Quantitative Description for Sand Void Fabric with the Principle of Stereology

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Abstract: Based on the principle of stereology to describe void fabric, the fabric tensor is redefined by the idea of normalization, and a novel quantitative description method for the orthotropic fabric of granular materials is presented. The scan line is described by two independent angles in the stereo space, and the projection of the scan line on three orthogonal planes is used to determine the plane tensor. The second-order plane tensor can be described equivalently by two invariants, which describe the degree and direction of anisotropy of the material, respectively. In the three-dimensional orthogonal space, there are three measurable amplitude parameters on the three orthogonal planes. Due to the normalized definition of tensor in this paper, there are only two independent variations of the three amplitude parameters, and any two amplitude parameters can be used to derive the three-dimensional orthotropic fabric tensor. Therefore, the same orthorhombic anisotropy structure can be described by three fabrics, which enriches the theoretical description of orthotropy greatly. As the geometric relationship of the stereoscopic space scan line changes, the three sets of orthotropic fabrics degenerate into different forms of transversely isotropic and isotropic fabrics naturally and have a clear physical meaning. The novel fabric tensor is quantitatively determined based on mathematical probability and statistics. The discrete distribution of voids in space is projected as a scalar measurable parameter on a plane. This parameter is related to the macroscopic constitutive relationship directly and can be used to describe the effect of microscopic voids on the macroscopic phenomenon of materials.

Keywords: sand; orthogonal anisotropy; void fabric; quantitative analysis

1. Introduction

The void ratio is one of the most important, earliest, and most widely used material parameters for controlling the mechanical response of the soil. In critical state soil mechanics, it is the only material physical parameter that describes the critical state. However, Li and Dafalias [1], Zhao and Guo [2] and Abouzar et al. [3] have recently confirmed that the critical state of soil was not unique due to the existence of fabric anisotropy, i.e., the relationship between the void ratio of critical state and hydrostatic pressure was not unique, which was a challenge to the uniqueness hypothesis for the critical state theory of soil mechanics. According to the anisotropic characteristics of soil meso-structure, Chow et al. [4] studied the meso-structure of particles under one-dimensional consolidation conditions and found that the particle structure had a horizontal arrangement trend, and the void structure showed a similar orientation trend. Sun et al. [5] and Zheng et al. [6] found that the void fabric tensor and particle sphericity, relative density, and coordination number have a strong functional relationship through the image analysis of loose and dense sand specimens. Hu et al. [7] presented a fabric tensor-based bounding surface model accounting for the anisotropic behavior of granular materials. Zhang et al. [8] established the relations between the macroscopic volumetric strain, shear strain, and void fabric combined with the micromechanics theory, and linked with void fabric tensor. Zhao et al. [9] considered
the effects of initial anisotropy, porosity, stress ratio, loading direction, and intermediate principal stress ratio, and established the anisotropic evolution law for fabric. Although the void fabric has a substantial impact on the mechanical properties of sand, the relative lag in the development of mesoscopic testing technology, experiment and description theory of void fabric has led to a lack of understanding of void fabric and has restricted the study of the mechanical properties by the method of macro and micro combination.

The three main causes of the meso-fabric of sand are the anisotropic distribution of contact normal particles, void space, and the arrangement of the nonspherical particles [10]. It is difficult to consider the three causes simultaneously because they have different physical and geometric meanings and applications. Therefore, the different fabric theories and their description methods have been formed. For example, Oda [10] and Tobita [11] defined the fabric tensor by considering the arrangement direction of the long axes of sand particles and the distribution of contact stress, which laid the foundation of the fabric theory and has been widely applied. However, the determination of single-particle direction and the direction of contact normal between particles has always puzzled scholars, who believed that these two factors were hardly measured accurately [12,13]. Thus, there are more qualitative studies than quantitative studies for fabric, which is the biggest obstacle to be applied to soil constitutive relationships. In the author’s work of establishing strength criterion [14], constitutive model [15] and potential theory [16] with fabric to describe anisotropy, the fabric description has always been at the core of thinking. Comparatively speaking, the description of void in three kinds of fabric is more intuitive and easier to accept, but the bottleneck is the development of its theory and measurement technology. Void fabric is a mathematical relationship describing the spatial distribution of voids in soil and there are three main theories to describe void fabric. First, Oda [17] proposed the 2D void fabric theory and its measurement method; then Bhatia and Soliman [18] used it in an experimental study. This method was difficult to popularize because it involved segmentation and image recognition, such as the center of gravity, boundary, shape, arrangement, and movement of particles. Second, Bagi [19] proposed a dual geometric system to describe the effects of particles and voids; however, the difficulty in defining the 3D void space was its application. Based on Bagi’s study [19], Li and Li [20] modified the theoretical expression of fabric. Using the modified expression, Fu and Dafalias [21] obtained 2D linear relationships of a different fabric caused by discrete element simulation. Nevertheless, there were still similar problems in the quantitative determination of Oda’s fabrics [17]. Third, the void fabric was determined by the stereology theory. Hilliard [22] first established the mathematical framework and determined the void distribution in different planes and spaces with scan lines quantitatively. Later, Kanatani [23–25] extended the Hilliard method to the form of Cartesian coordinate tensor, and for the first time unified the Hilliard method to solve different problems into a unique mathematical framework. Buffon transformed and derived the inverse transform of Buffon transform that determined the fabric tensor with the scan line directly. Based on the work of Kanatani [23–25], Kuo et al. [26] and Shiva et al. [27] conducted quantitative detection of the void tensor for sand. Ghedia et al. [28] and Theocharis et al. [29] used scan lines to quantify the void in granular materials. The results showed that the method can quantify the anisotropy and 3D evolution of void fabric adequately. Through DEM analysis, it was found that the method was adapted to the existing quantification methods of the void fabric. All the above studies show the rationality of using scan lines to quantify the void of granular materials, but there are relatively few theoretical and experimental results. To sum up, the third theoretical basis is dependable, and the test analysis is simple.

According to the theoretical description of the particle arrangement fabric and the quantitative detection of the plane amplitude parameters, authors [30,31] presented a quantitative detection method of the plane parameters for the sand void fabric by stereology [32]. Based on this method, there was also a better effect on the quantitative determination of rock fracture fabrics [33,34]. Hence, for the shortcomings of the existing void fabric theory in the measurement process, the authors redefined the theoretical expression of the void
fabric. On the basis of plane quantitative measurement for void fabric, the method was
extended to 3D space, and theoretical expressions of void fabric for different 3D fabric were
derived by using quantitative measurement parameters on three orthogonal planes, i.e., the
3D fabric expressions of orthotropic and transversely isotropic. In this paper, the physical
and geometric significance was analyzed in detail to popularize and apply quantitative
determination technology of void fabric.

2. Existing Theories of the Void Fabric Tensors

The distribution equation of void space is determined based on the principle of
stereology. The equation is determined by the average porosity (scalar) and the symmetric
fabric tensor that’s trace is 0 [23–25] and reads:

\[ \mathbf{R} = \alpha \mathbf{A} + \beta \mathbf{B} \]

where \( \alpha \) and \( \beta \) are independent integral variables of the integral interval.

Then, the average porosity in a unit sphere is as follows:

\[ n_m = \frac{1}{4\pi} \int_0^{2\pi} \int_0^\pi L_L(\alpha, \beta) \sin \alpha \mathrm{d}\alpha \mathrm{d}\beta \]  

(2)

where \( n_m \) is the average porosity per unit measured through the \( m \)-th scan line. Equation
(2) expresses in the Cartesian coordinate system as follows:

\[ n_m = \frac{1}{8\pi} \left( \int S_{yz} l_x \mathrm{d}y \mathrm{d}z + \int S_{zx} l_y \mathrm{d}z \mathrm{d}x + \int S_{xy} l_z \mathrm{d}x \mathrm{d}y \right) \]

(3)

where \( l_x, l_y \), and \( l_z \) are the distribution functions of the void density on the corresponding co-
dordinate plane, respectively. \( S_{yz}, S_{zx}, \) and \( S_{xy} \) are the integral intervals on the corresponding
plane, respectively.

The void distribution equation is expressed as average porosity and a symmetric
fabric tensor that’s trace is 0 [23–25] and reads:

\[ N(\vec{n}) = n_m(1 + N_{ij}n_i n_j + N_{ijkl}n_i n_j n_k n_l + \cdots) \]  

(4)
where $N(\mathbf{n})$ is the average void distribution function, $\mathbf{n}$ is the unit vector, $N_{i_1i_2...i_n}$ is a void tensor that’s trace is 0 and is reads:

$$N_{i_1i_2...i_n} = \frac{2n+1}{2n} \frac{2n}{n} \Omega_{i_1i_2...i_n}$$

(5)

where $\Omega_{i_1i_2...i_n}$ is the tensor defined by Kanatani [23–25] and reads:

$$\Omega_{i_1i_2...i_n} = \frac{1}{4\pi n_m} \int_{\Omega} n_{i_1i_2...i_n} n_l L_l (\alpha, \beta) d\mathbf{n}$$

(6)

The key of Equation (4) to describe the void distribution is how to measure $n_m$ and $N_{i_1i_2...i_n}$.

3. Novel Void Fabric Tensors Definitions

Based on the description theory of void tensors in the principle of stereology and the theoretical research results of existing void tensors, a novel test method for fabric tensor is presented in this paper.

3.1. Definition of Void Fabric

The void fabric describes the distribution form of the three orthogonal planes where the value of trace is equal to 1. Thus, according to the characteristic and combining with normalized ideas, the equation of the void fabric tensor is defined and reads:

$$M_{i_1i_2...i_n} = \int_{\Omega} n_{i_1i_2...i_n} n_l L_l (\alpha, \beta) d\mathbf{n}$$

$$\int_{\Omega} L_l (\alpha, \beta) d\mathbf{n}$$

(7)

where $M_{i_1i_2...i_n}$ is the void fabric tensor, which is used for the microscopic quantitative detection of the void tensor directly.

The tensor determined by Equation (7) accurately describes the variation of void space distribution in theory. However, in practice, the second-order fabric tensor has been able to describe the variation of void distribution. Hence, the influence of higher-order tensors is ignored. Equation (7) describes the second-order tensor as follows.

$$M_{ij} = \frac{\int L_l (\alpha, \beta) n_i n_j d\mathbf{n}}{\int L_l (\alpha, \beta) d\mathbf{n}}$$

(8)

where $M_{ij}$ is the second-order symmetric fabric tensor. $\alpha_m$ and $\beta_m$ are the description angles of the $m$-th scan line. $n_i n_j$ is the direction component of the second-order fabric tensor.

According to Equation (5), a tensor that’s trace is 0 is obtained directly and reads:

$$N_{ij} = \frac{15}{2} (M_{ij} - \frac{1}{3} \delta_{ij})$$

(9)

where $N_{ij}$ is the symmetric fabric tensor that’s trace is 0 describing the void distribution. $\delta_{ij}$ is the Kronecker tensor.

According to Equation (4), the void distribution equation of the second-order tensor is as follows.

$$N(\mathbf{n}) = n_m (1 + N_{ij} n_i n_j)$$

(10)

where $n_m$ is the form described by Equation (2).
From Equation (8), the description method in this paper improved the fabric definition. According to the definition of measurement voids, the measurement process is expressed as the following equation by series.

$$M_{ij} = \frac{\sum_{m=0}^{N-1} L_{L_1}(\alpha_m, \beta_m) n_i n_j}{\sum_{m=0}^{N-1} L_{L_1}(\alpha_m, \beta_m)} = \frac{\sum_{m=0}^{N-1} L_1(\alpha_m, \beta_m) n_i n_j}{\sum_{m=0}^{N-1} L_1(\alpha_m, \beta_m)}$$ (11)

From Figure 2, the components of the unit vector $\vec{n}$ in the three orthogonal directions are $n_1 = \cos \alpha$, $n_2 = \sin \alpha \sin \beta$, and $n_3 = \sin \alpha \cos \beta$, i.e., the tensor defined by Equation (11) is the following equation.

$$M_{ij} = \begin{bmatrix} M_{11} & M_{12} & M_{13} \\ M_{21} & M_{22} & M_{23} \\ M_{31} & M_{32} & M_{33} \end{bmatrix}$$ (12)

From Equations (11) and (12), the trace of the novel void tensor $M_{ij}$ is equal to 1, so the trace of the tensor described in Equation (9) is equal to 0, which provides great convenience for the derivation of the void distribution equation and the determination of the test tensor.

![Figure 2](image_url)  

**Figure 2.** The coordinate used in the void fabric tensor analysis.

### 3.2. A Novel Definition of 2D Void Fabric

As shown in the unit test sphere in Figure 1, the spatial distribution of voids cannot be obtained directly by spatial scan line but can be obtained by plane image analysis of void distribution and then can be carried out reasonably in 3D modeling. The void projection distribution on three orthogonal planes is obtained by plane image analysis, and the detailed quantitative method is shown in the reference [35]. Then the void projection described in Figure 1 on the three orthogonal planes is measured by the actual image, i.e., the fabric tensor on the three orthogonal planes $x_1$-$x_3$, $x_1$-$x_2$, and $x_2$-$x_3$. According to Equation (12), the tensor on the plane $x_1$-$x_3$ is the following equation.

$$M_{ij}^{1-3} = \begin{bmatrix} M_{11} & M_{13} \\ M_{31} & M_{33} \end{bmatrix}$$ (13)
From Equation (11), $N_{ij}$ is the partial tensor of $M_{ij}$, then $N_{ij}^{1-3}$ is described equivalently by the second invariant and component angle of $M_{ij}^{1-3}$, and reads:

$$b_1 = \sqrt{2} = \frac{1}{2} \arctan \frac{2M_{11}}{M_{11} - M_{22}},$$
$$\theta_1 = \frac{1}{2} \arctan \frac{2M_{11}}{M_{11} - M_{22}},$$

where $b_1$ is the void amplitude parameter and is the second invariant of the void tensor in plane $x_1$-$x_3$, which is a scalar and describes the anisotropic degree. $\theta_1$ is the angle between the major direction of the void fabric and the direction of the coordinate axis, which describes the plane direction of the void fabric anisotropic degree.

Similarly, the invariants and directions in the planes $x_1$-$x_2$ and $x_2$-$x_3$ are the following equations.

$$b_2 = \sqrt{2} = \frac{1}{2} \arctan \frac{2M_{12}}{M_{12} - M_{23}},$$
$$\theta_2 = \frac{1}{2} \arctan \frac{2M_{12}}{M_{12} - M_{23}},$$

$$b_3 = \sqrt{2} = \frac{1}{2} \arctan \frac{2M_{13}}{M_{13} - M_{33}},$$
$$\theta_3 = \frac{1}{2} \arctan \frac{2M_{13}}{M_{13} - M_{33}},$$

where $b_2$ and $b_3$ are the void amplitude parameters on planes of $x_1$-$x_2$ and $x_2$-$x_3$, which describes the anisotropic degree. $\theta_2$ and $\theta_3$ are the angles of the two corresponding planes.

According to Equation (12), the distribution of the void tensor on three orthogonal planes is described by its invariant.

$$N_i(n_{m}^{2D}, \theta_m) = n_{m}^{2D} (1 + b_i \cos 2(\theta_m - \theta_i))$$

where $\theta_m$ is the angle of the unit vector in the plane coordinate system. $n_{m}^{2D}$ is the average porosity of the plane, which is determined directly by image analysis. $b_i$ ($i = 1, 2, 3$) are the void amplitude parameters defined in Equations (14)–(16), respectively. $\theta_i$ ($i = 1, 2, 3$) are the angle invariants defined by the corresponding equation. Due to $M_{kk} = 1$, the values of all three amplitude parameters are between 0 and 1. When $b_i = 0$, the voids are distributed evenly and the specimen is isotropic. When $b_i = 1$, the voids are distributed ideally in a fixed direction. $\theta_i$ represents the anisotropic direction of the void distribution.

4. Novel Void Fabric Tensors Definitions

According to the novel fabric definition of the normalized ideas, i.e., $M_{kk} = 1$, there are only two independent variables in the amplitude parameters of $b_1$, $b_2$, and $b_3$. Hence, as long as the amplitude parameters on any two orthogonal planes are measured in theory, the fabric tensor is determined uniquely. Then it is deduced that any two amplitude parameters are used to describe the void fabric tensor.
4.1. Orthotropic Void Fabrics

The void amplitude parameter \((b_1, b_2, \text{ and } b_3)\) obtained by Equations (14)–(16) in 2D space is not equal to the principal value \((M_1, M_2, \text{ and } M_3)\) in 3D space, but proportional to it. Therefore, the following void fabric equation is established and reads:

\[
M_{ij} = \begin{bmatrix}
M_1 & 0 & 0 \\
0 & M_2 & 0 \\
0 & 0 & M_3
\end{bmatrix}
\]  

(18)

According to \(M_{kk} = 1\) and any two parameters from \(b_1, b_2, \text{ and } b_3\), the orthotropic fabric tensor is obtained, and the detailed derivative process is shown in reference [31]. The three equations of orthotropic fabric tensor are as follows:

\begin{align*}
M_1 &= \frac{(1+b_1) (1+b_2)}{3+b_1+b_2-b_1 b_2} \\
M_2 &= \frac{2+b_3+b_1 b_2}{3+b_1+b_2-b_1 b_2} \\
M_3 &= \frac{1}{3+b_1+b_2-b_1 b_2}
\end{align*}

(19)

\begin{align*}
M_1 &= \frac{(1+b_1) (1+b_3)}{3+b_1-b_3-b_1 b_3} \\
M_2 &= \frac{2+b_2+b_1 b_3}{3+b_1-b_3-b_1 b_3} \\
M_3 &= \frac{1}{3+b_1-b_3-b_1 b_3}
\end{align*}

(20)

\begin{align*}
M_1 &= \frac{(1+b_2) (1+b_3)}{3+b_2+b_3+b_2 b_3} \\
M_2 &= \frac{2+b_1+b_2 b_3}{3+b_2+b_3+b_2 b_3} \\
M_3 &= \frac{1}{3+b_2+b_3+b_2 b_3}
\end{align*}

(21)

Equation (19) is the three principal value parameters \(M_1, M_2, \text{ and } M_3\) of the orthotropic void fabric tensor, which are calculated by the void amplitude parameters \(b_1, b_2, \text{ and } b_3\) of the surface \(x_1-x_3\) and surface \(x_1-x_2\). Similarly, Equation (20) is the three principal value parameters \(M_1, M_2, \text{ and } M_3\) of the orthotropic void fabric tensor, which are calculated by the void amplitude parameters \(b_1, b_2, \text{ and } b_3\) of the surface \(x_1-x_3\) and surface \(x_2-x_3\). Equation (21) is the three principal value parameters \(M_1, M_2, \text{ and } M_3\) of the orthotropic void fabric tensor, which are calculated by the void amplitude parameters \(b_2, b_3, \text{ and } b_3\) of the surface \(x_1-x_2, x_1-x_3, \text{ and } x_2-x_3\).

Therefore, as long as any two void invariants of the three orthogonal planes are obtained through experiments, the orthogonal anisotropic fabric is determined by Equation (18). Equations (19)–(21) not only provided more options for the theoretical description of \(M_{ij}\), but also provided more flexible methods for the orthotropic experimental measurement of void fabric for sand.

4.2. Transversely Isotropic Void Fabrics

In this paper, the definition of orthotropic void fabric is based on the measurement method of stereology, which describes the orthotropic distribution of voids. When the scan line distribution meets certain geometric conditions, it is simplified into the form of transversely isotropy and isotropy naturally.

In Equations (14) and (15), when \(\beta_m = \pi / 4\), then \(b_1 = b_2\), i.e., the void parameters in the two directions are equal. At this point, the material shows as transversely isotropic, and Equation (19) is simplified into 3D fabric and reads:

\[
M_{ij} = \frac{1}{3-b} \begin{bmatrix}
1+b & 0 & 0 \\
0 & 1-b & 0 \\
0 & 0 & 1-b
\end{bmatrix}
\]  

(22)
where:

\[
b = \sqrt{\left( \frac{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m) \cos 2 \alpha_m - \frac{1}{2} \sin^2 \alpha_m}{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m)} \right)^2 + \frac{1}{2} \left( \frac{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m) \sin 2 \alpha_m}{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m)} \right)^2}
\]  (23)

where \( b \) is the amplitude parameter of the transversely isotropic void tensor, and its theoretical value range is \([0,1]\), which is obtained by solving the invariant of the planar void fabric tensor from any one of the two homogeneous planes. \( b_1 = b_2 = b \) indicates that the void tensor invariants of the two planes are equal. Equation (22) is used to describe the transversely isotropy of the voids in the sand by an amplitude parameter. The physical geometric meaning of transversely isotropy is legible.

According to Equations (9) and (22), \( N_{ij} \) is obtained and reads:

\[
N_{ij} = \frac{5}{3 - b} \begin{bmatrix}
2b & 0 & 0 \\
0 & -b & 0 \\
0 & 0 & -b
\end{bmatrix}
\]  (24)

The average porosity \( n_m \) in Equation (9) is easy to determine. Thus, when \( N_{ij} \) is determined, the distribution of transversely isotropic void space is determined.

Similarly, when \( \alpha_m = \pi/2 \) in Equation (14) and \( \beta_m = 0 \) in Equation (16), then \( b_1 = b_3 \) and Equation (20) is simplified into the form of transversely isotropy and reads:

\[
M_{ij} = \frac{1}{3 + b} \begin{bmatrix}
1 + b & 0 & 0 \\
0 & 1 + b & 0 \\
0 & 0 & 1 - b
\end{bmatrix}
\]  (25)

where \( b \) is the following:

\[
b = \sqrt{\left( \frac{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m) \cos 2 \alpha_m}{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m)} \right)^2 + \frac{1}{2} \left( \frac{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m) \sin 2 \alpha_m}{\sum_{m=0}^{N-1} L_\alpha (\alpha_m, \beta_m)} \right)^2}
\]  (26)

where \( b \) is the parameter of transversely isotropic fabric. The variable of Equation (14) after degenerating is \( \beta_m \). The variable of Equation (16) after degenerating is \( \alpha_m \). For convenience, the variable \( \alpha_m \) is used here.

When \( \beta_m = \pi/2 \) in Equation (15) and \( \alpha_m = 0 \) in Equation (16), then \( b_2 = b_3 \). Equation (19) is simplified into the following equation.

\[
M_{ij} = \frac{1}{3 + b^2} \begin{bmatrix}
(1 + b)^2 & 0 & 0 \\
0 & 1 - b^2 & 0 \\
0 & 0 & (1 - b)^2
\end{bmatrix}
\]  (27)

where the equation of \( b \) is the same as the form of Equation (26), but the variable \( \beta_m \) is different. Although the amplitude parameter is simplified into a transversely isotropic form, the simplified fabric tensor (Equation (27)) is orthotropic.

To sum up, when the orthotropic void fabrics are simplified into transversely isotropy, Equation (22) is applied to the detection and application of transversely isotropic void fabric directly. Although Equation (25) has some contradictions in the degradation process, it is consistent with the description results of the existing void fabric. Hence, under certain conditions, Equation (25) still has certainly applicable scope. Equation (27) is still in the orthotropic form after degradation and cannot describe transversely isotropic materi-
5. Image Analysis of Void Fabric

5.1. Analysis Procedure and Method

According to the theoretical determination method of void tensor presented in this paper, an image analysis program is compiled with Matlab, and the program frame diagram is presented in Figure 3, which shows the whole process of fabric determination. Since the major purpose of this study is to determine the orthotropy of the void tensor, cube specimens are required for specimen collection and preparation.

The calculation program in Figure 3 is composed of two parts. The first part is the Matlab program of image processing, which aims to reduce the interference of environmental factors and to obtain a clear binary image for image analysis. The second part is the Matlab program of image analysis, which is the most critical part of the process. To obtain the probability statistic law of the void distribution in three orthogonal directions, the program has to perform statistical analysis on the void distribution of multiple pictures from different orthogonal directions, and there are two cyclic programs to accomplish this task. Finally, the void distribution extracted by image analysis is used to calculate the void amplitude parameters, direction, and spatial distribution of the void plane.

5.2. Parallel Scan Line Analysis Method

According to the principle of stereology, the scan line is the key to the test of void fabric. The void is the sum of all pixels with a value 0 in a binary image. Porosity is the ratio of the voids to the total pixels of the scan line, this definition is different from the soil mechanics, while their spatial distribution is the same and can be interchangeable.

In the image analysis, the scan line and the image processing diagram of specimens are operated with “&”, and the intersection image of the scan line and void is obtained, then void data is extracted. Figure 4 shows the calculation results of image analysis with parallel scan lines. Figure 4a is the diagram of the scan line (60°). Figure 4b is the binary image. Figure 4c is the result measured by the 60° scan line and Figure 4d is the result measured by the 30° scan line. The number of scan lines is 180. The scan line is drawn by AutoCAD. Figure 4c,d show that the calculated image will better describe the void distribution.
Before test verification, the influence of scan line density and angle needs to be analyzed. Two examples are designed for the same image. One is to analyze the image with different scan line densities and the same angle. The other is to analyze the image with different scan lines at the same density and different angles. Figure 5 shows the influence of scan line density on test results, and the relationship between porosity and scan line density is obtained by increasing the number of scan lines with a fixed angle of the scan line. The images adopt three orthogonal planes of sand specimens from Kuo et al. [26].

As is presented in Figure 5, the fewer the number of test lines, the greater the impact on the porosity. However, as the number of scan lines increases, the fluctuation tends to be stable and nearly constant. When the number of scan lines is more than 100, the porosity fluctuation is ignored. Therefore 230 scan lines were used in this test. Figure 6 shows the relationship between the angle of parallel scan lines and porosity. The angle of the scan lines varied from 0° to 180° with an angle interval of 10°. Figure 6a shows that the porosity varies little with the angle of the scan line and is close to a constant value.
Figure 6b intuitively shows that the plane porosity measured by parallel scan lines is an invariant, which cannot reflect the plane distribution of voids.

![Figure 6a](image1.png) ![Figure 6b](image2.png)

**Figure 6.** Different angle scan line vs. porosity. (a) Planar relationship. (b) Roses.

To sum up, the average porosity fluctuated greatly when the number of scan lines was small, but after reaching a certain number, the value tends to be constant. The average porosity is a scalar, which is independent of the direction. Thus, parallel scan lines can measure the average porosity, but cannot measure the distribution of voids.

### 5.3. Analysis Method with Annular Scan Line

To obtain the distribution of voids, an annular scan line has to be used. Figure 7a shows the drawing of the annular scan line, which is a method used by some scholars such as Kuo and Frost [26], i.e., RECs (representative element circles) method. The RECs method is used to measure the planar distribution of sand voids with an annular scan line. According to the results of reference [26], when $R_1$ is greater than 35 pixels points and $R_2$ is less than 240 pixels points, stable void distribution is obtained. The size of the scan line used in this test is as follows: $R_1$ is equal to 40 pixels points, $R_2$ is equal to 230 pixels points, and the number of scan lines is 180. Figure 7b shows the specimen picture of Kuo et al. [26]. Figure 7c shows the distribution of the scan line. Figure 7d shows the image analysis effect of 90 scan lines.

![Figure 7a](image3.png) ![Figure 7b](image4.png)

**Figure 7.** Cont.
Figure 7. The procedures to determine voids with the annular scan line. (a) Scan line painting, (b) Binarization, (c) Annular scan line, (d) Analysis of image.

6. Determination and Application Analysis of Void Fabric

The experimental determination involves the acquisition method and image processing of the orthogonal fabric image from the sand specimens, identification technology, and quantitative analysis technology. This test aims to present a fabric equation that can be applied to macroscopic constitutive equations directly. For the methods of image acquisition of sand specimens, please refer to the author’s article [32].

6.1. The Fabric of Orthogonal Plane Determined by Experiment

Experimental images are selected from reference [26]. Kuo et al. [26] used SEM (Scanning Electron Microscope) to collect images of sand in three orthogonal planes from solidifying sand specimens. The image processing technology is used to obtain a clear picture of the void distribution, and then the image analysis technology is used to extract the void information. The distribution of voids is obtained by annular scan line, of which the number is 180. The inner diameter $R_1$ is 40 pixels and the outer diameter $R_2$ is 230 pixels. The calculation results are presented in Figure 8b.

Figure 8. SEM binary diagrams of sand specimens. (a) $x_2$-$x_3$ plane. (b) Analysis of image. (c) $x_1$-$x_3$ plane. (d) $x_1$-$x_2$ plane.

Figure 9 shows the image analysis results of void distribution and the simulation results in this paper. The polar diameter is the amplitude parameter, and the polar angle is the rotation angle per 1° of the plane scan line on the test surface. $\beta_m = 0°$, $\beta_m = 45°$, and
\( \beta_m = 90^\circ \) in the legend represents the amplitude parameters measured by \( 0^\circ, 45^\circ \) and \( 90^\circ \) spatial scan lines, respectively. The discrete points in Figure 9 are the measured data from image analysis, which shows the anisotropy with different degrees. For the measured value \((b_1, b_2, \text{and } b_3)\) of each plane \((\text{plane } x_1-x_3, x_1-x_2, \text{and } x_2-x_3)\) in the figure, the simulated data of three geometric conditions are given, i.e., the plane void distribution is measured when the angle of the spatial scan line is \( \beta_m = 0^\circ, \beta_m = 45^\circ, \text{and } \beta_m = 90^\circ \), respectively. The crucial data to be calculated are as follows: the average porosity \( n_0 \) and amplitude parameter \( b \) varied with \( \beta_m = 0^\circ, 45^\circ, 90^\circ \). In Figure 9a, \( n_0 = 0.365, b_1 = 0.012, 0.053 \text{ and } 0.169, \theta_m = 92.9^\circ \). In Figure 9b, \( n_0 = 0.308, b_2 = 0.128, 0.067 \text{ and } 0.008, \text{respectively, and the direction } \theta_m \text{ is } -4^\circ \). In Figure 9c, \( n_0 = 0.348, b_3 = 0.249, \text{and } \theta_m = 0^\circ, -45^\circ, 0^\circ \), respectively. \( \beta_m \) defined in this paper is another independent variable that is a possible description of the spatial distribution of voids. When \( \beta_m = 0^\circ \) in Figure 9a, \( \beta_m = 45^\circ \) in Figure 9b and \( \beta_m = 90^\circ \) in Figure 9c, the calculation of the horizontal plane tensor is not affected, i.e., the plane tensor is simplified into the form proposed by Kanatani [23]. Under such conditions, the method defined in this paper will better simulate the planar void experiment and determine the distribution. Under other conditions, the void distribution is affected by the measured value of voids and \( \beta_m \).

![Figure 9](image-url)

**Figure 9.** Rose diagrams of amplitude parameters. (a) Results of \( b_1 \). (b) Results of \( b_2 \). (c) Results of \( b_3 \).
According to the results of the void fabric on the orthogonal plane in Figure 9, the test laws of different spatial scan lines for the same plane image are analyzed. Figure 10 shows all possible spatial distributions with the different $\beta_m$ in three planes. It is concluded from the figure that amplitude parameters on different planes have different effects on $\beta$. With the variation of the spatial position of the scan line, the trend of $b_1$ and $b_2$ is reversed, while $b_3$ remains unchanged, which is consistent with the theoretical definition in this paper. Since the trace of the void fabric is defined as 1, any two amplitude parameters measured in Figure 10 can be used to describe the orthotropic of the void fabric. In Figure 10, when $\beta_m = 45^\circ$, then $b_1 = b_2$. The void distribution is used in Equation (22) to describe the transversely isotropy of the void fabric. In this case, the value of the void fabric is unique. Hence, the measured form of fabric tensor is also unique.

![Figure 10. Relationships of amplitude parameters $b$ and $\beta_m$.](image)

6.2. Application of Orthogonal Fabric

When the amplitude parameters on the orthogonal plane are determined, the orthotropic void tensor or transversely isotropic tensor of sand fabric is obtained by Equation (18). According to the definition of void fabric, fabric tensor describes the probability and statistical law of the void spatial distribution. Therefore, the measured tensor is substituted directly into the constitutive model to describe the effect of micro-voids on the macro-mechanics response of the material. According to the measured values in Figure 9, $b_1 = 0.012$, $b_2 = 0.128$, and substitute $b_1$, $b_2$ to Equation (19), the orthotropic fabric tensor of orthotropic materials are as follows:

$$M_{ij} = \begin{bmatrix} 0.3637 & 0 & 0 \\ 0 & 0.2812 & 0 \\ 0 & 0 & 0.3551 \end{bmatrix}$$ (28)

According to the measured value in Figure 9b and Equation (19), the transversely isotropic fabric tensor of transversely isotropic materials is as follows, when $b_1 = b = 0.128$.

$$M_{ij} = \begin{bmatrix} 0.3928 & 0 & 0 \\ 0 & 0.3036 & 0 \\ 0 & 0 & 0.3036 \end{bmatrix}$$ (29)

Combined with the analysis results of Section 6.1, it can be seen that in the 3D orthogonal space, the value of a plane void fabric can be quantitatively and uniquely determined, while the measured value of the other two planar fabrics is hardly determined uniquely. However, the measurement values of the other two plane fabrics are difficult to determine uniquely, so the orthotropic fabric is not unique. This also fully illustrates the complexity of orthogonal spatial fabrics. For fabrics projected on the same plane, the spatial void distribution is not unique. It also affects the application of orthogonal fabrics greatly. However, under specific conditions or test lines, the fabric is unique. For example, under
transversely isotropic conditions, the definition in this article shows that the fabric expressions on two independent measurement surfaces are unique and can be directly applied to macro-mechanical equations.

7. Conclusions

Based on the framework of the stereology to describe void fabric, a novel description method of fabric tensor for sand was presented. This method uses the idea of normalization to redefine the fabric tensor to ensure that the trace of the tensor is always one, which facilitates the determination of the tensor greatly. The planar second-order void tensor was described equivalently by the defined void amplitude parameter and component angle. Both parameters are scalar, which describes the degree and direction of the material’s macroscopic anisotropy. Among the three amplitude parameters defined on the orthogonal plane, there are only two independent changes. Any two amplitude parameters can be used to derive the orthotropic fabric tensor. With the change of the geometric relationship of void distribution, orthotropy will degenerate into transversely isotropy and isotropy naturally, and transversely isotropy can be described by only one amplitude parameter.

Two kinds of scan lines were used for image comparison analysis. Parallel scan line analysis showed that the scan line density had a greater impact on the test results, the density was small, the test fluctuations were large, and the measured value was constant after the density reached a certain value. Parallel scan lines at different angles were used to measure average porosity, but the distribution of planar voids could not be determined. However, the annular scan line would better describe the spatial distribution of voids. The SEM image analysis for sand showed that the method presented in this paper would better describe the plane distribution. The novel method converted the void information into two scalars to describe its plane distribution. Through the change of angle conditions in the void space, it naturally degenerates into the traditional description form. The simulation results verify the rationality of its description, so that the measured void tensor can be used as a material parameter to be applied to the macro-mechanical equation of sand directly.

Compared with the existing methods such as Kanatani, the novel method in this paper adopted normalized ideas and described the fabric with tensor invariants, which made the quantitative determination easier and more flexible. The method derives from the expressions of three different forms of orthotropic fabric tensor, which describe the orthotropy and transversely isotropy of materials with different forms. Its measurement methods are diverse and have a wide range of applications.

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