Distributed Random Walks

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Performing random walks in networks is a fundamental primitive that has found applications in many areas of computer science, including distributed computing. In this article, we focus on the problem of sampling random walks efficiently in a distributed network and its applications. Given bandwidth constraints, the goal is to minimize the number of rounds required to obtain random walk samples.

All previous algorithms that compute a random walk sample of length \( \ell \) as a subroutine always do so naively, that is, in \( O(\ell) \) rounds. The main contribution of this article is a fast distributed algorithm for performing random walks. We present a sublinear time distributed algorithm for performing random walks whose time complexity is sublinear in the length of the walk. Our algorithm performs a random walk of length \( \ell \) in \( O(\sqrt{D}) \) rounds (\( O \) hides polylog factors where \( n \) is the number of nodes in the network) with high probability on an undirected network, where \( D \) is the diameter of the network. For small diameter graphs, this is a significant improvement over the naive \( O(\ell) \) bound. Furthermore, our algorithm is optimal within a poly-logarithmic factor as there exists a matching lower bound [Nanongkai et al. 2011]. We further extend our algorithms to efficiently perform \( k \) independent random walks in \( O(\sqrt{D} + k) \) rounds. We also show that our algorithm can be applied to speedup the more general Metropolis-Hastings sampling.

Our random-walk algorithms can be used to speed up distributed algorithms in applications that use random walks as a subroutine. We present two main applications. First, we give a fast distributed algorithm for computing a random spanning tree (RST) in an arbitrary (undirected unweighted) network which runs in \( O(\sqrt{mD}) \) rounds with high probability (\( m \) is the number of edges). Our second application is a fast decentralized algorithm for estimating mixing time and related parameters of the underlying network. Our algorithm is fully decentralized and can serve as a building block in the design of topologically-aware networks.

Categories and Subject Descriptors: C.2.4 [Computer-Communication Networks]: Distributed Systems; F.0 [Theory of Computation]: General; G.2.2 [Discrete Mathematics]: Graph Theory

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1. INTRODUCTION

Random walks play a central role in computer science, spanning a wide range of areas in both theory and practice. The focus of this article is on random walks in networks, in particular, decentralized algorithms for performing random walks in arbitrary networks. Random walks are used as an integral subroutine in a wide variety of network applications ranging from token management [Bernard et al. 2004; Coppersmith et al. 1993; Israeli and Jalfon 1990], load balancing [Karger and Ruhl 2006], small-world routing Kleinberg [2000], search [Adamic et al. 2001; Cooper 2005; Gkantsidis et al. 2005; Lv et al. 2002; Zhong and Shen 2006], information propagation and gathering [Bharambe et al. 2004; Kempe et al. 2004], network topology construction [Gkantsidis et al. 2005; Law and Siu 2003; Loguinov et al. 2003], checking expansion [Dolev and Tzachar 2010], constructing random spanning trees [Baala et al. 2003; Bar-Ilan and Zernik 1989; Broder 1989], monitoring overlays [Morales and Gupta 2007], group communication in ad-hoc network [Dolev et al. 2006], gathering and dissemination of information over a network [Aleliunas et al. 1979], distributed construction of expander networks [Law and Siu 2003], and peer-to-peer membership management [Ganesh et al. 2003; Zhong et al. 2005]. Random walks are also very useful in providing uniform and efficient solutions to distributed control of dynamic networks [Bui et al. 2004; Zhong and Shen 2006]. Random walks are local and lightweight; moreover, they require little index or state maintenance which makes them especially attractive to self-organizing dynamic networks such as Internet overlay and ad hoc wireless networks.

A key purpose of random walks in many of these network applications is to perform node sampling. While the sampling requirements in different applications vary, whenever a true sample is required from a random walk of certain steps, typically all applications perform the walk naively—by simply passing a token from one node to its neighbor: thus to perform a random walk of length \( \ell \) takes time linear in \( \ell \).

In this article, we present an optimal (within a poly-logarithmic factor) sublinear time (sublinear in \( \ell \)) distributed random walk sampling algorithm that is significantly faster than the naive algorithm when \( \ell \gg D \). Our algorithm runs in time \( O(\sqrt{D}) \) rounds. This running time is optimal (within a poly-logarithmic factor) since a matching lower bound was shown recently in Nanongkai et al. [2011]. We then present two key applications of our algorithm. The first is a fast distributed algorithm for computing a random spanning tree, a fundamental problem that has been studied widely in the classical setting (see e.g., Kelner and Madry [2009] and references therein) and in some special cases in distributed settings [Bar-Ilan and Zernik 1989]. To the best of our knowledge, our algorithm gives the fastest known running time in an arbitrary network. The second is to devising efficient decentralized algorithms for computing key global metrics of the underlying network—mixing time, spectral gap, and conductance. Such algorithms can be useful building blocks in the design of topologically (self-)aware networks, that is, networks that can monitor and regulate themselves in a decentralized fashion. For example, efficiently computing the mixing time or the
spectral gap, allows the network to monitor connectivity and expansion properties of the network.

1.1. Distributed Computing
Consider an undirected, unweighted, connected \( n \)-node graph \( G = (V, E) \). The network is modeled by an undirected \( n \)-vertex graph, where vertices model the processors and edges model the links between the processors. Suppose that every node (vertex) hosts a processor with unbounded computational power, but with limited initial knowledge. The processors communicate by exchanging messages via the links (henceforth, edges). The vertices have limited global knowledge, in particular, each of them has its own local perspective of the network, which is confined to its immediate neighborhood. Specifically, assume that each node is associated with a distinct identity number from the set \( \{1, 2, \ldots, \text{poly}(n)\} \). At the beginning of the computation, each node \( v \) accepts as input its own identity number and the identity numbers of its neighbors in \( G \). The node may also accept some additional inputs as specified by the problem at hand. The nodes are allowed to communicate through the edges of the graph \( G \). The communication is synchronous, and occurs in discrete pulses, called rounds. In particular, all the nodes wake up simultaneously at the beginning of round 1. For convenience, our algorithms assume that nodes always know the number of the current round (although this is not really needed—cf. Section 2).

We assume the CONGEST communication model, a widely used standard model to study distributed algorithms [Peleg 2000]: a node \( v \) can send an arbitrary message of size at most \( O(\log n) \) through an edge per time step. (We note that if unbounded-size messages were allowed through every edge in each time step, then the problems addressed here can be trivially solved in \( O(D) \) time by collecting all information at one node, solving the problem locally, and then broadcasting the results back to all the nodes [Peleg 2000].) The design of efficient algorithms for the CONGEST model has been the subject of an active area of research called (locality-sensitive) distributed computing (see Peleg [2000] and references therein.) It is straightforward to generalize our results to a CONGEST\((B)\) model, where \( O(B) \) bits can be transmitted in a single time step across an edge.

There are several measures of efficiency of distributed algorithms, but we will concentrate on one of them, specifically, the running time, that is, the number of rounds of distributed communication. (Note that the computation that is performed by the nodes locally is “free”, that is, it does not affect the number of rounds.)

Many fundamental network problems such as minimum spanning tree, shortest paths, etc. have been addressed in this model (e.g., see Lynch [1996], Peleg [2000], and Pandurangan and Khan [2010]). In particular, there has been much research into designing very fast distributed approximation algorithms (that are even faster at the cost of producing suboptimal solutions) for many of these problems (see e.g., Elkin [2004], Dubhashi et al. [2007], Khan and Pandurangan [2008], and Khan et al. [2012]). Such algorithms can be useful for large-scale resource-constrained and dynamic networks where running time is crucial.

1.2. Problems
We consider the following basic random walk problem.

**Computing One Random Walk where Destination Outputs Source.** We are given an arbitrary undirected, unweighted, and connected \( n \)-node network \( G = (V, E) \) and a source node \( s \in V \). The goal is to devise a distributed algorithm such that, in the end, some node \( v \) outputs the ID of \( s \), where \( v \) is a destination node picked according to the
probability that it is the destination of a random walk of length $\ell$ starting at $s$. For brevity, this problem will henceforth be simply called Single Random Walk.

For clarity, observe that the following naive algorithm solves the previous problem in $O(\ell)$ rounds: The walk of length $\ell$ is performed by sending a token for $\ell$ steps, picking a random neighbor in each step. Then, the destination node $v$ of this walk outputs the ID of $s$. Our goal is to perform such sampling with significantly less number of rounds, that is, in time that is sublinear in $\ell$. On the other hand, we note that it can take too much time (as much as $\Theta(\sqrt{|E| + |D|}$) time) in the CONGEST model to collect all the topological information at some node (and then computing the walk locally).

We also consider the following variations and generalizations of the Single Random Walk problem.

1. **$k$ Random Walks, Destinations Output Sources ($k$-RW-DoS).** We have $k$ sources $s_1, s_2, \ldots, s_k$ (not necessarily distinct) and we want each of $k$ destinations to output the ID of its corresponding source.

2. **$k$ Random Walks, Sources Output Destinations ($k$-RW-SoD).** Same as (1) but we want each source to output the ID of its corresponding destination.

3. **$k$ Random Walks, Nodes Know Their Positions ($k$-RW-pos).** Instead of outputting the ID of source or destination, we want each node to know its position(s) in the random walk. That is, for each $s_i$, if $v_1, v_2, \ldots, v_\ell$ (where $v_1 = s_i$) is the resultant random walk starting at $s_i$, we want each node $v_j$ in the walk to know the number $j$ at the end of the process.

Throughout this article, we assume the standard (simple) random walk: in each step, an edge is taken from the current node $v$ with probability $1/\deg(v)$ where $\deg(v)$ is the degree of $v$. Our goal is to output a true random sample from the $\ell$-walk distribution starting from $s$.

### 1.3. Motivation

There are two key motivations for obtaining sublinear time bounds. The first is that in many algorithmic applications, walks of length significantly greater than the network diameter are needed. For example, this is necessary in both the applications presented later in the paper, namely distributed computation of a random spanning tree (RST) and computation of mixing time. In the RST algorithm, we need to perform a random walk of expected length $O(mD)$ (where $m$ is the number of edges in the network). In decentralized computation of mixing time, we need to perform walks of length at least the mixing time which can be significantly larger than the diameter (e.g., in a random geometric graph model [Muthukrishnan and Pandurangan 2010], a popular model for ad hoc networks, the mixing time can be larger than the diameter by a factor of $\Omega(\sqrt{n})$.) More generally, many real-world communication networks (e.g., ad hoc networks and peer-to-peer networks) have relatively small diameter, and random walks of length at least the diameter are usually performed for many sampling applications, that is, $\ell \gg D$. It should be noted that if the network is rapidly mixing/expanding, which is sometimes the case in practice, then sampling from walks of length $\ell \gg D$ is close to sampling from the steady state (degree) distribution; this can be done in $O(D)$ rounds (note however, that this gives only an approximately close sample, not the exact sample for that length). However, such an approach fails when $\ell$ is smaller than the mixing time.

The second motivation is understanding the time complexity of distributed random walks. Random walk is essentially a “global” problem which requires the algorithm to “traverse” the entire network. Classical global problems include the minimum spanning tree, shortest path etc. Network diameter is an inherent lower bound for such problems. Problems of this type raise the basic question whether $n$ (or $\ell$ as is
the case here) time is essential or is the network diameter $D$, the inherent parameter. As pointed out in the work of Garay et al. [1998], in the latter case, it would be desirable to design algorithms that have a better complexity for graphs with low diameter.

**Notation.** Throughout the article, we let $\ell$ be the length of the walks, $k$ be the number of walks, $D$ be the network diameter, $\delta$ be the minimum node degree, $n$ be the number of nodes, and $m$ be the number of edges in the network.

### 1.4. Our Results

**A Fast Distributed Random Walk Algorithm.** We present the first sublinear, time-optimal, distributed algorithm for the 1-RW-DoS problem in arbitrary networks that runs in time $\tilde{O}(\sqrt{\ell D})$ with high probability,\(^1\) where $\ell$ is the length of the walk (the precise theorem is stated in Section 2). Our algorithm is randomized (Las Vegas type, that is, it always outputs the correct result, but the running time claimed is with high probability).

The high-level idea behind our algorithm is to “prepare” a few short walks in the beginning and carefully stitch these walks together later as necessary. If there are not enough short walks, we construct more of them on the fly. We overcome a key technical problem by showing how one can perform many short walks in parallel without causing too much congestion.

Our algorithm exploits a certain key property of random walks. The key property is a bound on the number of times any node is visited in an $\ell$-length walk, for any length $\ell = O(m^2)$. We prove that w.h.p. any node $x$ is visited at most $\tilde{O}(\deg(x)\sqrt{\ell})$ times, in an $\ell$-length walk from any starting node (deg($x$) is the degree of $x$). We then show that if only certain $\ell/\lambda$ special points of the walk (called connector points) are observed, then any node is observed only $\tilde{O}(\deg(x)\sqrt{\ell/\lambda})$ times. The algorithm starts with all nodes performing short walks (of length uniformly random in the range $\lambda$ to $2\lambda$ for appropriately chosen $\lambda$) efficiently and simultaneously; here the randomly chosen lengths play a crucial role in arguing about a suitable spread of the connector points. Subsequently, the algorithm begins at the source and carefully stitches these walks together till $\ell$ steps are completed.

We note that the running time of our algorithm matches the unconditional lower bound recently shown in Nanongkai et al. [2011]. Thus, the running time of our algorithm is (essentially) the best possible (up to polylogarithmic factors).

We also extend the result to give algorithms for computing $k$ random walks (from any $k$ sources—not necessarily distinct) in $\tilde{O}(\min(\sqrt{k\ell D} + k, k + \ell))$ rounds. We note that the $k$ random walks generated by our algorithm are independent (cf. Section 4.1). Computing $k$ random walks is useful in many applications such as the one we present below on decentralized computation of mixing time and related parameters. While the main requirement of our algorithms is to just obtain the random walk samples (i.e., the end point of the $\ell$ step walk), our algorithms can regenerate the entire walks such that each node knows its position(s) among the $\ell$ steps (the $k$-RW-pos problem). Our algorithm can be extended to do this in the same number of rounds.

\(^1\)Throughout this article, “with high probability (whp)” means with probability at least $1 - 1/n^{\Omega(1)}$, where $n$ is the number of nodes in the network.
We finally present extensions of our algorithm to perform random walk according to the Metropolis-Hastings [Hastings 1970; Metropolis et al. 1953] algorithm, a more general type of random walk with numerous applications (e.g., Zhong and Shen [2006]). The Metropolis-Hastings algorithm gives a way to define transition probabilities so that a random walk converges to any desired distribution. An important special case is when the distribution is uniform.

Remarks. While the message complexity is not the main focus of this article, we note that our improved running time comes with the cost of an increased message complexity from the naive algorithm (we discuss this in Section 6). Our message complexity for computing a random walk of length $\ell$ is $\tilde{O}(m\sqrt{D} + n\sqrt{\ell/D})$ which can be worse than the naive algorithm’s $\tilde{O}(\ell)$ message complexity.

Applications. Our faster distributed random walk algorithm can be used in speeding up distributed applications where random walks arise as a subroutine. Such applications include distributed construction of expander graphs, checking whether a graph is an expander, construction of random spanning trees, and random-walk based search (we refer to Das Sarma et al. [2009] for details). Here, we present two key applications.

(1) A Fast Distributed Algorithm for Random Spanning Trees (RST). We give an $\tilde{O}(\sqrt{mD})$ time distributed algorithm (cf. Section 5.1) for uniformly sampling a random spanning tree in an arbitrary undirected (unweighted) graph (i.e., each spanning tree in the underlying network has the same probability of being selected). Spanning trees are fundamental network primitives and distributed algorithms for various types of spanning trees such as minimum spanning tree (MST), breadth-first spanning tree (BFS), shortest path tree, shallow-light trees etc., have been studied extensively in the literature [Peleg 2000]. However, not much is known about the distributed complexity of the random spanning tree problem. The centralized case has been studied for many decades, see for example, the recent work of Kelner and Madry [2009] and the references therein; also see the recent work of Goyal et al. [2009], which gives nice applications of RST to fault-tolerant routing and constructing expanders. In the distributed computing context, the work of Bar-Ilan and Zernik [1989] give distributed RST algorithms for two special cases, namely that of a complete graph (running in constant time) and a synchronous ring (running in $O(n)$ time). The work of Baala et al. [2003] gives a self-stabilizing distributed algorithm for constructing an RST in a wireless ad hoc network and mentions that RST is more resilient to transient failures that occur in mobile ad hoc networks.

Our algorithm works by giving an efficient distributed implementation of the well-known Aldous-Broder random walk algorithm [Aldous 1990; Broder 1989] for constructing an RST.

(2) Decentralized Computation of Mixing Time. We present a fast decentralized algorithm for estimating mixing time, conductance and spectral gap of the network (cf. Section 5.2). In particular, we show that given a starting point $x$, the mixing time with respect to $x$, called $\tau^x_{\text{mix}}$, can be estimated in $\tilde{O}\left(n^{1/2} + n^{1/4}/\sqrt{D\tau^x_{\text{mix}}}\right)$ rounds. This gives an alternative algorithm to the only previously known approach by Kempe and McSherry [2008] that can be used to estimate $\tau^x_{\text{mix}}$ in $\tilde{O}(\tau^x_{\text{mix}})$. 

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rounds.\textsuperscript{2} To compare, we note that when $t_{\text{mix}}^x = \omega(n^{1/2})$ the present algorithm is faster (assuming $D$ is not too large).

1.5. Related Work

Random walks have been used in a wide variety of applications in distributed networks as mentioned in the beginning of Section 1. We describe here some of the applications in more detail. Our focus is to emphasize the papers of a more theoretical nature, and those that use random walks as one of the central subroutines.

Speeding up distributed algorithms using random walks has been considered for a long time. Besides our approach of speeding up the random walk itself, one popular approach is to reduce the cover time. Recently, Alon et al. [2011] show that performing several random walks in parallel reduces the cover time in various types of graphs. They assert that the problem with performing random walks is often the latency. In these scenarios where many walks are performed, our results could help avoid too much latency and yield an additional speed-up factor. Other recent works involving multiple random walks in different settings include Elsässer and Sauerwald [2011] and Cooper et al. [2009].

A nice application of random walks is in the design and analysis of expanders. We mention two results here. Law and Siu [2003] consider the problem of constructing expander graphs in a distributed fashion. One of the key subroutines in their algorithm is to perform several random walks from specified source nodes. While the overall running time of their algorithm depends on other factors, the specific step of computing random walk samples can be improved using our techniques presented in this article. Dolev and Tzachar [2010] use random walks to check if a given graph is an expander. The first algorithm given in Dolev and Tzachar [2010] is essentially to run a random walk of length $n \log n$ and mark every visited vertices. Later, it is checked if every node is visited.

Broder [1989] and Wilson [1996] gave algorithms to generate random spanning trees using random walks and Broder’s algorithm was later applied to the network setting by Bar-Ilan and Zernik [1989]. Recently Goyal et al. [2009] show how to construct an expander/sparsifier using random spanning trees. If their algorithm is implemented on a distributed network, the techniques presented in this article would yield an additional speed-up in the random walk constructions.

Morales and Gupta [2007] discuss about discovering a consistent and available monitoring overlay for a distributed system. For each node, one needs to select and discover a list of nodes that would monitor it. The monitoring set of nodes need to satisfy some structural properties such as consistency, verifiability, load balancing, and randomness, among others. This is where random walks come in. Random walks is a natural way to discover a set of random nodes that are spread out (and hence scalable), that can in turn be used to monitor their local neighborhoods. Random walks have been used for this purpose in another paper by Ganesh et al. [2003] on peer-to-peer membership management for gossip-based protocols.

The general high-level idea of using a few short walks in the beginning (executed in parallel) and then carefully stitch these walks together later as necessary was

\textsuperscript{2}Note that Kempe and McSherry [2008] in fact does more and gives a decentralized algorithm for computing the top $k$ eigenvectors of a weighted adjacency matrix that runs in $O\left( t_{\text{mix}}^{2/3} \log^2 n \right)$ rounds if two adjacent nodes are allowed to exchange $O(k^3)$ messages per round, where $t_{\text{mix}}$ is the mixing time and $n$ is the size of the network.

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introduced in Das Sarma et al. [2011a] to find random walks in data streams with the main motivation of computing PageRank. However, the two models have very different constraints and motivations and hence the subsequent techniques used here and in Das Sarma et al. [2011a] are very different. Recently, Sami and Twigg [2008] consider lower bounds on the communication complexity of computing the stationary distribution of random walks in a network. Although their problem is related to our problem, the lower bounds obtained do not imply anything in our setting.

The work of Gkantsidis et al. [2007] discusses spectral algorithms for enhancing the topology awareness, for example, by identifying and assigning weights to critical links. However, the algorithms are centralized, and it is mentioned that obtaining efficient decentralized algorithms is a major open problem. Our algorithms are fully decentralized and based on performing random walks, and so are more amenable to dynamic and self-organizing networks.

Subsequent Work. Since the publication of the conference versions of our papers Das Sarma et al. [2009, 2010], additional results have been shown, extending our algorithms to various settings.

The work of Nanongkai et al. [2011] showed a tight lower bound on the running time of distributed random walk algorithms using techniques from communication complexity Das Sarma et al. [2011b]. Specifically, it is shown in Nanongkai et al. [2011] that for any \( n, D, \) and \( D \leq \ell \leq (n / (D^3 \log n))^{1/4} \), performing a random walk of length \( \Theta(\ell) \) on an \( n \)-node network of diameter \( D \) requires \( \Omega(\sqrt{D} + D) \) time. This shows that the running time of our 1-RW-DoS algorithm is (essentially) the best possible (up to polylogarithmic factors).

In Das Sarma et al. [2012b], it is shown how to improve the message complexity of the distributed random walk algorithms presented in this article. The main reason for the increased message complexity of our algorithms is that to compute one long walk many short walks are generated—most of which go unused. One idea is to use these unused short walks to compute other (independent) long walks. This idea is explored in Das Sarma et al. [2012b] where it is shown that under certain conditions (e.g., when the starting point of the random walk is chosen proportional to the node degree), the overall message complexity of computing many long walks can be made near-optimal.

The fast distributed random walk algorithms presented in this article applies only for static networks and does not apply to a dynamic network. The recent work of Das Sarma et al. [2012a] investigates efficient distributed computation in dynamic networks in which the network topology changes (arbitrarily) from round to round. The article presents a rigorous framework for design and analysis of distributed random walk sampling algorithms in dynamic networks. Building on the techniques developed in this article, the main contribution of Das Sarma et al. [2012a] is a fast distributed random walk sampling algorithm that runs in \( \tilde{O}(\sqrt{\tau \Phi}) \) rounds (with high probability) (\( \tau \) is the dynamic mixing time and \( \Phi \) is the dynamic diameter of the network) and returns a sample close to a suitably defined stationary distribution of the dynamic network. This is then shown to be useful in designing a fast distributed algorithm for information spreading in a dynamic network.

2. ALGORITHM FOR 1-RW-DoS

In this section, we describe the algorithm to sample one random walk destination. We show that this algorithm takes \( \tilde{O}(\sqrt{\tau D}) \) rounds with high probability and extend it to other cases in the next sections. First, we make the following simple observation, which will be assumed throughout.
Observation 2.1. We may assume that $\ell$ is $O(m^2)$, where $m$ is the number of edges in the network.

The reason is that if $\ell$ is $\Omega(m^2)$, the required bound of $\tilde{O}(\sqrt{D})$ rounds is easily achieved by aggregating the graph topology (via upcast) onto one node in $O(m + D)$ rounds (e.g., see Peleg [2000]). The difficulty lies in proving the case of $\ell = O(m^2)$.

A Slower Algorithm. Let us first consider a slower version of the algorithm to highlight the fundamental idea used to achieve the sublinear time bound. We will show that the slower algorithm runs in time $\tilde{O}(\ell^2/D^{1/3})$. The high-level idea (see Figure 1) is to perform “many” short random walks in parallel and later stitch them together as needed. In particular, we perform the algorithm in two phases, as follows.

In Phase 1, we perform $\eta$ “short” random walks of length $\lambda$ from each node $v$, where $\eta$ and $\lambda$ are some parameters whose values will be fixed in the analysis. (We note that we will need slightly more short walks when we develop a faster algorithm.) This is done naively by forwarding $\eta$ “coupons” having the ID of $v$, from $v$ to random destinations, as follows.

1. Initially, each node $v$ creates $\eta$ messages (called coupons) $C_1, C_2, ..., C_\eta$ and writes its ID on them.
2. for $i = 1$ to $\lambda$ do
3.   This is the $i$th iteration. Each node $v$ does the following: Consider each coupon $C$ held by $v$ which is received in the $(i - 1)$th iteration. (The zeroth iteration is the initial stage where each node creates its own messages.) Now $v$ picks a neighbor $u$ uniformly at random and forwards $C$ to $u$ after incrementing the counter on the coupon to $i$.
4. end for

At the end of the process, for each node $v$, there will be $\eta$ coupons containing $v$’s ID distributed to some nodes in the network. These nodes are the destinations of short walks of length $\lambda$ starting at $v$. We note that the notion of “phase” is used only for simplicity. The algorithm does not really need round numbers. If there are many messages to be sent through the same edge, send one with minimum counter first.

For Phase 2, for sake of exposition, let us first consider an easier version of the algorithm (that is incomplete) which avoids some details. Starting at source $s$, we “stitch” some of the $\lambda$-length walks prepared in Phase 1 together to form a longer walk. The algorithm starts from $s$ and randomly picks one coupon distributed from $s$ in Phase 1. This can be accomplished by having every node holding coupons of $s$ write their IDs on the coupon and sending the coupons back to $s$. Then $s$ picks one of these coupons randomly and returns the rest to the owners. (However, aggregating all coupons at $s$ is inefficient. The better way to do this is to use the idea of reservoir sampling [Vitter 1985]. We will develop an algorithm called SAMPLE-COUPON to do this job efficiently later on.)

Let $C$ be the sampled coupon and $v$ be the destination node of $C$. The source $s$ then sends a “token” to $v$ and $v$ deletes coupon $C$ (so that $C$ will not be sampled again next time). The process then repeats. That is, the node $v$ currently holding the token samples one of the coupons it distributed in Phase 1 and forwards the token to the destination of the sampled coupon, say $v'$. (Nodes $v, v'$ are called “connectors”—they are the endpoints of the short walks that are stitched.) A crucial observation is that the walk of length $\lambda$ used to distribute the corresponding coupons from $s$ to $v$ and from

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3The term “coupon” refers to the same meaning as the more commonly used term of “token” but we use the term “coupon” here and reserve the term “token” for the second phase.
After Phase 1, many short walks of length $1\cdot[0,1]$ are prepared.

Starting at source, these walks get stitched. Connectors are the stitching points.

Fig. 1. Figure illustrating the algorithm of stitching short walks together.

$v$ to $v'$ are independent random walks. Therefore, we can stitch them to get a random walk of length $2\lambda$. (This fact will be formally proved in the next section.) We therefore can generate a random walk of length $3\lambda, 4\lambda, ...$ by repeating this process. We do this until we have completed more than $\ell - \lambda$ steps. Then, we complete the rest of the walk by running the naive random walk algorithm. The algorithm for Phase 2 is thus the following.

1: The source node $s$ creates a message called “token” which contains the ID of $s$

2: while Length of the walk completed is at most $\ell - \lambda$

3: Let $v$ be the node that is currently holding the token.

4: $v$ calls $\text{SAMPLE-COUPON}(v)$ to sample one of the coupons distributed by $v$ (in Phase 1) uniformly at random. Let $C$ be the sampled coupon.

5: Let $v'$ be the node holding coupon $C$. (ID of $v'$ is written on $C$.)

6: $v$ sends the token to $v'$ and $v'$ deletes $C$ so that $C$ will not be sampled again.

7: The length of the walk completed has now increased by $\lambda$.

8: end while

9: Walk naively (i.e., forward the token to a random neighbor) until $\ell$ steps are completed.

10: A node holding the token outputs the ID of $s$.

Figure 1 illustrates the idea of this algorithm. To understand the intuition behind this (incomplete) algorithm, let us analyze its running time. First, we claim that Phase 1 needs $\tilde{O}(\eta\lambda)$ rounds with high probability. This is because if we send out $\deg(v)$ coupons from each node $v$ at the same time, each edge should receive two coupons in the average case. In other words, there is essentially no congestion (i.e., not too many coupons are sent through the same edge). Therefore, sending out (just) one coupon from each node for $\lambda$ steps will take $O(\lambda)$ rounds in expectation and the time becomes $O(\eta\lambda)$
for $\eta$ coupons. This argument can be modified to show that we need $O(\eta \lambda)$ rounds with high probability. (The full proof will be provided in Lemma 3.2 in the next section.) We will also show that SAMPLE-COUPON can be done in $O(D)$ rounds and it follows that Phase 2 needs $O(D \cdot \ell / \lambda)$ rounds. Therefore, the algorithm needs $O(\eta \lambda + D \cdot \ell / \lambda)$ which is $O(\sqrt{\ell D})$ when we set $\eta = 1$ and $\lambda = \sqrt{\ell D}$.

The reason the above algorithm for Phase 2 is incomplete is that it is possible that $\eta$ coupons are not enough: We might forward the token to some node $v$ many times in Phase 2 and all coupons distributed by $v$ in the first phase may get deleted. In other words, $v$ is chosen as a connector node many times, and all its coupons have been exhausted. If this happens, then the stitching process cannot progress. To cope with this problem, we develop an algorithm called SEND-MORE-COUPONS to distribute more coupons. In particular, when there is no coupon of $v$ left in the network and $v$ wants to sample a coupon, it calls SEND-MORE-COUPONS to send out $\eta$ new coupons to random nodes. (SEND-MORE-COUPONS gives the same result as Phase 1 but the algorithm will be different in order to get a good running time.) In particular, we insert the following lines between Line 4 and 5 of the previous algorithm.

1: if $C = \text{NULL}$ (all coupons from $v$ have already been deleted) then
2: $v$ calls SEND-MORE-COUPONS($v$, $\eta$, $\lambda$) (Distribute $\eta$ new coupons. These coupons are forwarded for $\lambda$ rounds.)
3: $v$ calls SAMPLE-COUPON($v$) and let $C$ be the returned coupon.
4: end if

To complete this algorithm we now describe SAMPLE-COUPON and SEND-MORE-COUPONS. The main idea of algorithm SAMPLE-COUPON is to sample the coupons through a BFS (breadth-first search) tree from the leaves upward to the root. We allow each node to send only one coupon to its parent to avoid congestion. That is, in each round some node $u$ will receive some coupons from its children (at most one from each child). Let these children be $u_1, u_2, \ldots, u_q$. Then, $u$ picks one of these coupons and sends to its parent. To ensure that $u$ picks a coupon with uniform distribution, it picks the coupon received from $u_i$ with probability proportional to the number of coupons in the subtree rooted at $u_i$. The precise statement of this algorithm can be found in Algorithm 1. The correctness of this algorithm (i.e., it outputs a coupon from uniform probability) will be proved in the next section (cf. Claim 3.8).

The SEND-MORE-COUPONS algorithm does essentially the same as what we did in Phase 1 with only one exception: Since this time we send out coupons from only one node, we can avoid congestions by combining coupons delivered on the same edge in each round. This algorithm is described in Algorithm 2, Part 1. (We will describe Part 2 later after we explain how to speed up the algorithm).

The analysis in the next section shows that SEND-MORE-COUPONS is called at most $\ell / (\eta \lambda)$ times in the worst case and it follows that the algorithm above takes time $O(\sqrt{\ell D})$.

Faster Algorithm. We are now ready to introduce the second idea which will complete the algorithm. (The complete algorithm is described in Algorithm 3.) To speed up the above slower algorithm, we pick the length of each short walk uniformly at random in range $[\lambda, 2\lambda - 1]$, instead of fixing it to $\lambda$. The reason behind this is that we want every node in the walk to have some probability to take part in token forwarding in Phase 2.

For example, consider running our random walk algorithm on a star network starting at the center and let $\lambda = 2$. If all short walks have length two then the center will always forward the token to itself in Phase 2. In other words, the center is the only connector and thus will appear as a connector $\ell / 2$ times. This is undesirable since we
**Algorithm 1:** \textsc{Sample-Coupon}(v)

**Input:** Starting node \(v\).

**Output:** A node sampled from among the nodes holding the coupon of \(v\).

1: Construct a Breadth-First-Search (BFS) tree rooted at \(v\). While constructing, every node stores its parent’s ID. Denote such a tree by \(T\).

2: We divide \(T\) naturally into levels 0 through \(D\) (where nodes in level \(D\) are leaf nodes and the root node \(v\) is in level 0).

3: Every node \(u\) that holds some coupons of \(v\) picks one coupon uniformly at random. Let \(C_0\) denote such a coupon and let \(x_0\) denote the number of coupons \(u\) has. Node \(u\) writes its ID on coupon \(C_0\).

4: for \(i = D\) down to 0 do

5: Every node \(u\) in level \(i\) that either receives coupon(s) from children or possesses coupon(s) itself do the following.

6: Let \(u\) have \(q\) coupons (including its own coupons). Denote these coupons by \(C_0, C_1, C_2, \ldots, C_{q-1}\) and let their counts be \(x_0, x_1, x_2, \ldots, x_{q-1}\). Node \(u\) samples one of \(C_0\) through \(C_{q-1}\), with probabilities proportional to the respective counts. That is, for any \(0 \leq j \leq q - 1\), \(C_j\) is sampled with probability \(\frac{x_j}{x_0 + x_1 + \ldots + x_{q-1}}\).

7: The sampled coupon is sent to the parent node (unless already at root) along with a count of \(x_0 + x_1 + \ldots + x_{q-1}\) (the count represents the number of coupons from which this coupon has been sampled).

8: end for

9: The root outputs the ID of the owner of the final sampled coupon (written on such a coupon).

have to prepare many walks from the center. In contrast, if we randomize the length of each short walk between two and three then the number of times that the center is a connector is \(\ell/4\) in expectation. (To see this, observe that, regardless of where the token started, the token will be forwarded to the center with probability \(1/2\).)

In the next section, we will show an important property which says that a random walk of length \(\ell = O(m^2)\) will visit each node \(v\) at most \(\tilde{O}(\sqrt{\ell \deg(v)})\) times. We then use this modification to claim that each node will be visited as a connector only \(\tilde{O}(\sqrt{\ell \deg(v)}/\lambda)\) times. This implies that each node does not have to prepare too many short walks, which leads to the improved running time.

To do this modification, we need to modify Phase 1 and \textsc{Send-More-Coupons}. For Phase 1, we simply change the length of each short walk to \(\lambda + r\) where \(r\) is a random integer in \([0, \lambda - 1]\). This modification is shown in Algorithm 3. A very slight change is also made on Phase 2. For a technical reason, we also prepare \(\eta \deg(v)\) coupons from each node in Phase 1, instead of previously \(\eta\) coupons. Our analysis in the next section shows that this modification still needs \(\tilde{O}(\eta \lambda)\) rounds as before.

To modify \textsc{Send-More-Coupons}, we add Part 2 to the algorithm (as in Algorithm 2) where we keep forwarding each coupon with some probability. It can be shown by a simple calculation that the number of steps each coupon is forwarded is uniformly between \(\lambda\) and \(2\lambda - 1\).

We now have the complete description of the algorithm (Algorithm 3) and are ready to show the analysis.

**3. Analysis of Single-Random-Walk**

We divide the analysis into four parts. First, we show the correctness of Algorithm \textsc{Single-Random-Walk}. (The proofs of the following lemmas will be shown in subsequent sections.)
ALGORITHM 2: SEND-MORE-COUPONS\((v, \eta, \lambda)\)

Part 1. Distribute \(\eta\) new coupons for \(\lambda\) steps.
1: The node \(v\) constructs \(\eta\) (identical) messages containing its ID. We refer to these messages new coupons.
2: \(\text{for } i = 1\text{ to } \lambda\text{ do}\)
3: Each node \(u\) does the following:
4: - For each new coupon \(C\) held by \(u\), node \(u\) picks a neighbor \(z\) uniformly at random as a receiver of \(C\).
5: - For each neighbor \(z\) of \(u\), node \(u\) sends the ID of \(v\) and the number of new coupons for which \(z\) is picked as a receiver, denoted by \(c(u, v)\).
6: - Each neighbor \(z\) of \(u\), upon receiving ID of \(v\) and \(c(u, v)\), constructs \(c(u, v)\) new coupons, each containing the ID of \(v\).
7: \(\text{end for}\)

Part 2. Each coupon has now been forwarded for \(\lambda\) steps. These coupons are now extended probabilistically further by \(r\) steps where each \(r\) is independent and uniform in the range \([0, \lambda - 1]\).
1: \(\text{for } i = 0\text{ to } \lambda - 1\text{ do}\)
2: For each coupon, independently with probability \(\frac{1}{\lambda - i}\), stop sending the coupon further and save the ID of the source node (in this event, the node with the message is the destination). For each coupon that is not stopped, each node picks a neighbor correspondingly and sends the coupon forward as before.
3: \(\text{end for}\)
4: At the end, each destination node knows the source ID as well as the number of times the corresponding coupon has been forwarded.

Lemma 3.1. Algorithm SINGLE-RANDOM-WALK solves 1-RW-DoS. That is, for any node \(v\), after algorithm SINGLE-RANDOM-WALK finishes, the probability that \(v\) outputs the ID of \(s\) is equal to the probability that it is the destination of a random walk of length \(\ell\) starting at \(s\).

Once we have established the correctness, we focus on the running time. In the second part, we show the probabilistic bound of Phase 1.

Lemma 3.2. Phase 1 finishes in \(\tilde{O}(\lambda \eta)\) rounds with high probability.

In the third part, we analyze the worst case bound of Phase 2, which is a building block of the probabilistic bound of Phase 2.

Lemma 3.3. Phase 2 finishes in \(\tilde{O}\left(\frac{\ell D}{\lambda} + \frac{\ell}{\eta}\right)\) rounds.

We note that this bound holds even when we fix the length of the short walks (instead of randomly picking from \([\lambda, 2\lambda]\)). Moreover, using these lemmas, we can conclude the (weaker) running time of \(\tilde{O}\left(\frac{\ell^2 D^{1/3}}{\lambda^{1/3}}\right)\) by setting \(\eta\) and \(\lambda\) appropriately, as follows.

Corollary 3.4. For any \(\ell\), Algorithm SINGLE-RANDOM-WALK (cf. Algorithm 3) solves 1-RW-DoS correctly and, with high probability, finishes in \(\tilde{O}\left(\frac{\ell^2 D^{1/3}}{\lambda^{1/3}}\right)\) rounds.

Proof. Set \(\eta = \ell^{1/3}/D^{1/3}\) and \(\lambda = \ell^{1/3}D^{2/3}\). Using Lemma 3.2 and 3.3, the algorithm finishes in \(\tilde{O}\left(\lambda \eta + \frac{D}{\lambda} + \frac{\ell}{\eta}\right) = \tilde{O}\left(\frac{\ell^2 D^{1/3}}{\lambda^{1/3}}\right)\) with high probability. \(\Box\)

In the last part, we improve the running time of Phase 2 further, using a probabilistic bound, leading to a better running time overall. The key ingredient here is the Random Walk Visits Lemma (cf. Lemma 3.12) stated formally in Section 3.4 and
proved in Section 3.5. Then, we use the fact that the short walks have random length to obtain the running time bound.

**Lemma 3.5.** For any $\eta$ and $\lambda$ such that $\eta \lambda \geq 32\sqrt{\eta} (\log n)^2$, Phase 2 finishes in $\tilde{O}\left(\frac{D}{\lambda}\right)$ rounds with high probability.

Using these results, we conclude the following theorem.

**Theorem 3.6.** For any $\ell$, Algorithm SINGLE-RANDOM-WALK (cf. Algorithm 3) solves 1-RW-DoS correctly and, with high probability, finishes in $\tilde{O}(\sqrt{\ell D})$ rounds.
PROOF. Set $\eta = 1$ and $\lambda = 32\sqrt{D}(\log n)^3$. Using Lemma 3.2 and 3.5, the algorithm finishes in $\tilde{O}\left(\lambda \eta + \frac{D}{\lambda}\right) = \tilde{O}(\sqrt{D})$ with high probability. \qed

3.1. Correction (Proof of Lemma 3.1)

In this section, we prove Lemma 3.1, which claims the correctness of the algorithm. Recall that the lemma is as follows.

**Lemma 3.1 (Restated).** Algorithm `SINGLE-RANDOM-WALK` solves `1-RW-DoS`. That is, for any node $v$, after algorithm `SINGLE-RANDOM-WALK` finishes, the probability that $v$ outputs the ID of $s$ is equal to the probability that it is the destination of a random walk of length $\ell$ starting at $s$.

To prove this lemma, we first claim that `SAMPLE-COUPON` returns a coupon where the node holding this coupon is a destination of a short walk of length uniformly random in $[\lambda, 2\lambda - 1]$.

**Claim 3.7.** Each short walk length (returned by `SAMPLE-COUPON`) is uniformly sampled from the range $[\lambda, 2\lambda - 1]$.

**Proof.** Each walk can be created in two ways.

— It is created in Phase 1. In this case, since we pick the length of each walk uniformly from the length $[\lambda, 2\lambda - 1]$, the claim clearly holds.

— It is created by `SEND-MORE-COUPON`. In this case, the claim holds by the technique of reservoir sampling [Vitter 1985]: Observe that after the $\lambda$th step of the walk is completed, we stop extending each walk at any length between $\lambda$ and $2\lambda - 1$ uniformly. To see this, observe that we stop at length $\lambda$ with probability $1/\lambda$. If the walk does not stop, it will stop at length $\lambda + 1$ with probability $\frac{1}{\lambda - 1}$. This means that the walk will stop at length $\lambda + 1$ with probability $\frac{\lambda - 1}{\lambda} \times \frac{1}{\lambda - 1} = \frac{1}{\lambda}$. Similarly, it can be argued that the walk will stop at length $i$ for any $i \in [\lambda, 2\lambda - 1]$ with probability $\frac{b_i}{a_i}$.

Moreover, we claim that `SAMPLE-COUPON(v)` samples a short walk uniformly at random among many coupons (and therefore, short walks starting at $v$).

**Claim 3.8.** Algorithm `SAMPLE-COUPON(v)` (cf. Algorithm 1), for any node $v$, samples a coupon distributed by $v$ uniformly at random.

**Proof.** Assume that before this algorithm starts, there are $t$ (without loss of generality, let $t > 0$) coupons containing ID of $v$ stored in some nodes in the network. The goal is to show that `SAMPLE-COUPON` brings one of these coupons to $v$ with uniform probability. For any node $u$, let $T_v$ be the subtree rooted at $u$ and let $S_u$ be the set of coupons in $T_u$. (Therefore, $T_v = T$ and $|S_u| = t$.)

We claim that any node $u$ returns a coupon to its parent with uniform probability (i.e., for any coupons $x \in S_u$, $\mathbb{P}[u$ returns $x] = 1/|S_u|$ (if $|S_u| > 0$)). We prove this by induction on the height of the tree. This claim clearly holds for the base case where $u$ is a leaf node. Now, for any non-leaf node $u$, assume that the claim is true for any of its children. To be precise, suppose that $u$ receives coupons and counts from $q - 1$ children. Assume that it receives coupons $d_1,d_2,...,d_{q-1}$ and counts $c_1,c_2,...,c_{q-1}$ from nodes $u_1,u_2,...,u_{q-1}$ respectively. (Also recall that $d_0$ is the sample of its own coupons (if exists) and $c_0$ is the number of its own coupons.) By induction, $d_j$ is sent from $u_j$ to $u$ with probability $1/|S_u|$, for any $0 \leq j \leq q - 1$. Moreover, $c_j = |S_{u_j}|$ for any $j$. Therefore, any coupon $d_j$ will be picked with probability $\frac{1}{|S_u|} \times \frac{c_j}{c_0 + c_1 + \ldots + c_{q-1}} = \frac{1}{|S_u|}$ as claimed.

The lemma follows by applying the claim above to $v$. \qed
The preceding two claims imply the correctness of the Algorithm Single-Random-Walk as shown next.

**Proof of Lemma 3.1.** Any two \([\lambda, 2\lambda − 1]\)-length walks (possibly from different sources) are independent from each other. Moreover, a walk from a particular node is picked uniformly at random. Therefore, algorithm Single-Random-Walk is equivalent to having a source node perform a walk of length between \(\lambda\) and \(2\lambda − 1\) and then have the destination do another walk of length between \(\lambda\) and \(2\lambda − 1\) and so on. That is, for any node \(v\), the probability that \(v\) outputs the ID of \(s\) is equal to the probability that it is the destination of a random walk of length \(\ell\) starting at \(s\).

\[ \square \]

**3.2. Analysis of Phase 1 (Proof of Lemma 3.2)**

In this section, we prove the performance of Phase 1 claimed in Lemma 3.2. Recall that the lemma is as follows.

**Lemma 3.2 (Restated).** Phase 1 finishes in \(O(\lambda n\eta)\) rounds with high probability.

We now prove the lemma. For each coupon \(C\), any \(j = 1, 2, \ldots, \lambda\), and any edge \(e\), we define \(X^j_C(e)\) to be a random variable having value 1 if \(C\) is sent through \(e\) in the \(j\)th iteration (i.e., when the counter on \(C\) is increased from \(j - 1\) to \(j\)). Let \(X^j(e) = \sum_{C\text{coupon}} X^j_C(e)\). We compute the expected number of coupons that go through an edge \(e\), as follows.

**Claim 3.9.** For any edge \(e\) and any \(j\), \(\mathbb{E}[X^j(e)] = 2\eta\).

**Proof.** Recall that each node \(v\) starts with \(\eta \deg(v)\) coupons and each coupon takes a random walk. We prove that after any given number of steps \(j\), the expected number of coupons at node \(v\) is still \(\eta \deg(v)\). Consider the random walk’s probability transition matrix, call it \(A\). In this case, \(Au = u\) for the vector \(u\) having value \(\frac{\deg(v)}{2m}\) where \(m\) is the number of edges in the graph (since this \(u\) is the stationary distribution of an undirected unweighted graph). Now the number of coupons we started with at any node \(i\) is proportional to its stationary distribution, therefore, in expectation, the number of coupons at any node remains the same.

To calculate \(\mathbb{E}[X^j(e)]\), notice that edge \(e\) will receive coupons from its two end points, say \(x\) and \(y\). The number of coupons it receives from node \(x\) in expectation is exactly the number of coupons at \(x\) divided by \(\deg(x)\). The claim follows. \(\square\)

By Chernoff’s bound (e.g., in Mitzenmacher and Upfal [2005, Theorem 4.4.]), for any edge \(e\) and any \(j\),

\[ \mathbb{P}[X^j(e) \geq 4\eta \log n] \leq 2^{-4\log n} = n^{-4}. \]

(We note that the number \(4\eta \log n\) above can be improved to \(c \eta \log n/ \log \log n\) for some constant \(c\). This improvement of \(\log \log n\) can be further improved as \(\eta\) increases. This fact is useful in practice but does not help improve our claimed running time since we always hide a polylog \(n\) factor.)

It follows that the probability that there exists an edge \(e\) and an integer \(1 \leq j \leq \lambda\) such that \(X^j(e) \geq 4\eta \log n\) is at most \(|E(G)|\lambda n^{-4} \leq \frac{1}{n}\) since \(|E(G)| \leq n^2\) and \(\lambda \leq \ell \leq n\) (by the way we define \(\lambda\)).

Now suppose that \(X^j(e) \leq 4\eta \log n\) for every edge \(e\) and every integer \(j \leq \lambda\). This implies that we can extend all walks of length \(i\) to length \(i + 1\) in \(4\eta \log n\) rounds. Therefore, we obtain walks of length \(\lambda\) in \(4\lambda \eta \log n\) rounds, with high probability, as claimed.
3.3. Worst-Case Bound of Phase 2 (Proof of Lemma 3.3)

In this section, we prove the worst-case performance of Phase 2 claimed in Lemma 3.3. Recall that the lemma is as follows.

**Lemma 3.3 (Restated).** Phase 2 finishes in $\tilde{O}\left(\frac{\ell D}{\lambda} + \frac{\ell}{\eta}\right)$ rounds.

We first analyze the running time of `SEND-MORE-COUPONS` and `SAMPLE-COUPON`.

**Lemma 3.10.** For any $v$, `SEND-MORE-COUPONS$(v, \eta, \lambda)$ always finishes within $O(\lambda)$ rounds.

**Proof.** Consider any node $u$ during the execution of the algorithm. If it contains $x$ coupons of $v$ (i.e., which just contain the ID of $v$), for some $x$, it has to pick $x$ of its neighbors at random, and pass the coupon of $v$ to each of these $x$ neighbors. It might pass these coupons to less than $x$ neighbors and cause congestion if the coupons are sent separately. However, it sends only the ID of $v$ and a count to each neighbor, where the count represents the number of coupons it wishes to send to such neighbor. Note that there is only one ID sent during the process since only one node calls `SEND-MORE-COUPONS` at a time. Therefore, there is no congestion and thus the algorithm terminates in $O(\lambda)$ rounds.

**Lemma 3.11.** `SAMPLE-COUPON` always finishes within $O(D)$ rounds.

**Proof.** Since, constructing a BFS tree can be done easily in $O(D)$ rounds, it is left to bound the time of the second part where the algorithm wishes to sample one of many coupons (having its ID) spread across the graph. The sampling is done while retracing the BFS tree starting from leaf nodes, eventually reaching the root. The main observation is that when a node receives multiple samples from its children, it only sends one of them to its parent. Therefore, there is no congestion. The total number of rounds required is therefore the number of levels in the BFS tree, $O(D)$.

Now we prove the worst-case bound of Phase 2. First, observe that `SAMPLE-COUPON` is called $O\left(\frac{\ell}{\eta}\right)$ times since it is called only by a connector (to find the next node to forward the token to). By Lemma 3.11, this algorithm takes $O\left(\frac{\ell D}{\lambda}\right)$ rounds in total. Next, we claim that `SEND-MORE-COUPONS` is called at most $O\left(\frac{\ell}{\lambda \eta}\right)$ times in total (summing over all nodes). This is because when a node $v$ calls `SEND-MORE-COUPONS$(v, \eta, \lambda)$`, all $\eta$ walks starting at $v$ must have been stitched and therefore $v$ contributes $\lambda \eta$ steps of walk to the long walk we are constructing. It follows from Lemma 3.10 that `SEND-MORE-COUPONS` algorithm takes $O\left(\frac{\ell}{\lambda}\right)$ rounds in total. The claimed worst-case bound follows by summing up the total running times of `SAMPLE-COUPON` and `SEND-MORE-COUPONS`.

3.4. A Probabilistic Bound for Phase 2 (Proof of Lemma 3.5)

In this section, we prove the high-probability time bound of Phase 2 claimed in Lemma 3.5. Recall that the lemma is as follows.

**Lemma 3.5 (Restated).** For any $\eta$ and $\lambda$ such that $\eta \lambda \geq 32 \sqrt{\ell} (\log n)^3$, Phase 2 finishes in $\tilde{O}\left(\frac{\ell^2}{\lambda}\right)$ rounds with high probability.

Recall that we may assume that $\ell = O(m^2)$ (cf. Observation 2.1). We prove the stronger bound using the following lemmas. As mentioned earlier, to bound the
number of times \textsc{Send-More-Coupons} is invoked, we need a technical result on random walks that bounds the number of times a node will be visited in a $\ell$-length random walk. Consider a simple random walk on a connected undirected graph on $n$ vertices. Let $\deg(x)$ denote the degree of $x$, and let $m$ denote the number of edges. Let $N^x_t(y)$ denote the number of visits to vertex $y$ by time $t$, given that the walk started at vertex $x$.

Now, consider $k$ walks, each of length $\ell$, starting from (not necessary distinct) nodes $x_1, x_2, \ldots, x_k$. We show a key technical lemma that applies to random walks on any (undirected) graph: With high probability, no vertex $y$ is visited more than $32 \deg(x) \sqrt{k\ell + 1} \log n + k$ times.

**Lemma 3.12 (Random Walk Visits Lemma).** For any nodes $x_1, x_2, \ldots, x_k$, and $\ell = O(m^2)$,

$$
P \left( \exists y \text{ such that } \sum_{i=1}^k N^x_i(y) \geq 32 \deg(x) \sqrt{k\ell + 1} \log n + k \right) \leq 1/n.
$$

Since the proof of this lemma is interesting on its own and lengthy, we defer it to Section 3.5. We note that one can also show a similar bound for a specific vertex, that is, $P \left( \exists y \text{ such that } \sum_{i=1}^k N^x_i(y) \geq 32 \deg(x) \sqrt{k\ell + 1} \log n + k \right)$. Since we will not use this bound here, we defer it to Lemma 3.18 in Section 3.5. Moreover, we prove the above lemma only for a specific number of visits of roughly $\sqrt{k\ell}$ because this is the expected number of visits (we show this in Proposition 3.16 in Section 3.5). It might be possible to prove more general bounds; however, we do not include them here since they need more proofs and are not relevant to the results of this article.

Also note that Lemma 3.12 is not true if we do not restrict $\ell$ to be $O(m^2)$. For example, consider a star network and a walk of length $\ell$ such that $\ell \gg n^2$ and $\ell$ is larger than the mixing time. In this case, this walk will visit the center of the star $\Omega(\ell)$ times with high probability. This contradicts Lemma 3.12 which says that the center will be visited $O(n\sqrt{\ell}) = o(\ell)$ times with high probability. We can modify the statement of Lemma 3.12 to hold for a general value of $\ell$ as follows (this fact is not needed in this paper): $P \left( \exists y \text{ such that } \sum_{i=1}^k N^x_i(y) \geq 32 \deg(x) \sqrt{k\ell + 1} \log n + k + \ell \deg(x)/m \right) \leq 1/n$. (Recall that $m$ is the number of edges in the network.) This inequality can be proved using Lemma 3.12 and the fact that $m^2$ is larger than the mixing time, which means that the walk will visit vertex $x$ with probability $\deg(x)/m$ in each step after the $(m^2)$th step.

Lemma 3.12 says that the number of visits to each node can be bounded. However, for each node, we are only interested in the case where it is used as a connector. The lemma below shows that the number of visits as a connector can be bounded as well; that is, if any node $v_i$ appears $t$ times in the walk, then it is likely to appear roughly $t/\lambda$ times as connectors.

**Lemma 3.13.** For any vertex $v$, if $v$ appears in the walk at most $t$ times, then it appears as a connector node at most $t(\log n)^2/\lambda$ times with probability at least $1 - 1/n^2$.

At first thought, Lemma 3.13 might sound correct even when we do not randomize the length of the short walks since the connectors are spread out in steps of length approximately $\lambda$. However, there might be some periodicity that results in the same node being visited multiple times but exactly at $\lambda$-intervals. (As we described earlier, one example is when the input network is a star graph and $\lambda = 2$.) This is where we crucially
use the fact that the algorithm uses walks of length uniformly random in \([\lambda, 2\lambda - 1]\).

The proof then goes via constructing another process equivalent to partitioning the \(t\) steps into intervals of \(\lambda\) and then sampling points from each interval. We analyze this by constructing a different process that stochastically dominates the process of a node occurring as a connector at various steps in the \(t\)-length walk and then use a Chernoff bound argument.

In order to give a detailed proof of Lemma 3.13, we need the following two claims.

**Claim 3.14.** Consider any sequence \(A\) of numbers \(a_1, \ldots, a_{\ell'}\) of length \(\ell'\). For any integer \(\lambda'\), let \(B\) be a sequence \(a_{i' + 1}, a_{i' + 2}, \ldots, a_{i' + \ell'}\) where \(r_i\) for any \(i\), is a random integer picked uniformly from \([0, \lambda' - 1]\). Consider another subsequence of numbers \(C\) of \(A\) where an element in \(C\) is picked from “every \(\lambda'\) numbers” in \(A\); that is, \(C\) consists of \([\ell' / \lambda']\) numbers \(c_1, c_2, \ldots\) where, for any \(i\), \(c_i\) is chosen uniformly at random from \(a_{i(i-1)\lambda'+1}, a_{i(i-1)\lambda'+2}, \ldots, a_{i\lambda'}\). Then, \(\mathbb{P}[C\text{ contains } \{a_{i_1}, a_{i_2}, \ldots, a_{i_k}\}] = \mathbb{P}[B = \{a_{i_1}, a_{i_2}, \ldots, a_{i_k}\}]\) for any set \(\{a_{i_1}, a_{i_2}, \ldots, a_{i_k}\}\).

**Proof.** Observe that \(B\) will be equal to \(\{a_{i_1}, a_{i_2}, \ldots, a_{i_k}\}\) only for a specific value of \(r_1, r_2, \ldots, r_k\). Since each of \(r_1, r_2, \ldots, r_k\) is chosen uniformly at random from \([1, \lambda']\), \(\mathbb{P}[B = \{a_{i_1}, a_{i_2}, \ldots, a_{i_k}\}] = \lambda'^{-k}\). Moreover, the \(C\) will contain \(a_{i_1}, a_{i_2}, \ldots, a_{i_k}\) if and only if, for each \(j\), we pick \(a_{i_j}\) from the interval that contains it (i.e., from \(a_{(i-1)\lambda'+1}, a_{(i-1)\lambda'+2}, a_{i\lambda'}\), for some \(i\)). (Note that \(a_{i_1}, a_{i_2}, \ldots\) are all in different intervals because \(i_{j+1} - i_j \geq \lambda'\) for all \(j\)). Therefore, \(\mathbb{P}[C\text{ contains } a_{i_1}, a_{i_2}, \ldots, a_{i_k}] = \lambda'^{-k}\). \(\Box\)

**Claim 3.15.** Consider any sequence \(A\) of numbers \(a_1, \ldots, a_{\ell'}\) of length \(\ell'\). Consider subsequence of numbers \(C\) of \(A\) where an element in \(C\) is picked from “every \(\lambda'\) numbers” in \(A\); that is, \(C\) consists of \([\ell' / \lambda']\) numbers \(c_1, c_2, \ldots\) where, for any \(i\), \(c_i\) is chosen uniformly at random from \(a_{(i-1)\lambda'+1}, a_{(i-1)\lambda'+2}, \ldots, a_{i\lambda'}\). For any number \(x\), let \(n_x\) be the number of appearances of \(x\) in \(C\); that is, \(n_x = |\{i \mid a_i = x\}|\). Then, for any \(R \geq 6n_{x/\lambda'}\), \(x\) appears in \(C\) more than \(R\) times with probability at most \(2^{-R}\).

**Proof.** For \(i = 1, 2, \ldots, [\ell' / \lambda']\), let \(X_i\) be a 0/1 random variable that is 1 if and only if \(c_i = x\) and \(X = \sum_{i=1}^{[\ell' / \lambda']} X_i\). That is, \(X\) is the number of appearances of \(x\) in \(C\). Clearly, \(E[X] = n_x/\lambda'\). Since \(X_i’s\) are independent, we can apply the Chernoff bound (e.g., in Mitzenmacher and Upfal [2005, Theorem 4.4.1]): For any \(R \geq 6E[X] = 6n_{x/\lambda'}\), \(\mathbb{P}[X \leq R] \geq 2^{-R}\).

The claim is thus proved. \(\Box\)

**Proof of Lemma 3.13.** Now we use the claims to prove the lemma. Choose \(\ell' = \ell\) and \(\lambda' = \lambda\) and consider any node \(v\) that appears at most \(t\) times. The number of times it appears as a connector node is the number of times it appears in the subsequence \(B\) described in Claim 3.14. By applying Claim 3.14 and 3.15 with \(R = t(\log n)^2\), we have that \(v\) appears in \(B\) more than \(t(\log n)^2\) times with probability at most \(1/n^2\) as desired. \(\Box\)

Now we are ready to prove the probabilistic bound of Phase 2 (cf. Lemma 3.5).

First, we claim, using Lemma 3.12 and 3.13, that each node is used as a connector node at most \(32\deg(x)\sqrt{\ell(\log n)^3} \lambda / x\) times with probability at least \(1 - 2/n\). To see this, observe that the claim holds if each node \(x\) is visited at most \(t(x) = 32\deg(x)\sqrt{\ell + 1} \log n\) times and consequently appears as a connector node at most \(t(x)(\log n)^2 / \lambda\) times. By Lemma 3.12, the first condition holds with probability at least \(1 - 1/n\). By Lemma 3.13 and the union bound over all nodes, the second condition holds with probability at
least $1 - 1/n$, provided that the first condition holds. Therefore, both conditions hold together with probability at least $1 - 2/n$ as claimed.

Now, observe that SAMPLE-COUPON is invoked $O \left( \frac{\ell}{\lambda} \right)$ times (only when we stitch the walks) and therefore, by Lemma 3.11, contributes $O \left( \frac{D}{\lambda} \right)$ rounds. Moreover, we claim that SEND-MORE-COUPONS is never invoked, with probability at least $1 - 2/n$. To see this, recall our previous claim that each node $x$ is used as a connector node at most $32 \deg(x) \sqrt{\ell (\log n)}$ times. Additionally, observe that we have prepared this many walks in Phase 1; that is, after Phase 1, each node has $\eta \deg(x) \geq 32 \deg(x) \sqrt{\ell (\log n)}$ short walks. The claim follows.

Therefore, with probability at least $1 - 2/n$, the rounds are $\tilde{O} \left( \frac{D}{\lambda} \right)$ as claimed.

3.5. Proof of Random Walk Visits Lemma (cf. Lemma 3.12)

In this section, we prove the Random Walk Visits Lemma introduced in the previous section. We restated it here for the sake of readability.

**Lemma 3.12 (Random Walk Visits Lemma, Restated).** For any nodes $x_1, x_2, \ldots, x_k$, and $\ell = O \left( m^2 \right)$,

$$
\mathbb{P} \left( \exists y \text{ such that } \sum_{i=1}^{k} N^{x_i}_t(y) \geq 32 \deg(x) \sqrt{k \ell + 1} \log n + k \right) \leq 1/n.
$$

We start with the bound of the first moment of the number of visits at each node by each walk.

**Proposition 3.16.** For any node $x$, node $y$ and $t = O \left( m^2 \right)$,

$$
\mathbb{E} \left[ N^x_t(y) \right] \leq 8 \deg(y) \sqrt{t + 1}.
$$

To prove this proposition, let $P$ denote the transition probability matrix of such a random walk and let $\pi$ denote the stationary distribution of the walk, which in this case is simply proportional to the degree of the vertex, and let $\pi_{\text{min}} = \min_x \pi(x)$.

The basic bound we use is the following estimate from Lyons (see Lemma 3.4 and Remark 4 in Lyons [2005]). Let $Q$ denote the transition probability matrix of a chain with self-loop probability $\alpha > 0$, and with $c = \min \{ \pi(x)Q(x,y) : x \neq y \text{ and } Q(x,y) > 0 \}$. Note that for a random walk on an undirected graph, $c = \frac{1}{2m}$. For $k > 0$, a positive integer (denoting time),

$$
\left| \frac{Q^k(x,y)}{\pi(y)} - 1 \right| \leq \min \left\{ \frac{1}{ac \sqrt{k + 1}}, \frac{1}{2a^2c^2(k + 1)} \right\}.
$$

For $k \leq \beta m^2$ for a sufficiently small constant $\beta$, and small $\alpha$, this can be simplified to the following bound (we use Observation 2.1 here); see Remark 3 in Lyons [2005].

$$
Q^k(x,y) \leq \frac{4\pi(y)}{c \sqrt{k + 1}} = \frac{4 \deg(y)}{\sqrt{k + 1}}.
$$

Note that given a simple random walk on a graph $G$, and a corresponding matrix $P$, one can always switch to the lazy version $Q = (I + P)/2$, and interpret it as a walk on graph $G'$, obtained by adding self-loops to vertices in $G$ so as to double the degree of each vertex. In the following, with abuse of notation, we assume our $P$ is such a lazy version of the original one.
Proof of Proposition 3.16. Let $X_0, X_1, \ldots$ describe the random walk, with $X_i$ denoting the position of the walk at time $i \geq 0$, and let $1_A$ denote the indicator $(0–1)$ random variable, which takes the value 1 when the event $A$ is true. In the following, we also use the subscript $x$ to denote the fact that the probability or expectation is with respect to starting the walk at vertex $x$. We get the expectation.

$$\mathbb{E}\left[N^x_t(y)\right] = \mathbb{E}_x\left[\sum_{i=0}^{t} 1_{\{X_i=y\}}\right] = \sum_{i=0}^{t} P^x(x, y)$$

$$\leq 4 \deg(y) \sum_{i=0}^{t} \frac{1}{\sqrt{i + 1}}, \quad \text{(using the above inequality (3))}$$

$$\leq 8 \deg(y) \sqrt{t} + 1.$$  

Using Proposition 3.16, we bound the number of visits of each walk at each node, as follows.

**Lemma 3.17.** For $t = O(m^2)$ and any vertex $y \in G$, the random walk started at $x$ satisfies:

$$\mathbb{P}\left(N^x_t(y) \geq 32 \deg(y) \sqrt{t + 1} \log n\right) \leq \frac{1}{n^2}.$$  

**Proof.** First, it follows from the Proposition and Markov’s inequality that

$$\mathbb{P}\left(N^x_t(y) \geq 4 \cdot 8 \deg(y) \sqrt{t + 1}\right) \leq \frac{1}{4}. \quad (4)$$

For any $r$, let $L^x_r(y)$ be the time that the random walk (started at $x$) visits $y$ for the $r$th time. Observe that, for any $r$, $N^x_t(y) \geq r$ if and only if $L^x_r(y) \leq t$. Therefore,

$$\mathbb{P}\left(N^x_t(y) \geq r\right) = \mathbb{P}\left(L^x_r(y) \leq t\right). \quad (5)$$

Let $r^* = 32 \deg(y) \sqrt{t + 1}$. By (4) and (5), $\mathbb{P}\left(L^x_{r^*}(y) \leq t\right) \leq \frac{1}{4}$. We claim that

$$\mathbb{P}\left(L^x_{r^* \log n}(y) \leq t\right) \leq \left(\frac{1}{4}\right)^{\log n} = \frac{1}{n^2}. \quad (6)$$

To see this, divide the walk into $\log n$ independent subwalks, each visiting $y$ exactly $r^*$ times. Since the event $L^x_{r^* \log n}(y) \leq t$ implies that all subwalks have length at most $t$, (6) follows. Now, by applying (5) again,

$$\mathbb{P}\left(N^x_t(y) \geq r^* \log n\right) = \mathbb{P}\left(L^x_{r^* \log n}(y) \leq t\right) \leq \frac{1}{n^2}$$

as desired.  

We now extend Lemma 3.17 to bound the number of visits of all the walks at each particular node.

**Lemma 3.18 (Random Walk Visits Lemma for a Specific Vertex).** For $\gamma > 0$, and $t = O(m^2)$, and for any vertex $y \in G$, the random walk started at $x$ satisfies:

$$\mathbb{P}\left(\sum_{i=1}^{k} N^x_{\gamma i}(y) \geq 32 \deg(y) \sqrt{kt + 1} \log n + k\right) \leq \frac{1}{n^2}.$$
To see this, we construct a walk \( W \) of length \( kt \) starting at \( y \) in the following way: For each \( i \), denote a walk of length \( t \) starting at \( x_i \) by \( W_i \). Let \( \tau_i \) and \( \tau'_i \) be the first and last time (not later than time \( t \)) that \( W_i \) visits \( y \). Let \( W'_i \) be the subwalk of \( W_i \) from time \( \tau_i \) to \( \tau'_i \). We construct a walk \( W \) by stitching \( W'_1, W'_2, \ldots, W'_k \) together and complete the rest of the walk (to reach the length \( kt \)) by a normal random walk. It then follows that the number of visits to \( y \) by \( W_1, W_2, \ldots, W_k \) (excluding the starting step) is at most the number of visits to \( y \) by \( W \). The first quantity is \( \sum_{i=1}^{k} N^i(y) \). The second quantity is \( N_k(y) \). The observation thus follows.

Therefore, \[ \mathbb{P} \left( \sum_{i=1}^{k} N^i(y) \geq 32 \deg(y) \sqrt{kt} + 32 \log n + k \right) \leq \mathbb{P} \left( N_k(y) \geq 32 \deg(y) \sqrt{kt} + 3 \log n \right) \leq \frac{1}{n^2} \text{ where the last inequality follows from Lemma 3.17.} \]

The Random Walk Visits Lemma (cf. Lemma 3.12) follows immediately from Lemma 3.18 by union bounding over all nodes.

4. VARIATIONS, EXTENSIONS, AND GENERALIZATIONS

4.1. Computing \( k \) Random Walks

We now consider the scenario when we want to compute \( k \) walks of length \( \ell \) from different (not necessary distinct) sources \( s_1, s_2, \ldots, s_k \). We show that SINGLE-RANDOM-WALK can be extended to solve this problem. Consider the following algorithm.

**Many-Random-Walks.** Let \( \lambda = (32 \sqrt{kD} + 3 \log n + k)(\log n)^2 \) and \( \eta = 1 \). If \( \lambda > \ell \), then run the naive random walk algorithm, that is, the sources find walks of length \( \ell \) simultaneously by sending tokens. Otherwise, do the following. First, modify Phase 2 of SINGLE-RANDOM-WALK to create multiple walks, one at a time; that is, in the second phase, we stitch the short walks together to get a walk of length \( \ell \) starting at \( s_1 \), then do the same thing for \( s_2, s_3, \) and so on.

The correctness of MANY-RANDOM-WALKs follows from Lemma 3.1; intuitively, this algorithm outputs independent random walks because it obtains long walks by stitching short walks that are all independent (no short walk is used twice). We now prove the running time of this algorithm.

**Theorem 4.1.** MANY-RANDOM-WALKS finishes in \( \tilde{O}(\min (\sqrt{kD} + k, k + \ell)) \) rounds with high probability.

**Proof.** First, consider the case where \( \lambda > \ell \). In this case, \( \min (\sqrt{kD} + k, \sqrt{kD} + k + \ell) = \tilde{O}(\sqrt{kD} + k + \ell) \). By Lemma 3.12, each node \( x \) will be visited at most \( \tilde{O}(\deg(x)(\sqrt{kD} + k)) \) times. Therefore, using the same argument as Lemma 3.2, the congestion is \( \tilde{O}(\sqrt{kD} + k) \) with high probability. Since the dilation is \( \ell \), MANY-RANDOM-WALKs takes \( \tilde{O}(\sqrt{kD} + k + \ell) \) rounds as claimed. Since \( 2\sqrt{kD} \leq k + \ell \), this bound reduces to \( \tilde{O}(k + \ell) \).

Now, consider the other case where \( \lambda \leq \ell \). In this case, \( \min (\sqrt{kD} + k, \sqrt{kD} + k + \ell) = \tilde{O}(\sqrt{kD} + k) \). Phase 1 takes \( \tilde{O}(\lambda, \eta) = \tilde{O}(\sqrt{kD} + k) \). The stitching in Phase 2 takes
\( \tilde{O}(kD/\lambda) = \tilde{O}(\sqrt{kD}) \). Moreover, by Lemma 3.12, \textsc{send-more-coupons} will never be invoked. Therefore, the total number of rounds is \( \tilde{O}(\sqrt{kD} + k) \) as claimed. 

4.2. Regenerating the Entire Random Walk

Our algorithm can be extended to regenerate the entire walk, solving \( k \)-RW-pos. This will be used, for example, in generating a random spanning tree. The algorithm is the following. First, inform all intermediate connecting nodes of their position which can be done by keeping track of the walk length when we do token forwarding in Phase 2. Then, these nodes can regenerate their \( O(\sqrt{\ell}) \) length short walks by simply sending a message through each of the corresponding short walks. This can be completed in \( \tilde{O}(\sqrt{\ell D}) \) rounds with high probability. This is because, with high probability, \textsc{send-more-coupons} will not be invoked and hence all the short walks are generated in Phase 1. Sending a message through each of these short walks (in fact, sending a message through every short walk generated in Phase 1) takes time at most the time taken in Phase 1, that is, \( \tilde{O}(\sqrt{\ell D}) \) rounds.

4.3. Generalization to the Metropolis-Hastings Algorithm

We now discuss extensions of our algorithm to perform a random walk according to the Metropolis-Hastings algorithm, a more general type of random walk with numerous applications (e.g., Zhong and Shen [2006]). The Metropolis-Hastings [Hastings 1970; Metropolis et al. 1953] algorithm gives a way to define a transition probability so that a random walk converges to any desired distribution \( \pi \) (where \( \pi_i \), for any node \( i \), is the desired stationary probability at node \( i \)). It is assumed that every node \( i \) knows its steady state probability \( \pi_i \) (and can know its neighbors' steady state probabilities in one round).

The Metropolis-Hastings algorithm is roughly as follows (see, e.g., Hastings [1970] and Metropolis et al. [1953] for the full description). For any desired distribution \( \pi \) and any desired laziness factor \( 0 < \alpha < 1 \), the transition probability from node \( i \) to its neighbor \( j \) is defined to be

\[
P_{ij} = \alpha \min \left( \frac{1}{d_i}, \frac{\pi_j}{\pi_i d_j} \right),
\]

where \( d_i \) and \( d_j \) are degree of \( i \) and \( j \) respectively. It can be shown that a random walk with this transition probability converges to \( \pi \).

Using the transition probability defined here, we now run the \textsc{single-random-walk} algorithm with one modification: in Phase 1, we generate

\[
\eta \cdot \frac{\pi(x)}{\alpha \min_x \frac{\pi(x)}{\deg(x)}}
\]

short walks instead of \( \eta \deg(v) \).

The correctness of the algorithm follows from Lemma 3.1. The running time follows from the following theorem.

**Theorem 4.2.** For any \( \eta \) and \( \lambda \) such that \( \eta\lambda \geq 32\sqrt{\ell}(\log n)^3 \), the modified \textsc{single-random-walk} algorithm stated previously finishes in

\[
\tilde{O} \left( \lambda \eta \cdot \frac{\max_x \pi(x)/\deg(x)}{\min_y \pi(y)/\deg(y)} + \frac{\ell D}{\lambda} \right)
\]

rounds with high probability.

An interesting application of Theorem 4.2 is when \( \pi \) is a stationary distribution. In this case, we can compute a random walk of length \( \ell \) in \( \tilde{O}(\lambda \eta + \ell D/\lambda) \) rounds which is
exactly Theorem 3.6. Like Theorem 3.6, Theorem 4.2 follows from the following two lemmas, which are similar to Lemmas 3.2 and 3.5.

**Lemma 4.3.** For any \( \pi \) and \( \alpha \), Phase 1 finishes in \( O\left(\lambda \eta \log n \cdot \frac{\max_x \pi(x)/\deg(x)}{\min_y \pi(y)/\deg(y)}\right) \) rounds with high probability.

**Proof.** The proof is essentially the same as Lemma 3.2. We present it here for completeness. Let \( \beta = \frac{1}{\alpha \min_x \frac{\pi(x)}{\deg(x)}} \). Consider the case when each node \( i \) creates \( \beta \pi(i)_\eta \) messages. We show that the lemma holds even in this case.

We use the same definition as in Lemma 3.2. That is, for each message \( M \), any \( j = 1, 2, ..., \lambda \), and any edge \( e \), we define \( X_j(e) \) to be a random variable having value 1 if \( M \) is sent through \( e \) in the \( j \)th iteration (i.e., when the counter on \( M \) has value \( j - 1 \)). Let \( X_j(e) = \sum_M: \text{message} \ X_j(e) \). We compute the expected number of messages that go through an edge. As before, we show the following claim.

**Claim 4.4.** For any edge \( e \) and any \( j \), \( \mathbb{E}[X_j(e)] = 2\eta \cdot \frac{\max_x \pi(x)/\deg(x)}{\min_y \pi(y)/\deg(y)} \).

**Proof.** Assume that each node \( v \) starts with \( \beta \pi(v)_\eta \) messages. Each message takes a random walk. We prove that after any given number of steps \( j \), the expected number of messages at node \( v \) is still \( \beta \pi(v)_\eta \). Consider the random walk's probability transition matrix, say \( A \). In this case \( Au = u \) for the vector \( u \) having value \( \pi(v) \) (since this \( \pi(v) \) is the stationary distribution). Now the number of messages we started with at any node \( i \) is proportional to its stationary distribution, therefore, in expectation, the number of messages at any node remains the same.

To calculate \( \mathbb{E}[X_j(e)] \), notice that edge \( e \) will receive messages from its two end points, say \( x \) and \( y \). The number of messages it receives from node \( x \) in expectation is exactly \( \beta \pi(x)_\eta \times \alpha \min \left( \frac{1}{d_x}, \frac{\pi(y)}{\pi(x)} \right) \leq \eta \cdot \frac{\pi(x)/\deg(x)}{\min_y \pi(y)/\deg(y)} \). The claim follows.

The high-probability analysis follows the same way as the analysis of Lemma 3.2.

**Lemma 4.5.** For any \( \eta \) and \( \lambda \) such that \( \eta \lambda \geq 32 \sqrt{\ell} (\log n)^3 \), Phase 2 finishes in \( \tilde{O}\left(\frac{\lambda}{\eta} \right) \) rounds with high probability.

**Proof (sketched).** We first prove a result similar to Proposition 3.16

**Claim 4.6.** For any node \( x \), node \( y \) and \( t = O(m^2) \),

\[
\mathbb{E}[N_t^x(y)] \leq \frac{8\pi(y)\sqrt{t + 1}}{\min_x \pi(x)/\deg(x)}.
\]

**Proof.** The proof is similar to the proof of Lemma 3.16 except that

\[
c = \alpha \min_x \pi(x)/\deg(x).
\]
It follows that
\[
\mathbb{E}[N_t^x(y)] = \mathbb{E}\left[ \sum_{i=0}^{t} \mathbf{1}_{(X_i = y)} \right] = \sum_{i=0}^{t} P_t(x, y) \leq \frac{4\pi(y)}{c} \sum_{i=0}^{t} \frac{1}{\sqrt{i+1}}, \quad \text{(using inequality (3))}
\]
\[
\leq \frac{8\pi(y)\sqrt{t+1}}{\alpha \min_x \pi(x)/\deg(x)}.
\]

By following the rest of the proof of Lemma 3.12, we conclude the following.

**Claim 4.7.** For any nodes \(x_1, x_2, \ldots, x_k\), and \(\ell = O(m^2)\),
\[
P\left( \exists y \text{ such that } \sum_{i=1}^{k} N_{i\ell}^x(y) \geq 32 \frac{\pi(y)}{\alpha \min_x \pi(x)/\deg(x)} \sqrt{\ell + 1\log n + k} \right) \leq \frac{1}{n}. \]

Following the proof of Lemma 3.5, we have that each node \(y\) is used as a connector at most
\[
32 \left( \frac{\pi(y)}{\alpha \min_x \pi(x)/\deg(x)} \right) \sqrt{\ell (\log n)^3}
\]
times with probability at least \(1 - 2/n\). Additionally, observe that we have prepared this many walks in Phase 1; that is, after Phase 1, each node \(x\) has
\[
\eta \cdot \frac{\pi(x)}{\alpha \min_x \pi(x)/\deg(x)} \geq \frac{32 \left( \frac{\pi(x)}{\alpha \min_x \pi(y)/\deg(y)} \right) \sqrt{\ell (\log n)^3}}{\lambda}
\]
short walks. The claim follows. \(\square\)

### 4.4. \(k\) Walks where Sources Output Destinations (\(k\)-RW-SoD)

In this section, we extend our results to \(k\)-RW-SoD using the following lemma.

**Lemma 4.8.** Given an algorithm that solves \(k\)-RW-DoS in \(O(S)\) rounds, for any \(S\), one can extend the algorithm to solve \(k\)-RW-SoD in \(O(S + k + D)\) rounds.

The idea of this lemma is to construct a BFS tree and have each destination node send its ID to the corresponding source via the root. By using upcast and downcast algorithms [Peleg 2000], this can be done in \(O(k + D)\) rounds.

**Proof.** Let the algorithm that solves \(k\)-RW-DoS perform one walk each from source nodes \(s_1, s_2, \ldots, s_k\). Let the destinations that output these sources be \(d_1, d_2, \ldots, d_k\) respectively. This means that for each \(1 \leq i \leq k\), node \(\deg(x)\) has the ID of source \(s_i\). To prove the lemma, we need a way for each \(\deg(x)\) to communicate its own ID to \(s_i\) respectively, in \(O(k + D)\) rounds. The simplest way to do this is for each node ID pair \((\deg(x), s_i)\) to be communicated to some fixed node \(r\), and then for \(r\) to communicate this information to the sources \(s_i\). This is done by \(r\) constructing a BFS tree rooted at itself. This step takes \(O(D)\) rounds. Now, each destination \(\deg(x)\) sends its pair \((\deg(x), s_i)\) up this tree to the root \(r\). This can be done in \(O(D + k)\) rounds using an upcast algorithm [Peleg 2000]. Node \(r\) then uses the same BFS tree to route back the pairs to the appropriate sources. This again takes \(O(D + k)\) rounds using a downcast algorithm [Peleg 2000]. \(\square\)
Applying Theorem 4.1 and Lemma 4.8, the following theorem follows.

**THEOREM 4.9.** Given a set of \( k \) sources, one can perform \( k \)-RW-SoD after random walks of length \( \ell \) in \( \tilde{O}(\sqrt{k\ell D} + D + k) \) rounds.

5. APPLICATIONS

In this section, we present two applications of our algorithm.

5.1. A Distributed Algorithm for Random Spanning Tree

We now present an algorithm for generating a random spanning tree (RST) of an unweighted undirected network in \( \tilde{O}(\sqrt{mD}) \) rounds with high probability. The approach is to simulate Aldous and Broder's [Aldous 1990; Broder 1989] RST algorithm, which is as follows. First, pick one arbitrary node as a root. Then, perform a random walk from the root node until all nodes are visited. For each nonroot node, output the edge that is used for its first visit. (That is, for each nonroot node \( v \), if the first time \( v \) is visited is \( t \), then we output the edge \((u, v)\) where \( u \) is the node visited at time \( t - 1 \).) The output edges clearly form a spanning tree and this spanning tree is shown to come from a uniform distribution among all spanning trees of the graph [Aldous 1990; Broder 1989].

The running time of this algorithm is bounded by the time to visit all the nodes of the graph that can be shown to be \( \tilde{O}(mD) \) (in the worst case, that is, for any undirected, unweighted graph) by Aleliunas et al. [1979].

This algorithm can be simulated on the distributed network by our random walk algorithm as follows. The algorithm can be viewed in phases. Initially, we pick a root node arbitrarily and set \( \ell = n \). In each phase, we run \( \log n \) (different) walks of length \( \ell \) starting from the root node (this takes \( \tilde{O}(\sqrt{D}) \) rounds using our distributed random walk algorithm). If none of the \( O(\log n) \) different walks cover all nodes (this can be easily checked in \( O(D) \) time), we double the value of \( \ell \) and start a new phase, that is, perform again \( \log n \) walks of length \( \ell \). The algorithm continues until one walk of length \( \ell \) covers all nodes. We then use such walk to construct a random spanning tree: As the result of this walk, each node knows its position(s) in the walk (cf. Section 3), that is, it has a list of steps in the walk that it is visited. Therefore, each nonroot node can pick an edge that is used in its first visit by communicating to its neighbors. Thus at the end of the algorithm, each node can know which of its adjacent edges belong to the output tree. (An additional \( O(n) \) rounds may be used to deliver the resulting tree to a particular node if needed.)

We now analyze the number of rounds in term of \( \tau \), the expected cover time of the input graph. The algorithm takes \( O(\log \tau) \) phases before \( 2\tau \leq \ell \leq 4\tau \), and since one of \( \log n \) random walks of length \( 2\tau \) will cover the input graph with high probability, the algorithm will stop with \( \ell \leq 4\tau \) with high probability. Since each phase takes \( \tilde{O}(\sqrt{D}) \) rounds, the total number of rounds is \( \tilde{O}(\sqrt{D}) \) with high probability. Since \( \tau = \tilde{O}(mD) \), we have the following theorem.

**THEOREM 5.1.** The algorithm described here generates a uniform random spanning tree in \( \tilde{O}(\sqrt{mD}) \) rounds with high probability.

5.2. Decentralized Estimation of Mixing Time

We now present an algorithm to estimate the mixing time of a graph from a specified source. Throughout this section, we assume that the graph is connected and non-bipartite (the conditions under which mixing time is well defined). The main idea in estimating the mixing time is, given a source node, to run many random walks of
length \( \ell \) using the approach described in the previous section, and use these to estimate the distribution induced by the \( \ell \)-length random walk. We then compare the distribution at length \( \ell \), with the stationary distribution to determine if they are close, and if not, double \( \ell \) and retry. For this approach, one issue that we need to address is how to compare two distributions with few samples efficiently (a well-studied problem). We introduce some definitions before formalizing our approach and theorem.

**Definition 5.2 (Distribution Vector).** Let \( \pi_x(t) \) define the probability distribution vector reached after \( t \) steps when the initial distribution starts with probability 1 at node \( x \). Let \( \pi \) denote the stationary distribution vector.

**Definition 5.3 (\( \tau^x(\delta) \) (\( \delta \)-Near Mixing Time), and \( \tau^x_{\text{mix}} \) (Mixing Time) for Source \( x \)).** Define \( \tau^x(\delta) = \min t : ||\pi_x(t) - \pi||_1 < \delta \). Define \( \tau^x_{\text{mix}} = \tau^x(1/2\epsilon) \).

The goal is to estimate \( \tau^x_{\text{mix}} \). Notice that the definitions of \( \tau^x(\delta) \) and \( \tau^x_{\text{mix}} \) are consistent due to the following standard monotonicity property of distributions.

**LEMMA 5.4.** \( ||\pi_x(t + 1) - \pi||_1 \leq ||\pi_x(t) - \pi||_1 \).

**PROOF.** We need to show that the definition of mixing times are consistent, that is, monotonic in \( t \) the number of steps of the random walk. This is folklore but for completeness, we show this via simple linear algebra and the definition of distributions. Let \( A \) denote the transpose of the transition probability matrix of the graph being considered. That is, \( A(i,j) \) denotes the probability of transitioning from node \( j \) to node \( i \). Further, let \( x \) denote any probability vector. Now notice that we have \( ||Ax||_1 \leq ||x||_1 \); this follows from the fact that the sum of entries of any column of \( A \) is 1 (since it is a Markov chain), and the sum of entries of the vector \( x \) is 1 (since it is a probability distribution vector).

Now let \( \pi \) be the stationary distribution of the graph corresponding to \( A \). This implies that if \( \ell \) is \( \delta \)-near mixing, then \( ||A^\ell u - \pi||_1 \leq \delta \), by the definition of \( \delta \)-near mixing time. Now consider \( ||A^{\ell+1} u - \pi||_1 \). This is equal to \( ||A^{\ell+1} u - A\pi||_1 \) since \( A\pi = \pi \). However, this reduces to \( ||A^\ell (u - \pi)||_1 \leq \delta \) (which again follows from the fact that \( A \) is stochastic). It follows that \( (\ell + 1) \) is \( \delta \)-near mixing.

To compare two distributions, we use the technique of Batu et al. [2001] to determine if the distributions are \( \delta \)-near. Their result (slightly restated) is summarized in the following theorem.

**THEOREM 5.5 [BATU ET AL. 2001].** For any \( \epsilon \), given \( \tilde{O}(n^{1/2}\text{poly}(\epsilon^{-1})) \) samples of a distribution \( X \) over \([n]\), and a specified distribution \( Y \), there is a test that outputs PASS with high probability if \( |X - Y|_1 \leq \frac{\epsilon^3}{4\sqrt{n}\log n} \), and outputs FAIL with high probability if \( |X - Y|_1 \geq 6\epsilon \).

The distribution \( X \) in our context is some distribution on nodes and \( Y \) is the stationary distribution, that is, \( Y(v) = \deg(v)/(2m) \) (recall that \( m \) is the number of edges in the network). In this case, the algorithm used in that is, theorem can be simulated in a distributed network in \( \tilde{O}(D + 2/\log(1 + \epsilon)) \) rounds, as in the following theorem.

**THEOREM 5.6.** For any \( \epsilon \), given \( \tilde{O}(n^{1/2}\text{poly}(\epsilon^{-1})) \) samples of a distribution \( X \) over \([n]\), and a stationary distribution \( Y \), there is a \( \tilde{O}(D + 2/\log(1 + \epsilon)) \)-time test that outputs PASS with high probability if \( |X - Y|_1 \leq \frac{\epsilon^3}{4\sqrt{n}\log n} \), and outputs FAIL with high probability if \( |X - Y|_1 \geq 6\epsilon \).
PROOF. We now give a brief description of the algorithm of Batu et al. [2001] to illustrate that it can in fact be simulated on the distributed network efficiently. The algorithm partitions the set of nodes into \( k \) buckets, where \( k = (2/\log(1 + \epsilon)) \log n \), based on \( Y \) (the stationary distribution in this case). Denote these buckets by \( R_1, \ldots, R_k \). Each bucket \( R_i \) consists of all nodes \( v \) such that \( \frac{(1+\epsilon)^{\ell-1}}{n \log n} \leq Y(v) < \frac{(1+\epsilon)^\ell}{n \log n} \). Since \( n, m \) and \( \epsilon \) can be broadcasted to all nodes in \( O(D) \) rounds and each node \( v \) can compute its stationary distribution \( Y(v) = \deg(v)/(2m) \), each node can determine which bucket it is in in \( O(D) \) rounds.

Now, we sample \( \tilde{O}(n^{1/2} \text{poly}(\epsilon^{-1})) \) nodes based on distribution \( X \). Each of the \( \tilde{O}(n^{1/2} \text{poly}(\epsilon^{-1})) \) sampled nodes from \( X \) falls in one of these buckets. We let \( \ell_i \) be the number of sampled nodes in bucket \( R_i \) and let \( Y(R_i) \) be the distribution of \( Y \) on \( R_i \). The values of \( \ell_i \) and \( Y(R_i) \), for all \( i \), can compute and sent to some central node in \( O(k) = \tilde{O}(2/\log(1 + \epsilon)) \) rounds. Finally, the central node uses this information to determine the output of the algorithm. We refer the reader to Batu et al. [2001] for a precise description.

Our algorithm starts with \( \ell = 1 \) and runs \( K = \tilde{O}((\sqrt{n} \log(1/\epsilon^{-1})) \) walks (for choice of \( \epsilon = 1/12\epsilon \)) of length \( \ell \) from the specified source \( x \). As the test of comparison with the stationary distribution outputs FAIL, \( \ell \) is doubled. This process is repeated to identify the largest \( \ell \) such that the test outputs FAIL with high probability and the smallest \( \ell \) such that the test outputs PASS with high probability. These give lower and upper bounds on the required \( \tau_{mix}^x \) respectively. Our resulting theorem is

**Theorem 5.7.** Given a graph with diameter \( D \), a node \( x \) can find, in \( \tilde{O}(n^{1/2} + n^{1/4} \sqrt{D \text{poly}(\delta)}) \) rounds, a time \( \tau_{mix}^x \) such that \( \tau_{mix}^x \leq \tau_{mix}^x \leq \tau^x(\delta) \), where \( \delta = \frac{1}{6912 \epsilon \sqrt{n \log n}} \).

PROOF. For undirected unweighted graphs, the stationary distribution of the random walk is known and is \( \frac{\deg(i)}{2m} \) for node \( i \) with degree \( \deg(i) \), where \( m \) is the number of edges in the graph. If a source node in the network knows the degree distribution, we only need \( \tilde{O}(n^{1/2} \text{poly}(\epsilon^{-1})) \) samples from a distribution to compare it to the stationary distribution. This can be achieved by running \textsc{MultipleRandomWalk} to obtain \( K = \tilde{O}(n^{1/2} \text{poly}(\epsilon^{-1})) \) random walks. We choose \( \epsilon = 1/12\epsilon \). To find the approximate mixing time, we try out increasing values of \( \ell \) that are powers of 2. Once we find the right consecutive powers of 2, the monotonicity property admits a binary search to determine the exact value for the specified \( \epsilon \).

The result in Batu et al. [2001] can also be adapted to compare with the stationary distribution even if the source does not know the entire distribution. As described previously, the source only needs to know the count of number of nodes with stationary distribution in given buckets. Specifically, the buckets of interest are at most \( \tilde{O}(n^{1/2} \text{poly}(\epsilon^{-1})) \) as the count is required only for buckets were a sample is drawn from. Since each node knows its own stationary probability (determined just by its degree), the source can broadcast a specific bucket information and recover, in \( O(D) \) steps, the count of number of nodes that fall into this bucket. Using upcast, the source can obtain the bucket count for each of these at most \( \tilde{O}(n^{1/2} \text{poly} \epsilon^{-1}) \) buckets in \( \tilde{O}(n^{1/2} \text{poly}(\epsilon^{-1}) + D) \) rounds.

By Theorem 4.1, a source node can obtain \( K \) samples from \( K \) independent random walks of length \( \ell \) in \( \tilde{O}(K + \sqrt{K \ell D}) \) rounds. Setting \( K = \tilde{O}(n^{1/2} \text{poly}(\epsilon^{-1}) + D) \) completes the proof.
Suppose our estimate of $\tau_{mix}^x$ is close to the mixing time of the graph defined as $\tau_{mix} = \max_x \tau_{mix}^x$, then this would allow us to estimate several related quantities. Given a mixing time $\tau_{mix}$, we can approximate the spectral gap $(1 - \lambda_2)$ and the conductance ($\Phi$) due to the known relations that $\frac{1}{1-\lambda_2} \leq \tau_{mix} \leq \frac{\log n}{1-\lambda_2}$ and $\Theta(1-\lambda_2) \leq \Phi \leq \Theta(\sqrt{1-\lambda_2})$ as shown in Jerrum and Sinclair [1989].

6. CONCLUDING REMARKS
This article gives a tight upper bound on the time complexity of distributed computation of random walks in undirected networks. Thus, the running time of our algorithm is optimal (within a polylogarithmic factor), matching the lower bound that was shown recently [Nanongkai et al. 2011]. However, our upper bound for performing $k$ independent random walks may not be tight and it will be interesting to resolve this.

While the focus of this article is on time complexity, message complexity is also important. In particular, our message complexity for computing $k$ independent random walks of length $\ell$ is $\tilde{O}(m\sqrt{\ell/D} + n\sqrt{\ell/D})$, which can be worse than the naive algorithm's $\tilde{O}(k\ell)$ message complexity. It would be important to come up with an algorithm that is round efficient and yet has smaller message complexity. In a subsequent paper [Das Sarma et al. 2012b], we have addressed this issue partly and shown that, under certain assumptions, we can extend our algorithms to be message efficient also.

We presented two algorithmic applications of our distributed random walk algorithm: estimating mixing times and computing random spanning trees. It would be interesting to improve upon these results. For example, is there a $\tilde{O} \left( \sqrt{\tau_{mix}^x} + n^{1/4} \right)$ round algorithm to estimate $\tau^x$; and is there an algorithm for estimating the mixing time (which is the worst among all starting points)? Another open question is whether there exists a $\tilde{O}(n)$ round (or a faster) algorithm for RST?

There are several interesting directions to take this work further. Can these techniques be useful for estimating the second eigenvector of the transition matrix (useful for sparse cuts)? Are there efficient distributed algorithms for random walks in directed graphs (useful for PageRank and related quantities)? Finally, from a practical standpoint, it is important to develop algorithms that are robust to failures and it would be nice to extend our techniques to handle such node/edge failures. This can be useful for doing decentralized computation in large-scale dynamic networks.

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