L) = 0 .
\]
These ideas are made rigorous below with a convexity argument.

The following notation will be used:

- Let \( p_k \equiv \Pr(X_0 | S_0 = \sigma_k) \) and \( p_w \equiv \Pr(X_0 | S_0 \sim \phi(w)) \).
- Let \( h_k \equiv H[p_k] \) (as above), \( h_w \equiv H[p_w] \), and \( \tilde{h}_w \equiv \sum_k \phi(w)_k h_k \).
- Let \( A_{\epsilon,L} \equiv \{ w \in L_L(M) : \epsilon(w) < \epsilon \} \) and \( \tilde{A}_{\epsilon,L} \equiv L_L(M) / A_{\epsilon,L} \), the complement of \( A_{\epsilon,L} \).

We note that for any word \( w \):
\[
 p_w = \sum_k p_k \phi(w)_k ,
\]
and, hence, by the concavity of the entropy function \( H[\cdot] \):
\[
 h_w = H[p_w]
\]
\[
 = H \left[ \sum_k p_k \phi(w)_k \right]
\]
\[
 \geq \sum_k \phi(w)_k H[p_k]
\]
\[
 = \sum_k \phi(w)_k h_k
\]
\[
 = \tilde{h}_w .
\]

Also, for any length \( L \):
\[
 h_{\mu}(L+1) = H[X_L | \tilde{X}^L ]
\]
\[
 = \sum_{w \in L_L(M)} \Pr(w) h_w ,
\]
and
\[
 h_{\mu} = \sum_k \pi_k h_k
\]
\[
 = \sum_k \left( \sum_{w \in L_L(M)} \Pr(w) \phi(w)_k \right) h_k
\]
\[
 = \sum_{w \in L_L(M)} \Pr(w) \sum_k \phi(w)_k h_k
\]
\[
 = \sum_{w \in L_L(M)} \Pr(w) \tilde{h}_w .
\]

**Proposition 2.** For any finite-state \( \epsilon \)-machine \( M \):
\[
 \lim_{L \to \infty} U(L) = 0 .
\]

**Proof.** We first prove the statement under the assumption that \( U(L) \neq 0 \), then there must be some \( \epsilon > 0 \) for which \( \Pr(A^c_{\epsilon,L}) \neq 0 \). Hence, there exists some \( \delta > 0 \) and a subsequence \( (L_i)_{i=1}^{\infty} \) of the \( L_s \) such that \( \Pr(A^c_{\epsilon,L_i}) \geq \delta \), for all \( i \).

Let \( \Delta \) be the unit simplex in \( \mathbb{R}^N \):
\[
 \Delta = \left\{ \phi \in \mathbb{R}^N : \sum_k \phi_k = 1 \text{ and } \phi_k \geq 0, \text{ for all } k \right\} ,
\]
and let:
\[
 \Delta_\epsilon = \left\{ \phi \in \Delta : H[\phi] \geq \epsilon \right\} .
\]

Define \( f : \Delta_\epsilon \to \mathbb{R} \) by:
\[
 f(\phi) = H \left[ \sum_k \phi_k p_k \right] - \sum_k \phi_k H[p_k] ,
\]
so that, for any word \( w \), \( f(\phi(w)) = h_w - \tilde{h}_w \).

Then, with respect to \( \| \cdot \|_1 \), \( f(\phi) \) is a continuous function on \( \Delta_\epsilon \), and \( \Delta_\epsilon \) is a compact set. Therefore, we know \( f \) obtains its minimum \( f^* \) at some point \( \phi^* \in \Delta_\epsilon \).

Since \( M \) has a minimum distinguishing length \( L^* = 1 \) and the entropy function \( H[\cdot] \) is strictly concave, we know \( f(\phi) > 0 \) for all \( \phi \in \Delta_\epsilon \). In particular, \( f(\phi^*) = f^* > 0 \).

Hence, for each \( i \) we have:
\[
 h_{\mu}(L_i + 1) - h_{\mu}
\]
\[
 \overset{(a)}{=} \sum_{w \in L_L(M)} \Pr(w) h_w - \sum_{w \in L_L(M)} \Pr(w) \tilde{h}_w
\]
\[
 = \sum_{w \in L_L(M)} \Pr(w) \cdot (h_w - \tilde{h}_w)
\]
\[
 \overset{(b)}{\geq} \sum_{w \in A^c_{\epsilon,L_i}} \Pr(w) \cdot (h_w - \tilde{h}_w)
\]
\[
 = \Pr(A^c_{\epsilon,L_i}) \cdot f^*
\]
\[
 \geq \delta f^* .
\]

Step (a) follows from Eqs. (3) and (6) and step (b) follows from Eq. (4). Equation (5) implies that \( h_{\mu}(L) \neq h_{\mu} \), which is a contradiction. Hence, we know
\[
 \lim_{L \to \infty} U(L) = 0 .
\]

**Case (ii):** \( M \) has minimum distinguishing length \( L^* = 1 \). Take \( n \geq L^* \) and relatively prime to the period \( p \) of \( M^* \)’s graph, so that \( M^* \) is an \( \epsilon \)-machine with a minimum distinguishing length of 1. Let \( Y_L \) be the RV for the \( L_{th} \) output symbol generated by the machine \( M^* \), let \( R_L \) be
the RV for $M^n$’s $L_{th}$ state, and let $\mathcal{V}(L) = H[R_L|\overline{Y}_L]$. Note that for any $L$:

$$\mathcal{V}(L) = \mathcal{U}(nL).$$

(9)

Now, for a contradiction assume $\lim_{L \to \infty} \mathcal{U}(L) \neq 0$. Then, since $\mathcal{U}(L)$ is monotonically decreasing, we know there exists some $\epsilon > 0$ such that $\mathcal{U}(L) \geq \epsilon$, for all $L$. Thus, by Eq. (9), we know that $\mathcal{V}(L) \geq \epsilon$ for all $L$ as well, so $\mathcal{V}(L) \neq 0$. However, since $M^n$ has a minimum distinguishing length of 1, by case (i) above we know that $\mathcal{V}(L)$ must go to zero. This contradiction implies that $\lim_{L \to \infty} \mathcal{U}(L) = 0$.

VI. THE NONEXACT MACHINE SYNCHRONIZATION THEOREM

In this section we prove our primary result, the Nonexact Machine Synchronization Theorem. This extends the weak asymptotic synchronization result of Sec. V to show that synchronization occurs exponentially fast for nonexact machines. The statement is quite analogous to the Exact Machine Synchronization Theorem given in Ref. [1]. Essentially, it says that, except on a set of words $\overline{\mathcal{L}}^L$ of exponentially small probability, an observer’s uncertainty after observing $\overline{\mathcal{L}}^L$ is exponentially small.

The following notation will be used. $\Phi_L \equiv \phi(\overline{\mathcal{L}}^L)$ is the random variable for the belief distribution over states induced by the first length-$L$ word the machine generates, and $\mathcal{S}_L$ is the most likely state in $\Phi_L$ (if a tie the lowest numbered state is taken). $P_L \equiv \Pr(\mathcal{S}_L)$ is the probability of the most likely state in the distribution $\Phi_L$, and $Q_L \equiv \Pr(\text{NOT } \mathcal{S}_L)$ is the combined probability of all other states in the distribution $\Phi_L$. For example, if $\Phi_L = (0.2, 0.7, 0.1)$, then $\mathcal{S}_L = \sigma_2$, $P_L = 0.7$, and $Q_L = 0.3$. Realizations are denoted $\phi_L$, $\mathcal{S}_L$, $P_L$, and $Q_L$, respectively. We also define $U_L = H[\Phi_L]$ and $u_L = H[\phi_L]$.

**Theorem 1.** (Nonexact Machine Synchronization Theorem) For any nonexact $\epsilon$-machine $M$,

1. There exist constants $K_1 > 0$ and $0 < \alpha_1 < 1$ such that:

$$\Pr(Q_L > \alpha_1^L) \leq K_1 \alpha_1^L, \text{ for all } L \in \mathbb{N}.$$  

2. There exist constants $K_2 > 0$ and $0 < \alpha_2 < 1$ such that:

$$\Pr(U_L > \alpha_2^L) \leq K_2 \alpha_2^L, \text{ for all } L \in \mathbb{N}.$$  

The proof strategy is as follows. We first take a power machine $M^n$ of the machine $M$ with $\mathcal{U}(n) = \epsilon \ll 1$, and prove the theorem for the power machine. We then use the exponential convergence of the power machine to establish the theorem in general with a subsequence-type argument.

The following lemma on large deviations of Markov chains will be critical.

**Lemma 1.** Let $Z_0, Z_1, ...$ be a finite-state, irreducible Markov chain, with state set $R = \{r_1, ..., r_n\}$ and equilibrium distribution $\rho = (\rho_1, ..., \rho_n)$. Let $F : R \to \mathbb{R}$, $Y_L = F(Z_L)$, and $\overline{Y}_L = \frac{1}{L} \sum_{i=0}^{L-1} Y_i$. Define $\mu_\rho = \text{E}_\rho(F) = \sum_k \rho_k F(r_k)$. Then, for any $\epsilon > 0$, there exist constants $K > 0$ and $0 < \alpha < 1$ such that, for any state $r_k$:

$$\Pr(|\overline{Y}_L - \mu_\rho| > \epsilon|S_0 = r_k) \leq K \alpha^L, \text{ for all } L \in \mathbb{N}.$$  

Proof. A similar statement (with more explicit values of the constants) is given in Ref. [2] for a general class of Markov chains, which includes all finite-state, irreducible, aperiodic chains. The result stated here follows directly for finite-state, irreducible, aperiodic chains, and can be extended to the periodic case by considering length $p$-blocks, where $p$ is the chain’s period.

**Remark.** Note that since the deviation bound holds conditionally on any initial state $r_k$, it also holds conditionally on any distribution over the initial state by linearity. In particular, we apply this lemma assuming $Z_0 \sim \rho$.

Let us denote:

$$\Pr(x, \sigma_k) = \Pr(S_0 = \sigma_k, X_0 = x),$$

$$\Pr(x|\sigma_k) = \Pr(X_0 = x|S_0 = \sigma_k),$$

$$\Pr(\sigma_k|x) = \Pr(S_0 = \sigma_k|X_0 = x),$$

and

$$\sigma_{\text{max}, x} = \text{argmax } \Pr(\sigma|x),$$

where again the lowest numbered state is chosen in the case of a tie for $\sigma_{\text{max}, x}$. Also, for any $x$ and $\sigma_j$ with $\Pr(x|\sigma_j) > 0$, let us define:

$$\mathcal{S}_{x,j} = \{\sigma_k \in \mathcal{S} : \Pr(x|\sigma_k) > 0, \delta(\sigma_k, x) \neq \delta(\sigma_j, x)\},$$

$$g(x, \sigma_j) = \max_{\sigma_k \in \mathcal{S}_{x,j}} \Pr(x|\sigma_k),$$

and

$$f(x, \sigma_j) = \max_{\sigma_k \in \mathcal{S}_{x,j}} \Pr(\sigma_k|x).$$

Note that $g(x, \sigma_j)$ and $f(x, \sigma_j)$ are both always strictly positive for nonexact $\epsilon$-machines. And, also, that for any joint length-$L$ realization $(\overline{\mathcal{L}}^L, \overline{\mathcal{S}}^L)$:

$$\frac{p_L}{q_L} \geq \frac{\Pr(s_0)}{\Pr(\text{NOT } s_0)} \prod_{i=0}^{L-1} \frac{\Pr(x_i|s_i)}{g(x_i, s_i)},$$

by Eq. (1). Here, $\Pr(s_0) = \pi_k$ is the stationary probability of the state $s_0 = \sigma_k$ and $\Pr(\text{NOT } s_0) = 1 - \Pr(s_0)$.

Using Lemma 1 we now prove our desired theorem under the (relatively strong) assumption that:

$$E_{\pi_{\text{edge}}} \left\{ \log_2 \left( \frac{\Pr(X_0|S_0)}{g(X_0, S_0)} \right) \right\} > 0.$$  

(11)

This assumption will later be satisfied for some power machine $M^n$. 
Lemma 2. Let $M$ be a nonexact $\epsilon$-machine satisfying Eq. (11). Then:

1. There exist constants $K_1 > 0$ and $0 < \alpha_1 < 1$ such that:
   \[
   \Pr(Q_L > \alpha_1^L) \leq K_1\alpha_1^L, \quad \text{for all } L \in \mathbb{N}.
   \]

2. There exist constants $K_2 > 0$ and $0 < \alpha_2 < 1$ such that:
   \[
   \Pr(U_L > \alpha_2^L) \leq K_2\alpha_2^L, \quad \text{for all } L \in \mathbb{N}.
   \]

Proof. We first prove Claim 1 and then use this to show Claim 2.

Proof of Claim 1: Consider the edge-label Markov process $P_{\text{edge}}$ generated by the edge machine $M_{\text{edge}}$. Let $Z_L = (X_L, S_L)$ denote the RV for the $L$th $M_{\text{edge}}$-state and let:

\[
Y_L = F(Z_L) = \log_2 \left( \frac{\Pr(X_L|S_L)}{g(X_L, S_L)} \right).
\]

We assume, of course, that $(X_0, S_0) \sim \pi_{\text{edge}}$ or, equivalently, $S_0 \sim \pi$.

By hypothesis, $\mu_F = \mathbb{E}_{\pi_{\text{edge}}}(F) = C > 0$. Take $\epsilon = C/2$. By Lemma 1 there exist constants $B_1 > 0$ and $0 < \eta_1 < 1$ such that:

\[
\Pr(|Y_L - \mu_F| > \epsilon) \leq B_1\eta_1^L, \quad \text{for all } L \in \mathbb{N}.
\]

Thus, for any $L$:

\[
\Pr \left( \sum_{i=0}^{L-1} \log_2 \left( \frac{\Pr(x_i|x_i)}{g(x_i, x_i)} \right) \leq \frac{C}{2} L \right) = \Pr(Y_L < C/2) = \Pr(Y_L < \mu_F - \epsilon) \leq \Pr(|Y_L - \mu_F| > \epsilon) \leq B_1\eta_1^L.
\]

Now, let $\overrightarrow{x} = (\overrightarrow{x}, \overrightarrow{x})$ be any typical sequence, i.e.:

\[
\sum_{i=0}^{L-1} \log_2 \left( \frac{\Pr(x_i|x_i)}{g(x_i, x_i)} \right) \geq \frac{C}{2} L.
\]

Taking logarithms of Eq. (10) we find:

\[
\log_2 \left( \frac{p_L}{q_L} \right) \geq \log_2 \left( \frac{\Pr(s_0)}{\Pr(\text{NOT } s_0)} \right) + \sum_{i=0}^{L-1} \log_2 \left( \frac{\Pr(x_i|x_i)}{g(x_i, x_i)} \right) \geq \beta + \frac{C}{2} L,
\]

where $\beta \equiv \min_{0 \leq \eta_1 \leq 1} \log_2 \left( \frac{\Pr(s_i=x_i)}{\Pr(s_i \neq x_i)} \right)$. Or, equivalently:

\[
\frac{p_L}{q_L} \geq 2^\beta \cdot 2^{\frac{C}{2} L} = B_2\eta_2^L,
\]

where $B_2 \equiv 2^\beta > 0$ and $\eta_2 \equiv 2^{C/2} > 1$. Thus:

\[
q_L \leq \frac{p_L}{q_L} \leq B_2\eta_2^L,
\]

where $B_3 \equiv 1/B_2 > 0$ and $\eta_3 \equiv 1/\eta_2 < 1$. Since this holds for any typical sequence $(\overrightarrow{x}, \overrightarrow{x})$ we have, for each $L$:

\[
\Pr(Q_L > B_3\eta_3^L) \leq B_1\eta_1^L.
\]

And, therefore, for any $1 > \alpha_1 > \max(\eta_1, \eta_3)$ there exists some $K_1 = K_1(\alpha_1)$ sufficiently large that:

\[
\Pr(Q_L > \alpha_1^L) \leq K_1\alpha_1^L, \quad \text{for all } L \in \mathbb{N}.
\]

Proof of Claim 2: By Claim 1 we know there exist constants $K_1 > 0$ and $0 < \alpha_1 < 1$ such that:

\[
\Pr(Q_L > \alpha_1^L) \leq K_1\alpha_1^L, \quad \text{for all } L \in \mathbb{N}.
\]

Let us define:

\[
V_L^+ = \{ \overrightarrow{x} : q_L > \alpha_1^L \} \quad \text{and} \quad V_L^- = \{ \overrightarrow{x} : q_L \leq \alpha_1^L \}.
\]

Take $L_1$ sufficiently large that $1 - \alpha_1^L \geq 1/2$, for all $L \geq L_1$. Note that the first-order Taylor expansion about $x = 1$ of $\log_2(1-\alpha_1^L)$ is $-\log_2(e)\alpha_1^L + O(\alpha_1^2) \approx -1.44\alpha_1^L$. Thus, there exists some $L_2 \in \mathbb{N}$ such that $|\log_2(1-\alpha_1^L)| \leq 2\alpha_1^L$ for all $L \geq L_2$. Take $L_0 = \max(L_1, L_2)$.

Then, for any $L \geq L_0$ and any $\overrightarrow{x} \in V_L^-$, we have:

\[
H[S_L|\overrightarrow{x}^L] \leq H \left[ \frac{\alpha_1^L}{N-1}, \ldots, \frac{\alpha_1^L}{N-1} \right] = -(1 - \alpha_1^L)\log_2(1 - \alpha_1^L) + \alpha_1^L\log_2 \left( \frac{\alpha_1^L}{N-1} \right) = (1 - \alpha_1^L)\log_2(1 - \alpha_1^L) - \alpha_1^L\log_2(\alpha_1) + \alpha_1^L\log_2(N - 1) \leq (1 - \alpha_1^L)2\alpha_1^L - \alpha_1^L\log_2(\alpha_1) + \alpha_1^L\log_2(N - 1) \leq \frac{L_0}{2}\log_2(C_1\alpha_1^L) \leq C_2\alpha_1^L,
\]

where $C_1 \equiv 2 - \log_2(\alpha_1) + \log_2(N - 1) > 0$, step (a) follows from the fact that $1 - \alpha_1^L \geq 1/2$ for $L \geq L_1$, and step (b) follows from the Taylor expansion bound on $\log_2(1 - \alpha_1^L)$ for $L \geq L_2$. In the last line, $\alpha$ may be chosen as any real number in the interval $(\alpha_1, 1)$ and $C_2 = C_2(\alpha)$ is chosen sufficiently large to ensure the last inequality holds for all $L \geq L_0$.

Equation (12) implies that, for all $L \geq L_0$:

\[
\Pr(U_L \leq C_2\alpha_1^L) \geq \Pr(V_L^-) \geq 1 - K_1\alpha_1^L.
\]

So, we know that, for all $L \geq L_0$:

\[
\Pr(U_L > C_2\alpha_1^L) \leq K_1\alpha_1^L \leq K_1\alpha^L.
\]
Therefore, for any \( \alpha_2 \in (\alpha, 1) \) and \( L \) sufficiently large:

\[
\Pr(U_L > \alpha_2^L) \leq K_1 \alpha_2^L.
\]

And, hence, there exists some \( K_2 \geq K_1 \) such that:

\[
\Pr(U_L > \alpha_2^L) \leq K_2 \alpha_2^L, \quad \text{for all } L \in \mathbb{N}.
\]

To establish the theorem in general now, we show that for any machine \( M \) there exists a power machine \( M^\alpha \) satisfying Eq. (11). To do so requires several additional lemmas.

**Lemma 3.** Let \( M \) be a nonexact \( \epsilon \)-machine. Then, for all \( x \) and \( \sigma_j \) with \( \Pr(x | \sigma_j) > 0 \):

\[
g(x, \sigma_j) \leq f(x, \sigma_j) \frac{\Pr(x)}{\Pr(\sigma_j)} \lambda^2,
\]

where \( \lambda \equiv \max_{i,j} \frac{\pi_i}{\pi_j} \) and \( \Pr(\sigma_j) \) and \( \Pr(x) \) are the respective stationary probabilities of the state \( \sigma_j \) and symbol \( x \): \( \Pr(\sigma_j) = \pi_j \) and \( \Pr(x) = \Pr(x_0 = x | S_0 \sim \pi) \).

**Proof.** Fix \( x \) and \( \sigma_j \). Take \( \sigma_k \in S_{x,j} \) such that:

\[
\Pr(\sigma_k | x) / \Pr(\sigma_k) = \max_{\sigma \in S_{x,j}} \Pr(\sigma | x) / \Pr(\sigma_k),
\]

and take \( \sigma_k \in S_{x,j} \) such that:

\[
\Pr(\sigma_k | x) = \max_{\sigma \in S_{x,j}} \Pr(\sigma | x).
\]

Then:

\[
\begin{align*}
\Pr(\sigma_k | x) / \Pr(\sigma_k) & \geq \frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \\
& = \frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \cdot \frac{\Pr(\sigma_k)}{\Pr(\sigma_k)} \\
& \geq \frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \cdot 1 / \lambda,
\end{align*}
\]

and

\[
\begin{align*}
\Pr(\sigma_k | x) / \Pr(\sigma_k) & = \frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \cdot \frac{\Pr(\sigma_k)}{\Pr(\sigma_k)} \\
& \geq \frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \cdot 1 / \lambda
\end{align*}
\]

Combining these relations we see that:

\[
\frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \leq \lambda^2 \cdot \frac{\Pr(\sigma_k)}{\Pr(\sigma)}.
\]

And, therefore:

\[
g(x, \sigma_j) = \max_{\sigma \in S_{x,j}} \left\{ \Pr(\sigma | x) \right\}
\]

\[
= \max_{\sigma \in S_{x,j}} \left\{ \frac{\Pr(\sigma | x)}{\Pr(\sigma_k)} \right\} \cdot \frac{\Pr(\sigma_k)}{\Pr(\sigma_k)} \cdot \Pr(x)
\]

\[
= \frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \cdot \Pr(x)
\]

\[
\leq \lambda^2 \cdot \frac{\Pr(\sigma_k | x)}{\Pr(\sigma_k)} \cdot \Pr(x)
\]

\[
= f(x, \sigma_j) \frac{\Pr(x)}{\Pr(\sigma_j)} \lambda^2.
\]

Define \( A_e = A_{e,1} = \{ x \in A : u(x) < \epsilon \} \).

**Lemma 4.** Let \( M \) be a nonexact \( \epsilon \)-machine such that:

1. \( \Pr(A_{\epsilon}) > 1 - \epsilon \), for some \( \epsilon < 1/2 \), and

2. \( \Pr(\sigma_{\max,x} | x) / (f(x, \sigma_{\max,x}) \lambda^2) \geq 2^{N^2 \lambda^2} \), for all \( x \in A_{\epsilon} \).

Then, \( \mathbb{E}_{\pi_{\text{edge}}} \left\{ \log_2 \left( \frac{\Pr(x_0 | S_0)}{g(x_0, S_0)} \right) \right\} > 0 \).

**Proof.** Applying Lemma 3 we see:

\[
\begin{align*}
\mathbb{E}_{\pi_{\text{edge}}} \left\{ \log_2 \left( \frac{\Pr(x_0 | S_0)}{g(x_0, S_0)} \right) \right\}
& = \sum_{x \in A} \sum_j \Pr(x, \sigma_j) \log_2 \left( \frac{\Pr(x | \sigma_j)}{g(x, \sigma_j)} \right) \\
& \geq \sum_{x \in A} \sum_j \Pr(x, \sigma_j) \log_2 \left( \frac{\Pr(x | \sigma_j)}{f(x, \sigma_j) \lambda^2} \Pr(x) / \Pr(\sigma_j) \right) \\
& = \sum_{x \in A} \Pr(x) \sum_j \Pr(\sigma_j | x) \log_2 \left( \frac{\Pr(x)}{f(x, \sigma_j) \lambda^2} \right) \\
& + \sum_{x \in A} \Pr(x) \sum_j \Pr(\sigma_j | x) \log_2 \left( \frac{\Pr(\sigma_j | x)}{f(x, \sigma_j) \lambda^2} \right).
\end{align*}
\]

Now, for any \( x \in A_{\epsilon} \) we have:

\[
\begin{align*}
\sum_j \Pr(\sigma_j | x) \log_2 \left( \frac{\Pr(\sigma_j | x)}{f(x, \sigma_j) \lambda^2} \right)
& \geq \sum_j \lambda^2 \left[ \log_2 \left( \frac{\Pr(\sigma_j | x)}{\lambda^2} \right) \right] \\
& \geq \sum_j \lambda^2 \cdot -H \left( \frac{\Pr(\sigma_j | x)}{\lambda^2} \right) \\
& \geq \sum_j \lambda^2 \cdot (-1) \\
& = -N \lambda^2,
\end{align*}
\]

where \( H(\cdot) \) is the binary entropy function. So:

\[
\sum_{x \in A_{\epsilon}} \Pr(x) \sum_j \Pr(\sigma_j | x) \log_2 \left( \frac{\Pr(\sigma_j | x)}{f(x, \sigma_j) \lambda^2} \right)
\geq \Pr(A_{\epsilon}) \cdot -N \lambda^2 > -\epsilon N \lambda^2.
\]
Also, if we let $S^- \equiv S/\{\sigma_{\max,x}\}$, then for any $x \in A_e$:

$$
\sum_j \Pr(\sigma_j|x) \log_2 \left( \frac{\Pr(\sigma_j|x)}{f(x,\sigma_j)\lambda^2} \right) \\
= \Pr(\sigma_{\max,x}|x) \log_2 \left( \frac{\Pr(\sigma_{\max,x}|x)}{f(x,\sigma_{\max,x})\lambda^2} \right) \\
+ \sum_{\sigma_j \in S^-} \Pr(\sigma_j|x) \log_2 \left( \frac{\Pr(\sigma_j|x)}{f(x,\sigma_j)\lambda^2} \right) \\
\geq \frac{1}{N} 2N^2\lambda^2 + \sum_{\sigma_j \in S^-} \Pr(\sigma_j|x) \log_2 \left( \frac{\Pr(\sigma_j|x)}{f(x,\sigma_j)\lambda^2} \right) \\
\geq \frac{1}{N} 2N^2\lambda^2 + \sum_{\sigma_j \in S^-} \lambda^2 \left[ \frac{\Pr(\sigma_j|x)}{\lambda^2} \log_2 \left( \frac{\Pr(\sigma_j|x)}{\lambda^2} \right) \right] \\
\geq 2N\lambda^2 + \sum_{\sigma_j \in S^-} \lambda^2 \cdot -H \left( \frac{\Pr(\sigma_j|x)}{\lambda^2} \right) \\
\geq 2N\lambda^2 - N\lambda^2 \\
= N\lambda^2 .
$$

And, hence:

$$
\sum_{x \in A_e} \Pr(x) \sum_j \Pr(\sigma_j|x) \log_2 \left( \frac{\Pr(\sigma_j|x)}{f(x,\sigma_j)\lambda^2} \right) \\
\geq \Pr(A_e) \cdot N\lambda^2 \\
> (1-\epsilon)N\lambda^2 .
$$

Combining Eqs. (13), (14), and (15), we see that:

$$
E \left\{ \log_2 \left( \frac{\Pr(X_0|S_0)}{g(X_0,S_0)} \right) \right\} > (1-2\epsilon)N\lambda^2 \equiv C' ,
$$

where $C' > 0$ for $\epsilon < 1/2$. Since $M$ is not exactly synchronizable, we know $g(x,\sigma_j)$ is always strictly positive, so this expectation must be finite. Hence, there exists some real number $C > C' > 0$ such that:

$$
E \left\{ \log_2 \left( \frac{\Pr(X_0|S_0)}{g(X_0,S_0)} \right) \right\} = C .
$$

**Remark.** In the above proof we implicitly assumed $\Pr(x,\sigma_j) \neq 0$ for all $x$ and $j$. The sums for the expectation are, of course, computed only over those $x$ and $j$ for which $\Pr(x,\sigma_j) \neq 0$. Terms involving pairs $(x,\sigma_j)$ with $\Pr(x,\sigma_j) = 0$ should be omitted.

**Lemma 5.** For any nonexact $\epsilon$-machine $M$, there exists some $n \in \mathbb{N}$ such that the power machine $M^n$ is an $\epsilon$-machine with

$$
E \left\{ \log_2 \left( \frac{\Pr(Y_0|R_0)}{g(Y_0,R_0)} \right) \right\} > 0 ,
$$

where $Y_L$ is the RV for the the $L_{th}$ output symbol generated by the machine $M^n$ and $R_L$ is the RV for the $L_{th}$ $M^n$-state.

We also denote the alphabet of $M^n$ as $B$ and the set $A_e$ for the machine $M^n$ as $B_e$; i.e., $B_e \sim A_{\epsilon,n}$ for $M$. We define $\mathcal{P}(\phi)$ to be the most likely state in a distribution $\phi$ over the machine states, and $\Pr(\mathcal{P}(\phi))$ to be the probability of this state in the distribution $\phi$. For example, if $\phi = (0.3,0.1,0.2,0.4)$, then $\mathcal{P}(\phi) = 4$ and $\Pr(\mathcal{P}(\phi)) = 0.4$.

**Proof.** Given any nonexact $\epsilon$-machine $M$,

1. Take $\tau = 1/\left( N\lambda^2 2^{2N^2\lambda^2} \right)$.
2. Take $\epsilon$ small enough that $\Pr(\mathcal{P}(\phi)) > 1 - \tau$ for any state distribution $\phi$ with $H(\phi) < \epsilon$. (Without loss of generality, we may assume $\epsilon < 1/2$.)
3. For $\epsilon$ as above, take $n$ relatively prime to the period $p$ of $M$’s graph and large enough such that $\Pr(A_{\epsilon,n}) > 1 - \epsilon$. (Note that this is possible since $\lim_{L \to \infty} \Pr(A_{\epsilon,n}) = 1$, for all $\epsilon > 0$, since $\lim_{L \to \infty} U(L) = 0$.)

Then, $M^n$ is an $\epsilon$-machine for the process $\mathcal{P}^n$ and $\Pr(B_e) = \Pr(A_{\epsilon,n}) > 1 - \epsilon$. Moreover, for all $y \in B_e$ we have:

$$
H[\phi(y)] < \epsilon \quad \text{(a)} \quad \Pr(\mathcal{P}(\phi(y))) > 1 - \tau \\
\implies f(y,\sigma_{\max,y}) < \tau \\
\implies \Pr(\sigma_{\max,y}|y) \geq 1/N \\
\implies \mathcal{P}(\sigma_{\max,y}) \geq \lambda^2 2^{2N^2\lambda^2} \\
\implies \Pr(\sigma_{\max,y}|y) \geq \phi(y,\sigma_{\max,y}) \lambda^2 > 2^{2N^2\lambda^2} ,
$$

where step (a) follows from item 2 above and step (b) follows from our choice of $\tau$. Hence, by Lemma 4

$$
E \left\{ \log_2 \left( \frac{\Pr(Y_0|R_0)}{g(Y_0,R_0)} \right) \right\} = C > 0 .
$$

(Note that $\lambda$ for $M$ is the same as $\lambda$ for $M^n$, since $M$ and $M^n$ have the same stationary distribution $\pi$.)

Finally, in order to convert between $U_L$ and $Q_L$ convergence in our theorem we need one last lemma.

**Lemma 6.** For any $\Phi_L$:

1. If $Q_L \leq 1/2$, then $U_L \geq Q_L$.
2. If $Q_L > 1/2$, then $U_L \geq H(1/N)$, where $H(\cdot)$ is the binary entropy function.

**Proof.** Note that:

$$
U_L = H[\Phi_L] \\
\geq H([1 - Q_L, Q_L, 0, \ldots, 0]) \\
= H(Q_L) .
$$
Since $H(Q_L) \geq Q_L \log_2(1/Q_L)$, we know $H(Q_L) \geq Q_L$ for $Q_L \leq 1/2$. Since $H(Q_L)$ is monotonically decreasing on $[\frac{1}{2}, 1 - 1/N]$ and $Q_L$ is at most $1 - 1/N$, we know $H(Q_L) \geq H(1 - 1/N) = H(1/N)$ for $Q_L > 1/2$. □

Using these lemmas we can now prove the primary result of this section.

**Proof.** (Nonexact Machine Synchronization Theorem) We first prove Claim 2 of the theorem and then use this to show Claim 1.

**Proof of Claim 2:** Given any nonexact $\epsilon$-machine $M$, take a power machine $M^n$ as in Lemma 5 such that:

$$E \left\{ \log_2 \left( \frac{Pr(Y_0|R_0)}{g(Y_0, R_0)} \right) \right\} = C > 0.$$ 

Denote the random variable $U_L$ for the machine $M^n$ as $V_L$ and the quantity $U(L)$ for the machine $M^n$ as $V(L)$. By Lemma 2 we know there exist constants $B_1 > 0$ and $0 < \eta_1 < 1$ such that:

$$Pr(V_L > \eta_1 L) \leq B_1 \eta_1^L,$$ 

for all $L \in \mathbb{N}$.

A proof identical to that of Prop. 3 below then shows there exists some $B_2 > B_1$ such that:

$$V(L) \leq B_2 \eta_1^L,$$ 

for all $L \in \mathbb{N}$.

Or, equivalently:

$$U(nL) \leq B_2 \eta_1^L,$$ 

for all $L \in \mathbb{N}$.

Taking $\eta_2 = \eta_1^{1/n}$ we have:

$$U(m) \leq B_2 \eta_2^m,$$ 

for any length $m$ that is an integer multiple of $n$. Since $U(m) \leq \log_2(N)$ for any $m$ and is monotonically decreasing, it follows that:

$$U(m) \leq K \eta_2^m,$$ 

for all $m \in \mathbb{N}$,

where $K \equiv \max\{B_2, \log_2(N)/\eta_2^2\}$. Thus, by Markov’s inequality, we know that for any $m \in \mathbb{N}$ and $t > 0$:

$$\Pr(U_m > t) \leq \frac{\mathbb{E}U_m}{t} = \frac{U(m)}{t} \leq \frac{K \eta_2^m}{t}.$$ 

Taking $t = \eta_2^{m/2}$ yields:

$$\Pr(U_m > \alpha^m) \leq K \alpha^m,$$ 

where $\alpha \equiv \eta_2^{1/2}$.

**Proof of Claim 1:** By Claim 2 we know there exist constants $K > 0$ and $0 < \alpha < 1$ such that:

$$\Pr(U_L > \alpha^L) \leq K \alpha^L,$$ 

for all $L \in \mathbb{N}$.

Take $L_0$ large enough that $\alpha^{L_0} < H(1/N)$. Then, for all $L \geq L_0$ we have:

$$\Pr(Q_L > \alpha^L) = \Pr(\alpha^L < Q_L \leq 1/2) + \Pr(Q_L > 1/2) \leq \Pr(U_L > \alpha^L, Q_L \leq 1/2) + \Pr(U_L > H(1/N)) \leq \Pr(U_L > \alpha^L) + \Pr(U_L > \alpha^L) \leq 2K \alpha^L,$$

where step (*) follows from Lemma 6. Hence, for some $K \geq 2K$ we have:

$$\Pr(Q_L > \alpha^L) \leq K \alpha^L,$$ 

for all $L \in \mathbb{N}$.

□

**VII. CONSEQUENCES**

As a direct consequence of Thm. 4 we establish exponential convergence results for $U(L)$ and $h_{\mu}(L)$ analogous to those in the exact case [1]. We also use Thm. 1 to prove the existence of pointwise almost everywhere (a.e.) exponential synchronization for nonexact machines. This establishes that any $\epsilon$-machine is indeed asymptotically synchronizable in the pointwise sense of Def. 8.

**A. Exponential Convergence of $U(L)$**

**Proposition 3.** For any nonexact $\epsilon$-machine $M$ there exist constants $K > 0$ and $0 < \alpha < 1$ such that:

$$U(L) \leq K \alpha^L,$$ 

for all $L \in \mathbb{N}$.

**Proof.** Let $M$ be any nonexact $\epsilon$-machine. Then by Thm. 6 there exist constants $C > 0$ and $0 < \alpha < 1$ such that $Pr(U_L > \alpha^L) \leq C \alpha^L$, for all $L \in \mathbb{N}$. Define:

$$A_L = \{w \in \mathcal{L}_L(M) : u(w) \leq \alpha^L\}$$ 

and

$$A'_L = \mathcal{L}_L(M)/A_L.$$

Then,

$$U(L) = \sum_{w \in \mathcal{L}_L(M)} \Pr(w)u(w) = \sum_{w \in A_L} \Pr(w)u(w) + \sum_{w \in A'_L} \Pr(w)u(w) \leq \Pr(A_L) \cdot \alpha^L + \Pr(A'_L) \cdot \log_2(N) \leq 1 \cdot \alpha^L + C \alpha^L \cdot \log_2(N) = K \alpha^L,$$

where $K \equiv 1 + C \log_2(N)$. □

**B. Exponential Convergence of $h_{\mu}(L)$**

**Proposition 4.** For any nonexact $\epsilon$-machine $M$, there exist constants $K > 0$ and $0 < \alpha < 1$ such that:

$$h_{\mu}(L) - h_{\mu} \leq K \alpha^L,$$ 

for all $L \in \mathbb{N}$. [1]
Equating the RHS of Eqs. (17) and (18) gives:

\[
\text{Proof. This follows directly from Prop. } \text{[3]} \text{ and Lemma } \text{[7]} \text{ below.}
\]

**Lemma 7.** For any \( \epsilon \)-machine \( M \) and any \( L \in \mathbb{N} \):

\[
h_\mu(L + 1) - h_\mu \leq \mathcal{U}(L) .
\]  

**Proof.** Note that:

\[
H[\overrightarrow{X}_L, X_L, S_L] = H[\overrightarrow{X}_L] + H[S_L|\overrightarrow{X}_L] + H[X_L|\overrightarrow{X}_L, S_L]
\]

\[
= H[\overrightarrow{X}_L] + H[S_L|\overrightarrow{X}_L] + H[X_L|S_L]
\]

\[
= H[\overrightarrow{X}_L] + H[S_L|\overrightarrow{X}_L] + h_\mu ,
\]

and also that:

\[
H[\overrightarrow{X}_L, X_L, S_L] = H[\overrightarrow{X}_L] + H[X_L|\overrightarrow{X}_L]
\]

\[
+ H[S_L|\overrightarrow{X}_L, X_L] .
\]

Equating the RHS of Eqs. (17) and (18) gives:

\[
H[S_L|\overrightarrow{X}_L] + h_\mu = H[X_L|\overrightarrow{X}_L] + H[S_L|\overrightarrow{X}_L, X_L]
\]

\[
\geq H[X_L|\overrightarrow{X}_L] .
\]

Or, in other words:

\[
\mathcal{U}(L) + h_\mu \geq h_\mu(L + 1) .
\]

**Remark.** If we define the synchronization and predication decay constants, respectively, as:

\[
\alpha_s = \limsup_{L \to \infty} \mathcal{U}(L)^{1/L}
\]

\[
\alpha_p = \limsup_{L \to \infty} (h_\mu(L) - h_\mu)^{1/L}
\]

then Lemma [7] also implies that \( \alpha_p \leq \alpha_s \). This is to say, the observer’s predictions approach their optimal level at least as fast as the observer synchronizes. Since Lemma [7] applies to any \( \epsilon \)-machine, this statement also holds for any \( \epsilon \)-machine (exact or nonexact).

**C. Pointwise a.e. Asymptotic Synchronization**

**Proposition 5.** For any nonextreme \( \epsilon \)-machine \( M \) there exists some \( 0 < \alpha < 1 \) such that for a.e. \( \vec{x} \in \mathcal{L}_\infty(M) \), there exists \( L_0 \in \mathbb{N} \) such that for all \( L \geq L_0 \),

\[
u(\vec{x}^L) \leq \alpha^L .
\]

**Proof.** Apply the Borel-Cantelli Lemma to Thm. [1].

**VIII. CONCLUSION**

We analyzed the process of asymptotic synchronization to nonextreme \( \epsilon \)-machines. Although the treatment is more involved mathematically, the primary results are essentially the same as those for the exact case given in Ref. [1]. An observer’s average state uncertainty \( \mathcal{U}(L) \) vanishes exponentially fast and, consequently, an observer’s average uncertainty in predictions \( h_\mu(L) \) converges to the machine’s entropy rate \( h_\mu \) exponentially fast, as well.

We hope to extend the asymptotic synchronization results to more general model classes such as countable-state \( \epsilon \)-machines or nonunifilar HMMs. We also intend to improve the bounds on the constant \( \alpha \) given in the convergence theorems.

**Acknowledgments**

NT was partially supported by an NSF VIGRE fellowship. This work was partially supported by the Defense Advanced Research Projects Agency (DARPA) Physical Intelligence project via subcontract No. 9060-000709. The views, opinions, and findings contained here are those of the authors and should not be interpreted as representing the official views or policies, either expressed or implied, of the DARPA or the Department of Defense.

[1] N. Travers and J. P. Crutchfield. Exact synchronization for finite-state sources. 2010. Santa Fe Institute Working Paper 10-11-031; arxiv.org:1008.4182 [nlin.CD].
[2] J. P. Crutchfield and D. P. Feldman. Regularities unseen, randomness observed: Levels of entropy convergence. CHAOS, 13(1):25-54, 2003; C. J. Ellison, J. R. Mahoney, and J. P. Crutchfield. Prediction, Retrodiction, and the Amount of Information Stored in the Present. J. Stat. Phys. 136(6):1005–1034, 2009; J. R. Mahoney, C. J. Ellison, and J. P. Crutchfield. Information Accessibility and Cryptic Processes. J. Phys. A: Math. Theo. 42:362002, 2009.
[3] J. P. Crutchfield and K. Young. Inferring statistical complexity. Phys. Rev. Let., 63:105–108, 1989.
[4] T. M. Cover and J. A. Thomas. Elements of Information Theory. Wiley-Interscience, New York, second edition, 2006.
[5] C. E. Shannon and W. Weaver. The Mathematical Theory of Communication. University of Illinois Press, Champaign-Urbana, 1962.
[6] J. L. Massey. Markov information sources. In J. K. Skwirzyński, editor, New Directions in Signal Processing in Communication and Control, volume E25 of NATO Advanced Study Institutes Series, pages 15–26. Noordhoff, Leydon, The Netherlands, 1975.
[7] P. W. Glynn and D. O’Rourke. Hoeffding’s inequality for uniformly ergodic Markov chains. Stat. Prob. Lett., 56(2):143–146, 2002.