DENSITY ESTIMATES FOR PHASE TRANSITIONS WITH A TRACE

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Abstract. We consider a functional obtained by adding a trace term to the Allen-Cahn phase segregation model and we prove some density estimates for the level sets of the interfaces.

We treat in a unified way also the cases of possible degeneracy and singularity of the ellipticity of the model and the quasiminimal case.

1. Introduction

Let \( p \in (1, +\infty) \), \( n \geq 2 \) and \( \Omega \) be an open bounded subset of \( \mathbb{R}^n \). For any \( u \in W^{1,p}_{\text{loc}}(\mathbb{R}^n, [-1, 1]) \), we define the functional

\[
\mathcal{E}_\Omega(u) := \int_{\Omega \cap \mathbb{R}_+^n} |\nabla u(x)|^p \, dx + \int_{\Omega \cap \{x_n = 0\}} G(u(x', 0)) \, dx',
\]

where we used the notation \( x := (x', x_n) \in \mathbb{R}^{n-1} \times \mathbb{R} \) and \( \mathbb{R}_+^n := \mathbb{R}^{n-1} \times (0, +\infty) \). Also, for any \( R > 0 \) and any \( x \in \mathbb{R}^n \), we denote by \( B_R^p(x) \) the Euclidean, open, \( n \)-dimensional ball centered at \( x \), and \( B_R^p = B_R^p(0) \). We set \( B_R^p(x) := B_R^p(x) \cap \mathbb{R}^n_+ \), \( B_R^n := B_R^n(0) \), and we use the short notation

\[
\mathcal{E}_{R,x_0}(u) := \mathcal{E}_{B_R^p(x_0)}(u) = \int_{B_R^p(x_0)} |\nabla u(x)|^p + F(u(x)) \, dx + \int_{B_R^{n-1}(x_0)} G(u(x', 0)) \, dx'.
\]

We will suppose that \( F \) and \( G \) are non-negative “double-well” potentials. More precisely, and in fact more generally, we assume that there exists \( C_o \geq 1 \) such that, for any \( \tau \in \mathbb{R} \), we have

\[
\max\{F(\tau), G(\tau)\} \leq C_o(1 - \tau^2)^p \quad \text{and} \quad F(\tau) \geq \frac{1}{C_o}(1 - \tau^2)^p.
\]

A paradigmatic example is given by \( F(\tau) = G(\tau) = (1 - \tau^2)^p \), but more general potentials are allowed by (2). The gradient term in (1) is reminiscent of a \( p \)-Laplacian partial differential equation (hence, it encodes a possibly singular or degenerate ellipticity). We remark that the functional in (1) reduces to the standard Allen-Cahn phase segregation model when \( G \) is identically zero and \( \Omega \) lies in \( \{x_n > 0\} \). Thus, in a sense, the functional in (1) represents a phase transition in \( \mathbb{R}^n_+ \) with a double-well \( G \) keeping track of a phase segregation on the trace of \( \Omega \) along \( \{x_n = 0\} \) and it may be seen as a toy-model to understand the more complicated phenomena arising in non-local phase transitions, which have been the object of an extensive study in recent years (see, among the others, [ABS94, AB98, ABS98, Gon09] and also [CSM05, SV09a, SV09b, CC10] for a relation between fractional operators and boundary inequalities).
reactions). In practical situations, the non-local effects may be the consequence of a long-range interaction between particles, as it happens in some statistical mechanics models (see, e.g., [DO10]).

The trace term \[ \int_{\Omega \cap \{x_n=0\}} G(u(x',0)) \, dx' \]
may also be considered as a model for taking into account the effect of the boundary of the container in which the phase transition occurs: in this framework, the container is \( \mathbb{R}^n_+ \), which, of course, up to a blow up, is a simplified, but effective, version of a smooth container when we are interested in the behavior near its boundary. In this sense, we hope that this paper may be as a first step towards a more comprehensive study of the geometric features of the phase transitions under even more severe boundary and non-local effects.

Given \( Q \geq 1 \), we say that \( u \) is a \( Q \)-minimizer if
\[
\mathcal{E}_\Omega(u) < +\infty \quad \text{and} \quad \mathcal{E}_\Omega(u + \varphi) \leq Q \mathcal{E}_\Omega(u) \quad \text{for all bounded and open } \Omega \subset \mathbb{R}^n \quad \text{and all Lipschitz continuous functions } \varphi \text{ supported in } \Omega.
\]

The case of \( Q \)-minimizers in a fixed domain \( \Omega_o \) may be treated in a similar way (just suppose that \( \Omega \subseteq \Omega_o \) in (3) and so on). The study of \( Q \)-minimizers is a classical topic in the calculus of variations (see, e.g., [GG84]). When \( Q = 1 \) in (3), \( u \) is usually said to be a minimizer. It is easily seen that when \( p = 2 \) the minimizers satisfy the partial differential equation problem with Neumann condition
\[
\begin{cases}
2\Delta u = F'(u) & \text{in } \mathbb{R}^n_+,
2\partial_{x_n} u = G'(u) & \text{on } \{x_n = 0\}.
\end{cases}
\]

Such type of problems have been studied in [CSM05, SV09a]. Analogously, the minimizers for \( p \in (1,2) \cup (2, +\infty) \) satisfy a quasilinear partial differential equation whose ellipticity becomes singular or degenerate at the critical points of the solution, and the corresponding Neumann condition becomes non-linear too: these types of problem have been studied, for instance, in [SV09b].

This is the main result of this paper:

**Theorem 1.** Let \( \mathcal{L}^n \) denote the \( n \)-dimensional Lebesgue measure. Let \( u \) be a Lipschitz continuous \( Q \)-minimizer.

Then, there exists a positive \( C_\ast \), only depending on \( n, Q, p \), the quantity \( C_0 \) in (2) and the Lipschitz constant of \( u \), such that
\[
\mathcal{E}_{R,x_o}(u) \leq C_\ast R^{n-1}
\]
for any \( x_o \in \mathbb{R}^n_+ \) and any \( R \geq 1 \).

Furthermore, given any \( \theta \in (-1,1) \), if we suppose that there exist two positive real numbers \( \mu_1 \) and \( \mu_2 \) such that
\[
\mathcal{L}^n\left( B^{+}_{\mu_1}(x_o) \cap \{u > \theta\} \right) \geq \mu_2,
\]
then there exist positive \( r_0 \) and \( c \), which depend only on \( n, Q, p, \theta, \mu_1, \mu_2 \), the quantity \( C_0 \) in (2) and the Lipschitz constant of \( u \), in such a way that
\[
\mathcal{L}^n\left( B^{+}_r(x_o) \cap \{u > \theta\} \right) \geq cr^n,
\]
for any \( r \geq r_0 \).
Analogously, if

\[ \mathcal{L}^n(B^+_\mu(x_o) \cap \{u < \theta\}) \geq \mu_2 \]

then

\[ \mathcal{L}^n(B^+_\tau(x_o) \cap \{u < \theta\}) \geq c r^n, \]

for any \( r \geq r_0 \).

We remark that (5) (respectively, 7) is satisfied if \( u(x_o) > \theta \) (respectively, \( u(x_o) < \theta \)): in this case, \( \mu_1 \) and \( \mu_2 \) just depend on \(|\theta - u(x_o)|\) and on the modulus of continuity of \( u \). Our Theorem 1 fits into the line of research of density estimates for phase transition, as started in [CC95], to which it reduces when \( G := 0 \) or, basically, when we look at balls \( B_r(x_o) \) that do not intersect \( \{x_n = 0\} \). Namely, the purpose of this type of researches is to try to understand how the level sets of a “good” solution \( u \) behave in measure. Such level sets are physically very relevant, since they represent, roughly speaking, the separation interface of the two phases +1 and −1 in the Allen-Cahn system. Also, from these measure theoretic estimates, it is possible to deduce a locally uniform convergence of the level sets at the \( \Gamma \)-limit, and this information plays a crucial role in some rigidity problems (see [Sav03, VSS06, Sav09]).

Among the many extensions of [CC95], we recall here the ones in [PV05], where the \( p \)-Laplacian case has been considered, [FP08], for quasiminima, and the recent preprint [SV10], dealing with a fully non-local case.

Estimate (6) (as well as (8)) is obviously optimal (up to the constant \( c \)), because of the trivial upper bound

\[ \mathcal{L}^n(B^+_\tau(x_o) \cap \{u > \theta\}) \leq \mathcal{L}^n(B^+_\tau(x_o)) \leq \mathcal{L}^n(B_\tau(x_o)) \sim r^n. \]

Estimate (4) is optimal too, as shown by the case \( G := 0 \), taking as \( u(x) = u_o(\omega \cdot x) \), where \( \omega \in S^{n-1} \) and \( u_o : \mathbb{R} \to \mathbb{R} \) is a minimizer of the one-dimensional Allen-Cahn functional.

As far as we know, in the framework of the functional in (1), Theorem 1 of this paper is new even in the cases \( p = 2 \) (i.e., when the diffusion term reduces to the standard Laplacian) and \( Q = 1 \) (i.e., for minimizers).

2. Proof of Theorem 1

We will denote by “const” suitable positive constants (possibly different line by line) only depending on the quantities fixed in the hypotheses of Theorem 1. First of all, we prove (4). This is done by a technique well-developed after [CC95]: given any \( x_o \in \mathbb{R}_+^n \) and any \( R \geq 1 \), we take \( \beta \in C^\infty(\mathbb{R}^n) \), with \( \beta(x) = -1 \) for any \( x \in B_{R-\frac{1}{2}}(x_o) \) and \( \beta(x) = 1 \) for any \( x \in \mathbb{R}^n - B_{R-\frac{1}{2}}(x_o) \), with \(|\nabla \beta(x)| \leq 50 \) for any \( x \in \mathbb{R}^n \). Let \( w(x) := \min\{u(x), \beta(x)\} \). Then, \( w(x) = u(x) \) in \( \mathbb{R}^n - B_R(x_o) \), and \( w = -1 \) in \( B_{R-\frac{1}{2}}(x_o) \). So, by (3), we obtain that

\[ \frac{1}{Q} \mathcal{E}_{R,x_o}(u) \leq \mathcal{E}_{B_R(x_o)}(w) \]

\[ = \int_{(B_R^n(x_o) - B_{R-\frac{1}{2}}^n(x_o)) \cap \mathbb{R}_+^n} |\nabla w(x)|^p + F(w(x)) \, dx + \int_{(B_R^n(x_o) - B_{R-\frac{1}{2}}^n(x_o)) \cap \{x_n=0\}} G(w(x',0)) \, dx'. \]
Moreover, we have that $|\nabla w(x)| \leq |\nabla u(x)| + |\nabla \beta(x)| \leq \text{const}$, and so \(9\) gives that
\[
E_{R,x_o}(u) \leq \text{const} \left[ \mathcal{L}^n \left( (B^n_R(x_o) - B^n_{R-1/2}(x_o)) \cap \mathbb{R}^n_+ \right) + \mathcal{H}^{n-1} \left( (B^n_R(x_o) - B^n_{R-1/2}(x_o)) \cap \{ x_n = 0 \} \right) \right] \leq \text{const} R^{n-1},
\]
where we denoted by $\mathcal{H}^{n-1}$ the \((n - 1)\)-dimensional Hausdorff measure. This proves \(4\).

Now, we prove \(5\) (the proof of \(8\) is the same and it will be omitted). The proof of \(6\) that we give here is a modification of one of the proofs performed in [PV08], which was inspired by [Sav07] (other approaches, as the ones in [CC95, PV05] are also possible, but they may require additional assumptions). Differently from the existing literature, here some technical complications arise in order to cope with the trace term of the functional along $\{x_n = 0\}$. Indeed, even if such a term behaves as an $(n - 1)$-dimensional correction, and therefore may look negligible, it is not completely clear that it does not dangerously interact with some “area terms” arising in the density estimates, such as the bound in \(9\) and the subsequent quantities in \(10\). For this, we will have to perform some careful computation.

First, we observe that once \(9\) is proved for some $\theta_o \in (-1, -1/2)$, then it is proved for all $\theta \in [\theta_o, 1)$, because
\[
E_{r,x_o}(u) \geq \int_{B^+_r(x_o)} F(u) \, dx \geq \inf_{[\theta_o, \theta]} F \cdot \mathcal{L}^n \left( B^+_r(x_o) \cap \{ \theta > u > \theta_o \} \right),
\]
and if \(5\) holds for $\theta \in [\theta_o, 1)$, it holds for $\theta_o$ too, so using \(6\) for $\theta_o$ and \(4\) we obtain
\[
\mathcal{L}^n \left( B^+_r(x_o) \cap \{ u > \theta \} \right) \geq \mathcal{L}^n \left( B^+_r(x_o) \cap \{ u > \theta_o \} \right) - \mathcal{L}^n \left( B^+_r(x_o) \cap \{ \theta > u > \theta_o \} \right) \\
\geq cr^n - \text{const} E_{r,x_o}(u) \geq cr^n - \text{const} r^{n-1} \geq \frac{c}{2} r^n
\]
if $r \geq r_o$ and $r_o$ is large enough (here the “const” may depend on the fixed $\theta_o$ too). This would be the proof of \(5\) for any $\theta \in [\theta_o, 1)$, up to relabeling $c$, and therefore, in what follows, we will assume, without any restriction, that
\[
\theta \in (-1, -1/2].
\]

Moreover, we observe that the portion of space $\mathbb{R}^n \cap \{ x_n < 0 \}$ does not play any role in Theorem \(1\) in the sense that, if we define
\[
\bar{u}(x) = \bar{u}(x', x_n) := \begin{cases} u(x', x_n) & \text{if } x_n \geq 0, \\ u(x', -x_n) & \text{if } x_n < 0, \end{cases}
\]
we have that $\bar{u}$ is Lipschitz, since so is $u$, that $E_{\Omega}(\bar{u} + \varphi) = E_{\Omega}(u + \varphi)$ for any perturbation $\varphi$ in \(5\), that $\bar{u}$ is a Q-minimizer and that if \(6\) holds for $\bar{u}$ then it holds for $u$ as well. Consequently, we replace $u$ with $\bar{u}$ and then we drop the superscript tilde, that is we may and do suppose that
\[
(11) \quad u(x', -x_n) = u(x', x_n).
\]

This symmetry property will play an important role, by allowing us to disregard some trace term in a subsequent isoperimetric inequality (that is \(20\) below: roughly speaking, this trick will make the trace term in the density estimates always be weighted by the potential, thus killing any unweighted geometric measure on $\{x_n = 0\}$).
We take 

\[ T \]

\( T \) to be a free parameter, that in the sequel will be chosen to be suitably large, possibly in dependence of the quantities fixed in the statement of Theorem \[ 1 \]
and also in dependence of a further auxiliary parameter \( \varepsilon \)
that will be introduced later on, after (24).

We set \( S(\tau) := \min\{(\tau + 1)^p, 1\} \) for any \( \tau \in \mathbb{R} \).

Also, for any \( x \in \mathbb{R}^n_+ \) and any \( k \in \mathbb{N} \), we let

\[ v_k(x) := \begin{cases} 
2e^{|x - x_o| - (k+1)T} - 1 & \text{for any } x \in B_{(k+2)T}(x_o) \cap \mathbb{R}^n_+ \\
2e^T - 1 & \text{for any } x \in \mathbb{R}^n_+ - B_{(k+2)T}(x_o).
\end{cases} \]

If \( x \in \mathbb{R}^n \cap \{x_n < 0\} \), we also define

\[ v_k(x', x_n) := v_k(x', -x_n). \]

By construction, \( v_k \) is Lipschitz. Furthermore, we deduce from (2) that

\[ |\nabla v_k(x)|^p = (2e^{|x - x_o| - (k+1)T})^p \]

\( = (v_k(x) + 1)^p \]

\[ \leq \text{const } S(v_k(x)) \]

for any \( x \in B_{(k+2)T}(x_o) \), and therefore, by (13), for almost every \( x \in \mathbb{R}^n \). Furthermore, we see that

\[ \max\{F(\tau), G(\tau)\} \leq \text{const } S(\tau) \]

for any \( \tau \in [-1, 1] \), and that

\[ F(\tau) \geq \text{const } (\tau + 1)^p = \text{const } S(\tau) \]

when \( \tau \in [-1, -1/2] \).

We remark that

\[ \text{if } x \in \mathbb{R}^n_+ \text{ and } |x - x_o| > (k + 1)T, \text{ then } v_k(x) > 1 \geq u(x) \]

and so, recalling (11) and (13), we conclude that \( \{u > v_k\} = \{x \in \mathbb{R}^n \text{ s.t. } u(x) > v_k(x)\} \) is a bounded set. Accordingly, we can make use of (3) with \( \Omega := \{u > v_k\} \). This, and the use of (14) and (15), imply the following estimate:
Now, we make a general observation: given any Lipschitz function $w$ on a measurable set $U \subseteq \mathbb{R}^n$ with image in $[-1,1]$, we have

\[
\int_U |\nabla w|^p + F(w) \, dx \geq \text{const} \int_U |\nabla w| \left( F(w) \right)^{(p-1)/p} \, dx
\]

(19)

\[
= \text{const} \int_{-1}^1 \left( F(\tau) \right)^{(p-1)/p} \mathcal{H}^{n-1}(U \cap \{w = \tau\}) \, d\tau,
\]

due to the Young inequality and the coarea formula.

Also, we define

\[
\mathcal{M}_k(\tau) := \{ x \in \mathbb{R}^n \text{ s.t. } \tau(x) = u_k(x) \}
\]

\[
= \{ u \geq v_k \} \cap \{ u = \tau \}
\]

and

\[
\mathcal{N}_k(\tau) := \{ x \in \mathbb{R}^n \text{ s.t. } u(x) \geq v_k = \tau \}
\]

\[
= \{ u \geq v_k \} \cap \{ v_k = \tau \},
\]

and we remark that

\[
B_{kT}(x_0) \cap \{ u > \theta \} \subseteq \{ x \in B_{kT}(x_0) \text{ s.t. } u(x) > \tau > v_k(x) \}
\]

\[
\subseteq \{ x \in \mathbb{R}^n \text{ s.t. } u(x) > \tau > v_k(x) \} = \{ u > \tau > v_k \}
\]

for any $\tau \in [(\theta - 1)/2, \theta]$ as long as the free parameter $T$ is chosen large enough.

We employ the latter formula and the isoperimetric inequality to obtain

\[
\left( \mathcal{L}^n(B_{kT}(x_0) \cap \{ u > \theta \}) \right)^{(n-1)/n} \leq \left( \mathcal{L}^n(\{ u > \tau > v_k \}) \right)^{(n-1)/n}
\]

(20)

\[
\leq \text{const} \left( \mathcal{H}^{n-1}(\mathcal{M}_k(\tau)) + \mathcal{H}^{n-1}(\mathcal{N}_k(\tau)) \right),
\]

for any $\tau \in [(\theta - 1)/2, \theta]$.

Notice that we have in the back of our mind here the symmetry in (11) and (13), since we are willing to estimate sets in (20) in the whole of $\mathbb{R}^n$ instead of $\mathbb{R}^n_+$: due to such a symmetry, this choice will be paid only by a factor 2 later on: see (22). On the contrary, without this trick we would have got also a term of the form $\mathcal{H}^{n-1}(B_{kT}^-)$ in (20), and this would have risked to be too large to be controlled by the quantities in (4) and (40).

Making use of (20) and then of (19) with $U := \{ u \geq v_k \}$ and either $w := u$ or $w := v_k$, we conclude that

\[
\left( \mathcal{L}^n(B_{kT}(x_0) \cap \{ u > \theta \}) \right)^{(n-1)/n}
\]

\[
= \text{const} \int_{(\theta-1)/2}^\theta \left( F(\tau) \right)^{(p-1)/p} \, d\tau \left( \mathcal{L}^n(B_{kT}(x_0) \cap \{ u > \theta \}) \right)^{(n-1)/n}
\]

(21)

\[
\leq \text{const} \int_{-1}^1 \left( F(\tau) \right)^{(p-1)/p} \left( \mathcal{H}^{n-1}(\mathcal{M}_k(\tau)) + \mathcal{H}^{n-1}(\mathcal{N}_k(\tau)) \right) \, d\tau
\]

\[
\leq \text{const} \left( \int_{u > v_k} |\nabla u|^p + F(u) \, dx + \int_{u > v_k} |\nabla v_k|^p + F(v_k) \, dx \right).
\]
Now, we remark that
\[
\int_{\{u \geq v_k\}} |\nabla u|^p + F(u) \, dx + \int_{\{u \geq v_k\}} |\nabla v_k|^p + F(v_k) \, dx
\]
\[
= 2 \left[ \int_{\{u \geq v_k\} \cap \mathbb{R}^n_+} |\nabla u|^p + F(u) \, dx + \int_{\{u \geq v_k\} \cap \mathbb{R}^n_+} |\nabla v_k|^p + F(v_k) \, dx \right],
\]
thanks to (11) and (13). Therefore, exploiting (21), (22), (14), (15) and (18), we obtain
\[
\left(\mathcal{L}^n(B_{kT}^+(x_o) \cap \{u > \theta\})\right)^{(n-1)/n}
\]
\[
\leq \text{const} \left[ \int_{\{u \geq v_k\} \cap \mathbb{R}^n_+} |\nabla u|^p + F(u) \, dx + \int_{\{u \geq v_k\} \cap \mathbb{R}^n_+} |\nabla v_k|^p + F(v_k) \, dx \right]
\]
\[
\leq \text{const} \left[ \int_{\{u \geq v_k\} \cap \mathbb{R}^n_+} S(v_k) \, dx + \int_{\{u \geq v_k\} \cap \{x_n = 0\}} S(v_k) \, dx' \right].
\]
That is, recalling (17),
\[
\left(\mathcal{L}^n(B_{kT}^+(x_o) \cap \{u > \theta\})\right)^{(n-1)/n}
\]
\[
\leq \text{const} \left[ \int_{\{u \geq v_k\} \cap \mathbb{R}^n_+} S(v_k) \, dx + \int_{\{u \geq v_k\} \cap B_{(k+1)T}(x_o) \cap \{x_n = 0\}} S(v_k) \, dx' \right].
\]
We define
\[
\ell_1 = \ell_1(k) := \int_{B_{kT}^+(x_o)} S(v_k) \, dx
\]
\[
\ell_2 = \ell_2(k) := \int_{\{u \geq v_k\} \cap (B_{(k+1)T}(x_o) - B_{kT}^+(x_o))} S(v_k) \, dx
\]
and
\[
\ell_3 = \ell_3(k) := \int_{\{u \geq v_k\} \cap B_{(k+1)T}(x_o) \cap \{x_n = 0\}} S(v_k) \, dx'.
\]
With this notation, we see that (23) can be written as
\[
\left(\mathcal{L}^n(B_{kT}^+(x_o) \cap \{u > \theta\})\right)^{(n-1)/n} \leq \text{const} (\ell_1 + \ell_2 + \ell_3).
\]
Now, we fix a small \(\varepsilon > 0\) to be taken appropriately small (in fact, at the end, this \(\varepsilon\) will be fixed explicitly in Lemma (2) below) and we claim that
\[
\ell_3 \leq \varepsilon k^{n-1} + C_\varepsilon (kT)^{n-2},
\]
for a suitable \(C_\varepsilon > 0\). The proof of (25) is indeed a bit long and complicated and it will be completed only below (35), after some delicate computations. To prove (25), first we notice that when \(|x_{o,n}| > (k + 1)T\) then \(B_{(k+1)T}(x_o) \cap \{x_n = 0\} = \emptyset\), so \(\ell_3 = 0\) and (25) is obviously true. As a consequence, we may suppose that
\[
|x_{o,n}| \leq (k + 1)T
\]
and so we can define
\[
\rho_k := \sqrt{(k + 1)^2 T^2 - x_{o,n}^2}.
\]
We see that
\[ B_{(k+1)T}(x_o) \cap \{ x_n = 0 \} \subseteq B_{\rho_k}^{n-1}(x'_o) \]
and therefore
\[
\begin{align*}
\ell_3 & \leq \text{const} \int_{B_{(k+1)T}(x_o) \cap \{ x_n = 0 \}} (v_k(x', 0) + 1)^p \, dx' \\
& \leq \text{const} \int_{B_{\rho_k}^{n-1}(x'_o)} e^p \left( \sqrt{r^2 + x_{o,n}^2} - (k+1)T \right) \, dx' \\
& = \text{const} e^{-p(k+1)T} \int_0^\rho_k r^{n-2} e^{p\sqrt{r^2 + x_{o,n}^2}} \, dr.
\end{align*}
\]

Now, to prove (25), we distinguish two cases: either \( n \geq 3 \) or \( n = 2 \).
If \( n \geq 3 \), we make use of (27) to conclude that
\[
\ell_3 \leq \text{const} \rho_k^{n-3} e^{-p(k+1)T} \int_0^\rho_k r^{n-2} e^{p\sqrt{r^2 + x_{o,n}^2}} \, dr,
\]
and we perform the substitution
\[
s := \sqrt{r^2 + x_{o,n}^2}.
\]
We obtain that \( s \, ds = r \, dr \), hence (28) becomes
\[
\ell_3 \leq \text{const} \rho_k^{n-3} e^{-p(k+1)T} \int_(k+1)T_{|x_{o,n}|} s e^{ps} \, ds
\]
\[
\leq \text{const} \rho_k^{n-3} (k + 1) T e^{-p(k+1)T} \int_(k+1)T_{|x_{o,n}|} e^{ps} \, ds
\]
\[
\leq \text{const} \rho_k^{n-3} (k + 1) T
\]
\[
\leq \text{const} \left( (k + 1)T \right)^{n-2}
\]
\[
\leq \text{const} \left( kT \right)^{n-2}.
\]
This proves (25) when \( n \geq 3 \), so now we deal with the proof of (25) when \( n = 2 \): in this case, we claim that
\[
\int_0^\rho_k e^{p\sqrt{r^2 + x_{o,n}^2}} \, dr \leq \left( 2e^{2kT} + \tilde{C}_\varepsilon \right) e^{p(k+1)T}
\]
for a suitable \( \tilde{C}_\varepsilon > 0 \).
To prove (30), we distinguish two sub-cases: either \( \rho_k < \varepsilon^2(k+1)T \) or \( \rho_k \geq \varepsilon^2(k+1)T \).
If \( \rho_k < \varepsilon^2(k+1)T \), we have that
\[
\int_0^\rho_k e^{p\sqrt{r^2 + x_{o,n}^2}} \, dr \leq e^{p\sqrt{\rho_k^2 + x_{o,n}^2}} \rho_k = e^{p(k+1)T} \rho_k
\]
\[
\leq e^{p(k+1)T} \varepsilon^2(k+1)T \leq 2e^{p(k+1)T} \varepsilon^2kT,
\]
and this proves (30) in the sub-case \( \rho_k < \varepsilon^2(k+1)T \).
Now, we prove (30) in the sub-case \( \rho_k \geq \varepsilon^2(k+1)T \), that gives, recalling (26),
\[
|x_{o,n}| \leq \sqrt{1 - \varepsilon^4(k+1)T}.
\]
Then, we make the substitution in (29), we split the domains of integration, and we obtain
\[
\int_0^{\rho_k} e^{p \sqrt{r^2 + x_{o,n}^2}} \, dr = \int_{|x_{o,n}|}^{(k+1)T} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds
\]
(32)
\[
\leq \int_{|x_{o,n}|}^{\sqrt{1 + \varepsilon^4}|x_{o,n}|} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds + \Xi \int_{\sqrt{1 + \varepsilon^4}|x_{o,n}|}^{(k+1)T} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds,
\]
where
\[
\Xi := \begin{cases} 
1 & \text{if } \sqrt{1 + \varepsilon^4}|x_{o,n}| < (k+1)T, \\
0 & \text{if } \sqrt{1 + \varepsilon^4}|x_{o,n}| \geq (k+1)T.
\end{cases}
\]
So, we compute separately the latter two integrals in (32). For the first one, recalling (31), we have:
\[
\int_{|x_{o,n}|}^{\sqrt{1 + \varepsilon^4}|x_{o,n}|} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds \leq e^{p\sqrt{1 + \varepsilon^4}|x_{o,n}|} \int_{|x_{o,n}|}^{\sqrt{1 + \varepsilon^4}|x_{o,n}|} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds \leq e^{p\sqrt{1 + \varepsilon^4}|x_{o,n}|} \varepsilon^2 T e^{p(k+1)T} \varepsilon^2 (k+1)T \leq 2e^{p(k+1)T} \varepsilon^2 kT.
\]
(33)

Now we estimate the last integral in (32) as follows:
\[
\Xi \int_{\sqrt{1 + \varepsilon^4}|x_{o,n}|}^{(k+1)T} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds = \Xi \int_{\sqrt{1 + \varepsilon^4}|x_{o,n}|}^{(k+1)T} e^{ps} \sqrt{1 + \frac{x_{o,n}^2}{s^2 - x_{o,n}^2}} \, ds
\]
(34)
\[
\leq \Xi \int_{\sqrt{1 + \varepsilon^4}|x_{o,n}|}^{(k+1)T} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds \leq \Xi \int_{-\infty}^{(k+1)T} e^{ps} \frac{s}{\sqrt{s^2 - x_{o,n}^2}} \, ds = \tilde{C}_\varepsilon e^{p(k+1)T},
\]
for a suitable $\tilde{C}_\varepsilon > 0$. By plugging (33) and (34) into (32), we complete the proof of (30) in the sub-case $\rho_k \geq \varepsilon(k+1)T$ too.

Having completed the proof of (30), we use it to complete the proof of (25) in the case $n = 2$: indeed, by (27) and (30), when $n = 2$ we have
\[
\ell_3 \leq \text{const } e^{-p(k+1)T} \int_0^{\rho_k} e^{p \sqrt{r^2 + x_{o,n}^2}} \, dr \leq \text{const } (\varepsilon^2 kT + \tilde{C}_\varepsilon).
\]
(35)
This proves (25) also in the case $n = 2$, since (recalling (12)), we may take
\[
T \geq 1/\varepsilon.
\]
(36)

So, the proof of (25) is completed.
Now, we observe that

\[ \ell_1 \leq \text{const} \int_{B_{kT}^+(x_o)} (v_k + 1)^p \, dx \]

\[ \leq \text{const} \int_{B_{kT}(x_o)} e^p(|x-x_o|-(k+1)T) \, dx \]

\[ \leq \text{const} \int_0^{kT} r^{n-1} e^{p(r-(k+1)T)} \, dr \]

\[ \leq \text{const} (kT)^{n-1} e^{-p(k+1)T} \int_0^{kT} e^{pr} \, dr \]

\[ = \text{const} (kT)^{n-1} e^{-pT} \]

\[ \leq \varepsilon k^{n-1}, \]

provided that \( T \) is sufficiently large, possibly in dependence of \( \varepsilon \). This last requirement, recalling also (12) and (36), fixes \( T \) once and for all (in dependence of \( \varepsilon \), which, in turn, will be fixed in the forthcoming Lemma 2).

Furthermore, since \( S \) is non-decreasing and bounded by 1, we obtain that

\[
\ell_2 = \int_{\{\theta \geq u \geq v_k\} \cap (B_{(k+1)T}^+(x_o) - B_{kT}^+(x_o))} S(v_k) \, dx
\]

\[
+ \int_{\{u \geq \theta \} \cap (u \geq v_k) \cap (B_{(k+1)T}^+(x_o) - B_{kT}^+(x_o))} S(v_k) \, dx
\]

\[ \leq \int_{\{\theta \geq u \geq v_k\} \cap (B_{(k+1)T}^+(x_o) - B_{kT}^+(x_o))} S(u) \, dx
\]

\[ + |B^n \left( \{u > \theta\} \cap (B_{(k+1)T}^+(x_o) - B_{kT}^+(x_o)) \right)|. \]

Moreover, using also (10), (16) and (18), and recalling (17) once more, we get

\[
\int_{B_{kT}^+(x_o) \cap \{u \leq \theta\}} S(u) \, dx \leq \int_{B_{kT}^+(x_o) \cap \{\theta \geq u \geq v_k\}} S(u) \, dx + \int_{B_{kT}^+(x_o) \cap \{u \leq v_k\}} S(v_k) \, dx
\]

\[ \leq \text{const} \int_{\{\theta \geq u \geq v_k\} \cap \mathbb{R}^n_+} F(u) \, dx + \int_{B_{kT}^+(x_o)} S(v_k) \, dx \]

\[ \leq \text{const} \left[ \int_{\{u \geq v_k\} \cap \mathbb{R}^n_+} S(v_k) \, dx + \int_{\{u \geq v_k\} \cap \{x_n = 0\}} S(v_k) \, dx' + \int_{B_{kT}^+(x_o)} S(v_k) \, dx \right]
\]

\[ \leq \text{const} (\ell_1 + \ell_2 + \ell_3). \]

Now, it is convenient to introduce the following quantities:

\[ V_r := \mathcal{L}^n \left( B_r^+(x_o) \cap \{u > \theta\} \right) \quad \text{and} \quad A_r := \int_{B_r^+(x_o) \cap \{u \leq \theta\}} S(u) \, dx. \]
These quantities are appropriate variations of similar ones defined in \[CC95\], and they somewhat play the role of “volume” and “area terms”, respectively, in the minimal surface analogue. By collecting the estimates in (24), (39), (37), (38) and (25), we conclude that

\[
A_k + V_k^{(n-1)/n} \leq \text{const} \left( \ell_1 + \ell_2 + \ell_3 \right)
\]

\[
\leq \text{const} \left[ \int_{\{\theta \leq u \leq v_k\} \cap (B_{k+1} - B_k)} S(u) \, dx \right.
\]

\[
+ \mathcal{L}^n \left( \{u > \theta\} \cap (B_{k+1} - B_k) \right) + \frac{\varepsilon k^{n-1}}{2} + C \varepsilon (kT)^{n-2} \]

\[
\leq \text{const} \left( (V_{k+1} - V_k) + (A_{k+1} - A_k) + \frac{\varepsilon k^{n-1}}{2} + C \varepsilon (kT)^{n-2} \right).
\]

We define \(k_\varepsilon\) to be the smallest integer bigger than \(\mu_1 + (2C\varepsilon T^{n-2}/\varepsilon)\), where \(\mu_1\) is as in (5). This gives that \(C \varepsilon (kT)^{n-2} \leq \varepsilon k^{n-1}/2\) and so

(41) \[A_k + V_k^{(n-1)/n} \leq \text{const} \left( (V_{k+1} - V_k) + (A_{k+1} - A_k) + \varepsilon k^{n-1} \right)\]

for any \(k \in \mathbb{N}\), with \(k \geq k_\varepsilon\). Notice that, since \(T\) has been fixed in dependence of \(\varepsilon\) after (37), it is conceivable to keep track of the dependence of \(k_\varepsilon\) on \(\varepsilon\) only and disregard the dependence on \(T\).

So, it is convenient to recall the following general recursive result, which is a variation of an argument in \[CC95\] and whose detailed proof may be found in Lemma 12 of \[FV08\]:

**Lemma 2.** Let \(C \geq 1\), \(\varepsilon > 0\). Let \(\mathcal{A}_k\) and \(\mathcal{V}_k\) be two sequences of non-negative real numbers, for \(k \in \mathbb{N}\).

Suppose that

(42) \[\mathcal{V}_k \geq 1/C\]

and

(43) \[\mathcal{V}_k^{(n-1)/n} + \mathcal{A}_k \leq C \left( (\mathcal{V}_{k+1} - \mathcal{V}_k) + (\mathcal{A}_{k+1} - \mathcal{A}_k) + \varepsilon k^{n-1} \right)\]

for any \(k \in \mathbb{N}\).

Let

\[
c := \min \left\{ \frac{1}{C}, \frac{1}{2C(n+1)!} \right\}.
\]

Suppose that

(44) \[\varepsilon \leq \min \left\{ \frac{c}{4C}, \frac{c^{(n-1)/n}(\sqrt{2} - 1)}{2C} \right\}.
\]

Then,

(45) \[\mathcal{A}_k + \mathcal{V}_k \geq ck^n\]

for any \(k \geq 4C(n+1)!\).

With this, we define \(\mathcal{A}_k := A_{k+k_\varepsilon}T\) and \(\mathcal{V}_k := V_{k+k_\varepsilon}T\), we have that \(\mathcal{V}_k \geq V_{\mu_1} \geq \mu_2\), by (5), and so (42) holds true, if \(C\) is chosen large enough. Also, (43) follows from (41), again by choosing \(C\) appropriately large.
Hence, we can exploit Lemma 2 (notice that (44) fixes now the value of $\varepsilon$), and we deduce from (45) that

$$A_kT + V_kT \geq \text{const} T^n k^n$$

as long as $k$ is large enough.

Since, by (10), (16) and (4), we have that

$$A_r \leq \text{const} \int_{B_r \cap \{u \leq \theta\}} F(u) \, dx \leq \text{const} r^{n-1}$$

for any $r \geq 1$, we conclude that $V_r \geq \text{const} r^n$ for any $r$ suitably large, that is (6).

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