Geometric phase in St"uckelberg interferometry

Lih-King Lim,1,2 Jean-No"el Fuchs,3,4 and Gilles Montambaux4
1LCF, Institut d’Optique, CNRS, Universit´e Paris-Sud, 2 avenue Augustin Fresnel, F-91127 Palaiseau, France
2Max-Planck-Institut f¨ur Physik komplexer Systeme, D-01187 Dresden, Germany
3LPTMC, CNRS UMR 7600, Universit´e Pierre et Marie Curie, 4 place Jussieu, F-75252 Paris, France
4Laboratoire de Physique des Solides, CNRS UMR 8502, Universit´e Paris-Sud, F-91405 Orsay, France
(Received 23 December 2014; published 15 April 2015)

We study the time evolution of a two-dimensional quantum particle exhibiting a two-band energy spectrum with two Dirac cones as, for example, in the honeycomb lattice. A force is applied such that the particle experiences two Landau-Zener transitions in succession in the vicinity of the Dirac cones. The adiabatic evolution between the two transitions leads to St¨uckelberg interferences, due to two possible trajectories in energy-momentum space. In addition to well-known dynamical and Stokes phases, the interference pattern reveals a geometric phase which depends on the chirality (winding number) and the mass sign associated with each Dirac cone, as well as on the type of trajectory (parallel or diagonal with respect to the two cones) in parameter space. This geometric phase reveals the coupling between the bands encoded in the structure of the wave functions. St¨uckelberg interferometry therefore appears as a way to access both intra- and interband geometric information.

DOI: 10.1103/PhysRevA.91.042119 PACS number(s): 03.65.Vf, 03.75.Dg, 03.75.Lm, 37.10.Jk

I. INTRODUCTION

St¨uckelberg interferometry is the realization of an interferometer for a quantum particle with an energy spectrum possessing at least two branches, or bands, separated by a gap (for example, due to a band structure). The problem was originally raised in the context of slow atomic or molecular collisions experiencing multiple electronic transitions [1], where each transition is modeled by the Landau-Zener (LZ) tunneling process [2]. It has since been mapped onto a wide class of systems described by a two-level, time-dependent Hamiltonian with multiple avoided crossings, including the microwave excitation of Rydberg atoms [3,4], superconducting qubits [5–7], quantum wires [8], as well as Bose-Einstein condensates in optical lattices [9,10]. For a general review of St¨uckelberg interferometry, see Ref. [5].

Recently, topological band-structure engineering has attracted a lot of interest both in condensed-matter systems [11,12] as well as in artificial crystals [13] simulated by various means such as cold atoms in optical lattices [14–19], microwave resonators [20], or polaritons [21]. In these systems, Dirac cones in the Bloch energy spectrum are the basic entity of interest [22,23]. Moreover, the construction of topological bands can be induced by a modification of the local character of Dirac cones, e.g., by changing the relative signature of the masses of two Dirac cones [24]. While the hallmark of a simple topological state is displaying perfectly quantized conductance at the edge (or boundary) [11], it is interesting to search for measurable bulk topological signatures in these new systems [17,25–27].

In this work, we consider a St¨uckelberg interferometer made of two massive Dirac cones in two dimensions (2D). By accelerating a quantum particle through the two cones in succession, nonadiabatic processes at the two avoided crossings (described by LZ tunnelings) coherently split and recombine the wave function; see Fig. 1(a). The final transition probability oscillates in magnitude due to interferences between the two possible paths in the energy space, as the phase accumulated along the path is varied [Fig. 1(b)]. An analogy can be drawn with the optical Mach-Zehnder interferometer, except that with a St¨uckelberg interferometer the motion of the quantum particle takes place in the energy-momentum plane instead of the real-space x-y plane. The avoided crossings play the role of the optical beam splitters and the two adiabatic energy

FIG. 1. (Color online) (a) A St¨uckelberg interferometer made of two avoided crossings (D and D’) in an energy spectrum E as a function of momentum p. A particle initially in the lower band is forced through the two avoided crossings that act as beam splitters. Pf is the probability for the particle to end up in the upper band. This can occur through two different paths in energy-momentum space. (b) The geometric phase \( \phi_g \) is revealed in the interference pattern \( (P_f, \text{as a function of the distance } DD’) \). The dashed blue line \( \phi_g = 0 \) corresponds to trajectory (c) and the solid red line \( \phi_g \neq 0 \) corresponds to trajectory (d). (c),(d) Double Dirac cone energy spectrum as a function of two-dimensional momentum with parallel [(c) blue arrow] or diagonal [(d) red arrow] trajectories. Chirality (shown as directed circles) and mass \( M \) of each Dirac cone are also indicated (see text).
bands (upper and lower bands) are the analog of the two optical arms [28,29]. It is also important to realize that the St"uckelberg interferometer here deals with spinorial and not scalar waves. The internal degree of freedom is related to the band index (lower or upper band) which arises, for example, from the pseudospin-1/2 sublattice degree of freedom in a honeycomb tight-binding system. In an optical Mach-Zehnder interferometer, this role would be played by the polarization of light. As anticipated long ago by Pancharatnam [30], the phase and the contrast of interferences can be modified by the polarization degree of freedom. The purpose of the present article is to study the influence of the pseudospin degree of freedom of the quantum particle on the St"uckelberg interferometer.

We show that, in addition to the well-known dynamical phase which depends on the energy separation between the two bands and the Stokes phase accumulated at the LZ transitions, there is a geometric contribution which has the form of a gauge-invariant open-path geometric phase (also called noncyclic geometric phase) [31,32]. The later being a generalization of the well-known Berry phase [33]. This is the central result of this work, as first anticipated by us in a recent letter [34]. A gauge-dependent geometric phase had been proposed earlier in the context of multiple LZ transitions [6]. This geometric phase depends on the chirality and the mass of the Dirac cones, as well as the type of trajectory crossing the two Dirac cones. As an illustration, Figs. 1(c) and 1(d) show two different trajectories for a double cone energy spectrum with given masses and chiralities. They both correspond to the same energy landscape [Fig. 1(a)] but result in different interference pattern, see the two curves Fig. 1(b).

We stress the differences with recent interferometric studies with Dirac cones where only adiabatic evolution within a single band is considered [19,35,36]. Here, nonadiabatic transitions between two bands are required to realize the St"uckelberg interferometer. Moreover, unlike the single avoided crossing problem (a LZ problem) an exact solution to the problem of a double LZ Hamiltonian does not generally exist [37–39]. The theoretical framework we employ is therefore founded on two approximation schemes, i.e., the so-called adiabatic impulse model [5], where the two LZ tunneling events are taken to be independent, and the adiabatic perturbation theory.

The paper is organized as follows. In Sec. II we introduce four classes of Bloch Hamiltonians featuring a pair of Dirac cones. Then by considering two types of trajectories in the parameter space, we obtain eight time-dependent Hamiltonians for St"uckelberg interferometry. In Sec. III, we provide a heuristic but general solution to the interferometer problem based on St"uckelberg theory and showing the presence of a nontrivial geometric phase affecting the interference pattern. In Sec. IV, we mathematically formulate the dynamics of a quantum particle going through such an interferometer. In Secs. V–VIII, we consider the specific case of a double cone with the same mass, opposite chirality, and a diagonal trajectory and contrast it with that of a parallel trajectory studied in Ref. [37]. In Sec. V, we first show numerically the presence of a phase shift. Then we compute the geometric phase using different basis and gauge choices. In Sec. VI, we give its analytic derivation using adiabatic perturbation theory. We then study the special massless limit in Sec. VII. Section VIII provides a geometrical interpretation of the geometric phase on the Bloch sphere. In Sec. IX we give the geometric phase for the eight types of St"uckelberg interferometers. We conclude in Sec. X.

II. MODELS AND STATEMENT OF THE PROBLEM

A Dirac cone in the energy spectrum displays interesting topological character related to the (pseudo-)spinorial nature of the associated wave function. To give an example that highlights the importance of the pseudospin structure, it essentially determines the Chern number of a 2D energy band in the modern topological characterization of band structure [11]. To reveal this pseudospin structure in St"uckelberg interferometry, we consider the low-energy description of a given pair of inequivalent Dirac cones, inspired by the merging transition of Dirac points in uniaxially deformed graphene [15,40,41].

A. Four classes of Bloch Hamiltonians featuring a pair of Dirac cones

By restricting to Dirac cones with ±1 topological charges (see below), we begin by introducing two broad classes [40–42] of Bloch Hamiltonians [43].

1. Dirac cone pair with opposite chirality

The first class is given by the low-energy expansion

\[ H(\vec{p}) = \left( \frac{p_x^2}{2m} - \Delta_+ \right) \sigma_x + c_y p_x \sigma_y + M_z(\vec{p}) \sigma_z, \]

(1)

where \( \vec{p} = (p_x, p_y) \) is the long-wavelength quasimomentum (a parameter, not an operator), \( m \) gives the band curvature in the \( x \) direction, and \( c_y > 0 \) is the \( y \)-direction velocity. The Pauli matrices \( \sigma_x,y,z \) operate in the pseudospin space, which stems from a sublattice degree of freedom of the microscopic 2D tight-binding lattice model of graphene. In other words, the Hamiltonian is the low-energy Bloch Hamiltonian centered at the midpoint in reciprocal space between the two Dirac cones. The function \( M_z(\vec{p}) \) opens a gap at the two Dirac cones and is usually referred to as a “mass.” We consider two such mass functions: Either \( M_z(\vec{p}) = M \) is a constant or \( M_z(\vec{p}) = c_z p_x \)

changes sign between \( p_x < 0 \) and \( p_x > 0 \) assuming that the velocity parameter \( c_z > 0 \) (see the end of the section for their physical meanings).

The properties of this first class of Bloch Hamiltonians are, first, that the energy spectrum is

\[ E_{\pm}(\vec{p}) = \pm \left[ \left( \frac{p_x^2}{2m} - \Delta_+ \right)^2 + c_y^2 p_y^2 + M_z(\vec{p})^2 \right]^{1/2}. \]

(2)

The two gapped Dirac cones lie on the \( p_y = 0 \) axis and \( \Delta_+ \geq 0 \) determines the distance between the two cones located at valleys \( \vec{p} = D, D' \approx (\pm \sqrt{2m} \Delta_+ 0) \); see Fig. 3. The gap is \( 2|M_z(D, D')| \).

Second, the Dirac cones are characterized by their chirality, or winding number. This is a property of the eigenstates \( |\psi_{\pm}(\vec{p})\rangle \) or of the Bloch Hamiltonian \( H(\vec{p}) \) that is not apparent in the energy spectrum. In order to reveal it, we parametrize the \( 2 \times 2 \) Bloch Hamiltonian (1) as a Zeeman-like Hamiltonian for
a spin $\vec{\sigma}$ in a magnetic field $\vec{B}(\vec{p})$ such that

$$H(\vec{p}) = \vec{B}(\vec{p}) \cdot \vec{\sigma} = E_+ \vec{n}(\vec{p}) \cdot \vec{\sigma},$$

(3)

where $\vec{n}(\vec{p})$ is a 3D unit vector living on a Bloch sphere $S^2$ (see Fig. 2). In spherical coordinates $\vec{n} = [\sin \theta \cos \phi, \sin \theta \sin \phi, \cos \theta]$, where $\theta$ is the polar angle (from the north pole between 0 and $\pi$) and $\phi$ is the azimuthal angle (along the equator from 0 to $2\pi$). At each point in the 2D quasimomentum $\vec{p} = (p_x, p_y)$ space, we associate the unit vector $\vec{n}(\vec{p})$ that gives rise to the pseudospin texture mentioned at the beginning of this section. One interesting quantity to examine is the azimuthal angle $\phi$ as a function of $\vec{p}$ (see Fig. 3), where we notice the presence of quantized vortices located at the position of the Dirac cones in the energy spectrum; i.e., $\vec{p} = D, D' \approx (\pm \sqrt{2m\Delta_x}, 0)$. Note that the existence of these vortices is independent of $M_z(\vec{p})$ being zero or not; i.e., it is not tied to the existence of contact points (Dirac points) in the energy spectrum. These vortices carry opposite topological charges $W = \pm 1$, known as a chirality or winding number; see Fig. 3(a). This can be computed on a line integral on a contour encircling $D$ or $D'$ as $W = \frac{1}{2\pi} \oint \vec{B} \cdot d\vec{l} \phi$. When $M_z = 0$, the two Dirac cones are gapless. In that case, the Berry phase acquired when encircling a single Dirac cone is quantized to $\pi$ (note that the Berry phase is defined modulo $2\pi$), so that the winding numbers $\pm 1$ correspond to the same Berry phase of $\pi$). This is no longer true upon opening a gap $M_z \neq 0$, although the quantized vortices are still present (see, e.g., the discussion of that point in Ref. [44]). We thus see that the opening of an energy gap, even though rendering the band structure semiconductorlike, merely modifies the orientation of the pseudospin direction while band coupling effects remain important. As we already mentioned, for a gapped spectrum both the signs of the "masses" $\text{sgn}[M_z(D, D')]$ and their chirality are relevant information for determining the Chern number of that band; see, e.g., Refs. [11,45].

2. Dirac cone pair with same chirality

The second class of Bloch Hamiltonians is given by [42]

$$H(\vec{p}) = \left(\frac{p_x^2 - p_y^2}{2m} - \Delta \right) \sigma_x + \frac{p_x p_y}{m} \sigma_y + M_z(\vec{p}) \sigma_z,$$

(4)

In this case, the energy spectrum $E_\pm(\vec{p}) = \pm \sqrt{\left(\frac{p_x^2 - p_y^2}{2m} - \Delta \right)^2 + \left(\frac{p_x p_y}{m}\right)^2 + M_z(\vec{p})^2}$ is qualitatively similar to the previous case (see Fig. 3), featuring two gapped Dirac cones at $\vec{p} = (D, D') \approx (\pm \sqrt{2m\Delta_x}, 0)$. The crucial difference is that here, the two Dirac cones possess the same chirality. This is most clearly seen by plotting the corresponding azimuthal phase $\phi(\vec{p})$; see Fig. 3(b). The two vortices with topological charge $+1$ are clearly seen. For this Bloch Hamiltonian, we also consider two different mass functions $M_z(\vec{p}) = M$ or $c_1 p_x$.

3. Physical examples

In order to refer to these four cases, we introduce the following notations. Let $\chi$ be the product of the chirality of the two cones ($\chi = \pm 1$), and $\mu$ be the product of the mass sign of the two cones ($\mu = \pm 1$). The four classes of Bloch Hamiltonians parametrized by $(\chi, \mu) = (\pm, \pm)$ becomes

$$H_{\chi, \mu}(\vec{p}) = X_\chi(\vec{p}) \sigma_x + Y_\chi(\vec{p}) \sigma_y + Z_\mu(\vec{p}) \sigma_z,$$

(5)

with $X_\chi(\vec{p})$, $Y_\chi(\vec{p})$, and $Z_\mu(\vec{p})$ summarized in Table I. The physical meaning of the four Bloch Hamiltonians becomes clear. For $(\chi, \mu) = (+, +)$, it describes a pair of Dirac cones with opposite chirality and a constant mass function. This is the low-energy Hamiltonian describing gapped graphene due to inversion symmetry breaking (as boron nitride, e.g.) [46]. For $(\chi, \mu) = (-, -)$, it corresponds to a pair of Dirac cones
TABLE I. Summary of four classes of Bloch Hamiltonians $H_{χ,μ}(\vec{p}) = X_χ(\vec{p})\sigma_χ + Y_χ(\vec{p})\sigma_y + Z_μ(\vec{p})\sigma_z$ with $(χ,μ) = (±,±)$ depending on the chirality product $χ$ and the mass sign product $μ$.

| $(χ,μ)$ | $X_χ(\vec{p})$ | $Y_χ(\vec{p})$ | $Z_μ(\vec{p}) = M_χ(\vec{p})$ |
|------|--------|--------|-----------------|
| ($+,+$) | $\frac{p_+^2}{2m} - \Delta_+$ | $c_χp_χ$ | $M$ |
| ($-,+$) | $\frac{p_-^2}{2m} - \Delta_-$ | $c_χp_χ$ | $c_χp_χ$ |
| ($+,−$) | $\frac{p_+^2}{2m} - \Delta_+$ | $\frac{p_0p_y}{m}$ | $M$ |
| ($−,−$) | $\frac{p_-^2}{2m} - \Delta_-$ | $\frac{p_0p_y}{m}$ | $c_χp_χ$ |

Stückelberg interferometer given by

$$H_{χ,μ,τ}(t) = X_χ(t)\sigma_χ + Y_χ(t)\sigma_y + Z_μ(t)\sigma_z,$$

with the components summarized in Table II. The adiabatic energy spectrum takes the form $E_±(\vec{p}) \rightarrow E_±(t)$ featuring two avoided crossings as expected; see Fig. 4(b).

C. Statement of the problem

For the $2 \times 2$ time-dependent Hamiltonian $H_{χ,μ,τ}(t)$ of the above form, the state $|ψ(t)⟩$ evolves according to the time-dependent Schrödinger equation $i\frac{d}{dt}|ψ(t)⟩ = H_{χ,μ,τ}(t)|ψ(t)⟩$. The instantaneous eigenstates corresponding to upper (lower) energy bands are defined in the usual way $H_{χ,μ,τ}(t)|ψ_+(t)⟩ = E_+(t)|ψ_+(t)⟩$, with the eigenstates being spinors (they can be represented on a Bloch sphere) and are defined up to a gauge choice (i.e., a time-dependent phase choice). The Stückelberg interferometer problem is to compute the transition probability $P_f = |⟨ψ_+(+∞)|ψ(t → +∞)⟩|^2$, namely the probability for a particle to end up in the upper band in the far future $|ψ_+(+∞)⟩$ given the initial state (in the far past) in the lower band $|ψ(t → −∞)⟩ = |ψ_-(−∞)⟩$.

III. STÜCKELBERG THEORY INCLUDING A GEOMETRIC PHASE

We first give a heuristic solution of the interferometer problem, based on Stückelberg theory. The spirit is to treat each avoided crossing as an independent LZ tunneling event.

### Table II

| No. | $(χ,μ,τ)$ | $X_χ(t)$ | $Y_χ(t)$ | $Z_μ(t)$ |
|-----|---------|--------|--------|--------|
| 1   | $(+,+,+)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $c_χp_χ$ | $M$ |
| 2   | $(+,+,-)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $c_χF_χt$ | $M$ |
| 3   | $(+,−,+)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $c_χp_χ$ | $c_χF_χt$ |
| 4   | $(+,−,−)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $c_χF_χt$ | $c_χF_χt$ |
| 5   | $(+,+,+)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $\frac{p_0p_y}{m}$ | $M$ |
| 6   | $(+,+,-)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $\frac{p_0p_y}{m}$ | $M$ |
| 7   | $(+,−,+)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $\frac{p_0p_y}{m}$ | $c_χF_χt$ |
| 8   | $(+,−,−)$ | $\frac{p_+^2}{2m} - \Delta_+$ | $\frac{p_0p_y}{m}$ | $c_χF_χt$ |
and paying extra attention to the adiabatically accumulated phase in between the two LZ events. Everything nonadiabatic is assumed to occur at the LZ events.

For a single linear crossing, usually described by a Hamiltonian $\mathcal{H}(t) = A \sigma_z + V \sigma_x$ (with $A$ and $V \in \mathbb{R}$) in the vicinity of the crossing assumed at $t = 0$, the LZ tunneling probability is $P_{LZ} = e^{-\gamma V^2/2|A|}$, where $\gamma = V^2/2|A|$ is the speed of the adiabaticity parameter ($\delta \to \infty$ in the adiabatic limit).

In the St"uckelberg interferometer problem $H_{\text{st},\mu,\tau}(t)$ with two linear avoided crossings, we follow Ref. [5] using the so-called adiabatic impulse model, which is valid in the St"uckelberg regime, i.e., assuming the two LZ events are independent. This means that the time spent between the two avoided crossings should be much larger than the tunneling time, which may be estimated as $t_{LZ} \sim \frac{1}{|\gamma|} \max(\delta, \sqrt{\delta})$ [5].

Around the first linear crossing $t = t_i$, we use the so-called $N$ matrix which relates the probability amplitudes (in the upper, lower band) at time right before the crossing $t = t_i^-$ to the probability amplitudes at time right after the crossing $t = t_i^+$ [5]. The $N$ matrix is a recasting of the exact solution of the time-dependent problem of a single linear avoided crossing [2] in terms a scattering matrix, including the crucial phase information related to nonadiabatic processes. The $N$ matrix for the second linear crossing at $t = t_f$ is similarly defined. The two matrices are given by

$$N_{i=+t} = \left( \begin{array}{cc} \sqrt{1 - P_{LZ}e^{-i\varphi_S}} & -\sqrt{P_{LZ}} \\ -\sqrt{P_{LZ}} & \sqrt{1 - P_{LZ}e^{i\varphi_S}} \end{array} \right)$$

and

$$N_{i=+t} = \left( \begin{array}{cc} \sqrt{1 - P_{LZ}e^{-i\varphi_S}} & \sqrt{P_{LZ}} \\ -\sqrt{P_{LZ}} & \sqrt{1 - P_{LZ}e^{i\varphi_S}} \end{array} \right) = (N_{i=+t})^T,$$ (8)

where $\varphi_S = \pi/4 + \delta(\ln \delta - 1) + \arg \Gamma(1 - \delta i)$ is the phase acquired upon being reflected at a LZ crossing (the so-called Stokes phase). The transpose relation between the two $N$ matrices is related to the fact that the notion of upper and lower bands is inverted for the first and second avoided crossings in $H_{\text{st},\mu,\tau}(t)$. To give an example on how to read the $N$ matrix, according to $N_{i=+t}$, an initial state right before the crossing $|\psi(t_i^-)\rangle = a_- |\psi_-(t_i^-)\rangle + a_+ |\psi_+(t_i^-)\rangle$ will be transformed to a final state right after the crossing as

$$|\psi(t_i^+)\rangle = (\sqrt{1 - P_{LZ}e^{i\varphi_S}} a_- + \sqrt{P_{LZ}} a_+) |\psi_-(t_i^-)\rangle$$

$$+ (-\sqrt{P_{LZ}} a_- + \sqrt{1 - P_{LZ}e^{-i\varphi_S}} a_+) |\psi_+(t_i^-)\rangle.$$ (9)

Note that these amplitudes here do not contain any adiabatically accumulated phase. In this work we adopt the viewpoint that everything nonadiabatic is described by $N$ matrices, while everything adiabatic will be in phases acquired between tunneling events [48]. Drawing the analogy with optical Mach-Zehnder interferometer, such an $N$ matrix characterizes a linearly avoided crossing as a beam splitter of transmission $P_{LZ}$ and reflection phase $\varphi_S$ (see, e.g., [28,29]).

In traversing two linear crossings in succession (the St"uckelberg interferometer), we take the product of the two matrices $N_{i=+t}, N_{i=+t}$, and read off the final nonadiabatic phase accumulated for the two possible paths. However, the amplitude for each path also contains a phase accumulated during the adiabatic evolution. Therefore, the amplitude $B_+$ for the upper path is

$$B_+ = -\sqrt{P_{LZ} \times e^{i\varphi_S}} \sqrt{1 - P_{LZ}}.$$ (11)

It is the product of three terms (see, for example, Ref. [37]).

The first $-\sqrt{P_{LZ}}$ is the probability amplitude to tunnel from the lower to the upper band at the first crossing, and the third $\sqrt{1 - P_{LZ}}$ is the probability amplitude not to tunnel (i.e., to stay in the upper band) at the second crossing. The second term $e^{i\varphi_S}$ is the complex exponential of the total phase of the adiabatic motion between the two crossings at $t_i$ and $t_f$ given by

$$\varphi_S(t_f) = -\int_{t_i}^{t_f} dt E_+(t) + \int_{t_i}^{t_f} dt \langle \psi_+(t) | i \partial_t | \psi_+(t) \rangle + \text{arg} \langle \psi_+(t) | \psi_+(t_f) \rangle$$

$$- \int_{t_i}^{t_f} dt E_+(t) + \Gamma_+.$$ (10)

The total adiabatic phase is itself the sum of three terms: a dynamical phase, a line integral of a Berry connection along an open-path, and a projection (or geodesic) closure (i.e., an argument of an overlap between two eigenstates). While the dynamical phase depends on the band structure, the latter two depend on the band eigenstates along the path. Note that the path is open in the parameter space and that, in addition, the initial and final states are not proportional to each other.

The reason for the projection closure contribution can be understood in the adiabatic theory for the upper path between $t_i$ and $t_f$. Take an initial condition $|\psi(t_i^-)\rangle = |\psi_+(t_i^-)\rangle$ and compute $|\psi(t > t_i)\rangle$ using the adiabatic theory. This gives at the second crossing

$$|\psi(t_f)\rangle = |\psi_+(t_f)\rangle e^{i \int_{t_i}^{t_f} dt E_+(t) + \Gamma_+},$$ (11)

Therefore, the adiabatically accumulated phase along the upper path starting at $t_i$ with $|\psi_+(t_i^-)\rangle$ and ending at $t_f$ with $|\psi_+(t_f)\rangle$ is the argument of

$$\langle \psi_+(t_+)| \psi(t_f) \rangle = \langle \psi_+(t_i^-)| \psi_+(t_f) \rangle e^{i \int_{t_i}^{t_f} dt E_+(t) + \Gamma_+ | \psi_+(t_i^-) \rangle | \psi_+(t_f) \rangle$$,

which is indeed (10). Note that the open-path geometric phase $\Gamma_+$ is gauge invariant, thanks to the projection closure term [31,32]. The expression for the geometric phase is well defined when the initial and final states are not orthogonal. We come back to this point in Sec. VII when the two states are orthogonal, and in Sec. VIII we discuss its geometrical meaning.

The amplitude $B_-$ for the lower path is similarly given by the product of three terms (amplitude not to tunnel at the first crossing; adiabatically acquired phase; and amplitude to tunnel at the second crossing):

$$B_- = \sqrt{P_{LZ} e^{i\varphi_S} \sqrt{1 - P_{LZ}}},$$ (12)

where

$$\varphi_- = -\int_{t_i}^{t_f} dt E_-(t) + \Gamma_-$$
is the total adiabatic phase accumulated by the particle traveling in the lower band from one crossing to the other.

The final transition probability is therefore

\[ P_f = |B_+ + B_-|^2 \]

\[ = 4P_{LZ}(1 - P_{LZ})\sin^2(\frac{\varphi_S - \varphi_+}{2}) \]

\[ = 4P_{LZ}(1 - P_{LZ})\sin^2(\varphi_g + \varphi_{dyn}/2 + \varphi_g/2), \quad (13) \]

where the total phase (defined modulo \(2\pi\)) of the St"uckelberg interferometer is the sum of a Stokes phase \(\varphi_g\) (acquired during nonadiabatic tunneling events), a dynamical phase \(\varphi_{dyn} = \int_{t_i}^{t_f} dt(E_+ - E_-)\), and a geometric phase \(\varphi_g \equiv \Gamma_- - \Gamma_+\) given by

\[ \varphi_g = \int_{t_i}^{t_f} dt(\psi_-(i\partial_t)\psi_-) + \arg(\psi_-(t_f)\psi_-(t_f)) \]

\[ - \int_{t_i}^{t_f} dt(\psi_+(i\partial_t)\psi_+) - \arg(\psi_+(t_f)\psi_+(t_f)), \quad (14) \]

with the latter two acquired during the adiabatic evolution in between the two crossings.

In short, we recover the expected St"uckelberg interference structure in the transition probability with the overall double LZ tunnelings factor \(2P_{LZ}(1 - P_{LZ})\), a quantity determined solely by the adiabaticity parameter \(\delta\). However, in the interference pattern, besides a phase modulation related to the dynamical phase \(\varphi_S\), it generally contains a nontrivial geometric phase \(\varphi_g\), which requires the knowledge of the band eigenstates that is beyond the band structure. The appearance of this geometric phase is surprising at first sight, and it is sensitive to the pseudospin structure of the Hamiltonian \(H_{\chi,\mu}(p)\) discussed in Sec. II.

IV. DYNAMICS OF A QUANTUM PARTICLE IN THE ADIABATIC BASIS

The derivation provided in the previous section, while physically appealing, requires a more careful justification. To introduce the solution methods in the following sections, we formulate the main time evolution equations of the complete \(2 \times 2\) Hamiltonian \(H_{\chi,\mu}(t)\) in terms of the adiabatic basis.

Let the state of the system be written as

\[ |\psi(t)\rangle = \sum_{\sigma=\pm} A_\sigma(t) e^{-i\int_{t_i}^{t} dt E_\sigma(t')} \psi_\sigma(t'), \]

with \(E_+(t) = -E_-(t)\). Then the time-dependent Schrödinger equation gives

\[ \dot{A}_+ = -\langle \psi_+|\dot{\psi}_-\rangle A_- e^{i\int_{t_i}^{t} dt E_+} \]

\[ \times e^{i\int_{t_i}^{t} dt \langle [\psi_+,i\partial_t]\psi_-\rangle - \langle \psi_+,i\partial_t\psi_-\rangle}, \]

\[ \dot{A}_- = -\langle \psi_-|\dot{\psi}_+\rangle A_+ e^{-i\int_{t_i}^{t} dt E_-} \]

\[ \times e^{-i\int_{t_i}^{t} dt \langle [\psi_-,i\partial_t]\psi_+\rangle - \langle \psi_-,i\partial_t\psi_+\rangle}, \quad (15) \]

with the initial conditions \(A_-(\pm\infty) = 1\) and \(A_+(\pm\infty) = 0\). We are interested in the final transition probability \(P_f = |A_+(\pm\infty)|^2\). Band coupling occurs through \(\langle \psi_+|\psi_-\rangle\), which is the off-diagonal Berry connection \(A_{+,\pm}(t) \equiv (\langle \psi_+|\vec{p}\rangle, \pm\psi_-)\).

For a derivation of the above equations using a scalar time-independent gauge, see Appendix A.

In Ref. [37], we studied a similar set of time evolution equations with two avoided crossings that actually corresponds to case No. 1 (parallel trajectory) in Table II. Now both the off-diagonal Berry connection and the diagonal Berry connection \(\langle \psi_+|i\partial_t|\psi_\pm\rangle\) generally permit a much richer analytic structure for the transition probability (see later in the adiabatic perturbation theory section). Specifically, case No. 1 (and case No. 6) is a special case where geometric corrections are absent due to vanishing of the diagonal Berry connection and the off-diagonal Berry connection being real. In general, they are nonzero and complex valued, and these will be shown to shift the the St"uckelberg oscillations, i.e., to give rise to a geometric phase contribution to the final probability of the St"uckelberg interferometer. Thus, it generalizes our previous work (Ref. [37]) in a crucial way.

V. DIRAC CONES WITH SAME MASS, OPPOSITE CHIRALITY, AND DIAGONAL TRAJECTORY

To proceed with explicit expressions for the time-dependent Hamiltonian, we take the specific case of two Dirac cones with the same mass, an opposite chirality and diagonal trajectory (case No. 2 in Table II), where we expect nontrivial geometrical effects. The rest of the paper is devoted to this case, whereas in Sec. IX we give a summary of the results for the other cases.

We first study numerically the exact time evolution Eq. (15) and compare with the result of the St"uckelberg theory (see Sec. III). We then study the invariance of the geometric phase with respect to several choices. Only in the next section we use the adiabatic perturbation theory to derive the results analytically.

A. St"uckelberg regime

The \(2 \times 2\) time-dependent Hamiltonian of case No. 2 reads (in units such that \(F = \hbar = 2m = 1\) [34]

\[ H(t) = (t^2 - \Delta_c)\sigma_x + c_y F(t)\sigma_y + M\sigma_z, \quad (16) \]

with \(E_{\pm}(t) = \pm[(t^2 - \Delta_c)^2 + c_y^2 F_t^2 + M^2]^{1/2}\). The band crossings occur at complex times \(t\) such that \(E_+(t) = 0\). The St"uckelberg regime corresponds to the limit in which the two tunneling events are well separated. In this limit, the two avoided linear crossings are at time \(t_{\pm} = -\sqrt{\Delta_c} \approx -t_i\) and are characterized by an energy gap of magnitude \(2\sqrt{\Delta_c^2 + c_y^2 F_t^2 + M^2}/2\); see Fig. 4(b). The precise definition of the St"uckelberg regime is that the time between tunneling events \(\sim 2\sqrt{\Delta_c} \approx \text{much larger than their duration} \)

\[ \tau_{LZ} \sim (\sqrt{\Delta_c}/|c_y|) \sqrt{c_y^2 F_t^2 + M^2} \approx \sqrt{\Delta_c} \approx -t_i \approx \text{characterized by an energy gap of magnitude} \]

\[ 2\sqrt{\Delta_c^2 + c_y^2 F_t^2 + M^2}/2\]. In practice, this means that \(\Delta_c \gg \sqrt{c_y^2 F_t^2 + M^2} \gg c_y^2 F_t^2, M\), which we assume in the following.

B. Numerics

The time evolution of the system is governed by Eq. (15) using the Hamiltonian (16). We solve these equations numerically and compare also with the numerical result for a
However, as we now show, the result is unique and well defined. The dots correspond to the full numerical solution. The lines correspond to the St"uckelberg theory $P_f = 4P_{LZ}(1 - P_{LZ})\sin^2(\phi_S + \phi_{\text{g}n}/2 + \phi_S/2)$. In case No. 1 (dashed line) $\phi_S = 0$, whereas $\phi_S = \Delta\varphi = -2\arctan\frac{\Delta k}{M} \approx -\pi/4$ in case No. 2 (solid line); see Sec. V.C. The parameters are $c, F_y = 0.14$, $M^2 = 0.35^2 - (c_y F_y t_0)^2$ and $c, F_y = c_y F_y t_0$ such that the gap at the avoided crossings is $2\sqrt{M^2 + (c_y F_y t_0)^2} = 0.7$ in both cases.

parallel trajectory (case No. 1), shown in Fig. 5 as open and solid circles, respectively. We see that the interference fringes in the latter case agree well with the prediction of the St"uckelberg theory in the absence of a geometric phase shift, namely, $P_f = 4P_{LZ}(1 - P_{LZ})\sin^2(\phi_S + \phi_{\text{g}n}/2 + \phi_S/2)$, shown as a dashed curve [37]. On the other hand, there is an obvious mismatch between the cases No. 1 and No. 2 (solid and open circles, respectively), despite the fact that the two adiabatic spectra are identical; see Fig. 4(b). However, the phase shift between the two cases is well accounted for by using the result of the St"uckelberg theory including a geometric phase shift $\phi_S = \Delta\varphi$ (see next section) with $P_f = 4P_{LZ}(1 - P_{LZ})\sin^2(\phi_S + \phi_{\text{g}n}/2 + \phi_S/2)$, shown as the solid curve. This confirms numerically that the nontrivial geometrical shift provides an additional ingredient in the understanding of the St"uckelberg phenomenon.

C. Geometric phase

We now examine more closely the geometric phase $\phi_S$ of Eq. (14) for case No. 2. Its explicit computation appears different for different choices such as Hamiltonian bases or gauge choices for the associated adiabatic eigenstates. However, as we now show, the result is unique and well defined.

1. “Basis” and gauge choices

For the case No. 2 that we study, the Hamiltonian (16) given by

$$H_{LZ}(t) = (t^2 - \Delta_n)\sigma_z + c_y F_y t \sigma_y + M \sigma_z$$

(17)

is written in the “natural” Pauli matrix basis when considering the tight-binding model for graphene consisting of two inequivalent Dirac points $D, D'$ (we call it the “graphene (gr) basis”; see Eq. (1) in Ref. [34]). To help visualize the time evolution of the Hamiltonian curve, we plot its trajectory on the Bloch sphere for the time in between $t_i$ and $t_f$; see Fig. 6(b).

By performing a time-independent unitary rotation in pseudospin space, the Hamiltonian can also be written as

$$H_{LZ}(t) = c_y F_y t \sigma_y + M \sigma_z + (t^2 - \Delta_n)\sigma_z.$$  (18)

We call it the “LZ basis”; see Eq. (2) in Ref. [34]. It is just another representation for the Pauli matrices, with the property that the main time evolution $(t^2 - \Delta_n)$ is on the matrix diagonal. The Hamiltonian curve in this basis can be obtained from a global rotation of the Hamiltonian curve plotted for the graphene basis. It is convenient at this point to introduce the angle

$$\phi_{LZ}(t_f) - \phi_{LZ}(t_i) = -2\arctan(c_y F_y \sqrt{\Delta_n}/M) \equiv \Delta\varphi$$  (19)

that will be shown to be equal to the geometric phase later. The subscript “LZ” reminds us that the parameters are obtained in the LZ basis.

Apart from these “bases” for the Hamiltonian $H(t)$, it is also necessary to specify the adiabatic eigenstates $|\psi_{\pm}(t)\rangle$ with a gauge choice. We consider two such choices called the south (S) pole gauge (when the multivaluedness of the eigenstates is at the south pole of the Bloch sphere) and the north (N) pole gauge, which combine to cover the whole parameter space of the Bloch sphere. The lower and upper band eigenstates in the two gauge choices are, respectively, given by

S: $|\psi_-(t)\rangle = \left(\begin{array}{c} -e^{-i\phi} \sin \frac{\theta}{2} \\ \cos \frac{\theta}{2} \end{array} \right)$,  $|\psi_+(t)\rangle = \left(\begin{array}{c} \cos \frac{\theta}{2} \\ e^{i\phi} \sin \frac{\theta}{2} \end{array} \right)$,

and

N: $|\psi_-(t)\rangle = \left(\begin{array}{c} -\sin \frac{\theta}{2} \\ e^{i\phi} \cos \frac{\theta}{2} \end{array} \right)$,  $|\psi_+(t)\rangle = \left(\begin{array}{c} e^{-i\phi} \cos \frac{\theta}{2} \\ \sin \frac{\theta}{2} \end{array} \right)$.

The two sets of eigenstates are related by a gauge transformation: $|\psi_{\pm}(t)\rangle \rightarrow e^{i\alpha(t)}|\psi_{\pm}(t)\rangle$.

Independently of the gauge choice, one has $\langle\psi_{\pm}(t)|\sigma_i|\psi_{\pm}(t)\rangle = \pm\vec{n}(t)$, which belongs to the unit sphere. Therefore, the Bloch sphere can be seen as either representing the direction $\vec{n}(t)$ of the magnetic field specifying the Hamiltonian $H(t) = E_n(t)\vec{n}(t) \cdot \vec{\sigma}$ or as being the projective Hilbert space for the upper band (each point $\vec{n}$ is $\langle\psi_+|\vec{\sigma}|\psi_+\rangle$ of the sphere represents a ray $e^{i\alpha}|\psi_+\rangle$, where $\alpha$ is an arbitrary phase).
TABLE III. Geometric phase $\Phi_g$ for Dirac cones with a constant mass, opposite chirality, and a diagonal trajectory (case No. 2). It is computed as the sum of a Berry connection line integral $\Theta$ and a projection closure term $\Pi$ using different Hamiltonian bases and gauge choices for the eigenstates. Here $\Delta \varphi = -2 \arctan(c_F \sqrt{\Delta s}/M)$. We see that $\Phi_g = \Delta \varphi$ in all cases.

| Basis and gauge | Berry connection line integral $\Theta$ | Projection closure $\Pi$ | Sum $\Phi_g$ |
|-----------------|---------------------------------|-----------------|----------------|
| Graphene, south (article [34] choice) | $\Delta \varphi$ | 0 | $\Delta \varphi$ |
| Graphene, north | $\Delta \varphi$ | 0 | $\Delta \varphi$ |
| LZ, south | $2 \Delta \varphi$ | $- \Delta \varphi$ | $\Delta \varphi$ |
| LZ, north (parallel transport) | 0 | $\Delta \varphi$ | $\Delta \varphi$ |

2. Computation of the geometric phase

The geometric phase is the sum of two terms $\Phi_g = \Theta + \Pi$: (i) the line integral of the Berry connection $\Theta \equiv \int_{t_0}^{t_f} dt \{ \langle \psi_r | i \partial_t | \psi_r \rangle - \langle \psi_l | i \partial_t | \psi_l \rangle \}$, which is $\int_{t_0}^{t_f} dt \phi(1 - \cos \theta)$ in the south-pole gauge and $\int_{t_0}^{t_f} dt \phi(-1 - \cos \theta)$ in the north-pole gauge; (ii) the projection closure $\Pi \equiv \arg \{ \langle \psi_r(t_f) | \psi_r(t_f) \rangle - \arg \{ \psi_l(t_f) | \psi_l(t_f) \rangle \}$, which is $2 \arg \left( e^{-i \phi(t_f)} - e^{i \phi(t_0)} \right) \sin \left[ \frac{\theta(f)}{2} \sin \left( \frac{\theta(t)}{2} \right) \right] + \cos \theta(t) / 2$ in the south-pole gauge and $2 \arg \left( e^{i \phi(t_f)} - e^{-i \phi(t_0)} \right) \cos \theta(t)/2$ in the north-pole gauge.

Using Table VI in Appendix B, we compute separately the contributions $\Theta$ and $\Pi$ in the two gauge choices with the two Hamiltonian bases. The results are summarized in Table III. We always take the limit of well-separated tunneling events ($\Delta_+ \gg c_F^2 F_{2}^2 M$), i.e., deep in the St"uckelberg regime, at the end of the computation. The line integral of the Berry connection in the LZ basis simplifies in the St"uckelberg regime in noting that the function $\cos \theta_{LZ} \approx -1$ for all $t$ except very close to $t = t_{i,f}$, where $\cos \theta_{LZ} = 0$. So we can approximate the integral $\int_{t_0}^{t_f} dt \phi(t) \cos \theta_{LZ} \approx - \int_{t_0}^{t_f} dt \phi(t) = - \Delta \varphi$.

From the results of Table III, we see that the terms $\Theta$ and $\Pi$, obtained after explicit computations of different integrals and expressions, each can assume different values from one basis or gauge choice to another but the sum of the two is an invariant (modular $2\pi$) given by $\Phi_g = \Delta \varphi$. We thus show explicitly that the geometric phase $\Phi_g = \Gamma_- - \Gamma_+$ given by the difference between two open-path geometric phases $\Gamma_{\pm}$ is a well-defined quantity: It does not depend on a choice of basis or on a gauge choice.

VI. ADIABATIC PERTURBATION THEORY: PROOF OF THE GEOMETRIC PHASE

Here we use adiabatic perturbation theory (APT) to analyze the St"uckelberg phenomenon. In order to solve Eq. (15), we follow the calculation done in [37] for the case of a parallel trajectory with $M_1(\vec{p}) = 0$ (case No. 1) and adapt it to the problem of a diagonal trajectory with $M_1(\vec{p}) = M$ (case No. 2); see Hamiltonian (16). The goal is to use APT to compute the tunneling probability directly for the St"uckelberg interferometer and to prove that, in the adiabatic limit in which $\delta \to \infty$, $\psi_S \to 0$ and $P_{LZ} = e^{-2 \pi L} \to 0$, the total tunneling probability is $P_T \approx 4 P_{LZ} \sin^2 \left[ \frac{\pi L}{2} + \frac{\pi L}{2} \right]$ with a geometric phase given by $\Phi_g = \Gamma_- - \Gamma_+$.

A. First-order adiabatic perturbation theory

We start from Eqs. (15). First-order perturbation theory means $|A_-(t)| \approx 1 \gg |A_+(t)|$ and therefore $A_- \approx 0$ so that $A_-(t) \approx 1$ at all $t$. As a consequence, we are left with one equation to solve in this approximation,

$$A_+(t) = - \int_{-\infty}^{t} dt \left\{ \langle \psi_r(t) | \psi_r(t) \rangle e^{i \phi(t) dt} 2 E_+ + \langle \psi_r(t) | i \partial_t | \psi_r(t) \rangle e^{-i \phi(t) dt} \right\} \approx e^{i \phi(t) dt} 2 E_+,$$

in order to compute the transition probability $P_T = |A_+(t_f)|^2$.

We first note that by performing a gauge transformation, $|\psi_{a(i)}(t) \rangle \to e^{i g(t) \beta} |\psi_{a(i)}(t) \rangle$, the amplitude transforms according to $A_+ \to e^{i f(t) \beta} A_+$. Thus, it differs by a constant phase, which has no consequence in the tunneling probability. Without loss of generality, we use the eigenstates in the south-pole gauge throughout this section. This leads to a band coupling expression $- \langle \psi_r | \psi_r \rangle = (1/2)(\theta - i \phi \sin \theta) e^{-i \phi \theta}$ and also the Berry connection $\langle \psi_r | i \partial_t | \psi_r \rangle - \langle \psi_r | i \partial_t | \psi_r \rangle = \phi(1 - \cos \theta)$. We then obtain for the amplitude

$$A_+(t_f) = - \int_{-\infty}^{t_f} dt \pecific{\theta - i \phi \sin \theta}{2} e^{i \phi(t) dt},$$

where the total phase is $\beta(t) \equiv - \phi(t) + \int_{-\infty}^{t} dt \pecific{\phi(t)}{1 - \cos \theta} + \int_{-\infty}^{t} dt \pecific{2 E_+}{(t)}$. The explicit form of the integrand with case No. 2 of the Hamiltonian (18) in the LZ basis can be written with the help of Table VI in Appendix B. As we will see, each term in the phase has its corresponding physical meaning as we already encountered in Sec. III: The $e^{-i \phi \theta}$ term will give rise to the projection closure when evaluated close to the two poles at $t \approx t_{i,f}$; $e^{i \phi(t) dt} (1 - \cos \theta)$ the line integral of the Berry connection and $e^{i \phi(t) dt} 2 E_+$ will give the dynamical phase.

To evaluate the expression Eq. (21), we perform a contour integration in the complex time plane. As the computation of the complex plane is quite lengthy, we give the details in Appendix C and directly discuss the results. The amplitude $A_+(t_f)$ is given as the sum of two dominant residues coming from poles at $t \approx \sqrt{\Delta s} + i c_F F_{2} / 2$ and $t \approx -t_{i}$.

$$A_+(t_f) = - \frac{\pi}{3} \left( e^{-i \beta_1 + i \beta_2} - e^{-i \beta_1 + i \beta_2} \right),$$

where we defined $\beta_{1,4} \equiv \beta(t_{i,4})$.

To simplify further, we note that for the imaginary part of $\beta_{1,4}$, we have $\Im \beta_1 = Re \int_{0}^{L} dv (2 E_+ - \phi \cos \theta) |v = Re_{i} + iv \approx \int_{0}^{L} dv (2 E_+ - \phi \cos \theta) |v = Re_{i}$, when $Re_{i} = \sqrt{\Delta s} \gg \Im m_{1} \approx 0$.
$c, F_z/2$. Similarly for $\text{Im} \beta_2 \approx \frac{1}{4} \int_0^1 d\tau (2E_+ - \phi \cos \theta)|_{\tau = Re \phi}$.

However, the terms $E_+, \phi$, and $\cos \theta$ are even function of $\tau$ and therefore $\text{Im} \beta_1 = 0$. We then have

$$A_+ (+\infty) = -\frac{\pi}{3} e^{-\text{Im} \beta_1} e^{\frac{Re \beta_1 - Re \beta_2}{2}} 2i \sin \left(\frac{Re \beta_1 - Re \beta_2}{2}\right)$$

(23)

and

$$P_f = |A_+(\infty)|^2 \approx \left(\frac{\pi}{3}\right)^2 4 e^{-2\text{Im} \beta_1} \sin^2 \left(\frac{Re \beta_1 - Re \beta_2}{2}\right)$$

$$\rightarrow 4 e^{-2\text{Im} \beta_1} \sin^2 \left(\frac{Re \beta_1 - Re \beta_2}{2}\right),$$

(24)

where in the last line we use the standard procedure to resolve the “$\pi/3$ problem” [49–51]. We now recognize the general St"uckelberg probability structure $P_f = 4P_{LZ}(1 - P_{LZ}) \sin^2(\phi_S + (\phi_{dyn} + \phi_\beta)/2)$ with $P_{LZ}$ replaced by $e^{-2\text{Im} \beta_1}$ and the total phase $\phi_S + (\phi_{dyn} + \phi_\beta)/2$ replaced by $Re \beta_1 - Re \beta_2$. In the adiabatic limit, we always have that $1 - P_{LZ} \approx 1$ and $\phi_S \rightarrow 0$.

### B. St"uckelberg formula with geometric correction

We consider separately the real and imaginary parts of $\beta_{1,2}$. For the real part, we have $Re \beta_1 = Re \phi_1 - \pi/2 - Re \int_0^{\tau_i} dt \phi_{LZ} \cos \theta_{LZ} \approx Re \phi_1 - \pi/2 + \int_0^{\tau_i} dt \phi_{LZ} \approx Re \phi_1 + \phi_{LZ}(\tau_i) - \pi$, and $Re \beta_2 \approx Re \phi_2 + \phi_{LZ}(\tau_i) - \pi$. We finally get

$Re \beta_1 - Re \beta_2 \approx 2 \int_0^{\tau_i} dt E_+(t) + \phi_{LZ}(\tau_i) - \phi_{LZ}(\tau_i) = \phi_{dyn} + \Delta \phi,$

as expected for the phase of the St"uckelberg interferometer in the adiabatic limit in which the Stokes phase vanishes.

We therefore find that indeed the extra phase $\phi_S$ in the St"uckelberg oscillations, which we previously identified to the two-band open-path geometric phase $\Gamma_+ - \Gamma_-$, is also equal to $\Delta \phi$, which is a phase difference accumulated at each tunneling event. Note that the two derivations are quite different: On the one hand, the extra phase appears as being accumulated during the adiabatic evolution along each band, and on the other hand, it seems to be captured during tunneling events.

For the imaginary part, we have $Im \beta_1 = Im \phi_1 - Im \int_0^{\tau_i} dt \phi \cos \theta$. First, $Im \phi_1 \approx \frac{\pi}{4} \sqrt{\frac{\gamma^2}{2} + \frac{\Delta^2}{2}}$. We recognize the adiabaticity parameter $\delta = \frac{\gamma^2 F_z^2}{4 \sqrt{\frac{\Delta^2}{2} + \frac{\gamma^2}{2}}} \approx \frac{\gamma^2 F_z^2}{\sqrt{\frac{\Delta^2}{2} + \frac{\gamma^2}{2}}}$ and the LZ probability $P_Z = e^{-2\text{Im} \beta_1} \approx e^{-\pi/\sqrt{\frac{\Delta^2}{2} + \frac{\gamma^2}{2}}} \approx e^{-2\text{Im} \phi_1}$. This is not surprising as $e^{-2\text{Im} \phi_1} = e^{-2 Im \int_0^{\tau_i} dt [E_+(t) - E_-(t)]}$ is the general expression of Dykhne for the tunneling probability in the adiabatic limit [49]. Second, there is a small correction to the LZ probability coming from the imaginary part of the “geometrical phase” $-Im \int_0^{\tau_i} dt \phi_{LZ} \cos \theta_{LZ}$. This is similar to the geometrical correction for the tunneling probability found for a single avoided crossing by Berry in 1990 [52]. This is a small correction that we neglect in the following.

Eventually, in the spirit of the Dykhne-Davis-Pechukas formula [49,50], we can propose a heuristic generalization of the result (that we obtained in the adiabatic limit), which should work well also in the diabatic and in the intermediate force regimes:

$$P_f \approx 4e^{-2\text{Im} \beta_1} (1 - e^{-2\text{Im} \beta_1}) \sin^2 \left(\frac{Re \beta_1 - Re \beta_4}{2} + \phi_\beta\right).$$

(26)

This was called the “modified St"uckelberg formula” in [37] with the extra extension that it now also includes geometrical effects. Note that here, $Re \beta_1 - Re \beta_4 \neq Re \beta_2$ due to the geometric phase, in contrast to the case found in [37].

### C. Hamiltonian in the graphene basis

Finally, we also want to verify that the result is independent of the Hamiltonian basis used. Indeed, the same analysis can be repeated for the same trajectory and parameters with the Hamiltonian (17) in the graphene basis. Following the procedures as in Appendix C, we arrive at the final probability amplitude

$$|A_+|^2 = 4e^{-2\text{Im} \beta_1} \cos^2 \left(\frac{Re \beta_{gr,1} - Re \beta_{gr,4}}{2}\right),$$

(27)

noting the $\cos^2(\cdot \cdot \cdot)$ dependence in this basis [rather than $\sin^2(\cdot \cdot \cdot \cdot)$ dependence] due to the difference in the sign of the residue contributions. The subscript “$gr$” reminds us that the expressions are obtained in the graphene basis. In particular, its argument is given by

$$Re \beta_{gr,1} - Re \beta_{gr,4} = \phi_{dyn} - \int_0^{\tau_i} dt \phi_{gr} \cos \theta_{gr}.$$  

(28)

The last integral can be evaluated to give $-\int_0^{\tau_i} dt \phi_{gr} \cos \theta_{gr} \approx \Delta \phi + \pi$ (see Appendix D). So the extra “$\pi$ shift” in the second term brings us back to the same result as Eq. (24). In other words, we arrive at the same gauge invariant geometric contribution $\Delta \phi$ in the St"uckelberg interferometer in the adiabatic limit.

Looking back at Table III, we see that the two bases result in Berry connection and projection closure terms that are quite different. It is a priori a result based on a heuristic derivation of the St"uckelberg theory. Here with the APT in the two bases, we prove that the final gauge invariant observable is indeed $\phi_S = \Delta \phi$.

### VII. MASSLESS DIRAC CONES WITH OPPOSITE CHIRALITY AND DIAGONAL TRAJECTORY

The massless limit of case No. 2 (Dirac cones with zero mass) deserves special attention. By restricting to $M = 0$, the Hamiltonian curve is restricted to evolve on a great circle of the Bloch sphere [i.e., on the equator in the graphene basis at $\theta_{gr}(t) = \pi/2$] with only two of three Pauli matrices appearing in the Hamiltonian $H(t)$, despite the fact that the spectrum remains gapped $E_{\pm} (t) = \pm (t^2 - \Delta)^2 + c_1^2 F_z^2 t^2)^{1/2}$. This is a limit which is often referred to as possessing a chiral or sublattice symmetry in the graphene literature (in the graphene basis, $\sigma_z$ plays the role of a chiral operator as it squares to 1 and anticommutes with the Hamiltonian).

It follows that the open-path geometric phase $\Gamma_- = \pi/2$.
we find that $\Gamma_+ - \Gamma_- = 2\Gamma_+ = 0$ modulo $2\pi$ (except in the antipodal case). Therefore, it would seem that $\varphi_S = 0$ in the massless case. Actually, the initial and end points of the Hamiltonian curve for case No. 2 with $M \rightarrow 0$ move to $\theta_{g}(t_i) = \theta_{g}(t_f) \rightarrow \pi/2$ and $\phi_{g}(t_i) = 0, \phi_{g}(t_f) = \pi$. On the Bloch sphere, thus, they are positioned precisely at an antipodal position, which results in this case in an ill-defined expression for the geometric phase (see, however, Ref. [53]). We therefore devote this section to the study of this special limit using several techniques.

Following the solution methods in the last two sections, we first numerically solve the time evolution equation. Then we use the APT in two ways. First, we take the massless limit $M \rightarrow 0$ of the “massive” case of Eq. (24). Second, we redo the APT working directly with $M = 0$.

A. Numerics

We numerically solve the time-dependent Schrödinger equation (15) for case No. 2 with $M = 0$ in the Stückelberg regime; see Fig. 7 with open circles. As a reference, we compare it with the Stückelberg theory in the absence of a geometric phase shift, namely, we find that $\varphi_S = 0$ (case No. 1; see [37]) or $\varphi_S \rightarrow \pi$ (case No. 2). Therefore, it would seem that $\varphi_S = 0$ in the massless case. Actually, the initial and end points of the Hamiltonian curve for case No. 2 with $M \rightarrow 0$ move to $\theta_{g}(t_i) = \theta_{g}(t_f) \rightarrow \pi/2$ and $\phi_{g}(t_i) = 0, \phi_{g}(t_f) = \pi$. On the Bloch sphere, thus, they are positioned precisely at an antipodal position, which results in this case in an ill-defined expression for the geometric phase (see, however, Ref. [53]). We therefore devote this section to the study of this special limit using several techniques.

Following the solution methods in the last two sections, we first numerically solve the time evolution equation. Then we use the APT in two ways. First, we take the massless limit $M \rightarrow 0$ of the “massive” case of Eq. (24). Second, we redo the APT working directly with $M = 0$.

B. Adiabatic perturbation theory in the $M \rightarrow 0$ limit

The APT result for case No. 2 with a finite mass is $P_f \approx 4e^{-2\Im \beta_1} \sin^2 \left( \frac{\Re \beta_1 - \Re \beta_4}{2} \right)$ with $\Re \beta_1 - \Re \beta_4 = \varphi_{\text{dyn}} + \Delta \varphi$, $\Delta \varphi = -2 \arctan(c_F \sqrt{\Delta_0 / M})$ and $\Im \beta_1 = \Im \alpha_1 = -\pi / (2 \Delta_0)$. We also noted that in the LZ basis, when $M \rightarrow 0$ the $\alpha_0$ pole does not contribute to $A_+$ either because of the vanishing $M^3$ preexponential factor in the residue; see the paragraph before Eq. (22). Therefore, we can still use the finite $M$ form of $P_f$ and take $M \rightarrow 0$ there, obtaining $\Delta \varphi = -\pi$.

![FIG. 7. Final transition probability $P_f$ as a function of the time interval $2t_0 = 2\sqrt{\Delta_0}$ between the two Dirac cones for the case of No. 2 with $M = 0$. The open circles are the full numerical solution. The solid curve corresponds to Stückelberg theory without the geometric phase $P_f = 4P_{ZJ}(1 - P_{ZJ}) \sin^2(\varphi_S + \varphi_{\text{dyn}}/2)$. The parameters are $c_F = 0.1$ with the gap at the avoided crossings given by $2c_F t_0$. There is a clear $\pi$ shift.](042119-10)

C. Adiabatic perturbation theory directly with $M = 0$

Here it is easier to work in the graphene basis (because in the LZ basis, the path on the Bloch sphere passes the poles),

$$H_g(t) = (t^2 - \Delta_0)\sigma_x + c_F t \sigma_y,$$

and we use the south-pole gauge eigenstates. Following the same technique of complex integration (see Appendix C), we obtain for the final amplitude as given by the sum of the residues (see Appendix E)

$$A_+(\pm \infty) = -2\pi i \left( \frac{1}{6} e^{i\alpha_1} + \frac{1}{6} e^{-i\alpha_1} \right) = -\frac{\pi}{3} e^{-i\alpha_0} 2\cos(\Re \alpha_1),$$

and therefore giving the transition probability

$$P_f = |A_+(\pm \infty)|^2 = 4e^{-2\Im \alpha_1} \cos^2(\Re \alpha_1) \sin^2 \left( \frac{\Re \alpha_1 - \Re \alpha_4 + \pi}{2} \right),$$

in agreement with the previous methods showing the presence of the extra $\pi$ shift.

In summary, we have shown that there can be a geometric phase also in the massless case (i.e., when the trajectory on the Bloch sphere is restricted to a great circle). We have found that this phase $\varphi_S$ is either 0 (case No. 1; see [37]) or $\pi$ (case No. 2).

VIII. GEOMETRIC PHASE AS A SOLID ANGLE

To complete our understanding of the phase shift $\varphi_S$, let us focus on the geometrical meaning of the expression

$$\Gamma = \int_C dt \langle \psi(t) | i \partial_t | \psi(t) \rangle + \arg[\langle \psi(t_i) | \psi(t_f) \rangle].$$

It is an open-path geometric phase because the initial and final states are not necessarily proportional. Samuel and Bhandari [31] supplemented the open-path line integral of the Berry connection [first term of Eq. (31)] with a geodesic closure (second term) making the sum of the two gauge invariant. The open-path geometric phase was measured, for example, in neutron interferometry [54]. On the Bloch sphere, the quantity $\Gamma$ is equal to half the solid angle (or area) subtended by the path $C$ closed by the shortest geodesic connecting $|\psi(t_i)\rangle$ and $|\psi(t_f)\rangle$ [32]. This is known as the geodesic rule (see a simple proof in Appendix F). With this picture, we understand why the projection closure term becomes ill defined when the initial and final states sit at antipodal positions (when they are orthogonal); there is no unique geodesic line connecting the two points.
In the St"uckelberg interferometer the geometric phase shift is given by \( \varphi_g = \Gamma_- - \Gamma_+ \). Focusing on the lower band geometric phase \( \Gamma_- \), typical trajectories on the Bloch sphere—according to the Hamiltonian curve (17) in the graphene basis with a finite mass \( M \)—are shown in Fig. 8. The shortest geodesic path is indicated as the dotted line, which is the full solid angle, rather than half the solid angle due to two equal contributions from both the upper and the lower bands (a model with particle-hole symmetry). With this interpretation, we can understand the massless limit \( M \to 0 \) quite naturally as the limiting area spanning a quarter of the Bloch sphere \( |\psi_g| = 2 \arctan(e_F \sqrt{\Delta_\sigma}/M) \to \pi \). In Fig. 8, we show the evolution of the enclosed area as the mass parameter decreases.

![Figure 8](https://example.com/figure8.png)

**FIG. 8.** (Color online) Trajectories (solid line) of the Hamiltonian (17) as the dimensionless mass parameter \( M/(e_F \sqrt{\Delta_\sigma}) \) decreases from 0.2 in (a) to 0 in (d). The dotted line is the shortest geodesic line connecting positions of the initial and the final points of the Hamiltonian curve. We see that the area of the enclosed region evolves smoothly to the value \( \pi \) for \( M = 0 \).

IX. PHASE SHIFT FOR THE EIGHT DOUBLE CONE INTERFOMETERS

In this paper, we have mainly considered the special case of two cones with same mass, opposite chirality, traversed by a diagonal trajectory (case No. 2). The case of a parallel trajectory (No. 1) was studied in [37]. We do not elaborate here on the other cases which can be studied by similar techniques. Table IV presents our results for the phase shift \( \Delta \varphi \) computed using the \( N \)-matrix approach for LZ crossings with complex gaps. These results can be summarized as follows.

Let \( D \) be the closest “distance” to the Dirac points (i.e., at the tunneling events when \( t \approx \pm t_0 \), \( D \equiv |Y_{\chi,\mu}(t_0)| \)) and \( M \) be the absolute value of the mass at the Dirac points \( M \equiv |M_{\chi,\mu}(t)| = |Z_{\mu}(t)| \). In all cases, we assumed that the tunneling events occur at \( t_0 \approx \pm \sqrt{2m\Delta_s}/F_x \), corresponding to \( X_{\chi,\mu}(t_0) = 0 \).

It is possible to write a single formula for the eight cases. It is

\[
\Delta \varphi = -2\mu \arctan \left( \frac{D + \chi \mu \tau}{M} \right)^\mu, \tag{32}
\]

where \( \chi = \pm 1 \) is the product of the chirality of the two cones, \( \mu = \pm 1 \) is the product of the mass sign of the two cones, and \( \tau = +1 \) for parallel and \( -1 \) for diagonal trajectory. From the above formula, it is obvious that two different cases with the same \( \mu \) and the same \( \chi \tau \) have the same geometric phase shift. Actually, there are only four essentially different cases. In all cases \( X(t) \) has the structure \( \sim t^2 - \text{const.} \approx t^2 - 1, Y(t) \) either changes sign (\( \chi \tau = + \)) or does not (\( \chi \tau = - \)) between the two crossings, and similarly for \( Z \), which either changes

**TABLE IV.** The phase shift \( \Delta \varphi \) for the eight different time-dependent Hamiltonians \( H_{\chi,\mu}(t) = X_{\chi,\mu}(t) \sigma_x + Y_{\chi,\mu}(t) \sigma_y + Z_{\mu}(t) \sigma_z \), with \( (\chi,\mu,\tau) = (\pm, \pm, \pm) \), where \( \tau = +1 \) for a parallel trajectory \( \tilde{\sigma}(t) = (F_x, t, p_y) \) or \( \tau = -1 \) for a diagonal trajectory \( \tilde{\sigma}(t) = (F_x, t, F_t) \). Here we reintroduced \( F_x \) and \( m \) and do not take units such that \( F_x = \hbar = 2m = 1 \). We also give the closest “distance” to the Dirac points \( D \equiv |Y_{\chi,\mu}(t_0)| \), where \( t_0 \approx \sqrt{2m\Delta_s}/F_x \) and the absolute value of the mass at the Dirac points \( M \equiv |Z_{\mu}(t_0)| \): This allows one to easily check the formula \( \Delta \varphi = -2\mu \arctan \left( \frac{D + \chi \mu \tau}{M} \right) \).

| No. | \( (\chi,\mu,\tau) \) | \( X_{\chi,\mu}(t) \) | \( Y_{\chi,\mu}(t) \) | \( Z_{\mu}(t) \) | \( \Delta \varphi \) | \( D \) | \( M \) | Remarks |
|-----|------------------|------------------|------------------|------------------|------------------|------------------|------------------|------------------|
| 1   | (-, +, +)        | \( \frac{F_x^2}{2m} - \Delta_s \) | \( c_y p_y \) | \( M \) | 0 | \( c_y p_y \) | \( M \) | Studied in [37] |
| 2   | (-, -, -)        | \( \frac{F_x^2}{2m} - \Delta_s \) | \( c_y F_y t \) | \( M \) | \( -2\arctan \left( \frac{\sqrt{2m\Delta_s} F_y}{F_x} \right) \) | \( c_y F_y \sqrt{2m\Delta_s} \) | \( M \) | Mostly studied here |
| 3   | (-, -, -)        | \( \frac{F_x^2}{2m} - \Delta_s \) | \( c_y p_y \) | \( c_y F_y t \) | \( 2\arctan \left( \frac{\sqrt{2m\Delta_s} c_y}{F_x} \right) \) | \( c_y \sqrt{2m\Delta_s} \) | \( c_y \sqrt{2m\Delta_s} \) | |
| 4   | (-, -, -)        | \( \frac{F_x^2}{2m} - \Delta_s \) | \( c_y F_y t \) | \( \pi \) | \( c_y F_y \sqrt{2m\Delta_s} \) | \( c_y \sqrt{2m\Delta_s} \) | \( c_y \sqrt{2m\Delta_s} \) | |
| 5   | (+, +, +)        | \( \frac{F_x^2}{2m} - \frac{F_y^2}{2m} - \Delta_s \) | \( \frac{p_y p_y}{m} - \frac{F_x^2}{m} \) | \( M \) | \( -2\arctan \left( \frac{\sqrt{2m\Delta_s} F_y}{F_x} \right) \) | \( F_x F_y \sqrt{2m\Delta_s} \) | \( M \) | Similar to No. 2 |
| 6   | (+, +, -)        | \( \frac{F_x^2}{2m} - \frac{F_y^2}{2m} - \Delta_s \) | \( \frac{p_y p_y}{m} - \frac{F_x^2}{m} \) | \( M \) | 0 | \( F_x F_y \sqrt{2m\Delta_s} \) | \( M \) | Similar to No. 1 |
| 7   | (+, -, +)        | \( \frac{F_x^2}{2m} - \frac{F_y^2}{2m} - \Delta_s \) | \( \frac{p_y p_y}{m} - \frac{F_x^2}{m} \) | \( F_y F_x \sqrt{2m\Delta_s} \) | \( \pi \) | \( c_y \sqrt{2m\Delta_s} \) | \( c_y \sqrt{2m\Delta_s} \) | Similar to No. 4 |
| 8   | (+, -, -)        | \( \frac{F_x^2}{2m} - \frac{F_y^2}{2m} - \Delta_s \) | \( \frac{p_y p_y}{m} - \frac{F_x^2}{m} \) | \( c_y F_y t \) | \( 2\arctan \left( \frac{m c_y p_y}{F_x^2} \right) \) | \( F_y F_x \sqrt{2m\Delta_s} \) | \( c_y \sqrt{2m\Delta_s} \) | Similar to No. 3 |
from older work of Pancharatnam in optical interferometry, where he first realized the role of the polarization degree of freedom [30], and other works on open-path geometric phases [31,32]. The geometrical area picture clarifies the role of the mass term in the Hamiltonian curve, and the observability of the open-path geometric phase.

ACKNOWLEDGMENTS

We thank Immanuel Bloch, Manuel Endres, Monika Schleier-Smith, and Ulrich Schneider for useful discussions about their current experiment on St"uckelberg interferometry in a honeycomb optical lattice.

APPENDIX A: BLOCH OSCILLATIONS FOR COUPLED BANDS WITH A SCALAR GAUGE POTENTIAL

We give an alternative derivation of Eqs. (15). Instead of using a time-dependent vectorial gauge to include the effect of the external force (minimal coupling is $\hat{p}_x \rightarrow \hat{p}_x + F_t$), we now use a scalar and time-independent gauge (minimal coupling leads to $\hat{H}_t = \hat{H} - F \tilde{x}$) and employ a well-known wave-function ansatz due to Houston [55] in the time-dependent Schrödinger equation.

For simplicity of notation, we consider a 1D crystal of lattice spacing $a$ characterized by a Hamiltonian $\hat{H}$ describing the motion of electrons in the absence of an external force. This Hamiltonian is diagonalized by Bloch eigenstates $|\psi_{n,k}\rangle$ such that $\hat{H}|\psi_{n,k}\rangle = E_n(k)|\psi_{n,k}\rangle$, where $n$ is a band index and $k \in [-\pi/a, \pi/a]$ is a Bloch wave vector in the first Brillouin zone (BZ). One has $|\psi_{n,k}\rangle = e^{ikx}|\psi_{n,k}\rangle$, where $\tilde{x}$ is the position operator (i.e., the complete position operator, not just the position of the unit cell) and $|\psi_{n,k}\rangle$ is the cell-periodic part of the Bloch state such that $\psi_{n,k}(x + R) = \psi_{n,k}(x)$ for any Bravais lattice vector $R = a \times \text{integer}$. In the presence of a constant force $F$ the Hamiltonian becomes $\hat{H} - F \tilde{x}$ (this is a time-independent scalar gauge choice). We now assume that the electron is initially in a Bloch state $|\psi(t = 0)\rangle \equiv |\psi_{0,k}\rangle$ and want to solve its dynamics in the Bloch-state basis $|\psi_{n,k}\rangle$. Expanding the state of the electron at time $t$ on this basis, we get $|\psi(t)\rangle = \sum_n \int \mathcal{D}k \psi_{n,k}(t)|\psi_{n,k}\rangle$. We make an ansatz for $|\psi(t)\rangle$ following Houston [55],

$$|\psi(t)\rangle = \sum_n C_n(k(t))|\psi_{n,k(t)}\rangle \quad \text{with} \quad k(t) = k_0 + F t,$$

where $C_n(k(t))$ are unknown expansion coefficients. This ansatz is inspired from our knowledge of Bloch oscillations and the equation describing the dynamics of electrons in crystals, $\frac{d}{dt} = F$, which gives $k(t) = k_0 + F t$. This ansatz is injected in the Schrödinger equation $i \frac{d}{dt} |\psi(t)\rangle = (\hat{H} - F \tilde{x}) |\psi(t)\rangle$. Next, we project on the Bloch state $|\psi_{n',k'(t)}\rangle$ to obtain

$$\delta(k' - k) \frac{d}{dt} C_n(k') = \delta(k' - k)E_n(k')C_n(k')$$

$$- F \sum_n C_n(k)|\psi_{n,k}(\tilde{x} + i \partial \tilde{x})|\psi_{n,k}\rangle,$$

(A2)

| TABLE V. Summary of phase shift in four essential cases. |

| No. | $\chi$ | $\mu$ | $X(t)$ | $Y(\mp t_0)$ | $Z(\mp t_0)$ | $\Delta \varphi$ |
|-----|-------|-------|--------|--------------|--------------|----------------|
| 1 and 6 | $+$ | $+$ | $t^2 - 1$ | $D$ | $\mathcal{M}$ | 0 |
| 2 and 8 | $-$ | $-$ | $t^2 - 1$ | $D$ | $\mp \mathcal{M}$ | $2 \arctan \frac{\mathcal{M}}{D}$ |
| 3 and 7 | $-$ | $-$ | $t^2 - 1$ | $D$ | $\mp \mathcal{M}$ | $\pi$ |

$\delta$ (sign ($\mu = -$) or does not ($\mu = +$)). This is summarized in Table V and represented in Fig. 9.

In all cases, the validity of the St"uckelberg regime is $\Delta \varphi \gg \sqrt{D^2 + \mathcal{M}^2} \gg D, \mathcal{M}$. 

X. CONCLUSIONS

The present paper extends our previous letter [34]. It presents a careful derivation of the transition probability in a double cone St"uckelberg interferometer. The Dirac cones are gapped and constitute avoided linear band crossings. We actually considered eight different cases, having almost the same adiabatic energy spectrum but different adiabatic eigenstates. The differences come from the relative chirality (winding number) of the two Dirac cones, from their relative mass sign and from the reciprocal space trajectory crossing (winding number) of the two Dirac cones, from their relative eigenstates. The differences come from the relative chirality (winding number) of the two Dirac cones, from their relative mass sign and from the reciprocal space trajectory crossing (winding number) of the two Dirac cones, from their relative eigenstates.
where we used that $\partial_t = F \partial_\delta$ (in the above equation we wrote $k$ for $k(t) = k_0 + Ft$ to simplify the notations) and moved the term $i\partial_t \phi$ from the left to the right-hand side. The matrix elements of the position operator in the Bloch-state basis are [56]

$$\langle \psi_{n',k} | \hat{\phi} | \psi_{n,k} \rangle = \delta_{n',n} \delta(k' - k) + A_{n',n}(k') \delta(k' - k), \quad (A3)$$

where $A_{n,n}(k) \equiv \langle \psi_{n,k} | i \partial_t | \psi_{n,k} \rangle$ is the Berry connection and $\delta(x)$ is the derivative of the Dirac $\delta$ function [with $\delta(-x) = -\delta(x)$]. Using the fact that $\langle \psi_{n',k} | i \partial_t | \psi_{n,k} \rangle = i \delta_{n',n} \delta(k - k') = \delta_{n,n'} i \delta(k' - k)$, we find that $\langle \psi_{n',k} | (\hat{\phi} + i \partial_t) | \psi_{n,k} \rangle = A_{n',n}(k') \delta(k' - k)$. Eventually, the projected Schrödinger equation becomes

$$i \frac{d}{dt} C_n(k') = E_n(k') C_n(k') - F \sum_n A_{n,n}(k') C_n(k'), \quad (A4)$$

which we rewrite

$$i \frac{d}{dk} C_n(k) = \left[ \frac{E_n(k)}{F} - A_n(k) \right] C_n(k) - \sum_{n \neq n'} A_{n,n'}(k) C_{n'}(k), \quad (A5)$$

with initial condition $C_n(k_0) = \delta_{n,n_0}$. The first term in the right-hand side gives the dynamical phase, the second the line integral of the diagonal Berry connection $A_n(k) = A_{n,n}(k)$ (these two terms together contribute to the adiabatically accumulated phase in the $n^\text{th}$ band), and the third term represents the coupling to other bands ($n' \neq n$) and depends on the off-diagonal Berry connection $A_{n',n}(k)$.

In the particular case of only two bands $n = \pm$, if we define $A_+(k) \equiv C_+(k(t)) e^{-i \int_0^t d\tau E_+(\delta(t'))} e^{i \int_0^t d\tau A_+(\delta(t))}$, we obtain

$$\frac{d}{dt} A_+ = i A_+ e^{i \int_0^t d\tau [E_+ - E_-]} e^{i \int_0^t d\tau [A_+ - A_-]}$$

$$\frac{d}{dt} A_- = i A_- e^{i \int_0^t d\tau [E_+ - E_-]} e^{-i \int_0^t d\tau [A_+ - A_-]}$$

where $A_{n,n}(k) \equiv \langle \psi_{n,k} | i \partial_t | \psi_{n,k} \rangle = F \langle \psi_{n,k} | i \partial_t | \psi_{n,k} \rangle = F A_{n,n}(k(t))$. These are exactly the equations (15) obtained in the time-dependent vectorial gauge upon using $E_+ = -E_-$ and $A_{n,n}(t) = (\psi_{n,k}(t) i \partial_t \psi_{n,k}(t))$ with $\langle \psi_{n,k}(t) \rangle = e^{i k_0 t} | u_{n,k(t)} \rangle$. When comparing the derivation of these equations in the two different gauges, one should not forget about the gauge transformation $e^{ik_0 t} \hat{F}_k$ that turns $e^{ik_0 t} | u_{n,k(t)} \rangle$ (in the vectorial gauge) into $e^{ik_0 t} \hat{F}_0 | u_{n,k(t)} \rangle$ (in the scalar gauge) [47].

The understanding gained from this alternative derivation of the main equations is threefold. (i) These equations are exact and do not rely on a classical treatment of the orbital motion and a quantum treatment of the internal state (band indices) dynamics. Indeed, $\partial_t F$ is actually exact (see, for example, p. 1971 of Ref. [25]). These equations are not restricted to a semiclassical regime and can be used whatever the magnitude of the force (from the adiabatic to the sudden regime). (ii) The matrix elements of the position operator in the Bloch states are crucial. It is the complete position operator $\hat{\delta}$ appearing. In the case of a lattice with several sites in the unit cell (such as the dimerized chain with two sublattices A and B), this automatically selects a Bloch Hamiltonian $\hat{H}(k) = e^{-i k \hat{R}} F e^{i k \hat{R}}$ written in the so-called basis II rather than $\hat{H}(k) = e^{-i k \hat{R}} F e^{i k \hat{R}}$ written in the so-called basis I, where $\hat{R}$ is the position operator of the unit cell only and not the full position operator $\hat{\delta} = \hat{R} + \hat{\delta}$, where $\delta$ gives the relative position within the unit cell. Note that $\hat{H}(k)$ is not periodic in $k$ with the BZ periodicity [in contrast to $\hat{H}(k)$]. Basis I versus basis II issues are discussed in [44,57,58]. It is important to pay attention to that when discussing motion in reciprocal space that crosses the edge of the BZ. (iii) The force can be included in whatever gauge. We showed derivation in both the time-dependent vectorial gauge [$\hat{H}(\hat{\phi}) = \hat{H}(\hat{\phi} + F \hat{t})$] (for more details in a similar case, see [37]) and the time-independent scalar gauge [$\hat{H} = \hat{H}(\hat{\phi}) = \hat{F} = \hat{F} + \hat{\delta}$].

### APPENDIX B: STANDARD PARAMETRIZATION FOR A SPIN-$\frac{1}{2}$ ZEEMAN HAMILTONIAN

Given the $2 \times 2$ Hamiltonian

$$H(t) = \hat{B}(t) \cdot \hat{\sigma} = E_+(t) \begin{pmatrix} \cos \theta & \sin \theta e^{-i \phi} \\ \sin \theta e^{i \phi} & -\cos \theta \end{pmatrix}, \quad (B1)$$

where $\hat{B}(t) = (B_x(t), B_y(t), B_z)$ and $E_+ = |\hat{B}|$ (here and in the following, the time-dependence of the parameters are assumed), we have

$$\sin \theta = \sqrt{\frac{B_x^2 + B_y^2}{B_+^2}}, \quad \cos \theta = \frac{B_z}{B_+}, \quad (B2)$$

and

$$e^{i \phi} = \frac{B_z + i B_y}{\sqrt{B_x^2 + B_y^2}}, \quad (B3)$$

| TABLE VI. Summary of the coordinate parametrizations and their time derivatives for the Hamiltonian written in the graphene (gr) and LZ bases, respectively, with the adiabatic spectrum $E_+(t) = [(t^2 - \Delta_s)^2 + c_s^2 F_s^2 t^2 + M^2 t^2]^{1/2}$. |
|-----------------|-----------------|-----------------|
| Graphene basis  | LZ basis         |                 |
| $B_x$           | $t^2 - \Delta_s$| $c_s F_s$       |
| $B_y$           | $c_s F_s$       | $M$             |
| $B_z$           | $M$             | $t^2 - \Delta_s$|
| $\sin \theta$  | $\frac{\sqrt{t^2 - \Delta_s^2 + c_s^2 F_s^2 t^2}}{E_+}$ | $\frac{\sqrt{c_s^2 F_s^2 t^2 + M^2}}{E_+}$ |
| $\cos \theta$  | $\frac{M}{E_+} \sqrt{t^2 - \Delta_s^2 + c_s^2 F_s^2 t^2}$ | $\frac{t^2 - \Delta_s}{E_+ \sqrt{c_s^2 F_s^2 t^2 + M^2}}$ |
| $\theta$       | $\arctan \left( \frac{c_s F_s \sqrt{c_s^2 F_s^2 t^2 + M^2}}{\sqrt{t^2 - \Delta_s^2 + c_s^2 F_s^2 t^2}} \right)$ | $\frac{\pi}{2}$ |
| $\phi$         | $\pi$           | $\frac{\pi}{2}$ |
| $\phi(t_f) - \phi(t_i)$ | $- \pi$         | $- 2 \arctan \left( \frac{c_s F_s \sqrt{c_s^2 F_s^2 t^2 + M^2}}{\sqrt{t^2 - \Delta_s^2 + c_s^2 F_s^2 t^2}} \right)$ |
| $\phi(0)$      | $\pi$           | $\frac{\pi}{2}$ |
Accordingly, their time derivatives are given by
\[
\dot{\alpha} = \frac{B_1 (B_x B_y + B_z^2) - E_1^2 B_z}{E_1^2 \sqrt{B_x^2 + B_z^2}} \tag{B4}
\]
\[
\dot{\phi} = \frac{B_x B_y - B_z^2}{B_x^2 + B_z^2}. \tag{B5}
\]

For the two main Hamiltonians we study in the paper (case No. 2 written in two Hamiltonian bases), we summarize the parametrizations and their derivatives in Table VI.

**APPENDIX C: FIRST-ORDER ADIABATIC PERTURBATION THEORY—INTEGRAL IN THE COMPLEX PLANE**

1. **Analytic structure of the integral**

It is known that a direct complex time integration of
\[
A_+ (\infty) = \int_{-\infty}^{\infty} dt \frac{\dot{\alpha} + i \phi \sin \theta}{2} e^{i \phi(t)}, \tag{C1}
\]
only obtained generally in the APT [59], is inconvenient due to the presence of branch cuts; see Fig. 10(a). Following Ref. [60] we make a change of integration variable from the time variable \( t \) to the phase variable given by the dynamical phase \( \alpha(t) \equiv \int_{-\infty}^{t} dt' E_+ (t') \) so that \( \int dt = \int d\alpha(1/\alpha) \) [61]. For the case of Dirac cones with a constant mass, an opposite chirality, and a diagonal trajectory (case No. 2) in the LZ basis, we have
\[
A_+ (\infty) = \int_{-\infty}^{\infty} d\alpha f(\alpha), \text{ with}
\]
\[
f(\alpha) = -i \frac{2 c_1^2 F_1^2}{1 + c_1^2 F_1^2 + i \epsilon^2 c_1^2 F_1^2 M E_+(t)}
\times \frac{2 i \epsilon^2 c_1^2 F_1^2 + M^2 E_+(t)}{4}
× e^{i \int_{-\infty}^{t} dt' \phi(t') (1 - \cos \theta - \phi(t')) + i \phi(t)}, \tag{C2}
\]
where we use the fact that \(-\phi(t) + \int_{-\infty}^{t} dt' \dot{\phi}(t') (1 - \cos \theta) = -\int_{-\infty}^{t} dt' \dot{\phi} \cos \theta - \phi(t), \phi(t) \mid_{t=0} = \pi / 2\).

To see the merit of changing integration variable, we now analyze the structure of \( f(\alpha) \). In the original complex plane, there are only four branch points related to the function of the dynamical phase \( \exp[i \int_{-\infty}^{t} dt' E_+(t')] \) emanating from the four poles of \( f(\alpha) \) at \( \epsilon = \pm i M / \sqrt{E_+ (t)} \) (before the change of variable) when \( E_+(t) = 0 \), giving
\[
t_1 \approx \sqrt{\Delta_3} + i c_1 F_1 / 2, \quad t_2 = t_1^*,
\quad t_3 = -t_1, \quad t_4 = -t_1^*.
\tag{C3}
\]
In the \( \alpha \) plane with \( \alpha_j \equiv \alpha(t_j) \), we define the complex line element as
\[
\int_{t_j}^{t_{j+1}} dt' \epsilon (\cdots) = \int_{Re}^{Re} du (\cdots) + i \int_{0}^{Im} dv (\cdots) \mid_{v=Re+iv}, \tag{C4}
\]
where \( t_j \equiv u + iv \) and \( u, v \) being real. The location corresponding to the \( t_j \)'s are then given by \( \alpha_1 \approx 4 \Delta_2^{1/2} / 3 + i \epsilon^2 c_1^2 F_1^2 / \Delta_3 / 4, \quad \alpha_2 = \alpha_1^*, \quad \alpha_3 = -\alpha_1, \quad \alpha_4 = -\alpha_1^* \). These are computed in the St¨uckelberg limit, \( \epsilon \rightarrow 0 \), \( \text{Im} \alpha = \text{Re} \int_{0}^{Im} dt' E_+(\text{Re} t_1 + iv) \)

![Fig. 10](https://example.com/fig10.png)

**FIG. 10.** (Color online) (a) The analytic structure of the function \( f(t) e^{i \alpha(t)} \) in the complex \( t \) plane. The function has four branch points [because of \( \alpha(t) \)] in \( t_1 \) to \( t_4 \). In addition, there are five poles at \( t_1, t_2, t_3, t_4, \) and \( t_6 \). (b) In complex \( \alpha \) plane, the function \( g(\alpha) e^{i \theta} \) has five simple poles \( (\alpha_1, \alpha_2, \alpha_3, \alpha_4, \) and \( \alpha_5 ) \) indicated by crosses, three of which are in the upper complex plane \( (\alpha_1, \alpha_2, \) and \( \alpha_3 ) \). The integration contour is shown in red. The point \( \alpha_5 = -\alpha_6 \) is also indicated but is not a pole of \( g(\alpha) \).

\[
\text{Re} \int_{0}^{Im} dv \sqrt{4 \Delta_3 v^2 + c_1^2 F_1^2 (\Delta_4 + 2i \sqrt{\Delta_3} v) + M^2} \approx \int_{0}^{Im} dv \Delta_4 (c_1^2 F_1^2 - 4 v^2) = \frac{1}{2} c_1^2 F_1^2 \sqrt{\Delta_4}.
\]

The behavior of the function \( f(\alpha) \) around \( \alpha_j \) is determined as follows. First, we compute the change of \( \alpha \) around \( \alpha_1 \), in terms of the variable \( t \) around \( t_1 \), by making an expansion \( \alpha(t) = \int_{0}^{t} dt' E_+(t') \) around \( t = t_1 \). This gives \( \alpha - \alpha_1 \approx 8i / \Delta_3 c_1 F_1 (t - t_1)^{3/2} / 3 \). Next, by making an expansion of \( f(\alpha(t)) \) around \( t_1 \) and using the former relation, we get to the leading order in \( \alpha_1 \) the expression
\[
f(\alpha) \approx \left( \frac{1}{6} e^{-i \int_{-\infty}^{t} dt' \phi \cos \theta + i \phi + i \phi(t')} \right) \frac{1}{\alpha - \alpha_1}, \tag{C5}
\]
which shows that \( \alpha_1 \) is a pole in the \( \alpha \) plane (rather than a branch point as \( t_1 \)).

Second, an expansion around \( t = t_4 \) for \( \alpha(t) \) similarly yields \( \alpha - \alpha_4 \approx 8i / \Delta_3 c_1 F_1 (t - t_4)^{3/2} / 3 \). For the expansion of \( f(\alpha(t)) \) we have
\[
f(\alpha) \approx \left( \frac{1}{6} e^{-i \int_{-\infty}^{t} dt' \phi \cos \theta + i \phi(t)} \right) \frac{1}{\alpha - \alpha_4}, \tag{C6}
\]
showing that it is again a simple pole with an additional minus sign. These expressions also give the residues around \( \alpha_1, \alpha_2, \) and \( \alpha_3 \), which we use in the next section when computing the contour integral. Similar structures are obtained for \( \alpha \approx \alpha_2, \beta_3 \) as simple poles.

From the expression of Eq. (C2), there seems to be two additional branch points (in both \( t \) and \( \alpha \) planes) coming from \( \sqrt{c_1^2 F_1^2 t^2 + M^2} = 0 \) which are located at \( t_6 = i M / (c_1 F_1) \) and \( t_7 = -t_6 \). In other words, at \( \alpha_6 = 2 \int_{0}^{Im} E_+(t) \approx 2i \Delta_3 M / c_1 F_1 \) and \( \alpha_7 = -\alpha_6 \). A little thinking actually shows that these are not branch points in the complex \( \alpha \) plane but a
simple pole at $\alpha_6$ and no pole at $\alpha_5$. To see this, we let $t = iy$ on the imaginary axis with real $y$, then $\cos \theta_{LZ} \approx \frac{-y^2 + \Delta_s}{\sqrt{y^2 + \Delta_s^2}} = -1$ when $\Delta_s$ is large. The phase factor is then approximately $e^{-i \int_0^y dt \phi_{LZ} \cos \theta_{LZ}} \approx e^{i \int_0^y dt \phi_{LZ}} = -ie^{i\theta_L(t)}$. We arrive, in a rough approximation, at

$$f(\alpha) \approx \frac{\theta_{LZ} - i \phi_{LZ} \sin \theta_{LZ} e^{i\phi_{LZ} + ia}}{2\alpha} = \frac{c_1^2 F_1^2 (t^2 + \Delta_s) + 2t M^2 - ic_1 F_1 M E_+(t)}{4E_+(t)c_1 F_1 t - i M} e^{i\alpha} \quad (C7)$$

on the imaginary axis. We thus see that the apparent poles at $t_2$ and $t_3$ reduce to a single pole at $t_6$. By making an expansion around $\alpha_6$ we get

$$f(\alpha) \approx \frac{M^3 e^{i\alpha}}{2\Delta_s^2 c_1^2 F_1^2} \frac{1}{\alpha - \alpha_6}, \quad (C8)$$

which shows that it is also a simple pole in the $\alpha$ plane.

In summary, the function $f(\alpha)$ displays five simple poles located at

$$\alpha_1 \approx \frac{4}{3} \Delta_s^{3/2} + \frac{i\pi}{c_1^2 F_1^2 \sqrt{\Delta_s}}, \quad \alpha_2 = \alpha_1^*, \quad \alpha_3 = -\alpha_1, \quad \alpha_4 = -\alpha_1^*, \quad \alpha_6 \approx 2i \Delta_s M / (c_1 F_1); \quad (C9)$$

see Fig. 10. When studying the function $f(\alpha)$ in the vicinity of the imaginary axis, we use (C7); elsewhere we use the complete expression (C2).

2. Residues of $A_+(\infty)$

To evaluate the expression $A_+(\infty)$ we use the red contour shown in Fig. 10(b) and the residue theorem gives

$$A_+(\infty) + \int_{\text{UHP}} d\alpha f(\alpha) = \oint_{\text{Circ}} d\alpha f(\alpha) = 2\pi i \text{Res}(f, \alpha_1) + \text{Res}(f, \alpha_4) + \text{Res}(f, \alpha_6). \quad (C10)$$

The line integral over the upper half plane (UHP) vanishes exponentially, thanks to the factor $e^{i\alpha}$ when $\text{Im}\alpha > 0$. Therefore, $A_+(\infty) = 2\pi i \sum_{j=1,4,6} \text{Res}(f, \alpha_j)$. The residues for the first two simple poles are given as $\text{Res}(f, \alpha_j) = f(\alpha)(\alpha - \alpha_j)|_{\alpha = \alpha_j}$ for $j = 1, 4$, using Eqs. (C5) and (C6).

Next, we consider the residue at $\alpha_6$. From the fact that $\alpha_6$ is further away from the real axis than $\alpha_4$ and $\alpha_6$, we already see that its contribution to $A_+$ will be negligible. Using Eqs. (C8) and (C9), we have $\text{Res}(f, \alpha_6) \approx i M^3 e^{i\alpha} \frac{1}{2\Delta_s^2 c_1^2 F_1^2} e^{-2i\Delta_s M/c_1 F_1}$. Indeed $e^{-\text{Im}\alpha_6} \ll e^{-\text{Im}\alpha_4}$ when $\Delta_s$ is large, which is reminiscent of the Landau argument for tunneling in the adiabatic limit [59]. Furthermore, note that the residue vanishes also at $M \to 0$.

The sum of the two dominant residues becomes

$$\text{Res}(f, \alpha_1) + \text{Res}(f, \alpha_4) = \frac{i}{6} (e^{i\beta_1} - e^{i\beta_4})$$

where we define $\beta_{1,4} \equiv \beta(t_{1,4})$ and we recall that $\beta(t) = -\pi/2 - \int_0^t dt' \phi_{LZ} \cos \theta_{LZ} + \alpha(t)$.

**APPENDIX D: INTEGRAL GIVING THE GEOMETRIC PHASE IN THE GRAPHENE BASIS**

The integral $I = \int_{-\infty}^{\infty} dt \phi_{LZ} \cos \theta_{LZ}$ in the graphene basis is given by

$$I = -2c_1 F_1 M \int_0^{\infty} dt \frac{t^2 + \Delta_s}{(t^2 - \Delta_s)^2 + c_1^2 F_1^2 t^2} \times 1 \frac{1}{\sqrt{(t^2 - \Delta_s)^2 + c_1^2 F_1^2 t^2 + M^2}}. \quad (D1)$$

By perfecting the square for the variable $t$ and using that $\Delta_s \gg c_1^2 F_1^2$, we get

$$I \approx -2c_1 F_1 M \int_0^{\infty} dt \frac{t^2 + \Delta_s}{(t^2 - \Delta_s)^2 + c_1^2 F_1^2 \Delta_s} \times 1 \frac{1}{\sqrt{4 \Delta_s \epsilon^2 + c_1^2 F_1^2 \Delta_s + M^2}}. \quad (D2)$$

One notices that the main contribution of the integral comes from $t \approx \sqrt{\Delta_s}$ as $c_1^2 F_1^2 \to 0$. So we expand around the value $t = \sqrt{\Delta_s} - \epsilon$ and keeping the leading contribution of $\epsilon$:

$$I \approx -2c_1 F_1 M \int_0^{\infty} d\epsilon \frac{2 \Delta_s}{4 \Delta_s \epsilon^2 + c_1^2 F_1^2 \Delta_s} \times 1 \frac{1}{\sqrt{4 \Delta_s \epsilon^2 + c_1^2 F_1^2 \Delta_s + M^2}}. \quad (D3)$$

The integral can be evaluated using the identity

$$\int \frac{dx}{(x^2 + a)\sqrt{x^2 + b}} = \frac{1}{\sqrt{ab - a^2}} \arctan \left( \frac{x \sqrt{b - a}}{\sqrt{ax^2 + ab}} \right) \quad (D4)$$

to give

$$I \approx -2 \arctan \frac{M}{c_1 F_1 \sqrt{\Delta_s}} = 2 \arctan \frac{c_1 F_1 \sqrt{\Delta_s}}{M} - \pi. \quad (D5)$$

**APPENDIX E: ADIABATIC PERTURBATION THEORY FOR THE MASSLESS CASE**

The full expression for the amplitude for case No. 2 with $M = 0$, in the graphene basis and south-pole gauge, is given by $A_+(\infty) = \int_{-\infty}^{\infty} d\alpha g(\alpha)e^{i\alpha}$ with

$$g(\alpha) = -i \frac{c_1 F_1 (t^2 + \Delta_s)}{4E_+^3} \quad (E1)$$

and $E_+(t) = \sqrt{(t^2 - \Delta_s)^2 + c_1^2 F_1^2 t^4}$. There are only four poles in $\alpha$ (coming from $E_+ = 0$ and located at $\alpha_1 \approx 4 \Delta_s^{3/2}/3 + i\pi c_1^2 F_1^2 \sqrt{\Delta_s}$, $\alpha_2 \approx \alpha_1^*$, $\alpha_3 \approx -\alpha_1$, and $\alpha_4 \approx -\alpha_1^*$) and no branch cuts; see Fig. 11. The contour is therefore as before but there are only two residues to compute.

In both cases ($j = 1$ and 4), the relationship between the change in $\alpha$ around the pole $\alpha_j$ and $t$ around the branch point $t_j$ is obtained similarly by making an expansion around $t = t_j$ for the function $a(t) = \int_0^t dt' E_+(t')$, giving $\alpha - \alpha_j \approx$
FIG. 11. (Color online) The analytic structure of \( \Re(\alpha) \) for the massless case. The function has four simple poles \((\alpha_1, \alpha_2, \alpha_3, \alpha_4)\) indicated by crosses, two of which are in the upper complex plane \((\alpha_1, \alpha_4)\). The integration contour is shown in red.

\[
8\sqrt{\pi c_F^2 \Delta_s (t - t_f)^{3/2}} / 3. \text{ Plugging this into the leading-order expansion of } g(\alpha) \text{ around the poles and using the fact that } E_s(t \sim t_f) \sim 3 t c_F^2 \Delta_s (\alpha - \alpha_f), \text{ we find } g(\alpha \sim \alpha_1) \approx -\frac{1}{6(\alpha - \alpha_f)} \quad \text{and } g(\alpha \sim \alpha_4) \approx -\frac{1}{6(\alpha - \alpha_f)}. \text{ We thus see that both poles give the same residues, the same as for the massive case in the graphene case; see Sec. V1C.}
\]

**APPENDIX F: PROOF THAT THE OPEN-PATH GEOMETRIC PHASE EQUALS HALF OF A SOLID ANGLE**

In this Appendix, we give an elementary proof that the open-path geometric phase \( \Gamma = \int_{C} \langle \psi | i \partial_t | \psi \rangle + \arg \langle \psi_i | \psi_f \rangle = \int_{t_i}^{t_f} dt \langle \psi(t') | i \partial_t | \psi(t) \rangle + \arg \langle \psi(t_i) | \psi(t_f) \rangle \) for a spinor (spin-1/2) \( | \psi \rangle \) is given by half of the solid angle \((\alpha - \alpha_1) \) of the open trajectory closed by the shortest geodesic (which is a portion of great circle in the case of a sphere). The open path \( C \) on the Bloch sphere (see Fig. 12) is parametrized by \( t \) going from \( t_i \) to \( t_f \) so that the state \( | \psi(t) \rangle \) depends on \( t \). Because this phase is gauge independent (see Sec. V), we can choose a specific gauge to compute it. We therefore parametrize the spinor by \( | \psi \rangle = (\cos \theta/2 e^{i \phi/2} \), which is well defined except at the south pole \( (\theta = \pi) \), where it suffers a phase ambiguity. In the following, we first compute the line integral of the Berry connection and then the argument of the scalar product.

The line integral of the Berry connection is \( \int_{C} \langle \psi | i \partial_t | \psi \rangle = -\int_{C} d\phi \sin^2(\phi/2) \). This is actually equal to (minus) half of the solid angle \( \Omega_C \) of a closed path constructed from the open path \( C \) and the two meridians (called \( a \) and \( b \) in Fig. 12) relating the north pole \((\theta = 0)\) either to \((\theta_i, \phi_i)\) or \((\theta_f, \phi_f)\). Considering \( \theta \) as a function of \( \phi \), this solid angle is \( \Omega_C = \int_{C} d\phi \sin^2(\phi/2) \) as the area measure on the sphere is \( d\phi d\theta \sin \theta \). Therefore, \( \int_{C} \langle \psi | i \partial_t | \psi \rangle = -\Omega_C/2 \).

The overlap between the initial and final spinors is given by

\[
\langle \psi_i | \psi_f \rangle = \cos \theta_i/2 \cos \phi_i/2 + \sin \theta_i/2 \sin \phi_i/2 e^{i(\phi_f - \phi_i)}. \tag{F1}
\]

We call \( \Phi \equiv \arg \langle \psi_i | \psi_f \rangle \). Then

\[
\tan \Phi = \frac{\sin \theta_i/2 \sin \phi_i/2}{\cos \theta_i/2 \cos \phi_i/2 + \sin \theta_i/2 \sin \phi_i/2 \cos(\phi_f - \phi_i)}, \tag{F2}
\]

which, from elementary spherical geometry [62], we recognize as equal to \( \tan \Omega_C/2 \) where \( \Omega_C \) is the solid angle of the triangle on the sphere (also known as the spherical excess \( E \)) with corners located at the north pole \((\theta = 0)\), at the initial point \((\theta, \phi_i)\), and at the final point \((\theta, \phi_f)\). This triangle is made of three portions of great circles (among which are two meridians of length \( a = \theta_i \) and \( b = \theta_f \), their included angle being \( C = \phi_f - \phi_i \)). Therefore, \( \Phi = \arg \langle \psi_i | \psi_f \rangle = \Omega_C/2 \).

Combining this two partial results, we obtain that the open-path geometric phase \( \Gamma = (\Omega_C + \Omega_f)/2 = -\Omega_C/2 \), where \( \Omega_C = 2 \Omega_f \) is the area of the loop made of the open-path \( C \) closed by the shortest geodesic (portion of great circle) \( C_g \) going from \((\theta_f, \phi_f)\) to \((\theta_i, \phi_i)\).

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