Fast Magnetic Measurements Of 8.6 m Undulator

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Abstract

The design of the large-aperture variable-period undulator (VPU) developed for the Novosibirsk free electron laser (FEL) is shortly described. High amplitude of on-axis field is achieved due to the arc shape of the magnet blocks and poles of the undulator. To conduct magnetic measurements and fine tuning of the undulator as well as to perform real time position tracking of magnet blocks, pulsed wire technique was adopted.

Introduction

A permanent magnet variable-period undulator with large (1.4) ratio of the aperture to the minimum period and possibility to change the number of poles was designed to upgrade the first stage FEL of the Novosibirsk FEL facility. The Novosibirsk FEL is a source of radiation in the THz range. The new undulator will replace the existing insertion device section which consists of two 4-meter-long undulators and the three-pole buncher. That will shift long-wave border of the tuning range from 200 \( \mu \text{m} \) to 450 \( \mu \text{m} \). A comparison of parameters of former and new undulators is given in the following table:

| Parameter                  | EM undulators | VPU          |
|----------------------------|---------------|--------------|
| Period, cm                 | 12            | 10 – 16      |
| Gap (inner diameter), cm   | 8             | 14           |
| Number of periods          | 2\times32     | 50 – 80      |
| Radiation wavelength, \( \mu \text{m} \) | 90 – 240      | 82 – 450     |
| Deflection parameter       | 0 – 1.1       | 0.45 – 1.9   |
| Full length, cm            | 2\times400    | 860          |

The idea of a VPU with free moving poles was proposed in [1]. At the minimum period \( L_{\text{min}} \), the developed undulator is a conventional hybrid device with neodymium magnets and poles made of soft steel with large permeability. All poles in the undulator are split into halves, and so the undulator is two arrays (upper and lower) of separate removable blocks. Each block is \( L_{\text{min}}/2 \) long and consists of a magnet embraced by two pole halves and the whole structure is set in an aluminum frame. The pairs of blocks in upper and lower arrays are connected and placed on a carriage that can move freely along the undulator, see Fig. 1. Adjacent magnets in an array always have antiparallel longitudinal magnetizations, so they experience strong repulsion from each other. Due to repulsion force and the low-friction between guide rail and carriages, the undulator period can be changed via shifting the terminal blocks. This procedure, which changes the overall length of the undulator, is performed by pushers that can be remotely controlled. More details about similar undulator can be found in [2].

![Fig. 1. Front view of the undulator](image)

The stretched wire is passed through the wire it interacts with the magnetic field. Flexural waves that travel through the wire towards detector contain information about transverse field profile in the region of interest.

Measurement system

The basic components of the measurement setup are a wire stretched along the axis of investigated magnetic field, a current pulse generator and a detector of the wire displacement. When current is passing through the wire it interacts with the magnetic field. The expression for wire displacement at the detector position \( z = 0 \)
reads:

\[ x(0, t) = \frac{1}{\sqrt{2\pi}} \int_{t-\tau}^{t} \int_{0}^{\infty} B_{\text{eff}}(z) dz \, dt', \]

where \( \mu \) is the mass per unit length of the wire, \( T \) is the tension in the wire, \( \tau \) is current pulse duration, \( v_0 \) is \( \sqrt{T/\mu} \) and \( B_{\text{eff}} \) is defined by the following expression:

\[ B_{\text{eff}}(x) = \int_{-\infty}^{\infty} A(k) e^{-\omega(k)x} \, dk, \]

where \( A(k) \) is the Fourier transform of the magnetic field in the path of the current and \( \omega(k) \) is the dispersion relations for the flexural waves in the wire [5]. Using above expressions one can correct effects of dispersion, current pulse form averaging and restore the magnetic field distribution from the data obtained by the detector.

An experimental setup was constructed in order to adopt the technique. A beryllium copper wire with a diameter of 200 \( \mu \)m and length of 10 m was stretched by applying tension close to yield point. A capacitor based current pulse generator can generate pulses with duration of 50 \( \mu \)s and amplitude of 10 A. A homemade optocoupler is used as the wire position detector, it is based on fd-24k photodiode and provide 0.14 mV/\( \mu \)m gradient. Since the size of the undulator do not allow avoiding intersection of the main signal and reflections by elongation of the wire and the period of the undulator can be changed during operation of the FEL it was decided to use dampers based on oil drops, see [6], placed on the ridges of an automated pantograph.

Several trial launches of the system were performed, see example in Fig. 2.

![Test measurement](image)

**Fig. 2.** Test measurement

The field distribution was reconstructed from the measured first integral data by differentiating, no filter was applied.

**Discussion and conclusion**

The described experimental setup is under active development now. Test measurements of reference magnet and VPU short prototype were conducted, see Fig. 2, and obtained results indicate that detector sensitivity should be improved in order to obtain larger signal to noise ratio.

The task to commission a pulsed wire measurements setup over 10 m long has not been challenged yet. It is yet to be determined whether complete compensation of signal distortion effects e.g. wire sagging influence, attenuation and dispersion is possible during postprocessing. Alternatively, complementary components, like wire supports and additional detector, could be applied to minimize the influence of distortion effects.

Currently authors attempt to increase the sensitivity of the detector and suppress impact from external noises in order to acquire clean data.

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