HOMOLOGICAL- AND ANALYTICAL-PRESERVING SERENDIPITY FRAMEWORK FOR POLYTOPAL COMPLEXES, WITH APPLICATION TO THE DDR METHOD

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Abstract. In this work we investigate from a broad perspective the reduction of degrees of freedom through serendipity techniques for polytopal methods compatible with Hilbert complexes. We first establish an abstract framework that, given two complexes connected by graded maps, identifies a set of properties enabling the transfer of the homological and analytical properties from one complex to the other. This abstract framework is designed having in mind discrete complexes, with one of them being a reduced version of the other, such as occurring when applying serendipity techniques to numerical methods. We then use this framework as an overarching blueprint to design a serendipity DDR complex. Thanks to the combined use of higher-order reconstructions and serendipity, this complex compares favorably in terms of degrees of freedom (DOF) count to all the other polytopal methods previously introduced and also to finite elements on certain element geometries. The gain resulting from such a reduction in the number of DOFs is numerically evaluated on two model problems: a magnetostatic model, and the Stokes equations.

Mathematics Subject Classification. 65N30, 65N99, 65N12, 78A30.

Received March 6, 2022. Accepted August 7, 2022.

1. Introduction

1.1. Hilbert complexes and their role in the stability of partial differential equations

A Hilbert complex is a sequence of Hilbert spaces $X_i$ connected by closed densely defined linear operators $d_i : X_i \to X_{i+1}$ such that the range of $d_i$ is contained in the kernel of $d_{i+1}$ (complex property). The best-known example of Hilbert complex is the de Rham complex which, for a domain $\Omega$ of $\mathbb{R}^3$, reads

$$
\mathbb{R} \leftarrow H^1(\Omega) \xrightarrow{\text{grad}} H(\text{curl}; \Omega) \xrightarrow{\text{curl}} H(\text{div}; \Omega) \xrightarrow{\text{div}} L^2(\Omega) \xrightarrow{0} 0,
$$

where $H^1(\Omega)$ is spanned by scalar-valued functions that are square-integrable over $\Omega$ along with their gradient, while $H(\text{curl}; \Omega)$ and $H(\text{div}; \Omega)$ are spanned by vector-valued functions that are square-integrable over $\Omega$ along

Keywords and phrases. Discrete de Rham method, Virtual Element method, compatible discretisations, polytopal methods, serendipity.

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with their curl and divergence, respectively. The complex property corresponds, in this case, to the classical relations \( \text{grad } C = 0 \) for all \( C \in \mathbb{R} \), \( \text{curl } \text{grad } = 0 \), and \( \text{div } \text{curl } = 0 \).

Moreover, the divergence \( \text{div} : H^1(\Omega) \to L^2(\Omega) \) is surjective and, depending on the topology of \( \Omega \), the previous properties can become stronger. Specifically, if \( \Omega \) is not crossed by any tunnel (i.e., its first Betti number \( b_1 \) is zero), then \( \text{Im } \text{grad } = \text{Ker } \text{curl } \) for every function \( v \in H(\text{curl}; \Omega) \) such that \( \text{curl } v = 0 \), there exists a function \( q \in H^1(\Omega) \) such that \( v = \text{grad } q \). Similarly, if \( \Omega \) does not enclose any void (i.e., its second Betti number \( b_2 \) is zero), then \( \text{Im } \text{curl } = \text{Ker } \text{div} : \) for every function \( w \in H(\text{div}; \Omega) \) such that \( \text{div } w = 0 \), there exists a function \( v \in H(\text{curl}; \Omega) \) such that \( w = \text{curl } v \).

The above exactness properties are key to the well-posedness of certain classes of partial differential equations (PDEs). An example is provided by the following formulation of magnetostatics ([1], Sect. 4.5.3): Given the magnetic permeability \( \mu > 0 \) and the free current density \( J \in \text{curl } H(\text{curl}; \Omega) \), find the magnetic field \( H \in H(\text{curl}; \Omega) \) and the vector potential \( A \in H(\text{div}; \Omega) \) such that

\[
\int_{\Omega} \mu H \cdot v - \int_{\Omega} A \cdot \text{curl } v = 0 \quad \forall v \in H(\text{curl}; \Omega),
\]

\[
\int_{\Omega} \text{curl } H \cdot w + \int_{\Omega} \text{div } A \cdot \text{div } w = \int_{\Omega} J \cdot w \quad \forall w \in H(\text{div}; \Omega).
\]

The first equation is the definition of the vector potential and incorporates the homogeneous natural boundary condition on the tangential trace of \( A \), while the second expresses both Ampère’s law and the so-called Coulomb gauge. The well-posedness of this problem hinges heavily on the exactness of the second portion of the de Rham complex. Specifically, to bound \( A \), we use \( L^2 \)-orthogonal complements to write

\[
A = A^* + A^\perp \in \text{ker } \text{div} \oplus (\text{ker } \text{div})^\perp = \text{Im } \text{curl} \oplus (\text{ker } \text{div})^\perp,
\]

where the last equality comes from the exactness property \( \text{Im } \text{curl } = \text{Ker } \text{div} \). The component \( A^* \in \text{Im } \text{curl} \) is then estimated taking \( v \) such that \( \text{curl } v = A^* \) as test function in (1.1), while a bound on \( A^\perp \in (\text{ker } \text{div})^\perp \) is obtained using the fact that \( \text{div } : (\text{ker } \text{div})^\perp \to L^2(\Omega) \) is an isomorphism, due to the exactness property \( \text{Im } \text{div } = L^2(\Omega) \) (see Sect. 2 of [2] for the detailed analysis).

When writing numerical schemes for problem (1.1), reproducing exactness properties at the discrete level is crucial for stability (see, e.g., [1], Thm. 5.4 or [3], Thm. 10), and essentially requires to derive discrete counterparts of Hilbert complexes, with continuous spaces replaced by finite-dimensional analogs. Methods based on (exact) discrete Hilbert complexes are often referred to as compatible. A very general exposition of compatible finite element methods can be found in [1]. Finite elements are, however, essentially confined to conforming meshes composed of tetrahedral or hexahedral elements. Since the early 2010s, the development of methods supporting meshes made of much more general polytopal elements, as well as arbitrary order of accuracy, has been an extremely active field of research; a representative but by far non-exhaustive list of references includes [4–11]. Recent efforts have focused on the compatibility of polytopal methods; see, in particular [12, 13] and [2, 14] concerning, respectively, Virtual Element (VEM) and Discrete de Rham (DDR) methods, as well as [16], where bridges between these technologies have been built.

It is worth noticing that the notion of compatibility can be extended to the case when exactness does not hold. Coming back to our example, when the Betti numbers \( b_1 \) or \( b_2 \) are nonzero, de Rham’s cohomology characterises the non-trivial cohomology spaces \( \text{Ker } \text{curl} / \text{Im } \text{grad} \) and \( \text{Ker } \text{div} / \text{Im } \text{curl} \). In this case, \( \text{ker } \text{div } = \text{Im } \text{curl} \oplus \tilde{\mathcal{H}} \) where \( \tilde{\mathcal{H}} \approx \text{Ker } \text{div} / \text{Im } \text{curl} \) is the space of harmonic 2-forms, and the decomposition (1.2) becomes

\[
\mathcal{A} = A^* + A^\perp + A^\perp \in \text{Im } \text{curl} \oplus \tilde{\mathcal{H}} \oplus (\text{ker } \text{div})^\perp.
\]

The weak formulation (1.1) must then be supplemented by conditions that enforce the orthogonality of the potential \( A \) to \( \tilde{\mathcal{H}} \) in order to control (in fact, eliminate) the component \( A^\perp \); see Section 4.5.3 of [1]. In these situations of non-exactness of the complexes, the notion of compatibility of the discretisation translates into the existence of isomorphisms between the cohomology spaces of the continuous and discrete complexes.
1.2. Polytopal discrete Hilbert complexes

Vanilla versions of polytopal methods often display more degrees of freedom (DOFs) than the corresponding finite element counterparts. A remedy to this drawback has been proposed in [17], where a version of the nodal ($H^1$-conforming) VEM space with fewer face DOFs has been introduced. The idea, inspired by serendipity finite elements, consists in selecting a subset of the DOFs sufficient to uniquely identify polynomials of the desired degree, and in using them to fix the values of the remaining DOFs. A similar path had been previously followed in [18] to reduce the number of element DOFs in the framework of discontinuous Galerkin methods. In the context of low-order methods, this approach is also called barycentric elimination [19], and has been used to eliminate cell unknowns in hybrid methods [20]. Notice that the word serendipity historically originates from the fact that, “by chance”, internal DOFs can be eliminated from low-order rectangular $Q^k$ finite elements without compromising accuracy; however, the above approaches, as well as the one developed in this paper, are systematic and apply to much more general geometries.

Serendipity techniques for DOFs reduction are appealing for several reasons: they enable an interfacing of finite element and polytopal methods on standard geometries, as argued in [17]; they lead to smaller algebraic systems by reducing the number of face DOFs (which cannot be, in general, eliminated by static condensation); in the context of nonlinear problems, they provide a means to eliminate (a portion of the) element DOFs that is potentially more efficient than static condensation, as the serendipity reduction operators need not be recomputed at each iteration of the nonlinear solver.

In the context of compatible polytopal methods, serendipity techniques have to be applied in such a way as to preserve the homological and analytical properties of the discrete complex, that is, its cohomology spaces, and its stability and approximation properties. Concerning VEM methods, the issue of face DOFs reduction through compatible serendipity techniques has been considered in [21, 22], where the authors build a virtual serendipity de Rham complex for which they provide a direct proof of local exactness properties; see, in particular, Propositions 3.2, 3.6, and 3.8 of [22]. A variation of the VEM complex in the previous reference has been recently proposed in [16], where links with DDR have also been established.

Inspired by these recent results, we tackle in this paper the issue of DOFs reduction for compatible polytopal methods from a broader perspective. Specifically, we start by constructing an abstract framework which, given two complexes connected by graded maps (that is, a family of maps between each space of the first complex and its counterpart in the second complex), identifies a set of requirements on these maps that enable the transfer of all the relevant homological and analytical results from one complex to the other. In particular, the properties we identify ensure that the original and serendipity complexes have isomorphic cohomologies, even in the case of non-exact complexes due to non-trivial topologies of the domain. Moreover, the identification of sufficient conditions for the preservation of analysis results such as Poincaré inequalities, primal and adjoint consistency, etc. in a general nonconforming setting seems to be entirely new (in a conforming setting, the preservation of such properties is significantly easier).

This general framework is specifically adapted to the situation where one complex is a reduced version of the other, and the graded connecting maps are extensions/reductions which transfer properties from the full complex to the reduced one. This framework then enables us to derive a serendipity version (hereafter referred to as SDDR) of the DDR complex of [14]. The SDDR complex hinges on novel serendipity operators that rely on the same construction for both the discrete $H^1$ and $H(\text{curl})$ spaces, and that enable the reduction of both faces and element DOFs. The fulfillment of the requirements identified in the abstract framework ensures that the full panel of homological and analytical results derived in [14] transfers to the serendipity DDR complex. The new SDDR complex is extremely efficient as it combines two DOFs-reduction strategies: the use of higher-order reconstructions, inherent to DDR and akin to the enhancement techniques in VEM, and serendipity on both faces and elements. The DOFs count therefore compares favorably to existing polytopal de Rham complexes [2, 3, 12, 16, 22], but also to finite elements on hexahedra (while being very close, although slightly higher, on tetrahedra). The achieved DOFs reduction for the discrete counterparts of the spaces $H^1(T)$ and $H(\text{curl}; T)$, when the element $T$ is a tetrahedron or a hexahedron and polynomial degrees $k$ between 1 and 3 are considered,
Table 1: Summary of the serendipity reduction of the number of DOFs for the DDR complex, for $T$ a tetrahedron or a hexahedron.

| Discrete space | Tetrahedron | Hexahedron |
|---------------|-------------|-------------|
|               | $k = 1$     | $k = 2$     | $k = 3$     | $k = 1$     | $k = 2$     | $k = 3$     |
| $H^1(T)$      | $-5(-33\%)$ | $-12(-37.5\%)$ | $-21(-37.5\%)$ | $-7(-26\%)$ | $-22(-41\%)$ | $-40(-44\%)$ |
| $H(curl; T)$  | $-5(-18\%)$ | $-12(-18\%)$  | $-21(-17.5\%)$ | $-7(-15\%)$ | $-22(-22\%)$ | $-40(-23\%)$ |

Figure 1: Degrees of freedom on a triangular and pentagonal faces of the discrete $H^1$ and $H(curl)$ spaces for the DDR and SDDR methods, with polynomial degree $k = 3$. A black circle represents a pointwise evaluation, a circle with number $N$ represents a scalar projection on a polynomial space of dimension $N$, and a circle with number $N$ and arrow(s) represents a tangential projection on a polynomial space of dimension $N$ (which is vector-valued, in case of two arrows).

is summarised in Table 1 (see also Tab. 3 for further details and a comparison with classical finite element spaces for $k = 0, 1, 2$); serendipity procedures do not achieve any DOFs reduction for the lowest approximation order $k = 0$, where internal DOFs are not present. We also represent in Figure 1 the degrees of freedom on a triangular and pentagonal face (the later being a typical face in a Voronoi tessellation, as the ones used in the tests of Sect. 6.6).

It has to be noticed that serendipity versions of finite elements on cubical meshes have been recently explored with a DOF count comparable to the present construction (see, e.g., [23] and references therein), but an analysis is presented and shape functions exhibited only for the lowest-order degree. The method discussed here is much more general as it applies to meshes of polyhedral elements, and is additionally designed so as to preserve the commutation properties between the interpolator and discrete differential operators discussed in Section 3.5 of [14].

Having clarified the requirements for compatible serendipity techniques through an abstract framework also enables us to provide an answer to an open question left in [21], namely whether it is possible to perform DOFs
reduction on the discrete $\mathbf{H}(\text{div})$ spaces in a compatible manner. Specifically, we prove in this paper that such a reduction is not possible as it would violate crucial requirements of the discrete complex.

1.3. Structure of the paper

The rest of the paper is organised as follows. In Section 2 we develop an abstract framework for the preservation of the homological and analytical properties in reduced complexes. Section 3 contains a description of the setting (mesh, polynomial spaces), while the original DDR complex of [14] is briefly recalled in Section 4. The construction of the novel serendipity DDR complex is detailed in Section 5 and its properties are proved in Section 6, which also contains numerical tests to assess the performance gain resulting from the reduction of DOFs. Finally, Appendix A contains the proofs of estimates of polynomials from boundary values that are at the origin of the design of the serendipity operators.

2. Blueprint for homological and analytical properties preservation in reduced complexes

Consider a sequence $(X_i, d_i)_i$ of spaces and (discrete) operators defining a complex. An important notion for discrete complexes is that of consistency, which determines a way to “embed” polynomials of certain degrees into the spaces of the complex through the use of interpolators, and states that, when applied to these embedded polynomials, the discrete operators (e.g., the discrete gradient) act as their continuous counterparts (e.g., the usual gradient). To precisely state such consistency properties, we therefore select, for each space $X_i$, a (possibly vector-valued) polynomial space $\mathcal{P}^{k_i}$, and an interpolator $I_i : \mathcal{P}^{k_i} \to X_i$.

\begin{equation}
\begin{array}{c}
\mathcal{P}^{k_i} \\
\downarrow I_i \\
\cdots \\
X_i \\
\downarrow d_i \\
X_{i+1} \\
\downarrow \cdots
\end{array}
\begin{array}{c}
\mathcal{P}^{k_{i+1}} \\
\downarrow I_{i+1} \\
\cdots \\
\hat{X}_i \\
\downarrow \hat{d}_i \\
\hat{X}_{i+1} \\
\downarrow \cdots
\end{array}
\end{equation}

Assume that we have a second sequence of spaces $(\hat{X}_i)_i$ and connecting linear graded maps $E$ and $\hat{R}$ as in Diagram (2.1), and set, for all index $i$,

\begin{equation}
\hat{d}_i := \hat{R}_{i+1} d_i E_i.
\end{equation}

Having this diagram in mind, we will refer to $(X_i, d_i)_i$ as the top sequence and to $(\hat{X}_i, \hat{d}_i)_i$ as the bottom sequence. Since we think of the spaces $\hat{X}_i$ as “reduced” versions (with smaller dimension) of the spaces $X_i$, we hereafter call reductions the maps $\hat{R}$ and extensions the maps $E$. We now list properties on the connecting maps $\hat{R}$, $E$ that ensure that the two sequences have the same cohomology.

Assumption 1 (Homological properties).

(C1) $\hat{R}_i$ is a left-inverse of $E_i$ on $\ker \hat{d}_i$, that is: $(\hat{R}_i E_i)|_{\ker \hat{d}_i} = \text{Id}_{\ker \hat{d}_i}$.

(C2) $(E_{i+1} \hat{R}_{i+1} - \text{Id}_{X_{i+1}})(\ker d_{i+1}) \subset \text{Im} d_i$.

(C3) Both the reduction and extension are cochain maps, i.e., $\hat{R}_{i+1} d_i = \hat{d}_i \hat{R}_i$ and $E_{i+1} \hat{d}_i = d_i E_i$. Equivalently, recalling the definition (2.2) of $d_i$, $\hat{R}_{i+1} d_i = \hat{R}_{i+1} d_i E_i \hat{R}_i$ and $E_{i+1} \hat{R}_{i+1} d_i E_i = d_i E_i$. 

\begin{equation}
\begin{array}{c}
\mathcal{P}^{k_i} \\
\downarrow I_i \\
\cdots \\
X_i \\
\downarrow d_i \\
X_{i+1} \\
\downarrow \cdots
\end{array}
\begin{array}{c}
\mathcal{P}^{k_{i+1}} \\
\downarrow I_{i+1} \\
\cdots \\
\hat{X}_i \\
\downarrow \hat{d}_i \\
\hat{X}_{i+1} \\
\downarrow \cdots
\end{array}
\end{equation}
Continuity of interpolators

**Proposition 2** (Isomorphic cohomologies). Under Assumption 1, the sequence \((\hat{X}_i, \hat{d}_i)_i\) is a complex and the cohomologies of \((X_i, d_i)_i\) and \((\hat{X}_i, \hat{d}_i)_i\) are isomorphic. In particular, if one complex is exact then so is the other.

*Proof.* The fact that \((\hat{X}_i, \hat{d}_i)_i\) is a complex follows from (2.2) and (C3). Denoting now the cohomology groups by \(H_i := \ker d_i / \text{Im } d_{i-1}\) and \(H_* := \ker d_1 / \text{Im } d_0\), by (C3) we can project \(E_i\) and \(\hat{R}_i\) on these groups, defining \([E_i] : H_i \to H_*\) and \([\hat{R}_i] : H_i \to H_*\). By (C1), we have \([\hat{R}_i][E_i] = \text{Id}_{H_i}\) and, by (C2) for \(i - 1\), \([E_{i-1}\hat{R}_i - \text{Id}_{X_{i-1}}] = 0\), so that \([E_i][\hat{R}_i] = \text{Id}_{H_i}\). This proves that \([E_i] : H_i \to H_*\) and \([\hat{R}_i] : H_i \to H_*\) are isomorphisms.

Our goal now is to deduce analytical properties of the bottom sequence based on corresponding properties of the top sequence. To do so, we assume that each \(X_i\) is equipped with an inner product \((\cdot, \cdot)_{X_i}\) with norm \(\|\cdot\|_{X,i}\). The inner product \((\cdot, \cdot)_{\hat{X}_i}\) and associated norm \(\|\cdot\|_{\hat{X},i}\) on \(\hat{X}_i\) are defined so that \(E_i\) is an isometry, that is:

\[
(\hat{x}, \hat{y})_{\hat{X},i} := (E_i \hat{x}, E_i \hat{y})_{X,i} \quad \text{and} \quad \|\hat{x}\|_{\hat{X},i} = \|E_i \hat{x}\|_{X,i} \quad \forall (\hat{x}, \hat{y}) \in \hat{X}_i \times \hat{X}_i.
\] (2.3)

Of importance when considering discrete complexes is the degree of polynomial consistency they preserve, which is measured through the interpolators \(I_i\) in (2.1). Oftentimes, some properties involving interpolators on larger spaces are also useful. We will therefore consider that, for each \(X_i\), there is a Hilbert space \(H_i \supseteq \mathcal{P}^k\), such that the interpolator \(I_i\) can be extended as \(I_i : H_i \to X_i\). The norm on \(H_i\) is denoted by \(\|\cdot\|_{H,i}\), and we define interpolator for the bottom sequence by:

\[
\hat{I}_i := \hat{R}_i I_i : H_i \to \hat{X}_i.
\] (2.4)

To properly define the interpolator, the norm on \(H_i\) is typically quite “strong” (this space corresponds to a Sobolev space). Some estimates and consistency properties will require an “\(L^2\)-like” space \(\mathcal{L}_i\) (with inner product \((\cdot, \cdot)_{\mathcal{L},i}\) and norm \(\|\cdot\|_{\mathcal{L},i}\)) in which \(H_i\) is continuously embedded. We denote by \(c_{H,i}\) the embedding constant such that

\[
\|v\|_{\mathcal{L},i} \leq c_{H,i} \|v\|_{H,i} \quad \forall v \in H_i.
\] (2.5)

We now cite three assumptions that are involved in deducing analytical properties of the bottom sequence from properties of the top sequence.

**Assumption 3** (Analytical properties).

(A1) **Continuity of reductions:** \(\hat{R}_i : X_i \to \hat{X}_i\) is continuous, with norm denoted by \(\|\hat{R}_i\|\).

(A2) **Polynomial consistency:** \(\hat{R}_i\) is a right-inverse of \(E_i\) on the subspace \(I_i(\mathcal{P}^k)\); recalling (2.4), this translate into: \(E_i \hat{I}_i \chi_p = I_i \chi_p\) for all \(\chi_p \in \mathcal{P}^k\).

(A3) **Continuity of interpolators:** \(I_i : H_i \to X_i\) is continuous for the norms \(\|\cdot\|_{H,i}\) and \(\|\cdot\|_{X,i}\), with norm denoted by \(\|\cdot\|_{I_i}\).

**Proposition 4** (Poincaré inequality). Assume (C3) and (A1). If \((X_i, d_i)\) satisfies a Poincaré inequality, then so does \((\hat{X}_i, \hat{d}_i)\). More specifically, if there is \(c_P \geq 0\) such that

\[
\|x\|_{X,i} \leq c_P \|d_i x\|_{X,i+1} \quad \forall x \in (\ker d_i)^\perp
\] (2.6)

then

\[
\|\hat{x}\|_{\hat{X},i} \leq c_P \|\hat{R}_i\| \|\hat{d}_i \hat{x}\|_{\hat{X},i+1} \quad \forall \hat{x} \in (\ker \hat{d}_i)^\perp.
\]

*Proof.* The proof is inspired by that done for conforming discrete complexes in Theorem 5.3 of [1]. Let \(\hat{x} \in (\ker \hat{d}_i)^\perp\). Since \(d_i : (\ker d_i)^\perp \to \text{Im } d_i\) is an isomorphism, there is \(x \in (\ker d_i)^\perp\) such that \(d_i x = d_i E_i \hat{x}\). Using the cochain map property (C3) for the reduction, we infer that \(\hat{d}_i \hat{R}_i x = \hat{R}_{i+1} d_i x = \hat{R}_{i+1} d_i E_i x = \hat{d}_i x\) (where we have used (2.2) to conclude), and thus that \(\hat{R}_i x - \hat{x} \in \ker \hat{d}_i\). Hence, \(\hat{x} \perp (\hat{x} - \hat{R}_i x)\), which gives
\[ \| \hat{x} \|_{X,i} = (\hat{x}, \hat{x})_{X,i} = (\hat{x}, \hat{R}_i x)_{X,i} \leq \| \hat{x} \|_{X,i} \| \hat{R}_i x \|_{X,i} \leq \| \hat{x} \|_{X,i} \| \hat{R}_i \| \| x \|_{X,i}, \]

where the last inequality follows from (A1). Simplifying by \( \| \hat{x} \|_{X,i} \) and applying (2.6), we obtain

\[ \| \hat{x} \|_{X,i} \leq c_p \| \hat{R}_i \| \| d_i x \|_{X,i+1} = c_p \| \hat{R}_i \| \| E_i \hat{x} \|_{X,i+1} = c_p \| \hat{R}_i \| \| E_{i+1} \hat{d}_i x \|_{X,i+1}, \]

where we have used the cochain map property (C3) of the extensions in the last equality. The proof is completed by recalling that \( E_{i+1} \) is an isometry by (2.3), so that \( \| E_{i+1} \hat{d}_i x \|_{X,i+1} = \| \hat{d}_i x \|_{X,i+1}. \)

**Proposition 5** (Primal consistency of inner products). Assume (A2), (A3), and suppose that the top sequence satisfies the polynomial consistency property

\[ (I_i v_p, I_i w_p)_{X,i} = (v_p, w_p)_{\mathcal{L},i} \quad \forall v_p, w_p \in \mathcal{P}^k_i. \]

Then, the bottom sequence satisfies the following properties:

1. Polynomial consistency:
\[ (\hat{I}_i v_p, \hat{I}_i w_p)_{\hat{X},i} = (v_p, w_p)_{\mathcal{L},i} \quad \forall v_p, w_p \in \mathcal{P}^k_i. \]  
\[ (2.7) \]

2. Consistency in \( \mathcal{H}_i \): Assuming (A1), for all \( v, w \in \mathcal{H}_i \),

\[ \left| (\hat{I}_i v, \hat{I}_i w)_{\hat{X},i} - (v, w)_{\mathcal{L},i} \right| \leq \left( \| \hat{R}_i \| \| I_i \| + c_{\mathcal{H}_i}^2 \right) \times \left( \omega_{\mathcal{H},\mathcal{P},i}(v) \| w \|_{\mathcal{H},i} + \omega_{\mathcal{H},\mathcal{P},i}(w) \| v \|_{\mathcal{H},i} \right), \]

where \( \omega_{\mathcal{H},\mathcal{P},i}(\xi) := \inf_{\xi_p \in \mathcal{P}^k_i} \| \xi - \xi_p \|_{\mathcal{H},i} \quad \forall \xi \in \mathcal{H}_i. \)

**Remark 6** (Scaling of the \( \mathcal{H}_i \)-norm). To ensure that \( \omega_{\mathcal{H},\mathcal{P},i}(\xi) \) has optimal decay properties with respect to the meshsize, the norm \( \| \cdot \|_{\mathcal{H},i} \) on \( \mathcal{H}_i \) should be chosen to scale as an \( L^2 \)-norm (e.g., multiplying norms of derivatives of \( \xi \) by the appropriate characteristic length; see for example the choices in [14, Lemma 6]).

**Proof.** For the polynomial consistency we simply write, for \( v_p, w_p \in \mathcal{P}^k_i \),

\[ \left( \hat{I}_i v_p, \hat{I}_i w_p \right)_{\hat{X},i} \overset{(2.3)}{=} \left( E_i I_i v_p, E_i I_i w_p \right)_{X,i} \overset{(A2)}{=} (I_i v_p, I_i w_p)_{X,i} = (v_p, w_p)_{\mathcal{L},i}. \]

We now turn to the consistency on \( \mathcal{H}_i \). Let \( v, w \in \mathcal{H}_i \), and take arbitrary \( v_p, w_p \in \mathcal{P}^k_i \). Introducing \( \pm \hat{I}_i v_p \) and \( \pm I_i w_p \) we have

\[ \left( \hat{I}_i v, \hat{I}_i w \right)_{\hat{X},i} = \left( I_i (v - v_p), I_i w \right)_{\hat{X},i} + \left( I_i v_p, I_i (w - w_p) \right)_{\hat{X},i} + \left( \hat{I}_i v_p, \hat{I}_i w_p \right)_{\hat{X},i}, \]

(2.8)

Invoking the polynomial consistency (2.7), we can write, for the last term in (2.8),

\[ \left( \hat{I}_i v_p, \hat{I}_i w_p \right)_{\hat{X},i} = (v_p, w_p)_{\mathcal{L},i} = (v_p - v, w_p)_{\mathcal{L},i} + (v, w_p - w)_{\mathcal{L},i} + (v, w)_{\mathcal{L},i}. \]
Plugging this into (2.8) and using \[ \| \hat{I}_i \|_{\hat{X},i} \leq \| \hat{R}_i \| \| I_i \|_{\mathcal{H},i} \] for all \( \xi \in \mathcal{H}_i \) (which results from (2.4), (A1), and (A3)) along with (2.5), we obtain
\[
\left( \hat{I}_i v, \hat{I}_i w \right)_{\hat{X},i} - (v, w)_{\mathcal{L},i} \leq \| \hat{R}_i \|^2 \| I_i \|^2 \left( \| v - v_p \|_{\mathcal{H},i} \| w \|_{\mathcal{H},i} + \| w - w_p \|_{\mathcal{H},i} \right)
+ c_{\mathcal{H},i} \left( \| v - v \|_{\mathcal{H},i} \| w_p \|_{\mathcal{H},i} + \| w_p - w \|_{\mathcal{H},i} \| v \|_{\mathcal{H},i} \right).
\]
The proof is completed by writing \( \| v_p \|_{\mathcal{H},i} \leq \| v - v \|_{\mathcal{H},i} + \| v \|_{\mathcal{H},i} \) and similarly for \( w_p \), and taking the infimum over \( v_p, w_p \in \mathcal{P}^{k_i} \).

As the sequences we consider in the following sections are “fully discrete” (that is, the discrete spaces are those of the degrees of freedom of the method), they are not naturally related to any polynomial function on the computational domain. Instead, such functions are obtained through potential reconstructions, mappings that build from a set of degrees of freedom some polynomial functions on the mesh elements. We therefore assume, for all index \( i \), the existence of a linear map \( P_i : X_i \rightarrow \mathcal{P}^{k_i} \), the norm of which (when \( \mathcal{P}^{k_i} \) is endowed with the \( \mathcal{L}_p \)-norm) is denoted by \( \| P_i \| \). We then set
\[
\hat{P}_i := P_i E_i : X_i \rightarrow \mathcal{P}^{k_i}.
\]
The proof of the following primal consistency result is done as the proof of Proposition 5 and is therefore omitted.

**Proposition 7** (Primal consistency of potential reconstructions). Assume (A1)–(A3), and that \( P_i \) is polynomially consistent, in the sense that \( P_i I_i v_p = v_p \) for all \( v_p \in \mathcal{P}^{k_i} \). Then, \( \hat{P}_i \) is also polynomially consistent, in the sense that \( \hat{P}_i \hat{I}_i v_p = v_p \) for all \( v_p \in \mathcal{P}^{k_i} \), and we moreover have
\[
\| \hat{P}_i \hat{I}_i v - v \|_{\mathcal{L},i} \leq \left( \| P_i \| \| \hat{R}_i \| \| I_i \| + 1 \right) \omega_{\mathcal{H},p,i}(v), \quad \forall v \in \mathcal{H}_i.
\]
Commutation properties for discrete differential operators are essential tools for designing schemes that are robust with respect to physical parameters [16, 24]. They also naturally lead to optimal consistency properties. Both properties are considered in the following proposition.

**Proposition 8** (Commutation and consistency of differential operators). Assume (C3) and that, for some unbounded operator \( D_i : \mathcal{H}_i \rightarrow \mathcal{H}_{i+1} \) with domain \( \text{dom}(D_i) \), the commutation property \( I_{i+1} D_i = d_i I_i \) holds on \( \text{dom}(D_i) \) for the top sequence. Then, it also holds for the bottom sequence: \( \hat{I}_{i+1} D_i = d_i \hat{I}_i \) on \( \text{dom}(D_i) \).

As a consequence, if (A1)–(A3) hold, and if the potential reconstruction \( P_{i+1} \) is polynomially consistent, then
\[
\| \hat{P}_{i+1} d_i \hat{I}_i v - D_i v \|_{\mathcal{L},i+1} \leq \left( \| P_{i+1} \| \| \hat{R}_{i+1} \| \| I_{i+1} \| + 1 \right) \omega_{\mathcal{H},p,i+1}(D_i v) \quad \forall v \in \text{dom}(D_i).
\]

**Proof.** We simply write
\[
\hat{d}_i \hat{I}_i = \hat{d}_i \hat{R}_i I_i = \hat{R}_{i+1} d_i I_i = \hat{R}_{i+1} I_{i+1} D_i = \hat{I}_{i+1} D_i,
\]
where the third equality comes from the commutation property for the top sequence. The consistency property (2.9) then directly follows by writing \( \hat{P}_{i+1} d_i \hat{I}_i v - D_i v = \hat{P}_{i+1} \hat{I}_{i+1} D_i v - D_i v \) and applying Proposition 7 with \((i+1, D_i v)\) instead of \((i, v)\).

**Remark 9** (Consistency in non-Hilbert spaces). The primal consistency of the potential reconstruction and the discrete differential operator do not rely on the inner product of the spaces \( \mathcal{H} \), and could therefore also be stated with non-Hilbert spaces.

Adjoint consistency error bounds are crucial to establish error estimates for numerical schemes based on non-conforming complexes. The following proposition shows that, if the top sequence satisfies an adjoint consistency...
estimate, then so does the bottom sequence. Contrary to the previous results, which are mostly useful for local complexes (that is, with spaces restricted to one mesh element), adjoint consistency is really meaningful only for global complexes (that is, with spaces on the entire mesh). We therefore assume in what follows that the complex $\mathcal{X}_i$, is built by patching local complexes $(\mathcal{X}_{i,T}, \mathcal{P}_{i,T})$, together; the global inner products are also obtained by summing local inner products, and all local quantities (norms, potential reconstructions, polynomial approximation errors, etc.) are indicated by an index $T$.

**Proposition 10** (Adjoint consistency). Assume that \( (A1)-(A3) \) hold for the local complexes, and that \( (C3) \) holds for the global complex. Consider an unbounded operator $D^*_i : \mathcal{L}_{i+1} \rightarrow \mathcal{L}_i$ with domain $\mathcal{D}^*_i$. Let $u \in \mathcal{H}_{i+1}\cap \text{dom}(D^*_i)$ and define the adjoint consistency error of the top and bottom sequences, respectively, by

\[
E_i(u) := \sup_{x \in \mathcal{X}_i \setminus \{0\}} \frac{(I_{i+1} u, d_i x)_{X,i+1} + \sum_T (D^*_i u, P_{i,T} x)_{\mathcal{L},i,T}}{\|x\|_{X,i} + \|d_i x\|_{X,i+1}},
\]

\[
\hat{E}_i(u) := \max_{\hat{x} \in \mathcal{X}_i \setminus \{0\}} \frac{(\hat{I}_{i+1} u, \hat{d}_i \hat{x})_{\hat{X},i+1} + \sum_T (D^*_i u, \hat{P}_{i,T} \hat{x})_{\mathcal{L},i,T}}{\|\hat{x}\|_{\hat{X},i} + \|\hat{d}_i \hat{x}\|_{\hat{X},i+1}}.
\]

Then, the following estimate holds:

\[
\hat{E}_i(u) \leq E_i(u) + \left( \sum_T \left( \left\| \hat{R}_{i+1,T} \right\|^2 + 1 \right)^2 \|I_{i+1,T}\|^2 \omega_{\mathcal{H},\mathcal{P},i+1,T}(u)^2 \right)^{1/2}.
\]

**Proof.** We first notice that, for all $u_p \in \mathcal{P}^T_{i+1}$, $E_{i+1,T} \hat{I}_{i+1,T} u_p - I_{i+1,T} u_p = 0$ by \( (A2) \) for the local complex corresponding to $T$ with $i+1$ instead of $i$. Hence, inserting this quantity into the left-hand side norm below, using a triangle inequality, invoking the isometry property of $E_{i+1,T}$ and (2.4) to write $\|E_{i+1,T} \hat{I}_{i+1,T}\|_{X,i+1,T} = \|\hat{R}_{i+1,T} I_{i+1,T}\|_{X,i+1,T}$, and taking the infimum over $u_p$, we have

\[
\|E_{i+1,T} \hat{I}_{i+1,T} u - I_{i+1,T} u\|_{X,i+1,T} \leq \inf_{u_p \in \mathcal{P}^T_{i+1}} \left( \|E_{i+1,T} \hat{I}_{i+1,T} (u - u_p)\|_{X,i+1,T} + \|I_{i+1,T} (u_p - u)\|_{X,i+1,T} \right)
\]

\[
\quad \quad \leq \left( \|\hat{R}_{i+1,T}\| + 1 \right) \|I_{i+1,T}\| \omega_{\mathcal{H},\mathcal{P},i+1,T}(u).
\]

Recalling (2.3), we then write, for $\hat{x} \in \hat{X}_i$,

\[
(\hat{I}_{i+1,T} u, \hat{d}_i \hat{x})_{\hat{X},i+1} = (I_{i+1} \hat{I}_{i+1,T} u, E_{i+1} \hat{d}_i \hat{x})_{X,i+1} = (I_{i+1} u, d_i E_i \hat{x})_{X,i+1} + (E_{i+1} \hat{I}_{i+1,T} u - I_{i+1,T} u, d_i E_i \hat{x})_{X,i+1},
\]

where the second line is obtained inserting $\pm \hat{I}_{i+1,T}$ and using the cochain map property \( (C3) \) of the extension to write $E_{i+1} \hat{d}_i \hat{x} = d_i E_i \hat{x}$. Invoking then (2.10) for each $T$, the definition of $E_i(u)$ with $x = E_i \hat{x}$, and $P_{i,T} x = P_{i,T} E_i \hat{x} = \hat{P}_{i,T} \hat{x}$, together with the fact that the inner products on the complex spaces are obtained summing the local inner products for each $T$, we infer

\[
(\hat{I}_{i+1,T} u, \hat{d}_i \hat{x})_{\hat{X},i+1} + \sum_T (D^*_i u, \hat{P}_{i,T} \hat{x})_{\mathcal{L},i,T} \leq E_i(u) \left( \|E_i \hat{x}\|_{X,i} + \|d_i E_i \hat{x}\|_{X,i+1} \right)
\]

\[
+ \left( \sum_T \left( \left\| \hat{R}_{i+1,T} \right\|^2 + 1 \right)^2 \|I_{i+1,T}\|^2 \omega_{\mathcal{H},\mathcal{P},i+1,T}(u)^2 \right)^{1/2} \|d_i E_i \hat{x}\|_{X,i+1}.
\]
The proof is completed by noticing that, by isometry and cochain map property (C3) of the extensions, 
\[ \|E_i\hat{x}\|_{X,i} + \|d_i E_i\hat{x}\|_{X,i+1} = \|\hat{x}\|_{X,i} + \|d_i\hat{x}\|_{X,i+1}. \]

3. Setting

3.1. Domain and mesh

Let \( \Omega \subset \mathbb{R}^3 \) denote a connected polyhedral domain. We consider, as in [14], a polyhedral mesh \( \mathcal{M}_h := T_h \cup F_h \cup E_h \cup V_h \) where \( T_h \) gathers the elements, \( F_h \) the faces, \( E_h \) the edges, and \( V_h \) the vertices. For all \( P \in \mathcal{M}_h \), we denote by \( h_P \) its diameter and set \( h := \max_{T \in T_h} h_T \). For each face \( F \in F_h \), we fix a unit normal \( \mathbf{n}_F \) to \( F \) and, for each edge \( E \in E_h \), a unit tangent \( \mathbf{t}_E \). For \( T \in T_h, F_T \) gathers the faces on the boundary \( \partial T \) of \( T \) and \( E_T \) the edges in \( \partial T \); if \( F \in F_T, E_F \) is the set of edges contained in the boundary \( \partial F \) of \( F \). For \( F \in F_T, \omega_{TF} \in \{-1, 1\} \) is such that \( \omega_{TF} \mathbf{n}_F \) is the outer normal on \( F \) to \( T \).

Each face \( F \in F_h \) is oriented counter-clockwise with respect to \( \mathbf{n}_F \) and, for \( E \in E_F \), we let \( \omega_{FE} \in \{-1, 1\} \) be such that \( \omega_{FE} = +1 \) if \( t_E \) points along the boundary \( \partial F \) of \( F \) in the clockwise sense, and \( \omega_{FE} = -1 \) otherwise; we also denote by \( \mathbf{n}_{FE} \) the unit normal vector to \( E \), in the plane spanned by \( F \), such that \( (\mathbf{t}_E, \mathbf{n}_{FE}, \mathbf{n}_F) \) is a right-handed system of coordinate (so that, in particular, \( \omega_{FE} \mathbf{n}_{FE} \) points outside \( F \)). We denote by \( \text{grad}_F \) and \( \text{div}_F \) the tangent gradient and divergence operators acting on smooth enough functions. Moreover, for any \( r : F \to \mathbb{R} \) and \( z : F \to \mathbb{R}^2 \) smooth enough, we let \( \text{rot}_F r := (\text{grad}_F r) \perp \) and \( \text{rot}_F z = \text{div}_F (z \perp) \), with \( \perp \) denoting the rotation of angle \( -\frac{\pi}{2} \) in the oriented tangent space to \( F \).

We further assume that \((T_h, \mathcal{F}_h)\) belongs to a regular mesh sequence as per Definition 1.9 of [11], with mesh regularity parameter \( q > 0 \). This assumption ensures the existence, for each \( P \in T_h \cup F_h \cup E_h \), of a point \( x_P \in P \) such that the ball centered at \( x_P \) and of radius \( q h_P \) is contained in \( P \).

3.2. Polynomial spaces and \( L^2 \)-orthogonal projectors

For any \( P \in \mathcal{M}_h \) and an integer \( \ell \geq 0 \), we denote by \( \mathcal{P}^\ell(P) \) the space spanned by the restriction to \( P \) of polynomial functions of the space variables. The subspace of \( \mathcal{P}^\ell(P) \) spanned by polynomials with zero average on \( P \) is denoted by \( \mathcal{P}^{0,\ell}(P) \). Letting \( \mathcal{P}^\ell(P) := \mathcal{P}^\ell(P)^n \) for \( P \in T_h \) and \( n = 3 \) or \( P \in F_h \) and \( n = 2 \), it holds: For all \( F \in F_h \),

\[ \mathcal{P}^\ell(F) = \mathcal{G}^\ell(F) \oplus \mathcal{G}^{c,\ell}(F) \quad \text{with} \quad \mathcal{G}^\ell(F) := \text{grad}_F \mathcal{P}^{\ell+1}(F) \quad \text{and} \quad \mathcal{G}^{c,\ell}(F) := (x - x_F) \perp \mathcal{P}^{\ell-1}(F) \]

(3.1)

and, for all \( T \in T_h \),

\[ \mathcal{P}^\ell(T) = \mathcal{G}^\ell(T) \oplus \mathcal{G}^{c,\ell}(T) \quad \text{with} \quad \mathcal{G}^\ell(T) := \text{grad} \mathcal{P}^{\ell+1}(T) \quad \text{and} \quad \mathcal{G}^{c,\ell}(T) := (x - x_T) \times \mathcal{P}^{\ell-1}(T) \]

(3.3)

We extend the above notations to negative exponents \( \ell \) by setting all the spaces appearing in the decompositions equal to the trivial vector space \( \{0\} \). Given a polynomial (sub)space \( \mathcal{X}^\ell(P) \) on \( P \in \mathcal{M}_h \), the corresponding \( L^2 \)-orthogonal projector is denoted by \( \pi_{\mathcal{X}^\ell} \). Boldface font will be used when the elements of \( \mathcal{X}^\ell(P) \) are vector-valued, and \( \pi_{\mathcal{X}^{c,\ell}} \) denotes the \( L^2 \)-orthogonal projector on \( \mathcal{X}^{c,\ell}(P) \). The spaces in the above decompositions are hierarchical, i.e., for all \( \mathcal{X} \subset \{G, R\} \) and all \( P \in T_h \cup F_h \), \( \mathcal{X}^{c,\ell}(F) \subset \mathcal{X}^{c,\ell}(P) \). In what follows, we will frequently use this property to write, for all integers \( \ell \leq k - 1 \) and \( P \in T_h \cup F_h \),

\[ \pi_{\mathcal{X}^{c,\ell+1}} \pi_{\mathcal{X}^{c,k}} = \pi_{\mathcal{X}^{c,\ell+1}}. \]

(3.5)

4. DDR complex

In this section we briefly recall the DDR complex and refer to Section 3 of [14] for further details. From this point on, we fix an integer \( k \geq 0 \) corresponding to the polynomial degree of the complex.
4.1. Spaces and component norms

The DDR counterparts of $H^1(\Omega)$, $H(\text{curl}; \Omega)$, $H(\text{div}; \Omega)$ and $L^2(\Omega)$ are respectively defined as follows:

$$X^{k}_{\text{grad},h} := \left\{ q_h = ((q_T)_{T \in T_h}, (q_F)_{F \in \mathcal{F}_h}, q_{\mathcal{E}_h}) : q_T \in \mathcal{P}^{k-1}(T) \text{ for all } T \in T_h, q_F \in \mathcal{P}^{k-1}(F) \text{ for all } F \in \mathcal{F}_h, \text{ and } q_{\mathcal{E}_h} \in \mathcal{P}^{k+1}_{c}(\mathcal{E}_h) \right\},$$

with $\mathcal{P}^{k+1}_{c}(\mathcal{E}_h)$ denoting the space of functions that are continuous on the mesh edge skeleton and the restriction of which to each $E \in \mathcal{E}_h$ belongs to $\mathcal{P}^{k+1}(E)$,

$$X^{k}_{\text{curl},h} := \left\{ v_h = \left( (v_{\mathcal{R},T}, \mathcal{R}_{\mathcal{T},T})_{T \in T_h}, (v_{\mathcal{R},F}, \mathcal{R}_{\mathcal{F},F})_{F \in \mathcal{F}_h}, (v_E)_{E \in \mathcal{E}_h} \right) : v_{\mathcal{R},T} \in \mathcal{R}^{k-1}(T) \text{ and } \mathcal{R}_{\mathcal{T},T} \in \mathcal{R}^{c,k}(T) \text{ for all } T \in T_h, v_{\mathcal{R},F} \in \mathcal{R}^{k-1}(F) \text{ and } \mathcal{R}_{\mathcal{F},F} \in \mathcal{R}^{c,k}(F) \text{ for all } F \in \mathcal{F}_h, \text{ and } v_E \in \mathcal{P}^{k}(E) \text{ for all } E \in \mathcal{E}_h \right\},$$

$$X^{k}_{\text{div},h} := \left\{ w_h = \left( (w_{\mathcal{G},T}, \mathcal{G}_{\mathcal{T},T})_{T \in T_h}, (w_F)_{F \in \mathcal{F}_h} \right) : w_{\mathcal{G},T} \in \mathcal{G}^{k-1}(T) \text{ and } \mathcal{G}_{\mathcal{T},T} \in \mathcal{G}^{c,k}(T) \text{ for all } T \in T_h, \text{ and } w_F \in \mathcal{P}^{k}(F) \text{ for all } F \in \mathcal{F}_h \right\},$$

and

$$\mathcal{P}^{k}(T_h) := \left\{ q_h \in L^2(\Omega) : (q_h)|_T \in \mathcal{P}^{k}(T) \text{ for all } T \in T_h \right\}.$$

Throughout this paper, we use underlines to denote vectors whose components are polynomials, and boldface fonts when some of these components are vector-valued. The same convention applies to the discrete operators defined in Section 4.3 below.

The corresponding interpolators are denoted by $I^{k}_{\text{grad},h}$, $I^{k}_{\text{curl},h}$, $I^{k}_{\text{div},h}$, and $\pi^{k}_{p,h}$ (using the same underlines/boldface convention as above). The interpolator on $X^{k}_{\text{grad},h}$ is defined by (4.9) below, while the remaining interpolators correspond to the $L^2$-projections on the polynomial spaces appearing in the definitions of $X^{k}_{\text{curl},h}$, $X^{k}_{\text{div},h}$, and $\mathcal{P}^{k}(T_h)$, respectively; see [14] for details. The restriction of each of these spaces to a mesh entity $P \in \mathcal{M}_h$ that appears in its definition gathers the polynomial components on $P$ and the geometric entities on its boundary, and is denoted replacing the subscript $h$ by $P$ (e.g., $X^{k}_{\text{grad},T}$ or $X^{k}_{\text{curl},F}$). A similar convention is used for the vectors in such restrictions (e.g., $X^{k}_{F} = (v_{\mathcal{R},F}, \mathcal{R}_{\mathcal{F},F})_{E \in \mathcal{E}_F} \in X^{k}_{\text{curl},F}$) as well as for the interpolators (e.g., $I^{k}_{\text{grad},T}$).

From this point on, to alleviate the notation, for all $P \in \{ \Omega \} \cup T_h \cup \mathcal{F}_h \cup \mathcal{E}_h$, we denote by $\| \|_P$ the standard $L^2(P)$-norm. The same notation is used for the norm of $L^2(P)^n$ (with $n$ denoting the dimension of $P$), any ambiguity being removed by the scalar or vector nature of the argument. In the analysis, we will additionally make use of the following local component $L^2$-norms $\| \|^{k}_{\bullet,P} : X^{k}_{\bullet,P} \rightarrow \mathbb{R}$, for $\bullet \in \{ \text{grad}, \text{curl}, \text{div} \}$ and $P \in T_h \cup \mathcal{F}_h$.
Note that (4.3) fully determines $\gamma$ where $q$ are such that, for all $P_{4.2.1.\ Gradient}$

For future use, we notice that, using discrete inverse and trace inequalities and, for mesh elements, the continuity of $\gamma^{k+1}$ stated in Proposition 6 of [14], it holds, for all $P \in T_h \cup F_h$, 

For $\bullet \in \{\text{grad, curl, div}\}$, a global component $L^2$-norm is obtained setting $\|\|_{\bullet,h} := \left(\sum_{T \in T_h} \|\bullet^2\right)^{1/2}$.

4.2. Discrete vector calculus operators and potentials

The discrete operators and potentials are defined mimicking integration-by-parts formulas, replacing internal/boundary values with those provided by the unknowns in each space.

4.2.1. Gradient

For any $E \in \mathcal{E}_h$, the edge gradient $G^k_E : X^k_{\text{grad},E} \rightarrow \mathcal{P}^k(E)$ is such that, for all $q_E \in X^k_{\text{grad},E}$, $G^k_E q_E = q_E$, where $q_E$ denotes the restriction to $E$ of $q_{E_h}$ and the derivative is taken is the direction $t_E$.

For any $F \in \mathcal{F}_h$, the face gradient $G^k_F : X^k_{\text{grad},F} \rightarrow \mathcal{P}^k(F)$ and the scalar trace $\gamma^{k+1}_F : X^k_{\text{grad},F} \rightarrow \mathcal{P}^{k+1}(F)$ are such that, for all $q_F \in X^k_{\text{grad},F}$,

\[
\int_F G^k_F q_F \cdot v_F = -\int q_F \text{div}_F v_F + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E q_E (v_F \cdot n_{FE}) \quad \forall v_F \in \mathcal{P}^k(F),
\]

Note that (4.3) fully determines $\gamma^{k+1}_F q_F \in \mathcal{P}^{k+1}(F)$ owing to the fact that $\text{div} : \mathcal{R}^{c,k+2}(F) \rightarrow \mathcal{P}^{k+1}(F)$ is an isomorphism.

Similarly, for all $T \in T_h$, the element gradient $G^k_T : X^k_{\text{grad},T} \rightarrow \mathcal{P}^k(T)$ and the scalar potential $p^{k+1}_{\text{grad},T} : X^k_{\text{grad},T} \rightarrow \mathcal{P}^{k+1}(T)$ are defined such that, for all $q_T \in X^k_{\text{grad},T}$,

\[
\int_T G^k_T q_T \cdot v_T = -\int q_T \text{div}_T v_T + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F q^{k+1}_F (v_T \cdot n_F) \quad \forall v_T \in \mathcal{P}^k(T),
\]

For future use, we notice that, using discrete inverse and trace inequalities and, for mesh elements, the continuity of $\gamma^{k+1}_F$ stated in Proposition 6 of [14], it holds, for all $P \in T_h \cup F_h$, 

\[
\|G_P q_P\|_P \lesssim h_P^{-1} \|q_P\|_{\text{grad},P} \quad \forall q_P \in X^k_{\text{grad},P}.
\]
4.2.2. Curl

For all $F \in \mathcal{F}_h$, the face curl $C^k_F : X^k_{\text{curl}, F} \to \mathcal{P}^k(F)$ and the corresponding vector potential (which can be interpreted as a tangential component) $\gamma^k_{\text{curl}} : X^k_{\text{curl}, F} \to \mathcal{P}^k(F)$ are such that, for all $v_F \in X^k_{\text{curl}, F},$

$$\int_F C^k_F v_F \cdot r_F = \int_F v_F \cdot \text{rot}_F r_F - \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E v_F \cdot r_F \quad \forall r_F \in \mathcal{P}^k(F)$$

(4.6)

and, for all $(r_F, w_F) \in \mathcal{P}^{0,k+1}(F) \times \mathcal{R}^{c,k}(F),$

$$\int_F \gamma^k_{\text{curl}, F} r_F \cdot (\text{rot}_F r_F + w_F) = \int_F C^k_F v_F \cdot r_F + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E v_F \cdot r_F + \int_F \mathcal{I}^c_{\text{curl}, F} \cdot w_F.$$

We note that testing $\gamma^k_{\text{curl}, F}$ against $\text{rot}_F r_F$ fixes $\pi^k_{\mathcal{R}^c, F} \gamma^k_{\text{curl}, F} v_F$, while testing against $w_F$ provides the remaining projection $\pi^c_{\mathcal{R}^c, F} \gamma^k_{\text{curl}, F} v_F$ and therefore fixes $\gamma^k_{\text{curl}, F} v_F \in \mathcal{P}^k(F)$ entirely due to (3.1).

For all $T \in \mathcal{T}_h$, the element curl $C^k_T : X^k_{\text{curl}, T} \to \mathcal{P}^k(T)$ and the vector potential $P^k_{\text{curl}, T} : X^k_{\text{curl}, T} \to \mathcal{P}^k(T)$ are defined such that, for all $v_T \in X^k_{\text{curl}, T},$

$$\int_T C^k_T v_T \cdot w_T = \int_T v_T \cdot \text{curl} w_T + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F \gamma^k_{\text{curl}, F} v_F \cdot (w_T \times n_F) \quad \forall w_T \in \mathcal{P}^k(T)$$

(4.7)

and, for all $(w_T, z_T) \in \mathcal{G}^{c,k+1}(T) \times \mathcal{R}^{c,k}(T),$

$$\int_T P^k_{\text{curl}, T} v_T \cdot (\text{curl} w_T + z_T) = \int_T C^k_T v_T \cdot w_T - \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F \gamma^k_{\text{curl}, F} v_F \cdot (w_T \times n_F) + \int_T v^c_{\text{curl}, T} \cdot z_T.$$

4.2.3. Divergence

For all $T \in \mathcal{T}_h$, the element divergence $D^k_T : X^k_{\text{div}, T} \to \mathcal{P}^k(T)$ and vector potential $P^k_{\text{div}, T} : X^k_{\text{div}, T} \to \mathcal{P}^k(T)$ are defined by: For all $w_T \in X^k_{\text{div}, T},$

$$\int_T D^k_T w_T \cdot q_T = - \int_T w_T \cdot \text{grad} q_T + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F w_T q_T \quad \forall q_T \in \mathcal{P}^k(T)$$

(4.8)

and, for all $(r_T, z_T) \in \mathcal{P}^{0,k+1}(T) \times \mathcal{G}^{c,k}(T),$

$$\int_T P^k_{\text{div}, T} w_T \cdot (\text{grad} r_T + z_T) = - \int_T D^k_T w_T \cdot r_T + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F w_T r_T + \int_T w^c_{\text{div}, T} \cdot z_T.$$

4.3. DDR complex

The DDR complex reads:

$$\mathbb{R} \xrightarrow{I^k_{\text{grad}, h}} X^k_{\text{grad}, h} \xrightarrow{\mathcal{G}^k} X^k_{\text{curl}, h} \xrightarrow{C^k} X^k_{\text{div}, h} \xrightarrow{D^k} \mathcal{P}^k(T_h) \xrightarrow{0} \{0\},$$

where the interpolator on $X^k_{\text{grad}, h}$ is such that, for all $q : \Omega \to \mathbb{R}$ smooth enough,

$$I^k_{\text{grad}, h} q := \left( \pi^{k-1}_{p, T} q|_T \right)_{T \in \mathcal{T}_h} \left( \pi^{k-1}_{p, F} q|_F \right)_{F \in \mathcal{F}_h}, q_{\mathcal{E}_h},$$

with $q_{\mathcal{E}_h} \in \mathcal{P}^{k+1}_{\mathcal{E}_h}$ such that

$$q_{\mathcal{E}_h}(x_V) = q(x_V) \text{ for all } V \in \mathcal{V}_h \text{ and } \pi^{k-1}_{p, E} q_{\mathcal{E}_h} = \pi^{k-1}_{p, E} q_{\mathcal{E}_h} \text{ for all } E \in \mathcal{E}_h,$$

(4.9)
and the global discrete gradient, curl, and divergence operators are obtained projecting the local face and element operators onto the appropriate spaces and patching together these projections: for all \((q_h, v_h, w_h) \in X^k_{\text{grad}, h} \times X^k_{\text{curl}, h} \times X^k_{\text{div}, h}\),

\[
\begin{align*}
\mathcal{C}^k_{\text{grad}, h} &:= \left( \left( \pi^{k-1}_{\mathcal{R}, T} \mathcal{C}^k_{\text{grad}, T}, \pi^{c,k}_{\mathcal{R}, T} \mathcal{C}^k_{\text{grad}, T} \right) \right)_{T \in T_h}, \\
\mathcal{C}^k_{\text{curl}, h} &:= \left( \left( \pi^{k-1}_{\mathcal{G}, T} \mathcal{C}^k_{\text{curl}, T}, \pi^{c,k}_{\mathcal{G}, T} \mathcal{C}^k_{\text{curl}, T} \right) \right)_{T \in T_h}, \\
\mathcal{C}^k_{\text{div}, h} &:= \left( \left( \pi^{k-1}_{\mathcal{P}, T} \mathcal{C}^k_{\text{div}, T}, \pi^{c,k}_{\mathcal{P}, T} \mathcal{C}^k_{\text{div}, T} \right) \right)_{T \in T_h},
\end{align*}
\]

\((D^k_h w_h)_{|T} := D^k h w_T, \forall T \in T_h.\)

4.4. Discrete \(L^2\)-products and norms

For \(\bullet \in \{\text{grad, curl, div}\}\), we define a discrete \(L^2\)-product on \(X^k_{\bullet, h}\) setting, for all \(x_h, y_h \in X^k_{\bullet, h}\),

\[
(x_h, y_h)_{\bullet, h} := \sum_{T \in T_h} (x_T, y_T)_{\bullet, T},
\]

with local contribution such that, denoting by \(P^l_{\bullet, T}\) the potential on \(X^k_{\bullet, T}\) (with \(l = k + 1\) if \(\bullet = \text{grad}\), \(l = k\) otherwise),

\[
(x_T, y_T)_{\bullet, T} := \int_T P^l_{\bullet, T} x_T \cdot y_T + s_{\bullet, T}(x_T, y_T).
\]

Above, \(s_{\bullet, T} : X^k_{\bullet, T} \times X^k_{\bullet, T} \to \mathbb{R}\) is a local stabilisation bilinear form, the precise expression of which can be found in Section 4.4 of [14] and whose role is to control the differences between the traces of the potentials \(P^k_{\bullet, T}\) and the degrees of freedom on the boundary of \(T\). We will also need, in what follows, the discrete global and local \(L^2\)-norms induced by the above \(L^2\)-products, that will be denoted by \(\|\cdot\|_{\bullet, h}\) and \(\|\cdot\|_{\bullet, T}\), respectively.

5. Serendipity DDR complex

As demonstrated by the example of the DDR complex, polytopal discrete complexes have degrees of freedom (DOFs) attached to mesh entities of various dimensions: elements, faces, edges, vertices. Their specific choice is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency. The principle for constructing a serendipity version is to notice that, on a polygonal face (resp. polyhedral element), the knowledge of a polynomial on the boundary is related to the degree of their polynomial consistency.

Following the notations of Section 2, this principle guides the construction of the serendipity spaces \(\hat{X}_{\bullet, h}\), in which face or element internal DOFs that are not required to reconstruct polynomials of the desired degree are removed. The reduction map \(\hat{R}\) consists in removing these DOFs, while the extension map \(E\) re-creates these DOFs by fixing them to those of the polynomial reconstructed from the boundary and remaining internal DOFs; this way, DOFs representing in \(X_{\bullet, i}\) (through \(I_{\bullet, j}\)) polynomials in \(P^k_{\bullet, i}\) are exactly recovered, ensuring the polynomial consistency expressed by (A2), which is a driving property in the process.

This design, however, has a caveat, as the DOFs removed on a lower-dimensional entity (e.g., a face) can impact some components of the discrete differential operators on higher-dimensional entities (e.g., an element); in particular, to ensure the cochain map property (C3), the values of the reduction operator attached to higher-dimensional entities might have to be adjusted to account for the removal of DOFs on lower-dimensional entities. The design of the reduction operator is thus initially inspired by the consistency property, but must then be tuned to fulfill Assumption 1, which relates to the choice of serendipity spaces in each vertical section of Diagram (2.1).

The rest of this section shows how to apply these principles to the DDR sequence presented in [14, 16]. In this context, focusing on the local sequence on an element \(T\) of the mesh, Diagram (2.1) becomes Diagram (5.1).
Table 2: Synoptic table of the operators appearing in the construction of the SDDR complex.

| Notation | Name | Definition |
|----------|------|------------|
| \( S^k_{\text{grad},F} \) | Gradient serendipity operator on faces | Problem (5.5) with \( \mathcal{L}_F \) given by (5.14) |
| \( S^k_{\text{curl},F} \) | Curl serendipity operator on faces | Problem (5.5) with \( \mathcal{L}_F \) given by (5.16) |
| \( E_{\text{grad},F} \) | Gradient extension on faces | Equation (5.18) |
| \( E_{\text{curl},F} \) | Curl extension on faces | Equation (5.19) |
| \( \hat{R}_{\text{grad},F} \) | Gradient reduction on faces | Equation (5.23) |
| \( \hat{R}_{\text{curl},F} \) | Curl reduction on faces | Equation (5.24) |
| \( S^k_{\text{grad},T} \) | Gradient serendipity operator on elements | Problem (5.26) with \( \mathcal{L}_T \) given by (5.28) |
| \( S^k_{\text{curl},T} \) | Curl serendipity operator on elements | Problem (5.26) with \( \mathcal{L}_T \) given by (5.30) |
| \( E_{\text{grad},T} \) | Gradient extension on elements | Equation (5.32) |
| \( E_{\text{curl},T} \) | Curl extension on elements | Equation (5.33) |
| \( \hat{R}_{\text{grad},T} \) | Gradient reduction on elements | Equation (5.35) |
| \( \hat{R}_{\text{curl},T} \) | Curl reduction on elements | Equation (5.36) |

below. The operators that appear in the construction of the SDDR complex are summarized in Table 2.

\[
\begin{align*}
\mathcal{P}^{k+1}(T) & \overset{\hat{I}^k_{\text{grad},T}}{\longrightarrow} \mathcal{P}^k(T) & \overset{\hat{I}^k_{\text{curl},T}}{\longrightarrow} \mathcal{P}^k(T) & \overset{\hat{I}^k_{\text{div},T}}{\longrightarrow} \mathcal{P}^k(T) \\
\mathbb{R}^k & \overset{\hat{L}^k_{\text{grad},T}}{\longrightarrow} \mathcal{X}^k_{\text{grad},T} & \overset{\hat{G}^k_{\text{curl},T}}{\longrightarrow} \mathcal{X}^k_{\text{curl},T} & \overset{\hat{C}^k_{\text{div},T}}{\longrightarrow} \mathcal{X}^k_{\text{div},T} & \overset{D_{\hat{P}}^k}{\longrightarrow} & \mathcal{P}^k(T) & \longrightarrow 0
\end{align*}
\]

Remark 11 (No serendipity for \( \mathcal{X}^k_{\text{div},T} \) spaces). Notice that no serendipity is performed on the space \( \mathcal{X}^k_{\text{div},T} \). The strong objection to reducing the DOFs in that space is discussed in Section 6.5.

The global complexes are obtained collecting the local components of the spaces and operators and enforcing their single-valuedness on vertices, edges, and faces internal to the domain. For the global complex, the polynomial consistency property is not relevant. A comparison in terms of DOFs count for tetrahedral and hexahedral elements among SDDR, DDR, and (non-serendipity) finite elements is provided in Table 3.

In the rest of this paper, as can be seen in Diagram (5.1) and in line with the notations adopted in Section 2, the objects related to the SDDR complex (spaces, discrete operators, vectors), as well as the reduction maps (having co-domain in serendipity spaces), will be denoted with a hat, to visually distinguish them from objects related to the DDR complex.

5.1. Boundary selection and notation for inequalities

As discussed above, designing serendipity versions of the DDR spaces requires to reconstruct polynomials inside elements/faces from boundary values on selected faces/edges. To ensure a stable reconstruction, the
Table 3: Dimension of the local spaces in the DDR $\odot$ SDDR $\odot$ Raviart–Thomas–Nédélec FEM discrete Hilbert complexes of comparable degree $k \in \{0, 1, 2\}$ on a tetrahedron ($\eta_T = 4$ and $\eta_F = 3$ for all $F \in \mathcal{F}_T$) and a hexahedron ($\eta_T = 6$ and $\eta_F = 4$ for all $F \in \mathcal{F}_T$).

| Discrete space | Tetrahedron | Hexahedron |
|----------------|-------------|------------|
| $H^1(T)$       | $4 \odot 4 \odot 4$ | $15 \odot 10 \odot 10$ |
| $H(\curl; T)$ | $6 \odot 6 \odot 6$ | $28 \odot 23 \odot 20$ |
| $H(\text{div}; T)$ | $4 \odot 4 \odot 4$ | $18 \odot 15 \odot 15$ |
| $L^2(T)$       | $1 \odot 1 \odot 1$ | $4 \odot 4 \odot 4$ |

selection of these faces/edges must be done in such a way that they are not close to being aligned. This is stated more precisely in the following assumption.

**Assumption 12** (Boundaries selection for serendipity spaces). For each $P$ element (resp. face) of the mesh, we select a set $\mathcal{B}_{s,P}$ of $\eta_P \geq 2$ faces (resp. edges) that are not pairwise aligned and such that $P$ lies entirely on one side of the hyperplane $H_b$ spanned by each $b \in \mathcal{B}_{s,P}$. The scaled distance function to $H_b$ is defined by $\text{dist}_{\mathcal{B}_b}(x) = h_b^{-1}(x - x_b) \cdot n_{pb}$, with $n_{pb}$ outer normal to $P$ on $b$. Finally, we define a boundaries selection regularity parameter $\theta > 0$ such that $\text{dist}_{\mathcal{B}_b}(x_b) \geq \theta$ for all $b \neq b'$ in $\mathcal{B}_{s,P}$.

From this point on, $a \lesssim b$ (resp., $a \gtrsim b$) means $a \leq Cb$ (resp. $a \geq Cb$) with $C$ only depending on $\Omega$, $k$, the mesh regularity parameter $q$ (cf. Sect. 3.1), and the boundaries selection regularity parameter $\theta$. We also write $a \simeq b$ as a shorthand for “$a \lesssim b$ and $b \lesssim a$”.

**Remark 13** (Trivial boundaries selection). We can always select two faces (resp. edges) in each element (resp. face) such that $\theta \gtrsim q$. This minimal selection corresponds to the absence of serendipity, as can be easily verified by noticing that, in this case, equations (5.4) and (5.25) below give $\ell_P = k - 1$ for $P \in \mathcal{T}_h \cup \mathcal{F}_h$.

### 5.2. Estimates of polynomials from boundary values

We state in this section some bounds of polynomial functions on polytopes in terms of boundary values and, possibly, reduced projections in the interior of the polytope. Similar estimates have been established in the recent preprint [25], but only for 2D convex polygons and with a proof by contradiction that, contrary to the one developed in Appendix A, does not allow for a direct estimate of the constants.

**Lemma 14** (Estimate of scalar polynomials from boundary values). Let $k \geq 0$ and let Assumption 12 hold. Let $P \in \mathcal{T}_h \cup \mathcal{F}_h$ be a mesh element or face. Then, it holds

$$
\|q\|_P \lesssim \|\pi_P^{k+1-n_P} q\|_P + h_P^{\frac{1}{2}} \sum_{b \in \mathcal{B}_{s,P}} \|q_b\|_b \quad \forall q \in \mathcal{P}^{k+1}(P).
$$

**Proof.** See Section A.1. □

**Lemma 15** (Estimate of vector polynomials from tangential boundary values). Let $k \geq 0$ and let Assumption 12 hold. Let $P \in \mathcal{T}_h \cup \mathcal{F}_h$ be a mesh element or face. Then, denoting by $\mathcal{B}_P$ the set of faces (if $P$ is an element) or edges (if $P$ is a face) of $P$, it holds

$$
\|v\|_P \lesssim \left( \|\pi_{R_P} v\|_P^2 + \|\pi_{R_P}^{-1} v\|_P^2 + \sum_{b \in \mathcal{B}_P} h_P \|v_{t,b}\|_b^2 \right)^{1/2} \quad \forall v \in \mathcal{P}^k(P),
$$

where $v_{t,b}$ is the tangential component of $v$ on $b$ (that is, $v_{t,b} = v_{|E} \cdot t_E$ if $b = E$ is an edge, $v_{t,b} = n_F \times (v_{|F} \times n_F)$ if $b = F$ is a face).

**Proof.** See Section A.2. □
5.3. Serendipity, extension, and reduction operators on faces

5.3.1. Serendipity problem

For a face \( F \in \mathcal{F}_k \), recalling that \( \eta_F \) is defined in Assumption 12, we let
\[
\ell_F := k + 1 - \eta_F \leq k - 1. \tag{5.4}
\]
Given a linear form \( \mathcal{L}_F : \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F) \to \mathbb{R} \), we consider the following problem: Find \( (\sigma, \lambda) \in \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F) \) such that
\[
A_F((\sigma, \lambda), (\tau, \mu)) = \mathcal{L}_F(\tau, \mu) \quad \forall (\tau, \mu) \in \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F), \tag{5.5}
\]
with bilinear form \( A_F : [\mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F)]^2 \to \mathbb{R} \) such that
\[
A_F((v, \nu), (\tau, \mu)) := h_F \sum_{E \in \mathcal{E}_F} \int_E (v \cdot t_E) (\tau \cdot t_E) + h_F^2 \int_F \text{rot}_F v \cdot \text{rot}_F \tau + \int_F v \cdot \mu - \int_F \tau \cdot \nu. \tag{5.6}
\]

**Proposition 16** (Well-posedness of the serendipity problem on faces). The serendipity problem (5.5) admits a unique solution which satisfies
\[
\|(\sigma, \lambda)\|_F := \|\sigma\|_F + \|\lambda\|_F \lesssim \|\mathcal{L}_F\|_F \tag{5.7}
\]
where \( \|\mathcal{L}_F\|_F \) is the norm of the linear form \( \mathcal{L}_F \) induced by the \( L^2 \)-norm on \( \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F) \).

**Proof.** The estimate (5.7) classically follows from the following inf-sup condition on \( A_F \): For all \( (v, \nu) \in \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F) \),
\[
\|(v, \nu)\|_F \lesssim \sup_{(\tau, \mu) \in \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F) \setminus \{(0, 0)\}} \frac{A_F((v, \nu), (\tau, \mu))}{\|(\tau, \mu)\|_F} := S. \tag{5.8}
\]
Let us prove this condition. Taking \( (\tau, \mu) = (v, \nu) \) in the definition (5.6) of \( A_F \), we obtain
\[
h_F \sum_{E \in \mathcal{E}_F} \|v \cdot t_E\|^2_E + h_F^2 \|	ext{rot}_F v\|^2_F = A_F((v, \nu), (v, \nu)) \leq S\|(v, \nu)\|_F. \tag{5.9}
\]
We next notice that, for all \( q \in \mathcal{P}^{0, k-1}(F) \),
\[
\int_F \text{rot}_F q = \int_F \pi_{\mathcal{R}, F}^{-2} q \cdot \text{rot}_F q - \sum_{E \in \mathcal{E}_F} \omega_E \int_E (v \cdot t_E) q.
\]
Taking \( q \) such that \( \text{rot}_F q = \pi_{\mathcal{R}, F}^{-2} v \) (which is possible since \( \text{rot}_F : \mathcal{P}^{0, k-1}(F) \to \mathcal{R}^{k-2}(F) \) is an isomorphism) and using Cauchy–Schwarz, discrete inverse, and trace inequalities along with \( \|q\|_F \lesssim h_F \|\text{rot}_F q\|_F = h_F \|\pi_{\mathcal{R}, F}^{-2} v\|_F \), this gives, after simplifying and raising to the square,
\[
\|\pi_{\mathcal{R}, F}^{-2} v\|^2_F \lesssim h_F \sum_{E \in \mathcal{E}_F} \|v \cdot t_E\|^2_E + h_F^2 \|	ext{rot}_F v\|^2_F \lesssim S\|(v, \nu)\|_F, \tag{5.10}
\]
the conclusion being a consequence of (5.9). On the other hand, taking \( (\tau, \mu) = (0, \pi_{\mathcal{R}, F}^{c,\ell_F+1} v) \) in the definition (5.6) of \( A_F \) and recalling the definition (5.8) of \( S \), we obtain
\[
\|\pi_{\mathcal{R}, F}^{c,\ell_F+1} v\|^2_F = A_F((v, \nu), (0, \pi_{\mathcal{R}, F}^{c,\ell_F+1} v)) \leq S\|\pi_{\mathcal{R}, F}^{c,\ell_F+1} v\|_F \lesssim S\|v\|_F \leq S\|(v, \nu)\|_F, \tag{5.11}
\]
where the second inequality follows from the \( L^2 \)-boundedness of \( \pi_{\mathcal{R}, F}^{c,\ell_F+1} \). Summing (5.9)–(5.11) and recalling (5.3) along with (5.4), we obtain
\[
\|v\|^2_F \lesssim S\|(v, \nu)\|_F, \tag{5.12}
\]
To estimate the $L^2$-norm of $\nu$, we notice that $\nu \in \mathcal{P}^k(F)$ owing to (5.4), and we write
\[
\|\nu\|_F^2 = A_F((\nu, \nu), (-\nu, 0)) + h_F \sum_{E \in \mathcal{E}_F} \int_E (\nu \cdot t_E) (\nu \cdot t_E) + h_F^2 \int F \operatorname{rot}_F \nu \operatorname{rot}_F \nu
\]
\[
\lesssim s \|\nu\|_F + h_F^\frac{1}{2} \left( \sum_{E \in \mathcal{E}_F} \|\nu \cdot t_E\|_E^2 \right)^{\frac{1}{2}},
\]
where we have used Cauchy–Schwarz, discrete trace, and inverse inequalities to pass to the second line. Combining this estimate with (5.9), simplifying, and raising to the square, we conclude that
\[
\|\nu\|_F^2 \lesssim s^2 + \|((\nu, \nu))\|_F.
\] (5.13)

Summing (5.12) and (5.13), using Young’s inequality and taking the square root gives (5.8).

5.3.2. Serendipity spaces and operators

The serendipity gradient and curl spaces on a face $F \in \mathcal{F}_h$ are respectively defined as
\[
\hat{X}_{\text{grad}, F}^k := \left\{ \hat{q}_F = (\hat{q}_F, \hat{q}_E) : \hat{q}_F \in \mathcal{P}^k(F) \text{ and } \hat{q}_E \in \mathcal{P}_c^{k+1}(\mathcal{E}_F) \right\},
\]
\[
\hat{X}_{\text{curl}, F}^k := \left\{ \hat{v}_F = (\hat{v}_\mathcal{R}, F, \hat{v}_E^{\mathcal{E}}, (\hat{v}_E)_{E \in \mathcal{E}_F}) : \hat{v}_\mathcal{R}, F \in \mathcal{R}^{k-1}(F), \hat{v}_E^{\mathcal{E}} \in \mathcal{R}^{c, \ell_F+1}(F), \text{ and } \hat{v}_E \in \mathcal{P}^k(E) \text{ for all } E \in \mathcal{E}_F \right\}.
\]

We note that, since these serendipity spaces are subspaces of $\hat{X}_{\text{grad}, F}^k$ and $\hat{X}_{\text{curl}, F}^k$, the components $L^2$-norms defined by (4.1) can be applied to their elements.

The gradient serendipity operator on faces $\hat{S}_{\text{grad}, F}^k : \hat{X}_{\text{grad}, F}^k \rightarrow \mathcal{P}^k(F)$, the role of which is to reconstruct a consistent gradient (see Prop. 18 below), is defined, for all $\hat{q}_F \in \hat{X}_{\text{grad}, F}^k$, as the component $\sigma$ of the unique solution to problem (5.5) with right-hand side linear form $\mathcal{L}_F = \mathcal{L}_F^\text{grad, F}$ given by
\[
\mathcal{L}_F^\text{grad, F}(\hat{q}_F; \tau, \mu) = h_F \sum_{E \in \mathcal{E}_F} \int_E \hat{q}_E (\tau \cdot t_E) - \int_E \hat{q}_F \text{div}_F \mu + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{q}_E (\mu \cdot n_{FE}).
\] (5.14)

Combining the estimate (5.7) with Cauchy–Schwarz and discrete trace and inverse inequalities, we infer
\[
\left\| \hat{S}_{\text{grad, F}}^k \hat{q}_F \right\|_F \lesssim h_F^\frac{1}{2} \left\| \hat{q}_F \right\|_{\text{grad, F}} \quad \forall \hat{q}_F \in \hat{X}_{\text{grad, F}}^k.
\] (5.15)

The curl serendipity operator on faces $\hat{S}_{\text{curl, F}}^k : \hat{X}_{\text{curl, F}}^k \rightarrow \mathcal{P}^k(F)$, which reconstructs a consistent vector potential (as shown by Prop. 18 below), is defined for all $\hat{v}_F \in \hat{X}_{\text{curl, F}}^k$ as the component $\sigma$ of the unique solution to problem (5.5) with right-hand side linear form $\mathcal{L}_F = \mathcal{L}_F^\text{curl, F}$ given by
\[
\mathcal{L}_F^\text{curl, F}(\hat{v}_F; \tau, \mu) = h_F \sum_{E \in \mathcal{E}_F} \int_E \hat{v}_E (\tau \cdot t_E)
\]
\[
+ h_F^\frac{1}{2} \left( \int_F \hat{v}_\mathcal{R}, F \cdot \operatorname{rot}_F \tau - \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{v}_E \operatorname{rot}_F \tau \right) + \int_F \hat{v}_\mathcal{E}^{\mathcal{R}, F} \cdot \mu.
\] (5.16)

The estimate (5.7) along with Cauchy–Schwarz and discrete trace and inverse inequalities yields
\[
\left\| \hat{S}_{\text{curl, F}}^k \hat{v}_F \right\|_F \lesssim \left\| \hat{v}_F \right\|_{\text{curl, F}} \quad \forall \hat{v}_F \in \hat{X}_{\text{curl, F}}^k.
\] (5.17)
5.3.3. Extensions and reductions

The extensions on faces $E_{\text{grad},F} : \mathbb{X}_{\text{grad},F}^k \rightarrow \mathbb{X}_{\text{grad},F}^k$ and $E_{\text{curl},F} : \mathbb{X}_{\text{curl},F}^k \rightarrow \mathbb{X}_{\text{curl},F}^k$ are such that

$$\begin{align*}
E_{\text{grad},F} \hat{q}_F &= \left( E_{\text{grad},F}^{-1} \hat{q}_F, \hat{q}_F \right) \quad \forall \hat{q}_F \in \mathbb{X}_{\text{grad},F}^k, \\
E_{\text{curl},F} \hat{w}_F &= \left( \hat{v}_{\mathcal{R},F}, \pi_{\mathcal{R},F}^{c,k} S_{\text{curl},F}^{k} \hat{w}_F, (\hat{v}_E)_{E \in \mathcal{E}_F} \right) \quad \forall \hat{w}_F \in \mathbb{X}_{\text{curl},F}^k,
\end{align*}$$

(5.18)

with $E_{\text{grad},F}^{-1} \mathbb{X}_{\text{grad},F}^k \rightarrow \mathcal{P}^{k-1}(F)$ defined through a formal integration-by-parts using the serendipity gradient:

$$\int_F E_{\text{grad},F}^{-1} \hat{q}_F \text{ div}_F w_F = - \int_F \hat{q}_F \cdot w_F + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{q}_E (w_F \cdot n_{FE}).$$

(5.20)

Using discrete trace inequalities, equations (5.15), (5.17), and the isomorphism property of $\text{div}_F : \mathcal{R}^{c,k}(F) \rightarrow \mathcal{P}^{k-1}(F)$ stated in Lemma 9 of [14], we get the following continuity properties:

$$\begin{align*}
\left\| E_{\text{grad},F} \hat{q}_F \right\|_{\text{grad},F} &\lesssim \left\| \hat{q}_F \right\|_{\text{grad},F} \quad \forall \hat{q}_F \in \mathbb{X}_{\text{grad},F}^k, \\
\left\| E_{\text{curl},F} \hat{w}_F \right\|_{\text{curl},F} &\lesssim \left\| \hat{w}_F \right\|_{\text{curl},F} \quad \forall \hat{w}_F \in \mathbb{X}_{\text{curl},F}^k.
\end{align*}$$

(5.21)

(5.22)

The reductions on faces, which also define the interpolators $\hat{I}_{\text{grad},F}^k$ on $\mathbb{X}_{\text{grad},F}^k$ and $\hat{I}_{\text{curl},F}^k$ on $\mathbb{X}_{\text{curl},F}^k$ through (2.4), are $\hat{I}_{\text{grad},F} : \mathbb{X}_{\text{grad},F}^k \rightarrow \mathbb{X}_{\text{grad},F}^k$ and $\hat{I}_{\text{curl},F} : \mathbb{X}_{\text{curl},F}^k \rightarrow \mathbb{X}_{\text{curl},F}^k$ such that

$$\begin{align*}
\hat{I}_{\text{grad},F} \hat{q}_F &= \left( \hat{q}_F^\text{grad,F}, \hat{q}_F^\text{grad,F} \right) \quad \forall \hat{q}_F \in \mathbb{X}_{\text{grad},F}^k, \\
\hat{I}_{\text{curl},F} \hat{w}_F &= \left( \hat{v}_{\mathcal{R},F}, \pi_{\mathcal{R},F}^{c,k} \hat{w}_F^\text{curl,F} \right) \quad \forall \hat{w}_F \in \mathbb{X}_{\text{curl},F}^k.
\end{align*}$$

(5.23)

(5.24)

5.4. Serendipity, extension, and reduction operators on elements

5.4.1. Serendipity problem

For a fixed element $T \in \mathcal{T}_h$, recalling that $\eta_T$ is given by Assumption 12, we let

$$\ell_T := k + 1 - \eta_T \leq k - 1$$

(5.25)

and, given a linear form $\mathcal{L}_T : \mathcal{P}^k(T) \times \mathcal{R}^{c,\ell_T+1}(T) \rightarrow \mathbb{R}$, consider the following problem: Find $(\sigma, \lambda) \in \mathcal{P}^k(T) \times \mathcal{R}^{c,\ell_T+1}(T)$ such that

$$\mathcal{A}_T((\sigma, \lambda), (\tau, \mu)) = \mathcal{L}_T(\tau, \mu) \quad \forall (\tau, \mu) \in \mathcal{P}^k(T) \times \mathcal{R}^{c,\ell_T+1}(T),$$

(5.26)

with bilinear form $\mathcal{A}_T : \left[ \mathcal{P}^k(T) \times \mathcal{R}^{c,\ell_T+1}(T) \right]^2 \rightarrow \mathbb{R}$ such that

$$\mathcal{A}_T((\sigma, \lambda), (\tau, \mu)) := h_T \sum_{F \in \mathcal{T}_h} \int_{T \setminus F} v_{\text{t,F}} \cdot \tau_{\text{t,F}} + h_T^2 \int_T \text{curl} v \cdot \text{curl} \tau + \int_T \tau \cdot \mu - \int_T v \cdot \mu.$$

We remind the reader that, for any $v : T \rightarrow \mathbb{R}^3$ smooth enough and any $F \in \mathcal{T}_h$, $v_{\text{t,F}} := n_F \times (v_{\mid F} \times n_F)$ denotes the tangential component of $v$ on $F$. Proceeding as in the proof of Proposition 16, we can prove the following result.

**Proposition 17** (Well-posedness of the serendipity problem on elements). The serendipity problem (5.26) admits a unique solution which satisfies

$$\|\sigma\|_T + \|\lambda\|_T \lesssim \|\mathcal{L}_T\|_T$$

(5.27)

where $\|\mathcal{L}_T\|_T$ is the norm of the linear form $\mathcal{L}_T$ induced by the $L^2$-norm on $\mathcal{P}^k(T) \times \mathcal{R}^{c,\ell_T+1}(T)$. 


5.4.2. Serendipity spaces and operators

The serendipity spaces on an element \( T \in \mathcal{T}_h \) are defined as

\[
\hat{X}^k_{\text{grad}, T} := \left\{ \hat{q}_T = (\hat{q}_T, (\hat{q}_F)_{F \in \mathcal{F}_T}, \hat{q}_E) : \hat{q}_T \in \mathcal{D}^{l_T}(T), \hat{q}_F \in \mathcal{P}^{l_F}(F) \text{ for all } F \in \mathcal{F}_T, \right. \\
\text{and } \hat{q}_E \in \mathcal{P}^{k+1}(E_T) \right\},
\]

\[
\hat{X}^k_{\text{curl}, T} := \left\{ \hat{v}_T = (\hat{v}_T, (\hat{v}_F, \hat{v}_E)_{F \in \mathcal{F}_T}, (\hat{v}_E)_{E \in \mathcal{E}_T}) : \right. \\
\hat{v}_T \in \mathcal{R}^{k-1}(T) \text{ and } \hat{v}_F \in \mathcal{R}^{c,k+1}(T), \\
\hat{v}_F \in \mathcal{R}^{k-1}(F) \text{ and } \hat{v}_E \in \mathcal{R}^{c,F+1}(F) \text{ for all } F \in \mathcal{F}_T, \\
\text{and } \hat{v}_E \in \mathcal{P}^{k}(E) \text{ for all } E \in \mathcal{E}_T \left. \right\}.
\]

The component norms defined by (4.1) naturally apply to these spaces.

The **gradient serendipity operator on elements** \( S^k_{\text{grad}, T} : \hat{X}^k_{\text{grad}, T} \rightarrow \mathcal{P}^k(T) \) is defined, for all \( \hat{q}_T \in \hat{X}^k_{\text{grad}, T} \), as the component \( \sigma \) of the unique solution to problem (5.26) with \( \mathcal{L}_T = \mathcal{L}_{\text{grad}, T} \), where

\[
\mathcal{L}_{\text{grad}, T}(\hat{q}_T; \tau, \mu) = h_T \sum_{F \in \mathcal{F}_T} \int_F \mathcal{G}_F^{\text{grad}, F} \hat{q}_F \cdot \tau_{i,F} \\
- \int_T \hat{q}_T \text{div } \mu + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F \gamma_{k+1}^{F} \mathcal{E}_{\text{grad}, F} \hat{q}_F \cdot (\mu \cdot n_F). 
\]  

(5.28)

Combining the *a priori* estimate (5.27) with Cauchy–Schwarz and discrete trace and inverse inequalities, observing that \( \| \mathcal{G}_F^{\text{grad}, F} \hat{q}_F \|_{F} \lesssim h_T^{-\frac{1}{2}} \| \hat{q}_F \|_{\text{grad}, F} \) by (4.5) for \( (P, q_p) = (F, \mathcal{E}_{\text{grad}, F} \hat{q}_F) \) followed by (5.21), and that \( \| \gamma_{k+1}^{F} \mathcal{E}_{\text{grad}, F} \hat{q}_F \|_{F} \lesssim \| \hat{q}_F \|_{\text{grad}, F} \) (consequence of Prop. 6 from [14] followed by (5.21)), we have

\[
\| S^k_{\text{grad}, T} \hat{q}_T \|_T \lesssim h_T^{-\frac{1}{2}} \| \hat{q}_T \|_{\text{grad}, T} \quad \forall \hat{q}_T \in \hat{X}^k_{\text{grad}, T}. 
\]  

(5.29)

The **curl serendipity operator on elements** \( S^k_{\text{curl}, T} : \hat{X}^k_{\text{curl}, T} \rightarrow \mathcal{P}^k(T) \) is defined, for all \( \hat{v}_T \in \hat{X}^k_{\text{curl}, T} \), as the component \( \sigma \) of the unique solution to problem (5.26) with \( \mathcal{L}_T = \mathcal{L}_{\text{curl}, T} \) defined by

\[
\mathcal{L}_{\text{curl}, T}(\hat{v}_T; \tau, \mu) = h_T \sum_{F \in \mathcal{F}_T} \int_F \gamma_{k,F}^{\text{curl}, F} \hat{v}_F \cdot \tau_{i,F} \\
+ h_T^2 \left( \int_T \hat{v}_T \cdot \text{curl } \tau + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F \gamma_{k,F}^{\text{curl}, F} \hat{v}_F \cdot (\text{curl } \tau \times n_F) \right) \\
+ \int_T \hat{v}_F \cdot \mu. 
\]  

(5.30)

Using the *a priori* estimate (5.27), Cauchy–Schwarz and discrete trace and inverse inequalities, as well as estimates of \( \gamma_{k,F}^{\text{curl}, F} \hat{v}_F \) following from Proposition 6 of [14] and (5.22), we have

\[
\| S^k_{\text{curl}, T} \hat{v}_T \|_T \lesssim \| \hat{v}_T \|_{\text{curl}, T} \quad \forall \hat{v}_T \in \hat{X}^k_{\text{curl}, T}. 
\]  

(5.31)
5.4.3. Extensions and reductions

The extensions on elements are $\mathbf{E}_{\text{grad,T}}: \mathcal{X}_{\text{grad,T}}^k \rightarrow \mathcal{X}_{\text{grad,T}}^k$ and $\mathbf{E}_{\text{curl,T}}: \mathcal{X}_{\text{curl,T}}^k \rightarrow \mathcal{X}_{\text{curl,T}}^k$ such that

$$
\mathbf{E}_{\text{grad,T}} q_T = \left( E_{F,T}^{k-1}(q_T) \right)_{F \in F_T}, \quad \forall q_T \in \mathcal{X}_{\text{grad,T}}^k ,
$$

$$
\mathbf{E}_{\text{curl,T}} v_T = \left( E_{F,T}^{k-1}(v_T) \right)_{F \in F_T}, \quad \forall v_T \in \mathcal{X}_{\text{curl,T}}^k ,
$$

with $E_{F,T}^{k-1}$ defined by (5.20) and $E_{F,T}^{k-1}: \mathcal{X}_{\text{grad,T}}^k \rightarrow \mathcal{P}^{k-1}(T)$ such that, for all $w_T \in \mathcal{R}_{c,k}(T)$,

$$
\int_T E_{F,T}^{k-1}(w_T) \cdot \text{div} w_T = - \int_T S_{\text{grad,T}}^{k-1}(w_T) \cdot w_T + \sum_{F \in F_T} \omega_F \gamma_F^{k+1} E_{\text{grad,F}}(w_T \cdot n_F).
$$

Proceeding in a similar way as for the face extensions, (5.29) and (5.31) yield

$$
\left\| \mathbf{E}_{\text{grad,T}} q_T \right\|_{\text{grad,T}} \lesssim \left\| q_T \right\|_{\text{grad,T}}, \quad \forall q_T \in \mathcal{X}_{\text{grad,T}}^k ,
$$

$$
\left\| \mathbf{E}_{\text{curl,T}} v_T \right\|_{\text{curl,T}} \lesssim \left\| v_T \right\|_{\text{curl,T}}, \quad \forall v_T \in \mathcal{X}_{\text{curl,T}}^k ,
$$

The reductions on elements are $\mathbf{R}_{\text{grad,T}}: \mathcal{X}_{\text{grad,T}}^k \rightarrow \mathcal{X}_{\text{grad,T}}^k$ and $\mathbf{R}_{\text{curl,T}}: \mathcal{X}_{\text{curl,T}}^k \rightarrow \mathcal{X}_{\text{curl,T}}^k$ such that

$$
\mathbf{R}_{\text{grad,T}} q_T = \left( R_{F,T}^{k-1}(q_T) \right)_{F \in F_T}, \quad \forall q_T \in \mathcal{X}_{\text{grad,T}}^k ,
$$

$$
\mathbf{R}_{\text{curl,T}} v_T = \left( R_{F,T}^{k-1}(v_T) \right)_{F \in F_T}, \quad \forall v_T \in \mathcal{X}_{\text{curl,T}}^k ,
$$

where $R_{F,T}^{k-1} q_T \in \mathcal{P}_{c,T}(T)$ is such that, for all $w_T \in \mathcal{R}_{c,k}(T)$,

$$
\int_T R_{F,T}^{k-1}(w_T) \cdot \text{div} w_T = - \int_T C_T q_T \cdot w_T + \sum_{F \in F_T} \omega_F \gamma_F^{k+1} E_{\text{grad,F}}(R_T^{k-1}(w_T \cdot n_F)).
$$

while $R_{F,T}^{k-1} v_T \in \mathcal{R}_{c,k-1}(T)$ is such that, for all $w_T \in \mathcal{G}_{c,k}(T)$,

$$
\int_T R_{F,T}^{k-1} v_T \cdot \text{curl} w_T = \int_T C_T v_T \cdot w_T - \sum_{F \in F_T} \omega_F \gamma_F^{k+1} E_{\text{curl,F}}(R_T^{k-1}(v_T \times n_F))
$$

6. Properties of the SDDR complex

6.1. Preliminary results

Proposition 18 (Polynomial consistency of the serendipity operators and extensions). The serendipity operators and extensions enjoy the following polynomial consistency properties: For all $P \in T_h \cup F_h$,

$$
\mathbf{S}_{\text{grad,P}}^k = \text{grad}_P q \quad \forall q \in \mathcal{P}^{k+1}(P),
$$

$$
\mathbf{E}_{\text{grad,P}}^k = \text{I}_{\text{grad,P}}^k q \quad \forall q \in \mathcal{P}^{k+1}(P),
$$

$$
\mathbf{S}_{\text{curl,P}}^k = v \quad \forall v \in \mathcal{P}^k(P),
$$

$$
\mathbf{E}_{\text{curl,P}}^k = \text{I}_{\text{curl,P}}^k v \quad \forall v \in \mathcal{P}^k(P).
$$
Proof. Let us first consider the case \( P = F \in \mathcal{F}_h \). Let \( q \in \mathcal{P}^{k+1}(F) \). By uniqueness of the solution to (5.5), (6.1) follows from proving that \( (\text{grad}_F q, 0) \) solves this problem with \( \mathcal{L}_F = \mathcal{L}_{\text{grad}, F} \) defined by (5.14) with \( \hat{q}_F = \hat{I}_{\text{grad}, F} q \). Recalling the definition (5.6) of \( A_F \), it holds, for all \((\tau, \mu) \in \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell,F+1}(F), \)

\[
A_F((\text{grad}_F q, 0), (\tau, \mu)) = h_F \sum_{E \in \mathcal{E}_F} \int_E (\text{grad}_F q \cdot t_E) (\tau \cdot t_E) + \int_F \text{grad}_F q \cdot \mu \]

\[
= h_F \sum_{E \in \mathcal{E}_F} \int_E q|_E (\tau \cdot t_E) - \int_F \pi_{\text{grad},F}^k q \ \text{div}_F \mu + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \pi_{\text{grad},F}^{k-1} q (\mu \cdot n_{FE})
\]

\[
= \mathcal{L}_{\text{grad}, F}(\hat{I}_{\text{grad}, F} q; \tau, \mu),
\]

where we have used \( \text{rot}_F \text{grad}_F = 0 \) in the first line, an integration by parts along with the fact that \( \text{div}_F \mu \in \mathcal{P}^\ell(F) \) and, for all \( E \in \mathcal{E}_F, \mu \cdot n_{FE} \in \mathcal{P}^\ell(E) \subset \mathcal{P}^{k-1}(E) \) (see [14], Prop. 8) to insert \( \pi_{\text{grad}, F}^k \) and \( \pi_{\text{grad}, E}^{k-1} \) in the second line, and the definition of \( \hat{I}_{\text{grad}, F} \) (based on (2.4) with full interpolator and reduction respectively given by (4.9) and (5.23)) together with (5.14) to conclude. This proves (6.1) for \( P = F \). From this result, using an integration by parts in (5.20) together with the fact that \( \text{div}_F : \mathcal{R}^{c,k}(F) \rightarrow \mathcal{P}^{k-1}(F) \) is an isomorphism, we infer that \( E^{k-1}_{\text{grad}, F} = \pi_{\text{grad}, F}^{k-1} q \), which gives (6.2).

We proceed similarly to prove (6.3) for \( P = F \). Specifically, let \( v \in \mathcal{P}^k(F) \). For all \((\tau, \mu) \in \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell,F+1}(F), \) it holds

\[
A_F((v, 0), (\tau, \mu)) = h_F \sum_{E \in \mathcal{E}_F} \int_E (v \cdot t_E) (\tau \cdot t_E) + \int_F \text{rot}_F v \ \text{rot}_F \tau + \int_F v \cdot \mu
\]

\[
= h_F \sum_{E \in \mathcal{E}_F} \int_E k_{\text{rot}_F}^k (v \cdot t_E) (\tau \cdot t_E)
\]

\[
+ h_F^2 \left( \int_F k_{\text{rot}_F}^{k-2} v \cdot \text{rot}_F \tau - \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E k_{\text{rot}_F}^k (v \cdot t_E) \ \text{rot}_F \tau \right) + \int_F \ell_{\text{curl}, F}^k v \cdot \mu
\]

\[
= \mathcal{L}_{\text{curl}, F}(\hat{I}_{\text{curl}, F} v; (\tau, \mu)),
\]

where we have used an integration by parts along with the definitions of the \( L^2 \)-orthogonal projectors to pass to the second line, and (5.16) together with the definition of \( \hat{I}_{\text{curl}, F}^k \) (obtained, according to (2.4), composing (5.24) and the \( L^2 \)-projectors on the components of \( X^k_{\text{curl}, F} \)) to conclude. This proves that \((v, 0)\) solves (5.5) with \( \mathcal{L}_F = \mathcal{L}_{\text{curl}, F} \) given by (5.16) with \( \hat{v}_F = \hat{I}_{\text{curl}, F}^k v \). This establishes (6.3), from which (6.4) immediately follows by definition (5.19) of \( \mathcal{E}_{\text{curl}, F} \).

We now briefly discuss the case \( P = T \in \mathcal{T}_h \). Let \( q \in \mathcal{P}^{k+1}(T) \). Using \( \hat{R}_{\text{grad}, Q}^k = \hat{R}_{\text{grad}, Q}^k \) for \( Q \in T_h \cup \mathcal{F}_h \) (by definition (2.4)), (6.2) for \( P = F \), and the polynomial consistencies of \( \mathcal{G}_T^k \) and \( \gamma_T^{k+1} \) (see [14], Lem. 3), the definition (5.37) shows that the element component of \( \hat{I}_{\text{grad}, T}^k q \) is \( \hat{R}_{\text{grad}, T}^k \hat{I}_{\text{grad}, T}^k q = \pi_{T, T}^k q \). We can then proceed as above, using the polynomial consistency of \( \mathcal{G}_T^k \) and \( \gamma_T^{k+1} \) together with (6.2) for \( P = F \) to see that (6.1) and (6.2) hold for \( P = T \).

The proof of (6.3) and (6.4) for \( P = T \) is similar, noticing that the polynomial consistencies of \( \gamma_T^k \) and \( \mathcal{C}_T^k \) (see [14], Eqs. (3.25) and (3.29)) and (6.4) for \( P = F \) yield \( \hat{R}_{\text{grad}, T}^k \hat{I}_{\text{curl}, T}^k v = \pi_{T, T}^{k-1} v \). \( \square \)

**Lemma 19** (Projections of extension, serendipity and gradient operators). For all \( P \in T_h \cup \mathcal{F}_h \), it holds:

\[
\pi_{\text{grad}, P}^k E^{k-1}_{\text{grad}, P} \hat{q}_P = \hat{v}_P \quad \forall \hat{q}_P \in X^k_{\text{grad}, P},
\]

(6.5)
\[
\pi_{\mathcal{R},p}^c E_{\text{grad},p} \frac{\partial \hat{u}}{\partial p} = \pi_{\mathcal{R},p}^c S_{\text{grad},p}^k \frac{\partial \hat{u}}{\partial p} \quad \forall \frac{\partial \hat{u}}{\partial p} \in \hat{X}_{\text{grad},p}^k. \tag{6.6}
\]

\[
\pi_{\mathcal{R},F}^c S_{\text{curl},p}^F \frac{\partial \hat{u}}{\partial p} = \hat{v}_{\mathcal{R},p}^c \quad \forall \frac{\partial \hat{u}}{\partial p} \in \hat{X}_{\text{curl},p}^k. \tag{6.7}
\]

**Proof.** We focus, for the sake of brevity, on the case \( \mathbb{P} = F \in \mathcal{F}_h \), the case \( \mathbb{P} = T \in \mathcal{T}_h \) being similar. Taking a generic \( \mathbf{w}_F \in \mathcal{R}^{c,\ell+1}(F) \) and plugging \( (\tau, \mu) = (0, \mathbf{w}_F) \) into the variational problem defining \( S_{\text{grad},F}^k \hat{q}_F \) (i.e., \( \mathcal{L} = \mathcal{L}_{\text{grad},F} \) given by \( (5.14) \)), we infer that

\[
\int_F S_{\text{grad},F}^k \hat{q}_F \cdot \mathbf{w}_F = - \int_F \frac{\hat{q}_F}{\partial F} \text{div}_F \mathbf{w}_F + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{q}_E \left( \mathbf{w}_F \cdot \mathbf{n}_{FE} \right). \tag{6.8}
\]

Writing the definition \( (5.20) \) of \( E_{\mathbb{P},F}^{k-1} \) with this choice of \( \mathbf{w}_F \) (which is possible since \( \mathcal{R}^{c,\ell+1}(F) \subset \mathcal{R}^{c,k}(F) \) by \( (5.5) \)) and subtracting \( (6.8) \) from the resulting expression yields

\[
\int_F E_{\mathbb{P},F}^{k-1} \frac{\partial \hat{q}_F}{\partial F} \text{div}_F \mathbf{w}_F = \int_F \frac{\hat{q}_F}{\partial F} \text{div}_F \mathbf{w}_F,
\]

which proves \( (6.5) \) since \( \text{div}_F : \mathcal{R}^{c,\ell+1}(F) \rightarrow \mathcal{P}^{\ell+1}_F \) is an isomorphism. To establish \( (6.6) \), we take \( \mathbf{w}_F \in \mathcal{R}^{c,k}(F) \) and write the definition \( (4.2) \) of \( G_{\mathbb{P}}^k E_{\text{grad},F} \frac{\partial \hat{q}_F}{\partial F} \) to get

\[
\int_F G_{\mathbb{P}}^k E_{\text{grad},F} \frac{\partial \hat{q}_F}{\partial F} \cdot \mathbf{w}_F = - \int_F E_{\mathbb{P},F}^{k-1} \frac{\partial \hat{q}_F}{\partial F} \text{div}_F \mathbf{w}_F + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{q}_E \left( \mathbf{w}_F \cdot \mathbf{n}_{FE} \right) = \int_F S_{\text{grad},F}^k \frac{\partial \hat{q}_F}{\partial F} \cdot \mathbf{w}_F,
\]

where the second equality follows from the definition \( (5.20) \) of \( E_{\mathbb{P},F}^{k-1} \). Finally, to prove \( (6.7) \), it suffices to take test functions of the form \((0, \mu)\), with \( \mu \) spanning \( \mathcal{R}^{c,\ell+1}(F) \), in the problem defining \( S_{\text{curl},F}^k \hat{q}_F \) (i.e., \( (5.5) \) with right-hand side \( \mathcal{L}_F = \mathcal{L}_{\text{curl},F} \) given by \( (5.16) \)). \( \square \)

**Lemma 20** (Equivalence of norms on \( \hat{X}_{\mathbb{P},T}^k \) and \( \hat{X}_{\text{curl},T}^k \)). For \( \bullet \in \{\mathbf{grad}, \mathbf{curl}\} \), it holds \( \|\cdot\|_{s,T} \simeq \|\cdot\|_{s,T} \) on \( \hat{X}_{s,T}^k \) where, in accordance with \( (2.3) \), \( \|\cdot\|_{s,T} := \|E_{\mathbb{P},T} \|_{s,T} \) with \( \|\cdot\|_{s,T} \) defined in Section 4.4.

**Proof.** We only consider the case \( \bullet = \mathbf{grad} \), the proof for \( \bullet = \mathbf{curl} \) being similar. For all \( \hat{q}_T \in \hat{X}_{\mathbf{grad},T}^k \), we have

\[
\left\| \hat{q}_T \right\|_{\mathbf{grad},T} \leq \left\| \pi_{\mathbf{grad},T} E_{\mathbf{grad},T} \hat{q}_T \right\|_{\mathbf{grad},T} \leq \left\| \pi_{\mathbf{grad},T} E_{\mathbb{P},T} \hat{q}_T \right\|_{\mathbf{grad},T} \leq \left\| \hat{q}_T \right\|_{\mathbf{grad},T},
\]

where the first inequality comes from the equivalence of norms on \( \hat{X}_{\mathbf{grad},T}^k \), see Lemma 5 of [14], and the second inequality is \( (5.34) \). To prove the converse inequality, we use \( (6.5) \) to write

\[
\left\| \hat{q}_T \right\|_{\mathbf{grad},T}^2 = \left\| \pi_{\mathbb{P},T} E_{\mathbb{P},T} \hat{q}_T \right\|_{\mathbb{P},T}^2 + \sum_{F \in \mathcal{F}_T} h_F \left\| \pi_{\mathbb{P},F} E_{\mathbb{P},F} \hat{q}_F \right\|_{\mathbb{P},F}^2 + \sum_{F \in \mathcal{F}_T} h_F \sum_{E \in \mathcal{E}_F} h_E \left\| q_E \right\|_{E}^2 \\
\leq \left\| E_{\mathbf{grad},T} \hat{q}_T \right\|_{\mathbf{grad},T}^2,
\]

where the last bound follows from the \( L^2 \)-boundedness of the \( L^2 \)-projectors and the definition \( (5.32) \) of \( E_{\mathbf{grad},T} \hat{q}_T \). We then invoke the equivalence of norms in \( \hat{X}_{\mathbf{grad},T}^k \) (see [14], Lem. 5) to get \( \left\| E_{\mathbf{grad},T} \hat{q}_T \right\|_{\mathbf{grad},T}^2 \leq \left\| E_{\mathbf{grad},T} \hat{q}_T \right\|_{\mathbf{grad},T}^2 \leq \left\| \hat{q}_T \right\|_{\mathbf{grad},s,T}^2 \). \( \square \)
6.2. Commutation property for the serendipity operators

The property in the following lemma justifies the choice of serendipity operators made in Sections 5.3.2 and 5.4.2 and will play a crucial role in the proof of Lemma 24 below (cochain property for the extension map).

**Lemma 21** (Commutation property for the serendipity operators). For all $P \in T_h \cup \mathcal{F}_h$, it holds, recalling that $\hat{G}^k_p := \hat{R}_{\text{curl},p} G^k_p E_{\text{grad},p}$ by (2.2),

$$S^k_{\text{curl},p} \hat{G}^k_p \hat{q}_p = S^k_{\text{grad},p} \hat{q}_p \quad \forall \hat{q}_p \in X^k_{\text{grad},p},$$  \hspace{1cm} (6.9)

which expresses the fact that the following diagram commutes:

\[ \begin{array}{ccc} X^k_{\text{grad},p} & \xrightarrow{S^k_{\text{grad},p}} & \mathcal{P}^k(P) \\ \downarrow & & \uparrow S^k_{\text{curl},p} \\ \hat{G}^k_p & \xrightarrow{\hat{S}^k_{\text{grad},p}} & \hat{X}^k_{\text{curl},p} \end{array} \]

**Proof.** Let us consider $P = F$, and set, for the sake of brevity, $\hat{v}_F := \hat{G}^k_p \hat{q}_F$. Then, $\hat{v}_E = \hat{q}_E$ and

$$\hat{v}_{\mathcal{R},F} = \pi_{\mathcal{R},F}^{\ell_F+1} G^k_F E_{\text{grad},F} \hat{q}_F = \pi_{\mathcal{R},F}^{\ell_F+1} S^k_{\text{grad},F} \hat{q}_F$$ \hspace{1cm} (6.10)

by (6.6) for $P = F$ recalling (3.5) along with $\ell_F + 1 \leq k$ (cf. (5.4)). Moreover, for all $z_F \in \mathcal{P}^k(F)$,

$$\int_F \hat{v}_{\mathcal{R},F} \cdot \text{rot}_F z_F - \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{v}_E z_F = \int_F \pi_{\mathcal{R},F}^{k-1} G^k_F E_{\text{grad},F} \hat{q}_F \cdot \text{rot}_F z_F - \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{q}_E z_F$$ \hspace{1cm} (6.11)

where, to pass to the second line, we have invoked the definition (4.6) of $C^k_F$ together with the fact that the edge components of $G^k_F E_{\text{grad},F} \hat{q}_F$ are $(\hat{q}_E')_{E \in \mathcal{E}_F}$, and we have concluded thanks to the local complex property stated in Proposition 2 of [14]. We next notice that, recalling (6.10) and (6.8), for all $\mu \in \mathcal{R}^{c,\ell_F+1}(F)$,

$$\int_F \hat{v}_{\mathcal{R},F} \cdot \mu = \int_F S^k_{\text{grad},F} \hat{q}_F \cdot \mu = - \int_F \hat{q}_F \text{div}_F \mu + \sum_{E \in \mathcal{E}_F} \omega_{FE} \int_E \hat{q}_E (\mu \cdot n_{FE}).$$ \hspace{1cm} (6.12)

Recalling that $v_E = \hat{q}_E'$ for all $E \in \mathcal{E}_h$, plugging (6.11) and (6.12) into the expression (5.16) of the linear form $\mathcal{L}_{\text{curl},E}(\hat{P}_F; \cdot, \cdot)$, and recalling the expression (5.14) of the linear form $\mathcal{L}_{\text{grad},F}$, we conclude that $\mathcal{L}_{\text{curl},F}(\hat{P}_F; \tau, \mu) = \mathcal{L}_{\text{grad},F}(\hat{q}_F; \tau, \mu)$ for all $(\tau, \mu) \in \mathcal{P}^k(F) \times \mathcal{R}^{c,\ell_F+1}(F)$. Letting $\lambda_{\mathcal{R},F}', \lambda_{\mathcal{G},F}' \in \mathcal{R}^{c,\ell_F+1}(F)$ be the second components in the serendipity problems (5.5) defining $S^k_{\text{curl},F} \hat{P}_F$ and $S^k_{\text{grad},F} \hat{q}_F$, respectively, this implies

$$A_F \left( \begin{pmatrix} S^k_{\text{curl},F} \hat{P}_F - S^k_{\text{grad},F} \hat{q}_F, \lambda_{\mathcal{R},F}' - \lambda_{\mathcal{G},F}' \end{pmatrix}, (\tau, \mu) \right) = 0 \quad \forall (\tau, \mu) \in \mathcal{P}^k \times \mathcal{R}^{c,\ell_F+1}(F),$$

showing that $S^k_{\text{curl},F} \hat{P}_F = S^k_{\text{grad},F} \hat{q}_F$. The proof in the case $P = T \in T_h$ is similar. The details are left to the reader. \hfill $\square$
6.3. Homological and analytical properties for the gradient

**Lemma 22** (Properties of the serendipity gradient space). The serendipity construction for the gradient space satisfies both the homological properties of Assumption 1 and the analytical properties of Assumption 3, with continuity constants in (A1) and (A3) that do not depend on h.

**Proof.** (i) *Proof of (C1).* Let $T \in \mathcal{T}_h$ and $\tilde{q}_T^k \in \hat{X}_{\text{grad},T}^k$ and let, for the sake of brevity, $q_T := E_{\text{grad},T} \tilde{q}_T^k$. Owing to (6.5), for all $F \in \mathcal{F}_T$ we have $\hat{R}_{\text{grad},T} q_T^F = \tilde{q}_F^k$. Plugging this relation into the definition (5.37) of $\hat{R}_{P,T}^k q_T^k$ we find, for all $\mathbf{w}_T \in \mathcal{R}^{c,T-1}_{c,T}(T)$,

$$
\int_T \hat{R}_{P,T}^k q_T^k \cdot \mathbf{w}_T = -\int_T \mathbf{G}_T^k q_T^k \cdot \mathbf{w}_T + \sum_{F \in \mathcal{F}_T} \omega_T \int_F \gamma_F^{k+1} q_T^F (\mathbf{w}_T \cdot \mathbf{n}_F) = \int_T E_{P,T}^{-1} \tilde{q}_T^k \text{ div } \mathbf{w}_T,
$$

where the conclusion comes from the definitions (4.4) of $\mathbf{G}_T^k$ and (5.32) of $E_{\text{grad},T}$. Recalling that div : $\mathcal{R}^{c,T-1}_{c,T}(T) \to \mathcal{P}^{c,T}(T)$ is an isomorphism and applying (6.5) for $P = T$ yields $\hat{R}_{P,T}^k q_T^k = \tilde{q}_T^k$. This proves that $\hat{R}_{\text{grad},h} E_{\text{grad},h} = \text{Id}$ on the whole of $\hat{X}_{\text{grad},T}^k$.

(ii) *Proof of (A2).* The polynomial consistency is only meaningful for the local complex on a mesh element $T \in \mathcal{T}_h$, for which it is simply (6.2) with $P = T$.

(iii) *Proof of (C2).* Take $q_h \in \text{ker} \mathbf{G}_h^k$. We claim that $E_{\text{grad},T} \hat{R}_{\text{grad},T} q_T^h = q_h^k$ for all $T \in \mathcal{T}_h$, which establishes a stronger version of (C2) (namely, $E_{\text{grad},h} \hat{R}_{\text{grad},h} = \text{Id}$ on ker $\mathbf{G}_h^k$). The condition $\mathbf{G}_h^k q_h^k = 0$ implies $\mathbf{G}_h^k q_T^h = 0$ for all $T \in \mathcal{T}_h$ and thus, by exactness of the DDR sequence on $T$, $q_T^h = I_{\text{grad},T}^k M$ for some $M \in \mathbb{R}$. The property (A2) then yields $E_{\text{grad},T} \hat{R}_{\text{grad},T} q_T^h = q_T^h$, as claimed.

(iv) *Proof of (C3).* For this slice of the complex between $\mathbb{R}$ and $\hat{X}_{\text{grad},h}^k$, we have $E_i = \hat{R}_i = \text{Id}_h$ and the operators in the sequences are $I_{\text{grad},h}^k$ and $\hat{I}_{\text{grad},h}^k$. The fact that the reductions are cochain maps then follows from the definition (2.4) of $\hat{I}_{\text{grad},h}^k$, while the cochain map property of the extension is simply (A2), proved above, applied to constant polynomials.

(v) *Proof of (A1).* For all $T \in \mathcal{T}_h$, the continuity of $\hat{R}_{\text{grad},T} : \hat{X}_{\text{grad},T}^k \to \hat{X}_{\text{grad},T}^k$ is a direct consequence of the norm equivalences in $X_{\text{grad},T}^k$ and $\hat{X}_{\text{grad},T}^k$ (see Lem. 5 of [14] and Lem. 20), the boundedness of the $L^2$-projector $\pi_{P,T}$, and, to estimate $\hat{R}_{P,T}^k q_T^k$, Lemma 9 in [14] and the continuities of $\mathbf{G}_T^k$ and $\gamma_F^{k+1}$ (see (4.5) above and Eq. (4.22) in [14]).

(vi) *Proof of (A3).* This property on the original DDR complex is proved in Lemma 6 of [14].

\[ \square \]

6.4. Homological and analytical properties for the curl

The goal of this section is to prove homological and analytical properties for the curl. We remind the reader that, according to (2.2),

$$
\hat{\mathbf{G}}_h^k := \hat{R}_{\text{curl},h} \mathbf{G}_h^k E_{\text{grad},h} \quad \text{and} \quad \hat{C}_h^k := \hat{R}_{\text{div},h} \mathbf{C}_h^k E_{\text{curl},h}.
$$

We start by addressing the cochain property for the reduction and extension maps.

**Lemma 23** (Cochain property of the reduction). For the slice of the complex between $X_{\text{grad},h}^k$ and $X_{\text{curl},h}^k$, property (C3) holds for the reduction, i.e.,

$$
\hat{\mathbf{G}}_h^k \hat{R}_{\text{grad},h} q_h^k = \hat{R}_{\text{curl},h} \mathbf{G}_h^k q_h^k \quad \forall q_h^k \in X_{\text{grad},h}^k.
$$

**Proof.** Let $q_h^k \in X_{\text{grad},h}^k$ and set, for the sake of brevity, $\tilde{q}_h^k := \hat{R}_{\text{grad},h} q_h^k$. 

\[ \square \]
(i) Gradient components on $\mathcal{R}^{c,f+1}(P)$. We start by proving the following result: For all $P \in \mathcal{T}_{h} \cup \mathcal{F}_{h}$,

\[
\pi_{\mathcal{R}_{k}^{c,f+1}}^{c,f+1} G_{P} E_{\text{grad},P} \hat{r}_{T}^{k} = \pi_{\mathcal{R}_{k}^{c}}^{c,f+1} G_{P} \hat{q}_{T}^{k} \quad \forall \hat{q}_{T}^{k} \in \mathcal{X}_{\text{grad},P}^{k}.
\]

We detail the proof for the case $P = T \in \mathcal{T}_{h}$, the case $P = F \in \mathcal{F}_{h}$ being similar. Owing to (6.6) and (3.5) with $\ell = \ell_{T}$, we only have to prove that $\pi_{\mathcal{R}_{k}^{c,f+1}}^{c,f+1} S_{\mathcal{R}_{k}^{c,f+1}}^{k} = \pi_{\mathcal{R}_{k}^{c,f+1}}^{c,f+1} G_{P} \hat{q}_{T}^{k}$. This relation can be established taking $(\tau, \mu) = (0, w_{T})$ with $w_{T} \in \mathcal{R}^{c,f+1}(T)$ as a test function in the problem defining $S_{\mathcal{R}_{k}^{c,f+1}}^{k}$ (i.e., (5.26) with $L_{T} = L_{\text{grad},T}$ given by (5.28)) to write

\[
\int_{T} S_{\text{grad},T}^{k} \cdot w_{T} = -\int_{T} \hat{r}_{T}^{k} \cdot w_{T} + \sum_{F \in \mathcal{T}_{h}} \int_{F} \omega_{T} \int_{F} \gamma_{F}^{k+1} E_{\text{grad},F} \hat{q}_{F}^{k} (w_{T} \cdot n_{F}) (5.37) = \int_{T} G_{P} \hat{q}_{T}^{k} \cdot w_{T}.
\]

(ii) Cochain property of the reduction. The components of $E_{\text{grad},h} \hat{q}_{h}$ and $q_{h}$ on the mesh edge skeleton coincide, and thus do their edge gradient as well as the components of their discrete gradients on $\mathcal{R}^{k-1}(F), F \in \mathcal{F}_{h}$ (depending only on the skeletal components). By definition of $\hat{R}_{\text{curl},h}$, this shows that the equality in (6.13) holds for these components. The equality of the components on $\mathcal{R}^{c,f+1}(F), F \in \mathcal{F}_{h}$, is an immediate consequence of (6.14) for $P = F$.

Let now $T \in \mathcal{T}_{h}$. We have just proved that, for all $F \in \mathcal{F}_{h}, \hat{G}_{F}^{k} \hat{q}_{F}^{k} = \hat{R}_{\text{curl},h} \hat{q}_{F}^{k}$. By Remark 15 of [14], we have $C_{h}^{k} G_{F}^{k} = 0$. Hence, the definition (5.38) of $\hat{R}_{\text{curl},h}$ applied to $\nu_{T} = C_{h}^{k} E_{\text{grad},h} \hat{q}_{h}$ and $\nu_{F} = G_{F}^{k} \hat{q}_{F}^{k}$ shows that the components of each side of (6.13) on $\mathcal{R}^{k-1}(T)$ coincide. The equality of the components on $\mathcal{R}^{c,f+1}(T), T \in \mathcal{T}_{h}$, is an immediate consequence of (6.14).

\[\square\]

**Lemma 24** (Cochain property of the extension). For the slice of the complex between $X_{\text{grad},T}^{k}$ and $X_{\text{curl},T}^{k}$, property (C3) holds for the extensions, i.e.,

\[
E_{\text{curl},h} \hat{G}_{h}^{k} \hat{q}_{h} = C_{h}^{k} E_{\text{grad},h} \hat{q}_{h} \quad \forall \hat{q}_{h} \in \mathcal{X}_{\text{grad},h}^{k}.
\]

**Proof.** Given that $E_{\text{curl},h}$ and $\hat{R}_{\text{curl},h}$ leave the components on $P^{k}(E), E \in \mathcal{E}_{h}$, and $\mathcal{R}^{k-1}(F), F \in \mathcal{F}_{h}$, unchanged, the equality of these components on each side of (6.15) is trivial. For $F \in \mathcal{F}_{h}$ we have, owing to (6.9) and (6.6) for $P = F$,

\[
\pi_{\mathcal{R}_{k}^{c,f+1}}^{c,f+1} \hat{r}_{T}^{k} = \pi_{\mathcal{R}_{k}^{c,f+1}}^{c,f+1} \hat{r}_{F}^{k} = \pi_{\mathcal{R}_{k}^{c,f+1}}^{c,f+1} \hat{q}_{F}^{k} = \pi_{\mathcal{R}_{k}^{c,f+1}}^{c,f+1} G_{F} E_{\text{grad},F} \hat{q}_{F}^{k},
\]

which proves that the components on $\mathcal{R}^{c,k}(F)$ of each side of (6.15) also coincide, so that

\[
E_{\text{curl},F} \hat{G}_{F}^{k} \hat{q}_{F}^{k} = E_{\text{curl},F} \hat{R}_{\text{curl},F} \hat{q}_{F}^{k} = G_{F} E_{\text{grad},F} \hat{q}_{F}^{k} \quad \forall F \in \mathcal{F}_{h}.
\]

With the same approach, using (6.9) and (6.6) for $P = T \in \mathcal{T}_{h}$, we show that the components on $\mathcal{R}^{c,k}(T)$ also coincide. It remains to analyse, for $T \in \mathcal{T}_{h}$, the components on $\mathcal{R}^{k-1}(T)$. Setting $\nu_{T}^{k} := C_{h}^{k} E_{\text{grad},T} \hat{q}_{T}^{k}$, this component for the left-hand side of (6.15) is $\nu_{T}^{k-1}$ given by (5.38). Plugging into this expression $C_{h}^{k} \nu_{T} = 0$ (consequence of [14], Rem. 15), using (6.16) to write $E_{\text{curl},F} \hat{R}_{\text{curl},F} \nu_{T} = G_{F} E_{\text{grad},F} \hat{q}_{F}^{k}$, and recalling the link between element and face gradients expressed by equation (3.17) of [14], we infer that

\[
\int_{T} \gamma_{T}^{k-1} T_{\text{curl}} \cdot \nu_{T}^{k} = \int_{T} G_{F} E_{\text{grad},F} \hat{q}_{F}^{k} \cdot \nu_{T}^{k},
\]

which proves the equality of the components on $\mathcal{R}^{k-1}(T)$ of each side of (6.15).

\[\square\]
The following intermediate result will be used to establish (C2), as well as (C3) for the last part of the complex involving $X_{\text{div},h}^k$.

**Lemma 25** (Relation among $C^k_h$, $E_{\text{curl},h}$, and $R_{\text{curl},h}$). It holds

$$C^k_h E_{\text{curl},h} R_{\text{curl},h} v_h = C^k_h v_h \quad \forall v_h \in X_{\text{curl},h}^k. \quad (6.17)$$

**Proof.** Let $v_h \in X_{\text{curl},h}^k$ and set, for the sake of brevity, $\hat{v}_h := R_{\text{curl},h} v_h$. The components of $v_h$ and $E_{\text{curl},h} \hat{v}_h$ on $\mathcal{P}^k(E)$, $E \in \mathcal{E}_h$, and on $\mathcal{R}^{k-1}(F)$, $F \in \mathcal{F}_h$, coincide. Since the face curls only depend on these components, we infer that $C^k_F E_{\text{curl},F} \hat{v}_F = C^k_F v_F$ for all $F \in \mathcal{F}_h$. The link between full curl and face curls given in Proposition 4 of [14] then shows that $\pi_{\mathcal{G},F}^{-1} C^k_F E_{\text{curl},T} \hat{v}_T = \pi_{\mathcal{G},F}^{-1} C^k_F v_T$ for all $T \in \mathcal{T}_h$. We have therefore proved that the components on the faces and on $\mathcal{G}^{k-1}(T)$, $T \in \mathcal{T}_h$, of both sides of (6.17) coincide. Let now $T \in \mathcal{T}_h$ and consider the components of the discrete curls on $\mathcal{G}^{c,k}(T)$. By definition (5.33) of $E_{\text{curl},T}$, the component of $E_{\text{curl},T} \hat{v}_T$ on $\mathcal{R}^{k-1}(T)$ is that of $\hat{v}_T$, which is $R_{\mathcal{R},T} \hat{v}_T$ given by (5.38). The definitions (4.7) of $C^k_T E_{\text{curl},T} \hat{v}_T$ and (5.38) of $R_{\mathcal{R},T} \hat{v}_T$ then give, for all $w_T \in \mathcal{G}^{c,k}(T)$,

$$\int_T C^k_T E_{\text{curl},T} \hat{v}_T \cdot w_T = \int_T R_{\mathcal{R},T} \hat{v}_T \cdot \text{curl } w_T + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F \gamma^k_{T,F} E_{\text{curl},F} \hat{v}_F \cdot (w_T \times n_F)$$

$$= \int_T C^k_T v_T \cdot w_T.$$

This implies that $\pi_{\mathcal{G},T}^{c,k} C^k_T E_{\text{curl},T} \hat{v}_T = \pi_{\mathcal{G},T}^{c,k} C^k_T v_T$ and concludes the proof. \hfill \qedsymbol

**Lemma 26** (Properties of the serendipity curl space). The serendipity construction for the curl space satisfies both the homological properties of Assumption 1 and the analytical properties of Assumption 3, with continuity constants in (A1) and (A3) that do not depend on $h$.

**Proof.** (i) **Proof of (C1).** Let $F \in \mathcal{F}_h$ and $\hat{v}_F \in \hat{X}_{\text{curl},F}^k$. By (6.7) with $P = F$, we have $\pi_{\mathcal{R},F}^{c,F} S^k_{\text{curl},F} \hat{v}_F = \hat{v}_F^\text{curl}$. Combined with the definition (5.24) of $R_{\text{curl},F}$ with $\hat{v}_F = E_{\text{curl},F} \hat{v}_F$ and (3.5), this gives

$$\forall F \in \mathcal{F}_h, \quad R_{\text{curl},F} E_{\text{curl},F} \hat{v}_F = \hat{v}_F \quad \forall \hat{v}_F \in \hat{X}_{\text{curl},F}^k, \quad (6.18)$$

the equality of the components on $\mathcal{P}^k(E)$, $E \in \mathcal{E}_F$, and $\mathcal{R}^{k-1}(F)$ being trivial as these are not affected by the reduction/extension operators.

Take now $\hat{v}_h \in \hat{X}_{\text{curl},h}^k$ and set, for the sake of brevity, $v_h := E_{\text{curl},h} \hat{v}_h$. For all $T \in \mathcal{T}_h$, invoking (6.18) and using again (6.7) and (3.5) gives

$$\hat{R}_{\text{curl},T} \hat{v}_T = \left( R_{\mathcal{R},T} \hat{v}_T, \hat{v}_{\mathcal{R},T} \cdot \hat{v}_{\mathcal{E},T} \right)_{F \in \mathcal{F}_T, \left( \hat{v}_E \right)_{E \in \mathcal{E}_T}}. \quad (6.19)$$

According to its definition (5.38), $R_{\mathcal{R},T} \hat{v}_T \in \mathcal{R}^{k-1}(T)$ satisfies, for all $w_T \in \mathcal{G}^{c,k}(T)$,

$$\int_T R_{\mathcal{R},T} \hat{v}_T \cdot \text{curl } w_T = \int_T C^k_T v_T \cdot w_T - \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F \gamma^k_{T,F} v_F \cdot (w_T \times n_F) = \int_T \hat{v}_{\mathcal{R},T} \cdot \text{curl } w_T,$$

where we have used (6.18) to write

$$\gamma^k_{T,F} E_{\text{curl},F} R_{\mathcal{R},T} \hat{v}_T = \gamma^k_{T,F} E_{\text{curl},F} R_{\mathcal{R},T} E_{\text{curl},F} \hat{v}_F = \gamma^k_{T,F} E_{\text{curl},F} \hat{v}_F = \gamma^k_{T,F} v_F$$

and concluded using the definition (4.7) of $C^k_T$ together with the fact that the component of $v_f = E_{\text{curl},T} \hat{v}_T$ on $\mathcal{R}^{k-1}(T)$ is $\hat{v}_{\mathcal{R},T}$. Since $\text{curl} : \mathcal{G}^{c,k}(T) \to \mathcal{R}^{k-1}(T)$ is onto, this gives $R_{\mathcal{R},T} \hat{v}_T = \hat{v}_{\mathcal{R},T}$, concluding the proof of a stronger property than (C1), namely $R_{\text{curl},h} E_{\text{curl},h} = \text{Id}$ on the whole of $\hat{X}_{\text{curl},h}^k$.\hfill \qedsymbol
(ii) Proof of (C2). Let \( \mathbf{v}_h \in \ker \mathbf{C}_h^k \) and set \( \mathbf{v}_h := \mathbf{R}_{\text{curl},h} \mathbf{v}_h \). By (6.17), the vector

\[
E_{\text{curl},h} \mathbf{v}_h - \mathbf{v}_h = \left( \left( \mathbf{R}_{\mathbf{R},T}^{k-1} \mathbf{v}_{\mathbf{R},T} - \mathbf{v}_{\mathbf{R},T}, \pi_{\mathbf{R},T}^k \mathbf{S}_{\text{curl},T}^k \mathbf{v}_{\mathbf{R},T} - \mathbf{v}_{\mathbf{R},T} \right)_{T \in T_h},
(0, \pi_{\mathbf{R},T}^k \mathbf{S}_{\text{curl},T}^k \mathbf{v}_{\mathbf{R},T} - \mathbf{v}_{\mathbf{R},T}^k)_{F \in F_h} \right), (0)_{E \in E_h}
\]

belongs to \( \ker \mathbf{C}_h^k \). By local exactness, for all \( T \in T_h \) we therefore have \( E_{\text{curl},T} \mathbf{v}_h - \mathbf{v}_h = \mathbf{G}_T^k \mathbf{v}_T \) for some \( \mathbf{v}_T \in X_{\text{grad},T}^k \) that is constant on the edge skeleton of \( T \) (since its derivative there vanishes by (6.19)). We can therefore assume, possibly after translation, that \( \mathbf{v}_{\mathbf{L},T} = 0 \). Moreover, for all \( F \in \mathcal{F}_h \), by definition (4.2) of \( \mathbf{G}_F \), \( \mathbf{v}_F \in \mathcal{P}^{k-1}(F) \) is entirely and uniquely fixed by the component \( \pi_{\mathbf{R},F}^k \mathbf{G}_F^k \mathbf{v}_F \) of \( \mathbf{G}_F^k \mathbf{v}_F \) on \( \mathcal{C}^{c,k}(F) \) (and the zero edge value of \( \mathbf{v}_T \)), which is \( \pi_{\mathbf{R},F}^k \mathbf{S}_{\text{curl},F}^k \mathbf{v}_F - \mathbf{v}_{\mathbf{R},F} \) by (6.19); hence, \( \mathbf{v}_F \) matches between neighbouring elements. This enables us to trivially glue together all the \( \mathbf{v}_T \) in each element into a vector \( \mathbf{v}_h \in X_{\text{grad},T}^k \) that satisfies \( E_{\text{curl},h} \mathbf{v}_h - \mathbf{v}_h = \mathbf{C}_h^k \mathbf{v}_h \), which concludes the proof of (C2).

(iii) Proof of (C3). This property is established in Lemmas 23 and 24.

(iv) Proof of (A1). The continuity of \( \mathbf{R}_{\text{grad},h} \mathbf{v}_h \) is proved in a similar way as that of \( \mathbf{R}_{\text{curl},h} \mathbf{v}_h \), using Lemma 20, the norm equivalence in \( X_{\text{curl},T}^k \) stated in Lemma 5 of [14], and the continuity of \( \mathbf{C}_h^k \) stated in Proposition 13 of [3].

(v) Proof of (A2). This property is only meaningful for the local complex on a mesh element \( T \in T_h \), for which it is simply (6.4) for \( P = T \).

(vi) Proof of (A3). This property is proved in Lemma 6 of [14].

\[\Box\]

**6.5. Divergence space**

As mentioned in Remark 11, no serendipity reduction of DOFs is performed on \( X_{\text{div},h}^k \). Hence, \( E_{\text{div},T} = \mathbf{R}_{\text{div},T} = \text{Id}_{X_{\text{div},T}^k} \) and (C1), (C2), (A1), and (A2) are trivially satisfied. Regarding (C3), the co-chain property of the reduction follows from (6.17), while that of the extension is simply due to the definition (2.2) of \( \mathbf{C}_h^k \). The property (A3) is proved in Lemma 6 of [14].

Reducing the number of DOFs in discrete spaces associated with the divergence operator is actually technically quite challenging, as already noticed in [21]. However, we argue here that such a reduction is simply not possible if one wants to preserve even only two (important) properties of the discrete complex, namely the commutation property of Proposition 8 and the local exactness property.

Let \( T \in T_h \). The definition (4.8) of \( D_T^k \) shows that this operator depends on the components on \( \mathcal{P}^k(F) \), \( F \in \mathcal{T}_h \), and \( \mathcal{G}^{k-1}(T) \) of \( X_{\text{div},T}^k \). To preserve the commutation property, only the component \( \mathcal{G}^{c,k}(T) \) can therefore be reduced (as already noticed in [21] in the context of VEM spaces). A candidate for the local serendipity space would therefore be: For some \( m_T < k - 1 \),

\[
\mathbf{X}_{\text{div},T}^k := \left\{ \mathbf{w}_T = (\mathbf{w}_{\mathbf{g},T}, \mathbf{w}_{\mathbf{c},T}, (\mathbf{w}_F)_{F \in \mathcal{F}_T}) : \mathbf{w}_{\mathbf{g},T} \in \mathcal{G}^{k-1}(T) \text{ and } \mathbf{w}_{\mathbf{c},T} \in \mathcal{G}^{c,m_T+1}(T), \text{ and } \mathbf{w}_F \in \mathcal{P}^k(F) \text{ for all } F \in \mathcal{T}_T \right\},
\]

with reduction operator \( \mathbf{R}_{\text{div},T} : \mathbf{X}_{\text{div},T}^k \to \mathbf{X}_{\text{div},T}^k \) defined by

\[
\mathbf{R}_{\text{div},T} \mathbf{w}_T = \left( \mathbf{w}_{\mathbf{g},T}, \pi_{\mathbf{c},T}^{m_T+1} \mathbf{w}_{\mathbf{g},T}, (\mathbf{w}_F)_{F \in \mathcal{F}_T} \right) \quad \forall \mathbf{w}_T \in \mathbf{X}_{\text{div},T}^k.
\]

However, such a choice would lead to a defect of the exactness property of the complex, specifically:

\[
\ker \mathbf{C}_T^k \subsetneq \text{Im} \mathbf{C}_T^k.
\]

(6.20)
Let us clearly demonstrate this. Since $m_T < k - 1$, we can find $\hat{v}_{\mathcal{R}, T} \in \mathcal{R}^{k-1}(T)$ such that $\hat{v}_{\mathcal{R}, T} \neq 0$ and $\hat{v}_{\mathcal{R}, T}$ is orthogonal to $\mathcal{R}^{m_{rT}}(T)$ for the $L^2(T)$-inner product. Set $\hat{v}_T := (\hat{v}_{\mathcal{R}, T}, 0, 0)_{F \in \mathcal{F}_T}, (0)_{E \in \mathcal{E}_T} \in \mathcal{X}_{\text{curl}, T}$ and let $v_T := E_{\text{curl}, T} \hat{v}_T$. We prove (6.20) by showing that
\[
\mathcal{C}^k_T \hat{v}_T := R_{\text{inv}, T} \mathcal{C}^k_T v_T = 0 \quad \text{and} \quad \hat{v}_T \notin \text{Im} \mathcal{C}^k_T.
\]

We first notice that $\mathcal{C}^k_F v_F = 0$ for all $F \in \mathcal{F}_T$, since all face and edge components of $v_T$ are equal zero. The link between element and face discrete curls of Proposition 4 from [14] then shows that $\pi_{\mathcal{G}, T}^{k-1} \mathcal{C}^k_T v_T = 0$. It remains to prove that the component of $R_{\text{inv}, T} \mathcal{C}^k_T v_T$ on $\mathcal{G}^{c,m_{rT}+1}(T)$ vanishes. Since $m_{rT} + 1 < k$, this component is $\pi_{\mathcal{G}, T}^{c,m_{rT}+1} \mathcal{C}^k_T v_T$. Since $v_F = 0$ for all $F \in \mathcal{F}_T$, the definition (4.17) of $\mathcal{C}^k_T$ yields
\[
\int_T \mathcal{C}^k_T v_T \cdot z_T = \int_T \hat{v}_{\mathcal{R}, T} \cdot \text{curl} z_T = 0 \quad \forall z_T \in \mathcal{G}^{c,m_{rT}+1}(T),
\]
where we have used in the first equality $v_{\mathcal{R}, T} = \hat{v}_{\mathcal{R}, T}$ (see (5.33)) and, to conclude, the orthogonality of $v_{\mathcal{R}, T}$ and $\mathcal{R}^{m_{rT}}(T)$. This proves the first relation in (6.21).

We prove the second relation by contradiction. Assume that $\hat{v}_T = \mathcal{G}^k_T q_T$, for some $q_T, \in \mathcal{X}_{\text{grad}, T}$. This gives, for all $F \in \mathcal{F}_T$, $\mathcal{G}^k_T q_F = v_F = 0$ and thus, by the cochain property (C3), $\mathcal{G}^k_T \mathcal{E}_{\text{grad}, T} q_F = E_{\text{curl}, T} \mathcal{G}^k_T q_F = 0$. Using the definition (5.38) of $R_{\mathcal{R}, T}$ together with $\mathcal{C}^k_T \mathcal{G}^k_T q_T = 0$ (see [14], Rem. 15), we deduce that $R_{\mathcal{R}, T} \mathcal{G}^k_T E_{\text{grad}, T} q_T = 0$. Since $\mathcal{G}^k_T q_T = \hat{v}_T$, this condition implies $v_{\mathcal{R}, T} = 0$, which contradicts our choice of $\hat{v}_{\mathcal{R}, T}$.

### 6.6. Homological and analytical properties of the SDDR complex and numerical tests

Lemmas 22 and 26 show that the Diagram (5.1) (as well as its global counterpart) fulfills Assumptions 1 and 3. By the results in Section 2, the SDDR complex thus inherits the homological and analytical properties of the DDR complex. Specifically:

- The SDDR complex has the same cohomology as the de Rham complex, whether the latter is exact (as in the case of domains without holes/tunnels) or has a non-trivial cohomology (Prop. 2, [14], Sect. 3 and [15]);
- The SDDR complex satisfies Poincaré’s inequalities (Prop. 4 and [14], Sect. 5);
- The SDDR complex satisfies primal and adjoint consistency properties of the reconstructed potentials and discrete differential operators (Props. 5–8, 10, and [14], Sect. 6).

As a consequence, the numerical scheme for the magnetostatics problem (1.1) obtained replacing in Section 7 of [14] the space $X_{\text{curl}, h}^k$ with its serendipity version $\hat{X}_{\text{curl}, h}^k$ has analogous convergence properties as the original one (see Thm. 12 of [14] for a precise statement of an error estimate). The same holds for the scheme for the Stokes problem obtained replacing in equation (3.14) of [16] the spaces $X_{\text{curl}, h}^k$ and $\hat{X}_{\text{grad}, h}^k$ with their serendipity counterparts. To assess the possible difference in practical accuracy and the gain resulting from the use of the serendipity space, we therefore compare the original DDR and the SDDR schemes on the numerical examples of Section 7.3 from [14] (for the magnetostatics problem) and Section 5 of [16] (for the Stokes problem, with pressure scaling $\lambda = 1$), for polynomial degrees $k = 1, 2, 3$; no DOF reduction is achieved for the lowest order degree $k = 0$, which is therefore removed from our comparison. All schemes are implemented within the open-source HArDCore3D C++ framework (see http://github.com/jdroniou/HArDCore), using standard C++ multi-threading routines and linear algebra facilities from the Eigen3 library (see http://eigen.tuxfamily.org). All tests were performed on a Dell Precision 5820 desktop with a 14-core Intel Xeon processor (W-2275) clocked at 3.3 GHz and equipped with 128 GB of DDR4 RAM, running Ubuntu 20.04.4 LTS.

A comparison of the corresponding discrete errors as functions of the mesh size for the “Tetgen-Cube-0” (matching simplicial) and “Voro-small-0” (Voronoi) mesh families available in the HArDCore3D repository is
Figure 2: Relative errors in the discrete $\mathbf{H}(\text{curl}; \Omega) \times \mathbf{H}(\text{div}; \Omega)$ norm vs. $h$, for the standard DDR scheme (continuous lines), and the SDDR scheme (dashed lines) applied to the magnetostatic problem. (a) "Voro-small-0" mesh. (b) "Tetgen-Cube-0" mesh.

Figure 3: Relative errors in the $\mathbf{H}(\text{curl}; \Omega) \times L^2(\Omega)^d$ norm (for the couple velocity–gradient of the pressure) vs. $h$, for the standard DDR scheme (continuous lines), and the SDDR scheme (dashed lines) applied to the Stokes problem. (a) "Voro-small-0" mesh. (b) "Tetgen-Cube-0" mesh.

provided in Figures 2 and 3, showing that the DDR and SDDR achieve optimal rates of convergence, irrespective of the considered mesh, polynomial degree or problem. The accuracies of both methods are almost identical for the magnetostatics problem. For the Stokes problem, SDDR appears to be slightly less accurate than DDR on
some meshes (by a maximum factor of about 2–3); a more precise analysis of each error component shows that
the loss of accuracy only occurs on the pressure variable, which can be explained by the fact that $\hat{X}_k^k$ has
about 50% fewer DOFs than $X_{\text{grad},h}^k$ on Voronoi meshes.

The (processor and wall) CPU times for the resolution of the linear systems (after static condensation of the
remaining element unknowns) through the MKL PARDISO solver (see https://software.intel.com/en-us/mkl) are depicted in Figures 4 and 5. The observed gain is significant: for the magnetostatics problem and $k = 3$ on the finest “Voro-small-0” mesh, a 40% reduction of the solution processor time is observed for the SDDR scheme, translating into a 45% reduction of the wall time (626 s vs. 1145 s). The gain is even more pronounced for the Stokes problem, with a reduction of about 57% in processor time and 52% in wall time (742 s vs. 1566 s), which again can be explained by the fact that the serendipity process is more efficient on the discrete $H^1$ space, used in the scheme for the Stokes problem but not for the magnetostatics problem. A comparison of the assembly wall and processor times, not reported here for the sake of conciseness, also confirms that, being an embarrassingly parallel step, assembly can fully benefit from shared-memory parallelism and that the additional calculations required for the serendipity spaces form a negligible portion of that assembly time.
Appendix A. Estimates of polynomials from boundary values

A.1. Proof of Lemma 14

Let \( q \in P^{k+1}(\mathcal{P}) \) and let us list the elements of \( B_{a,P} \) as \( b_1, \ldots, b_{\eta_P} \). We will construct by induction polynomials \((q_i)_{i=1,\ldots,\eta_P}\) and \((\tilde{q}_i)_{i=1,\ldots,\eta_P}\) such that, for all \( i = 1, \ldots, \eta_P \),

\[
q = q_1 + \text{dist}_{Pb_1} q_2 + \cdots + (\text{dist}_{Pb_1} \cdots \text{dist}_{Pb_{i-1}}) q_i + (\text{dist}_{Pb_1} \cdots \text{dist}_{Pb_j}) \tilde{q}_i,
\]

\[
q_i \in P^{k+1-i}(\mathcal{P}), \quad \tilde{q}_i \in P^{k+1-i}(\mathcal{P}), \quad \|q_i\|_P \lesssim h_P^{1/2} \left( \|q_i\|_{b_1} + \cdots + \|q_i\|_{b_j} \right). \tag{A.1}
\]

Let us first consider \( i = 1 \). We can easily extend \( q|_{b_1} \) (e.g., by making it independent of the normal coordinate to \( b_1 \)) as a polynomial \( q_1 \in P^{k+1}(\mathcal{P}) \) such that \( \|q_1\|_P \lesssim h_P^{1/2} \|q|_{b_1}\|_{b_1} \). Then, \( q - q_1 \in P^{k+1}(\mathcal{P}) \) vanishes on \( b_1 \), and can thus be factorised by \( \text{dist}_{Pb_1} \in P^1(\mathcal{P}) \): there is \( \tilde{q}_1 \in P^{k}(\mathcal{P}) \) such that \( q - q_1 = \text{dist}_{Pb_1} \tilde{q}_1 \). This concludes the proof of (A.1) for \( i = 1 \).

Let us now take \( j \leq \eta_P - 1 \) and show that this relation holds for \( i = j + 1 \) if it holds for \( i = 1, \ldots, j \). Since

\[
|\text{dist}_{Pb_r}| \lesssim 1 \quad \forall r = 1, \ldots, \eta_P,
\]

we have, by triangle inequality and the equality in (A.1) for \( i = j \),

\[
\| (\text{dist}_{Pb_1} \cdots \text{dist}_{Pb_j}) (\tilde{q}_j) |_{b_{j+1}} \|_{b_{j+1}} \lesssim \|q|_{b_{j+1}}\|_{b_{j+1}} + \cdots + \|q_j|_{b_{j+1}}\|_{b_{j+1}} \lesssim \|q_j|_{b_{j+1}}\|_{b_j} + \cdots + \|q_j|_{b_j}\|_{b_j} \tag{A.3}
\]

where the second line is obtained using discrete trace inequalities and the estimates in (A.1) for \( i = 1, \ldots, j \). Assumption 12 ensures that \( 0 \leq (\text{dist}_{Pb_1} \cdots \text{dist}_{Pb_j}) |_{b_{j+1}} \lesssim 1 \), and that \( (\text{dist}_{Pb_1} \cdots \text{dist}_{Pb_j}) |_{b_{j+1}} \gtrsim 1 \) on a ball in

Figure 5: Wall and processor times (in seconds) for the resolution of the linear system for the DDR and SDDR methods for the Stokes problem. Times correspond to the finest mesh of each sequence.
b_{j+1} of radius \( \geq h_{b_{j+1}} \). The arguments in the proof of Lemma 1.25 from [11] then show that the norms \( \| \cdot \|_{b_{j+1}} \) and \( \|(\text{dist}_{p_{b_1}} \cdots \text{dist}_{p_{b_j}})_{b_{j+1}} \|_{b_{j+1}} \) are equivalent on \( P^{k+1-j}(b_{j+1}) \), and we infer from (A.3) that

\[
\left\| (q_j)_{b_{j+1}} \right\|_{b_{j+1}} \lesssim \| q_{b_1} \|_{b_1} + \cdots + \| q_{b_j} \|_{b_j} + \| q_{b_{j+1}} \|_{b_{j+1}}.
\]

We then extend \( (q_j)_{b_{j+1}} \) into \( q_{j+1} \in P^{k+1-j}(P) \) such that

\[
\left\| q_{j+1} \right\|_P \lesssim h_P^{1/2} \left( \left\| q_{b_1} \right\|_{b_1} + \cdots + \left\| q_{b_{j+1}} \right\|_{b_{j+1}} \right)
\]

and we note that, since \( \tilde{q}_j - q_{j+1} \in P^{k+1-j}(P) \) vanishes on \( b_{j+1} \), we can factorise this polynomial into \( \tilde{q}_j - q_{j+1} = \text{dist}_{p_{b_{j+1}}} \tilde{q}_{j+1} \) with \( \tilde{q}_{j+1} \in P^{k+1-j}(P) \), which concludes the proof of (A.1) for \( i = j + 1 \).

To conclude the proof of the lemma, we consider (A.1) with \( i = \eta_P \). A triangle inequality and the estimate stated in this relation, together with (A.2), give

\[
\left\| q \right\|_P \lesssim h_P^{1/2} \left( \left\| q_{b_1} \right\|_{b_1} + \cdots + \left\| q_{b_{\eta_P}} \right\|_{b_{\eta_P}} \right) + \left\| q_{\eta_P} \right\|_P.
\]

Multiplying the equality in (A.1) by \( \tilde{q}_{\eta_P} \) and integrating over \( P \) yields

\[
\int_P \left( \text{dist}_{p_{b_1}} \cdots \text{dist}_{p_{b_{\eta_P}}} \right) \tilde{q}_{\eta_P}^2 = \int_P q \tilde{q}_{\eta_P} - \int_P q_1 \tilde{q}_{\eta_P} - \cdots - \int_P \left( \text{dist}_{p_{b_1}} \cdots \text{dist}_{p_{b_{\eta_P}-1}} \right) q_{\eta_P} \tilde{q}_{\eta_P}
\]

\[
= \int_P \left( \pi_{P, P_{\eta_P}}^{k+1-\eta_P} q \right) \tilde{q}_{\eta_P} - \int_P q_1 \tilde{q}_{\eta_P} - \cdots - \int_P \left( \text{dist}_{p_{b_1}} \cdots \text{dist}_{p_{b_{\eta_P}-1}} \right) q_{\eta_P} \tilde{q}_{\eta_P},
\]

where the introduction of the projector in the second line is justified by \( \tilde{q}_{\eta_P} \in P^{k+1-\eta_P}(P) \). Since \( \text{dist}_{p_{b_1}} \cdots \text{dist}_{p_{b_{\eta_P}}} \) is nonnegative and, by mesh regularity assumption, \( \geq 1 \) on a ball in \( P \) of radius \( \geq h_P \), we can use the arguments in the proof of Lemma 1.25 from [11], (A.2) and Cauchy–Schwarz inequalities to get

\[
\left\| \tilde{q}_{\eta_P} \right\|_P^2 \lesssim \int_P \left( \text{dist}_{p_{b_1}} \cdots \text{dist}_{p_{b_{\eta_P}}} \right) \tilde{q}_{\eta_P}^2 \lesssim \left\| \pi_{P, P_{\eta_P}}^{k+1-\eta_P} q \right\|_P \left\| q \right\|_P + \left\| q_1 \right\|_P \left\| \tilde{q}_{\eta_P} \right\|_P + \cdots + \left\| q_{\eta_P} \right\|_P \left\| \tilde{q}_{\eta_P} \right\|_P.
\]

Simplifying by \( \left\| q_i \right\|_P \) gives an upper bound on this quantity which, plugged into (A.4) together with the estimates on \( \left\| q_i \right\|_P \) stated in (A.1) for \( i = 1, \ldots, \eta_P \), concludes the proof of (5.2).

### A.2. Proof of Lemma 15

We focus on the case \( P = T = T_h \), the case \( P = F \in F_h \) being similar. Let \( v \in P^k(T) \). We first prove that

\[
h_T \left\| \text{curl} v \right\|_T \lesssim \left\| \pi_{\mathcal{R}_T}^{k-2} v \right\|_T + \left( \sum_{F \in \mathcal{F}_T} h_T \left\| v_{n_F} \right\|_F^2 \right)^{1/2}.
\]

For all \( w_T \in P^{k-1}(T) \), integrating by parts and introducing \( \pi_{\mathcal{R}_T}^{k-2} \) (owing to \( \text{curl} w_T \in \mathcal{R}^{k-2}(T) \)) gives

\[
\int_T \text{curl} v \cdot w_T = \int_T \pi_{\mathcal{R}_T}^{k-2} v \cdot \text{curl} w_T + \sum_{F \in \mathcal{F}_T} \omega_{TF} \int_F v_{n_F} \cdot (w_T \times n_F).
\]

Making \( w_T = h_T \text{curl} v \), using Cauchy–Schwarz and discrete inverse and trace inequalities, and simplifying leads to (A.5).
We now turn to the estimate on \( \mathbf{v} \), which we decompose as \( \mathbf{v} = \nabla \mathbf{g} + \mathbf{z} \) with \( (q, \mathbf{z}) \in \mathcal{P}^{k+1}(T) \times \mathcal{G}^{c,k}(T) \) (see (3.3)). Since \( \nabla \times \nabla \mathbf{g} = 0 \), we have \( \nabla \mathbf{g} = \nabla \mathbf{z} \) and, using the isomorphism estimate of \( \nabla : \mathcal{G}^{c,k}(T) \to \mathcal{R}^{k-1}(T) \) (see [14], Lem. 9), (A.5) gives

\[
\| \mathbf{z} \|_T \lesssim h_T \| \nabla \mathbf{z} \|_T \lesssim \left( \sum_{F \in \mathcal{F}_T} h_T \| \mathbf{v}_{1,F} \|_F^2 \right)^{1/2}.
\]

Upon adding a constant to \( q \), we can assume that \( q \) has a zero average on \( \partial T \); a Poincaré–Wirtinger inequality along this boundary, which can be obtained gluing Poincaré–Wirtinger inequalities on each face (following similar ideas as in Proof of Lem. 7 from [14], but in a simpler way since \( q_{|\partial T} \) is here continuous across the edges), then gives \( \| q \|_{\partial T} \lesssim h_T \sum_{F \in \mathcal{F}_T} \| \nabla q \|_{1,F} \|_F \). Since \( \| \nabla q \|_{1,F} = \mathbf{v}_{1,F} - \mathbf{z}_{1,F} \), the estimate (A.6) and discrete trace inequalities lead to

\[
\| q \|_{\partial T} \lesssim h_T \sum_{F \in \mathcal{F}_T} \| \mathbf{v}_{1,F} \|_F + h_T \sum_{F \in \mathcal{F}_T} \| \mathbf{z}_{1,F} \|_F \lesssim h_T^{1/2} \left( \sum_{F \in \mathcal{F}_T} h_T \| \mathbf{v}_{1,F} \|_F^2 \right)^{1/2}.
\]

We now estimate \( \pi^{k+1-\eta_T} q \). For all \( \mathbf{w}_T \in \mathcal{R}^{c,k+2-\eta_T}(T) \), recalling that \( \nabla \mathbf{g} = \mathbf{v} - \mathbf{z} \) we have

\[
\int_T q \div \mathbf{w}_T = -\int_T (\mathbf{v} - \mathbf{z}) \cdot \mathbf{w}_T + \sum_{F \in \mathcal{F}_T} \omega_T \int_F q (\mathbf{w}_T \cdot \mathbf{n}_F) = -\int_T (\pi^{c,k+2-\eta_T} \mathbf{v} - \mathbf{z}) \cdot \mathbf{w}_T + \sum_{F \in \mathcal{F}_T} \omega_T \int_F q (\mathbf{w}_T \cdot \mathbf{n}_F).
\]

We now use Cauchy–Schwarz inequalities, discrete trace inequalities, (A.7), and (A.6) to deduce

\[
\int_T q \div \mathbf{w}_T \lesssim \left( \sum_{F \in \mathcal{F}_T} h_T \| \mathbf{w}_T \|_F^2 \right)^{1/2} \| \mathbf{w}_T \|_T.
\]

This estimate and the isomorphism bound of \( \div : \mathcal{R}^{c,k+2-\eta_T}(T) \to \mathcal{P}^{k+1-\eta_T}(T) \) stated in Lemma 9 of [14] yield

\[
\left\| \pi^{k+1-\eta_T} q \right\|_T \lesssim h_T \left( \sum_{F \in \mathcal{F}_T} h_T \| \nabla \mathbf{g} \|_F^2 \right)^{1/2} =: h_T \mathcal{N}(\mathbf{v}),
\]

Plugging this estimate and (A.7) into (5.2), we infer \( \| q \|_T \lesssim h_T \mathcal{N}(\mathbf{v}) \) and thus, via a discrete inverse inequality, \( \| \nabla \mathbf{g} \|_T \lesssim \mathcal{N}(\mathbf{v}) \). Since \( \mathbf{v} = \nabla \mathbf{g} + \mathbf{z} \), this bound and (A.6) conclude the proof of (5.3).

Acknowledgements. The authors acknowledge the partial support of Agence Nationale de la Recherche grant ANR-20-MRS2-0004 NEMESIS. Daniele Di Pietro also acknowledges the partial support of I-Site MUSE grant ANR-16-IDEX-0006 RHAMNUS. The authors also thank Liam Yemm for his work on the mesh module in HArDCore3D.

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