Reliable Spanners for Metric Spaces

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A spanner is reliable if it can withstand large, catastrophic failures in the network. More precisely, any failure of some nodes can only cause a small damage in the remaining graph in terms of the dilation. In other words, the spanner property is maintained for almost all nodes in the residual graph. Constructions of reliable spanners of near linear size are known in the low-dimensional Euclidean settings. Here, we present new constructions of reliable spanners for planar graphs, trees, and (general) metric spaces.

CCS Concepts: • Theory of computation → Computational geometry; Random walks and Markov chains;

Additional Key Words and Phrases: Computational geometry, spanners, reliable

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1 INTRODUCTION

Let \( M = (P, d) \) be a finite metric space. Let \( G = (P, E) \) be a sparse graph on the points of \( M \) whose edges are weighted with the distances of their endpoints. The graph \( G \) is a \( t \)-spanner if for any pair of vertices \( u, v \in P \) we have \( d_G(u, v) \leq t \cdot d(u, v) \), where \( d_G(u, v) \) is the length of the shortest path between \( u \) and \( v \) in \( G \), and \( d(u, v) \) is the distance in the metric space between \( u \) and \( v \). Spanners were first introduced by Peleg and Schäffer [30] as a tool in distributed computing, but they have since found use in many other areas, such as algorithms, networking, data structures, and metric geometry; see References [28, 29].

**Fault tolerant spanners.** A desired property of spanners is the ability to withstand failures of some of their vertices. One such notion is provided by fault tolerance [14, 23, 24, 26, 32]. A graph \( G \) is a \( k \)-fault tolerant \( t \)-spanner, if for any subset of vertices \( B \), with \( |B| \leq k \), the graph \( G \setminus B \)
is a $t$-spanner. However, for $k$-fault tolerant graphs there is no guarantee if more than $k$ vertices fail, and furthermore, the size of a fault tolerant graph grows (linearly) with the parameter $k$. In particular, for fixed $t \geq 1$, the optimal size of $k$-fault tolerant $(2t - 1)$-spanners on $n$ vertices is $O(k^{1-1/t}n^{1+1/t})$ [8]. Note that vertex degrees must be at least $\Omega(k)$ to avoid the possibility of isolating a vertex. Thus, it is not suitable for massive failures in the network.

Reliable spanners. An alternative notion was introduced by Bose et al. [10]. Here, for a parameter $\vartheta > 0$, a $\vartheta$-reliable $t$-spanner has the property that for any failure (or attack) set $B$, the residual graph $G \setminus B$ is a $t$-spanner path for the points of $V \setminus B^+$, where $B^+ \supseteq B$ is some set, such that $|B^+| \leq (1 + \vartheta)|B|$. We consider two variants:

(A) Adaptive adversary (i.e., standard or “deterministic” model): The adversary knows the spanner $G$, and the set $B$ is chosen as a worst case for $G$.

(B) Oblivious adversary (i.e., “randomized” model): Here, the spanner $G$ is drawn from a probability distribution $\chi$ (over the same number of vertices). The adversary knows $\chi$ in advance, but not the sampled spanner. In this oblivious model, we require that $\mathbb{E}[|B^+|] \leq (1 + \vartheta)|B|$.

See Section 2 for precise definitions.

Previous work. Bose et al. [10] provided some lower bounds and constructions in the general settings, but the bounds on the size of the damaged set (i.e., $B^+$) are much larger. In the Euclidean settings, for any point set $P \subseteq \mathbb{R}^d$, and for any constants $\vartheta, \varepsilon \in (0, 1)$, one can construct a $\vartheta$-reliable $(1 + \varepsilon)$-spanner with only $O(n \log n \log \log n)$ edges [11] (an alternative, but slightly inferior construction, was provided independently by Bose et al. [9]). The number of edges can be further reduced in the oblivious adversary case, where one can construct an oblivious $(1 + \varepsilon)$-spanner that is $\vartheta$-reliable in expectation and has $O(n \log \log^2 n \log \log n)$ edges [12].

Covers. A cover is a set of clusters (i.e., subsets of the point set) that covers the metric space with certain desirable properties. Awerbuch and Peleg [5] showed a cover, where (i) each cluster has diameter $O(k)$, (ii) every vertex participates in $O(kn^{1/k})$ clusters, and (iii) for every vertex $v$, the ball of radius $k$ centered at $v$, is contained in a single cluster. Busch et al. [13] show how to compute a cover of a planar graph, with diameter $\leq 16k$ per cluster, such that each pair in distance $k$ from each other belongs to some cluster, and every vertex participates in at most 18 clusters. For graphs that excludes a minor of fixed size, they get a similar result, except that each vertex might participate in $O(\log n)$ vertices, where $n$ is the number of vertices in the input graph. Abraham et al. [3] presented a result with better sparsity when the graphs do not have $K_{r, r}$ as a minor.

OUR RESULTS

We provide new constructions of reliable spanners for finite uniform metrics, ultrametrics, trees, planar graphs, and finite metrics. Our new results are summarized in Table 1.

Technique. Our approach for constructing reliable spanners is in two steps: We first construct reliable spanners for uniform metrics and then reduce the problem of constructing reliable spanners for general metrics to uniform metrics using covers.

Spanners for uniform metrics. Uniform metrics have trivial classical 2-spanners—that is, star graphs. In the oblivious model one can simply use “constellation of stars” with a constant number of random centers, and the resulting spanner is linear in size. In the adaptive settings, we present a lower bound of $\Omega(n^{1+1/t})$ edges for a reliable $t$-spanner, and asymptotically “matching” construction of a deterministic $(2t - 1)$-reliable spanner with $O(n^{1+1/t})$ edges. The construction is based on reliable expanders—these are expanders that remain expanding under the type of attacks described above. See Sections 3 and 6 for details.
Covers. A \( t \)-cover of a finite metric space \( M = (P, d) \) is a family of subsets \( C = \{ S \mid S \subseteq P \} \), such that for each pair \( p, q \in P \) of points there exists a subset in \( C \) that contains both points and whose diameter is at most \( t \cdot d(p, q) \). Covers are used here to extend reliable spanners for uniform metrics into reliable spanners for general metrics. This is done by using spanners for uniform in each set of the cover and then taking a union of the edges of those graphs. See Section 5.

Naturally, the size \( \sum_{S \in C} |S| \) of a \( t \)-cover \( C \) is an important parameter in the resulting size of the spanner, so in Section 4, we study the problem of constructing good covers. For general \( n \)-point spaces with spread at most \( \Phi \), we observe that the Ramsey partitions of Reference [27] provide \( O(t) \) covers of size \( O(n^{1+1/t} \log \Phi) \), which is close to optimal, because of an \( \Omega(n^{1/t} + \log \Phi) \) lower bound we provide. In more specific cases, like ultrametrics, trees, and planar graphs, one can do better. For example, for trees and planar graphs one gets \( (2 + \epsilon) \)-covers of near linear size. For planar graphs, known partitions have much larger gap, which makes these results quite interesting.

New reliable spanners. Plugging the constructions of spanners for uniform metrics with the construction of covers yields reliable spanners for finite uniform, ultrametric, tree, planar, and general metrics. The results are summarized in Table 1.

Efficient construction. All our constructions relies on randomized constructions of expanders (over \( m \) vertices), that succeeds with probability \( \geq 1 - 1/m^{O(1)} \). As such, the constructions described can be done efficiently, if one wants constructions of spanners for \( n \) vertices that succeeds with probability \( 1 - 1/n^{O(1)} \). See Remark 5 for details.

### Table 1. Our Results

| Metric          | \( \Delta \) | Guarantee              | Size                                      | Ref.          |
|-----------------|--------------|------------------------|-------------------------------------------|---------------|
| Uniform         | 2            | expectation            | \( O(n^{9/2} \log \Phi^{-1}) \)           | Lemma 3.1     |
|                 | \( t \)      | det. lower bound       | \( \Omega(n^{1+1/t}) \)                   | Lemma 3.2     |
|                 | 2t - 1       | deterministic          | \( O(9^{-2}n^{1+1/t}) \)                  | Theorem 3.5   |
|                 | 2t           | deterministic          | \( O(9^{-1}n^{1+1/t}) \)                  | Theorem 3.5   |
| Finite metrics  | \( O(\log n) \) | expectation           | \( O(9^{-1}n \text{ polylog}) \)         | Lemma 5.3     |
|                 | \( O(t) \)   | expectation            | \( O(9^{-1}n^{1+1/t} \text{ polylog}) \)  | Lemma 5.3     |
|                 | \( O(t \log n) \) | deterministic         | \( O(9^{-1}n^{1+1/t} \text{ polylog}) \)  | Lemma 5.4     |
|                 | \( O(t^2) \) | deterministic          | \( O(9^{-1}n^{1+1/t} \text{ polylog}) \)  | Lemma 5.4     |
| Ultrametrics    | \( 2 + \epsilon \) | expectation          | \( O(9^{-1}e^{-2}n \text{ polylog}) \)    | Lemma 5.5     |
|                 | \((2 + \epsilon)t - 1 \) | deterministic      | \( O(9^{-2}e^{-3}n^{1+1/t} \text{ polylog}) \) | Lemma 5.6     |
| Trees           | \( 3 + \epsilon \) | expectation          | \( O(9^{-1}e^{-2}n \text{ polylog}) \)    | Lemma 5.7     |
|                 | \((4 + \epsilon)t - 3 \) | deterministic      | \( O(9^{-2}e^{-3}n^{1+1/t} \text{ polylog}) \) | Lemma 5.8     |
| Planar graphs   | \( 3 + \epsilon \) | expectation          | \( O(9^{-1}e^{-4}n \text{ polylog}) \)    | Lemma 5.9     |
|                 | \((4 + \epsilon)t - 3 \) | deterministic      | \( O(9^{-2}e^{-6}n^{1+1/t} \text{ polylog}) \) | Lemma 5.10    |

Polylog factors are polynomial factors in \( \log n \) and \( \log \Phi \), where \( \Phi \) is the spread of the metric. For trees and planar graphs, these results are for graphs with weights on the edges. Here, “expectation” denotes that the spanner works against an oblivious adversary (here, the expectation is over the randomization in the construction), and the guarantee is on the expected size of the damaged set. Similarly, “deterministic” implies an adaptive adversary.
2 PRELIMINARIES

2.1 Metric Spaces

For a set \( \mathcal{X} \), a function \( d : \mathcal{X} \times \mathcal{X} \rightarrow [0, \infty) \), is a metric if it is symmetric, complies with the triangle inequality, and \( d(p, q) = 0 \iff p = q \). A metric space is a pair \( \mathcal{M} = (\mathcal{X}, d) \), where \( d \) is a metric. For a point \( p \in \mathcal{X} \), and a radius \( r \), the ball of radius \( r \) is the set

\[
\{ q \in \mathcal{X} \mid d(p, q) \leq r \}.
\]

For a finite set \( X \subseteq \mathcal{X} \), the diameter of \( X \) is

\[
\text{diam}(X) = \text{diam}_{\mathcal{M}}(X) = \max_{p, q \in X} d(p, q),
\]

and the spread of \( X \) is \( \Phi(X) = \frac{\text{diam}(X)}{\min_{p, q \in X} d(p, q)} \). A metric space \( \mathcal{M} = (\mathcal{X}, d) \) is finite, if \( \mathcal{X} \) is a finite set. In this case, we use \( \Phi = \Phi(X) \) to denote the spread of the (finite) metric.

A natural way to define a metric space is to consider an undirected connected graph \( G = (P, E) \) with positive weights on the edges. The shortest path metric of \( G \), denoted by \( d_G \), assigns for any two points \( p, q \in P \) the length of the shortest path between \( p \) and \( q \) in the graph. Thus, any graph \( G \) readily induces the finite metric space \( (V(G), d_G) \). If the graph is unweighted, then all the edges have weight 1.

A tree metric is a shortest path metric defined over a graph that is a tree.

2.2 Reliable Spanners

**Definition 2.1.** For a metric space \( \mathcal{M} = (P, d) \), a graph \( H = (P, E) \) is a \( t \)-spanner, if for any \( p, q \in P \),

\[
d_H(p, q) \leq t \cdot d(p, q).
\]

Here, \( d_H \) is the shortest path distance on \( H \) whose edges are weighted according to \( d \).

Given a weighted graph \( G = (V, E) \), and a set \( B \subseteq V \), we denote by \( G|_B \) the subgraph induced on \( B \). We also use the notation \( G \setminus B = G|_{V \setminus B} \). A randomized graph \( G \) is a probability distribution over the edge set \( E \) for a given set of vertices \( V \).

An attack on a graph \( G = (V, E) \) is a set of vertices \( B \) that fails and no longer can be used. An attack (on a randomized graph) is oblivious, if the set \( B \) is picked stochastically independent of the edge set of the graph.

**Definition 2.2 (Reliable Spanner).** Let \( G = (P, E) \) be a \( t \)-spanner for some \( t \geq 1 \) constructed by a (possibly) randomized algorithm. Given an attack \( B \), its damaged set \( B^+ \) is a set of smallest possible size, such that for any pair of vertices \( p, q \in P \setminus B^+ \), we have

\[
d_{G|_B}(p, q) \leq t \cdot d(p, q),
\]

that is, distances are preserved (up to a factor of \( t \)) for all pairs of points not contained in \( B^+ \). The quantity \( |B^+ \setminus B| \) is the loss of \( G \) under the attack \( B \). The loss rate of \( G \) is \( \lambda(G, B) = |B^+ \setminus B| / |B| \). For \( \delta \in (0, 1) \), the graph \( G \) is \( \delta \)-reliable (in the deterministic or non-oblivious setting), if \( \lambda(G, B) \leq \delta \) holds for any attack \( B \subseteq P \). Furthermore, the graph \( G \) is \( \delta \)-reliable in expectation (or in the oblivious model), if \( \mathbb{E}[\lambda(G, B)] \leq \delta \) holds for any oblivious attack \( B \subseteq P \).

**Remark 1.** The damaged set \( B^+ \) is not necessarily unique, since there might be freedom in choosing the point to include in \( B^+ \) for a pair that does not have a \( t \)-path in \( G \setminus B \).

2.3 Miscellaneous

For a graph \( G \), and two set of vertices \( Y, Z \subseteq V(G) \), let

\[
\Gamma_Z(Y) = \{ x \in Z \mid \exists y \in E(G) \text{ and } y \in Y \}
\]

denote the neighbors of \( Y \) in \( Z \). The neighbors of \( Y \) in \( G \) is denoted by \( \Gamma(Y) = \Gamma_{V(G)}(Y) \).
Definition 2.3. For a collection of sets $\mathcal{F}$, and an element $x$, let $\deg(x, \mathcal{F}) = |\{X \in \mathcal{F} \mid x \in X\}|$ denote the degree of $x$ in $\mathcal{F}$. The maximum degree of any element of $\mathcal{F}$ is the depth of $\mathcal{F}$.

Notations. We use $P + p = P \cup \{p\}$ and $P - p = P \setminus \{p\}$. Similarly, for a graph $G$, and a vertex $p$, let $G - p$ denote the graph resulting from removing $p$.

3 RELIABLE SPANNERS FOR UNIFORM METRIC

Let $P$ be a set of $n$ points and let $(P, d)$ be a metric space equipped with the uniform metric, that is, for all distinct pairs $p, q \in P$, we have that $d(p, q)$ is the same quantity (e.g., 1). Note that $n - 1$ edges are enough to achieve a 2-spanner for the uniform metric by using the star graph.

3.1 A Randomized Construction for the Oblivious Case

Construction. Let $\theta \in (0, 1)$ be a fixed parameter. Set $k = 2[\theta^{-1} \log \theta^{-1}] + 1$ and sample $k$ points from $P$ uniformly at random (with replacement). Let $C \subseteq P$ be the resulting set of center points. For each point $p \in C$, build the star graph $\ast_p = (P, \{pq \mid q \in P - p\})$, where $p$ is the center of the star. The constellation of $C$ is the graph $\ast = \bigcup_{p \in C} \ast_p$, which is the union of the star graphs induced by centers in $C$.

Lemma 3.1. The constellation $\ast$, defined above, is a $\theta$-reliable 2-spanner in expectation. The number of its edges is $O(n\theta^{-1} \log \theta^{-1})$.

Proof. Let $B \subseteq P$ be an oblivious attack, and let $b = |B|$. If there is a point of $C$ that is not in $B$, then there is a center point outside of the attack set, which provides 2-hop paths between all pairs of points in the residual graph, and therefore, we choose $B^+ = B$. On the other hand, if $C \subseteq B$, then the residual graph contains only isolated vertices, and therefore, we choose $B^+ = P$. If $(1 + \theta)b \geq n$, then there is nothing to prove. Thus, since $b/n < 1/(1 + \theta)$ and $1/(1 + \theta) \leq 1 - \theta/2$, we have

$$\mathbb{E}[\lambda(G, B)] = 0 \mathbb{P}[C \not\subseteq B] + \frac{n - 1 - b}{b} \mathbb{P}[C \subseteq B] \leq \frac{n}{b} \left(1 - \frac{1}{b} \right)^k \leq \frac{1}{(1 + \theta)^k - 1} \leq \exp\left(-\frac{k - 1}{2} \theta\right) \leq \theta.$$

As for the number of edges, $\ast$ has at most $k(n - 1)$ edges, since $\ast$ is the union of $k$ stars and each star has $n - 1$ edges. Thus, by the choice of $k$, the size of $\ast$ is $O(n\theta^{-1} \log \theta^{-1})$.

3.2 Lower Bound for a Deterministic Construction

In the non-oblivious settings, the attacker knows the constructed graph $G$ when choosing the attack set $B$.

Lemma 3.2. Let $G = (P, E)$ be a $\theta$-reliable $t$-spanner on $P$ for the uniform metric, where $\theta \in (0, 1)$ and $t \geq 1$. Then, in the non-oblivious settings, $G$ must have $\Omega(n^{1+1/t})$ edges.

Proof. We assume that the distance between any pair of points of $P$ is one. Let the attack set $B$ be the set of all nodes of degree at least $\Delta$, where $\Delta = n^{1/t}/4$. Assume, toward a contradiction, that $|B| \leq n/4$. By the reliability condition, there exists a set $Q \subseteq P \setminus B$ of nodes of the residual graph of size at least $n - (1 + \theta) |B| \geq n/2$, that has $t$-hop paths in $G \setminus B$ between all pairs of vertices of $Q$. Let $p \in Q$ be an arbitrary vertex. Let $b(p, t)$ be a ball of radius $t$ centered at $p$ in the shortest path metric in the residual graph $G \setminus B$. On the one hand, from the above, $b(p, t) \supseteq Q$. On the other hand, the maximum degree is at most $\Delta$, and therefore $|b(p, t)| \leq \Delta^t \leq n/4$. As such, we have $n/4 \geq |b(p, t)| \geq |Q| \geq n/2$. A contradiction.

Hence, $|B| > n/4$. The claim follows, since $\Delta|B| \leq 2|E|$, which implies $|E| \geq \Delta |B| / 2 = \Omega(n^{1+1/t})$. 

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Remark 2. Erdős' girth conjecture states that there exists a graph $G$ with $n$ vertices and $\Omega(n^{1+1/k})$ edges, and girth at least $2k + 1$, where the girth of $G$ is the length of the shortest cycle in $G$. The argument in the proof of Lemma 3.2 is closely related to the standard argument for proving a tight counterpart—any graph with $\Omega(n^{1+1/k})$ edges has girth at most $2k + 1$.

3.3 Reliable Spanners of the Uniform Metric for Adaptive Adversary

Here, we present a construction of reliable spanner that is close to being tight. The spanner is simply a high-degree expander whose properties are described in the following definition.

Definition 3.3. Denote by $\lambda(G)$ the second eigenvalue of the matrix $M/d$, where $M = \text{Adj}(G)$ is the adjacency matrix of a $d$-regular graph $G$. A proper expander specifies a constant $C > 1$, and functions $\mathcal{C}_\delta, c_\delta > 0$, such that for every $\delta \in (0, 1/4)$ and even integers $d \geq \mathcal{C}_\delta$, $n \geq d^2$, there exists an $n$-vertex, $d$-regular graph $G = (V, E)$, such that:

1. $\forall S \subseteq V, |S| \geq 12n/(\delta d) \implies |\Gamma(S)| > (1 - \delta)n$, $\quad (P1)$
2. $\forall S \subseteq V, |S| \leq c_\delta n/d \implies |\Gamma(S)| \geq (1 - \delta)d|S|$, $\quad (P2)$
3. $\lambda(G) \leq C/\sqrt{d}$. $\quad (P3)$

For each one of the properties above, it is known that there exists an expander satisfying it: Property $(P1)$ is essentially proved in Reference [11], Property $(P2)$ is folklore, and Property $(P3)$ appears in Reference [15]. Since they hold almost surely for “random regular graphs”, they also hold simultaneously. However, we were unable to find in the literature proofs of almost sure existence in the same model of random regular graphs, and contiguity of the different random models does not necessarily hold in the high-degree regime (which is what we need here). Therefore, for completeness, Appendix A reprove $(P1)$ and $(P2)$ in the same random model in which $(P3)$ was proved. We thus get the following:

Theorem 3.4. The random graph constructed in Section A.1 is a proper expander (see Definition 3.3), asymptotically almost surely. Specifically, the probability the graph has the desired properties is $\geq 1 - n^{-O(1)}$.

With the appropriate choice of parameters, these expanders are reliable spanners for uniform metrics.

Theorem 3.5. For every $t \in \mathbb{N}, \theta \in (0, 1), and n \in 2\mathbb{N}$, such that $n \geq e^{\Theta(t)}$, there exist:

1. $\theta$-reliable $2t$-spanner with $O(\theta^{-1}n^{1+1/t})$ edges for $n$-point uniform space, and
2. $\theta$-reliable $(2t - 1)$-spanner with $O(\theta^{-2}n^{1+1/t})$ edges for $n$-point uniform space.

The proof is somewhat cumbersome and is deferred to Section 6.

Applying the above theorem directly on non-uniform metric, we obtain the following corollaries.

Corollary 3.6. Let $M = (X, d)$ be a metric space, and let $P \subseteq X$ be a finite subset of size $n$. Given parameters $t \in \mathbb{N}$, and $\theta \in (0, 1)$, there exists a weighted graph $G$ on $P$, such that:

(A) The graph $G$ has $|E(G)| = O(\theta^{-2} \cdot n^{1+1/t})$ edges.
(B) The graph $G$ is $\theta$-reliable. Namely, given any attack set $B \subset X$, there exists a subset $Q \subset P$, such that $|Q| \geq |P| - (1 + \theta) |B \cap P|$. Furthermore, for any two points $p, q \in Q$, we have $d_M(p, q) \leq d_{G|Q_\delta}(p, q) \leq (2t - 1) \cdot \text{diam}_M(P)$, and the path realizing it has at most $(2t - 1)$ hops.

In particular, $G$ has hop diameter at most $2t - 1$, and diameter at most $(2t - 1) \cdot \text{diam}_M(P)$.

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Corollary 3.7. Let $M = (X, d)$ be a metric space, and let $P \subseteq X$ be a finite subset of size $n$. Given parameters $t \in \mathbb{N}$, and $\vartheta \in (0, 1)$, there exists a weighted graph $G$ on $P$, such that:

(A) The graph $G$ has $|E(G)| = O(\vartheta^{-1} \cdot n^{1+1/t})$ edges.

(B) The graph $G$ is $\vartheta$-reliable. Namely, given any attack set $B \subseteq X$, there exists a subset $Q \subseteq P$, such that $|Q| \geq |P| - (1 + \vartheta) |B \cap P|$. Furthermore, for any two points $p, q \in Q$, we have

$$d_M(p, q) \leq d_{G|Q}(p, q) \leq 2t \cdot \text{diam}_M(P),$$

and the path realizing it has at most $2t$ hops.

In particular, $G$ has hop diameter at most $2t$, and diameter at most $2t \cdot \text{diam}_M(P)$.

Remark 3. Corollaries 3.6 and 3.7 are quite weak as far as the guarantee on the length of the resulting path (i.e., they are not good spanners). A construction that provides a spanner guarantee is provided below in Lemma 5.4 below.

As an aside, proper expanders are reliable spanners, because their expansion property is robust, as testified by the following.

Theorem 3.8 (Reliable Vertex Expander). For every $\vartheta \in (0, 1)$ there exists a constant $c = c_\vartheta > 0$, such that for any expansion constant $h \geq c^{-2}$, there exists a family of vertex expander graphs $\{G = (V, E)\}_n$ on $n$ vertices of degree at most $4h/\vartheta$, with the following resiliency property: For any $B \subseteq V$, there exists $B^+ \supseteq B$, $|B^+| \leq (1 + \vartheta)|B|$ such that the graph $G \setminus B^+$ is a vertex expander in the sense that

(i) $\text{diam}(G \setminus B^+) \leq 2\lceil \log_h n \rceil$, and

(ii) For any $U \subseteq V \setminus B^+$ of size $|U| \leq cn/h$, we have $|\Gamma_{G \setminus B^+}(U)| \geq h|U|$.

The proof is deferred to Section 6.3.4.

4 COVERS FOR TREES, BOUNDED SPREAD METRICS, AND PLANAR GRAPHS

Definition 4.1. For a finite metric space $M = (P, d)$, a $t$-cover, is a family of subsets $C = \{S_i \subseteq P \mid i = 1, \ldots, m\}$, such that for any $p, q \in P$, there exists an index $i$, such that $p, q \in S_i$, and

$$\text{diam}(S_i)/t \leq d(p, q) \leq \text{diam}(S_i).$$

The size of a cover $C$ is $|C| = \sum_{S \in C} |S|$. Recalling Definition 2.3, the degree in $C$ of a point $p \in P$ is the number of sets of $C$ that contain it. The depth of $C$ is the maximum degree of any element of $P$, and is denoted by $D(C)$.

4.1 Lower Bounds

Unfortunately, in the worst case, the depth and the size of any cover must depend on the spread of the metric.

Proposition 4.2. For any parameter $t > 1$, any integer $h > 1$, $\Phi = t^h$, and any $n \geq h$, there exists a metric $M = (P, d)$ of $n$ points, such that

(I) $\Phi(P) = \Phi$, and

(II) any $t$-cover $C$ of $P$ has size $\Omega(n \log_t \Phi) = \Omega(nh)$, average degree $\geq h/2$, and depth $h$.

Proof. For simplicity of exposition, assume that $h$ divides $n$. Let $P_i$ be a set of $n/h$ points, such that the distance between any pair of points of $P_i$ is $\ell_i = (t + \varepsilon)^i$, for some fixed small $\varepsilon > 0$, for $i = 1, \ldots, h$. Furthermore, assume that the distance between any point of $P_i$ and any point of $P_j$, for $i < j$, is $\ell_j$. 

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Let $P = \bigcup P_i$, and observe that the distance function defined above is a metric (it is the union of uniform metrics of different resolutions). Now, consider any $t$-cover $C$ of $P$. The rank of a cluster $C \in C$, is the highest $j$, such that $P_j \cap C \neq \emptyset$. We can assume that all the clusters of $C$ have at least two points, as otherwise they can be removed. For any index $j \in [h]$, any point $p \in P_j$ and any point $q \in \bigcup_{i=1}^j P_i - p$, by definition, there exists a cluster $C \in C$, such that $p, q \in C$, and diam$(C) \leq t - \ell_j$, since $d(p, q) = \ell_j$. It follows that $C$ cannot contain any point of $\bigcup_{i=1}^h P_i$. Namely, the rank of $C$ is $j$.

If there are two clusters of rank $j$ in $C$, then we can merge them, since merging does not increase their diameter, and such an operation does not increase the size of the cover, and the degrees of its elements. As such, in the end of this process, the cover $C$ has $h$ clusters, and for any $j \in [h]$, there is a cluster $C_j \in C$ that is of rank $j$, and contains (exactly) all the elements of $\bigcup_{i=1}^j P_i$. Namely, $C = \{C_1, \ldots, C_h\}$, where $C_j = \bigcup_{i=1}^j P_i$. It is easy to verify that this cover has the desired properties. \hfill \Box

**Proposition 4.3.** For any $t \in 2, 3, \ldots$, and any sufficiently large $n$ there exists an $n$-point metric space for which any $t$-cover must be of size at least $\Omega(n^{1+1/2t})$.

**Proof.** Let $g = 2t + 2$. By a standard probabilistic argument, for any sufficiently large $n \in \mathbb{N}$ there exists a simple graph $G = (V, E)$ on $n$ vertices and $m = \Omega(n^{1+1/2t})$ edges whose girth is at least $g$. (This is not the best known bound, but it is sufficient for our purposes.) Consider $G$ as a metric space with the shortest (unweighted) path metric. Let $C$ be a $t$-cover for $G$, and let $C' = \{S \in C \mid \text{diam}(S) \leq t\}$. For $S \subset V$ let $E(S) = \{uv \in E \mid u, v \in S\}$.

We claim that for every $S \in C'$, $E(S)$ is a forest, and hence $|E(S)| < |S|$. Indeed, suppose $E(S)$ contains a cycle $(v_0, v_1, \ldots, v_h, v_0)$ such that $v_i v_{i+1}, v_0 v_h \in E(S) \subseteq E$. Denote $d_i = d(v_0, v_i)$. Since $\{v_i, v_{i+1}\} \in E$, we have $d_{i+1} - d_i \in \{-1, 0, 1\}$. Let $j$ be the smallest $i$ such that $d_{i+1} \leq d_i$. Hence, $d_j = j$. Let $P = (v_{j+1}, u_1, \ldots, u_k, v_0)$ be a shortest path in $G$ between $v_{j+1}$ and $v_0$. $P$’s length is at most $d_j = j$. Thus, the sequence $v_0, v_1, \ldots, v_j, v_{j+1}, u_1, \ldots, u_k, v_0$ is closed path of length at most $2j + 1$, and hence contains a cycle of length at most $2j + 1$. By the girth condition, $2j + 1 \geq 2t + 2$, and hence $d_j = j > t$. But, since $v_0, v_j \in S$, this means that diam$(S) \geq d_j > t$, which contradicts the definition of $C'$.

For every edge $pq \in E$, $d(p, q) = 1$, and by the $t$-covering condition there exists $S \in C'$ such that $p, q \in S$. Therefore, $pq \in E(S)$. Hence, $E \subseteq \bigcup_{S \in C'} E(S)$, and therefore,

\[ cn^{1+1/2t} \leq |E| \leq \sum_{S \in C'} |E(S)| < \sum_{S \in C'} |S| = \text{size}(C') \leq \text{size}(C). \hfill \Box

### 4.2 Cover for Ultrametrics

**Definition 4.4.** A *hierarchically well-separated tree (HST)* is a metric space defined on the leaves of a rooted tree $T$. To each vertex $u \in T$ there is an associated label $\Delta_u \geq 0$. This label is zero for all the leaves of $T$, and it is a positive number for all the interior nodes. The labels satisfy for every non-root vertex $v \in T$, $\Delta_v \leq \Delta_{\overline{P}(v)}/k$, where $\overline{P}(v)$ is the parent of $v$ in $T$. The distance between two leaves $x, y \in T$ is defined as $\Delta_{\text{lca}(x, y)}$, where $\text{lca}(x, y)$ is the least common ancestor of $x$ and $y$ in $T$. An HST $T$ is a $k$-**HST** if for every non-root vertex $v \in T$, $\Delta_v \leq \Delta_{\overline{P}(v)}/k$.

HSTs are one of the simplest non-trivial metrics, and surprisingly, general metrics can be embedded randomly into HSTs with expected distortion of $O(\log n)$ [6, 16].

**Definition 4.5.** A metric $M = (P, d)$ is an *ultrametric*, if for any $x, y, z \in P$, we have that $d(x, z) \leq \max(d(x, y), d(y, z))$. Notice, that this is a stronger version of the triangle inequality, which states that $d(x, z) \leq d(x, y) + d(y, z)$.
The following is folklore, and it also easy to verify (see, e.g., Reference [7, Lemma 3.5].

**Lemma 4.6.** For \( k \geq 1 \), every finite ultrametric can be \( k \)-approximated by a \( k \)-HST.

**Lemma 4.7.** For \( k > 1 \), every \( k \)-HST with spread \( \Phi \) has 1-cover of depth at most \( \log_k \Phi \).

**Proof.** Let \( T \) be the tree of the HST. With every vertex \( u \in T \) we associate a cluster \( C_u \) the leaves of the subtree rooted at \( u \). The properties of the cover are immediate.

**Corollary 4.8.** Let \( M = (P, d) \) be an ultrametric over \( n \) points with spread \( \Phi \). For any \( \varepsilon \in (0, 1) \), one can compute a \((1 + \varepsilon)\)-cover of \( M \) of depth \( O(\varepsilon^{-1} \log \Phi) \).

### 4.3 Cover for General Finite Metrics

We need the following result.

**Lemma 4.9 ([27]).** Let \( (P, d) \) be an \( n \)-point metric space and \( k \geq 1 \). Then there exists a distribution over decreasing sequences of subsets \( P = P_0 \supseteq P_1 \supseteq \cdots \supseteq P_s = \emptyset \) (itself is a random variable), such that for all \( \mu > -1/k \), we have \( \mathbb{E} \left[ \sum_{j=1}^{s} |P_j| \right] \leq \max \left( \frac{k}{1 + \mu k}, 1 \right) \cdot n^{\mu + 1/k} \), and such that for each \( j \in [s] \) there exists an ultrametric \( \rho_j \) on \( P_{j-1} \) satisfying for every \( p, q \in P \), that \( \rho_j(p, q) \geq d(p, q) \), and if \( p \in P_{j-1} \) and \( q \in P_{j-1} \setminus P_j \) then \( \rho_j(p, q) \leq O(k) \cdot d(p, q) \).

By computing a cover (using Corollary 4.8) for each ultrametric generated by the above lemma, we get the following.

**Lemma 4.10.** For an \( n \)-point metric space \( M = (P, d) \) with spread \( \Phi \), and a parameter \( k > 1 \), one can compute, in polynomial time, an \( O(k) \)-cover of \( M \) of size \( O(n^{1+1/k} \log \Phi) \) and depth \( O(k n^{1/k} \log \Phi) \).

**Proof.** Using Lemma 4.9, for the parameter \( k \), compute the sequence \( P = P_0 \supseteq P_1 \supseteq \cdots \supseteq P_s = \emptyset \) and the associated ultrametrics \( \rho_1, \ldots, \rho_s \). We build a 1-HST \( T_i \) for \( \rho_i \), when restricted to the set \( P_{i-1} \), for \( i = 1, \ldots, s - 1 \). For every HST in this collection, we compute a 2-cover using Corollary 4.8. Let \( C \) be the union of all these covers.

Since for every HST \( T_i \) the resulting cover has size \( O(|P_i| \log \Phi) \), then by Lemma 4.9 (applied with \( \mu = 1 \)), we have

\[
\mathbb{E} \left[ \sum_i |P_i| \log \Phi \right] = O(n^{1+1/k} \log \Phi).
\]

As for the quality of the cover, let \( p, q \) be any two points in \( P \), and assume (without loss of generality) that \( p \in P_{i-1} \) and \( q \in P_{i-1} \setminus P_i \) for some \( i \in [s] \). We have that \( \rho_i(p, q) = O(k) \cdot d(p, q) \), and since we computed a 2-cover for this tree, there is a cluster in the computed cover that contains both points and its diameter is at most twice the distance between those points.

The maximum depth, follows by using Lemma 4.9 with \( \mu = 0 \). This implies that a point of \( P \) participates in \( s = O(kn^{1/k}) \) HSTs, and each cover generated by such an HST might a point an element at most \( O(\log \Phi) \) times.

The bounds on the size and depth hold in expectation, and one can repeat the construction if they exceed the desired size by (say) a factor of eight. In expectation, after a constant number of iterations, the algorithm would compute with high probability a cover with the desired bounds.

### 4.4 Covers for Trees

Using a tree separator, and applying it recursively, implies the following construction of covers for trees.
Lemma 4.11. For a weighted tree metric $T = (P, d)$, with spread $\Phi$, and a parameter $\varepsilon \in (0, 1)$, one can compute in polynomial time a $(2 + \varepsilon)$-cover of $T$ of depth $O(\varepsilon^{-1} \log \Phi \log n)$, and size $O(n \varepsilon^{-1} \log \Phi \log n)$, where $n = |P|$.

Proof. The proof is by induction on $n$. When $n = 1$ the trivial cover is sufficient. Assume next that $n \geq 1$ and the minimum distance in $T$ is one. Find a separator node $s$ in $T$ such that there is no connected component in $T$ larger than $n/2$ after removing $s$. For $i \in \{0, 1, 2, \ldots, m = \lceil \log_{1+\varepsilon/2} \Phi \rceil \}$, define the sets $P(s, i) = \{ p \in P \mid d(s, p) \leq (1 + \varepsilon/2)^i \}$. By the inductive hypothesis, for each connected component $Q$ of $T - s$ there is a $(2 + \varepsilon)$-cover $C_Q$ of $Q$ of depth $O(\varepsilon^{-1} \log \Phi \log(n/2))$ and size $O(n \varepsilon^{-1} \log \Phi \log(n/2))$. The cover for $P$ is

$$C_P = \{ P(s, i) \mid i = 0, 1, 2, \ldots, m \} \cup \bigcup_Q C_Q.$$  

Since every element of $P$ participates in at most $m$ sets in each level of the recursion, the bound on the depth and size is immediate.

As for the quality of the cover, by the inductive hypothesis, we need only to check pairs of points $p, q \in P$, that are separated by $s$. Assume $d(s, p) \geq d(s, q)$, and let $j$ be the minimum index, such that $d(s, p) \leq (1 + \varepsilon/2)^j$. We have that $p, q \in P(s, j)$, and

$$d(p, q) \geq d(s, p) \geq (1 + \varepsilon/2)^{j-1} \quad \text{and} \quad \text{diam}(P(s, j)) \leq 2(1 + \varepsilon/2)^j.$$

As such, we have

$$\frac{\text{diam}(P(s, j))}{d(p, q)} \leq \frac{2(1 + \varepsilon/2)^j}{(1 + \varepsilon/2)^{j-1}} = 2 + \varepsilon.$$

4.5 Covers for Planar Graphs

The next lemma can be traced back to the work of Lipton and Tarjan [25].

Lemma 4.12. Let $H = (P, E)$ be a planar triangulated graph with non-negative edge weights. There is a partition of $P$ to three sets $X, Y, Z$, such that

(i) $|X| \leq (2/3)n$ and $|Y| \leq (2/3)n$,

(ii) there is no edge between $X$ and $Y$, and

(iii) $Z$ is composed of two interior disjoint shortest paths that share one of their endpoints, and an edge connecting their other two endpoints.

Definition 4.13. For a metric space $(\mathcal{X}, d)$ and a parameter $r$, an $r$-net $N$ is a maximal set of points in $\mathcal{X}$ satisfying:

(i) For any two net points $p, q \in N$, $p \neq q$, we have $d(p, q) > r$.

(ii) For any $p \in \mathcal{X}$, $d(p, N) = \min_{q \in N} d(p, q) \leq r$.

A net can be computed by repeatedly picking the point furthest away from the current net $N$, and adding it to the net if this distance is larger than $r$, and stopping otherwise. We denote a net computed by this algorithm by net$(X, r)$.

The following lemma testifies that if we restrict the net to lay along a shortest path in the graph, locally the cover it induces has depth as if the graph was one-dimensional.

Lemma 4.14. Let $G$ be a weighted graph, and let $d$ be the shortest path metric it induces. Let $\pi$ be a shortest path in $G$ and let $N = \text{net}(\pi, r) \subseteq \pi$ be a net computed for some distance $r > 0$. For some $R > 0$, consider the set of balls $\mathcal{B} = \{ b(p, R) \mid p \in N \}$. For any point $q \in V(G)$, we have that the degree of $q$ in $\mathcal{B}$ is at most $2R/r + 1$.

Proof. Let $p_1, \ldots, p_k$ be the points of $N \cap b(q, R)$ sorted by their order along $\pi$—these are the only points that their balls in $\mathcal{B}$ would contain $q$. By the definition of the net, $d(p_i, p_{i+1}) > r$ for
all $i$. Since $\pi$ is a shortest path, we also have that

$$2R \geq \text{diam}(b(q, R)) \geq d(p_1, p_k) = \sum_{i=1}^{k-1} d(p_i, p_{i+1}) > (k - 1)r.$$  \hfill $\square$

**Construction.** Let $\varepsilon \in (0, 1)$ be an input parameter, and let $G$ be a weighted planar graph. We assume that $G$ is triangulated, as otherwise it can be triangulated (we also assume that we have its planar embedding). Any new edge $pq$ is assigned as weight the distance between its endpoints in the original graph. This can be done in linear time. As usual, we assume that the minimum distance in $G$ is one, and its spread is $\Phi$.

Let $Z$ be the cycle separator given by Lemma 4.12 made out of two shortest paths $\pi_1$ and $\pi_2$. Let $p_1, p_2, p_3$ be the endpoints of these two paths.

For $i = 0, \ldots, m = \lceil \log_{b+\varepsilon/8} \Phi \rceil$, let $N_i = \text{net}(\pi_1, \varepsilon r_i/8) \cup \text{net}(\pi_2, \varepsilon r_i/8) \cup \{p_1, p_2, p_3\}$, where $r_i = (1 + \varepsilon/8)^i$. The associated set of balls is

$$\mathcal{B}_i = \{b(p, (1 + \varepsilon/8)r_i) \mid p \in N_i\}.$$  

The resulting set of balls is $\mathcal{B}(Z) = \bigcup \mathcal{B}_i$. We add the sets of $\mathcal{B}(Z)$ to the cover, and continue recursively on the connected components of $G - Z$. Let $C$ denote the resulting cover.

**Analysis.**

**Lemma 4.15.** For any two vertices $p, q \in V(G)$, there exists a cluster $C \in C$, such that $p, q \in C$, and $\text{diam}(C) \leq (2 + \varepsilon)d_G(p, q)$. That is, $C$ is a $(2 + \varepsilon)$-cover of $G$.

**Proof.** Assume, for the simplicity of exposition, that $p$ and $q$ get separated in the top level of the recursion (otherwise, apply the argument to the inductive step in which they get separated). The shortest path between $p$ and $q$ must intersect the separator $Z$, say at a vertex $v$. Assume that $d_G(p, v) \geq d_G(v, q)$ and that $r_{j-1} \leq d_G(p, v) \leq r_j = (1 + \varepsilon/8)^j$. There is a point $u \in N_j$ within distance $\varepsilon r_j/8$ from $v$. As such,

$$d_G(p, u) \leq d_G(p, v) + d_G(v, u) \leq (1 + \varepsilon/8)^j + (\varepsilon/8)(1 + \varepsilon/8)^j \leq (1 + \varepsilon/8)^{j+1},$$

which implies that $p \in b = b(u, (1 + \varepsilon/8)r_j)$. A similar argument shows that $q$ is also in $b$. Furthermore, we have that $d(p, q) \geq d(p, v) \geq r_{j-1}$. Note that $b \in \mathcal{B}_j \subseteq C$. We have that

$$\frac{\text{diam}(b)}{d(p, q)} \leq \frac{2(1 + \varepsilon/8)r_j}{r_{j-1}} = 2(1 + \varepsilon/8)^2 \leq 2 + \varepsilon. \hfill \square$$

**Lemma 4.16.** The depth of $C$ is $O(\varepsilon^{-2} \log n \log \Phi)$.

**Proof.** Fix a vertex $p$. By Lemma 4.14, for each $i$, at most

$$3 + 2 \left( \frac{2(1 + \varepsilon/8)r_i}{\varepsilon r_i/8} + 1 \right) = O(1/\varepsilon)$$

balls of $\mathcal{B}_i$ contains $p$. The number of such sets is $O(\log_{b+\varepsilon/8} \Phi) = O(\varepsilon^{-1} \log \Phi)$. The vertex $p$ get sent down to at most one recursive subproblem, and the recursion depth is $O(\log n)$. It follows that the depth of any point (and the degree of $p$ specifically) is at most $O(\varepsilon^{-2} \log \Phi \log n)$.  \hfill $\square$

**Theorem 4.17.** Let $G$ be a weighted planar graph over $n$ vertices with spread $\Phi$. Then, given a parameter $\varepsilon \in (0, 1)$, one can construct a $(2+\varepsilon)$-cover of $G$ with depth $O(\varepsilon^{-2} \log n \log \Phi)$ in polynomial time.
Remark 4. It is possible to generalize Theorem 4.17 to the shortest path metric on families of graphs excluding a fixed minor. Specifically, by Reference [22, Lemma 3.3], there exists \( O(s^2) \)-cover of depth \( O(3^s \log \Phi) \) for every metric space supported on a graph excluding \( K_s \) minor and spread \( \Phi \). It may be possible to improve the approximation parameter to \( O(s) \) using Reference [2]. This approach does not have a \( \log n \) factor in the depth parameter, but it can not provide a \( (2 + \varepsilon) \)-approximation as in Theorem 4.17. As communicated to us by an anonymous referee, the approach used here to prove Theorem 4.17 can also be extended to any family of graphs excluding fixed minor and obtain \( (2 + \varepsilon) \)-cover using the shortest paths separators of Reference [1]. We have not pursued those avenues.

5 FROM COVERS TO RELIABLE SPANNERS

5.1 The Oblivious Construction

Lemma 5.1. Let \( M = (P, d) \) be a finite metric space, and suppose there exists a \( \xi \)-cover \( C \) of \( M \) of size \( s \) and depth \( D \). Then, there exists an oblivious \( \vartheta \)-reliable 2-hop \( 2\xi \)-spanner for \( M \), of size \( O(s \frac{D}{\vartheta} \log \frac{D}{\vartheta}) \).

Proof. For each cluster \( C \in C \), let \( \ast_C \) be a random constellation graph on \( C \) as defined in Section 3.1, with reliability parameter \( \psi = \vartheta / D \). The resulting spanner is the union \( \bigcup_{C \in C} \ast_C \). The number of edges in the resulting graph is at most

\[
\sum_{C \in C} O(|C| \psi^{-1} \log \psi^{-1}) = O(s \psi^{-1} \log \psi^{-1}) = O\left(s \frac{D}{\vartheta} \log \frac{D}{\vartheta}\right).
\]

Fix an attack set \( B \subset P \). A cluster \( C \in C \) is failed if \( |C| \leq (1 + \psi) |C \cap B| \). Denote the set failed clusters by \( \mathcal{F} \). For \( C \in C \setminus \mathcal{F} \), let \( \text{dmg}(C, B) \) be the (random) set of damaged points in \( C \) as defined in the proof of Lemma 3.1, i.e., \( \text{dmg}(C, B) = C \) if \( B \) contains all the constellation’s centers, and \( \text{dmg}(C, B) = B \) otherwise. By Lemma 3.1, \( \mathbb{E}(|\text{dmg}(C, B)|) \leq (1 + \psi) |B \cap C| \). The damaged set is defined as

\[
B^+ = \left( \bigcup_{C \in \mathcal{F}} C \right) \cup \left( \bigcup_{C \in C \setminus \mathcal{F}} \text{dmg}(C, B) \right).
\]

We next bound expected size of the loss \( B^+ \setminus B \):

\[
\mathbb{E}(|B^+ \setminus B|) \leq \mathbb{E} \left( \sum_{C \in \mathcal{F}} |C \setminus B| \right) + \sum_{C \in C \setminus \mathcal{F}} \mathbb{E} \left( |\text{dmg}(C, B) \setminus B| \right)
\]

\[
\leq \psi \sum_{C \in \mathcal{F}} |B \cap C| + \psi \sum_{C \in C \setminus \mathcal{F}} |B \cap C| = \psi \sum_{p \in B} \sum_{C \in C} 1_{p \in C} \leq \psi |B| = \vartheta |B|.
\]

Finally, for any two points \( p, q \in P \setminus B^+ \), there exists a non-failed cluster \( C \in C \) that contains both points, such that \( \text{diam}(C) \leq \xi d(p, q) \). As such, the two hops in the resulting graph are going to be of length at most \( 2 \text{diam}(C) \leq 2\xi d(p, q) \).

\( \square \)

5.2 The Deterministic Construction

Lemma 5.2. Let \( M = (P, d) \) be a finite metric space over \( n \) points, and let \( C \) be a \( \xi \)-cover of it of depth \( D \) and size \( s \). Then, for any integer \( t \geq 1 \), there exists:

(A) A \( \vartheta \)-reliable \( (2t - 1) \)-hop \( (2t - 1)\xi \)-spanner for \( M \), of size \( O(\vartheta^{-2} D^2 s n^{1/t}) \).

(B) A \( \vartheta \)-reliable \( 2t \)-hop \( 2t \xi \)-spanner for \( M \), of size \( O(\vartheta^{-1} D s n^{1/t}) \).

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Proof. (A) For a cluster $C \in C$, let $G(C)$ be a $\psi$-reliable spanner constructed using Corollary 3.6 on $C$, with the reliability parameter $\psi = \vartheta/D$. Let $G = (P, E)$ be a graph whose edge set $E$ is the union of the edge sets of $G(C)$ for $C \in C$.

Let $n_i$ be the size of the $i$th cluster, for $i \in \{1, \ldots, m = |C|\}$. The number of edges in $G$ is bounded by $O(\psi^{-2}N) = O(D^2 \vartheta^{-2}N)$, where

$$N = \sum_{i=1}^{m} n_i^{1+1/t} = \sum_{i=1}^{m} n_i^{1/t} n_i \leq \left( \max_{i} n_i^{1/t} \right) \sum_{i=1}^{m} n_i \leq n^{1/t} s,$$

since $\sum_i n_i = s$, and $\max_i n_i \leq n$. We conclude that the total number of edges in $G$ is $O(\vartheta^{-2}D^2 s n^{1/t})$.

Let $B \subset P$ be an attack set. The damage set $B^+ \supseteq B$ is constructed as in the proof of Lemma 5.1. Thus, as argued there, $|B^+| \leq (1 + \vartheta) |B|$. For every two points $p, q \in P \setminus B^+$, there exists a cluster $C \in C$, such that $p, q \in C$, and

$$\text{diam}(C)/\xi \leq d(p, q) \leq \text{diam}(C).$$

Furthermore, by Corollary 3.6, we have

$$d_{G(B)}(p, q) \leq d_{G(C) \setminus B}(p, q) \leq (2t - 1)\text{diam}(C) \leq (2t - 1)\xi \cdot d(p, q).$$

and shortest path in $G(C) \setminus B$ realizing $d_{G(C) \setminus B}(p, q)$ has at most $2t - 1$ hops.

(B) Similar to the above, except for using Corollary 3.7 instead of Corollary 3.6.  

\[\Box\]

5.3 Applications

5.3.1 General Metrics.

Lemma 5.3. Let $M = (P, d)$ be an $n$-point metric space of spread at most $\Phi$, and let $\vartheta \in (0, 1)$ and $k \in \mathbb{N}$ be parameters. Then, one can build an oblivious $\vartheta$-reliable $O(k)$-spanner for $M$ with

$$O\left( \vartheta^{-1}kn^{1+1/k} \log^2 \Phi \log \frac{kn^{1/k} \log \Phi}{\vartheta} \right)$$

edges. In particular, for $k = \log n$, we obtain a $\vartheta$-reliable $O(\log n)$-spanner for $M$ with

$$O\left( \vartheta^{-1}n \log n \log^2 \Phi (\log \log n + \log \log \Phi + \log \vartheta^{-1}) \right)$$

edges.

Proof. By Lemma 4.10, $M$ has a $\xi = O(k)$-cover of size $O(n^{1+1/2k} \log \Phi)$ and depth $D = O(kn^{1/2k} \log \Phi)$. Plugging this into Lemma 5.1 yields an oblivious $\vartheta$-reliable $O(k)$-spanner with $O(\vartheta^{-1}kn^{1+1/k} \log^2 \Phi \log \frac{kn^{1/k} \log \Phi}{\vartheta})$ edges.  

\[\Box\]

Lemma 5.4. Let $M = (P, d)$ be a finite metric over $n$ points of spread $\Phi$, and let $\vartheta \in (0, 1)$ and $k, t \in \mathbb{N}$ be parameters. Then, one can build a $\vartheta$-reliable $O(kt)$-spanner for $M$ with $O(\vartheta^{-1}kn^{1+1/(k+1/t)} \log^2 \Phi)$ edges. In particular, when $t = \log n$, we obtain a $\vartheta$-reliable $O(k \log n)$-spanner for $M$ with

$$O(\vartheta^{-1}kn^{1+1/(2k)} \log^2 \Phi)$$

edges, and when $t = k$, we obtain $\vartheta$-reliable $O(t^2)$-spanner for $M$ with $O(\vartheta^{-1}tn^{1+1/t} \log^2 \Phi)$ edges.

Proof. By Lemma 4.10, $M$ has a $O(k)$-cover of size $s = O(n^{1+1/2k} \log \Phi)$ and depth $D = O(kn^{1/2k} \log \Phi)$. Plugging this into Lemma 5.2 (B), yields a $\vartheta$-reliable $O(kt)$-spanner with the number of edges bounded by

$$O(\vartheta^{-1}Dsn^{1/t}) = O(\vartheta^{-1}kn^{1+1/k+1/t} \log^2 \Phi).$$  

\[\Box\]
5.3.2 Ultrametrics.

**Lemma 5.5.** Let $M = (P,d)$ be an ultrametric over $n$ points with spread $\Phi$, and let $\vartheta, \varepsilon \in (0,1)$ be parameters. Then, one can build an oblivious $\vartheta$-reliable $(2 + \varepsilon)$-spanner for $M$ with 

$$ O\left(\frac{\vartheta^{-1} \varepsilon^{-2} n \log^2 \Phi}{\vartheta \varepsilon} \right) $$

edges.

**Proof.** By Corollary 4.8, one can build a $(1 + \varepsilon/2)$-cover of $M$ of depth $D = O(\varepsilon^{-1} \log \Phi)$ and size $O(nD)$. Plugging this into Lemma 5.1 yields an oblivious $\vartheta$-reliable 2-hop $(2 + \varepsilon)$-spanner for $M$, of size

$$ O\left(\frac{nD^2}{\vartheta \log \frac{D}{\vartheta}} \right) = O\left(\frac{\vartheta^{-1} \varepsilon^{-2} n \log^2 \Phi}{\vartheta \varepsilon} \right). \quad \square$$

**Lemma 5.6.** Let $M = (P,d)$ be an ultrametric over $n$ points with spread $\Phi$, and let $\vartheta, \varepsilon \in (0,1)$, and $t \in \mathbb{N}$ be parameters. Then, one can build a $\vartheta$-reliable $(2 + \varepsilon)(t-1)$-spanner for $M$ of size $O(\vartheta^{-2} \varepsilon^{-3} t \cdot n^{1+1/t} \log^3 \Phi)$.

**Proof.** By Corollary 4.8, one can build a $\xi = (1+\varepsilon/2)$-cover of $M$ of depth $D = O(\varepsilon^{-1} \log \Phi)$ and size $O(nD)$. Plugging this into Lemma 5.2 (A) yields a deterministic $\vartheta$-reliable $(2t-1)\xi$-spanner for $M$, of size

$$ O(\vartheta^{-2} t D^3 n^{1+1/t}) = O(\vartheta^{-2} \varepsilon^{-3} t \cdot n^{1+1/t} \log^3 \Phi). \quad \square$$

5.3.3 Tree Metrics.

**Lemma 5.7.** Let $M = (P,d)$ be a tree metric over $n$ points with spread $\Phi$, and let $\vartheta, \varepsilon \in (0,1)$ be parameters. Then, one can build an oblivious $\vartheta$-reliable $(3 + \varepsilon)$-spanner for $M$ with

$$ O\left(\frac{\vartheta^{-1} \varepsilon^{-2} n \polylog(n, \Phi)}{\vartheta \varepsilon} \right) $$

edges, where $\polylog(n, \Phi) = \log^2 n \log^2 \Phi \log \frac{\log \Phi \log n}{\vartheta \varepsilon}$.

**Proof.** By Lemma 4.11, one can build a $(2 + \varepsilon/2)$-cover of $T$ of depth $D = O(\varepsilon^{-1} \log \Phi \log n)$ and size $O(nD)$. Plugging this into Lemma 5.1 yields an oblivious $\vartheta$-reliable 2-hop $(4 + \varepsilon)$-spanner for $M$, of size

$$ O\left(\frac{nD^2}{\vartheta \log \frac{D}{\vartheta}} \right) = O\left(\frac{\vartheta^{-1} \varepsilon^{-2} n \log^2 \Phi \log \frac{\log \Phi \log n}{\vartheta \varepsilon}}{\vartheta \varepsilon} \right).$$

To get the improved bound on the dilation, let $p,q \in P$ be two points and let $C \subset C$ be the cluster such that $p,q \in C$ and $\text{diam}(C) \leq (2+\varepsilon)d(p,q)$. Assume that $|C| > 2$ (otherwise $C = \{p,q\}$ and there is nothing to prove). By construction, for the separator node $s \in C$, we have $d(s,z) \leq \text{diam}(C)/2$ for all $z \in C$. Observe, that the (shortest) path between $p$ and $q$ in $T$ passes through $s$. Thus, using the triangle inequality, the length of a 2-hop path between $p$ and $q$ via $z \in C$ can be bounded by

$$ d(p,z) + d(z,q) \leq d(p,s) + 2d(s,z) + d(s,q) \leq d(p,q) + 2\text{diam}(C)/2 \leq (3 + \varepsilon)d(p,q). \quad \square$$

**Lemma 5.8.** Let $M = (P,d)$ be a tree metric over $n$ points with spread $\Phi$, and let $\vartheta, \varepsilon \in (0,1)$, and $t \in \mathbb{N}$ be parameters. Then, one can build a $\vartheta$-reliable $(4 + \varepsilon)(t-3)$-spanner for $M$ of size $O(\vartheta^{-2} \varepsilon^{-3} t \cdot n^{1+1/t} \log^3 n \log^3 \Phi)$.

**Proof.** By Lemma 4.11, one can build a $\xi = (2 + \varepsilon/2)$-cover of $T$ of depth $D = O(\varepsilon^{-1} \log \Phi \log n)$ and size $O(nD)$. Plugging this into Lemma 5.2 (A) yields a deterministic $\vartheta$-reliable $(2t-1)\xi$-spanner for $M$, of size

$$ O(\vartheta^{-2} D^3 n^{1+1/t}) = O(\vartheta^{-2} \varepsilon^{-3} t \cdot n^{1+1/t} \log^3 n \log^3 \Phi).$$
To get the improved bound on the dilation, consider a \((2t - 1)\)-hop path \(p = p_0, p_1, \ldots, p_{2t-1} = q\), such that \(p_i \in C\), for all \(i\), for some cluster \(C\). We have
\[
\sum_{i=0}^{2t-2} d(p_i, p_{i+1}) = d(p, p_1) + d(p_{2t-2}, q) + \sum_{i=1}^{2t-3} d(p_i, p_{i+1}) \\
\leq d(p, s) + d(s, p_1) + d(p_{2t-2}, s) + d(s, q) + (2t - 3)diam(C) \\
\leq d(p, q) + (2t - 2)diam(C) \leq (1 + \xi(2t - 2)) \cdot d(p, q)
\]
for the length of the path. Thus, by using \(2 + \varepsilon/2\) for the cover quality, we get
\[
1 + (2t - 2)(2 + \varepsilon/2) = (4 + \varepsilon)t - 3 - \varepsilon \leq (4 + \varepsilon)t - 3.
\]

5.3.4 Planar Graphs.

Lemma 5.9. Let \(G\) be a weighted planar graph with \(n\) vertices and spread \(\Phi\). Furthermore, let \(\vartheta, \varepsilon \in (0, 1)\) be parameters. Then, one can build an oblivious \(\vartheta\)-reliable \((3 + \varepsilon)\)-spanner for \(G\) with \(O\left(\vartheta^{-1} \varepsilon^{-4} n \log(n, \Phi)\right)\) edges, where \(\log(n, \Phi) = \log^2 n \log^2 \Phi \log \frac{\log \Phi \log n}{\vartheta \varepsilon}\).

Proof. By Theorem 4.17, one can build a \((2 + \varepsilon/2)\)-cover of \(G\) of depth \(D = O(\varepsilon^{-2} \log \Phi \log n)\) and size \(O(\vartheta nD)\). Plugging this into Lemma 5.1 yields an oblivious \(\vartheta\)-reliable \(2\)-hop \((1 + \varepsilon)\)-spanner for \(G\), of size \(O\left(\frac{\vartheta^2 \log D}{\vartheta} \log \frac{\Phi}{\vartheta \varepsilon}\right) = O\left(\vartheta^{-1} \varepsilon^{-4} n \log^2 n \log^2 \Phi \log \frac{\log \Phi \log n}{\vartheta \varepsilon}\right)\).

We next show the improved bound on the dilation. Using the notation from Lemma 4.15, for a pair of points \(p, q \in P\), there is a cluster \(C \in C\), such that \(p, q \in C\) and \(diam(C) \leq (2 + \varepsilon)d(p, q)\). Let \(v\) be the point where the cycle separator and the shortest path between \(p\) and \(q\) intersect. Notice, that for the center point \(u \in C\), we have \(d(u, z) \leq diam(C)/2\), for all \(z \in C\). Furthermore, using the notation from the proof of Lemma 4.15, for some \(j\), we have
\[
\frac{d(u, v)}{d(p, q)} \leq \frac{\varepsilon r_j/8}{r_{j-1}} = \frac{\varepsilon}{8} \left(1 + \frac{\varepsilon}{8}\right) \leq \frac{\varepsilon}{4}.
\]
Thus, the length of a 2-hop path between \(p\) and \(q\) via \(z \in C\) can be bounded by
\[
d(p, z) + d(z, q) \leq d(p, v) + 2d(v, u) + 2d(u, z) + d(v, q) \leq d(p, q) + 2 + \frac{\varepsilon}{4} d(p, q) + 2diam(C)/2 \\
\leq \left(1 + \frac{\varepsilon}{2} + 2 + \varepsilon\right) d(p, q) \leq (3 + 2\varepsilon)d(p, q).
\]

Lemma 5.10. Let \(G\) be a weighted planar graph with \(n\) vertices and spread \(\Phi\). Furthermore, let \(\vartheta, \varepsilon \in (0, 1)\) and \(t \in N\) be parameters. Then, one can build a deterministic \(\vartheta\)-reliable \((4 + \varepsilon)t - 3\)-spanner for \(G\) of size \(O(\vartheta^{-2} \varepsilon^{-6} . n^{1+1/t} \log^3 n \log^3 \Phi)\).

Proof. Let \(\vartheta = 2 + \varepsilon/2\). By Theorem 4.17, one can build a \(\xi\)-cover of \(G\) with depth \(D = O(\varepsilon^{-2} \log \Phi \log n)\) and size \(O(\vartheta nD)\). Plugging this into Lemma 5.1 (A) yields a deterministic \(\vartheta\)-reliable \((2t - 1)\xi\)-spanner for \(M\), of size \(O(\vartheta^{-2} \xi^{1+1/t} n^{1+1/t}) = O(\vartheta^{-2} \varepsilon^{-6} . n^{1+1/t} \log^3 n \log^3 \Phi)\).

The improved dilation follows by using the same argument as in the proof of Lemmas 5.8 and 5.9.

6 PROPER EXPANDERS AS RELIABLE SPANNERS FOR UNIFORM METRIC

The purpose of this section is to prove that with the appropriate parameters, proper expanders (as defined in Definition 3.3) and edge-union of proper expanders constitute good reliable spanners for uniform metrics. That is, they satisfy the requirements of Theorem 3.5.
6.1 Preliminaries

In the following, \((n,d)\)-graph denotes a \(d\)-regular, \(n\)-vertex graph. Recall that \(\lambda(G)\) denotes the normalized eigenvalue of \(G\)—that is, the second largest in absolute value (see Definition 3.3).

For a given graph \(G = (V,E)\) and \(S,H \subseteq V\), denote by \(\Gamma_H(S) = \{v \in H \mid \exists u \in S, uv \in E\}\) the neighbors of \(S\) in \(H\). For \(S,T \subseteq V\), denote \(E(S,T) = \{uv \in E \mid u \in S, v \in T\}\).

The following is well known result on expanders, attributed to Alon and Chung [4] in Reference [21, Section 2.4].

**Lemma 6.1 (Expander Mixing Lemma).** Let \(G = (V,E)\) be an \((n,d)\) graph. Then for every \(S,T \subseteq V\),

\[
|E(S,T)| - \frac{\delta|S||T|}{n} \leq \lambda(G)d\sqrt{|S||T|}.
\]

We also need the following lemma, which is a minor variant of known constructions.

**Lemma 6.2 ([11]).** Let \(L,R\) be two disjoint sets, with a total of \(n \in 2\mathbb{N}\) elements, and let \(\xi \in (0,1)\) be a parameter. There exists a bipartite graph \(G = (L \cup R, E)\) with \(O(n/\xi^2)\) edges, such that

(i) for any subset \(X \subseteq L\), with \(|X| \geq \xi|L|\), we have that \(|\Gamma(X)| > (1-\xi)|R|\), and

(ii) for any subset \(Y \subseteq R\), with \(|Y| \geq \xi|R|\), we have that \(|\Gamma(Y)| > (1-\xi)|L|\).

**Remark 5.** The randomized construction of Lemma 6.2 succeeds with probability \(1 - 1/n^{O(1)}\). Since we use the construction below on sets that are polynomially large (i.e., \(n^{1/t}\)), one can use Lemma 6.2 constructively in this case (potentially losing an additional \(\log t\) factor). This also applies to the other expander constructions used in this article. But while the randomized construction works with high probability, verifying it seems computationally intractable.

6.2 Construction of Reliable Spanners from Proper Expanders

Theorem 3.5 states the existence two different spanners and accordingly, we present two different graphs, \(\mathcal{G}_{n,3,2t-1}\) and \(\mathcal{G}_{n,3,2t}\).

We begin with \(\mathcal{G}_{n,3,2t}\). Recall the definition of proper expander (Definition 3.3) with parameter \(\delta\). Fix \(n, t \in \mathbb{N}, n > t\), and \(\delta \in (0,1/4)\) such that

\[
n^{1/t} \geq (c_\delta \delta)^{-1}.
\]

The graph \(\mathcal{G}_{n,3,2t}\) is defined to be an \((n,d)\)-graph that is a proper expander with \(\delta = \delta\), and

\[
d = \left\lceil \max \left\{ 2\delta^{-1}n^{1/t}, 36c_\delta^2 \delta^{-3} \right\} \right\rceil.
\]

To define \(\mathcal{G}_{n,3,2t-1}\), we follow an idea we used slightly inferior construction in a preliminary version of this article, see Reference [20, Section 3.3.1]: Let \(n' = n^{1-1/t}\). Partition the space to \(n^{1/t}\) subsets, \(A_1, \ldots, A_{n^{1/t}}\), each of size \(n'\), and let \(t' = t - 1\). For every \(A_i\) construct a copy of the graph \(\mathcal{G}_{n',3,2t'}\) with \(A_i\) being the vertices. The degree in those graphs is \(d' = O(\delta^{-1}n'^{1/t'}) = O(\delta^{-1}n^{1/t})\).

In addition, for every \(i \neq j\) connect \(A_i\) with \(A_j\) with a bipartite expander \((A_i \cup A_j, E_{ij})\) according to Lemma 6.2, with \(\xi = \delta\). This increases the degree by \(O(\delta^{-2}n^{1/t})\). Thus, the total degree of \(\mathcal{G}_{n,3,2t-1}\) is \(O(\delta^{-2}n^{1/t})\).

6.3 Analysis of \(\mathcal{G}_{n,3,2t}\)

For the rest of Section 6.3, let \(G = \mathcal{G}_{n,3,2t}\), and \(\lambda = \lambda(G)\).
6.3.1 The Shadow of a Bad Set. Let $B \subset V$ an arbitrary subset, such that $(1 + 5\vartheta)|B| < n$ (otherwise, we can choose $B^+ = V$ and there is nothing to prove). Choose

\[
\varepsilon = (1 + \vartheta)(|B|/n + \lambda/\sqrt{n}) \quad \text{(P3)} \quad \text{Equation (4)} \leq (1 + \vartheta)(|B|/n + C/\sqrt{d}) \leq (1 + \vartheta)|B|/n + c_\vartheta \vartheta, \quad (5)
\]

so (recalling that $\delta = \vartheta$, and $c_\delta = c_\vartheta$)

\[
1 - \delta - \varepsilon \geq 1 - \delta - |B|/n - \vartheta|B|/n - c_\vartheta \vartheta \geq 1 - \delta - (1 - 4\vartheta) - \delta - c_\vartheta \vartheta \geq \delta. \quad (6)
\]

Define the “shadows of $B$” as follows. Let $S_0 = \emptyset$, and for $i > 0$ let

\[
S_i = S_{i-1} \cup \{u \in V \setminus (B \cup S_{i-1}) \mid |E(u, B \cup S_{i-1})| \geq \varepsilon d\}. \quad (7)
\]

These are all the “bad” vertices that have a lot of neighbors inside the (growing) bad set $B \cup S_{i-1}$.

Last, set $S = \bigcup_i S_i$ the limit of $S_i$, and $B^+ = B \cup S$.

6.3.2 Bounding the Size of the Shadow. By the construction above of the damaged set $B^+$, for every $u \in V \setminus B^+$,

\[
|E(u, B^+)| < \varepsilon d. \quad (8)
\]

CLAIM 6.1. $|S| \leq \vartheta|B|$.

**Proof.** The argument we use is similar to the one used in the proof of Reference [7, Lemma 5.3]. Let $\Delta_i = S_i \setminus S_{i-1}$. We have that

\[
\varepsilon d|S_i| \leq \varepsilon d \sum_{j=1}^i |\Delta_j| \quad \text{Equation (2)} \leq \sum_{j=1}^i |E(\Delta_j, B \cup S_{j-1})| = |E(S_i, B \cup S_{i-1})| \leq d(|B| + |S_{i-1}|)|S_i|/n + \lambda d\sqrt{(|B| + |S_{i-1}|)|S_i|}. \quad (7)
\]

This implies that $|S_i|(\varepsilon - \frac{|B| + |S_{i-1}|}{n}) \leq \lambda\sqrt{(|B| + |S_{i-1}|)|S_i|}$. Squaring, and dividing by $|S_i|$, we have

\[
|S_i| \left(\varepsilon - \frac{|B| + |S_{i-1}|}{n}\right)^2 \leq \lambda^2(|B| + |S_{i-1}|) \leq \lambda^2(|B| + |S_i|),
\]

which implies, for $\rho_i = \left(\varepsilon - \frac{|B| + |S_{i-1}|}{n}\right)^2$, that

\[
|S_i| \leq \frac{\lambda^2|B|}{\rho_i - \lambda^2}.
\]

We claim that $|S_i| \leq \vartheta|B|$ for every $i$. Indeed, otherwise let $i$ the smallest index such that $|S_i| > \vartheta|B|$. So $|S_{i-1}| \leq \vartheta|B| < |S_i|$. By definition, see Equation (5), we have that $\varepsilon = (1 + \vartheta)(|B|/n + \lambda/\sqrt{n})$ and as such

\[
\rho_i = \left(\varepsilon - \frac{|B| + |S_{i-1}|}{n}\right)^2 \geq (1 + \vartheta)\left(\frac{|B|}{n} + \frac{\lambda}{\sqrt{n}}\right) - (1 + \vartheta)|B|/n \geq 1 + \frac{\vartheta}{\sqrt{n}} \lambda^2.
\]

We thus have that

\[
\vartheta|B| < |S_i| \leq \frac{\lambda^2|B|}{\rho_i - \lambda^2} \leq \frac{\lambda^2|B|}{1 + \vartheta \lambda^2 - \lambda^2} = \vartheta|B|,
\]

which is a contradiction. □
6.3.3 The Expansion Happens Outside the Bad Set.

Claim 6.2. Let \( U \subseteq V \setminus B^+ \). If \(|U| \leq e_\beta \delta n^{1-1/t} \), then \(|\Gamma_{V \setminus B^+}(U)| \geq n^{1/t}|U|\).

Proof. We have
\[
|U| \leq e_\beta \delta n^{1-1/t} = \frac{e_\beta n}{n^{1/t}/\delta} \leq \frac{e_\beta n}{d/2} \leq \frac{e_\beta n}{d},
\]

since \( d \geq 2n^{1/t}/\delta \) by Equation (4). As such, by the expansion property (P2), \(|\Gamma(U)| \geq (1-\delta)d|U|\) (as \( \delta = \delta \)). Furthermore,
\[
|\Gamma_{B^+}(U)| \leq |E(U, B^+)|^t \leq \epsilon d|U|,
\]

so
\[
|\Gamma_{V \setminus B^+}(U)| \geq |\Gamma_U(U)| \geq (1-\delta-e)|d|U| \geq \delta d|U| \geq n^{1/t}|U| \quad \Box.
\]

Let
\[
\mathbb{B}_{G \setminus B^+}(u, i) = \{ v \in V \setminus B^+ \mid d_{G \setminus B^+}(u, v) \leq i \},
\]

the ball of radius \( i \) around \( u \) in the shortest path metric of the graph \( G \setminus B^+ \). Define \( U_0 = \{ u \} \), and \( U_t = \Gamma_{V \setminus B^+}(U_{t-1}) \). Observe that \( \mathbb{B}_{G \setminus B^+}(u, i) = \bigcup_{j=0}^{i} U_j \).

Claim 6.3. \(|\mathbb{B}_{G \setminus B^+}(u, t-1)| \geq n^{1-1/t} \).

Proof. Assume the contrary. Then \(|U_{t-1}| \leq |\mathbb{B}_{G \setminus B^+}(u, t-1)| < n^{1-1/t} \), which implies that there exists \( j < t-1 \) such that \(|U_{j+1}| < |U_t| n^{-1/t} \). From Claim 6.2, this means that \(|U_j| < e_\beta \delta n^{1-1/t} \). So take \( K \subseteq U_j \) such that \(|K| = e_\beta \delta n^{1-1/t} \). Then again by Claim 6.2,
\[
|\mathbb{B}_{G \setminus B^+}(u, t-1)| \geq |\Gamma_{V \setminus B^+}(K)| \geq e_\beta \delta n^{1-1/t} n^{1/t} \quad \geq n^{1-1/t} \quad \Box.
\]

We summarize the relevant properties of \( \mathcal{G}_{n, \delta, 2t} \).

Lemma 6.3. The graph \( \mathcal{G}_{n, \delta, 2t} \) has the following properties. For any \( B \subseteq V \), there exists a set \( B^+ \), \( B \subseteq B^+ \subseteq V \), \(|B^+| \leq (1 + 5\delta)|B| \), such that for any \( u \in V \setminus B^+ \), we have
\[
|\mathbb{B}_{G \setminus B^+}(u, t-1)| \geq n^{1-1/t},
\]
(9)
\[
\Gamma_U(\mathbb{B}_{G \setminus B^+}(u, t-1)) \geq (1-\delta)n, \quad (10)
\]
\[
|\mathbb{B}_{G \setminus B^+}(u, t)| \geq \delta n. \quad (11)
\]

Proof. Recall that when \((1 + 5\delta)|B| \geq n\), we can take \( B^+ = V \) and there is nothing to prove. So assume from now on that \((1 + 5\delta)|B| < n\).

When \( t = 1 \), \( \mathcal{G}_{n, \delta, 2t} \) is the complete graph, and we take \( B^+ = B \). Equation (9) is equivalent to \( 1 \geq 1 \); Equation (10) follows, since \( \Gamma_U(\{u\}) = V \) in complete graph; and Equation (11) follows, simply because \(|B| \leq n/(1+5\delta) \leq (1-\delta)n\).

Assume next that \( t \geq 2 \). Equation (9) is just a repetition of Claim 9. To prove Equation (10). Observe that
\[
|\mathbb{B}_{G \setminus B^+}(u, t-1)| \geq n^{1-1/t} \quad \geq 2n/(\delta d). \quad (4)
\]

We conclude using Property (P1) of proper expanders that
\[
\Gamma_U(\mathbb{B}_{G \setminus B^+}(u, t-1)) \geq (1-\delta)n. \quad (11)
\]

By Claim 6.1,
\[
|B^+| \leq (1 + \delta)|B| \leq (1 + \delta)|\frac{n}{1 + 5\delta}| \leq (1 - 3\delta)n.
\]
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So,
\[ |\mathbb{B}_{G\setminus B^+}(u, t)| \geq |\mathbb{V}_{G\setminus B^+}(u, t-1)| \geq |\mathbb{V}_{U_{t-1}}| - |B^+| \geq \vartheta n. \]

This completes the proof of Lemma 6.3.

**Proposition 6.4.** The graph $\mathcal{S}_{n, \vartheta, 2t}$ is a $\vartheta$-reliable $2t$-spanner for $n$-point uniform space with $O(\vartheta^{-1} n^{1+1/t})$ edges.

**Proof.** Fix $u, v \in V \setminus B^+$. By Equation (10),
\[ \min(|\mathbb{V}_{G\setminus B^+}(u, t-1)|, |\mathbb{V}_{G\setminus B^+}(v, t-1)|) \geq (1-\vartheta)n. \]

So,
\[ |\mathbb{B}_{G\setminus B^+}(u, t) \cap \mathbb{B}_{G\setminus B^+}(v, t)| \geq |\mathbb{V}_{G\setminus B^+}(u, t-1) \cap \mathbb{V}_{G\setminus B^+}(v, t-1)| - |B^+| \]
\[ \geq (1-2\vartheta)n - (1-5\vartheta)n > 0. \]

We conclude that $\mathbb{B}_{G\setminus B^+}(u, t) \cap \mathbb{B}_{G\setminus B^+}(v, t) \neq \emptyset$, which means that there is a path of length at most $2t$ in $G \setminus B^+$ between $u$ and $v$. □

**6.3.4 Proof of Theorem 3.8.**

**Restatement of Theorem 3.8.** For every $\vartheta \in (0, 1)$ there exists a constant $\epsilon = \epsilon_{\vartheta} > 0$, such that for any expansion constant $h \geq \epsilon^{-2}$, there exists a family of vertex expander graphs $\{G = (V, E)\}_n$ on $n$ vertices of degree at most $4h/\vartheta$, with the following resiliency property: For any $B \subset V$, there exists $B^+ \supseteq B$, $|B^+| \leq (1+\vartheta)|B|$ such that the graph $G \setminus B^+$ is a vertex expander in the sense that

(i) $\text{diam}(G \setminus B^+) \leq 2[\log_h \vartheta]$, and

(ii) For any $U \subset V \setminus B^+$ of size $|U| \leq \epsilon n/h$, we have $|\mathbb{V}_{G\setminus B^+}(U)| \geq h|U|$. □

**Proof.** The graphs are simply $\mathcal{S}_{n, \vartheta, 2t}$ for $t = \log_h n$. The claims follow immediately from Claim 6.2 and Proposition 6.4. □

**6.4 Analysis of $\mathcal{S}_{n, \vartheta, 2t-1}$**

**Proposition 6.5.** The graph $\mathcal{S}_{n, \vartheta, 2t-1}$ is $\vartheta$-reliable $(2t-1)$-spanner for $n$-point uniform space with $O(\vartheta^{-2} n^{1+1/t})$ edges.

**Proof.** Recall the definition of $\mathcal{S}_{n, \vartheta, 2t-1}$ from Section 6.2. Let $t' = t - 1$, and $n' = n^{1-1/t}$. Given an attack set $B$, construct $B_{i}^+$ from $A_i \cap B$ according to Lemma 6.3, and define $B^+ = \cup_i B_{i}^+$. Fix $u, v \in V \setminus B^+$. If $u, v \in A_j$, then by Proposition 6.4, there is a path of length $2t' = 2t - 2$ between them.

If $u \in A_i$, $v \in A_j$, $i \neq j$, then by Equation (11), $|\mathbb{B}_{A_i \setminus B^+}(u, t')| \geq \vartheta n'$ and $|\mathbb{B}_{A_j \setminus B^+}(v, t')| \geq \vartheta n'$. By Lemma 6.2, there is an edge in $E_{ij}$ between $\mathbb{B}_{A_i \setminus B^+}(u, t')$ and $\mathbb{B}_{A_j \setminus B^+}(v, t')$, and hence a path of length $2t' + 1 = 2t - 1$ in $G \setminus B^+$. □

**7 CONCLUDING REMARKS AND OPEN PROBLEMS**

**Subsequent work.** Recently, Filtser and Le [17] improved some of the results here. The obtained bounds that do not depend on the spread of the metrics in some cases, for the oblivious adversary case. They also obtained reliable spanners (in the oblivious adversary model) for trees with tight stretch of 2 and for planar graphs with tight stretch of $2 + \epsilon$.
Tradeoffs in deterministic constructions for general spaces. Classical spanners are known to have an approximation-size trade-off for general n-point metrics: To achieve $\Theta(t)$ approximation it is sufficient and necessary to have $n^{1+1/t}$ edges in the worst case. In contrast, for reliable spanners, we were only able to show an upper bound on the trade-off, with no asymptotically matching lower bound: To achieve $O(t^2)$ approximation it is sufficient to have $\tilde{O}(n^{1+1/t})$ edges. Classically, the uniform metric is 2-approximated by a star graph with only $n - 1$ edges. In contrast, we have shown here reliable spanners for uniform metric have approximation-size trade similar to the classical spanner for general metrics. The connection between the two problems is quite intriguing, and is worthy of further research.

The dependence of the size on the spread. The size of spanners constructed in this article depends on the spread of the metric space. This is because of the reduction to uniform spaces via covers, in which the dependence on the spread is unavoidable in general. However, in some setting this dependence is avoidable. For example, References [11, 12] achieve this for fixed-dimensional Euclidean spaces, and Reference [17] achieves it for doubling spaces and general finite spaces in the oblivious adversary model. Getting spread-free bounds for the non-oblivious adversary is an interesting problem for further research.

Explicit constructions. To the best of our knowledge, there is no known polynomial time deterministic algorithm for constructing expanders with Property (P1) or Property (P2). Getting such a construction is an interesting open problem.

APPENDIX

A RANDOM REGULAR GRAPHS

In Theorem 3.4 above, we prove that random construction using a union of random permutations yields a proper expander, see Definition 3.3. The properties are well known and are held by random regular graphs asymptotically almost surely. However, the literature on random regular graphs is more concerned with the setting of constant $d$ and $n$ tends to infinity, especially regarding Property (P3). Here, we need a slightly different range, where $d$ is sufficiently large, and $n \geq d^2$. For completeness, we gather here proofs and references that prove Theorem 3.4.

A.1 Construction

We use the permutation model $G_{n,d}$ for constructing random regular graph (see Reference [33] for other models). Assuming $d$ is even, sample $d/2$ independent and identically distributed random permutations $\pi_1, \ldots, \pi_{d/2} \in S_n$, where $S_n$ is the set of all permutations of $[n] = \{1, \ldots, n\}$. The resulting graph $G = (V, E)$, has $V = [n]$ and

$$E = \{\{i, \pi_j(i)\} \mid i \in [n] \text{ and } j \in [d/2]\}.$$ 

A.2 Analysis

A.2.1 Property (P3). All the proofs that random $d$-regular graphs have second eigenvalue at most $C/\sqrt{d}$ (that we are aware of) are non-trivial. It was first proved in Reference [19], and by now there are many proofs of this. Notably, Friedman [18] showed that random regular graphs are “almost Ramanujan,” i.e., $\lambda \leq \frac{2\sqrt{d-1} + \epsilon}{d}$ with probability $1 - o_n(1)$, see also Reference [31] for a recent and simpler proof. Unfortunately, most of those papers are interested in the settings where the degree $d$ is constant and only the number of vertices $n \to \infty$, which is not suitable for our needs. However, the argument of Kahn and Szemerédi [19] does work when $d$ is allowed to tend to infinity (together with $n$). Specifically, Dumitiriu et al. [15] used it to prove the following.
THEOREM A.1 ([15, THEOREM 24]). Fix $C = 41,000$. There exists $K > 0$ such that for any even $d$ and $n > \max\{K, d\}$, we have $\mathbb{P}[\lambda(G) \leq C/\sqrt{d}] \geq 1 - 2/n^2$, where $\mathbb{P}[\cdot]$ is the probability in the permutation model $\mathcal{G}_{n,d}$.

This implies (P3) holds asymptotically almost surely in the permutation model. Properties (P1) and (P2) are much easier to prove and are considered folklore. They are usually proved in different, more convenient, models of random regular graphs. However, contrary to the case when the degree is fixed, in the high-degree regime the different random models are not necessarily contiguous, i.e., asymptotically almost surely properties are not necessarily equivalent among the different models (for more on this, see Reference [33]). Therefore, for completeness, we next provide proofs that Properties (P1) and (P2) hold asymptotically almost surely in the permutation model.

A.2.2 Property (P1).

Lemma A.2. For integers $s, t, n \geq 0$, such that $s \leq t \leq n$, we have \( \left( \frac{s}{n} \right)^{t} \leq \left( \frac{t}{n} \right)^{s} \).

Similarly, if $s \leq t \leq n$ and $n \geq 3s$, we have \( \left( \frac{s}{2s} \right)^{t} \leq \left( \frac{t}{n} \right)^{s} \left( \frac{2s}{n-3s} \right)^{s} \).

Proof. Observe that for $k \leq m' \leq m$, we have
\[
\frac{m'}{m} \cdot \frac{m' - 1}{m - 1} \cdots \frac{m' - k + 1}{m - k + 1} \leq \left( \frac{m'}{m} \right)^{k},
\]
as $(m' - i)/(m - i) \leq m'/m$. As such, using the (easy to verify) identity $(n_s) = (n_s)^{(n-s)/(2s)}$, we have
\[
\left( \frac{s}{2s} \right)^{t} \leq \left( \frac{t}{n} \right)^{s} \left( \frac{2s}{n-3s} \right)^{s}. \quad \Box
\]

Lemma A.3. Fix sets $S, T \subset V$, with $s = |S|$ and $t = |T|$, such that $|S| \leq |T|$. Then $\mathbb{P}[\Gamma(S) \subseteq T] \leq \left( \frac{t}{n} \right)^{sd/2}$.

Proof. Fix $T' \subseteq T$ of cardinality $|T'| = s$. Then $\mathbb{P}[\pi(S) = T'] = 1/(n_s)$. By the union bound, and Lemma A.2, we have
\[
\mathbb{P}[\pi(S) \subseteq T] = \sum_{T' \in \{T\}} \mathbb{P}[\pi(S) = T'] = \left( \frac{s}{t} \right) \leq \left( \frac{t}{n} \right)^{s}. \quad \Box
\]

Let $\pi_1, \ldots, \pi_{d/2}$ be the permutations used in the construction. We have that
\[
\mathbb{P}[\Gamma(S) \subseteq T] \leq \mathbb{P} \left[ \bigcap_{k=1}^{d/2} \pi_k(S) \subseteq T \right] = \mathbb{P}[\pi(S) \subseteq T]^{d/2} \leq \left( \frac{t}{n} \right)^{sd/2}. \quad \Box
\]

Lemma A.4. Fix $\epsilon, \delta \in (0, 1/2)$. If $\sqrt{n} \geq d \geq 12/(\epsilon \delta)$ is an integer, then asymptotically almost surely over the random $(n, d)$-graph $G = (V, E)$, for any $S \subset V$ with $|S| \geq \epsilon n$, we have $|\Gamma(S)| \geq (1 - \delta)n$. That is, property (P1) of Definition 3.3 holds.

Proof. Using the union bound on the bound established in Lemma A.3, we conclude that the probability that there exists a subset $S$ of size $s = \epsilon n$, such that $|\Gamma(S)| \leq (1 - \delta)n = t$, is at most
\[
\left( \frac{n}{s} \right)^{t} \left( \frac{t}{n} \right)^{sd/2} \leq \left( \frac{\epsilon n}{s} \right)^{s} 2^{n} \left( \frac{t}{n} \right)^{sd/2} \leq \left( \frac{\epsilon}{\epsilon} \right)^{\epsilon n} 2^{n} (1 - \delta)^{\epsilon nd/2} \leq \left( \frac{\epsilon}{\epsilon} \right)^{\epsilon n} 2^{n} \exp(-\delta nd/2)
\]
\[ \leq 2^n \exp \left( \varepsilon n + \varepsilon n \ln \frac{1}{\varepsilon} - 6n \right) \leq \exp (2n + n/e - 6n) \leq \exp (-3n), \]

since \( \max_{x>0} x \ln (1/x) = 1/e \), as easy calculation shows.\(^1\)

A.2.3 Property (P2). The argument above used only the forward edges associated with the \( d/2 \) random permutations. Since there are only \( d/2 \) such edges associated with every vertex, that argument cannot prove vertex-expansion close to \( d \) as is stated in (P2). For this we have to also use the backward edges associated with the permutation as well. Since the backward edges and the forward edges associated with the same random permutation are not stochastically independent, more care is needed to prove this property, as we shall now see.

Claim A.1. Fix \( \varepsilon, \eta \in (0, 1) \) such that \( 0 < \varepsilon < \frac{1}{2a} < \frac{2}{a} < \eta < 1 \). Then,

\[ \Pr[\exists S \subset V, |S| \leq \varepsilon n, |E(S, S)| > \eta d|S|] = O(n^{-0.4}). \]

Proof. Fix \( S \subset V \), of cardinality \( s \leq \varepsilon n \). Observe that

\[ E(S, S) = \{ \{u, \pi_i(u)\} \mid u \in S, \pi_i(u) \in S, \text{ and } i \in [d/2] \}. \]

Fix \( R \subseteq S \times [d/2] \). For any \( (u, i) \in R \), let \( \mathcal{E}_{u,i} \) be the event that \( \pi_i(u) \in S \). The events induced by \( R \), that is \( \{ \mathcal{E}_{u,i} \mid (u, i) \in R \} \) are not independent, but they are non-positively correlated. Indeed, for a set \( R \subset S \times [d/2] \) consider the event \( \mathcal{E}_R = \bigwedge_{(z,j) \in R} \mathcal{E}_{z,j} \). For \( (u, i) \notin R \), we have

\[ \Pr[\pi_i(u) \in S \mid \mathcal{E}_R] \leq \Pr[\pi_i(u) \in S] = \frac{s}{n}. \]

Indeed, observe that all the sub-events in \( \mathcal{E}_R \) involving \( j \neq i \), are irrelevant (that is, stochastically independent of the events \( \mathcal{E}_{x,i} \)). As such, let \( X = \{ x \mid (x, i) \in R \} \). Imagine now picking the permutation \( \pi_i \) by first picking the locations of the elements of \( X \), and then choosing the location of \( u \). Clearly, if the event \( \mathcal{E}_R \) happened, then there are only \( s - |X| \) empty slots in \( S \), and \( n - |X| \) slots available overall. As such, we have that

\[ \Pr[\pi_i(u) \in S \mid \mathcal{E}_R] \leq \frac{s - |X|}{n - |X|} \leq \frac{s}{n} = \Pr[\pi_i(u) \in S]. \]

Now, order the elements of \( R \) in arbitrary order, and let \( R(i) \) be the subset with the first \( i \) elements in that order. We have

\[ \Pr[\mathcal{E}_R] = \prod_{i=1}^{\lvert R \rvert} \Pr[\mathcal{E}_{R(i)} \mid \mathcal{E}_{R(i-1)}] \leq (s/n)^{|R|}. \]

Therefore,

\[ \Pr[|E(S, S)| > \eta ds] \leq \sum_{r=\eta d+1}^{\frac{ds}{2}} \sum_{R \in \binom{V}{\eta d+1}} \Pr[\mathcal{E}_R] \leq \sum_{r=\eta d+1}^{\frac{ds}{2}} \binom{d/2}{r} \left( \frac{s}{n} \right)^r \leq \sum_{r=\eta d+1}^{\frac{ds}{2}} \left( \frac{ed s/2}{r} \cdot \frac{s}{n} \right)^r \]

since the summations behaves like a geometric series, using \( \frac{ed s^2}{2rn} \leq \frac{ed s^2}{2n \eta d s n} = \frac{es}{\eta n} \leq \frac{1}{2} \). Therefore,

\[ \Pr[\exists S \subset V, |S| \leq \varepsilon n, |E(S, S)| > \eta ds] \leq \sum_{s=1}^{\varepsilon n} \binom{n}{s} \left( \frac{es}{\eta n} \right)^{\eta ds} \leq \sum_{s=1}^{\varepsilon n} \left( e^{2} \left( \frac{s}{n} \right)^{\eta d} \eta^{-\eta d} \right)^{s} = O(n^{-0.4}). \]

\(^1\)Indeed, for \( f(x) = x \ln(1/x) \), we have \( f'(x) = -1 + \ln x^{-1} \). Setting \( f'(x) = 0 \), implies \( 1 = \ln x^{-1} \). Namely, the maximum of \( f \) is achieved at \( x = 1/e \), where \( f(1/e) = 1/e \).
The last inequality is derived by partitioning the sum on $s$ up to $2 \log n$—this part is bounded by $O\left(\frac{\log^{1/2} n}{\sqrt{n}}\right)$. The second part of the summation from $2 \log n$ to $\epsilon n$ be bounded by $O((\epsilon/\eta)^{2\log n})$. □

**Lemma A.5.** For every $\delta \in (0, 1/4)$, there exists $c_\delta > 0$, such that for any sufficiently large integer $d \geq e^{32/\delta}$, and any $n \geq d^2$, asymptotically (in $n$) almost surely, a random $(n, d)$ graph $G = (V, E) \sim \mathcal{G}_{n, d}$ have the following vertex expansion property: For any $S \subset V$ with $|S| \leq e^{-2.2/\delta} n/d$, we have $|\Gamma(S)| \geq (1 - \delta)|S|$

That is, Property (P2) of Definition 3.3 holds.

**Proof.** Fix $\eta = \delta/2$. Define $\mathcal{B}$ to be the event, that for all subsets $S \subset V$ of cardinality at most $\epsilon n$, we have that

$$|E(S, S)| \leq \eta d|S|.$$  

By Claim A.1, $\Pr[\mathcal{B}] \geq 1 - O(n^{-0.4})$. So, fix $S \subset V$ of cardinality $s \leq \epsilon n$. The following stochastic process samples a random bijection $\pi$ on $V$ uniformly.

(i) Order the vertices of $S$ arbitrarily $v_1, \ldots, v_s$.
(ii) For $i = 1, \ldots, s$, pick $\pi(v_i)$ uniformly at random from $V \setminus \{\pi(v_1), \ldots, \pi(v_{i-1})\}$.
(iii) Let $U = S \cap \pi(S)$. Reorder the elements of $S$ as $u_1, \ldots, u_s$, such that $U = \{u_{s+1}, \ldots, u_s\}$.
(iv) For $i = 1, \ldots, \ell$, pick $\pi^{-1}(u_i)$ uniformly at random from $V \setminus (S \cup \{\pi^{-1}(u_1), \ldots, \pi^{-1}(u_{i-1})\})$.
(v) Denote by $\pi'$ the partial injection constructed so far.
(vi) Note that, for $i = \ell + 1, \ldots, s$, the element $\pi^{-1}(u_i)$ is already fixed, and it is in $S$, as such we do nothing.
(vii) Complete $\pi'$ to a full permutation by sampling a random bijection $(V \setminus (S \cup \pi'(S))) \mapsto (V \setminus (S \cup \pi'(S)))$.

One can sample random regular graph $G$ from $\mathcal{G}_{n, d}$ by applying the above independently $d/2$ times, and constructing $d/2$ random permutations $\pi_1, \ldots, \pi_{d/2}$.

We next do for a fixed $S \subset V$ of cardinality $s \leq \epsilon n$ the following thought experiment. In the construction of each of the $d/2$ permutation, we replace step (vi) above with the following step generating a new partial injection $\tau$ into $V$, as follows:

(vi) For $i = \ell + 1, \ldots, s$, pick $\tau^{-1}(u_i)$ randomly and uniformly from $V \setminus (S \cup \{\pi^{-1}(u_1), \ldots, \pi^{-1}(u_\ell), \tau^{-1}(u_{\ell+1}), \ldots, \tau^{-1}(u_{i-1})\})$.

Denote by $\tau_i = \tau_i^S$ that random partial injection. Denote

$$F_S = \{u, \tau_i^{-1}(u) \mid i \in [d/2], u \in S \cap \pi_i(S)\}$$

the set of auxiliary edges associated with the above process for $S$. Denote $G_S = (V, E \cup F_S)$—it is the result of redirecting all the edges of $E(S, S)$ to be outside the $S \times S$ biclique. The graph $G_S$ is randomly generated, but the content of $F_S$ is not measurable in $\mathcal{G}_{n, d}$—meaning that the underline probability spaces is more refined than $\mathcal{G}_{n, d}$. We denote by $\mathcal{G}_{n, d}$ a probability space from which one can sample all of $G_S$. That is, it contains $d/2$ random permutations $\pi_1, \ldots, \pi_{d/2}$ that constitute $\mathcal{G}_{n, d}$ and all the relevant partial injections $\tau_i^S$.

Note that $|F_S| = |E(S, S)|$, and therefore depends only on $\mathcal{G}_{n, d}$. Furthermore, if $G \in \mathcal{B}$, then for every $S \subset V$, with cardinality at most $\epsilon n$, we have that $|F_S| \leq \eta d|S|$. Hence, conditioned on $\mathcal{B}$, for any such $S$,

$$|\Gamma_G(S)| \geq |\Gamma_{G_S}(S)| - \eta d|S|. \quad (12)$$

We next bound for a fixed $S \subset V$ of cardinality $s \leq \epsilon n$, the probability that there exists a subset $T$ of cardinality $t$ for which $\Gamma_G(S) \subseteq T$. Begin by fixing $S \subseteq T \subseteq V$ of cardinality $|T| = t$. We
claim that
\[ \Pr \left[ \pi(S) \cup \pi^{-1}(S) \cup \tau^{-1}(S \cap \pi(S)) \subseteq T \right] \leq \left( \frac{t}{n} \right)^{2s} . \] (13)
Indeed, fix \( T' \subset T \) of cardinality \( s \). Then,
\[ \Pr [ \pi(S) = T'] \leq \left( \frac{n}{s} \right)^{-1} . \]
Fix \( T'' \subset V \setminus S \) of cardinality \( s \). Recall that we denoted by \( \pi' \subset \pi \) the partial injection sampled at the end of step (v) in the sampling process described above. Observe that conditioned on \( \pi(S) = T' \) the partial injection \( \pi'^{-1} \cup \tau^{-1} : S \rightarrow V \setminus S \) is also uniformly random, and therefore,
\[ \Pr [ (\pi'^{-1} \cup \tau^{-1})(S) = T'' | \pi(S) = T'] \leq \left( \frac{n-s}{s} \right)^{-1} . \]
Hence,
\[
\Pr [ \pi(S) \cup \pi^{-1}(S) \cup \tau^{-1}(S \cap \pi(S)) \subseteq T ] = \Pr \left[ \bigvee_{T' \subset T, |T'|=s} \bigvee_{T'' \subset T \setminus T', |T''|=s} \pi(S) = T' \land (\pi'^{-1} \cup \tau^{-1})(S) = T'' \right ] \\
\leq \sum_{T' \subset T, |T'|=s} \sum_{T'' \subset T \setminus T', |T''|=s} \Pr [ \pi(S) = T' ] \cdot \Pr [ (\pi'^{-1} \cup \tau^{-1})(S) = T'' | \pi(S) = T' ] \\
= \frac{(t^s)}{\binom{n}{s}} \frac{(t-s)^s}{\binom{n-s}{s}} \leq \left( \frac{t}{n} \right)^s \left( \frac{t-s}{n-s} \right)^s \leq \left( \frac{t}{n} \right)^{2s} ,
\]
which completes the proof of Equation (13).

The probability on \( \{G_S\}_{S \subset V} \sim \mathcal{G}_{n,d} \) that there exists \( S \subset V \) of cardinality at most \( \varepsilon n \) for which \( |\Gamma_{G_S}(S)| \leq t \), where \( t = (1-\eta)ds \) is at most the probability that there exists \( T \subset V \setminus S \) of cardinality \( t \) for which \( \Gamma_{G_S}(S) \subseteq T \cup S \). By the union bound and Equation (13), this is at most
\[
\sum_{s=1}^{n} \binom{n}{s} \binom{n-s}{t} \left( \left( \frac{t+s}{n} \right)^{2d/2} \right)^{d/2} .
\]
We bound the summand above by
\[
\binom{n}{s} \binom{n-s}{t} \left( \frac{t+s}{n} \right)^{sd} \leq \binom{n}{s} \binom{n}{t} \left( \frac{t+s}{n} \right)^{sd} \\
\leq \left( \frac{en}{s} \right)^s \left( \frac{en}{(1-\eta)ds} \right)^{(1-\eta)ds} \left( \frac{1-\eta)ds + s}{n} \right)^{ds} \\
\leq e^{(1-\eta)d+1} (1-\eta)d \left( \frac{1-\eta)ds + 1}{(1-\eta)ds} \right) \left( \frac{1-\eta)ds}{n} \right)^{\eta d-1} s \\
\leq e^{d} d e^{1/(1-\eta)} \frac{ds}{n} \eta d-1 s \\
\leq 4 e^{d} \frac{ds}{n} \eta d-1 s .
\]
To bound the above, we let \( \varepsilon = e^{-1-1/\eta} / d \), and we do a case analysis according to the value of \( s \).
For $3 \log_2 n \leq s \leq e^{-1.1/n/d}$, we have
$$\left(4e^d d \left(\frac{ds}{n}\right)^{\eta d - 1}\right)^s \leq \left(4e^d d e^{-1.1/d} e^{1.1/n}\right)^s \leq 2^{-s} \leq n^{-2}.$$ 

For $1 \leq s \leq 3 \log_2 n$, we have
$$\left(4e^d d \left(\frac{ds}{n}\right)^{\eta d - 1}\right)^s \leq \left(4e^d d \left(\frac{3 \log_2 n}{\sqrt{n}}\right)^{\eta d - 1}\right)^s \leq \left(4d \left(\frac{e^{1.1/3} \log_2 n}{\sqrt{n}}\right)^{\eta d - 1}\right)^s \leq \left(d \left(\frac{1}{n^{6/16}}\right)^{\eta d - 1}\right)^s \leq n^{-2}.$$ 

Summing the above over $s = 1, \ldots, e^{-1.1/n/d}$, we have
$$\mathbb{P}_{G_{\delta}} \left[ \forall S \subset V, |S| \leq e^{-1.1/n/d} \implies |\Gamma_{G_{\delta}}(S)| \geq (1 - \eta)|S| \right] \geq 1 - O(n^{-1}).$$

So, conditioned on $\mathcal{B}$, by Equation (12), $\forall S \subset V, |S| \leq e^{-1.1/n/d}$, we have
$$|\Gamma_G(S)| \geq |\Gamma_{G_{\delta}}(S)| - \eta|S|.$$ 

Since $\Pr_{G_{\delta}}[\mathcal{B}] \geq 1 - O(n^{-0.4})$, we conclude
$$\mathbb{P}_{G - G_{\delta}} \left[ \forall S \subset V, |S| \leq e^{-1.1/n/d} \implies |\Gamma_G(S)| \geq (1 - 2\eta)|S| \right] \geq 1 - O(n^{-0.4}). \quad \square$$ 

### A.3 Summary

**Restatement of Theorem 3.4.** The random graph constructed in Section A.1 is a proper expander (see Definition 3.3), asymptotically almost surely. Specifically, the probability the graph has the desired properties is $\geq 1 - n^{-O(1)}$.

**Proof.** Property (P1) is proved in Lemma A.4. Property (P2) is proved in Lemma (P2). Property (P3) follows from Theorem A.1. \qed

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