Equations of motion in odd-dimensional spaces and $T$, $C$-invariance

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The properties of the equation of Dirac type in three-dimensional and five-dimensional Minkowski space-time with respect to time reflection (in sense of Pauli and Wigner) as well as to the operation of charge conjugation are investigated. $P$, $T$, $C$-invariance of Dirac equation for the cases of four components (in three-dimensional space) and eight components (in five-dimensional space) is established. Within the framework of the Poincaré group a relativistic equation is suggested which describes the movement of a particle with non-fixed (indefinite) mass in external electromagnetic field.

Introduction

F. Klein and latter de Broglie pointed out the usefulness of spaces with more than four dimensions for the construction of the physical theories. This idea was intensively developed in 1930–1940 years by many authors who tried to unify the gravitation and electromagnetic theories. Nowadays it is widely developed in connection with the extension of the Poincaré group ($\mathcal{P}(1,3)$) as well as with idea of combining $\mathcal{P}(1,3)$ with group of internal symmetries (a review of this works can be found in [1]).

In the works [2] the mass operator was proposed to be defined as one like momentum or angular momentum operator, i.e. we proposed to define the mass operator to be not a Casimir operator but the generator of a group which has the Poincaré group as its subgroup. For such a group in papers [3, 4] the inhomogeneous de Sitter group is chosen — a group of rotations and translations in 5-dimensional flat Minkowski space-time with the square-mass operator being related to the generator $P_4$ (of group $\mathcal{P}(1,4)$) in such a way

$$M^2 = \kappa^2 + P_4^2.$$

In the present work the $P$, $T$, $C$-invariance properties of the simplest equations invariant under the group $\mathcal{P}(1,4)$ are investigated.

§ 1. Dirac equation within $\mathcal{P}(1,4)$ scheme and $P$, $T$, $C$-transformations

The simplest equations invariant under $\mathcal{P}(1,4)$ group are Dirac equations which in the Hamilton form can be written down as following:

$$H^+\Psi^+(t, \vec{x}) = i\frac{\partial \Psi^+(t, \vec{x})}{\partial t},$$

$$H^-\Psi^-(t, \vec{x}) = i\frac{\partial \Psi^-(t, \vec{x})}{\partial t},$$

(1.1) (1.2)
\[ H^\pm \equiv \alpha_k p_k \pm \beta \kappa, \quad p_k = -i \frac{\partial}{\partial x_k}, \quad k = 1, 2, 3, 4, \]

\( \alpha_k = \gamma_0 \gamma_k, \quad \beta = \gamma_0, \quad \vec{x} \equiv (x_1, x_2, x_3, x_4), \)

where \( \gamma_\mu \) are five four-dimensional Dirac matrices (\( \mu = 0, 1, 2, 3, 4 \)).

The invariance of equation (1.1) (or (1.2)) under space-inversion \( x_k \rightarrow -x_k \) is obvious since in \( (1 + 4) \)-dimensional Minkowski space-time this inversion is reduced to a rotation.

Let us clear up now the question of the invariance of the equation (1.1) (or (1.2)) under the time reflection \( (t \rightarrow -t) \) and charge conjugation. To this aim we write down the generators of the group \( P(1, 4) \) defined of the solutions of the equations (1.1) and (1.2) explicitly

\[ P_0 = H^+, \quad P_k = p_k, \]
\[ J_{kl} = x_k p_l - x_l p_k + \frac{i}{2} \alpha_l \alpha_k, \]

\[ J_{0k} = x_0 p_k - \frac{1}{2}(x_k P_0 + P_0 x_k), \]

\[ [x_k, p_l] = i \delta_{kl}, \quad [x_k, x_l] = [p_k, p_l] = 0. \]

According to Pauli the time-reflection operator \( T^P \) satisfies the conditions

\[ T^P \Psi(t, \vec{x}) = \tau^P \Psi(-t, \vec{x}), \quad (T^P)^2 = 1, \]

\[ [T^P, P_0]_+ = 0, \quad [T^P, P_k]_+ = 0, \quad [T^P, J_{kl}]_- = 0, [T^P, J_{0k}]_+ = 0, \]

where \( \tau^P \) is a \((4 \times 4)\)-matrix.

According to Wigner the time-reflection operator \( T^W \) must satisfy the following conditions

\[ T^W \Psi(t, \vec{x}) = \tau^W \Psi^*(-t, \vec{x}), \quad (T^W)^2 = 1, \]

\[ [T^W, P_0] = 0, \quad [T^W, P_k]_+ = 0, \quad [T^W, J_{kl}]_- = 0, [T^W, J_{0k}] = 0, \]

where \( \tau^W \) is a \((4 \times 4)\) matrix.

Finally the charge-conjugation operator must satisfy the conditions

\[ C \Psi(t, \vec{x}) = \tau^C \Psi^*(t, \vec{x}), \quad C^2 = 1, \]

\[ [C, P_0]_+ = [C, P_k]_+ = 0, \quad [C, J_{\mu\nu}]_+ = 0, \]

where \( \tau^C \) is a \((4 \times 4)\) matrix.

Matrices \( \tau^P, \tau^W \) and \( \tau^C \) can be represented in following form

\[ \tau^P = a^P_\mu \alpha_\mu + a^P_{\mu\nu} \alpha_\mu \alpha_\nu, \quad \mu < \nu, \]

\[ \tau^W = a^W_\mu \alpha_\mu + a^W_{\mu\nu} \alpha_\mu \alpha_\nu, \quad \mu < \nu, \]

\[ \text{In general the squares of operators } T^P, T^W \text{ and } C \text{ are equal to unity to within a multiplicative factor of unit modulus.} \]
\[ \tau^c = a_\mu^c \alpha_\mu + a_{\mu\nu}^c \alpha_\mu \alpha_\nu, \quad \mu < \nu, \]  
(1.13)

where \( a_\mu, a_{\mu\nu} \) are the arbitrary numbers (\( \mu = 0, 1, 2, 3, 4 \)).

Using (1.11) and (1.13) one can immediately verify that the relations (1.6) and (1.10) are satisfied only for the zero-matrices \( \tau^p \) and \( \tau^c \). Relation (1.7) is satisfied if \( \tau^w = \alpha_1 \cdot \alpha_3 \).

Thus, the equation (1.1) or (1.2) is \( T^p \)-, \( C \)-noninvariant but \( P, T^w \)-invariant. This means that the four-component Dirac equations in five-dimensional scheme are not \( P T C \)-invariant as it was pointed out in [4, 5].

This result is a consequence of the fact that in contrary to the usual Dirac equation (1.1) (or (1.2)) do not describe a particle and antiparticle. In fact the generators of the group \( P(1, 4) \) given in the form (1.4) defined on the manifold of all solutions of equations (1.1) and (1.2) realize the representations

\[ D^+(1/2, 0) \oplus D^-(0, 1/2), \]
(1.14)

\[ D^+(0, 1/2) \oplus D^-(1/2, 0) \]
(1.15)

respectively. As it is commonly known, the usual Dirac equation describes a particle and antiparticle and on the manifold of all its solutions the representation \( D^+(1/2) \oplus D^-(1/2) \) is realized of group \( P(1, 3) \).

Starting from the equation (1.1) (or (1.2)) and using Bargman–Wigner’s method [6] one can describe some class of equations invariant under the \( P(1, 4) \) group and the time reflection in sense of Wigner, however they are noninvariant under \( T^p \) and \( C \) operations.

Hence we see that (1.1) (or (1.2)) as well as the class of the Bargman-Wigner type equations (derived from (1.1) or (1.2)) are \( T^w \)-invariant, but \( T^p, C \)-noninvariant.

It may seen in this connection that any theory which is built up in five-dimensional Minkowski space-time is always \( P T C \)-noninvariant [5]. Though actually it is not so. In fact, let us consider equation

\[ H \Psi(t, \vec{x}) = i \frac{\partial \Psi(t, \vec{x})}{\partial t}, \quad \Psi(t) \equiv \Psi(t, \vec{x}) = \begin{pmatrix} \Psi^+(t, \vec{x}) \\ \Psi^-(t, \vec{x}) \end{pmatrix}, \]  
(1.16)

where

\[ H \equiv \bar{\alpha}_k p_k + \bar{\beta} \gamma, \quad k = 1, 2, 3, 4, \]
\[ \bar{\alpha}_k = \begin{pmatrix} \alpha_k^0 & 0 \\ 0 & \alpha_k \end{pmatrix}, \quad \bar{\beta} = \begin{pmatrix} \beta & 0 \\ 0 & -\beta \end{pmatrix}. \]  
(1.17)

On the manifold of solutions of this equations operators \( T^w, T^p \) and \( C \) are defined as:

\[ T^p \Psi(t) = \bar{\tau}^p \Psi(-t), \quad T^w \Psi(t) = \bar{\tau}^w \Psi^*(-t), \quad C \Psi(t) = \bar{\tau}^c \Psi^*(t), \]  
(1.18)

\[ \bar{\tau}^p = \begin{pmatrix} 0 & \beta \\ \beta & 0 \end{pmatrix}, \quad \bar{\tau}^w = \begin{pmatrix} \alpha_1 & \alpha_3 & 0 \\ 0 & \alpha_1 & \alpha_3 \end{pmatrix}, \quad \bar{\tau}^c = \begin{pmatrix} 0 & \alpha_2 & \alpha_4 \\ \alpha_2 & \alpha_4 & 0 \end{pmatrix}. \]  
(1.19)

One can immediately verify that the relations (1.16), (1.8) and (1.10) actually satisfy for the equation (1.16). In means that the equation (1.16) is \( T^w \)-, \( T^p \)-, \( C \)-
and PTC-invariant. That is also clear from the fact that equation (1.16) realizes representation

\[ D^+(1/2, 0) \oplus D^-(1/2, 0) \oplus D^+(0, 1/2) \oplus D^-(0, 1/2). \] (1.20)

Starting from (1.16) and generalizing the Bargman–Wigner method on \( \mathcal{P}(1, 4) \) group one can describe all the equations of Bargman–Wigner type which are PTC-invariant [7].

Thus in case of five dimensions one has to choose for the basic equation on eight-component equation (1.16) but not a four-component equation (1.1) or (1.2).

If cane puts in (1.1) \( \kappa = 0 \), then such four-component equation is \( T^p, C^- \)-invariant and in this case:

\[ \tau^p = \gamma_0, \quad \tau^c = \alpha_2 \alpha_4, \quad \tau^w = \alpha_1 \alpha_3. \] (1.21)

Equation (1.1)

\[ \alpha_k p_k \Psi^\pm(t, \vec{x}) = i \frac{\partial \Psi^\pm(t, \vec{x})}{\partial t} \] (1.1')

describes a particle whose spin is 1/2 but the mass is non-fixed since

\[ M^2 \tilde{\Psi}(t, \vec{p}) = p^2 \tilde{\Psi}(t, \vec{p}) = m^2 \tilde{\Psi}(t, \vec{p}), \quad -\infty < p_4 < \infty, \quad 0 \leq m^2 \leq \infty. \] (1.22)

Here \( \tilde{\Psi}(t, \vec{p}) \) is the Fourier-image of function \( \Psi(t, \vec{x}) \).

From what was performed above it reveals that in \( \mathcal{P}(1, 4) \) scheme it is possible to describe a particle with non-fixed mass (i.e. the particles of resonance type) the spin of which fixed.

\[ \S\ 2. \] Equation for a particle with non-fixed mass on \( \mathcal{P}(1, 3) \) group

In this section we show how one can write down the relativistic equation of motion for a particle with the non-fixed mass within the framework of Poincaré group. Usually elementary particle either stable or unstable whose spin is \( s \), is associated with a Hilbert space \( R^s(m) \) in which on irreducible representation of the Poincaré group \( \mathcal{P}(1, 3) \) is realized. Such a correspondence is unjustified one since we cannot attribute the definite mass to the unstable particle. Following [2, 8] let us attribute to an unstable particle (resonance) a Hilbert space \( R^s \) with is the direct integral of spaces \( R^s(m) \), i.e.

\[ R^s = \int \oplus R^s(m) g^s(m^2) dm^2, \] (2.1)

where function \( g^s(m^2) \) is not equal to zero only within the interval \( [m_1^2, m_2^2] \) which characterizes the spread (indefinite) of mass of a particle.

According to (2.1) each vector from \( R^s \) can be represented as

\[ \Psi^s(t, \vec{x}) = \int \oplus \Psi^s(t, \vec{x}, m) g^s(m^2) dm^2, \] (2.2)

\[ \Psi^2(t, \vec{x}, m) \in R^s(m), \quad \vec{x} \equiv (x_1, x_2, x_3), \]

\[ P_\mu \Psi^s(t, \vec{x}, m) = m^2 \Psi^s(t, \vec{x}, m), \quad \mu = 0, 1, 2, 3, \] (2.3)
\[
P^2 \Psi^s(t, \vec{x}) = \int \otimes m^2 \Psi^s(t, \vec{x}, m) g^s(m^2) dm^2.
\]

The generators of the Poincaré group on vectors (2.2) are defined in such a way
\[
P_\mu \Psi^s(t, \vec{x}) = \int \otimes P_\mu \Psi^s(t, \vec{x}, m) g^s(m^2) dm^2,
\]

\[
J_{\mu\nu} \Psi^s(t, \vec{x}) = \int \otimes J_{\mu\nu} \Psi^s(t, \vec{x}, m) g^s(m^2) dm^2.
\]

The Dirac equation for the function \(\Psi^{s=1/2}(t, \vec{x})\) is:
\[
\left(i \gamma^0 p_0 + i \gamma^k p_k - \sqrt{p^2_\mu}\right) \Psi^{s=1/2}(t, \vec{x}) = 0.
\]

One can easily see now that (2.7) can be reduced to the usual Dirac equation if one formally replaces the function \(g^{s=1/2}(m^2)\) in (2.2) by \(\delta(m^2 - m_0^2)\). The generators of \(P(1,3)\) group defined by (2.5) and (2.6) on the manifold of solutions of eq. (2.7) are given by (1.4), where
\[
P_0 \equiv H \equiv \alpha_k p_k + \beta \sqrt{p^2_\mu}.
\]

We can write down the equation of motion for a particle with indefinite mass, which interacts with the external electromagnetic field in form
\[
\left(i \gamma^0 \pi_0 + i \gamma^k \pi_k - \sqrt{\pi^2_\mu}\right) \Psi^{s=1/2}(t, \vec{x}) = 0,
\]
where \(\pi_\mu \equiv p_\mu - eA_\mu\). It is clear that equation (2.9) essentially differs from the usual Dirac equation which describes the motion of a particle with fixed mass in the electromagnetic field. A detailed analysis of equation (2.9) will be performed in a forthcoming work.

Lurcat [8] pointed out, that interpretation of function \(\Psi^s(t, \vec{x})\) as a wave function of particle is not correct.

More appropriate is to characterize the unstable system by the density matrix (operator). In the Schrödinger picture the equation of motion for the density matrix looks like
\[
i \frac{\partial \rho}{\partial t} = [H, \rho],
\]
where \(H\) is defined by (2.8).

Equation (2.7) as well as the usual Dirac equation, is \(P^-, T^-, C\)-invariant.

\[\text{§ 3. Equation for the flat particle and } T^-, C\text{-invariance}\]

To clear up how can extend the obtained above (sec. 1) results upon any arbitrary group \(P(1,2n+1)\) let us consider in this section equations of motion which are invariant under \(P(1,2)\) group (the group of rotations and translations in three-dimensional Minkowski space).

The simplest equations invariant under \(P(1,2)\) are:
\[
H^+ \Psi^+(t, x_1, x_2) = i \frac{\Psi^+(t, x_1, x_2)}{\partial t},
\]

(3.1)
\[ H^{-} \Psi^{-}(t, x_1, x_2) = i \frac{\Psi^{-}(t, x_1, x_2)}{\partial t}, \quad (3.2) \]

\[ H^{\pm} = \alpha_k p_k \pm \beta \kappa, \quad k = 1, 2, \]

\[ \alpha_1 = \sigma_1, \quad \alpha_2 = \sigma_2, \quad \beta = \sigma_3, \quad p_k = -i \frac{\partial}{\partial x_k}, \quad (3.3) \]

Here \( \Psi(t, x_1, x_2) \) is a two-component spinor, and \( \sigma_1, \sigma_2, \sigma_3 \) are Pauli matrices.

Taking into account that in this case

\[ \tau^p = a^p \cdot 1 + \vec{a}^p \sigma, \quad \tau^w = a^w \cdot 1 + \vec{a}^w \sigma, \quad \tau^c = a^c \cdot 1 + \vec{a}^c \sigma \quad (3.4) \]

and arguing in a way similar to that of sec. 1, we reveal that equation (3.1) or (3.2) is \( T^p, T^w \)- and \( PTC \)-noninvariant but \( P \)- and \( C \)-invariant.

Equation

\[ H \Psi(t, x_1, x_2) \equiv \Psi(t, \vec{x}) = \begin{pmatrix} \Psi^+(t, \vec{x}) \\ \Psi^-(t, \vec{x}) \end{pmatrix}, \quad H = \tilde{\alpha}_k p_k + \tilde{\beta} \kappa, \quad k = 1, 2, \]

\[ \tilde{\alpha}_k = \begin{pmatrix} \alpha_k & 0 \\ 0 & \alpha_k \end{pmatrix}, \quad \tilde{\beta} = \begin{pmatrix} \sigma_3 & 0 \\ 0 & \sigma_3 \end{pmatrix}, \quad (3.5) \]

is \( T^p, T^w \) and \( C \)-invariant as well as equation (1.16) is, i.e. it is \( PTC \)-invariant, and for matrices and \( \tau^p, \tau^w \) we have

\[ \tilde{\tau}^p = \begin{pmatrix} 0 & \sigma_3 \\ \sigma_3 & 0 \end{pmatrix}, \quad \tilde{\tau}^w = \begin{pmatrix} 0 & \sigma_2 \\ \sigma_2 & 0 \end{pmatrix}, \quad \tilde{\tau}^c = \begin{pmatrix} \sigma_1 & 0 \\ 0 & \sigma_1 \end{pmatrix}. \quad (3.6) \]

Thus equations of (1.1), (3.1) type and a whole class of equations of Bargman–Wigner type which are derived from the equations of (1.1) type are invariant under the limited groups:

\( P(1, 2) \) are \( T^p, T^w, T^w C \)-noninvariant and \( C \)-invariant;

\( P(1, 4) \) are \( T^p, C, T^w C \)-noninvariant and \( T^w, T^p C \)-invariant;

\( P(1, 6) \) are \( T^p, T^w, T^p C, T^w C \)-noninvariant and \( C \)-invariant;

\( P(1, 8) \) are \( T^p, T^w, T^w C \)-noninvariant and \( T^w, T^p C \)-invariant.

To prove the assertions given above in the case of arbitrary \( P(1, 2n + 1) \) group one has to carry out the very similar procedure to that we employed for \( P(1, 4) \) group and to use the fact that Dirac matrices \( \gamma^{(2n+1)} \) of group \( P(1, 2n) \) are related with those \( \gamma^{(2n-1)} \) of group \( P(1, 2n - 2) \) by

\[ \begin{pmatrix} \gamma^{(2n+1)}_\mu, \gamma^{(2n+1)}_\nu, \gamma^{(2n+1)}_{2n+1} \end{pmatrix} = \begin{pmatrix} \gamma^{(2n-1)}_\mu \otimes \sigma_2, 1 \otimes \sigma_3, 1 \otimes \sigma_1 \end{pmatrix}, \]

\( \mu = 0, 1, \ldots, 2n - 1. \)

Putting in (3.1) and (3.2) \( \kappa = 0 \) one sees that equation (3.1) coincides with (3.2) and such equation is \( C, T \)-invariant, and \( \tau^p = \sigma_3, \tau^w = \sigma_2. \)
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