THE OBLIQUE ORBIT OF THE SUPER-NEPTUNE HAT-P-11b

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ABSTRACT

We find the orbit of the Neptune-sized exoplanet HAT-P-11b to be highly inclined relative to the equatorial plane of its host star. This conclusion is based on spectroscopic observations of two transits, which allowed the Rossiter–McLaughlin effect to be detected with an amplitude of 1.5 m s\(^{-1}\). The sky-projected obliquity is 103\(^{+26}_{-10}\) deg. This is the smallest exoplanet for which spin–orbit alignment has been measured. The result favors a migration scenario involving few-body interactions followed by tidal dissipation. This finding also conforms with the pattern that the systems with the weakest tidal interactions have the widest spread in obliquities. We predict that the high obliquity of HAT-P-11 will be manifest in transit light curves from the kepler spacecraft: starspot-crossing anomalies will recur at most once per stellar rotation period, rather than once per orbital period as they would for a well-aligned system.

Key words: planetary systems – planets and satellites: formation – planet–star interactions – stars: rotation

Online-only material: color figures, machine-readable table

1. INTRODUCTION

The origin of close-in planets is the longest-standing problem in exoplanetary science (Mayor & Queloz 1995). Recently, the orbits of some close-in planets were found to be highly inclined relative to the equatorial planes of their host stars (see, e.g., Hébrard et al. 2008; Narita et al. 2009; Winn et al. 2009; Triaud et al. 2010). This evidence supports theories for close-in planets in which their orbits shrink due to gravitational perturbations from other bodies followed by tidal dissipation (Matsumura et al. 2010). The evidence disfavors the other leading theory, in which the orbits shrink due to gradual interactions with the protoplanetary gas disk, unless the disks were somehow misaligned with their host stars (Bate et al. 2010; Lai et al. 2010).

To this point, spin–orbit alignment has been measured only for “hot Jupiters,” with masses ranging from 0.4 to 20 M\(_{\text{Jup}}\). We would like to extend these studies to smaller planets, in order to see whether they migrate in a similar way as larger planets and to understand which factors are associated with orbital misalignment. It has been claimed, for example, that tilted orbits are more prevalent for massive planets (Johnson et al. 2009; Hébrard et al. 2010) or for stars with thinner convection zones (Winn et al. 2010; Schlaufman 2010).

Here, we present a spin–orbit study of HAT-P-11b, a “hot Neptune” of mass 0.08 M\(_{\text{Jup}}\) and radius 0.42 R\(_{\text{Jup}}\) on an eccentric, 4.9 day orbit around a K4 dwarf (Bakos et al. 2010, B10 hereafter). We observed the Rossiter–McLaughlin (RM) effect (Section 2), and modeled it (Section 3), finding the orbit and stellar spin to be misaligned (Section 4).

2. OBSERVATIONS AND DATA REDUCTION

We obtained 132 new spectra of HAT-P-11 with the High Resolution Spectrograph (HIRES; Vogt et al. 1994) on the Keck I 10 m telescope. Most of the new spectra were gathered on nights when transits were predicted. On 2009 August 2/3, we gathered seven spectra during a transit, although fog prevented us from observing before or after the transit. On 2010 May 26/27, we obtained 32 spectra starting at around first contact and extending for a few hours beyond the transit. On 2010 August 22/23, we obtained 70 spectra spanning the entire transit and a few hours beforehand and afterward. The remaining 23 spectra were obtained sporadically throughout the 2009–2010 observing season.

We used the instrument settings and observing procedures that are standard for the California Planet Search (Howard et al. 2009). In particular, we used an iodine gas absorption cell to track the instrumental response and wavelength scale. The radial velocity (RV) of each spectrum was measured with respect to an iodine-free template spectrum, using a descendant of the algorithm of Butler et al. (1996). Measurement errors were estimated from the scatter among the fits to individual spectral segments spanning a few Angstroms. Table 1 gives all the Keck/HIRES RVs, including re-reductions of the 50 spectra presented by B10.

3. ANALYSIS

Merging all the RVs into a single analysis requires some care because the host star is chromospherically active. B10 found a photometric signal with period 29.2 days and amplitude 3 mmag, which they attributed to starspots being carried around by stellar rotation. One would expect a corresponding RV signal at the same period and its harmonics, with an amplitude of order 0.3% of the projected stellar rotation speed (v sin i\(_*\)), or

\[ v \sin i_\star \approx \frac{v}{2} \]
approximately 5 m s\(^{-1}\). Indeed, B10 found evidence for “stellar jitter” of amplitude 5 m s\(^{-1}\), supporting this interpretation.

We investigated this issue by fitting the out-of-transit RVs with a model consisting of a single Keplerian orbit plus a constant acceleration,\(^8\) and seeking evidence for time-correlated residuals. As seen in Figure 1, the residuals are strongly correlated on timescales shorter than 5–10 days, as expected. On longer timescales there are no obvious correlations.

While it would be possible to model the RV covariances, we chose the simpler approach of selecting a subset of RVs that are effectively independent. Specifically, we chose a single spectrum from each observing run, resulting in a sample of 21 out-of-transit RVs spaced apart by a minimum of 20 days.

We turn now to the transit nights. During a single night, one would expect the rotationally modulated RV signal to act as a nearly constant offset. Therefore, each transit night was assigned a free parameter that shifts all the RVs by a common amount; only the intranight variations were deemed significant. With this approach the data from 2009 August 2\(^3\) were rendered useless, because no data were gathered outside of the transit. We omitted those data from further consideration.

Our model for the RVs was the sum of the Keplerian orbital motion, a constant acceleration, the RM effect, and the offsets described above. The fitting statistic was

\[
\chi^2 = \sum_{i=1}^{123} \left( \frac{\text{RV}_{i,\text{obs}} - \text{RV}_{i,\text{calc}}}{\sigma_i} \right)^2 \\
+ \left( \frac{\text{BJD}_c - 2.45460589132}{0.00032} \right)^2 \\
+ \left( \frac{P_{\text{days}} - 4.8878162}{0.0000071} \right)^2 + \left( \frac{T_{\text{days}} - 0.0957}{0.0012} \right)^2 \\
+ \left( \frac{\tau_{\text{days}} - 0.0051}{0.0013} \right)^2 + \left( \frac{R_p/R_* - 0.0576}{0.0009} \right)^2 \\
+ \left( \frac{R_*/R_\odot - 0.752}{0.021} \right)^2 + \left( \frac{v \sin \iota_* - 1.5 \text{ km s}^{-1}}{1.5 \text{ km s}^{-1}} \right)^2,
\]

where the first term is the usual sum of squared residuals, and the other terms represent a priori constraints on parameters that were determined more precisely from the larger body of data analyzed by B10. In this expression, \(P_{\text{days}}\) is the orbital period in days, BJD, \(T_{\text{days}}\) is the time between first and fourth contact, \(R_\odot\) is the radius of the sun, and \(v \sin \iota_*\) is the star’s sky-projected rotation speed.

Each of the 21 orbital RVs was assigned an error bar \(\sigma_i\) equal to the quadrature sum of the measurement error and a “jitter” of 5.5 m s\(^{-1}\), the value giving \(\chi^2 = N_{\text{dof}}\) when the orbital RVs were fitted alone. For the transit-night RVs, the jitter was fixed by the requirement \(\chi^2 = N_{\text{dof}}\) when fitting the data from that night along with the orbital RVs. The results were 1.8 and 1.5 m s\(^{-1}\) for 2010 May 26\(\text{/}27\) and 2010 August 22\(\text{/}23\), respectively. The relative smallness of these values corroborates our assumption that the activity-induced RV variations occur mainly on longer timescales. A similar contrast between intranight and internight jitter was observed previously for HD 189733, another active K star (Winn et al. 2006).

We modeled the RM effect with the technique described by Winn et al. (2005), finding in this case that a sufficiently accurate description for the RV shift is the product of the loss of light and the RV of the portion of the stellar photosphere beneath the planet. We neglected differential rotation and took the stellar limb-darkening law to be linear with a coefficient of 0.79 (Claret 2004).

Parameter optimization and error estimation were achieved with a Markov Chain Monte Carlo algorithm, using Gibbs sampling and Metropolis–Hastings stepping. Table 2 gives the results for each parameter, based on the 15.85%, 50%, and 84.15% confidence levels of the marginalized posteriori distributions. Figure 2 shows the RV data: the left panel shows the orbital RVs; and the right panel shows the transit-night RVs after subtracting the calculated variation due to orbital motion, thereby isolating the “anomalous RV” due to the RM effect. Figure 3 shows the a posteriori distributions for the key parameters \(v \sin \iota_*\) and \(\lambda\) (the sky position angle from the stellar north pole to the orbital north pole).

The most important result is \(\lambda = 103^{+26}_{-10}\) deg, indicating a major misalignment between the stellar rotation axis and the orbit normal. Qualitatively this follows from the observation that the RM effect was observed to be a blueshift throughout

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\(\text{Table 1: Relative RV Measurements of HAT-P-11} \)

| BJD\(_{\text{UTC}}\) | RV (m s\(^{-1}\)) | Error (m s\(^{-1}\)) |
|-------------------|----------------|------------------|
| 2454335.89332     | -1.33          | 1.01             |
| 2454335.89998      | -2.66          | 1.03             |
| 2454336.74876      | -1.30          | 0.90             |
| 2454336.86163      | -4.74          | 1.02             |
| 2454336.94961      | -7.56          | 0.94             |

Notes. The RV was measured relative to an arbitrary template spectrum; only the differences are significant. The uncertainty given in Column 3 is the internal error only and does not account for any possible “stellar jitter.” (This table is available in its entirety in a machine-readable form in the online journal. A portion is shown here for guidance regarding its form and content.)

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\(\text{Figure 1: Correlations of the RV residuals. Top: products of pairs of residuals, as a function of the time elapsed between the observations. Significant positive correlations are seen for } \Delta t \lesssim 5 \text{ days. Bottom: same, but restricting the analysis to only one data point per observing run, giving a minimum time separation of } 20 \text{ days. No significant correlations are seen.}\)
Figure 2. RVs and the RM effect. Left: spectroscopic orbit of HAT-P-11, based on the subset of 21 RVs analyzed here. Right: anomalous RV of HAT-P-11 spanning two transits (top and bottom), and the time-binned combination (middle; binned × 7 with a maximum bin size of 0.5 hr). The orbital contribution to the RV has been subtracted. The solid line shows the best-fitting model of the RM effect. The dashed curve shows the best-fitting “well-aligned” model ($\lambda = 0, v \sin i = 1.3 \text{ km s}^{-1}$), which is ruled out with $\Delta \chi^2 = 52.4$.

(A color version of this figure is available in the online journal.)

Figure 3. Results for the RM parameters. Left: in this polar plot, the angular coordinate is $\lambda$ and the radial coordinate is $p(\lambda)$, the marginalized posterior probability distribution. Results are shown for analyses based only on individual transits as well as for the entire data set. Right: joint constraints on $\lambda$ and $v \sin i \star$. The contours represent 68%, 95%, and 99.73% confidence limits. The marginalized posterior probability distributions are shown on the sides of the contour plot. The dashed histogram shows the a priori constraint on $v \sin i \star$, the other parameter of greatest relevance to the RM effect. The results were $v \sin i \star = 1.13^{+0.44}_{-0.70}$ km s$^{-1}$ and $\lambda = 100^{\circ}$ deg. Third, we checked for any correlations between the RM signal and the strength of Ca ii H and K emission or the shape parameters of the instrumental line-spread function. Significant correlations would have raised suspicion of systematic errors, but none were found.

In addition, if the 29.2 day periodicity detected by B10 is indeed the rotation period, then a powerful test for spin–orbit misalignment is available. If the system were well aligned, we would have $\lambda = 0$ and $i \approx 90^\circ$. This would imply

$$v \sin i \star = v = \frac{2\pi R \star}{P_{\text{rot}}} = 1.30 \text{ km s}^{-1},$$

where $R \star$ denotes the stellar radius and $P_{\text{rot}}$ the rotation period. The results were consistent with this prediction.

(A color version of this figure is available in the online journal.)

the transit, as opposed to the “red-then-blue” pattern of a well-aligned system.

4. DISCUSSION

Because the signal has an amplitude of only 1.5 m s$^{-1}$, smaller than any other RM signal yet reported, it is important to test the robustness of the results. First, we tried analyzing each transit individually, rather than combining the data from both transits. As shown in Figure 3, the results are in good agreement.$^9$ Second, we repeated the analysis without the a priori constraint on $v \sin i \star$, the other parameter of greatest relevance to the RM effect. The results were $v \sin i \star = 1.13^{+0.44}_{-0.70}$ km s$^{-1}$ and $\lambda = 100^{\circ}$. Third, we checked for any correlations between the RM signal and the strength of Ca ii H and K emission or the shape parameters of the instrumental line-spread function. Significant correlations would have raised suspicion of systematic errors, but none were found.

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$^9$ In fact there are three mutually reinforcing data sets: Hirano et al. have submitted a paper reporting $\lambda \approx 100^\circ$ based on independent observations of HAT-P-11b (T. Hirano and N. Narita 2010, private communication).
where we have used $R_\star = 0.752 \, R_\odot$ and $P_{\text{rot}} = 29.2$ days (B10). When refitting the data with these constraints, the minimum $\chi^2$ rises from 111.9 to 164.3 ($\Delta \chi^2 = 52.4$), with 114 degrees of freedom. Thus, the well-aligned model is ruled out with $7.2\sigma$ confidence: either $\lambda$ is large, or else $i_\star$ must be far from 90$^\circ$ to be compatible with the low amplitude of the RM signal. The best-fitting well-aligned model is illustrated with a gray dashed curve in Figure 3.

HAT-P-11b is the first “hot Neptune” for which the RM effect has been measured. Our results suggest that tilted orbits are common for hot Neptunes, just as has been found for hot Jupiters. The same migration mechanisms that are invoked to explain the larger planets with tilted orbits—gravitational scattering by planets, or the three-body Kozai effect—may also have operated in this case. It should be noted that the spin–orbit results are not the only evidence for a perturbative origin for many close-in planets. Further evidence comes from their occasionally high orbital eccentricities, the clustering of their orbital distances near the value expected from tidal circularization, and their tendency to lack companions with periods between 10 and 100 days (Matsumura et al. 2010).

Since HAT-P-11b is the lowest-mass planet yet probed by RM measurements and it is misaligned, our findings are at odds with the hypothesis that misalignments occur mainly for the most massive planets (Johnson et al. 2009). They do, however, support the correlation between large obliquity and orbital eccentricity (Johnson et al. 2009; Hébrard et al. 2010), as the orbit of HAT-P-11b has a significant eccentricity.

Another emerging trend is that misalignments occur mainly for stars with high effective temperatures or large masses ($T_{\text{eff}} > 6250$ K or $M_\star \gtrsim 1.2 M_\odot$). Winn et al. (2010) speculated that this is due to tidal interactions: cool stars realign with the orbits, but hot stars cannot realign because tidal dissipation is weaker in their thinner outer convection zones. The HAT-P-11 system is an important test case because the star is cool and low mass, and yet tidal interactions are weak due to the planet’s relatively small size and long period. If stellar temperature and mass are the determinants then one would expect HAT-P-11 to be well aligned like other cool stars. But if tides are the underlying factor, then HAT-P-11 would be misaligned, as we have observed. Specifically, with reference to Equation (2) of Winn et al. (2010), HAT-P-11 experiences even weaker tides than WASP-8, a cool star already known to have a high obliquity. Thus, HAT-P-11 is a telling exception to the rule that hot stars have high obliquities: it implicates tidal evolution as the reason for low obliquities among cool stars with more massive planets in tighter orbits.

By good fortune, HAT-P-11 is in the field of view of the Kepler spacecraft (Borucki et al. 2010). The precise photometric time series will allow the candidate 29.2 day rotation period to be checked. Astroseismological studies may reveal the stellar mean density, age, inclination, and other parameters (Christensen-Dalsgaard et al. 2010). Furthermore, we predict that Kepler will see a pattern of anomalies in the transit light curves that will betray the system’s spin–orbit misalignment. As usual for a spotted star, there will be a “bump” or “rebrightening” in the transit light curve whenever the planet occults a starspot (see, e.g., Rabus et al. 2009). For a well-aligned star, the bumps recur in successive transits for as long as the spot is on the visible hemisphere. There is a steady advance in phase of the bumps due to the star’s rotation between transits. However, for a star like HAT-P-11 with $\lambda \approx 90^\circ$, the events will not recur in this manner, because the star’s rotation moves the spot away from the transit chord. A spot must complete a full rotation before returning to the transit chord, and even then, the planet will miss it unless it has also completed an integral number of orbits.

For HAT-P-11, it happens that $P_{\text{rot}}/P_{\text{orb}} \approx 6$. If the star were well aligned and had one spot initially on the transit chord, then we would typically see an alternation between 2 and 3 light curves with bumps, and 2 and 3 without bumps (when the spot is on the far side). But because of the misalignment, spot anomalies will only recur every 29.2 days, after the star has rotated once and the planet has completed six orbits. Complications may arise due to differential rotation as well as the multiplicity and evolution of spot patterns. Nevertheless, this phenomenon should allow for an independent test of spin–orbit misalignment for HAT-P-11 as well as other spotted stars.

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Matsumura et al. (2010) have also argued that tidal dissipation in the HAT-P-11 system would be too weak to realign the star with the orbit, despite the star’s thick outer convective zone.

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Table 2

| Parameter | Model Parameters |
|-----------|------------------|
| Orbital period, $P$ (days) | 4.88781501 ± 0.00000068 |
| Midtransit time (BJDUTC) | 2.454.605.89130 ± 0.00032 |
| Planet-to-star radius ratio, $R_p/R_\star$ | 0.0576 ± 0.00090 |
| Orbits inclination, $i$ (deg) | 89.175 ± 0.60 |
| RV offset, 2010 May 26 | 0.0673 ± 0.0018 |

Parameters controlled mainly by RV data

| Parameter | Value |
|-----------|-------|
| Velocity semi-amplitude, $K$ (m s$^{-1}$) | 12.9 ± 1.4 |
| $e \cos \omega$ | 0.261 ± 0.082 |
| $e \sin \omega$ | 0.085 ± 0.043 |
| RV offset, 2010 May 26 (m s$^{-1}$) | −19.8 ± 3.9 |
| RV offset, 2010 Aug 22/23 (m s$^{-1}$) | −17.5 ± 4.2 |
| RV offset, all other data (m s$^{-1}$) | −13.0 ± 2.2 |
| RV trend, $\gamma$ (m s$^{-1}$ day$^{-1}$) | 0.0185 ± 0.0036 |
| Projected stellar rotation rate, $\nu \sin i_\star$ (km s$^{-1}$) | 10.00 ± 0.56 |
| Projected spin–orbit angle, $\lambda$ (deg) | 103° ± 26° |

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