A semi-analytical method to solve family of Kuramoto–Sivashinsky equations

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ABSTRACT

In this article, a semi-analytical technique is implemented to solve Kuramoto–Sivashinsky equations. The present method is the combination of two well-known methods namely Laplace transform method and variational iteration method. This hybrid property of the proposed method reduces the numbers of calculations and materials. The accuracy and applicability of the suggested method is confirmed through illustration examples. The accuracy of the proposed method is described in terms of absolute error. It is investigated through graphs and tables that the Laplace transformation and variational iteration method (LVIM) solutions are in good agreement with the exact solution of the problems. The LVIM solutions are also obtained at different fractional-order of the derivative. It is observed through graphs and tables that the fractional-order solutions are convergent to an integer solution as fractional-orders approaches to an integer-order of the problems. In conclusion, the overall implementation of the present method support the validity of the suggested method. Due to simple, straightforward and accurate implementation, the present method can be extended to other non-linear partial fractional differential equations.

1. Introduction

Over recent years, the theory of fractional calculus (FC) has drawn global attention to its implementations over complex systems. According to the fractional derivative principles, the simulation of significant-world problems containing fractional-order derivatives provides better predictability compared to modelling involving integer-order derivatives. FC defines the background and non-local dispersed effects of any physical system, in specific phenomenon related to the analysis of chaos in wave motion, solitary waves, phase turbulence in reaction–diffusion schemes [1–4], wrinkled flame front propagation [5], chaotic drifting waves induced by photon collision [6], time fractional-coupled mKdV equation [7–9], fractional-order wave equations [10] and fractional space–time diffusion equation [11–13].

In 1977, Gregory I. Sivashinsky measured a scenario for such a laminar flaming front. An other researcher, Yoshiki Kuramoto, created a certain problem when simultaneously designing diffusion-induced chaotic in a three-dimensional experiment of the Belousov–Zabotinskii transformation [4,14–16]. Their combined result is named the Kuramoto–Sivashinsky (KS) model. This system defines the changes in that burning front orientation, the motion of the liquid down a circular surface and a dynamically particular oscillating chemical compound in a homogeneous fluid [17–19]. It introduces chaotic behaviour, requiring a result such as moving waves travelling to a finite space domain without altering size. That has a variety of implementations in a range of conceptual ideas, along with response diffusion systems [20], thin film hydrodynamics [21] and front burn instability [22], long waves on functionality among a couple viscous fluids [23].

As stated in [24], the generalized KS equation is a form of non-linear partial differential equations (PDEs) naturally found in the research of fluid materials that displays a chaotic type of conduct.

\[
\frac{\partial^\mu \mu}{\partial t^\mu} + \mu \frac{\partial \mu}{\partial x} + \eta \frac{\partial^2 \mu}{\partial x^2} + \theta \frac{\partial^3 \mu}{\partial x^3} + \omega \frac{\partial^4 \mu}{\partial x^4} = 0, \tag{1}
\]

where \(\eta, \theta\) and \(\omega\) are non-zero constants.

For \(\theta = 0\), Equation (1) is named the KS model, a canon non-linear reproduction equation that arises in a multitude of physical situations. For \(\eta = \omega = 1\) and \(\theta = 0\), it denotes pattern structure designs on unbalanced flame fronts and thin hydrodynamic movies, Equation (1) has been researched extensively [25,26].

In past decade, multiple types of mathematical systems have been produced for the numerical methods...
of time dependent PDEs [27]. The KSE has been studied by different methods, such as, homotopy analysis method [28], Runge-Kutta method [29], finite difference scheme [30], B-spline functions [31], mesh-free numerical method [32], Reduced differential transform method [33], Lattice Boltzmann method [34], Quasi-exact KS equation solutions [35], Sub-equation Method [36] and modified tanh–coth method [37].

A Lagrange multiplier method has been commonly used to solve a variety of non-linear equations [38]. This occurs in physics and mathematics or other related areas but has been developed as a basic analytical technique, i.e. a variational iteration method (VIM) for modelling differential equations [39]. The VIM was first suggested by He [40] and was effectively implemented in dealing with heat transform problems [40–42]. The fractional variational iteration technique (FVIM) was developed via modified Riemann–Liouville derivative in 2010 [43]. Recently, a procedure combined in this sense VIM and Laplace transform was proposed [44,45] and Wu developed a modification via FC and VIM and Laplace transform technique was proposed in 2010 [43]. Recently, a procedure combined in this sense VIM and Laplace transform was proposed [44,45] and Wu developed a modification via FC and VIM and Laplace transform technique was proposed [43].

In the present research work, we implemented a hybrid technique for the solution of family of fractional-order Kuramoto–Sivashinsky equations. The present technique is the combination of two well-known methods namely LVIM is discussed in Section 3 of the paper. The convergence analysis of the suggested method is discussed in Theorem 5.1 of the manuscript. For the purpose of the validity of the current method, some illustrative examples are presented. The graphical representations of Examples 6.1, 6.2 and 6.3 in the paper have shown close contact of LVIM solution with the exact solutions of the problems. Moreover, the LVIM solutions are calculated at different fractional-order of the targeted problems. It is investigated that the fractional-order solutions are converged to an integer-order solutions for the problem as fractional-orders approaches to an integer-order. The accuracy of the proposed methods analysed with the help of Tables 1–3 in terms absolute error (AE). From the table, it is clear that LVIM has the desired degree of accuracy. The overall, discussion and numerical implementation of the current method have suggested extending that it can be extended easily to solve other fractional-order differential equations.

2. Preliminaries and definitions

2.1. Definition

Laplace transformation of \( \tilde{\rho}(t) \), \( t > 0 \) represented as [51,52]

\[
Q(s) = \mathcal{L}[\tilde{\rho}(t)] = \int_0^\infty e^{-st} \tilde{\rho}(t) \, dt.
\]  

2.2. Definition

The Laplace transforms in forms of convolution

\[
\mathcal{L}[\tilde{\rho}_1 \ast \tilde{\rho}_2] = \mathcal{L}[\tilde{\rho}(t)] = \mathcal{L}[\tilde{\rho}_1(t)] \ast \mathcal{L}[\tilde{\rho}_2(t)],
\]

here \( \tilde{\rho}_1 \ast \tilde{\rho}_2 \), define the convolution between \( \tilde{\rho}_1 \) and \( \tilde{\rho}_2 \),

\[
(\tilde{\rho}_1 \ast \tilde{\rho}_2)t = \int_0^t \tilde{\rho}_1(r)\tilde{\rho}_2(t-r) \, dt.
\]

Laplace transform is a fractional derivative

\[
\mathcal{L} \left( D_\kappa^\kappa \tilde{\rho}(t) \right) = s^\kappa \mathcal{L}(\tilde{\rho}(s)) - \left( \sum_{k=1}^{n-1} \frac{n-k}{k} s^{n-k-1} \tilde{\rho}^{(k)}(0) \right) \times n - 1 < \kappa < n,
\]

where \( \mathcal{L}(\tilde{\rho}(s)) \) is the Laplace transformation of \( \tilde{\rho}(t) \).

2.3. Definition

Riemann–Liouville fractional integral [53,54]

\[
_0^\kappa \mathcal{I}_\kappa g(x) = \begin{cases} 
  g(x) & \text{if } \kappa = 0 \\
  \frac{1}{\Gamma(\kappa)} \int_0^x (x - \kappa)^{\kappa-1} g(\kappa) \, d\kappa & \text{if } \kappa > 0,
\end{cases}
\]

where \( \Gamma \) represent the gamma function as,

\[
\Gamma(\kappa) = \int_0^\infty e^{-x} x^{\kappa-1} \, dx, \quad \kappa \in \mathbb{C},
\]

2.4. Definition

The following mathematical expression is given to the Caputo of fractional derivative of order \( \kappa \) for \( \bar{m} \in \mathbb{N}, \ k \in \mathbb{C} \), \( t \geq -1 \).

\[
D^\kappa g(x) = \frac{\partial^\kappa g(x)}{\partial x^\kappa} = \begin{cases} 
  \rho^{\kappa-1} \left[ \frac{\partial^{\kappa} g(x)}{\partial x^\kappa} \right] & \text{if } \bar{m} - 1 < \kappa \leq \bar{m}, \bar{m} \in \mathbb{N} \\
  \frac{\partial^\kappa g(x)}{\partial x^\kappa} & \text{if } \bar{m} = \kappa \leq \bar{m}, \bar{m} \in \mathbb{N}
\end{cases}
\]

2.5. Lemma

If \( \bar{m} - 1 < \kappa \leq \bar{m} \) with \( \bar{m} \in \mathbb{N} \) and \( g \in \mathbb{C} \) with \( t \geq -1 \), then [55]

\[
_0^\kappa \mathcal{I}_\kappa g(x) = \frac{\mathcal{I}_\kappa g(x)}{\kappa}, \quad a, \kappa \geq 0.
\]

\[
_0^\kappa \mathcal{I}_\kappa x^\lambda = \frac{\Gamma(\lambda + 1)}{\Gamma(\kappa + \lambda + 1)} x^{\kappa + \lambda},
\]

\[
\times \kappa > 0, \lambda > 1, \ x > 0.
\]

\[
_0^\kappa D^\kappa g(x) = g(x) - \sum_{k=0}^{\bar{m}-1} g^{(k)}(0^+) \frac{x^k}{k!},
\]

\[
\times \text{for } x > 0, \bar{m} - 1 < \kappa \leq \bar{m}.
\]
The basic character of the technique is to construct an iteration formula for the solution of algebraic equation. In the case of an algebraic equation, let us revisit the equation
\[ \lambda(t, \tau) = \sum_{m=0}^{\infty} \frac{b^m}{\Gamma(\kappa m + 1)}, \quad \kappa > 0, \quad b \in \mathbb{C}, \] (10)

### 3. Basics of the VIM

In order to explain the basic knowledge of the method, consider the following common non-linear scheme:

\[ \frac{\partial^\kappa \mu}{\partial t^\kappa} + \mathcal{R}(\mu) + \mathcal{N}(\mu) = \mathcal{P}(t), \] (11)

where \( \mu = \mu(t) \), \( \mathcal{R} \) is a linear operator, \( \mathcal{N} \) is a non-linear operator and \( \mathcal{P} \) is a given continuous function.

The basic character of the technique is to construct the following correction well-designed for Equation (11):

\[ \mu_{m+1} = \mu_m + \int_0^t \lambda(t, \tau) \left( \frac{\partial^\kappa \mu}{\partial \tau^\kappa} + \mathcal{R}(\mu_m) + \mathcal{N}(\mu_m) - \mathcal{P}(t) \right) d\tau, \] (12)

where \( \lambda(t, \tau) \) is called the general Lagrange multiplier and \( \mu_m \) is the nth-order estimated solution.

### 4. The procedure of LVIM

In the case of an algebraic equation, let us revisit the original idea of the Lagrange multipliers. In the first place, an iteration formula for the solution of algebraic equation \( g(x) = 0 \) can be constructed as

\[ \chi_{m+1} = \chi_m + \lambda g(\chi_m). \] (13)

The optimal situation for the maximum \( \kappa \chi_{m+1} \) leads to

\[ \lambda = -\frac{1}{g'(\chi_m)}, \] (14)

In which \( \kappa \) is a classic variational operator. From (13) and (14), we can discover the estimated method \( \chi_{m+1} \) by the iterative system for (14) for a specified original value \( \chi_m \).

\[ \chi_{m+1} = \chi_m - \frac{g(\chi_m)}{g'(\chi_m)}, \quad g'(\chi_0) \neq 0, \quad m = 0, 1, 2, \ldots \] (15)

Now they expand its concept to find the unidentified Lagrange multiplier. The primary stage is to bring the
Laplace transformation to Equation (13) first. Therefore, the linear portion is converted into an algebraic statement as given:

\[
\begin{align*}
\mathcal{L}[\mu(s) - \mu^{k-1}(0) - s^{k-1}\mu(0)] \\
\quad \times + s \left[ \mathcal{L}(\mu) + \mathcal{N}(\mu) - \mathcal{P}(\mu) \right] = 0,
\end{align*}
\]

where \( \mu(s) = \mathcal{S}(\mu(t)) = \int_0^\infty e^{-st}\mu(t) \, dt \).

The iteration algorithm (16) is used to recommend the key iterative system that includes a Lagrange multiplier as

\[
\mu_{m+1}(s) = \mu_m(s) + \lambda(s)[s^k\mu(s) - \mu^{k-1}(0) - s^{k-1}\mu(0)] + s \left[ \mathcal{L}(\mu) + \mathcal{N}(\mu) - \mathcal{P}(\mu) \right].
\]

Considered \( \mathcal{S}[\mathcal{L}(\mu) + \mathcal{N}(\mu)] \) as limited conditions, a Lagrange calculation can be derived as

\[
\lambda(s) = -\frac{1}{s^k}.
\]

Because of Equation (18) and the inverse Laplace transformation \( S^{-1} \), iteration method (5) can also be expressively stated as

\[
\mu_{m+1}(t) = \mu_m(t) - S^{-1} \left[ \frac{1}{s^k} \{ s^k \mu(s) - \mu^{k-1}(0) \} \\
- s^{k-1}\mu(0) + s \left[ \mathcal{L}(\mu) + \mathcal{N}(\mu) - \mathcal{P}(\mu) \right] \right].
\]

The Laplace solution for equation (19) represents the general iterative formula for the target problem.

5. Convergence analysis

Theorem 5.1: Let \( \mathcal{X} \) and \( \mathcal{Y} \) be two Banach spaces and \( T : \mathcal{X} \rightarrow \mathcal{Y} \) be a contractive non-linear operator, such that for all \( u; u^* \in \mathcal{X} \), \( ||T(u) - T(u^*)|| \leq K||u - u^*|| \), \( 0 < K < 1 \) [56].

Then, in view of Banach contraction theorem, \( T \) has a unique fixed point \( u \), such that \( Tu = u \) : Let us write the generated series (19), by the Laplace variational iteration method as

\[
\chi_m = T(\chi_{m-1}), \quad \chi_{m-1} = \sum_{j=1}^{m-1} u_j, \quad j = 0, 1, 2, \ldots
\]

and supposed that \( \chi_0 = u_0 \in \mathcal{S}_p(u) \), where \( \mathcal{S}_p(u) = \{ u^* \in \mathcal{X} : ||u - u^*|| < p \} \) then, we have

\[
\begin{align*}
(\mathcal{B}_1) & \quad \chi_m \in \mathcal{S}_p(u) \\
(\mathcal{B}_2) & \quad \lim_{m \to \infty} \chi_n = u.
\end{align*}
\]

Proof: (B1) In view of mathematical induction for \( m = 1 \), we have

\[
||\chi_1 - u|| = ||T(\chi_0 - T(u))|| \leq K||u_0 - u||.
\]

Let the result be true for \( m-1 \), then

\[
||\chi_{m-1} - u|| \leq K||\chi_{m-1} - u|| \leq K^m||u_0 - u||.
\]

We have

\[
||\chi_m - u|| = ||T(\chi_{m-1} - T(u))|| \leq K||\chi_{m-1} - u|| \leq K^m||u_0 - u||.
\]

Hence, using (B1), we have

\[
||\chi_m - u|| \leq K^m||u_0 - u|| \leq K^m p < p,
\]

which implies that \( \chi_m \in \mathcal{S}_p(u) \). (B2): Since \( ||\chi_m - u|| \leq K^m||u_0 - u|| \) and as \( \lim_{m \to \infty} K^m = 0 \).

Therefore, we have \( \lim_{m \to \infty} ||u_n - u|| = 0 \Rightarrow \lim_{m \to \infty} u_n = u \).

6. Numerical examples

Example 6.1: In this instance, we discover the equation \( KS \) as described by \( \eta = \theta = 1 \) and \( \omega = 4 [31,32,50] \).

\[
\frac{\partial^3 \mu}{\partial x^3} + \mu \frac{\partial \mu}{\partial x} + \mu \frac{\partial^2 \mu}{\partial x^2} + \theta \frac{\partial^3 \mu}{\partial x^3} + \omega \frac{\partial^4 \mu}{\partial x^4} = 0,
\]

with initial condition

\[
\mu_0(x, 0) = 11 + 15 \tan \left( \frac{-1}{2} x \right) - 15 \tanh^2 \left( \frac{-1}{2} x \right)
\]

\[
- 15 \tanh^3 \left( \frac{-1}{2} x \right).
\]

Using LVIM on both sides equation (20), we get

\[
\begin{align*}
\mu_{m+1}(x, t) &= S^{-1} \left[ \frac{u_m(x, t)}{s} \right] \\
&\quad + S^{-1} \left[ \lambda(s) \left\{ s^2 \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right\} \\
&\quad + \eta \frac{\partial^2 \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} + \omega \frac{\partial^4 \mu_m}{\partial x^4} \right],
\end{align*}
\]

where \( \lambda(s) \) is the Lagrange multiplier

\[
\lambda(s) = -\frac{1}{s^k},
\]

\[
\mu_{m+1}(x, t) = u_m(x, t) - S^{-1} \left[ \frac{1}{s^k} \left\{ s^2 \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right\} \\
&\quad + \eta \frac{\partial^2 \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} + \omega \frac{\partial^4 \mu_m}{\partial x^4} \right].
\]

Now take,

\[
\mu_0(x, t) = 11 + 15 \tan \left( \frac{-1}{2} x \right) - 15 \tanh^2 \left( \frac{-1}{2} x \right)
\]
\[-15 \tanh^3 \left( \frac{-1}{2} x \right),\]

consequently, we get,

\[
\mu_1(x, t) = u_0(x, t) - \frac{1}{s^e} \left[ \frac{1}{s^e} \left( \frac{\partial \mu_0}{\partial s} + \mu_0 \frac{\partial \mu_0}{\partial x} \right) + \eta \frac{\partial^2 \mu_0}{\partial x^2} + \theta \frac{\partial^3 \mu_0}{\partial x^3} + \omega \frac{\partial^4 \mu_0}{\partial x^4} \right],
\]

\[
\mu_1(x, t) = 11 + 15 \tanh \left( \frac{-1}{2} x \right) - 15 \tanh^2 \left( \frac{-1}{2} x \right)
\]

\[
-15 \tanh^3 \left( \frac{-1}{2} x \right).
\]

The exact result is

\[
\mu(x, t) = 11 + 15 \tanh \Phi - 15 \tanh^2 \Phi - 15 \tanh^3 \Phi,
\]

then \( \Phi = -\frac{1}{2} x + t \), on the interval \([-1, 1]\).

**Example 6.2:** The KS equation as defined by \( \eta = 2 = \theta = 1 \) and \( \omega = 0 \) [31, 32],

\[
\frac{\partial^e \mu}{\partial t^e} + \mu \frac{\partial \mu}{\partial x} + \eta \frac{\partial^2 \mu}{\partial x^2} + \theta \frac{\partial^3 \mu}{\partial x^3} + \omega \frac{\partial^4 \mu}{\partial x^4} = 0,
\]

with initial condition

\[
u_0(x, 0) = -\frac{\sqrt{418}}{11} - \frac{270}{361} \sqrt{418} \tanh \left( \frac{\sqrt{418}}{38} x \right)
\]

\[
+ \frac{330}{361} \sqrt{418} \tanh^3 \left( \frac{\sqrt{418}}{38} x \right),
\]

Using LVIM on both sides equation (24), we get

\[
\mu_{m+1}(x, t) = \frac{1}{s} \left[ \frac{\partial \mu_m(x, t)}{\partial s} \right],
\]

\[
\lambda(s) = \frac{1}{s^e},
\]

\[
\mu_{m+1}(x, t) = u_m(x, t) - \frac{1}{s^e} \left[ \frac{1}{s^e} \left( \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right) + \eta \frac{\partial^2 \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} + \omega \frac{\partial^4 \mu_m}{\partial x^4} \right],
\]

where \( \lambda(s) \) is the Lagrange multiplier

\[
\lambda(s) = \frac{1}{s^e},
\]

\[
\mu_{m+1}(x, t) = u_m(x, t) - \frac{1}{s^e} \left[ \frac{1}{s^e} \left( \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right) + \eta \frac{\partial^2 \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} + \omega \frac{\partial^4 \mu_m}{\partial x^4} \right] .
\]

Now take,

\[
\mu_0(x, 0) = -\frac{\sqrt{418}}{11} - \frac{270}{361} \sqrt{418} \tanh \left( \frac{\sqrt{418}}{38} x \right)
\]

\[
+ \frac{330}{361} \sqrt{418} \tanh^3 \left( \frac{\sqrt{418}}{38} x \right),
\]

consequently, we get,

\[
\mu_1(x, t) = \mu_0(x, t) - \frac{1}{s^e} \left[ \frac{1}{s^e} \left( \frac{\partial \mu_0}{\partial s} + \mu_0 \frac{\partial \mu_0}{\partial x} \right) + \eta \frac{\partial^2 \mu_0}{\partial x^2} + \theta \frac{\partial^3 \mu_0}{\partial x^3} + \omega \frac{\partial^4 \mu_0}{\partial x^4} \right].
\]
Using LVIM on both sides equation (29), we get

\[ u_1(x, t) = -63536 \cosh^7 \left( \frac{\sqrt{18}}{38} x \right) \]

\[ + 73264 \sinh \left( \frac{\sqrt{18}}{38} x \right) \cosh^6 \left( \frac{\sqrt{18}}{38} x \right) \]

\[ \times \frac{t^2}{2476099 \cosh^9 \left( \frac{\sqrt{18}}{38} x \right) x! (2x + 1)^2}, \]

For \( m = 2, 3, \ldots \)

\[ \mu_{m+1}(x, t) = u_m(x, t) - s^{-1} \left[ \frac{1}{s} \left[ s^\nu \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right] + \eta \frac{\partial \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} \right] \],

The exact result is

\[ u(x, t) = -\frac{1}{\psi} + \frac{60}{19} \psi(-38\psi^2 + \eta) \tanh(\Phi) + 120\psi^3 \tanh^3(\Phi), \]

then \( \Phi = \psi x + t \) and \( \psi = 0.5 \sqrt{\frac{22}{79}} \). On the interval \([-1, 1]\) (Figures 1–3).

**Example 6.3:** Consider the KS equation as defined by \( \eta = 1 \theta = 0.5 \) and \( \omega = 0 [31,32] \).

\[ \frac{\partial^\nu \mu}{\partial t^\nu} + \mu \frac{\partial \mu}{\partial x} + \eta \frac{\partial^2 \mu}{\partial x^2} + \theta \frac{\partial^3 \mu}{\partial x^3} + \omega \frac{\partial^4 \mu}{\partial x^4} = 0, \]

with initial condition

\[ u_0(x, 0) = -0.1858640755 - 2.973310349 tanh \left( \frac{\sqrt{18}}{38} x \right), \]

Using LVIM on both sides equation (29), we get

\[ \mu_{m+1}(x, t) = s^{-1} \left[ \frac{u_m(x, t)}{s} \right] + s^{-1} \left[ \lambda(s) \left[ s^\nu \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right] + \eta \frac{\partial^2 \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} \right], \]
Figure 1. (a) The solution graph of exact and LVIM solution at $\kappa = 1$ of Example 6.1 and (b) the solution-graph of Example 6.1 at different fractional-order $\kappa$. (a) Graph of LVIM and exact solutions for $t = 0.1$ and $\kappa = 1$ for Example 6.1. (b) Graph of LVIM solutions for different value of $\kappa$ for Example 6.1.

Figure 2. (a) The solution graph of exact and LVIM solution at $\kappa = 1$ of Example 6.2 and (b) the solution-graph of Example 6.2 at different fractional-order $\kappa$. (a) Graph of LVIM and exact solutions for $t = 0.1$ and $\kappa = 1$ for Example 6.2. (b) Graph of LVIM solutions for different value of $\kappa$ for Example 6.2.

where $\lambda(s)$ is the Lagrange multiplier

$$
\lambda(s) = \frac{-1}{s^\kappa},
$$

$$
\mu_{m+1}(x, t) = u_m(x, t) - s^{-1} \left[ \frac{1}{s^\kappa} \left\{ s^\kappa \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right\} + \eta \frac{\partial^2 \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} \right].
$$

Now take,

$$
u_0(x, t) = -0.1858640755 - 2.973310349 \tanh \left( \frac{\sqrt{418}}{38} x \right) + 9.344689666 \tanh^3 \left( \frac{\sqrt{418}}{38} x \right)
$$

For $m = 0$

$$
\mu_1(x, t) = u_0(x, t) - s^{-1} \left[ \frac{1}{s^\kappa} \left\{ s^\kappa \frac{\partial \mu_0}{\partial s} + \mu_0 \frac{\partial \mu_0}{\partial x} \right\} + \eta \frac{\partial^2 \mu_0}{\partial x^2} + \theta \frac{\partial^3 \mu_0}{\partial x^3} \right],
$$

$$
u_1(x, t) = -0.1858640755 - 2.973310349 \tanh \left( \frac{\sqrt{418}}{38} x \right) + 9.344689666 \tanh^3 \left( \frac{\sqrt{418}}{38} x \right)
$$

For $m = 1$

$$
\mu_2(x, t) = u_1(x, t) - s^{-1} \left[ \frac{1}{s^\kappa} \left\{ s^\kappa \frac{\partial \mu_1}{\partial s} + \mu_1 \frac{\partial \mu_1}{\partial x} \right\} + \eta \frac{\partial^2 \mu_1}{\partial x^2} + \theta \frac{\partial^3 \mu_1}{\partial x^3} \right],
$$

$$
u_2(x, t) = -0.1858640755 - 2.973310349 \tanh \left( \frac{\sqrt{418}}{38} x \right) + 9.344689666 \tanh^3 \left( \frac{\sqrt{418}}{38} x \right)
$$
Figure 3. (a) The solution graph of exact and LVIM solution at $\kappa = 1$ of example 6.3 and (b) the solution-graph of example 6.3 at different fractional-order $\kappa$. (a) Graph of LVIM and exact solutions for $t = 0.1$ and $\kappa = 1$ for Example 6.3. (b) Graph of LVIM solutions for different value of $\kappa$ for Example 6.3. (c) Error plot of Example 6.3 for $\kappa = 1$.

The exact result is

$$u(x, t) = -\frac{0.5}{\varphi} + \frac{60}{19} \varphi \left( -38 \partial^2 \varphi^2 + \eta \right) \tanh(\Phi) + 120 \varphi^3 \tanh^3(\Phi),$$

For $m = 2, 3, \ldots$

$$\mu_{m+1}(x, t) = u_m(x, t) - s^{-1} \left[ \frac{1}{s} \left[ s^k \frac{\partial \mu_m}{\partial s} + \mu_m \frac{\partial \mu_m}{\partial x} \right] + \eta \frac{\partial^2 \mu_m}{\partial x^2} + \theta \frac{\partial^3 \mu_m}{\partial x^3} \right].$$

The exact result is

$$u(x, t) = -\frac{0.5}{\varphi} + \frac{60}{19} \varphi \left( -38 \partial^2 \varphi^2 + \eta \right) \tanh(\Phi) + 120 \varphi^3 \tanh^3(\Phi),$$

For $m = 2, 3, \ldots$
then \( \Phi = \varphi x + 0.1t \) and \( \psi = 0.5 \sqrt{11 \eta / 19 \nu} \), On the interval \([-1, 1] \).

### 7. Conclusion

In the current research work, an extended Laplace variational iteration method is applied to obtain analytical solution of fractional Kuramoto–Sivashinsky equations. The proposed method is a simple and effective tool to solve fractional PDEs because it uses the Lagrange multiplier directly to solve fractional PDEs.

In conclusion, the present method have the straight-forward implementation and small number of calculations and therefore can be implemented to other fractional-order PDE, that frequently arises in science and engineering.

Moreover, in future, the present method can be implemented to solve some important system of high non-linear fractional-order PDEs in applied science. In particular, the fractional-view analysis of some dynamical systems in economic, biology, physics, chemistry and engineering provide the best information about its physical, chemistry and engineering provide the best information about its physical behaviour. Therefore, in future, the proposed technique will be considered as an important tool to analyse and describe the fractional-order analysis of the important physical model.

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