Mapping the 3D Kinematical Structure of the Gas Disk of HD 169142

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Abstract

The disk around HD 169142 has been suggested to host multiple embedded planets due to the range of structures observed in the dust distributions. We analyze archival Atacama Large (sub-) Millimetre Array observations of 12CO (2–1), 13CO (2–1), and C18O (2–1) to search for large-scale kinematic structures associated with other embedded planets in the outer disk. At 125 au, we identify a coherent flow from the disk surface to the midplane, traced by all three CO isotopologues, and interpret it as a meridional flow potentially driven by an embedded planet. We use changes in the rotation speed of the gas to characterize the physical structure across this region, finding that at 125 au the CO emission traces regions of increased gas pressure, despite being at a surface density minimum. Developing a simple analytical model, we demonstrate that the physical structure of the gap can have non-trivial responses to changes in the surface density, consistent both with previous thermo-chemical models and the conditions inferred observationally. Applying this technique to a range of sources will allow us to directly confront theoretical models of gap-opening in protoplanetary disks.

Unified Astronomy Thesaurus concepts: Protoplanetary disks (1300); Submillimeter astronomy (1647); Planetary-disk interactions (2204)

1. Introduction

With the Atacama Large (sub-) Millimetre Array (ALMA), we have the ability to characterize the physical and chemical structure of protoplanetary disks, the formation location of exoplanets. Particularly, spatially and spectrally resolved molecular-line emission enables us to study the gas structure of the disk.

The dynamical structure of the disk encodes information about any potential planet–disk interactions, as embedded planets are predicted to drive large perturbations in the gas-velocity structure during their formation (e.g., Perez et al. 2015; Pérez et al. 2018; Pinte et al. 2019; Disk Dynamics Collaboration et al. 2020; Bae et al. 2021). The line-of-sight velocity, \(v_{\text{LOS}}\), of the gas, is a combination of the systemic velocity, \(v_{\text{LSR}}\), and the internal motions of the disk, including the rotational velocity, \(v_{\text{rot}}\), radial velocity, \(v_{r}\) and vertical velocity, \(v_{z}\), given by
\[
\begin{align*} 
    v_{\text{LOS}} = v_{\text{rot}} \sin(i) \cos(\phi) + v_{r} \sin(i) \sin(\phi) + v_{z} \cos(i) + v_{\text{LSR}}, 
\end{align*}
\]
where \(\phi\) is the azimuthal angle in the frame of reference of the disk, \(i\) is the inclination of the disk. If we assume that the disk is azimuthally symmetric, then we can disentangle the velocity structure of the disk according to the different dependence on \(\phi\) (e.g., Teague et al. 2019; Disk Dynamics Collaboration et al. 2020).

As protoplanetary disks are expected to be in hydrostatic equilibrium, the rotational velocity, \(v_{\text{rot}}\), is closely linked to the physical structure of the disk (e.g., Rosenfeld et al. 2012), through
\[
\begin{align*} 
    \frac{v_{\text{rot}}^{2}}{r} = \frac{G M_{\text{star}} r}{(r^{2} + z^{2})^{3/2}} + \frac{1}{\rho_{\text{gas}}} \frac{\partial P}{\partial r}, 
\end{align*}
\]
where \(P = n_{\text{gas}} k T\) is the gas pressure, \(\rho_{\text{gas}} = \mu_{\text{gas}} n_{\text{gas}}\) is the gas density, and \(\mu_{\text{gas}}\) is the mean molecular mass of the gas. As embedded planets are predicted to open large gaps in the gas surface density (e.g., Papaloizou & Lin 1984), leading to large radial changes in the gas pressure gradient, we therefore expect to see variations in the rotation speed of the gas if there are massive enough embedded planets (Kanagawa et al. 2015b). Thermo-chemical modeling by Rab et al. (2020) showed that this variation in pressure arises to changes in both the gas density and temperature.

The radial velocity, \(v_{r}\), and vertical velocity, \(v_{z}\), depend on any internal, large-scale gas flows within the disk. One such flow is the meridional flow, where the disk viscously spreads to “fill in” large gaps in the gas surface density, including that associated with embedded planets (Morbidelli et al. 2014; Szulágyi et al. 2014; Fung & Chiang 2016). Using 12CO observations of the disk around HD 163296, Teague et al. (2019) detected meridional flows at the radial location of two gaps in the distributions of mm-sized grains and at the radial location of a previously inferred planet (Pinte et al. 2018a), arguing that a planetary origin was the most likely scenario.

In this work, we study the velocity structure of the disk of HD 169142, a Herbig Ae star (The et al. 1994) with a stellar mass of 1.65 ± 0.05 \(M_{\odot}\) (Carney et al. 2018), an age of \(\sim 10\) Myr (Pohl et al. 2017), and at a distance of \(d = 113.6 ± 0.8\) pc \(^7\) (Bailer-Jones et al. 2018; Gaia Collaboration et al. 2018). The disk is observed almost at a face-on orientation, with an inclination \(i = 13^\circ\) (Raman et al. 2006) and with a position angle of \(\text{PA} = 5^\circ\) (Fedele et al. 2017).

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\(^7\) We note that with Gaia EDR3, the distance has been updated to 114.9 pc (Gaia Collaboration et al. 2021). This change in distance of \(\sim 1\) pc will result in a change of only \(\sim 1\%\) of the derived stellar mass.
This source is of particular interest as both millimeter continuum and near-infrared (NIR) observations, tracing mm-sized grains and sub-μm grains, respectively, have revealed a variety of structures (e.g., Quanz et al. 2013; Reggiani et al. 2014; Biller et al. 2014; Monnier et al. 2017; Ligi et al. 2018; Macías et al. 2017, 2019) in the disk dust distribution indicative of embedded planets. Two major ring-like structures, located at radii \( \sim 0.022 \) (\( \sim 25 \) au; B25) and \( \sim 0.053 \) (\( \sim 60 \) au; B60), have been identified by both millimeter continuum and near-IR observations (e.g., Osorio et al. 2014; Fedele et al. 2017; Macías et al. 2017; Bertrang et al. 2018; Carney et al. 2018; Pérez et al. 2019; Macías et al. 2019). With higher angular resolution observations, Pérez et al. (2019) observed that B60 was actually composed of three narrow rings. Two dust-depleted regions were observed: an inner cavity (\( r \lesssim 20 \) au; Fedele et al. 2017; D10) and a gap centered at \( \approx 41 \) au (Fedele et al. 2017, D41) bounded by B25 and B60. In terms of the gas distribution, Fedele et al. (2017) observed depletions of CO isotopologue emission in D41, but not in D10, attributing them to drops in CO column density. The authors were unable to distinguish whether these CO column density drops reflected a gas surface density depletion or a CO abundance depletion.

One possible scenario for explaining the creation of these rings and gaps is planet–disk interactions (Fedele et al. 2017; Bertrang et al. 2018; Macías et al. 2019). Given that the density drops of CO isotopologues are only observed in D41, not in D10, and given the lack of azimuthal asymmetries in the two dust rings, B25 and B60, Fedele et al. (2017) inferred that two planets of masses of \( \sim 0.1–1 M_{\text{Jup}} \) and \( \sim 1–10 M_{\text{Jup}} \) in D10 and D41, respectively, are needed to explain the observed surface density depletion. More recent hydrodynamic simulations published by Bertrang et al. (2018) suggested that one planet might not be sufficient to open up a gap as wide as D41 (width \( \sim 20 \) au), arguing that two \( 1 M_{\text{Jup}} \) planets would better reproduce the observations. Besides, hydrodynamic simulations by Toci et al. (2020) were able to reproduce observed long-lived dust rings between two giant planets, with masses of \( \sim 2.4 M_{\text{Jup}} \) at 17.4 and 50 au. In the outer regions of the disk, Pérez et al. (2019) found the triple-ring structure they observed might relate to the formation of an embedded mini-Neptune-sized planet at \( \sim 65 \) au based on their hydrodynamic simulations.

Besides rings and gaps, other structures have been observed, suggestive of embedded planets. A blob was observed with NIR-scattered light observations at 36.4 au, with a rotation speed of \( -2.08 \pm 0.25 \) yr\(^{-1} \), which might relate to a \( 2.2^{+1.4}_{-0.8} M_{\text{Jup}} \) still-accreting planet at about 38 au. This plane could also be responsible for carving the D41 and exciting a spiral-like structure observed within B25 and B60 (Gratton et al. 2019).

In Bertrang et al. (2020), a time-variable surface brightness dip was found spanning several observations covering 6 yr. The dip is located in B25, with a rotation speed of \( \sim 6^{+8}_{-6} \) yr\(^{-1} \).

Based on the width of the shadow, Bertrang et al. (2020) suggested that the dip could be due to a \( \sim 1–10 M_{\text{Jup}} \) planet at \( \sim 12 \) au.

Given that there is strong evidence for multiple embedded planets in the inner disk around HD 169142, we explore the dynamic structure of the disk to search for kinematic evidence of embedded planets in the outer disk (i.e., \( \gtrsim 80 \) au), regions that are inaccessible when studying the dust distributions. We measured three-dimensional velocity structures of different layers of the gas in this disk, traced by \(^{12}\text{CO} \) (2–1), \(^{13}\text{CO} \) (2–1), and \(^{18}\text{O} \) (2–1) emission, which is described in Section 3. In Section 4, we use an analytical disk model to estimate the perturbations in the gas density based on changes in the gas rotational velocity. We discuss the findings in Section 5, and summarize in Section 6.

### 2. Observations

We combine observations from three archival ALMA projects, with details given in Table 1. These observations all target the (2–1) transition of the three main CO isotopologues, \(^{12}\text{CO} \), \(^{13}\text{CO} \), and \(^{18}\text{O} \). Each archival project was calibrated using the scripts provided by the ALMA Archive and the required version of CASA (McMullin et al. 2007), before transferring to CASA v5.8.0 for self-calibration and imaging.

#### 2.1. Self-calibration and Imaging

Each execution block was first imaged, then the phase center measured using the imfit task in CASA. These phase centers allowed all execution blocks to be centered using the fixvis command, before updating a common phase center for all execution blocks using the fixplanets command to account for any proper motion of the source. Then, each project was self-calibrated individually, following the procedure described in Andrews et al. (2018). Only continuum-based bands and line-free channels were considered. Numerous phase solutions were used, starting at infinity and decreasing to 10 s, or stopping sooner when the signal-to-noise of the data did not improve. A single round of amplitude self-calibration was performed for each project with an infinite solution interval. The self-calibration improved the signal-to-noise ratio of the continuum by factors of 2, 3, and 4 for the 2013.1.00592, 2015.1.00490, and 2015.1.01301.S projects, respectively. The solutions were applied to the spectral-line data before the continuum being subtracted using the uvcontsub task.

Imaging of the continuum and spectral-line data combined all three projects. Briggs weighting was chosen with a robust value of 0.5 which was found to give a good tradeoff between spatial resolution and sensitivity, yielding a synthesized beam size of \( 0.045 \times 0.089 \) (53.5") for the continuum, \( 0.0175 \times 0.00175 \) (60") for \(^{12}\text{CO} \), \( 0.0190 \times 0.0140 \) (61") for \(^{13}\text{CO} \), and \( 0.0191 \times 0.0146 \) (57") for \(^{18}\text{O} \). The channel spacing was set to 165 m s\(^{-1} \) due to the coarser spectral resolution of the 2015.1.01301.S data.
images were masked using a Keplerian mask\(^8\) assuming literature values, including stellar mass, inclination, and position angle (PA) for the system. The mask was enlarged through convolution of a \(1''\) circular kernel to ensure all emission was covered by the mask. Images were made using the “multiscale” algorithm adopting pixel scales of \((0, 6, 12, 18, 24)\), and were CLEANed down to a \(3\sigma\) level, where \(\sigma\) was the rms measured in a line-free channel. The rms is \(52.9\ \mu\text{Jy beam}^{-1}\) for the continuum, \(1.1\ \mu\text{Jy beam}^{-1}\) for both \(^{12}\text{CO}\) and \(^{13}\text{CO}\), and \(0.8\ \mu\text{Jy beam}^{-1}\) for \(^{13}\text{CO}\). To account for the mismatches in the line units of the model images and the residuals, we apply the “JvM” correction proposed in Jorsater & van Moorsel (1995, Appendix A) and described in more detail in Czekala et al. (2021). For the continuum data, we adopt the same imaging properties, and clean down to \(3\sigma\) where \(\sigma\) was measured from continuum-free regions offset from the center.

\[\text{2.2. Results}\]

We show the continuum map in Figure 1(a), and calculate its azimuthally averaged radial profile with the GoFish\(^9\) (Teague 2019a) package, shown in Figure 1(b). The shaded region in the radial profile shows the azimuthal scatter in each radial bin. We label the two major rings, B25 and B60, and the two major rings of dust depletion, D10 and D41, in the radial profile.

We calculate the moment 0 (velocity-integrated intensity) map of \(^{12}\text{CO} (2-1), ^{13}\text{CO} (2-1)\) and \(^{13}\text{CO} (2-1)\) with the bettermoments\(^10\) (Teague & Foreman-Mackey 2018) package, using a clip of \(2\times\text{rms}\), shown in Figure 2(a). Their radial profiles are shown in Figure 2(b). We also calculate the brightness temperature maps by measuring the peak values of the line spectra and apply Planck’s law. The maps and their radial profiles are shown in Figures 2(c) and (d).

We then calculate the line-of-sight velocity maps using the bettermoments package and employing the Gaussian method for all three CO isotopologues, shown in Figure 3. The Gaussian method fits a Gaussian profile to each pixel to measure the line center, \(v_{\text{LOS}}\). We have compared different methods for calculating the \(v_{\text{LOS}}\) maps and found that the Gaussian method provides the lowest statistical uncertainties on the measured \(v_{\text{LOS}}\), based on the uncertainties returned from bettermoments. More details on the comparison of different methods can be found in Appendix A.

\[\text{3. Measuring the Three-dimensional Velocity Structure}\]

In this section, we disentangle the 3D velocity structure of the disk from the measured line-of-sight velocity map following Teague et al. (2018a, 2018b, 2019). We extract perturbations in the rotational velocity and map out large-scale gas flows in the radial and vertical direction.

\[\text{3.1. Method}\]

\[\text{3.1.1. General Source Properties}\]

In order to accurately measure the profiles for three-dimensional velocities, we need geometrical properties, e.g., inclination, positional angle, of the disk to properly deproject the data cubes and split them into annuli of constant radius. We fit the projected line-of-sight velocities, \(v_{\text{LOS}}\), with a Keplerian velocity structure to measure the needed geometrical properties.

We use the eddy\(^11\) (Teague 2019b) package to fit a Keplerian rotation model, i.e., Equation (2), without the pressure-gradient term, to the velocity maps. As HD 169142 is observed at a near face-on orientation \((i = 13^\circ; \text{Raman et al. 2006})\), we assume that the disk is geometrically thin, i.e., setting \(z = 0\). This assumption results in an inferred dynamical mass slightly higher than the true stellar mass as we do not account for the vertical dependence of the rotation (e.g., Rosenfeld et al. 2012). If the emission traces a constant \(z/r\) across the radius of the disk, then the dynamical mass will be underestimated by a factor of \(1 + (z/r)^2\)^{-3/2}.

We use a Markov Chain Monte Carlo (MCMC) method with 256 walkers, 2000 burn-in steps, and 10,000 steps to estimate the posterior distributions of disk-center offset relative to the image center, \((\Delta x, \Delta y)\), PA, dynamical mass \(M_{\text{dyn}}\), and systemic velocity

\[\text{Figure 1. An overview of the dust observation data. Panel (a) shows the continuum map, while panel (b) shows its radial profile. The two major rings, B25 and B60, and the two major regions of dust depletion, D10 and D41, found in previous studies are labeled in panel (b). The shaded region in the radial profile shows the azimuthal scatter in each radial bin.}\]

\[\text{\(8\) https://github.com/richteague/keplerian_mask}\]

\[\text{\(9\) https://github.com/richteague/gofish}\]

\[\text{\(10\) https://github.com/richteague/bettermoments}\]

\[\text{\(11\) https://github.com/richteague/eddy}\]
The best-fit models for each CO isotopologue are described in Table 2. The values shown are the median of the posterior distributions, with statistical uncertainties given by the 16th to 84th percentile range (note, however, that the statistical uncertainties will substantially underpredict the true uncertainties which are rather likely dominated by systematic uncertainties associated with the choice of model, i.e., a Keplerian rotation model). The values we get from the three CO isotopologues are consistent among one another, suggesting that the values we derive are robust.

3.1.2. Measuring Rotational, Radial, and Vertical Velocities

To decompose the projected line-of-sight velocities, \( v_{\text{LOS}} \), into their cardinal components, we follow the method outlined in Figure 2. An overview of the gas observation data. Panels (a) and (c) show the moment 0 maps and the brightness temperature maps of \( ^{12}\text{CO} \) (2–1), \( ^{13}\text{CO} \) (2–1) and \( ^{18}\text{O} \) (2–1), respectively, while panels (b) and (d) show their radial profiles, respectively. The shaded region in each radial profile shows the azimuthal scatter in each radial bin.

Figure 2. An overview of the gas observation data. Panels (a) and (c) show the moment 0 maps and the brightness temperature maps of \( ^{12}\text{CO} \) (2–1), \( ^{13}\text{CO} \) (2–1) and \( ^{18}\text{O} \) (2–1), respectively, while panels (b) and (d) show their radial profiles, respectively. The shaded region in each radial profile shows the azimuthal scatter in each radial bin.

Figure 3. Line-of-sight velocity maps of \( ^{12}\text{CO} \) (2–1), \( ^{13}\text{CO} \) (2–1), and \( ^{18}\text{O} \) (2–1).
in Teague et al. (2018a, 2018b, 2019). In essence, we are able to
disentangle the three velocity components due to their
different dependence on the disk azimuthal angle, \( \phi \). We first
use the GoFish package to measure the azimuthally averaged
profiles for the rotational velocity, \( v_{\text{rot}} \), and the radial velocity,
\( v_{\text{rad}} \). This first splits the data cube into annuli each 25 mas wide,
roughly a quarter of the beam, based on the geometrical
properties shown in Table 2. In each annulus, spatially
independent spectra are shifted to a common velocity given a
\( \{ v_{\text{rot}}, v_{\text{rad}} \} \) tuple. The aligned spectra are compared to a
Gaussian process (GP) model to extract a goodness of fit. The
best-fit values for \( v_{\text{rot}} \) and \( v_{\text{rad}} \) should minimize the variance in
residuals between the average spectrum and the GP model. As
the vertical velocity, \( v_z \), has no dependence on \( \phi \), it will not
contribute to this variance. We use MCMC with 32 walkers,
500 burn-in steps, and 500 steps on each annulus to explore the
posterior distributions of model parameters of \( v_{\text{rot}} \) and \( v_{\text{rad}} \)
to estimate the best-fit values. To better characterize the range of
velocity profiles consistent with the data, we run multiple
instances of the above fitting procedure, each time selecting a
random set of independent pixels and taking the mean and
standard deviation of the ensemble of samples as the best-fit
value and associated uncertainty (as in Kepler et al. 2019).

The final profile is a combination of 25 unique pixels
selections. Appendix B.1 describes in more detail how the
number of independent samples was chosen.

We then estimate the profiles of vertical velocity, \( v_z \), in a
different way than Teague et al. (2019). In Teague et al. (2019),
the line center of the velocity-corrected and stacked line
profiles is determined by fitting a Gaussian profile. In this
work, following Equation (1), subtracting the inferred \( v_{\text{los}} \)
and \( v_{\text{rad}} \) profiles, together with the \( v_{\text{lsr}} \), from the \( v_{\text{los}} \) map will
leave a residual map of \( v_z \) values. We then make an azimuthally
averaged radial profile of this residual map to measure the
radial profile of \( v_z \). This approach is preferable to the approach
used in Teague et al. (2019) as we circumvent any issues
associated with asymmetries introduced in the line profiles
from poor constraints on \( v_{\text{los}} \) or \( v_{\text{rad}} \) (see the discussion on
asymmetric line profiles in the disk in Teague & Loomis 2020).
It was verified for the case of HD 169142 that, as there was no
asymmetry in the line profiles, both methods returned
comparable profiles for \( v_z \).

### 3.2. Results

The resulting velocity profiles are shown in Figure 4. The
shaded areas show the uncertainties of each profile. The first,
third, and fourth rows show the profiles for the rotational
velocity, \( v_{\text{rot}} \), radial velocity, \( v_{\text{rad}} \), and vertical velocity, \( v_z \),
respectively. The second row shows the perturbations in \( v_{\text{rot}} \) as
a percentage of the background rotational velocity, \( \delta v_{\text{rot}} \). Note
that all the velocity profiles start at around 50 au. This is
because these sort of kinematic techniques are only possible at
radii more than twice the beam major axis away from the
center, which was tested with forward models in Teague et al.
(2018a). For current observations, this is equivalent to between
40 and 45 au.

To identify the perturbations, \( \delta v_{\text{rot}} \) we implement a Butter-
worth low-pass filter, with a cut-off of 16 samples (~83 au) and
an order of 12, to extract a smooth background model of \( v_{\text{rot}} \).
Teague et al. (2019) shows that assuming different background
models will lead to subtle differences in the low-frequency
(i.e., large spatial scale) perturbations, although high-frequency
perturbations (small spatial scale features) persist. The filter
 technique used here will minimize such risk as it distinguishes
“background” and “perturbation” based on their spatial
frequency rather than the assumption that the background can
be well described by an analytical model. Appendix B.2
discussed this in more detail.

As shown in the second row of Figure 4, this approach
reveals perturbations in \( v_{\text{rot}} \) on scales of tens of au with
magnitudes of around 1%–2% of the background rotation.

| \( ^{12}\text{CO} \) (2–1) | \( ^{13}\text{CO} \) (2–1) | \( ^{13}\text{CO} \) (2–1) |
|-----------------|-----------------|-----------------|
| \( \Delta x \) (mas) | \( \Delta y \) (mas) | \( \Delta z \) (mas) |
| 10.5\( ^{+0.3}_{-0.3} \) | 18.1\( ^{+0.5}_{-0.5} \) | 16.6\( ^{+0.4}_{-0.4} \) |
| 15.7\( ^{+0.3}_{-0.3} \) | 19.6\( ^{+0.6}_{-0.6} \) | 24.3\( ^{+0.4}_{-0.4} \) |
| 5.3\( ^{+0.02}_{-0.02} \) | 5.3\( ^{+0.03}_{-0.03} \) | 5.45\( ^{+0.03}_{-0.03} \) |
| 0.393\( ^{+0.001}_{-0.001} \) | 1.393\( ^{+0.001}_{-0.001} \) | 1.423\( ^{+0.001}_{-0.001} \) |
| \( \delta v_{\text{rot}} \) (km s\(^{-1} \)) | \( \delta v_{\text{rot}} \) (km s\(^{-1} \)) | \( \delta v_{\text{rot}} \) (km s\(^{-1} \)) |
| 6.944\( ^{+0.002}_{-0.002} \) | 6.951\( ^{+0.003}_{-0.003} \) | 6.948\( ^{+0.003}_{-0.003} \) |

Note. The values shown are the median values of the posterior distributions, and the statistical uncertainties are given by the 16th to 84th percentile range.
Figure 4. Velocity profiles of $^{12}$CO (2–1), $^{13}$CO (2–1), and C$^{18}$O (2–1), are shown in the left, middle, and right columns, respectively. The first, third, and forth rows show the profiles for the rotational velocity, $v_{\text{rot}}$, radial velocity, $v_{\text{rad}}$, and vertical velocity, $v_{\text{z}}$, respectively. The second row shows the perturbations in $v_{\text{rot}}$ as a percentage of the background rotational velocity, $v_{\text{rot}}$. The orange crosses and dotted lines in the $v_{\text{rot}}$ profiles show the indicated local pressure minima. The shaded areas in each profile show the uncertainties.

sound speed when it is indicated to be $<20$ K. Panels (a), (b), and (c) of Figure 5 show the gas flows in the $(r, \phi)$ plane traced by the three CO isotopologues. Arrows pointing upward represent super-Keplerian motion, while arrows pointing downward show sub-Keplerian motion. The color of the background shows the magnitude of the perturbations of the rotational velocity relative to the background rotation. We can see that the perturbations of the rotation velocities of the three CO isotopologues are roughly consistent with each other. Note that at around 200 au, the perturbations of $^{12}$CO and $^{13}$CO are misaligned with each other. This is potentially due to the inability of estimating of the emission height, as this disk is observed almost at a face-on orientation, resulting in an incorrect calculation of radial distance, $r$.

Figure 6 shows the gas flows in the $(r, z)$ plane traced by all three CO isotopologues. Given that we are not able to extract the emission height due to the face-on geometry of the system, we assume emission heights based on the disk models shown in Fedele et al. (2017): for $^{12}$CO (2–1), $z/r = 0.26$; for $^{13}$CO (2–1), $z/r = 0.18$; and for C$^{18}$O (2–1), $z/r = 0.14$. These values of emission heights are broadly consistent with those observed in other sources, such as for the disk around IM Lup (Pinte et al. 2018b; Law et al. 2021). Note that the values of the emission height used here do not affect the inferred velocity structure; they are merely used to plot the figure. In Figure 6, we can clearly see collapsing gas flows around 125 au (indicated by a black dotted box), and tentatively 210 au, reminiscent of meridional flows (Szulágyi et al. 2014). Around these locations, gas flows toward a common center and downward toward the disk midplane. Both locations are well beyond the outer edge of the continuum emission and so unaffected by any continuum subtraction. Strikingly, we see coherent flows traced by all three CO isotopologues at 125 au—the first time-coherent flows have been traced across a range of heights in the disk. The interpretation of these flows will be discussed in Section 5.

4. Inferring the Perturbed Physical Structure

To account for the deviations observed in the rotational velocity (Figure 4, second row), we require perturbations in the gas number density, temperature, or emission height, e.g., Equation (2). In reality, this is likely a combination of all three properties, requiring full thermo-chemical modeling (e.g., Rab et al. 2020). As a first step, we infer the perturbations in each component, assuming that only one component is perturbed at a time, as in Teague et al. (2018b).

4.1. Method

For a geometrically thick disk, the rotational velocity $v_{\text{rot}}$ is given by Equation (2). To account for the deviations observed in $v_{\text{rot}}$, we need perturbations in either the CO emission height, $z_{\text{CO}}$, or the background gas density (here the total gas density, not just CO gas) and temperature at the heights traced by the CO isotopologue emission, $n$(H$_2$)$_{z=\text{CO}}$ and $T_{z=\text{CO}}$, respectively.

For temperature, $T_{z=\text{CO}}$, we assume that all three isotopologues are optically thick such that we can fix the temperature to the observed brightness temperature shown in Figures 2(c) and
Note that even in the case the lines are not optically thick, their intensities (or brightnesses) should still be linearly dependent on the temperature, and thus will not change the magnitude of the perturbations relative to their background value. For a more robust numerical differentiation, we require a smoothly varying model of $T_{\text{rot}}$ otherwise small noise spikes will manifest as spurious features in the pressure gradient and thus the velocity profile. We use a Savitzky–Golay filter with a window of 9 data points ($\sim$47 au) and polynomial order of 5 to remove the high-frequency noise in the observed $T_{\text{B}}$ profiles before using cubic interpolation to extract an interpolated model. Note that the process will not smooth out real

Figure 5. Panels (a), (b), and (c) represent gas flows in the $(r, \phi)$ plane of the three CO isotopologues. The color of the background shows the magnitude of the perturbations in the rotational velocity. A vector at the bottom right in each panel shows $0.1c_s$.

Figure 6. Gas flows in the $(r, z)$ plane of the three CO isotopologues. The black dotted box indicates the location of the coherent collapsing gas flow at around 125 au. A vector at the bottom right shows $0.1c_s$. 
perturbations originated in the observed $T_B$ profiles. It only removes high-frequency signals that have a much smaller scale than the beam size, and are thus noise.

For $n(H_2)_{2-12CO}$ and $z_{2CO}$, we construct models of the rotational velocity by considering smooth “background” models, each of which are perturbed with a sum of multiple Gaussian components. We refer to this sum of Gaussian components as the “perturbation.” (following Teague et al. 2018b, for example).

For the smooth background of emission height, $z_{2CO}$, we model it as having a constant $z/r$ for each isotopologue. We adopt the values described in Section 3.2: $^{12}$CO (2–1), $z_{bkg}/r = 0.26$; $^{13}$CO (2–1), $z_{bkg}/r = 0.18$; C$^{18}$O (2–1), $z_{bkg}/r = 0.14$.

For the smooth background of the density profile, $n(H_2)_{2-12CO}$, we opt to use a tapered power law,

$$n_{bkg}(r) = n_0 \left( \frac{r}{100 \, \text{au}} \right)^{q_{\text{nl}}} \exp \left[ - \frac{r}{r_{\text{exp}}} \right]^{-q_{\text{nl}}},$$

which was found through testing various analytical forms to provide the best tradeoff between flexibility and a minimal number of free parameters: $q_{\text{nl}}$, $q_{\text{nl}}$, $r_{\text{expr}}$, and $n_0$. Given that $n_0$ in Equation (3) is canceled out during the calculation of the modeled $v_{\text{rot}}$, we are unable to constrain the absolute scaling of $n_{bkg}(r)$. Hence, we use normalized values for $n(H_2)_{2-12CO}$ profiles.

We model the perturbation vector, $\delta(r)$, as the summation between 6 and 10 Gaussians,

$$\delta(r) = 1.0 + \sum_{i=1}^{k} \left\{ A_i \exp \left[ -0.5 \left( \frac{r-r_i}{d_i} \right)^2 \right] \right\}. \quad (4)$$

The numbers of Gaussian components used, $k$, depend on the numbers of the perturbations seen in the $\delta_{v_{\text{rot}}}$ profiles. For $^{12}$CO (2–1), $k = 11$; for $^{13}$CO (2–1), $k = 7$; for C$^{18}$O (2–1), $k = 6$. We multiply the perturbations, $\delta(r)$, with the background models to construct the fully perturbed models. We are then able to calculate the perturbed $v_{\text{rot}}$ profile from the perturbed model of $n(H_2)_{2-12CO}$ or $z_{2CO}$ through Equation (2). For the calculation of $v_{\text{rot}}$, we calculate the pressure profile on a radial grid that is sampled at a rate 10 times higher than the observed values, such that we can avoid any finite-differencing issues in the calculation of the gradient.

To obtain the best-fit values of the free parameters in the perturbed models of $n(H_2)_{2-12CO}$ or $z_{2CO}$, we first manually find reasonable initial values for these parameters. Then we use the dynasty12 package (Speagle 2020), which implements dynamic nested sampling (Higson et al. 2019) to explore the posterior distributions of the parameters around their initial values consistent with the observed $v_{\text{rot}}$ profiles. We use dynamic nested sampling instead of MCMC methods for the following reasons. First, nested sampling is more robust than MCMC methods when sampling complex, multi-modal distributions (e.g., Allison & Dunkley 2014; Speagle 2020), such as the parameter space here. Second, dynamic nested sampling can be much more efficient than static nested sampling given that it can dynamically allocate the number of live points (analogous to walkers in an MCMC approach) during a run. This enables us to obtain the highest accuracy per unit running time, which is particularly important when the total computational costs are high due to, e.g., high dimensionality of the parameter space (to fully model the perturbed density, we need around 22–37 free parameters, leading to prohibitive computational costs).

Although we model our gas density, emission height as the product of a smooth background and a perturbation term, these two components are not necessarily the same two components extracted when using a filtering technique as was used to identify perturbations in the $v_{\text{rot}}$ profile. Using the same filtering technique on our model output, we are then able to split our model profiles into analogous background and perturbation vectors such that we are only sensitive to the high-frequency perturbations. Figure 7 demonstrates this idea. Panel (a) shows the normalized modeled background of $n(H_2)_{2-12CO}$. Panel (b) shows the modeled perturbations: the dotted lines show the curve of each Gaussian perturbation and the blue solid line shows the sum of these curves. By multiplying the modeled perturbation to the background, we get the modeled perturbed $n(H_2)_{2-12CO}$, shown in panel (c). Then we use the abovementioned filtering technique to separate the background and perturbation profiles, shown in panels (d) and (e), respectively.

We follow this approach for the $n(H_2)_{2-12CO}$, $z_{2CO}$ separately, and for each CO isotopologue independently. The coupling between $n(H_2)_{2-12CO}$, $z_{2CO}$, and $T_{2-12CO}$ will be discussed in Section 5. 4.2. Results

The inferred perturbed profiles of the gas number density, $n(H_2)_{2-12CO}$, are shown in Figure 8 for each CO isotopologue. The estimated perturbed $n(H_2)_{2-12CO}$, shown here are the weighted mean values of all samples from the posterior distributions, where the weight is the importance weight of each sample in the dynamic nested sampling. The errors, indicated by the blue shaded area around them, are similarly calculated from the weighted standard deviation of all samples. Panels (a), (b), and (c) show comparisons between observed $v_{\text{rot}}$ (orange), and modeled perturbed $v_{\text{rot}}$ (blue). Panels (d), (e), and (f) show comparisons between the deviations from the observations (orange, with associated uncertainties) and from using the modeled $v_{\text{rot}}$ (blue). Panels (g), (h), and (i) show the normalized $n(H_2)_{2-12CO}$ profile that yields a consistent $v_{\text{rot}}$ profile, while panels (j), (k), and (l) show the filter-extracted perturbations in $n(H_2)_{2-12CO}$. This modeling suggests a significant depletion in gas number density inward of 100 au traced by each of the three CO isotopologues (Figures 8(g), (h), (i)). Such a density depletion may be the edge of the dust and gas gaps identified to span between 29 and 55 au (Fedele et al. 2017; Bertrang et al. 2018). In panels (j), (k), and (l), we find that the locations of the peaks and gaps in the perturbations are roughly consistent among the three CO isotopologues. Particularly, we see a clear coherent peak around 110 to 120 au in all three isotopologues.

Estimation of the perturbed profiles of emission height, $z_{2CO}$, are shown in Figure 9, following the same structure of Figure 8. The locations of the peaks and gaps in the perturbations are roughly consistent among the three CO isotopologues, e.g., we see a coherent gap around 95 to 105 au in all three isotopologues. Comparing to the perturbations in $n(H_2)_{2-12CO}$, the perturbations in $z_{2CO}$ are roughly at the same location but in a opposite direction, e.g., from $^{12}$CO, there is a negative

12 https://github.com/joshpeagle/dynasty
perturbation in \( z_{\text{CO}} \), but a positive perturbation in \( n(H_2)_{z=\text{CO}} \) at around 200–210 au.

As \( T_{\text{B}}_{z=\text{CO}} \) was fixed to \( T_{\text{B}} \) when the perturbations in \( n(H_2)_{z=\text{CO}} \) and \( z_{\text{CO}} \) were inferred, it is important to also test how large the perturbations in the gas temperature would need to be to account for the observed perturbations in \( v_{\text{rot}} \). Similar to \( n(H_2)_{z=\text{CO}} \) and \( z_{\text{CO}} \), we multiply the Gaussian perturbations, \( \delta(r) \), to \( T_{\text{B}}_{z=\text{CO}} \), and find best-fit values for the perturbed \( T_{\text{B}}_{z=\text{CO}} \) that are able to fully cover the perturbations in \( v_{\text{rot}} \). The result is shown in Figure 10, following the same structure of Figure 8. We find that the required perturbations can be up to 10% relative to their background values, which are much larger than the observed deviations in \( T_{\text{B}} \) profile, suggesting that perturbations in the gas temperature would only be a minor contribution to the observed velocity deviations. Furthermore, the perturbations are in radial locations that are inconsistent with the \( T_{\text{B}} \) profiles. Hence, we conclude that the deviations in \( v_{\text{rot}} \) are likely dominated by perturbations in \( n(H_2)_{z=\text{CO}} \) and \( z_{\text{CO}} \), rather than \( T_{\text{B}}_{z=\text{CO}} \).
5. Discussion

5.1. Meridional Flows

As shown in Figure 6, we have detected a collapsing gas flow around 125 au (indicated by a black dotted box) and tentatively, a second flow at 210 au, suggestive of a meridional flow. Meridional flows were previously detected in HD 163296 (Teague et al. 2019) where they were shown to have larger velocities in the atmospheric layers than in the midplane—consistent with what is observed for HD 169142. Such velocity structures require a large depletion in the gas surface density (e.g., Morbidelli et al. 2014; Szulágyi et al. 2014), with several studies (e.g., Papaloizou & Lin 1984) showing that such depletion can be created by planet–disk interactions, particularly for giant planets. However, other scenarios—unrelated to planets, such as the magneto-rotational instability (Flock et al. 2015) or the vertical shear instability (Flock et al. 2017; Riols & Lesur 2019), may also cause depletion of gas surface density and potentially form similar velocity structures, and cannot be ruled out as explanations for such collapsing flow. Future simulations can be proposed to help discriminate different origins of such flow.

5.2. Vertical Disk Model at the Gap Center

Based on the changes in rotational velocity, we infer an increase in the gas number density at the same location as the aforementioned meridional flow at 125 au. This is found for all three CO isotopologues, as shown in Figure 11. An increase in gas density is naively counter to the gas density depletions required for meridional flows. However, Rab et al. (2020) used thermo-chemical models to investigate the impact of dust and gas gaps on the gas properties, finding that a gas gap will lead to complex changes in the expected properties of gas density tracers. For instance, with a shallow gap in the gas surface density, CO emission will trace a denser gas, despite the drop in surface density, rather than intensity variations. This means even if we have a higher resolution observation in the future, such
structures may only be shown in the kinematics instead of emission maps.

To test this hypothesis and to reconcile the apparent increase in gas number density (inferred by changes in $v_{\text{rot}}$) at a surface density minimum (suggested by the meridional flows), we develop a 1D analytical model of the disk vertical structure, to explore how changes in the gas surface density are related to the changes in $z_{\text{CO}}$, $T_{z=\text{CO}}$, and $n(\text{H}_2)_{z=\text{CO}}$ inferred through $v_{\text{rot}}$ measurements.

5.2.1. Model Setup

We consider a vertical column that is in hydrostatic equilibrium with a vertical temperature gradient and a fiducial surface density of $\Sigma_0$. Following Williams & Best (2014), we model the vertical temperature structure as

$$T(z) = \begin{cases} T_{\text{mid}} + (T_{\text{atm}} - T_{\text{mid}}) \sin \left( \frac{\pi z}{2z_q} \right) & \text{if } z < z_q, \\ T_{\text{atm}} & \text{if } z \geq z_q, \end{cases}$$

where $T_{\text{mid}}$ is the midplane temperature, $T_{\text{atm}}$ is the atmospheric temperature, and $z_q$ represents the transition to the disk atmosphere where $T(z) = T_{\text{atm}}$. Following Williams & Best (2014), we fix $z_q = 4H_p$, where $H_p$ is the midplane pressure scale height, given by,

$$H_p = \sqrt{\frac{kT_{\text{mid}}r^3}{GM_\star \mu m_H}},$$

and $m_H$ is the mass of a hydrogen atom, $\mu = 2.37$ is the mean molecular weight of the gas in the disk. We fix $T_{\text{mid}} = 10$ K as this is typical of midplane temperatures (Guilloteau et al. 2016), and vary $T_{\text{atm}}$ from 10 to 60 K in steps of 10 K to cover the range of temperatures likely traced by CO isotopologue emissions based on their brightness temperatures (shown in Figures 2(c) and (d)). We show these vertical temperature profiles in panel (a) of Figure 12.

Figure 10. Estimation of the perturbed profiles of local temperature traced by $^{12}\text{CO}$ (2–1), $^{13}\text{CO}$ (2–1), and $^{13}\text{C}^{18}\text{O}$ (2–1), are shown in the left, middle, and right columns, respectively. Panels (a), (b), and (c) show comparisons between observed $v_{\text{rot}}$ (orange), and modeled perturbed $v_{\text{rot}}$ (blue). Panels (d), (e), and (f) show comparisons between the deviations in observed (orange) and modeled (blue) perturbed $v_{\text{rot}}$, which are extracted using the same filtering technique mentioned in Section 3.2. The orange shaded area shows the error of the observed $v_{\text{rot}}$. Panels (g), (h), and (i) show the comparison between the estimated perturbed (blue) $T_{z=\text{CO}}$ and the observed brightness temperature. Panels (j), (k), and (l) show the extracted perturbations of the perturbed $T_{z=\text{CO}}$ using the same filtering technique mentioned in Section 3.2.

Figure 11. A summary of the radial profiles of the estimated perturbation in $n(\text{H}_2)_{z=\text{CO}}$ traced by $^{12}\text{CO}$ (2–1), $^{13}\text{CO}$ (2–1), and $^{13}\text{C}^{18}\text{O}$ (2–1) emissions. The shaded area shows the error for each curve. The gray dotted box indicates the radial range of the collapsing flows found in the $v_{\text{rad}}$ and $v_z$ structure in Figure 6.
Figure 12. Vertical temperature structure, \( T(z) \), and density structure, \( n(z) \), at the gap center are shown in panels (a) and (b), respectively. \( T(z) \) is calculated from Equation (5). We fix \( T_{\text{mid}} = 10 \, \text{K} \) and vary \( T_{\text{ann}} \) from 10 K to 60 K in steps of 10 K. \( n(z) \) is calculated by numerically solving Equation (7) for each different \( T(z) \) in panel (a).

The vertical temperature structure, \( T(z) \), the vertical density structure can be calculated by solving for hydrostatic equilibrium:

\[
\frac{\partial \ln \rho}{\partial z} = - \left[ \left( \frac{GM_{\text{star}}}{r^2 + z^2} \right)^{3/2} \left( \frac{\mu m_{\text{H}}}{kT} \right) + \frac{\partial \ln T}{\partial z} \right].
\]  

(7)

This is solved numerically to yield the vertical density structure, \( n(z) \) \((\rho = \rho / m_{\text{gas}})\), for each different \( T(z) \) considered. We adopt a surface density of 5 g cm\(^{-2}\), typical of disks with large masses as used by Williams & Best (2014). The resulting vertical density structures are shown in Figure 12(b).

We include a simple model for the CO emission surface. CO is assumed to be present in large abundance when there is a large enough column density of material above it to sufficiently shield it from dissociating UV radiation \( (N_{\text{shield}}; \text{Visser et al. 2009}) \). Below this height, we assume that the abundance of CO is great enough that the emission becomes optically thick as soon as there is enough CO for self-shielding. The emission height of CO, \( z_{\text{CO}} \), is therefore the height where the gas column density, integrated from the surface of the disk down toward the midplane, reaches \( N_{\text{shield}} \). Thus, \( z_{\text{CO}} \) satisfies

\[
N_{\text{shield}} = \int_{z_{\text{CO}}}^{\infty} \rho(z) \, dz.
\]  

(8)

In typical ISM conditions, \( N_{\text{shield}} = 1.3 \times 10^{21} \, \text{H}_2 \, \text{cm}^{-2} \) (Visser et al. 2009; Qi et al. 2011) for \(^{12}\text{CO}, \^{13}\text{CO} \) and \(^{18}\text{O} \) require a larger \( N_{\text{shield}} \) value than they are less abundant than \(^{12}\text{CO}, \) and so the self-shielding process is less efficient. To account for this in our model, we adopt different \( N_{\text{shield}} \) to represent different CO isotopologues. We describe \( N_{\text{shield}} \) as

\[
N_{\text{shield}} = kN_0, \text{ where } N_0 = 1.3 \times 10^{21} \, \text{H}_2 \, \text{cm}^{-2}, \text{ and } k \text{ is varied from 1 to 5. Following Visser et al. (2009), } \text{we find comparable photodissociation rates to } ^{12}\text{CO} \text{ (} k = 1 \text{) for } ^{13}\text{CO} \text{ and } ^{18}\text{O} \text{ when } k \approx 5 \text{ for disk-like conditions (ignoring the influence of dust-shielding). As such, the adopted range of } k \text{ values provides a reasonable model to reproduce the different vertical layers traced by different molecular species.}

With \( z_{\text{CO}} \) to hand and the temperature and density structures shown in Figure 12, we can calculate the gas temperature and the number density traced by the CO emission, \( T = z_{\text{CO}} \), and \( n(H_2) = z_{\text{CO}} \), respectively. We do not consider \( v_{\text{rot}} \) given that it depends on the radial pressure gradient, requiring a 2D model instead of 1D model. Moving to a 2D model would require extra assumptions about the gap width and radial dependence of the gas properties, substantially complicating the interpretation.

5.2.2. Influence of Depletion in the Surface Density

We parameterize the surface density depletion through a parameter \( \delta \), such that the perturbed surface density is given by \( \delta \times N_0 \). \( \delta \) varies between 1, for no perturbation, and 0, representing a completely empty gap. We vary \( \delta \) to simulate different gap depths, and explore how the emission height of CO changes, and thus the temperature, \( T = z_{\text{CO}} \), and number density, \( n(H_2) = z_{\text{CO}} \), traced. We do not consider any change in the physical structure due to changes in the irradiation of the gap, i.e., a change in the temperature structure of the gap, which are discussed in some studies (e.g., Teague et al. 2017; Facchini et al. 2018; van der Marel et al. 2018). The simplifying choice of the gas temperature was made because the way the gas temperature reacts when a gap is opened is highly dependent on several factors, such as the local gas-to-dust ratio and the gap depth that really require an extensive thermo-chemical model to resolve (see Rab et al. 2020, for different responses within the same disk). Under this assumption, any change in the pressure will be entirely due to changes in the density structure of the disk as the temperature structure remains fixed.

We calculate \( z_{\text{CO}} \) for different values of \( \delta \) shown in panels (a) and (b) of Figure 13. In panel (a), we fix \( N_{\text{shield}} = N_0 \), and vary the temperature structure. Conversely, panel (b) shows a comparison for different \( N_{\text{shield}} \) values, representing different isotopologues, while the temperature structure is held constant with \( T_{\text{mid}} = 10 \, \text{K} \) and \( T_{\text{ann}} = 40 \, \text{K} \). For this panel we vary \( k \) from 1 to 5. We find that for all scenarios, \( z_{\text{CO}} \) decreases with decreasing \( \delta \), i.e., a deeper gap. As expected, all surface density depletions result in a drop in emission height. As shown in panel (a), for the same \( T_{\text{mid}} \)-but higher \( T_{\text{ann}} \) the \( z_{\text{CO}} \) decreases at a faster rate for a given change in \( \Sigma \) for small perturbations, but all curves tend to converge for significant depletions, e.g., after \( \delta < 10^{-2} \). This is because after \( \delta < 10^{-2} \), \( z_{\text{CO}} \) decreases monotonically with \( \delta \) (see Figures 13(a), (b)). In panel (b), we see that the change in \( z_{\text{CO}} \) with \( \delta \) is the same for all \( N_{\text{shield}} \) values.

Panels (c) and (d) in Figure 13 show how \( T = z_{\text{CO}} \) changes for different background temperature structures and different values of \( N_{\text{shield}} \), respectively. For all scenarios, \( T = z_{\text{CO}} \) decreases with a deeper gap (decreasing \( \delta \)). This is because in our model, \( T \) always decreases toward the midplane (see Figure 12(a)) and \( z_{\text{CO}} \) decreases monotonically with \( \delta \) (see Figures 13(a), (b)).

Panels (e) and (f) in Figure 13 show \( \delta n(H_2) = z_{\text{CO}} \) for different temperature structures and different values of \( N_{\text{shield}} \), respectively. According to Equation (2), the \( v_{\text{rot}} \) is dependent on the radial gradient of \( n(H_2) = z_{\text{CO}} \), and so we only want to know how
$n(\text{H}_2)_z = \text{zCO}$ changes relative to its unperturbed value, $n(\text{H}_2)_z = \text{zCO} (\delta = 1)$. Hence we plot the percentage change relative to this unperturbed value. In most scenarios we consider, $\delta n(\text{H}_2)_z = \text{zCO}$ shows a similar pattern: as we decrease $\delta$ (representing a deeper gap), $\delta n(\text{H}_2)_z = \text{zCO}$ first decreases for small changes in $\delta$, then increases for moderate perturbations, before finally decreasing again at large perturbations. One exception is that in the vertically isothermal case, as indicated by the blue curve in panel (e), the $\delta n(\text{H}_2)_z = \text{zCO}$ decreases monotonically with $\delta$—the behavior one naively expects for a gas gap. It should also be noted that the amplitude of the fluctuation of the $\delta n(\text{H}_2)_z = \text{zCO}$ increases with higher $T_{\text{atm}}$ while at higher $N_{\text{shield}}$ values, the $\delta n(\text{H}_2)_z = \text{zCO}$ curves have turning points at higher $\delta$ values.

We also show $\delta P(\text{H}_2)_z = \text{zCO}$ in panels (g) and (h) in Figure 13, which is the percentage change in gas pressure relative to the unperturbed value, $P(\text{H}_2)_z = \text{zCO} (\delta = 1)$ assuming an ideal gas. For all scenarios, $\delta P(\text{H}_2)_z = \text{zCO}$ decreases with a deeper gap (decreasing $\delta$), contrary to the pressure profile inferred from the observations.

With these models, we show that the physical structure of the gap can have non-trivial responses (i.e., molecule emission tracing a larger gas number density despite being in a gap) to changes in the surface density, as previously shown in Rab et al. (2020) through a full thermo-chemical modeling approach. Meanwhile, we note that the simplified model only provides absolute values and not the radial gradient that the
derivation of the kinematic structure needs—a radial temperature structure in the gap is needed to disentangle possible scenarios. As with current observation we cannot spatially resolve any changes in gas temperature (see Figure 10), we are unable to differentiate between different possible scenarios. With future observations at high angular resolution and more extensive chemical modeling, we will be able to leverage the kinematical constraints to better constrain the physical structure of the gap.

5.3. Interpretations

We compare the result of the above 1D modeling with the perturbed \( n(H_2)_{z=\text{co}} \) estimated in Section 4, and shown in Figure 11. As the radial pressure gradient is calculated at a constant height, rather than along the emission surface, when the temperature traced by CO emission decreases with an increasing gap depth, the radial temperature gradient remains fixed as the temperature structure has not changed (although a negligible change is expected if \( T_{\text{mid}} \) and \( T_{\text{atm}} \) have different radial dependencies as then the background temperature gradient would then be dependent on height). Conversely, as the gap is modeled as a depletion in the gas surface density, the density structure of the entire vertical column does change, resulting in a comparable change in the radial density profile, and thus the radial pressure profile.

Here we use the typical case of \( T_{\text{mid}} = 10 \) K, \( T_{\text{atm}} = 40 \) K, and \( N_{\text{shield}} = N_0 (k = 1) \) in the above 1D model as an example to compare with the perturbed \( n(H_2)_{z=\text{co}} \) in Figure 11. We arbitrarily define \( 1 \geq \delta \geq 0.07 \) as a shallow gap, \( 0.07 \geq \delta \geq 0.003 \) as a moderate gap, and \( \delta \leq 0.003 \) as a deep gap. In our model (Figures 13(e), (f)), we find that for shallow and deep gaps, the emission traces a negative \( \delta n(H_2)_{z=\text{co}} \), and thus a lower gas number density. While for moderate gaps, the emission traces a positive \( \delta n(H_2)_{z=\text{co}} \) corresponding to a higher gas number densities. This is because, with a depletion in the surface density, \( z_{\text{co}} \) decreases, indicating that we are tracing a denser region according to the vertical density structure (see Figure 12(b)). The tracing of a denser region competes with the decrease of the surface density, reducing the gas volume density at a given height. Therefore, the emission will trace a perturbation ranging from a positive \( \delta n(H_2)_{z=\text{co}} \) to a negative \( \delta n(H_2)_{z=\text{co}} \) depending on the results of this competition. This is consistent with the findings in Rab et al. (2020), where the authors demonstrate too the possibility that the CO emission will trace a denser region of the disk (i.e., a higher \( n(H_2)_{z=\text{co}} \)) despite the drop in surface density.

The inferred structure at \( r = 125 \) au, where a surface density minimum is required based on the \( v_{\text{rad}} \) and \( v_{\text{z}} \) structure, but CO isotopologue emission traces higher gas volume densities, is consistent with our modeling for a moderate gap, i.e., \( 0.07 \geq \delta \geq 0.003 \). Note that when interpreting these findings, we want to use the described model only as a guide as the true physical structure of the gaps will be far more complex. For example, while \( v_{\text{rot}} \) is sensitive to both \( n(H_2)_{z=\text{co}} \) and \( z_{\text{co}} \), we have considered \( n(H_2)_{z=\text{co}} \) separately in Section 4, meaning that the estimated scale of \( \delta \) here is only poorly constrained. As the disk around HD 169142 is observed from an almost face-on orientation, any information (e.g., emission height) about the vertical disk structure cannot be extracted from the observation. Future studies can repeat this analysis for disks at moderate inclination, where the emission height can be directly measured and thus used to break some of the degeneracy between the \( n(H_2)_{z=\text{co}} \) and \( z_{\text{co}} \).

To provide some representative numbers to demonstrate that a planet-opened gap is a plausible scenario and is consistent with the observed features, we predict the mass of the potential planet opening this gap based on the estimated gap depth, \( 0.07 \geq \delta \geq 0.003 \). Following the method outlined in Kanagawa et al. (2015a), Zhang et al. (2018), Gyeol Yun et al. (2019), we estimate that the mass of the planet is between 0.5 to 2.5 \( M_{\text{Jup}} \) assuming the disk viscosity \( \alpha = 1 \times 10^{-3} \) (Flaherty et al. 2015, 2017, 2020; Teague et al. 2016, 2018b). Assuming a lower \( \alpha \), i.e., \( 1 \times 10^{-4} \), the estimated planet mass can be as low as 0.15 \( M_{\text{Jup}} \). Estimating the planet mass based on the width of this gap or the velocity perturbation (Gyeol Yun et al. 2019) results in a mass \( \sim 1 M_{\text{Jup}} \).

6. Conclusion

We present an analysis of archival ALMA observations of \( ^{12}\text{CO} \) (2–1), \( ^{13}\text{CO} \) (2–1), and \( ^{18}\text{O} \) (2–1) emission from the disk around HD 169142 to search for large-scale kinematic structures. We extract 3D kinematical information at different vertical layers within the disk traced by the different CO isotopologues. We use analytical models to explore the dynamical and physical structure of the disk that would be consistent with the measured velocity profiles. The key findings are as follows:

1. We have extracted 3D velocity structure with the method following Teague et al. (2018a, 2018b, 2019). We identify collapsing gas flows around 125 au and tentatively 210 au. At 125 au, the flow appears to be continuous, traced by all three CO isotopologues. These features are interpreted as meridional flows, bearing a striking resemblance to those modeled for the HD 163296 disk in Teague et al. (2019).

2. We observe deviations up to 1% in the \( v_{\text{rot}} \) profiles, relative to the background rotation. We estimate the perturbations required to drive such deviations if they were to be from either changes in the gas number density, gas temperature, or the emission height. We find that the required perturbations can be up to 10% relative to a smooth background for all three properties. As these variations are much higher than those observed in the \( T_{\text{b}} \) profiles, we argue the perturbations are likely caused mainly by changes in the gas number density or the emission height.

3. We develop a simplified analytical model of a gap, and find that changes in the gas surface density can have non-trivial impacts on the physical structure of the gap where the molecular emission is tracing. These results are consistent with a full thermo-chemical modeling approach presented in Rab et al. (2020). We also show the possibility of inferring the mass of the planet responsible for opening the gap from such responses. While we cannot readily explain the kinematic deviation with this simplified model, these sort of observations provide a tool to access the temperature and density profiles within the gap and that when combined with extensive thermo-chemical modeling, provide the best opportunity to characterize the physical structure of a gap.

In sum, this work demonstrates the ability to map the 3D kinematical structure of protoplanetary disks, and serves as a
foundation for future studies to characterize the physical conditions around gap edges.

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Facilities: ALMA.

Software: CASA (McMullin et al. 2007), GoFish (Teague 2019a), bettermoments (Teague & Foreman-Mackey 2018), eddy (Teague 2019b), dynesty (Speagle 2020).

Appendix A
Different Methods for Calculating the Velocity Maps

We have tested different methods for calculating the line-of-sight velocity, $v_{\text{LOS}}$, using the bettermoments package. These methods include: the intensity-weighted average velocity, a first moment map; quadratic, fitting a quadratic function to the brightest pixels of the spectrum and its two neighboring pixels; Gaussian, fitting a Gaussian function to each pixel; and gaussthick, similar to Gaussian, but including an approximation of an optically thick line core (e.g., Hacar et al. 2016). We show a comparison of the performance of these methods in Figure 14, using velocities traced by $^{12}$CO (2–1) as an example. The first row shows the velocity maps calculated by the four methods, while the second row shows the associated uncertainties.

We also zoom into a few example pixels to compare in details the difference among methods for inferring the line center, $v_{\text{LOS}}$, in Figure 15. The examples pixels are labeled by yellow crosses in the example velocity map in the middle panel. The left and right panels show how the different functional forms fit those spectra. The dots and the error bars in the upper part of these panels show the inferred $v_{\text{LOS}}$ and associated statistical uncertainties from the four methods.

From the comparisons, we find that the gaussian method fits the best to the spectra, as well as provides the lowest uncertainties around both the center and the edge of the velocity map, while the first moment method returns the largest uncertainties. The gaussthick method also works well around the center of the map, but gets significantly worse when it comes close to the edge of the velocity map. As described in Teague & Foreman-Mackey (2018), the quadratic approach yields a robust measure of the line center even for asymmetric line profiles. If the underlying profile is close to a Gaussian, as is the case for HD 169142, then fitting an analytical form, such as the gaussian or gaussthick methods, will always yield more precise measures. For the specific case of the data used for this paper, the spectra are too coarse to find a better constraint with the gaussthick method, and large covariances between the optical depth and the line center result in only poor constraints.

Figure 14. Comparison between different methods for calculating the velocity maps. The first row shows the velocity maps calculated by the four methods: the intensity-weighted average velocity (a first moment map), quadratic, Gaussian, and gaussthick. The second row shows the associated uncertainties. (Use $^{12}$CO (2–1) as an example).
Appendix B
Radial Profiles for 3D Velocity Components

B.1. Enhancement on the Velocity Profiles

We use the method described in Section 3.1 to extract the profiles of 3D velocity components: rotational velocity, \( v_{\text{rot}} \), radial velocity, \( v_{\text{rad}} \), and vertical velocity, \( v_z \). We split the data into annuli, and run MCMC with 32 walkers, 500 burn-in steps and 500 steps on each annulus to explore the posterior distributions of model parameters of \( v_{\text{rot}} \) and \( v_{\text{rad}} \), in order to estimate the best-fit values. For each annulus, spatially independent pixels are randomly selected. After one instance of the fitting procedure, we find that there is a great amount of high-frequency noise mixed in the profiles, which interferes with our search for the real perturbations. To better characterize the range of velocity profiles consistent with the data, we run multiple instances of the fitting procedure, each time selecting a random set of independent pixels, and taking the mean and standard deviation of the ensemble of samples as the best-fit value and associated uncertainty (as in Kepler et al. 2019). To determine how many instances are needed, we calculate the average standard deviation (ASD), which is estimated by calculating the standard deviations of all samples at each radius, then taking the average across all radii. Using \( v_{\text{rad}} \) traced by \(^{12}\text{CO} \) (2–1) as an example, we show the ASD and the gradient of the ASD versus the number of instances in Figure 16(a). Given that the gradient of ASD is almost flat after around 25 instances, we therefore conclude that 25 instances of the fitting procedure are sufficient, that adding more instances hardly further improves the velocity profiles (i.e., suppress the high-frequency noise). We confirm this further from Figure 16(b), which shows examples of how \( v_{\text{rad}} \) profiles change with more instances averaged. We see that there are apparent improvements before 25 instances, but no noticeable changes afterward.

The final step of improving the profiles is to filter out the still remaining high-frequency noise (i.e., see Figure 16(b), \( N = 25 \)). We find that a Savitzky–Golay filter with a window of 9 data points (~47 au) and polynomial order of 3 performs best for our case, as it would not introduce or eliminate perturbations in the profiles. An example (\( v_{\text{rad}} \) traced by \(^{12}\text{CO} \) (2–1)) is shown Figure 16(c).

B.2. Modeling the Background Rotation

In order to identify perturbations in \( v_{\text{rot}} \), a background model must be subtracted. Due to the background pressure gradient and any potential change in the emission surface, a simple Keplerian model does not suffice (e.g., Teague et al. 2019). In this work, we adopt a new approach, employing a Butterworth low-pass filter to extract a background model based on the low-frequency components of the \( v_{\text{rot}} \) curve. In this Appendix, we compare this approach with analytical background models, and discuss the choice of filter properties.

In Figure 17(a), we compare different baseline models: a Keplerian model, a double power-law model, and a non-parametric model extracted by IIR Butterworth low-pass filter. The upper figure shows the baseline models with the observed \( v_{\text{rot}} \), while the lower figure shows the inferred deviations, \( \delta v_{\text{rot}} \). We find that the Butterworth filter method performs the best, as there is the smallest overall gradient in the extracted \( \delta v_{\text{rot}} \) profile. In panel (b), we compare different cut-offs of the filter. We find that a cut-off smaller than 16 samples (i.e., 8 samples, ~41 au) suppresses the real perturbations in \( v_{\text{rot}} \), while a cut-off bigger than 16 samples (i.e., 24 samples, ~124 au) leaves apparent overall gradients in the \( \delta v_{\text{rot}} \) profiles. In panel (c), we compare different orders of the filter. We find that an order lower than 12 (i.e., 2) leaves remaining baseline in the \( \delta v_{\text{rot}} \) profile, as the cutting-off of the low-frequency signal is not steep enough, while an order higher than 12 (i.e., 24) presents a very similar result as the order of 12.
Figure 16. Panel (a) shows the ASD and the gradient of the ASD vs. the number of instances. Panel (b) shows examples of how $v_{\text{rad}}$ profiles change with more instances averaged corresponding to panel (a). Panel (c) shows a comparison between before and after implementing the Savitzky–Golay filter with a window of 9 data points ($\sim$47 au) and polynomial order of 3. (Use $^{12}$CO (2–1) as an example.)

Figure 17. Comparisons among different methods for extracting $\delta v_{\text{rot}}$ profiles, using $v_{\text{rot}}$ traced by $^{12}$CO (2–1) as examples. The upper figures show the fittings to the $v_{\text{rot}}$ baselines, and the lower figures show the extracted $\delta v_{\text{rot}}$ profiles. Panel (a) shows a comparison among different baseline models: a Keplerian model, a double power-law model, and a non-parametric model extracted by IIR Butterworth low-pass filter. Panels (b) and (c) show comparisons between different cut-offs and orders, respectively, of the implemented IIR Butterworth low-pass filter.

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