Quasi-periodic oscillations from relativistic hydrodynamical slender tori

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ABSTRACT
We simulate an oscillating purely hydrodynamical torus with constant specific angular momentum around a Schwarzschild black hole. The goal is to search for quasi-periodic oscillations (QPOs) in the light curve of the torus. The initial torus setup is subjected to radial, vertical and diagonal (combination of radial and vertical) velocity perturbations. The hydrodynamical simulations are performed using the general relativistic magnetohydrodynamics code Cosmost++ and ray-traced using the GYOTO code. We found that a horizontal velocity perturbation triggers the radial and plus modes, while a vertical velocity perturbation triggers the vertical and X modes. The diagonal perturbation gives a combination of the modes triggered in the radial and vertical perturbations.

Key words: accretion, accretion disk, hydrodynamics, QPO, black hole

1 INTRODUCTION
Black-hole binaries, and especially black holes in low-mass X-ray binaries (LMXBs), have been extensively studied in the past decades (for a review, see van der Klis et al. 2004, Remillard & McClintock 2006). The advent of the Rossi X-ray Timing Explorer in the late 1990’s in particular allowed the study of rapid quasi-periodic oscillations (QPOs) in these sources, as well as in accreting neutron stars. QPOs appear as peaks (of non-zero width, hence their quasi-periodic nature) in the power density spectra (PDS, the simplest expression of which is the square modulus of the Fourier transform) of some black-hole binaries. Prior to the launch of the RXTE mission, it had been suggested that QPOs may be observed in LMXBs in the kHz range as a result of inhomogeneities in the inner accretion disk about neutron stars and that they could be used to test predictions of Einstein’s Theory of General Relativity (GR) in the strong field regime (Kluzniak et al. 1998). The power-law spectral state of X-ray binaries (Remillard & McClintock 2006) has a horizon.

In order to understand the high-frequency variability, numerous models have been proposed in the last few years. However, we are still far from understanding these phenomena. In black holes, high-frequency QPOs are associated with the so-called steep power-law spectral state of X-ray binaries (Remillard & McClintock 2006). This spectral state itself is not well understood. One important goal of investigations such as ours is to try to narrow down the choice between models for high-frequency QPOs by exploring their ability to account for observations. As of today, a large diversity of models are still advocated. Blobs of matter orbiting in the inner accretion disk have been an early favourite as the cause of a quasi-periodic modulation to the X-ray flux (Stella & Vietri 1998, Cui, Zhang & Chen 1998, Kluzniak 1998), but these have been ruled out (Barret et al. 2005), at least in the neutron star LMXBs, by the high degree of coherence of the oscillation (high quality factor Q). Although in black holes the Q value is low, so blobs are not ruled out, it seems much more likely that the QPOs

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reflect modulations imprinted on the photon flux by intrinsic disk oscillations, whose normal modes have been studied extensively (Wagoner 1999; Kato 2001; Miranda, Horák & Lut 2015).

Upon analyzing certain properties of twin kHz QPOs in neutron stars, Kluzniak & Abramowicz (2001) proposed that they could be accounted for by a resonance between two possible motions of the accreting fluid. The resonance model predicted that high frequency QPOs in black holes should occur in pairs, as they do in neutron stars, and that the two QPO frequencies should be in the ratio of small integer numbers, e.g., 2:1 or 3:2 ratio. These predictions were borne out with the discovery of a 450 Hz QPO in the binary black hole system GRO J1655-40 (Strohmayer 2001a) in which a 300Hz QPO had been reported previously. Abramowicz & Kluzniak (2001) pointed out that the two frequencies, 450 Hz and 300 Hz, are in a 3:2 ratio, and constrained the spin of the black hole assuming a particular resonance model. The resonance model has been used to relate the black hole spin to the frequencies expected also for other types of resonances that can occur in nearly Keplerian disks in strong gravity (Torok et al. 2005; Stuchlik, Kotrova & Tork 2013). In spite of the successful predictions of the resonance model, it is important to examine other possibilities, such as that the ratio may only be approximately 3:2, and may simply reflect the ratio of two eigenfrequencies of an accretion structure. Recently, Dexter & Blaes (2014) advocated a model that accounts for both the steep power-law spectral state and approximately for the 3:2 frequency ratio of twin-peak QPOs.

A torus oscillating along its own axis may cause periodic variations in its radiative flux (Bursa et al. 2004; Kluzniak et al. 2004; Lee, Abramowicz & Kluzniak 2004). Based on their analytical work Kluzniak, Abramowicz & Lee (2004) also suggested that axisymmetric, up and down, motion at the vertical epicyclic frequency can also be directly observable if it occurs in the inner regions of the disk. To produce synthetic light curves and PDS, Bursa et al. (2004) performed general relativistic ray-tracing of a torus undergoing simultaneous vertical and radial eigenmode oscillations with a 3:2 frequency ratio, finding that the (higher-frequency) vertical oscillation appreciably modulates the light curve only in GR, and not in Newtonian gravity. Schnittman & Bertschinger (2004) considered a hot spot radiating isotropically on nearly circular equatorial orbits around a Kerr black hole and also performed general relativistic ray-tracing to produce synthetic light curves and PDS, finding that the hot spots would have to be very elongated in the azimuthal direction to suppress the (unobserved) harmonic content. The hot spot model has also been investigated by Bakala et al. (2014). The Rossby wave instability may also lead to the appearance of QPOs in black hole binaries (Tagger & Varniere 2006; Vincent et al. 2013).

Geometrically thick disks or tori (Abramowicz, Jaroszynski & Sikora 1978; Abramowicz & Fragile 2013) have been of great interest in studies of QPOs using analytical as well as numerical simulations. Rezzolla, Yoshida & Zanotti (2003) studied high-frequency QPOs in oscillating tori in the Newtonian as well as GR framework. Kluzniak (2005; Abramowicz et al. 2006); Blaes, Arras & Fragile (2006) analytically calculated linear modes in relativistic slender hydrodynamical torus and also suggested that these modes can be excited in numerical simulations, Straub & Srámková (2009) extended these results to non-slimmer tori, Mazur et al. (2013) and Vincent et al. (2014) studied analytic tori subject to radial, vertical, shear and expansion perturbations using relativistic ray-tracing.

Ray-tracing of relativistic hydrodynamical simulations of an oscillating torus was performed for the first time by Schnittman & Rezzolla (2006), who perturbed the radial velocity to trigger the oscillations. They found multiple high-frequency peaks in the simulated light curve, and in this paper we are going to revisit the frequency identification with particular modes which was suggested by the authors. In order to generalize this hydrodynamical work, Schnittman, Krollik & Hawley (2006) used relativistic ray-tracing to compute the light curves from 3D global relativistic MHD simulations of accreting tori around black hole. However, these authors did not see any convincing evidence of QPOs in their MHD simulations.

This article aims to further develop the study of oscillating tori as a model for high-frequency QPOs and in particular twin-peak QPOs. To this end we perturb the 4-velocity of equilibrium tori, use relativistic hydrodynamical simulations to compute their evolution and relativistic ray-tracing to integrate the radiative transfer equation and produce power spectra. Such computations have been done in the past by Schnittman & Rezzolla (2006). The new ingredient of our work is an investigation of various perturbations of the equilibrium torus at various distances from the black hole to determine which oscillation modes are triggered, depending on the initial perturbation. We consider fairly slender tori (with a small cross-sectional diameter compared to its distance from the central object), whereas Schnittman & Rezzolla (2006) considered thick tori. Unlike for thick tori, comparison of our simulations with previous analytical studies developed in the limit of slender tori (Kluzniak 2005; Abramowicz et al. 2006; Blaes, Arras & Fragile 2006) allows an unambiguous identification of the modes responsible for the peaks in the simulated PDS. One of the main limitations of this study is the fact that no self-consistent model is given for the origin of the perturbation of the equilibrium torus. This point may be addressed in future work.

The article is organized as follows: In Section 2 we present the numerical method governing the general relativistic hydrodynamical (GRHD) equations to setup the torus simulation and perform relativistic ray-tracing of the results. In Section 3 we discuss the simulated PDS of oscillating tori for various initial perturbations. In Section 4 we shall give conclusions. We use $G = 1 = c$ throughout the paper.

## 2 QPO MODES AND NUMERICAL SETUP

### 2.1 Eigenfrequencies of QPO modes

The perturbation analysis in previous studies of QPOs predicted the analytical expressions of various eigenmodes we are interested in (Kluzniak 2005; Abramowicz et al. 2006; Blaes, Arras & Fragile 2006; Straub & Srámková 2009). These are the radial mode ($r$), the vertical ($\theta$) mode, the X mode, the plus mode (+), and the breathing mode (b). We shall follow the notations of Blaes, Arras & Fragile (2006) in defining the frequencies of the eigenmodes. These expressions are valid for a polytropic equation of state; in this work, we assume a polytropic index of $\Gamma = 5/3$.

The lowest order eigenmode frequencies at the center of torus, $r_c$, are

$$\sigma_1^r = \omega_h^r = \left(1 - \frac{6}{R_c}\right),$$  \hspace{1cm} (1)

$$\sigma_0^r = \omega_h^r = 1,$$  \hspace{1cm} (2)

$$\sigma_3^r = \sqrt{\sigma_h^r + \omega_h^r},$$  \hspace{1cm} (3)

$$\sigma_4^r = \frac{1}{3} \left[A - B^{1/2}\right]$$  \hspace{1cm} (4)

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$$\sigma_4^r = \frac{1}{3} \left[A - B^{1/2}\right]$$  \hspace{1cm} (4)
\( \sigma^2_b = \frac{1}{3} [A + B^{1/2}] \)  

where, \( \sigma^2_b \) and \( \sigma^2_v \) are radial and vertical epicyclic frequencies scaled by the Keplerian orbital frequency \( 2\nu \) at the center of the torus. \( A \) and \( B \) are defined by,

\[
A = 4 \left( \sigma^2_b + \sigma^2_v \right) - \frac{5}{3} \kappa^2_{Bc},
\]

\[
B = \left[ \left( 4 \left( \sigma^2_b - \sigma^2_v \right) + \frac{5}{3} \kappa^2_{Bc} \right)^2 + 4 \sigma^2_b \left( \sigma^2_v - \kappa^2_{Bc} \right) \right].
\]

where \( \kappa_{Bc} \) is characteristic squared frequency scaled with orbital frequency at the center of the torus (Blaes, Arras & Fragile 2006).

Table 1 shows the predicted values of these frequencies from the above expressions.

### 2.2 GRHD simulation

We numerically solve the equations of relativistic hydrodynamics derived from the following stress-energy tensor for the torus fluid

\[
T_{\mu \nu} = (\rho + \rho \nu + P) u_\mu u_\nu + P g_{\mu \nu},
\]

where \( \rho \) is the specific internal energy, \( \nu \) is the rest-mass density, \( P \) is the fluid pressure, \( u^\mu = e^\mu_\nu u_\nu \) is the fluid 4-velocity and \( g_{\mu \nu} \) is the Schwarzschild metric tensor. We use the Kerr-Schild coordinate system in the GRHD simulations. From the conservation of rest mass and energy-momentum, we arrive at the following conservation equations that we evolve numerically using the general relativistic magnetohydrodynamic code Cosmos++ (Anninos, Fragile & Salmonson 2005).

\[
\partial_t D + \partial_i \left( DV \right) = 0,
\]

\[
\partial_t S_j + \partial_i \left( \sqrt{-g} T^i_j \right) = -\sqrt{-g} T^i_j \Gamma^i_{jk},
\]

\[
\partial_t S_j + \partial_i \left( \sqrt{-g} T^i_j \right) = \sqrt{-g} T^i_j \Gamma^i_{jk}
\]

where \( D = W \nu \) is the generalized fluid density, \( W = \sqrt{-g'} \nu \) is the generalized boost factor, \( V^i = u^i / u^0 \) is the transport velocity, \( g \) is the metric determinant,

\[
S_j = -\sqrt{-g} T^0_j - W u_j \rho h - \sqrt{-g} P
\]

is the total energy density, \( h = 1 + \epsilon + P/\rho \) is the specific enthalpy, and

\[
S_v = \sqrt{-g} T^0_v = W u_v \rho h
\]

is the covariant momentum density. We solve the GRHD equations using the high resolution shock-capturing (HRSC) option described in Fragile et al. (2012) and Dibi et al. (2012).

We choose the black hole mass to be \( M = 10 M_\odot \) and set up a slender stationary hydrodynamical torus of cross-sectional radius, \( r_{cross} = 0.5 M \) around it. We accomplish this by setting the inner and center (density and pressure maximum) radii of the torus for each model, as given in Table 2. In order to understand the dependence of the results on radial position of the torus we chose two central radii, first at \( R_t = 10.0 M \) and second at \( R_t = 15.0 M \). All the simulations in our study assume a constant specific angular momentum distribution, which is defined as \( l = -u_\phi u_t / u_\phi \), where \( u_\phi \) and \( u_t \) are the covariant azimuthal and time components of the 4-velocity, respectively. We solve for the initial internal energy distribution of the torus \( e(\epsilon, \theta) \). To initialize the setup we assume a polytropic equation of state \( P = P_0 \epsilon (\Gamma - 1) / \kappa^{\Gamma - 1} \), so the density is given by \( \rho = [e(\epsilon, \theta)]^{\Gamma - 1} / \kappa \), with \( \Gamma = 5/3 \). We can choose \( \kappa \) to set the density (and mass) normalization of the initial torus. Once the initial setup is fixed, the gas temperature of the torus is fixed by the gravity. The torus is evolved with time using ideal gas equation of state \( P = (\Gamma - 1) \rho e \).

The initial torus setup is subjected to a vertical or radial velocity perturbation using uniform velocity fields corresponding to the vertical and radial eigenmodes, respectively, in the slender torus limit (Bursa et al. 2004; Blaes, Arras & Fragile 2006). The diagonal perturbation is obtained by adding these two uniform velocity fields. The equilibrium torus is defined by the covariant 4-velocity,

\[
u_i = (u_i, 0, 0, u_\phi).
\]

After applying the velocity perturbation, the covariant 4-velocity is given by

\[
u_i = \left\{ \begin{array}{ll} (u_i, \eta, 0, u_\phi), & \text{Radial} \\ (u_i, 0, K\eta, u_\phi), & \text{Vertical} \\ (u_i, \eta, K\eta, u_\phi), & \text{Diagonal} \end{array} \right.
\]

where

\[
K = -\frac{\sqrt{\det(R_c)}}{\sqrt{\det(R_c)}}
\]

This parameter is chosen such that radial and vertical 4-velocity perturbations will have the same magnitude. The parameter \( \eta \) normalizes the perturbation. We choose \( \eta = 0.003 V_{kepler} \), where \( V_{kepler} = 2\pi R_v/v_r \) is the Keplerian speed at the center of the torus, with \( v_r \) being the orbit frequency. Illustrations of the various topologies perturbations are shown in Fig. 1.

The various initial setups we study are given in Table 2. The computational domain along radial direction is defined by \( \rho_{min} = (R_t - 0.75) M \) and \( \rho_{max} = (R_t + 0.75) M \). The domain along the polar direction is defined by \( \theta_{min} = 86.4^\circ \) and \( \theta_{max} = 93.6^\circ \) for the torus at \( R_t = 10 M \) and \( \theta_{min} = 87.66^\circ \) and \( \theta_{max} = 92.34^\circ \) for the torus with \( R_t = 15 M \). We performed the hydrodynamics simulations with 256 zones along both radial and polar directions. We also checked one simulation with 512 \( x 512 \) to confirm that the results we obtained are not sensitive to the chosen resolution. All the models presented in Table 2 are computed for a total coordinate time of \( \Delta t = 20 t_{orb} \) (orbital period at the center of the torus), where \( t_{orb} = 198.6 M \) for \( R_t = 10 M \) and \( t_{orb} = 365.0 M \) for \( R_t = 15 M \).

### 2.3 Ray-tracing

The numerical data obtained from the Cosmos++ code are ray-traced using the open-source GYOTC code (Vincent et al. 2011). An observer is placed at a distance \( r_{obs} = 10^4 M \) from the black

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Table 1. Analytically predicted frequencies (defined in Section 2.1) of the five lowest order oscillation modes of slender tori for the two central radii considered in this study, in units of the Keplerian frequency at the center of the torus, \( \nu_v \).

| \( R_t \) | Radial | Vertical | X | Plus | Breathing |
|---------|--------|----------|---|------|-----------|
| 1      | 0.63   | 1        | 1.18 | 0.98 | 1.66      |
| 15     | 0.77   | 1        | 1.26 | 1.18 | 1.69      |

1 Freely available at gyroto.obspm.fr
The GRHD simulations are scale-free in density, meaning that the mass density obtained from one given solution can be multiplied by an arbitrary constant factor to get another well-defined solution. As a consequence, we have one degree of freedom to choose which is the mass density normalization. We choose it by imposing that the temperature at the last scattering surface be of the order of $10^5$ K, which fixes the density. Because of the way these two emission models are constructed, the optically thick case mostly traces the evolution of the torus surface (of last scattering), while the optically thin case traces the variation of its full volume.

For both the optically thick and thin cases, the torus 3-velocity and density are interpolated trilinearly in 2D space ($r, \theta$) and time. When the density is evolving too abruptly between adjacent cells to allow interpolating in this simple way (which is the case close to the surface of the torus where the density gradient becomes quite steep), the closest neighboring grid zone is used. The torus is assumed not to be varying in the $\varphi$ direction, but can easily be made 3D from the 2.5D simulations, since Cosmos++ evolves all three components of the spatial velocity.

### 3 POWER SPECTRA OF THE OSCILLATING TORI

The light curves from each of our simulations and each of our radiation models are shown in Figs. 2 and 3, for an observer inclination of $i = 10^\circ$ (nearly face-on view). For all cases, the maximum relative flux variation (pulsed fraction) is of the order of 1%. This is in reasonable agreement with observations. In Fig. 3, we also notice a small increasing trend in the optically thin lightcurves and decreasing trend in optically thick ones. Both are due to numerical fluctuations of density from cell to cell in the hydrodynamical simulations.

The Lomb-Scargle PDS [Press & Rybicki, 1989] of all light curves (two radial positions of torus with two different inclinations) are shown in Figs. 4 and 5. The first obvious feature appearing from the PDS is that all of them are dominated by peaks corresponding to the mode(s) of initial perturbation. More interesting is the presence of additional peaks in all PDS. Given that the diagonal perturbation PDS appear simply as the sums of the radial and vertical PDS, we shall mainly focus on these last ones in our discussion.

![Figure 1. Three initial velocity perturbations to the torus. Plots only present the initial torus with pressure maximum at $R_c = 15 M$. The torus setup at $R_c = 10 M$ looks qualitatively similar at the corresponding radial position.](image)

Table 2. Initial torus setup, the torus cross-section is always equal to $0.5 M$.

| Perturbation | $r_{in} (M)$ | $R_c (M)$ | $r_{cross}/R_c$ | Observed modes |
|--------------|-------------|-----------|----------------|----------------|
| Radial       | 9.5         | 10.0      | 0.05           | rad, +, breath |
| Radial       | 14.5        | 15.0      | 0.03           | vert, X, breath |
| Vertical     | 9.5         | 10.0      | 0.05           | vert, X, breath |
| Vertical     | 14.5        | 15.0      | 0.03           | vert, X, breath |
| Diagonal     | 9.5         | 10.0      | 0.05           | rad, vert, +, X, breath |
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In the radial PDS of Figs. 4 and 5, the prominent peaks correspond to the radial, plus, and breathing modes, as well as the sum of the radial and plus modes and higher harmonics of the radial mode. We note that the radial, optically thin PDS at $R_c = 15 M$ is comparable to the results obtained by Schnittman & Rezzolla (2006) for the same radial position of the center of torus, although our torus is much more slender (about a factor of 100). The peaks in Schnittman & Rezzolla (2006) with labels $f$, $o_1$, $o_2$, $o_3$ (reproduced, for convenience, in the upper panel of our Fig. 5) correspond to our radial (57 Hz), plus (82 Hz), twice the radial (114 Hz) and sum of radial and plus modes (140 Hz). In addition we also see a breathing mode, which was not present in Schnittman & Rezzolla (2006). We argue that this is due to the effect of the background on the slender torus. If we increase the cross section of our torus and make it more like Schnittman & Rezzolla (2006), the background does not affect the torus significantly and we do not see the breathing mode.

In the vertical PDS in Fig. 4 the vertical and breathing modes are present in both optically thin and thick cases. In addition, the optically thick case shows a prominent peak at the X-mode frequency, though it is much less prominent in the optically thin case. This is due to the fact that in the optically thick case we are tracing the surface and in the optically thin case the volume. The X-mode causes more fluctuations on surface than in volume. Fig. 5 has similar features as Fig. 4 except that we almost do not see the X-mode in this case. Three higher-frequency harmonics and combinations of frequencies also appear with strong power in both tori. They correspond to two times the vertical frequency, two times the X-mode frequency, as well as the sum of the vertical and X-mode frequencies. We note that multiplying two sinusoidal functions gives rise to a signal varying at the sum of their frequencies. The “vertical + X” peak could thus be interpreted as a non-linear coupling between these two modes. However, it seems more likely that it is related to the initialization of the vertical velocity perturbations. In all our PDS except for the optically-thick, vertically-perturbed case, there are clearly dominant peaks corresponding to the initial velocity perturbation mode, with all other oscillation modes appearing significantly weaker. Only in the case of the optically-thick, vertically-perturbed case is one of these “secondary” peaks of comparable strength. However, we note that the velocity eigenvector field for a vertically-oscillating, non-slender, torus contains within it the velocity field of an X-mode (see Fig. 5 of Blaes et al. 2007). Therefore, it seems most likely that this prominent X-mode is also the result of the initial perturbations and not evidence of non-linear coupling.

We also propose an intuitive explanation of the fact that a radial perturbation of the torus triggers the plus mode, whereas a vertical perturbation triggers the X-mode (qualitative sketch in Fig. 6). When the torus is excited vertically, it will essentially oscillate...
along the $z$-axis at the local, vertical epicyclic frequency. Likewise, when it is excited radially it will oscillate in the $r$-direction at the local, radial epicyclic frequency. These frequencies are functions of the coordinate radius $r$; thus different parts of the torus will oscillate at slightly different frequencies: the parts of the torus closest to the black hole will oscillate at a frequency slightly larger than the more distant parts. As a consequence, the torus cross-section will be distorted, roughly following the X mode pattern in the vertical case, and the plus mode pattern in the radial case. All PDSs in our study show precisely this trend.

Another observation that come from our data is that the breathing mode, present in all simulations, is stronger when the torus is further from the black hole. We believe that this is an anomaly owing to the fact that the background (which has the same characteristics in all simulations) acts more strongly on the more slender torus. Given that its cross-sectional radius is constant, the torus becomes relatively more slender when it is displaced away from the black hole. This bigger interaction of the background with the torus leads to a more prominent breathing mode. We also believe that the presence of the breathing just arises due to the initial mismatch between the torus and the background. This kind of initialization issue has been reported even in studies of unperturbed tori (Srámková, Torkelsson & Abramowicz 2007).

We do not note a strong inclination dependence in our optically thin PDS, which seems contradictory to previous works, in particular Bursa et al. (2004). However, these findings have been obtained for an incompressible torus and the inclination dependence is a very strong function of the torus equation of state (M. Bursa, private communication). The inclination dependence reported in Schnittman & Rezzolla (2006) is also obtained for a different equation of state ($\Gamma = 4/3$), and for a much thicker torus. Only a full parameter study, which goes beyond the scope of the present paper and will be the subject of future work, will allow a more thorough exploration of the inclination dependence.

To recapitulate, the most important conclusion of our analysis is that the dominant modes appearing in the PDS are the radial, plus and breathing modes for a radial perturbation, and the vertical, X and breathing modes for a vertical perturbation. However, we do not observe a clear domination of peaks in a 3:2 ratio (X/vertical, plus/radial, or vertical/breathing). Our current results thus do not show any natural selection mechanism for the 3:2 QPOs. However, the dominant peaks might be (and most probably are) dependent on the initial condition (in particular the initial velocity field and the torus size). We will devote future study to determining if some configurations naturally generate dominant 3:2 oscillations.

4 CONCLUSIONS

We performed hydrodynamic simulations of oscillating slender tori and ray-traced the results to obtain power density spectra. We con-
centrated on three types of perturbations: radial, vertical and diagonal. The important conclusions of the article concern the dominant modes, possibility of presence of non-linear coupling of vertical and X-mode, an absence of inclination dependence in optically thin case and the different distributions of mode power for different radiative transfer models. To summarize:

1. We found that a uniform radial perturbation of the velocity field can trigger both the radial mode and the plus mode. Likewise, a uniform vertical perturbation of the velocity field can trigger the vertical mode and an X-mode. This point is illustrated in Fig. 6. We also found that no matter where we place the center of the torus, we see a similar response. We argue that the presence of both the radial and plus mode or the vertical and X-mode is owing to non-uniform velocity vectors of the vertical and radial eigenmodes in an even slightly non-slender torus.

2. We did not find any clear dependence on inclination in our ray-traced light curves for optically thin case, whether the torus was nearly edge-on or nearly face-on. We suspect that this is due to the fact that our tori are very slender and compressible.

3. We found that the two different radiative models we considered can give very different lightcurves and hence different PDS. In particular, the optically thin and thick cases give different powers in the plus- and X-modes.

Figure 4. Power density spectra (PDS) of the oscillating torus with radial, vertical and diagonal velocity perturbation (top to bottom). The initial pressure maximum of the torus lies at \( R_c = 10 \, M \). The horizontal axis corresponds to frequency normalized to the Keplerian frequency at the center of the torus, \( \nu_c \). The solid black and dashed red curves show the PDS for two inclinations \( i = 10^\circ \) and \( i = 70^\circ \), respectively. The left and right panel correspond to optically thin and thick cases, respectively. The vertical gray lines are located at the values of frequencies of the five lowest order oscillation modes for a \( R_c = 10 \, M \) torus, as given in Table I.

Figure 6. Qualitative illustration of the response of a torus to a uniform vertical (top) and radial (bottom) 4-velocity perturbations.
ACKNOWLEDGMENTS

We thank Jiří Horák, Omer Blaes, Michal Bursa and Odele Straub for enlightening discussions at various stages of this work. MB also thank to College of Charleston SC for hosting during final stage of project. Research was supported by Polish NCN grant UMO-34 2011/01/B/ST9/05439 and 2013/08/A/ST9/00795. Part of the work was supported by the Polish NCN grant 2013/09/B/ST9/00060.

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